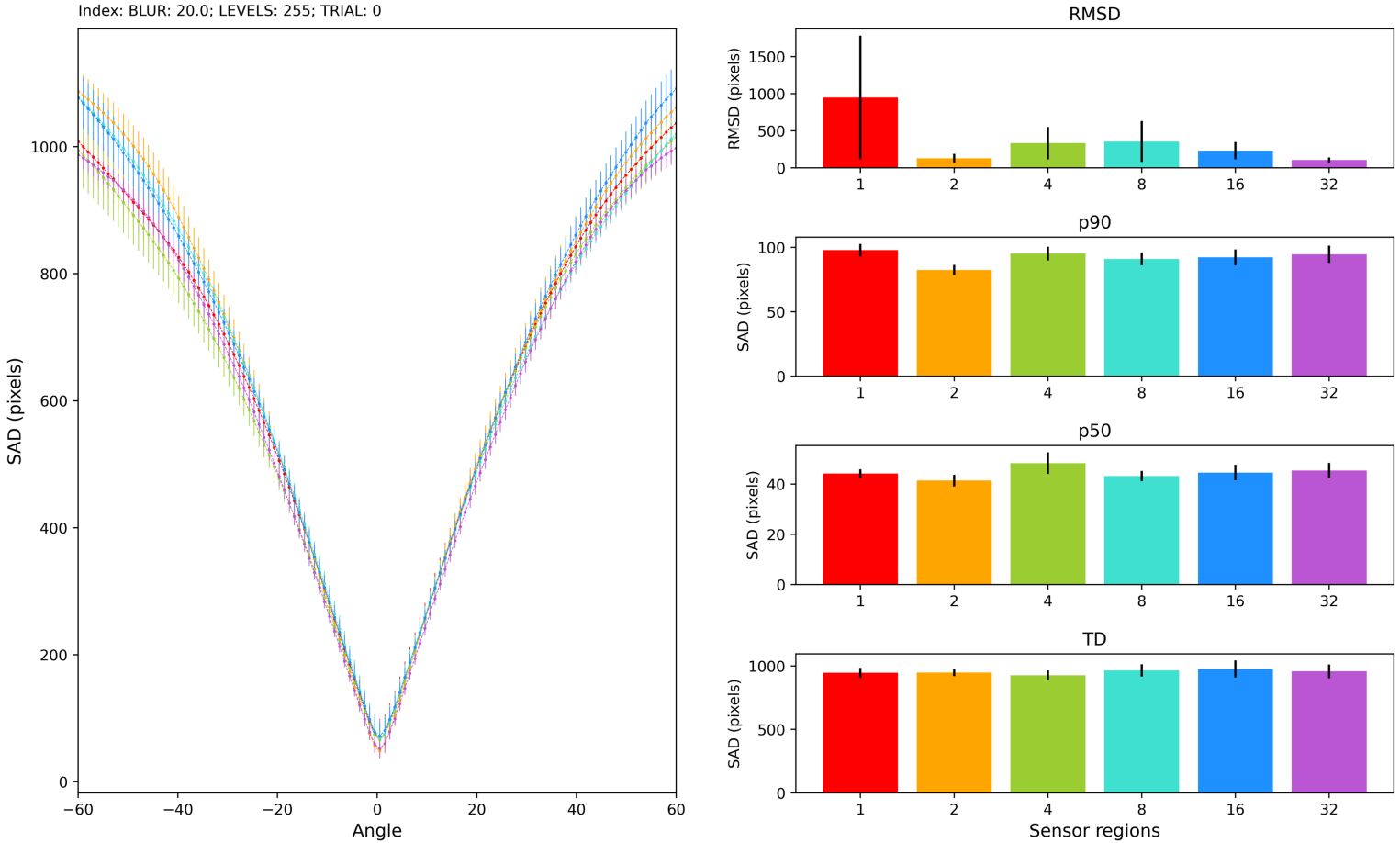
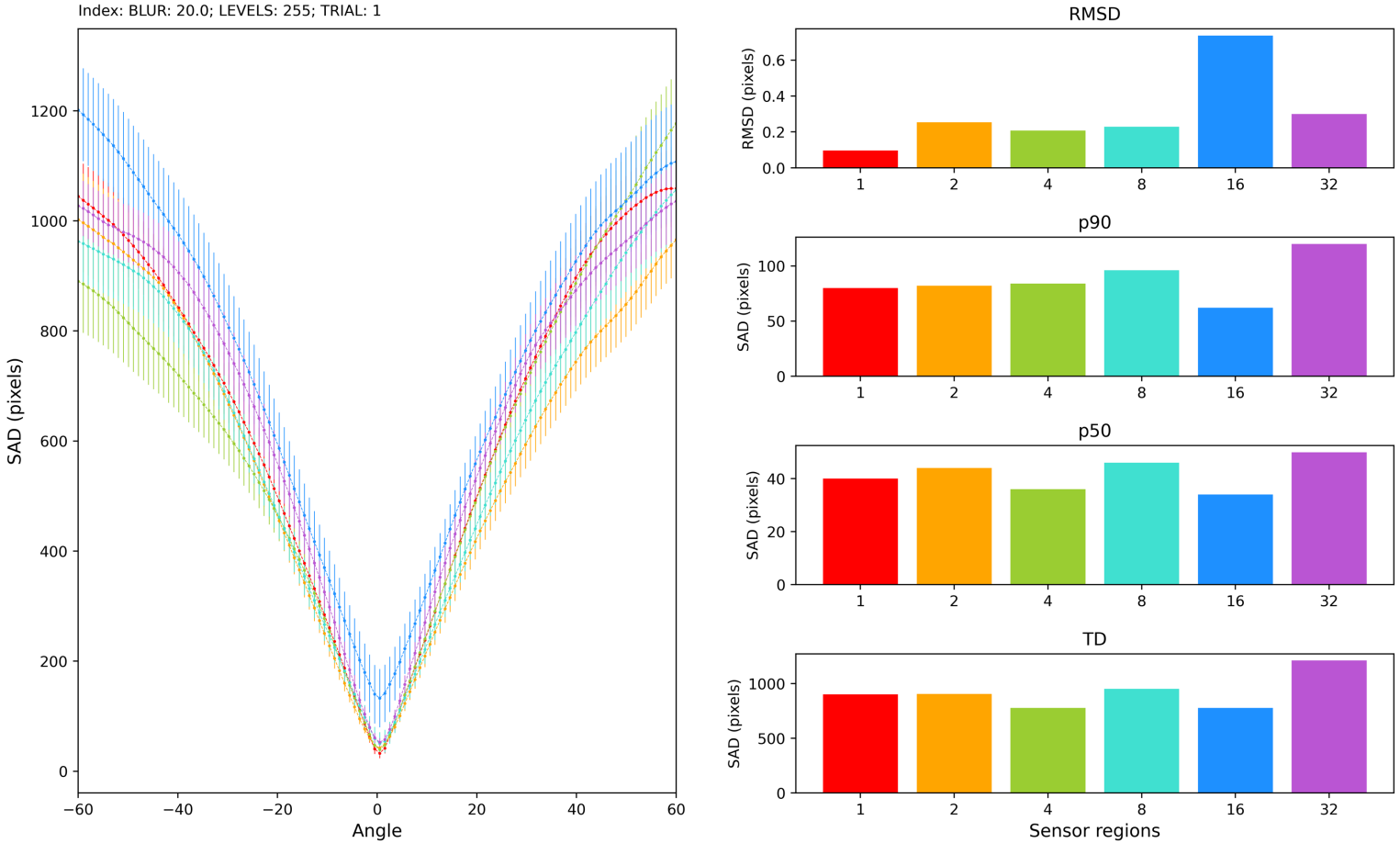
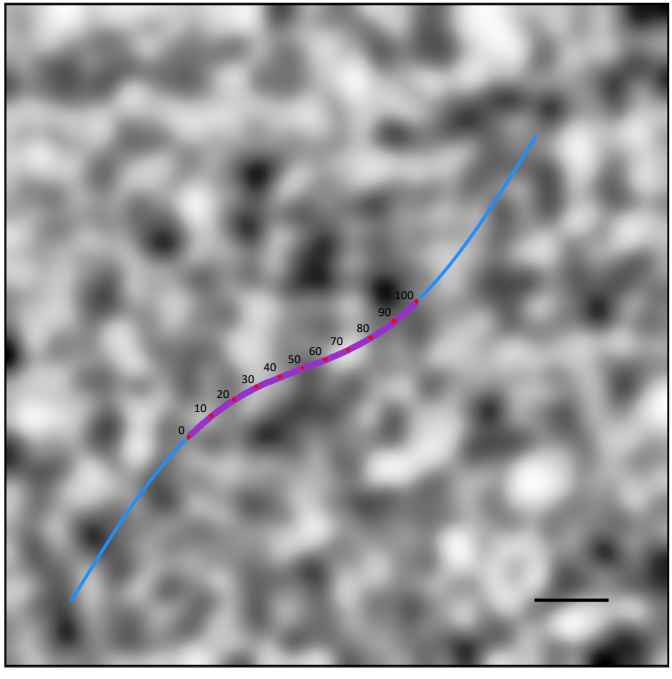
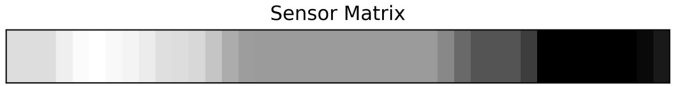
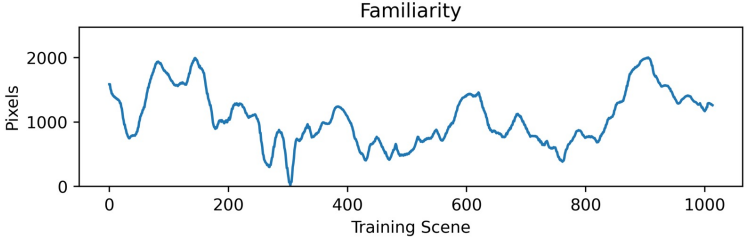

Index: BLUR: 20.0; LEVELS: 255; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

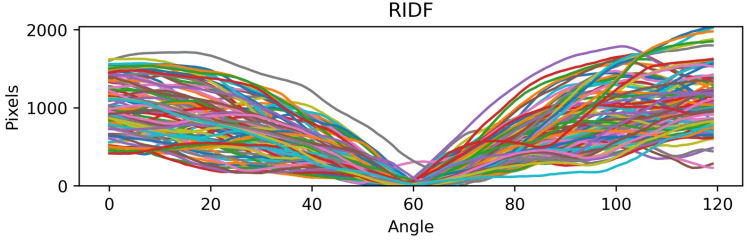

Index: BLUR: 20.0; LEVELS: 255; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

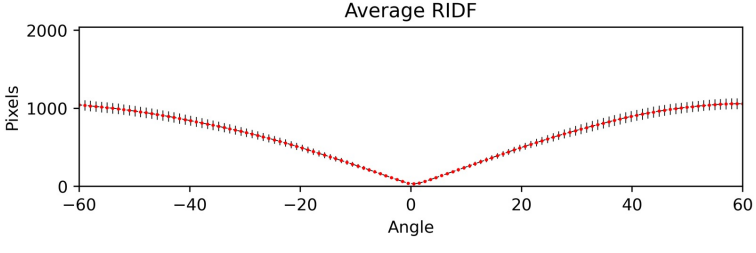
100%







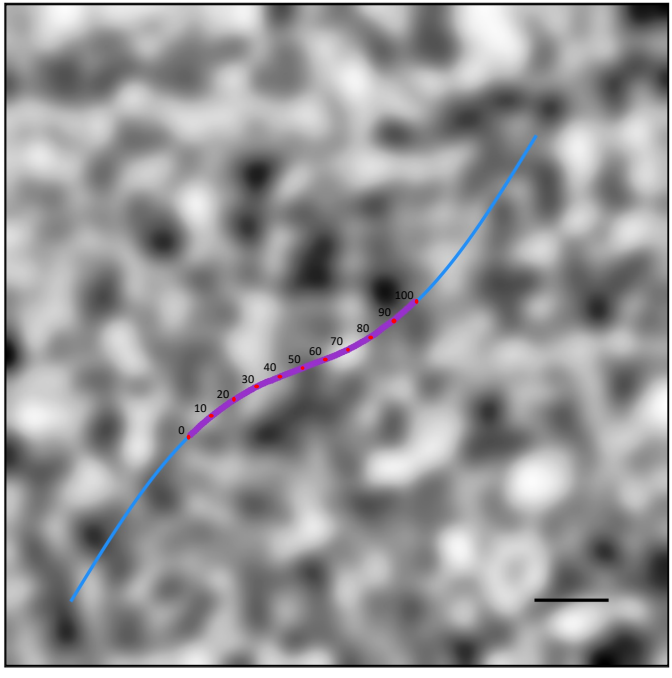


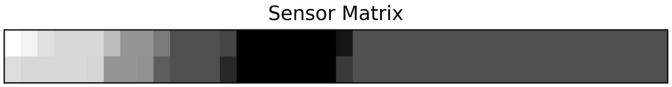


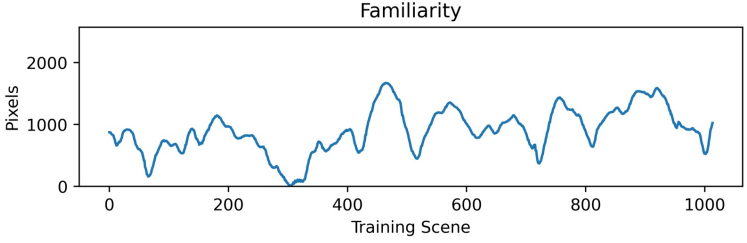
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

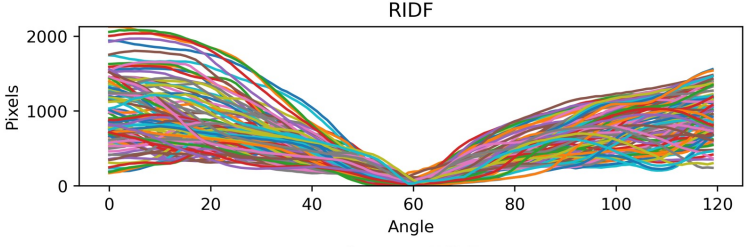
Navigation stats: RMSD error: 38.34; RMSD/dist: 0.096; TD: 900; p90: 80; p50: 40; complete: 0

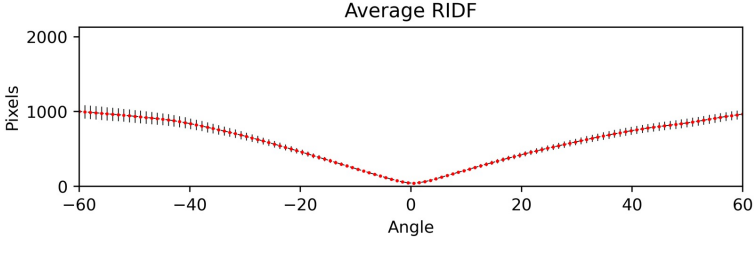
100%







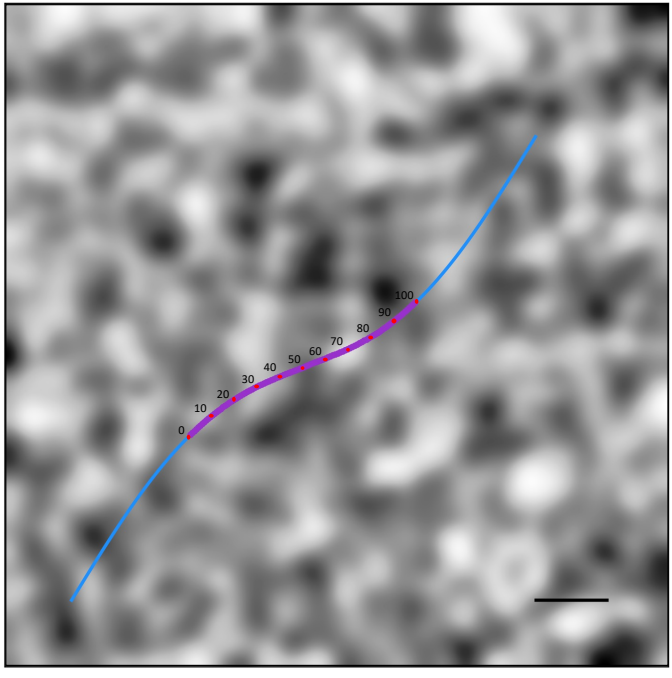


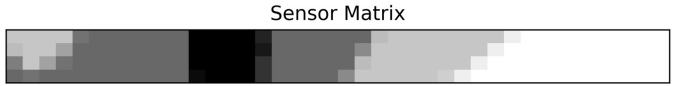


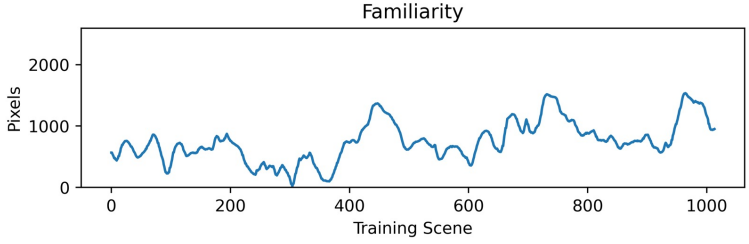
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

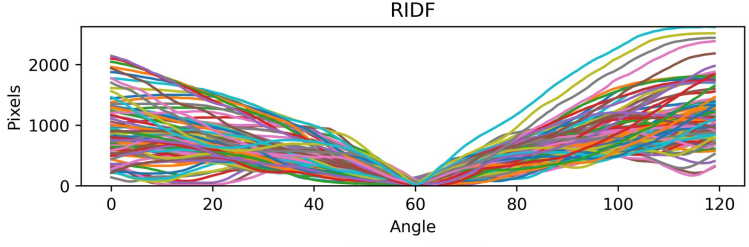
Navigation stats: RMSD error: 101.52; RMSD/dist: 0.254; TD: 905; p90: 82; p50: 44; complete: 0

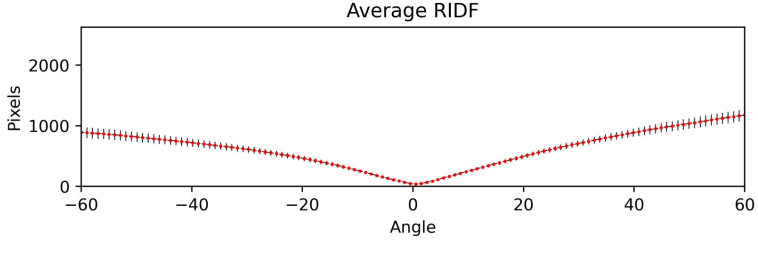
100%







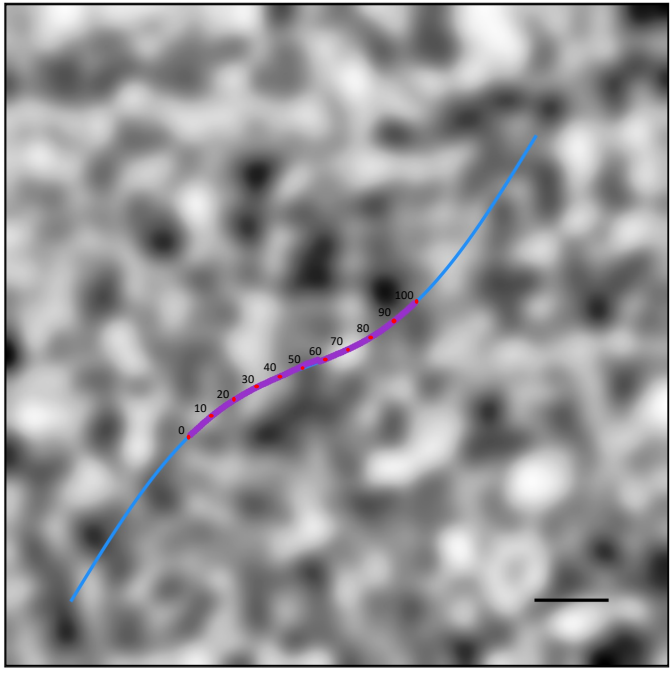


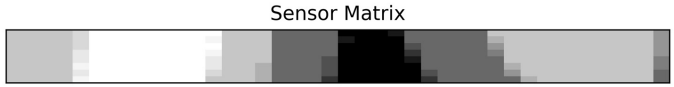


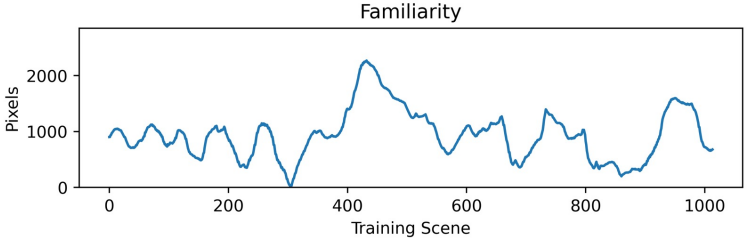
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

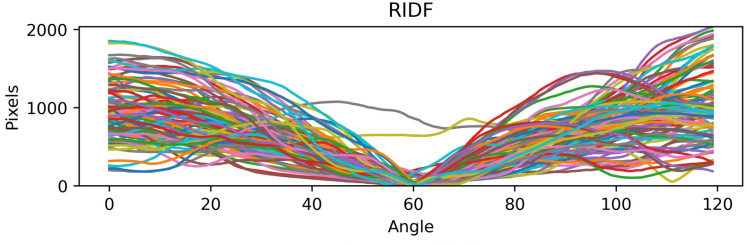
Navigation stats: RMSD error: 83.34; RMSD/dist: 0.208; TD: 777; p90: 84; p50: 36; complete: 0

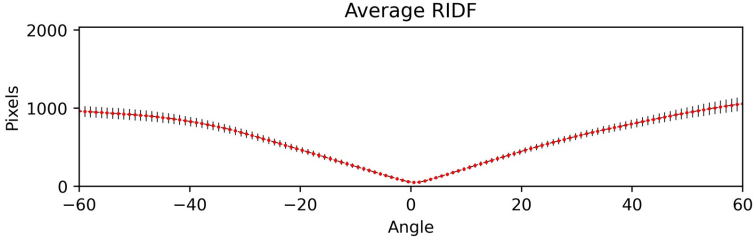
90%







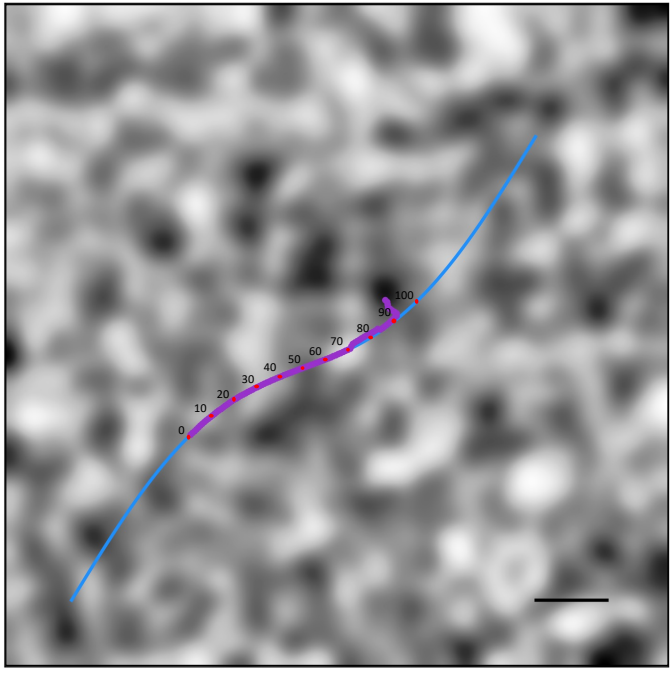


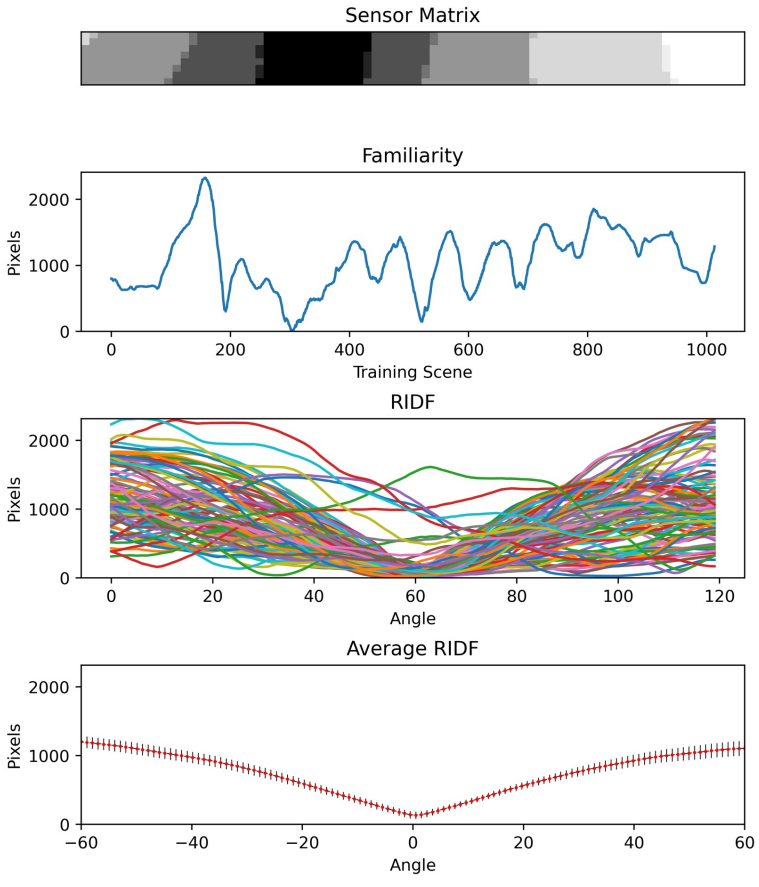


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 91.59; RMSD/dist: 0.229; TD: 951; p90: 96; p50: 46; complete: 0

70%

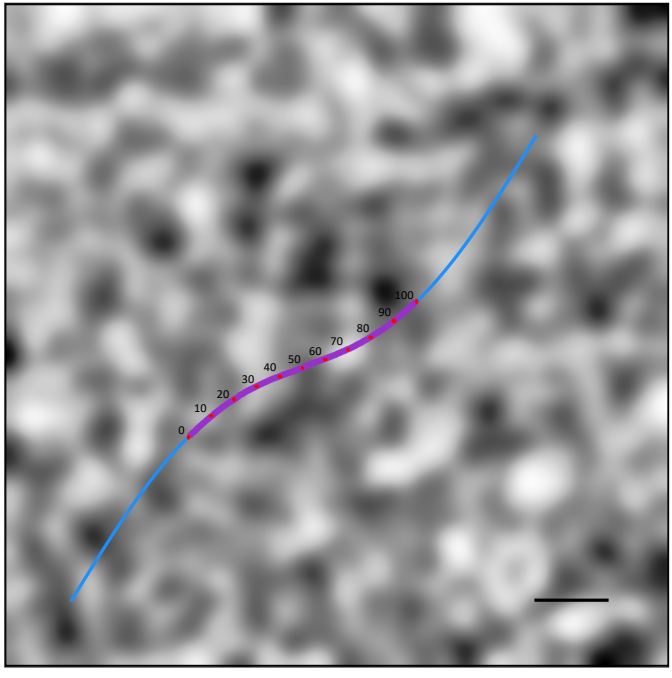


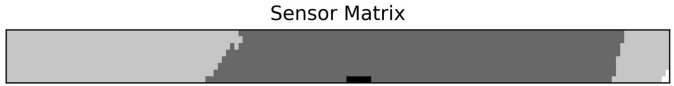


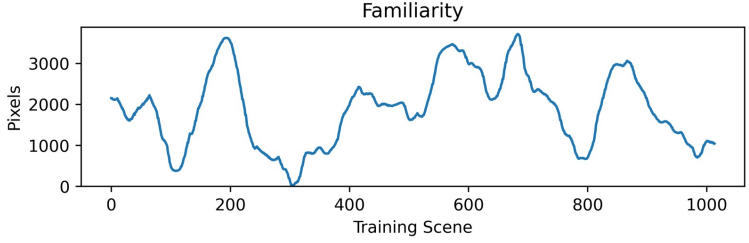
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

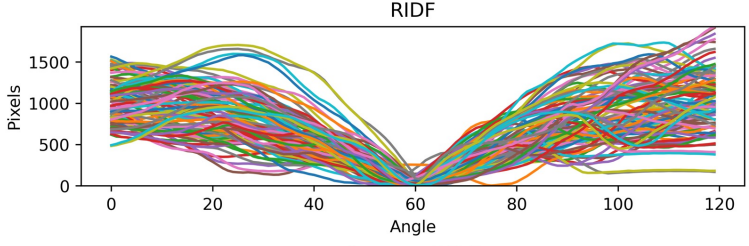
Navigation stats: RMSD error: 294.86; RMSD/dist: 0.737; TD: 777; p90: 62; p50: 34; complete: 0

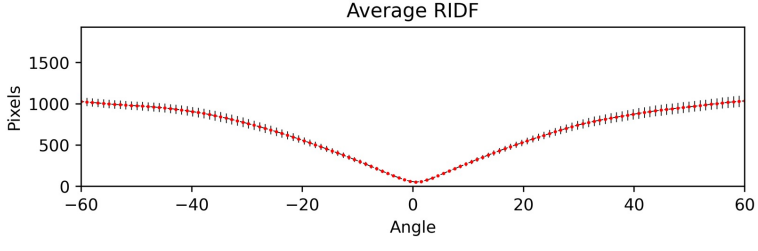
100%





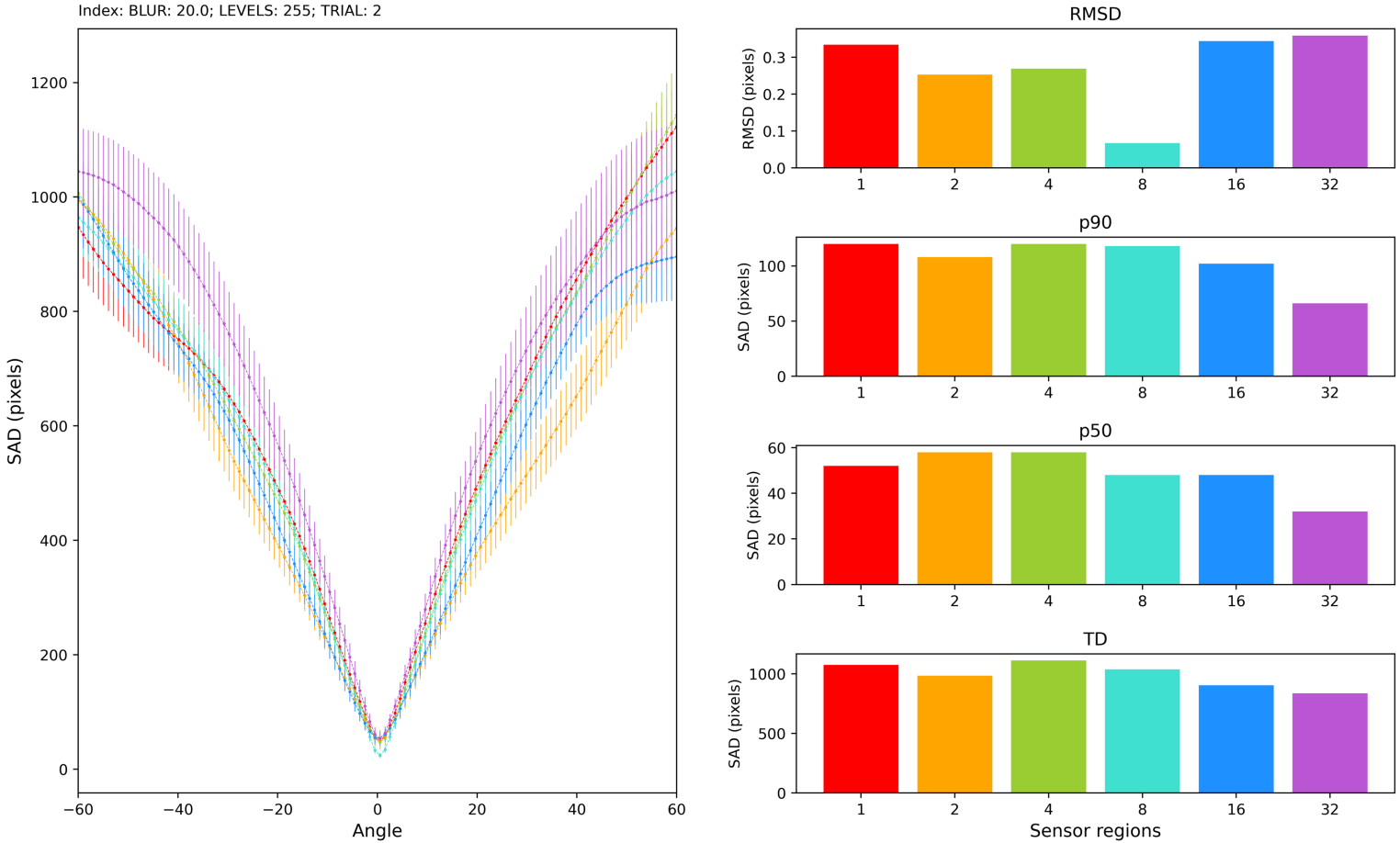




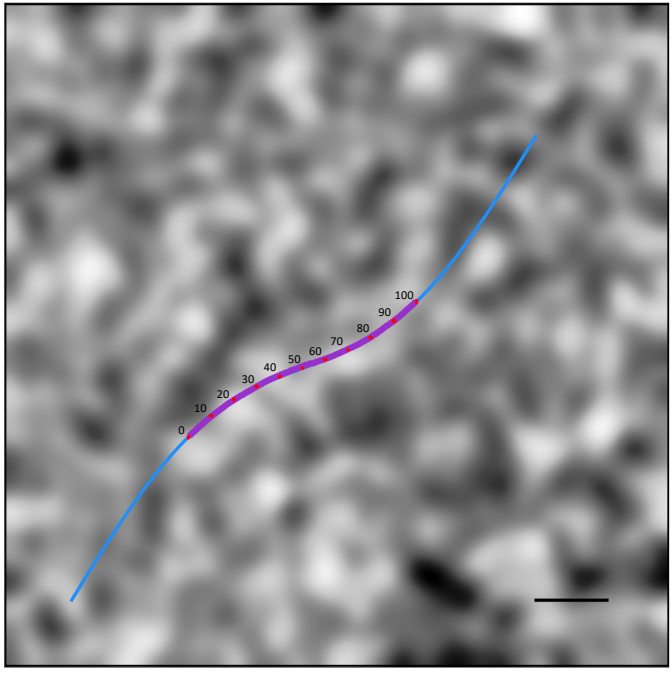


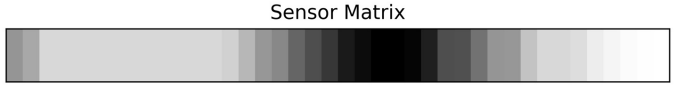
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

