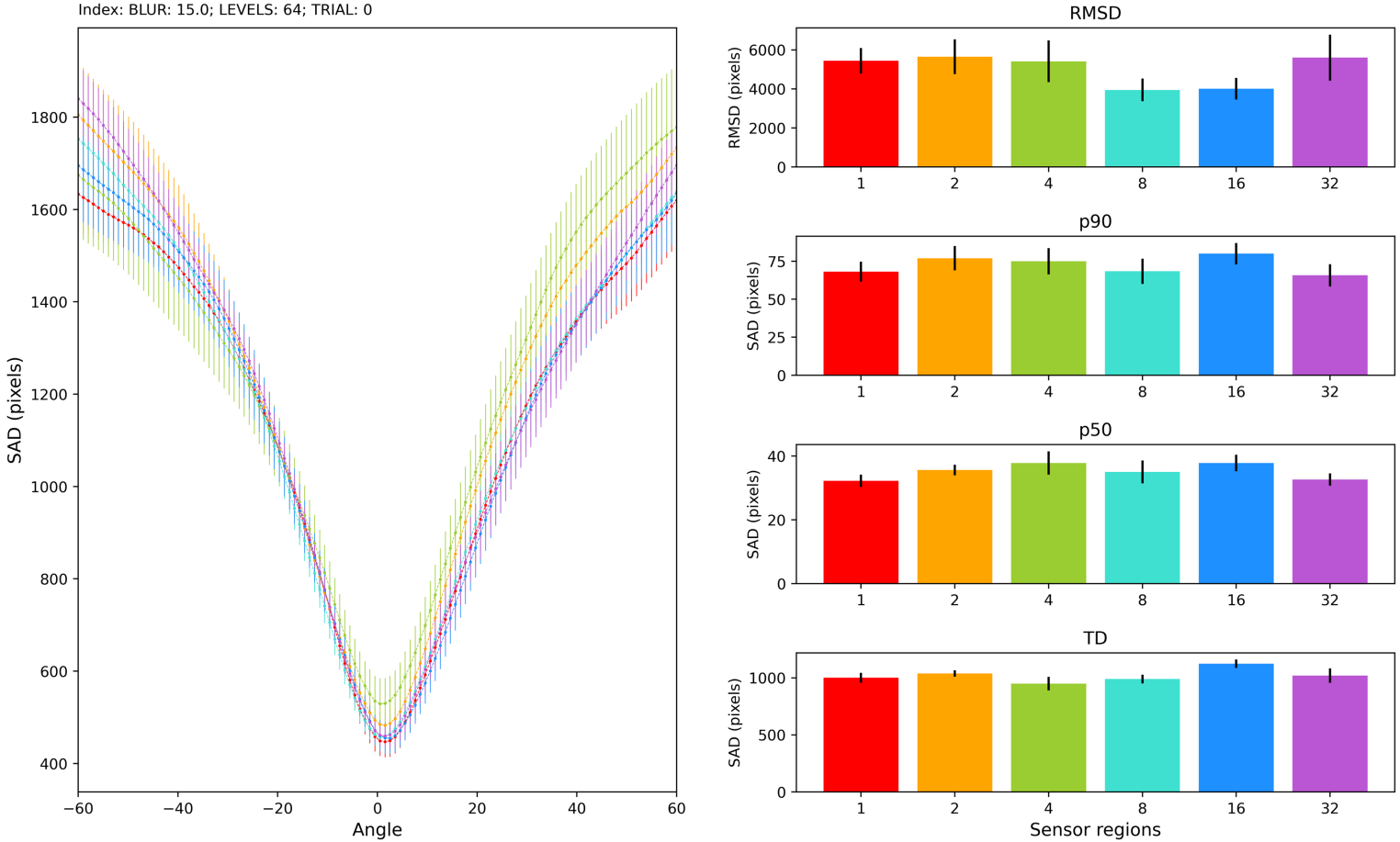
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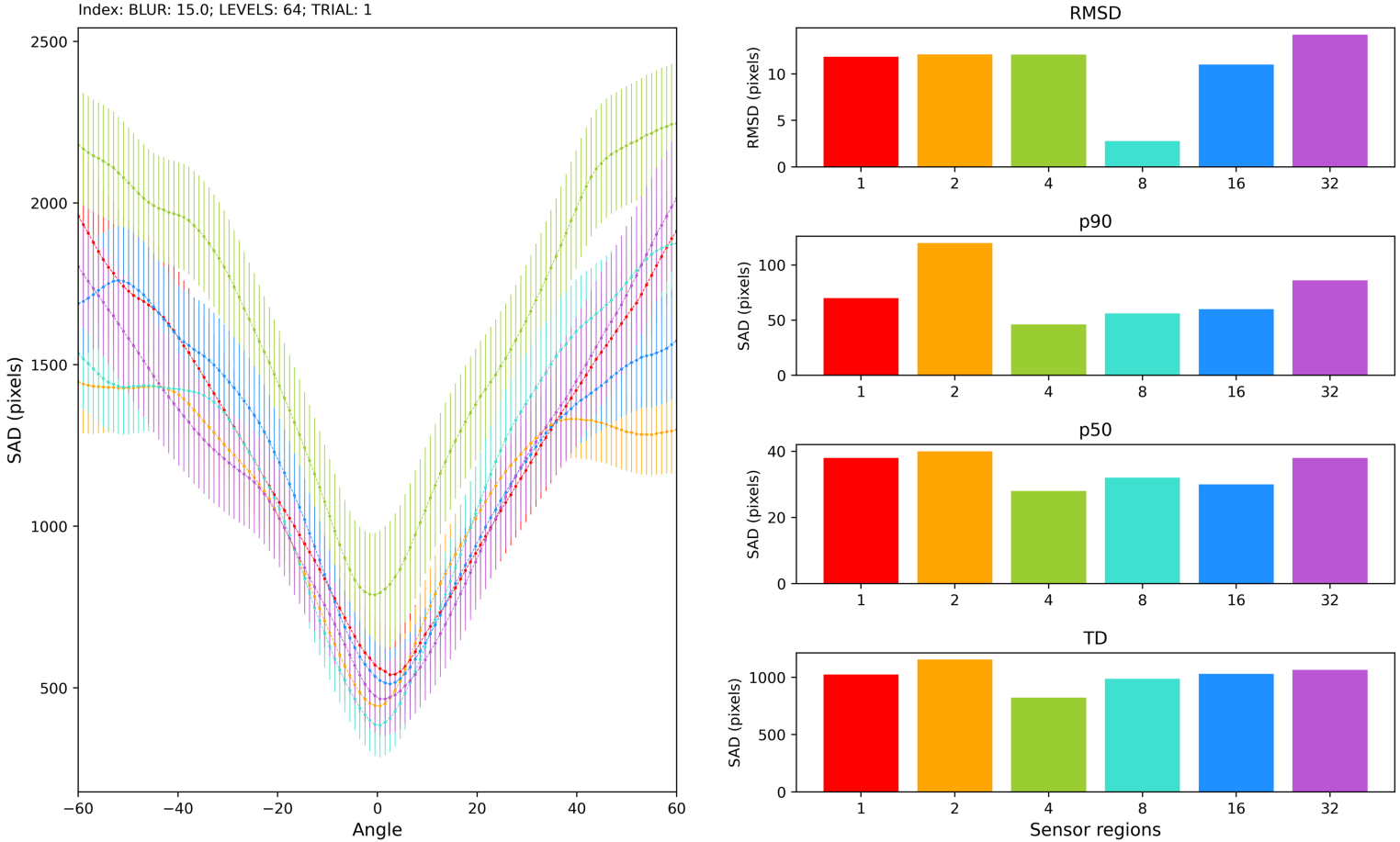
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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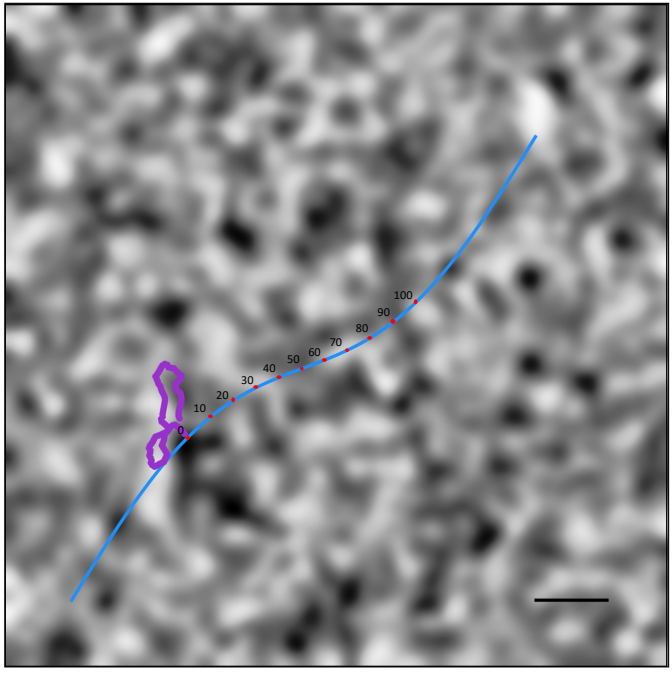
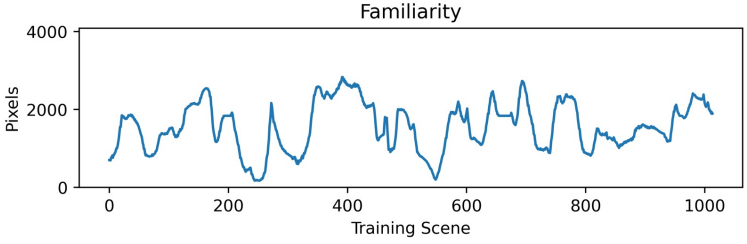
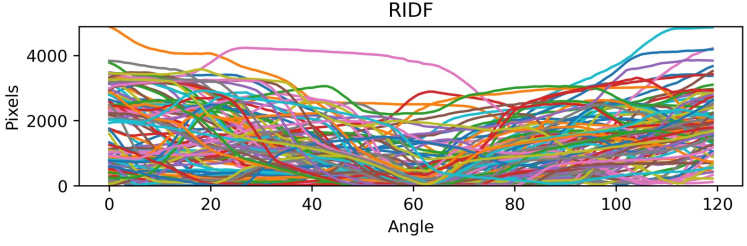
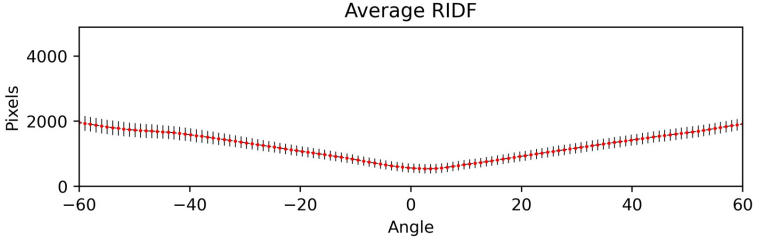
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





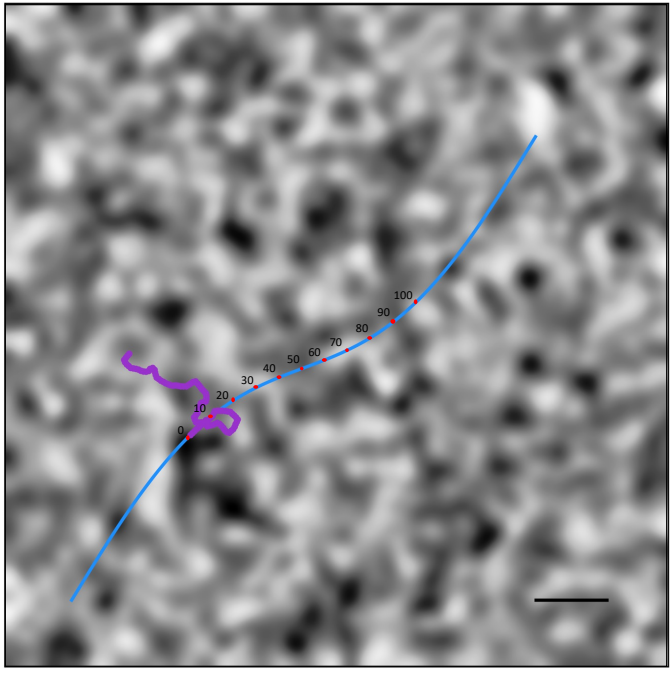


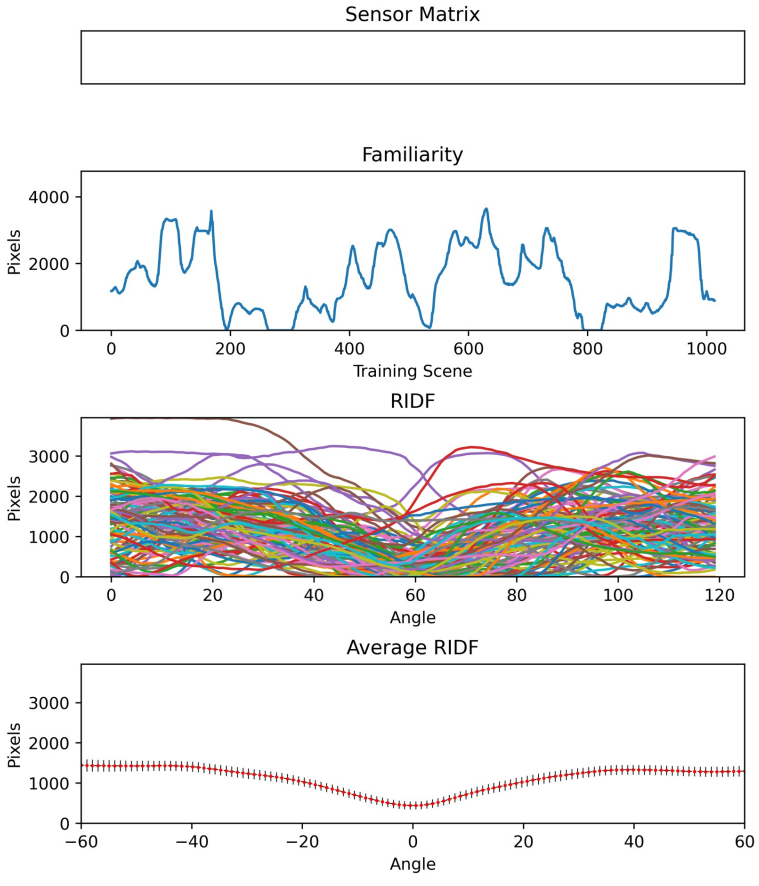


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4735.11; RMSD/dist: 11.838; TD: 1024; p90: 70; p50: 38; complete: 0

10%

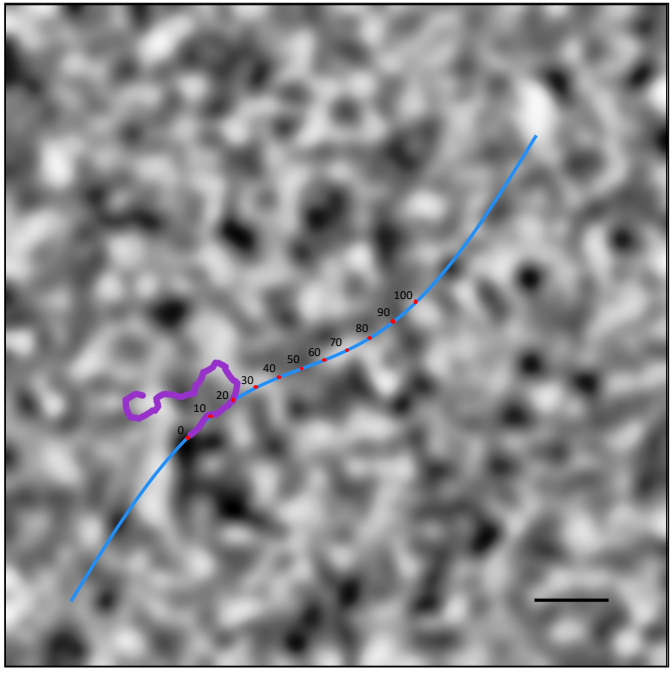


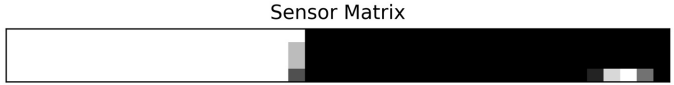


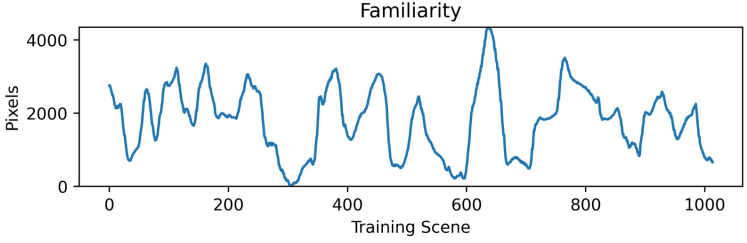
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

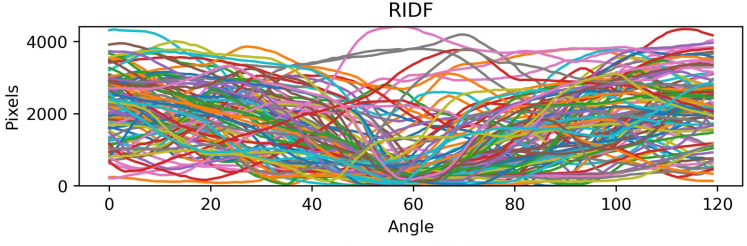
Navigation stats: RMSD error: 4839.95; RMSD/dist: 12.100; TD: 1155; p90: 120; p50: 40; complete: 0

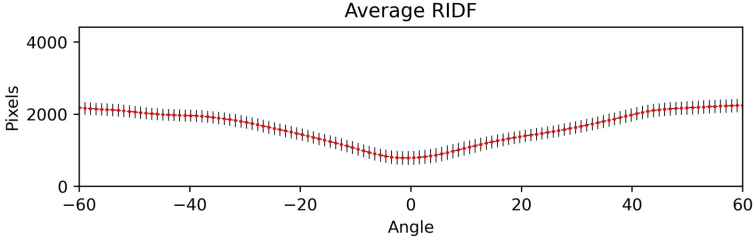
10%







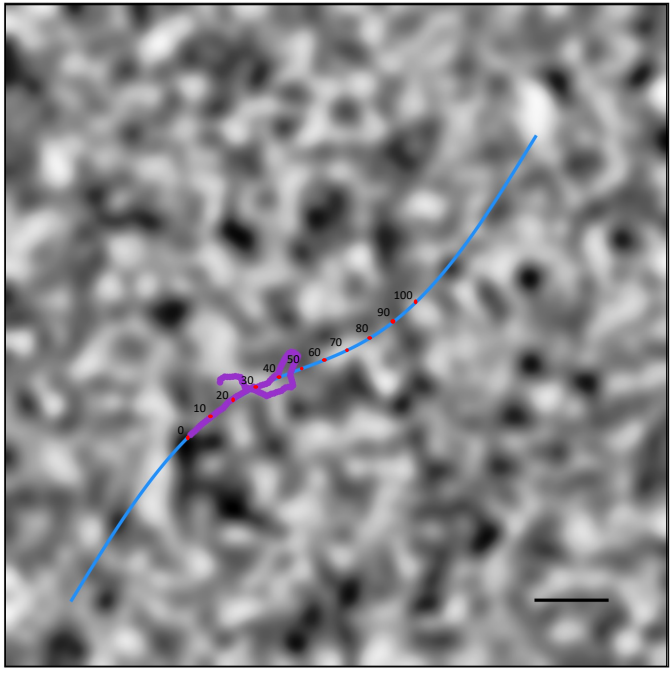


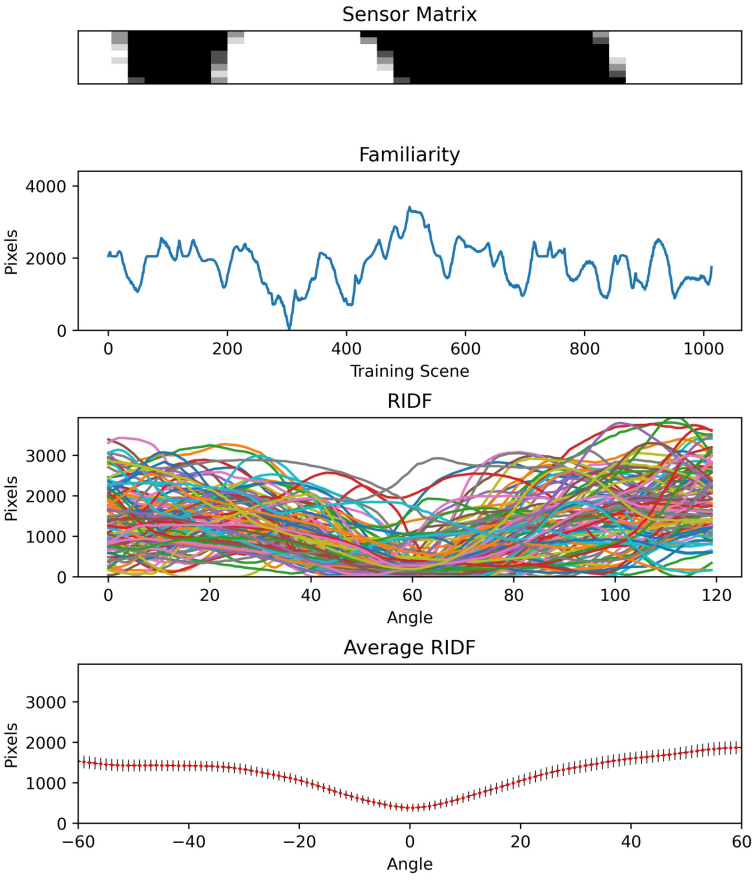


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4828.48; RMSD/dist: 12.071; TD: 823; p90: 46; p50: 28; complete: 0

30%

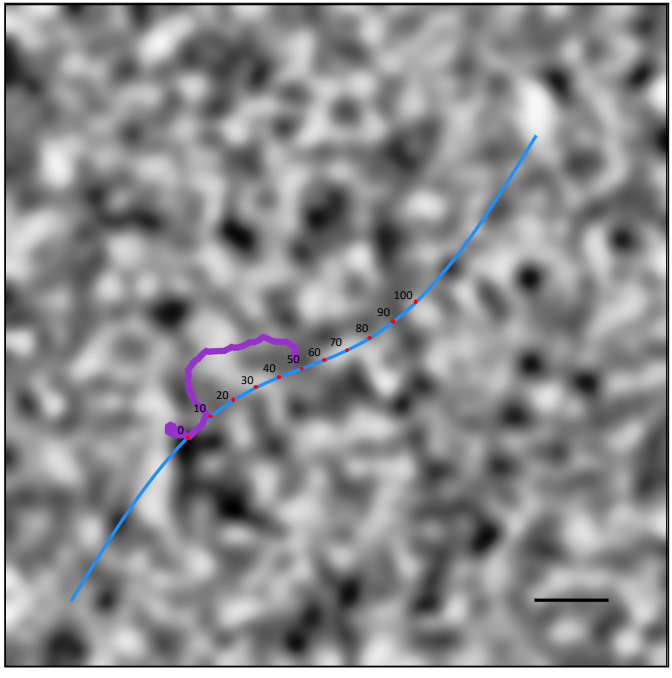


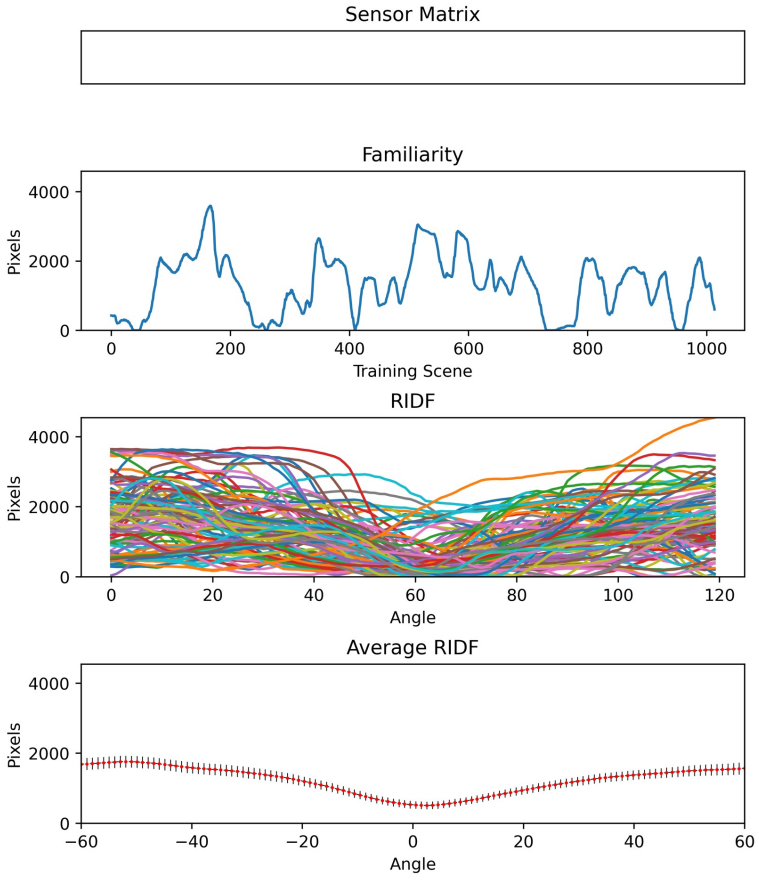


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1104.74; RMSD/dist: 2.762; TD: 988; p90: 56; p50: 32; complete: 0

0%

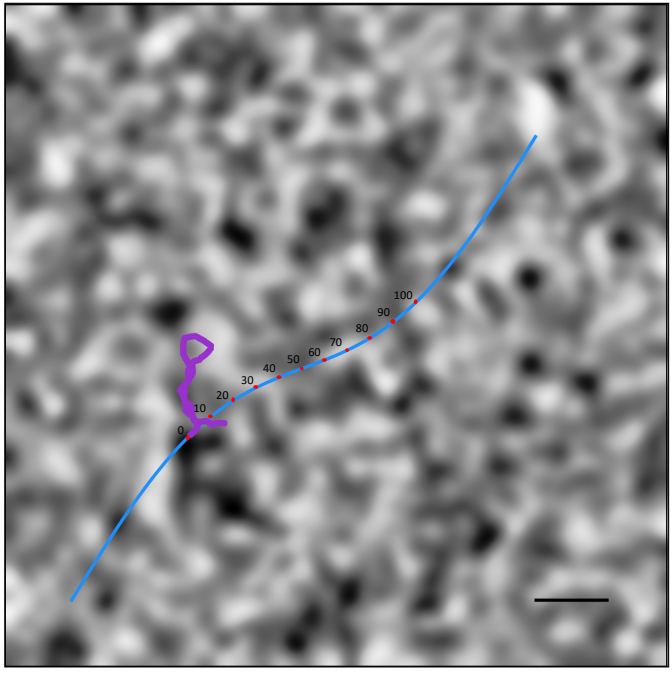


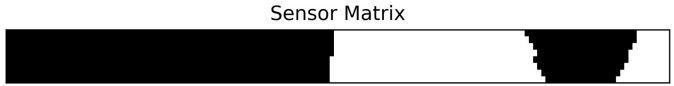


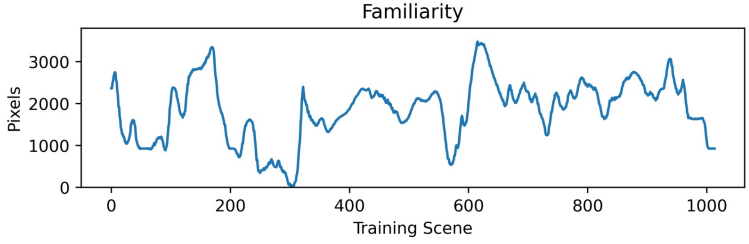
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

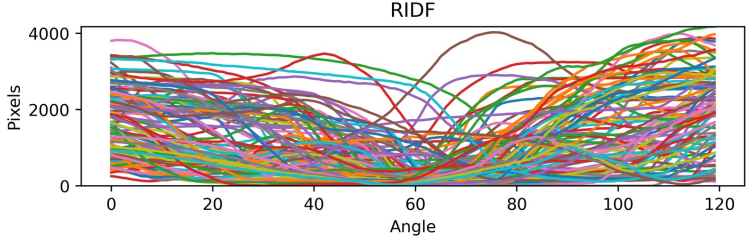
Navigation stats: RMSD error: 4400.20; RMSD/dist: 11.000; TD: 1031; p90: 60; p50: 30; complete: 0

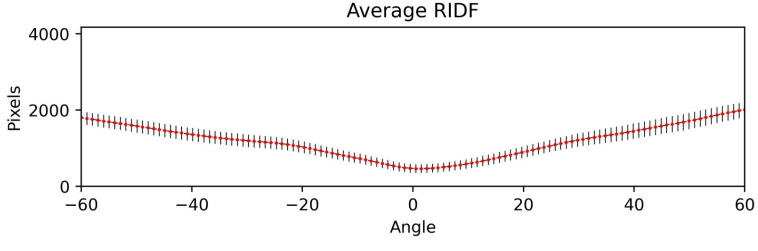
0%





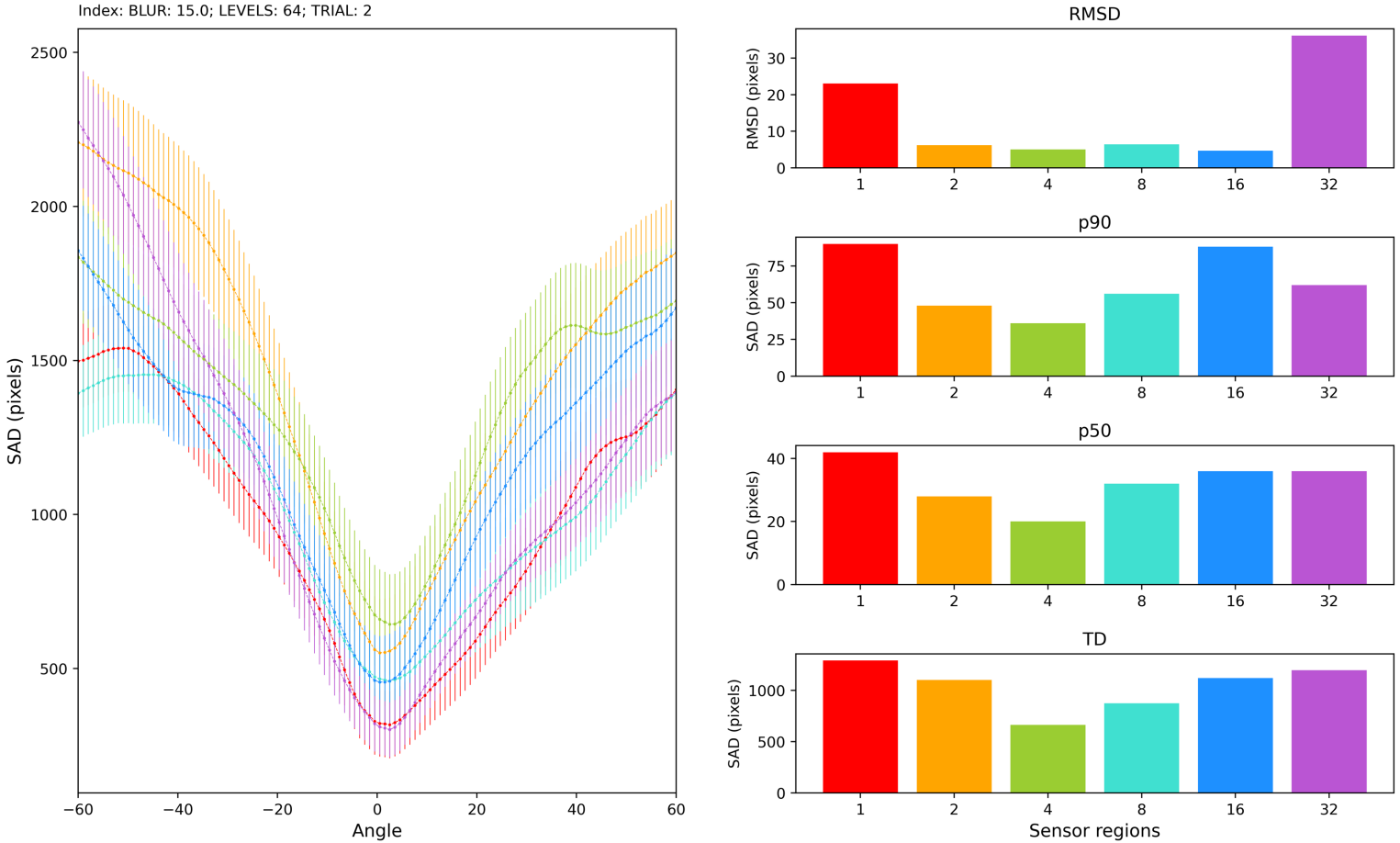




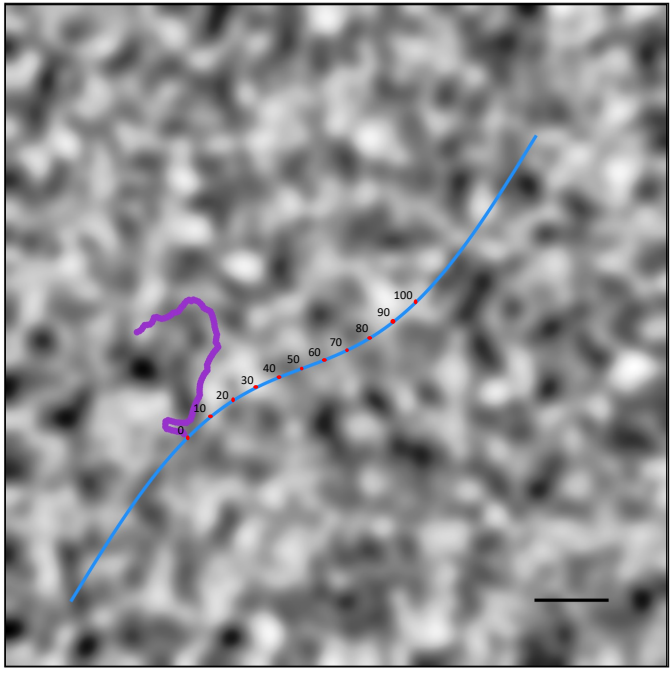


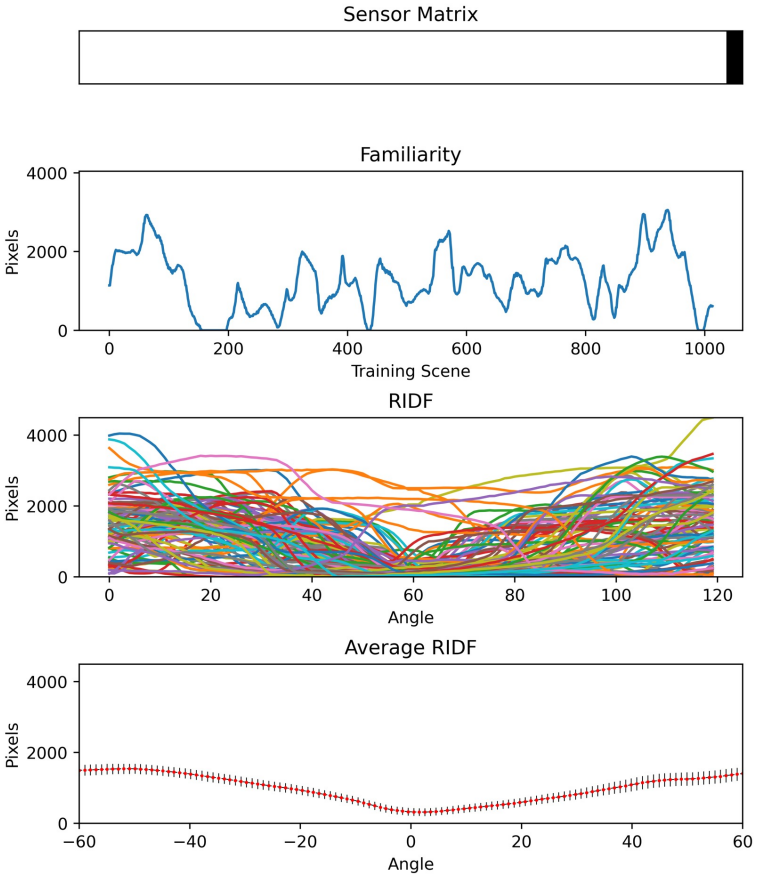
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 5688.00; RMSD/dist: 14.220; TD: 1066; p90: 86; p50: 38; complete: 0


