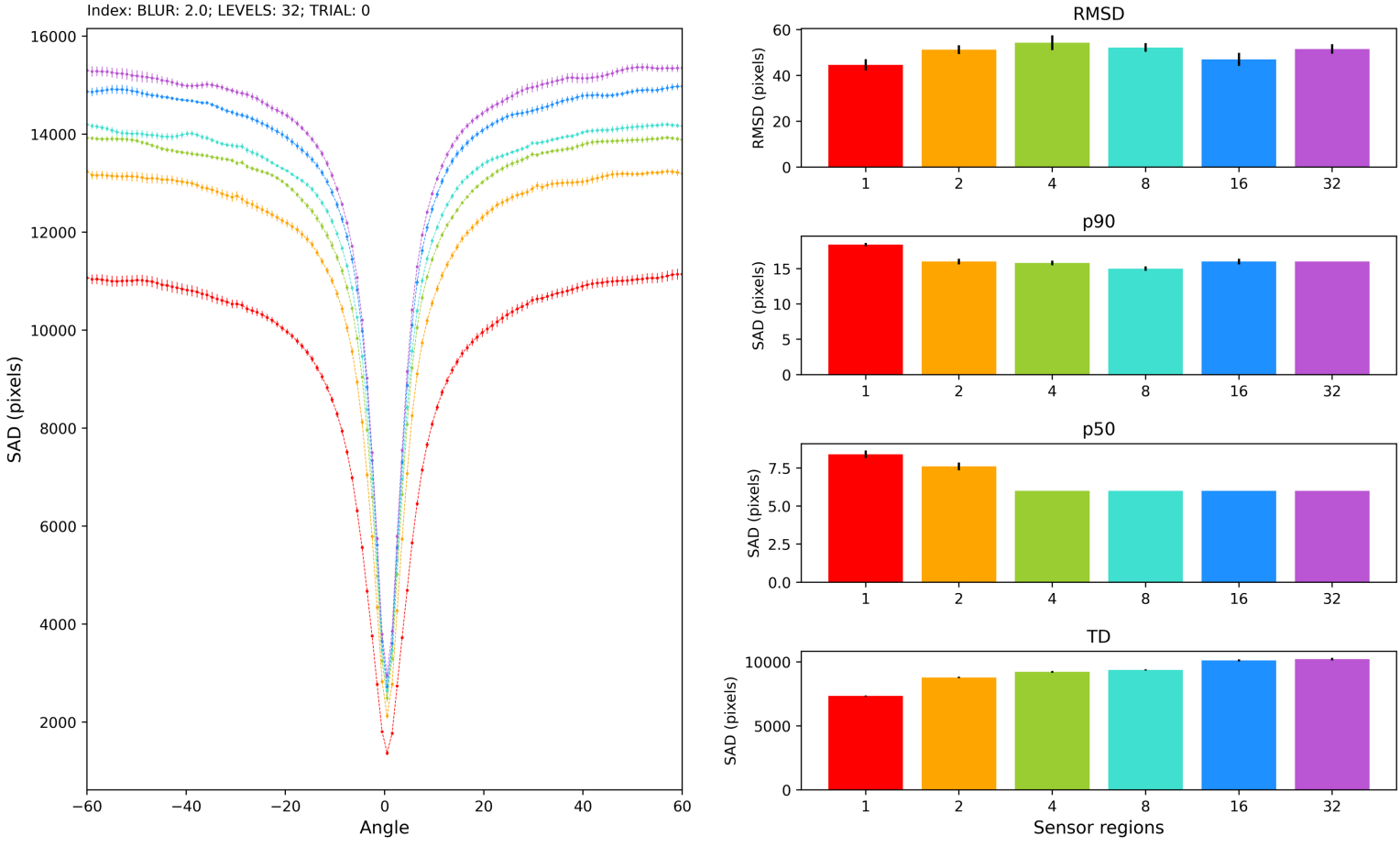
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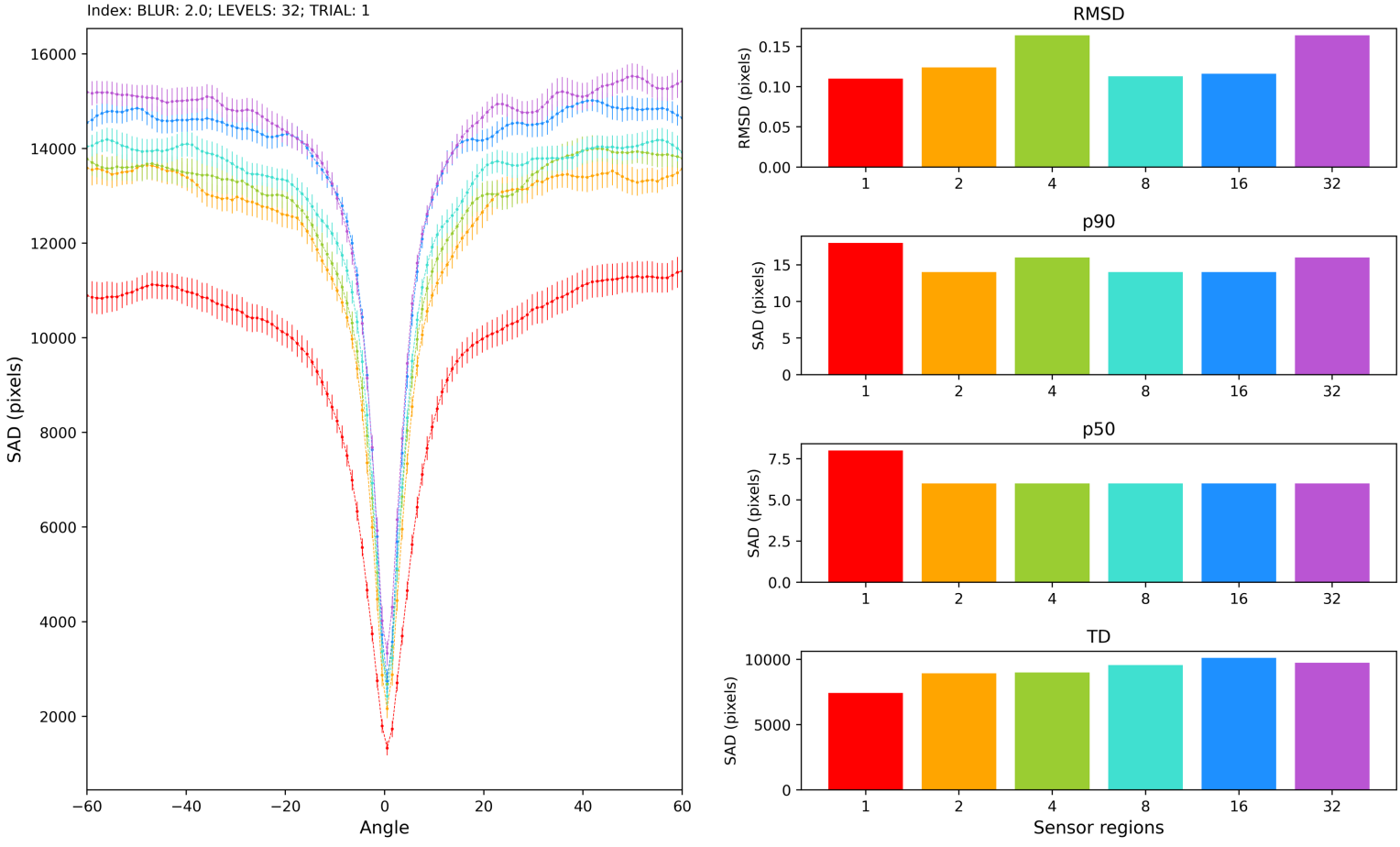
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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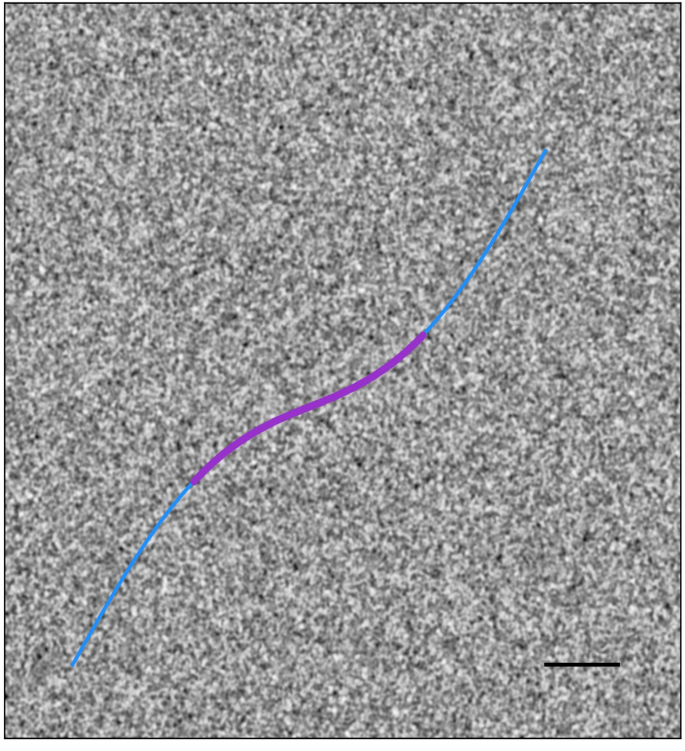
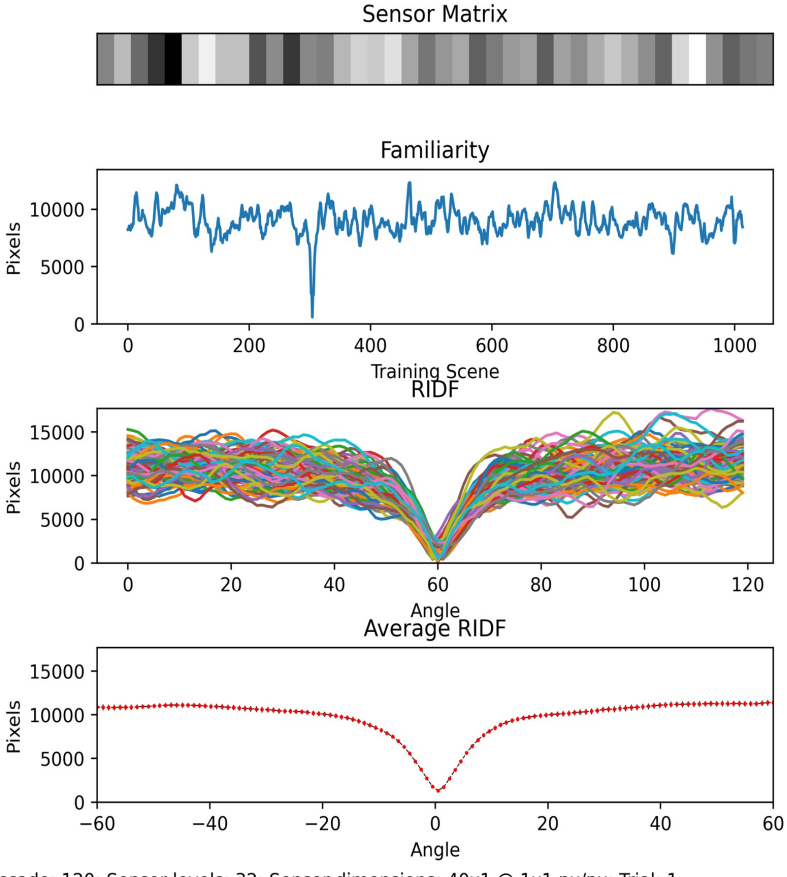
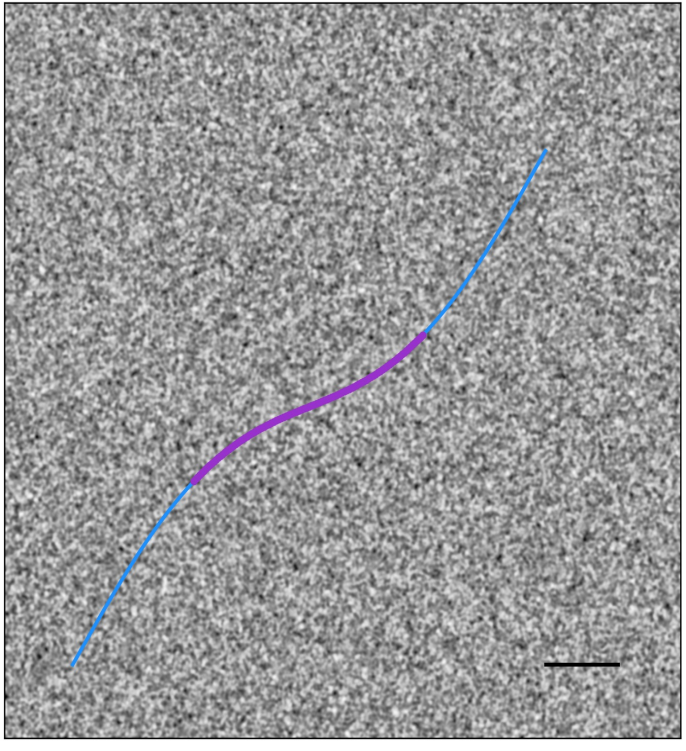
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

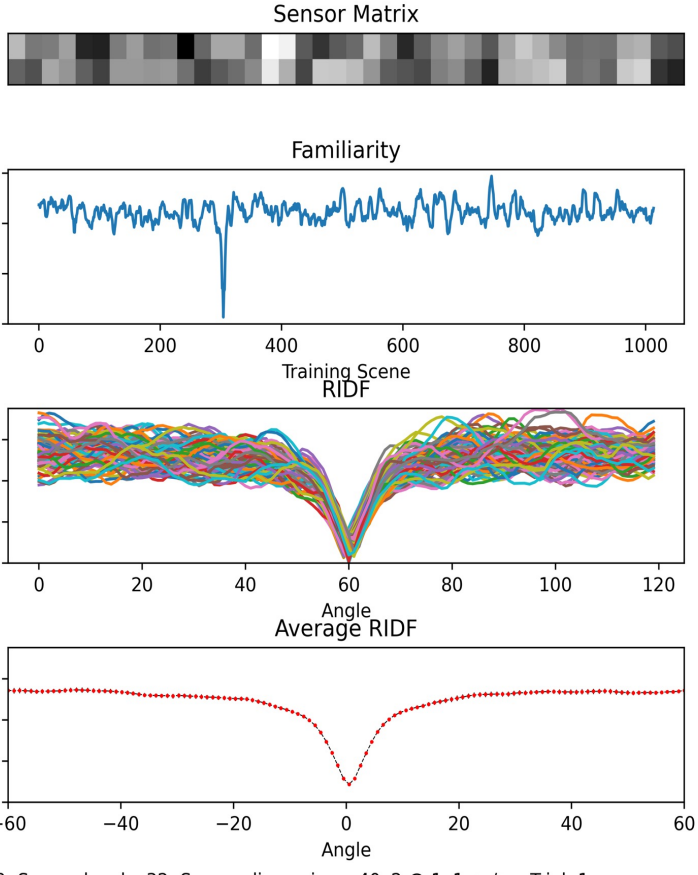




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

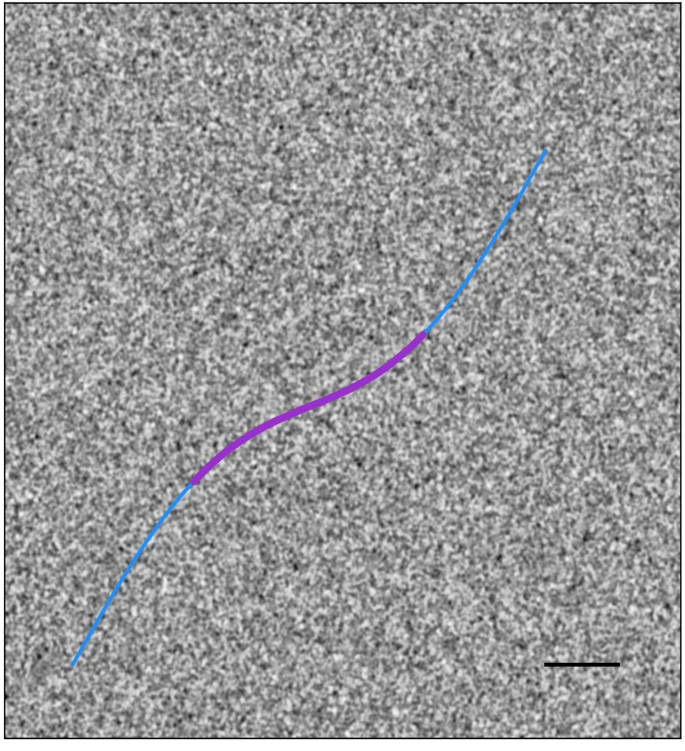
Navigation stats: RMSD error: 44.15; RMSD/dist: 0.110; TD: 7431; p90: 18; p50: 8; complete: 0

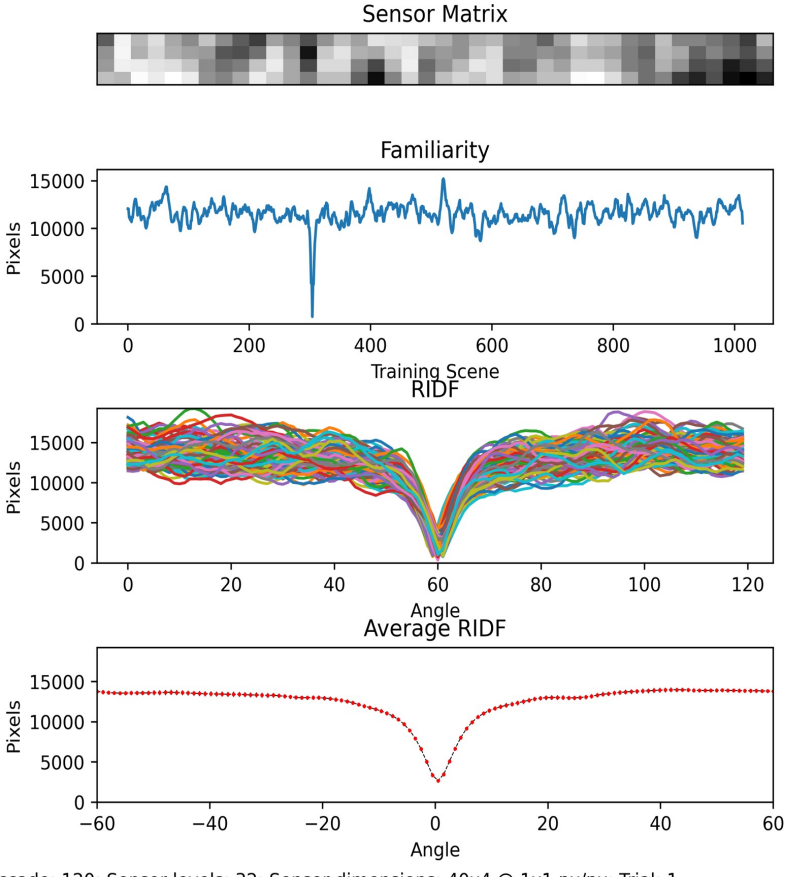




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

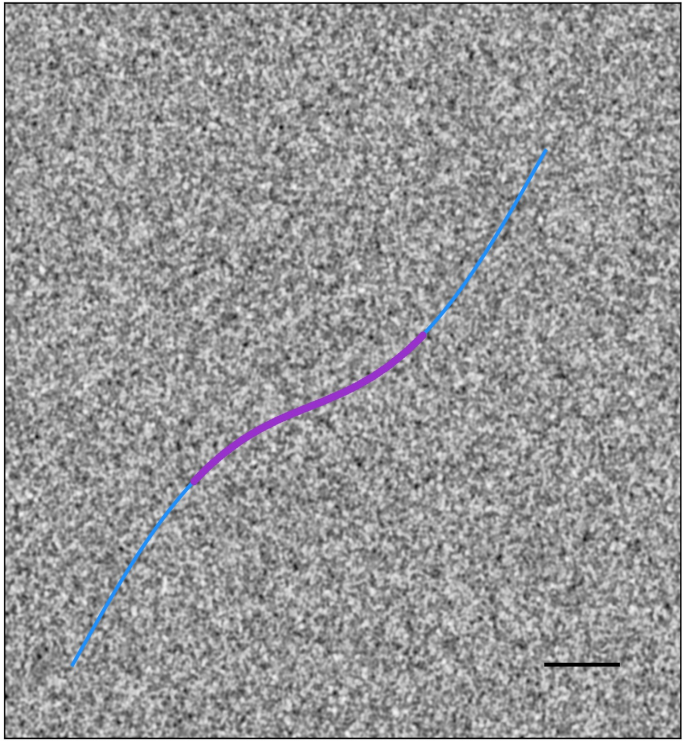
Navigation stats: RMSD error: 49.64; RMSD/dist: 0.124; TD: 8931; p90: 14; p50: 6; complete: 0

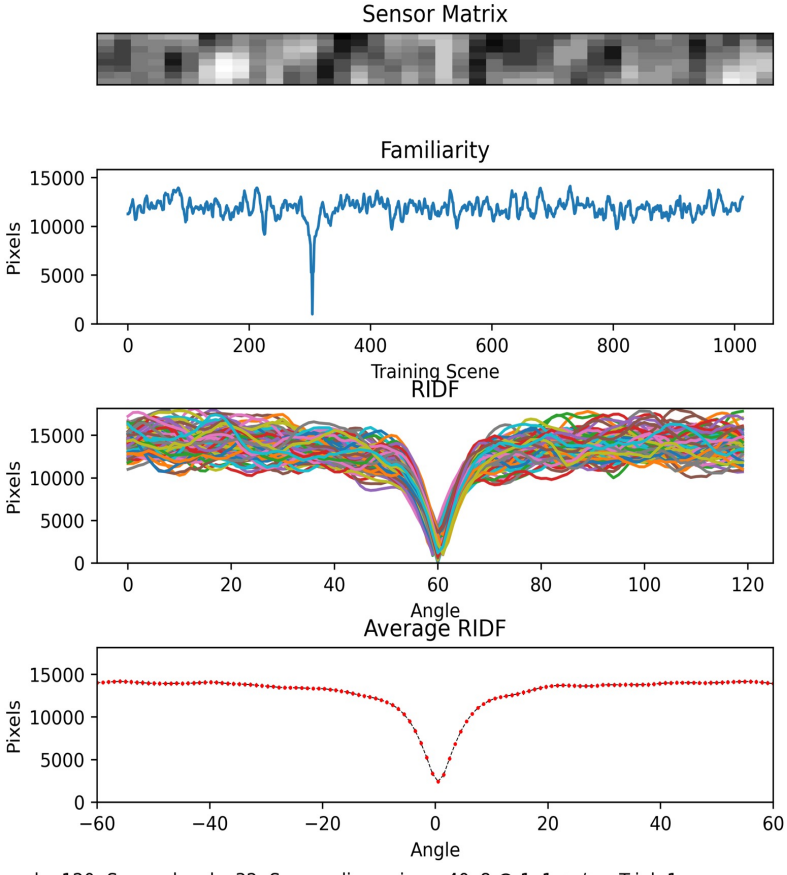




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

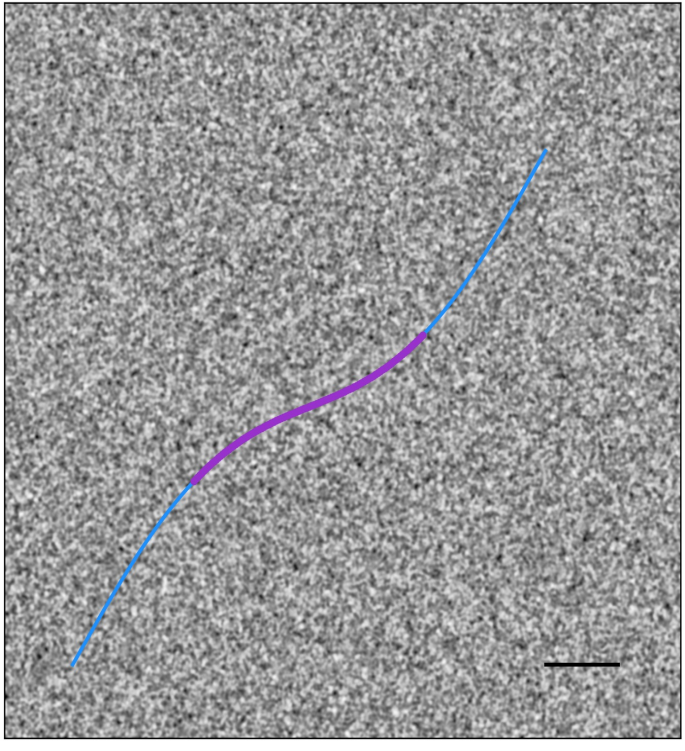
Navigation stats: RMSD error: 65.79; RMSD/dist: 0.164; TD: 9006; p90: 16; p50: 6; complete: 0

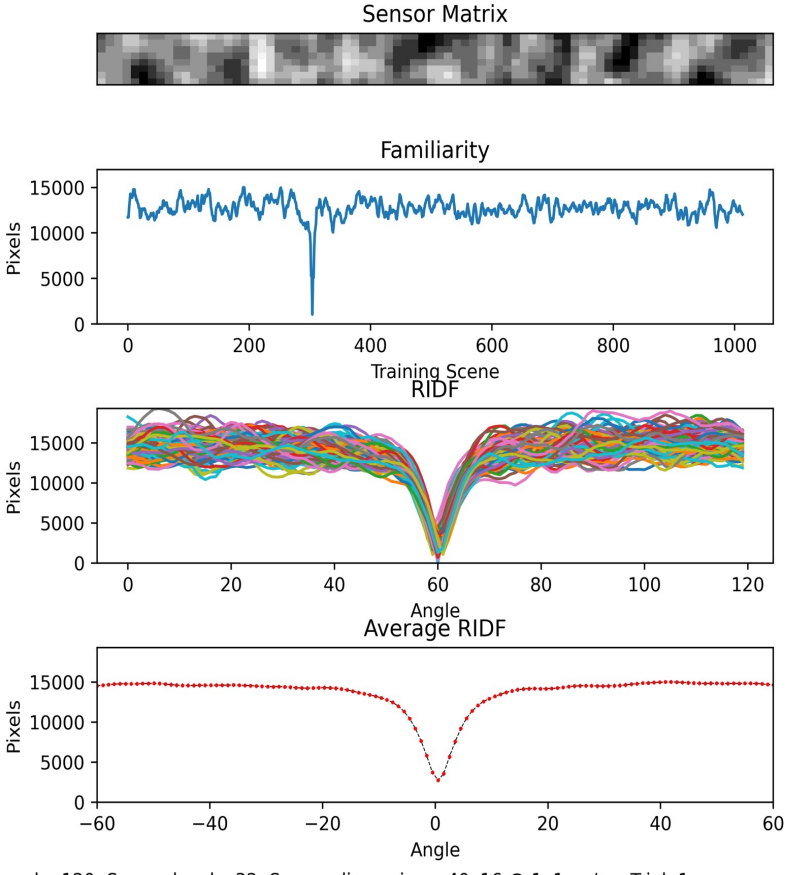




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

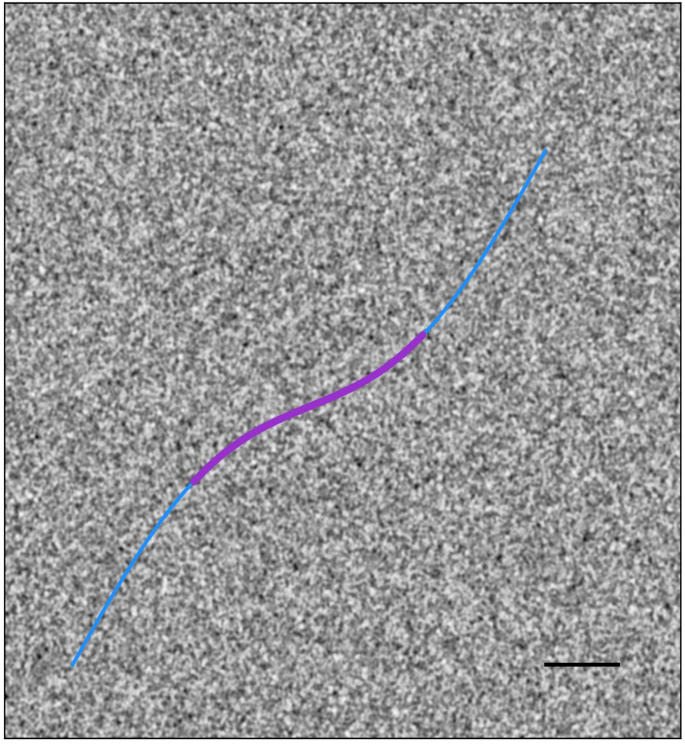
Navigation stats: RMSD error: 45.21; RMSD/dist: 0.113; TD: 9560; p90: 14; p50: 6; complete: 0

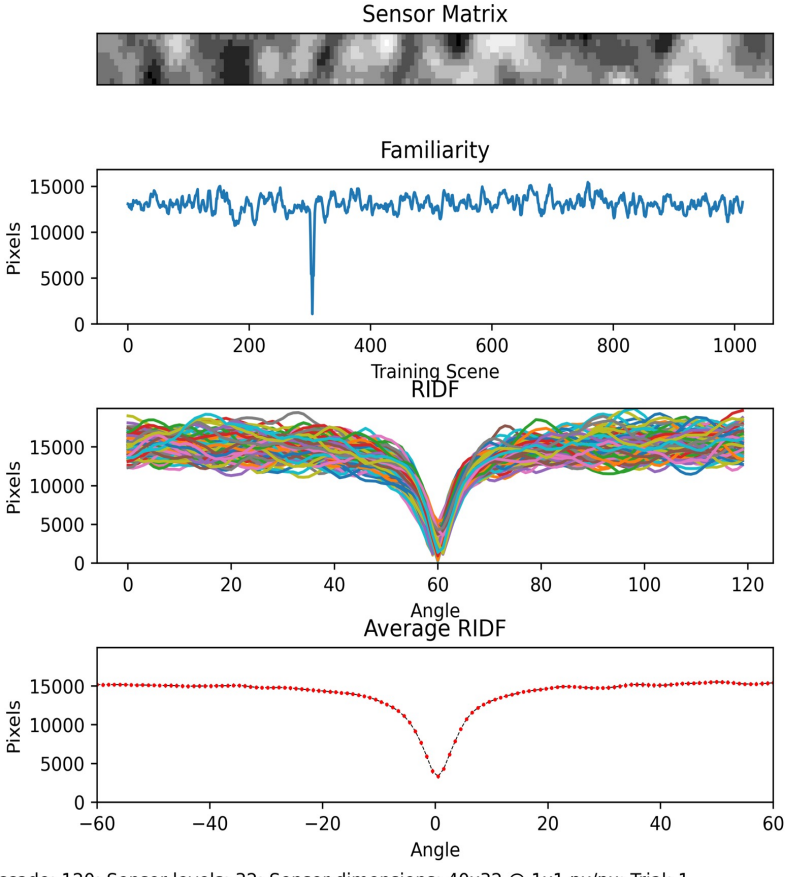




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

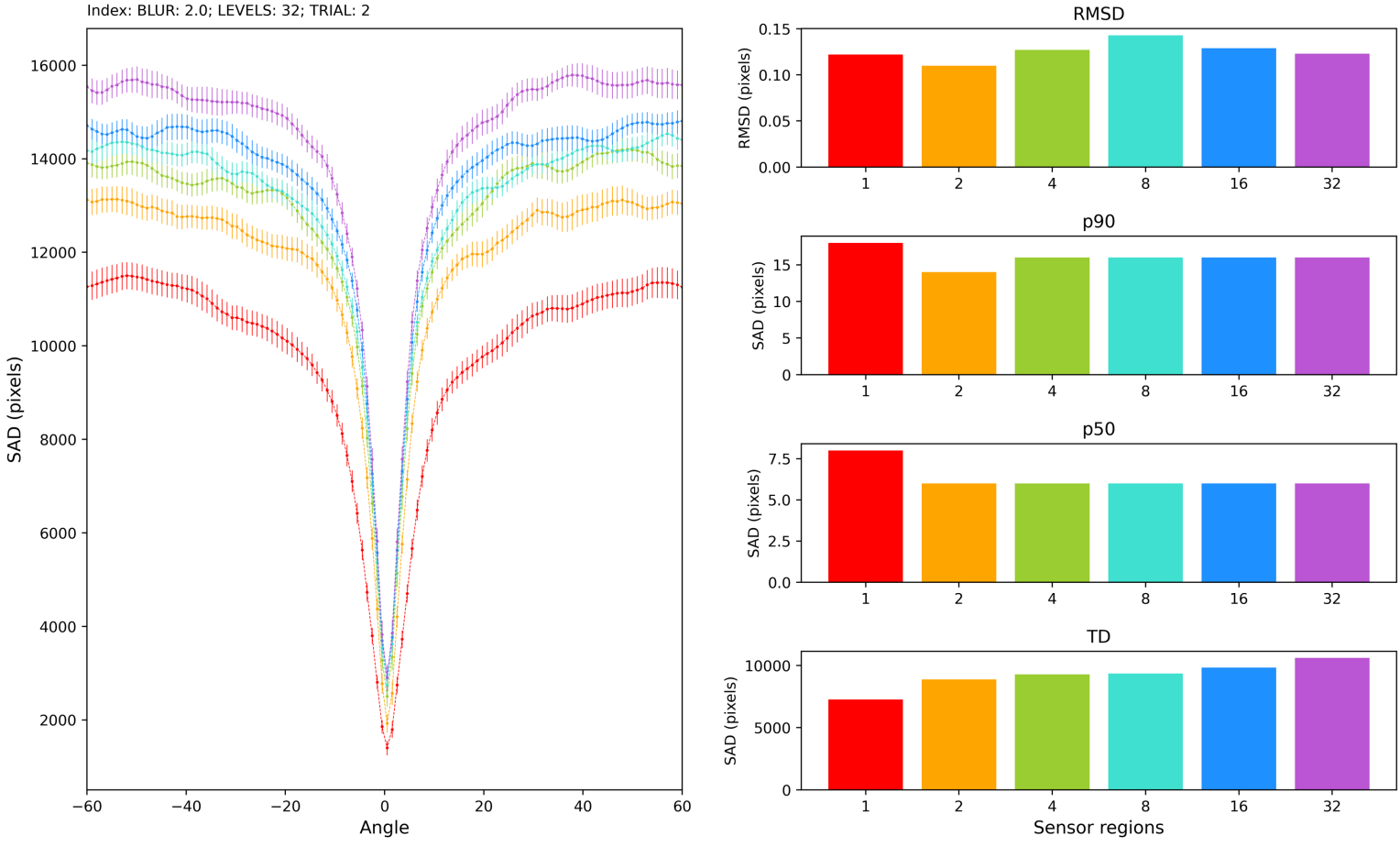
Navigation stats: RMSD error: 46.51; RMSD/dist: 0.116; TD: 10110; p90: 14; p50: 6; complete: 0

