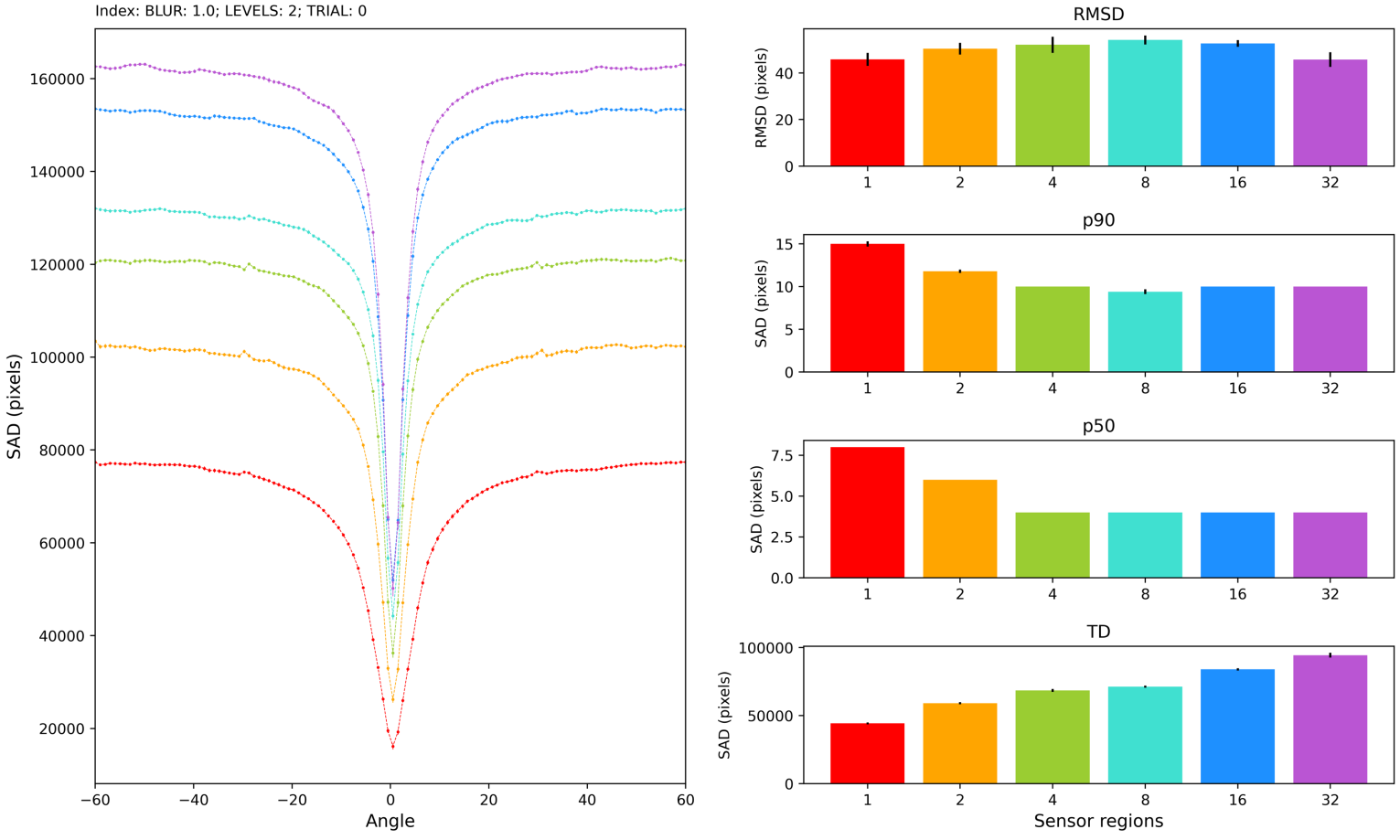
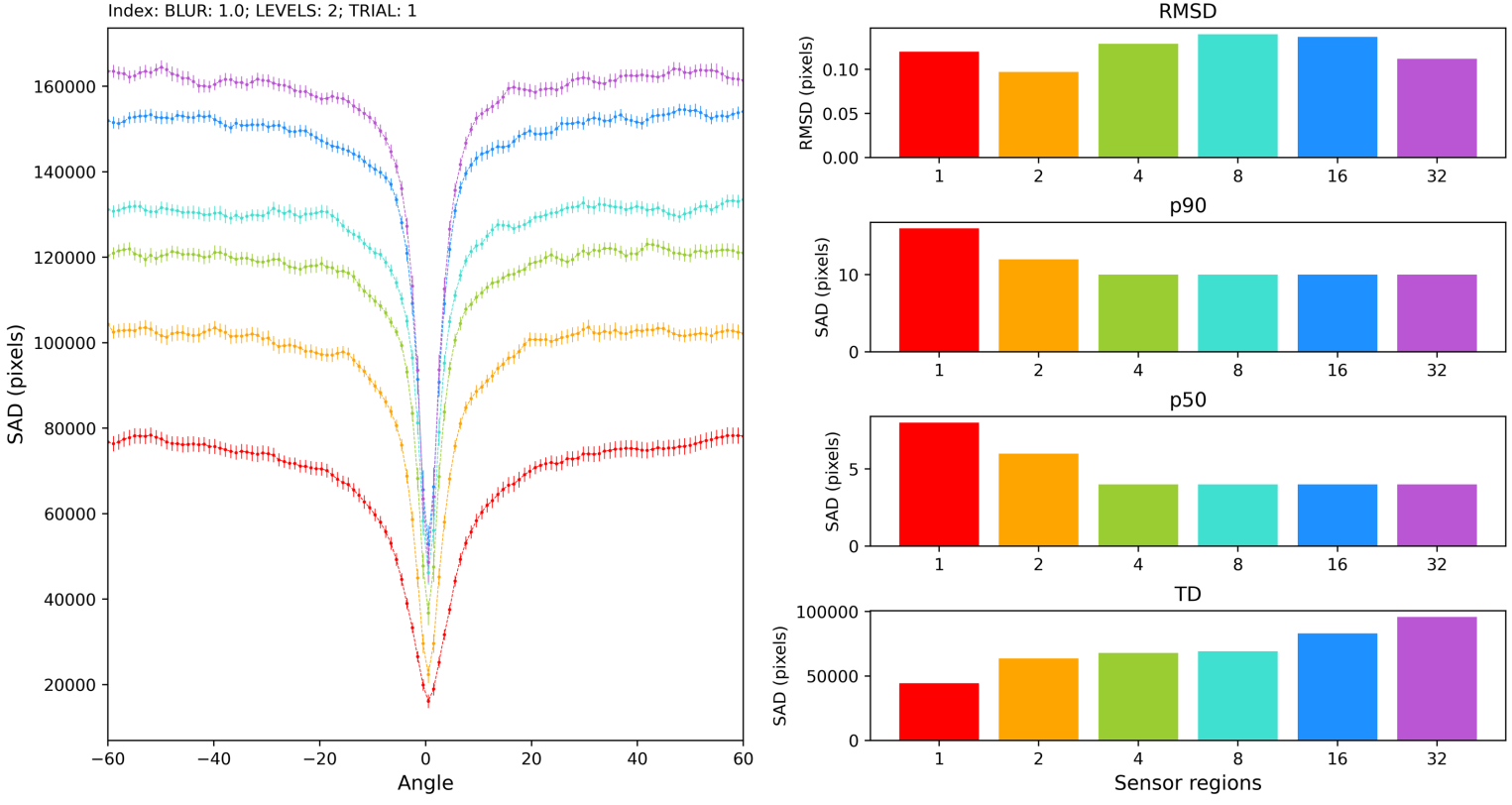
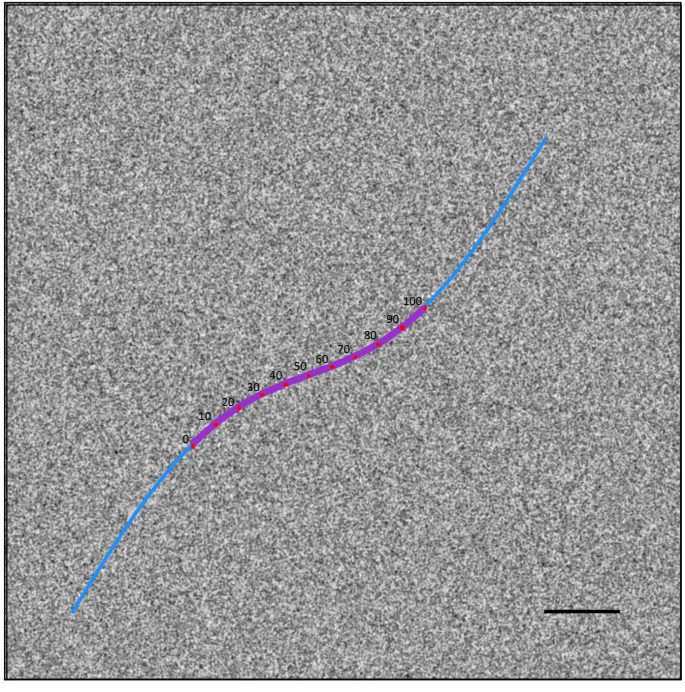
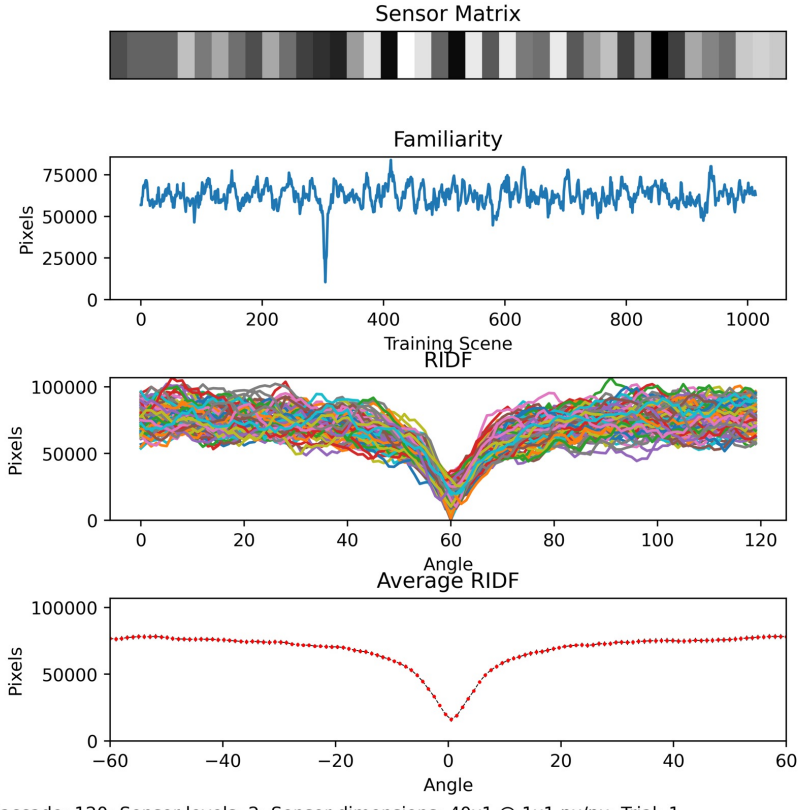

Index: BLUR: 1.0; LEVELS: 2; TRIAL: 0
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
40
20
0
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
100000
50000
0
Sensor regions


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 1
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

100%

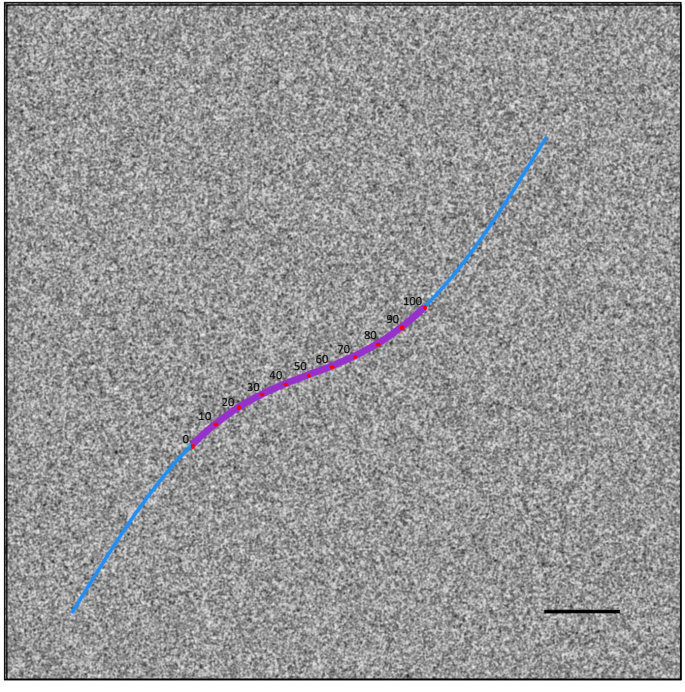


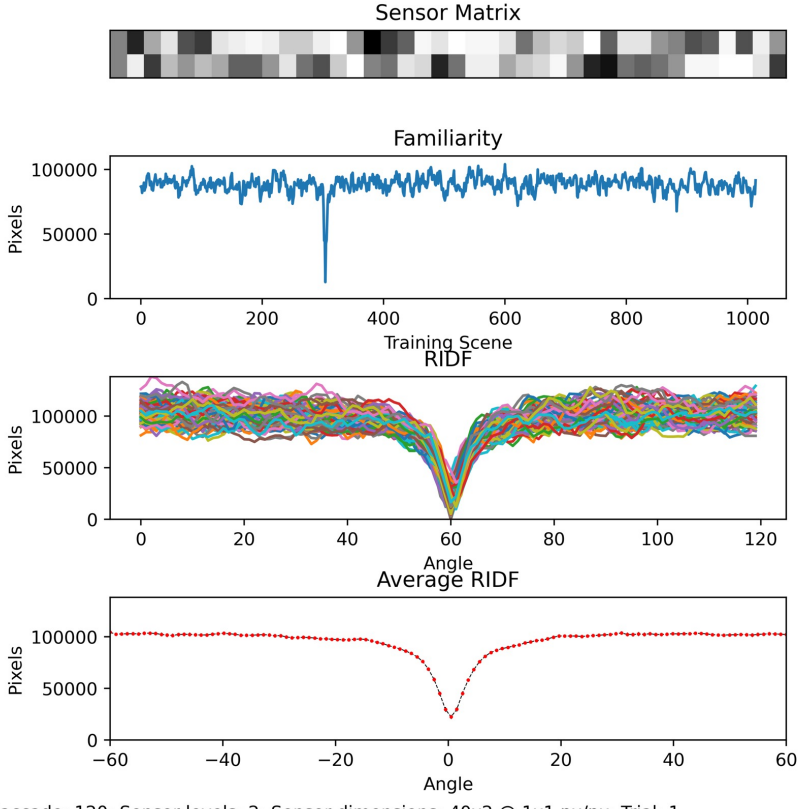


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 48.15; RMSD/dist: 0.120; TD: 44405; p90: 16; p50: 8; complete: 0

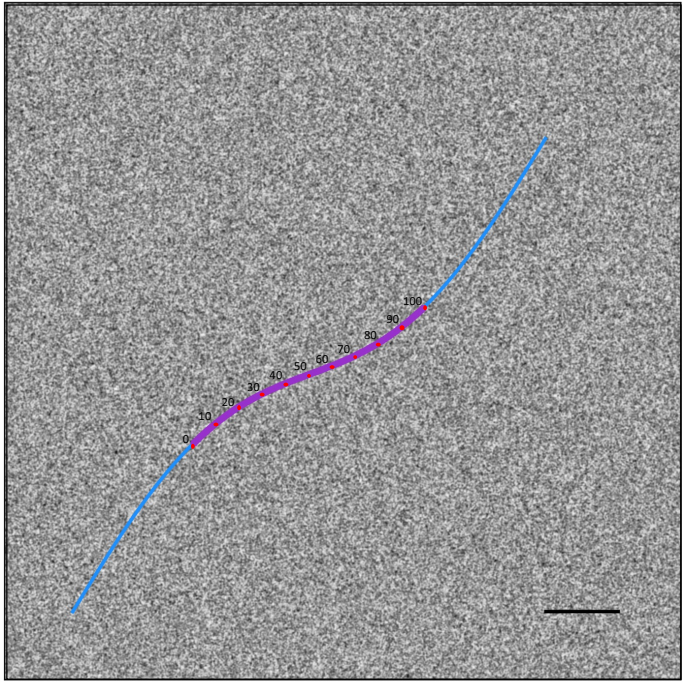
100%

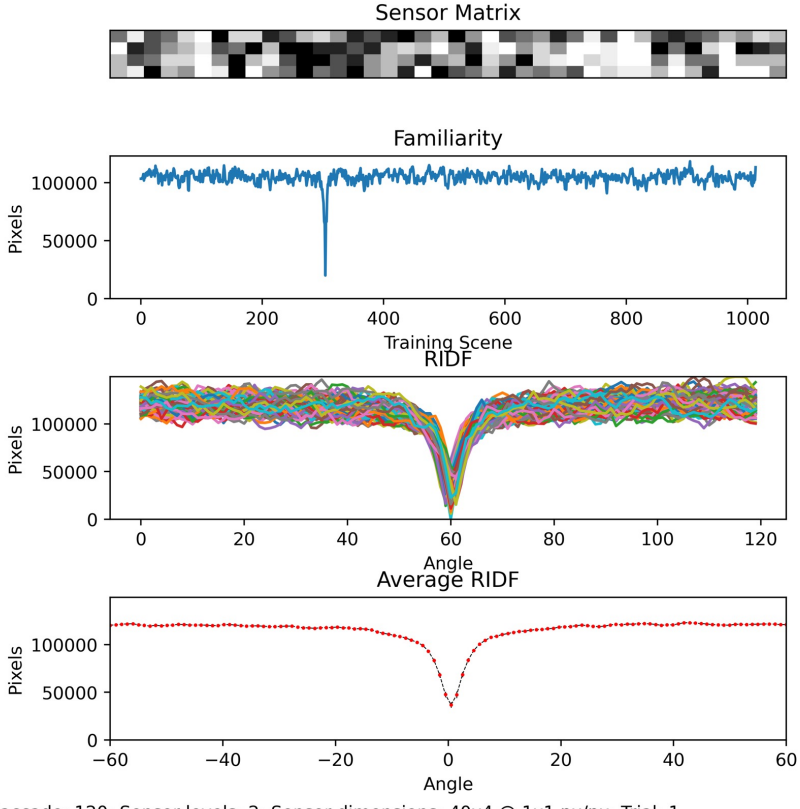




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 38.71; RMSD/dist: 0.097; TD: 63668; p90: 12; p50: 6; complete: 0

100%

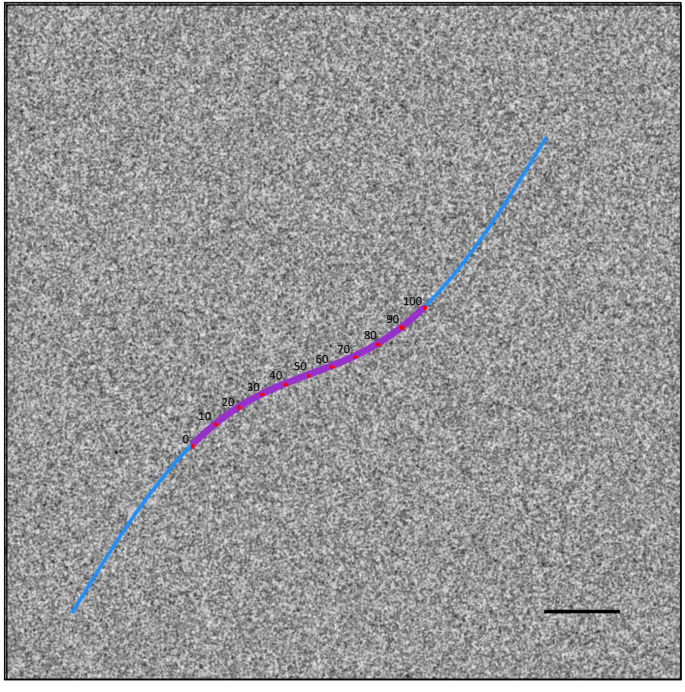


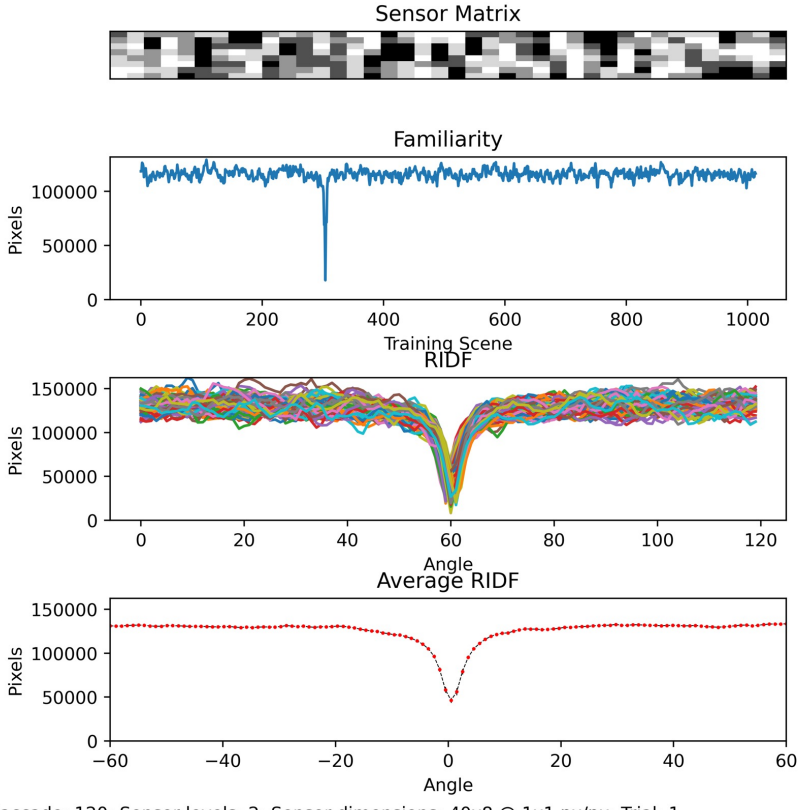


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 51.63; RMSD/dist: 0.129; TD: 67843; p90: 10; p50: 4; complete: 0

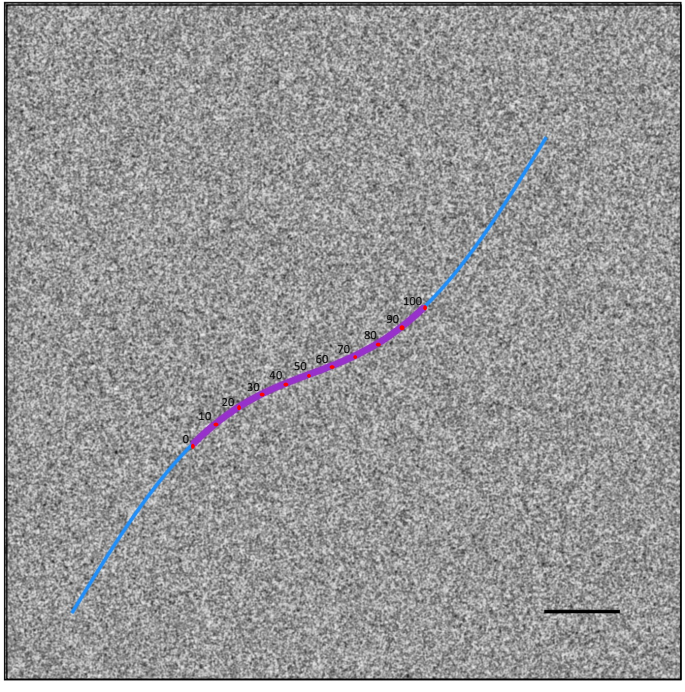
100%

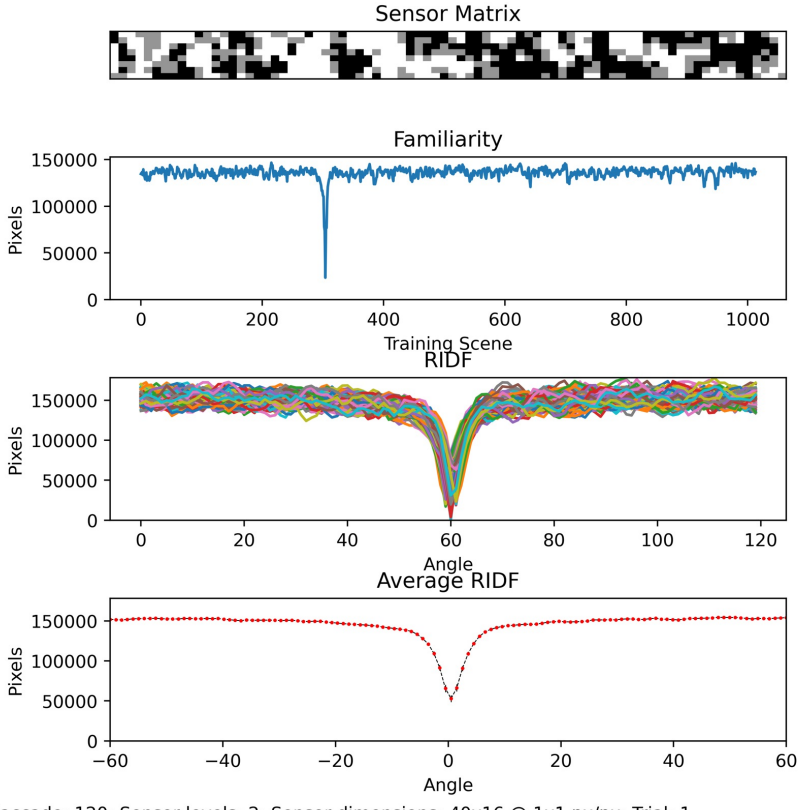




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 56.14; RMSD/dist: 0.140; TD: 69086; p90: 10; p50: 4; complete: 0

100%

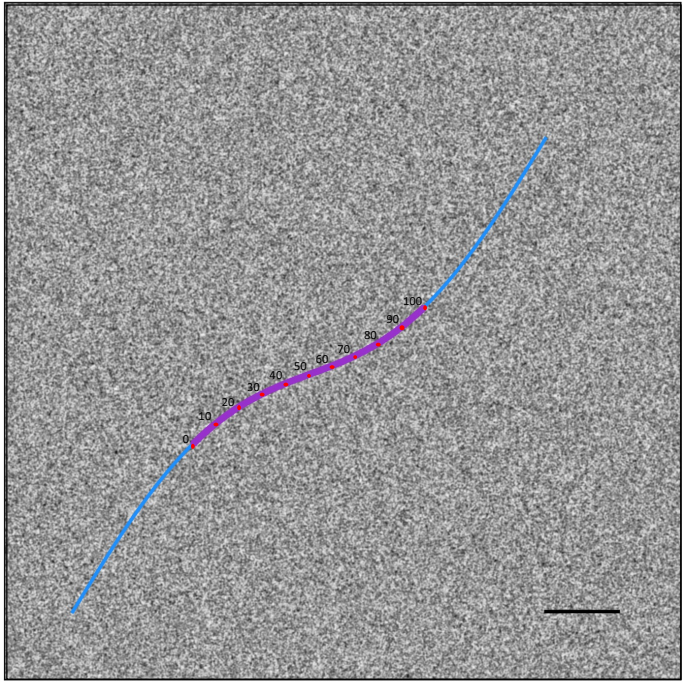


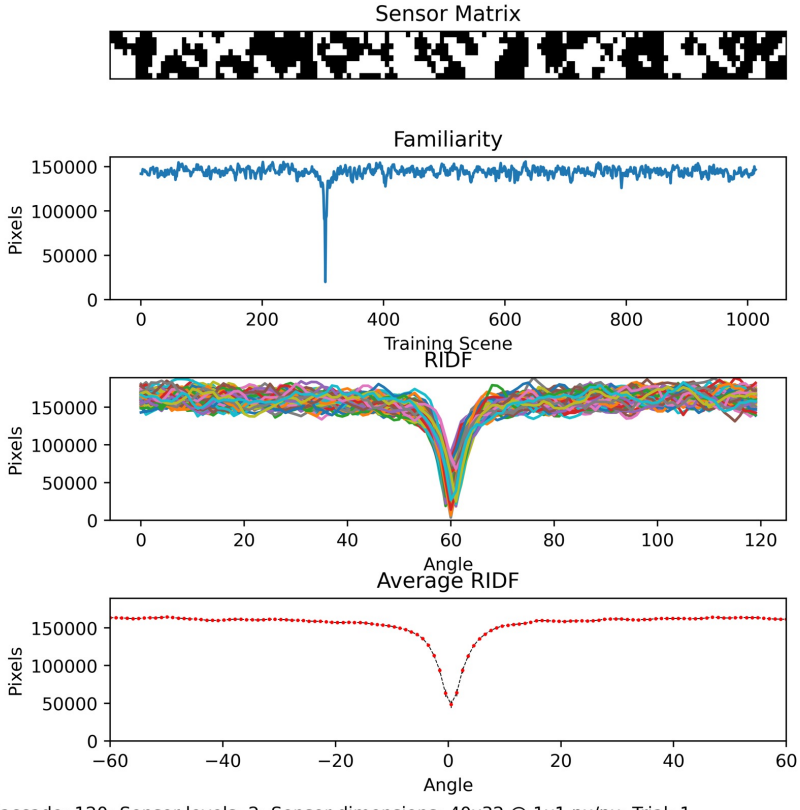


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 54.94; RMSD/dist: 0.137; TD: 83012; p90: 10; p50: 4; complete: 0

