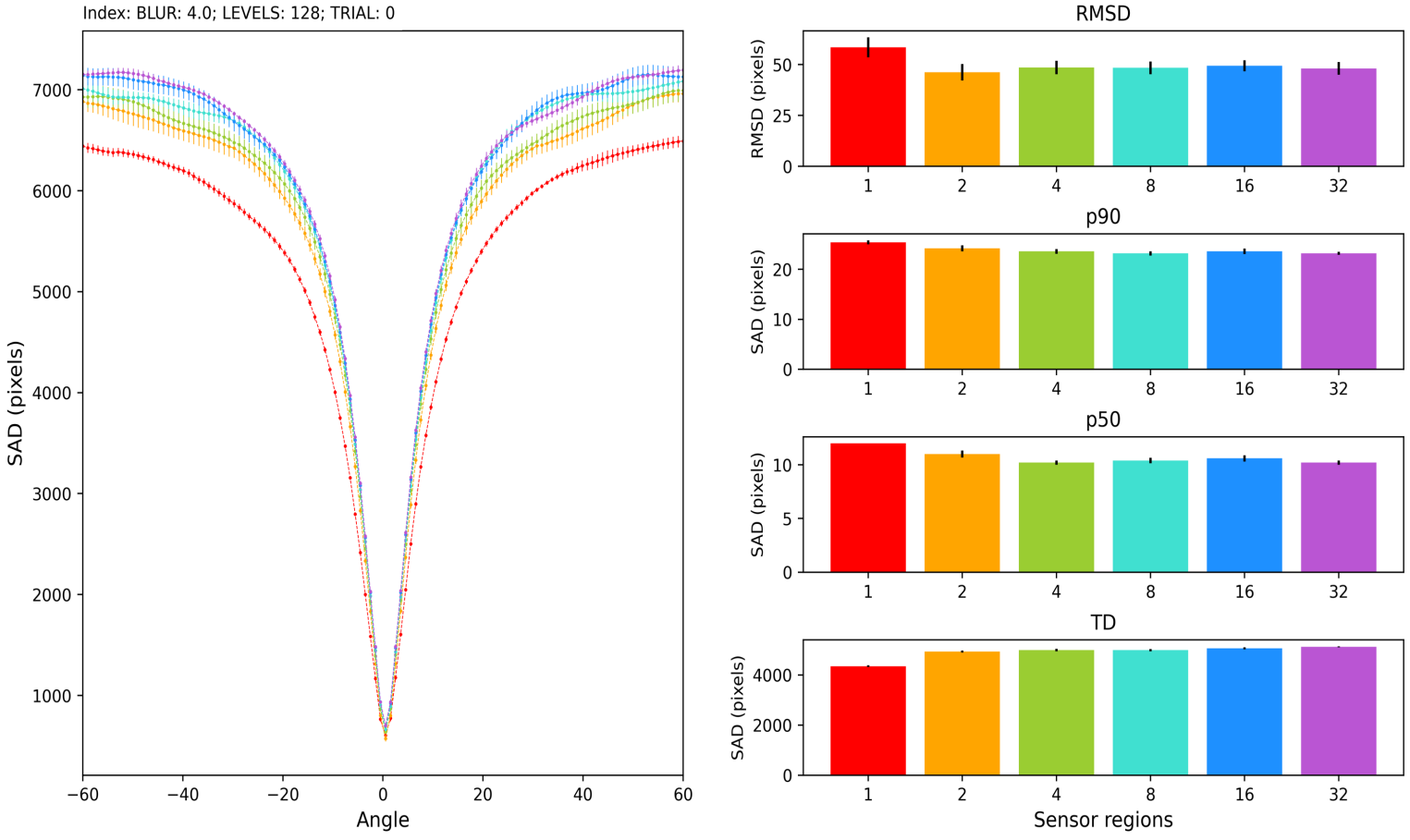
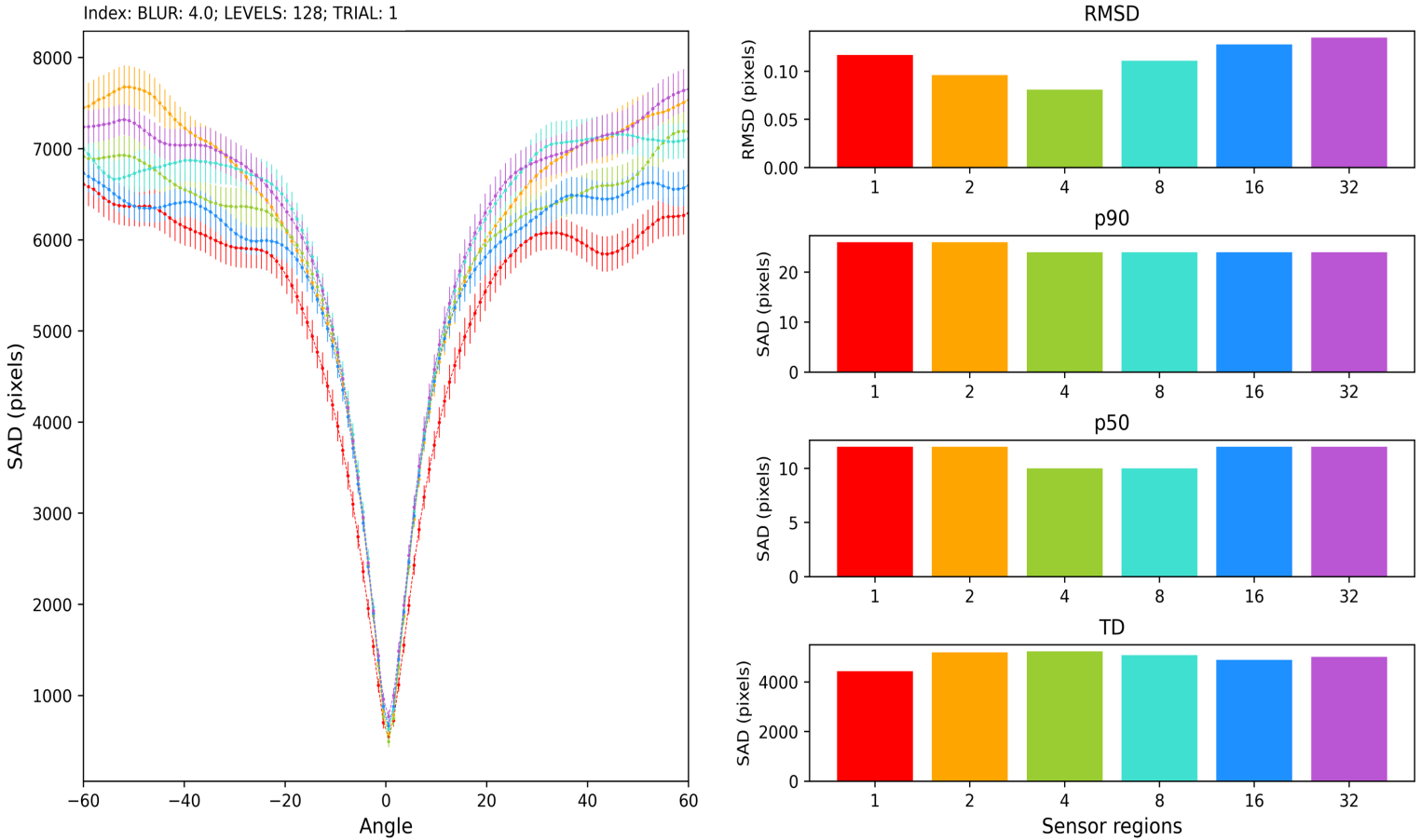

Index: BLUR: 4.0; LEVELS: 128; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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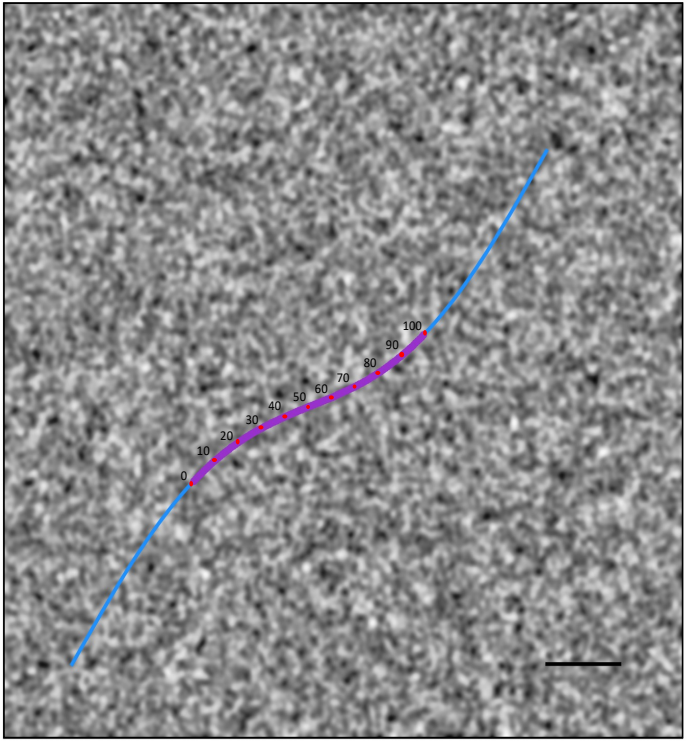
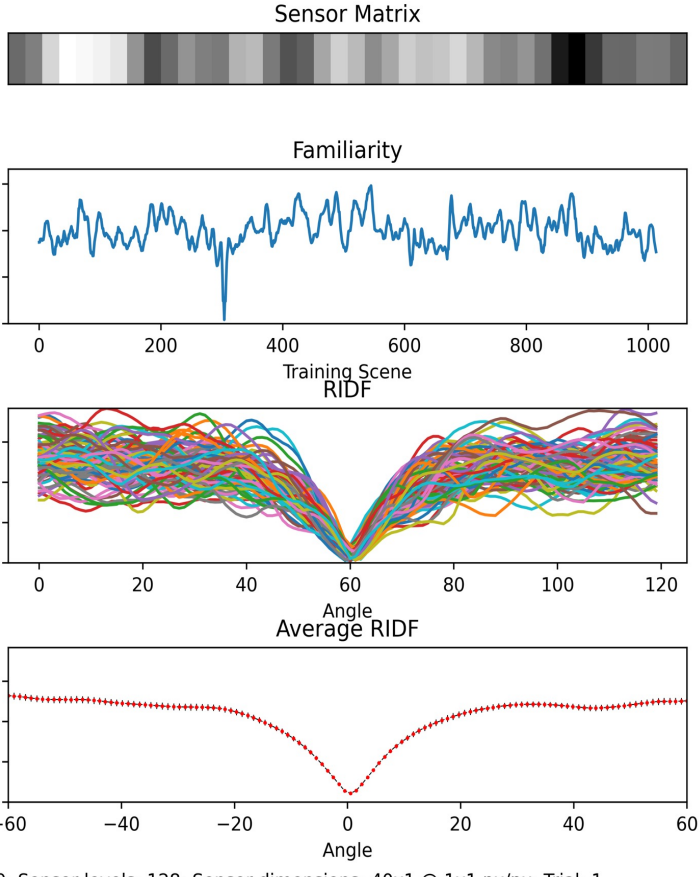
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

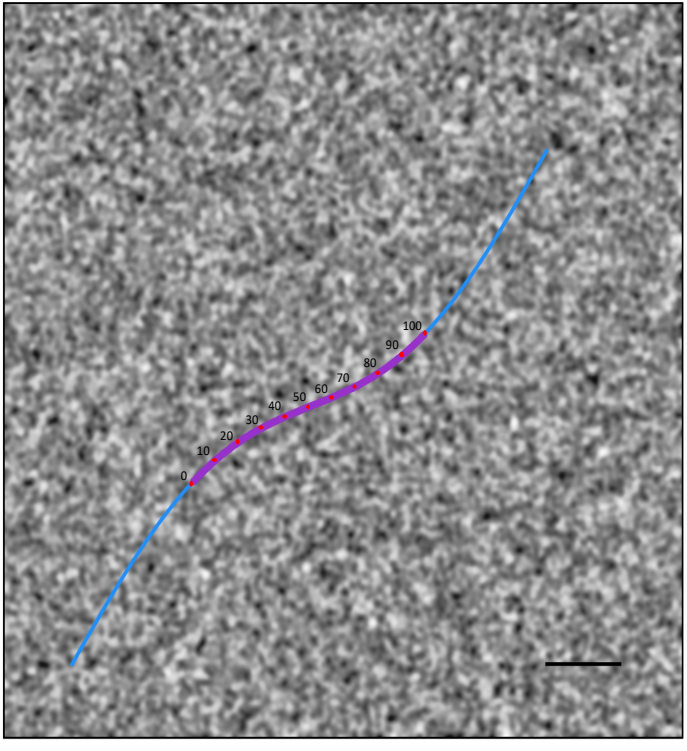


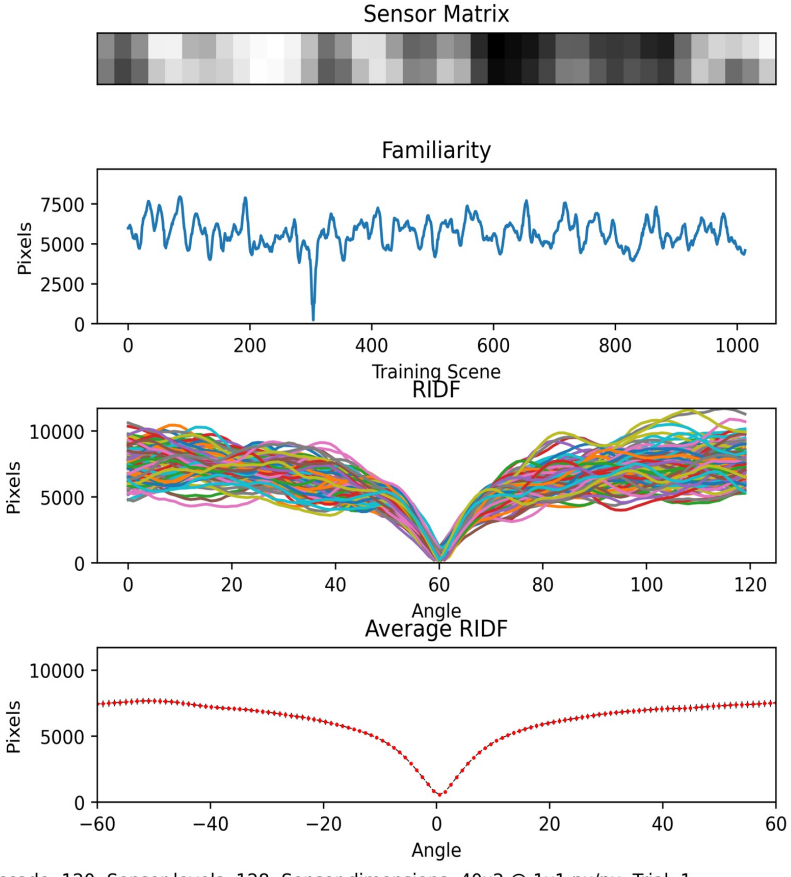




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 46.95; RMSD/dist: 0.117; TD: 4427; p90: 26; p50: 12; complete: 0

100%

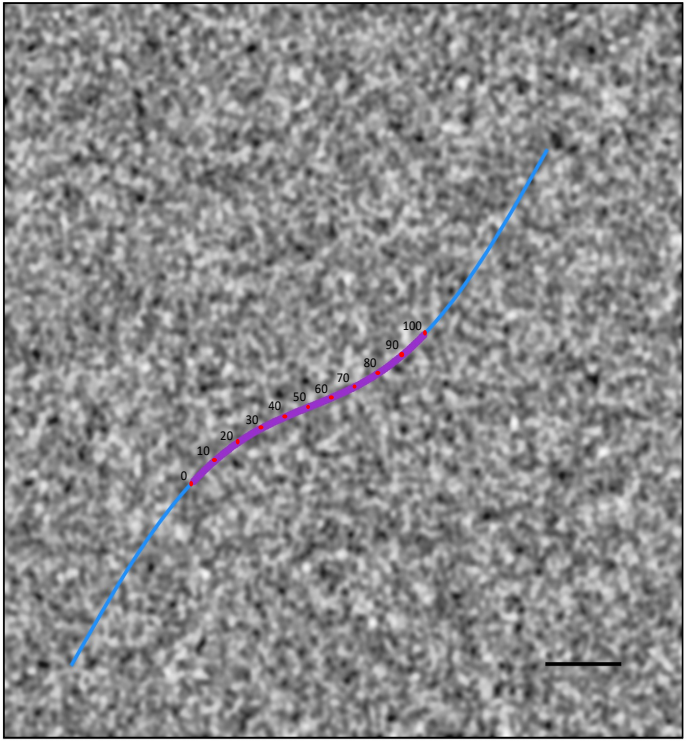


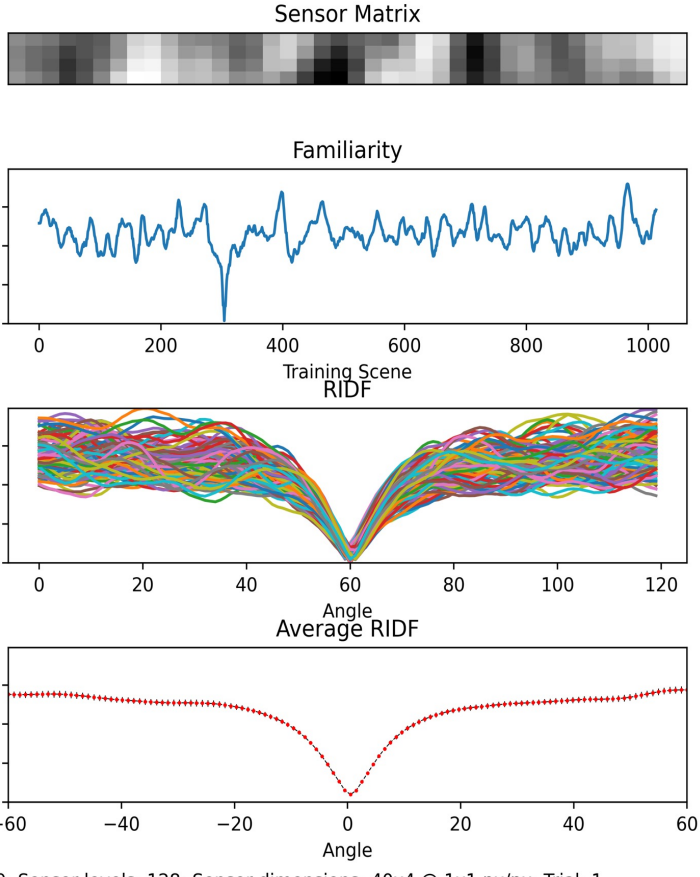




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 38.36; RMSD/dist: 0.096; TD: 5189; p90: 26; p50: 12; complete: 0

100%

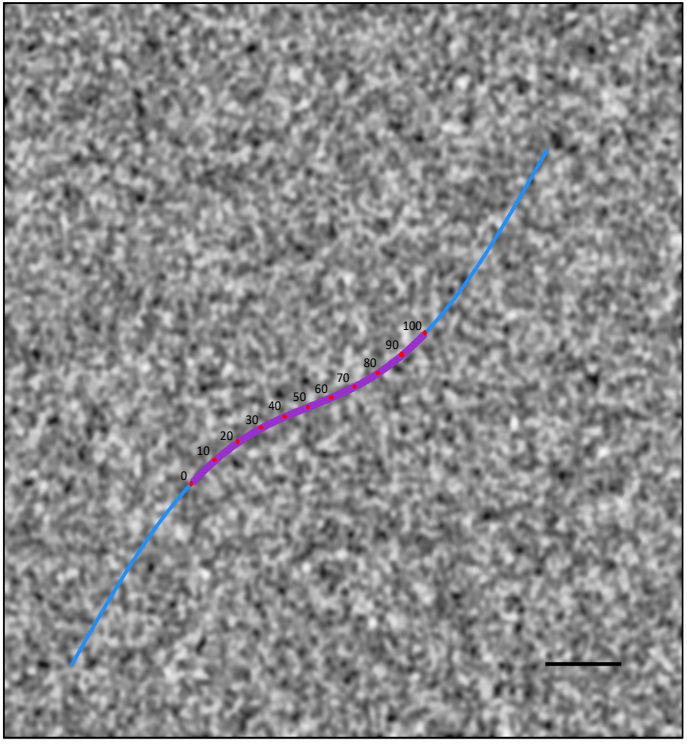


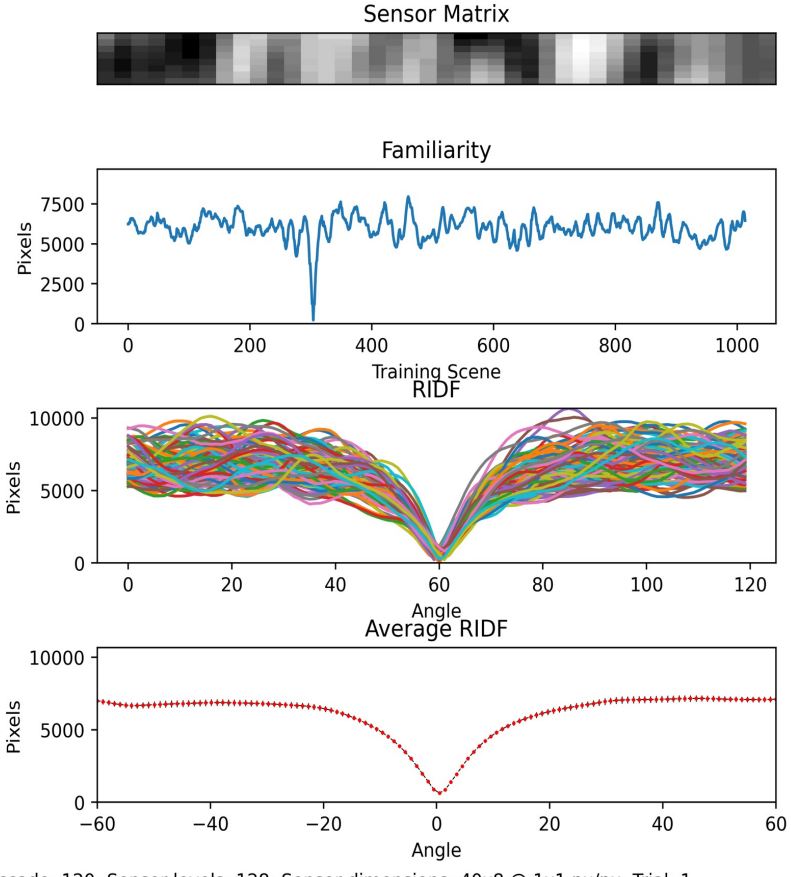




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 32.34; RMSD/dist: 0.081; TD: 5232; p90: 24; p50: 10; complete: 0

100%

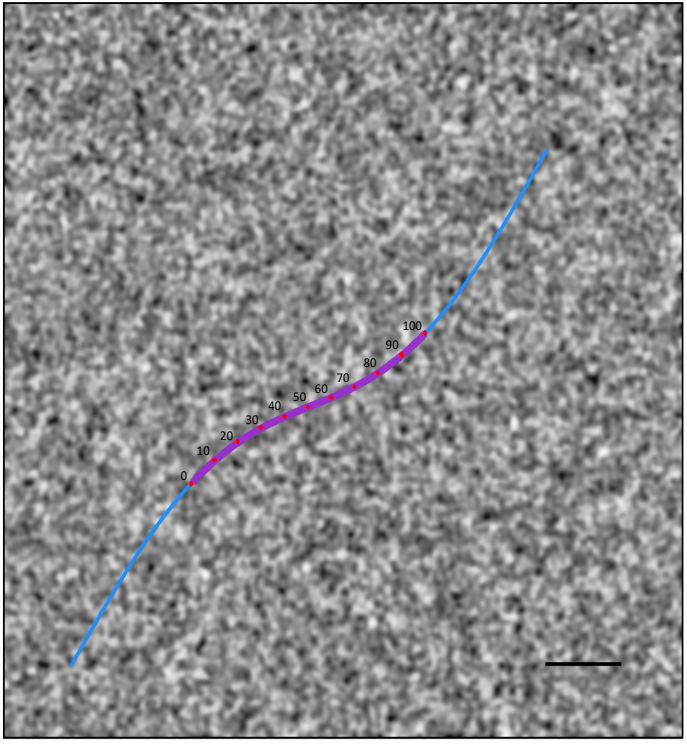


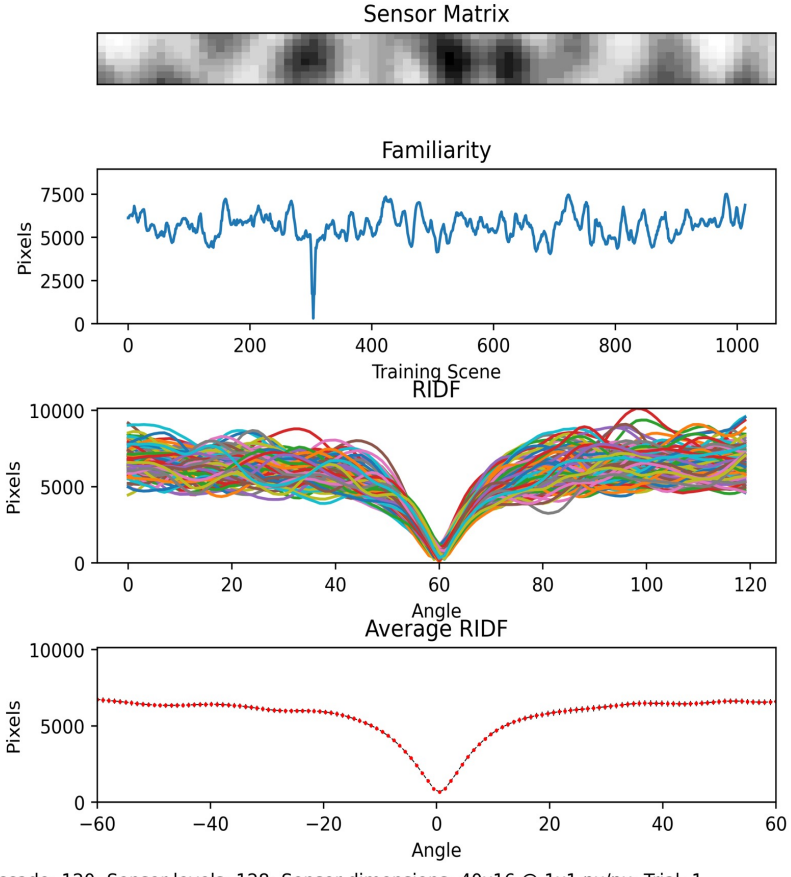




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 44.36; RMSD/dist: 0.111; TD: 5078; p90: 24; p50: 10; complete: 0

100%

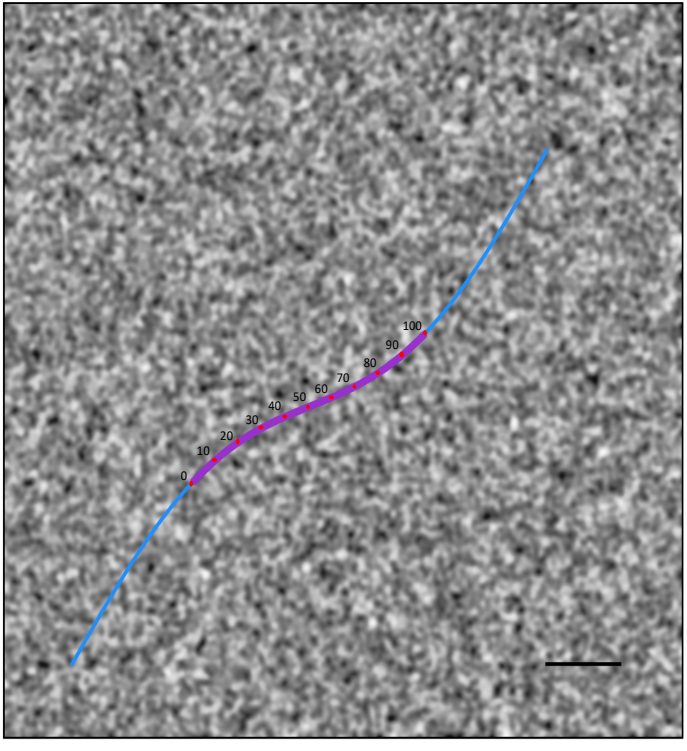


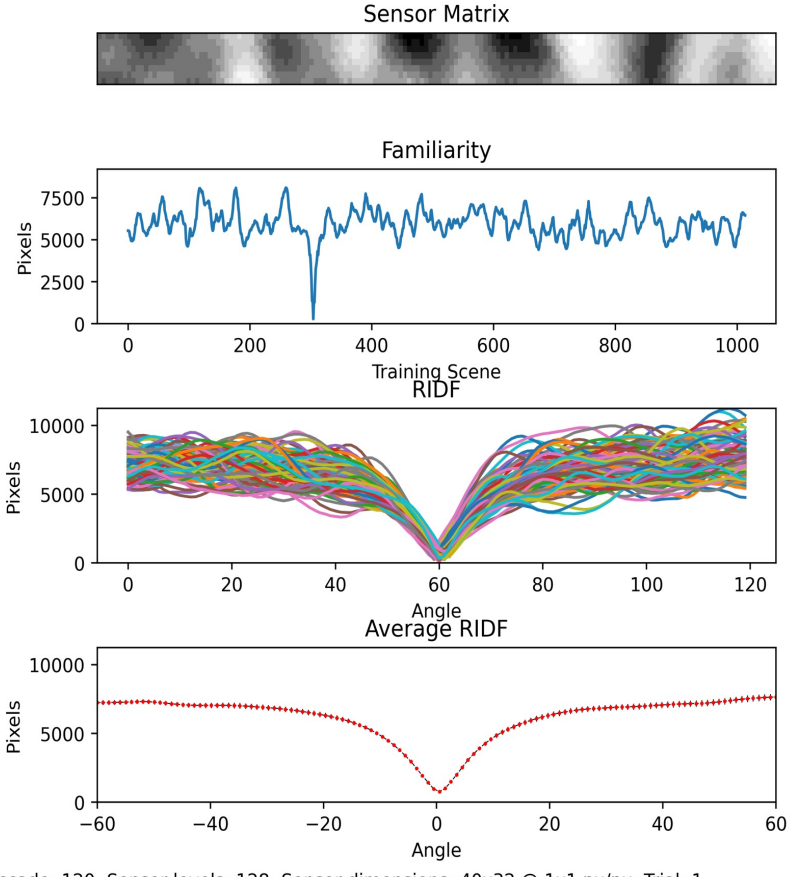




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 51.34; RMSD/dist: 0.128; TD: 4890; p90: 24; p50: 12; complete: 0

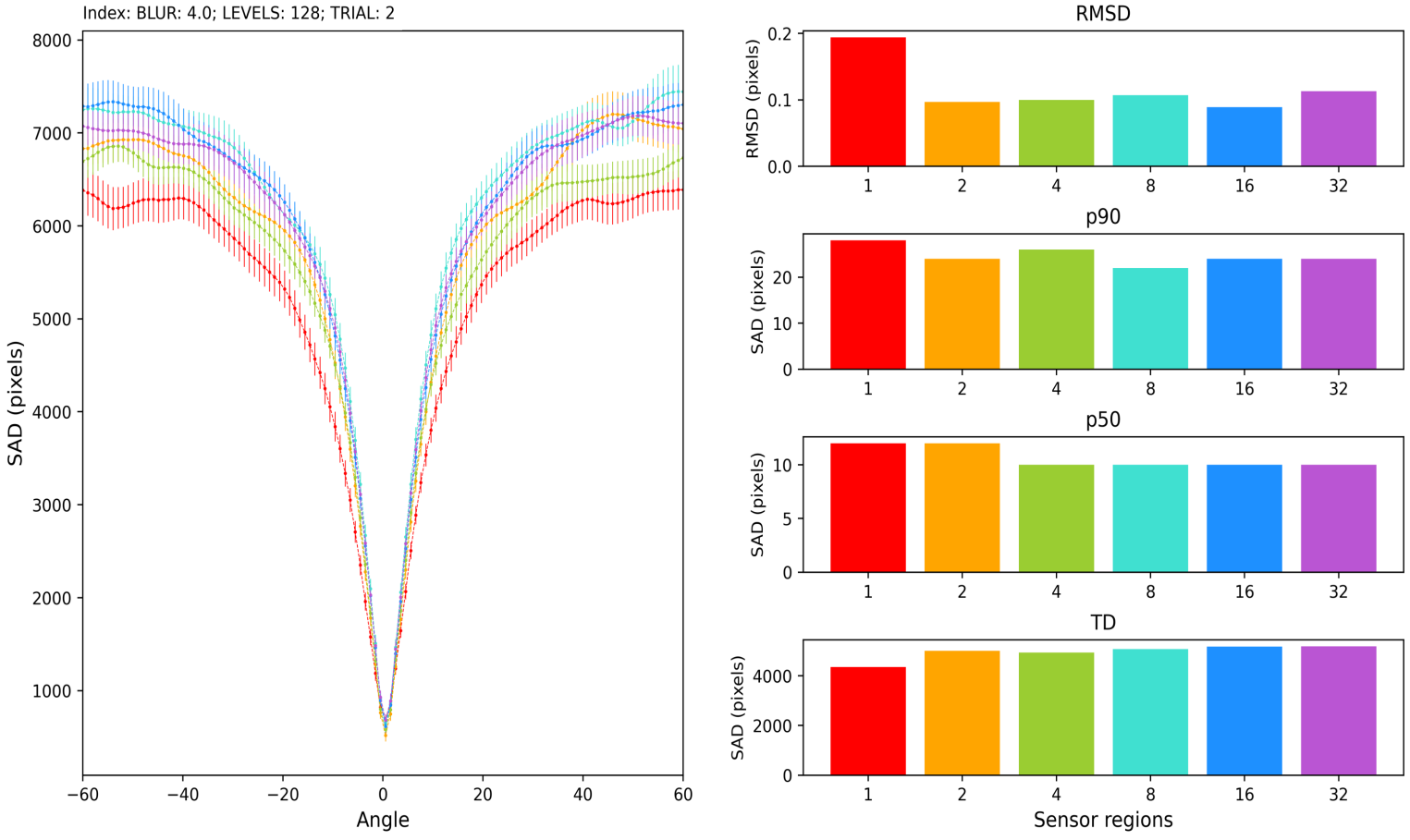
100%



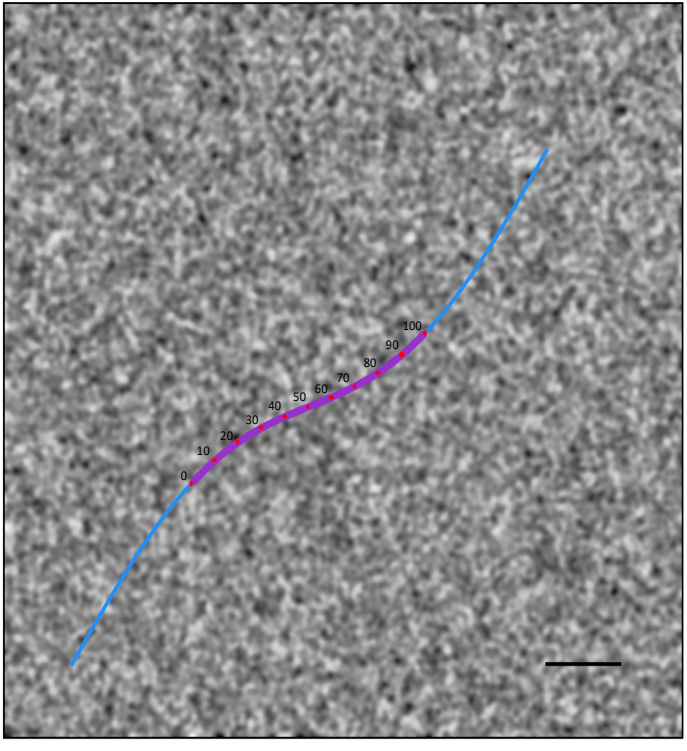



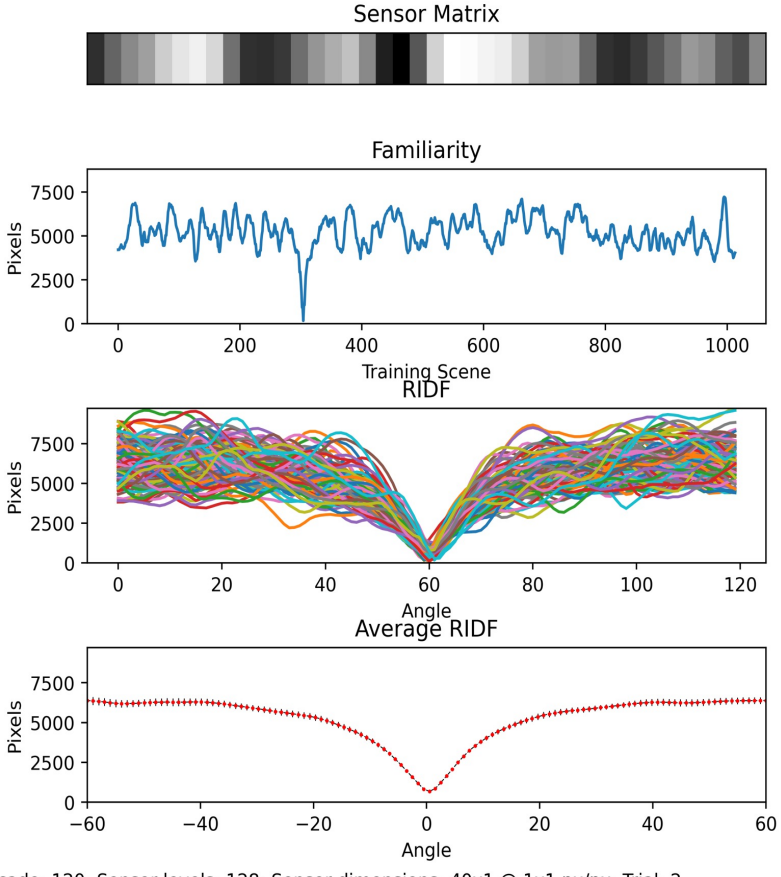

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 54.16; RMSD/dist: 0.135; TD: 5003; p90: 24; p50: 12; complete: 0


