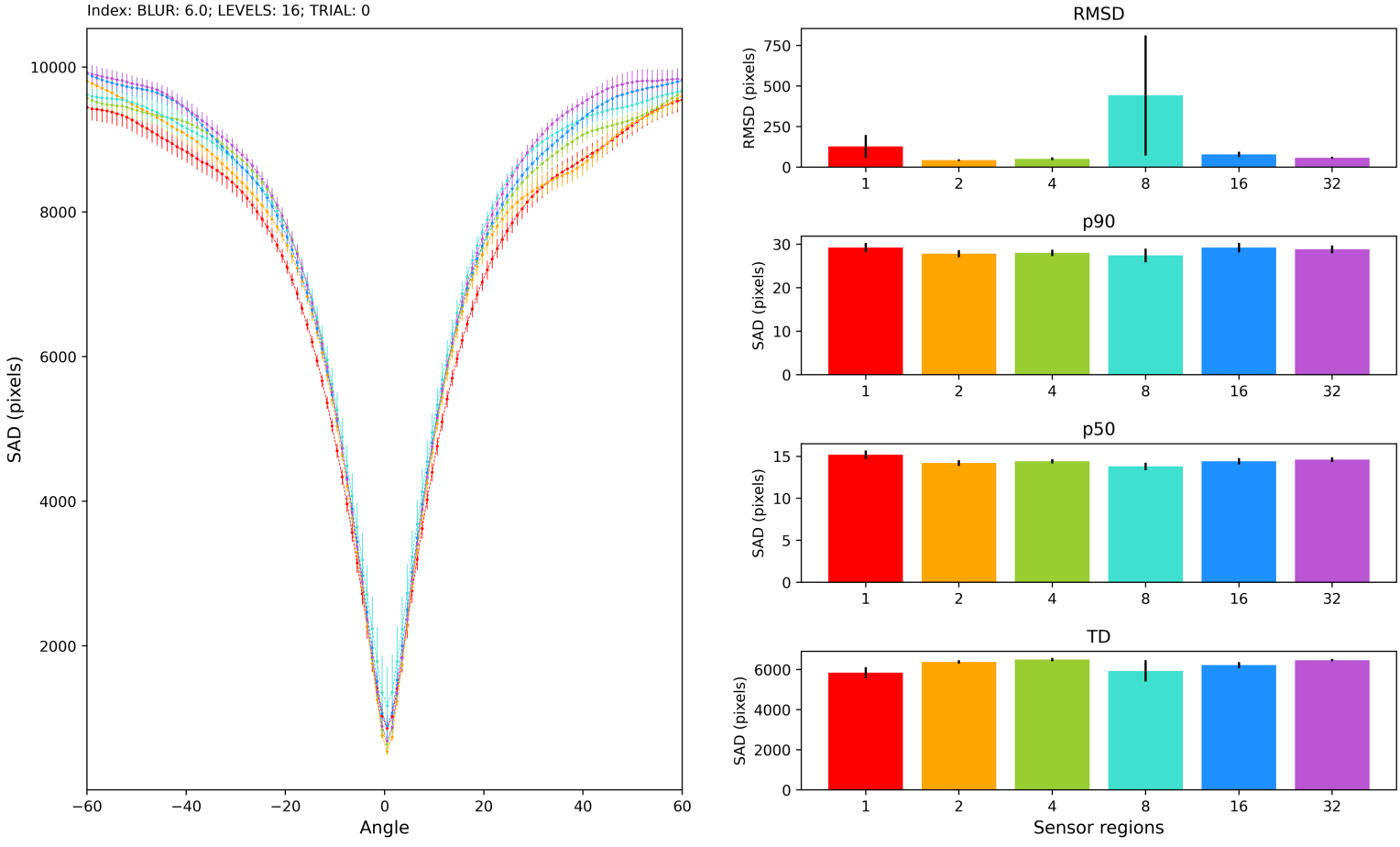
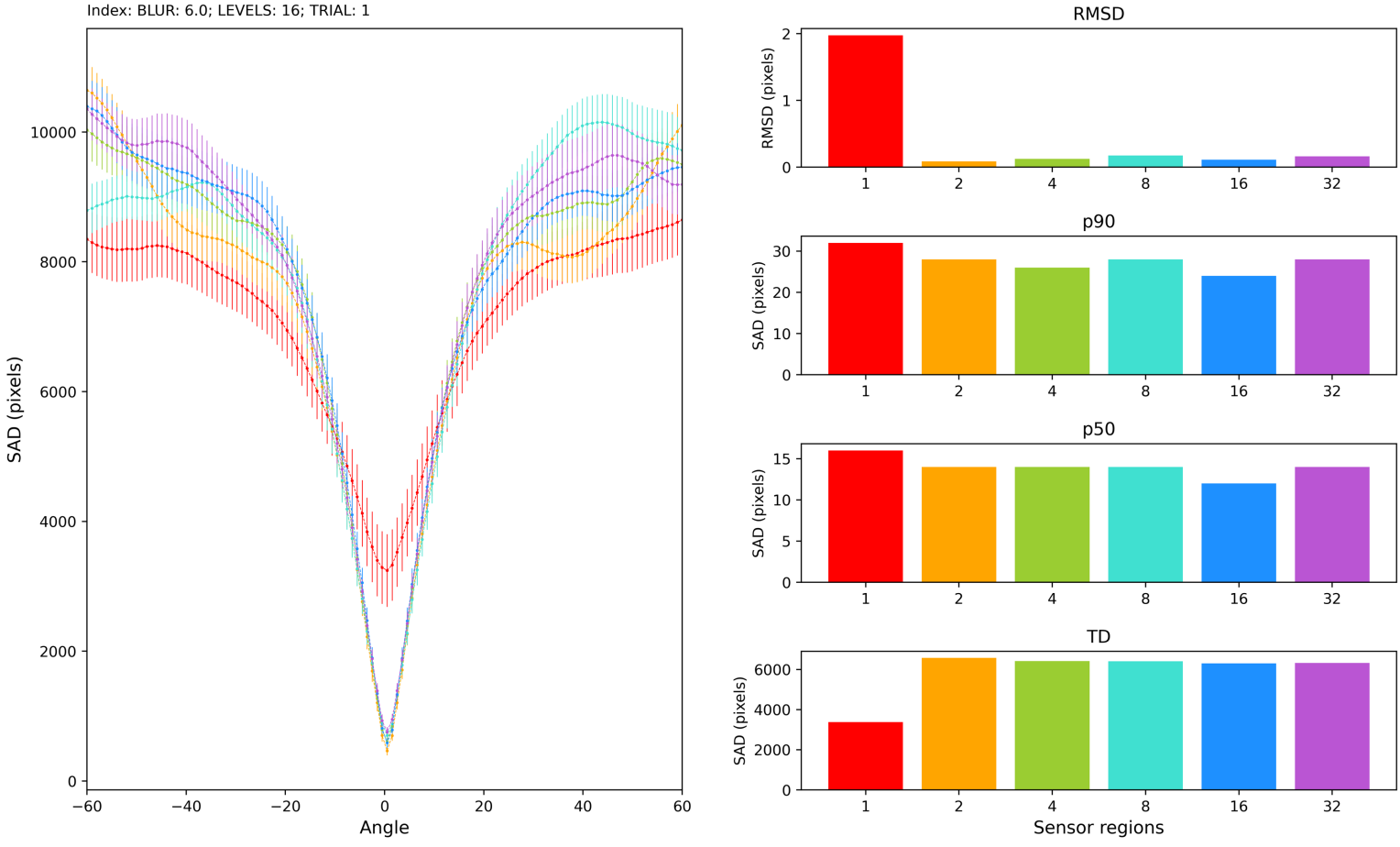
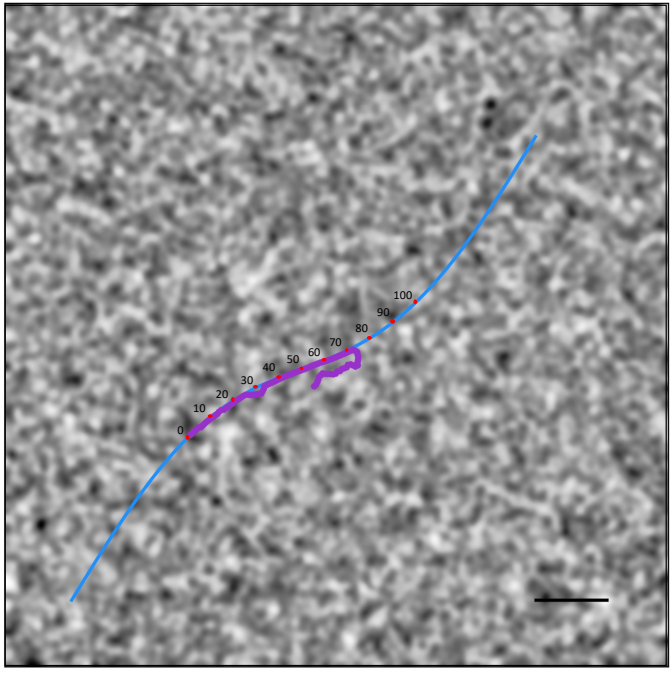
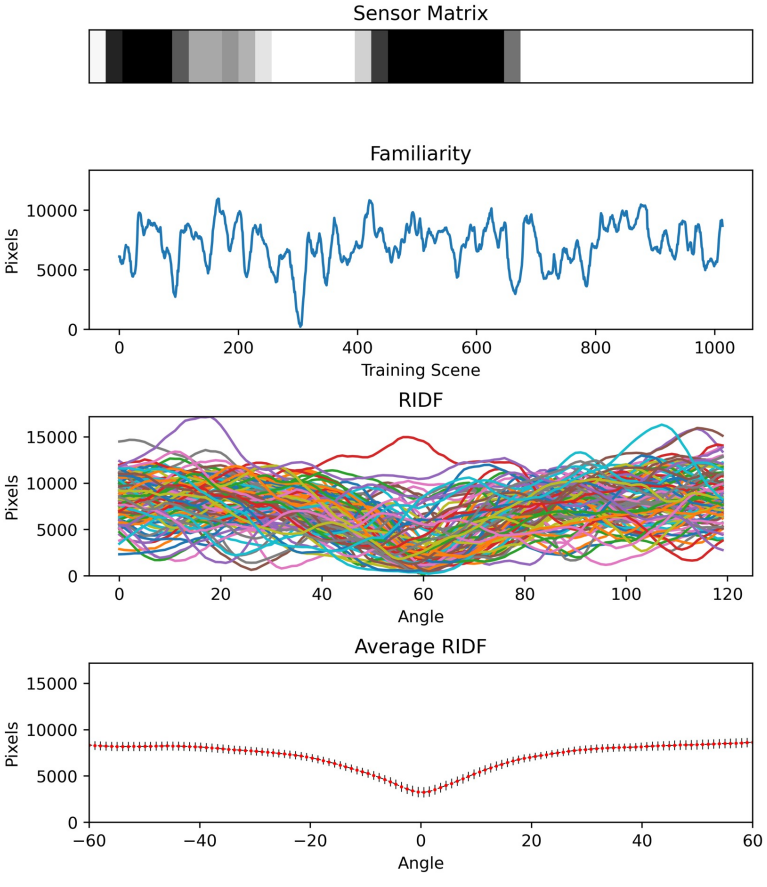

Index: BLUR: 6.0; LEVELS: 16; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 6.0; LEVELS: 16; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

60%

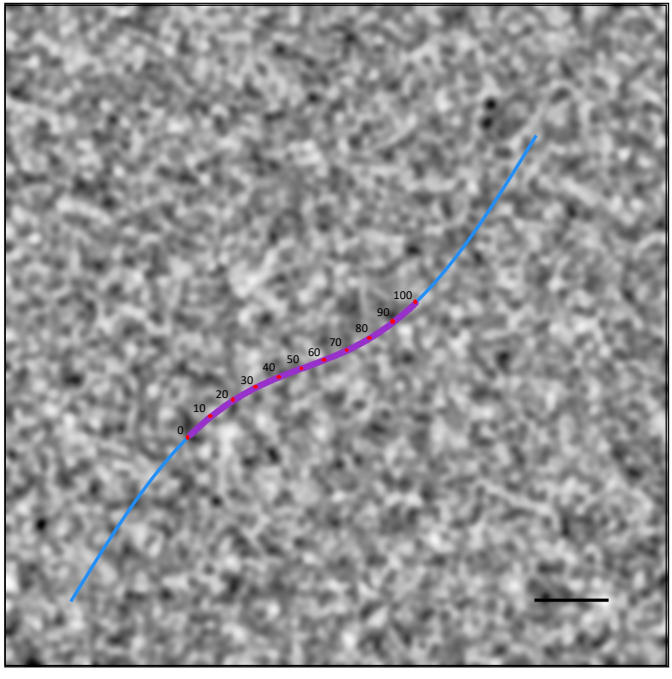


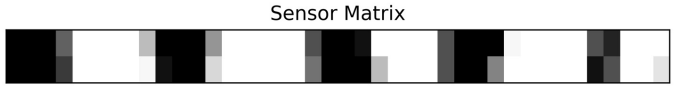



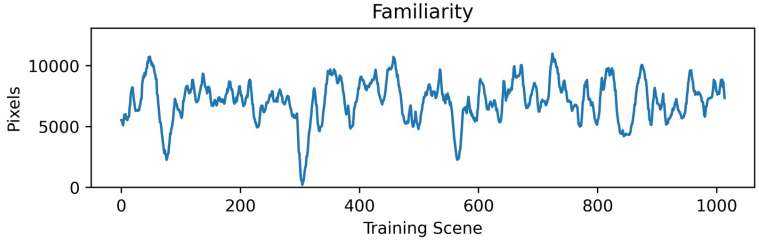

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

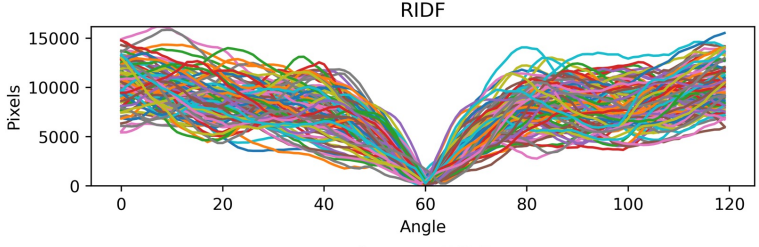
Navigation stats: RMSD error: 790.64; RMSD/dist: 1.977; TD: 3372; p90: 32; p50: 16; complete: 0

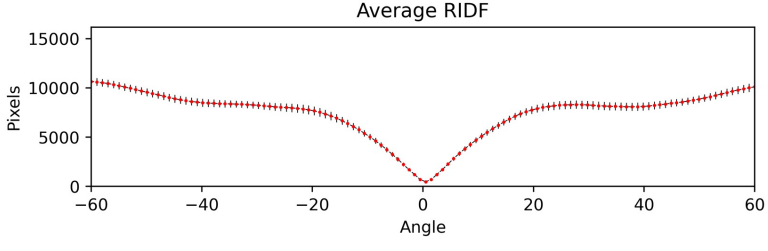
100%



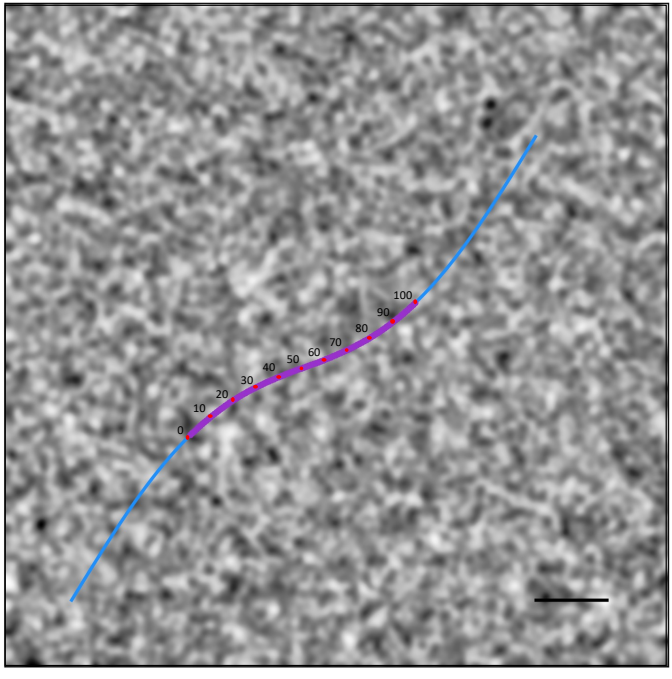



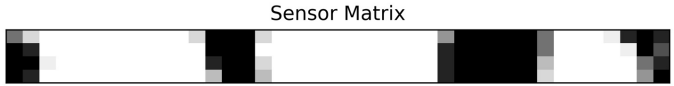



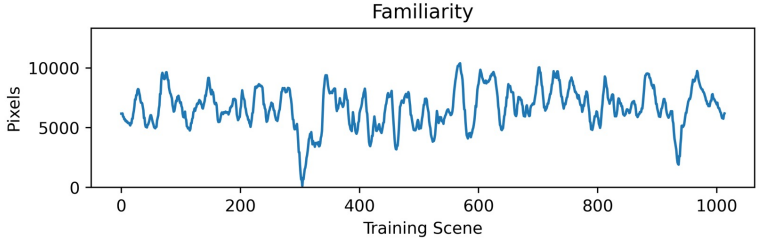

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

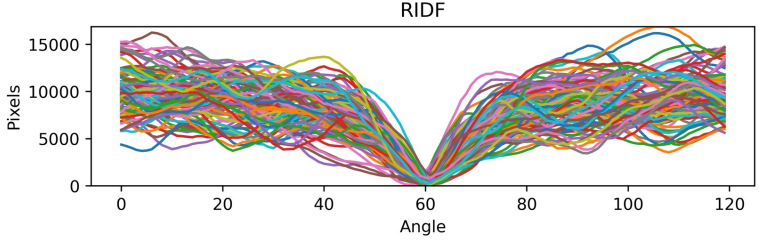
Navigation stats: RMSD error: 33.13; RMSD/dist: 0.083; TD: 6569; p90: 28; p50: 14; complete: 0

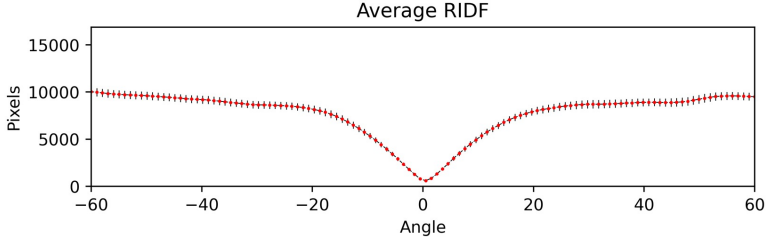
100%



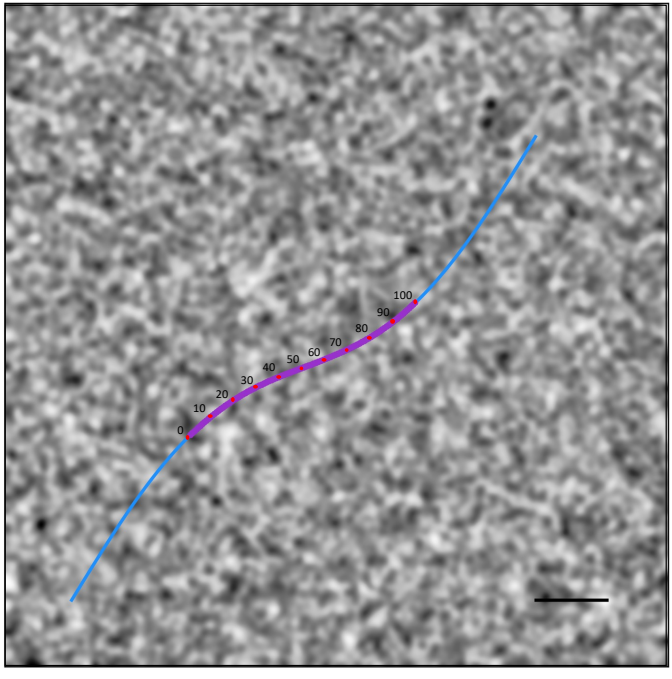



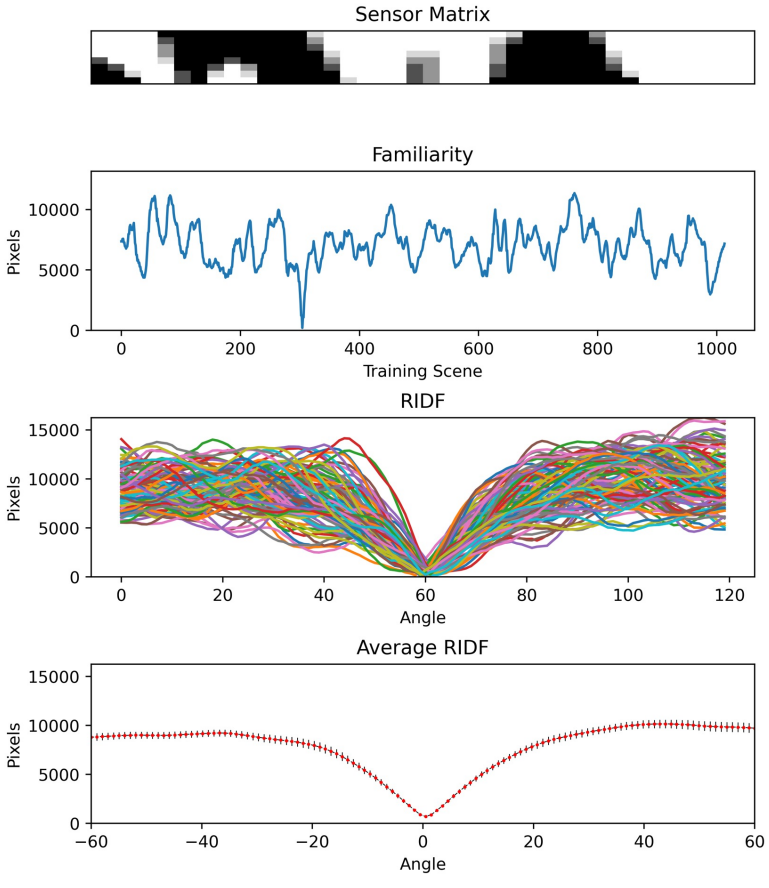




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 49.37; RMSD/dist: 0.123; TD: 6415; p90: 26; p50: 14; complete: 0

100%

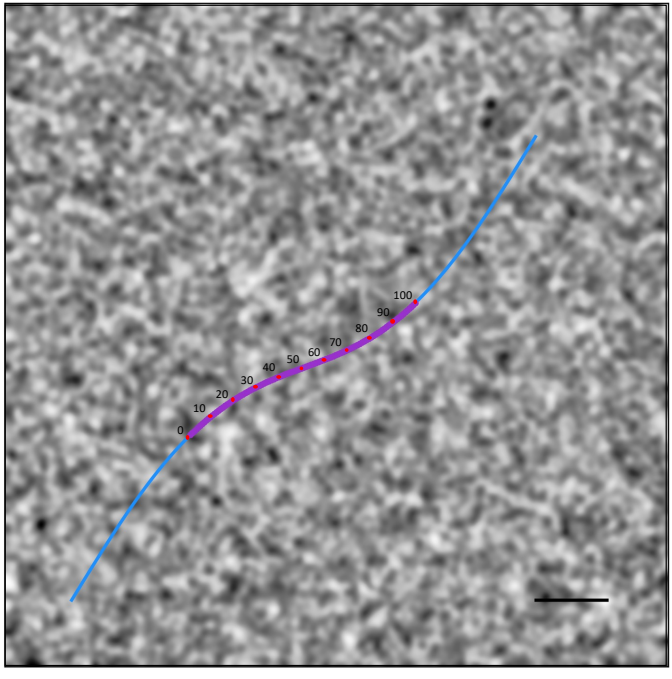


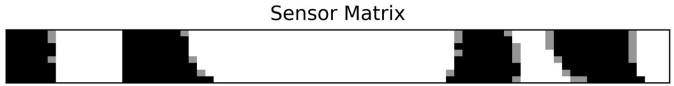



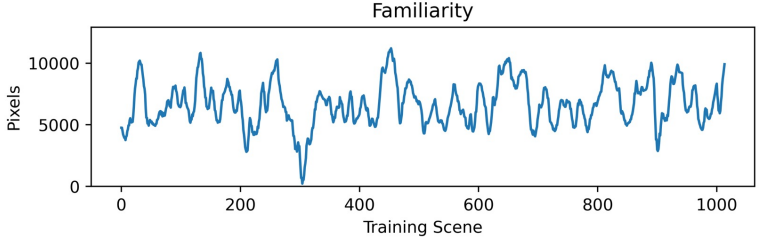

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

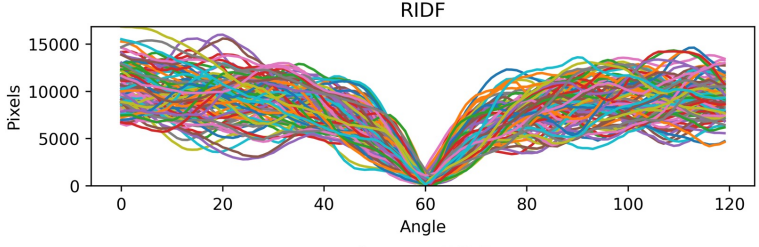
Navigation stats: RMSD error: 68.67; RMSD/dist: 0.172; TD: 6404; p90: 28; p50: 14; complete: 0

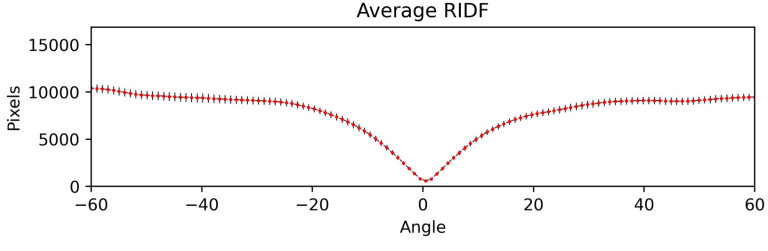
100%



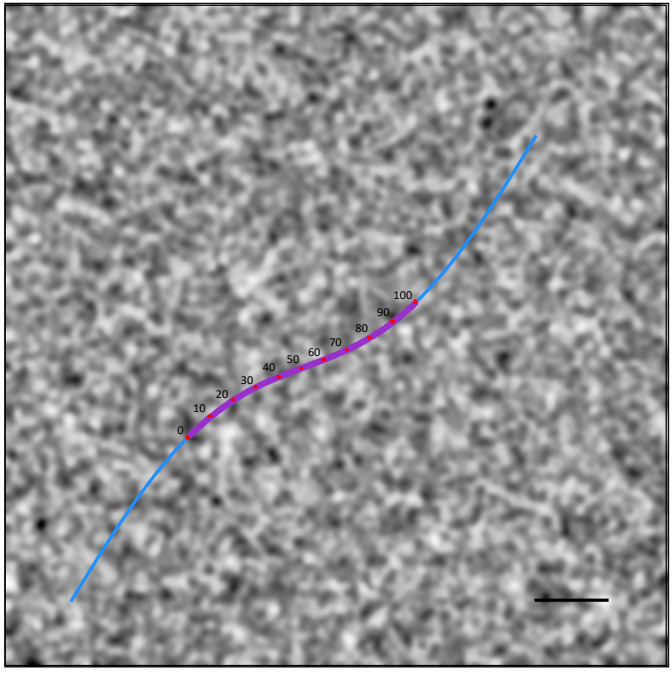



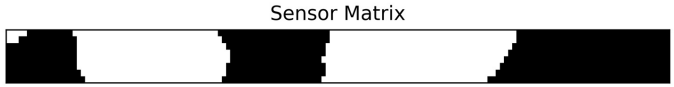



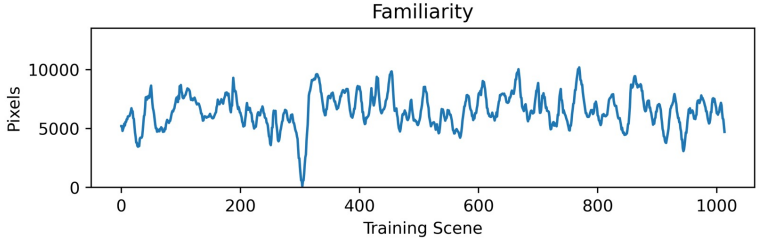

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

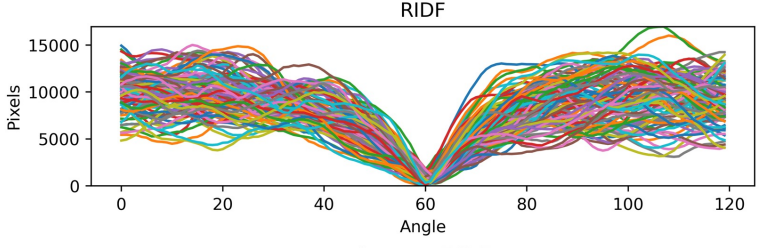
Navigation stats: RMSD error: 43.61; RMSD/dist: 0.109; TD: 6304; p90: 24; p50: 12; complete: 0

