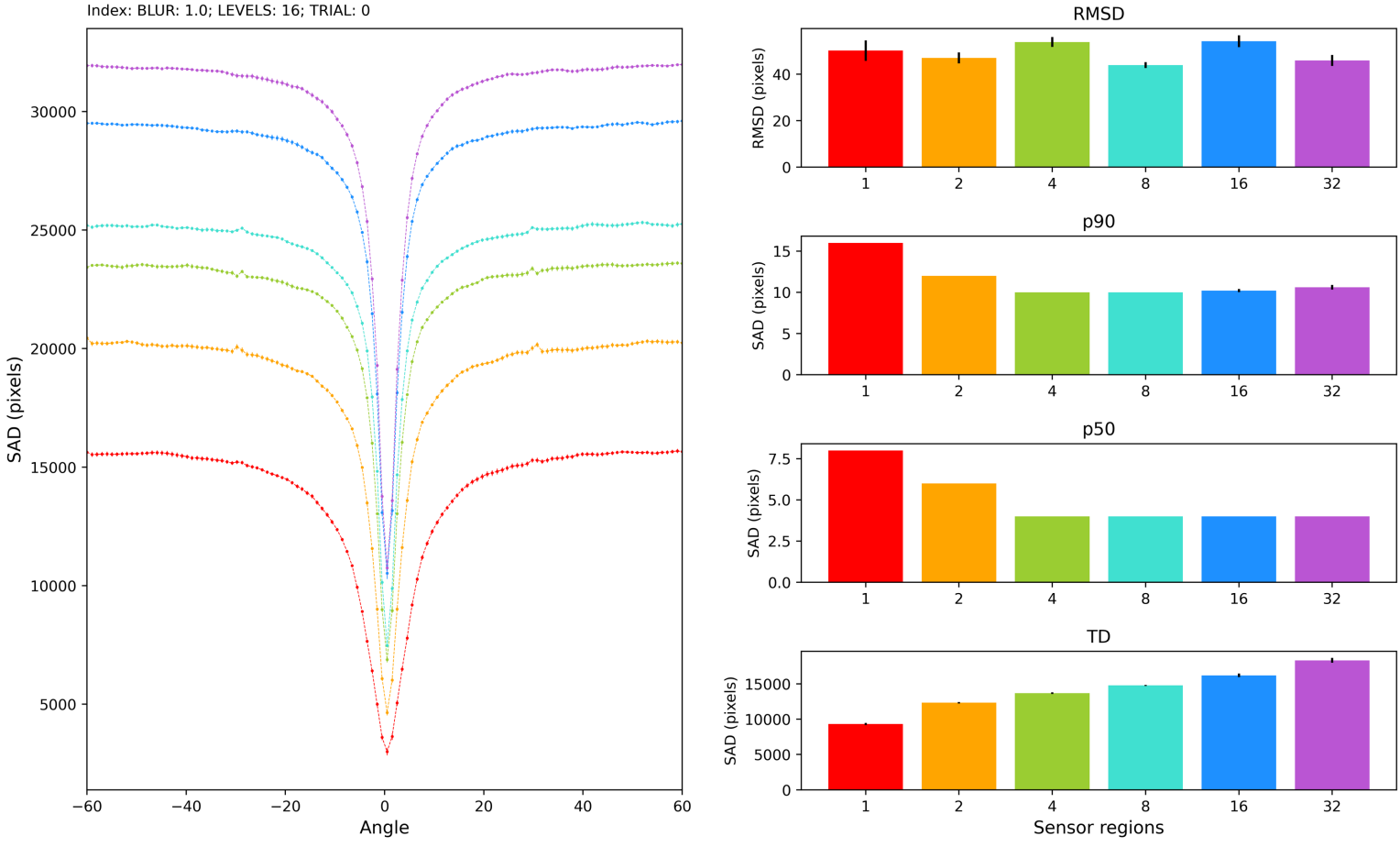
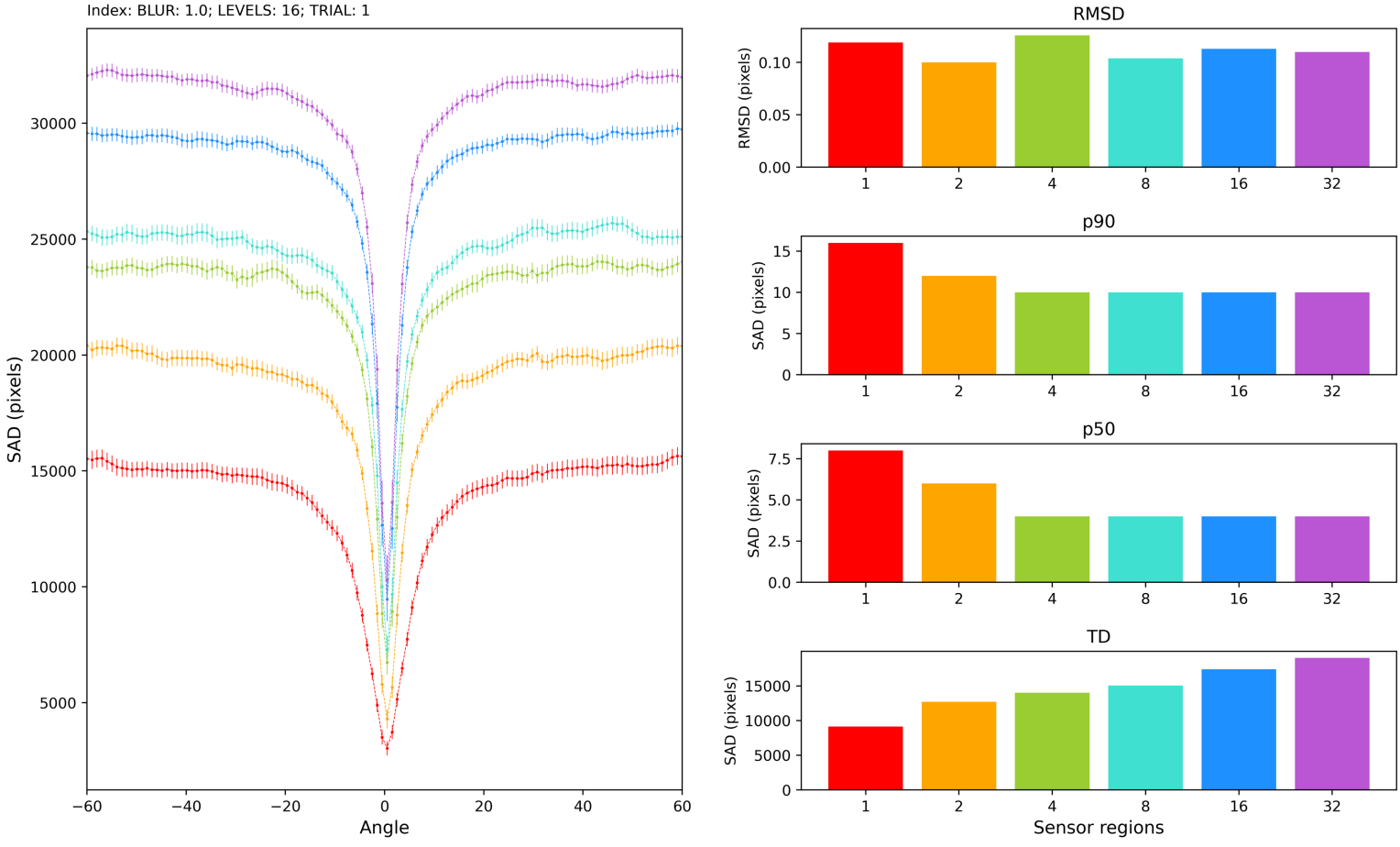

Index: BLUR: 1.0; LEVELS: 16; TRIAL: 0
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
40
20
0
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions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SAD (pixels)
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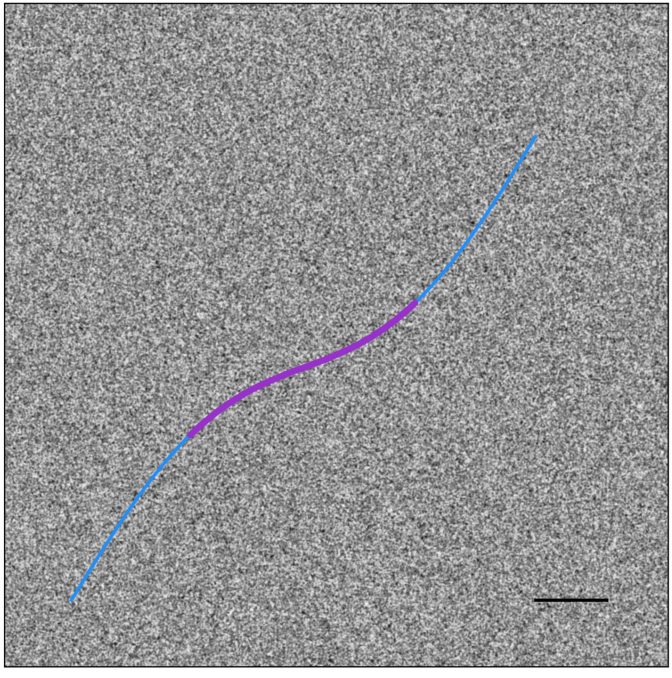
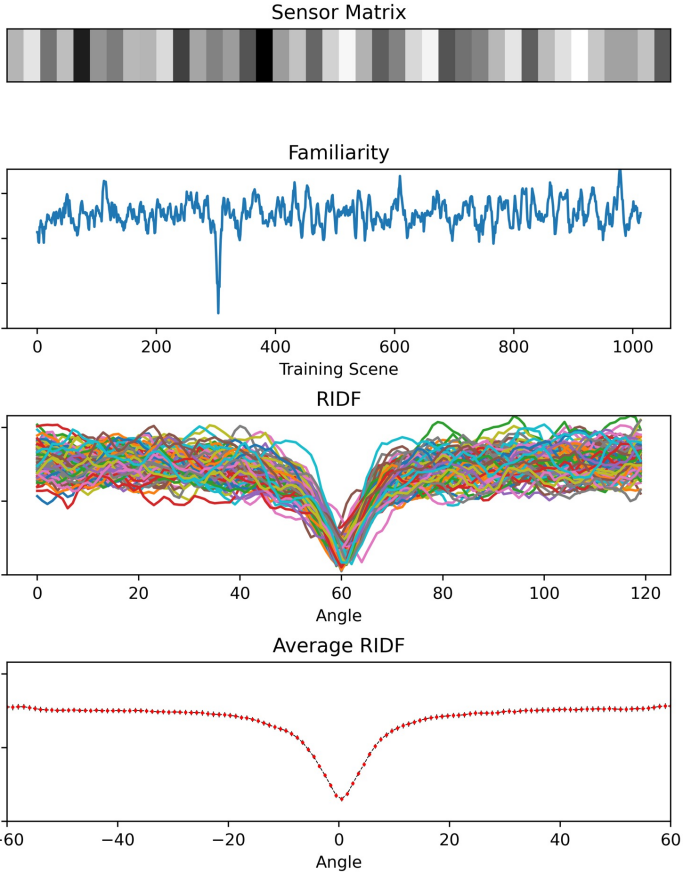
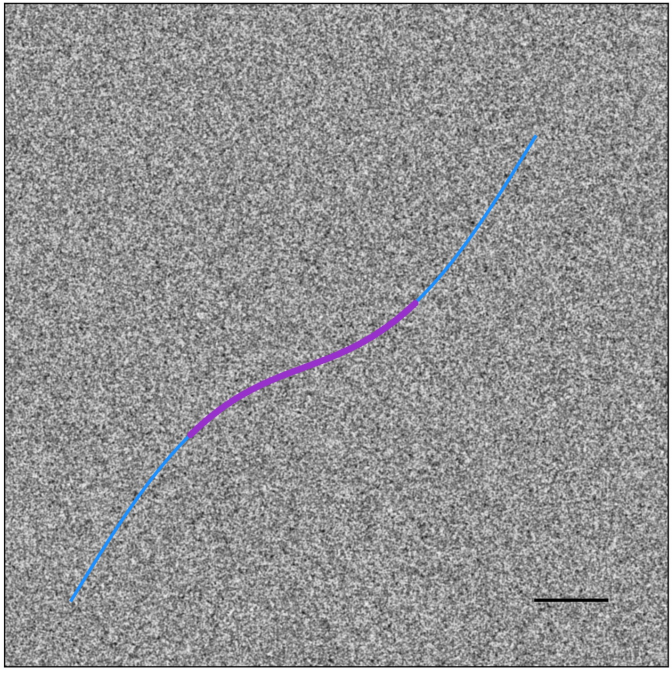
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

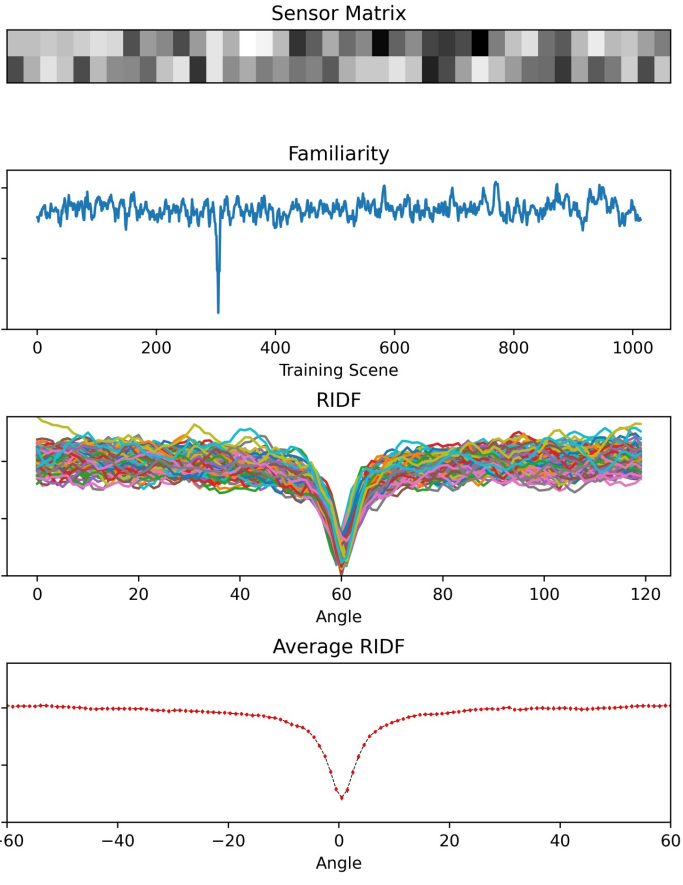




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

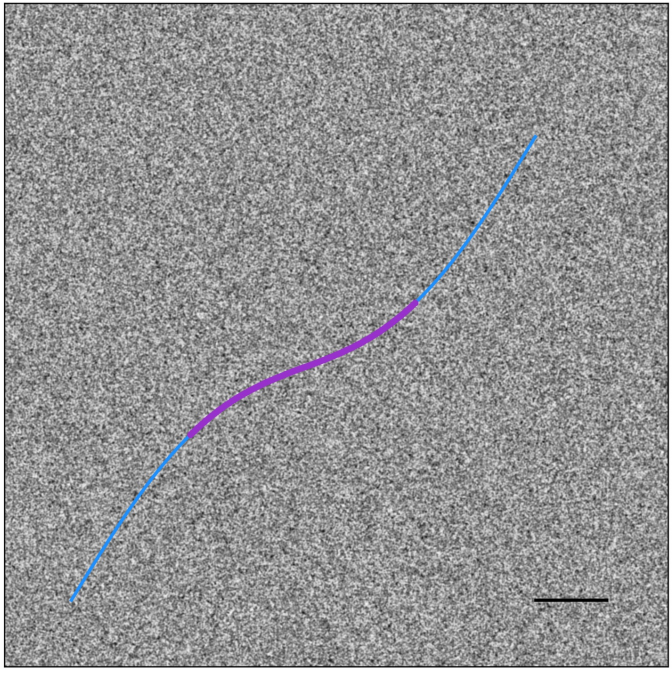
Navigation stats: RMSD error: 47.40; RMSD/dist: 0.119; TD: 9144; p90: 16; p50: 8; complete: 0

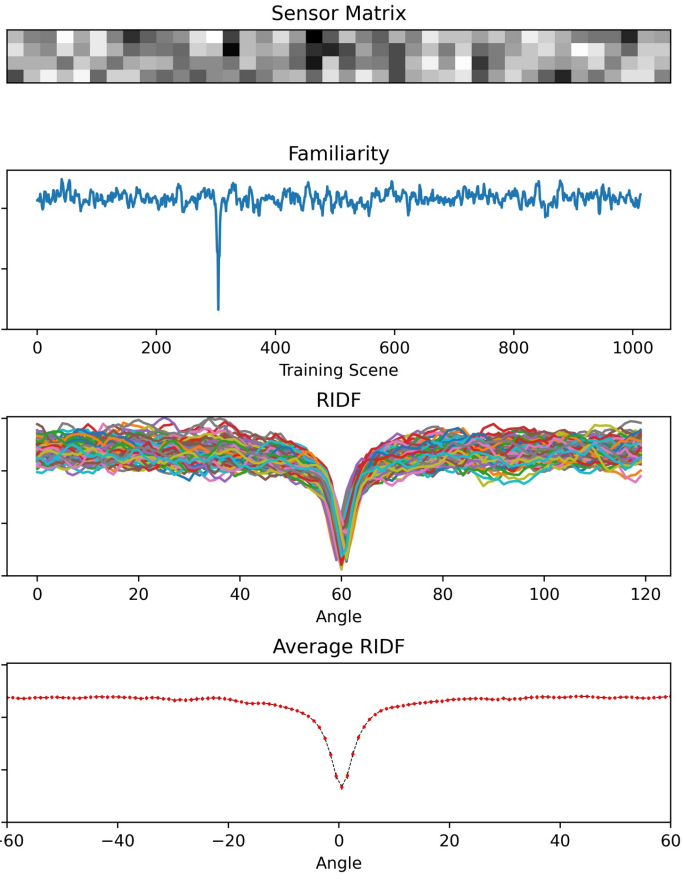




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

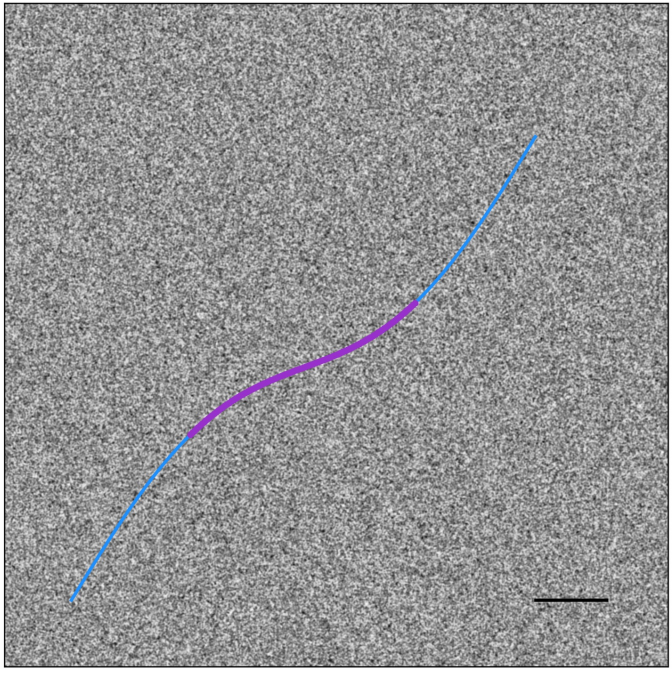
Navigation stats: RMSD error: 39.88; RMSD/dist: 0.100; TD: 12694; p90: 12; p50: 6; complete: 0

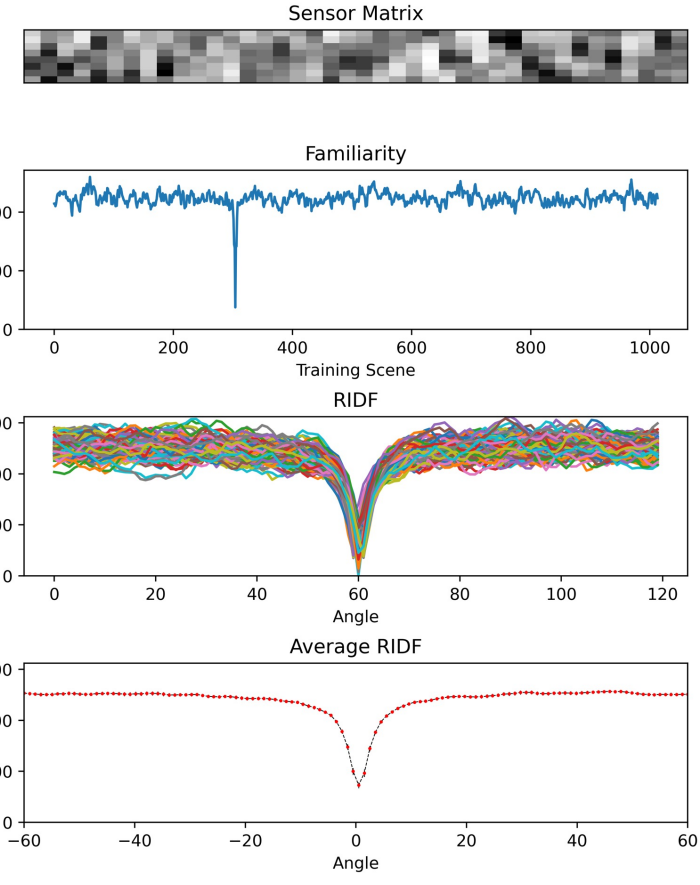




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

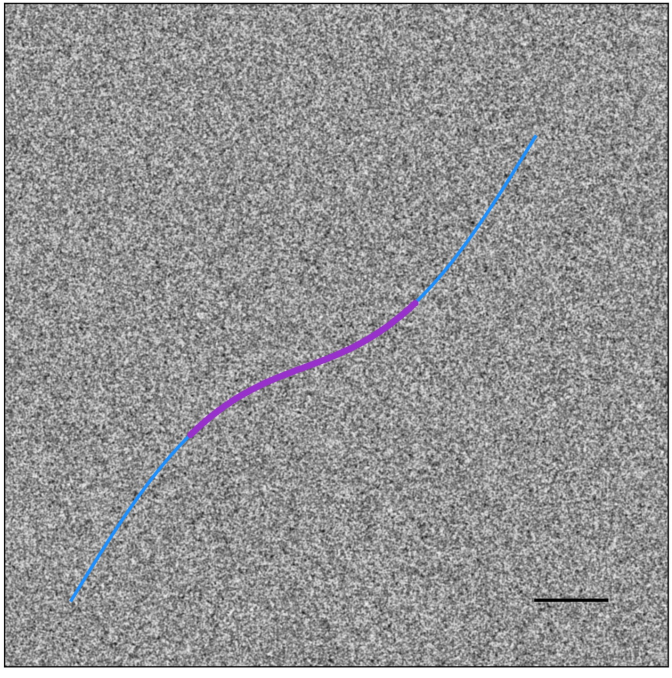
Navigation stats: RMSD error: 50.41; RMSD/dist: 0.126; TD: 13999; p90: 10; p50: 4; complete: 0

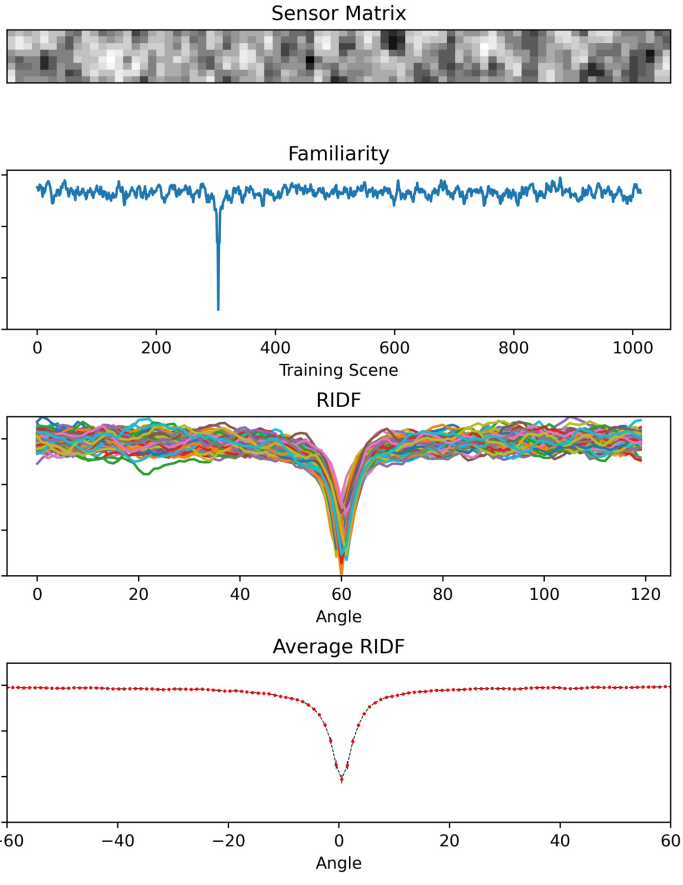




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

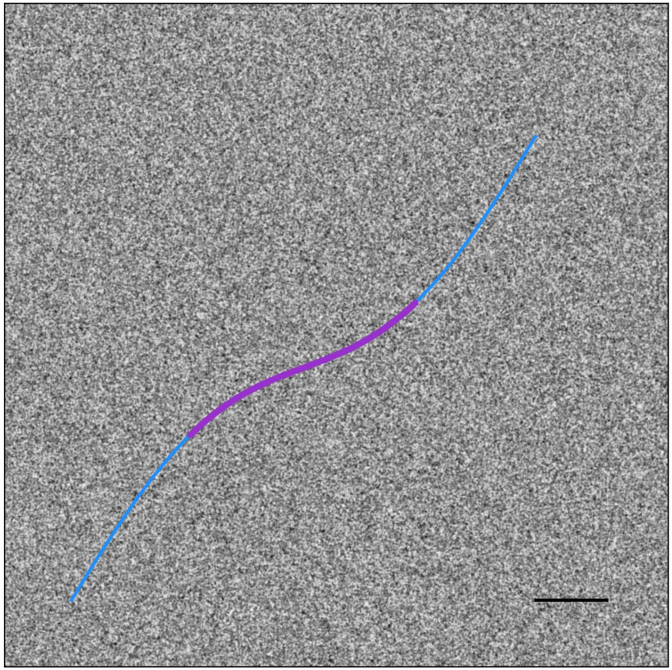
Navigation stats: RMSD error: 41.72; RMSD/dist: 0.104; TD: 15050; p90: 10; p50: 4; complete: 0