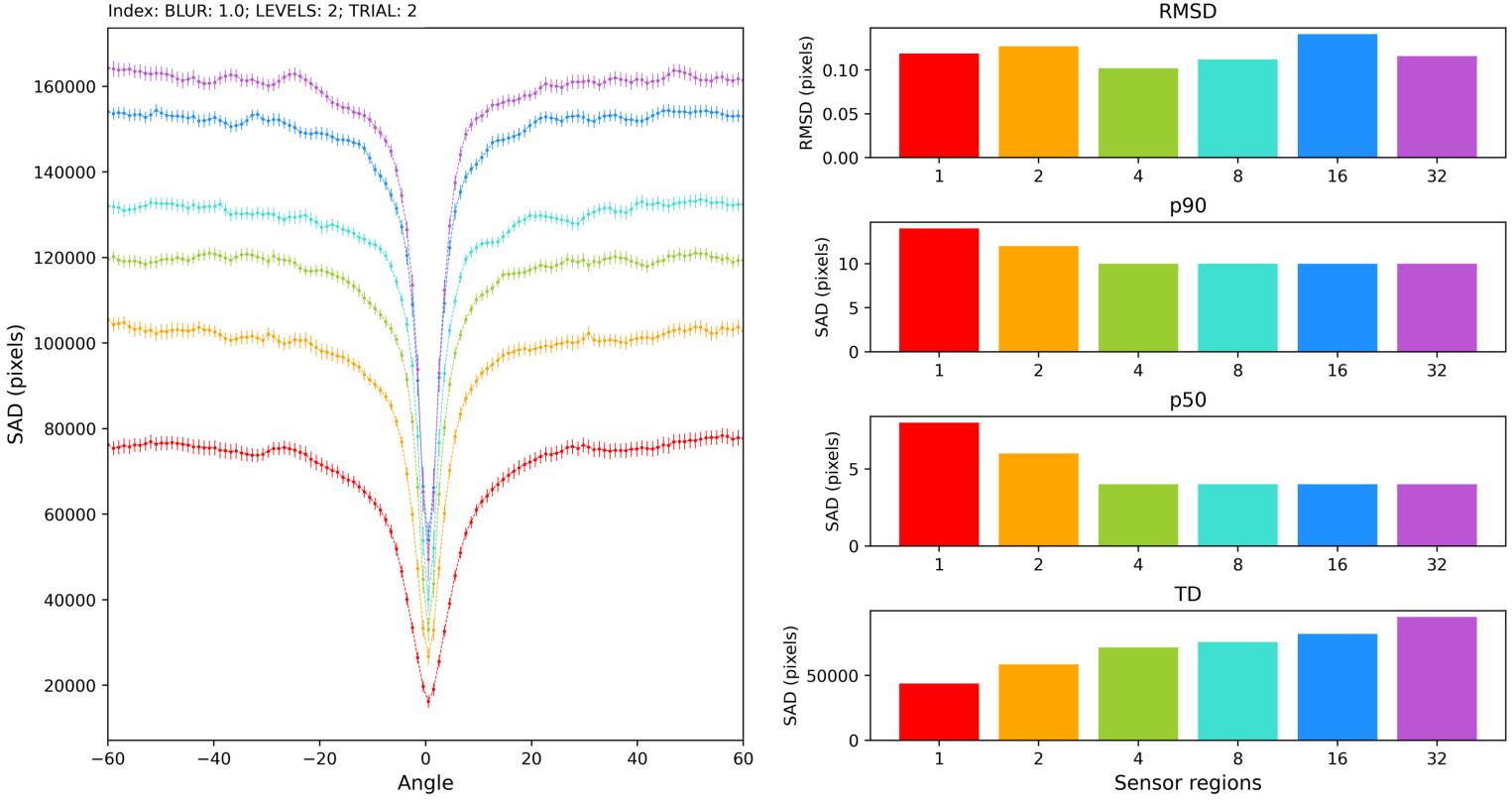
100%



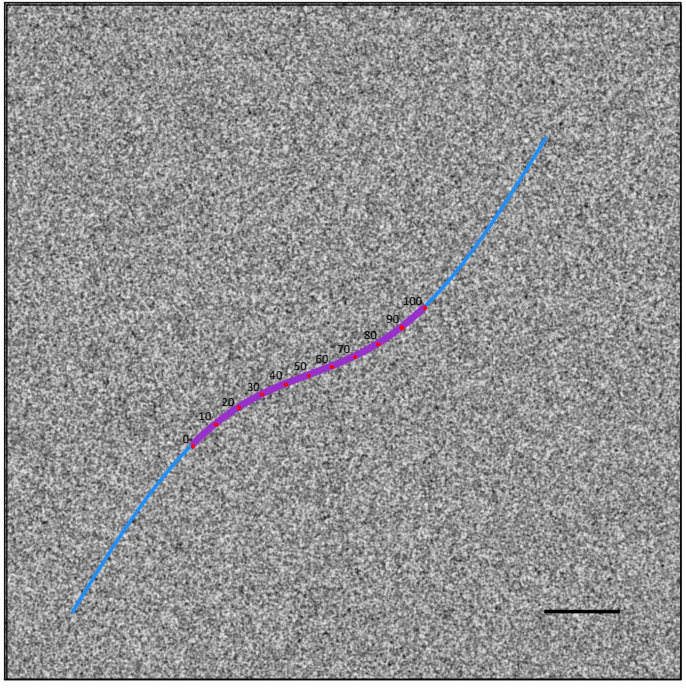


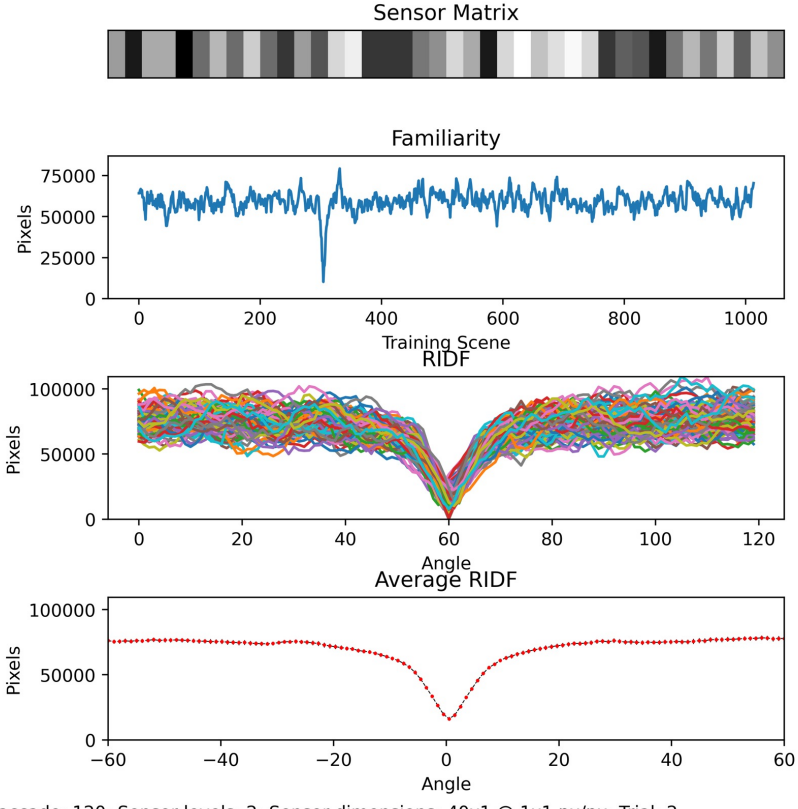
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 44.65; RMSD/dist: 0.112; TD: 95788; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 2
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
50000
0
Sensor regions

100%

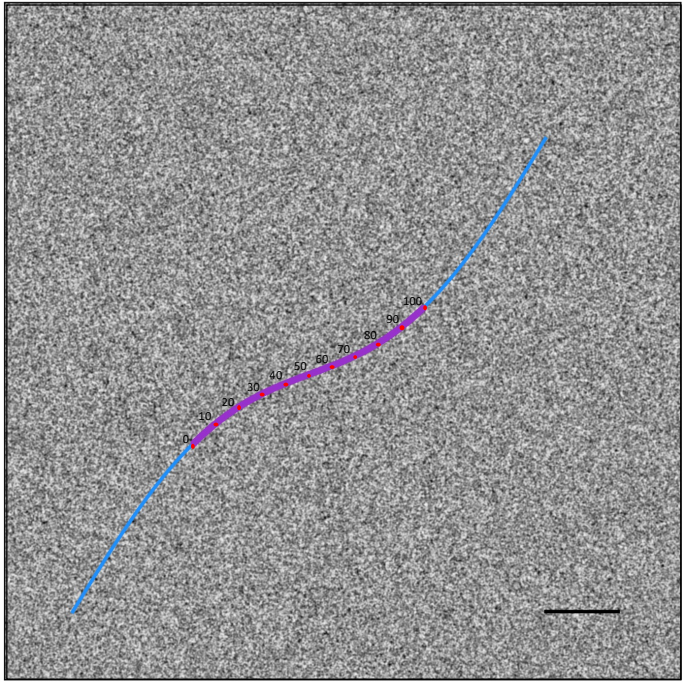


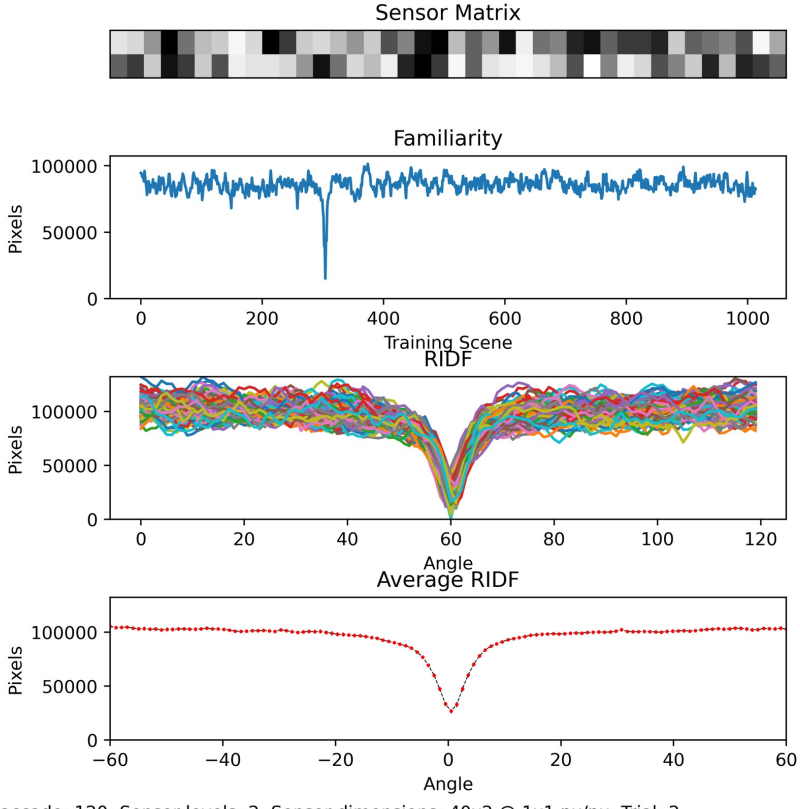


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 47.42; RMSD/dist: 0.119; TD: 43758; p90: 14; p50: 8; complete: 0

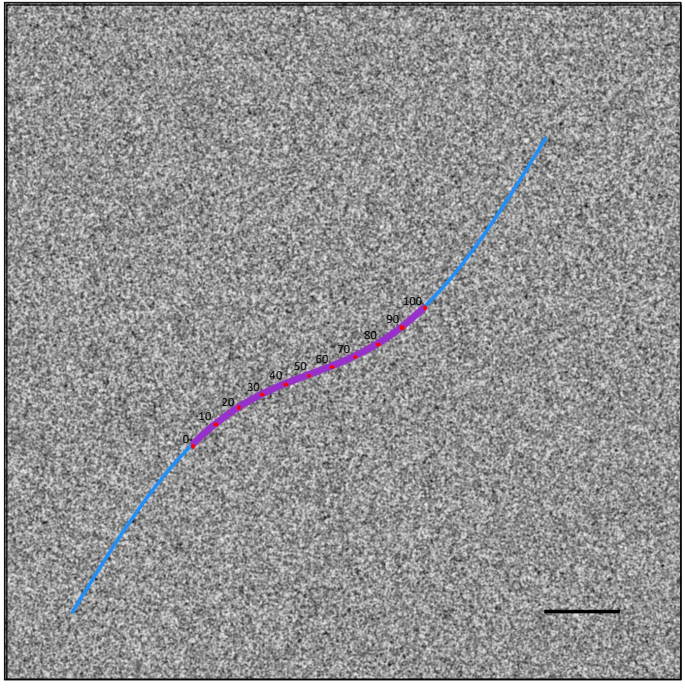
100%

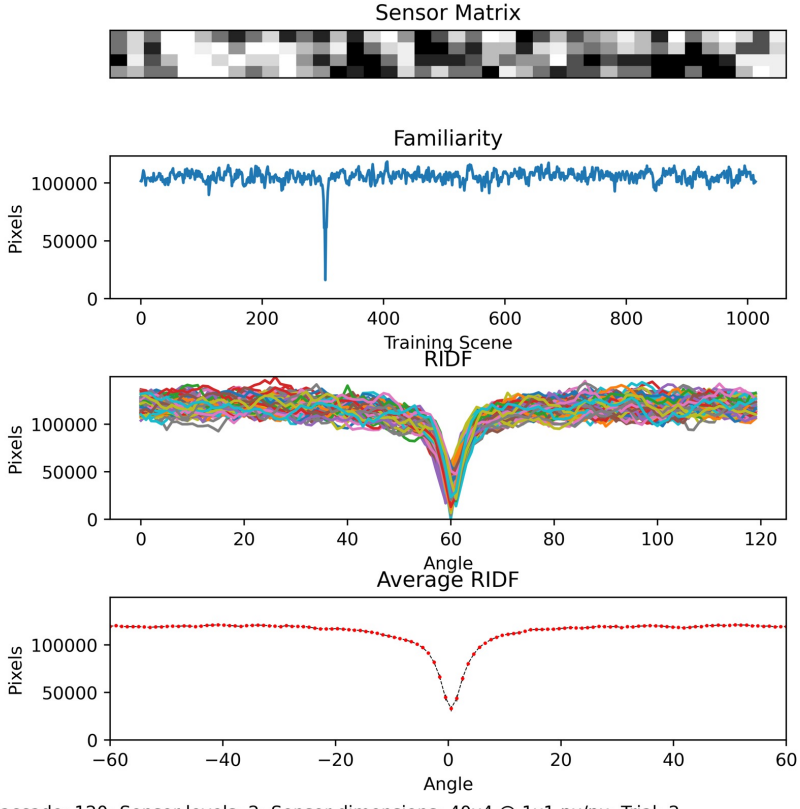




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 50.96; RMSD/dist: 0.127; TD: 58512; p90: 12; p50: 6; complete: 0

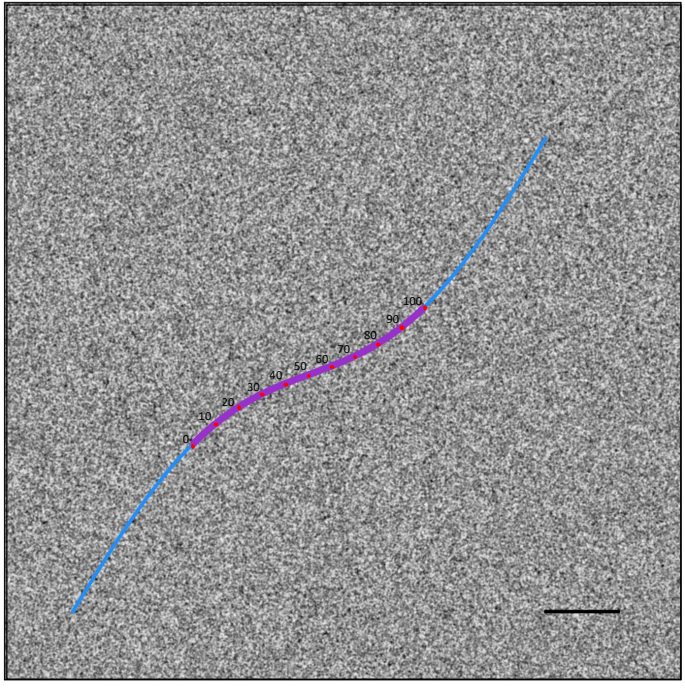
100%

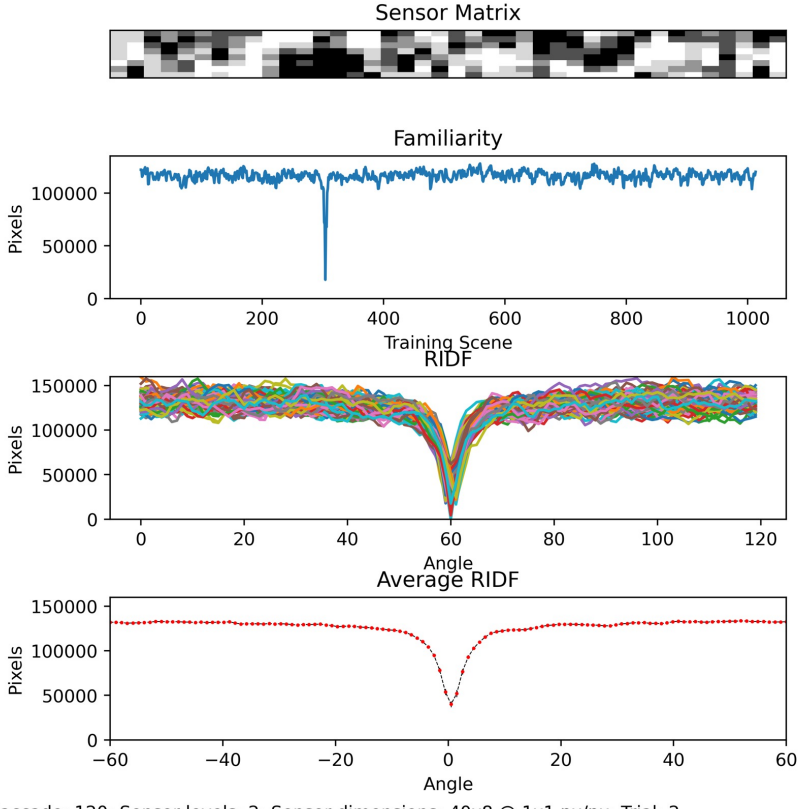




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 40.82; RMSD/dist: 0.102; TD: 71538; p90: 10; p50: 4; complete: 0

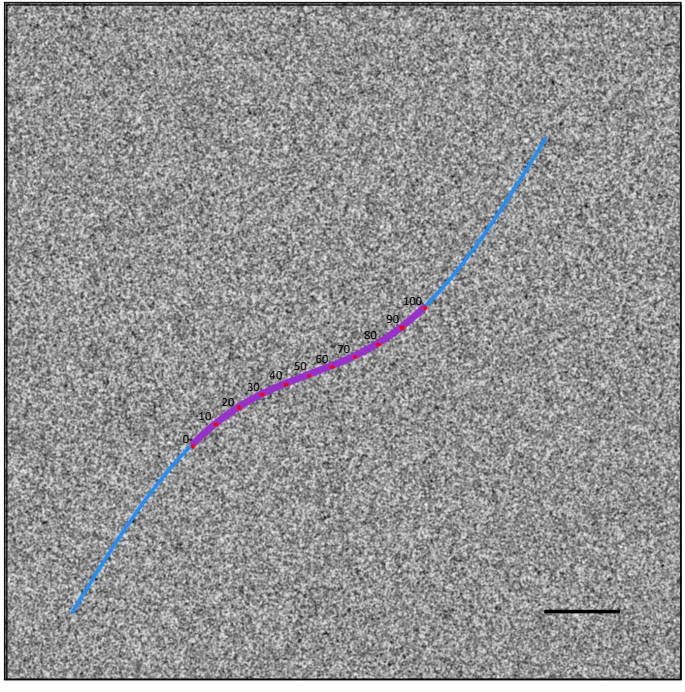
100%

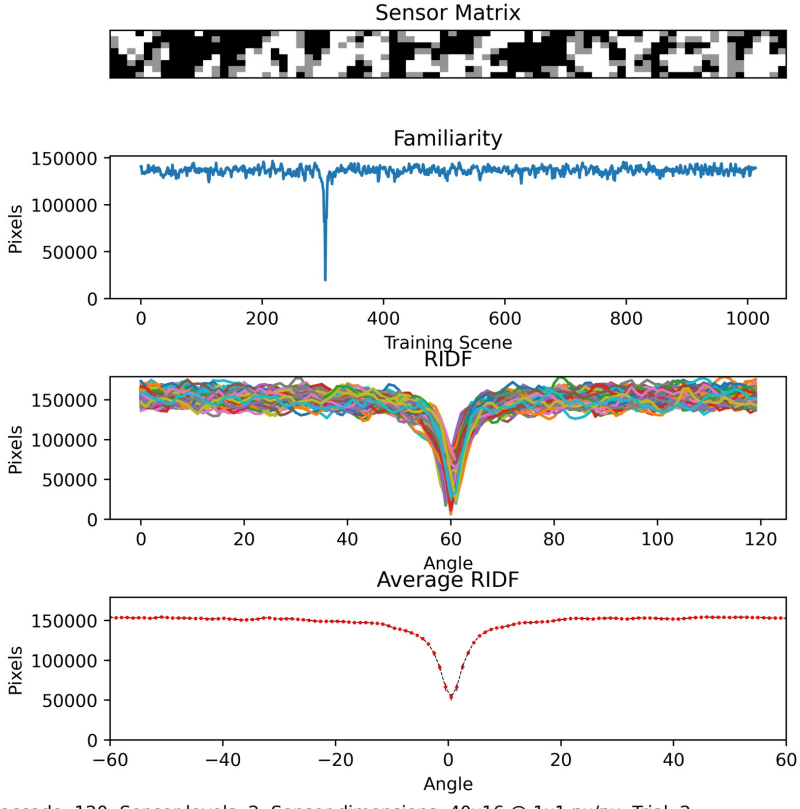




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 44.95; RMSD/dist: 0.112; TD: 75709; p90: 10; p50: 4; complete: 0

100%

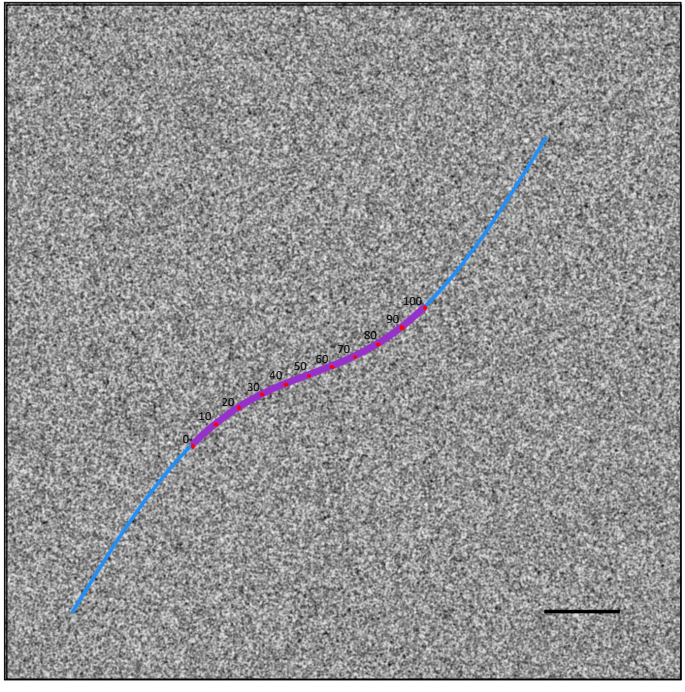


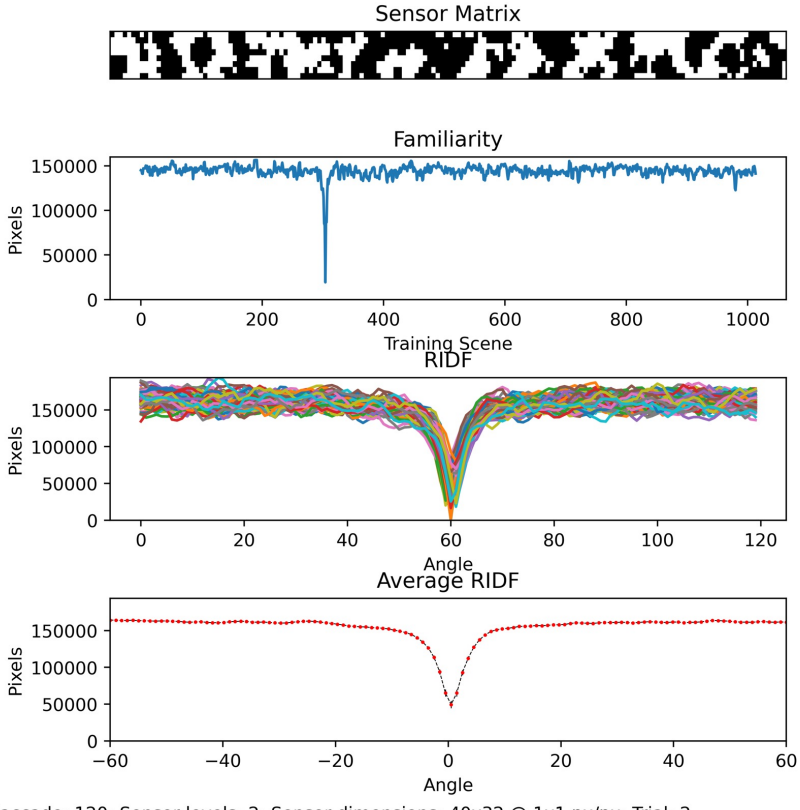


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 56.26; RMSD/dist: 0.141; TD: 81971; p90: 10; p50: 4; complete: 0

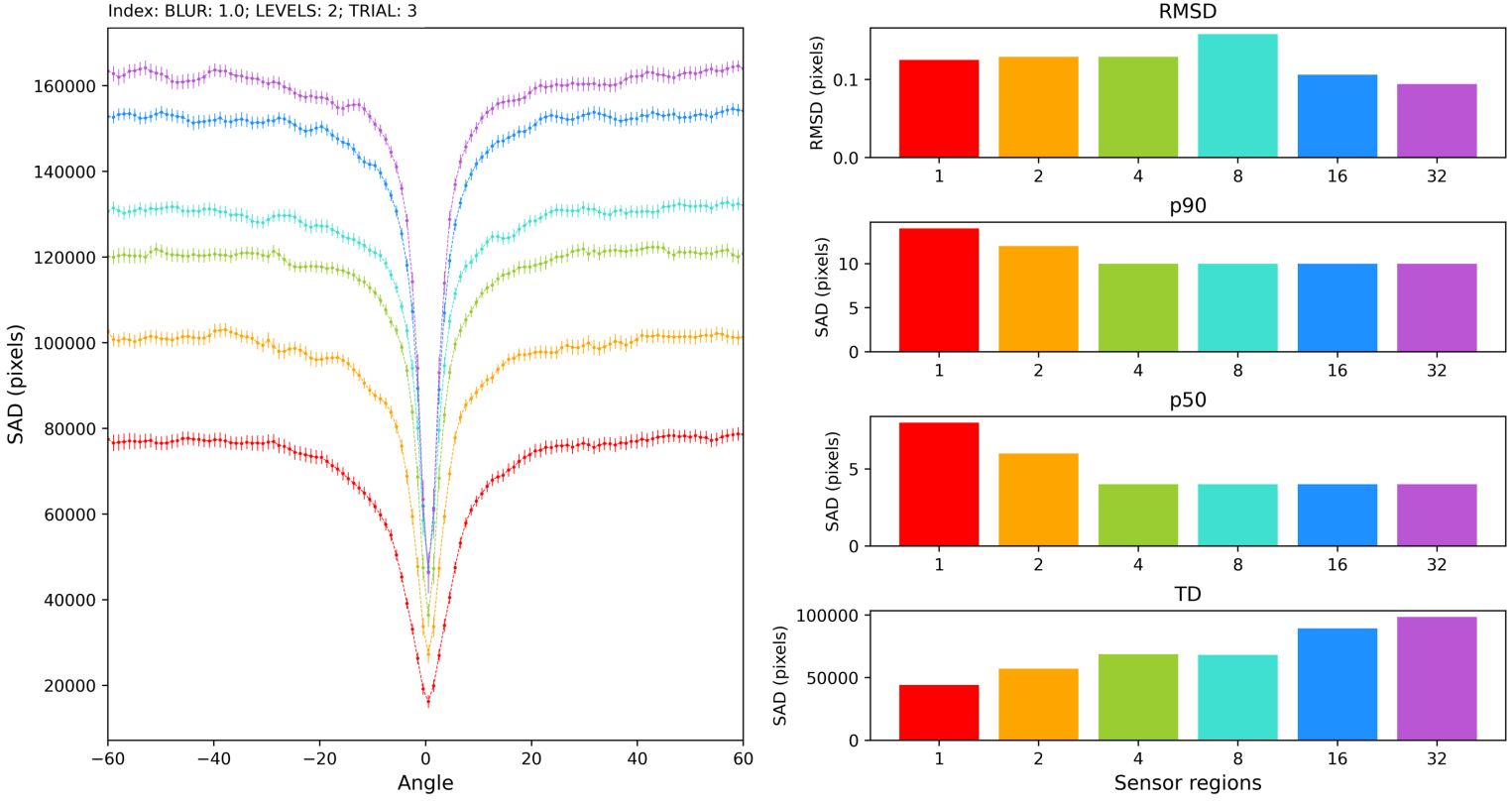
100%



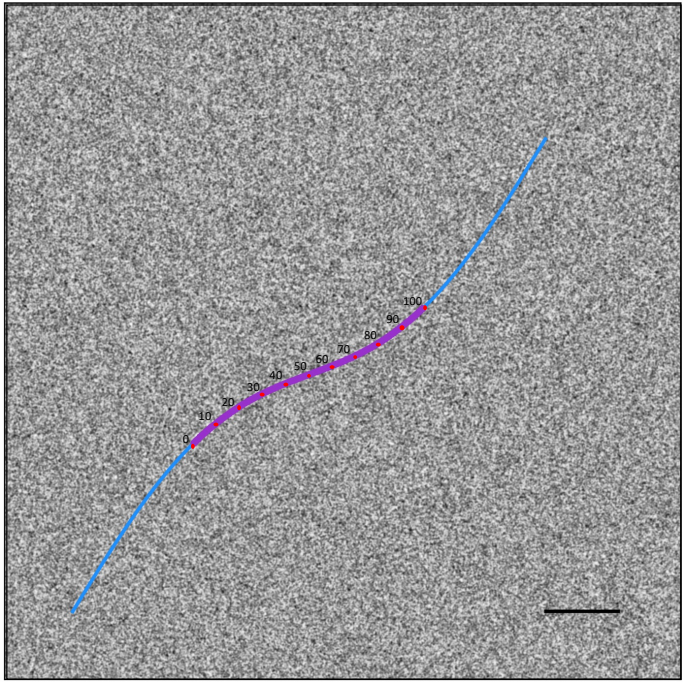


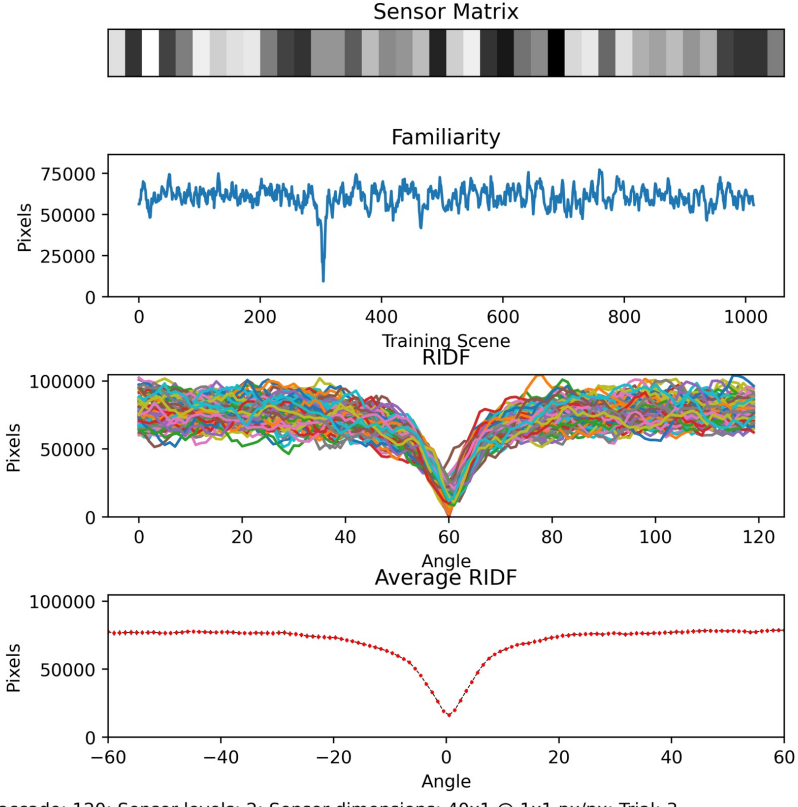
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 46.26; RMSD/dist: 0.116; TD: 95089; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 3
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
TD
100000
50000
Sensor regions

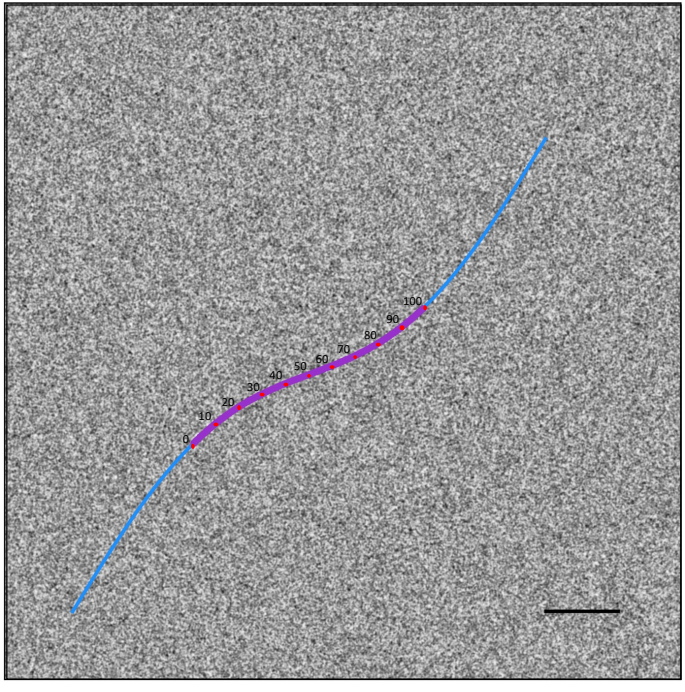
100%

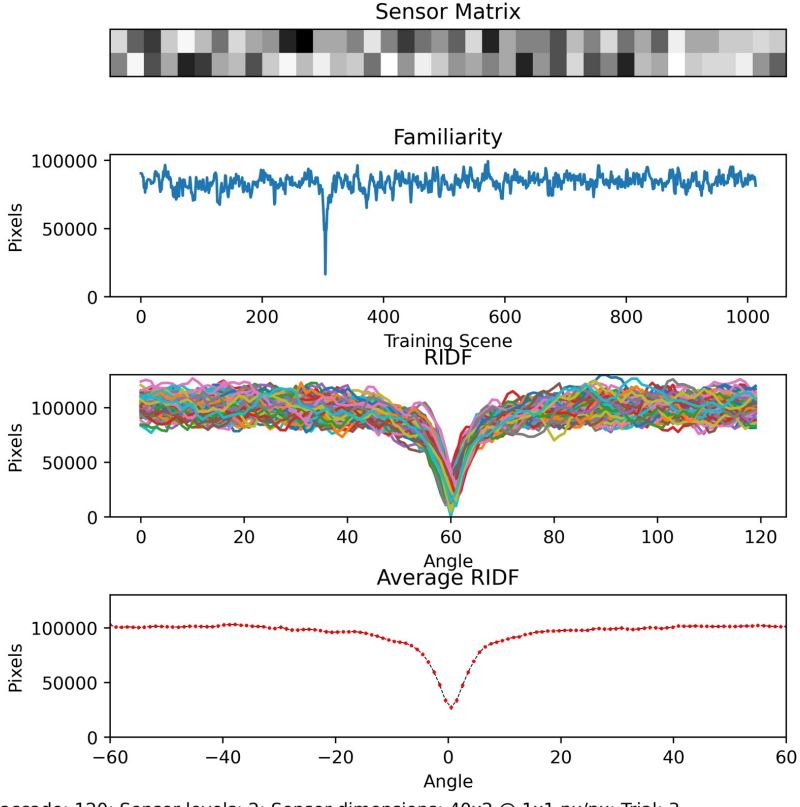




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 49.83; RMSD/dist: 0.125; TD: 44177; p90: 14; p50: 8; complete: 0

