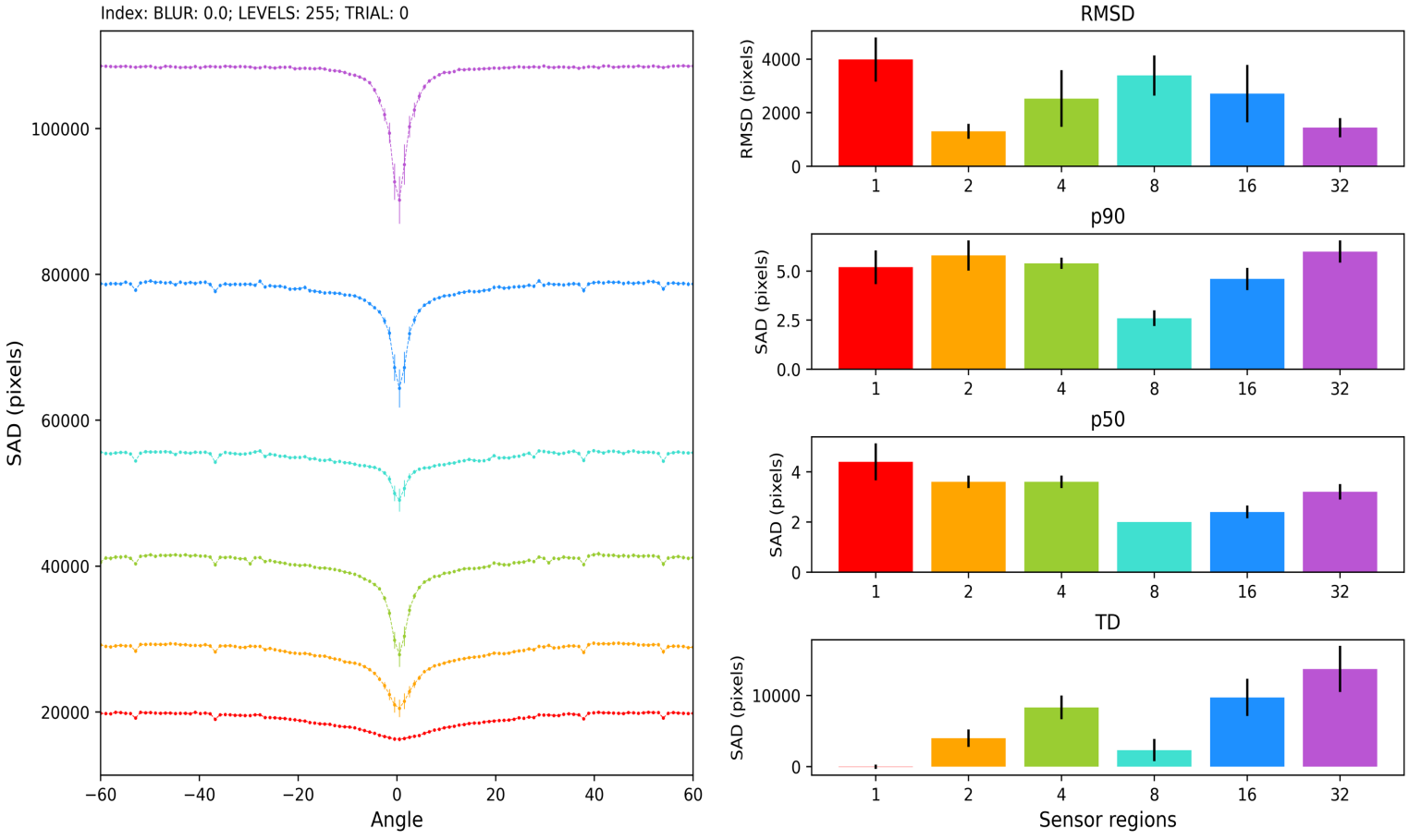
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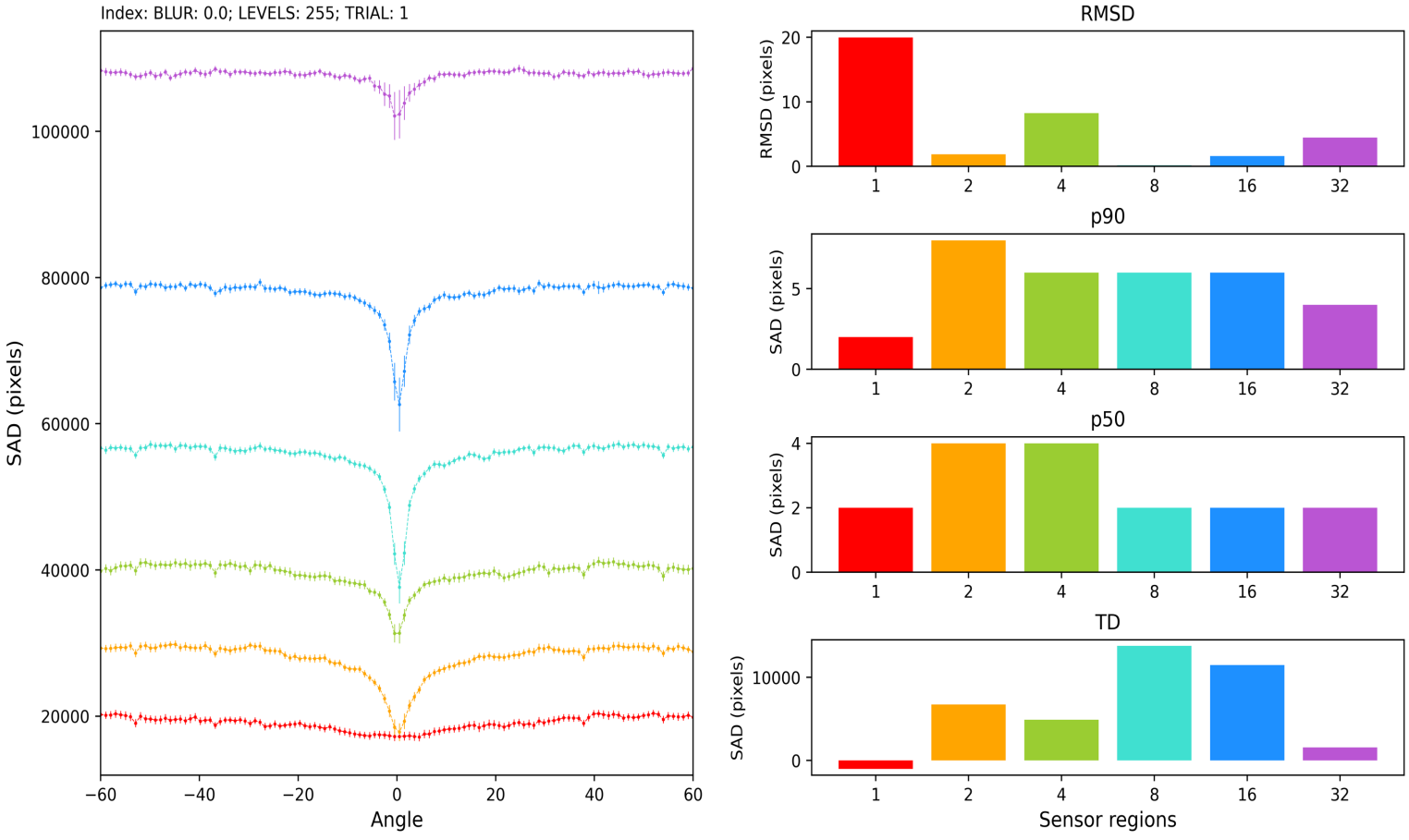
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4000
2000
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
4
2
TD
10000
Sensor regions


Index: BLUR: 0.0; LEVELS: 255; TRIAL: 1
SAD (pixels)
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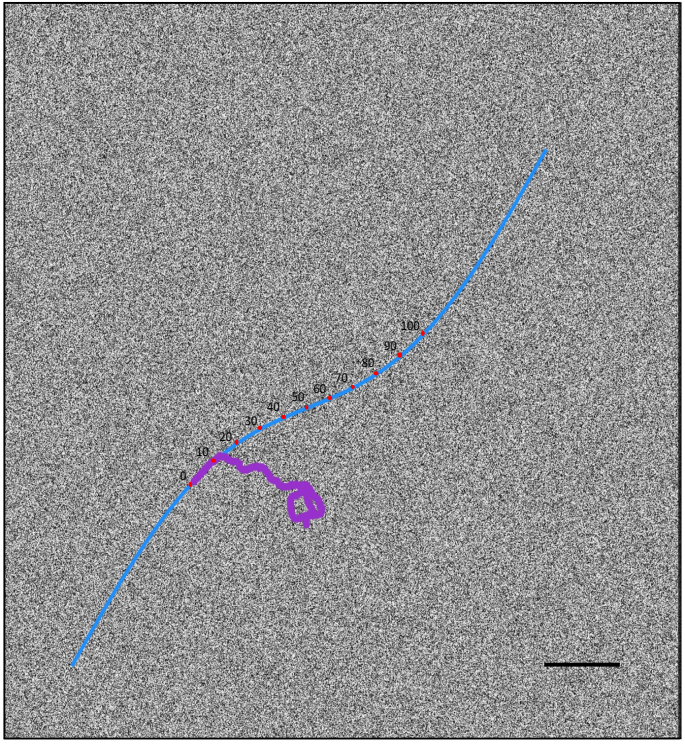
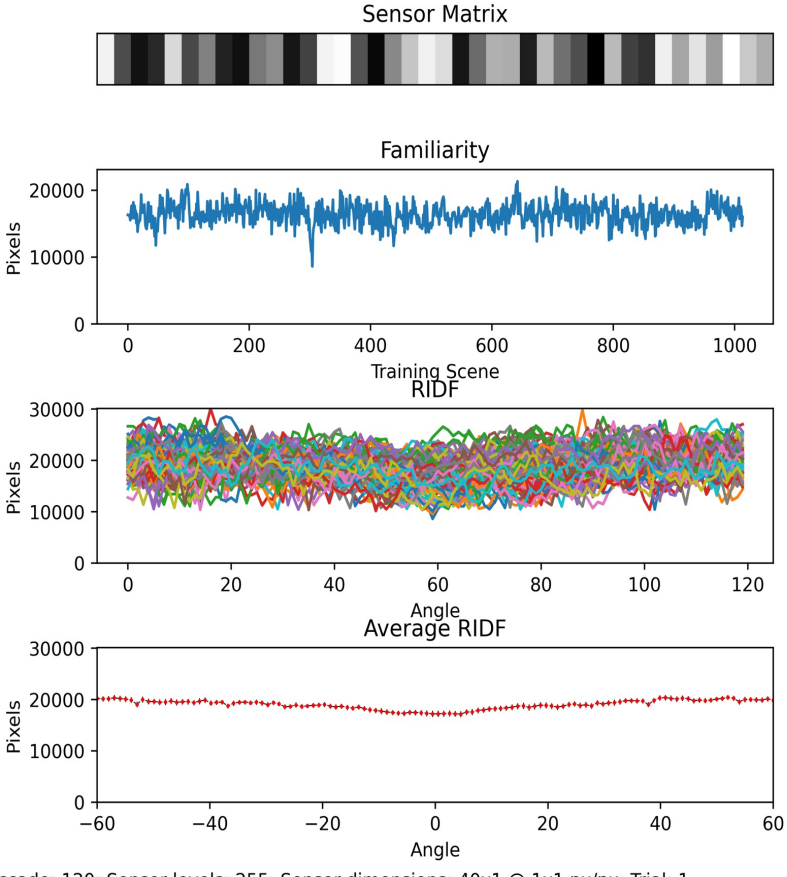
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
4
2
0
TD
SAD (pixels)
10000
0
Sensor regions

10%

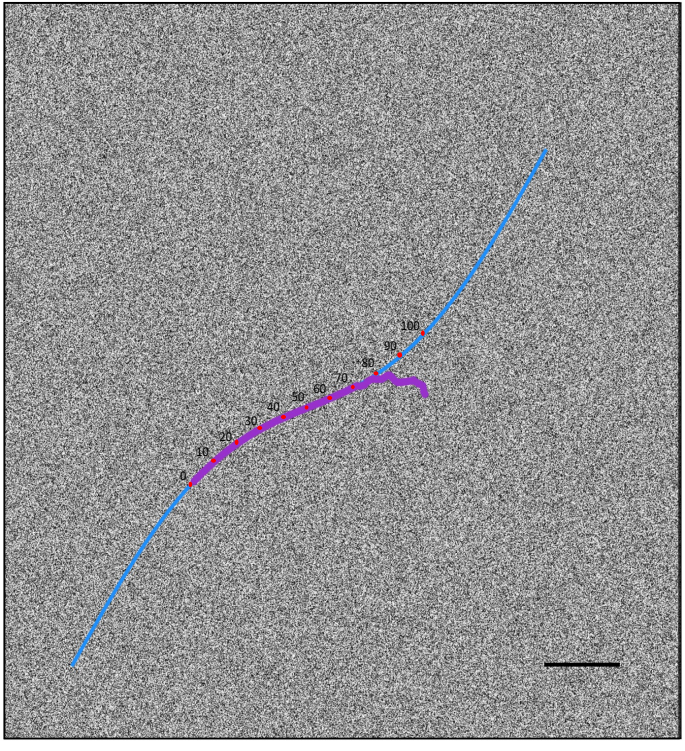


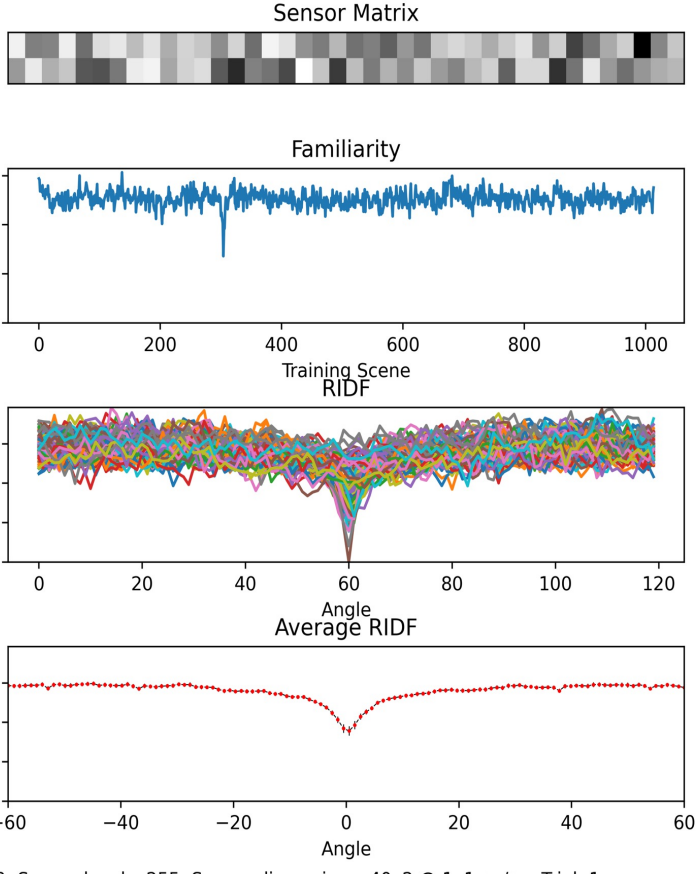


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 7993.87; RMSD/dist: 19.985; TD: -1023; p90: 2; p50: 2; complete: 0

70%

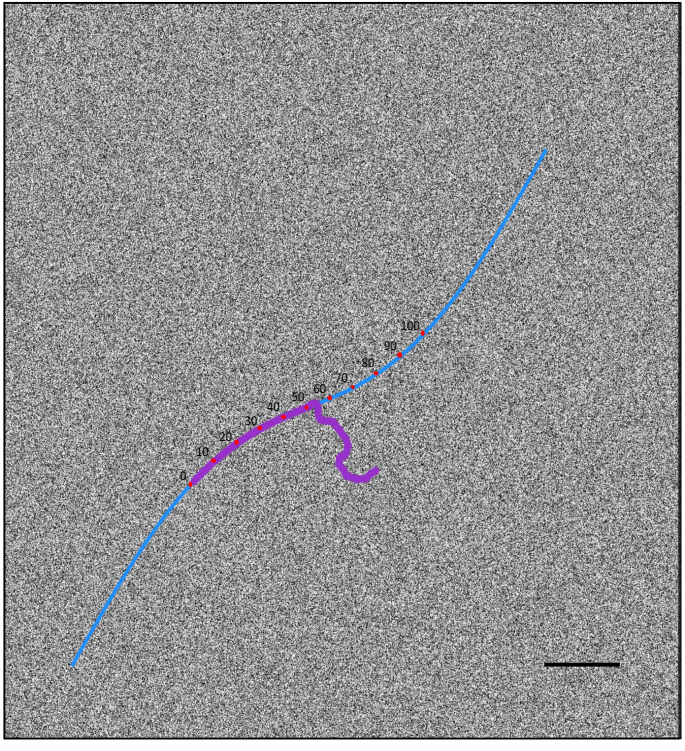


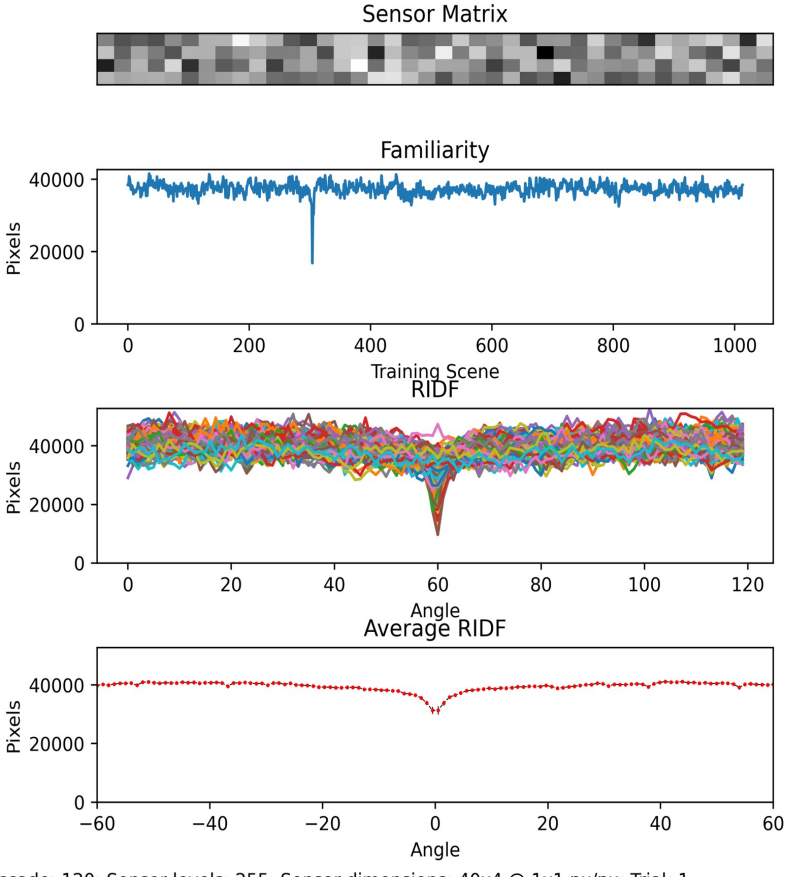


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 739.73; RMSD/dist: 1.849; TD: 6732; p90: 8; p50: 4; complete: 0

50%

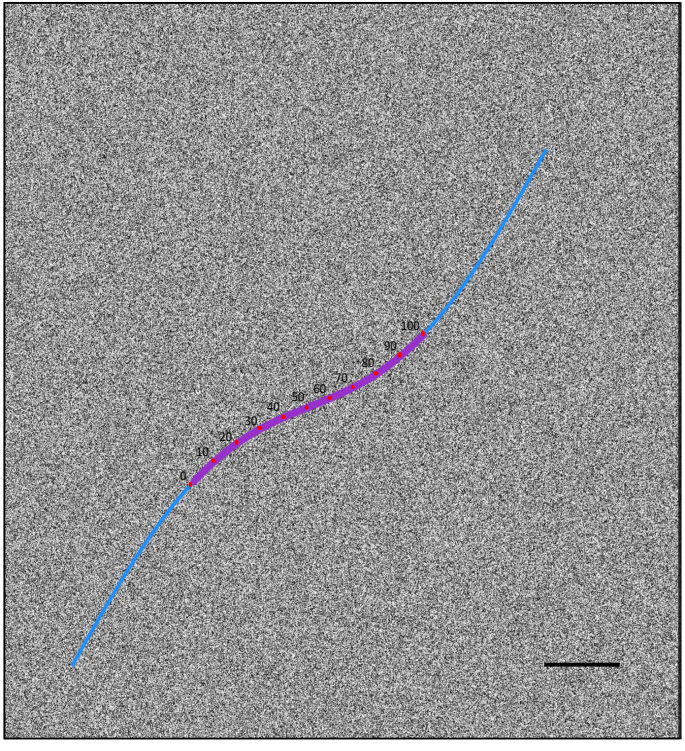


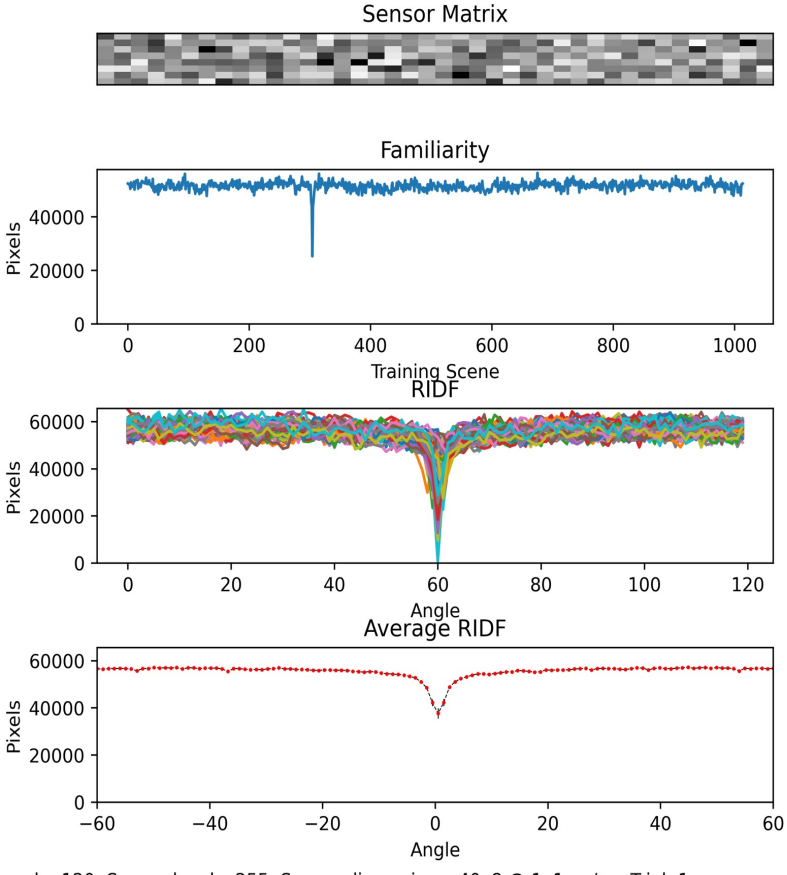


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3289.73; RMSD/dist: 8.224; TD: 4883; p90: 6; p50: 4; complete: 0

100%

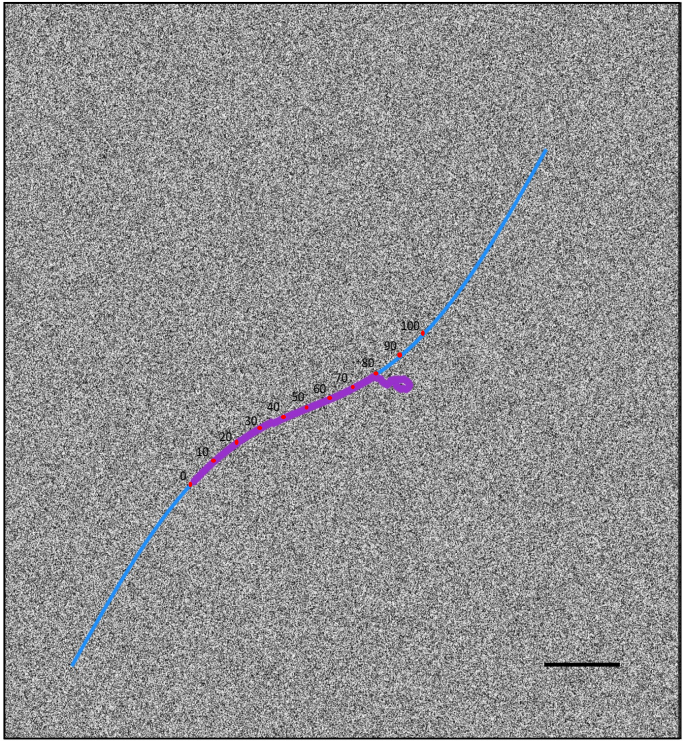


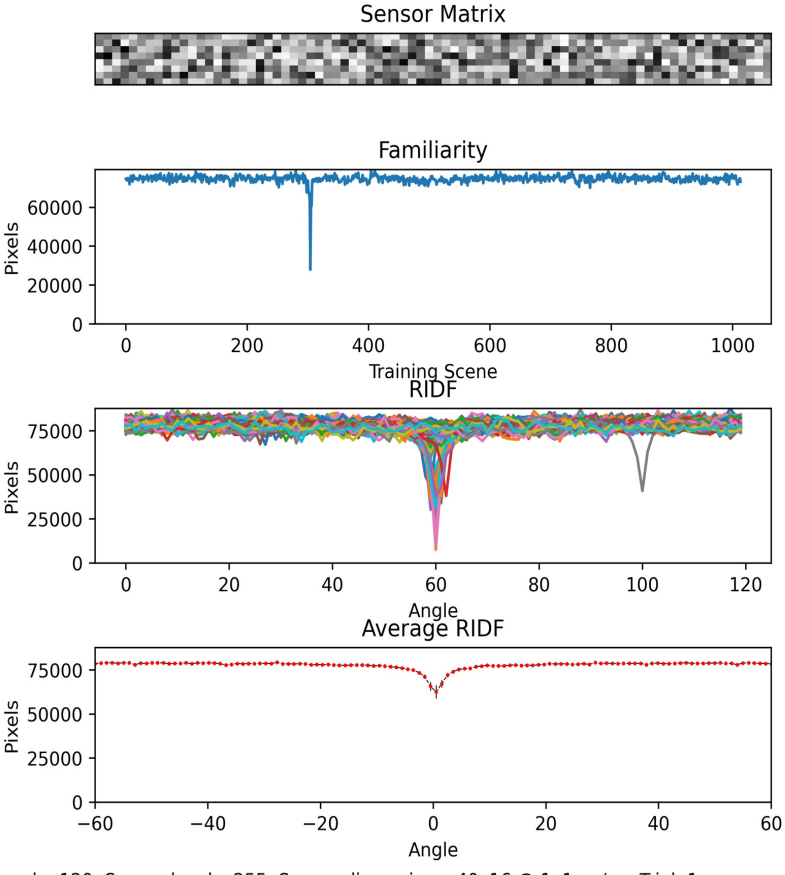


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 55.02; RMSD/dist: 0.138; TD: 13773; p90: 6; p50: 2; complete: 0

70%

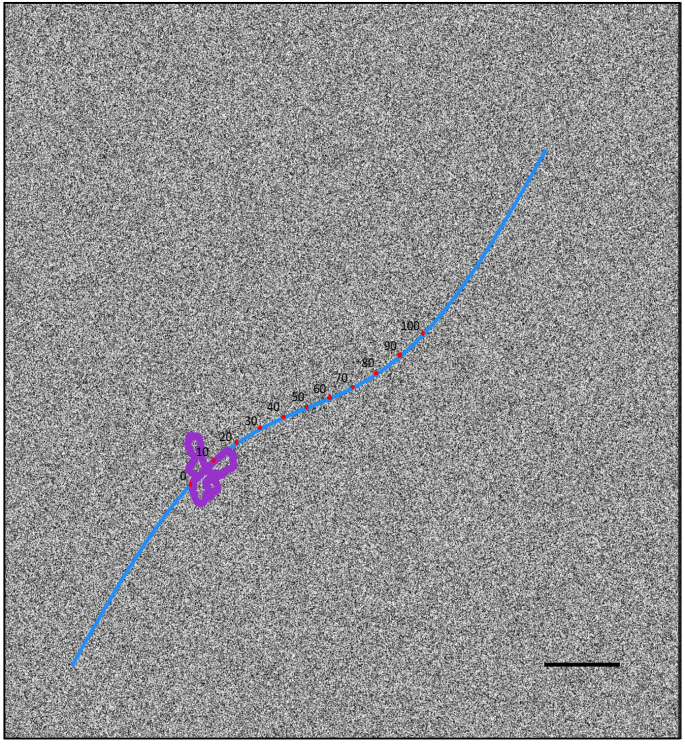


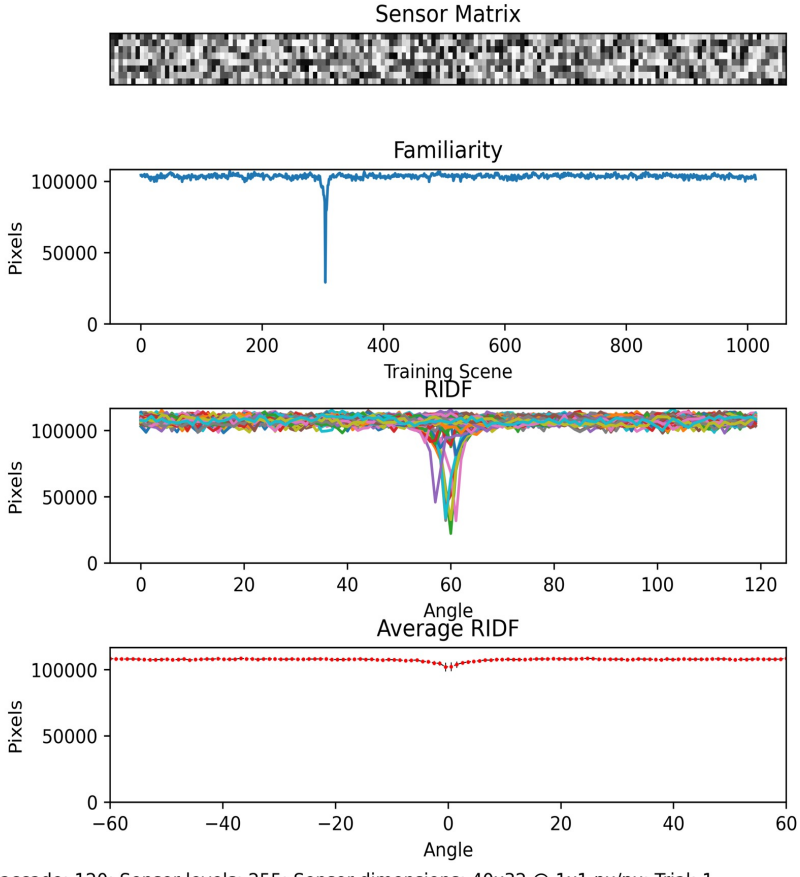


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 627.34; RMSD/dist: 1.568; TD: 11480; p90: 6; p50: 2; complete: 0