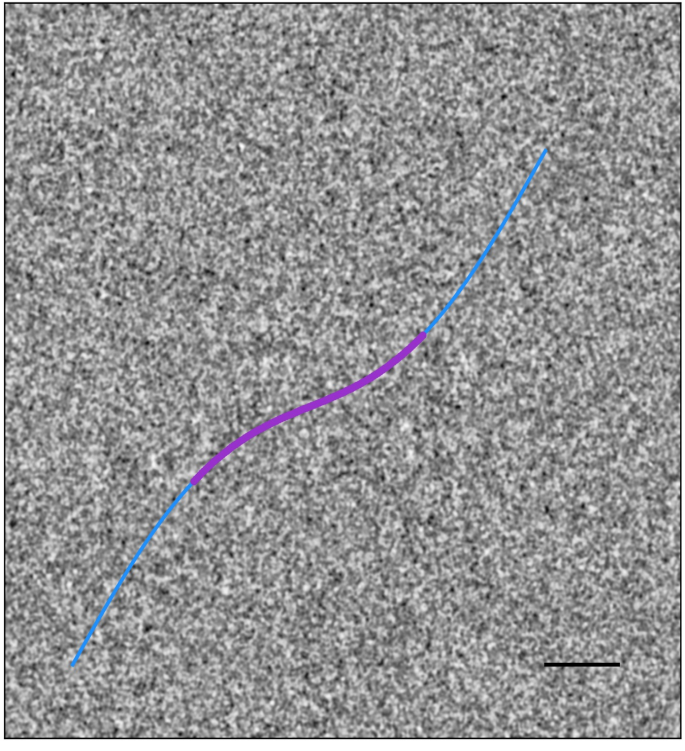


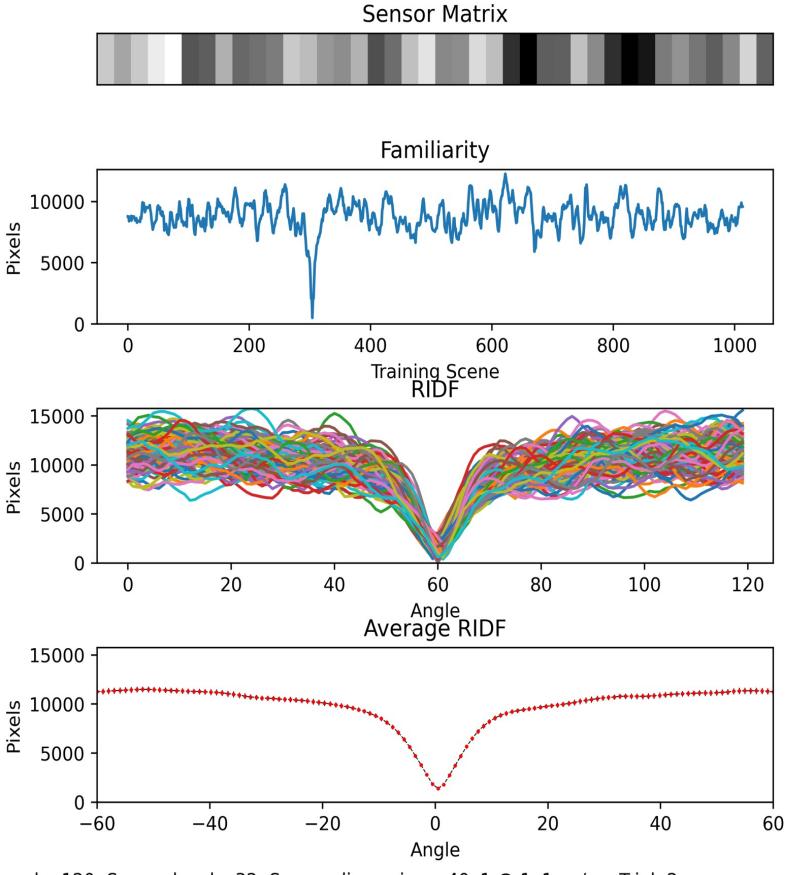


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 65.75; RMSD/dist: 0.164; TD: 9752; p90: 16; p50: 6; complete: 0

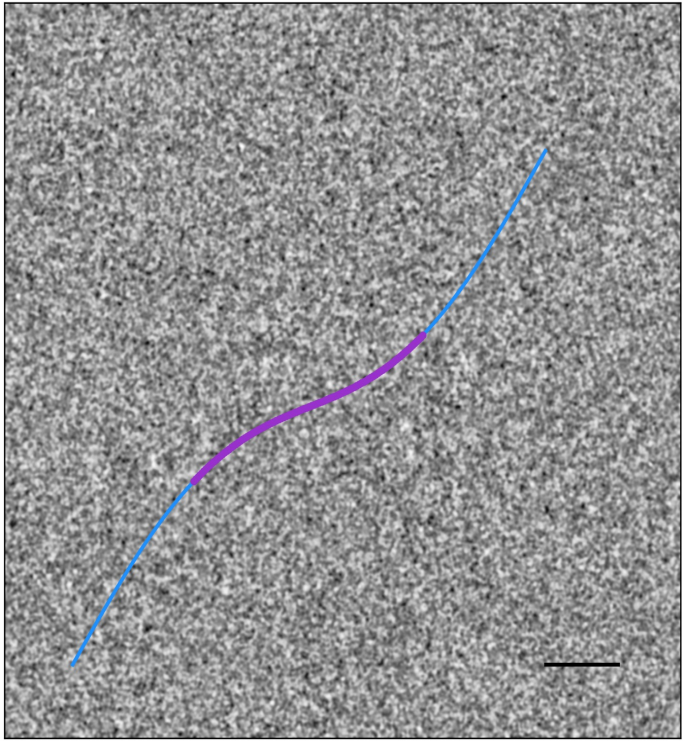

Index: BLUR: 2.0; LEVELS: 32; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

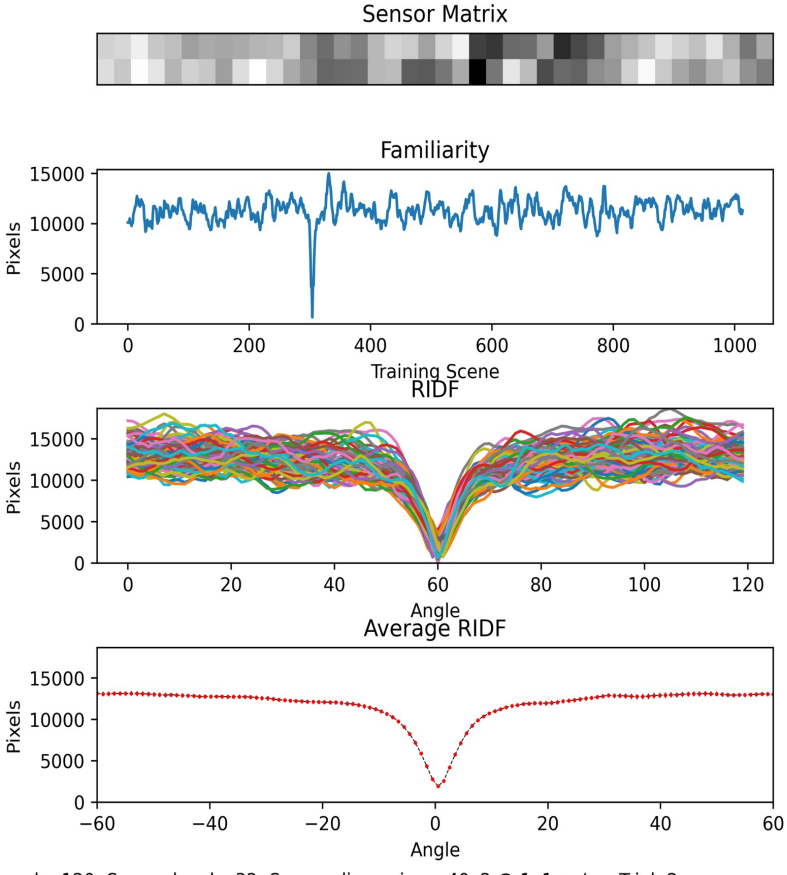




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

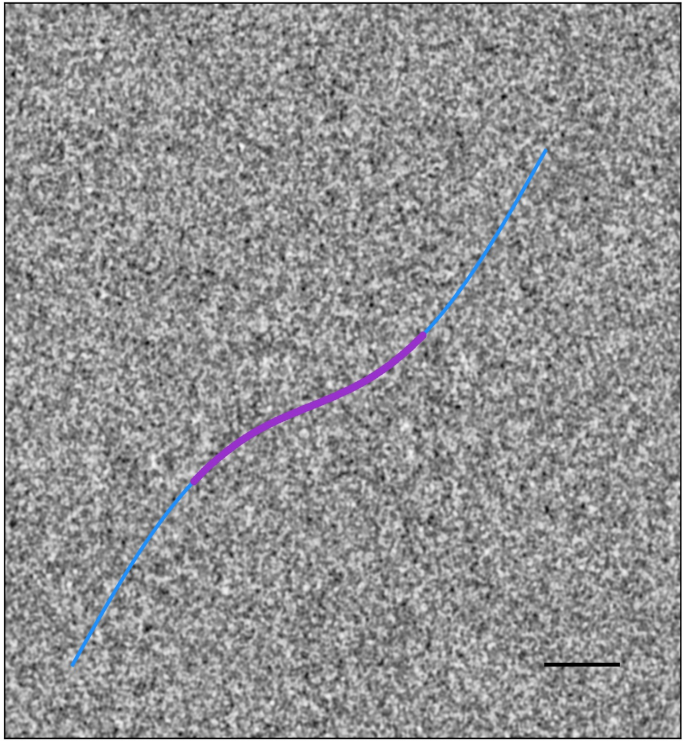
Navigation stats: RMSD error: 48.86; RMSD/dist: 0.122; TD: 7262; p90: 18; p50: 8; complete: 0

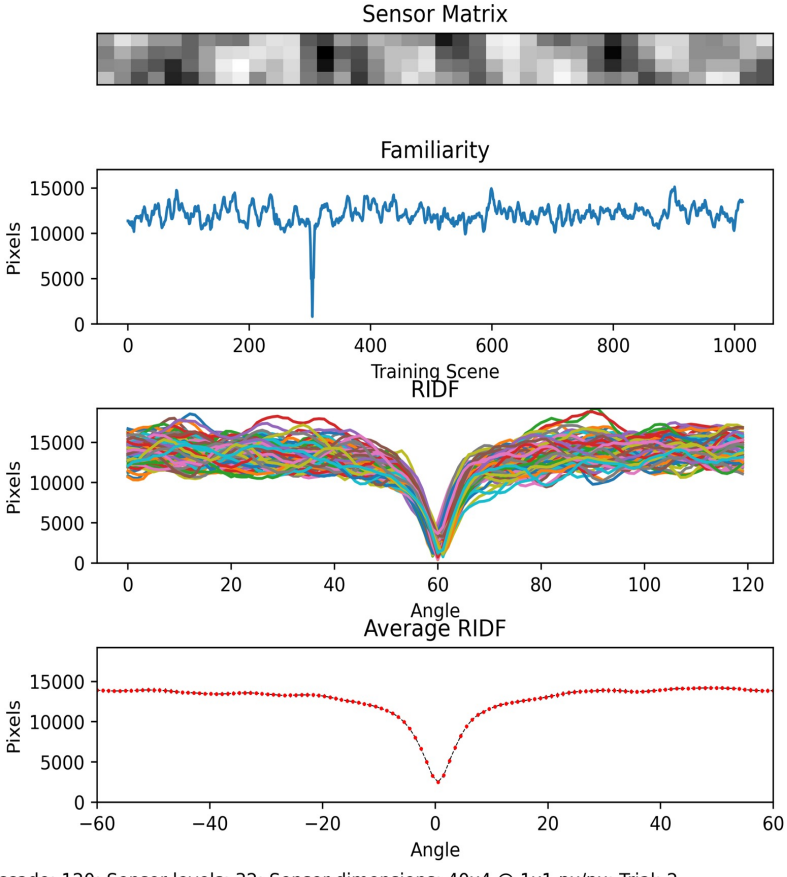




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

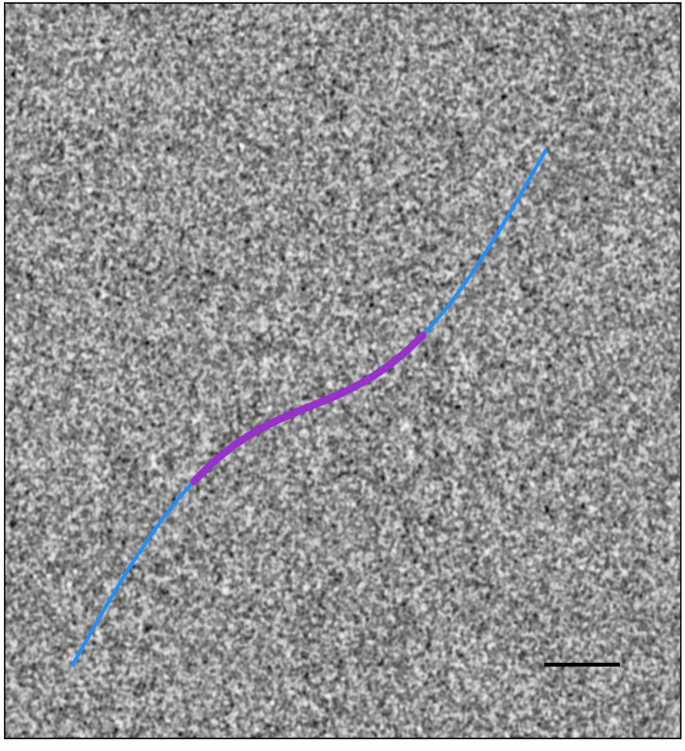
Navigation stats: RMSD error: 44.17; RMSD/dist: 0.110; TD: 8878; p90: 14; p50: 6; complete: 0

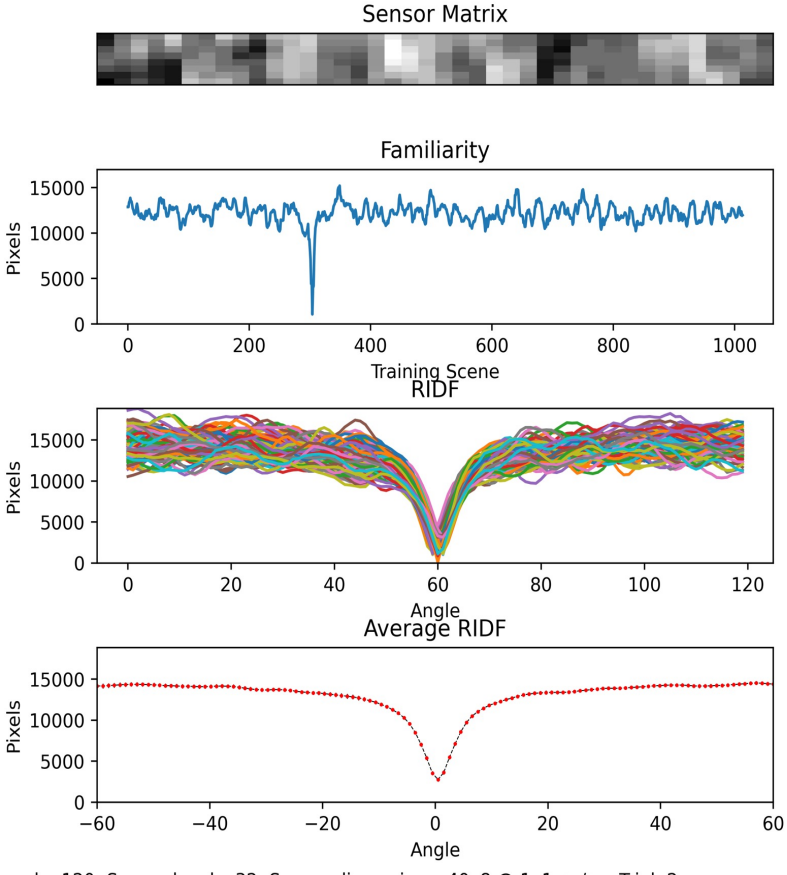




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

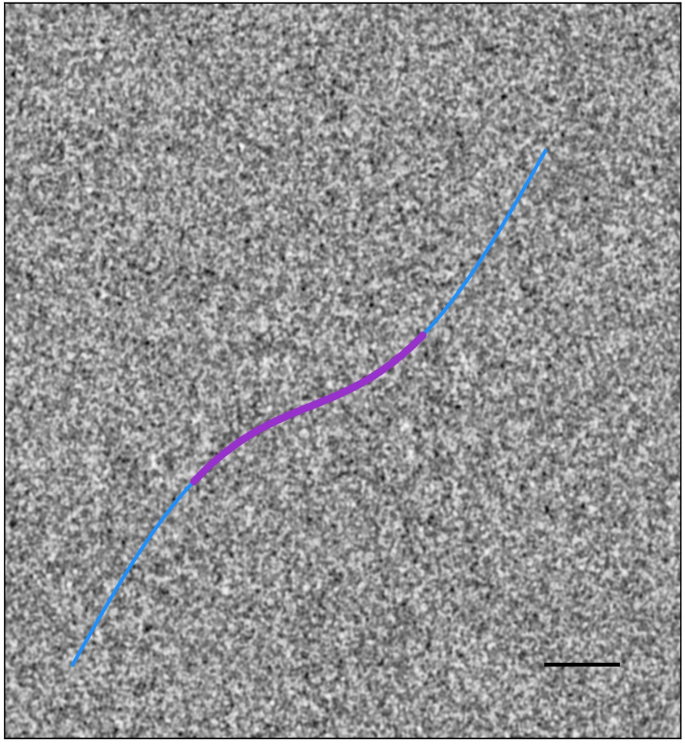
Navigation stats: RMSD error: 50.71; RMSD/dist: 0.127; TD: 9293; p90: 16; p50: 6; complete: 0

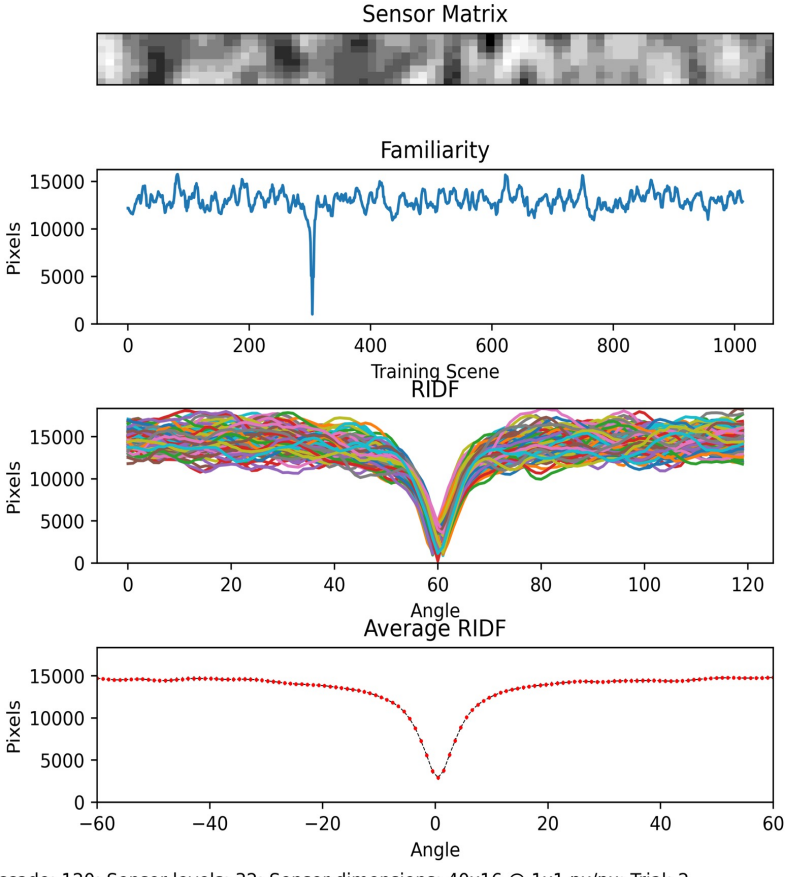




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

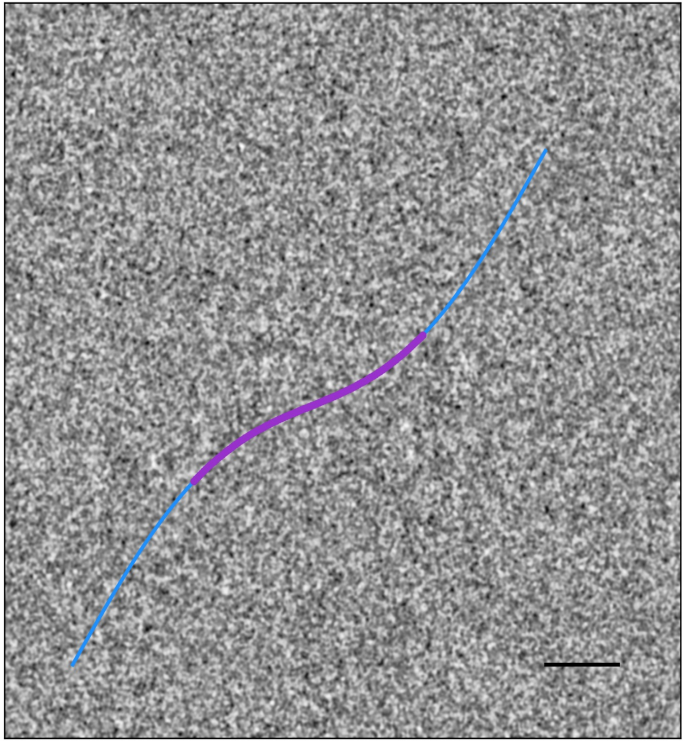
Navigation stats: RMSD error: 57.17; RMSD/dist: 0.143; TD: 9358; p90: 16; p50: 6; complete: 0

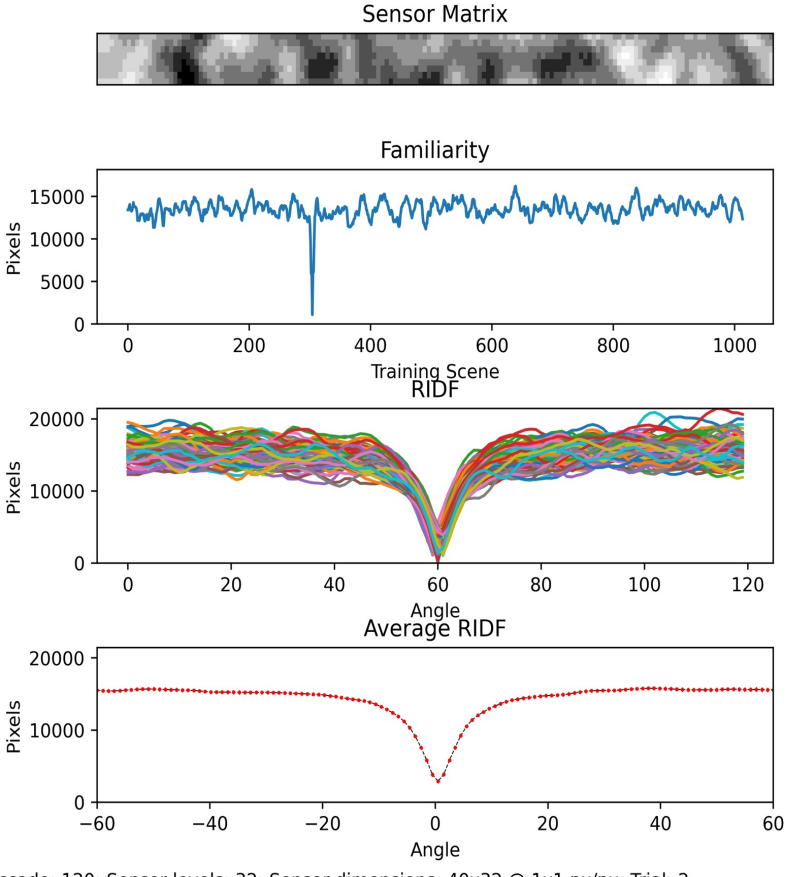




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

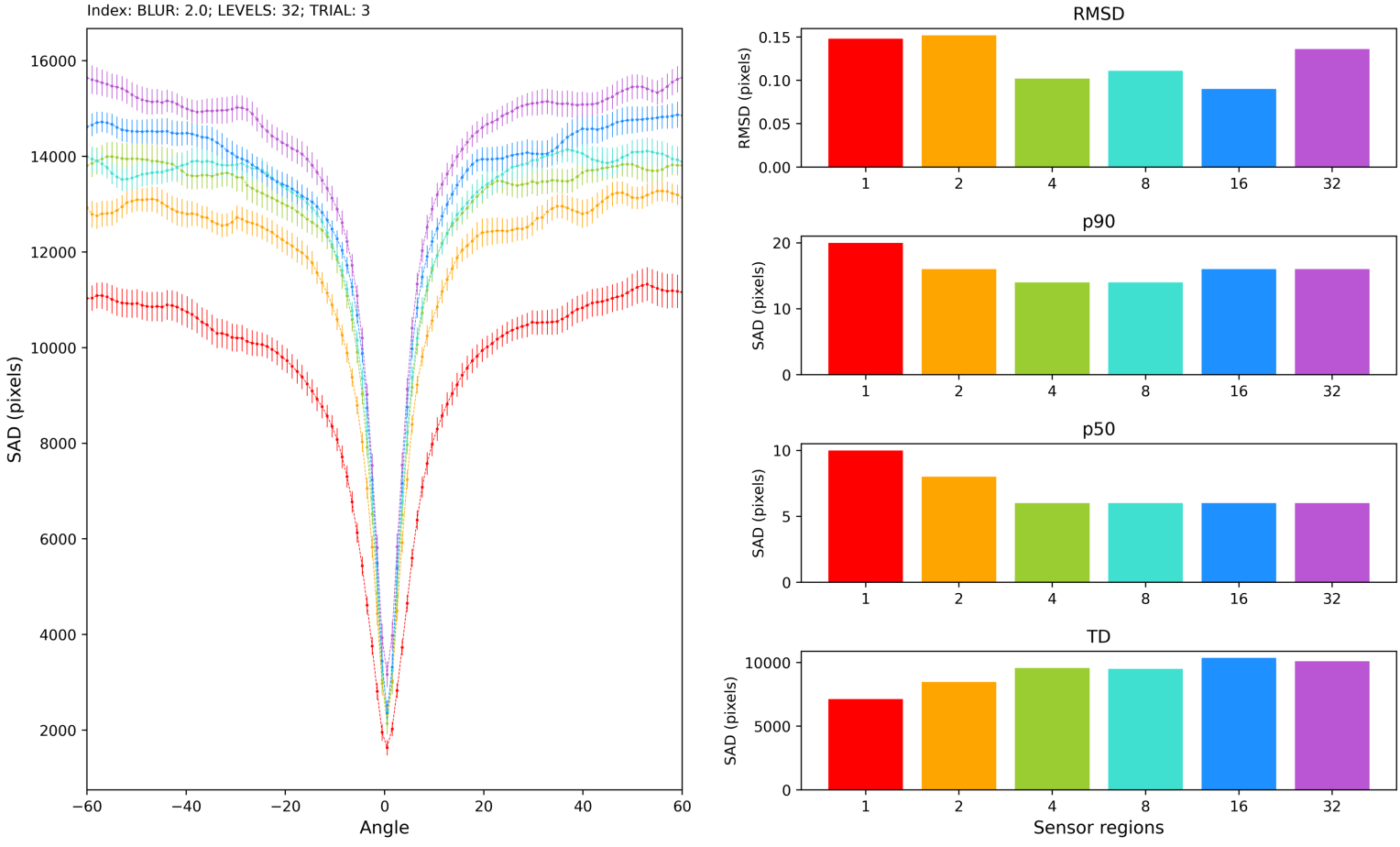
Navigation stats: RMSD error: 51.63; RMSD/dist: 0.129; TD: 9832; p90: 16; p50: 6; complete: 0

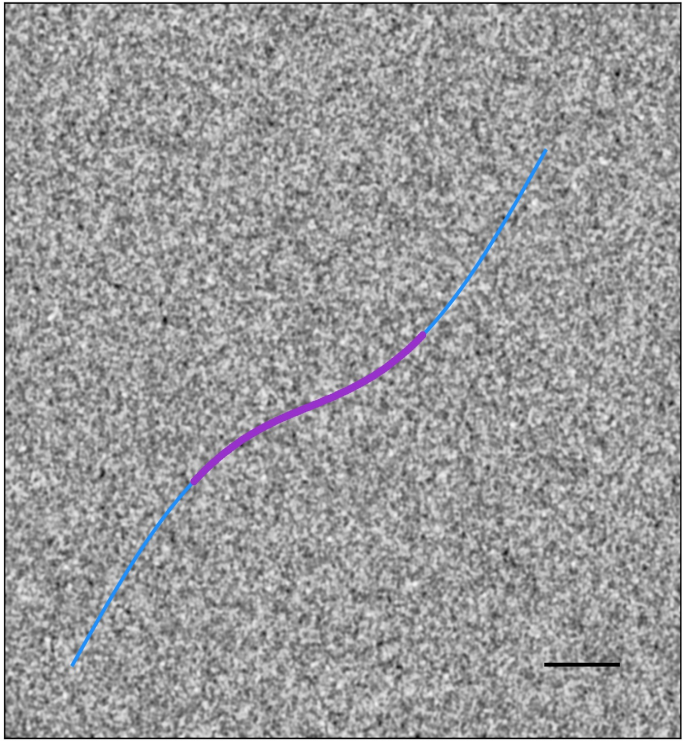


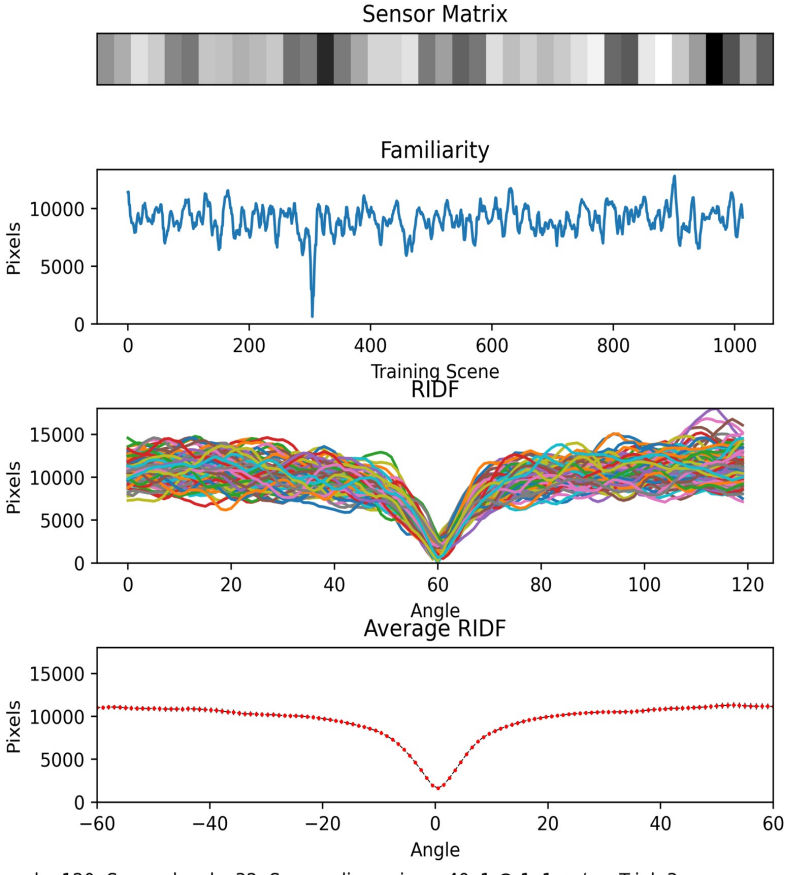


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 49.00; RMSD/dist: 0.123; TD: 10606; p90: 16; p50: 6; complete: 0

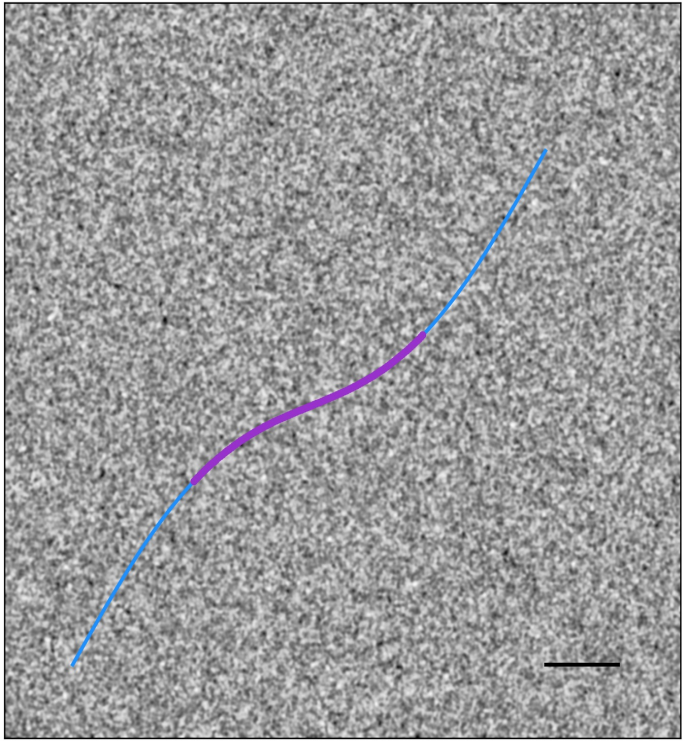

Index: BLUR: 2.0; LEVELS: 32; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

