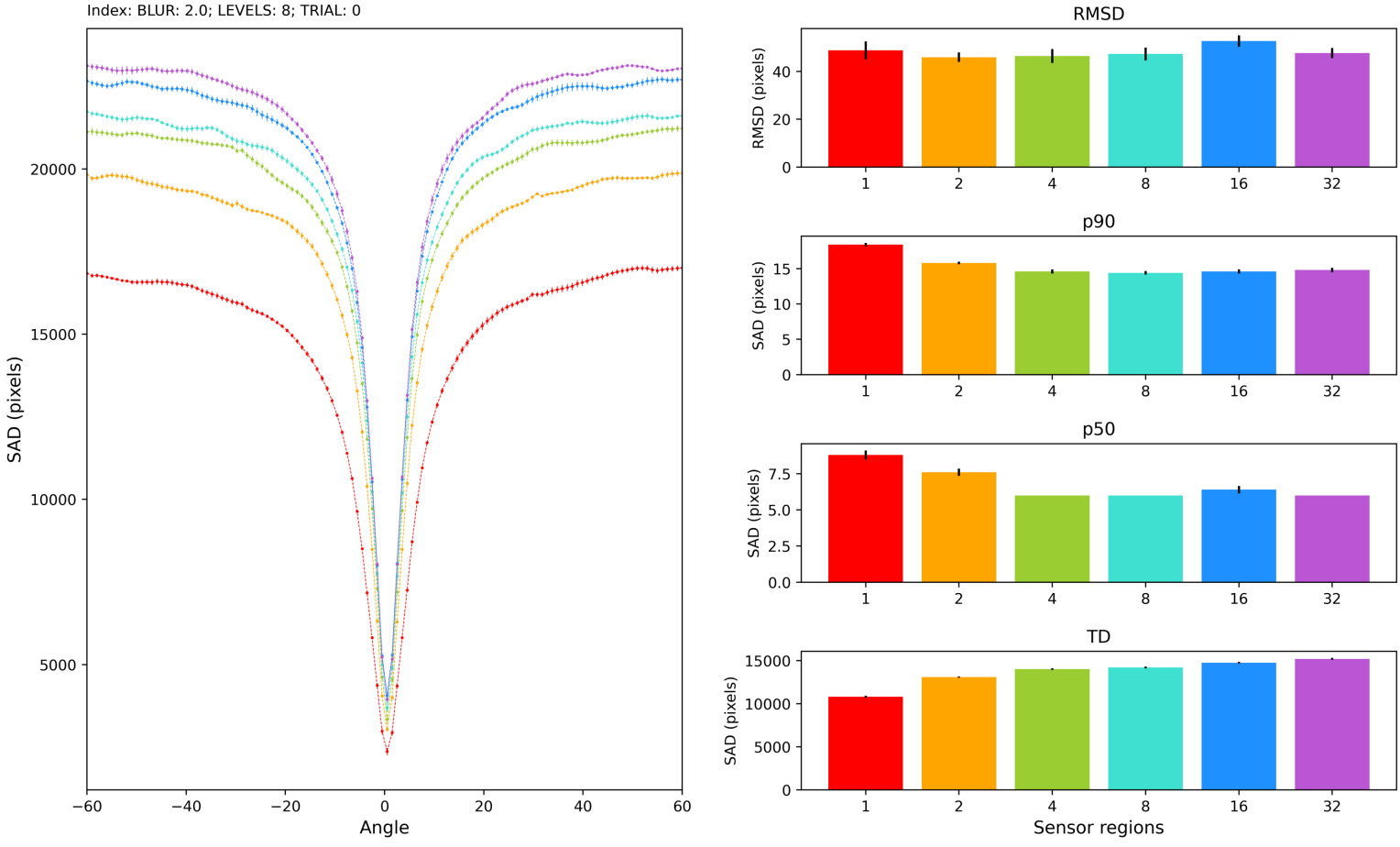
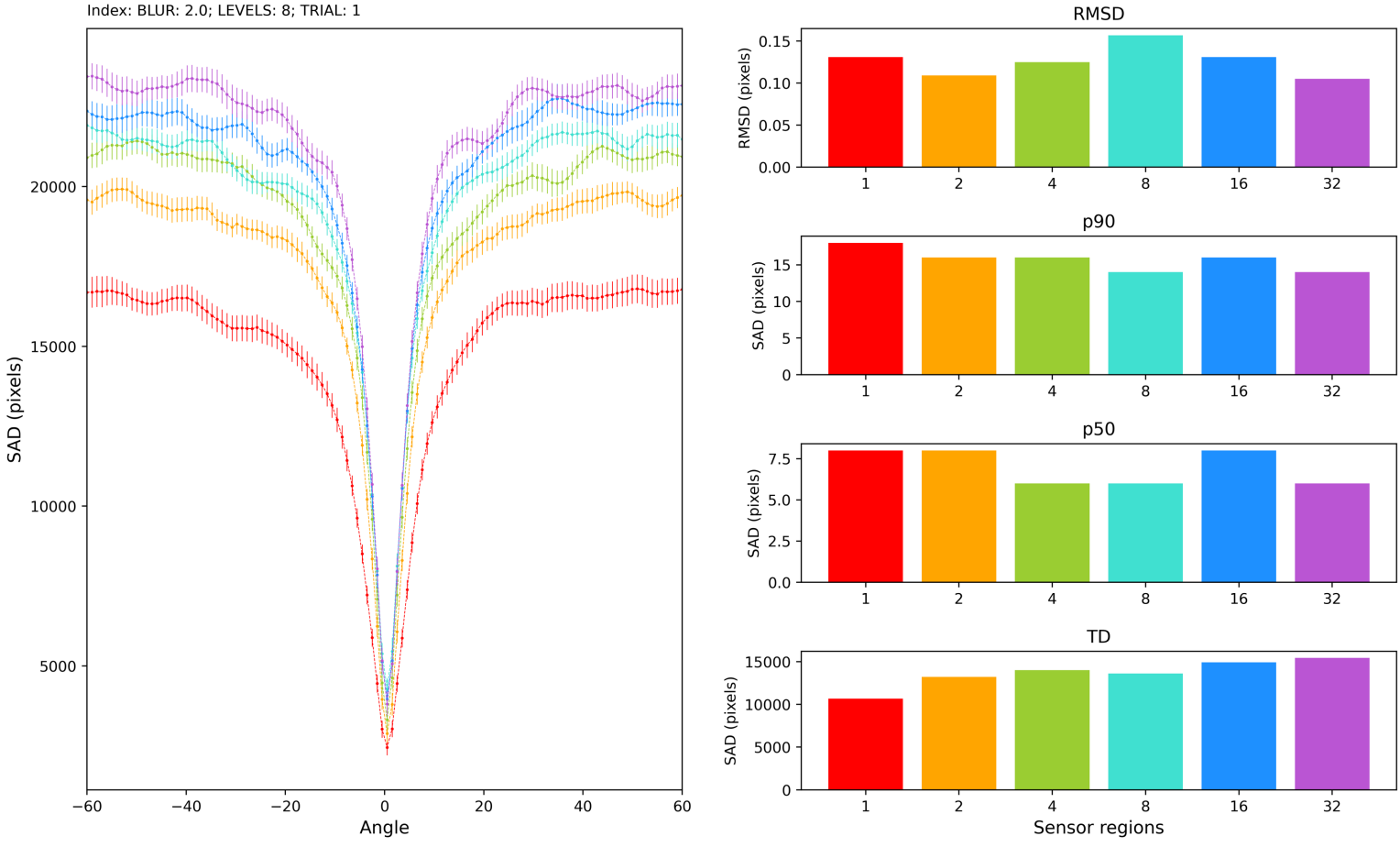

Index: BLUR: 2.0; LEVELS: 8; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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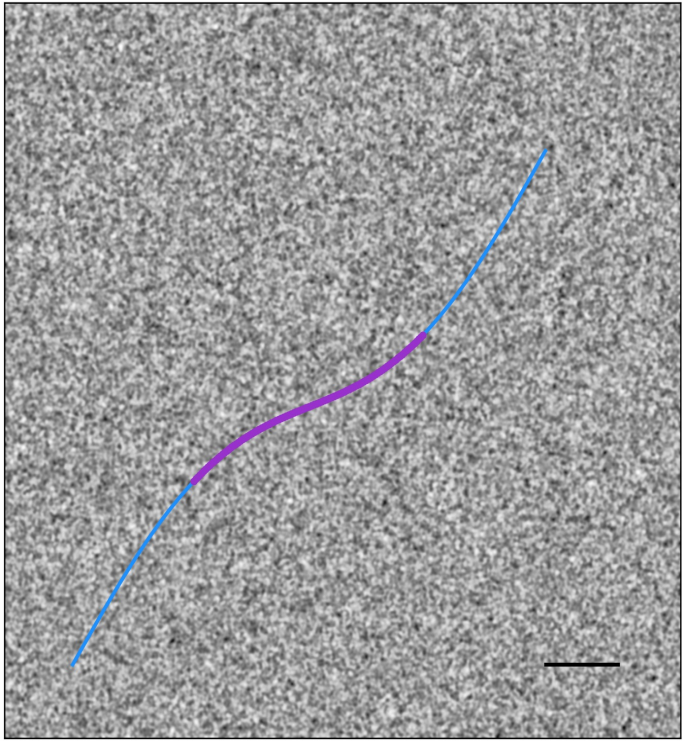
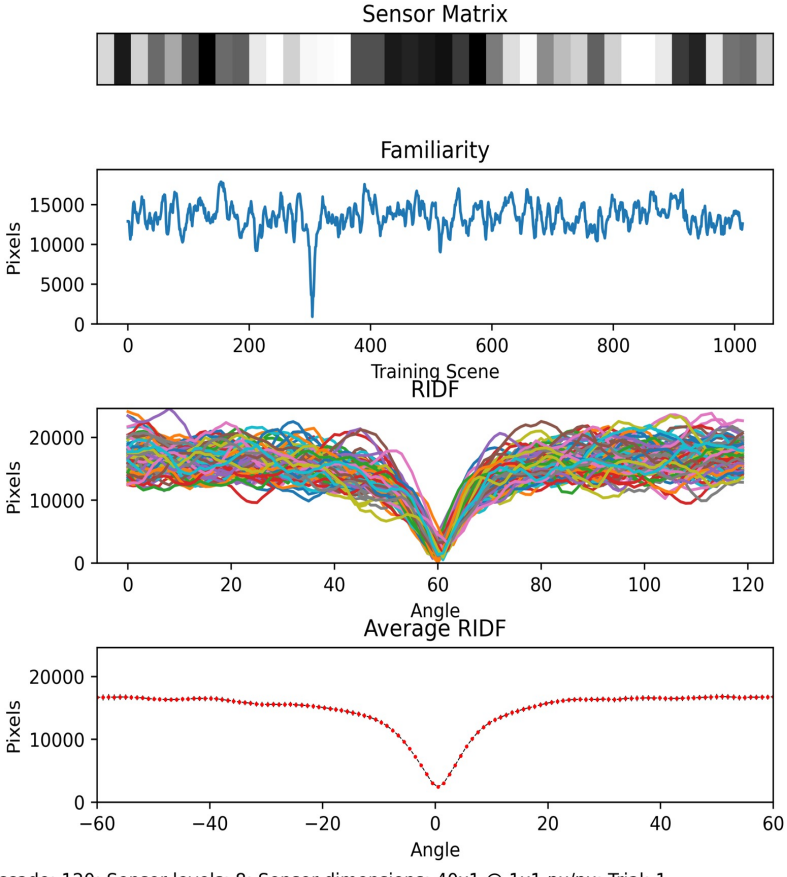
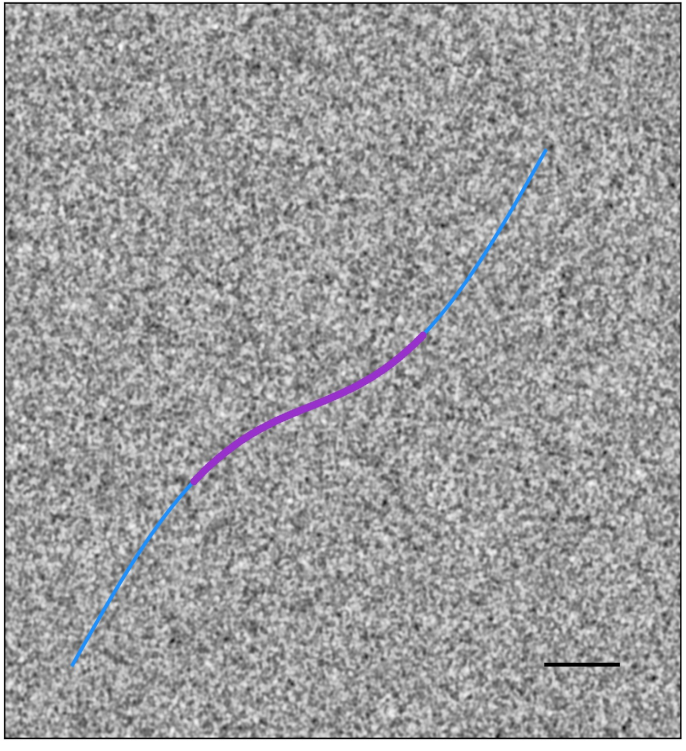
SAD (pixels)
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

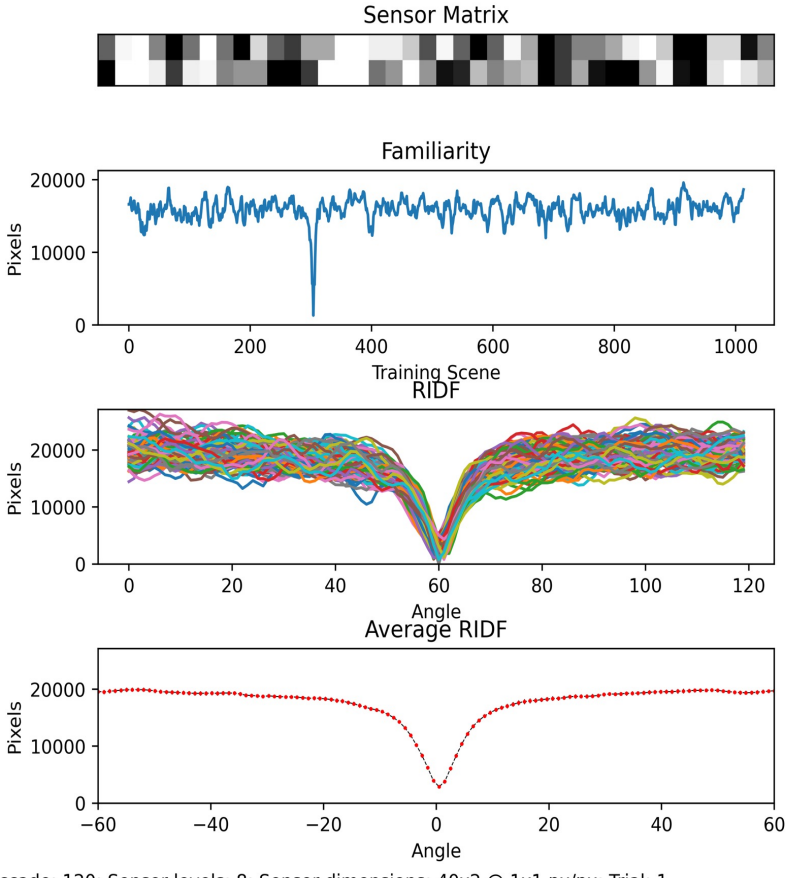




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

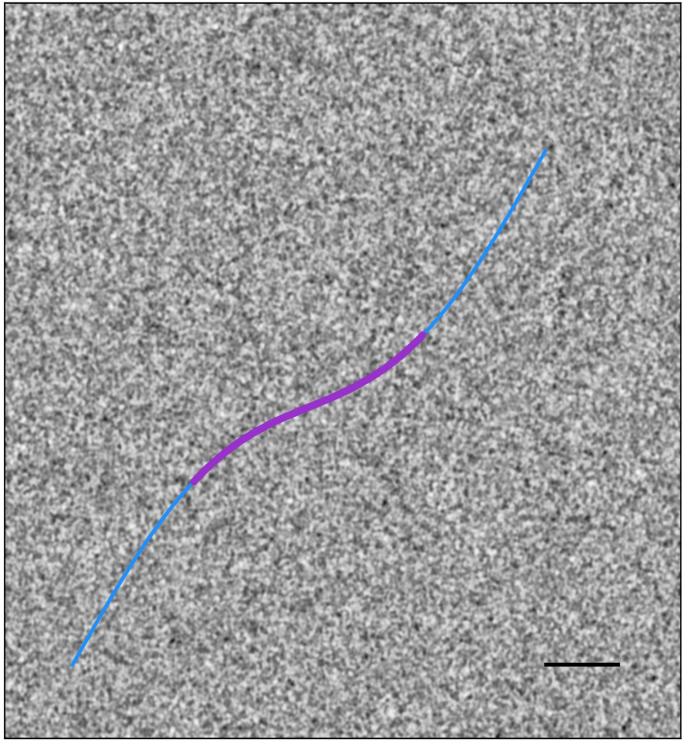
Navigation stats: RMSD error: 52.24; RMSD/dist: 0.131; TD: 10672; p90: 18; p50: 8; complete: 0

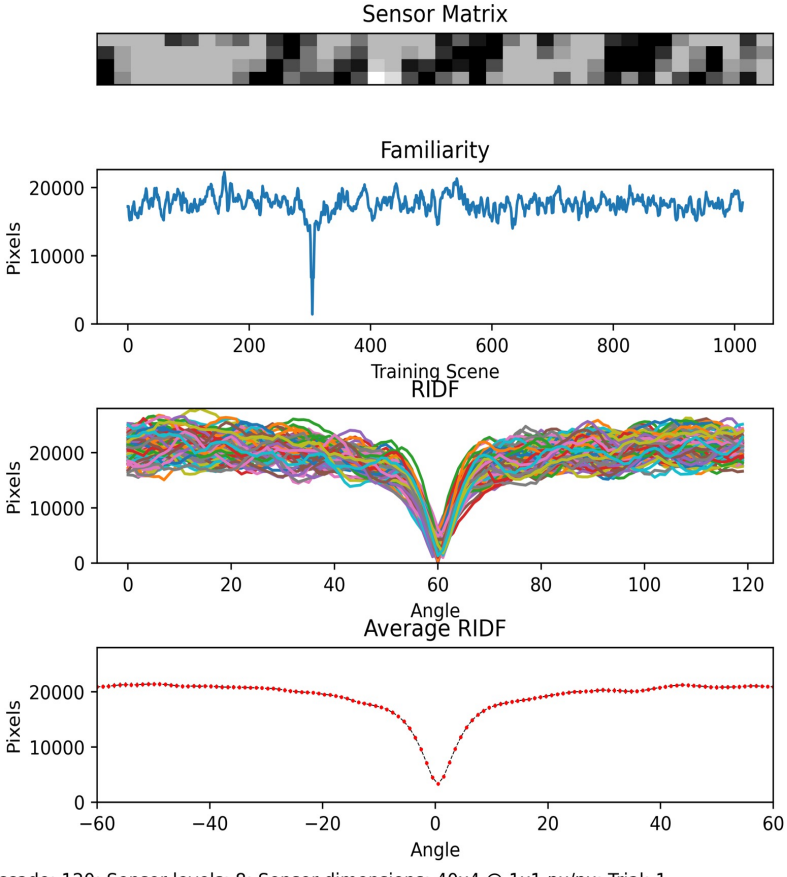




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

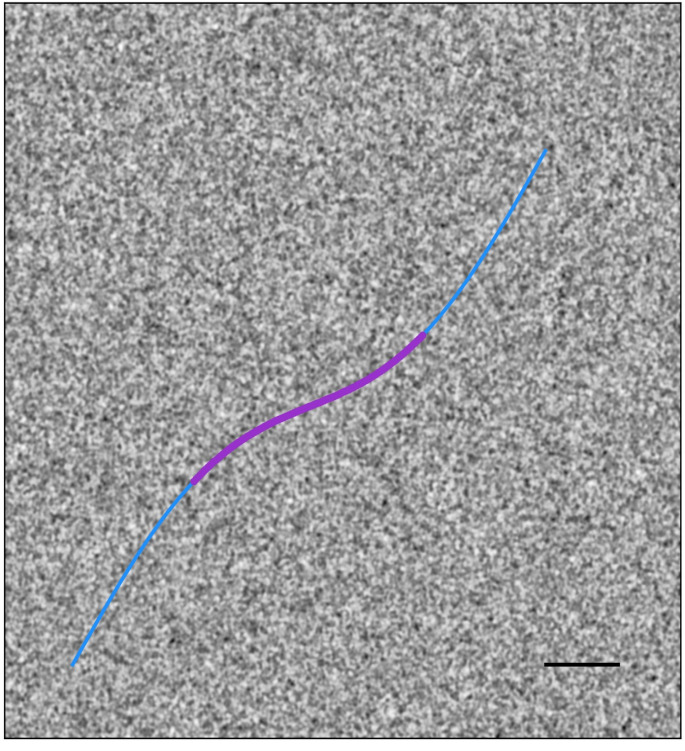
Navigation stats: RMSD error: 43.52; RMSD/dist: 0.109; TD: 13228; p90: 16; p50: 8; complete: 0

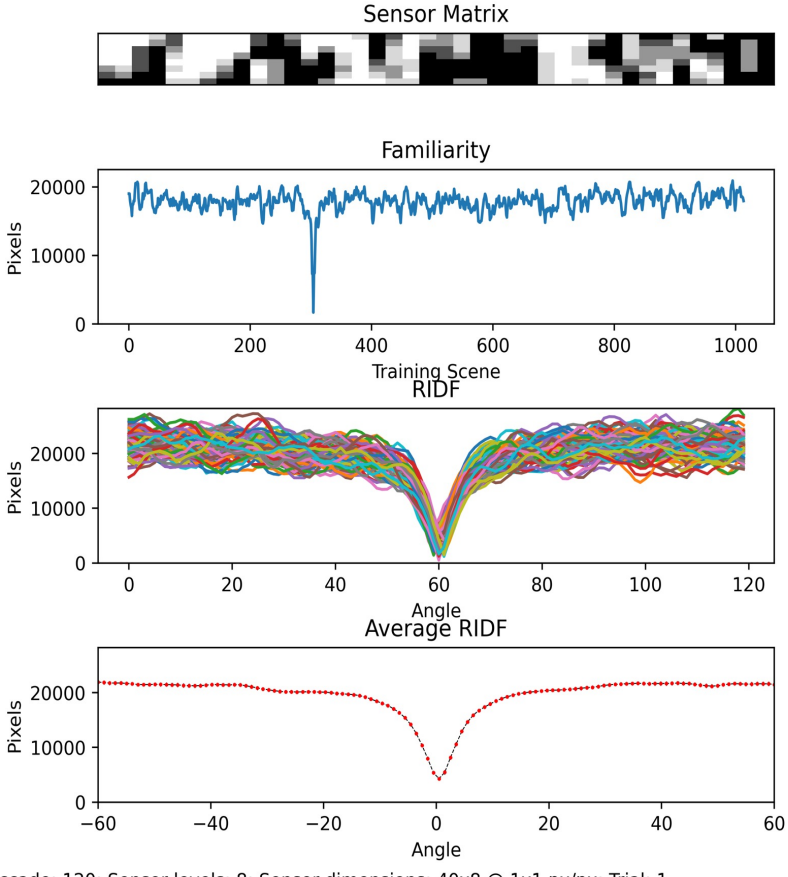




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

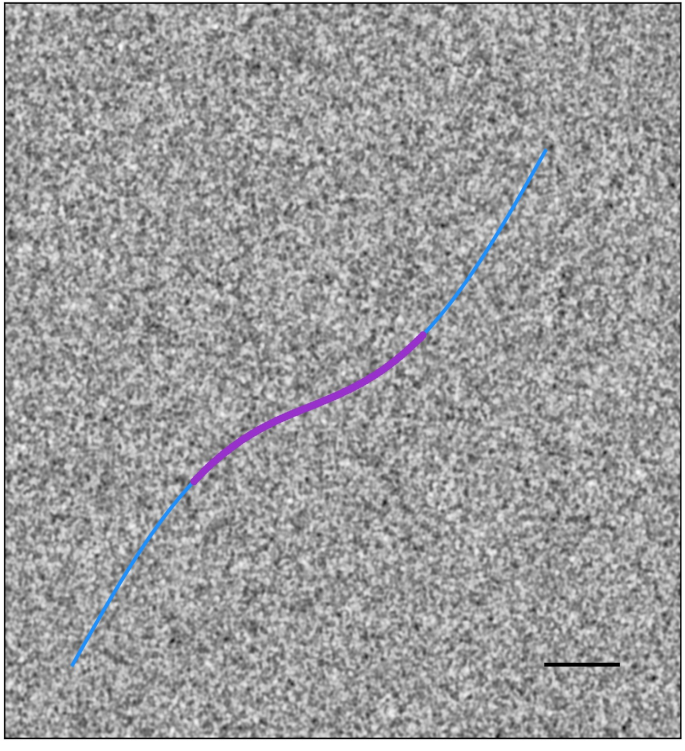
Navigation stats: RMSD error: 50.10; RMSD/dist: 0.125; TD: 14016; p90: 16; p50: 6; complete: 0

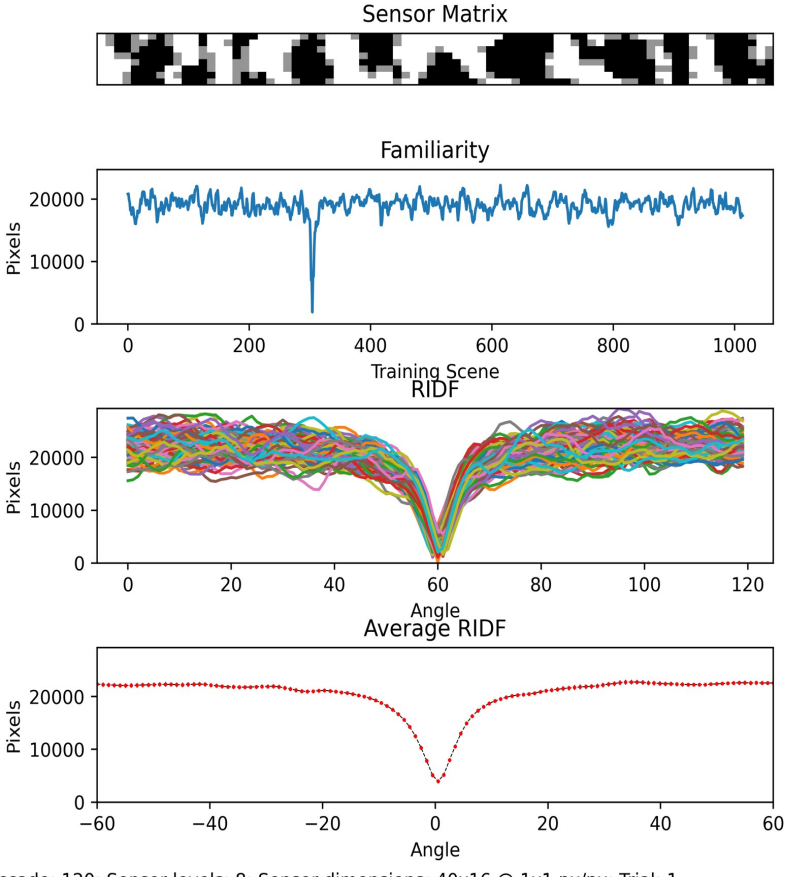




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

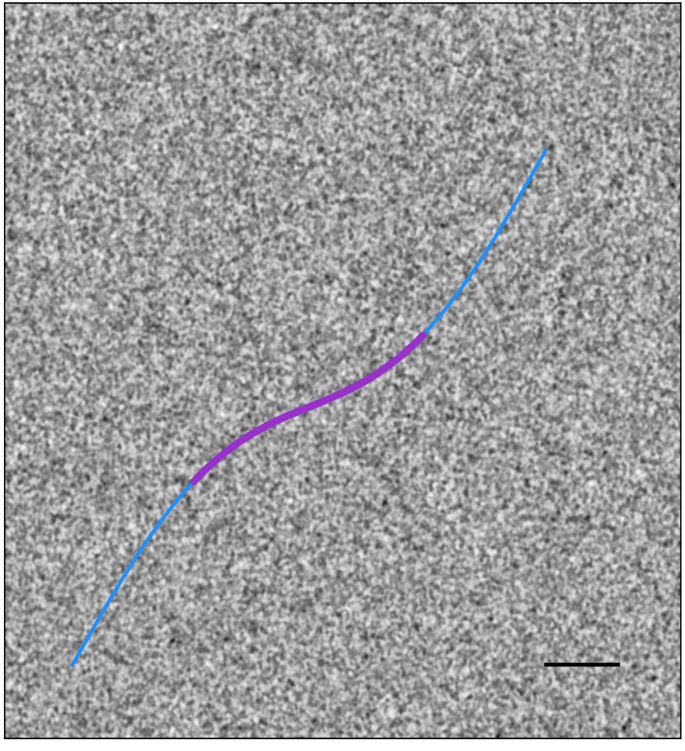
Navigation stats: RMSD error: 62.67; RMSD/dist: 0.157; TD: 13619; p90: 14; p50: 6; complete: 0

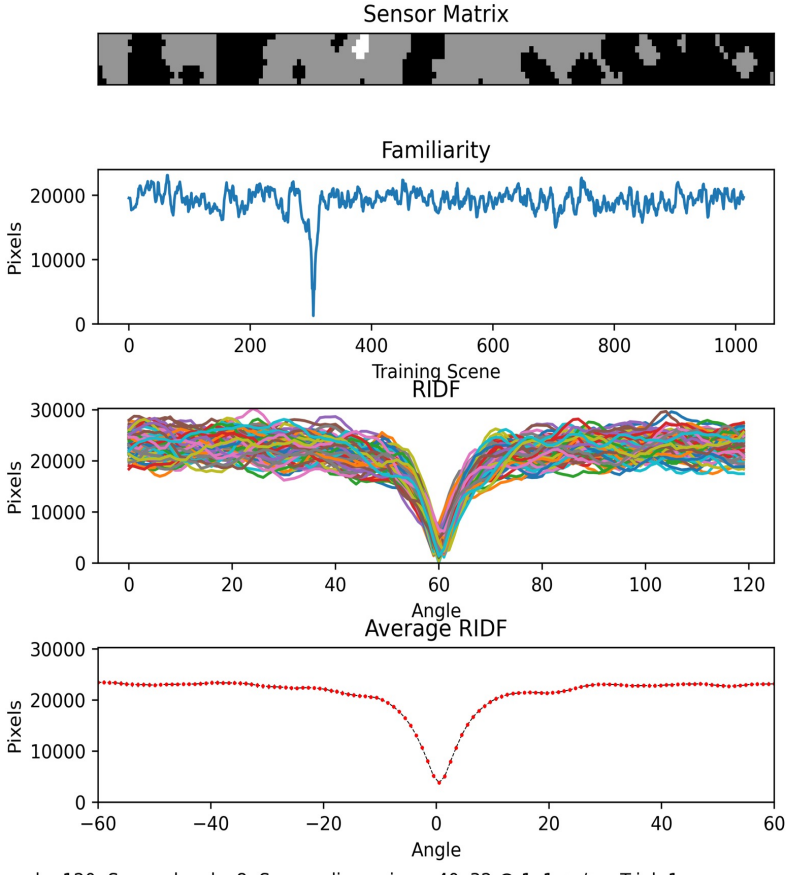




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

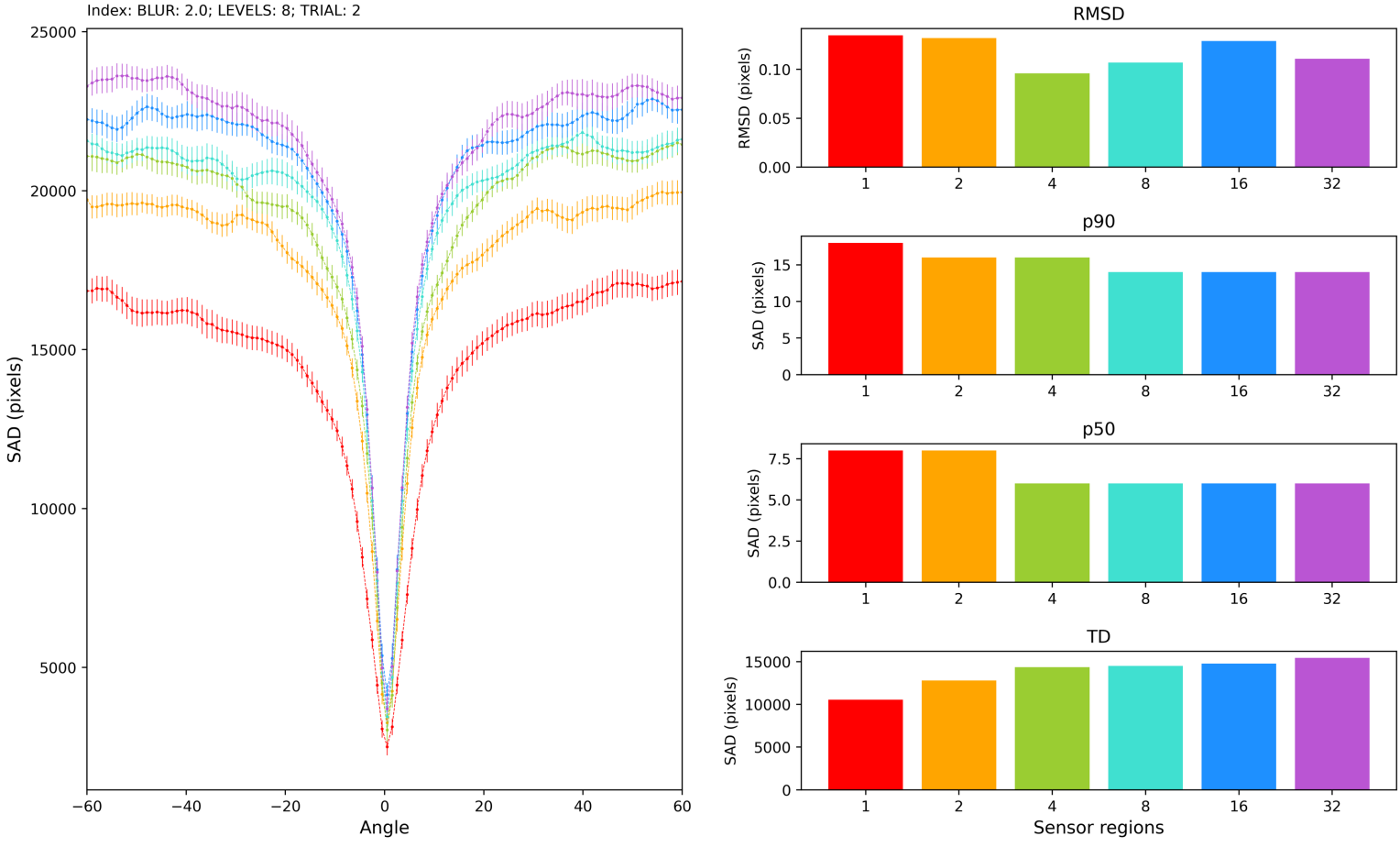
Navigation stats: RMSD error: 52.54; RMSD/dist: 0.131; TD: 14932; p90: 16; p50: 8; complete: 0