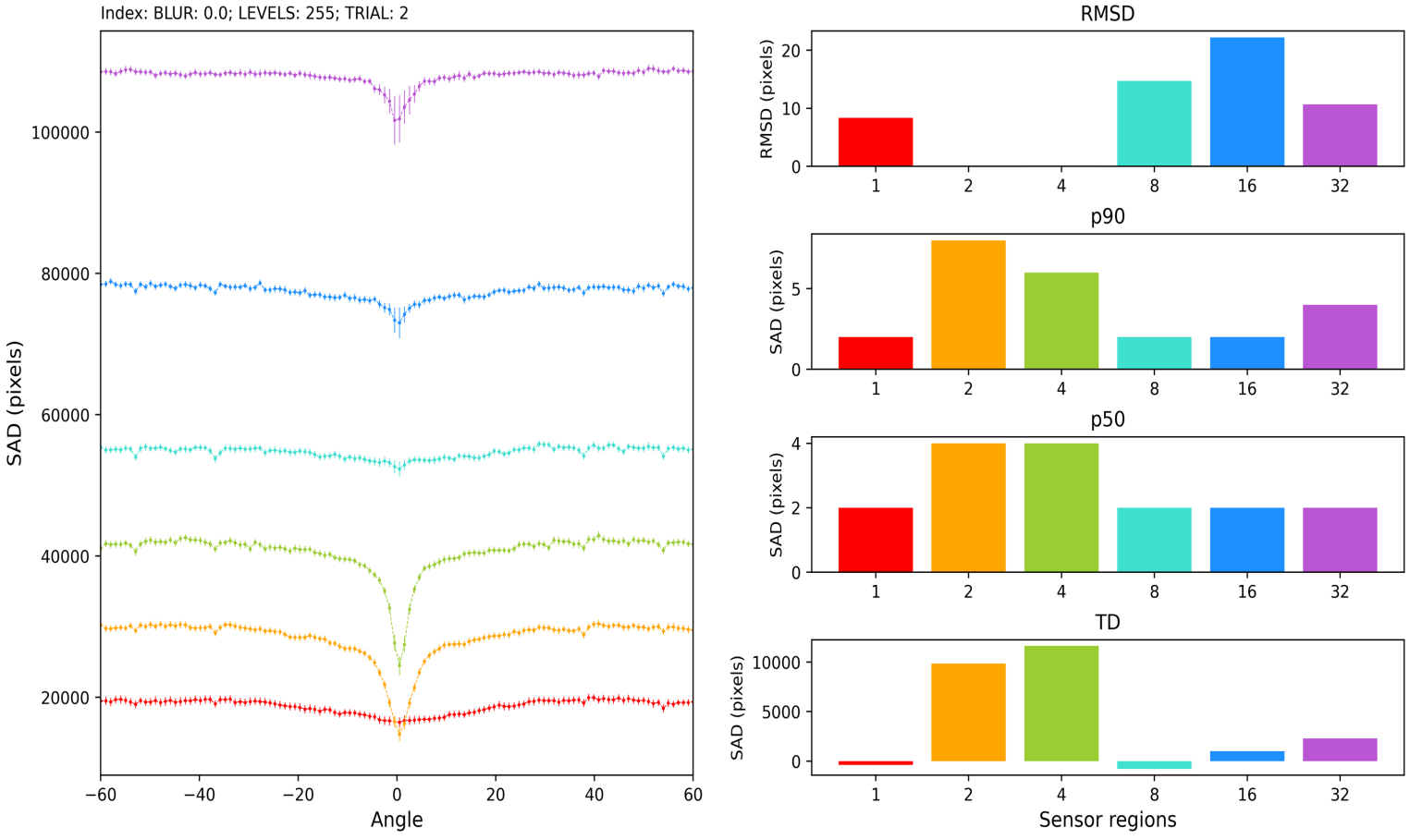
10%



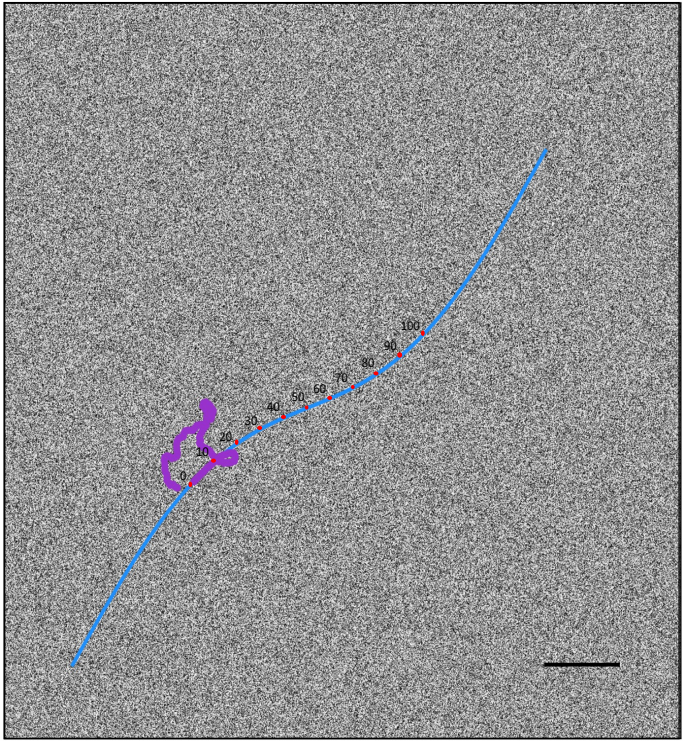


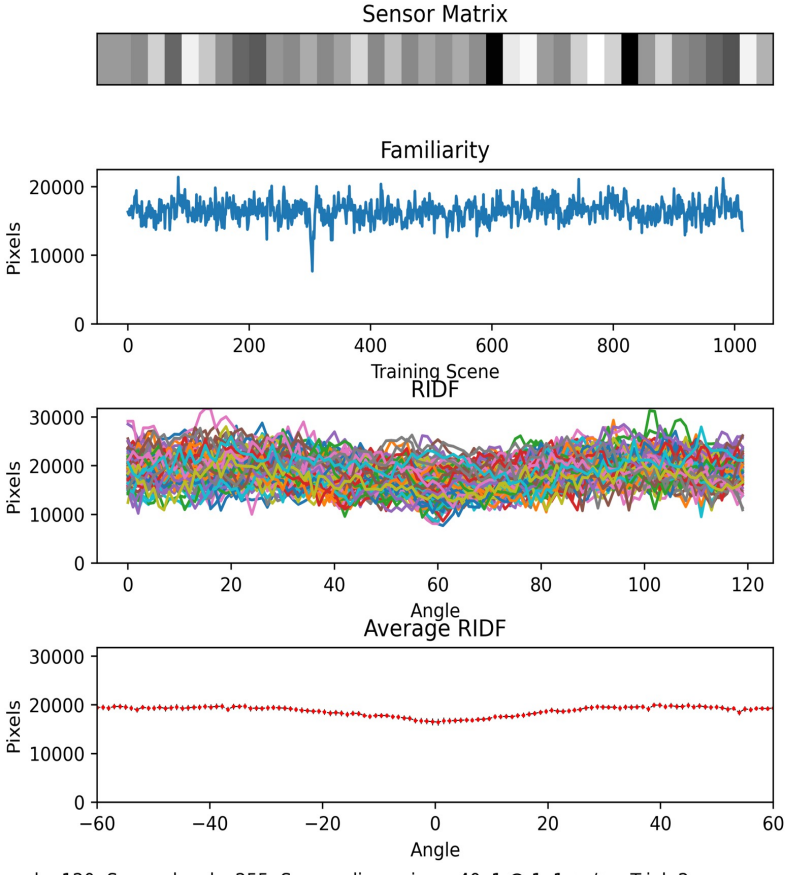
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1774.87; RMSD/dist: 4.437; TD: 1574; p90: 4; p50: 2; complete: 0


Index: BLUR: 0.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
4
2
0
TD
SAD (pixels)
10000
5000
0
Sensor regions

10%

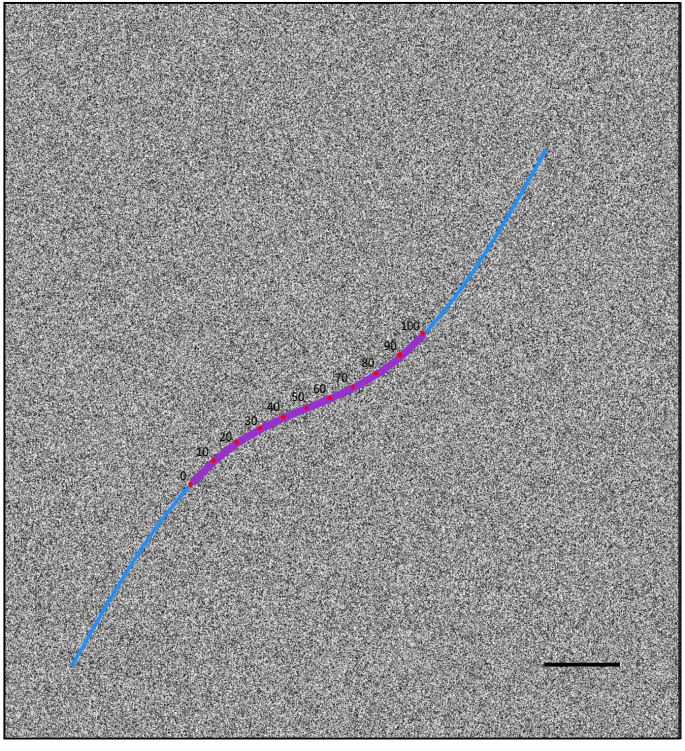


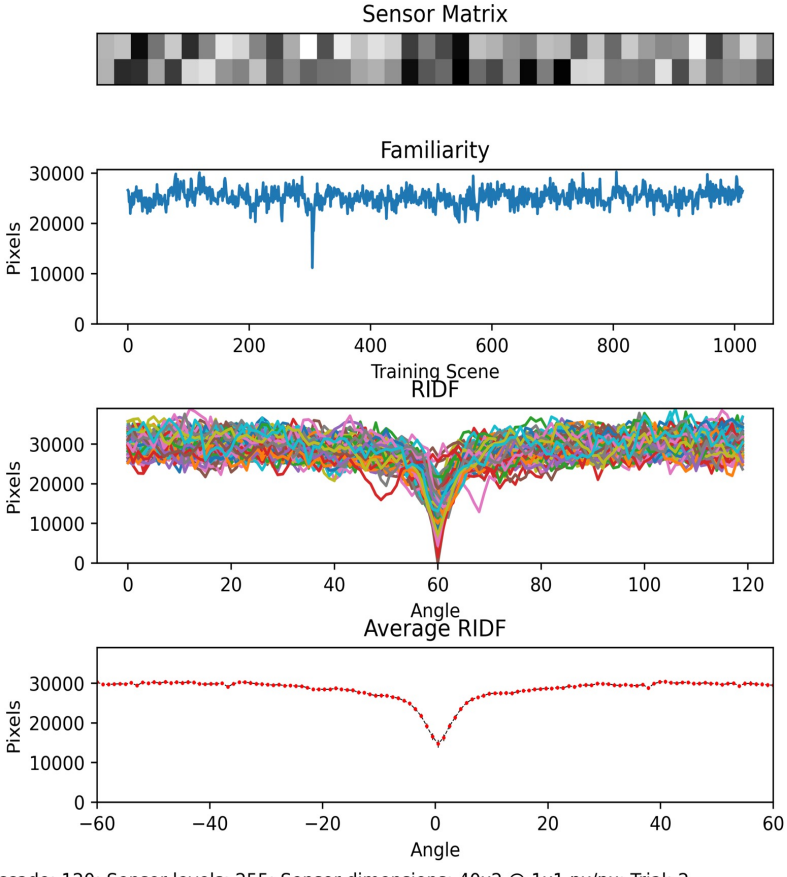


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 3334.55; RMSD/dist: 8.336; TD: -371; p90: 2; p50: 2; complete: 0

100%

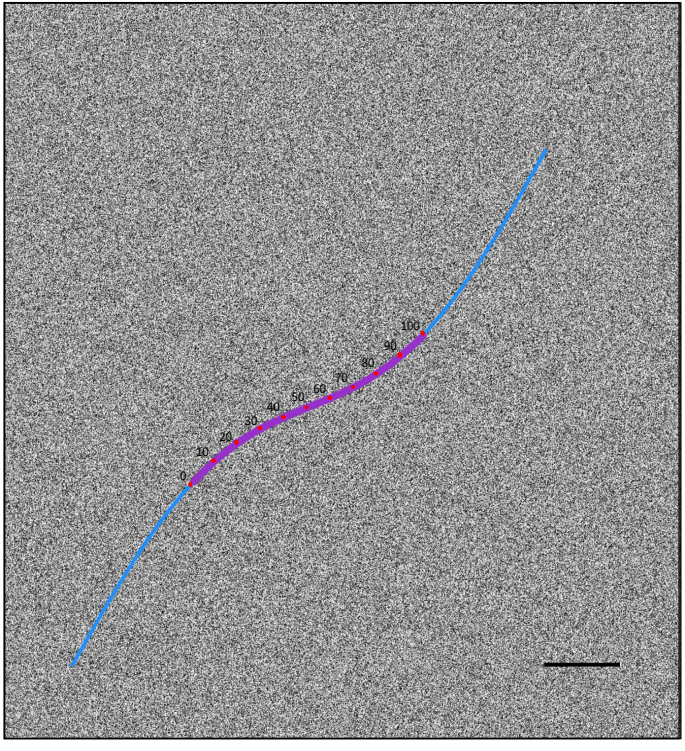


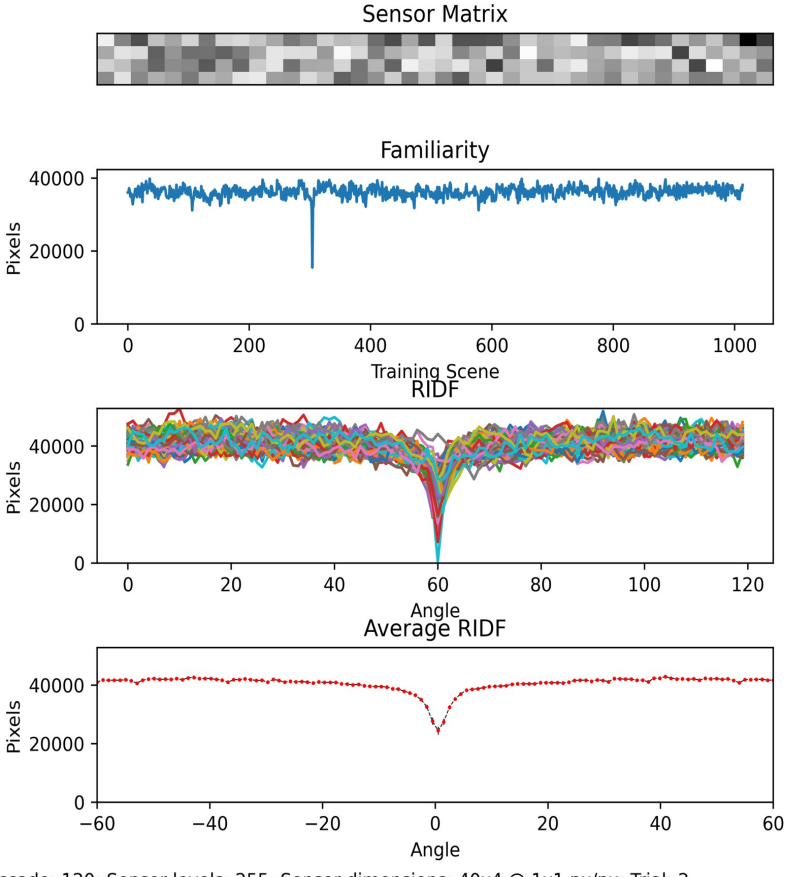


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 36.84; RMSD/dist: 0.092; TD: 9858; p90: 8; p50: 4; complete: 0

100%

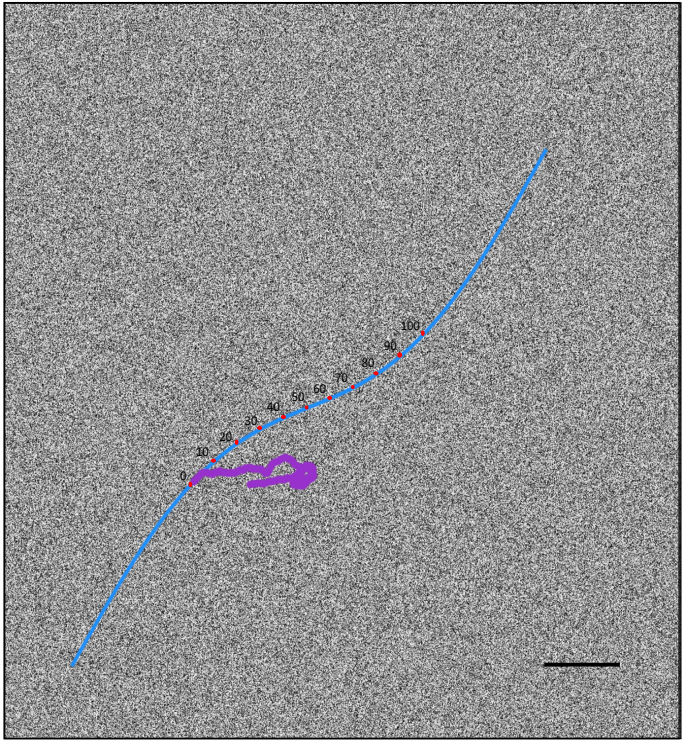


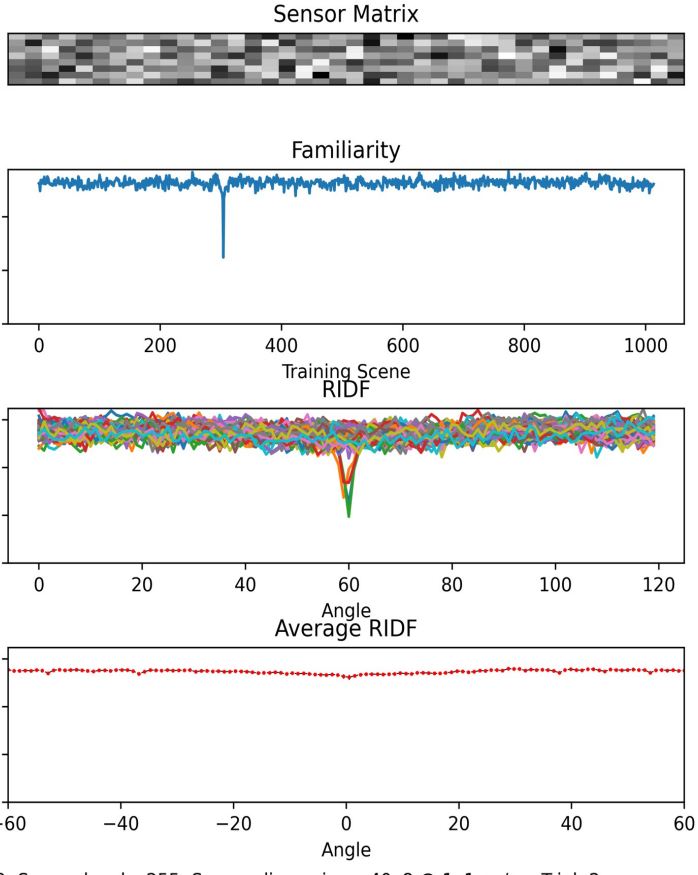


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 48.88; RMSD/dist: 0.122; TD: 11631; p90: 6; p50: 4; complete: 0

0%

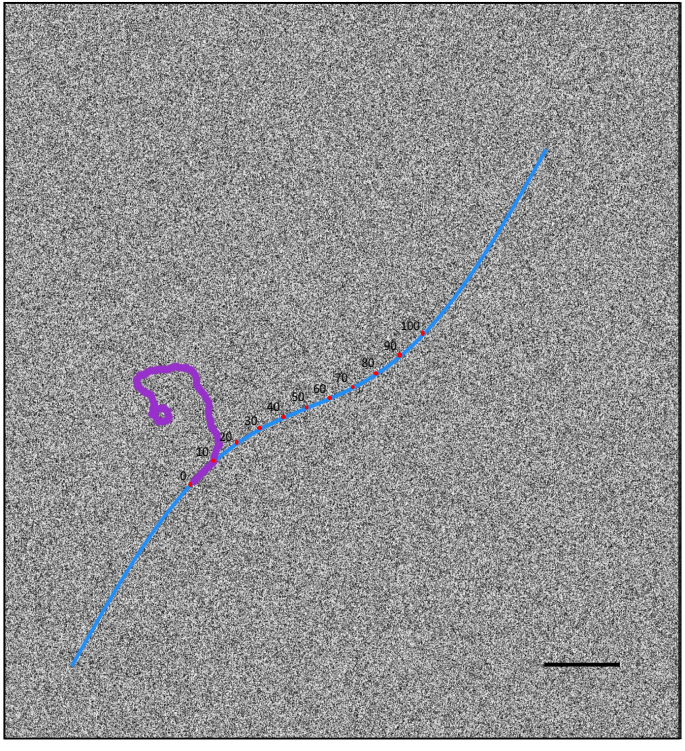


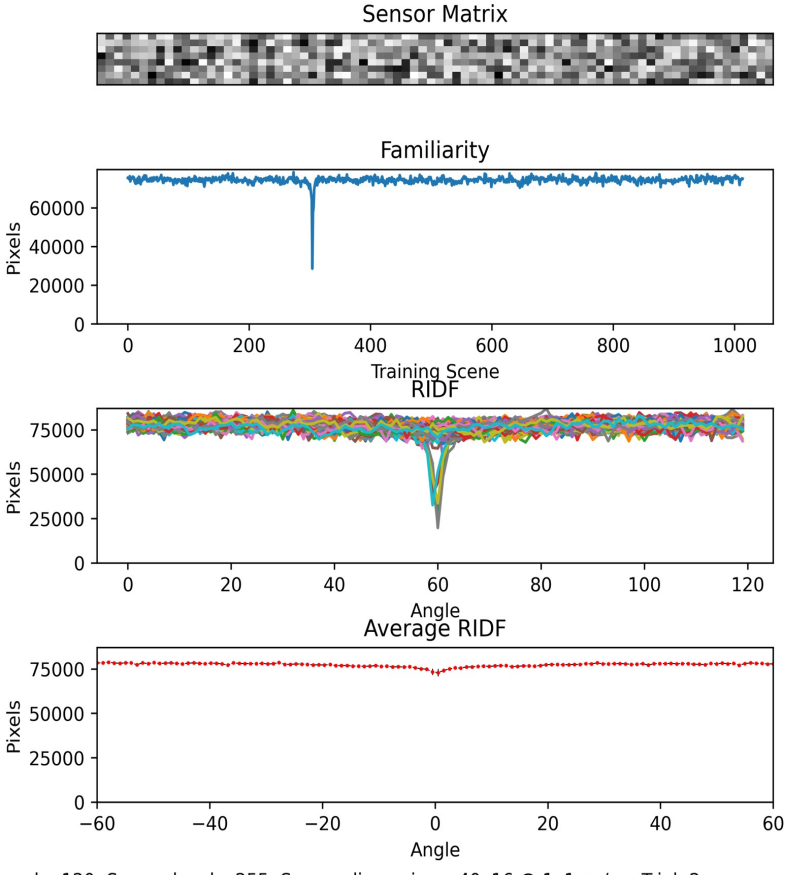


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 5879.82; RMSD/dist: 14.700; TD: -782; p90: 2; p50: 2; complete: 0

10%

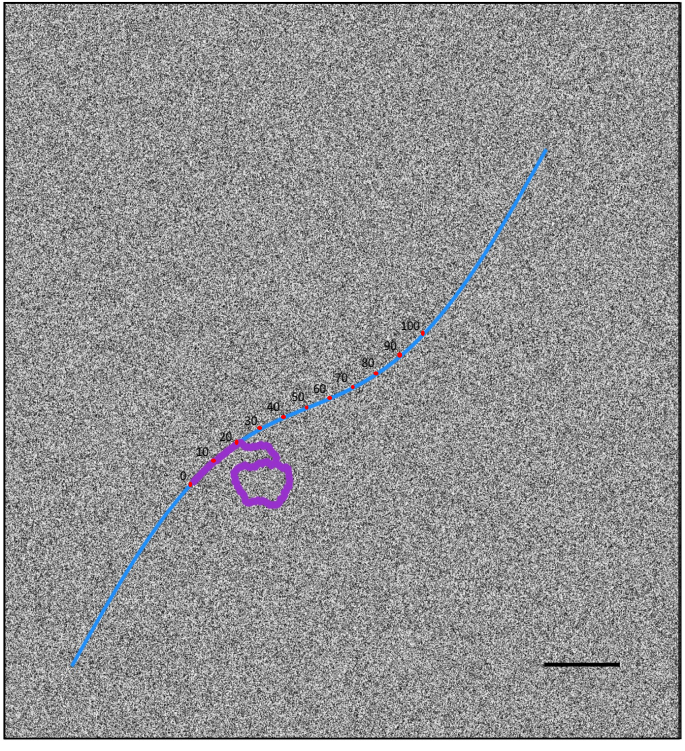


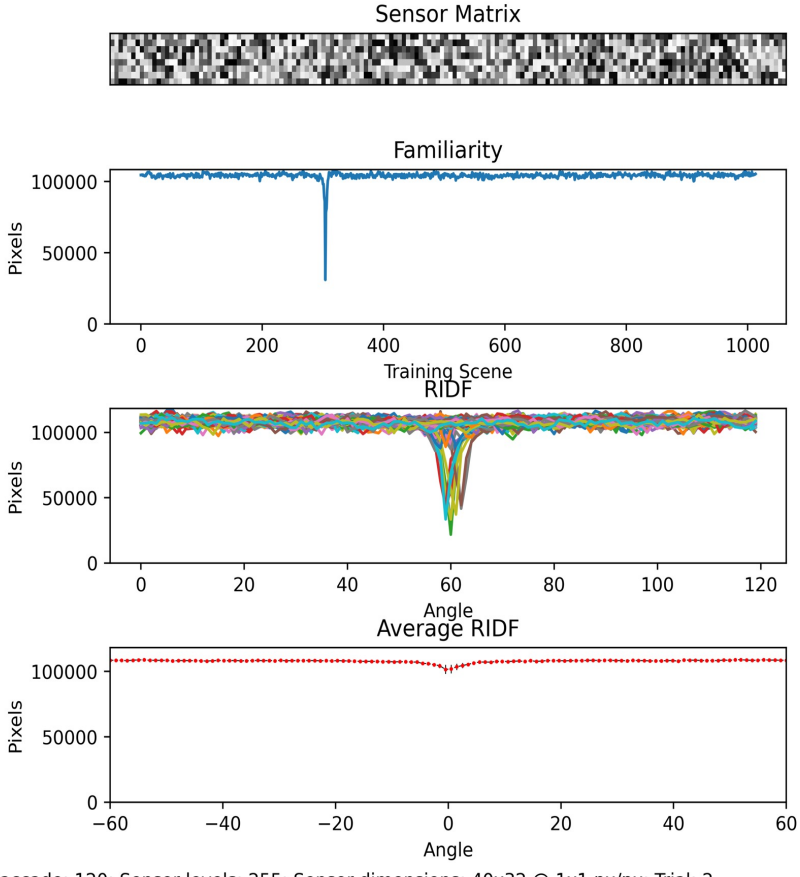


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 8890.76; RMSD/dist: 22.227; TD: 996; p90: 2; p50: 2; complete: 0

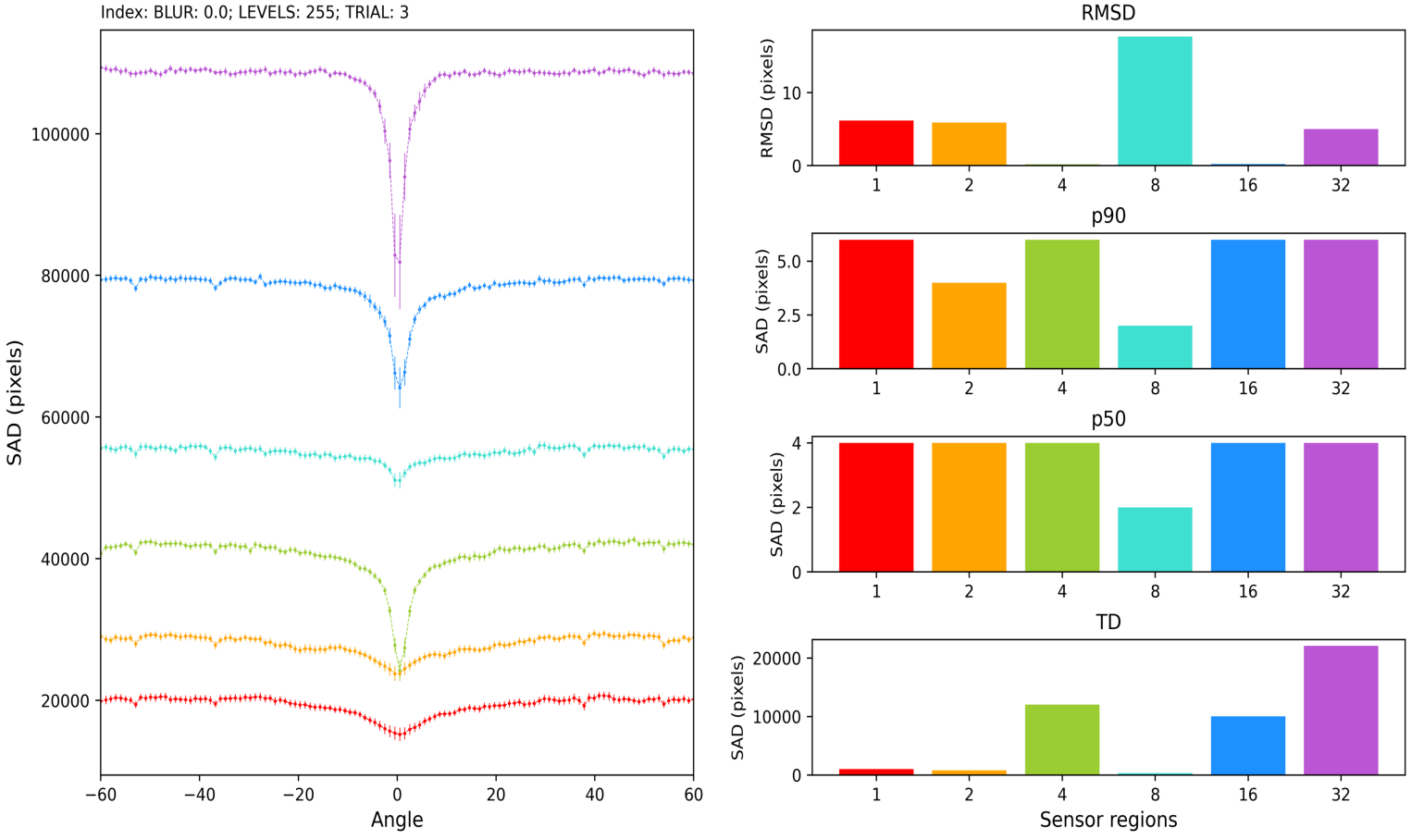
20%



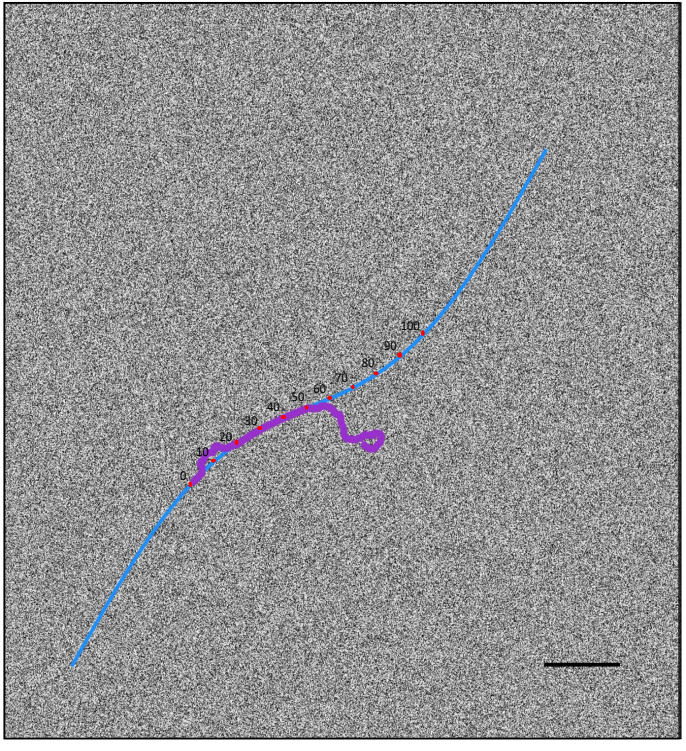


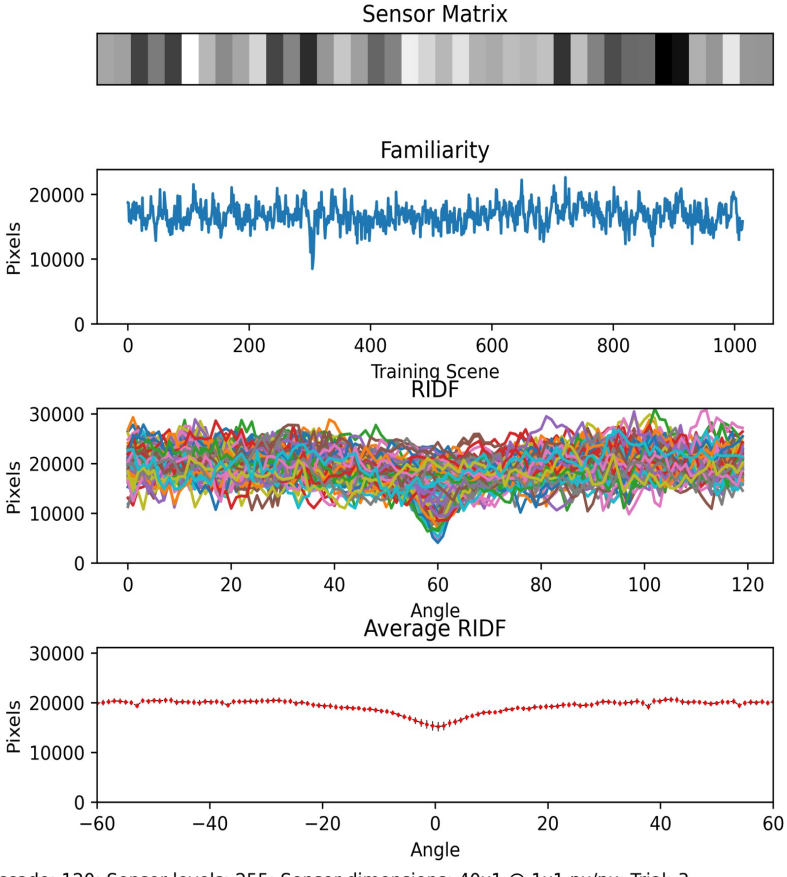
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 4269.91; RMSD/dist: 10.675; TD: 2291; p90: 4; p50: 2; complete: 0


Index: BLUR: 0.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
4
2
TD
20000
10000
Sensor regions

30%

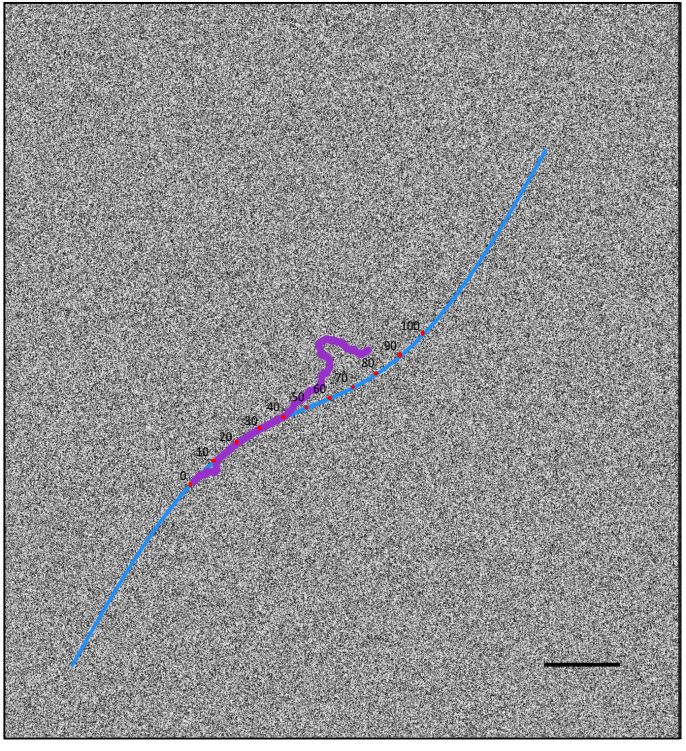


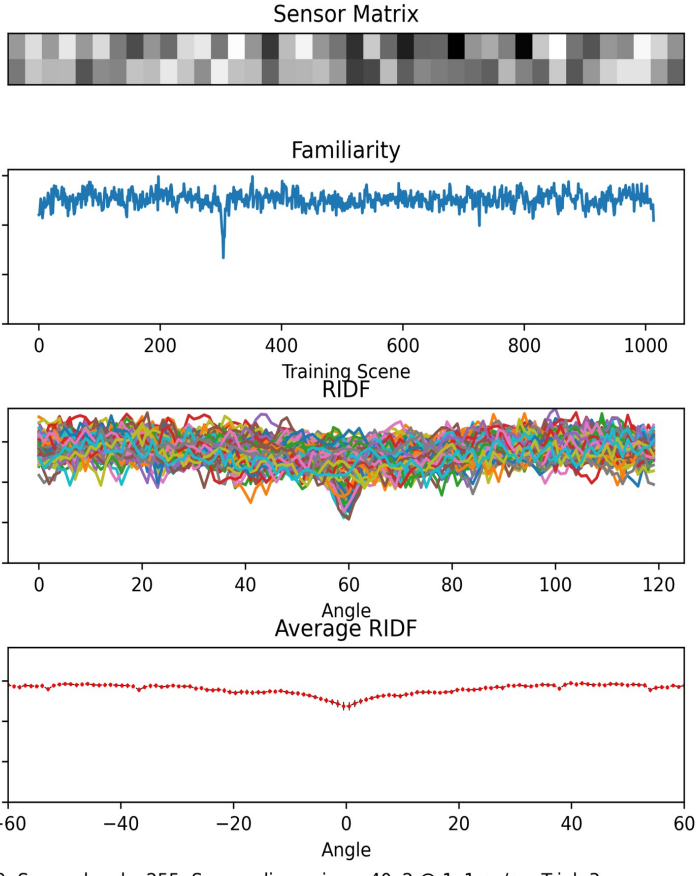


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2460.11; RMSD/dist: 6.150; TD: 990; p90: 6; p50: 4; complete: 0