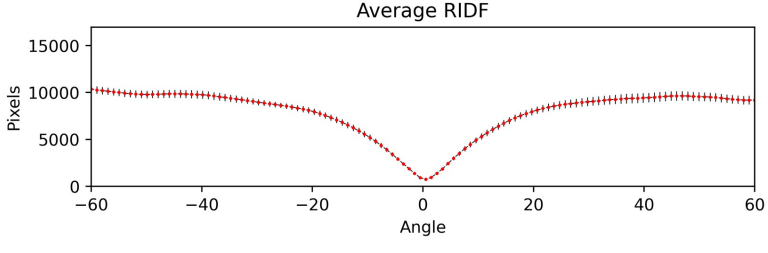
100%



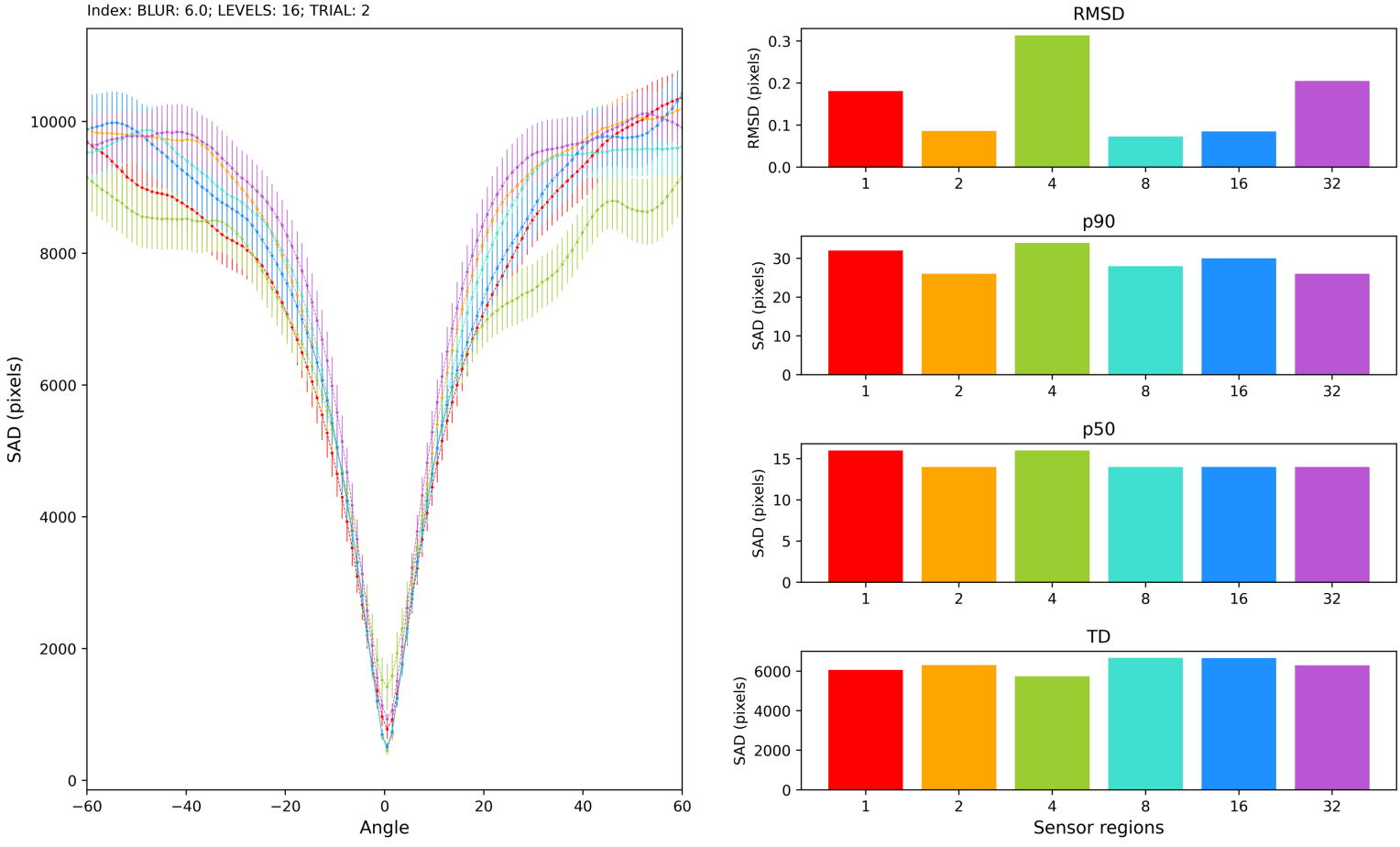



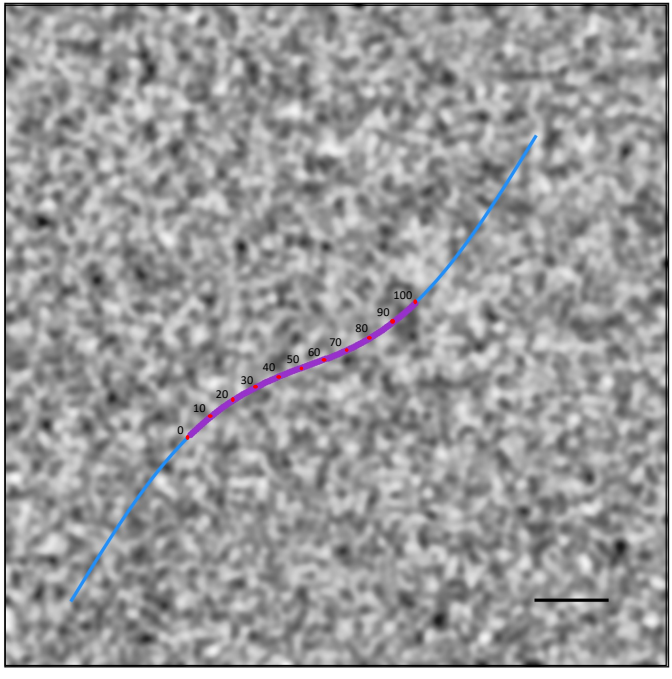



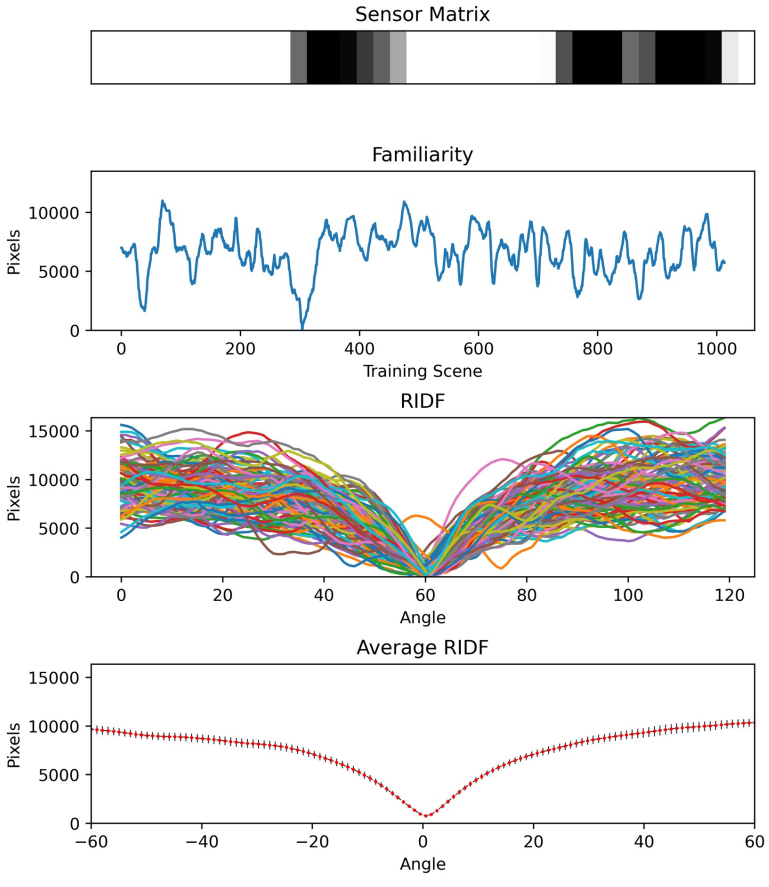

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 64.80; RMSD/dist: 0.162; TD: 6326; p90: 28; p50: 14; complete: 0


Index: BLUR: 6.0; LEVELS: 16; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

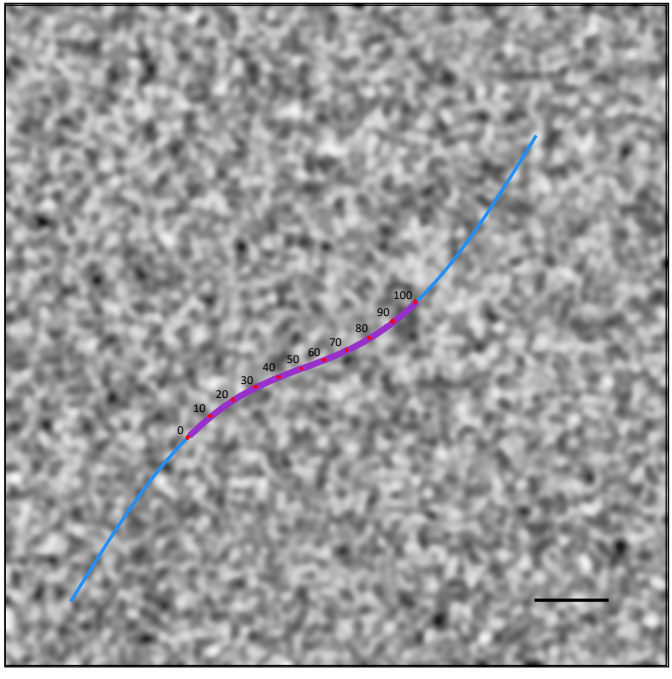


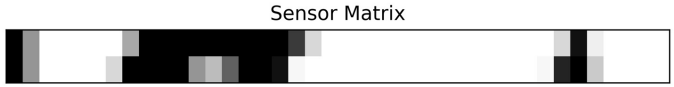



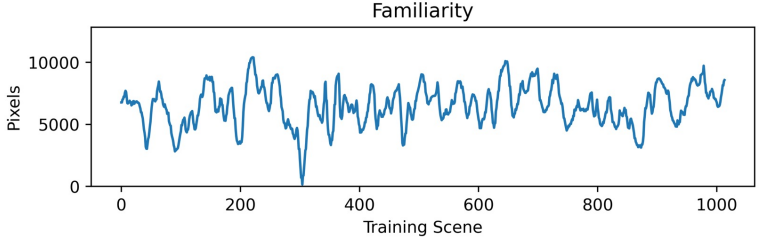

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

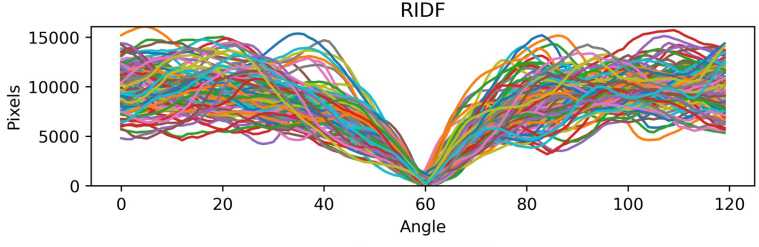
Navigation stats: RMSD error: 72.54; RMSD/dist: 0.181; TD: 6059; p90: 32; p50: 16; complete: 0

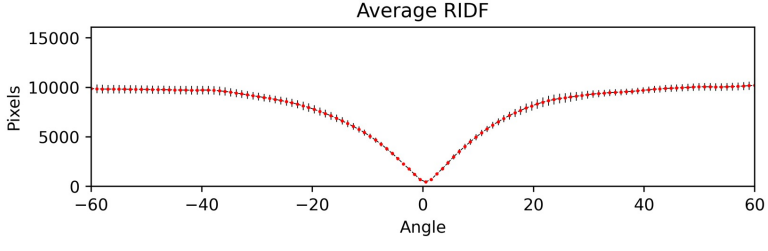
100%



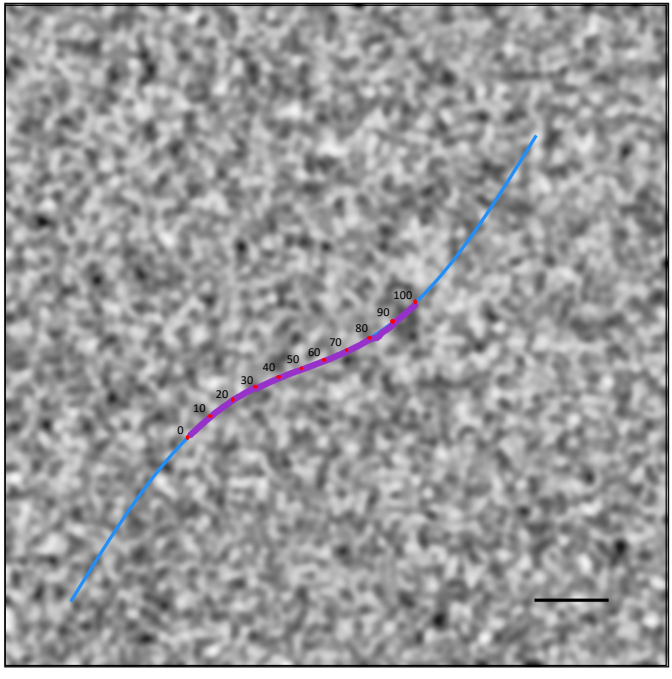



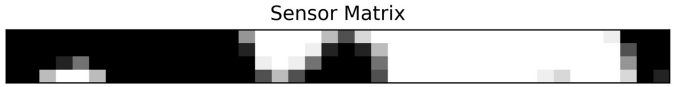



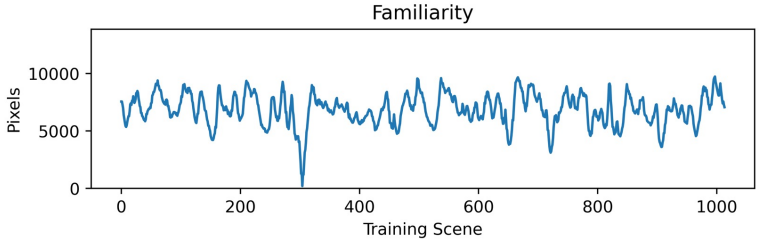

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

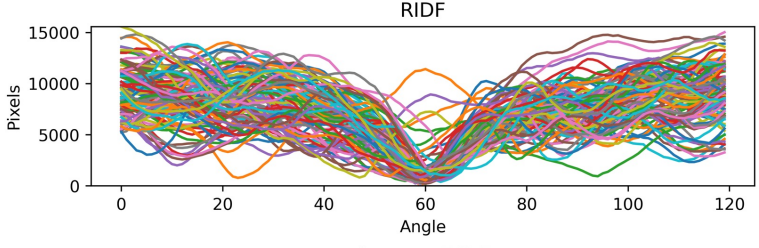
Navigation stats: RMSD error: 34.32; RMSD/dist: 0.086; TD: 6307; p90: 26; p50: 14; complete: 0

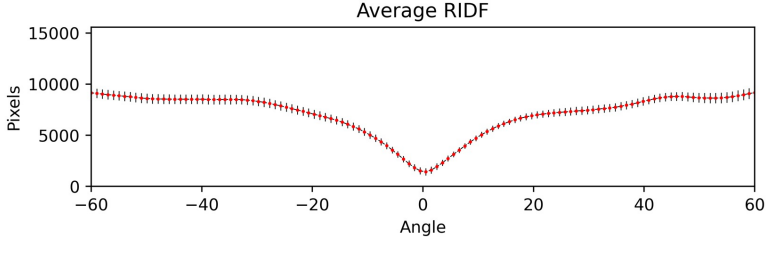
90%



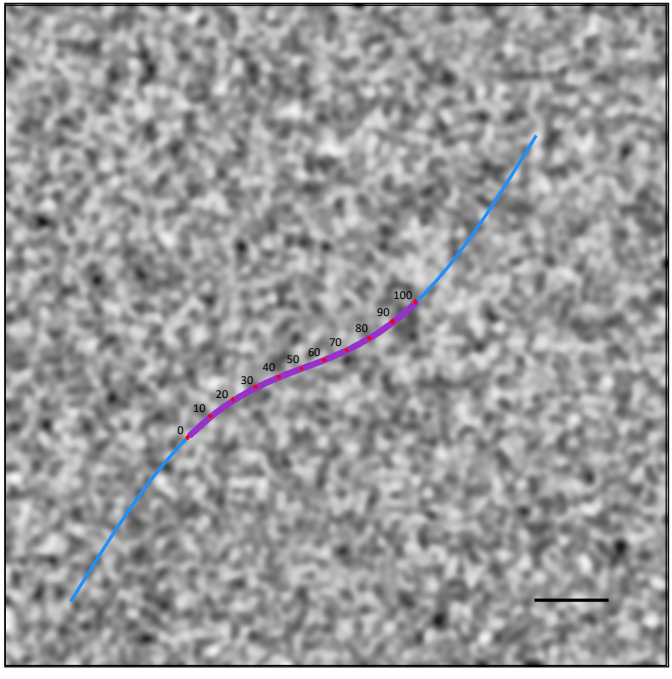



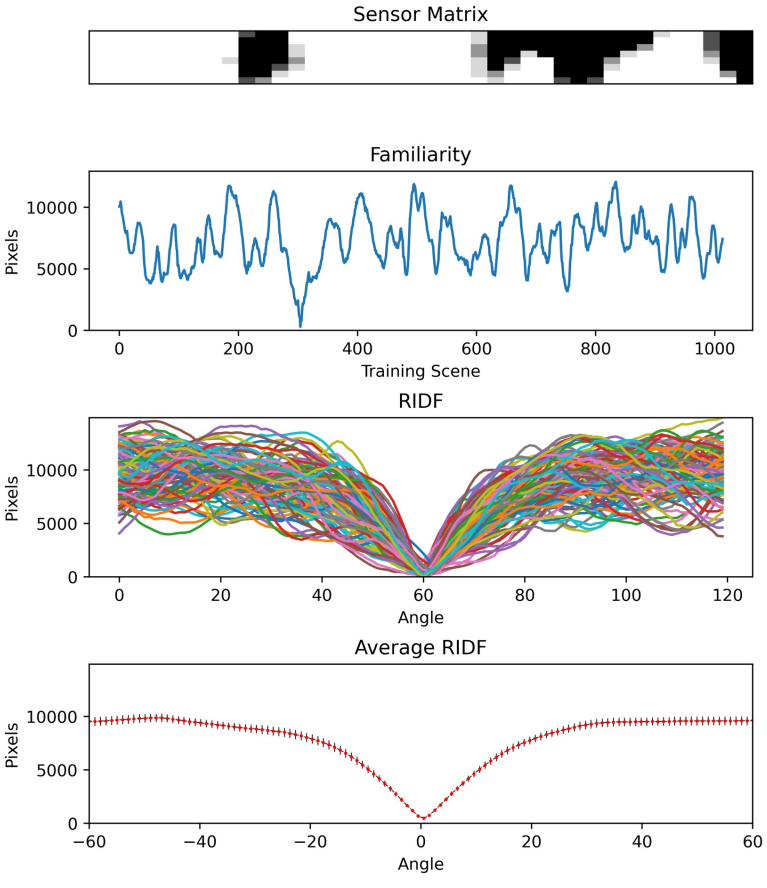




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 125.56; RMSD/dist: 0.314; TD: 5747; p90: 34; p50: 16; complete: 0

100%

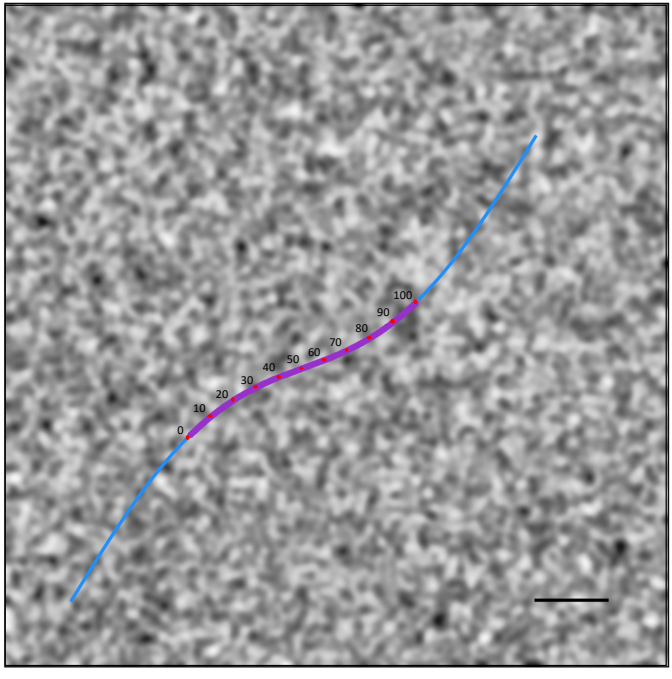


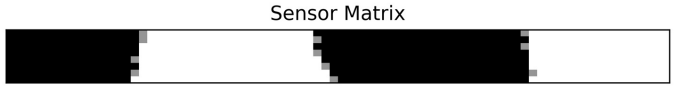



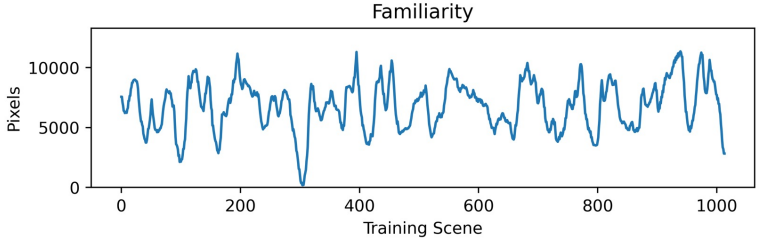

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

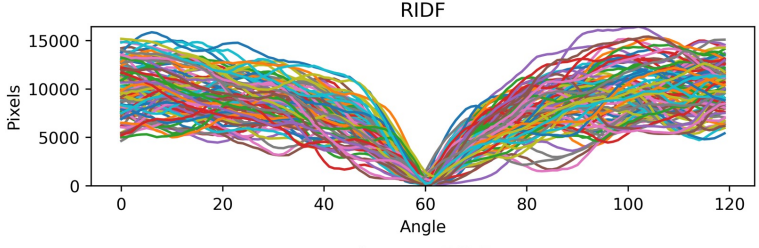
Navigation stats: RMSD error: 29.38; RMSD/dist: 0.073; TD: 6666; p90: 28; p50: 14; complete: 0

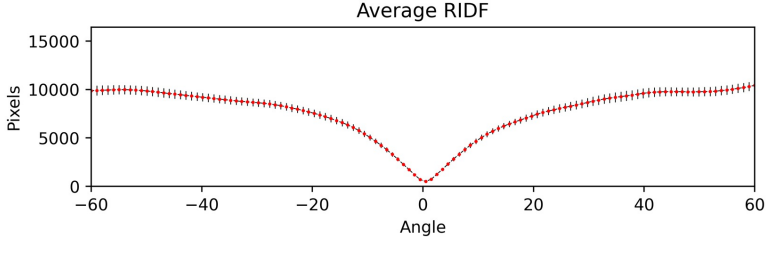
100%



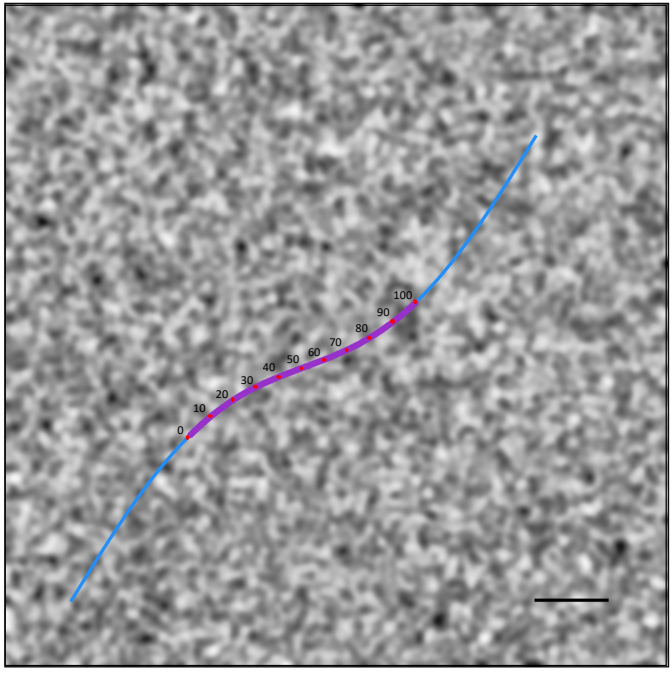



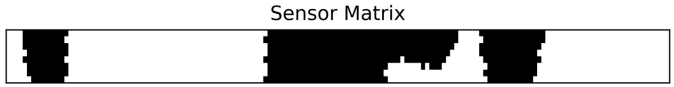



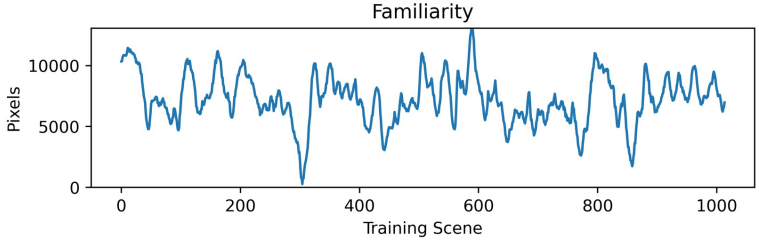

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

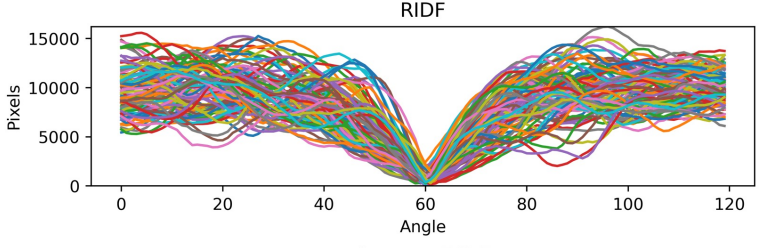
Navigation stats: RMSD error: 33.81; RMSD/dist: 0.085; TD: 6658; p90: 30; p50: 14; complete: 0

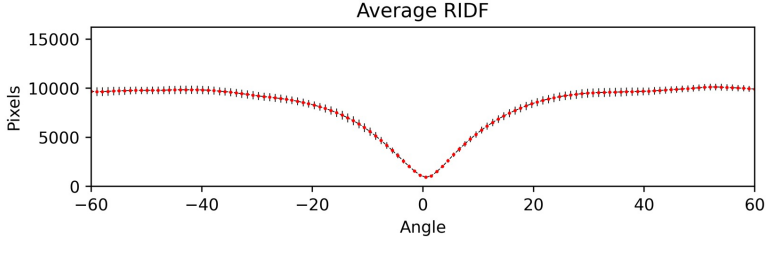
100%



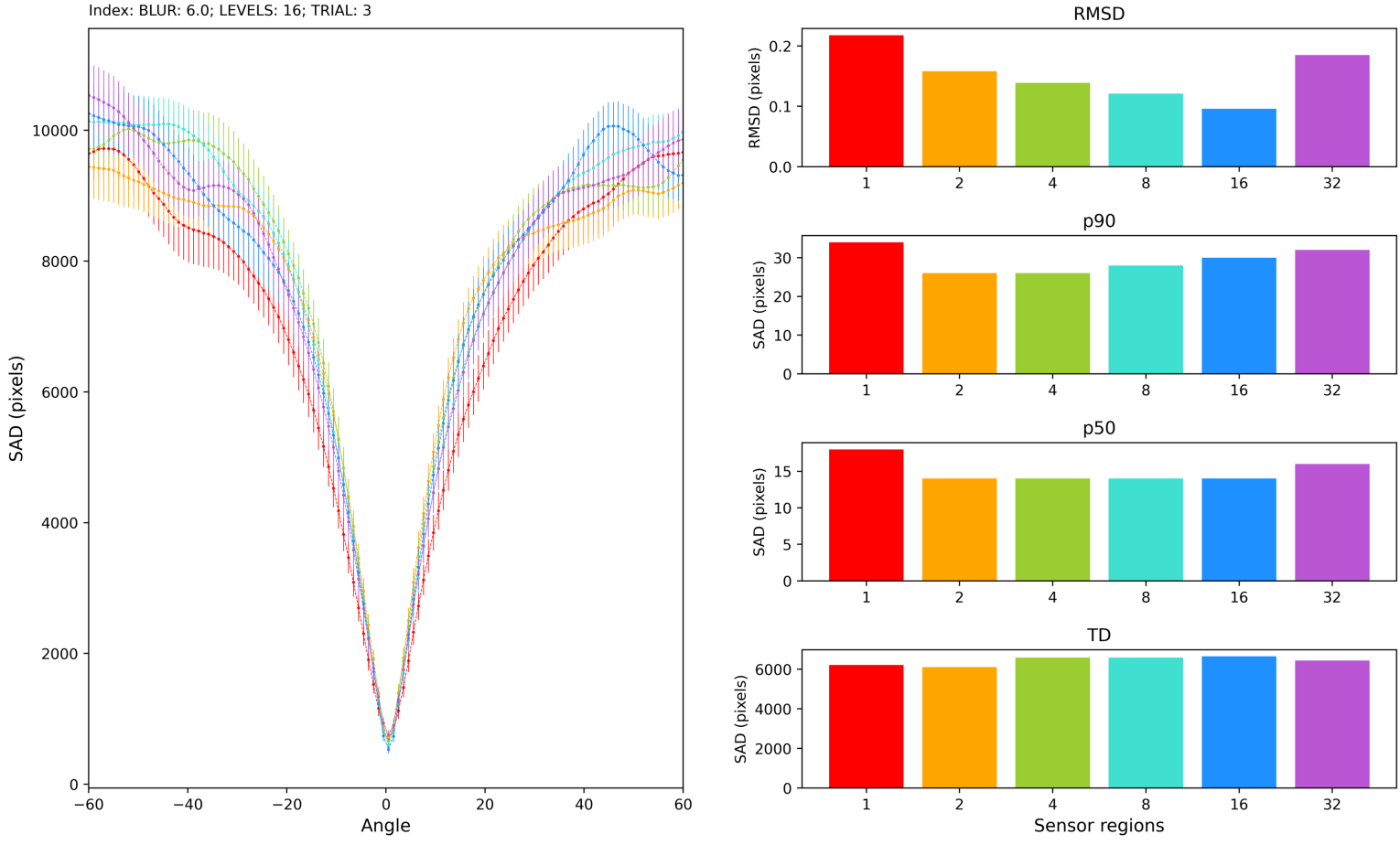



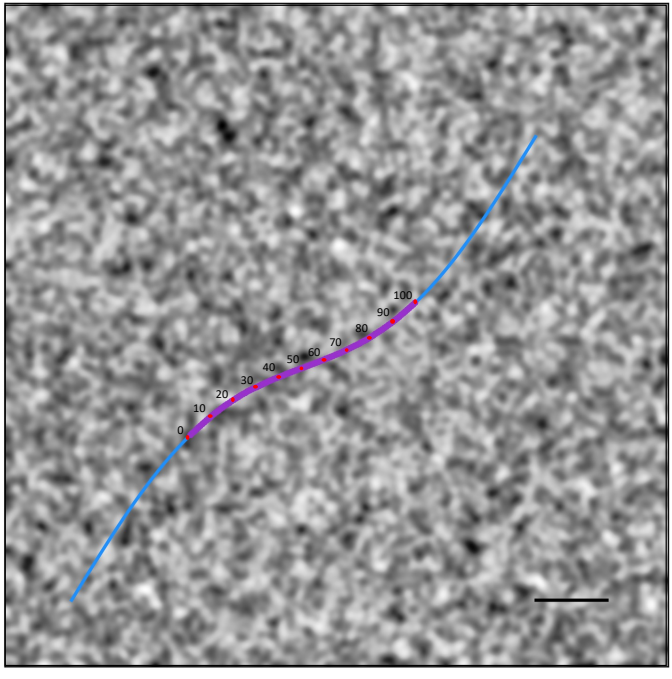



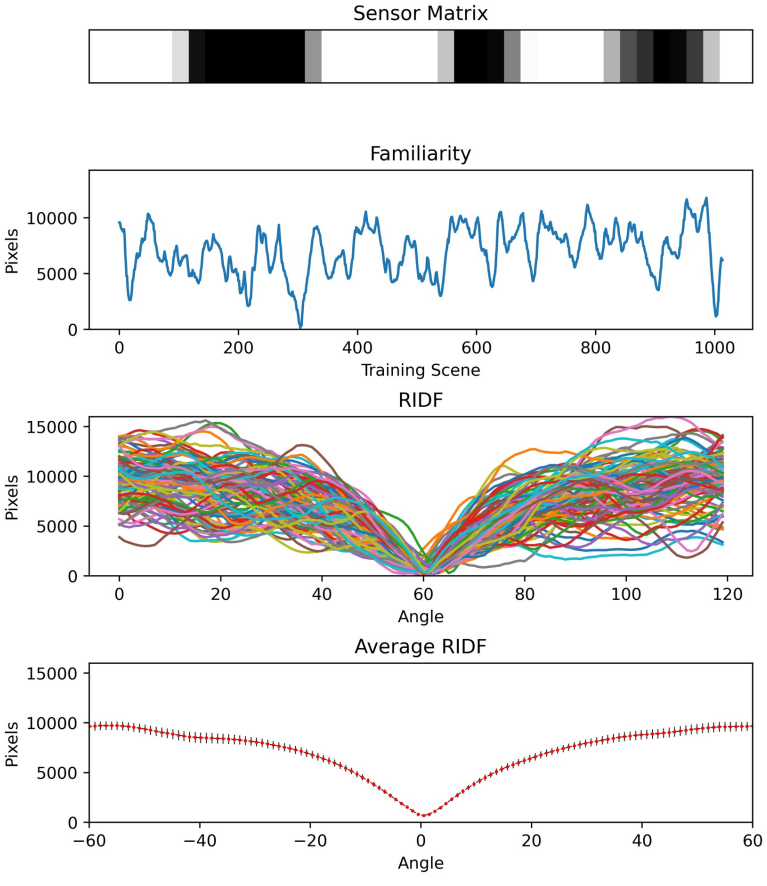

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 82.06; RMSD/dist: 0.205; TD: 6298; p90: 26; p50: 14; complete: 0


Index: BLUR: 6.0; LEVELS: 16; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

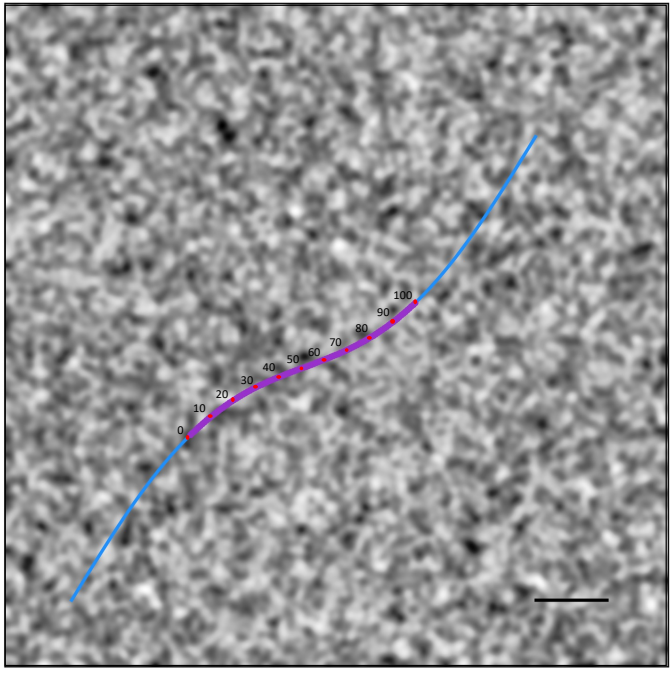


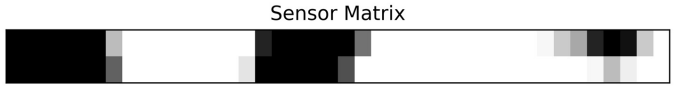



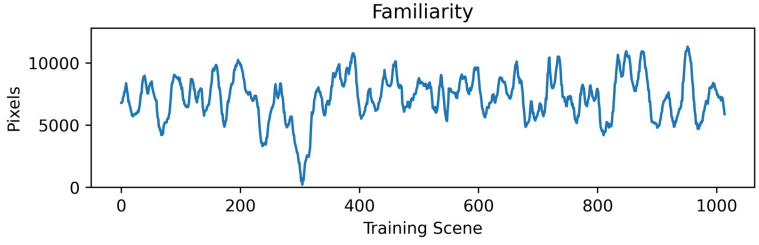

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

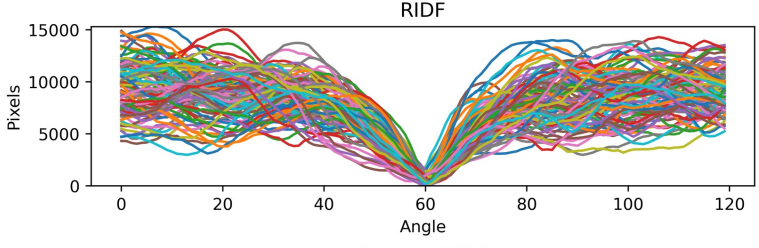
Navigation stats: RMSD error: 87.13; RMSD/dist: 0.218; TD: 6218; p90: 34; p50: 18; complete: 0

