CPGIS Educational Webinars on Spatiotemporal Study of Urban Dynamics (4)

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Journal of Computational Urban Science

"Monitoring urban land dynamics – from local to global scale"
Dr. Peng Gong, Geography and Earth Sciences，University of Hong Kong
Chair: Cuizhen Wang, University of South Carolina

Abstract

- Over the past three decades, a lot of efforts have been made to map and monitor urban land changes using remotely sensed data. Most studies concentrated on a single city or a cluster of cities. Global mapping and monitoring of cities are recent phenomena.

- Share our experience on mapping urban land from local to global scales.

- Present some possible future perspectives.

Urban land use / land cover mapping – spectral, spatial, texture, contextual methods

Performance analyses of probabilistic relaxation methods for land-cover classification ☆

Peng Gong *, Philip J. Howarth *

THE USE OF STRUCTURAL INFORMATION FOR IMPROVING LAND-COVER CLASSIFICATION ACCURACIES AT THE RURAL-URBAN FRINGE

作者: GONG, P; HOWARTH, PJ

PHOTOGRAMMETRIC ENGINEERING AND REMOTE SENSING 卷: 56 期: 1 页: 67-73 出版年: JAN 1990

FREQUENCY-BASED CONTEXTUAL CLASSIFICATION AND GRAY-LEVEL VECTOR REDUCTION FOR LAND-USE IDENTIFICATION

作者: GONG, P; HOWARTH, PJ

PHOTOGRAMMETRIC ENGINEERING AND REMOTE SENSING 卷: 58 期: 4 页: 423-437 出版年: APR 1992

LAND COVER TO LAND-USE CONVERSION - A KNOWLEDGE-BASED APPROACH

作者: GONG, P; HOWARTH, PJ

会议: 50TH ANNUAL MEETING OF THE AMERICAN CONGRESS ON SURVEYING AND MAPPING / 56TH ANNUAL MEETING OF THE AMERICAN SOC FOR PHOTOGRAMMETRY AND REMOTE SENSING 会议地点: DENVER, CO 会议日期: MAR 18-23, 1990

会议赞助商: AMER SOC PHOTOGRAMMETRY & REMOTE SENSING

TECHNICAL PAPERS : 1990 ACSM-ASPRS ANNUAL CONVENTION, VOL 4: IMAGE PROCESSING / REMOTE SENSING
 页: 447-456 出版年: 1990

A COMPARISON OF SPATIAL FEATURE-EXTRACTION ALGORITHMS FOR LAND-USE CLASSIFICATION WITH SPOT HRV DATA

作者: GONG, P; MARCEAU, DJ; HOWARTH, PJ

REMOTE SENSING OF ENVIRONMENT 卷: 40 期: 2 页: 137-151 出版年: MAY 1992

LAND-USE CLASSIFICATION OF SPOT HRV DATA USING A COVER-FREQUENCY METHOD

作者: GONG, P; HOWARTH, PJ

INTERNATIONAL JOURNAL OF REMOTE SENSING 卷: 13 期: 8 页: 1459-1471 出版年: MAY 20 1992

Spatial-temporal consistency check and probability adjustment

Improved the temporal continuity

Li et al., 2015, RSE

Hierarchical mapping of annual global land cover 2001 to present: The MODIS Collection 6 Land Cover product

Damien Sulla-Menashe[b,*], Josh M. Gray[b], S. Parker Abercrombie[c], Mark A. Friedl[a]