30%

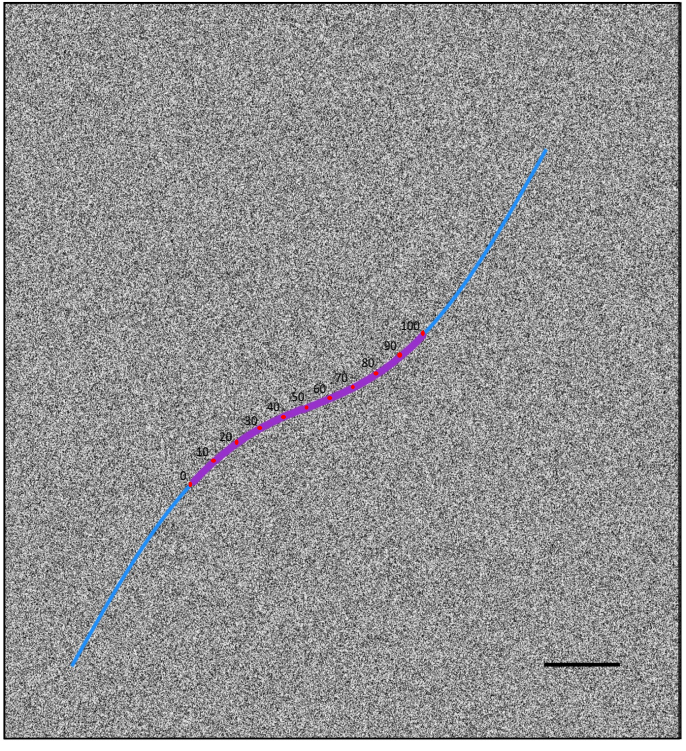


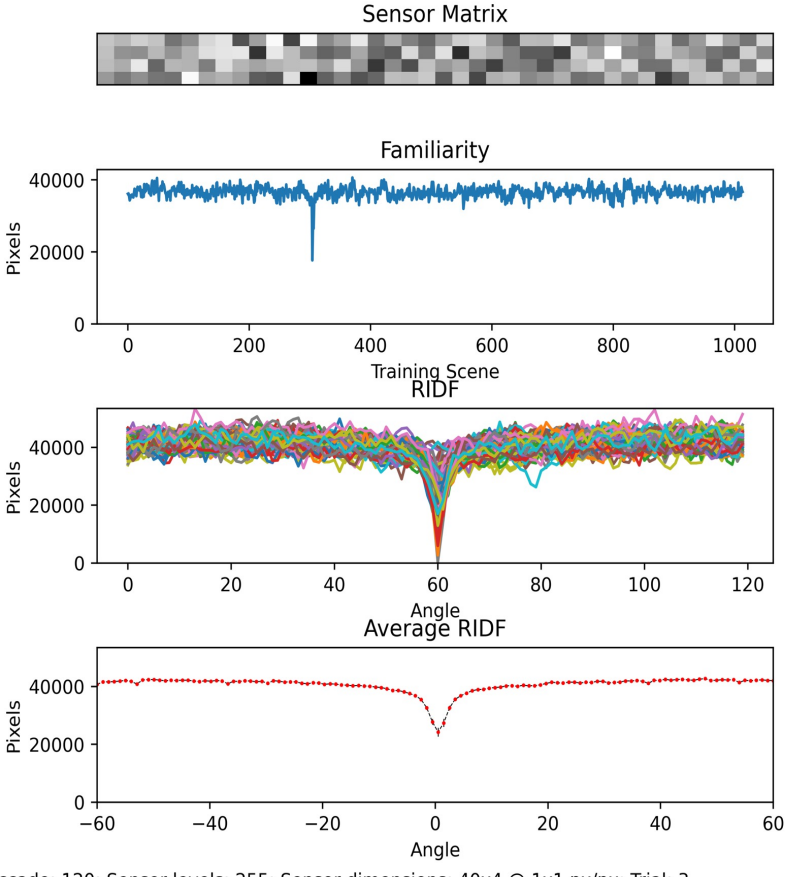


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2351.74; RMSD/dist: 5.879; TD: 775; p90: 4; p50: 4; complete: 0

100%

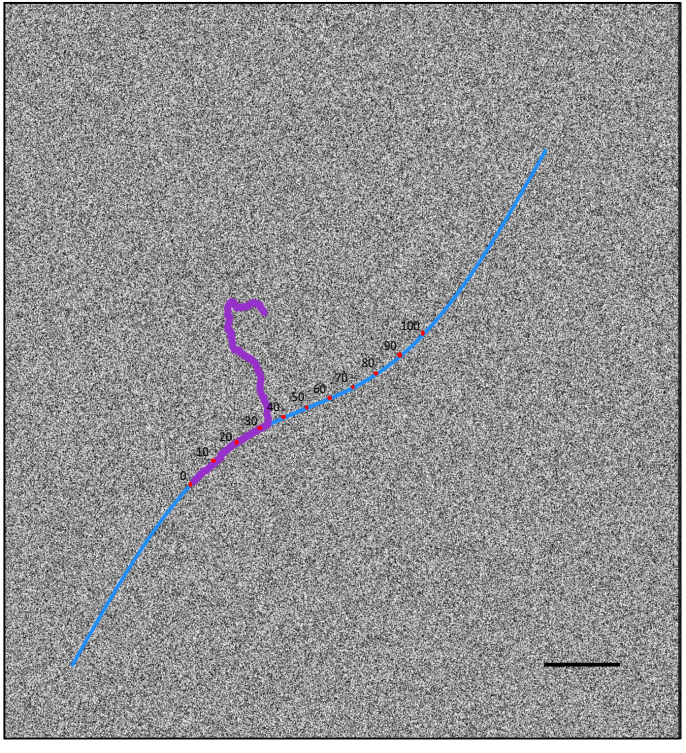


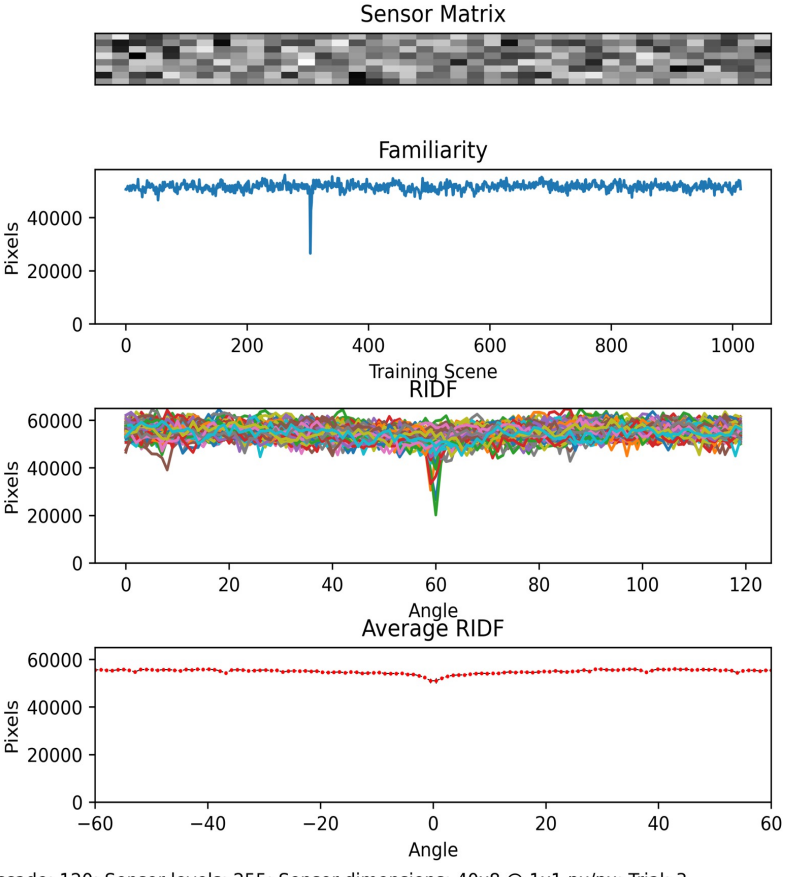


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 61.95; RMSD/dist: 0.155; TD: 12038; p90: 6; p50: 4; complete: 0

30%

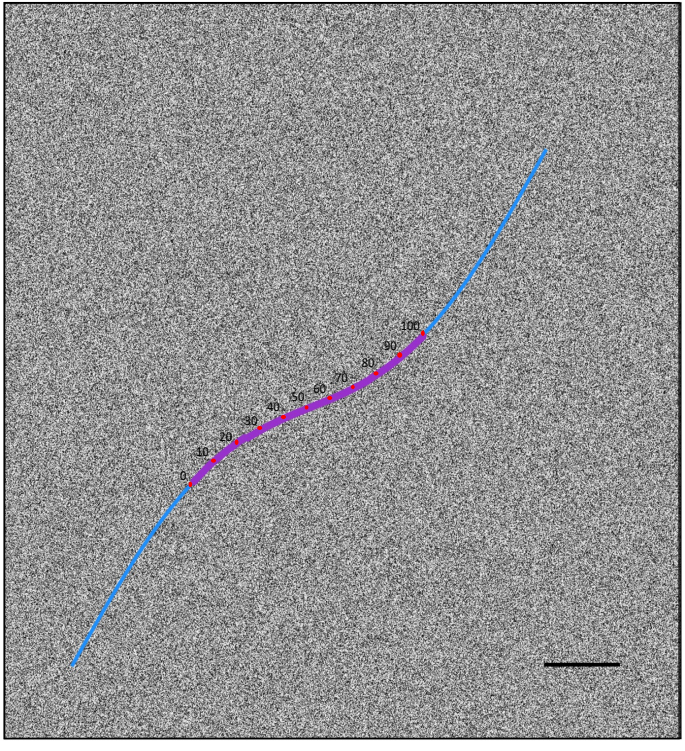


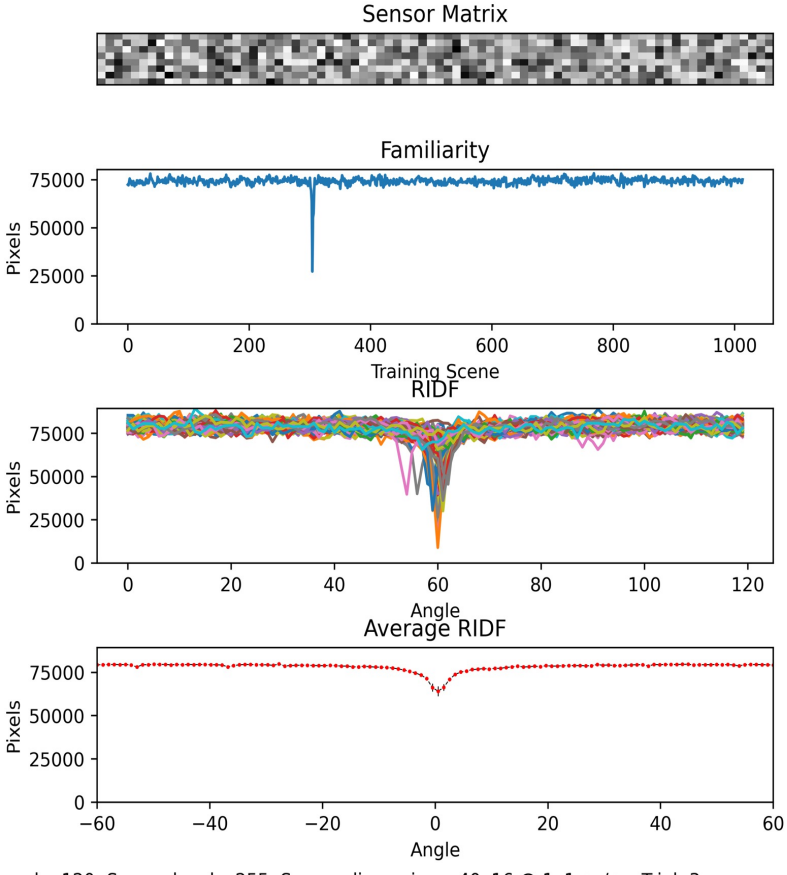


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 7074.15; RMSD/dist: 17.685; TD: 325; p90: 2; p50: 2; complete: 0

100%

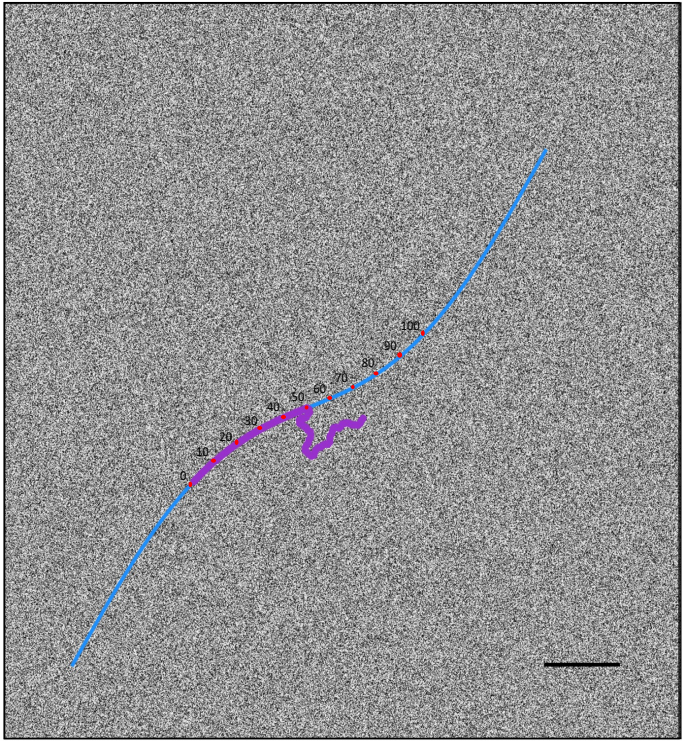


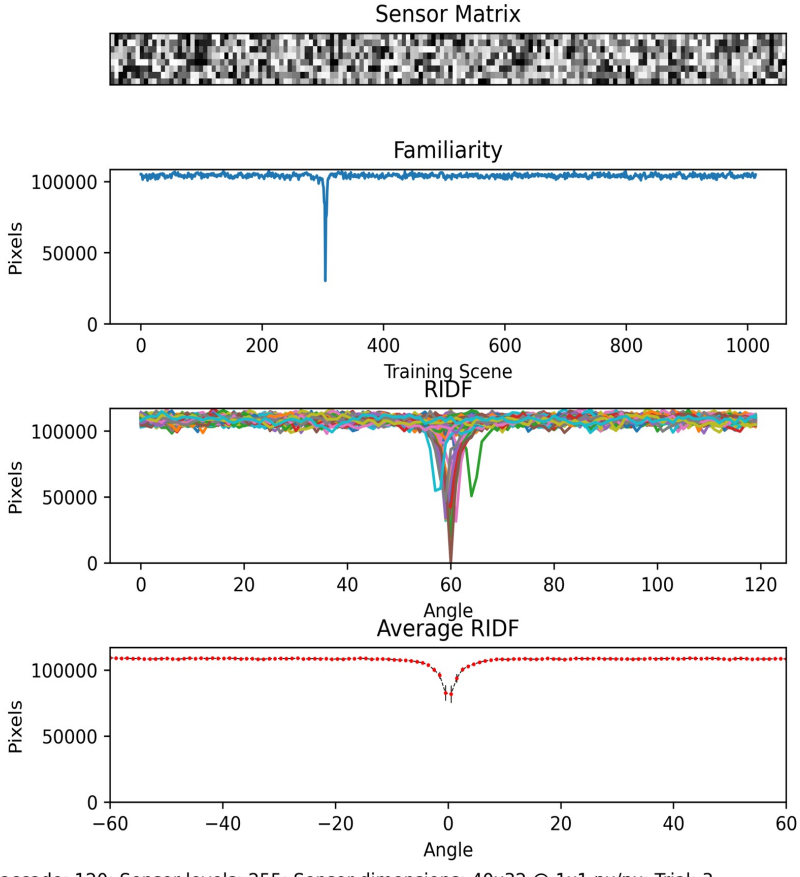


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 74.92; RMSD/dist: 0.187; TD: 10012; p90: 6; p50: 4; complete: 0

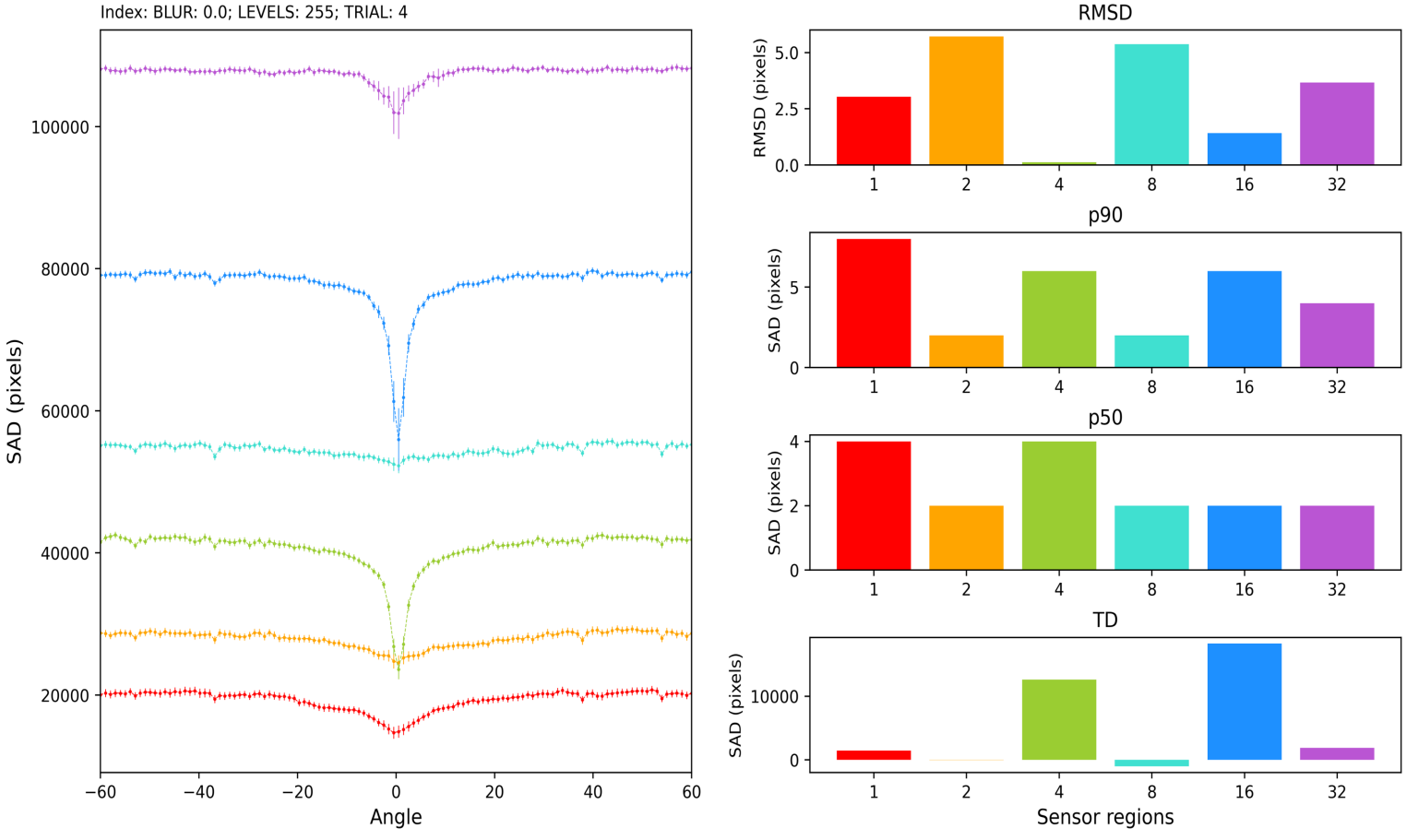
50%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2000.37; RMSD/dist: 5.001; TD: 22057; p90: 6; p50: 4; complete: 0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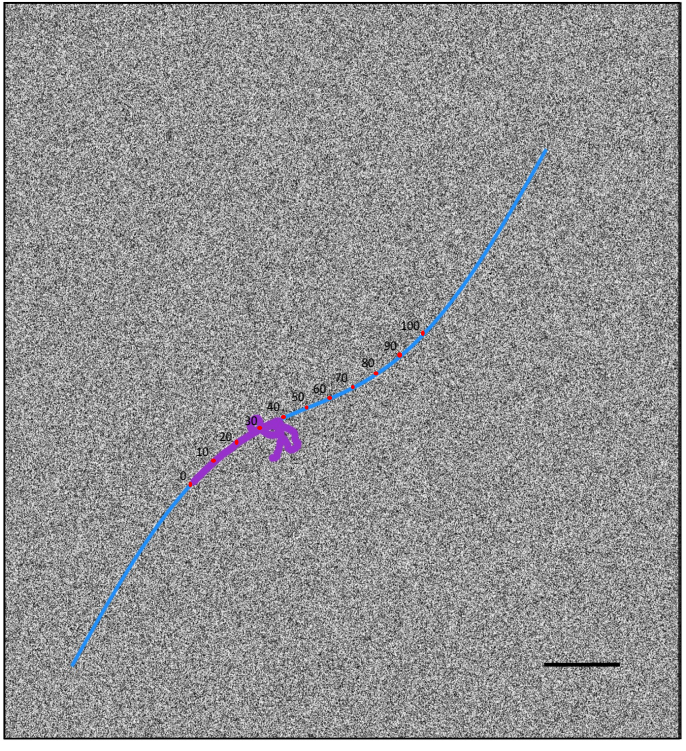
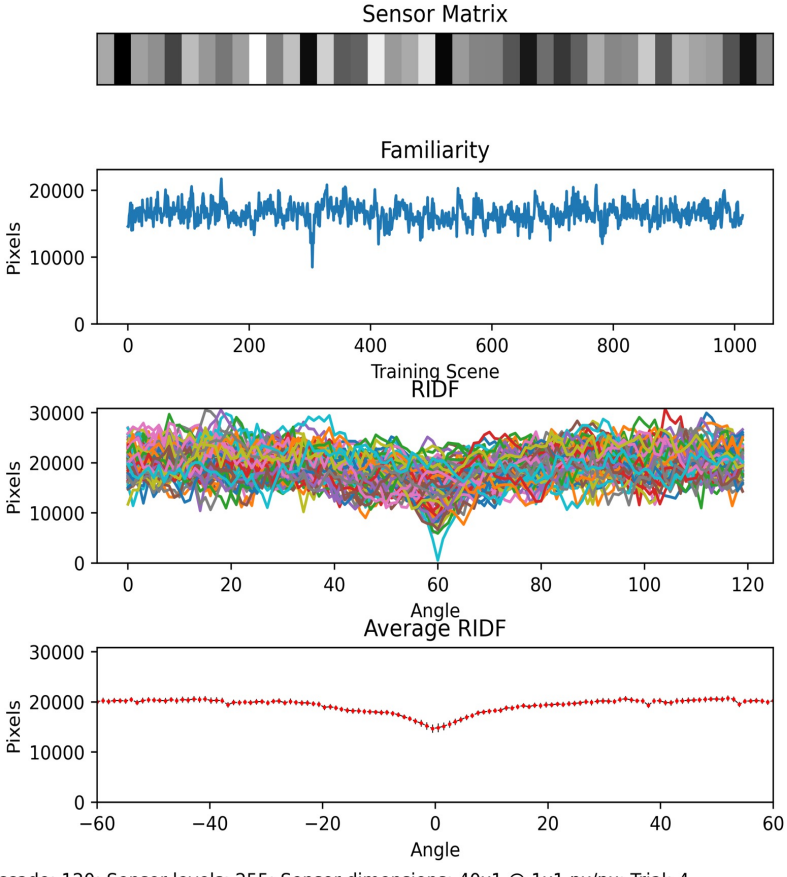
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
5.0
2.5
0.0
p90
SAD (pixels)
5
0
p50
SAD (pixels)
4
2
0
TD
SAD (pixels)
10000
0
1
2
4
8
16
32
Sensor regions

30%

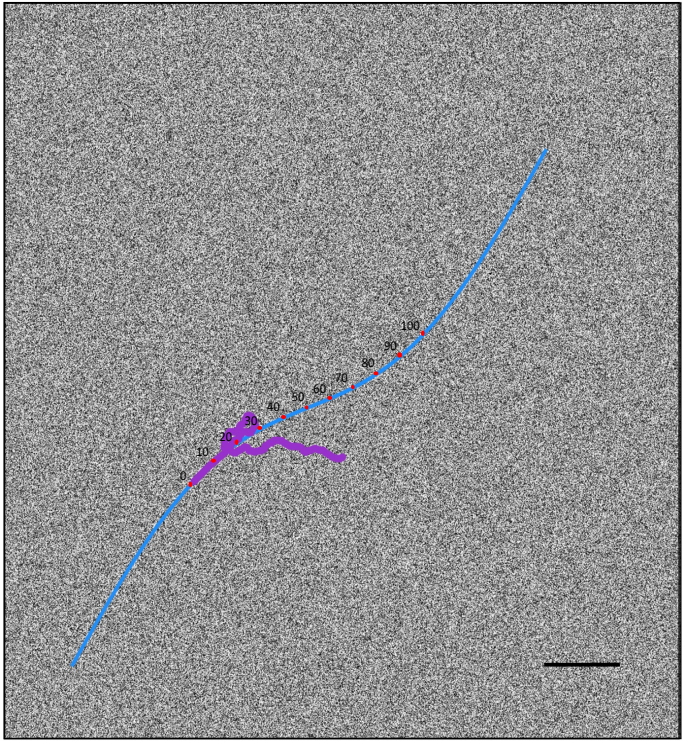


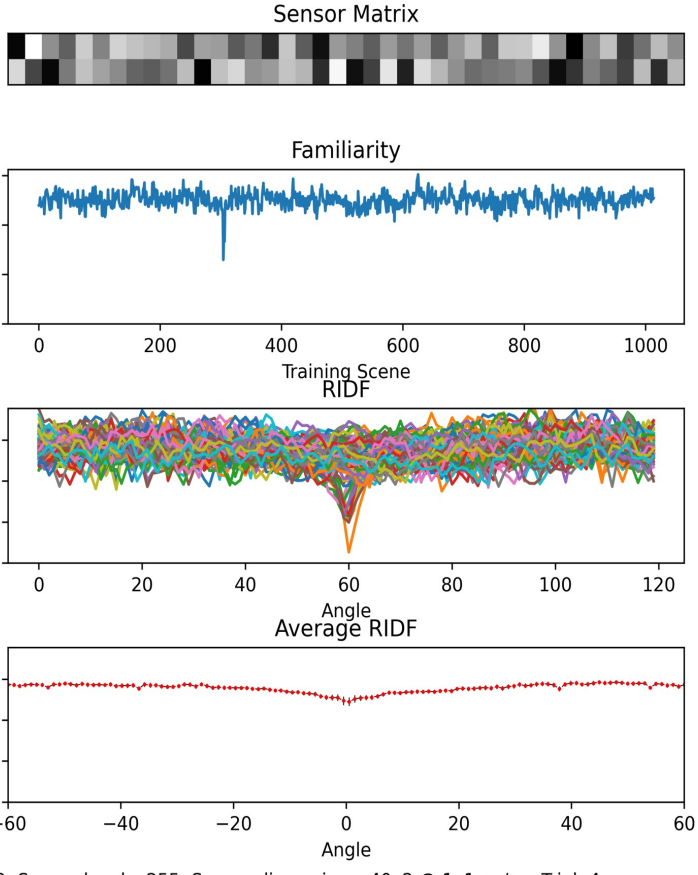


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1214.49; RMSD/dist: 3.036; TD: 1465; p90: 8; p50: 4; complete: 0

20%

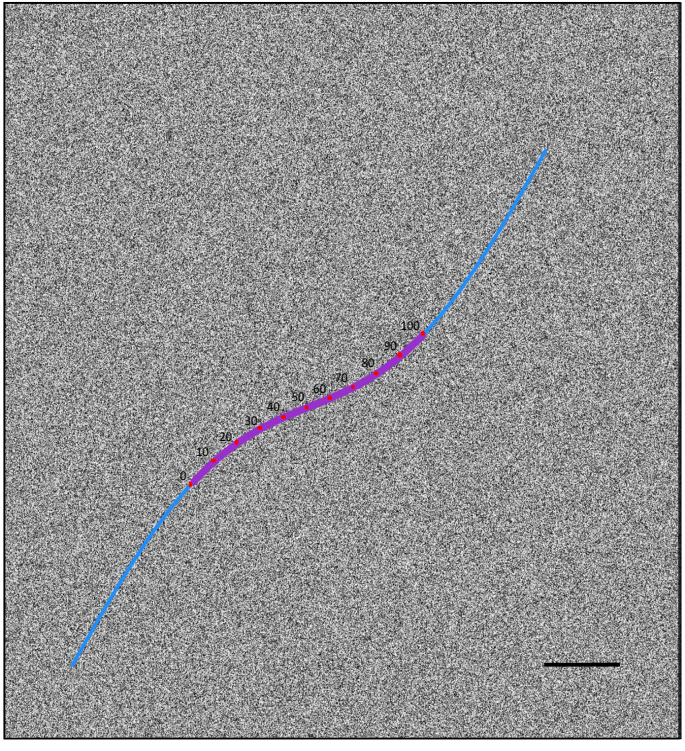


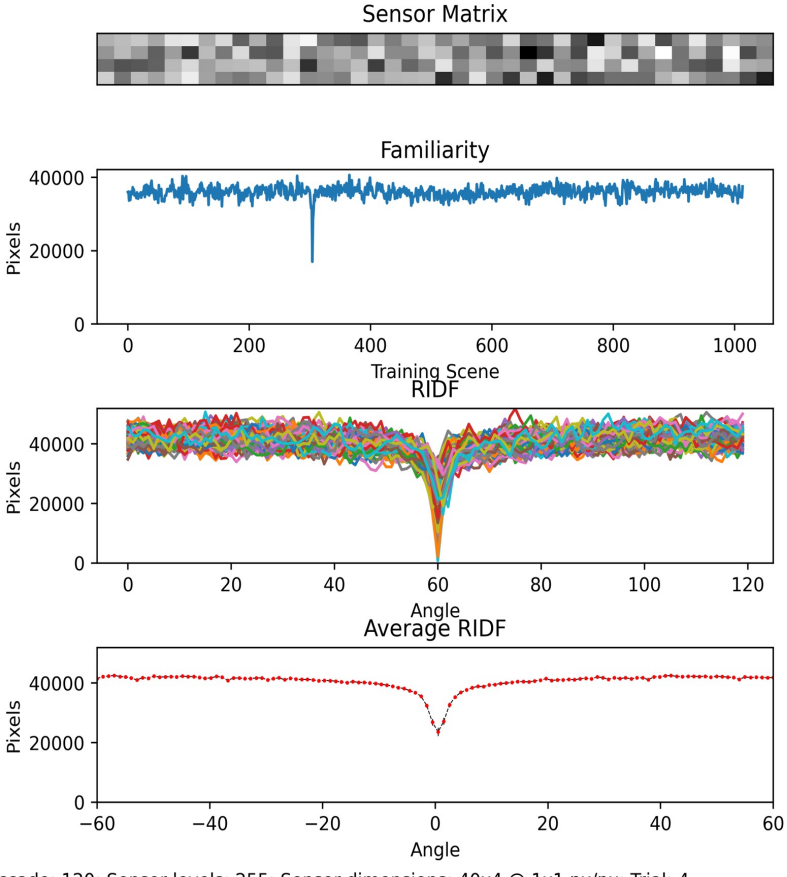


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2287.53; RMSD/dist: 5.719; TD: -30; p90: 2; p50: 2; complete: 0

100%

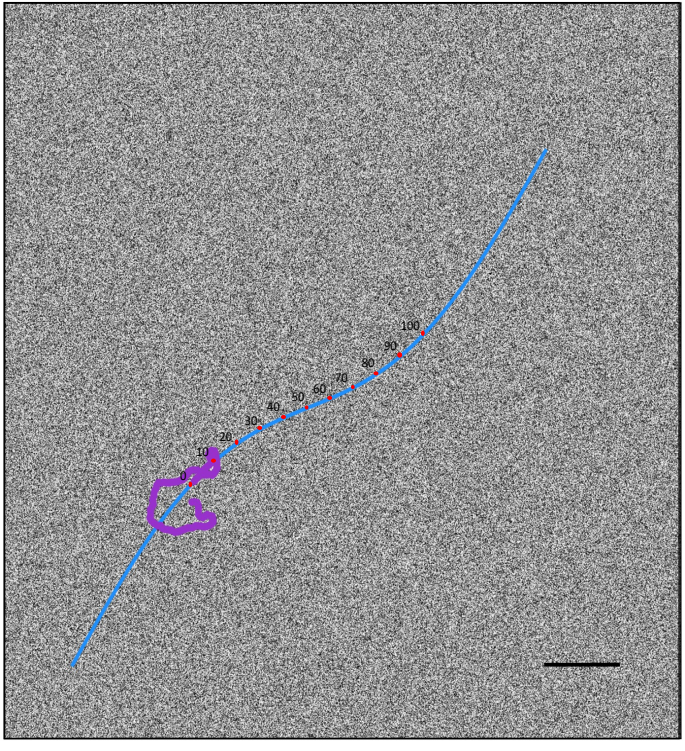


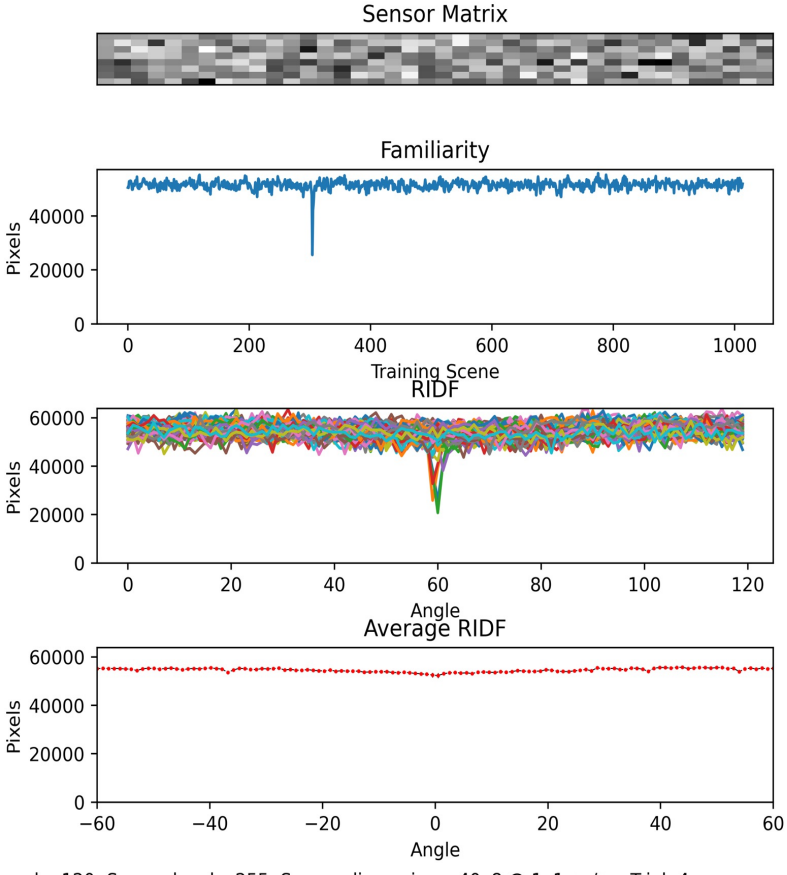


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 48.98; RMSD/dist: 0.122; TD: 12619; p90: 6; p50: 4; complete: 0

