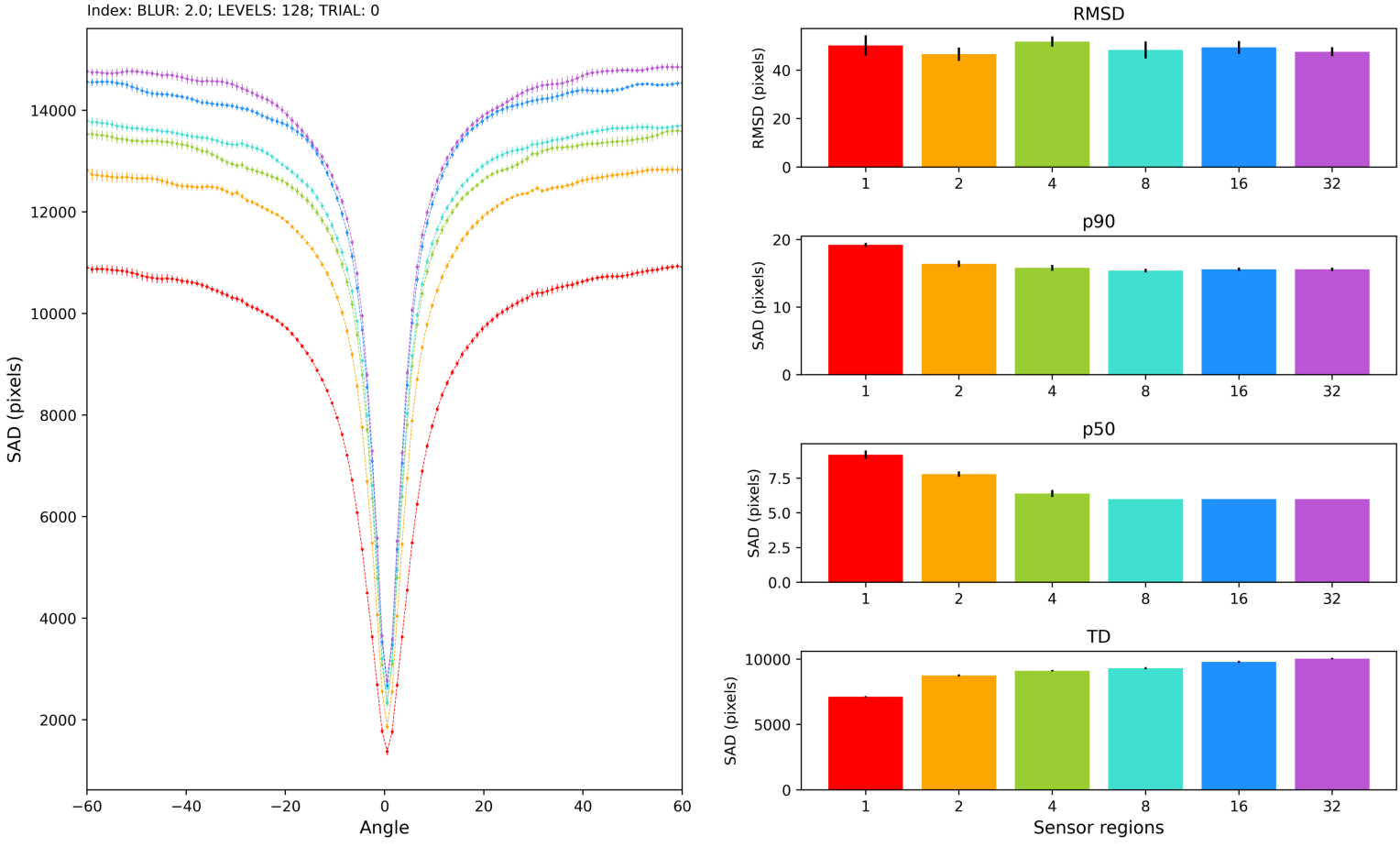
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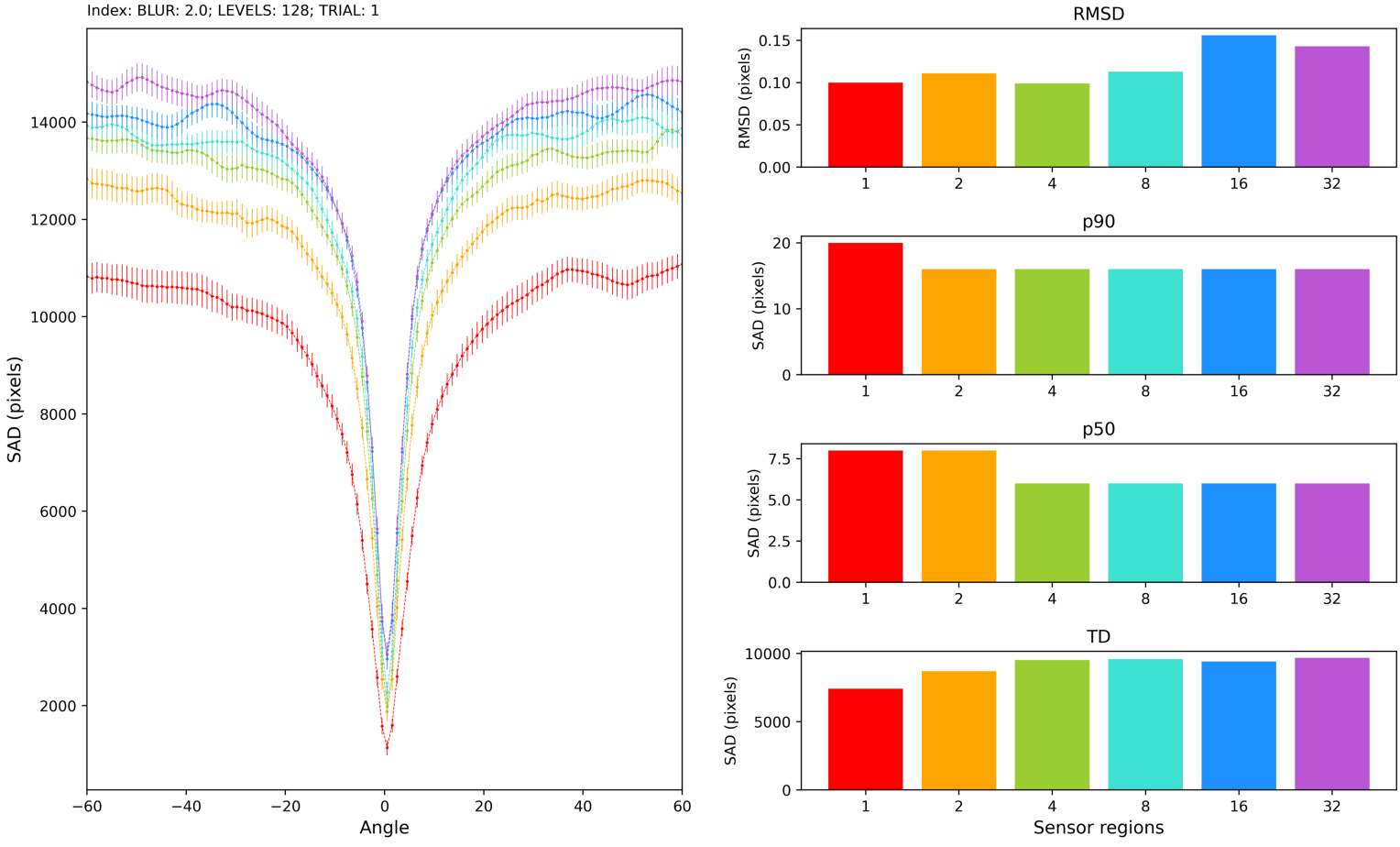
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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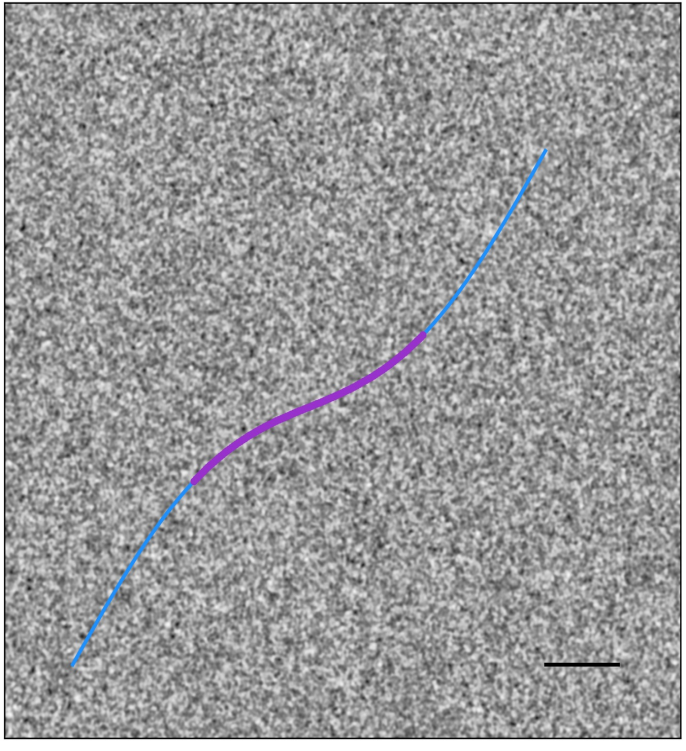
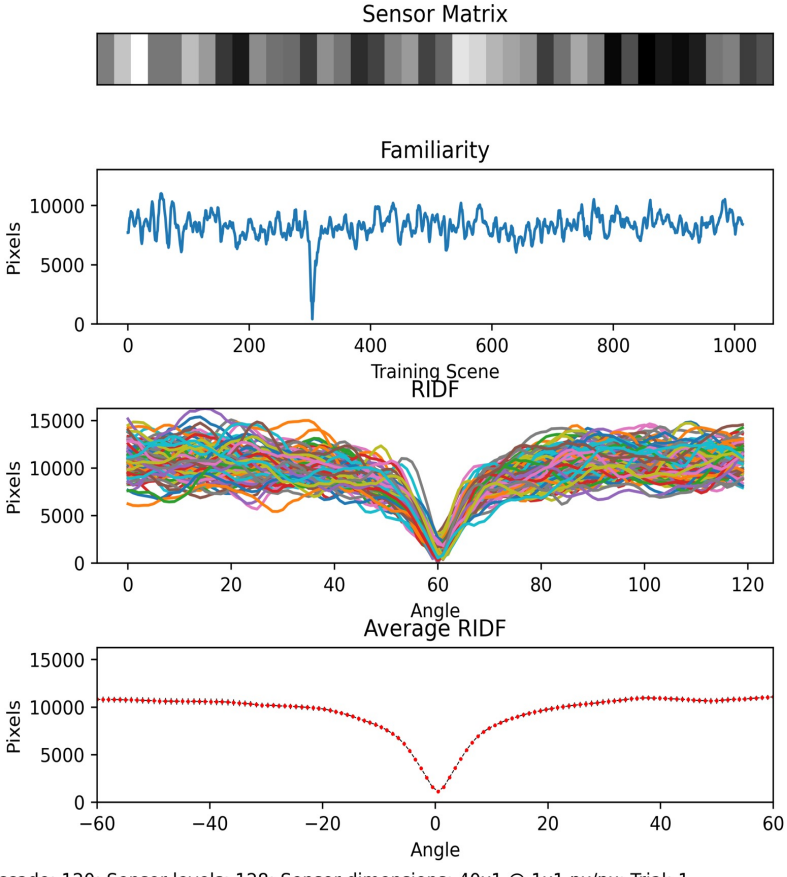
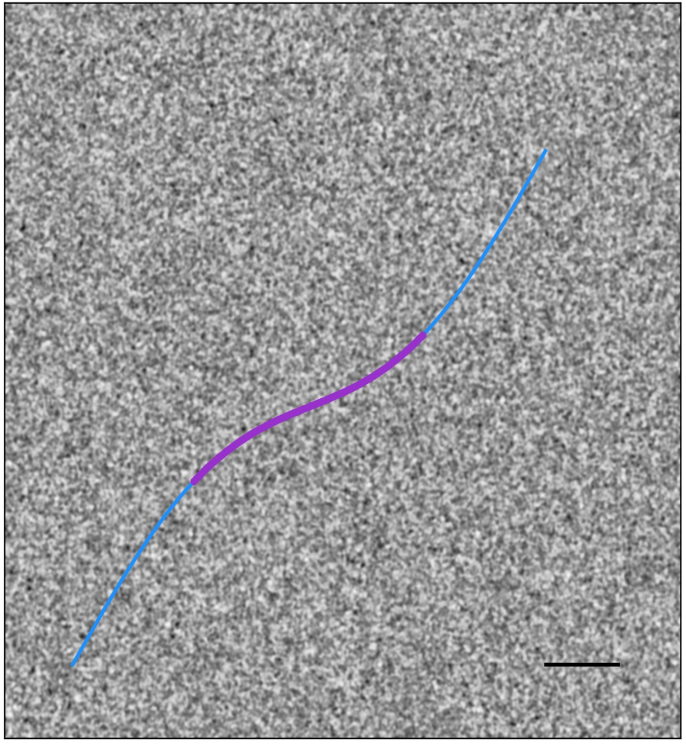
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

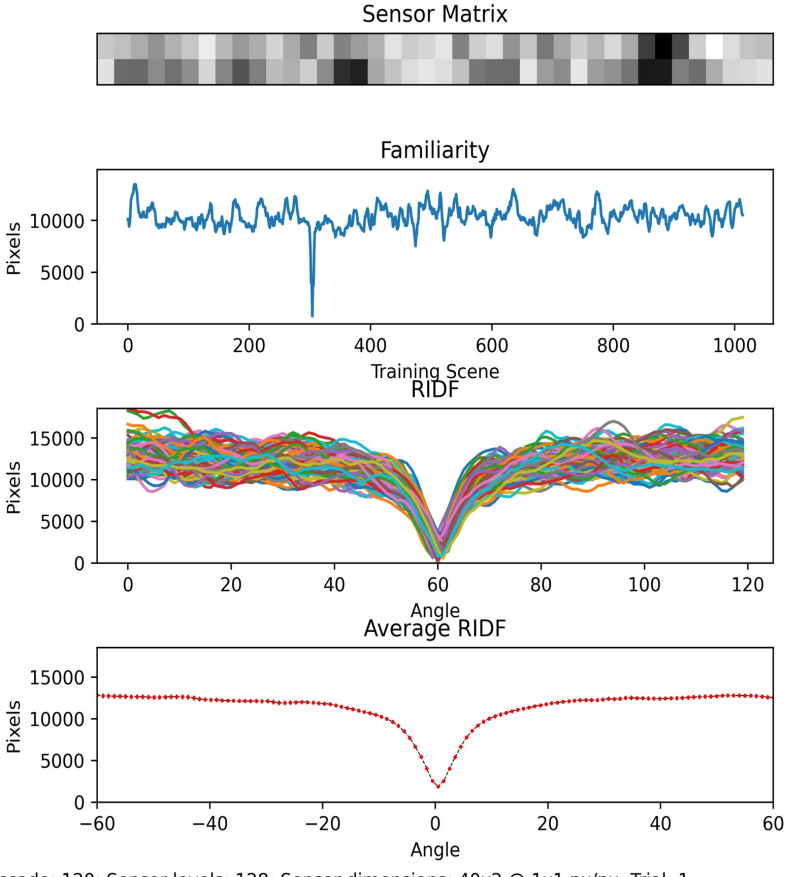




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

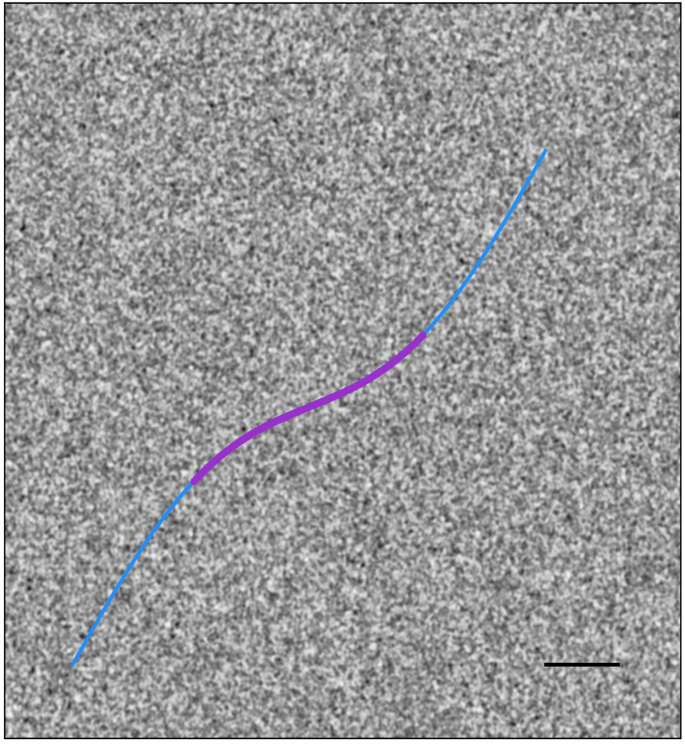
Navigation stats: RMSD error: 39.95; RMSD/dist: 0.100; TD: 7407; p90: 20; p50: 8; complete: 0

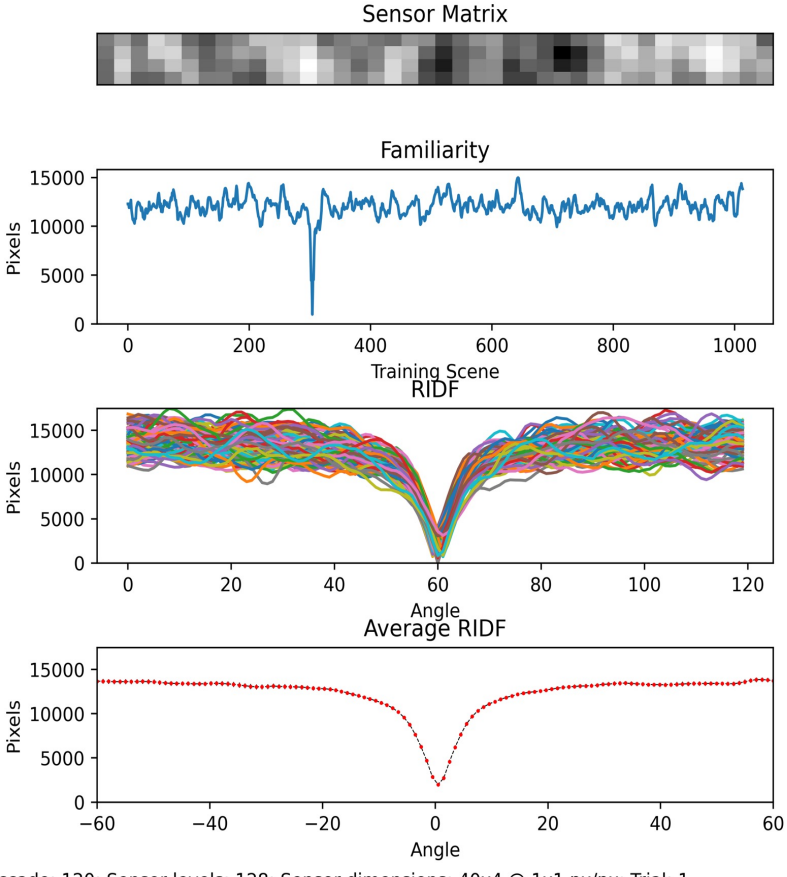




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

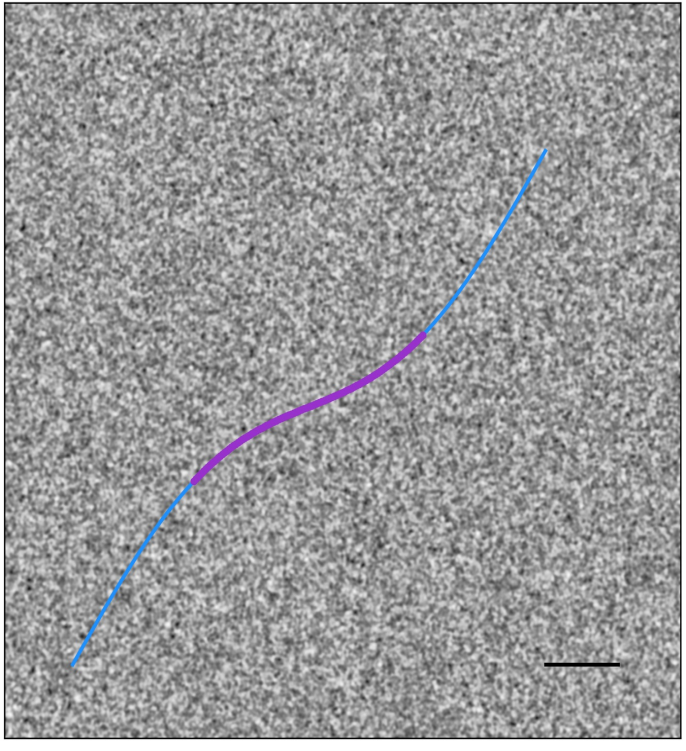
Navigation stats: RMSD error: 44.29; RMSD/dist: 0.111; TD: 8693; p90: 16; p50: 8; complete: 0

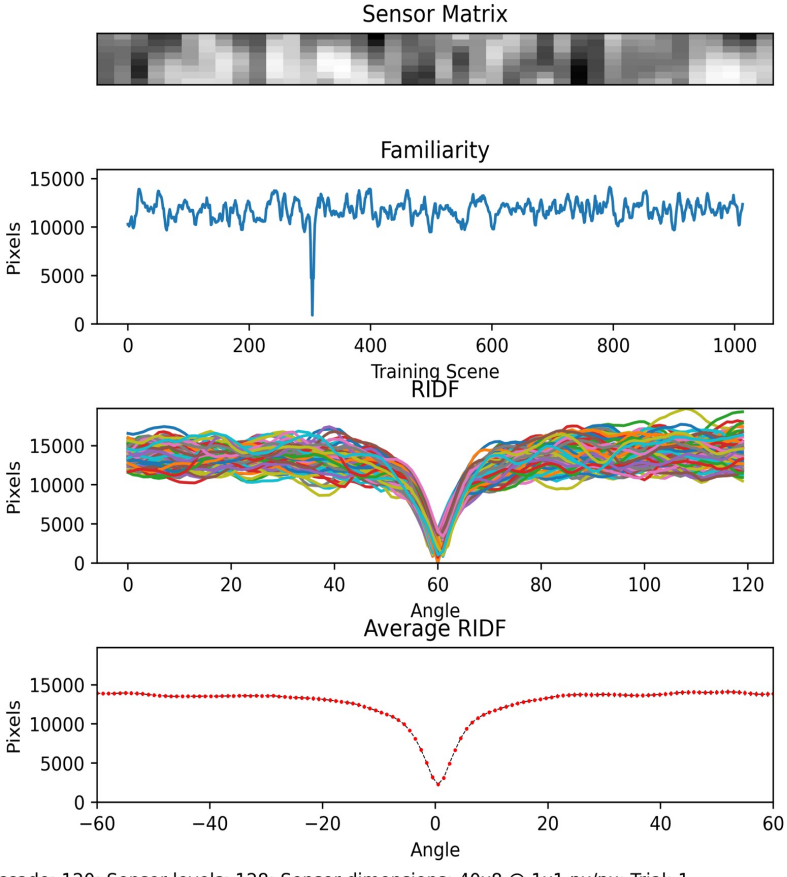




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

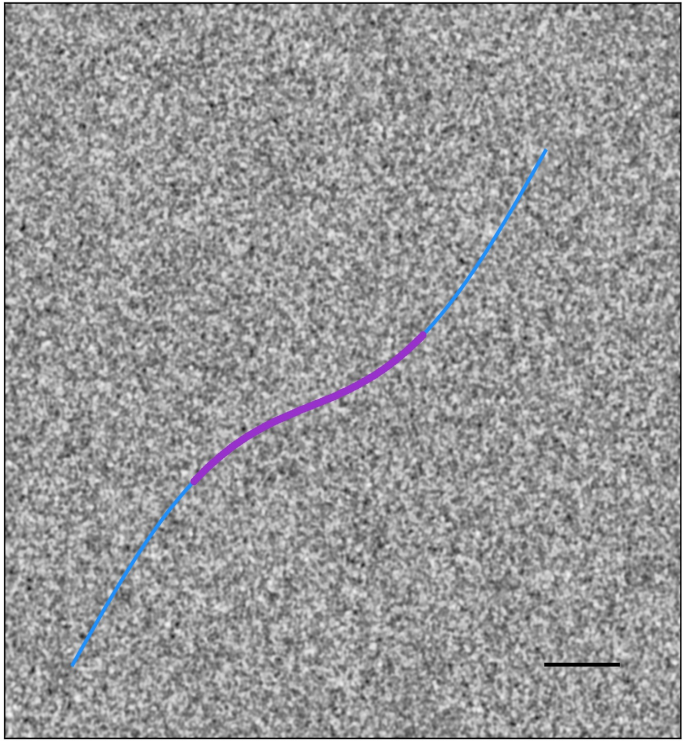
Navigation stats: RMSD error: 39.73; RMSD/dist: 0.099; TD: 9516; p90: 16; p50: 6; complete: 0

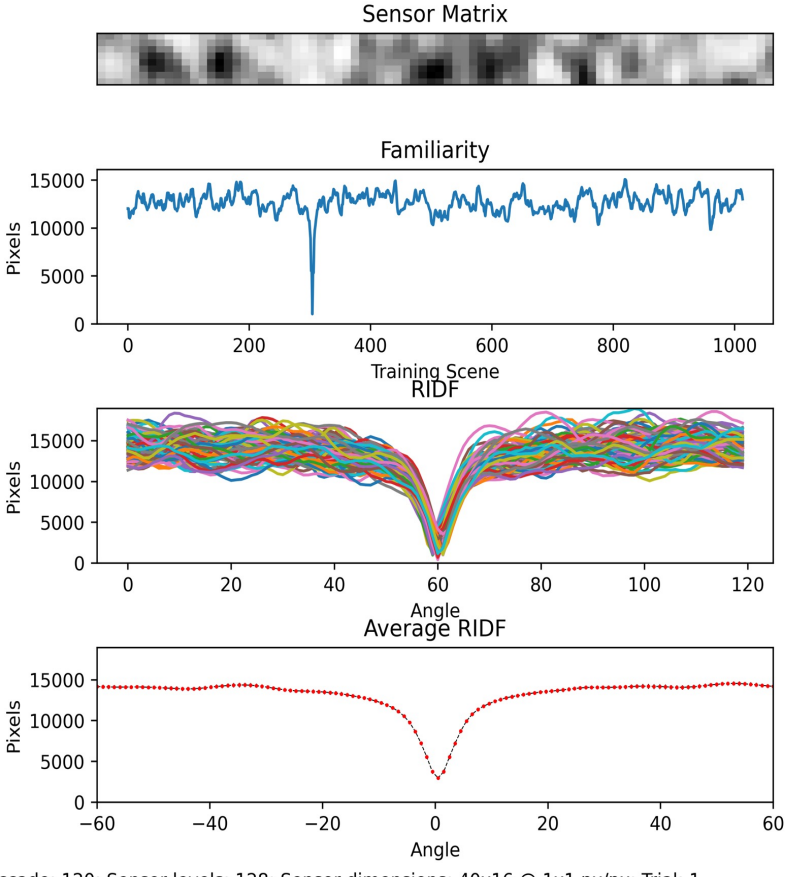




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

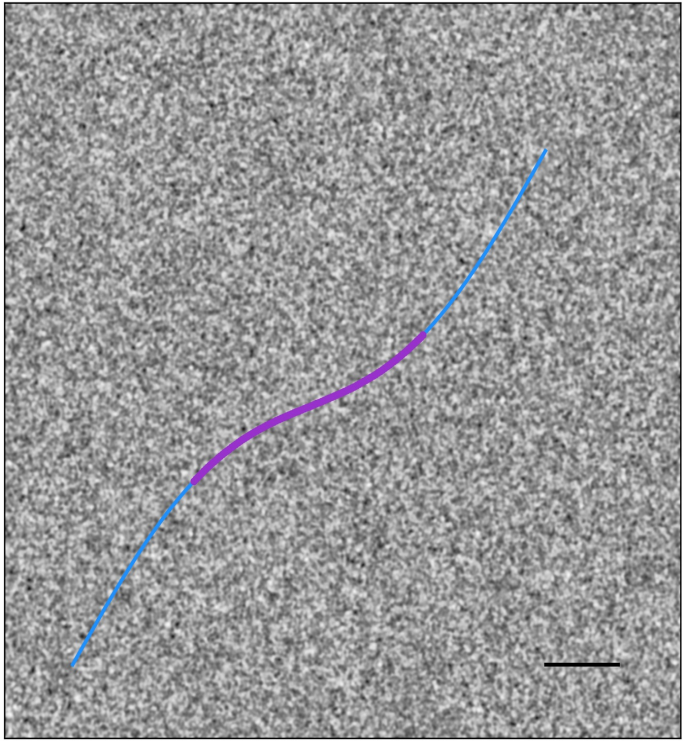
Navigation stats: RMSD error: 45.18; RMSD/dist: 0.113; TD: 9574; p90: 16; p50: 6; complete: 0

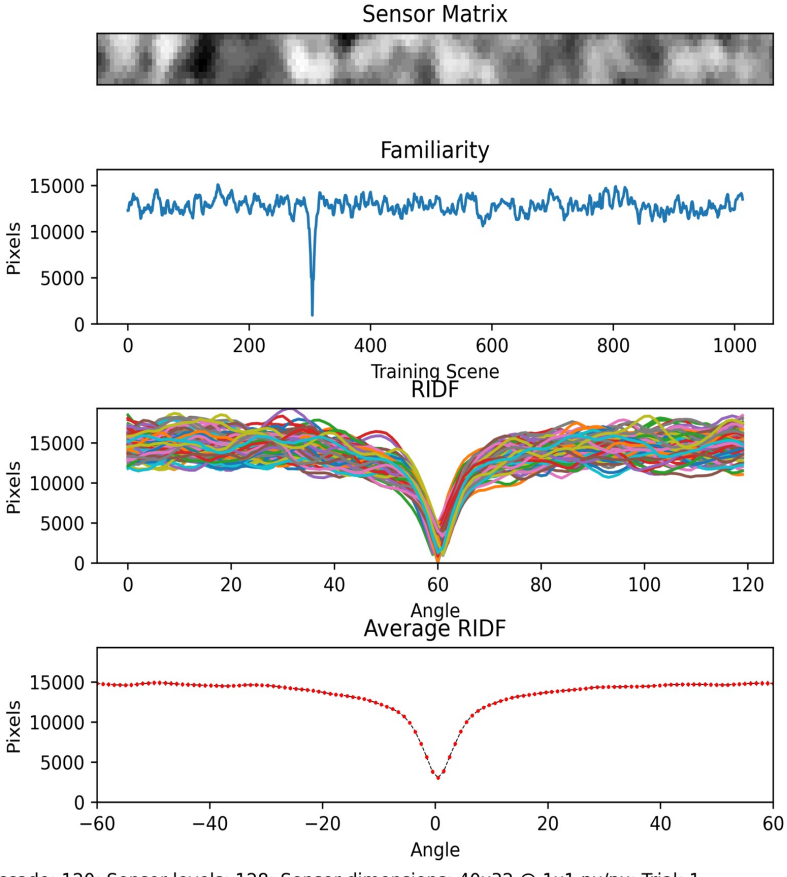




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

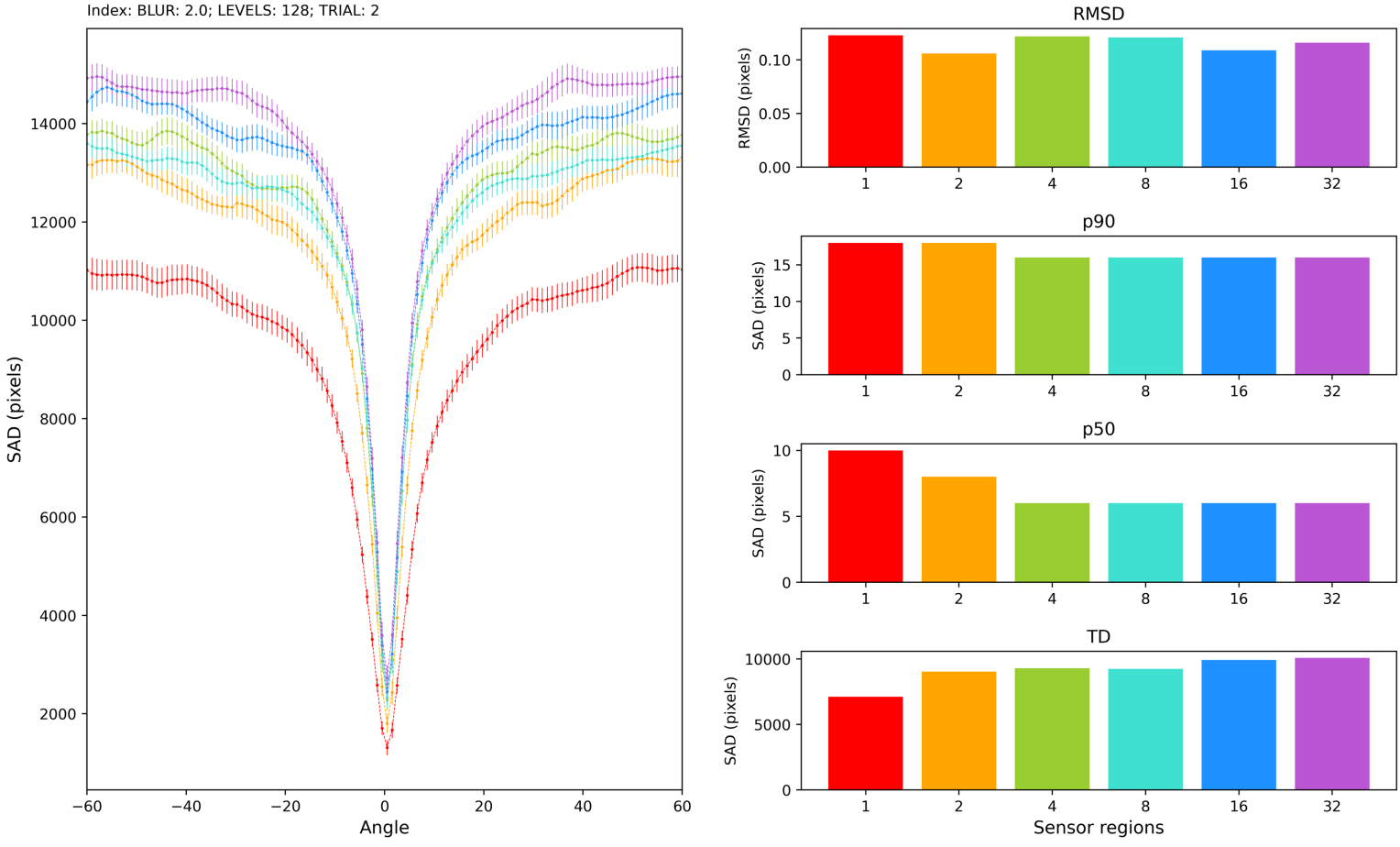
Navigation stats: RMSD error: 62.33; RMSD/dist: 0.156; TD: 9411; p90: 16; p50: 6; complete: 0