Index: BLUR: 15.0; LEVELS: 64; TRIAL: 2
SAD (pixels)
2500
2000
1500
1000
500
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
30
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
75
50
25
0
p50
40
20
TD
1000
500
Sensor regions

0%

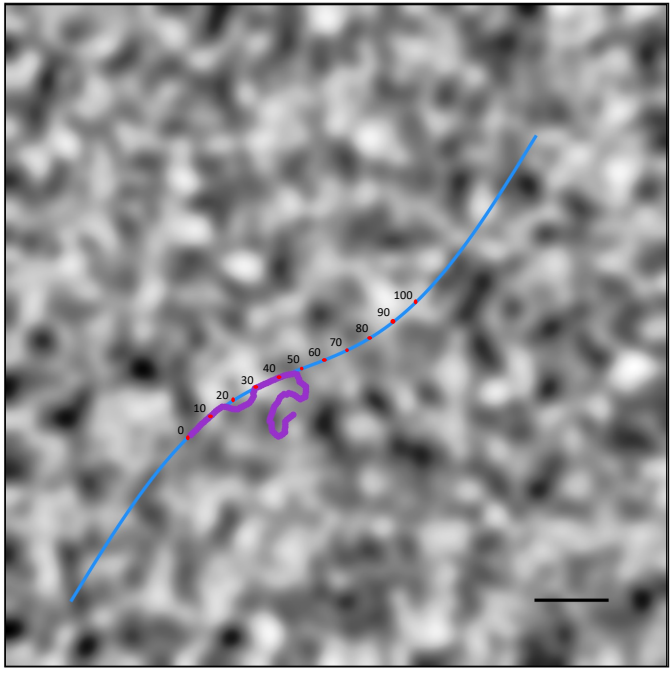


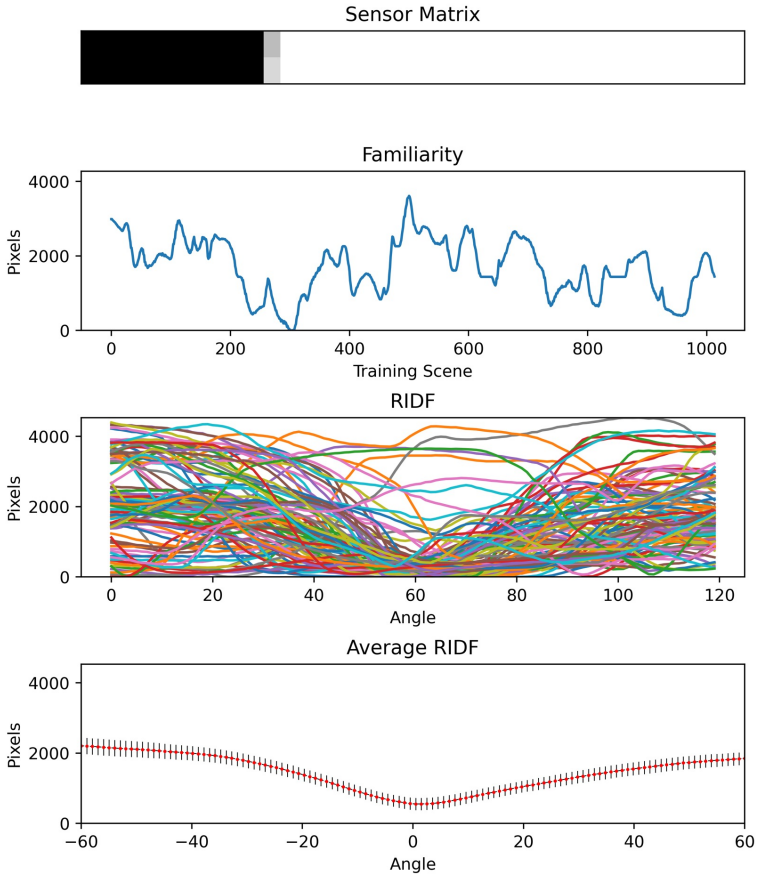


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 9224.17; RMSD/dist: 23.060; TD: 1291; p90: 90; p50: 42; complete: 0

30%

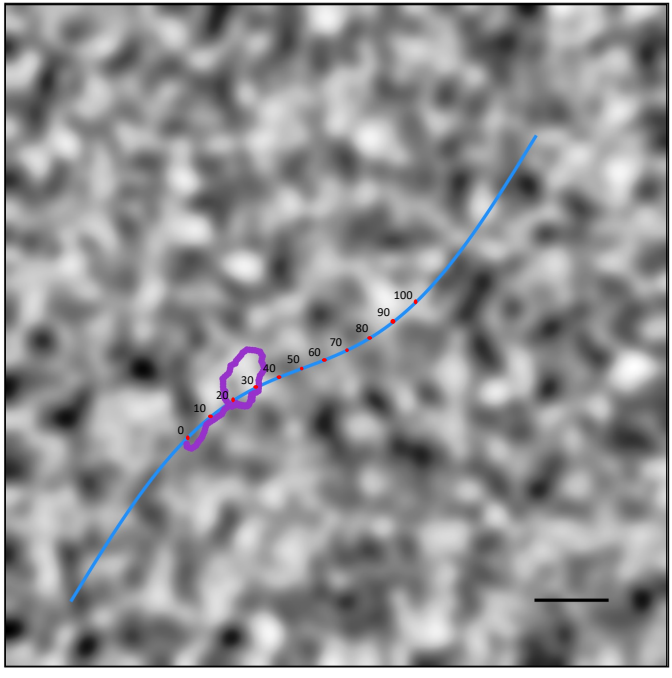


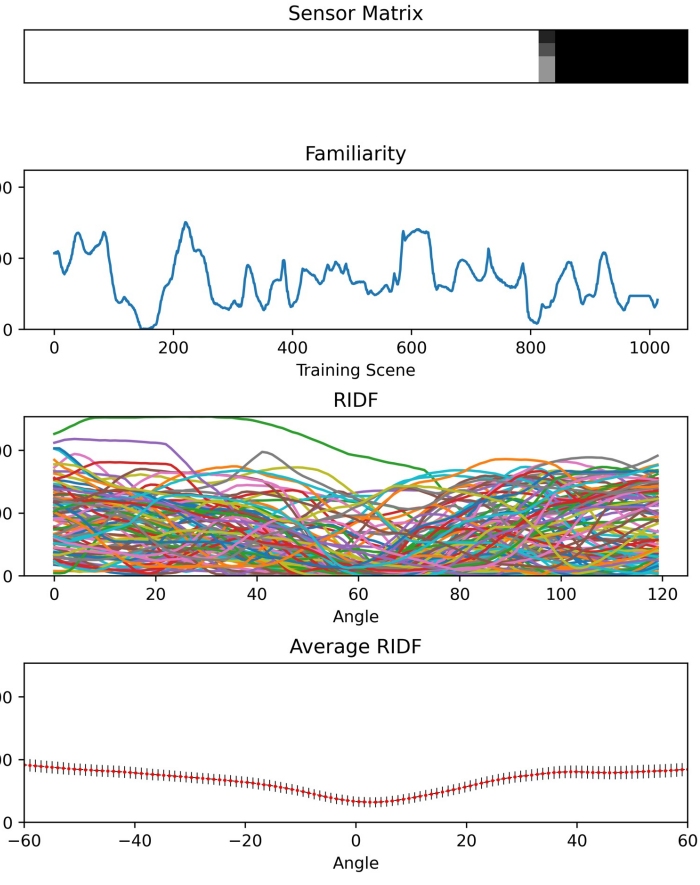


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2482.16; RMSD/dist: 6.205; TD: 1101; p90: 48; p50: 28; complete: 0

0%

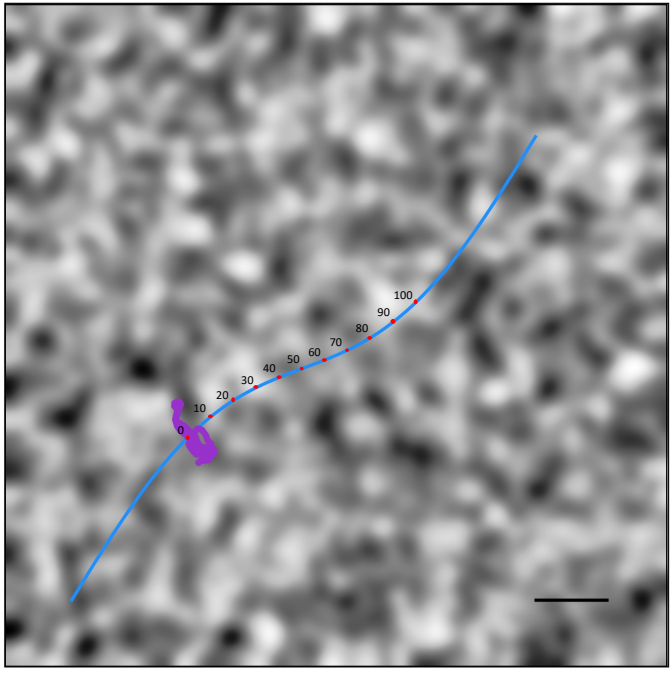


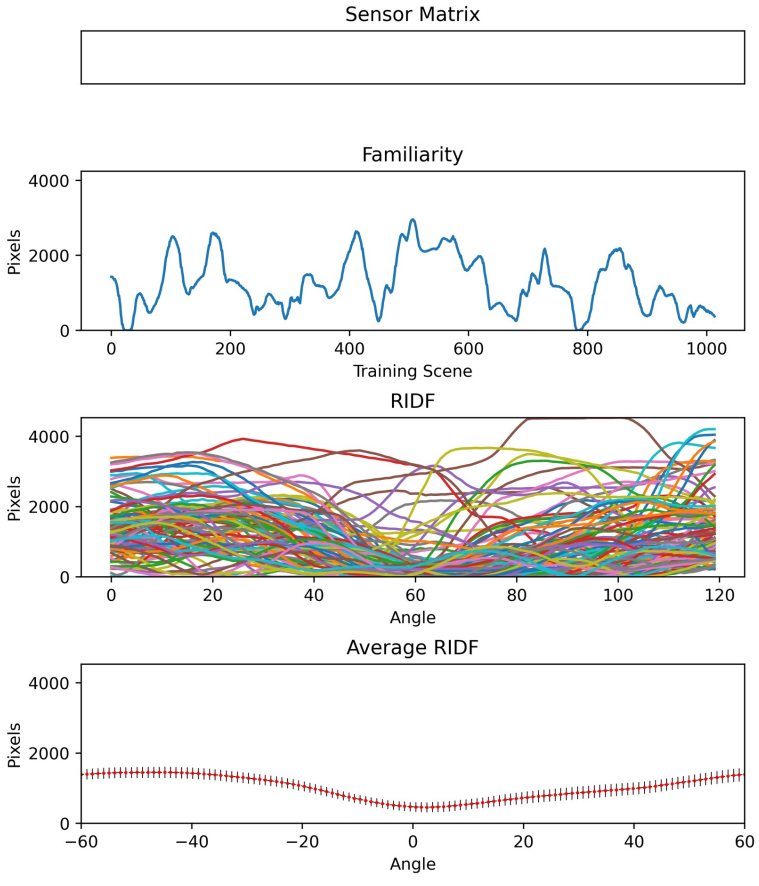


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2013.66; RMSD/dist: 5.034; TD: 663; p90: 36; p50: 20; complete: 0

0%

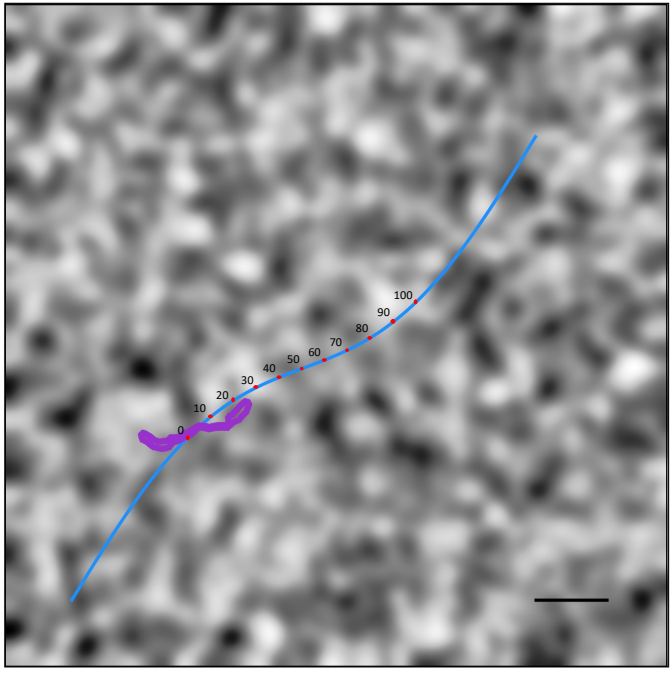


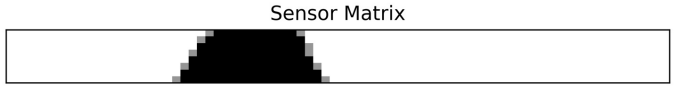


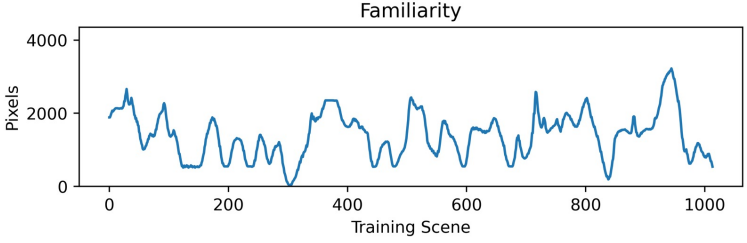
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

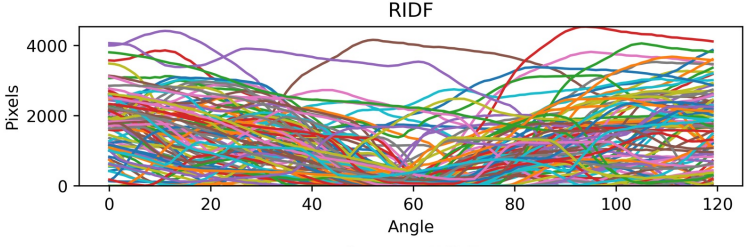
Navigation stats: RMSD error: 2564.09; RMSD/dist: 6.410; TD: 875; p90: 56; p50: 32; complete: 0

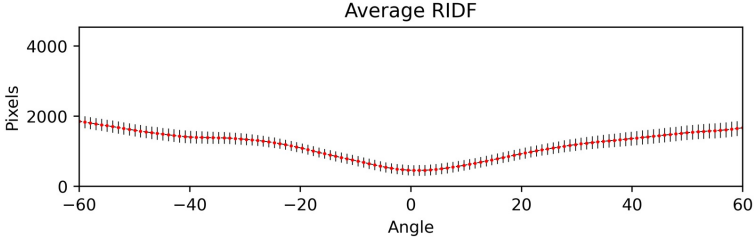
0%







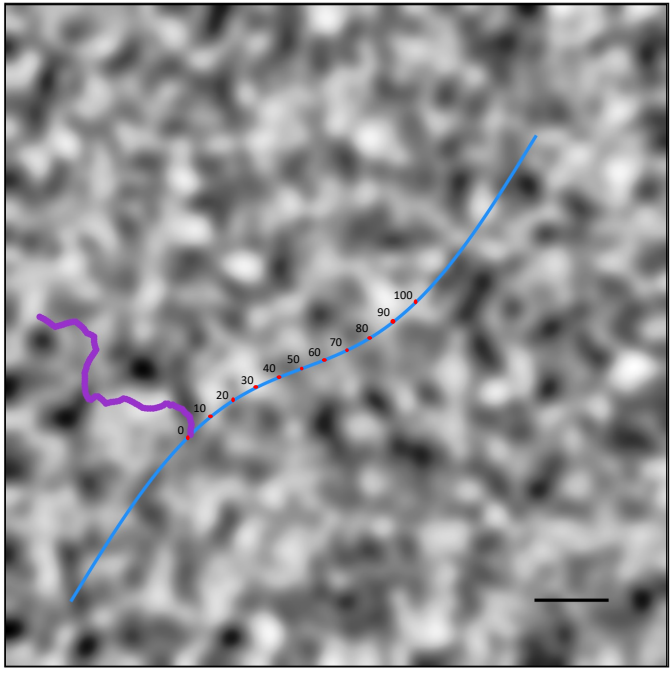


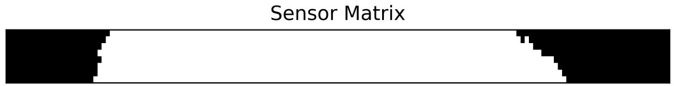


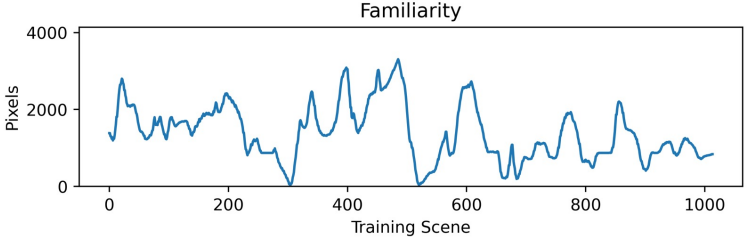
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

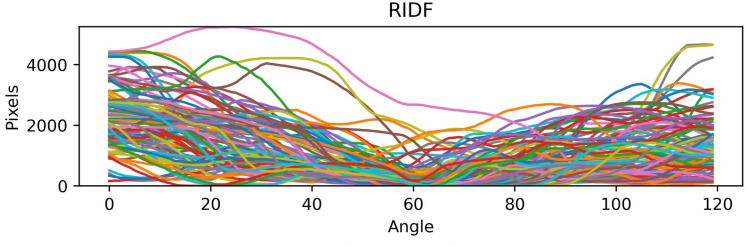
Navigation stats: RMSD error: 1867.67; RMSD/dist: 4.669; TD: 1120; p90: 88; p50: 36; complete: 0

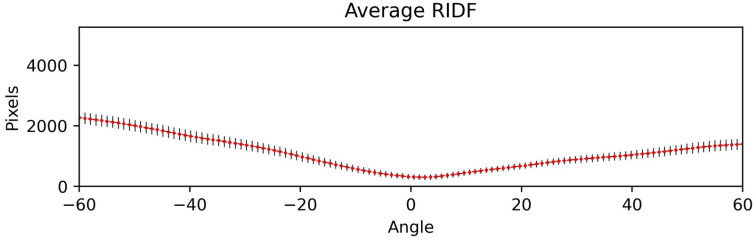
0%





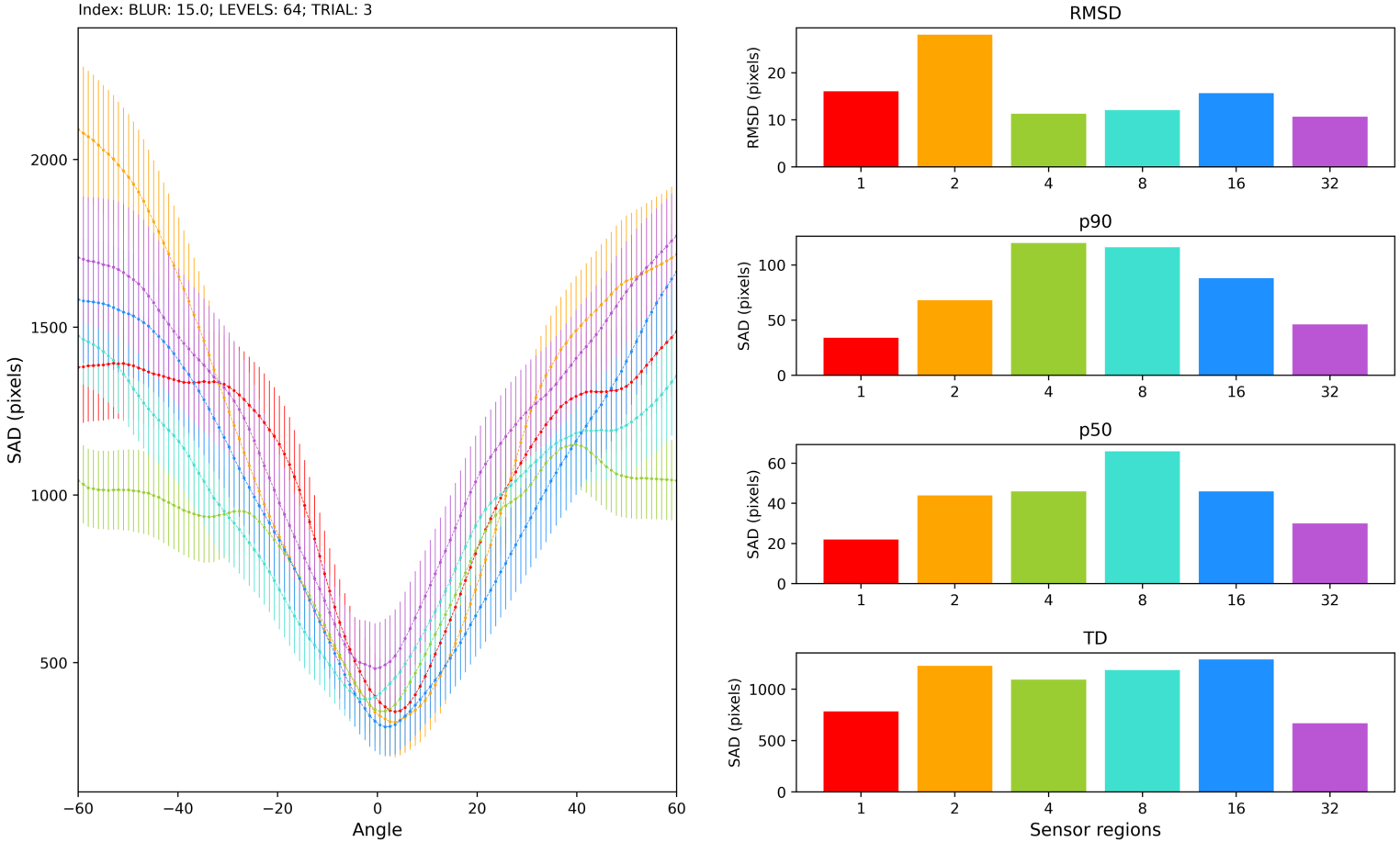




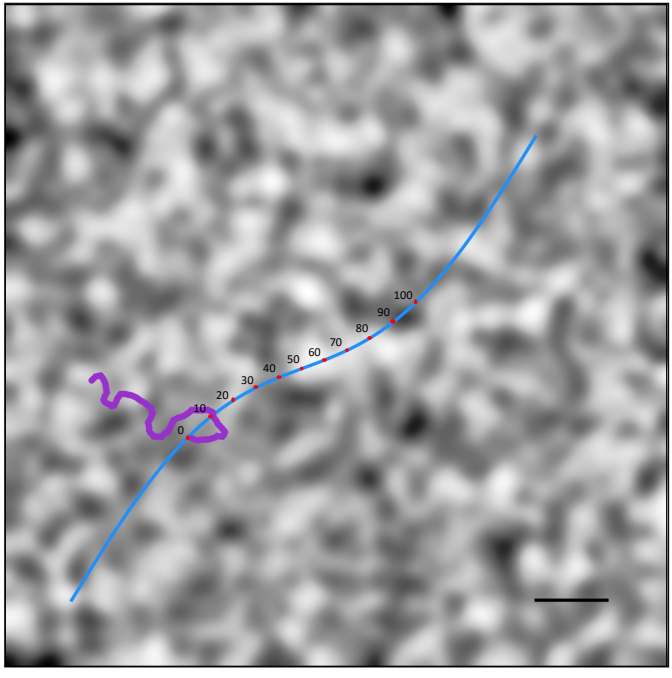


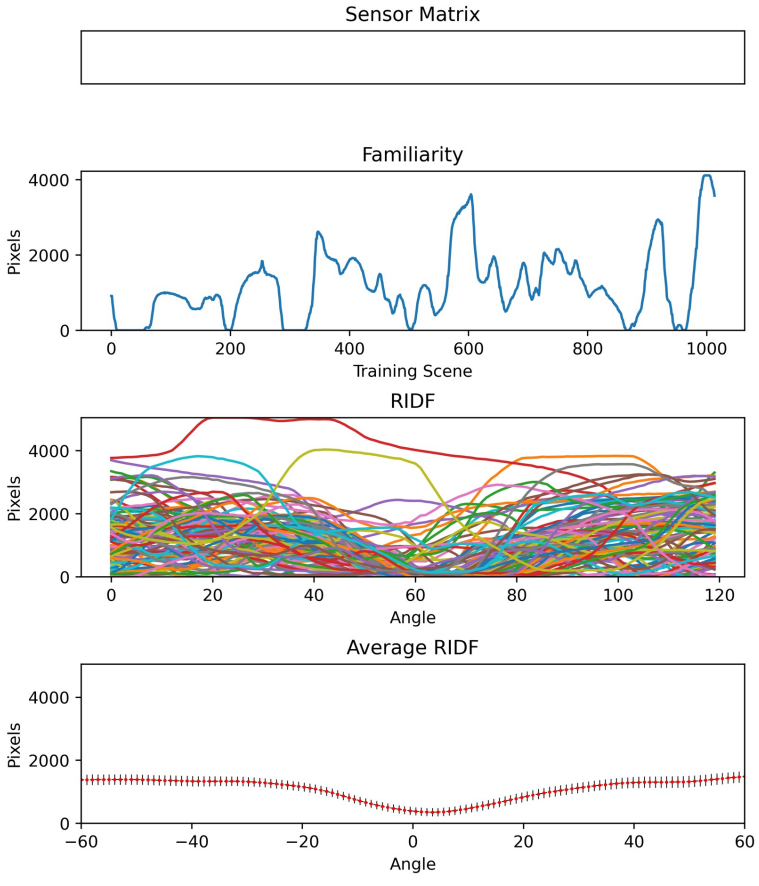
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 14480.12; RMSD/dist: 36.200; TD: 1196; p90: 62; p50: 36; complete: 0


Index: BLUR: 15.0; LEVELS: 64; TRIAL: 3
SAD (pixels)
2000
1500
1000
500
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0
10
20
1
2
4
8
16
32
p90
SAD (pixels)
0
50
100
p50
SAD (pixels)
0
20
40
60
TD
SAD (pixels)
0
500
1000
Sensor regions

0%

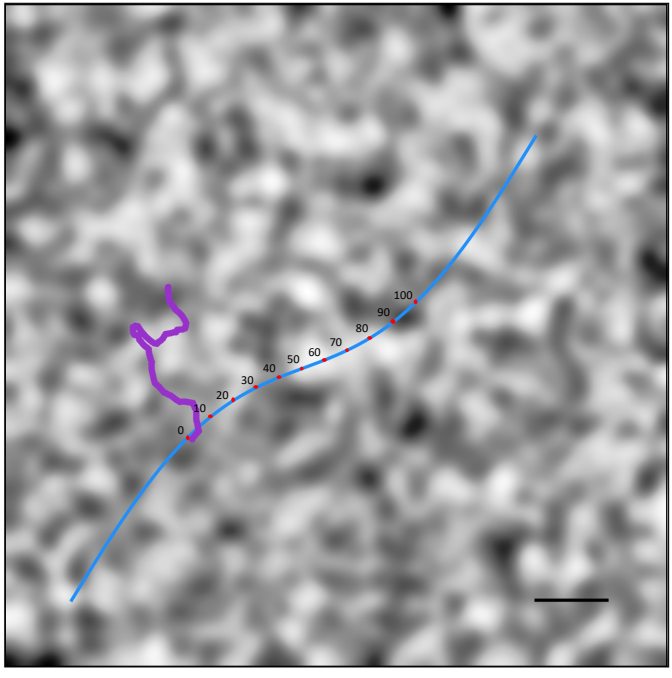


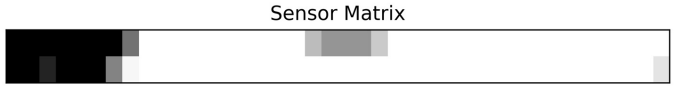


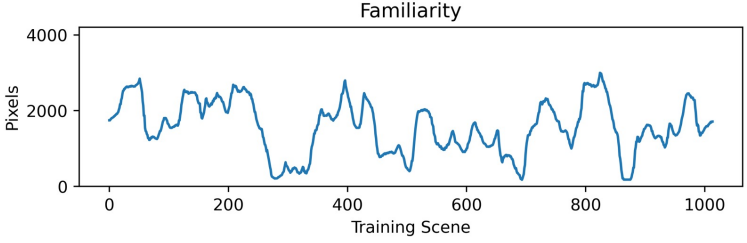
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