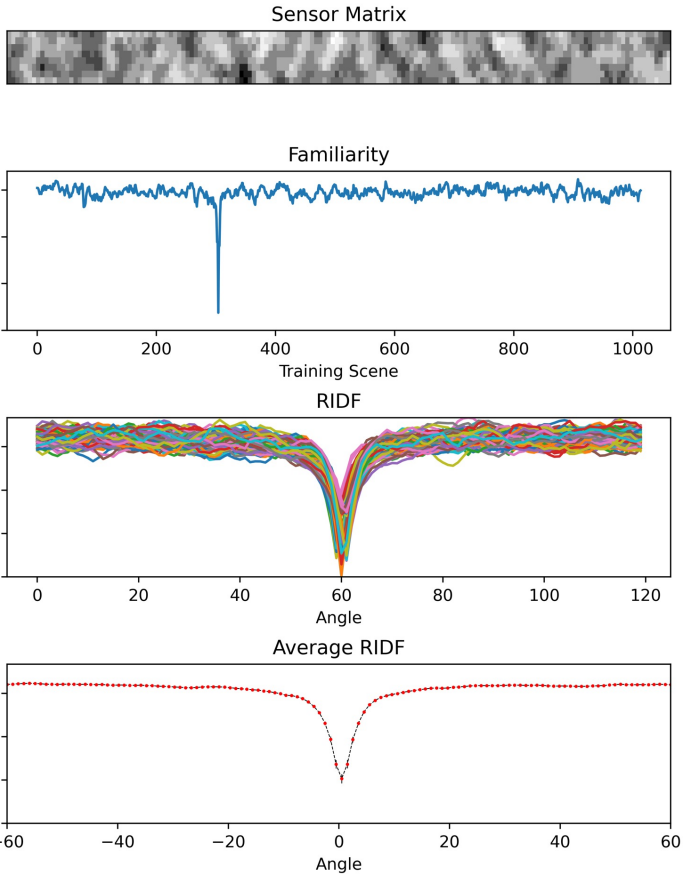




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

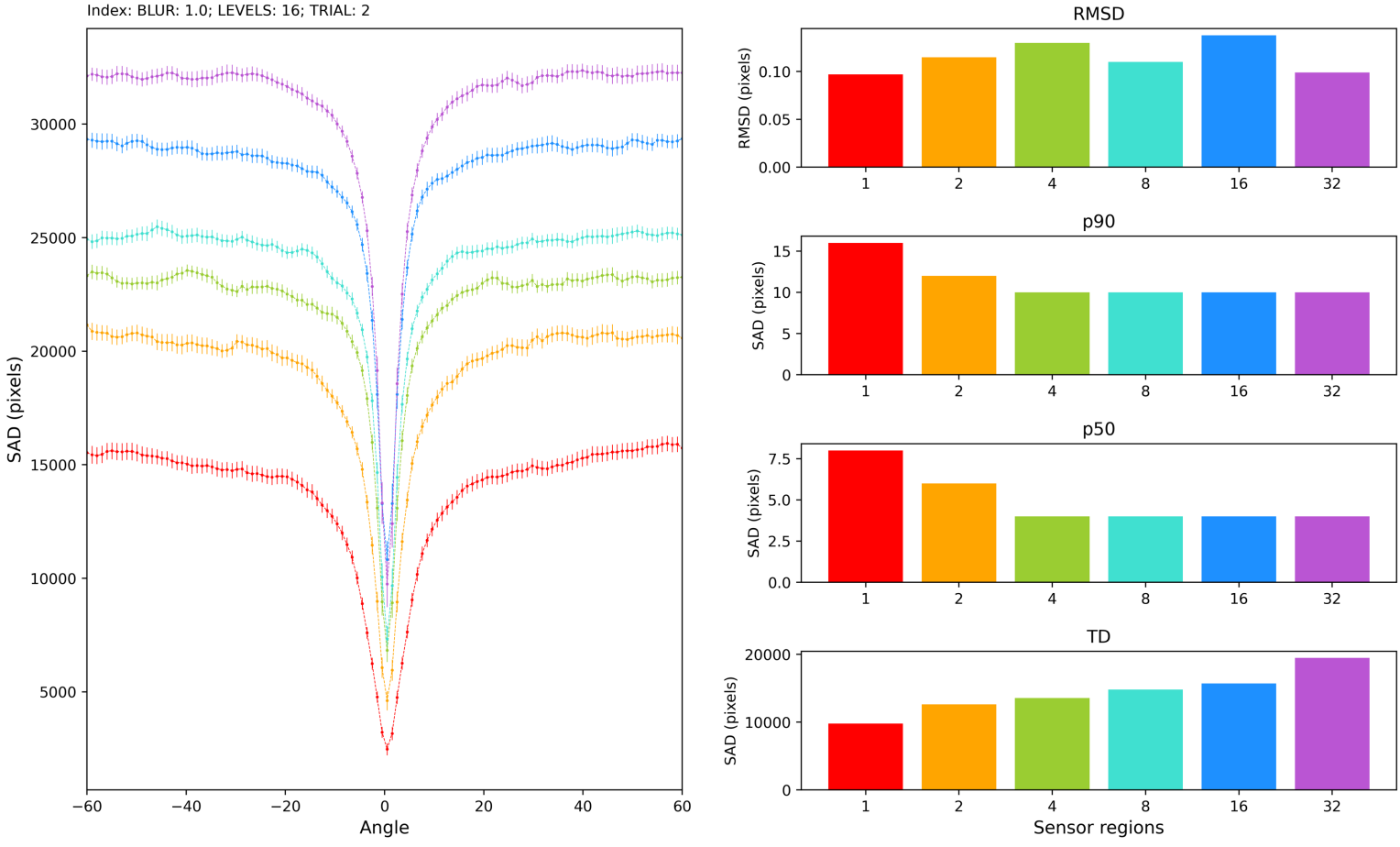
Navigation stats: RMSD error: 45.30; RMSD/dist: 0.113; TD: 17410; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 44.17; RMSD/dist: 0.110; TD: 19026; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 16; TRIAL: 2
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25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
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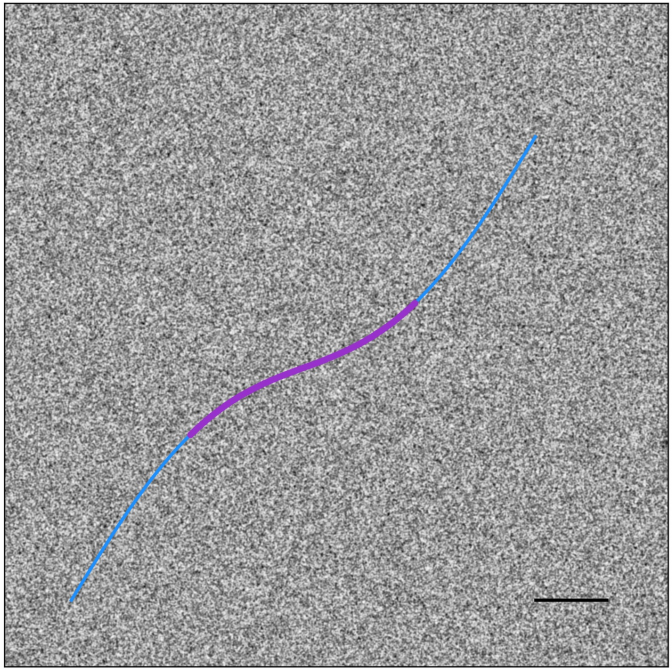
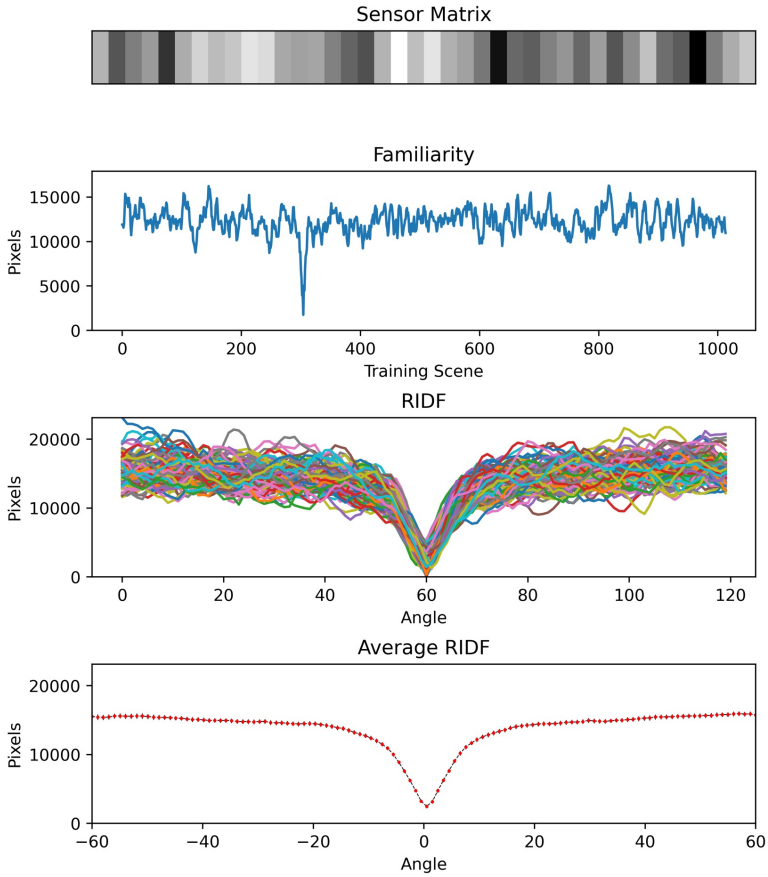
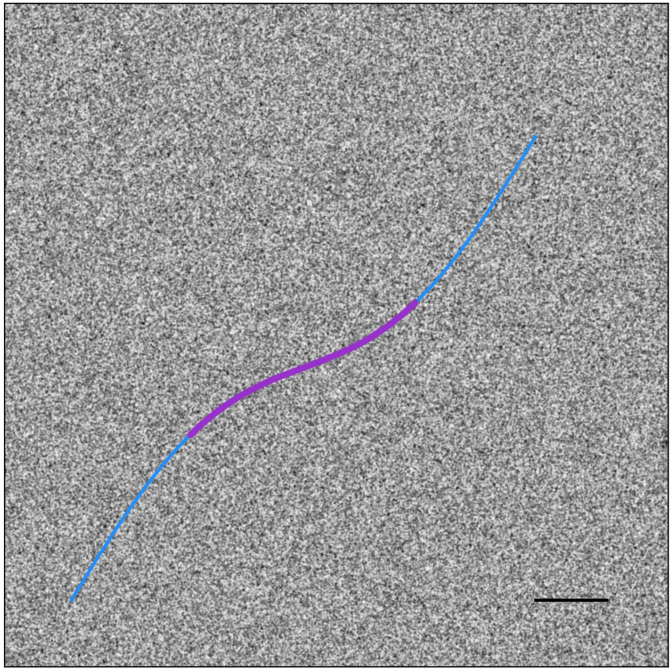
10000
0
Sensor regions

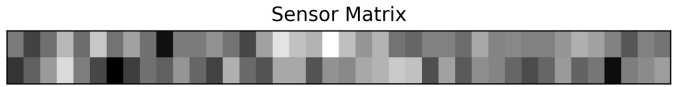


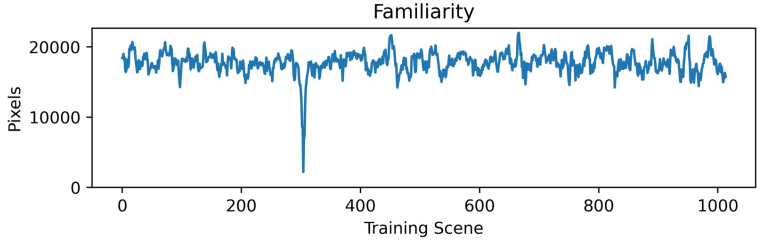


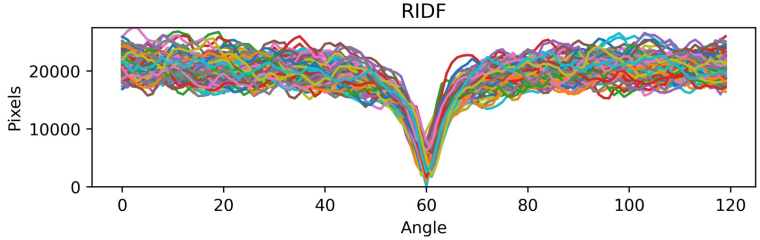
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

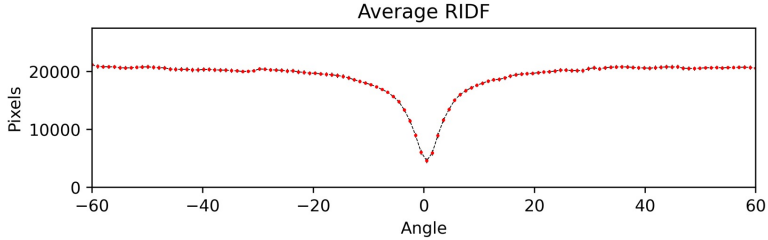
Navigation stats: RMSD error: 38.78; RMSD/dist: 0.097; TD: 9794; p90: 16; p50: 8; complete: 0





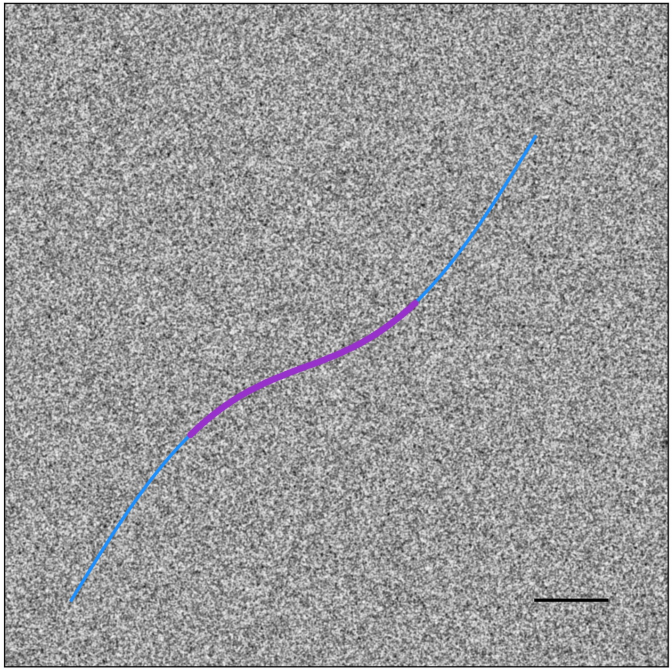


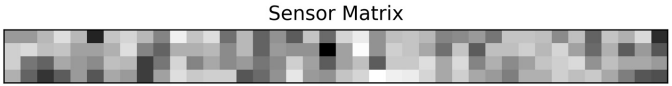


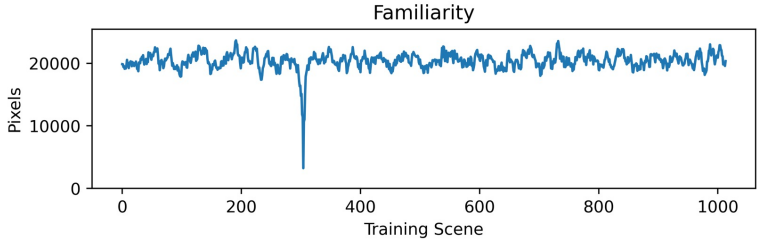


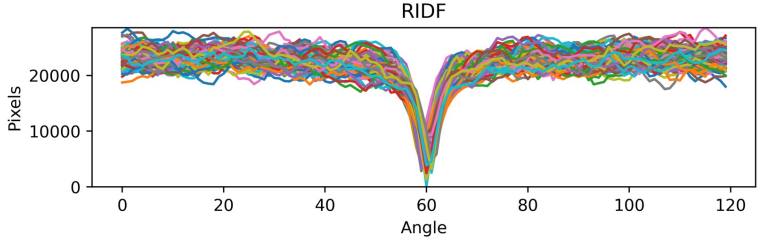
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

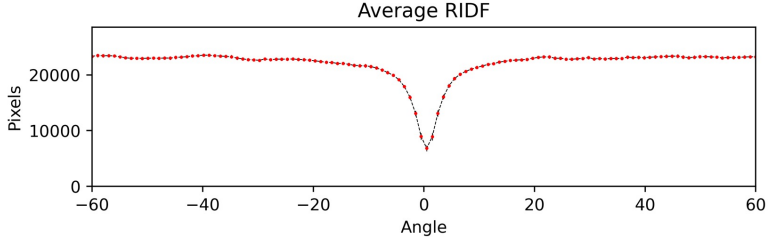
Navigation stats: RMSD error: 45.93; RMSD/dist: 0.115; TD: 12616; p90: 12; p50: 6; complete: 0





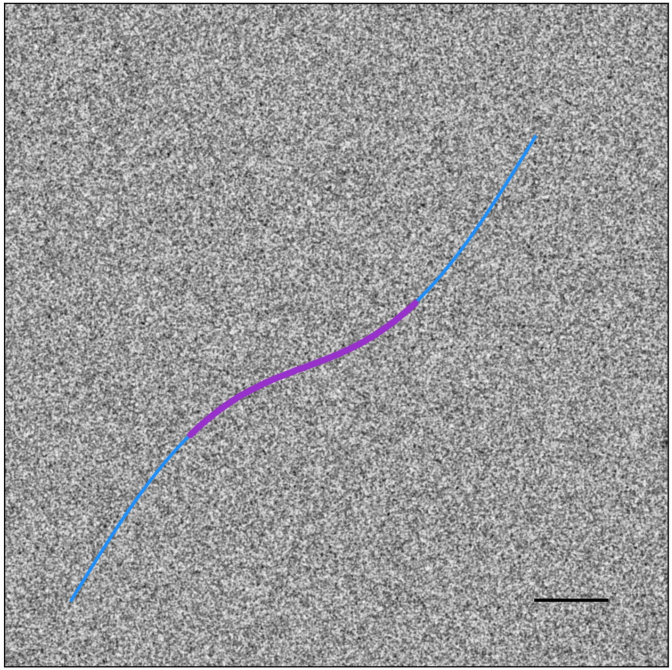


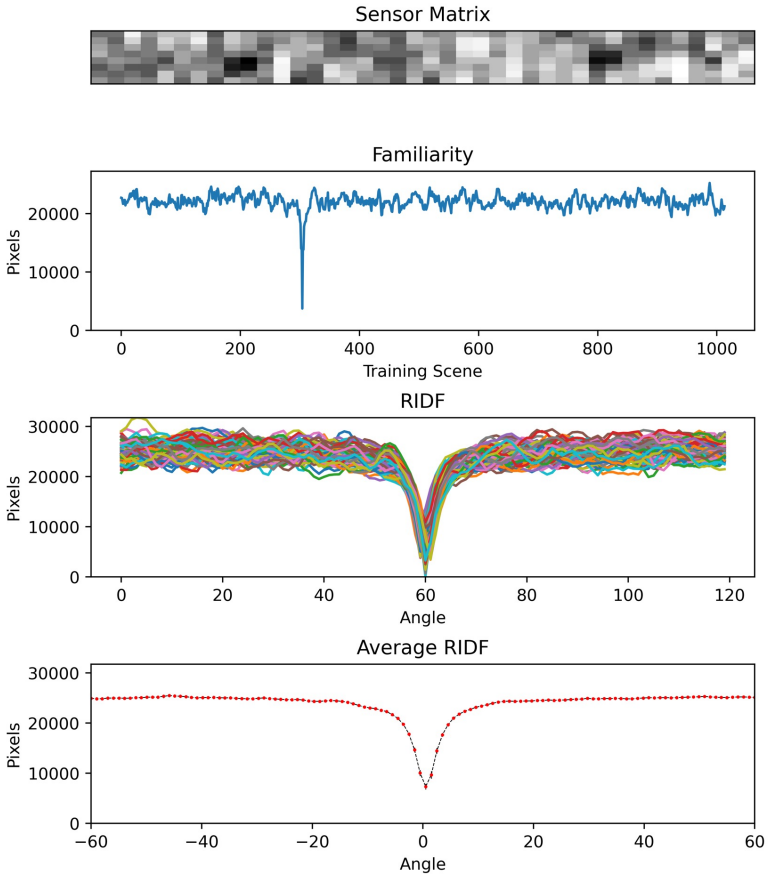




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

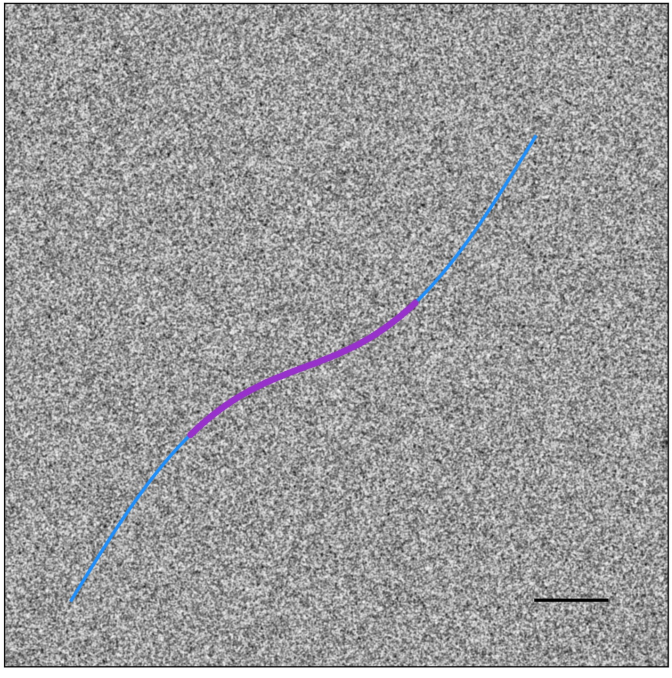
Navigation stats: RMSD error: 52.16; RMSD/dist: 0.130; TD: 13568; p90: 10; p50: 4; complete: 0

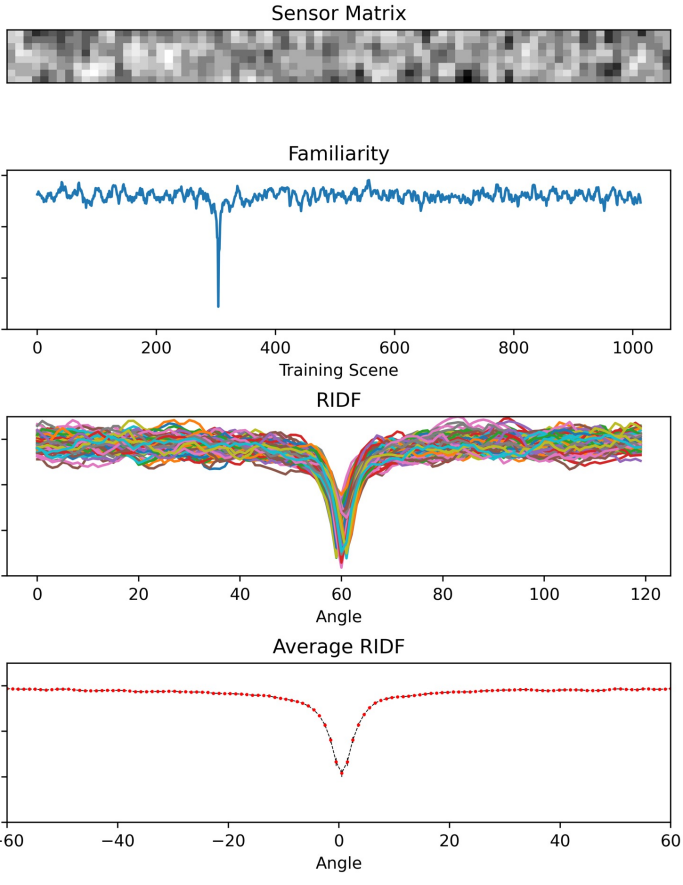




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

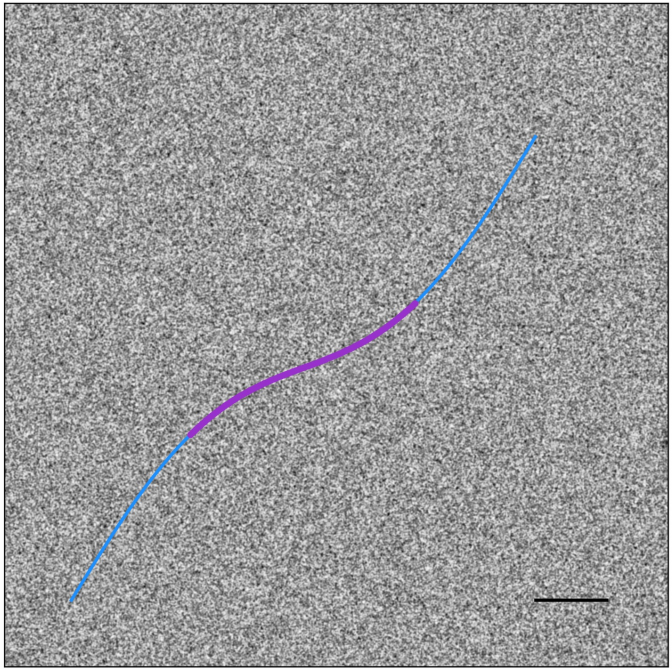
Navigation stats: RMSD error: 43.82; RMSD/dist: 0.110; TD: 14789; p90: 10; p50: 4; complete: 0

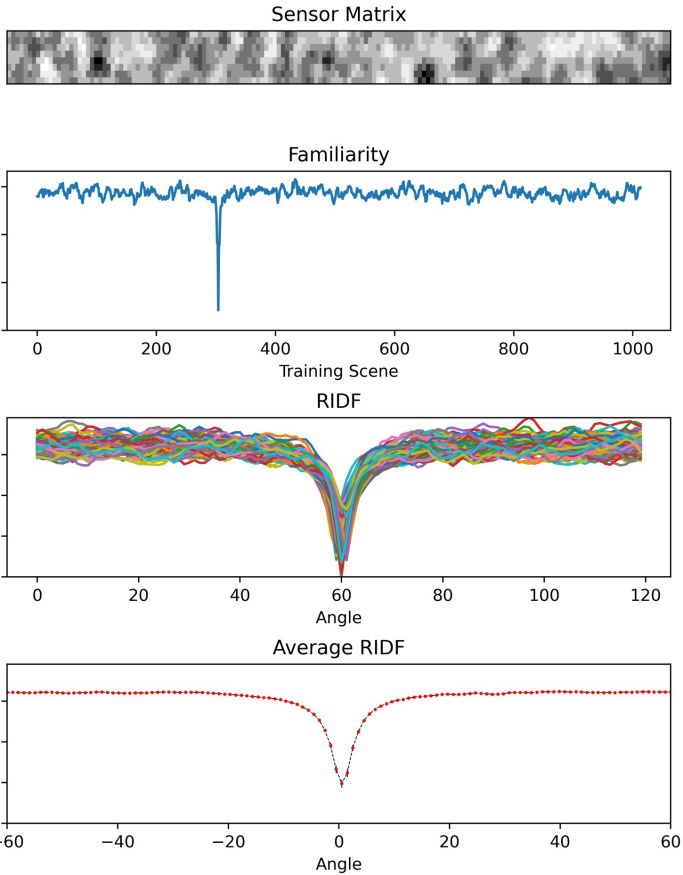




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

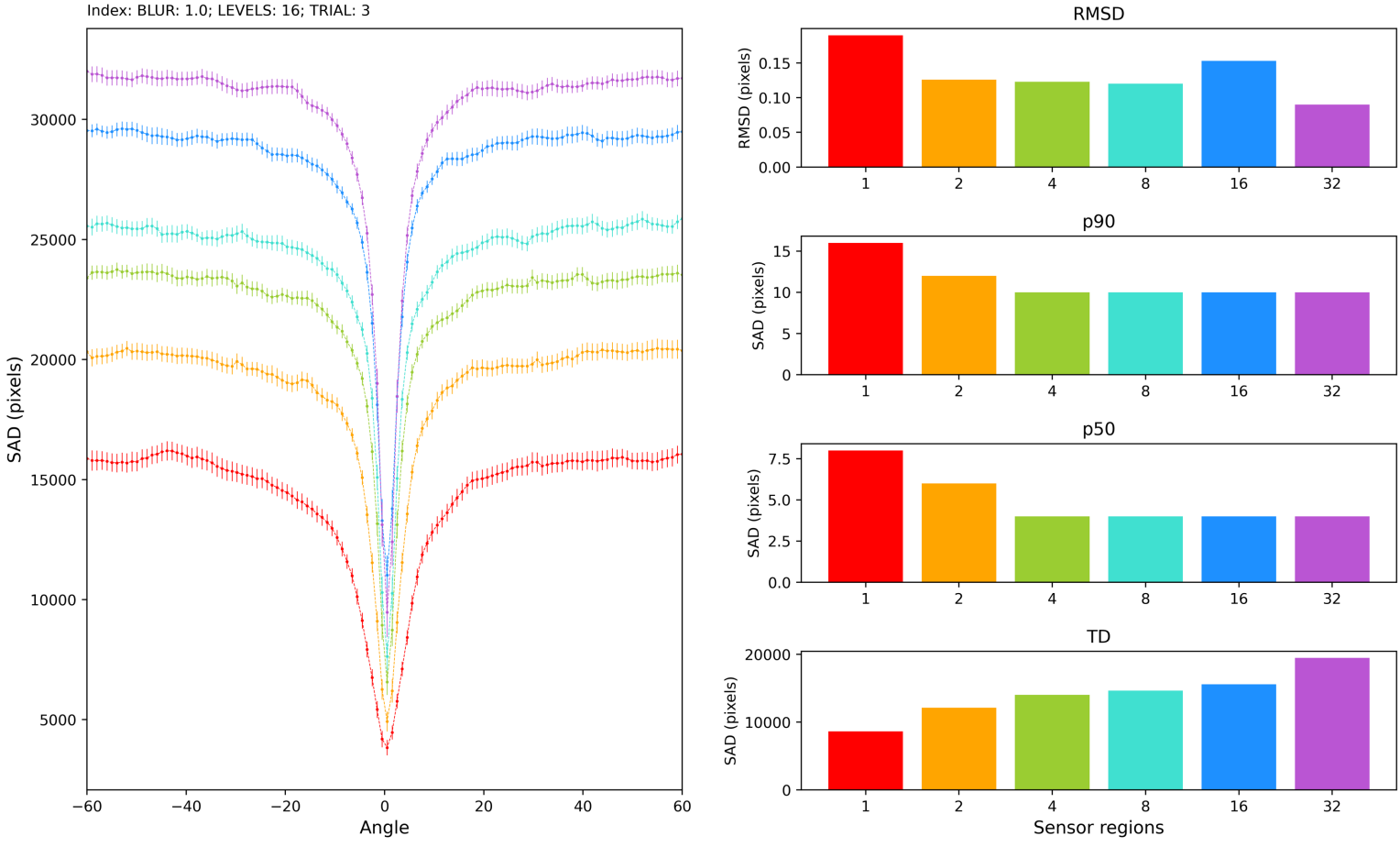
Navigation stats: RMSD error: 55.04; RMSD/dist: 0.138; TD: 15707; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 39.52; RMSD/dist: 0.099; TD: 19462; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 16; TRIAL: 3
SAD (pixels)
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25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
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5.0
2.5
0.0
TD
SAD (pixels)
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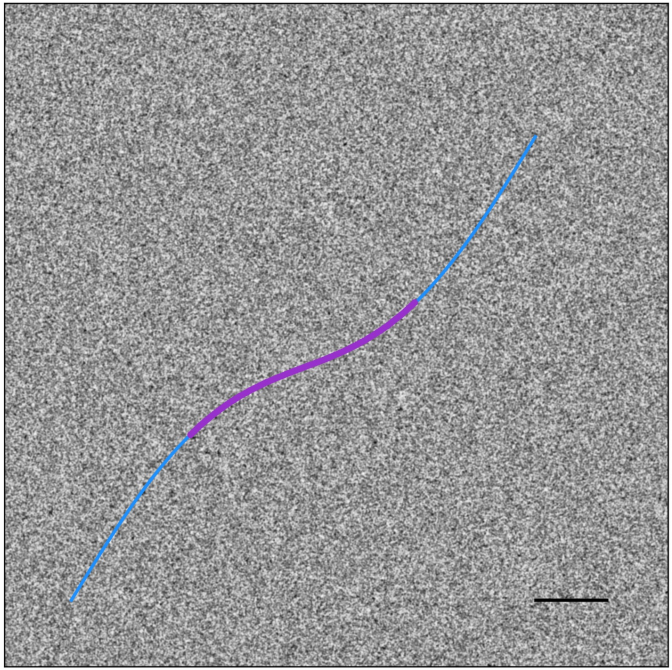
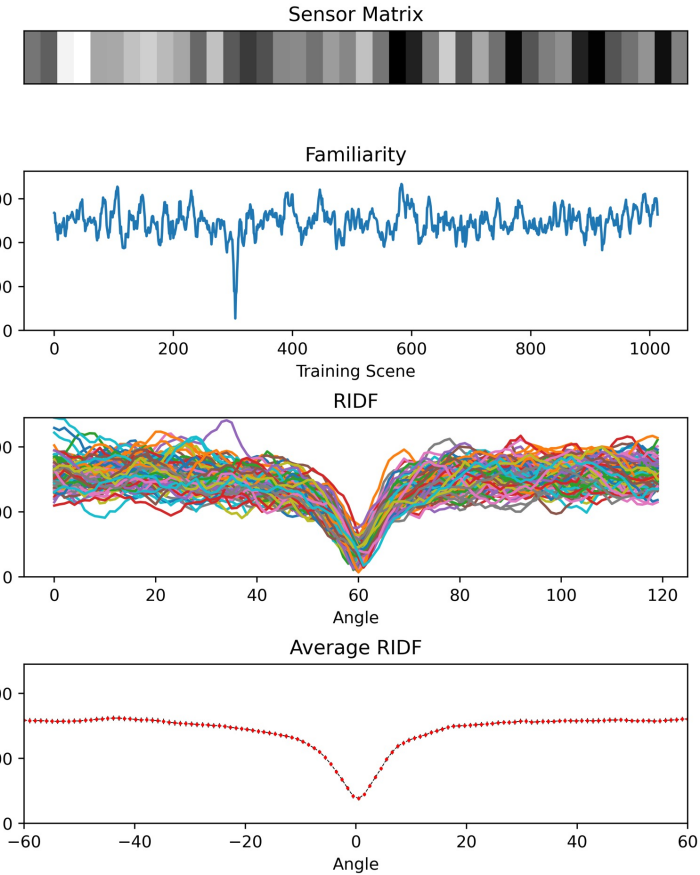
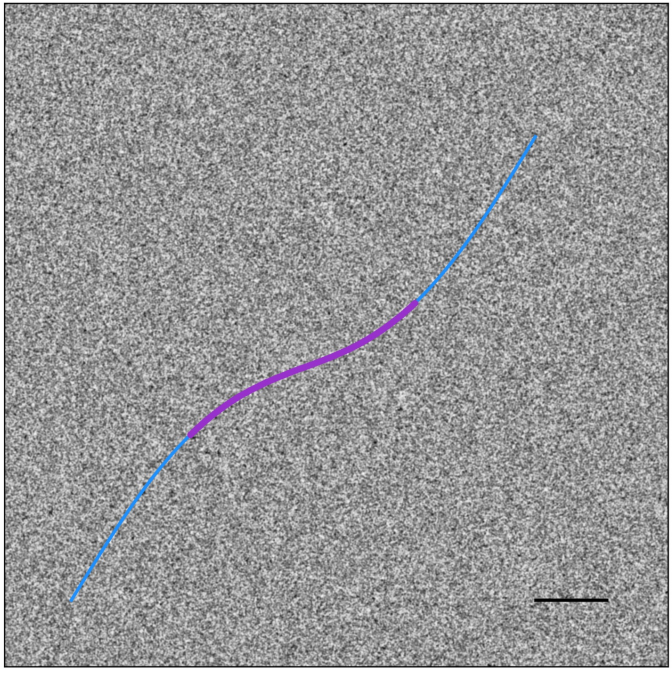
10000
0
Sensor regions