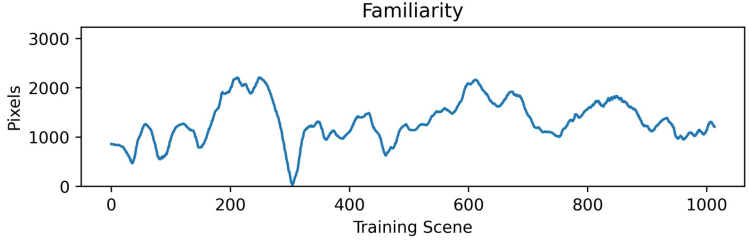
Navigation stats: RMSD error: 119.45; RMSD/dist: 0.299; TD: 1210; p90: 120; p50: 50; complete: 0

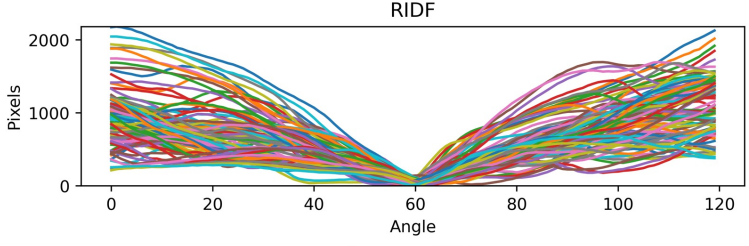

Index: BLUR: 20.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

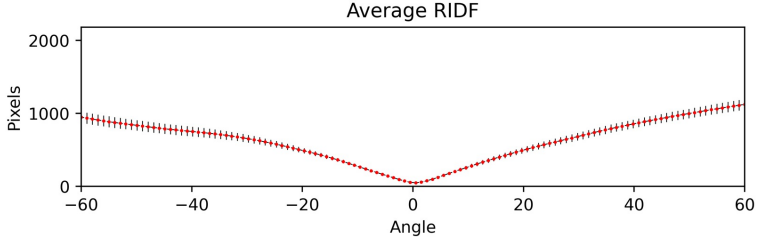
100%







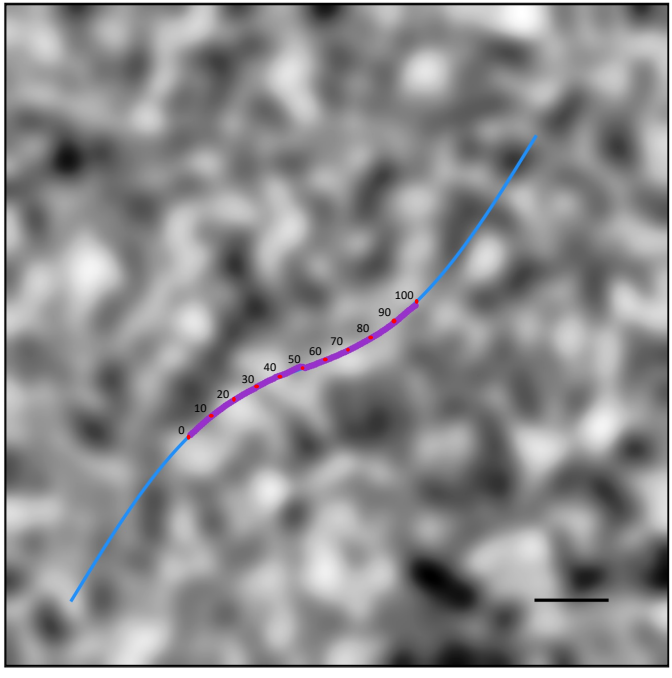


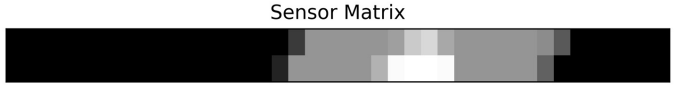


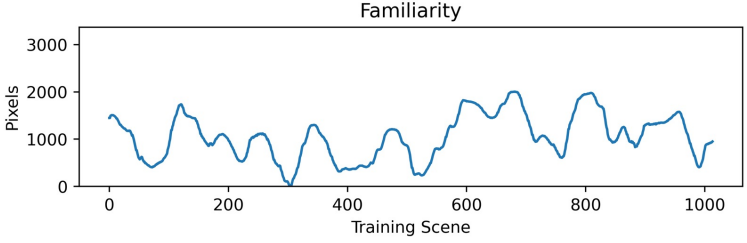
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

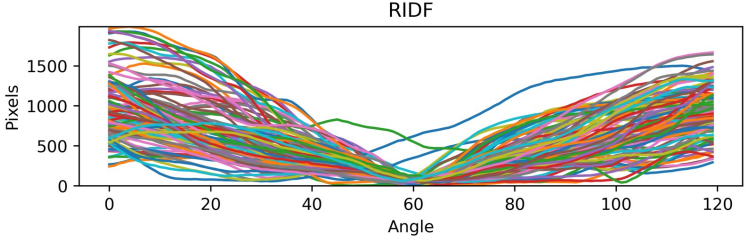
Navigation stats: RMSD error: 133.48; RMSD/dist: 0.334; TD: 1075; p90: 120; p50: 52; complete: 0

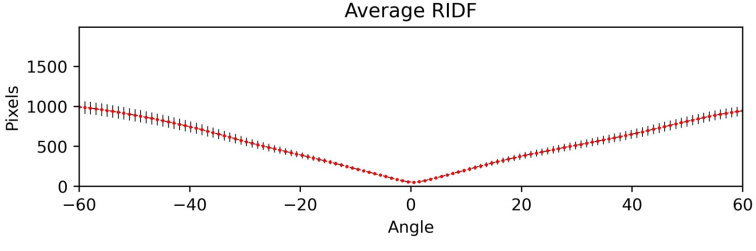
90%







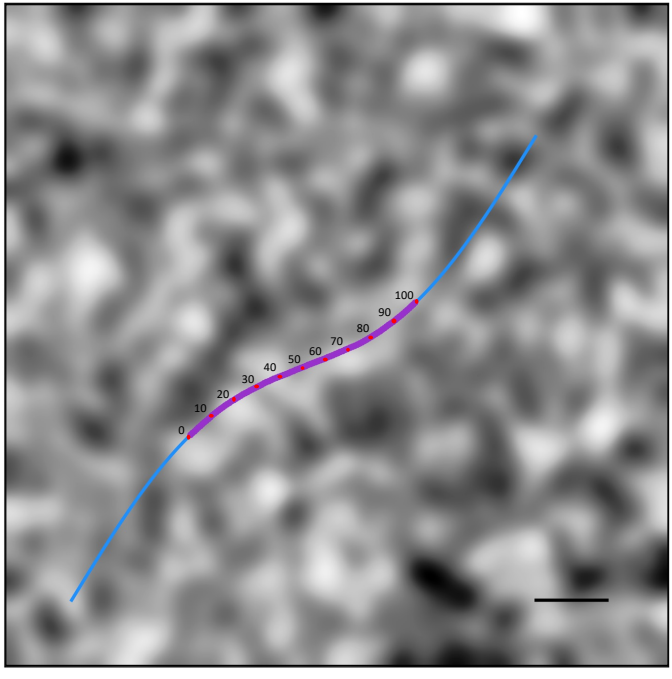


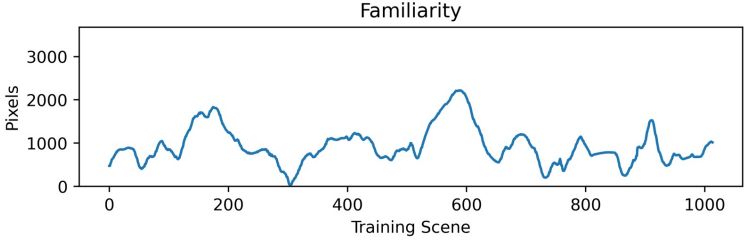


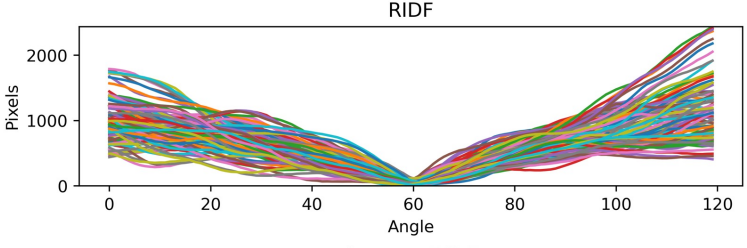
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

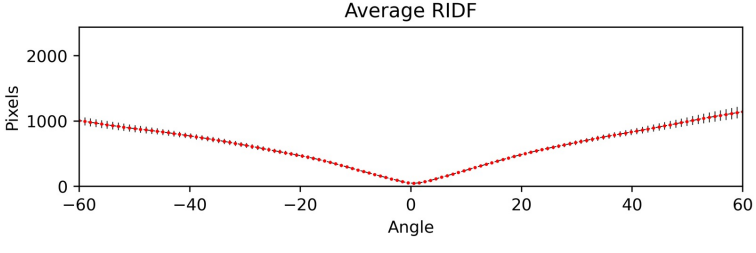
Navigation stats: RMSD error: 101.31; RMSD/dist: 0.253; TD: 984; p90: 108; p50: 58; complete: 0

100%





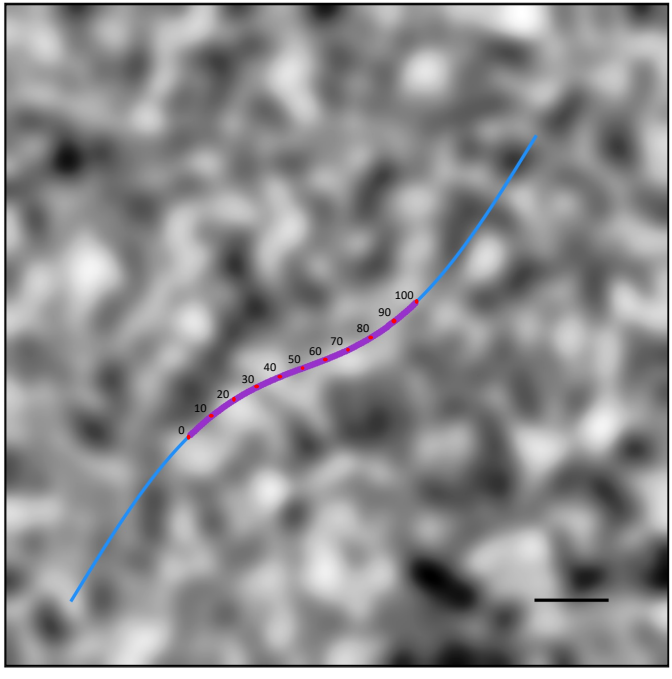


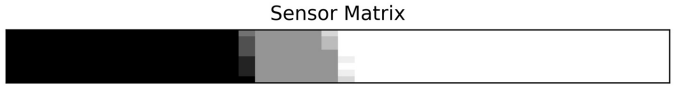


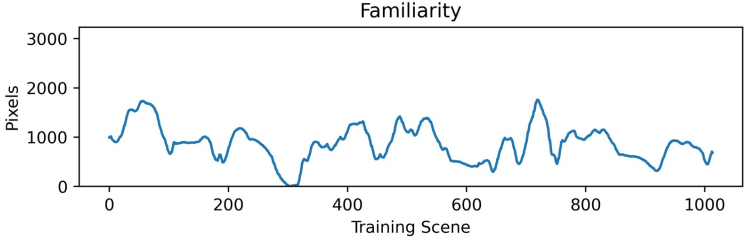
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

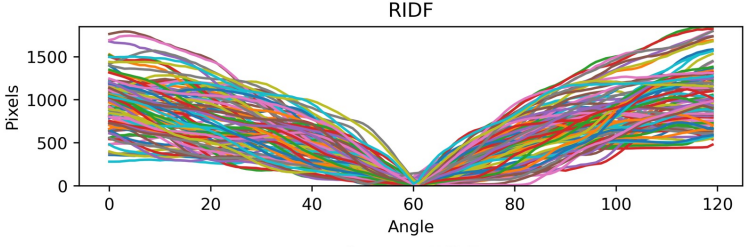
Navigation stats: RMSD error: 107.66; RMSD/dist: 0.269; TD: 1112; p90: 120; p50: 58; complete: 0

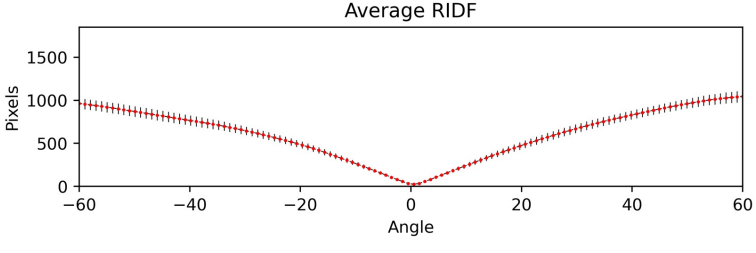
100%







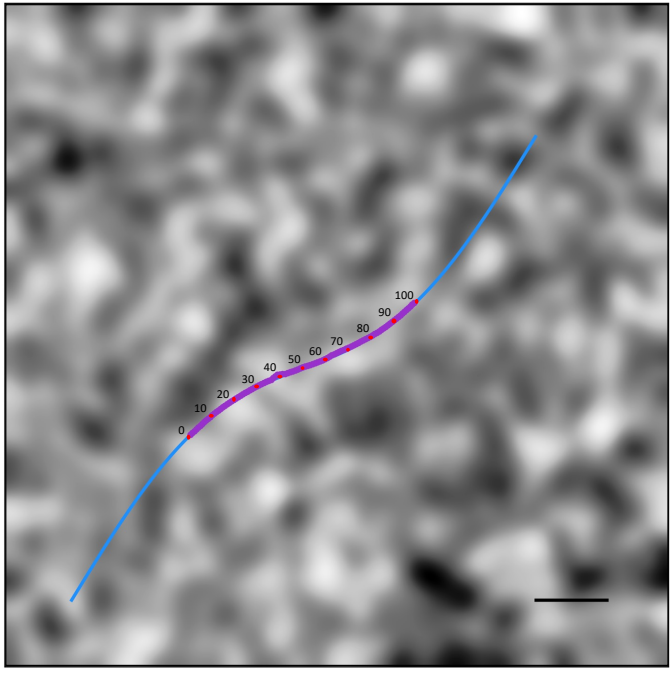


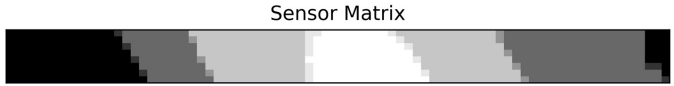


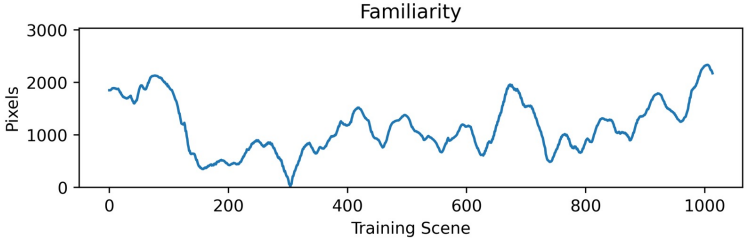
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

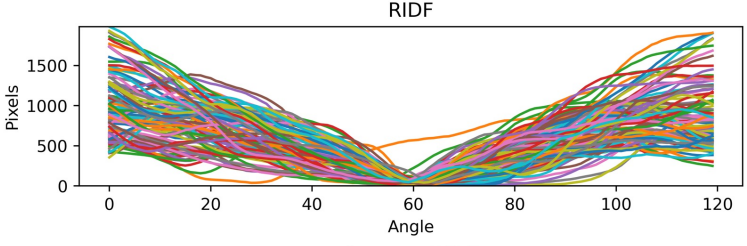
Navigation stats: RMSD error: 27.00; RMSD/dist: 0.067; TD: 1038; p90: 118; p50: 48; complete: 0

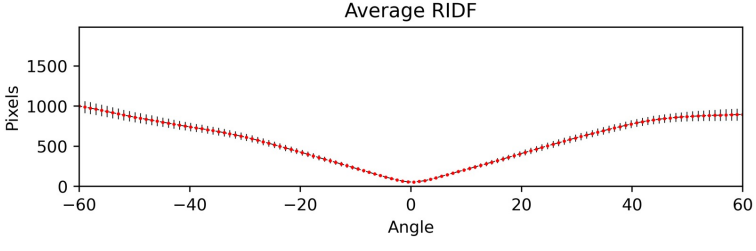
90%







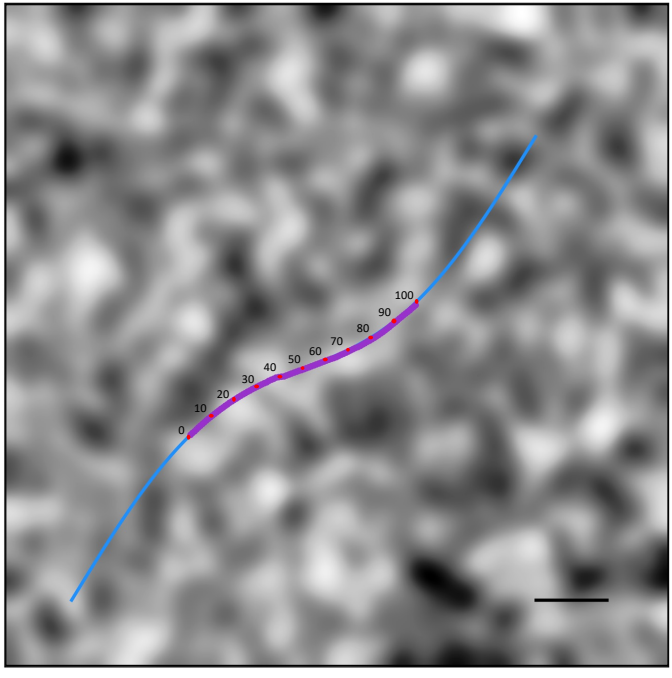


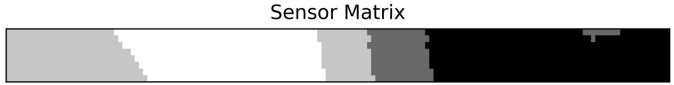


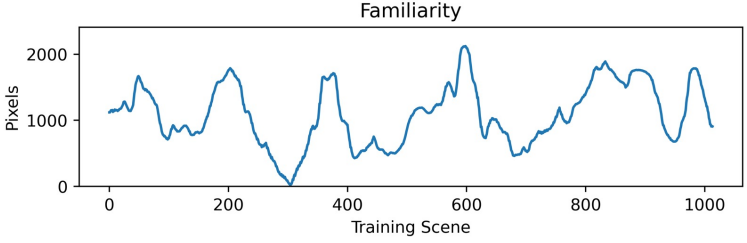
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

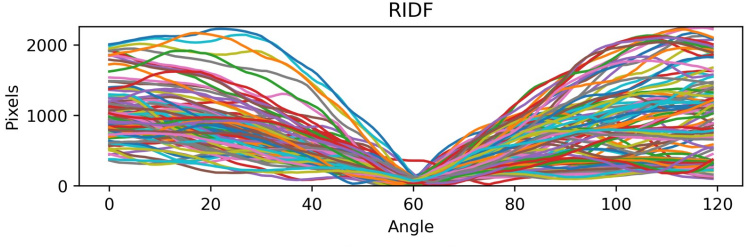
Navigation stats: RMSD error: 137.59; RMSD/dist: 0.344; TD: 905; p90: 102; p50: 48; complete: 0

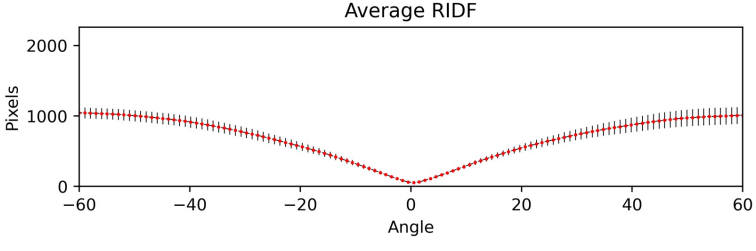
90%





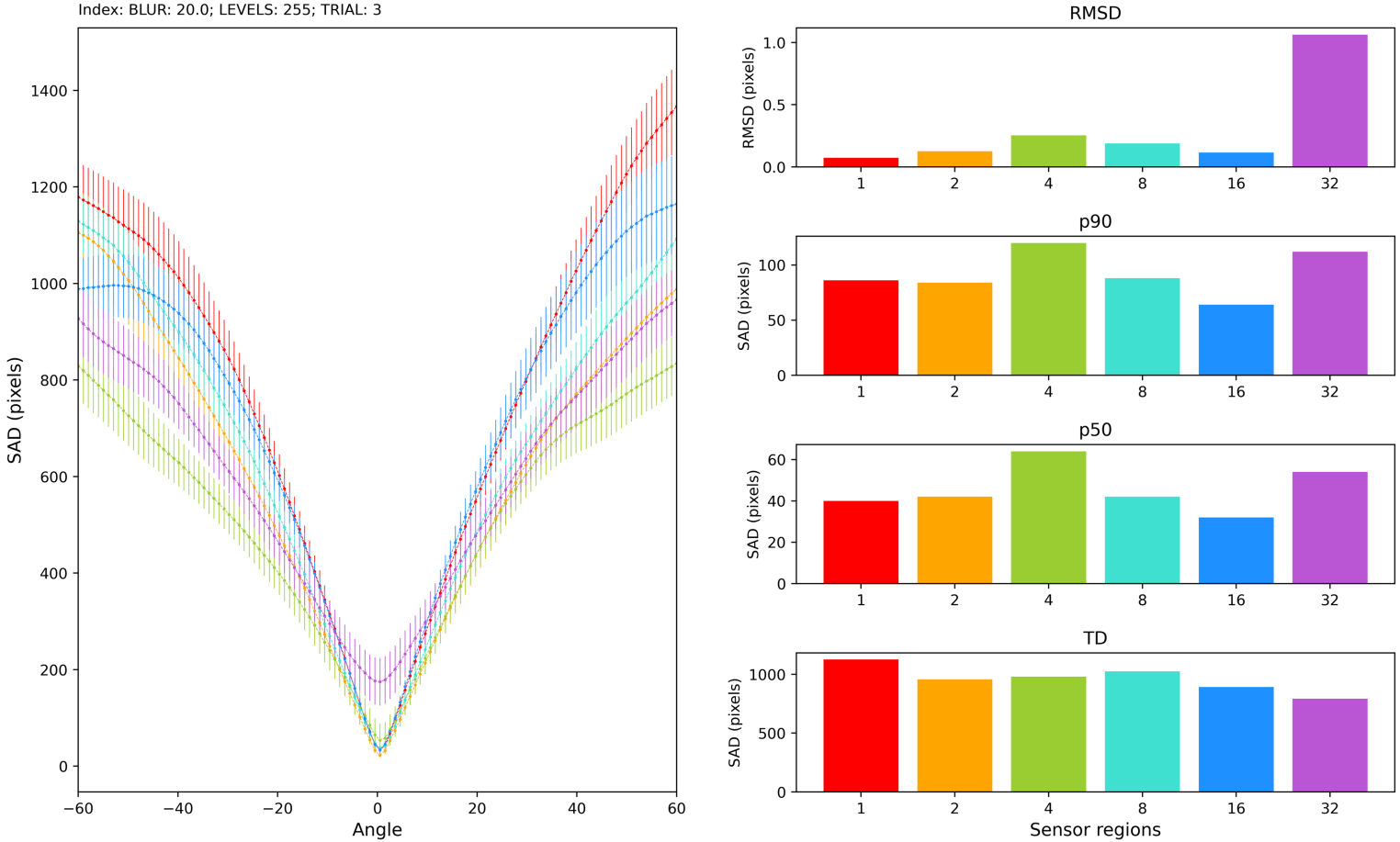




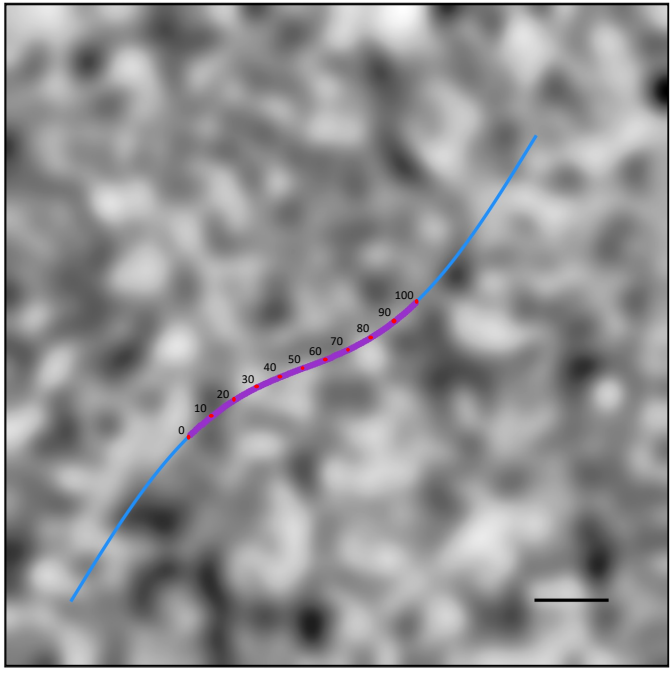


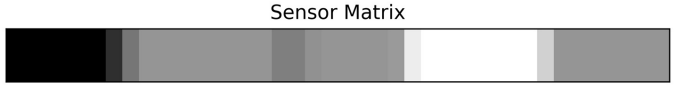
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

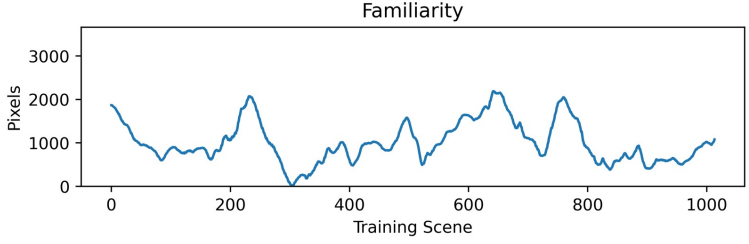
Navigation stats: RMSD error: 143.73; RMSD/dist: 0.359; TD: 837; p90: 66; p50: 32; complete: 0

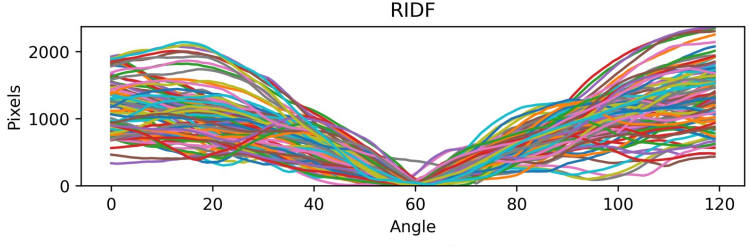

Index: BLUR: 20.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

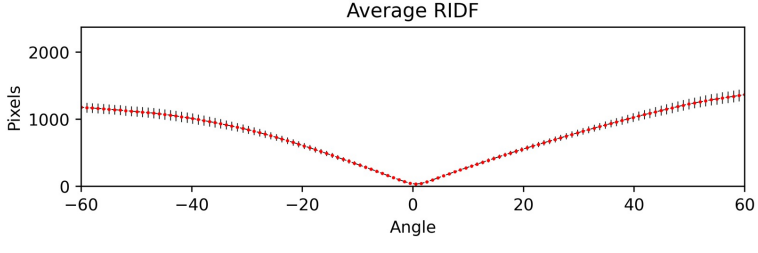
100%







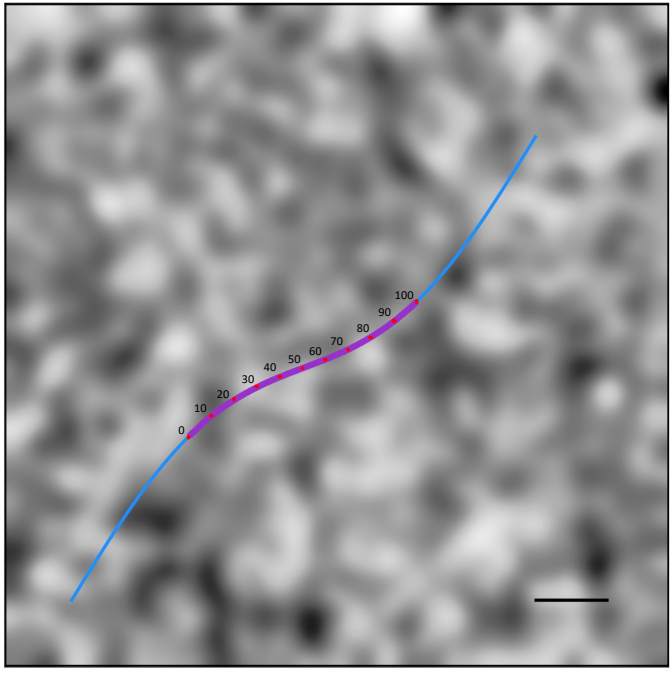


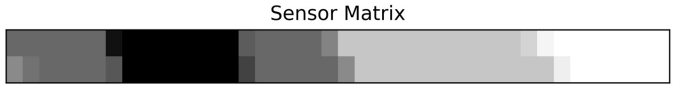


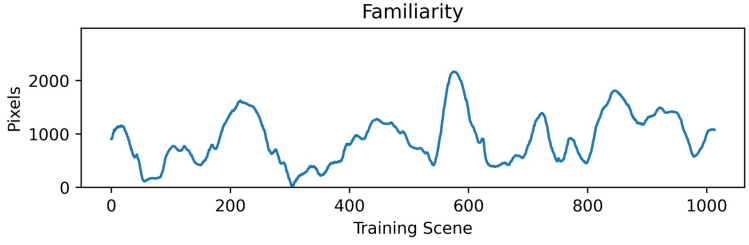
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