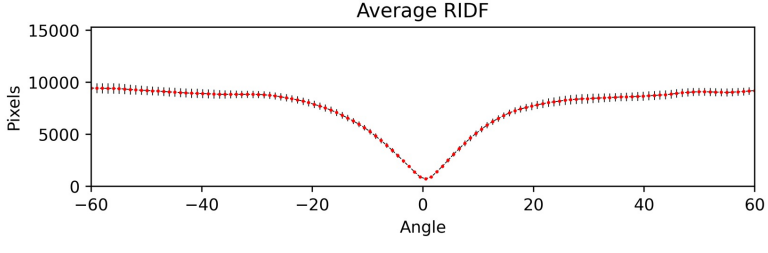
100%



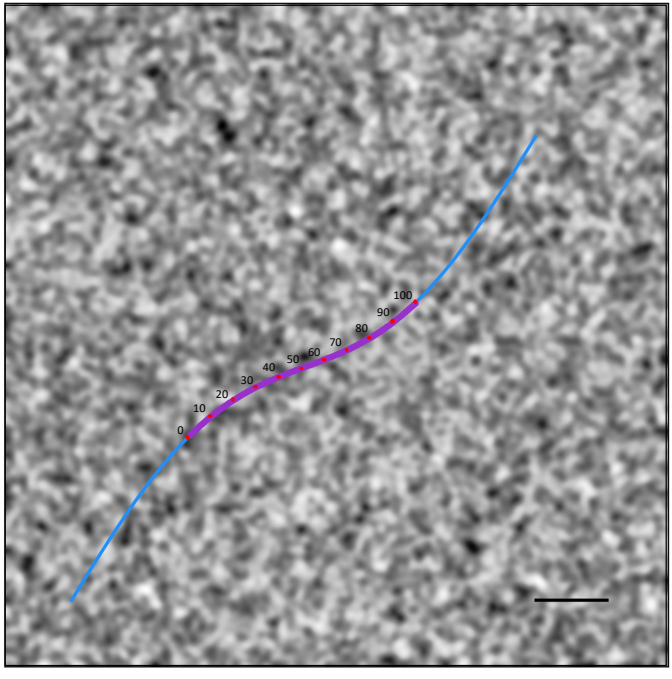



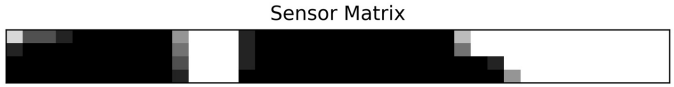



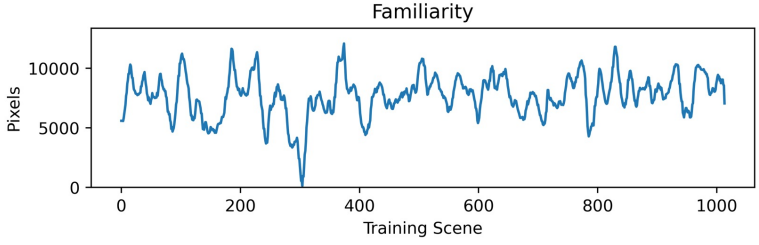

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

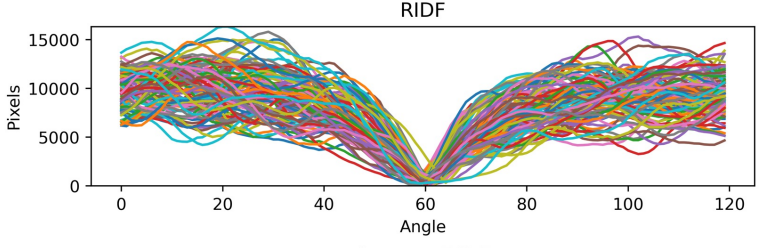
Navigation stats: RMSD error: 63.01; RMSD/dist: 0.158; TD: 6108; p90: 26; p50: 14; complete: 0

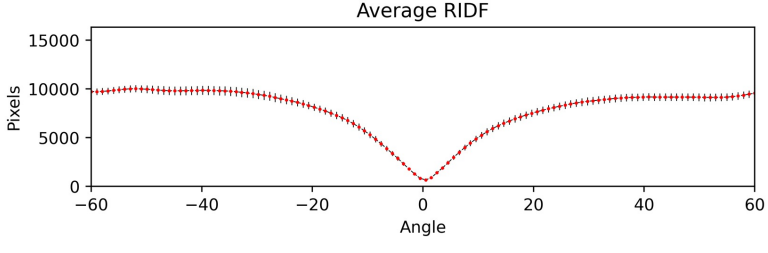
100%



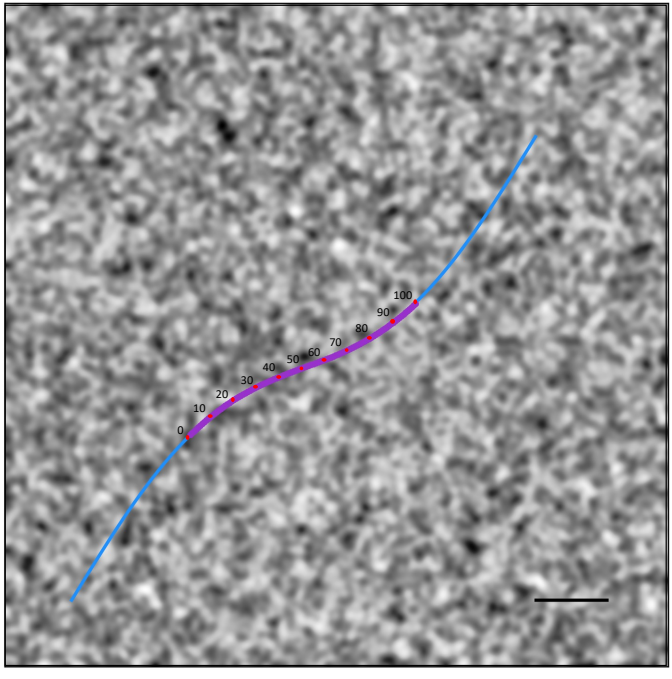



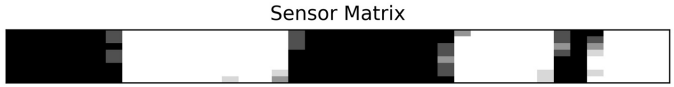



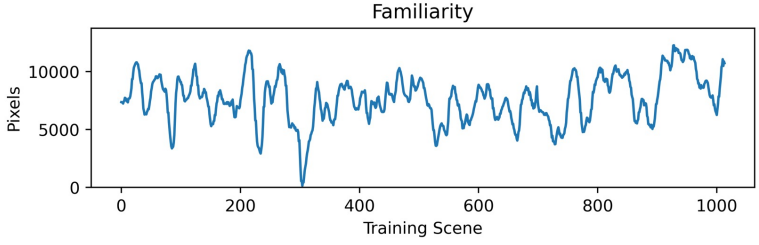

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

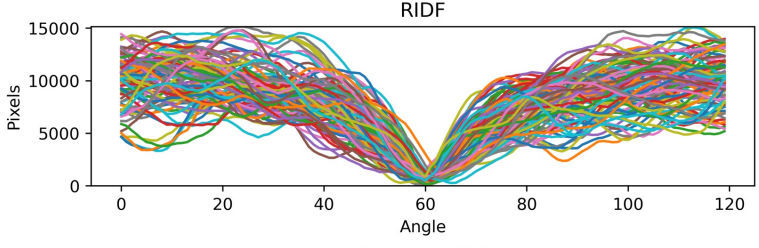
Navigation stats: RMSD error: 55.76; RMSD/dist: 0.139; TD: 6588; p90: 26; p50: 14; complete: 0

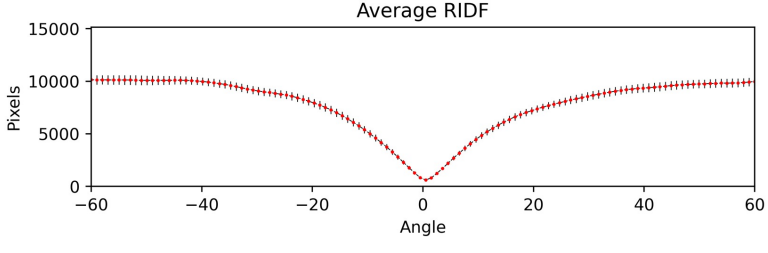
100%



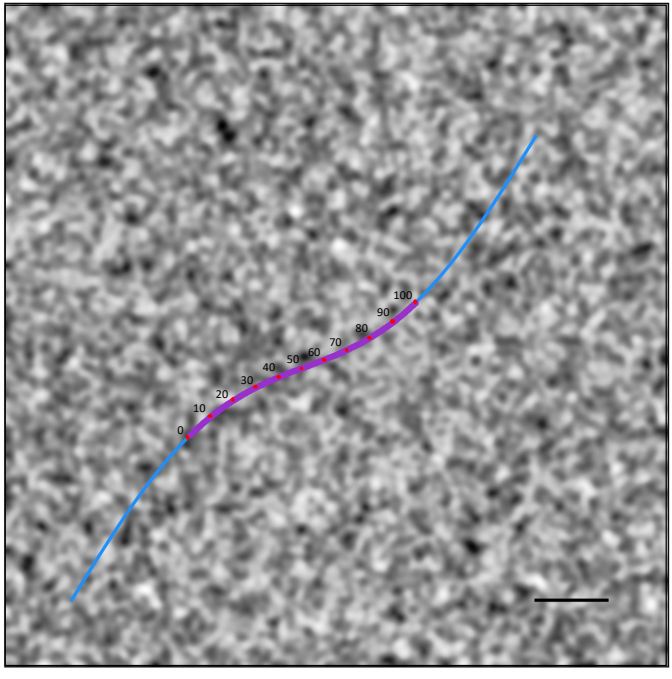



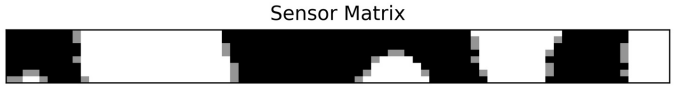



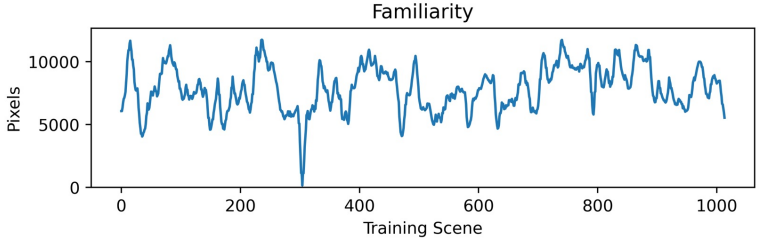

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

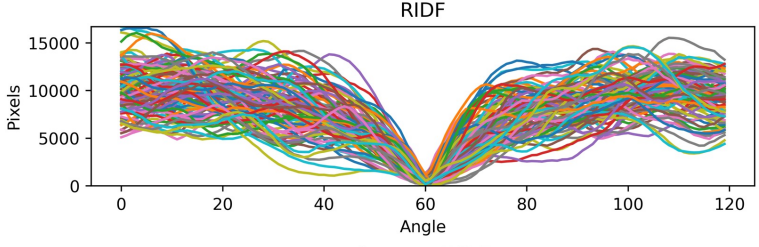
Navigation stats: RMSD error: 48.31; RMSD/dist: 0.121; TD: 6592; p90: 28; p50: 14; complete: 0

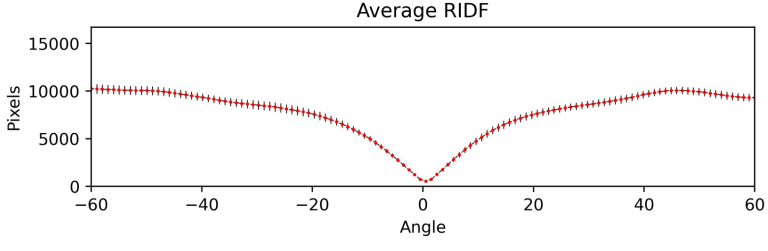
100%



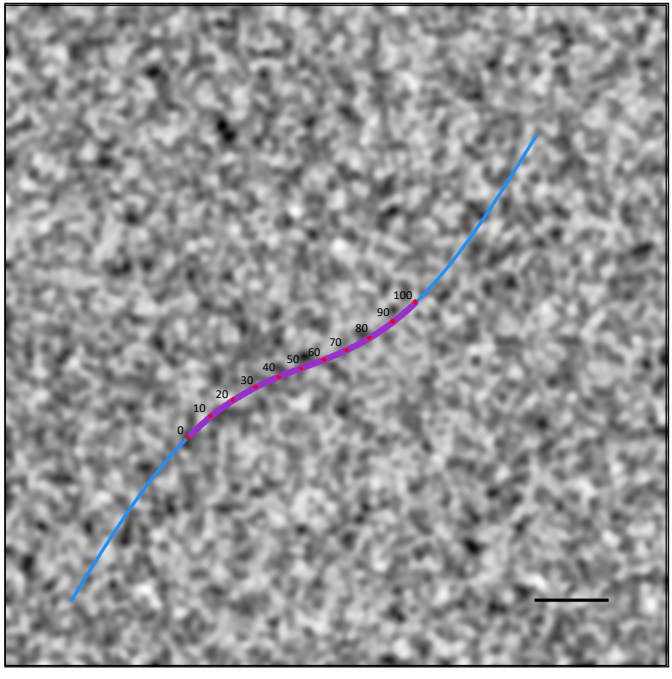



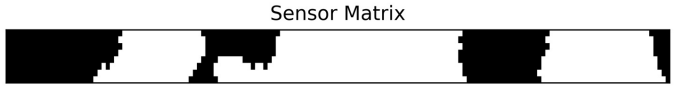



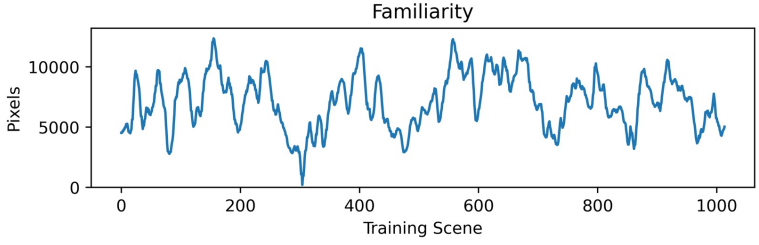

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

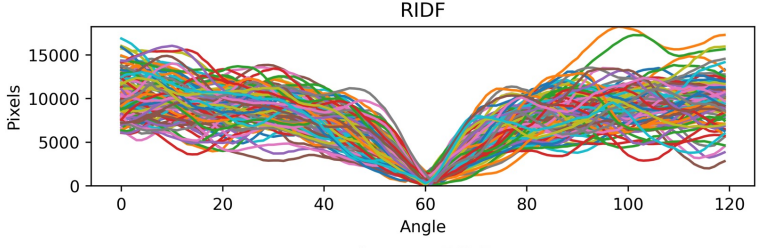
Navigation stats: RMSD error: 38.38; RMSD/dist: 0.096; TD: 6648; p90: 30; p50: 14; complete: 0

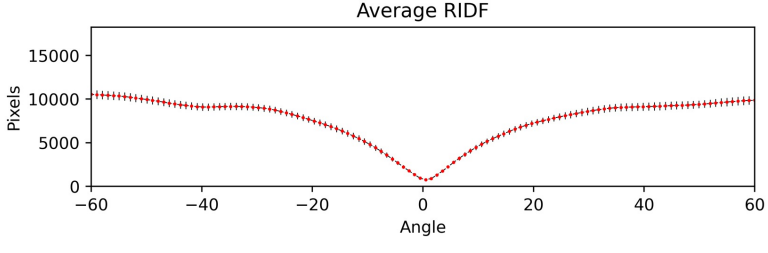
100%



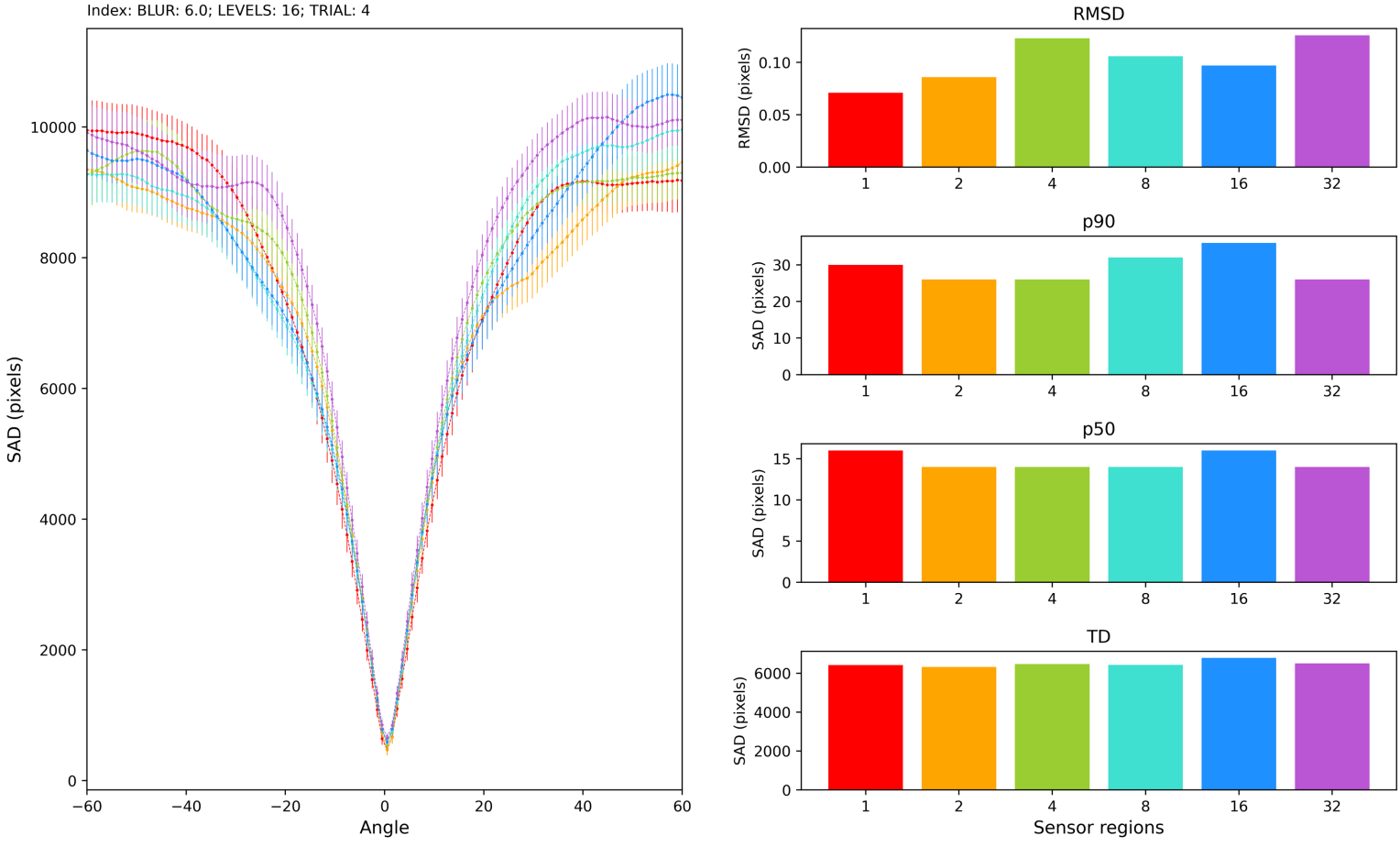



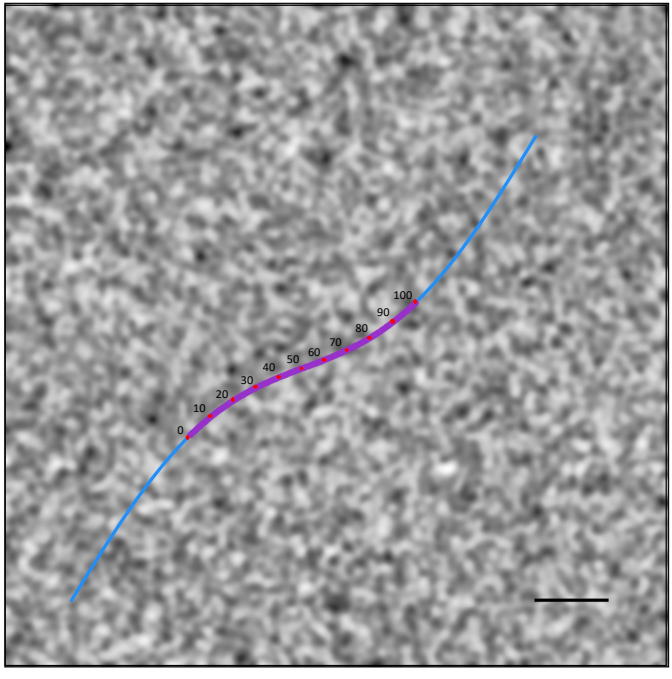



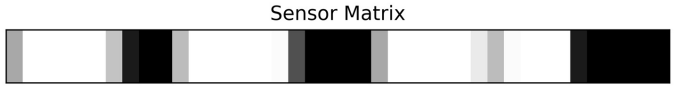

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

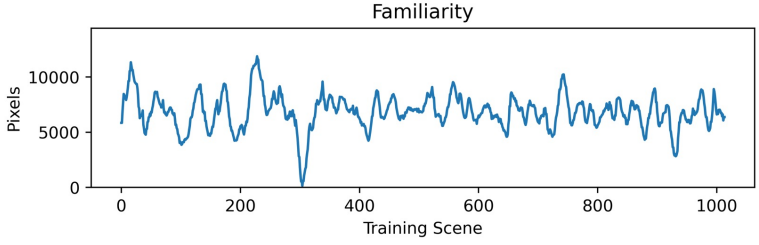
Navigation stats: RMSD error: 73.98; RMSD/dist: 0.185; TD: 6443; p90: 32; p50: 16; complete: 0

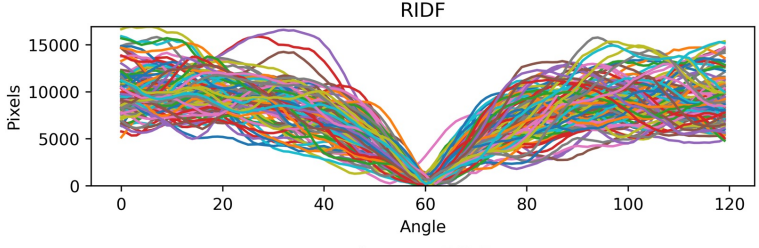

Index: BLUR: 6.0; LEVELS: 16; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

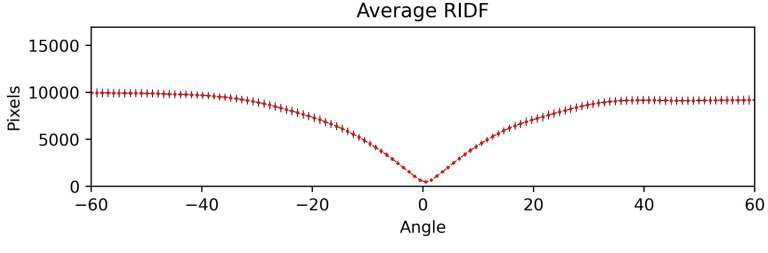
100%



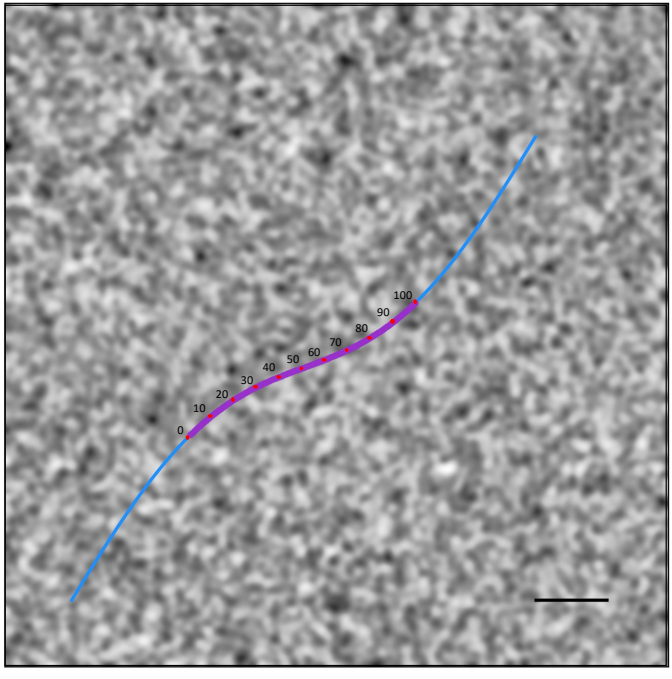



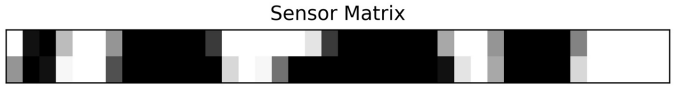



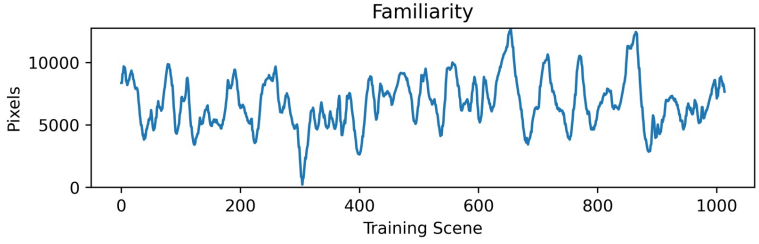

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

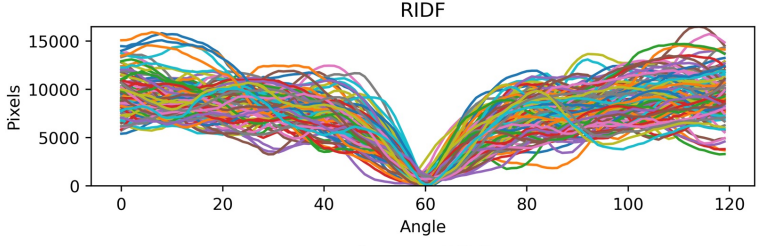
Navigation stats: RMSD error: 28.37; RMSD/dist: 0.071; TD: 6423; p90: 30; p50: 16; complete: 0

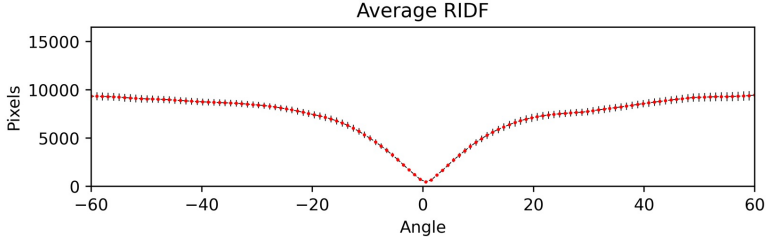
100%



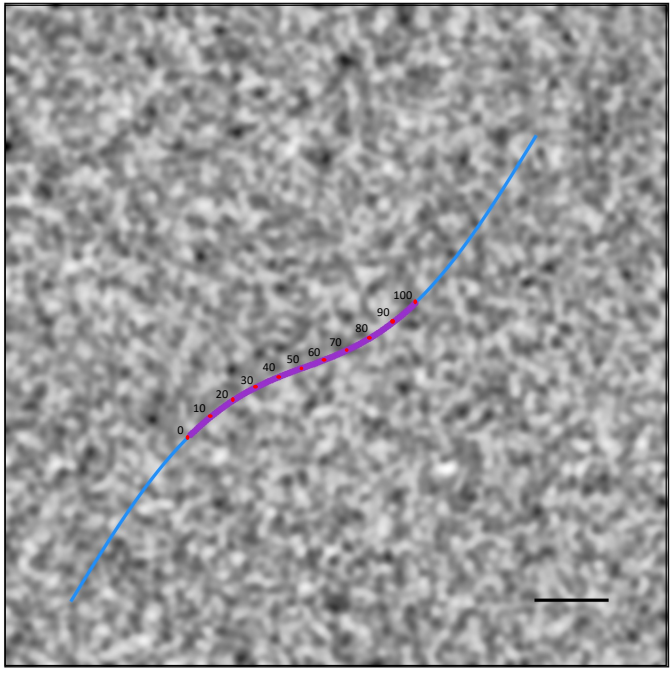



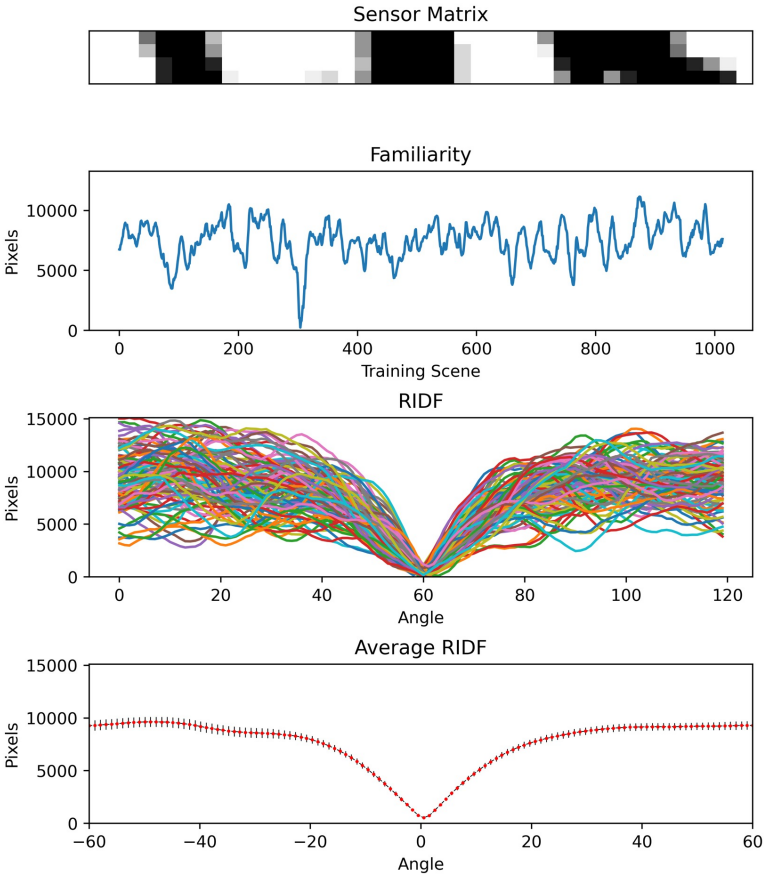




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 34.37; RMSD/dist: 0.086; TD: 6322; p90: 26; p50: 14; complete: 0

100%

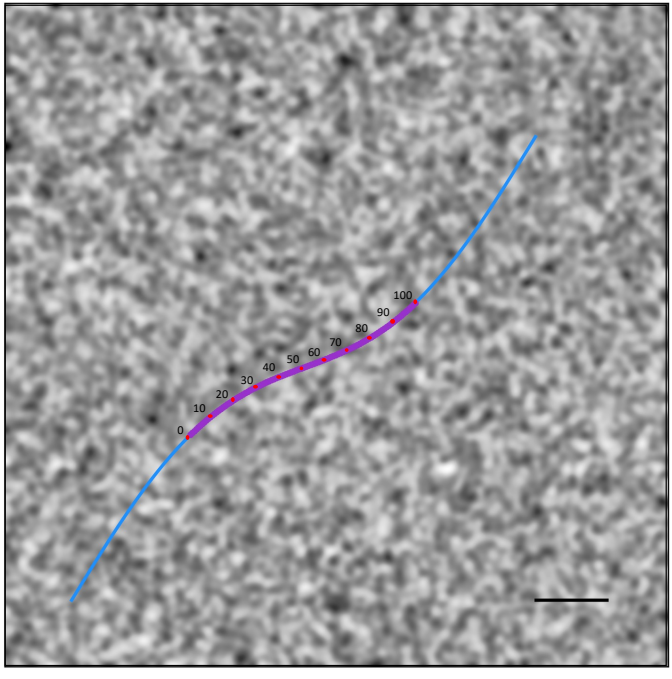


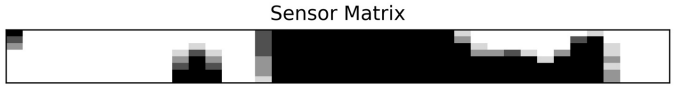



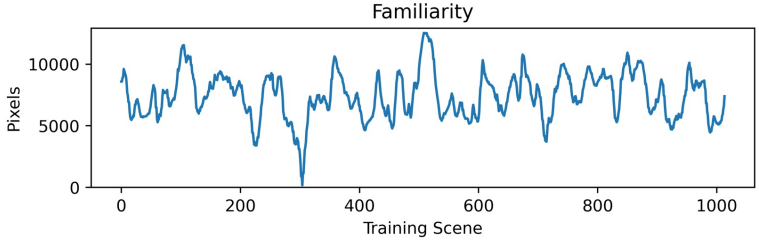

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

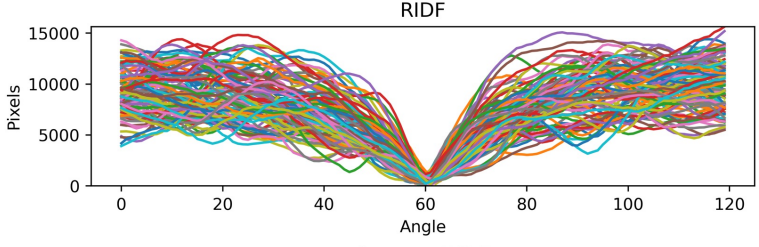
Navigation stats: RMSD error: 49.10; RMSD/dist: 0.123; TD: 6478; p90: 26; p50: 14; complete: 0