10%

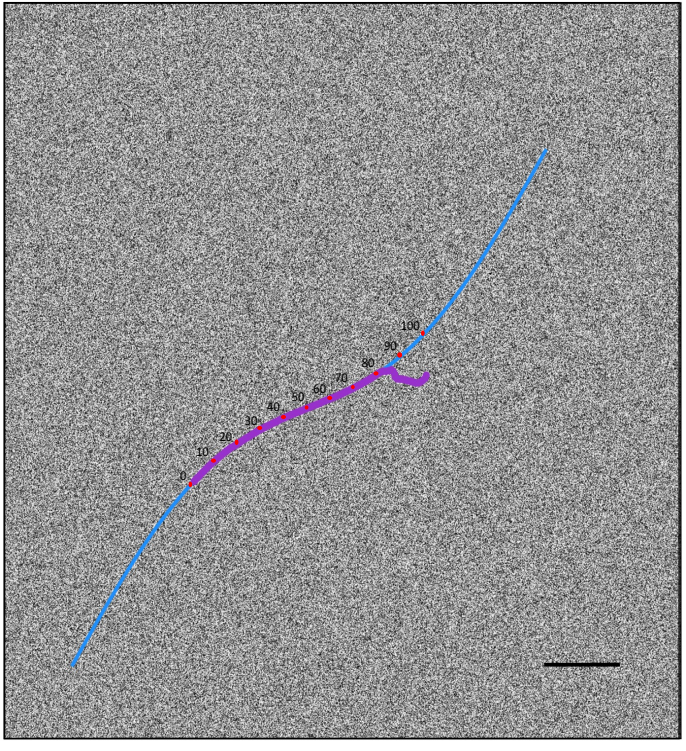


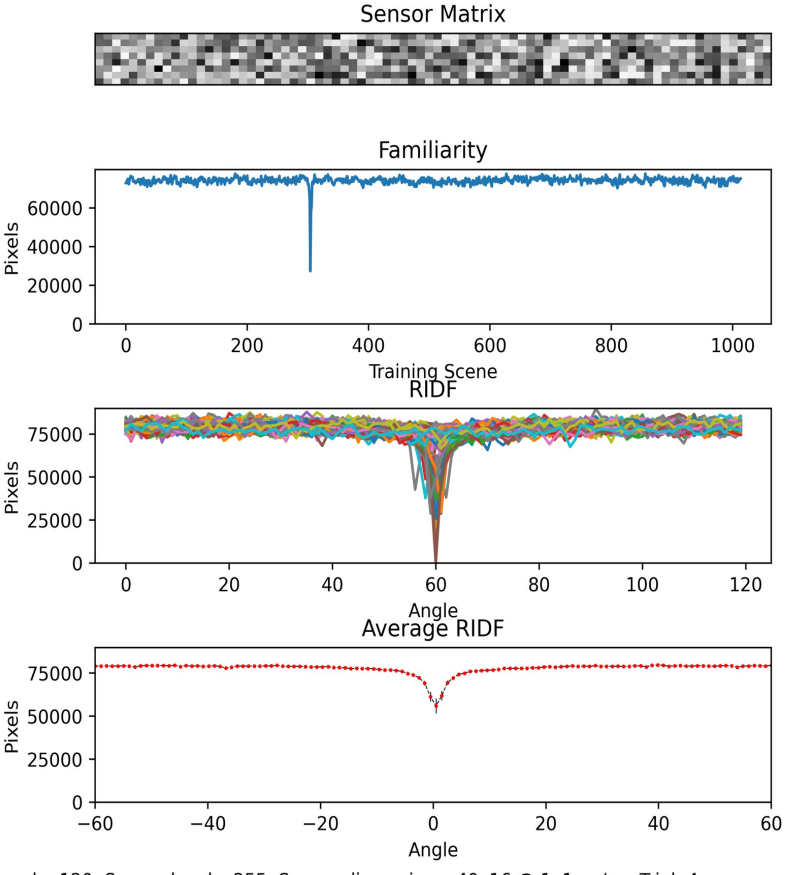


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2147.45; RMSD/dist: 5.369; TD: -996; p90: 2; p50: 2; complete: 0

80%

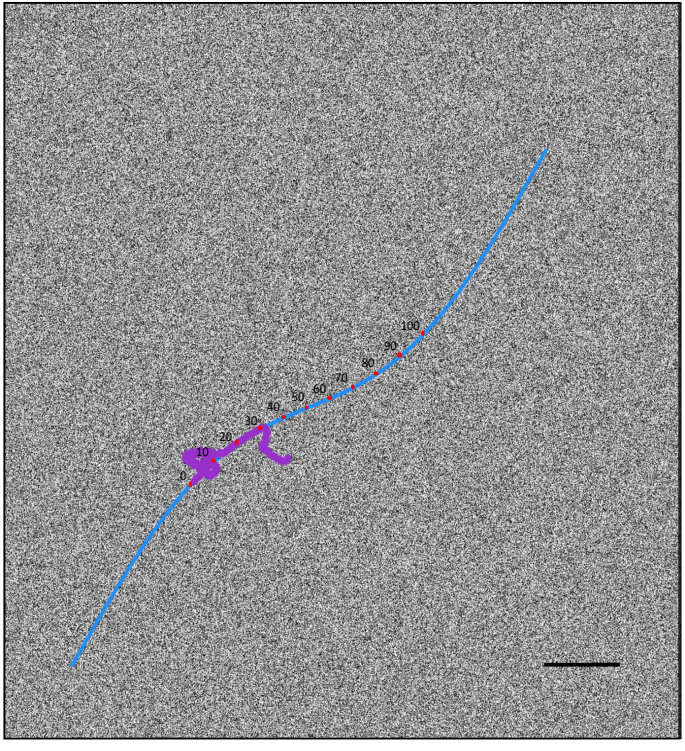


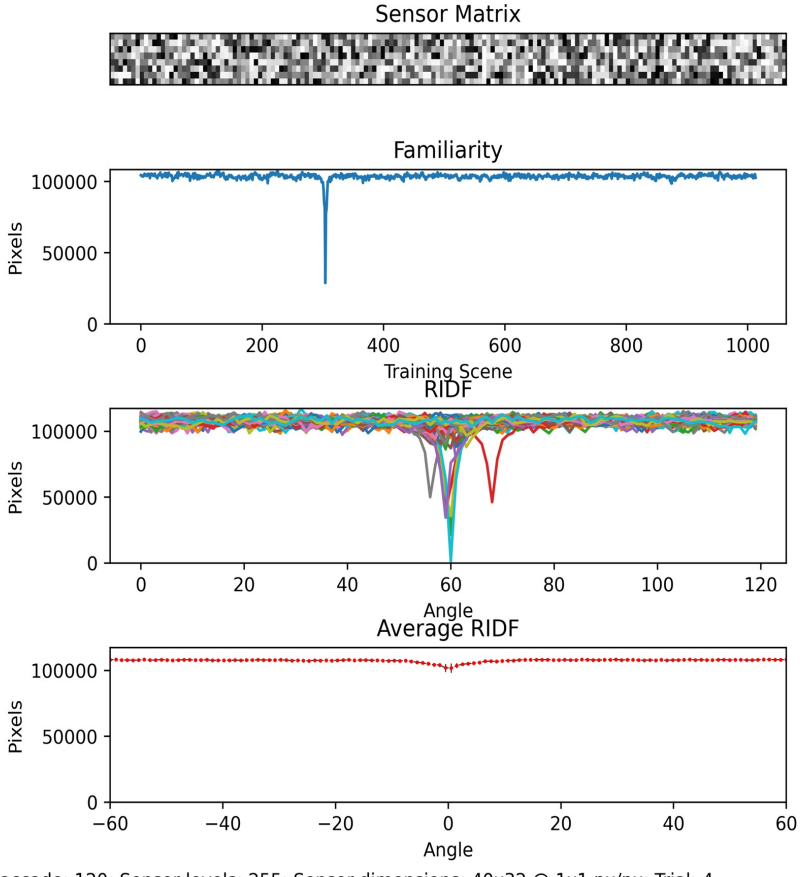


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 567.96; RMSD/dist: 1.420; TD: 18254; p90: 6; p50: 2; complete: 0

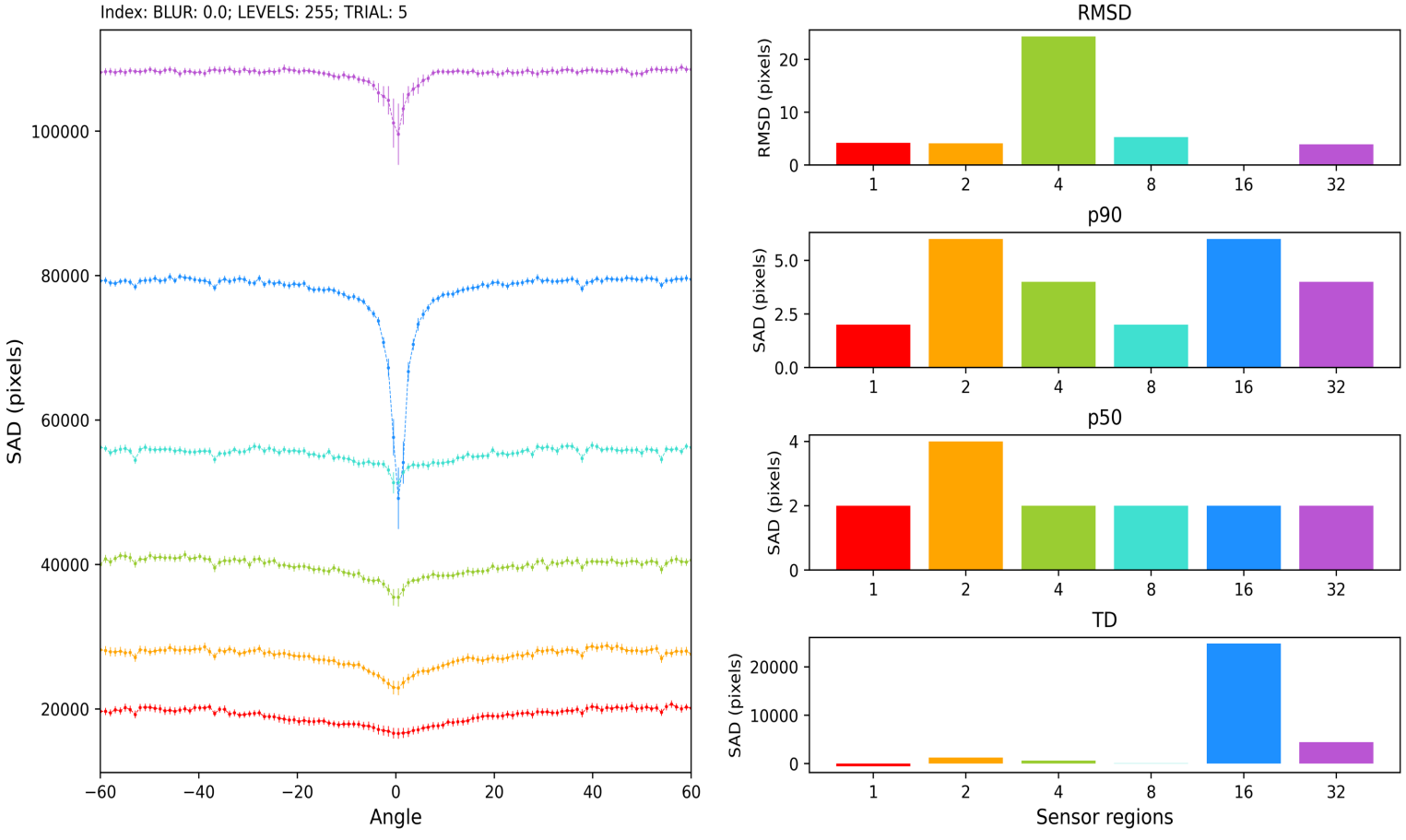
20%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1465.18; RMSD/dist: 3.663; TD: 1907; p90: 4; p50: 2; complete: 0


Index: BLUR: 0.0; LEVELS: 255; TRIAL: 5
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100000
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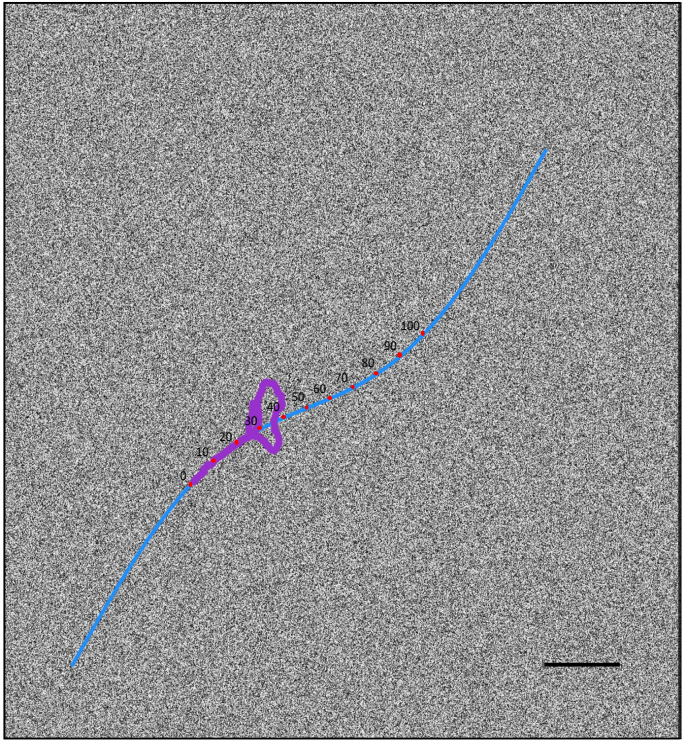
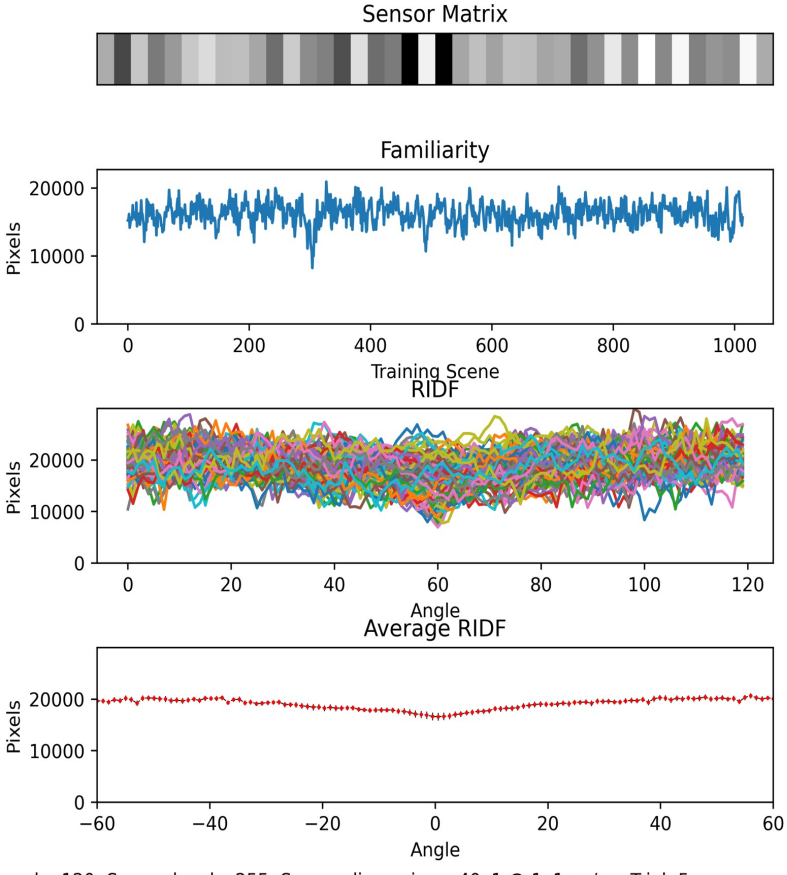
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
TD
20000
10000
Sensor regions

20%

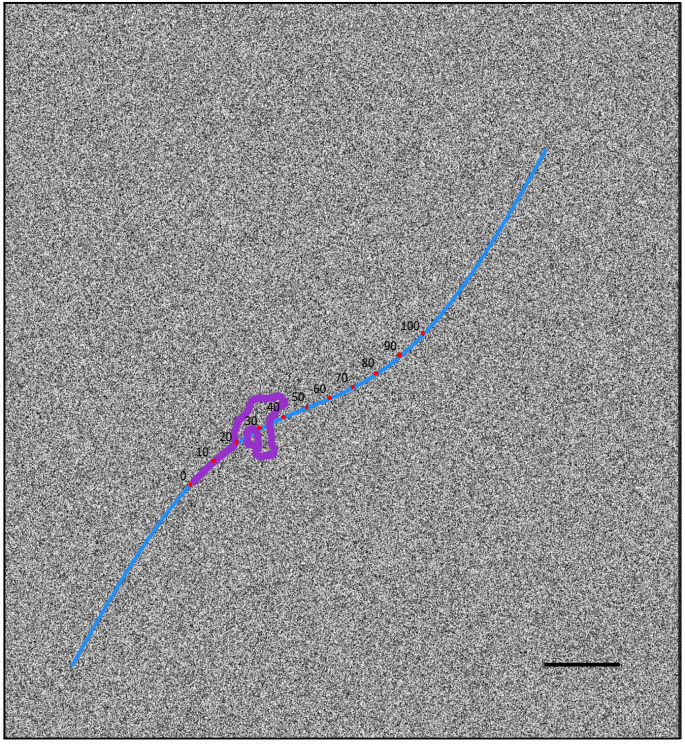


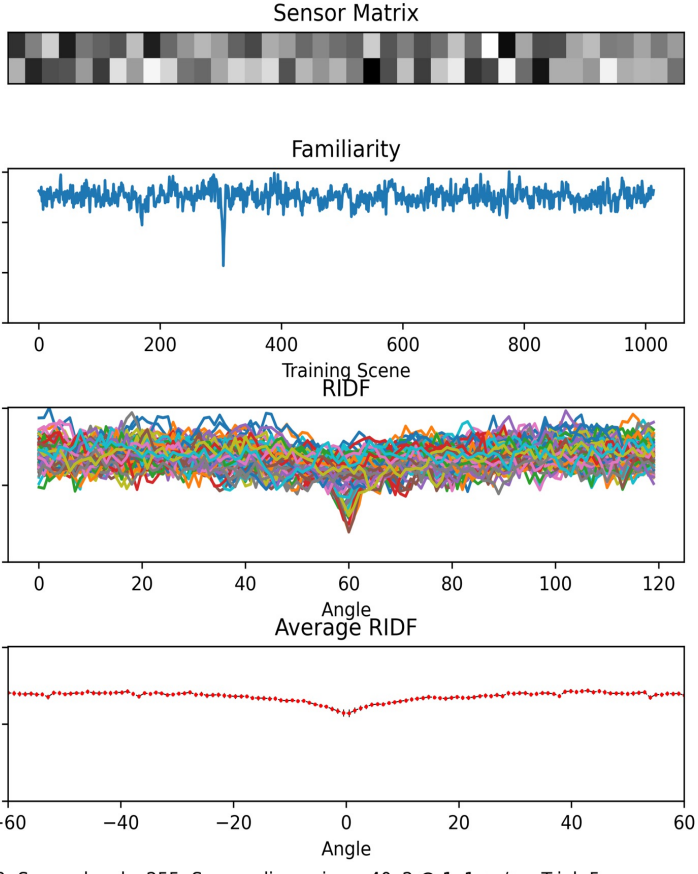


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1670.51; RMSD/dist: 4.176; TD: -557; p90: 2; p50: 2; complete: 0

20%

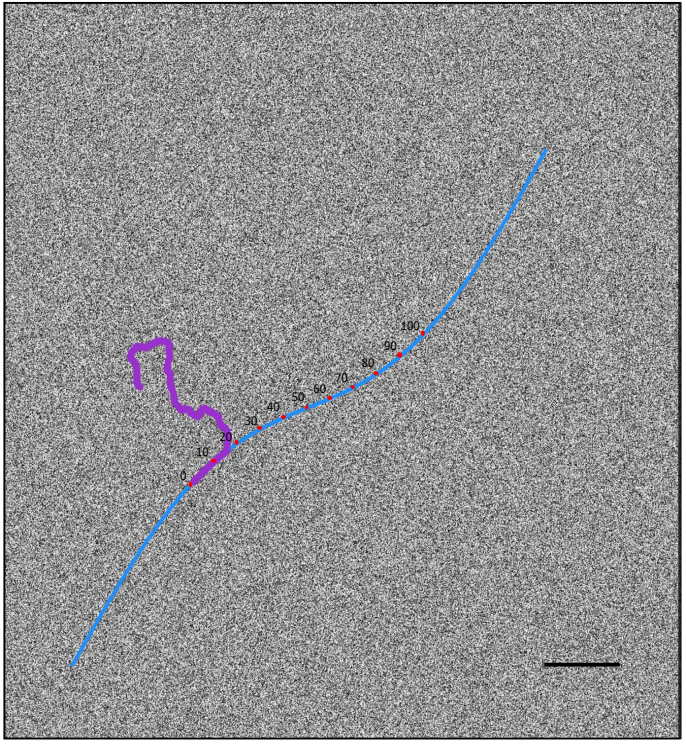


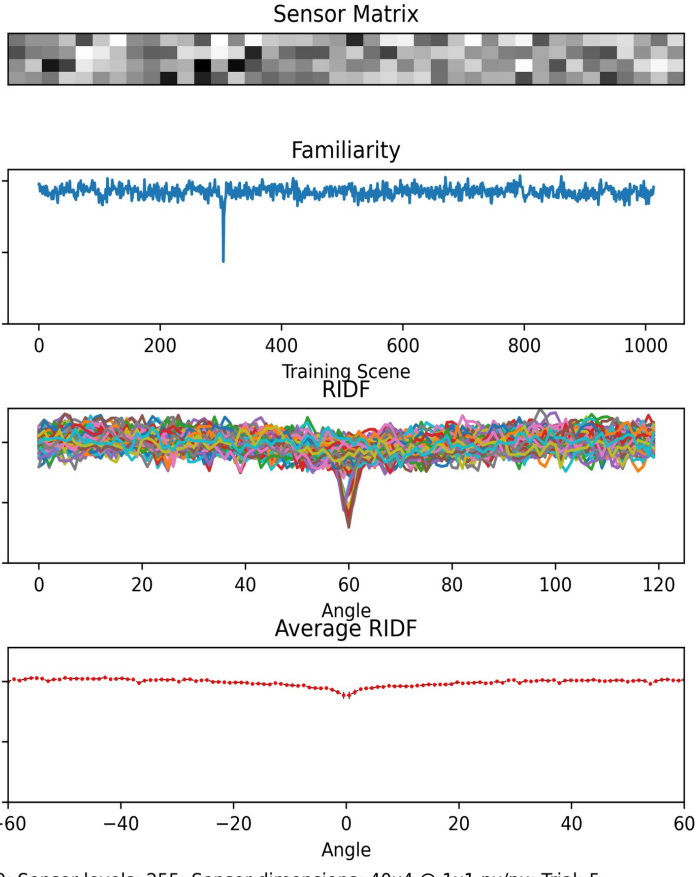


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1635.30; RMSD/dist: 4.088; TD: 1247; p90: 6; p50: 4; complete: 0

10%

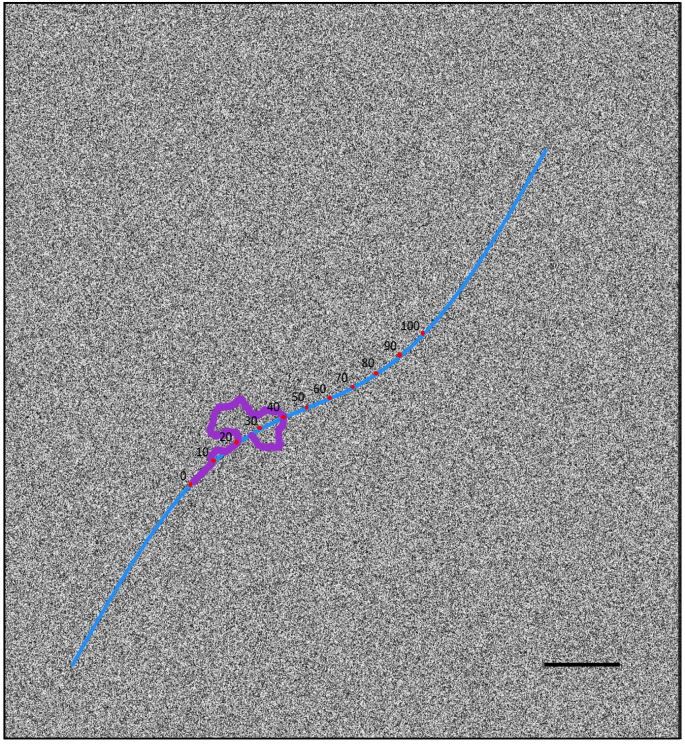


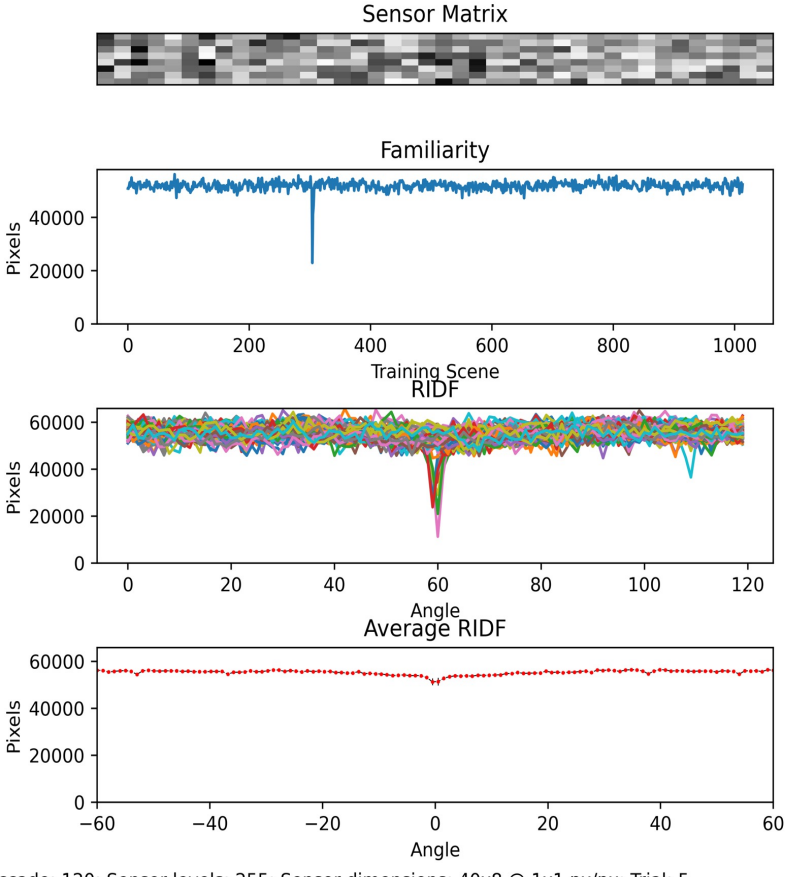


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 9738.58; RMSD/dist: 24.346; TD: 620; p90: 4; p50: 2; complete: 0

10%

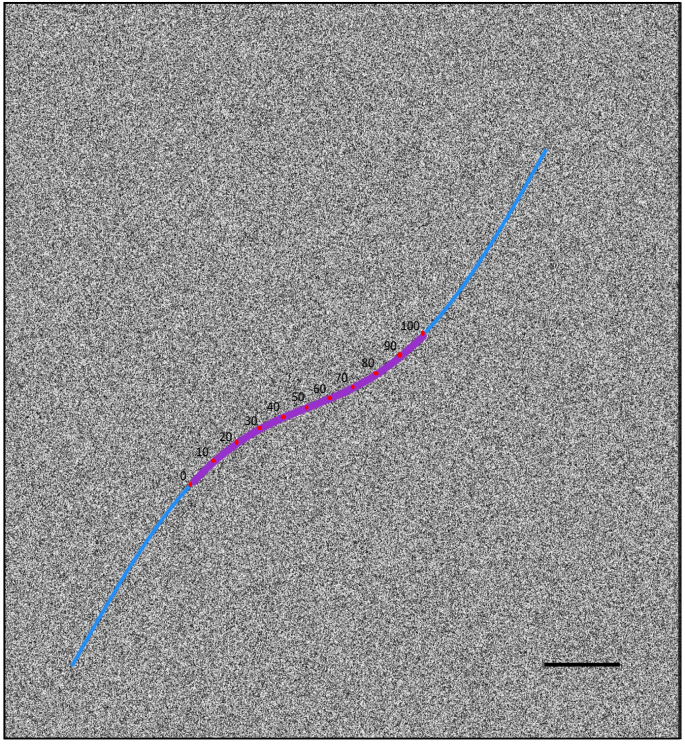


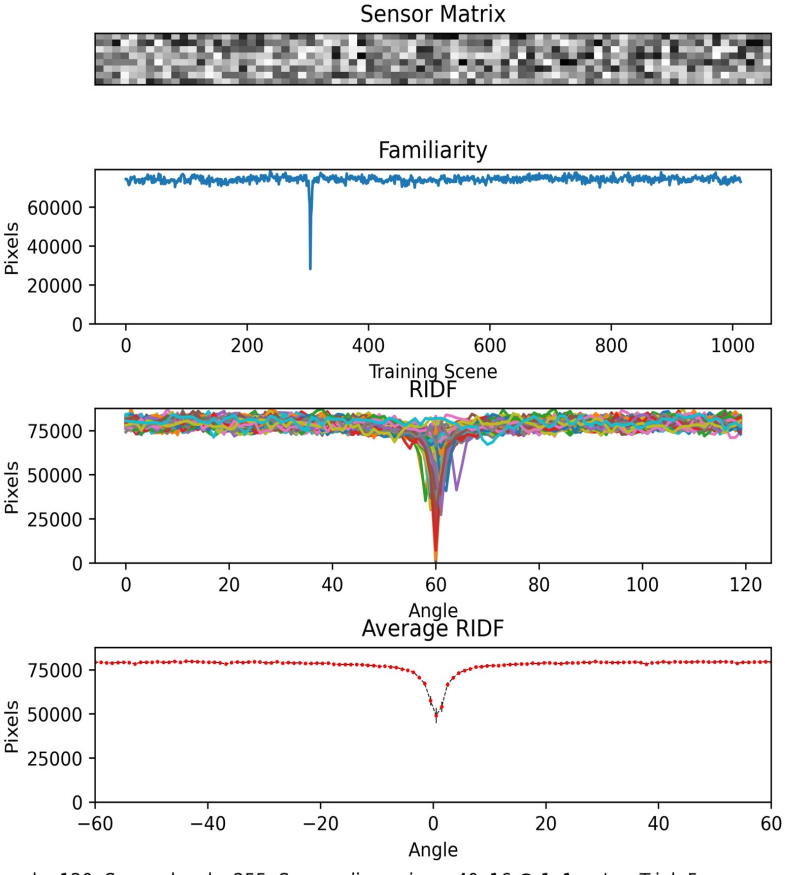


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2111.69; RMSD/dist: 5.279; TD: 76; p90: 2; p50: 2; complete: 0

100%

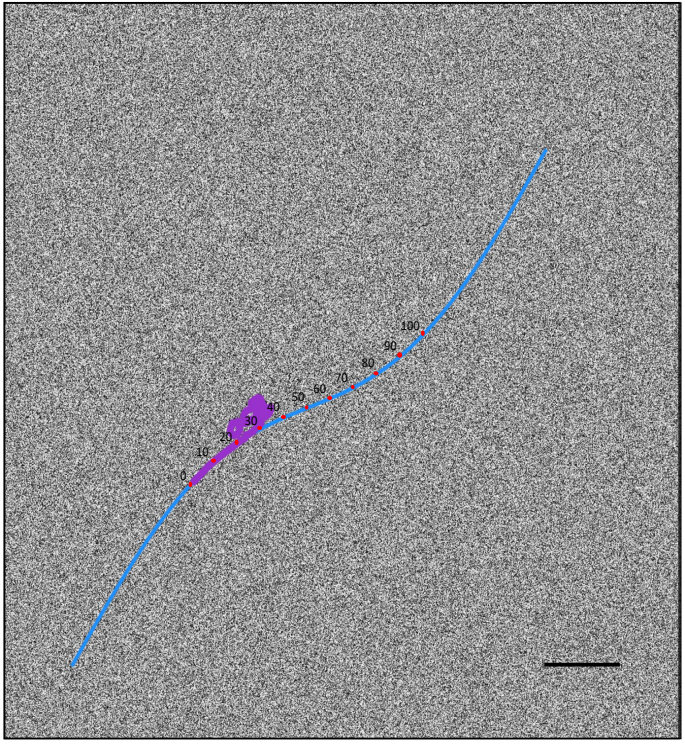


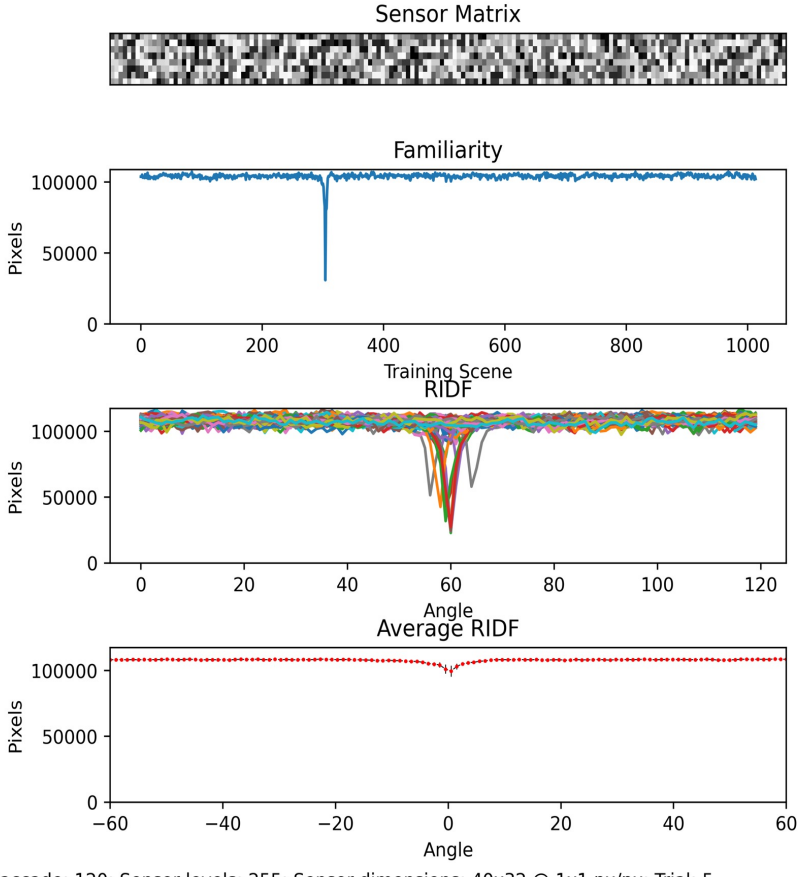


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 42.10; RMSD/dist: 0.105; TD: 24804; p90: 6; p50: 2; complete: 0