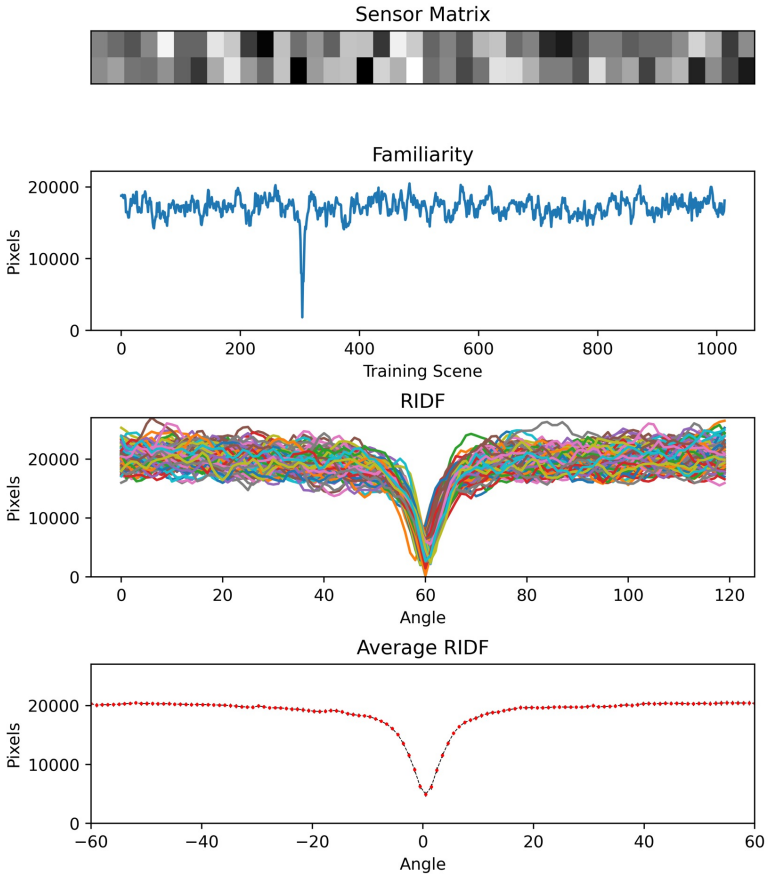




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

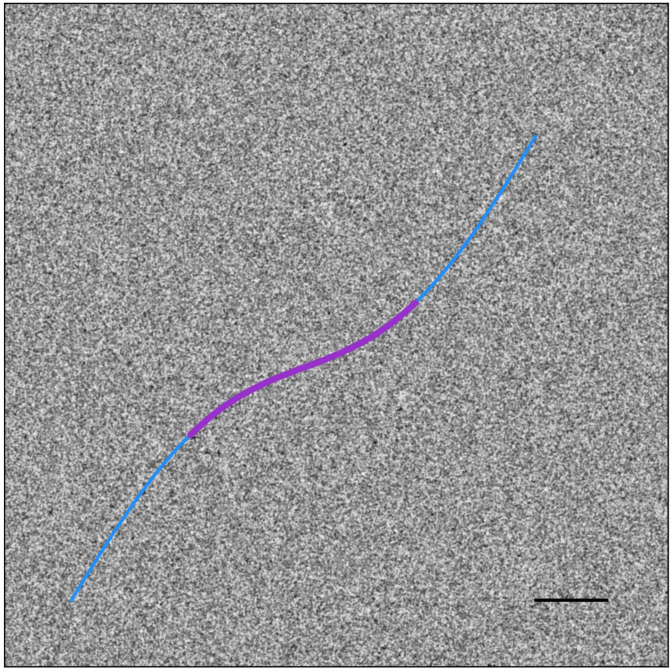
Navigation stats: RMSD error: 76.14; RMSD/dist: 0.190; TD: 8635; p90: 16; p50: 8; complete: 0

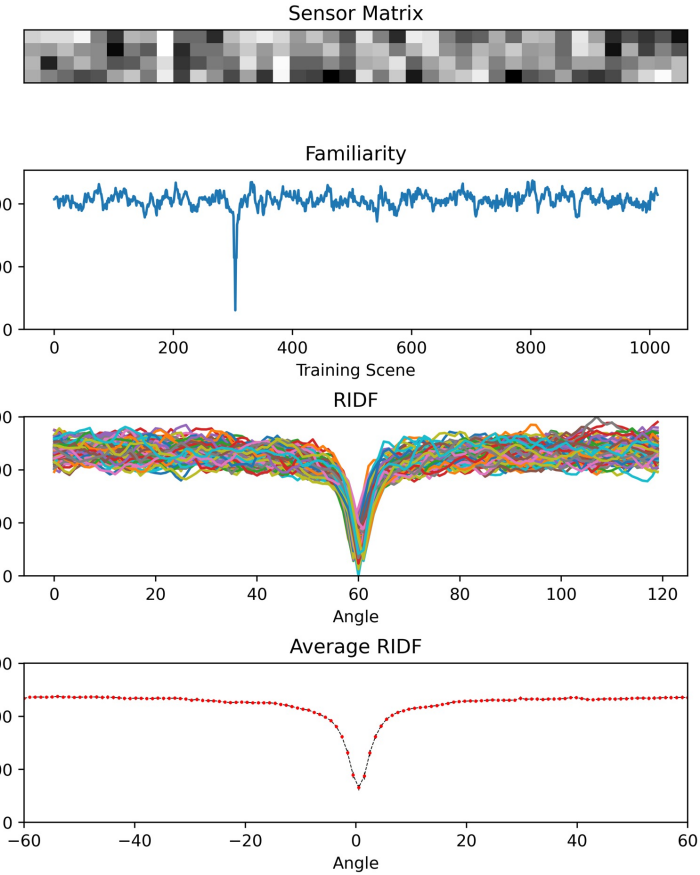




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

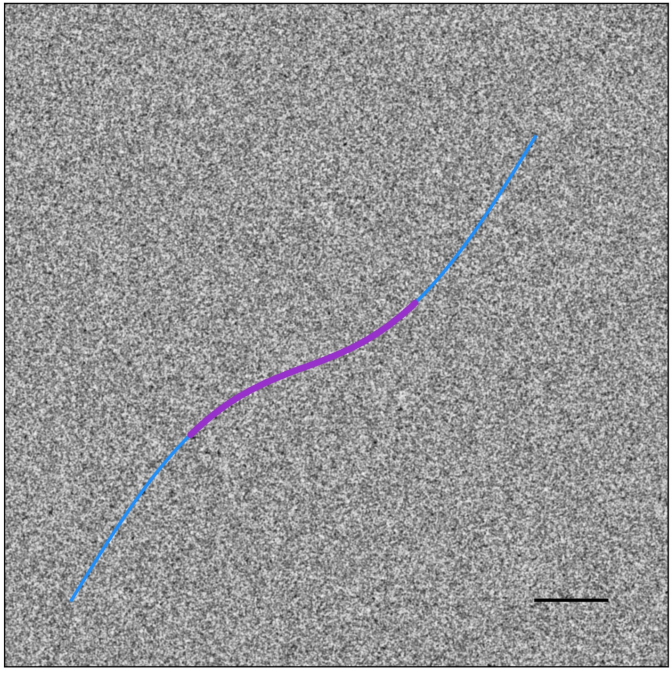
Navigation stats: RMSD error: 50.23; RMSD/dist: 0.126; TD: 12122; p90: 12; p50: 6; complete: 0

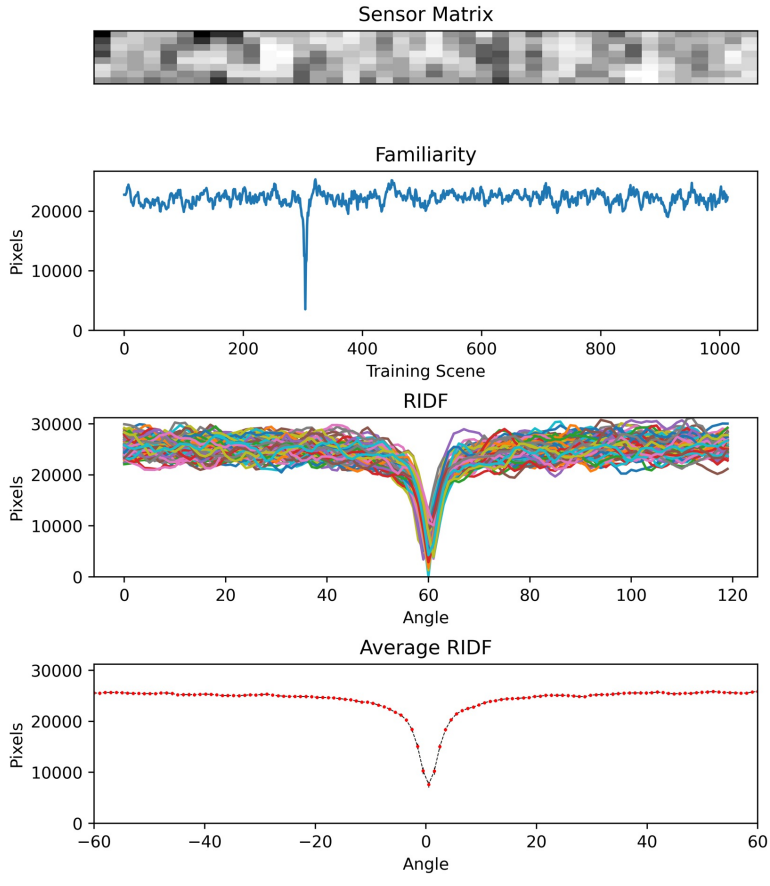




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

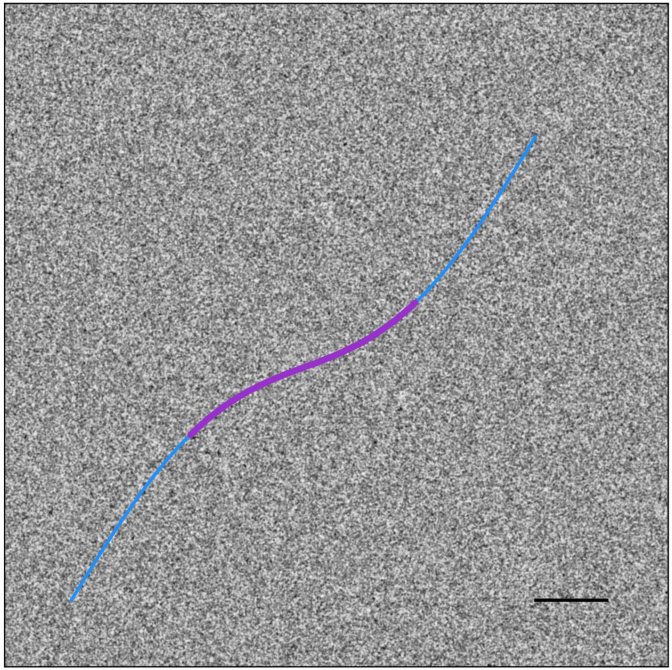
Navigation stats: RMSD error: 49.18; RMSD/dist: 0.123; TD: 14037; p90: 10; p50: 4; complete: 0

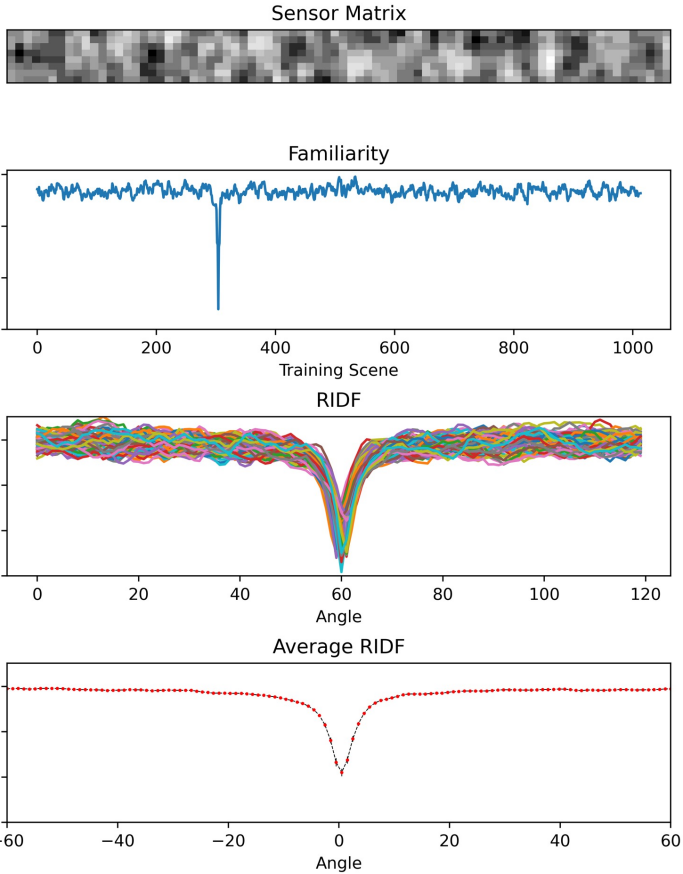




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

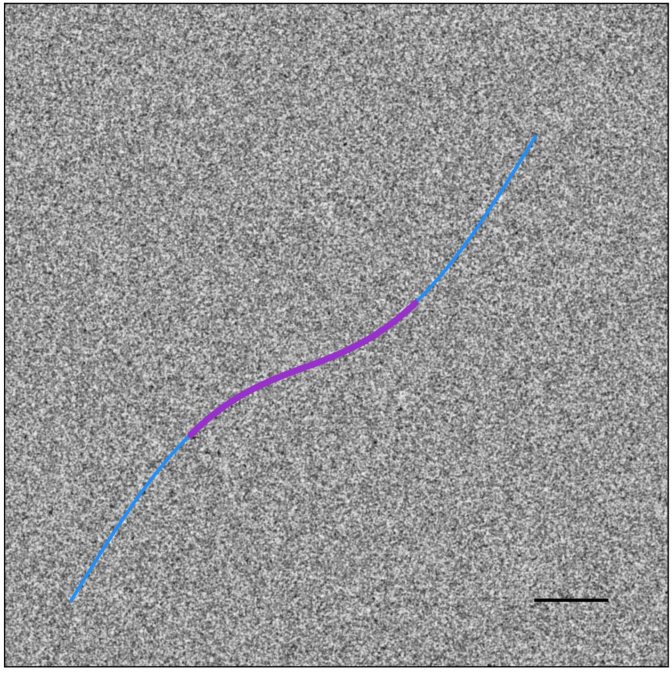
Navigation stats: RMSD error: 48.07; RMSD/dist: 0.120; TD: 14660; p90: 10; p50: 4; complete: 0

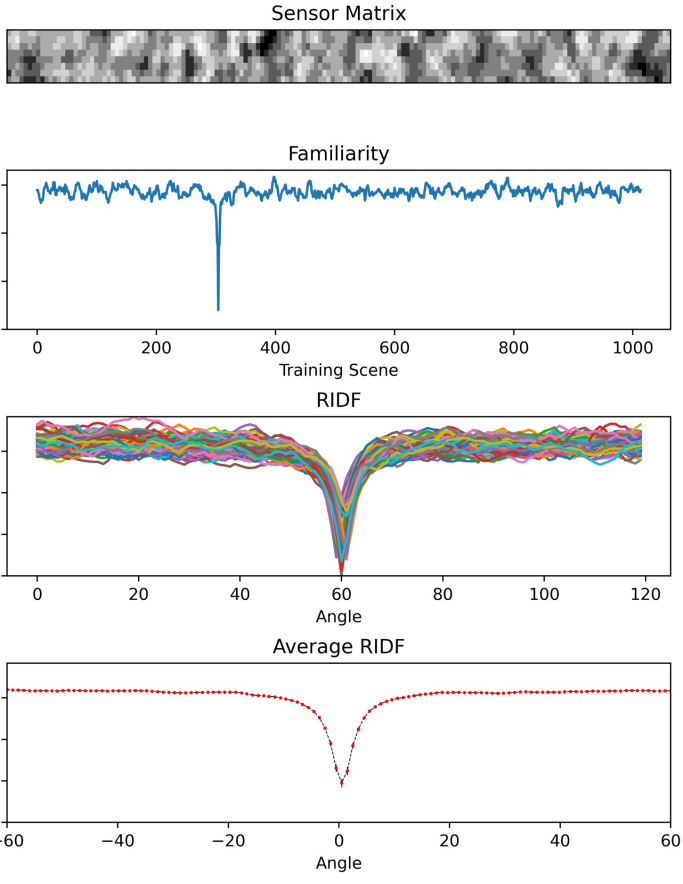




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

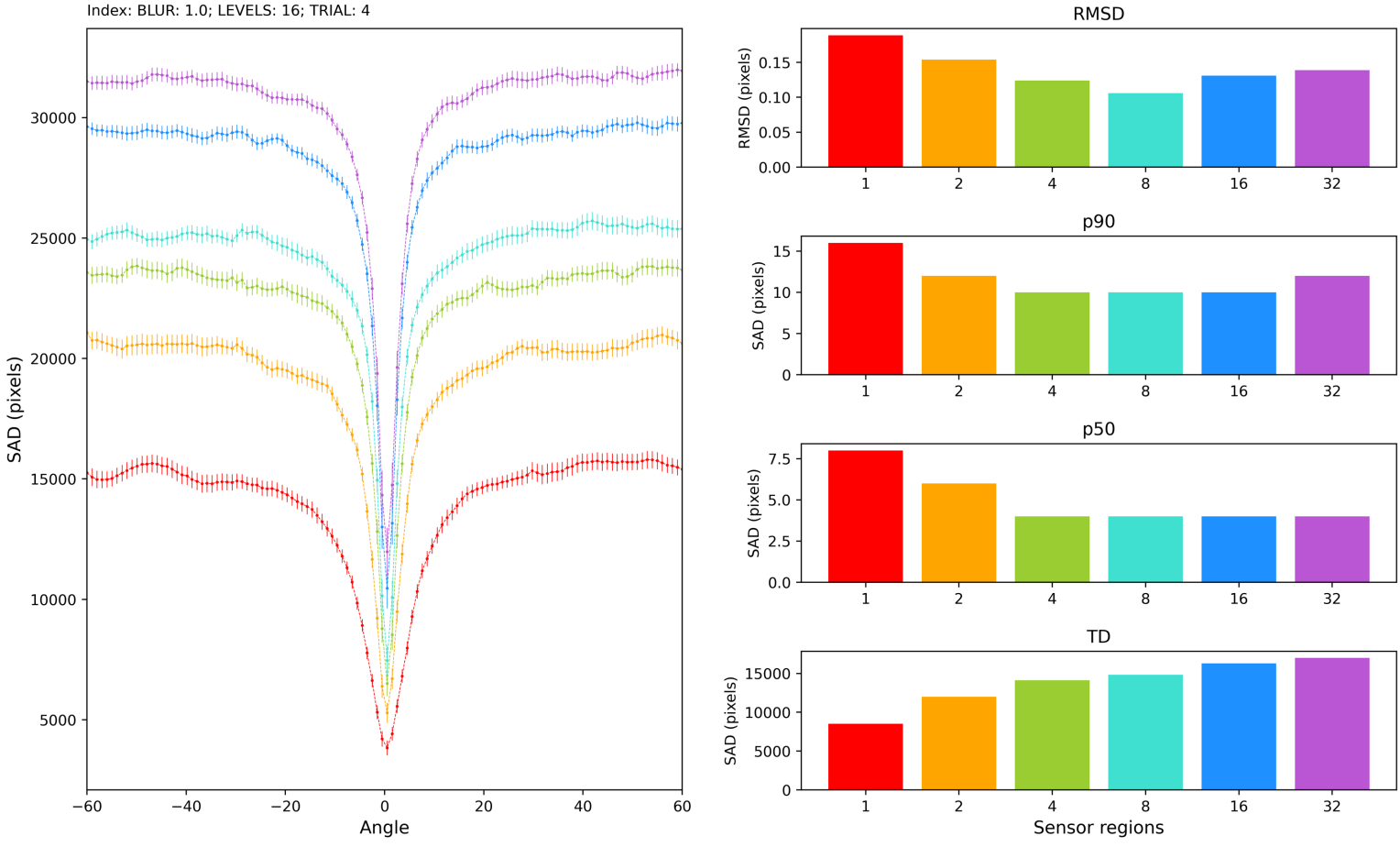
Navigation stats: RMSD error: 61.30; RMSD/dist: 0.153; TD: 15577; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 35.94; RMSD/dist: 0.090; TD: 19466; p90: 10; p50: 4; complete: 0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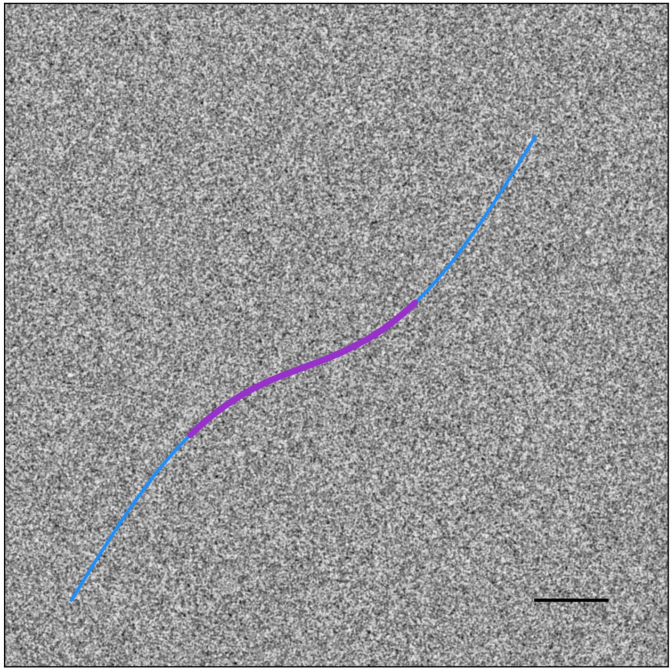
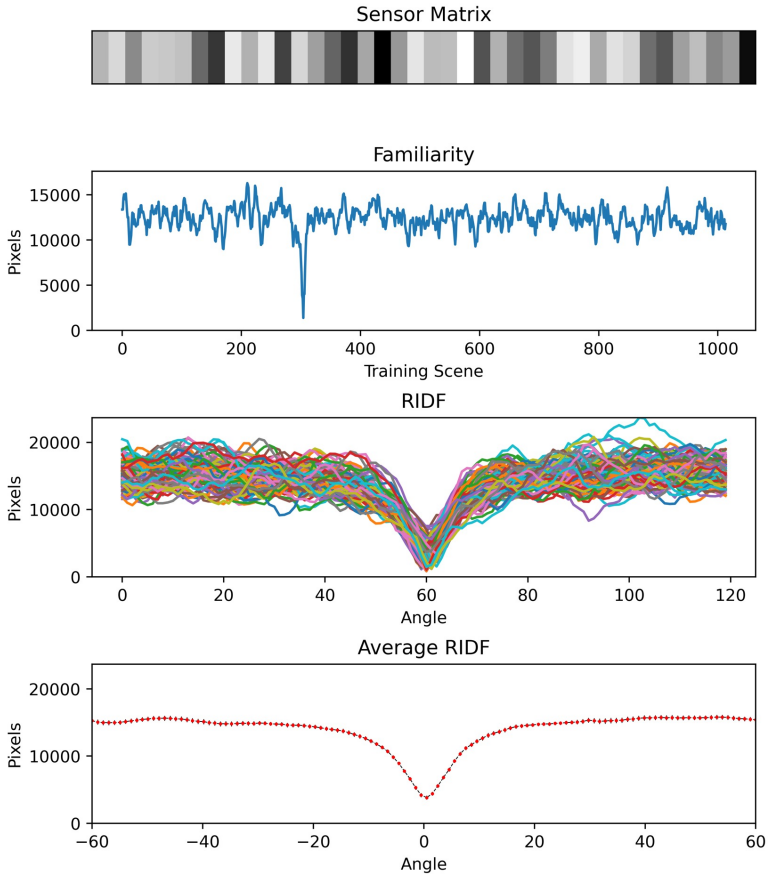
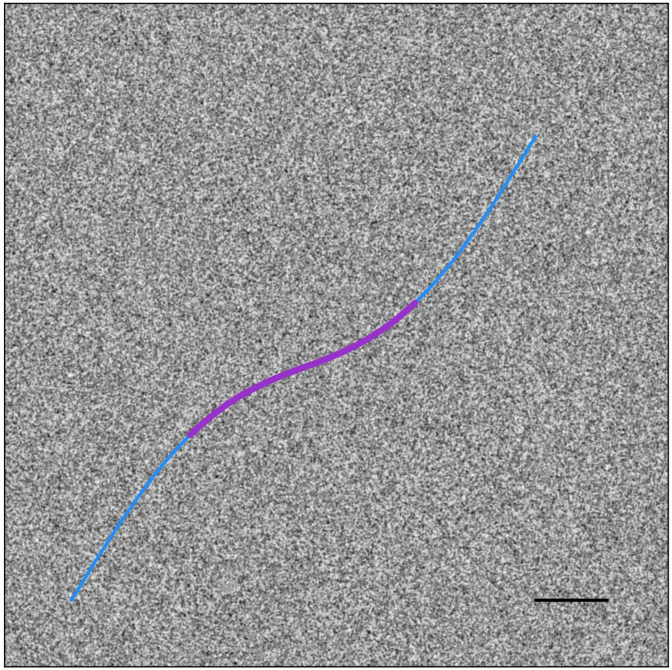
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

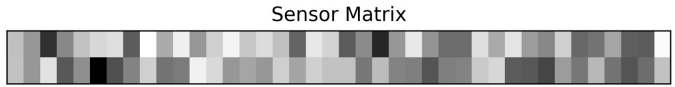


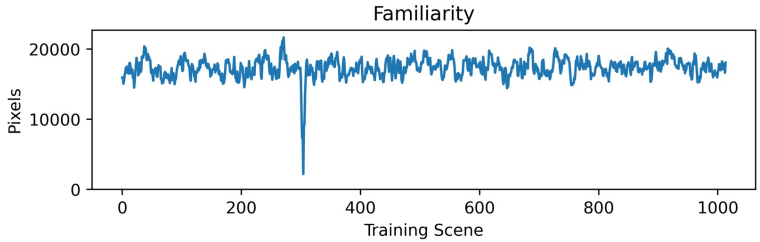


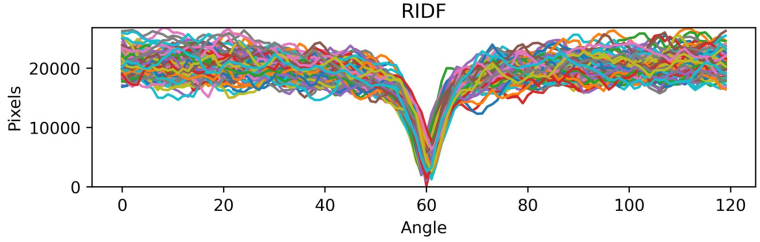
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

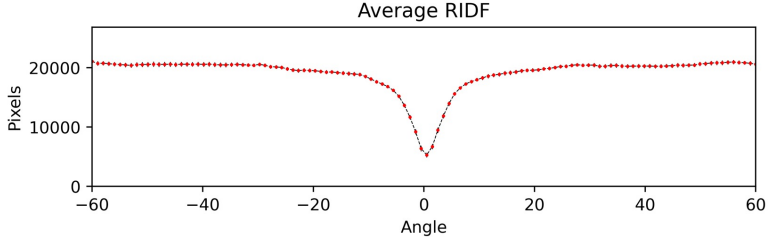
Navigation stats: RMSD error: 75.41; RMSD/dist: 0.189; TD: 8505; p90: 16; p50: 8; complete: 0





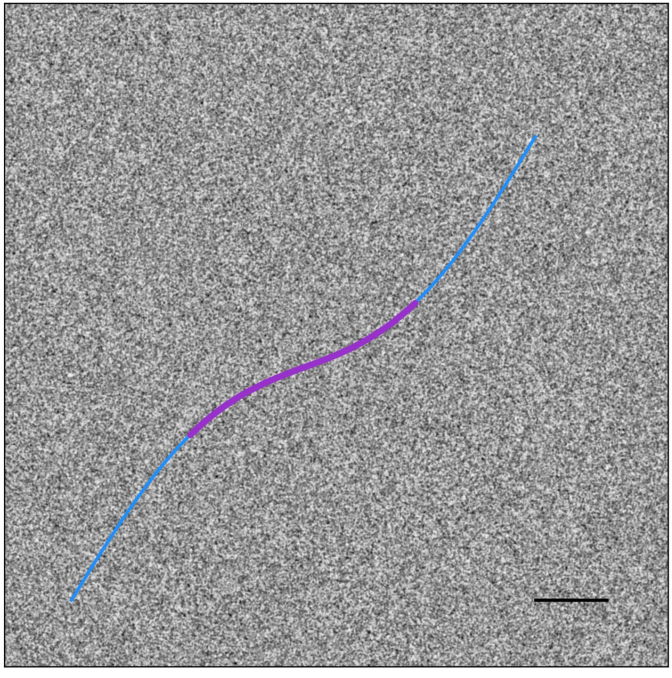


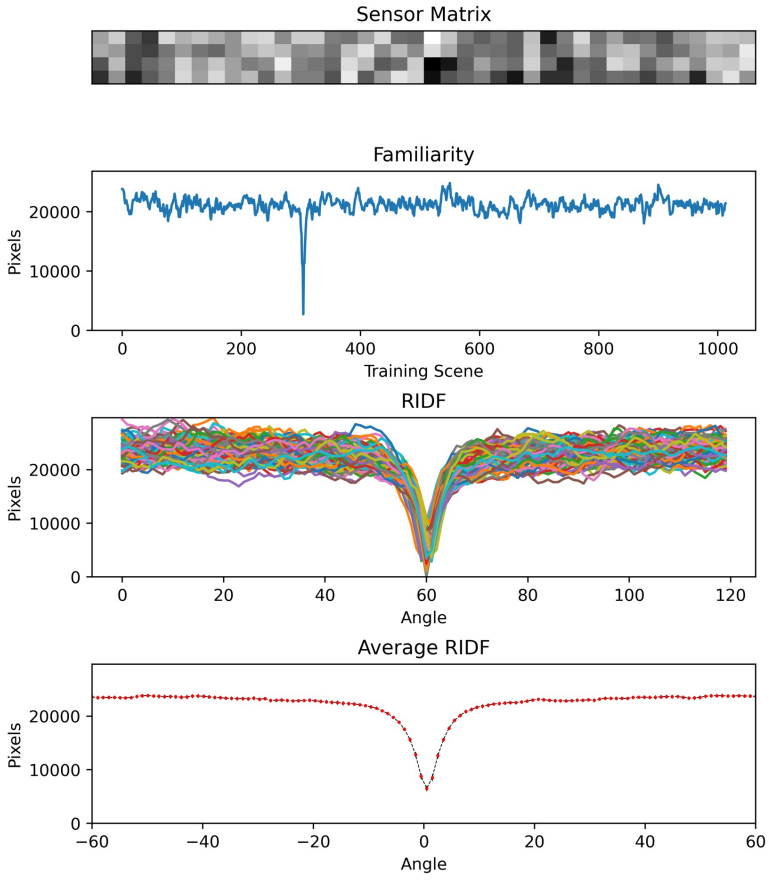




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

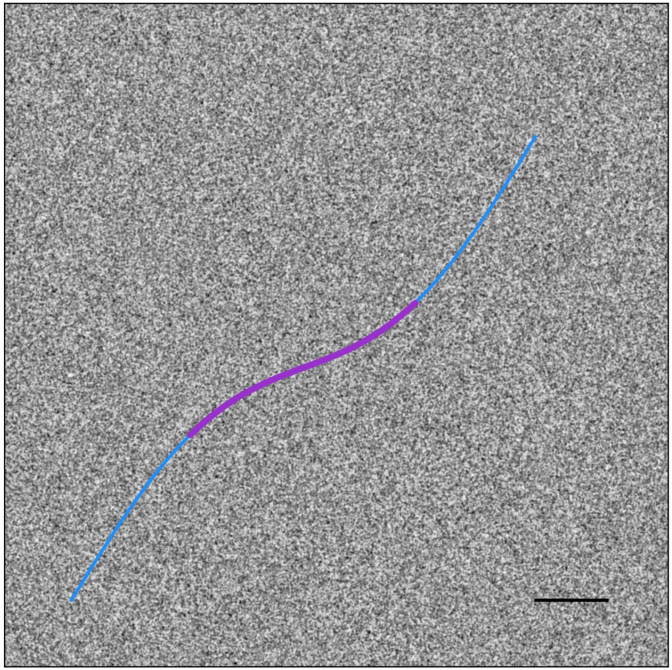
Navigation stats: RMSD error: 61.76; RMSD/dist: 0.154; TD: 11982; p90: 12; p50: 6; complete: 0

