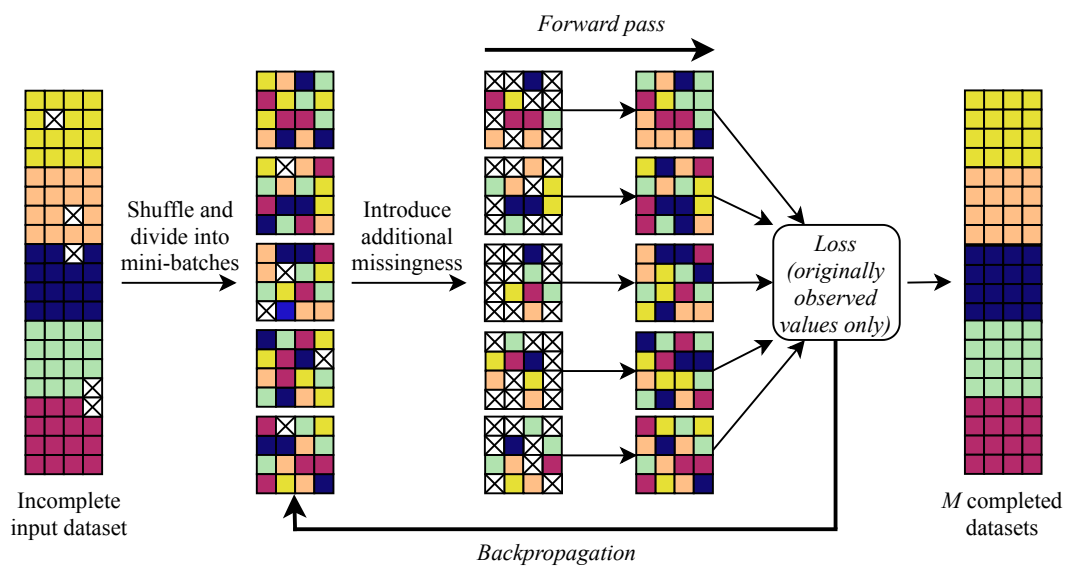
Forward pass
Shuffle and divide into mini-batches
Introduce additional missingness
Loss (originally observed values only)
Incomplete input dataset
M completed datasets
Backpropagation