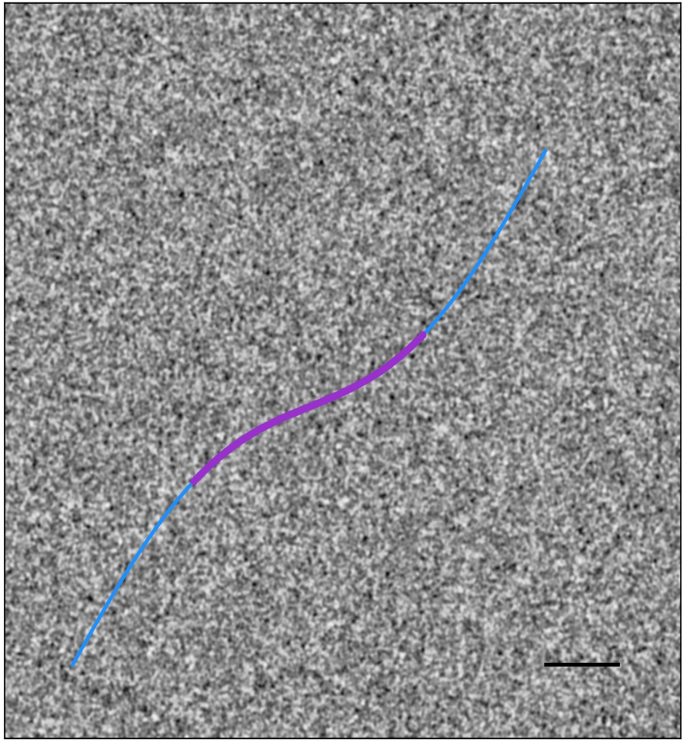


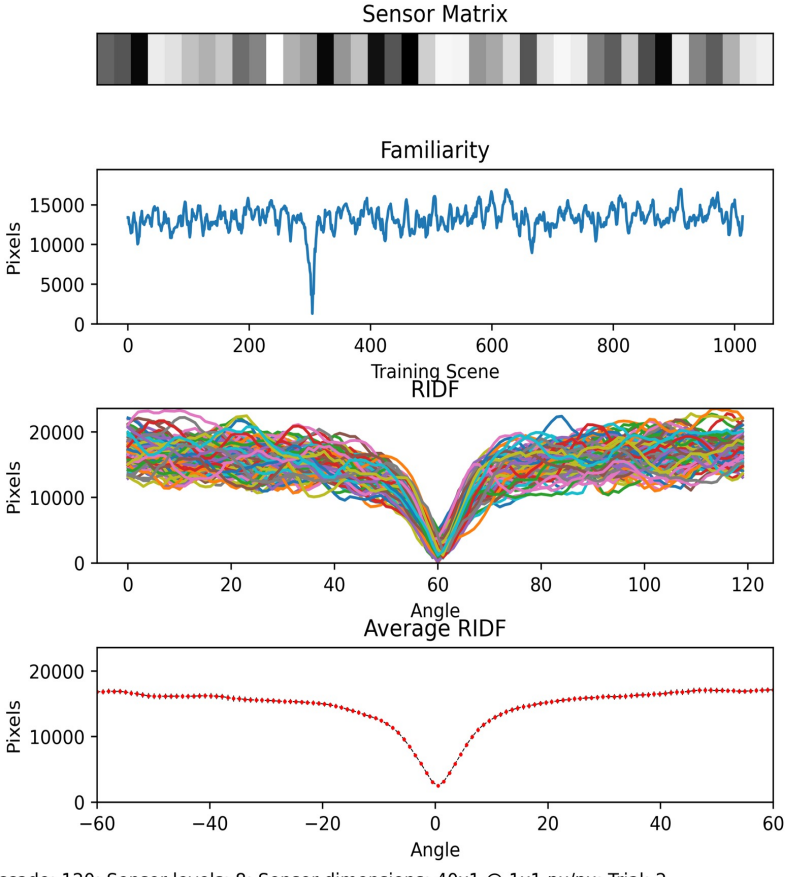


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 42.17; RMSD/dist: 0.105; TD: 15434; p90: 14; p50: 6; complete: 0

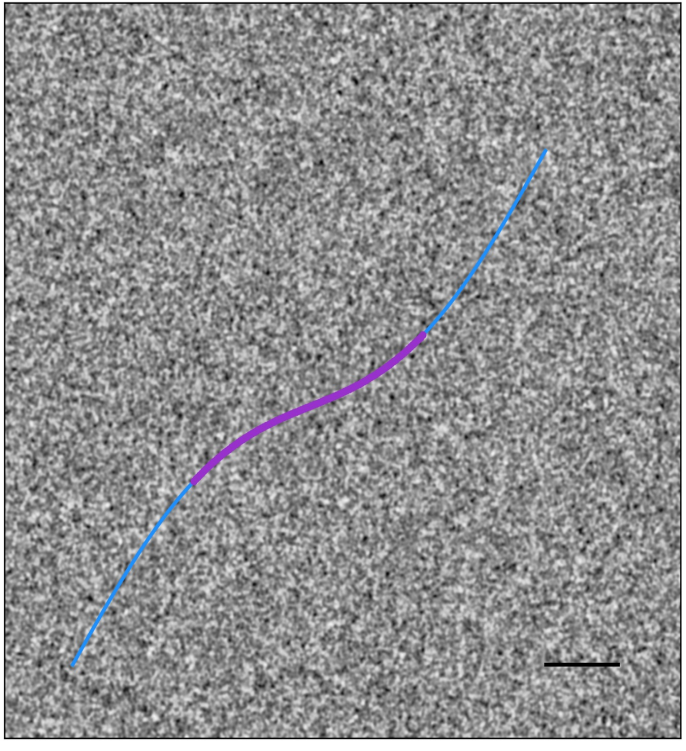

Index: BLUR: 2.0; LEVELS: 8; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

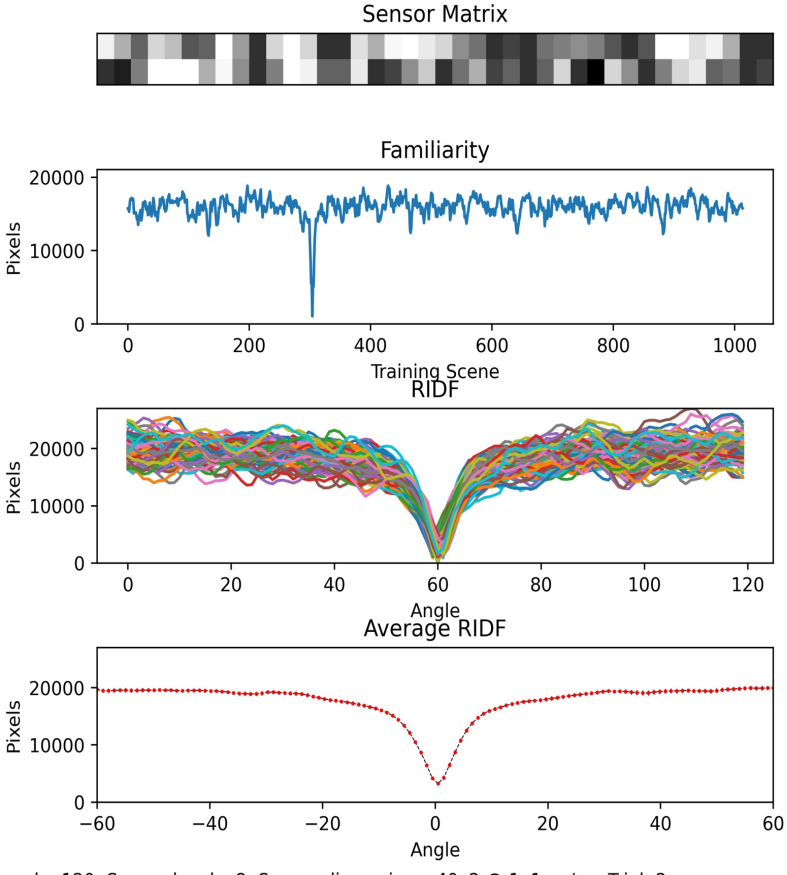




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

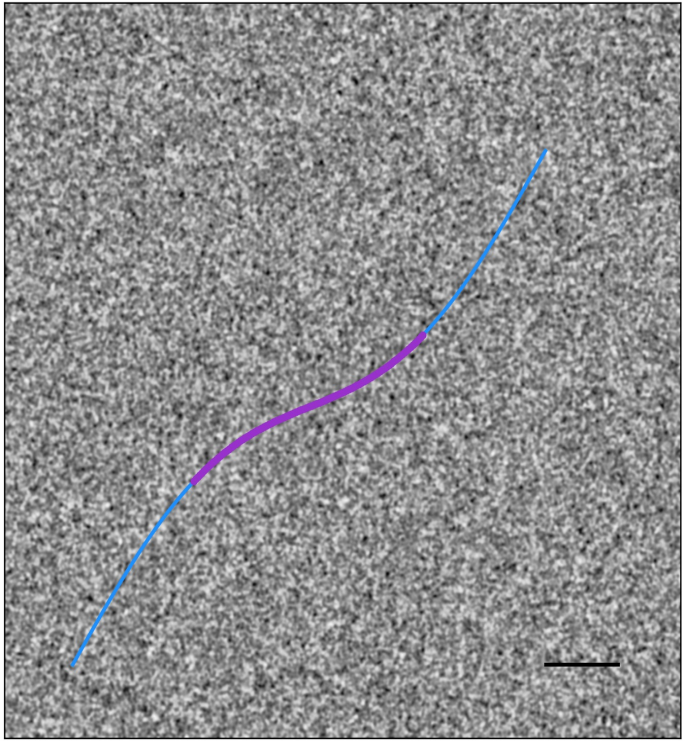
Navigation stats: RMSD error: 53.85; RMSD/dist: 0.135; TD: 10552; p90: 18; p50: 8; complete: 0

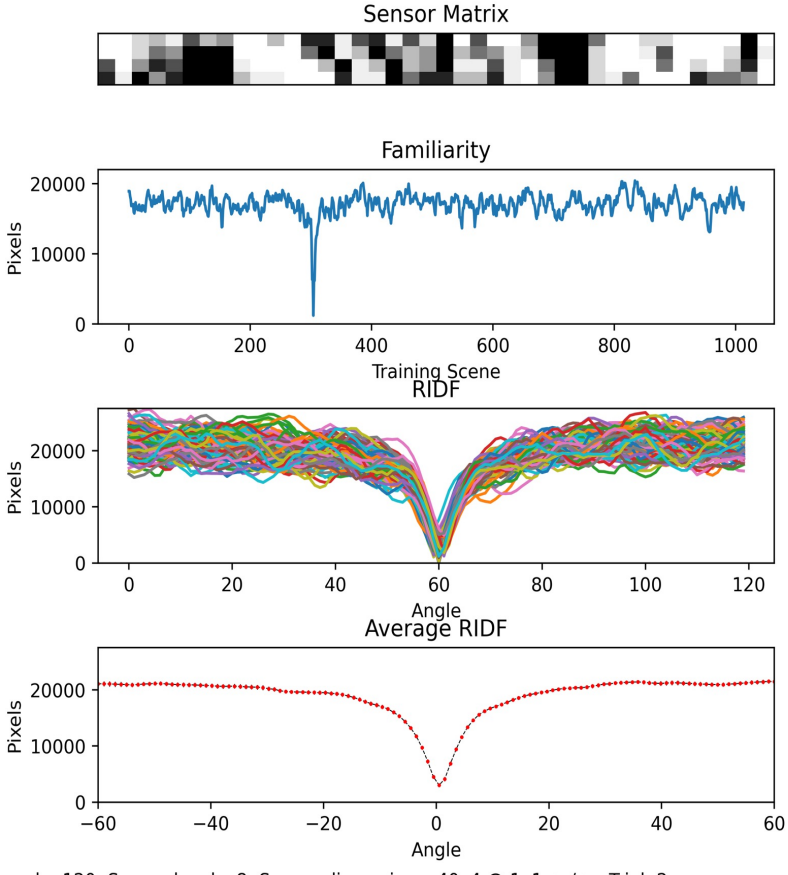




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

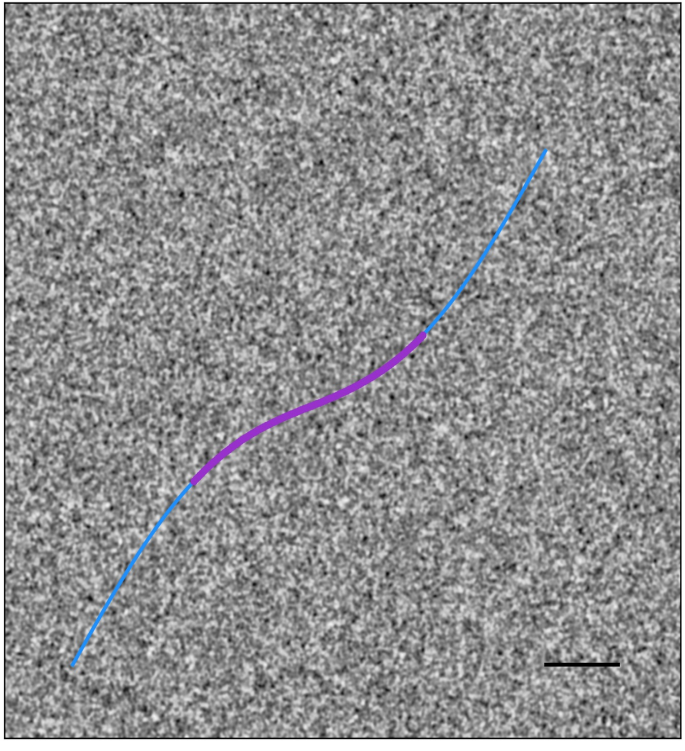
Navigation stats: RMSD error: 52.93; RMSD/dist: 0.132; TD: 12809; p90: 16; p50: 8; complete: 0

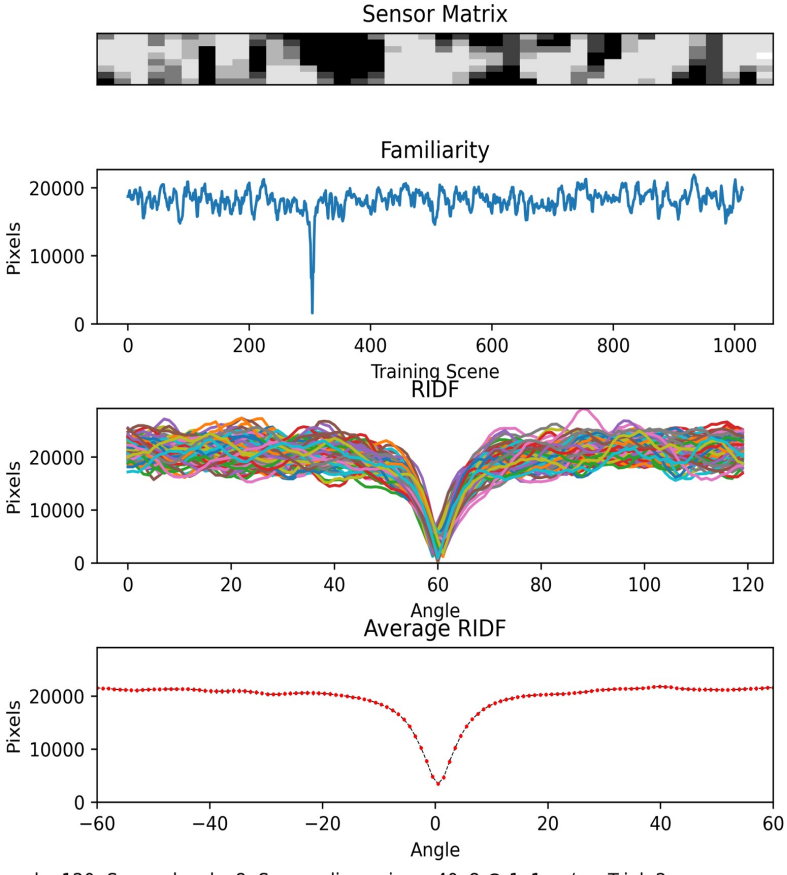




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

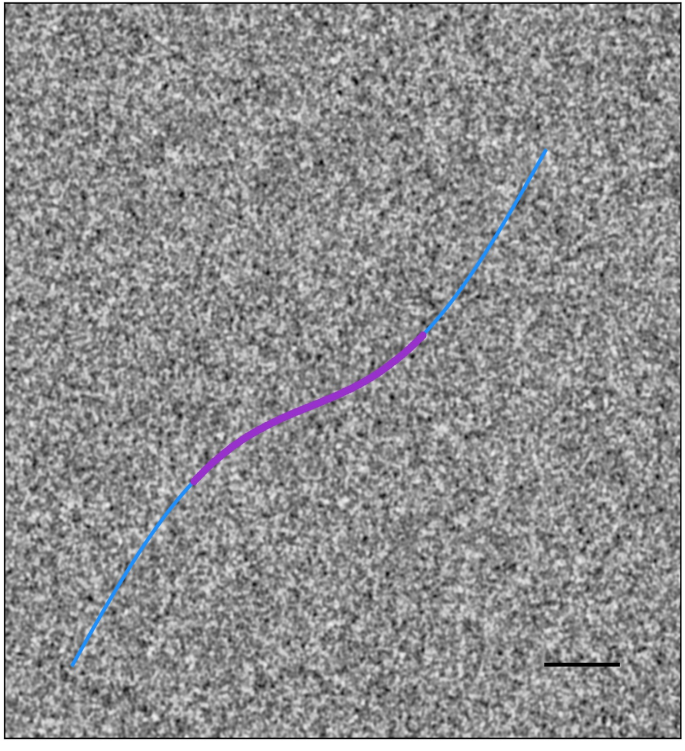
Navigation stats: RMSD error: 38.31; RMSD/dist: 0.096; TD: 14352; p90: 16; p50: 6; complete: 0

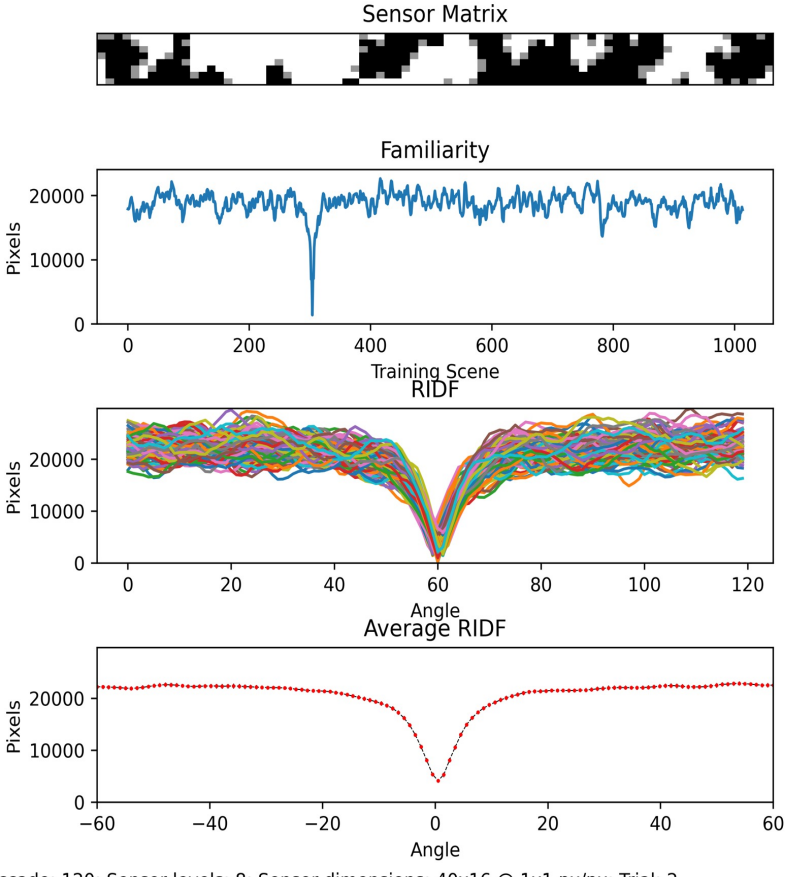




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

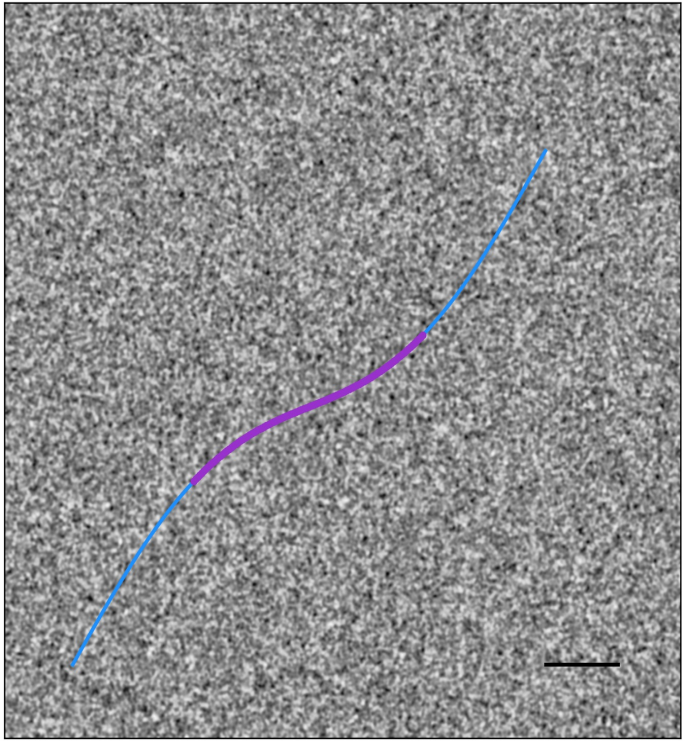
Navigation stats: RMSD error: 42.72; RMSD/dist: 0.107; TD: 14499; p90: 14; p50: 6; complete: 0

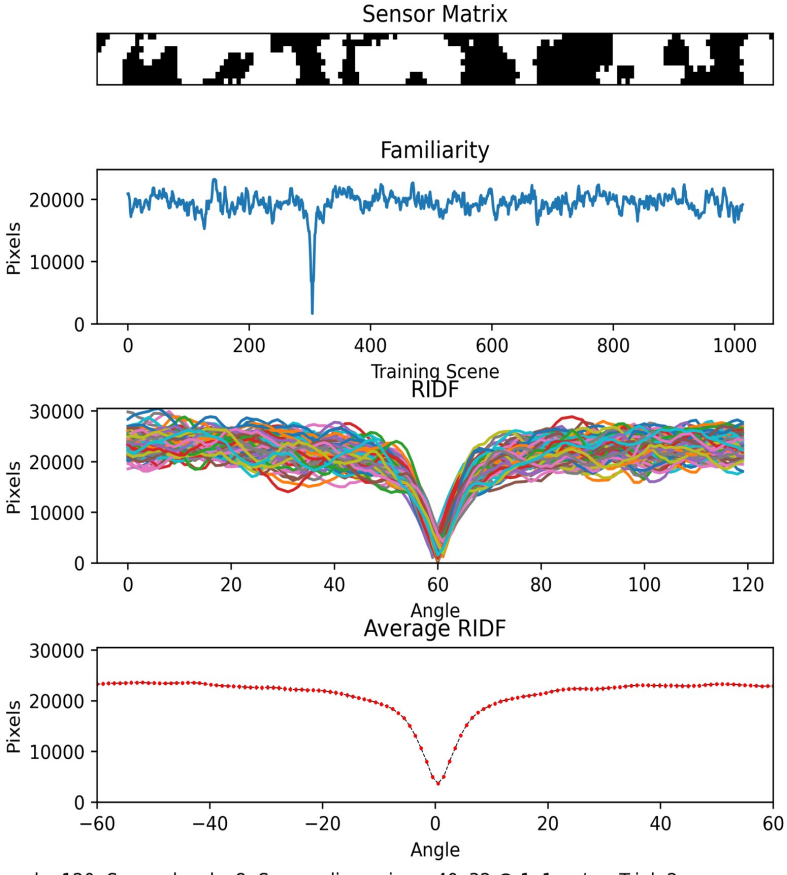




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

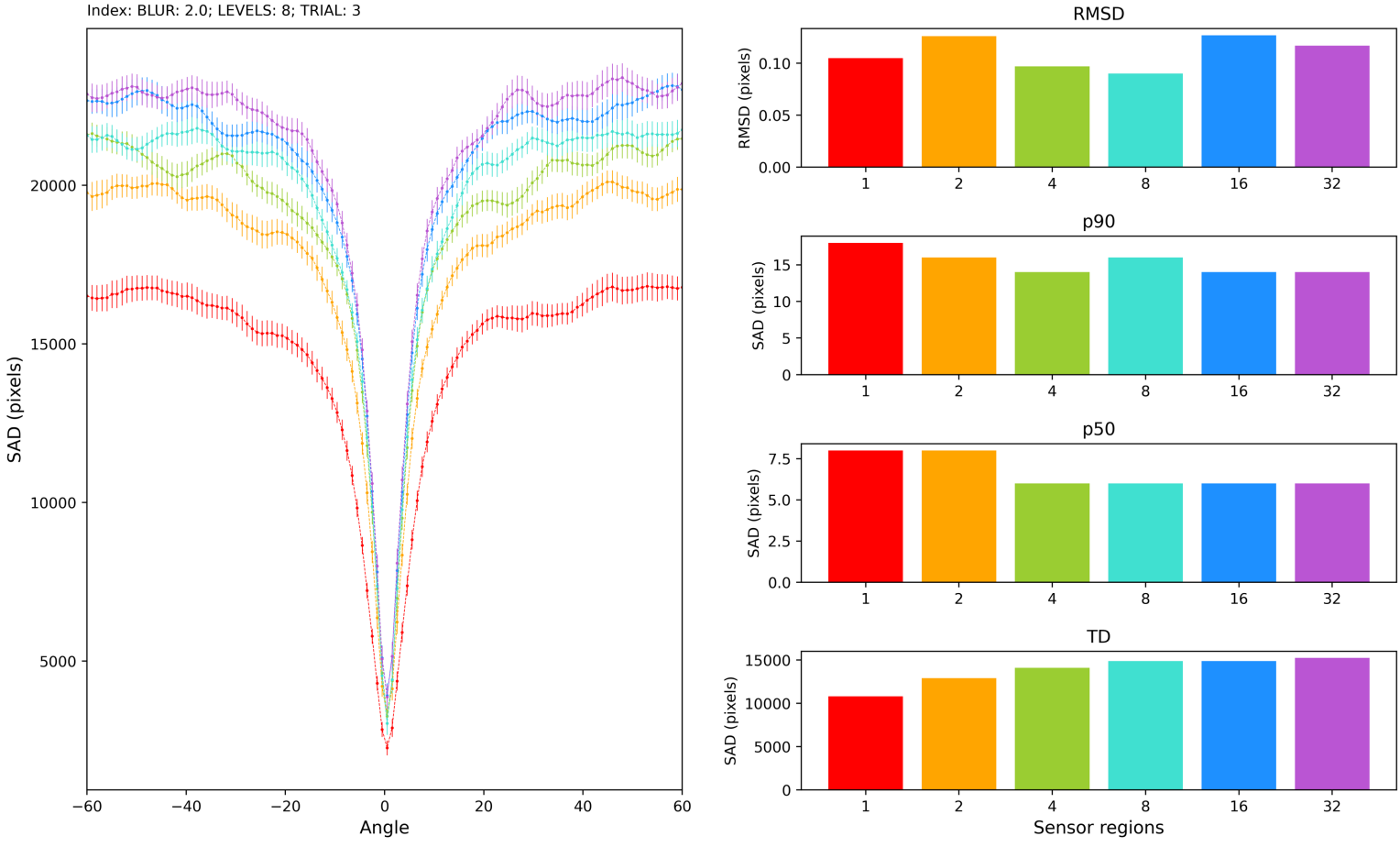
Navigation stats: RMSD error: 51.72; RMSD/dist: 0.129; TD: 14768; p90: 14; p50: 6; complete: 0

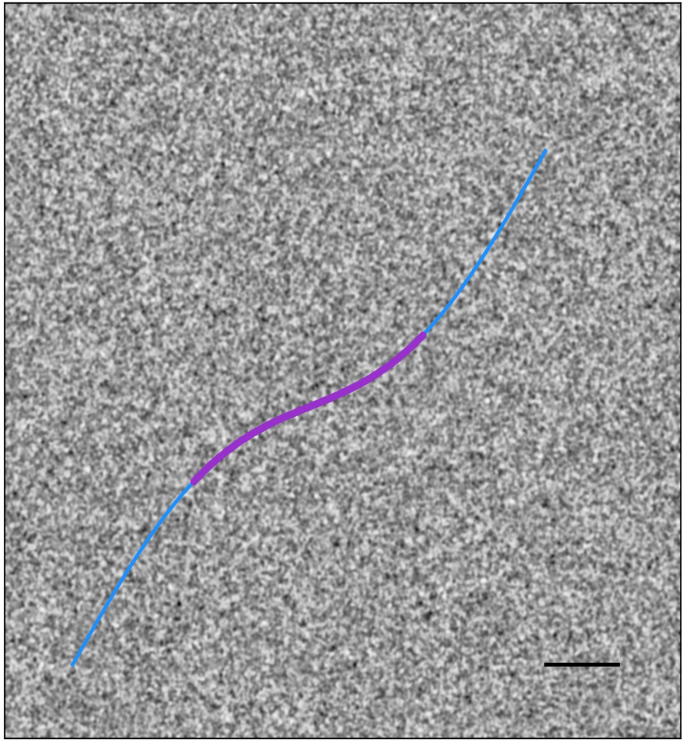


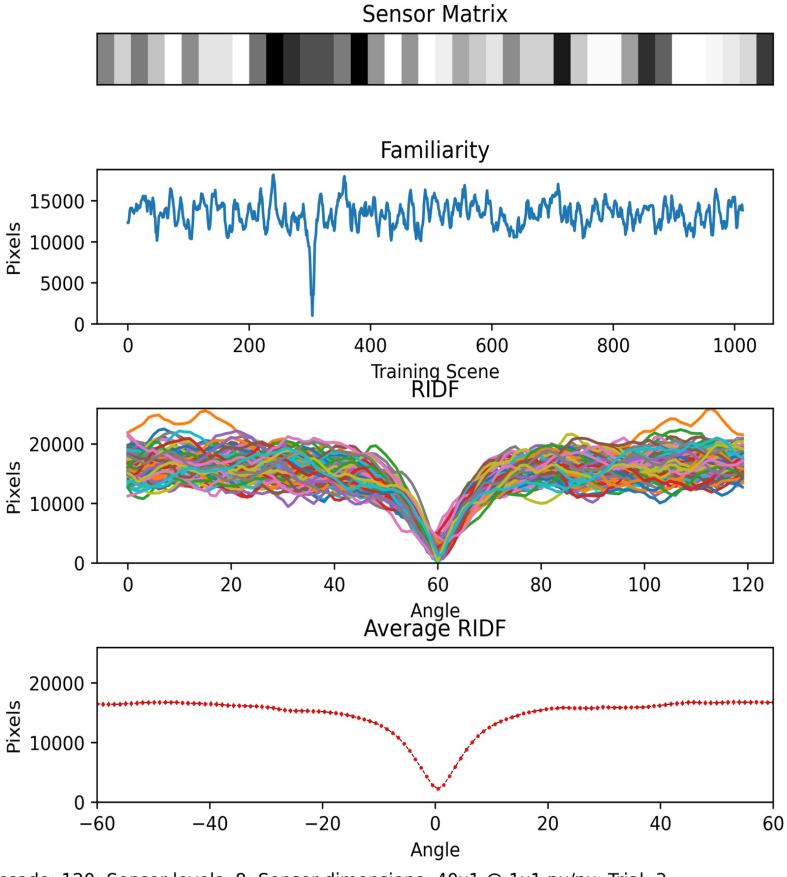


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 44.30; RMSD/dist: 0.111; TD: 15430; p90: 14; p50: 6; complete: 0

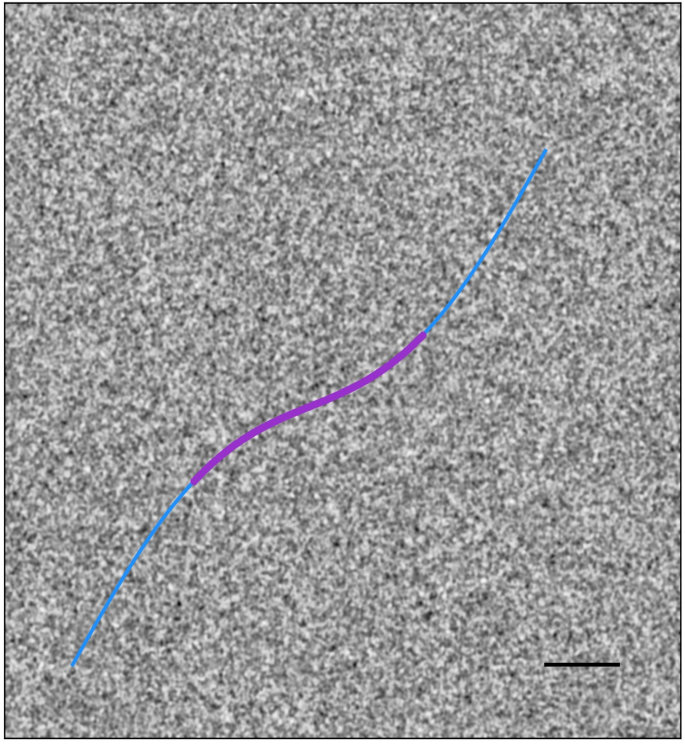

Index: BLUR: 2.0; LEVELS: 8; TRIAL: 3
SAD (pixels)
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

