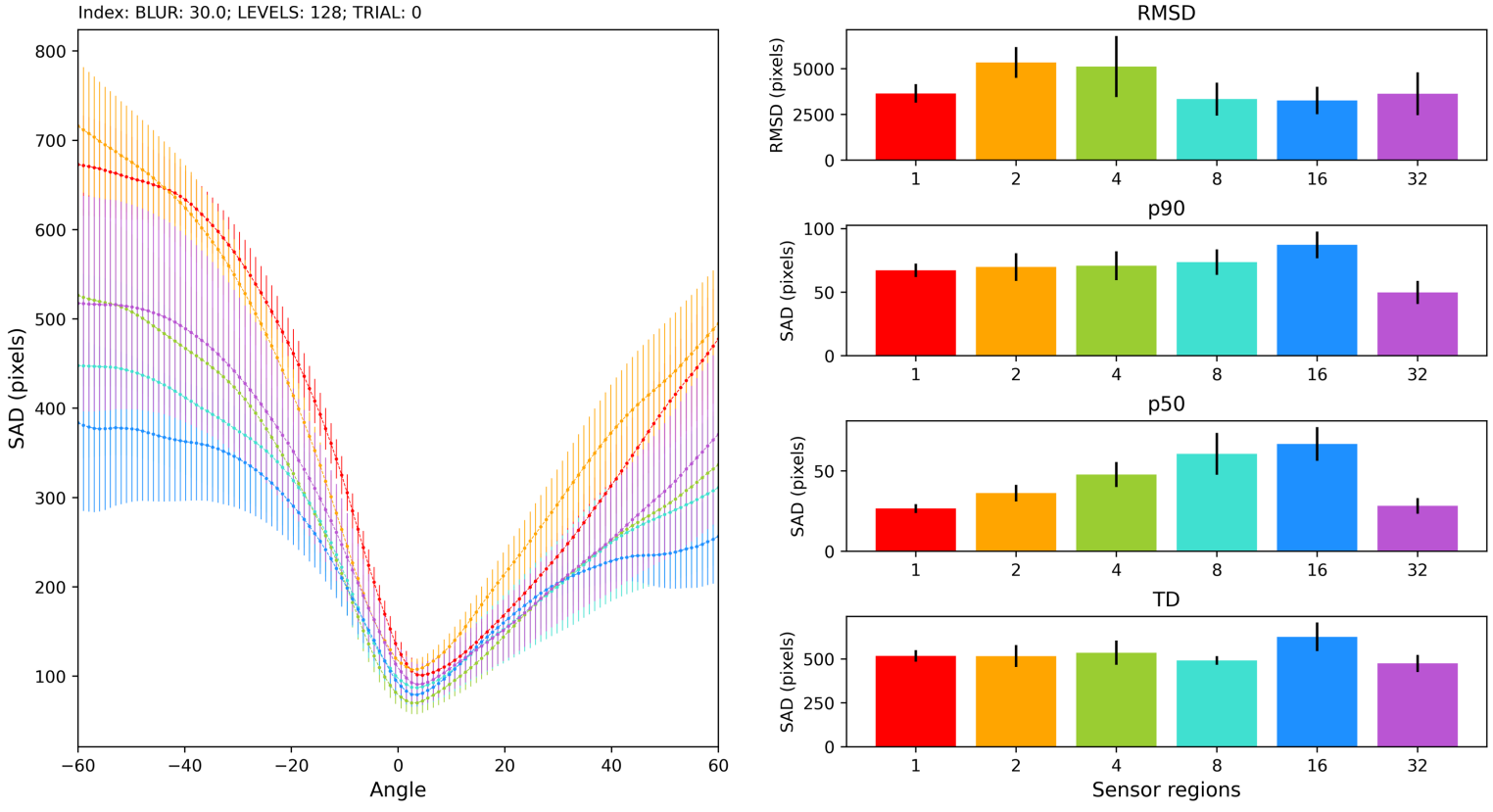
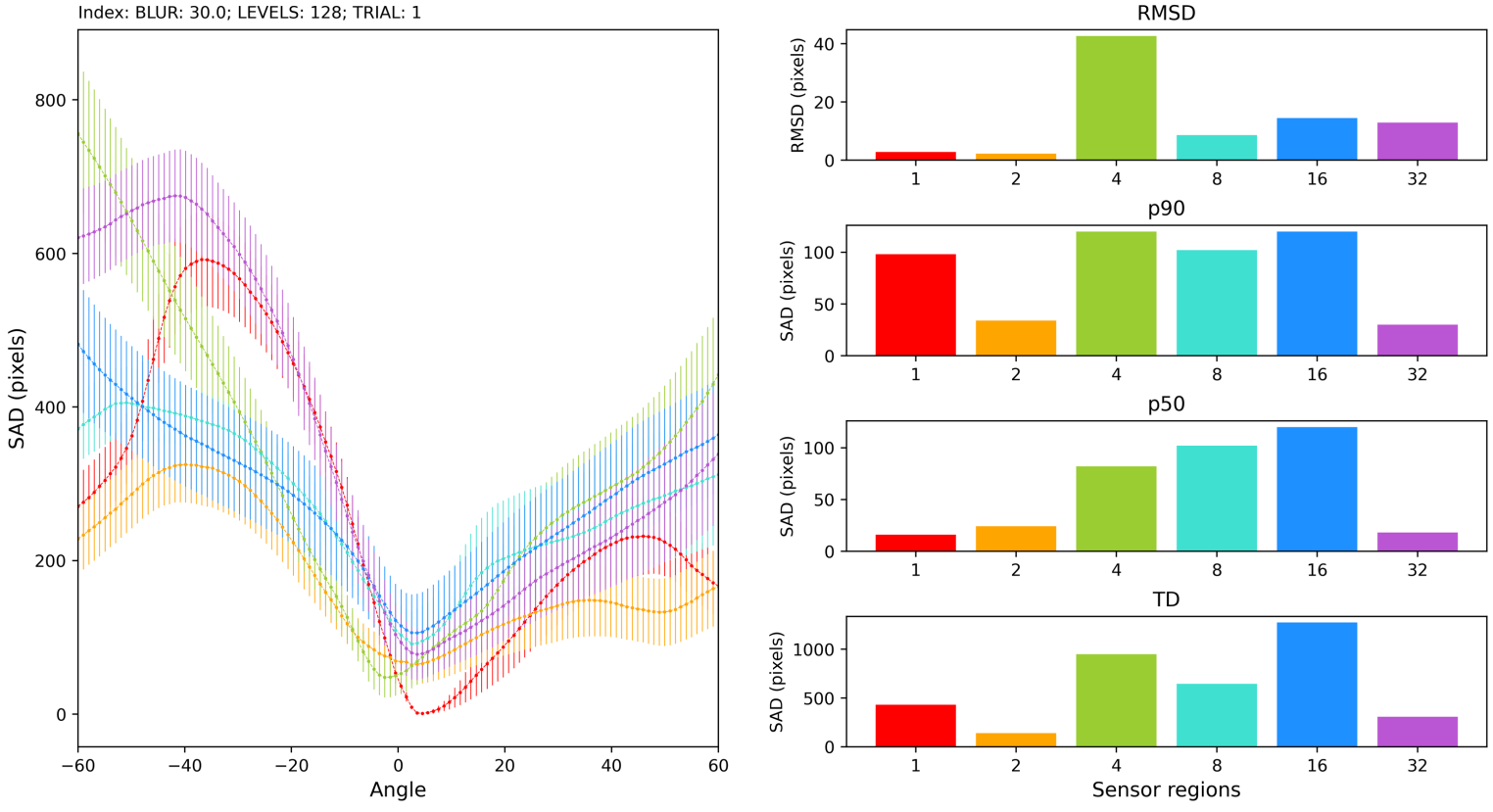