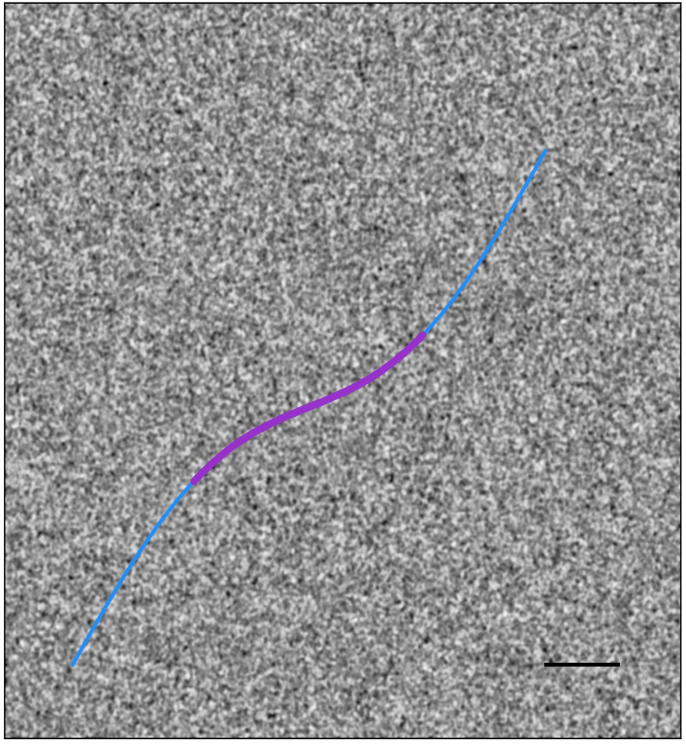


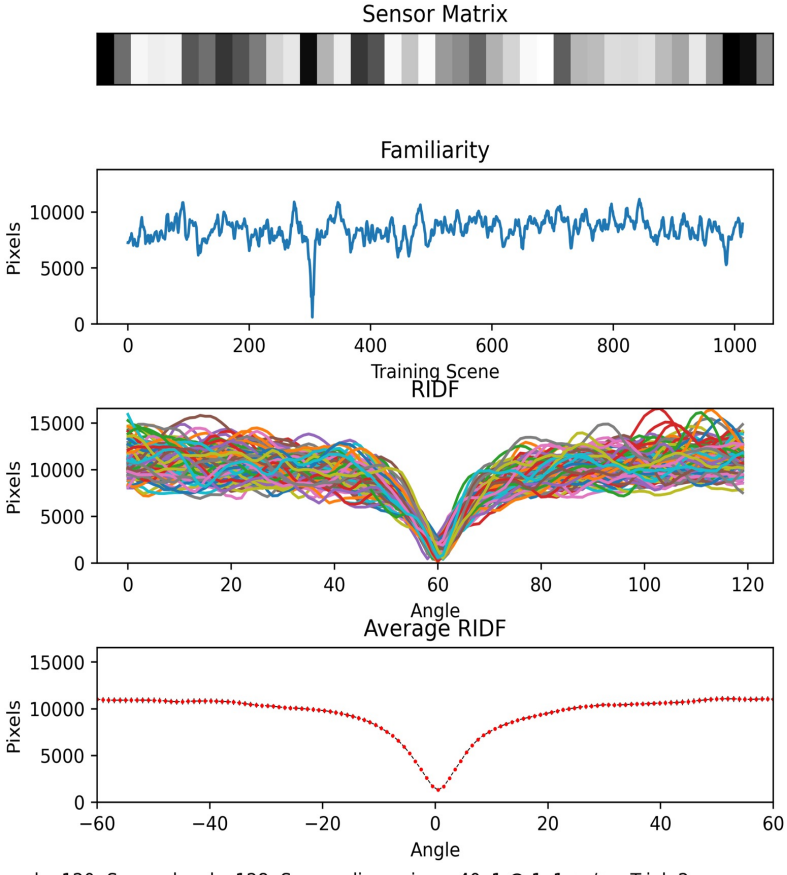


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 57.15; RMSD/dist: 0.143; TD: 9665; p90: 16; p50: 6; complete: 0

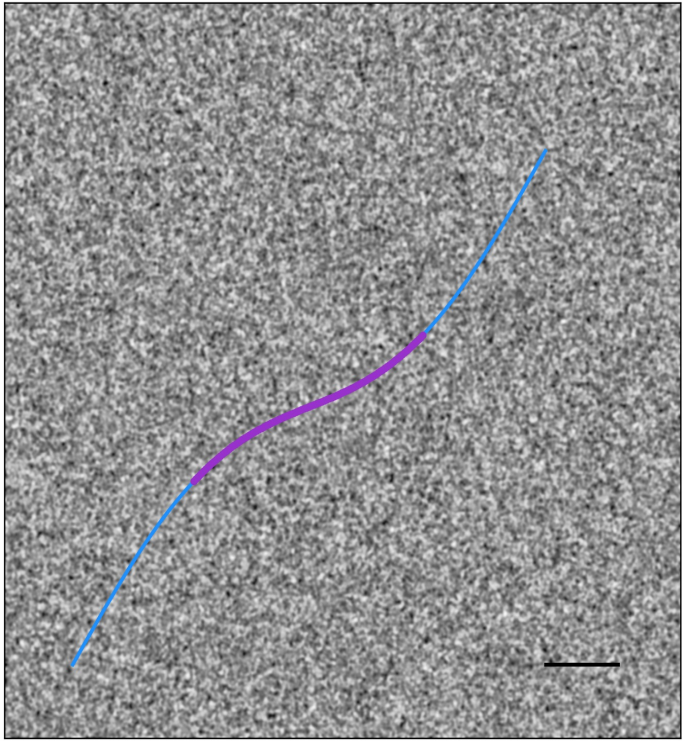

Index: BLUR: 2.0; LEVELS: 128; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

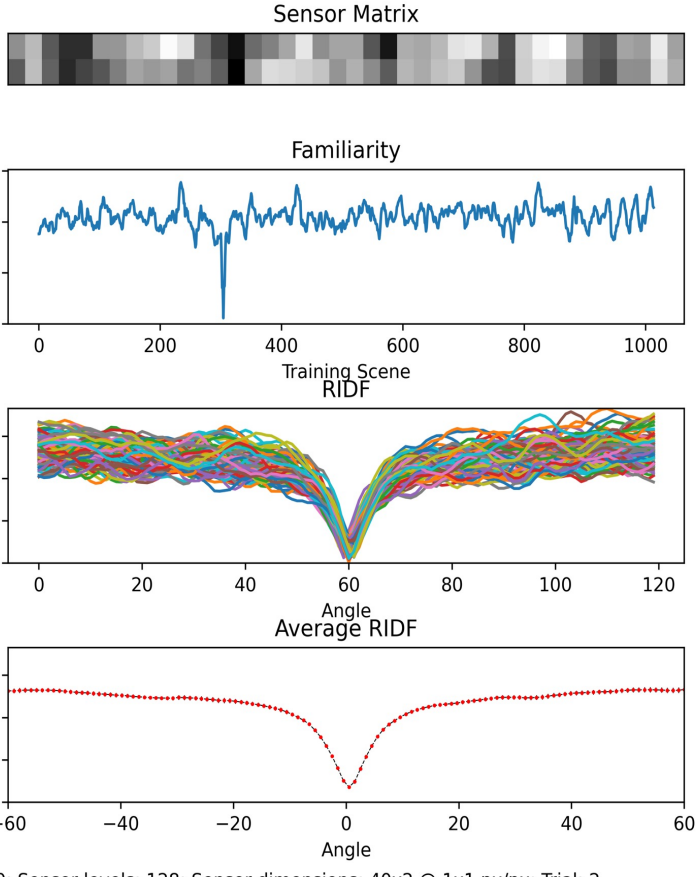




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

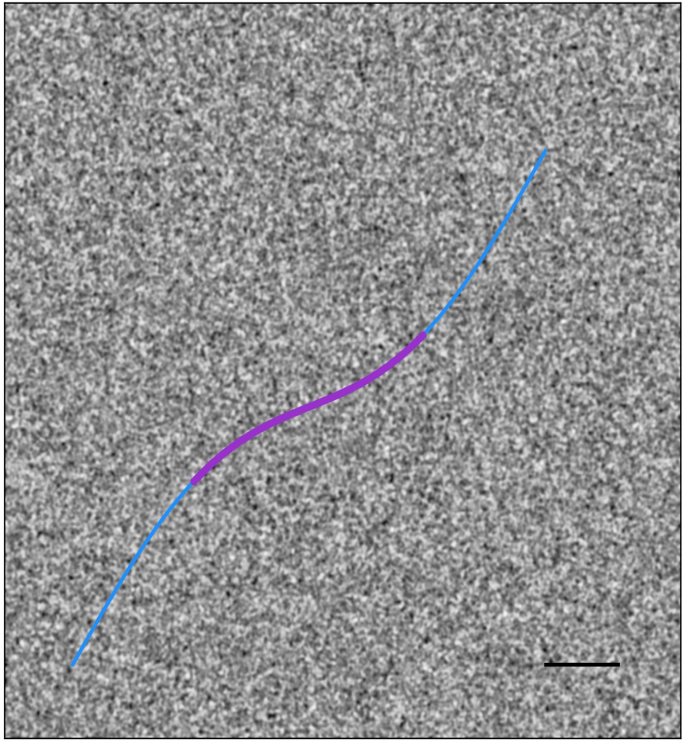
Navigation stats: RMSD error: 49.38; RMSD/dist: 0.123; TD: 7122; p90: 18; p50: 10; complete: 0

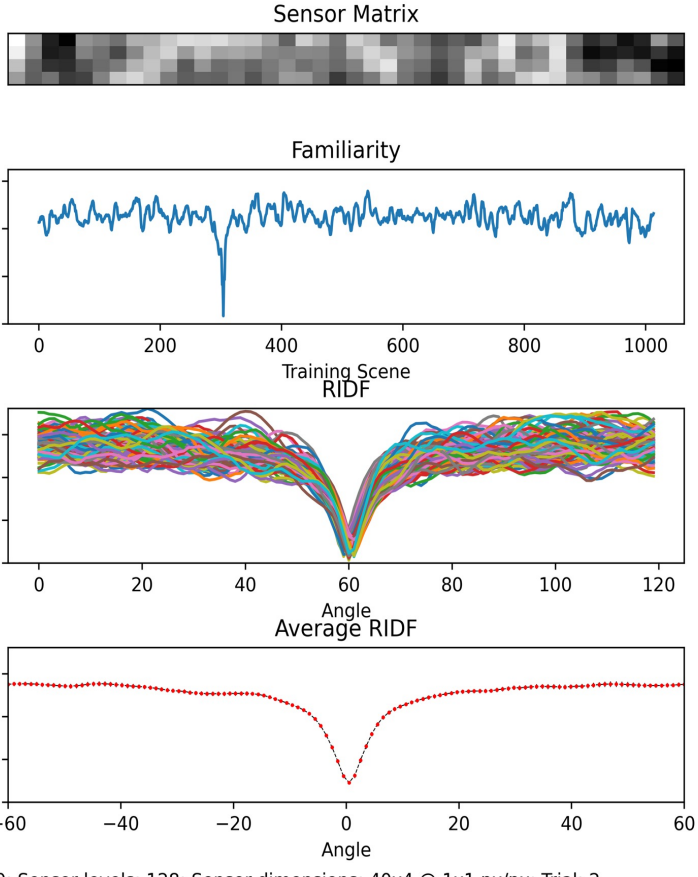




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

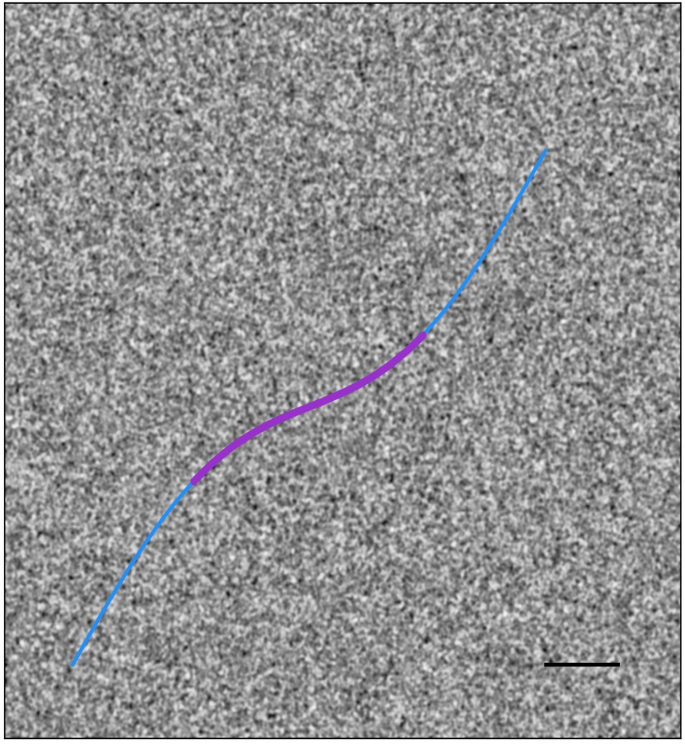
Navigation stats: RMSD error: 42.55; RMSD/dist: 0.106; TD: 9046; p90: 18; p50: 8; complete: 0

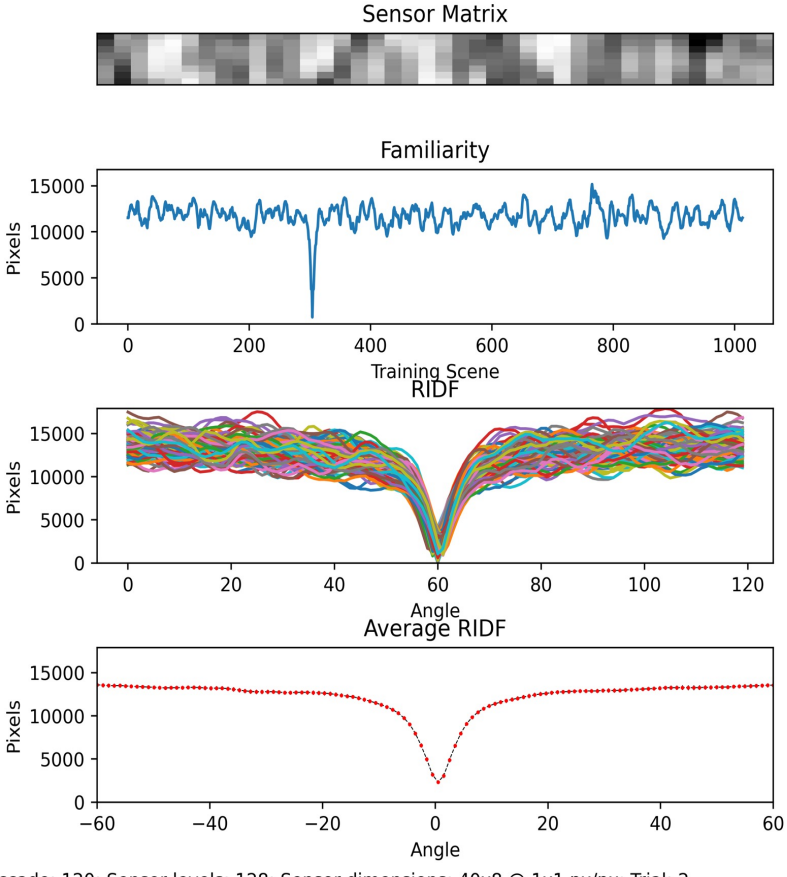




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

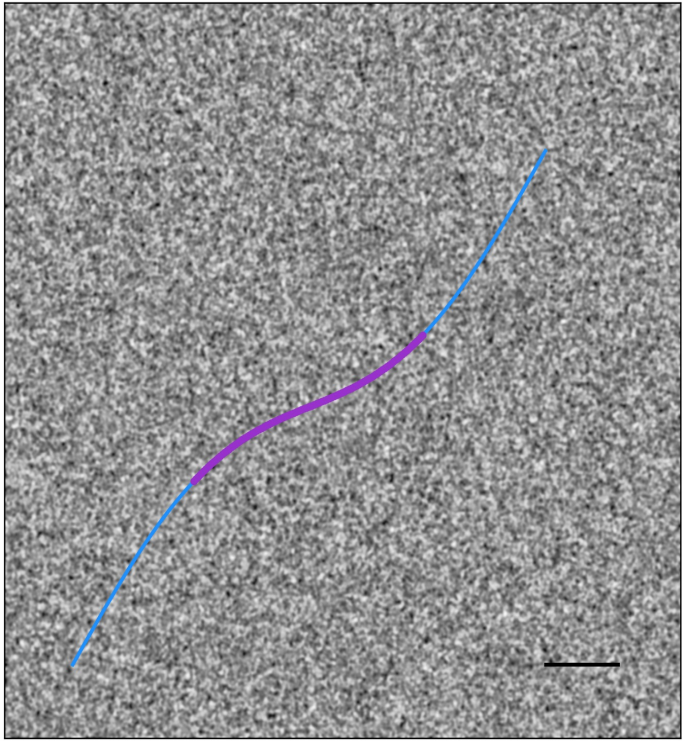
Navigation stats: RMSD error: 48.80; RMSD/dist: 0.122; TD: 9302; p90: 16; p50: 6; complete: 0

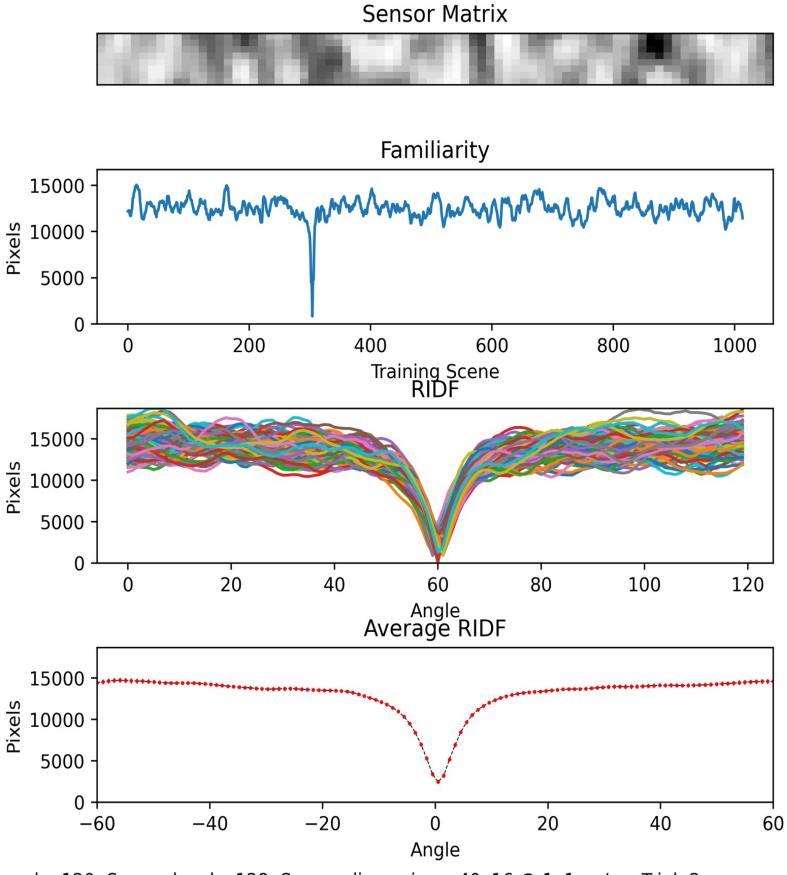




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

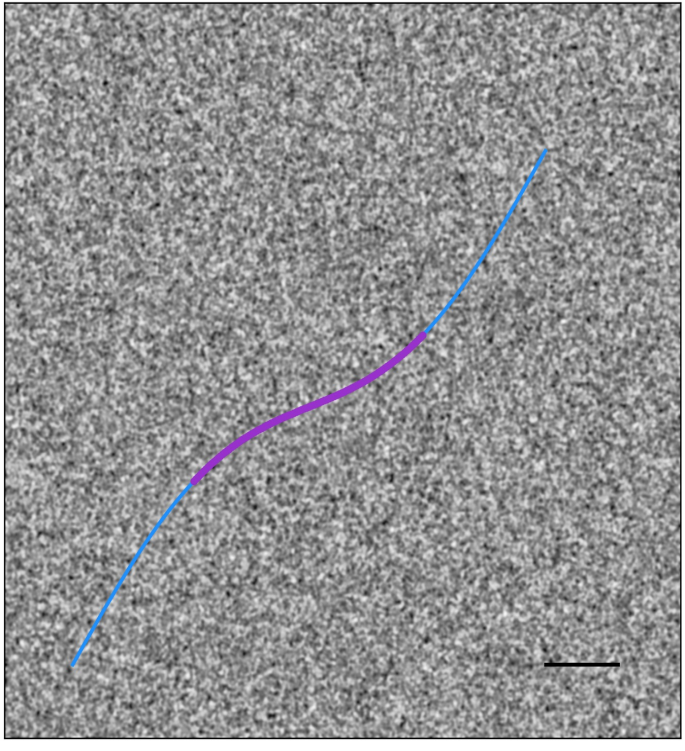
Navigation stats: RMSD error: 48.58; RMSD/dist: 0.121; TD: 9255; p90: 16; p50: 6; complete: 0

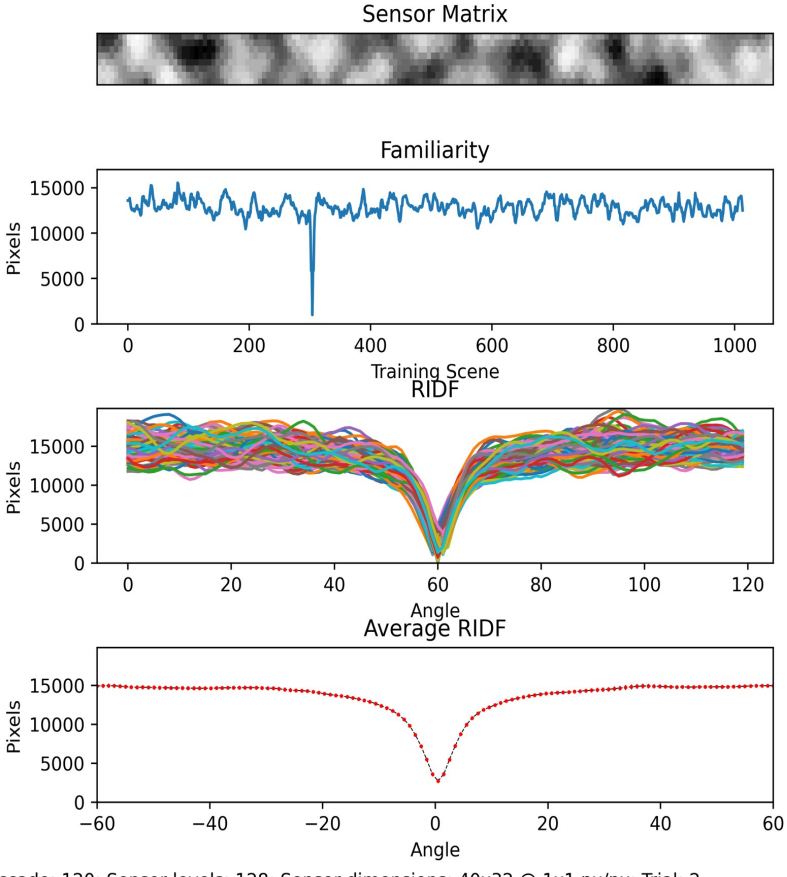




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

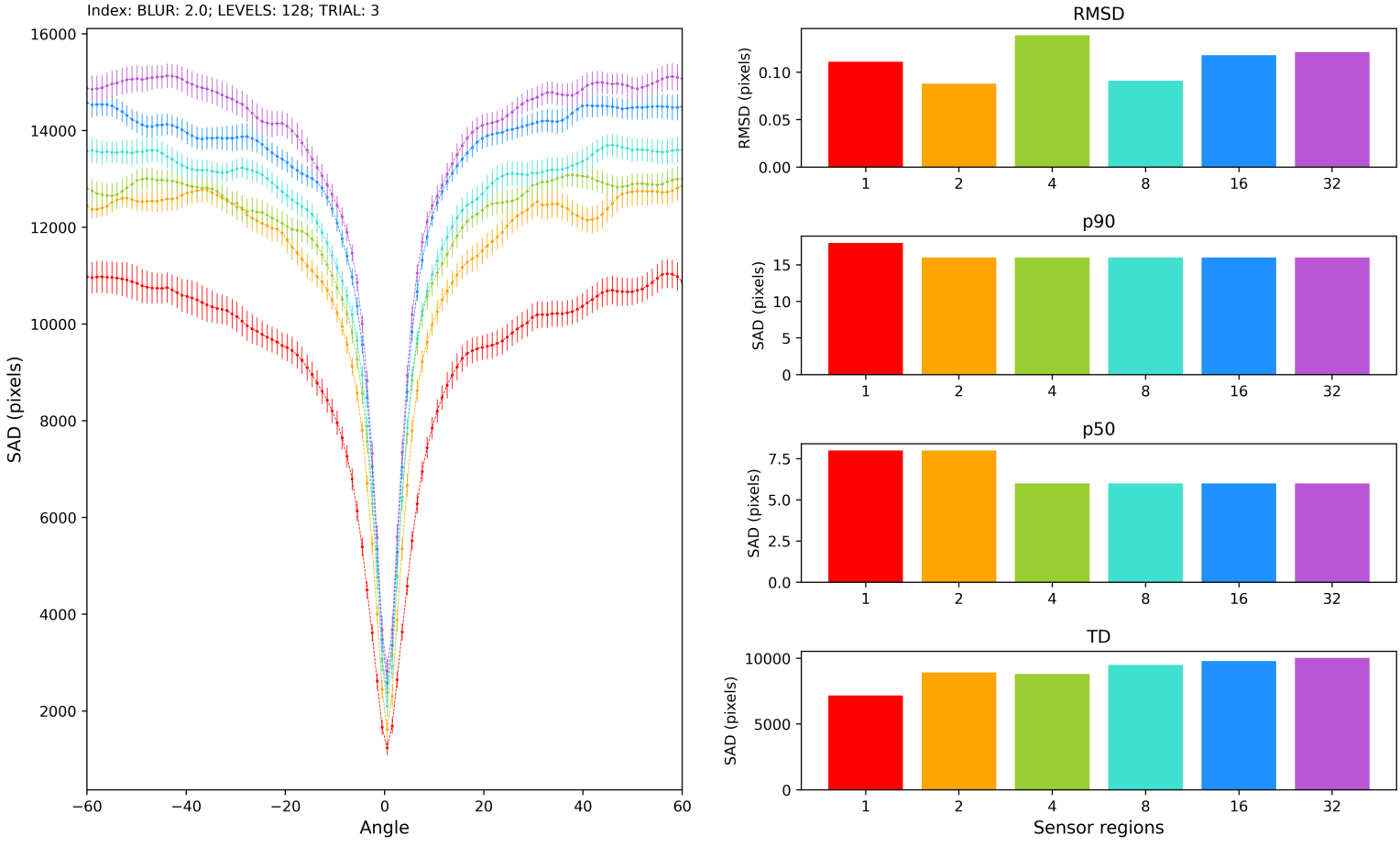
Navigation stats: RMSD error: 43.60; RMSD/dist: 0.109; TD: 9929; p90: 16; p50: 6; complete: 0

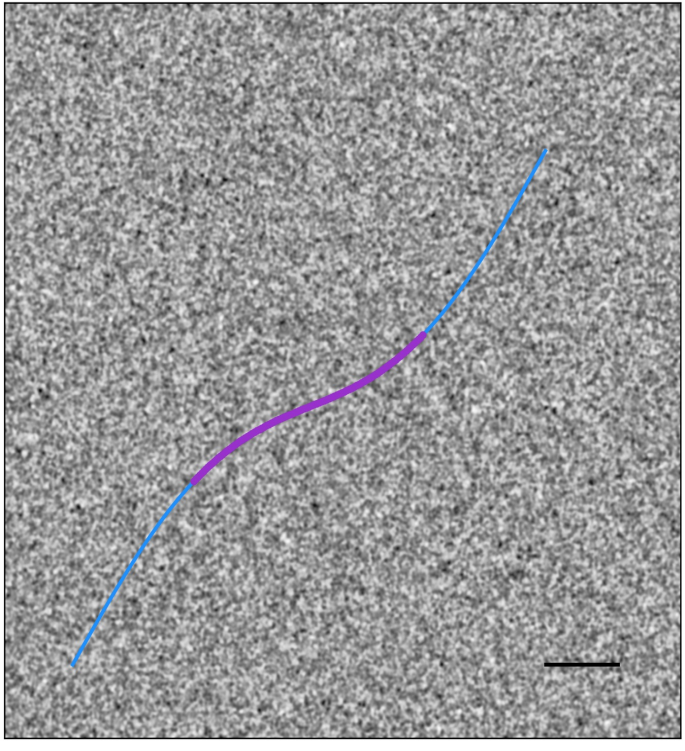


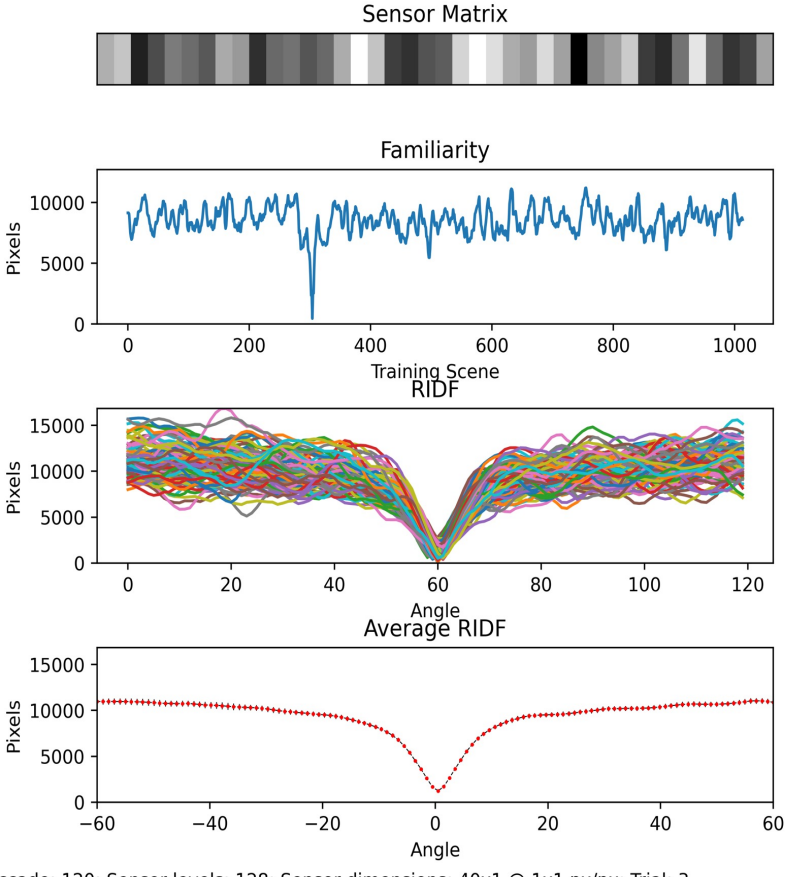


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 46.32; RMSD/dist: 0.116; TD: 10080; p90: 16; p50: 6; complete: 0

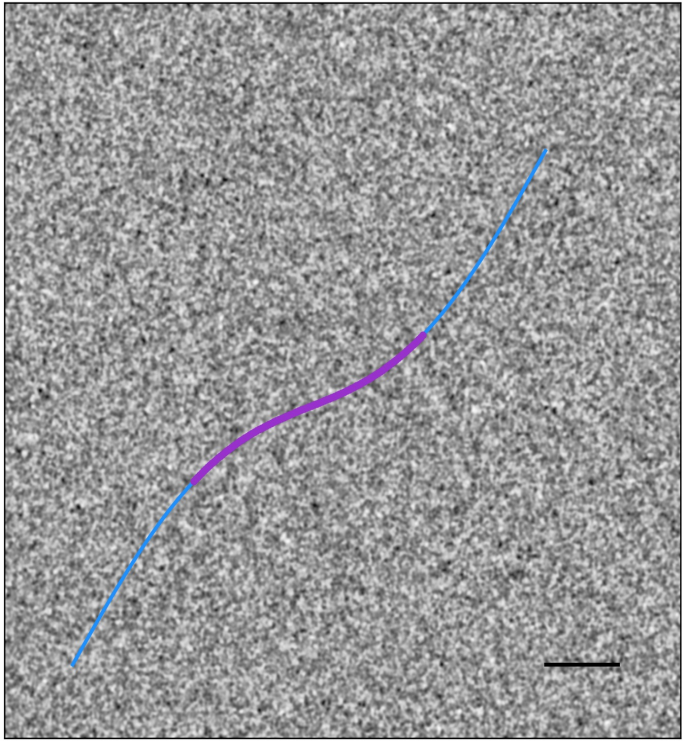

Index: BLUR: 2.0; LEVELS: 128; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

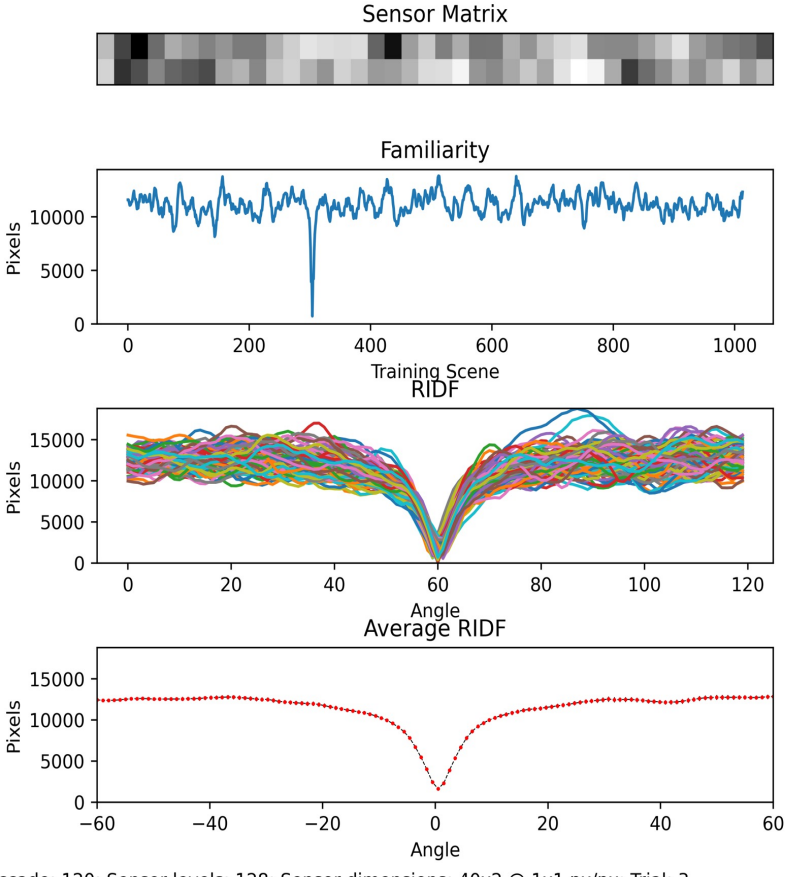




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

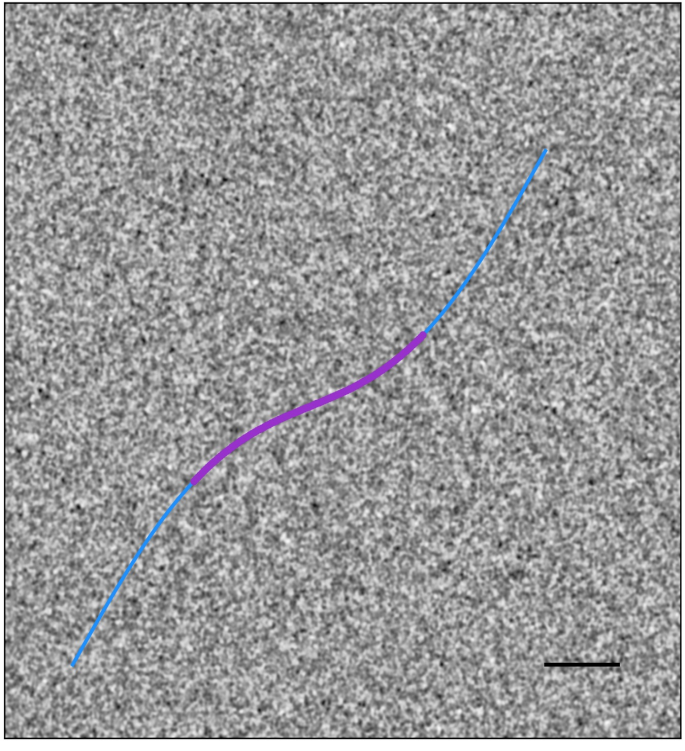
Navigation stats: RMSD error: 44.29; RMSD/dist: 0.111; TD: 7177; p90: 18; p50: 8; complete: 0