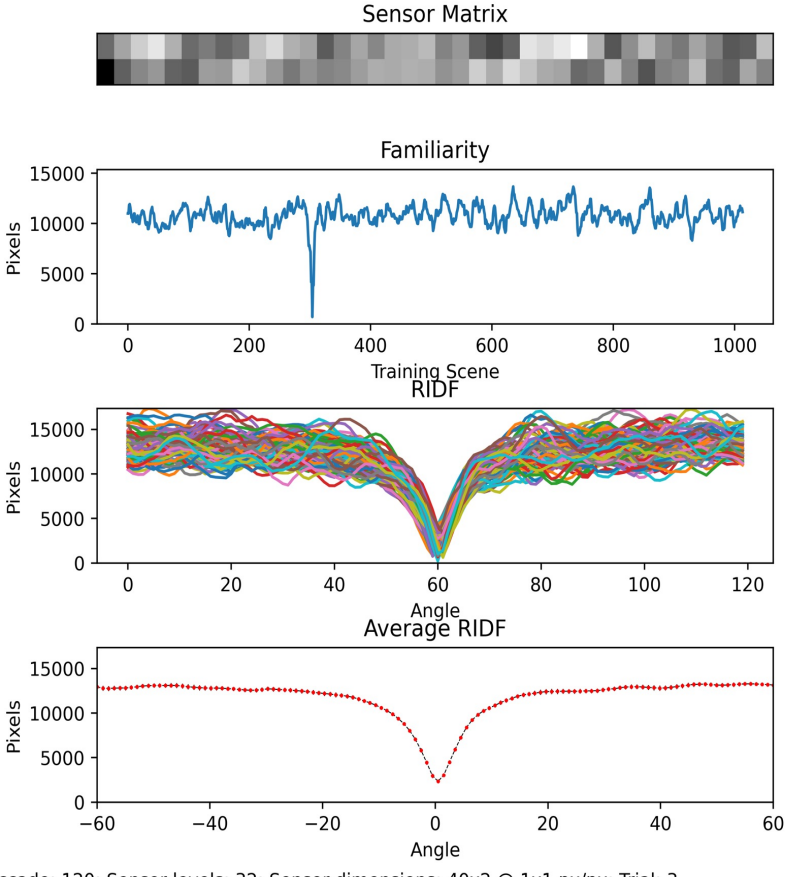




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

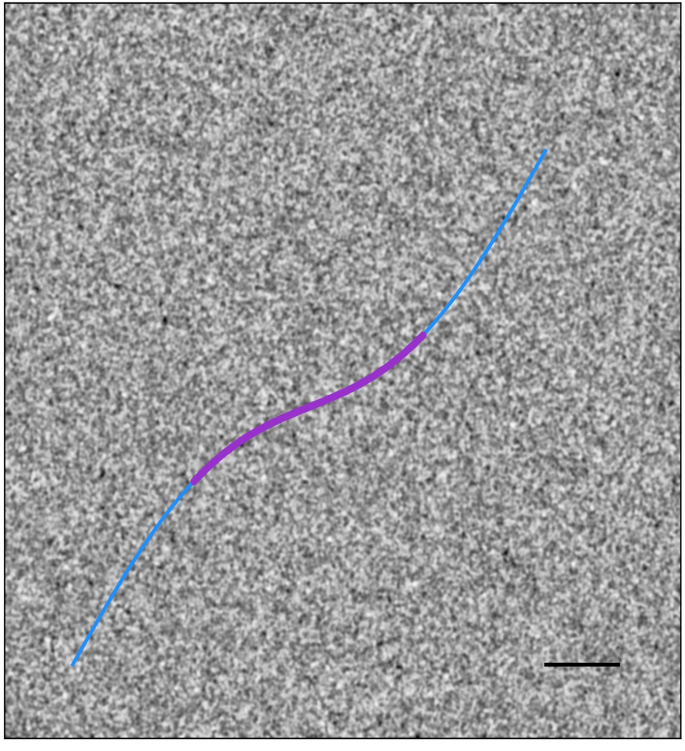
Navigation stats: RMSD error: 59.25; RMSD/dist: 0.148; TD: 7123; p90: 20; p50: 10; complete: 0

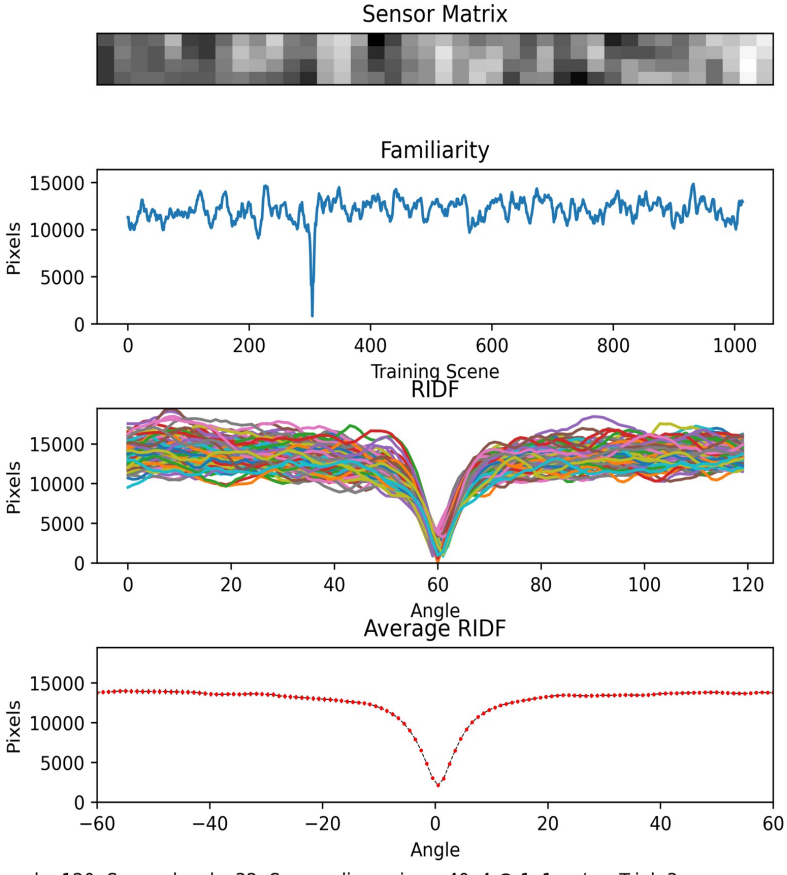




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

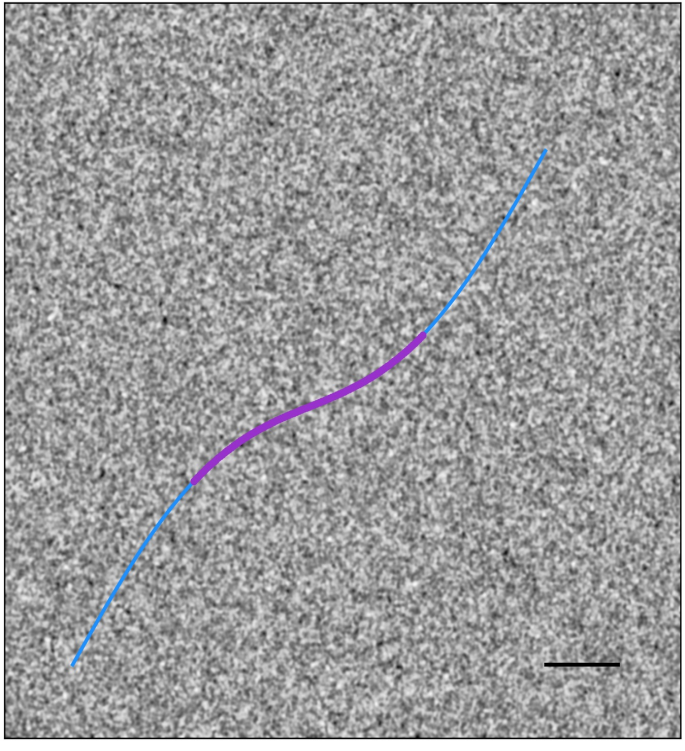
Navigation stats: RMSD error: 60.75; RMSD/dist: 0.152; TD: 8481; p90: 16; p50: 8; complete: 0

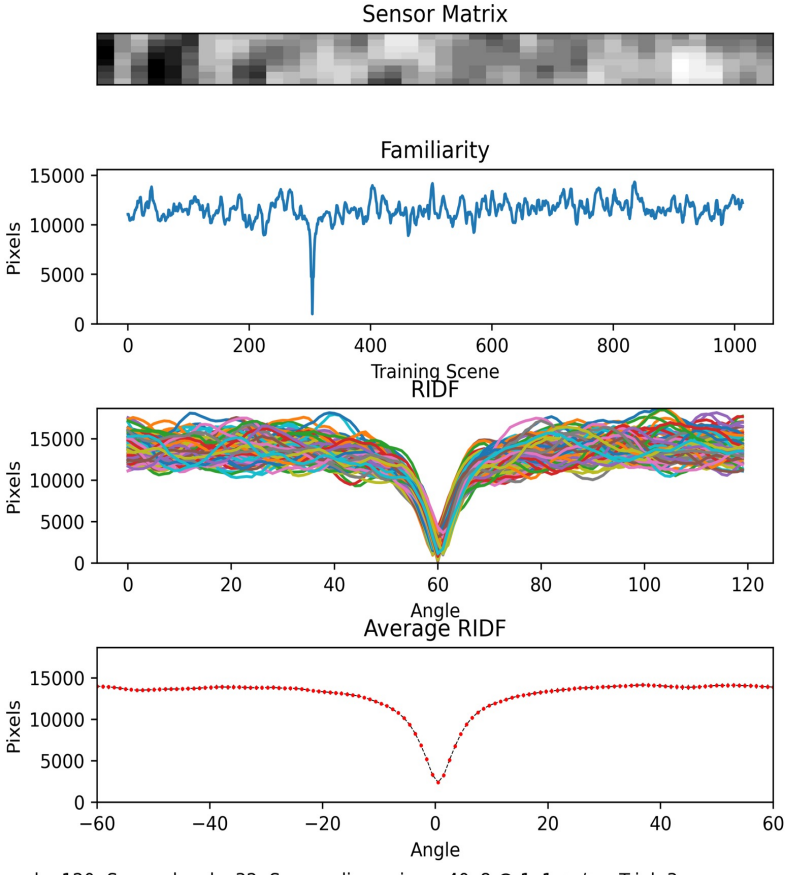




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

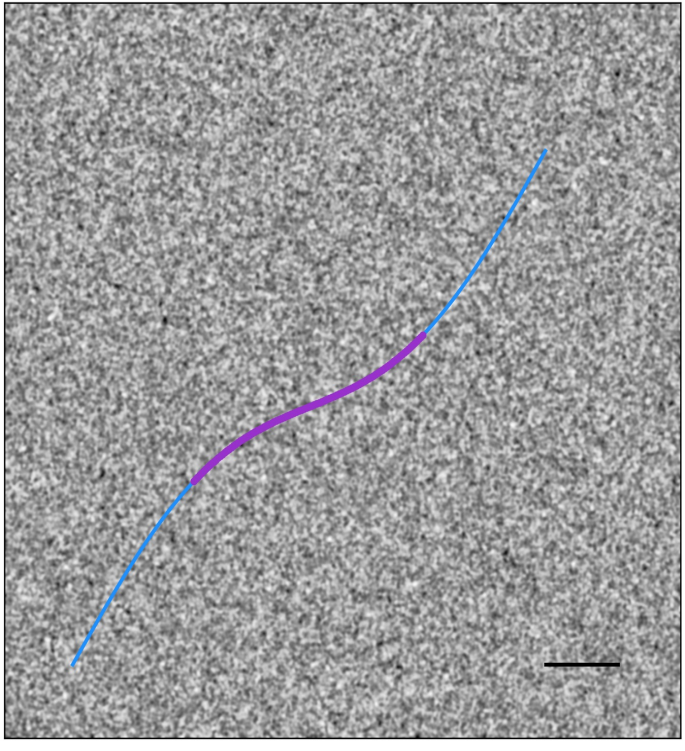
Navigation stats: RMSD error: 40.66; RMSD/dist: 0.102; TD: 9576; p90: 14; p50: 6; complete: 0

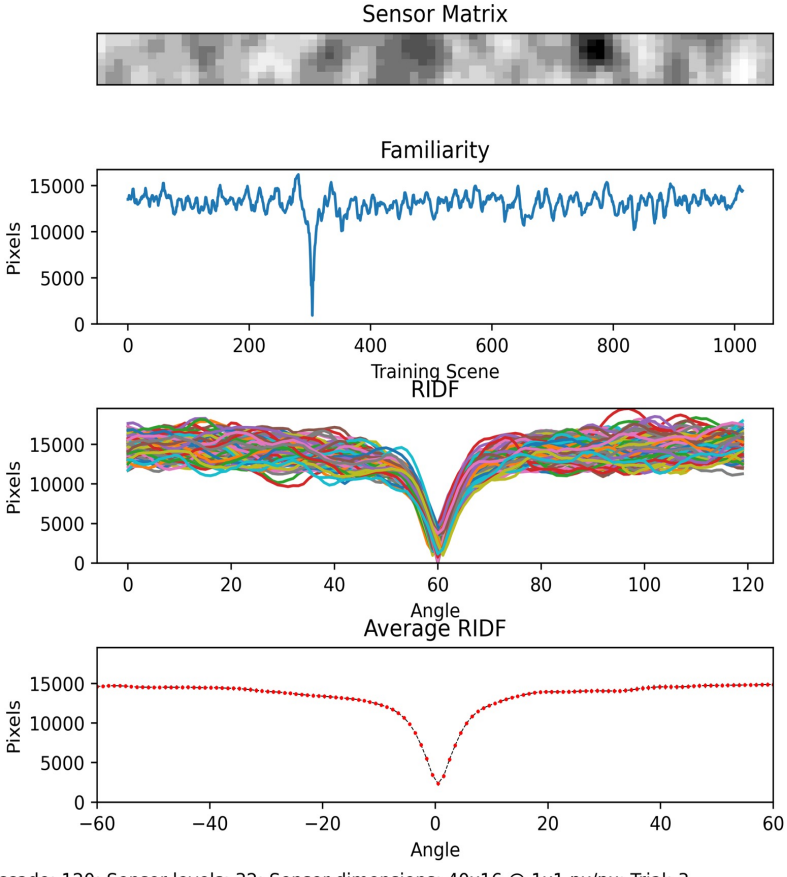




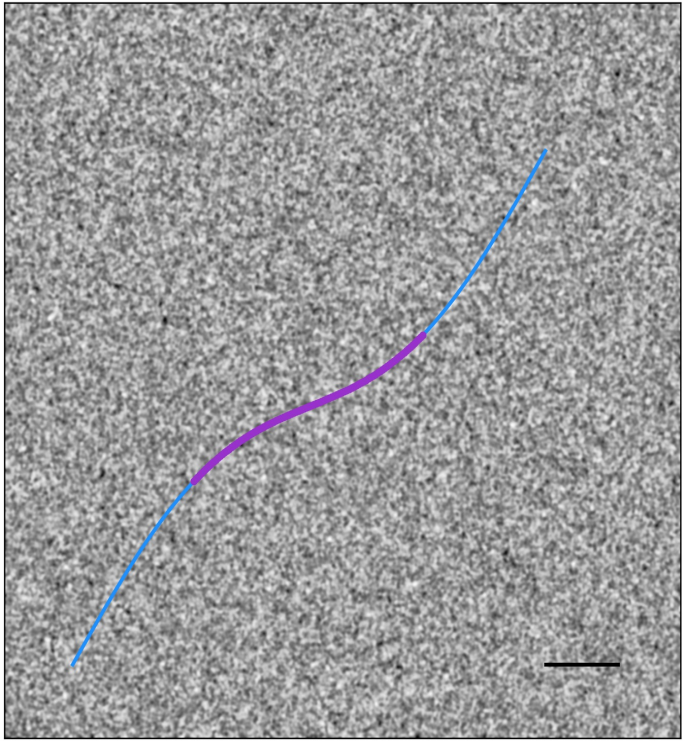
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

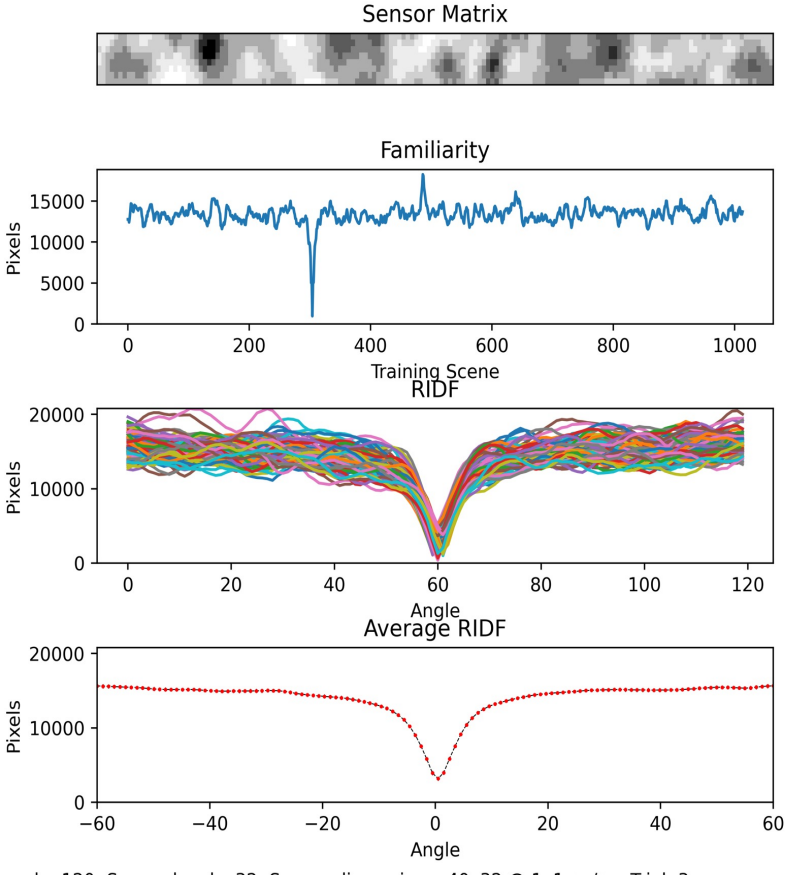
Navigation stats: RMSD error: 44.51; RMSD/dist: 0.111; TD: 9495; p90: 14; p50: 6; complete: 0





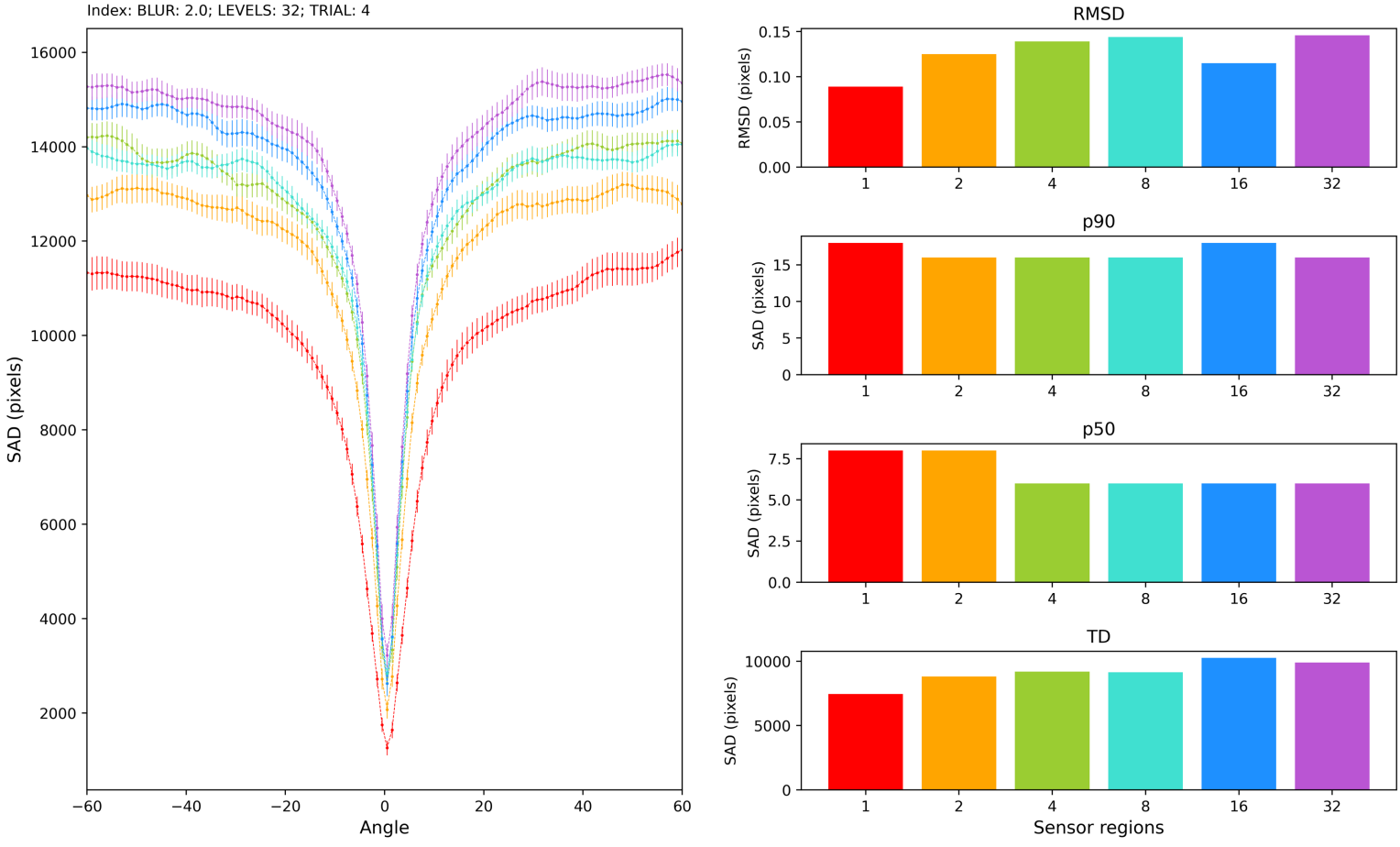
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 36.12; RMSD/dist: 0.090; TD: 10358; p90: 16; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 54.47; RMSD/dist: 0.136; TD: 10108; p90: 16; p50: 6; complete: 0


Index: BLUR: 2.0; LEVELS: 32; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
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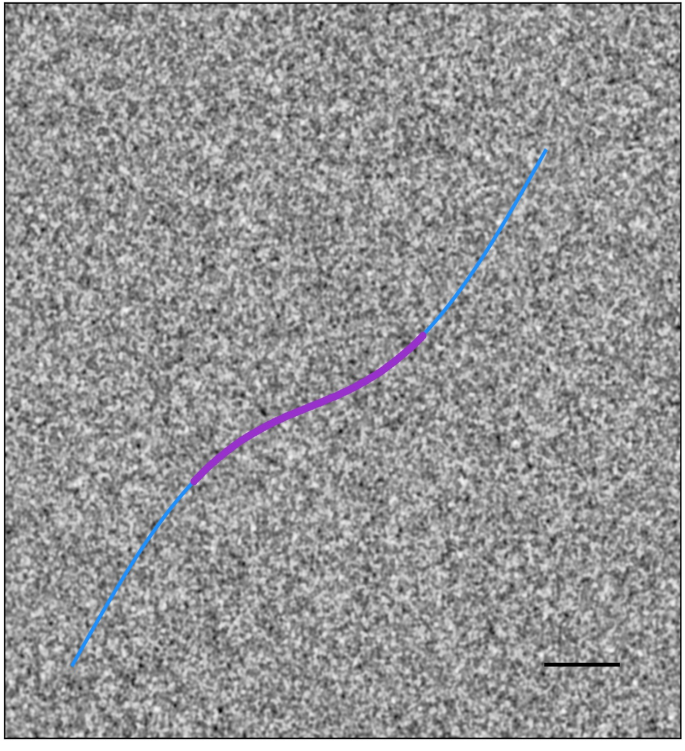
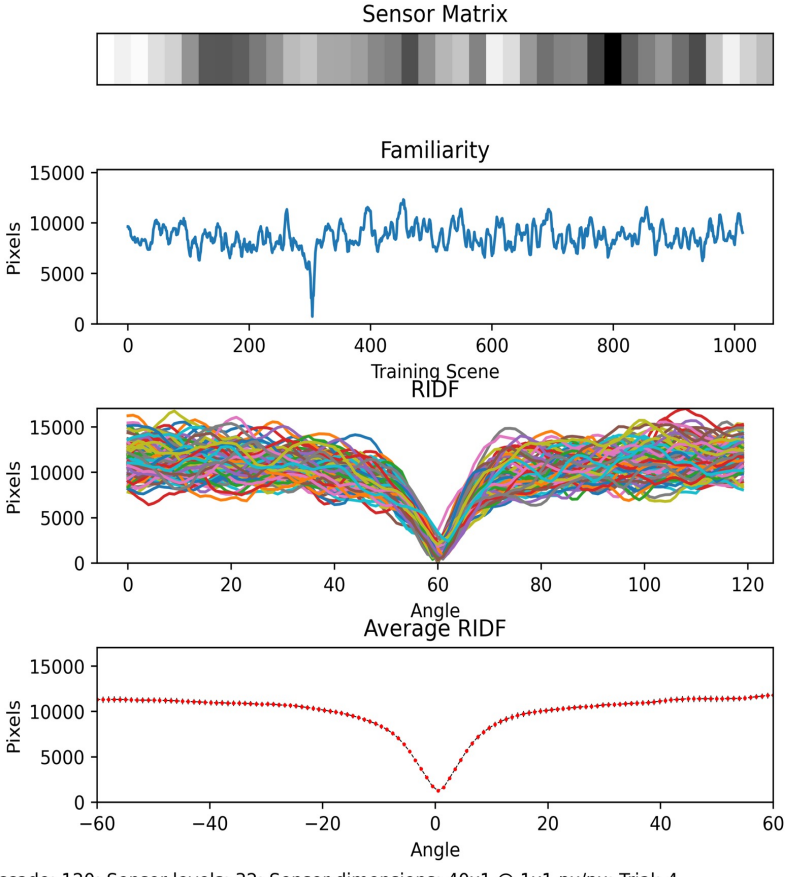
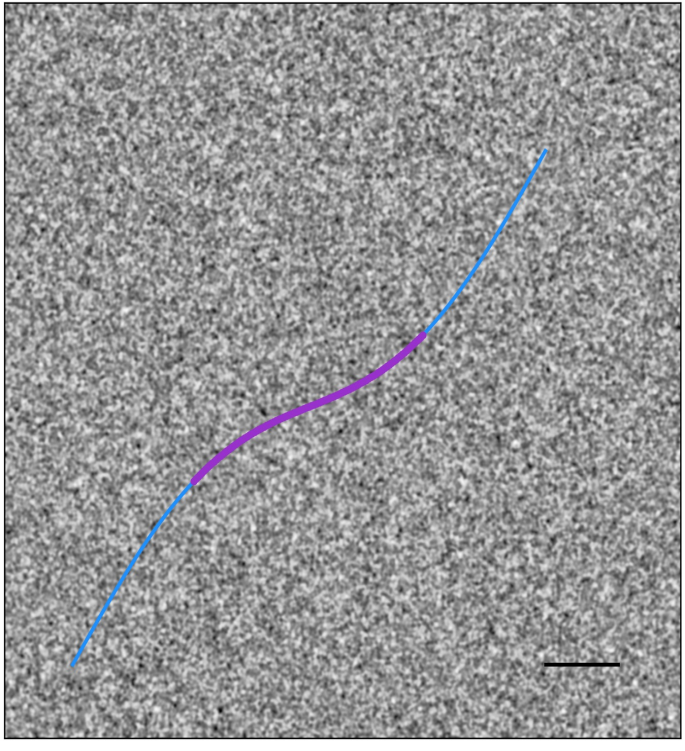
SAD (pixels)
TD
SAD (pixels)
Sensor regions

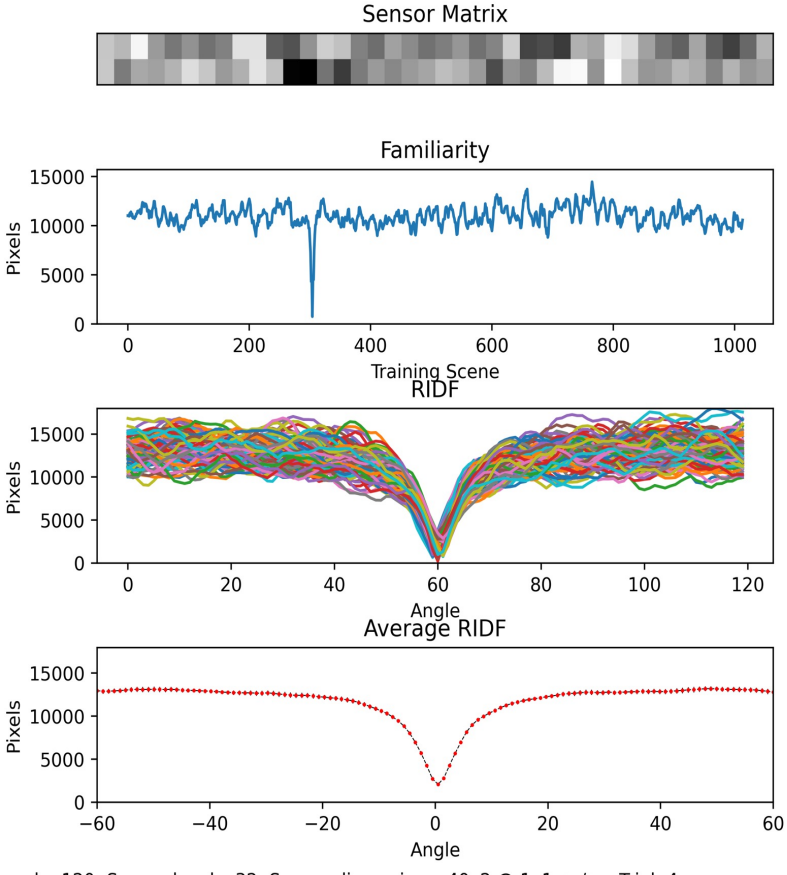




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

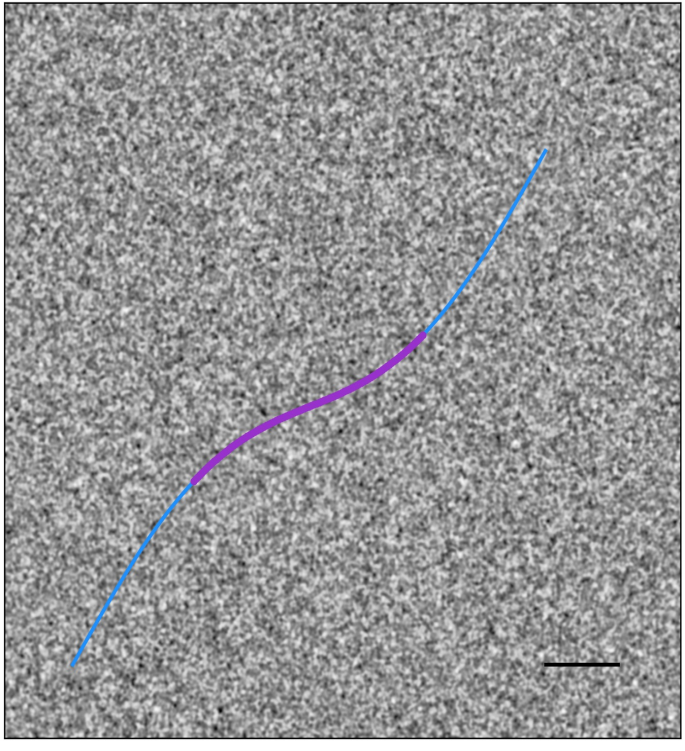
Navigation stats: RMSD error: 35.77; RMSD/dist: 0.089; TD: 7449; p90: 18; p50: 8; complete: 0

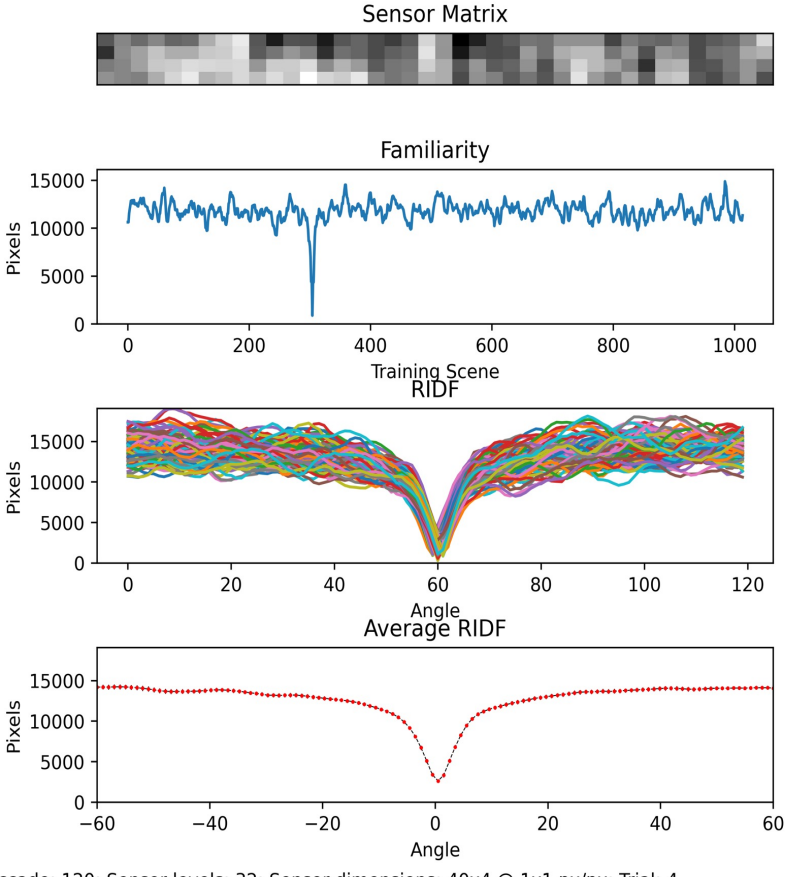




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

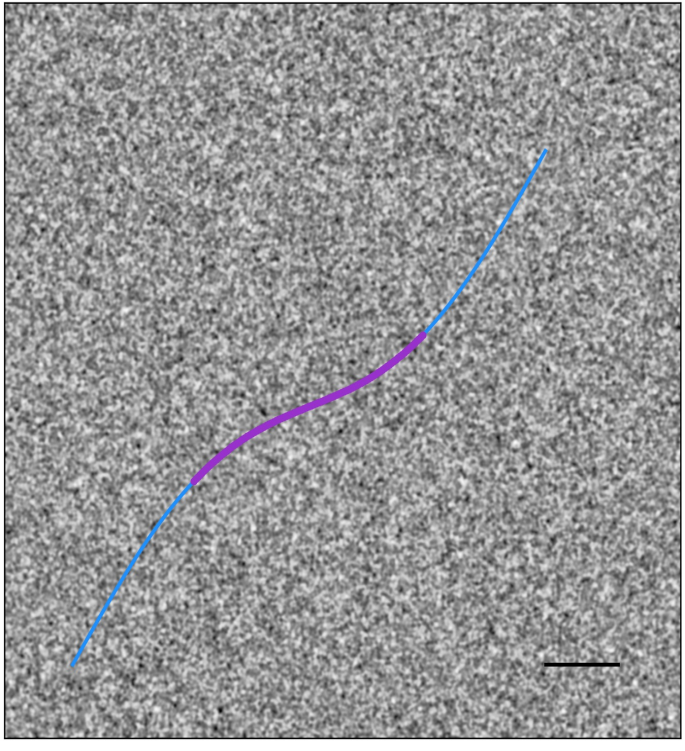
Navigation stats: RMSD error: 50.20; RMSD/dist: 0.125; TD: 8810; p90: 16; p50: 8; complete: 0