Index: BLUR: 30.0; LEVELS: 128; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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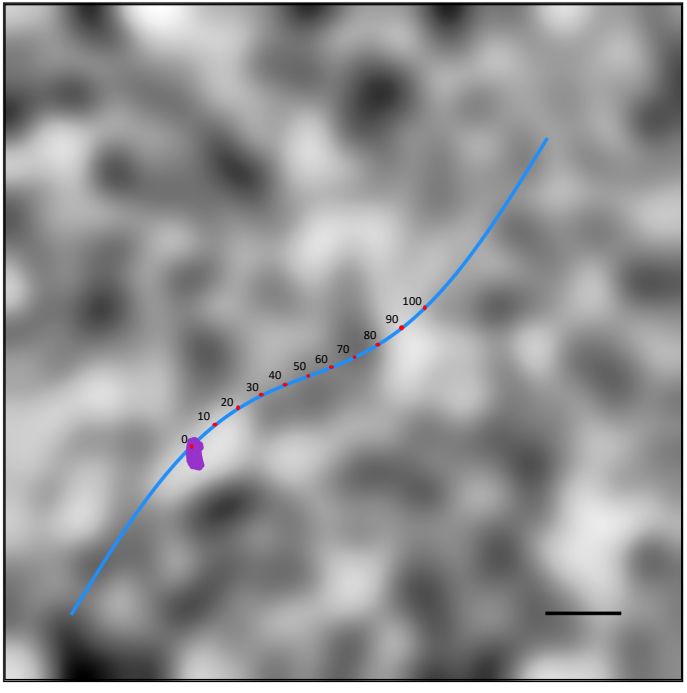
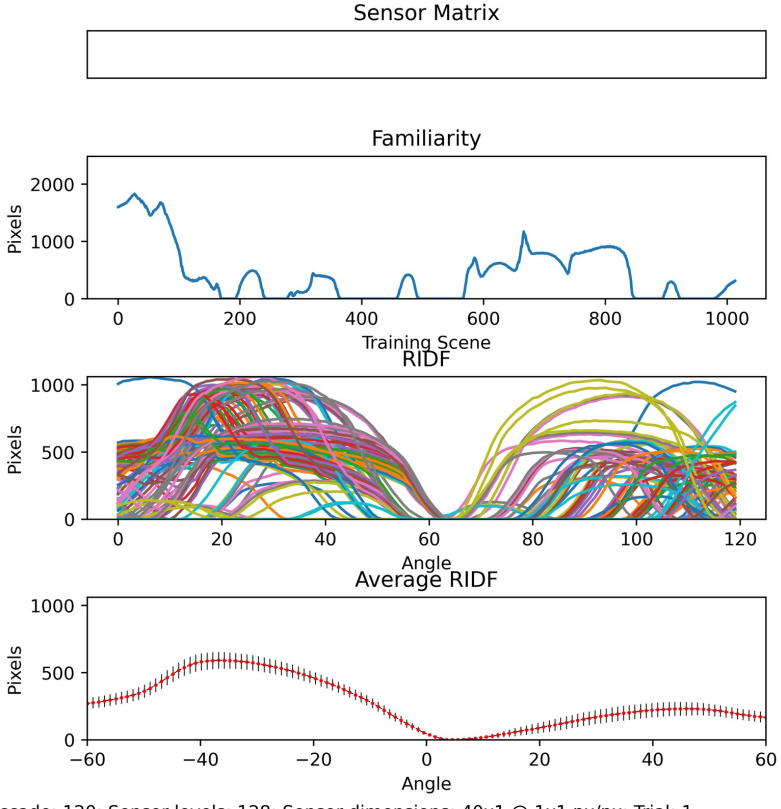
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

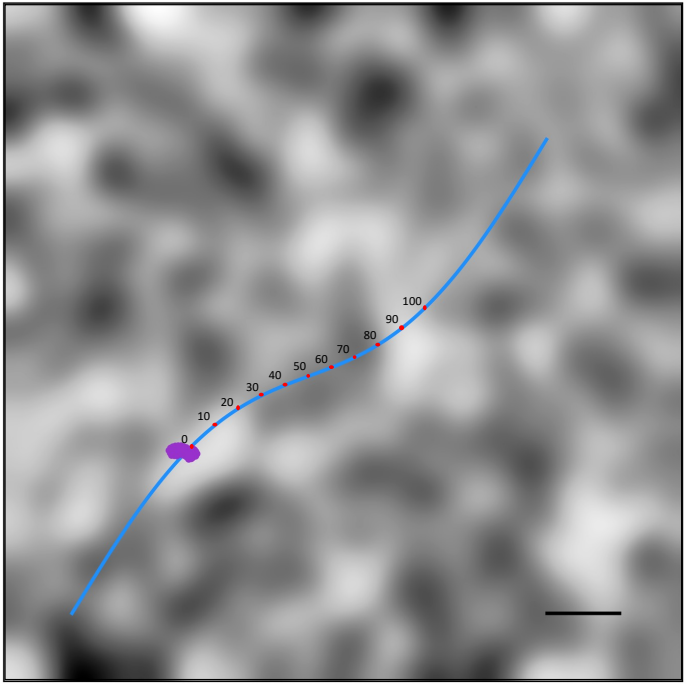
0%

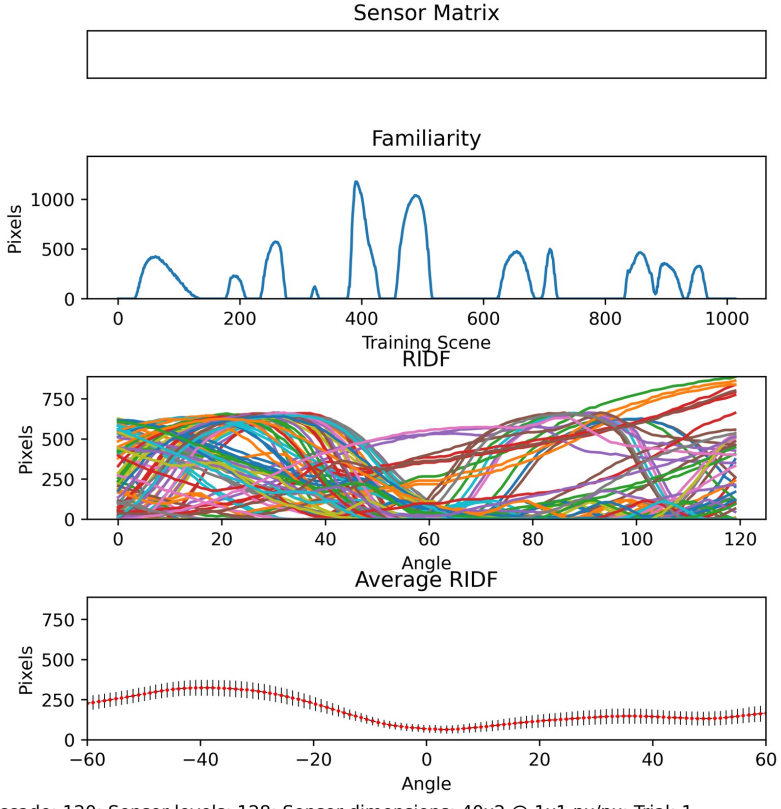




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 1122.14; RMSD/dist: 2.805; TD: 430; p90: 98; p50: 16; complete: 0