Index: BLUR: 4.0; LEVELS: 128; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

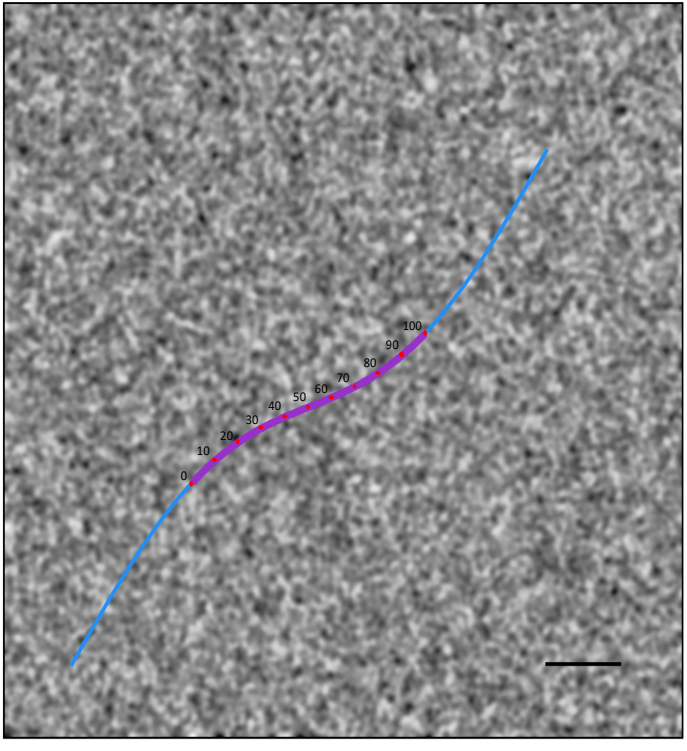


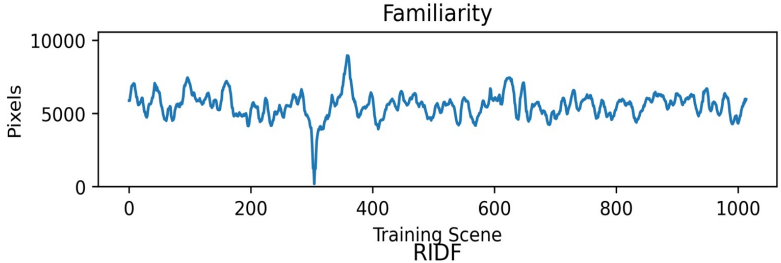



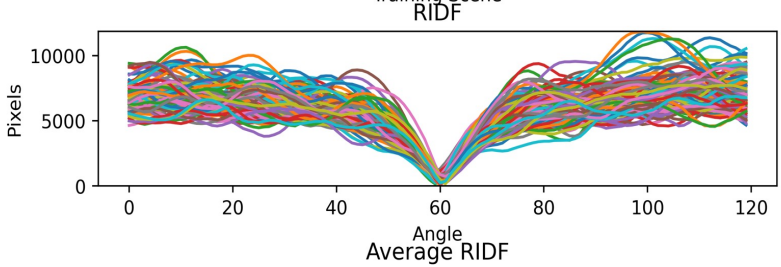

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

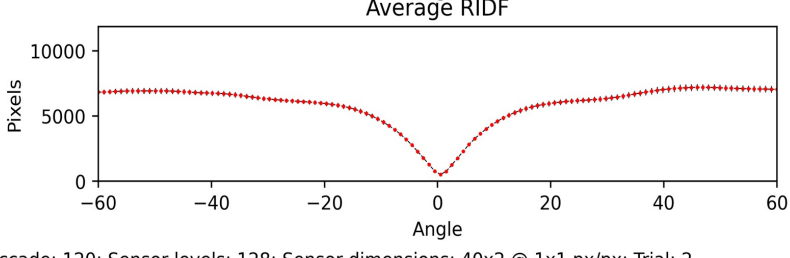
Navigation stats: RMSD error: 77.45; RMSD/dist: 0.194; TD: 4351; p90: 28; p50: 12; complete: 0

100%





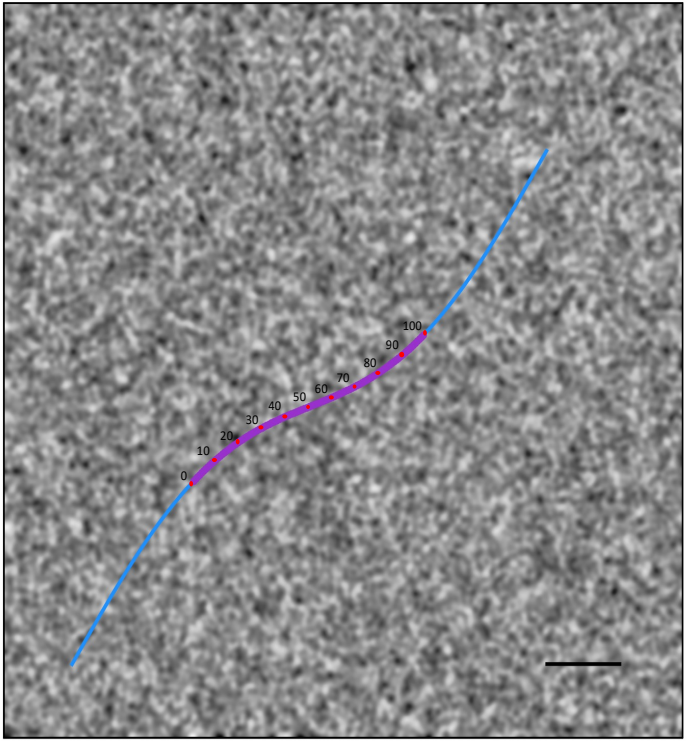



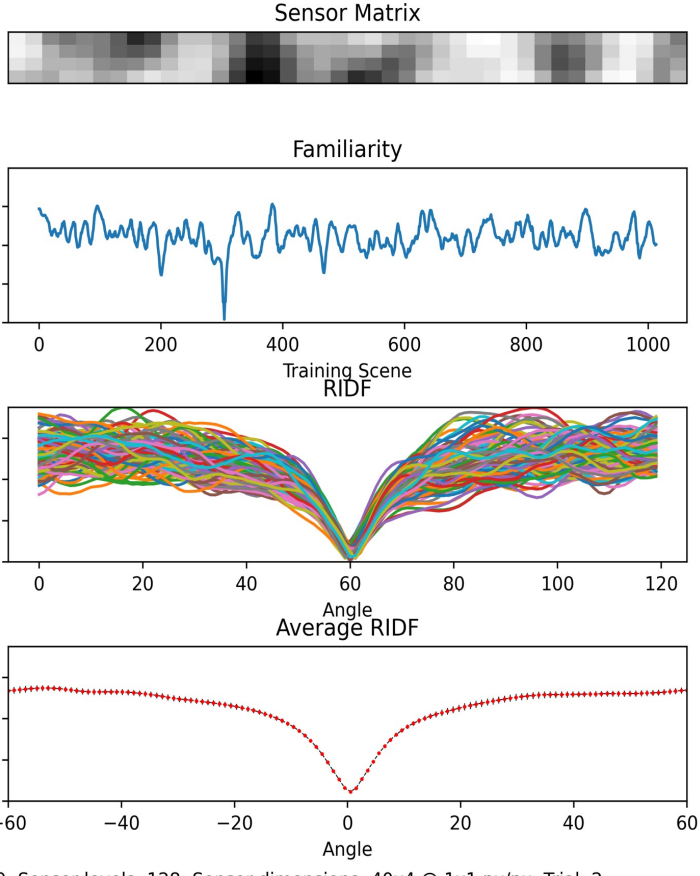




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 38.96; RMSD/dist: 0.097; TD: 5006; p90: 24; p50: 12; complete: 0

100%

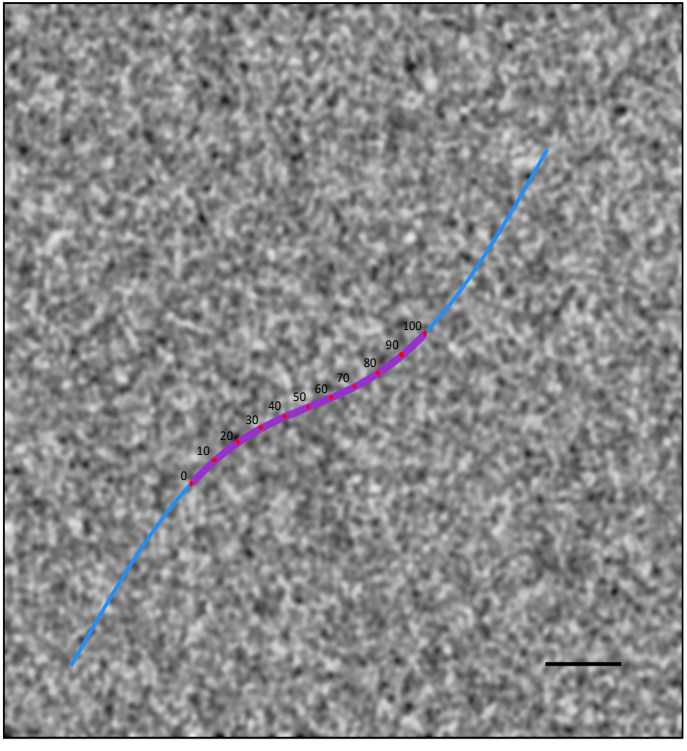


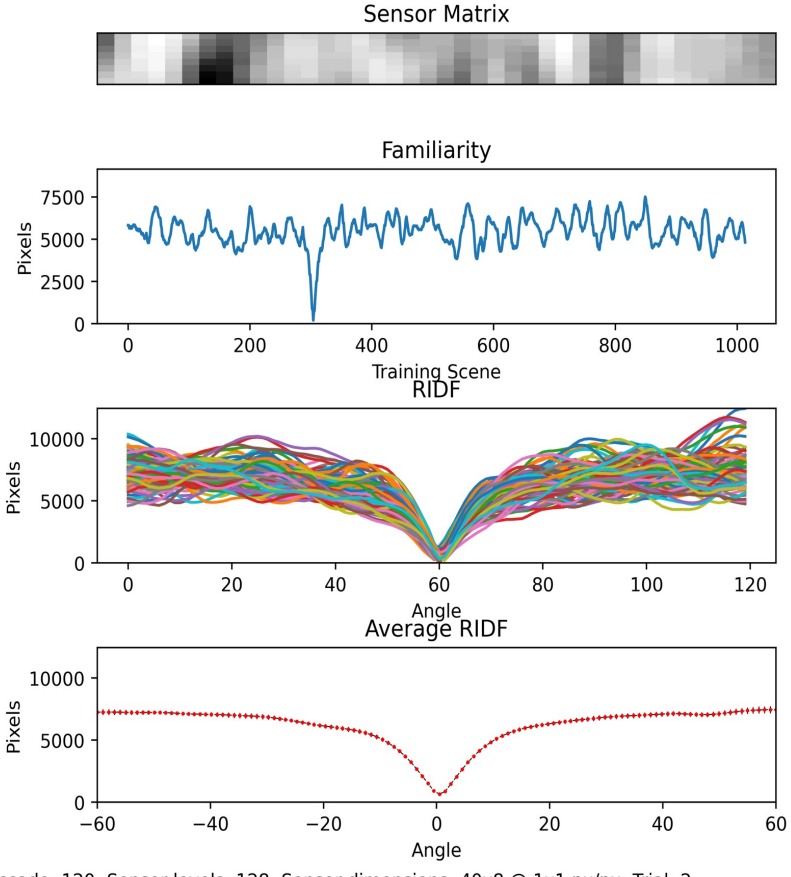




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 39.83; RMSD/dist: 0.100; TD: 4938; p90: 26; p50: 10; complete: 0

100%

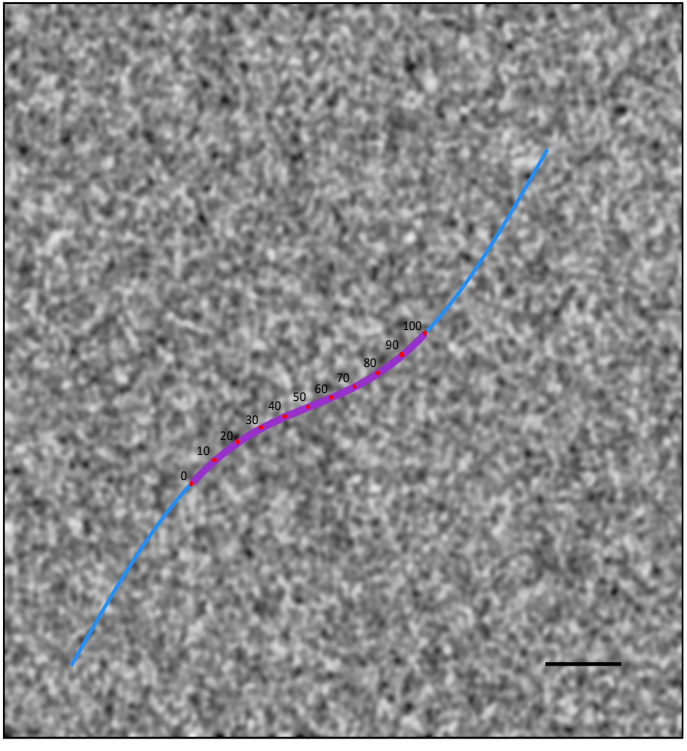


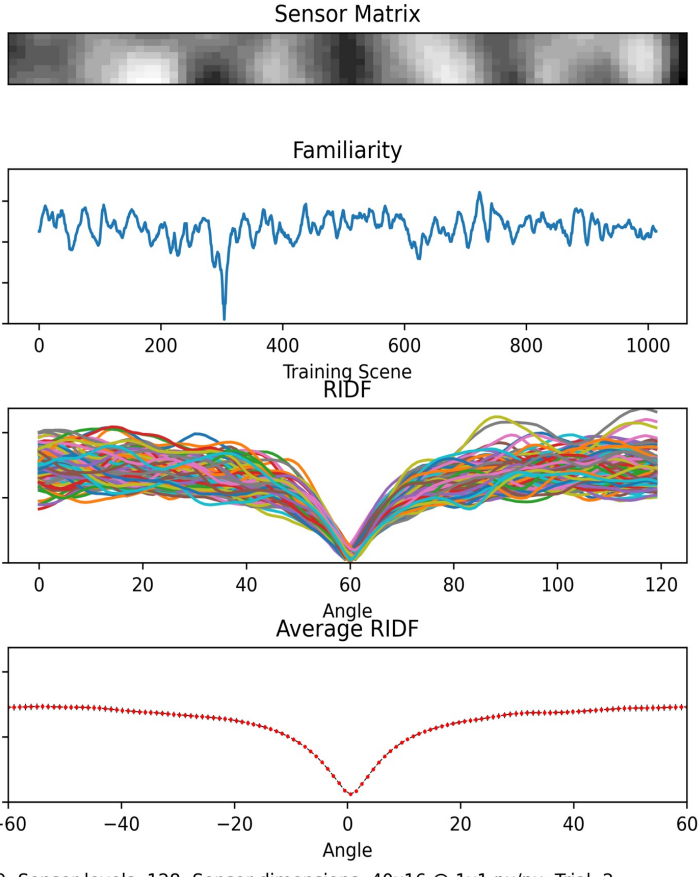




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 42.63; RMSD/dist: 0.107; TD: 5076; p90: 22; p50: 10; complete: 0

100%

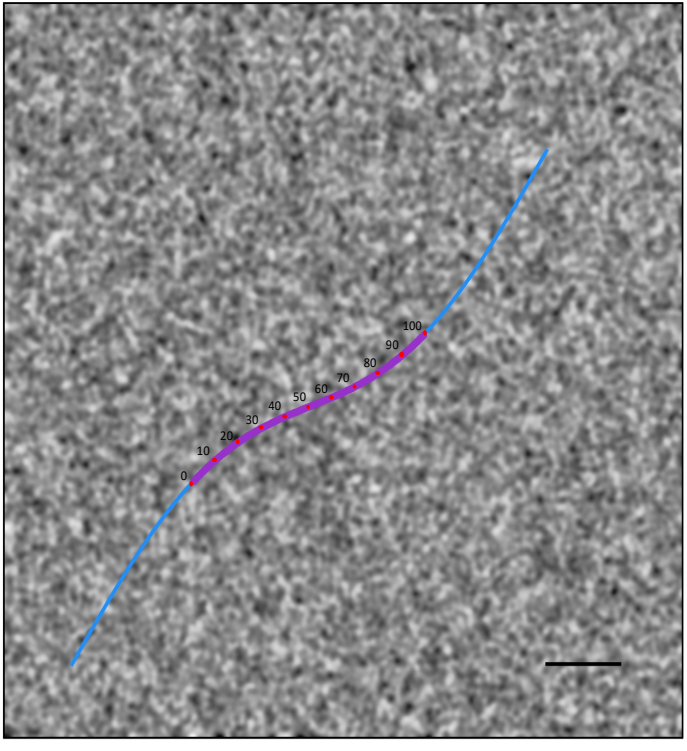


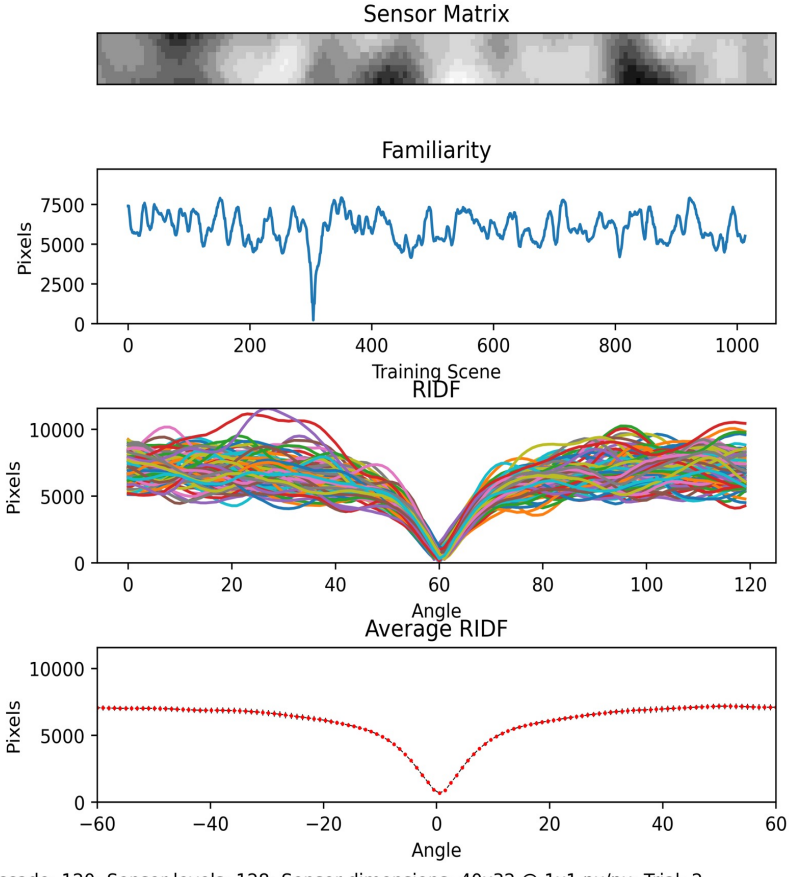




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 35.70; RMSD/dist: 0.089; TD: 5180; p90: 24; p50: 10; complete: 0

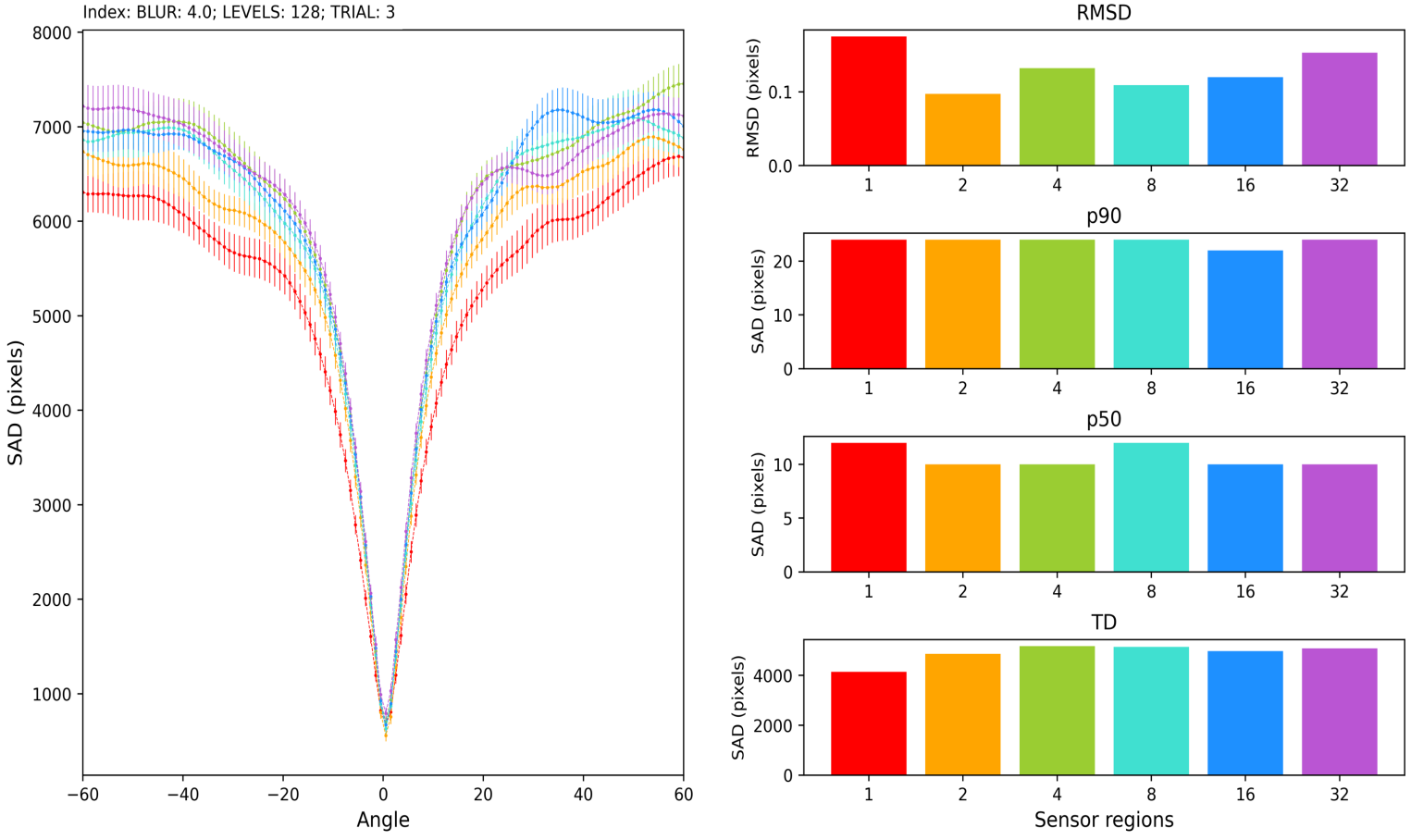
100%



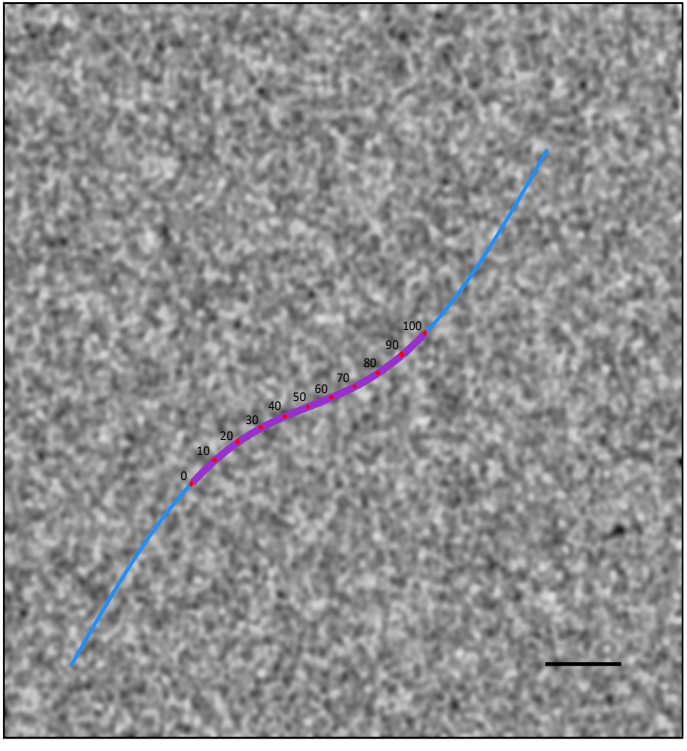



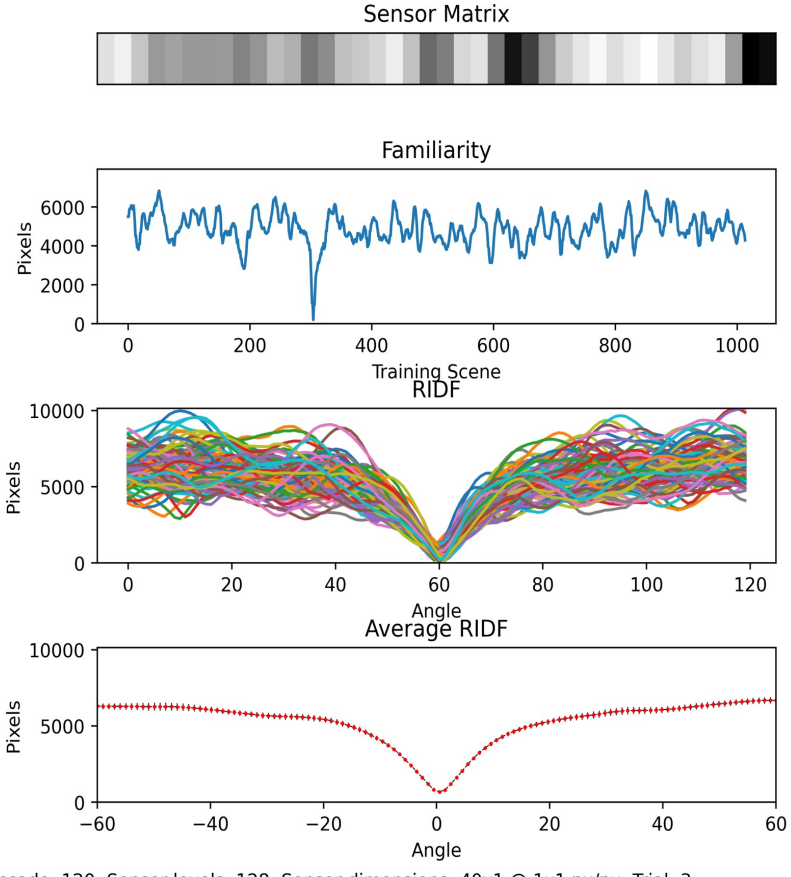

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 45.14; RMSD/dist: 0.113; TD: 5190; p90: 24; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 128; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

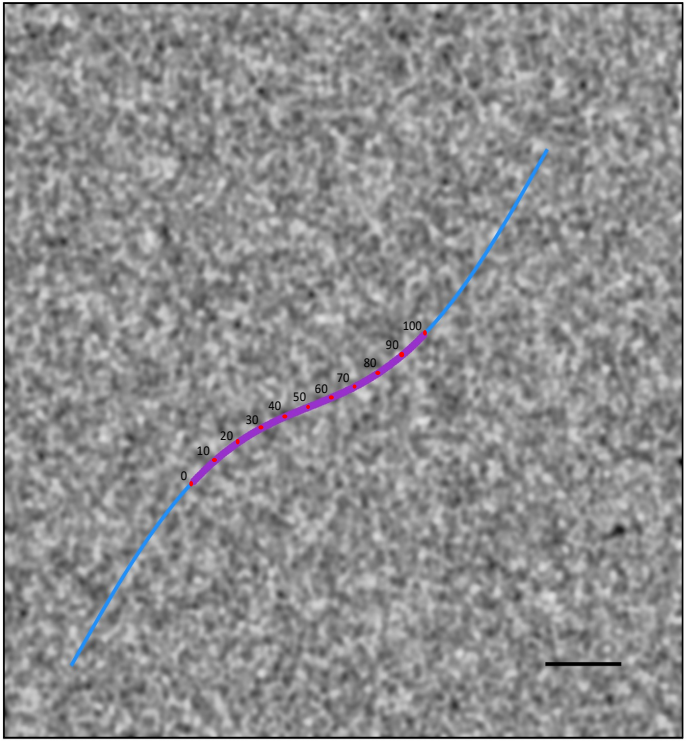


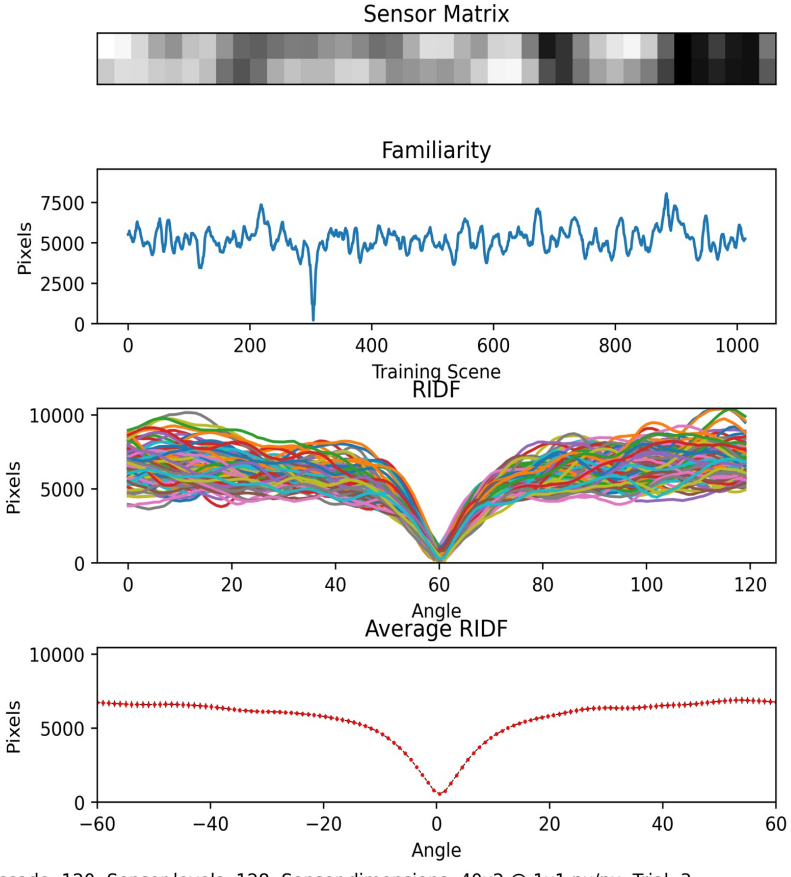




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 69.91; RMSD/dist: 0.175; TD: 4148; p90: 24; p50: 12; complete: 0