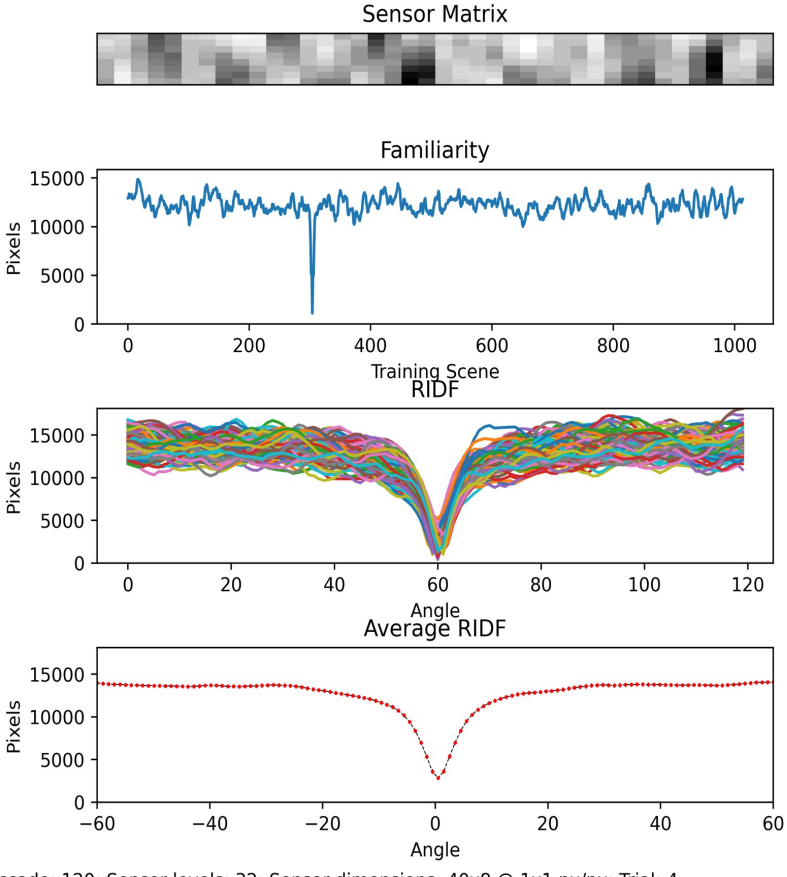




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

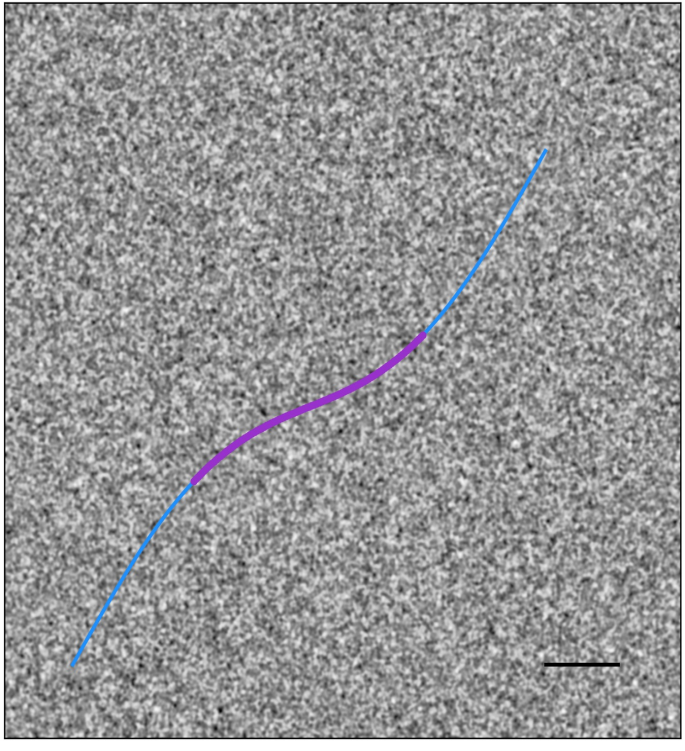
Navigation stats: RMSD error: 55.49; RMSD/dist: 0.139; TD: 9190; p90: 16; p50: 6; complete: 0

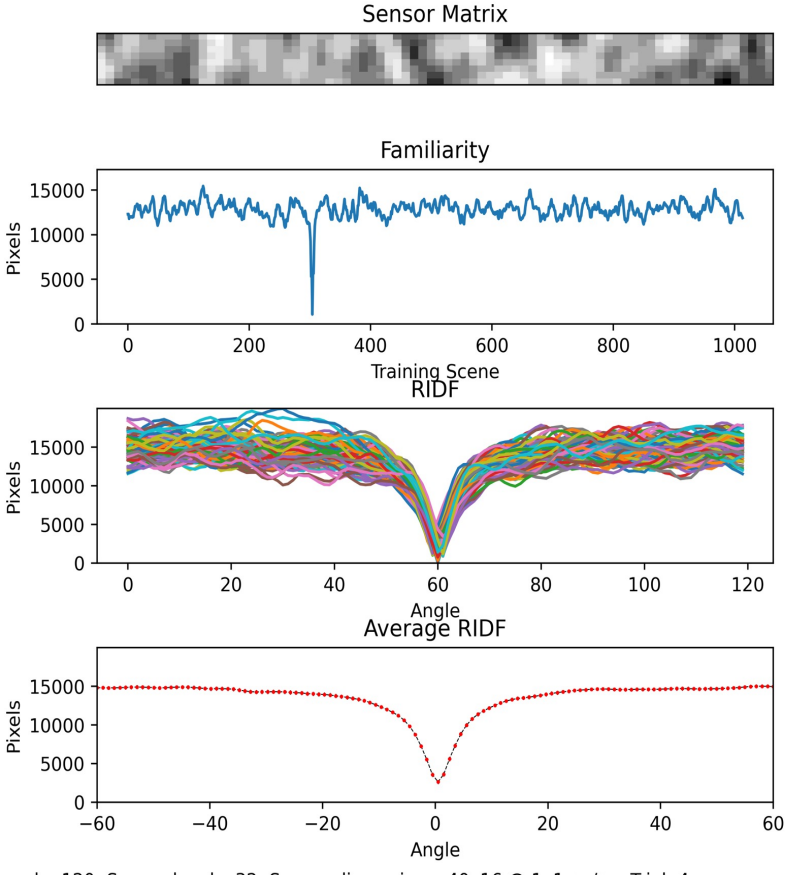




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

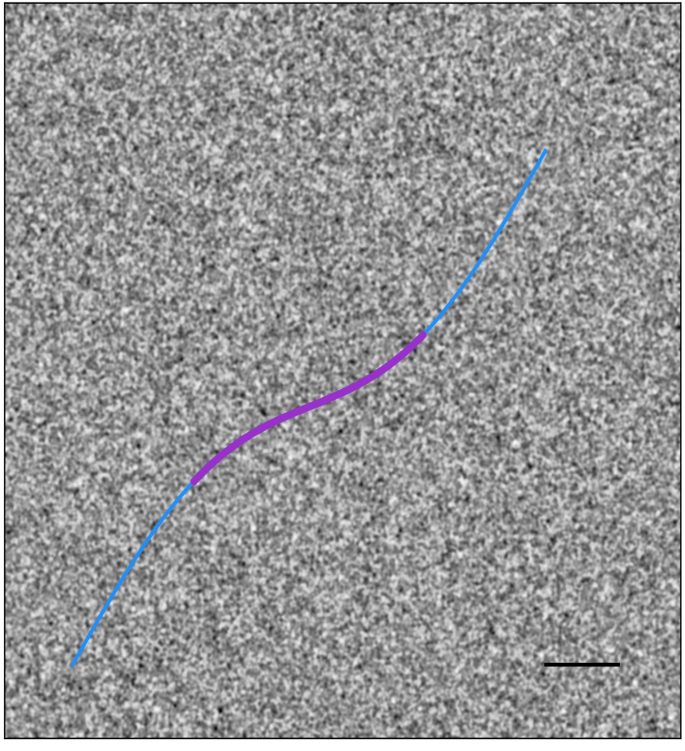
Navigation stats: RMSD error: 57.66; RMSD/dist: 0.144; TD: 9149; p90: 16; p50: 6; complete: 0

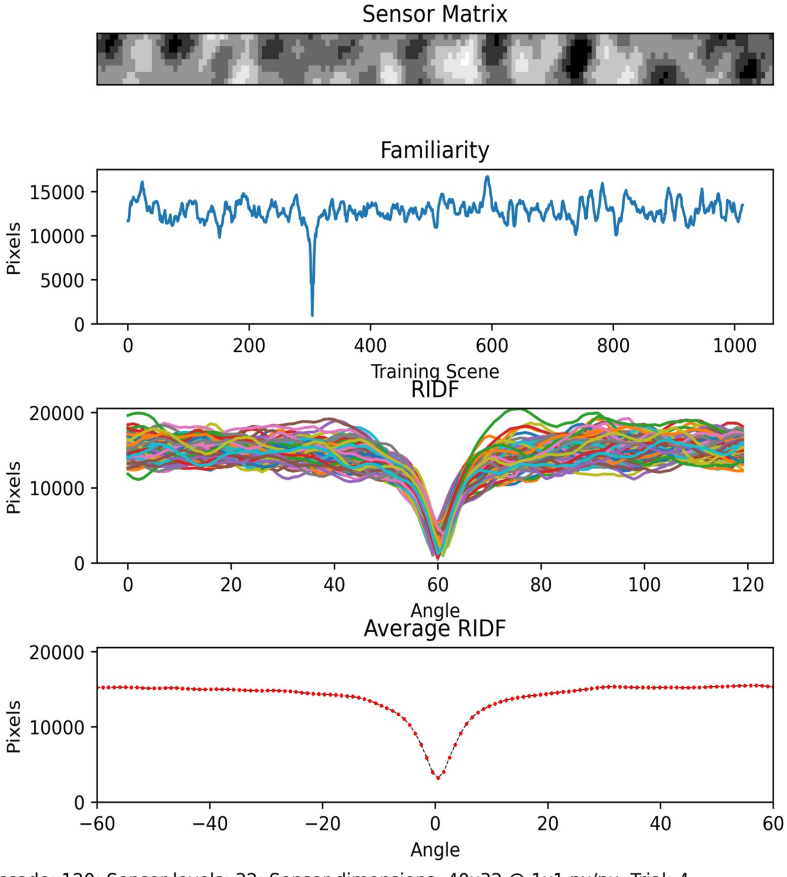




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

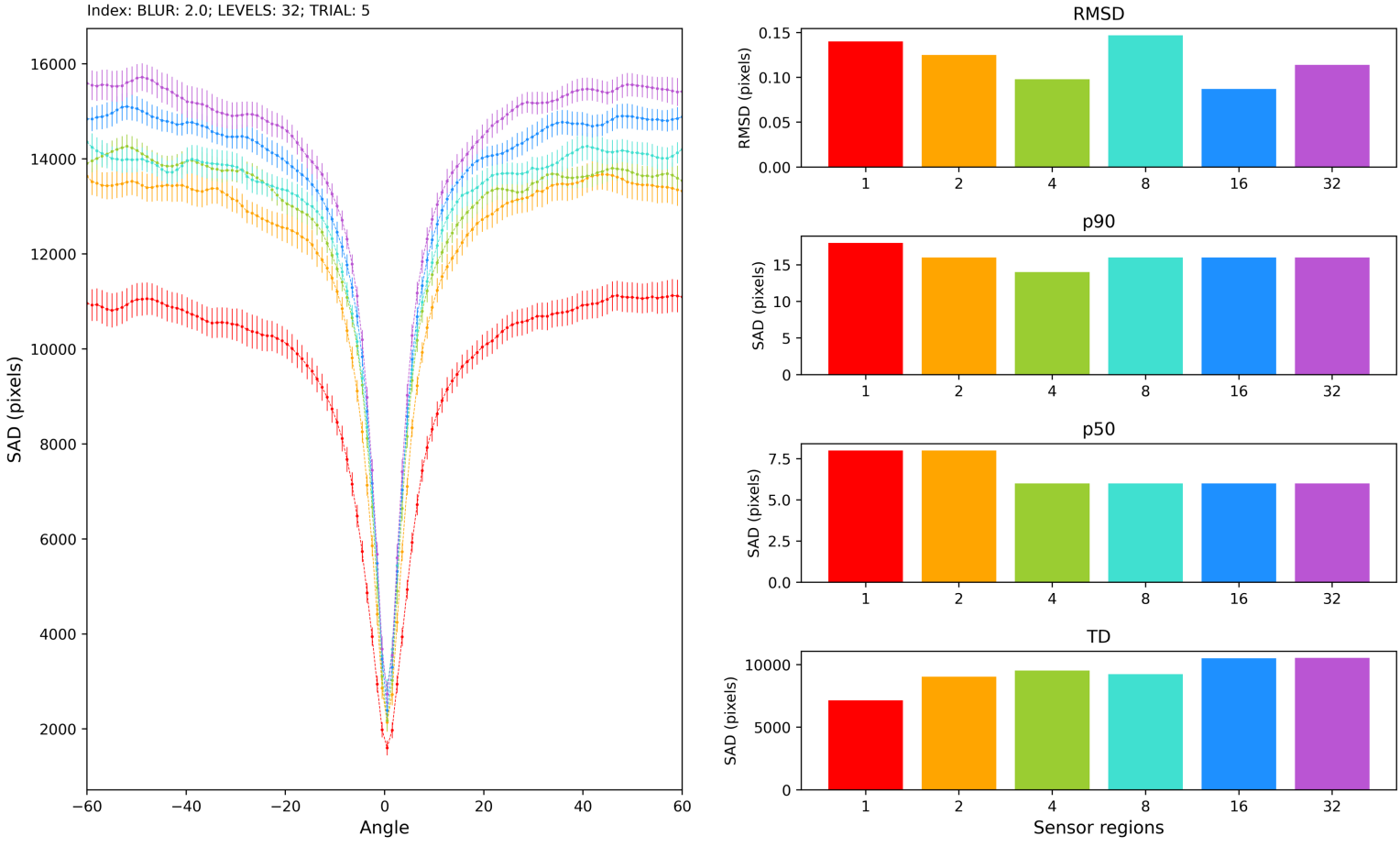
Navigation stats: RMSD error: 45.91; RMSD/dist: 0.115; TD: 10251; p90: 18; p50: 6; complete: 0

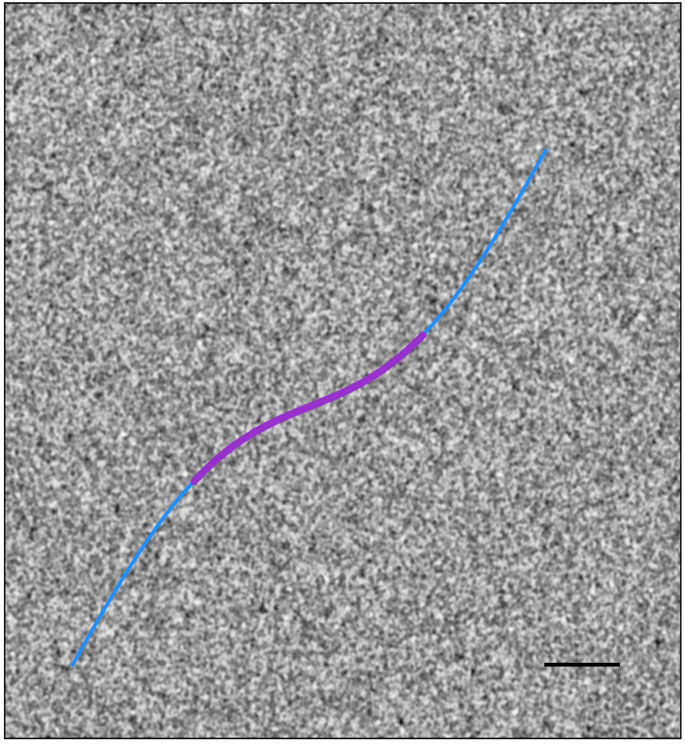


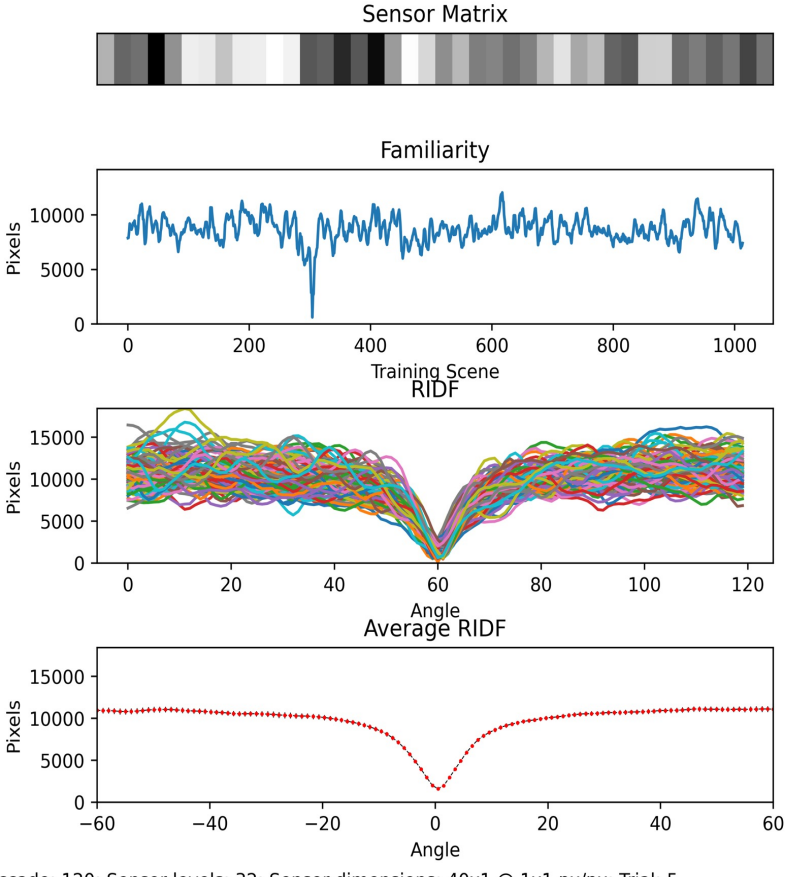


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 58.29; RMSD/dist: 0.146; TD: 9903; p90: 16; p50: 6; complete: 0

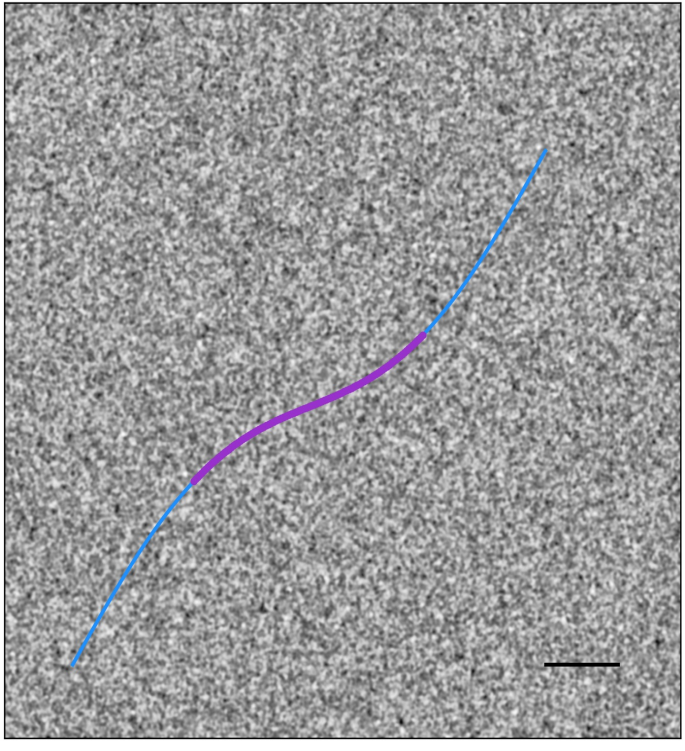

Index: BLUR: 2.0; LEVELS: 32; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

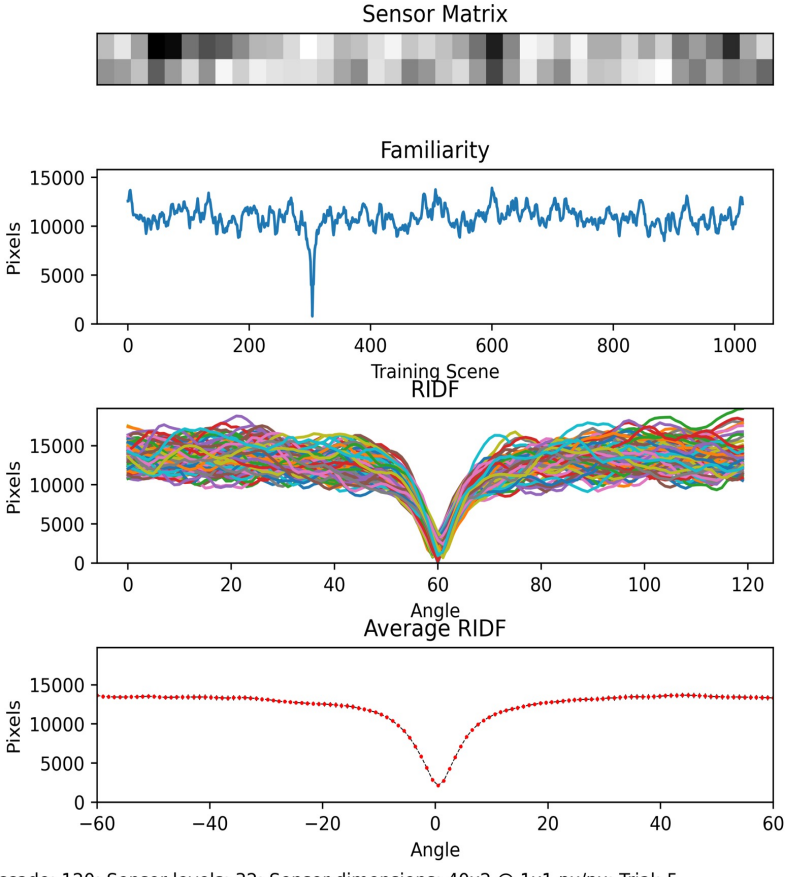




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 56.17; RMSD/dist: 0.140; TD: 7148; p90: 18; p50: 8; complete: 0





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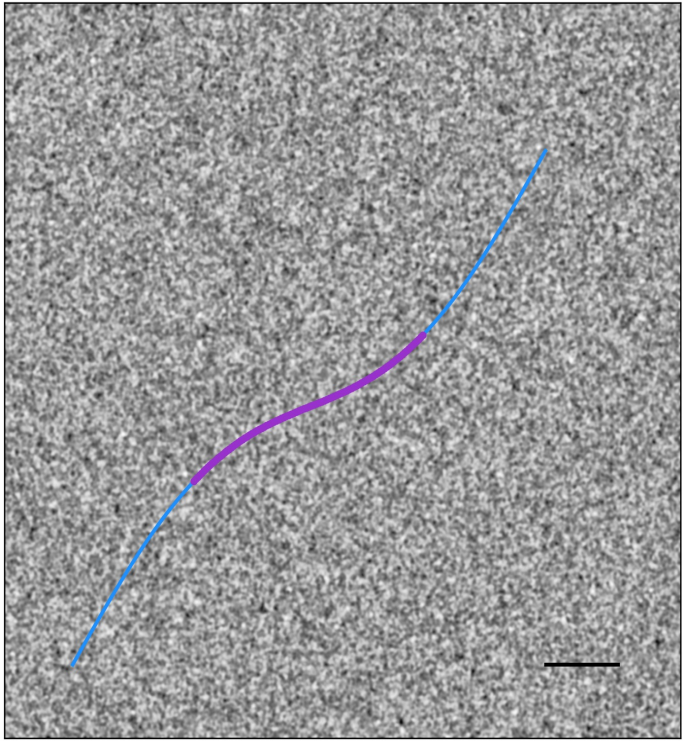
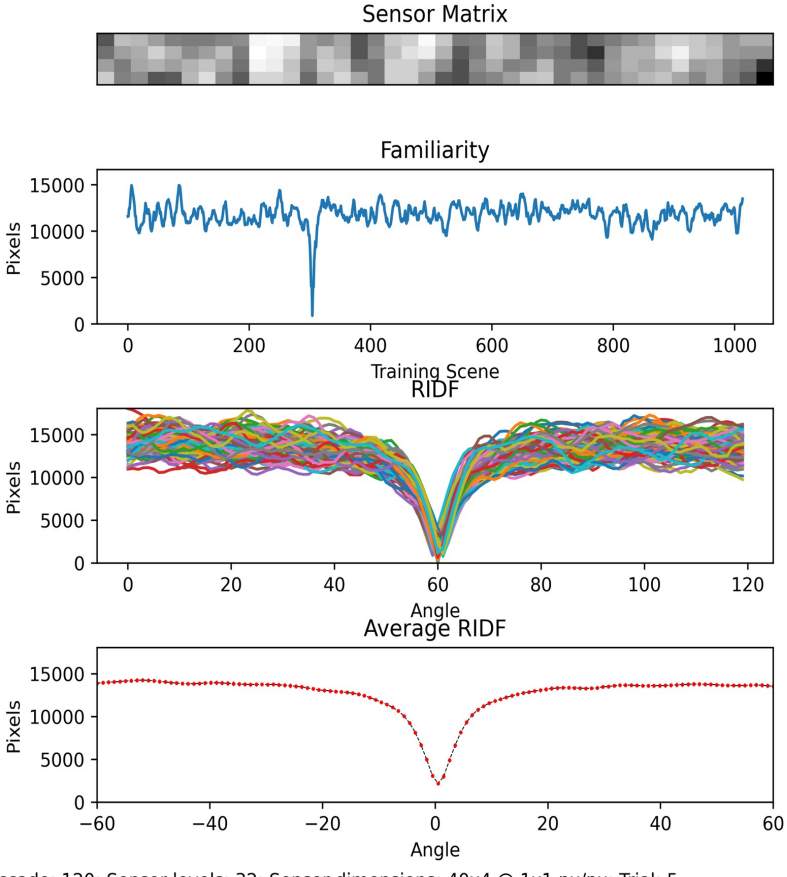
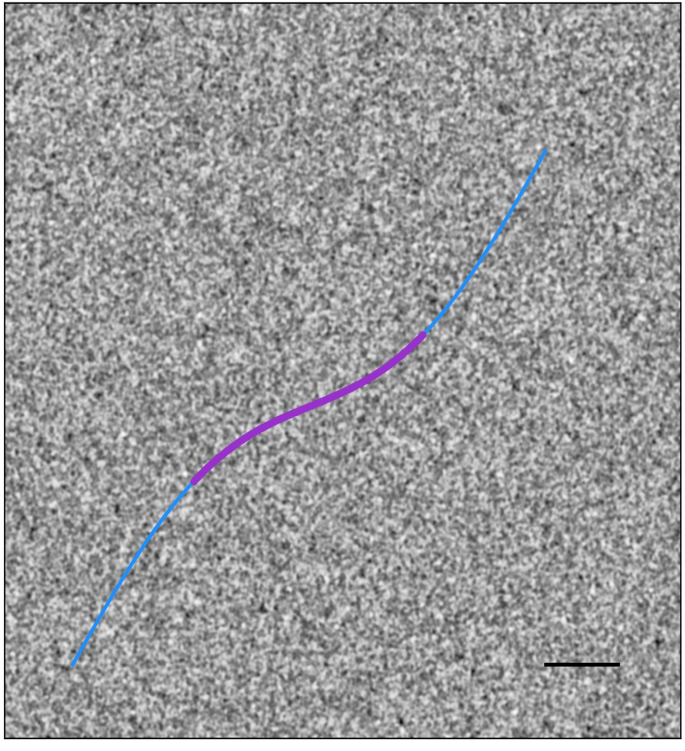
Navigation stats: RMSD error: 50.16; RMSD/dist: 0.125; TD: 9031; p90: 16; p50: 8; complete: 0

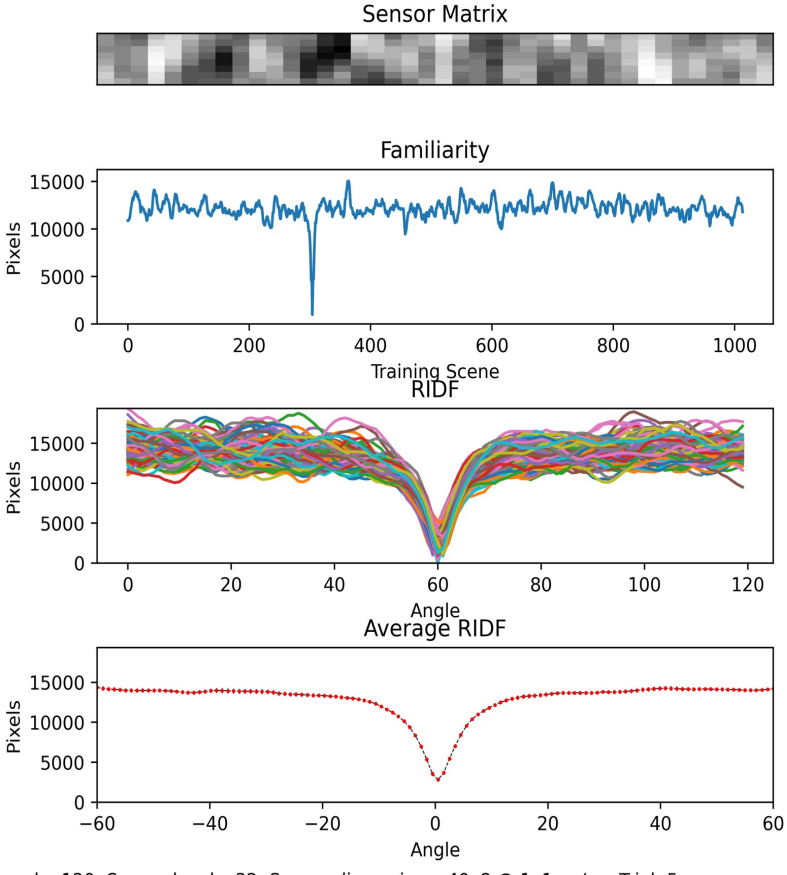




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

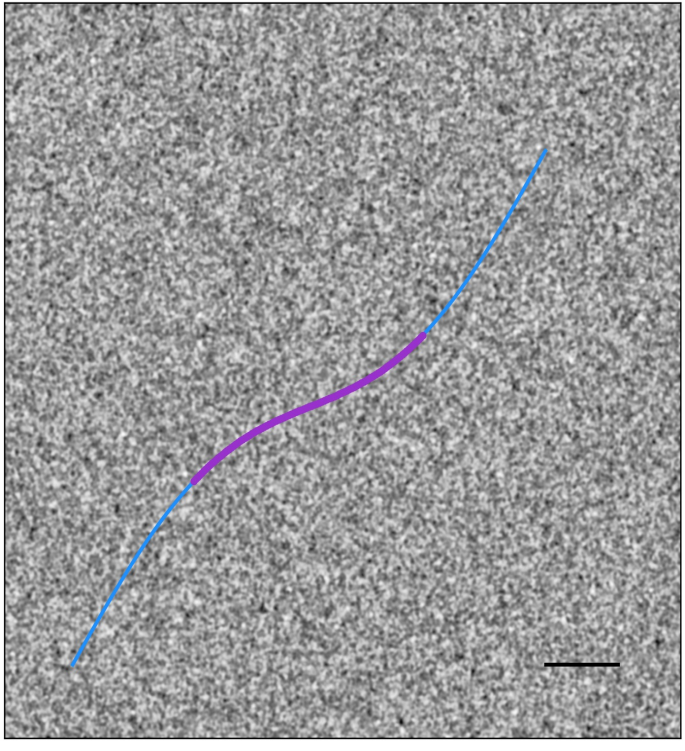
Navigation stats: RMSD error: 39.14; RMSD/dist: 0.098; TD: 9523; p90: 14; p50: 6; complete: 0

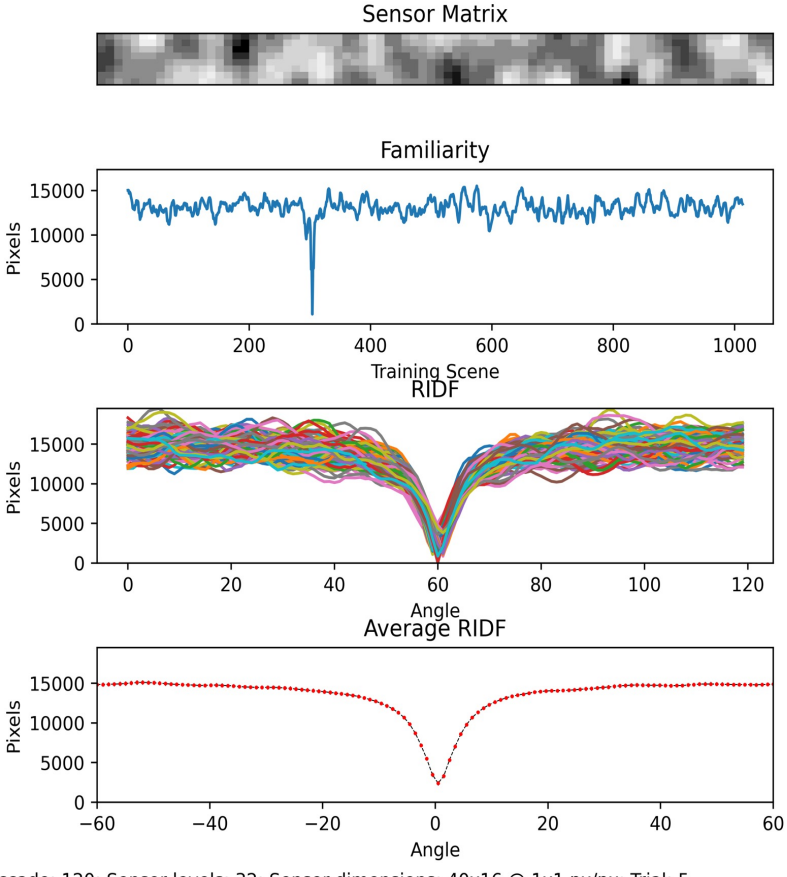




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

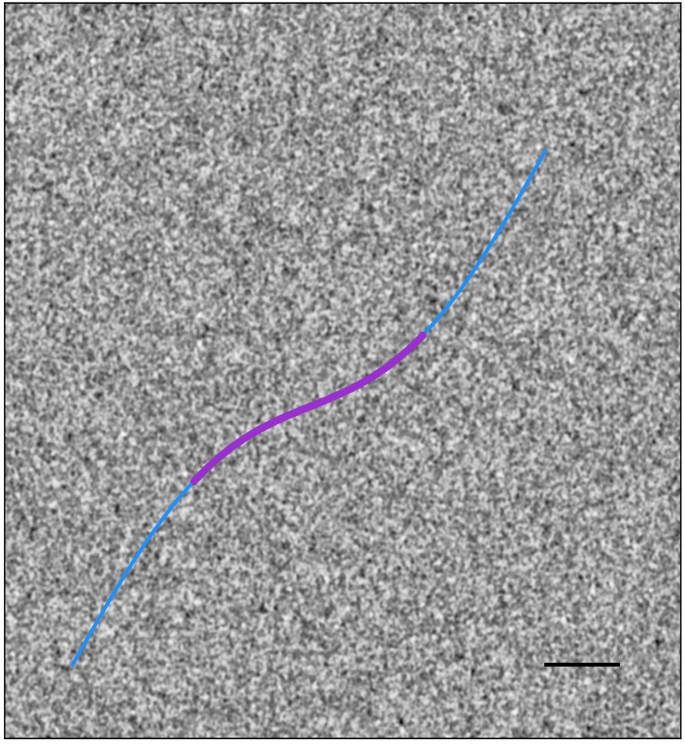
Navigation stats: RMSD error: 58.63; RMSD/dist: 0.147; TD: 9230; p90: 16; p50: 6; complete: 0