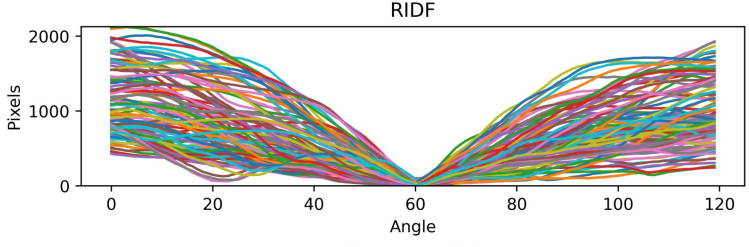
Navigation stats: RMSD error: 29.30; RMSD/dist: 0.073; TD: 1126; p90: 86; p50: 40; complete: 0

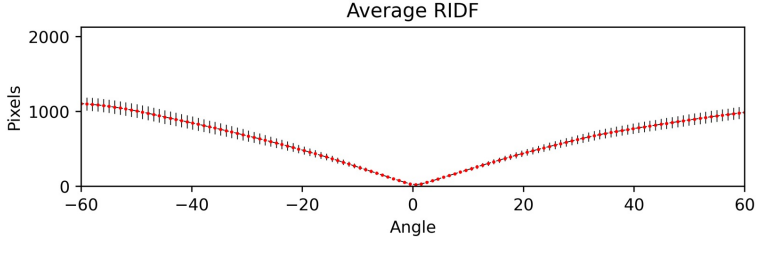
100%







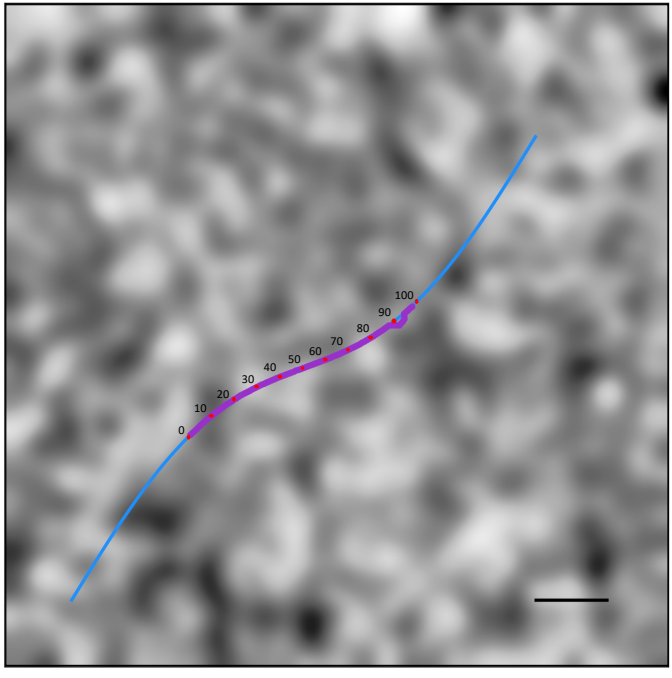


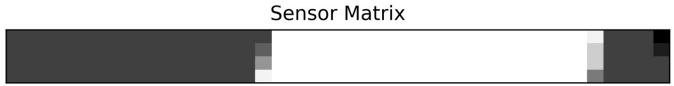


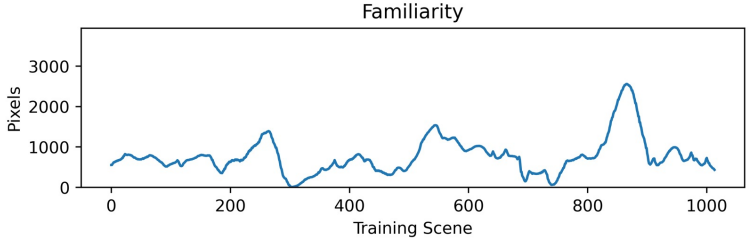
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

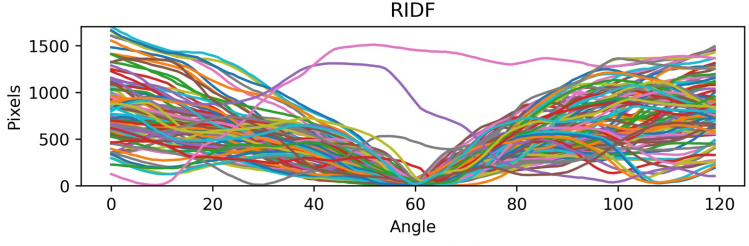
Navigation stats: RMSD error: 50.38; RMSD/dist: 0.126; TD: 958; p90: 84; p50: 42; complete: 0

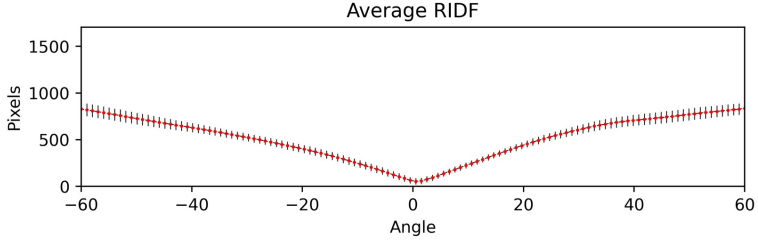
90%







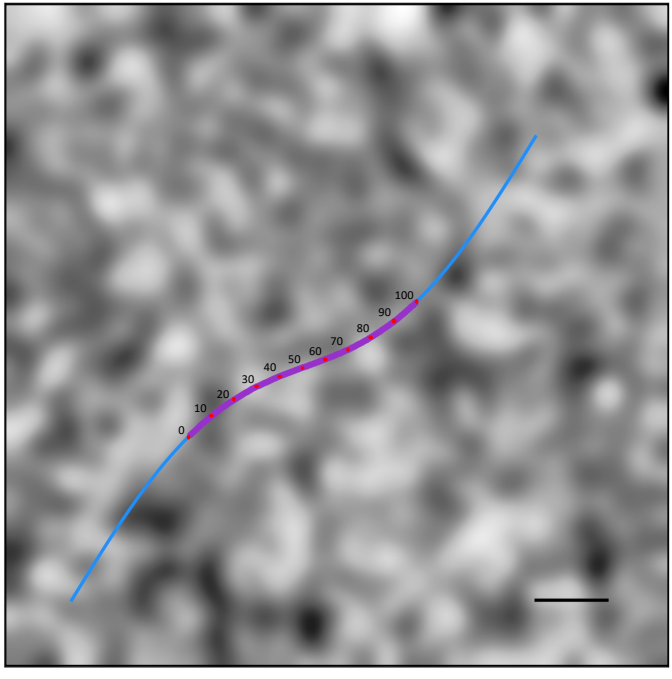


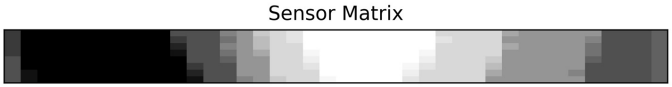


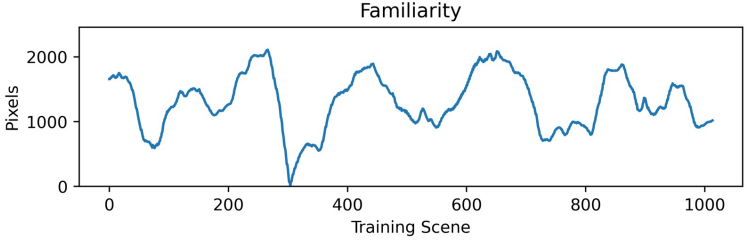
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

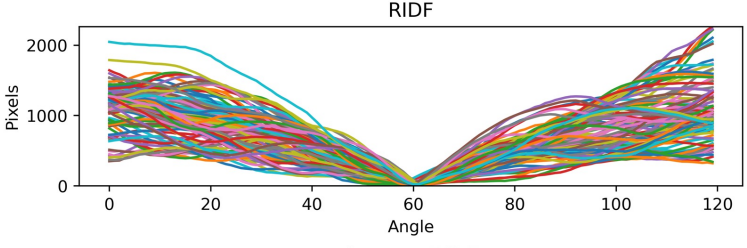
Navigation stats: RMSD error: 101.63; RMSD/dist: 0.254; TD: 981; p90: 120; p50: 64; complete: 0

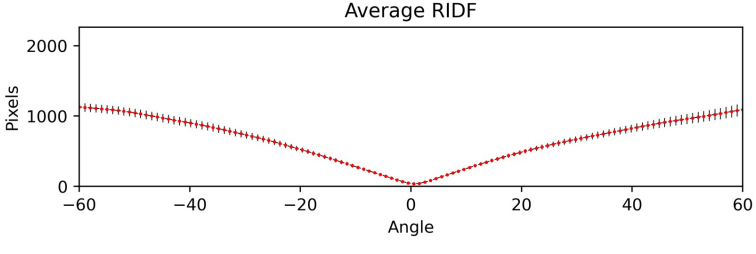
100%







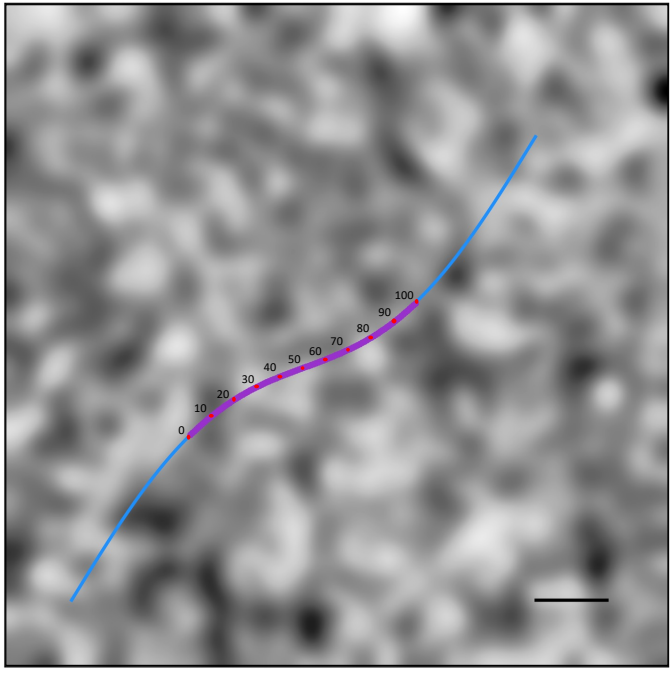


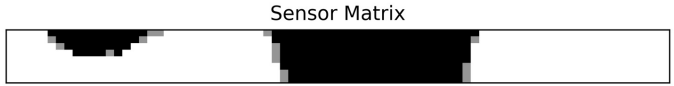


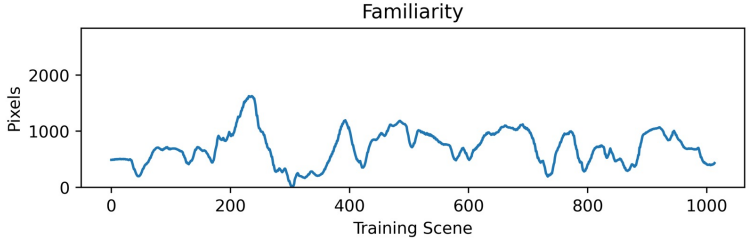
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

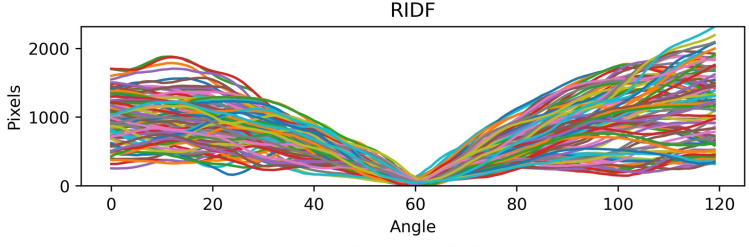
Navigation stats: RMSD error: 75.30; RMSD/dist: 0.188; TD: 1025; p90: 88; p50: 42; complete: 0

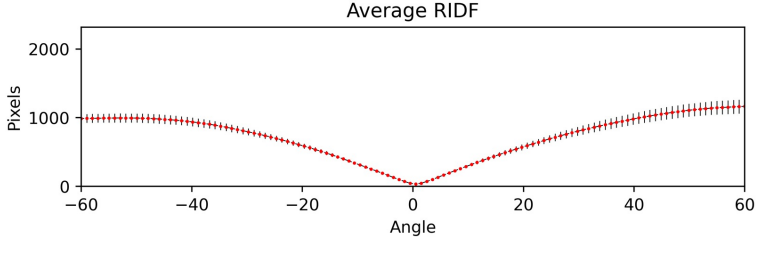
100%







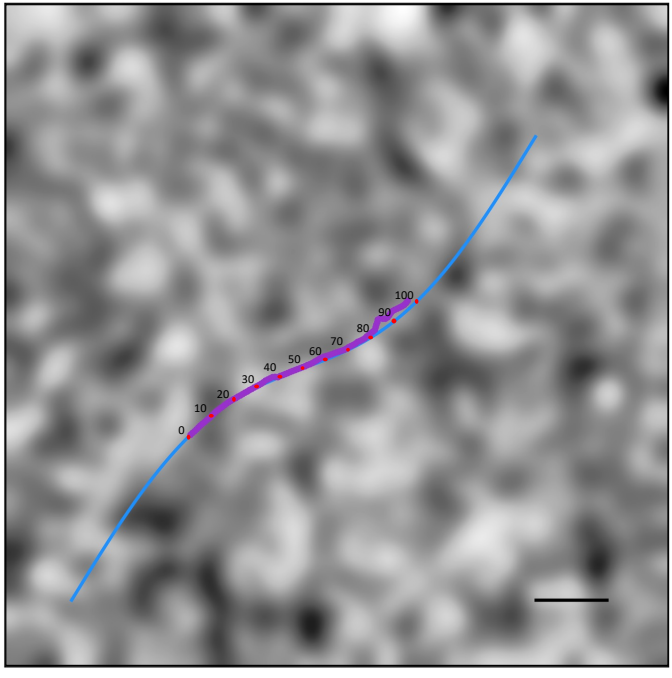


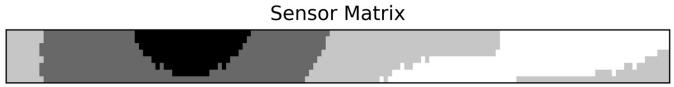


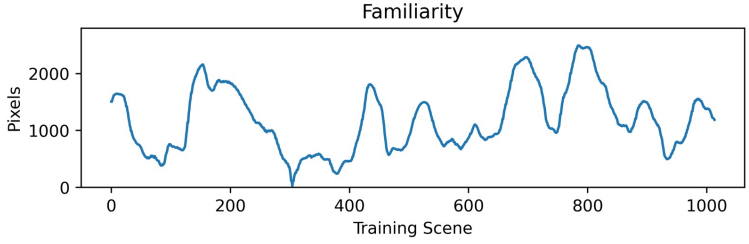
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

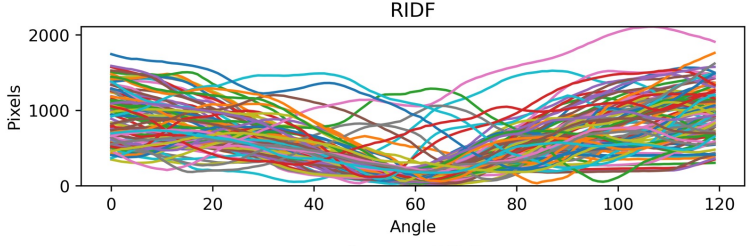
Navigation stats: RMSD error: 46.19; RMSD/dist: 0.115; TD: 892; p90: 64; p50: 32; complete: 0

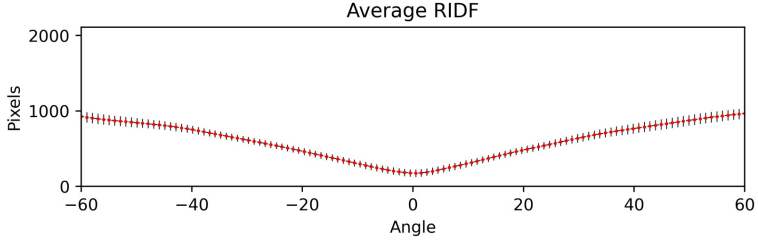
70%





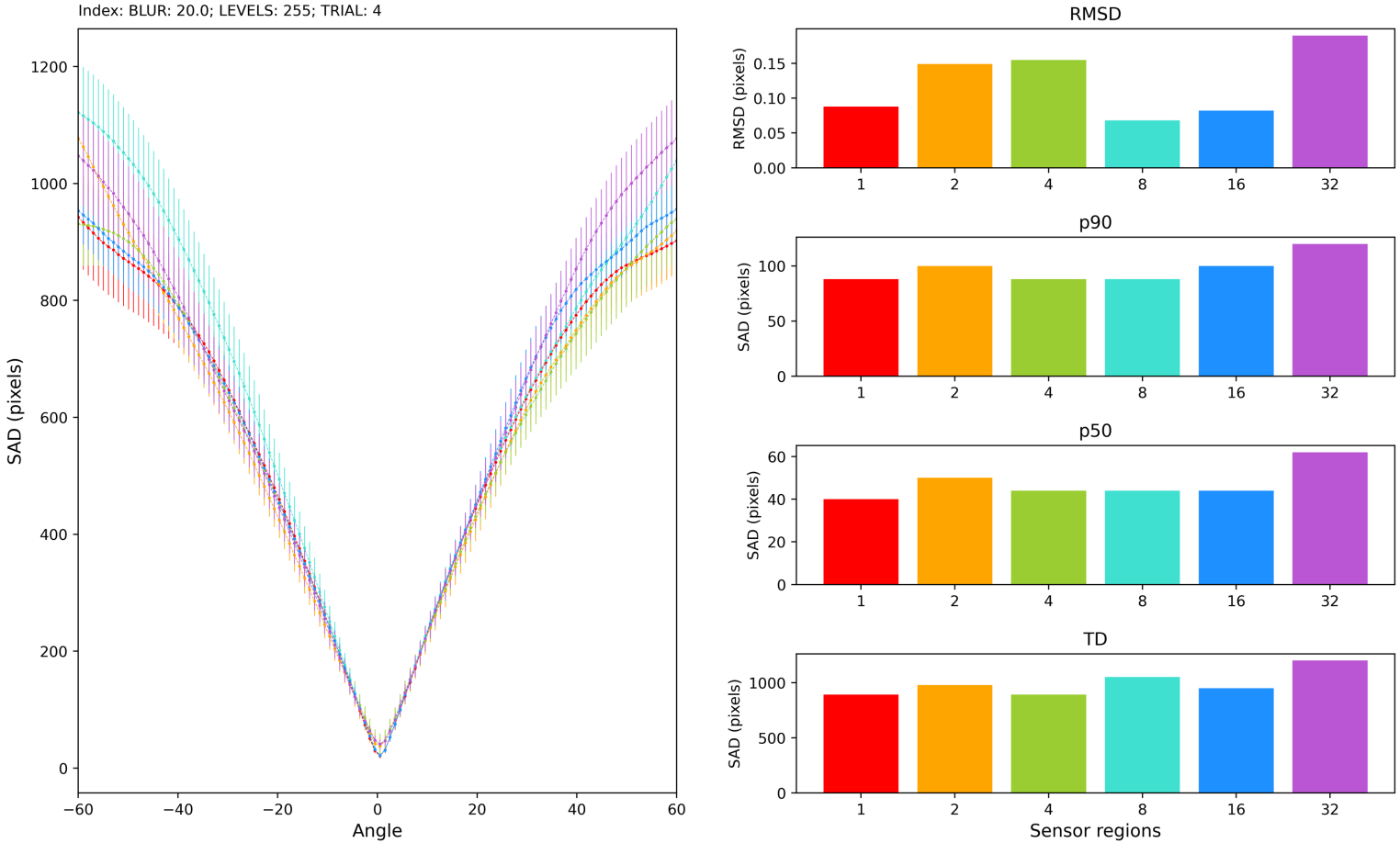




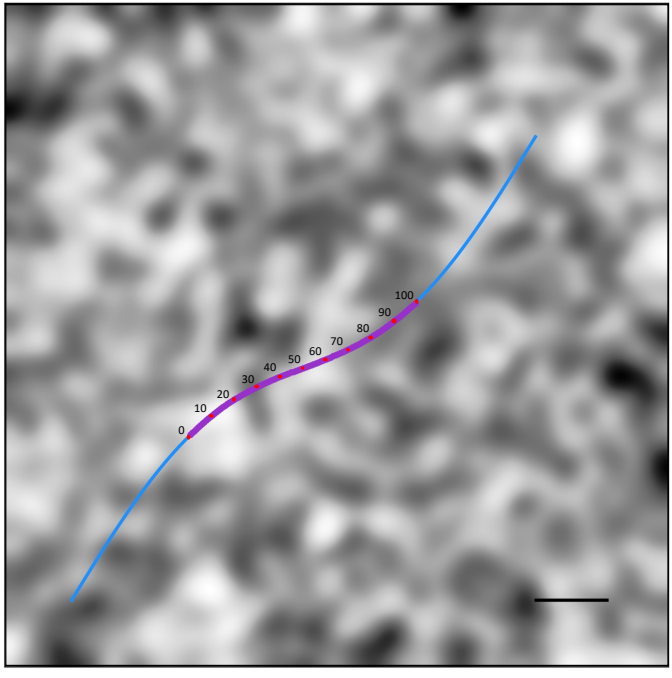


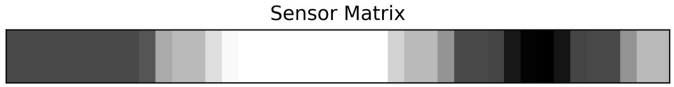
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

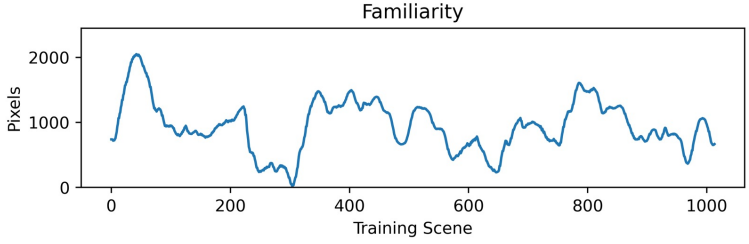
Navigation stats: RMSD error: 425.58; RMSD/dist: 1.064; TD: 793; p90: 112; p50: 54; complete: 0

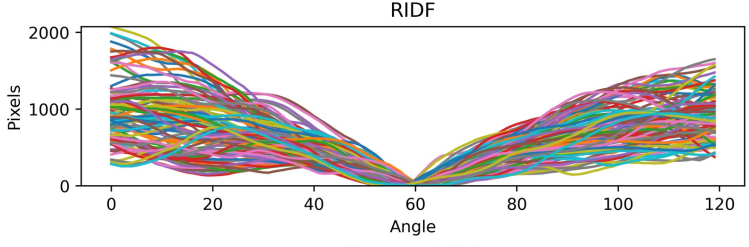

Index: BLUR: 20.0; LEVELS: 255; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

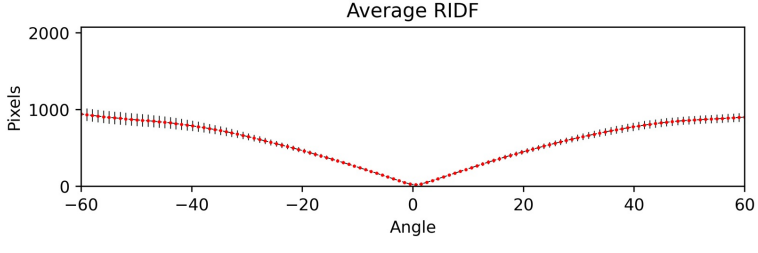
100%







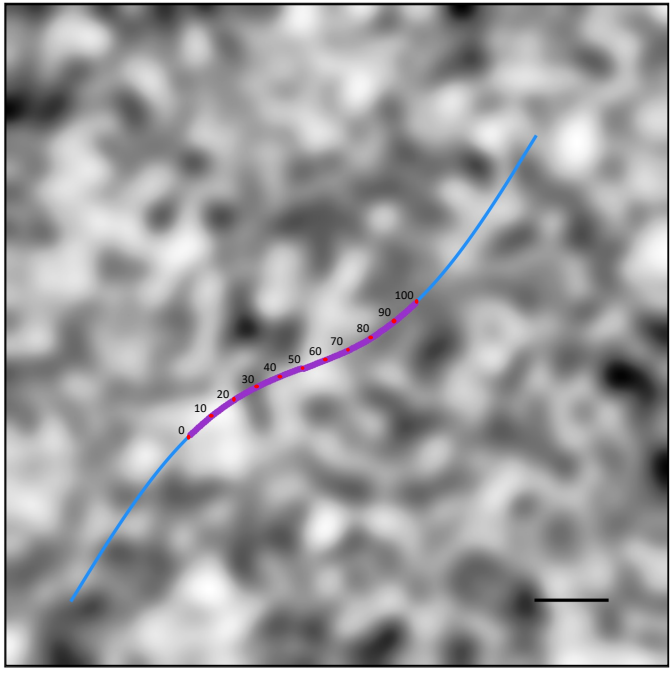


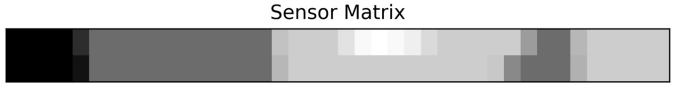


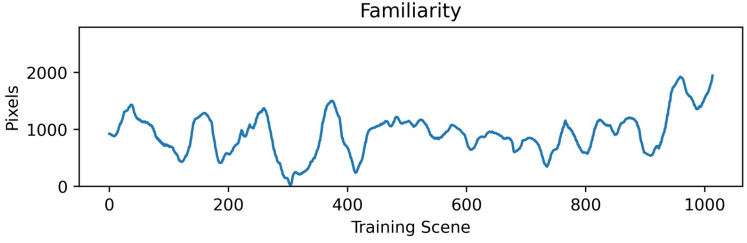
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

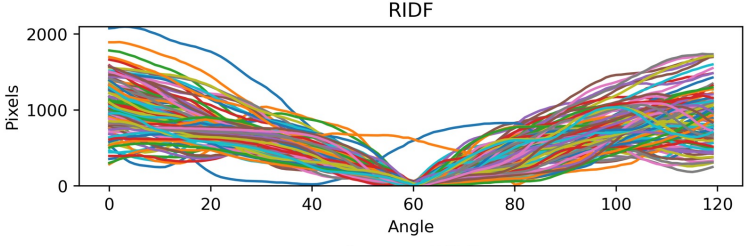
Navigation stats: RMSD error: 35.27; RMSD/dist: 0.088; TD: 893; p90: 88; p50: 40; complete: 0

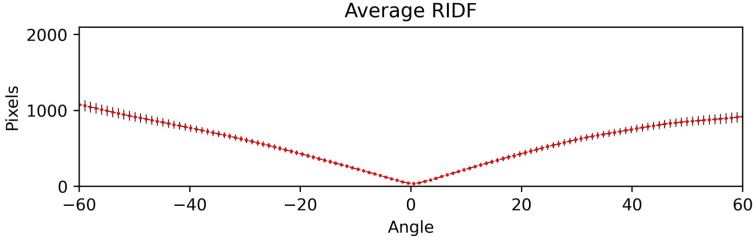
90%







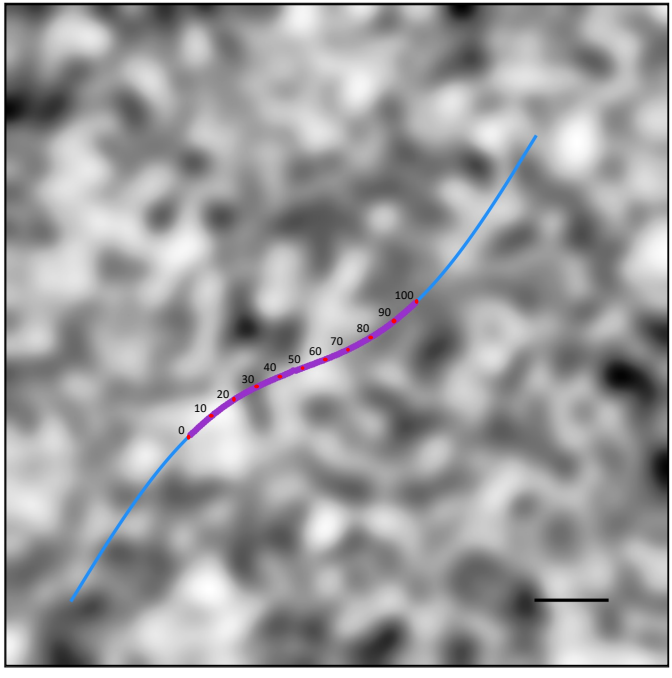


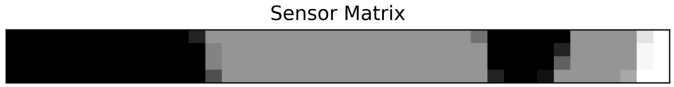


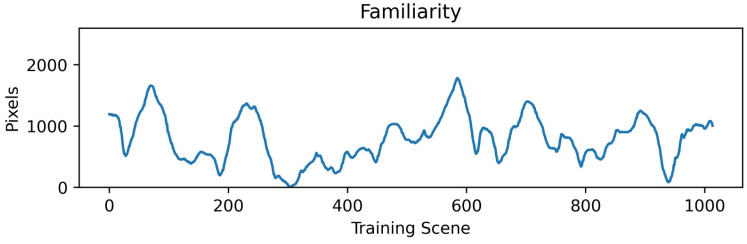
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

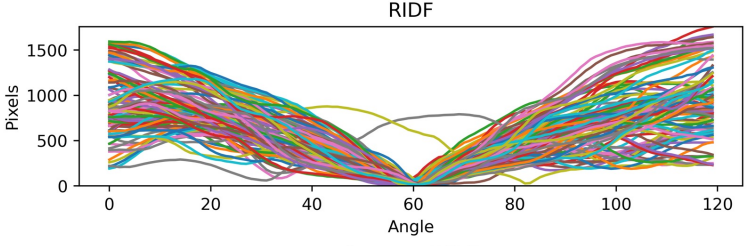
Navigation stats: RMSD error: 59.53; RMSD/dist: 0.149; TD: 980; p90: 100; p50: 50; complete: 0

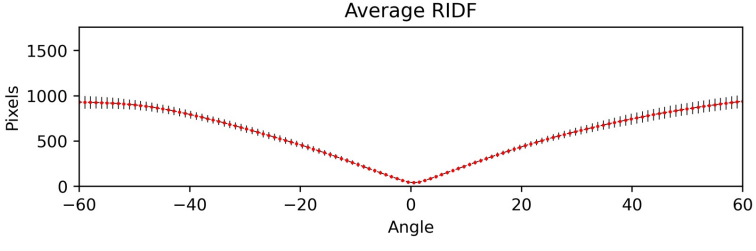
90%











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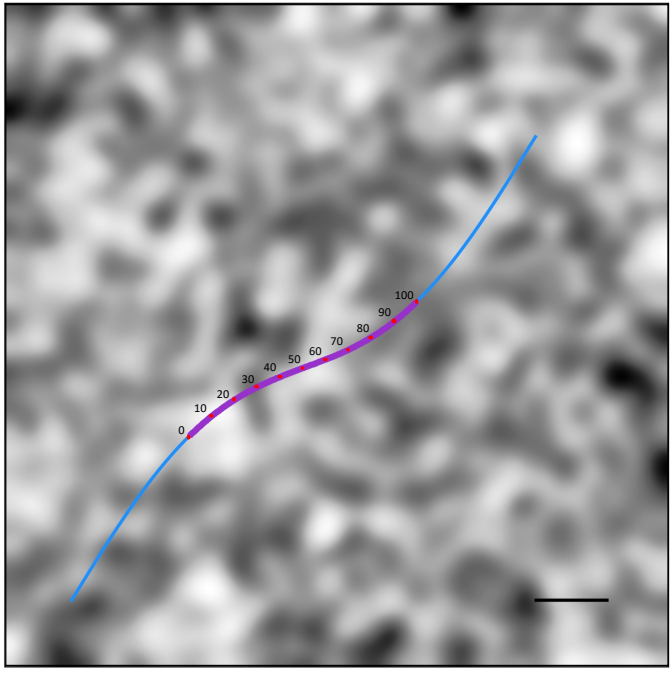
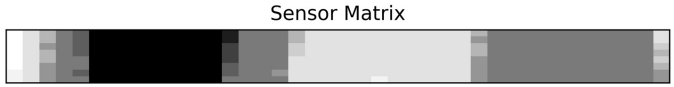
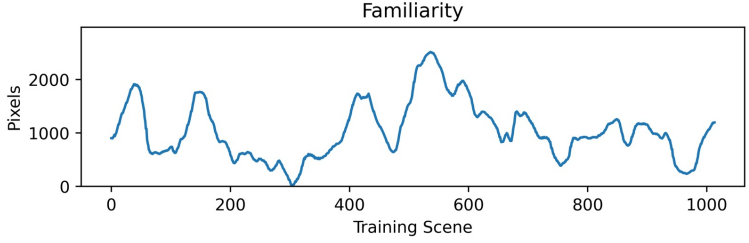
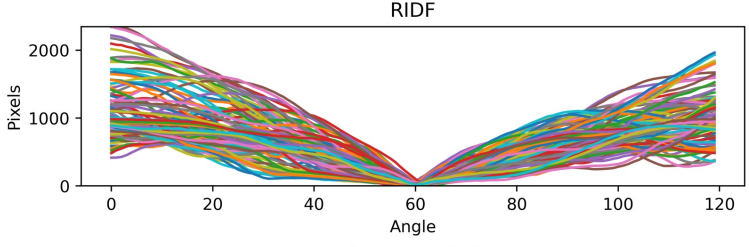
Navigation stats: RMSD error: 61.82; RMSD/dist: 0.155; TD: 893; p90: 88; p50: 44; complete: 0