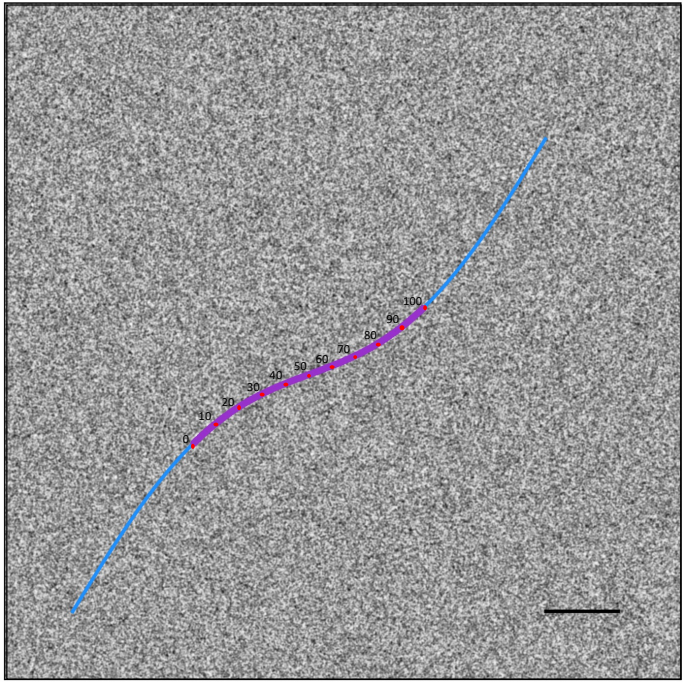
100%

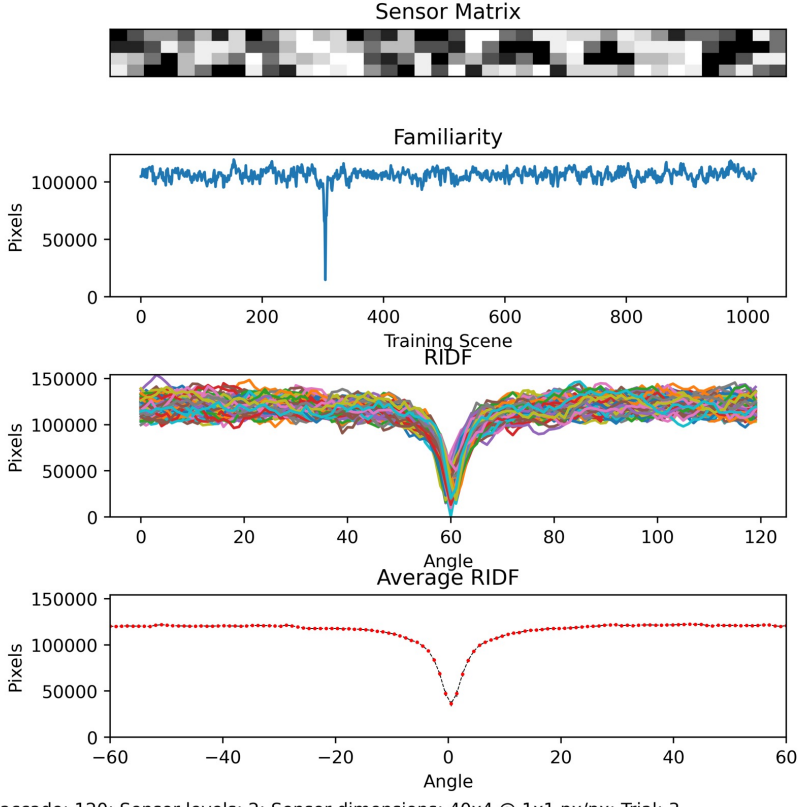




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 51.74; RMSD/dist: 0.129; TD: 57012; p90: 12; p50: 6; complete: 0

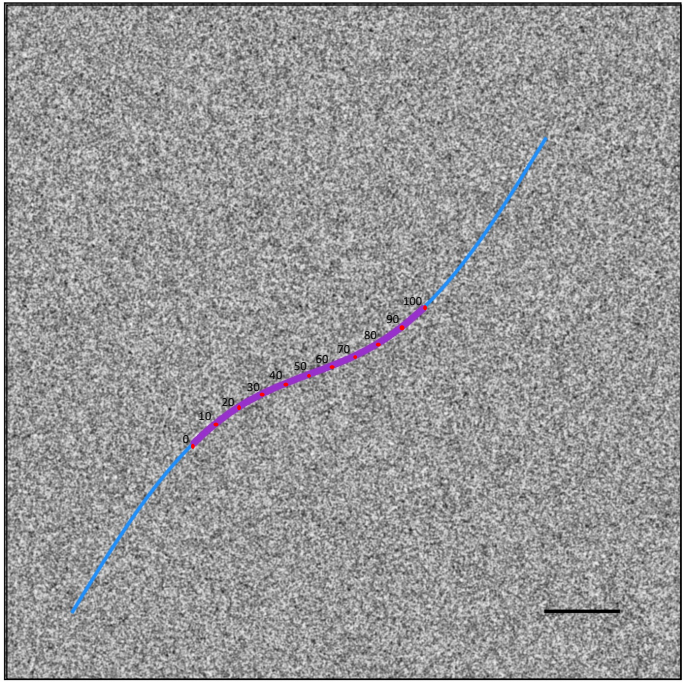
100%

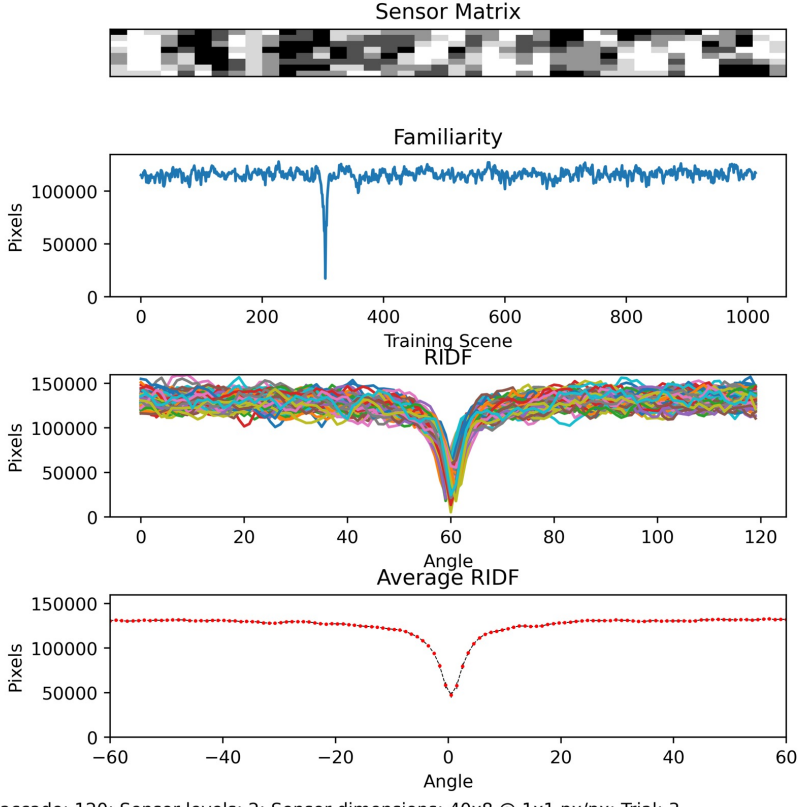




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 51.46; RMSD/dist: 0.129; TD: 68689; p90: 10; p50: 4; complete: 0

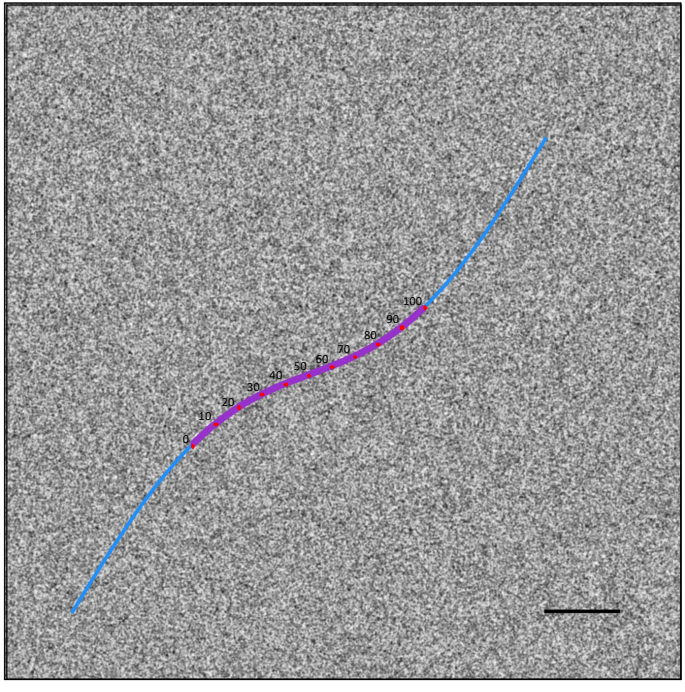
100%

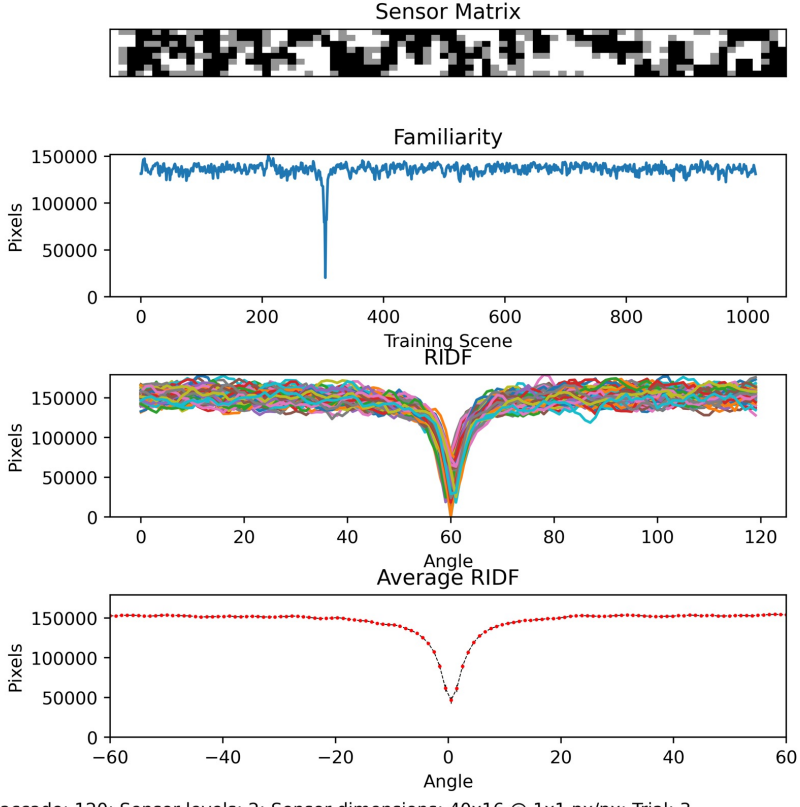




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 63.26; RMSD/dist: 0.158; TD: 68186; p90: 10; p50: 4; complete: 0

100%

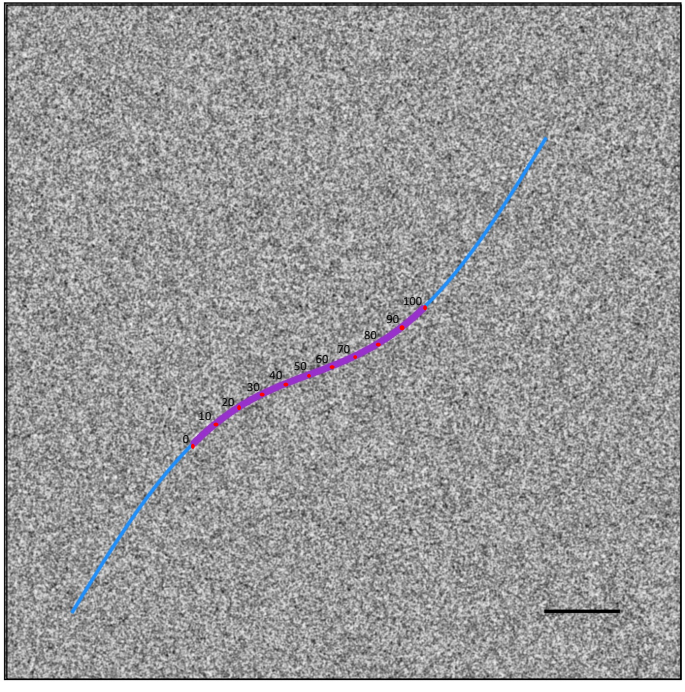


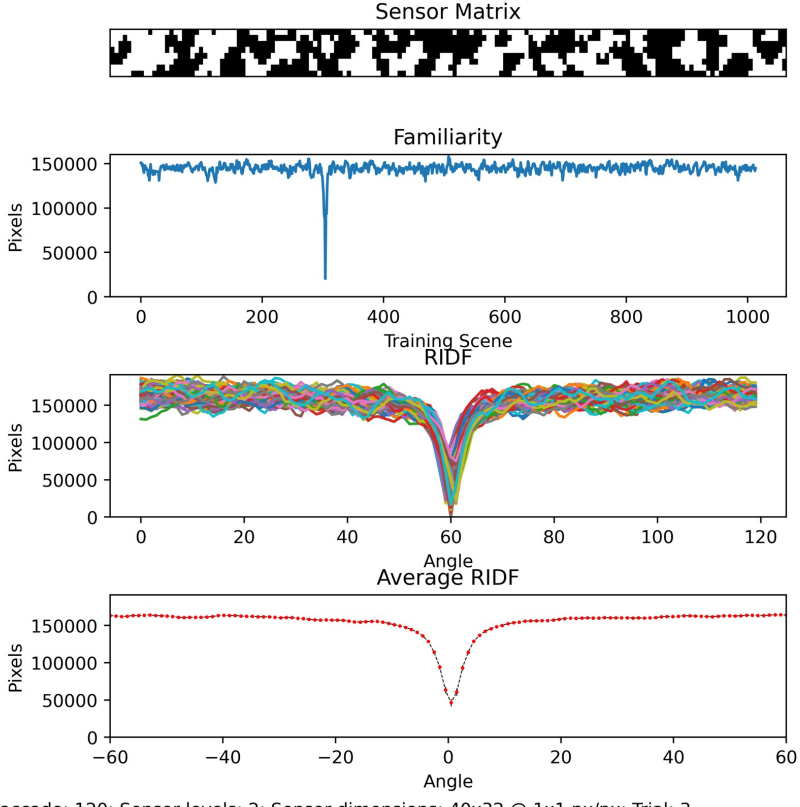


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

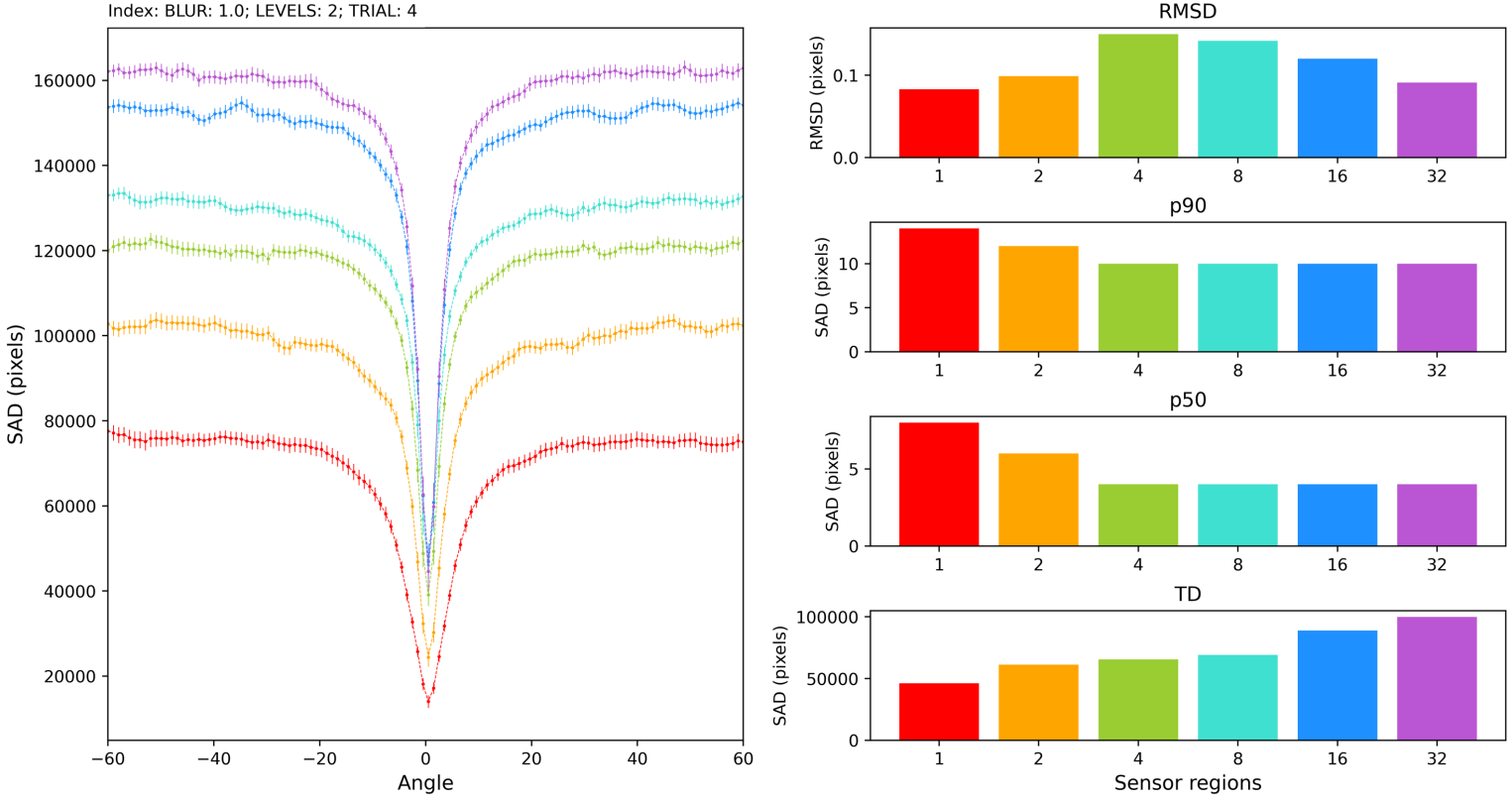
Navigation stats: RMSD error: 42.59; RMSD/dist: 0.106; TD: 89276; p90: 10; p50: 4; complete: 0

100%

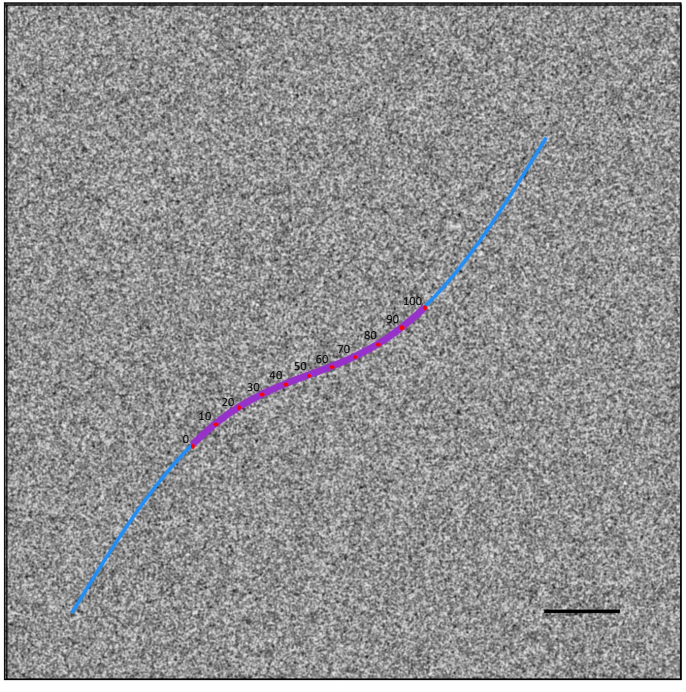


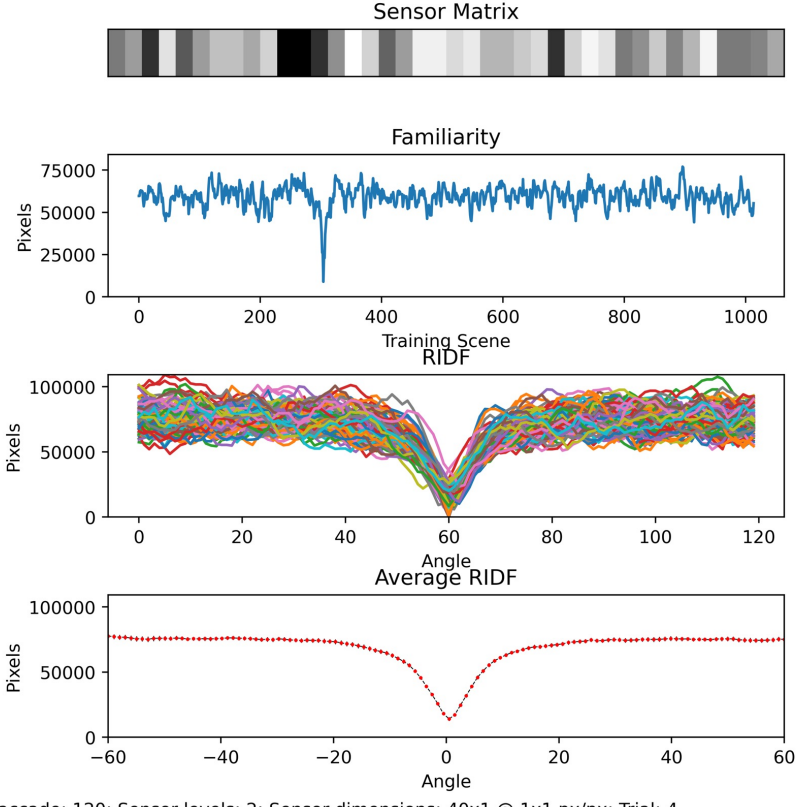


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 37.65; RMSD/dist: 0.094; TD: 98471; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 4
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

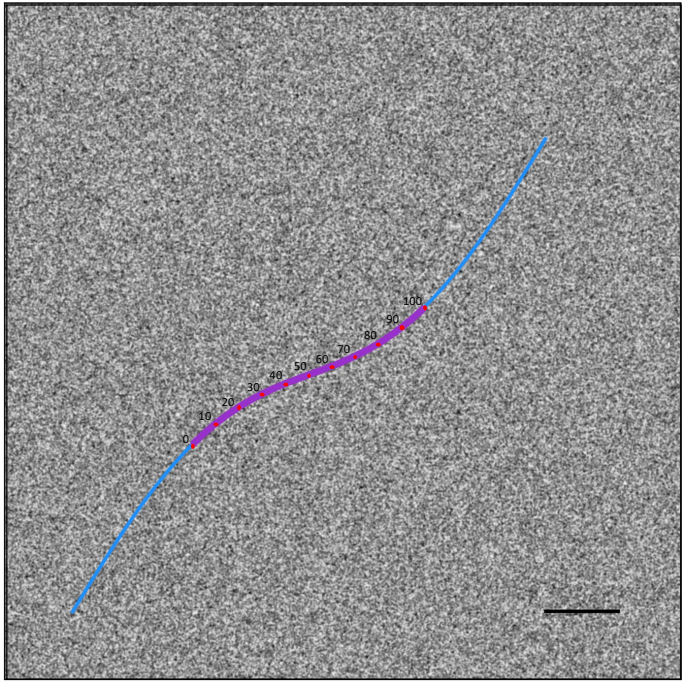
100%

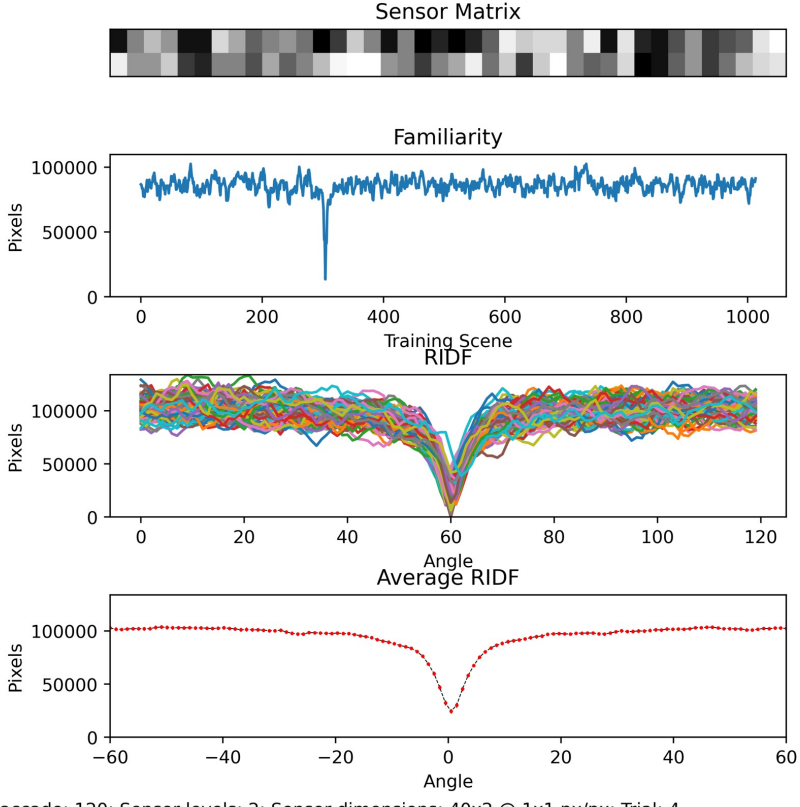




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 33.07; RMSD/dist: 0.083; TD: 46134; p90: 14; p50: 8; complete: 0

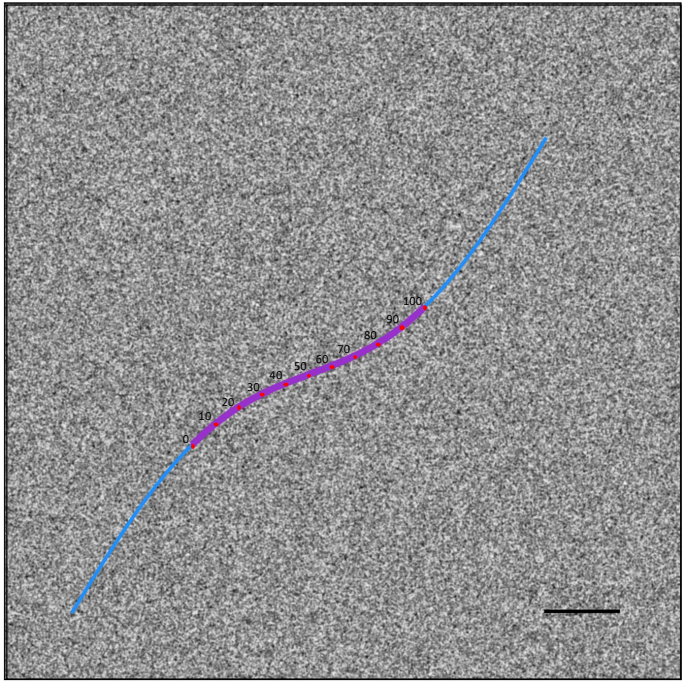
100%

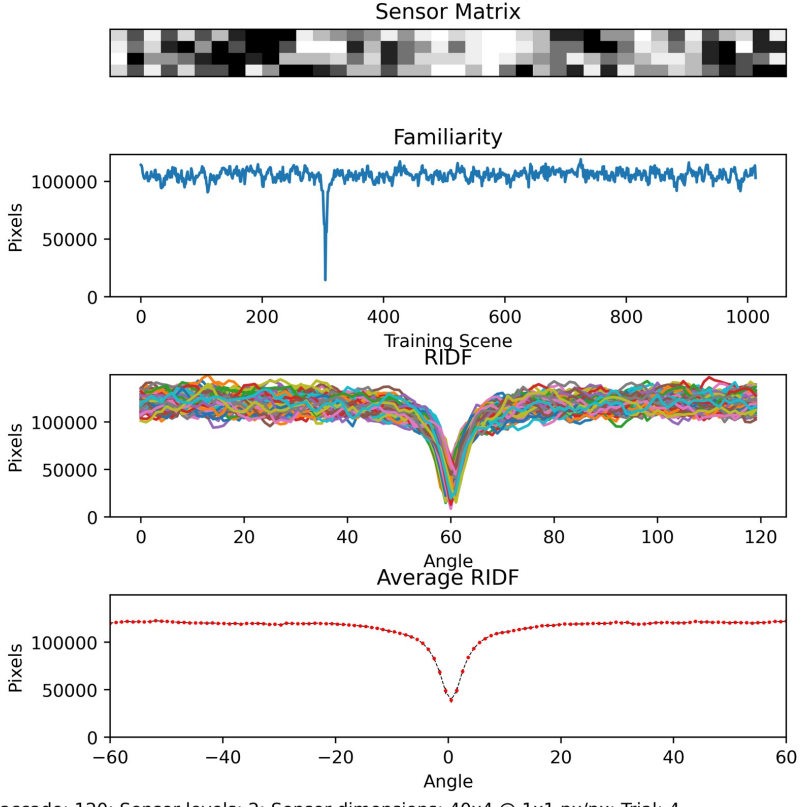




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 39.57; RMSD/dist: 0.099; TD: 61115; p90: 12; p50: 6; complete: 0

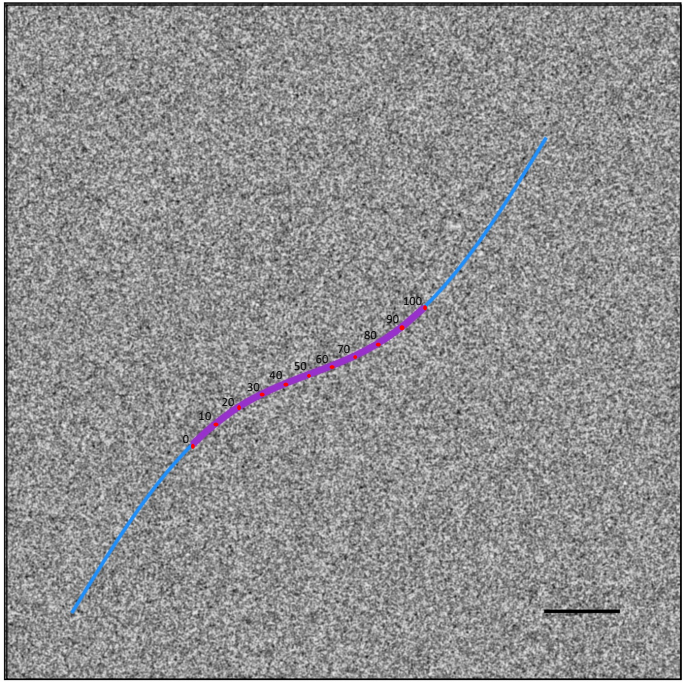
100%

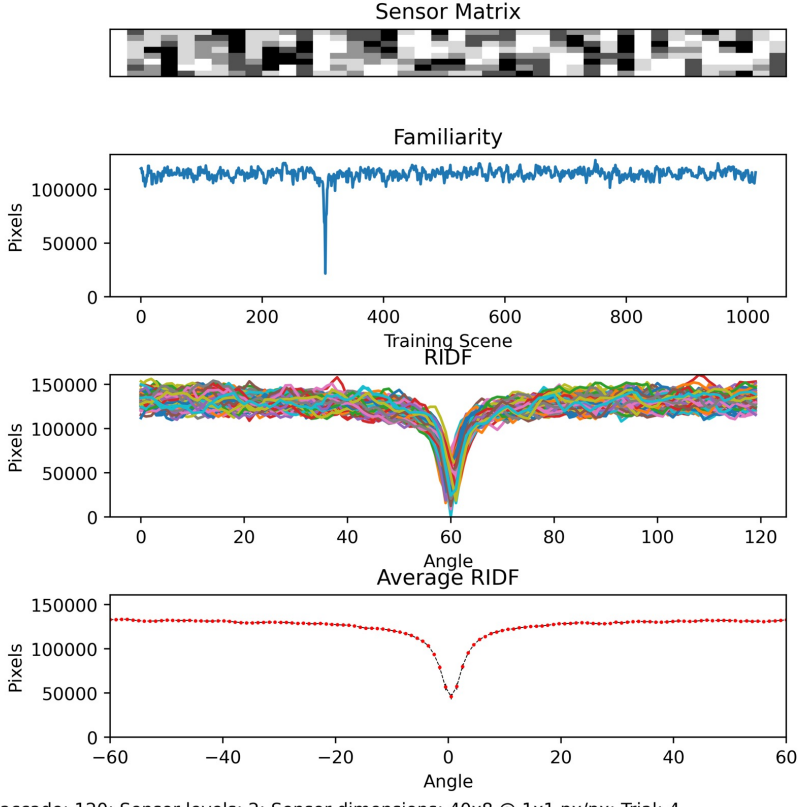




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 60.18; RMSD/dist: 0.150; TD: 65521; p90: 10; p50: 4; complete: 0