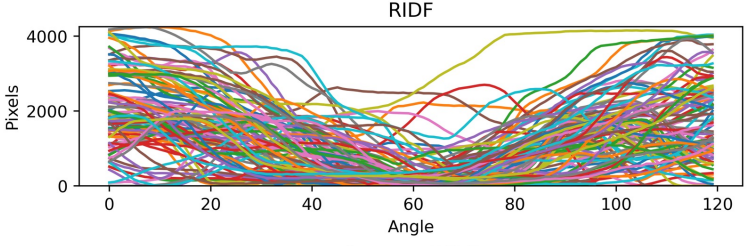
Navigation stats: RMSD error: 6432.81; RMSD/dist: 16.082; TD: 785; p90: 34; p50: 22; complete: 0

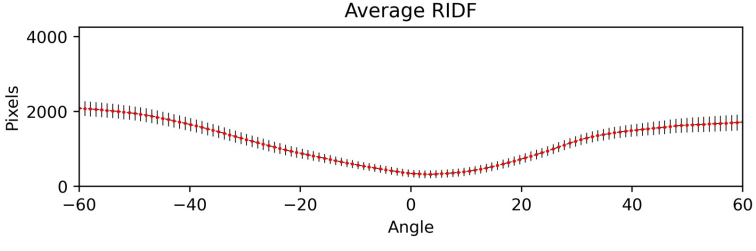
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 11241.97; RMSD/dist: 28.105; TD: 1228; p90: 68; p50: 44; complete: 0

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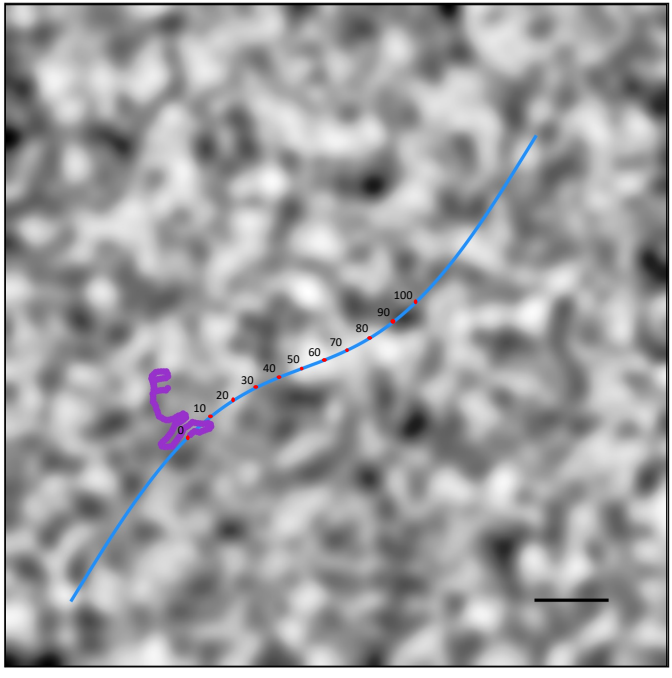

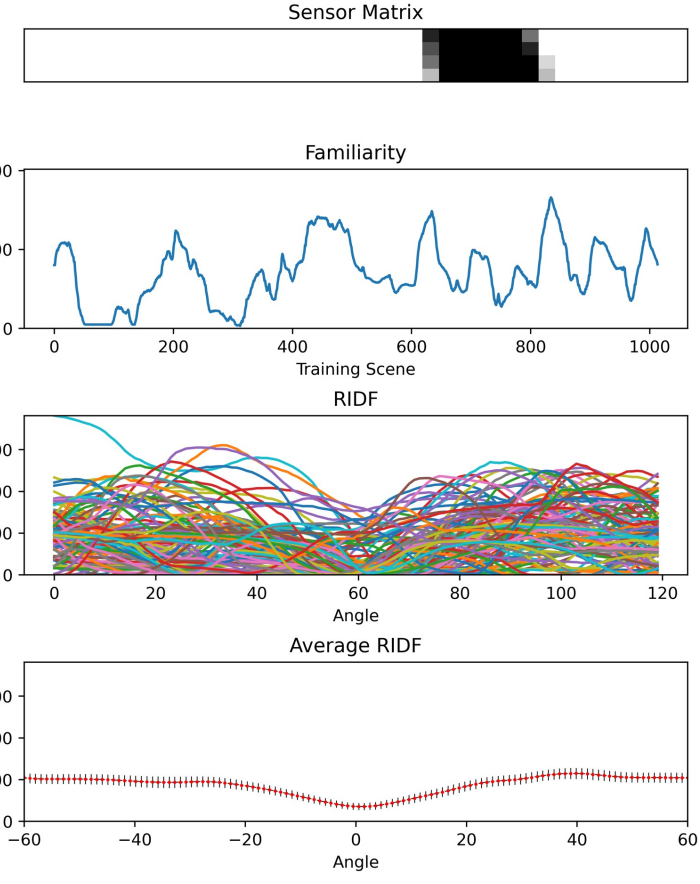

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4520.79; RMSD/dist: 11.302; TD: 1093; p90: 120; p50: 46; complete: 0

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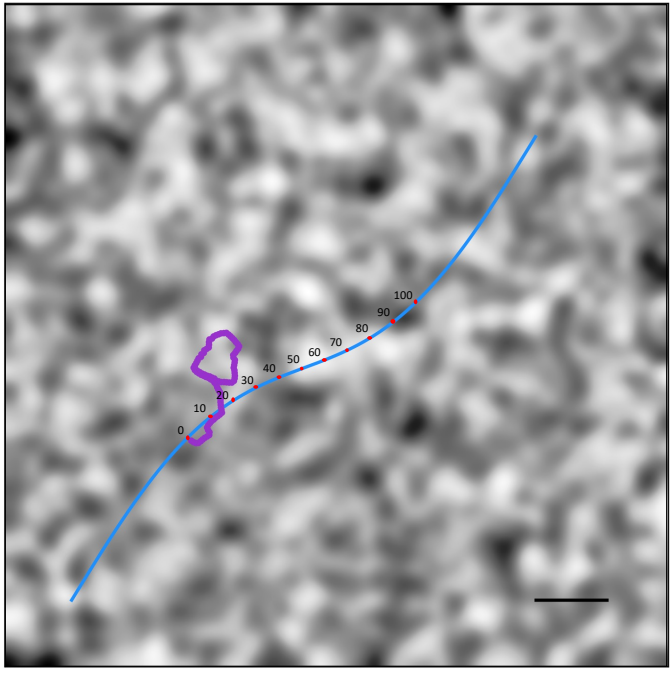
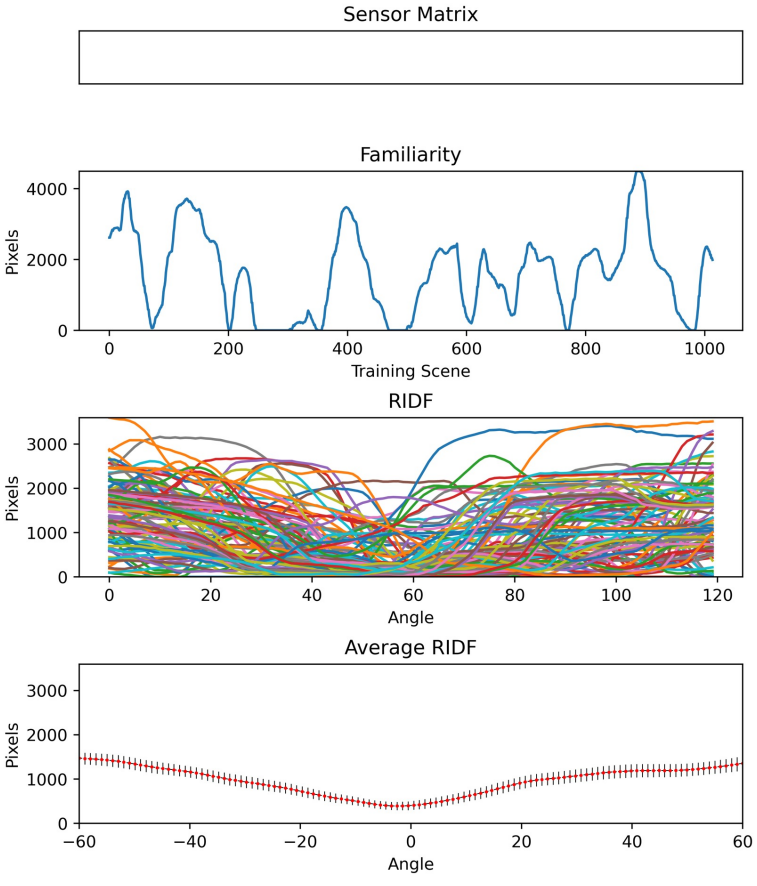
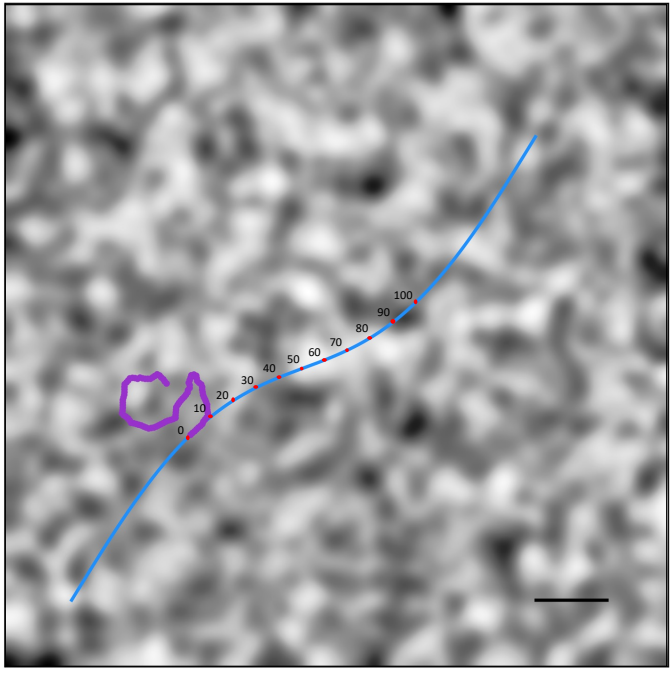


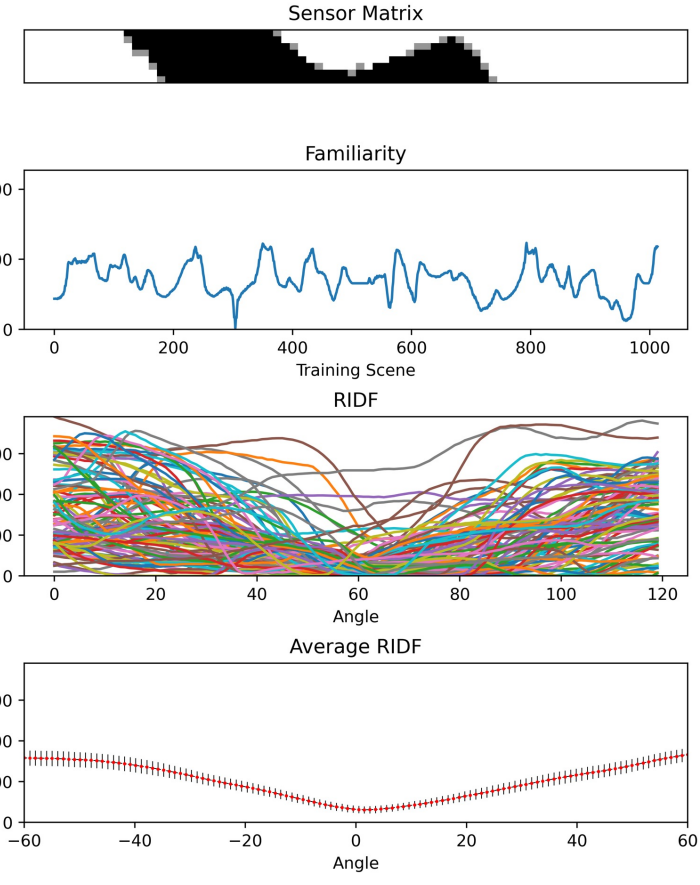


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4828.15; RMSD/dist: 12.070; TD: 1187; p90: 116; p50: 66; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 6266.23; RMSD/dist: 15.666; TD: 1289; p90: 88; p50: 46; complete: 0

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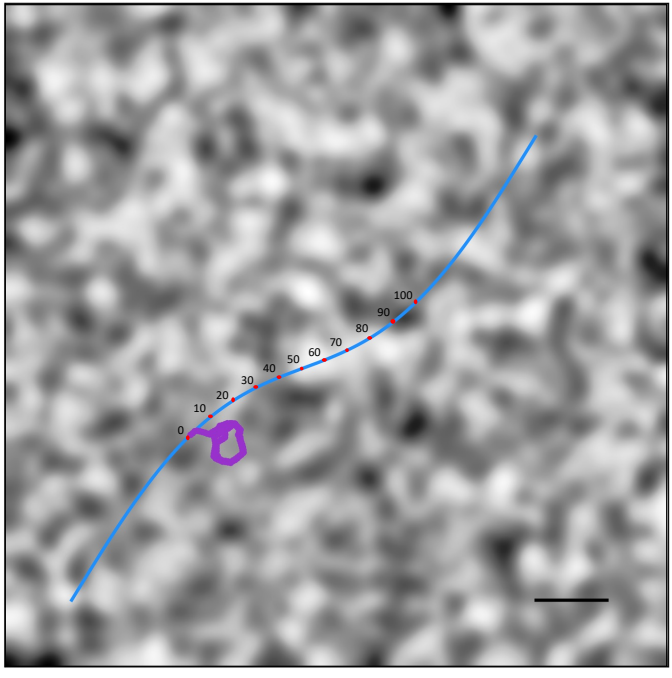
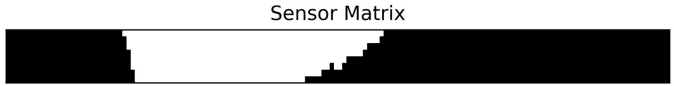
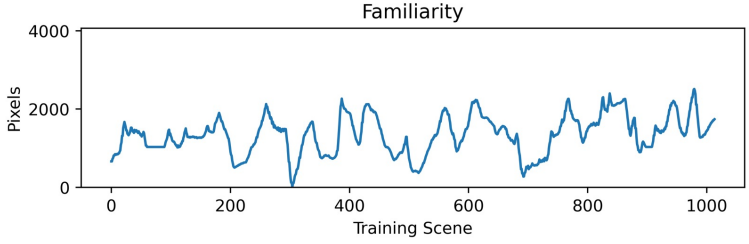
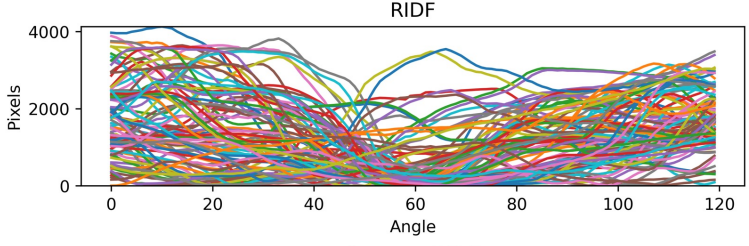
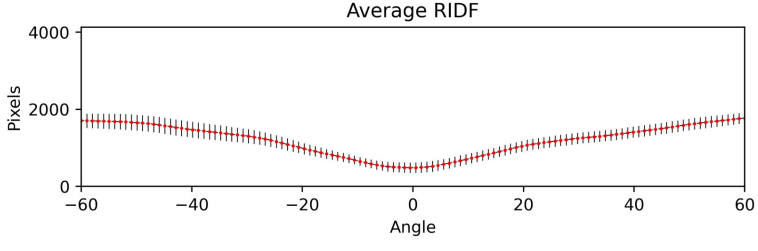




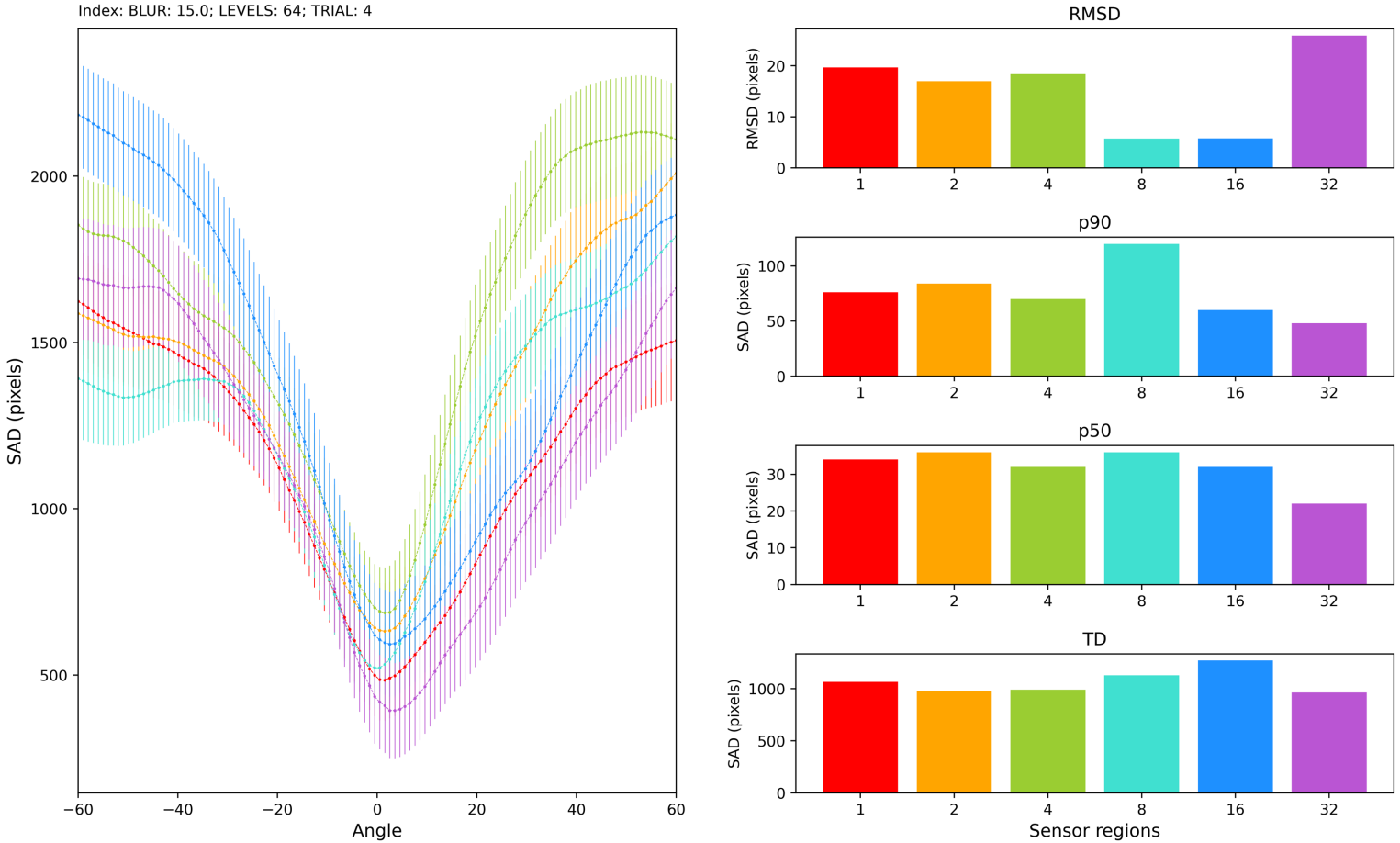






Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4256.53; RMSD/dist: 10.641; TD: 668; p90: 46; p50: 30; complete: 0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1000
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−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
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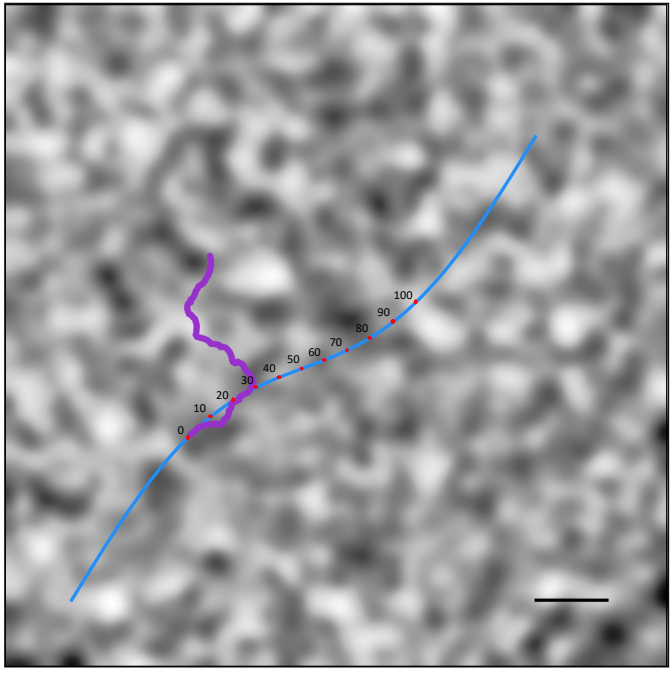
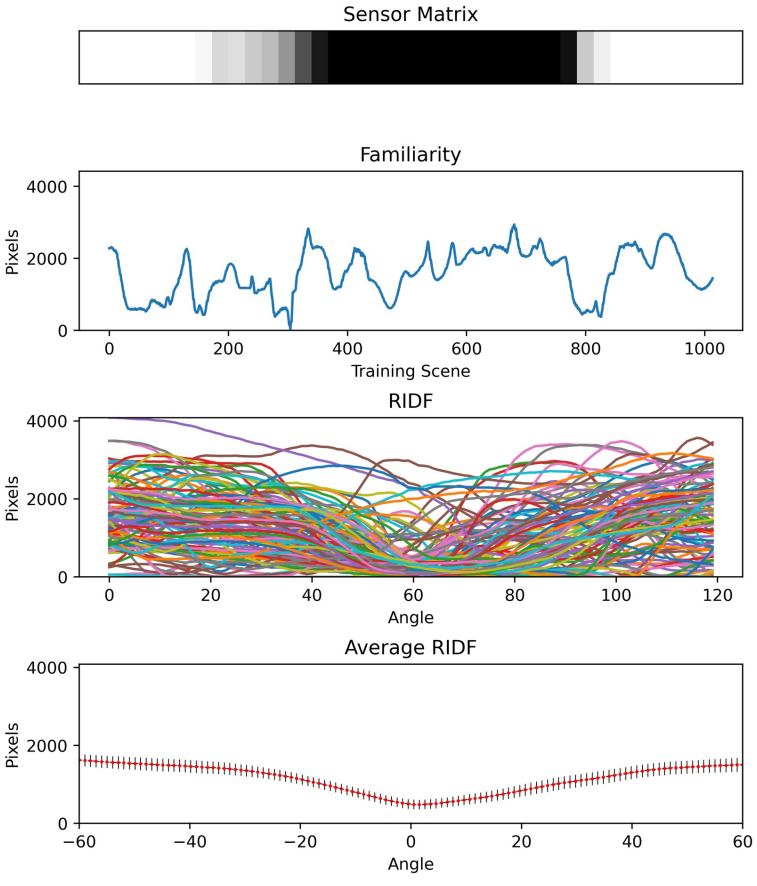
50
0
p50
30
20
10
TD
1000
500
Sensor regions

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 7870.92; RMSD/dist: 19.677; TD: 1066; p90: 76; p50: 34; complete: 0

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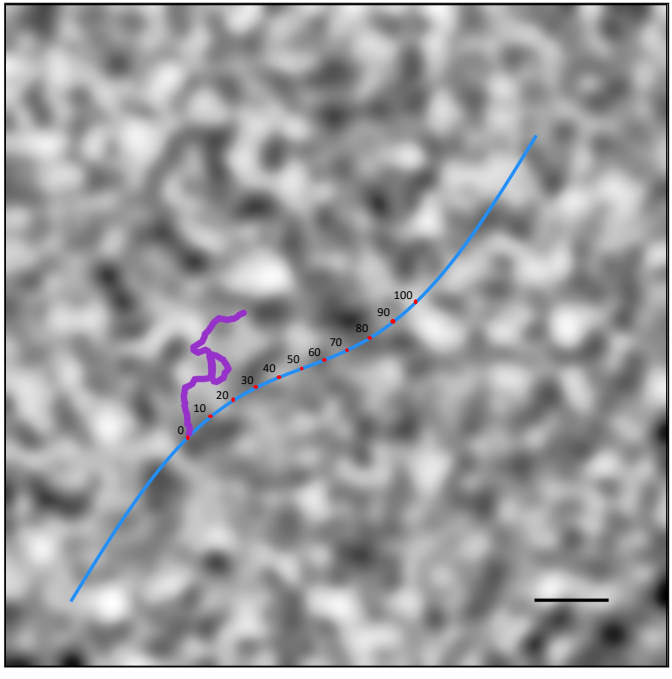
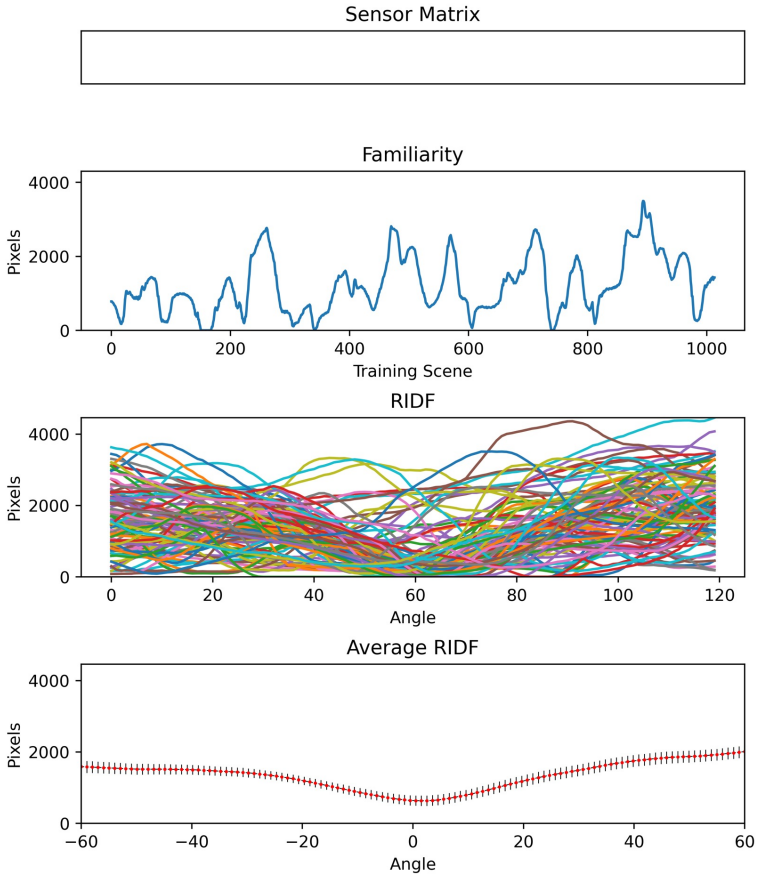
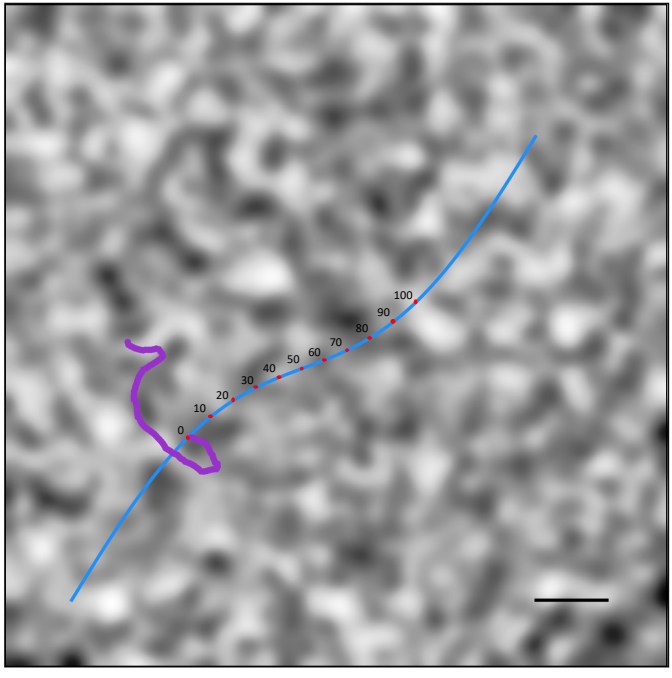


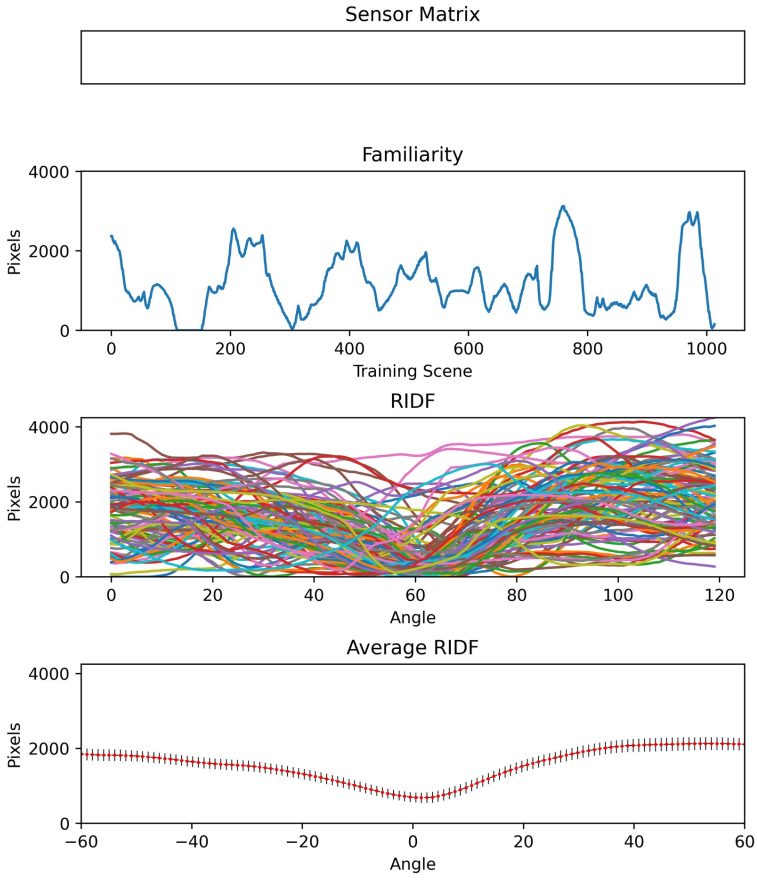


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 6784.32; RMSD/dist: 16.961; TD: 975; p90: 84; p50: 36; complete: 0

0%

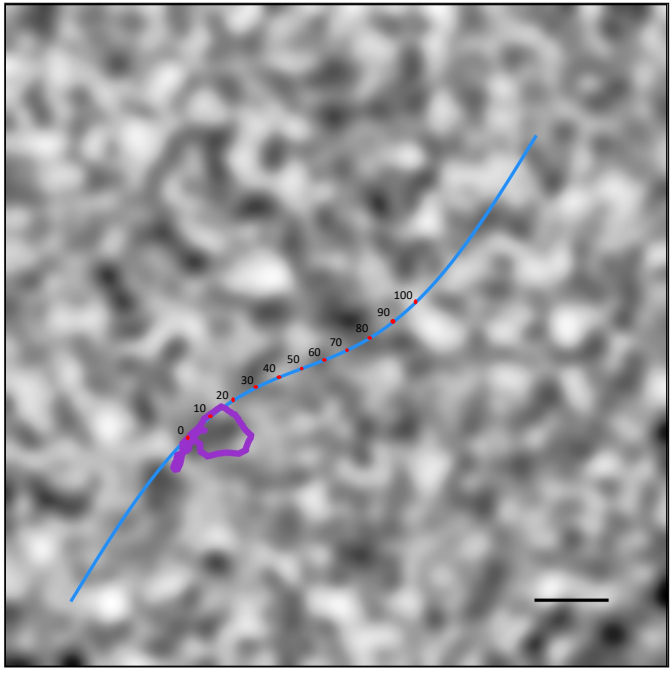


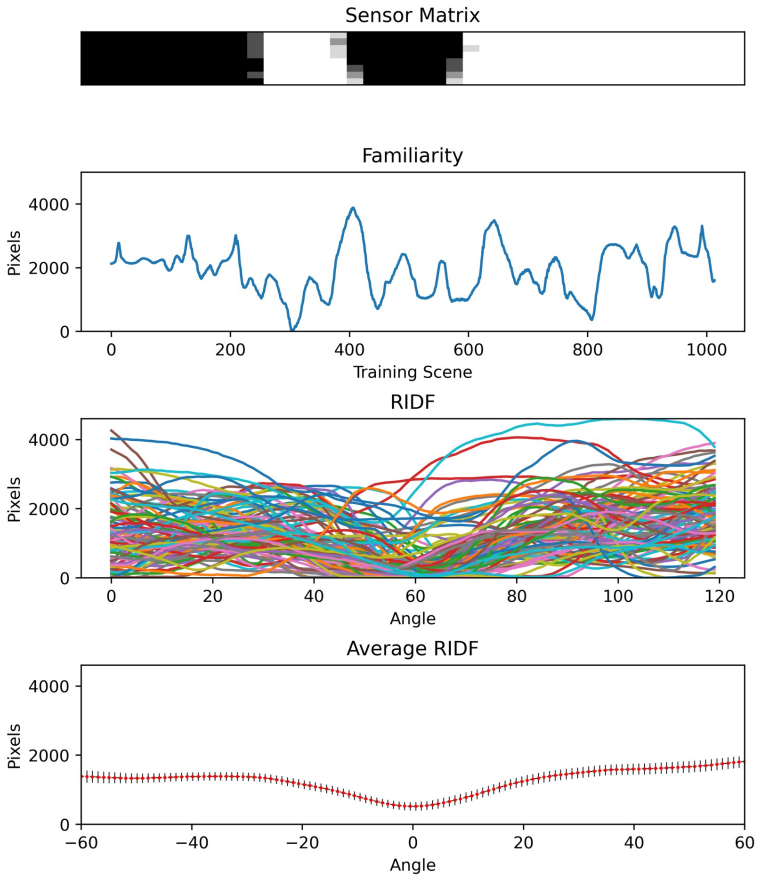


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 7338.08; RMSD/dist: 18.345; TD: 990; p90: 70; p50: 32; complete: 0