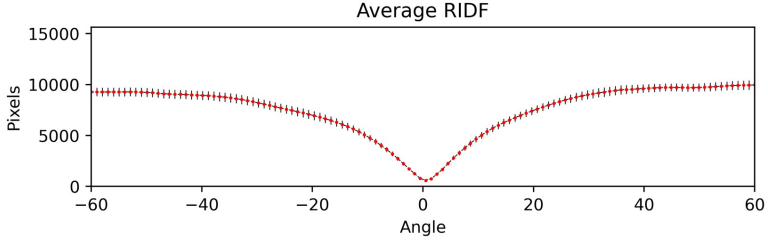
100%



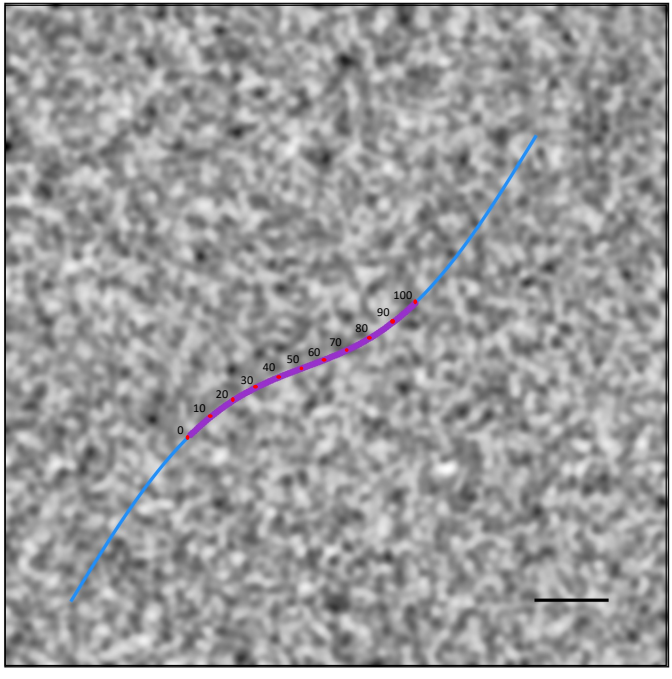



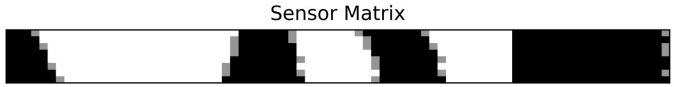



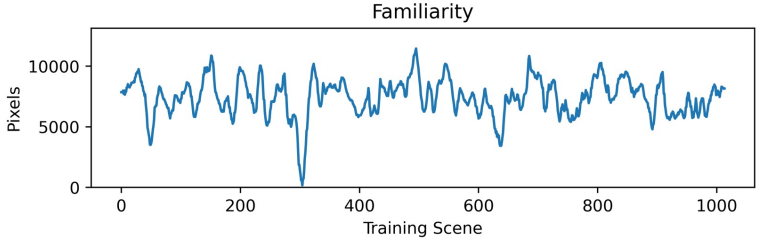

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

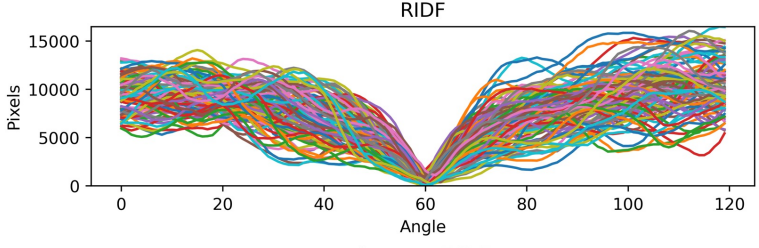
Navigation stats: RMSD error: 42.59; RMSD/dist: 0.106; TD: 6425; p90: 32; p50: 14; complete: 0

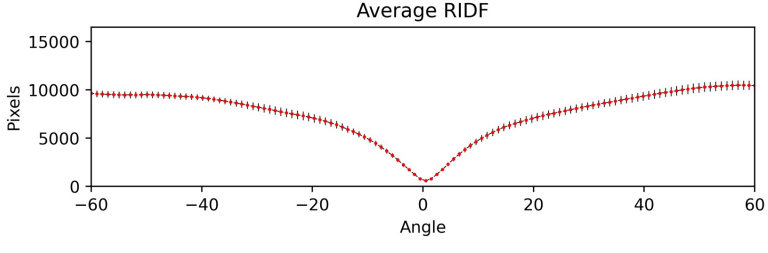
100%



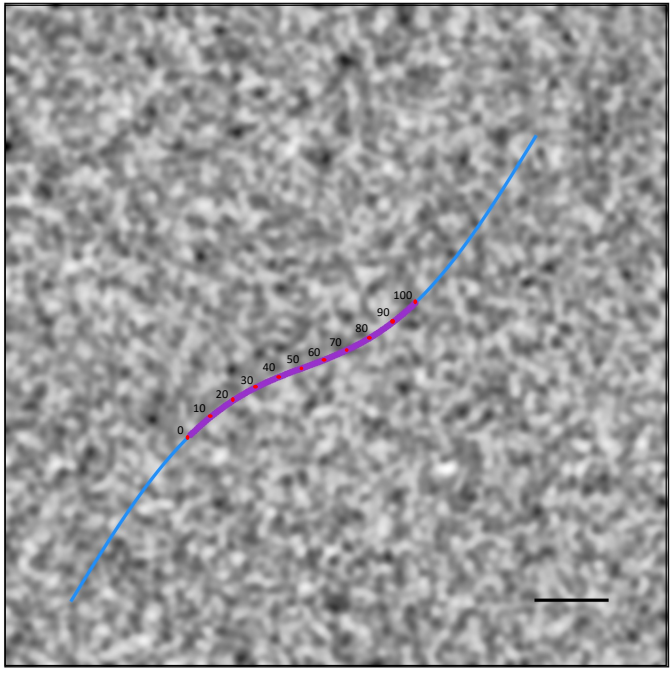



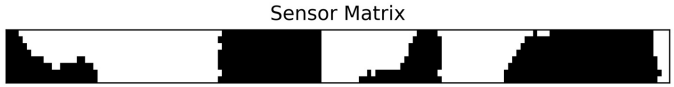



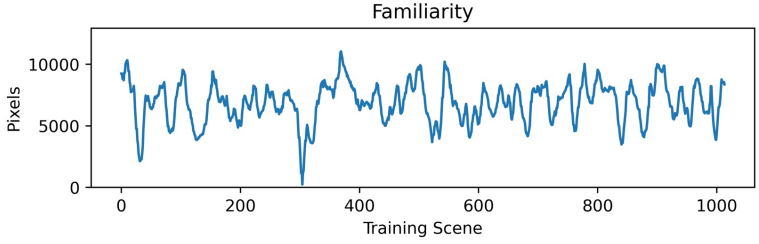

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

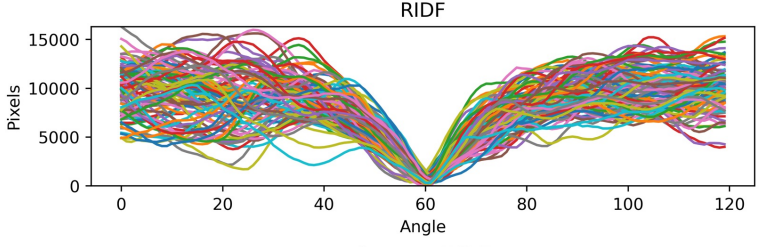
Navigation stats: RMSD error: 38.99; RMSD/dist: 0.097; TD: 6783; p90: 36; p50: 16; complete: 0

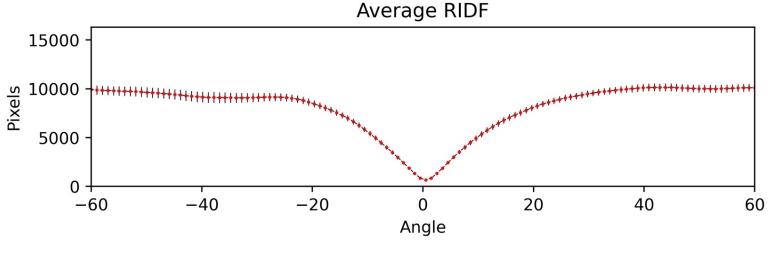
100%



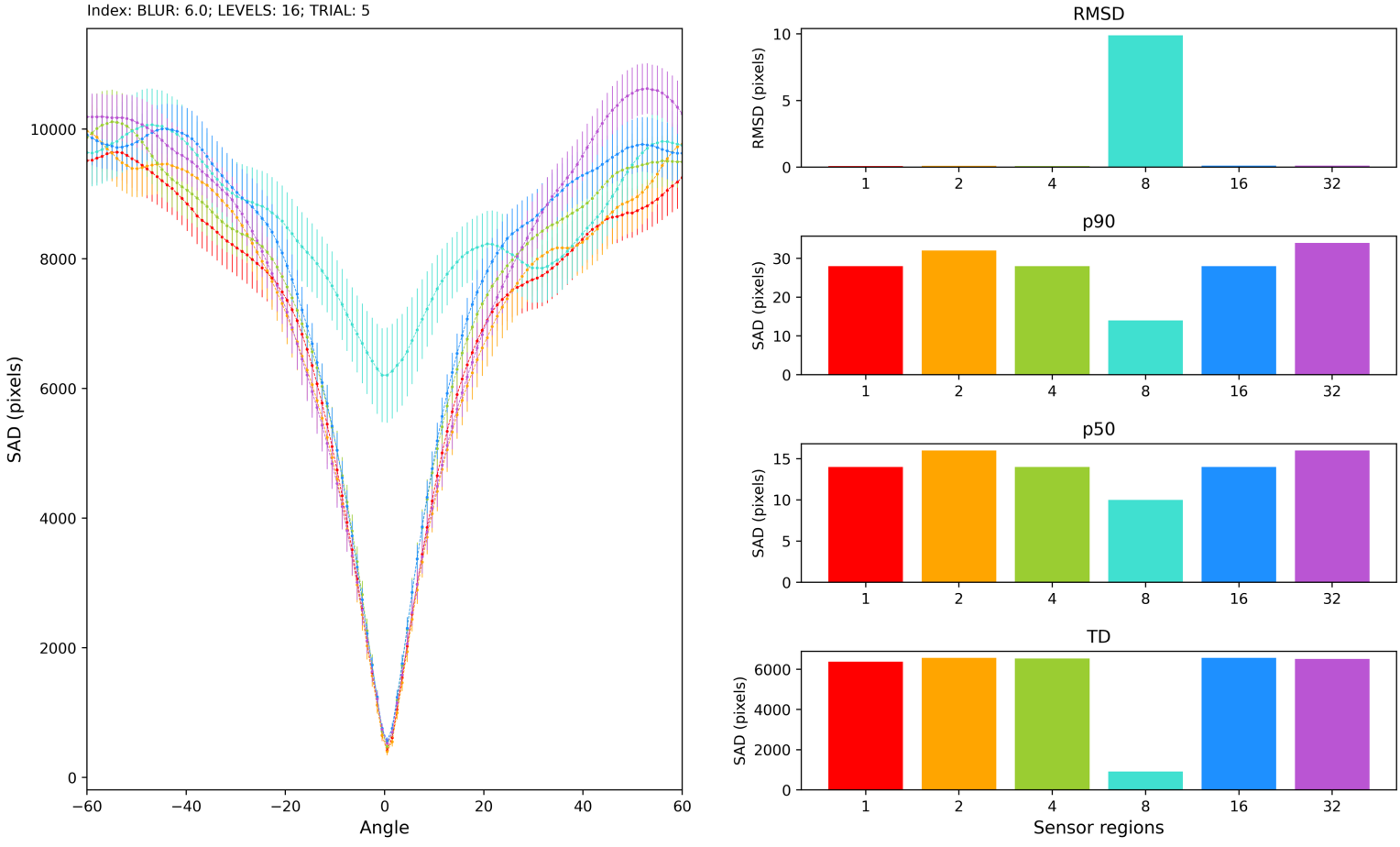



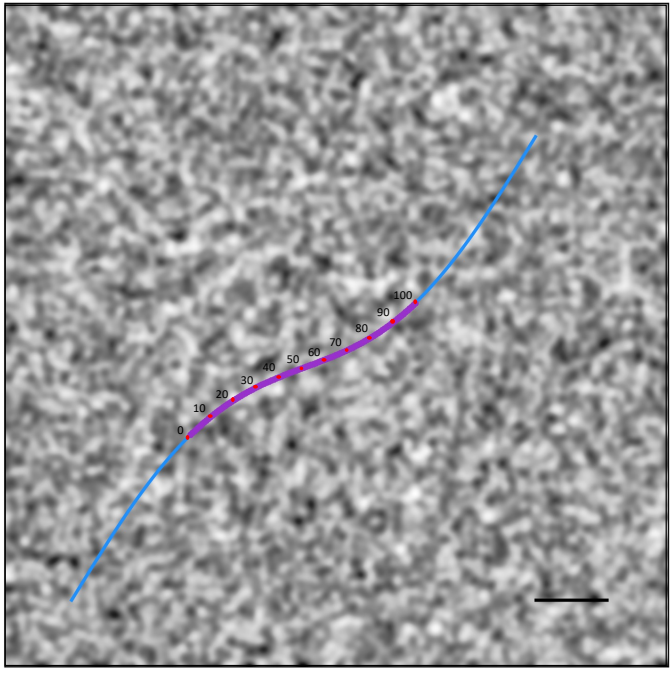



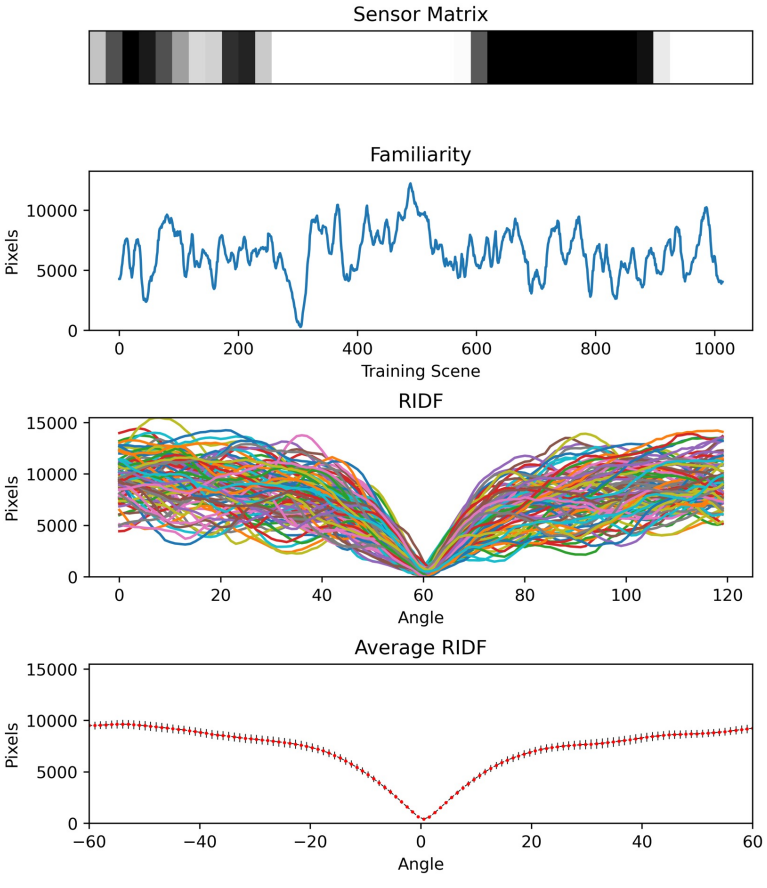

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 50.51; RMSD/dist: 0.126; TD: 6511; p90: 26; p50: 14; complete: 0


Index: BLUR: 6.0; LEVELS: 16; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

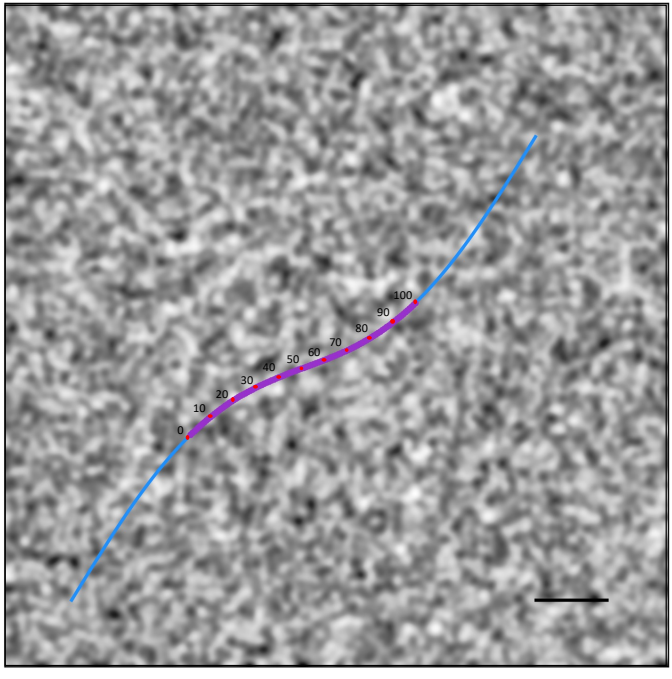


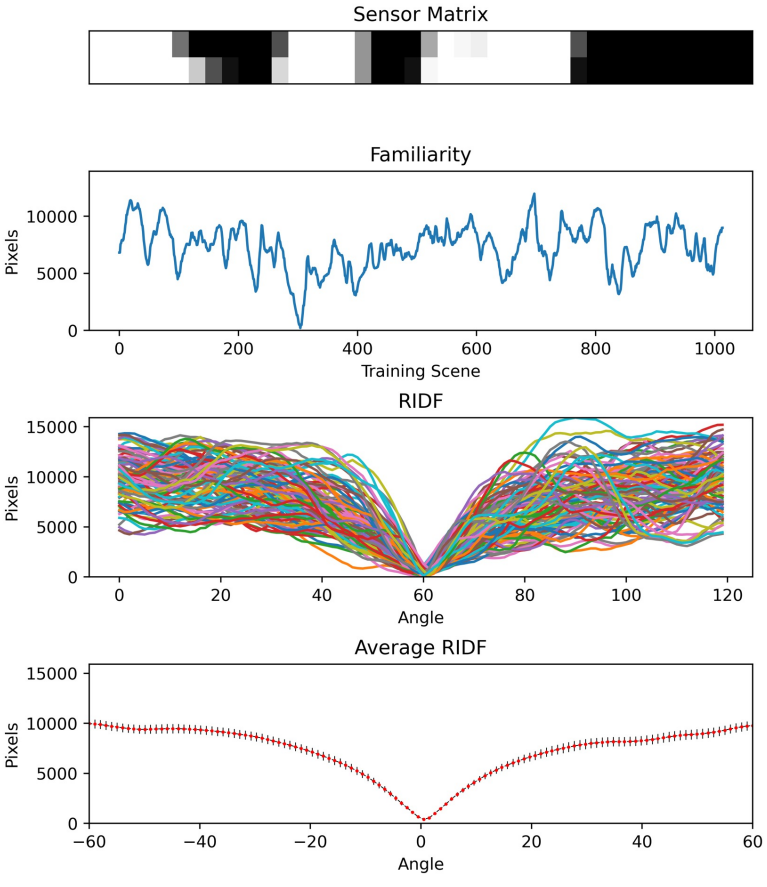




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 30.49; RMSD/dist: 0.076; TD: 6384; p90: 28; p50: 14; complete: 0

100%

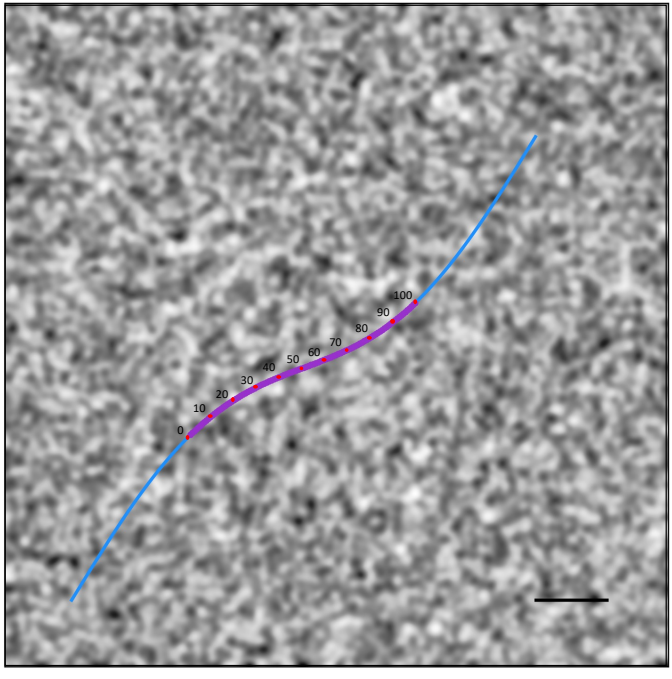


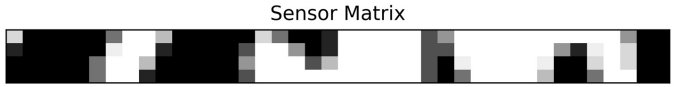



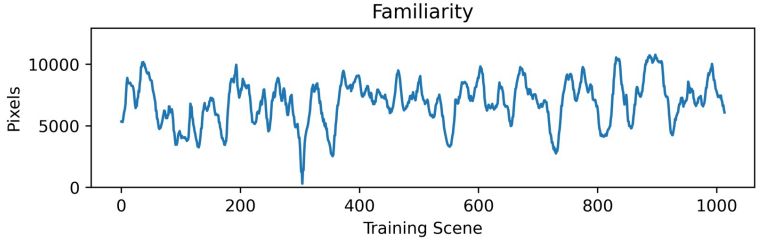

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

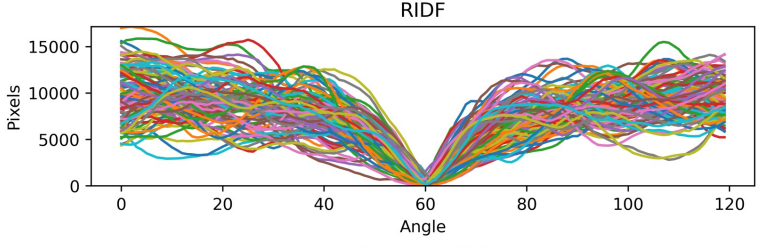
Navigation stats: RMSD error: 33.57; RMSD/dist: 0.084; TD: 6566; p90: 32; p50: 16; complete: 0

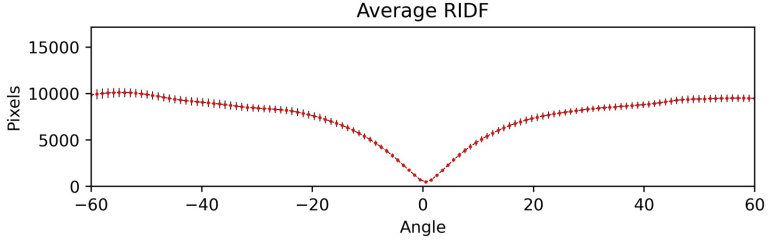
100%



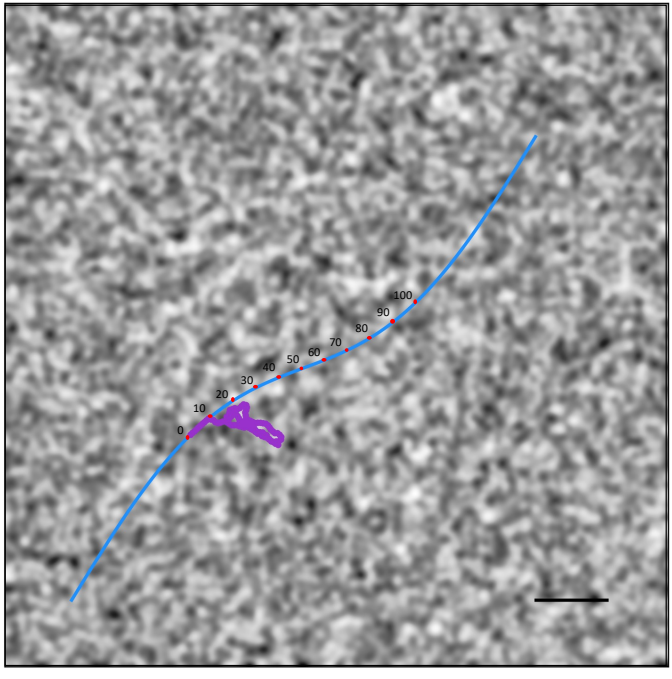



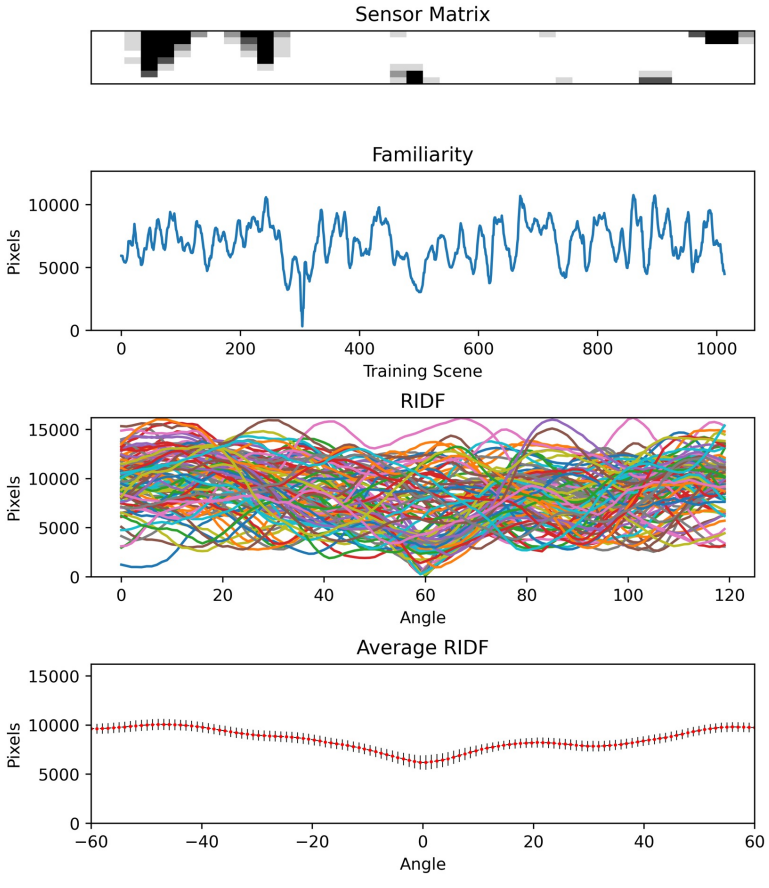




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 32.51; RMSD/dist: 0.081; TD: 6540; p90: 28; p50: 14; complete: 0

10%

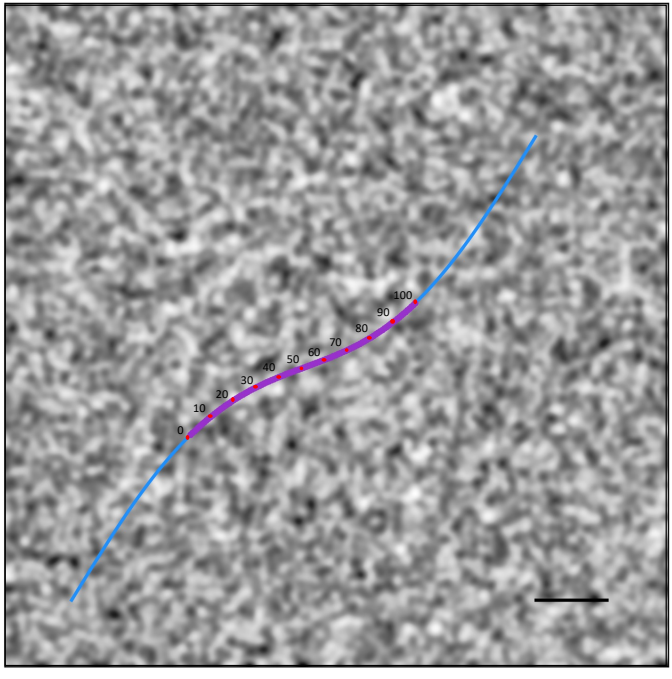


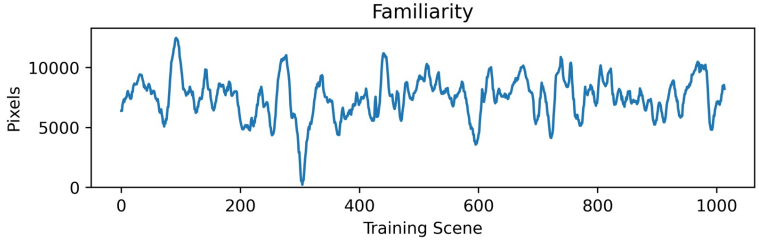



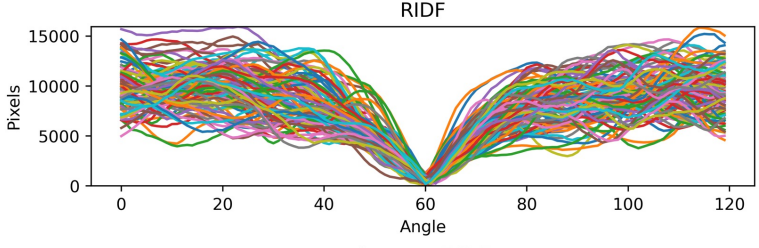

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

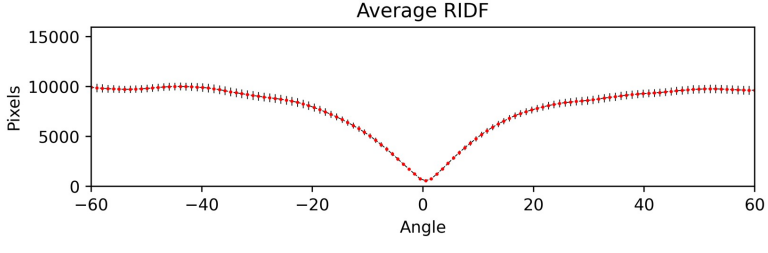
Navigation stats: RMSD error: 3961.21; RMSD/dist: 9.903; TD: 907; p90: 14; p50: 10; complete: 0

100%





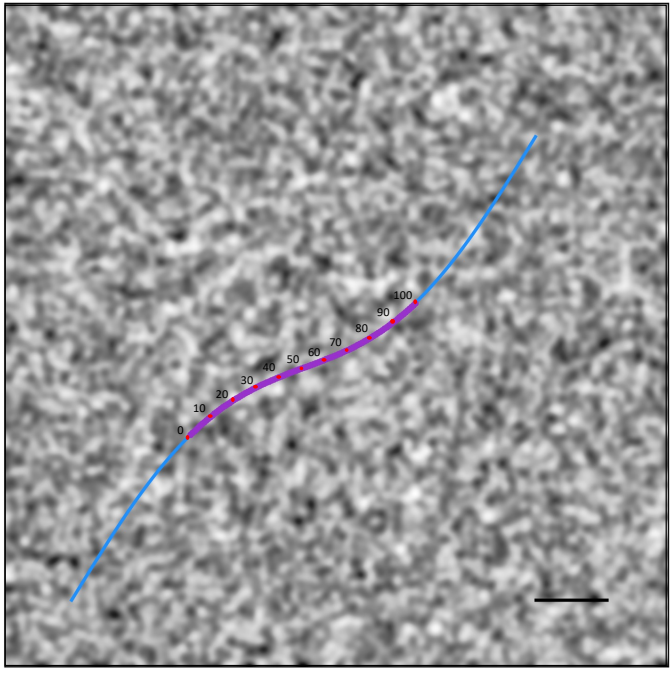



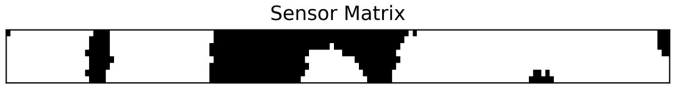



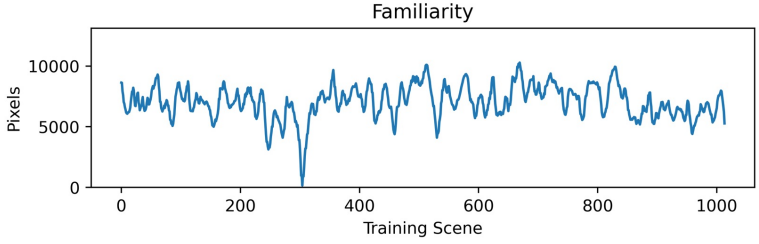

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

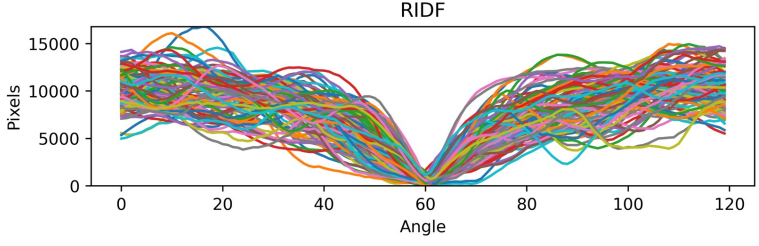
Navigation stats: RMSD error: 44.79; RMSD/dist: 0.112; TD: 6566; p90: 28; p50: 14; complete: 0