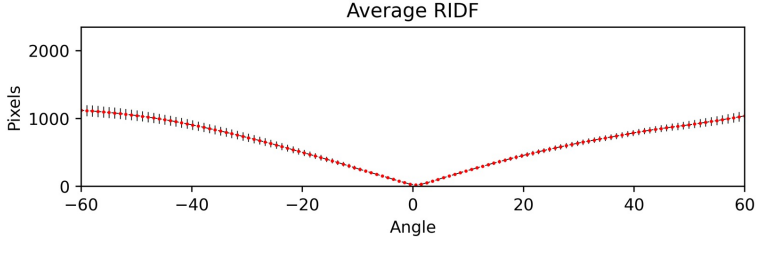
100%







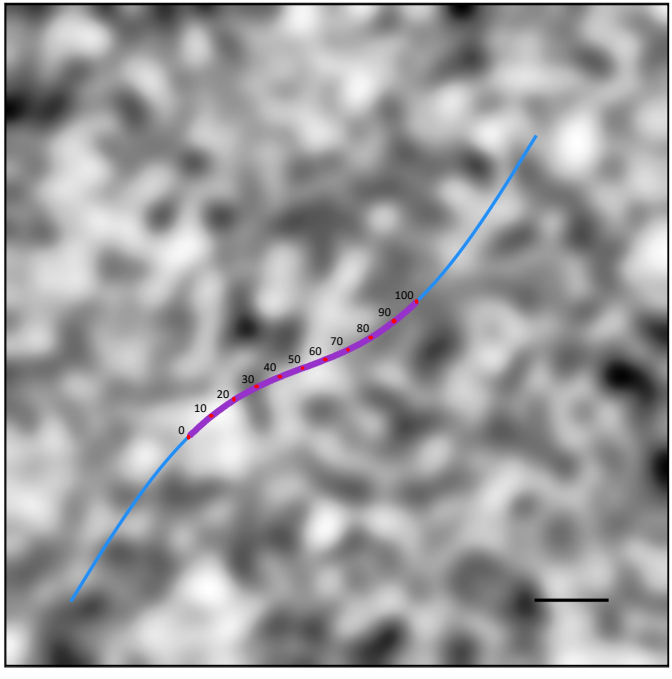


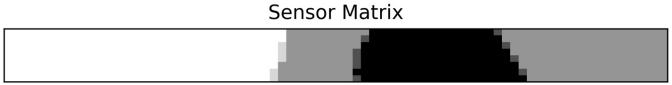


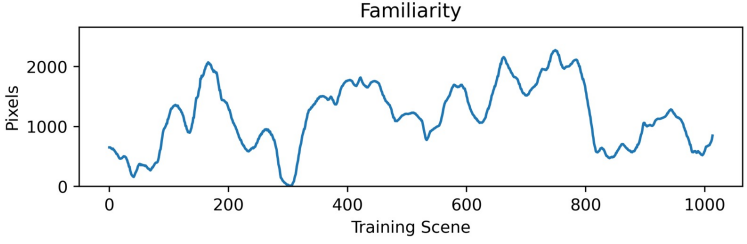
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

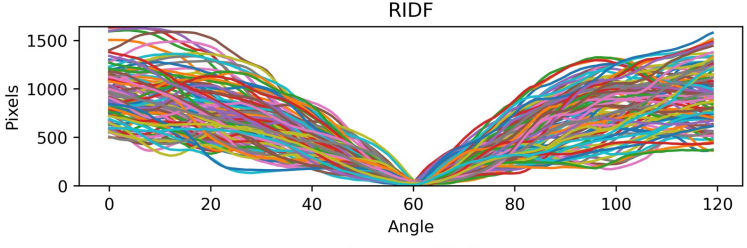
Navigation stats: RMSD error: 27.22; RMSD/dist: 0.068; TD: 1052; p90: 88; p50: 44; complete: 0

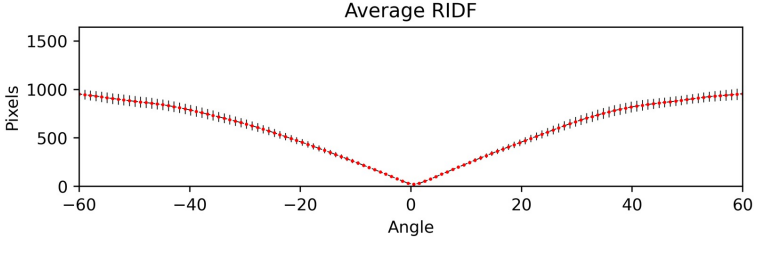
100%











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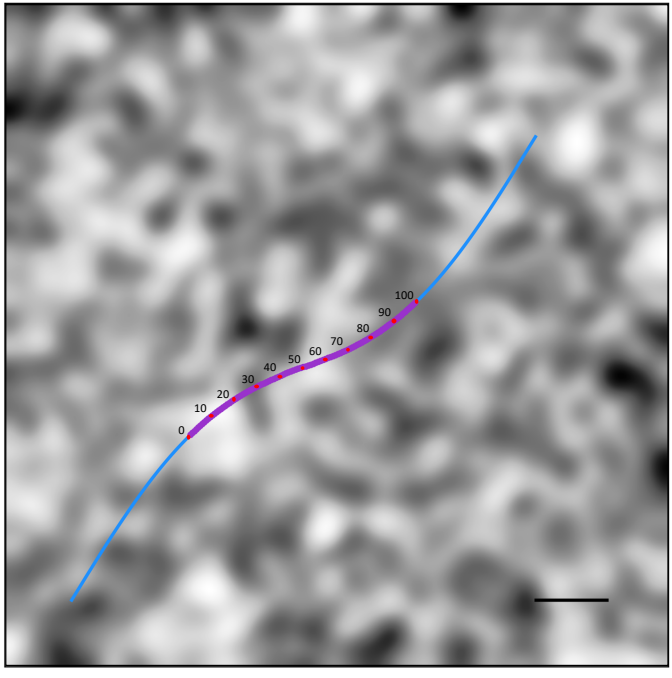
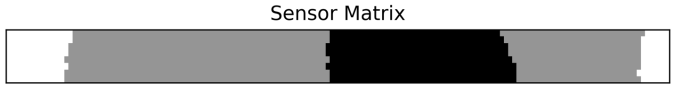
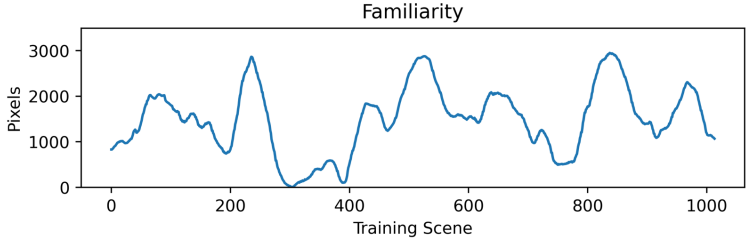
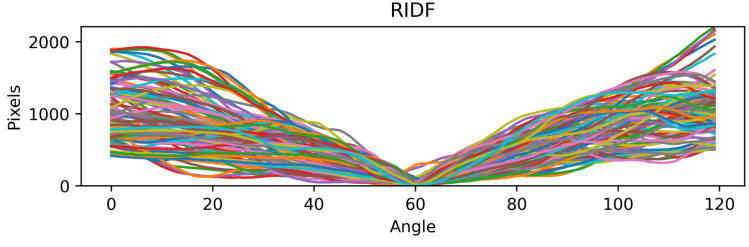
Navigation stats: RMSD error: 32.95; RMSD/dist: 0.082; TD: 950; p90: 100; p50: 44; complete: 0

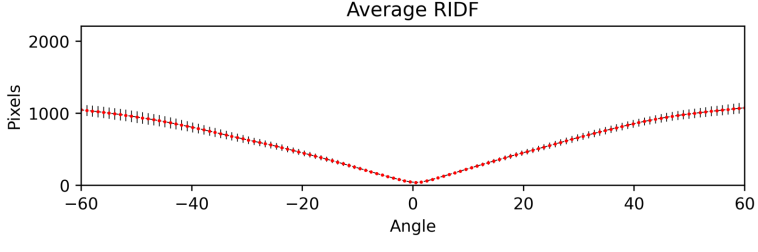
100%





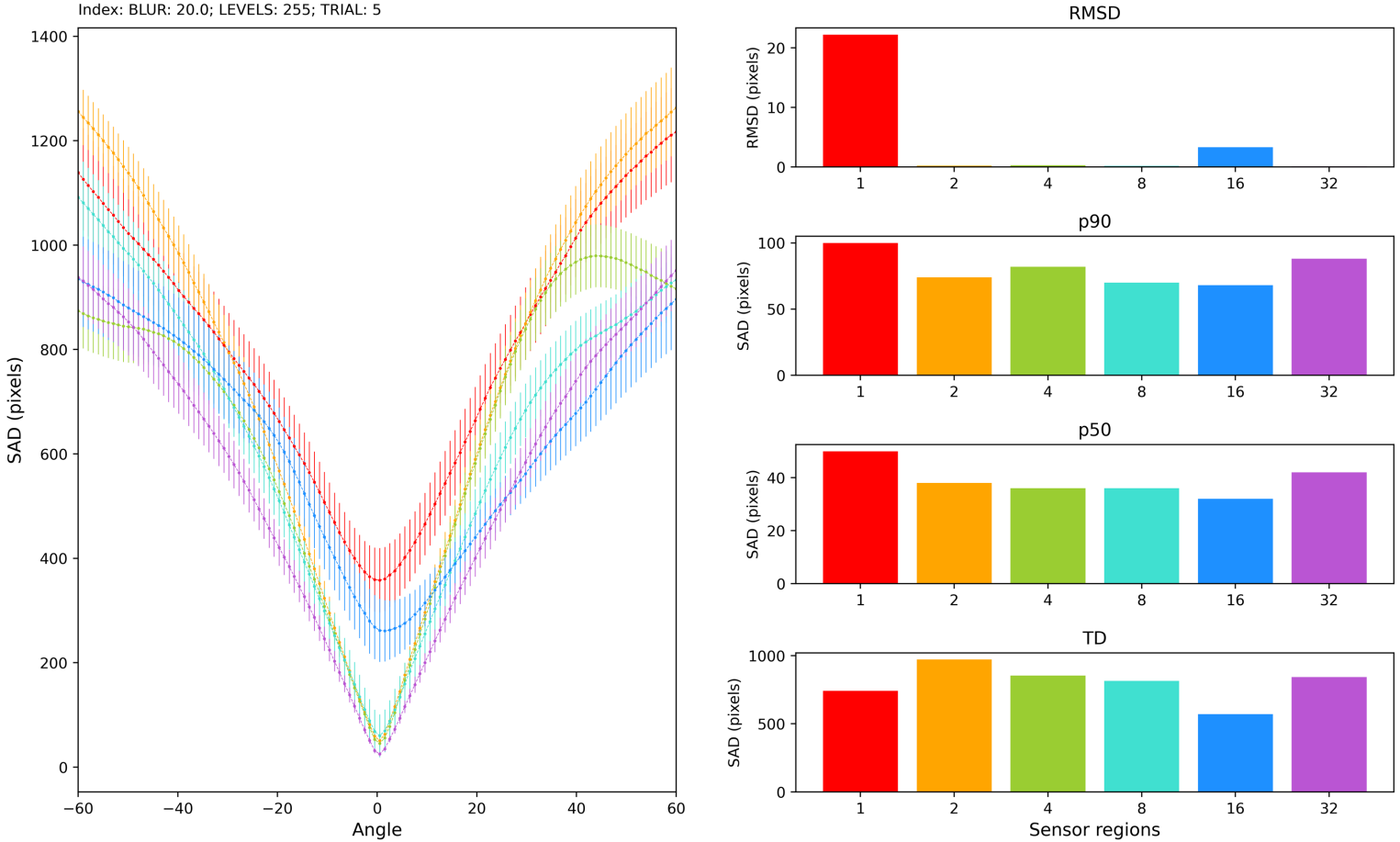




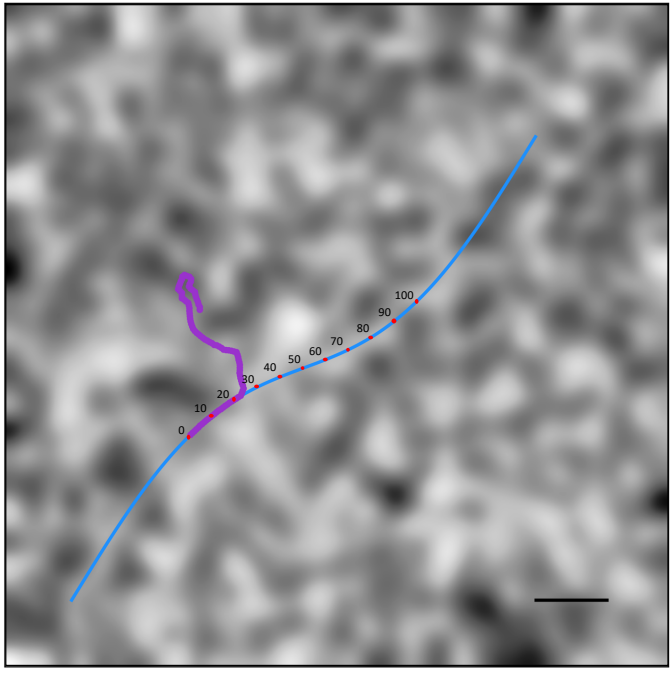


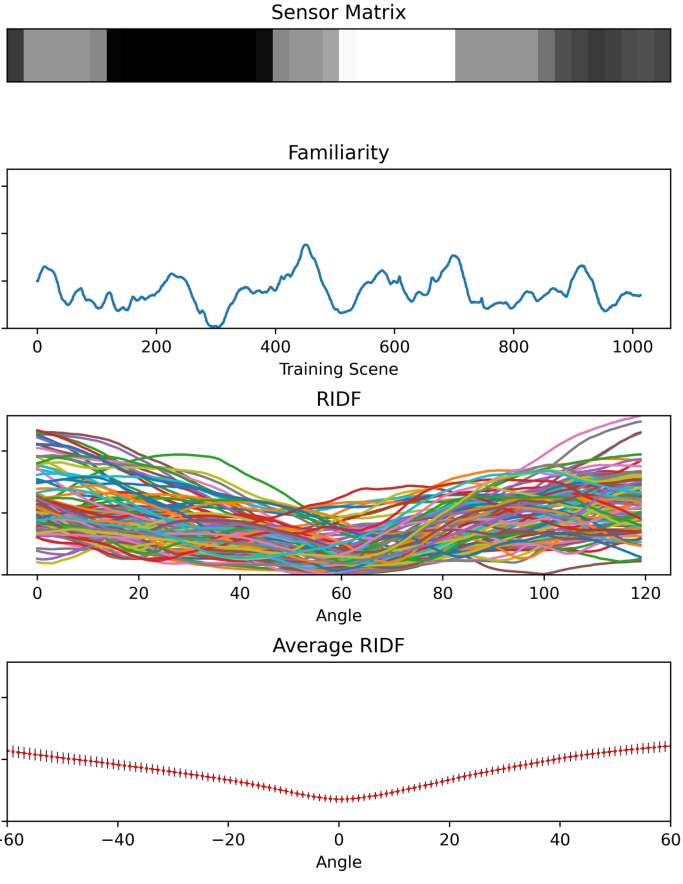
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 75.94; RMSD/dist: 0.190; TD: 1202; p90: 120; p50: 62; complete: 0


Index: BLUR: 20.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

20%

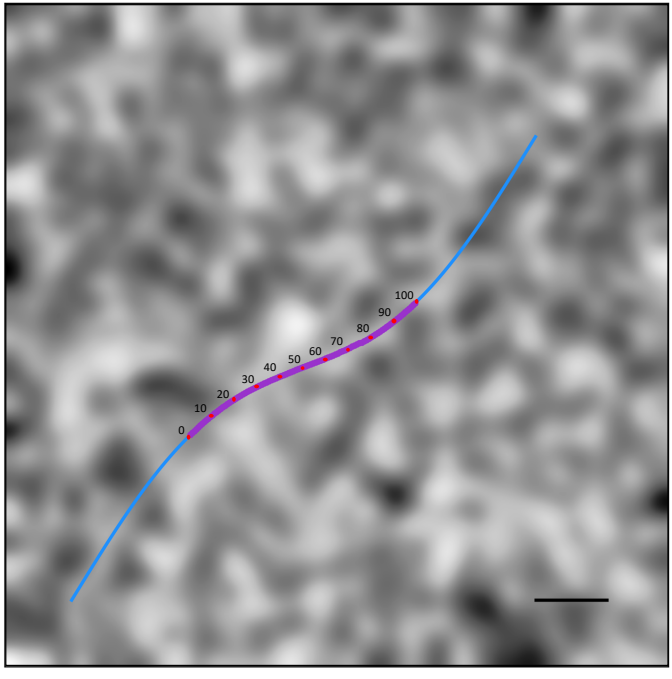


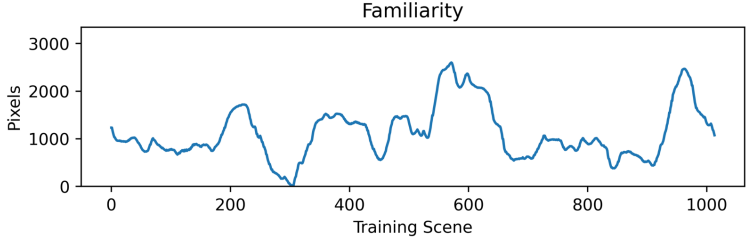


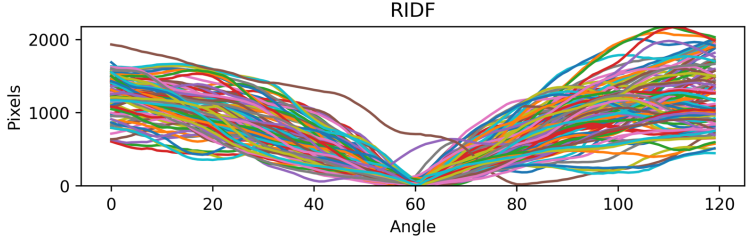
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

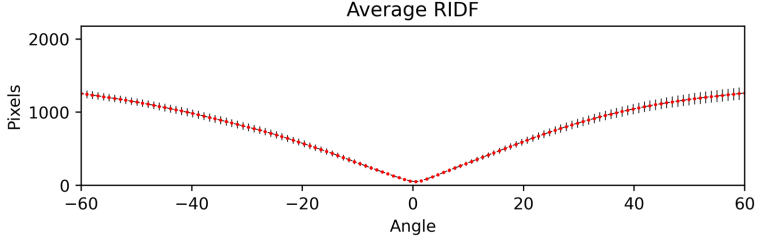
Navigation stats: RMSD error: 8885.22; RMSD/dist: 22.213; TD: 742; p90: 100; p50: 50; complete: 0

90%





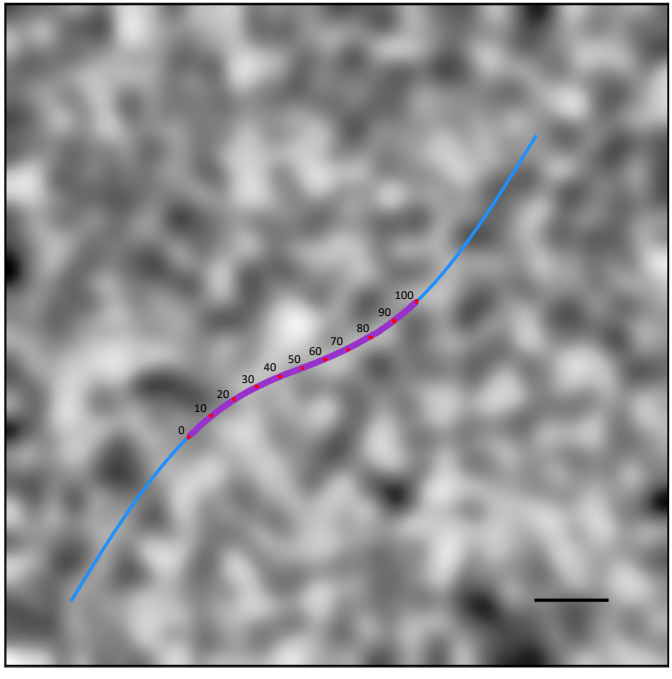


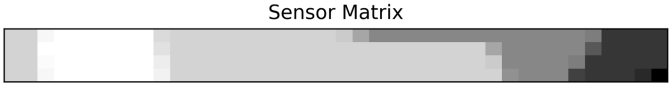


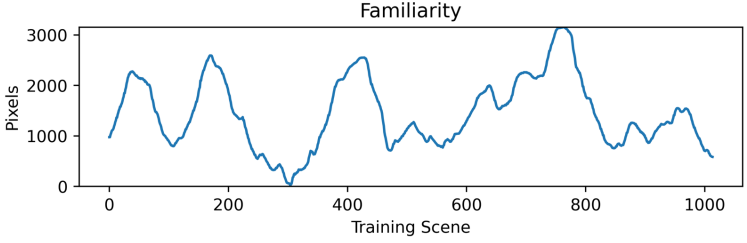
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

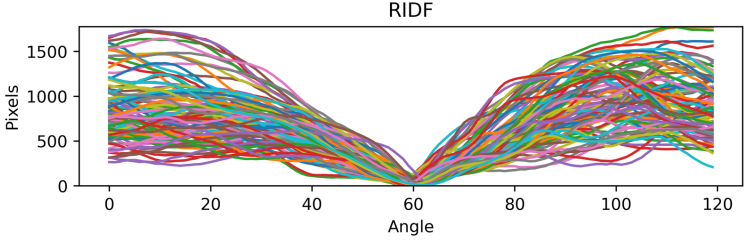
Navigation stats: RMSD error: 79.04; RMSD/dist: 0.198; TD: 971; p90: 74; p50: 38; complete: 0

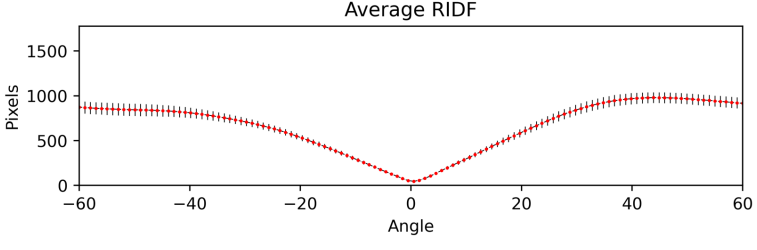
100%







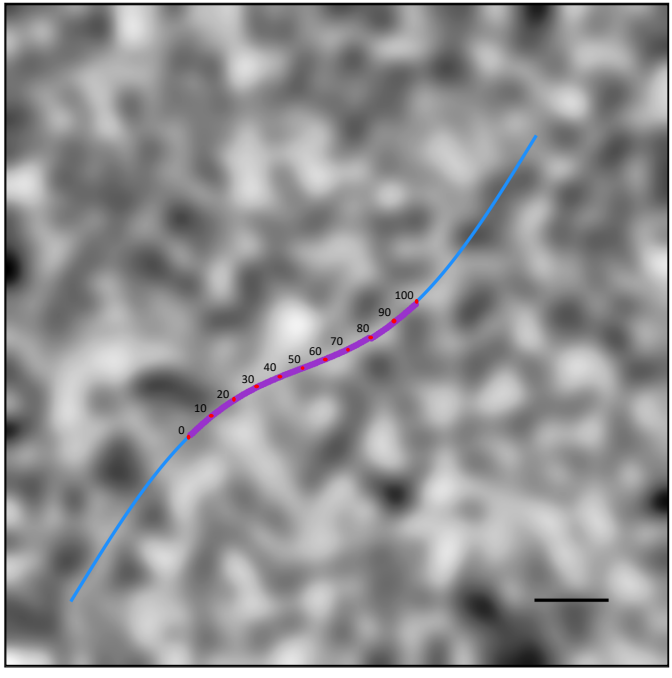


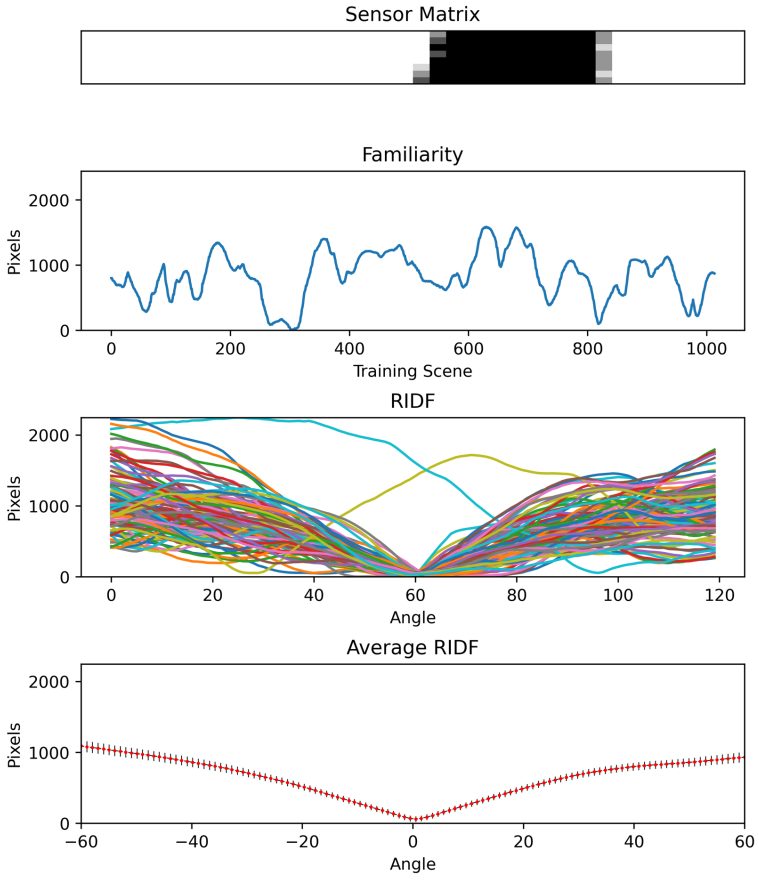


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 111.36; RMSD/dist: 0.278; TD: 854; p90: 82; p50: 36; complete: 0

90%

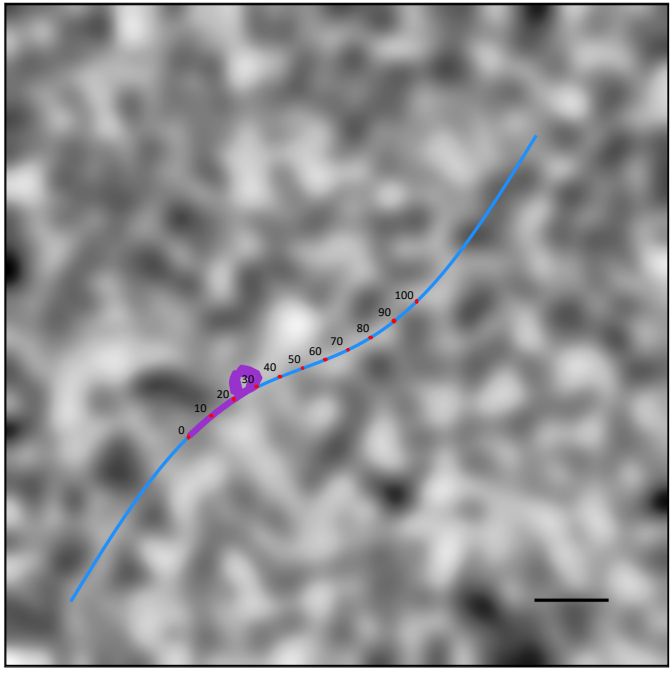


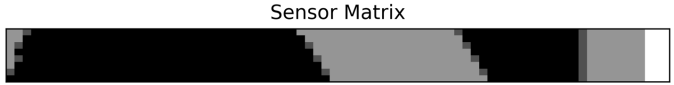


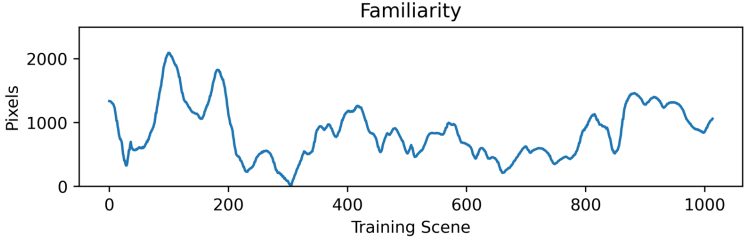
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

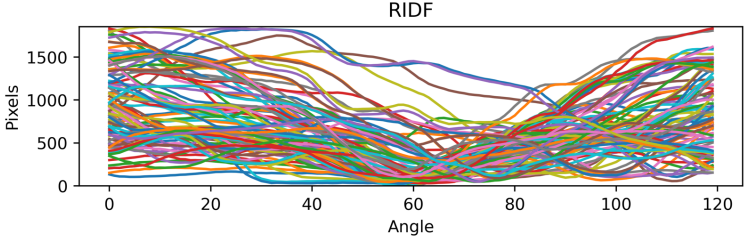
Navigation stats: RMSD error: 66.20; RMSD/dist: 0.165; TD: 815; p90: 70; p50: 36; complete: 0

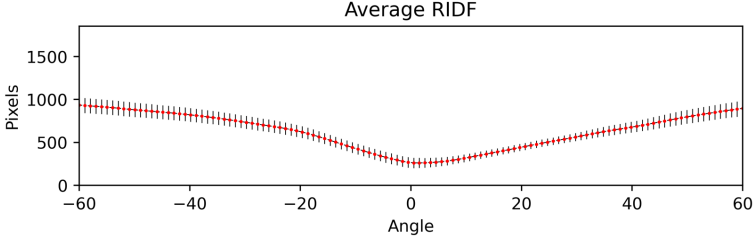
30%







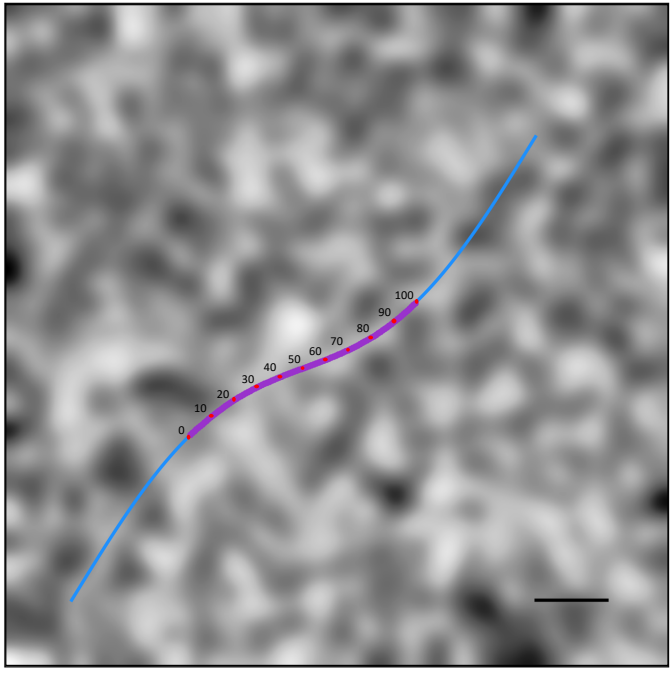


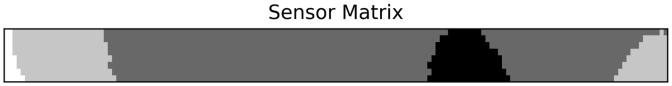


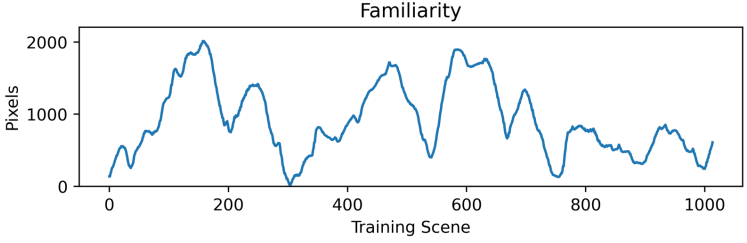
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