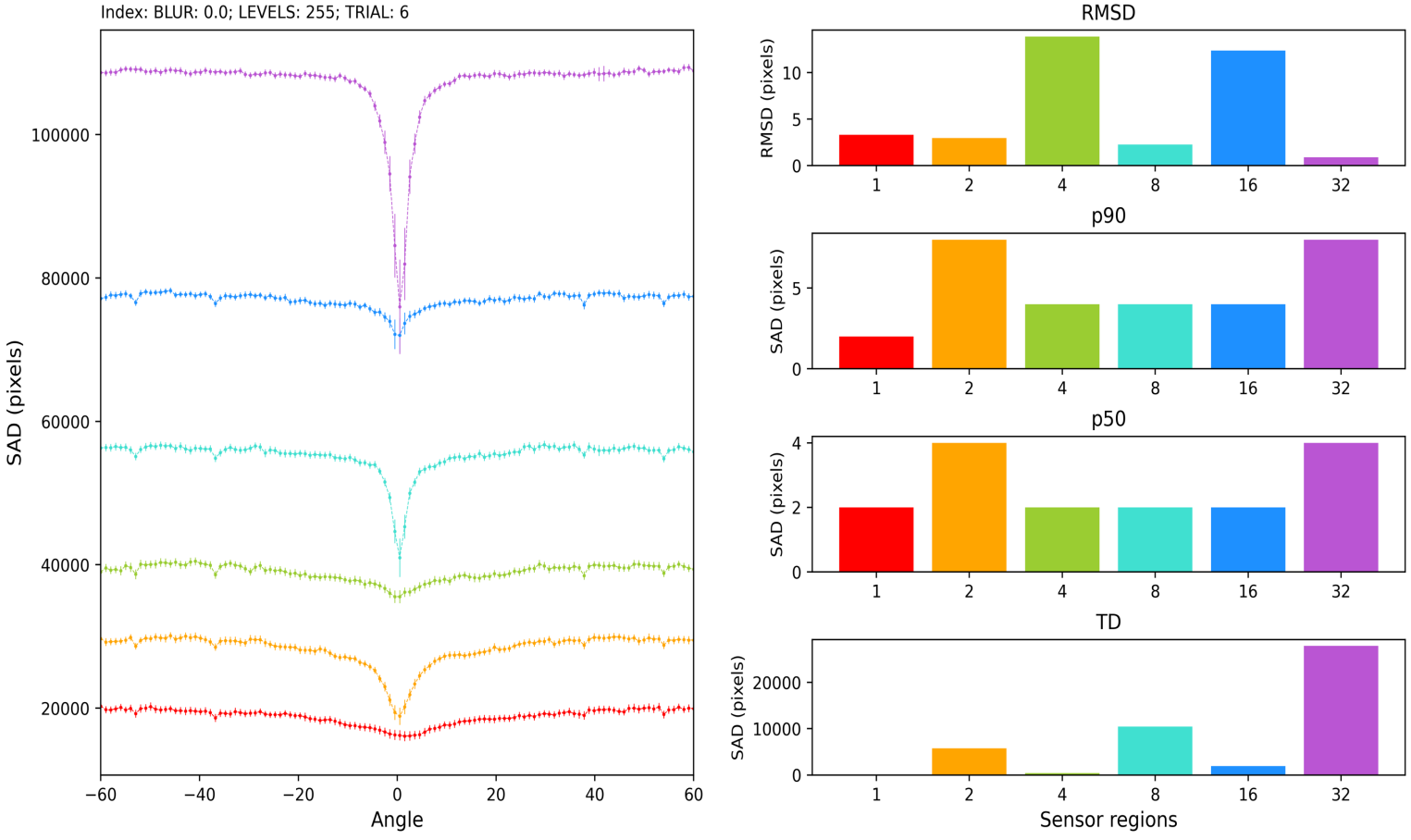
30%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1558.22; RMSD/dist: 3.896; TD: 4454; p90: 4; p50: 2; complete: 0


Index: BLUR: 0.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
5
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p50
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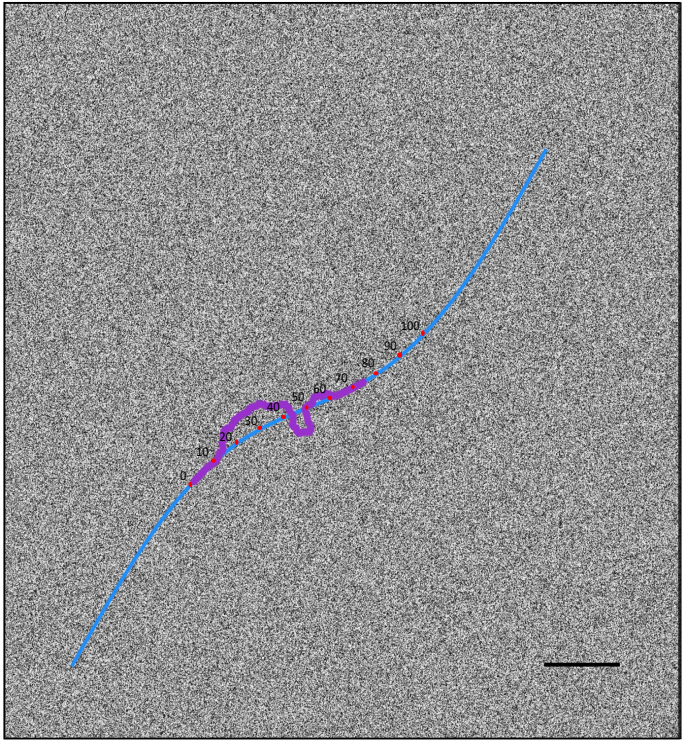
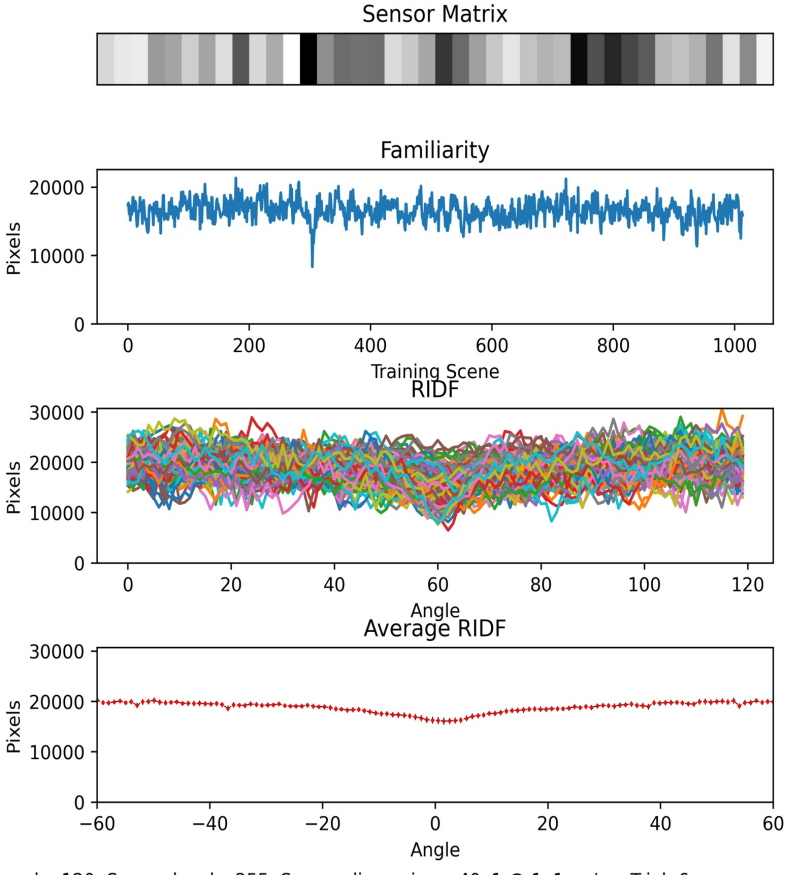
4
2
0
TD
SAD (pixels)
20000
10000
0
Sensor regions

20%

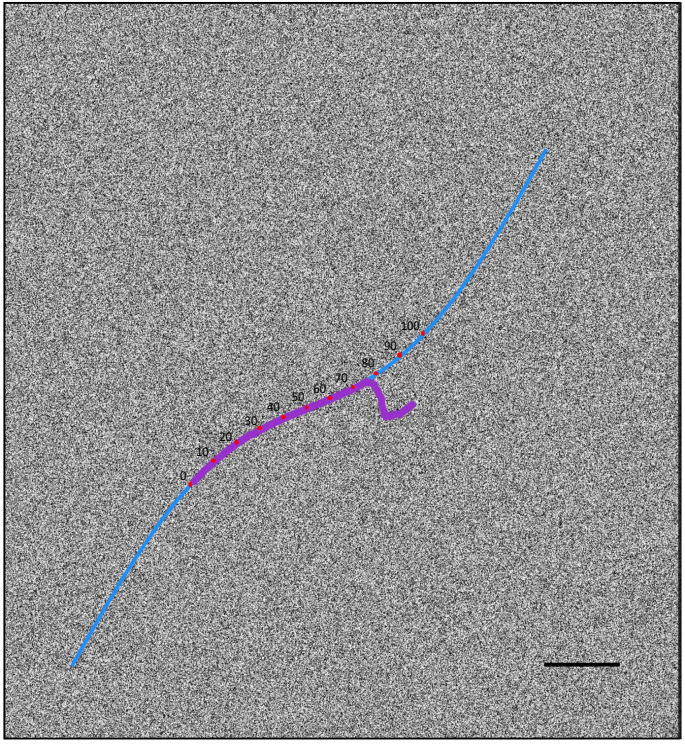


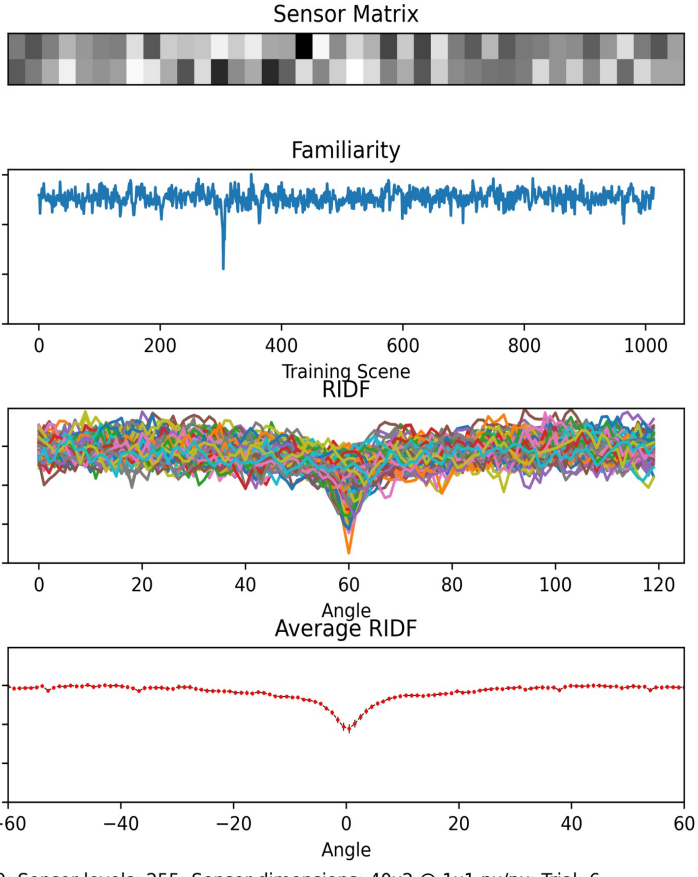


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1322.70; RMSD/dist: 3.307; TD: 44; p90: 2; p50: 2; complete: 0

70%

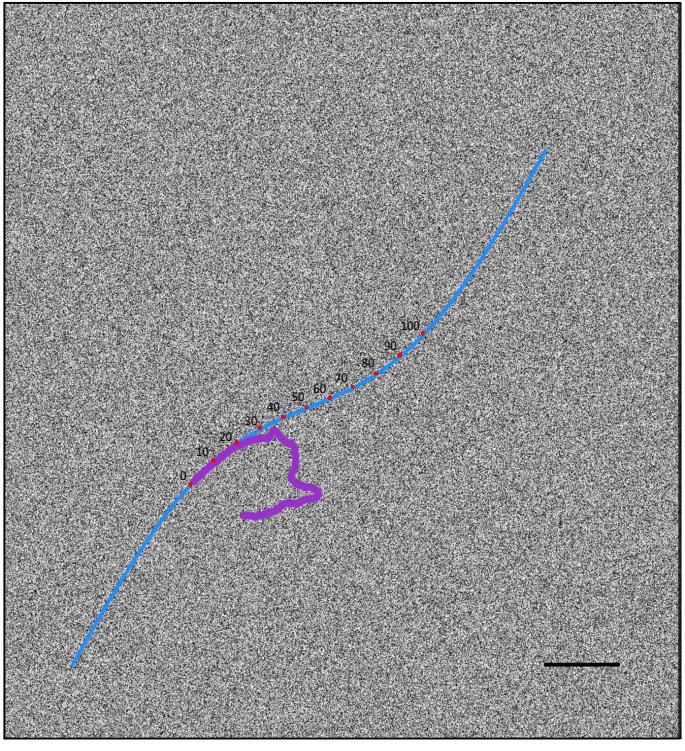


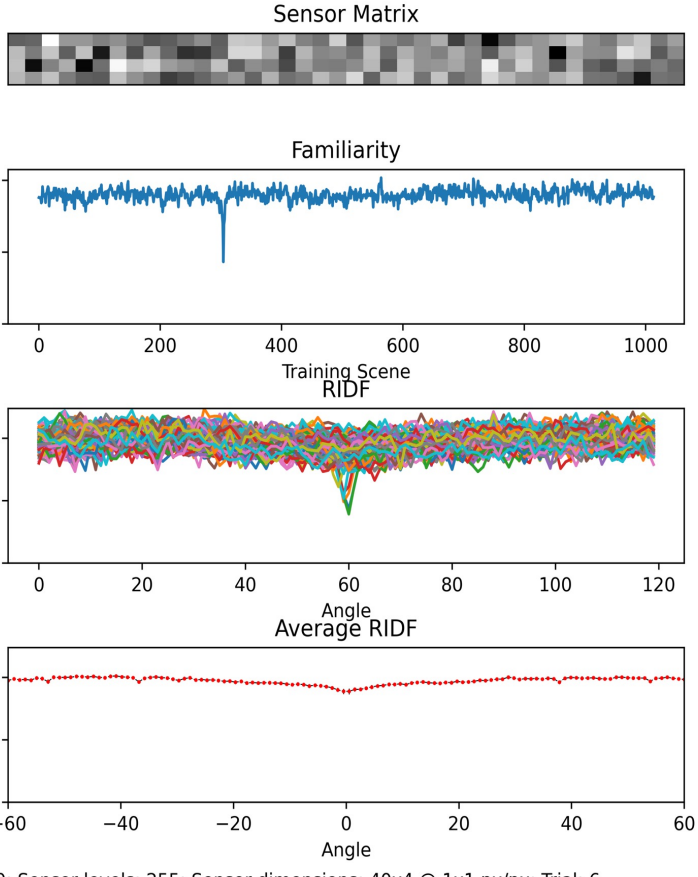


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1186.87; RMSD/dist: 2.967; TD: 5757; p90: 8; p50: 4; complete: 0

20%

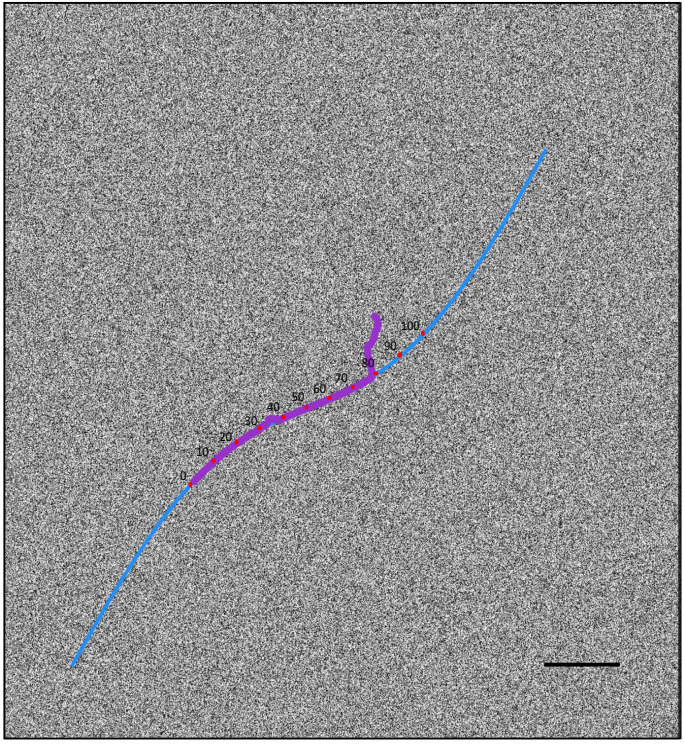


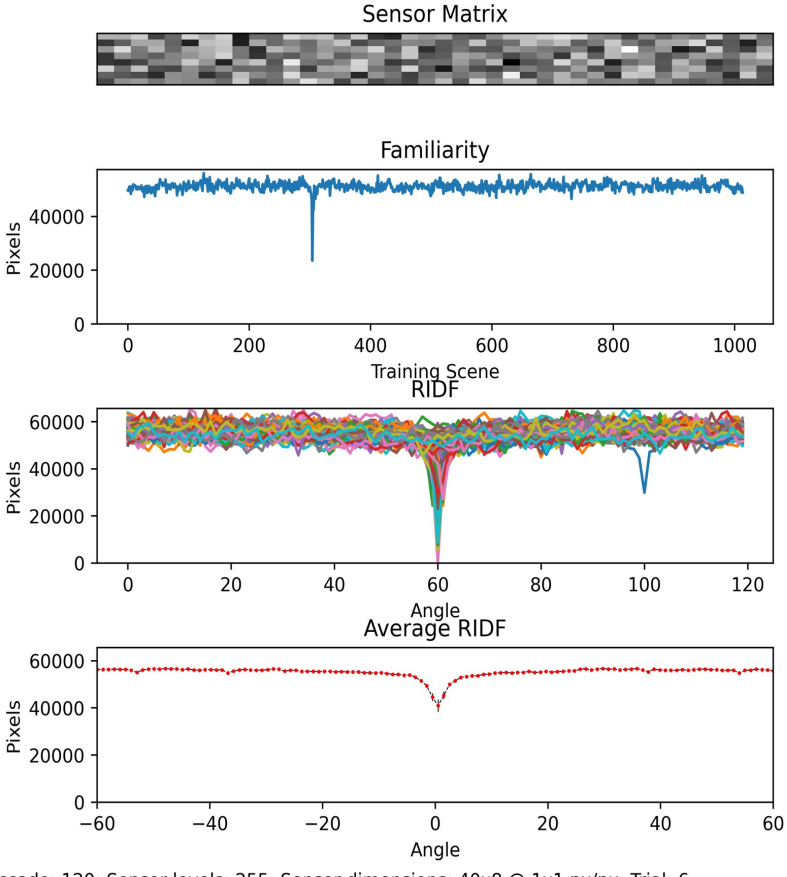


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 5551.45; RMSD/dist: 13.879; TD: 421; p90: 4; p50: 2; complete: 0

70%

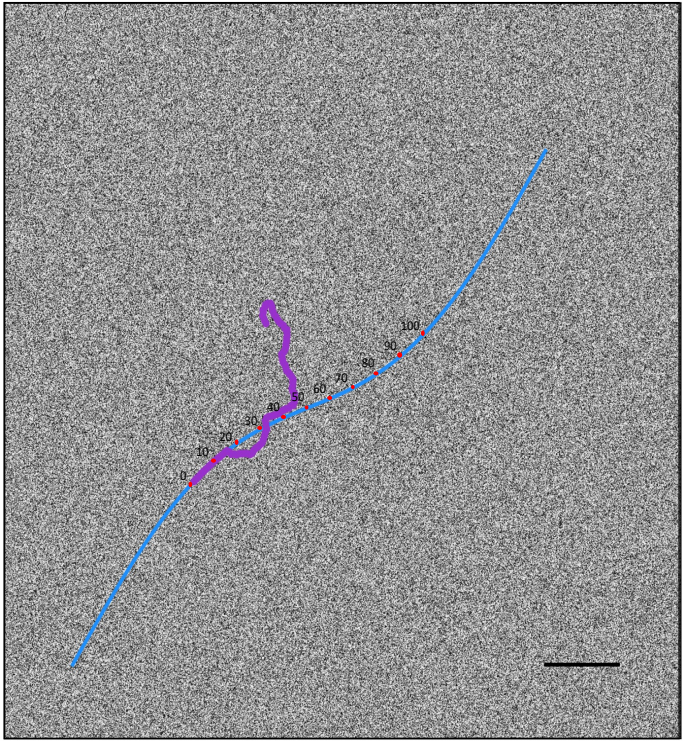


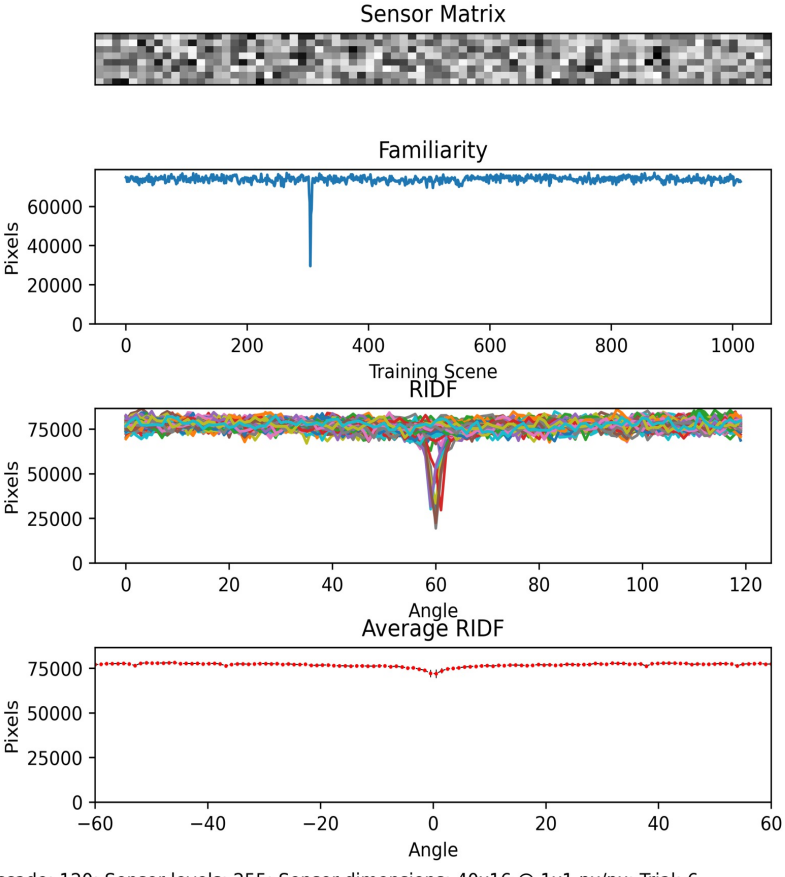


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 898.09; RMSD/dist: 2.245; TD: 10434; p90: 4; p50: 2; complete: 0

10%

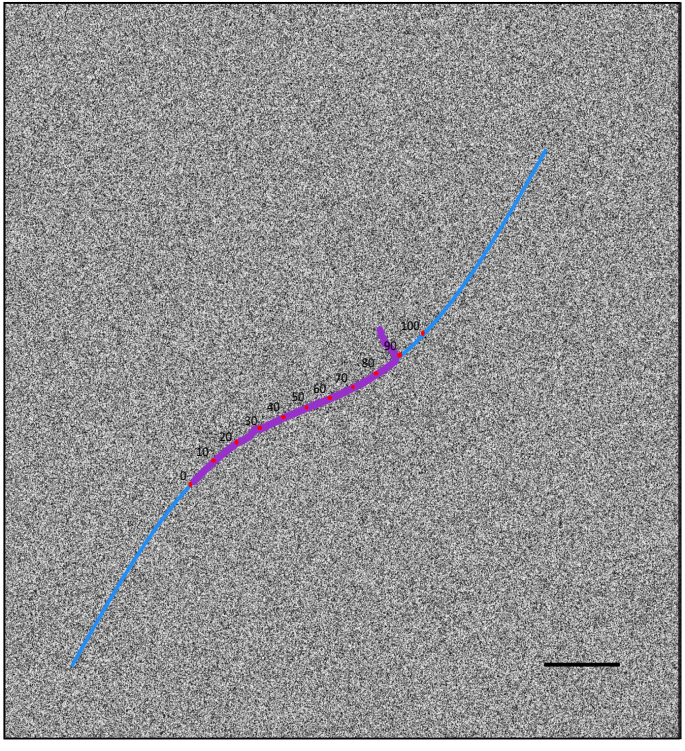


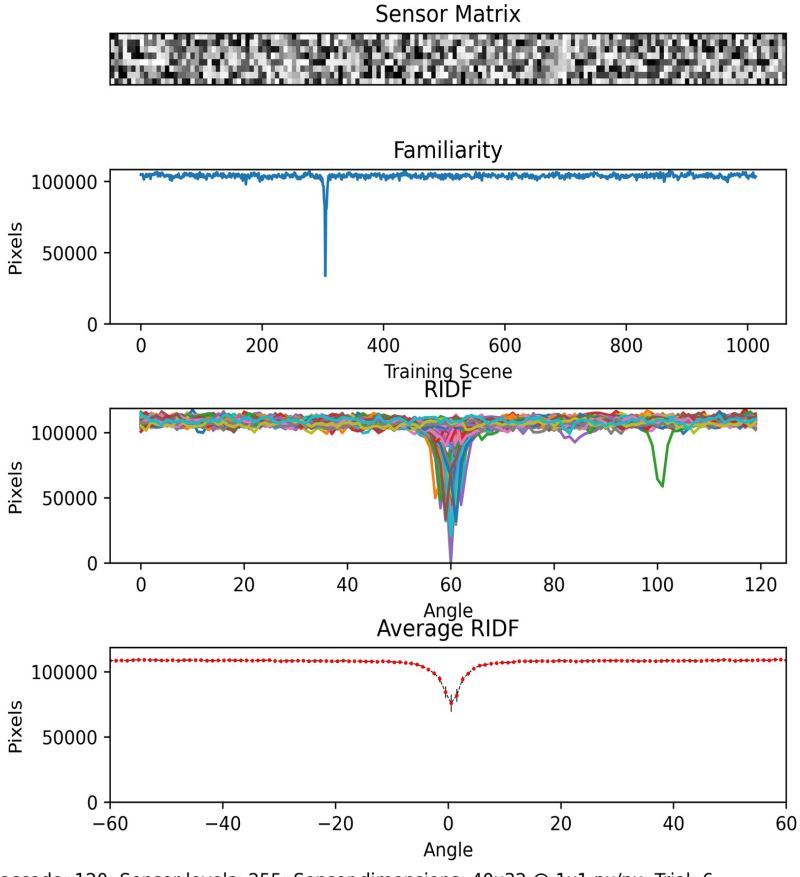


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4942.67; RMSD/dist: 12.357; TD: 1921; p90: 4; p50: 2; complete: 0

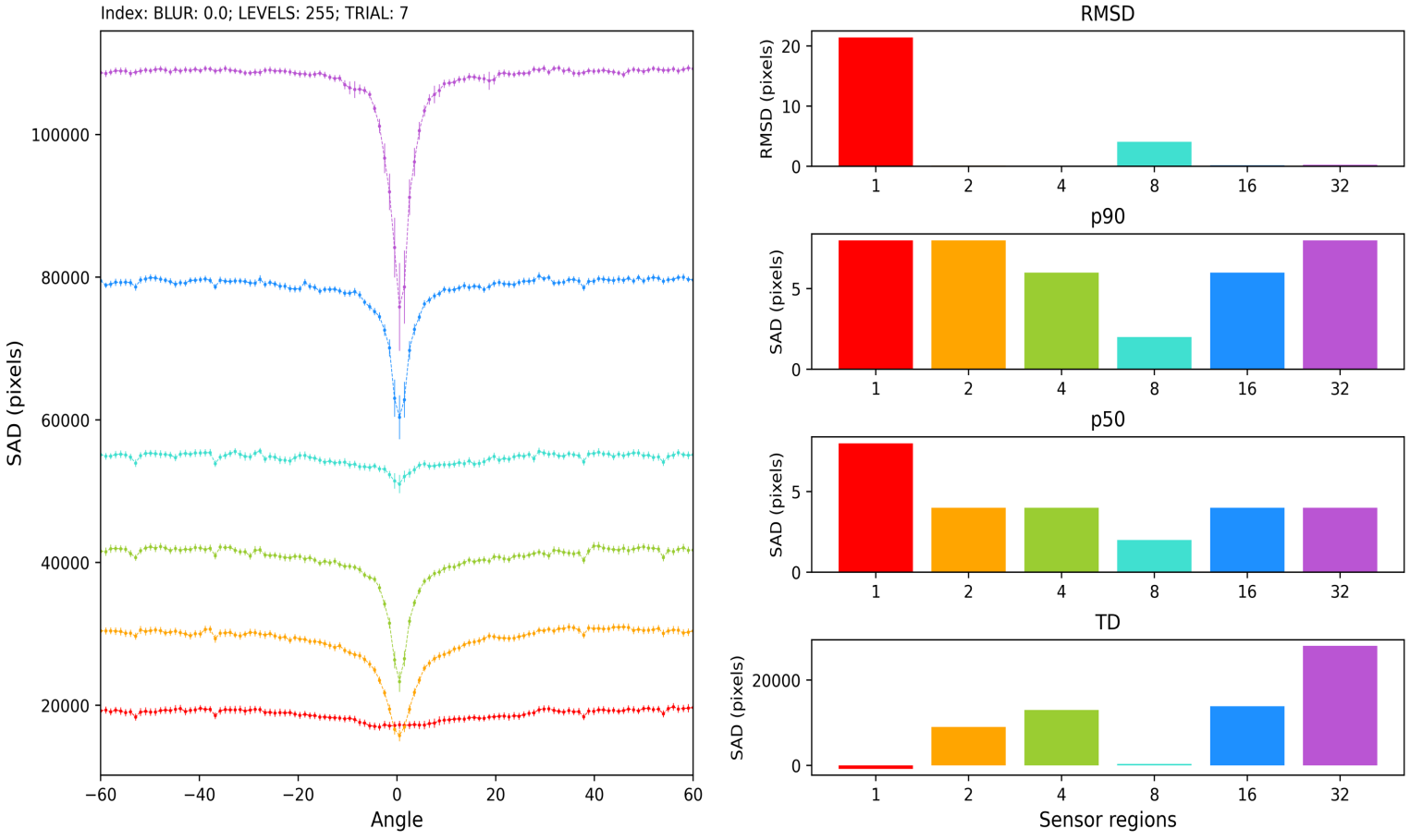
80%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 348.43; RMSD/dist: 0.871; TD: 27832; p90: 8; p50: 4; complete: 0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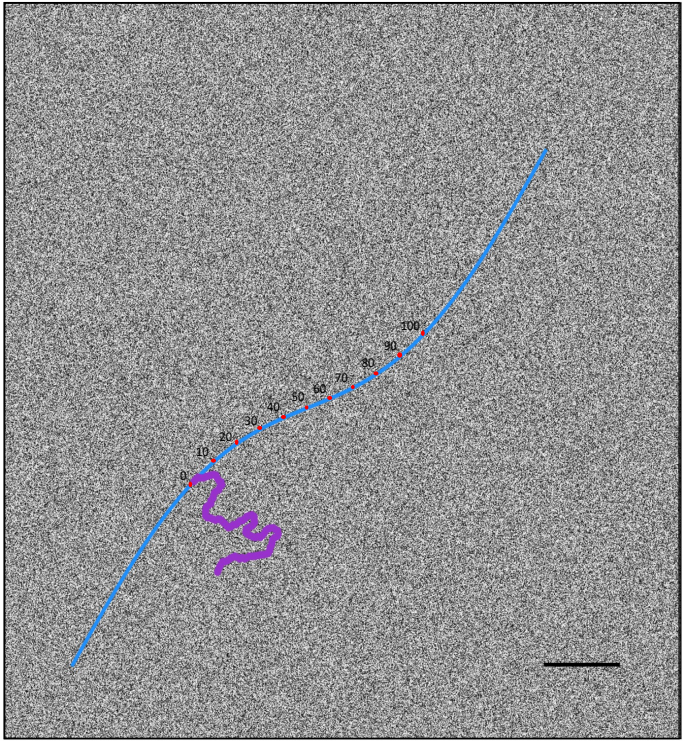
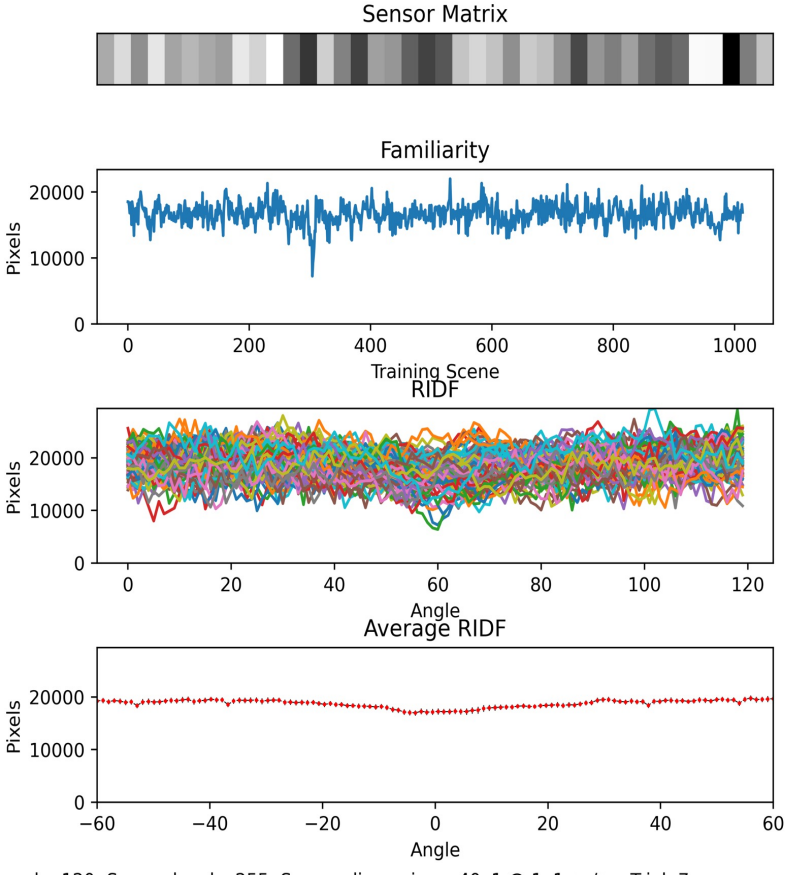
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
TD
20000
Sensor regions