10%

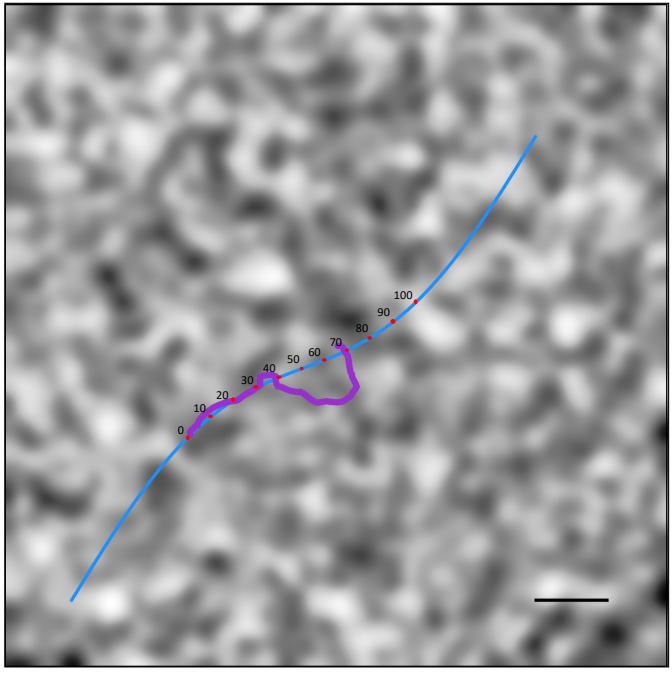


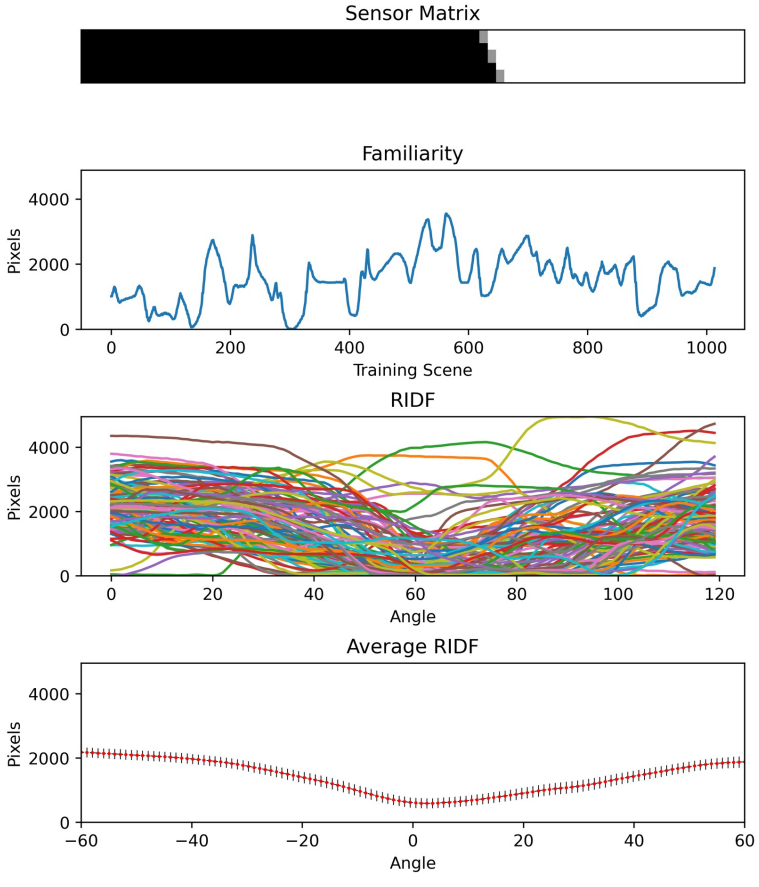


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2290.98; RMSD/dist: 5.727; TD: 1129; p90: 120; p50: 36; complete: 0

10%

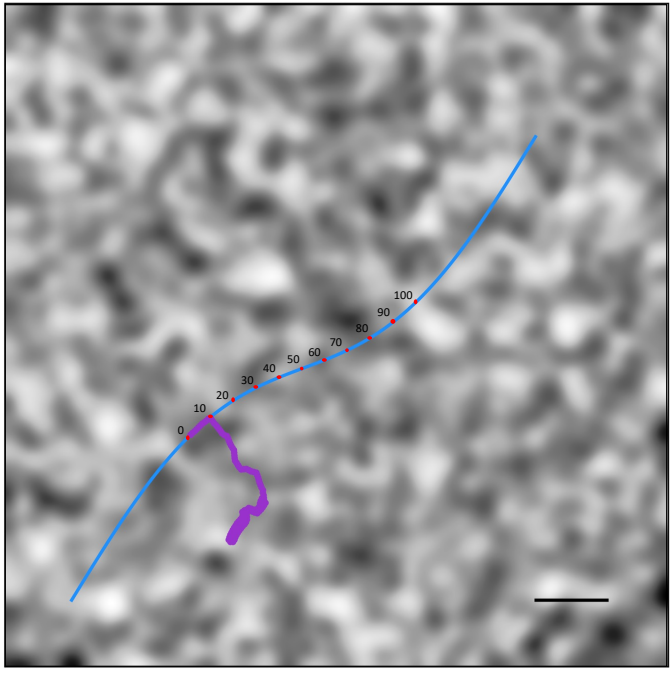


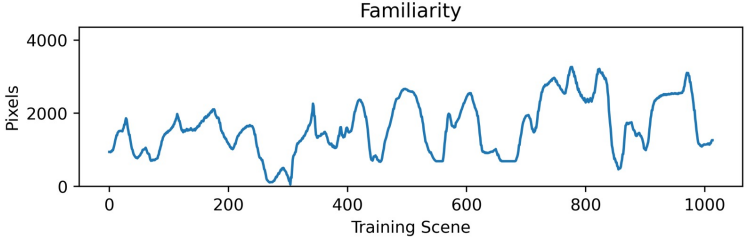


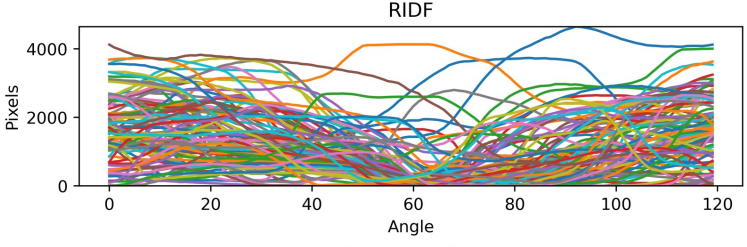
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

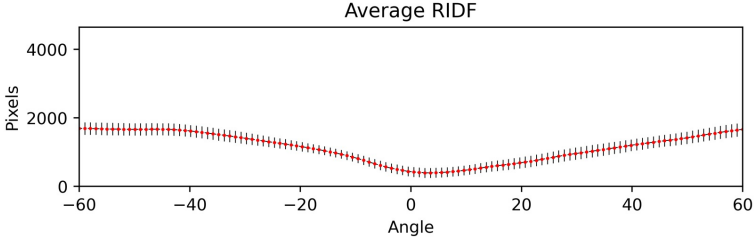
Navigation stats: RMSD error: 2296.42; RMSD/dist: 5.741; TD: 1270; p90: 60; p50: 32; complete: 0

10%



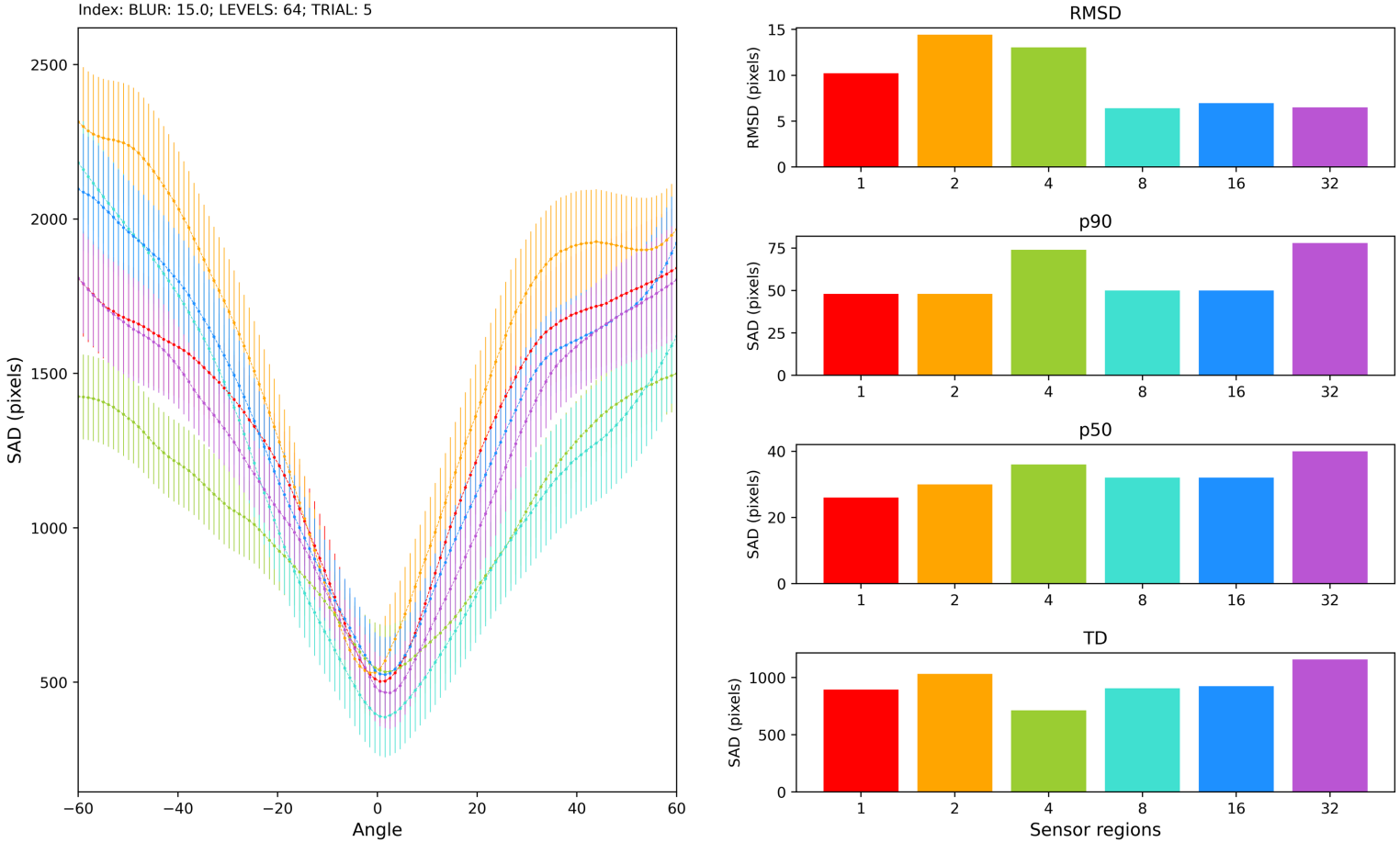






Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 10359.91; RMSD/dist: 25.900; TD: 963; p90: 48; p50: 22; complete: 0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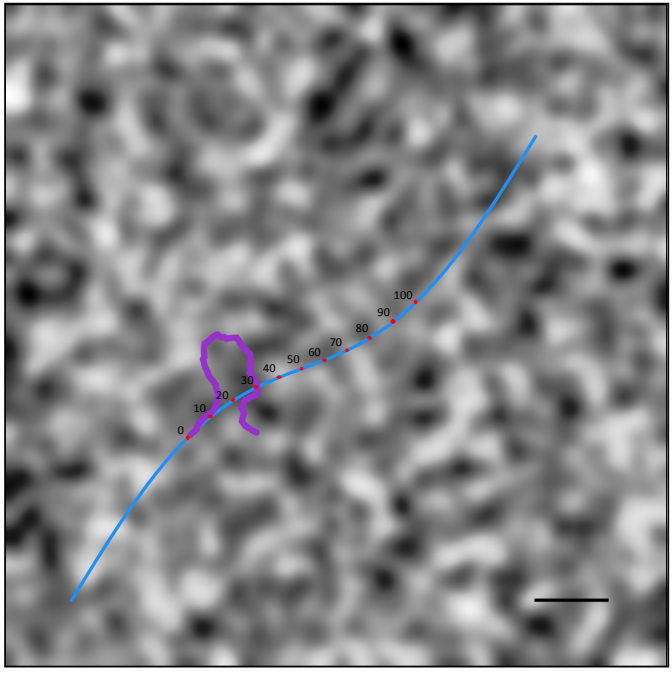
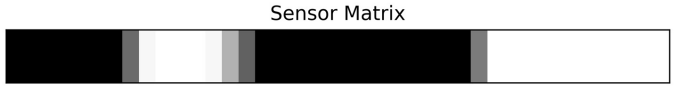
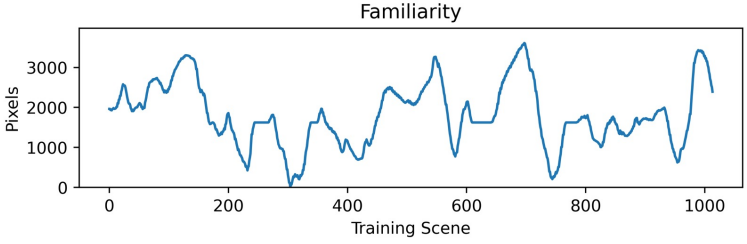
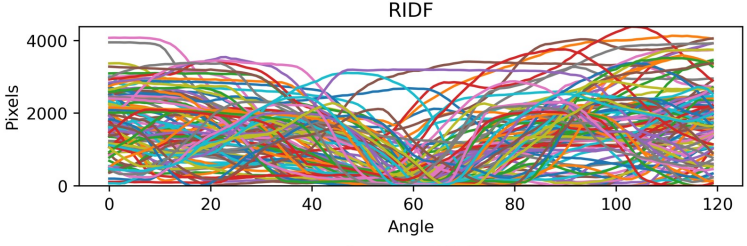
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
15
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
75
50
25
0
p50
40
20
TD
1000
500
Sensor regions

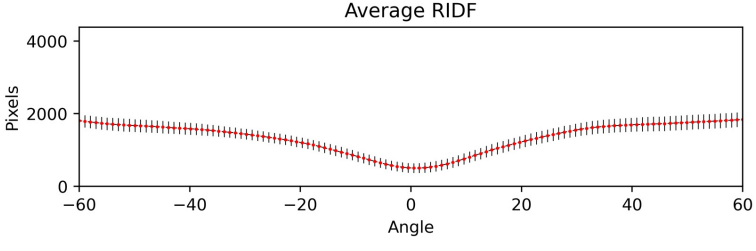
0%







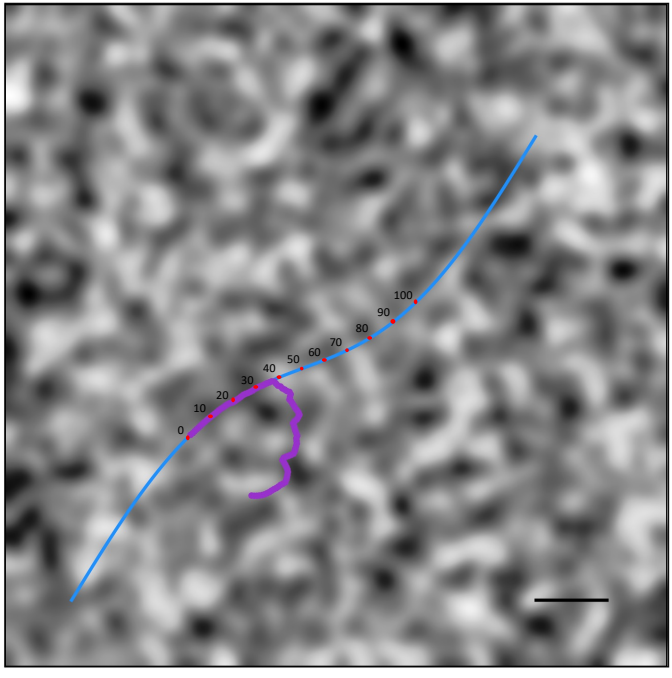


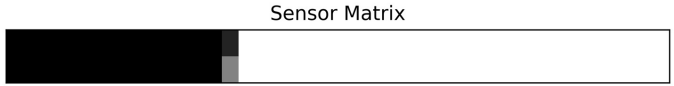


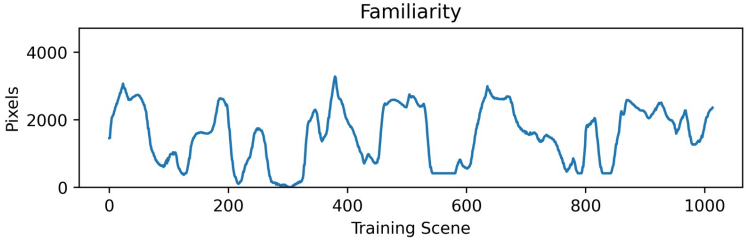
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

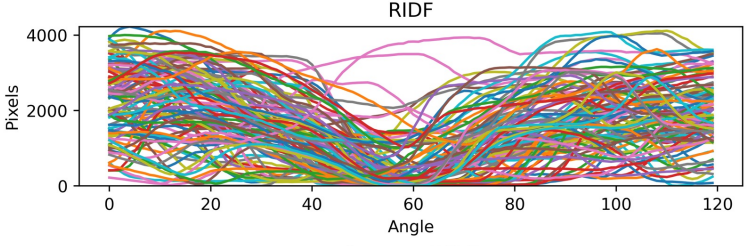
Navigation stats: RMSD error: 4090.06; RMSD/dist: 10.225; TD: 893; p90: 48; p50: 26; complete: 0

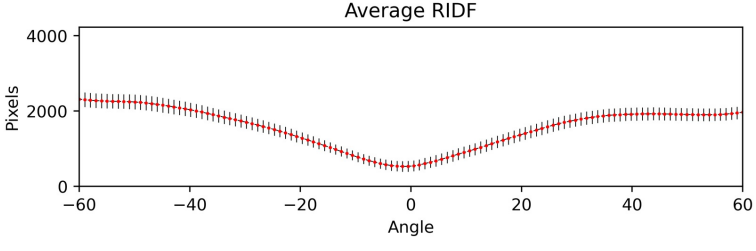
30%







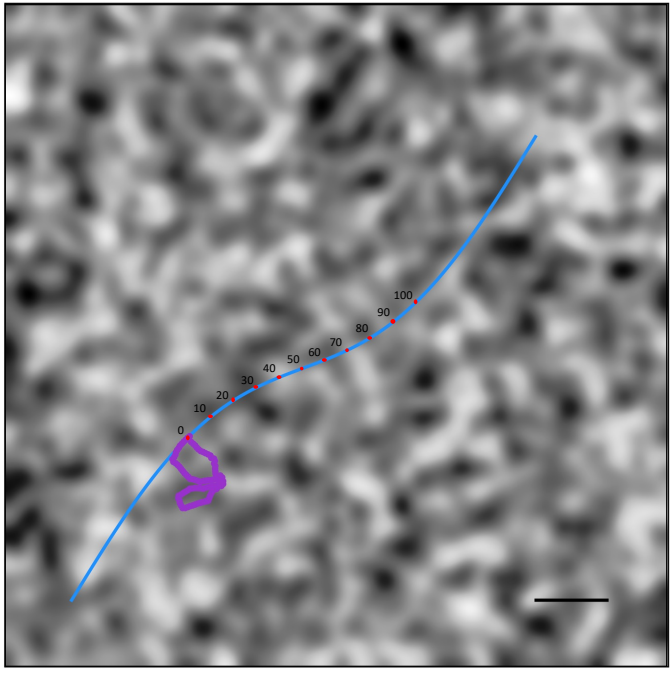


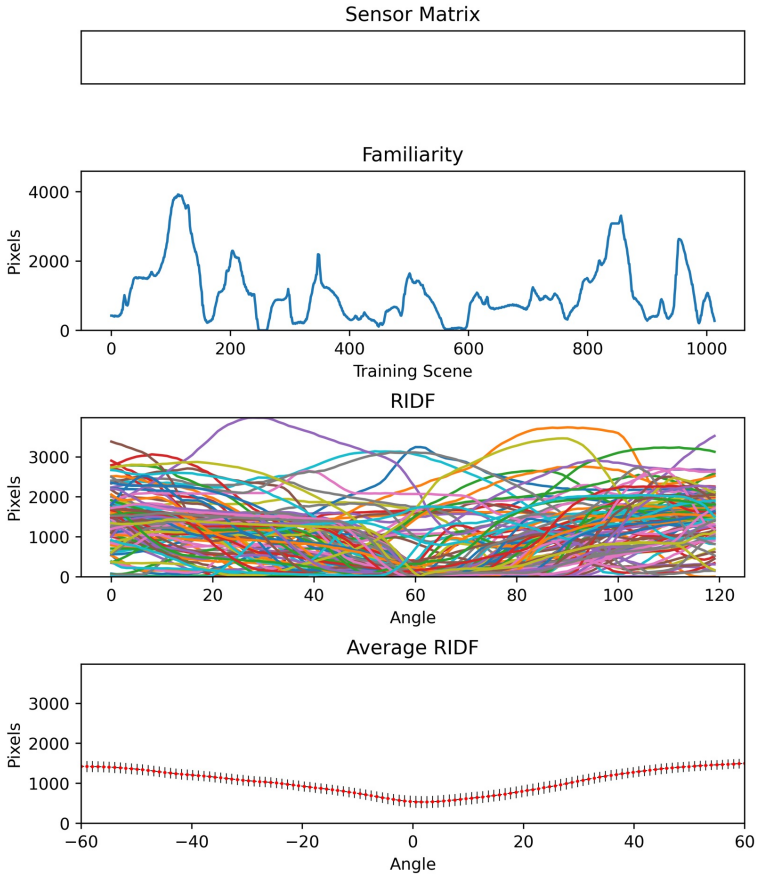


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5777.18; RMSD/dist: 14.443; TD: 1031; p90: 48; p50: 30; complete: 0

0%

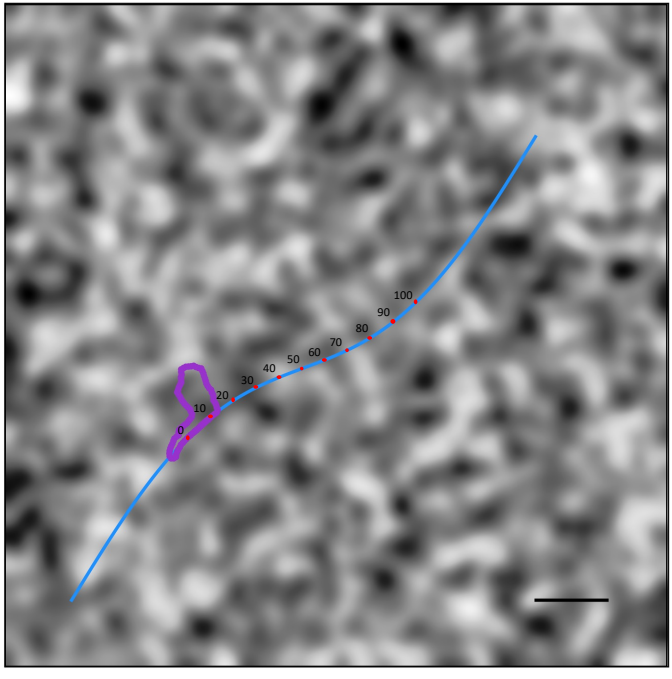


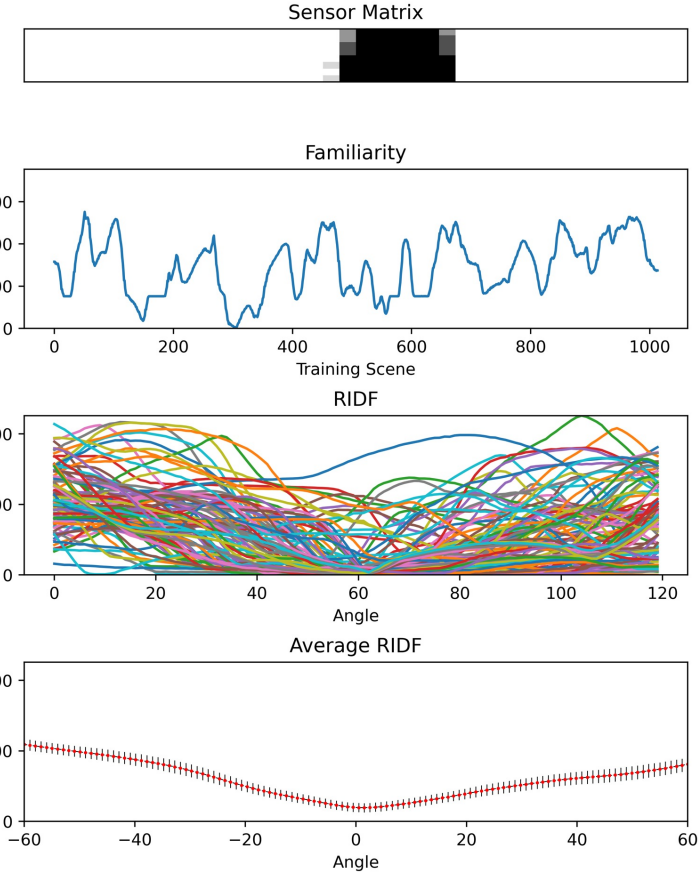


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5219.69; RMSD/dist: 13.049; TD: 713; p90: 74; p50: 36; complete: 0

10%

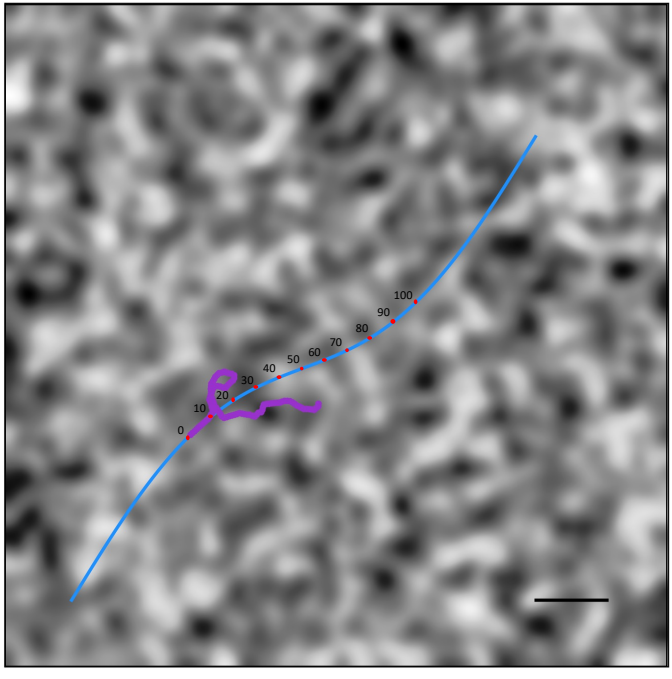


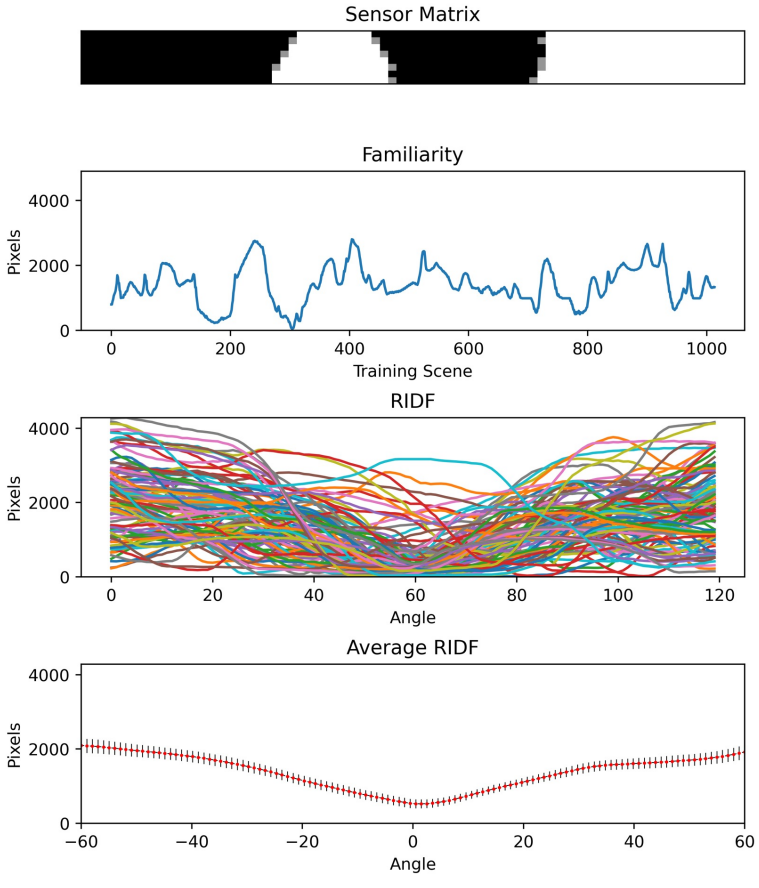


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2560.65; RMSD/dist: 6.402; TD: 905; p90: 50; p50: 32; complete: 0

10%

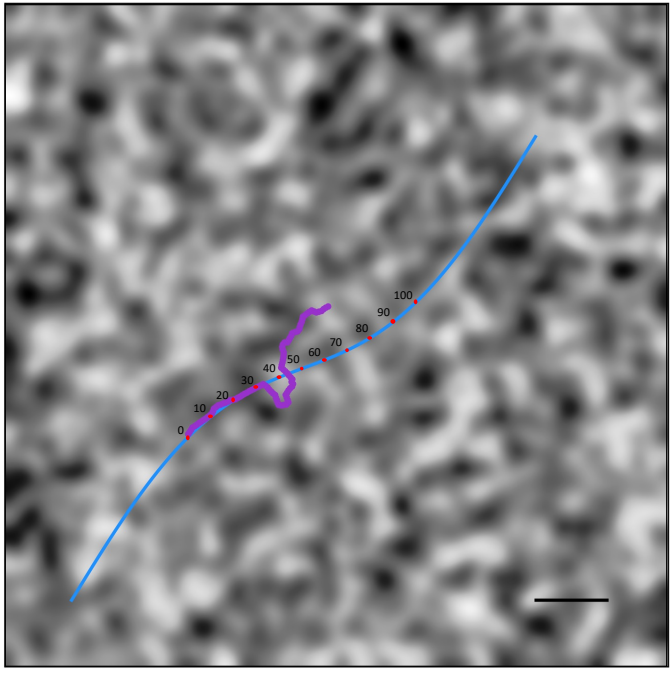


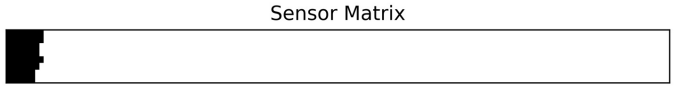


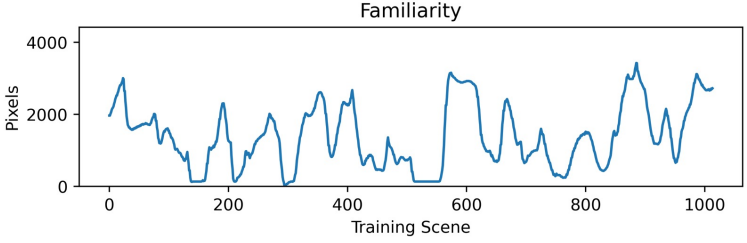
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