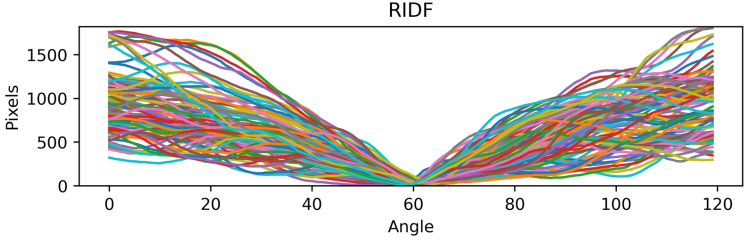
Navigation stats: RMSD error: 1320.98; RMSD/dist: 3.302; TD: 571; p90: 68; p50: 32; complete: 0

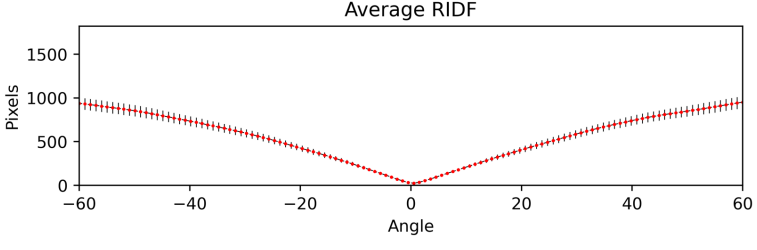
100%





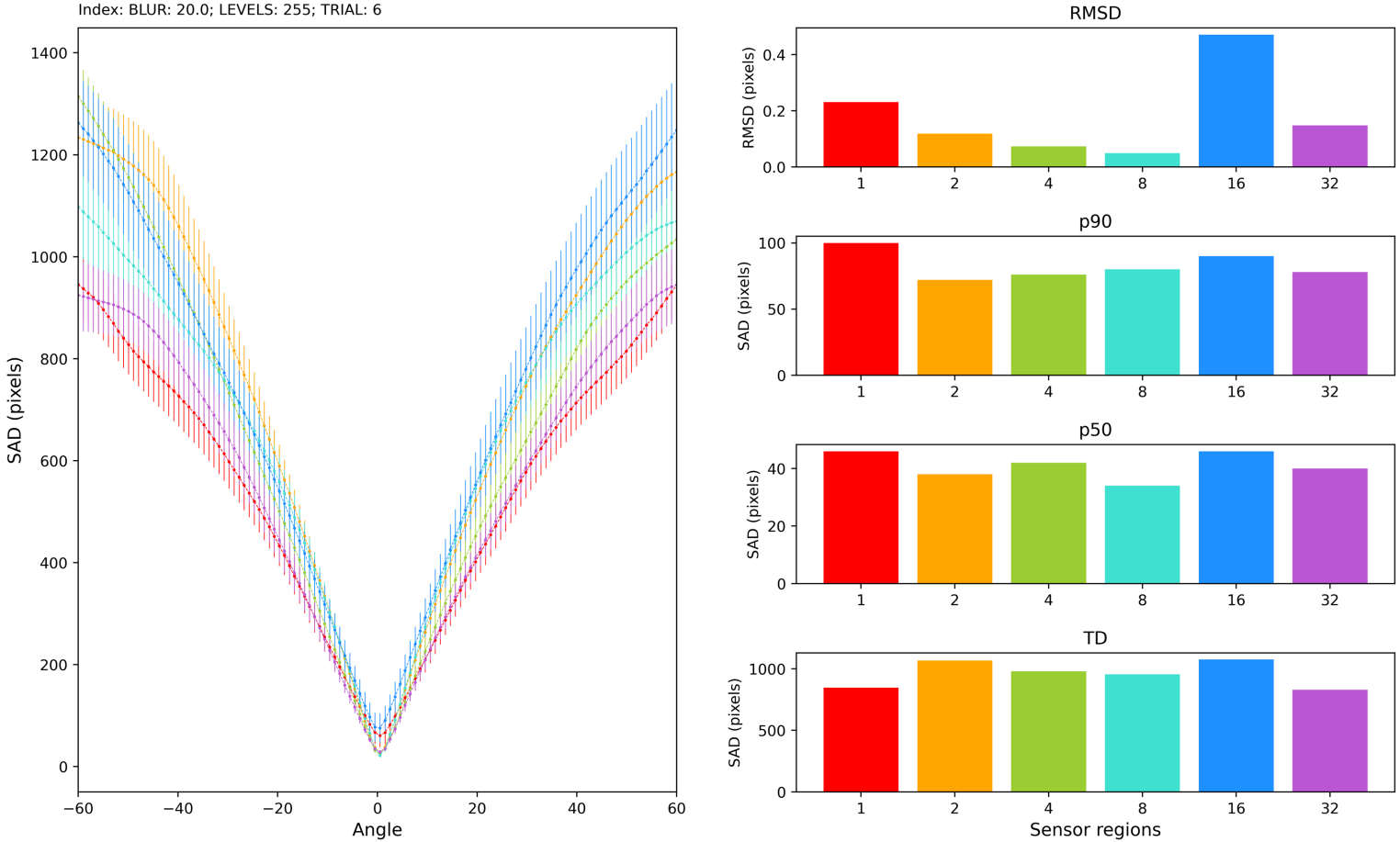




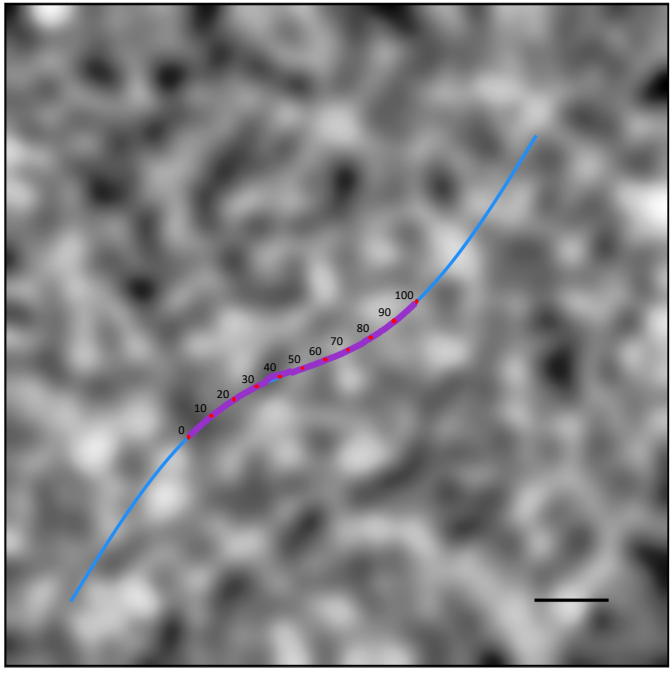


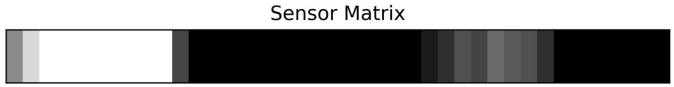
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

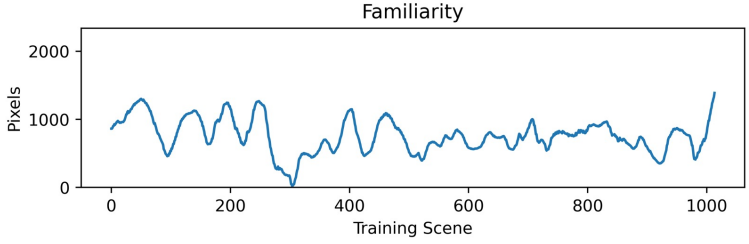
Navigation stats: RMSD error: 35.39; RMSD/dist: 0.088; TD: 843; p90: 88; p50: 42; complete: 0

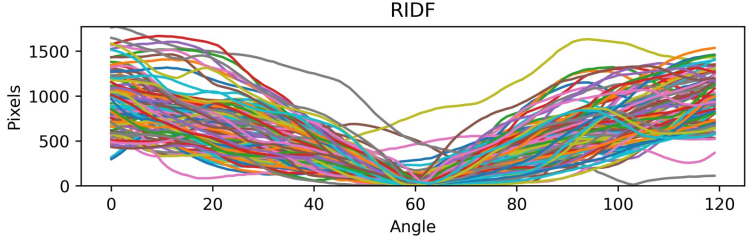

Index: BLUR: 20.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

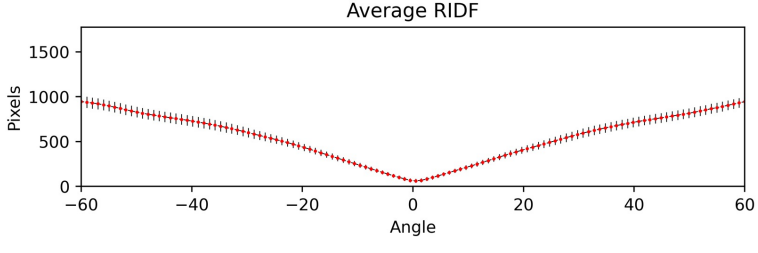
90%







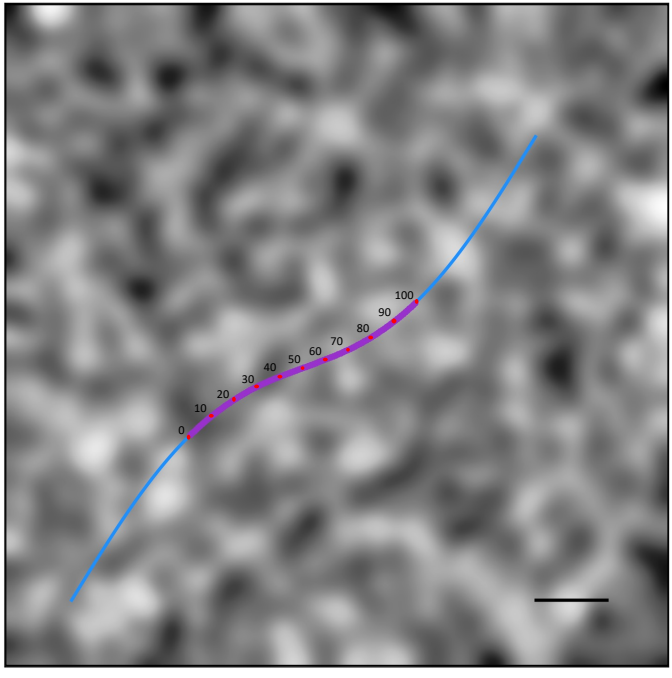


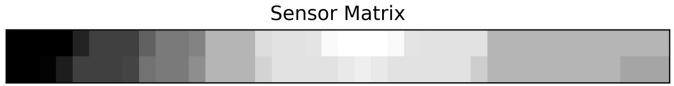


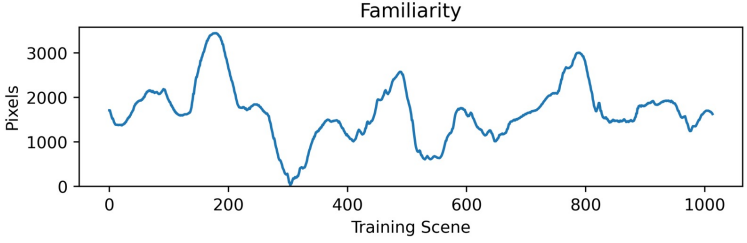
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

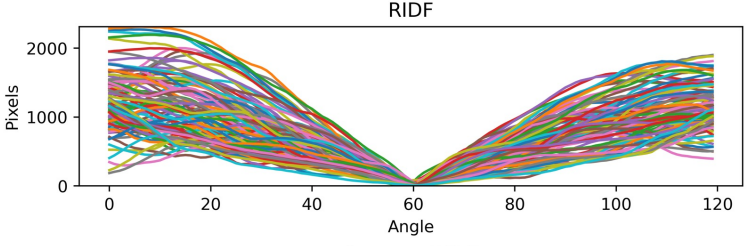
Navigation stats: RMSD error: 92.21; RMSD/dist: 0.231; TD: 847; p90: 100; p50: 46; complete: 0

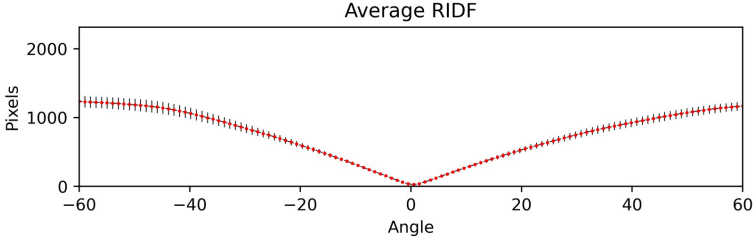
100%







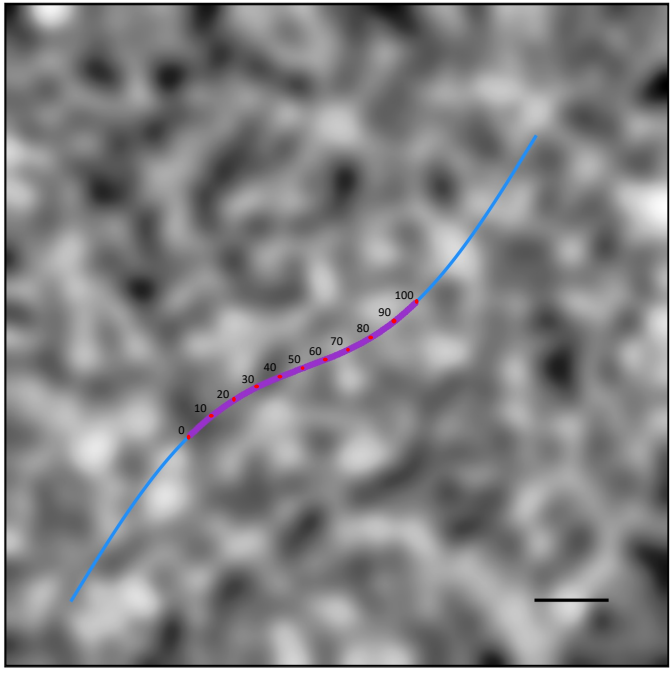


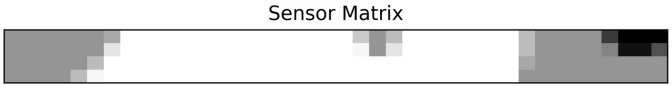


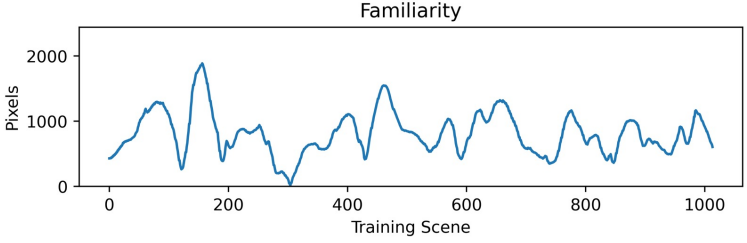
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

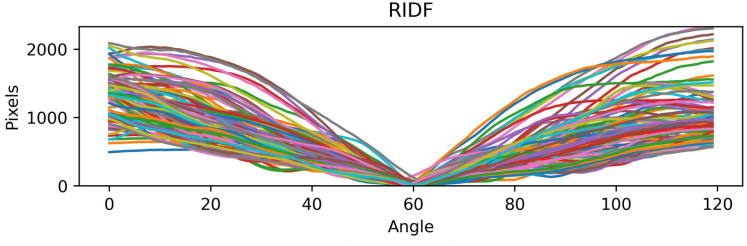
Navigation stats: RMSD error: 47.30; RMSD/dist: 0.118; TD: 1067; p90: 72; p50: 38; complete: 0

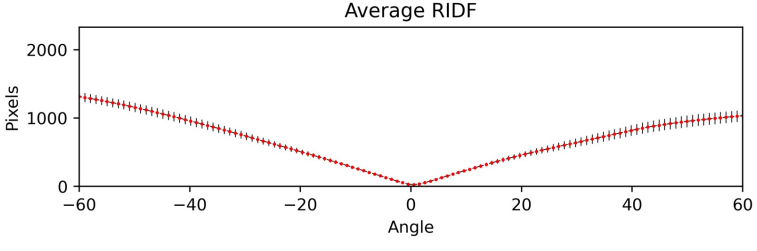
100%







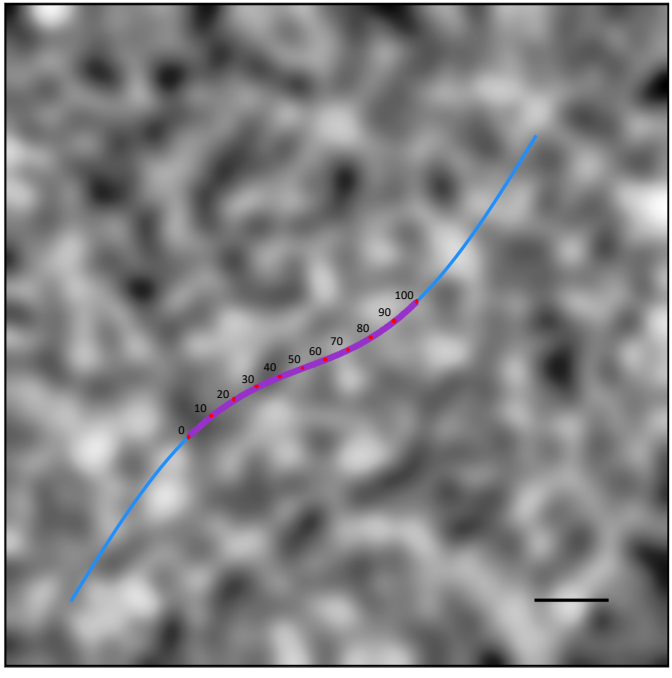


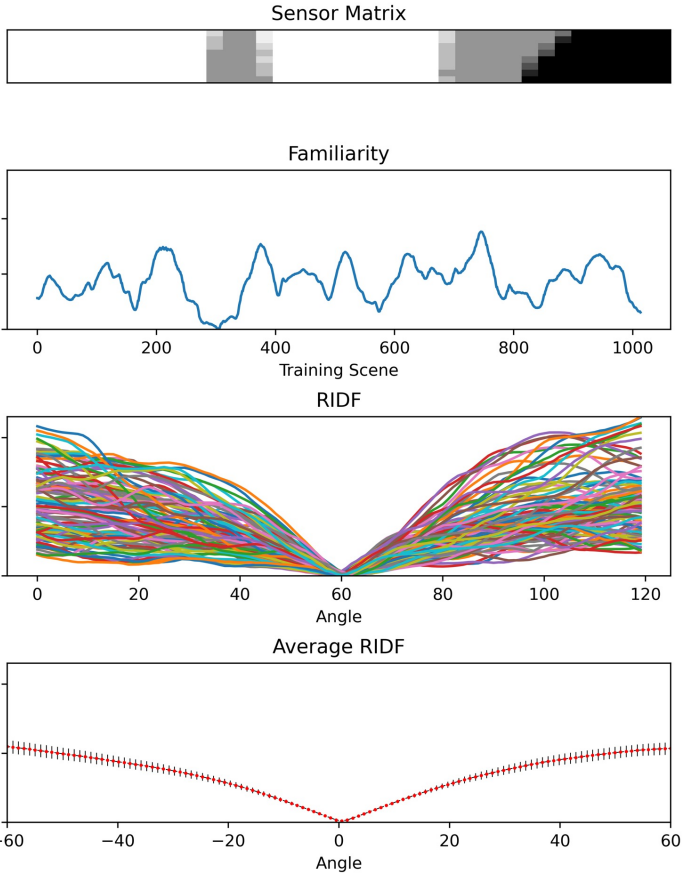


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 29.10; RMSD/dist: 0.073; TD: 979; p90: 76; p50: 42; complete: 0

100%

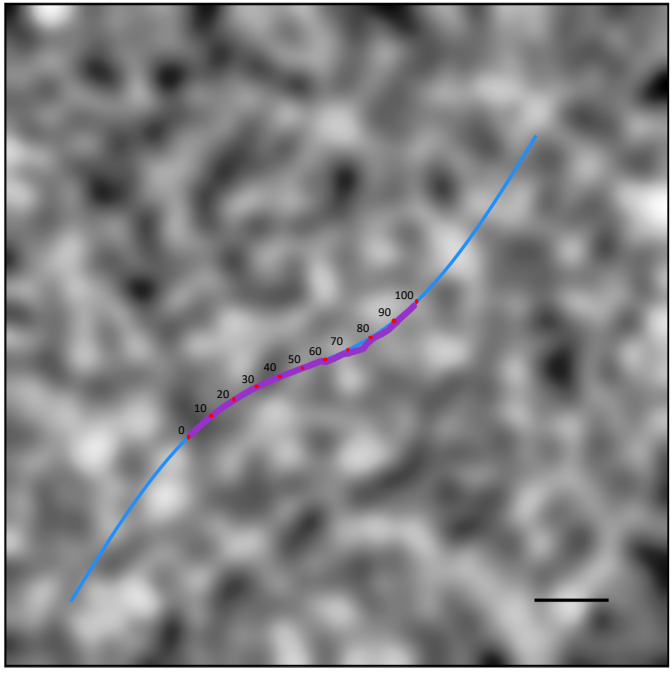


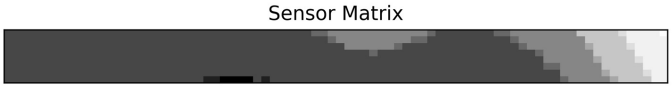


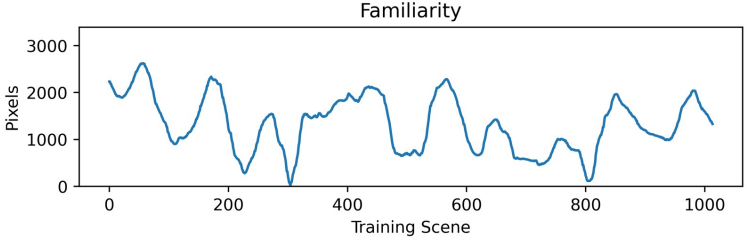
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

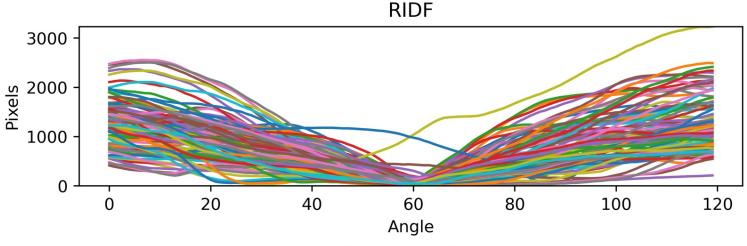
Navigation stats: RMSD error: 19.61; RMSD/dist: 0.049; TD: 956; p90: 80; p50: 34; complete: 0

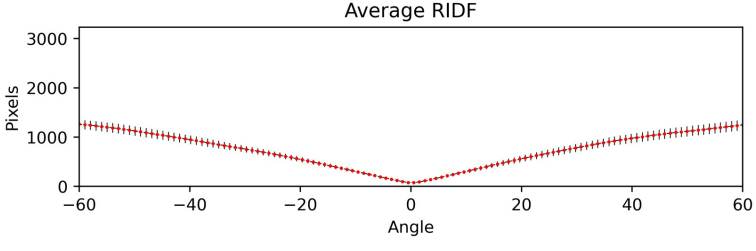
80%







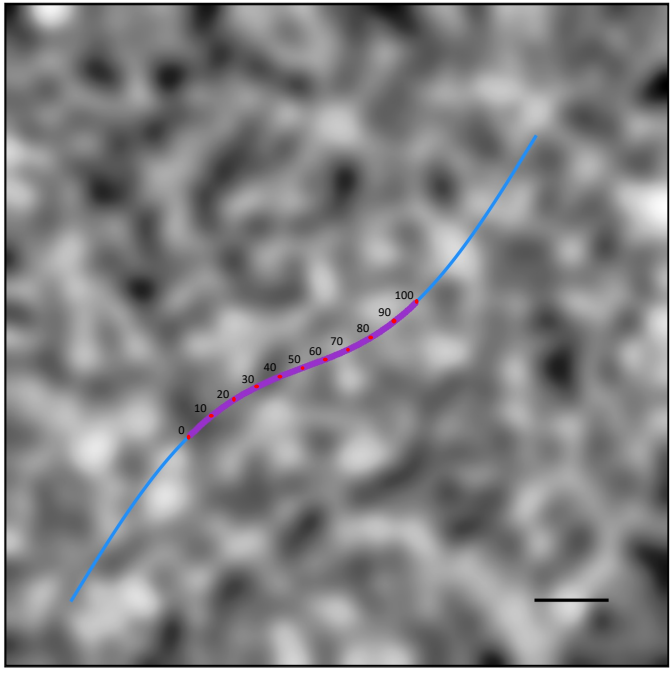


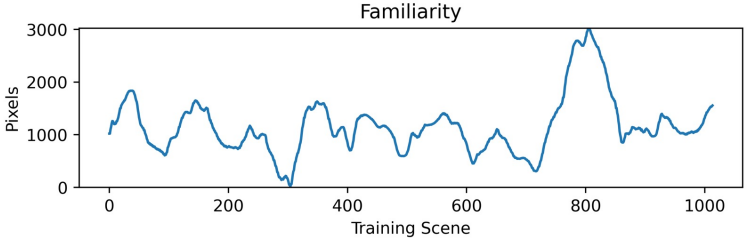


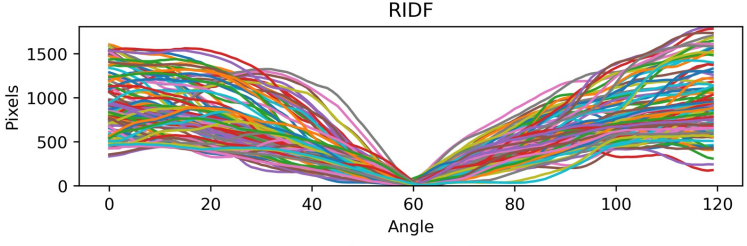
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

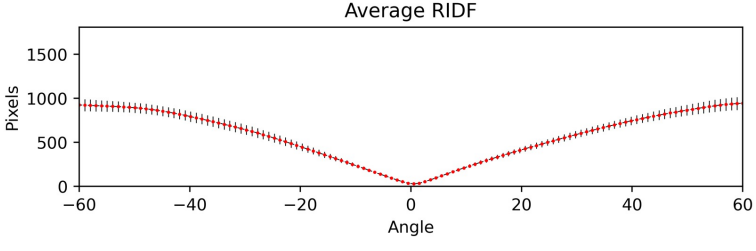
Navigation stats: RMSD error: 188.24; RMSD/dist: 0.471; TD: 1075; p90: 90; p50: 46; complete: 0

100%



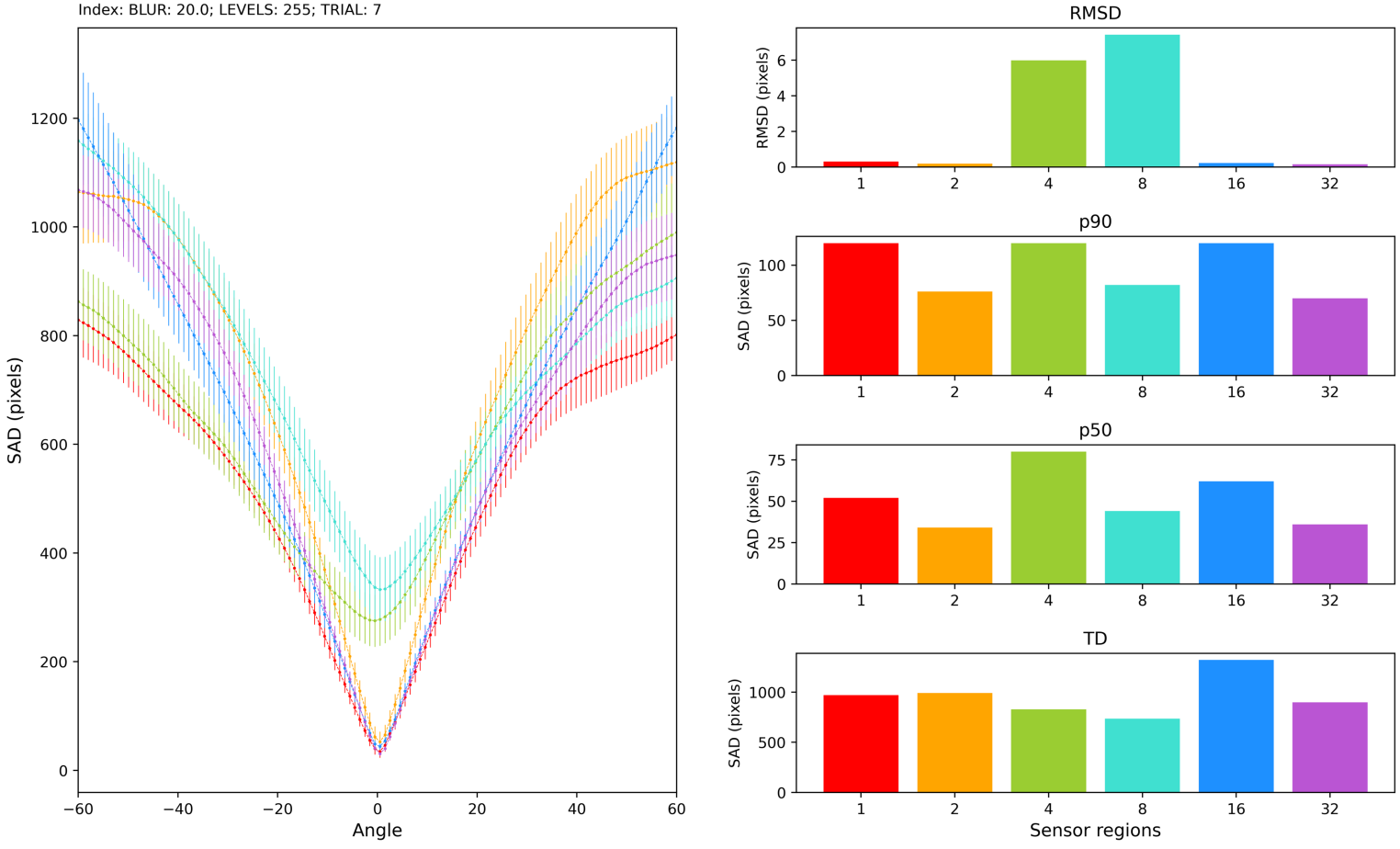




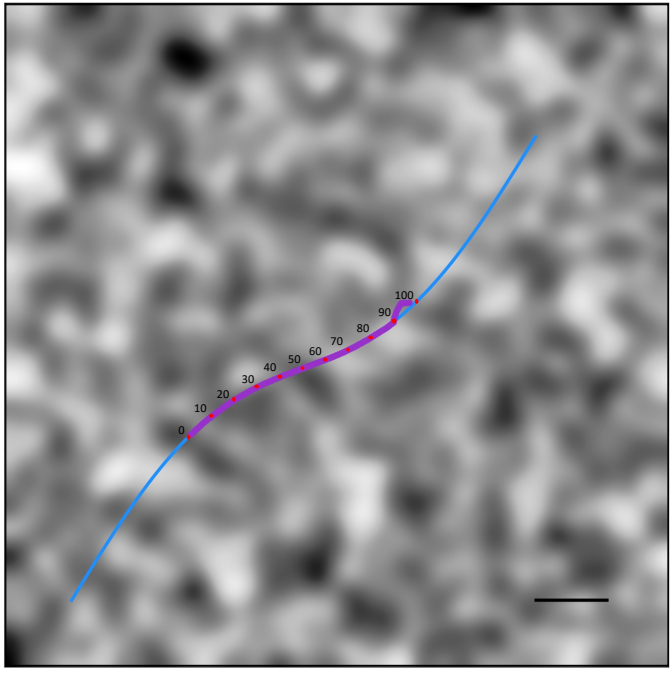


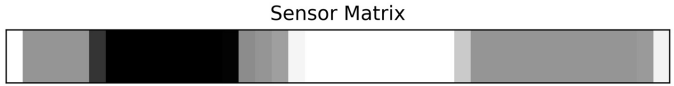
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