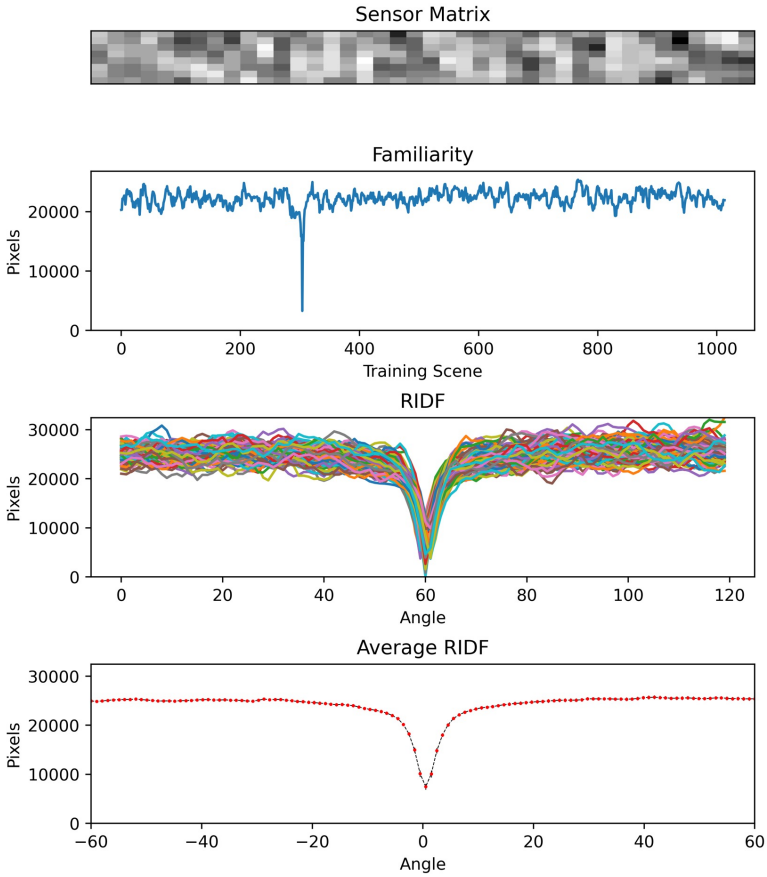




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

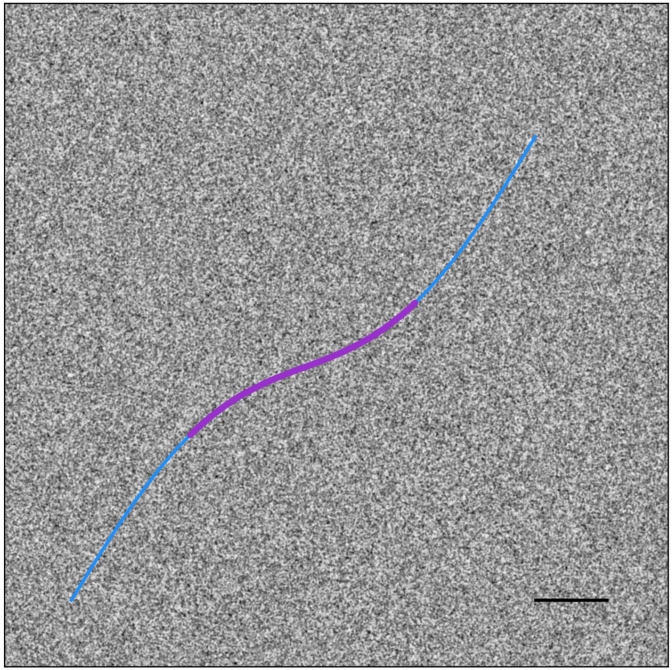
Navigation stats: RMSD error: 49.46; RMSD/dist: 0.124; TD: 14104; p90: 10; p50: 4; complete: 0

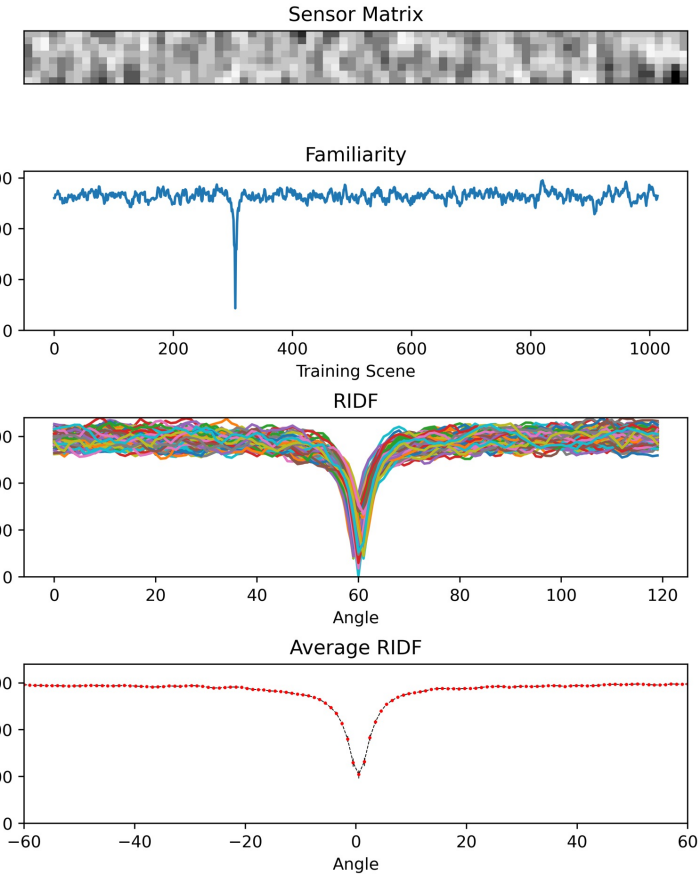




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

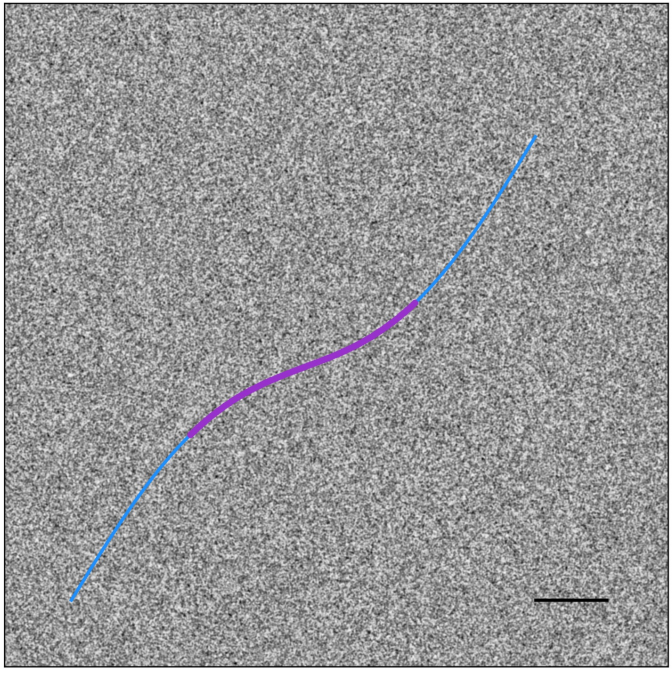
Navigation stats: RMSD error: 42.49; RMSD/dist: 0.106; TD: 14836; p90: 10; p50: 4; complete: 0

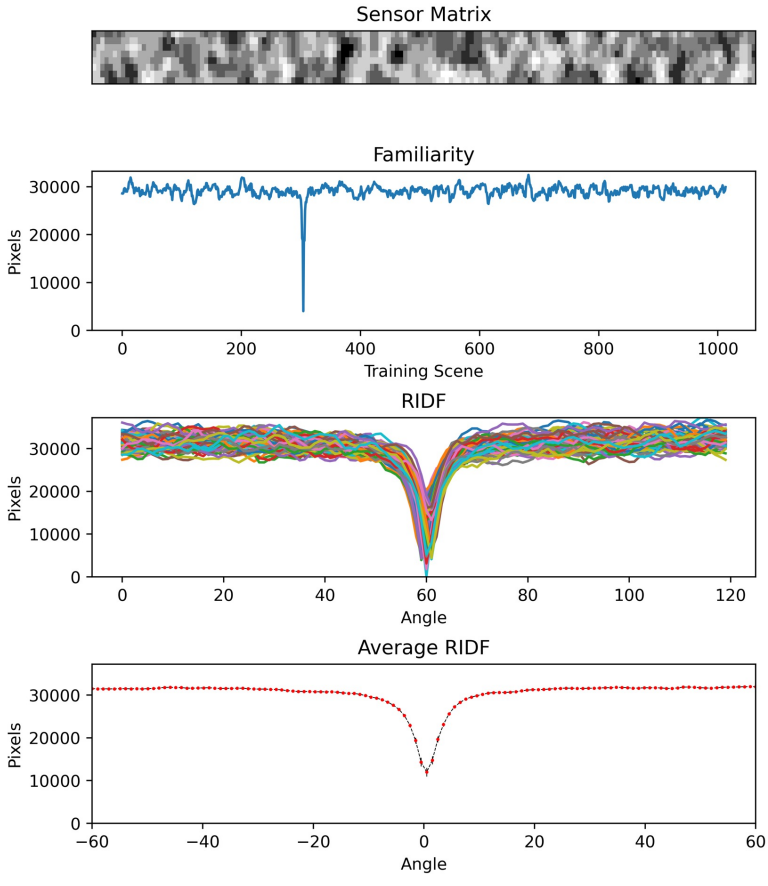




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

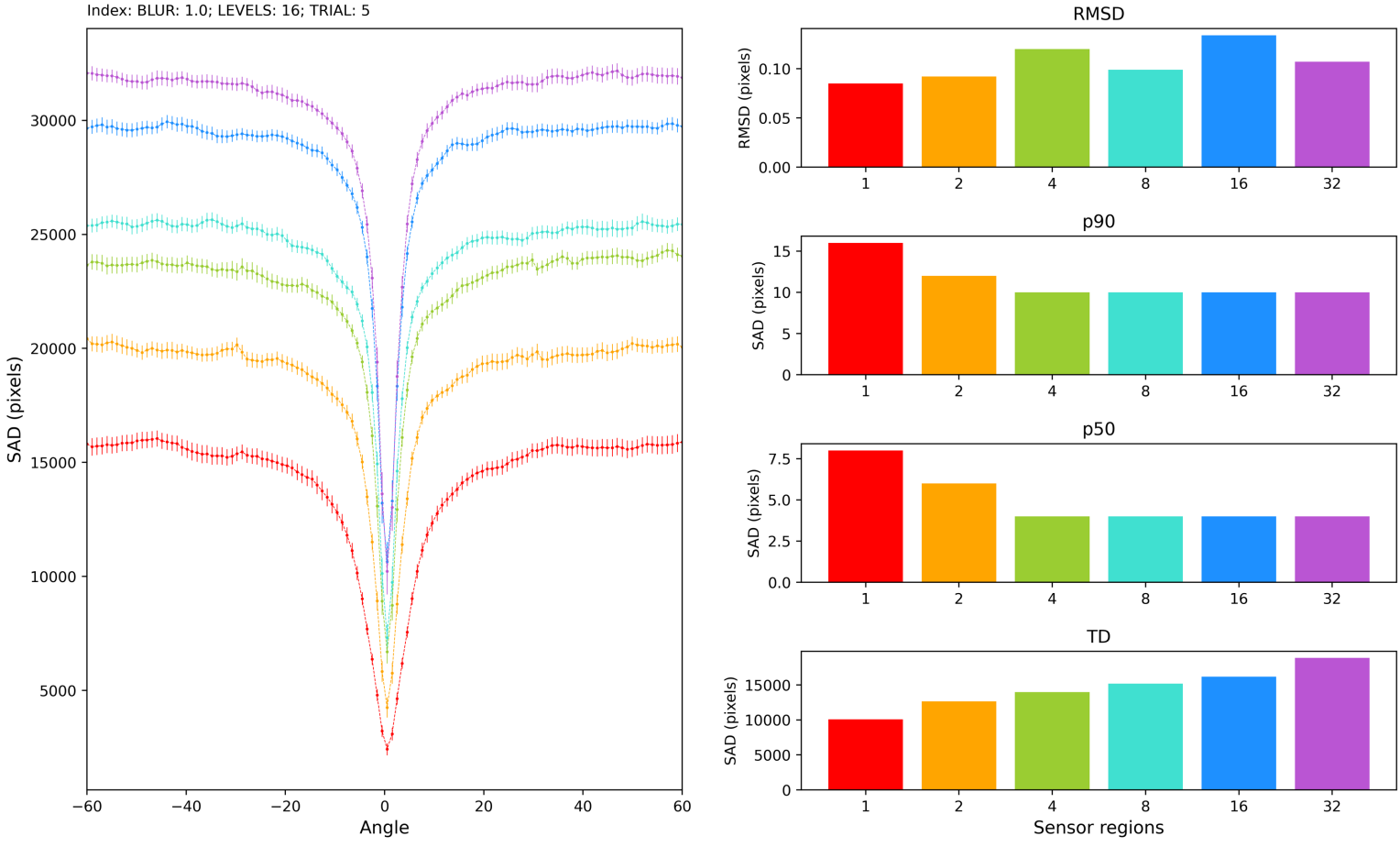
Navigation stats: RMSD error: 52.51; RMSD/dist: 0.131; TD: 16281; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 55.78; RMSD/dist: 0.139; TD: 16988; p90: 12; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 16; TRIAL: 5
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5000
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−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
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SAD (pixels)
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SAD (pixels)
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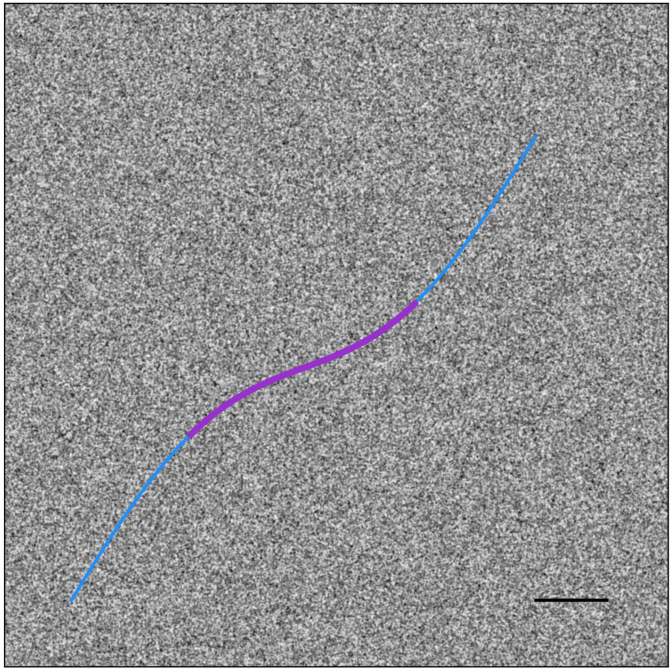
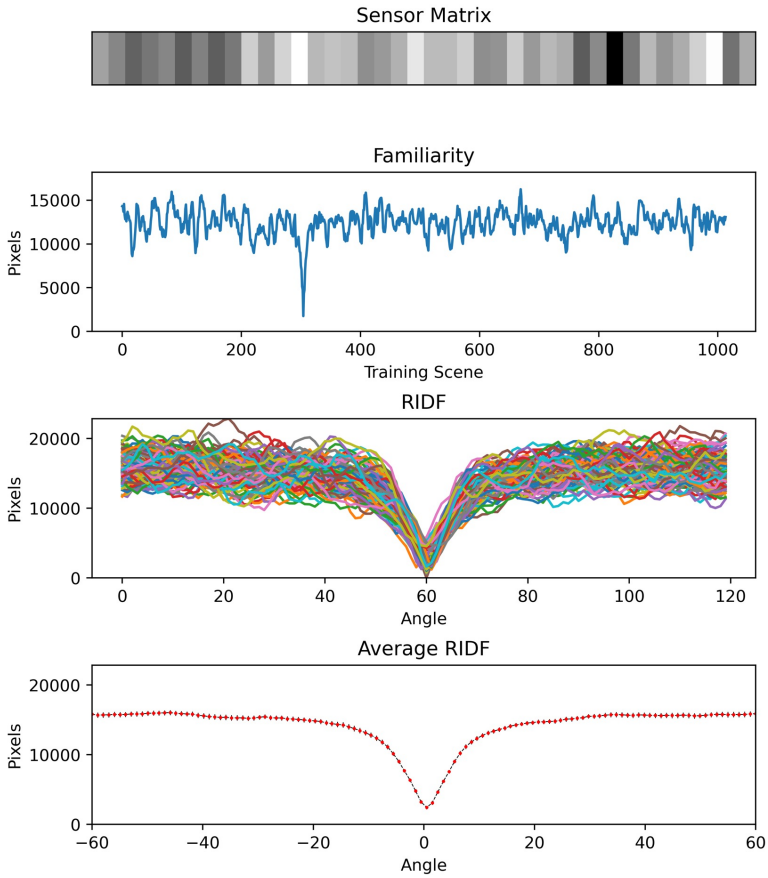
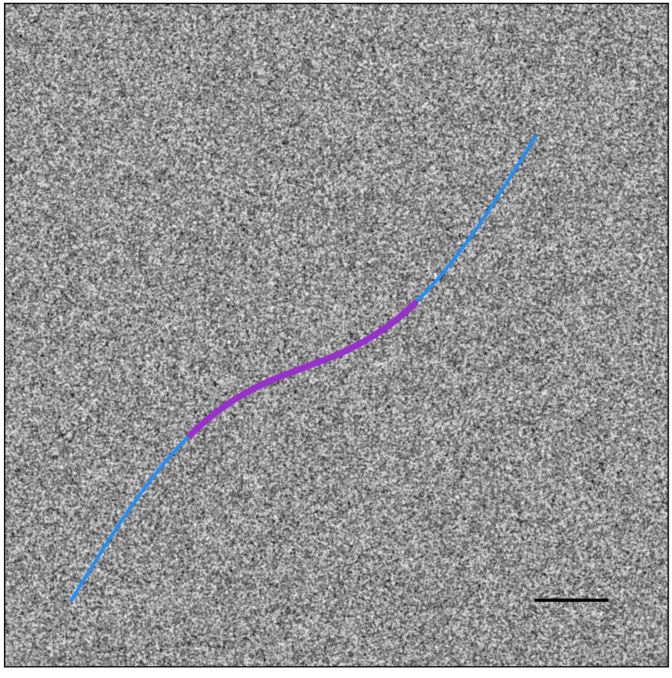
Sensor regions

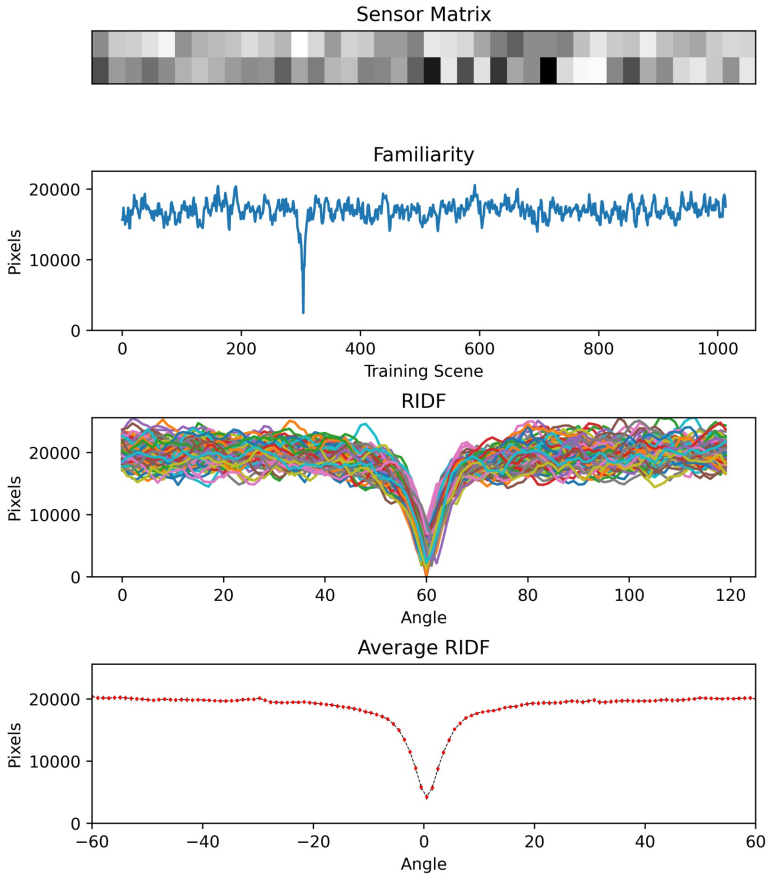




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

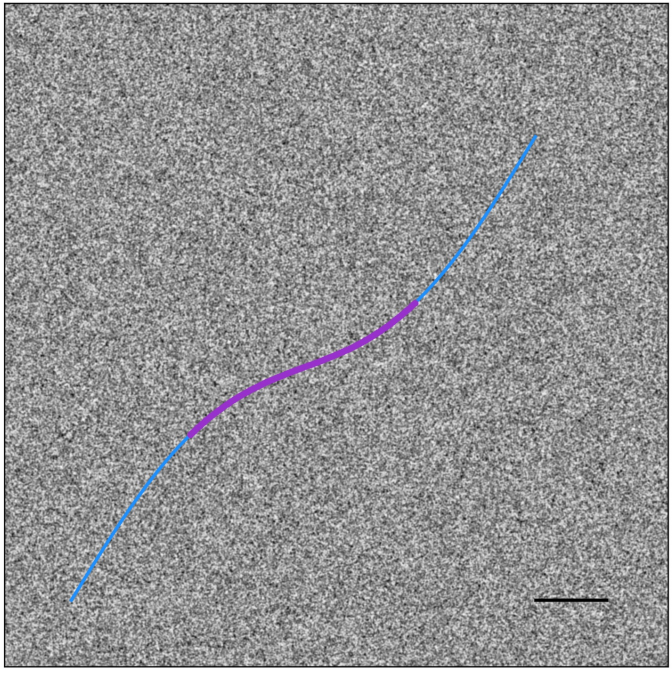
Navigation stats: RMSD error: 34.00; RMSD/dist: 0.085; TD: 10066; p90: 16; p50: 8; complete: 0

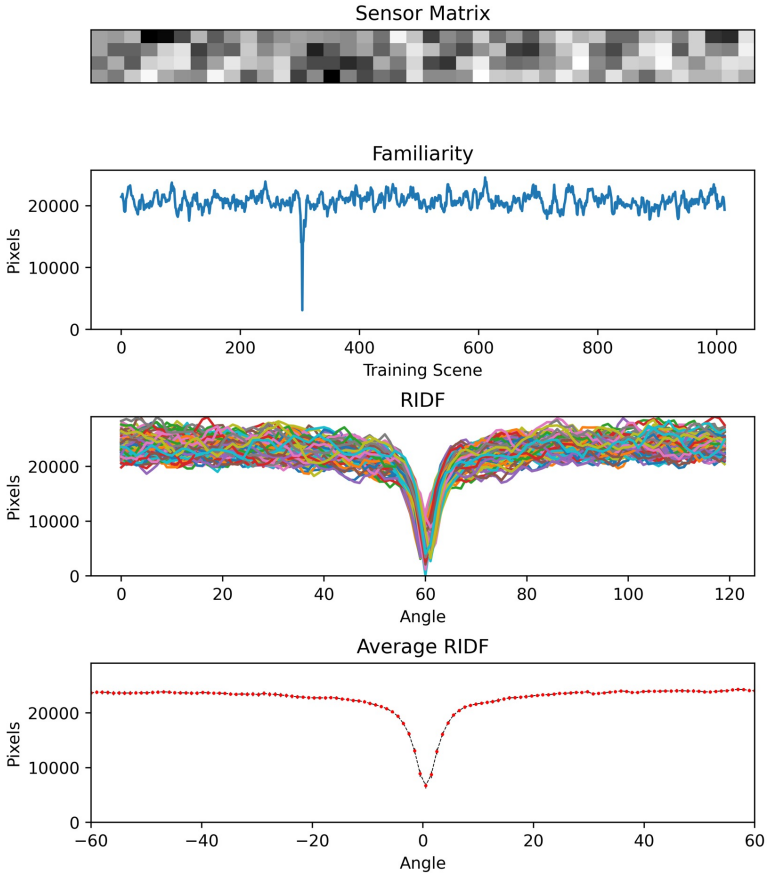




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

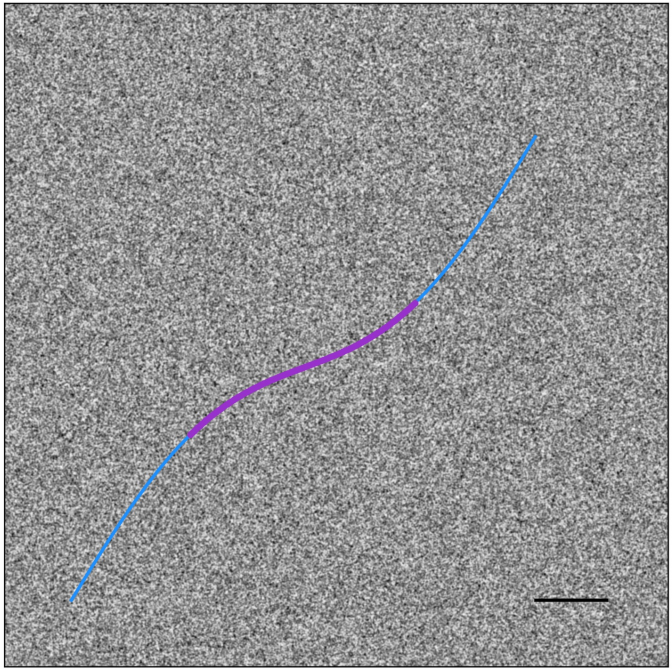
Navigation stats: RMSD error: 36.73; RMSD/dist: 0.092; TD: 12644; p90: 12; p50: 6; complete: 0

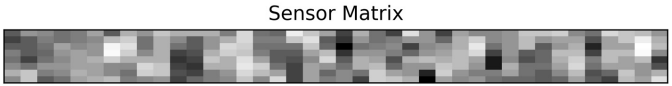


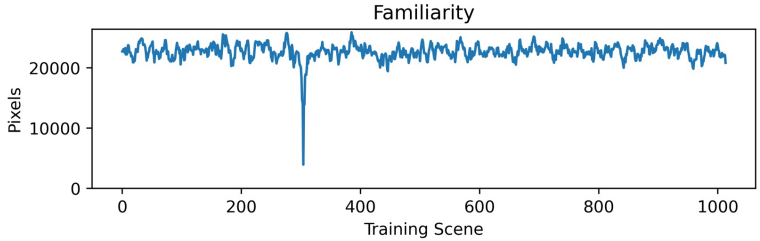


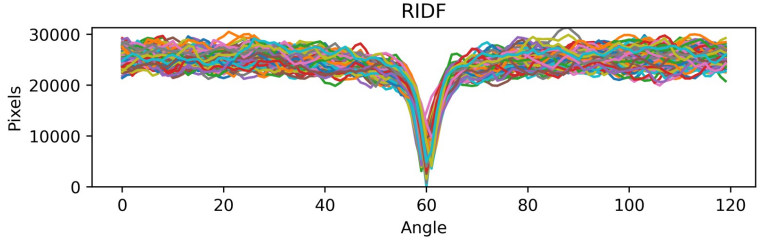
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

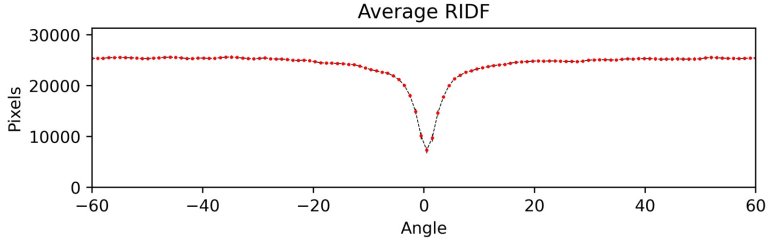
Navigation stats: RMSD error: 47.97; RMSD/dist: 0.120; TD: 13961; p90: 10; p50: 4; complete: 0





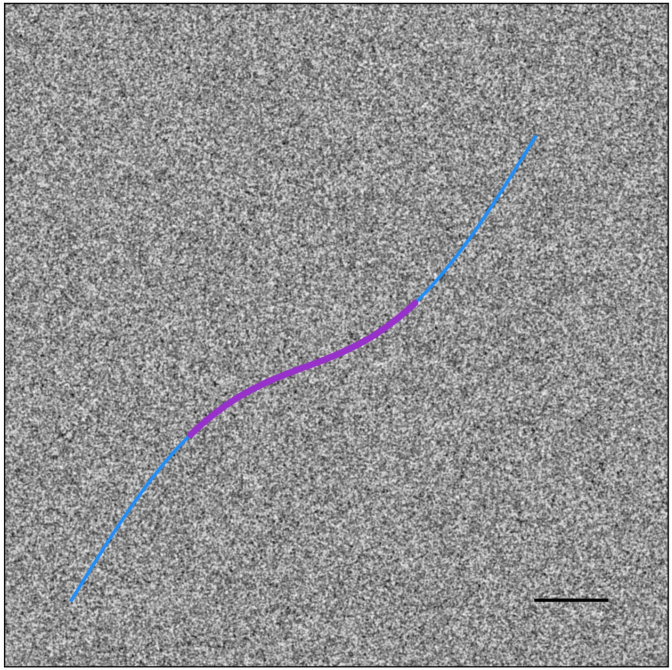


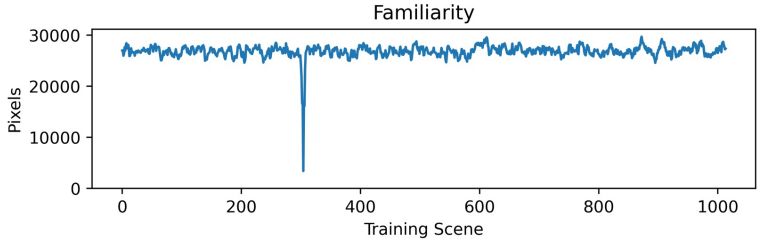


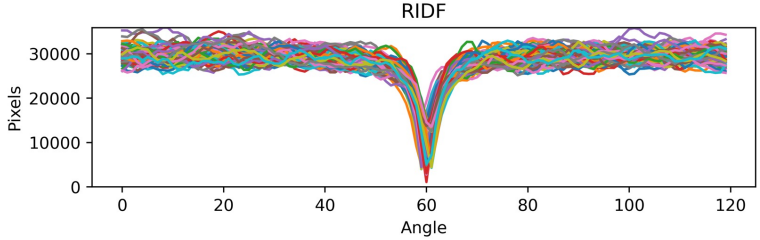


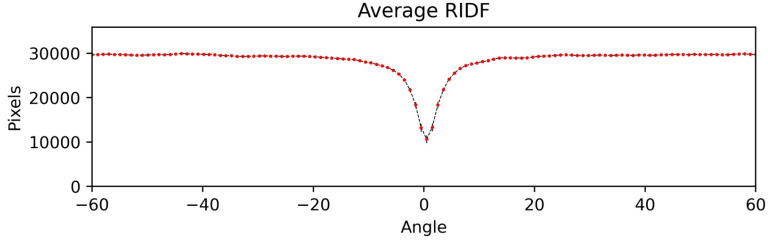
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 39.49; RMSD/dist: 0.099; TD: 15186; p90: 10; p50: 4; complete: 0