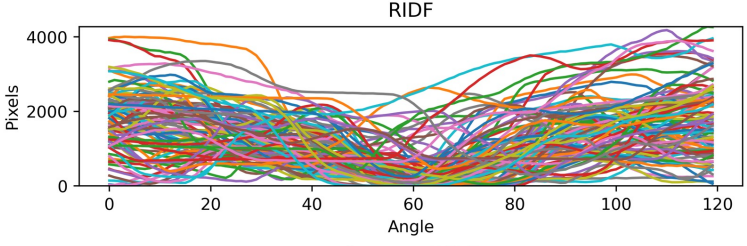
Navigation stats: RMSD error: 2780.47; RMSD/dist: 6.951; TD: 923; p90: 50; p50: 32; complete: 0

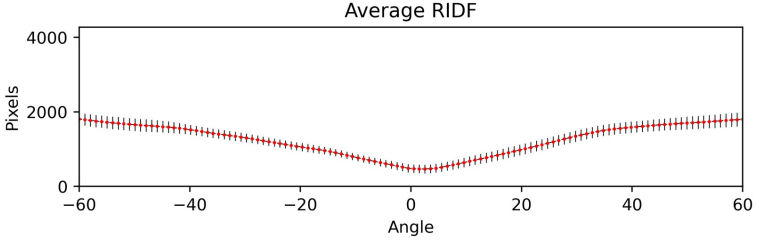
20%





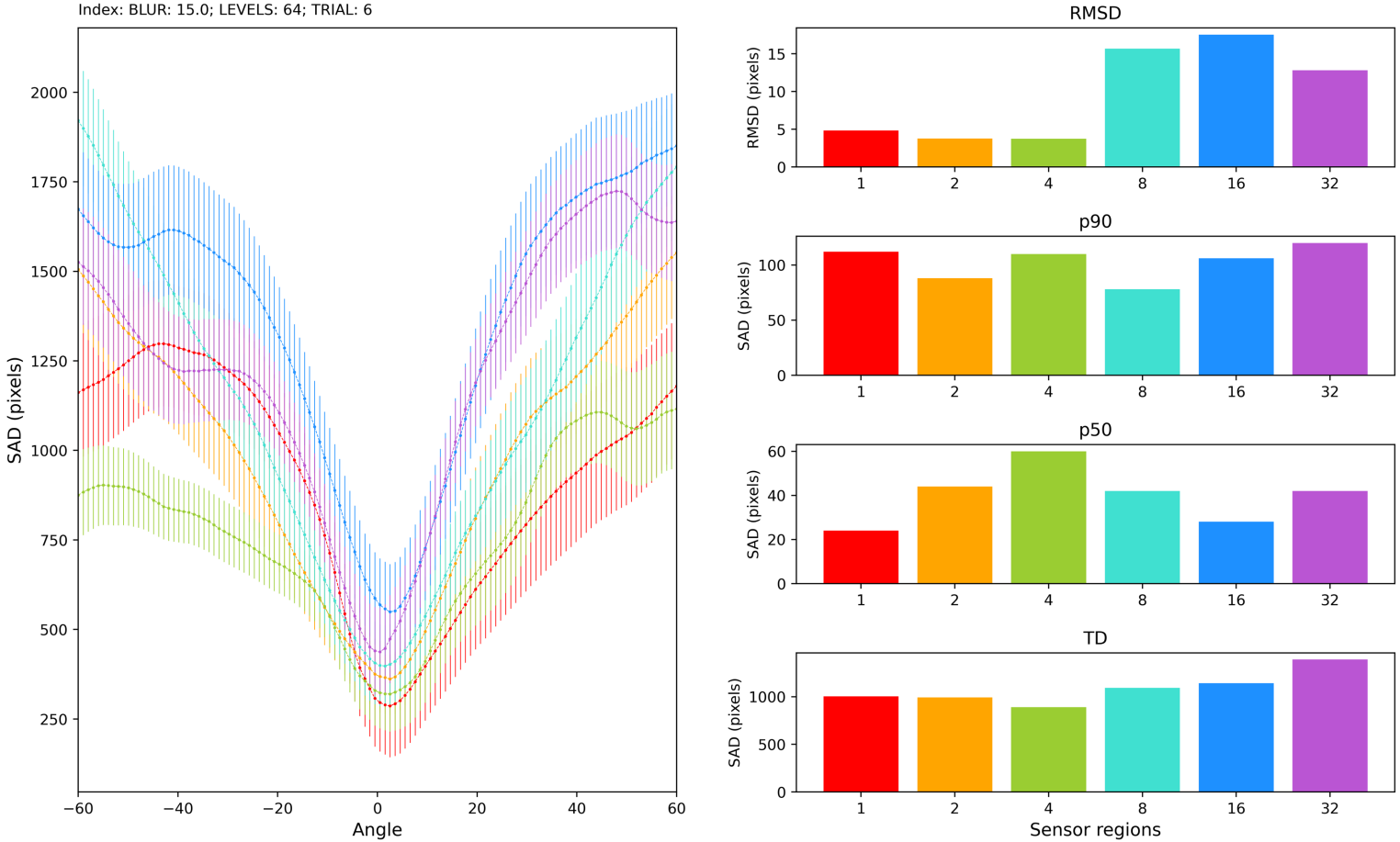




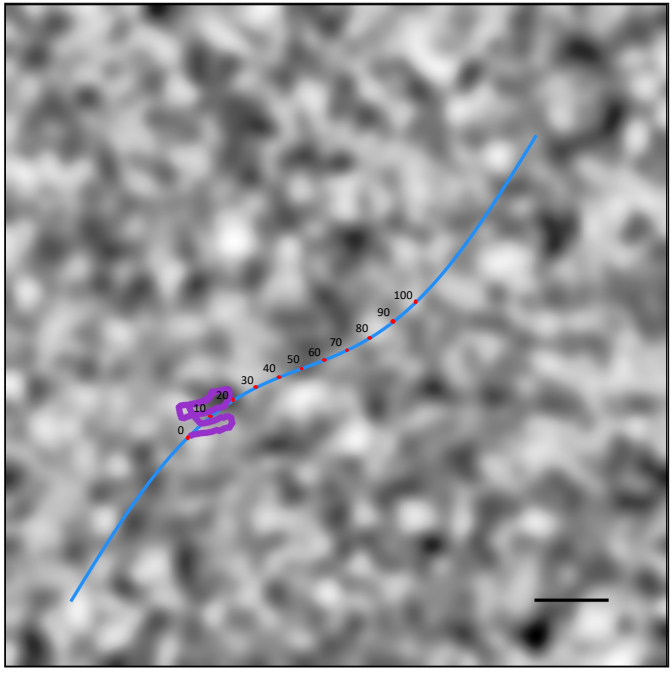


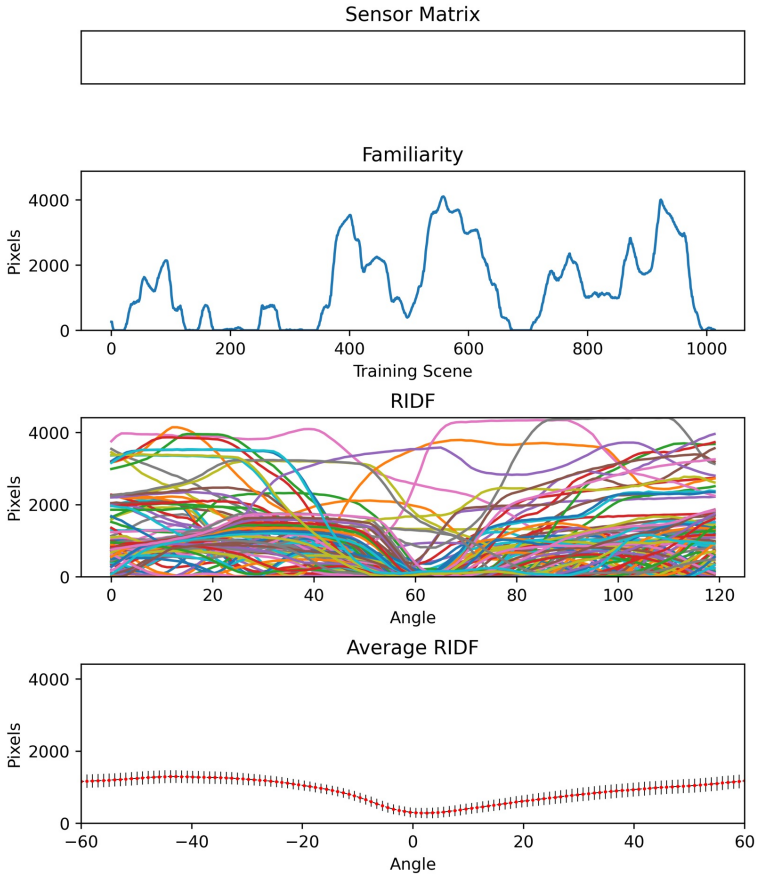
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2602.26; RMSD/dist: 6.506; TD: 1156; p90: 78; p50: 40; complete: 0


Index: BLUR: 15.0; LEVELS: 64; TRIAL: 6
SAD (pixels)
2000
1750
1500
1250
1000
750
500
250
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
15
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
SAD (pixels)
60
40
20
TD
SAD (pixels)
1000
500
Sensor regions

0%

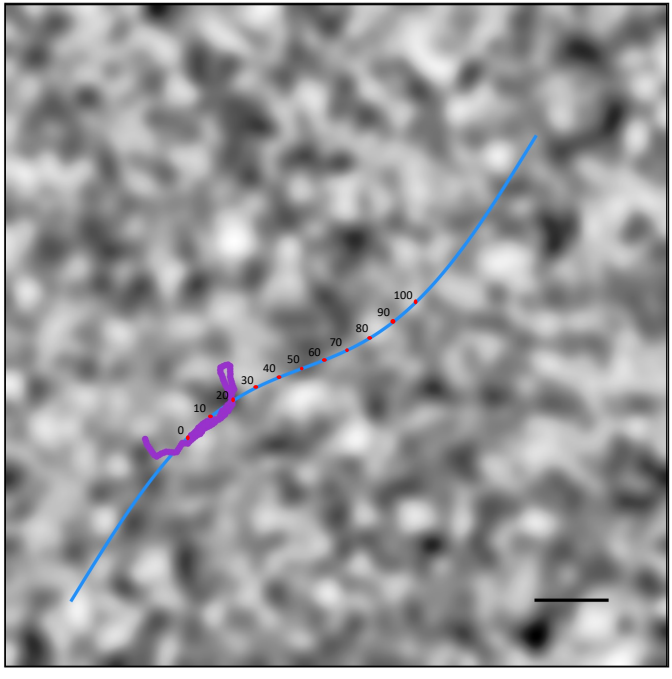


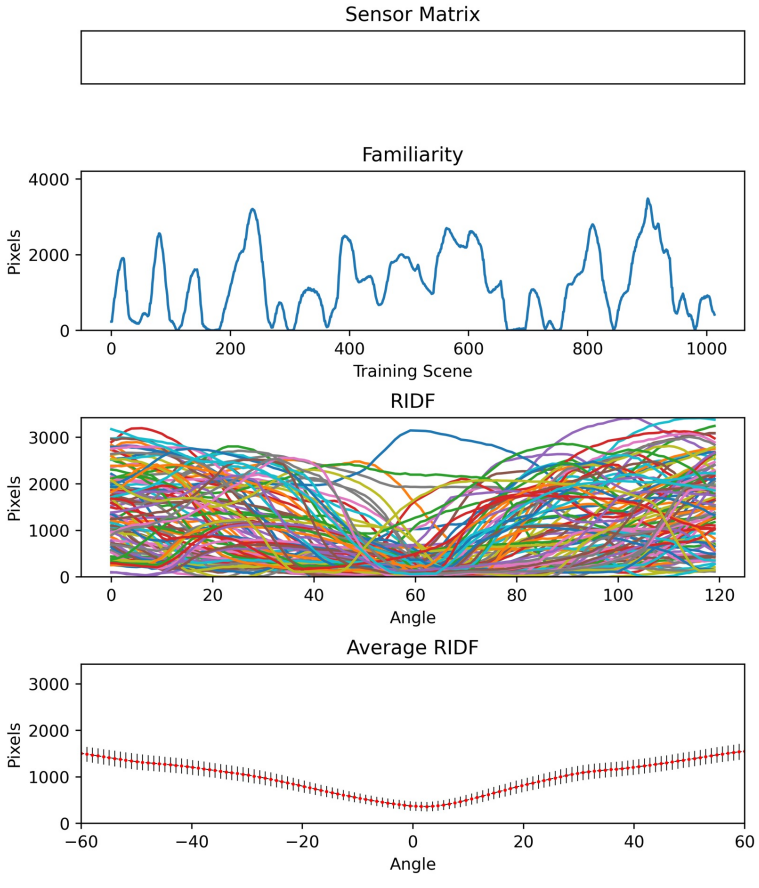


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1936.06; RMSD/dist: 4.840; TD: 1004; p90: 112; p50: 24; complete: 0

10%

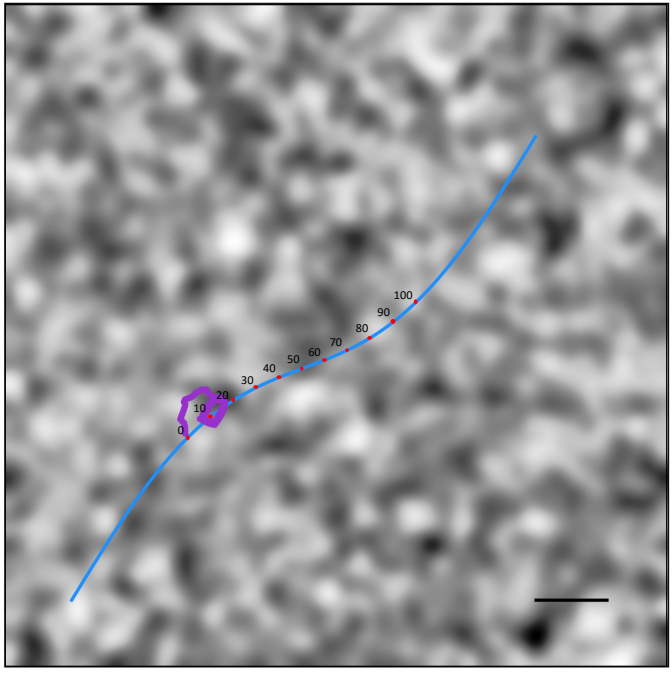


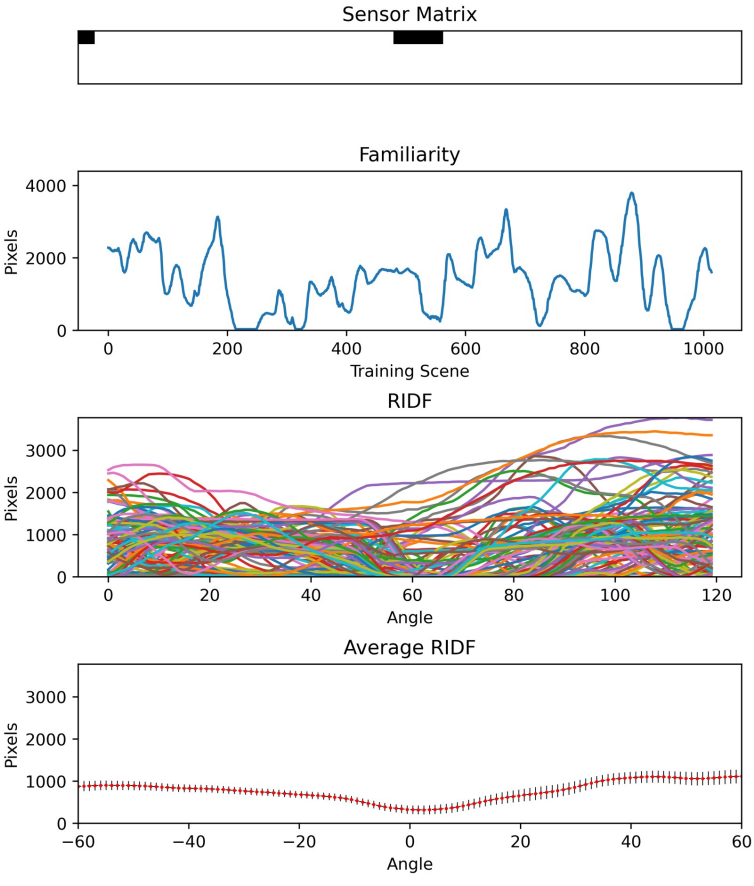


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1500.02; RMSD/dist: 3.750; TD: 992; p90: 88; p50: 44; complete: 0

0%

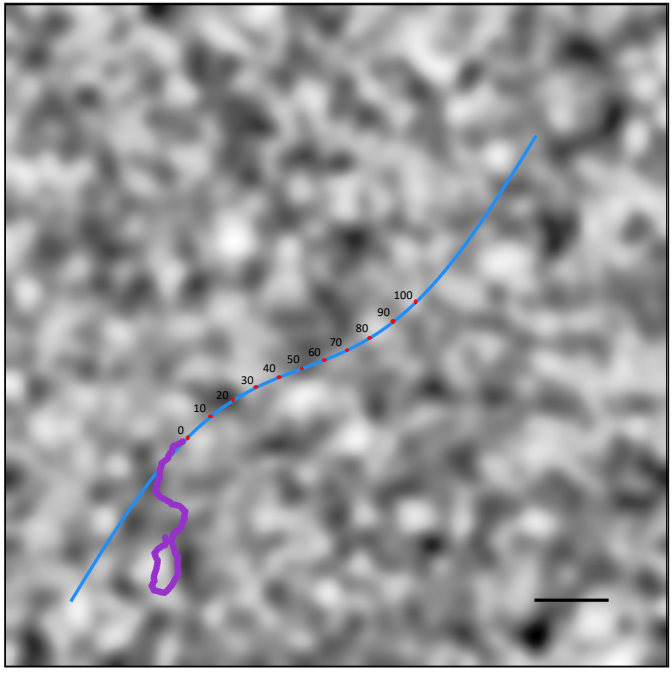


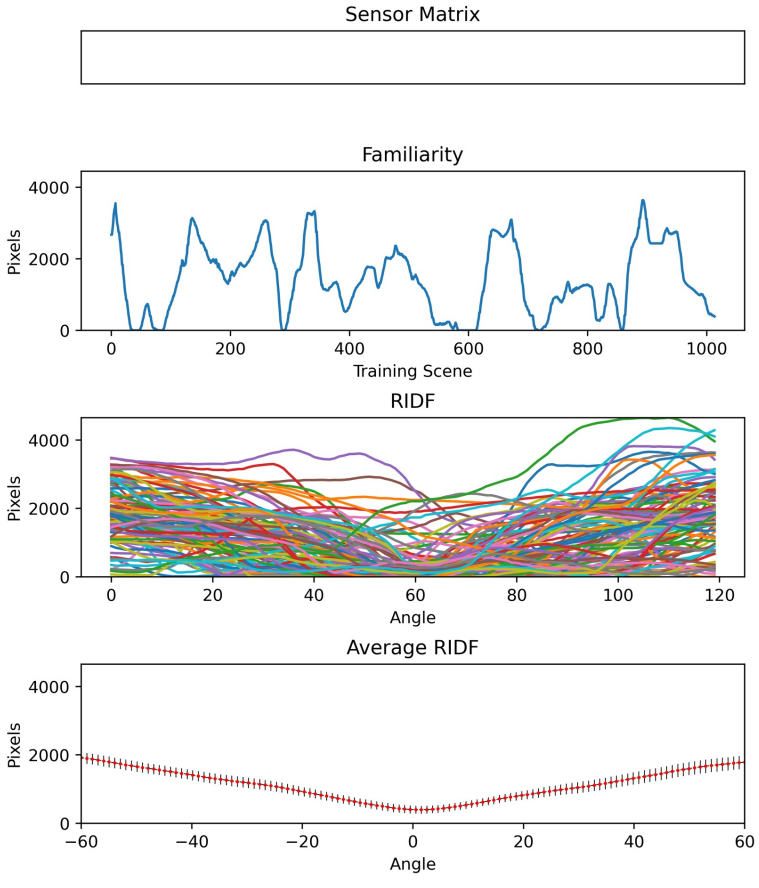


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1490.57; RMSD/dist: 3.726; TD: 889; p90: 110; p50: 60; complete: 0

0%

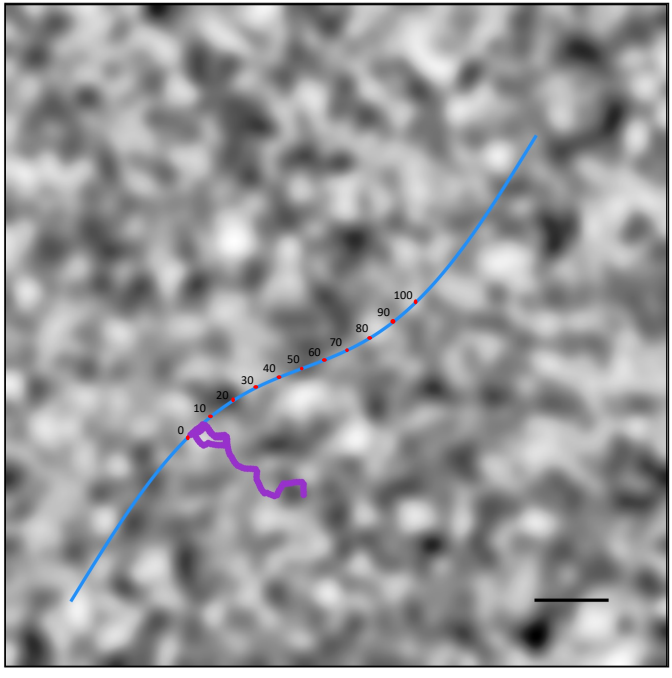


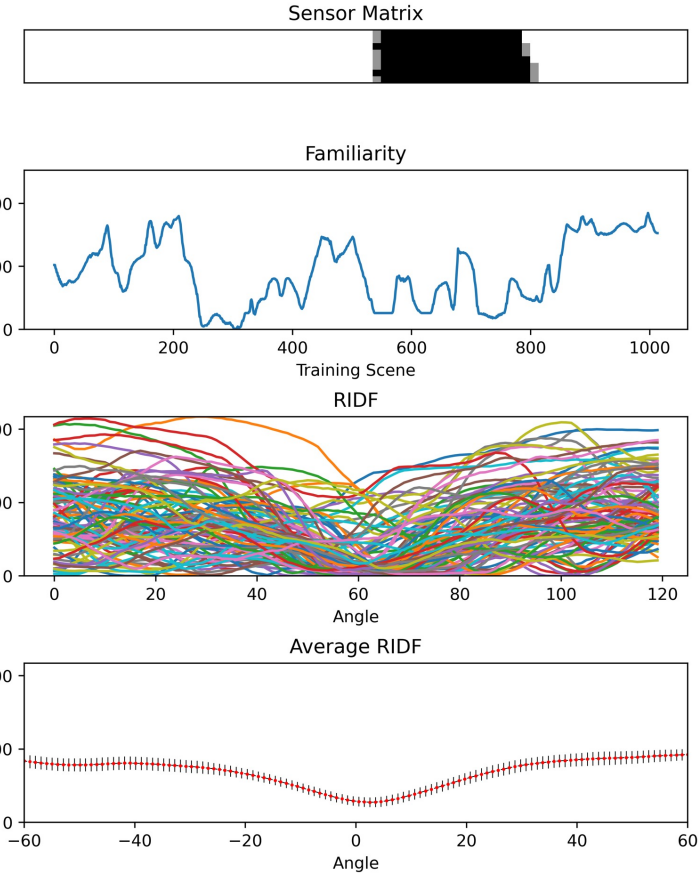


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 6277.35; RMSD/dist: 15.693; TD: 1093; p90: 78; p50: 42; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 7021.18; RMSD/dist: 17.553; TD: 1142; p90: 106; p50: 28; complete: 0

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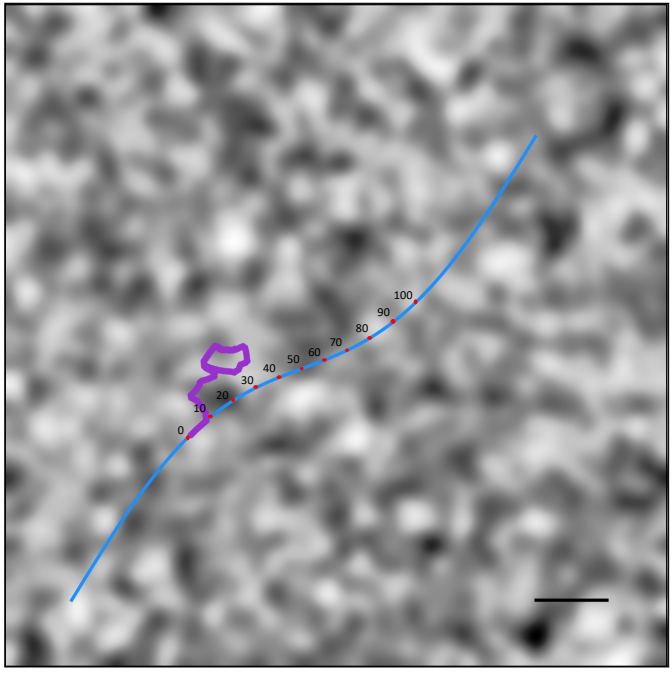
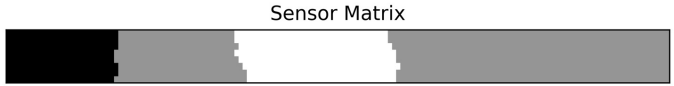
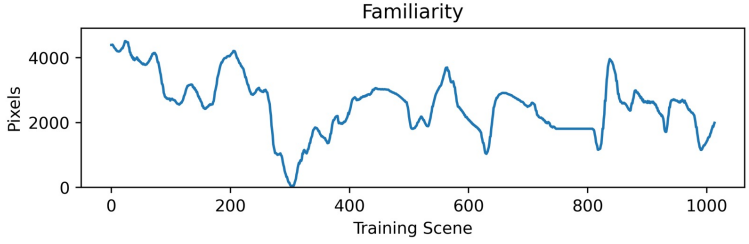
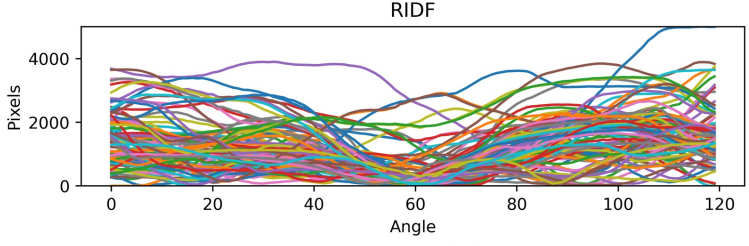
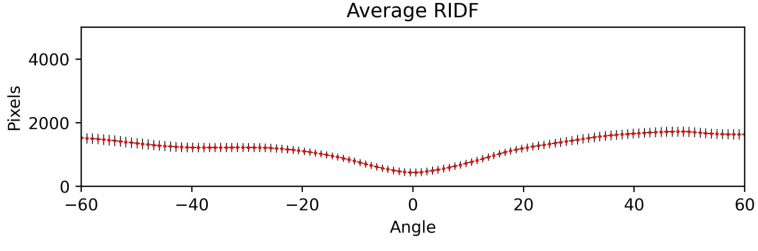




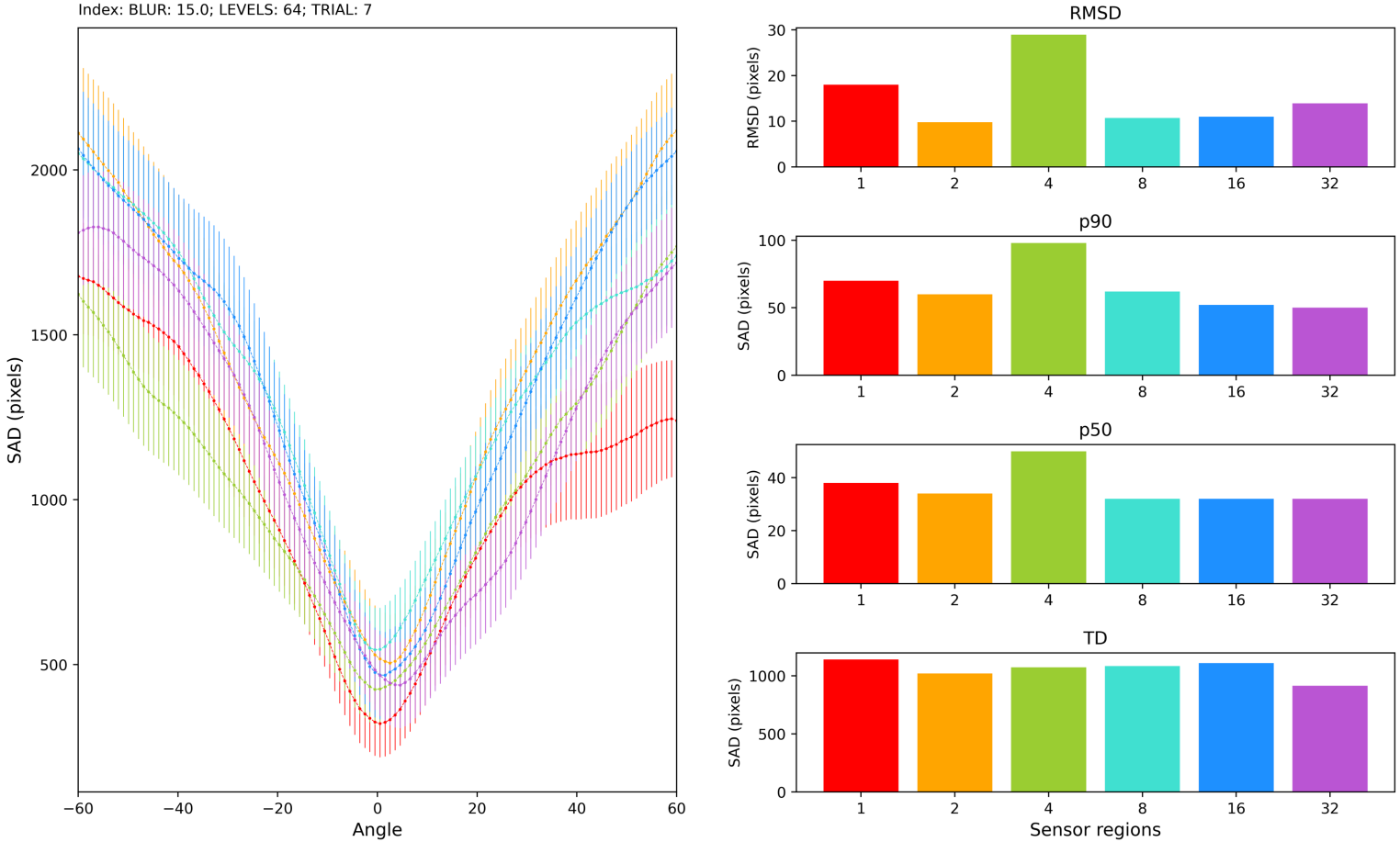




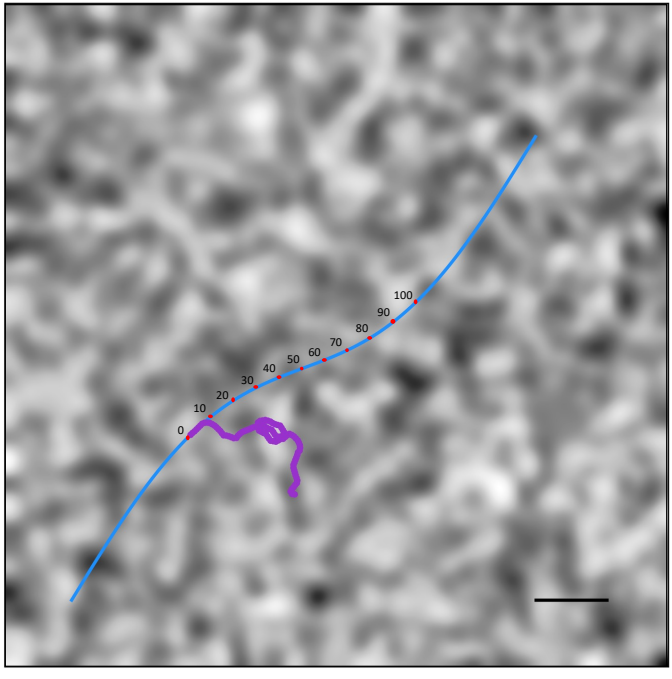


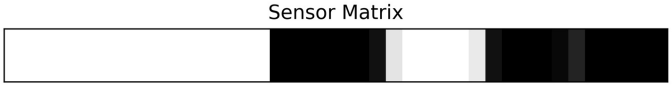
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