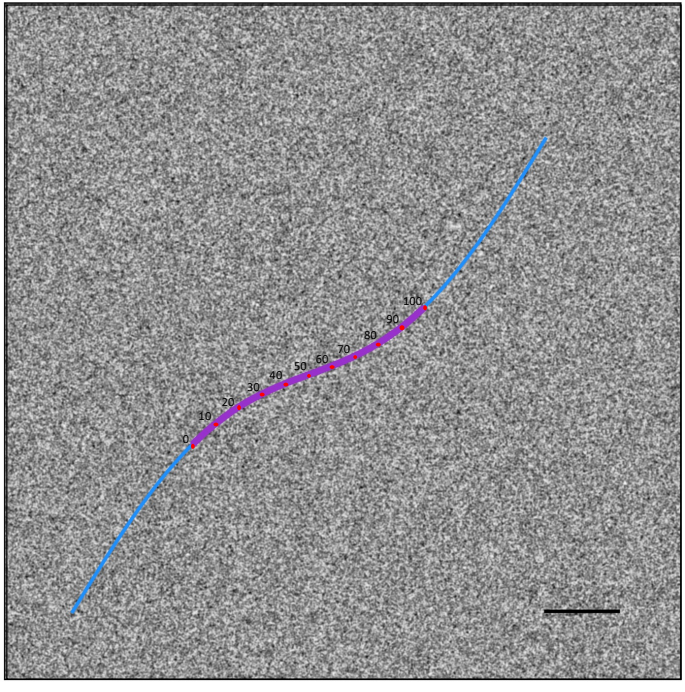
100%

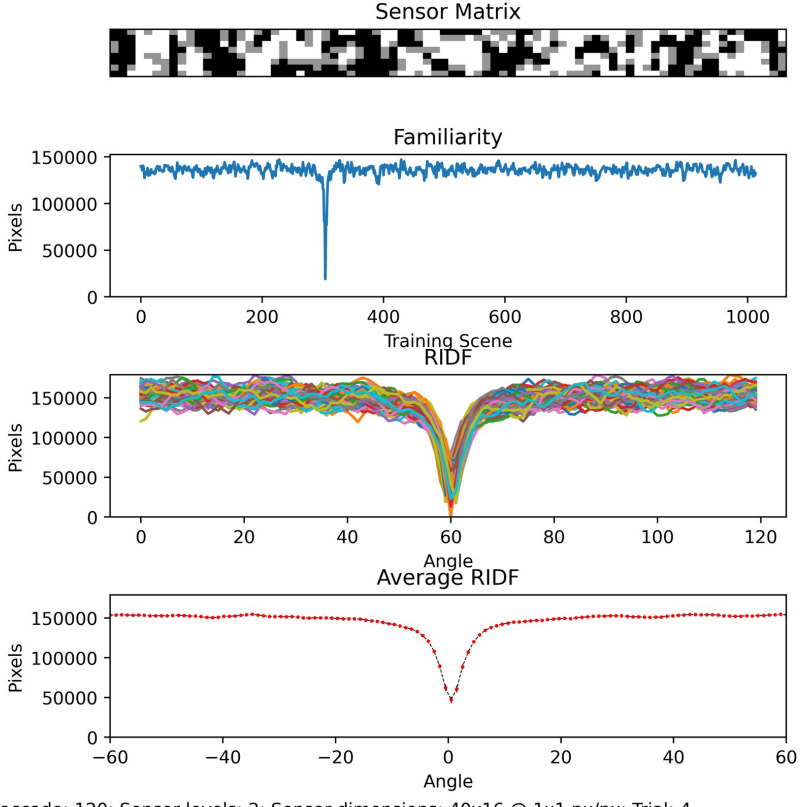




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 56.84; RMSD/dist: 0.142; TD: 69095; p90: 10; p50: 4; complete: 0

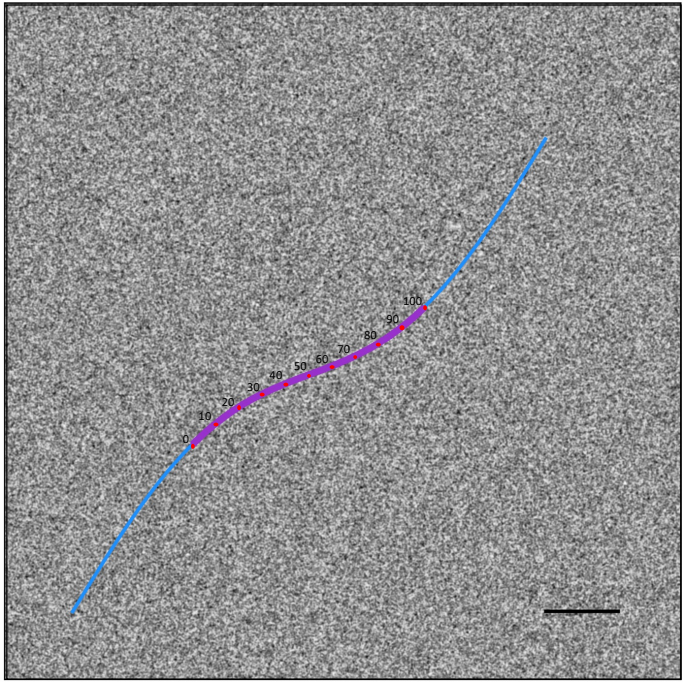
100%

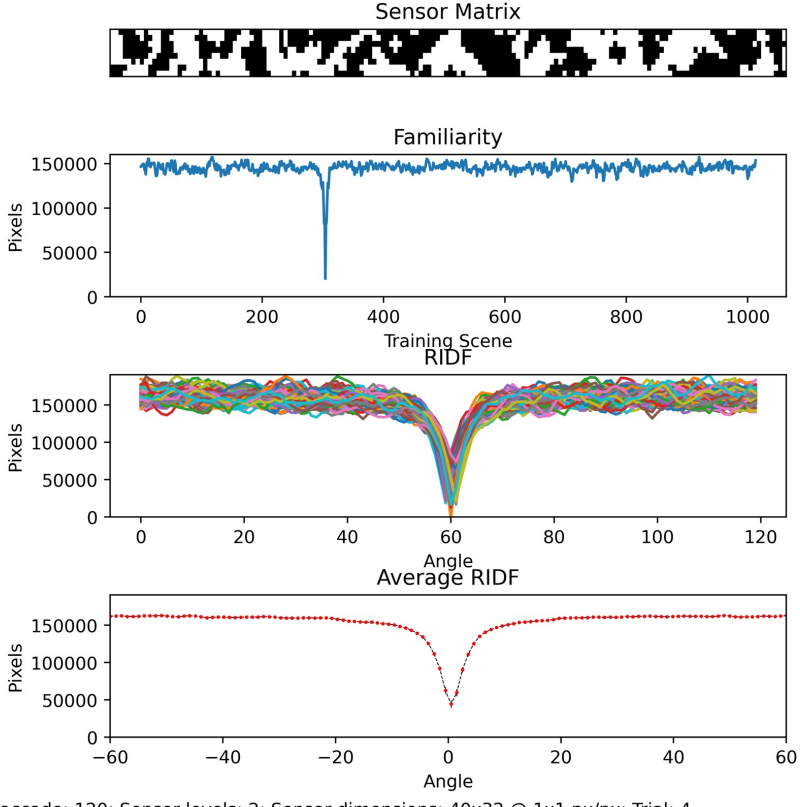




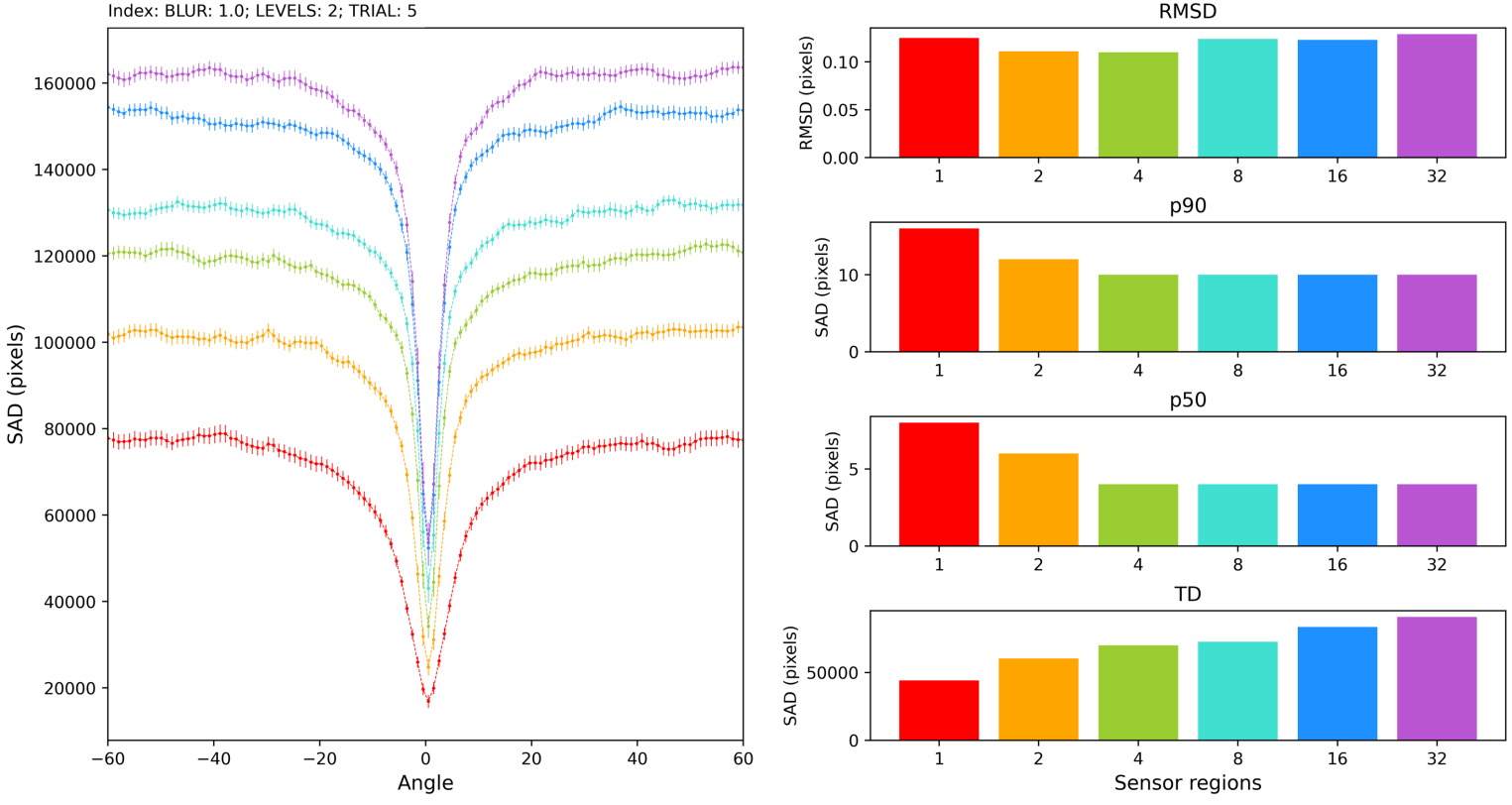
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 48.14; RMSD/dist: 0.120; TD: 88874; p90: 10; p50: 4; complete: 0

100%

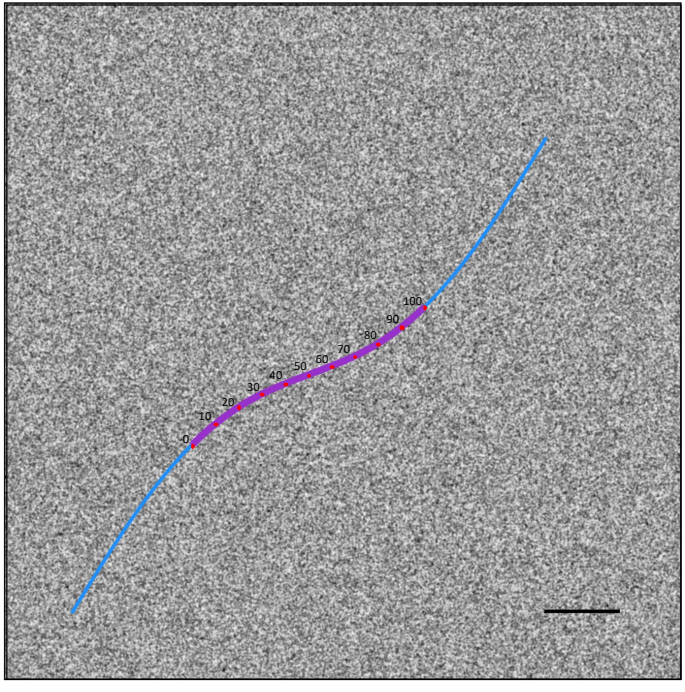


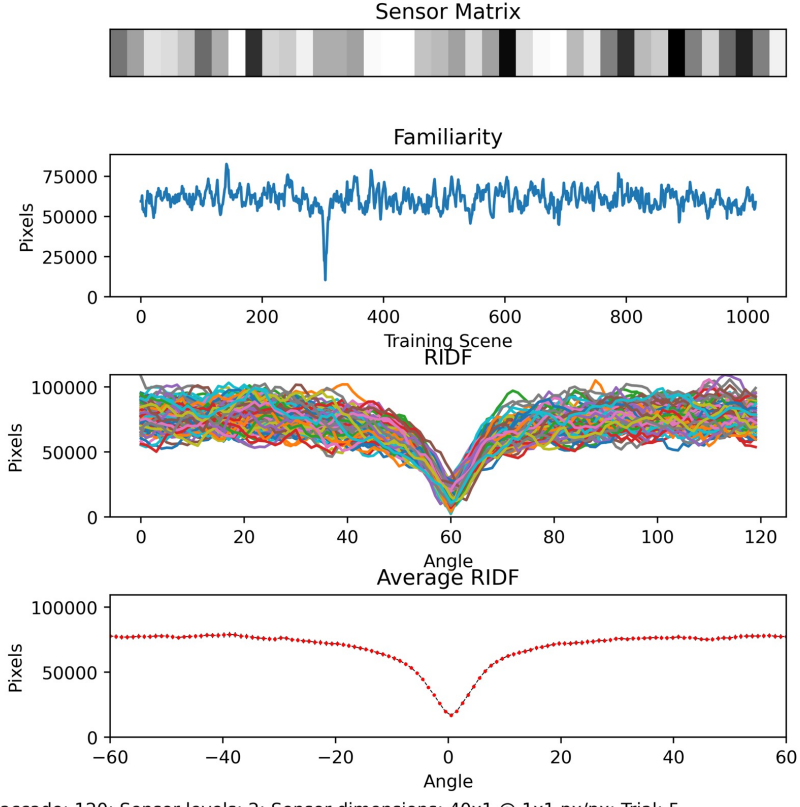


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 36.33; RMSD/dist: 0.091; TD: 99905; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 5
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
50000
0
Sensor regions

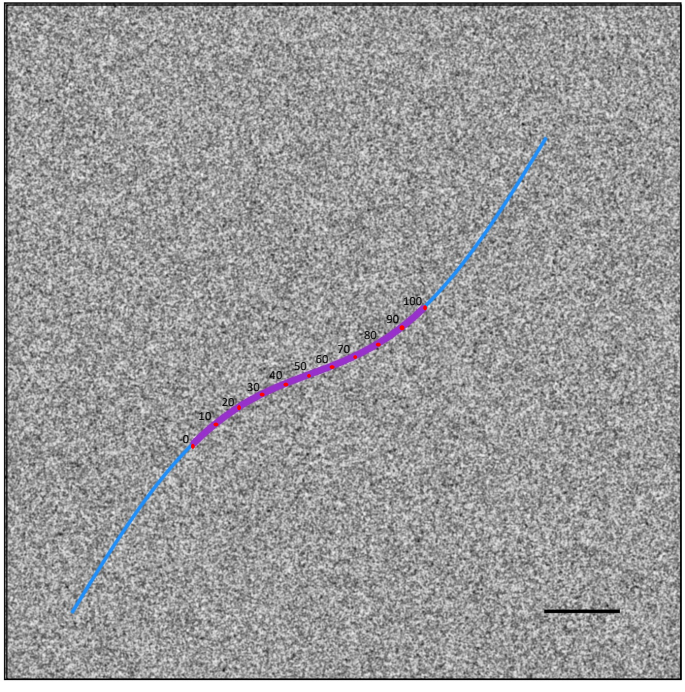
100%

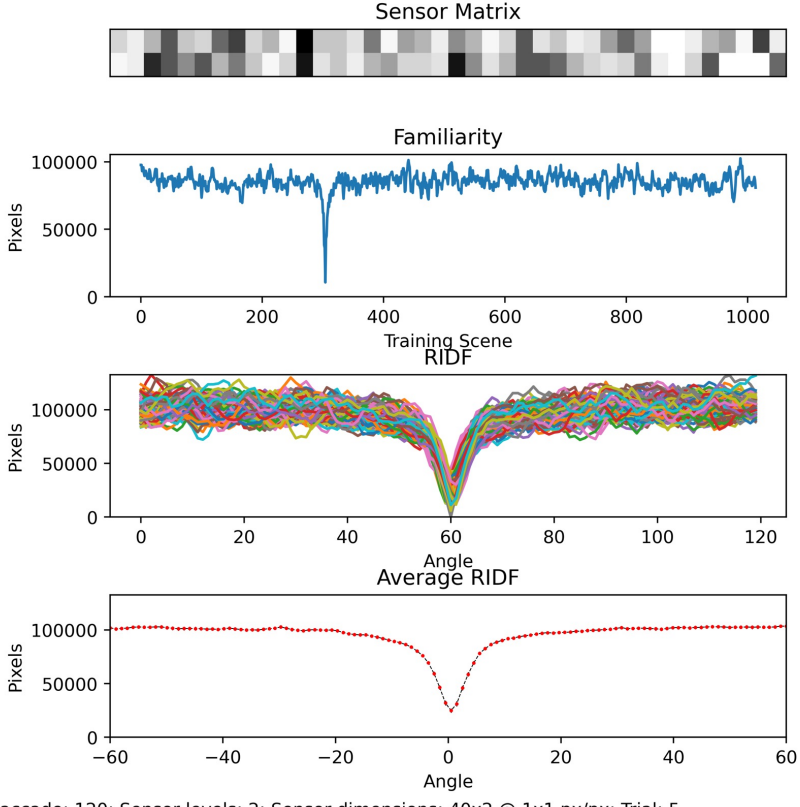




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 49.80; RMSD/dist: 0.125; TD: 44064; p90: 16; p50: 8; complete: 0

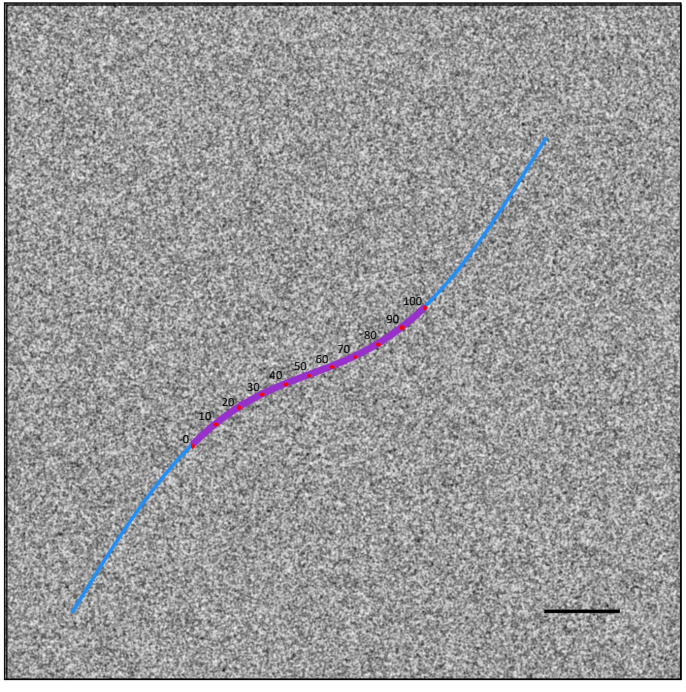
100%

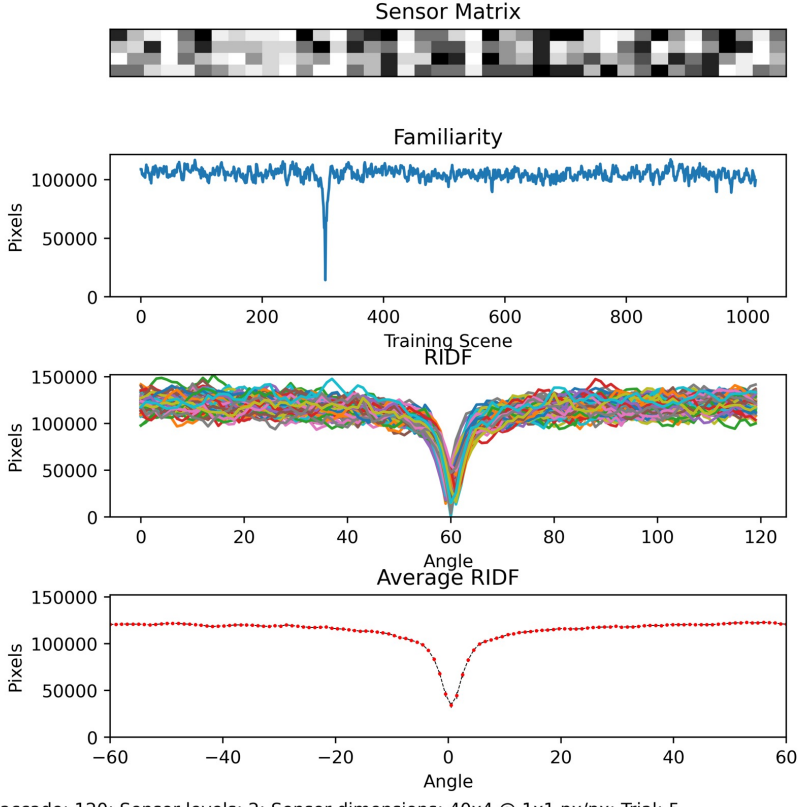




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 44.30; RMSD/dist: 0.111; TD: 60397; p90: 12; p50: 6; complete: 0

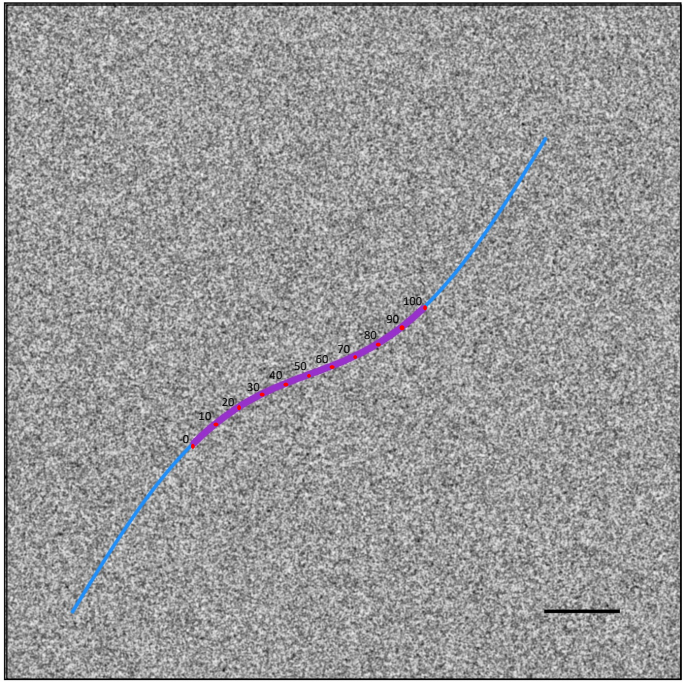
100%

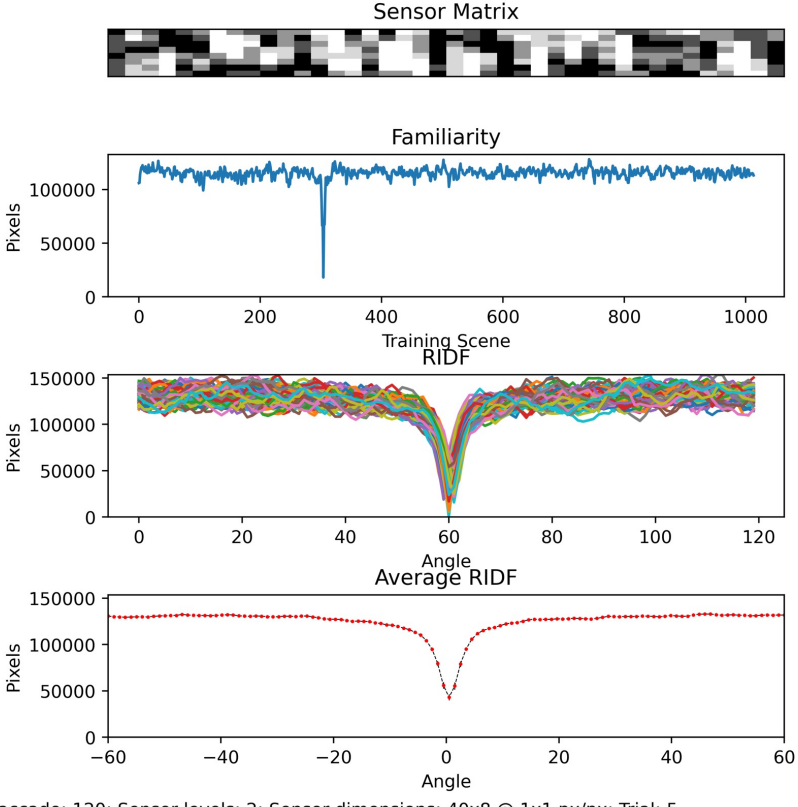




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 43.89; RMSD/dist: 0.110; TD: 69954; p90: 10; p50: 4; complete: 0

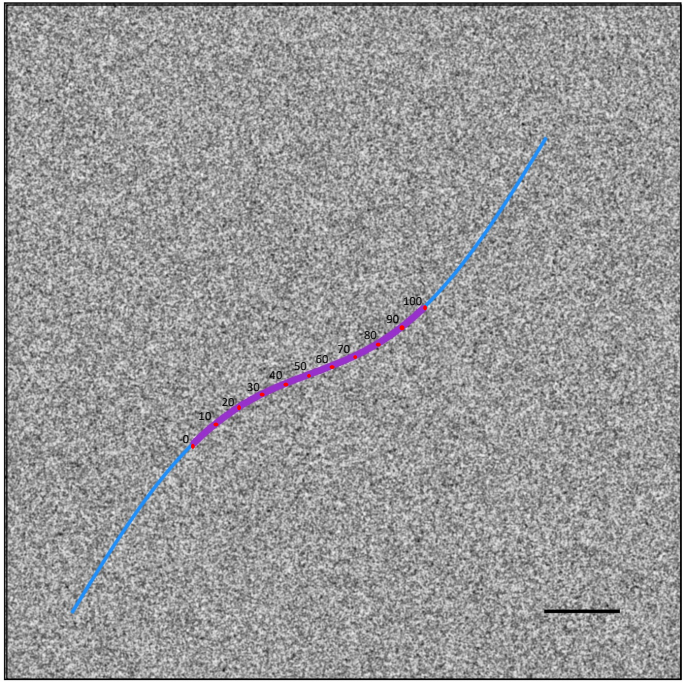
100%

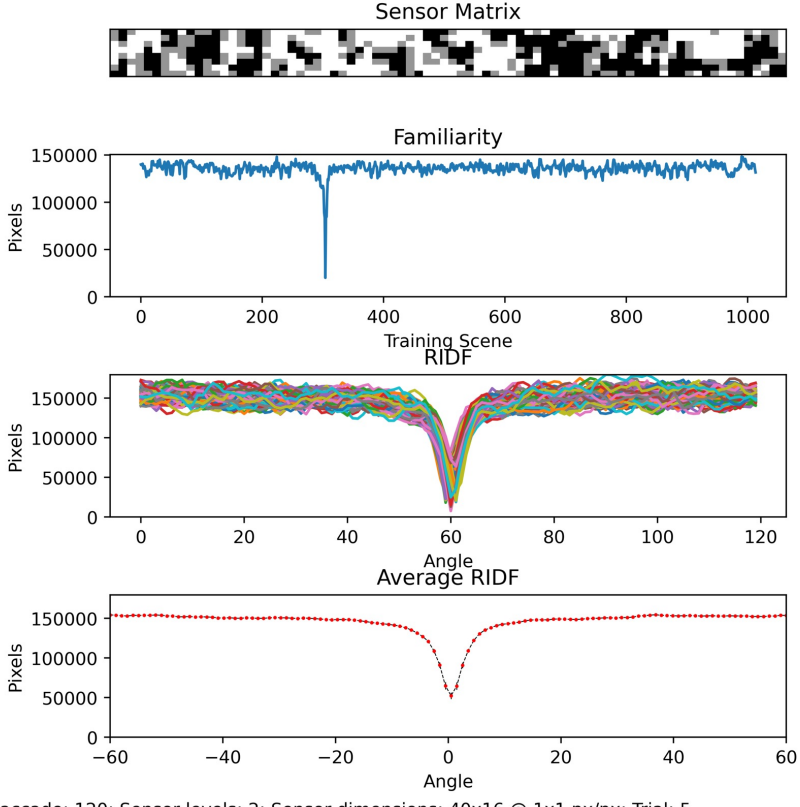




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 49.68; RMSD/dist: 0.124; TD: 72648; p90: 10; p50: 4; complete: 0

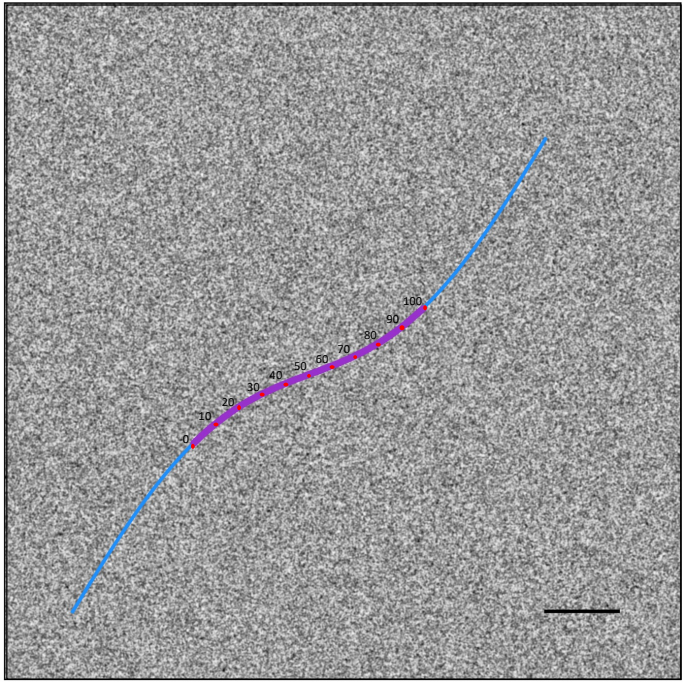
100%

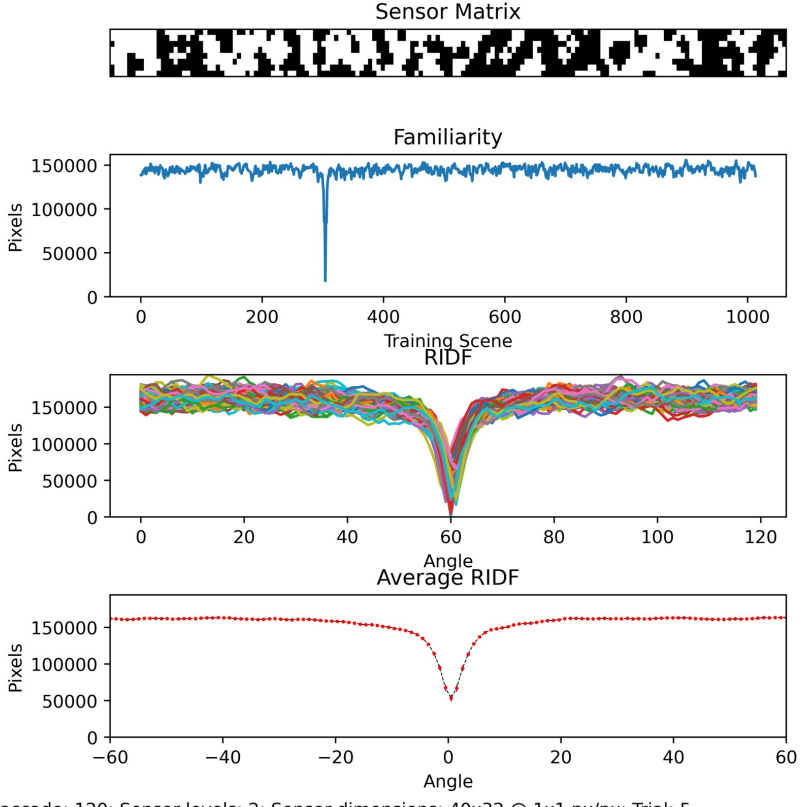




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 49.01; RMSD/dist: 0.123; TD: 83633; p90: 10; p50: 4; complete: 0