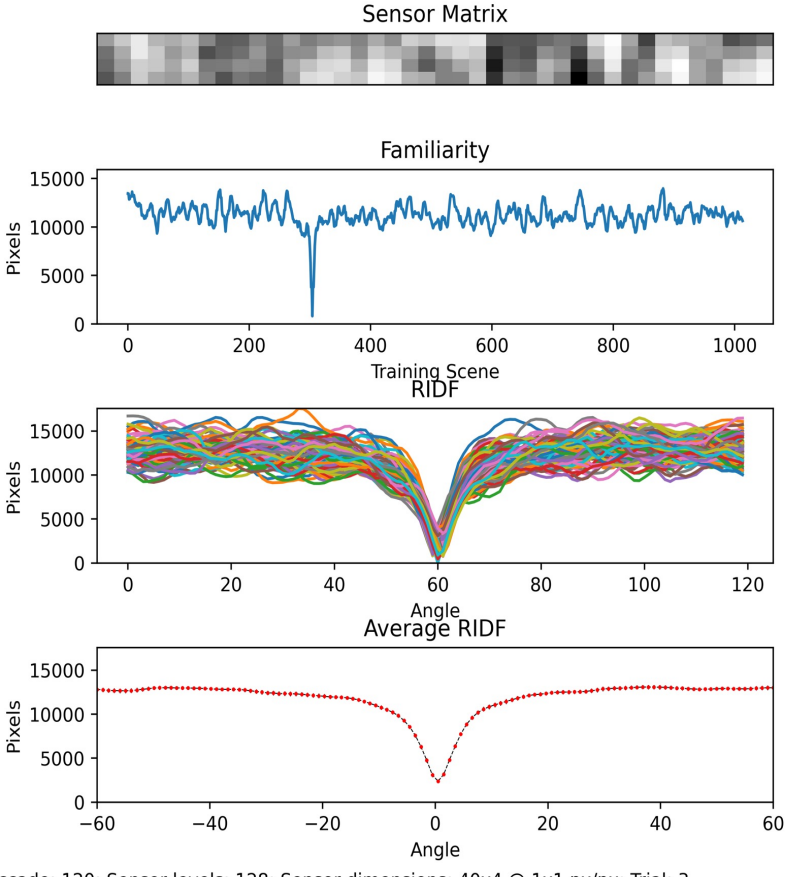




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

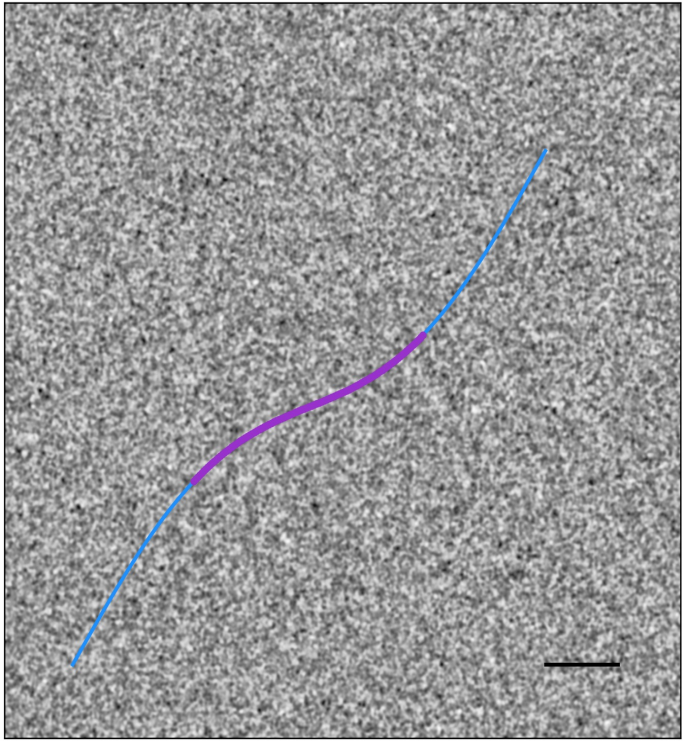
Navigation stats: RMSD error: 35.27; RMSD/dist: 0.088; TD: 8931; p90: 16; p50: 8; complete: 0

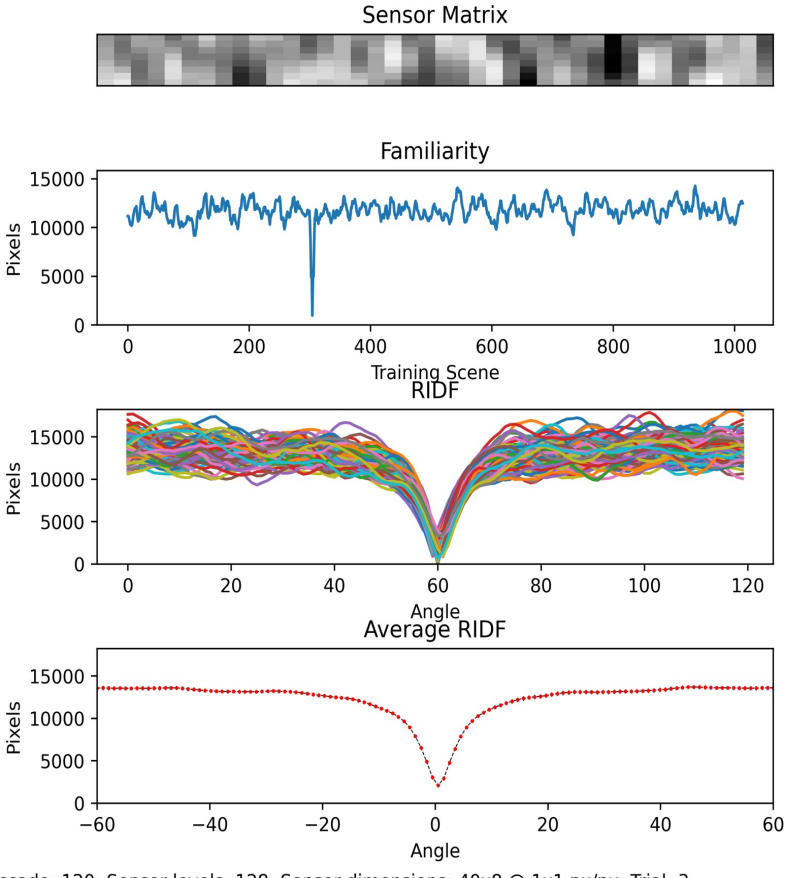




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

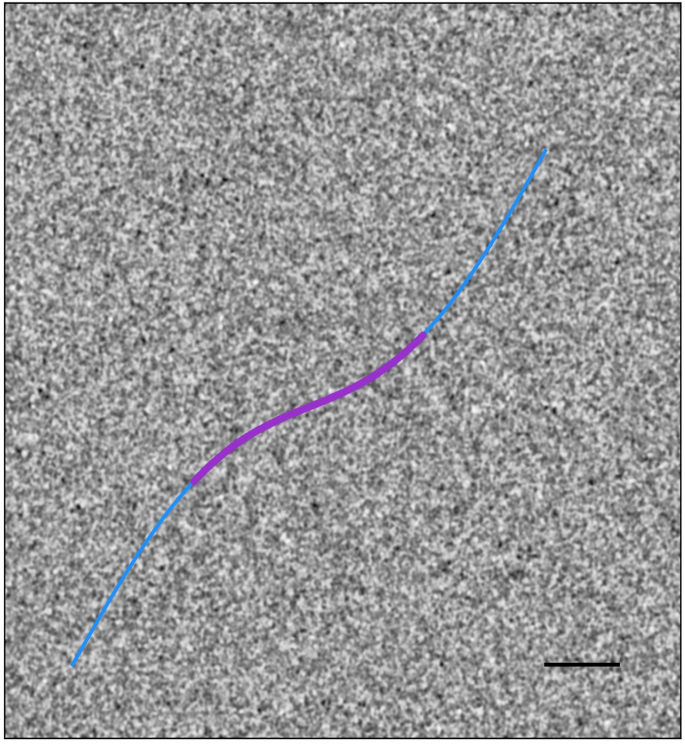
Navigation stats: RMSD error: 55.66; RMSD/dist: 0.139; TD: 8814; p90: 16; p50: 6; complete: 0

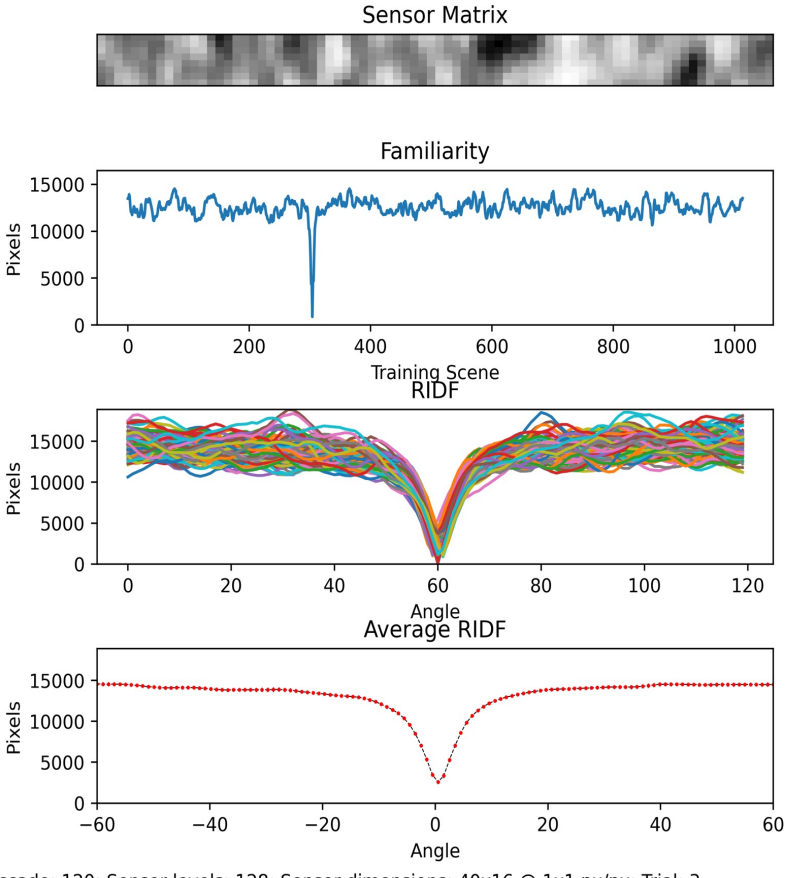




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

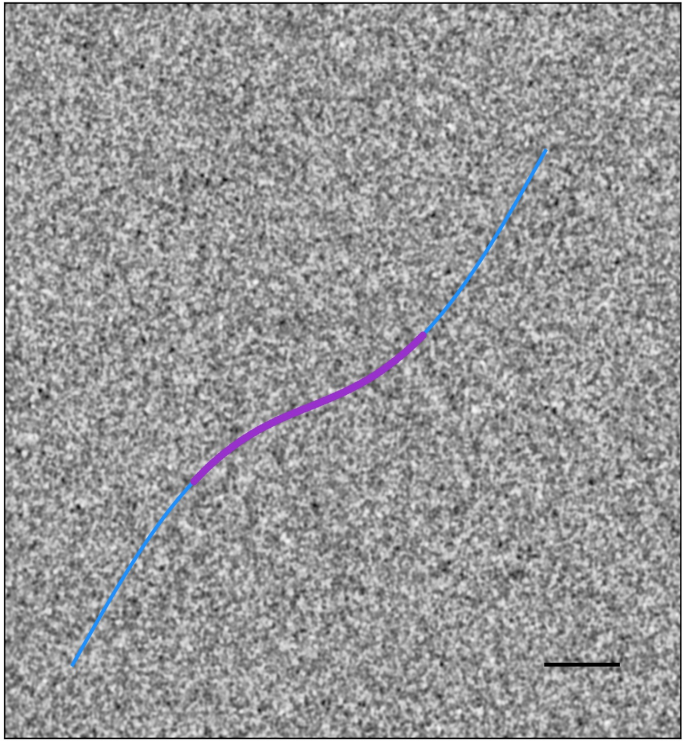
Navigation stats: RMSD error: 36.22; RMSD/dist: 0.091; TD: 9497; p90: 16; p50: 6; complete: 0

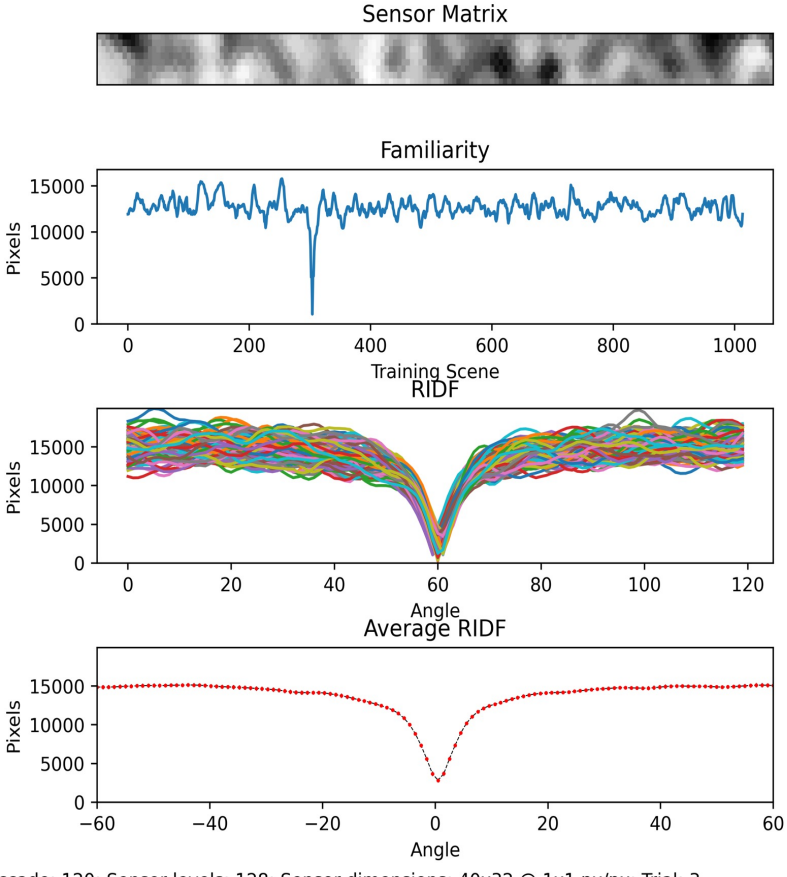




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

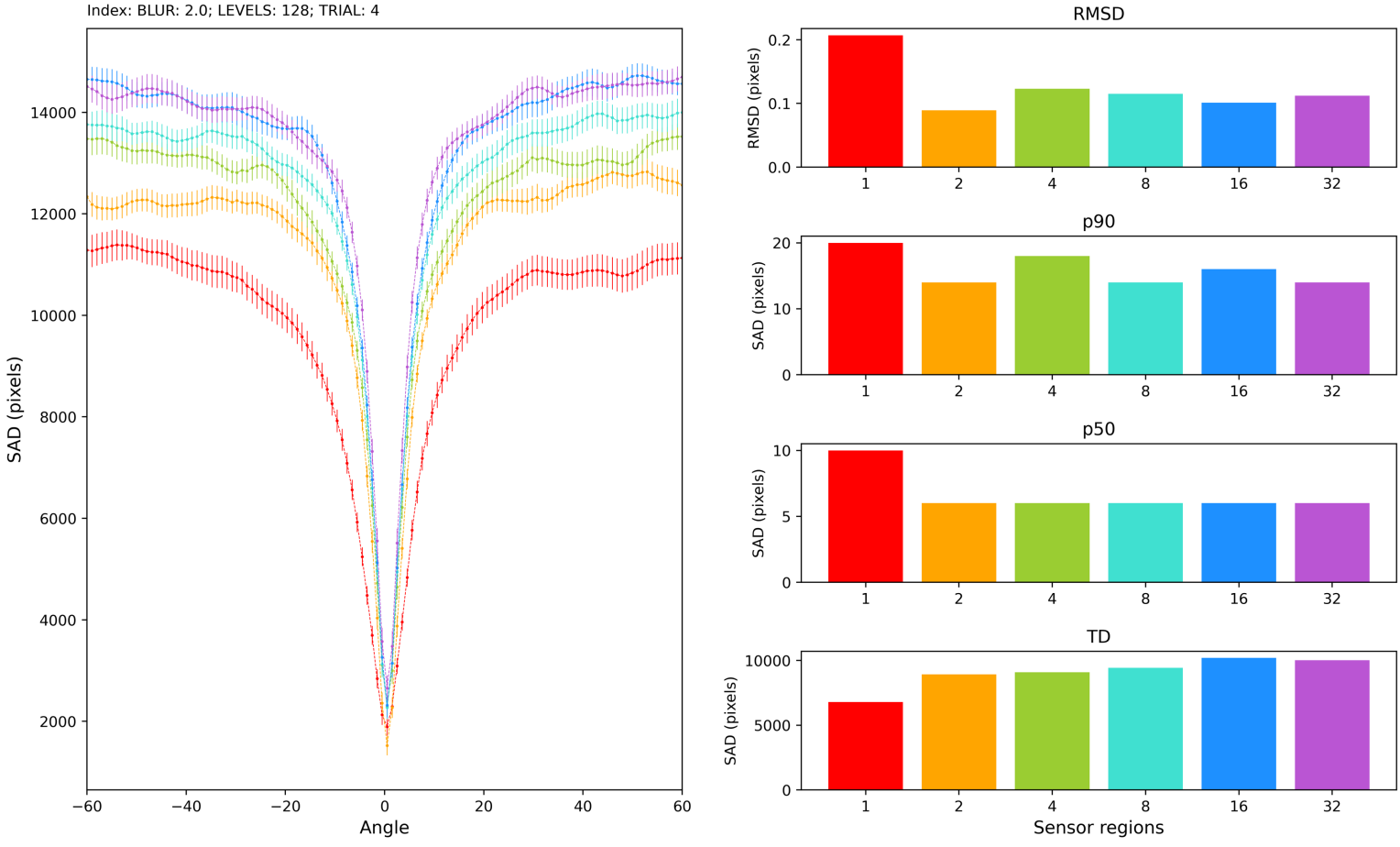
Navigation stats: RMSD error: 47.30; RMSD/dist: 0.118; TD: 9787; p90: 16; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 48.23; RMSD/dist: 0.121; TD: 10025; p90: 16; p50: 6; complete: 0


Index: BLUR: 2.0; LEVELS: 128; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
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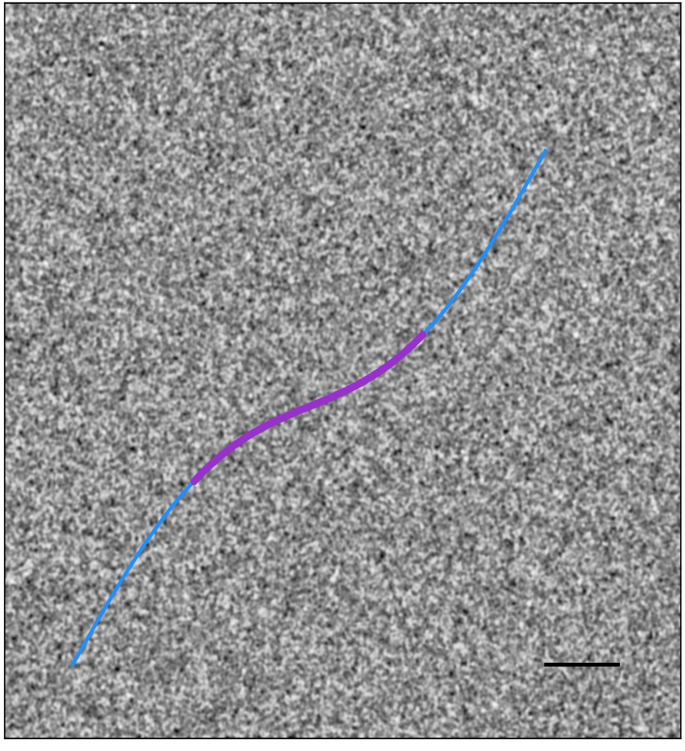
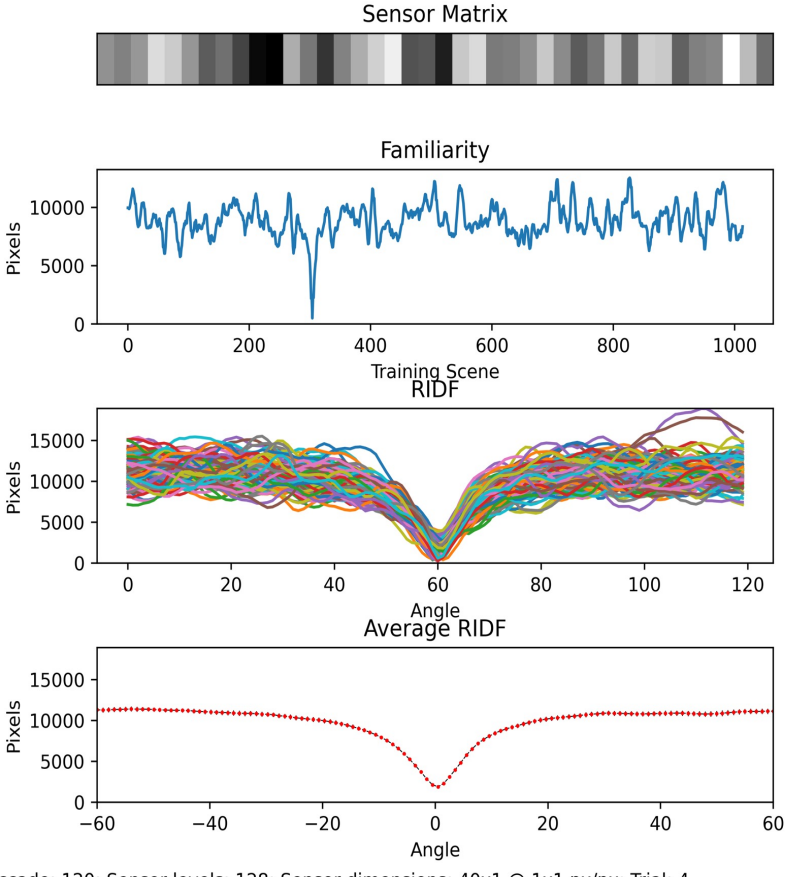
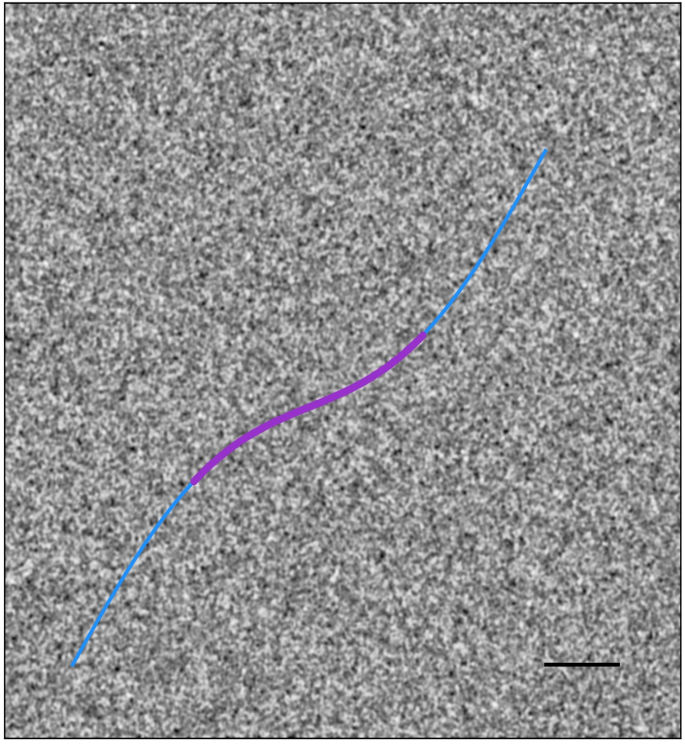
TD
SAD (pixels)
Sensor regions

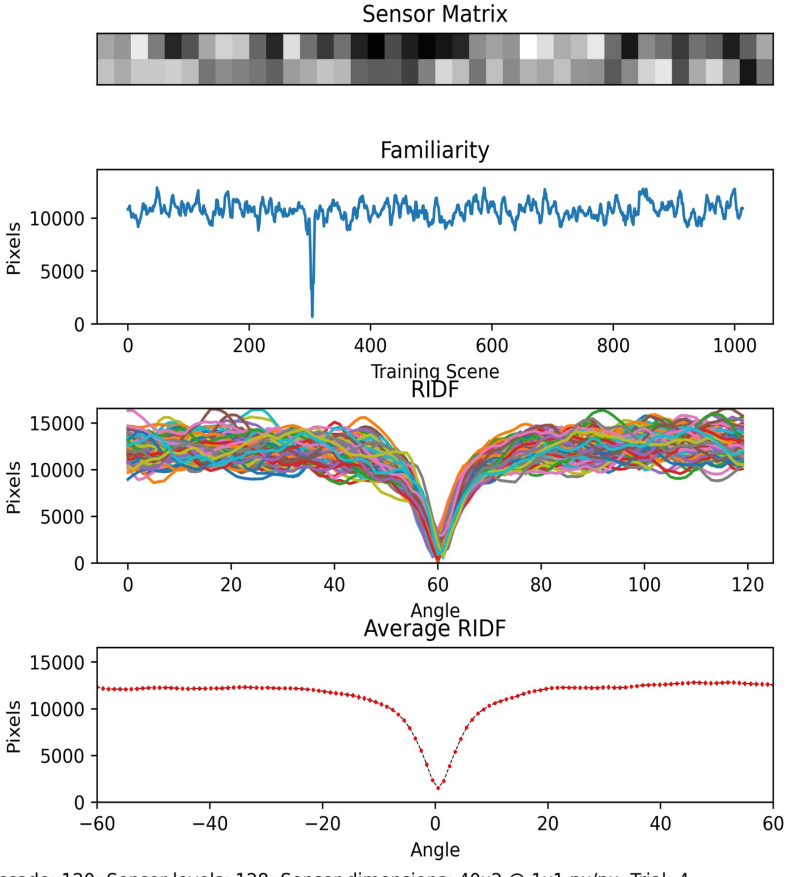




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

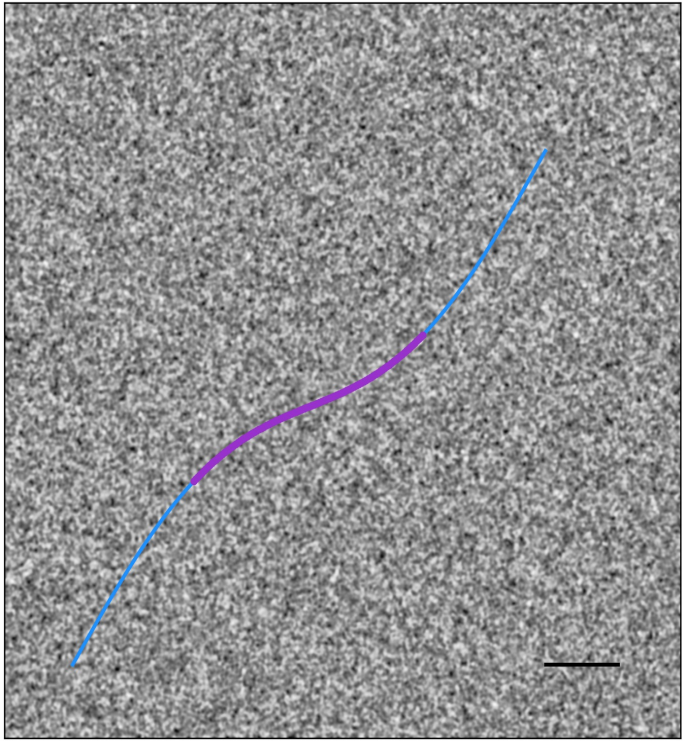
Navigation stats: RMSD error: 82.95; RMSD/dist: 0.207; TD: 6796; p90: 20; p50: 10; complete: 0

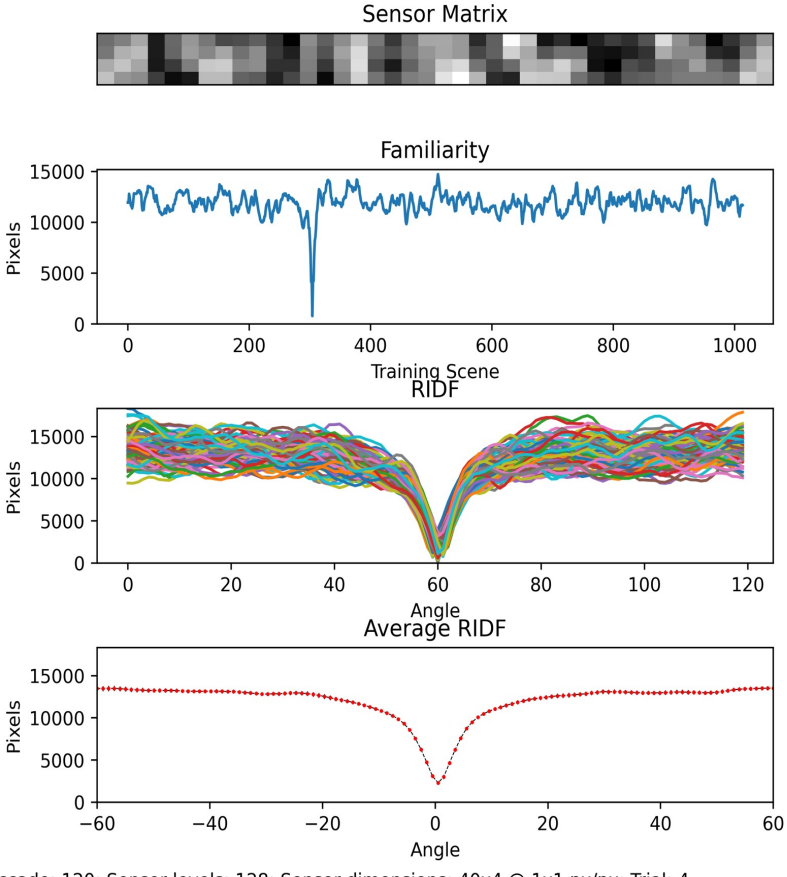




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

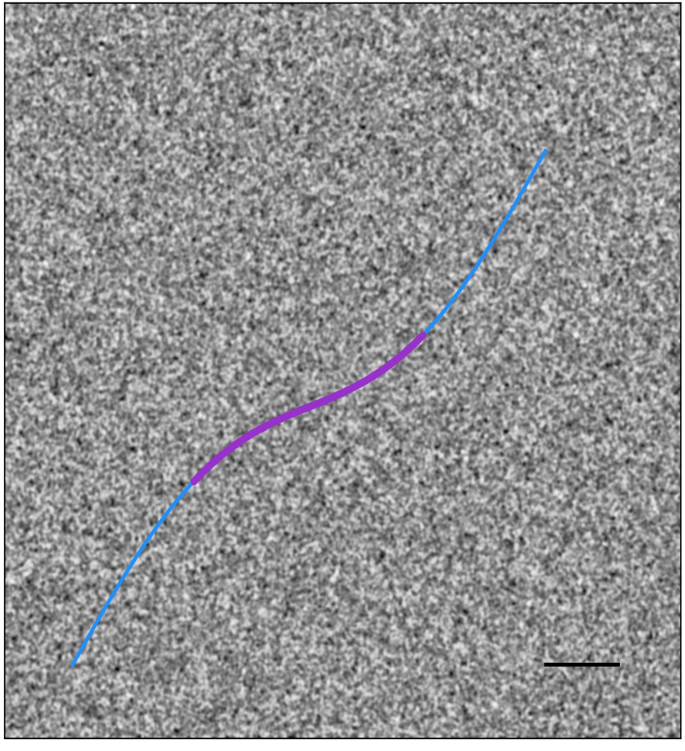
Navigation stats: RMSD error: 35.51; RMSD/dist: 0.089; TD: 8936; p90: 14; p50: 6; complete: 0