100%

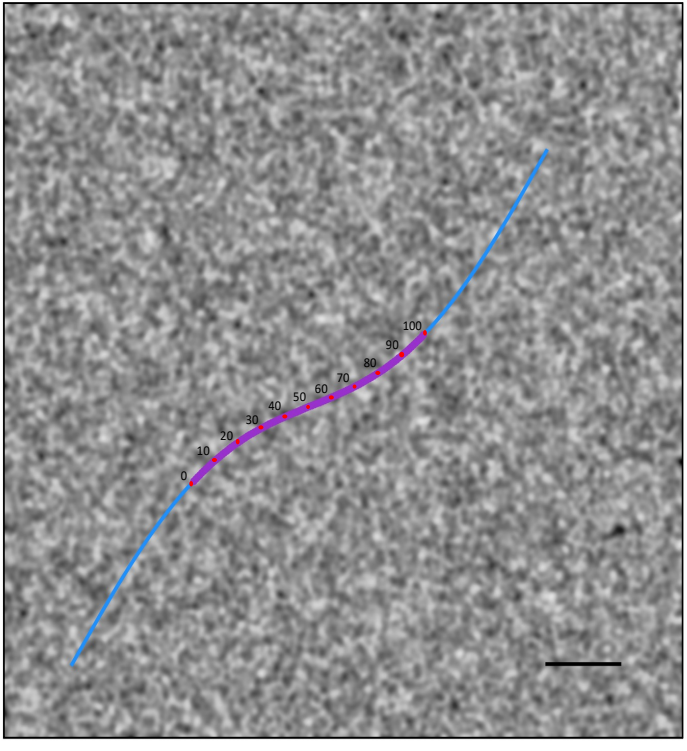


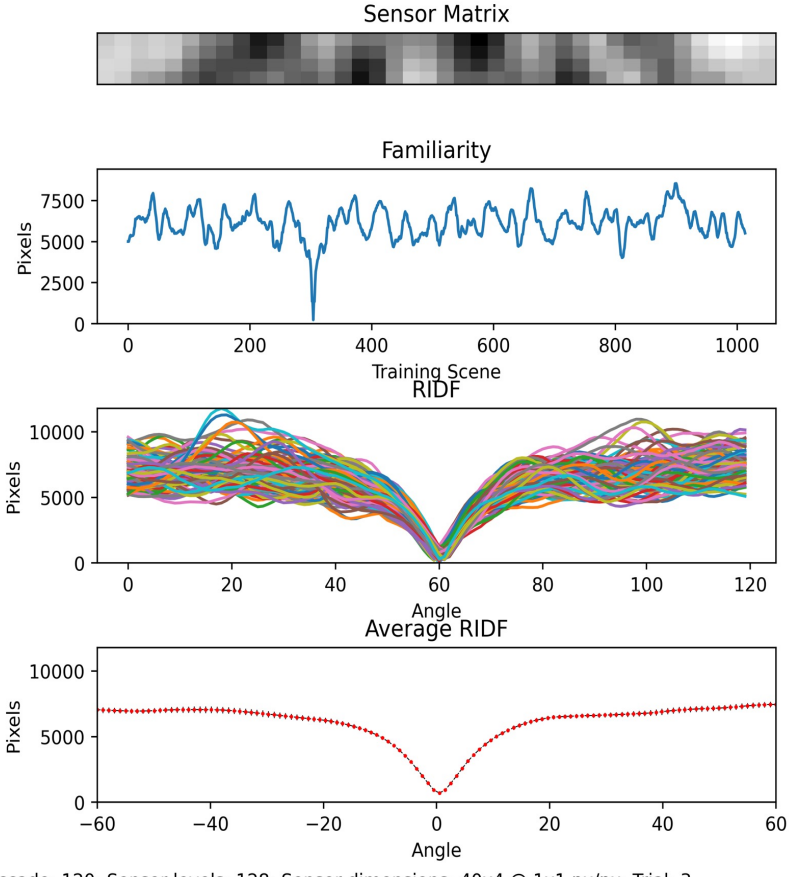




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 38.98; RMSD/dist: 0.097; TD: 4860; p90: 24; p50: 10; complete: 0

100%

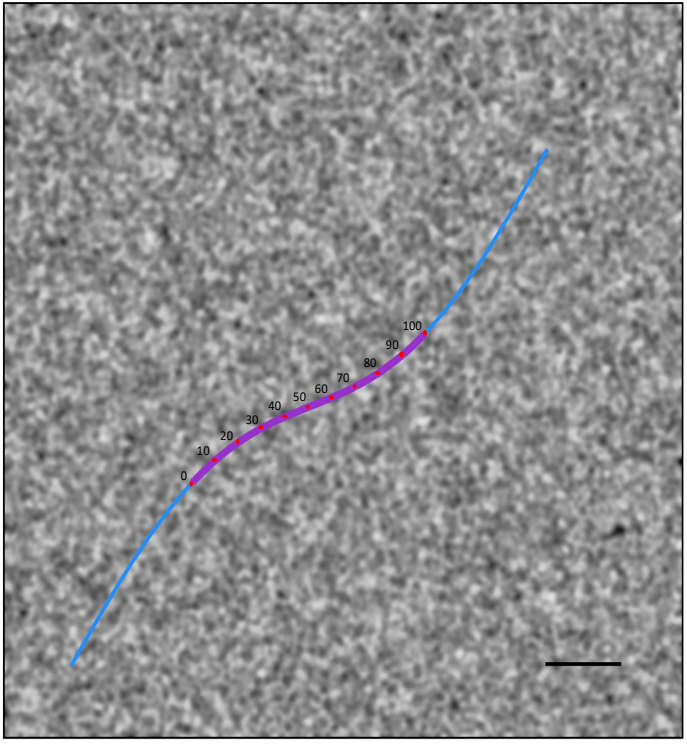


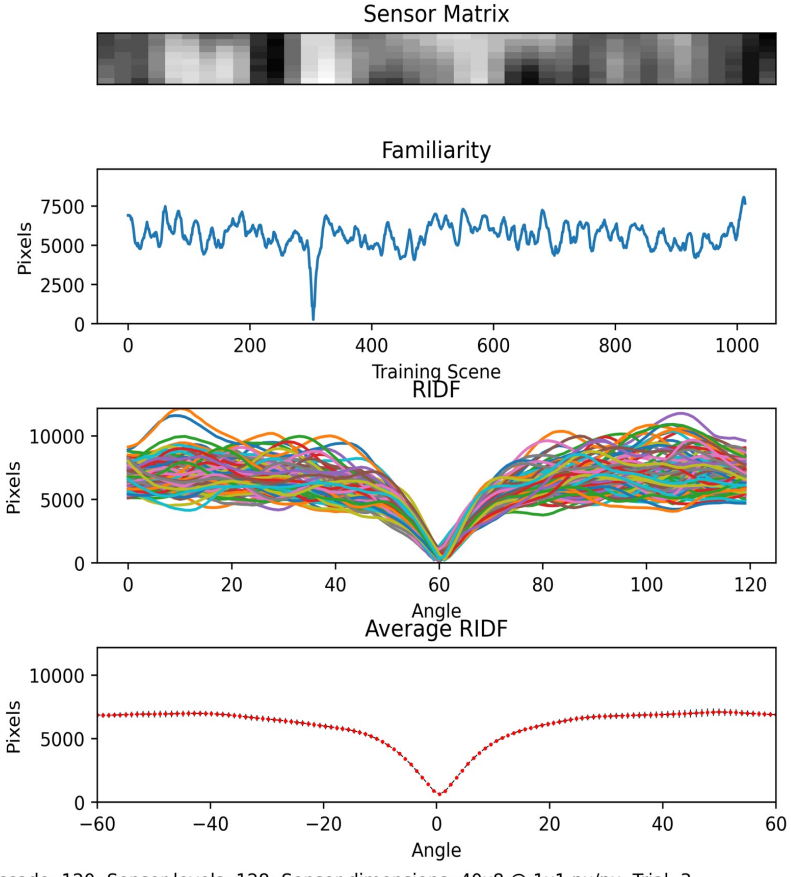




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 52.60; RMSD/dist: 0.132; TD: 5177; p90: 24; p50: 10; complete: 0

100%

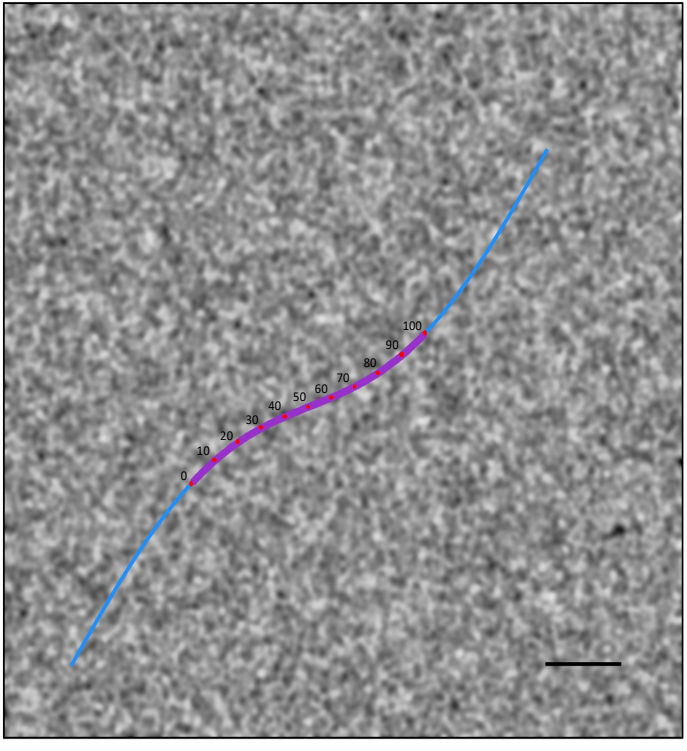


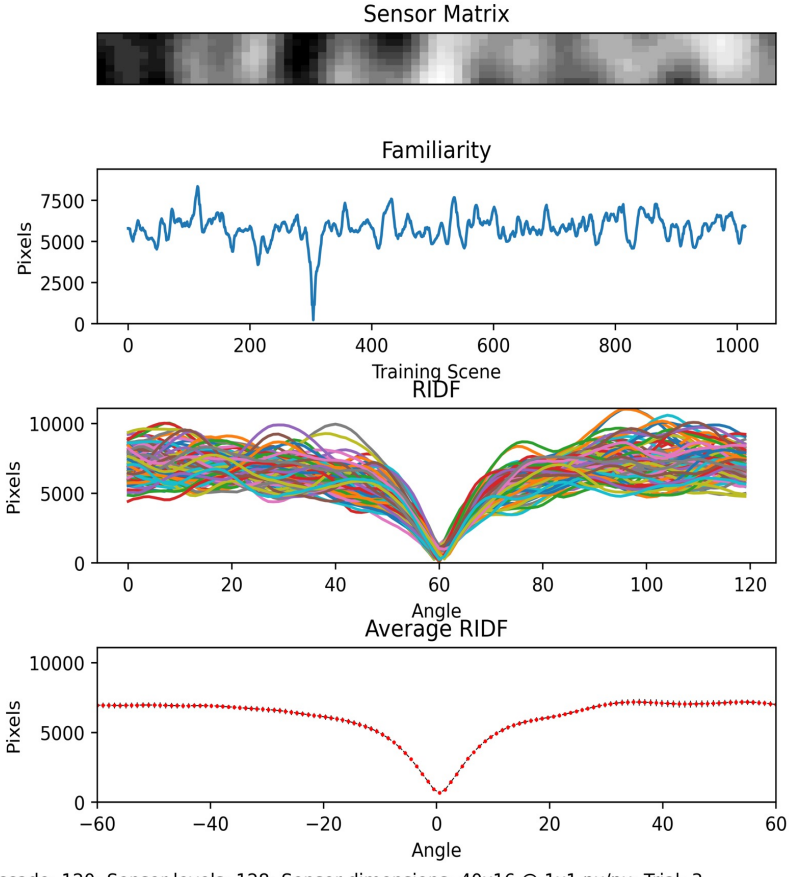




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 43.51; RMSD/dist: 0.109; TD: 5144; p90: 24; p50: 12; complete: 0

100%

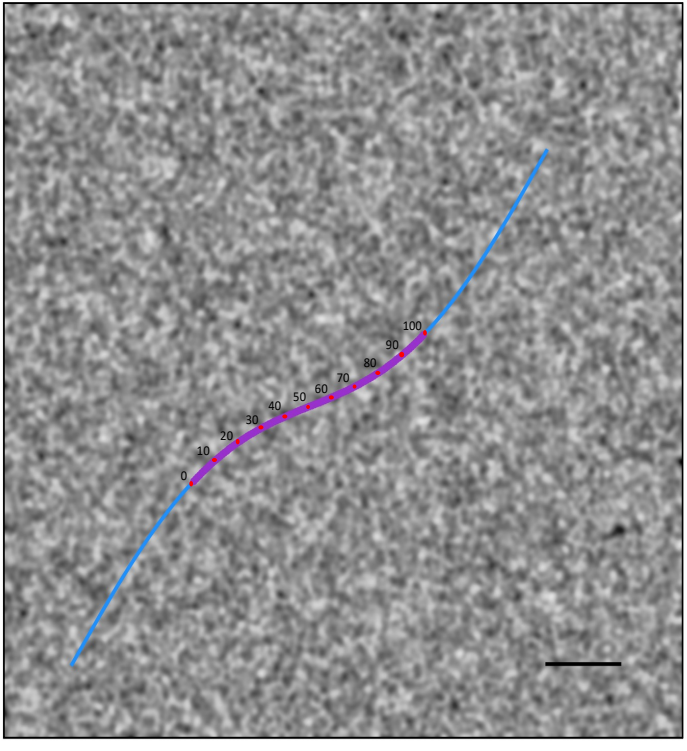


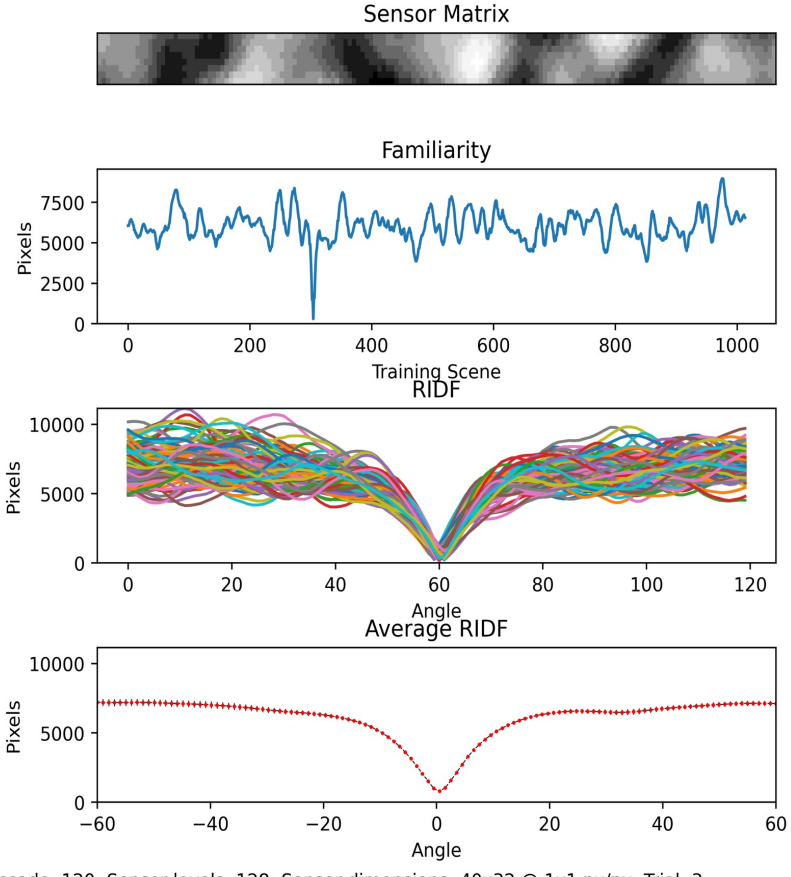




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 48.10; RMSD/dist: 0.120; TD: 4974; p90: 22; p50: 10; complete: 0

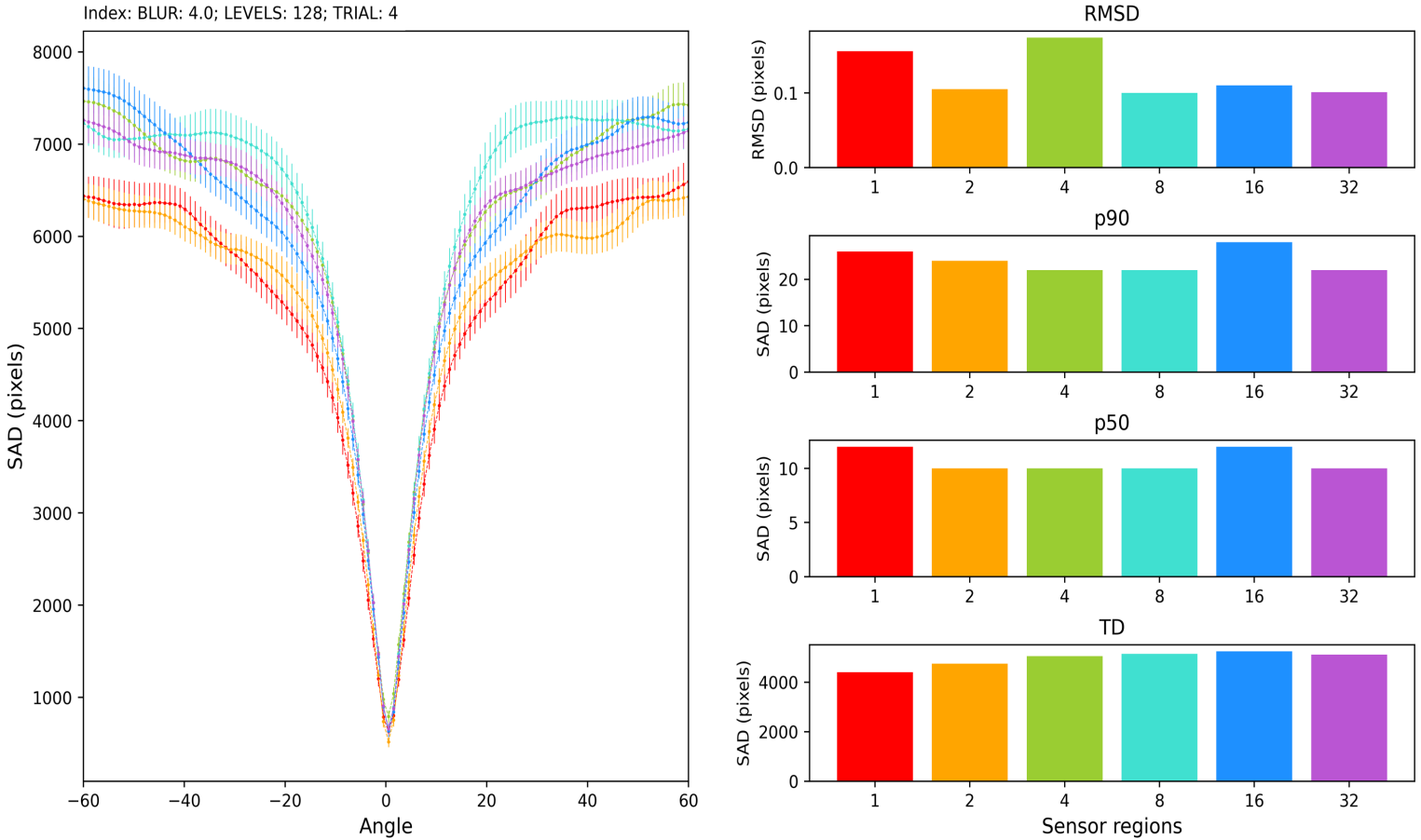
100%



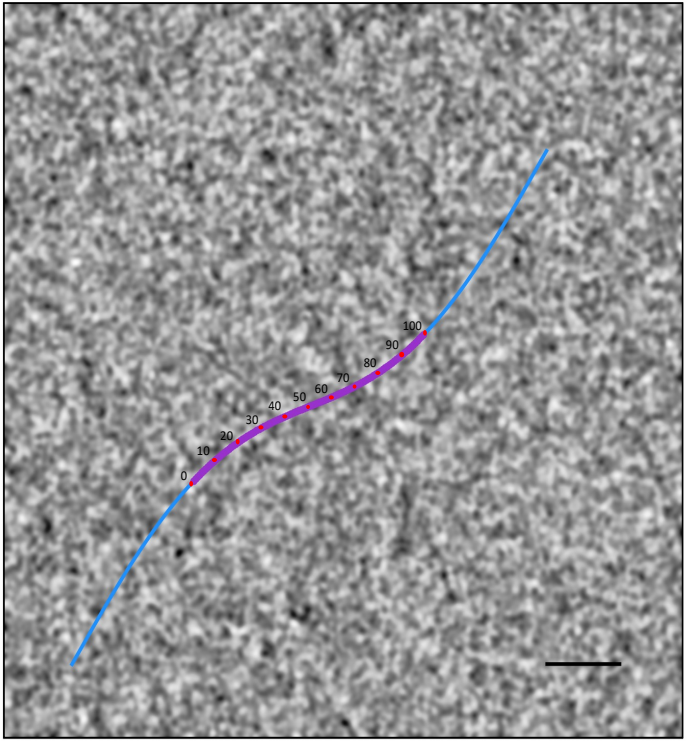



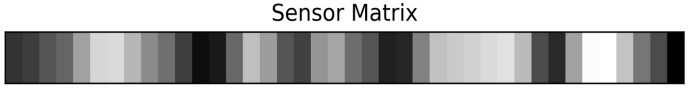

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

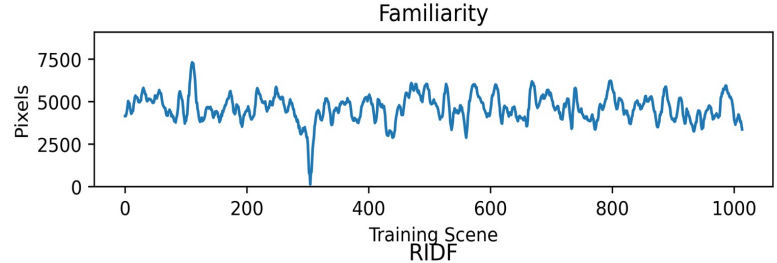
Navigation stats: RMSD error: 61.05; RMSD/dist: 0.153; TD: 5085; p90: 24; p50: 10; complete: 0

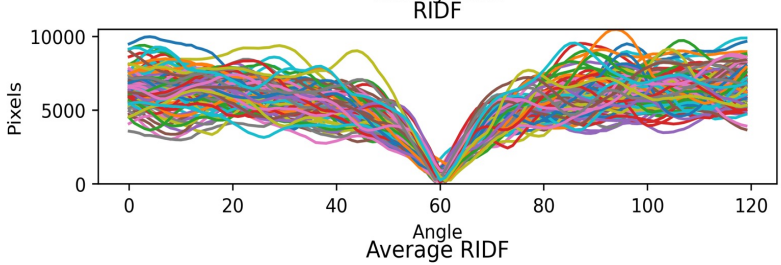

Index: BLUR: 4.0; LEVELS: 128; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

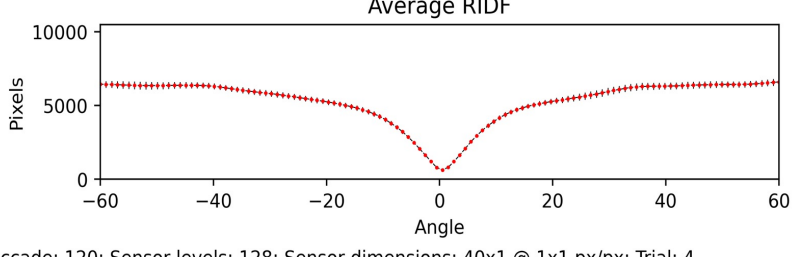
100%



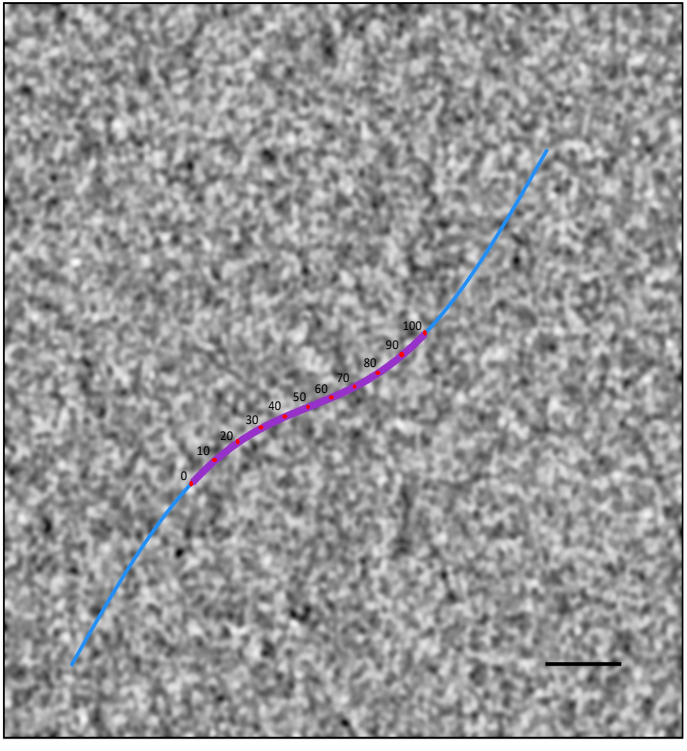



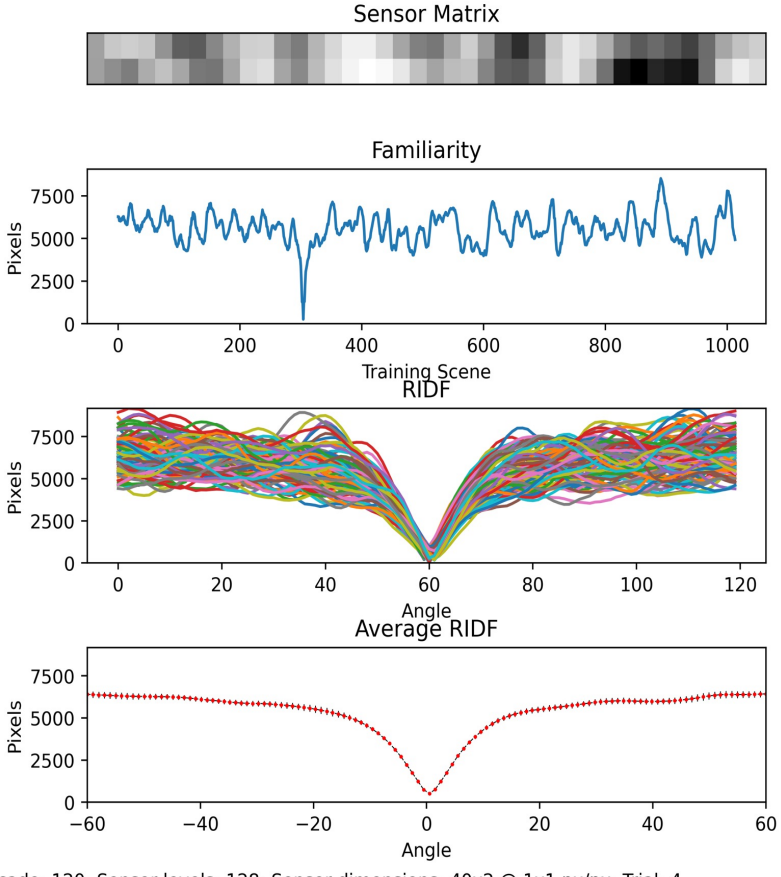




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 62.55; RMSD/dist: 0.156; TD: 4403; p90: 26; p50: 12; complete: 0

100%

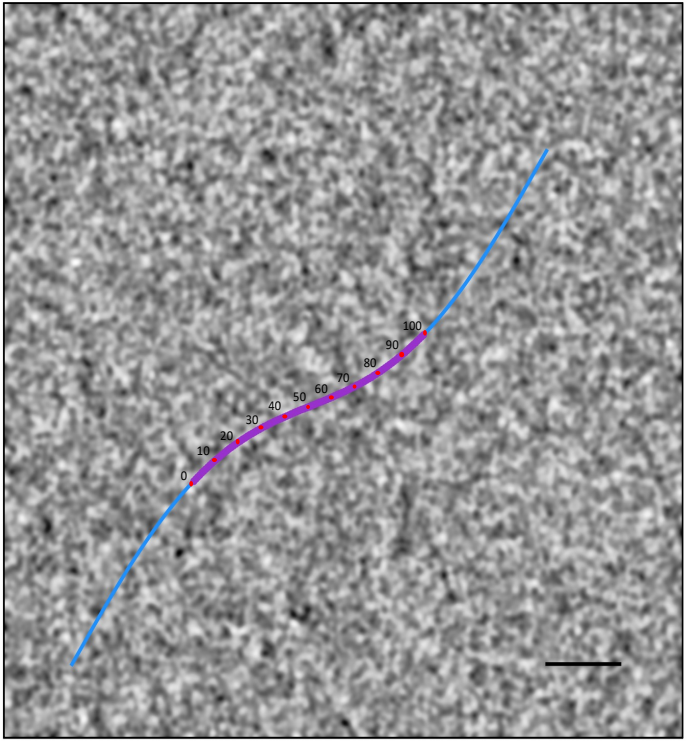


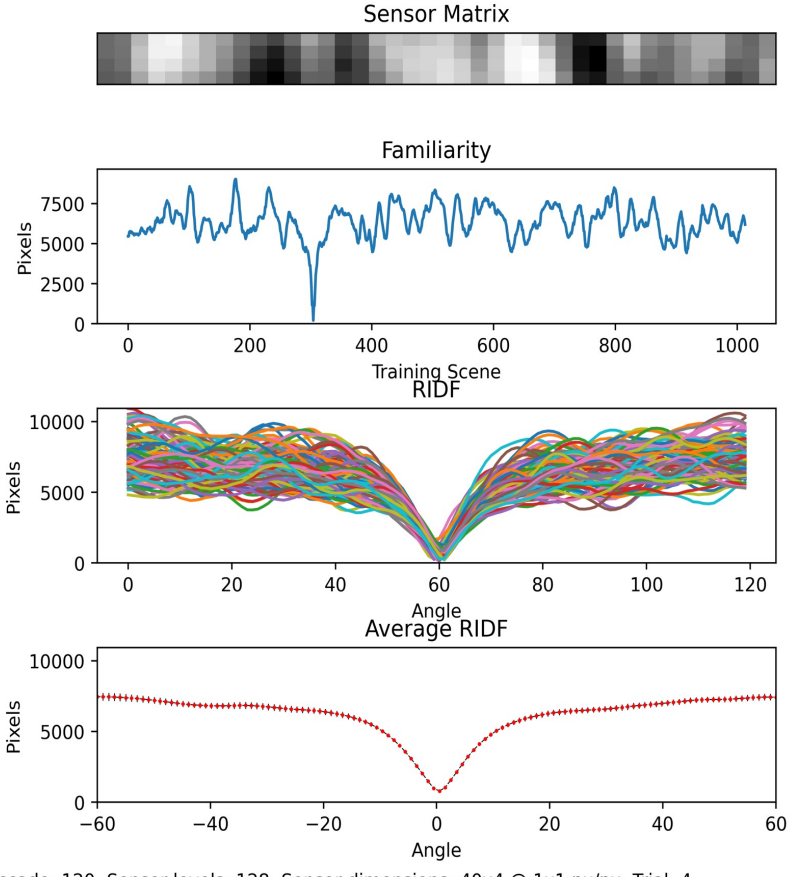




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 42.08; RMSD/dist: 0.105; TD: 4743; p90: 24; p50: 10; complete: 0

100%

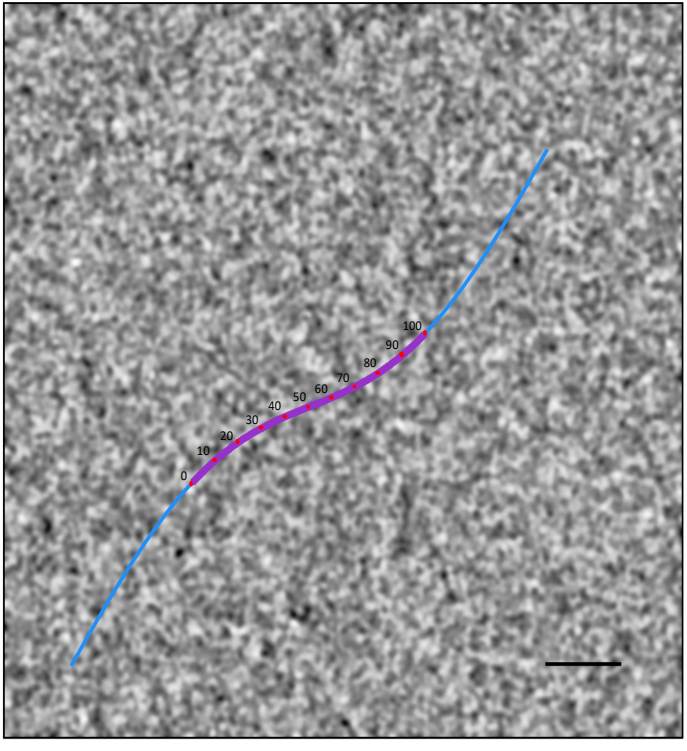


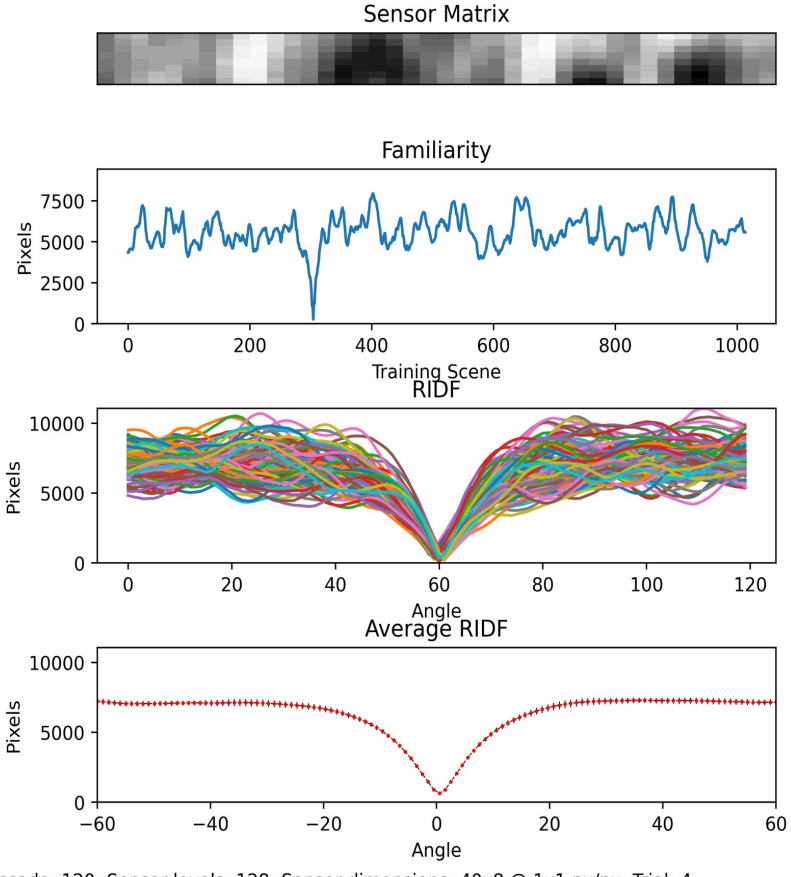




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 69.66; RMSD/dist: 0.174; TD: 5047; p90: 22; p50: 10; complete: 0