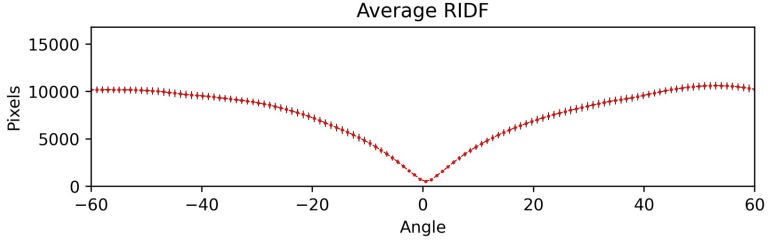
100%



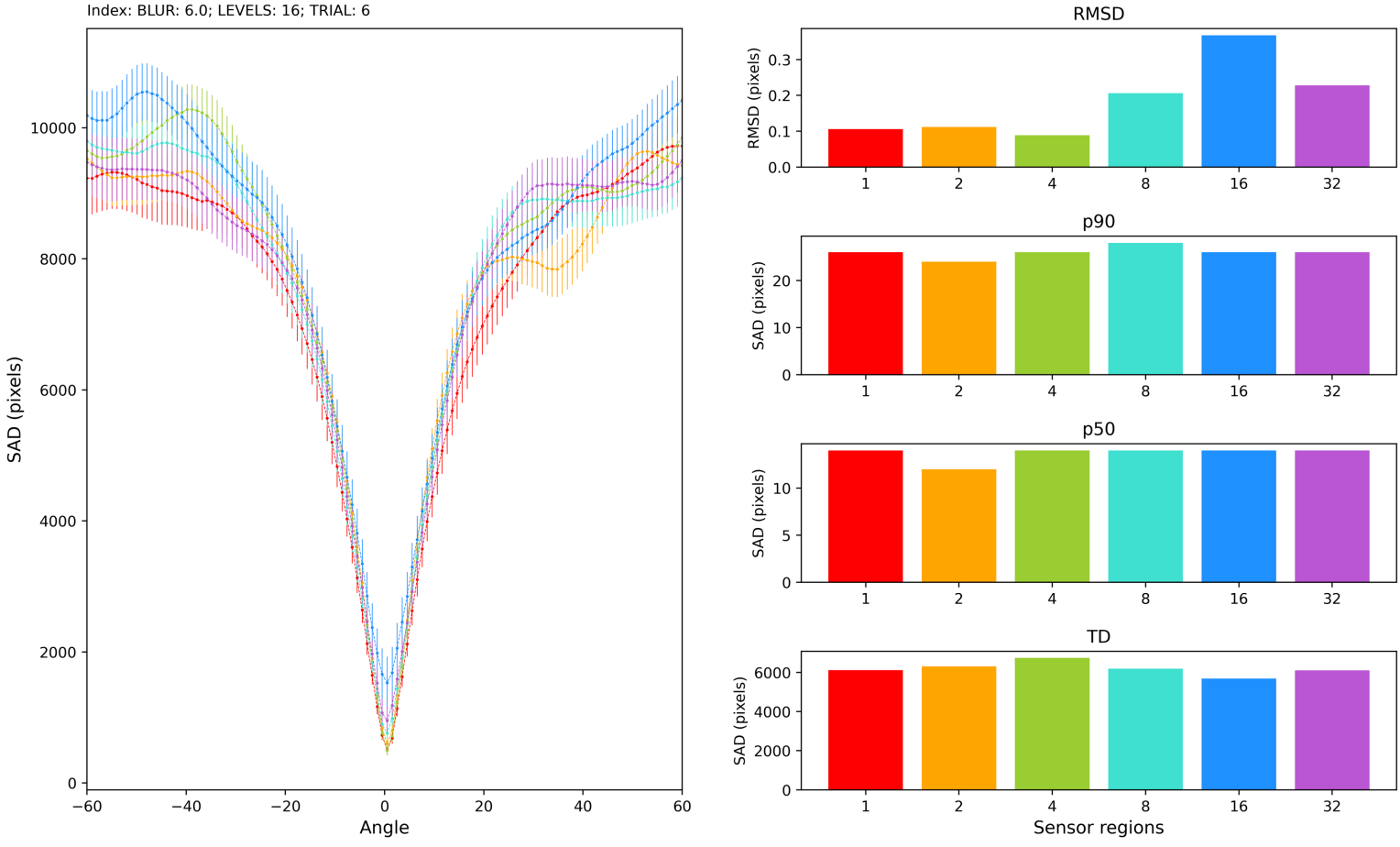



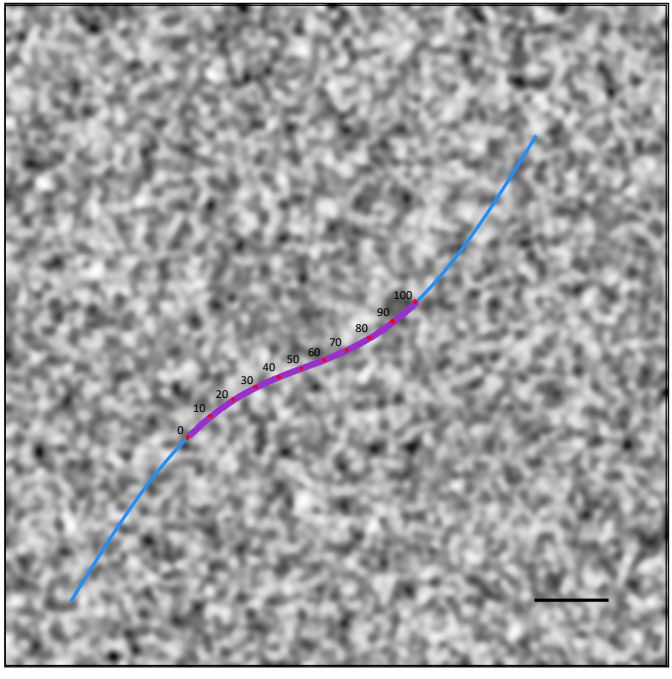



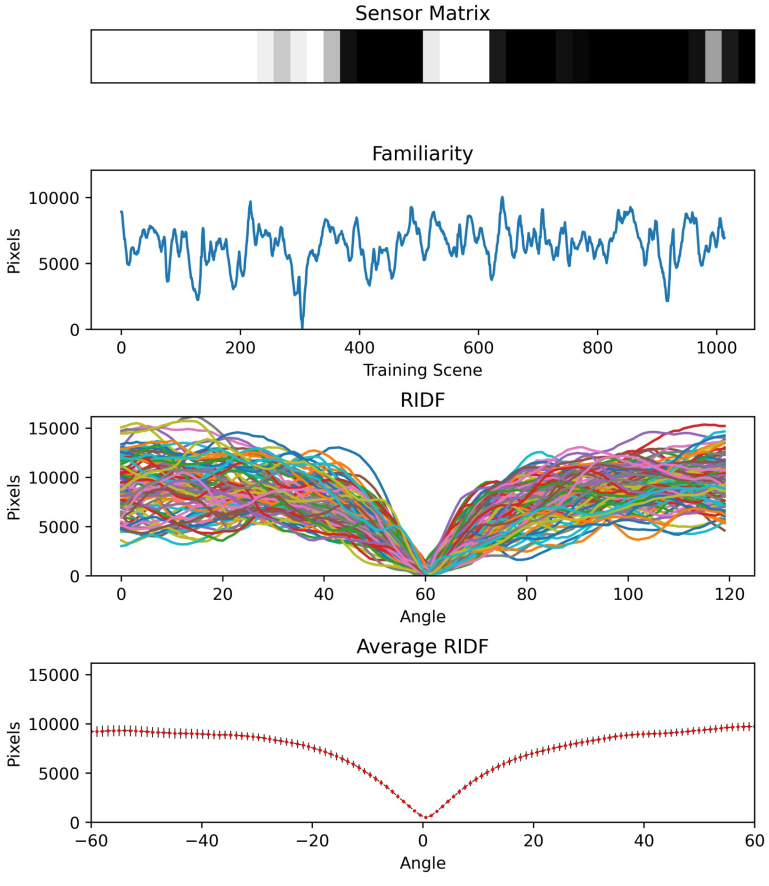

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 39.25; RMSD/dist: 0.098; TD: 6514; p90: 34; p50: 16; complete: 0


Index: BLUR: 6.0; LEVELS: 16; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

100%

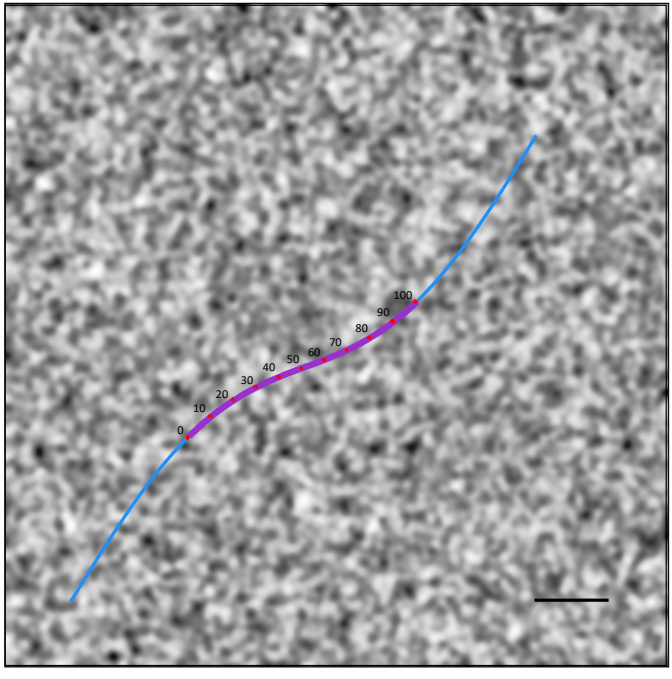


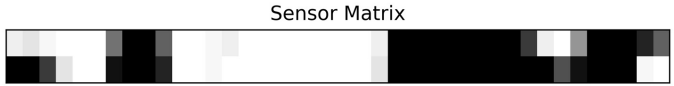



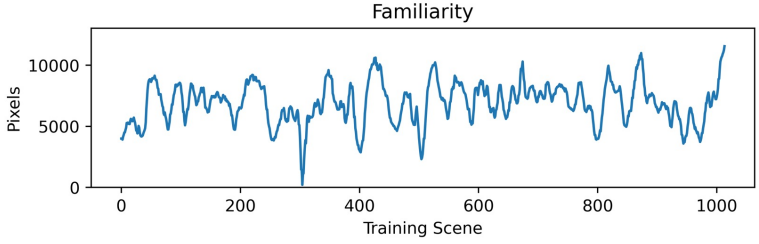

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

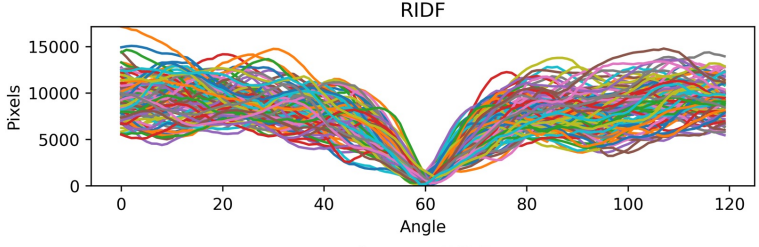
Navigation stats: RMSD error: 42.32; RMSD/dist: 0.106; TD: 6119; p90: 26; p50: 14; complete: 0

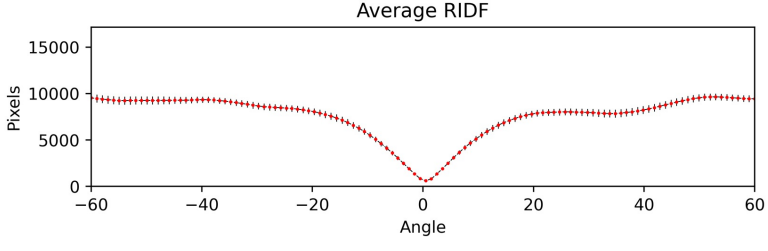
100%



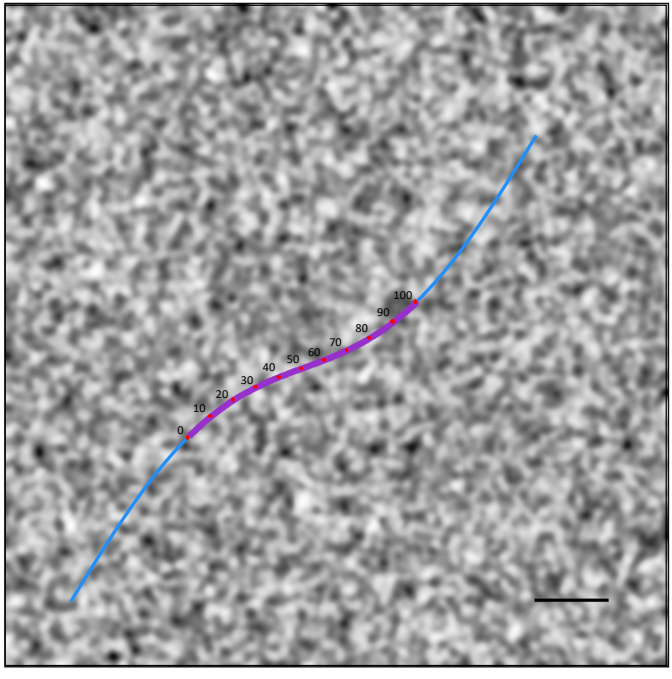



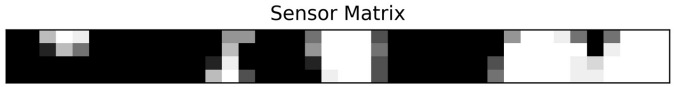



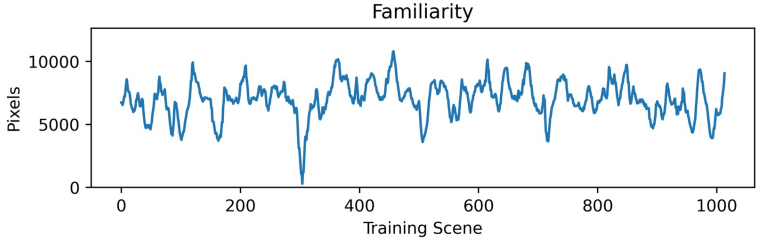

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

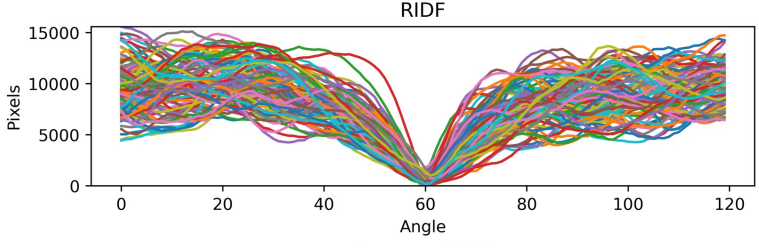
Navigation stats: RMSD error: 44.64; RMSD/dist: 0.112; TD: 6311; p90: 24; p50: 12; complete: 0

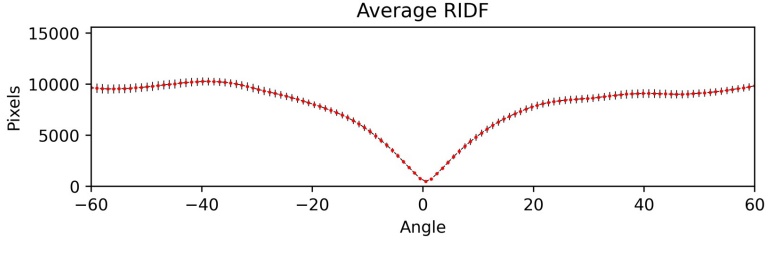
100%



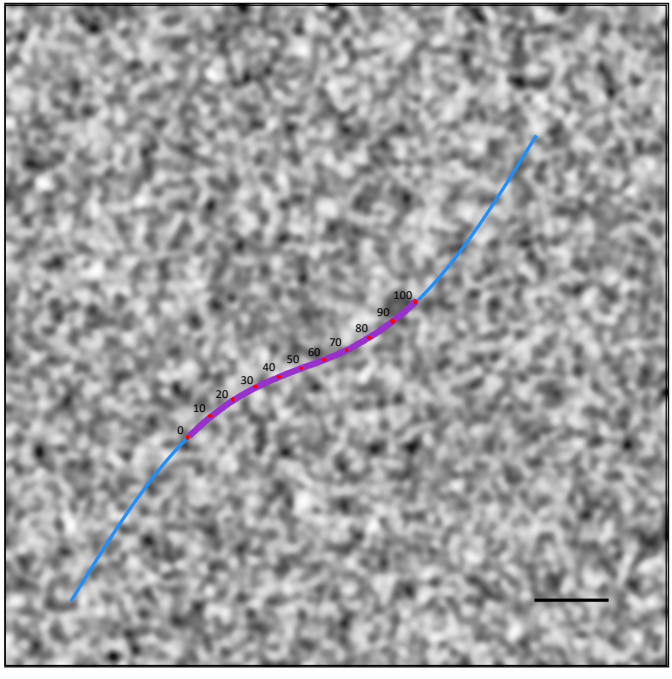



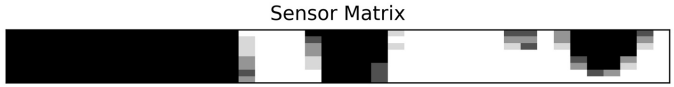



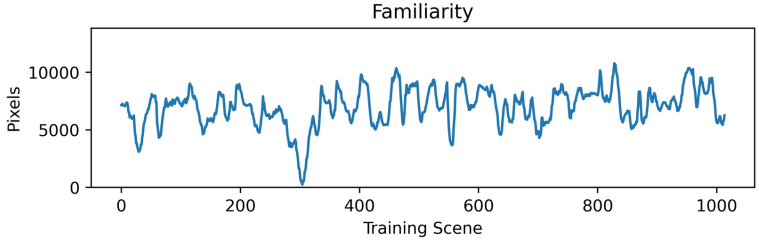

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

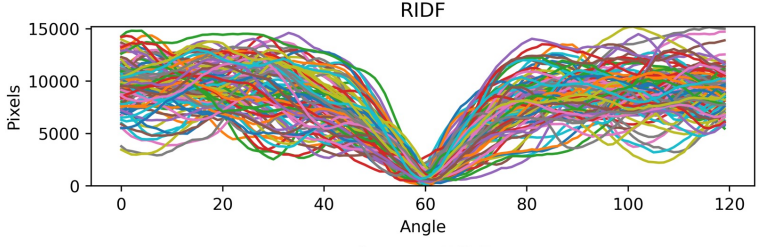
Navigation stats: RMSD error: 35.65; RMSD/dist: 0.089; TD: 6740; p90: 26; p50: 14; complete: 0

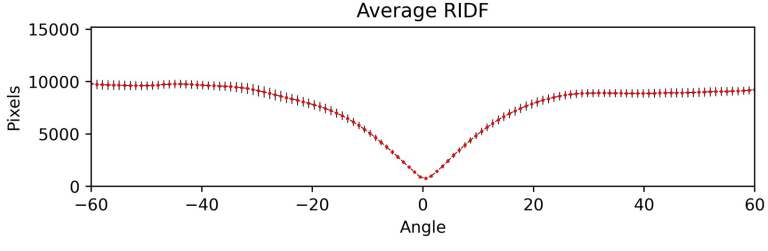
100%



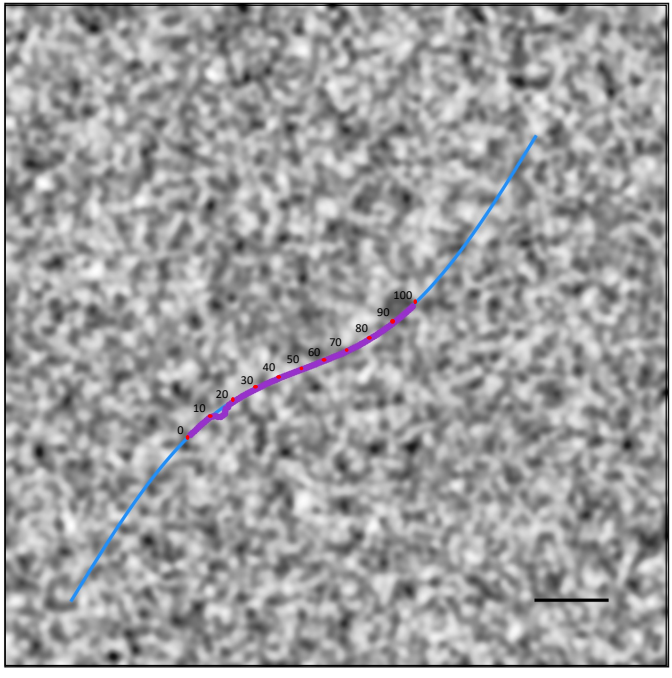



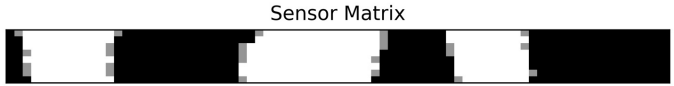



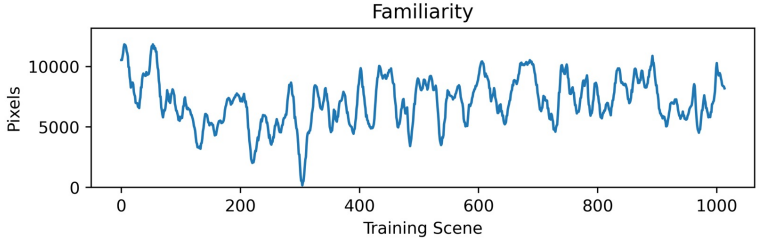

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

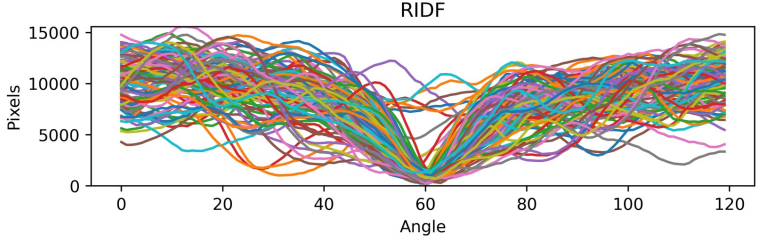
Navigation stats: RMSD error: 82.20; RMSD/dist: 0.206; TD: 6191; p90: 28; p50: 14; complete: 0

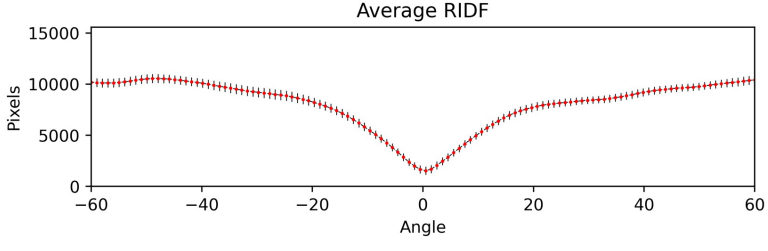
90%



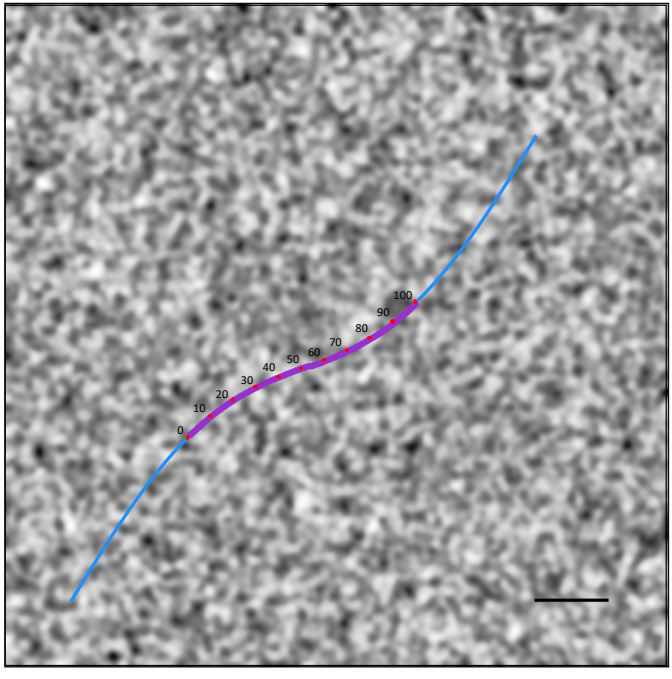



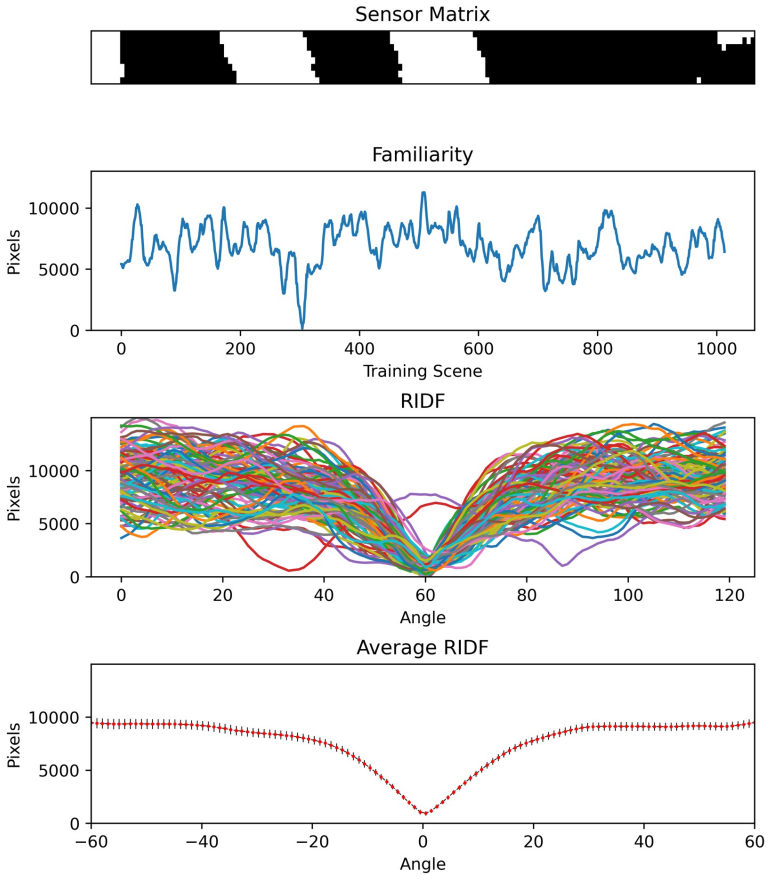




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 147.40; RMSD/dist: 0.368; TD: 5684; p90: 26; p50: 14; complete: 0

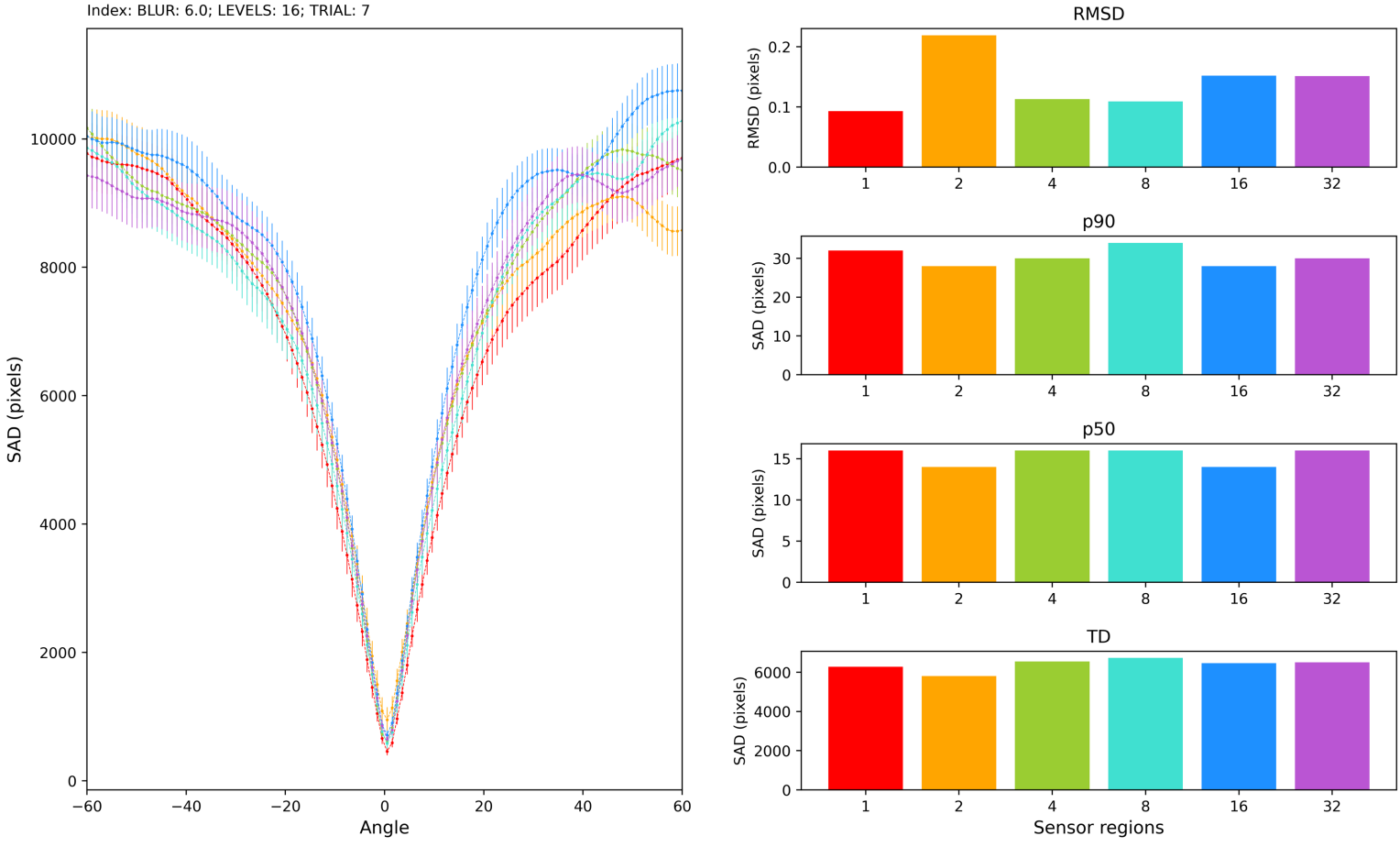
100%



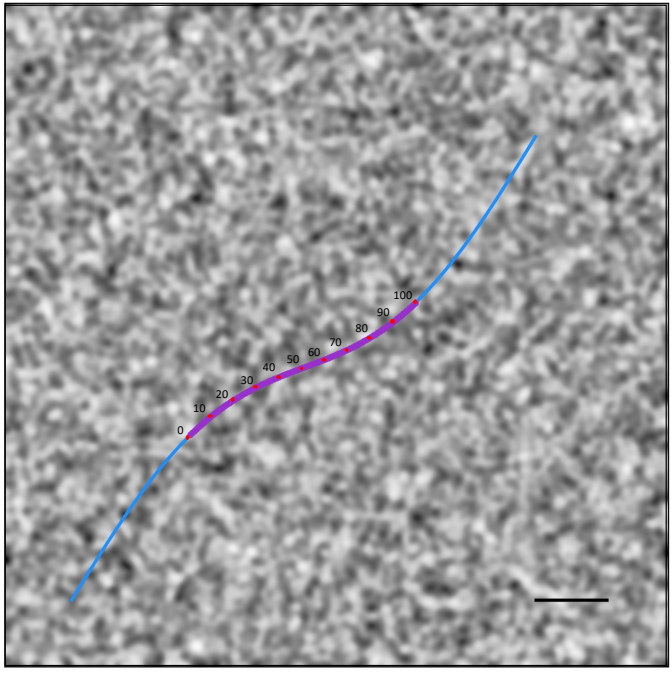



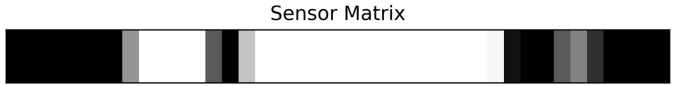

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

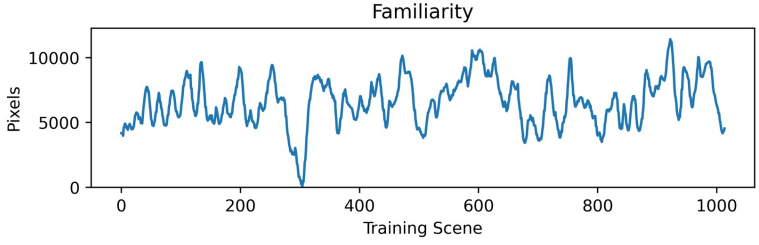
Navigation stats: RMSD error: 91.09; RMSD/dist: 0.228; TD: 6108; p90: 26; p50: 14; complete: 0