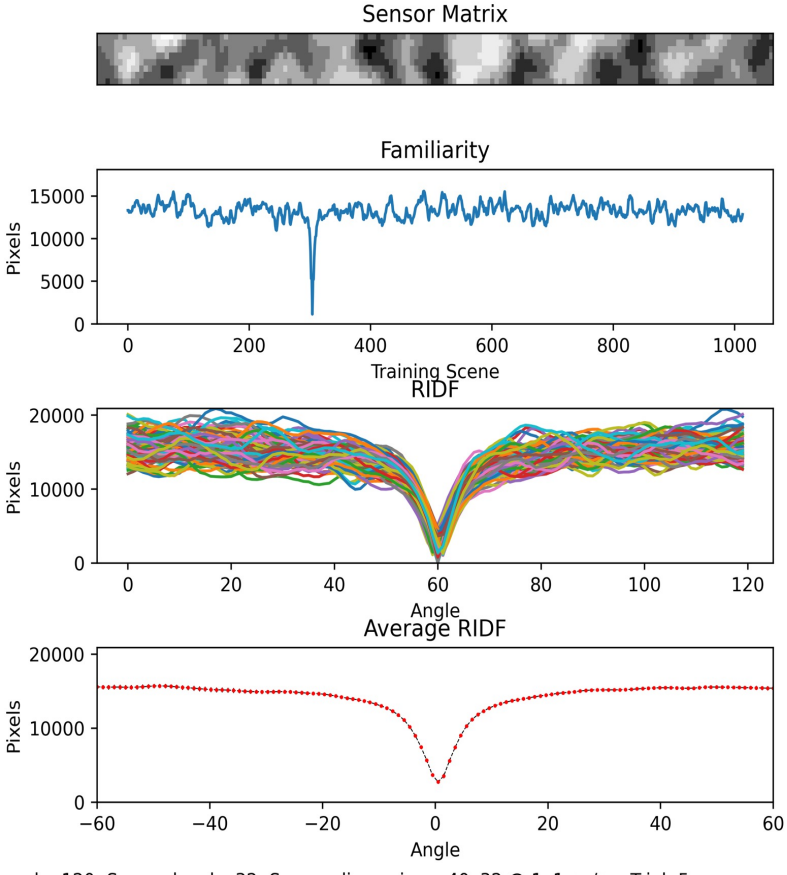




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

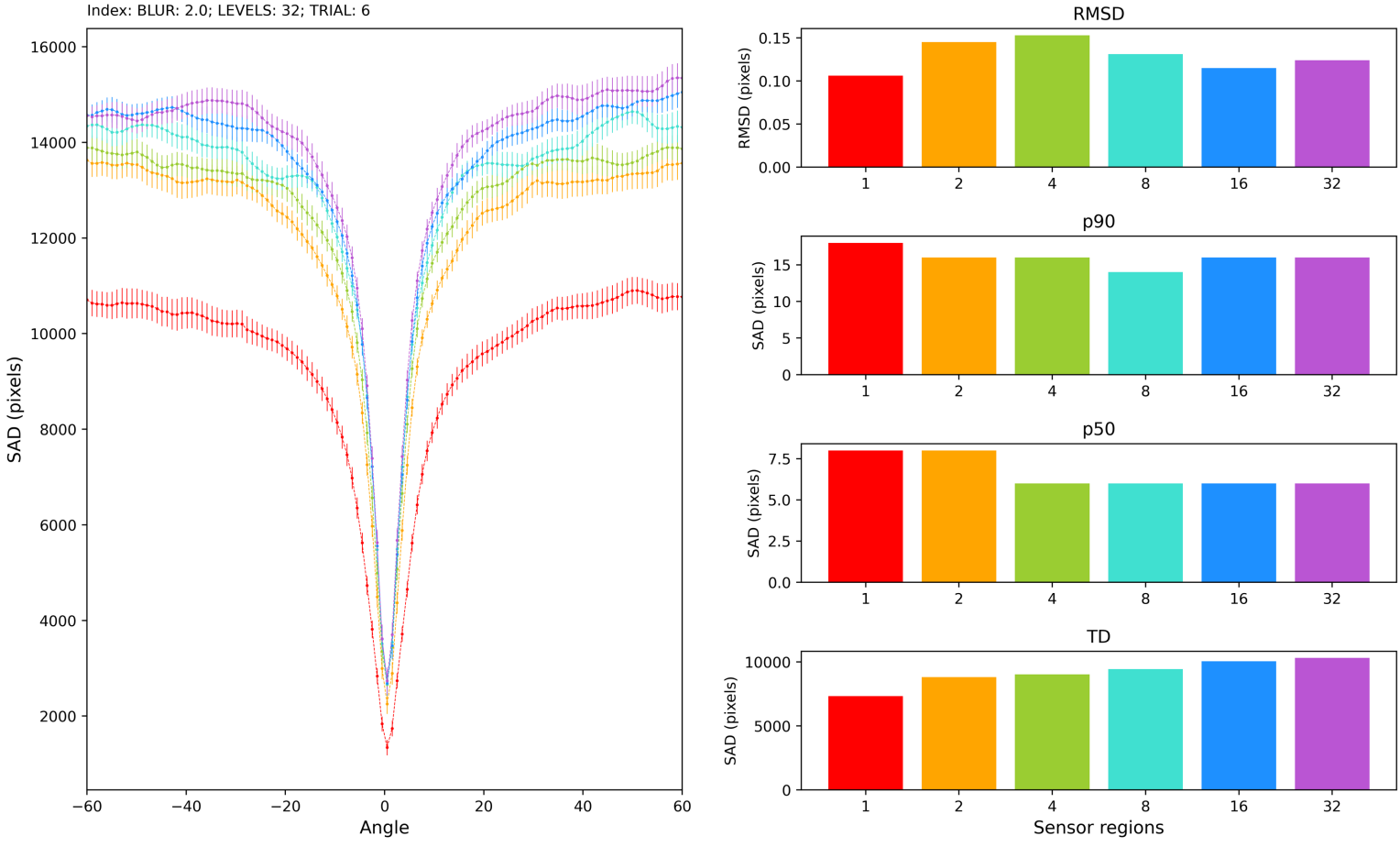
Navigation stats: RMSD error: 34.76; RMSD/dist: 0.087; TD: 10510; p90: 16; p50: 6; complete: 0

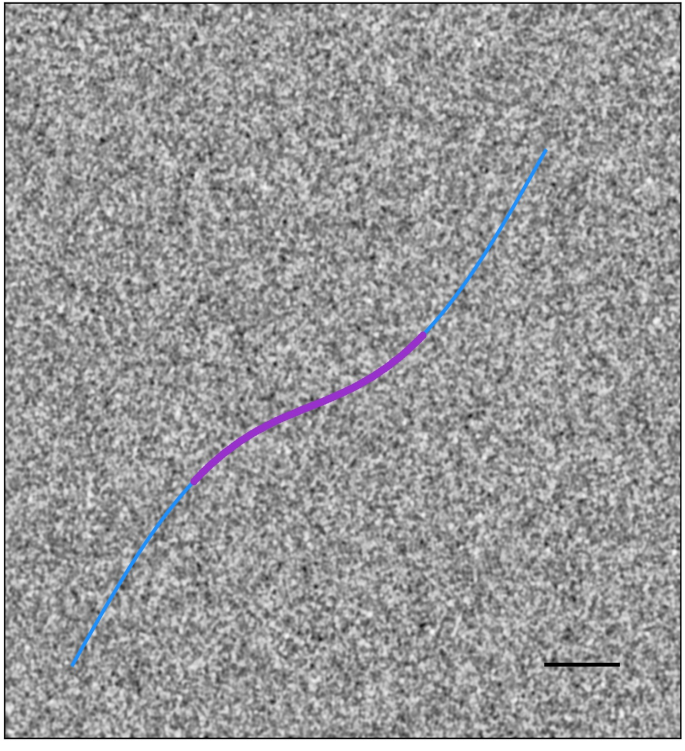


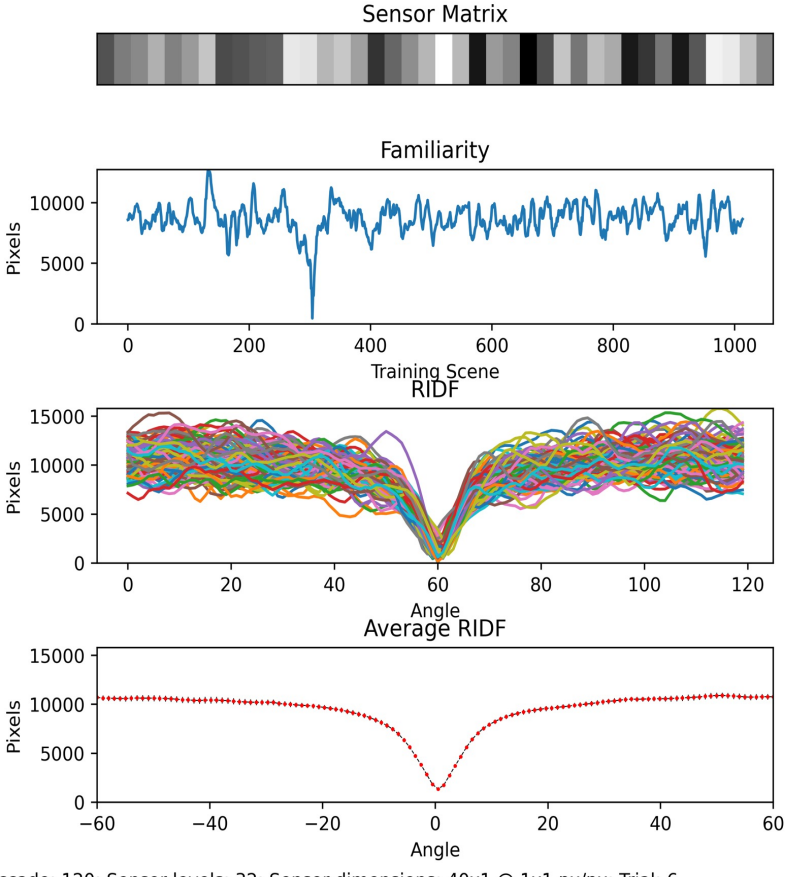


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 45.63; RMSD/dist: 0.114; TD: 10528; p90: 16; p50: 6; complete: 0

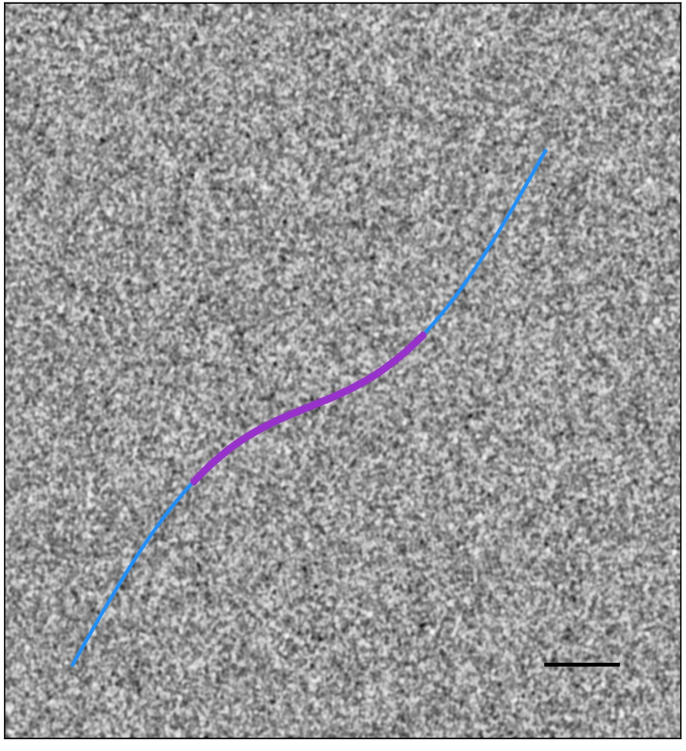

Index: BLUR: 2.0; LEVELS: 32; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

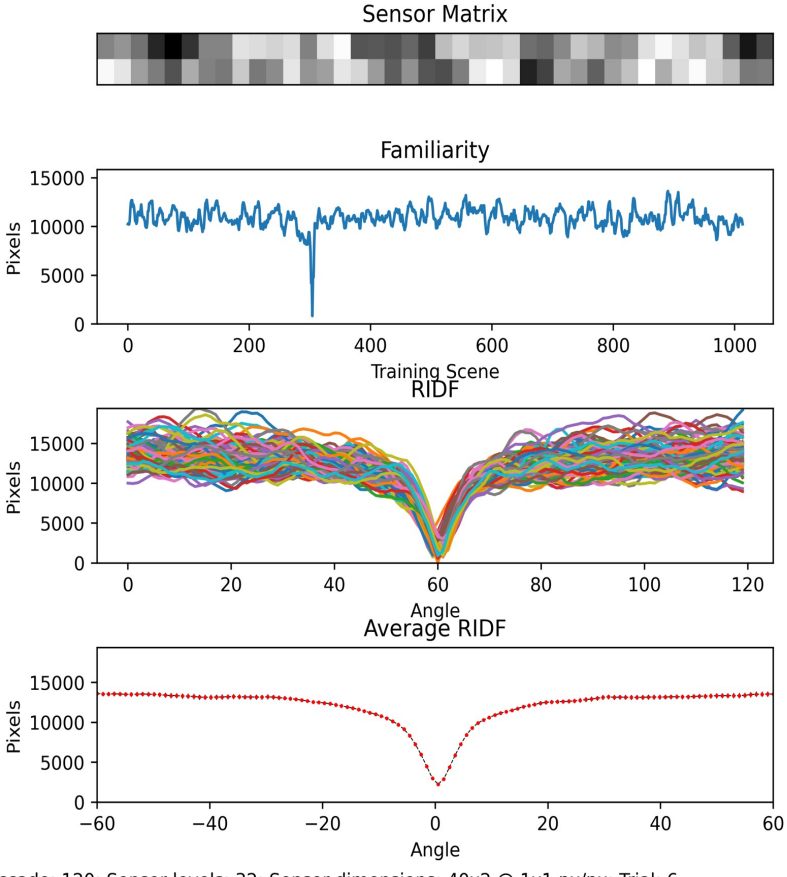




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

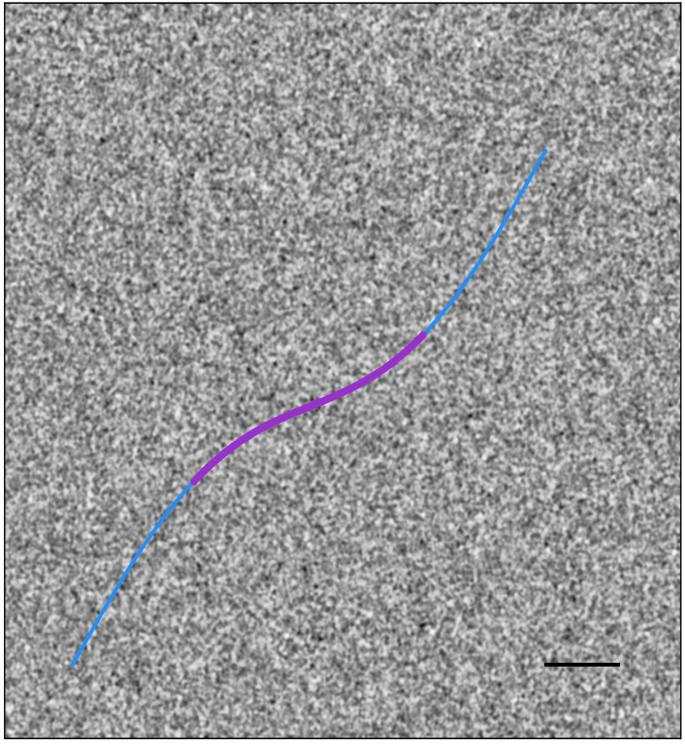
Navigation stats: RMSD error: 42.54; RMSD/dist: 0.106; TD: 7328; p90: 18; p50: 8; complete: 0

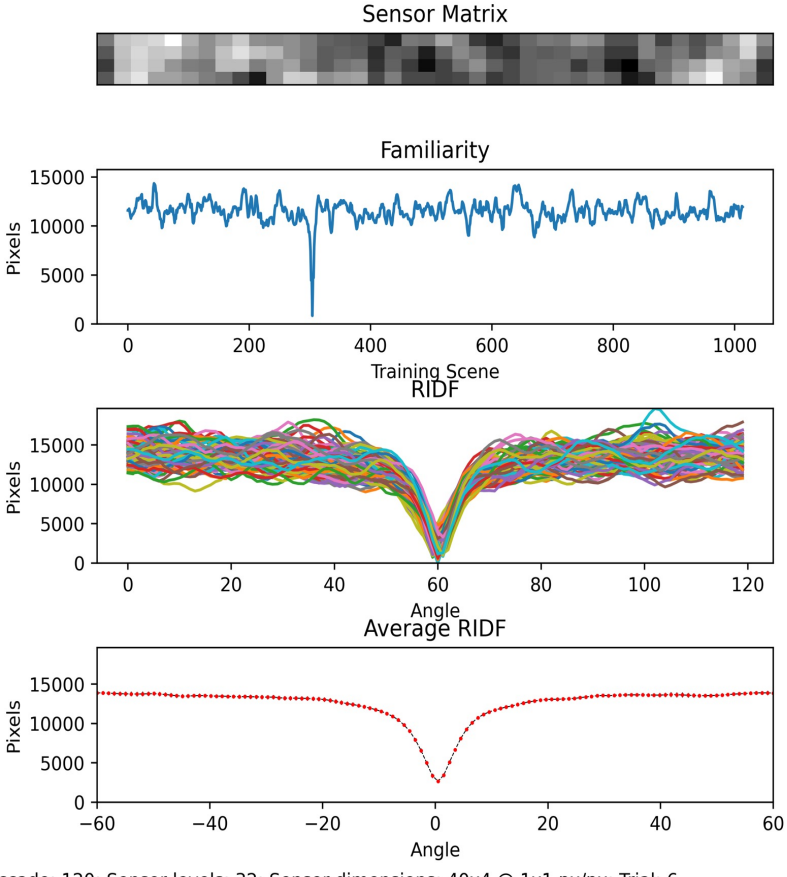




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

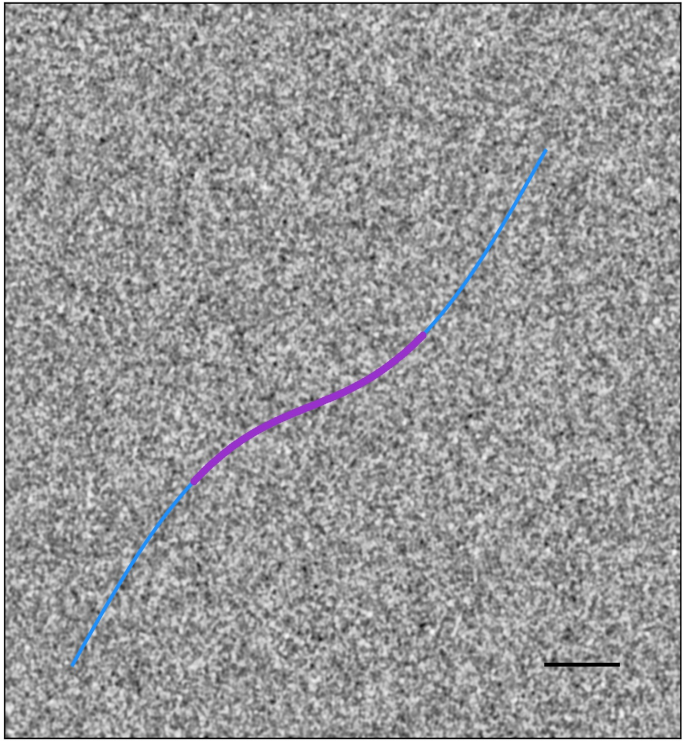
Navigation stats: RMSD error: 58.04; RMSD/dist: 0.145; TD: 8807; p90: 16; p50: 8; complete: 0

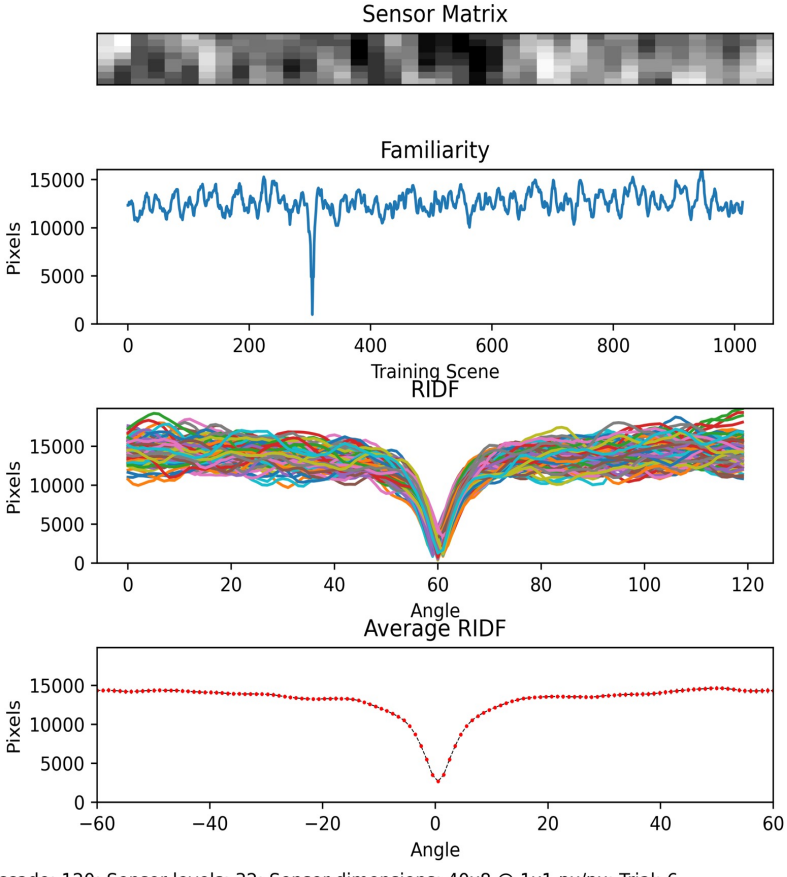




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

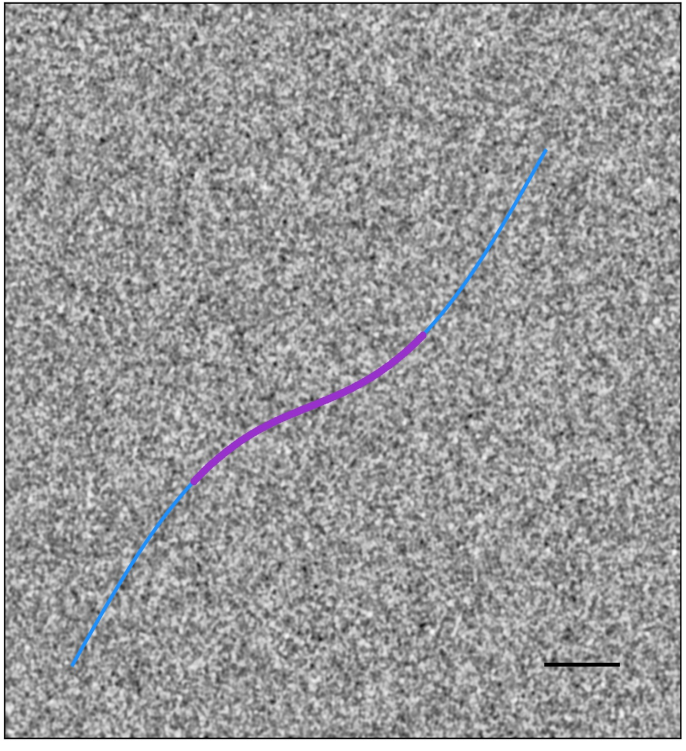
Navigation stats: RMSD error: 61.03; RMSD/dist: 0.153; TD: 9031; p90: 16; p50: 6; complete: 0

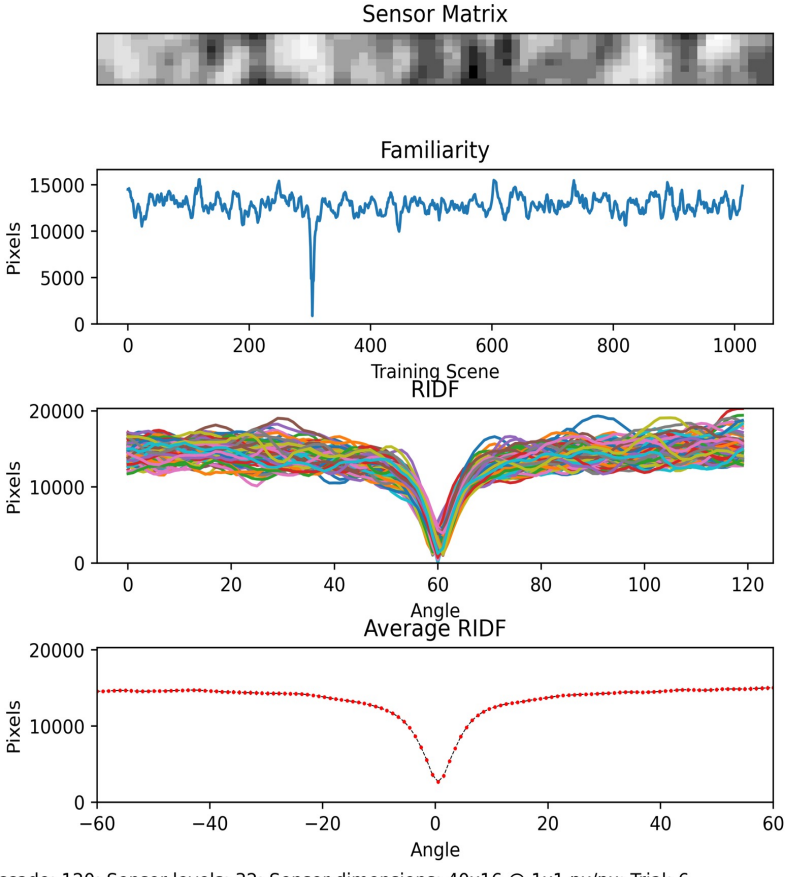




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

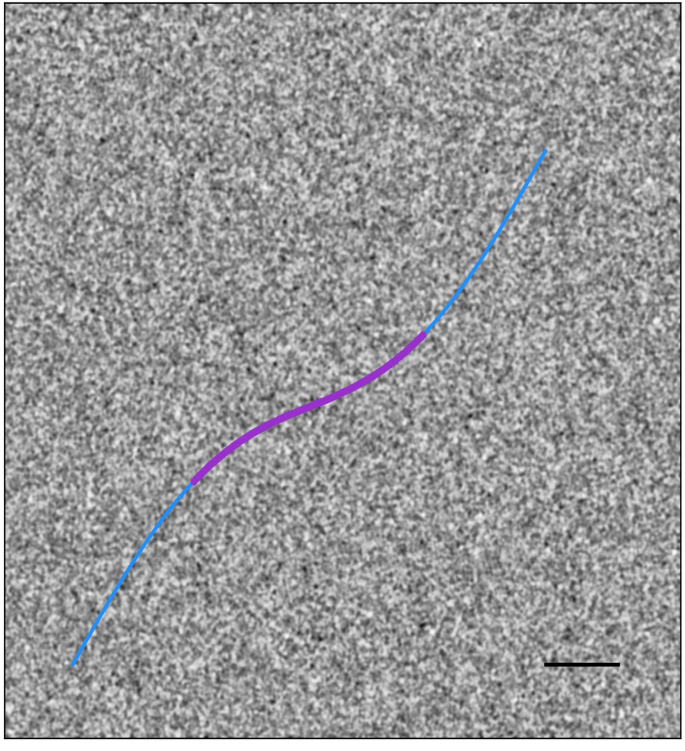
Navigation stats: RMSD error: 52.43; RMSD/dist: 0.131; TD: 9434; p90: 14; p50: 6; complete: 0

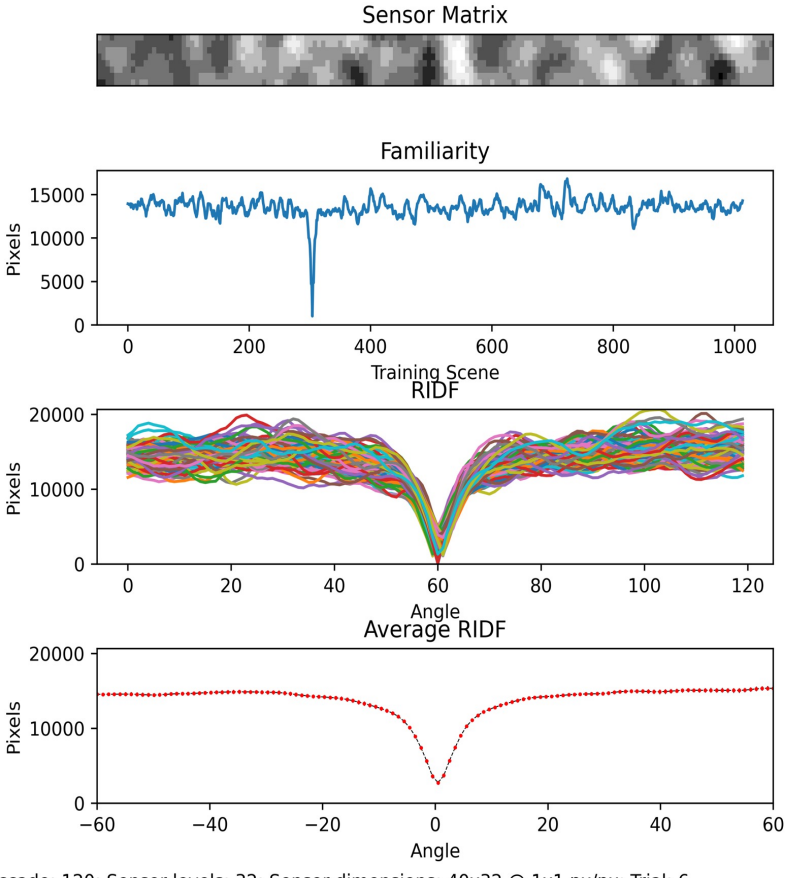




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

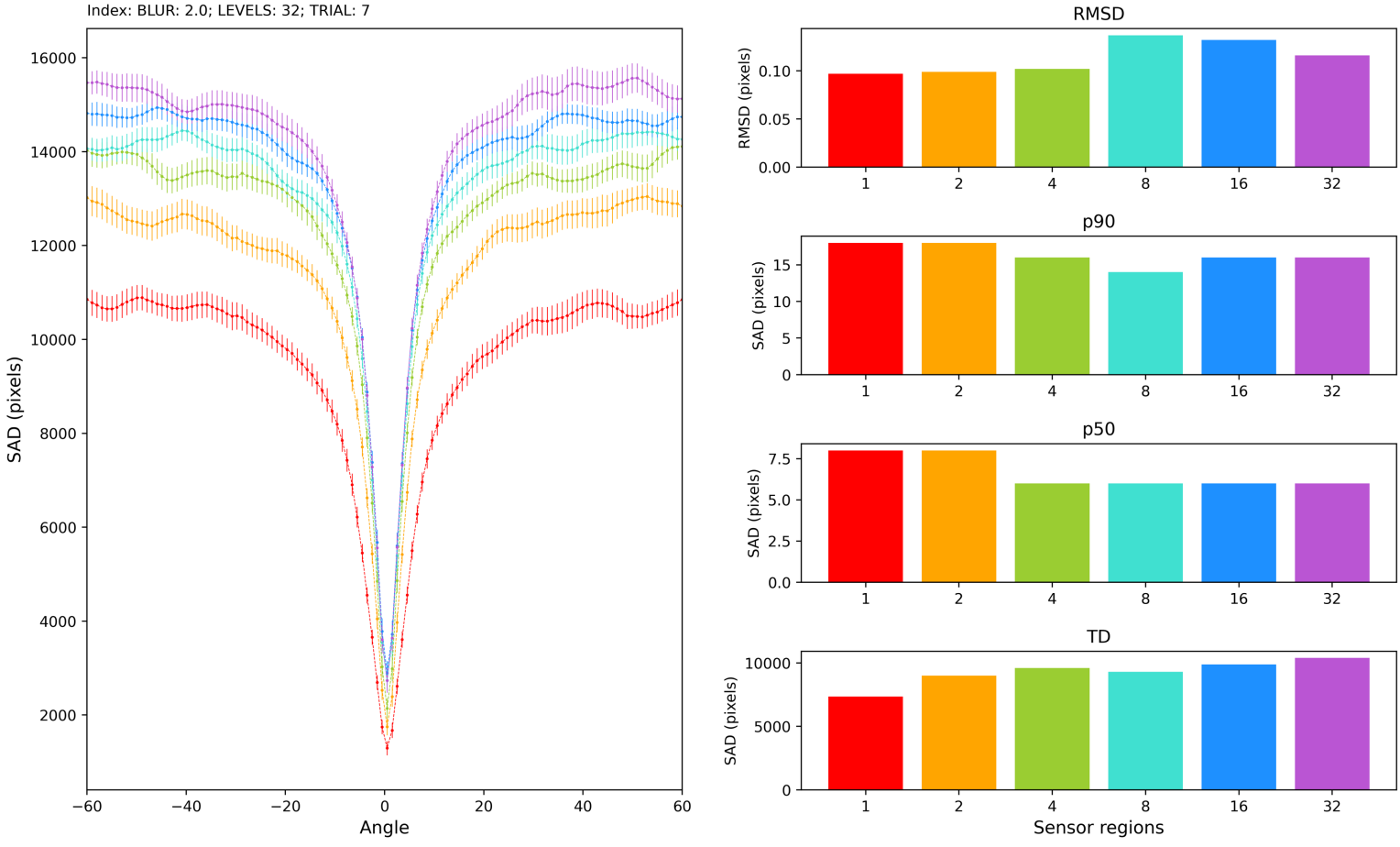
Navigation stats: RMSD error: 45.94; RMSD/dist: 0.115; TD: 10050; p90: 16; p50: 6; complete: 0