100%

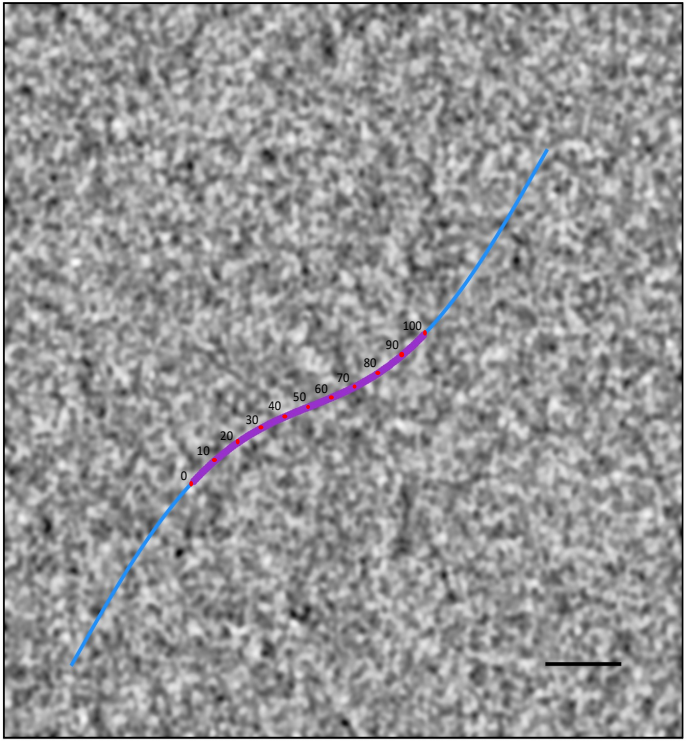


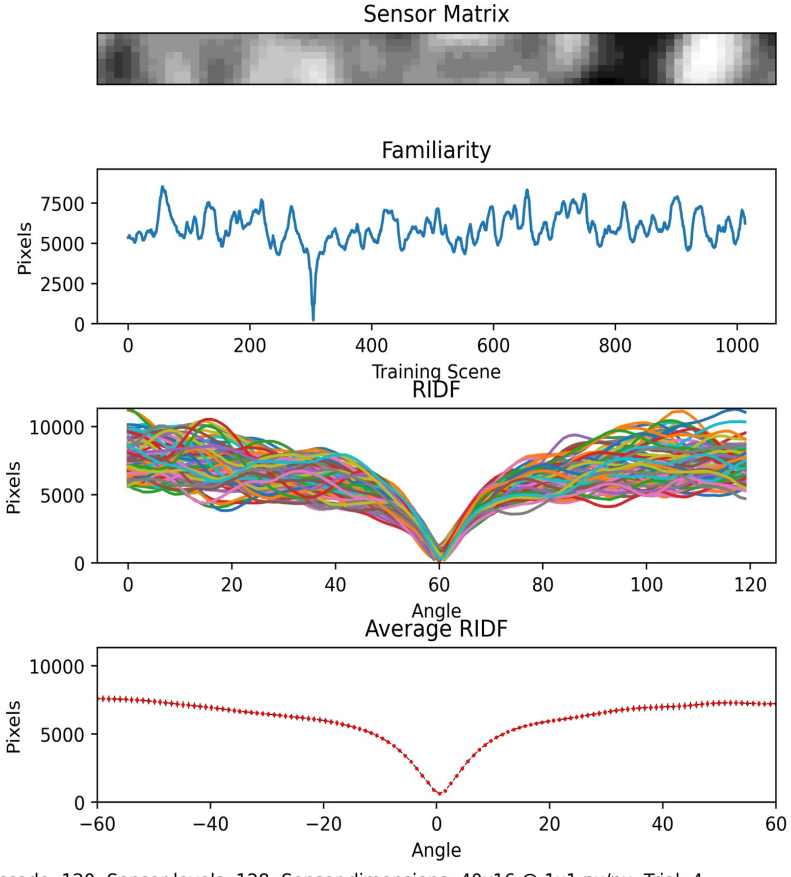




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 40.09; RMSD/dist: 0.100; TD: 5146; p90: 22; p50: 10; complete: 0

100%

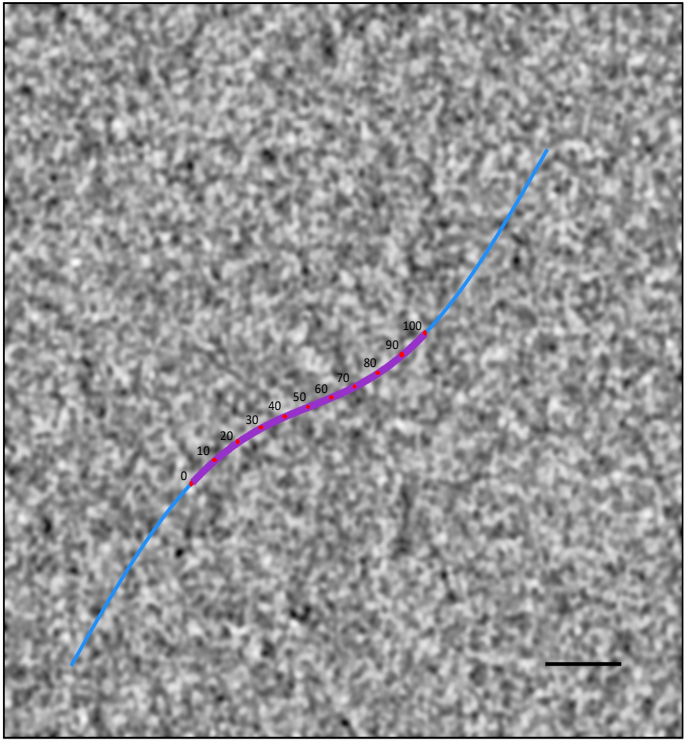


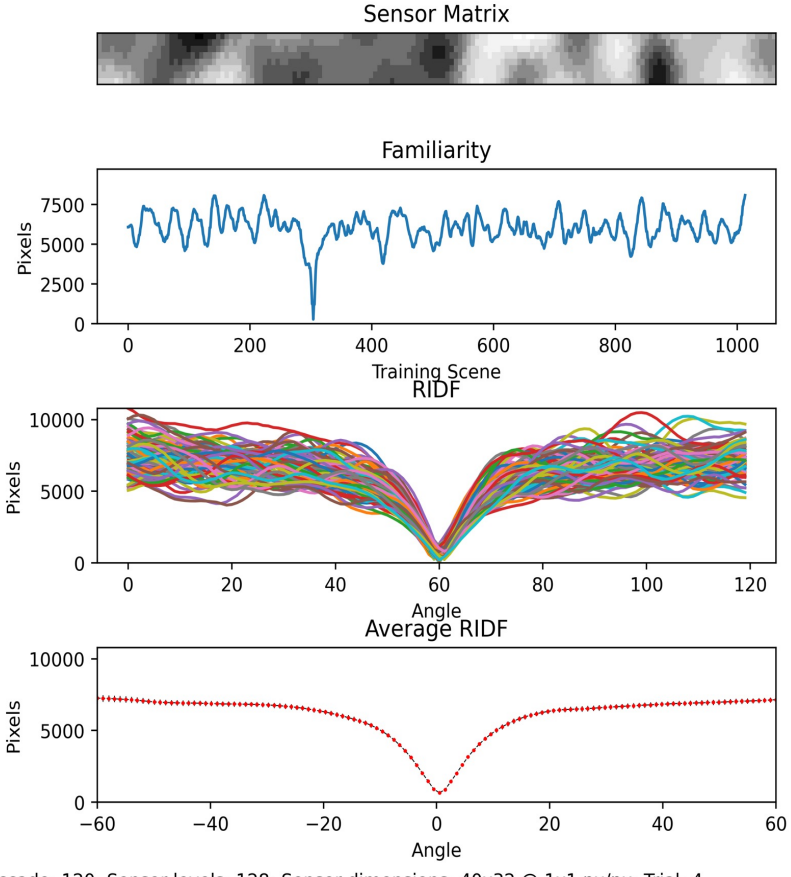




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 43.98; RMSD/dist: 0.110; TD: 5246; p90: 28; p50: 12; complete: 0

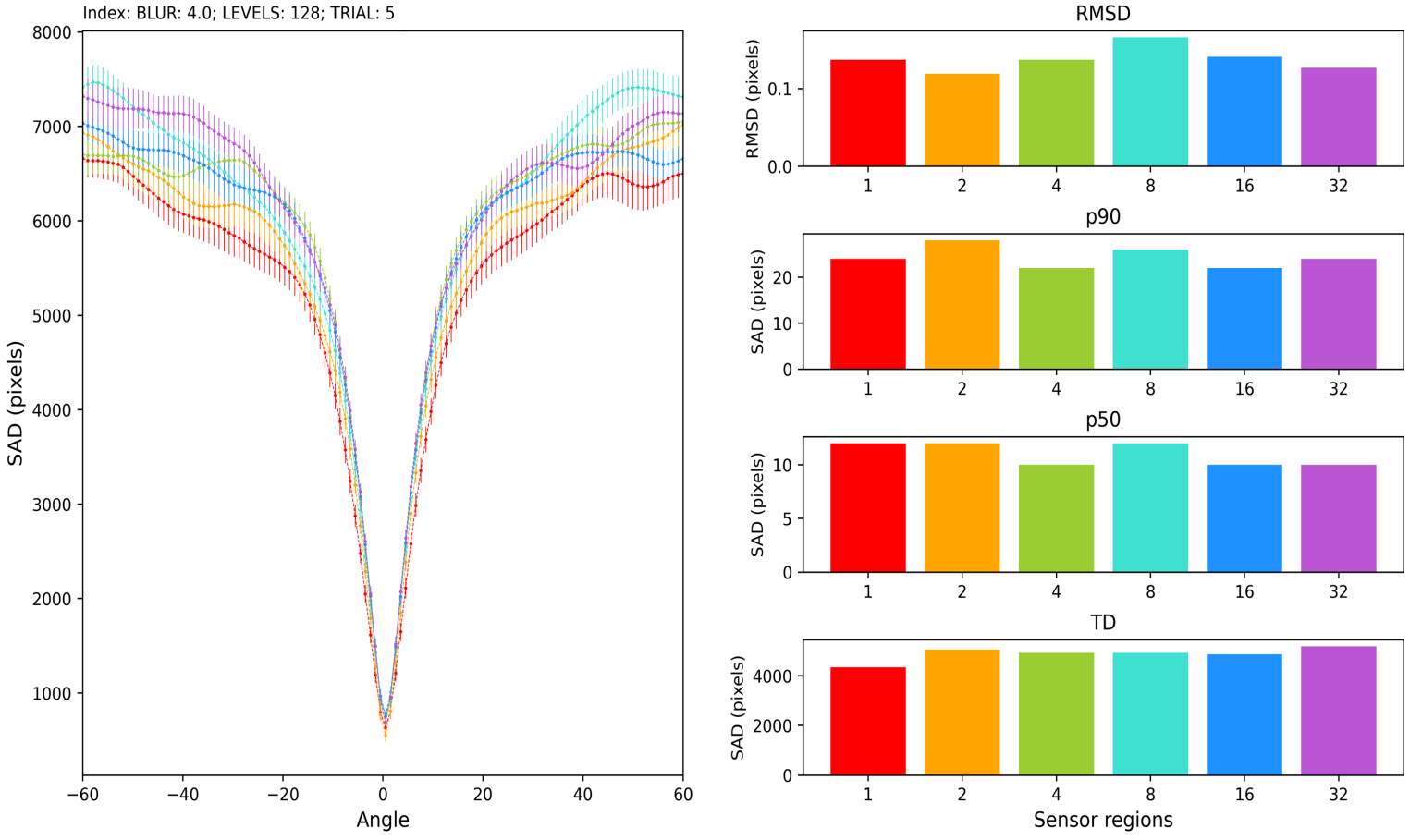
100%



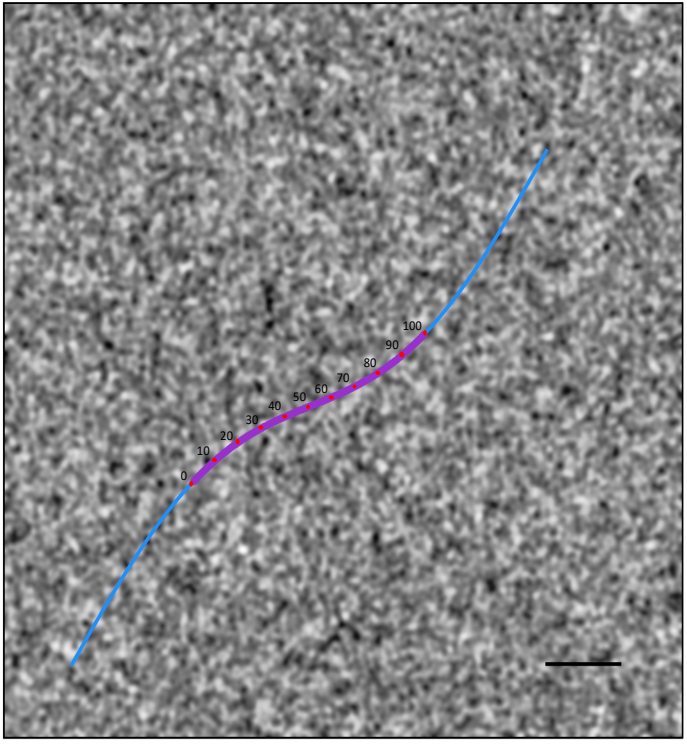



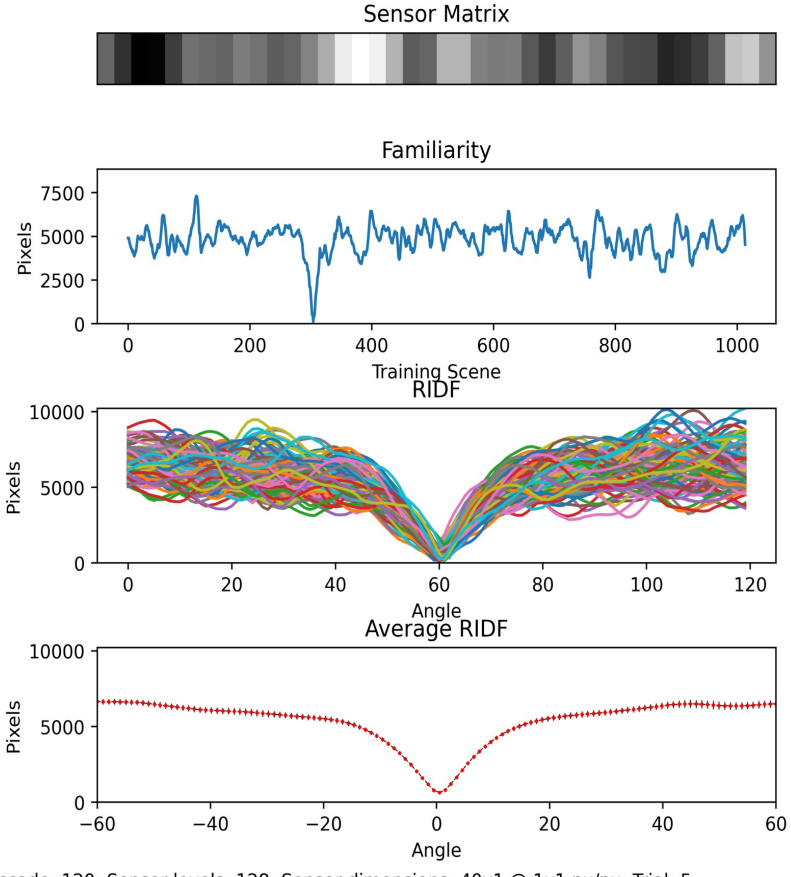

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 40.49; RMSD/dist: 0.101; TD: 5115; p90: 22; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 128; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

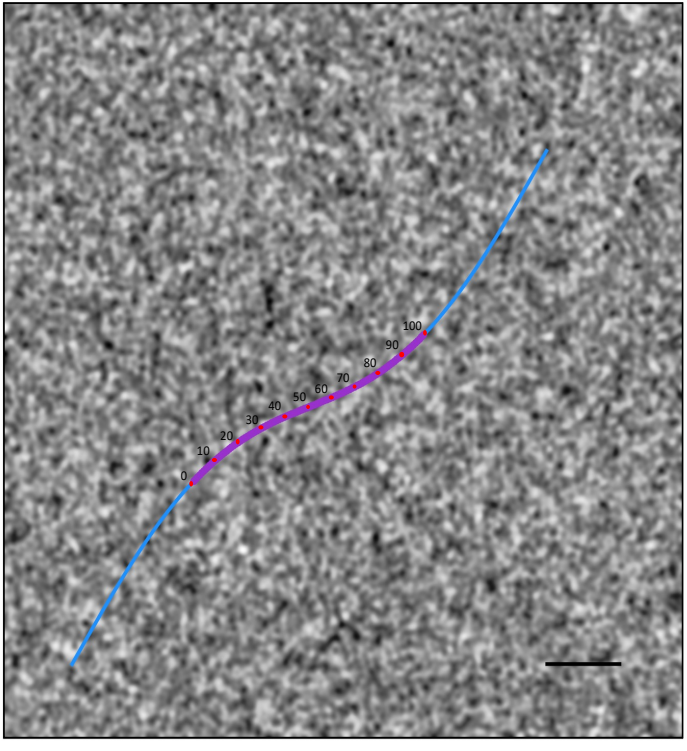


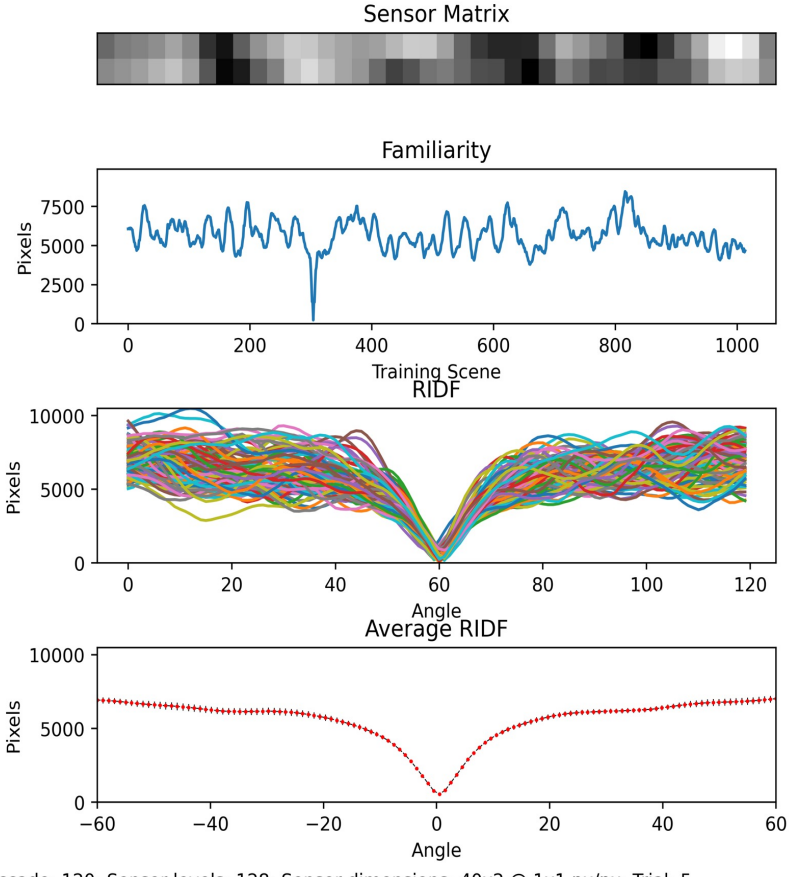




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 54.85; RMSD/dist: 0.137; TD: 4345; p90: 24; p50: 12; complete: 0

100%

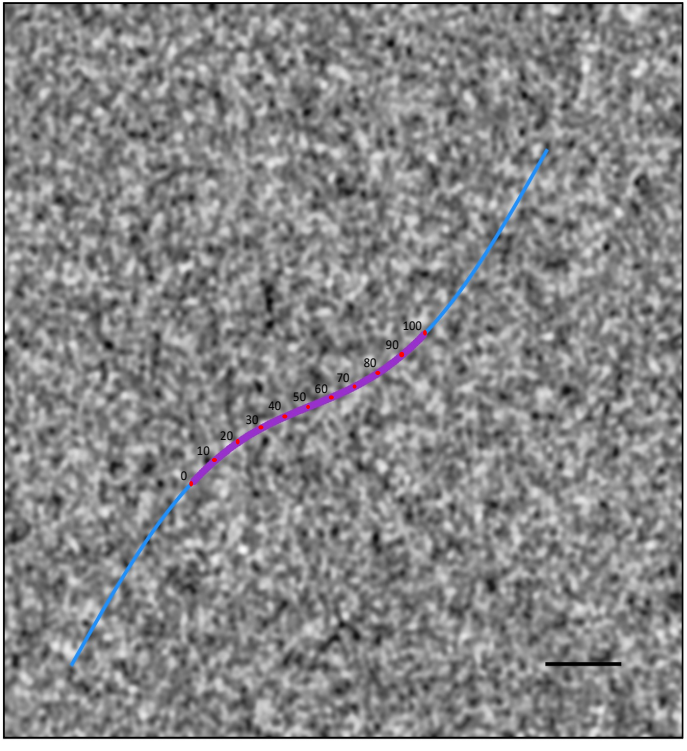


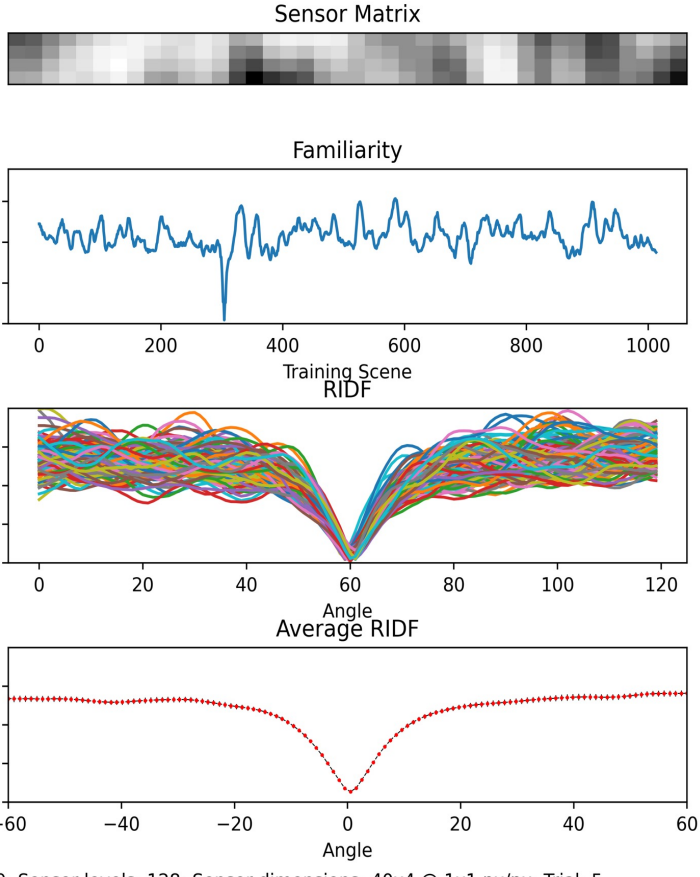




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 47.46; RMSD/dist: 0.119; TD: 5053; p90: 28; p50: 12; complete: 0

100%

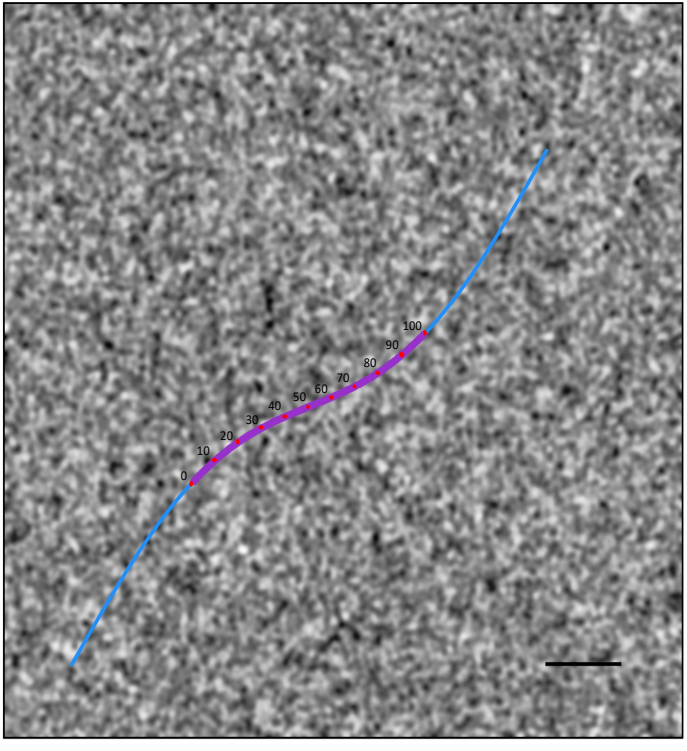


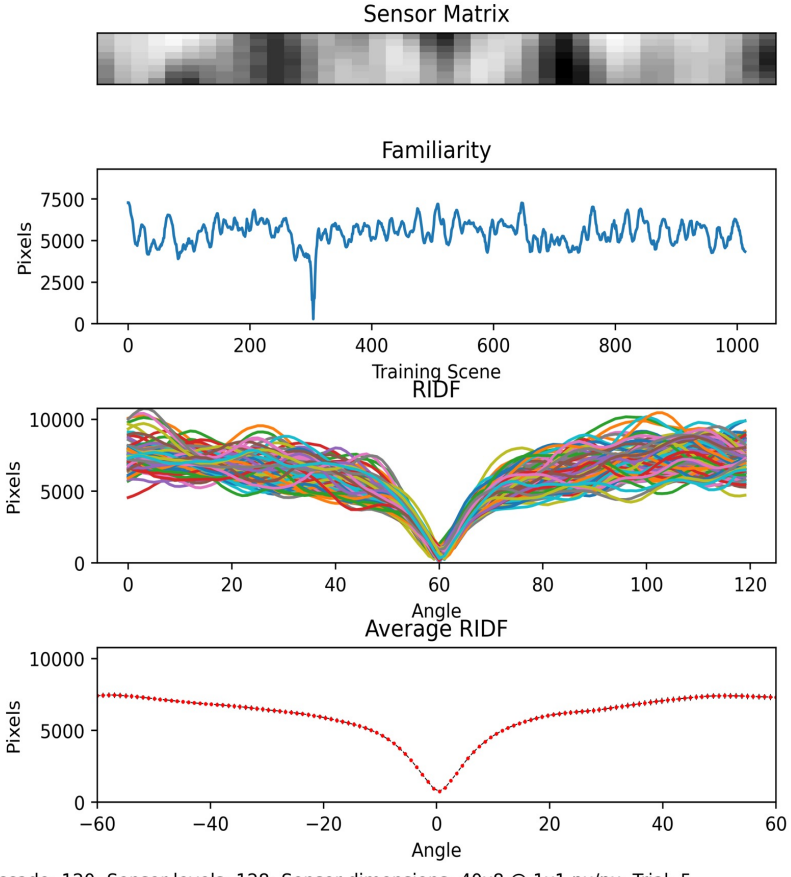




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 54.72; RMSD/dist: 0.137; TD: 4923; p90: 22; p50: 10; complete: 0

100%

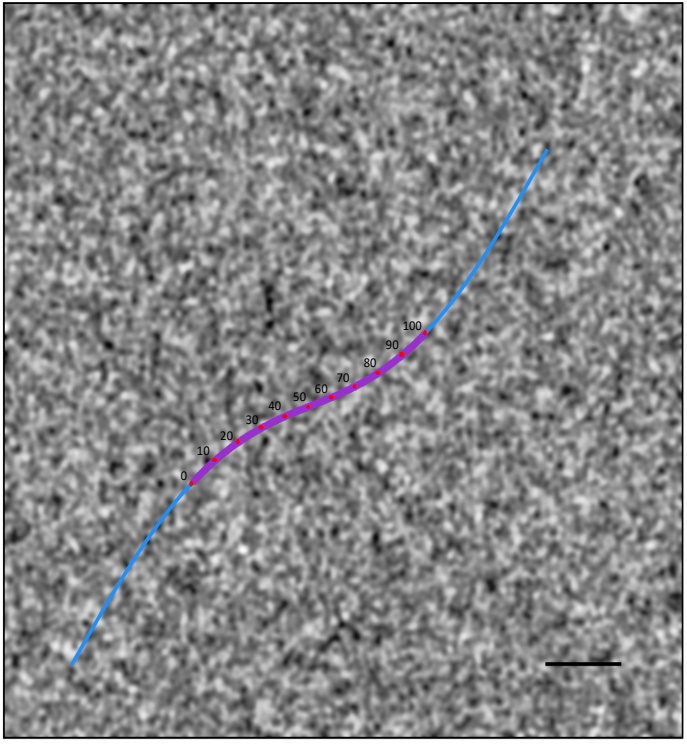


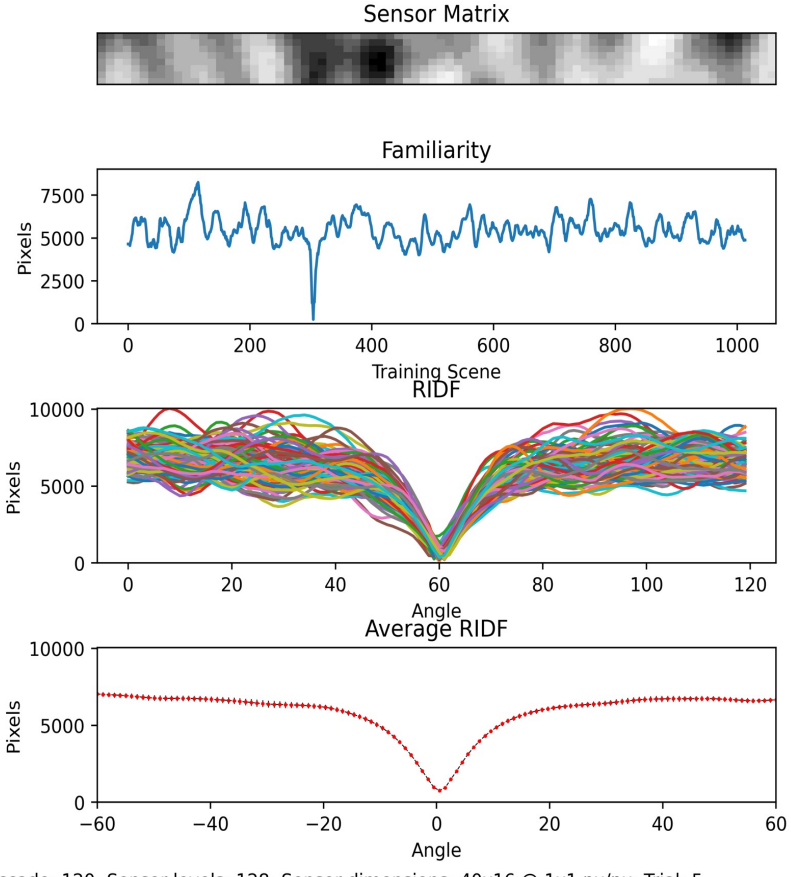




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 66.23; RMSD/dist: 0.166; TD: 4927; p90: 26; p50: 12; complete: 0

100%

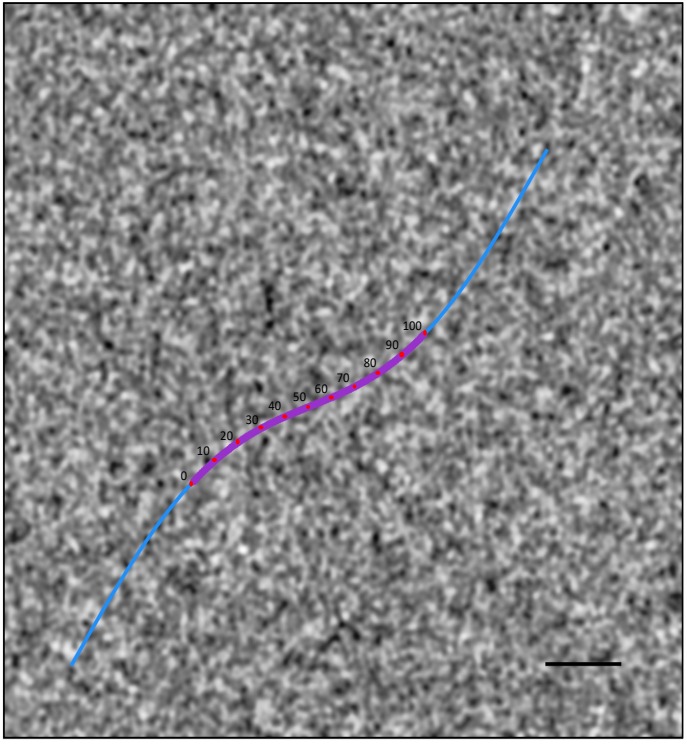


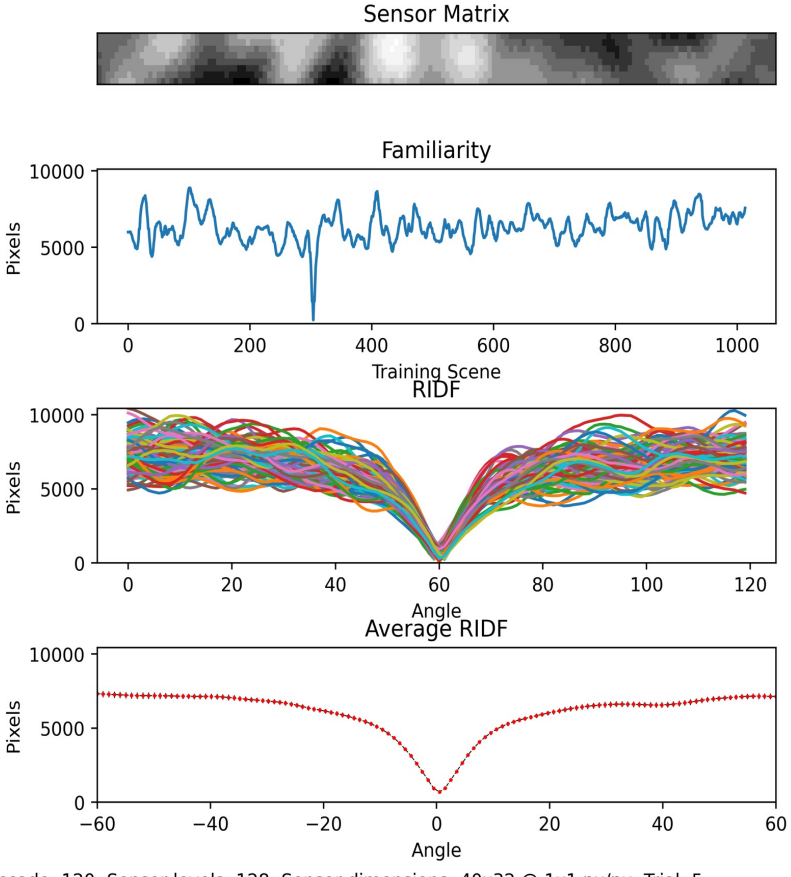




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 56.29; RMSD/dist: 0.141; TD: 4869; p90: 22; p50: 10; complete: 0