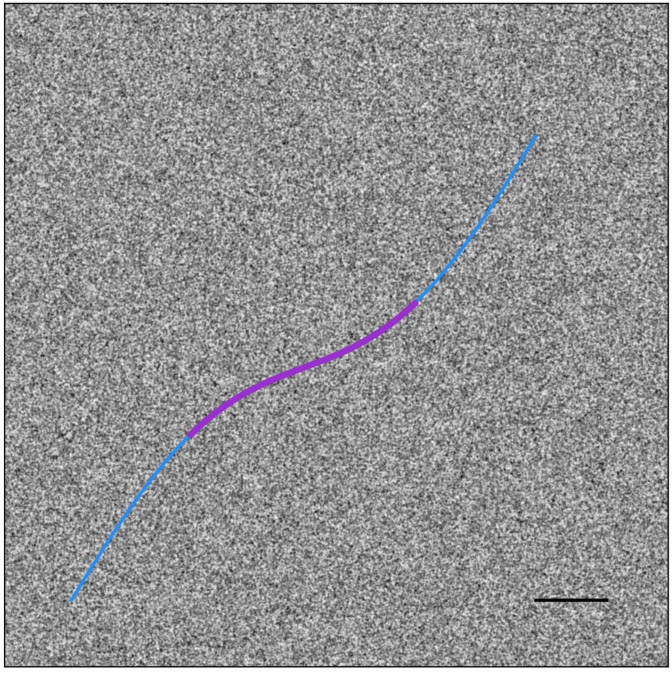


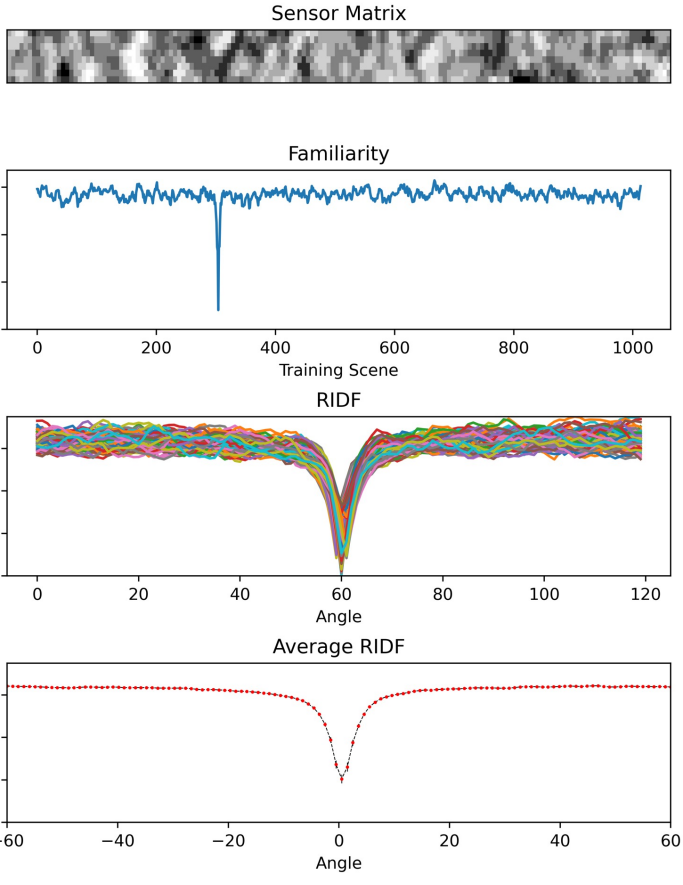




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

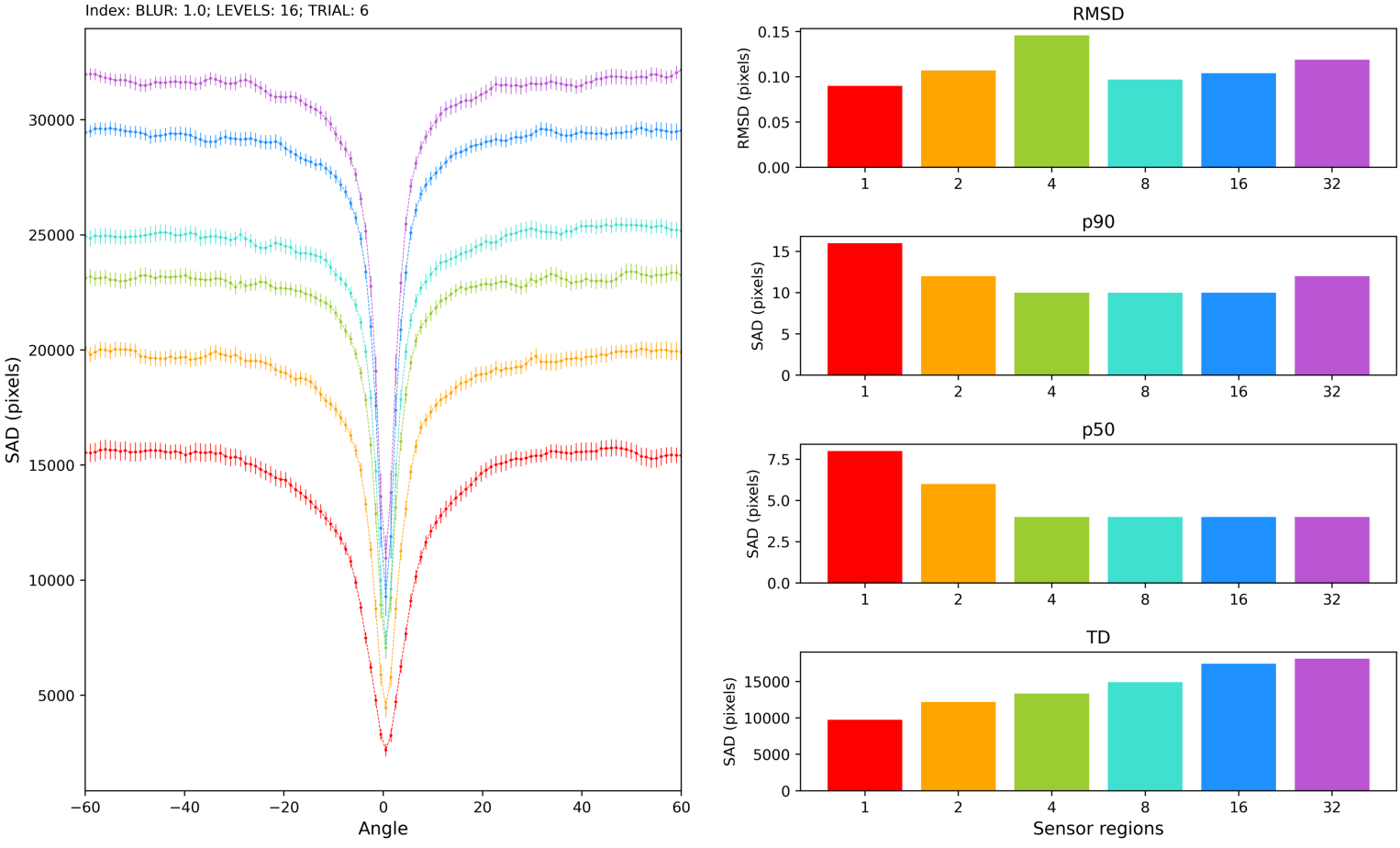
Navigation stats: RMSD error: 53.49; RMSD/dist: 0.134; TD: 16178; p90: 10; p50: 4; complete: 0

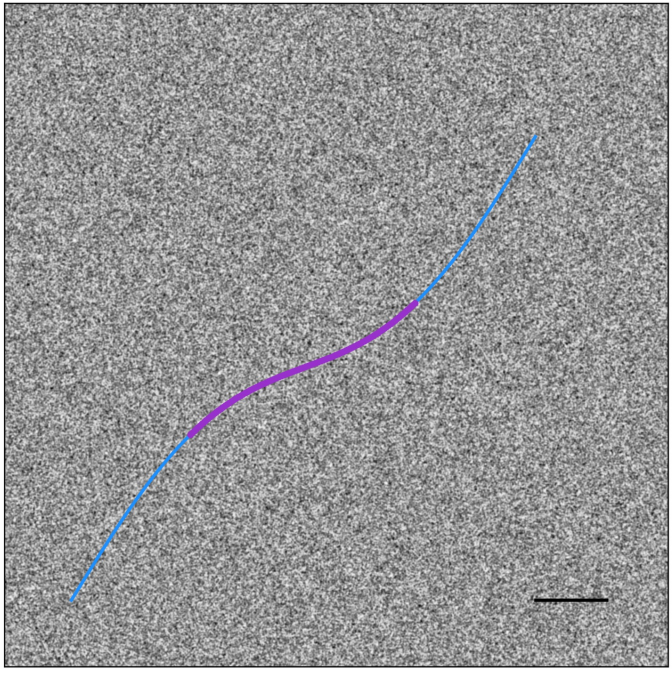


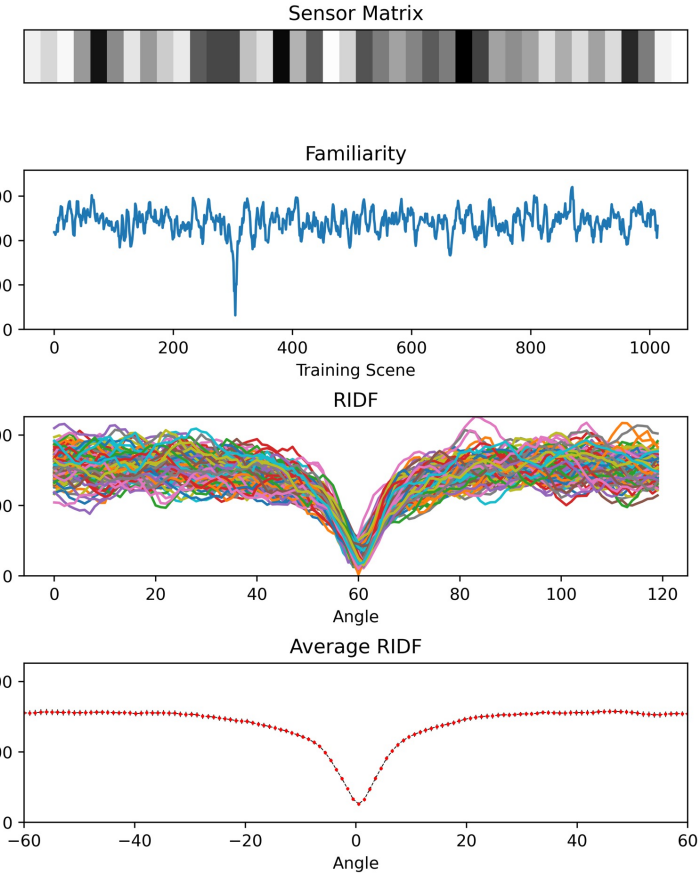


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 42.73; RMSD/dist: 0.107; TD: 18854; p90: 10; p50: 4; complete: 0

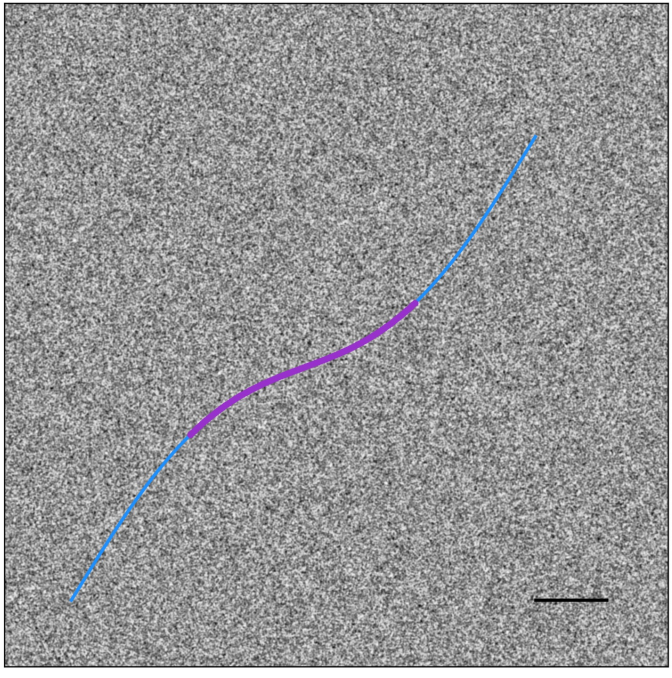

Index: BLUR: 1.0; LEVELS: 16; TRIAL: 6
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

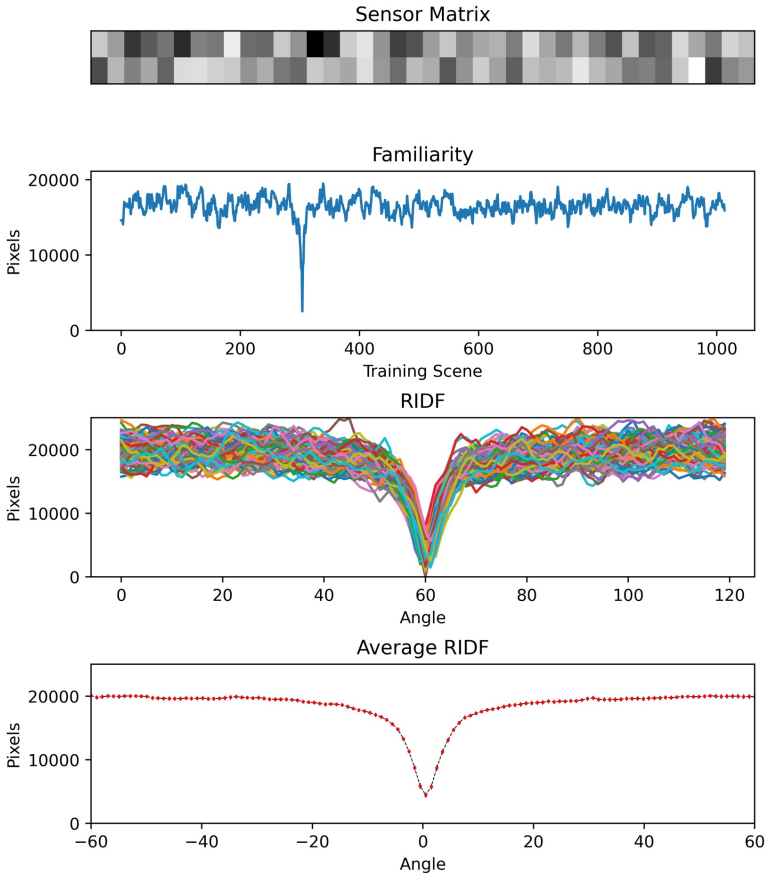




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

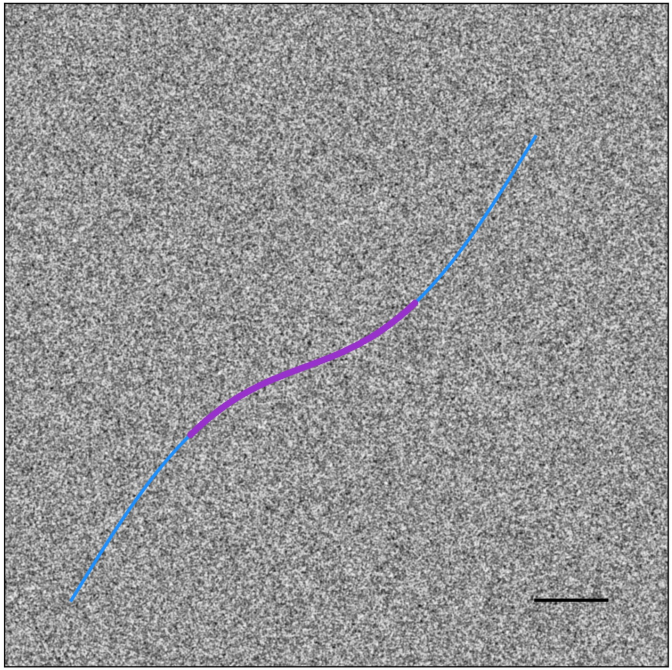
Navigation stats: RMSD error: 36.00; RMSD/dist: 0.090; TD: 9748; p90: 16; p50: 8; complete: 0

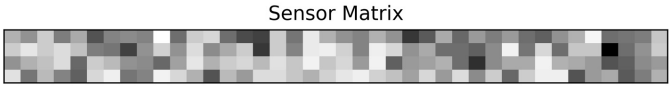


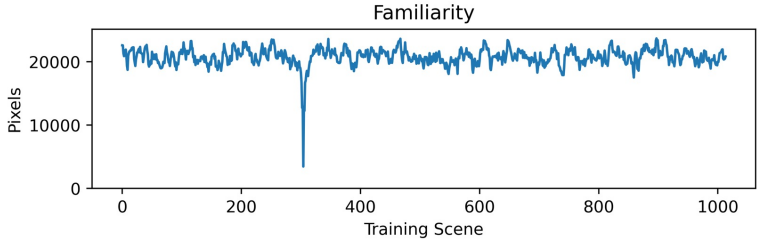


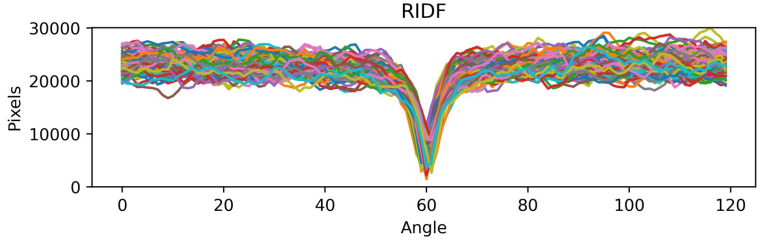
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

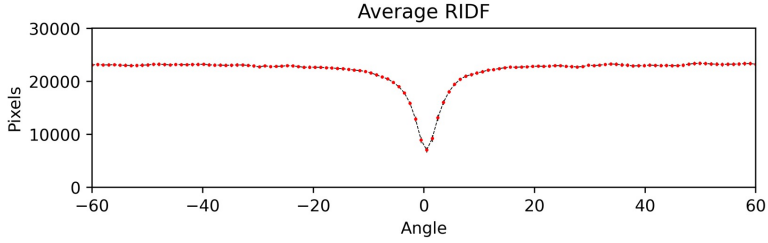
Navigation stats: RMSD error: 42.89; RMSD/dist: 0.107; TD: 12200; p90: 12; p50: 6; complete: 0





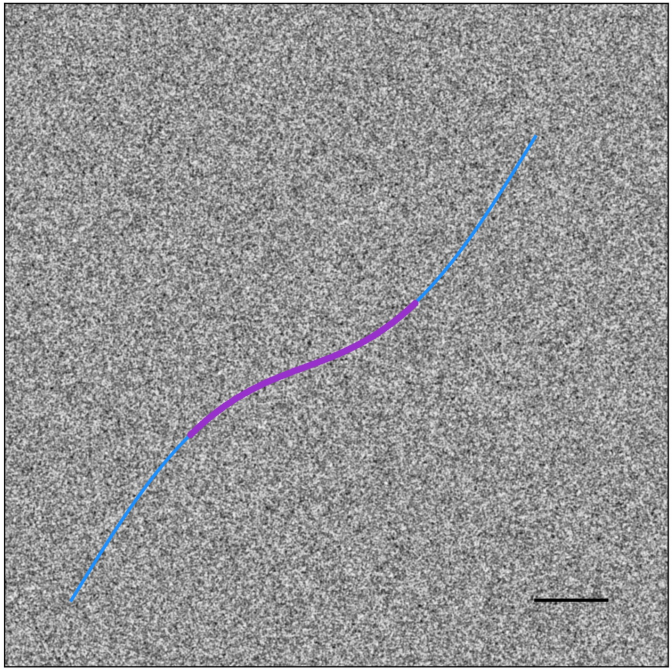


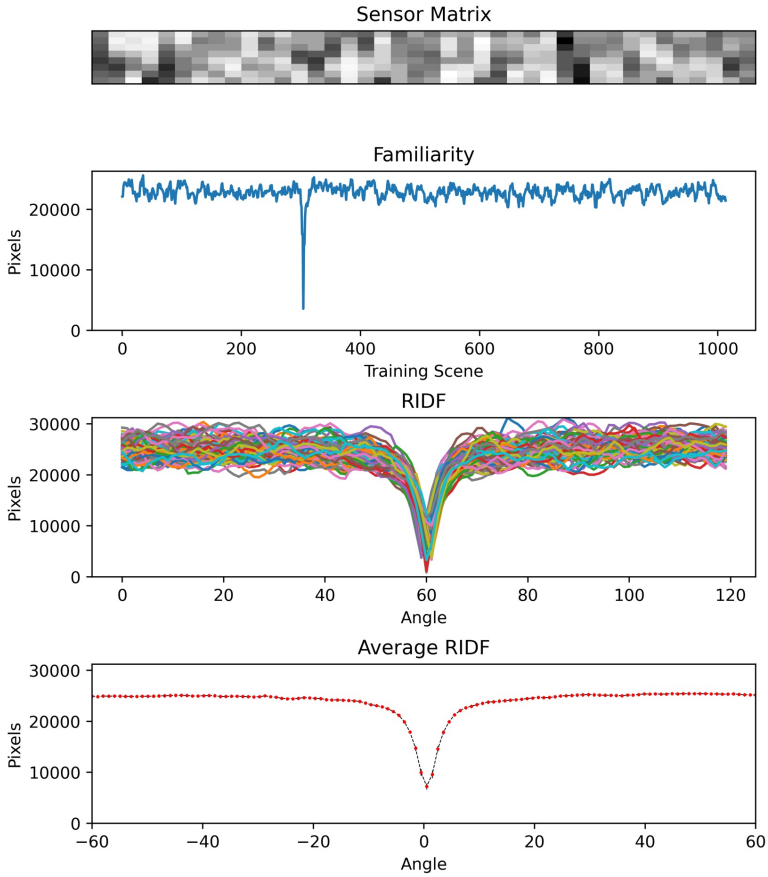




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

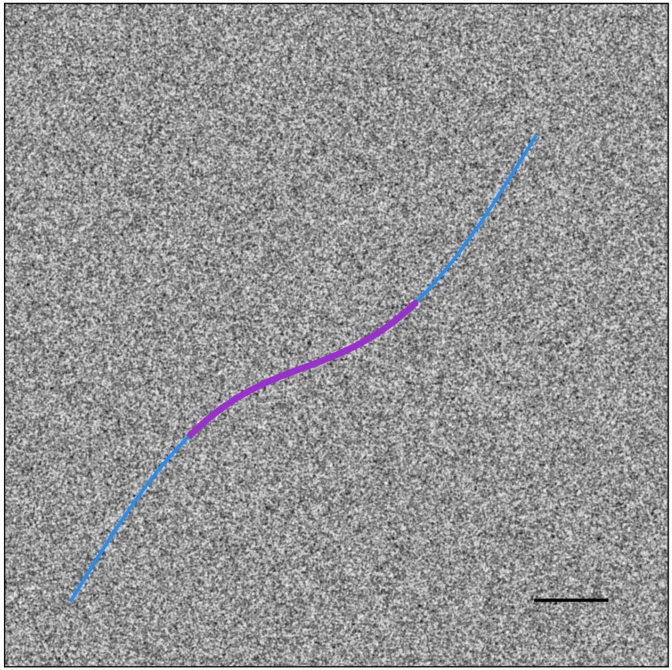
Navigation stats: RMSD error: 58.25; RMSD/dist: 0.146; TD: 13352; p90: 10; p50: 4; complete: 0

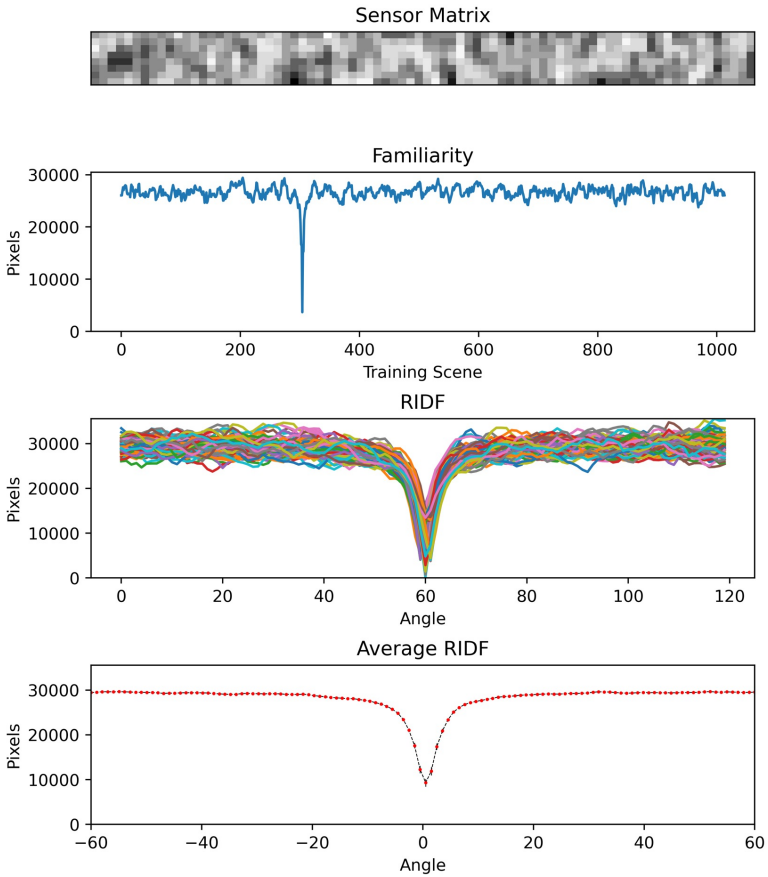




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

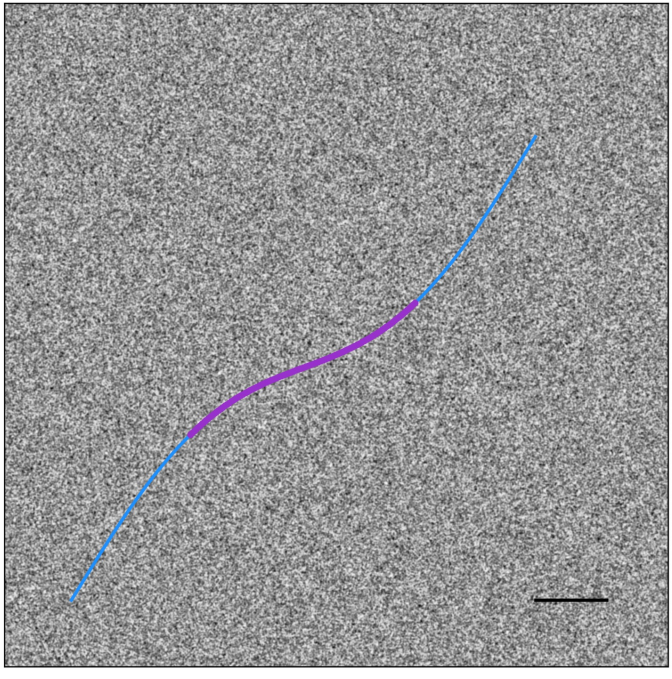
Navigation stats: RMSD error: 39.00; RMSD/dist: 0.097; TD: 14923; p90: 10; p50: 4; complete: 0

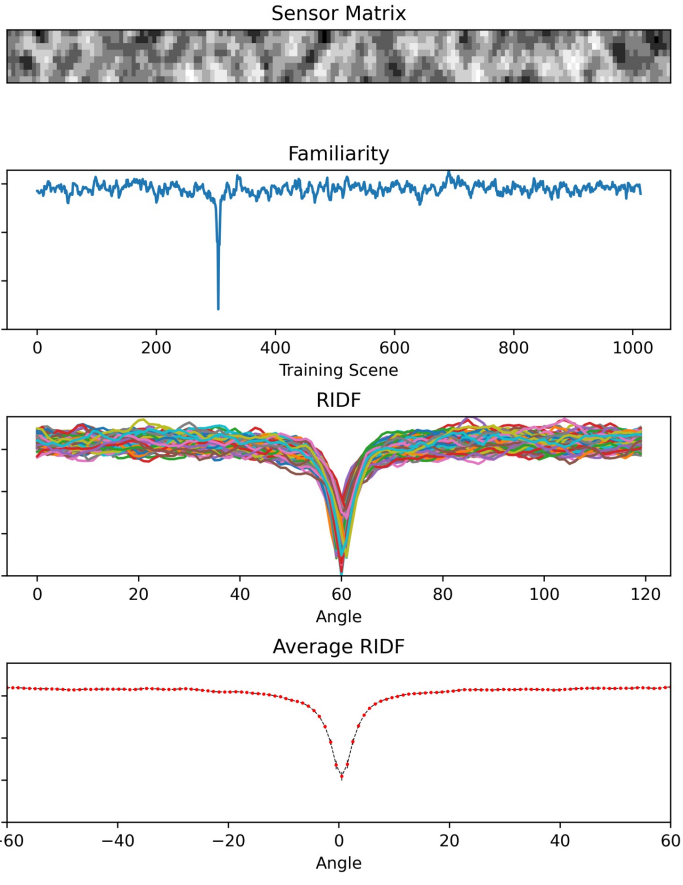




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

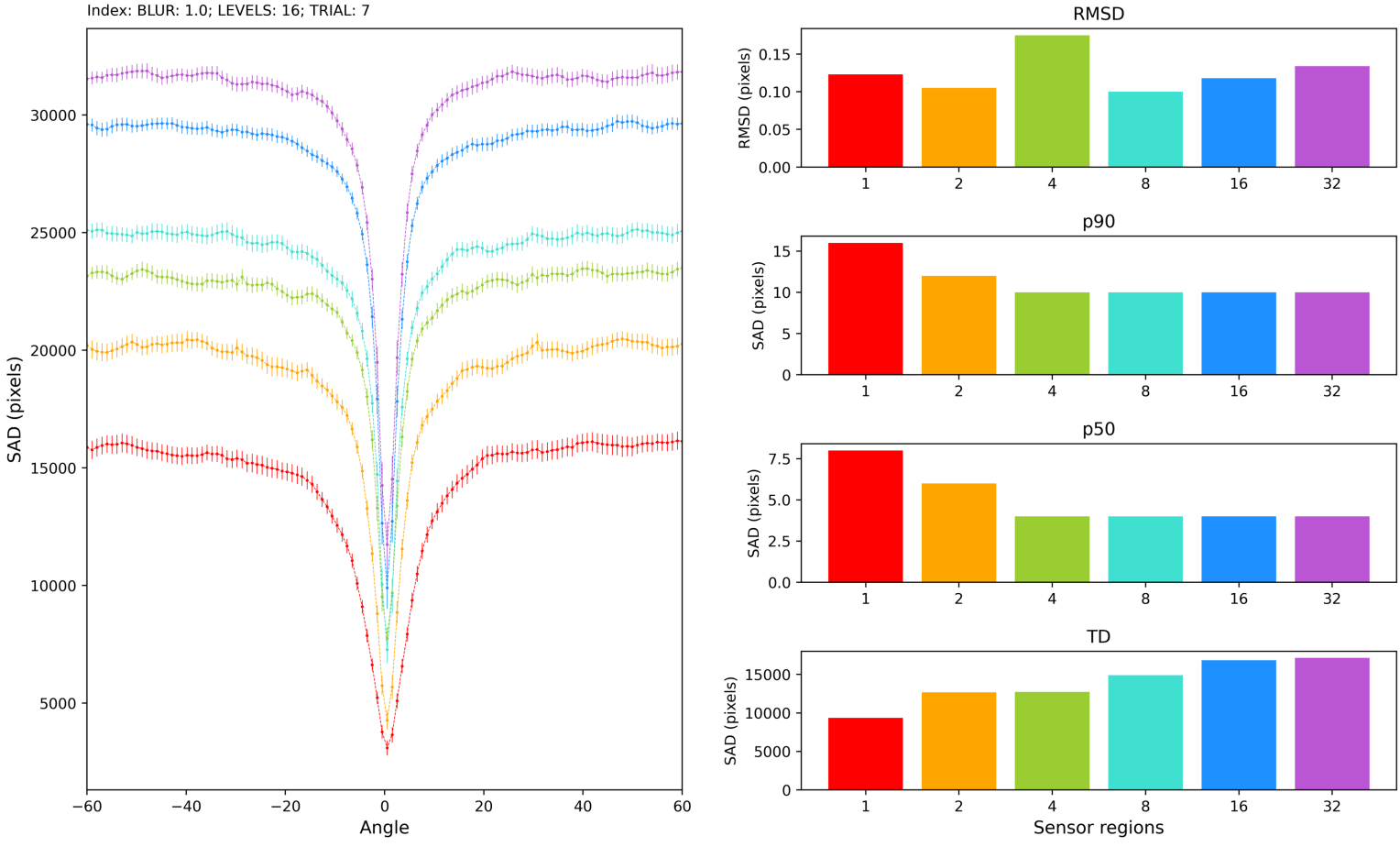
Navigation stats: RMSD error: 41.58; RMSD/dist: 0.104; TD: 17430; p90: 10; p50: 4; complete: 0