0%

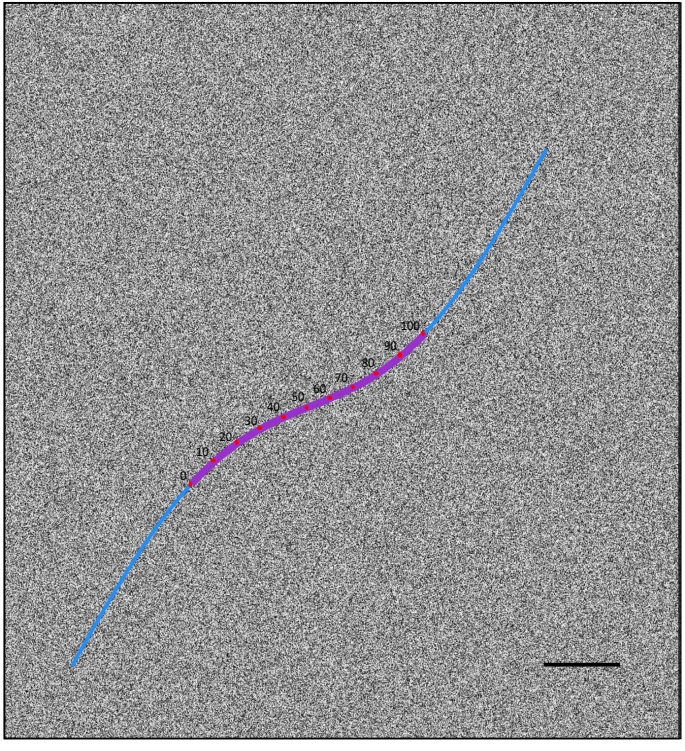


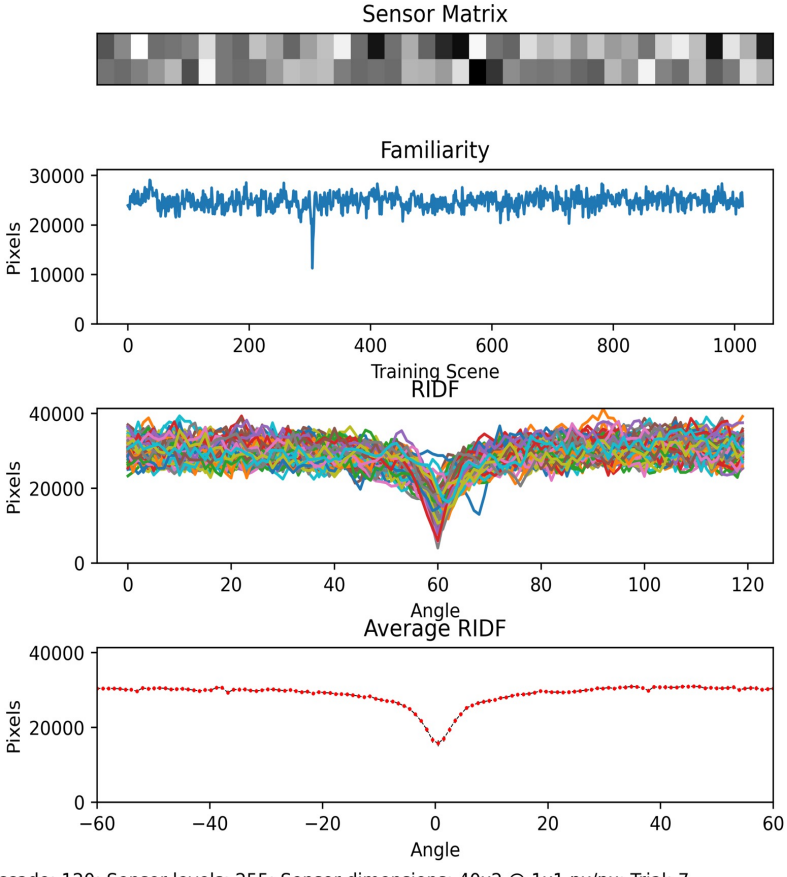


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 8564.70; RMSD/dist: 21.412; TD: -826; p90: 8; p50: 8; complete: 0

100%

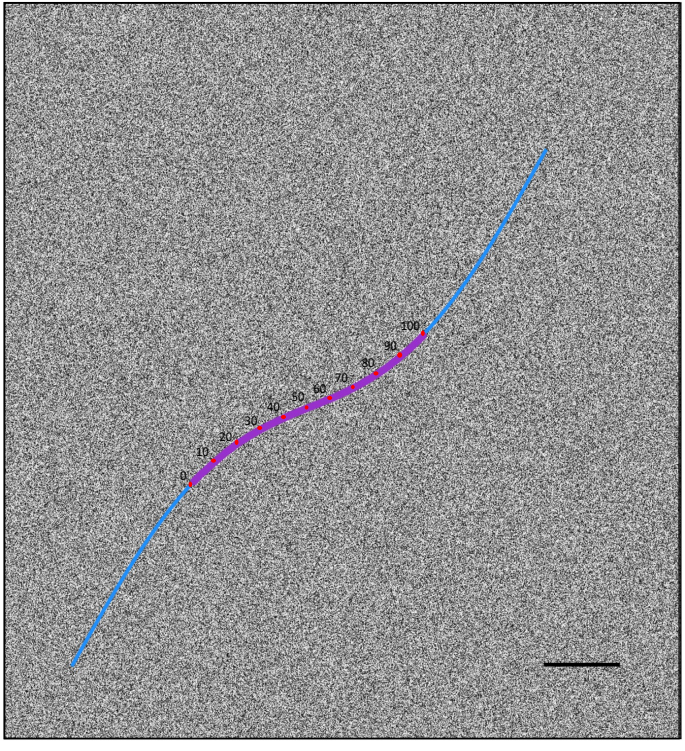


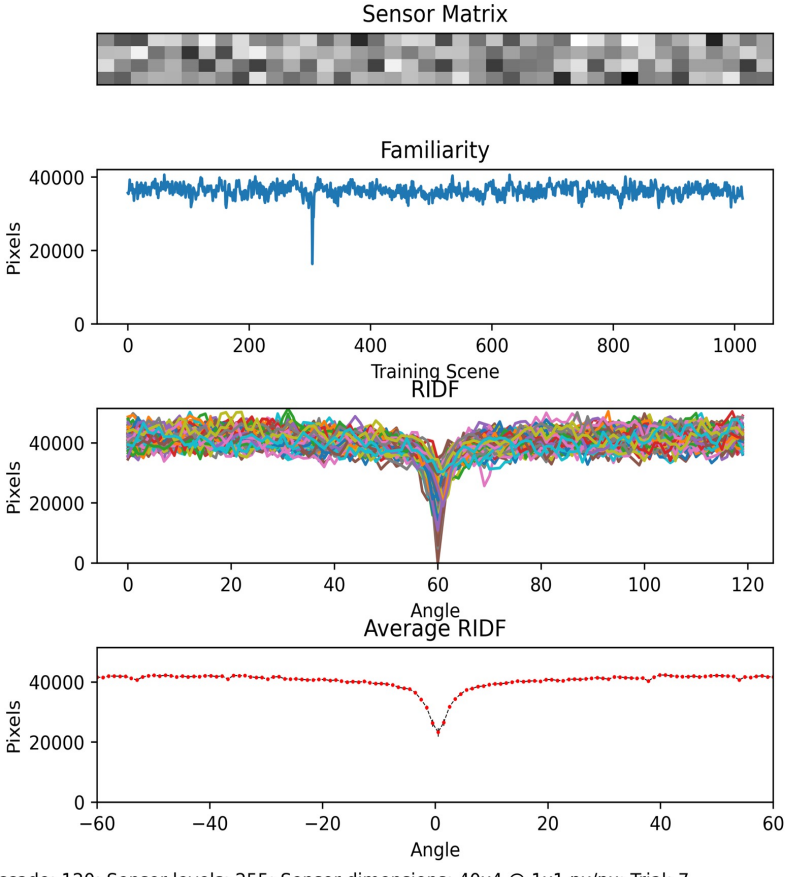


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 39.72; RMSD/dist: 0.099; TD: 9021; p90: 8; p50: 4; complete: 0

100%

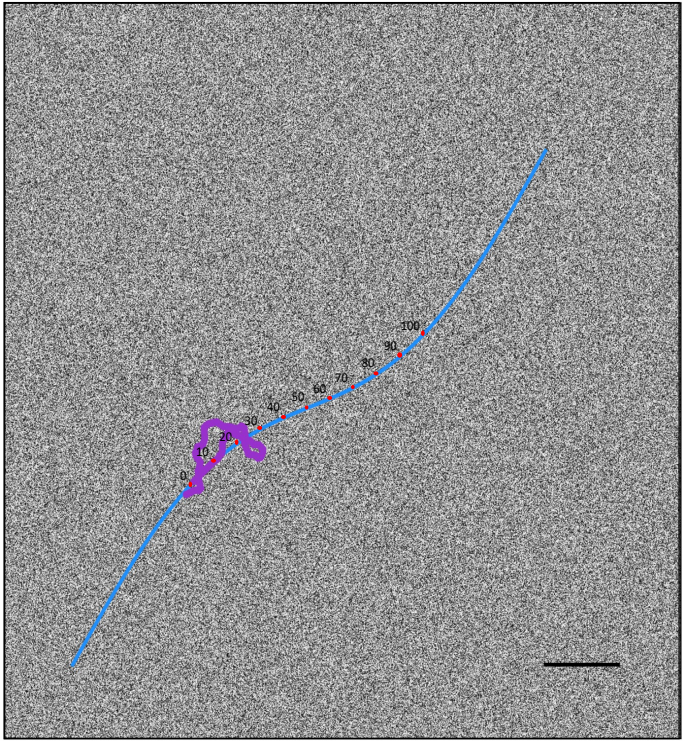


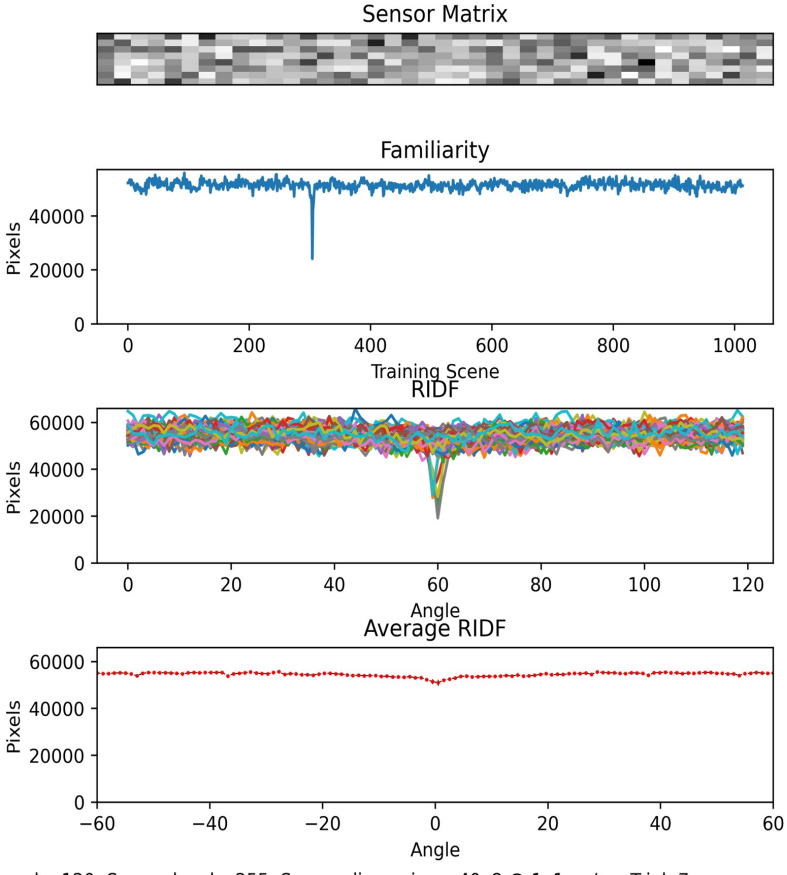


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 30.77; RMSD/dist: 0.077; TD: 13004; p90: 6; p50: 4; complete: 0

10%

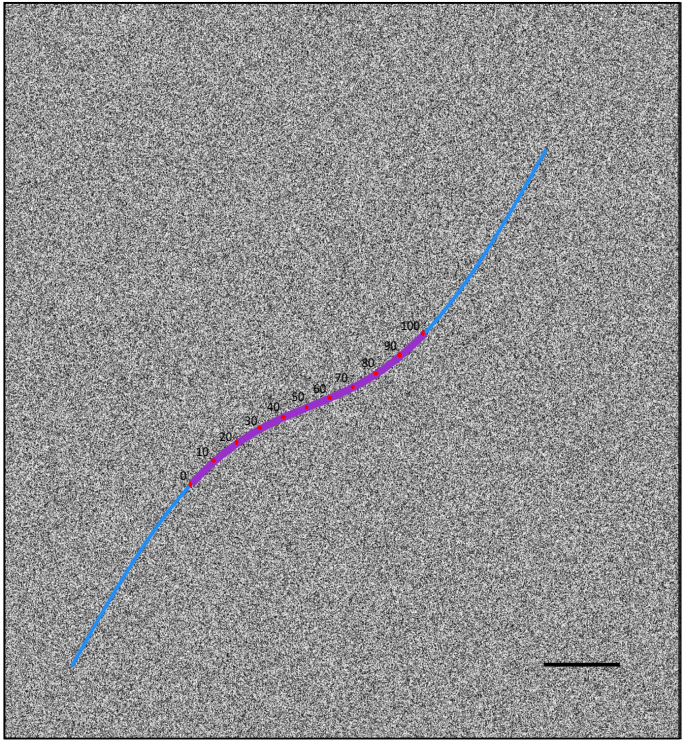


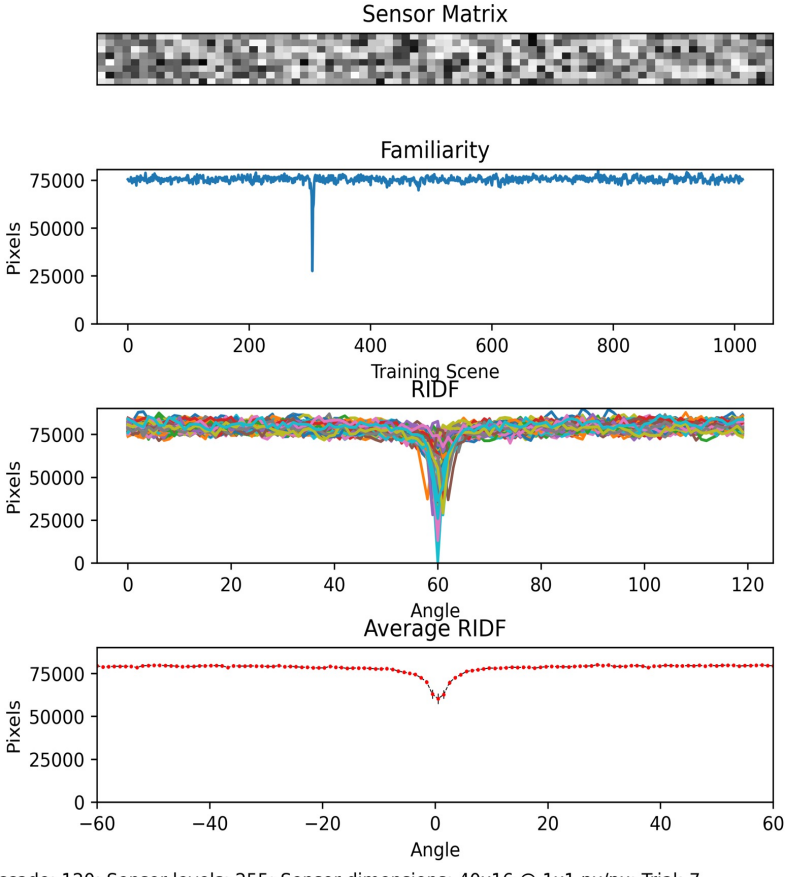


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1628.22; RMSD/dist: 4.071; TD: 369; p90: 2; p50: 2; complete: 0

100%

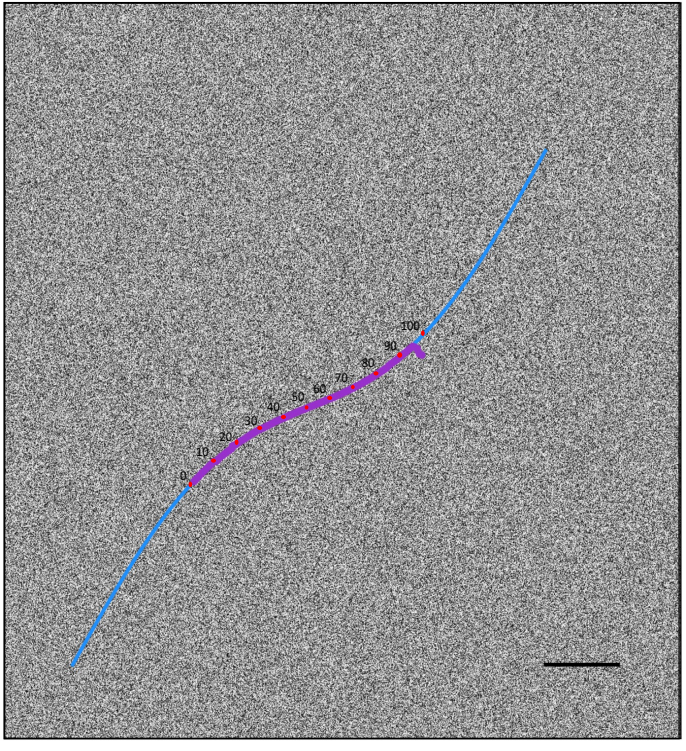


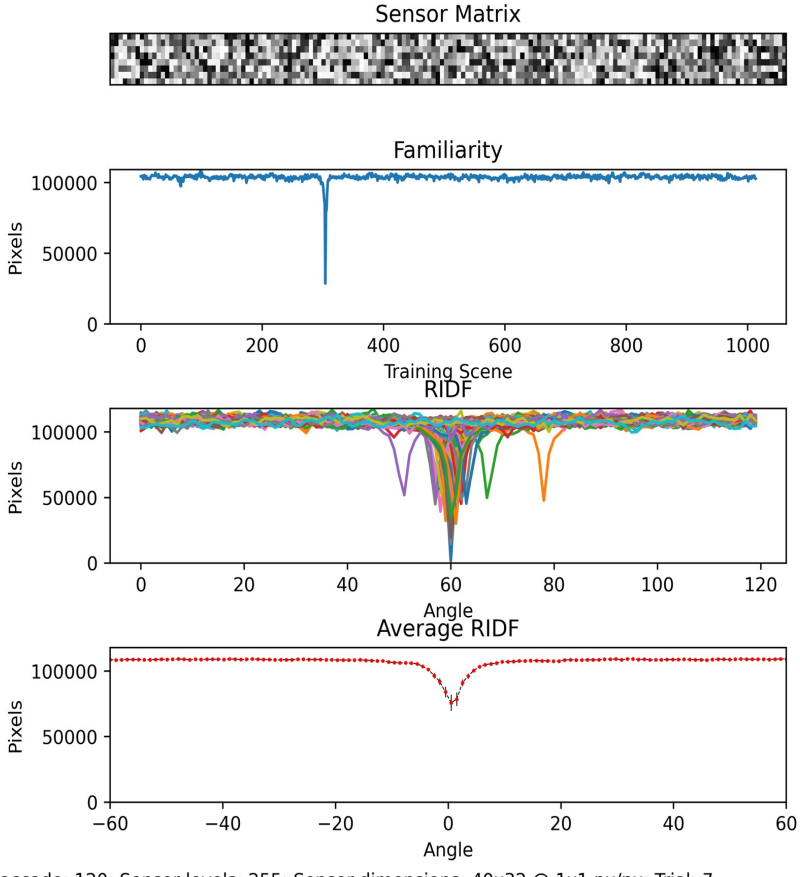


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 62.73; RMSD/dist: 0.157; TD: 13873; p90: 6; p50: 4; complete: 0

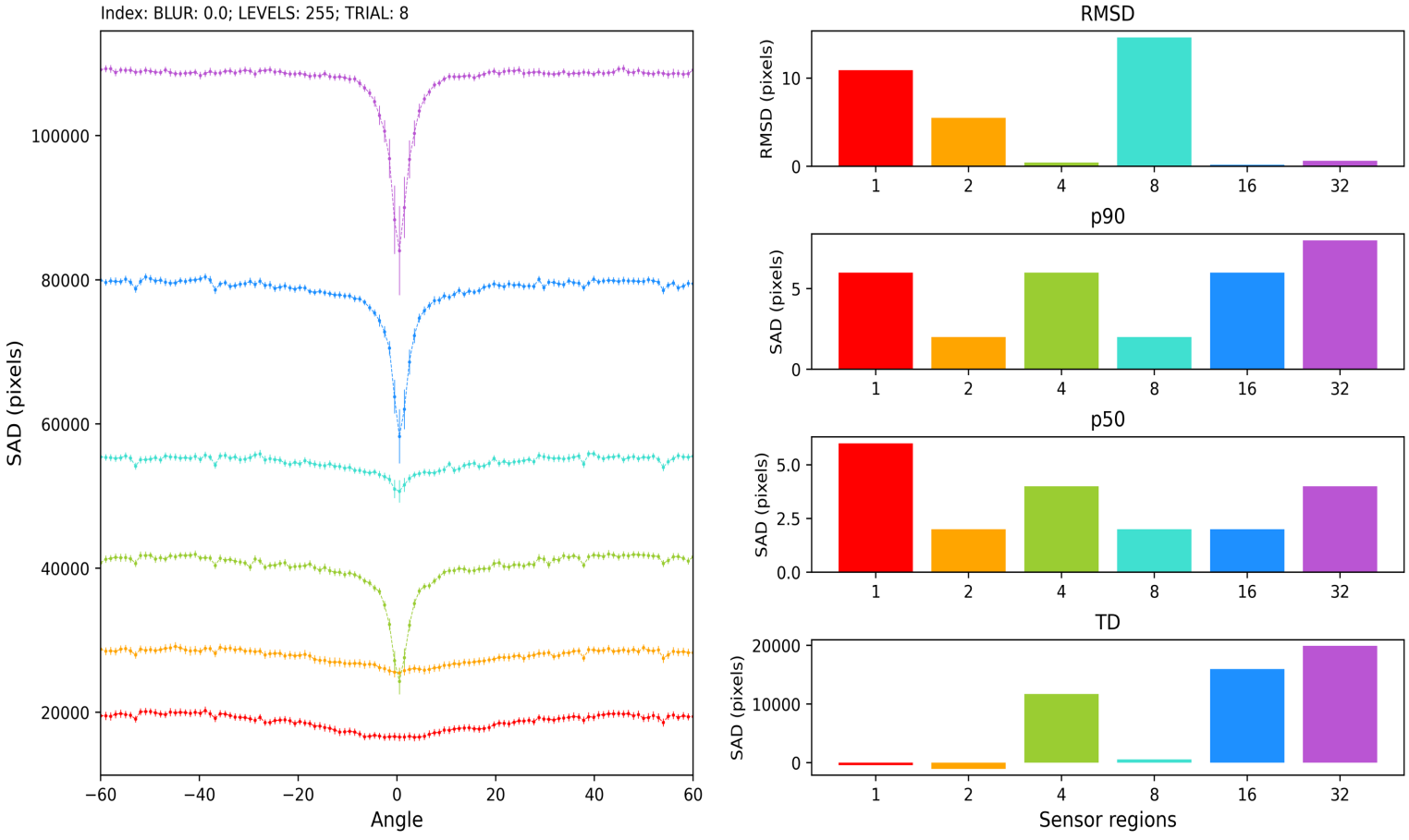
90%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 103.75; RMSD/dist: 0.259; TD: 28021; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.0; LEVELS: 255; TRIAL: 8
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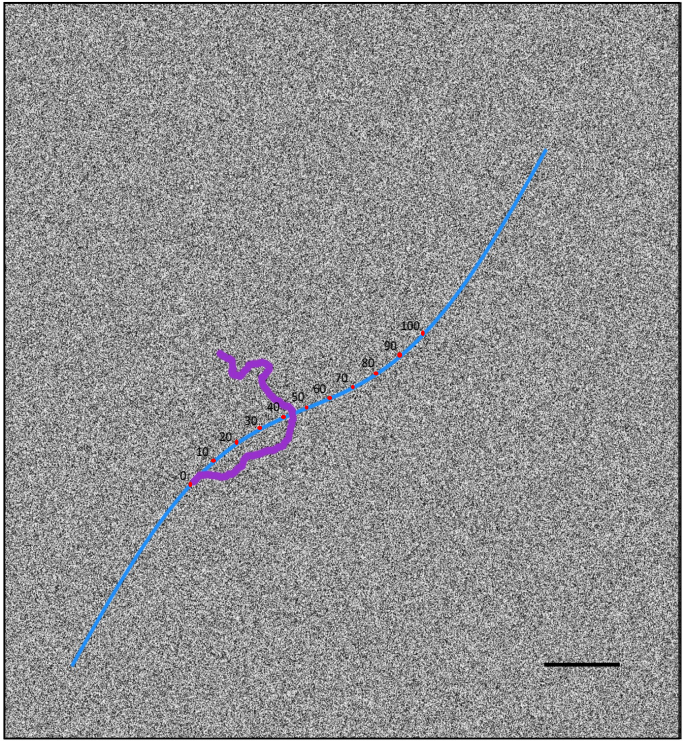
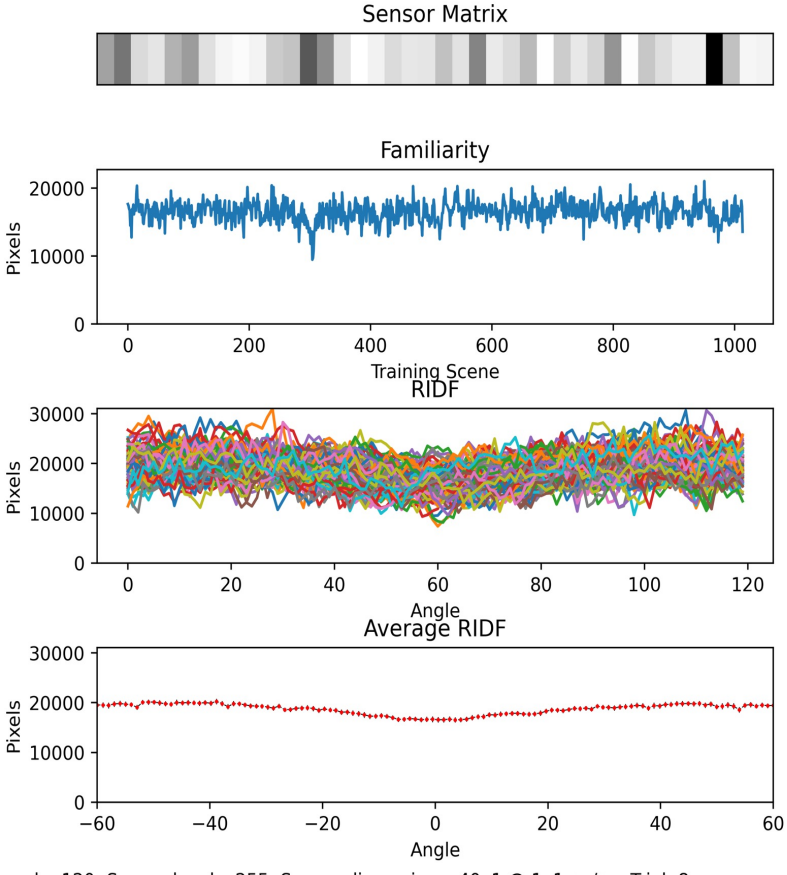
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

0%

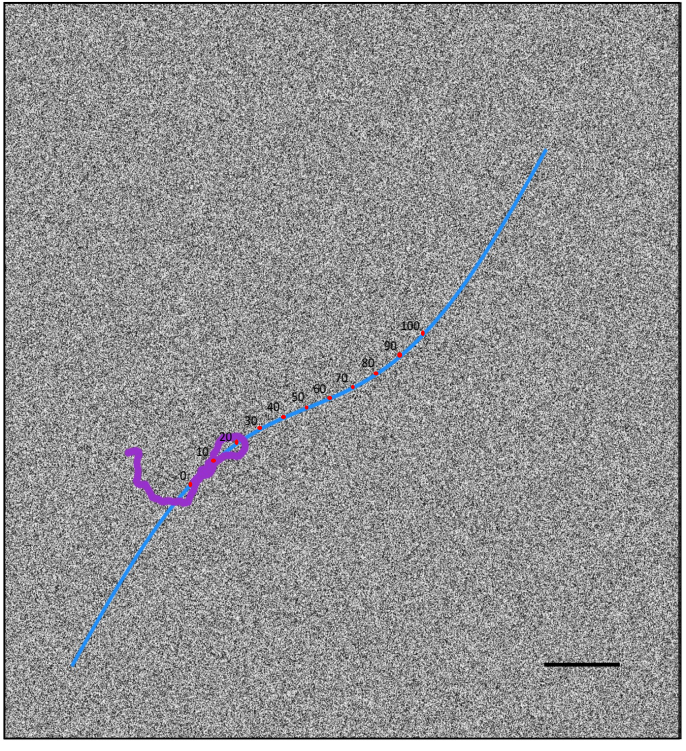


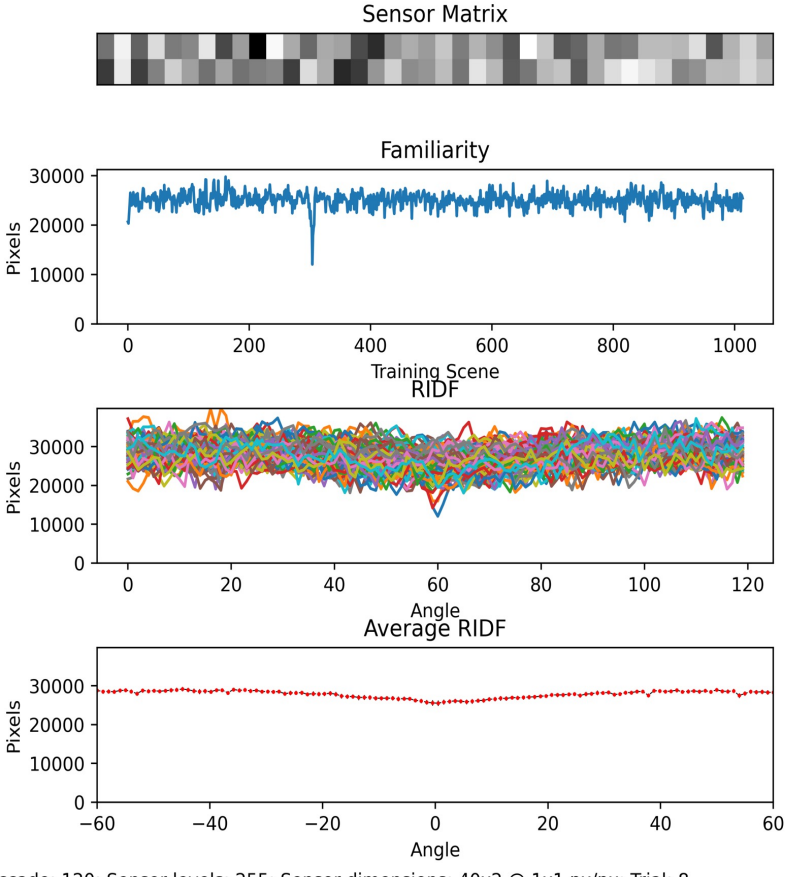


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 4354.36; RMSD/dist: 10.886; TD: -427; p90: 6; p50: 6; complete: 0