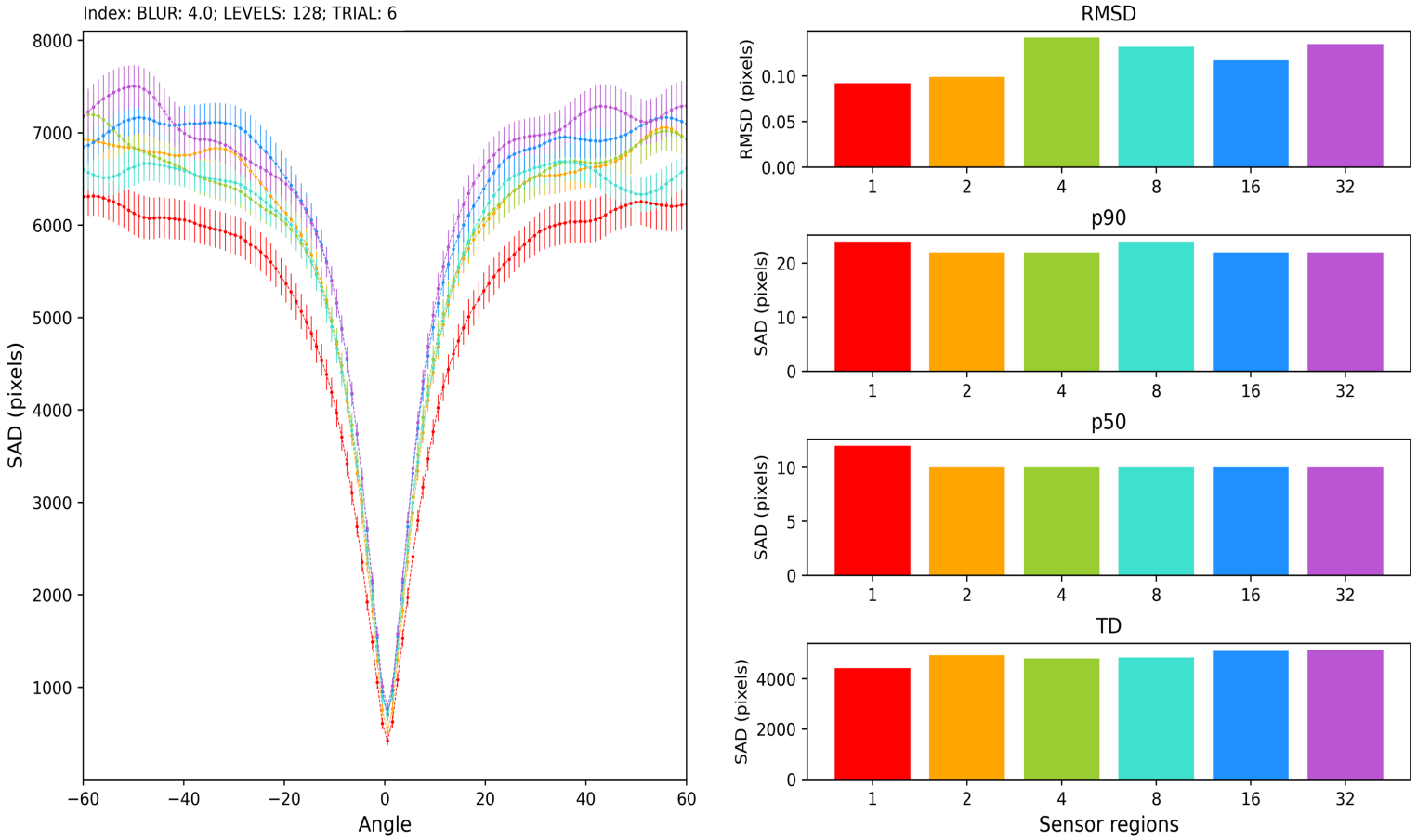
100%



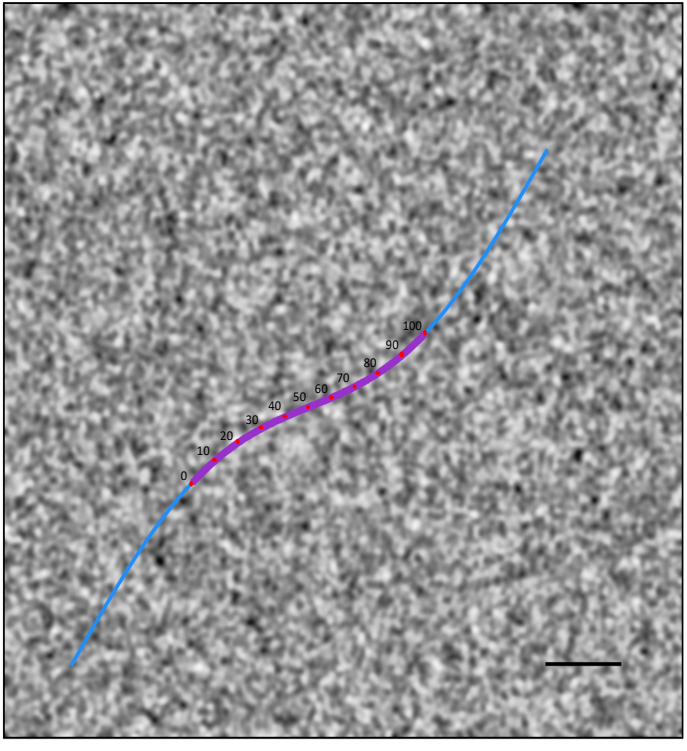



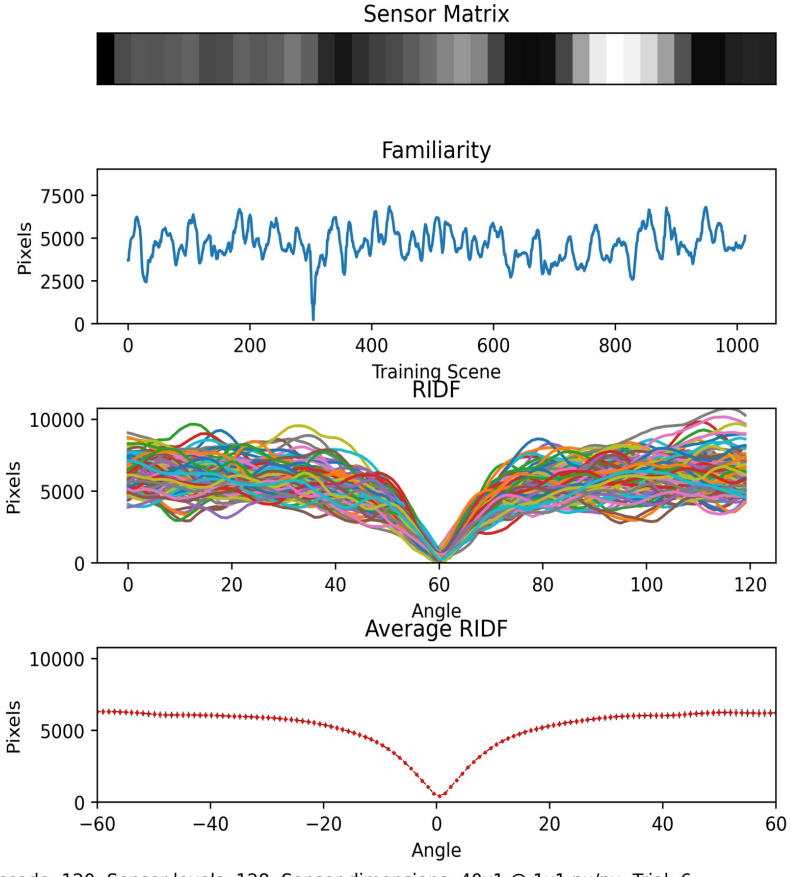

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 50.79; RMSD/dist: 0.127; TD: 5187; p90: 24; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 128; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

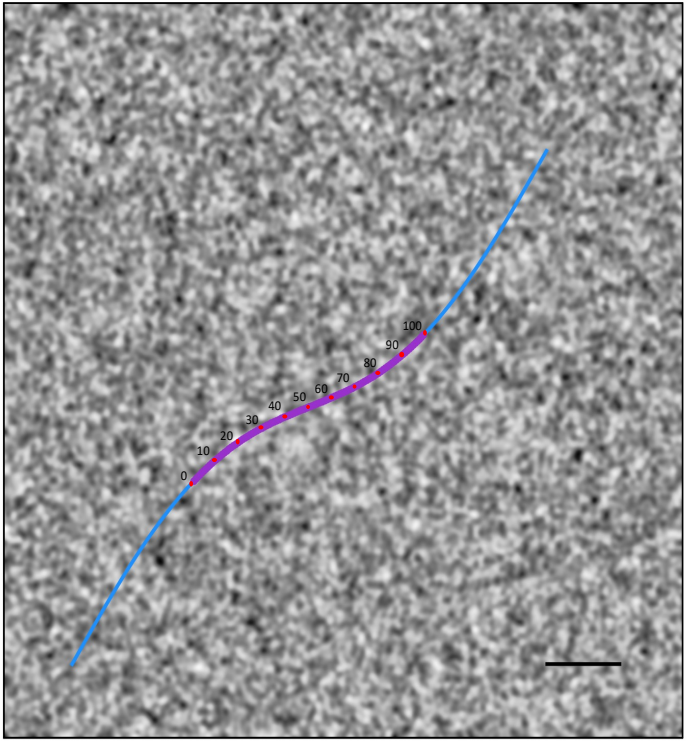


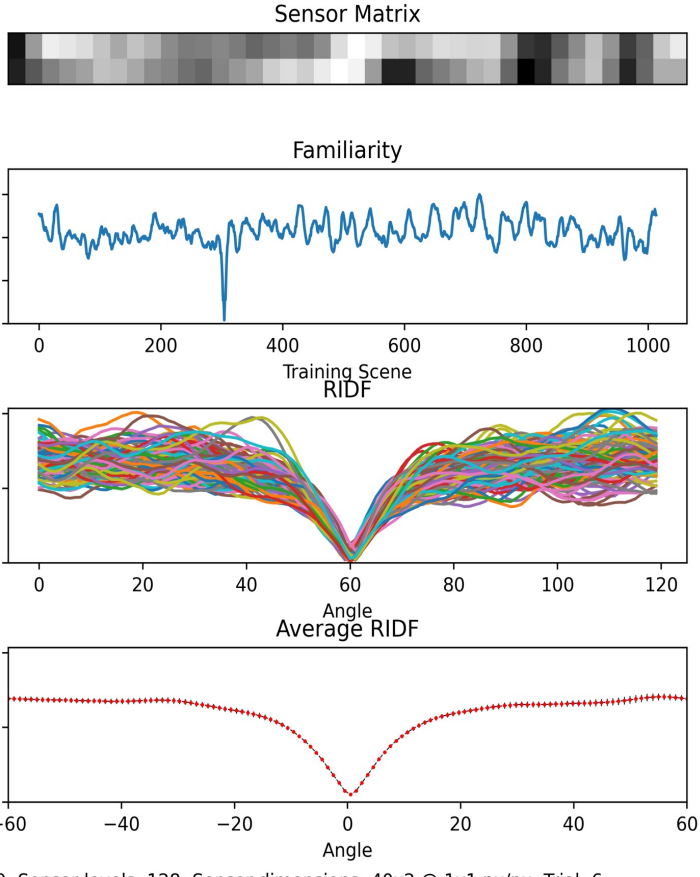




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 36.64; RMSD/dist: 0.092; TD: 4415; p90: 24; p50: 12; complete: 0

100%

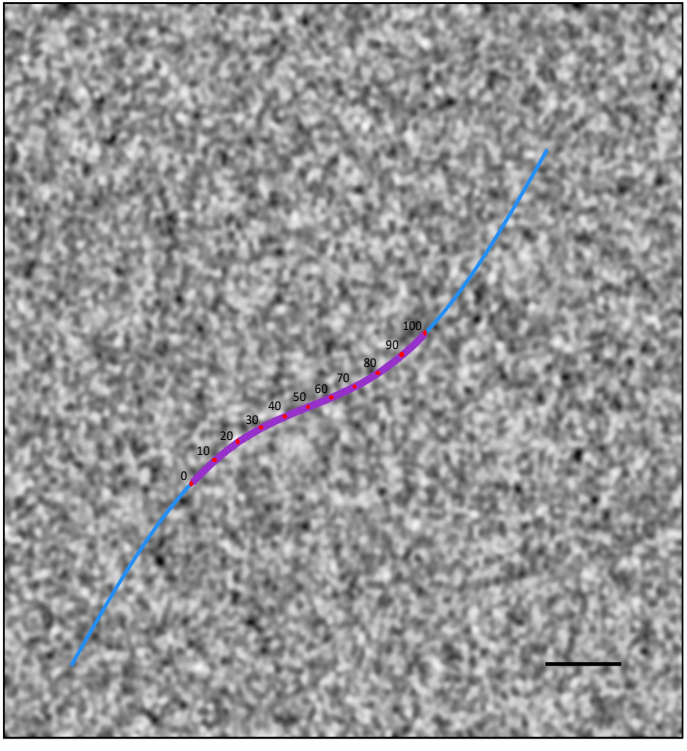


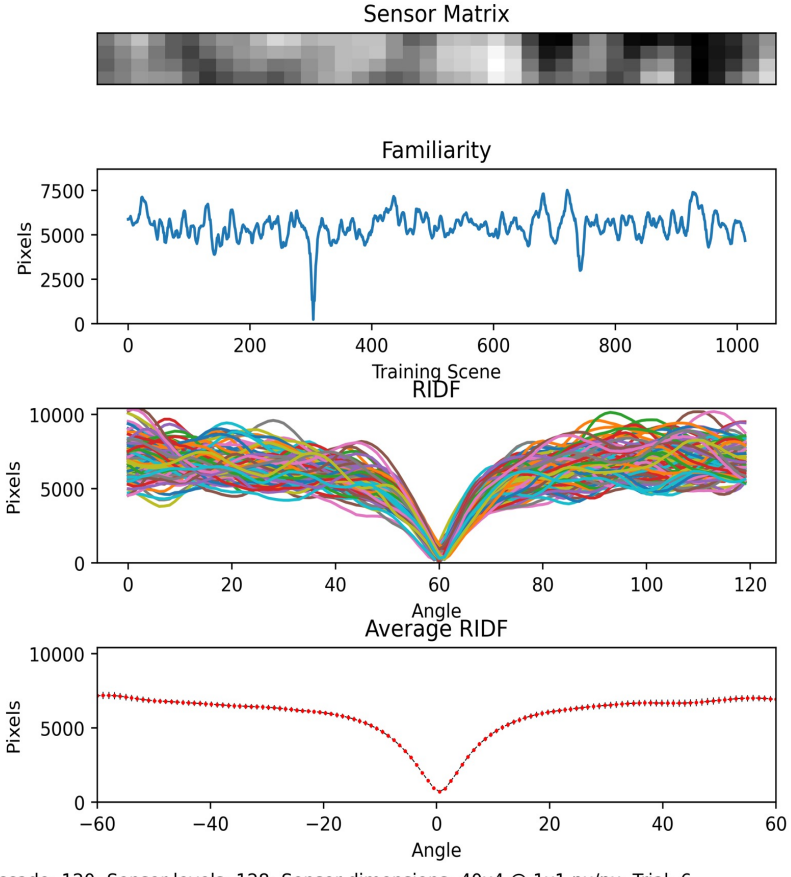




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 39.46; RMSD/dist: 0.099; TD: 4930; p90: 22; p50: 10; complete: 0

100%

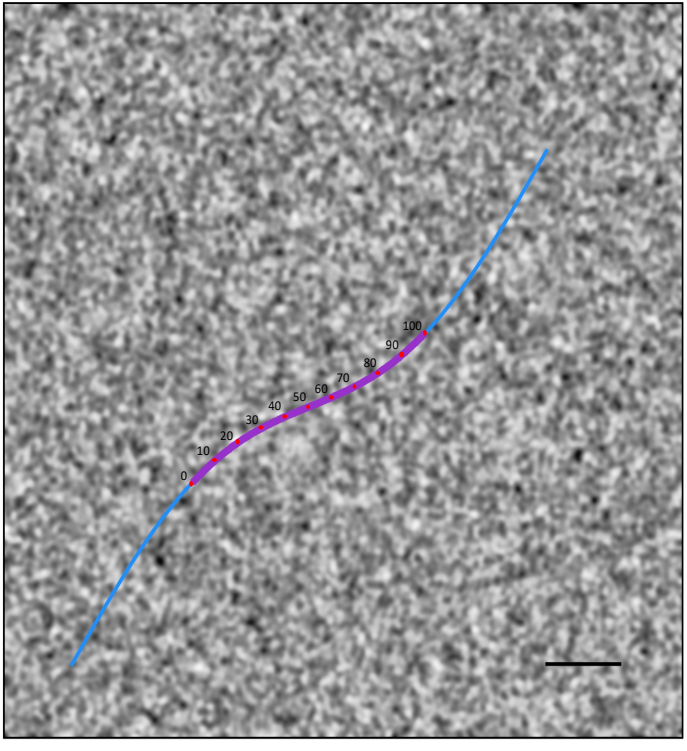


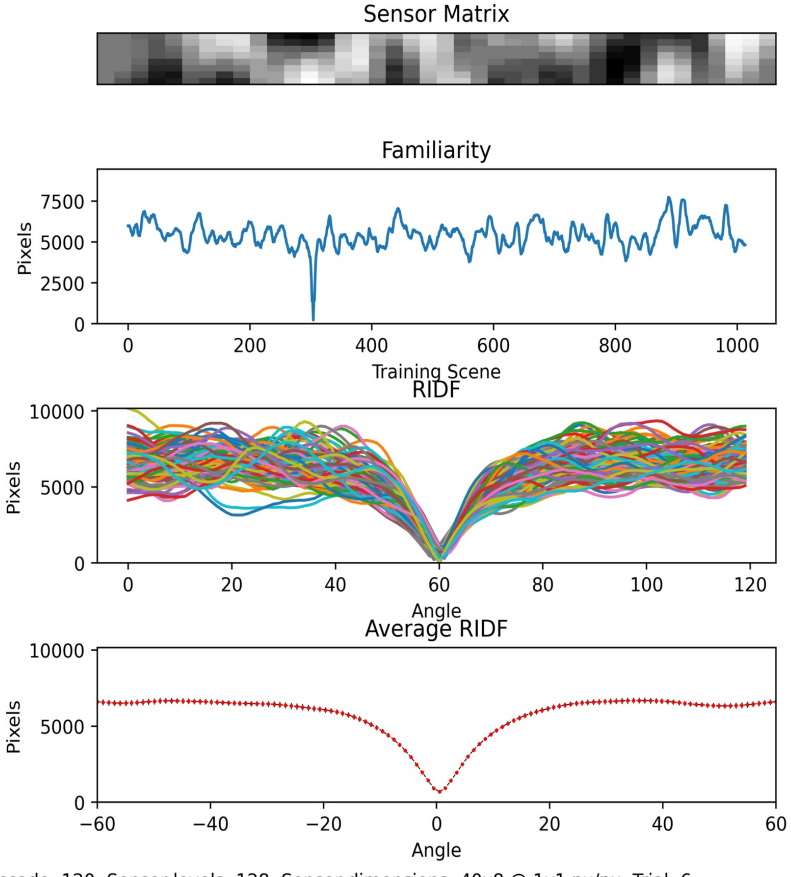




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 56.61; RMSD/dist: 0.142; TD: 4801; p90: 22; p50: 10; complete: 0

100%

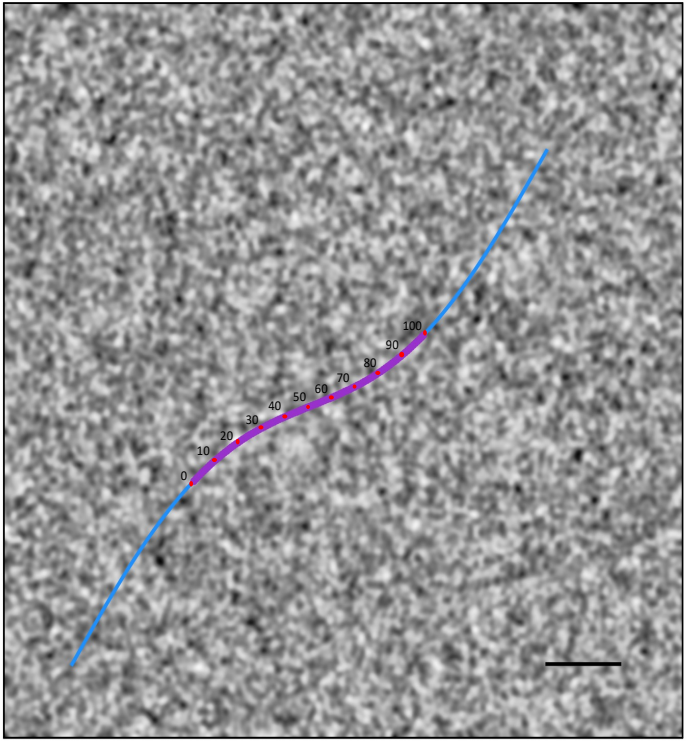


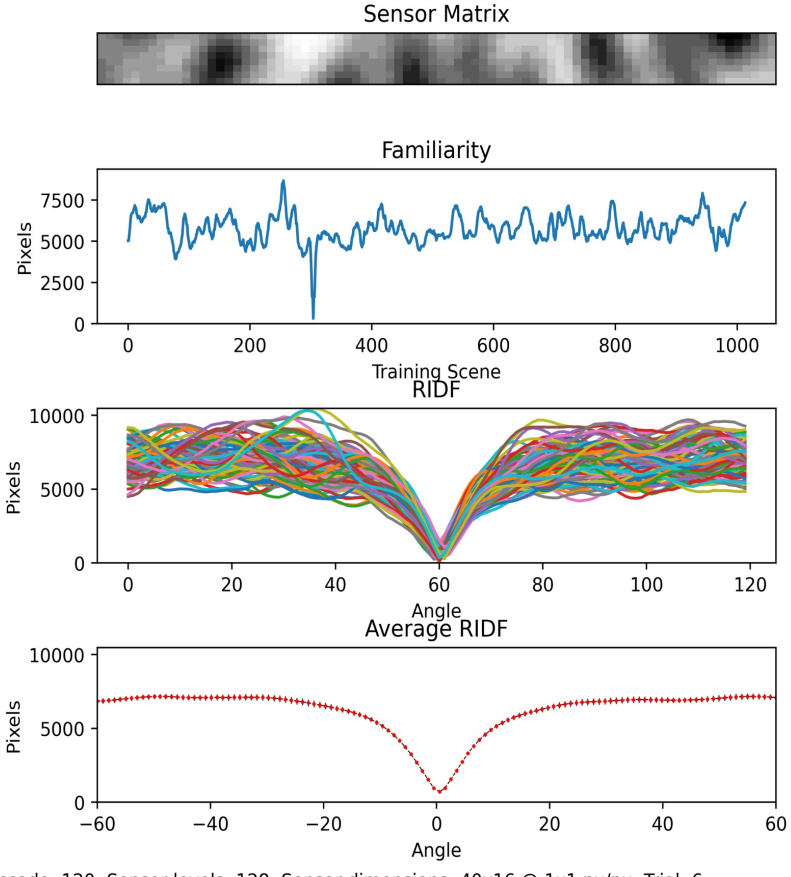




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 52.96; RMSD/dist: 0.132; TD: 4840; p90: 24; p50: 10; complete: 0

100%

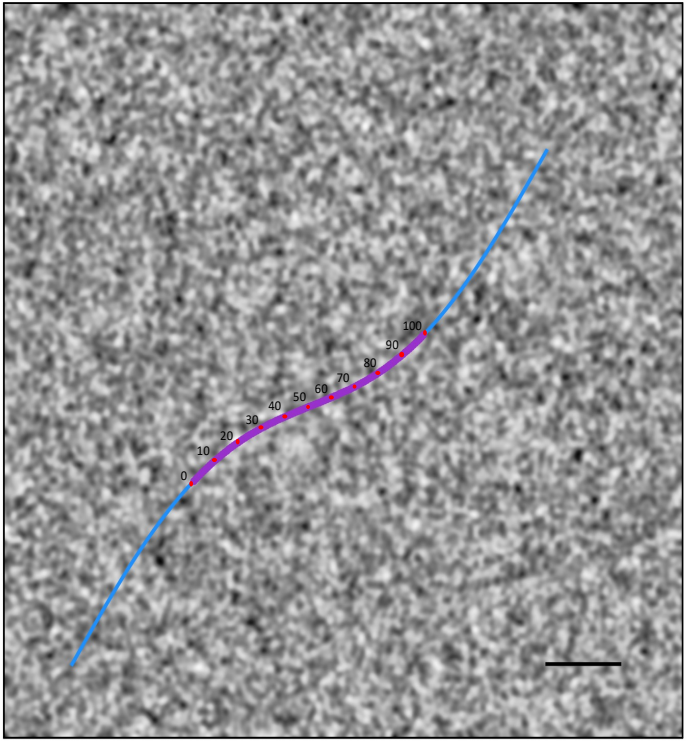


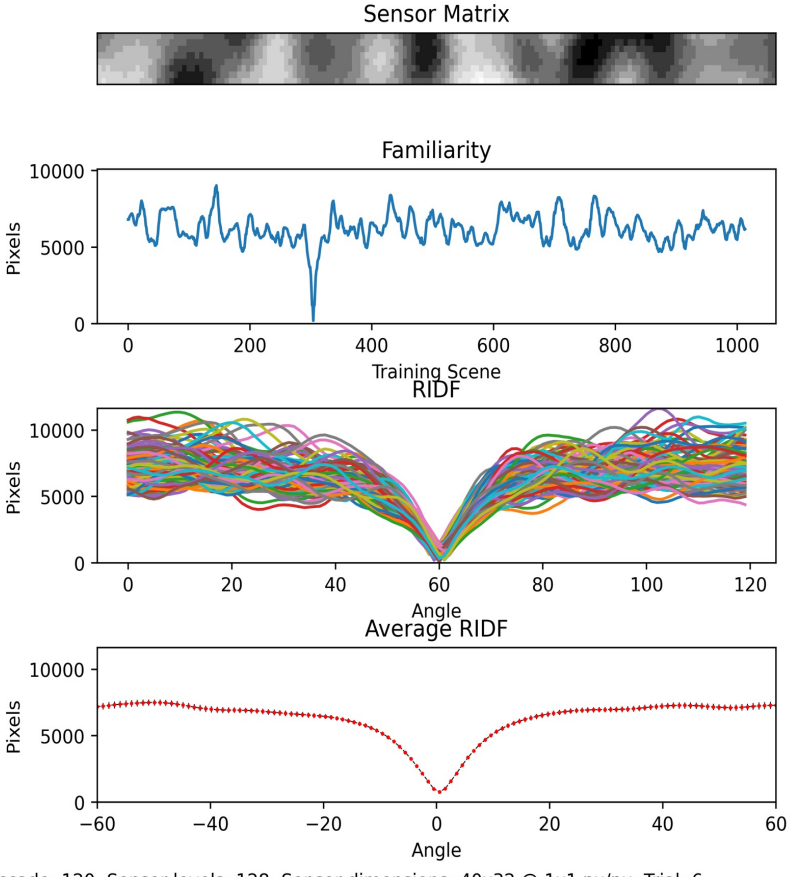




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 46.93; RMSD/dist: 0.117; TD: 5106; p90: 22; p50: 10; complete: 0

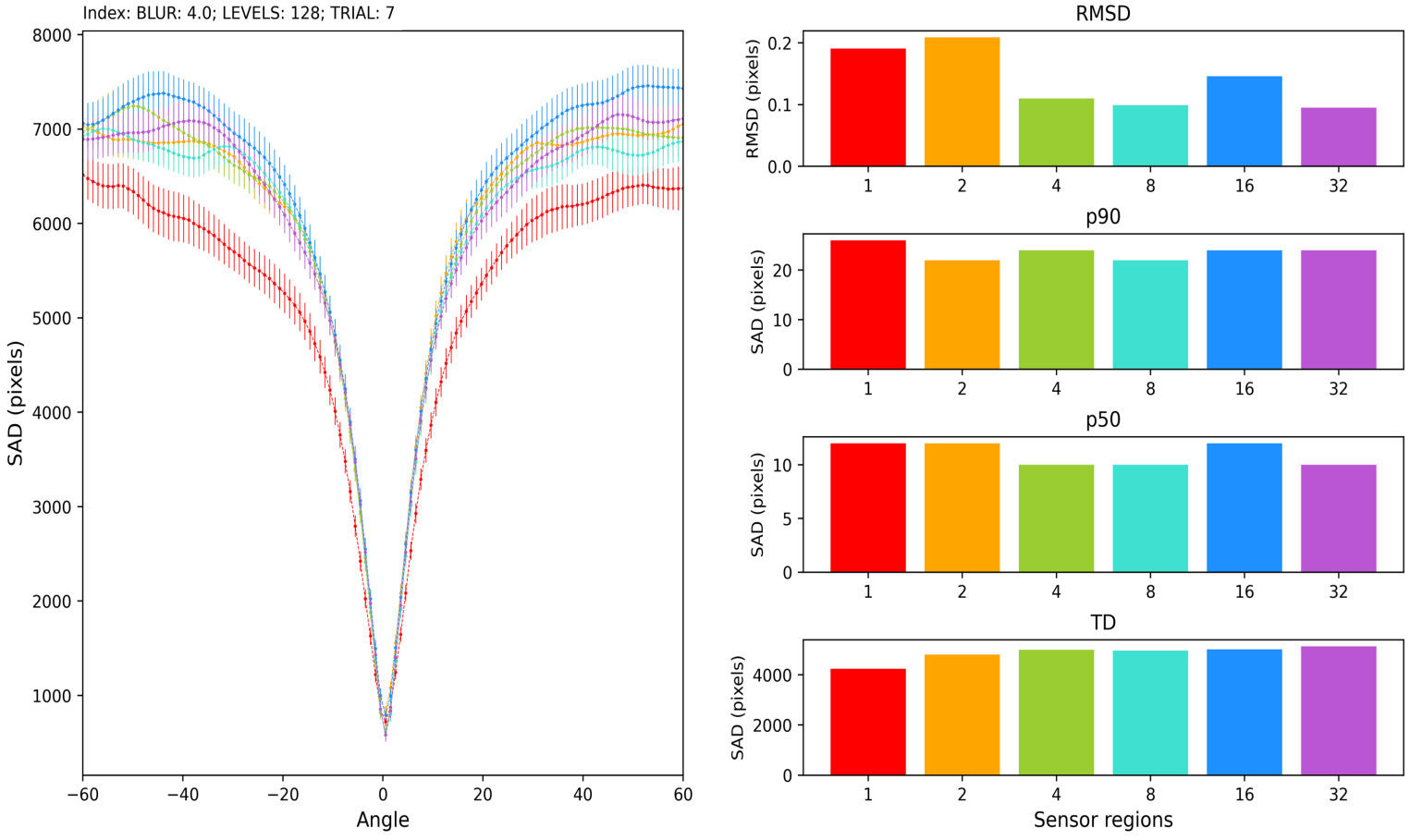
100%



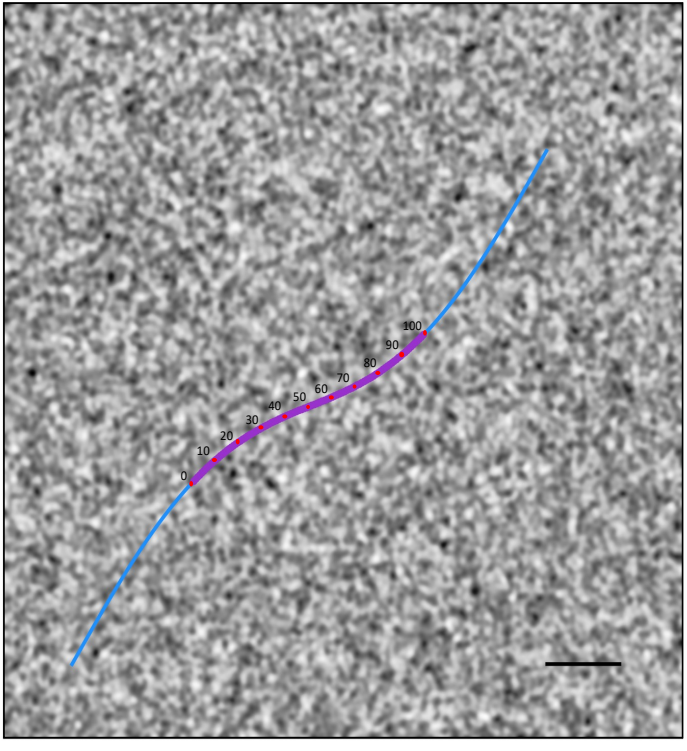



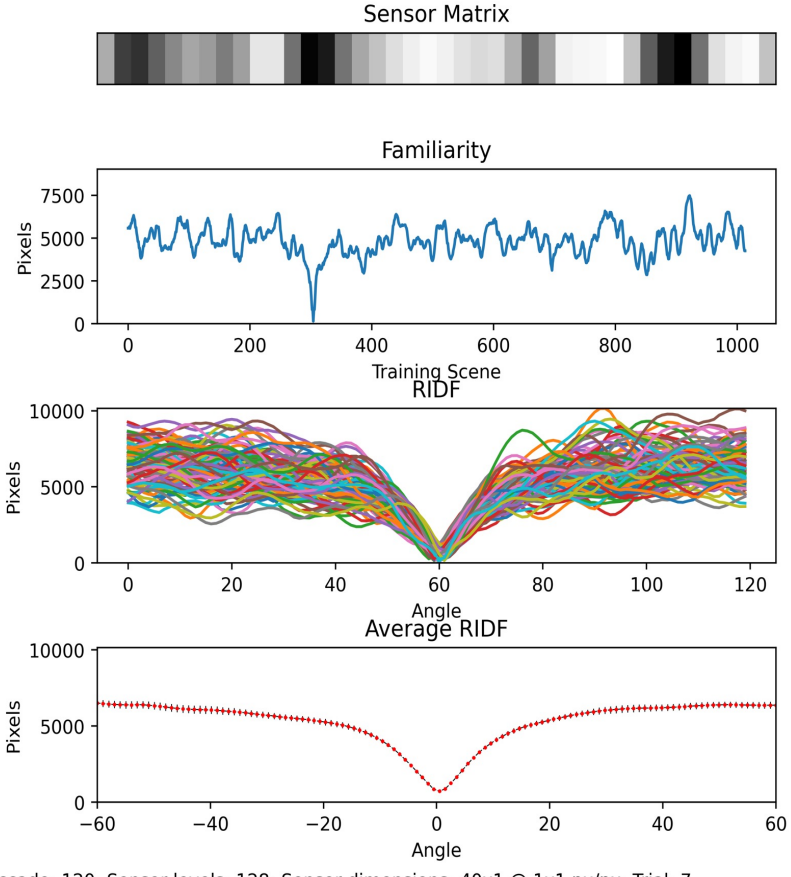

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 54.08; RMSD/dist: 0.135; TD: 5145; p90: 22; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 128; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