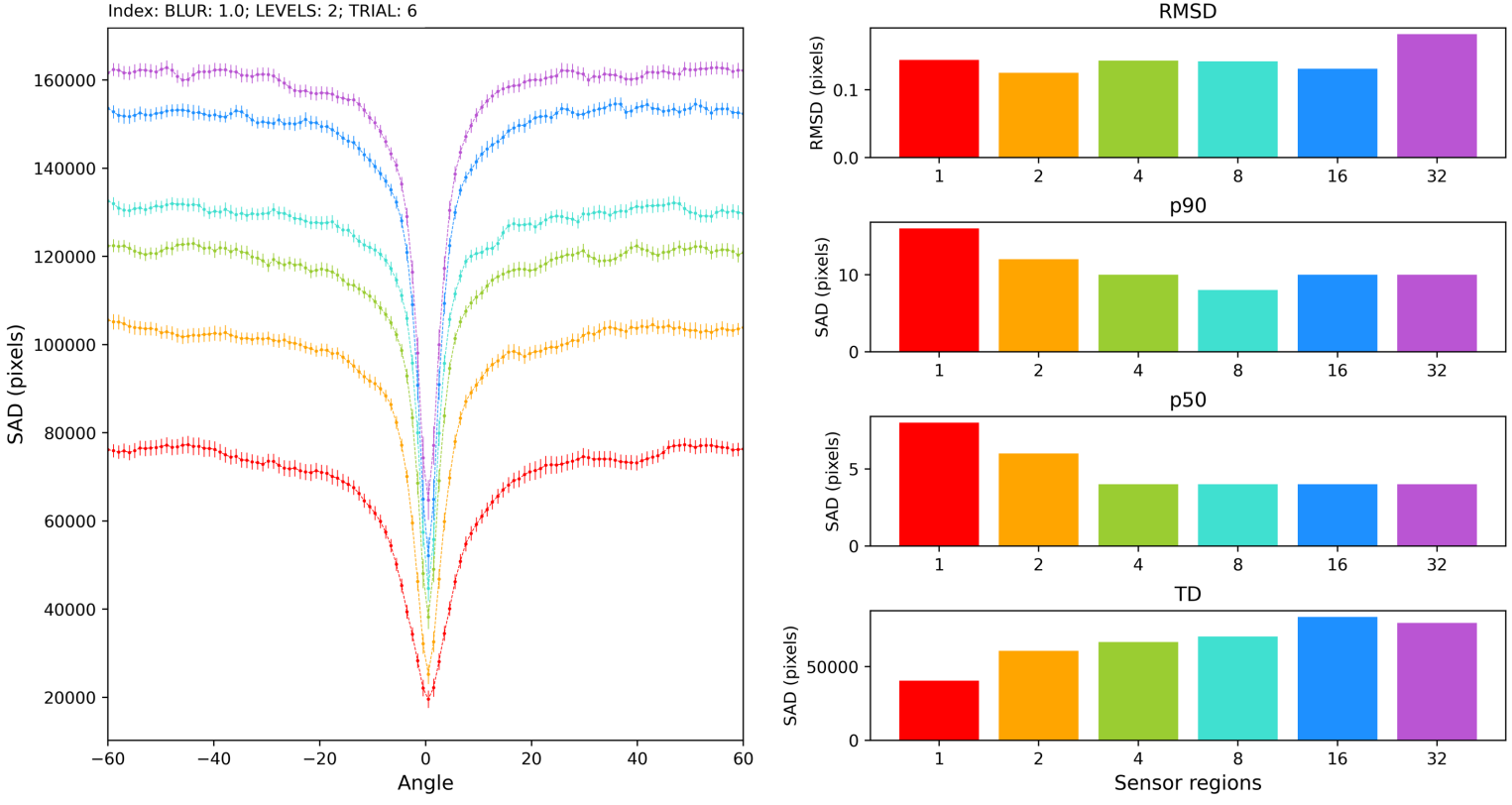
100%



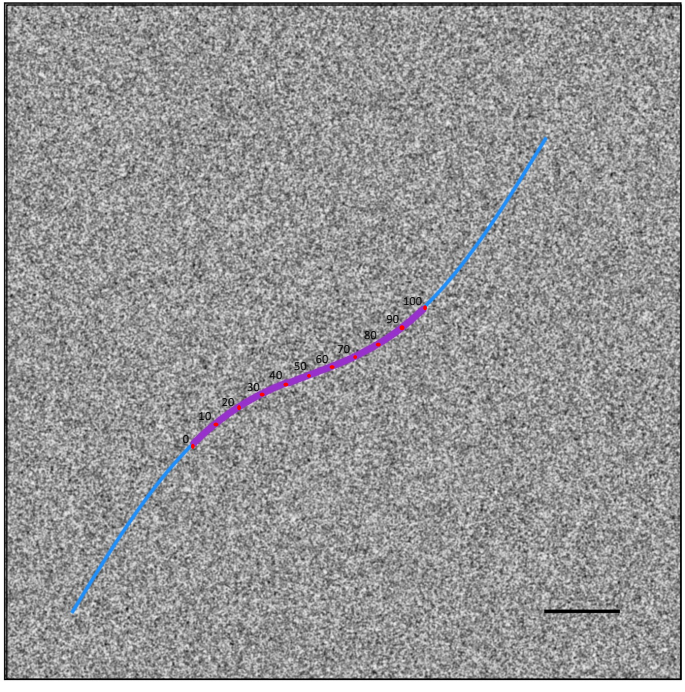


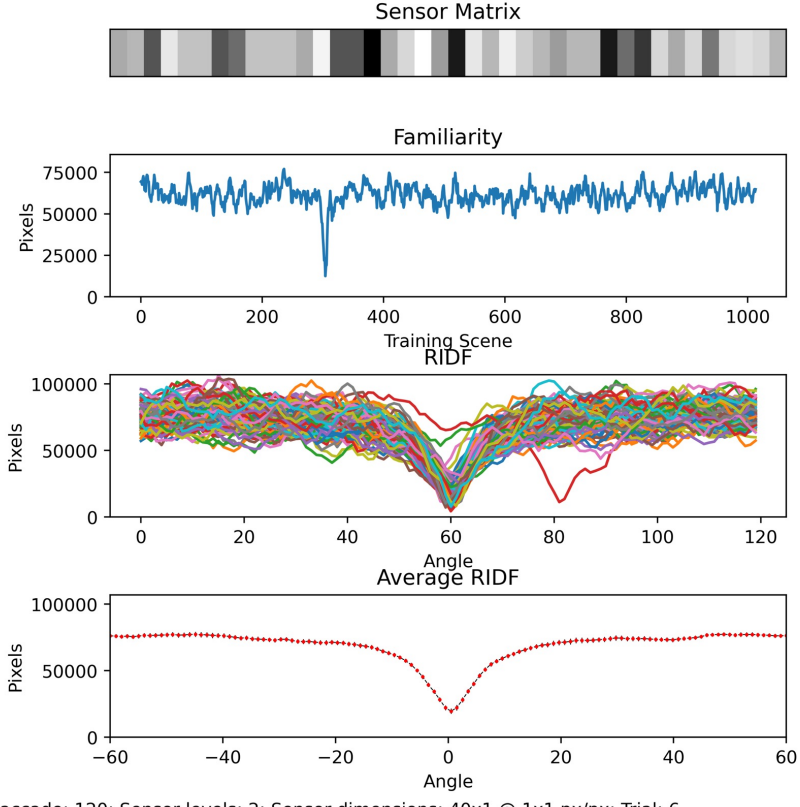
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 51.55; RMSD/dist: 0.129; TD: 91004; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 6
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.0
0.1
1
2
4
8
16
32
p90
SAD (pixels)
0
10
p50
5
TD
50000
Sensor regions

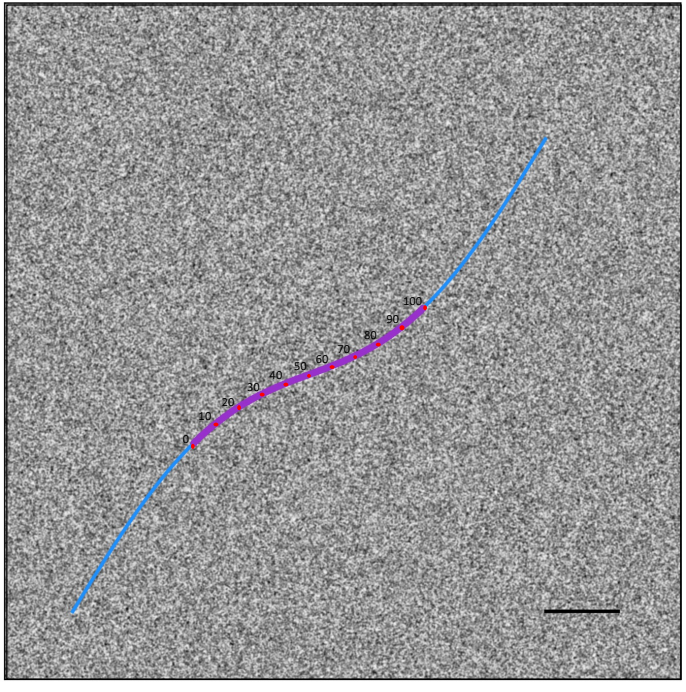
100%

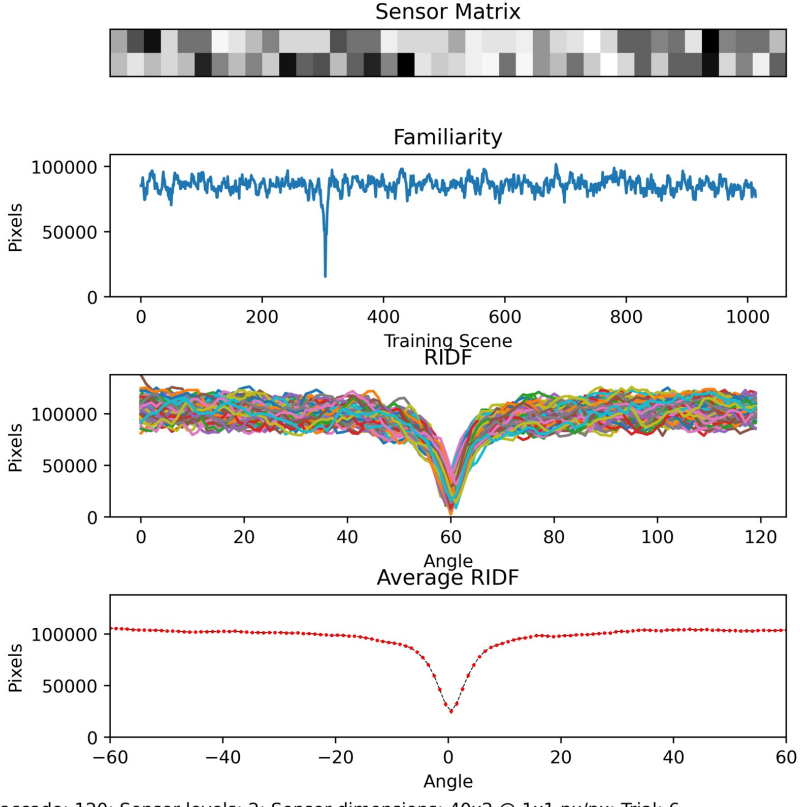




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 57.45; RMSD/dist: 0.144; TD: 40504; p90: 16; p50: 8; complete: 0

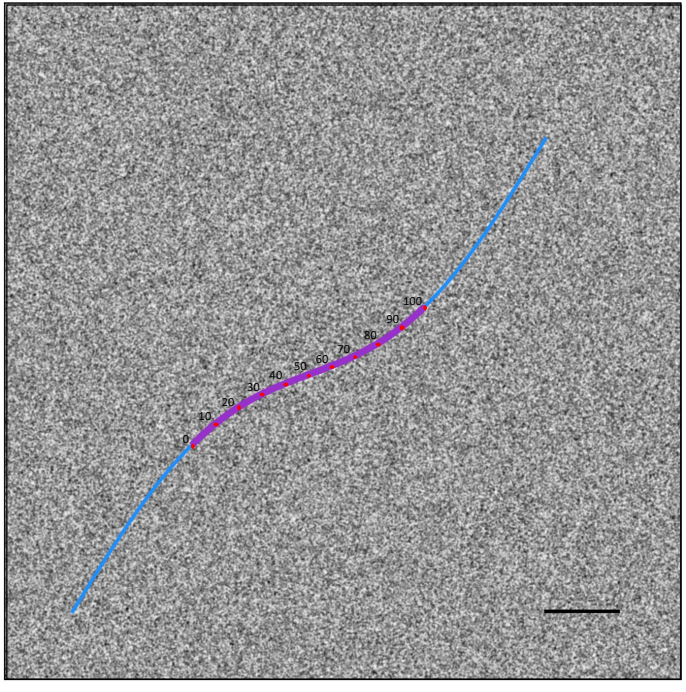
100%

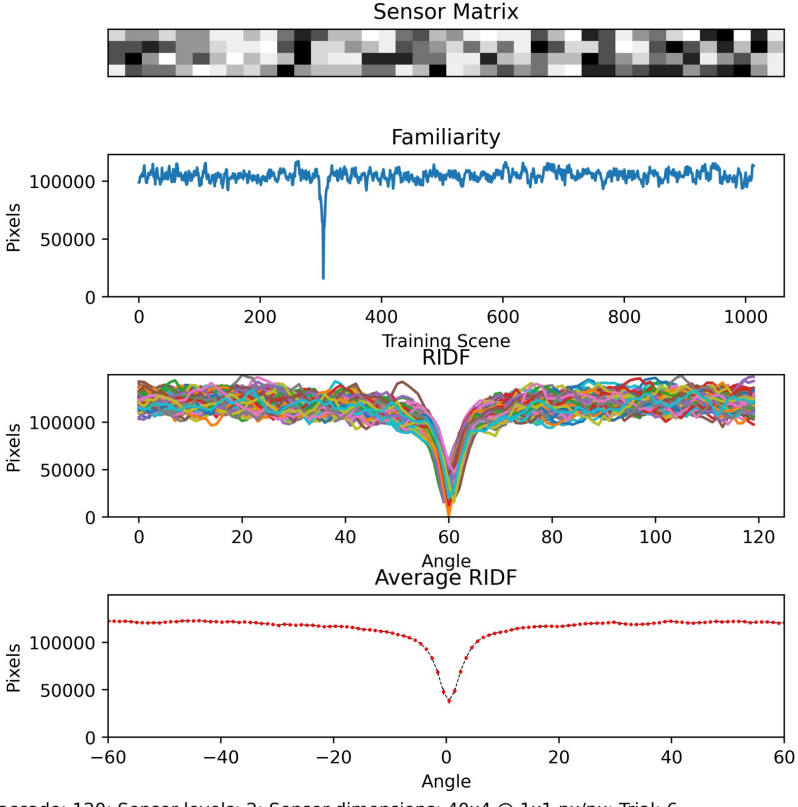




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 49.84; RMSD/dist: 0.125; TD: 60781; p90: 12; p50: 6; complete: 0

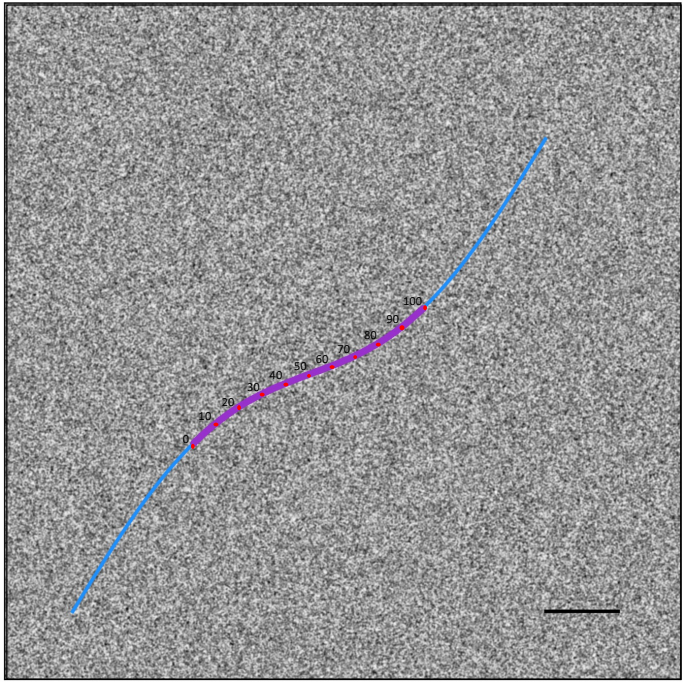
100%

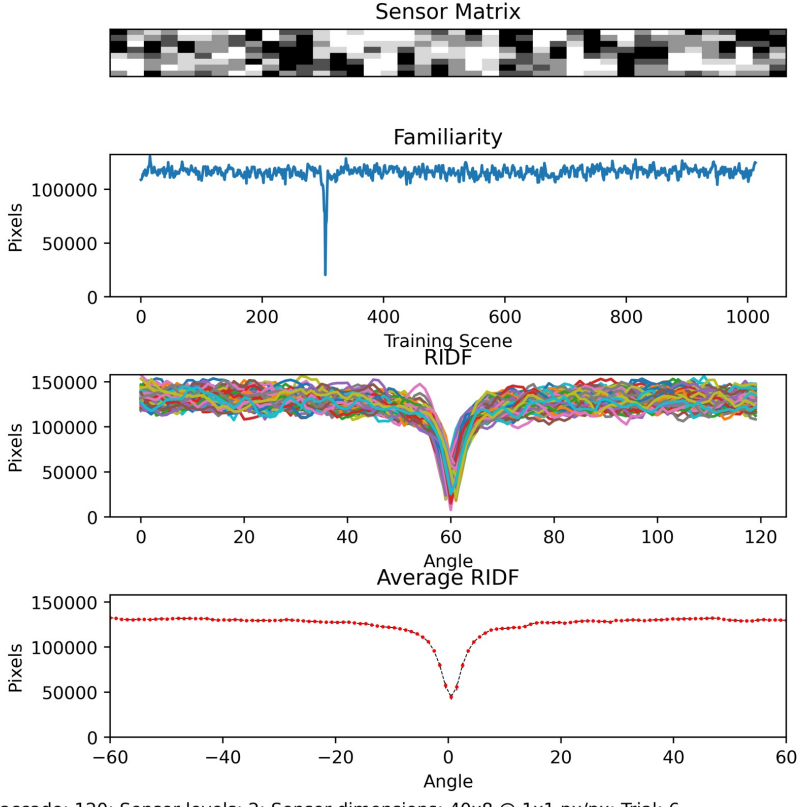




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 57.32; RMSD/dist: 0.143; TD: 66813; p90: 10; p50: 4; complete: 0

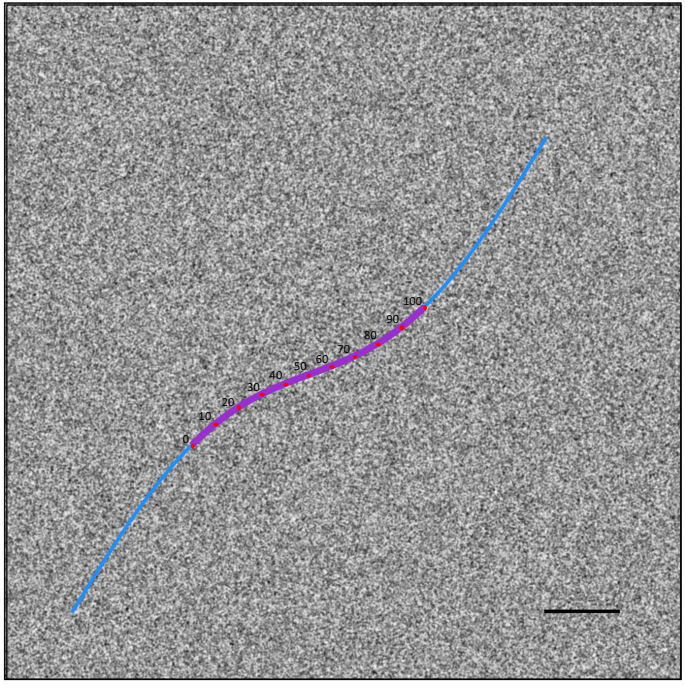
100%

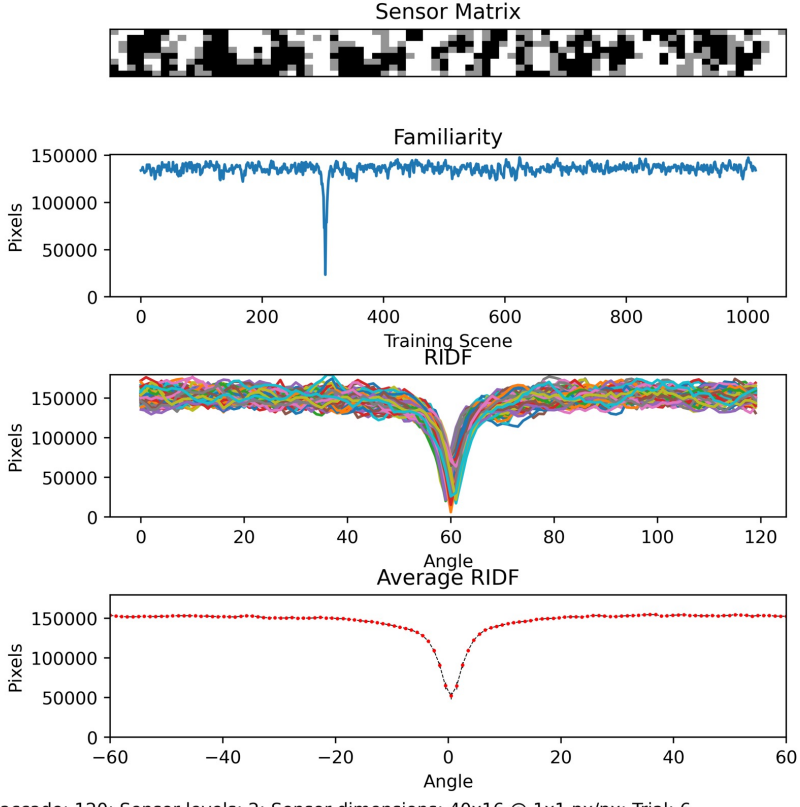




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 56.61; RMSD/dist: 0.142; TD: 70492; p90: 8; p50: 4; complete: 0

100%

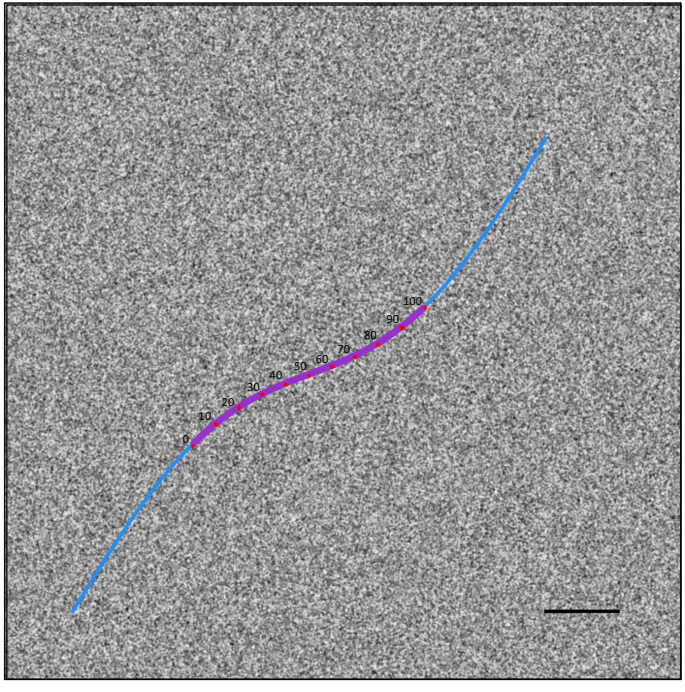


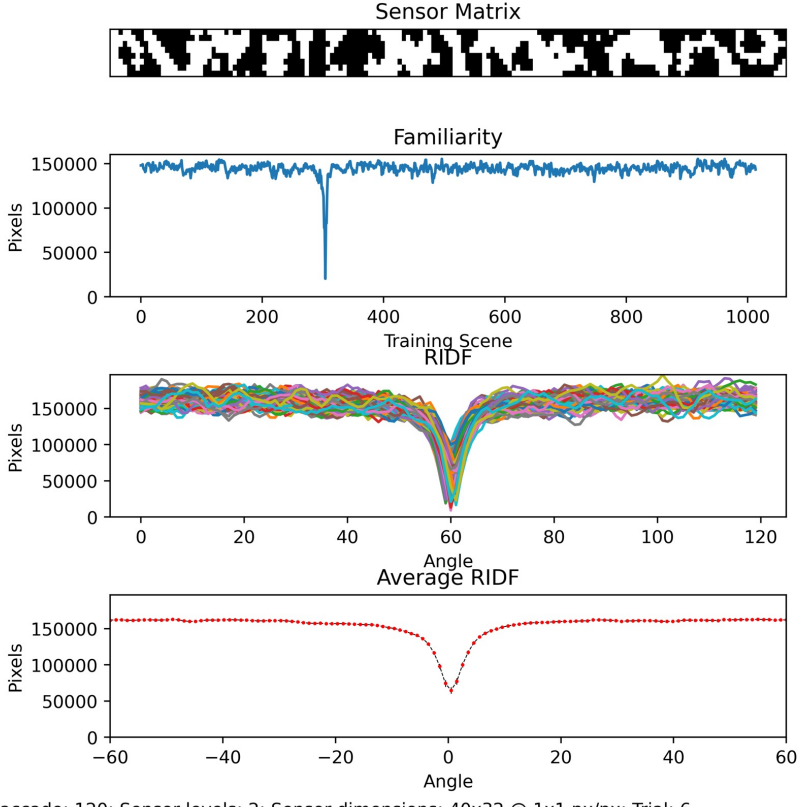


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

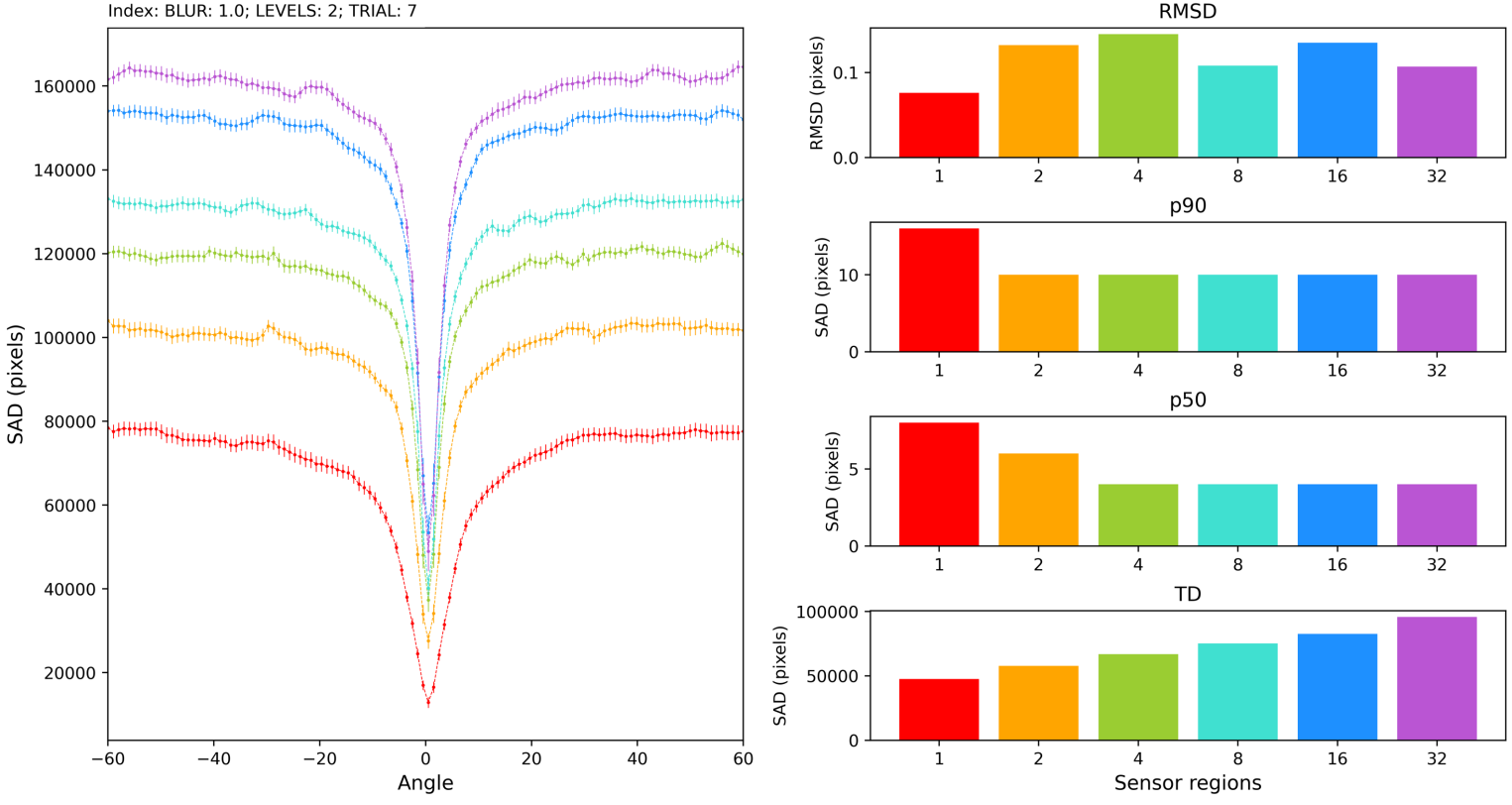
Navigation stats: RMSD error: 52.28; RMSD/dist: 0.131; TD: 83817; p90: 10; p50: 4; complete: 0