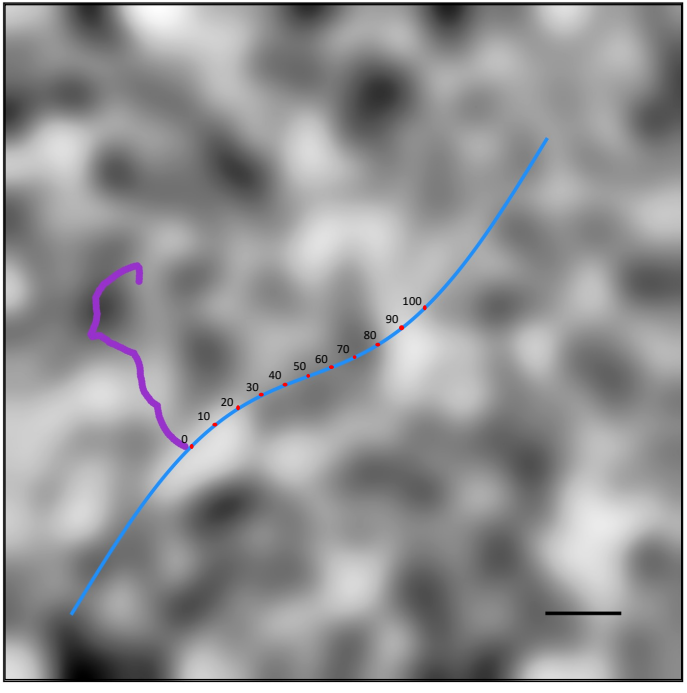
0%

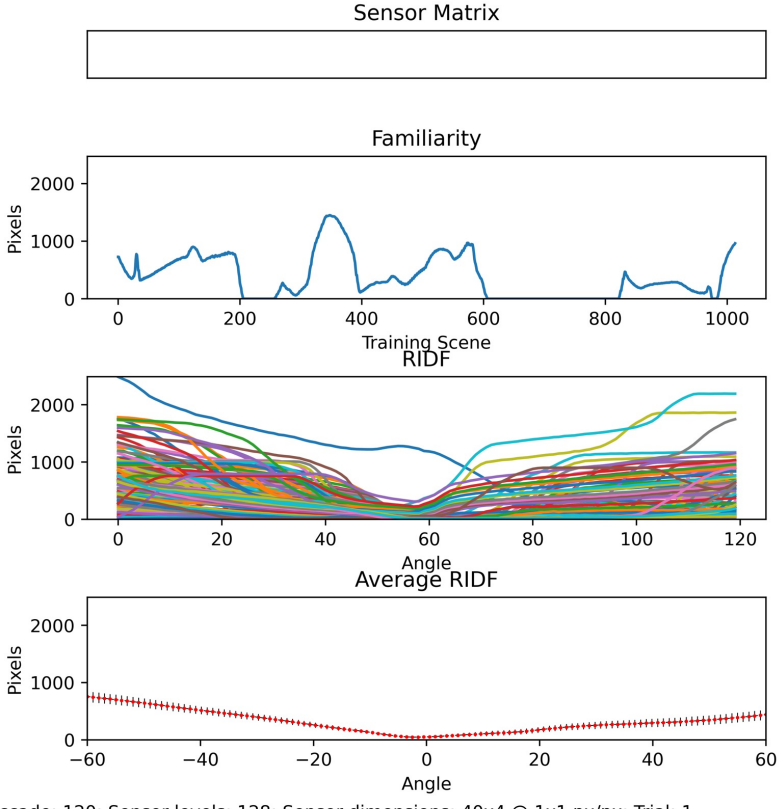




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 900.05; RMSD/dist: 2.250; TD: 139; p90: 34; p50: 24; complete: 0

0%





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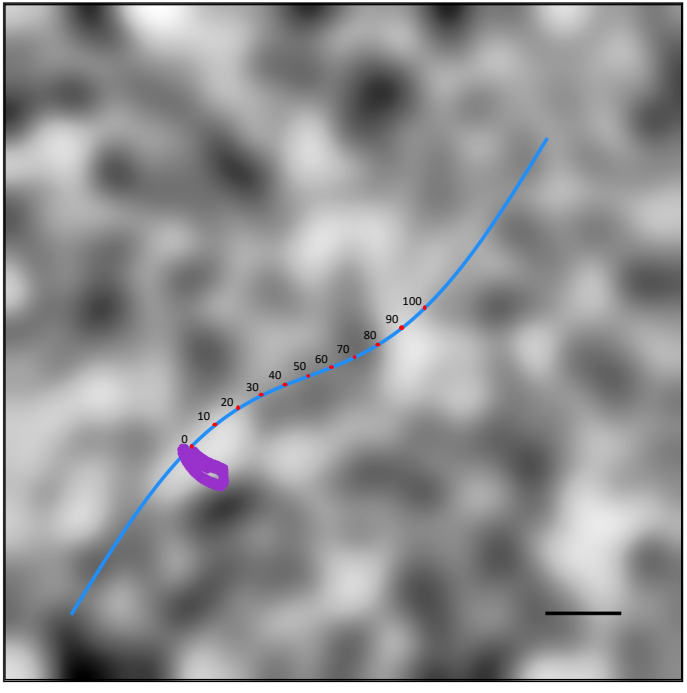
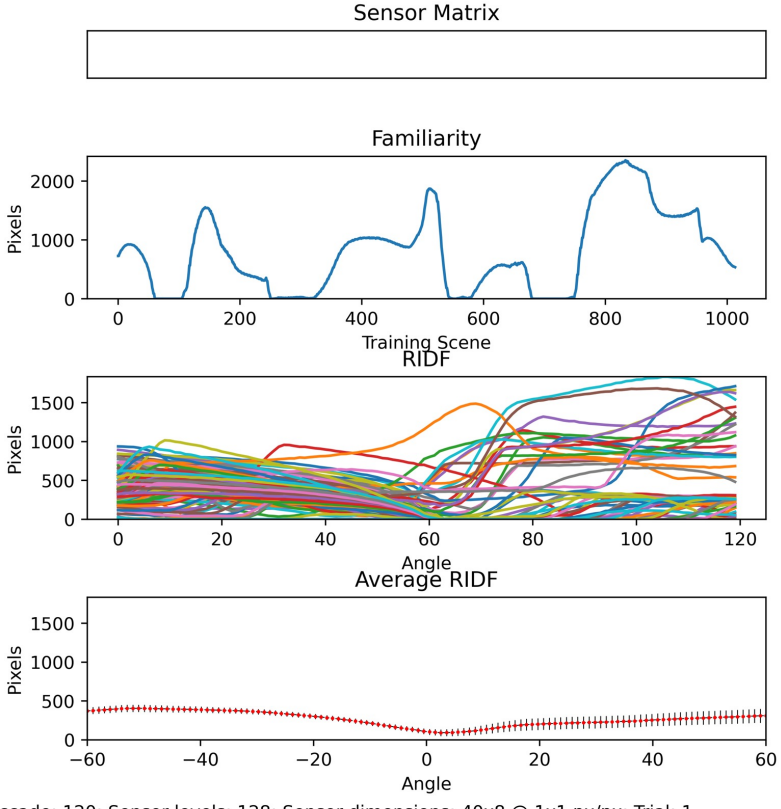
Navigation stats: RMSD error: 17077.79; RMSD/dist: 42.694; TD: 948; p90: 120; p50: 82; complete: 0