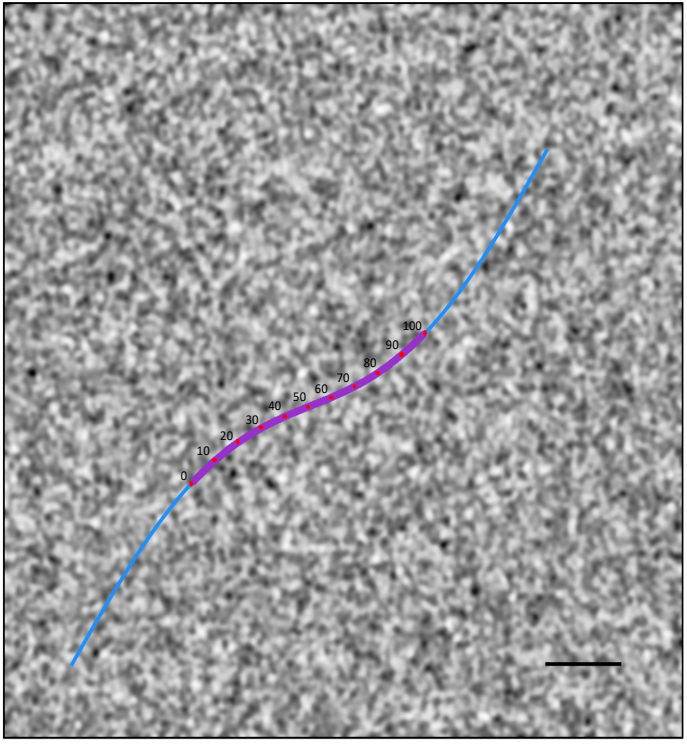


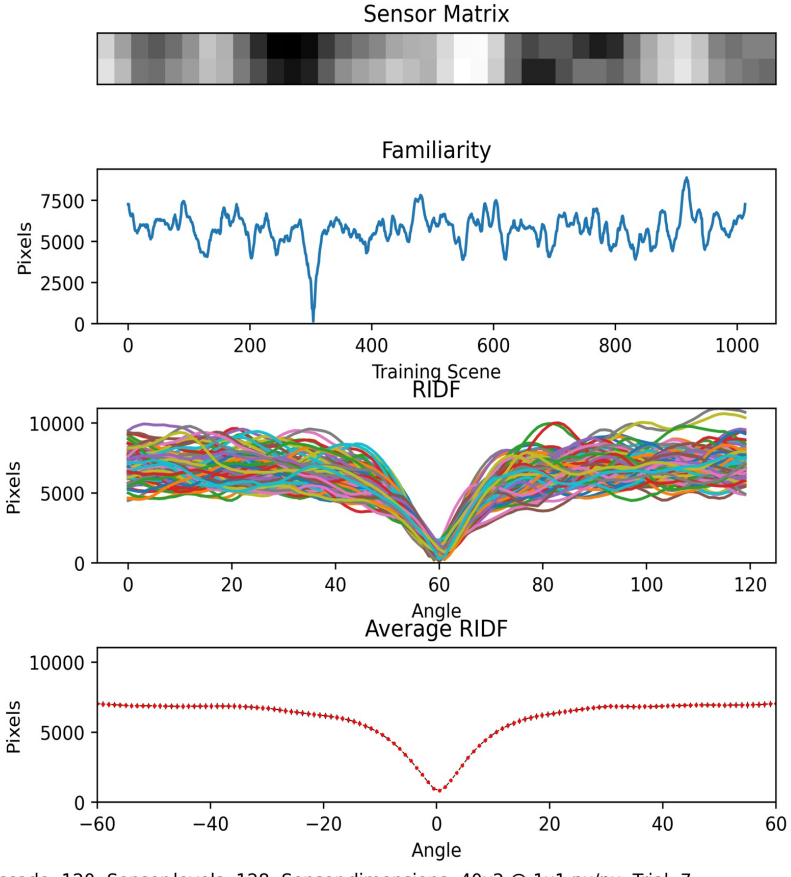




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 76.38; RMSD/dist: 0.191; TD: 4240; p90: 26; p50: 12; complete: 0

100%

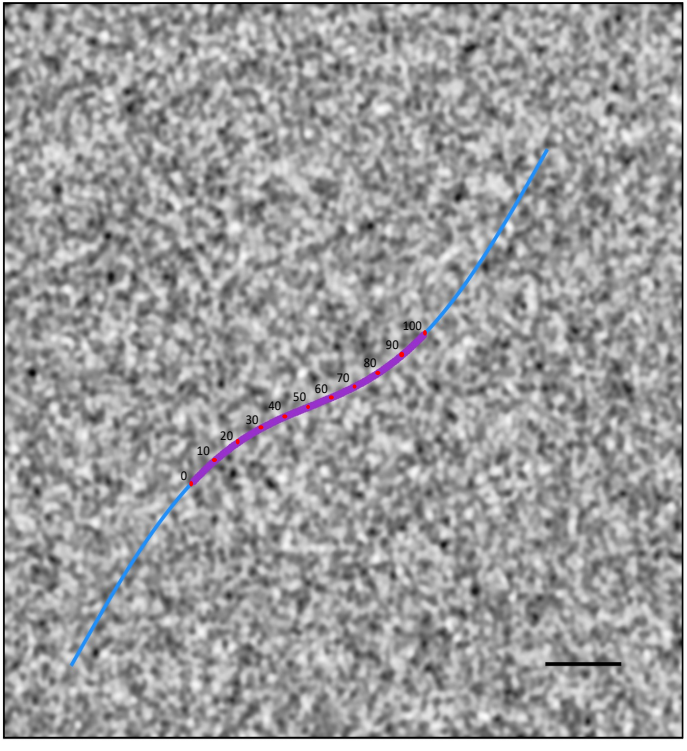


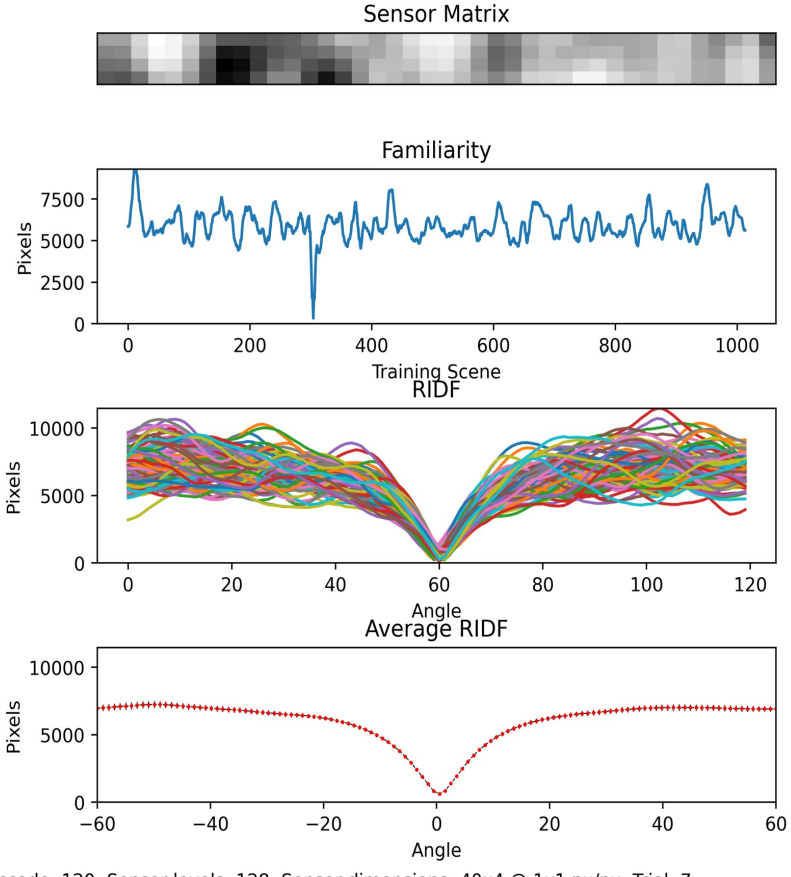




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 83.43; RMSD/dist: 0.209; TD: 4809; p90: 22; p50: 12; complete: 0

100%

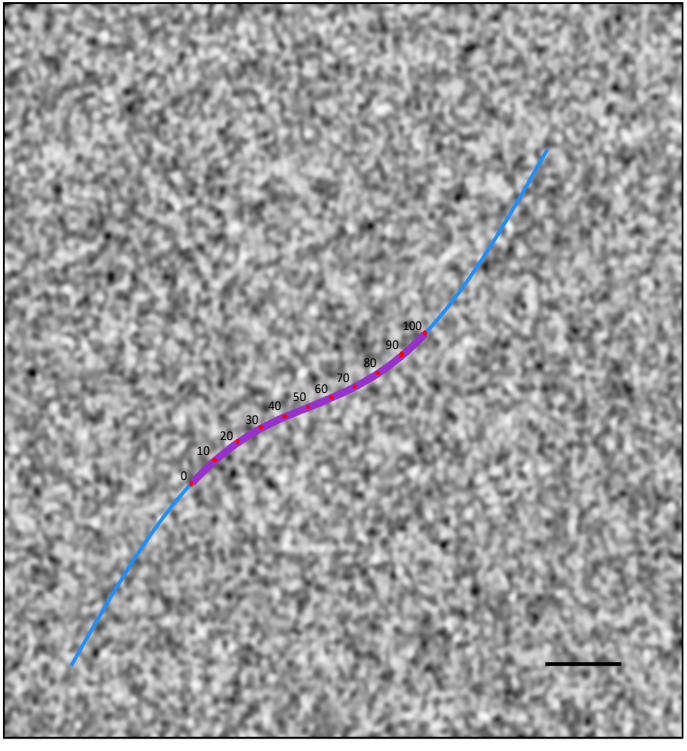


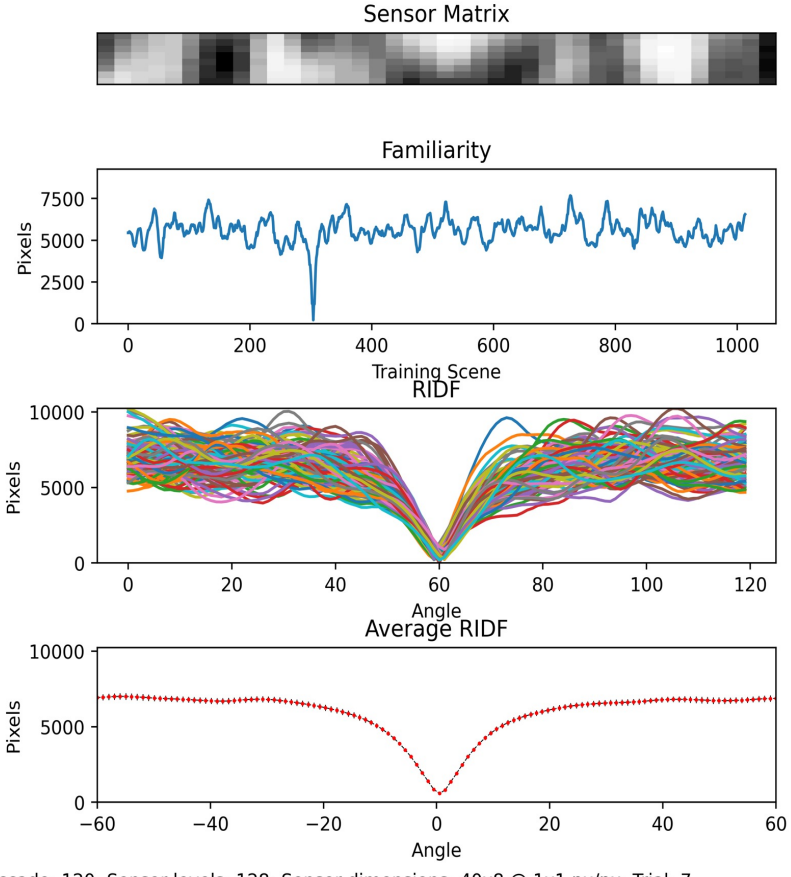




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 43.97; RMSD/dist: 0.110; TD: 4992; p90: 24; p50: 10; complete: 0

100%

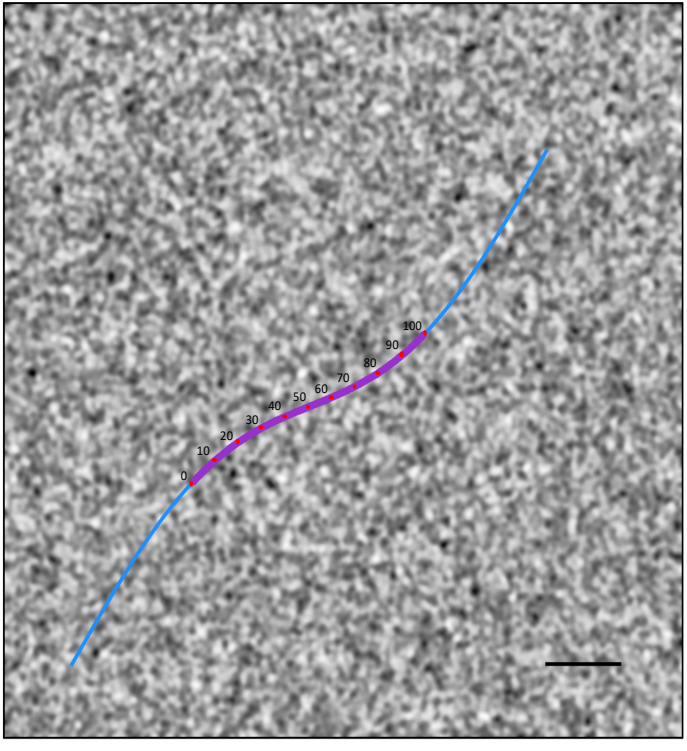


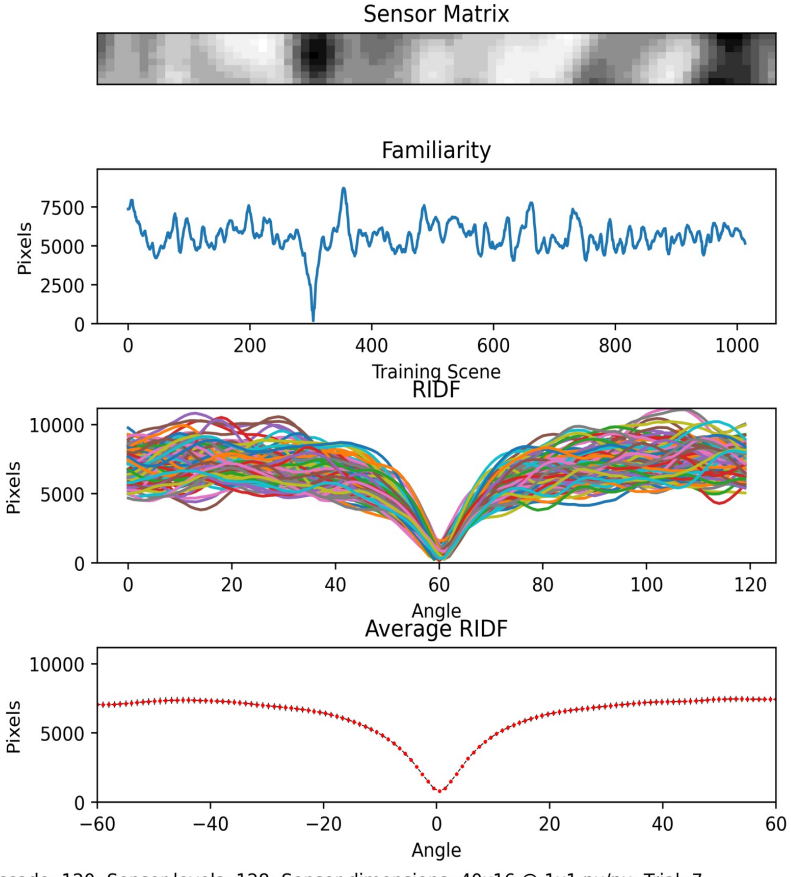




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 39.64; RMSD/dist: 0.099; TD: 4961; p90: 22; p50: 10; complete: 0

100%

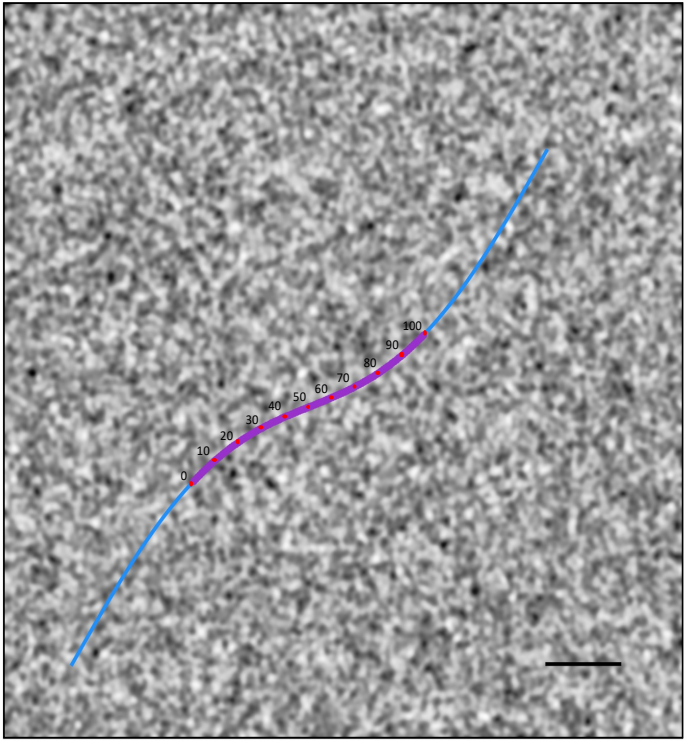


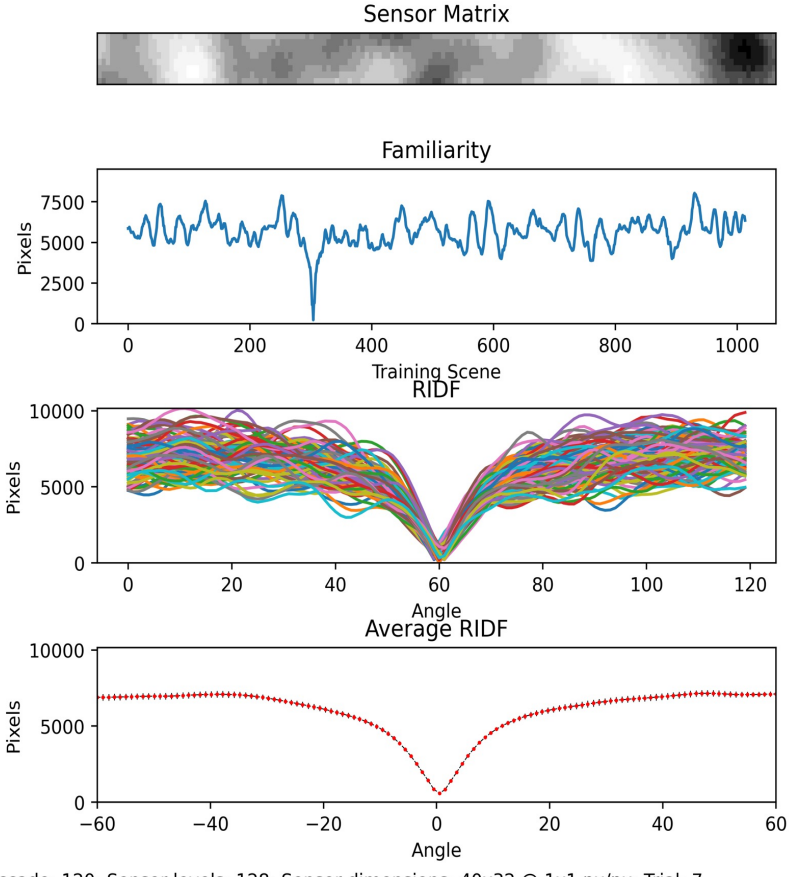




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 58.23; RMSD/dist: 0.146; TD: 5011; p90: 24; p50: 12; complete: 0

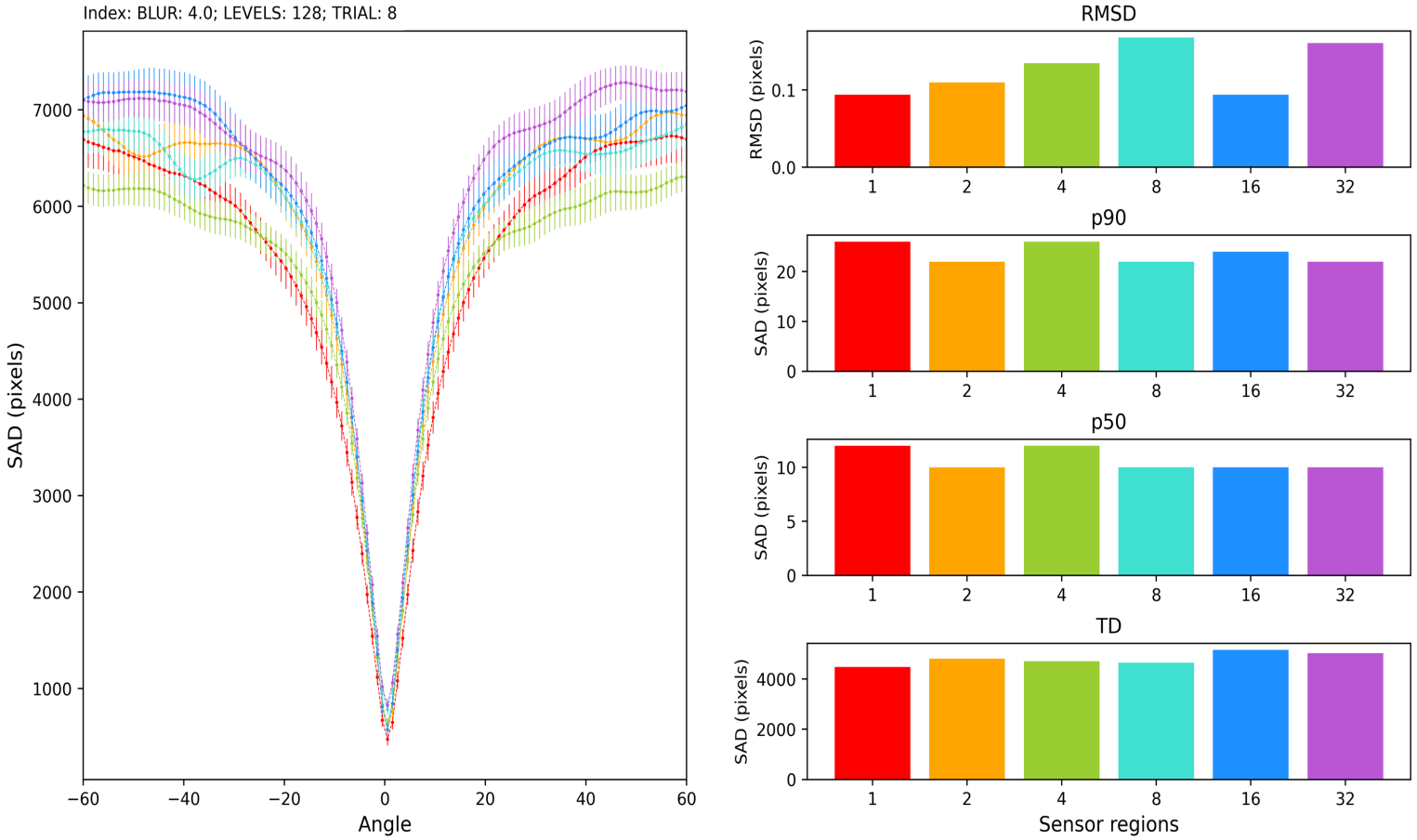
100%



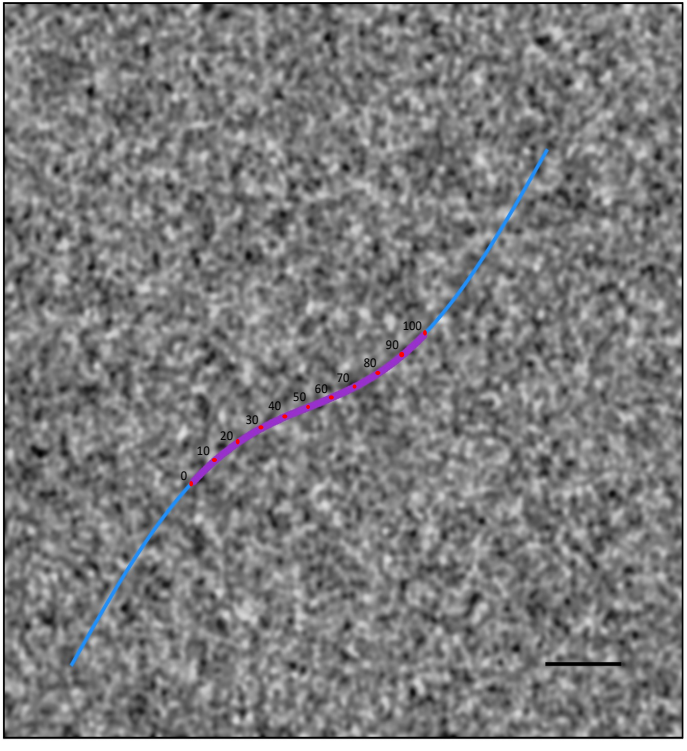



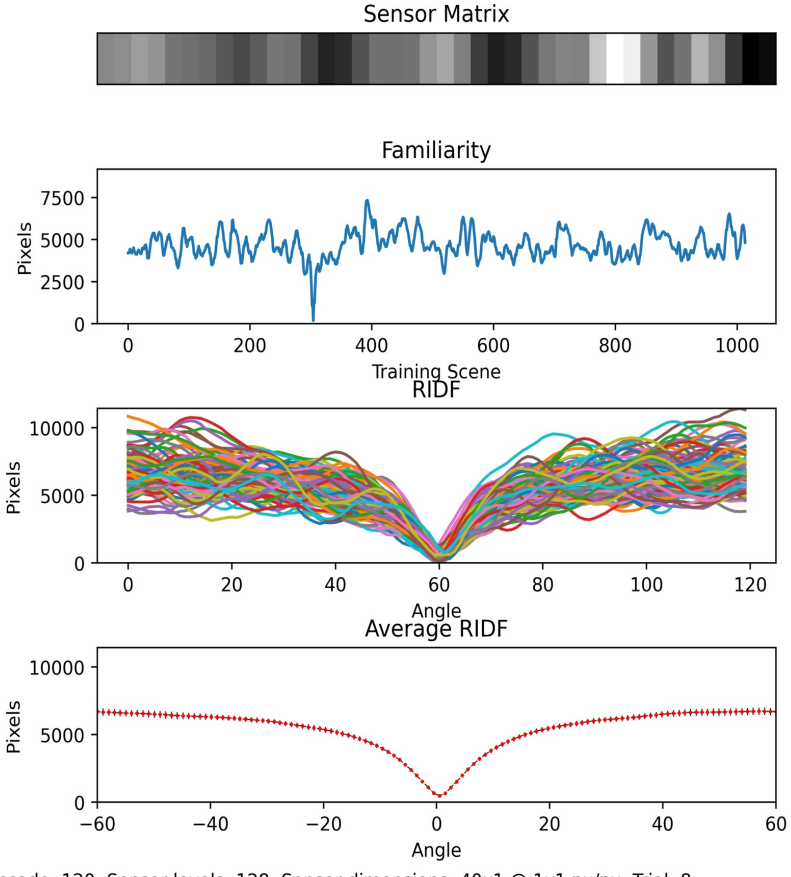

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 37.88; RMSD/dist: 0.095; TD: 5135; p90: 24; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 128; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

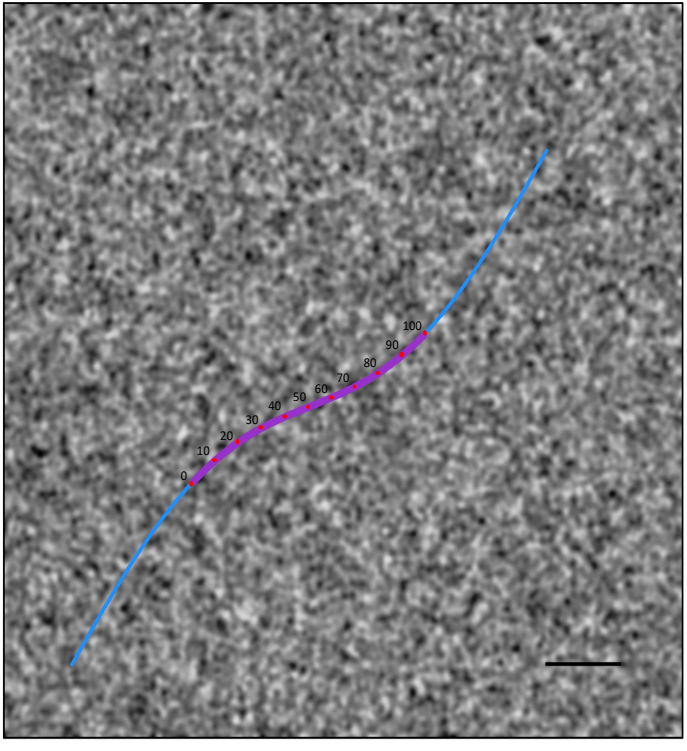


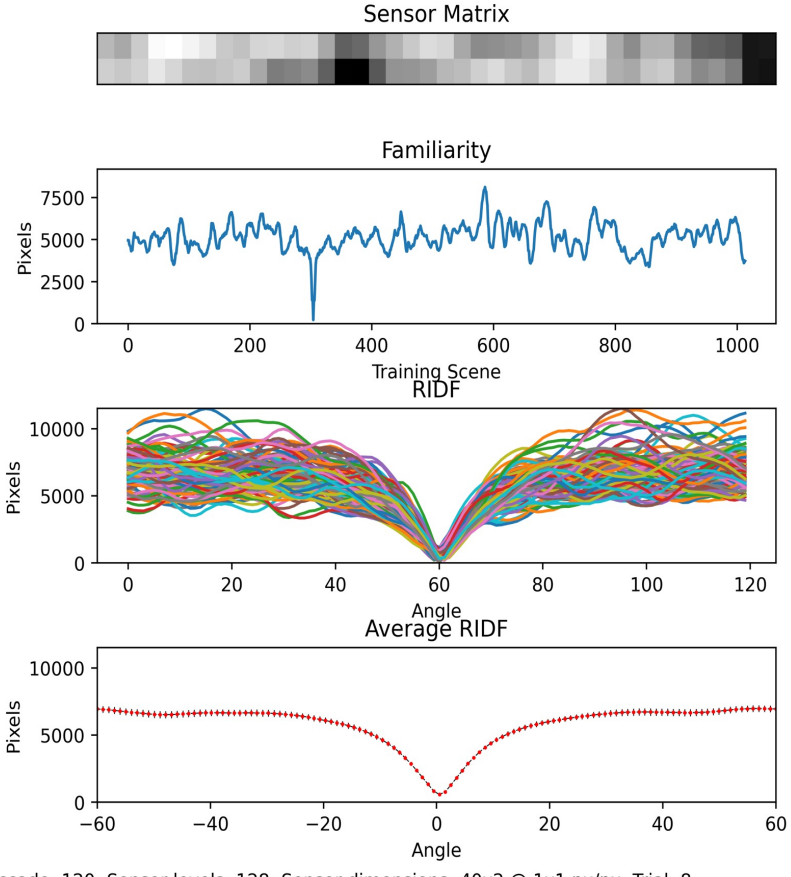




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 37.78; RMSD/dist: 0.094; TD: 4480; p90: 26; p50: 12; complete: 0

100%

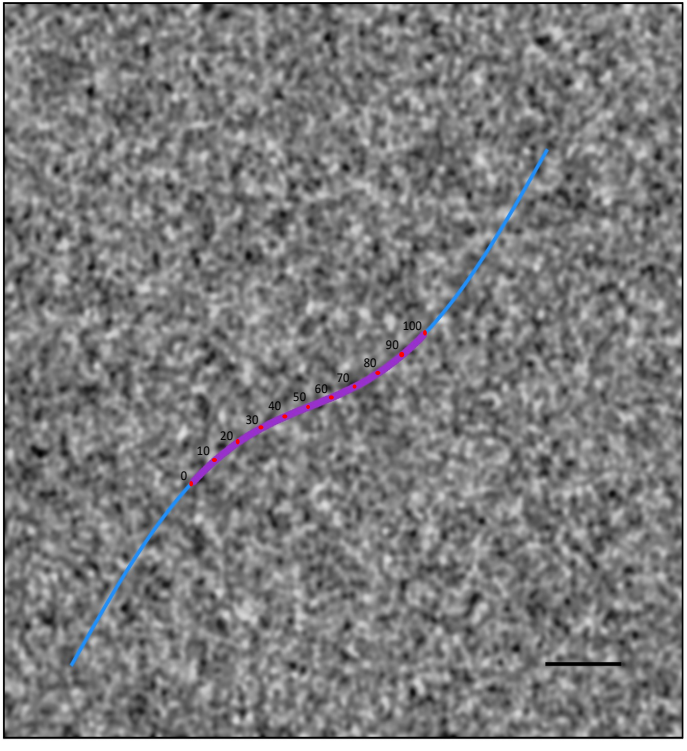


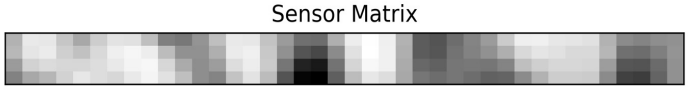



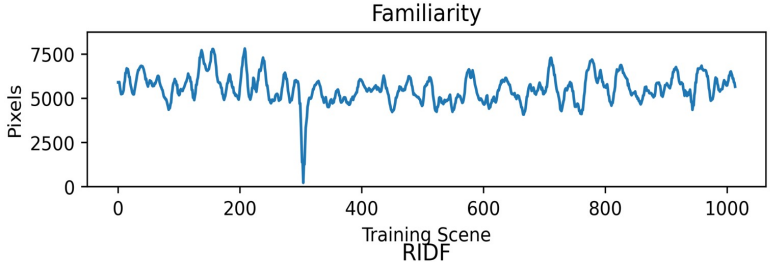

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

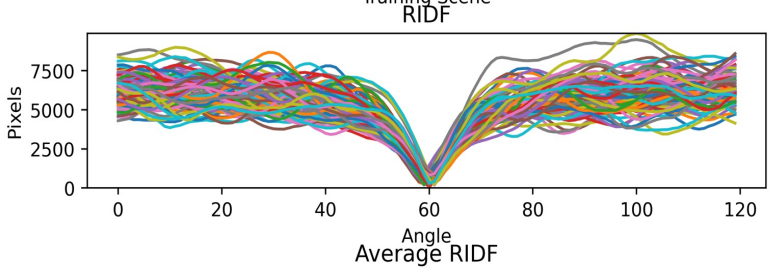
Navigation stats: RMSD error: 44.11; RMSD/dist: 0.110; TD: 4817; p90: 22; p50: 10; complete: 0