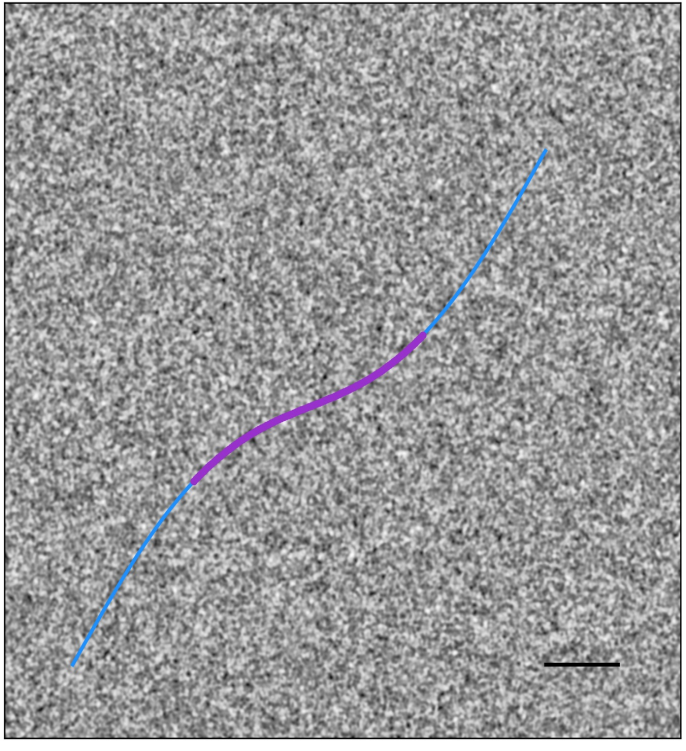


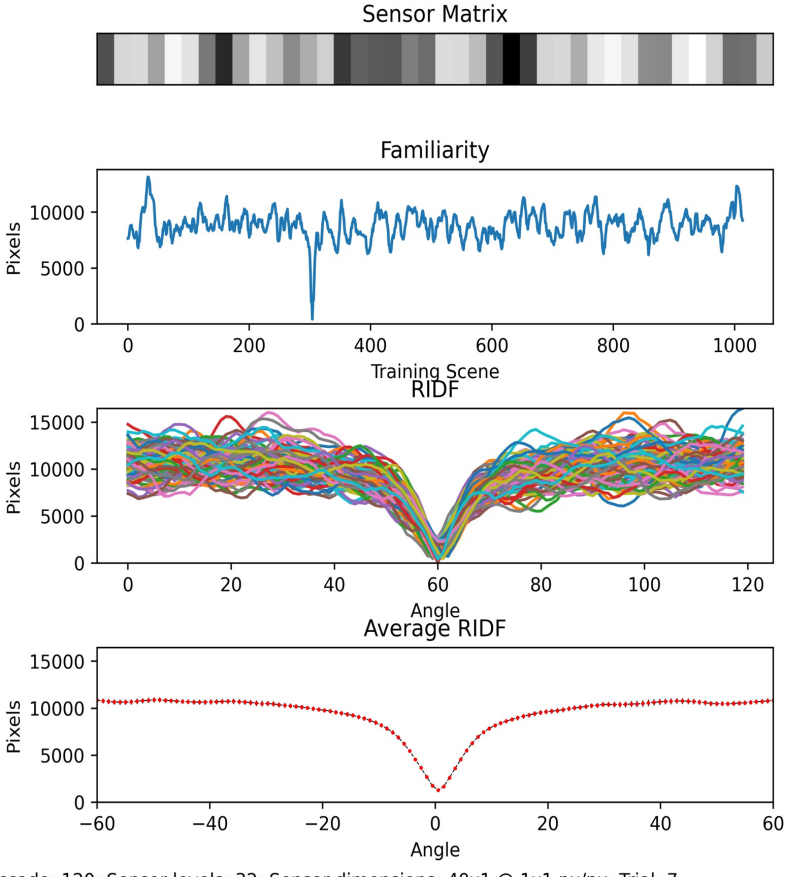


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 49.41; RMSD/dist: 0.124; TD: 10306; p90: 16; p50: 6; complete: 0

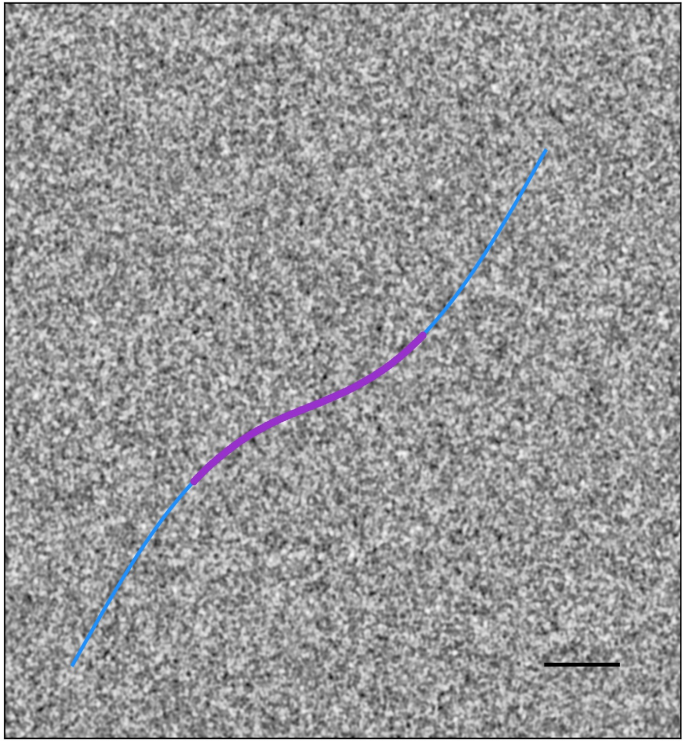

Index: BLUR: 2.0; LEVELS: 32; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

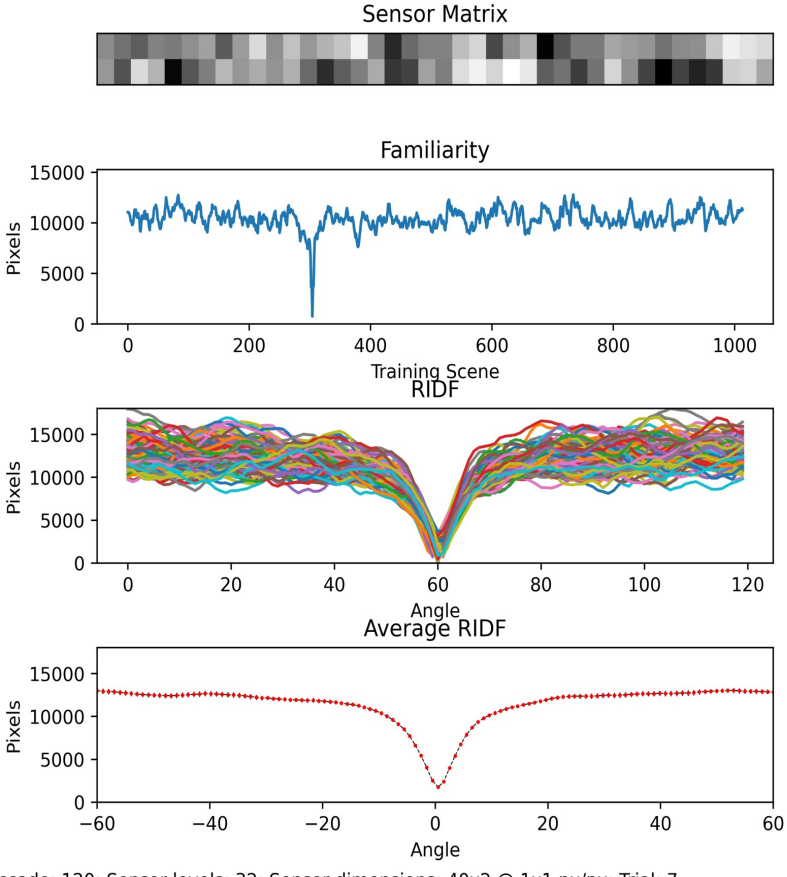




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

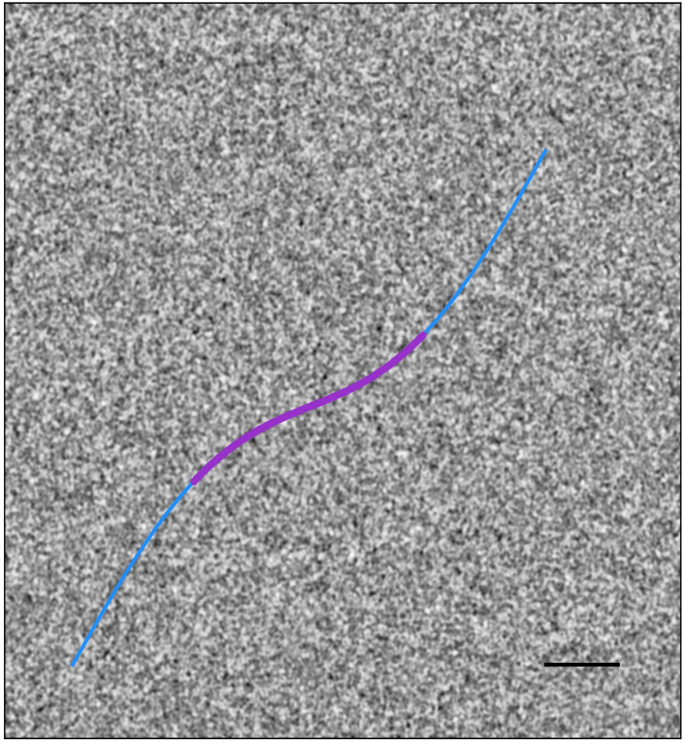
Navigation stats: RMSD error: 38.79; RMSD/dist: 0.097; TD: 7349; p90: 18; p50: 8; complete: 0

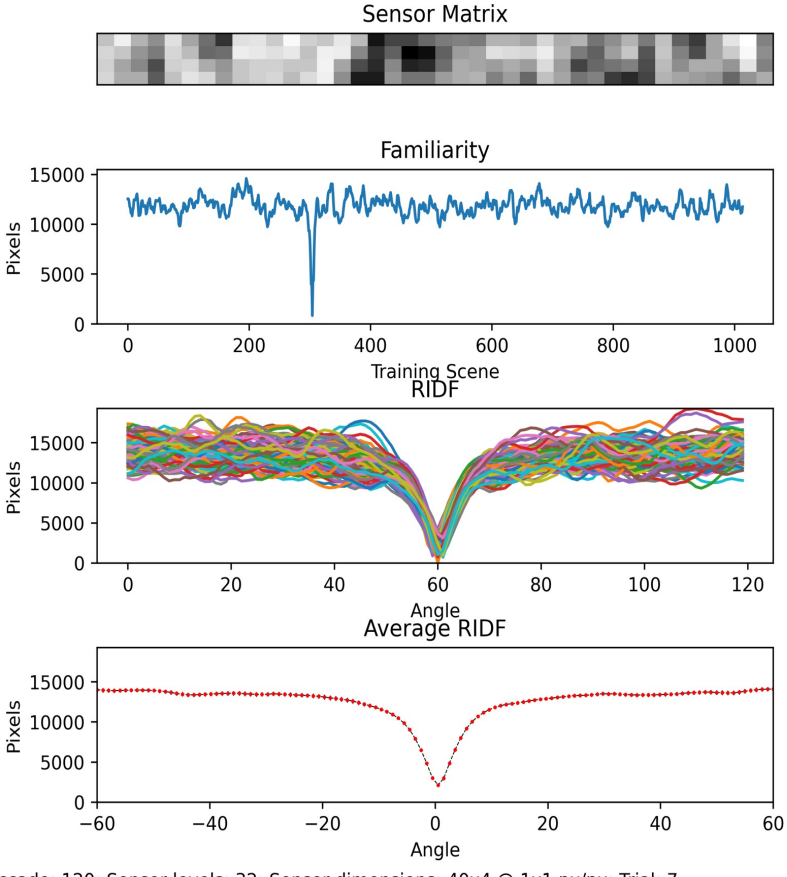




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

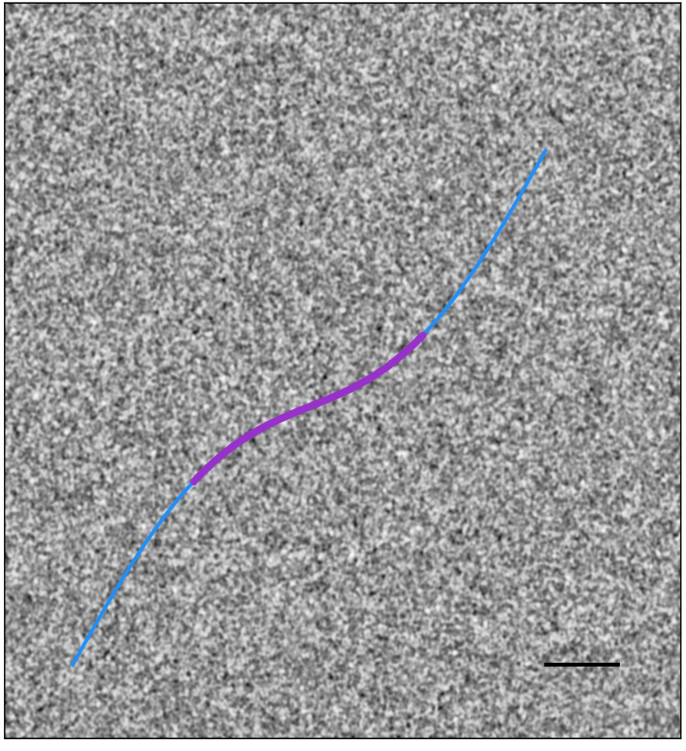
Navigation stats: RMSD error: 39.42; RMSD/dist: 0.099; TD: 8998; p90: 18; p50: 8; complete: 0

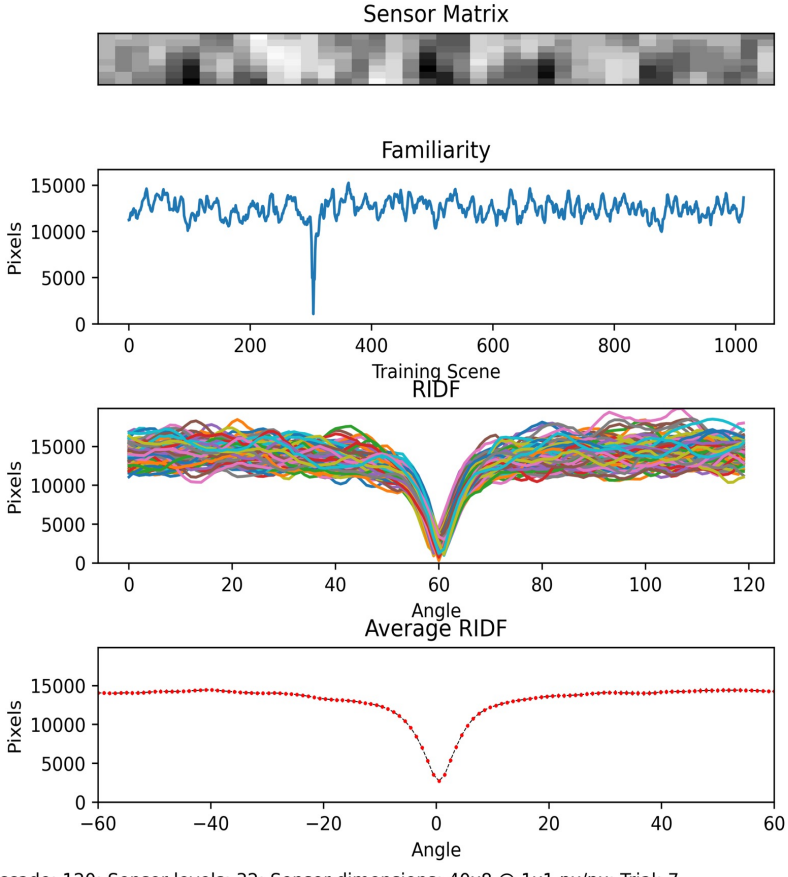




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

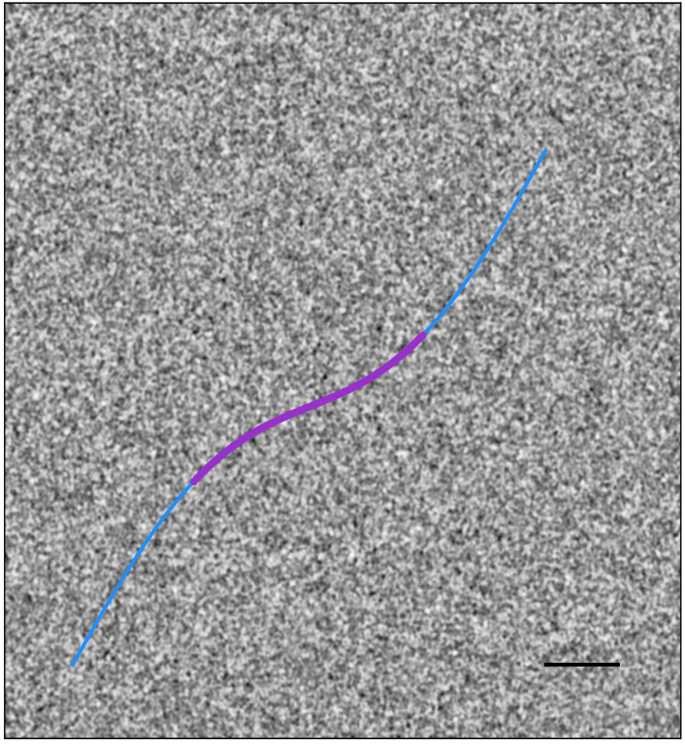
Navigation stats: RMSD error: 41.00; RMSD/dist: 0.102; TD: 9591; p90: 16; p50: 6; complete: 0

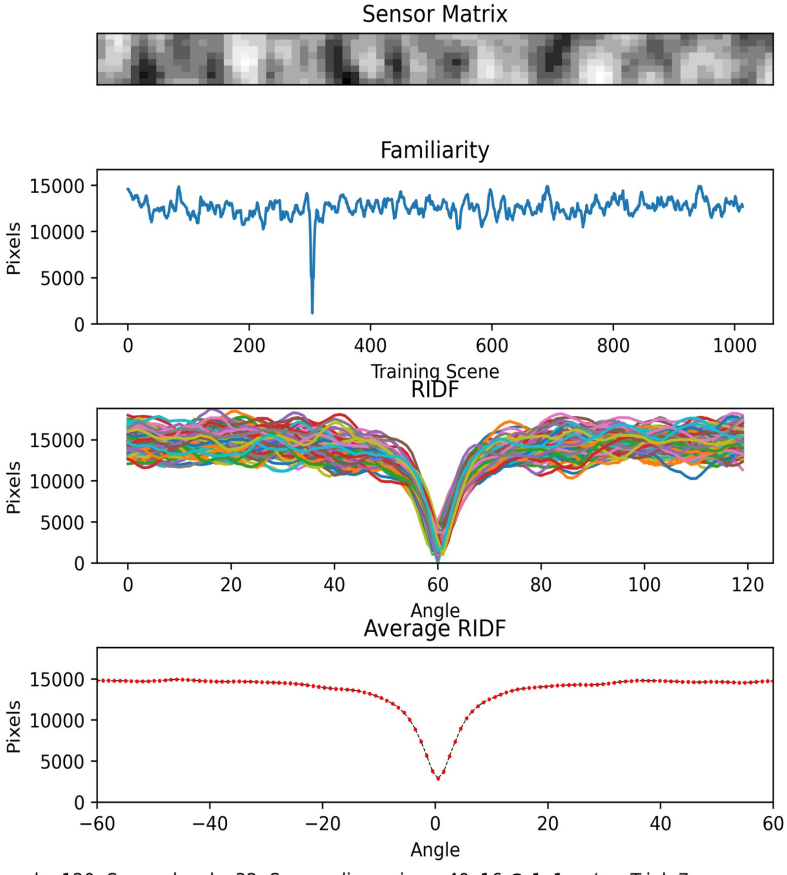




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

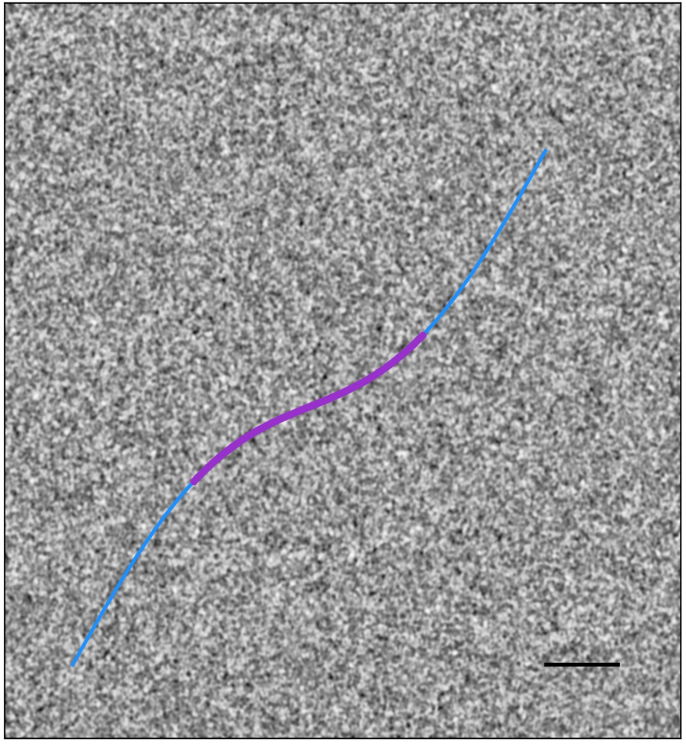
Navigation stats: RMSD error: 54.97; RMSD/dist: 0.137; TD: 9300; p90: 14; p50: 6; complete: 0

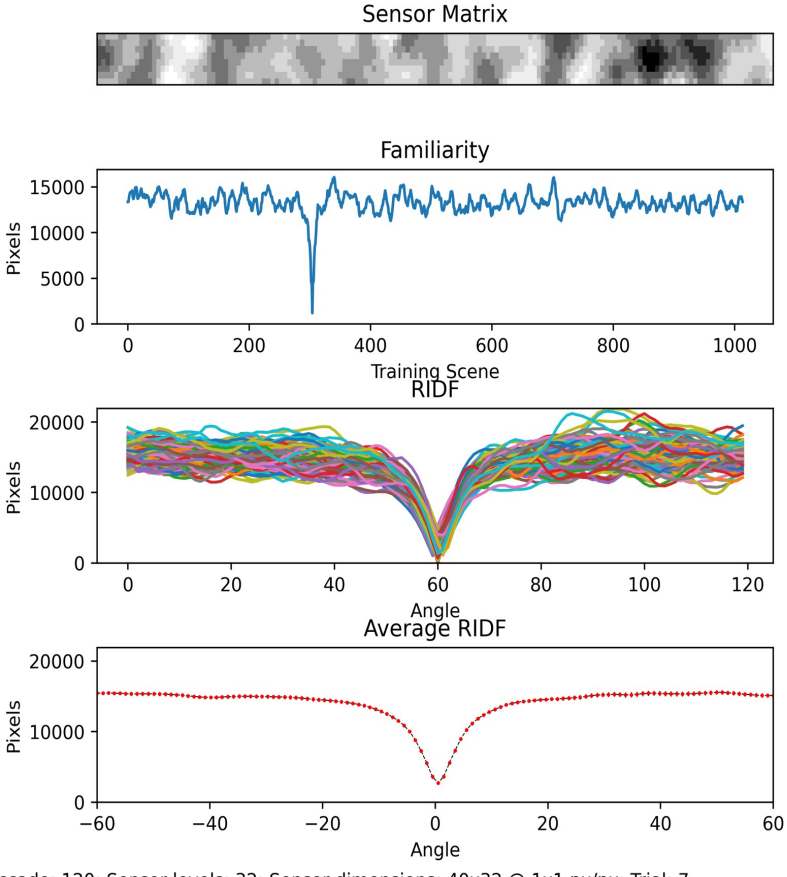




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

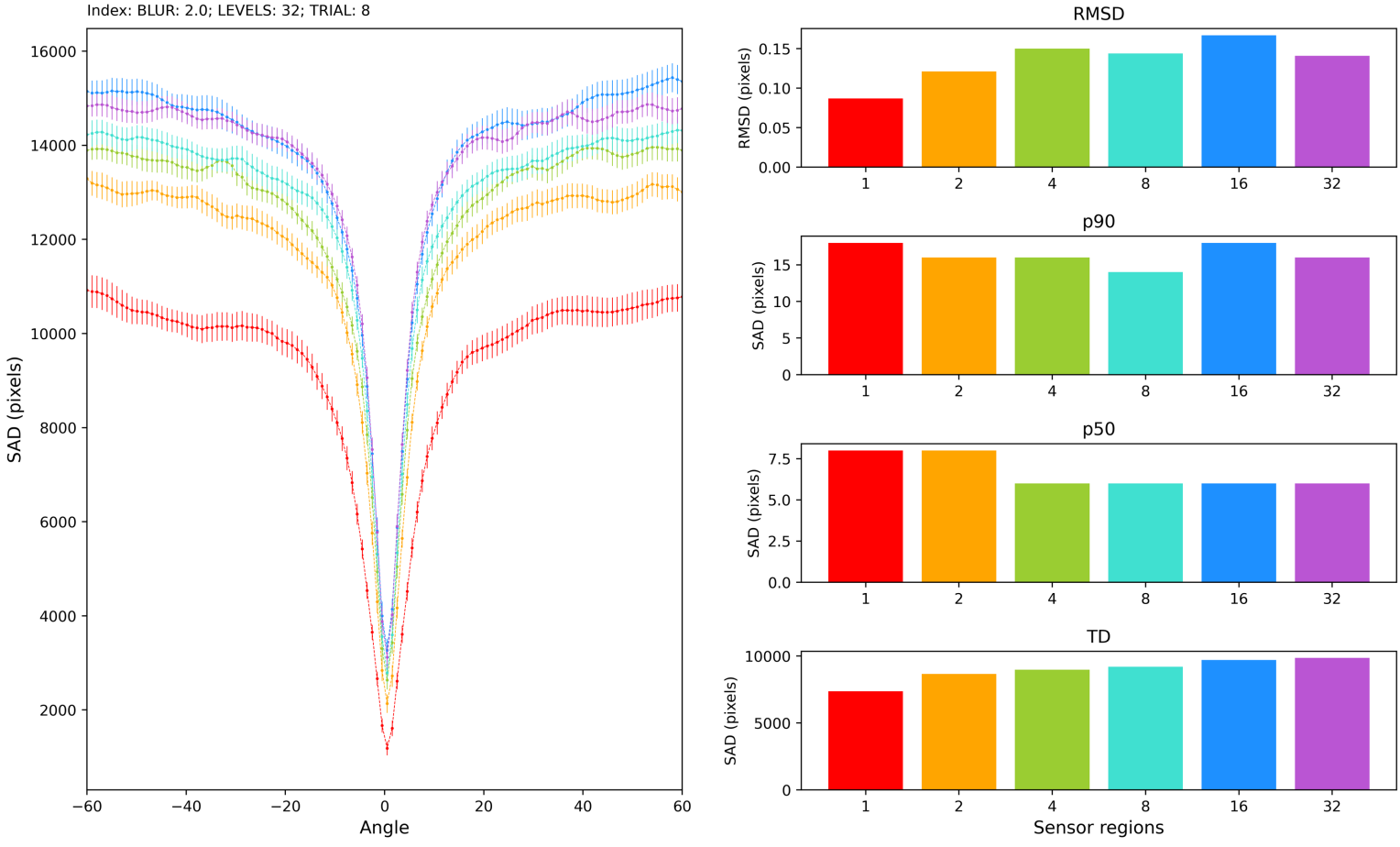
Navigation stats: RMSD error: 52.86; RMSD/dist: 0.132; TD: 9882; p90: 16; p50: 6; complete: 0

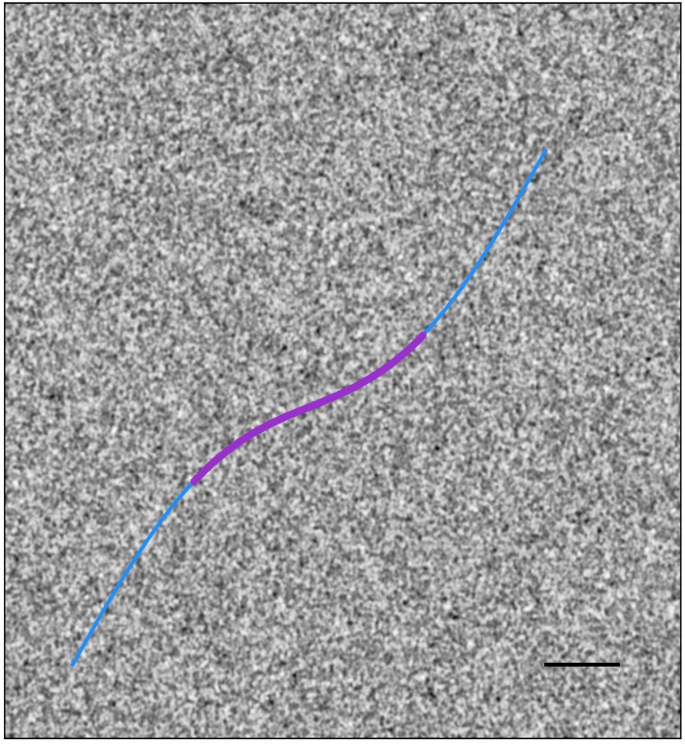


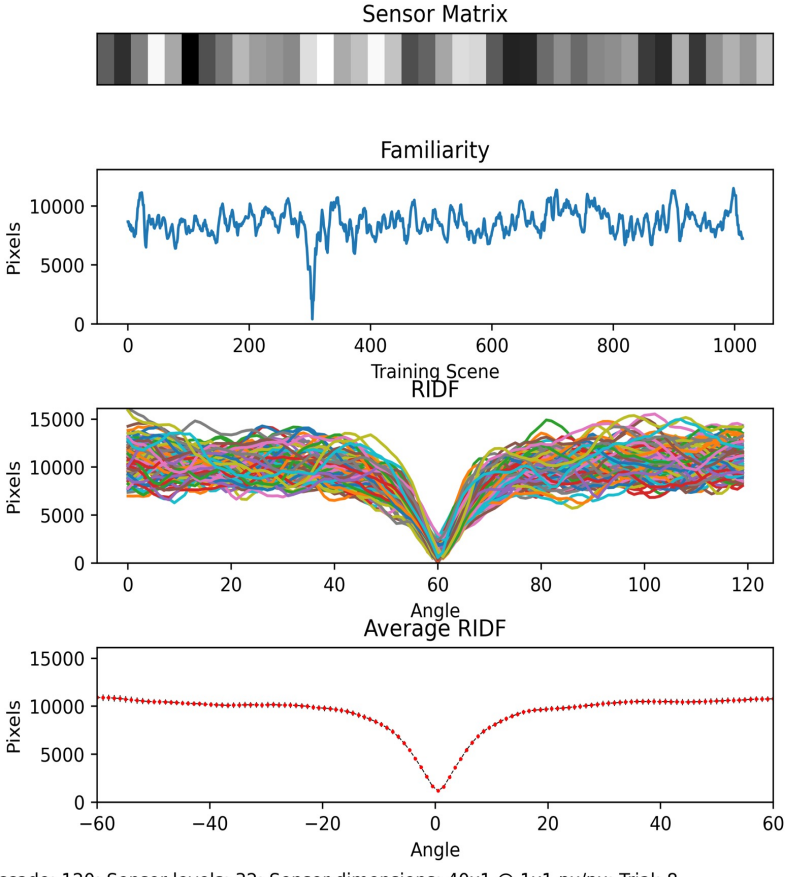


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 46.55; RMSD/dist: 0.116; TD: 10387; p90: 16; p50: 6; complete: 0

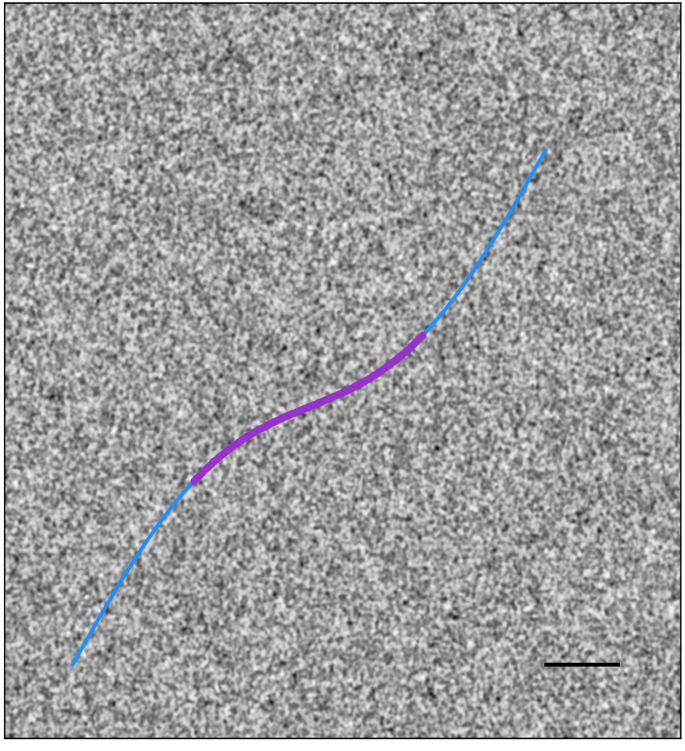

Index: BLUR: 2.0; LEVELS: 32; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

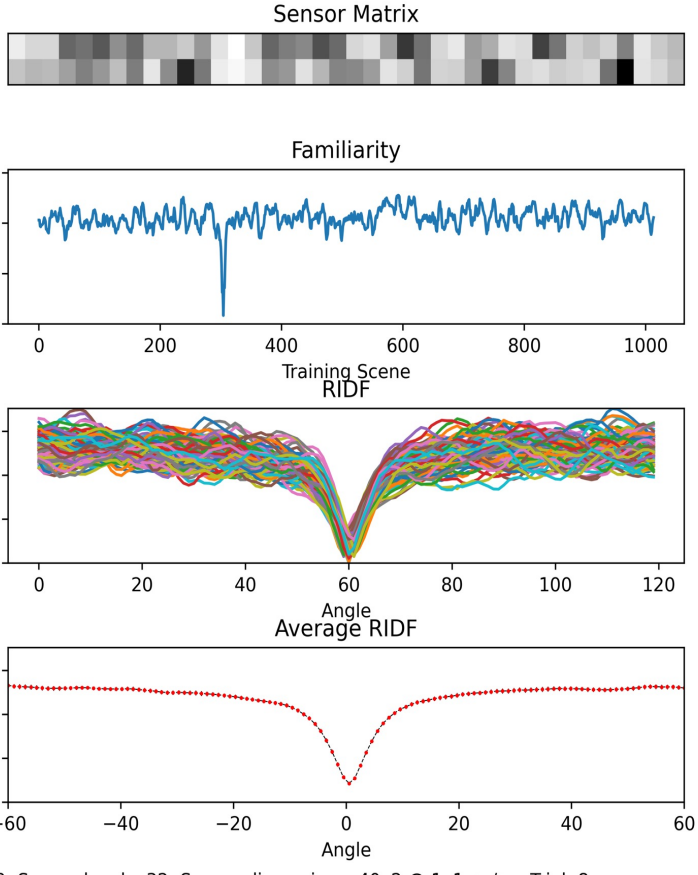




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

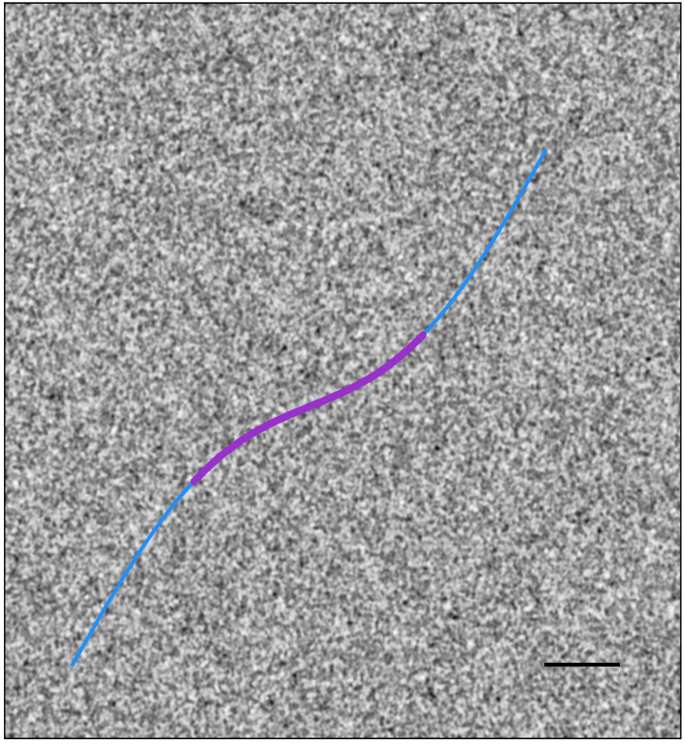
Navigation stats: RMSD error: 34.83; RMSD/dist: 0.087; TD: 7362; p90: 18; p50: 8; complete: 0