100%

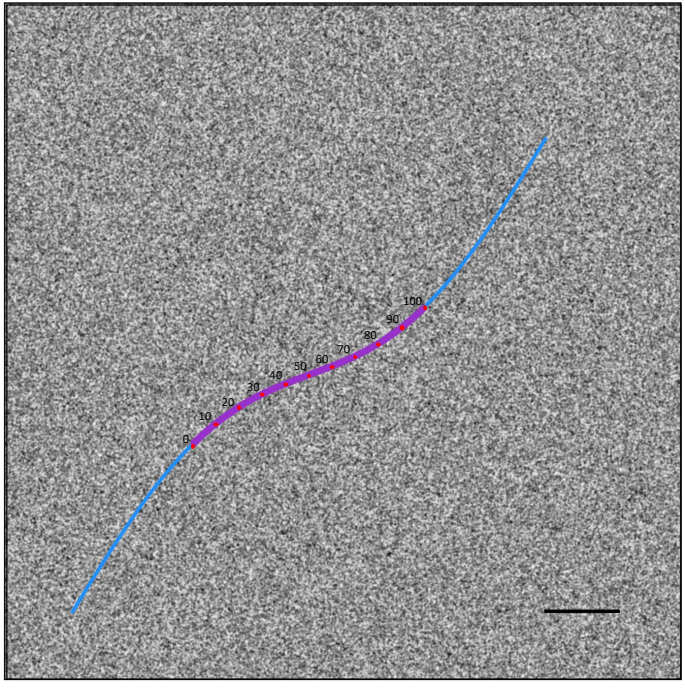


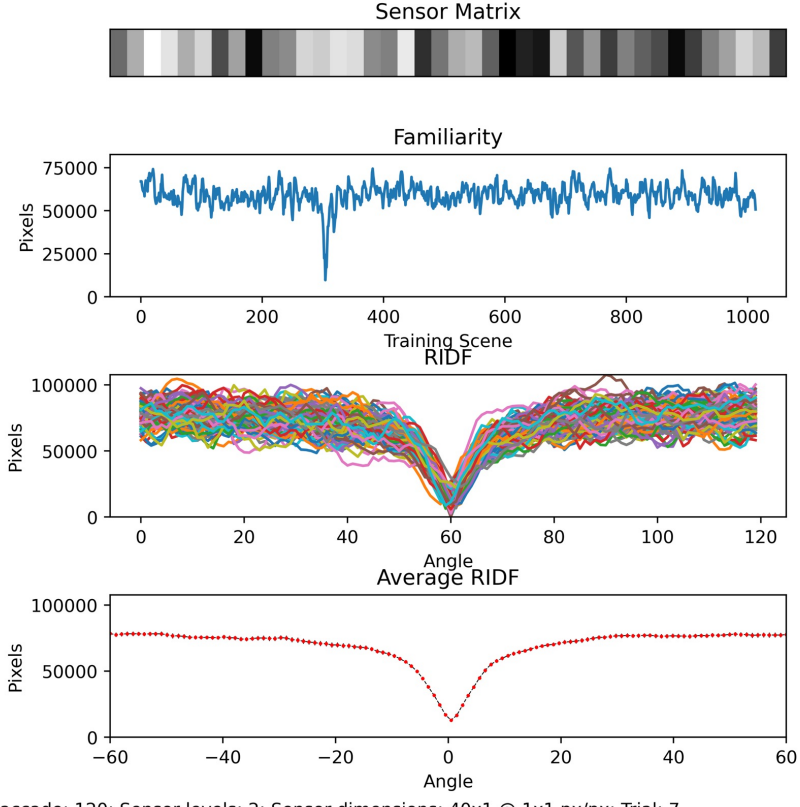


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 72.91; RMSD/dist: 0.182; TD: 79786; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 7
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.0
0.1
1
2
4
8
16
32
p90
SAD (pixels)
0
10
p50
SAD (pixels)
0
5
TD
SAD (pixels)
0
50000
100000
Sensor regions

100%

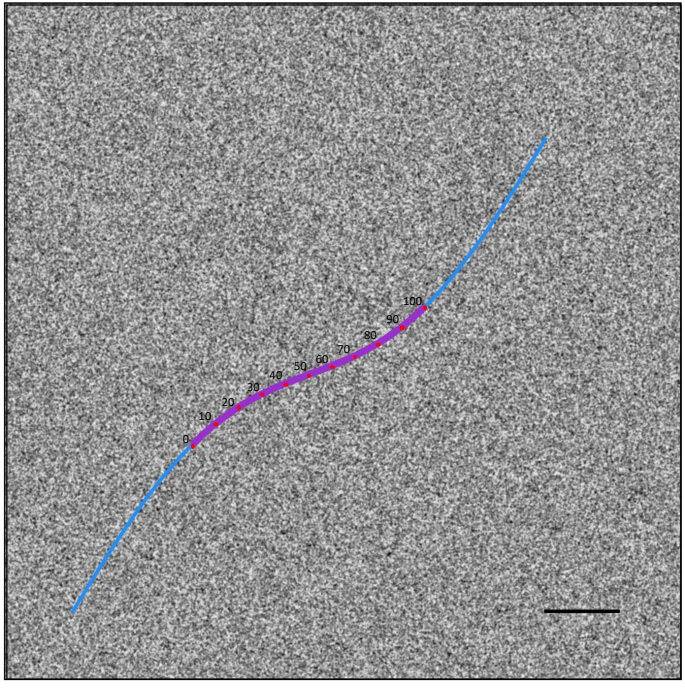


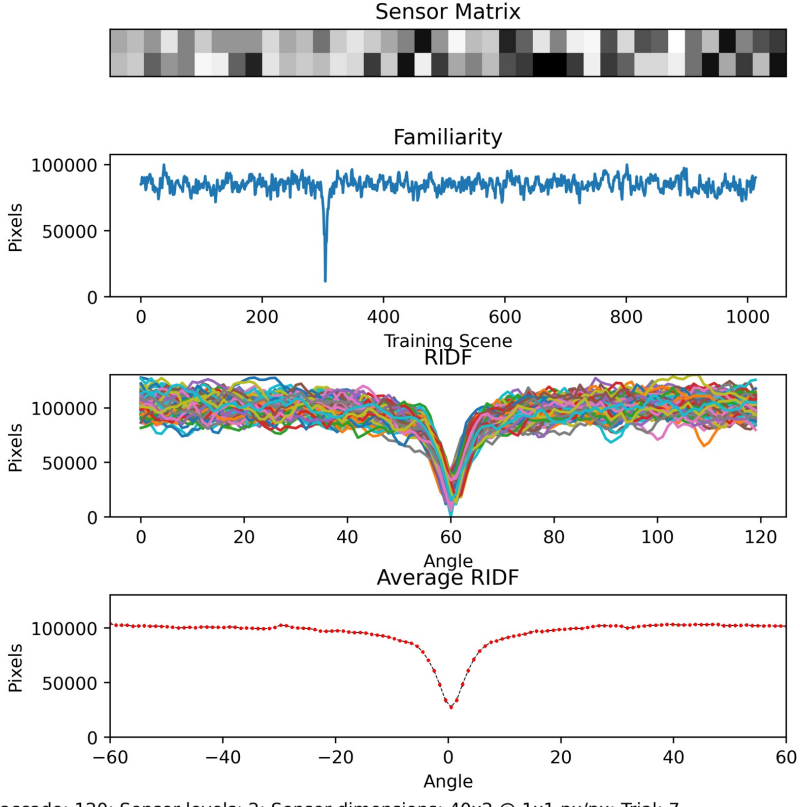


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 30.56; RMSD/dist: 0.076; TD: 47543; p90: 16; p50: 8; complete: 0

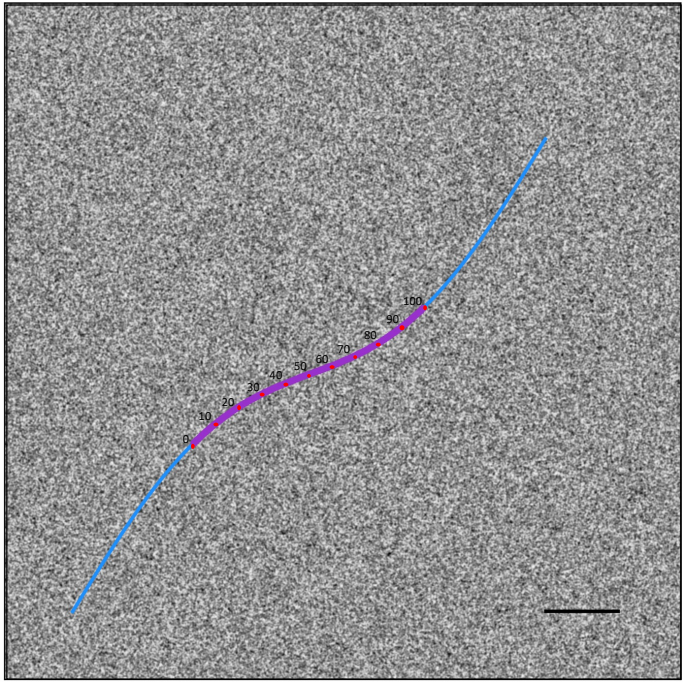
100%

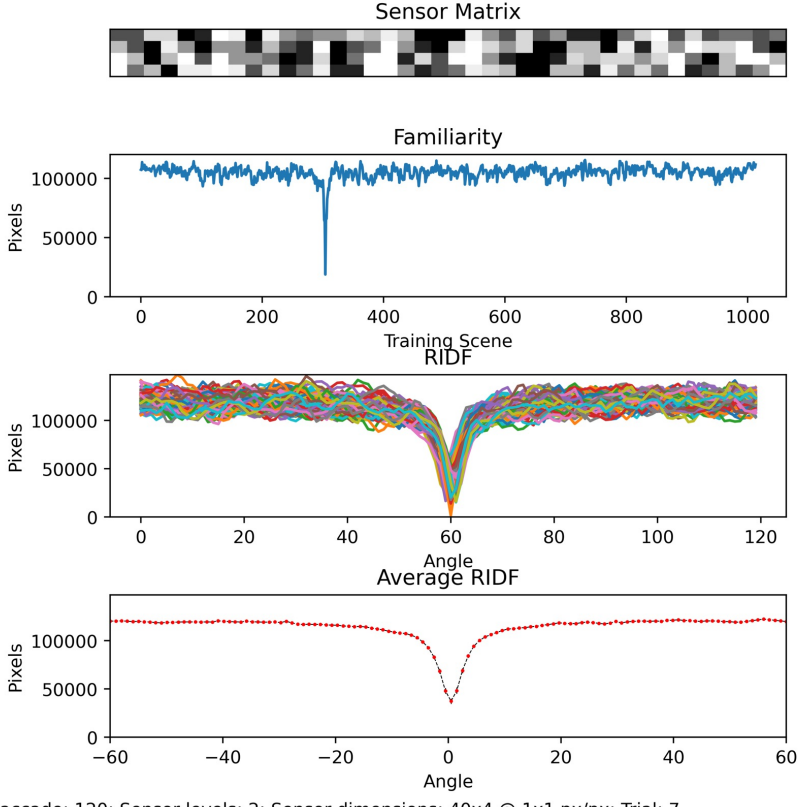




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 52.93; RMSD/dist: 0.132; TD: 57717; p90: 10; p50: 6; complete: 0

100%

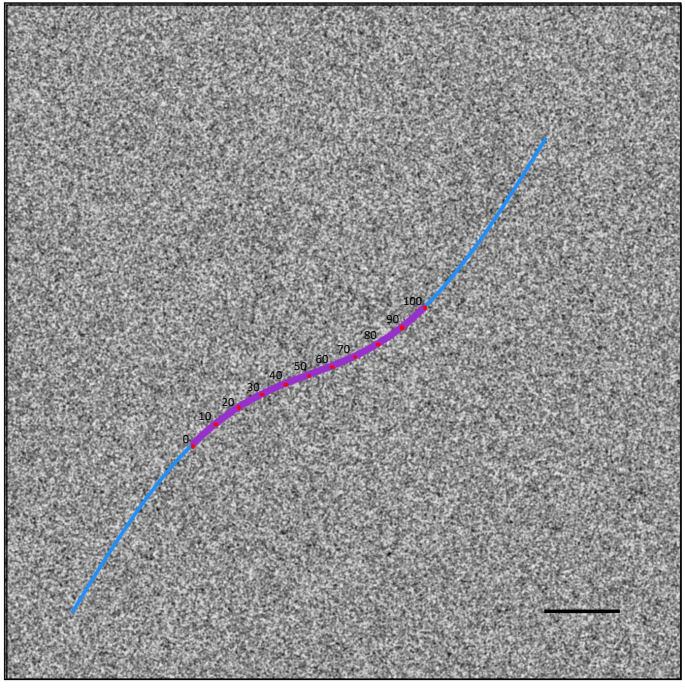


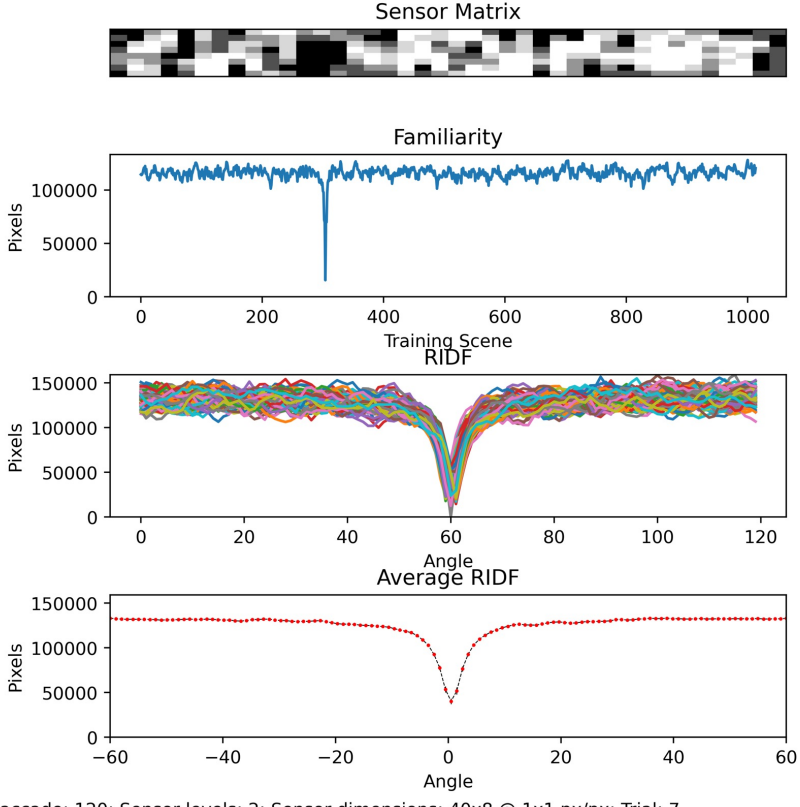


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 58.07; RMSD/dist: 0.145; TD: 66916; p90: 10; p50: 4; complete: 0

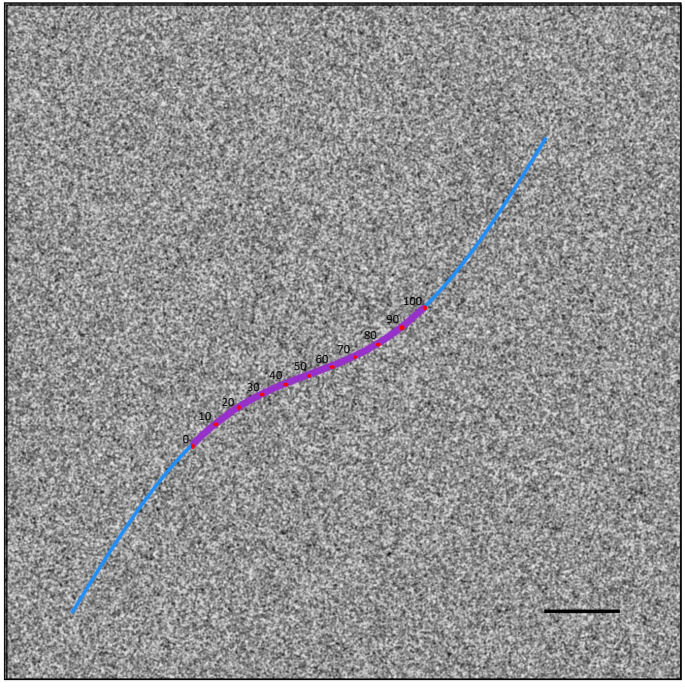
100%

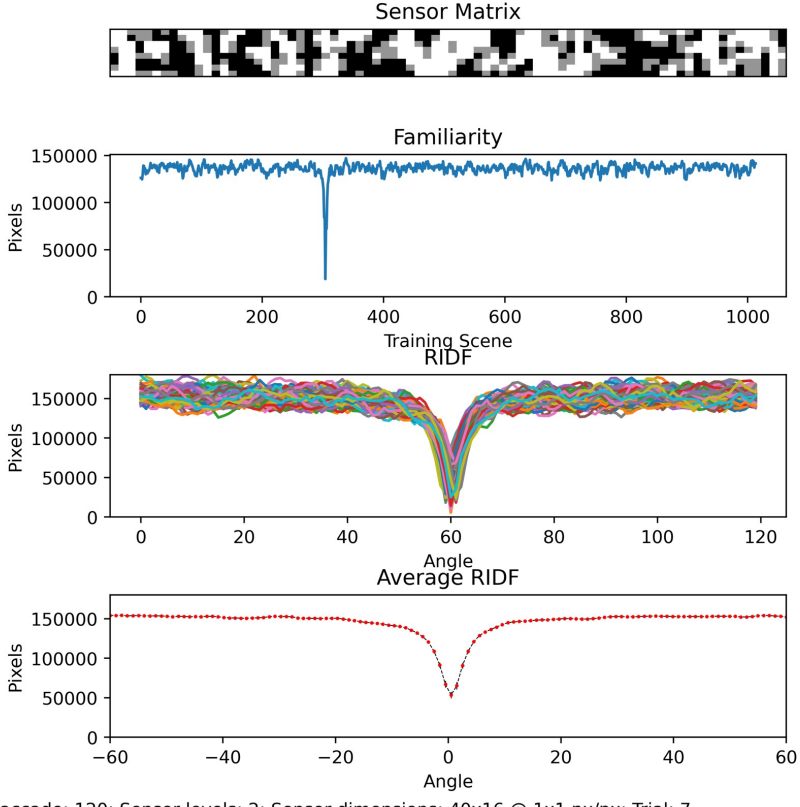




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 43.39; RMSD/dist: 0.108; TD: 75241; p90: 10; p50: 4; complete: 0

100%

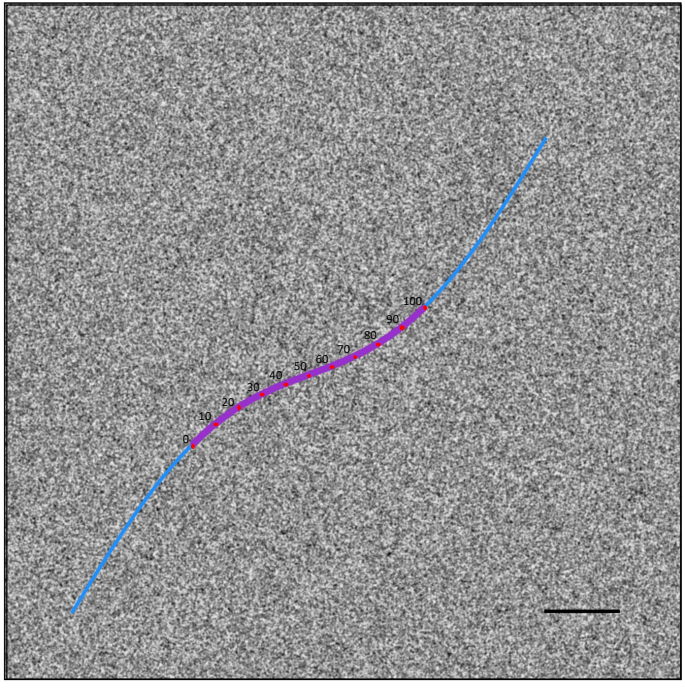


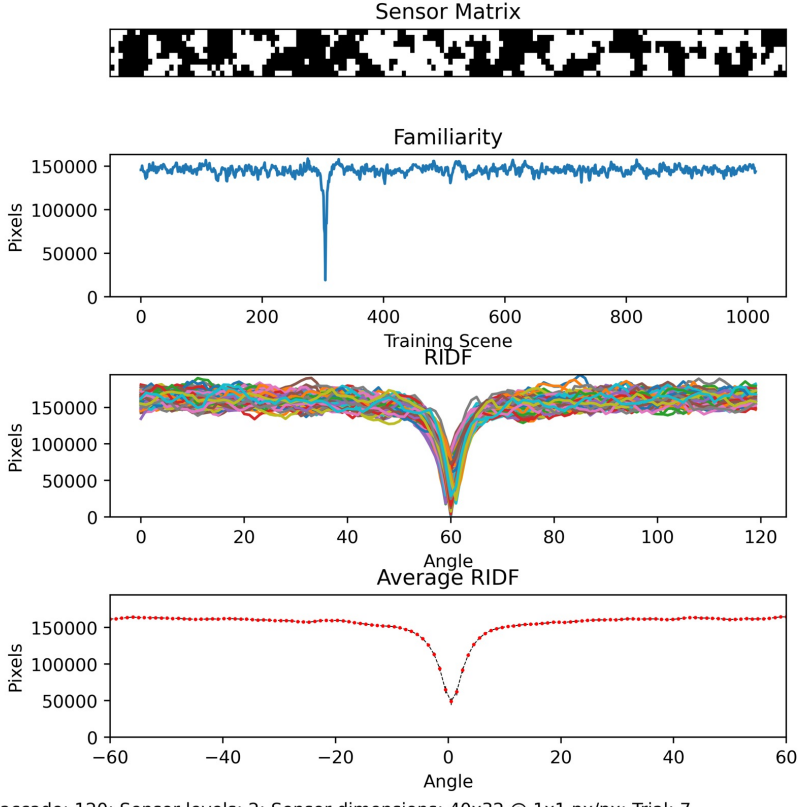


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 53.82; RMSD/dist: 0.135; TD: 82528; p90: 10; p50: 4; complete: 0

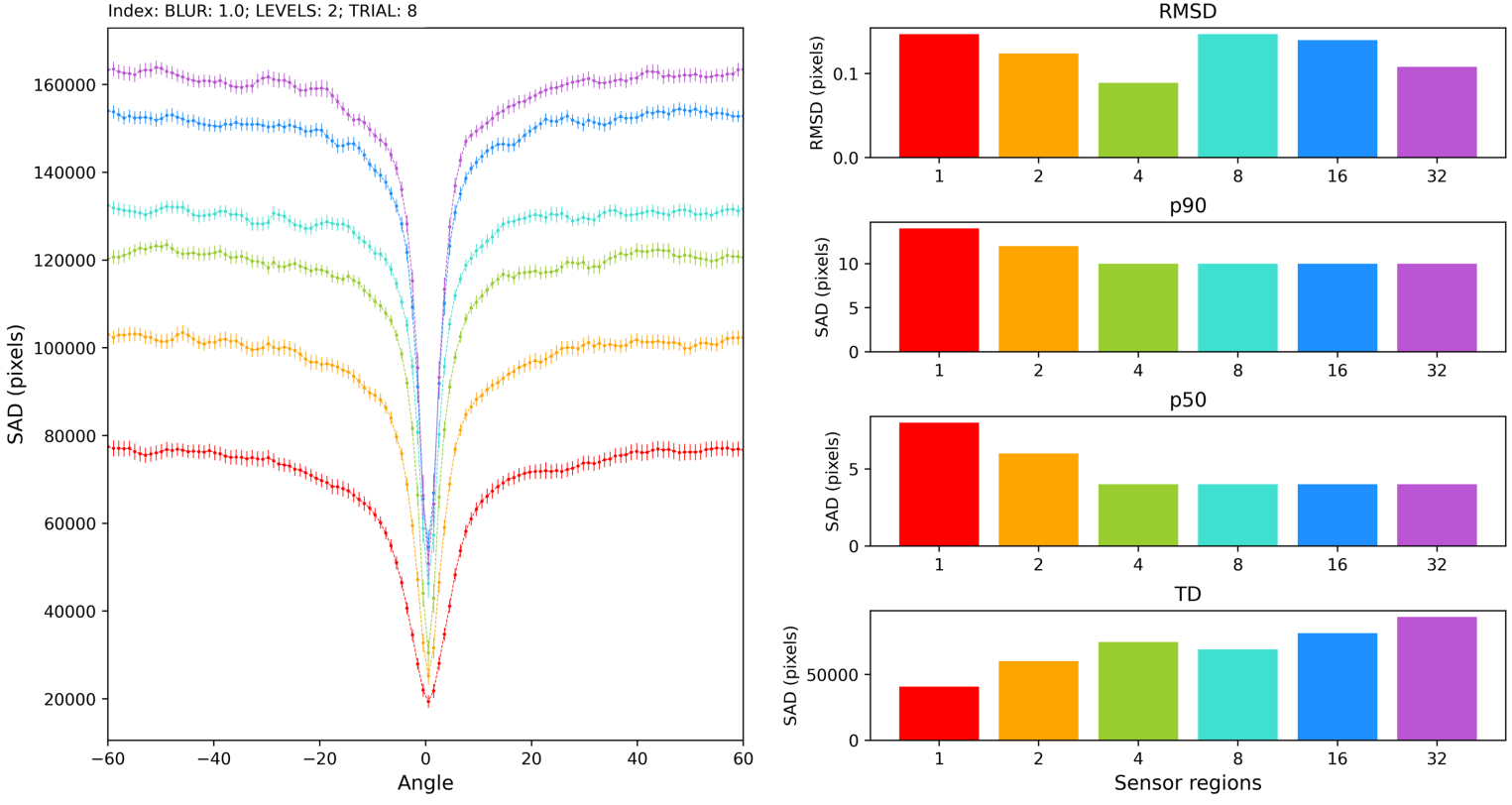
100%



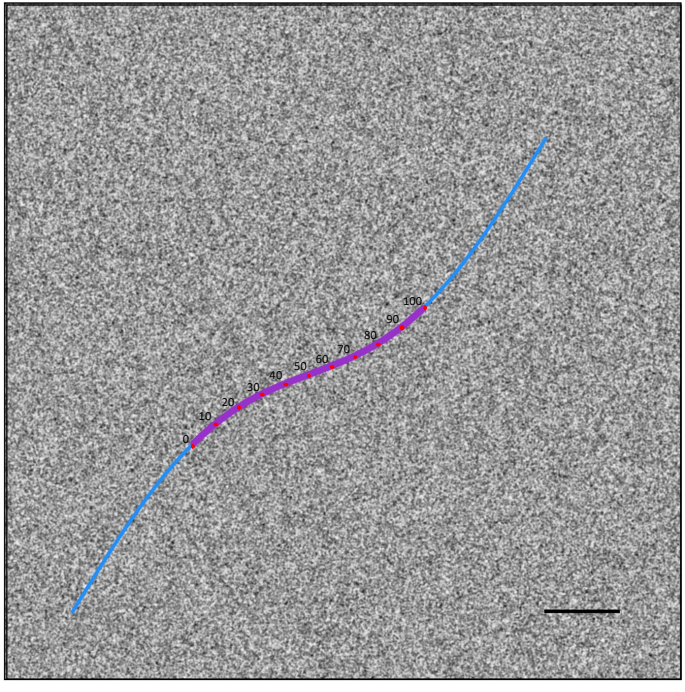


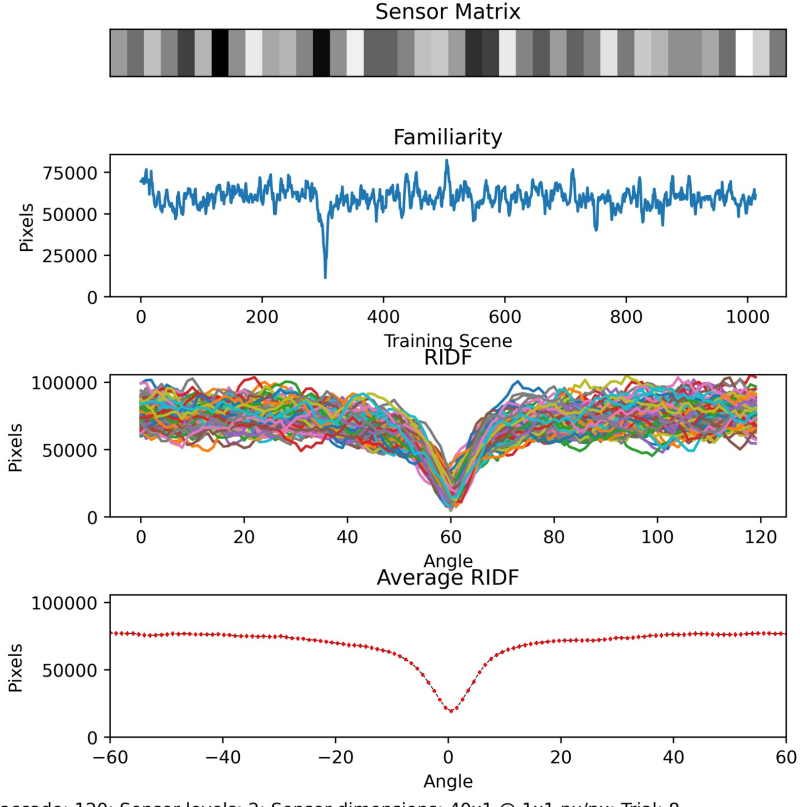
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 42.90; RMSD/dist: 0.107; TD: 95760; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 8
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
50000
0
Sensor regions

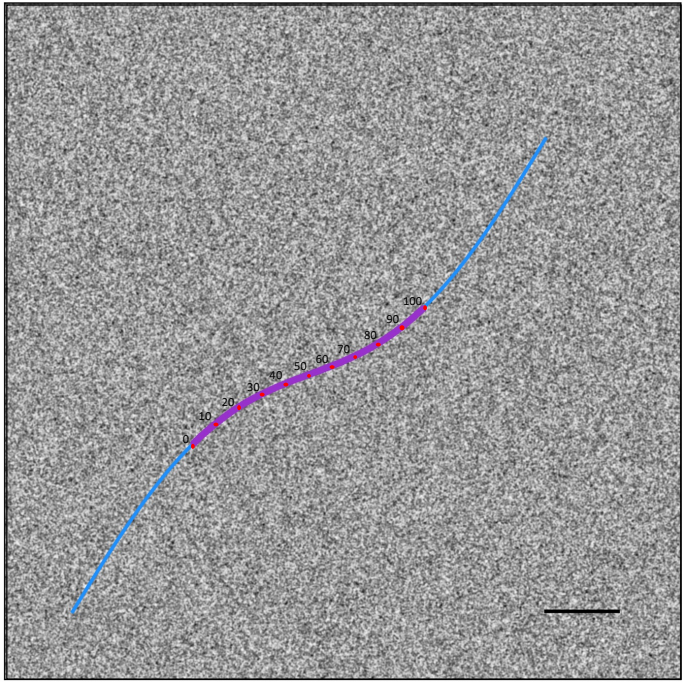
100%

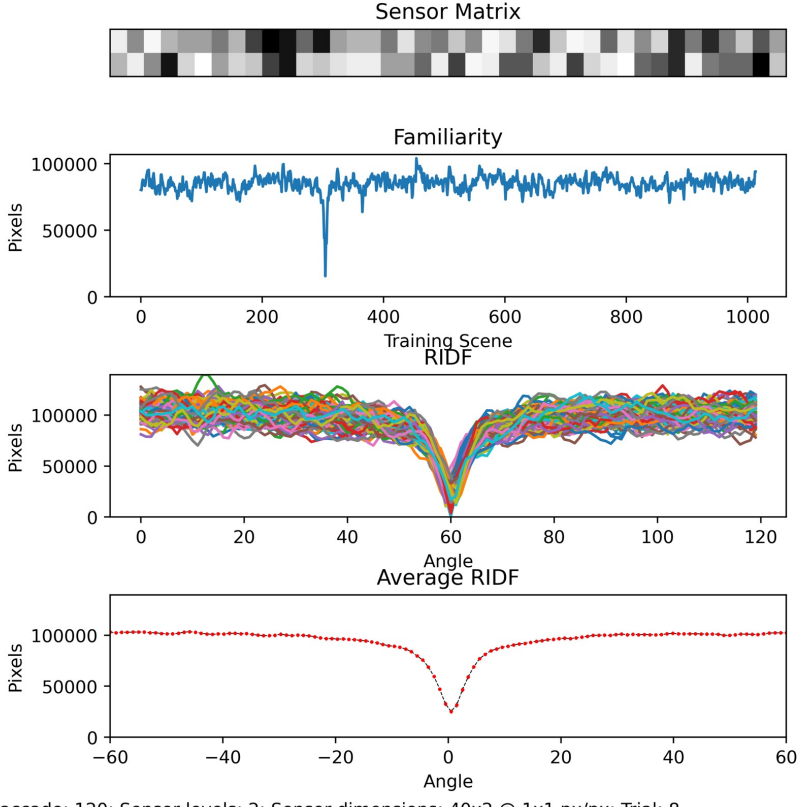




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 58.73; RMSD/dist: 0.147; TD: 40829; p90: 14; p50: 8; complete: 0