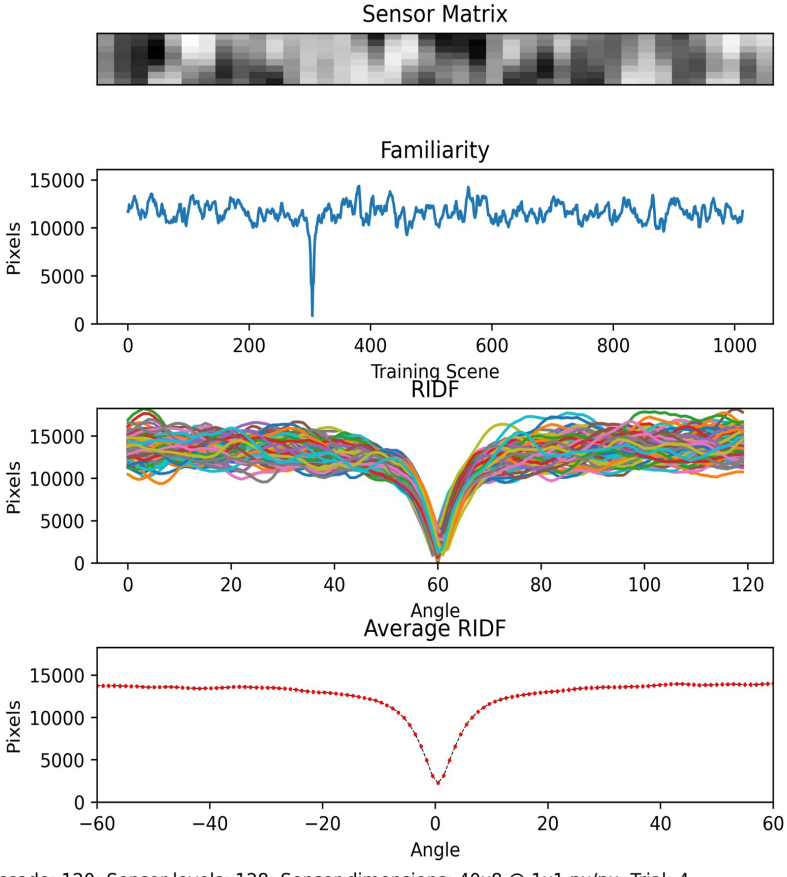




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

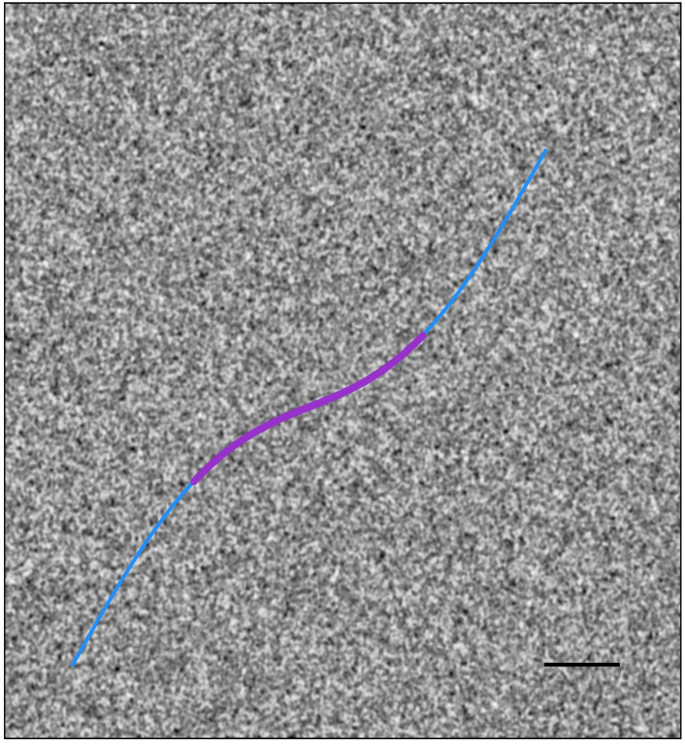
Navigation stats: RMSD error: 49.24; RMSD/dist: 0.123; TD: 9100; p90: 18; p50: 6; complete: 0

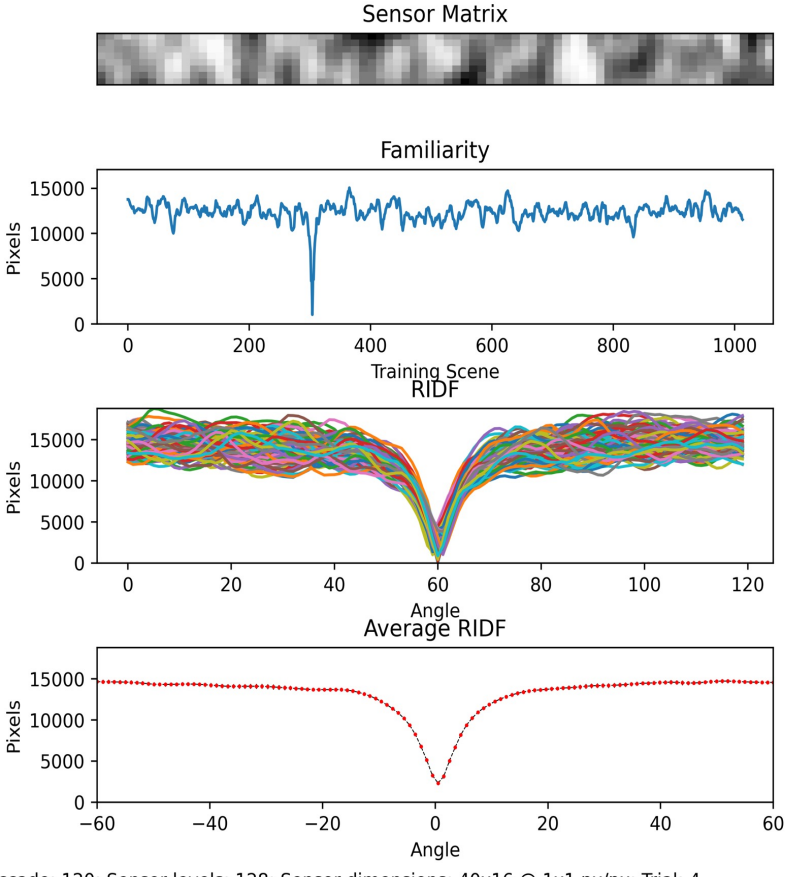




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

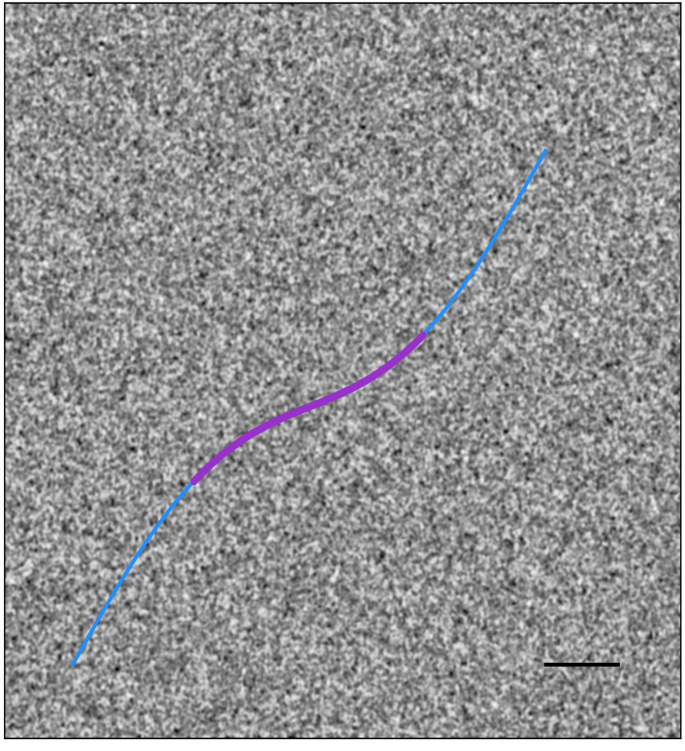
Navigation stats: RMSD error: 45.84; RMSD/dist: 0.115; TD: 9428; p90: 14; p50: 6; complete: 0

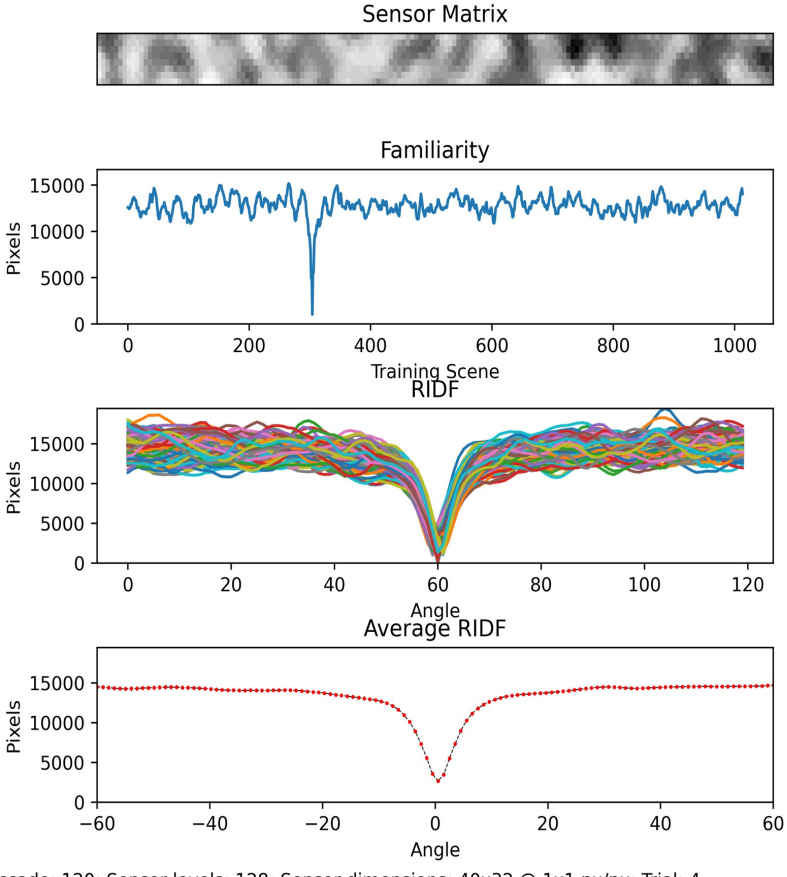




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

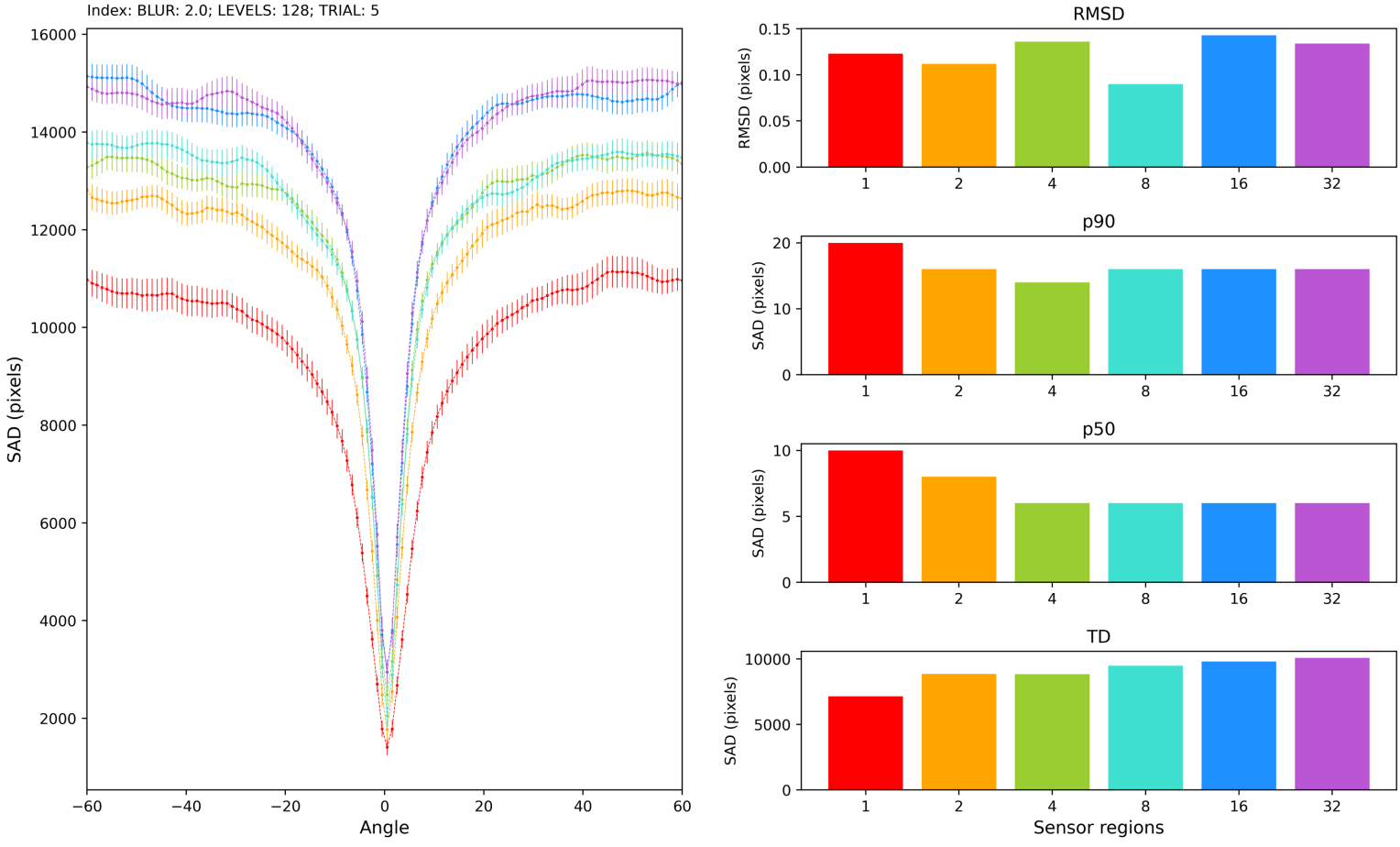
Navigation stats: RMSD error: 40.23; RMSD/dist: 0.101; TD: 10195; p90: 16; p50: 6; complete: 0

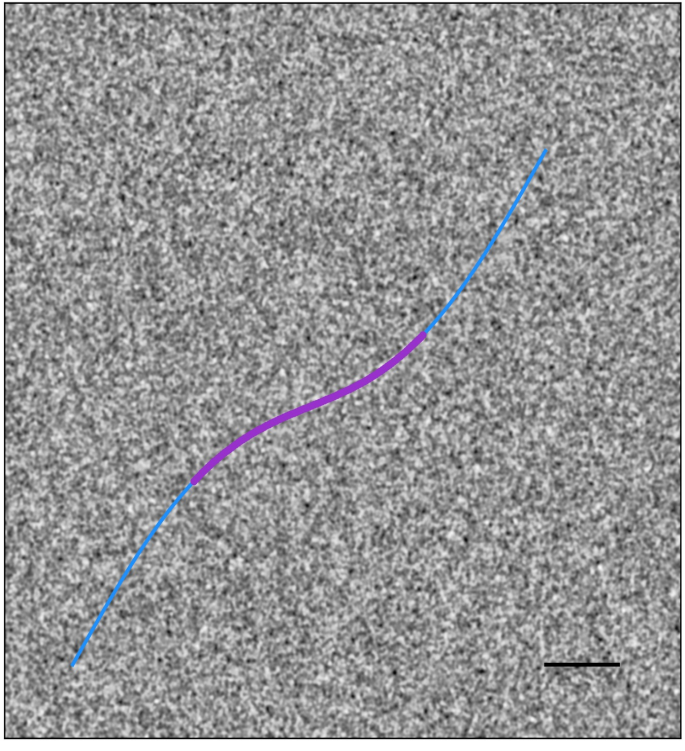


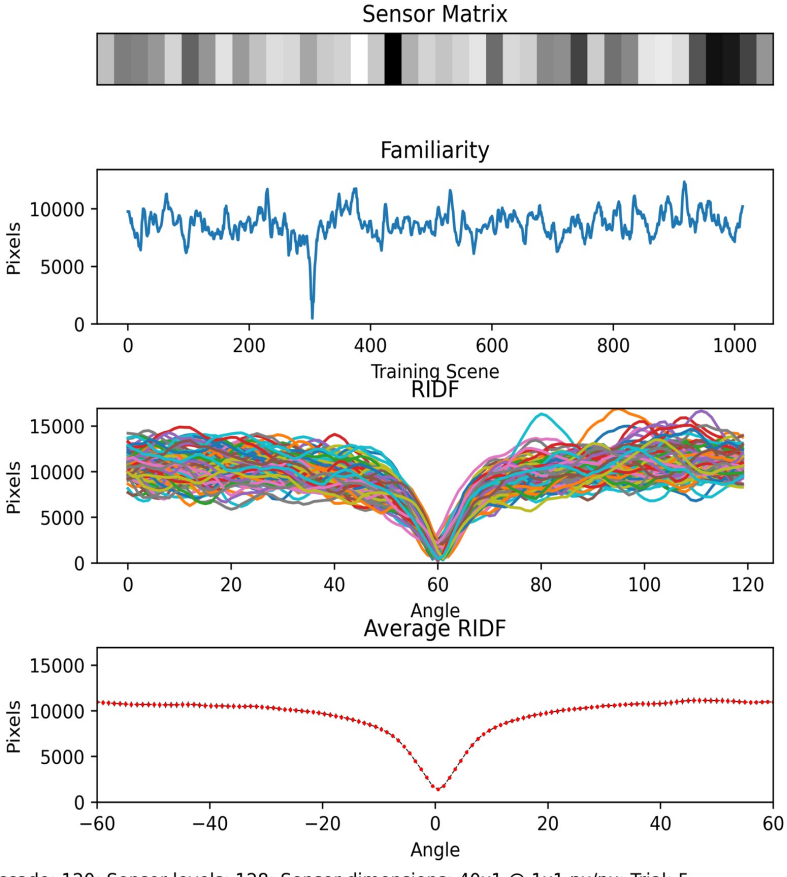


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 44.81; RMSD/dist: 0.112; TD: 10022; p90: 14; p50: 6; complete: 0

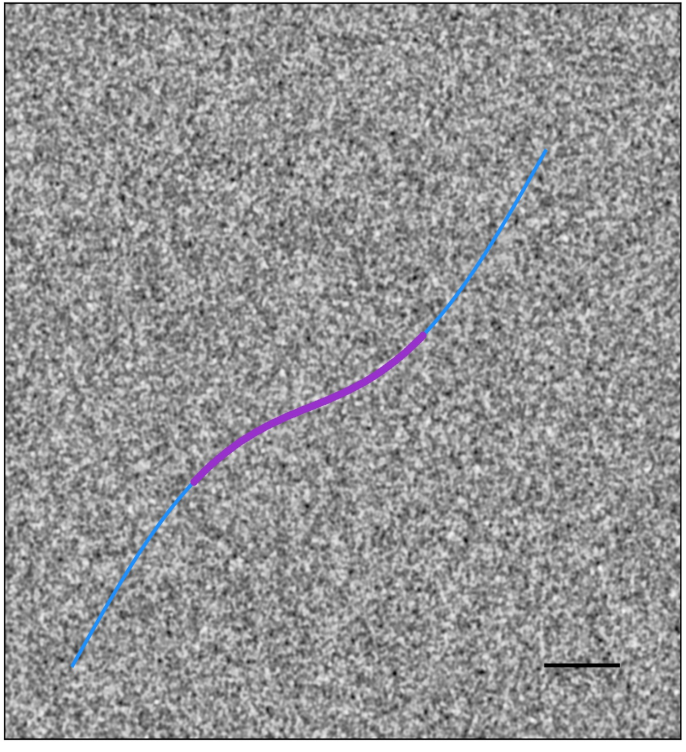

Index: BLUR: 2.0; LEVELS: 128; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

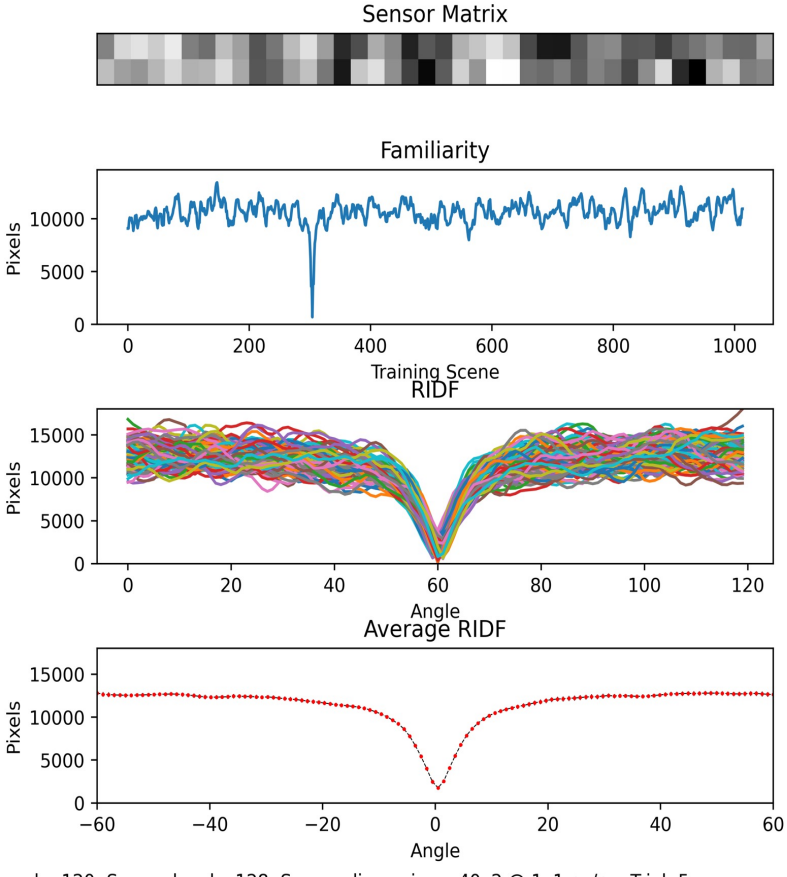




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

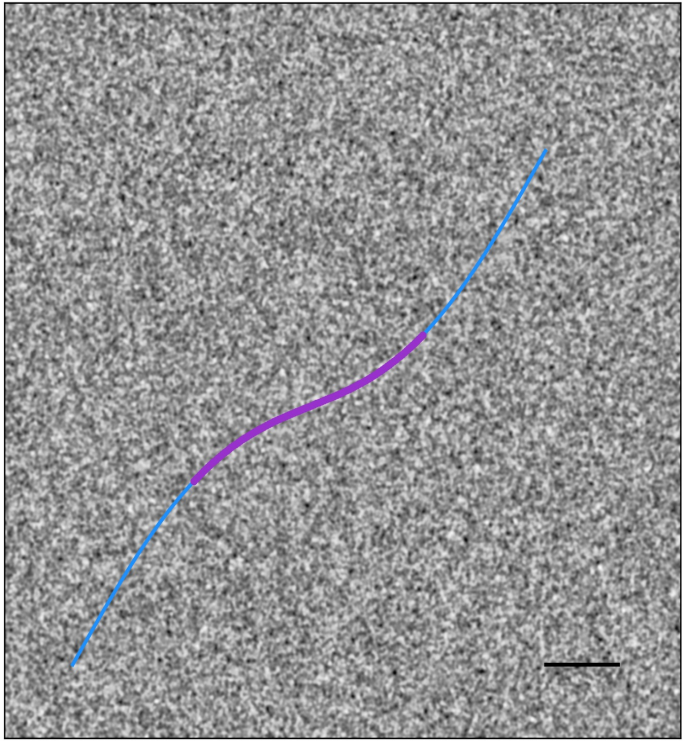
Navigation stats: RMSD error: 49.15; RMSD/dist: 0.123; TD: 7142; p90: 20; p50: 10; complete: 0

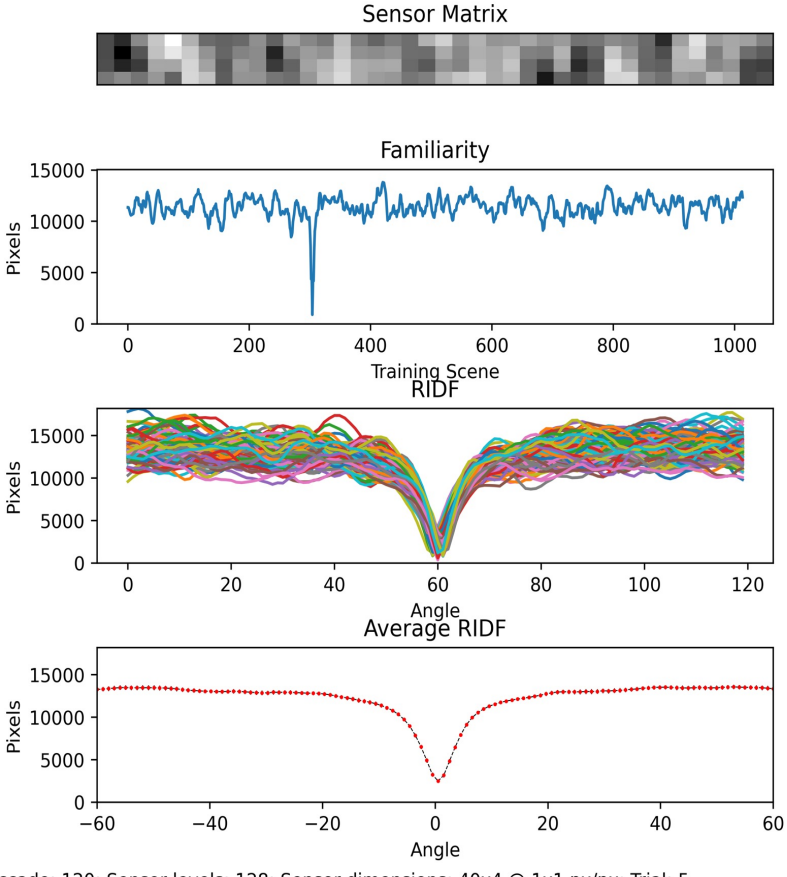




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

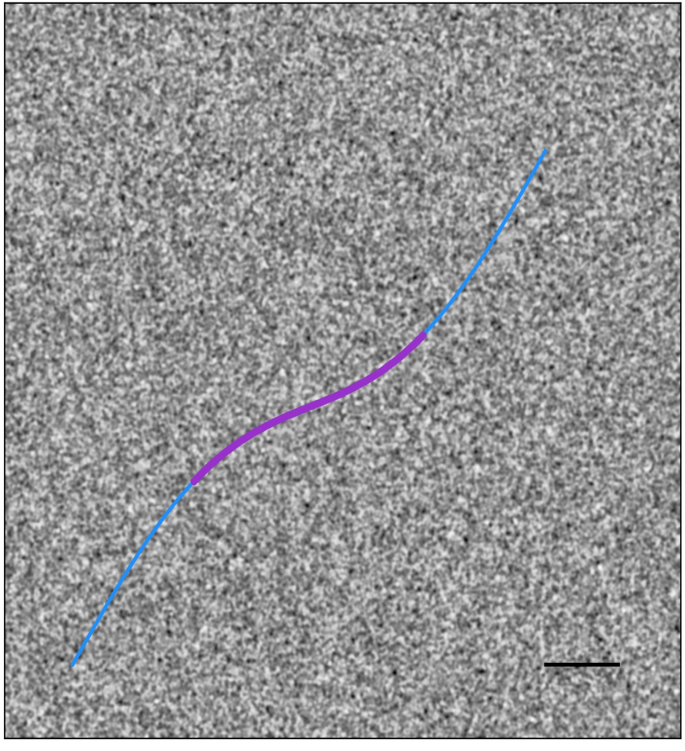
Navigation stats: RMSD error: 44.74; RMSD/dist: 0.112; TD: 8853; p90: 16; p50: 8; complete: 0

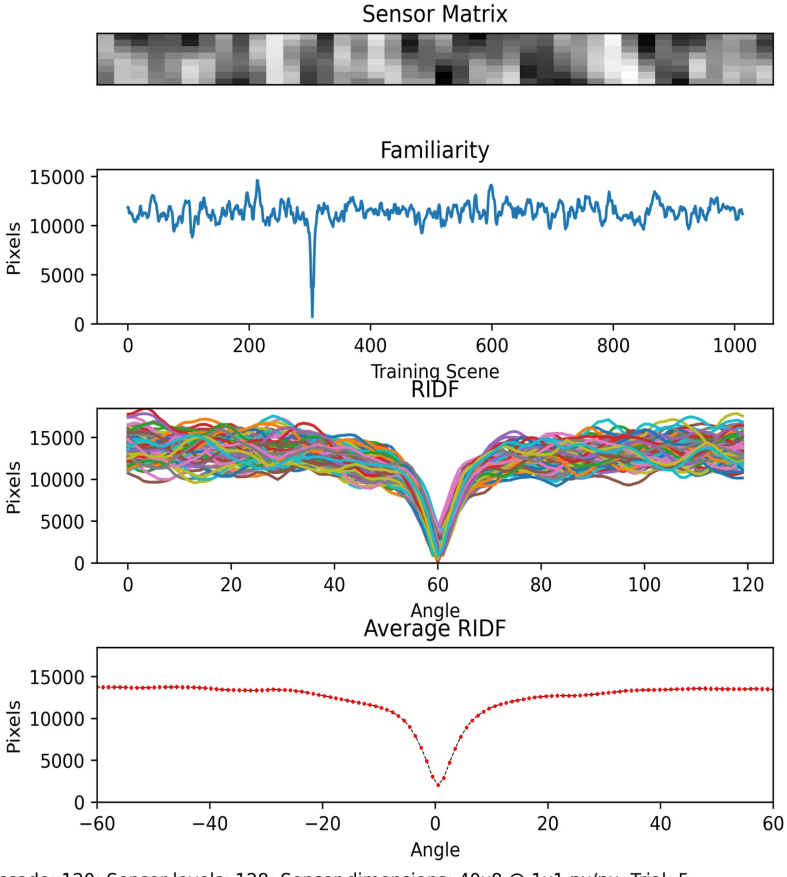




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

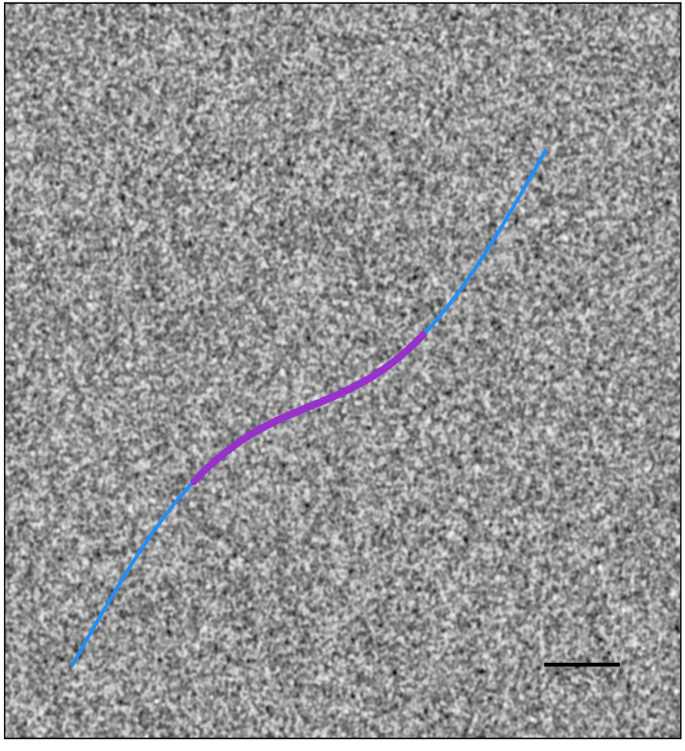
Navigation stats: RMSD error: 54.54; RMSD/dist: 0.136; TD: 8845; p90: 14; p50: 6; complete: 0

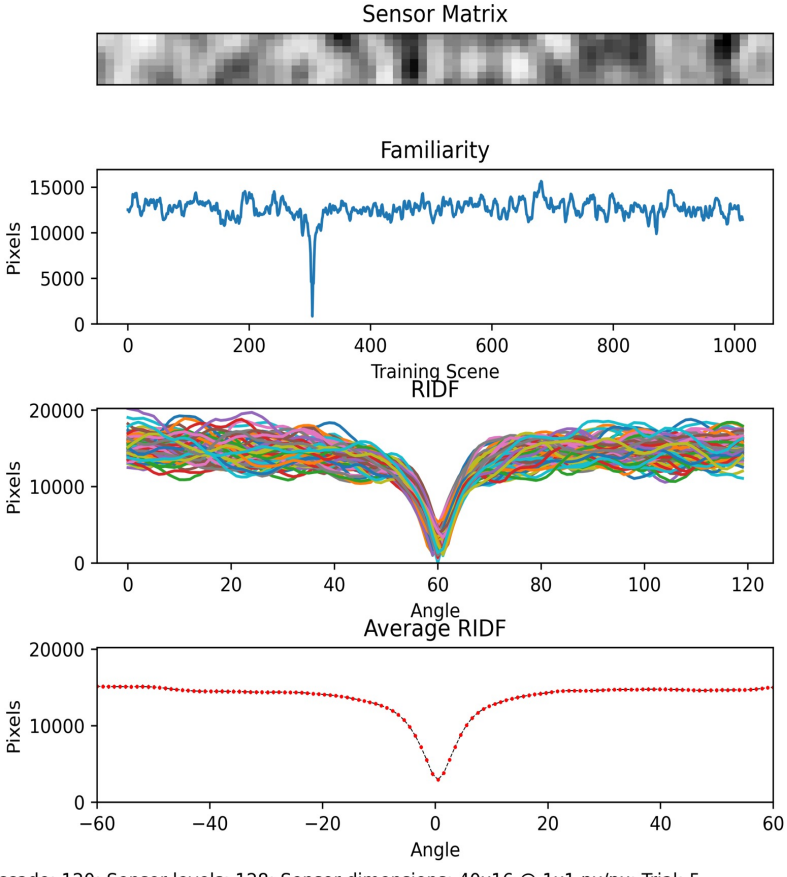




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

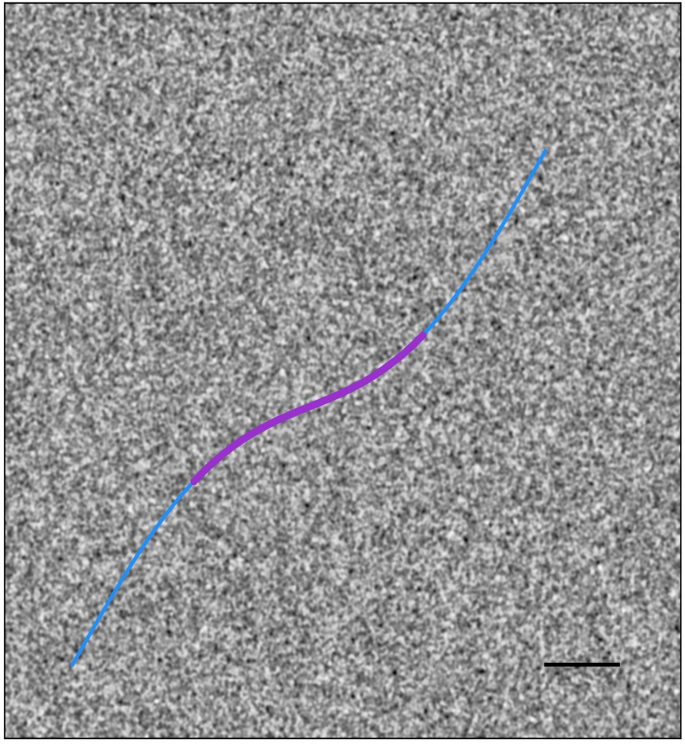
Navigation stats: RMSD error: 36.09; RMSD/dist: 0.090; TD: 9485; p90: 16; p50: 6; complete: 0