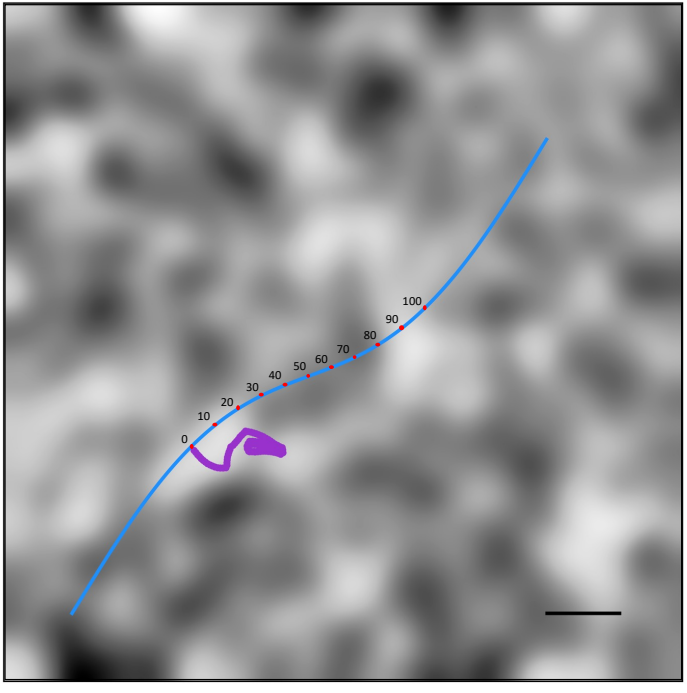
0%

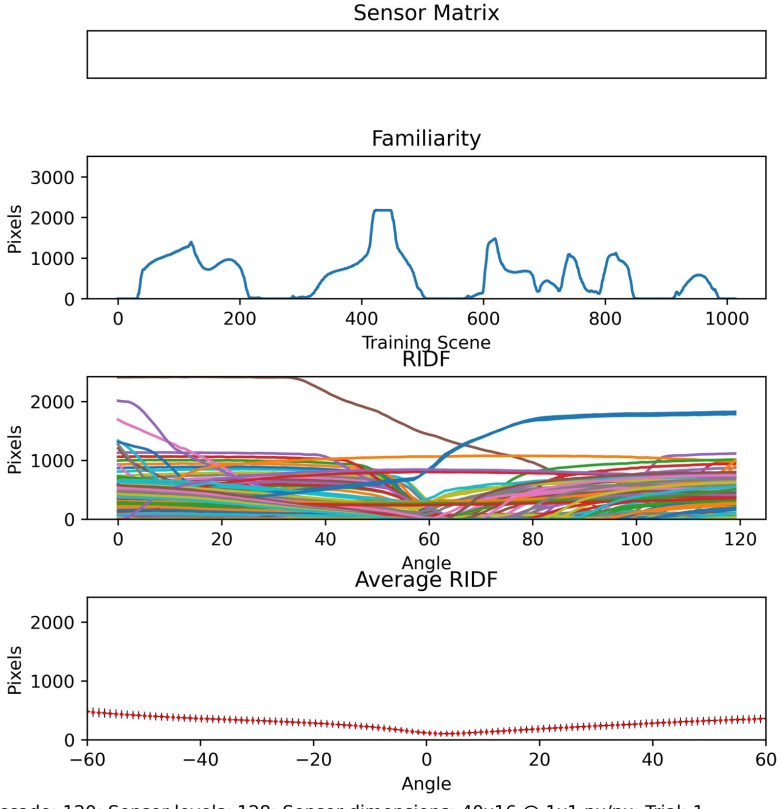




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 3421.49; RMSD/dist: 8.554; TD: 645; p90: 102; p50: 102; complete: 0

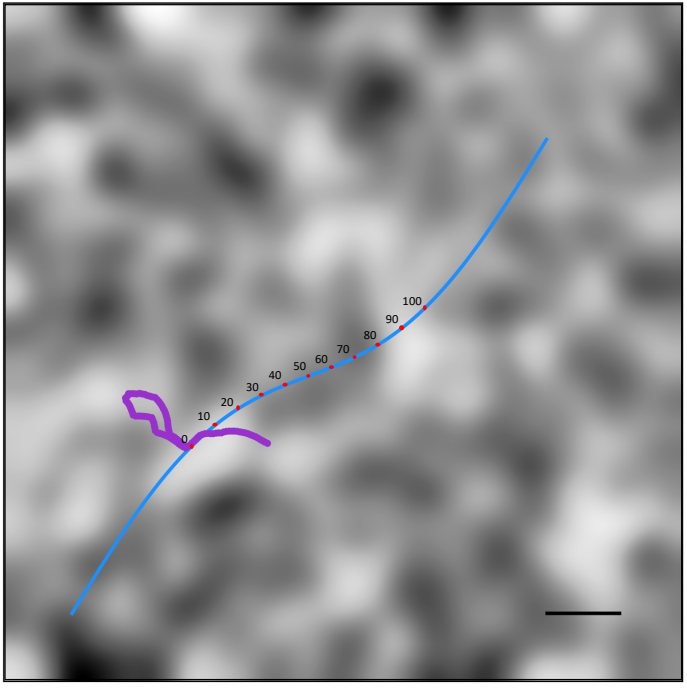
0%

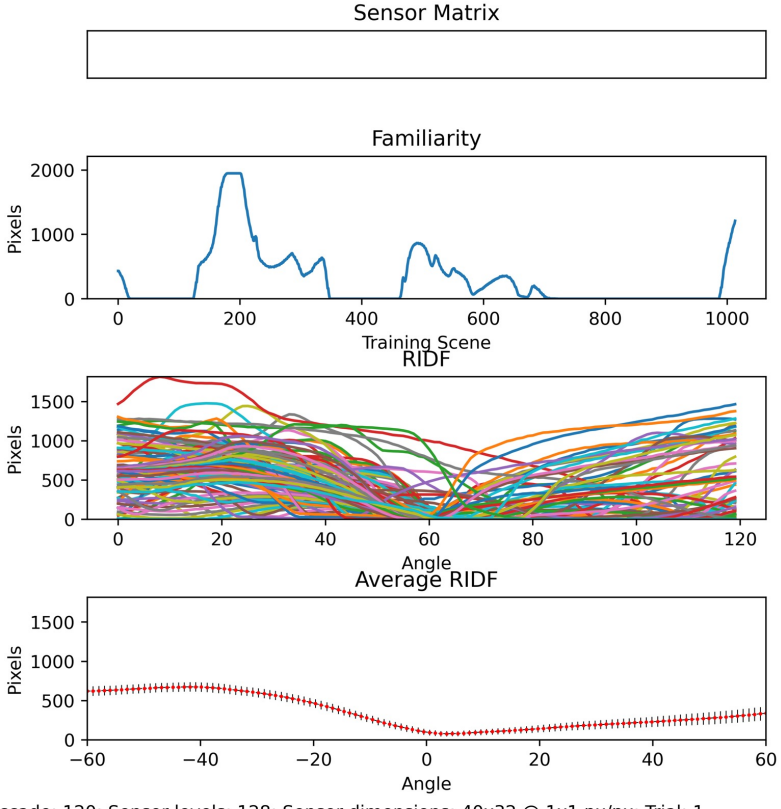




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 5787.36; RMSD/dist: 14.468; TD: 1273; p90: 120; p50: 120; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