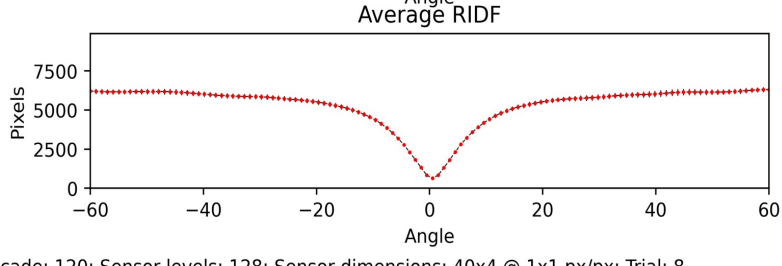
100%



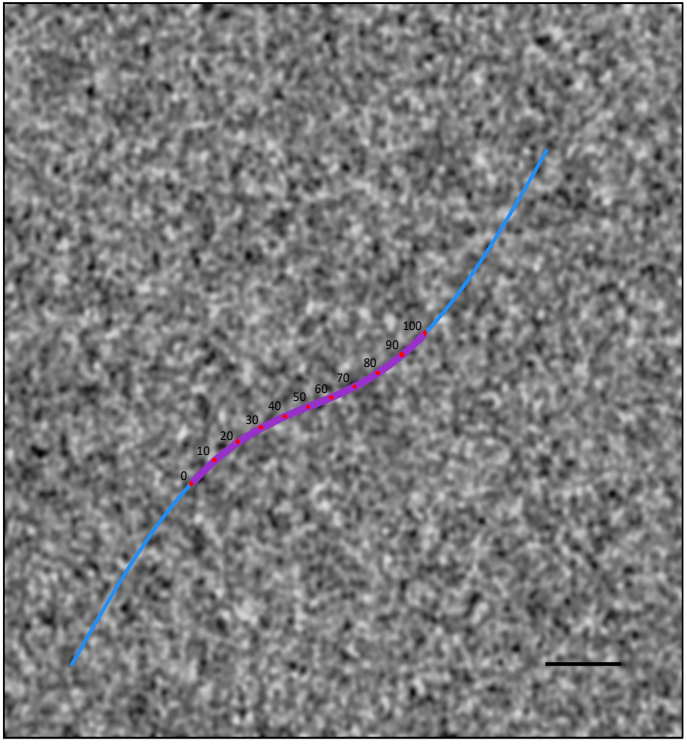



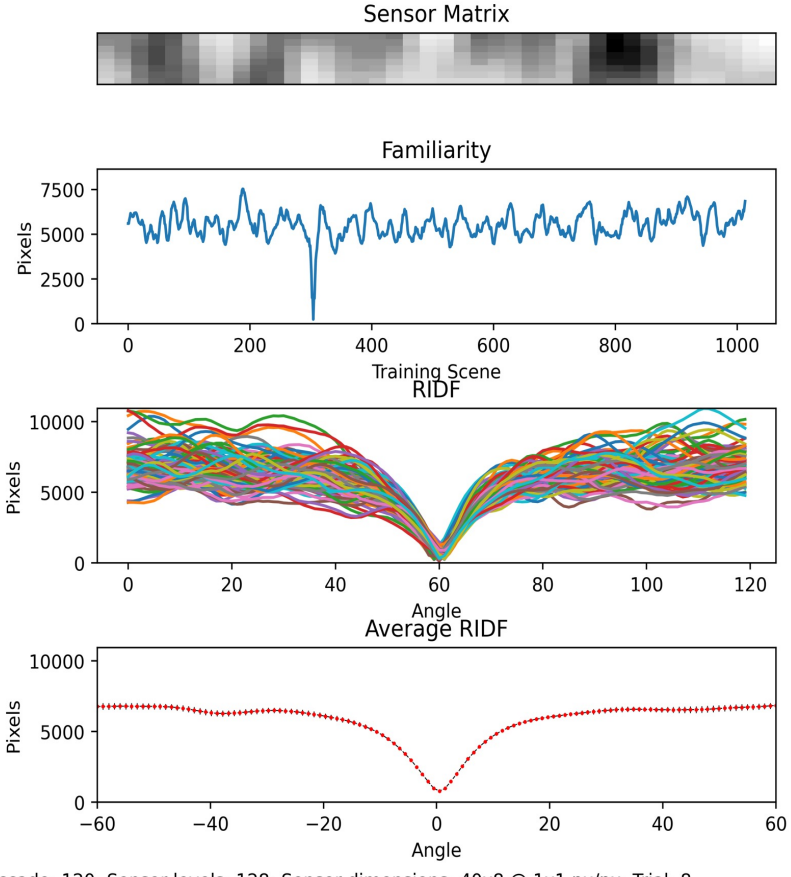




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 54.02; RMSD/dist: 0.135; TD: 4714; p90: 26; p50: 12; complete: 0

100%

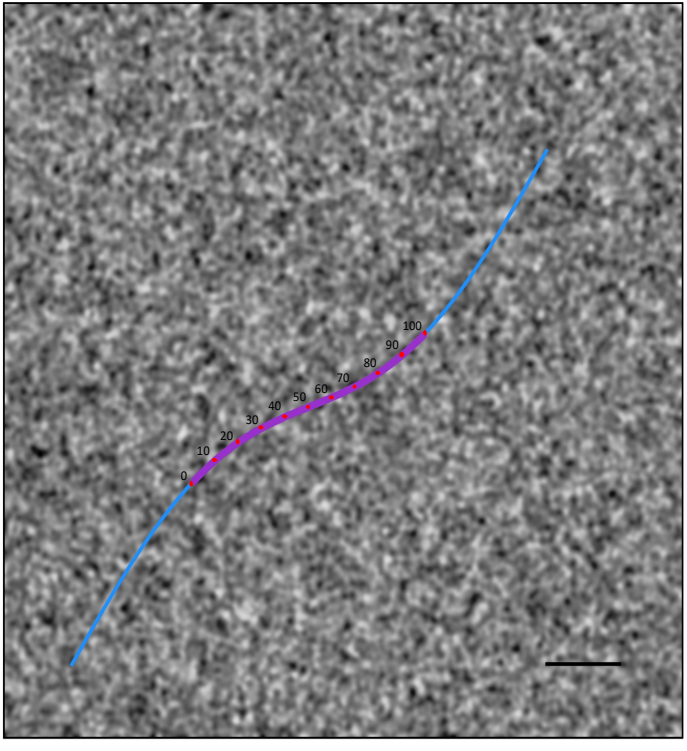


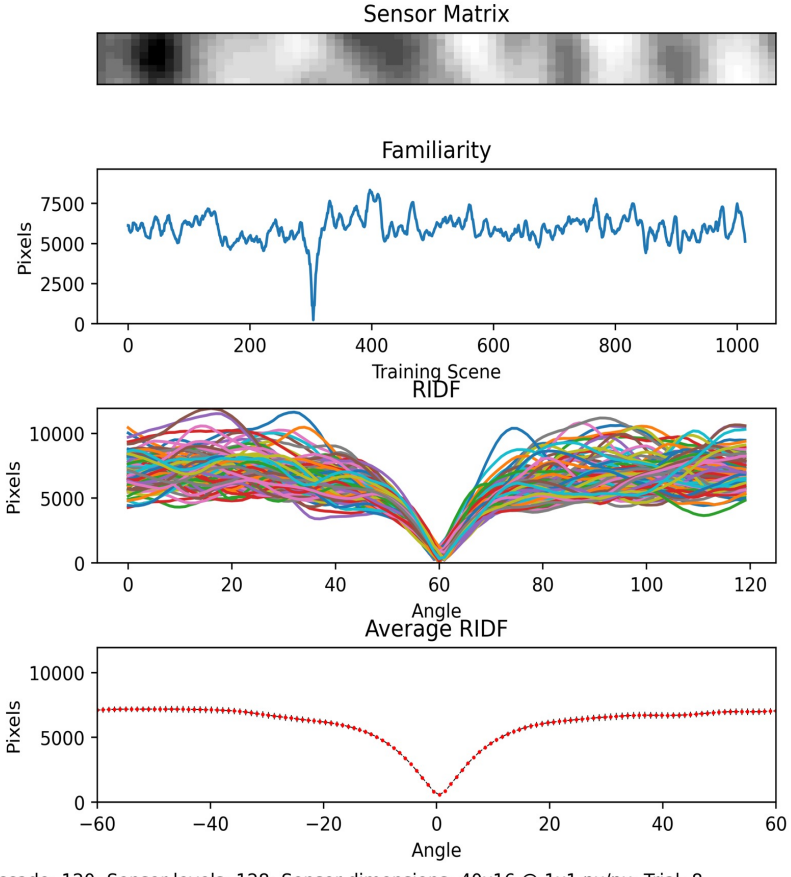




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 67.03; RMSD/dist: 0.168; TD: 4654; p90: 22; p50: 10; complete: 0

100%

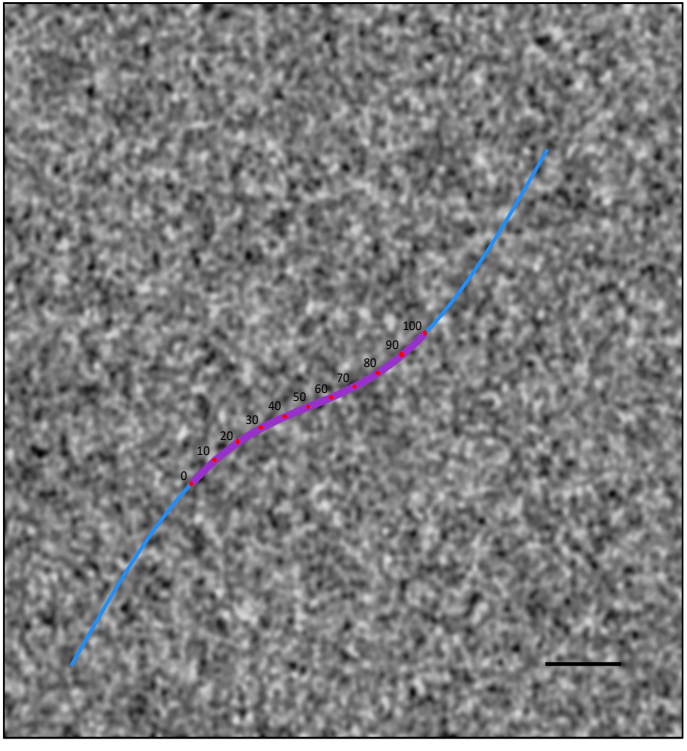


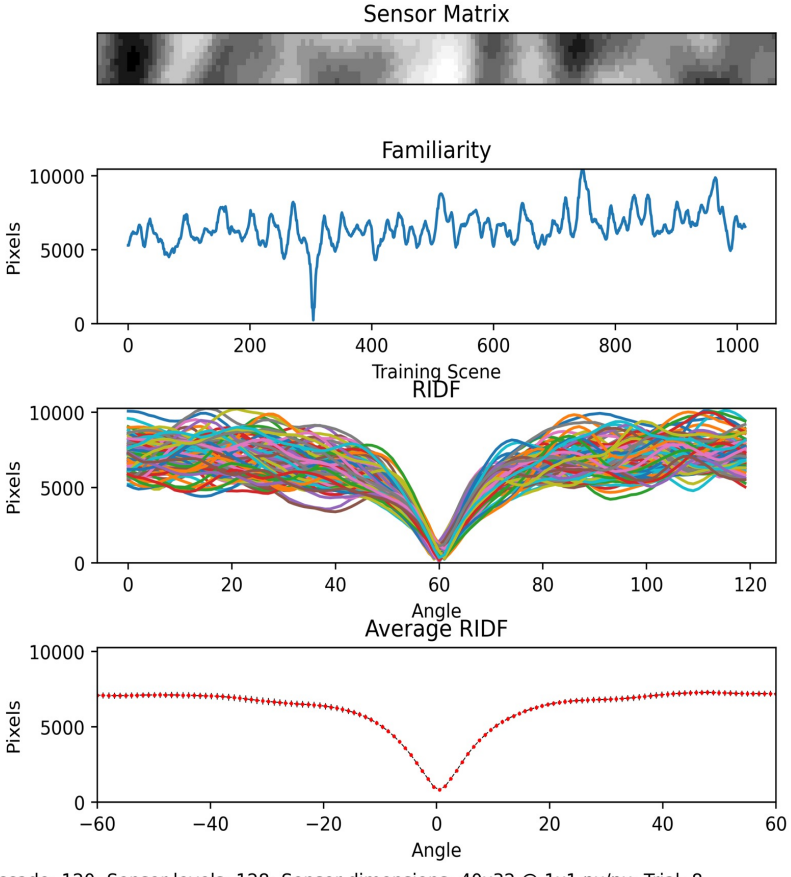




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 37.74; RMSD/dist: 0.094; TD: 5164; p90: 24; p50: 10; complete: 0

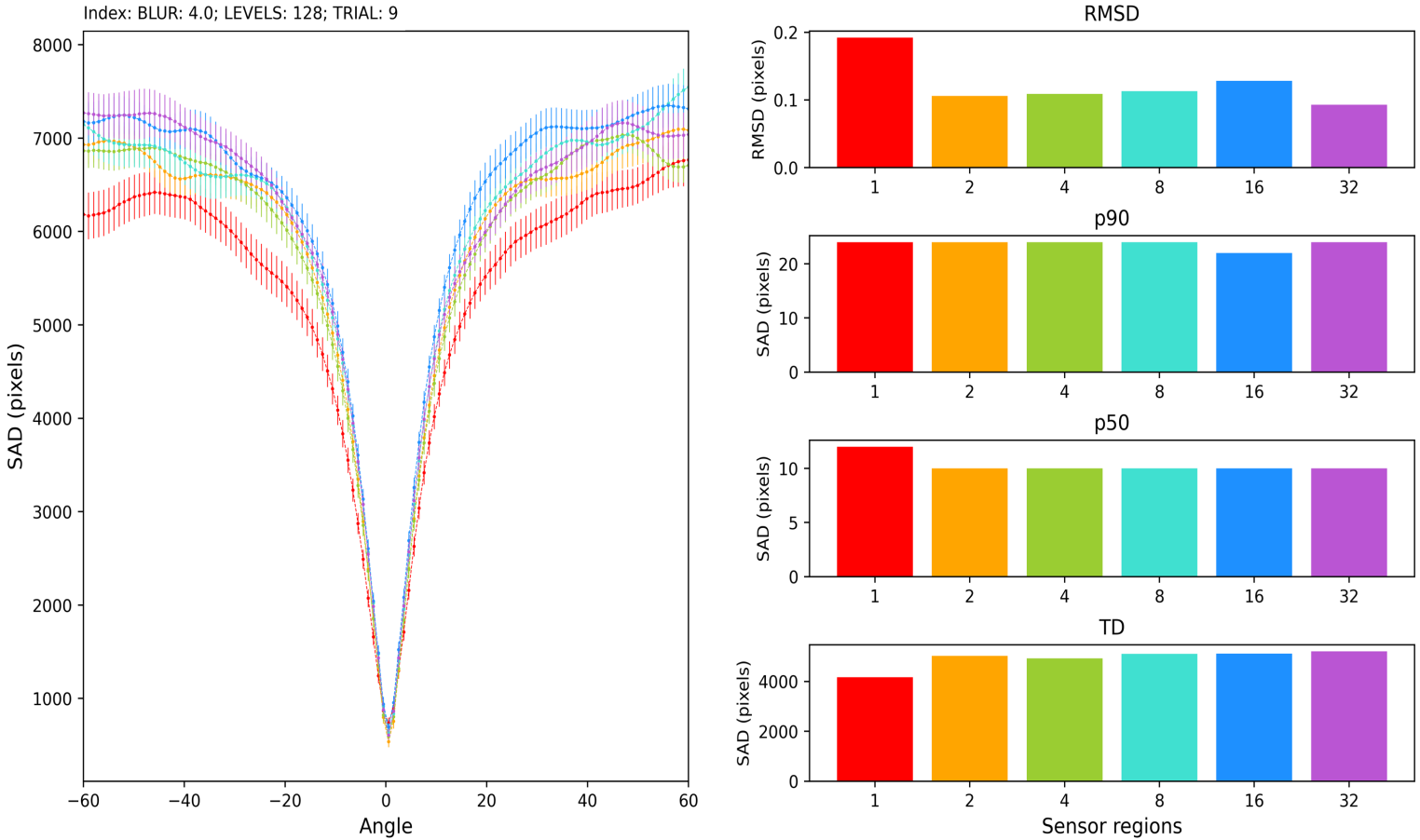
100%



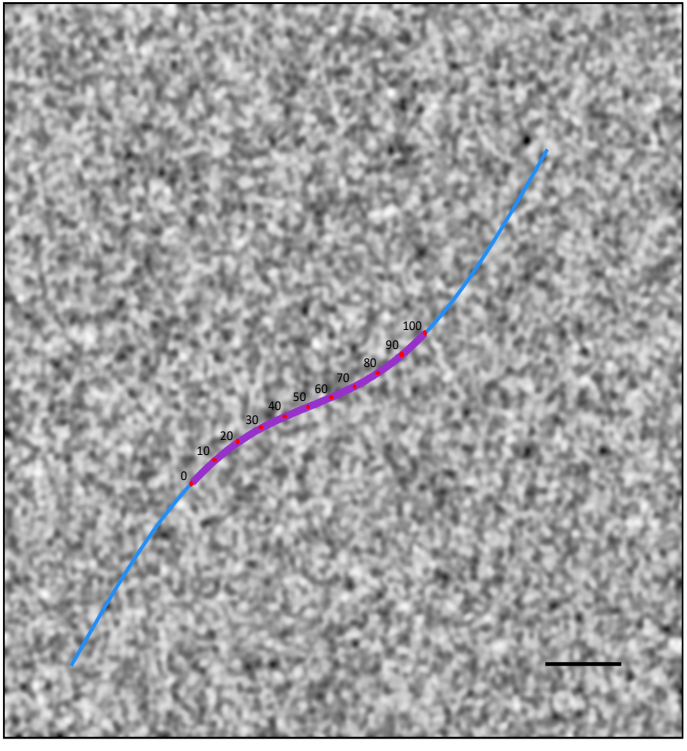



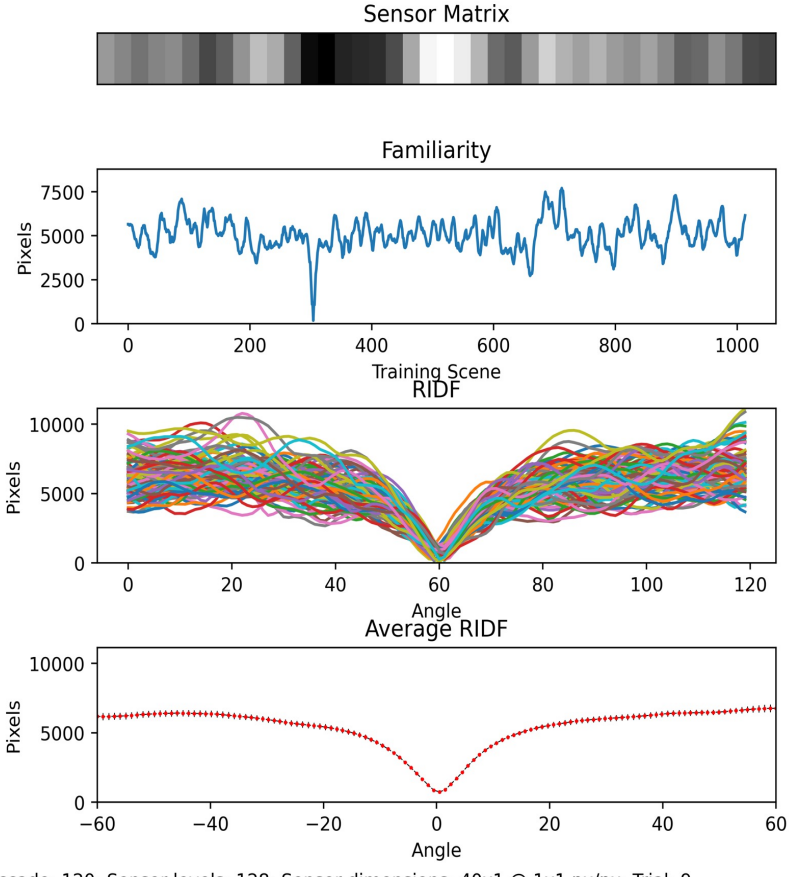

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 64.48; RMSD/dist: 0.161; TD: 5035; p90: 22; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 128; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

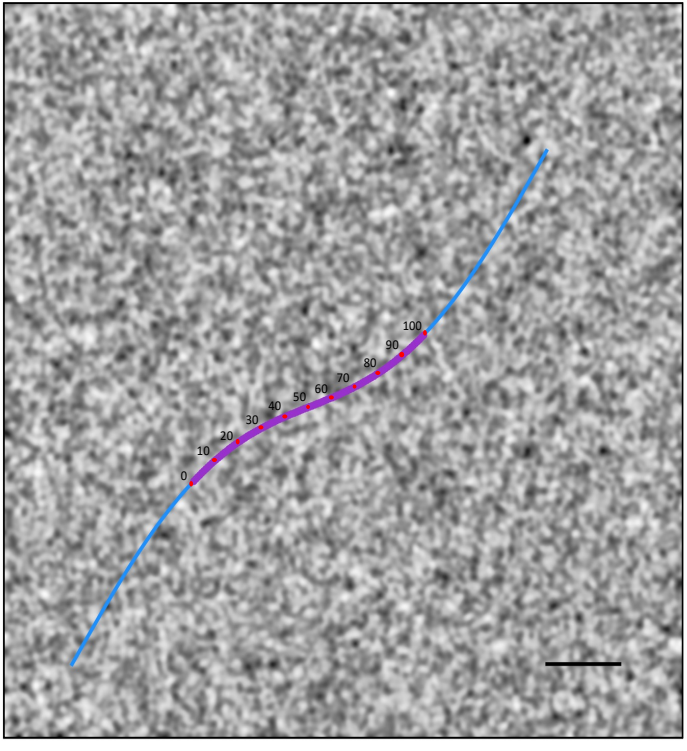


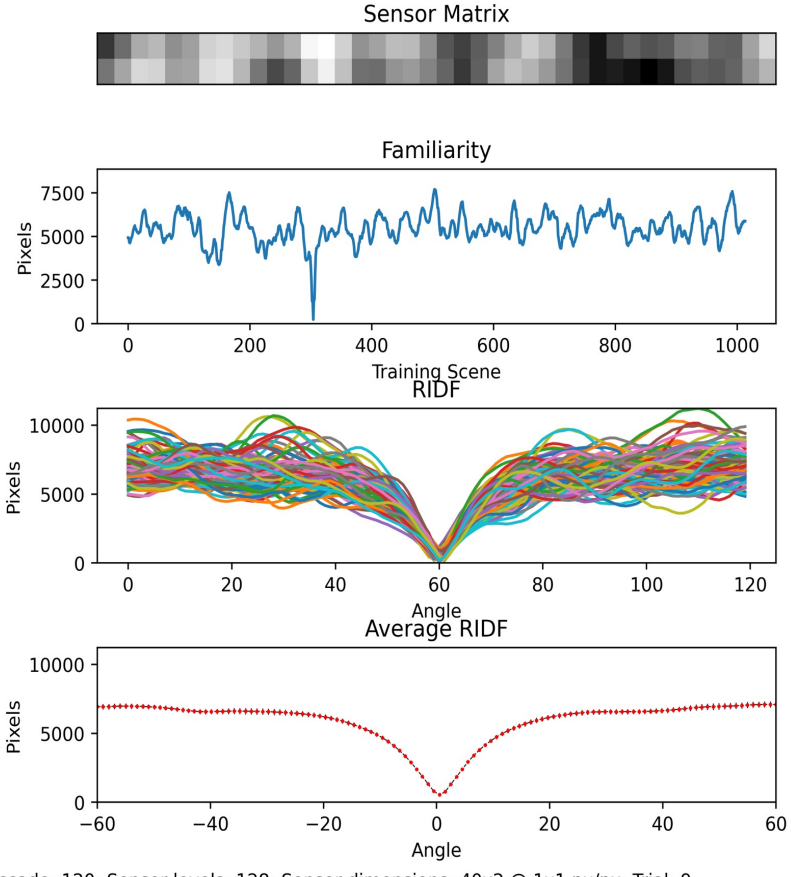




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 76.92; RMSD/dist: 0.192; TD: 4168; p90: 24; p50: 12; complete: 0

100%

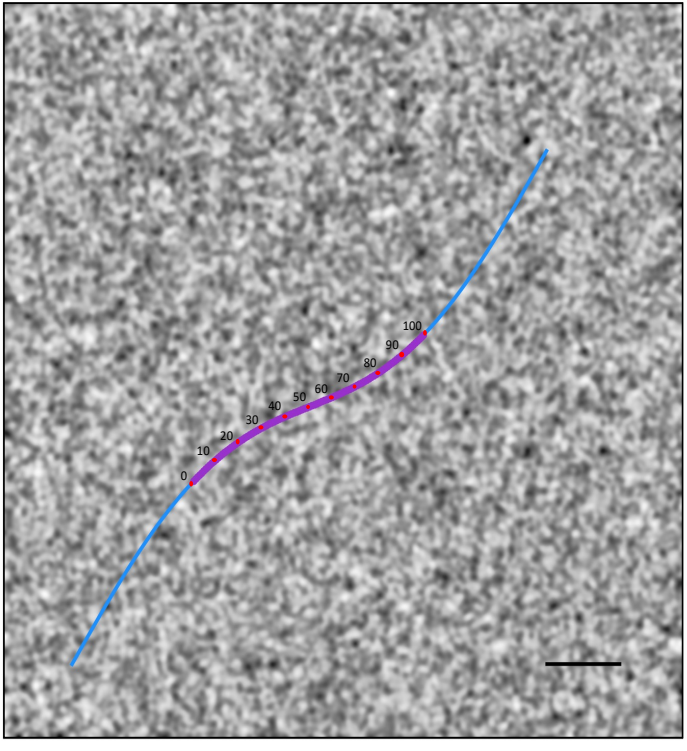


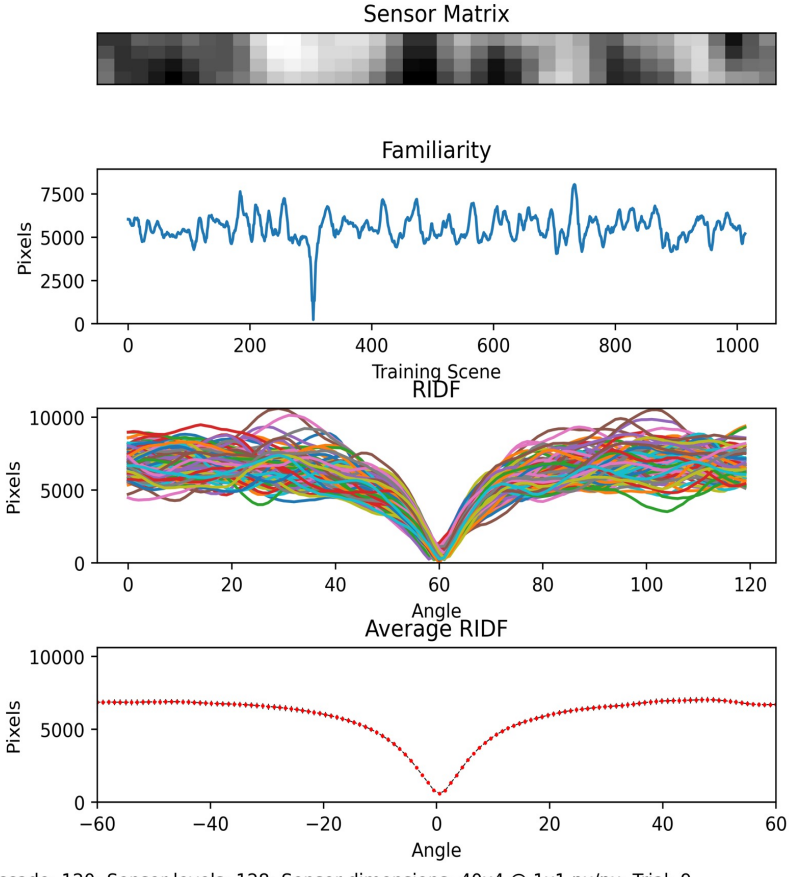




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 42.36; RMSD/dist: 0.106; TD: 5021; p90: 24; p50: 10; complete: 0

100%

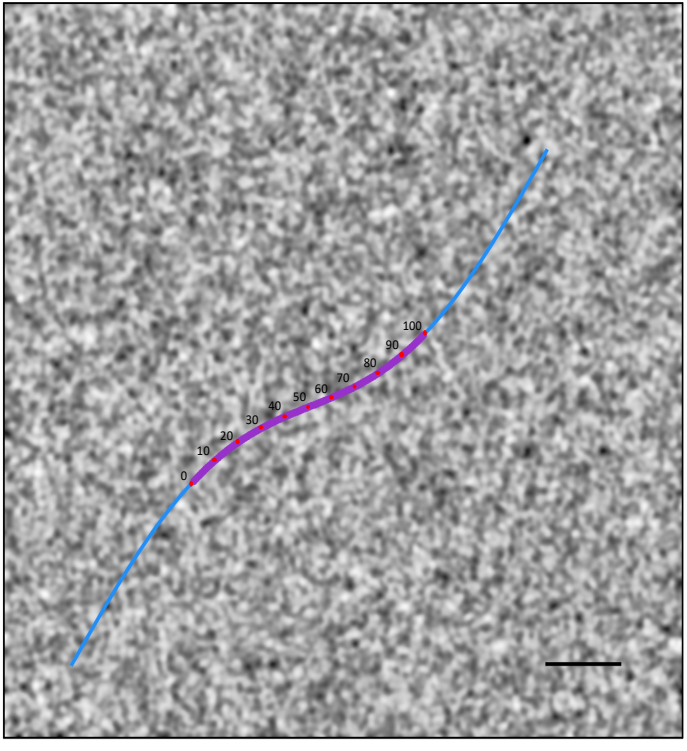


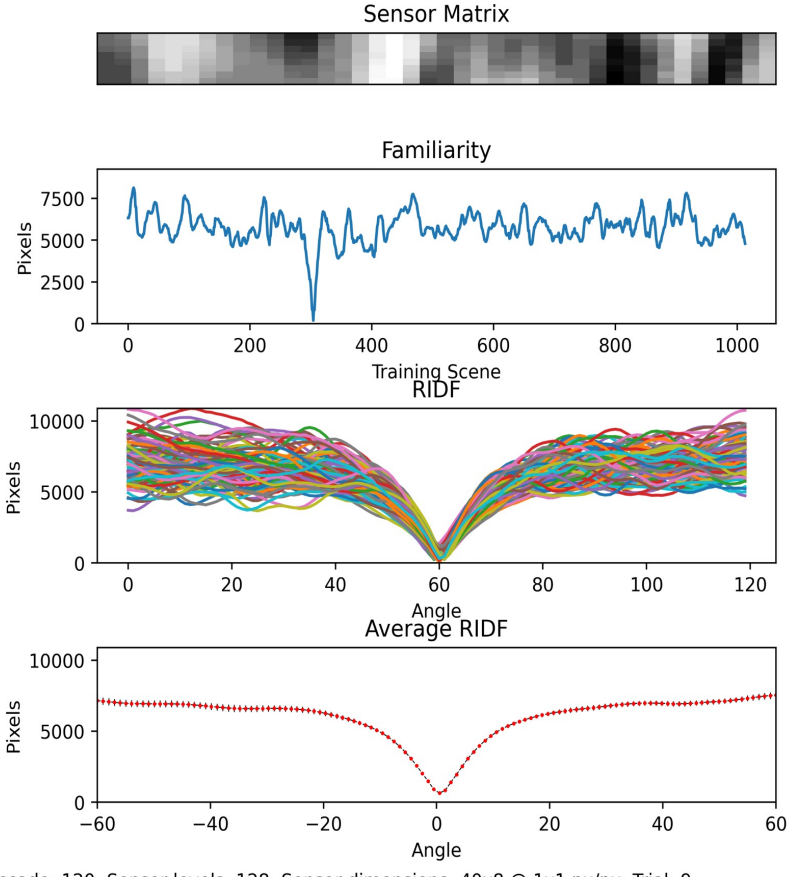




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 43.54; RMSD/dist: 0.109; TD: 4927; p90: 24; p50: 10; complete: 0