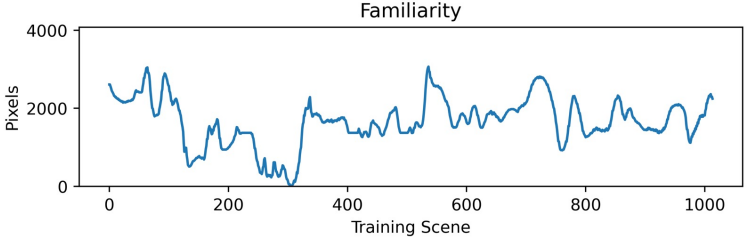
Navigation stats: RMSD error: 5131.64; RMSD/dist: 12.829; TD: 1390; p90: 120; p50: 42; complete: 0

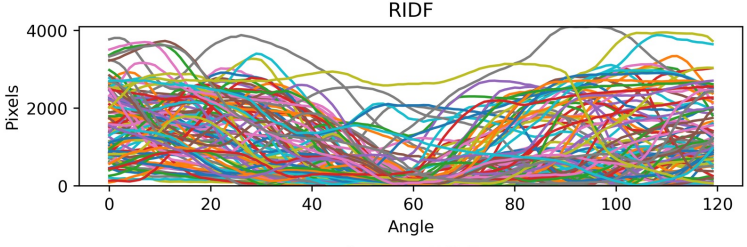

Index: BLUR: 15.0; LEVELS: 64; TRIAL: 7
SAD (pixels)
2000
1500
1000
500
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
30
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
40
20
TD
1000
500
Sensor regions

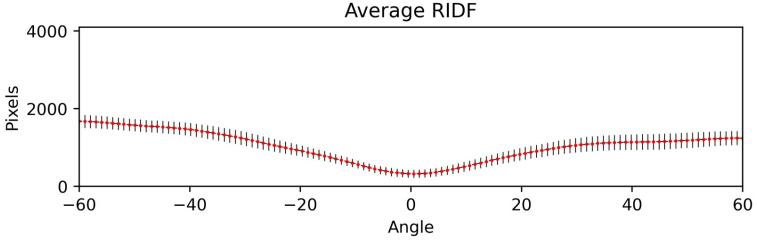
0%







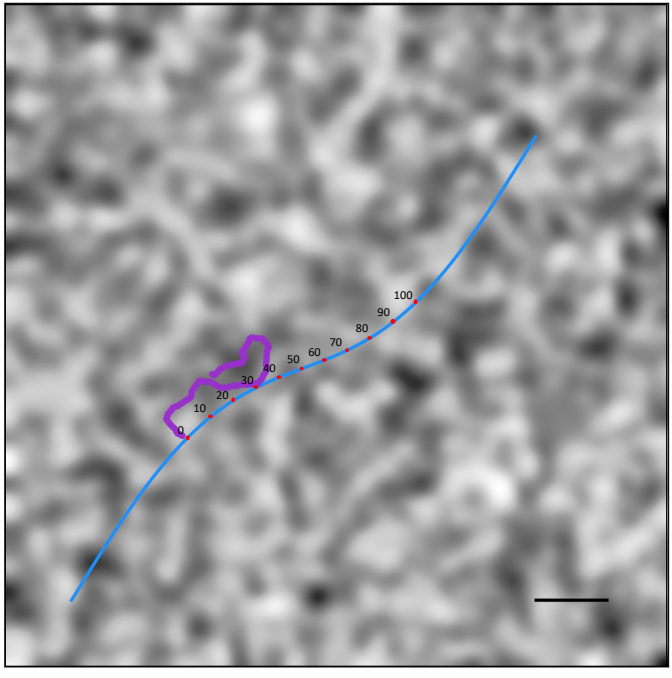


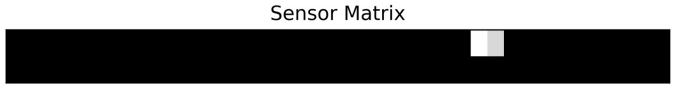


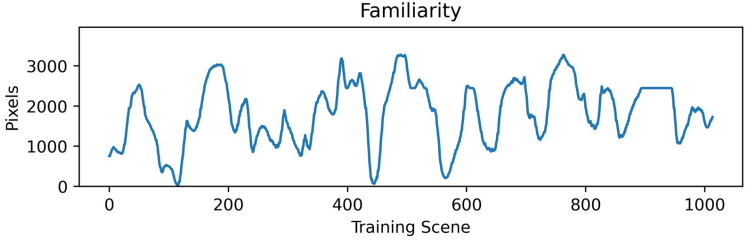
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

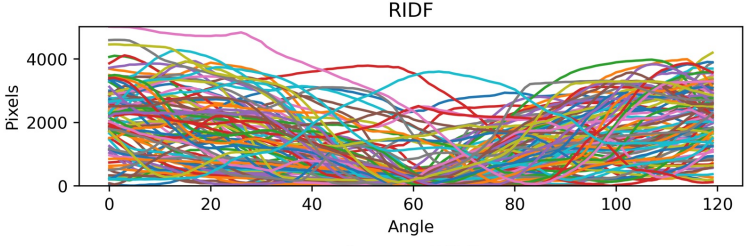
Navigation stats: RMSD error: 7207.66; RMSD/dist: 18.019; TD: 1139; p90: 70; p50: 38; complete: 0

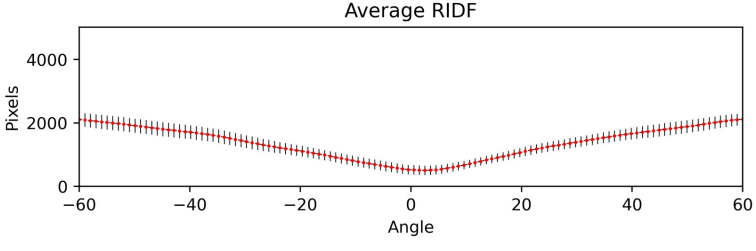
0%







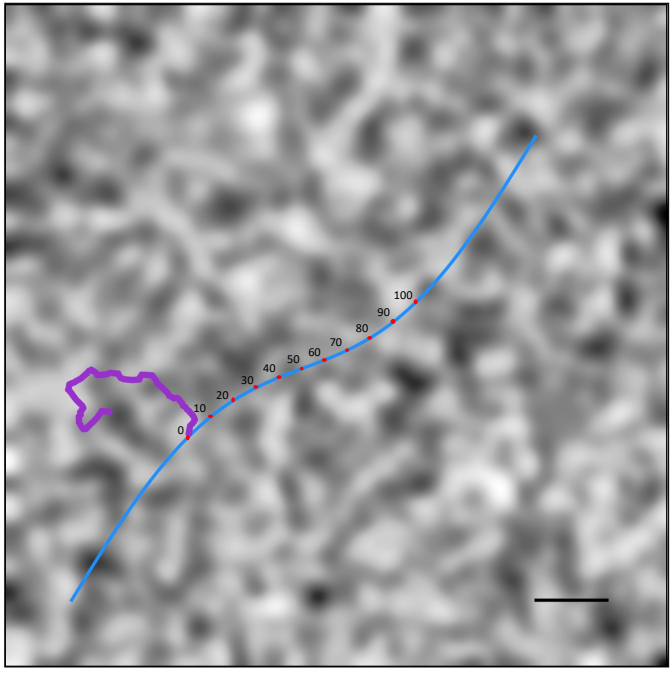


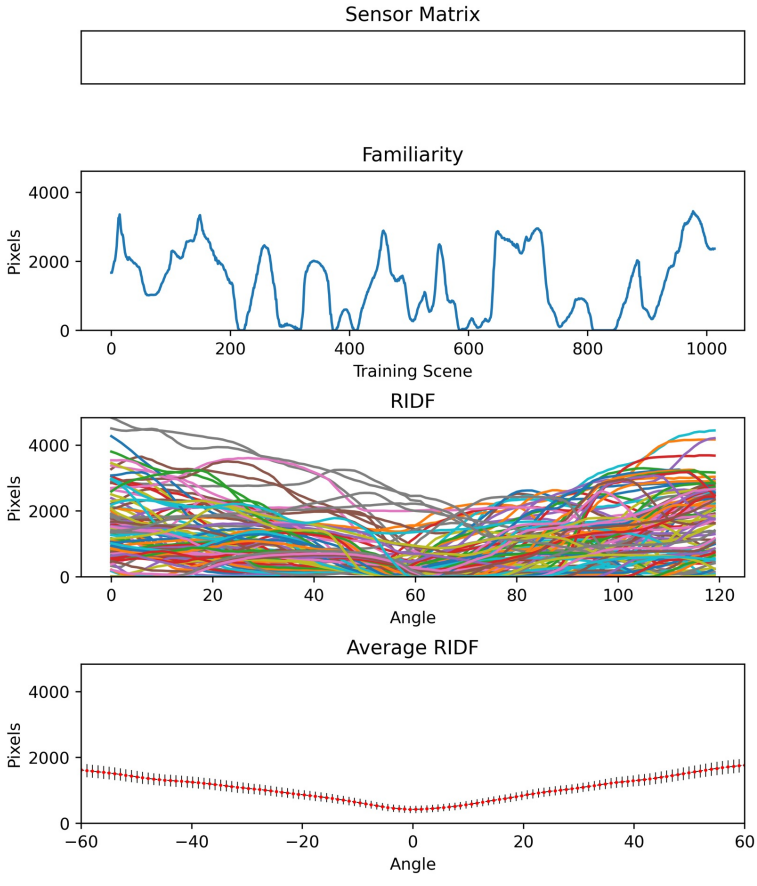


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3906.49; RMSD/dist: 9.766; TD: 1020; p90: 60; p50: 34; complete: 0

0%

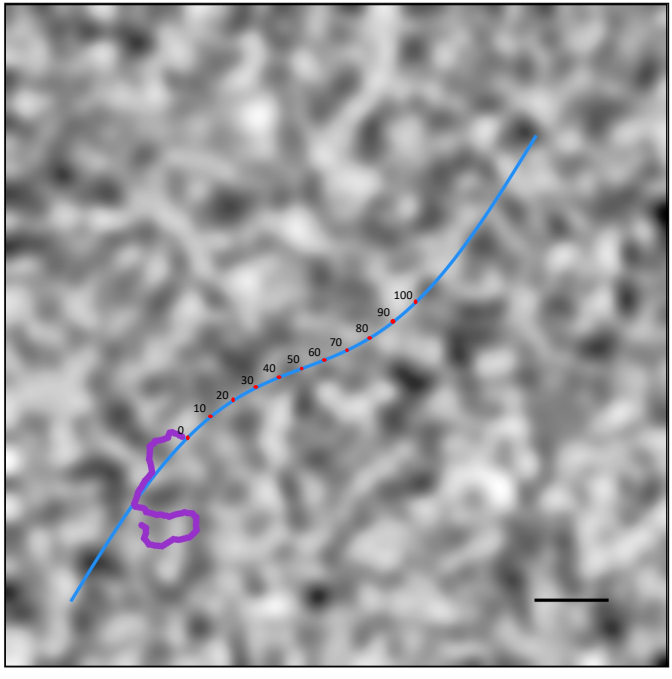


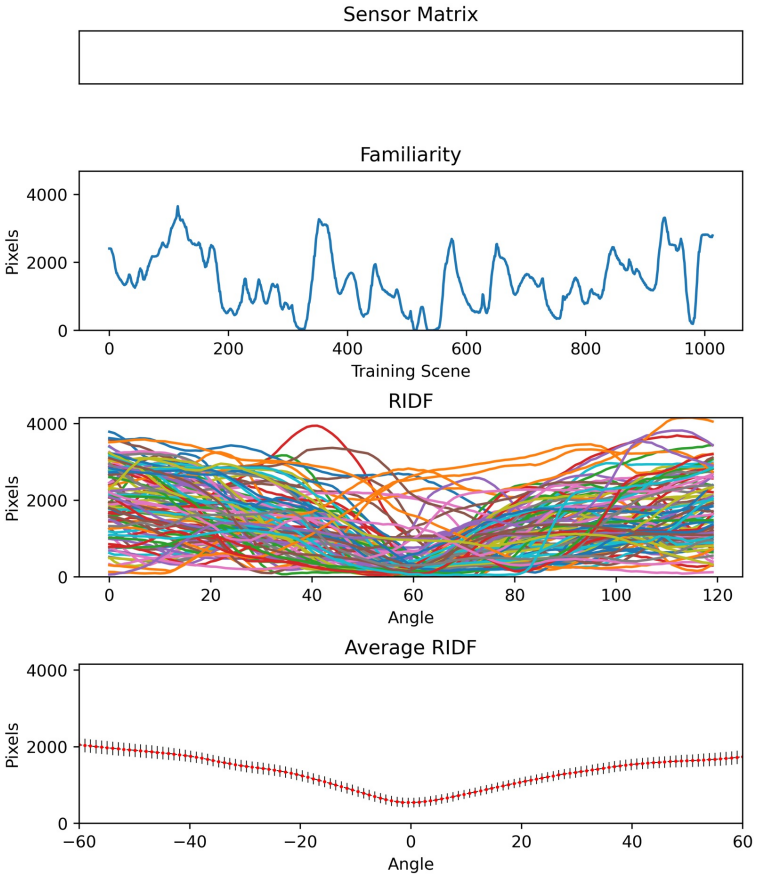


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 11590.04; RMSD/dist: 28.975; TD: 1073; p90: 98; p50: 50; complete: 0

0%

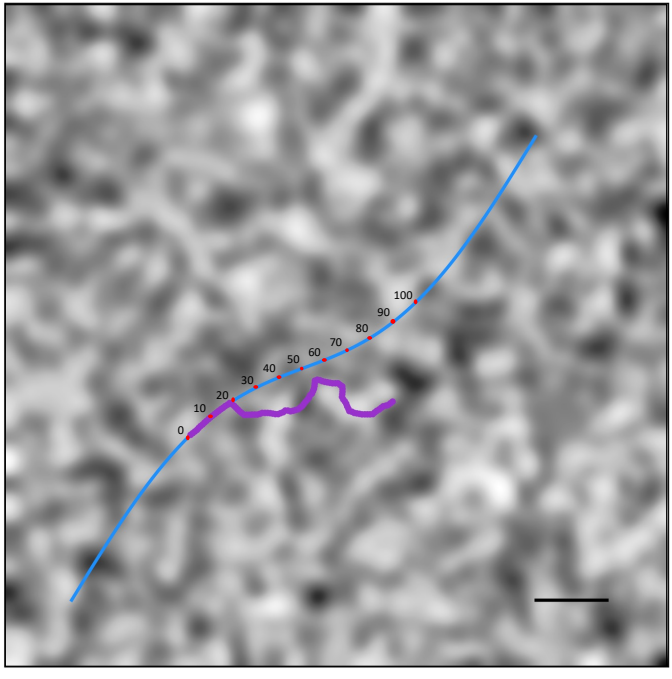


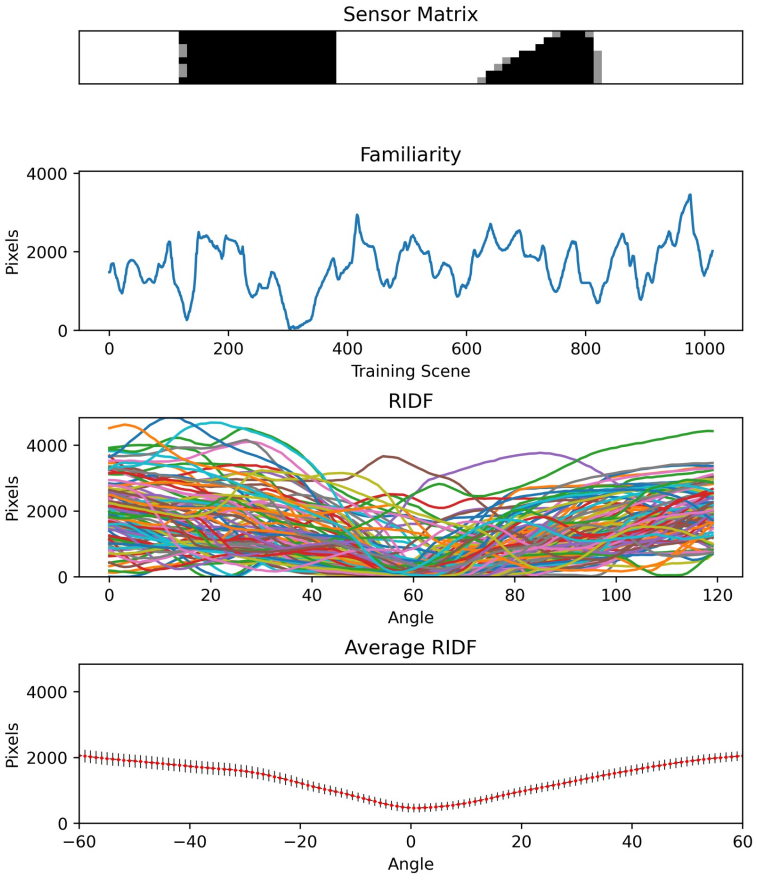


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 4290.08; RMSD/dist: 10.725; TD: 1083; p90: 62; p50: 32; complete: 0

10%





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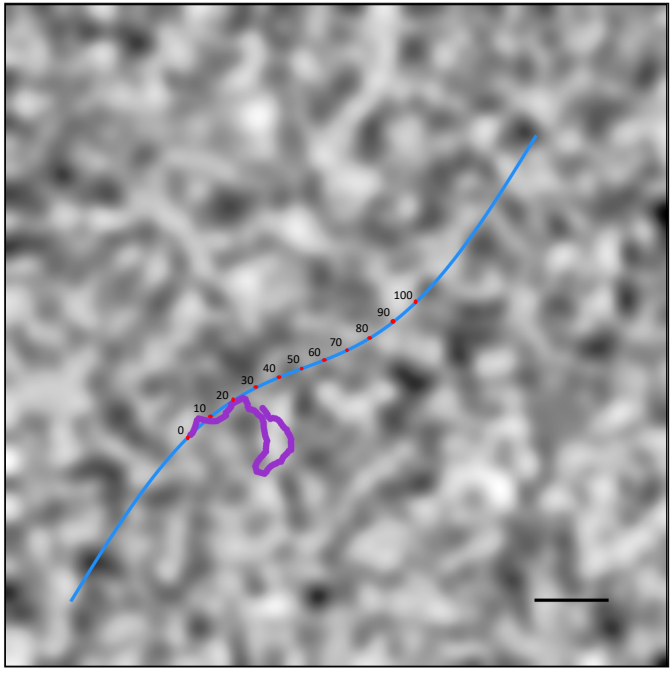
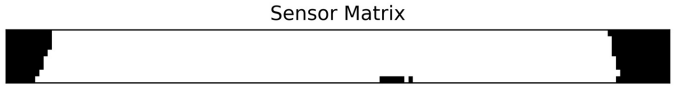
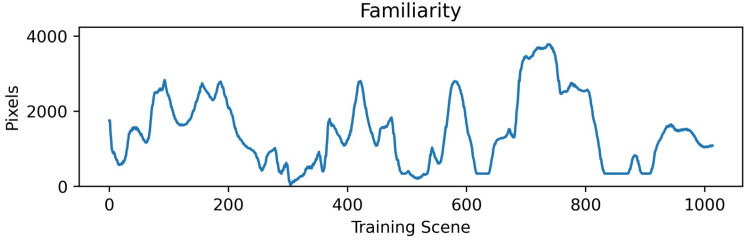
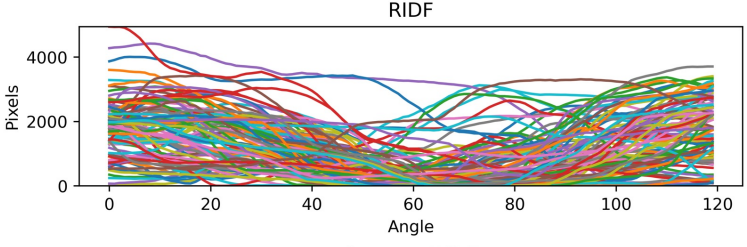
Navigation stats: RMSD error: 4396.33; RMSD/dist: 10.991; TD: 1108; p90: 52; p50: 32; complete: 0

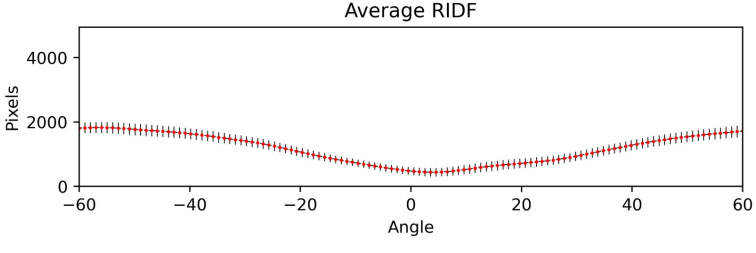
0%





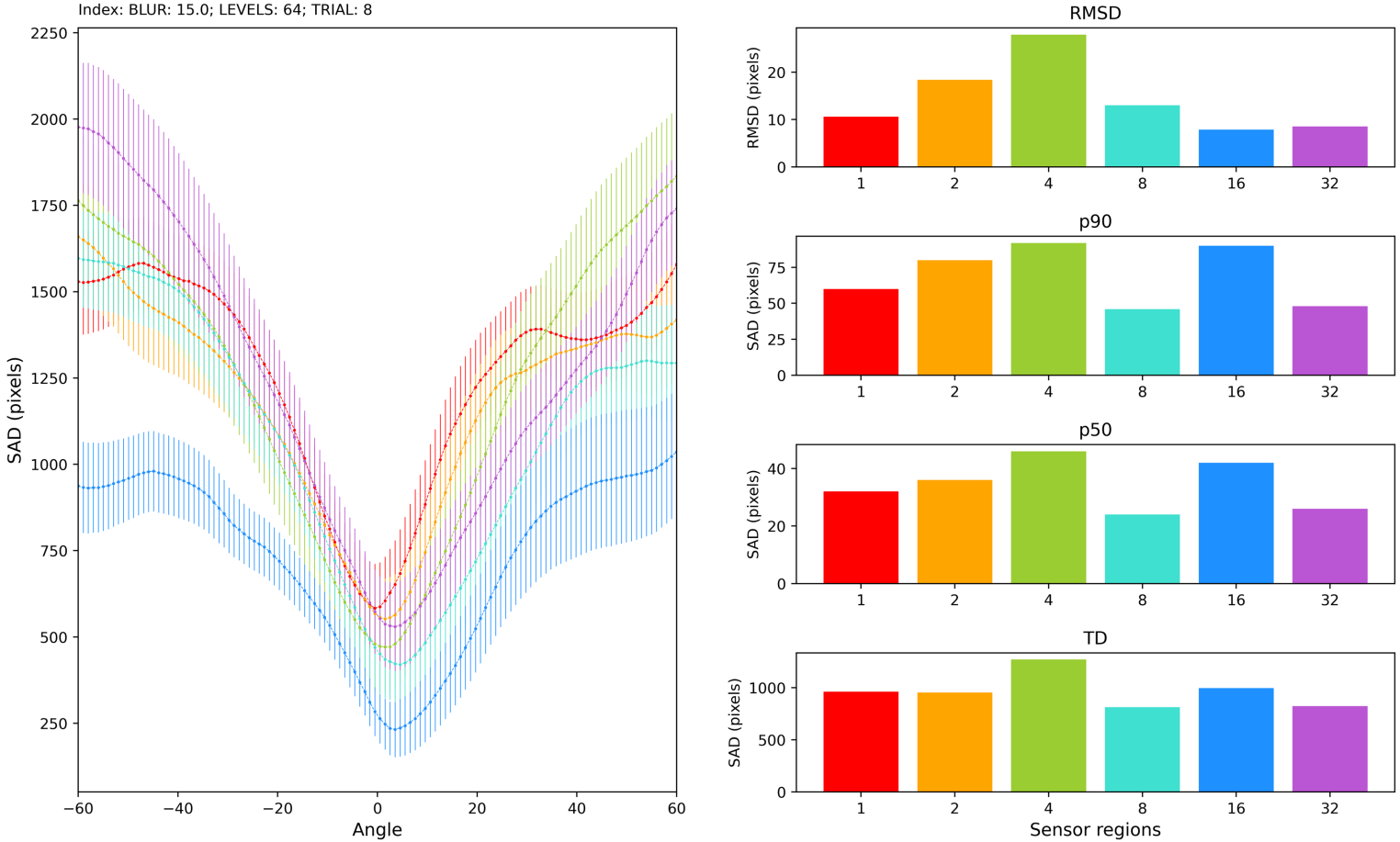




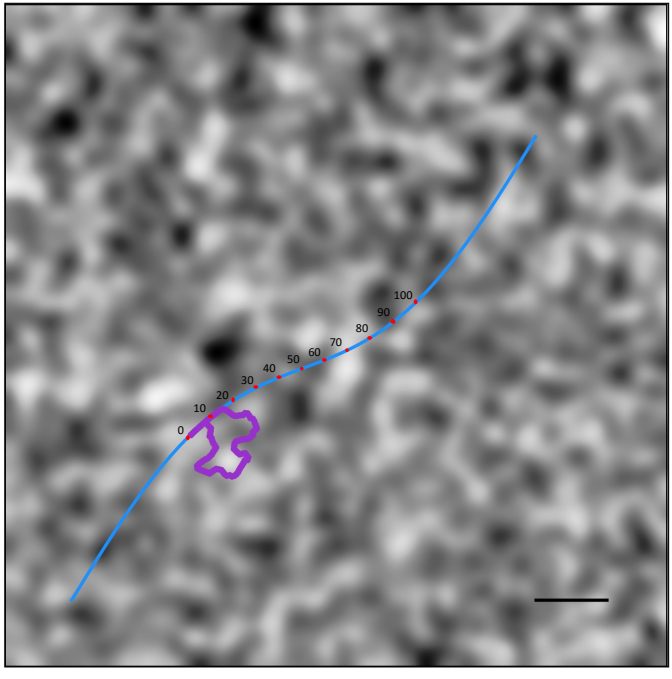


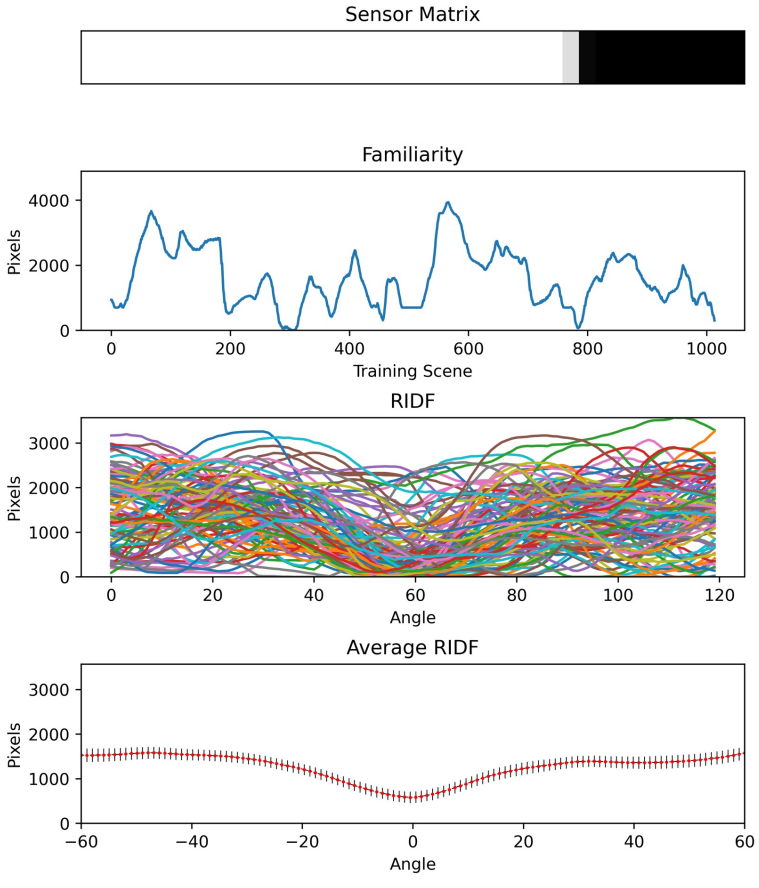
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 5568.55; RMSD/dist: 13.921; TD: 914; p90: 50; p50: 32; complete: 0


Index: BLUR: 15.0; LEVELS: 64; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

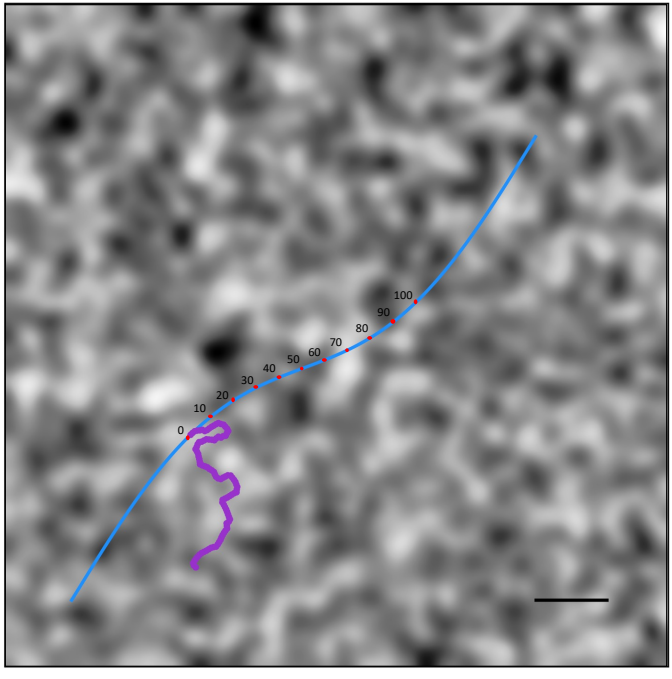


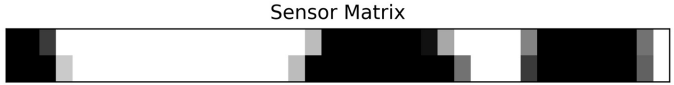


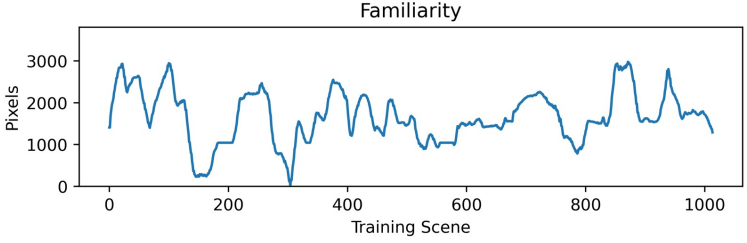
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

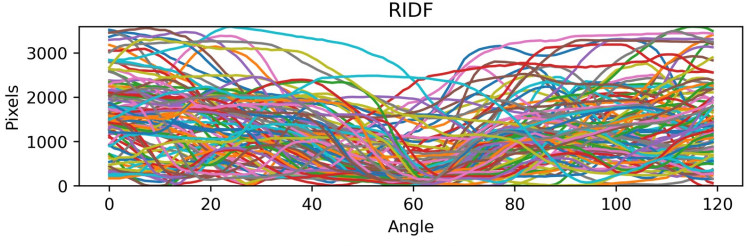
Navigation stats: RMSD error: 4240.04; RMSD/dist: 10.600; TD: 960; p90: 60; p50: 32; complete: 0