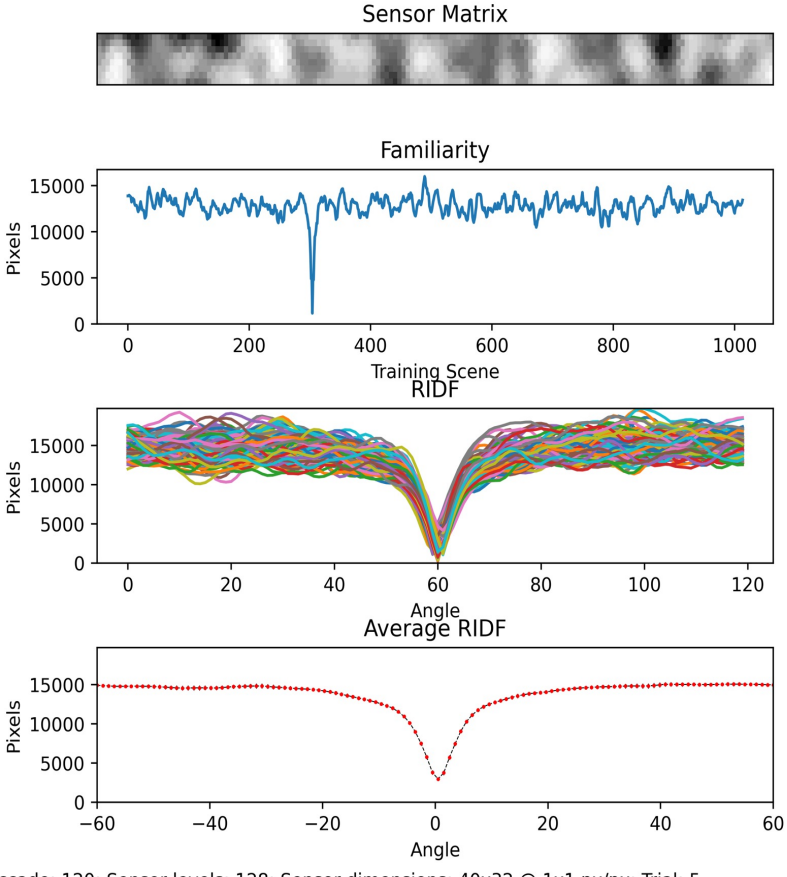




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

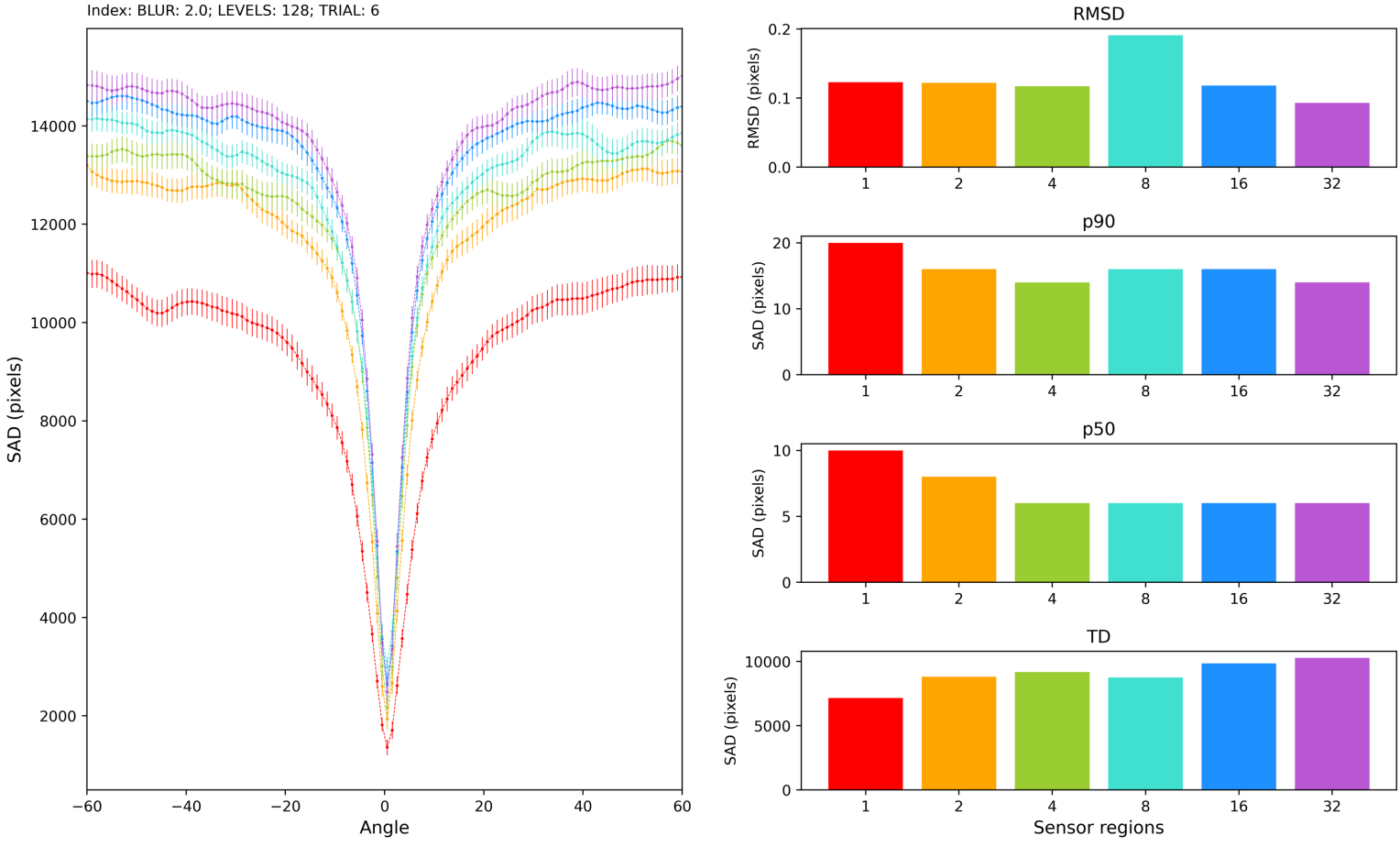
Navigation stats: RMSD error: 57.38; RMSD/dist: 0.143; TD: 9807; p90: 16; p50: 6; complete: 0

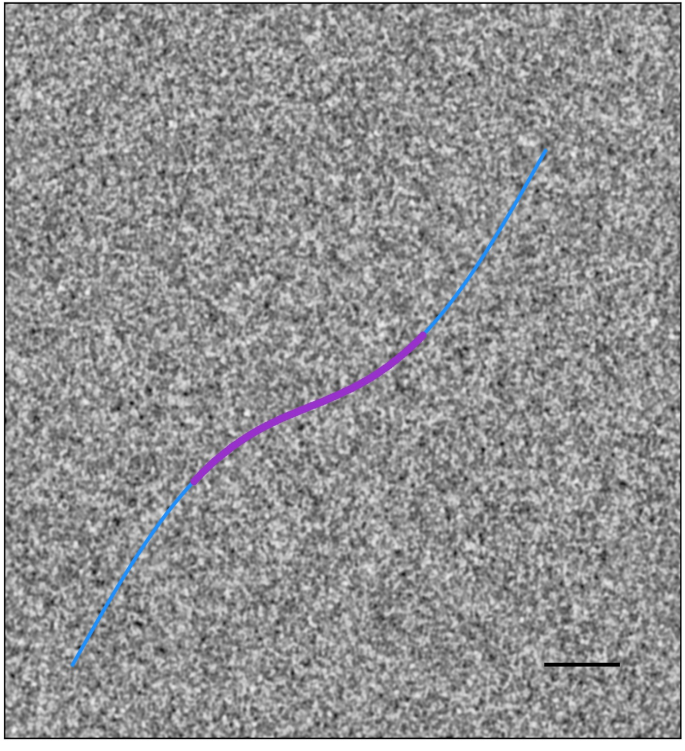


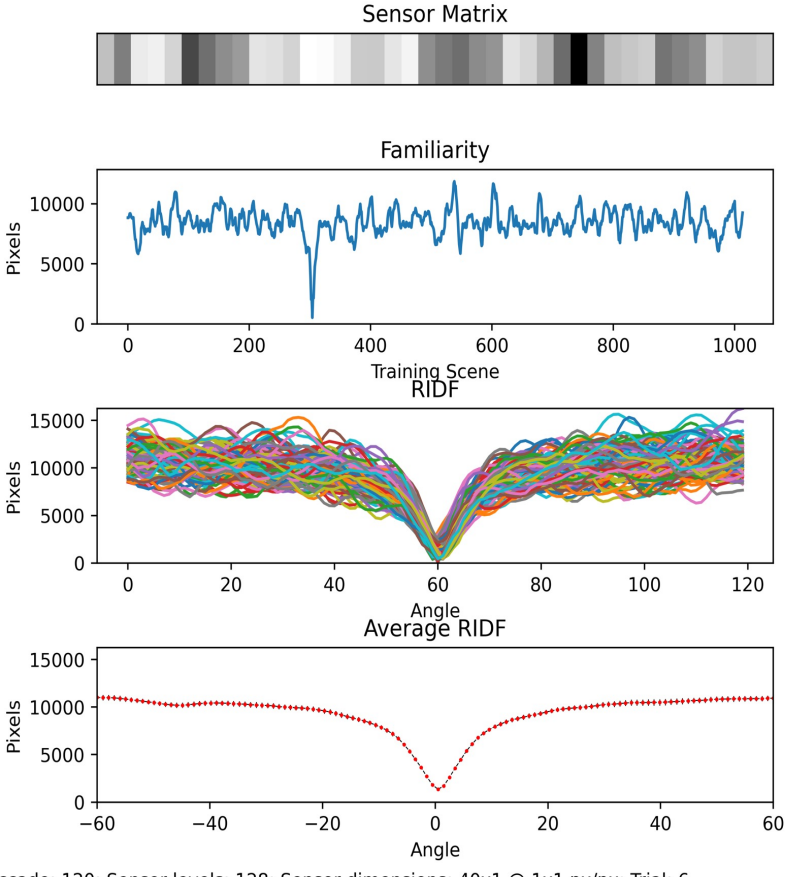


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 53.79; RMSD/dist: 0.134; TD: 10080; p90: 16; p50: 6; complete: 0

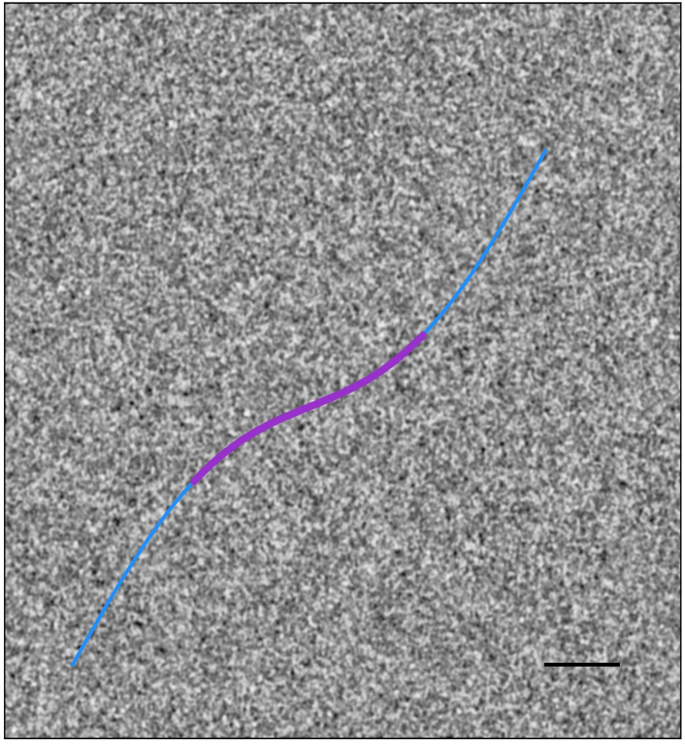

Index: BLUR: 2.0; LEVELS: 128; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

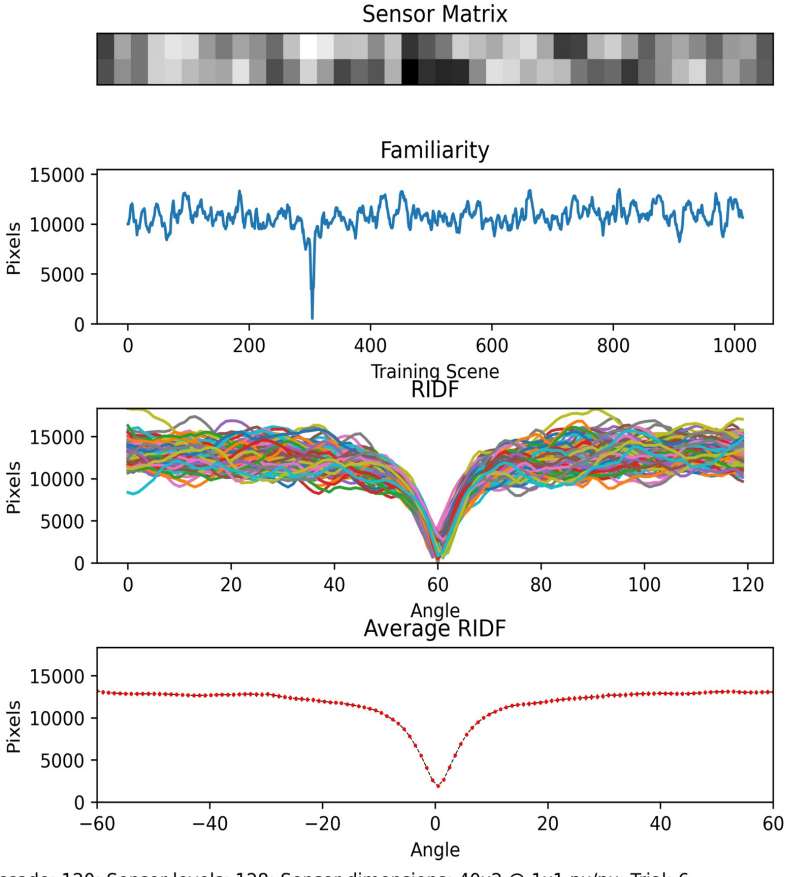




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

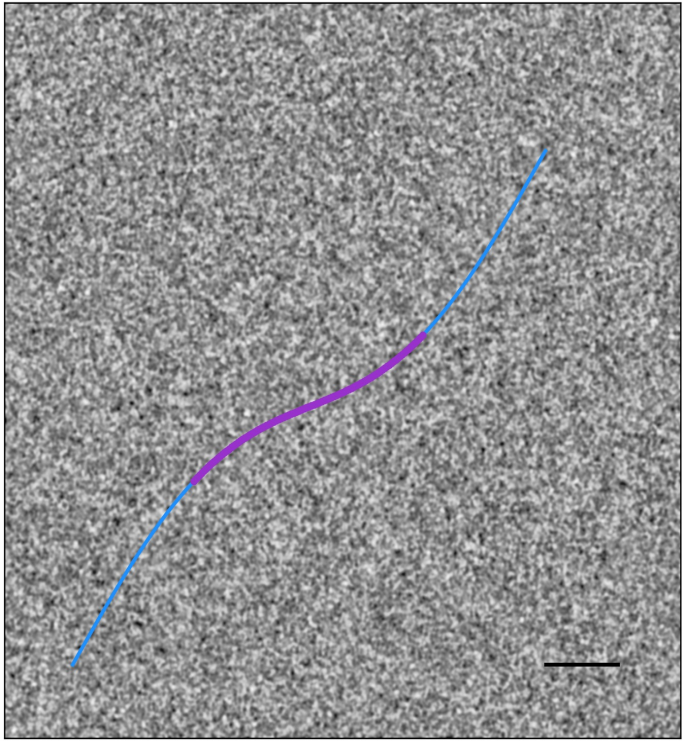
Navigation stats: RMSD error: 49.03; RMSD/dist: 0.123; TD: 7151; p90: 20; p50: 10; complete: 0

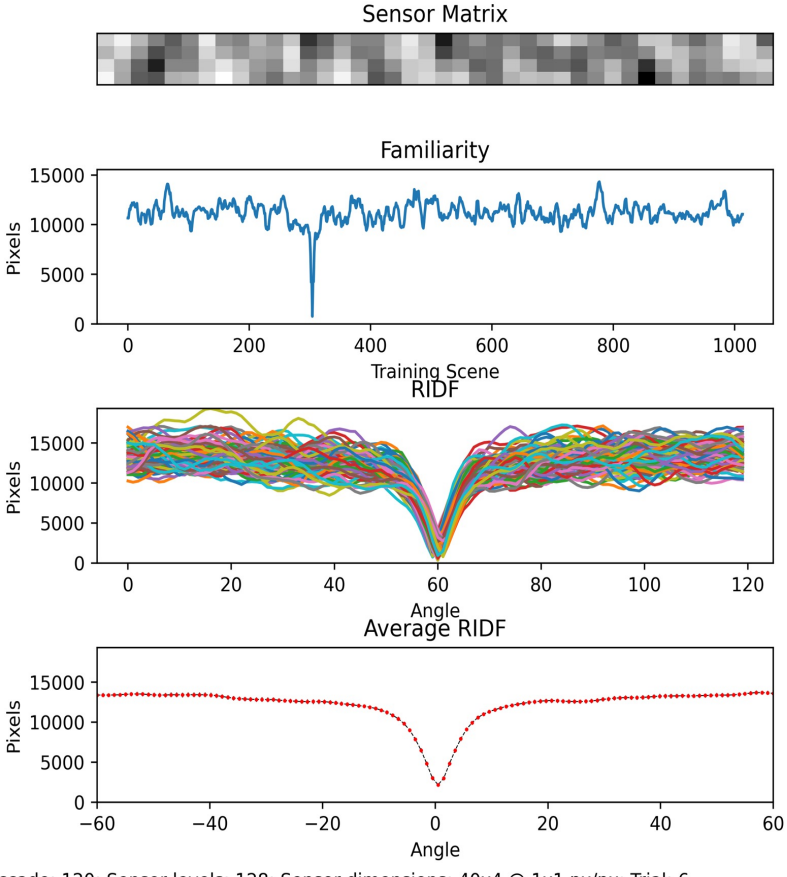




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

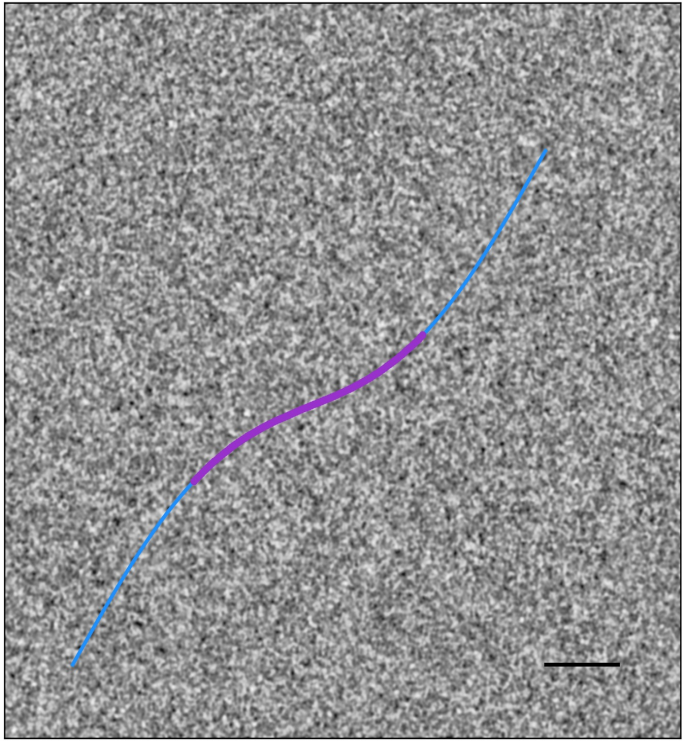
Navigation stats: RMSD error: 48.75; RMSD/dist: 0.122; TD: 8823; p90: 16; p50: 8; complete: 0

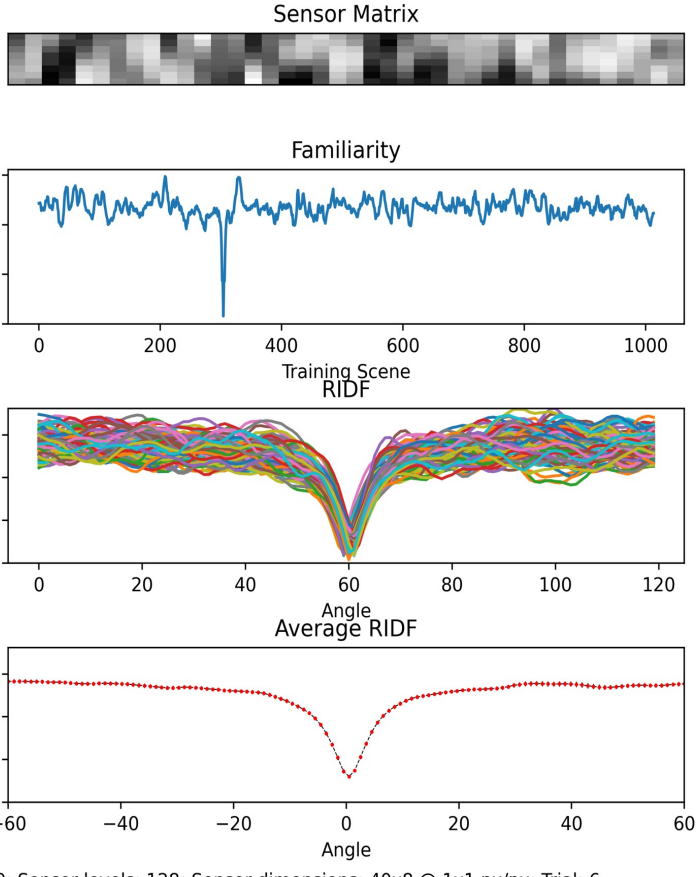




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

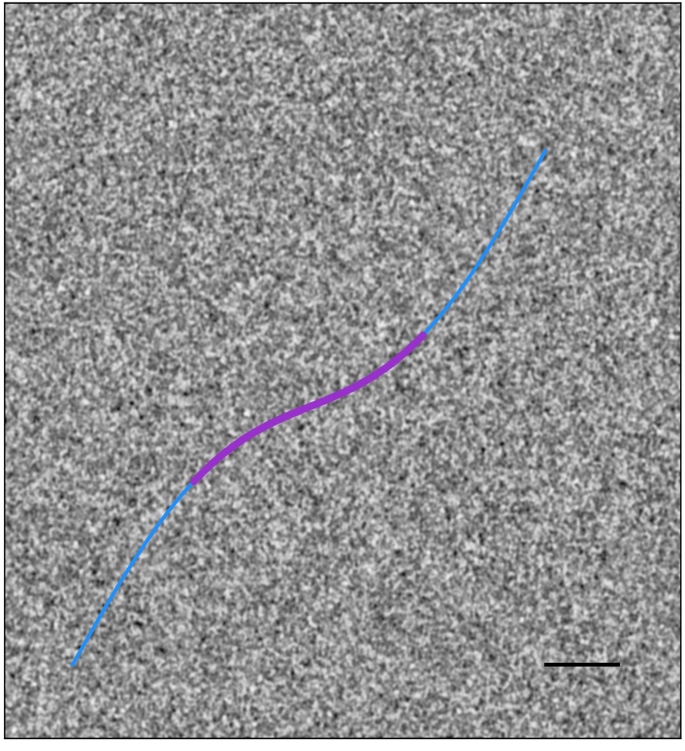
Navigation stats: RMSD error: 46.98; RMSD/dist: 0.117; TD: 9171; p90: 14; p50: 6; complete: 0

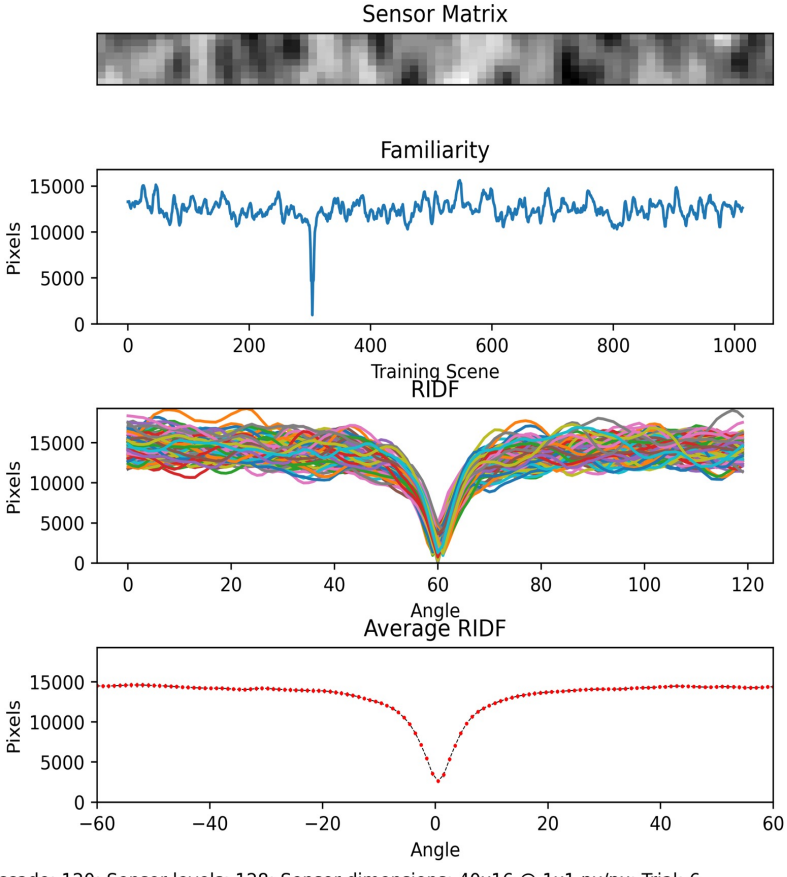




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

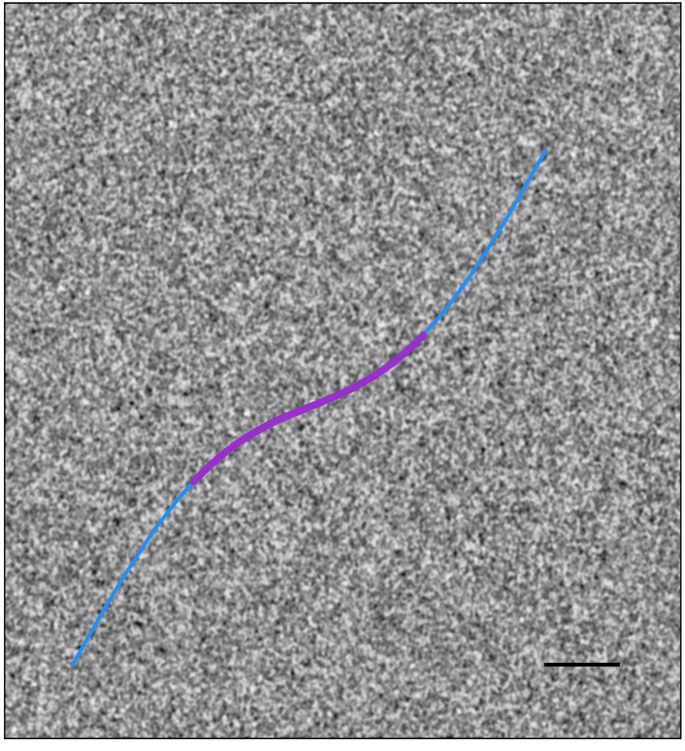
Navigation stats: RMSD error: 76.35; RMSD/dist: 0.191; TD: 8743; p90: 16; p50: 6; complete: 0

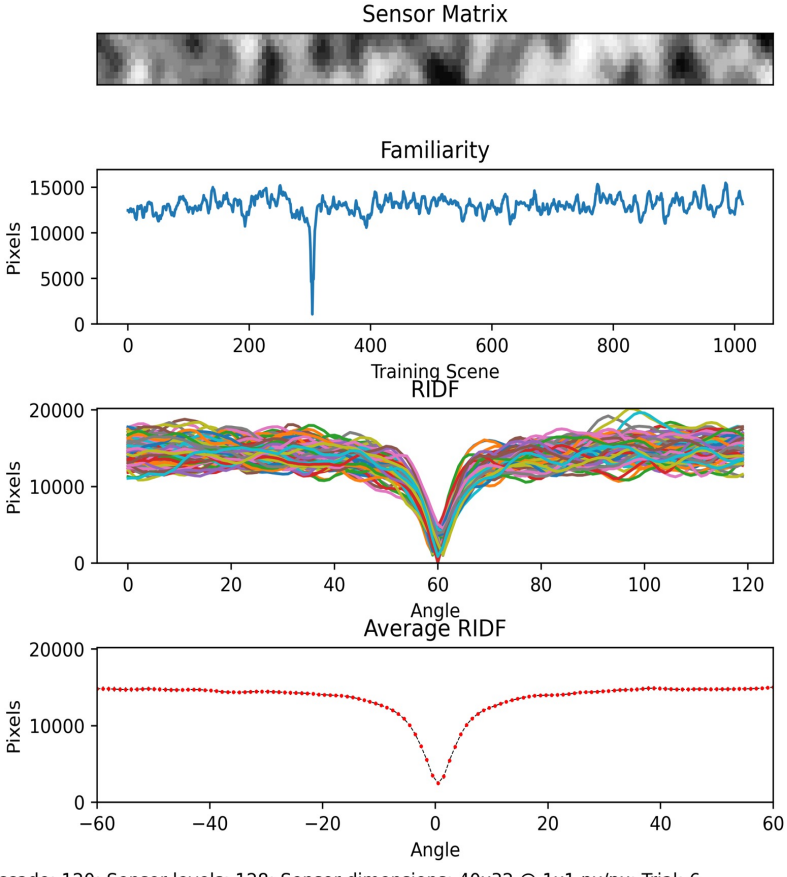




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

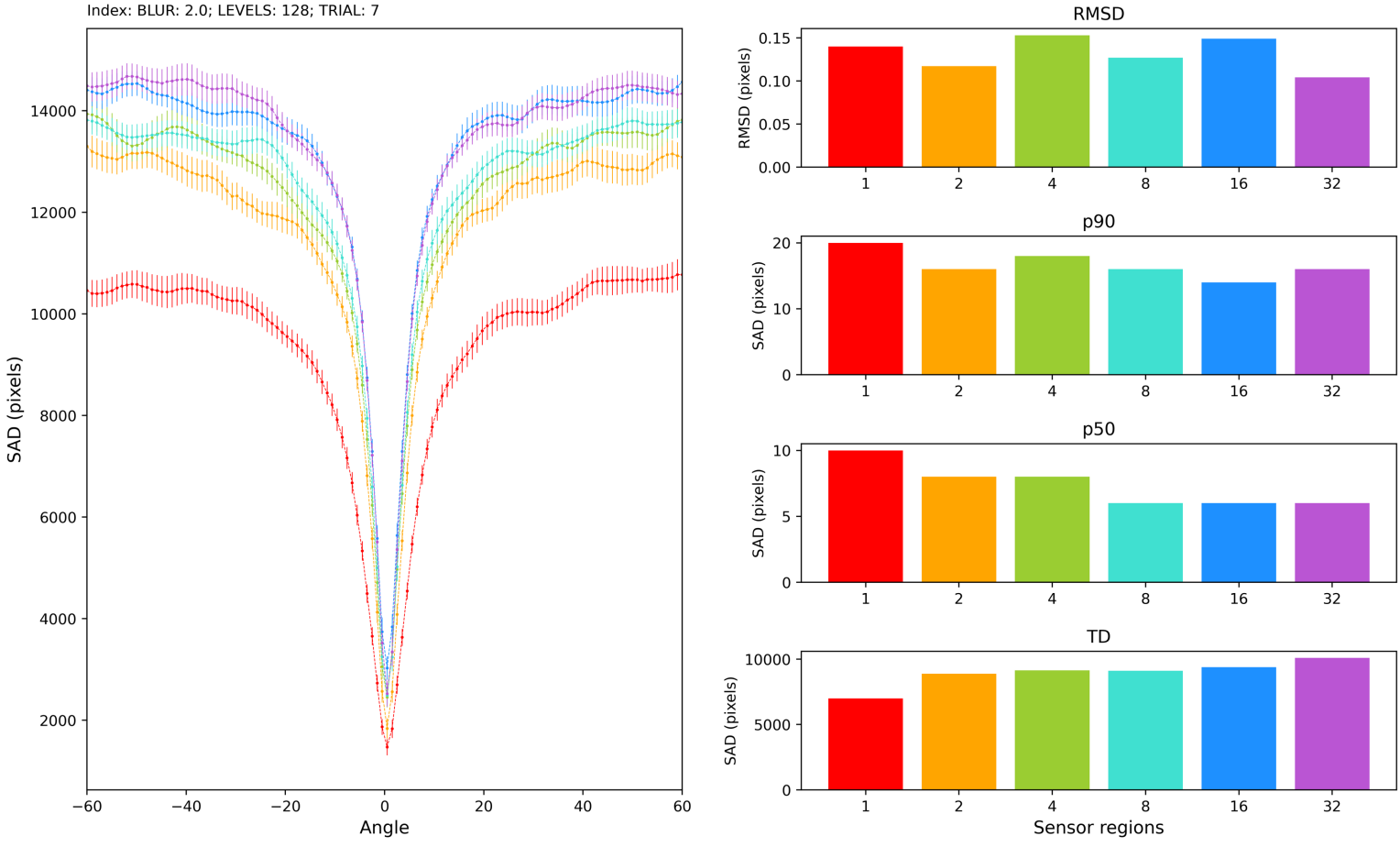
Navigation stats: RMSD error: 47.00; RMSD/dist: 0.118; TD: 9858; p90: 16; p50: 6; complete: 0

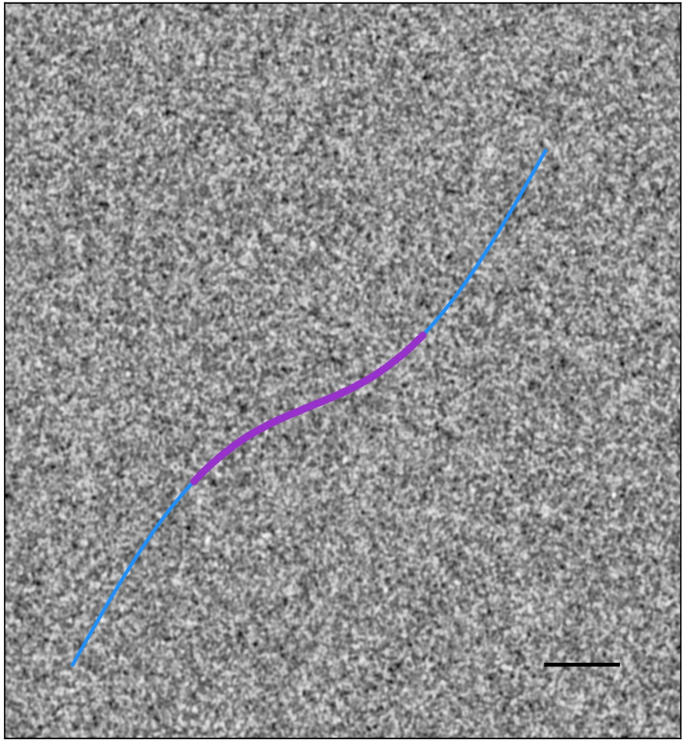


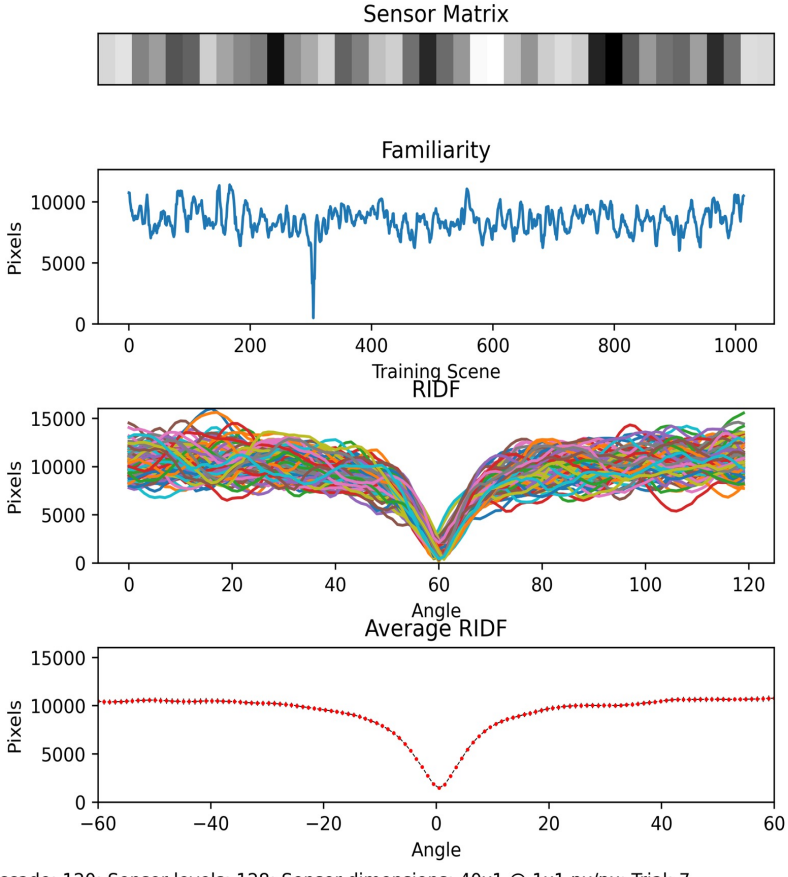


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 37.27; RMSD/dist: 0.093; TD: 10273; p90: 14; p50: 6; complete: 0