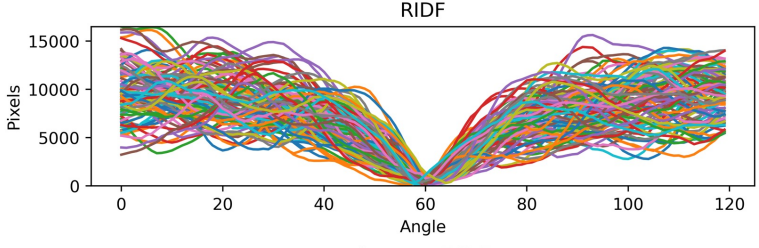

Index: BLUR: 6.0; LEVELS: 16; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

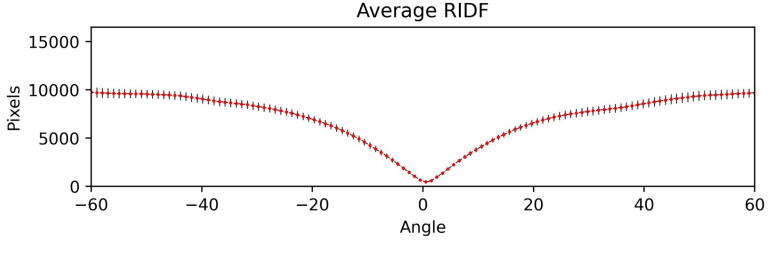
100%



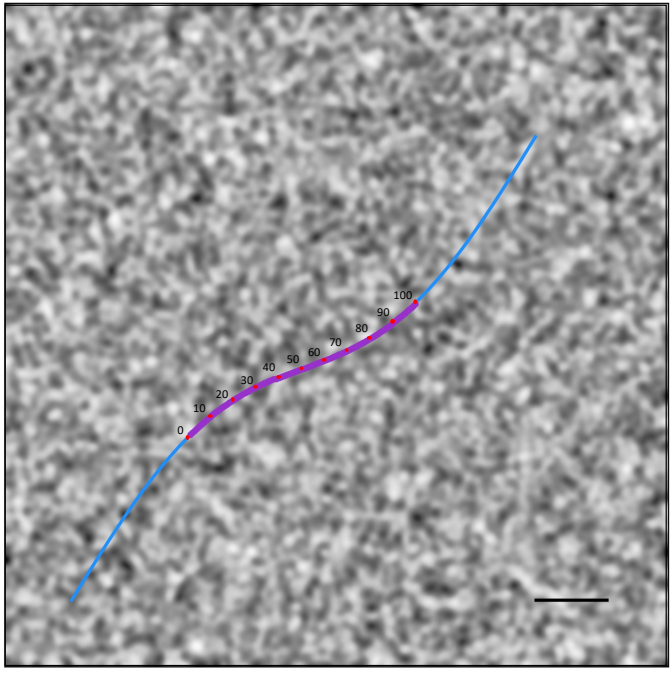



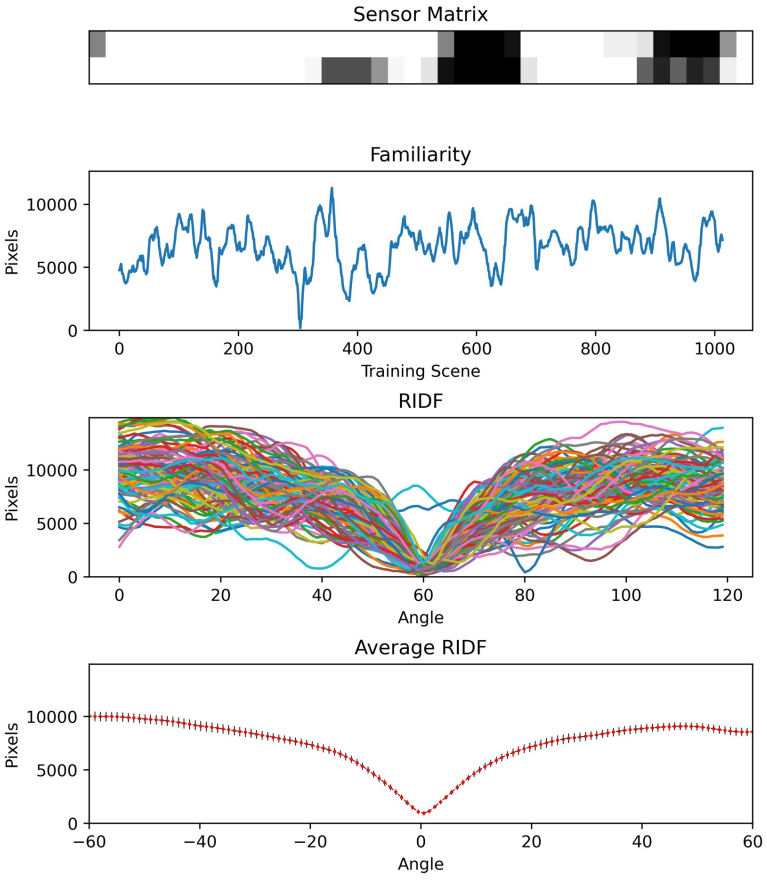




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 37.23; RMSD/dist: 0.093; TD: 6282; p90: 32; p50: 16; complete: 0

100%

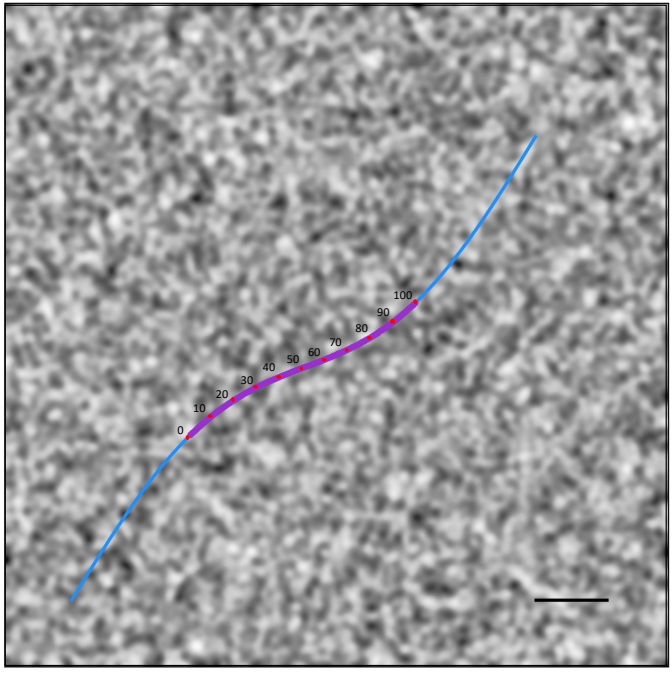


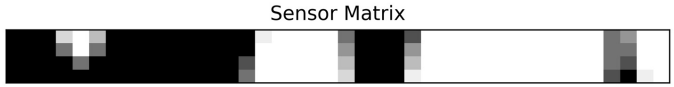



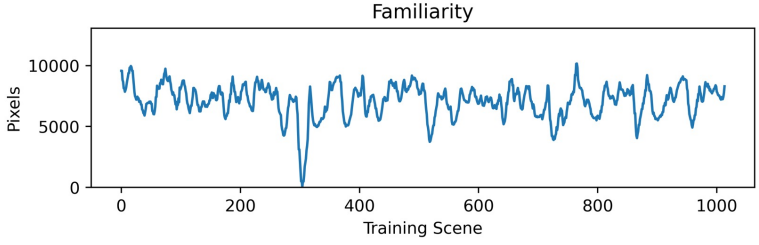

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

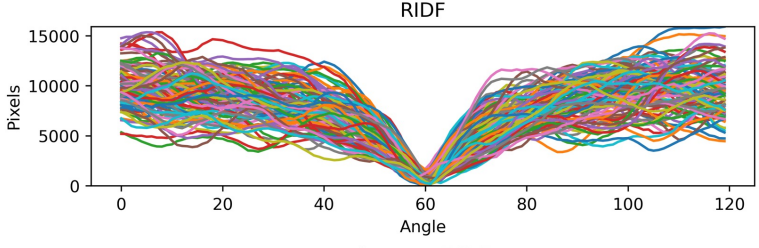
Navigation stats: RMSD error: 87.64; RMSD/dist: 0.219; TD: 5803; p90: 28; p50: 14; complete: 0

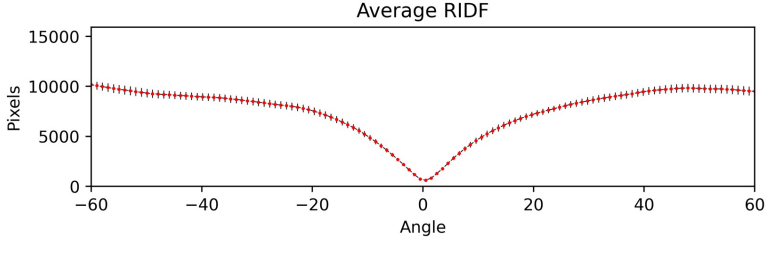
100%



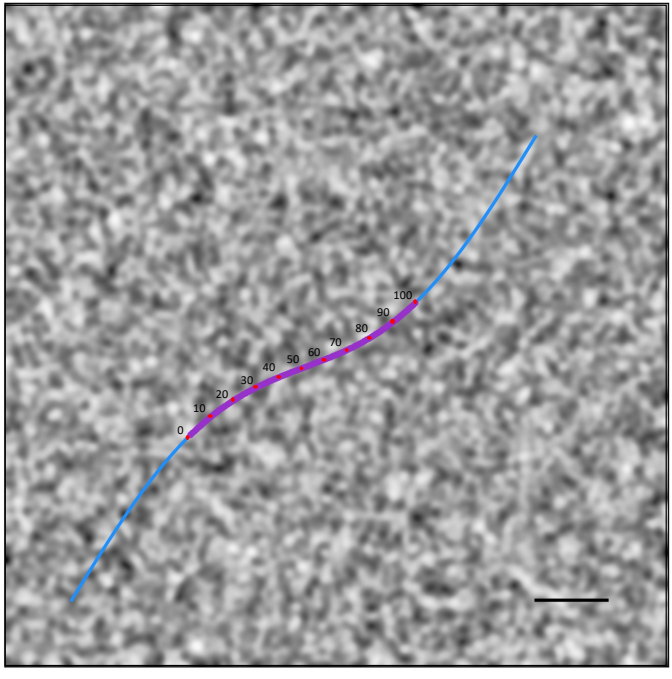



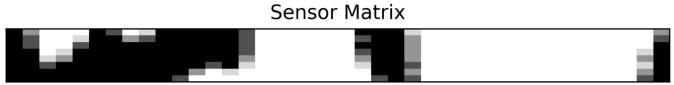



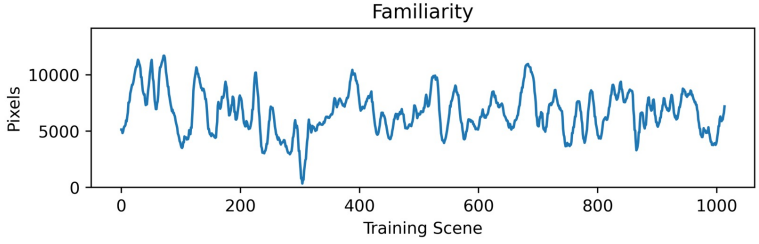

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

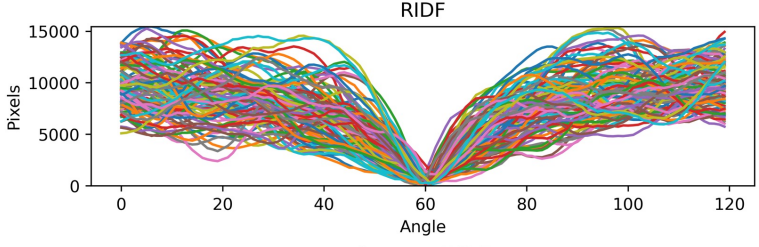
Navigation stats: RMSD error: 45.37; RMSD/dist: 0.113; TD: 6549; p90: 30; p50: 16; complete: 0

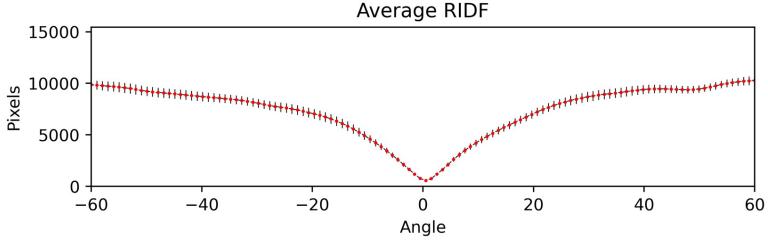
100%



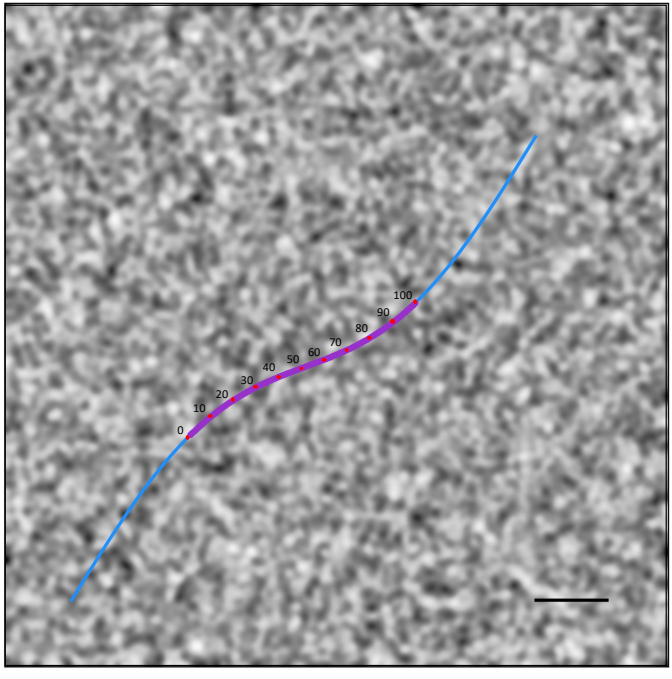



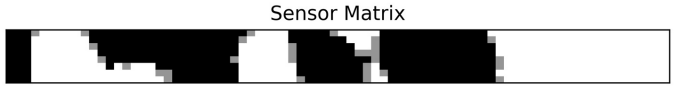



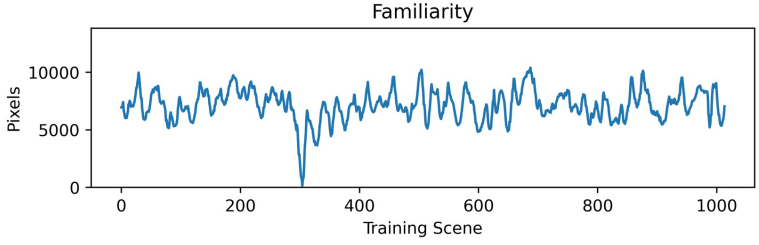

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

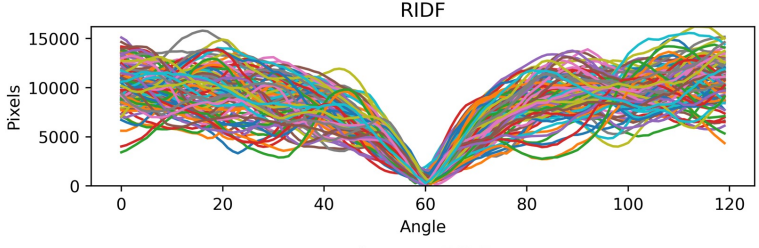
Navigation stats: RMSD error: 43.43; RMSD/dist: 0.109; TD: 6727; p90: 34; p50: 16; complete: 0

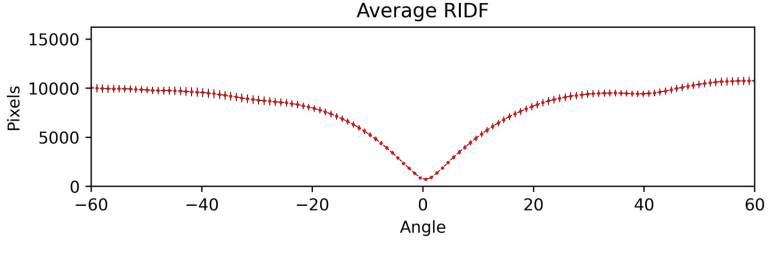
100%



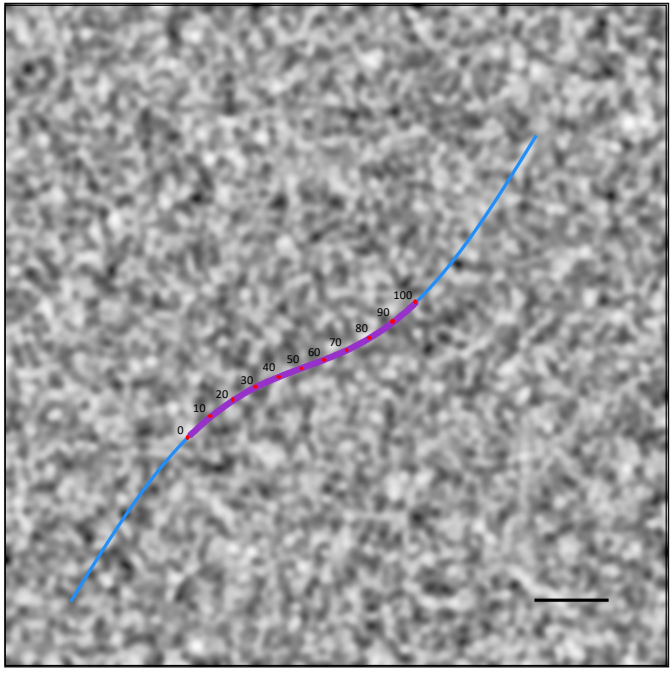



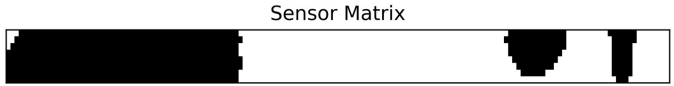



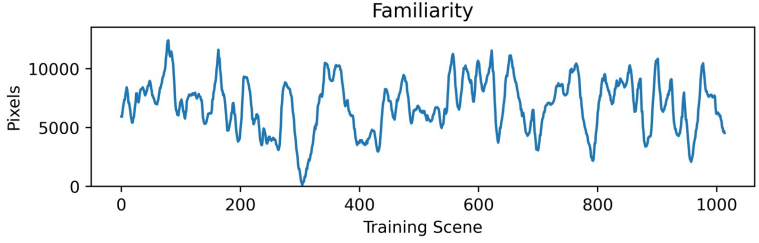

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

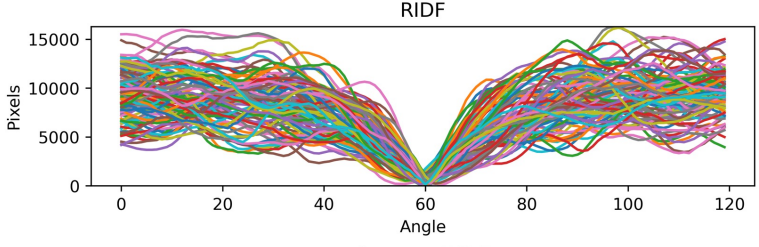
Navigation stats: RMSD error: 60.71; RMSD/dist: 0.152; TD: 6463; p90: 28; p50: 14; complete: 0

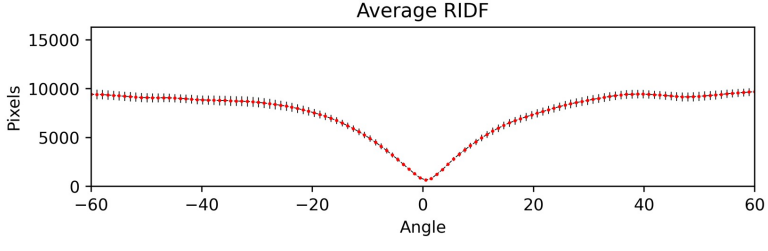
100%



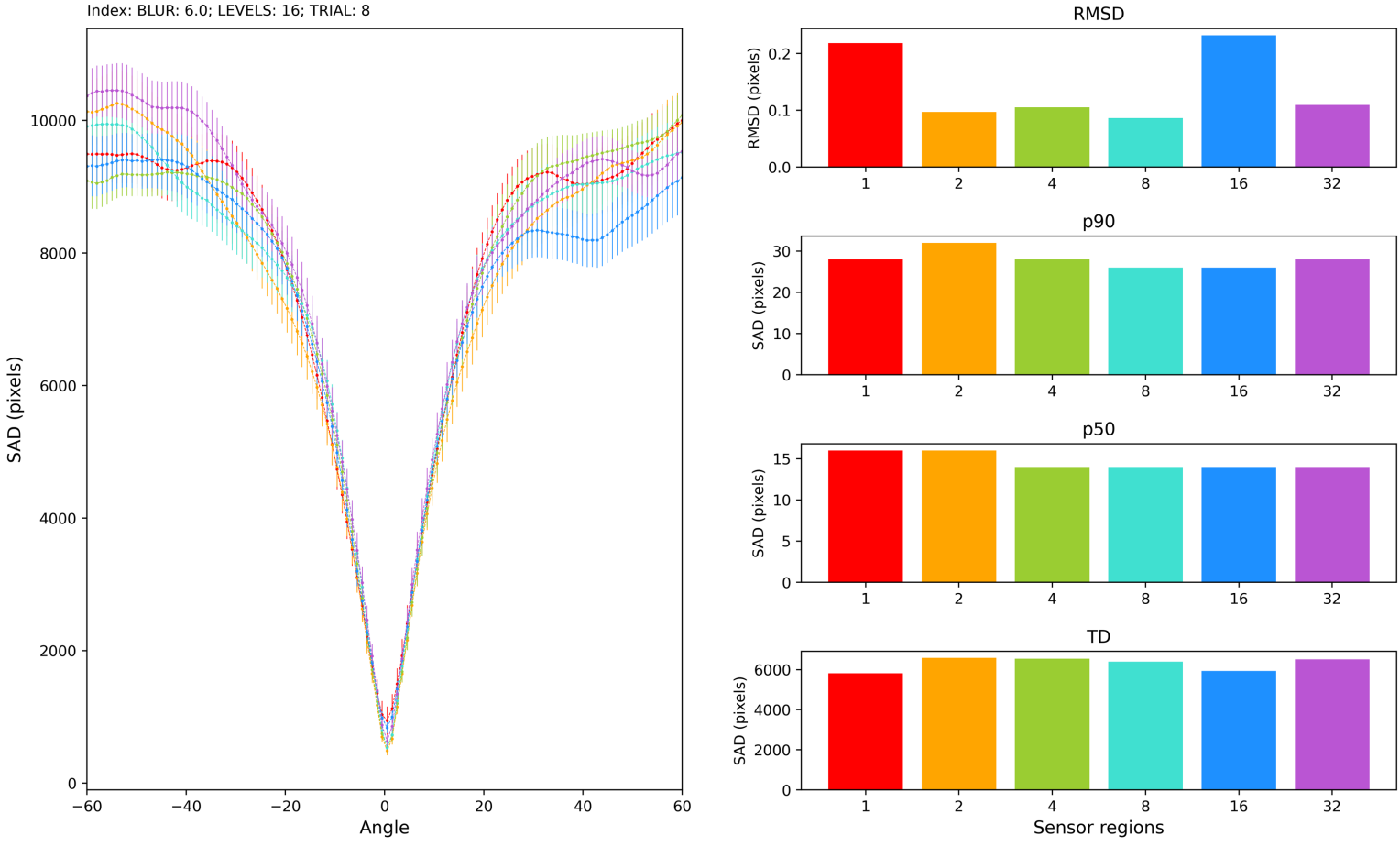



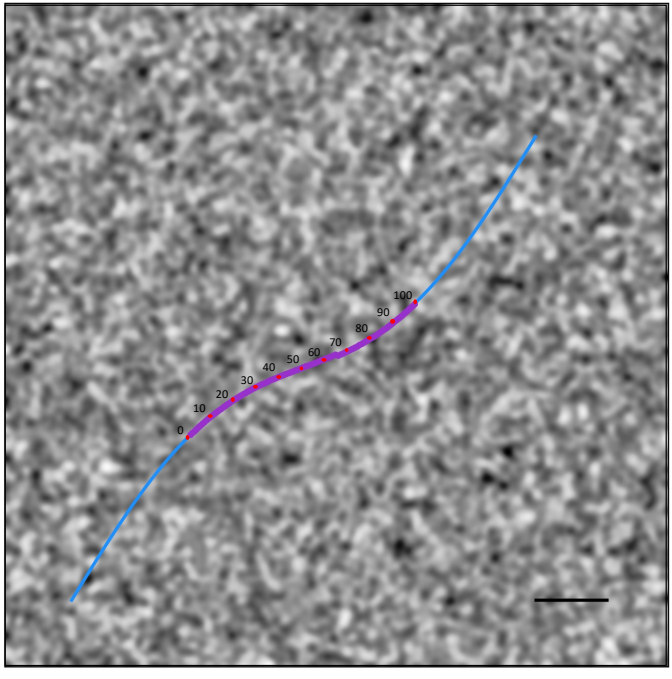



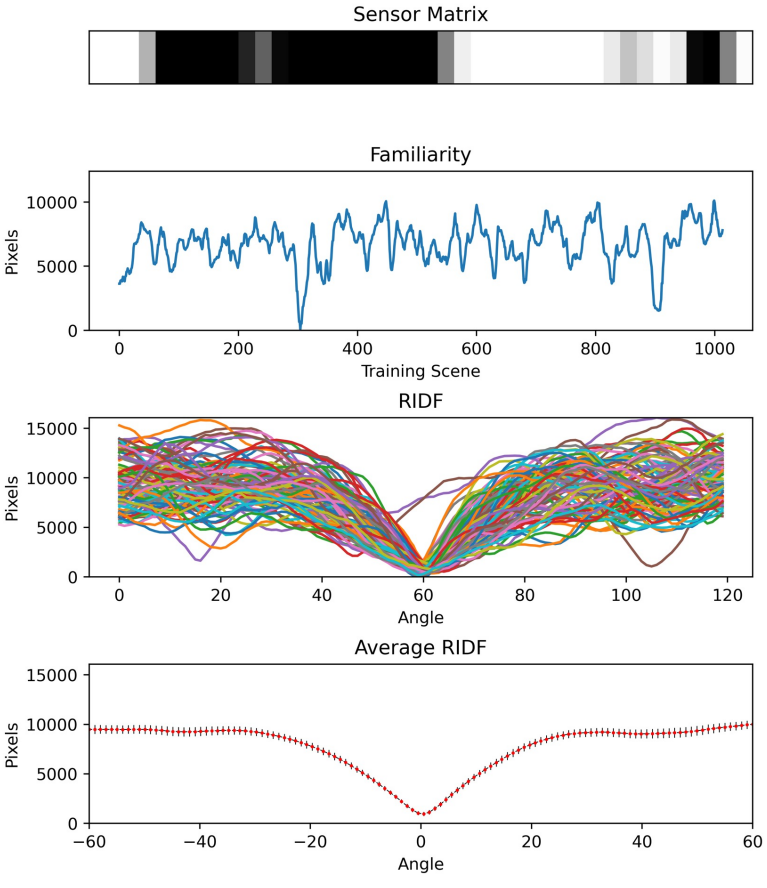

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 60.44; RMSD/dist: 0.151; TD: 6502; p90: 30; p50: 16; complete: 0


Index: BLUR: 6.0; LEVELS: 16; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

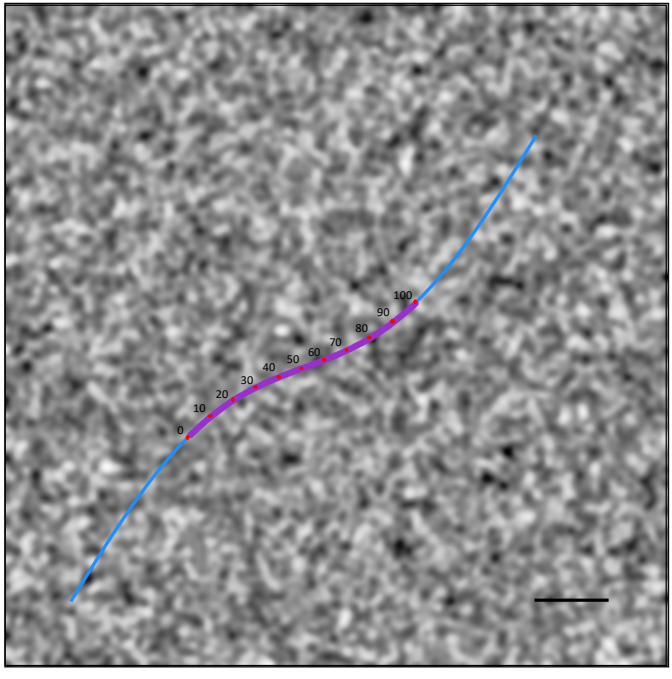


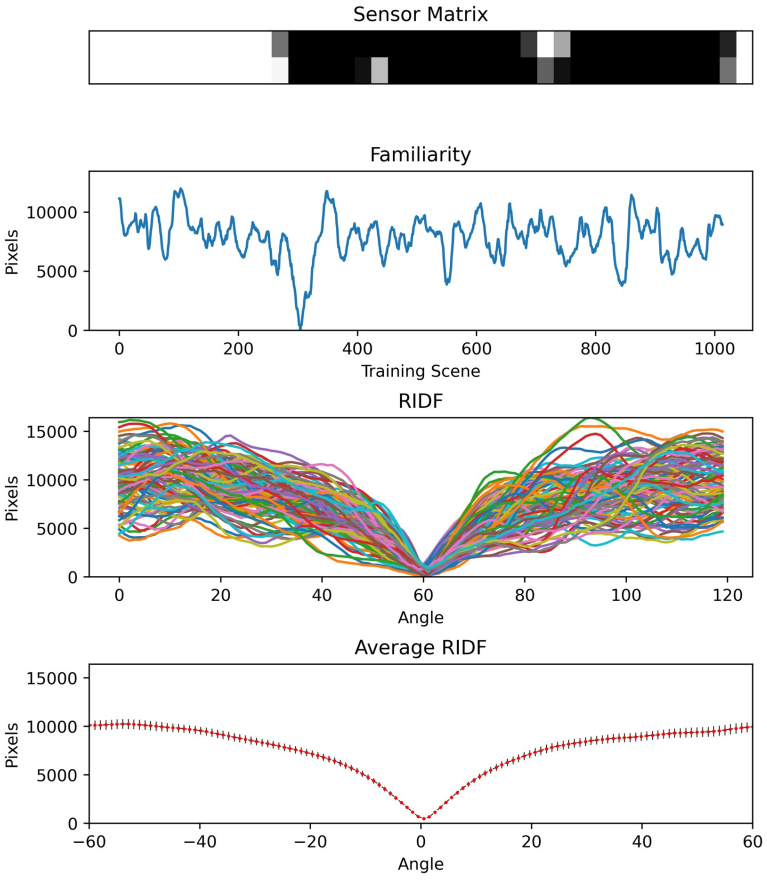




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 87.28; RMSD/dist: 0.218; TD: 5815; p90: 28; p50: 16; complete: 0