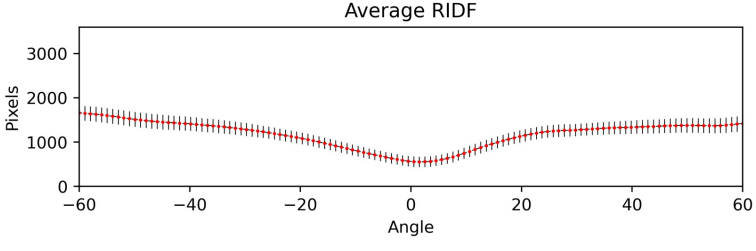
0%







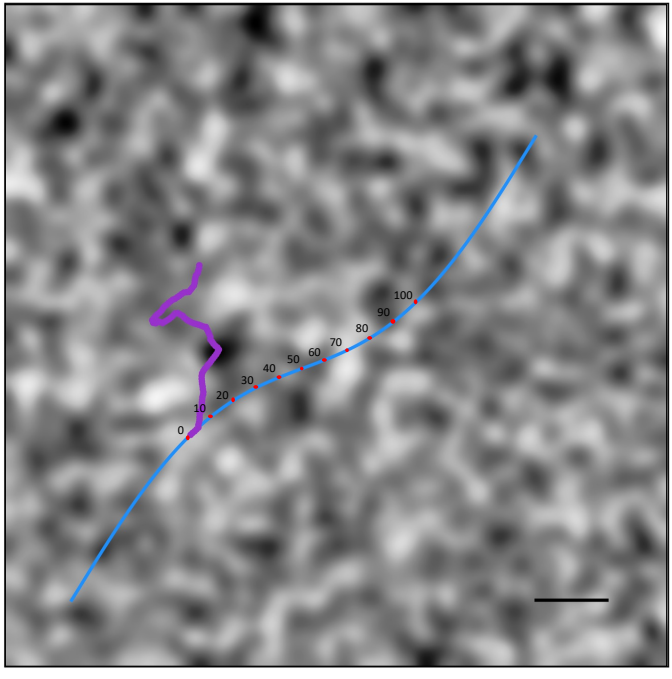


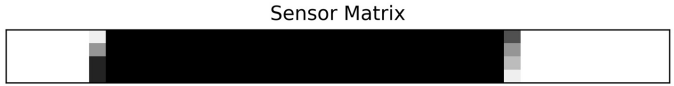


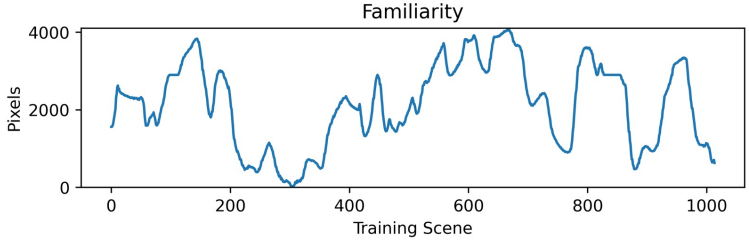
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

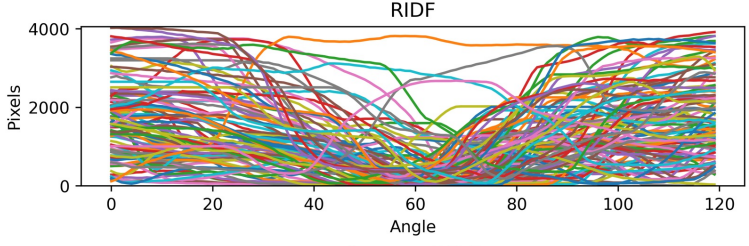
Navigation stats: RMSD error: 7358.19; RMSD/dist: 18.395; TD: 953; p90: 80; p50: 36; complete: 0

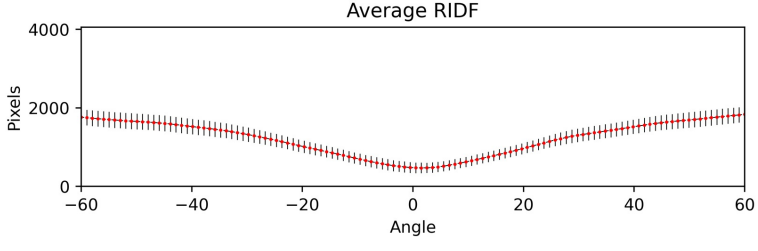
0%







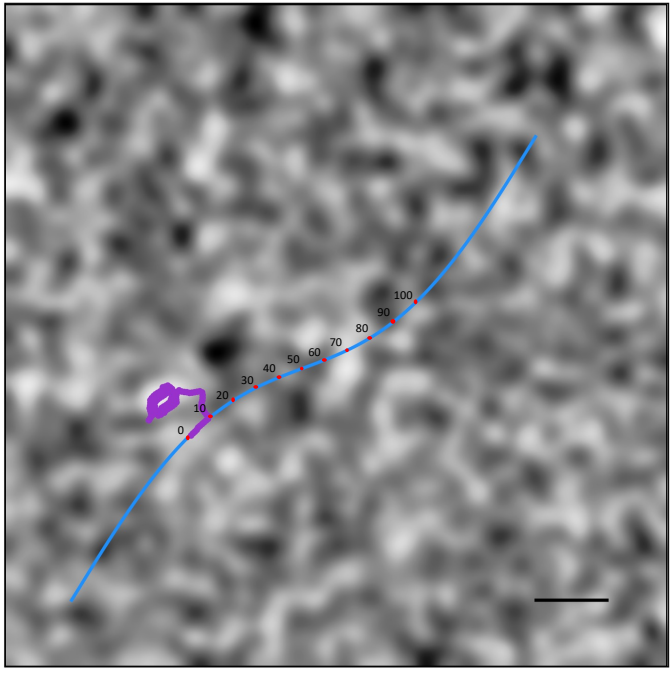


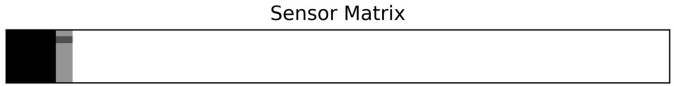


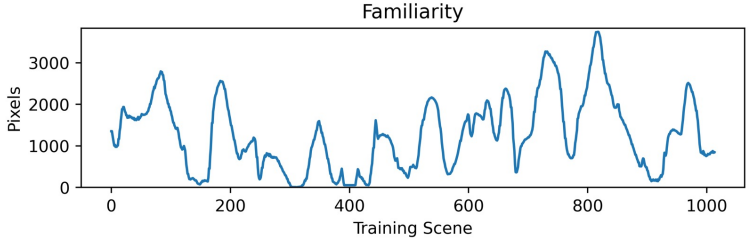
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

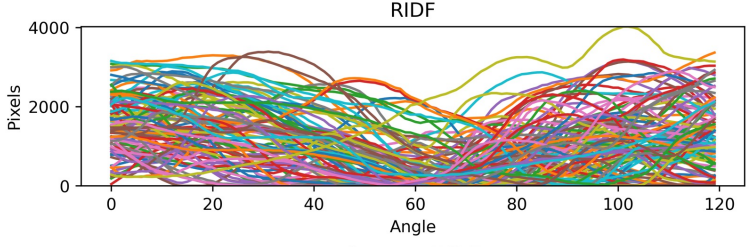
Navigation stats: RMSD error: 11173.20; RMSD/dist: 27.933; TD: 1269; p90: 92; p50: 46; complete: 0

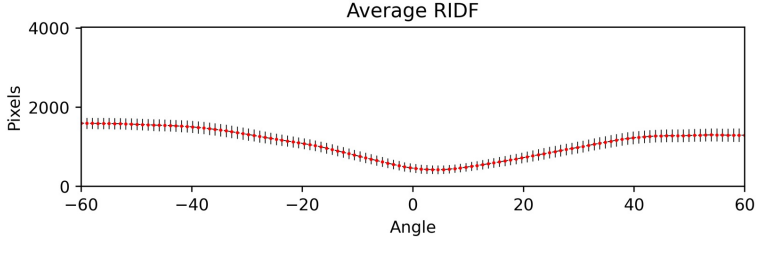
10%







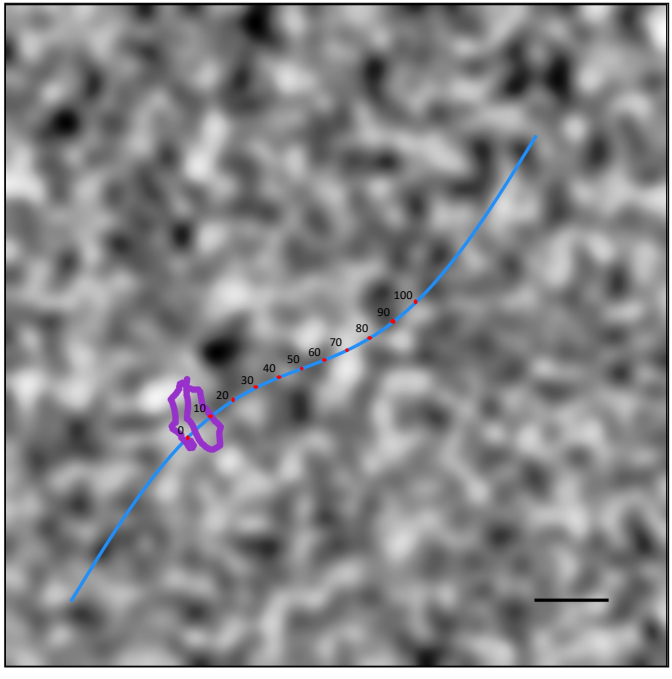


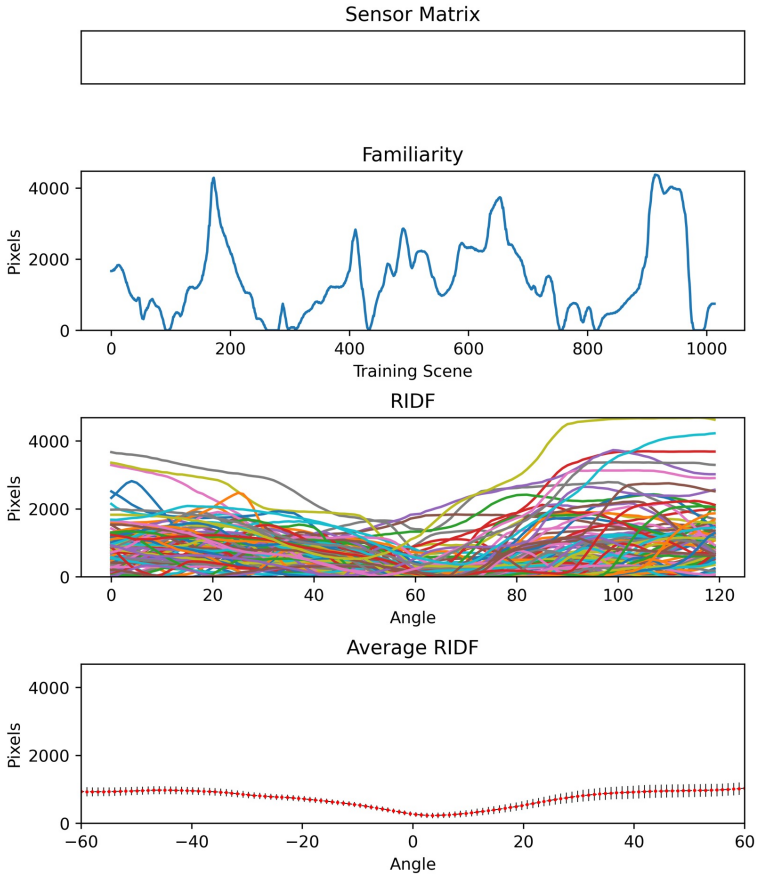


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5200.81; RMSD/dist: 13.002; TD: 813; p90: 46; p50: 24; complete: 0

0%

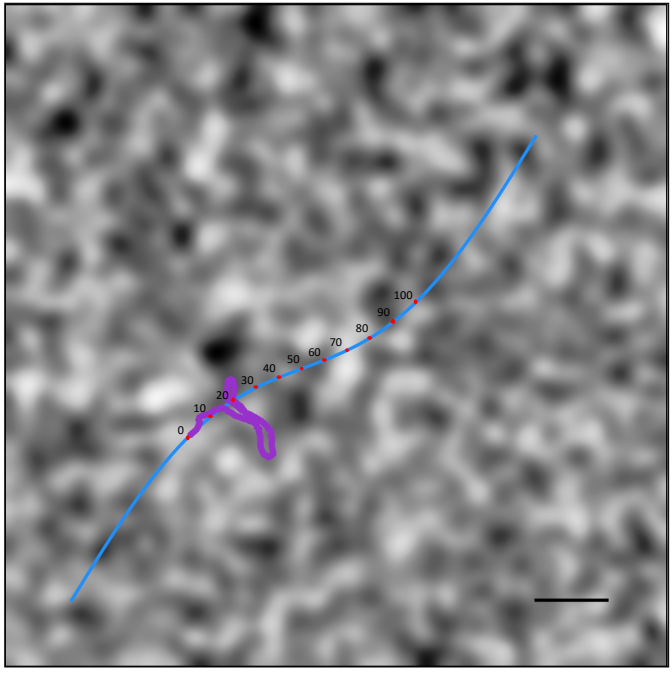


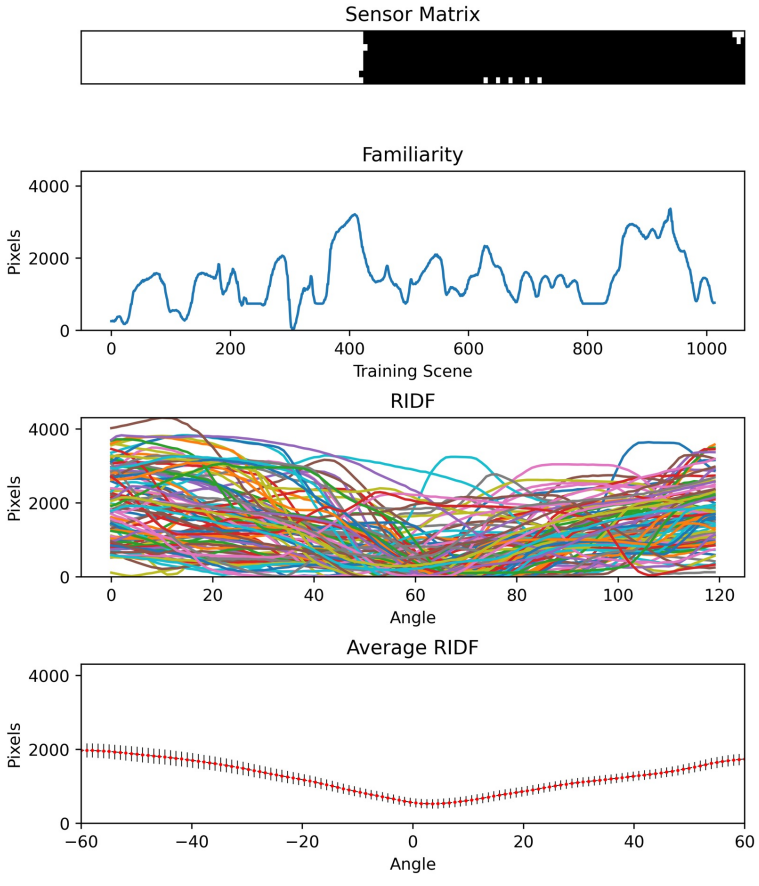


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3136.93; RMSD/dist: 7.842; TD: 996; p90: 90; p50: 42; complete: 0

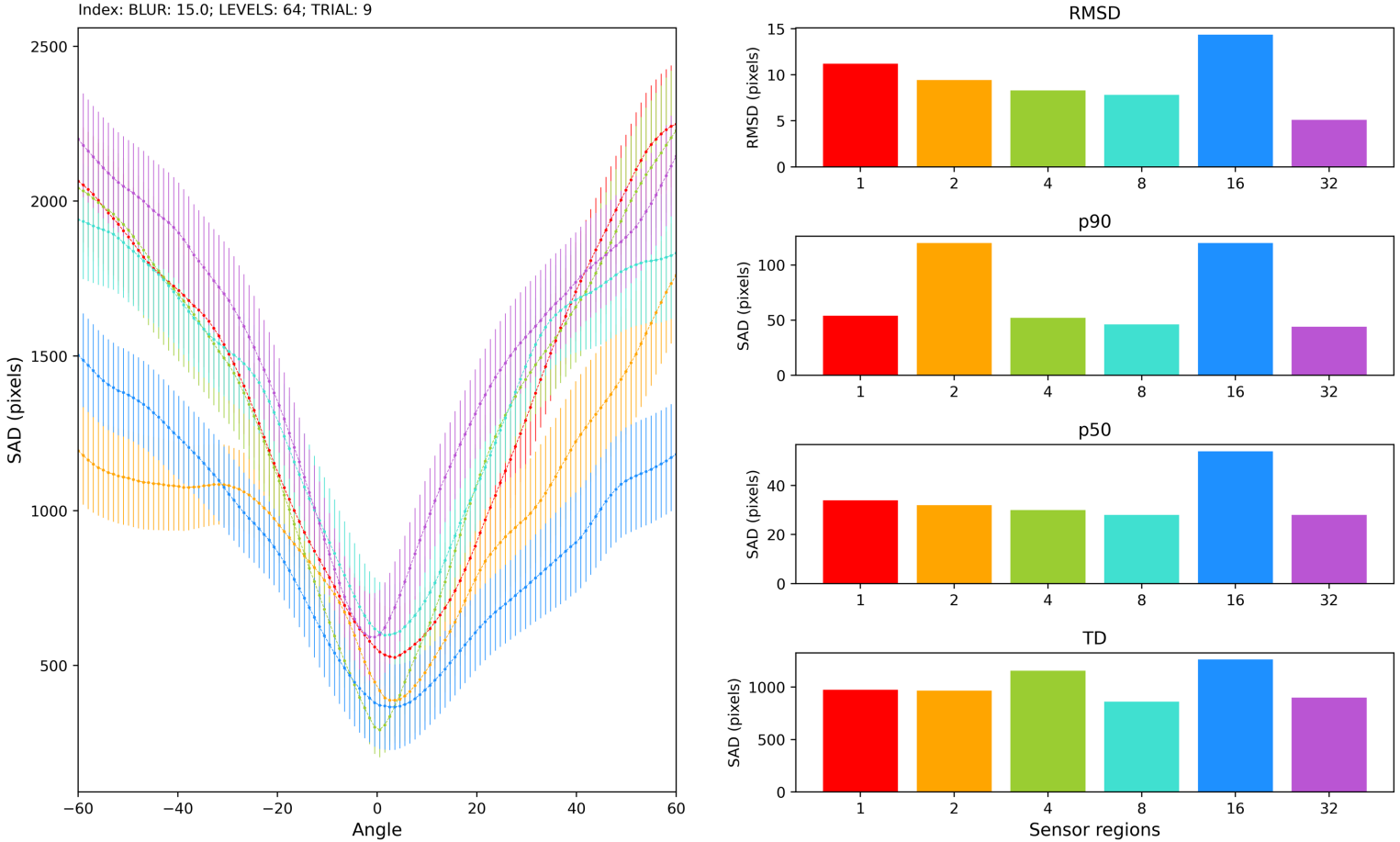
10%



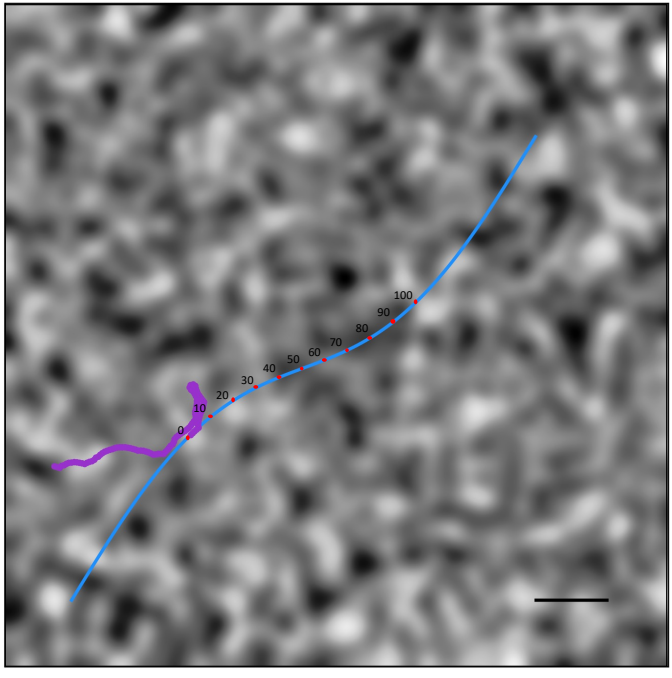


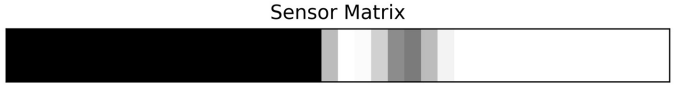
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

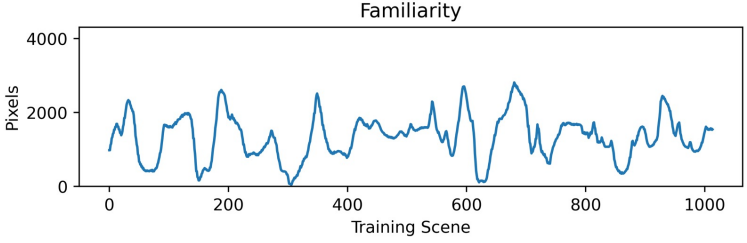
Navigation stats: RMSD error: 3410.29; RMSD/dist: 8.526; TD: 823; p90: 48; p50: 26; complete: 0

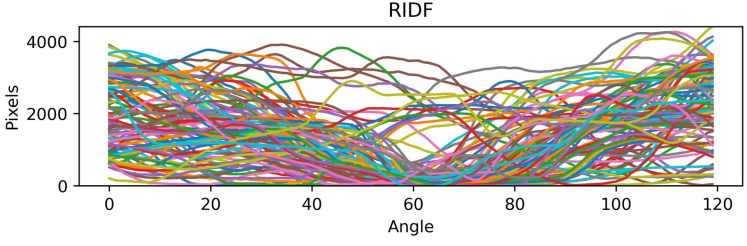

Index: BLUR: 15.0; LEVELS: 64; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

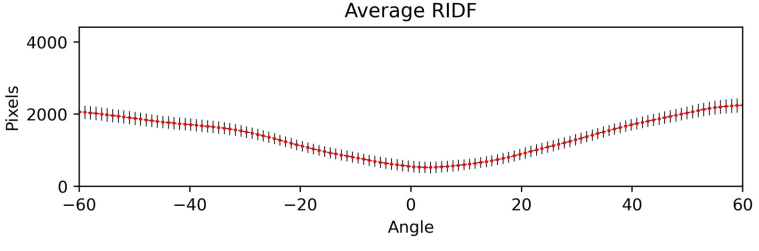
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 4482.81; RMSD/dist: 11.207; TD: 974; p90: 54; p50: 34; complete: 0

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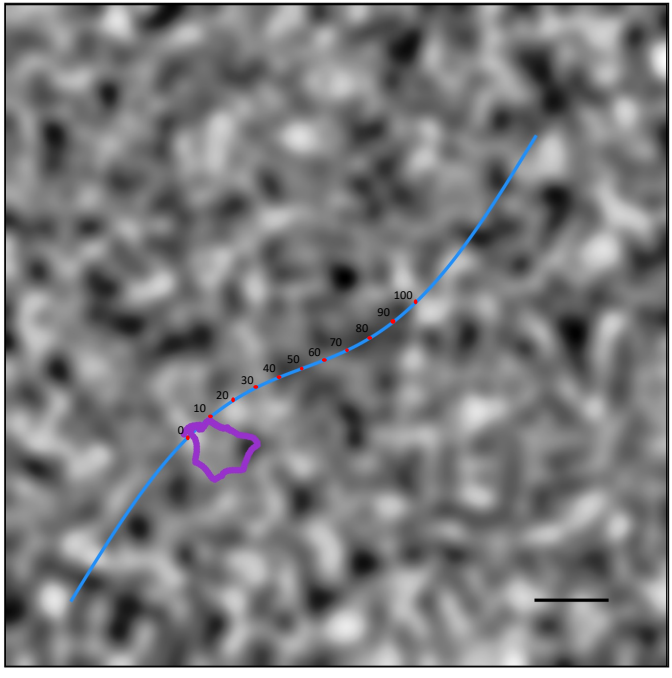
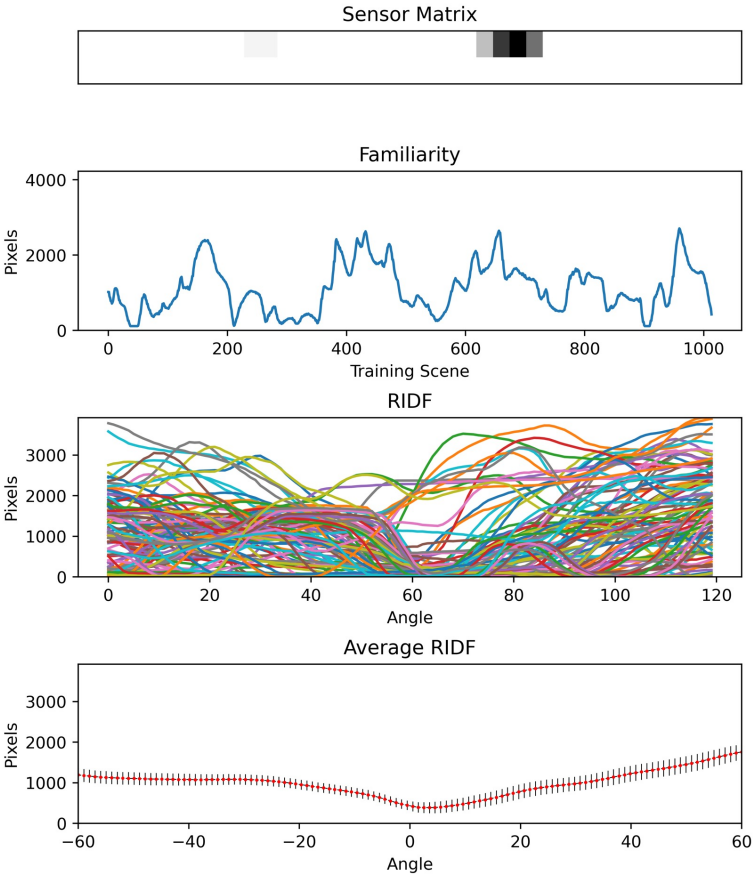
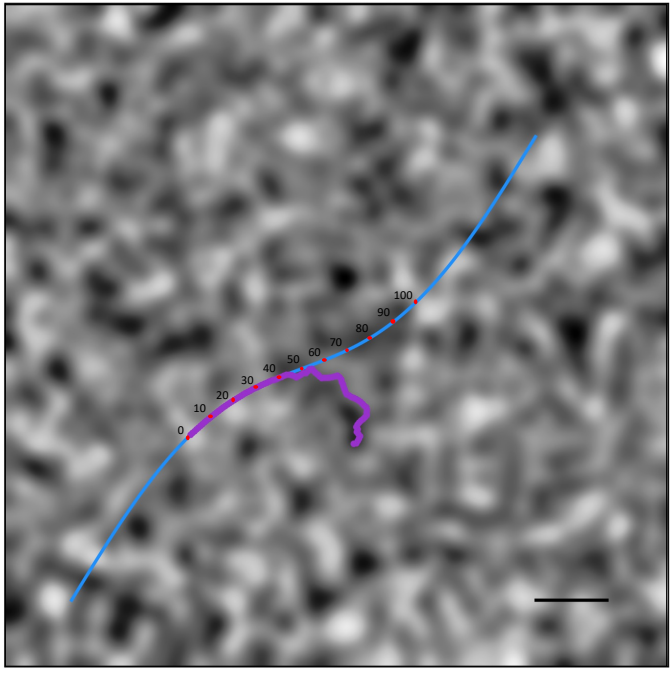


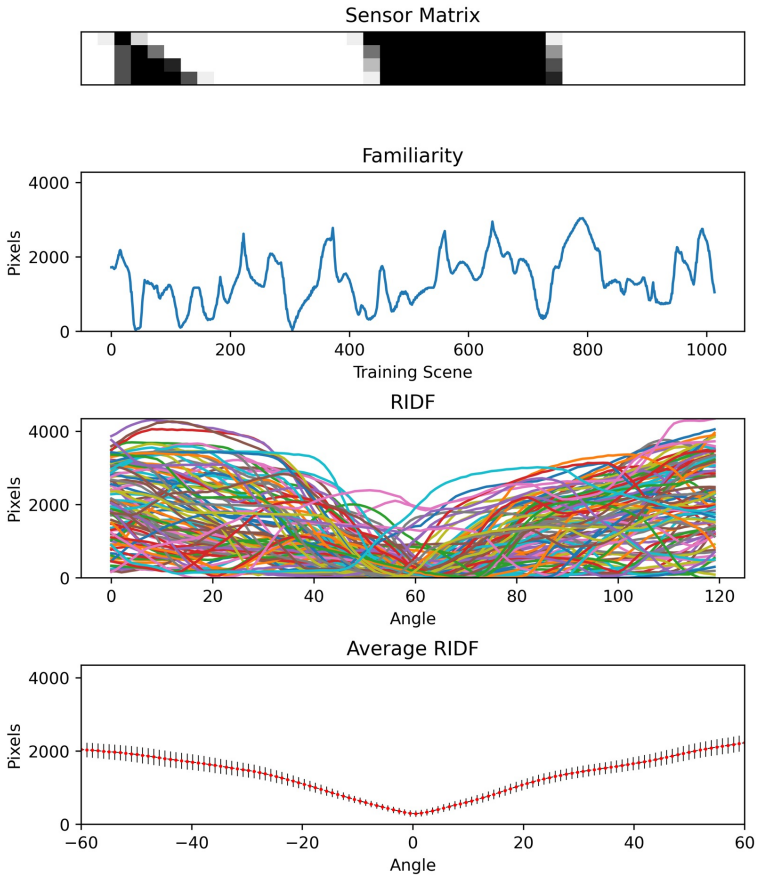


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3774.06; RMSD/dist: 9.435; TD: 966; p90: 120; p50: 32; complete: 0

40%

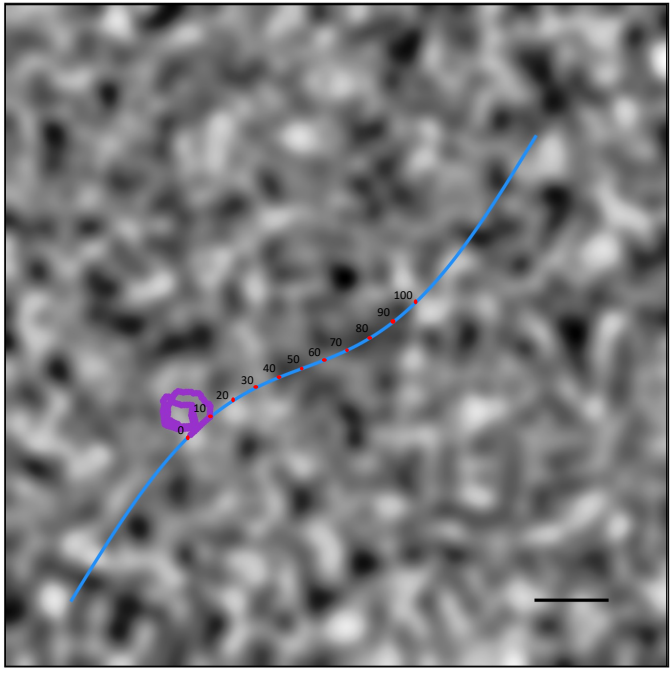


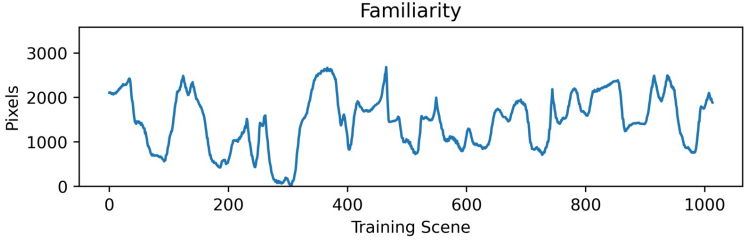


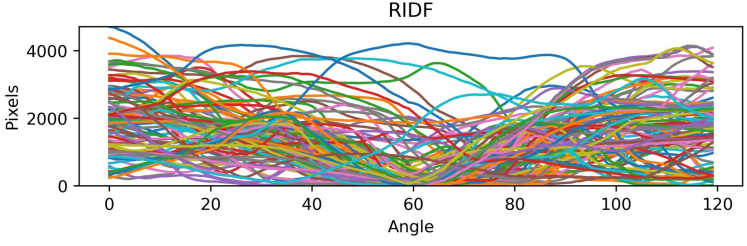
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

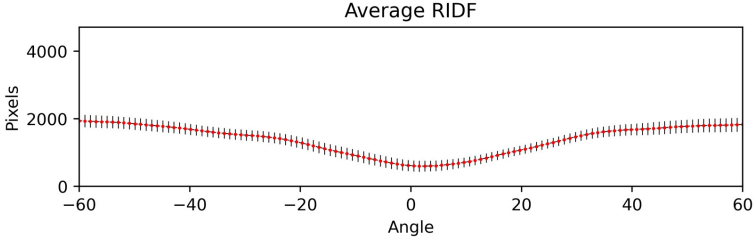
Navigation stats: RMSD error: 3323.51; RMSD/dist: 8.309; TD: 1157; p90: 52; p50: 30; complete: 0