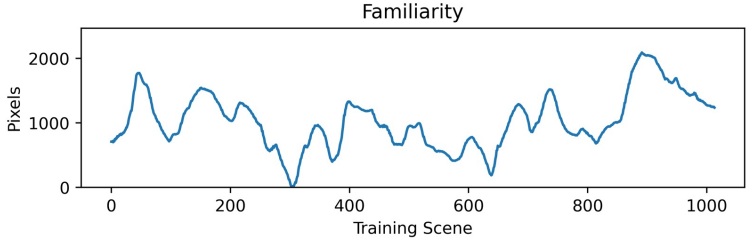
Navigation stats: RMSD error: 59.39; RMSD/dist: 0.148; TD: 830; p90: 78; p50: 40; complete: 0

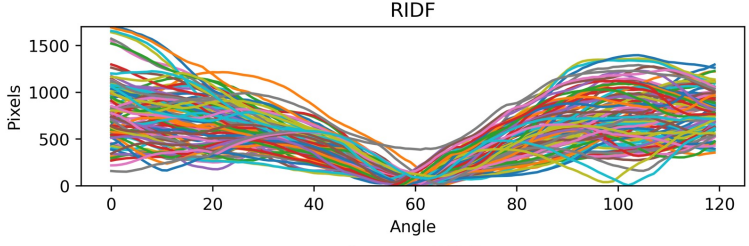

Index: BLUR: 20.0; LEVELS: 255; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

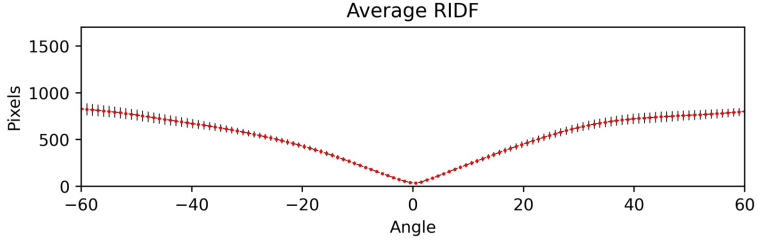
90%







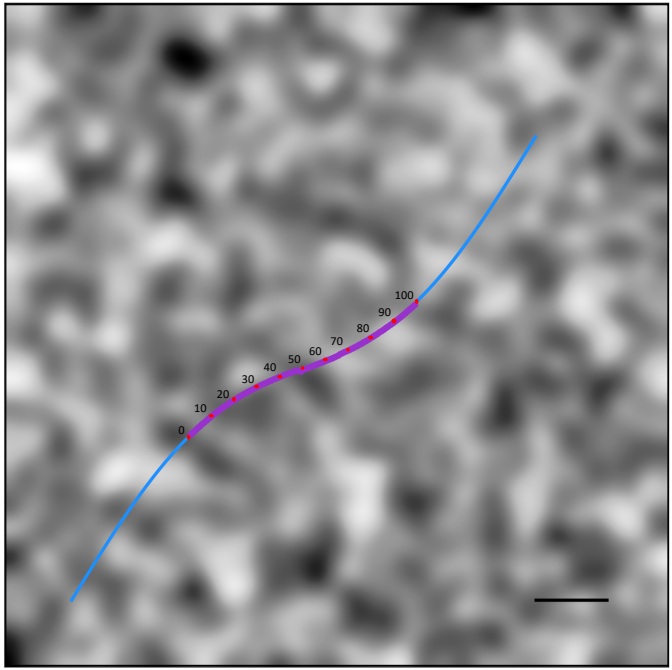


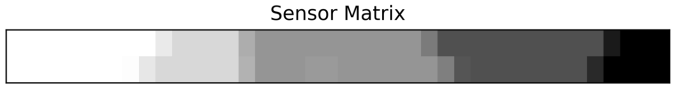


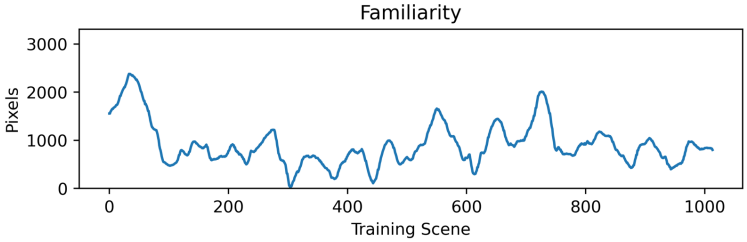
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

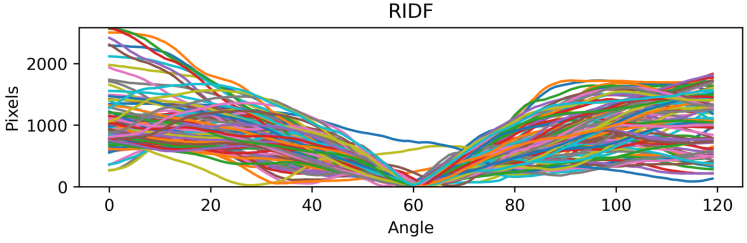
Navigation stats: RMSD error: 120.38; RMSD/dist: 0.301; TD: 970; p90: 120; p50: 52; complete: 0

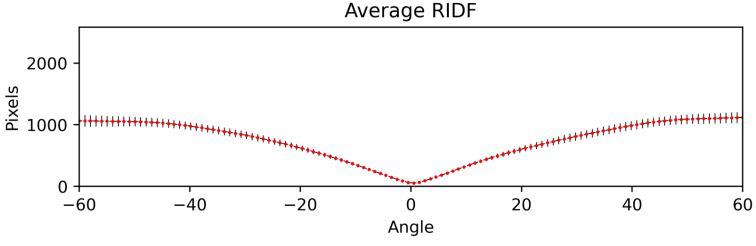
90%







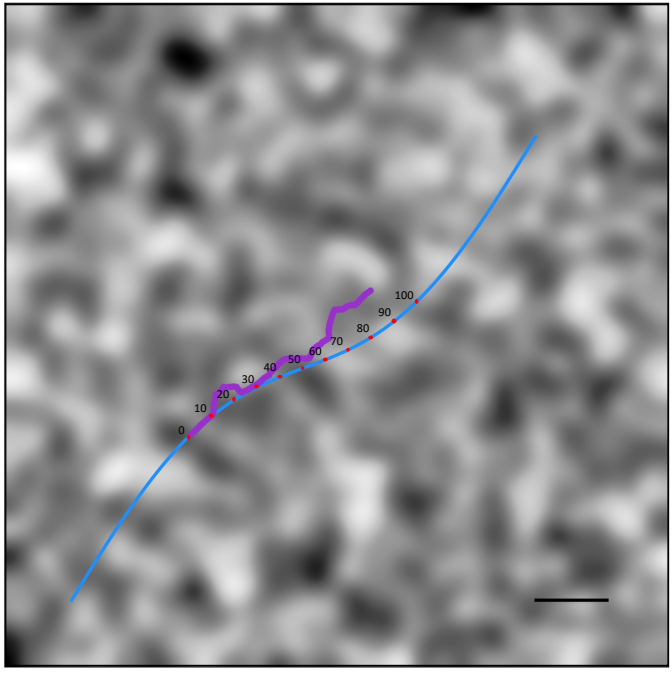


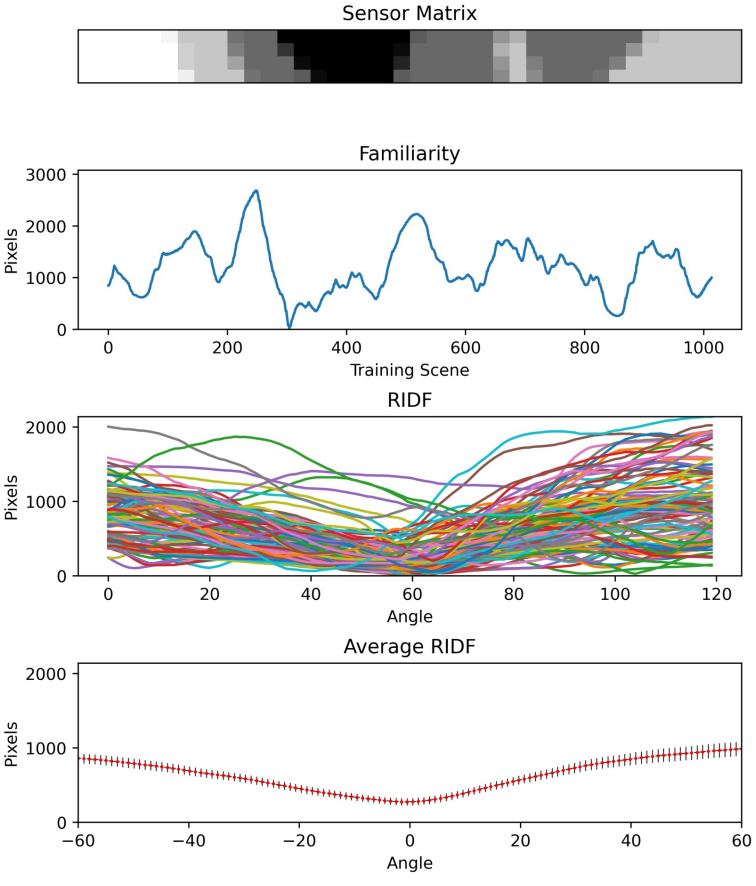


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 75.20; RMSD/dist: 0.188; TD: 992; p90: 76; p50: 34; complete: 0

10%

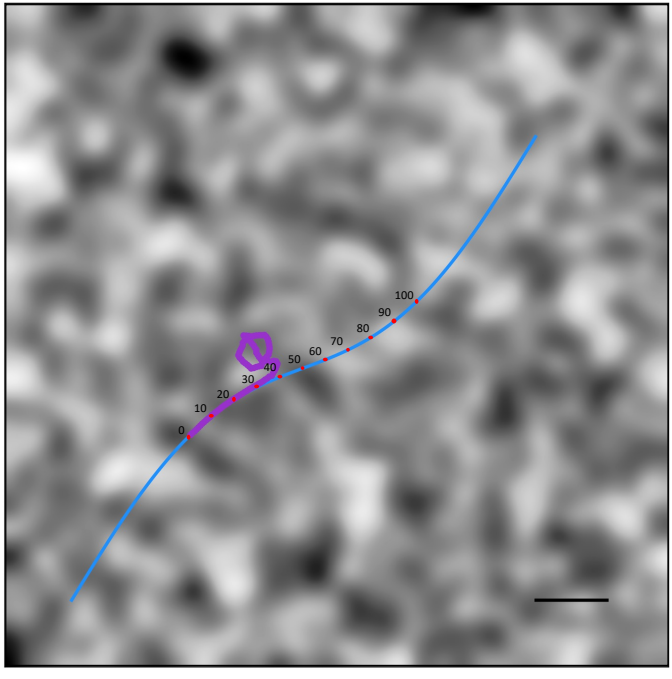


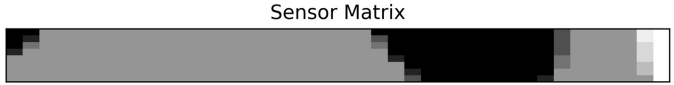


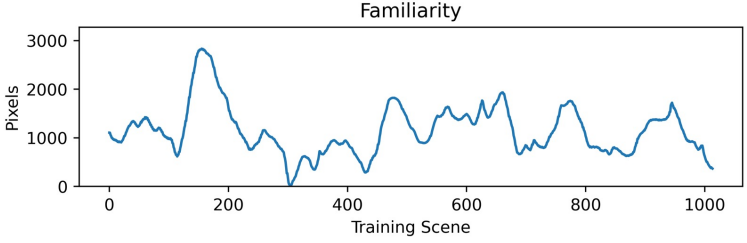
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

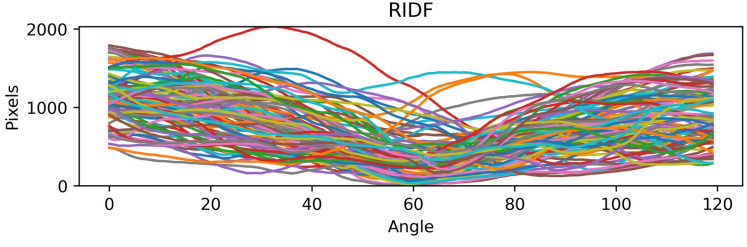
Navigation stats: RMSD error: 2398.87; RMSD/dist: 5.997; TD: 828; p90: 120; p50: 80; complete: 0

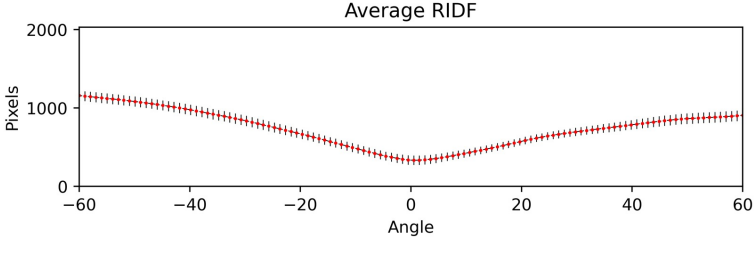
30%







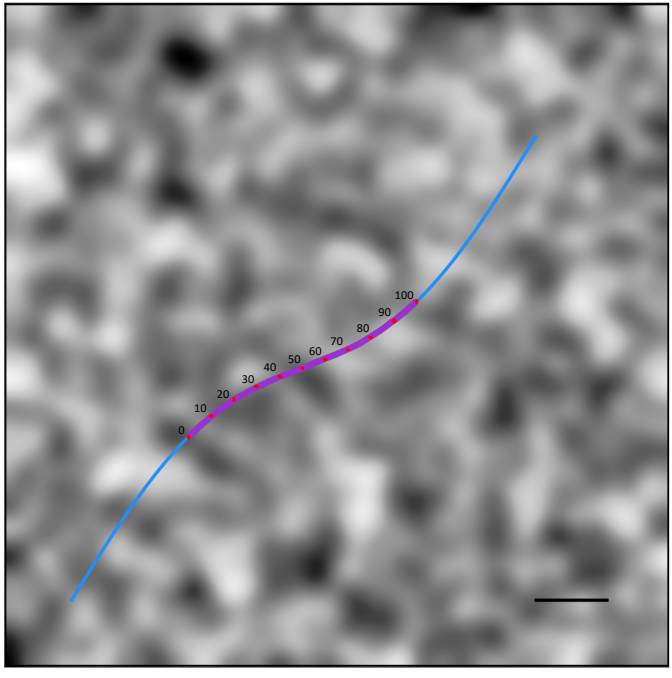


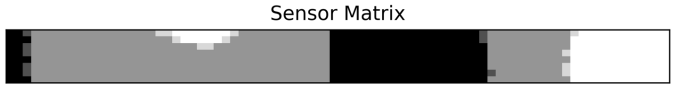


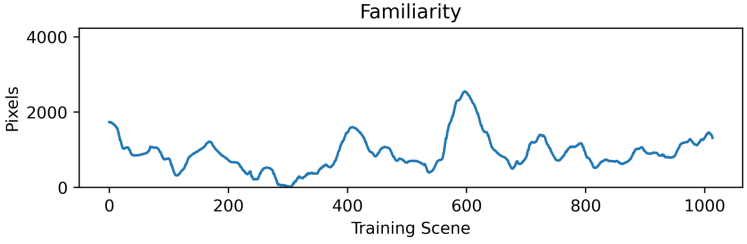
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

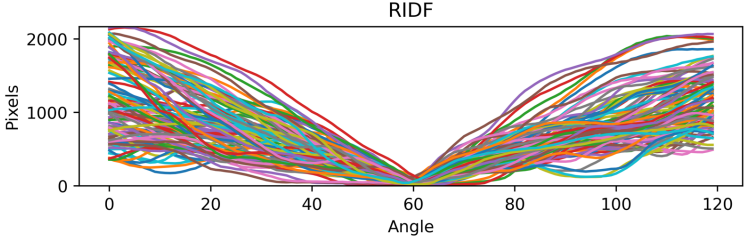
Navigation stats: RMSD error: 2975.60; RMSD/dist: 7.439; TD: 735; p90: 82; p50: 44; complete: 0

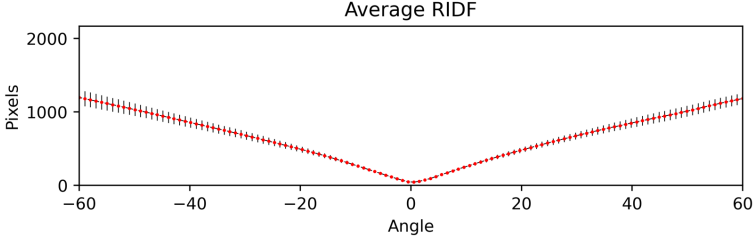
100%







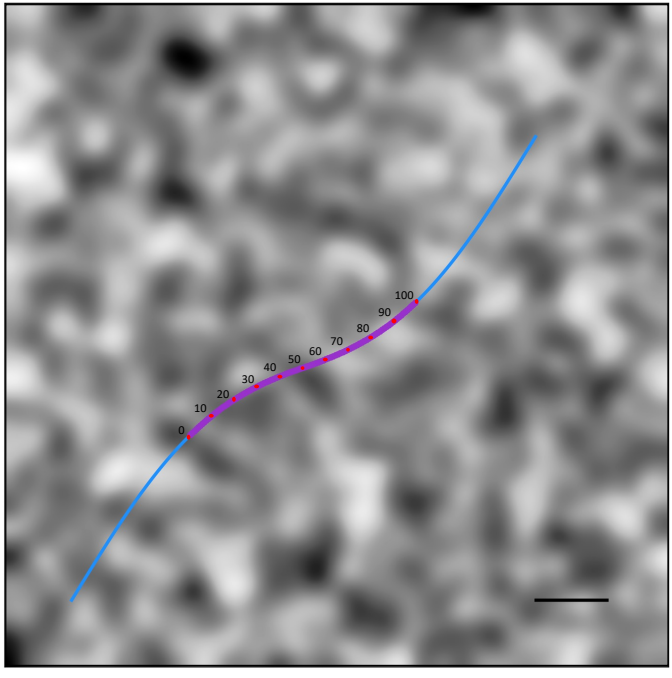


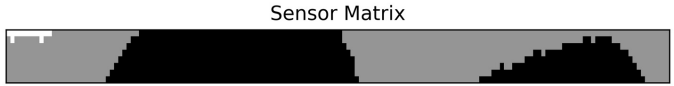


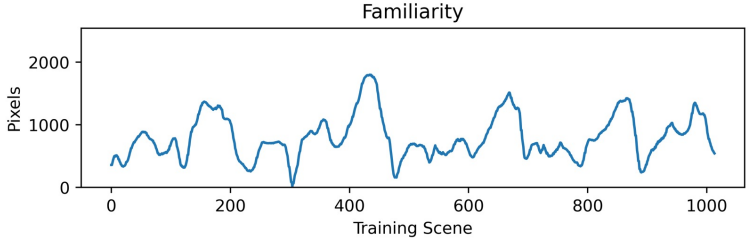
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

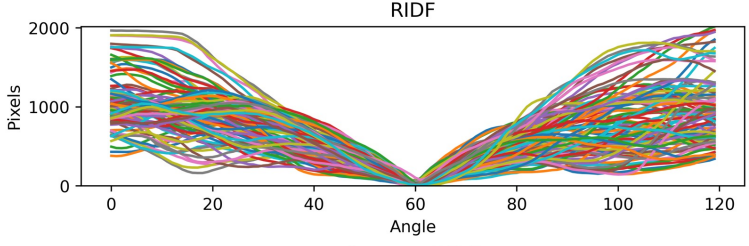
Navigation stats: RMSD error: 89.61; RMSD/dist: 0.224; TD: 1321; p90: 120; p50: 62; complete: 0

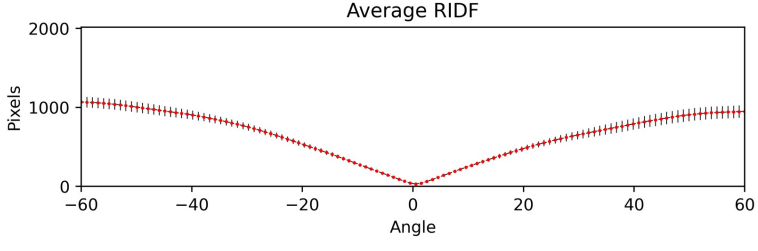
100%





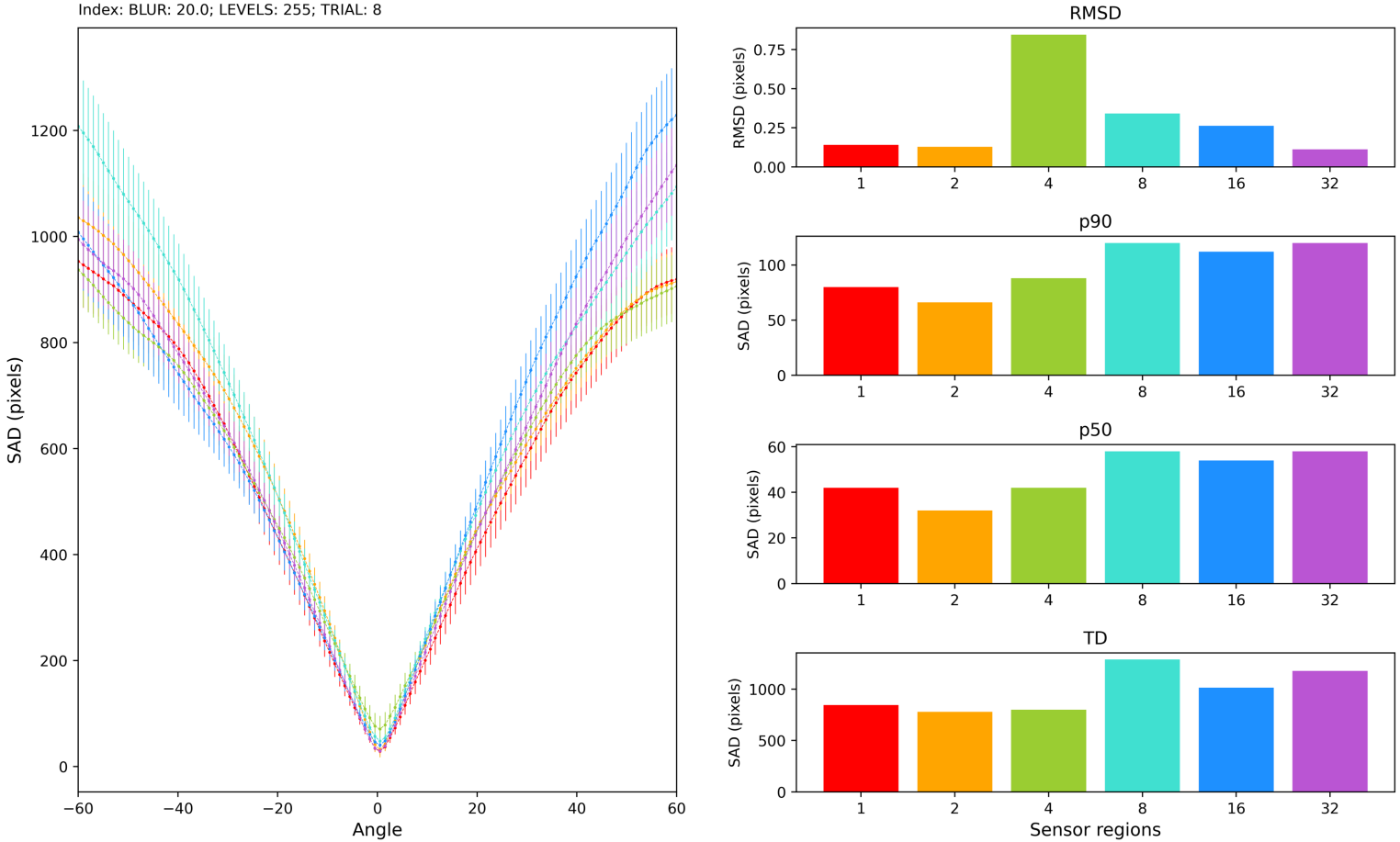




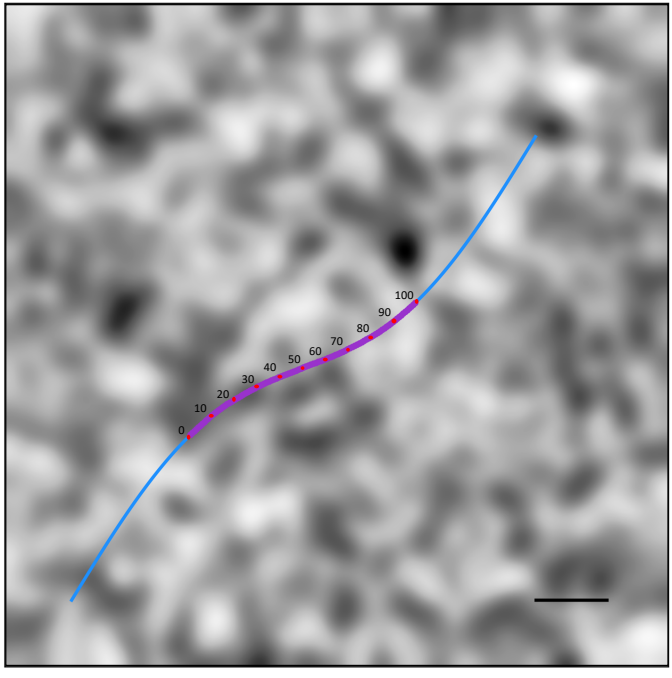


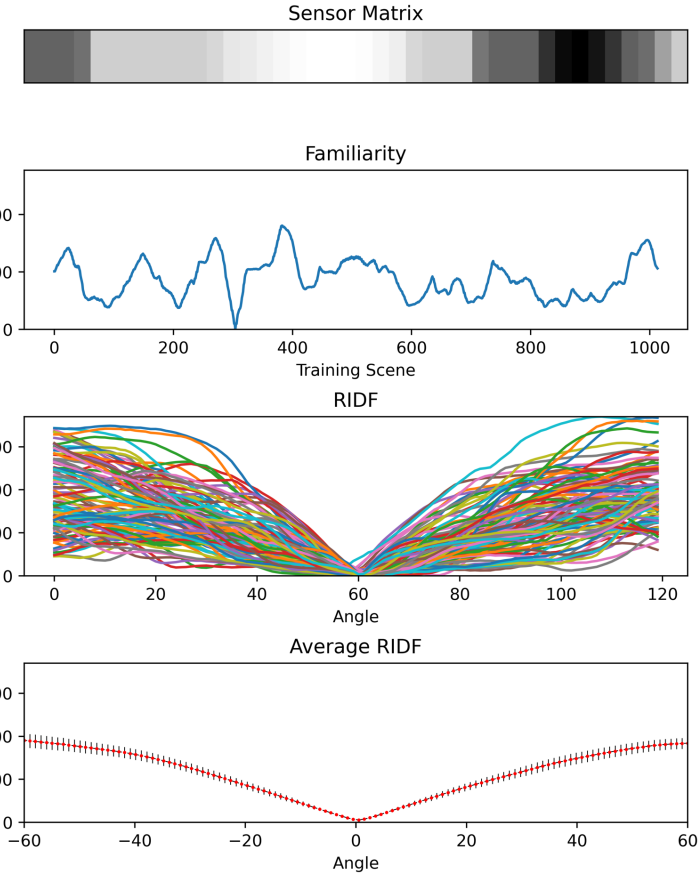
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 60.69; RMSD/dist: 0.152; TD: 898; p90: 70; p50: 36; complete: 0


Index: BLUR: 20.0; LEVELS: 255; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

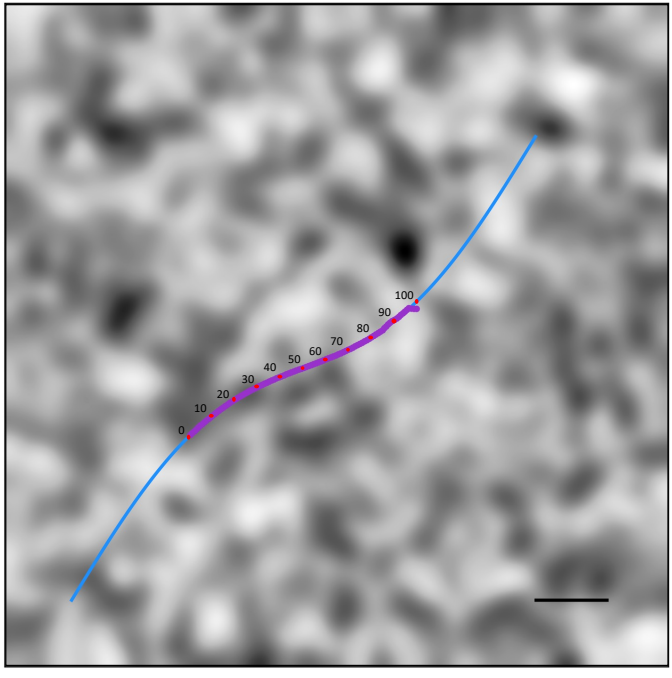


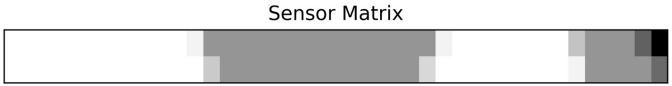


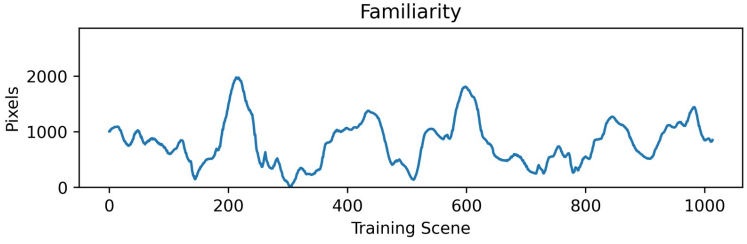
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

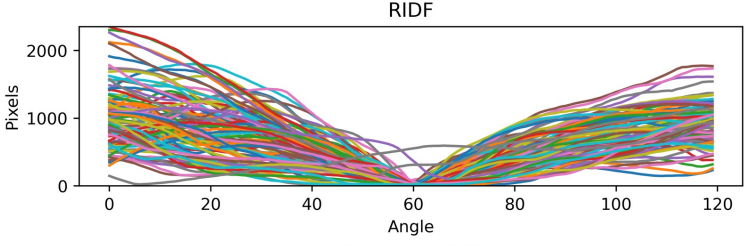
Navigation stats: RMSD error: 56.26; RMSD/dist: 0.141; TD: 845; p90: 80; p50: 42; complete: 0

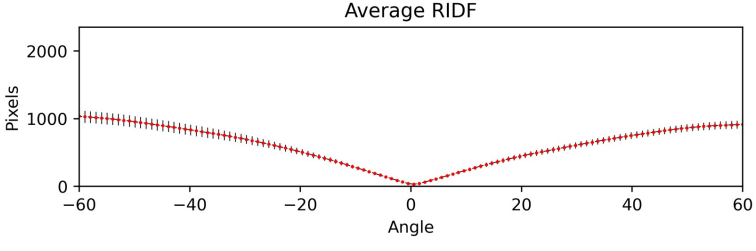
90%







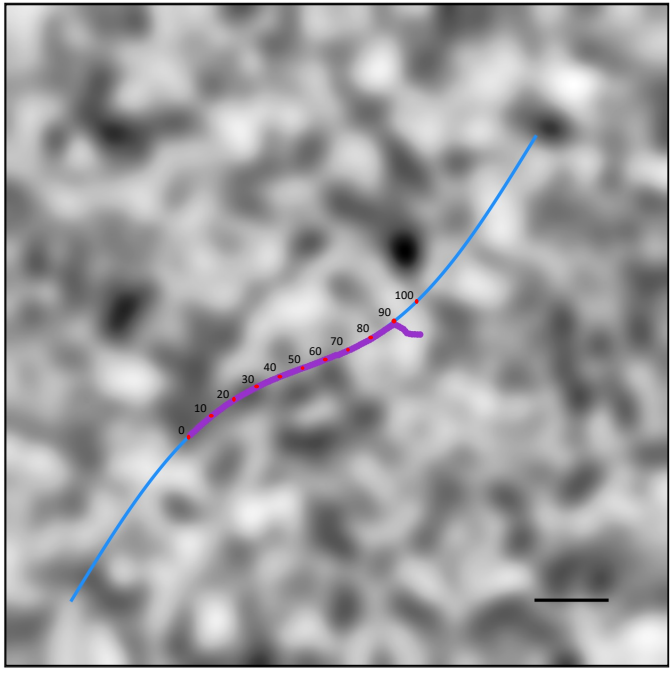


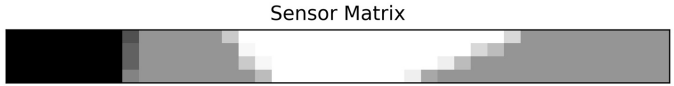


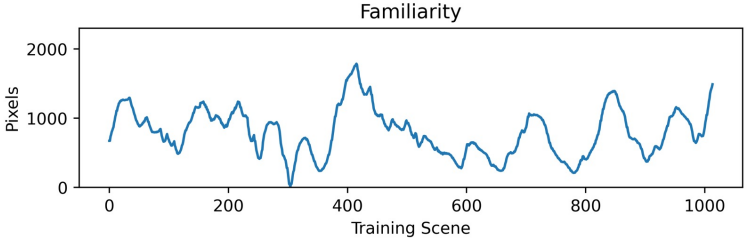
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