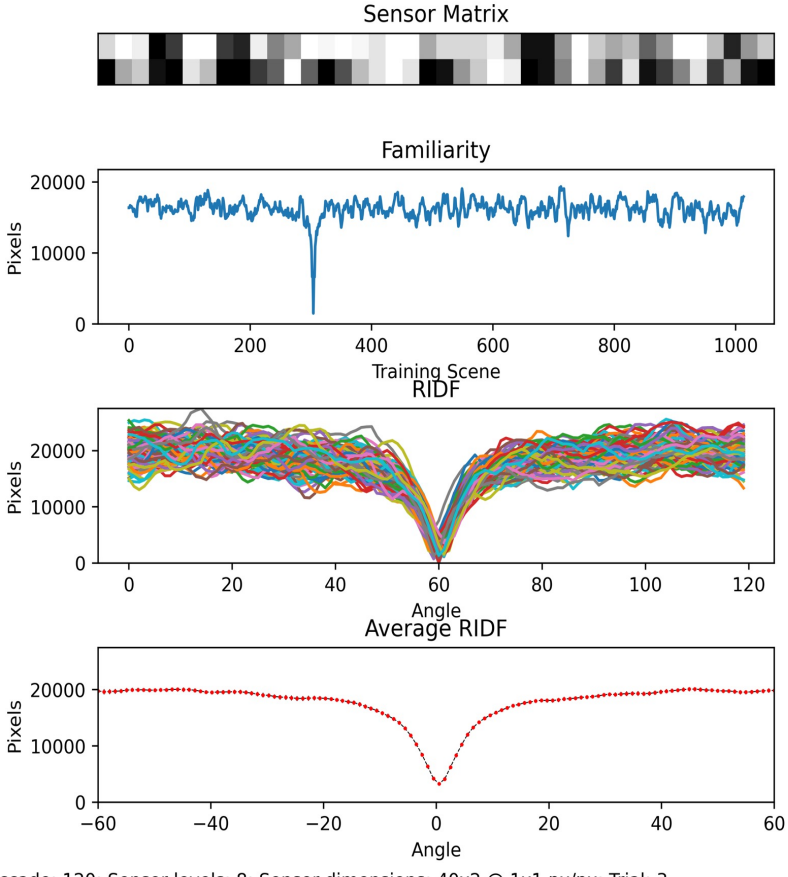




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

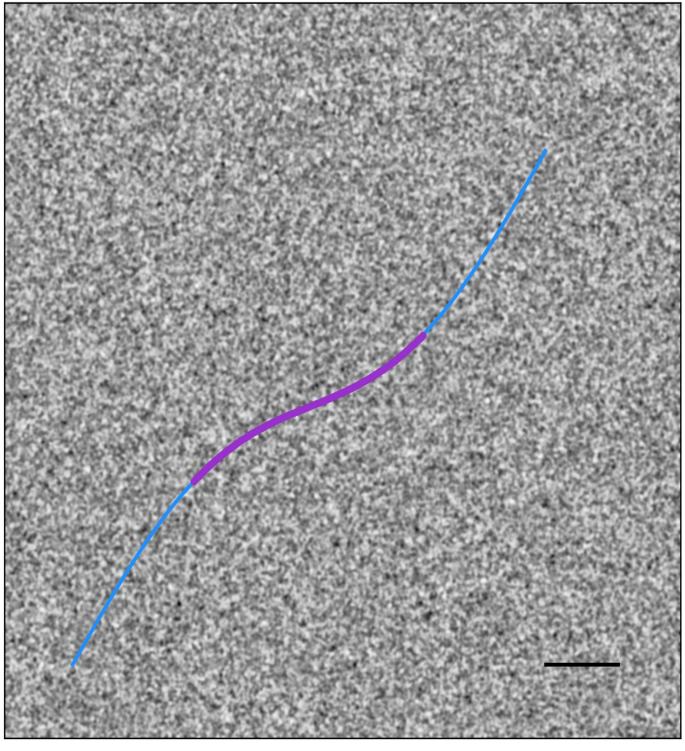
Navigation stats: RMSD error: 41.97; RMSD/dist: 0.105; TD: 10808; p90: 18; p50: 8; complete: 0

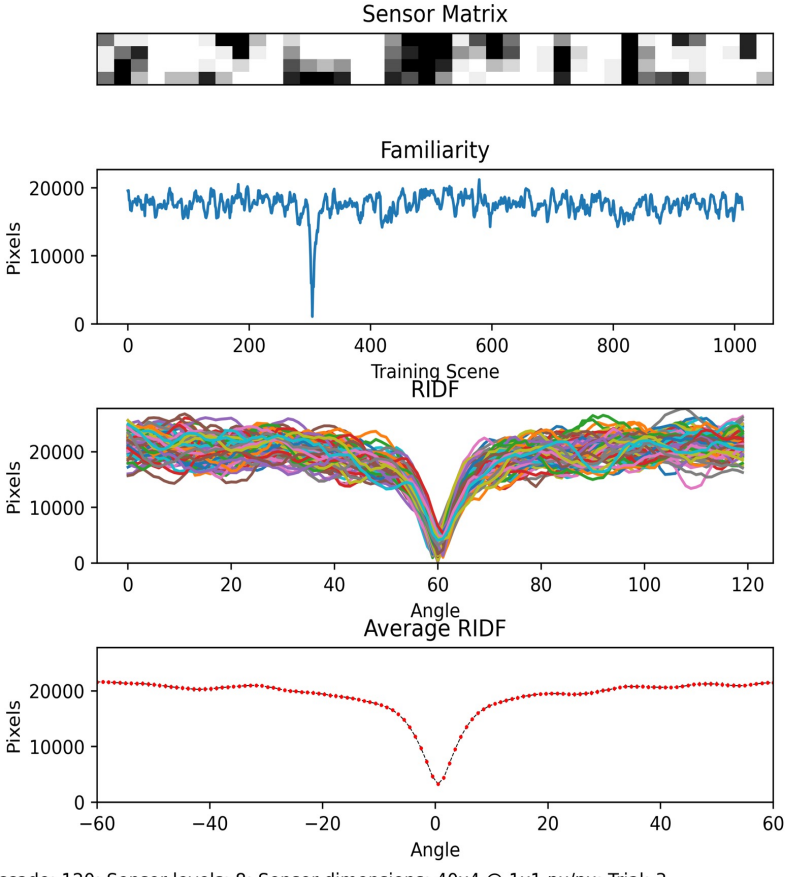




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

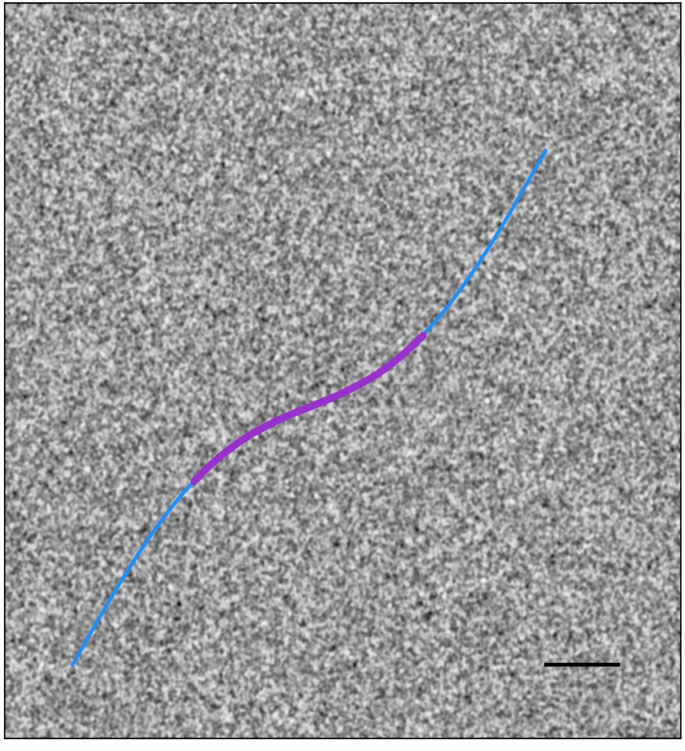
Navigation stats: RMSD error: 50.55; RMSD/dist: 0.126; TD: 12894; p90: 16; p50: 8; complete: 0

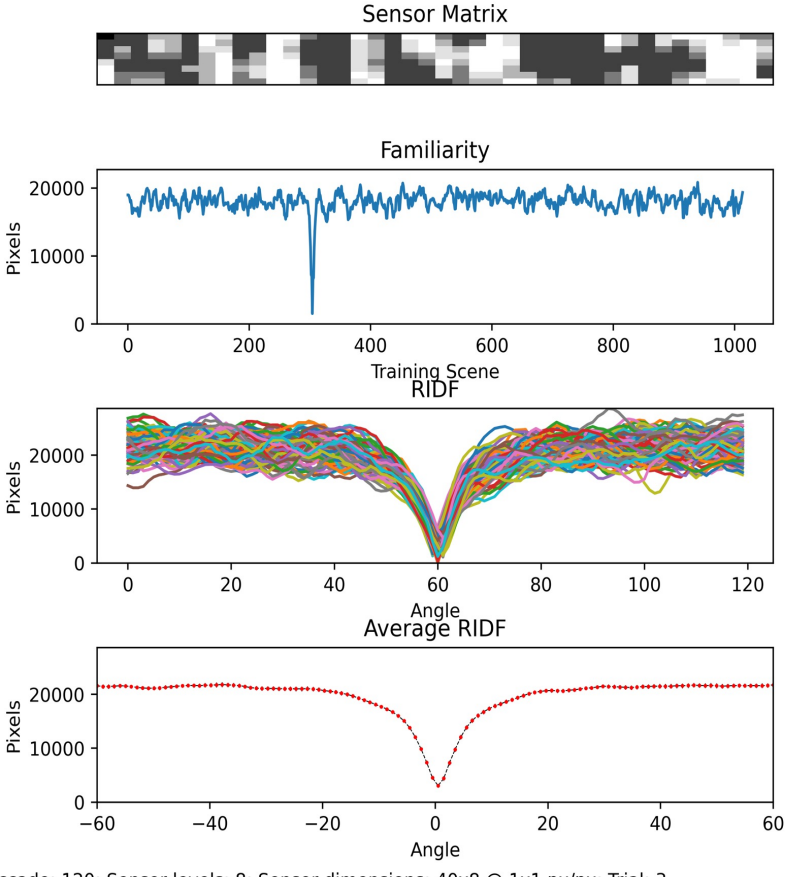




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

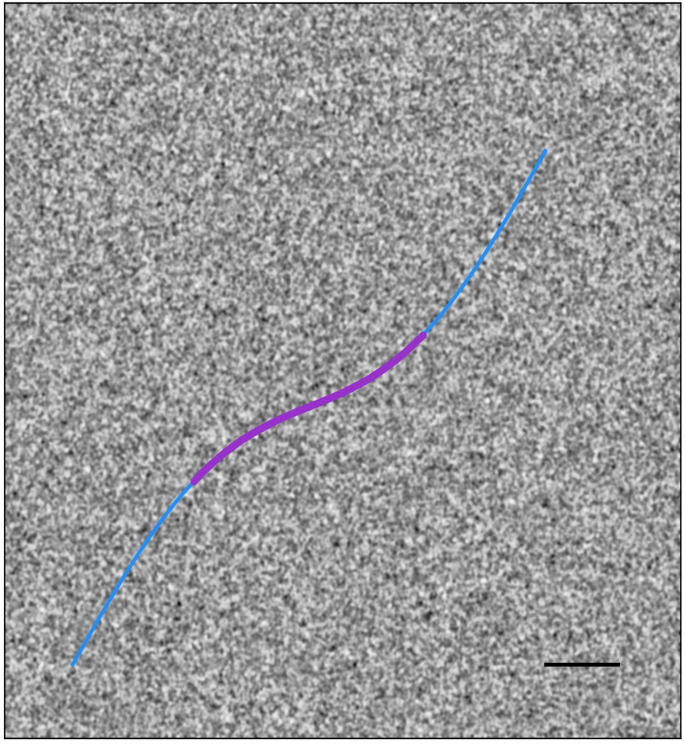
Navigation stats: RMSD error: 38.95; RMSD/dist: 0.097; TD: 14098; p90: 14; p50: 6; complete: 0

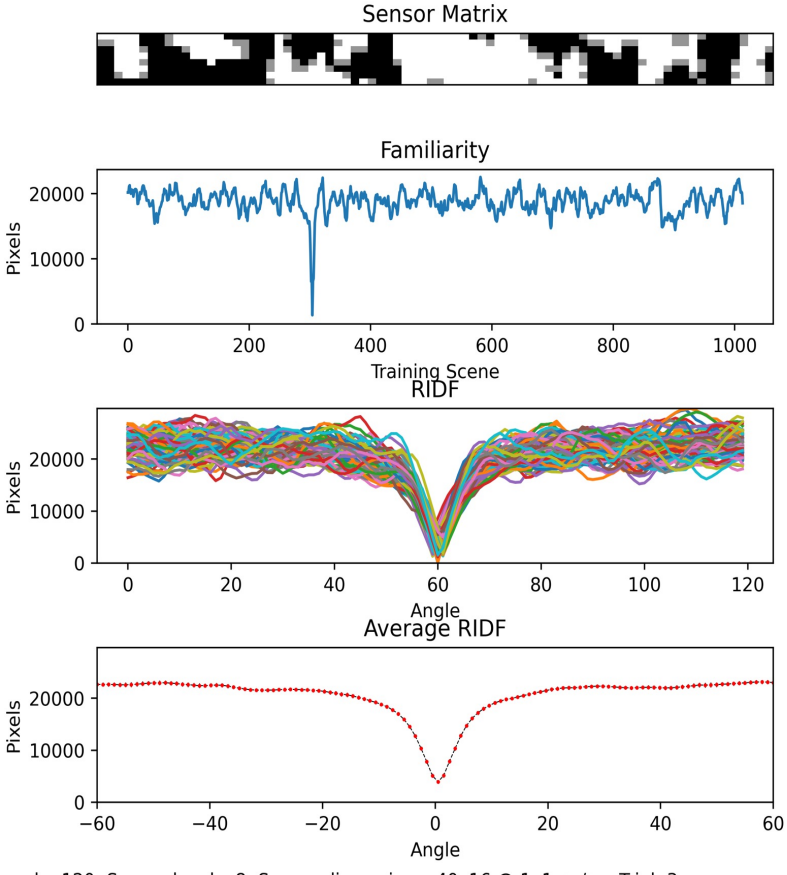




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

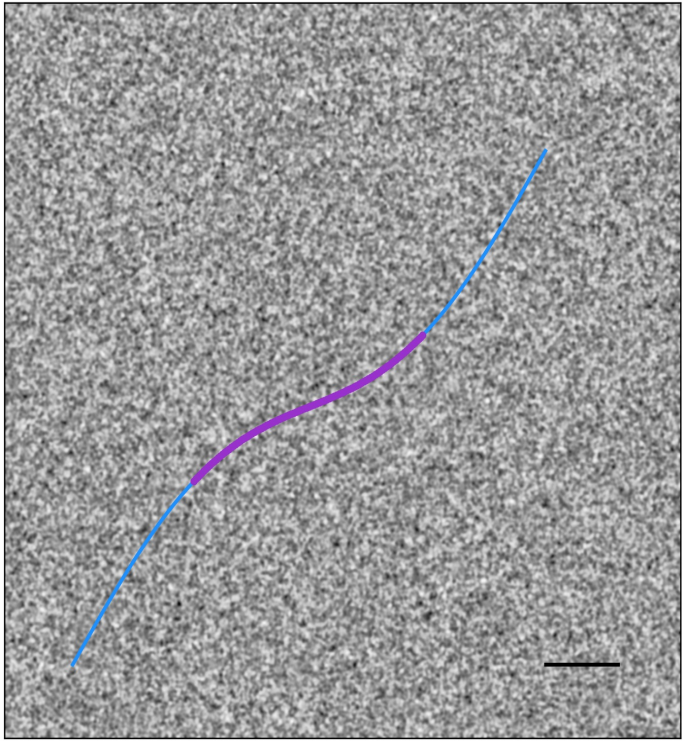
Navigation stats: RMSD error: 35.88; RMSD/dist: 0.090; TD: 14878; p90: 16; p50: 6; complete: 0

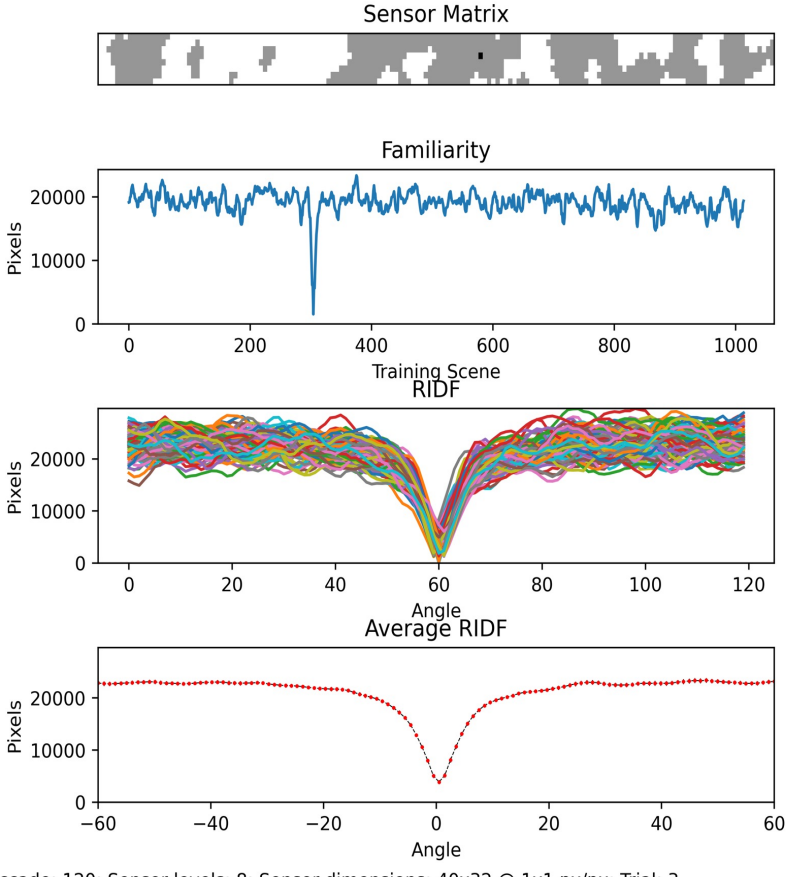




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

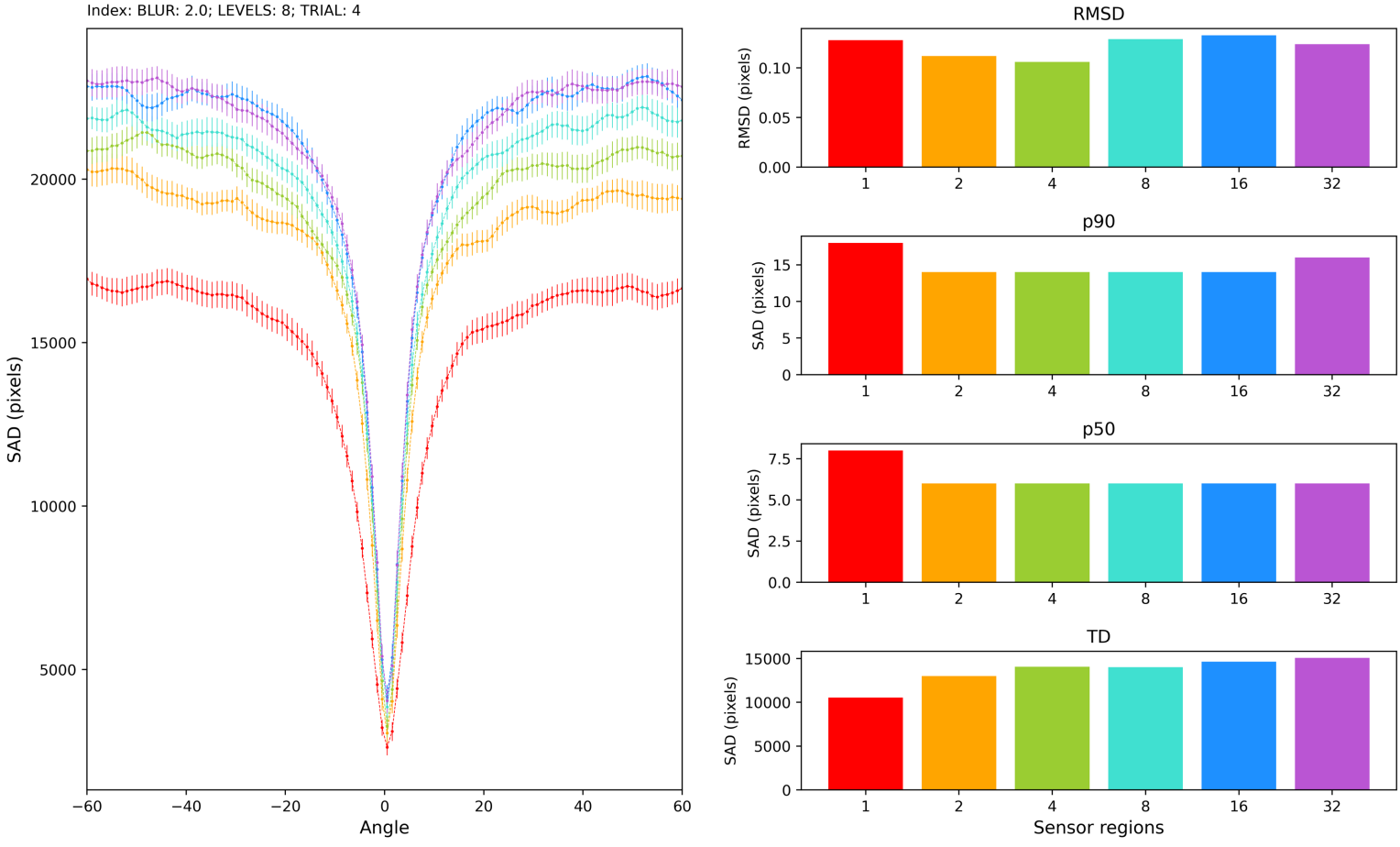
Navigation stats: RMSD error: 50.71; RMSD/dist: 0.127; TD: 14861; p90: 14; p50: 6; complete: 0

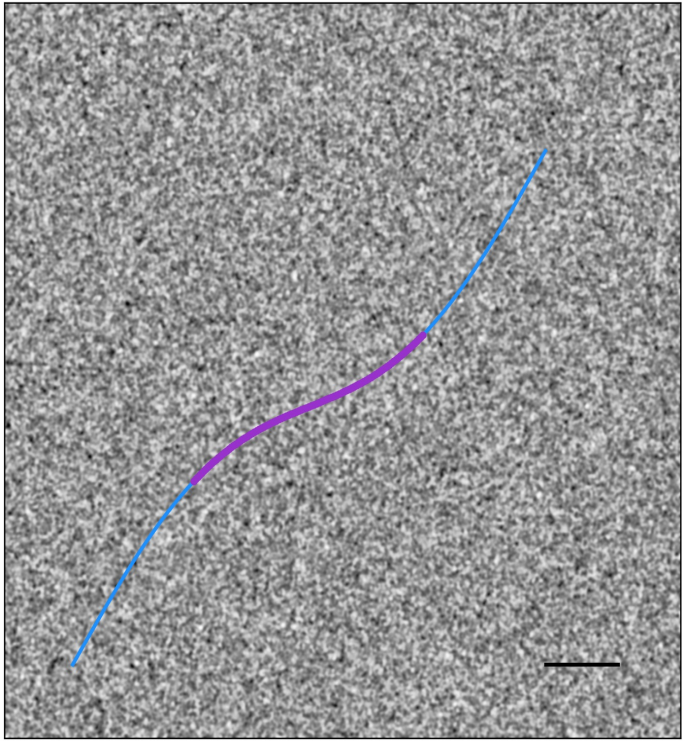


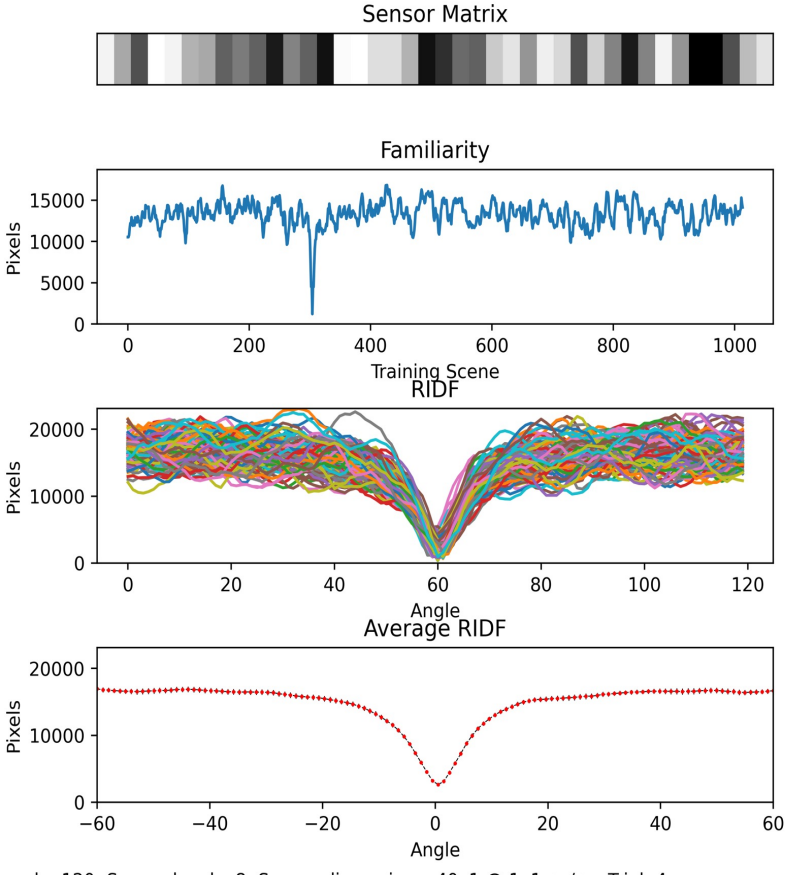


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 46.71; RMSD/dist: 0.117; TD: 15223; p90: 14; p50: 6; complete: 0

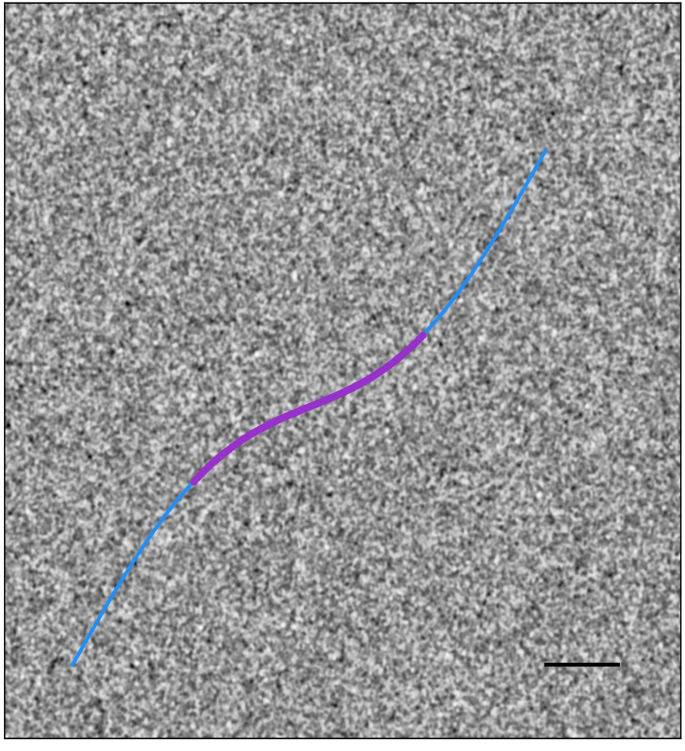

Index: BLUR: 2.0; LEVELS: 8; TRIAL: 4
SAD (pixels)
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

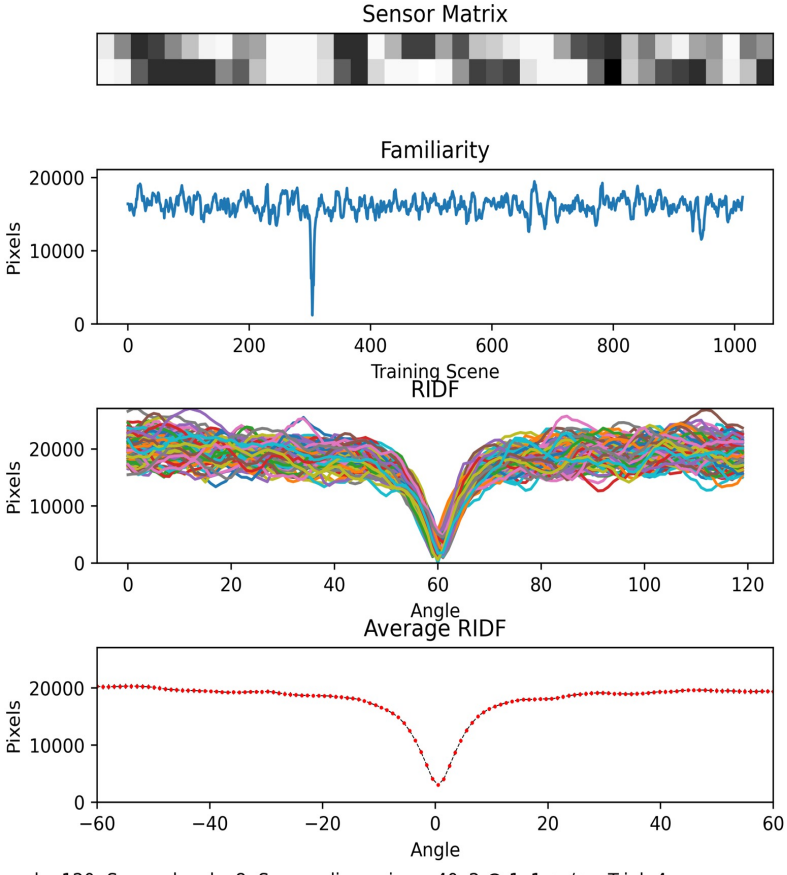




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

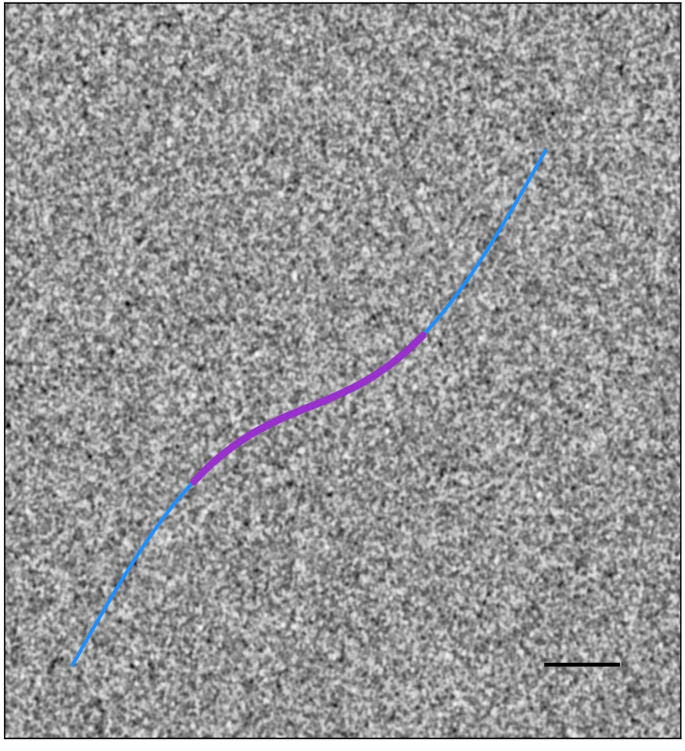
Navigation stats: RMSD error: 51.09; RMSD/dist: 0.128; TD: 10532; p90: 18; p50: 8; complete: 0

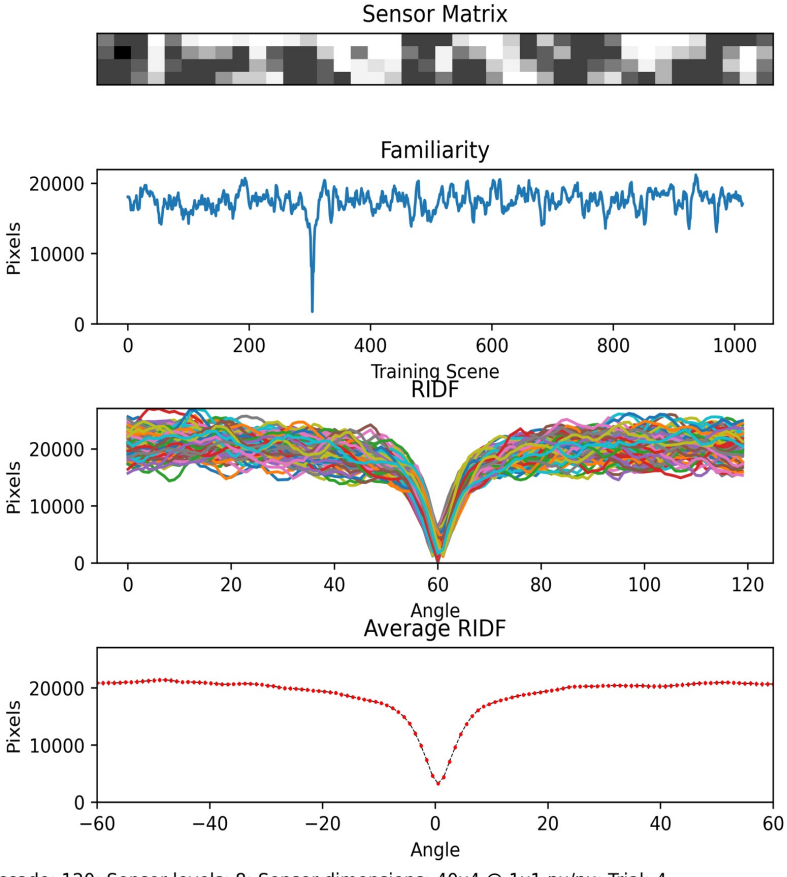




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

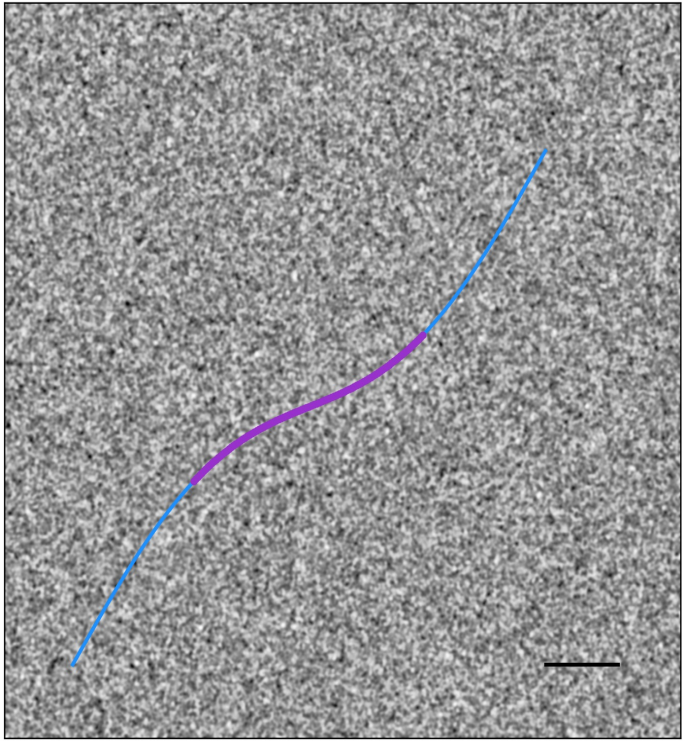
Navigation stats: RMSD error: 44.65; RMSD/dist: 0.112; TD: 12996; p90: 14; p50: 6; complete: 0