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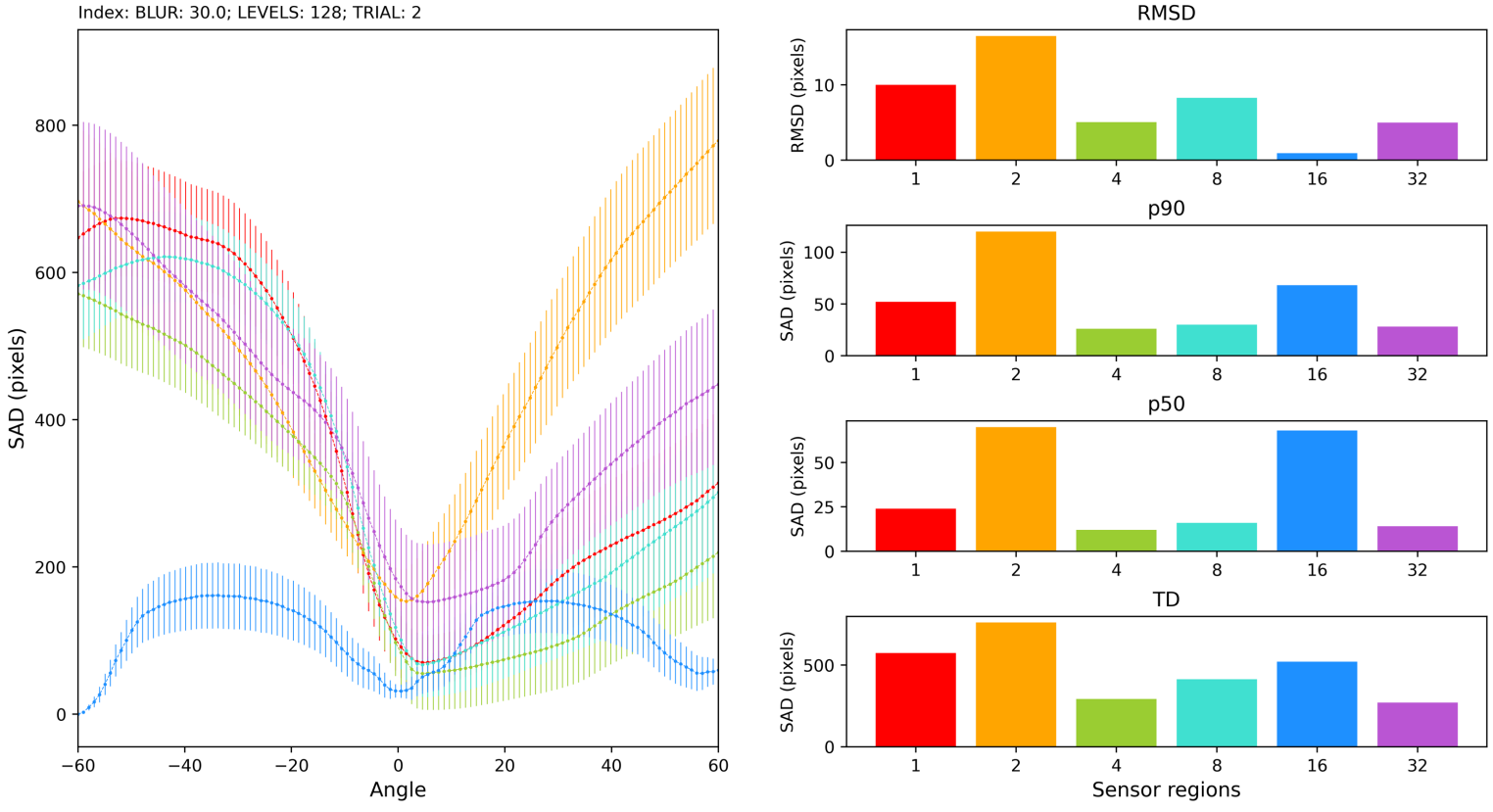
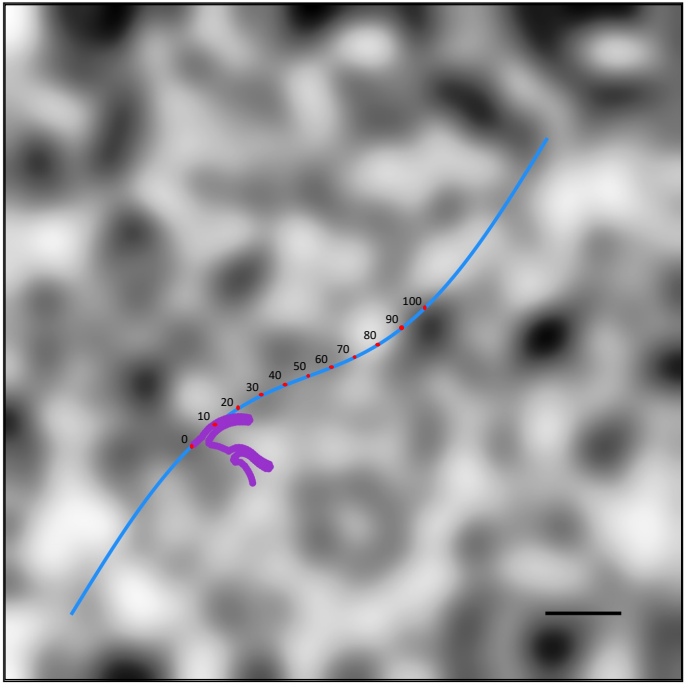
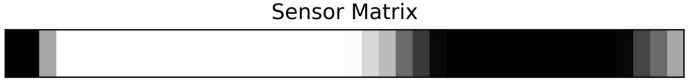
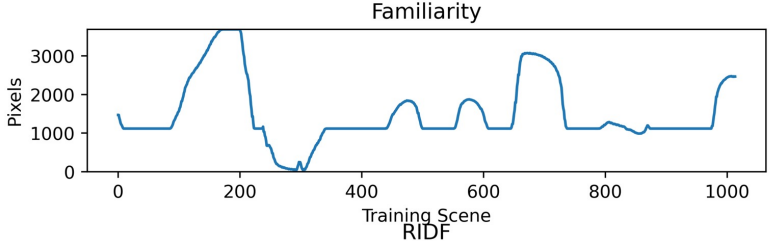
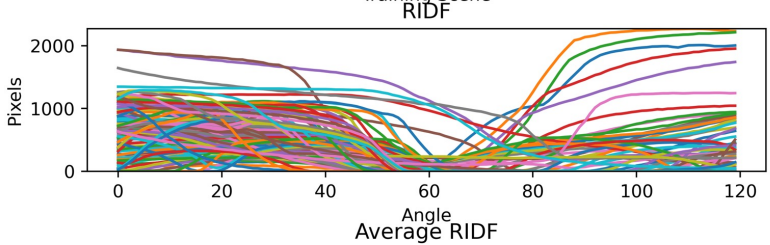

Index: BLUR: 30.0; LEVELS: 128; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

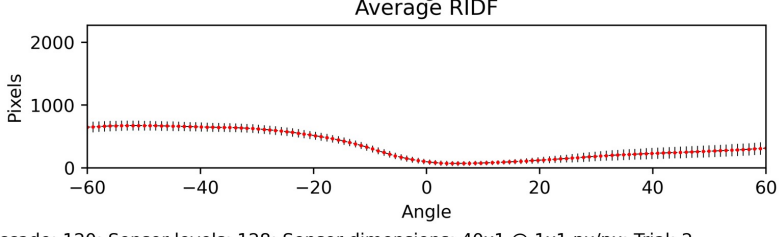
10%





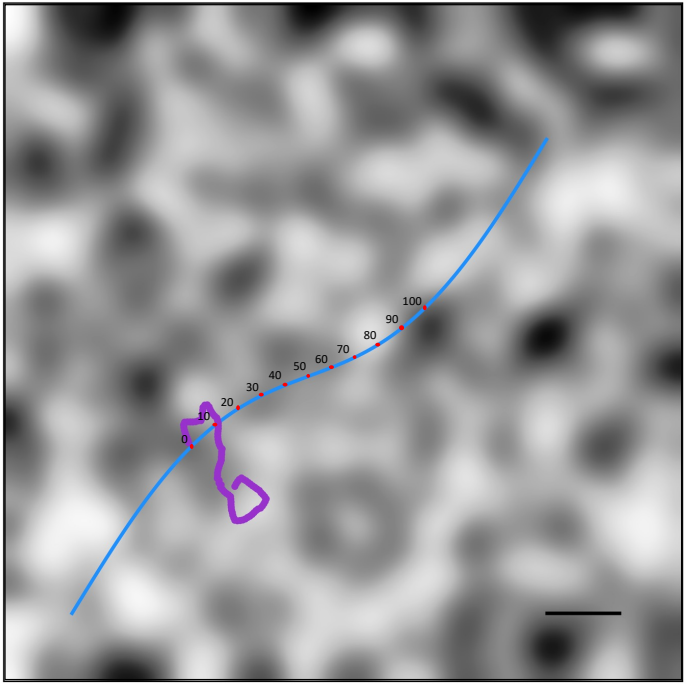


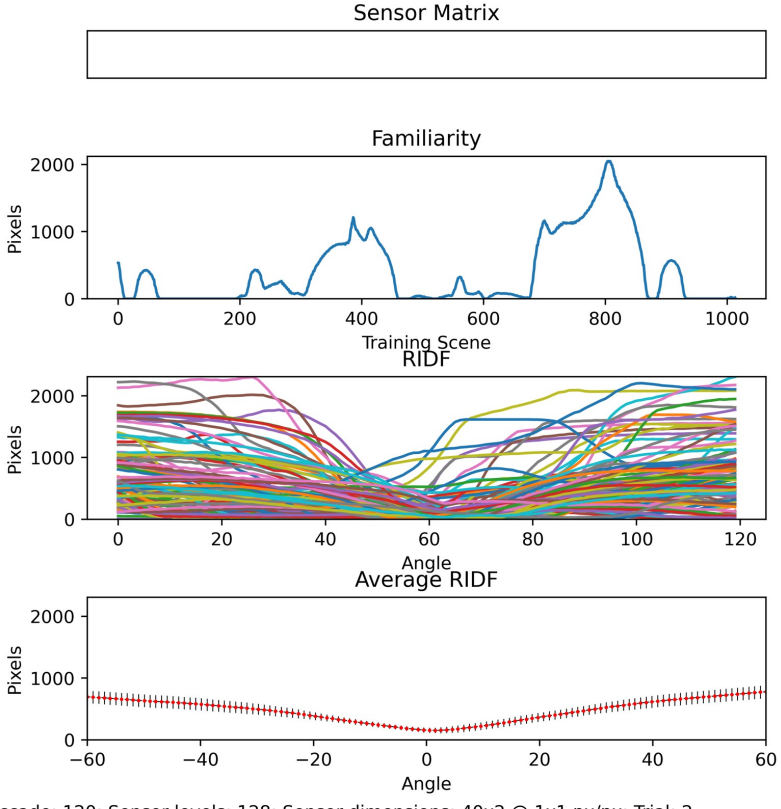




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 3996.52; RMSD/dist: 9.991; TD: 575; p90: 52; p50: 24; complete: 0