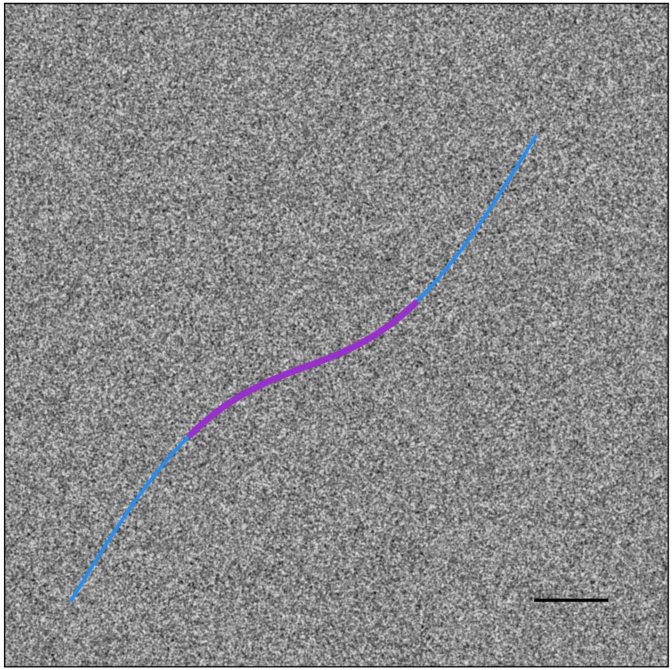


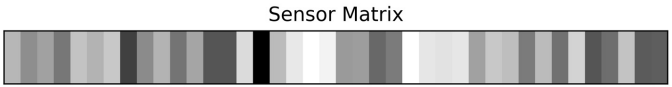


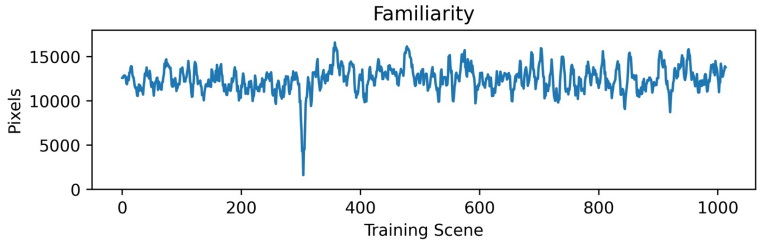
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

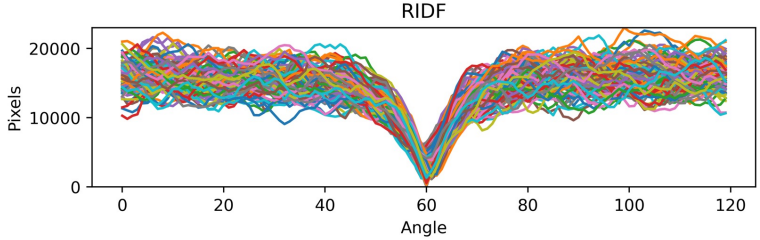
Navigation stats: RMSD error: 47.48; RMSD/dist: 0.119; TD: 18125; p90: 12; p50: 4; complete: 0

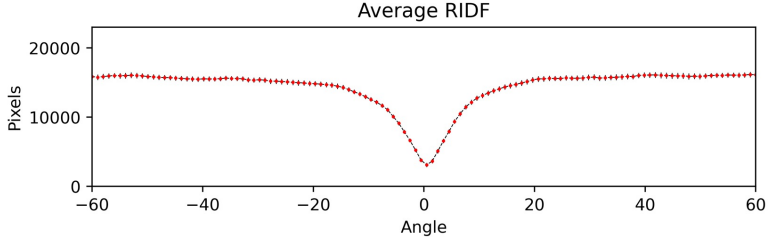

Index: BLUR: 1.0; LEVELS: 16; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions





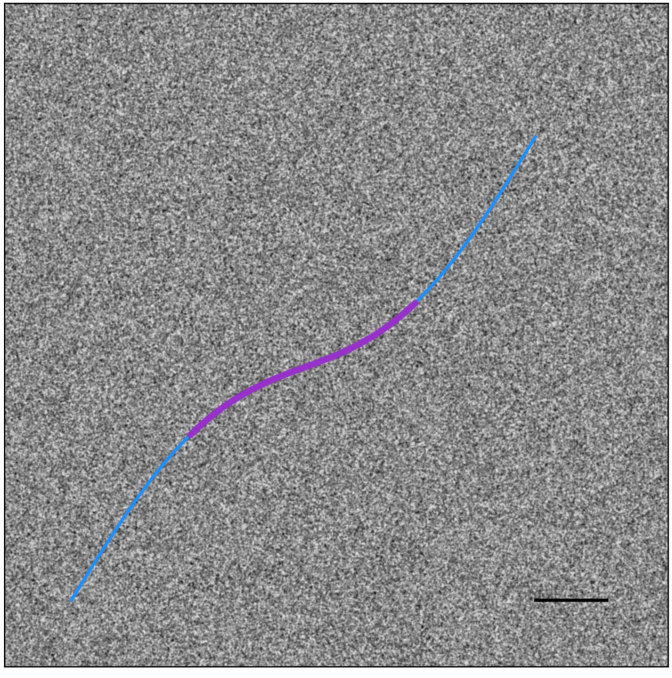


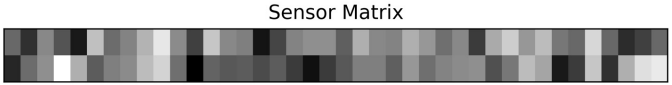


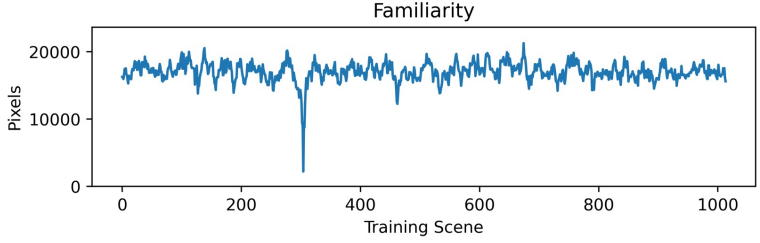


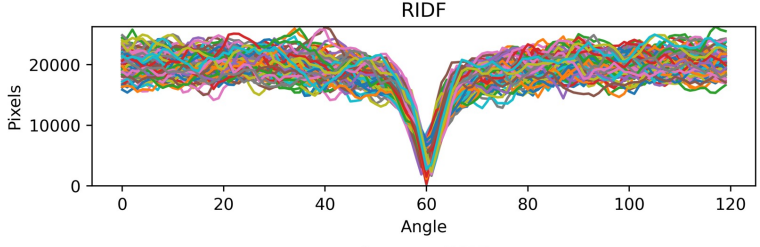
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

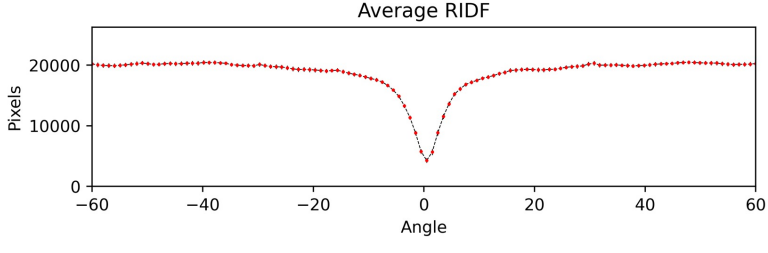
Navigation stats: RMSD error: 49.17; RMSD/dist: 0.123; TD: 9362; p90: 16; p50: 8; complete: 0





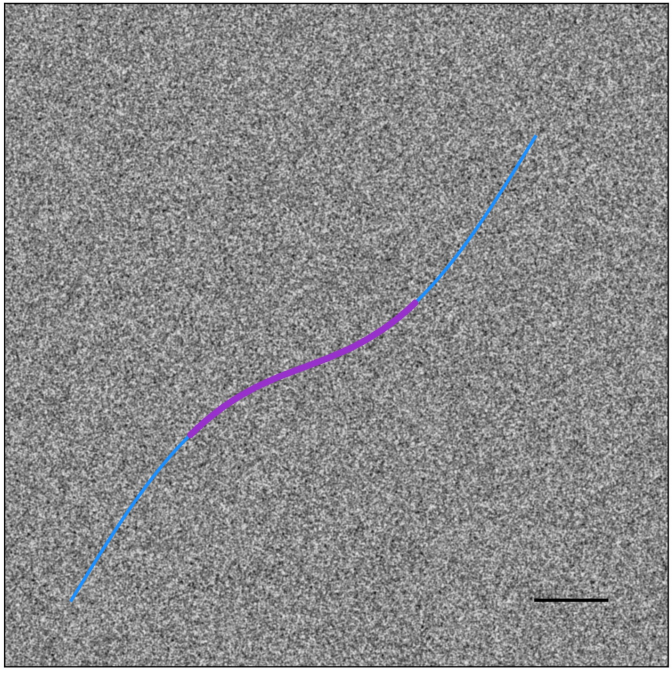


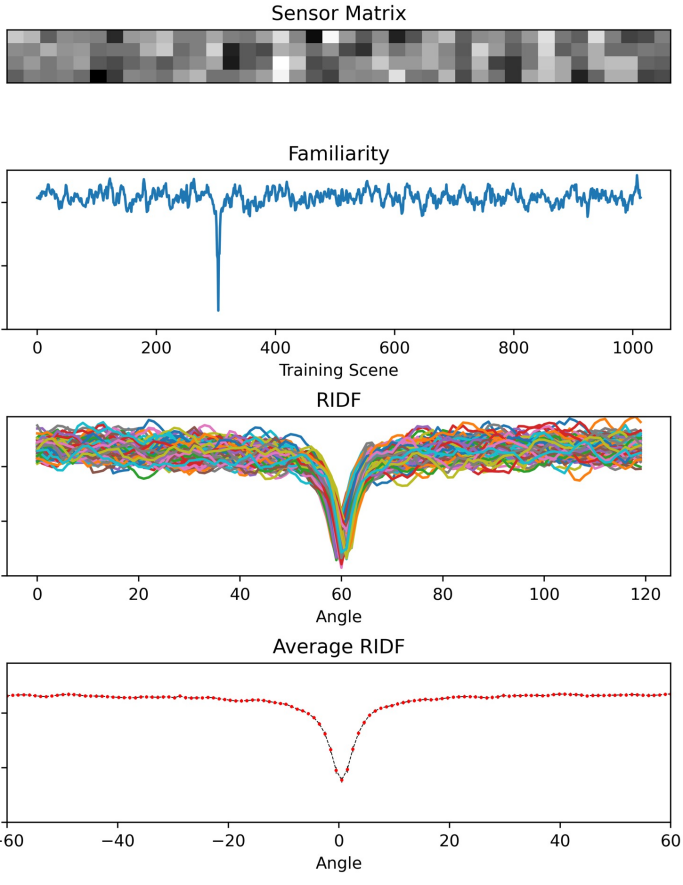




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

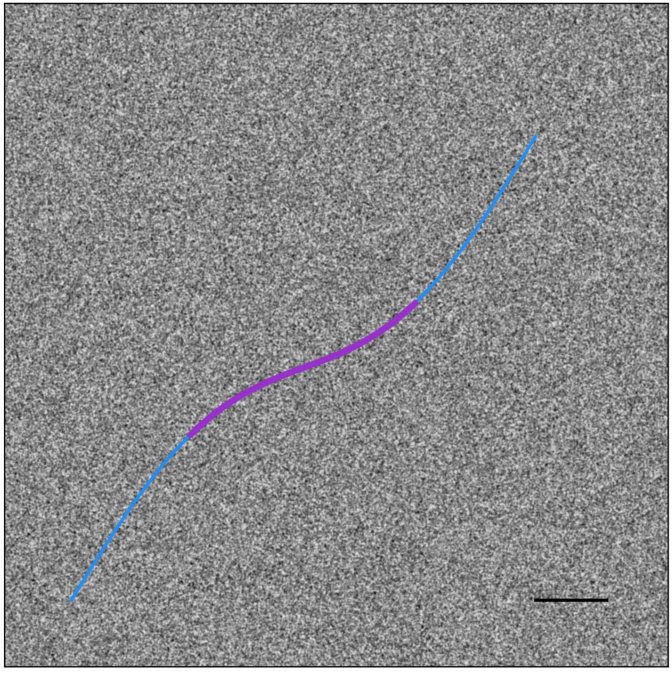
Navigation stats: RMSD error: 42.06; RMSD/dist: 0.105; TD: 12682; p90: 12; p50: 6; complete: 0

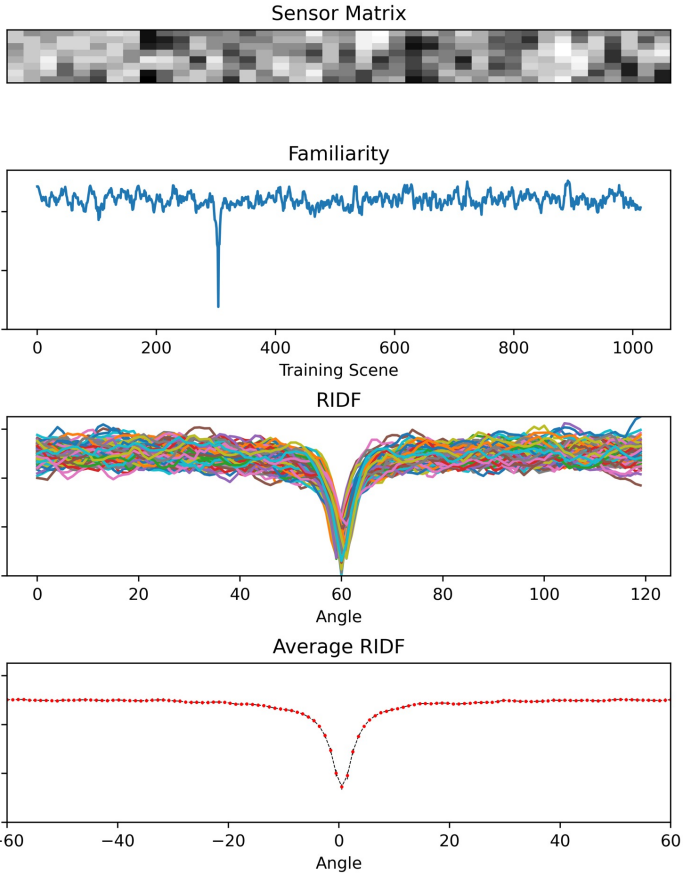




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

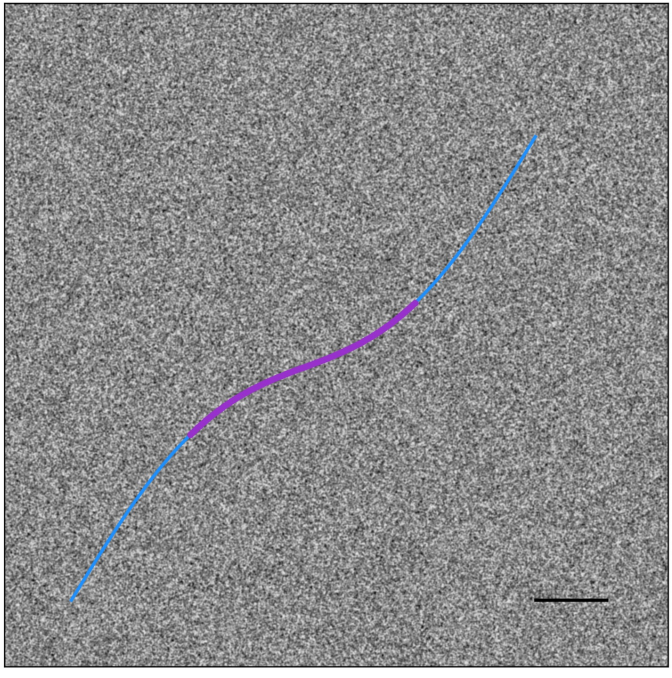
Navigation stats: RMSD error: 70.02; RMSD/dist: 0.175; TD: 12744; p90: 10; p50: 4; complete: 0

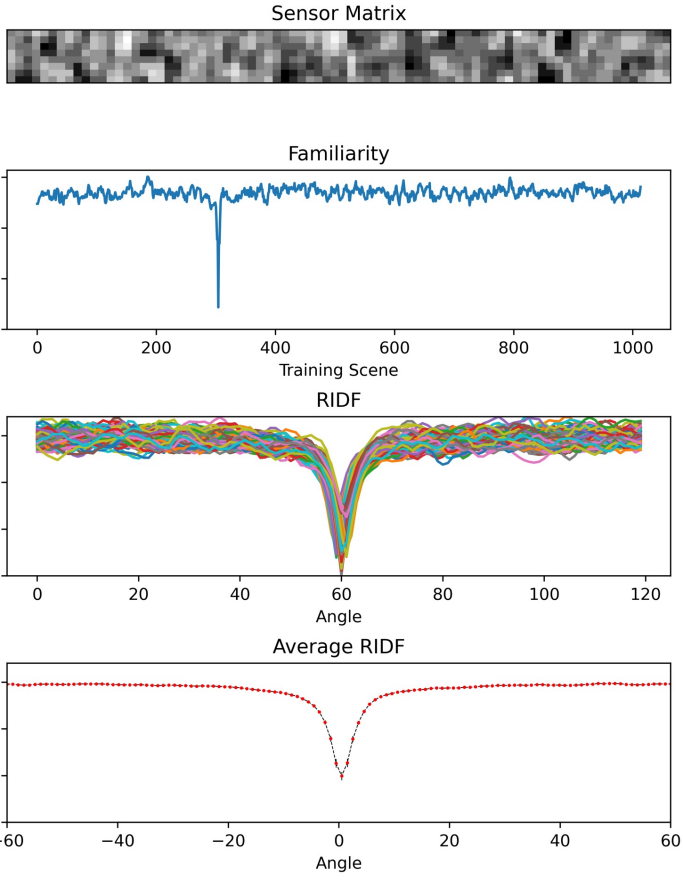




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

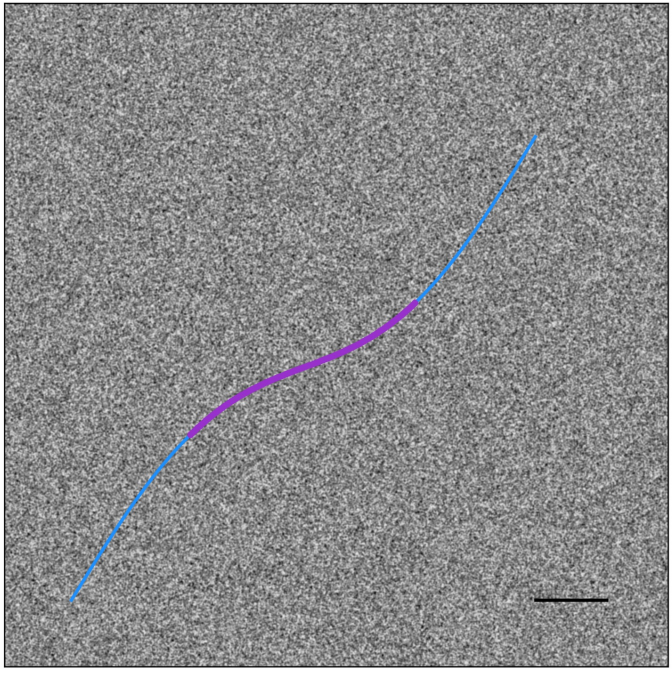
Navigation stats: RMSD error: 39.96; RMSD/dist: 0.100; TD: 14908; p90: 10; p50: 4; complete: 0

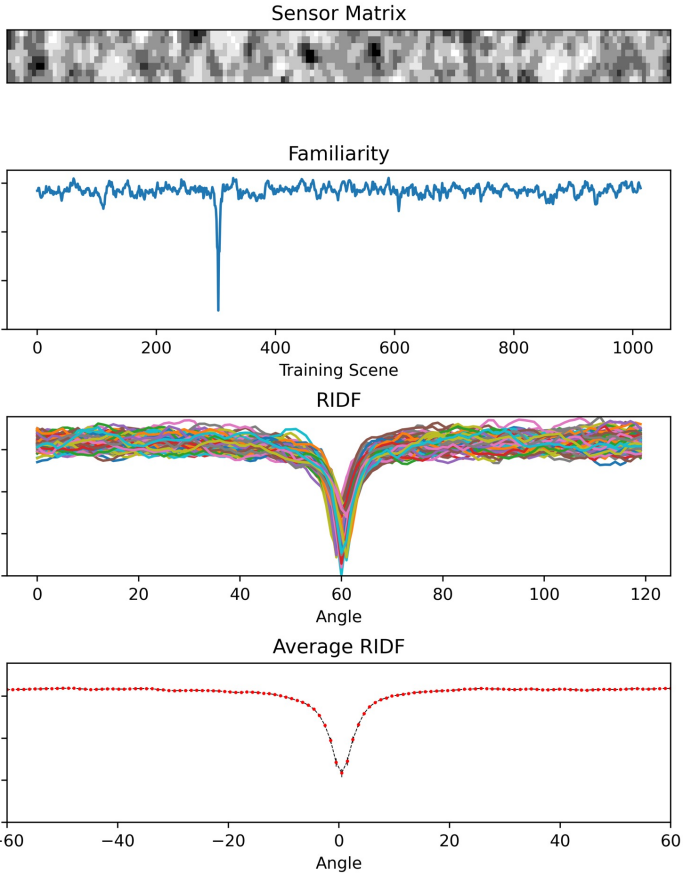




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

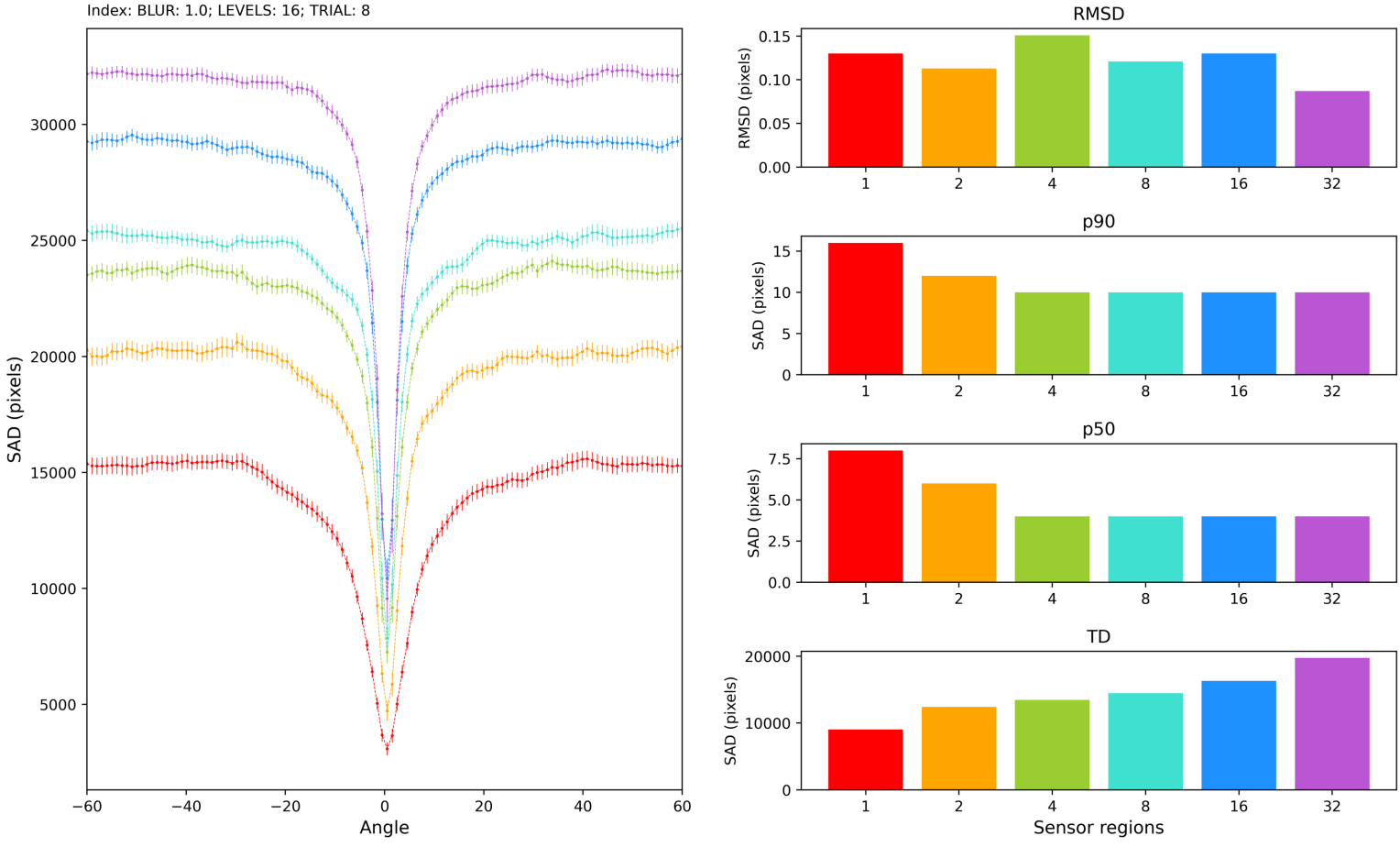
Navigation stats: RMSD error: 47.08; RMSD/dist: 0.118; TD: 16849; p90: 10; p50: 4; complete: 0

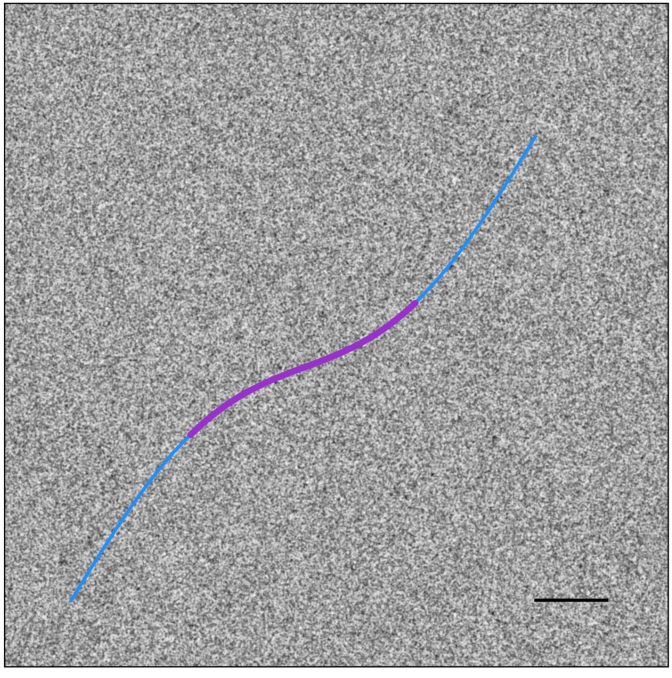


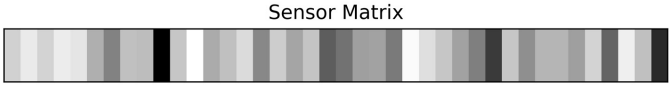


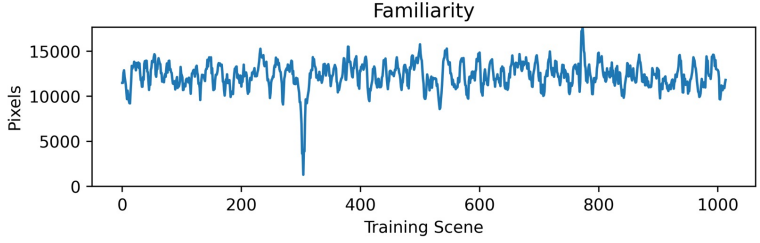
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

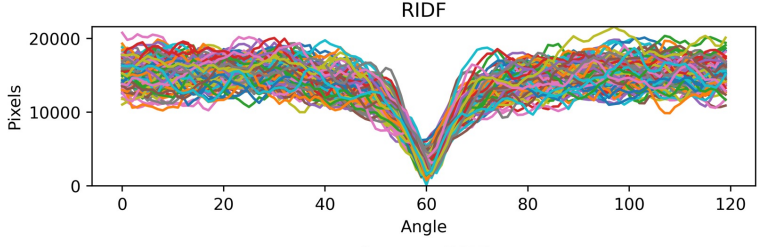
Navigation stats: RMSD error: 53.42; RMSD/dist: 0.134; TD: 17141; p90: 10; p50: 4; complete: 0

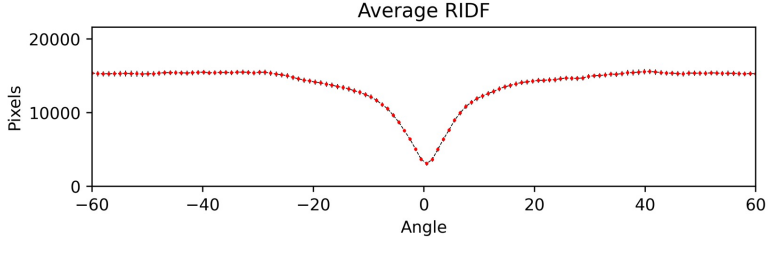

Index: BLUR: 1.0; LEVELS: 16; TRIAL: 8
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions





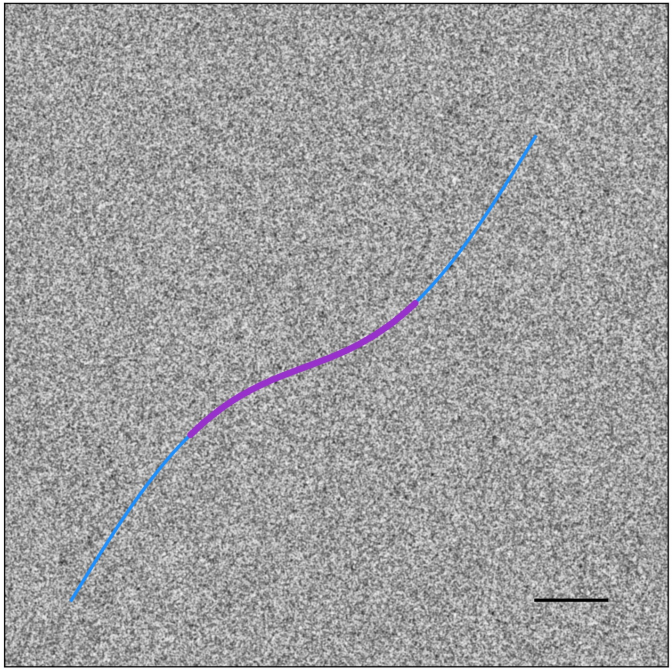


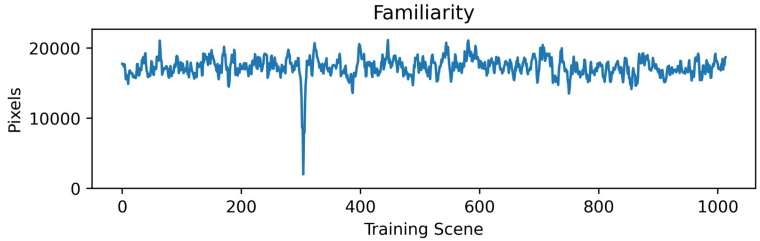


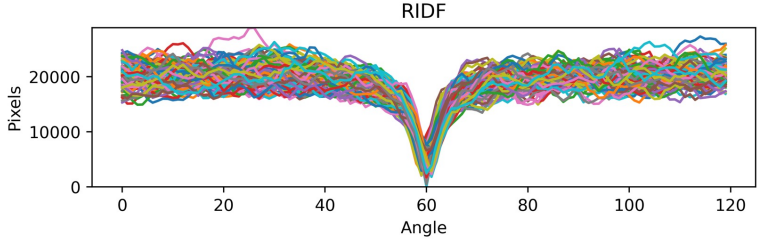


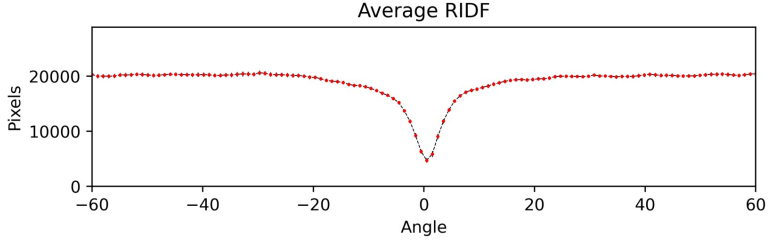
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 52.01; RMSD/dist: 0.130; TD: 9040; p90: 16; p50: 8; complete: 0