100%

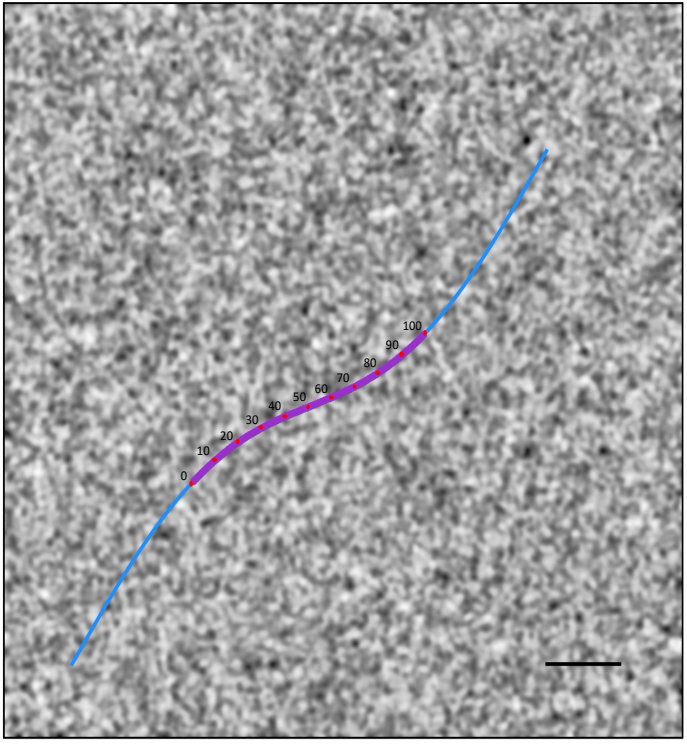


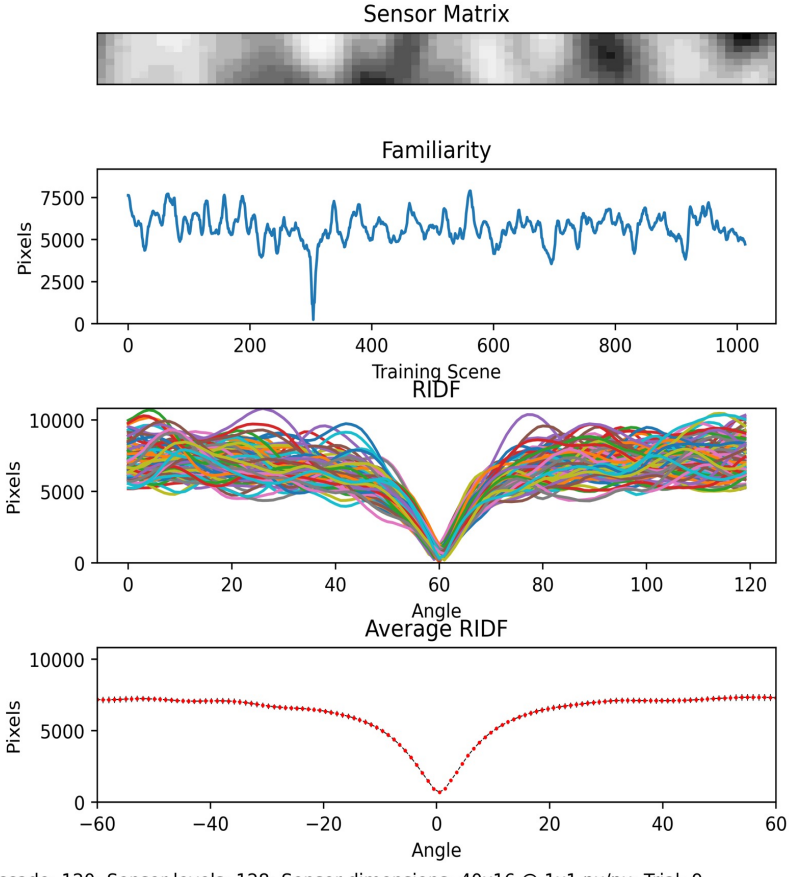




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 45.17; RMSD/dist: 0.113; TD: 5111; p90: 24; p50: 10; complete: 0

100%

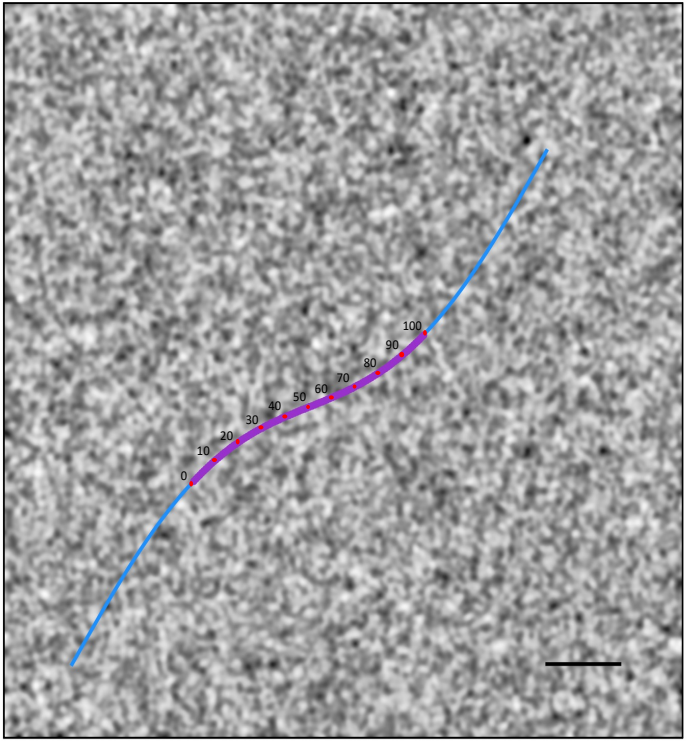


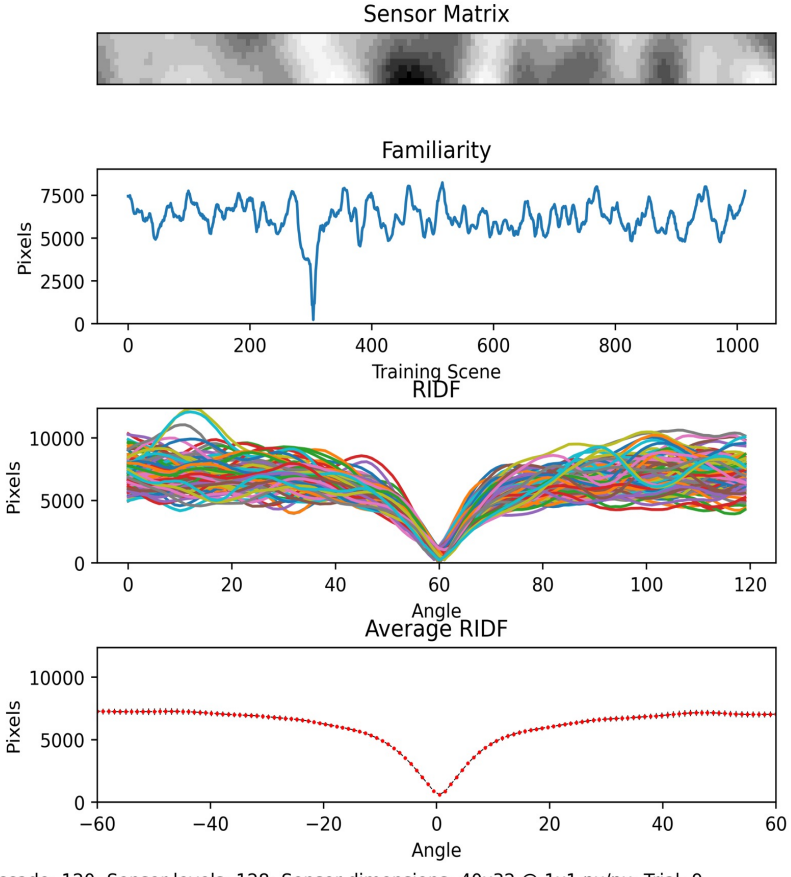




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 51.35; RMSD/dist: 0.128; TD: 5116; p90: 22; p50: 10; complete: 0

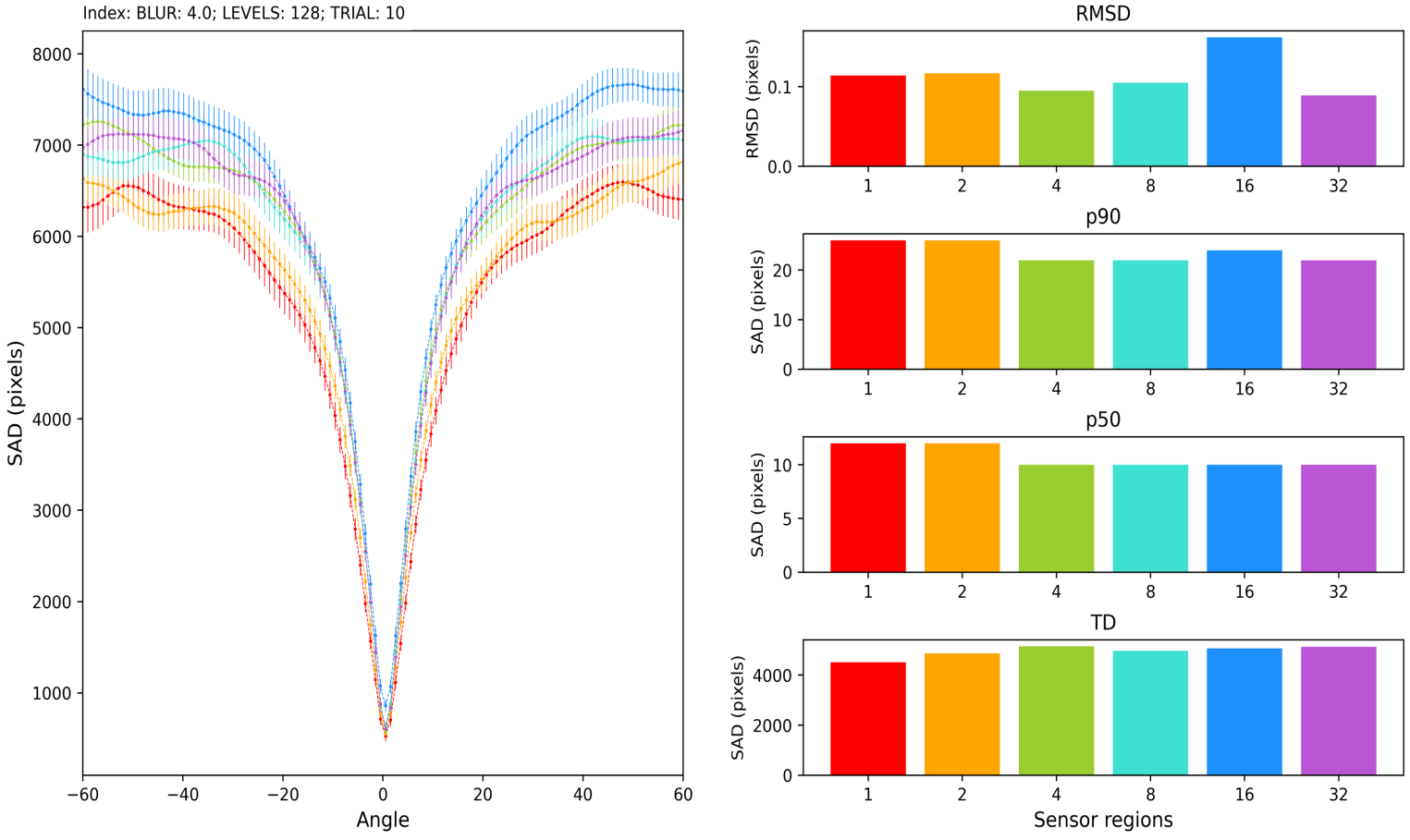
100%



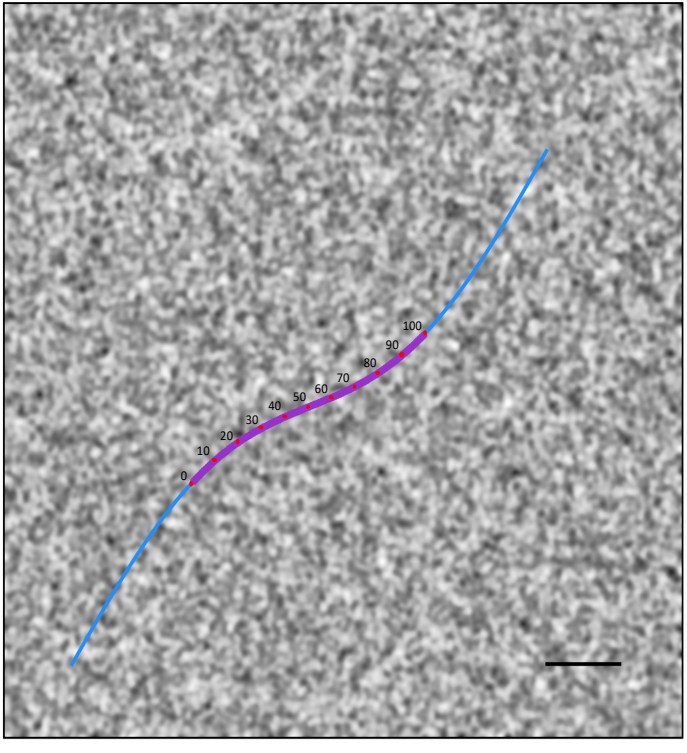



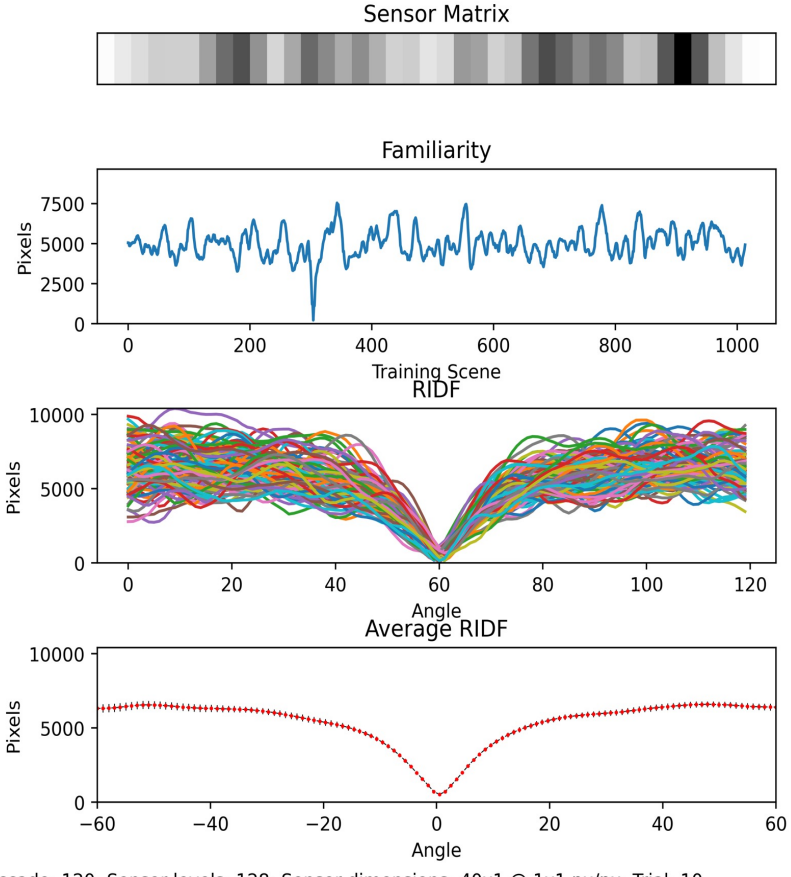

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 37.30; RMSD/dist: 0.093; TD: 5209; p90: 24; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 128; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

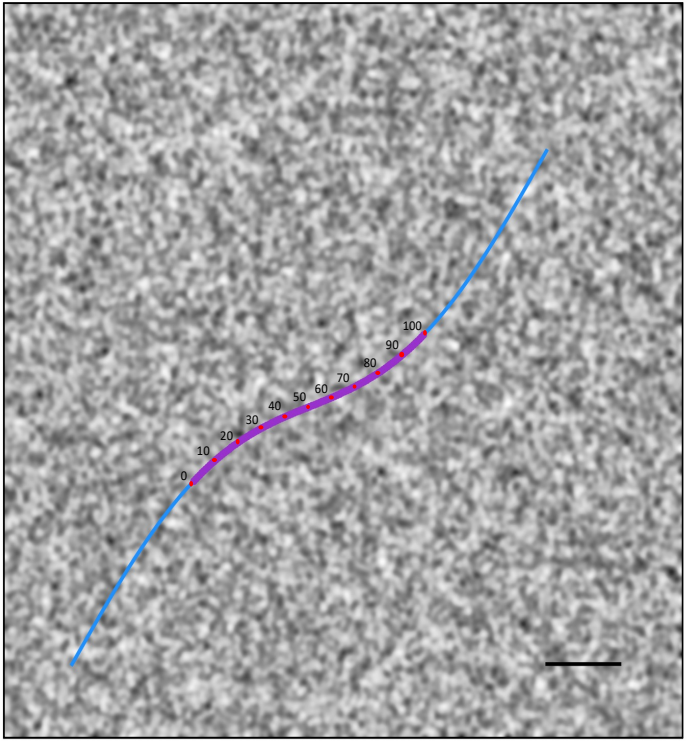


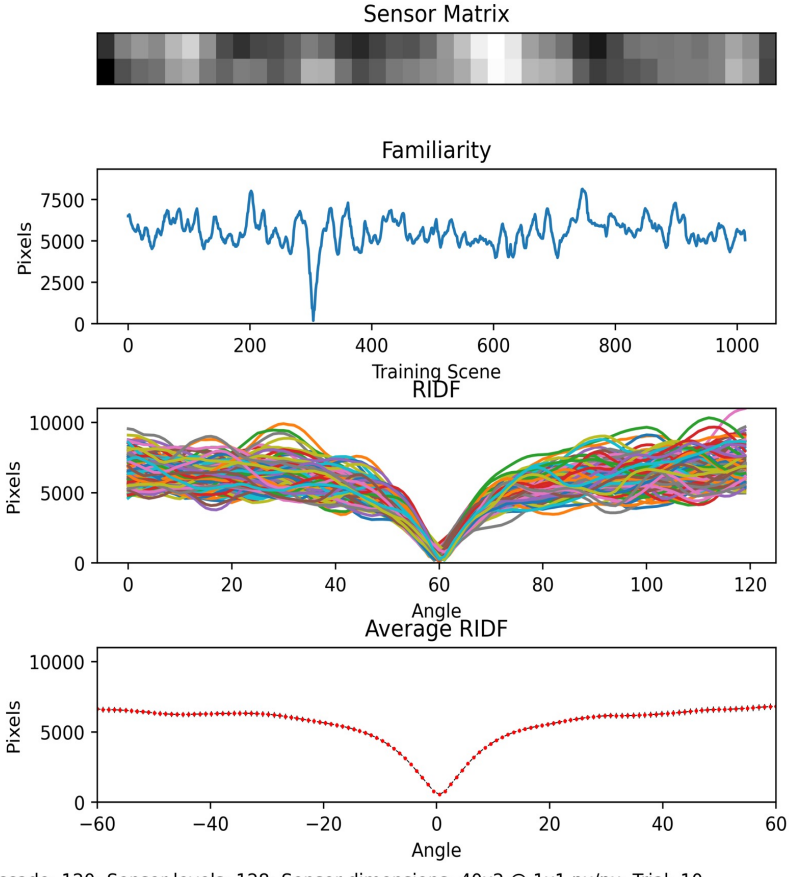




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 45.45; RMSD/dist: 0.114; TD: 4513; p90: 26; p50: 12; complete: 0

100%

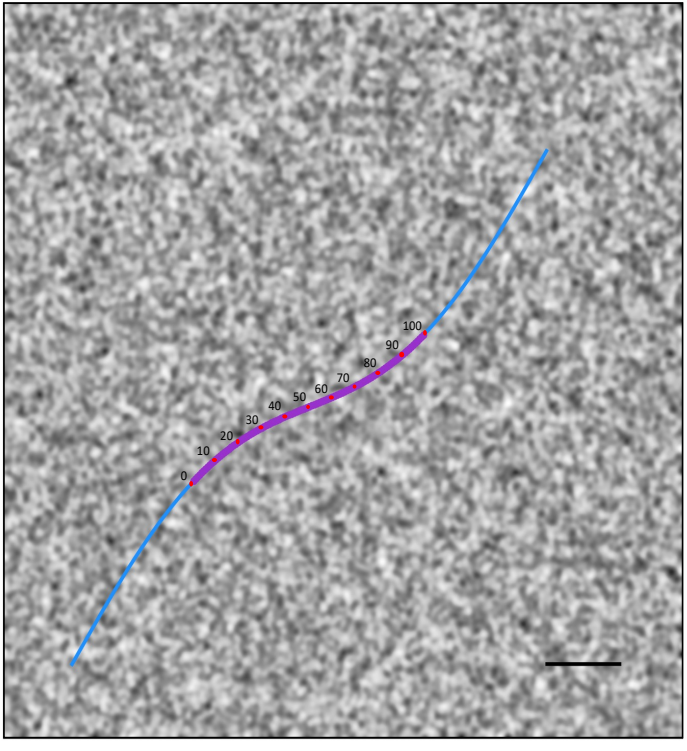


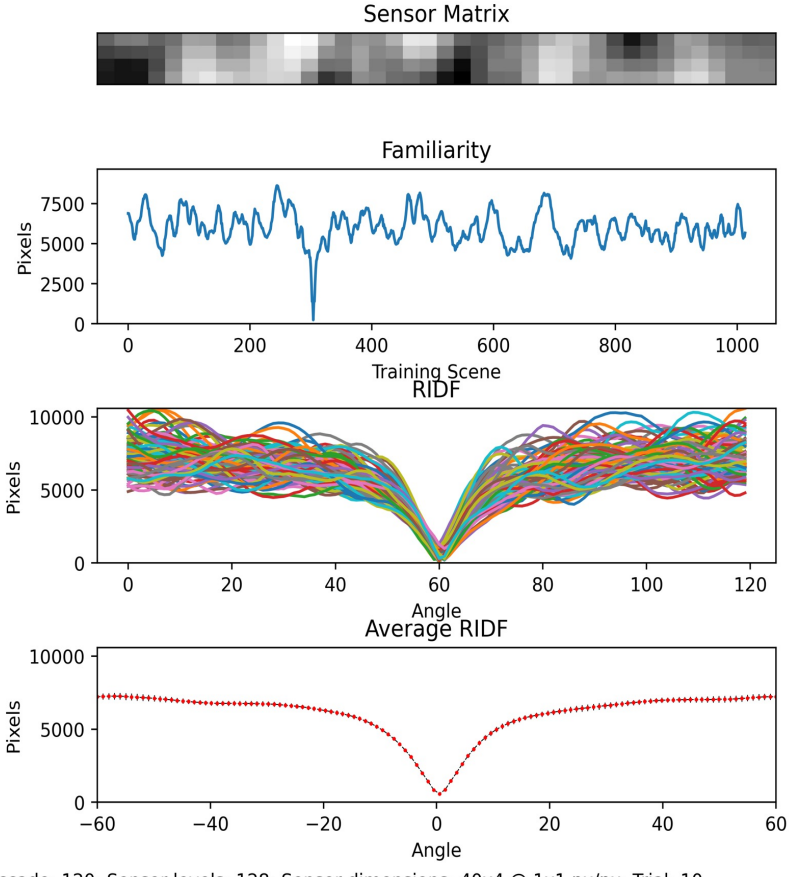




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 46.81; RMSD/dist: 0.117; TD: 4874; p90: 26; p50: 12; complete: 0

100%

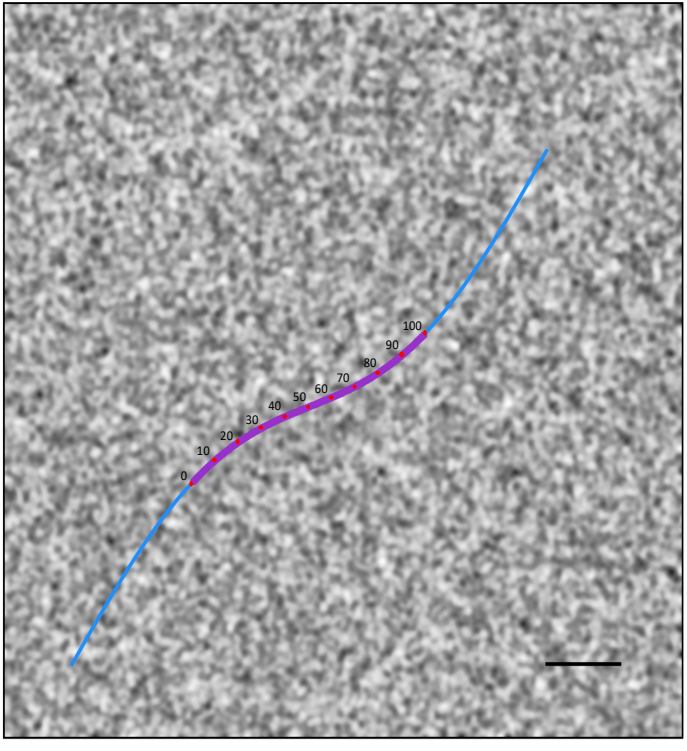


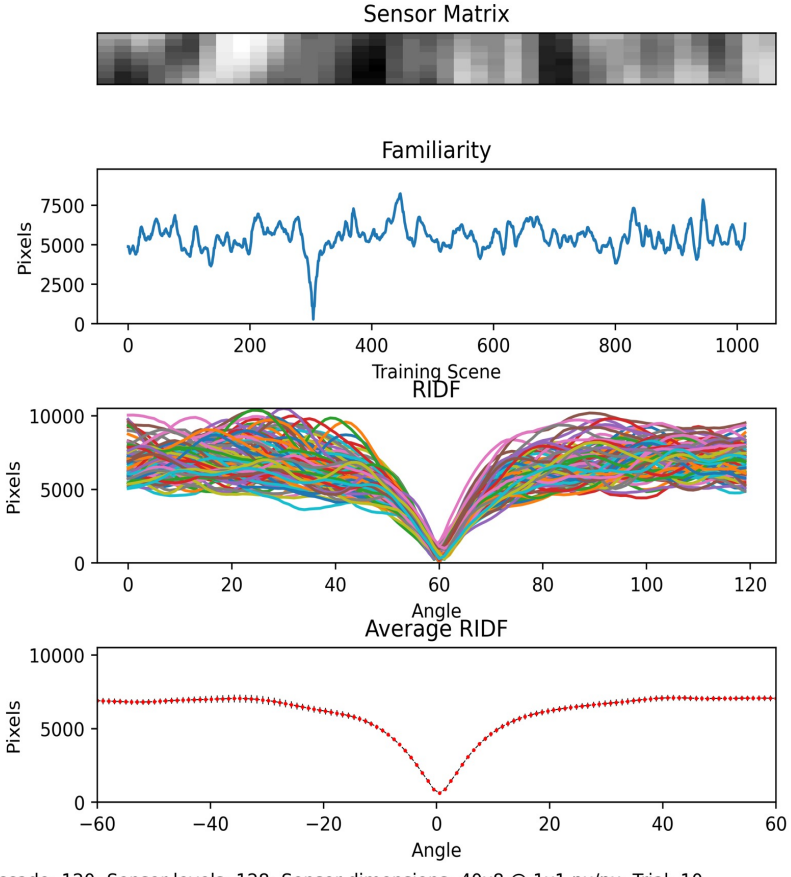




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 37.99; RMSD/dist: 0.095; TD: 5152; p90: 22; p50: 10; complete: 0

100%

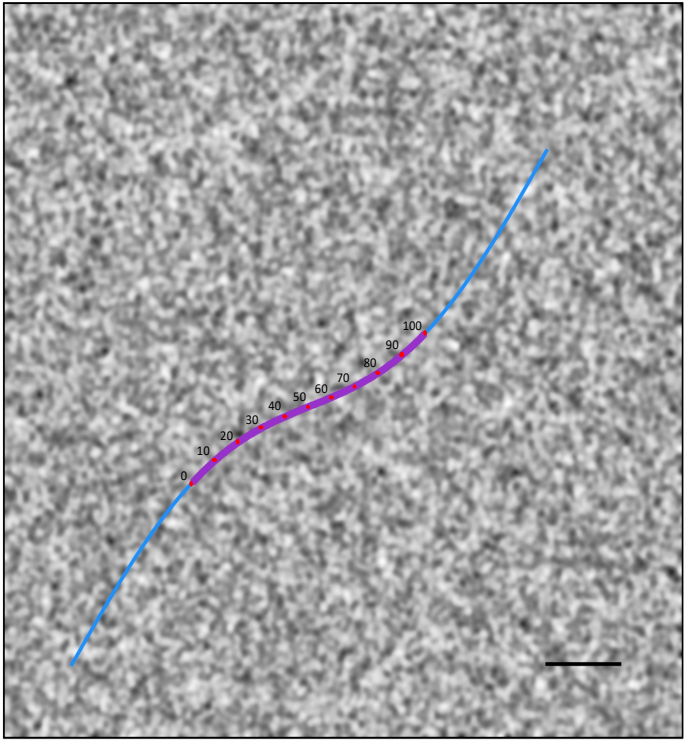


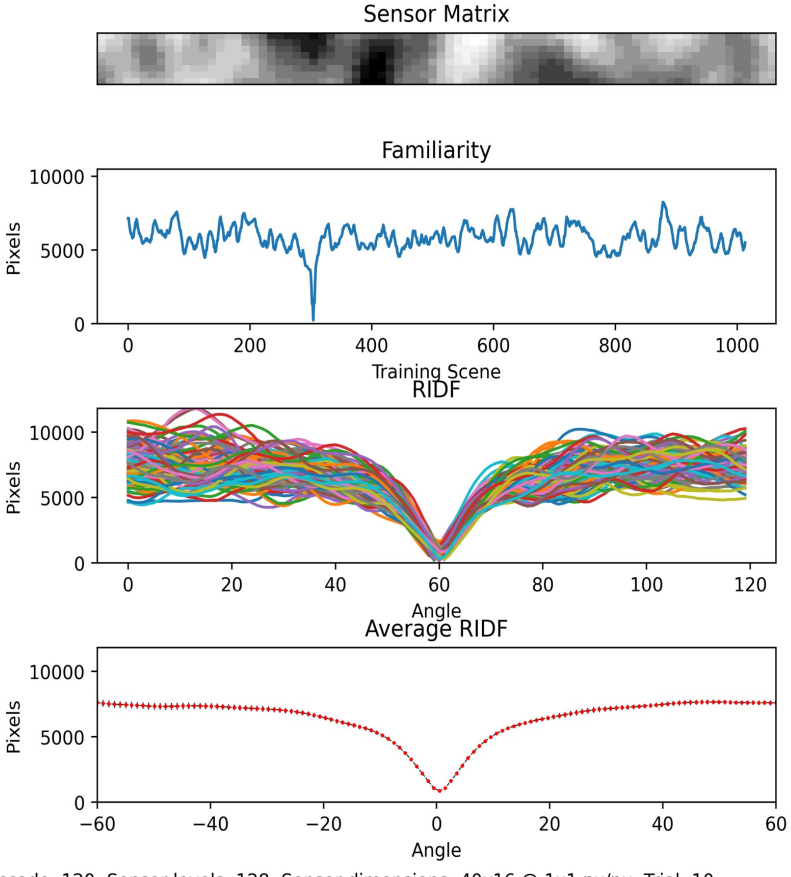




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 42.13; RMSD/dist: 0.105; TD: 4973; p90: 22; p50: 10; complete: 0

100%

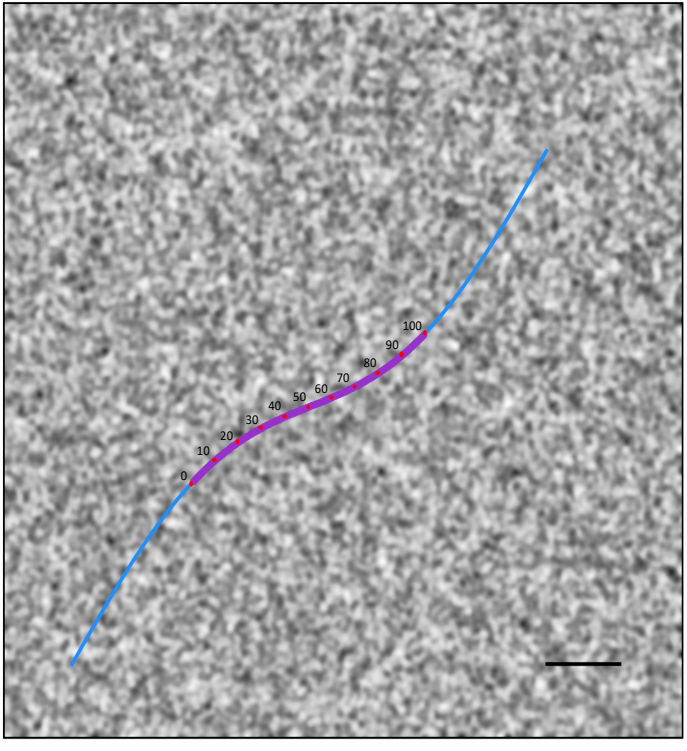


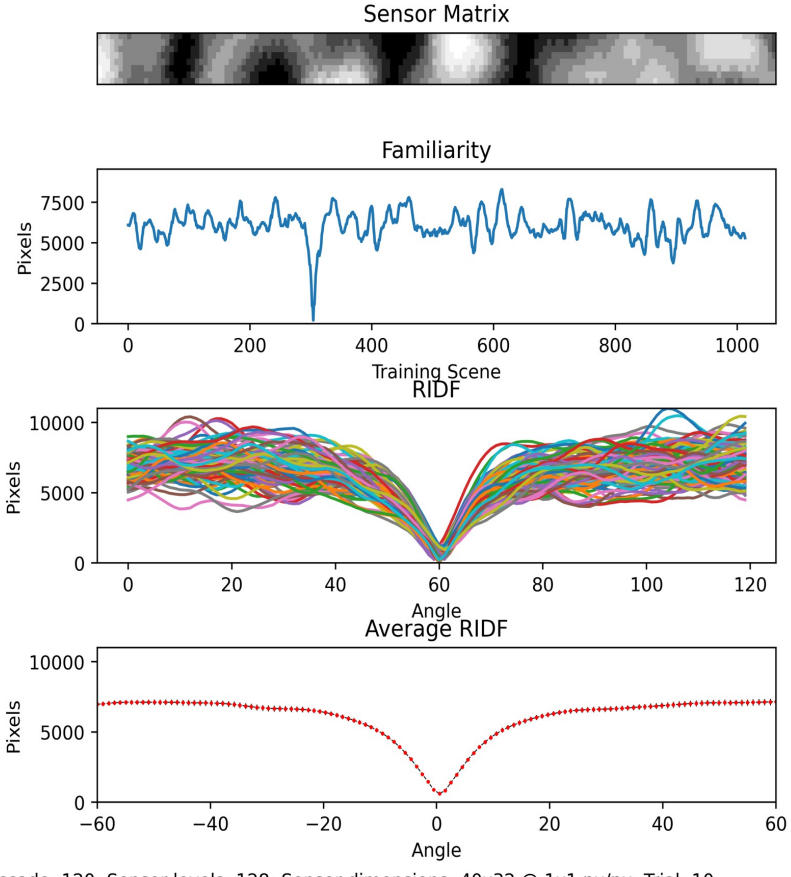




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 64.89; RMSD/dist: 0.162; TD: 5073; p90: 24; p50: 10; complete: 0

100%




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 35.52; RMSD/dist: 0.089; TD: 5134; p90: 22; p50: 10; complete: 0