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ARTICLE INFO   ABSTRACT

波士顿大学地球环境系系主任

A key weakness in previous MLCT collections was the frequency of interannual variability in class labels arising from classifier uncertainty (Friedl et al., 2010), which, as we describe previously, is largely related to challenges in land cover mapping at the coarse spatial resolution of MODIS. In C6, we mitigated (but did not resolve) this issue by post-processing annual classification results using hidden Markov models (Abercrombie and Friedl, 2016). Using information from the entire time series at each pixel, the hidden Markov model helps to distinguish actual state changes (i.e., land cover change) from stochastic variability in classification results arising from uncertainty in classification predictions (Hermosilla et al., 2018). The result, as we describe in Section 3.3, is a substantial decrease in the number and frequency of spurious land cover label changes, which increases the quality of the resulting maps, especially for land cover classes that are defined as mixtures. In this context, it is important to understand that the main benefit of the HMM post-processing implemented in C6 is to reduce spurious land cover changes. It does not, unfortunately, resolve fundamental issues surrounding uncertainty in land cover mapped from coarse spatial resolution instruments such as MODIS. By definition, land cover change is a local process. Hence,

legacy of existing land cover data sets.

Gong and Howarth 1989
to Liu et al 2006
to Cai and Liu 2013

Land-use classification based on eigen-space transformation – Gray level vector reduction method

Fast and accurate

Results

Traditional method 传统方法

特征提取
光谱信息
反射率
波段

分类结果

原始数据

Raw data

数据压缩
$N_i = \lambda_i^{\,p} \sqrt{\dfrac{\widehat{N}}{\lambda_1 \lambda_2 \dots \lambda_p}}$
4.25e2
第二本征
4.25e2
第一本征

特征提取
空间信息
空间频率
特征矢量

分类结果

Data reduction   Feature extraction

Gong and Howarth, 1992, PERS

Accuracy improvement

制图精度提高

15%

IEEE JOURNAL OF SELECTED TOPICS IN APPLIED EARTH OBSERVATIONS AND REMOTE SENSING, VOL. 4, NO. 4, DECEMBER 2011   923

Toward Global Automatic Built-Up Area Recognition Using Optical VHR Imagery

Martino Pesaresi, Daniele Ehrlich, Ivano Caravaggi, Mayeul Kauffmann, and Christophe Louvrier

II. IMAGE INFORMATION EXTRACTION

The method applied here for automatic information extraction benefits from the seminal work done in the early 90's by P.Gong and others on the use of image structural information for improvement of the recognition of rural-urban fringes [13], [14].

JRC TECHNICAL REPORTS

Operating procedure
for the production of
the Global Human Settlement Layer
from Landsat data of the epochs
1975, 1990, 2000, and 2014

Martino Pesaresi, Daniele Ehrlich, Stefano Ferri, Aneta J. Florczyk, Sergio Freire, Matina Halkia, Andreea Julea, Thomas Kemper, Pierre Soille, and Vasileios Syrris

2016

JRC is still using them for global human settlement monitoring

Comparison of sample size and algorithms

Learnt through a large amount of tests： Sample size is more important than algorithm in large area mapping

Different classifiers vs sample size

Accuracy (Kappa)

Classifiers

Li et al., 2014, RS

Sample size

✳	20 samples
●	40 samples
▲	60 samples
▼	80 samples
◆	100 samples
◀	120 samples
▶	140 samples
●	160 samples
★	180 samples
⬠	200 samples
●	220 samples
■	240 samples

EDITORIAL

The development of remote sensing in the last 40 years

What Gong et al. did was to make use of the release of the Landsat archive to derive a 30 m resolution Finer Resolution Observation and Monitoring of Global Land Cover (FROM-GLC) database. This involved using 8929 TM or ETM+ scenes from 1984 to 2011 to produce a global land cover map, see Figure 23. The data behind these four products is at 30 m resolution. While differences between the products of the four classification methods used can be detected, it is worth noting that these differences are small, which is consistent with the general view of Li et al. (2014) that it does not matter very much which classification method is used so long as one has good training data.