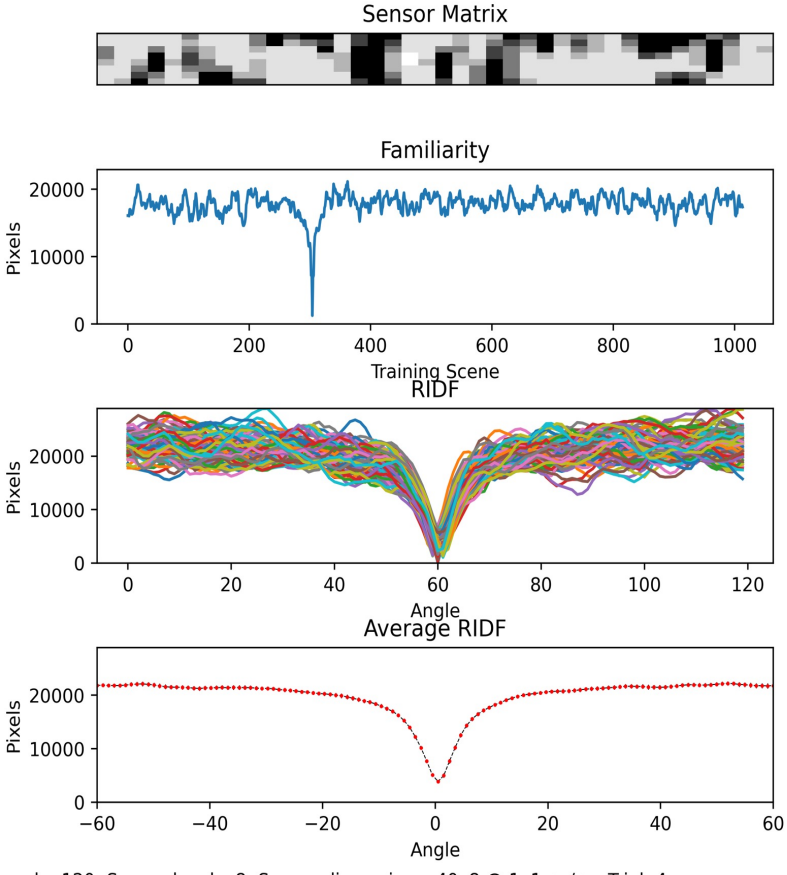




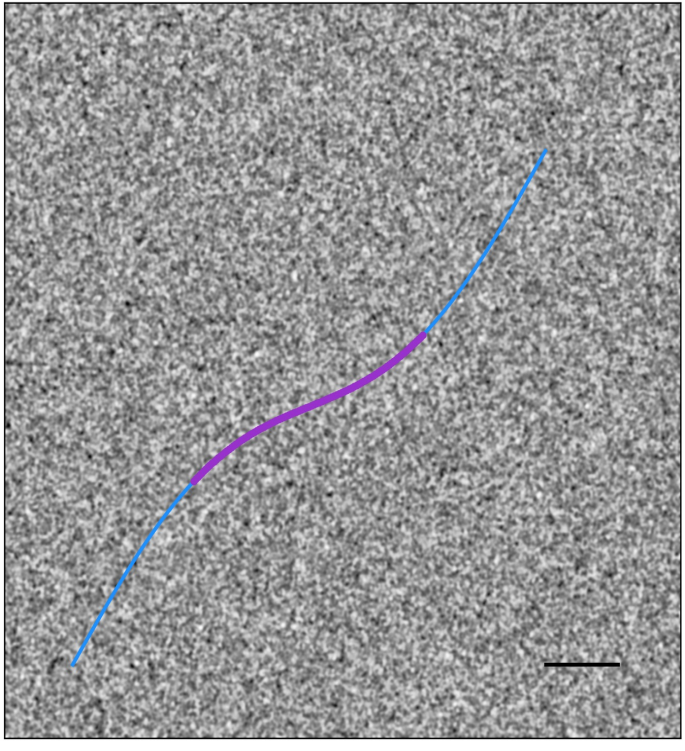
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

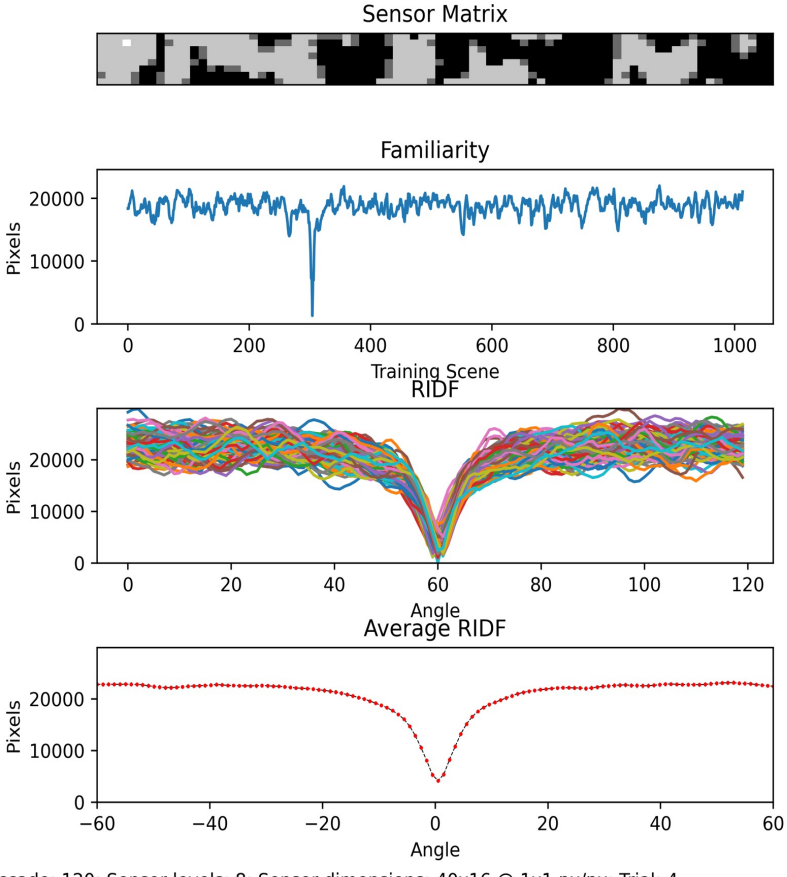
Navigation stats: RMSD error: 42.28; RMSD/dist: 0.106; TD: 14076; p90: 14; p50: 6; complete: 0





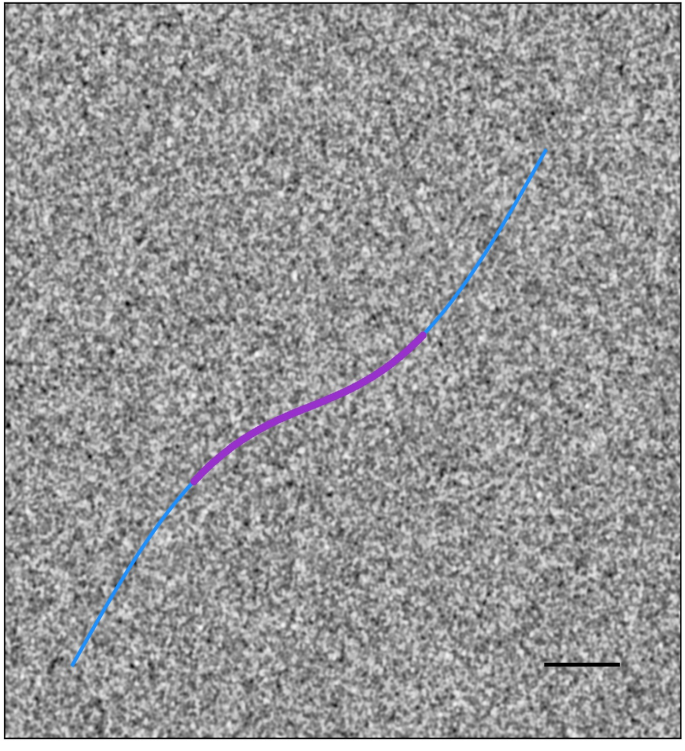
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 51.74; RMSD/dist: 0.129; TD: 14025; p90: 14; p50: 6; complete: 0

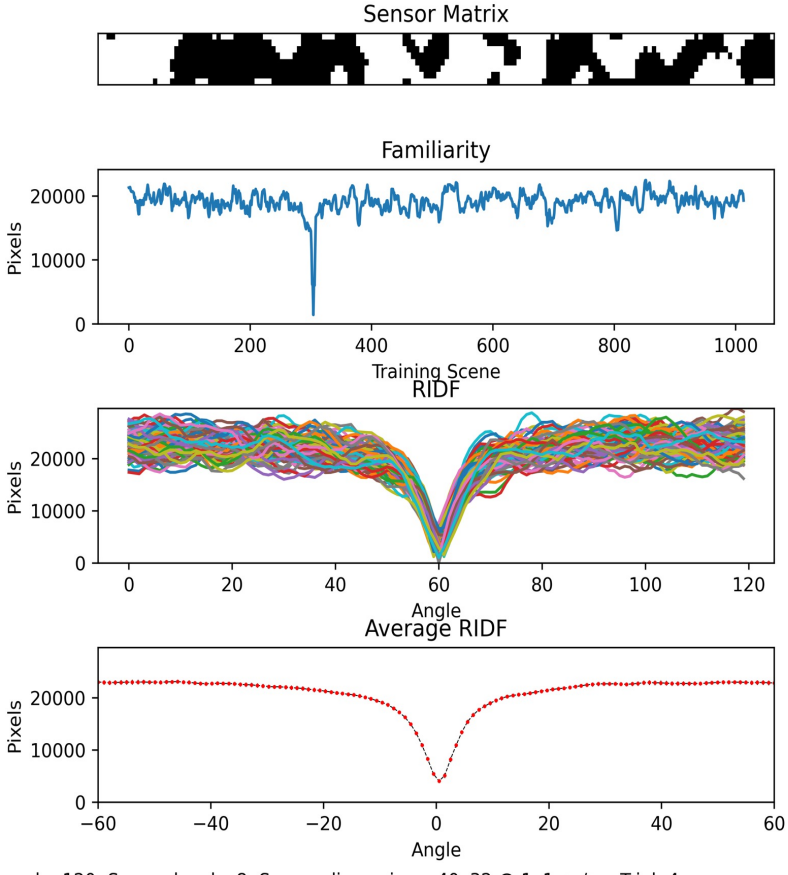




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

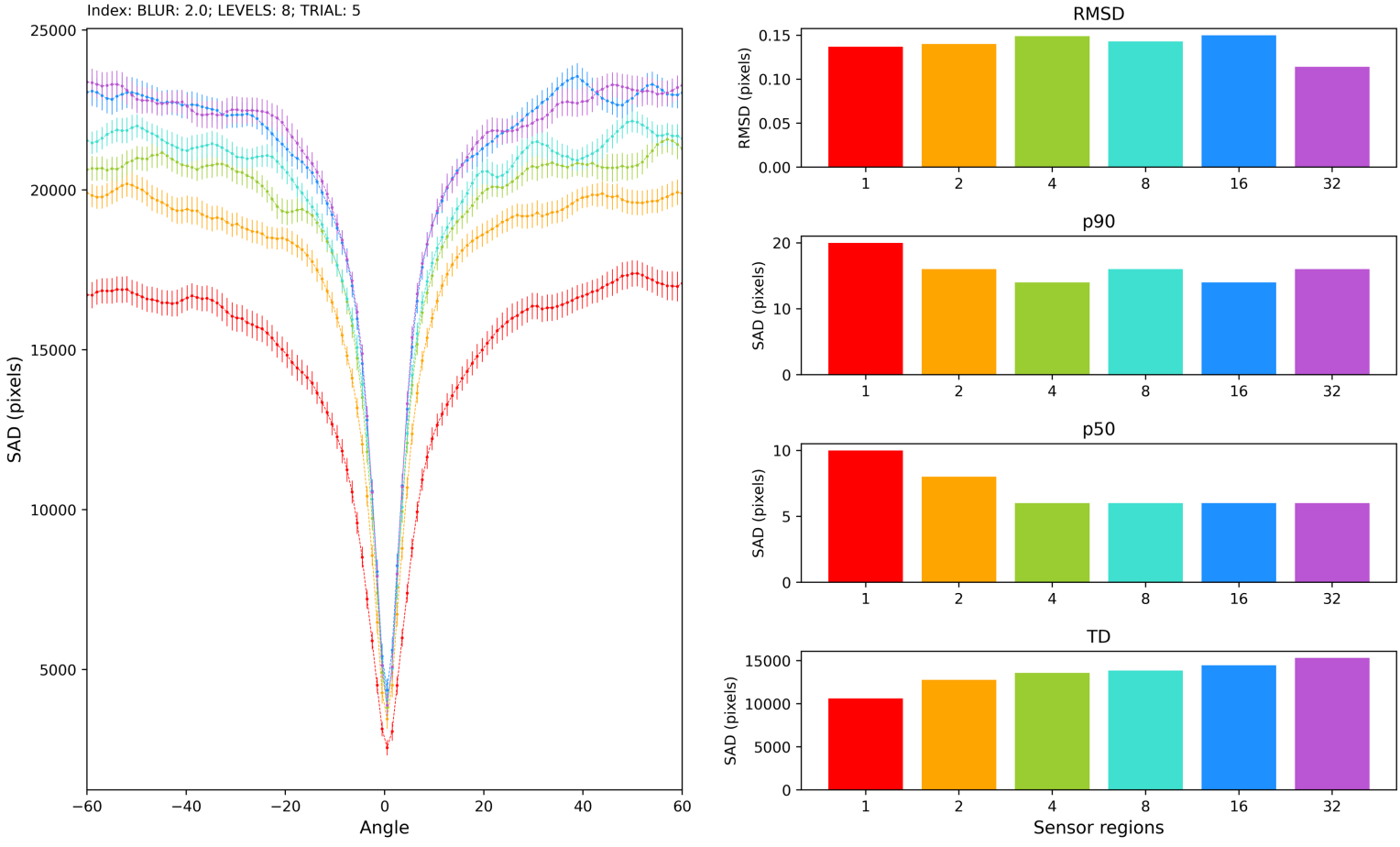
Navigation stats: RMSD error: 53.39; RMSD/dist: 0.133; TD: 14644; p90: 14; p50: 6; complete: 0

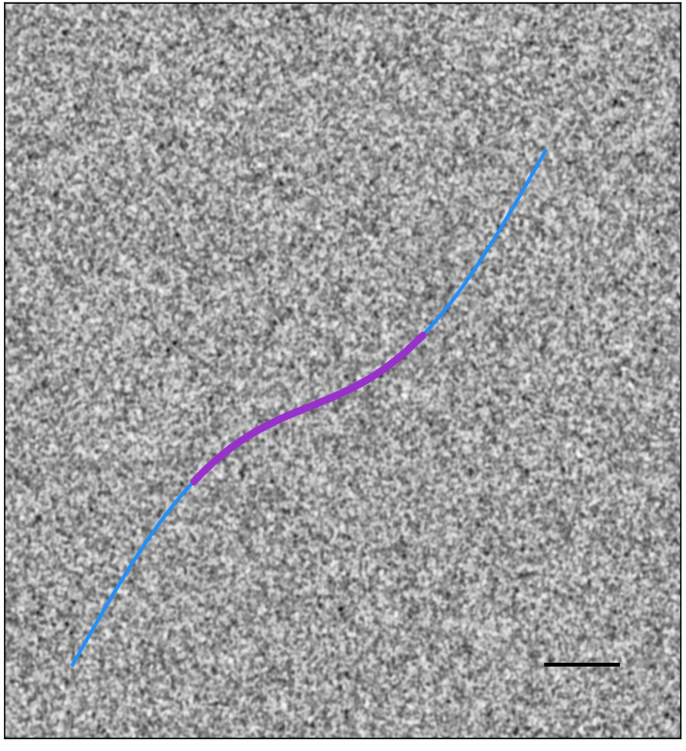


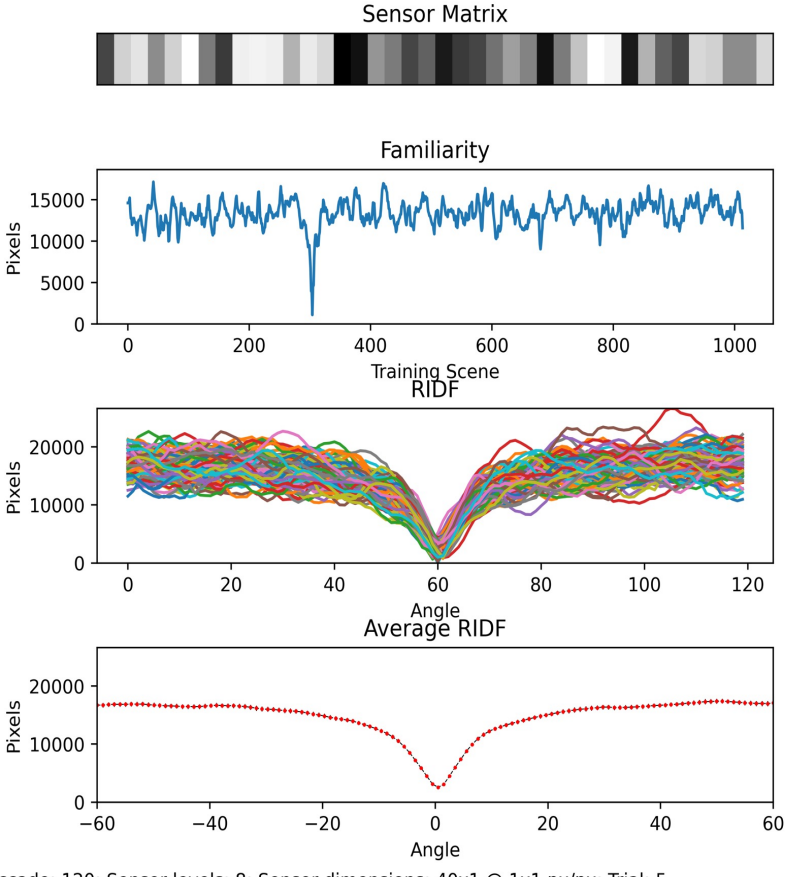


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 49.58; RMSD/dist: 0.124; TD: 15069; p90: 16; p50: 6; complete: 0

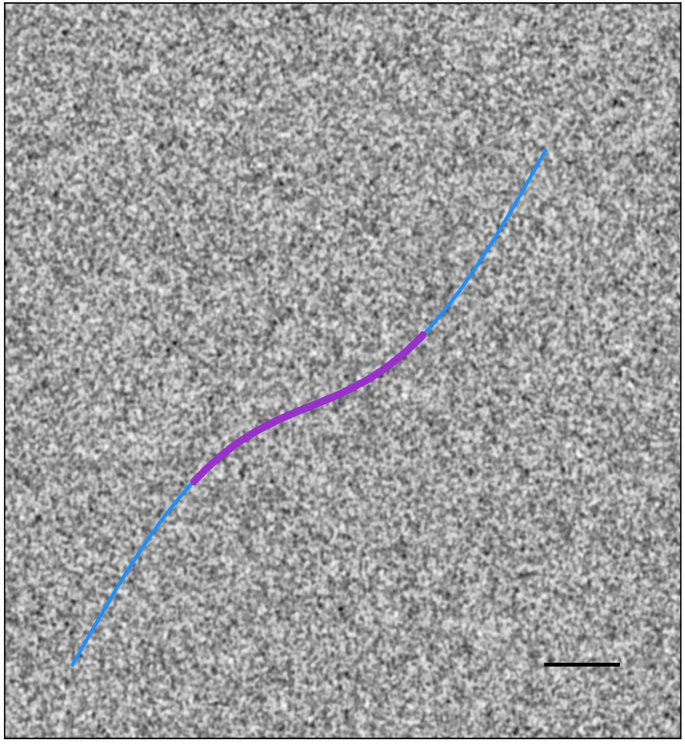

Index: BLUR: 2.0; LEVELS: 8; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

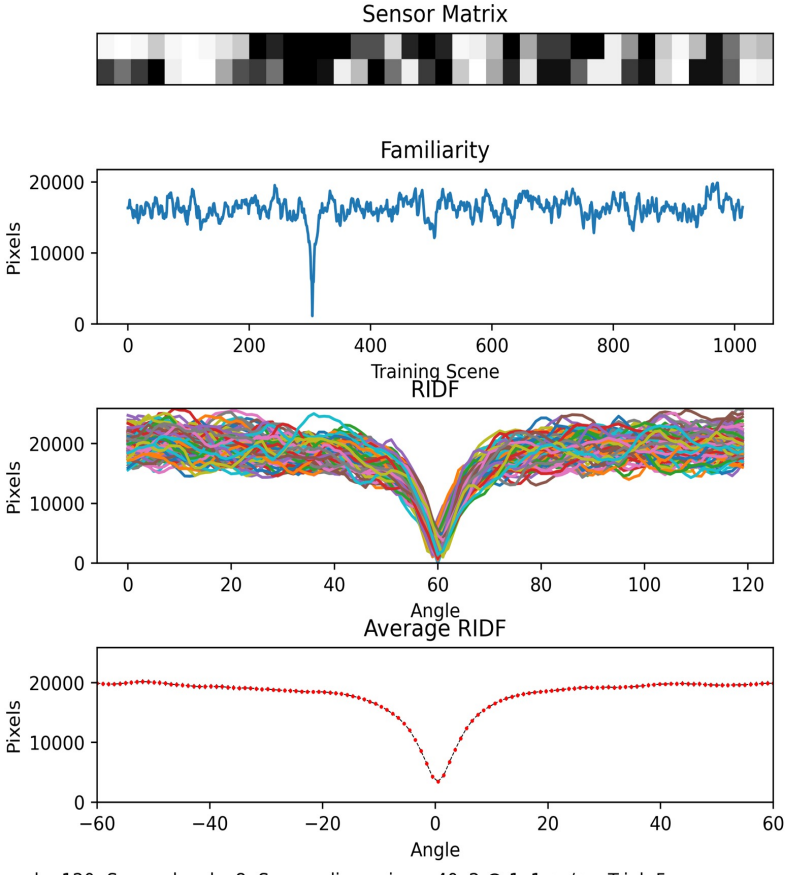




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

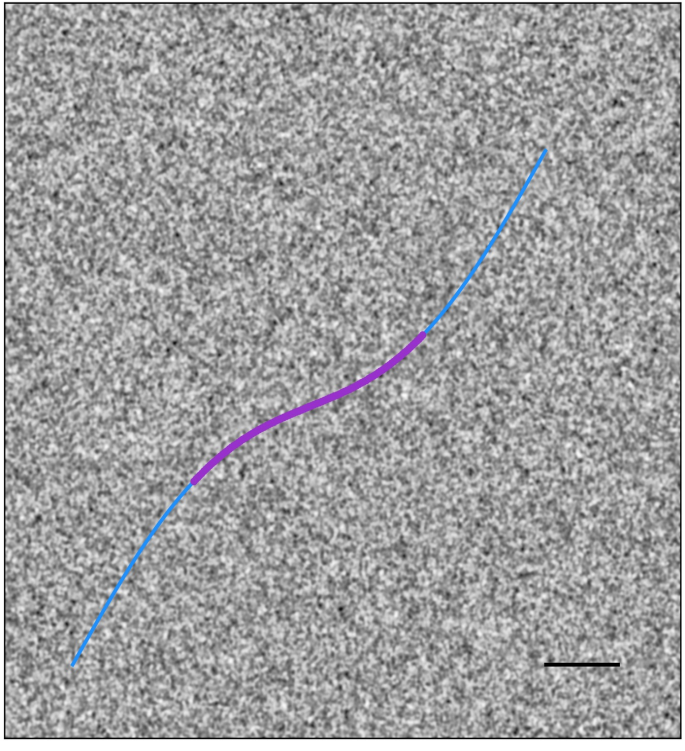
Navigation stats: RMSD error: 54.68; RMSD/dist: 0.137; TD: 10619; p90: 20; p50: 10; complete: 0

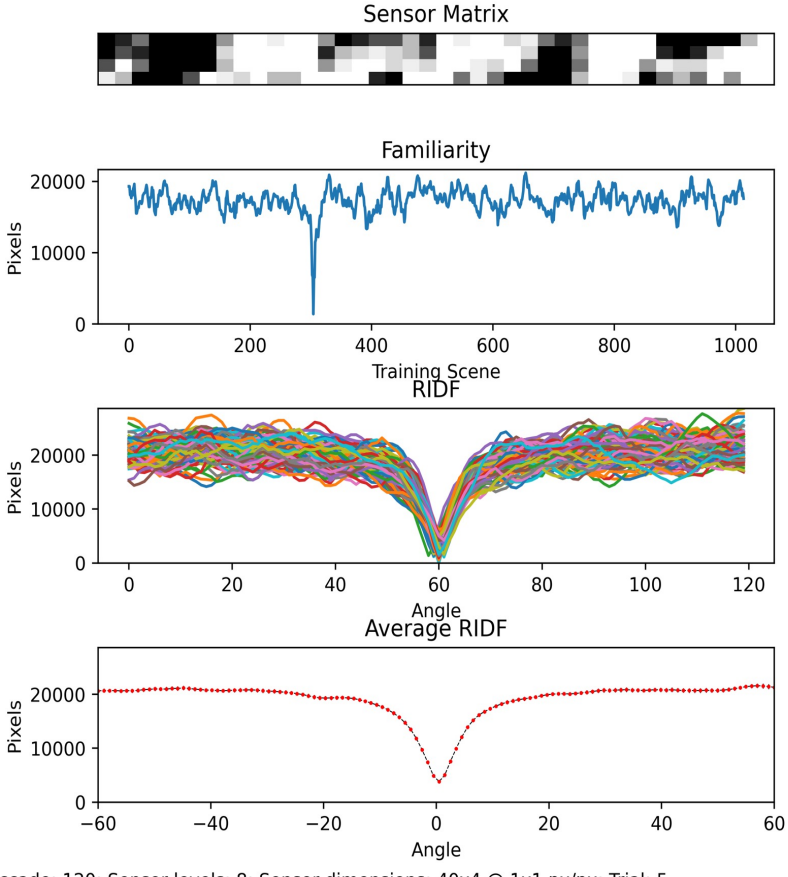




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

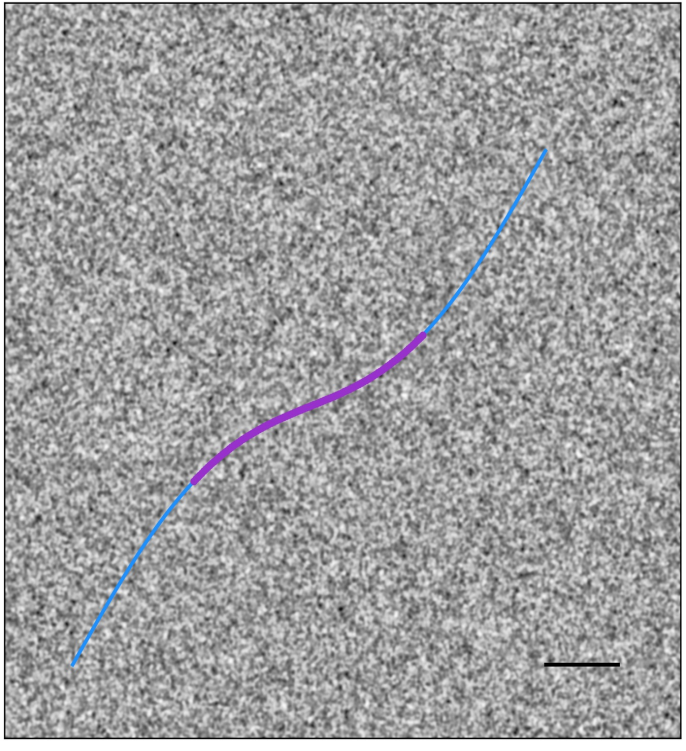
Navigation stats: RMSD error: 55.82; RMSD/dist: 0.140; TD: 12770; p90: 16; p50: 8; complete: 0

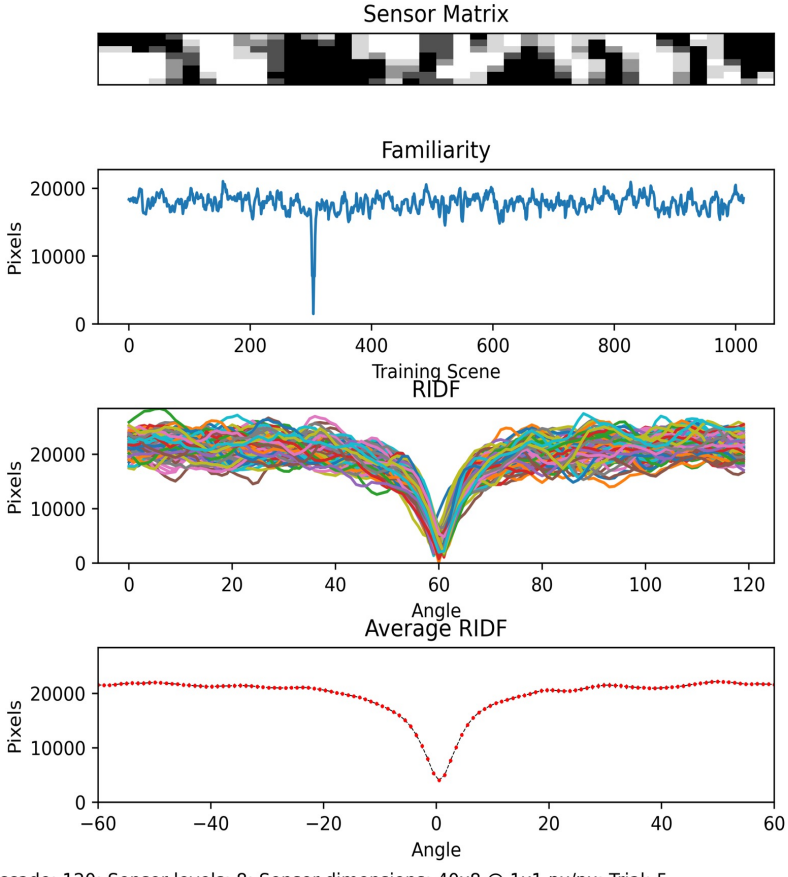




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

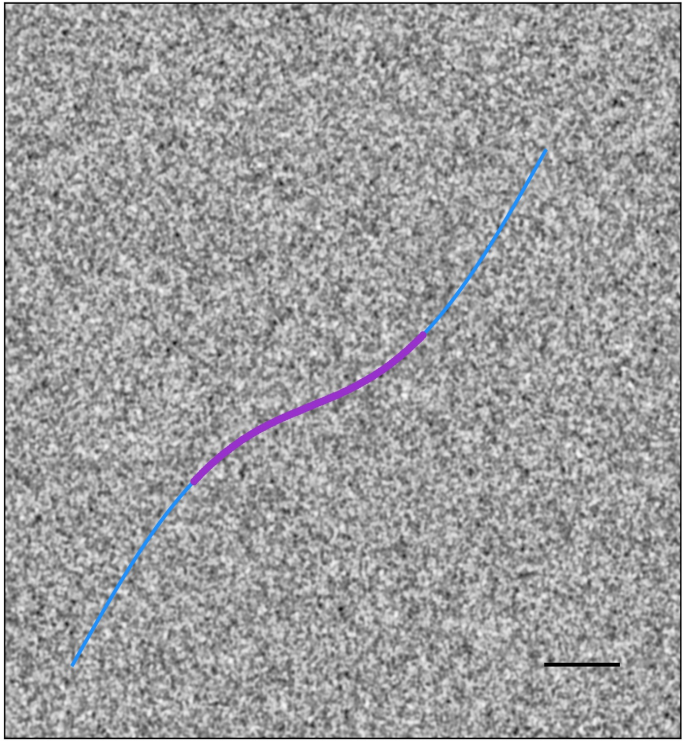
Navigation stats: RMSD error: 59.55; RMSD/dist: 0.149; TD: 13576; p90: 14; p50: 6; complete: 0

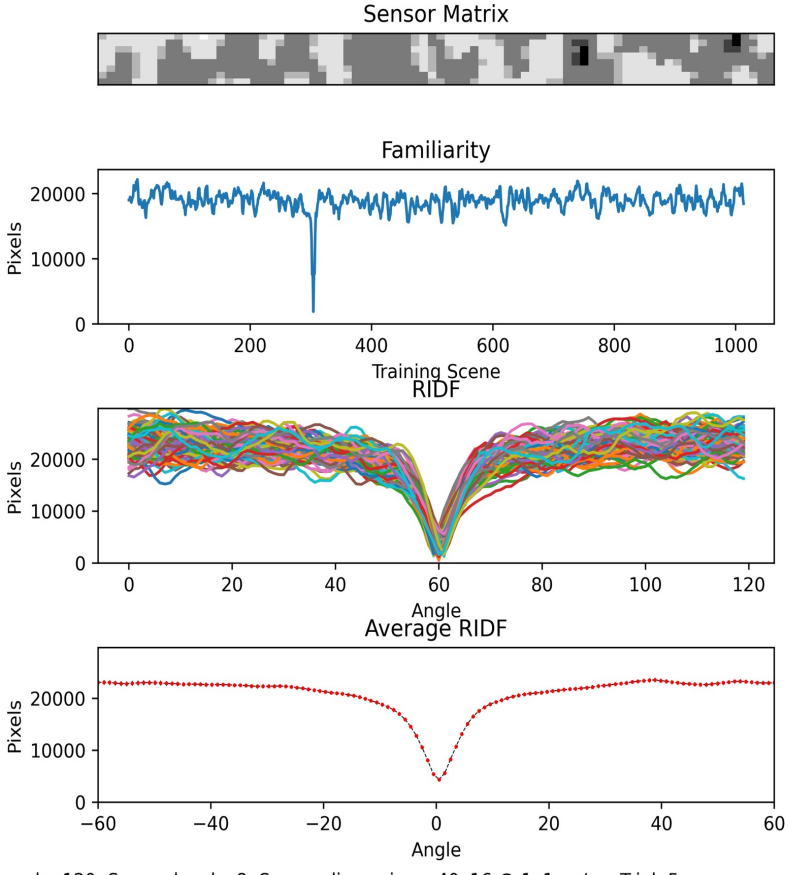




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

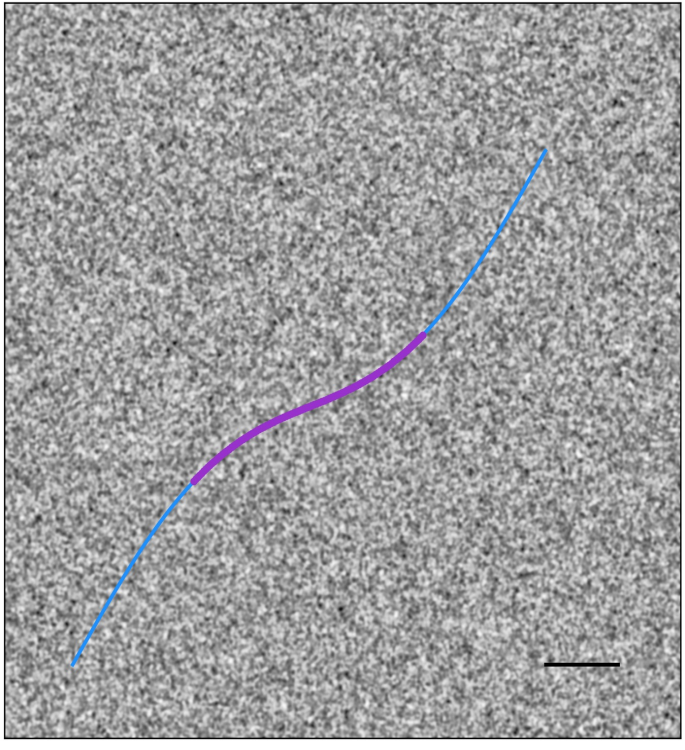
Navigation stats: RMSD error: 57.39; RMSD/dist: 0.143; TD: 13845; p90: 16; p50: 6; complete: 0

