Climate State Probabilities of Threshold Crossings with EBM - Kalman Filter

- P(threshold crossed by given year)
- a posteriori EKF state estimate $\hat{T}_n$
- 95% CI of EKF state $(2\sqrt{P_n})$
- thresholds in 0.5K increments

Temperature Forecast Probabilities of Threshold Crossings with EBM - Kalman Filter

- P(threshold crossed by given year)
- a posteriori EKF state estimate $\hat{T}_n$
- 95% CI of measurements from state $(2\sqrt{S_n})$
- thresholds in 0.5K increments