10%

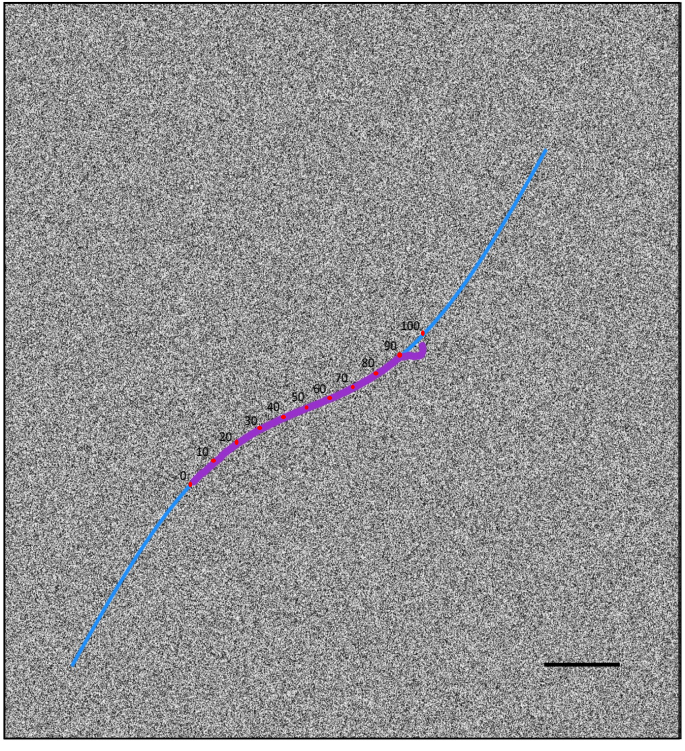


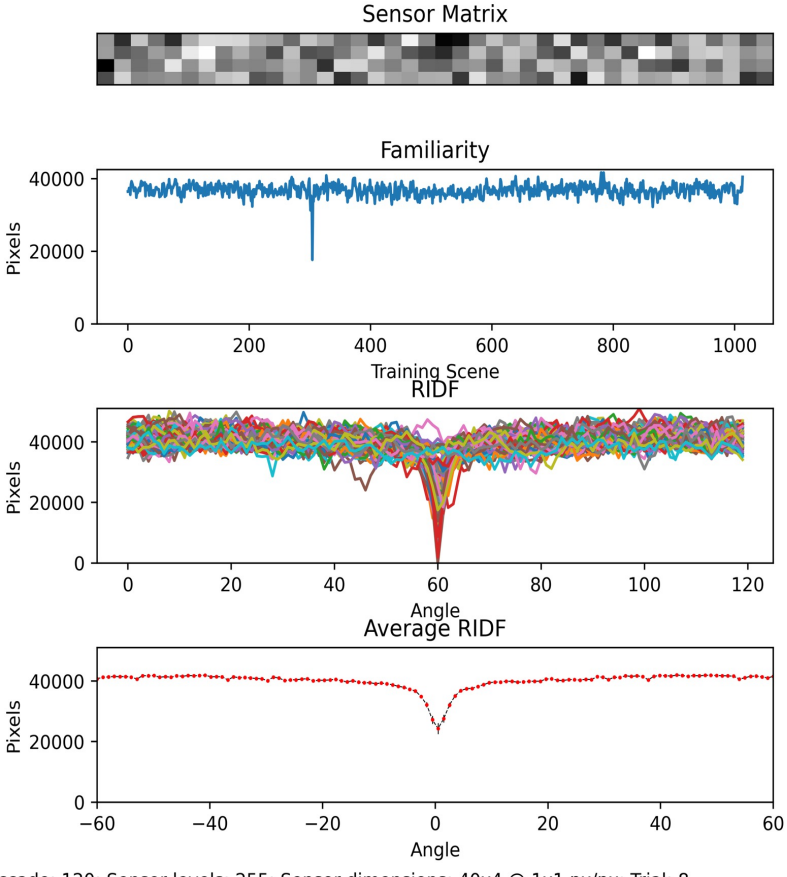


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2198.52; RMSD/dist: 5.496; TD: -1048; p90: 2; p50: 2; complete: 0

90%

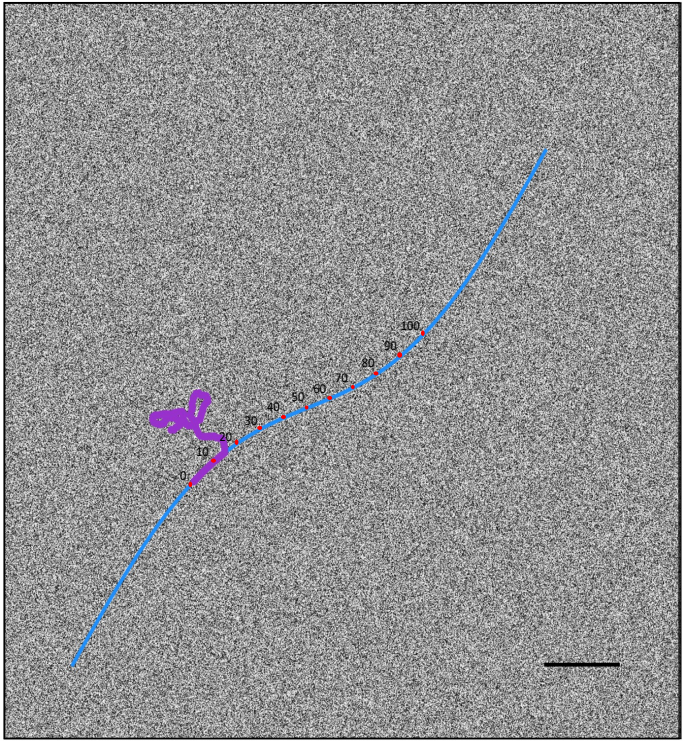


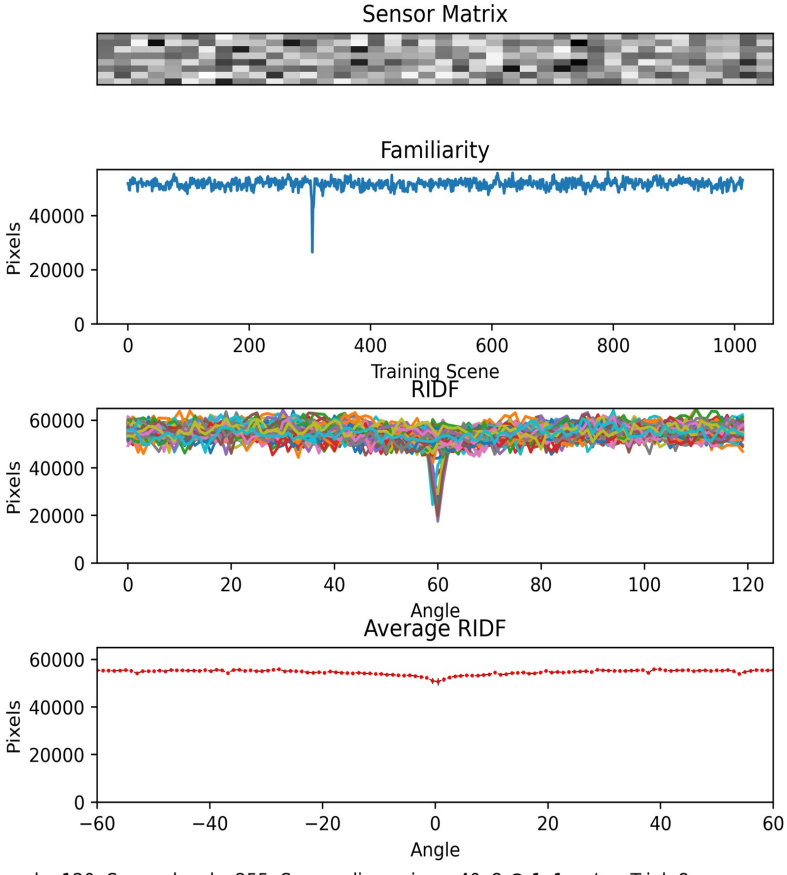


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 164.96; RMSD/dist: 0.412; TD: 11718; p90: 6; p50: 4; complete: 0

10%

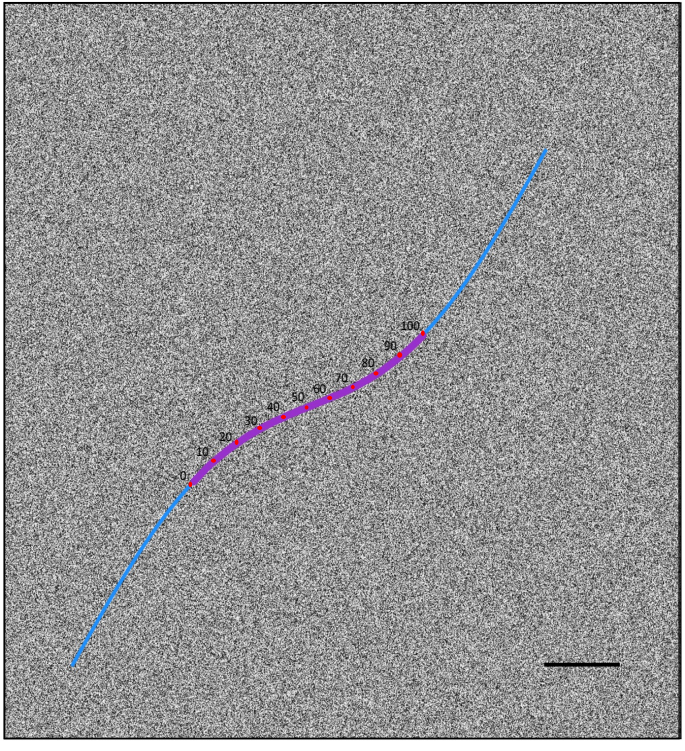


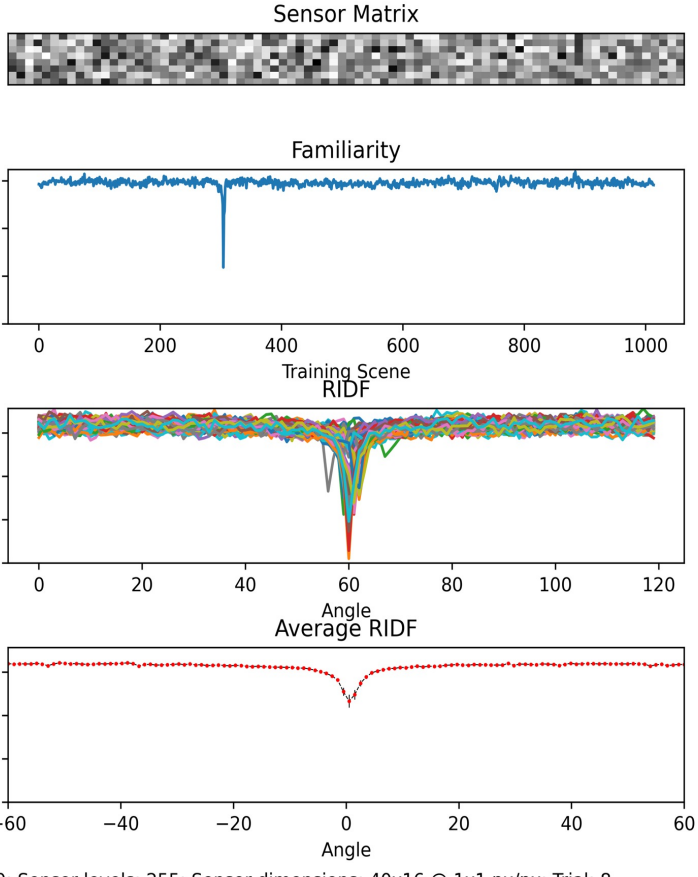


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5843.04; RMSD/dist: 14.608; TD: 557; p90: 2; p50: 2; complete: 0

100%

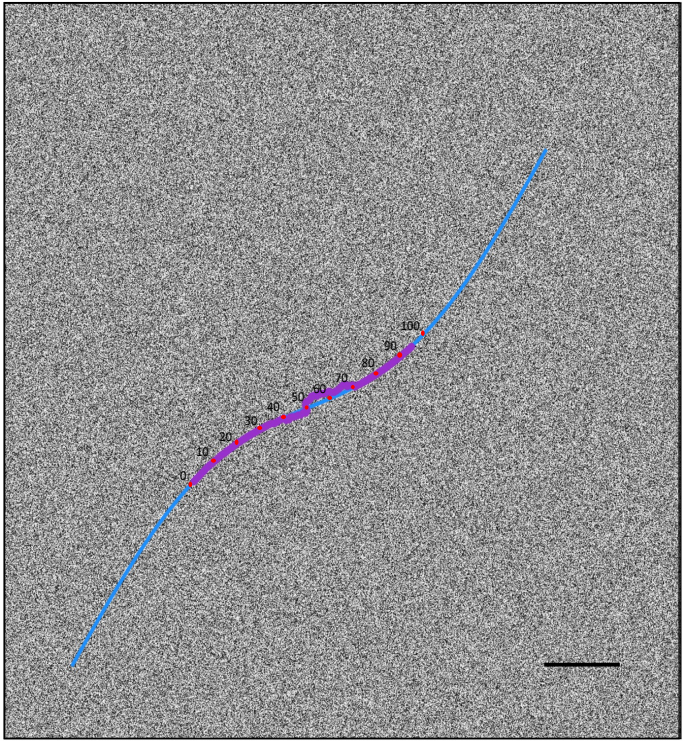


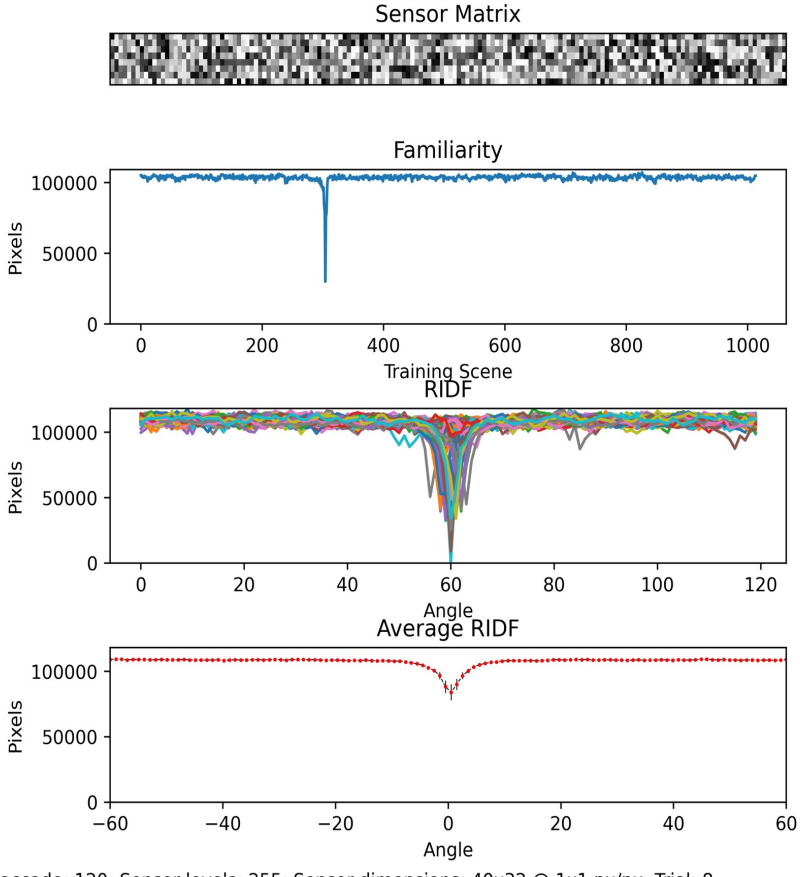


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 70.08; RMSD/dist: 0.175; TD: 15963; p90: 6; p50: 2; complete: 0

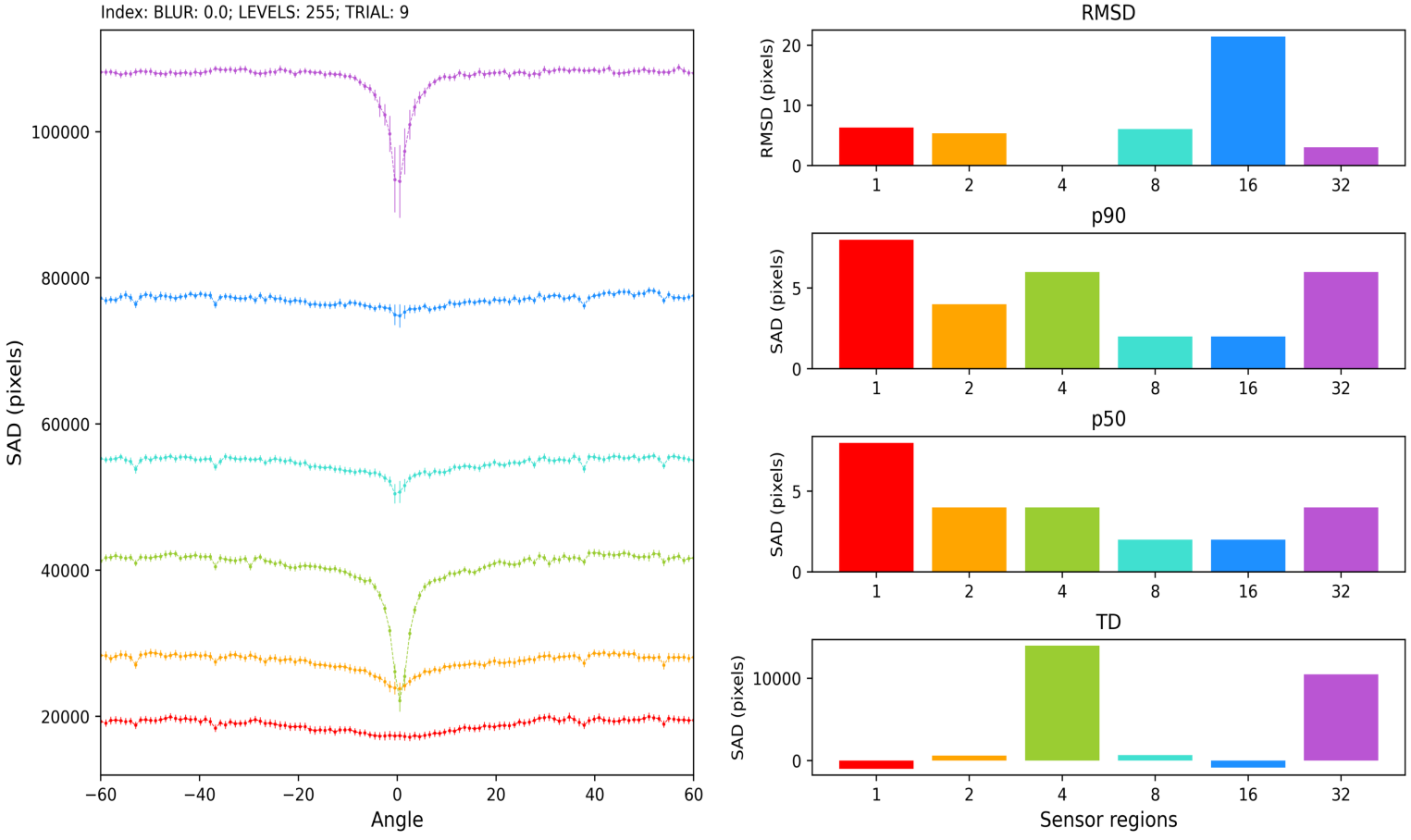
70%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 252.55; RMSD/dist: 0.631; TD: 19902; p90: 8; p50: 4; complete: 0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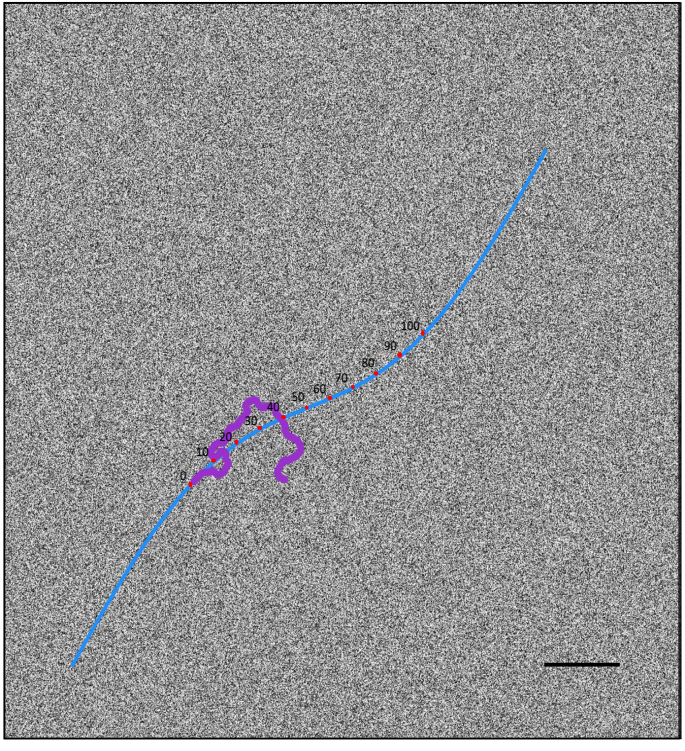
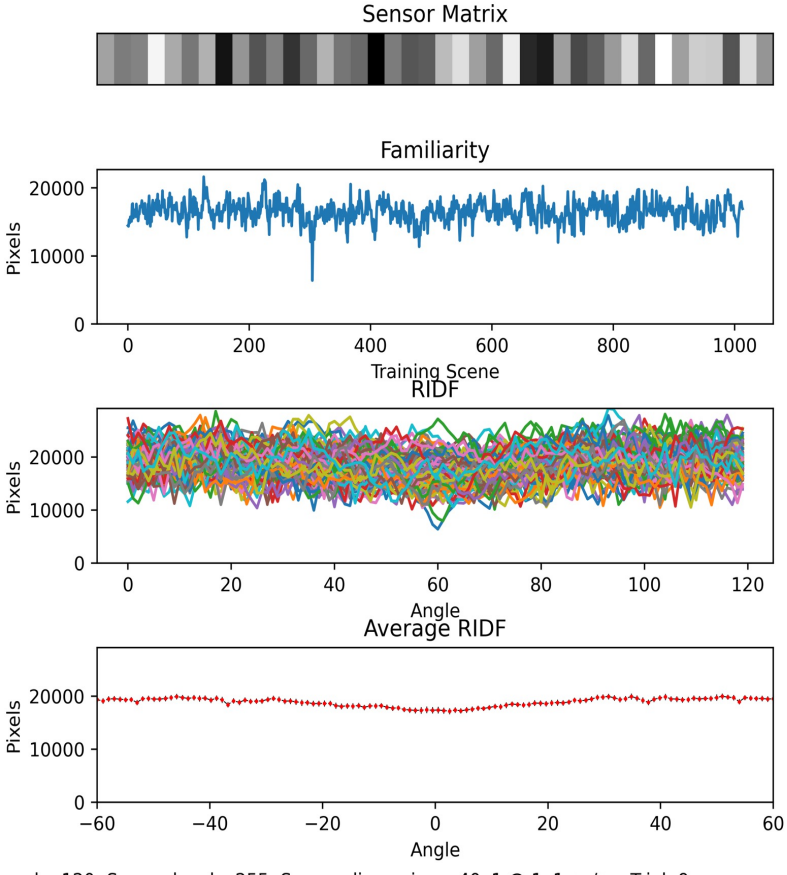
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
TD
10000
Sensor regions

0%

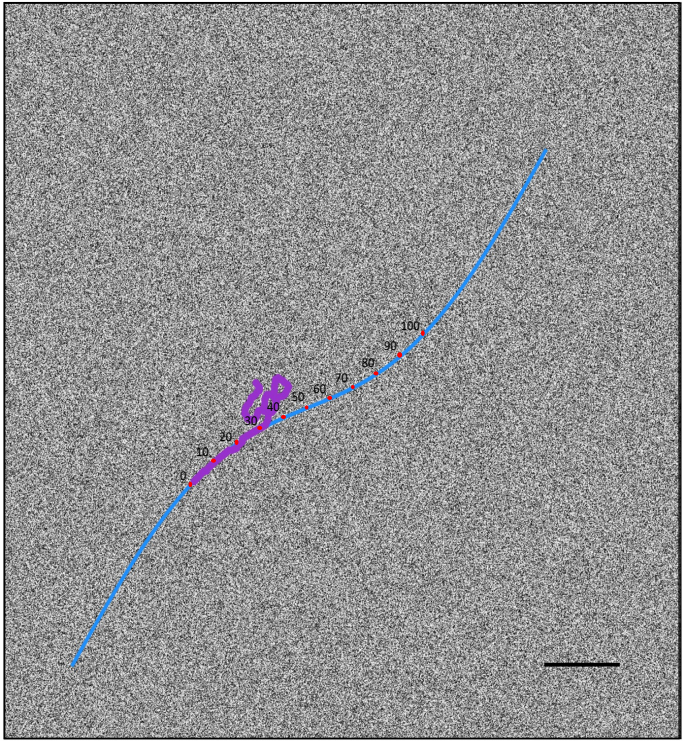


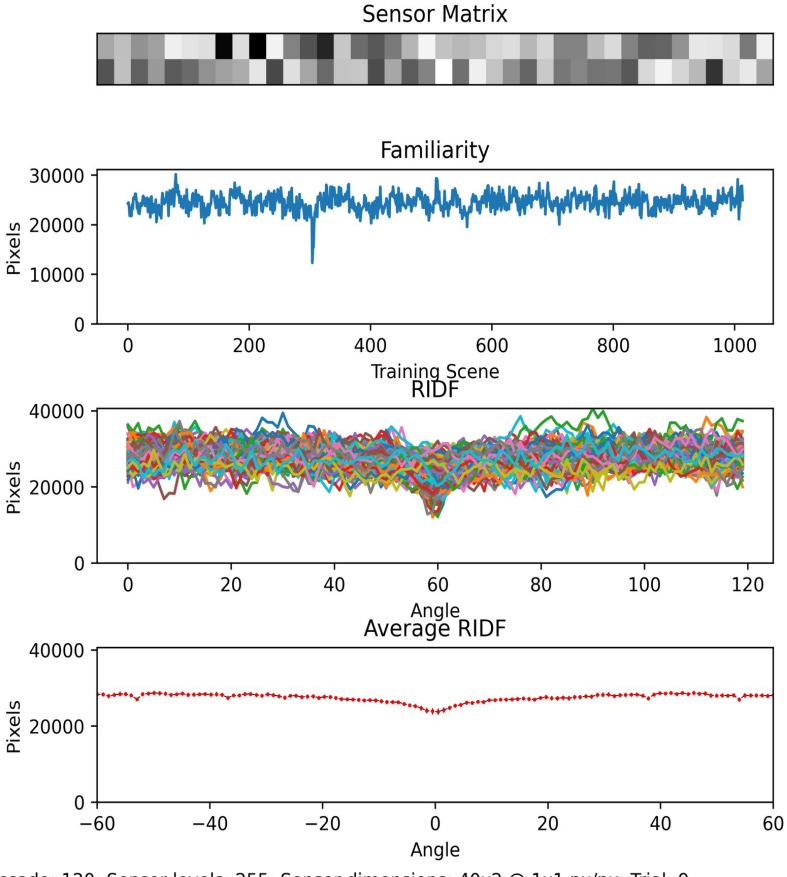


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2524.84; RMSD/dist: 6.312; TD: -1011; p90: 8; p50: 8; complete: 0

20%

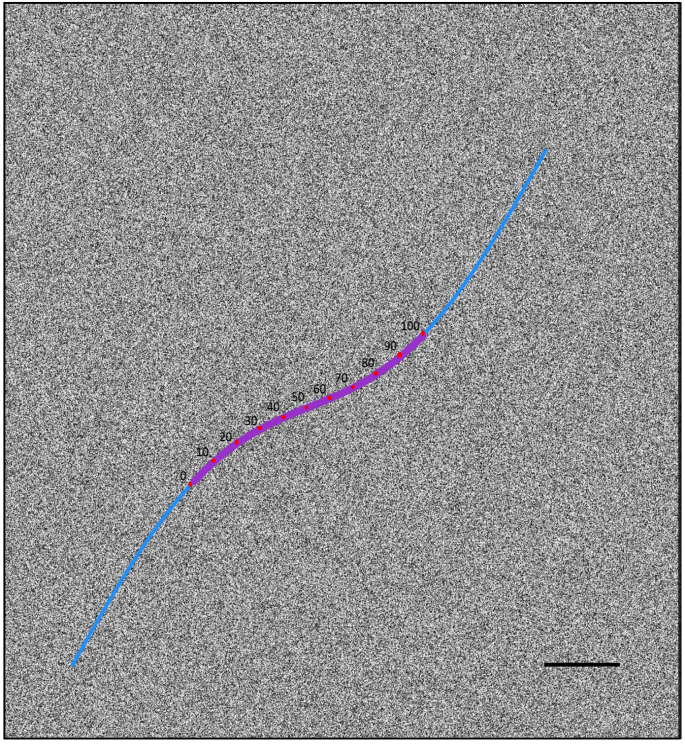


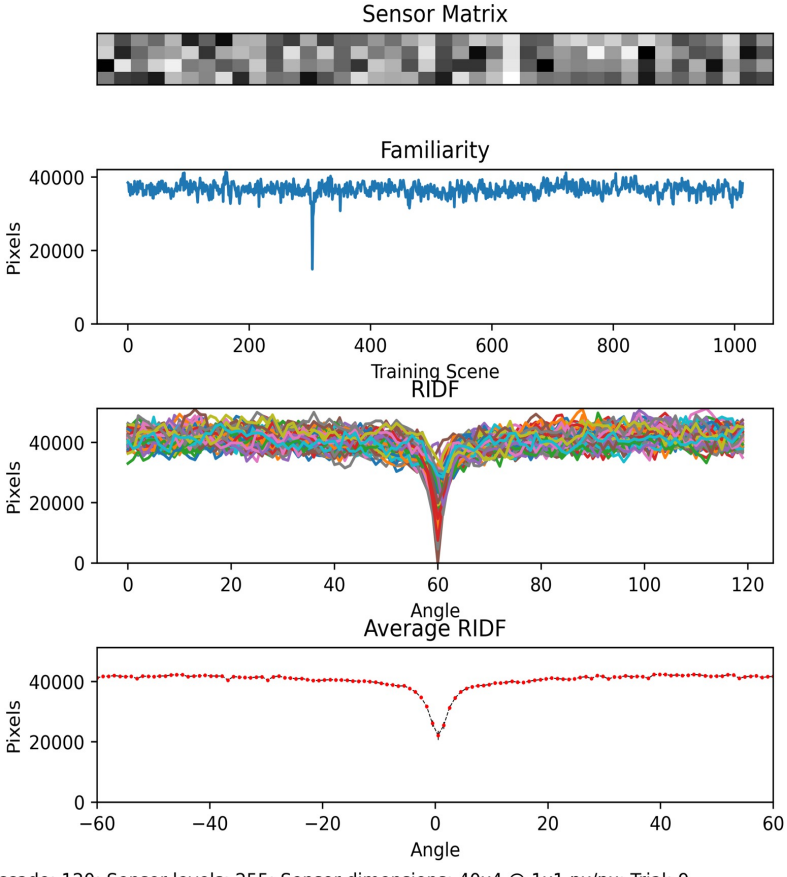


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2142.39; RMSD/dist: 5.356; TD: 599; p90: 4; p50: 4; complete: 0

100%

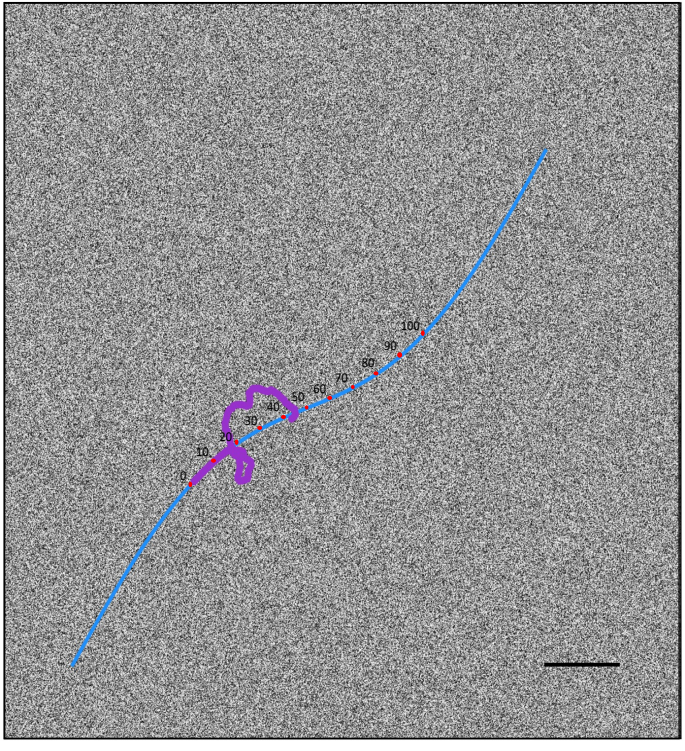


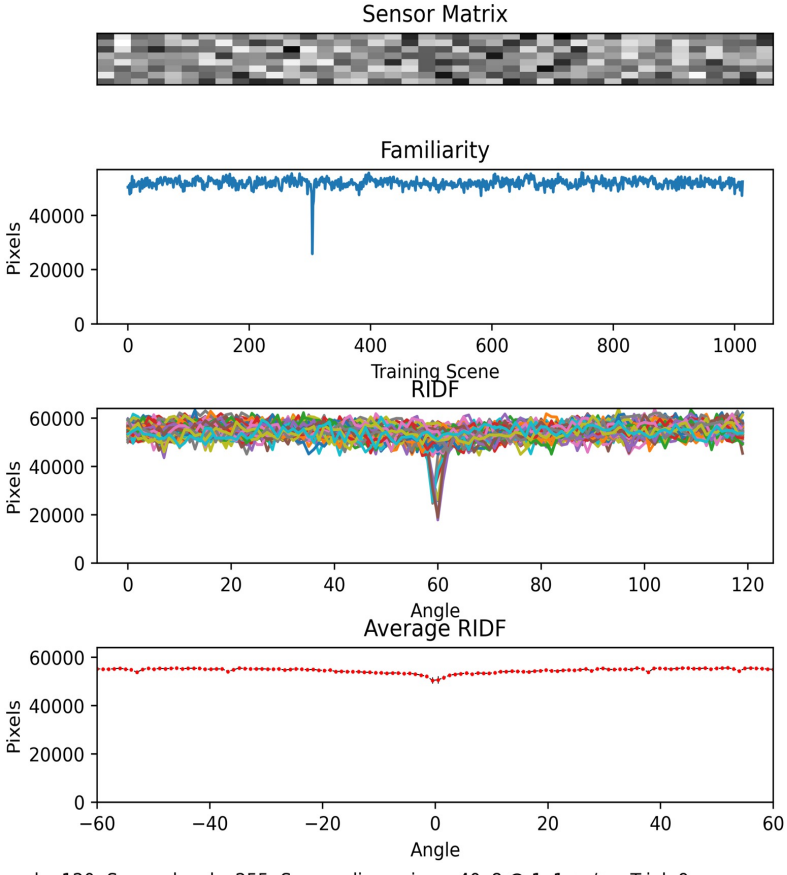


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 35.85; RMSD/dist: 0.090; TD: 13960; p90: 6; p50: 4; complete: 0