0%





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Navigation stats: RMSD error: 6594.79; RMSD/dist: 16.487; TD: 761; p90: 120; p50: 70; complete: 0

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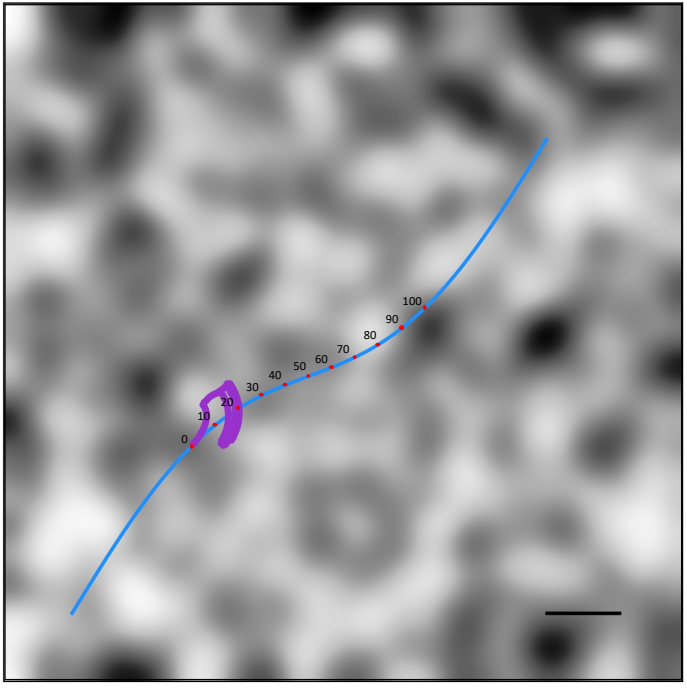

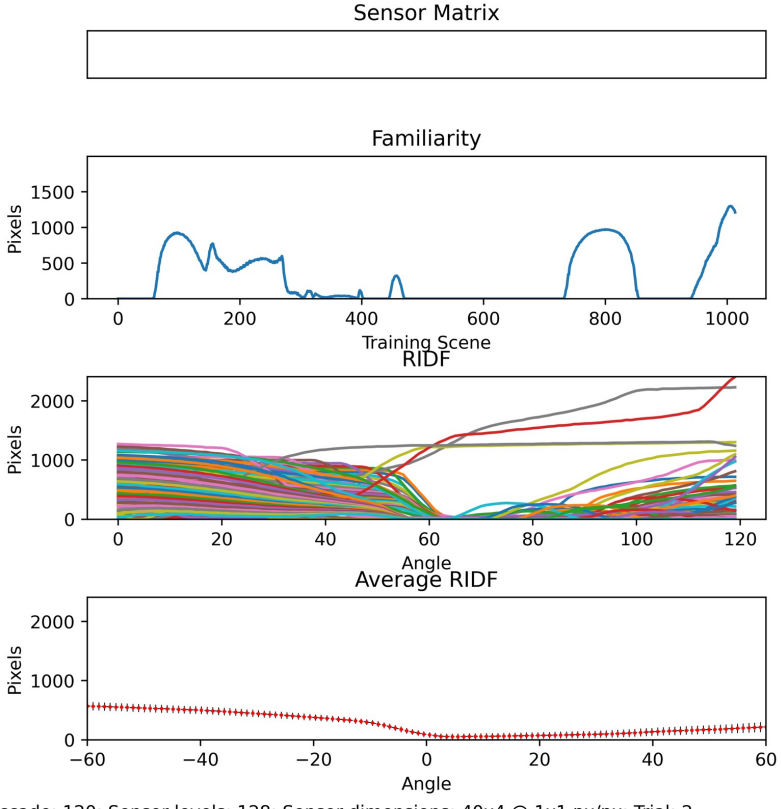

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 2011.44; RMSD/dist: 5.029; TD: 293; p90: 26; p50: 12; complete: 0

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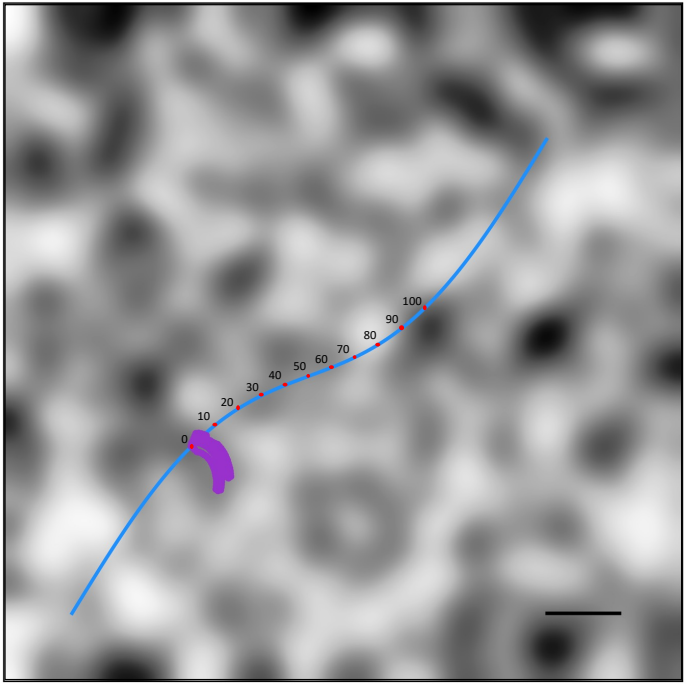

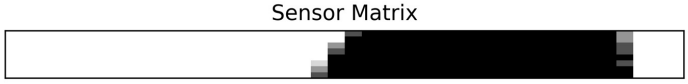

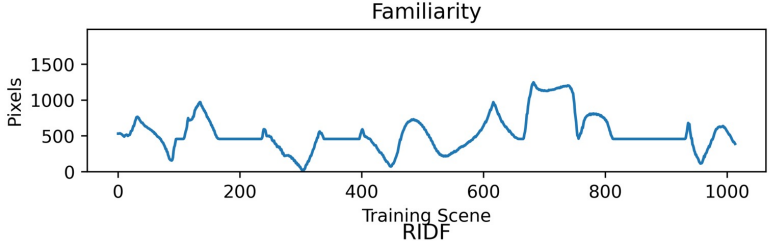

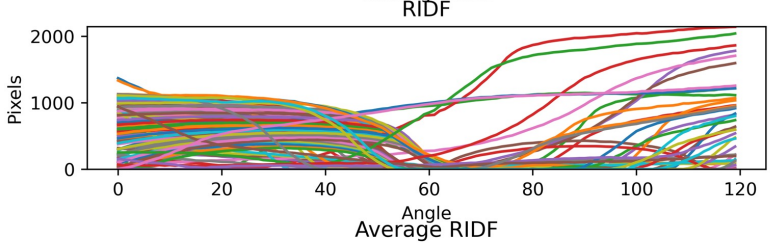

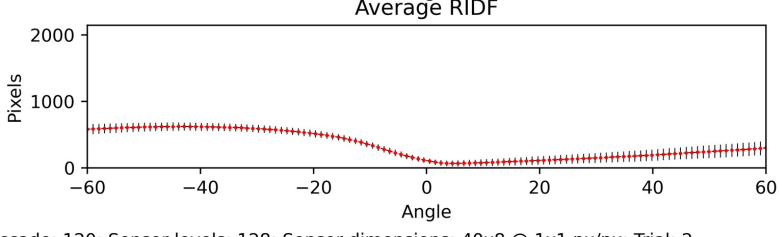

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 3301.94; RMSD/dist: 8.255; TD: 414; p90: 30; p50: 16; complete: 0