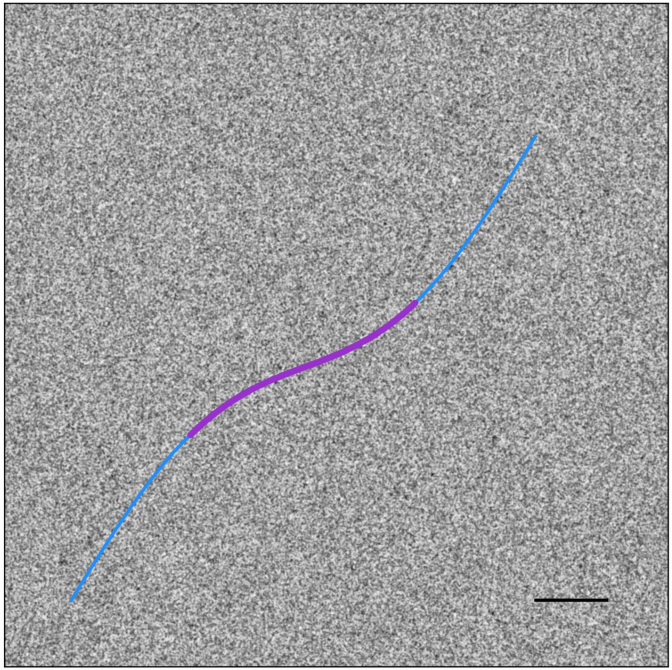


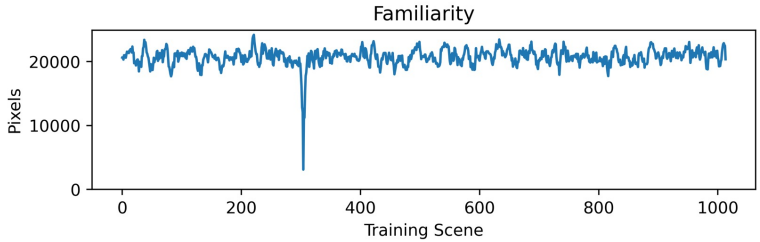


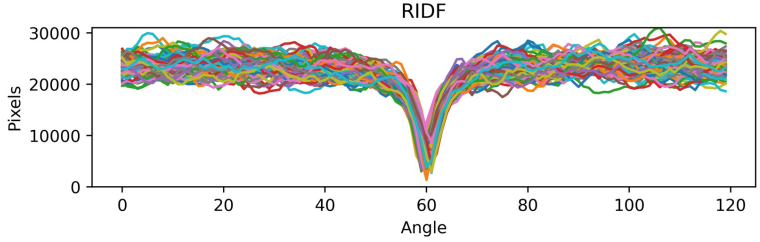


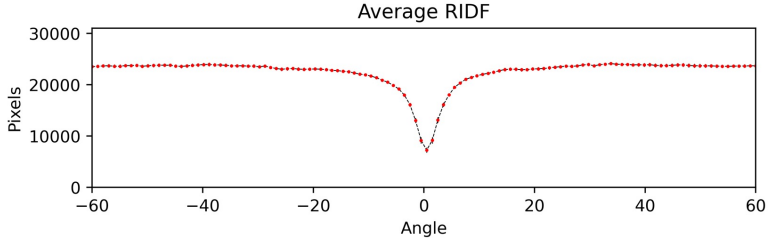
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 45.11; RMSD/dist: 0.113; TD: 12417; p90: 12; p50: 6; complete: 0



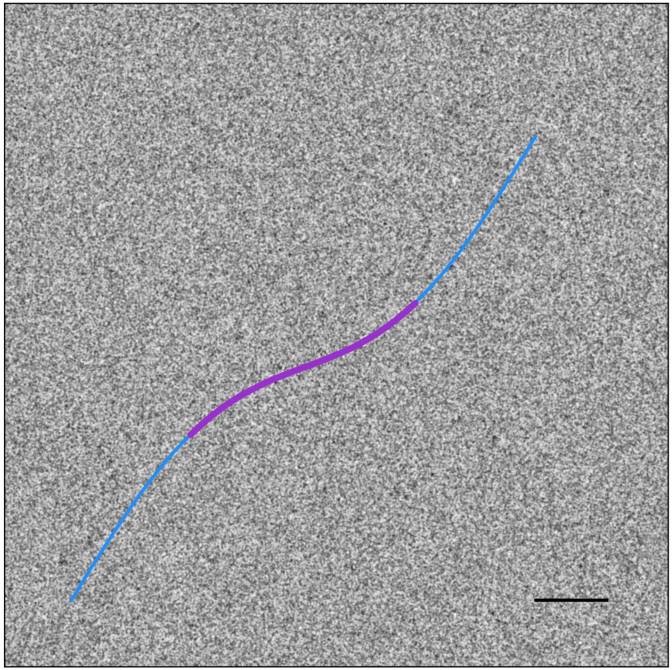


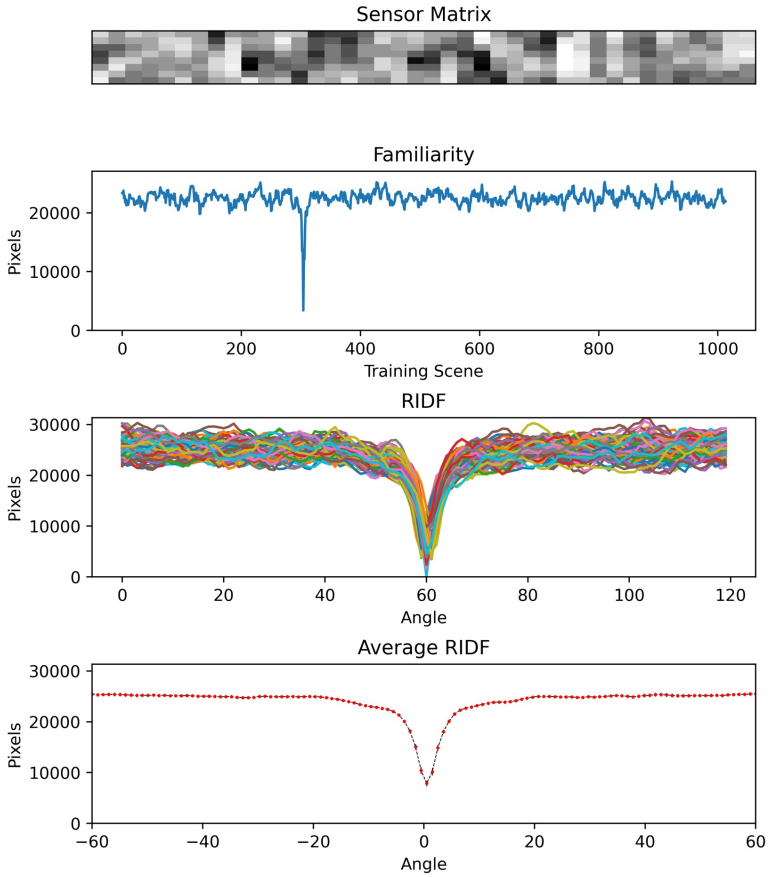




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

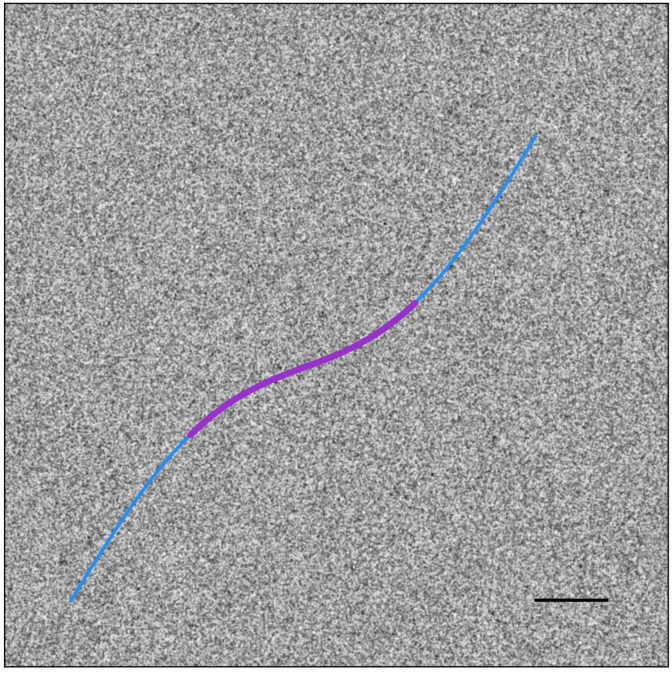
Navigation stats: RMSD error: 60.54; RMSD/dist: 0.151; TD: 13457; p90: 10; p50: 4; complete: 0

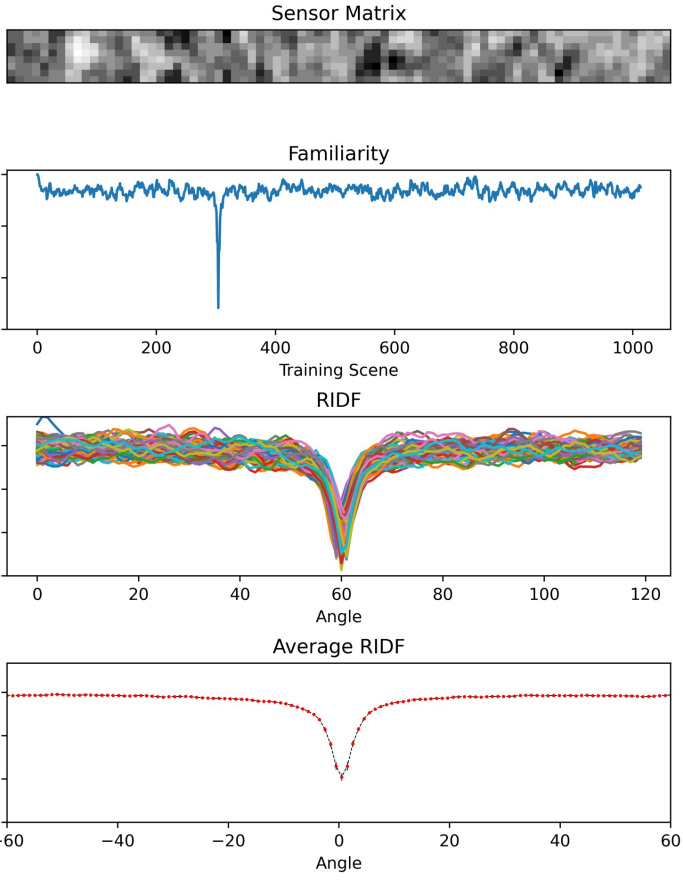




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

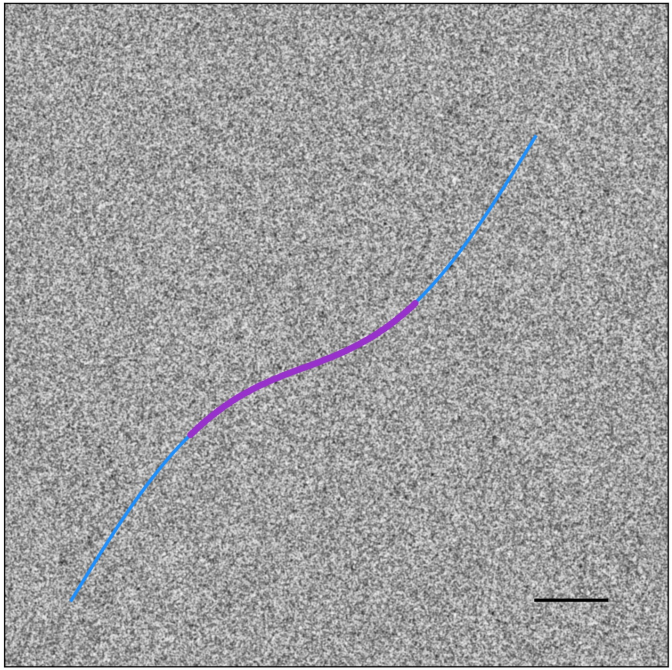
Navigation stats: RMSD error: 48.45; RMSD/dist: 0.121; TD: 14461; p90: 10; p50: 4; complete: 0

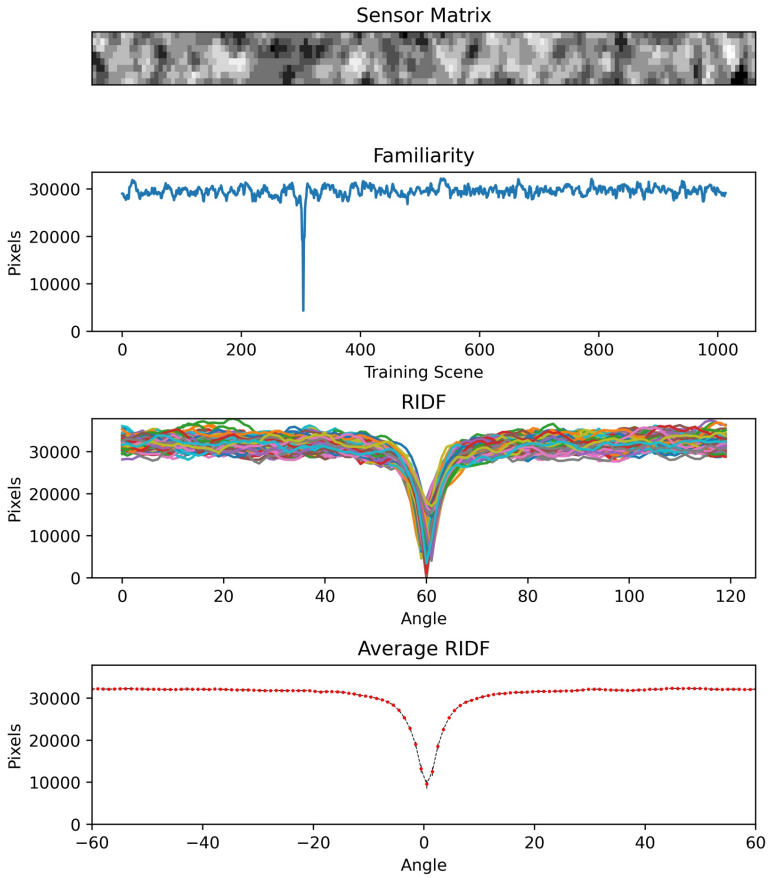




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

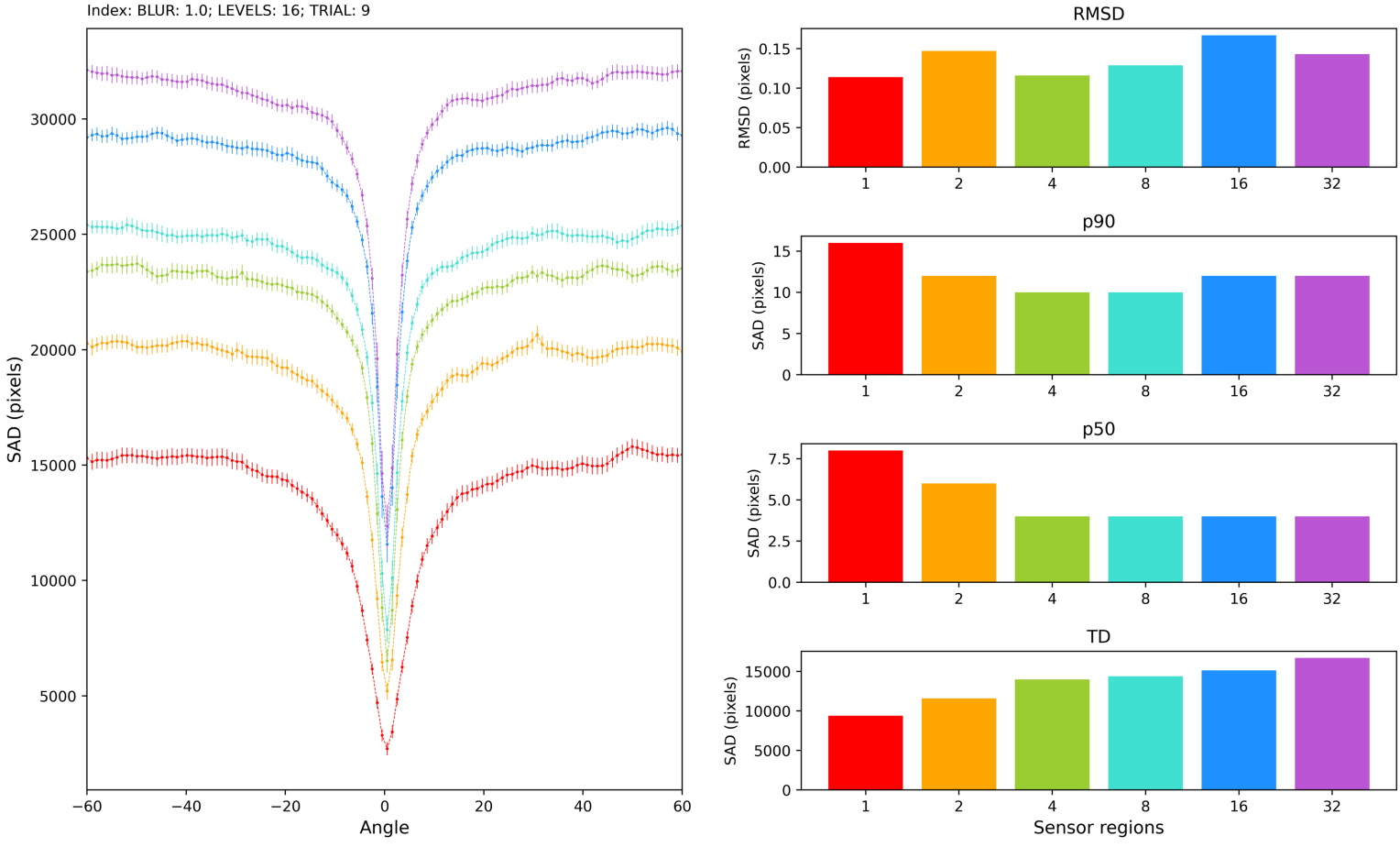
Navigation stats: RMSD error: 52.03; RMSD/dist: 0.130; TD: 16294; p90: 10; p50: 4; complete: 0

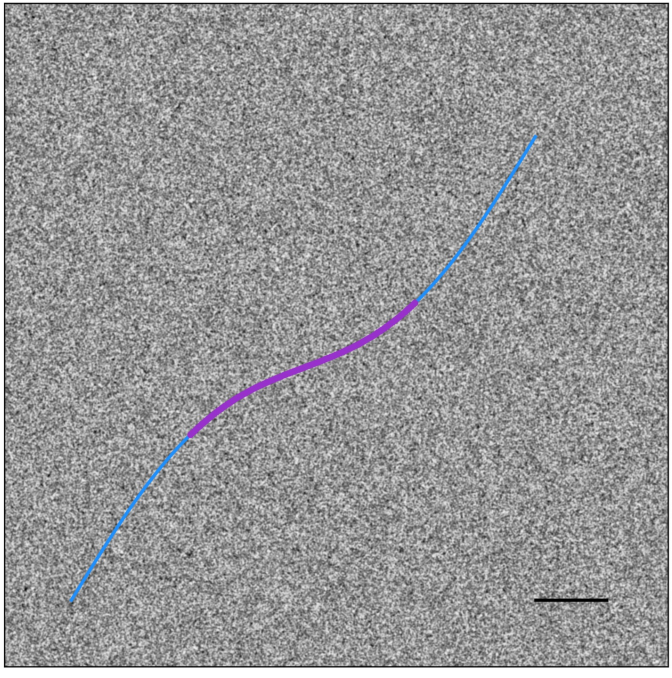


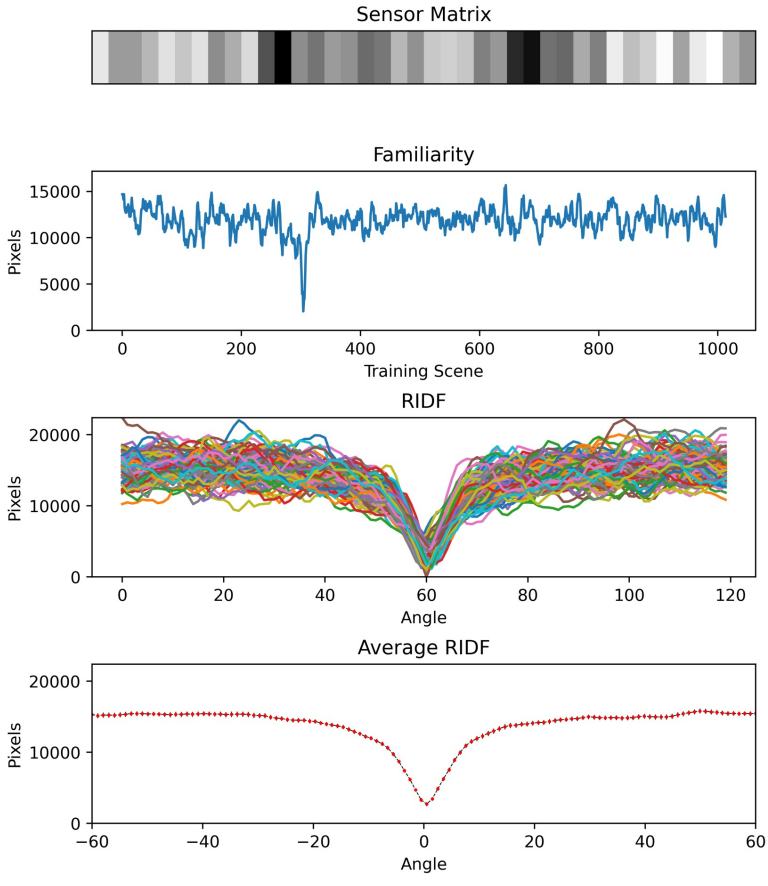


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 34.95; RMSD/dist: 0.087; TD: 19720; p90: 10; p50: 4; complete: 0

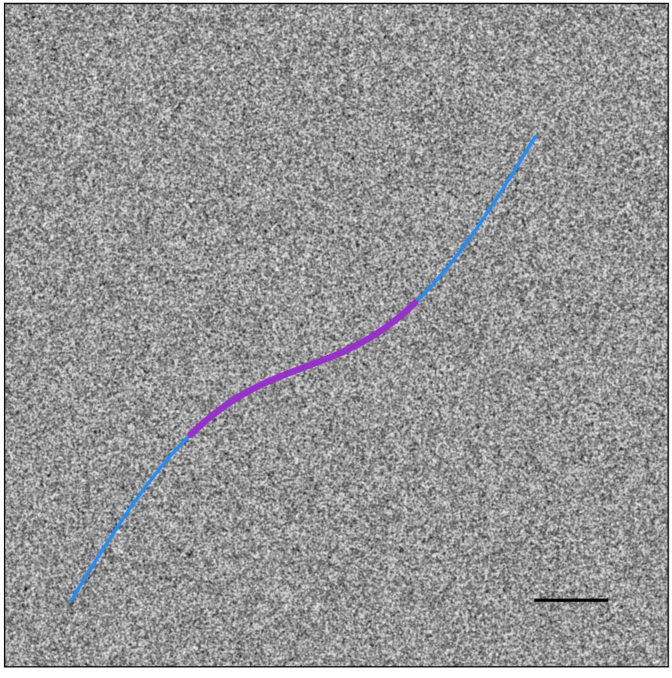

Index: BLUR: 1.0; LEVELS: 16; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

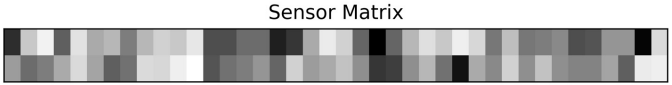


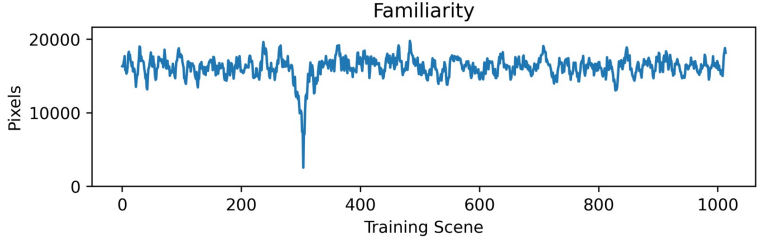


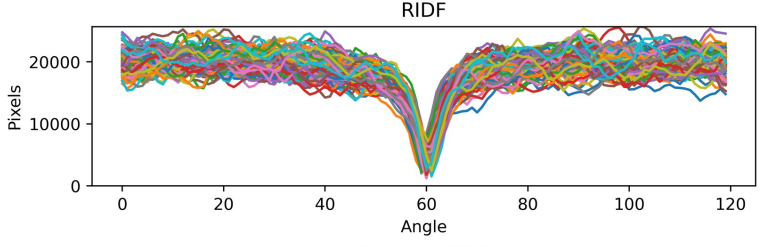
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

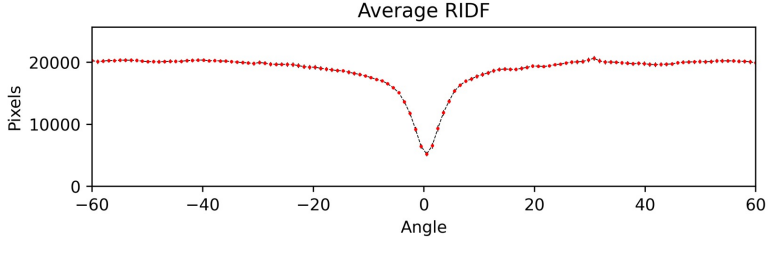
Navigation stats: RMSD error: 45.50; RMSD/dist: 0.114; TD: 9371; p90: 16; p50: 8; complete: 0





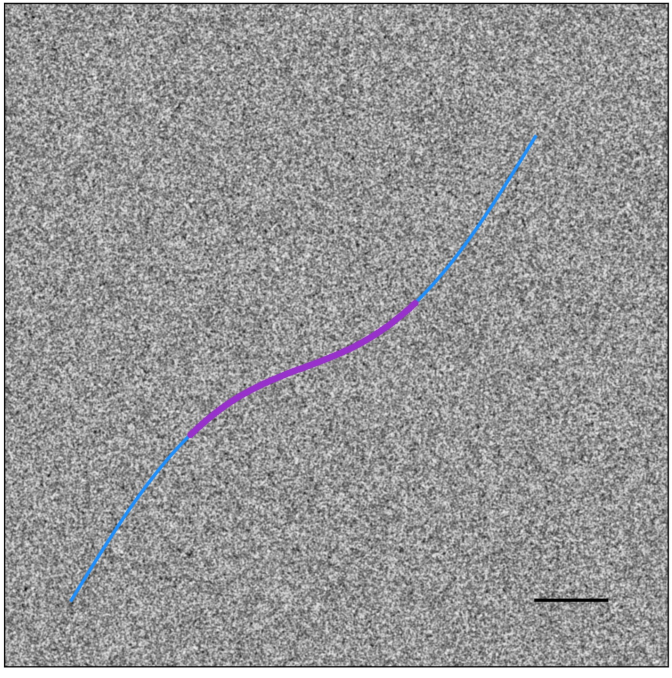


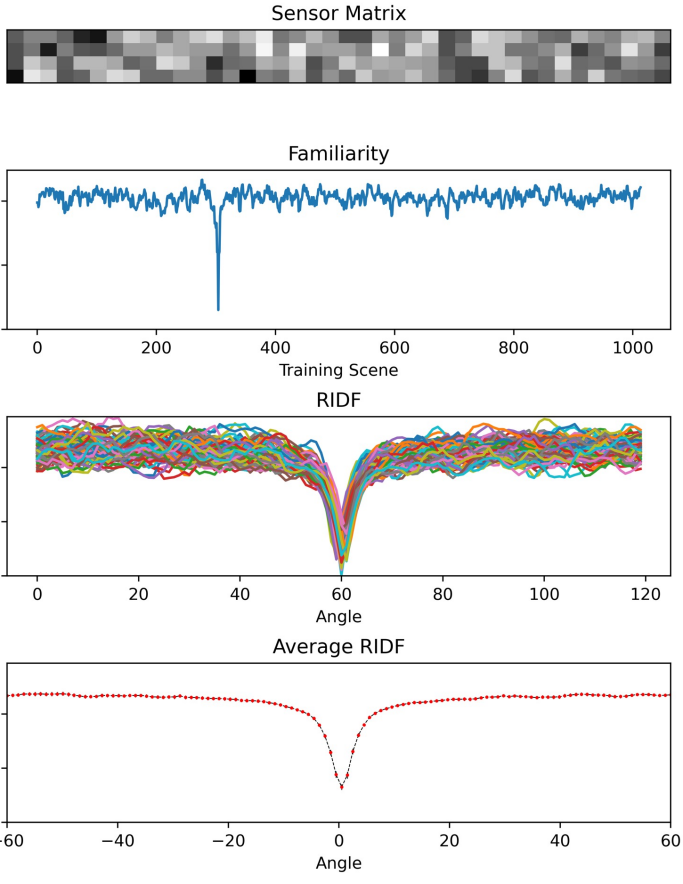




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

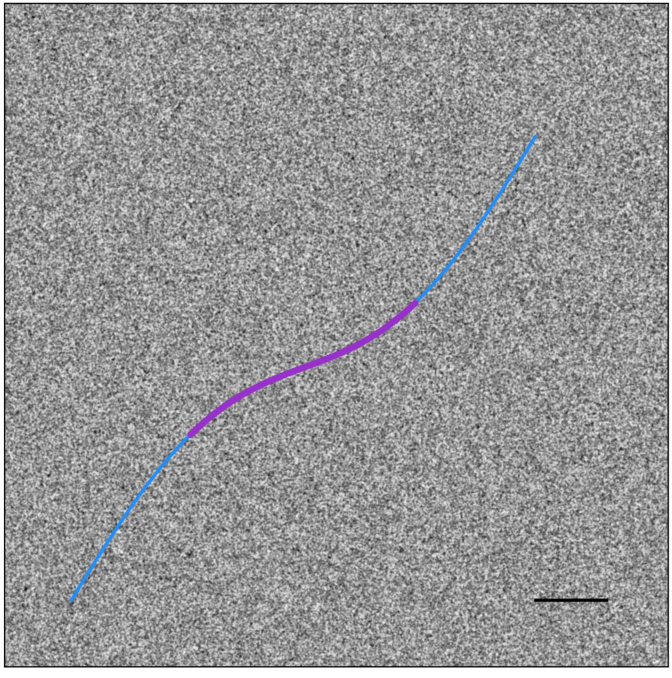
Navigation stats: RMSD error: 58.99; RMSD/dist: 0.147; TD: 11570; p90: 12; p50: 6; complete: 0

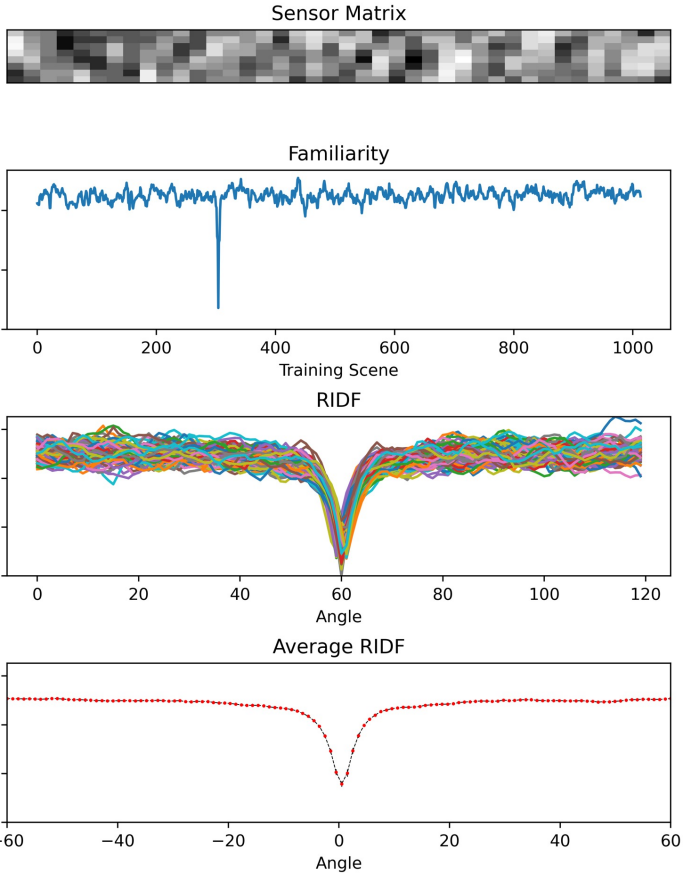




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

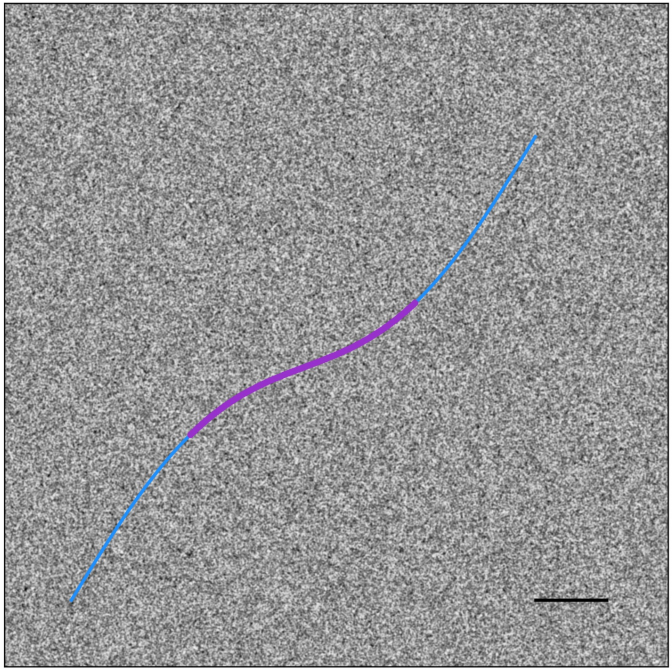
Navigation stats: RMSD error: 46.34; RMSD/dist: 0.116; TD: 13972; p90: 10; p50: 4; complete: 0