100%

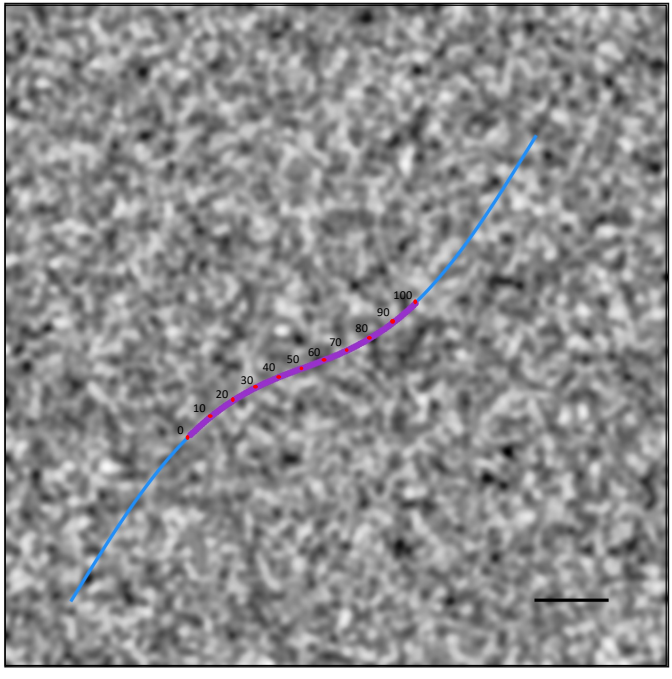


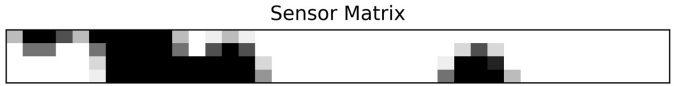



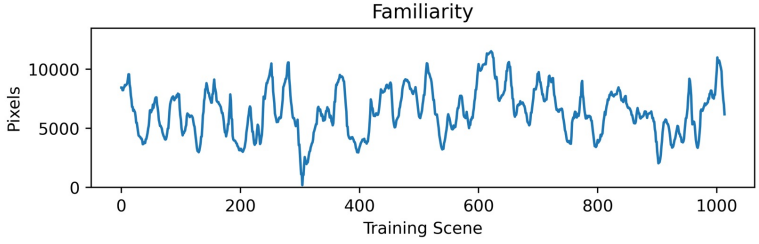

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

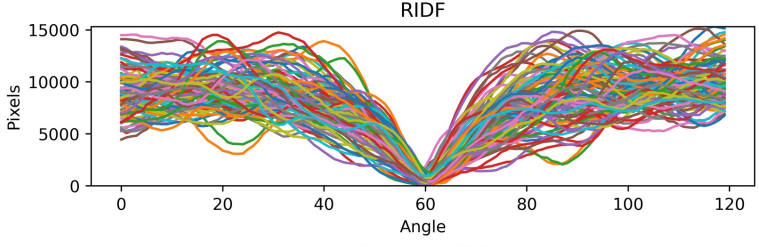
Navigation stats: RMSD error: 38.88; RMSD/dist: 0.097; TD: 6580; p90: 32; p50: 16; complete: 0

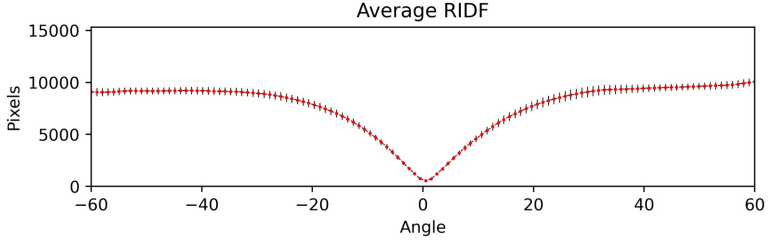
100%



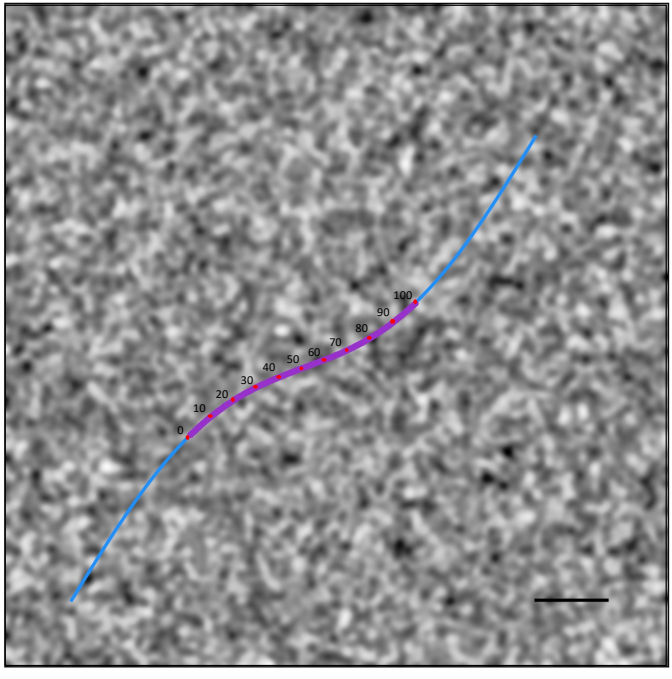



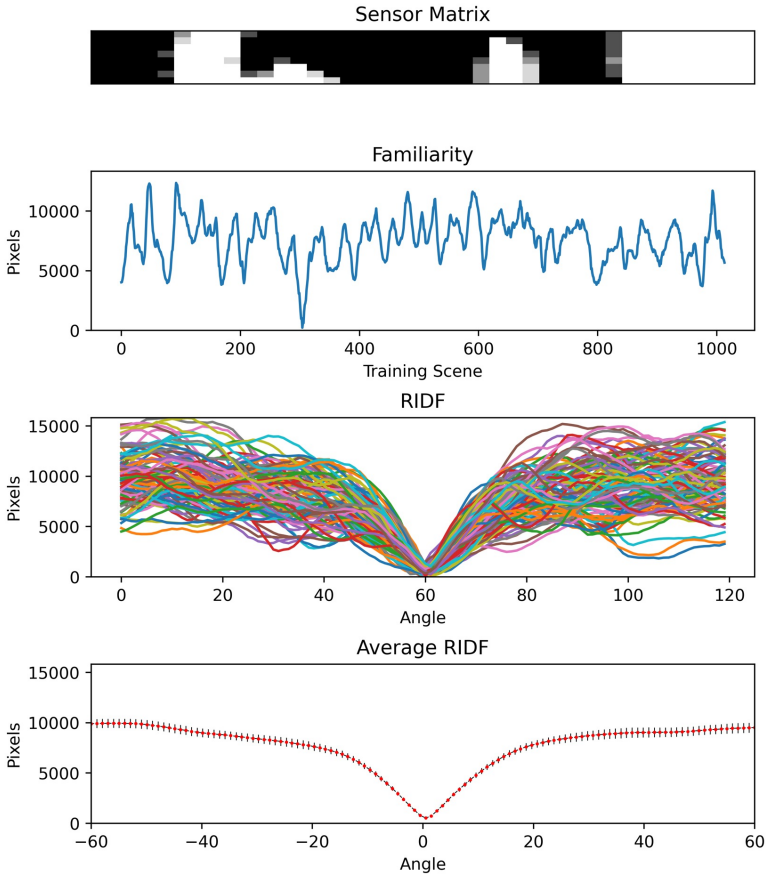




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 42.06; RMSD/dist: 0.105; TD: 6539; p90: 28; p50: 14; complete: 0

100%

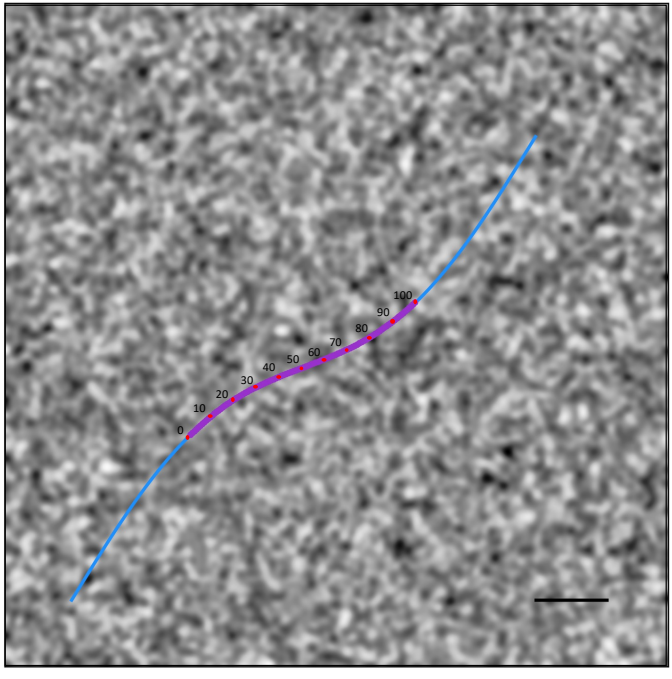


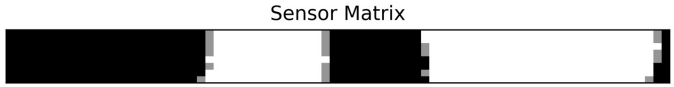



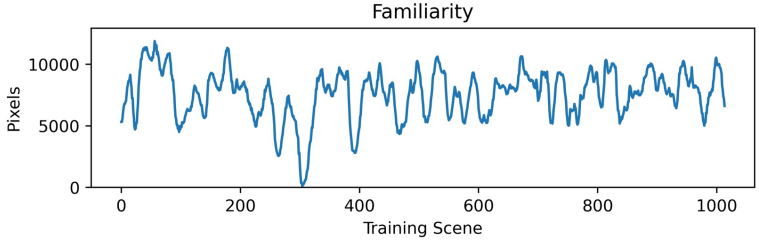

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

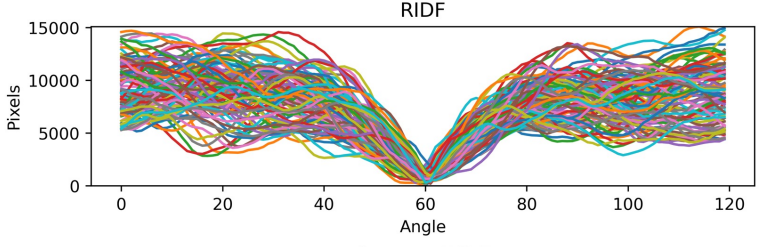
Navigation stats: RMSD error: 34.22; RMSD/dist: 0.086; TD: 6397; p90: 26; p50: 14; complete: 0

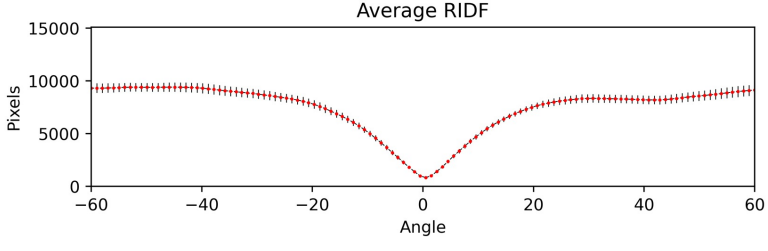
100%



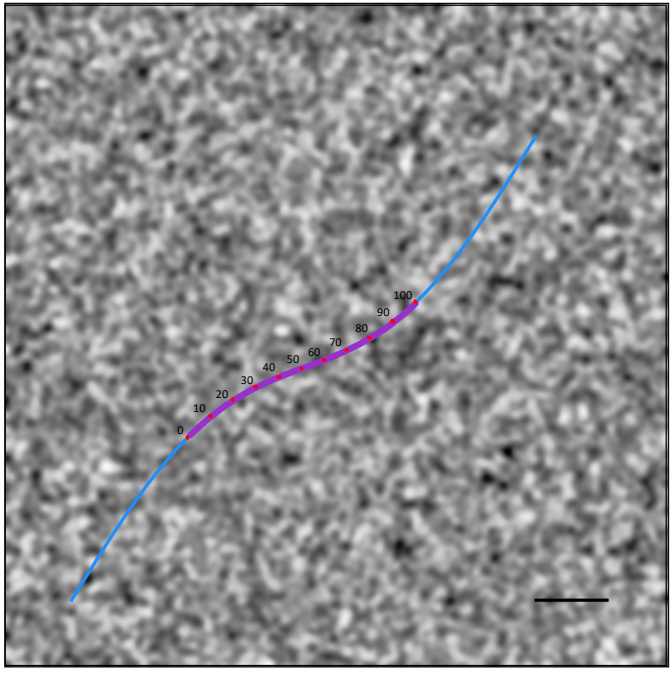



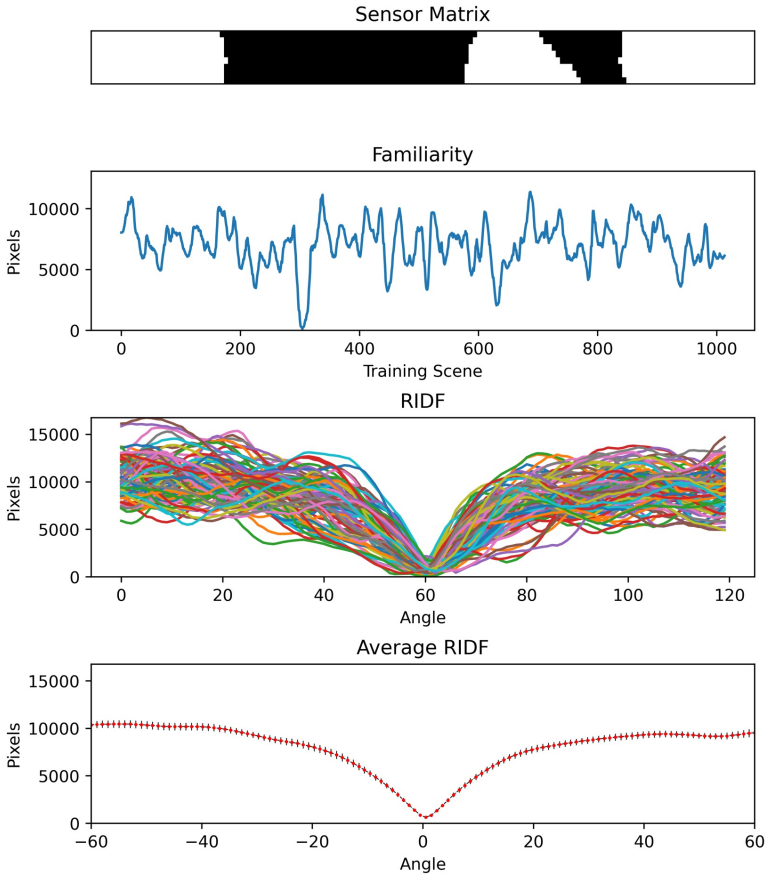




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 92.73; RMSD/dist: 0.232; TD: 5936; p90: 26; p50: 14; complete: 0

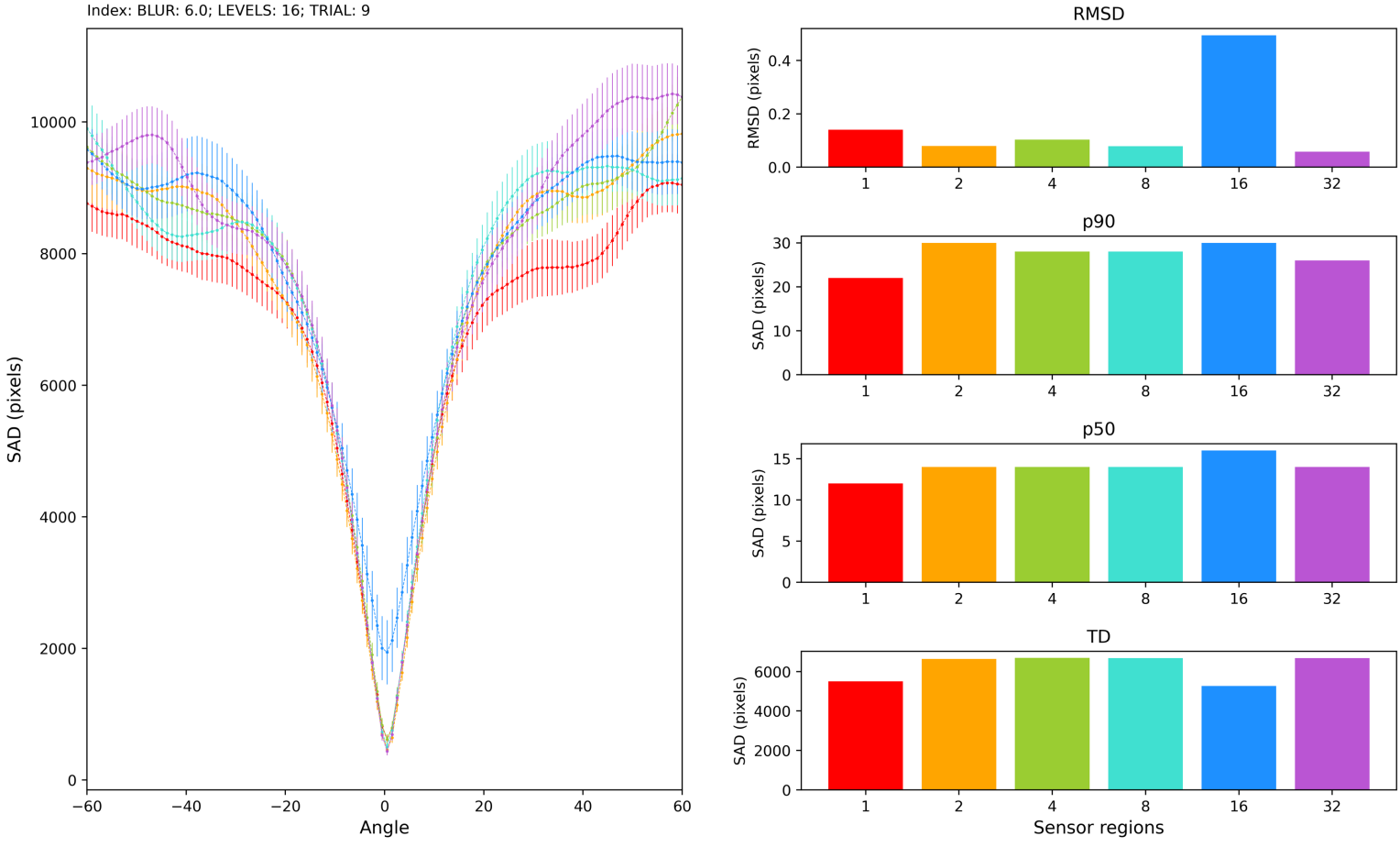
100%



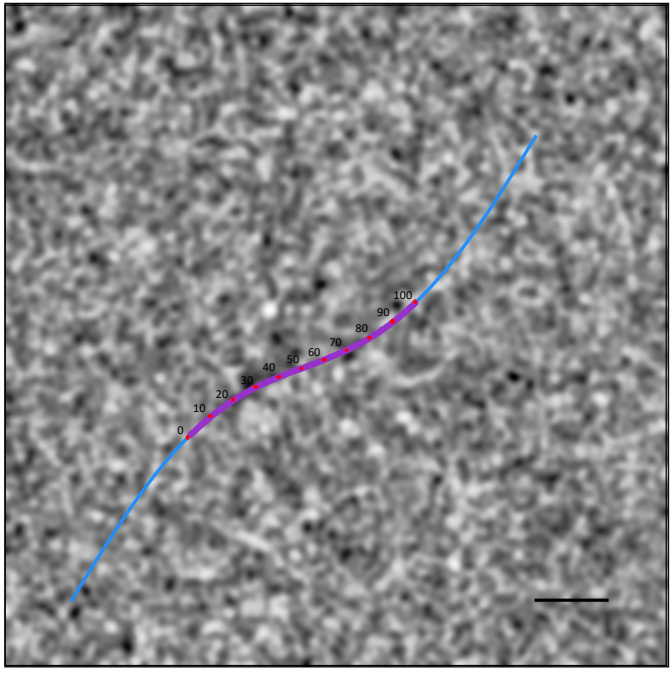



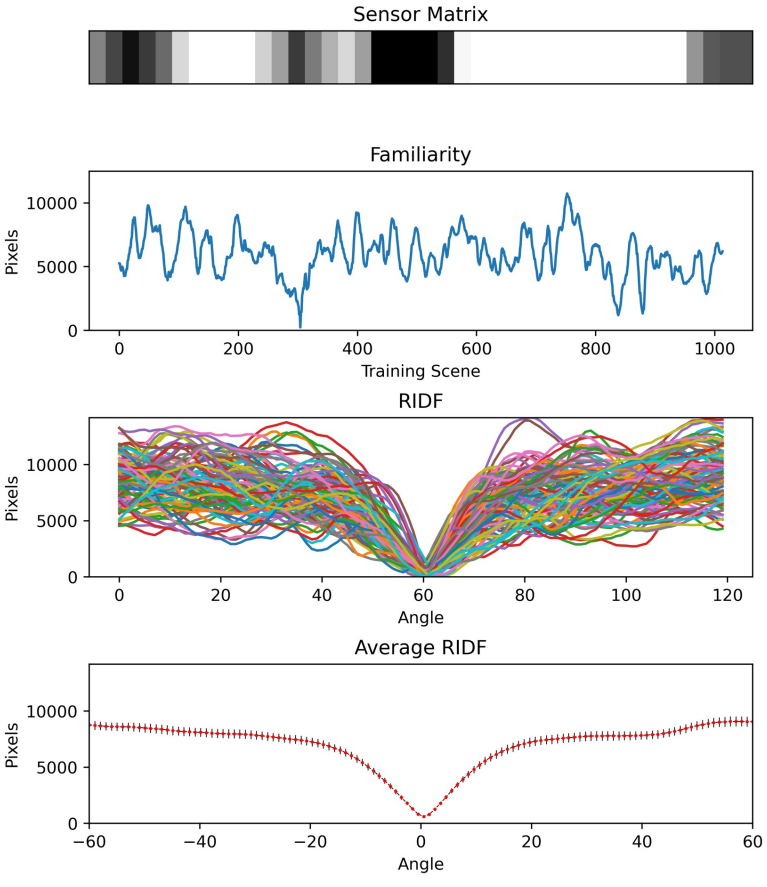

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 43.68; RMSD/dist: 0.109; TD: 6513; p90: 28; p50: 14; complete: 0


Index: BLUR: 6.0; LEVELS: 16; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

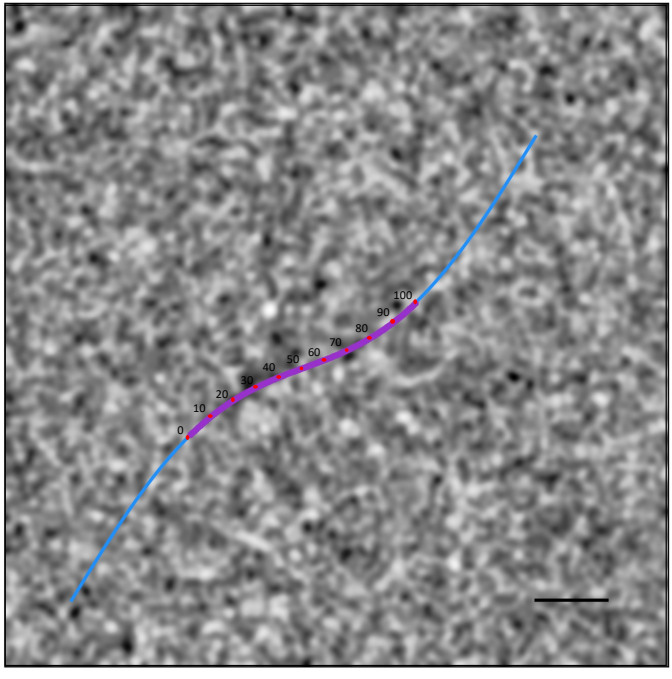


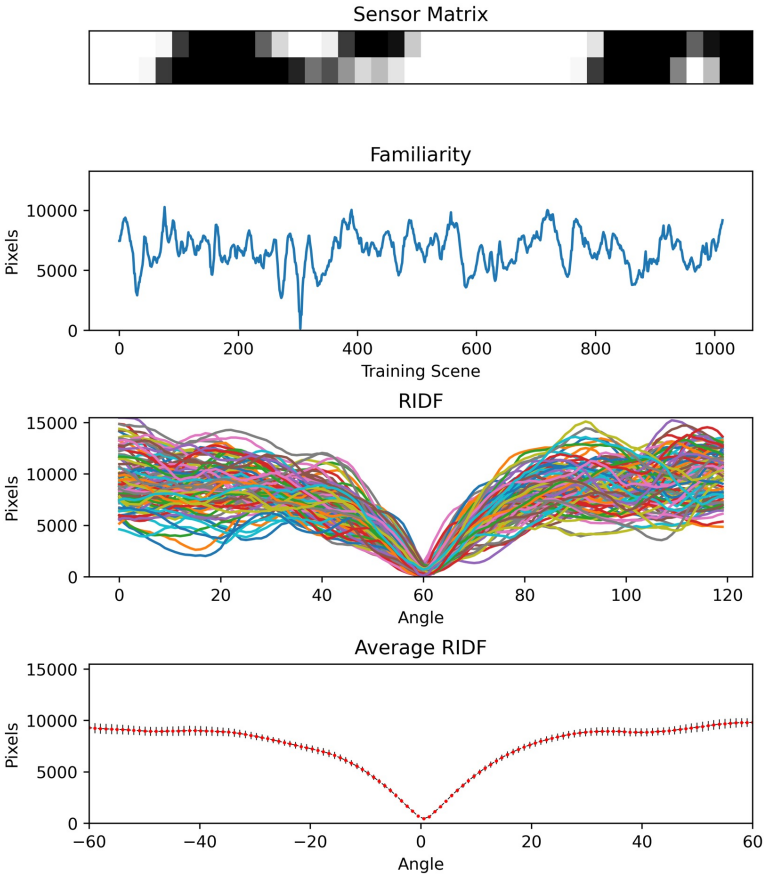




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 56.01; RMSD/dist: 0.140; TD: 5504; p90: 22; p50: 12; complete: 0

100%

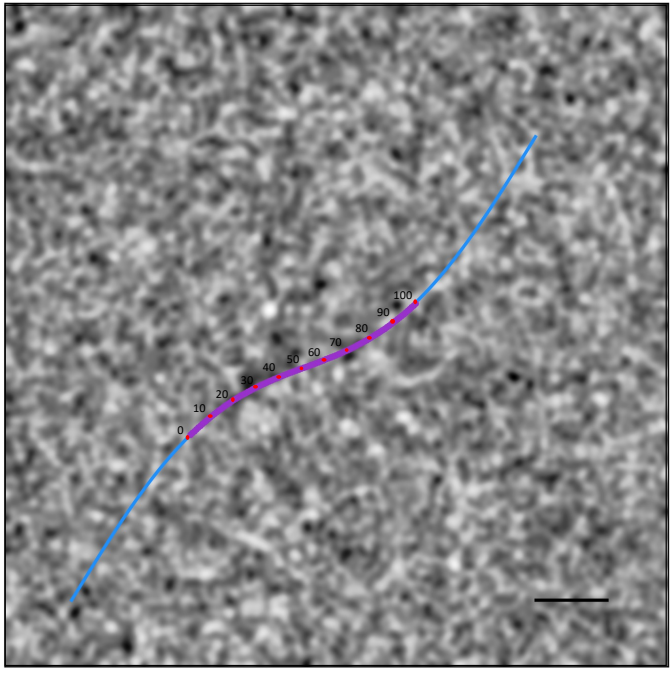


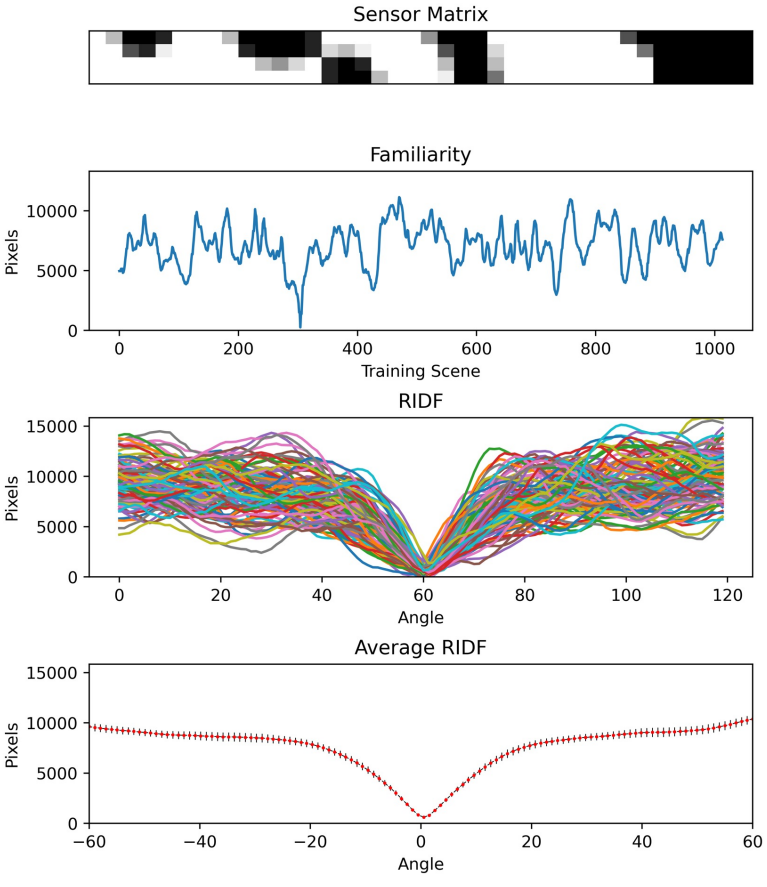




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 31.48; RMSD/dist: 0.079; TD: 6643; p90: 30; p50: 14; complete: 0

100%

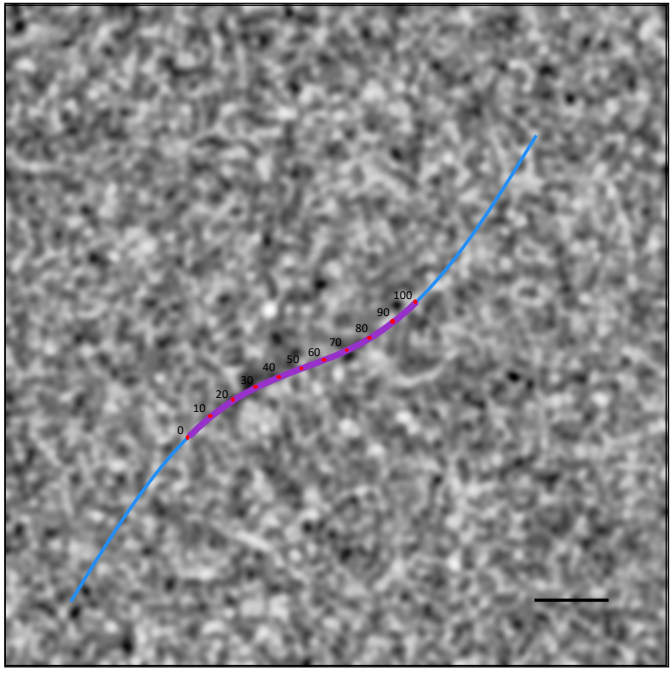


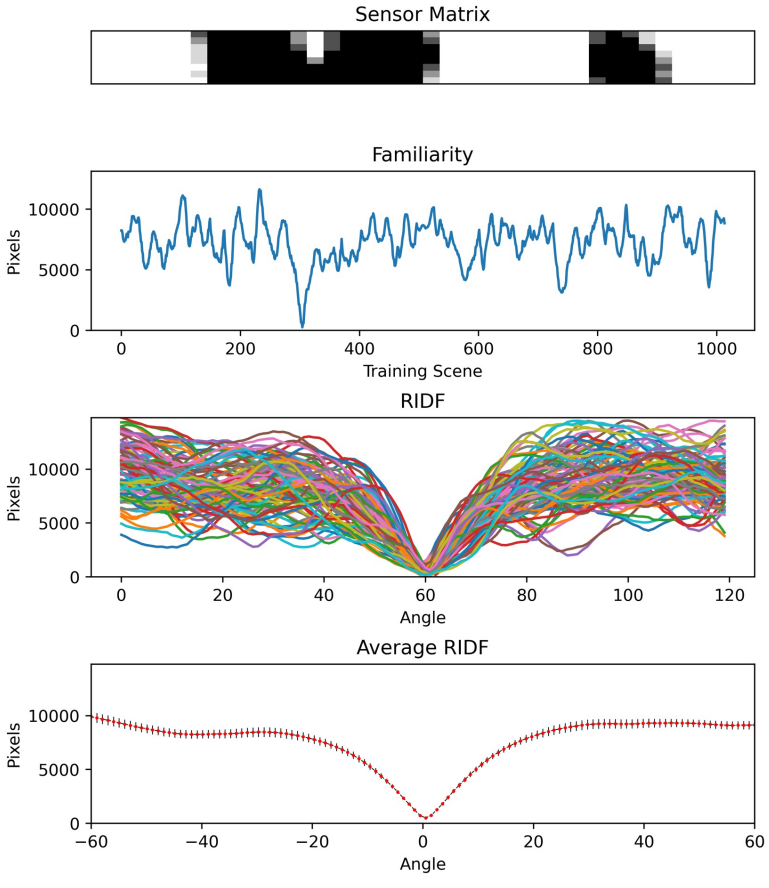




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 41.26; RMSD/dist: 0.103; TD: 6687; p90: 28; p50: 14; complete: 0