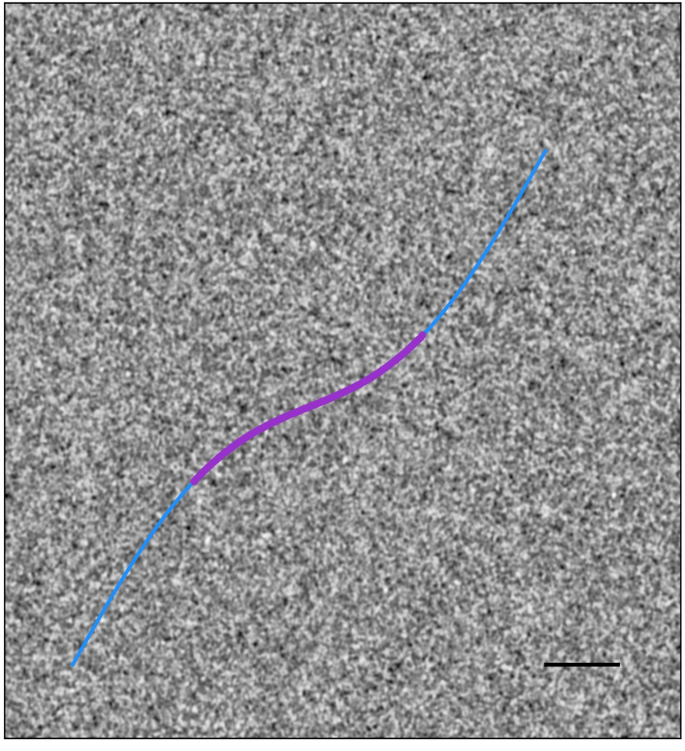

Index: BLUR: 2.0; LEVELS: 128; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

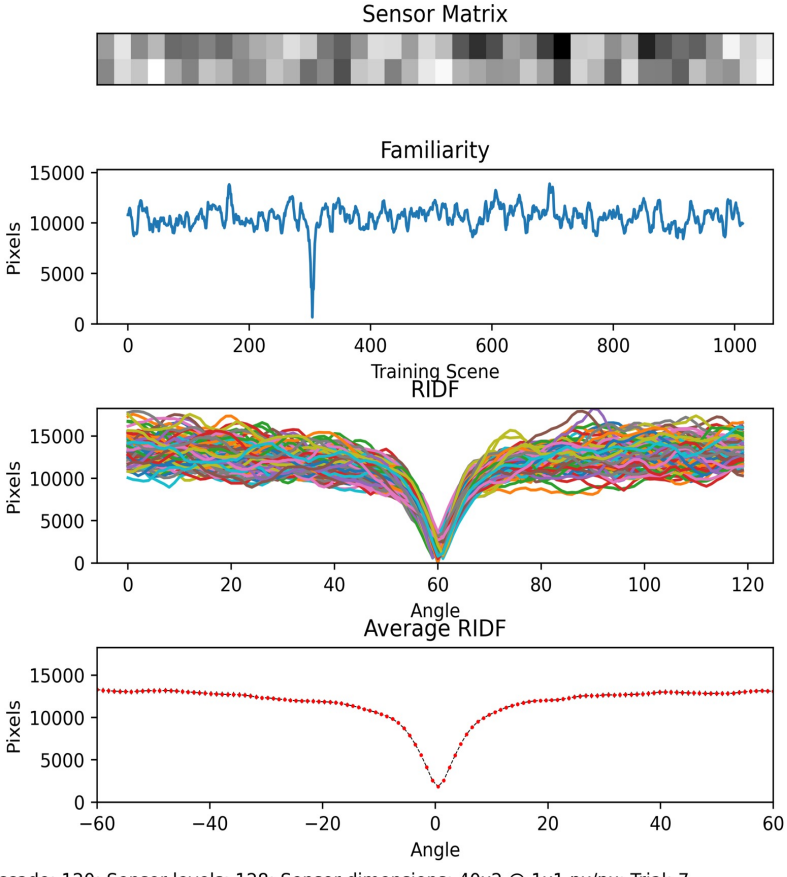




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

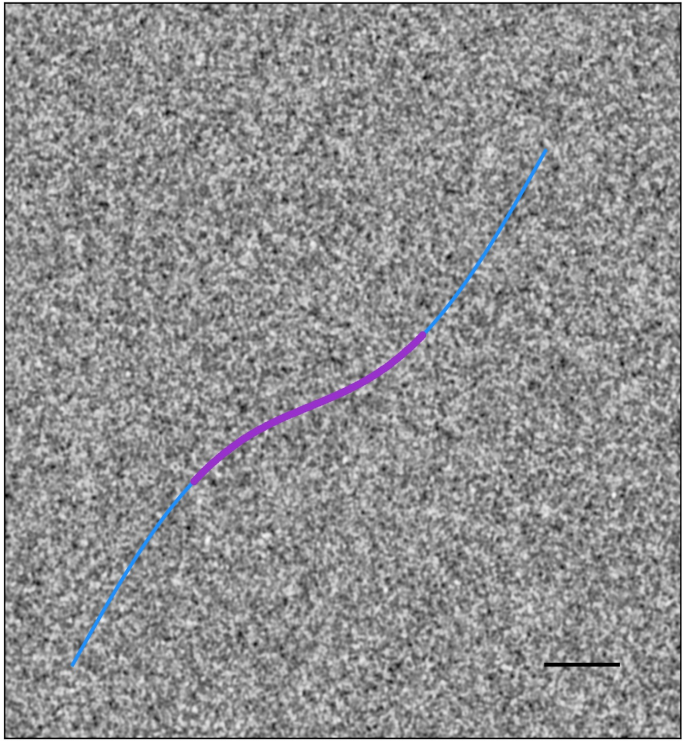
Navigation stats: RMSD error: 55.83; RMSD/dist: 0.140; TD: 6994; p90: 20; p50: 10; complete: 0

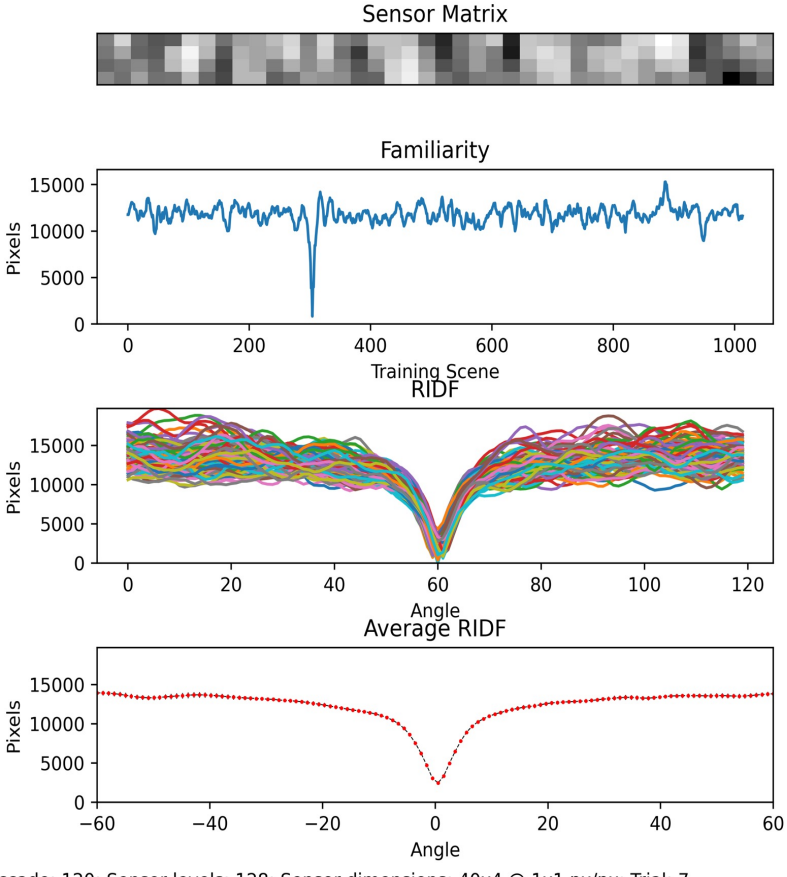




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

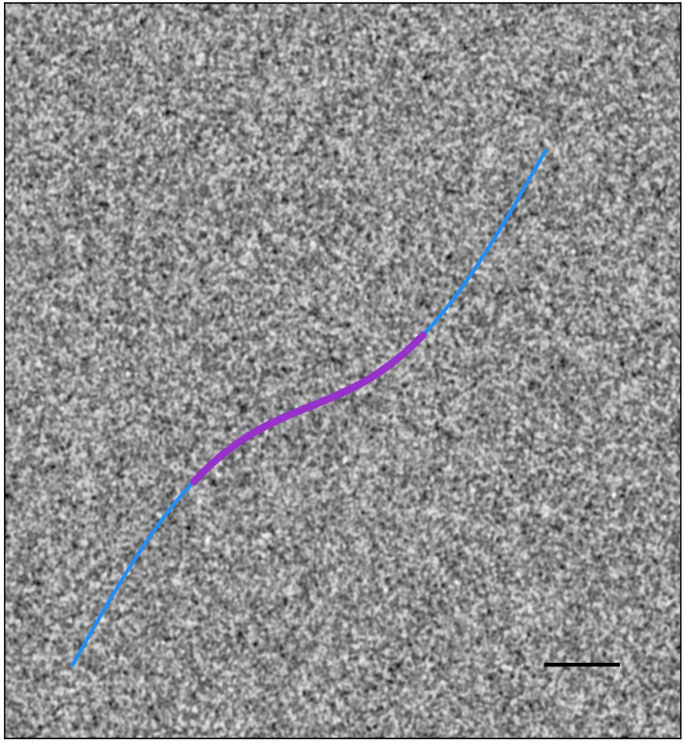
Navigation stats: RMSD error: 46.92; RMSD/dist: 0.117; TD: 8875; p90: 16; p50: 8; complete: 0

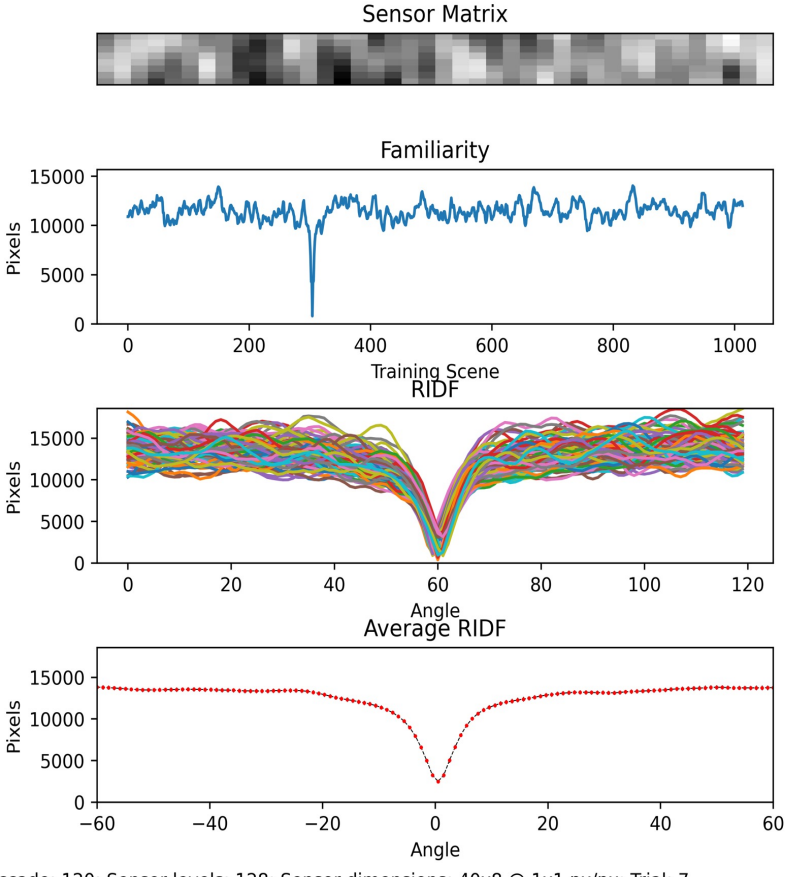




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

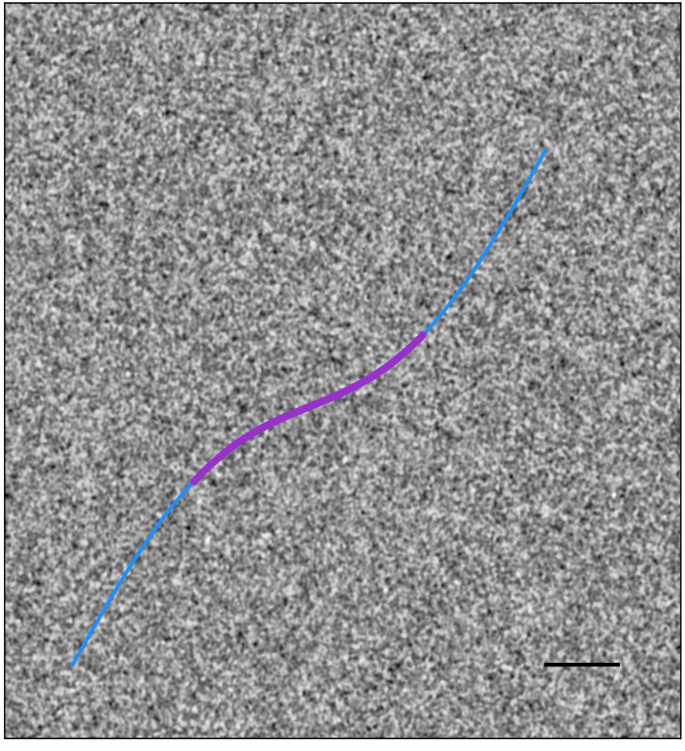
Navigation stats: RMSD error: 61.19; RMSD/dist: 0.153; TD: 9139; p90: 18; p50: 8; complete: 0

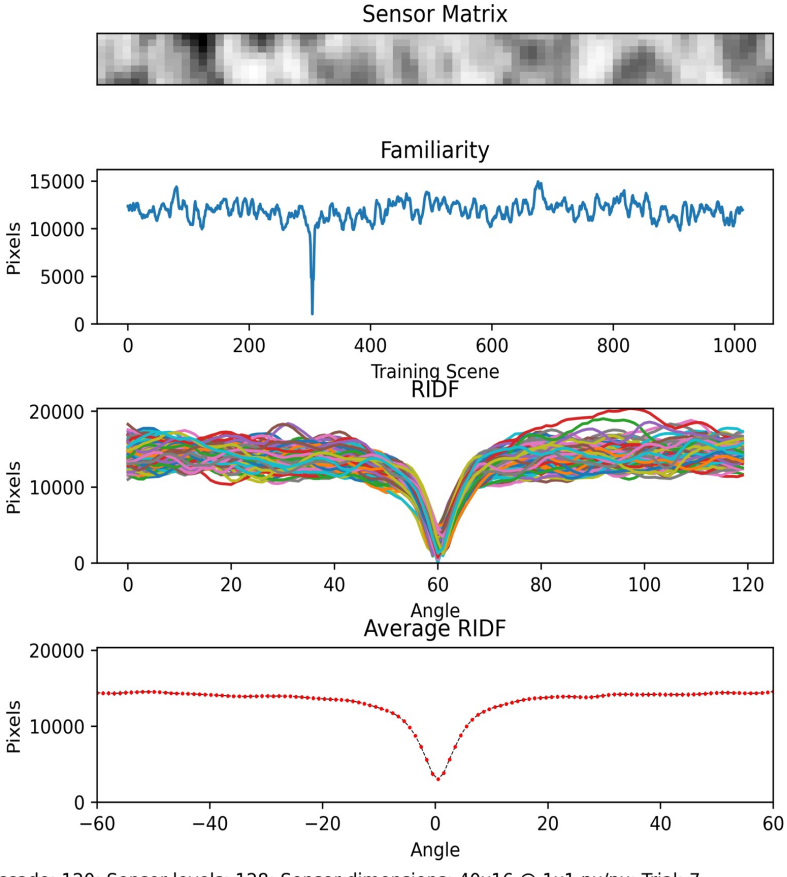




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

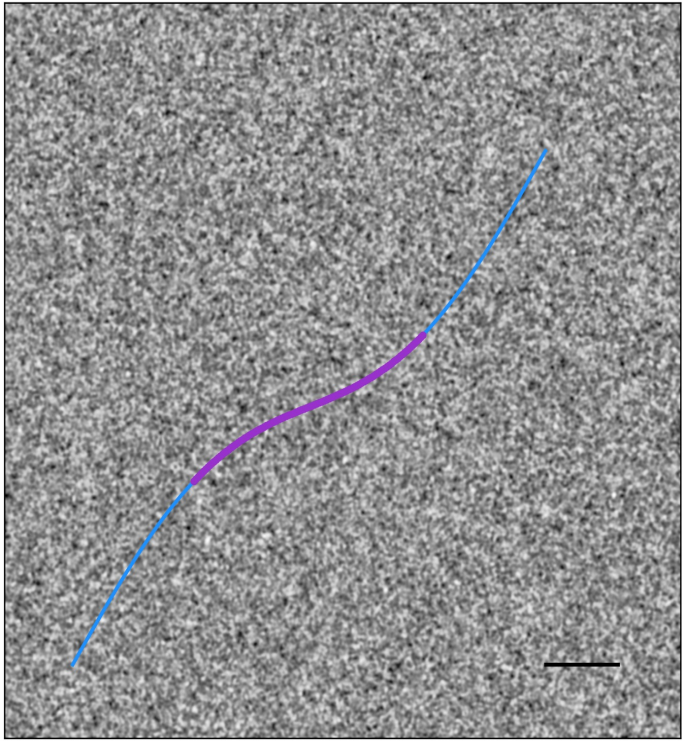
Navigation stats: RMSD error: 50.60; RMSD/dist: 0.127; TD: 9112; p90: 16; p50: 6; complete: 0

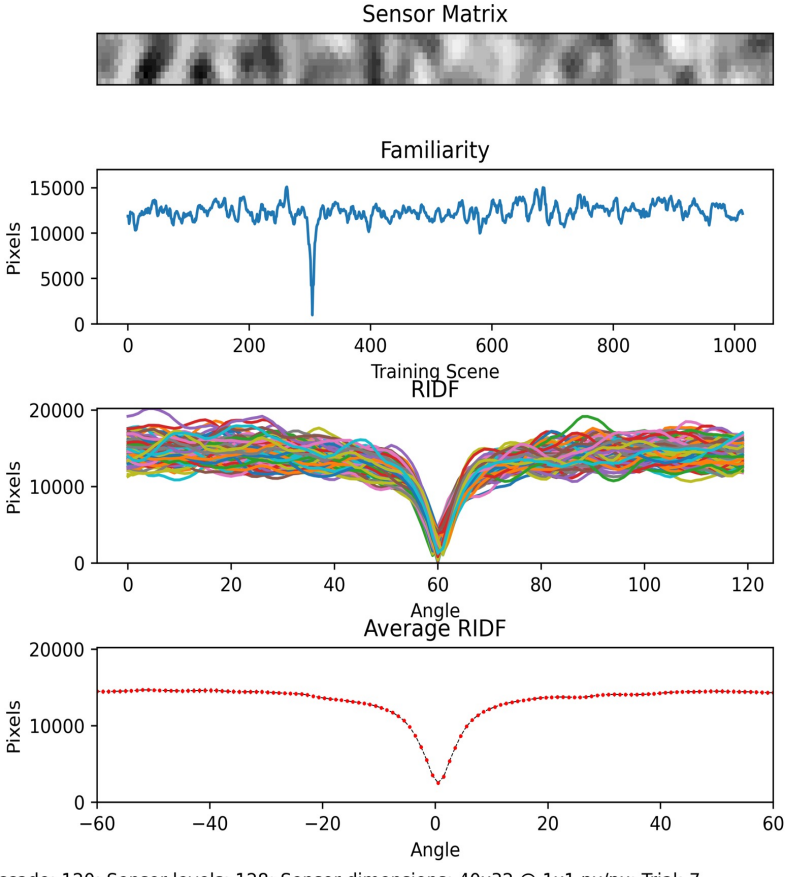




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

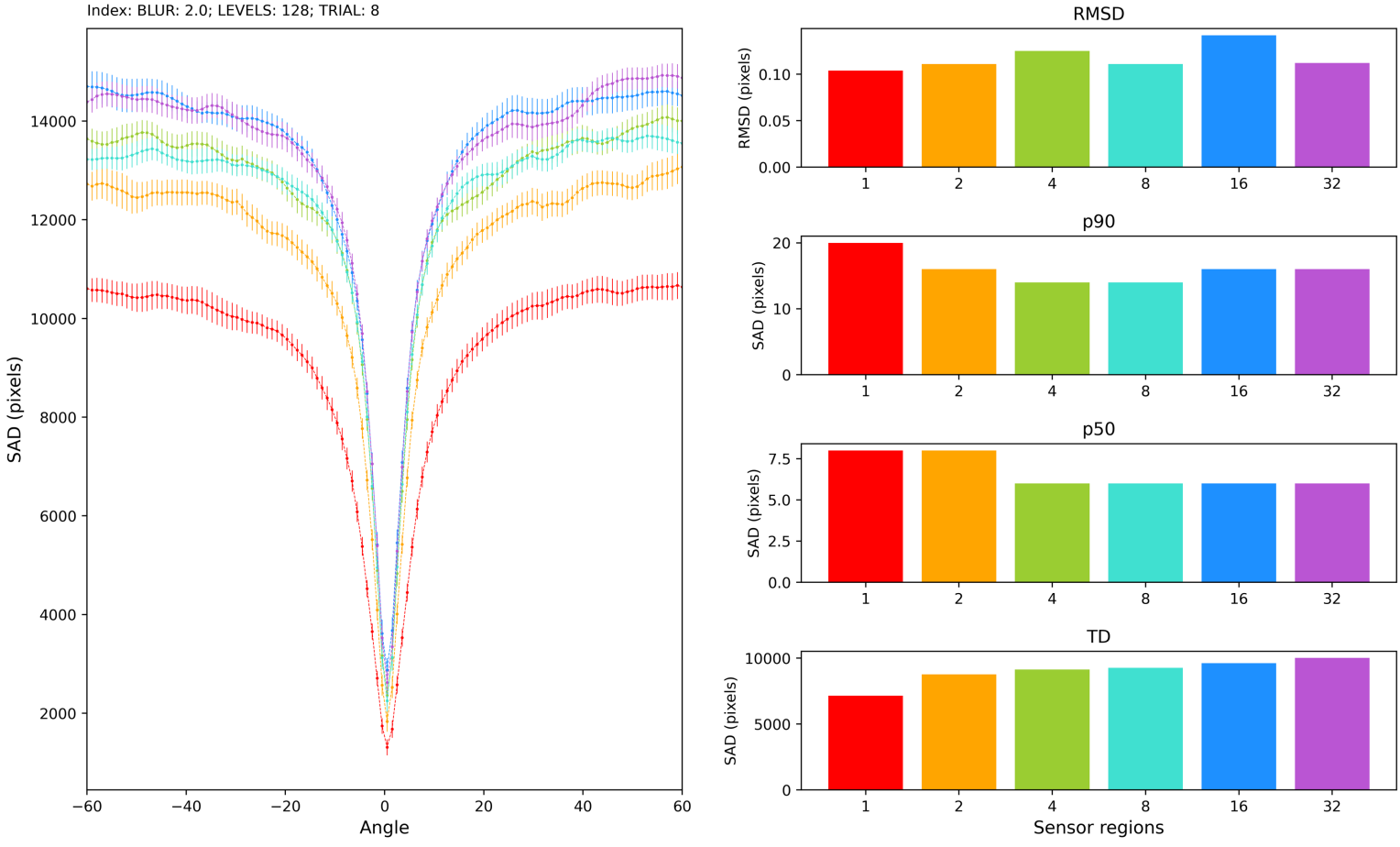
Navigation stats: RMSD error: 59.70; RMSD/dist: 0.149; TD: 9389; p90: 14; p50: 6; complete: 0

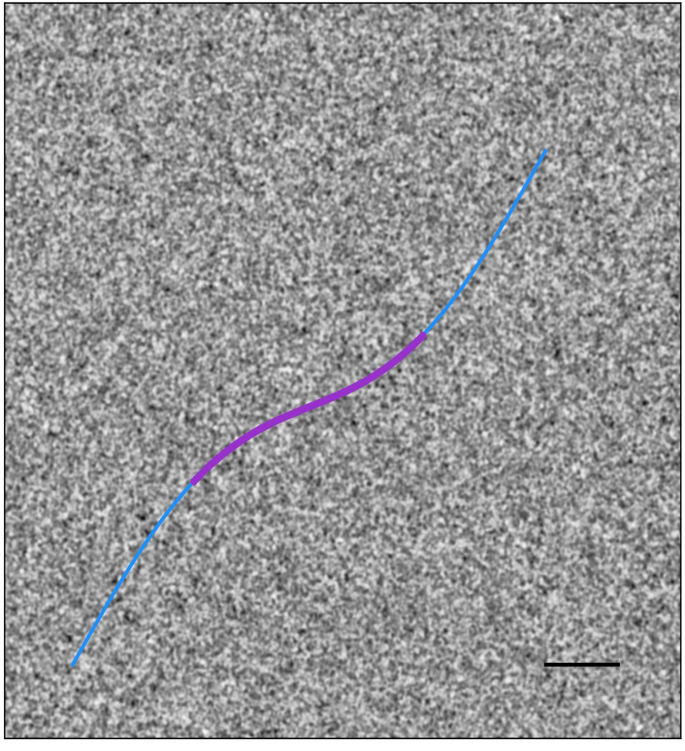


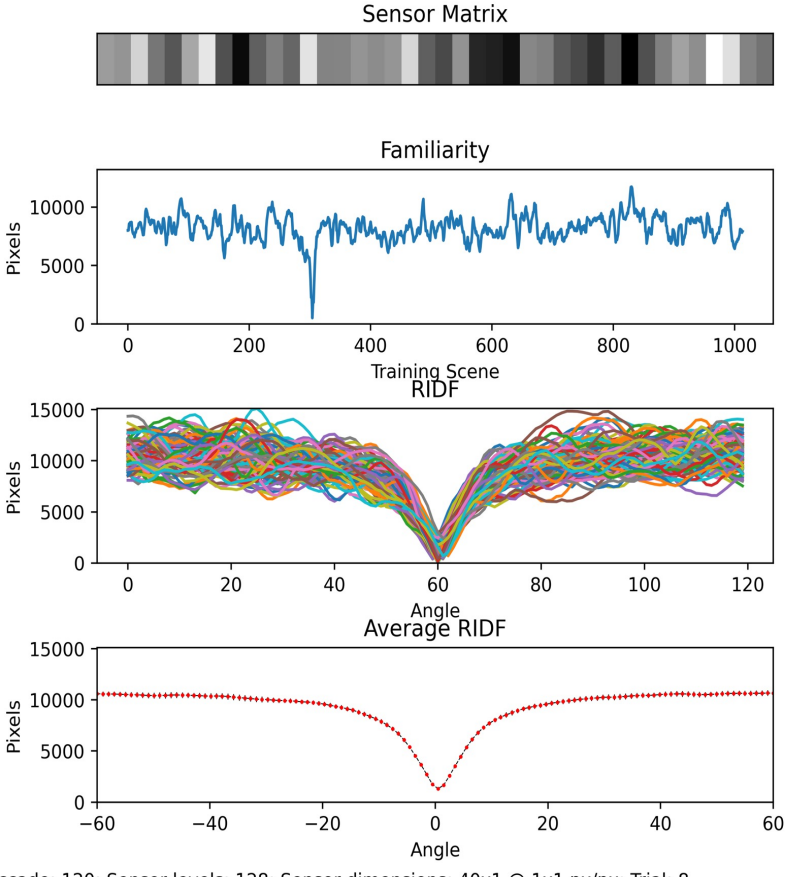


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 41.69; RMSD/dist: 0.104; TD: 10084; p90: 16; p50: 6; complete: 0

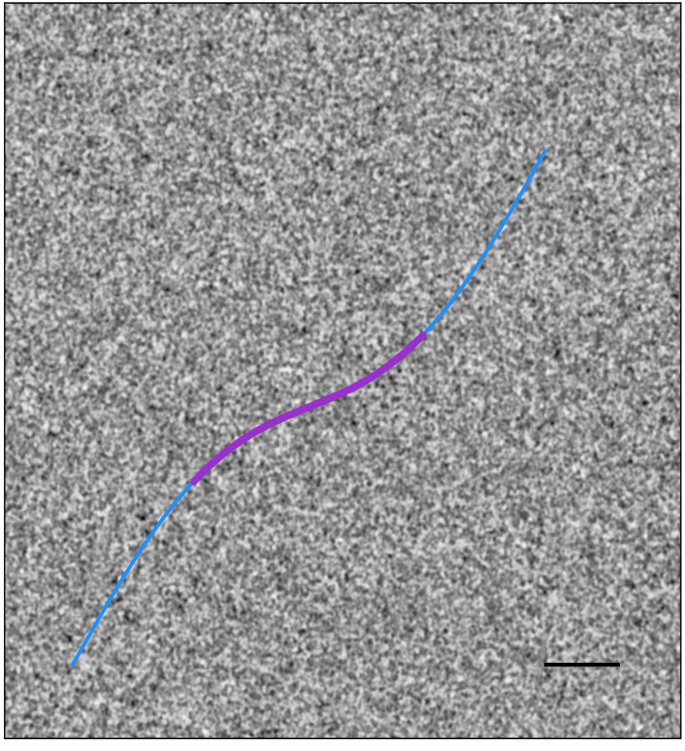

Index: BLUR: 2.0; LEVELS: 128; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

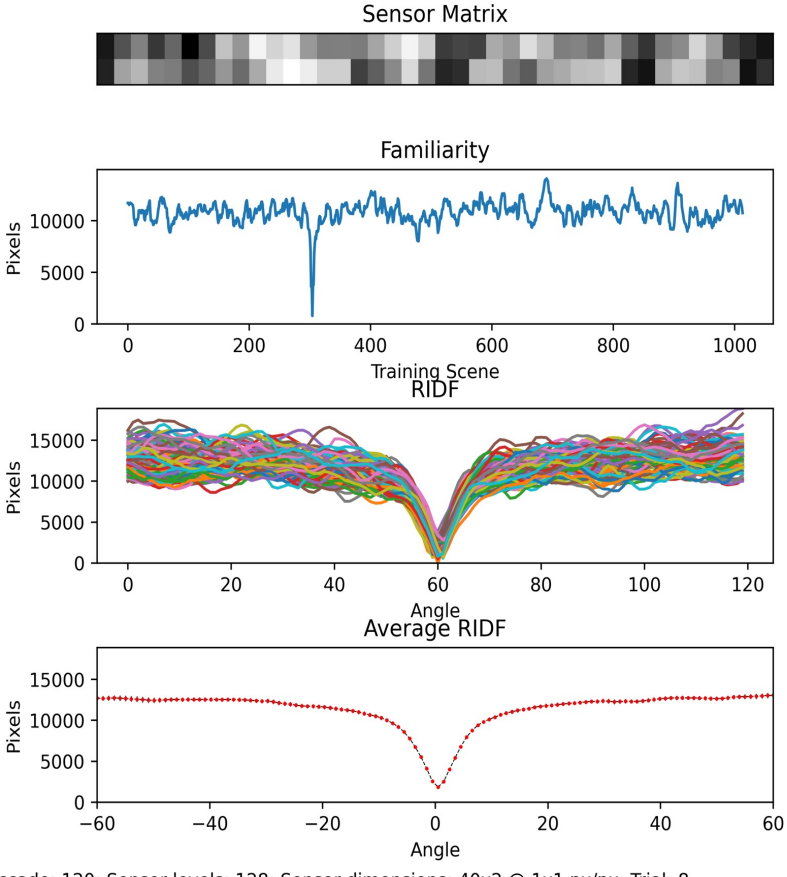




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

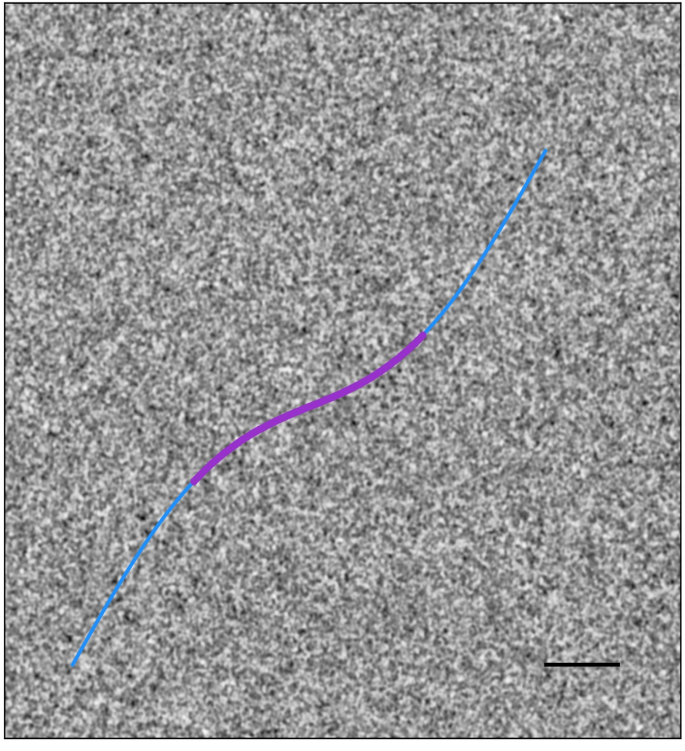
Navigation stats: RMSD error: 41.62; RMSD/dist: 0.104; TD: 7153; p90: 20; p50: 8; complete: 0