10%

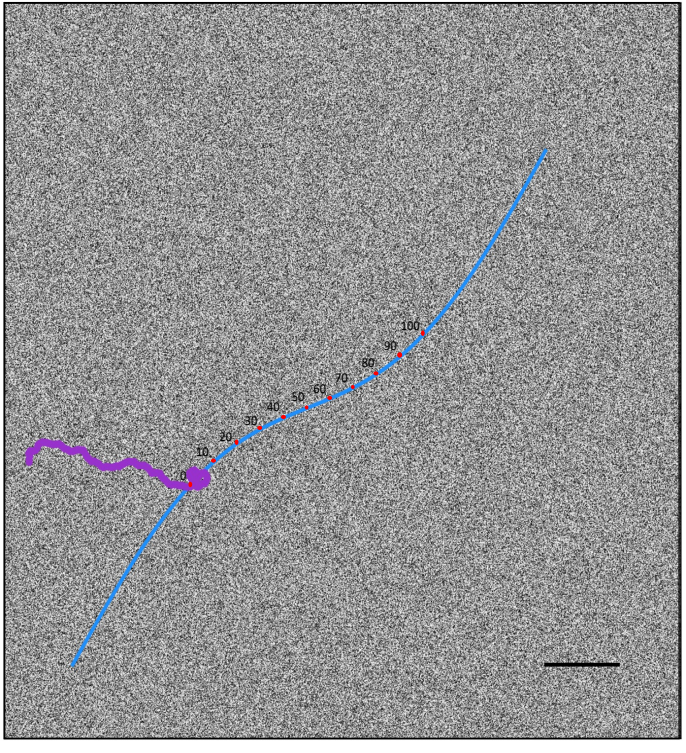


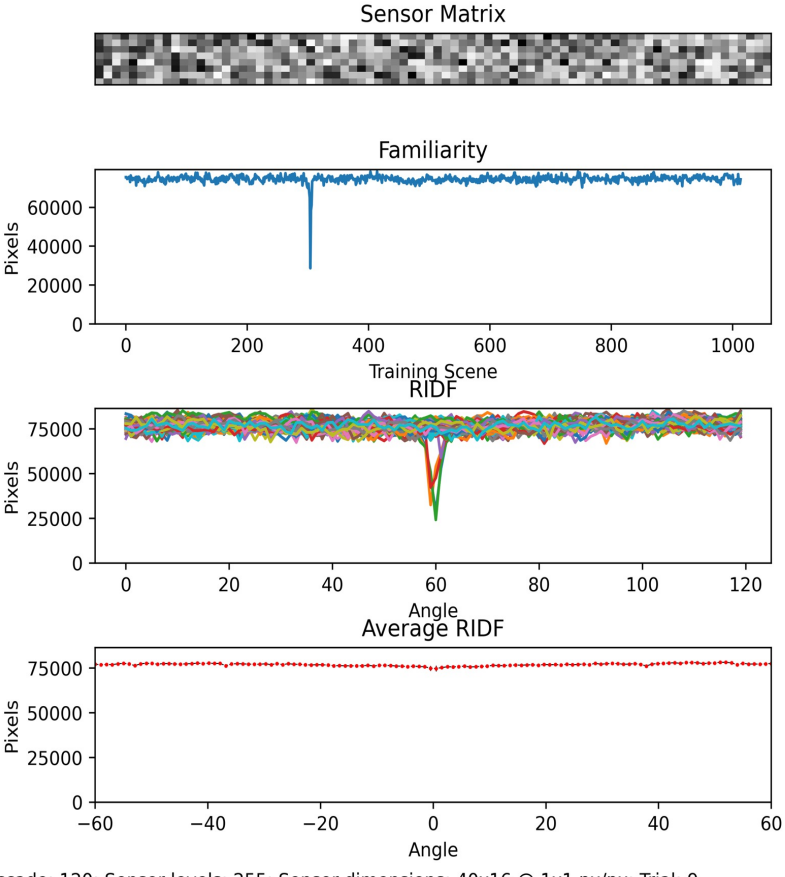


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2430.07; RMSD/dist: 6.075; TD: 666; p90: 2; p50: 2; complete: 0

0%

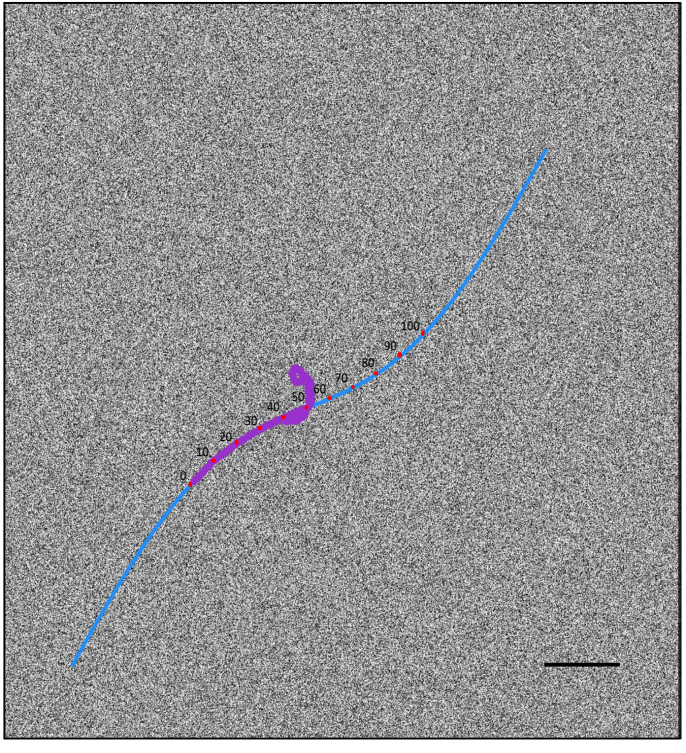


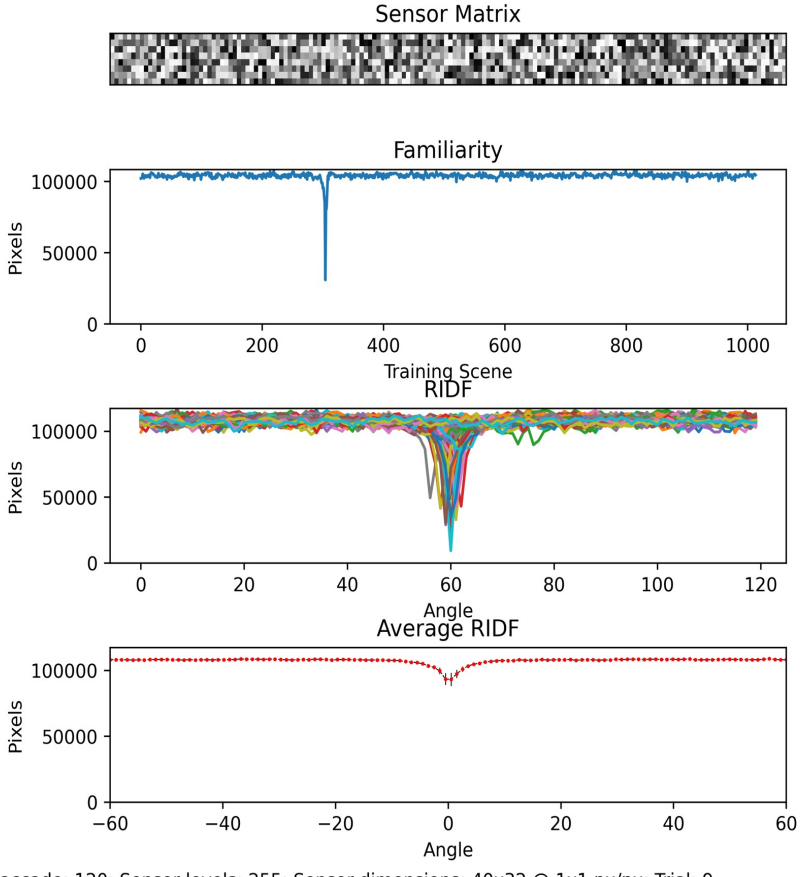


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 8578.85; RMSD/dist: 21.447; TD: -852; p90: 2; p50: 2; complete: 0

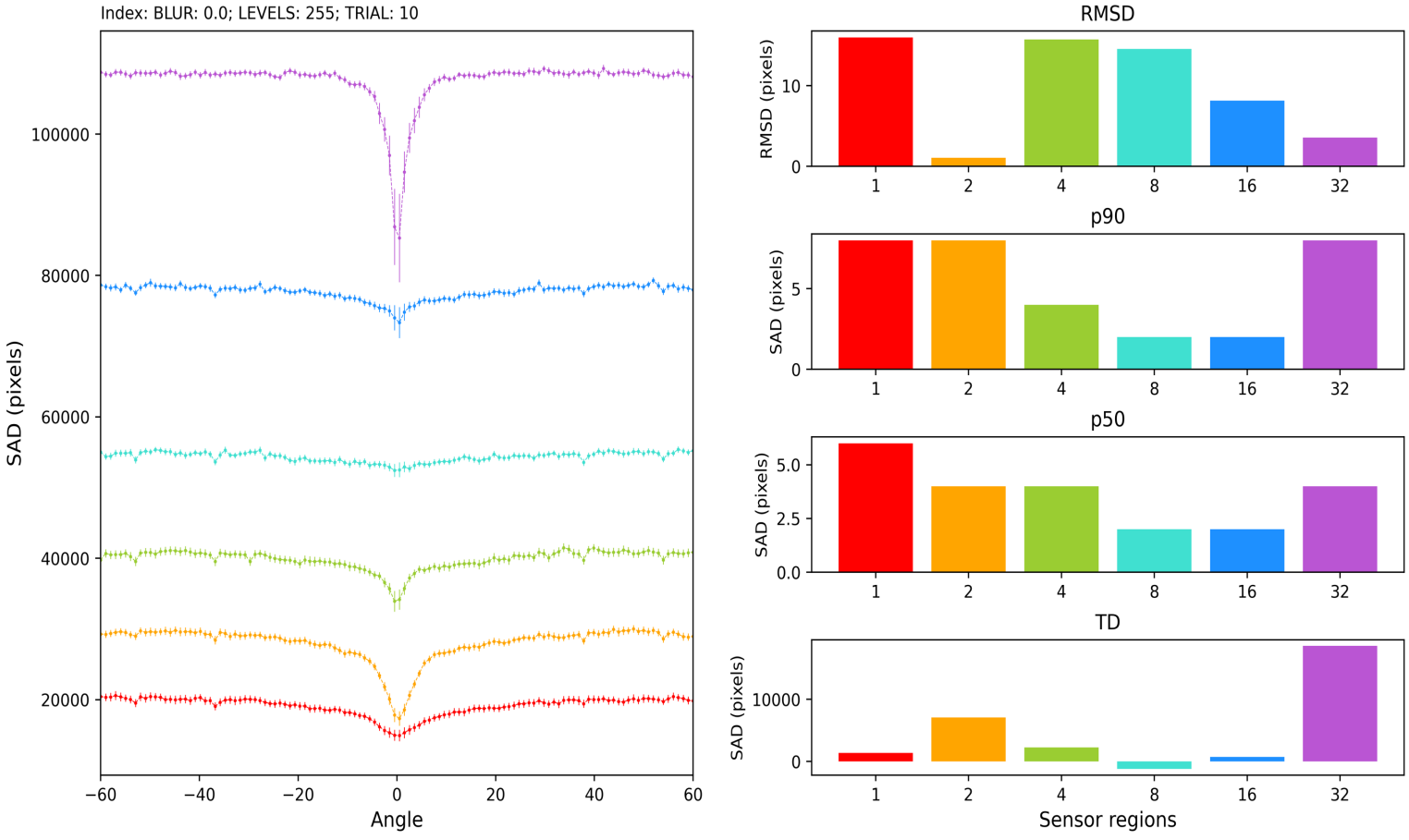
50%



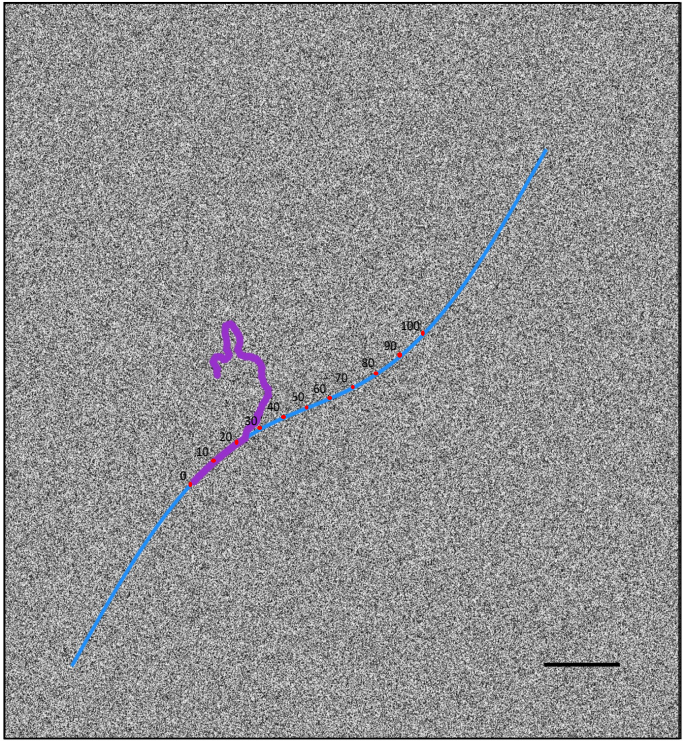


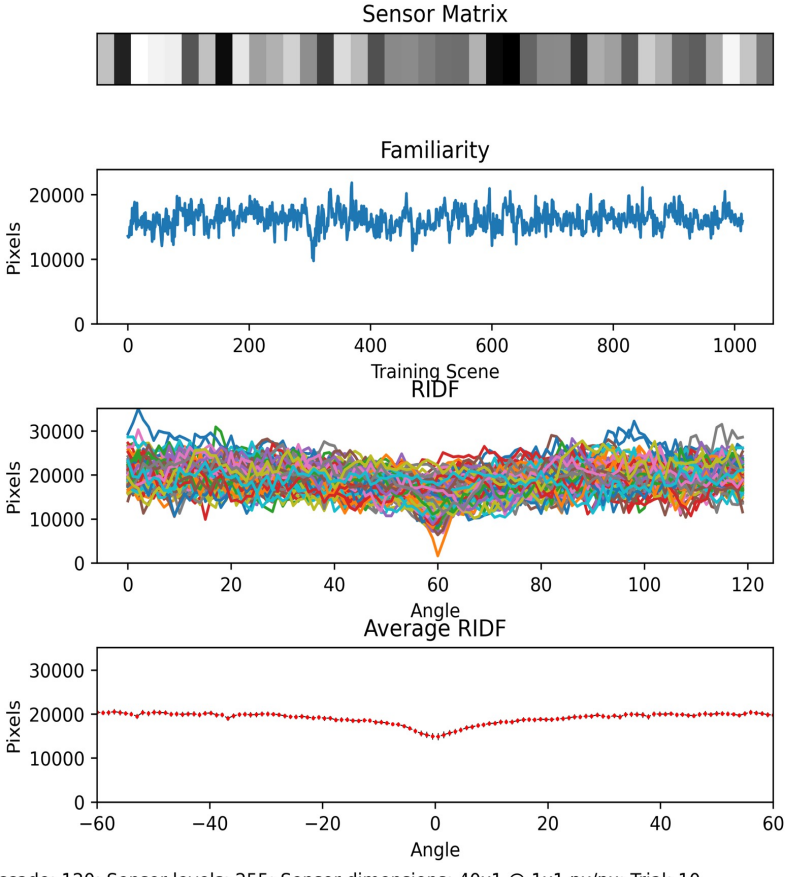
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1208.16; RMSD/dist: 3.020; TD: 10472; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
5.0
2.5
0.0
TD
SAD (pixels)
10000
0
Sensor regions

20%

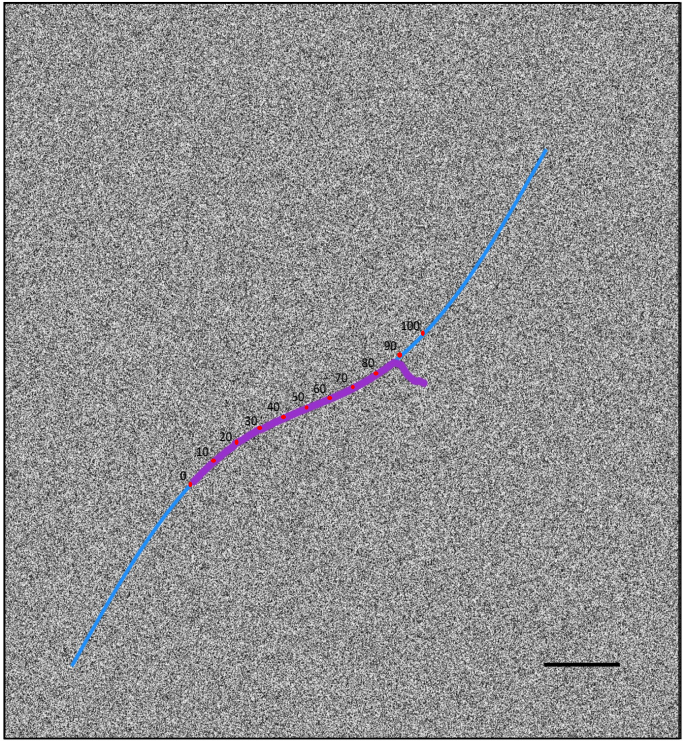


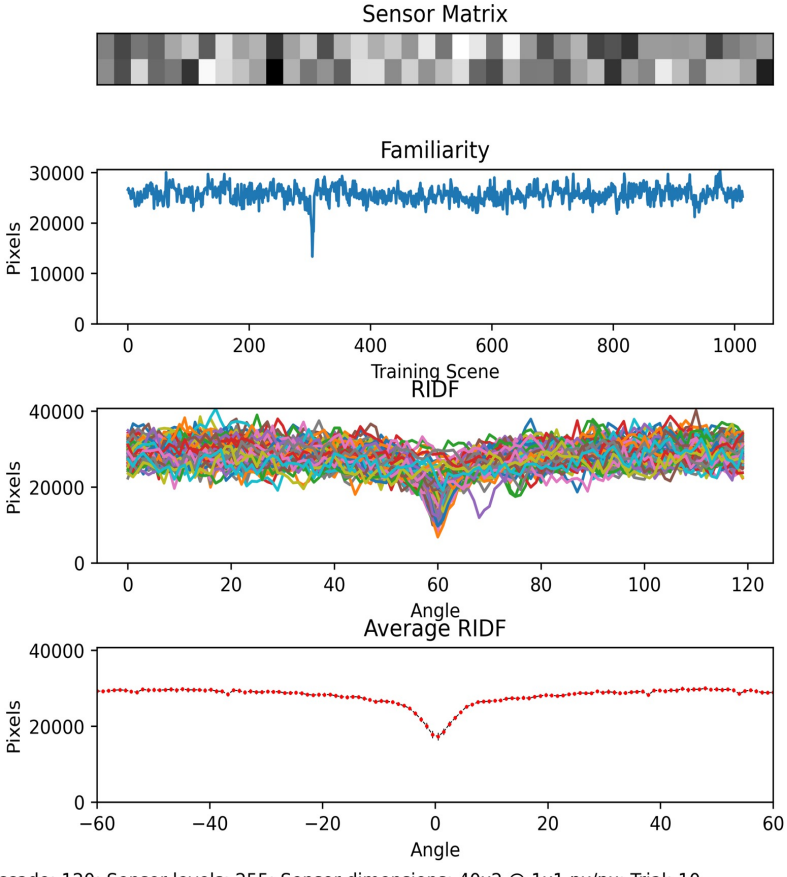


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 6401.45; RMSD/dist: 16.004; TD: 1371; p90: 8; p50: 6; complete: 0

80%

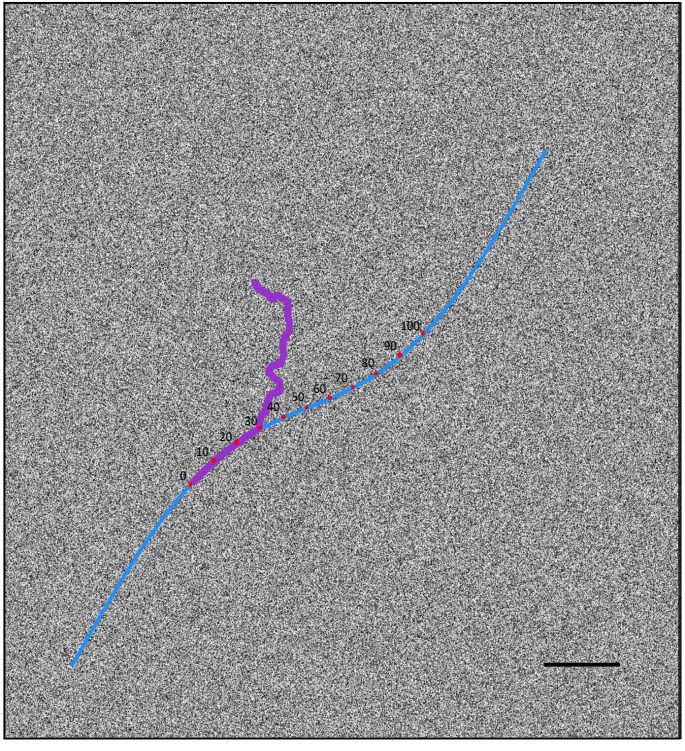


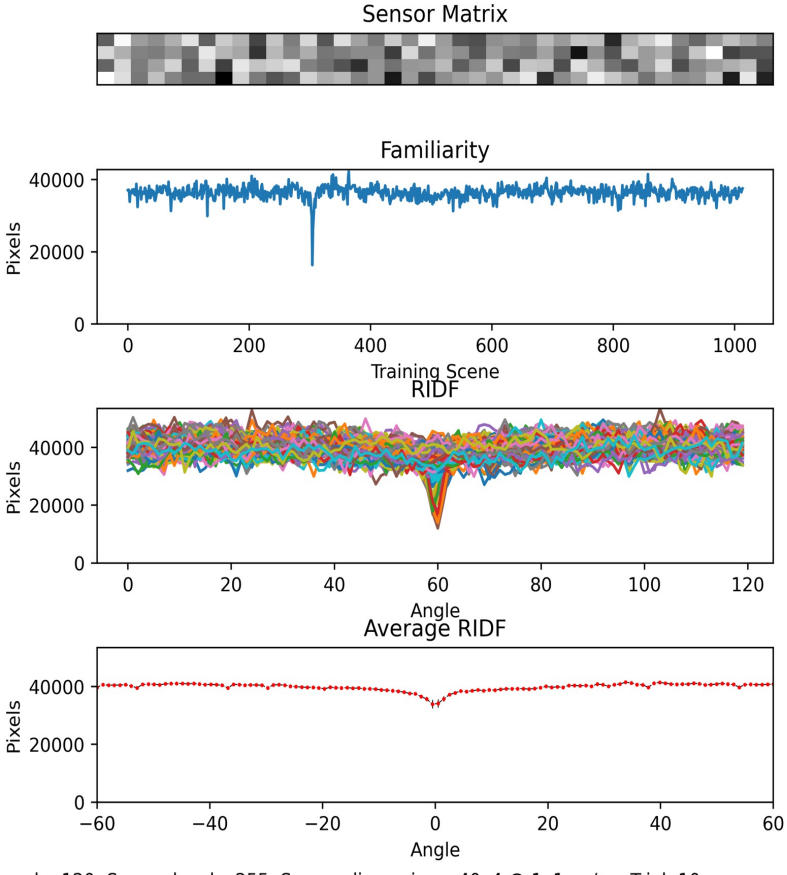


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 419.45; RMSD/dist: 1.049; TD: 7071; p90: 8; p50: 4; complete: 0

30%

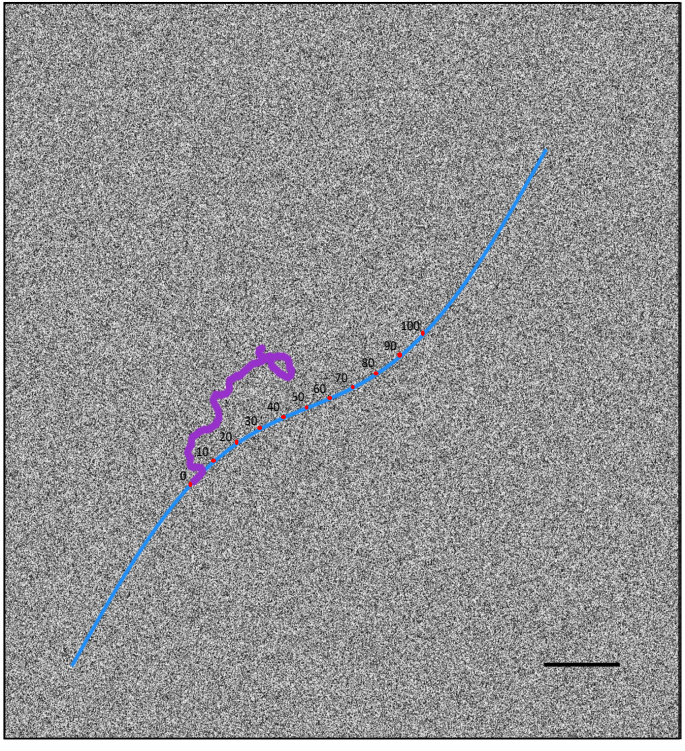


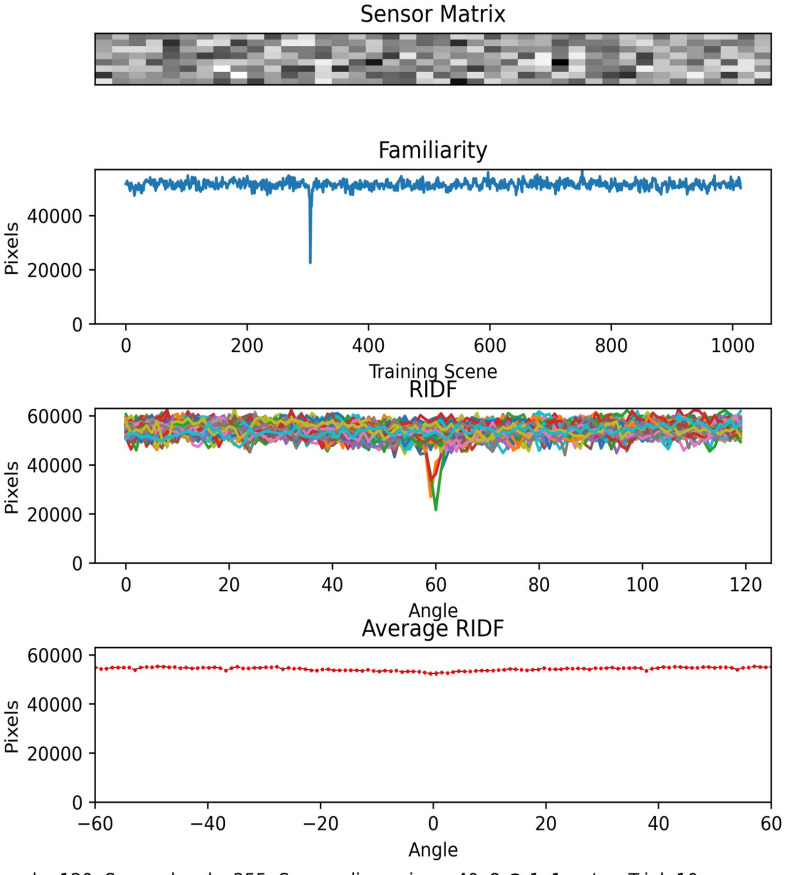


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 6300.28; RMSD/dist: 15.751; TD: 2275; p90: 4; p50: 4; complete: 0

0%

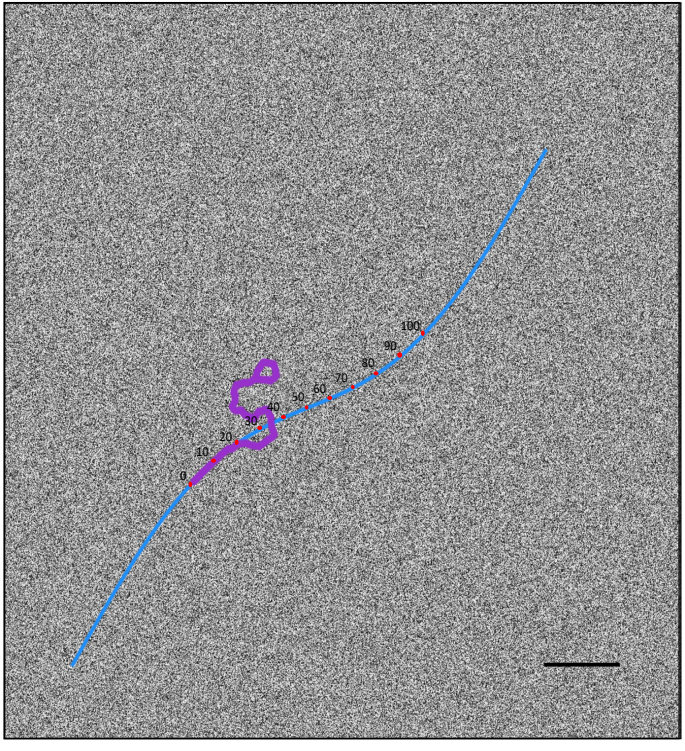


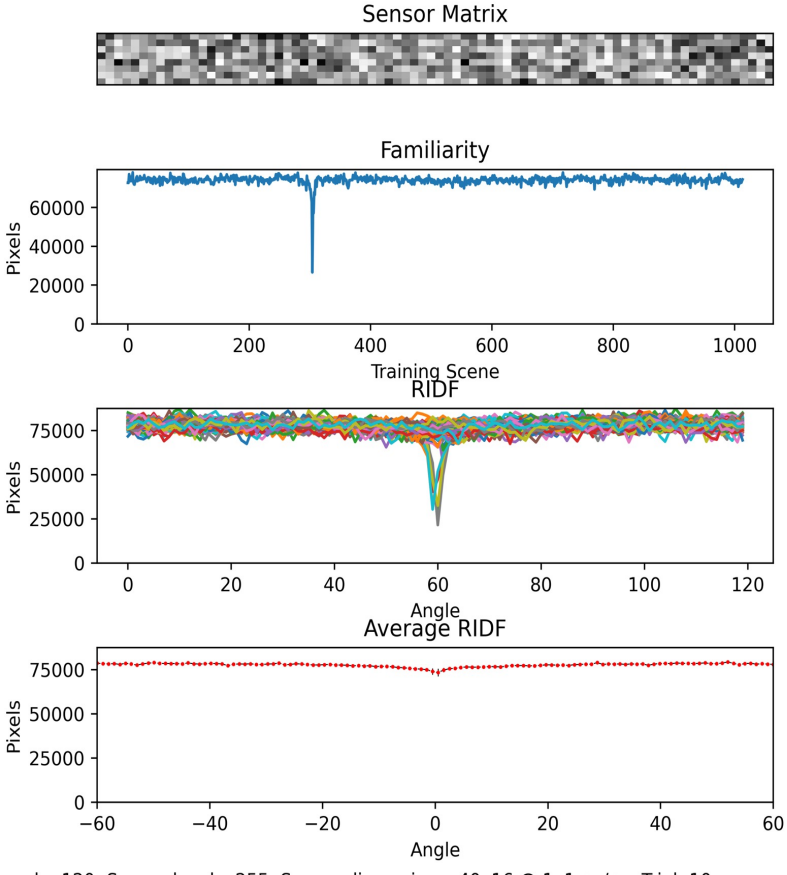


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 5827.01; RMSD/dist: 14.568; TD: -1198; p90: 2; p50: 2; complete: 0

20%

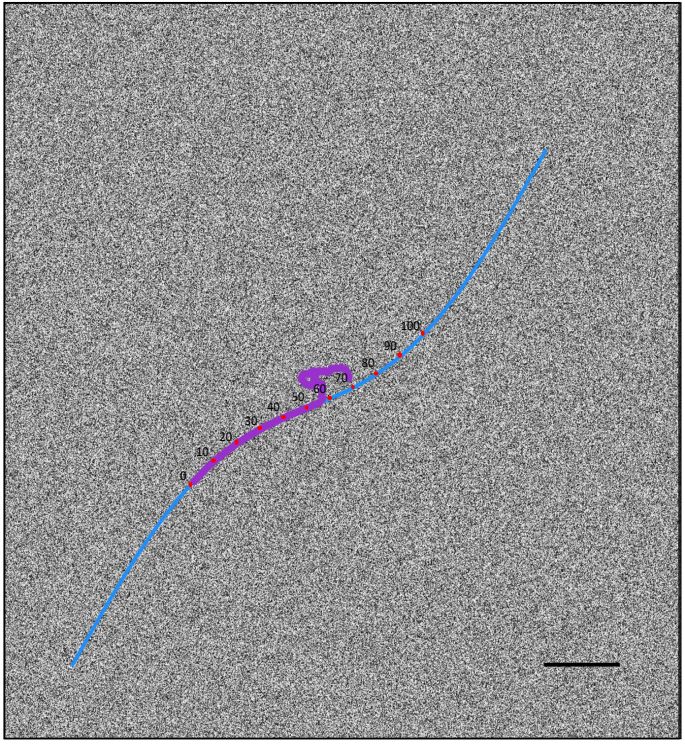


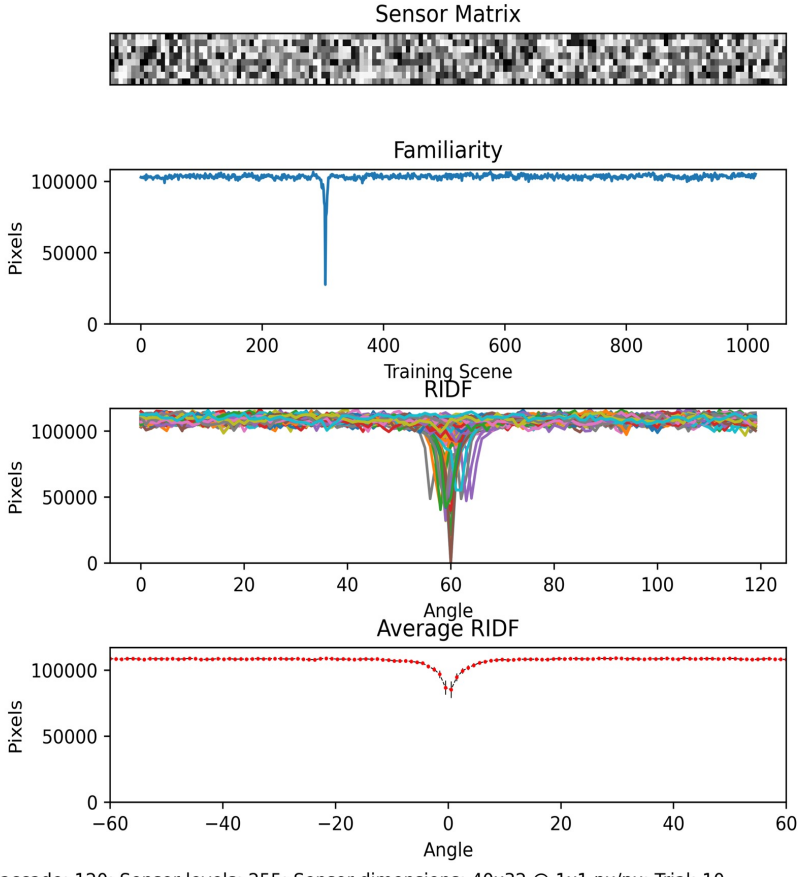


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3260.14; RMSD/dist: 8.150; TD: 741; p90: 2; p50: 2; complete: 0

50%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1420.05; RMSD/dist: 3.550; TD: 18608; p90: 8; p50: 4; complete: 0