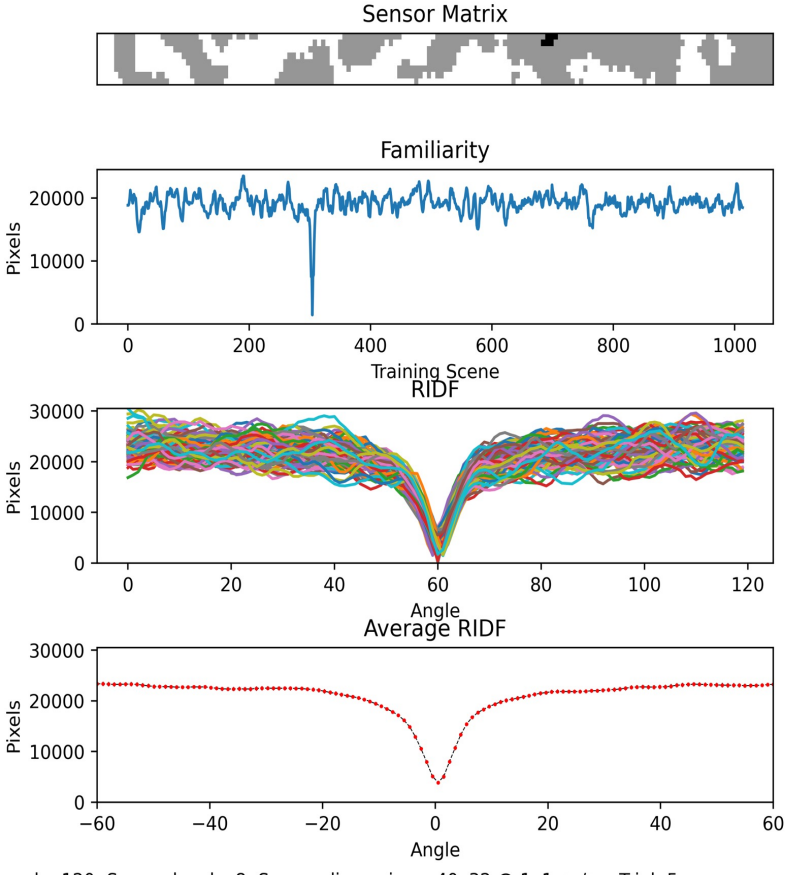




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

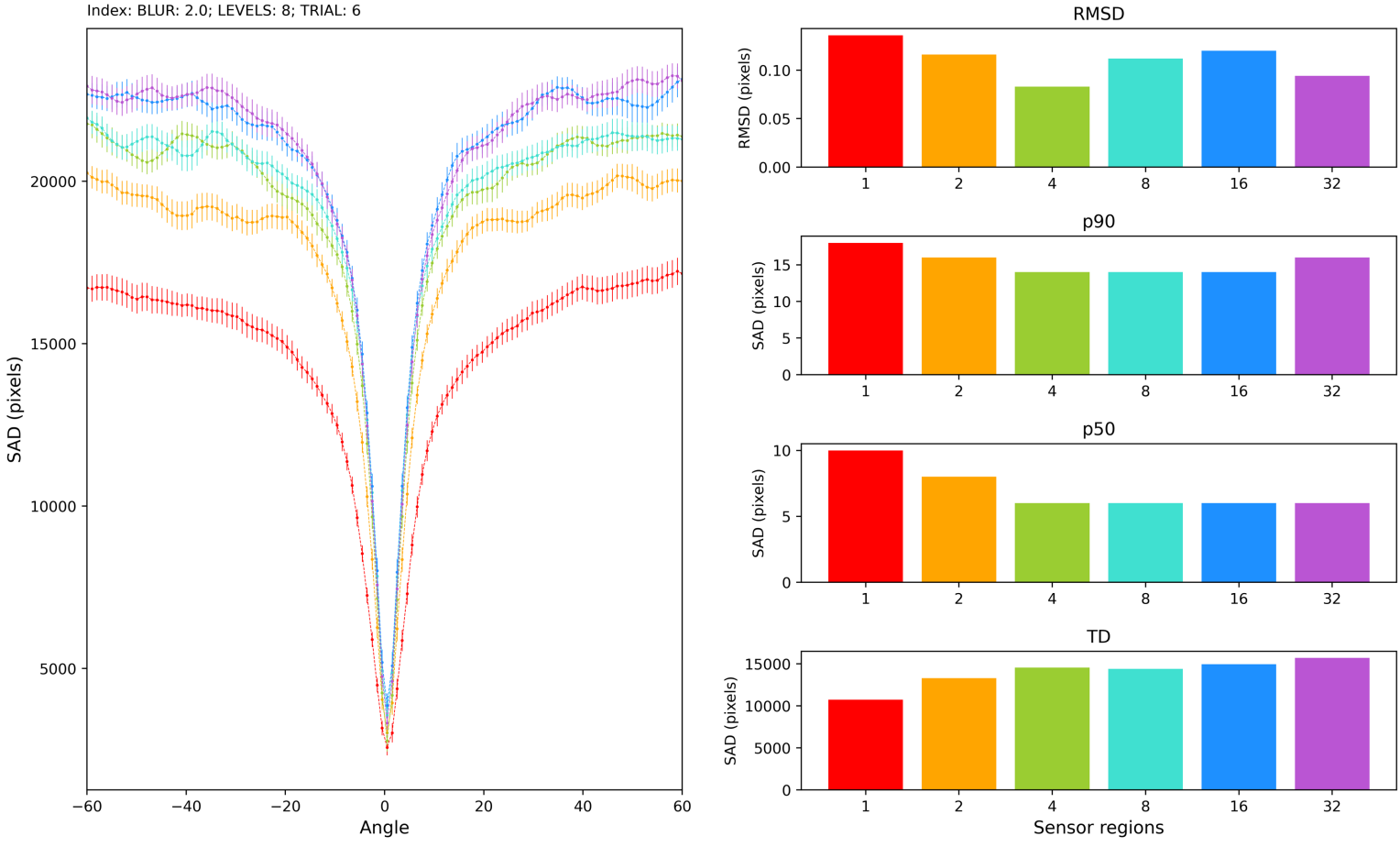
Navigation stats: RMSD error: 59.98; RMSD/dist: 0.150; TD: 14468; p90: 14; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 45.70; RMSD/dist: 0.114; TD: 15310; p90: 16; p50: 6; complete: 0


Index: BLUR: 2.0; LEVELS: 8; TRIAL: 6
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15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
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16
32
p90
SAD (pixels)
15
10
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0
p50
TD
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10000
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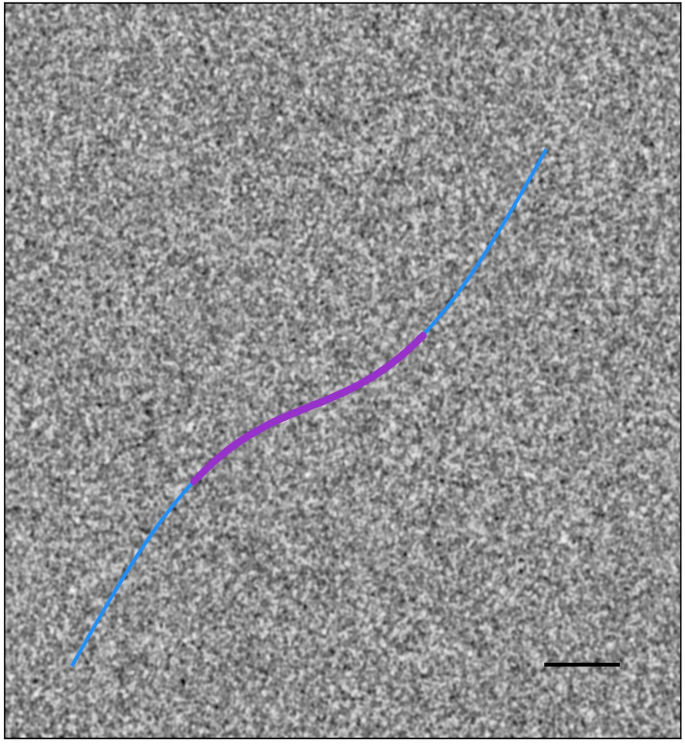
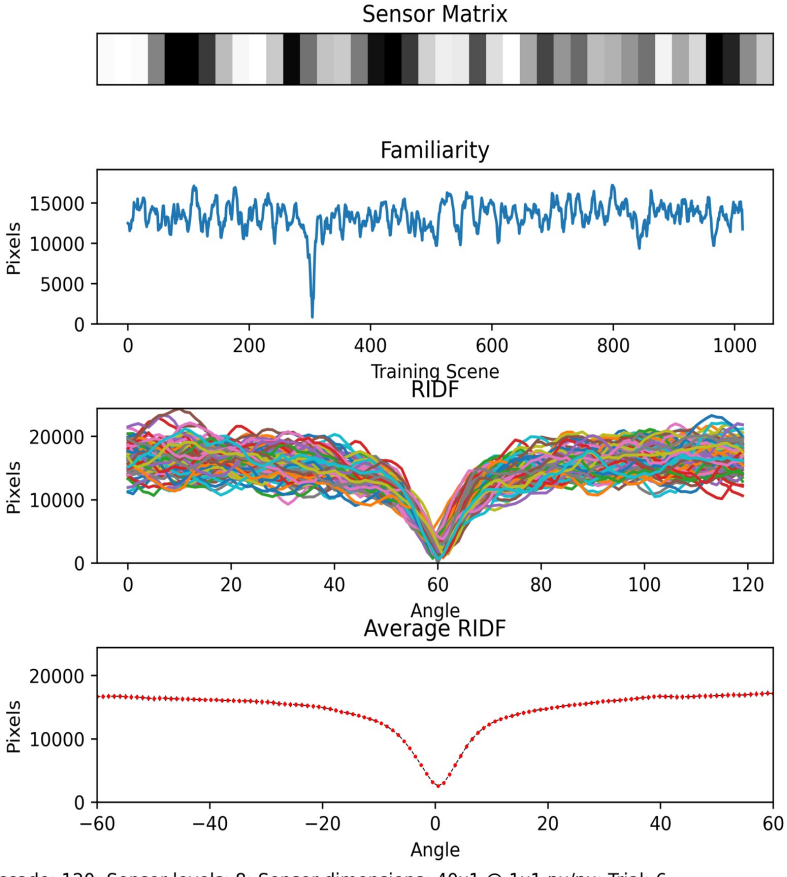
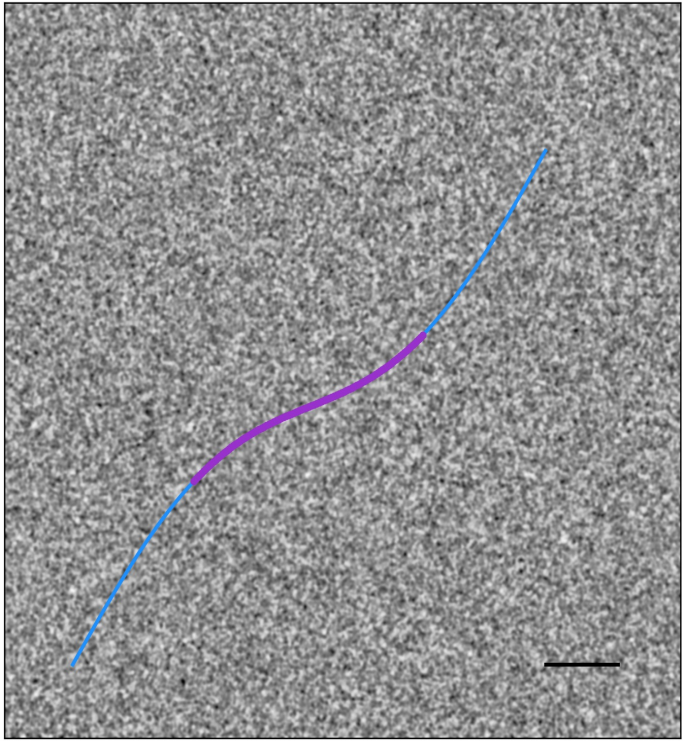
Sensor regions

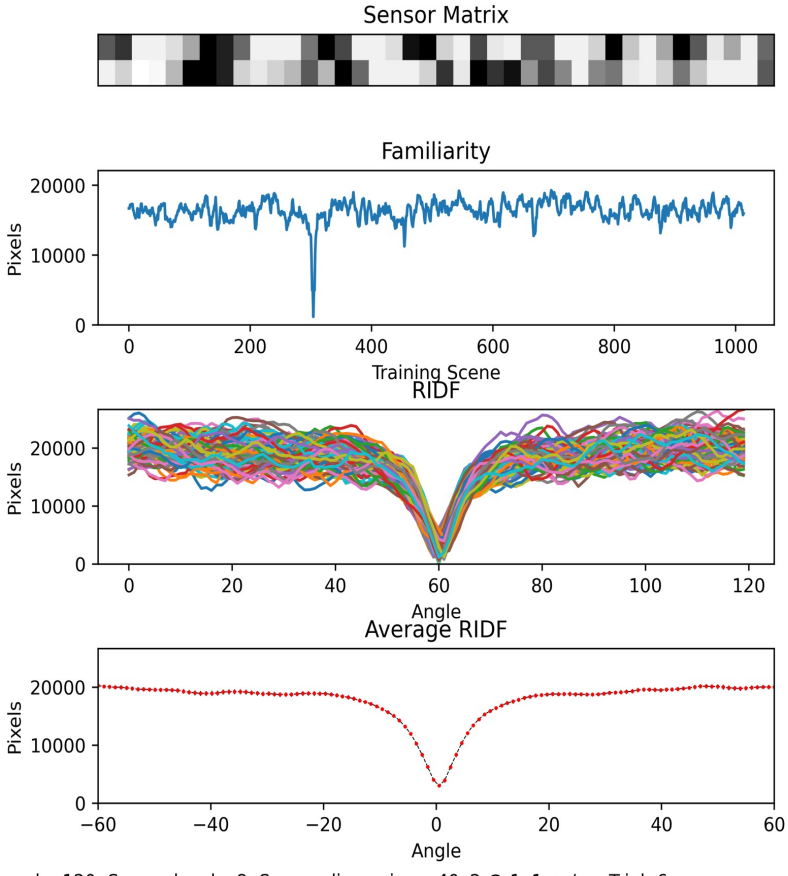




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

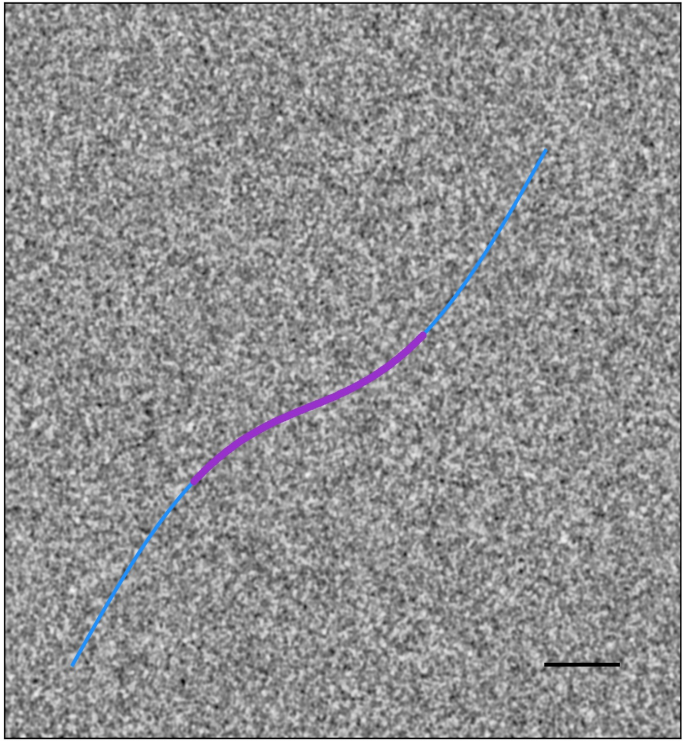
Navigation stats: RMSD error: 54.51; RMSD/dist: 0.136; TD: 10711; p90: 18; p50: 10; complete: 0

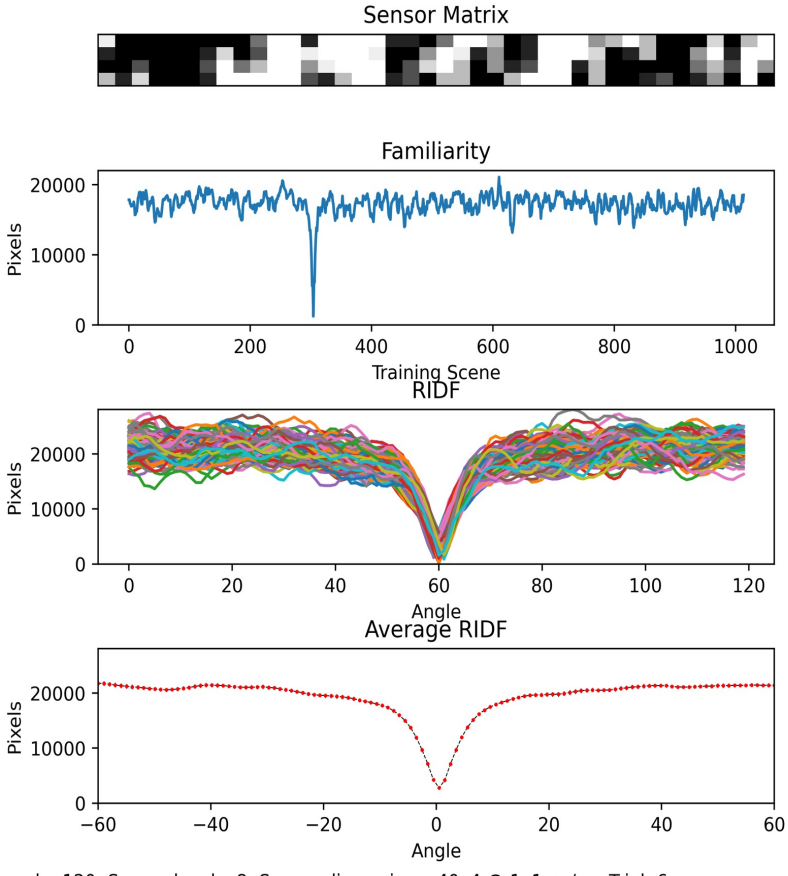




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

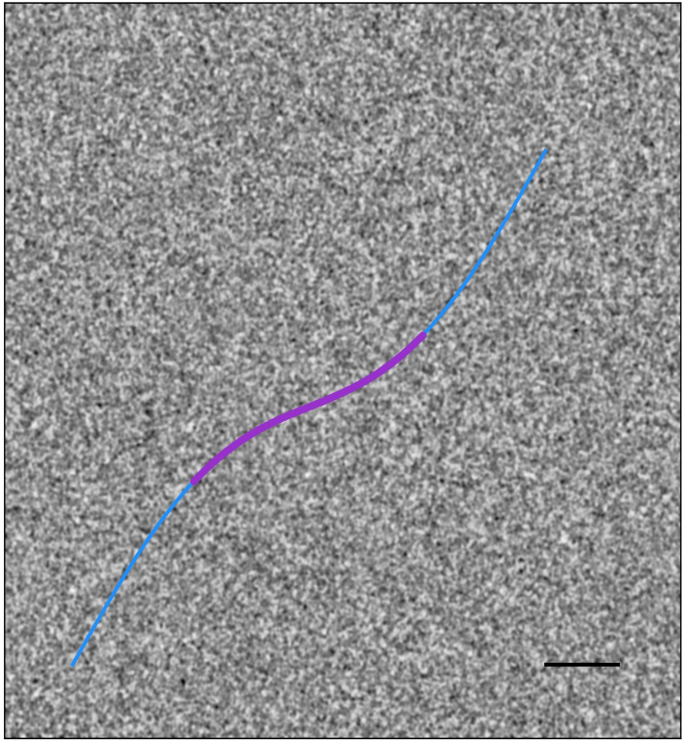
Navigation stats: RMSD error: 46.27; RMSD/dist: 0.116; TD: 13274; p90: 16; p50: 8; complete: 0

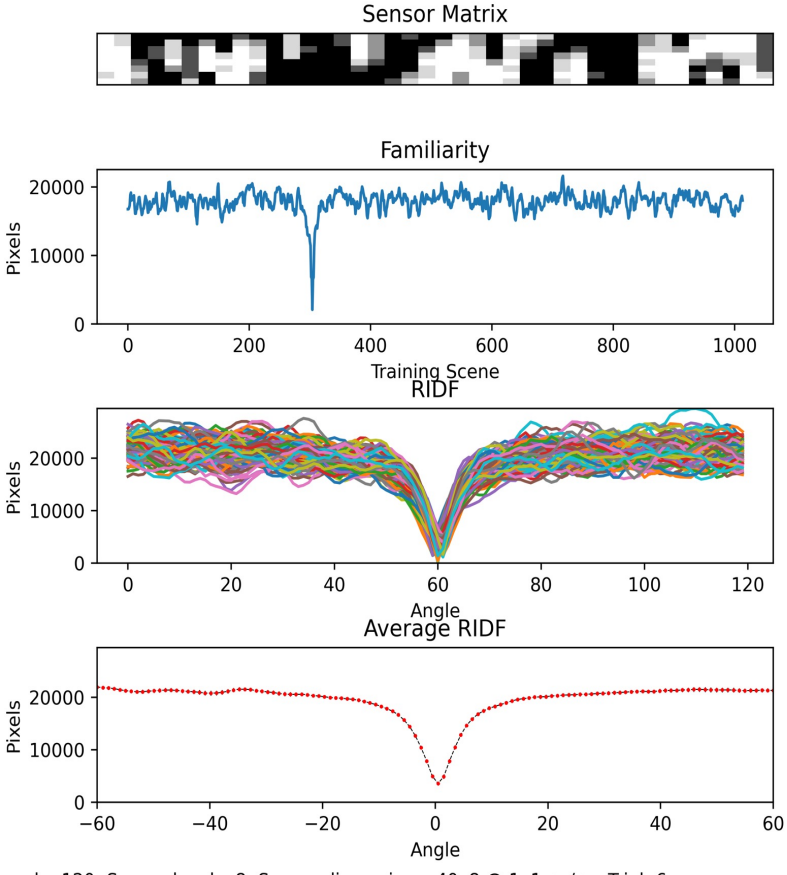




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

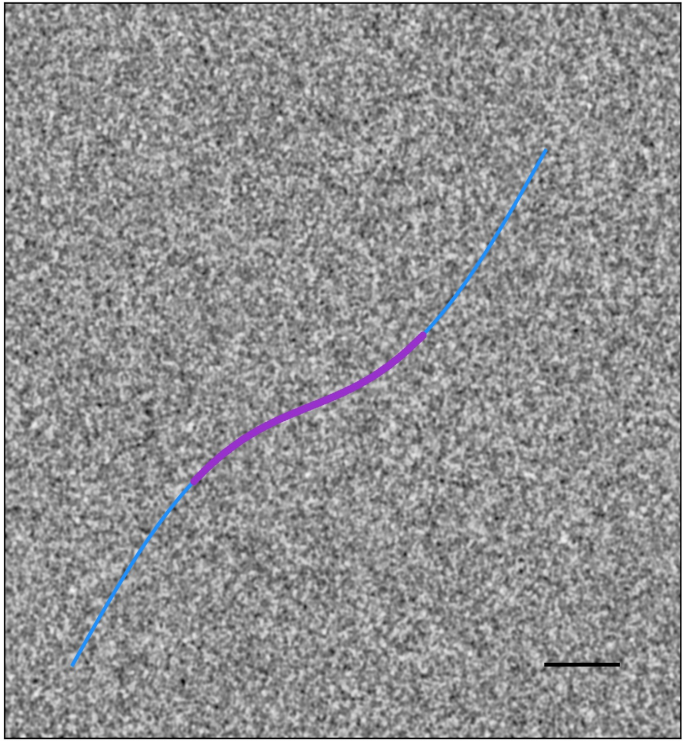
Navigation stats: RMSD error: 33.35; RMSD/dist: 0.083; TD: 14554; p90: 14; p50: 6; complete: 0

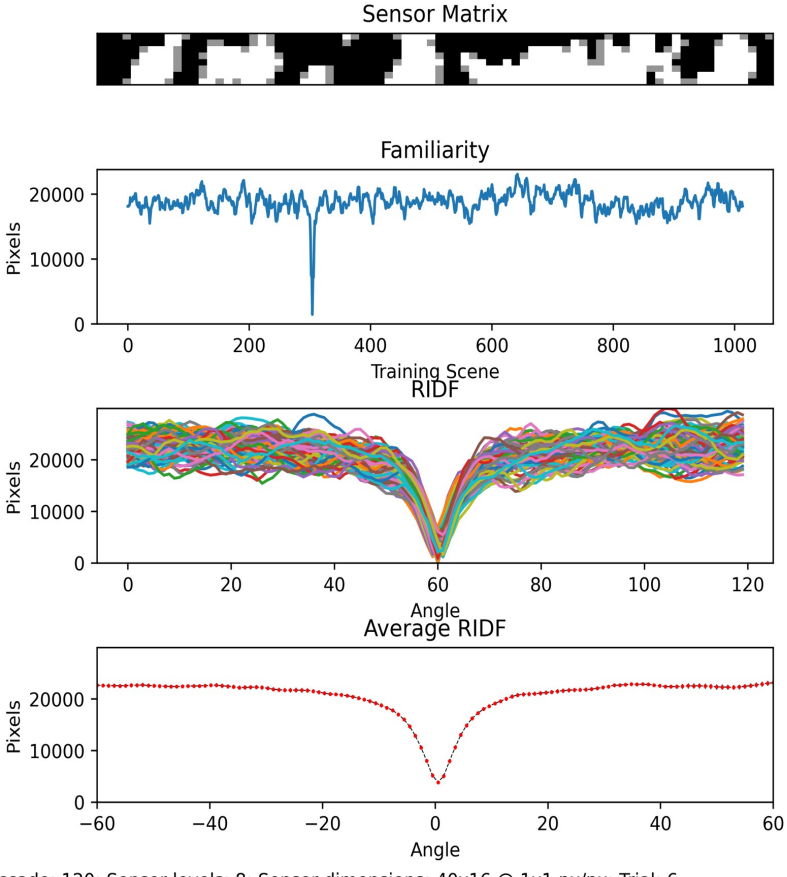




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

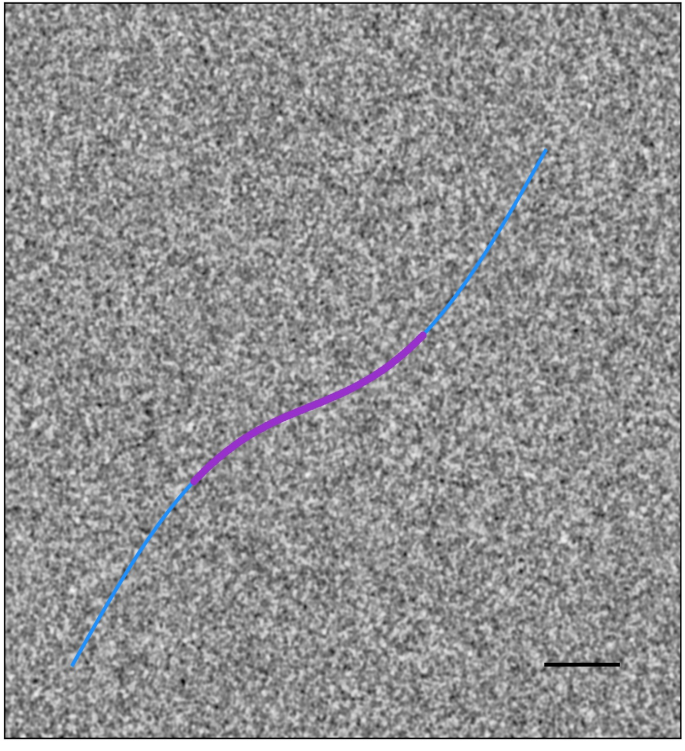
Navigation stats: RMSD error: 44.77; RMSD/dist: 0.112; TD: 14384; p90: 14; p50: 6; complete: 0

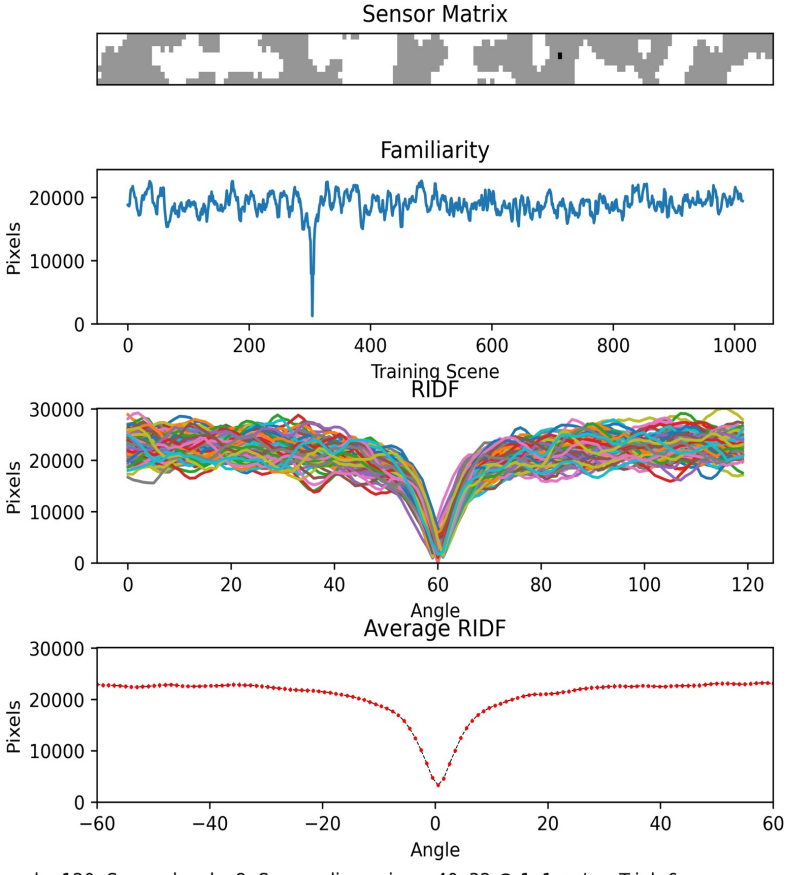




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

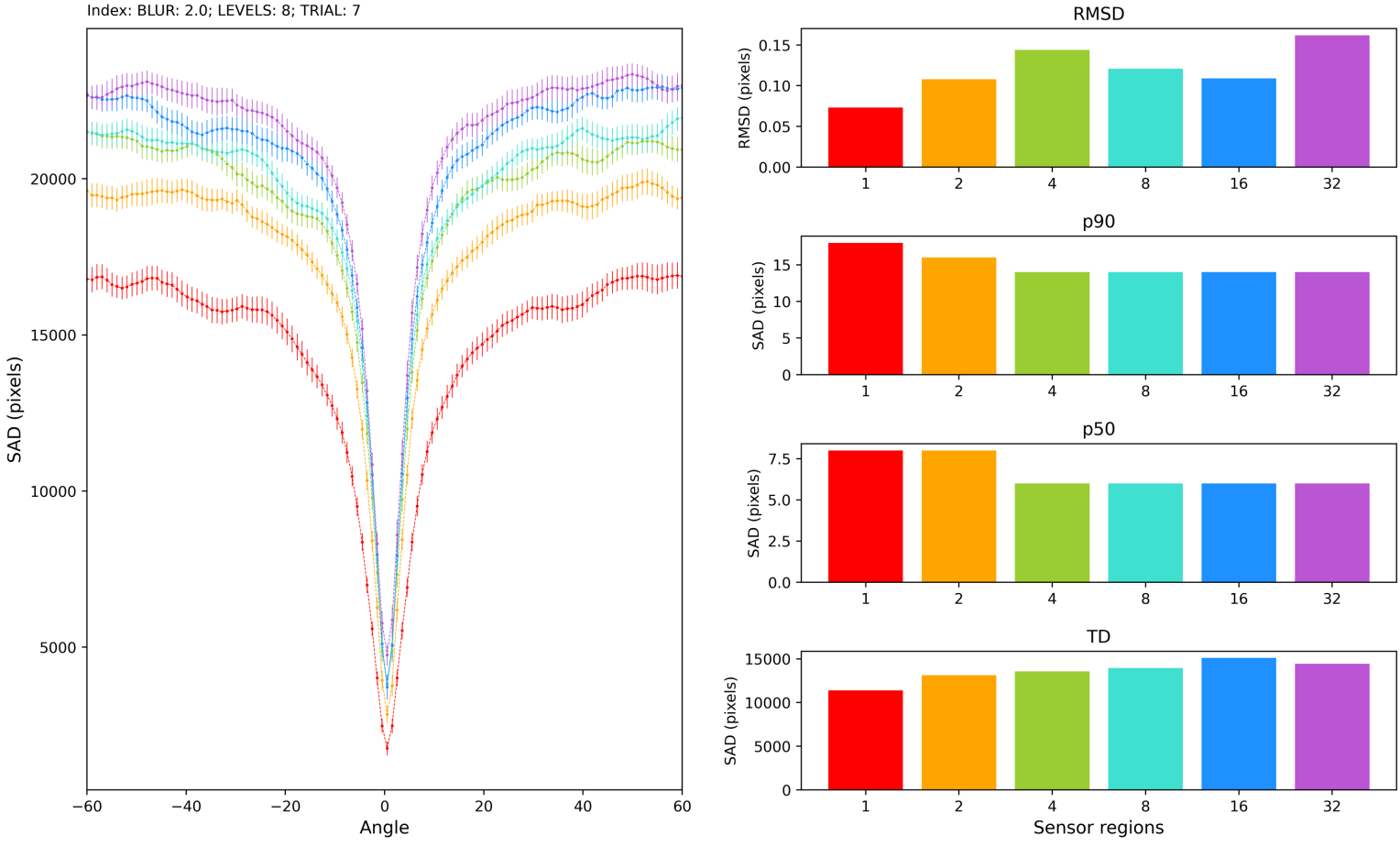
Navigation stats: RMSD error: 48.15; RMSD/dist: 0.120; TD: 14956; p90: 14; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 37.76; RMSD/dist: 0.094; TD: 15685; p90: 16; p50: 6; complete: 0