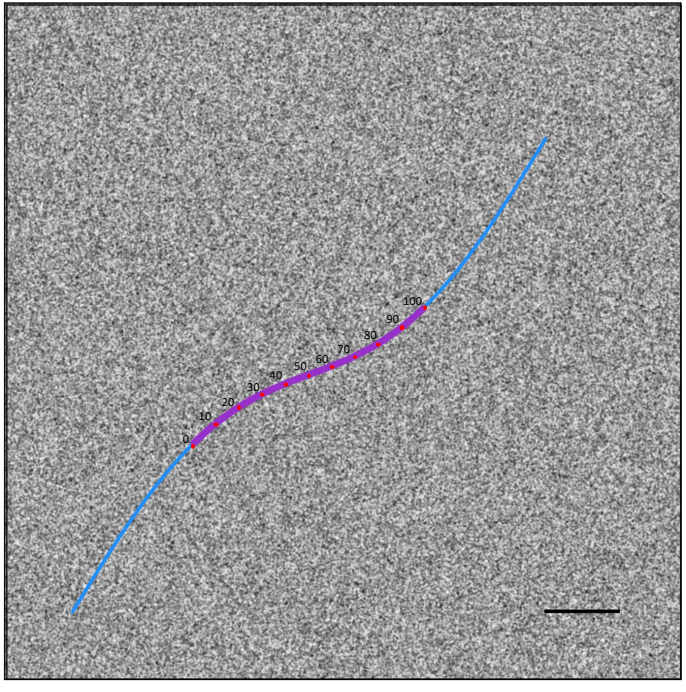
100%

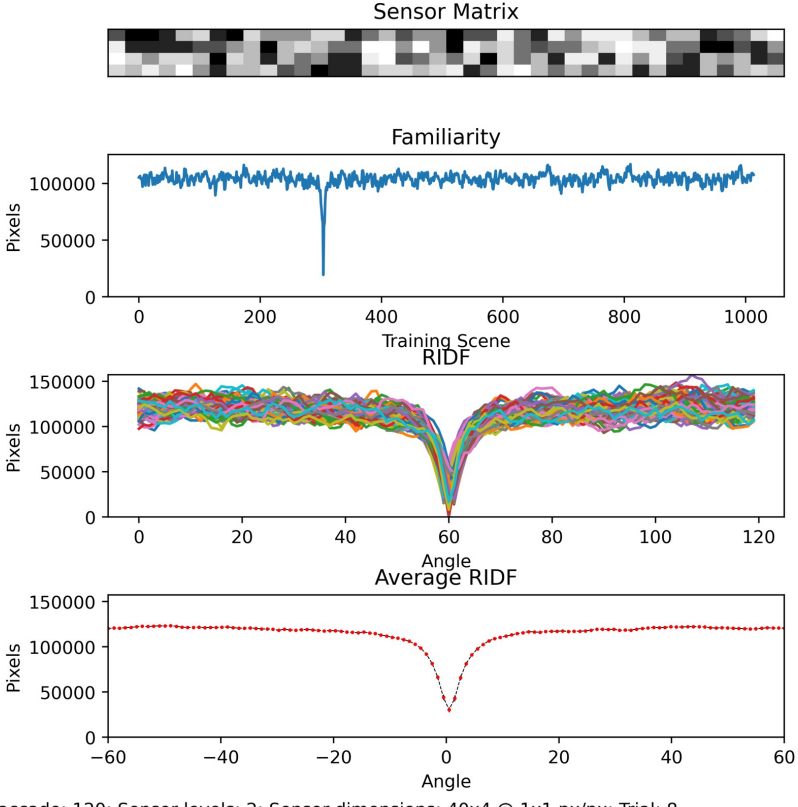




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 49.53; RMSD/dist: 0.124; TD: 60237; p90: 12; p50: 6; complete: 0

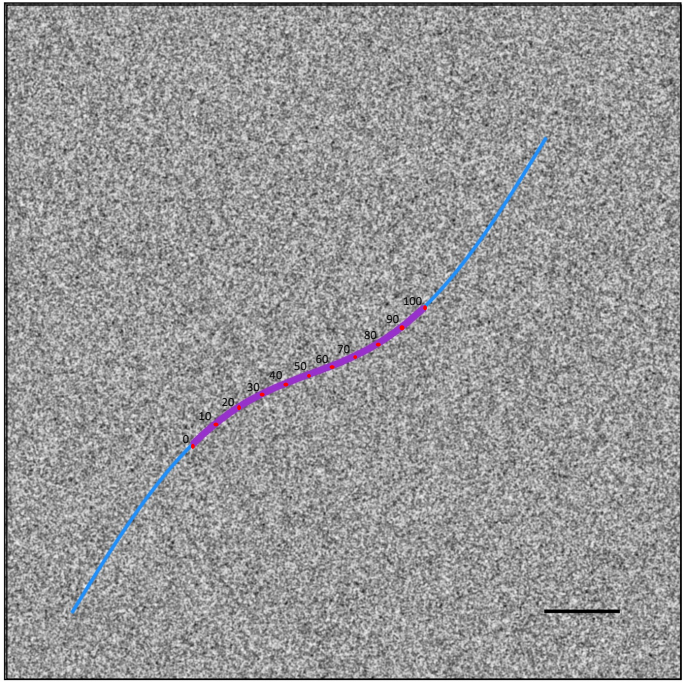
100%

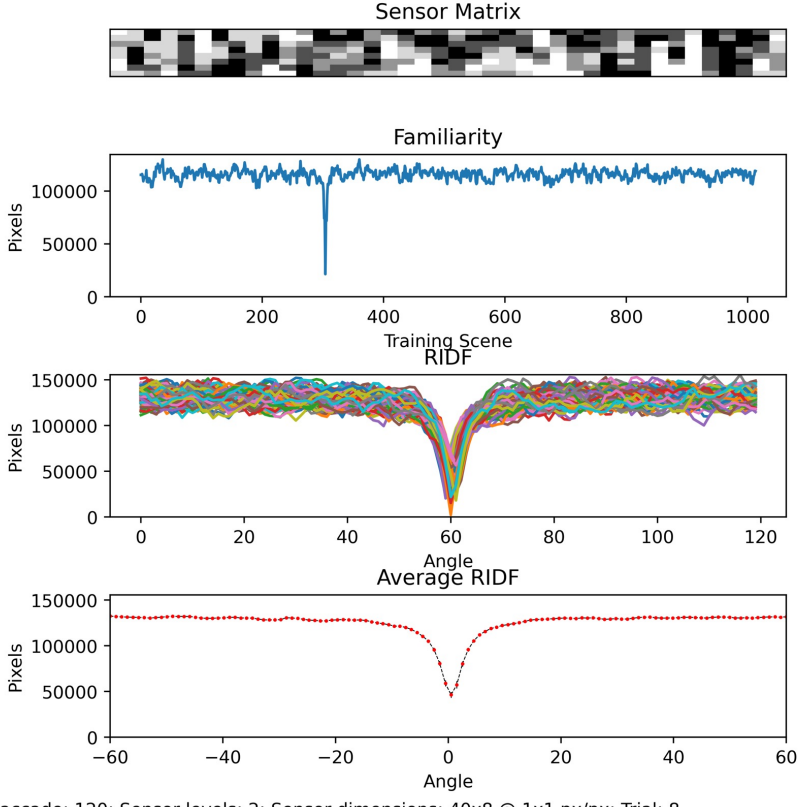




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 35.46; RMSD/dist: 0.089; TD: 74767; p90: 10; p50: 4; complete: 0

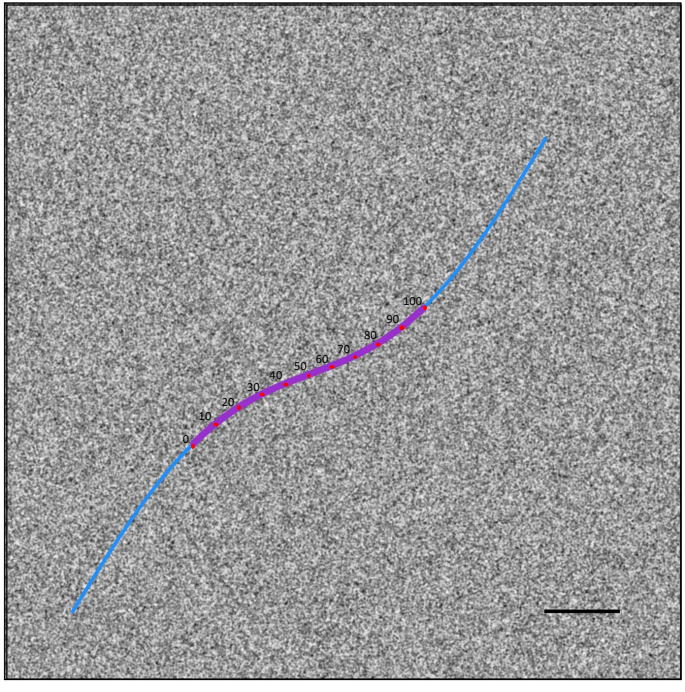
100%

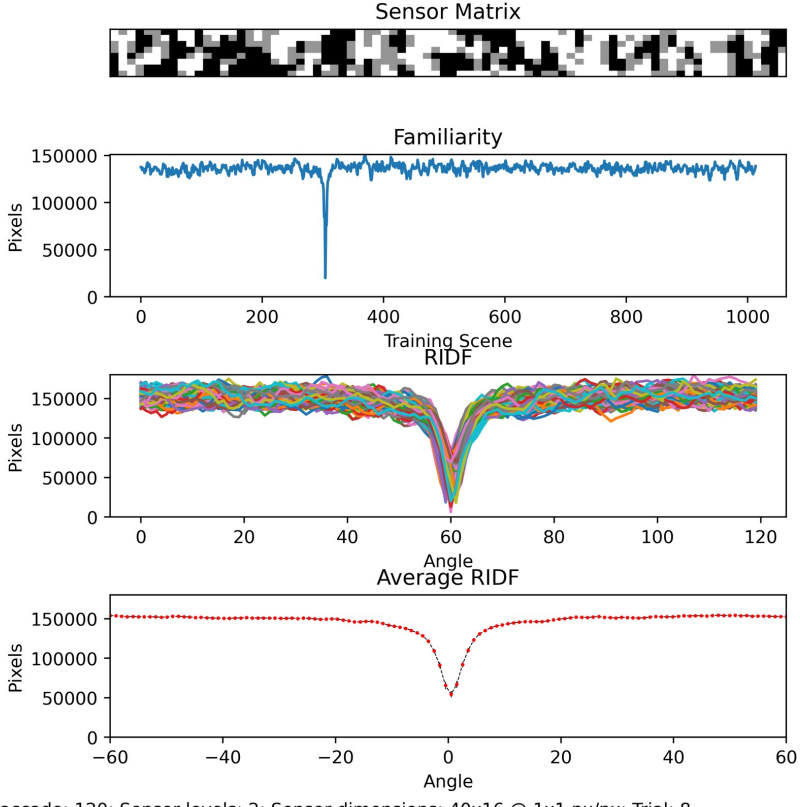




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 58.77; RMSD/dist: 0.147; TD: 69092; p90: 10; p50: 4; complete: 0

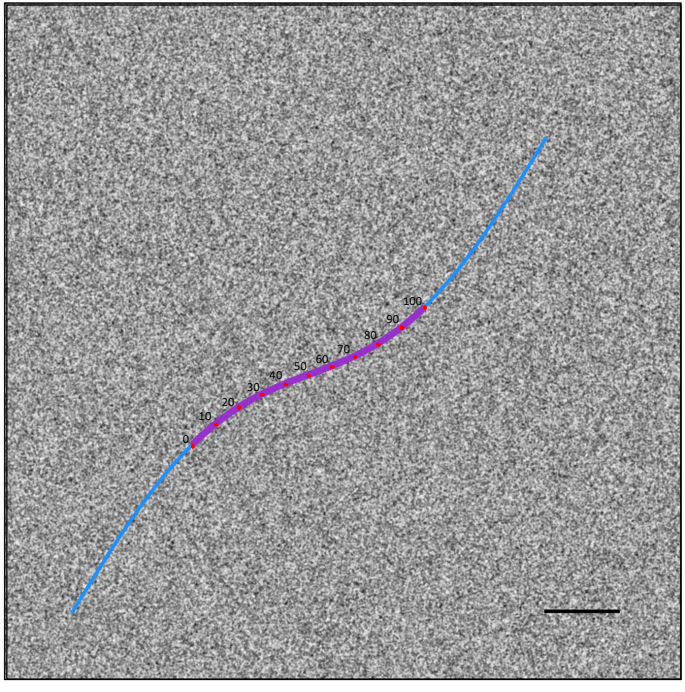
100%

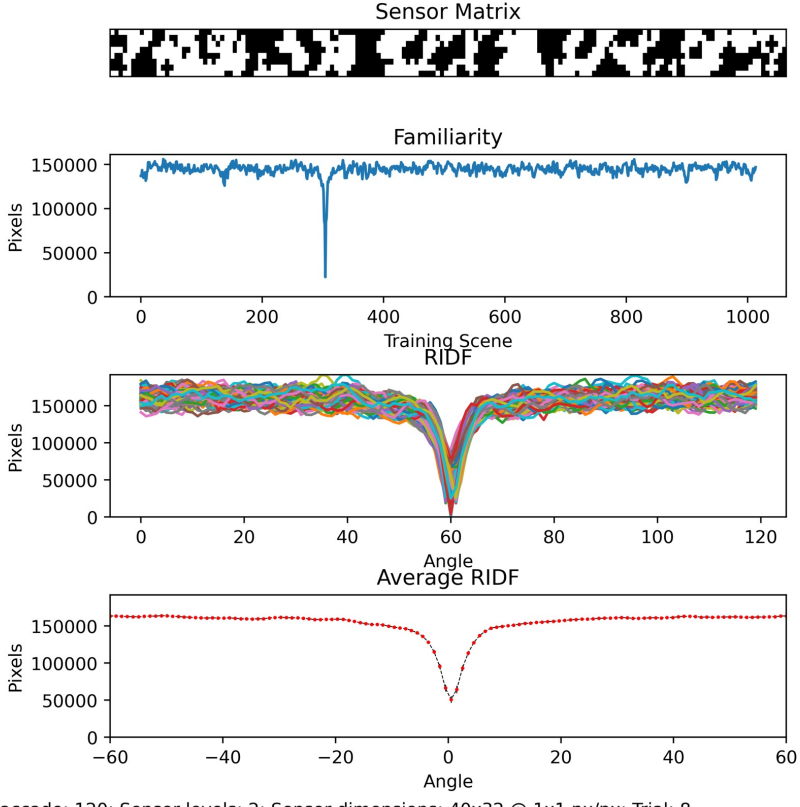




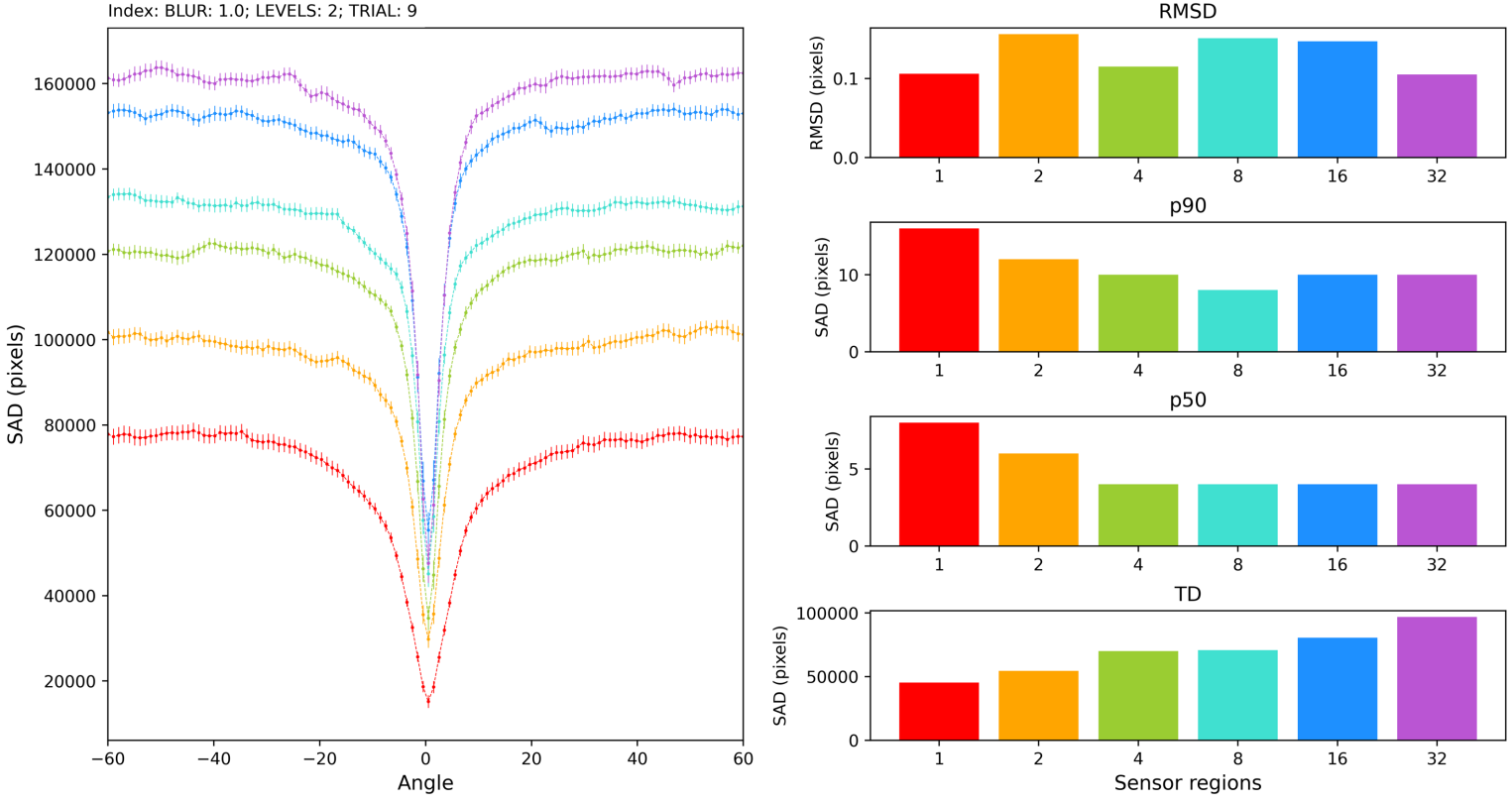
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 56.03; RMSD/dist: 0.140; TD: 81376; p90: 10; p50: 4; complete: 0

100%

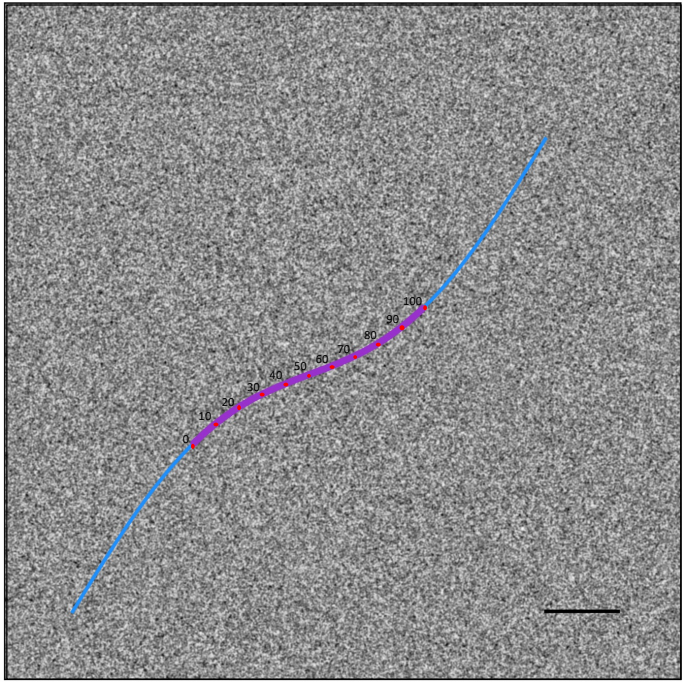


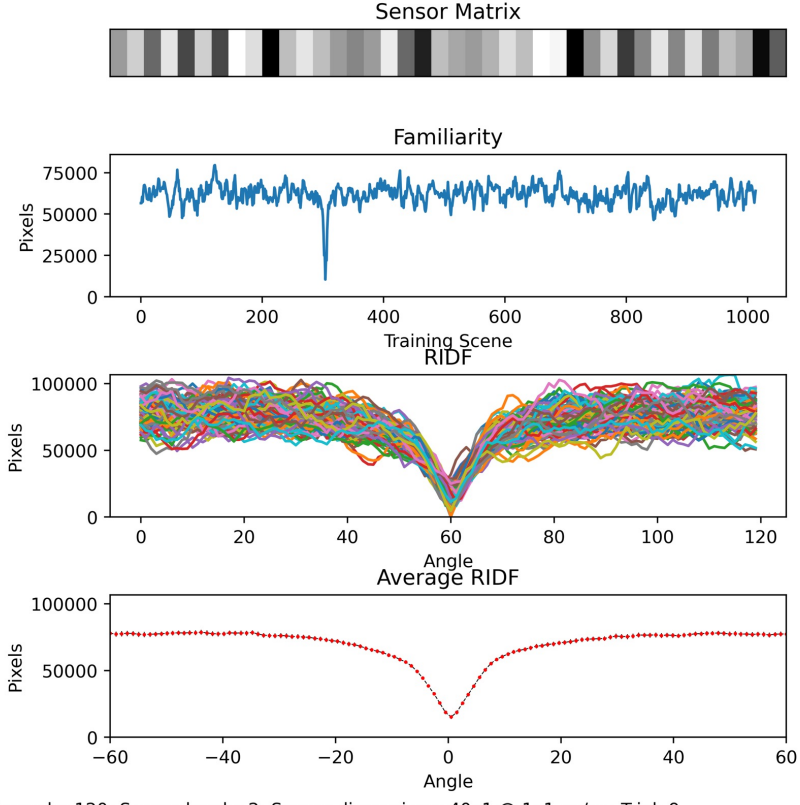


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 43.23; RMSD/dist: 0.108; TD: 93783; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 9
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

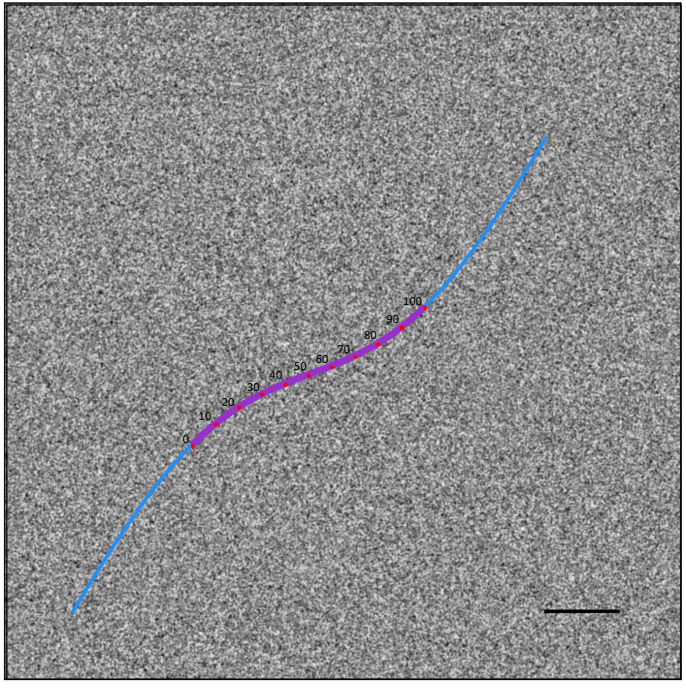
100%

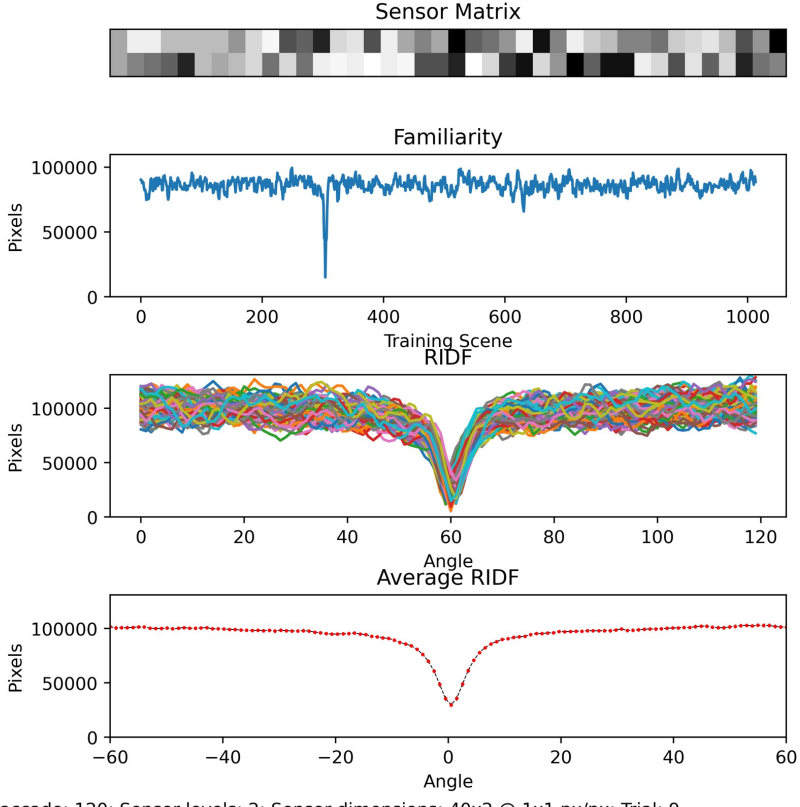




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 42.55; RMSD/dist: 0.106; TD: 45306; p90: 16; p50: 8; complete: 0

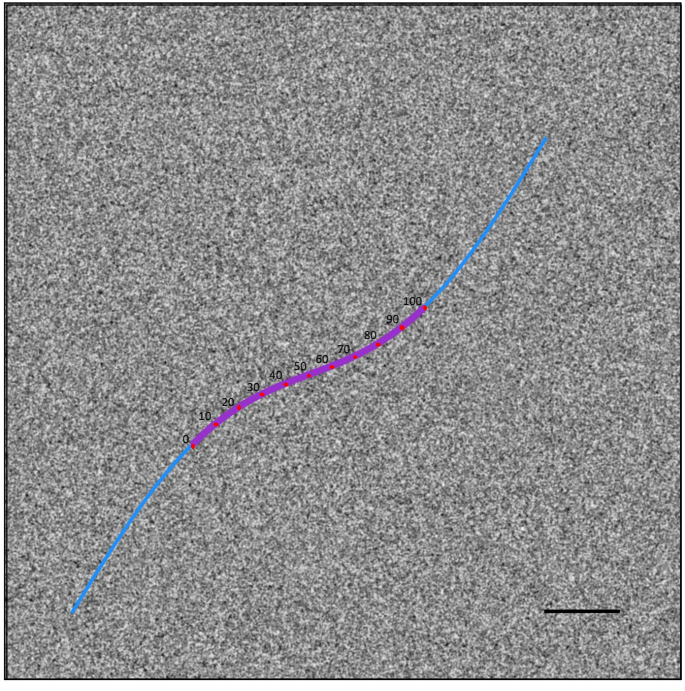
100%

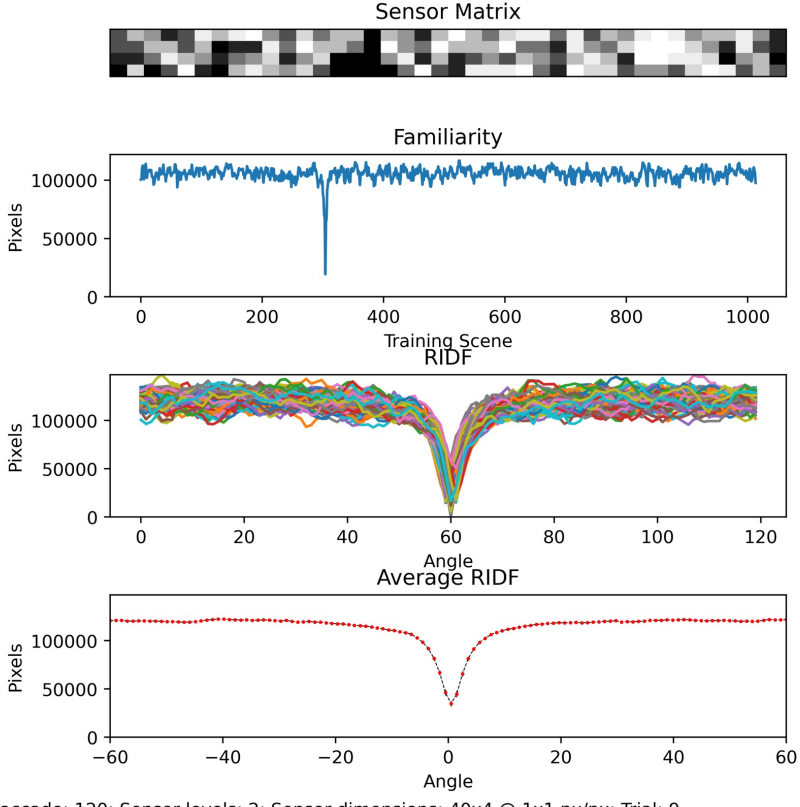




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 62.32; RMSD/dist: 0.156; TD: 54513; p90: 12; p50: 6; complete: 0

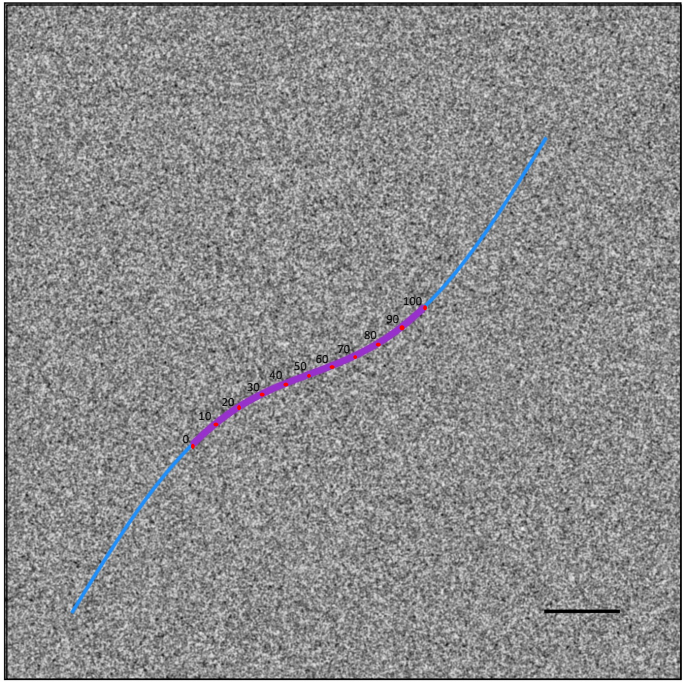
100%

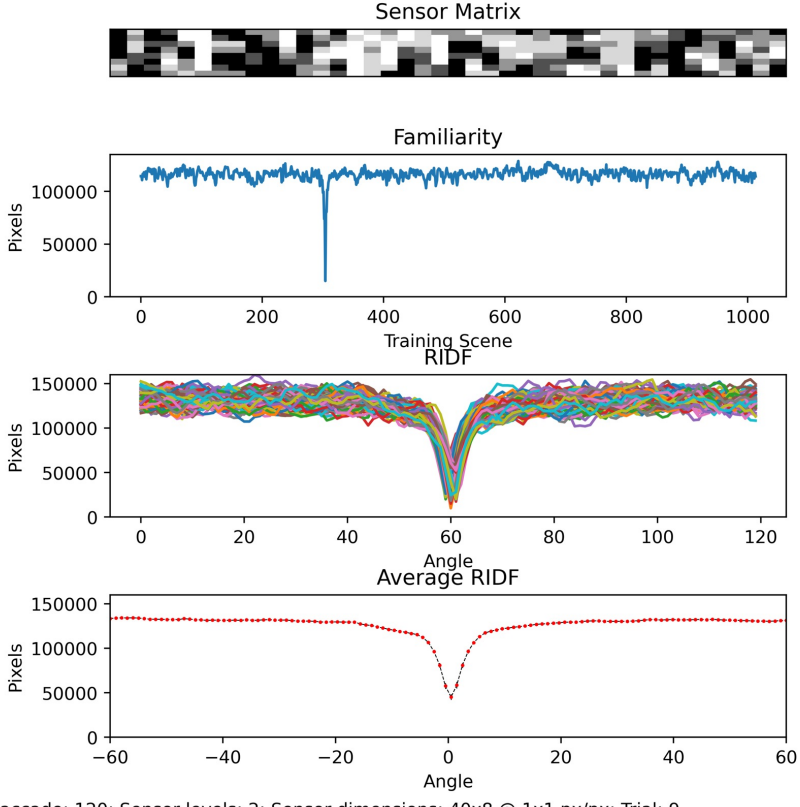




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 46.08; RMSD/dist: 0.115; TD: 69978; p90: 10; p50: 4; complete: 0