10%





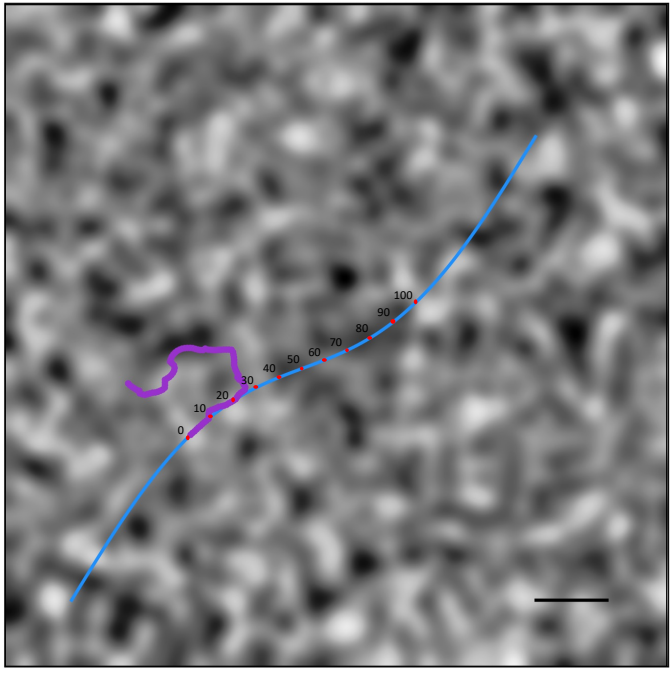


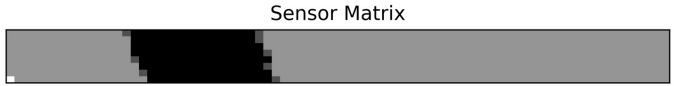


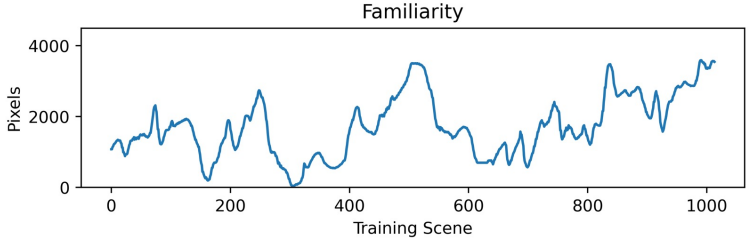
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

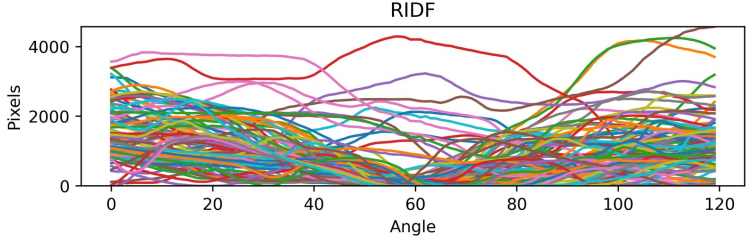
Navigation stats: RMSD error: 3127.96; RMSD/dist: 7.820; TD: 861; p90: 46; p50: 28; complete: 0

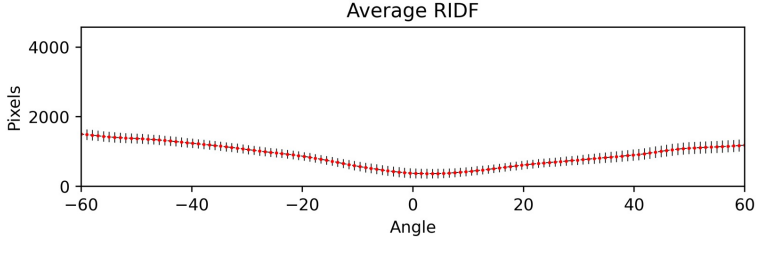
10%







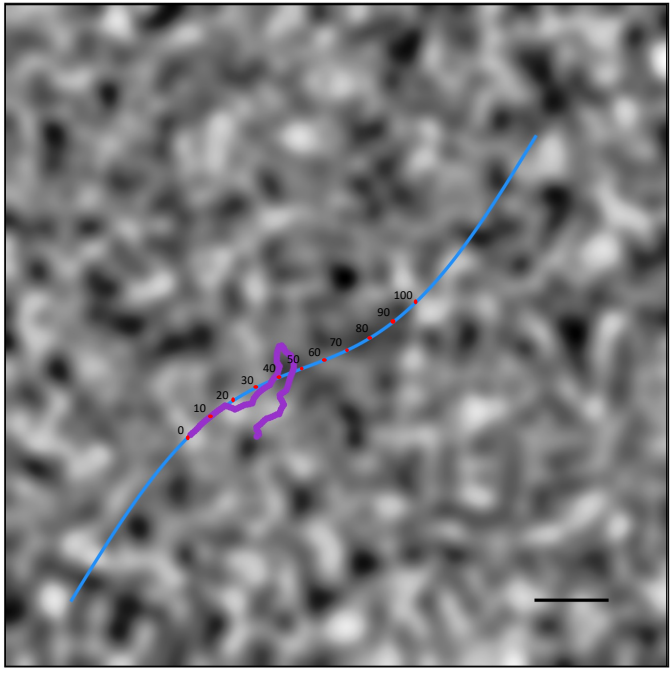


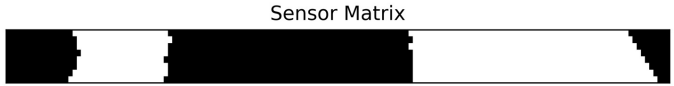


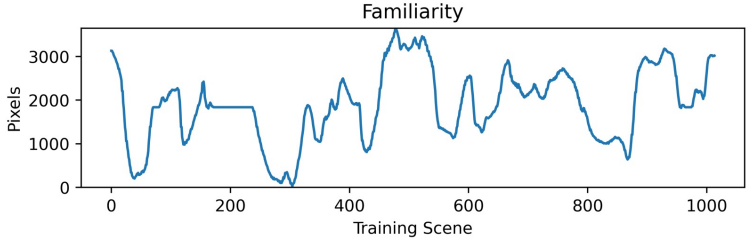
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

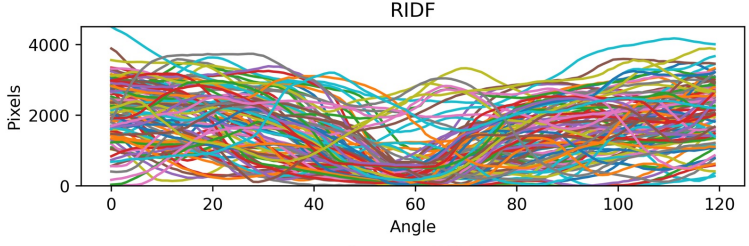
Navigation stats: RMSD error: 5744.59; RMSD/dist: 14.361; TD: 1263; p90: 120; p50: 54; complete: 0

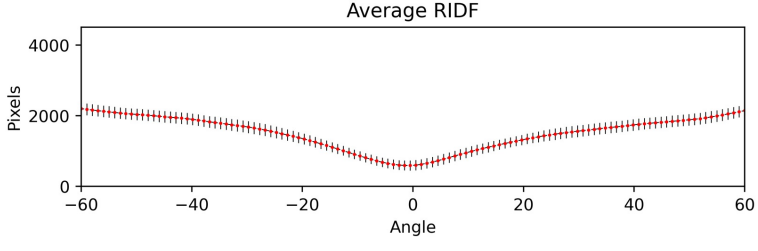
10%





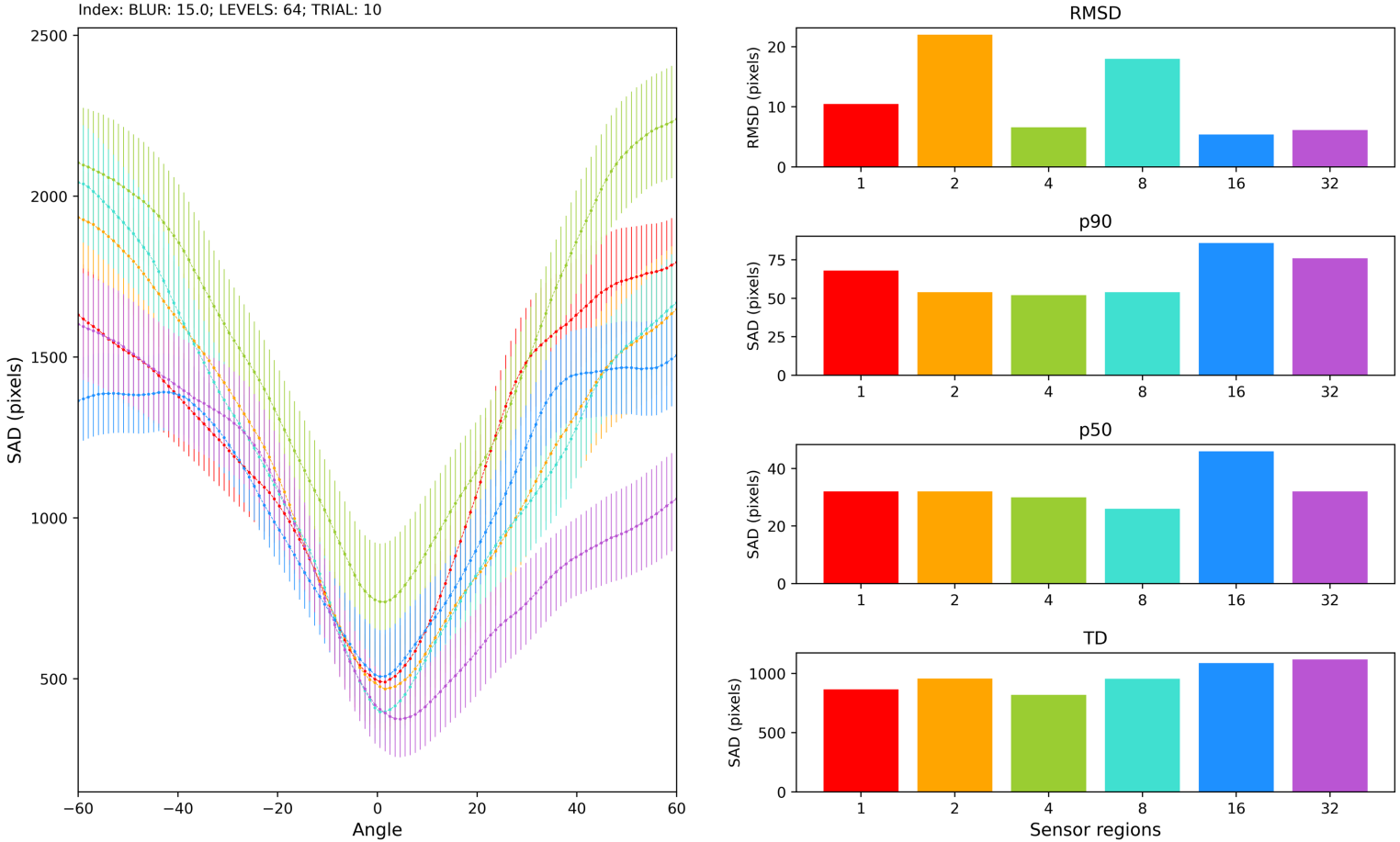




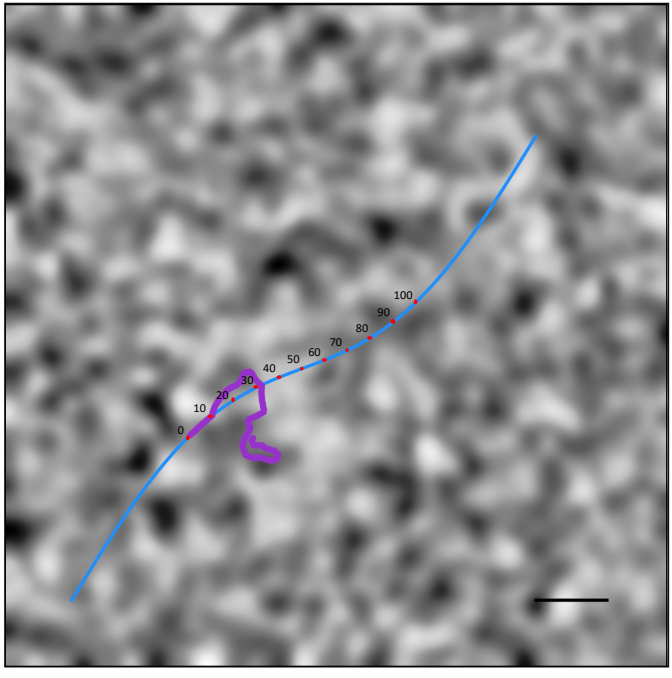


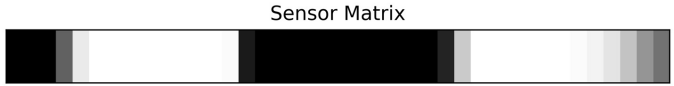
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

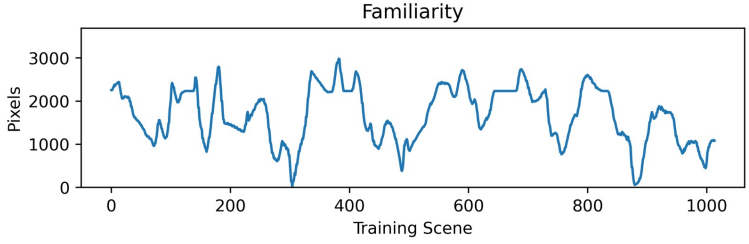
Navigation stats: RMSD error: 2043.30; RMSD/dist: 5.108; TD: 900; p90: 44; p50: 28; complete: 0

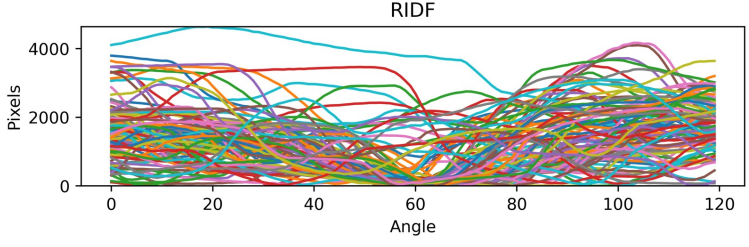

Index: BLUR: 15.0; LEVELS: 64; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

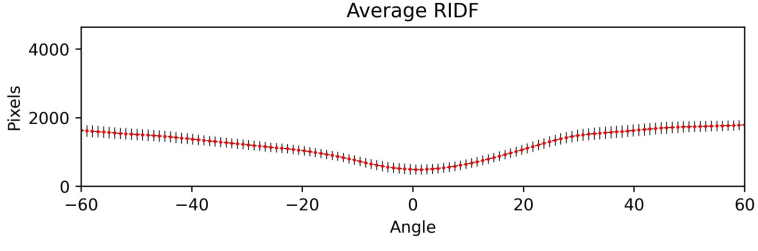
10%







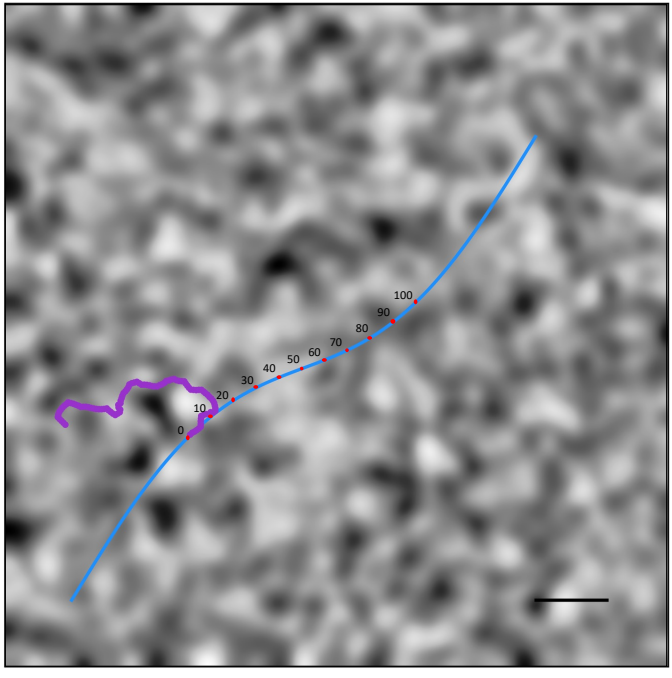


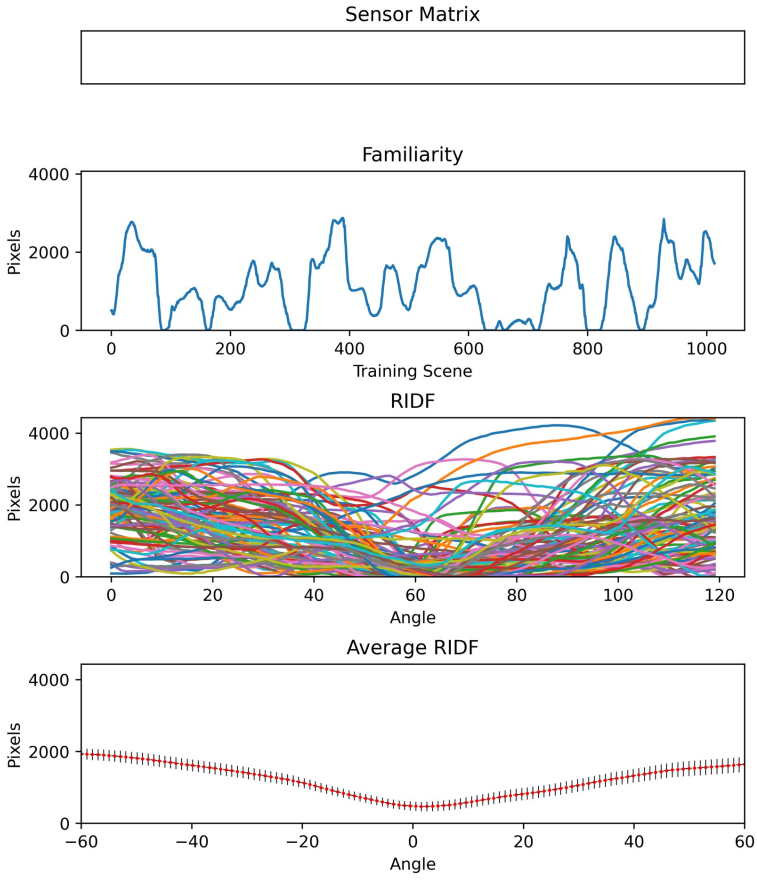


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4194.80; RMSD/dist: 10.487; TD: 866; p90: 68; p50: 32; complete: 0

0%

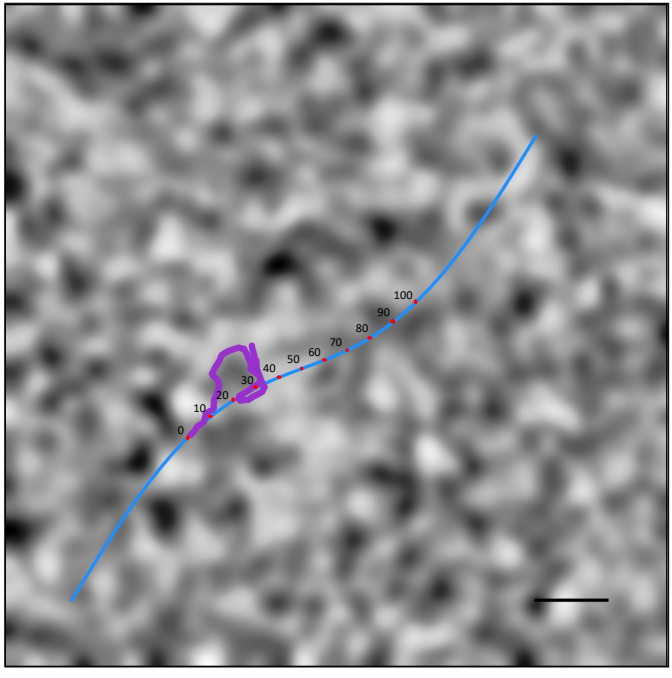


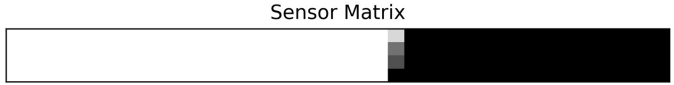


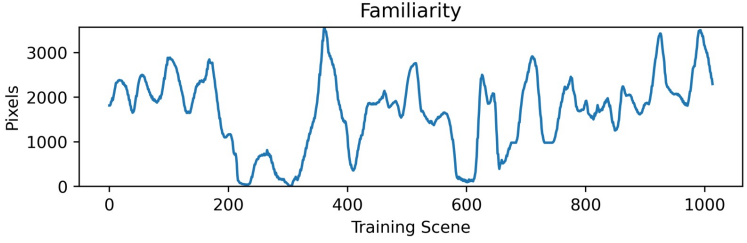
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

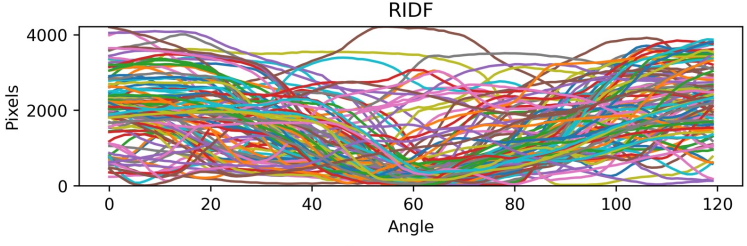
Navigation stats: RMSD error: 8810.54; RMSD/dist: 22.026; TD: 957; p90: 54; p50: 32; complete: 0

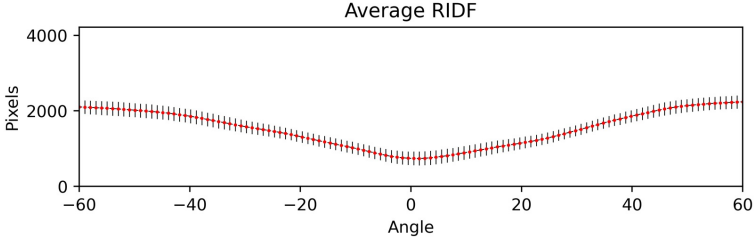
10%







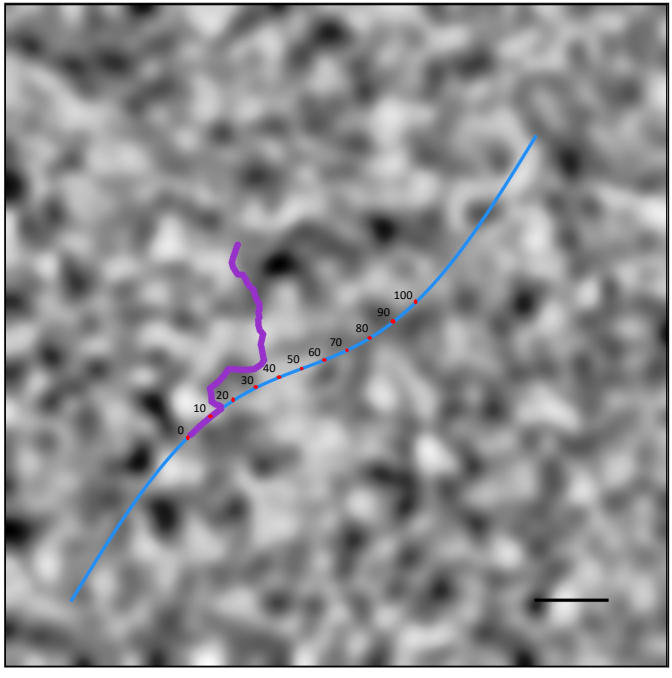


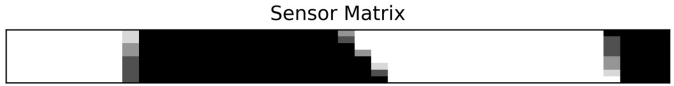


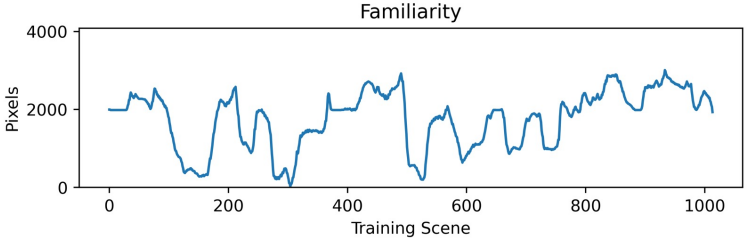
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

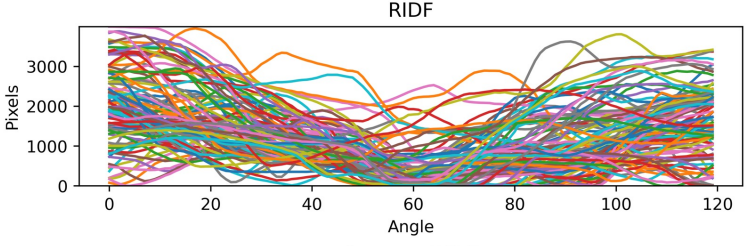
Navigation stats: RMSD error: 2630.82; RMSD/dist: 6.577; TD: 820; p90: 52; p50: 30; complete: 0

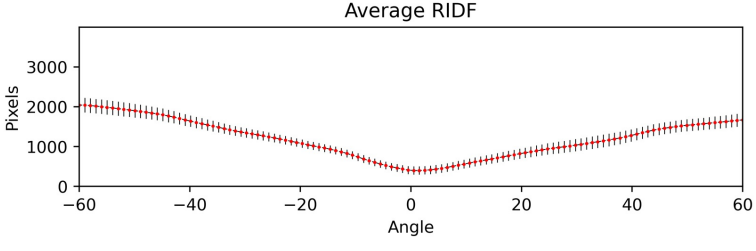
10%







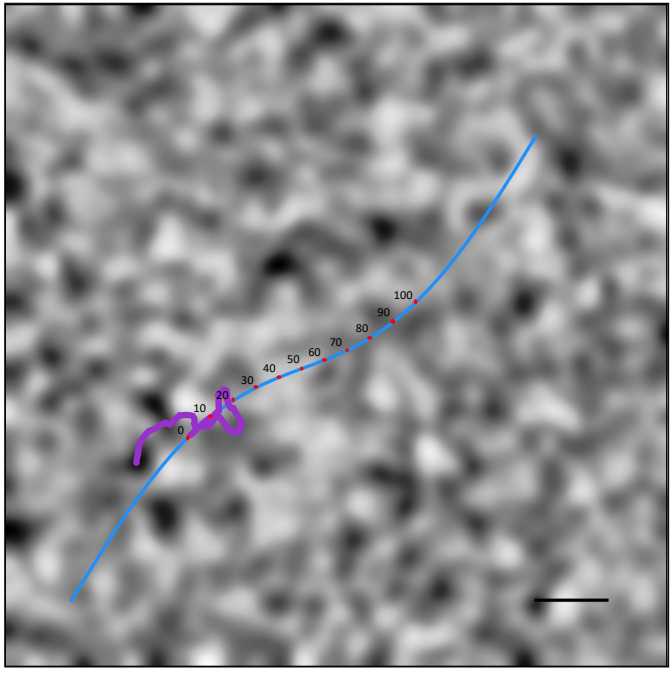


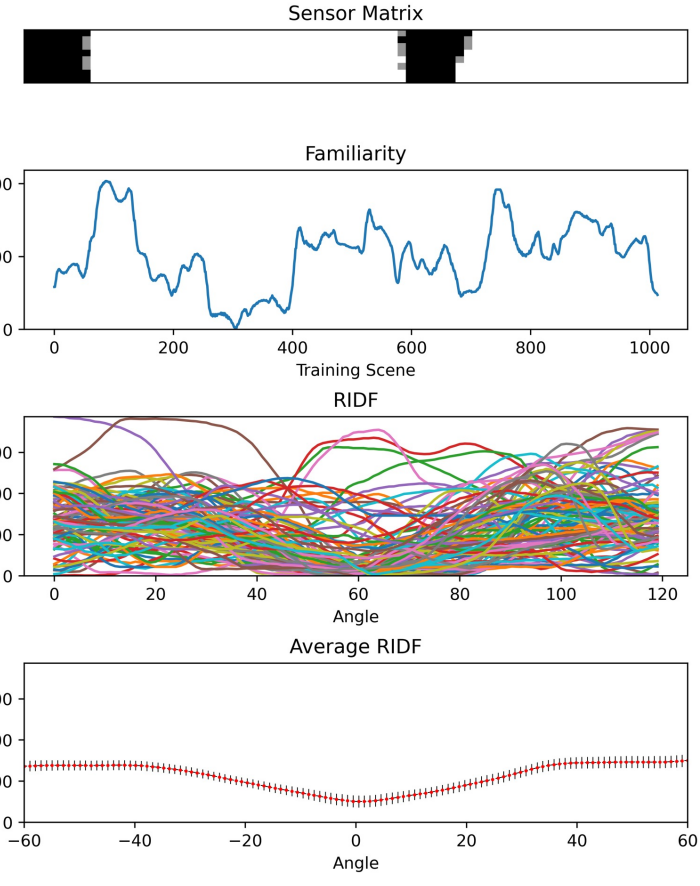


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 7191.38; RMSD/dist: 17.978; TD: 955; p90: 54; p50: 26; complete: 0

10%

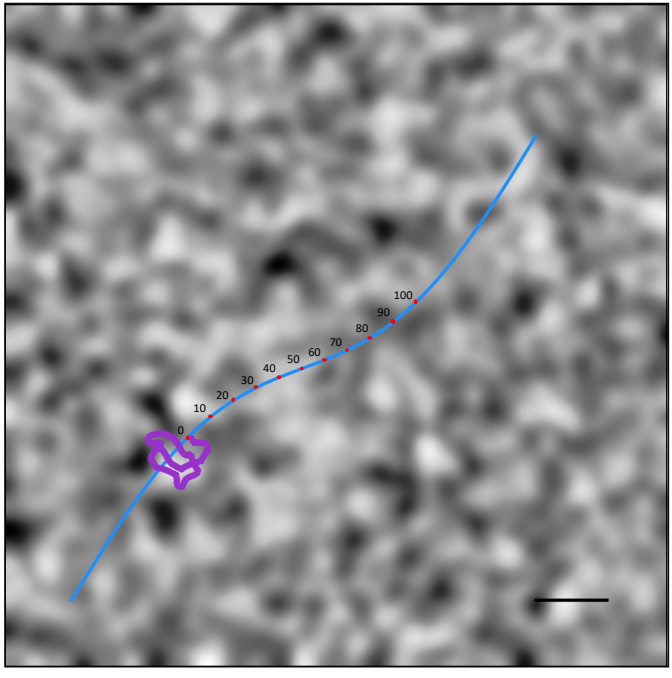


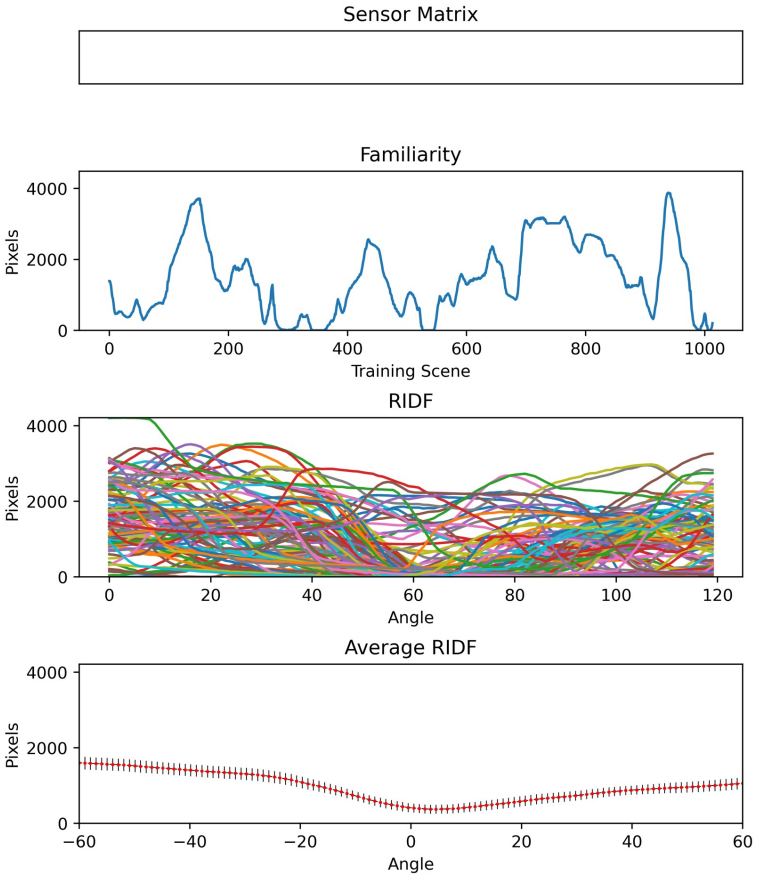


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2151.84; RMSD/dist: 5.380; TD: 1089; p90: 86; p50: 46; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2455.21; RMSD/dist: 6.138; TD: 1118; p90: 76; p50: 32; complete: 0