Index: BLUR: 2.0; LEVELS: 8; TRIAL: 7
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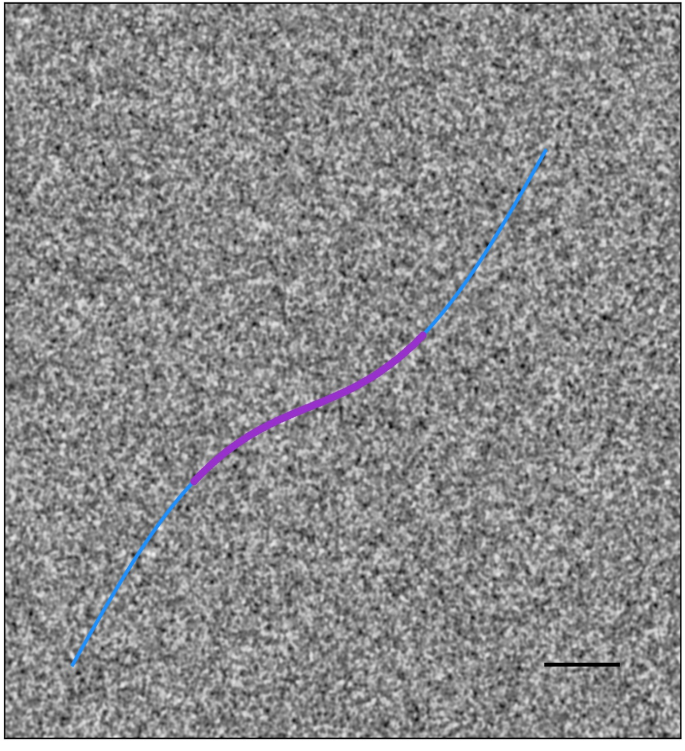
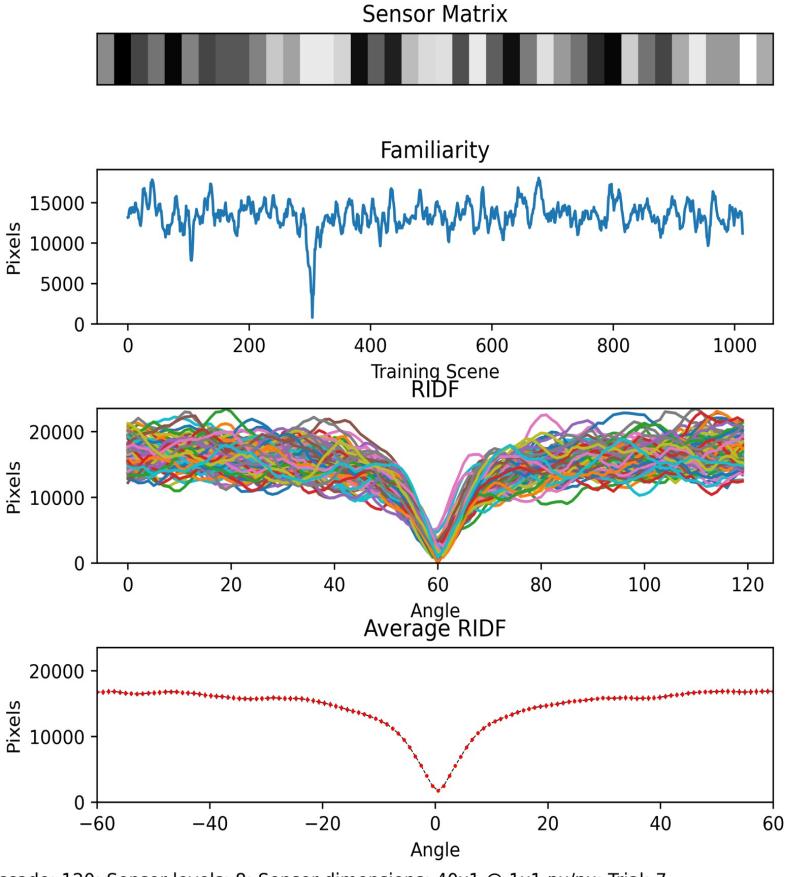
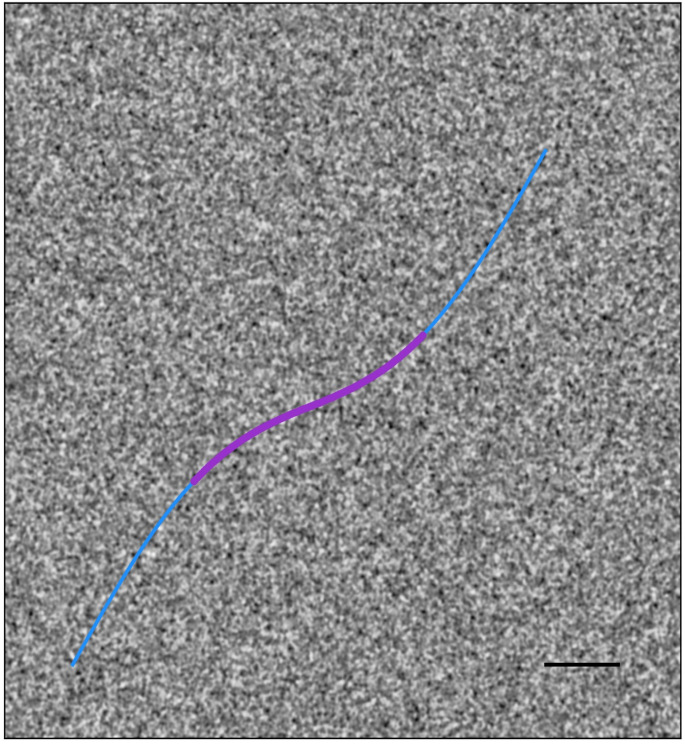
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

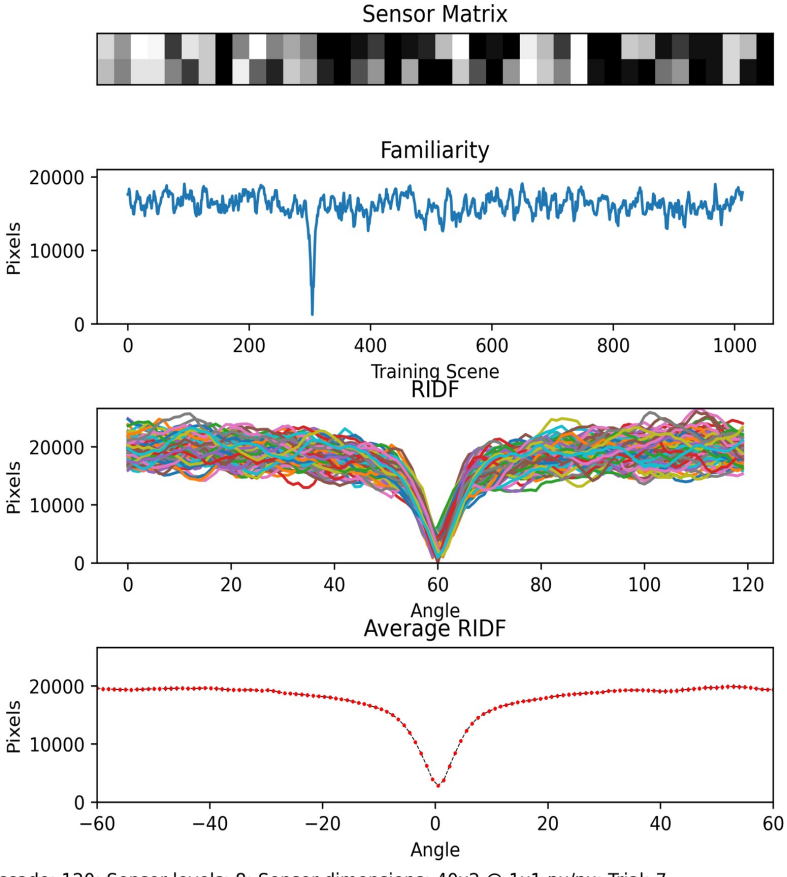




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

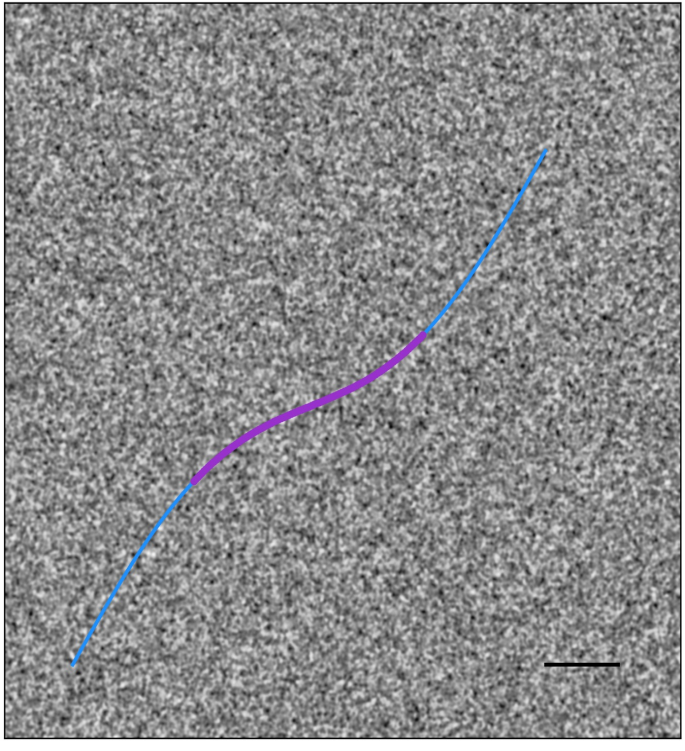
Navigation stats: RMSD error: 29.39; RMSD/dist: 0.073; TD: 11379; p90: 18; p50: 8; complete: 0

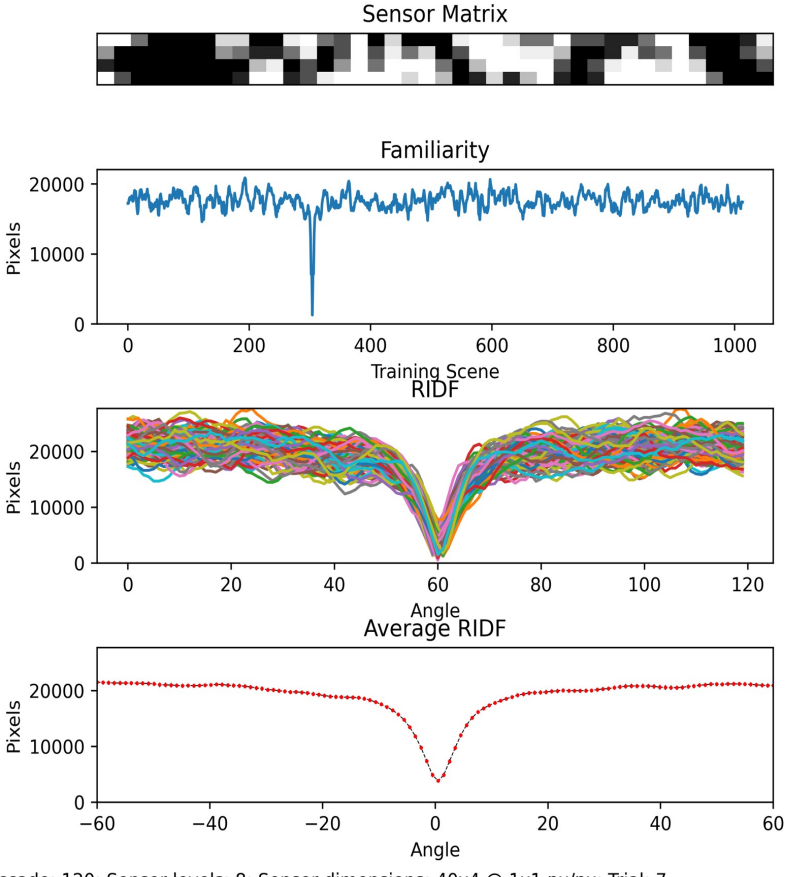




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

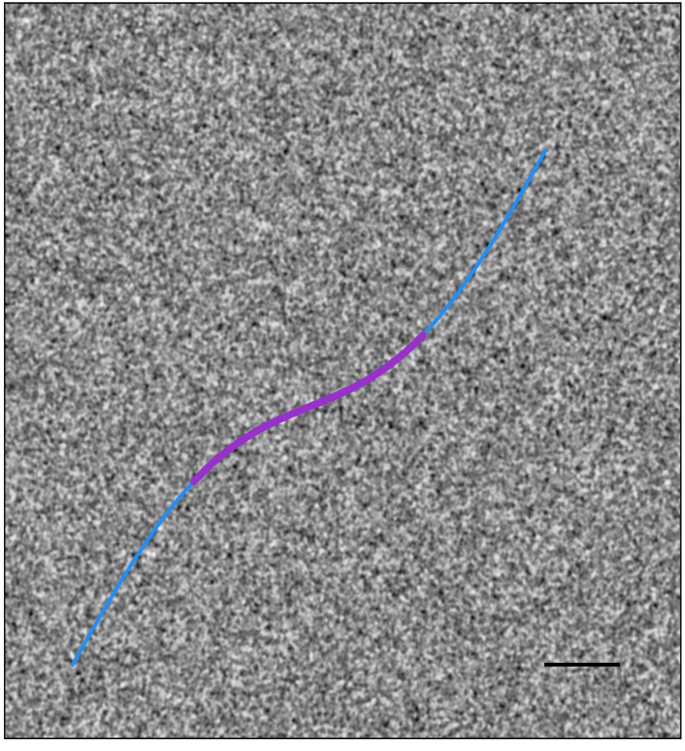
Navigation stats: RMSD error: 43.14; RMSD/dist: 0.108; TD: 13135; p90: 16; p50: 8; complete: 0

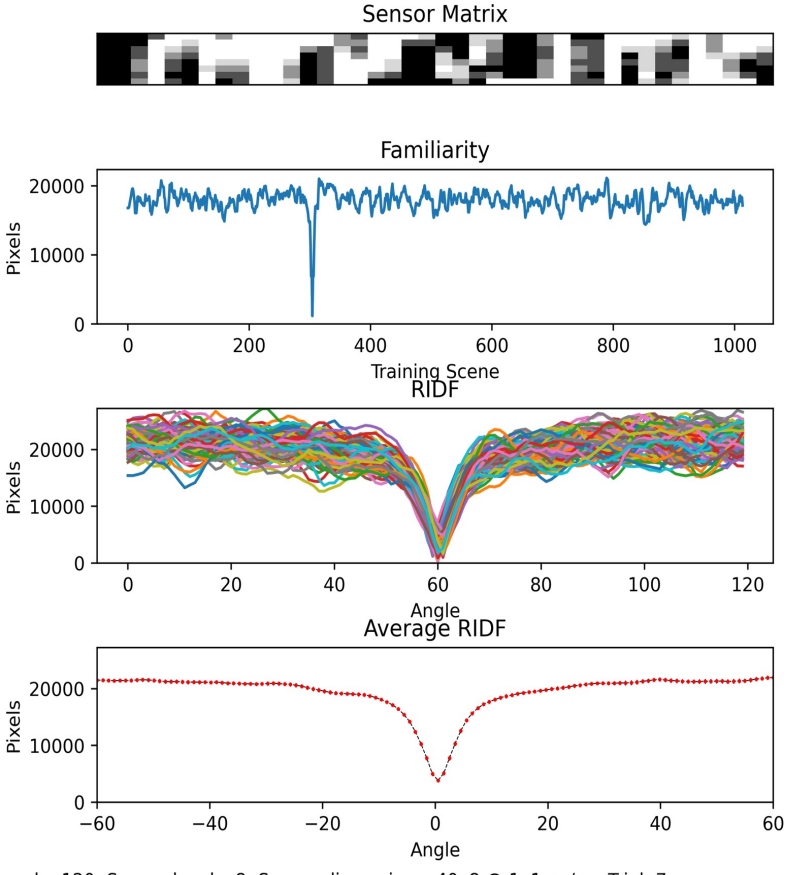




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

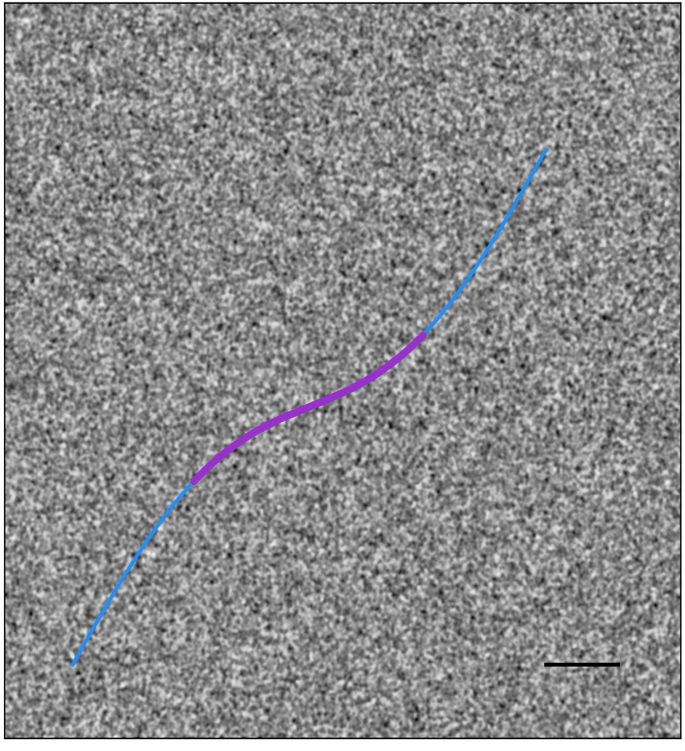
Navigation stats: RMSD error: 57.69; RMSD/dist: 0.144; TD: 13568; p90: 14; p50: 6; complete: 0

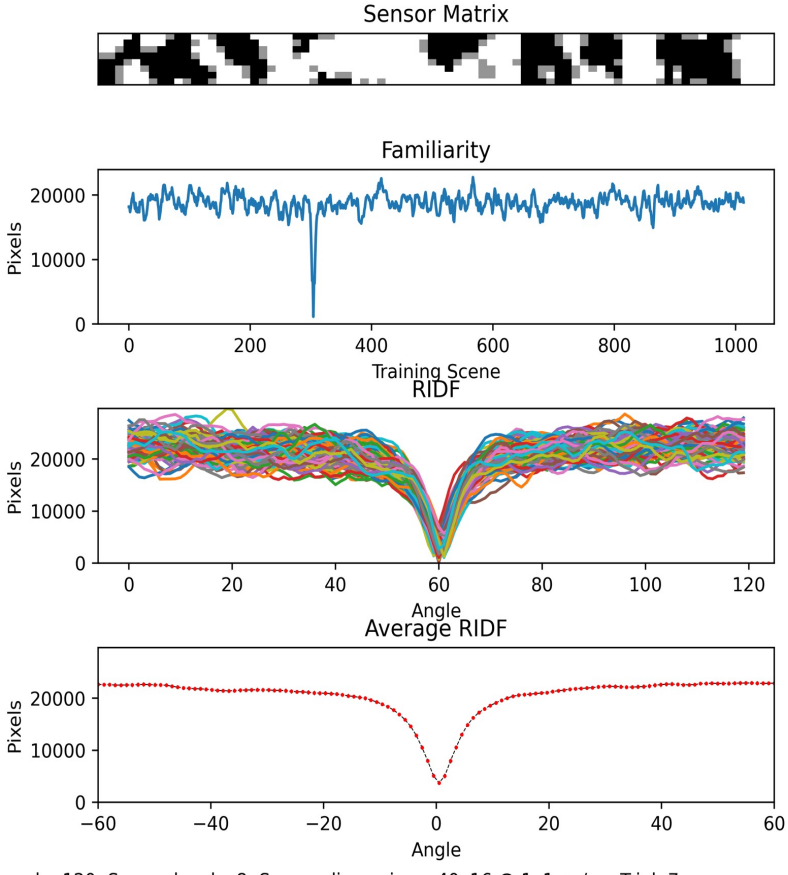




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

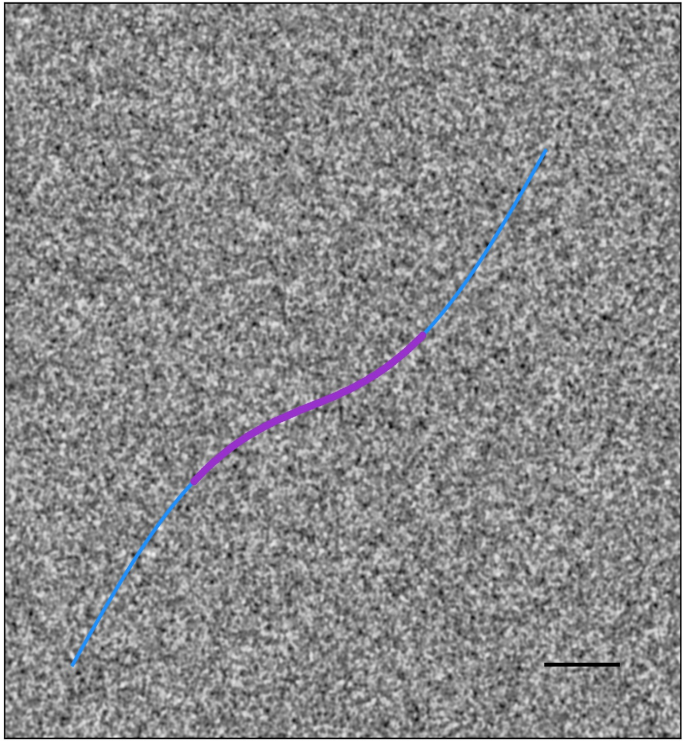
Navigation stats: RMSD error: 48.56; RMSD/dist: 0.121; TD: 13951; p90: 14; p50: 6; complete: 0

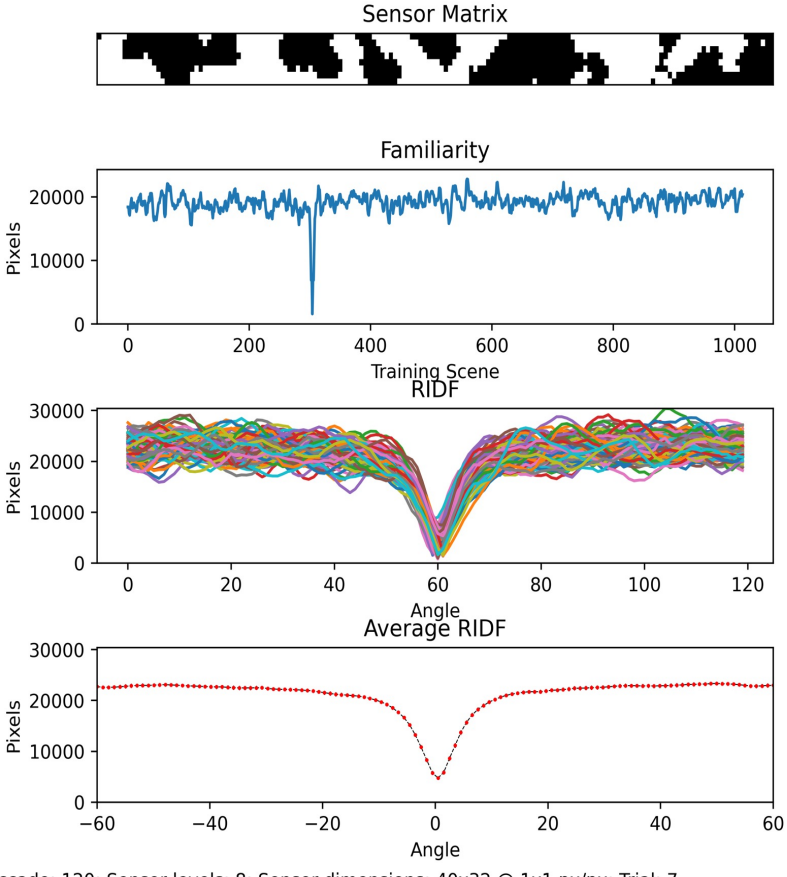




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

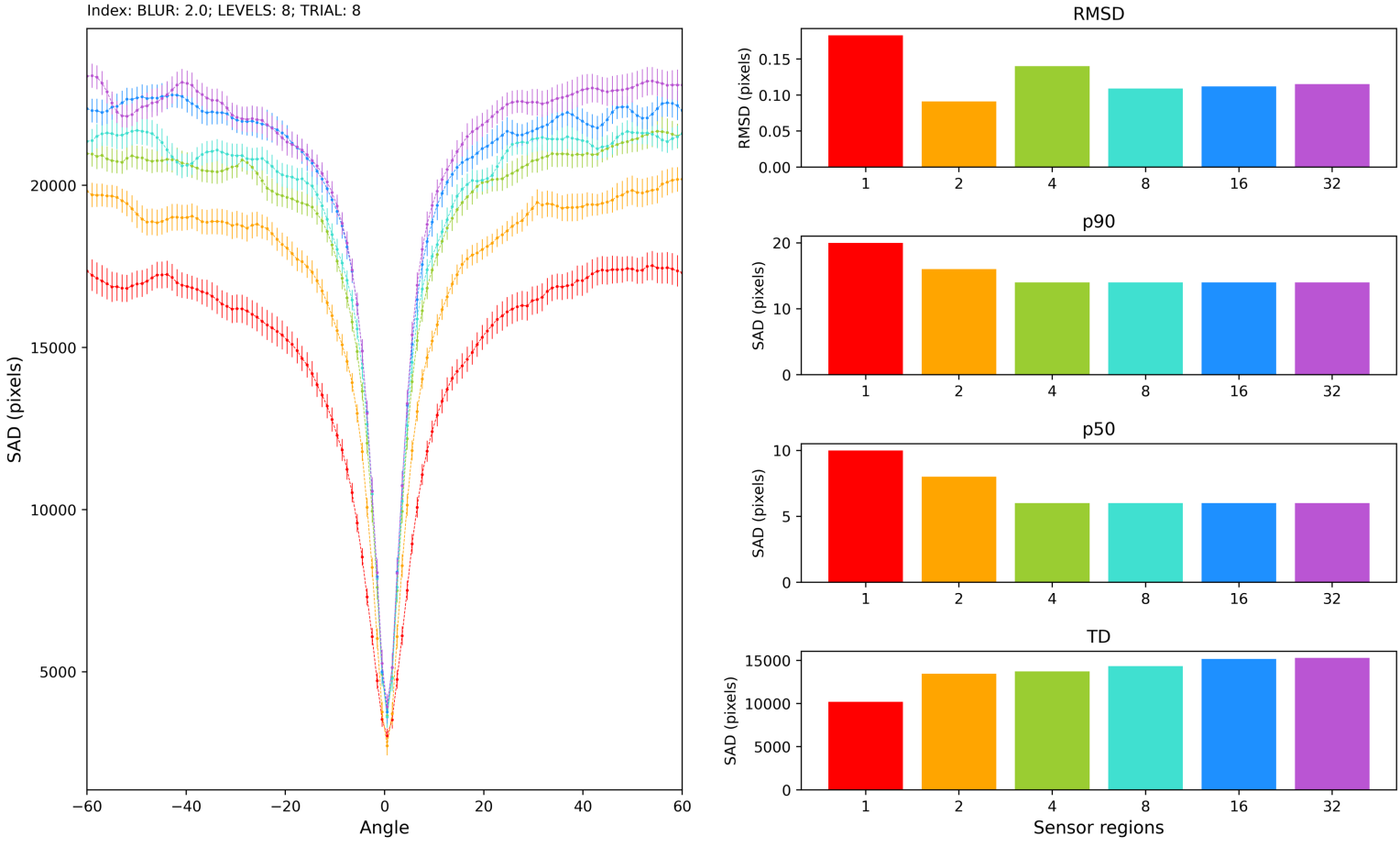
Navigation stats: RMSD error: 43.65; RMSD/dist: 0.109; TD: 15099; p90: 14; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 64.85; RMSD/dist: 0.162; TD: 14422; p90: 14; p50: 6; complete: 0


Index: BLUR: 2.0; LEVELS: 8; TRIAL: 8
SAD (pixels)
20000
15000
10000
5000
−60
−40
−20
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20
40
60
Angle
RMSD
RMSD (pixels)
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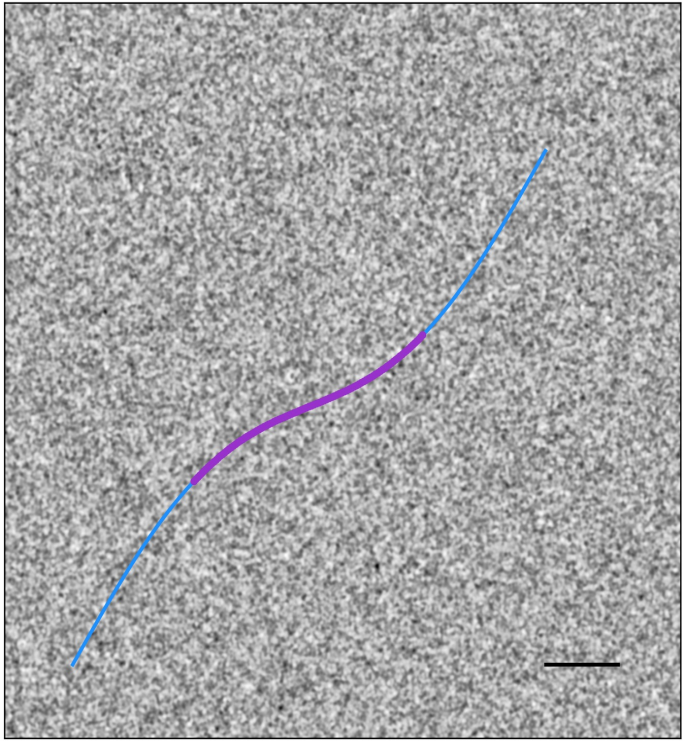
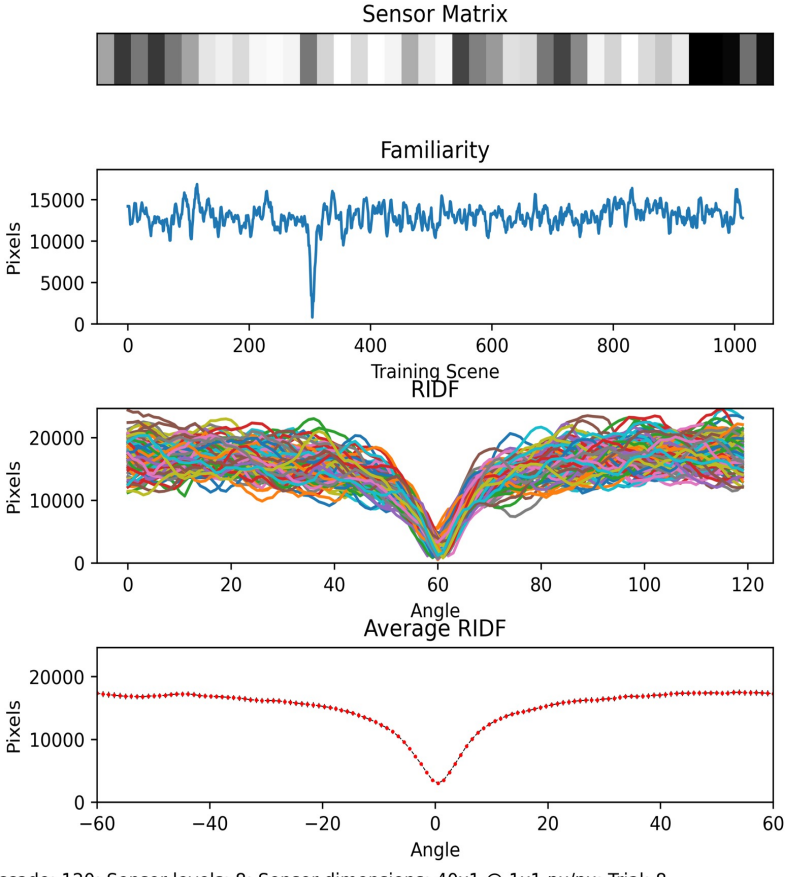
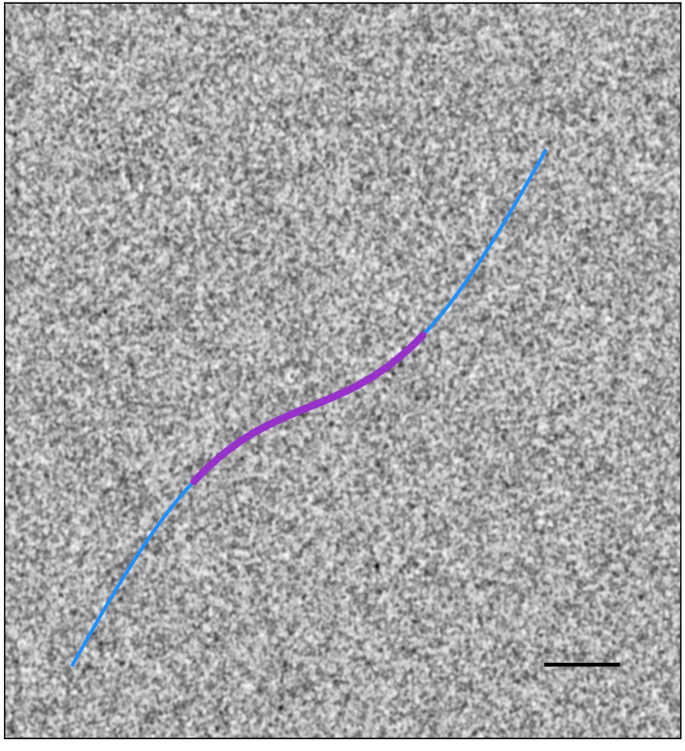
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

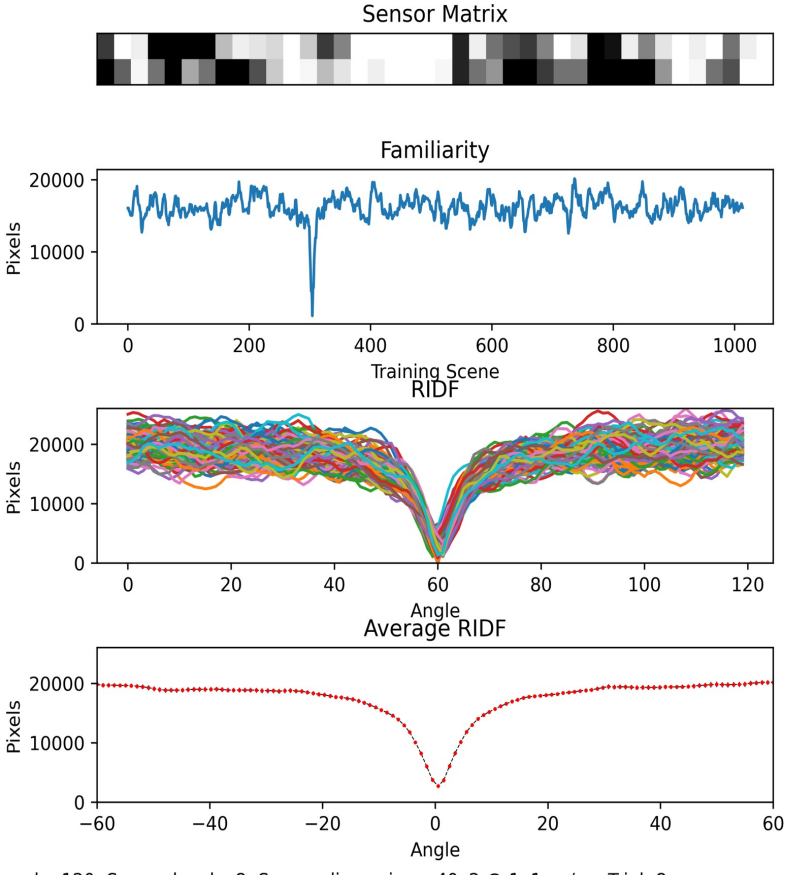




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

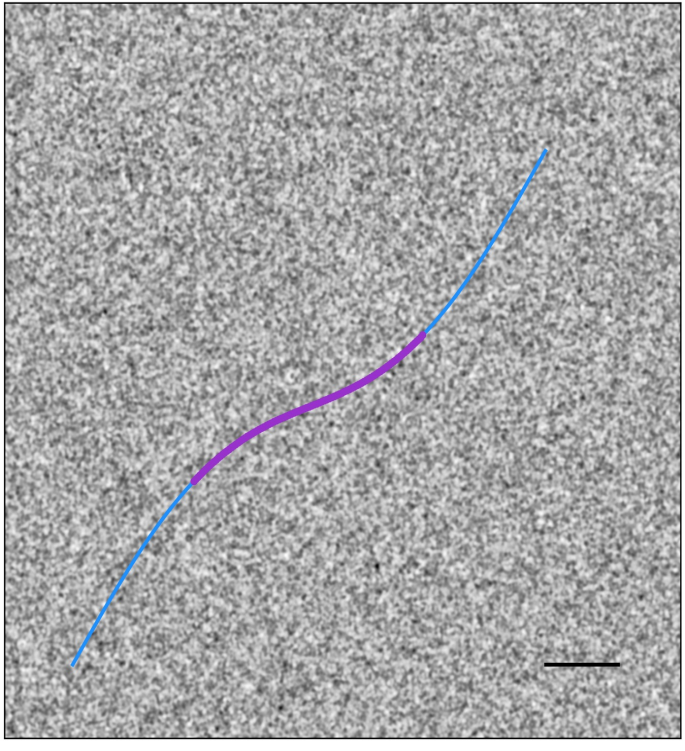
Navigation stats: RMSD error: 73.21; RMSD/dist: 0.183; TD: 10187; p90: 20; p50: 10; complete: 0