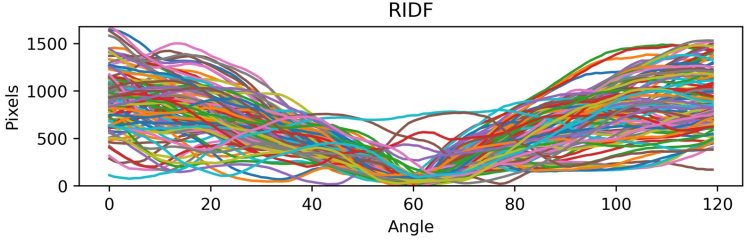
Navigation stats: RMSD error: 51.68; RMSD/dist: 0.129; TD: 780; p90: 66; p50: 32; complete: 0

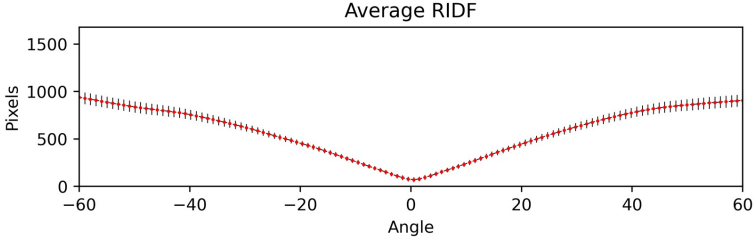
80%







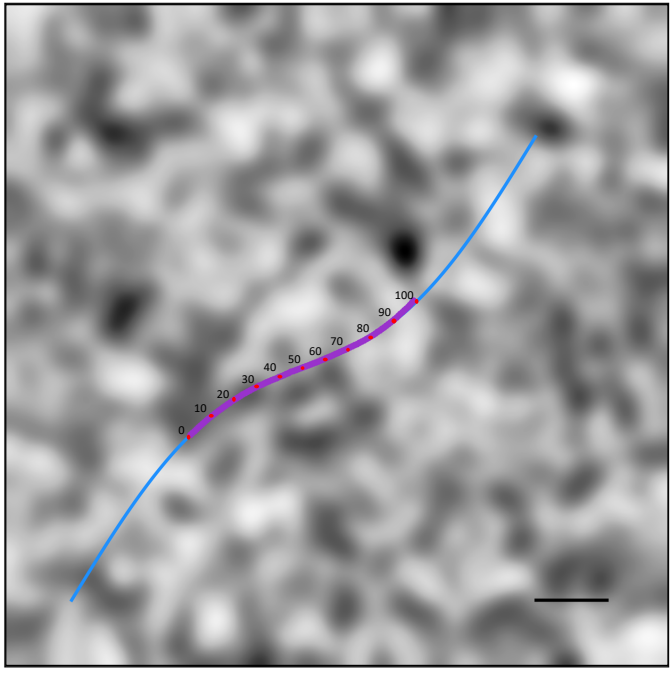


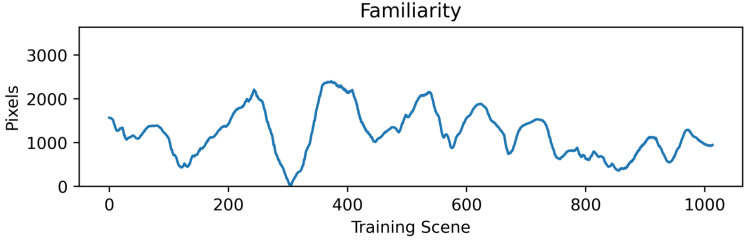


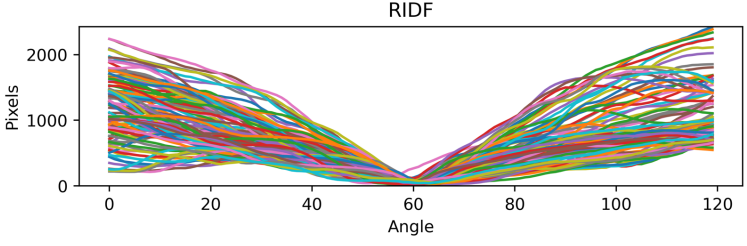
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

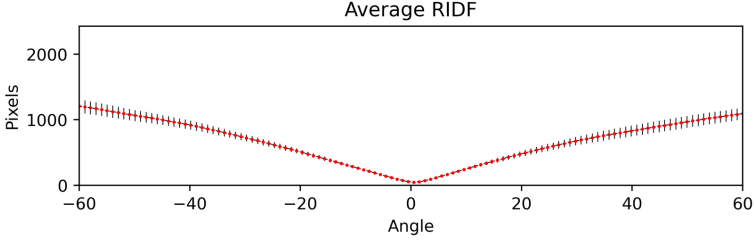
Navigation stats: RMSD error: 338.44; RMSD/dist: 0.846; TD: 800; p90: 88; p50: 42; complete: 0

100%





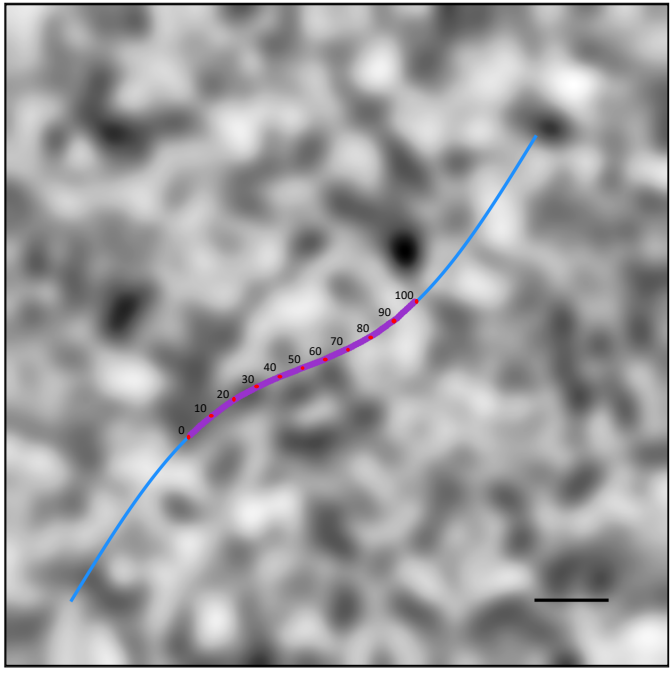


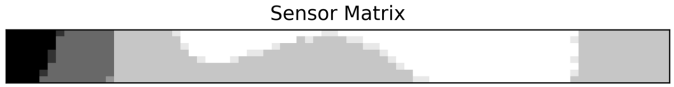


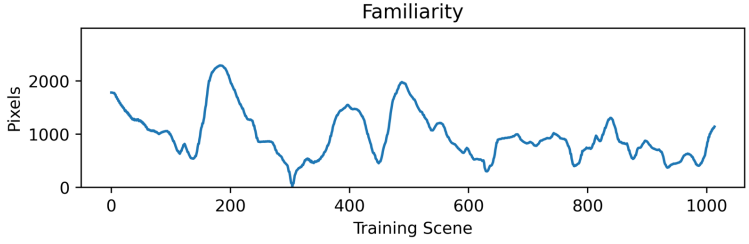
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

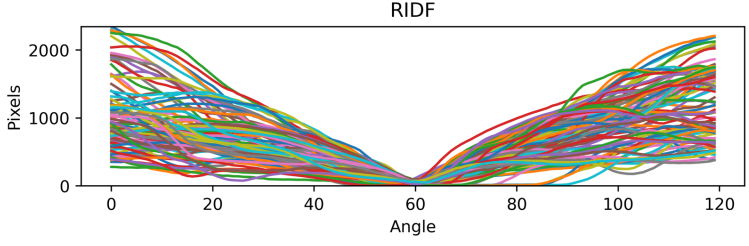
Navigation stats: RMSD error: 136.58; RMSD/dist: 0.341; TD: 1288; p90: 120; p50: 58; complete: 0

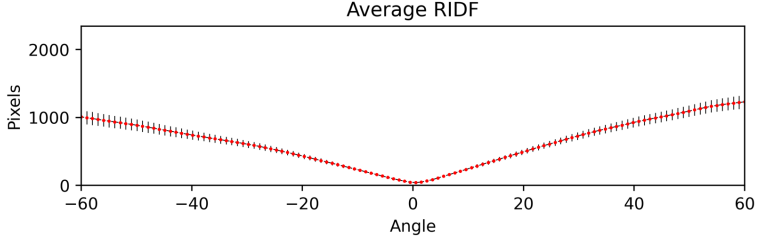
100%







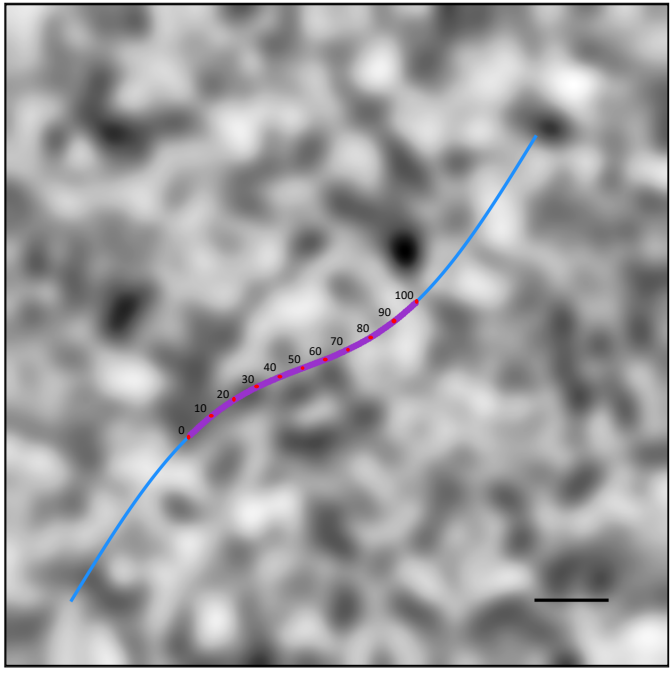


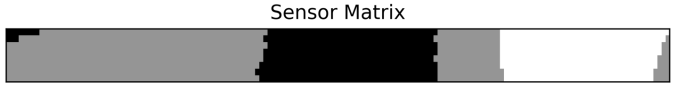


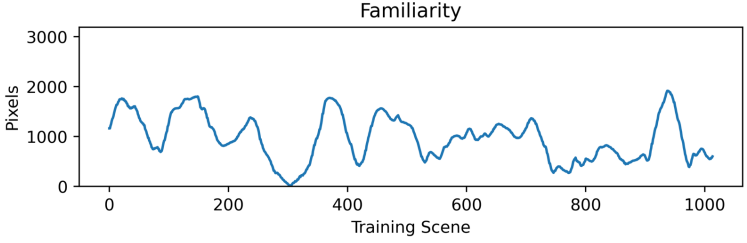
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

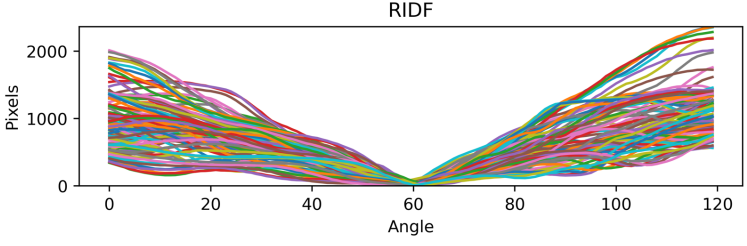
Navigation stats: RMSD error: 105.25; RMSD/dist: 0.263; TD: 1015; p90: 112; p50: 54; complete: 0

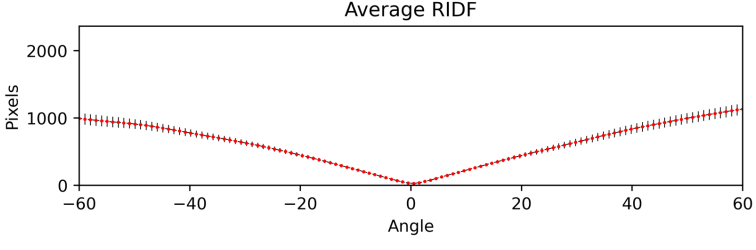
100%





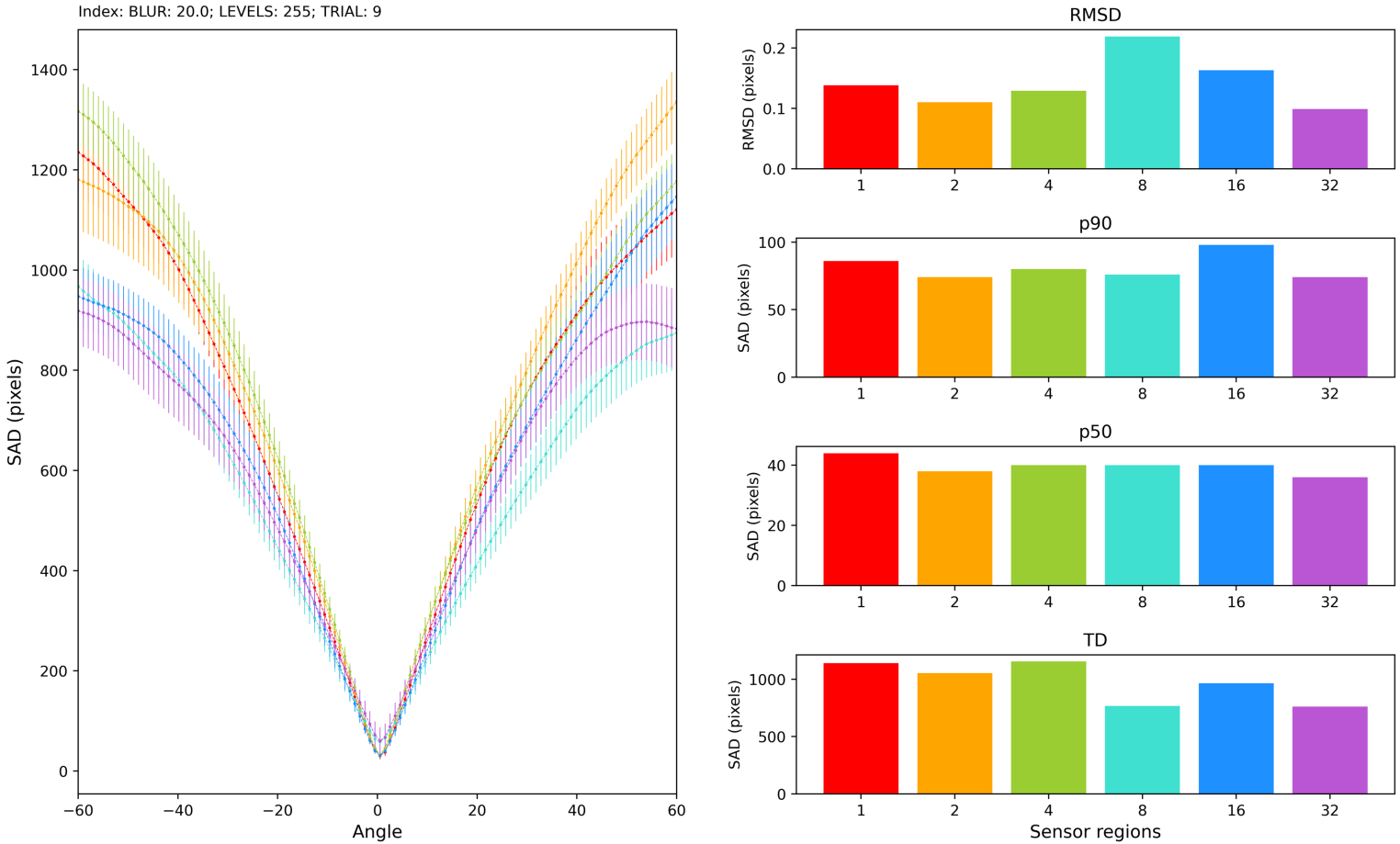




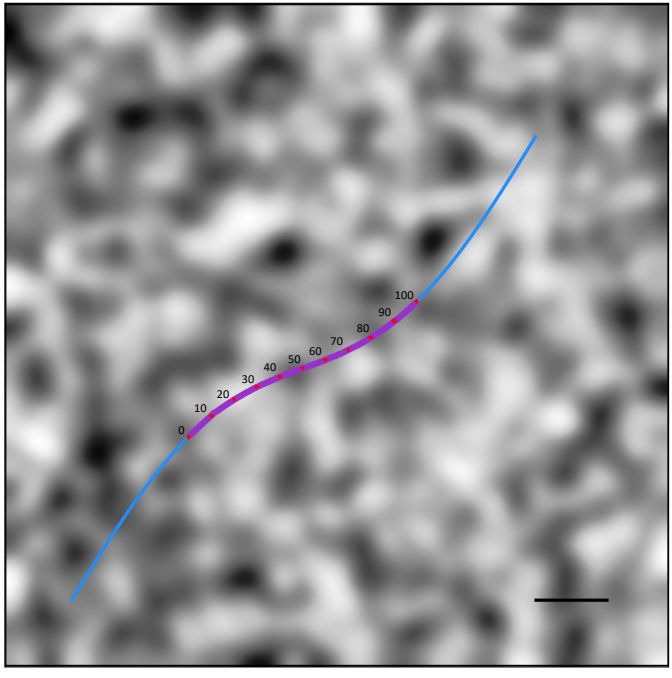


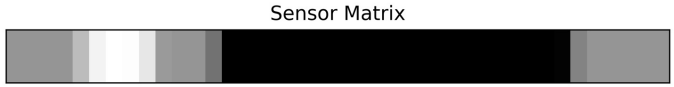
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

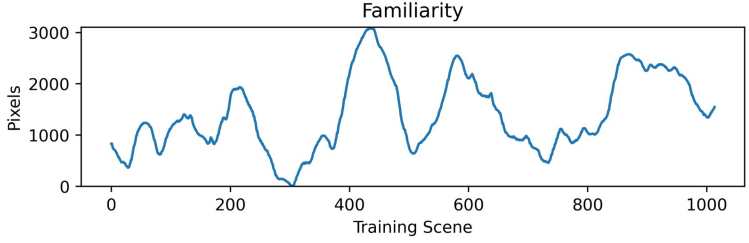
Navigation stats: RMSD error: 44.88; RMSD/dist: 0.112; TD: 1178; p90: 120; p50: 58; complete: 0

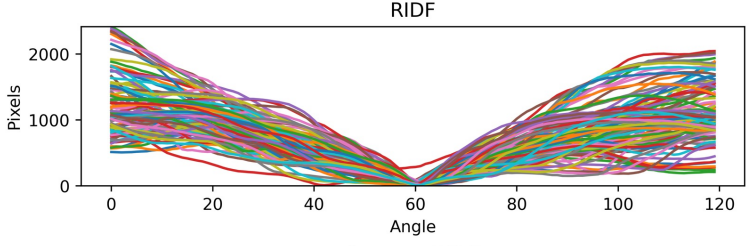

Index: BLUR: 20.0; LEVELS: 255; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

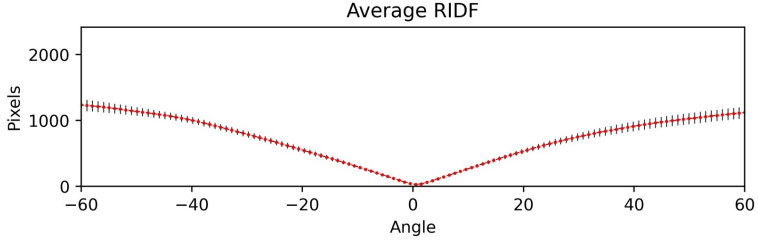
100%







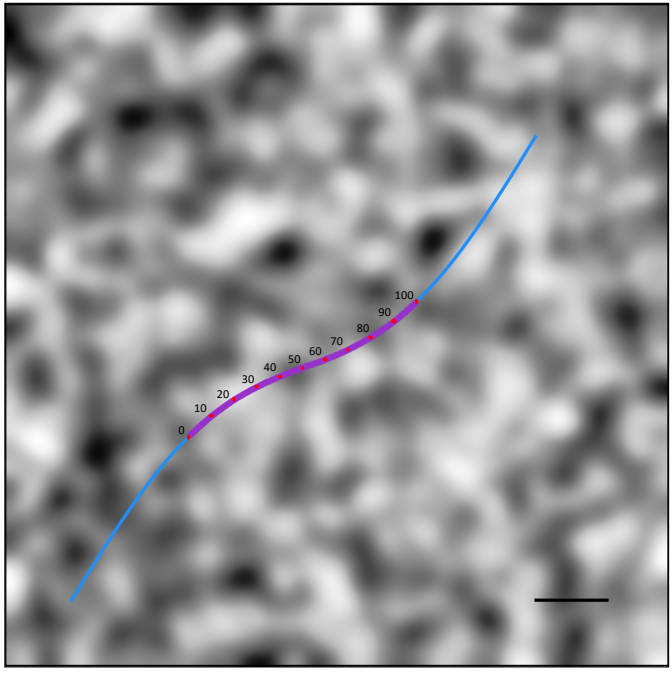


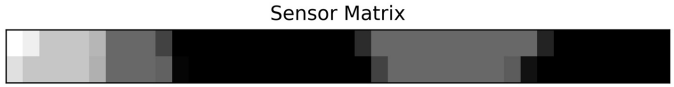


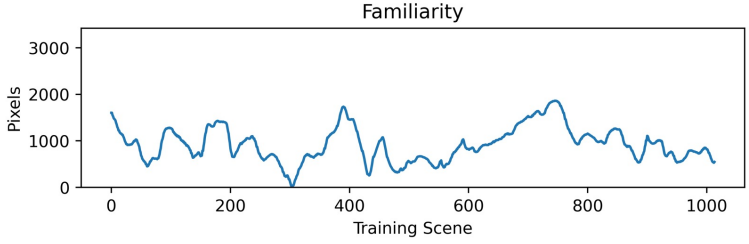
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

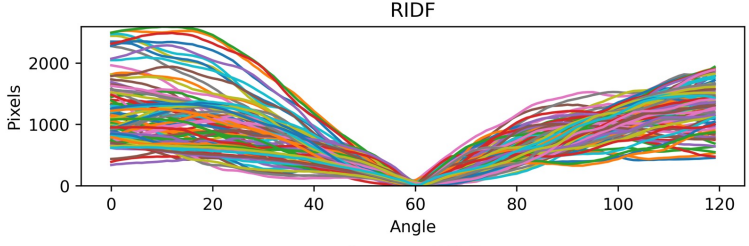
Navigation stats: RMSD error: 55.13; RMSD/dist: 0.138; TD: 1141; p90: 86; p50: 44; complete: 0

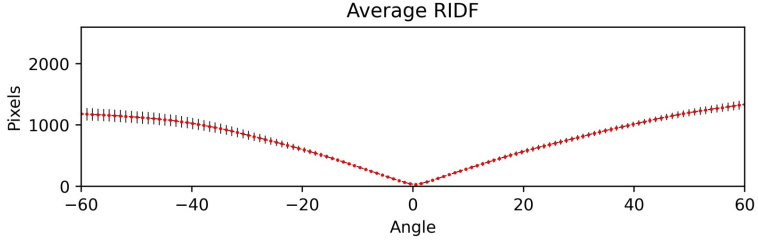
100%







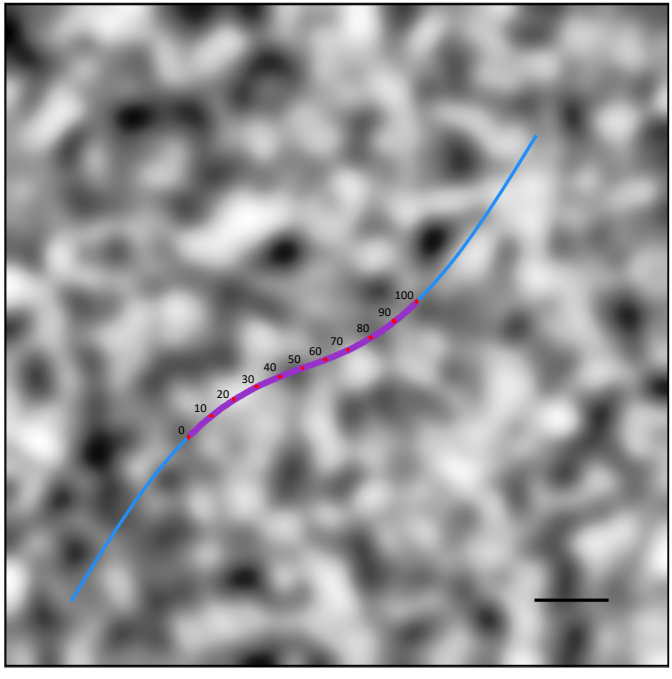


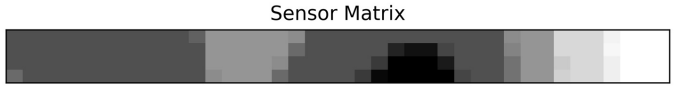


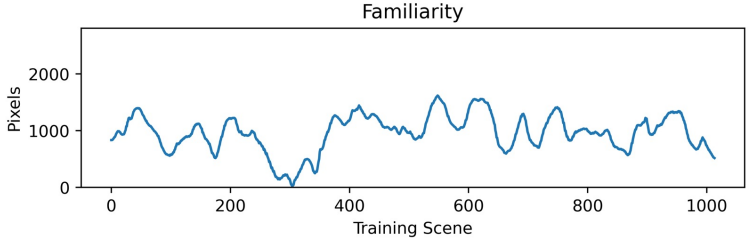
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

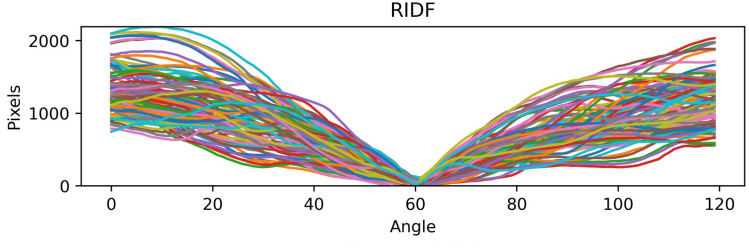
Navigation stats: RMSD error: 43.83; RMSD/dist: 0.110; TD: 1054; p90: 74; p50: 38; complete: 0

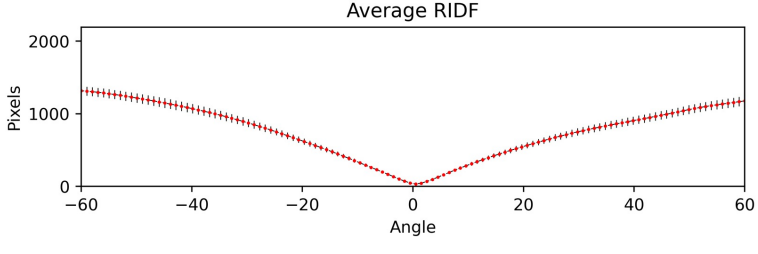
100%







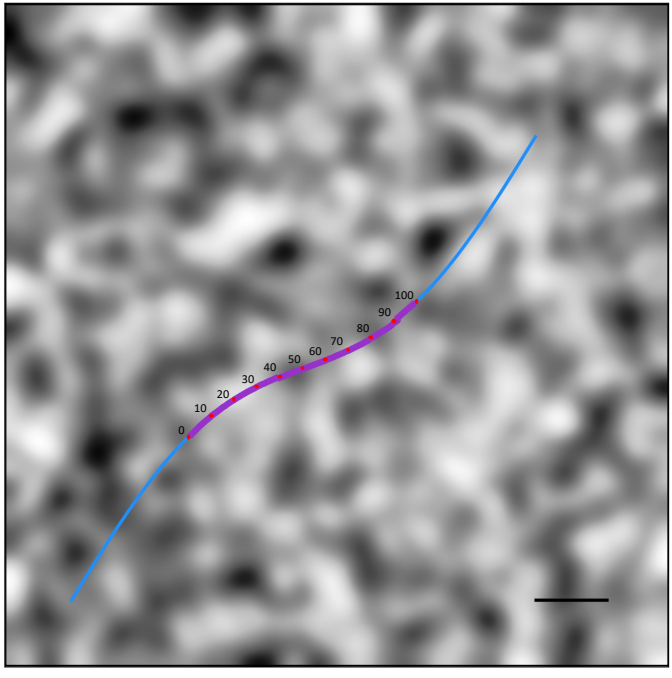


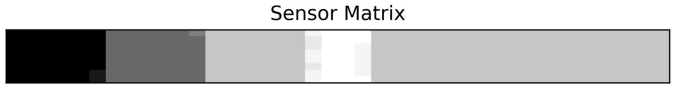


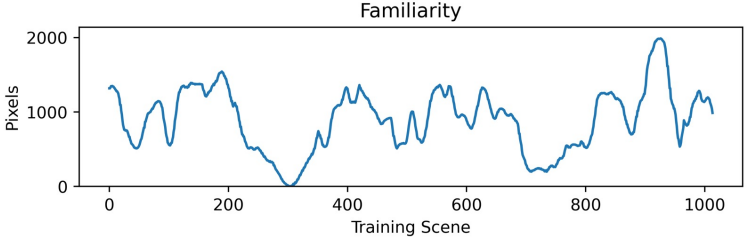
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

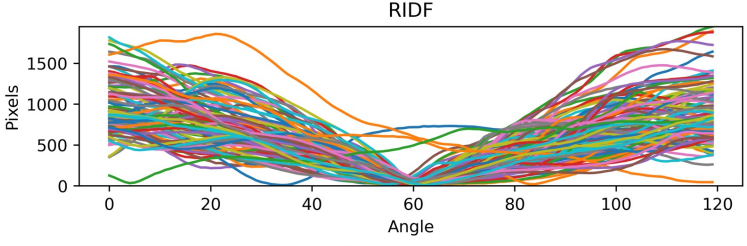
Navigation stats: RMSD error: 51.74; RMSD/dist: 0.129; TD: 1154; p90: 80; p50: 40; complete: 0