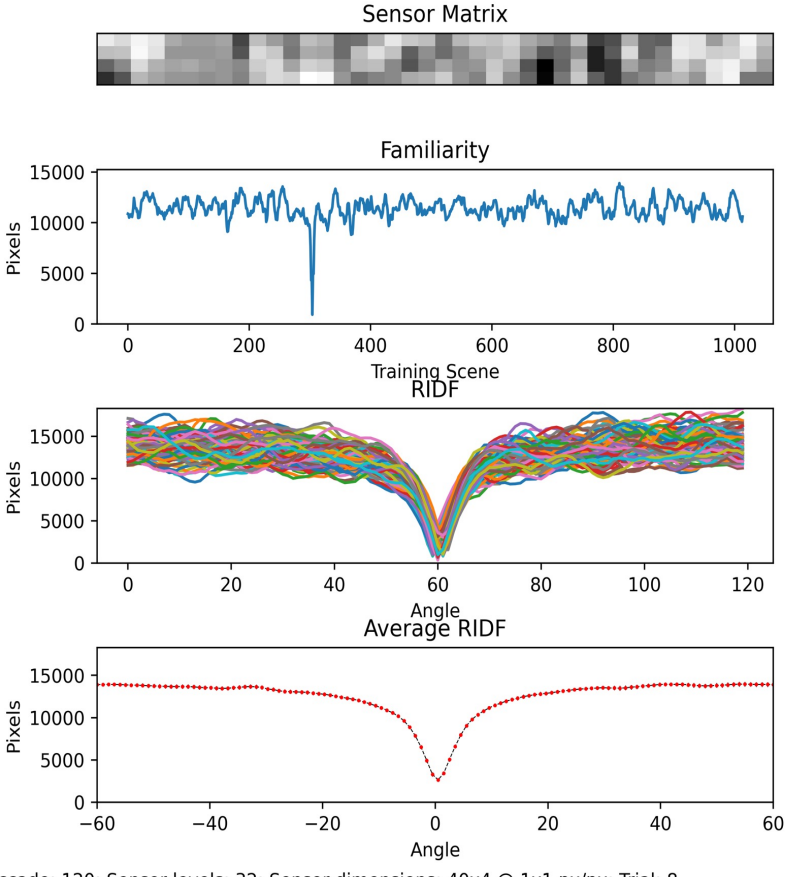




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

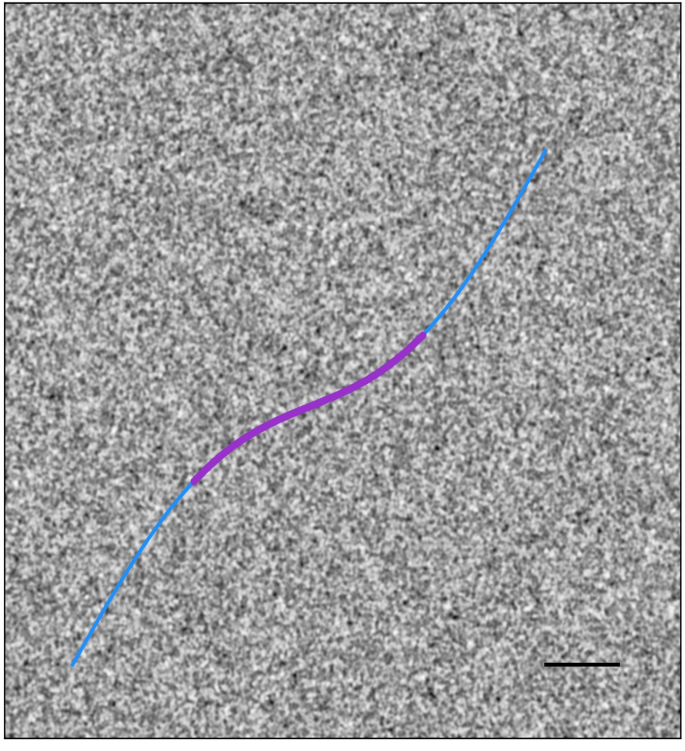
Navigation stats: RMSD error: 48.58; RMSD/dist: 0.121; TD: 8659; p90: 16; p50: 8; complete: 0

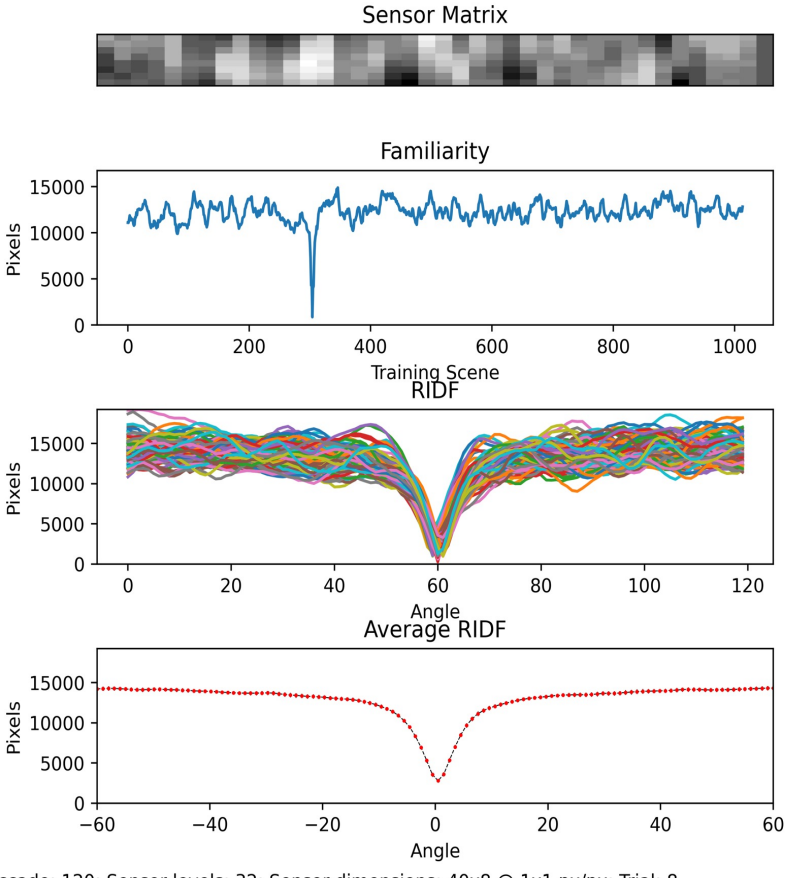




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

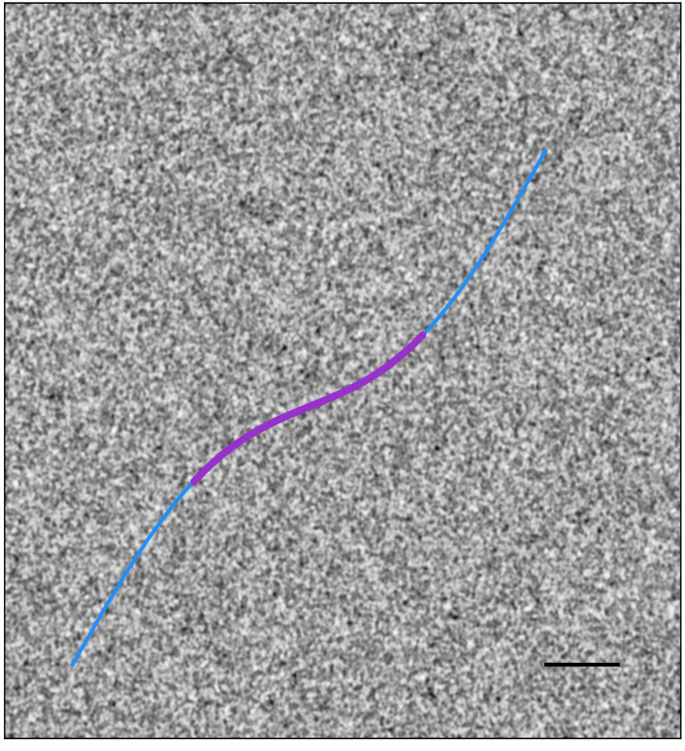
Navigation stats: RMSD error: 60.03; RMSD/dist: 0.150; TD: 8962; p90: 16; p50: 6; complete: 0

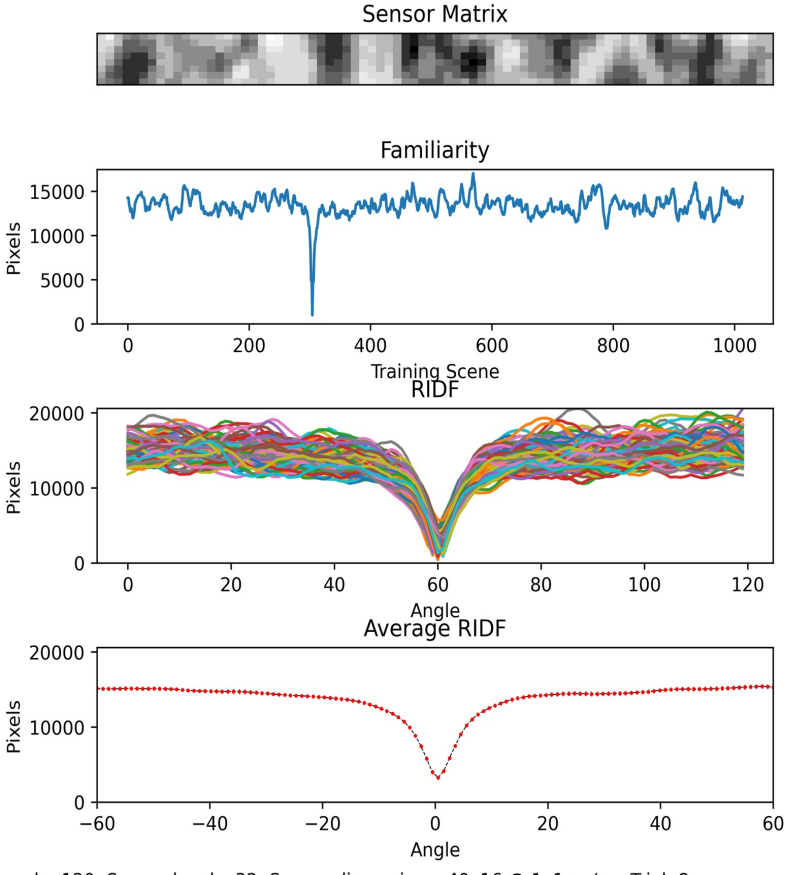




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

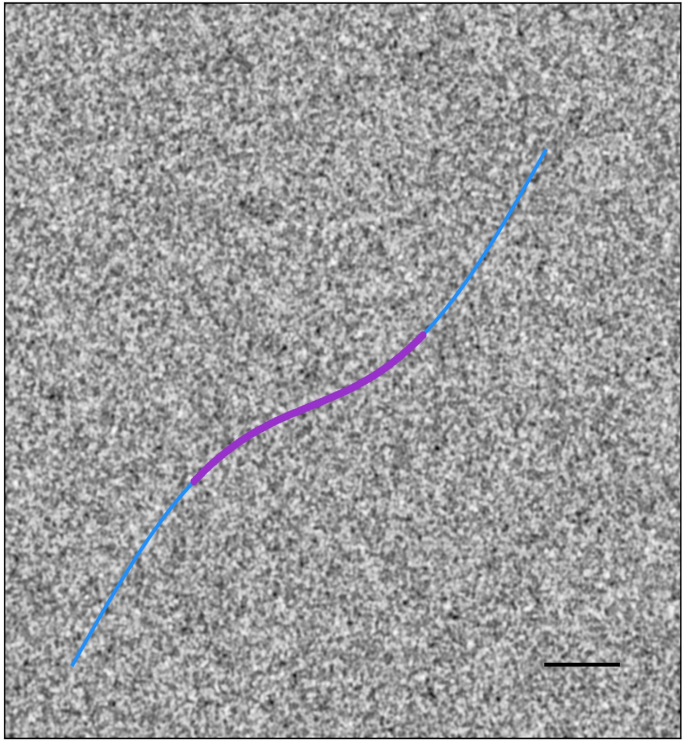
Navigation stats: RMSD error: 57.63; RMSD/dist: 0.144; TD: 9184; p90: 14; p50: 6; complete: 0

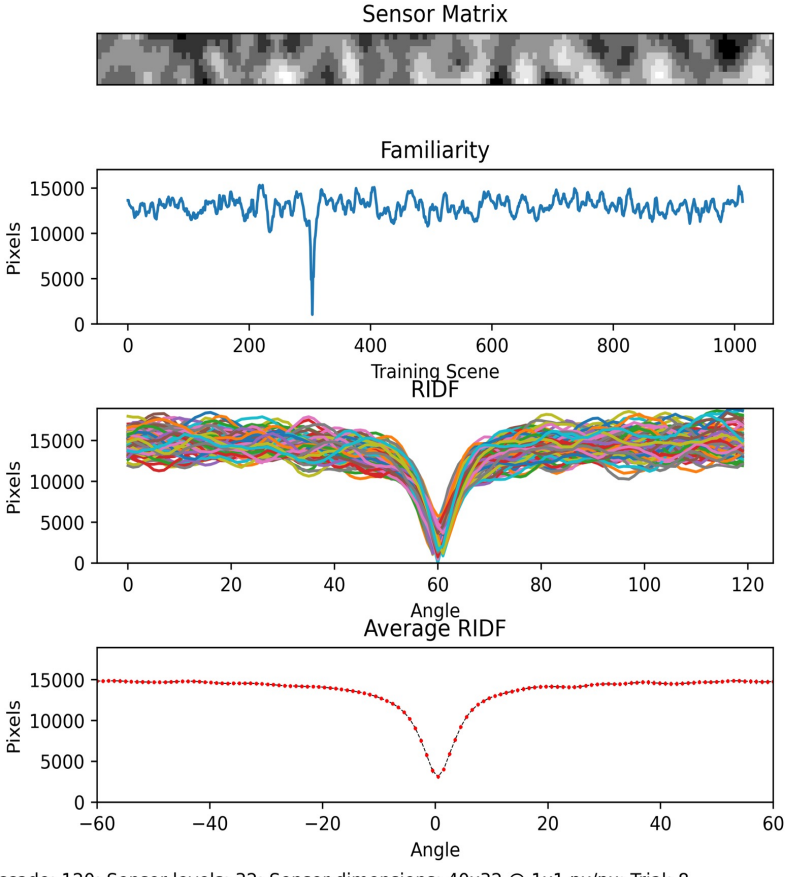




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

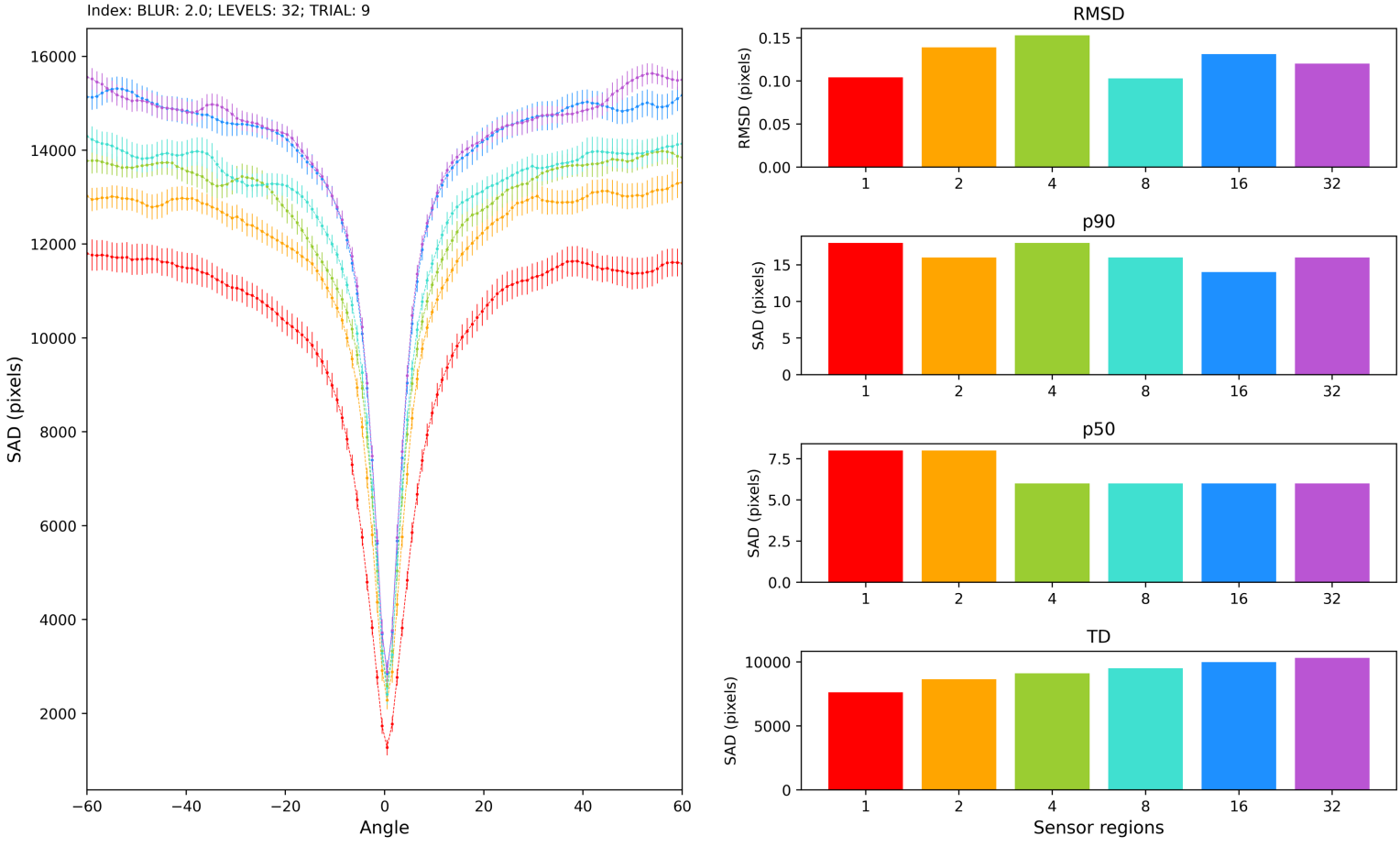
Navigation stats: RMSD error: 66.63; RMSD/dist: 0.167; TD: 9691; p90: 18; p50: 6; complete: 0

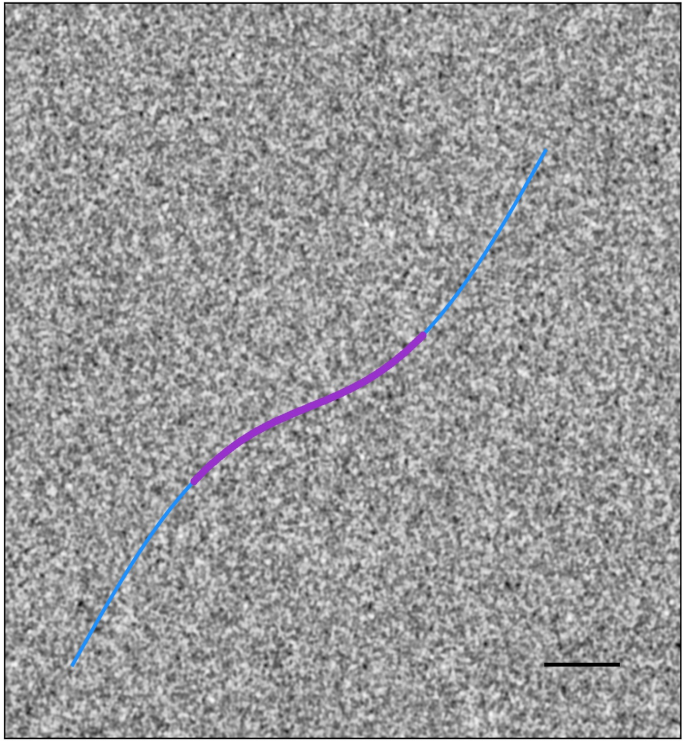


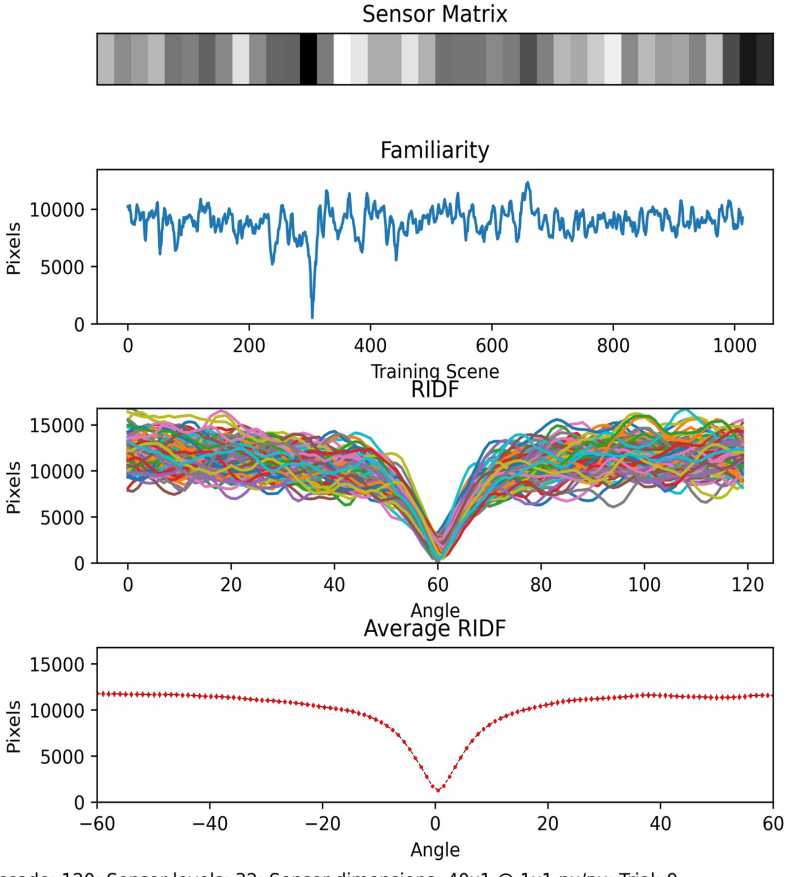


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 56.30; RMSD/dist: 0.141; TD: 9845; p90: 16; p50: 6; complete: 0

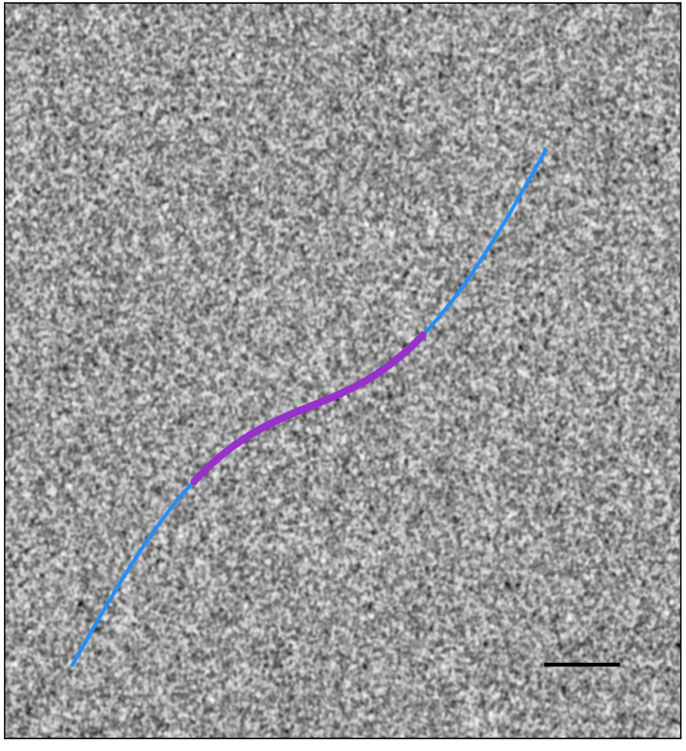

Index: BLUR: 2.0; LEVELS: 32; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

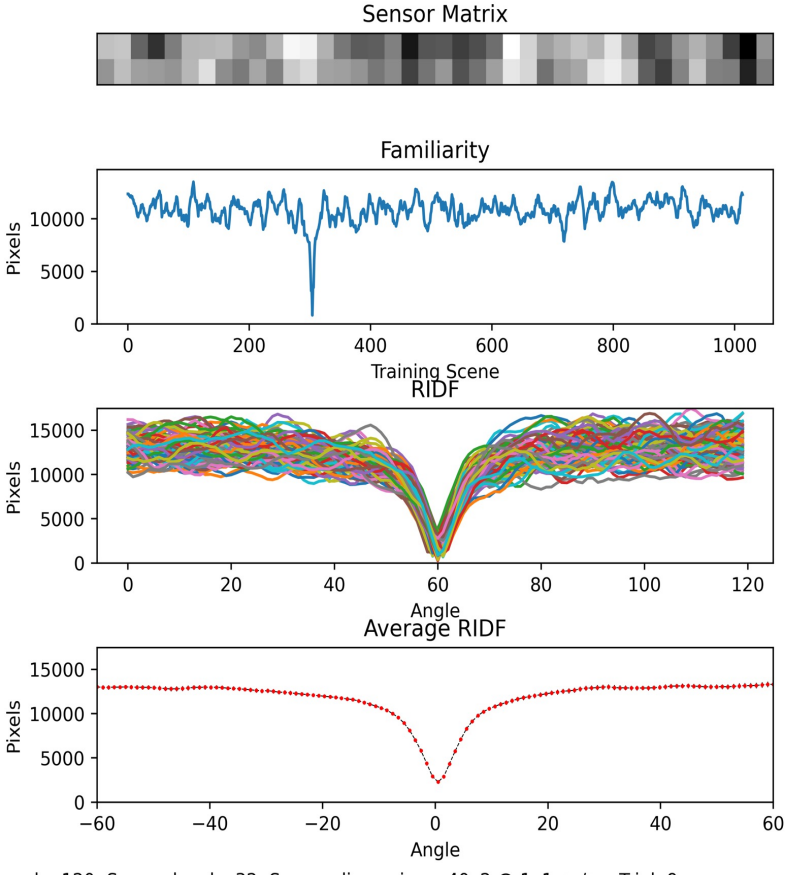




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

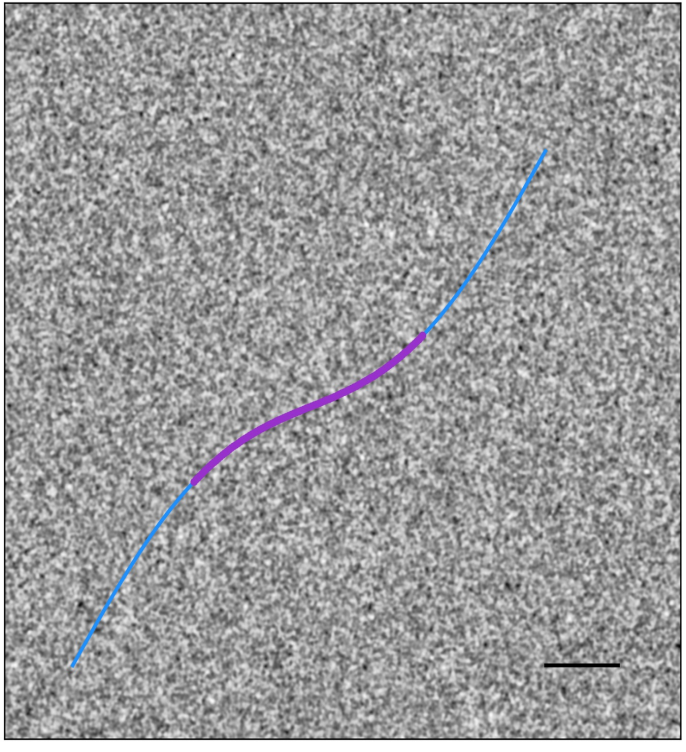
Navigation stats: RMSD error: 41.62; RMSD/dist: 0.104; TD: 7620; p90: 18; p50: 8; complete: 0

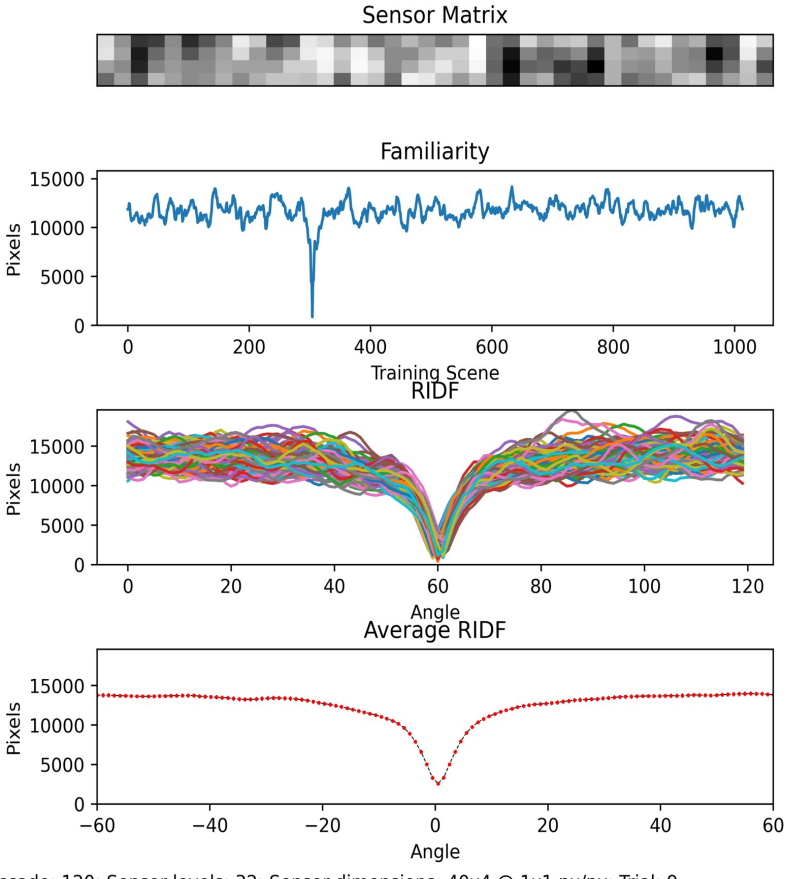




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

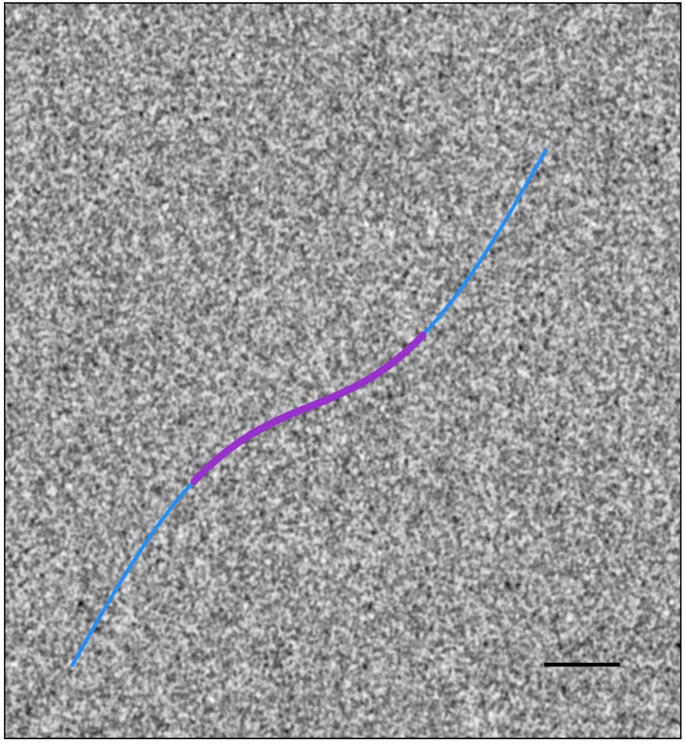
Navigation stats: RMSD error: 55.53; RMSD/dist: 0.139; TD: 8644; p90: 16; p50: 8; complete: 0

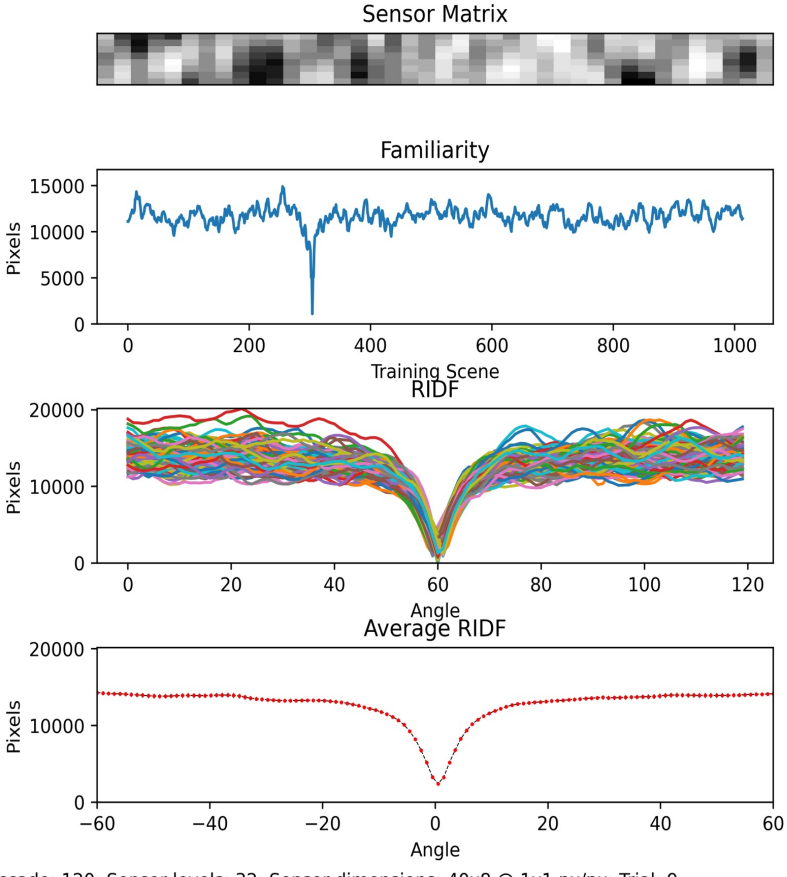




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

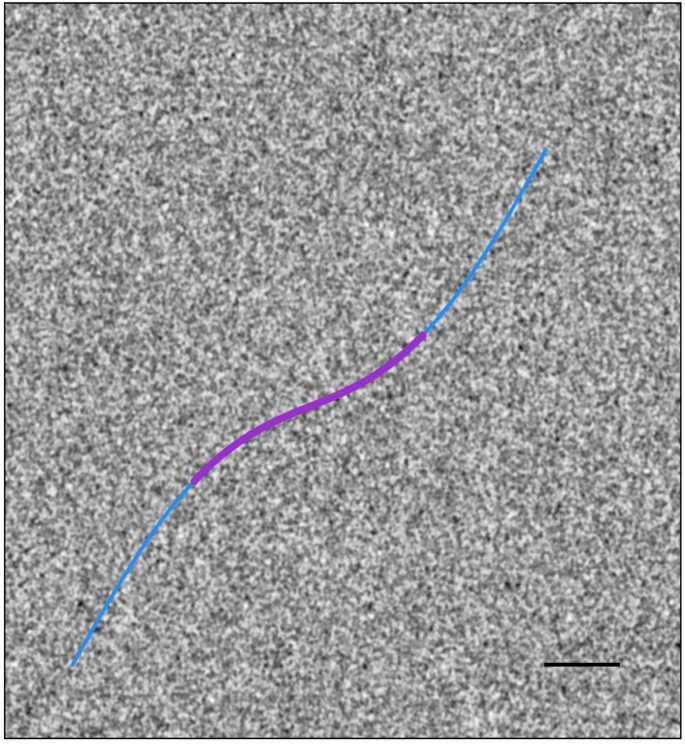
Navigation stats: RMSD error: 61.19; RMSD/dist: 0.153; TD: 9121; p90: 18; p50: 6; complete: 0