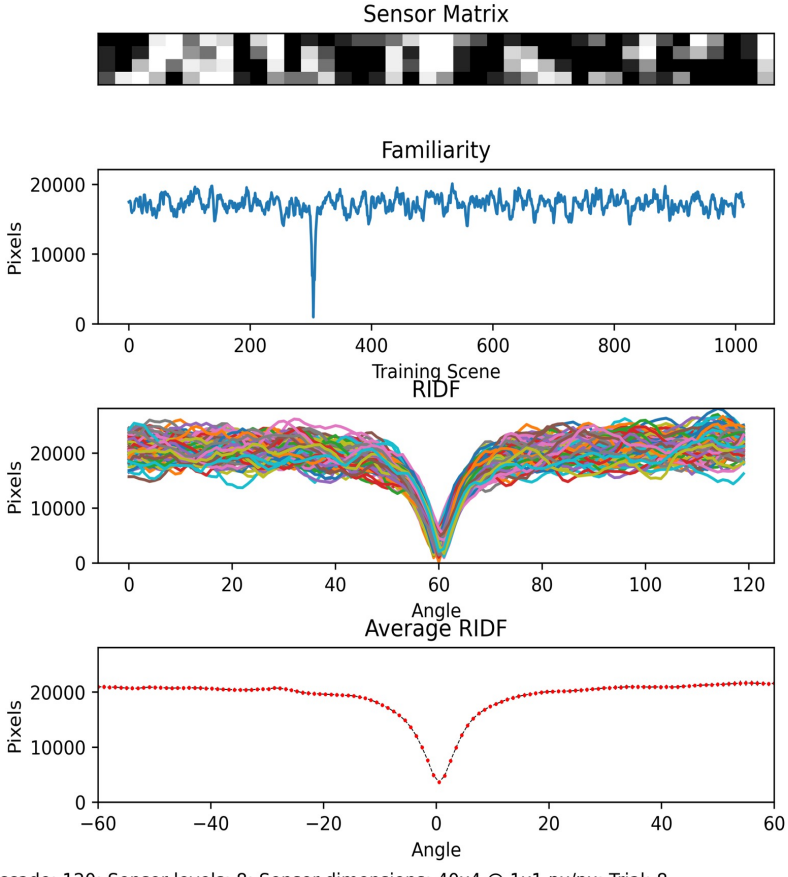




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

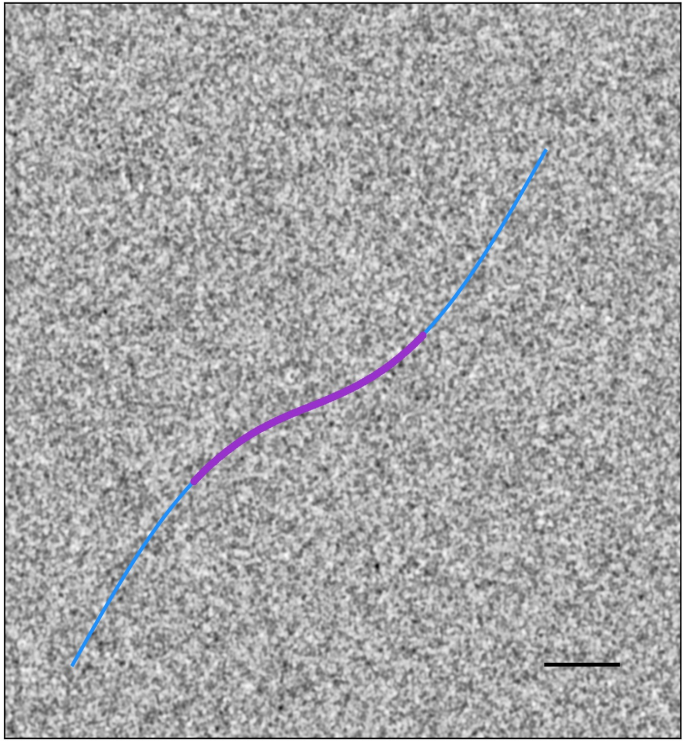
Navigation stats: RMSD error: 36.35; RMSD/dist: 0.091; TD: 13443; p90: 16; p50: 8; complete: 0

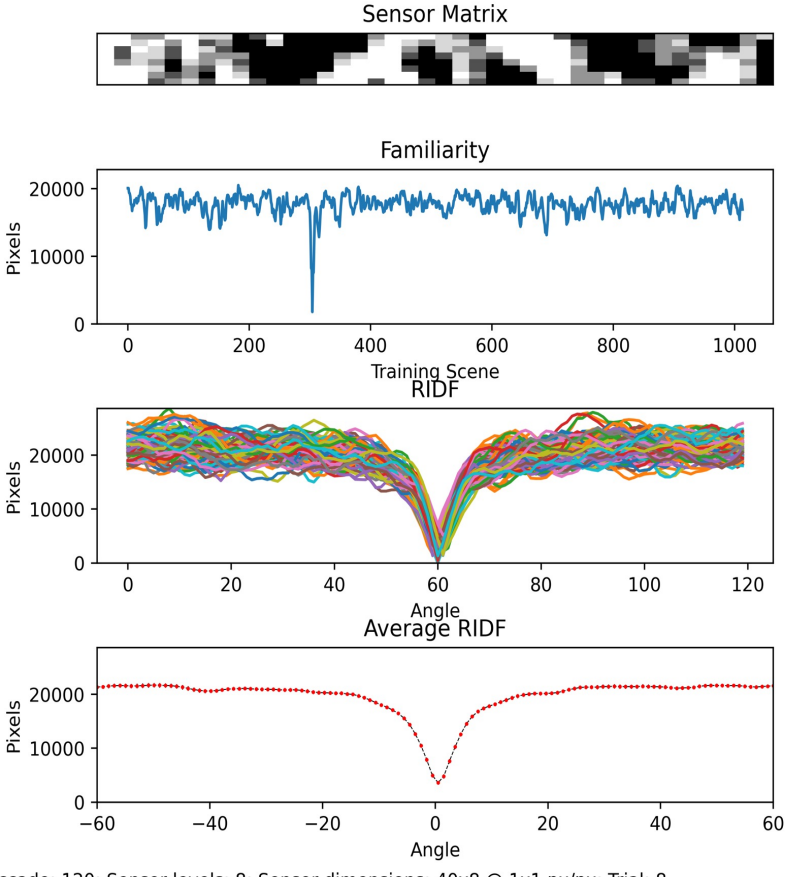




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

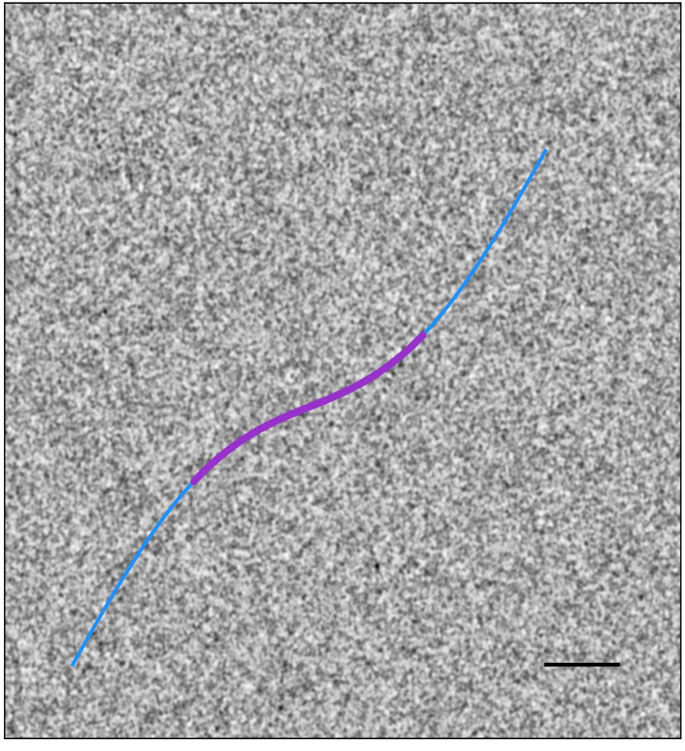
Navigation stats: RMSD error: 56.10; RMSD/dist: 0.140; TD: 13715; p90: 14; p50: 6; complete: 0

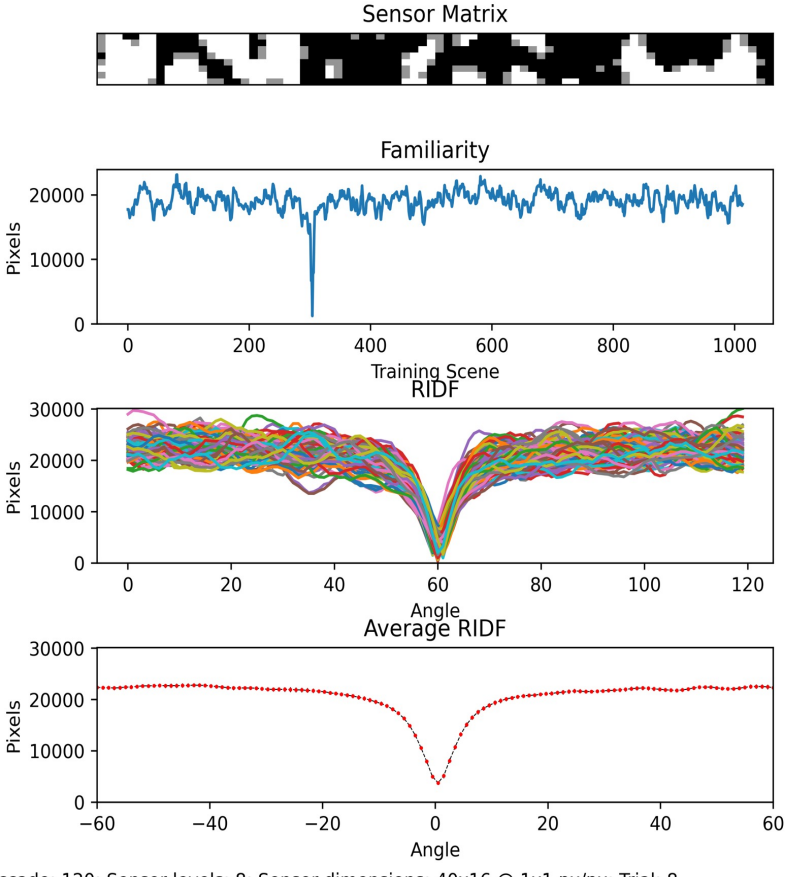




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

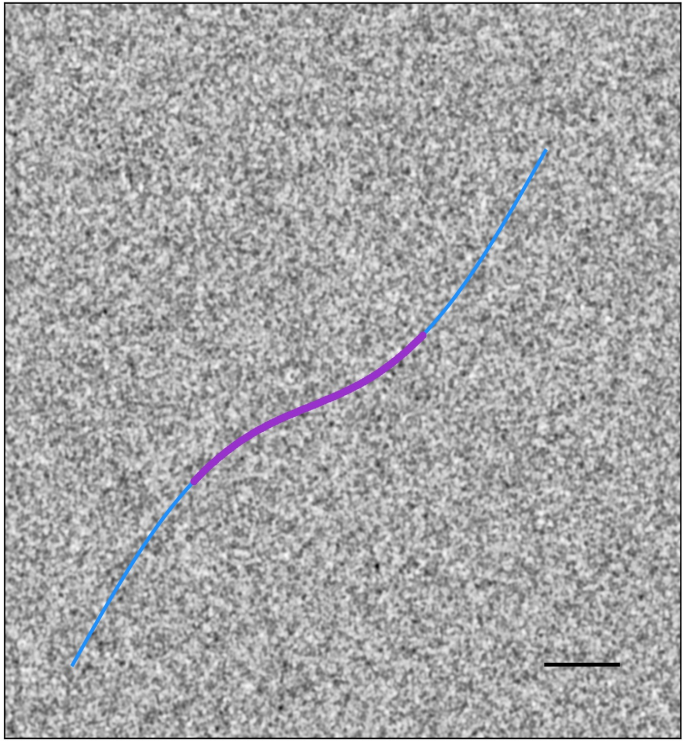
Navigation stats: RMSD error: 43.43; RMSD/dist: 0.109; TD: 14319; p90: 14; p50: 6; complete: 0

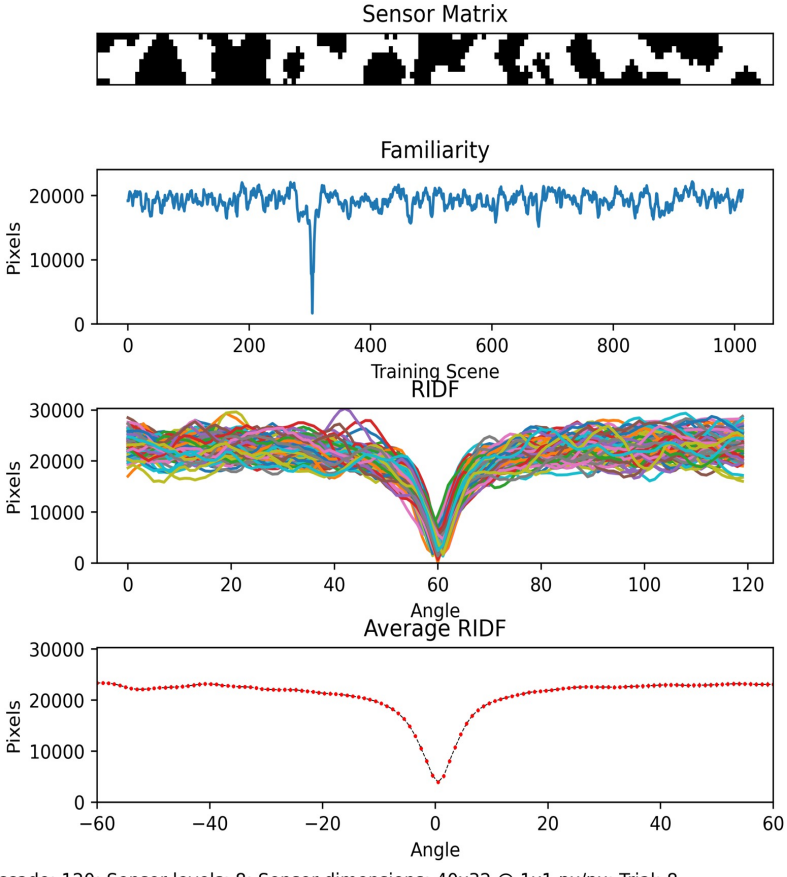




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

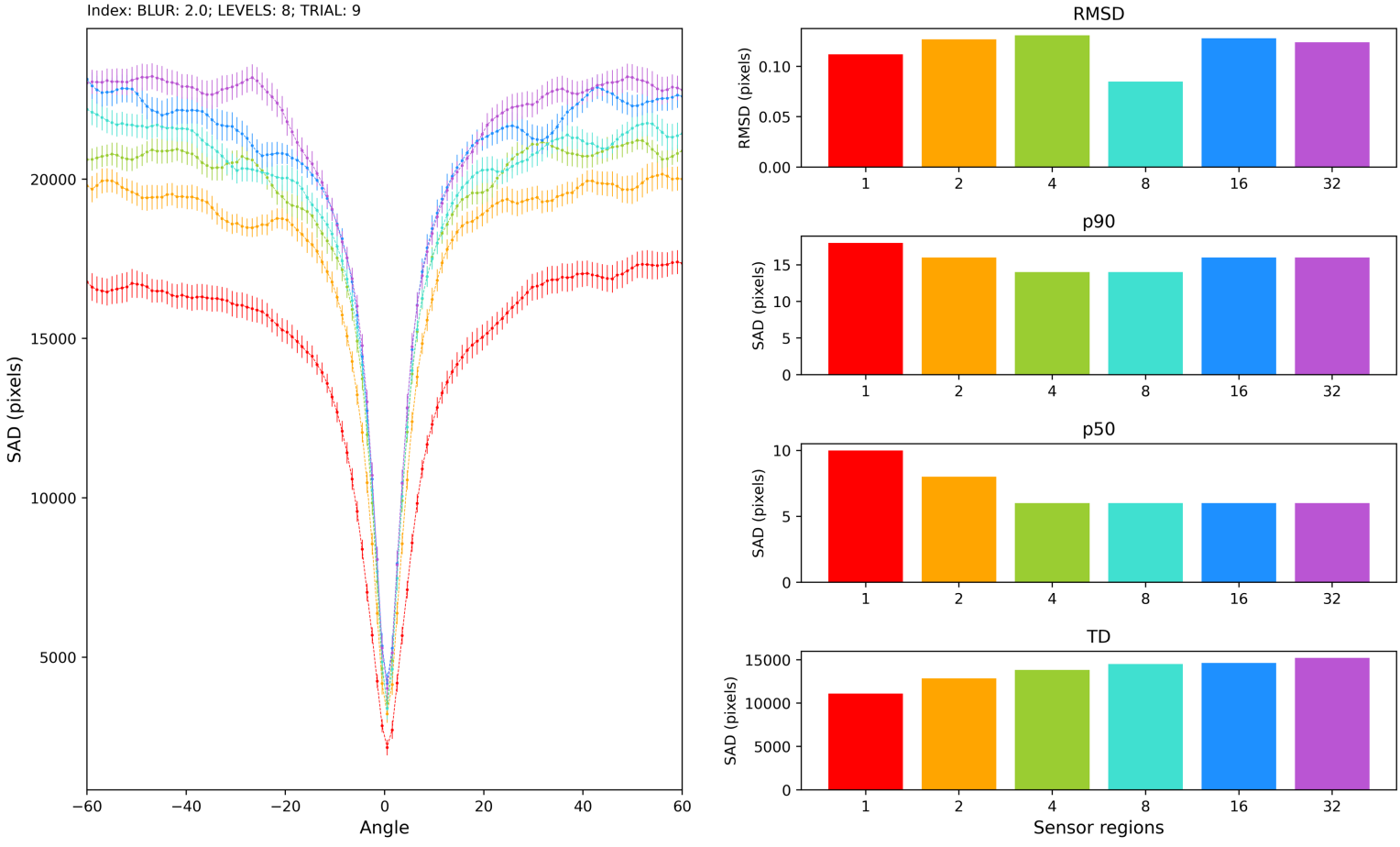
Navigation stats: RMSD error: 44.84; RMSD/dist: 0.112; TD: 15150; p90: 14; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 46.19; RMSD/dist: 0.115; TD: 15272; p90: 14; p50: 6; complete: 0


Index: BLUR: 2.0; LEVELS: 8; TRIAL: 9
SAD (pixels)
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
TD
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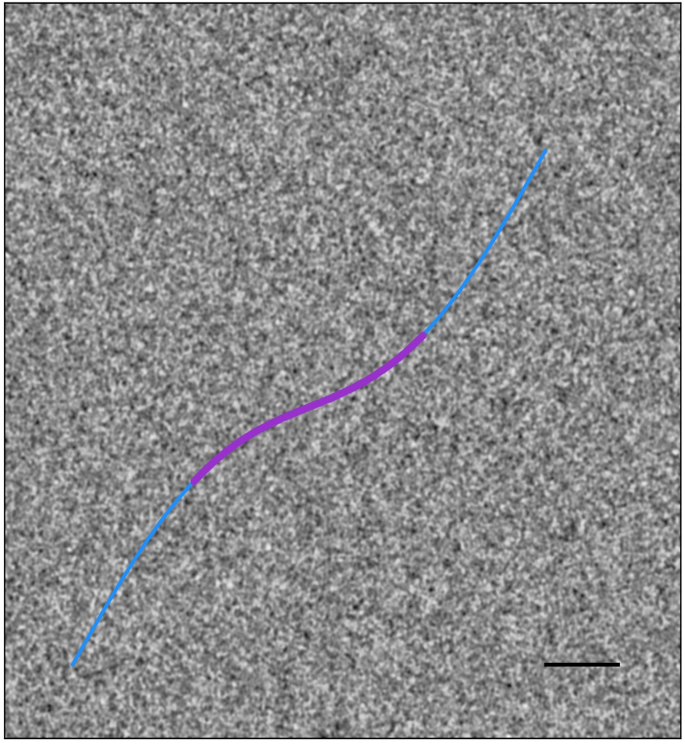
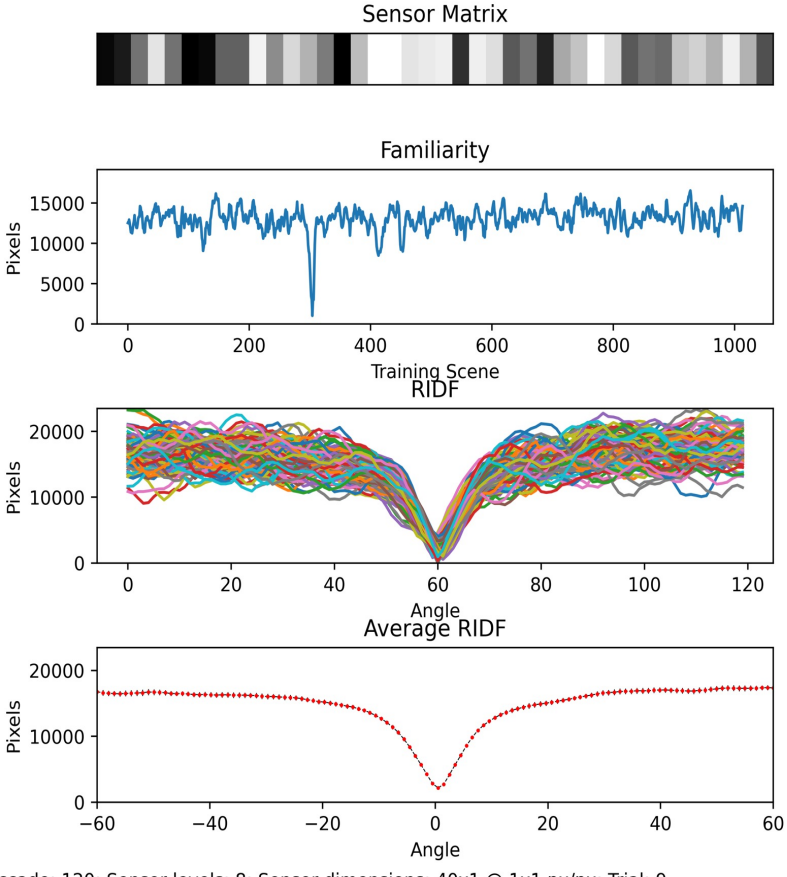
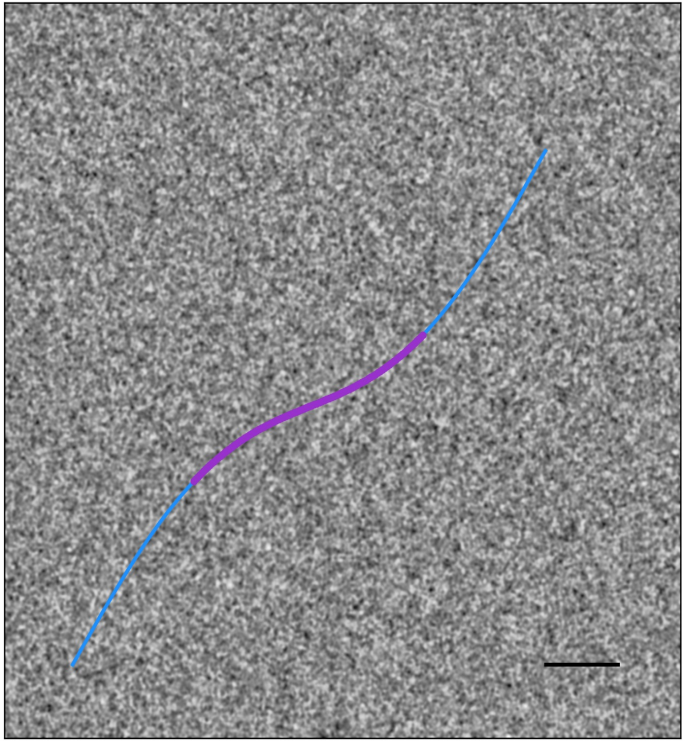
10000
5000
Sensor regions

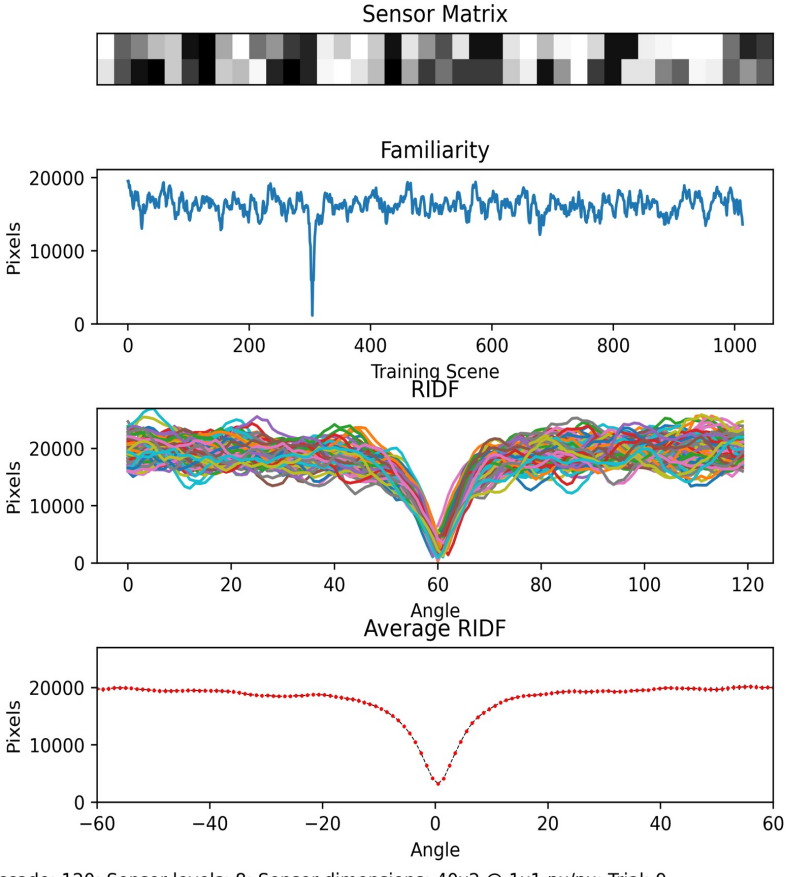




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

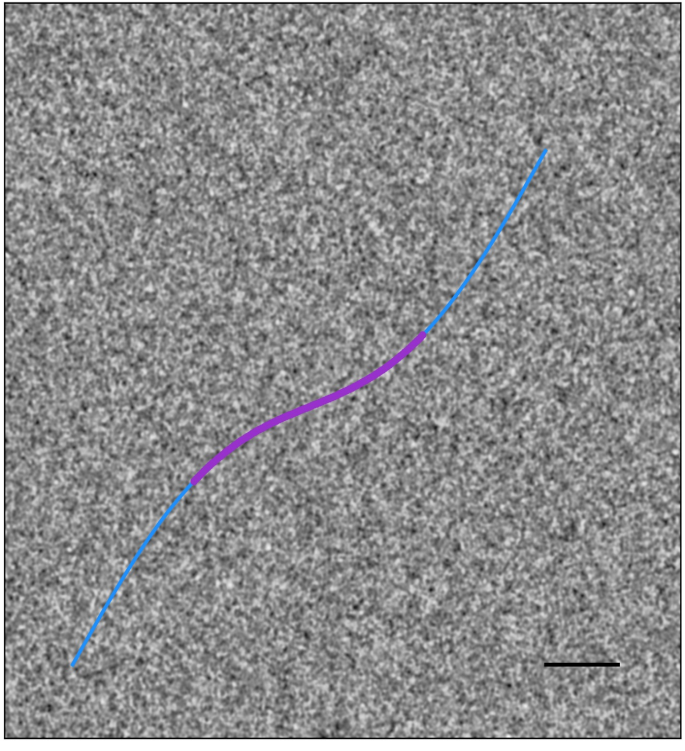
Navigation stats: RMSD error: 44.64; RMSD/dist: 0.112; TD: 11094; p90: 18; p50: 10; complete: 0

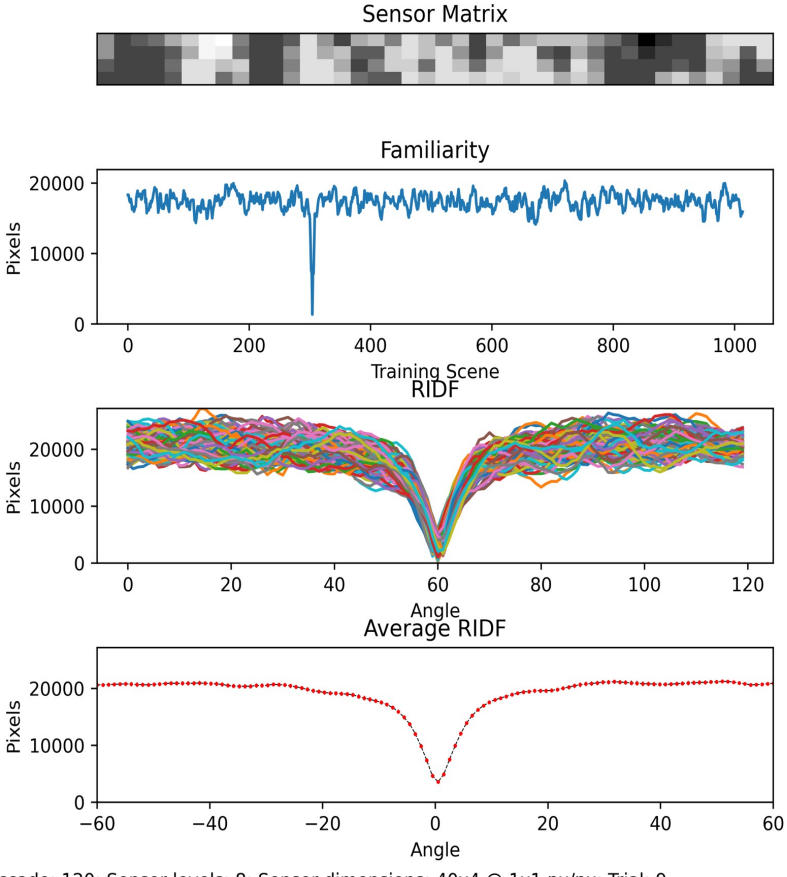




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

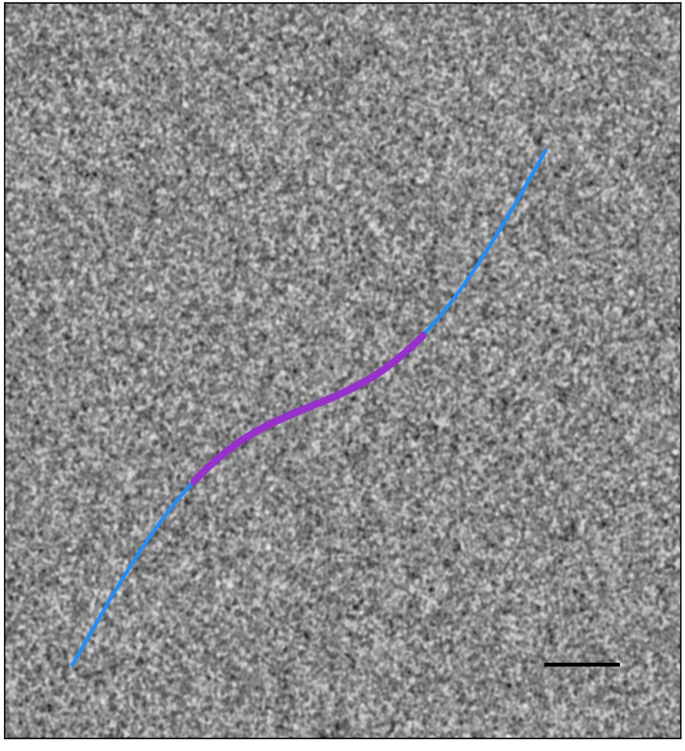
Navigation stats: RMSD error: 50.65; RMSD/dist: 0.127; TD: 12836; p90: 16; p50: 8; complete: 0

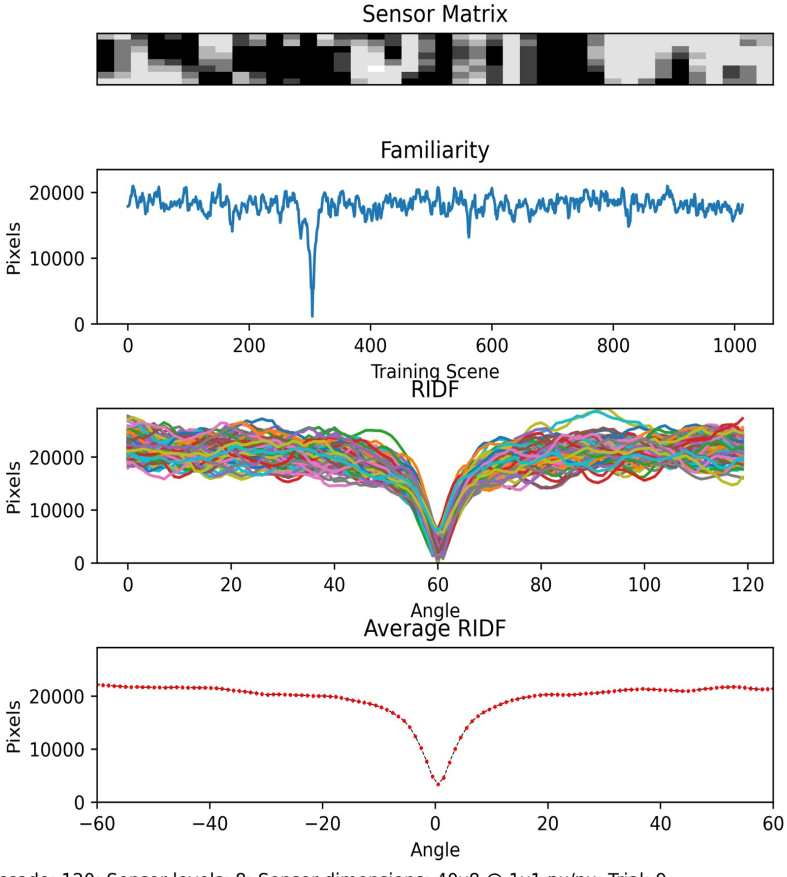




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

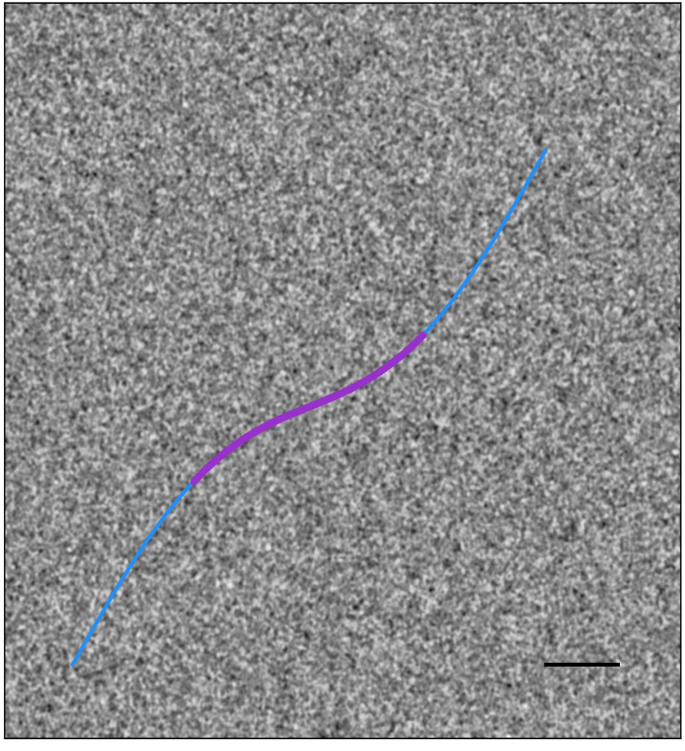
Navigation stats: RMSD error: 52.47; RMSD/dist: 0.131; TD: 13813; p90: 14; p50: 6; complete: 0