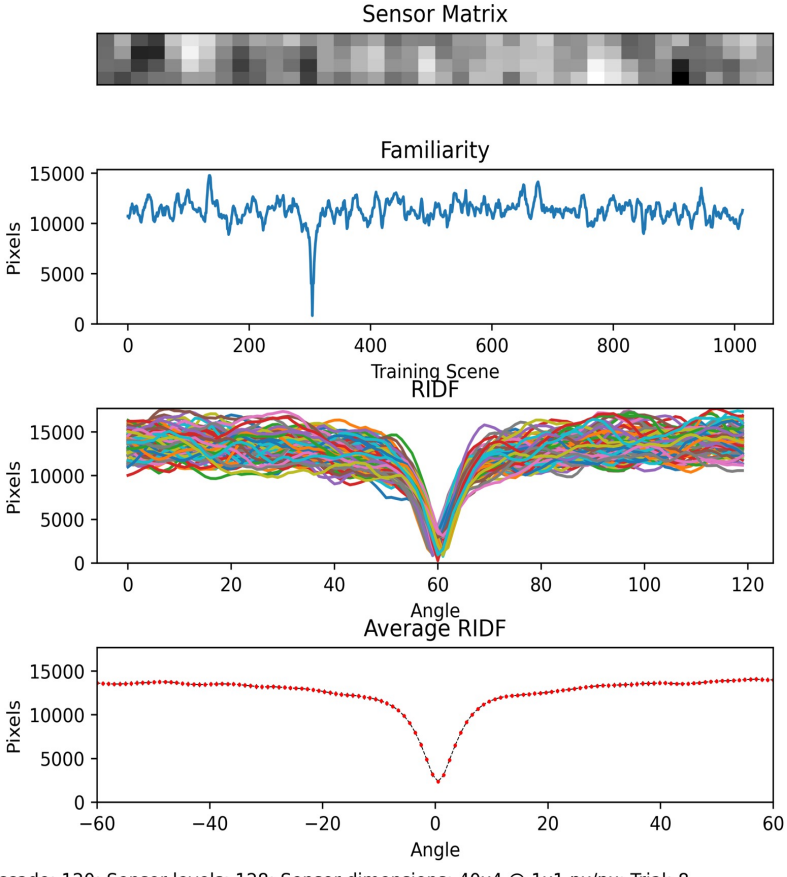




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

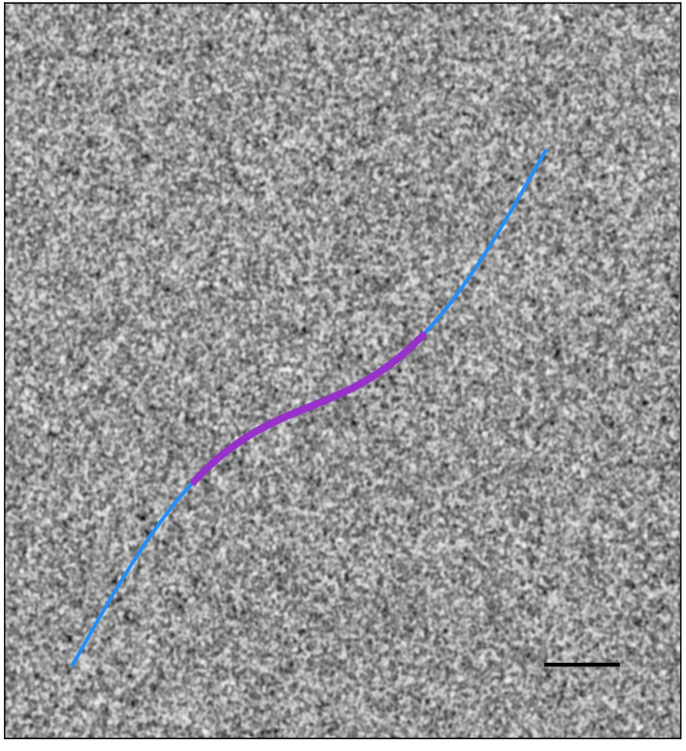
Navigation stats: RMSD error: 44.38; RMSD/dist: 0.111; TD: 8774; p90: 16; p50: 8; complete: 0

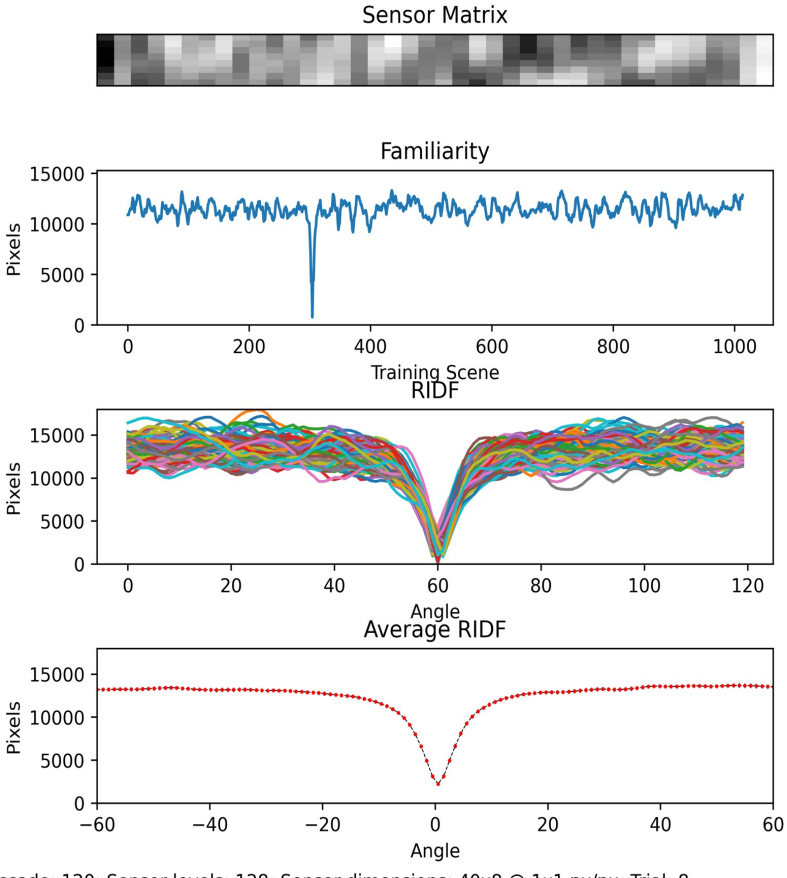




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

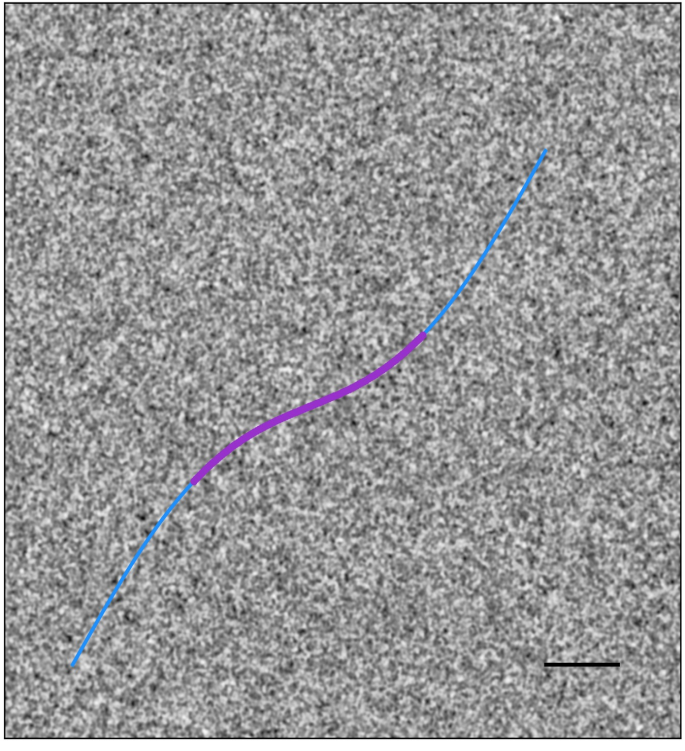
Navigation stats: RMSD error: 49.92; RMSD/dist: 0.125; TD: 9141; p90: 14; p50: 6; complete: 0

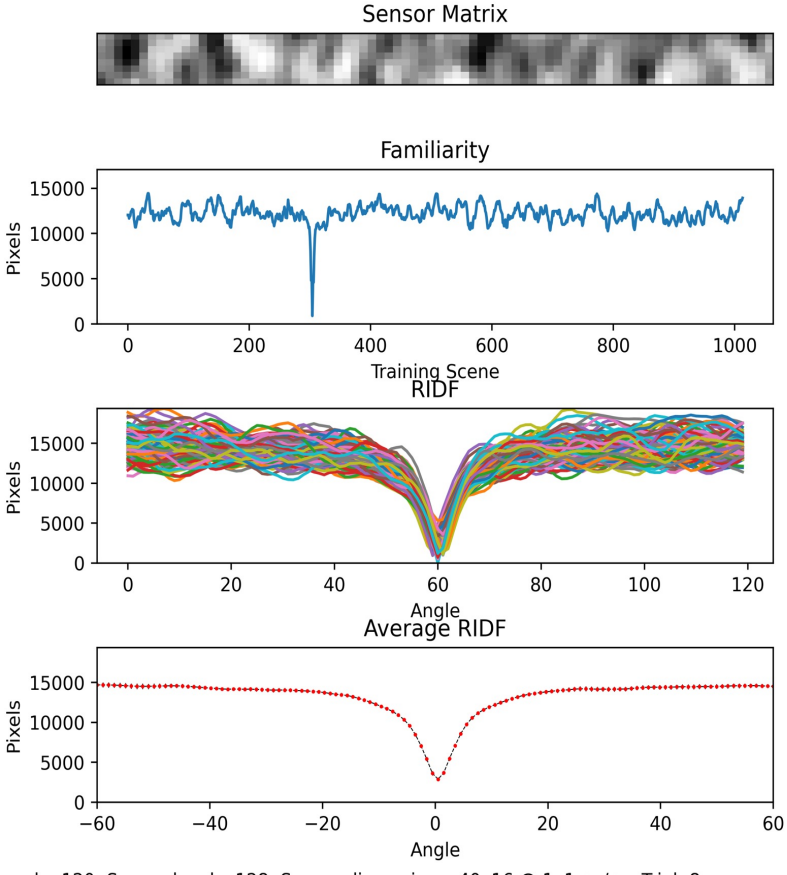




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

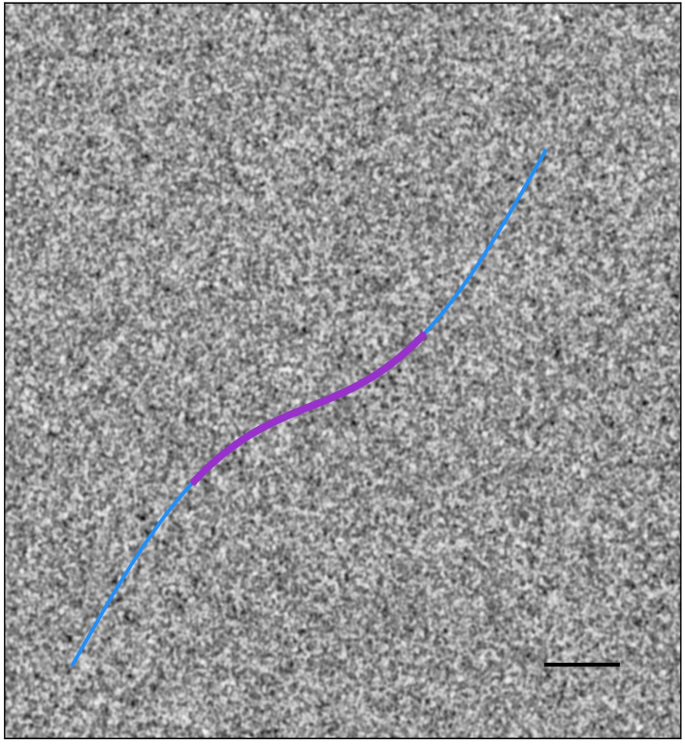
Navigation stats: RMSD error: 44.31; RMSD/dist: 0.111; TD: 9265; p90: 14; p50: 6; complete: 0

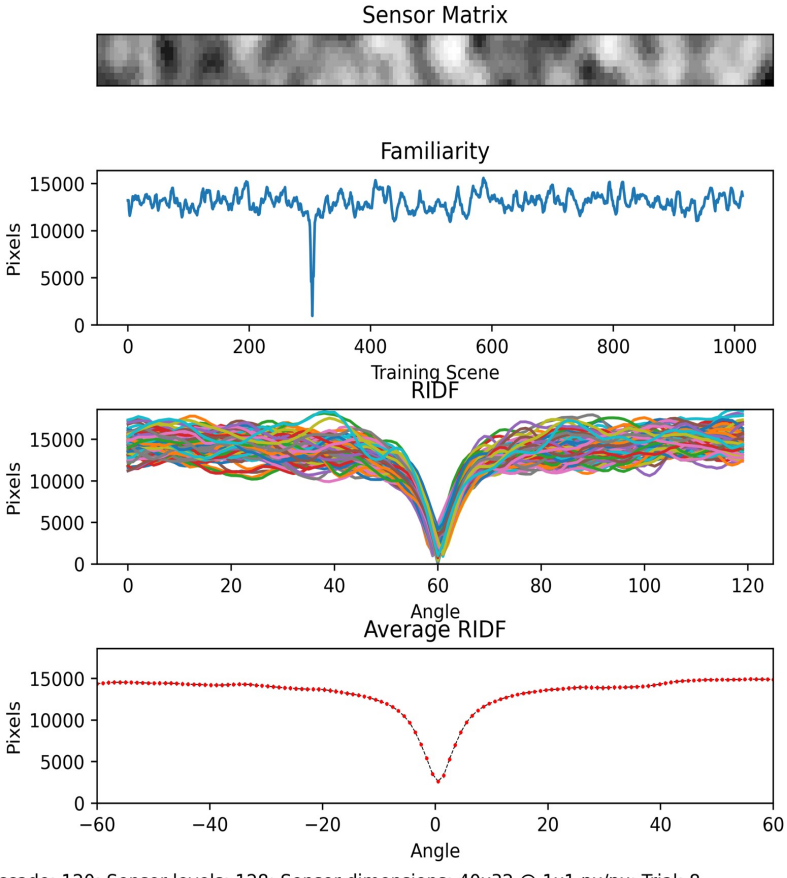




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

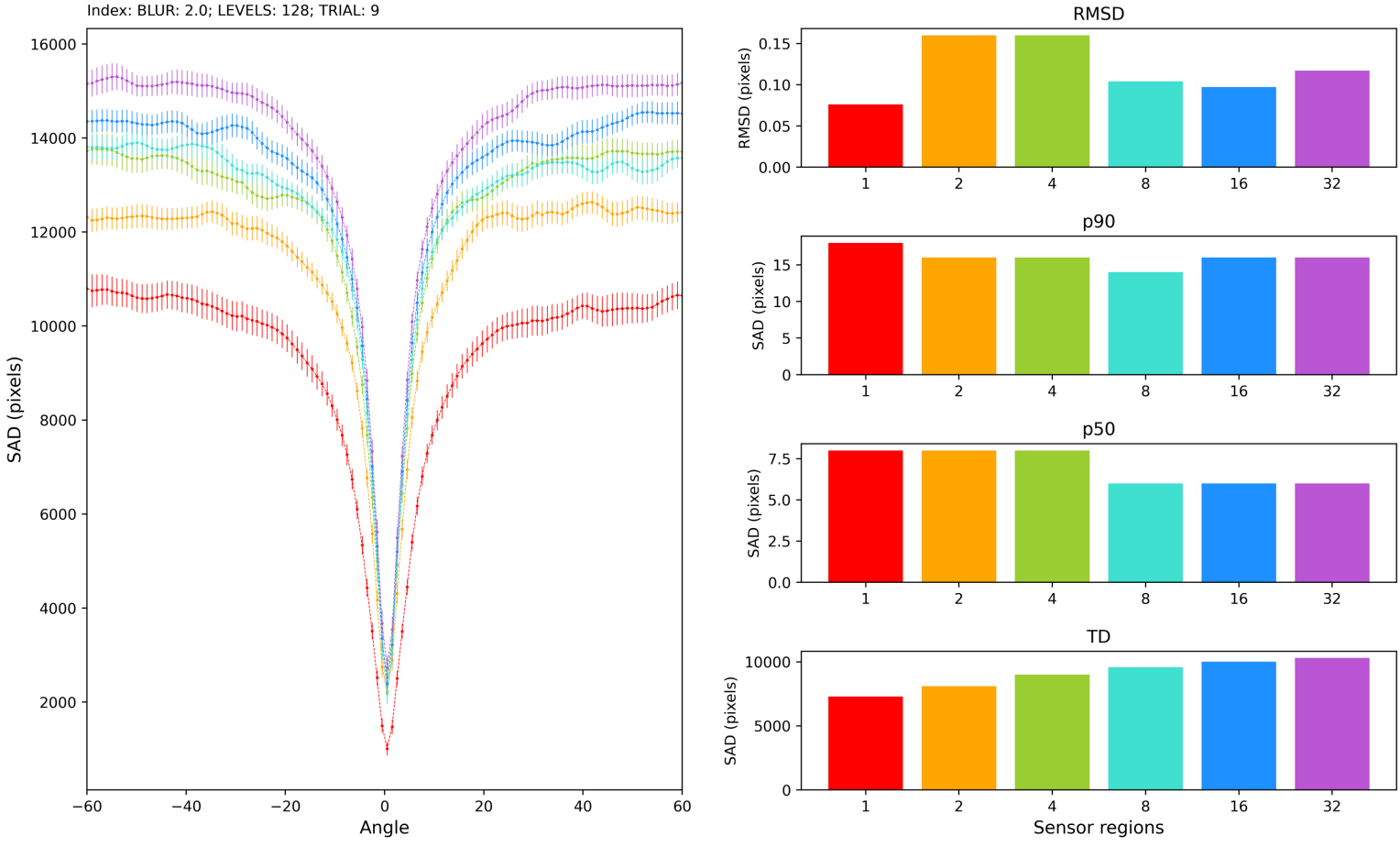
Navigation stats: RMSD error: 56.95; RMSD/dist: 0.142; TD: 9616; p90: 16; p50: 6; complete: 0

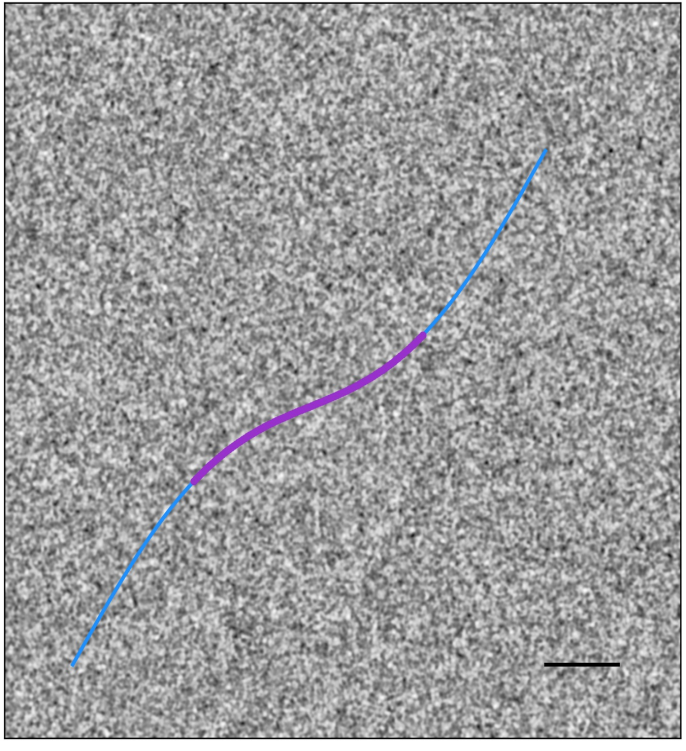


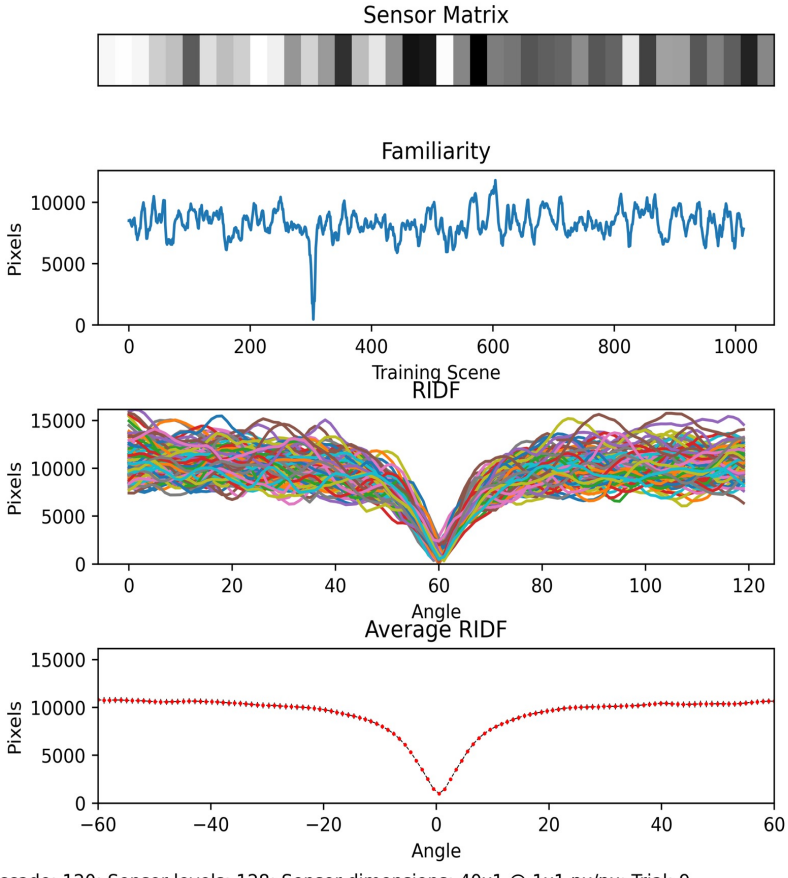


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 44.70; RMSD/dist: 0.112; TD: 10013; p90: 16; p50: 6; complete: 0

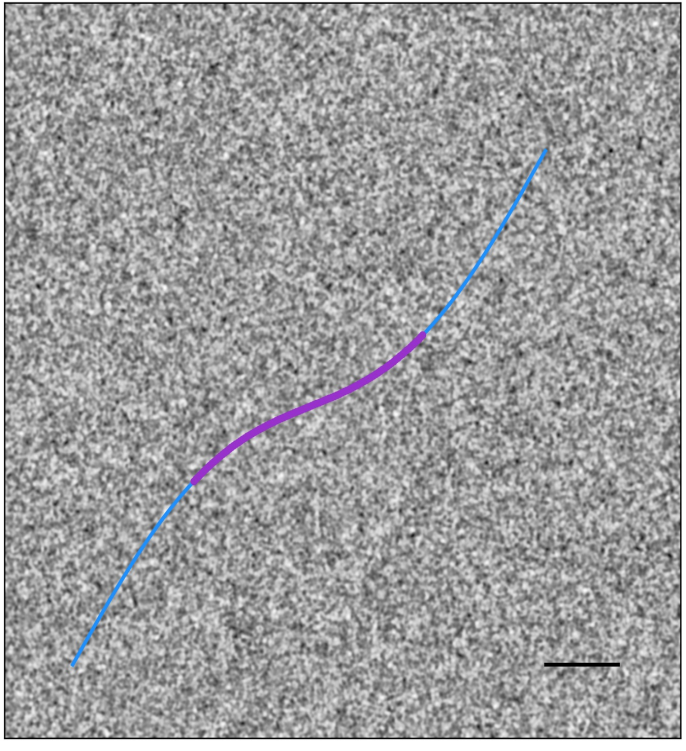

Index: BLUR: 2.0; LEVELS: 128; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

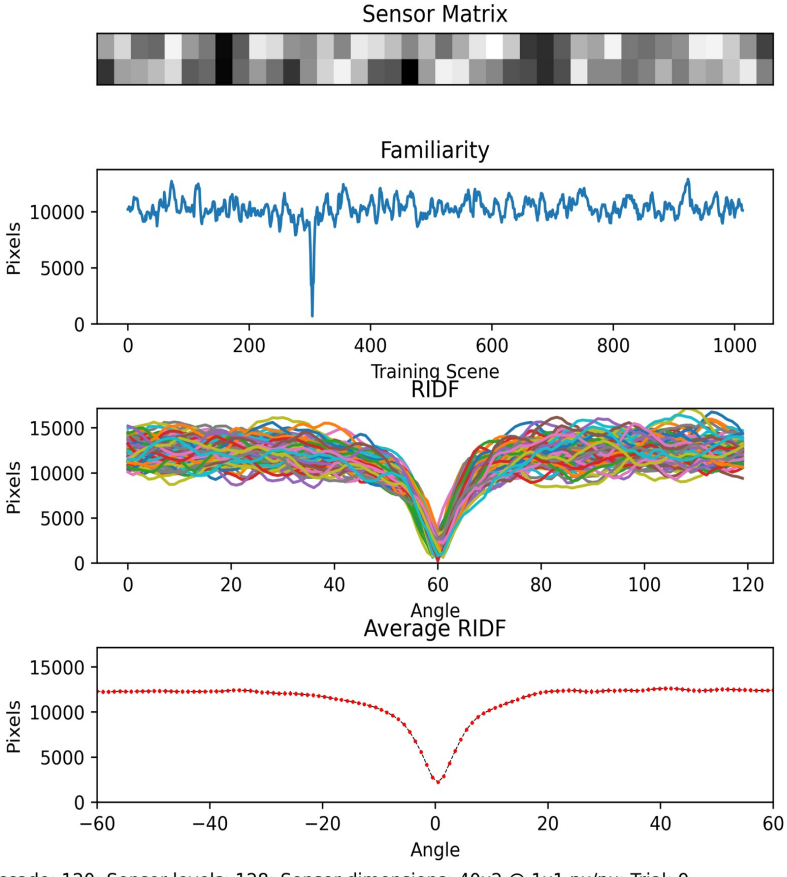




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

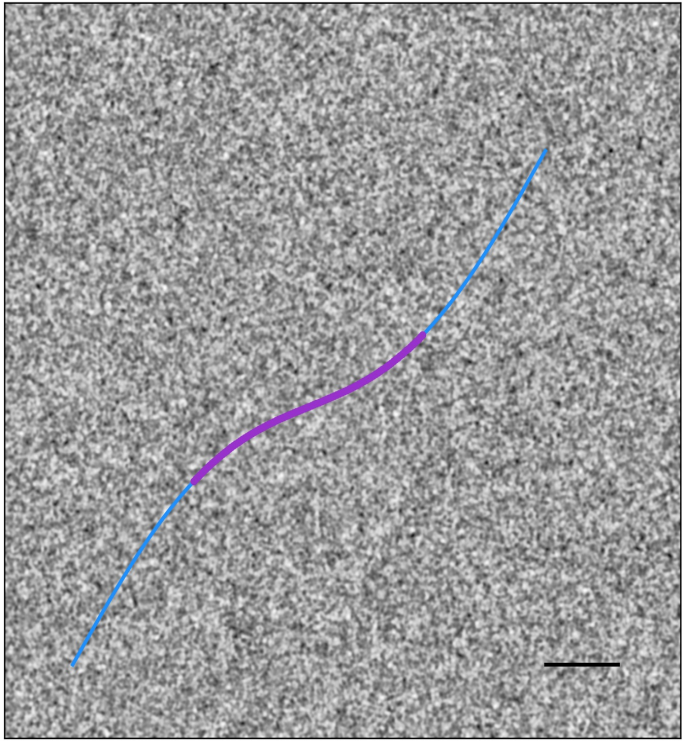
Navigation stats: RMSD error: 30.36; RMSD/dist: 0.076; TD: 7285; p90: 18; p50: 8; complete: 0

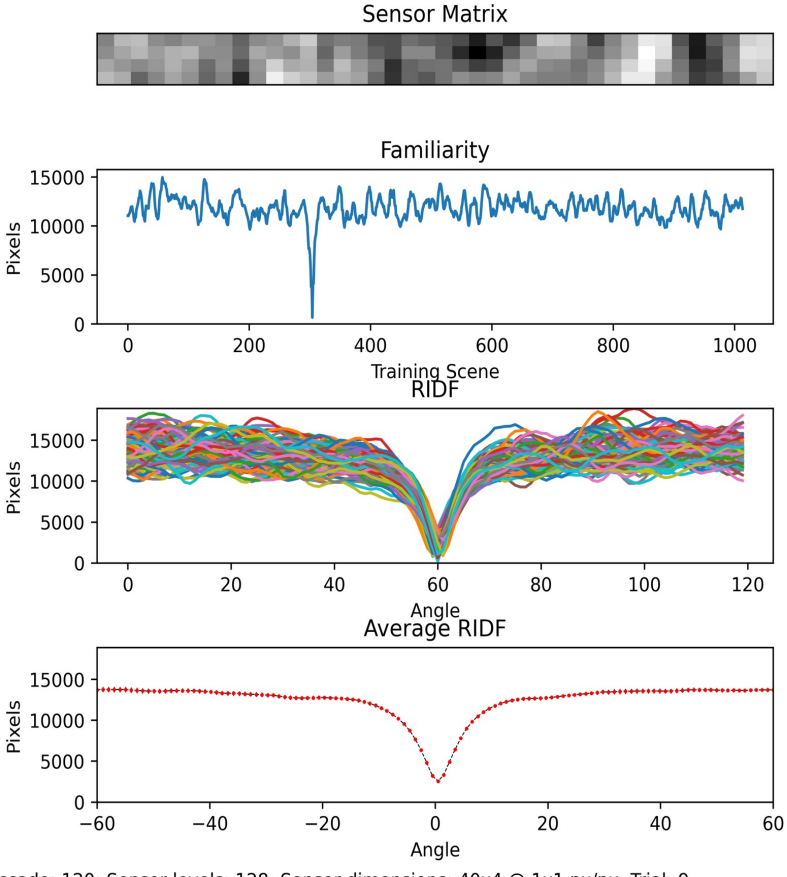




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

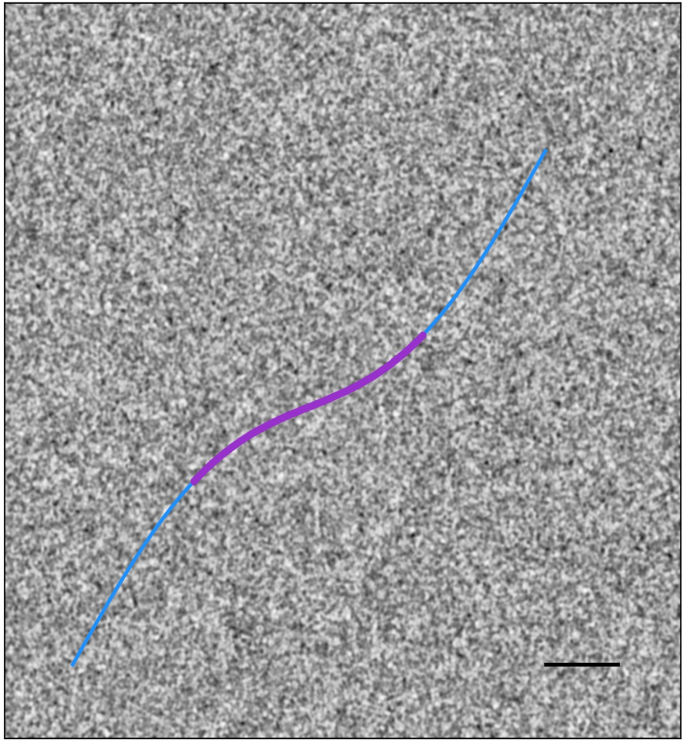
Navigation stats: RMSD error: 63.87; RMSD/dist: 0.160; TD: 8100; p90: 16; p50: 8; complete: 0

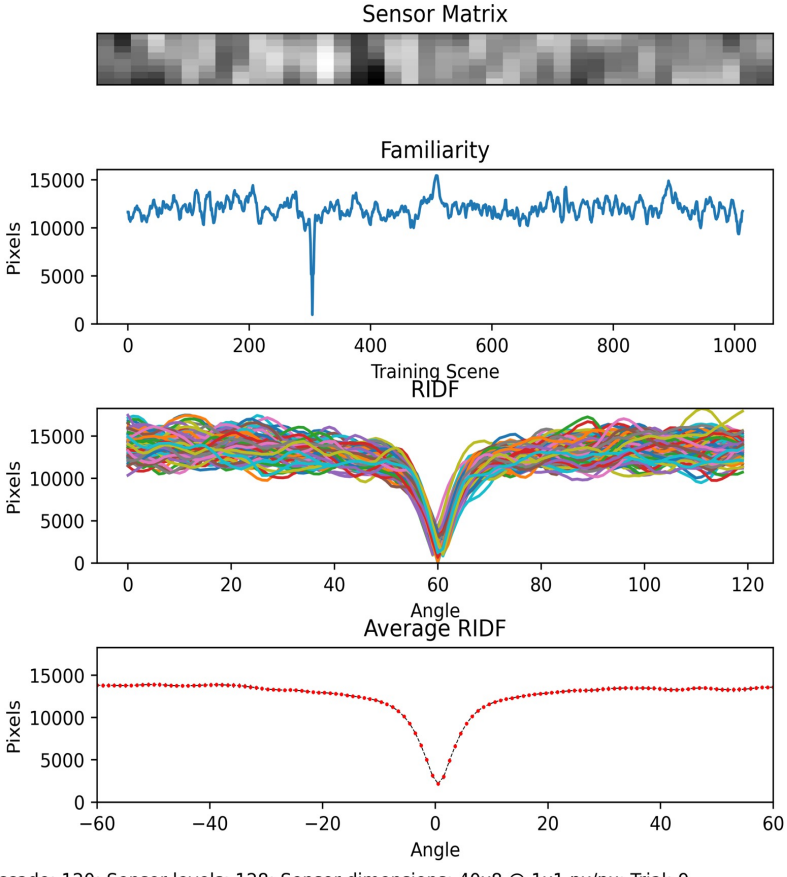




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

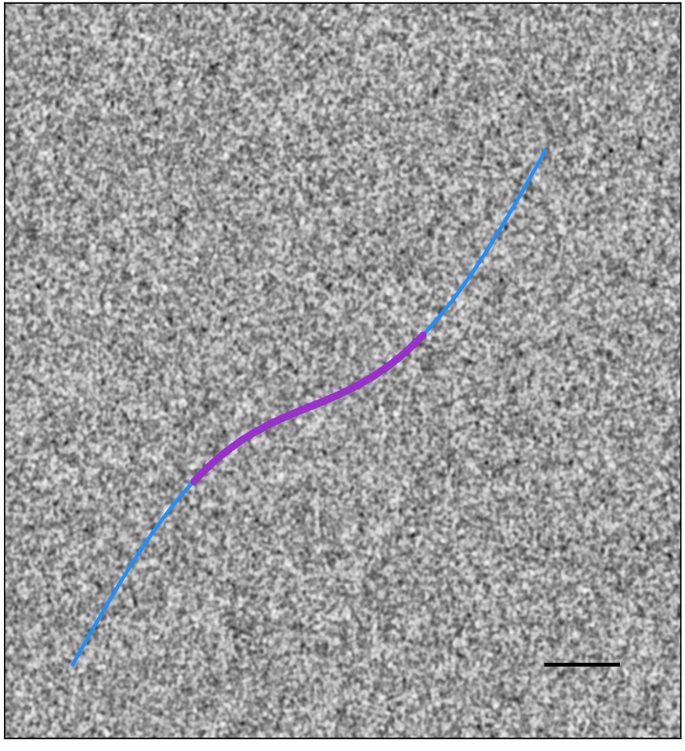
Navigation stats: RMSD error: 64.08; RMSD/dist: 0.160; TD: 9010; p90: 16; p50: 8; complete: 0