"Seminal work"
Arthur Cracknell and co-authors

From a single city to all cities in China

Proposed an adjustable threshold method for extraction of urban boundaries of different economic levels

Landsat 影像

Images

Henderson, Yeh, Gong, 2003, IJRS

DMSP 夜间灯光

Night light

Watershed segmentation algorithm
Wang et al, IJRS, 2010

Wang et al, 2010
Chinese Science Bulletin

A 30-year (1984-2013) record of annual urban dynamics of Beijing City derived from Landsat data

作者: Li, Xuecao; Gong, Peng; Liang, Lu

REMOTE SENSING OF ENVIRONMENT 卷: 166 页: 78-90 出版年: SEP 1 2015

Mapping Urban Land Use by Using Landsat Images and Open Social Data

作者: Hu, Tengyun; Yang, Jun; Li, Xuecao; 等.

REMOTE SENSING 卷: 8 期: 2 文献号: 151 出版年: FEB 2016

40-Year (1978-2017) human settlement changes in China reflected by impervious surfaces from satellite remote sensing

作者: Gong, Peng; Li, Xuecao; Zhang, Wei

SCIENCE BULLETIN 卷: 64 期: 11 页: 756-763 出版年: JUN 15 2019

Annual maps of global artificial impervious area (GAIA) between 1985 and 2018

作者: Gong, Peng; Li, Xuecao; Wang, Jie; 等.

REMOTE SENSING OF ENVIRONMENT 卷: 236 文献号: 111510 出版年: JAN 2020

Mapping essential urban land use categories in China (EULUC-China): preliminary results for 2018

作者: Gong, Peng; Chen, Bin; Li, Xuecao; 等.

SCIENCE BULLETIN 卷: 65 期: 3 页: 182-187 出版年: FEB 15 2020

From 2D to 3D

ICESat GLAS Data for Urban Environment Monitoring

Peng Gong, Zhan Li, Huabing Huang, Guoqing Sun, *Senior Member, IEEE*, and Lei Wang

Reference Data

Fig.1 Distribution of selected reference height data in US (a) and Europe (b). Building heights for representative cities in US and Europe (c). Each snapshot in (c) is about 20km x 20 km. Reference data in US and Europe were derived from LiDAR and Stereo images, respectively.

Building height extraction from Sentinel-1 data

(a)

(b)

fold: 1 — RMSE: 0.56, MAE = 0.33, R: 0.87
fold: 2 — RMSE: 0.60, MAE = 0.34, R: 0.86
fold: 3 — RMSE: 0.57, MAE = 0.32, R: 0.86
fold: 4 — RMSE: 0.61, MAE = 0.34, R: 0.87
fold: 5 — RMSE: 0.59, MAE = 0.33, R: 0.87

fold: 6 — RMSE: 0.59, MAE = 0.34, R: 0.87
fold: 7 — RMSE: 0.60, MAE = 0.35, R: 0.86
fold: 8 — RMSE: 0.58, MAE = 0.33, R: 0.86
fold: 9 — RMSE: 0.57, MAE = 0.32, R: 0.87
fold: 10 — RMSE: 0.58, MAE = 0.33, R: 0.88

Ln (Reference) (m) vs VVH

Ln (Estimated) (m)

North America: New York, Chicago, Dallas, Toronto, Mexico City
South America: Sao Paulo, Buenos Aires, Lima, Recife, Santiago
Europe: London, Pairs, Berlin, Madrid, Rome
African: Lagos, Nairobi, Johannesburg, Kampala, Kumasi
Asia: Dubai, New Delhi, Bangkok, Shanghai, Tokyo

Future cities require more innovative, frequent and flexible mapping and monitoring

Emily Badger

https://www.stephanemalka.com/portfolio/the-green-machine-i-greening-the-desert-i-sahara-2014/

Future perspectives

- Big data makes ground truthing easier – e.g. "building Rome in a day"

- Virtual organization – from bottom up – helps global mapping efforts

- Cloud computing is the trend for large area mapping

Work presented here are joint efforts primarily with

- Xuecao Li – Professor at CAU,
- Tengyun Hu – Engineer in Beijing Planning Institute
- Bin Chen – Assistant Professor at HKU
- Hao Ni – Grad student at Tsinghua