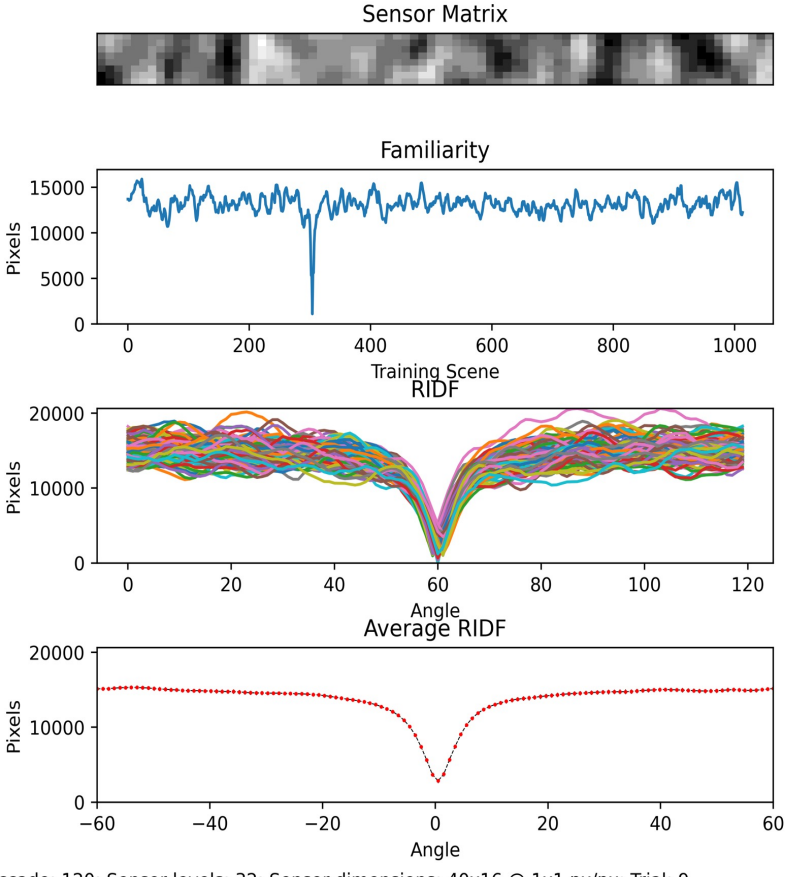




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

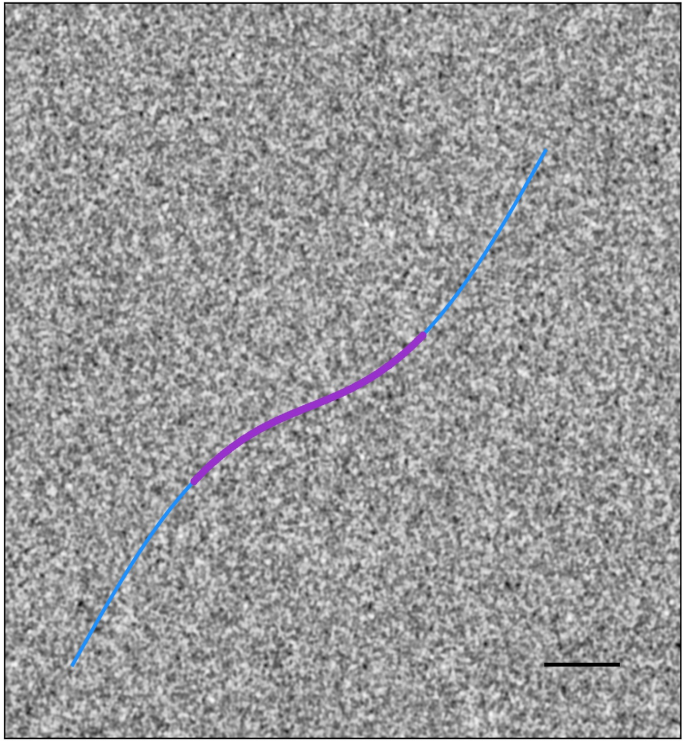
Navigation stats: RMSD error: 41.31; RMSD/dist: 0.103; TD: 9517; p90: 16; p50: 6; complete: 0

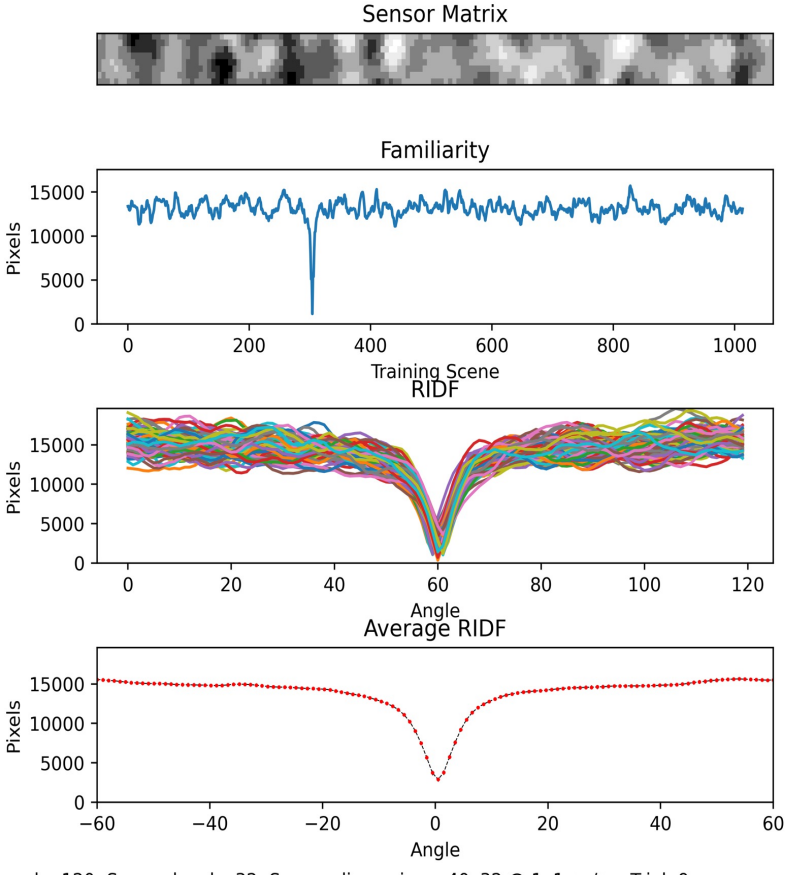




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

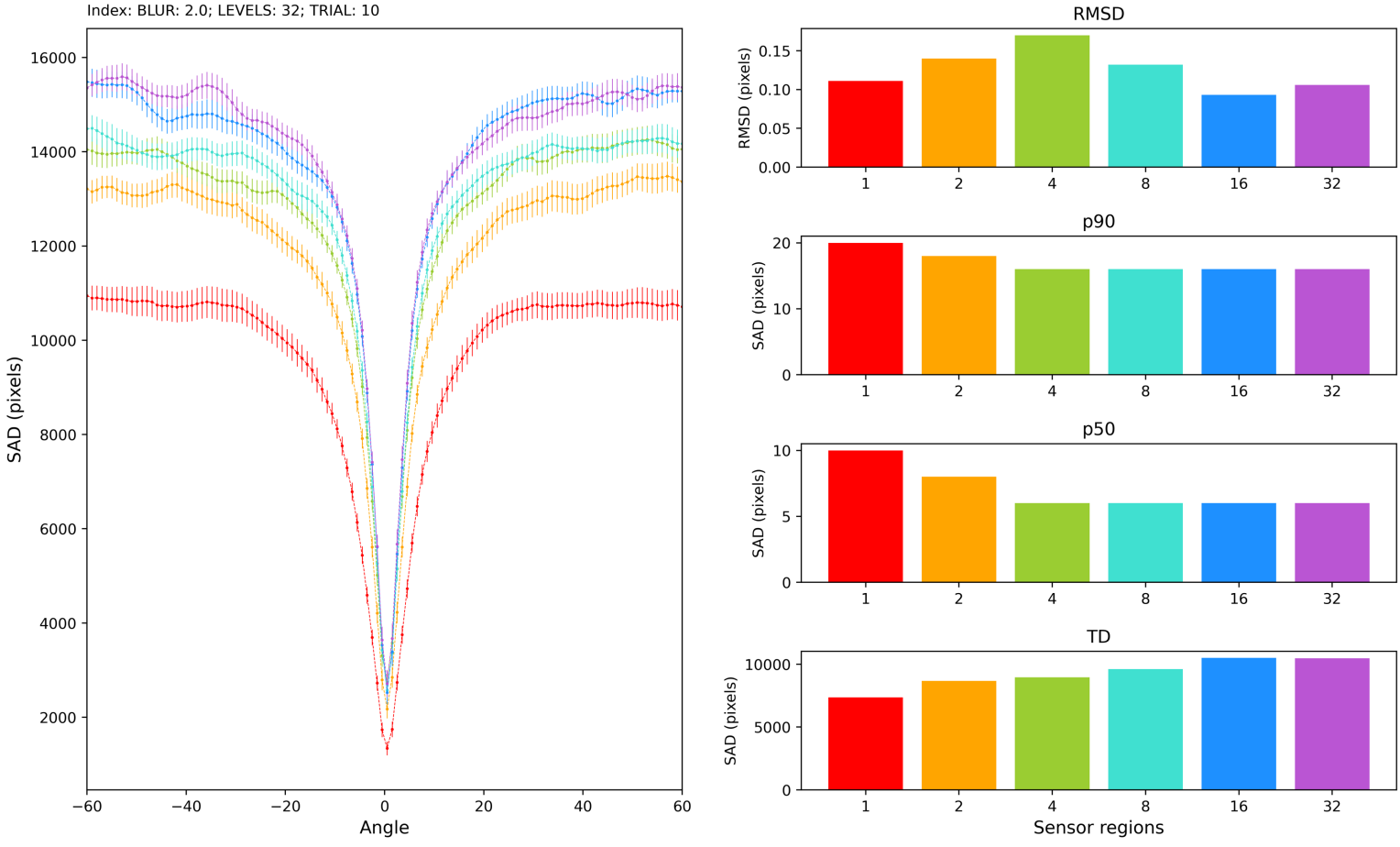
Navigation stats: RMSD error: 52.57; RMSD/dist: 0.131; TD: 9990; p90: 14; p50: 6; complete: 0

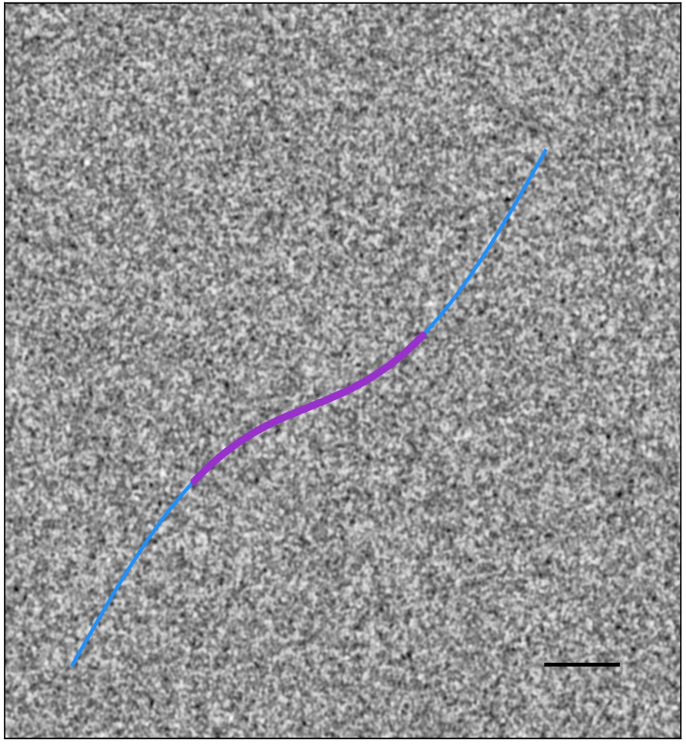


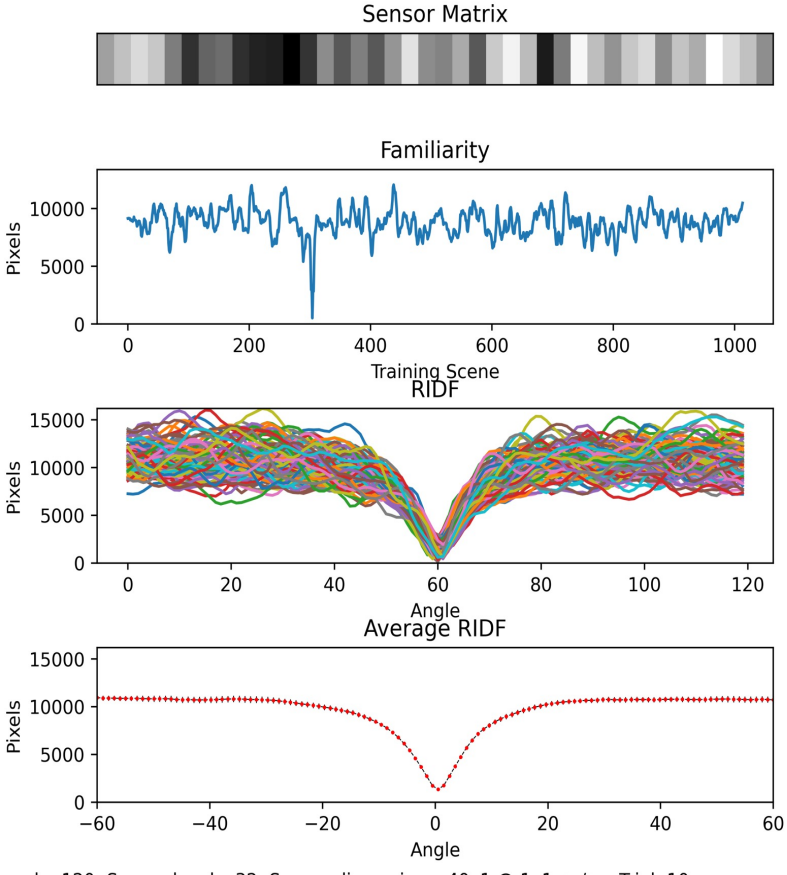


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 48.13; RMSD/dist: 0.120; TD: 10311; p90: 16; p50: 6; complete: 0

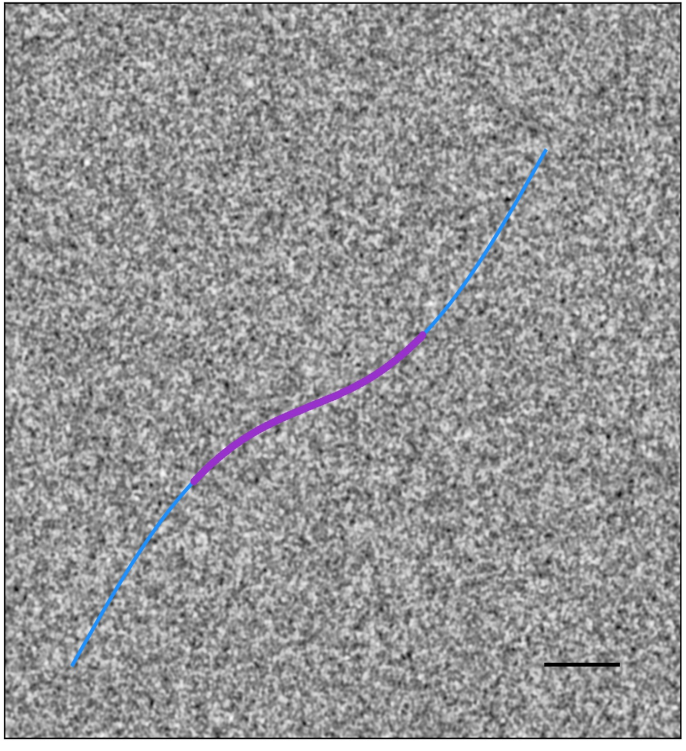

Index: BLUR: 2.0; LEVELS: 32; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

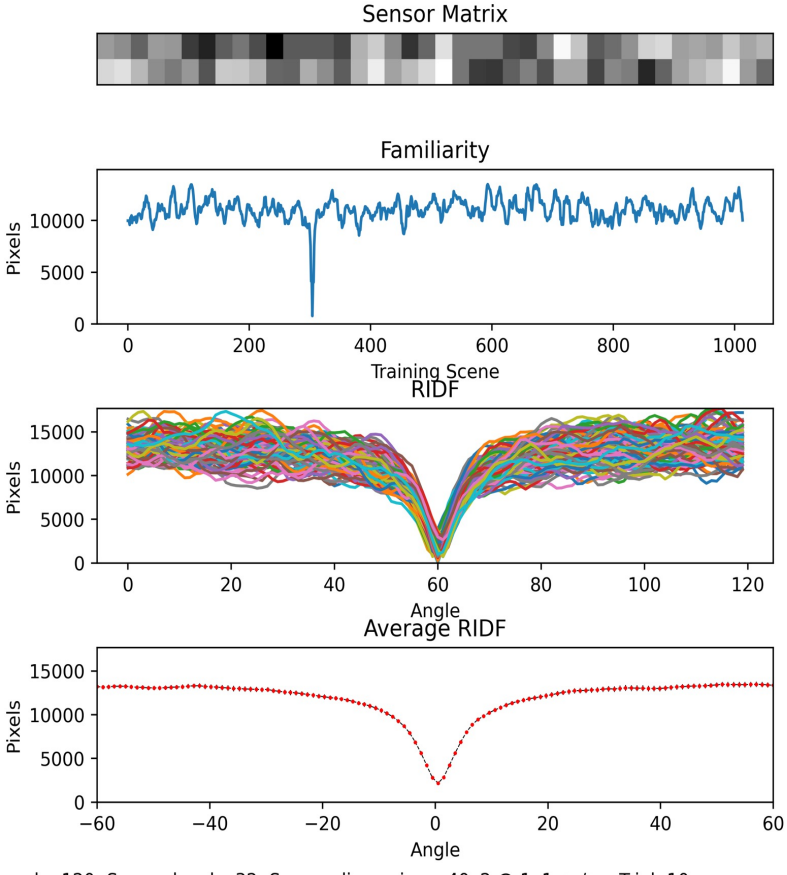




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

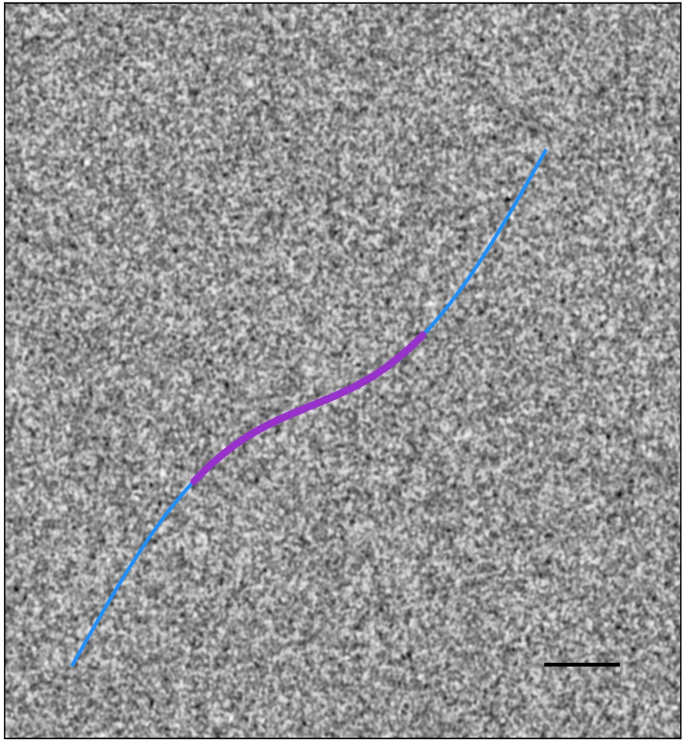
Navigation stats: RMSD error: 44.59; RMSD/dist: 0.111; TD: 7366; p90: 20; p50: 10; complete: 0

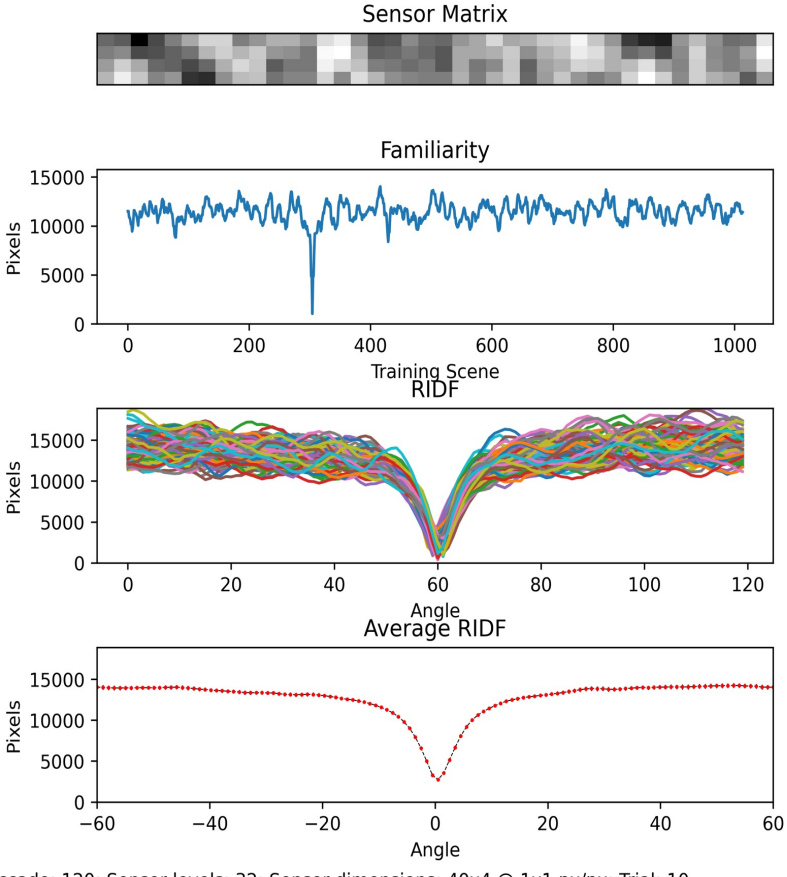




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

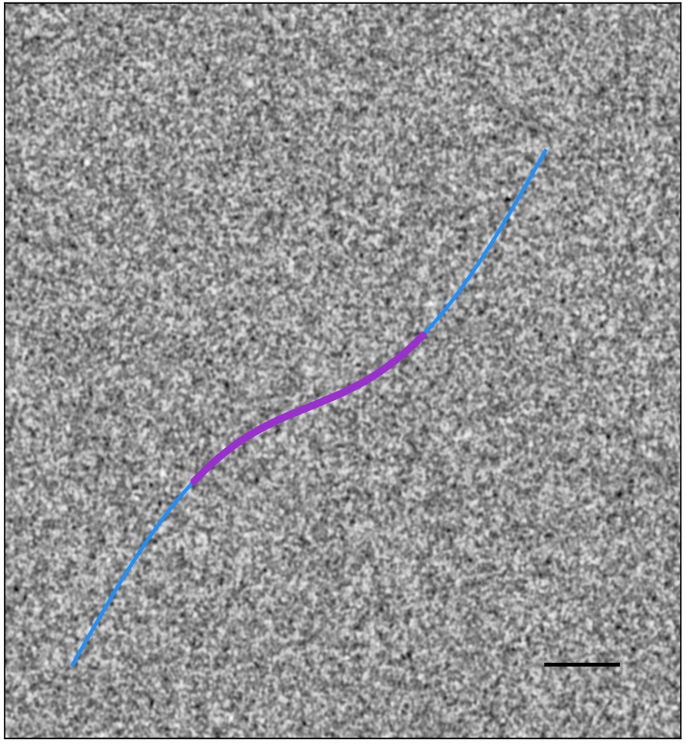
Navigation stats: RMSD error: 56.14; RMSD/dist: 0.140; TD: 8682; p90: 18; p50: 8; complete: 0

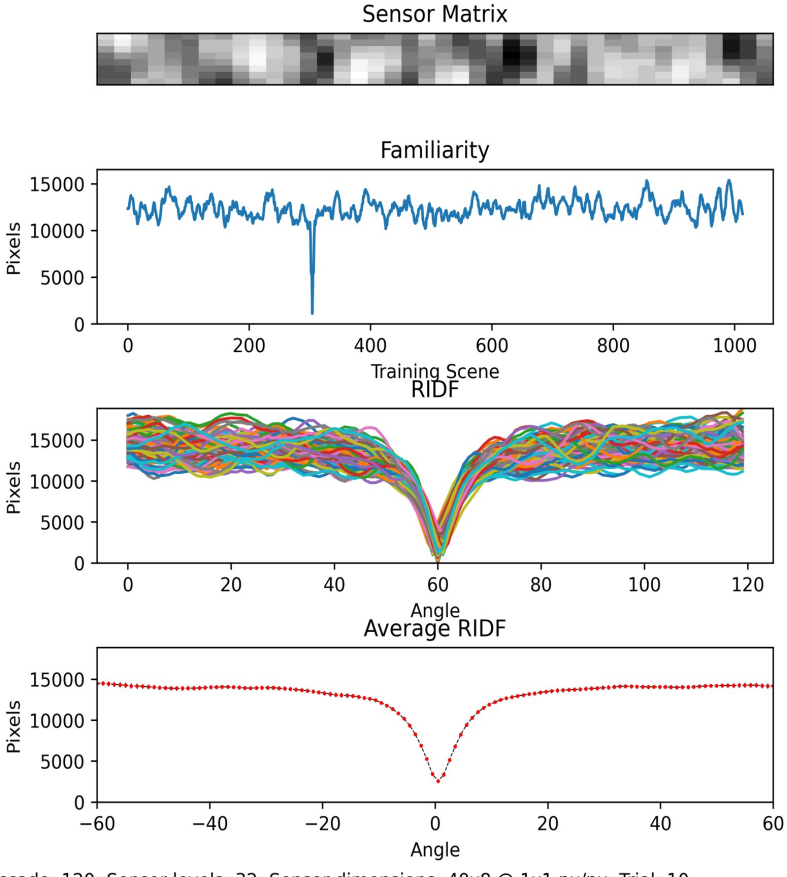




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

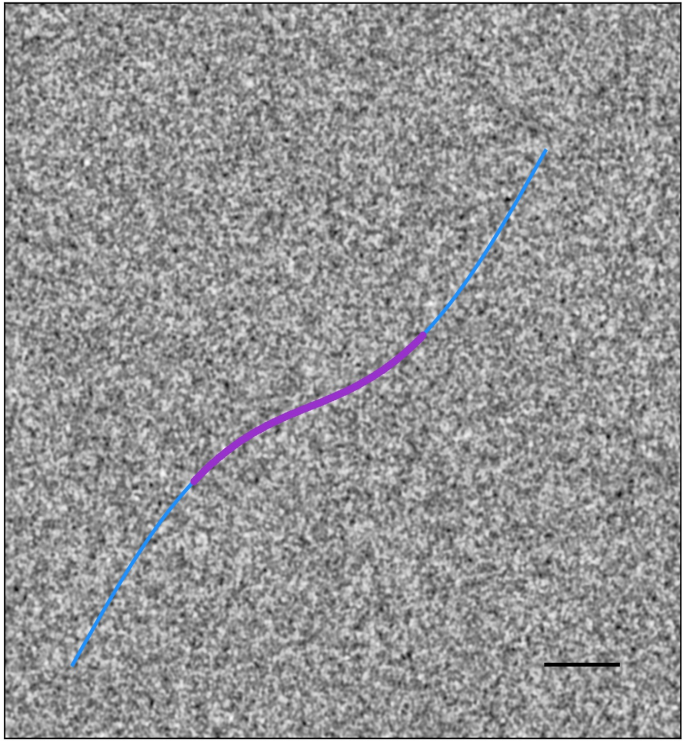
Navigation stats: RMSD error: 68.18; RMSD/dist: 0.170; TD: 8962; p90: 16; p50: 6; complete: 0

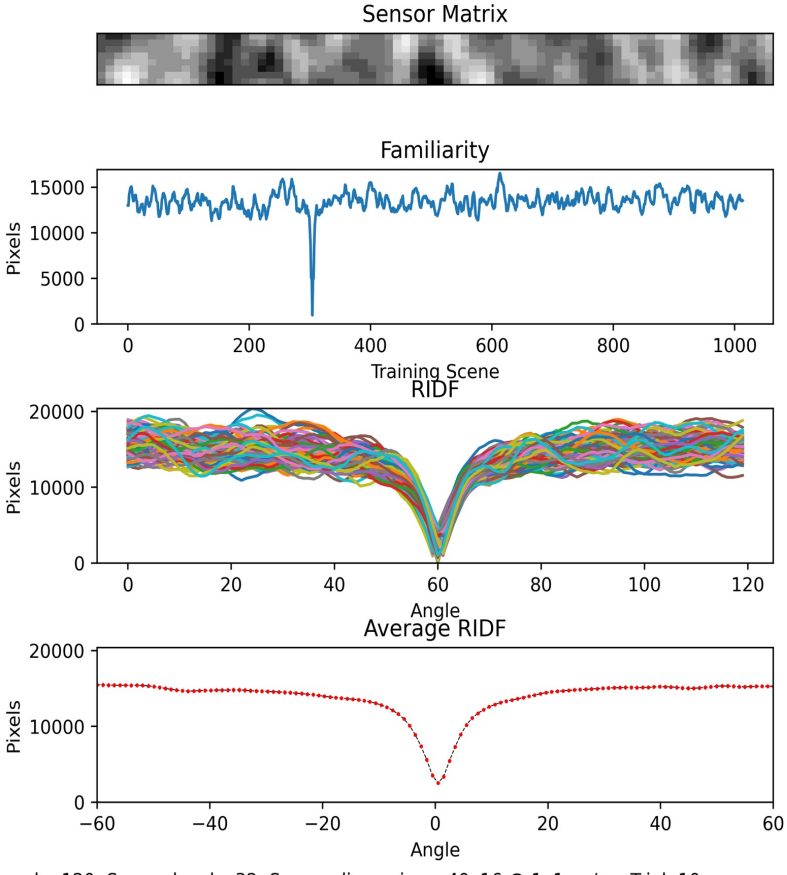




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

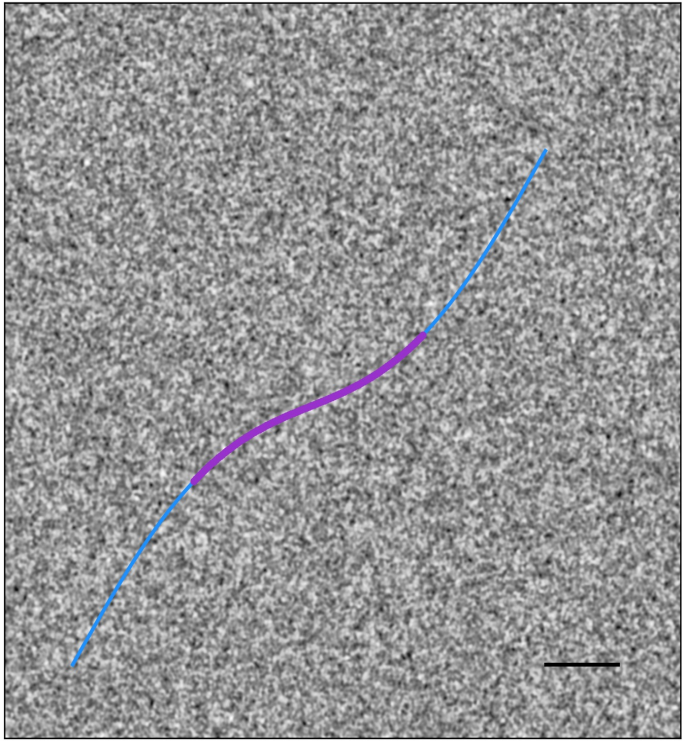
Navigation stats: RMSD error: 52.72; RMSD/dist: 0.132; TD: 9624; p90: 16; p50: 6; complete: 0

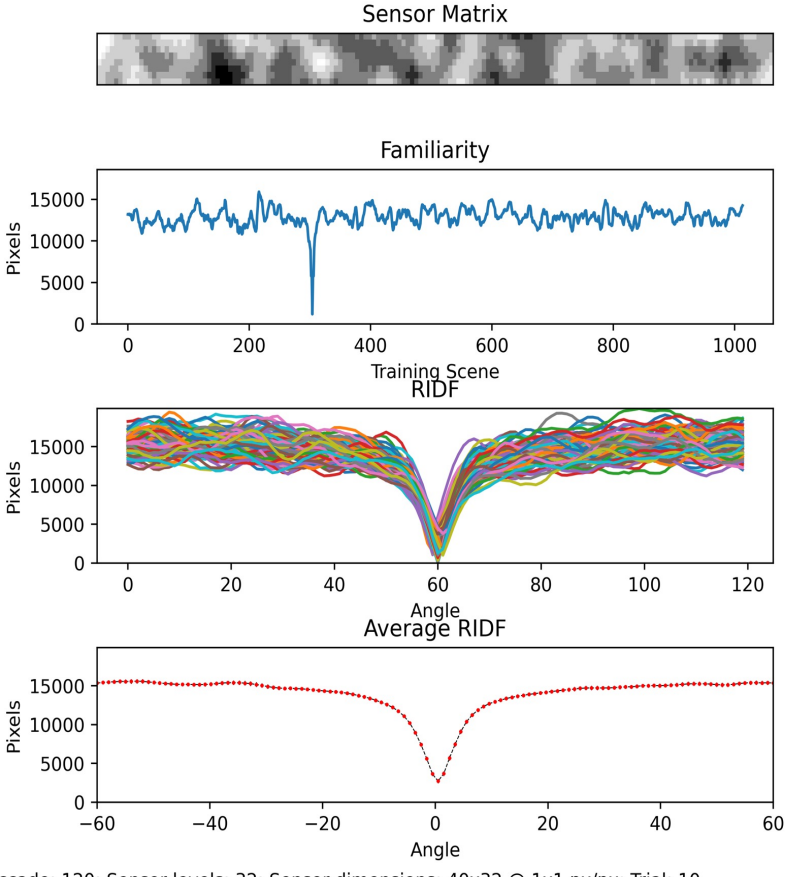




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 37.36; RMSD/dist: 0.093; TD: 10501; p90: 16; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 42.29; RMSD/dist: 0.106; TD: 10479; p90: 16; p50: 6; complete: 0