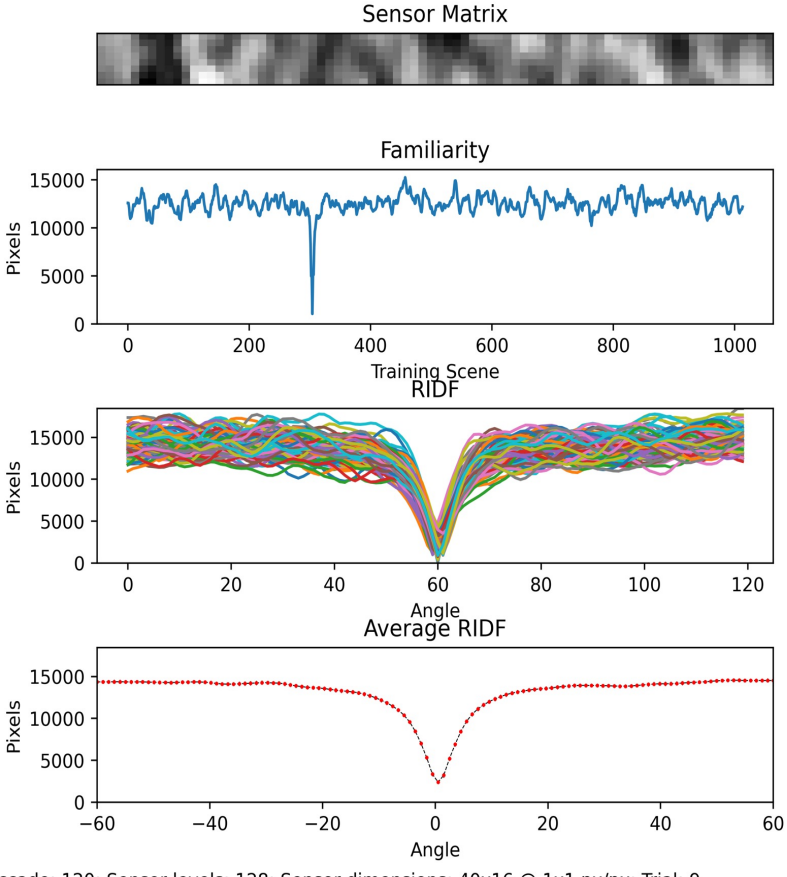




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

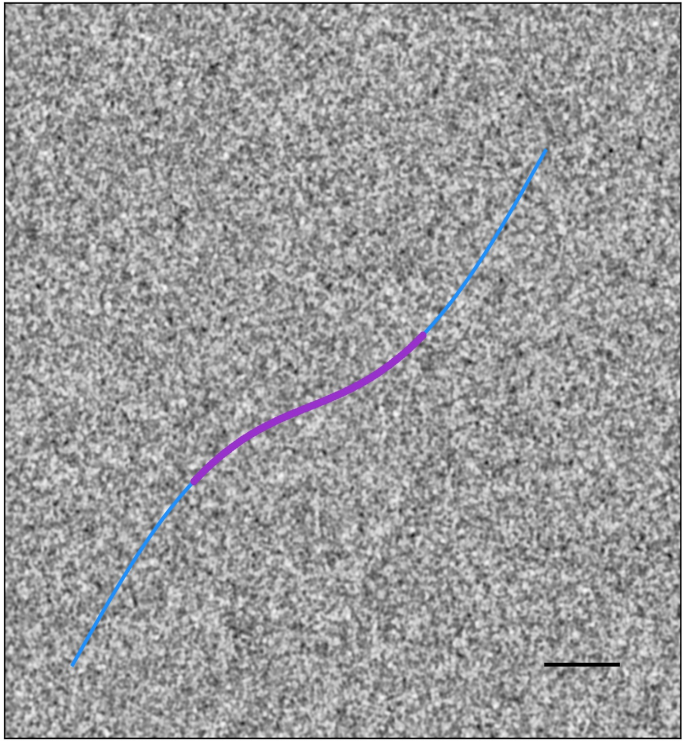
Navigation stats: RMSD error: 41.68; RMSD/dist: 0.104; TD: 9585; p90: 14; p50: 6; complete: 0

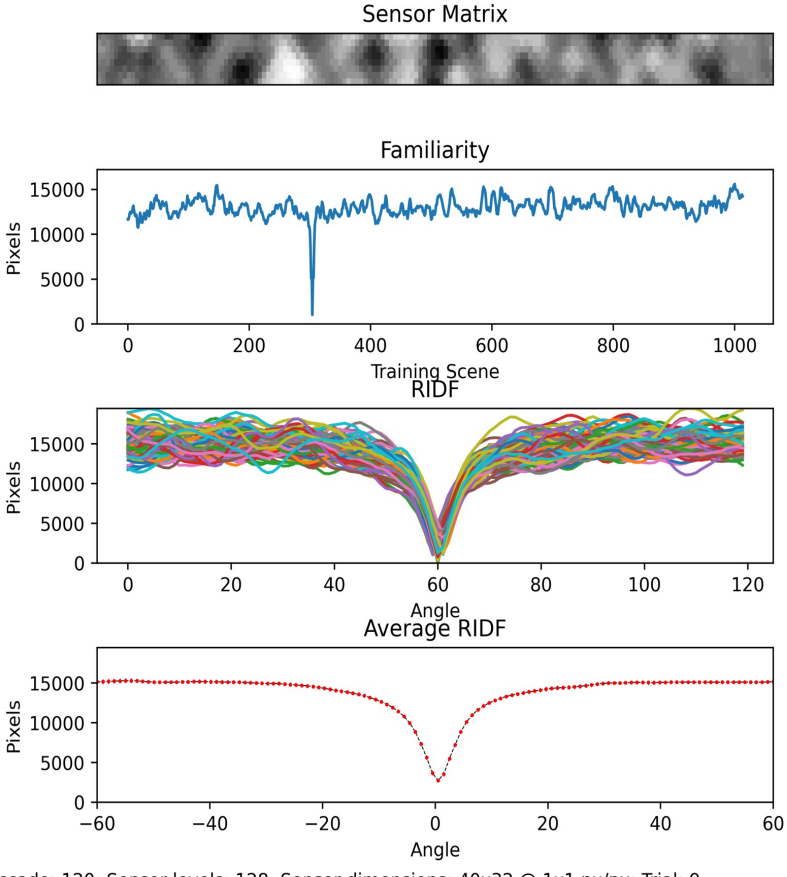




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

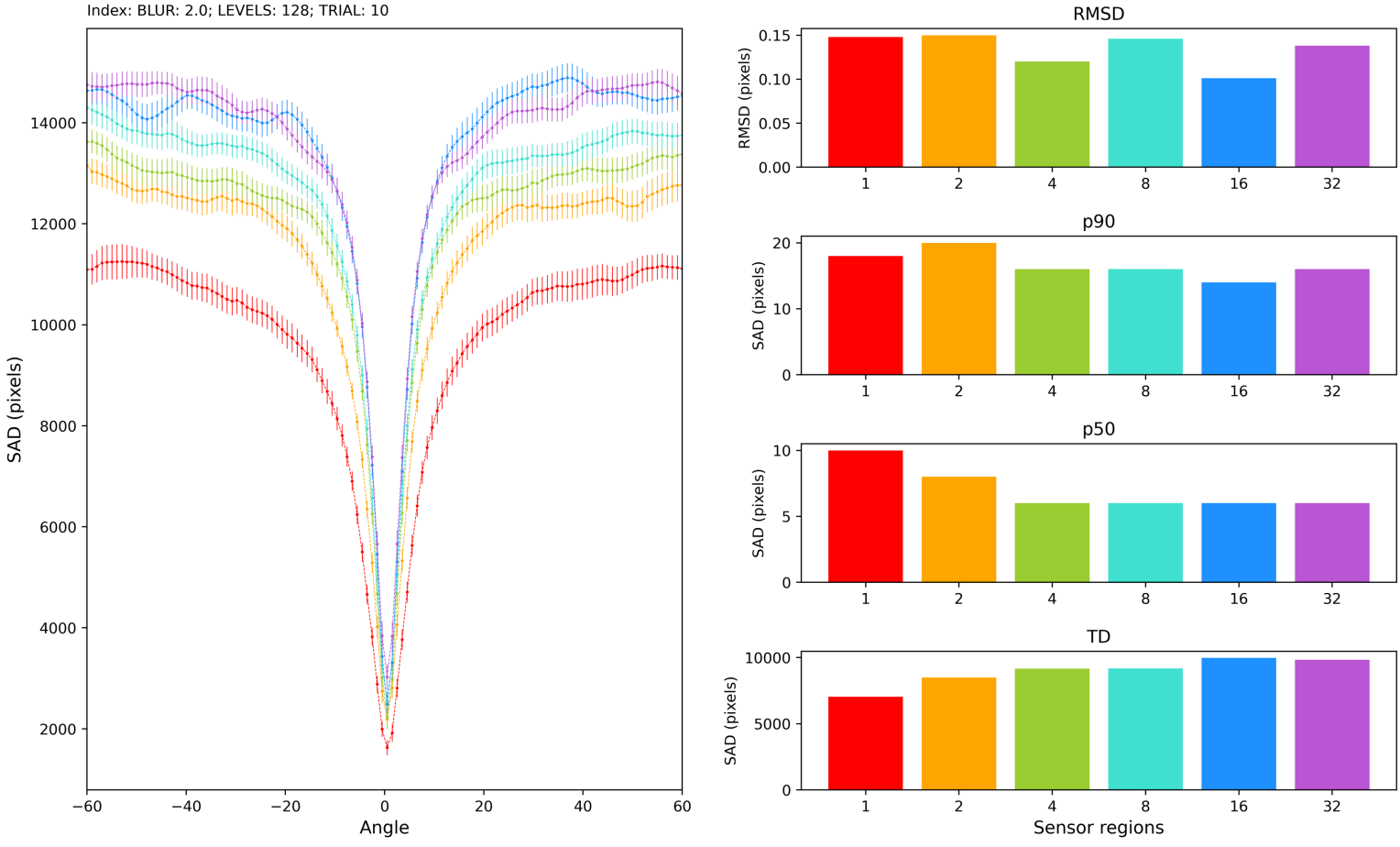
Navigation stats: RMSD error: 38.93; RMSD/dist: 0.097; TD: 10013; p90: 16; p50: 6; complete: 0

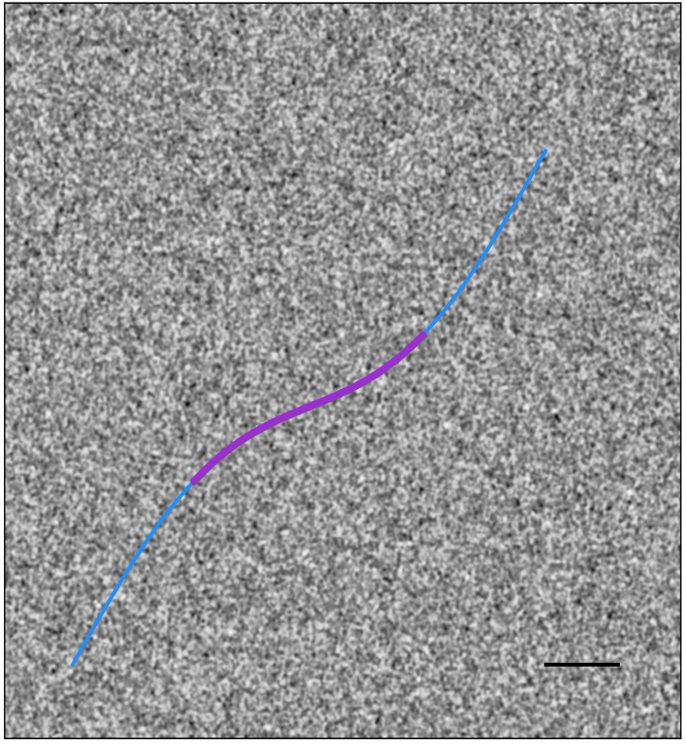


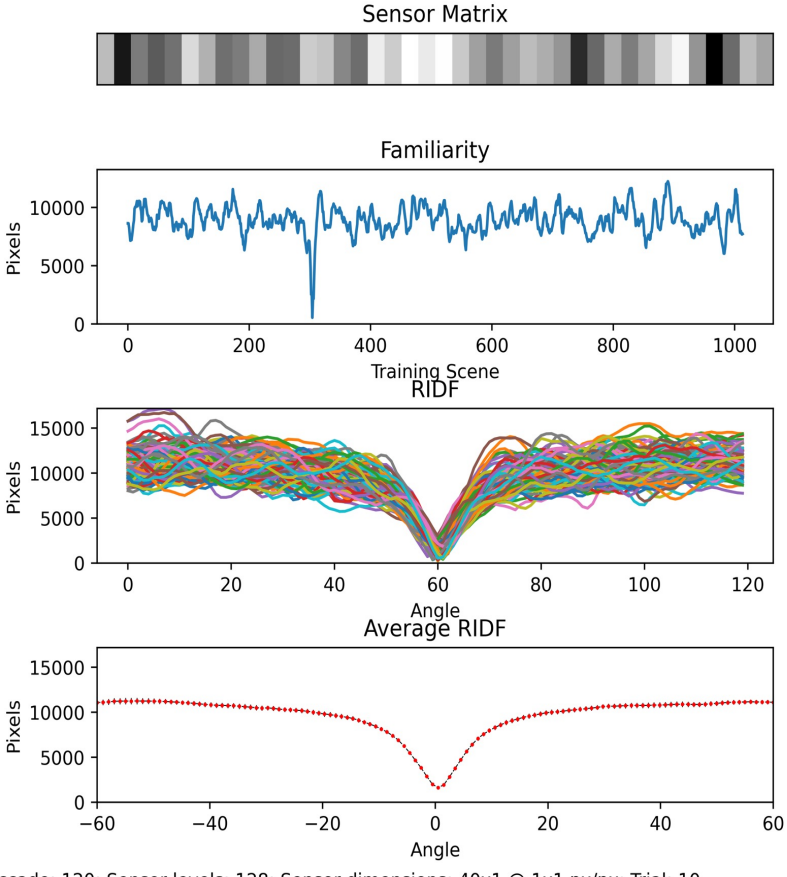


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 46.90; RMSD/dist: 0.117; TD: 10298; p90: 16; p50: 6; complete: 0

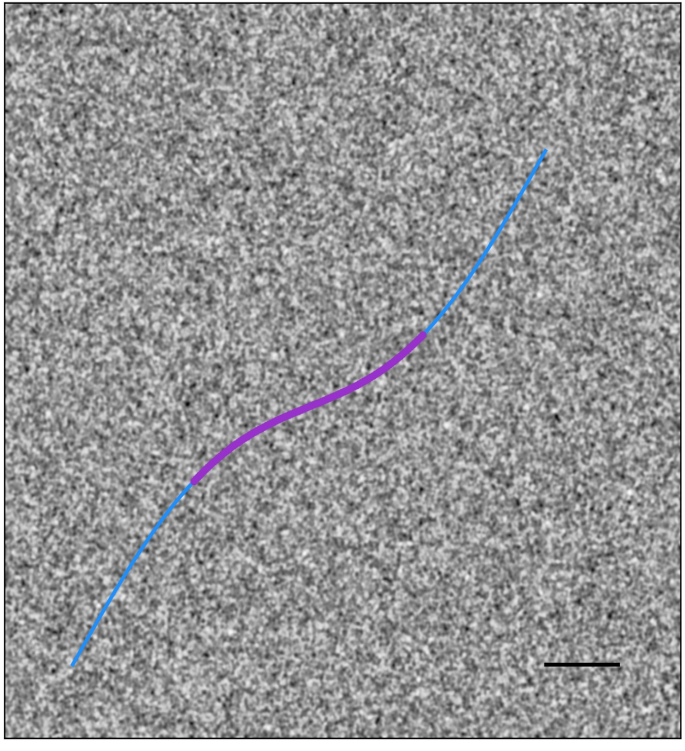

Index: BLUR: 2.0; LEVELS: 128; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

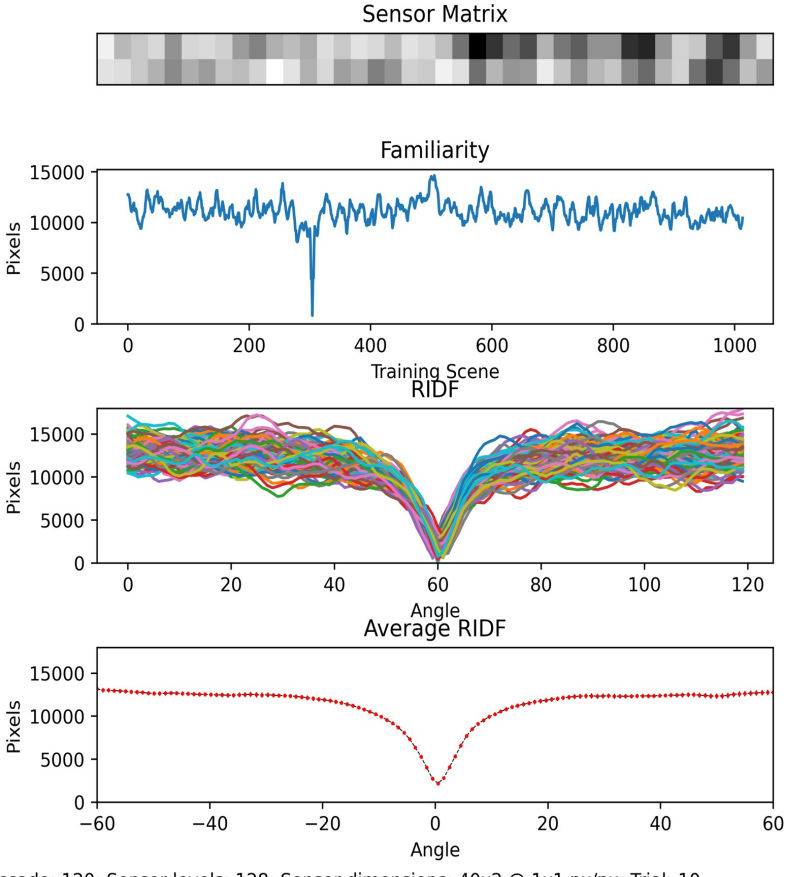




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

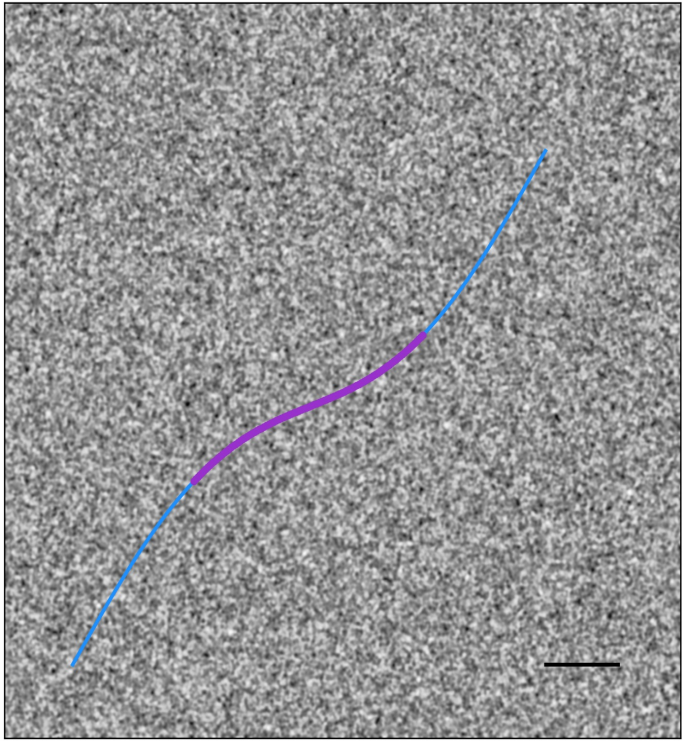
Navigation stats: RMSD error: 59.36; RMSD/dist: 0.148; TD: 7030; p90: 18; p50: 10; complete: 0

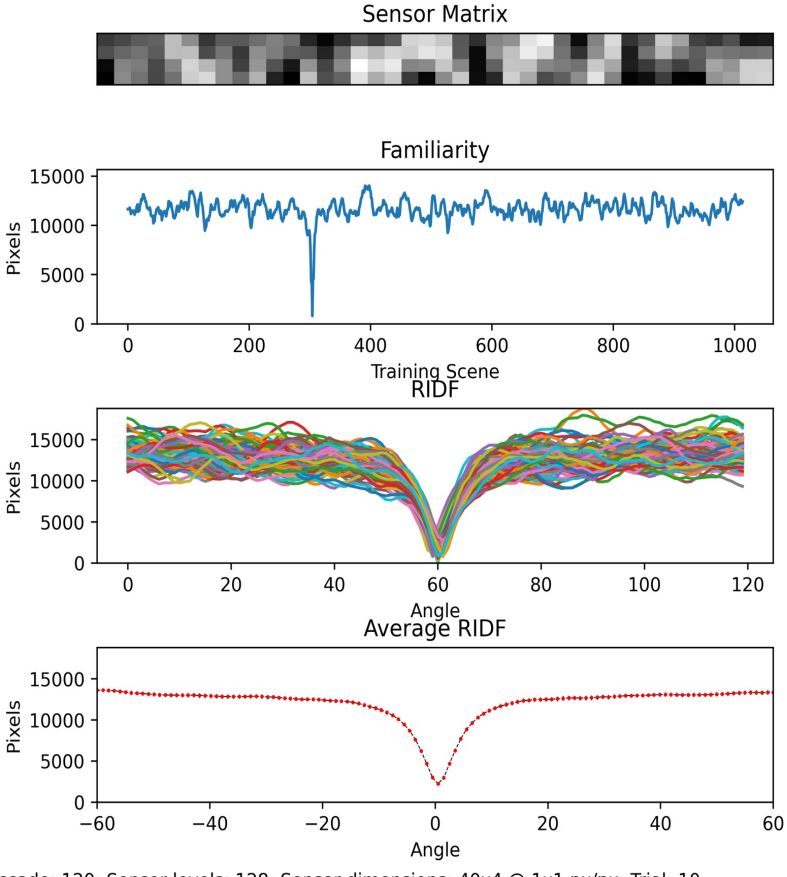




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

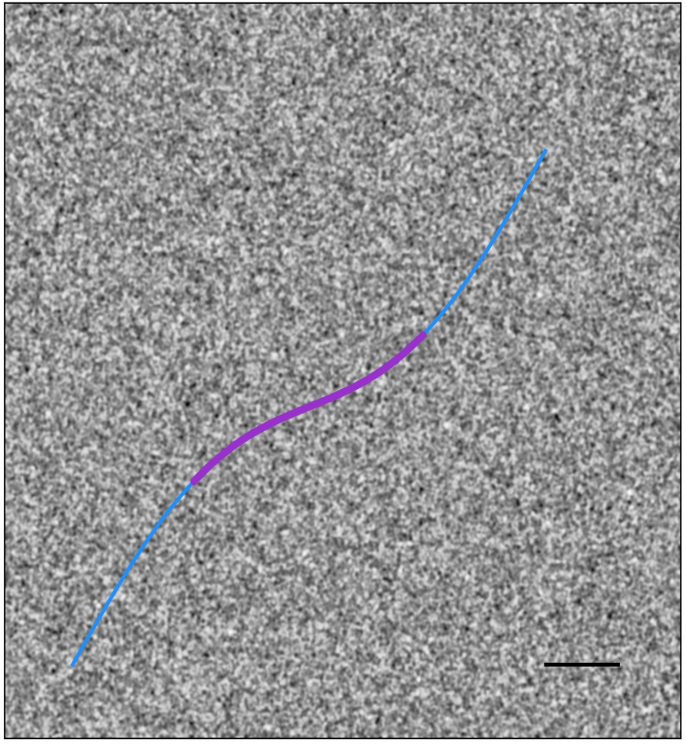
Navigation stats: RMSD error: 59.91; RMSD/dist: 0.150; TD: 8494; p90: 20; p50: 8; complete: 0

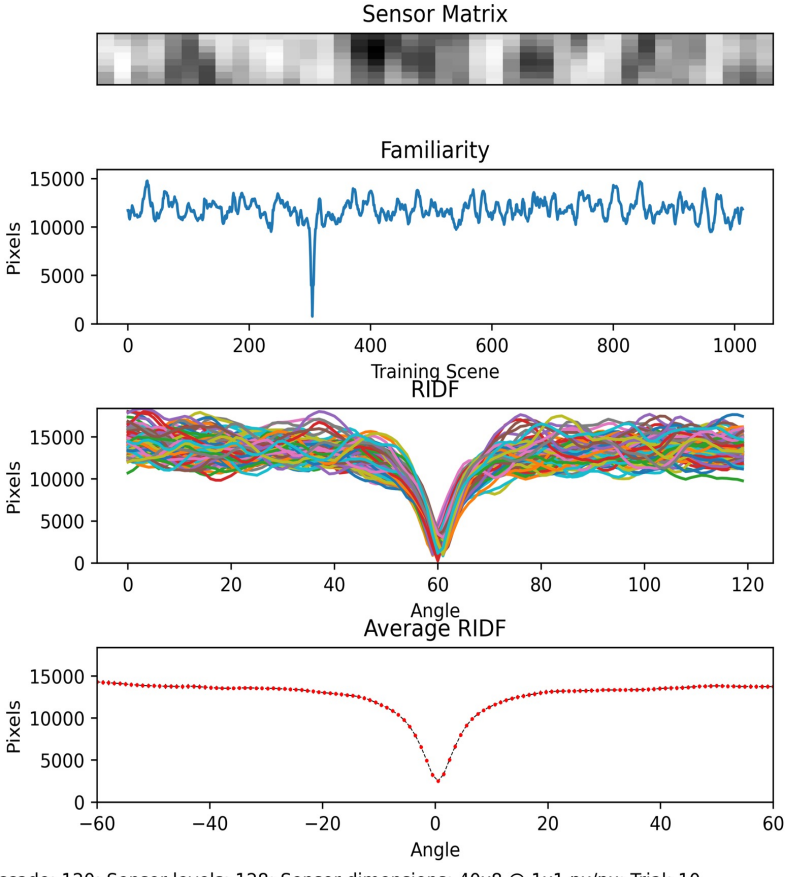




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

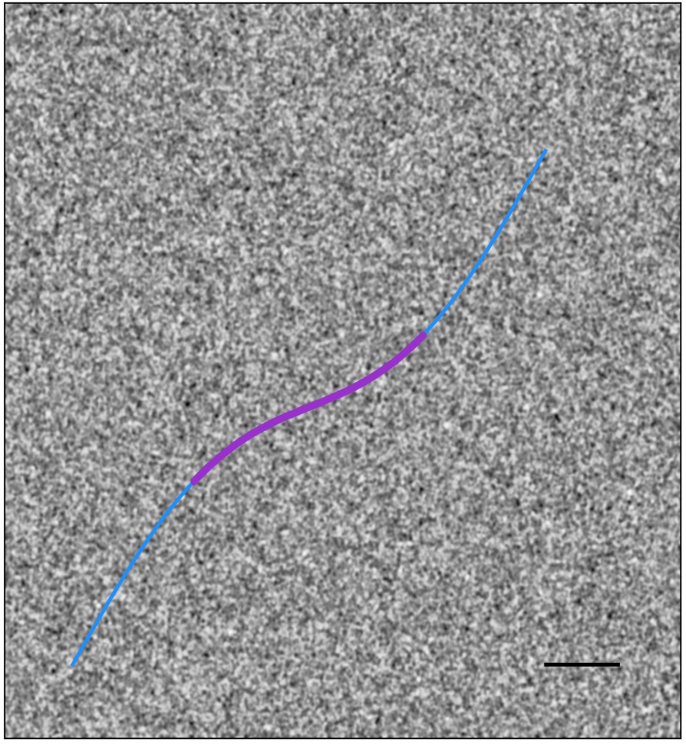
Navigation stats: RMSD error: 47.97; RMSD/dist: 0.120; TD: 9166; p90: 16; p50: 6; complete: 0

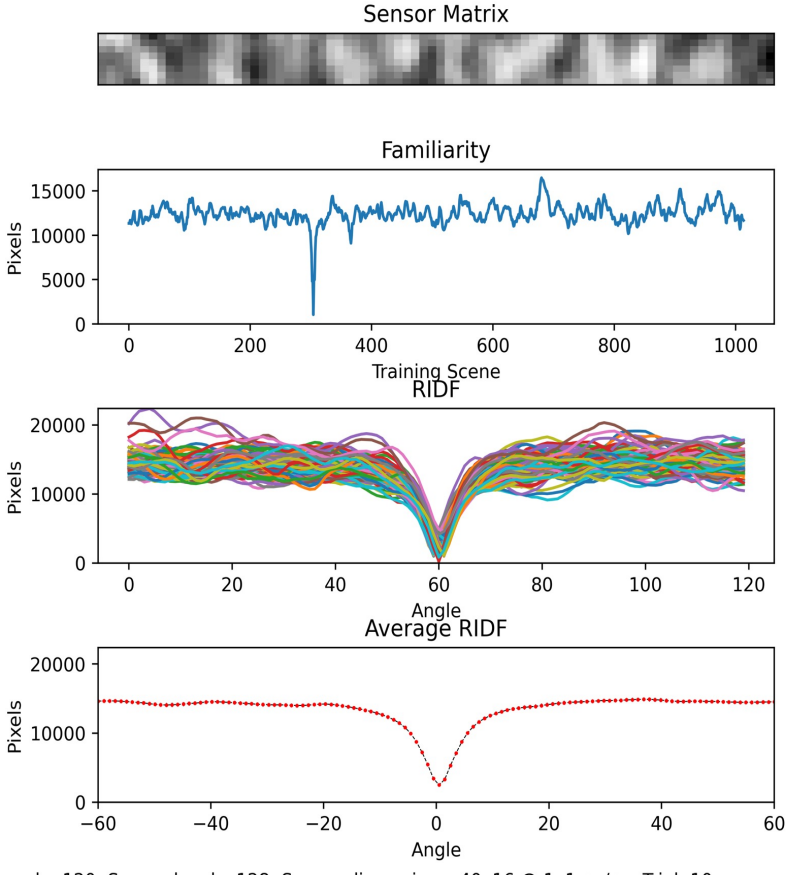




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

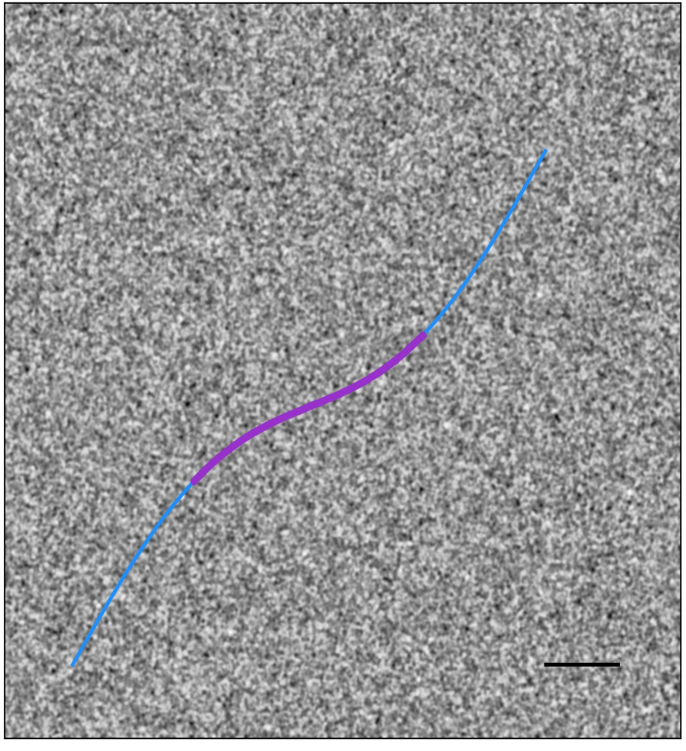
Navigation stats: RMSD error: 58.59; RMSD/dist: 0.146; TD: 9172; p90: 16; p50: 6; complete: 0

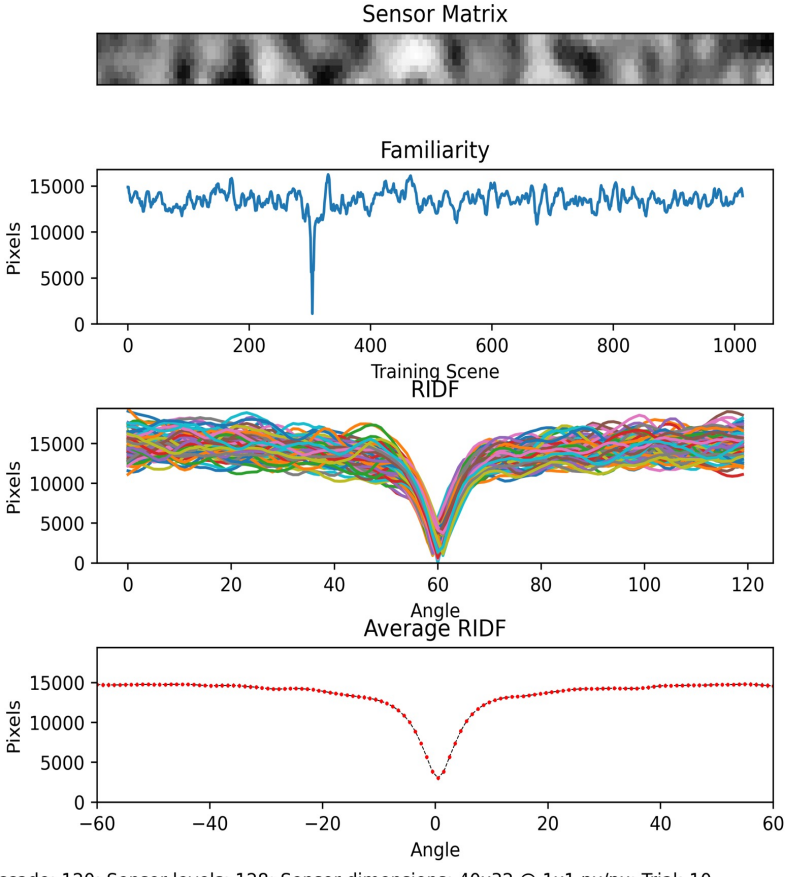




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 40.44; RMSD/dist: 0.101; TD: 9967; p90: 14; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 55.35; RMSD/dist: 0.138; TD: 9825; p90: 16; p50: 6; complete: 0