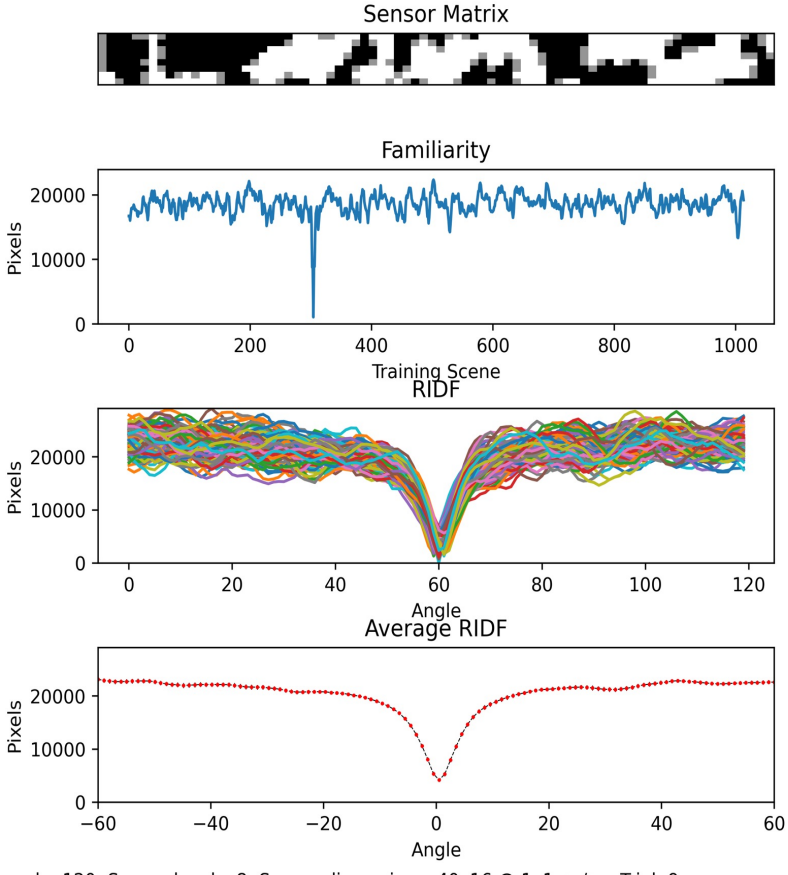




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

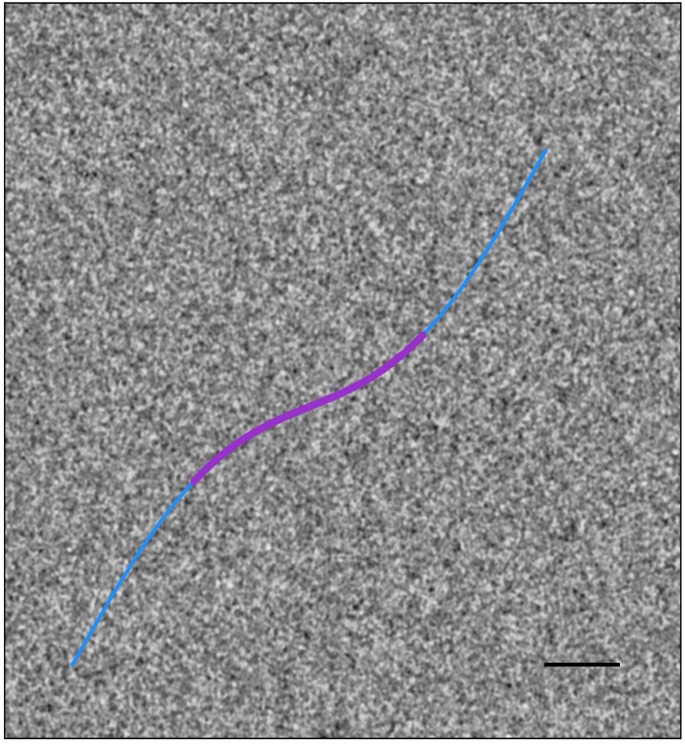
Navigation stats: RMSD error: 34.14; RMSD/dist: 0.085; TD: 14493; p90: 14; p50: 6; complete: 0

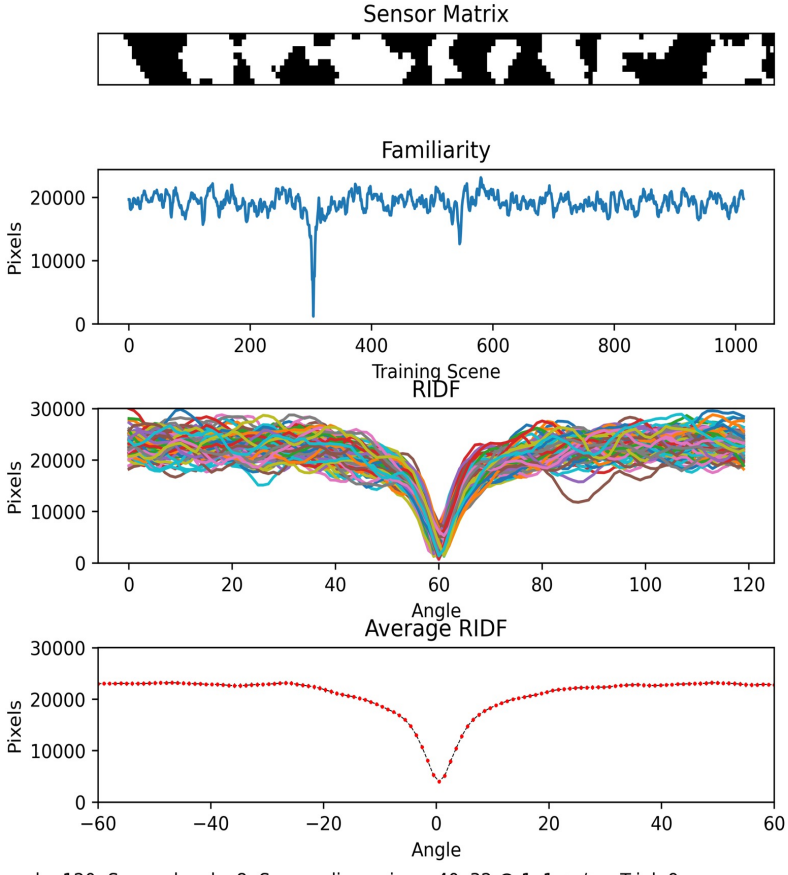




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

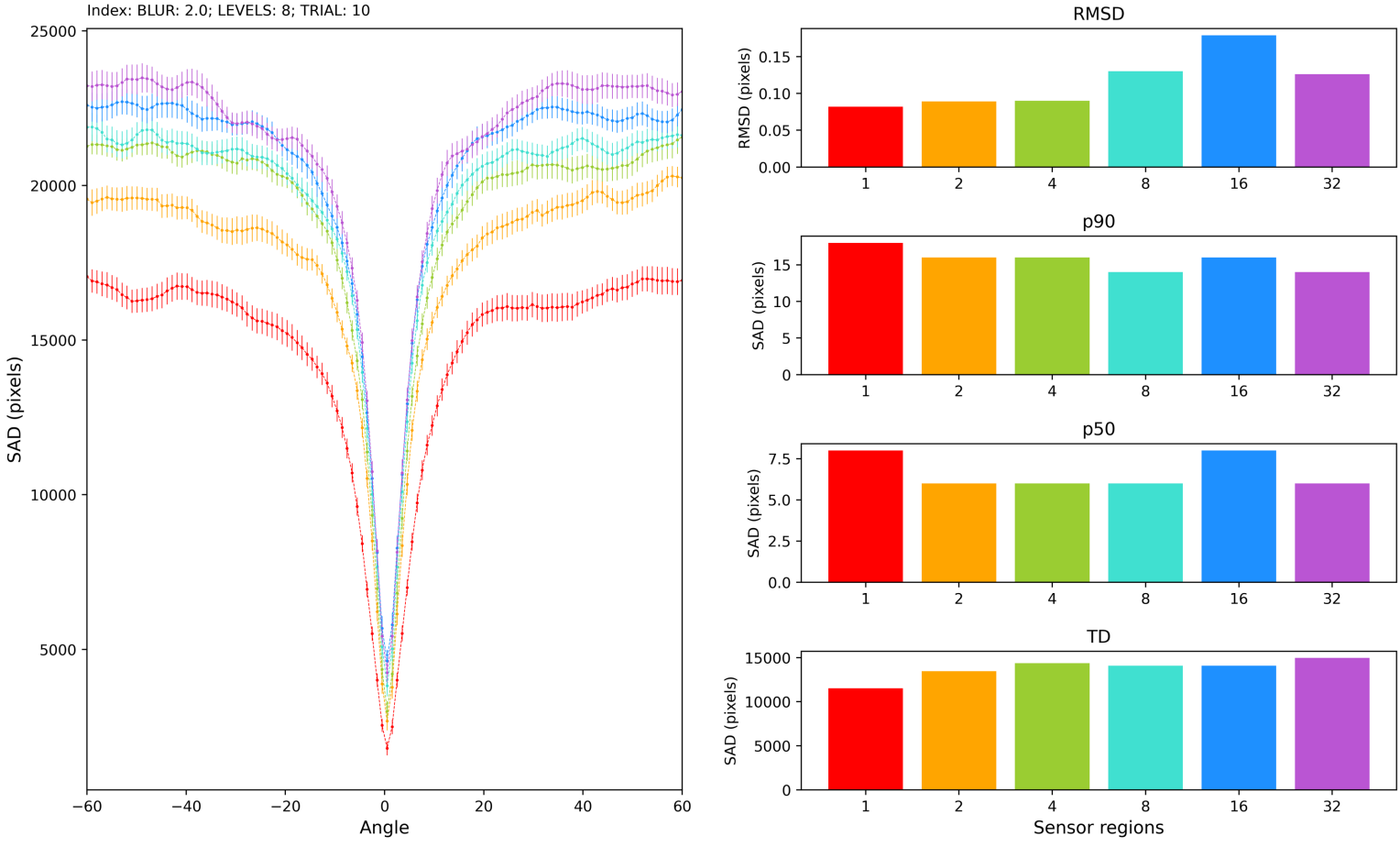
Navigation stats: RMSD error: 51.38; RMSD/dist: 0.128; TD: 14633; p90: 16; p50: 6; complete: 0

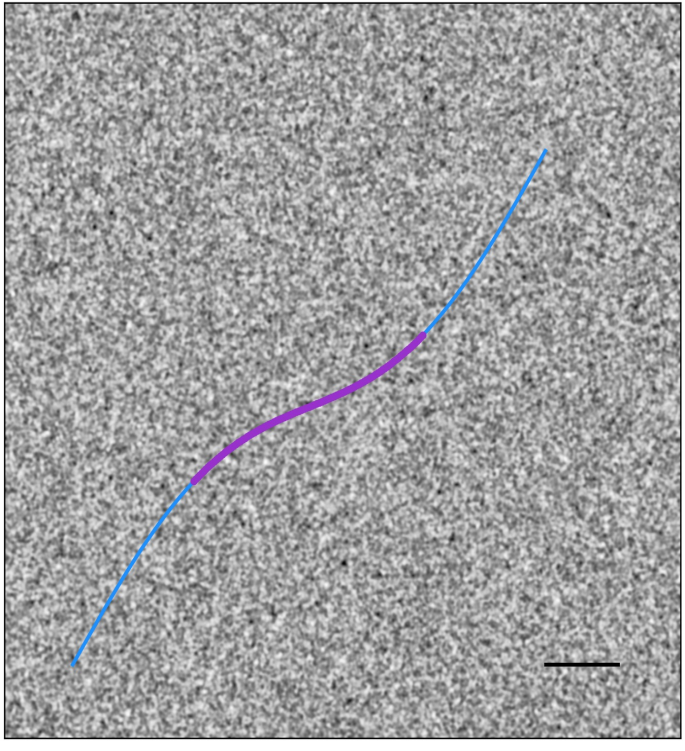


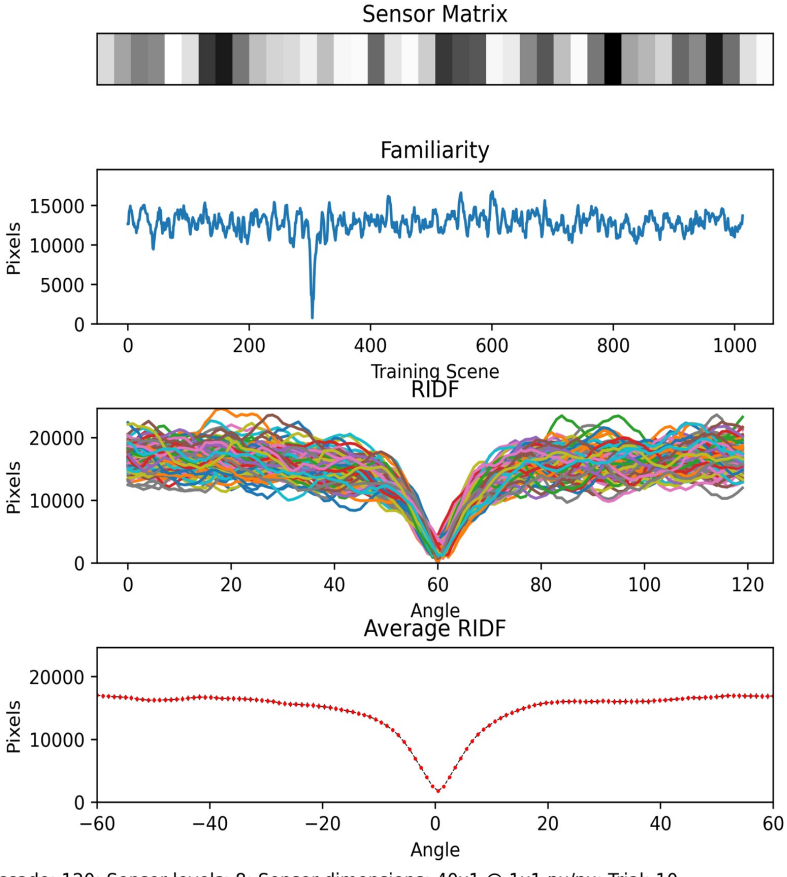


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 49.47; RMSD/dist: 0.124; TD: 15198; p90: 16; p50: 6; complete: 0

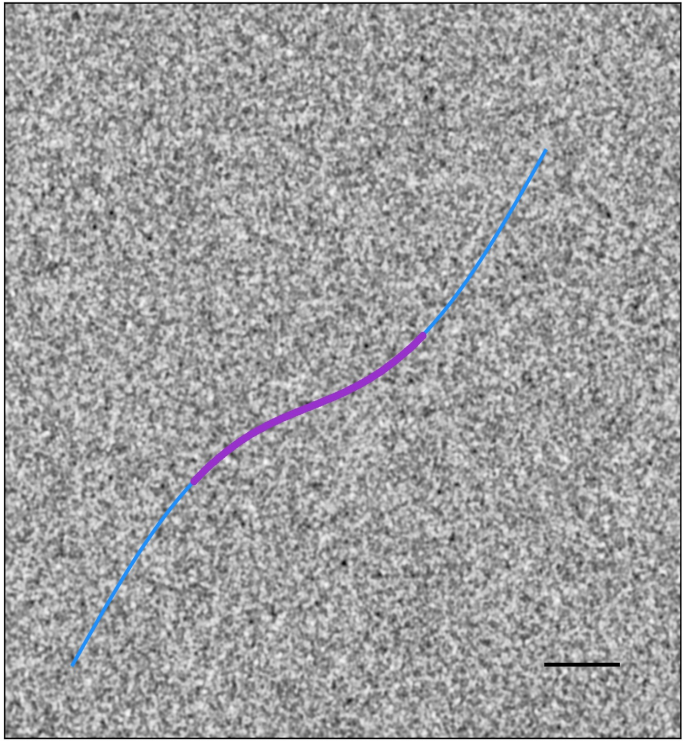

Index: BLUR: 2.0; LEVELS: 8; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

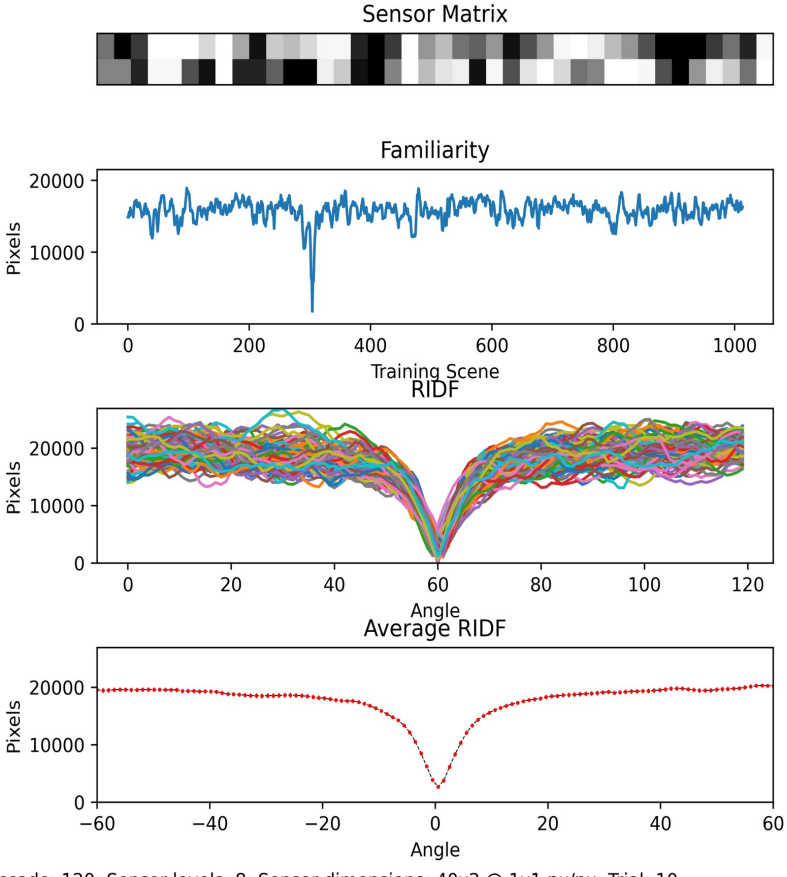




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

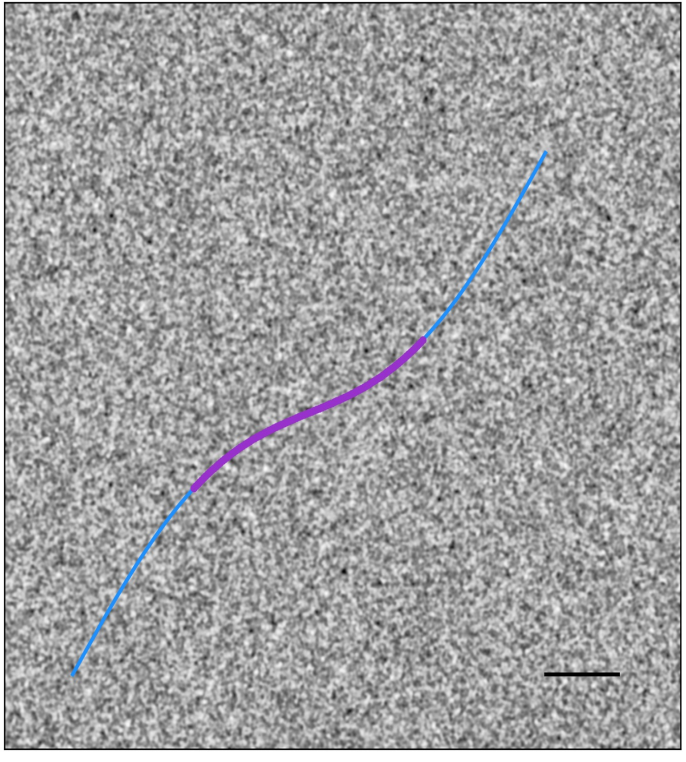
Navigation stats: RMSD error: 32.76; RMSD/dist: 0.082; TD: 11510; p90: 18; p50: 8; complete: 0

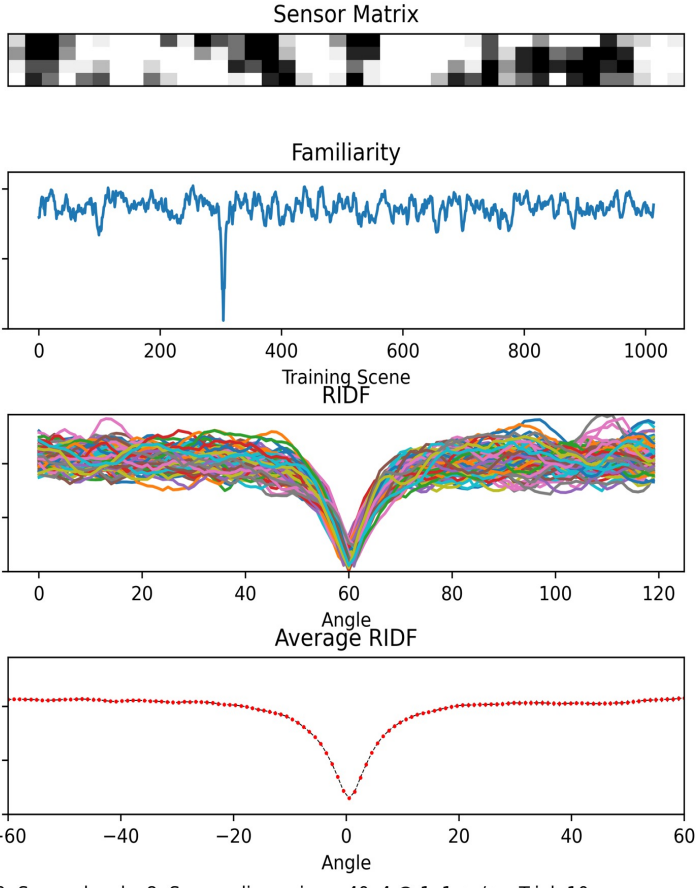




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

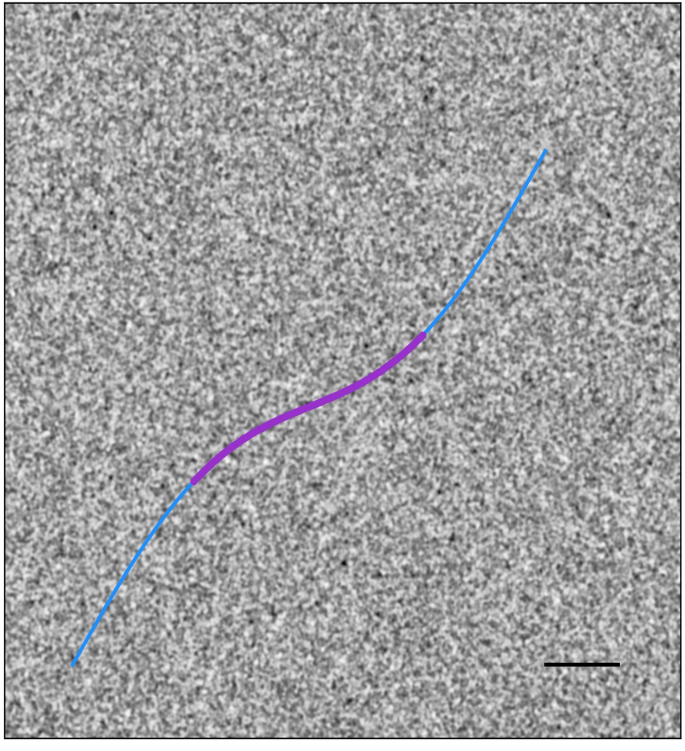
Navigation stats: RMSD error: 35.78; RMSD/dist: 0.089; TD: 13454; p90: 16; p50: 6; complete: 0

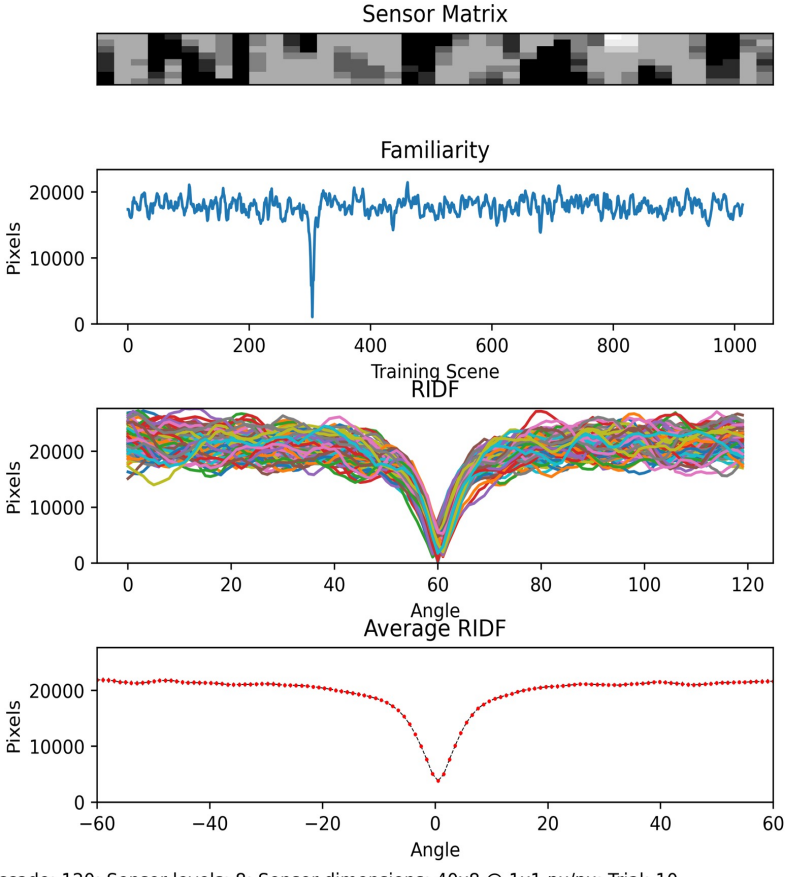




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

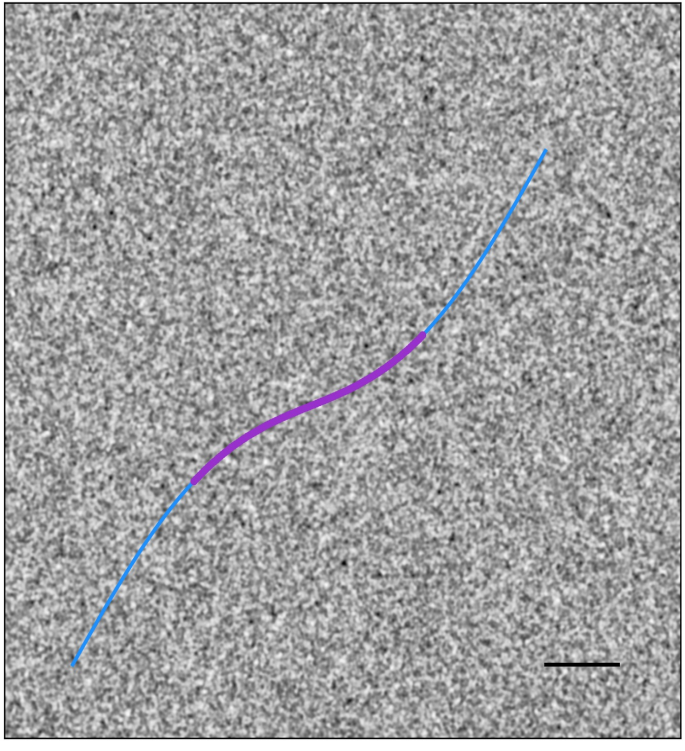
Navigation stats: RMSD error: 36.12; RMSD/dist: 0.090; TD: 14377; p90: 16; p50: 6; complete: 0

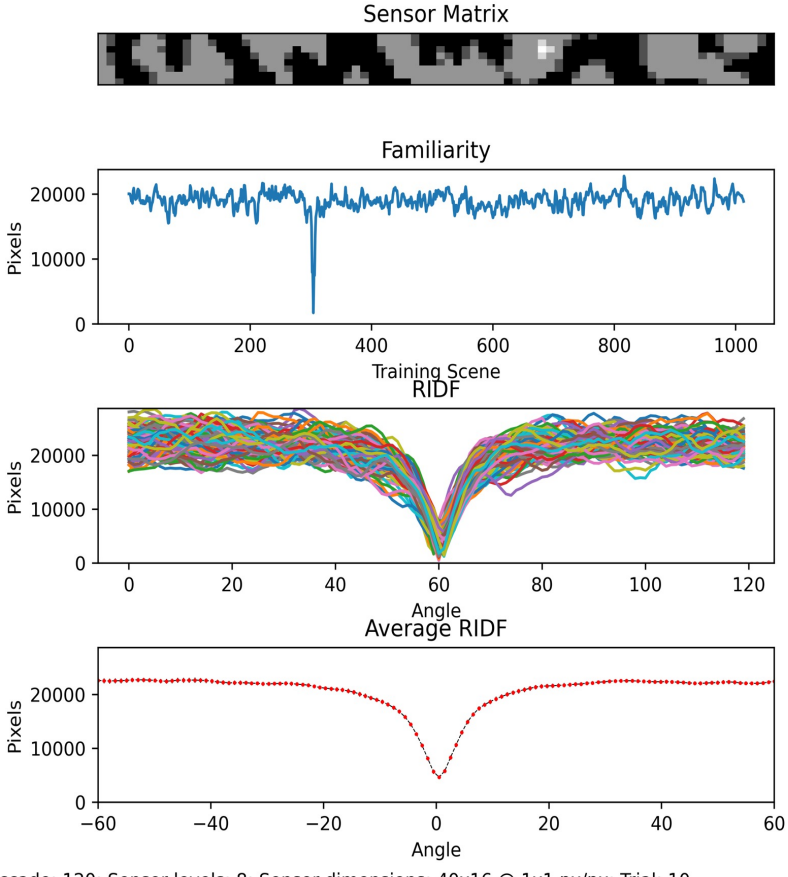




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

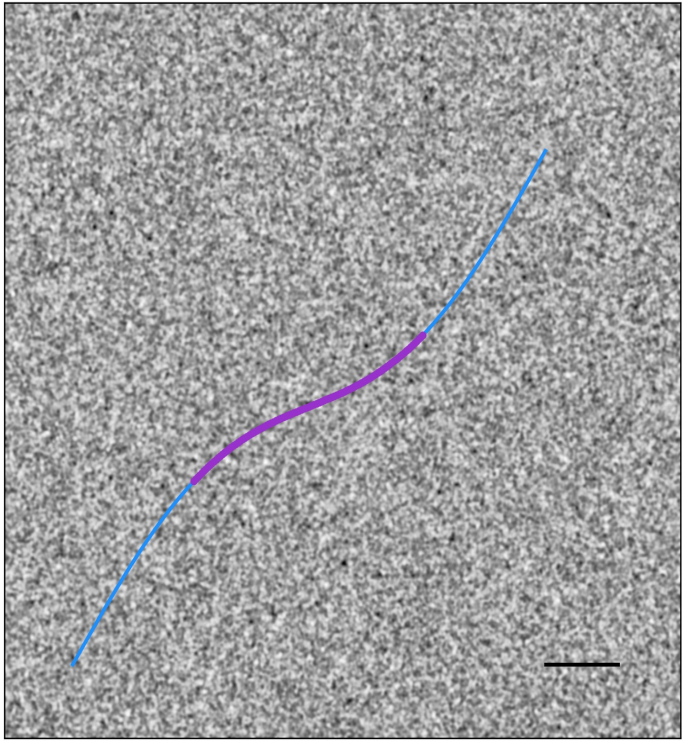
Navigation stats: RMSD error: 52.19; RMSD/dist: 0.130; TD: 14073; p90: 14; p50: 6; complete: 0

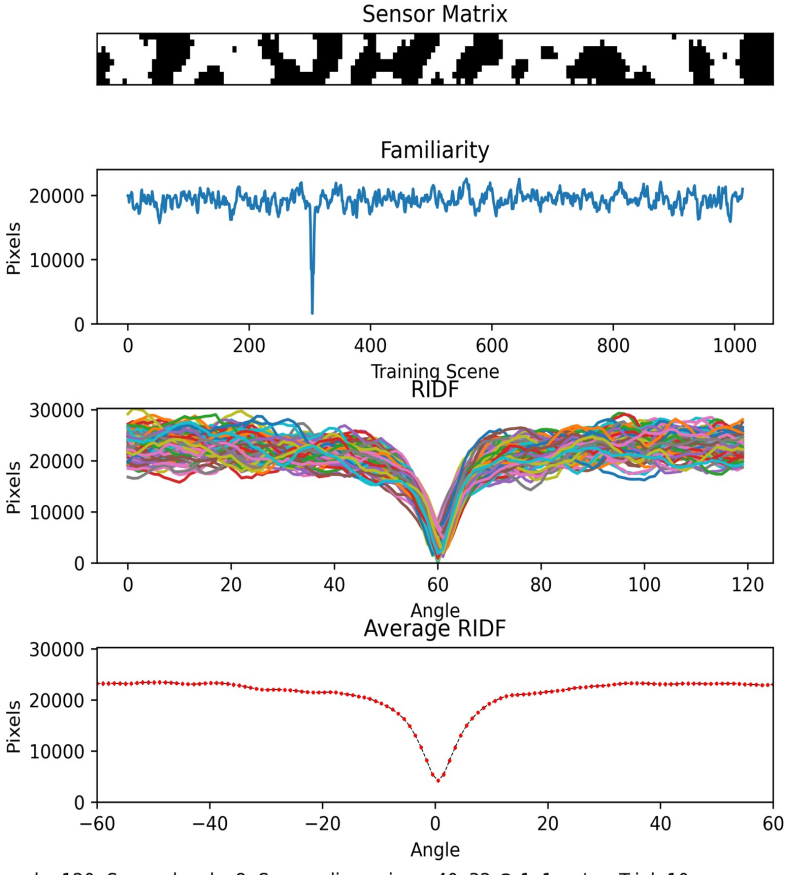




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 71.49; RMSD/dist: 0.179; TD: 14088; p90: 16; p50: 8; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 50.38; RMSD/dist: 0.126; TD: 14958; p90: 14; p50: 6; complete: 0