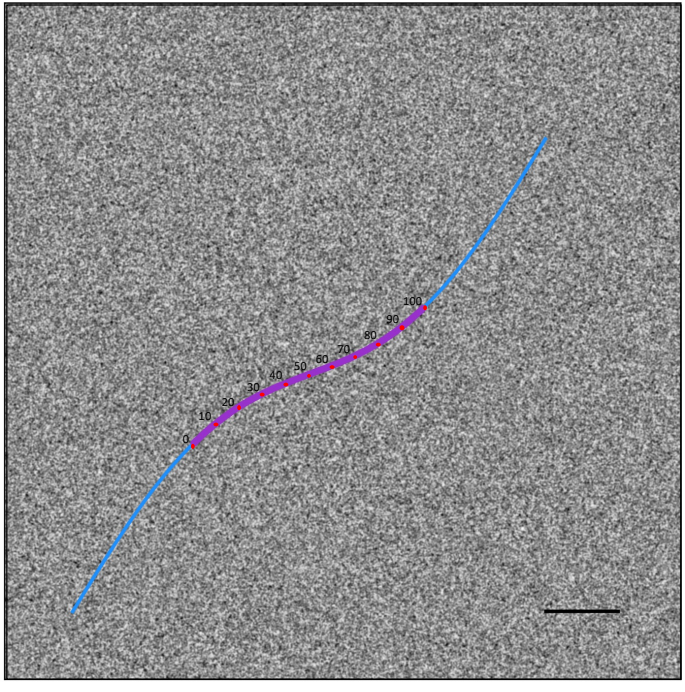
100%

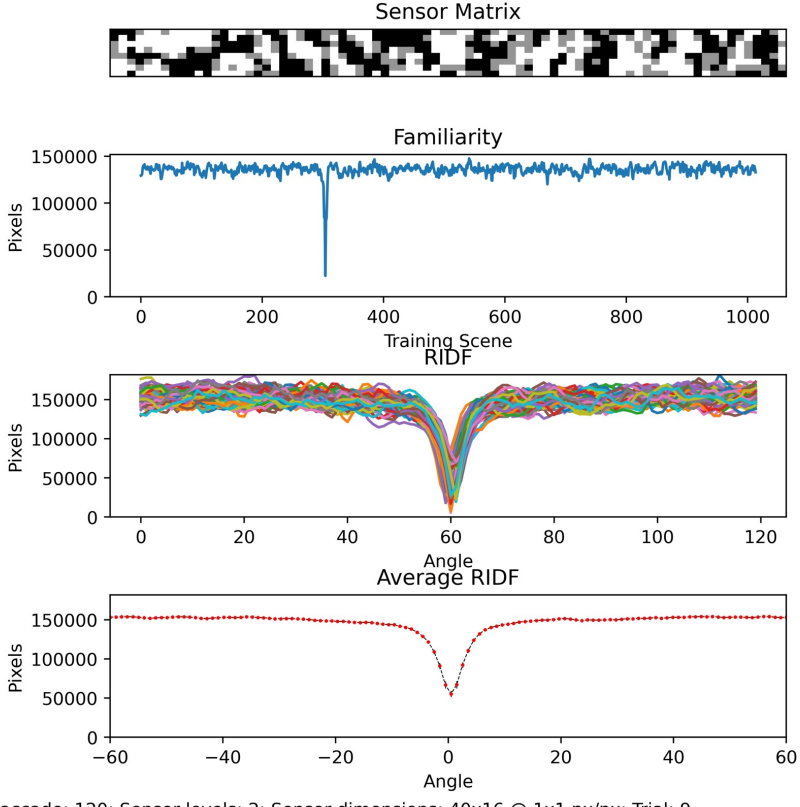




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 60.22; RMSD/dist: 0.151; TD: 70752; p90: 8; p50: 4; complete: 0

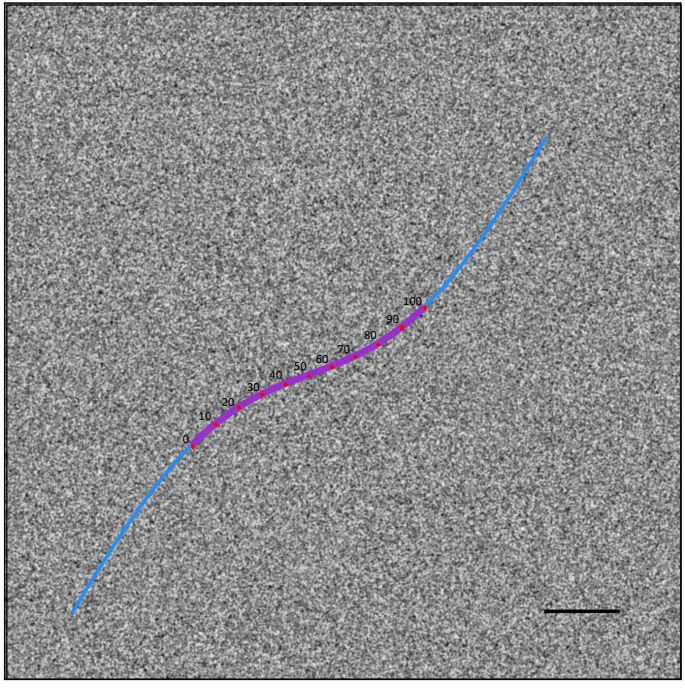
100%

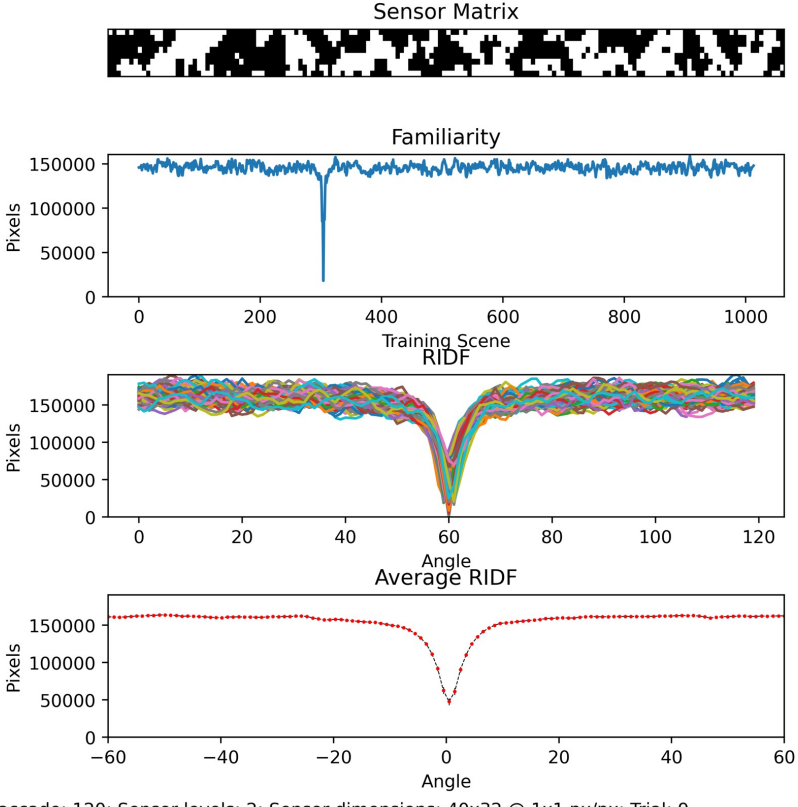




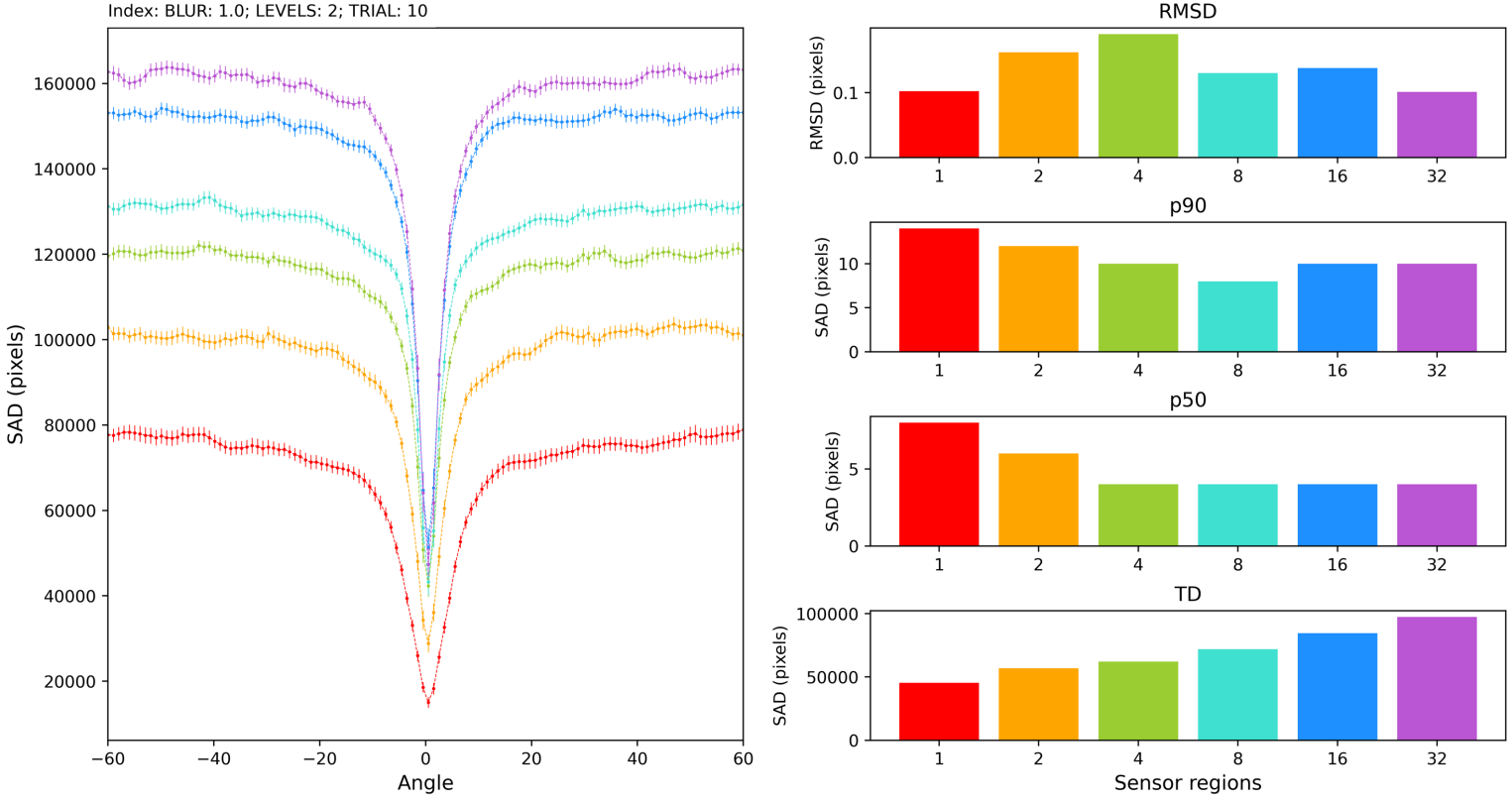
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 58.75; RMSD/dist: 0.147; TD: 80529; p90: 10; p50: 4; complete: 0

100%

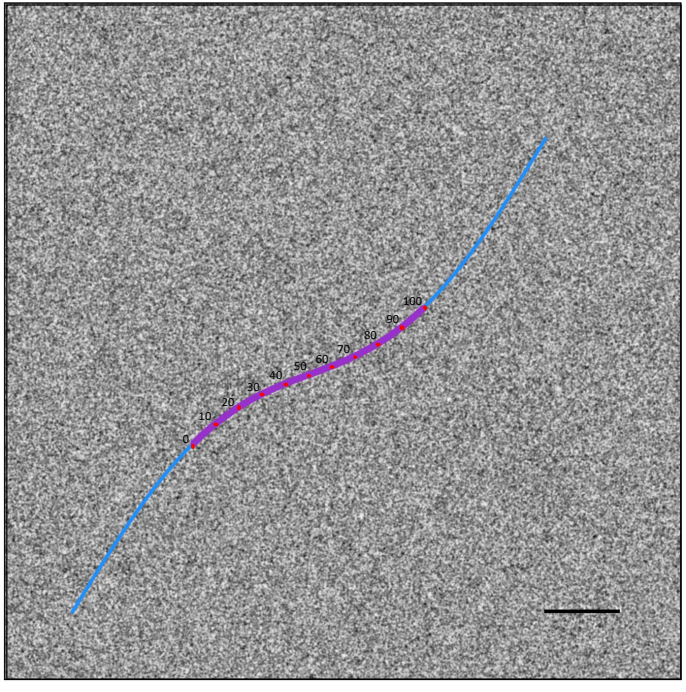


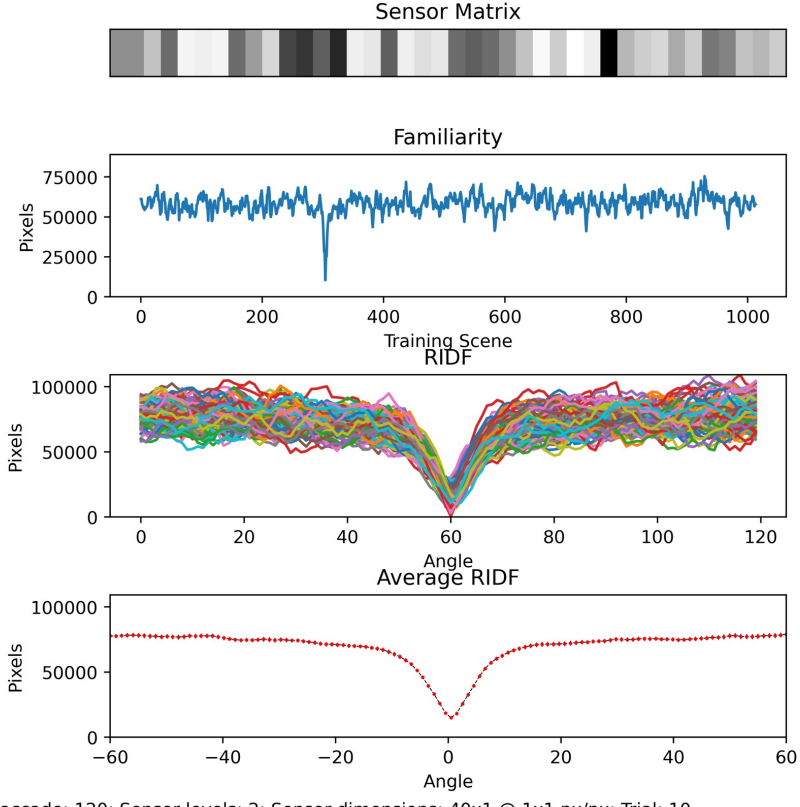


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 42.04; RMSD/dist: 0.105; TD: 96841; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 2; TRIAL: 10
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.0
0.1
1
2
4
8
16
32
p90
SAD (pixels)
0
5
10
p50
TD
100000
50000
Sensor regions

100%

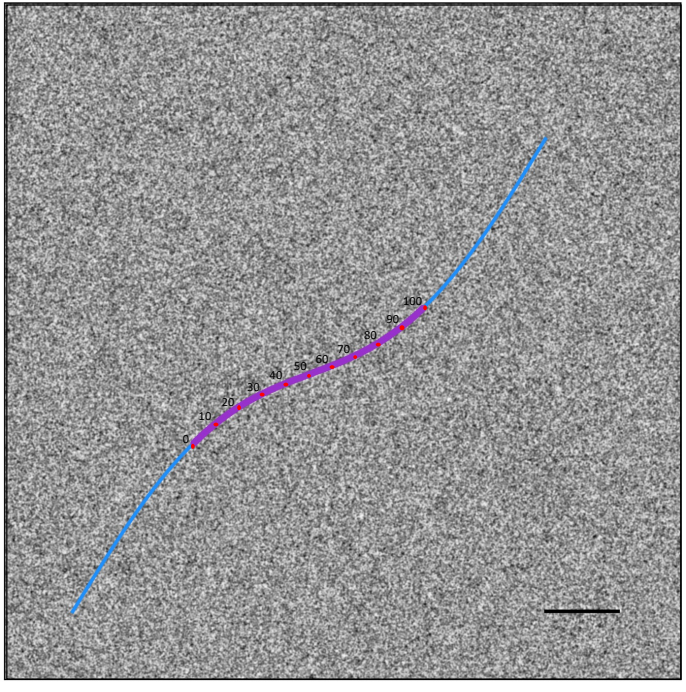


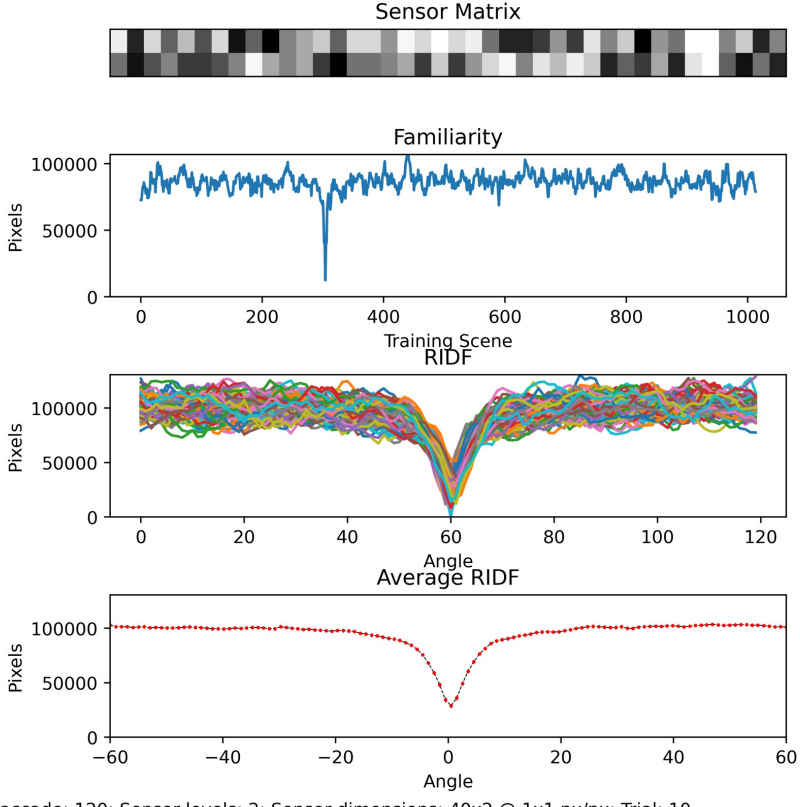


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 40.68; RMSD/dist: 0.102; TD: 45328; p90: 14; p50: 8; complete: 0

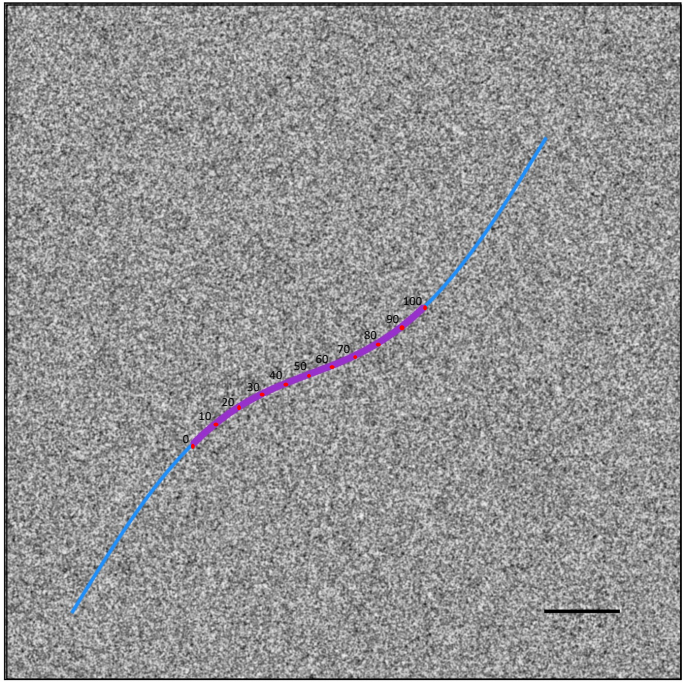
100%

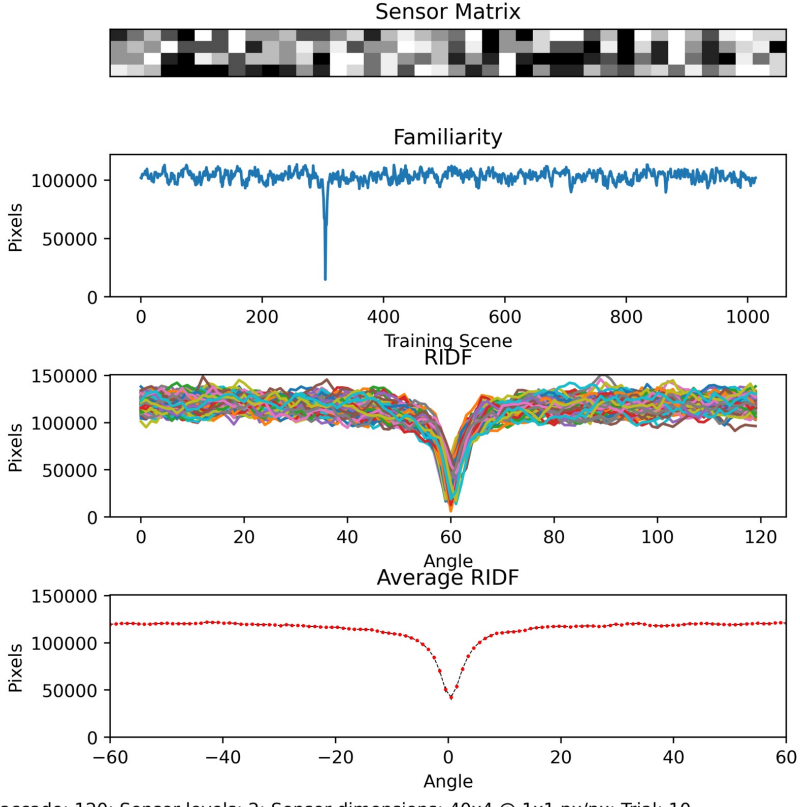




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 64.69; RMSD/dist: 0.162; TD: 56845; p90: 12; p50: 6; complete: 0

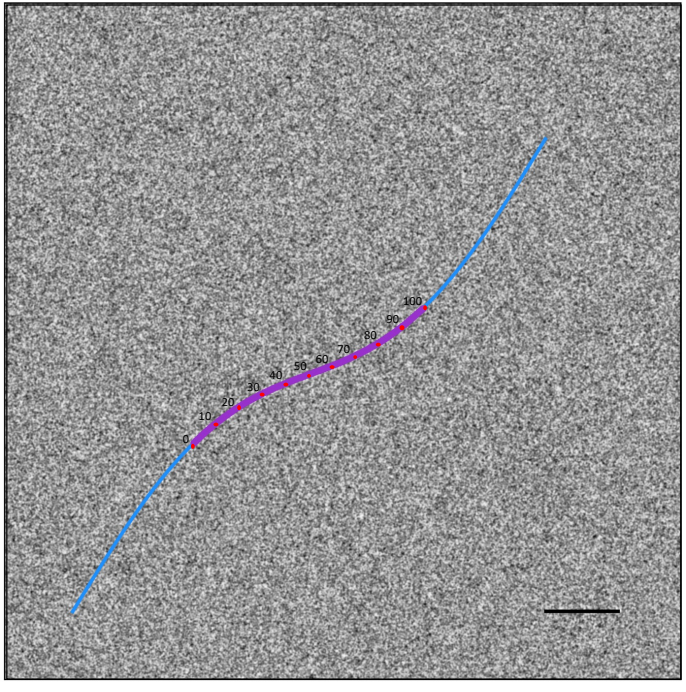
100%

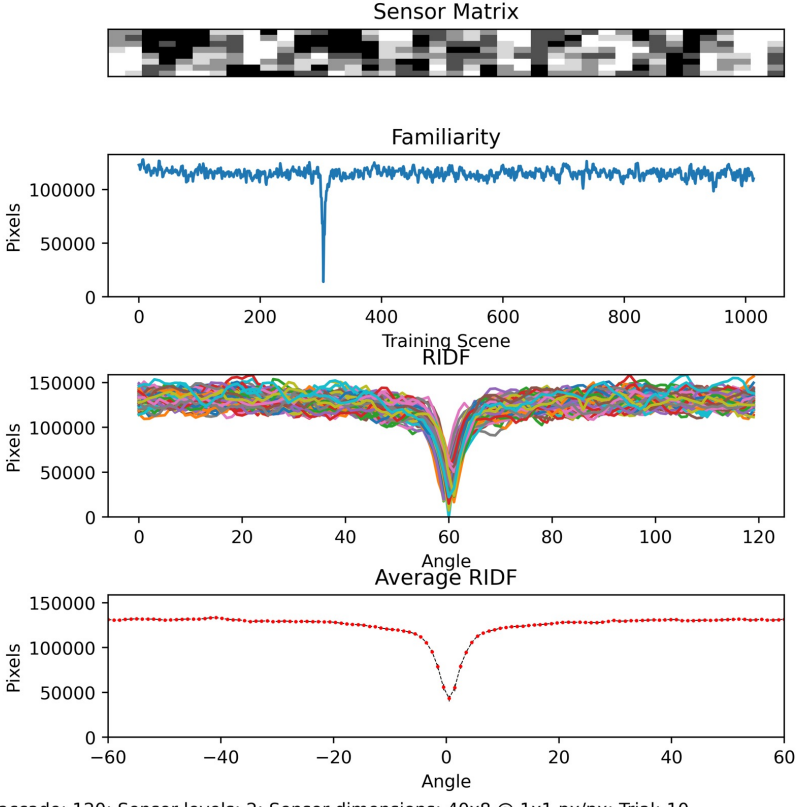




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 76.16; RMSD/dist: 0.190; TD: 62162; p90: 10; p50: 4; complete: 0

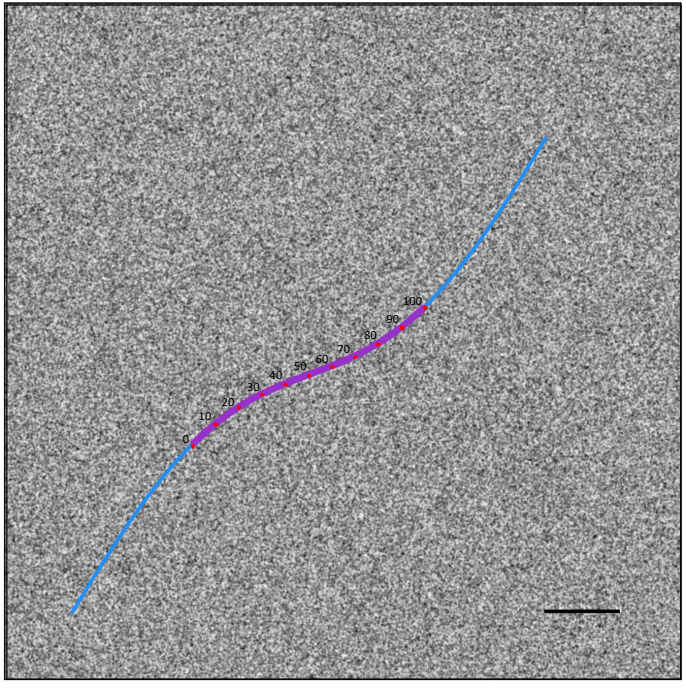
100%

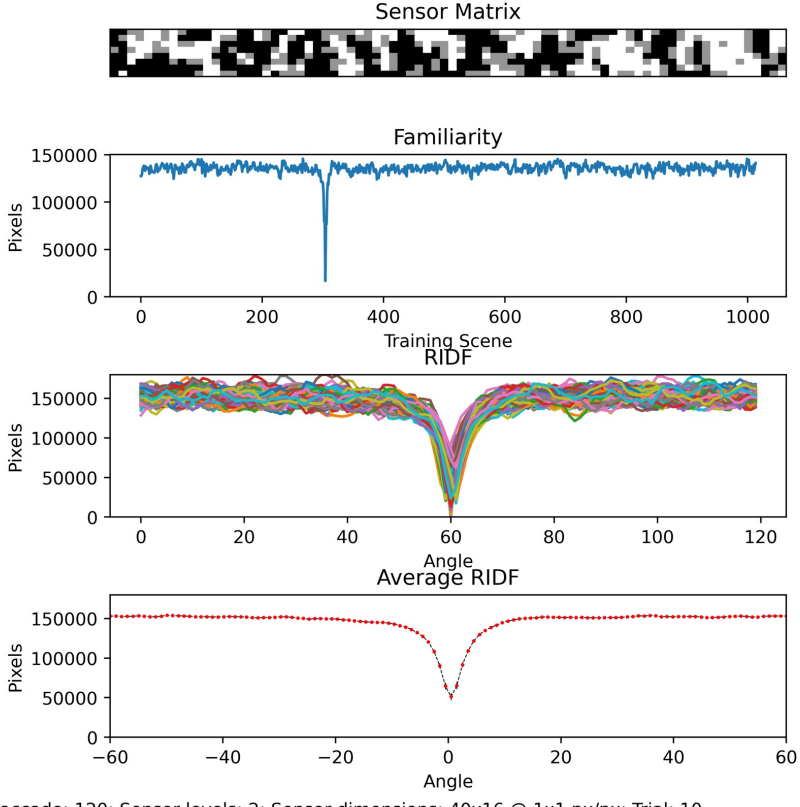




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 52.06; RMSD/dist: 0.130; TD: 71820; p90: 8; p50: 4; complete: 0

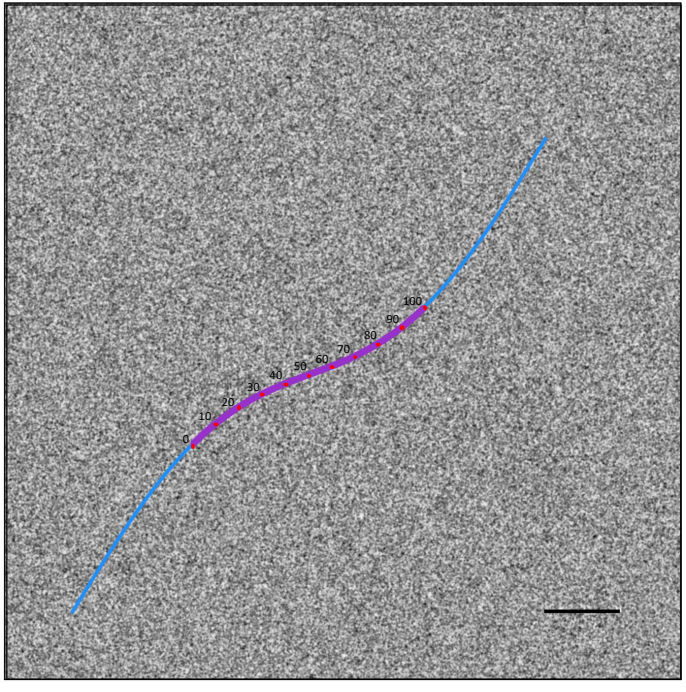
100%

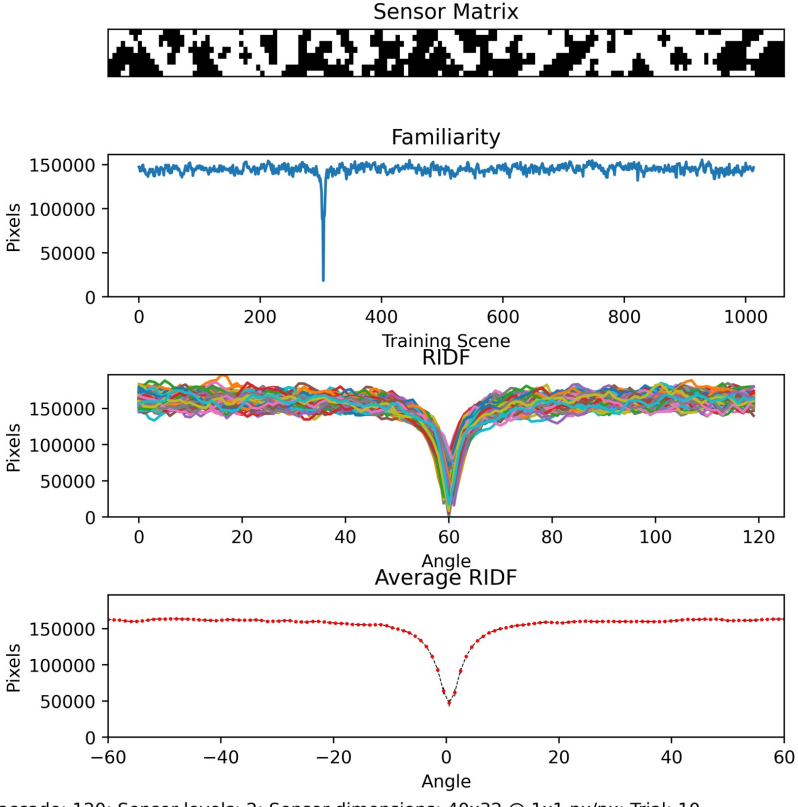




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 55.25; RMSD/dist: 0.138; TD: 84524; p90: 10; p50: 4; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 40.42; RMSD/dist: 0.101; TD: 97362; p90: 10; p50: 4; complete: 0