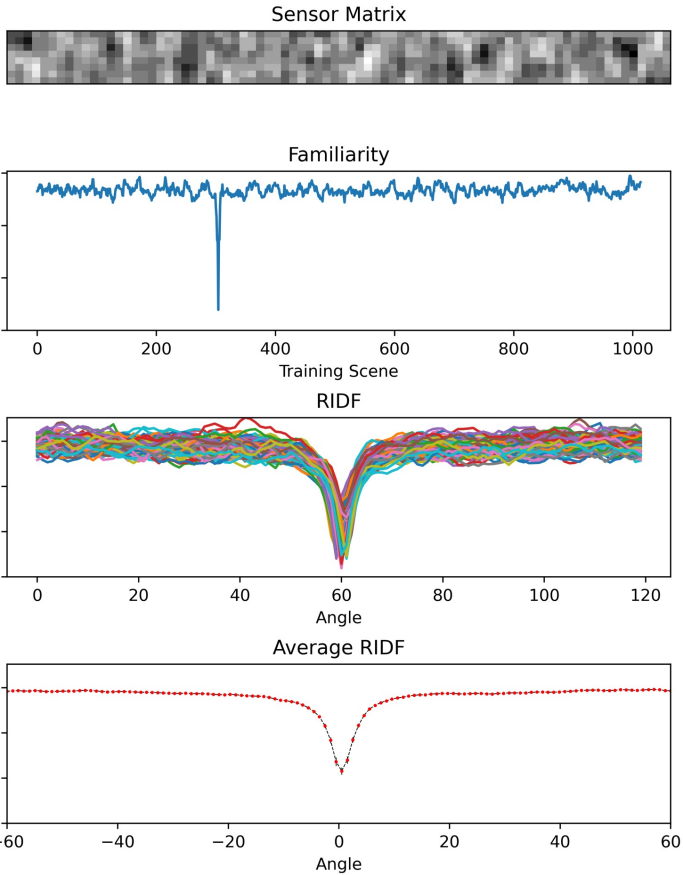




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

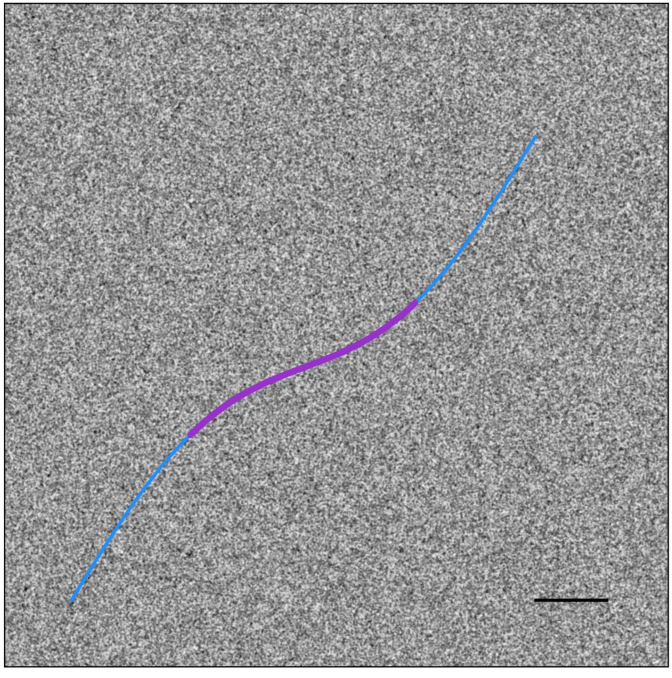
Navigation stats: RMSD error: 51.65; RMSD/dist: 0.129; TD: 14365; p90: 10; p50: 4; complete: 0

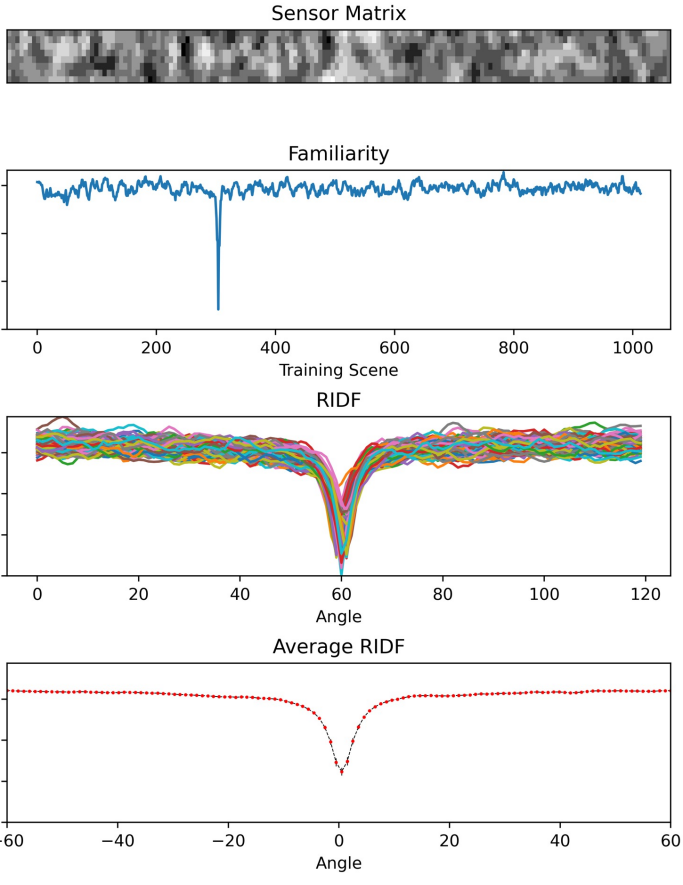




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

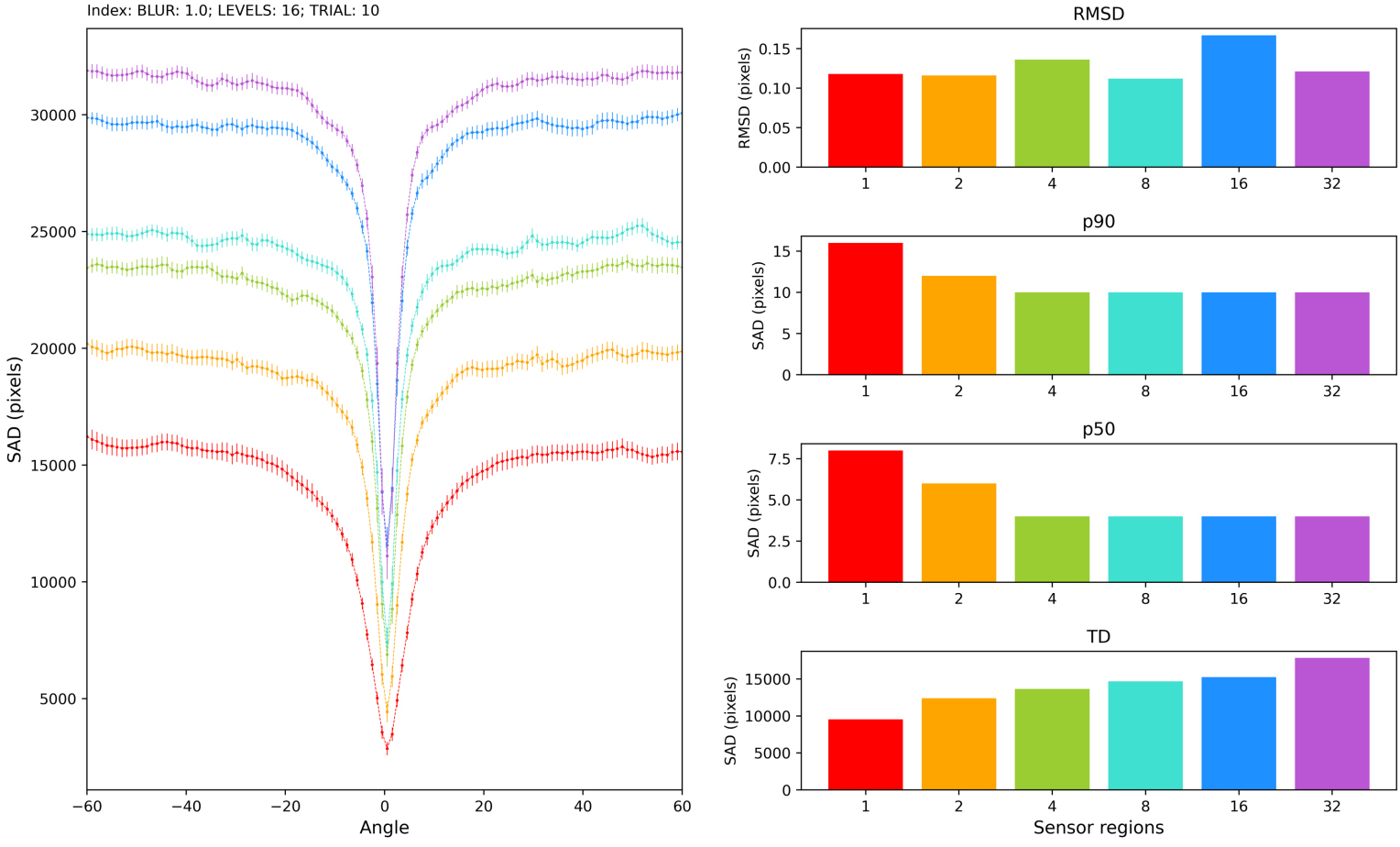
Navigation stats: RMSD error: 66.73; RMSD/dist: 0.167; TD: 15122; p90: 12; p50: 4; complete: 0

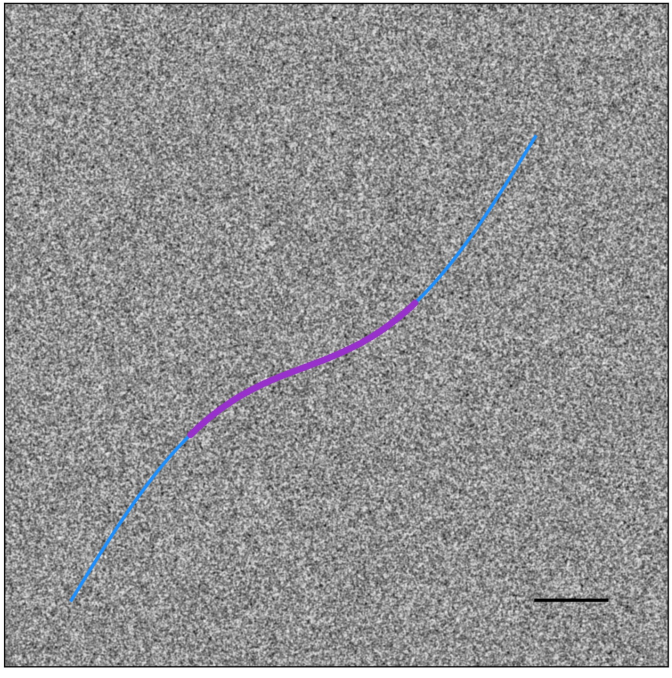


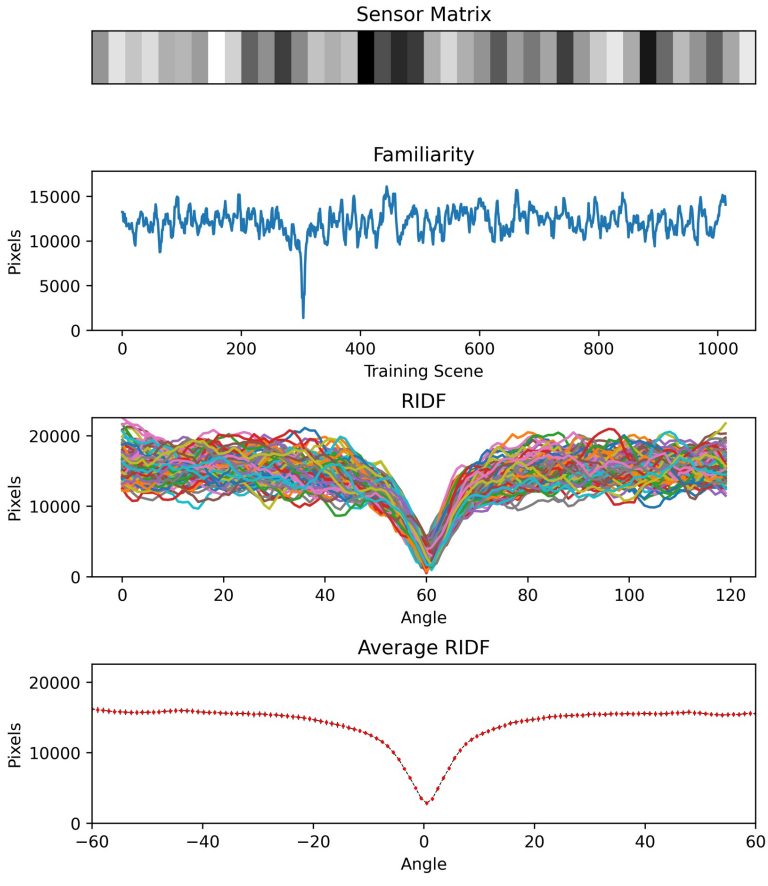


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 57.07; RMSD/dist: 0.143; TD: 16691; p90: 12; p50: 4; complete: 0

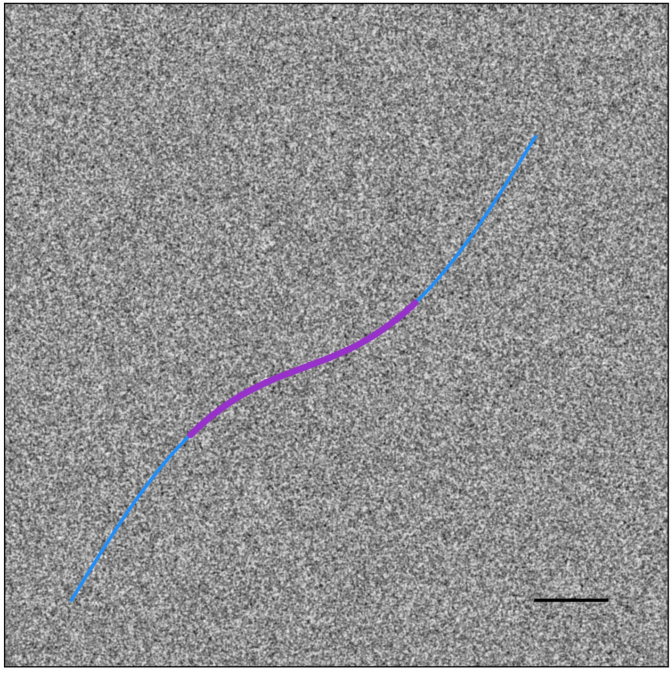

Index: BLUR: 1.0; LEVELS: 16; TRIAL: 10
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

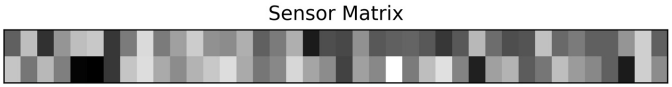


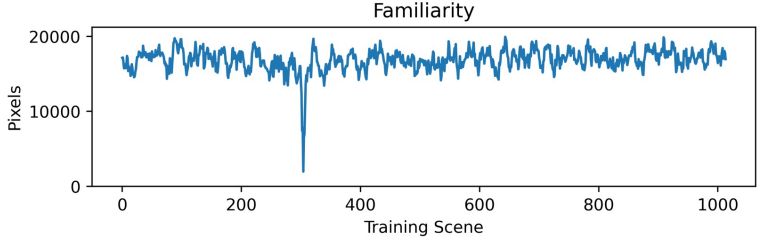


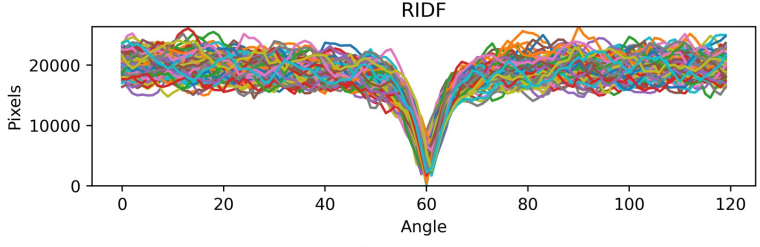
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

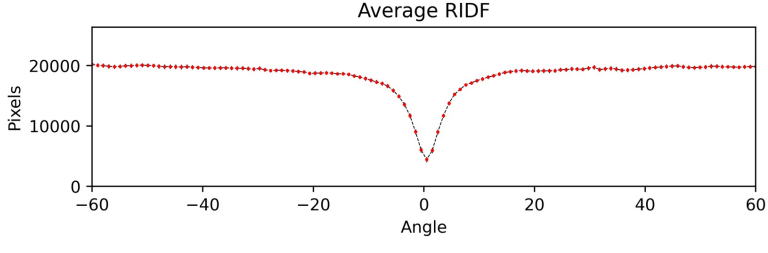
Navigation stats: RMSD error: 47.23; RMSD/dist: 0.118; TD: 9535; p90: 16; p50: 8; complete: 0





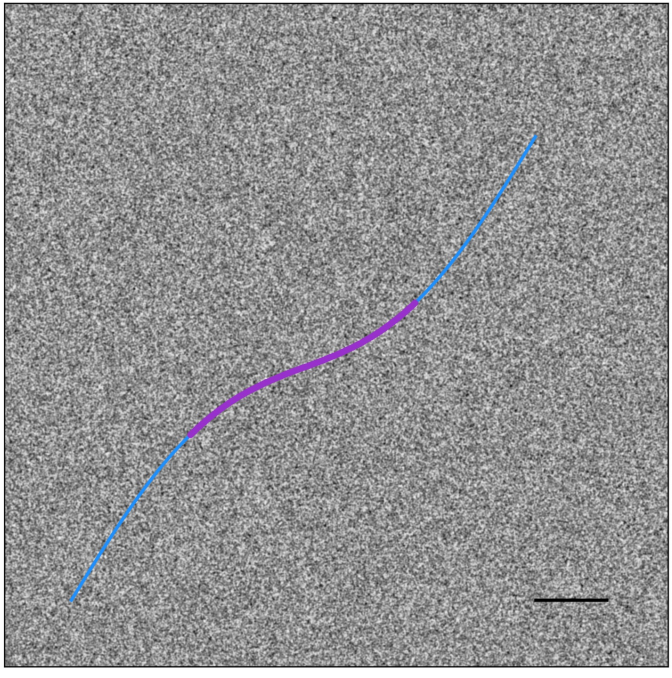


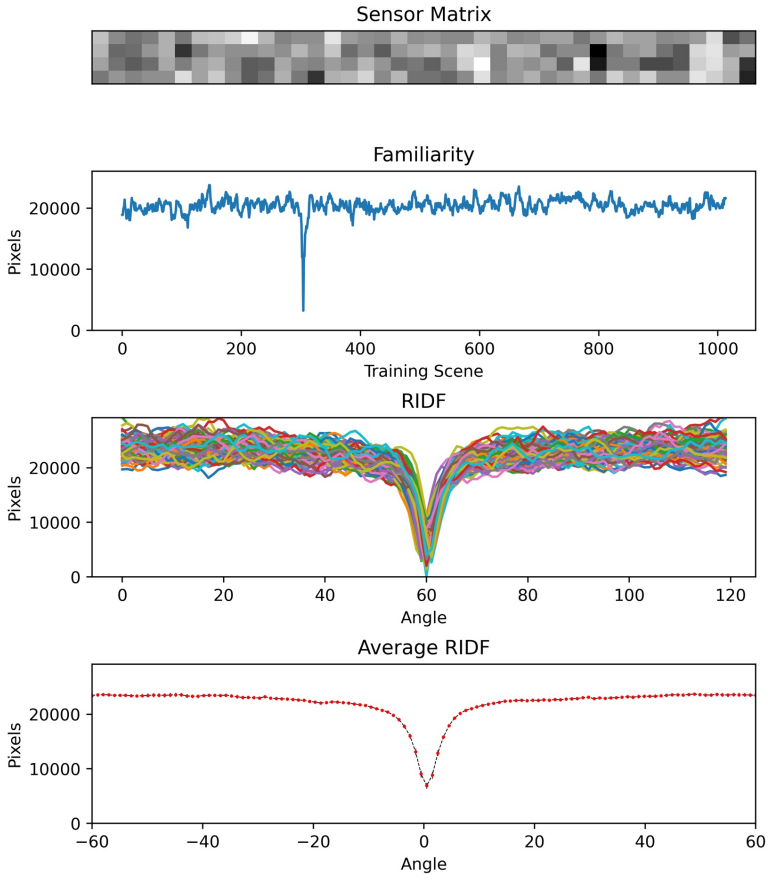




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

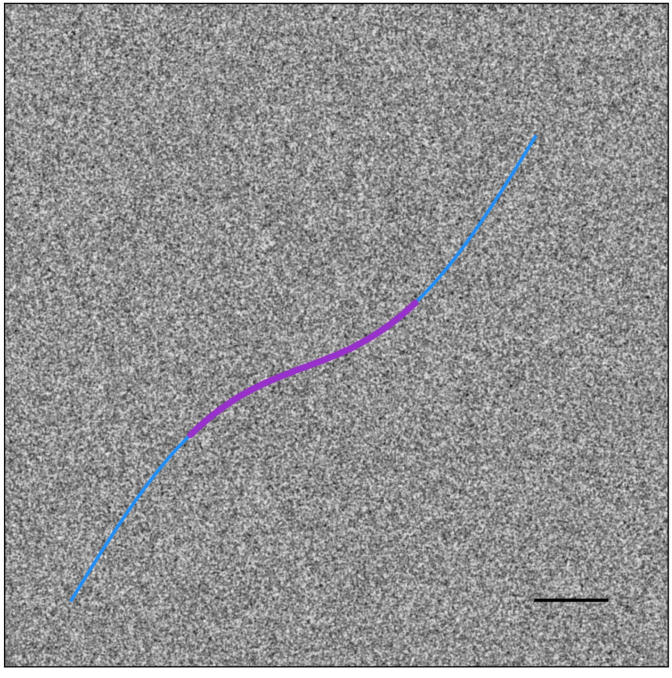
Navigation stats: RMSD error: 46.55; RMSD/dist: 0.116; TD: 12382; p90: 12; p50: 6; complete: 0

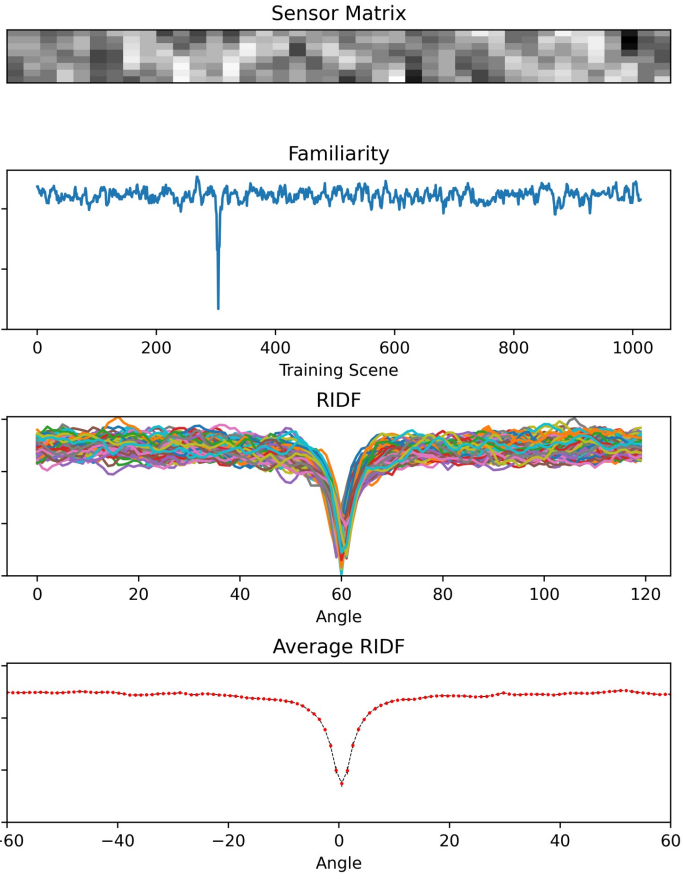




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

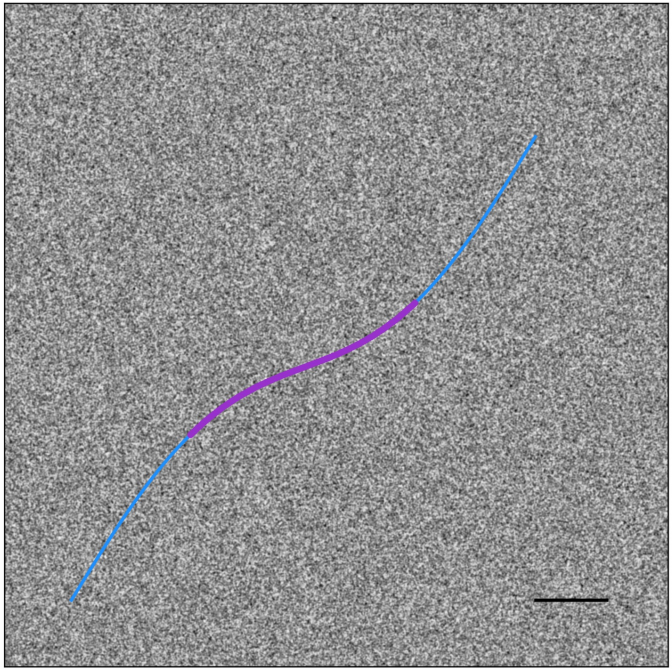
Navigation stats: RMSD error: 54.29; RMSD/dist: 0.136; TD: 13636; p90: 10; p50: 4; complete: 0

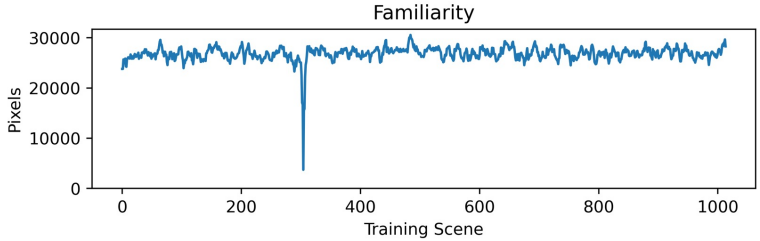


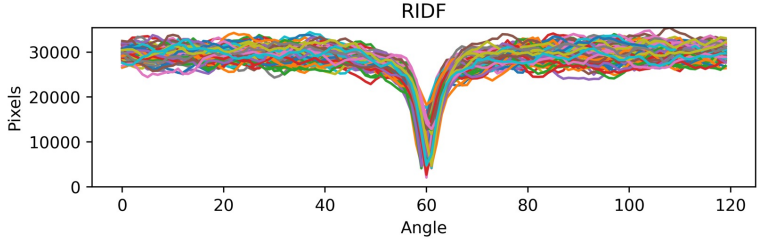


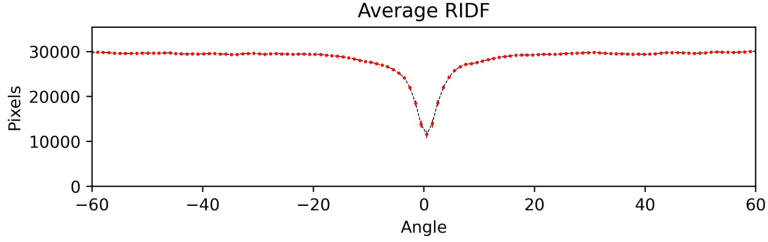
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 44.72; RMSD/dist: 0.112; TD: 14666; p90: 10; p50: 4; complete: 0



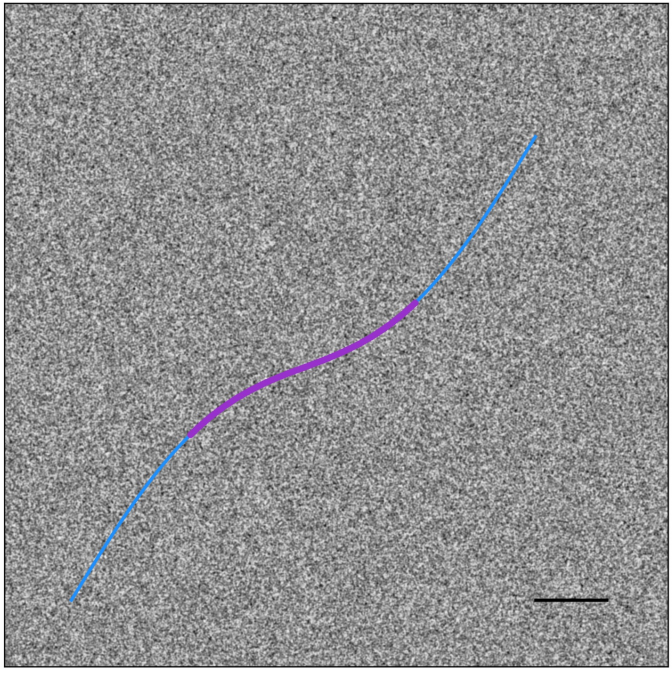


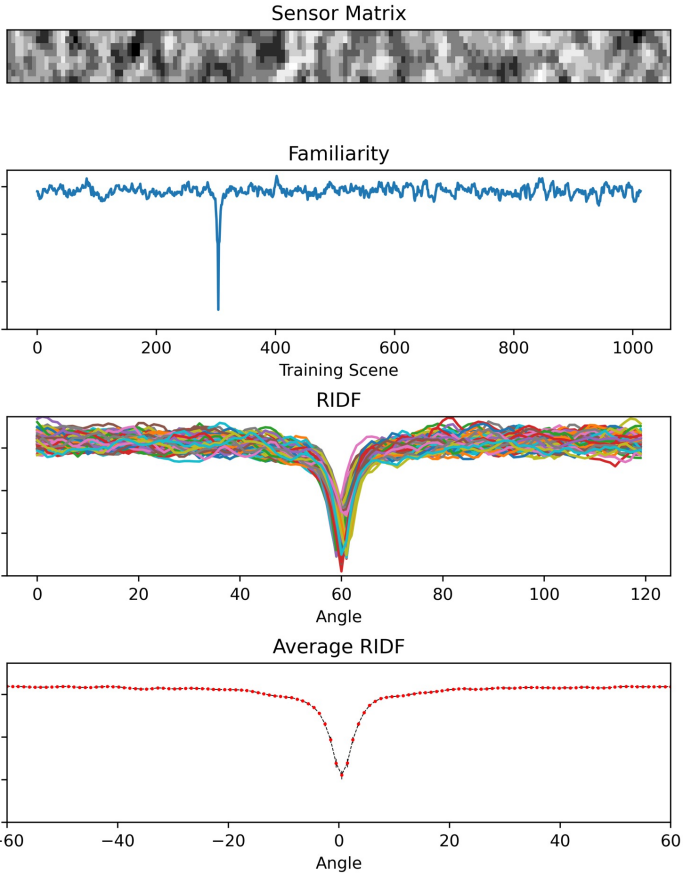




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 66.89; RMSD/dist: 0.167; TD: 15245; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 48.43; RMSD/dist: 0.121; TD: 17831; p90: 10; p50: 4; complete: 0