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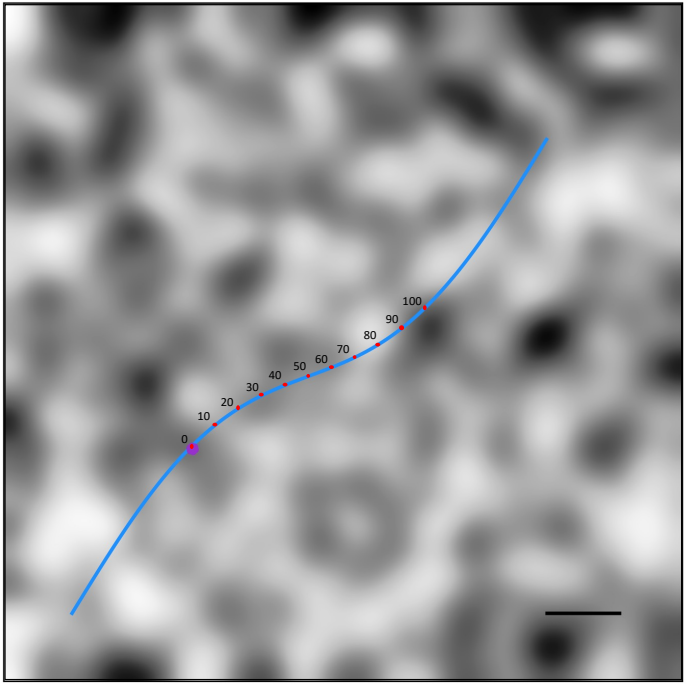

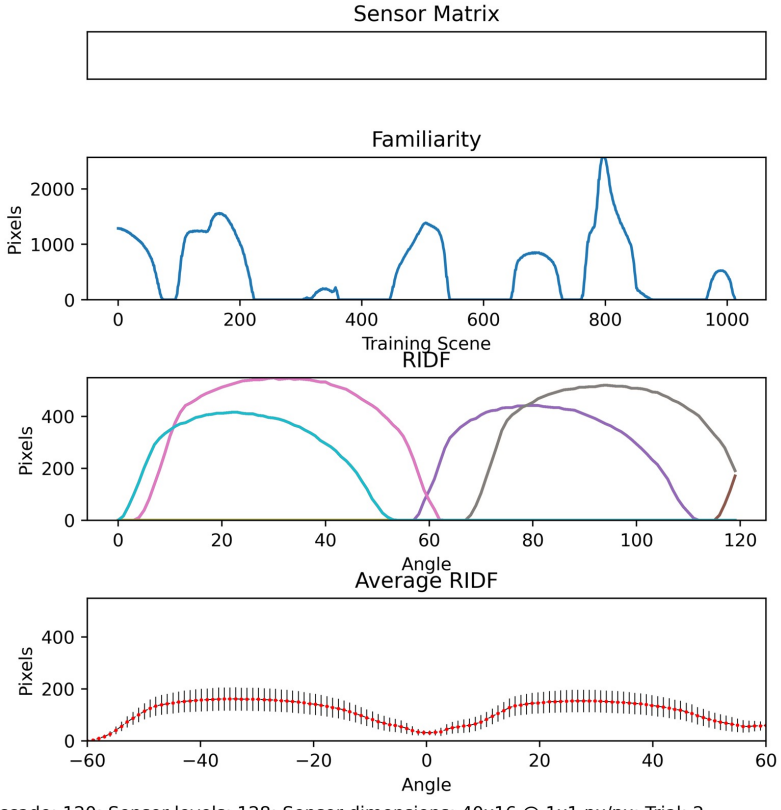

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Navigation stats: RMSD error: 362.69; RMSD/dist: 0.907; TD: 521; p90: 68; p50: 68; complete: 0

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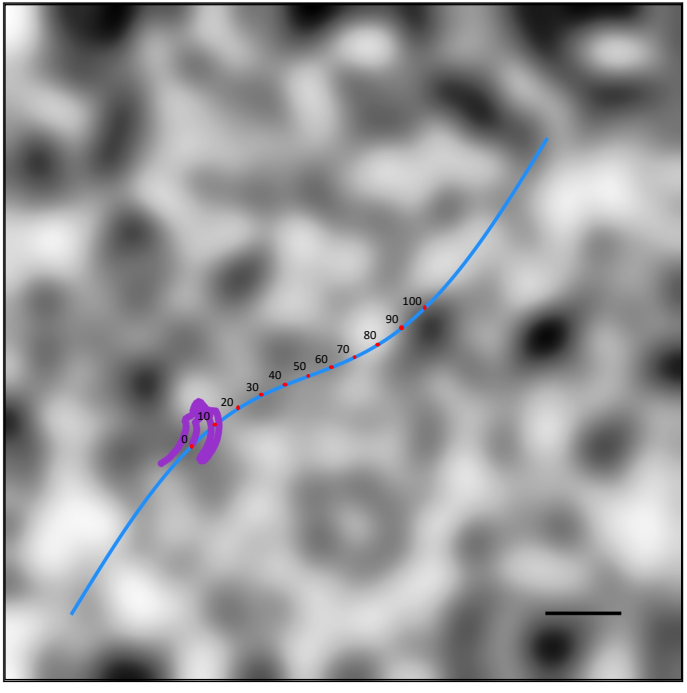
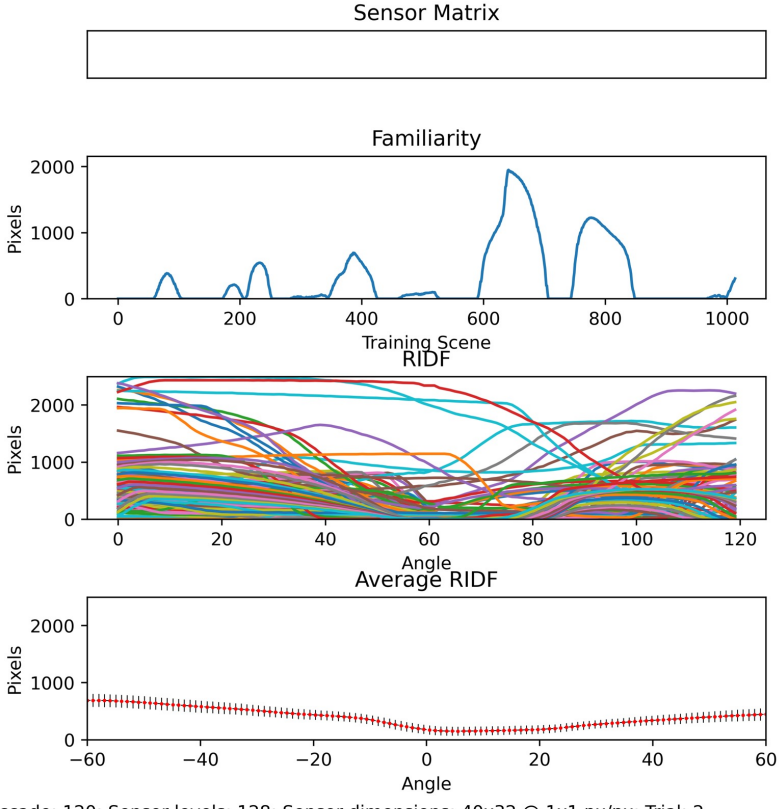
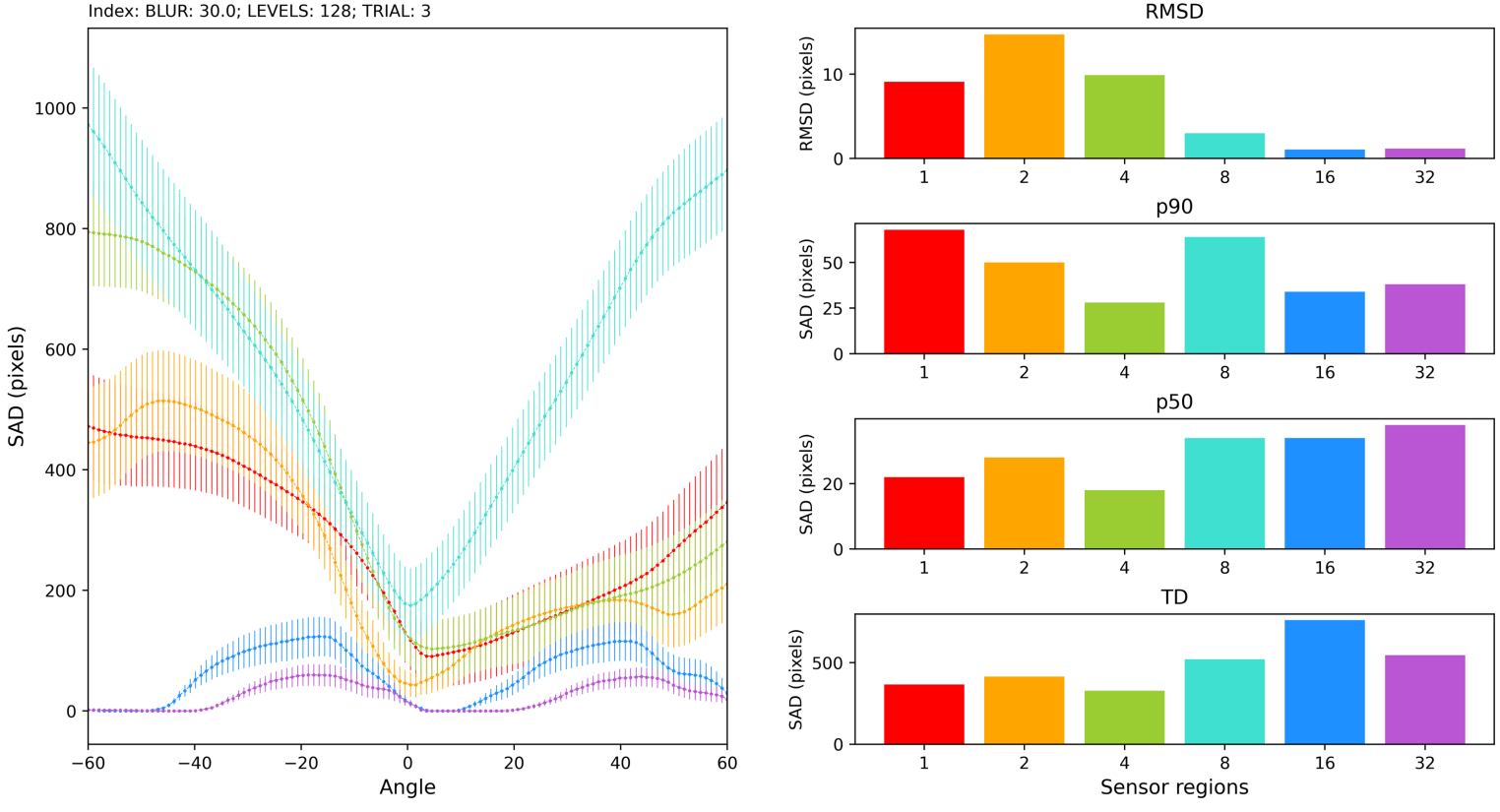
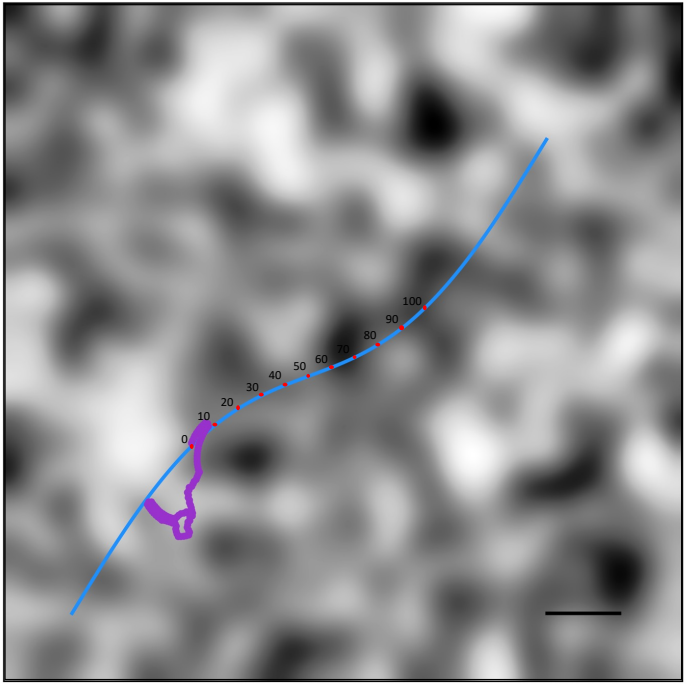


