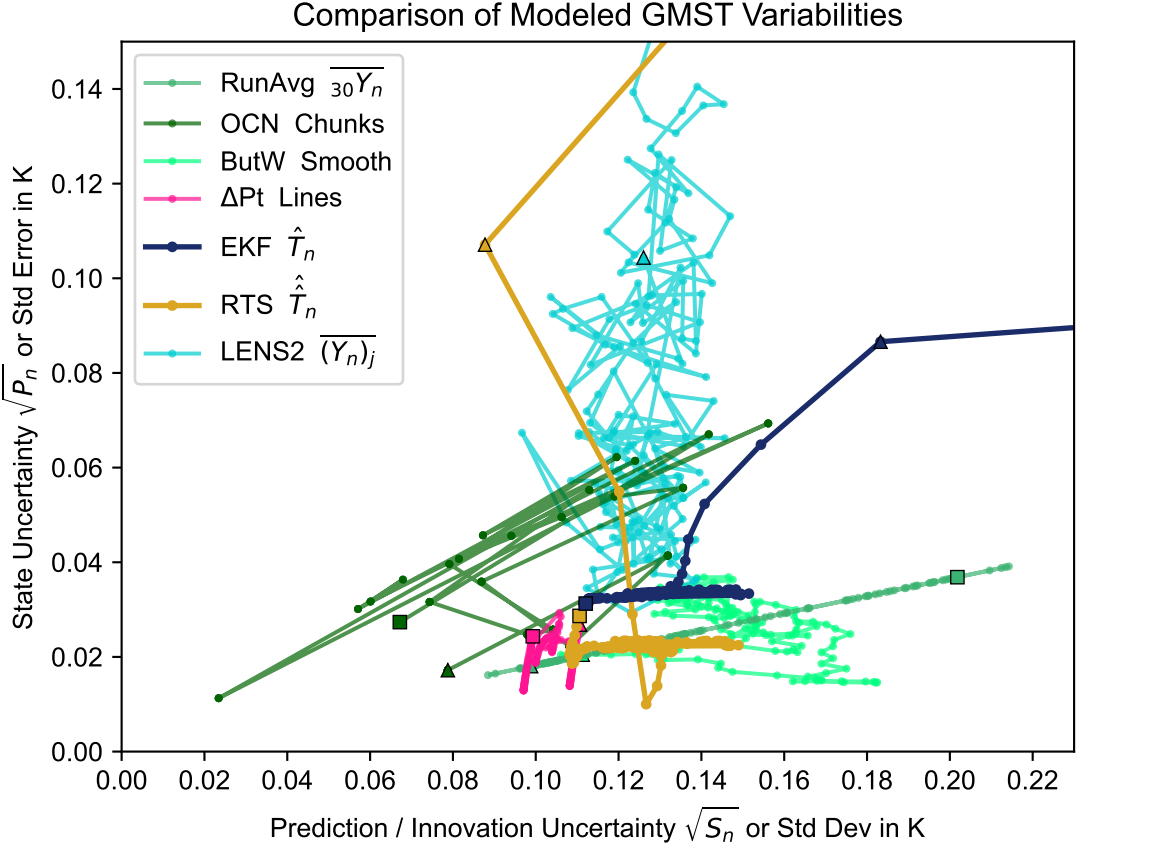
Comparison of Modeled GMST Variabilities
RunAvg $\overline{{}_{30}Y_n}$
OCN Chunks
ButW Smooth
ΔPt Lines
EKF $\hat{T}_n$
RTS $\hat{\hat{T}}_n$
LENS2 $\overline{(Y_n)_j}$
State Uncertainty $\sqrt{P_n}$ or Std Error in K
Prediction / Innovation Uncertainty $\sqrt{S_n}$ or Std Dev in K
0.00
0.02
0.04
0.06
0.08
0.10
0.12
0.14
0.16
0.18
0.20
0.22