100%

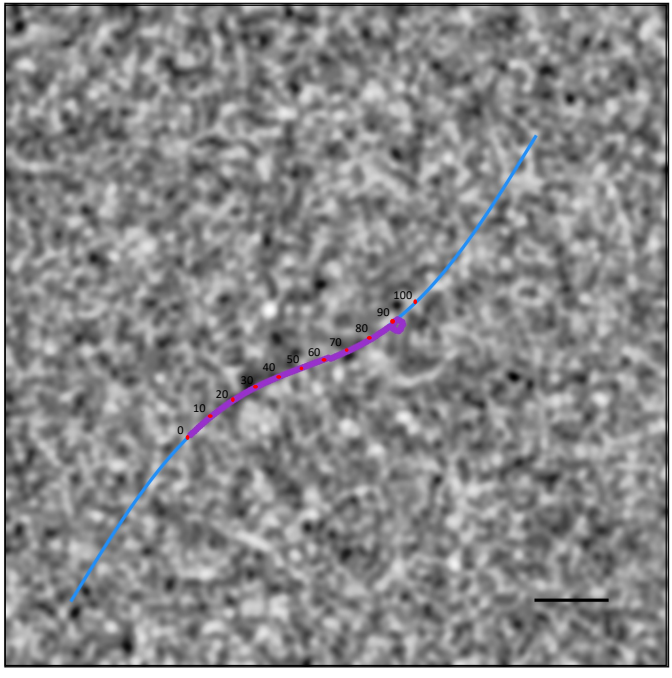


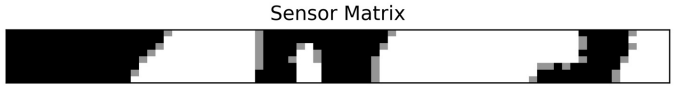



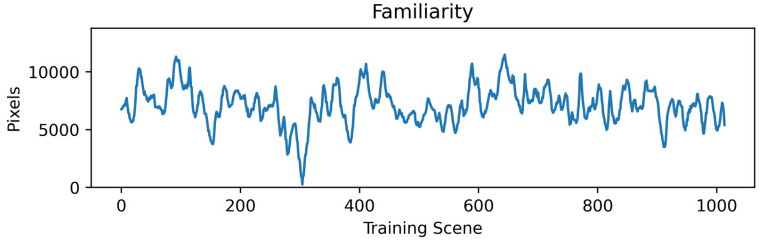

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

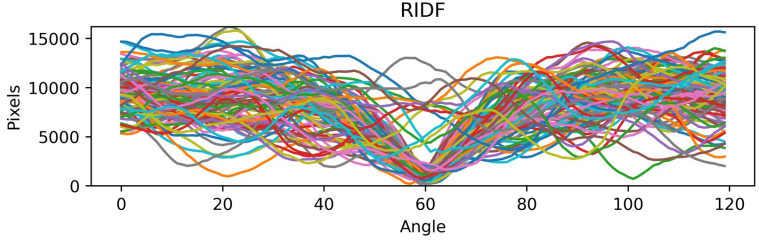
Navigation stats: RMSD error: 31.04; RMSD/dist: 0.078; TD: 6686; p90: 28; p50: 14; complete: 0

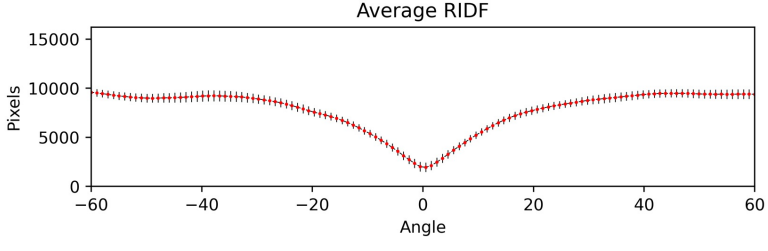
80%



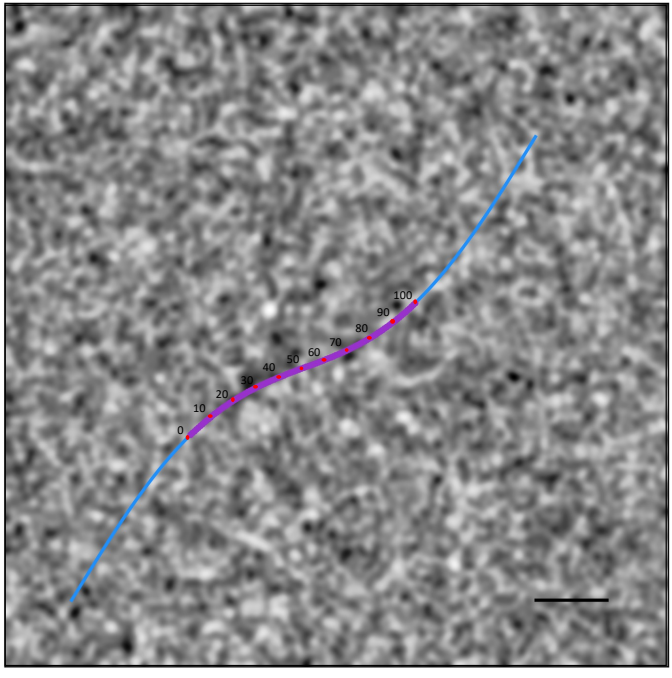



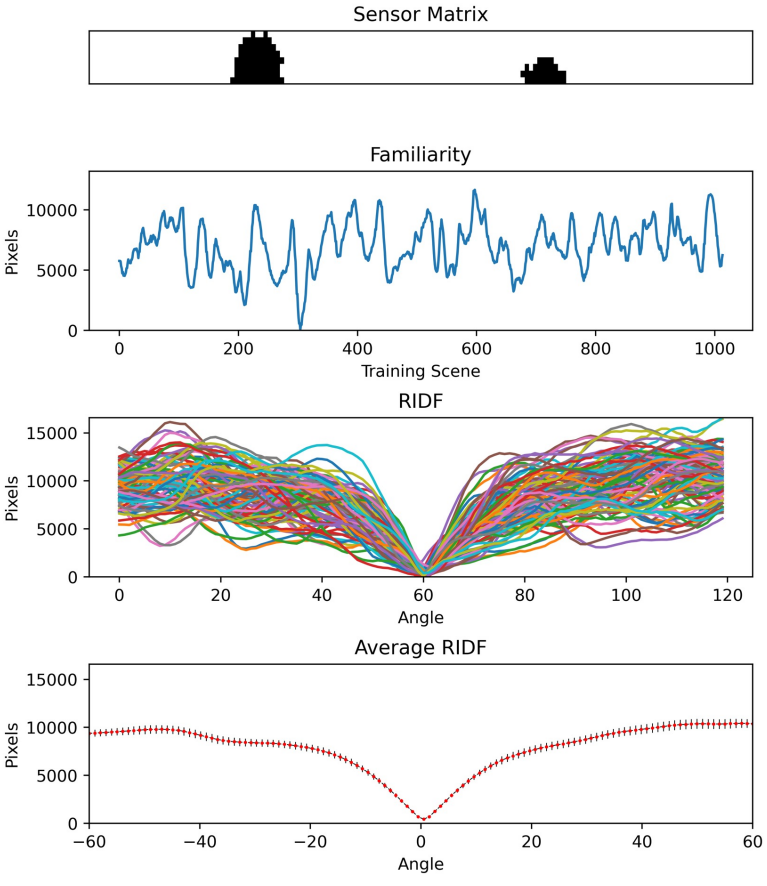




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 197.82; RMSD/dist: 0.495; TD: 5270; p90: 30; p50: 16; complete: 0

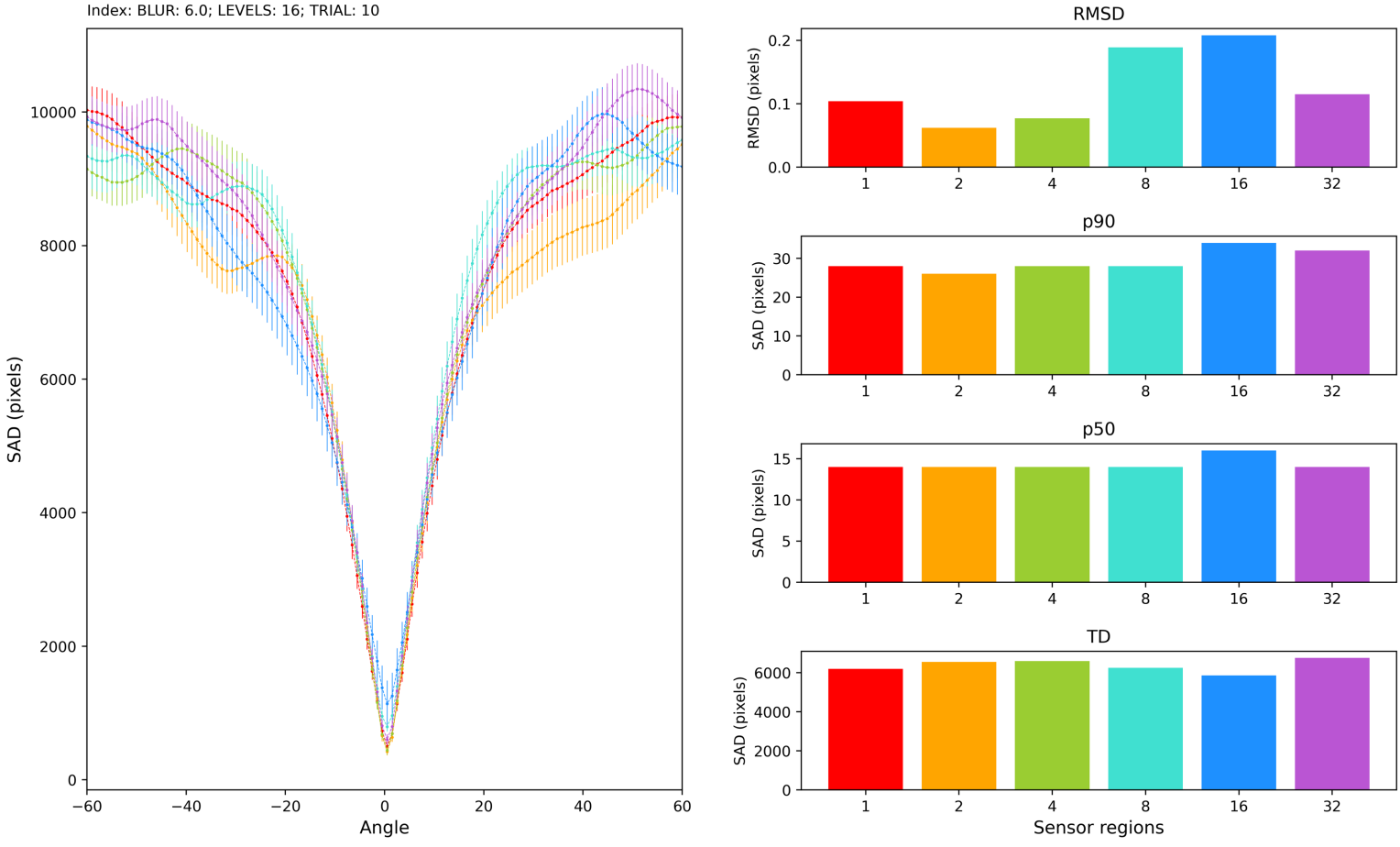
100%



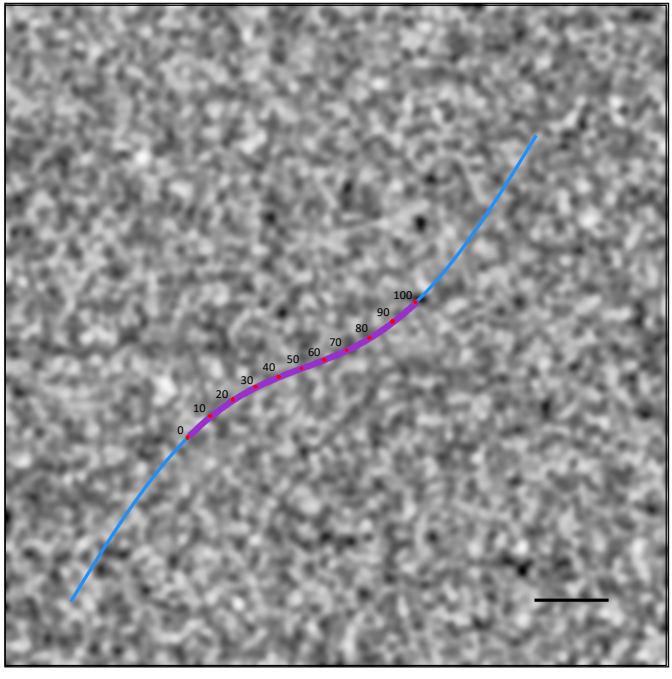



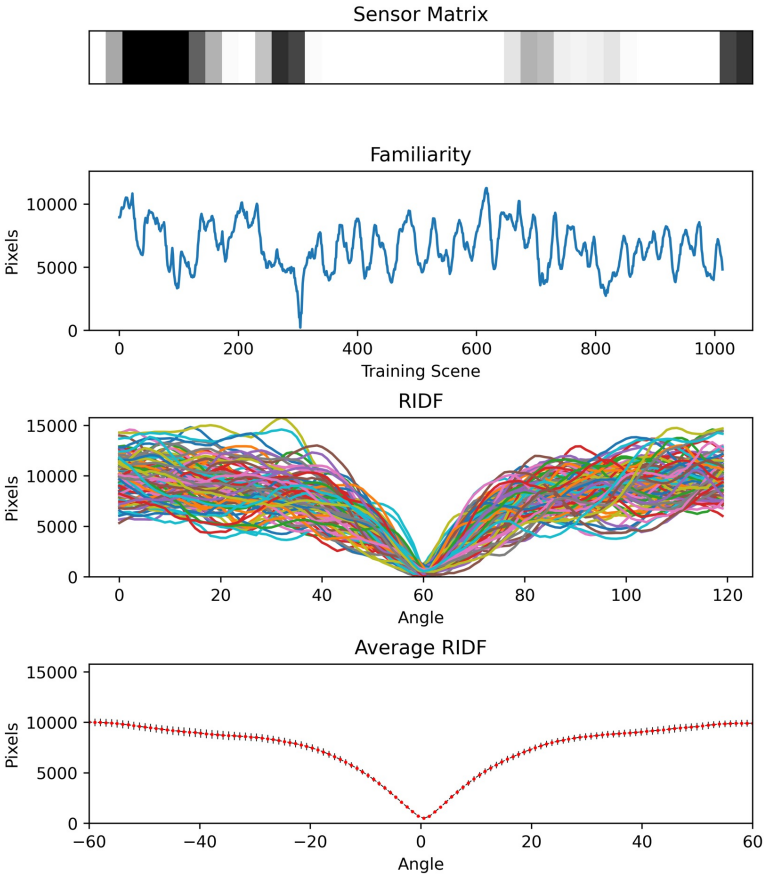

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 23.20; RMSD/dist: 0.058; TD: 6682; p90: 26; p50: 14; complete: 0


Index: BLUR: 6.0; LEVELS: 16; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

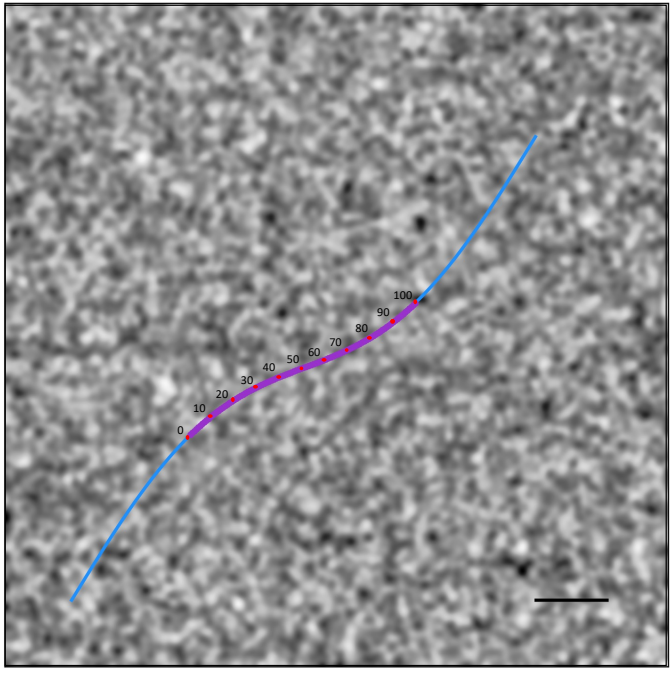


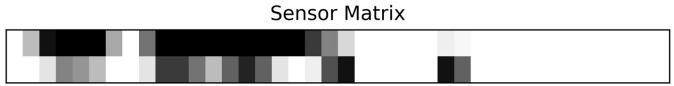



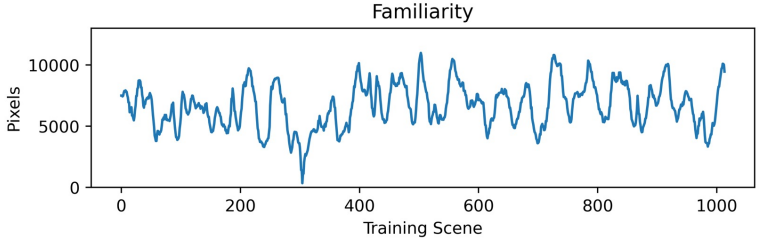

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

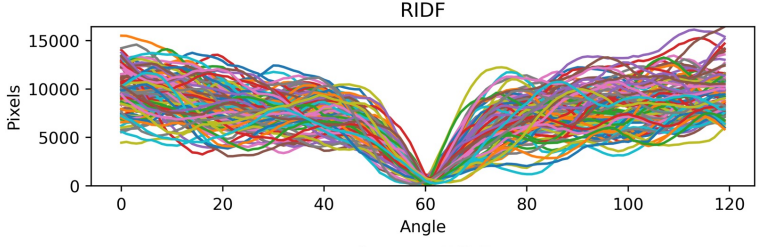
Navigation stats: RMSD error: 41.63; RMSD/dist: 0.104; TD: 6188; p90: 28; p50: 14; complete: 0

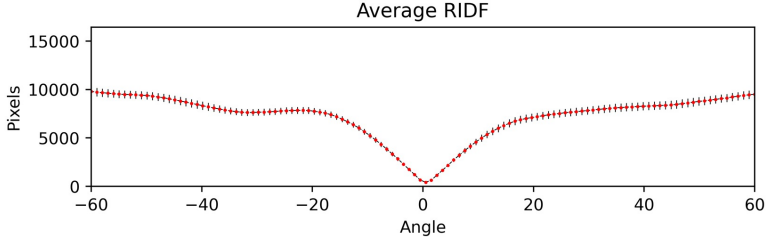
100%



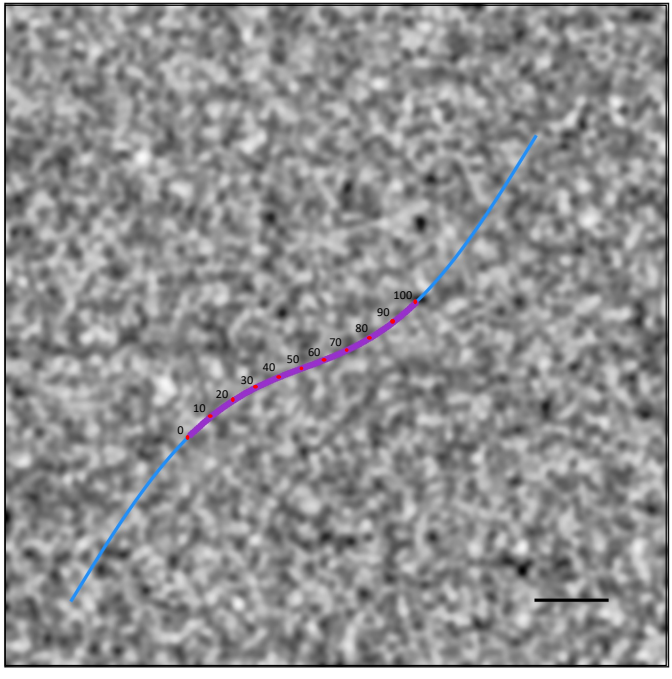



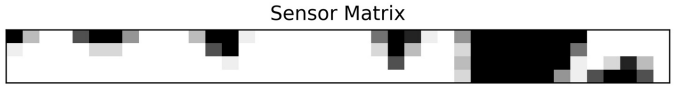



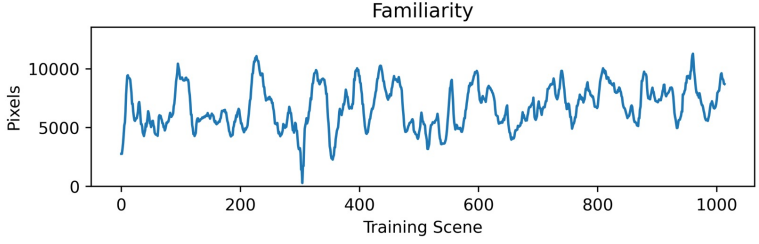

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

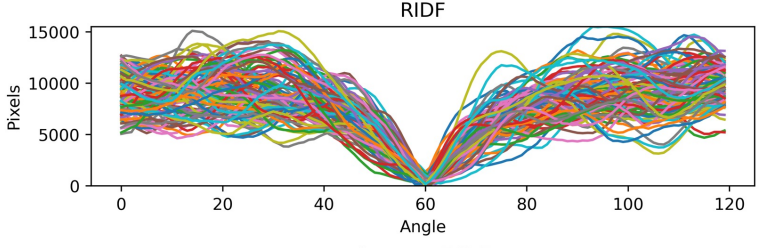
Navigation stats: RMSD error: 24.64; RMSD/dist: 0.062; TD: 6553; p90: 26; p50: 14; complete: 0

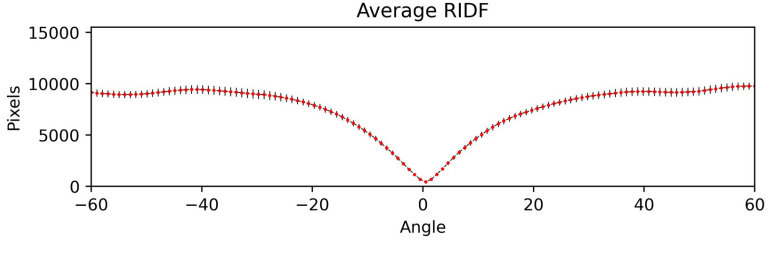
100%



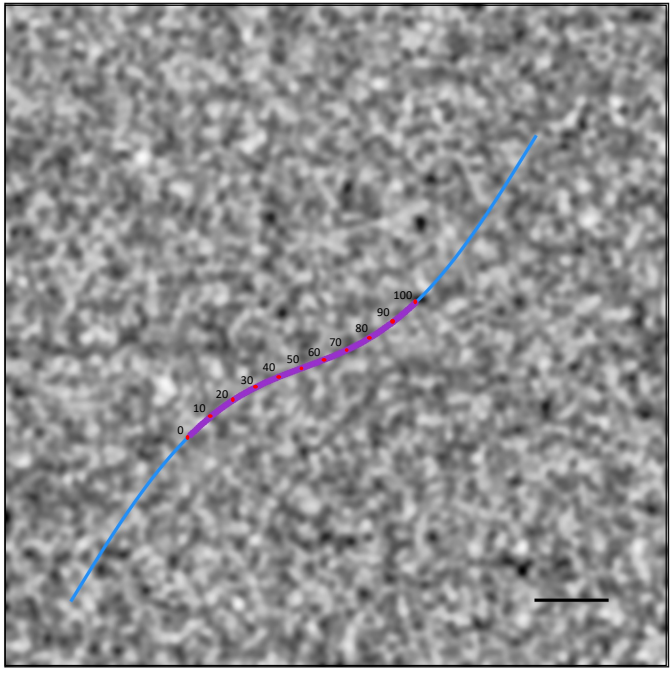



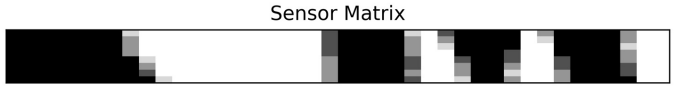



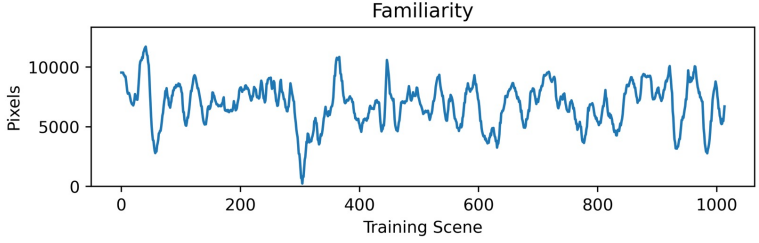

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

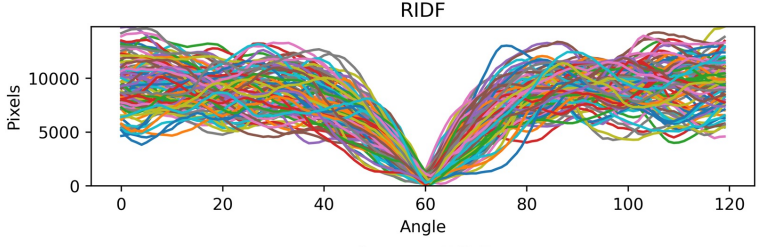
Navigation stats: RMSD error: 30.67; RMSD/dist: 0.077; TD: 6598; p90: 28; p50: 14; complete: 0

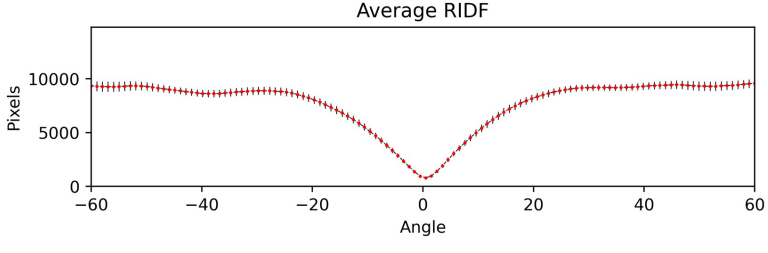
100%



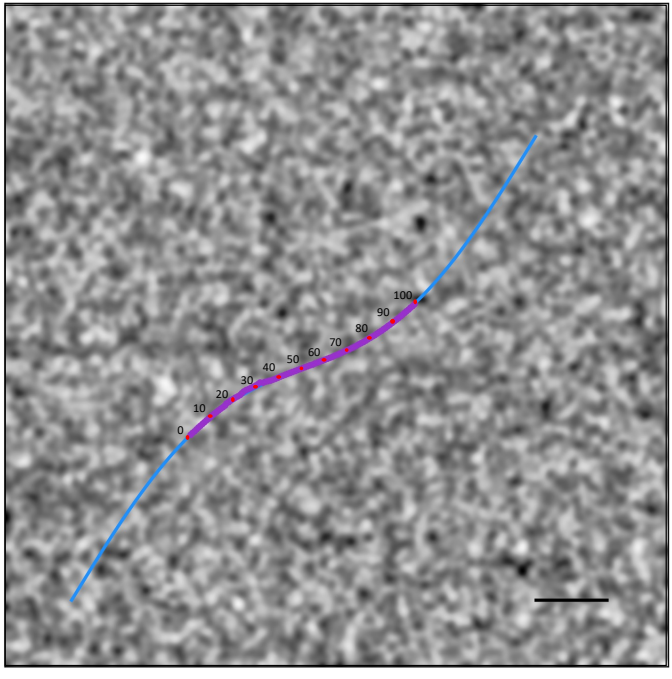



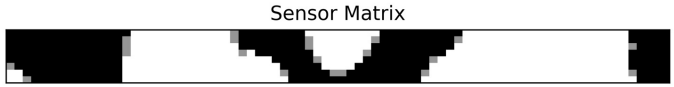



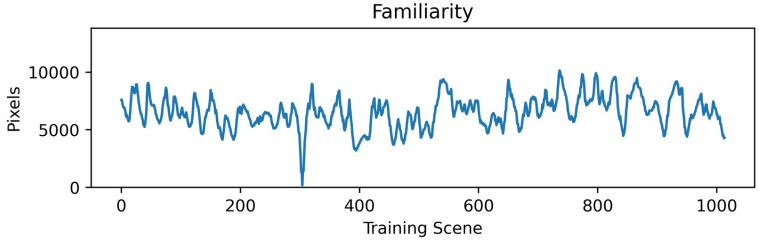

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

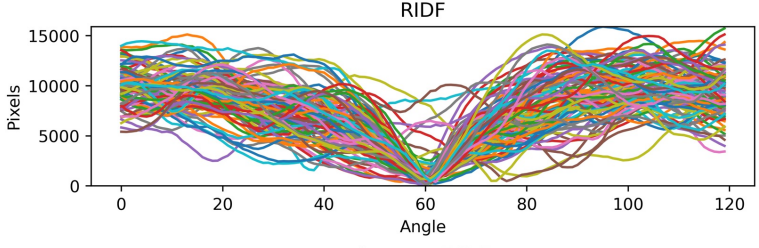
Navigation stats: RMSD error: 75.76; RMSD/dist: 0.189; TD: 6244; p90: 28; p50: 14; complete: 0

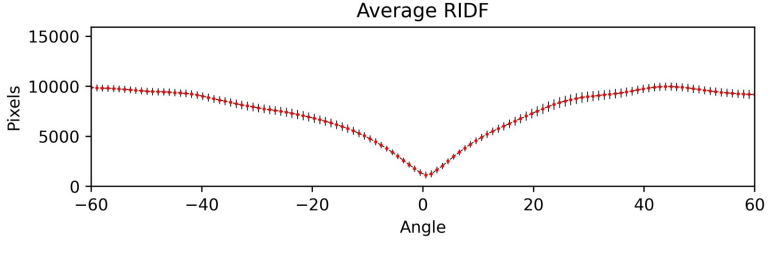
90%



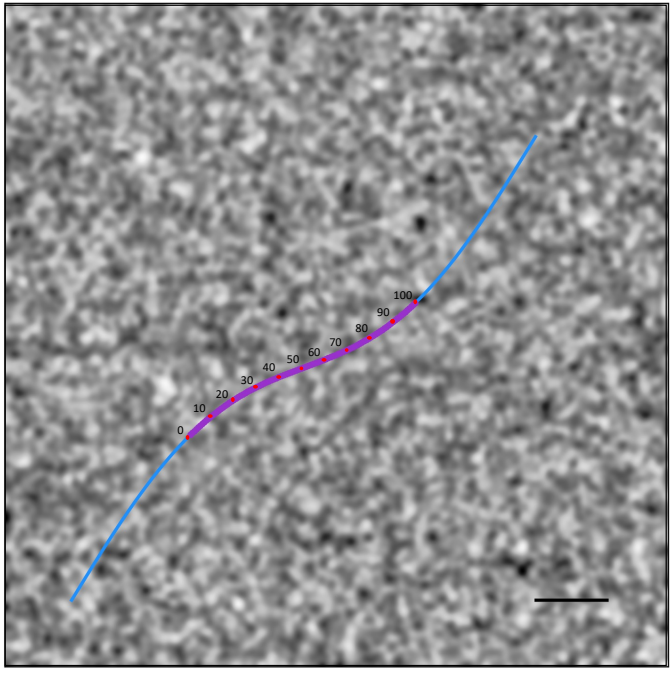



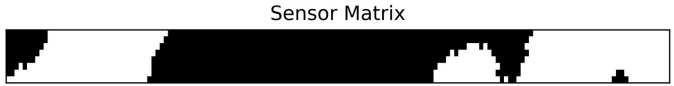



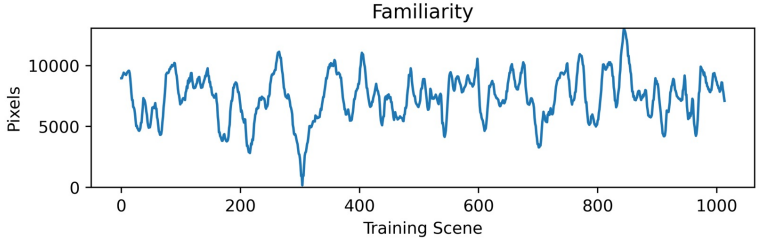

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

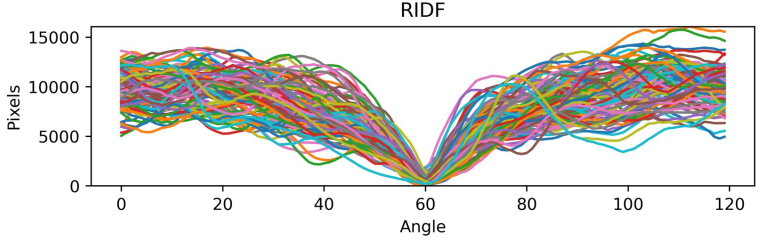
Navigation stats: RMSD error: 83.12; RMSD/dist: 0.208; TD: 5856; p90: 34; p50: 16; complete: 0

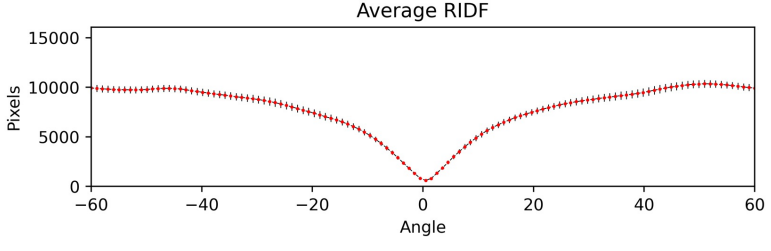
100%




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 46.04; RMSD/dist: 0.115; TD: 6750; p90: 32; p50: 14; complete: 0