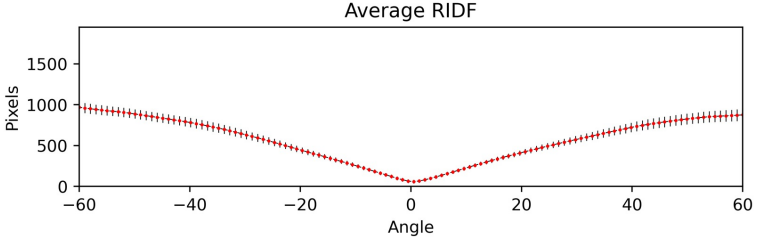
90%







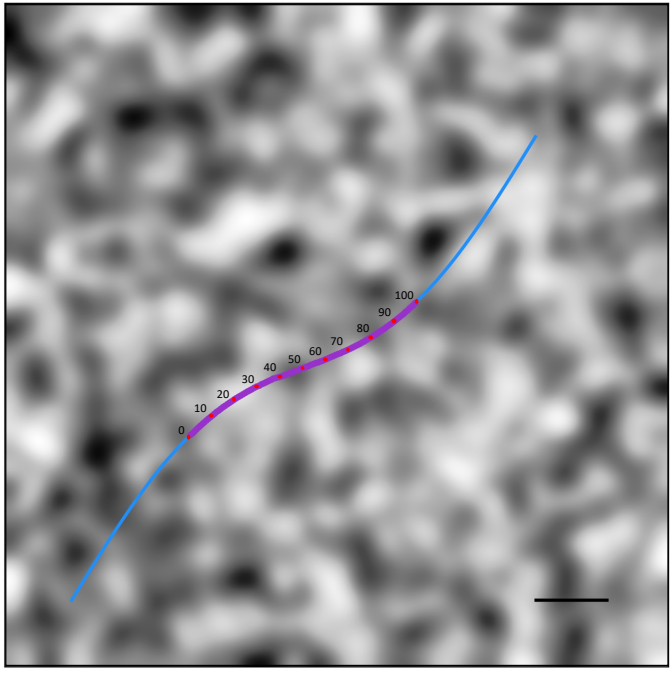


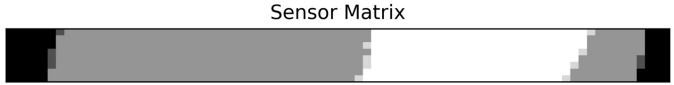


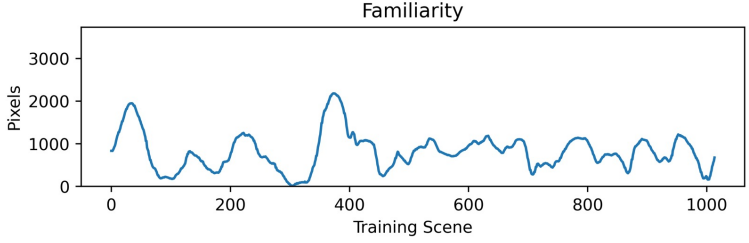
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

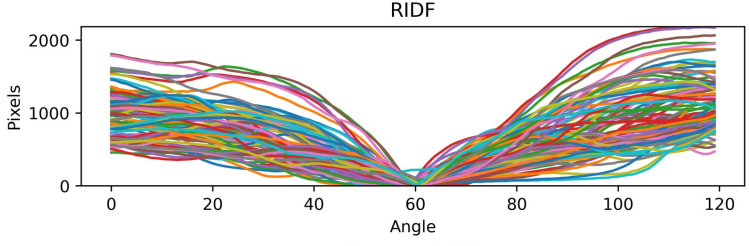
Navigation stats: RMSD error: 87.43; RMSD/dist: 0.219; TD: 766; p90: 76; p50: 40; complete: 0

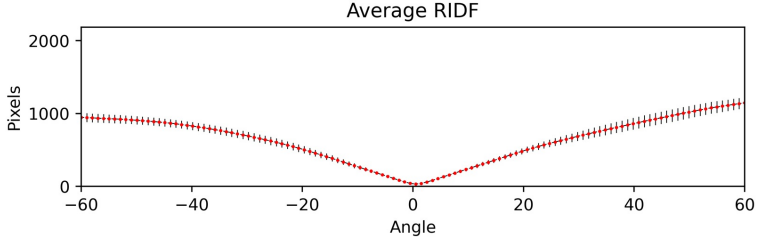
100%







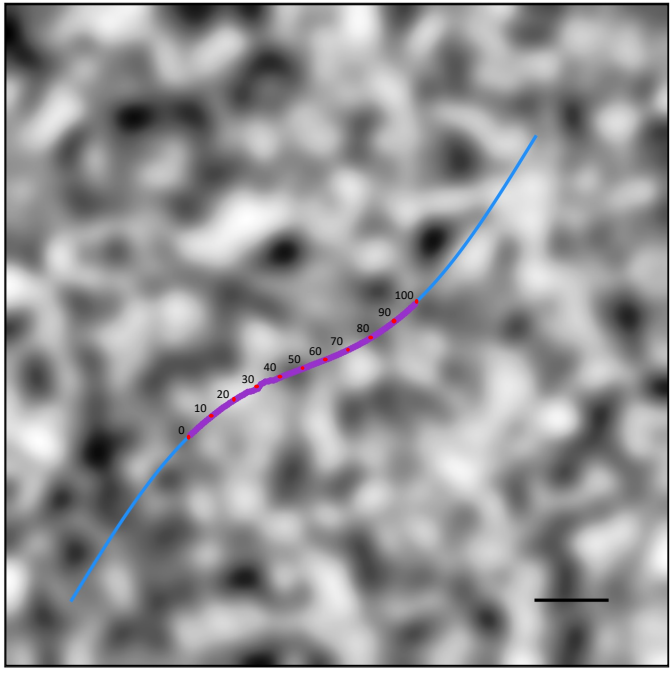


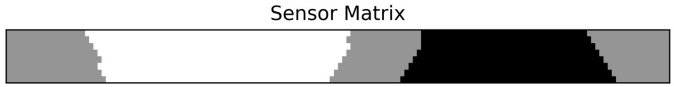


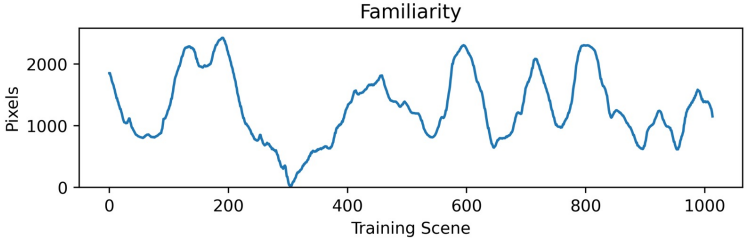
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

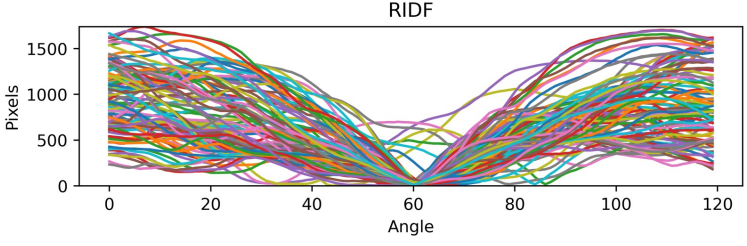
Navigation stats: RMSD error: 65.12; RMSD/dist: 0.163; TD: 964; p90: 98; p50: 40; complete: 0

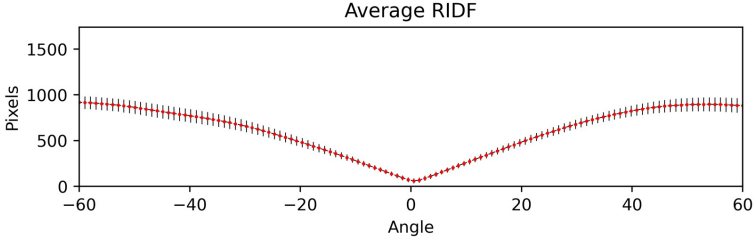
90%





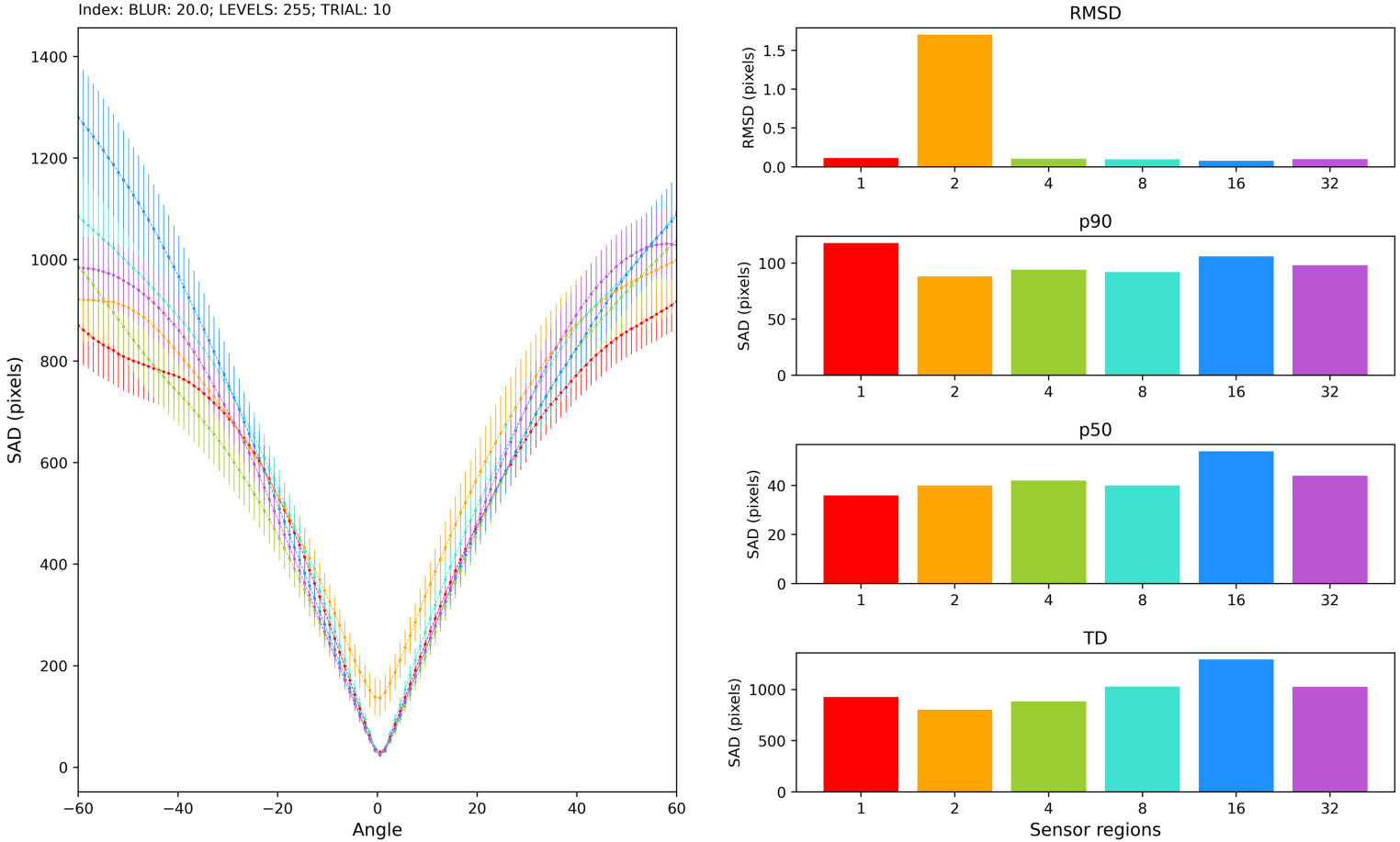




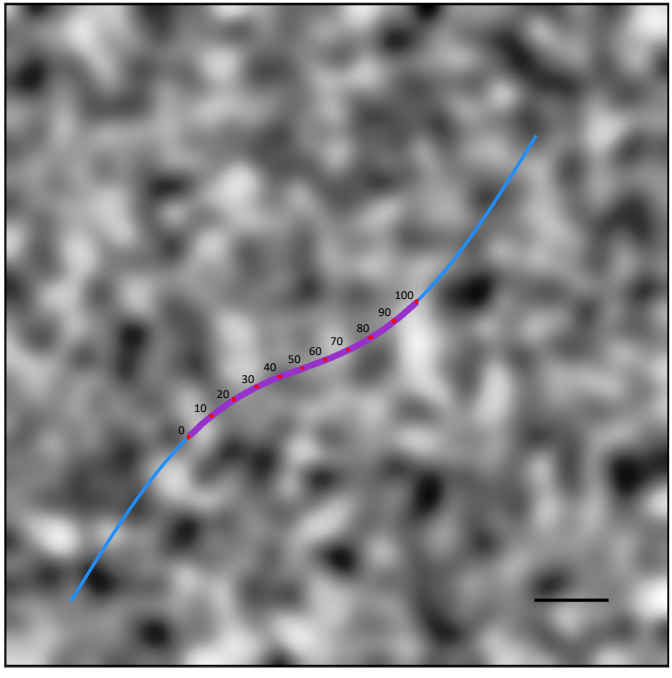


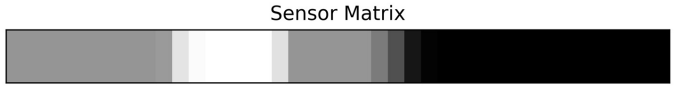
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

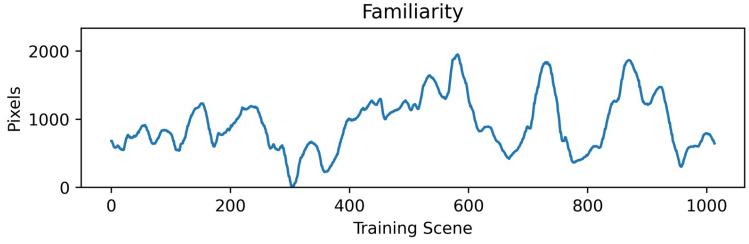
Navigation stats: RMSD error: 39.77; RMSD/dist: 0.099; TD: 761; p90: 74; p50: 36; complete: 0

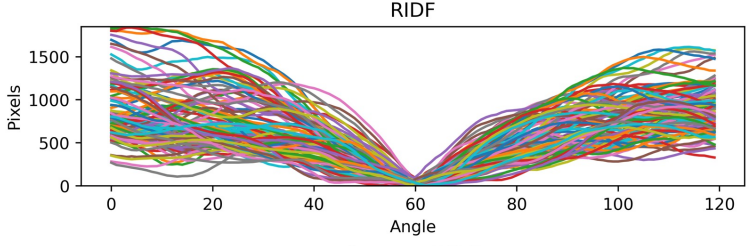

Index: BLUR: 20.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

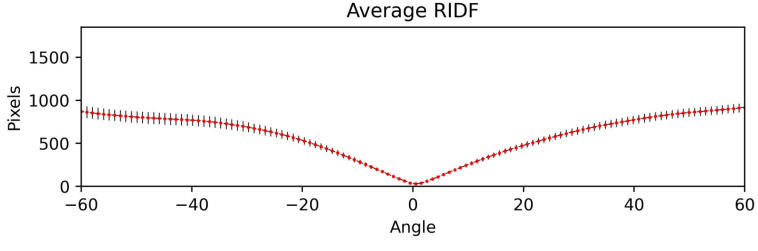
100%







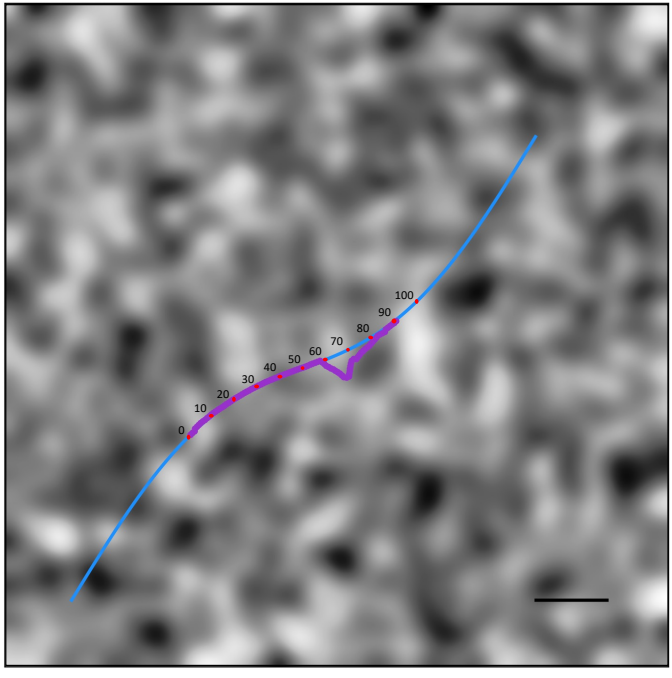


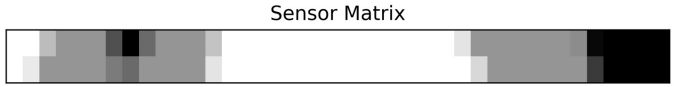


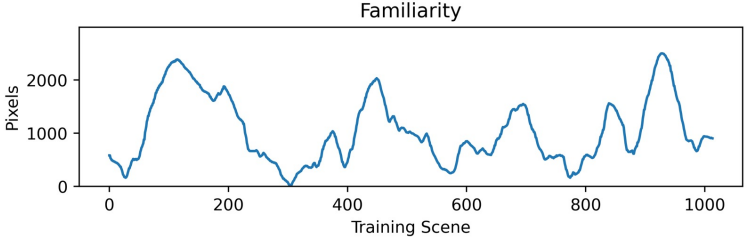
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

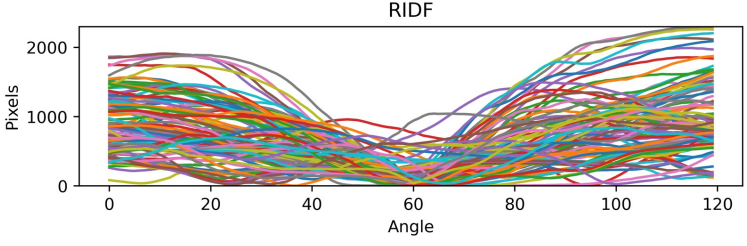
Navigation stats: RMSD error: 45.21; RMSD/dist: 0.113; TD: 927; p90: 118; p50: 36; complete: 0

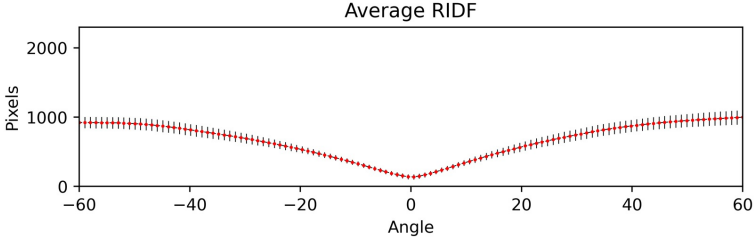
60%







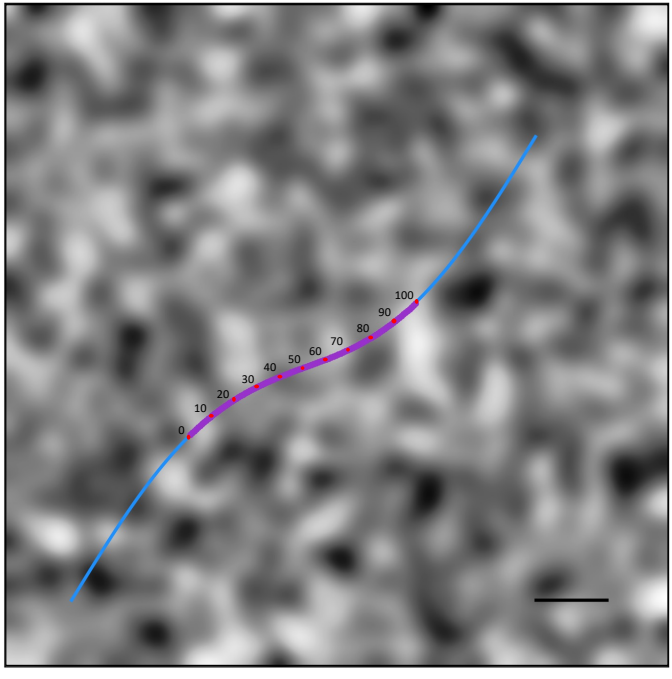


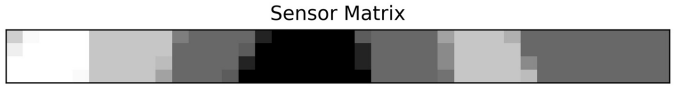


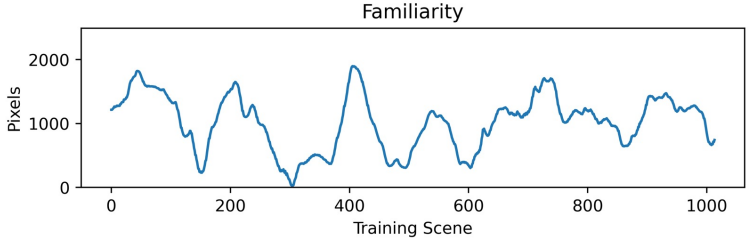
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

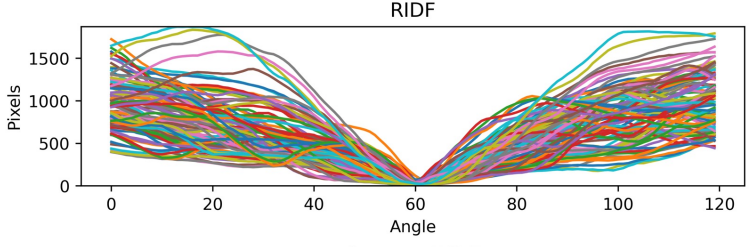
Navigation stats: RMSD error: 681.15; RMSD/dist: 1.703; TD: 803; p90: 88; p50: 40; complete: 0

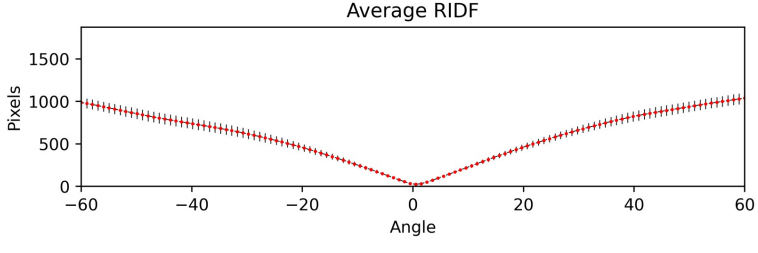
100%







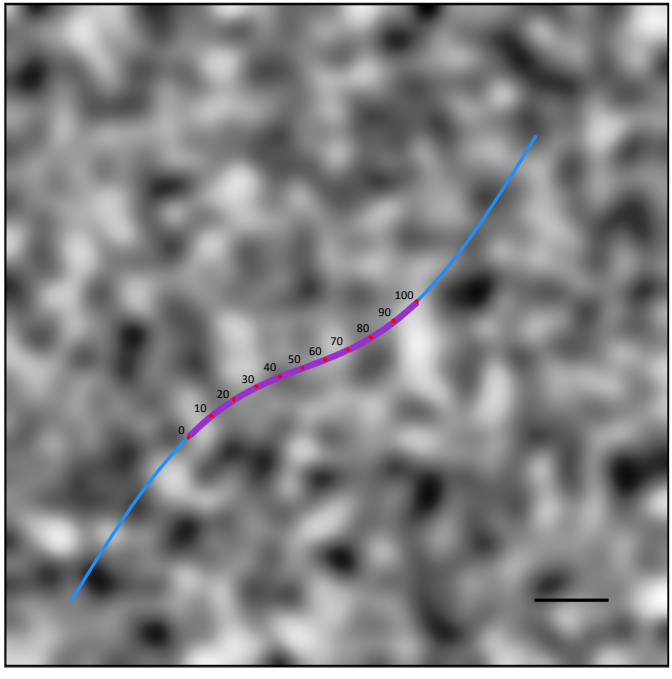


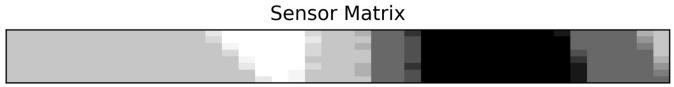


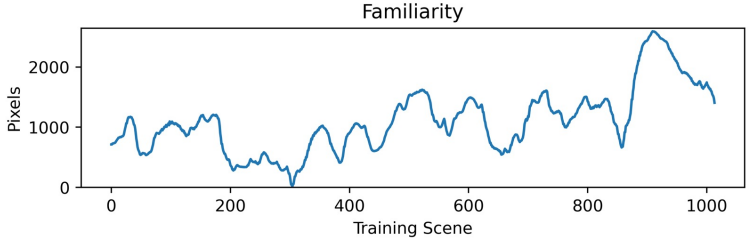
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

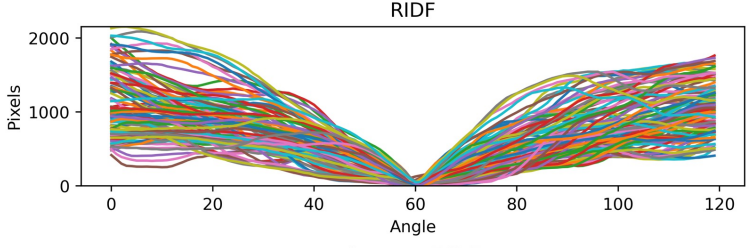
Navigation stats: RMSD error: 42.12; RMSD/dist: 0.105; TD: 883; p90: 94; p50: 42; complete: 0

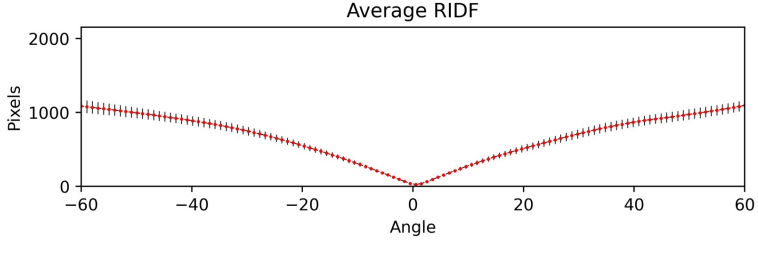
100%







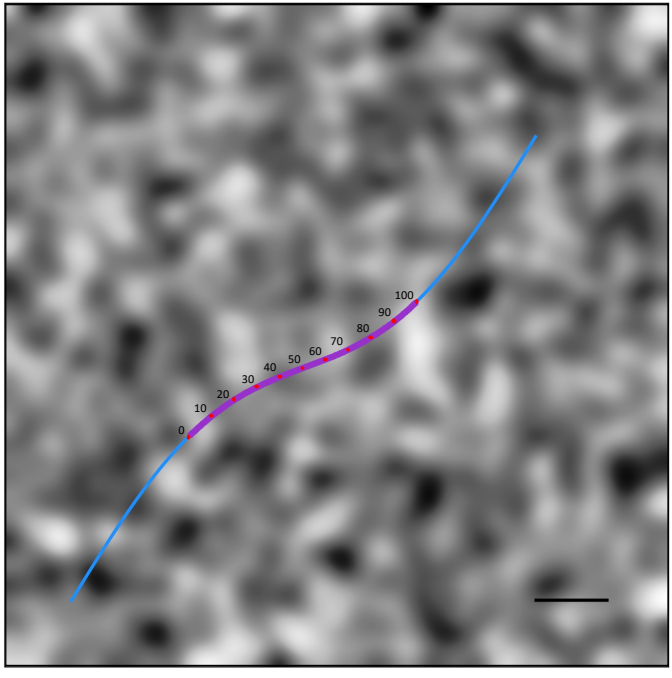


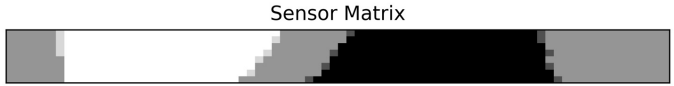


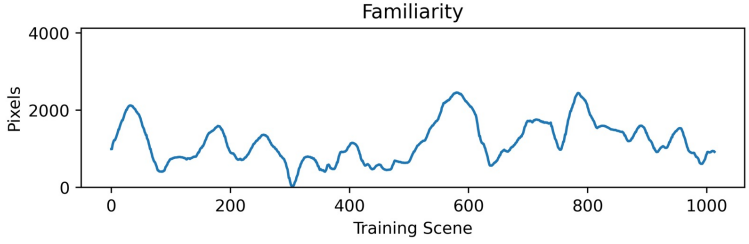
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

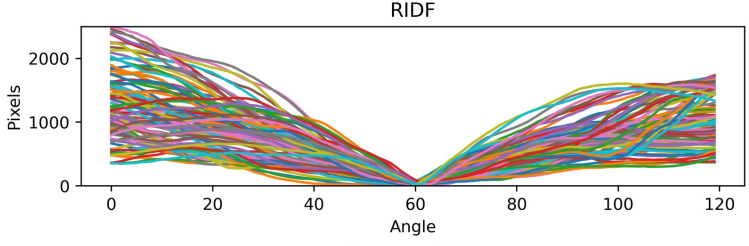
Navigation stats: RMSD error: 38.81; RMSD/dist: 0.097; TD: 1028; p90: 92; p50: 40; complete: 0

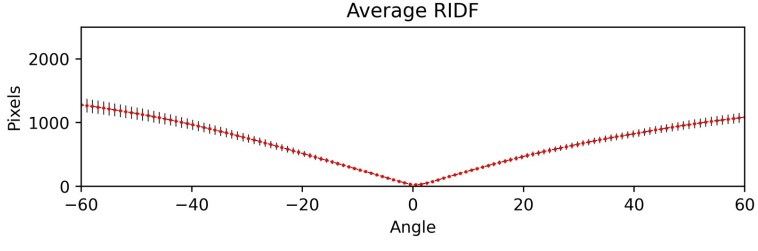
100%







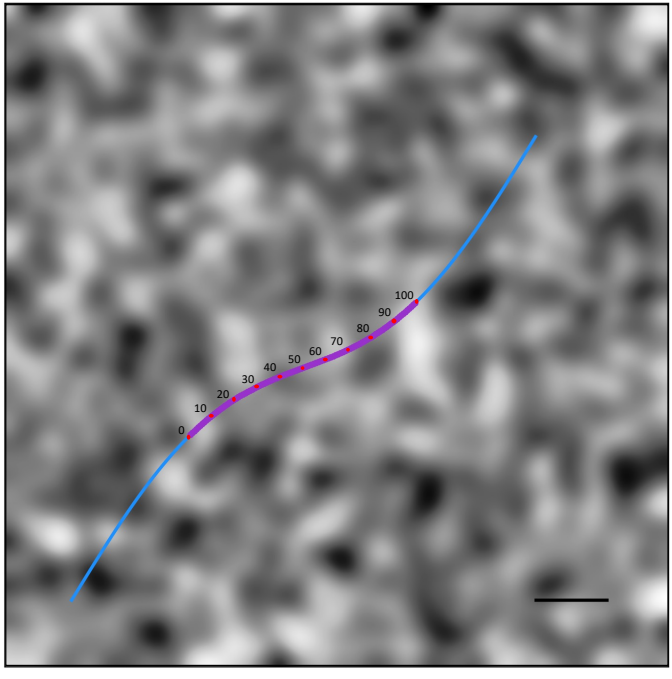


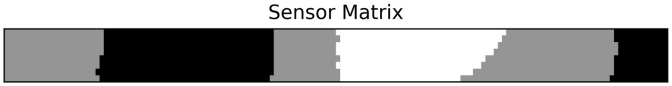


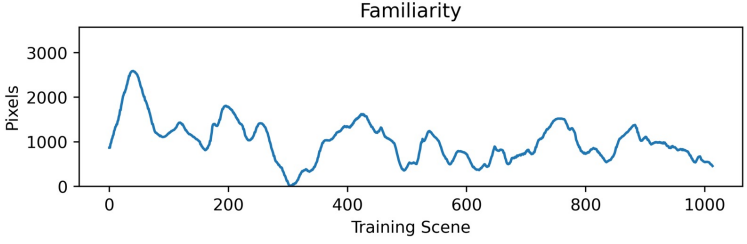
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

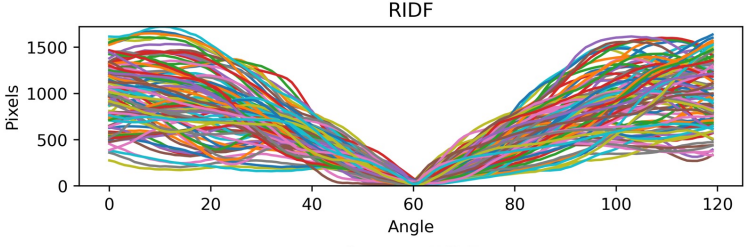
Navigation stats: RMSD error: 30.91; RMSD/dist: 0.077; TD: 1292; p90: 106; p50: 54; complete: 0

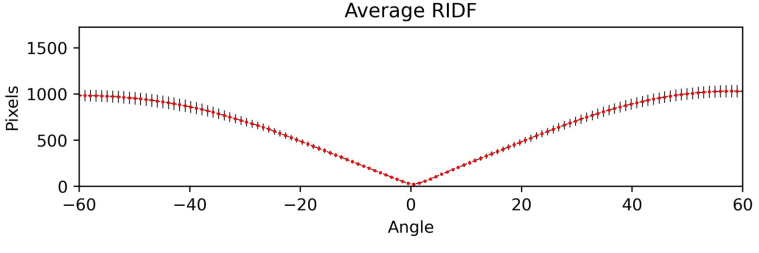
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 39.42; RMSD/dist: 0.099; TD: 1027; p90: 98; p50: 44; complete: 0