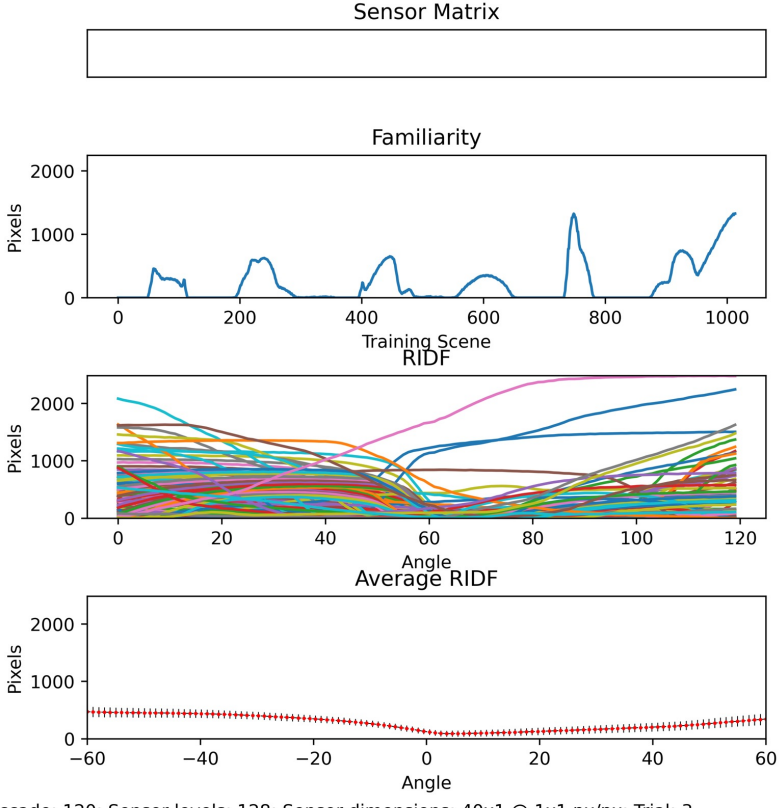


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 1990.03; RMSD/dist: 4.975; TD: 270; p90: 28; p50: 14; complete: 0


Index: BLUR: 30.0; LEVELS: 128; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 3641.38; RMSD/dist: 9.103; TD: 366; p90: 68; p50: 22; complete: 0

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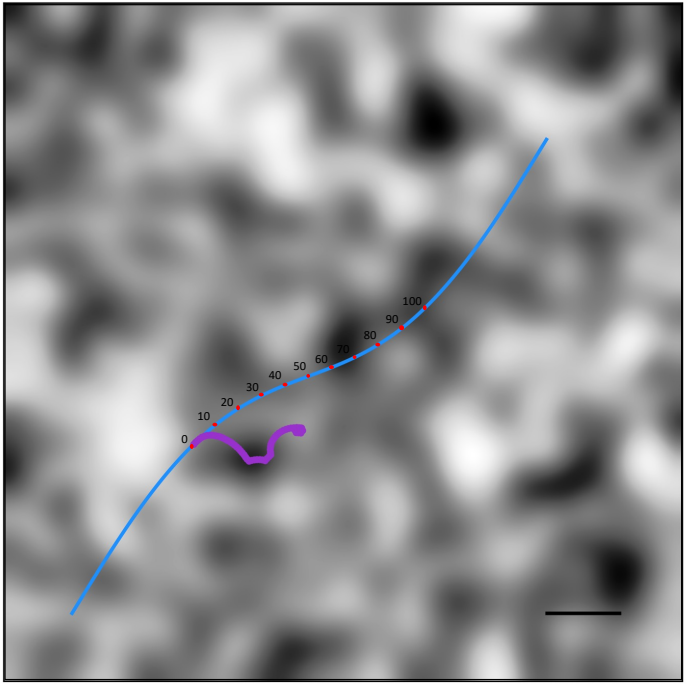
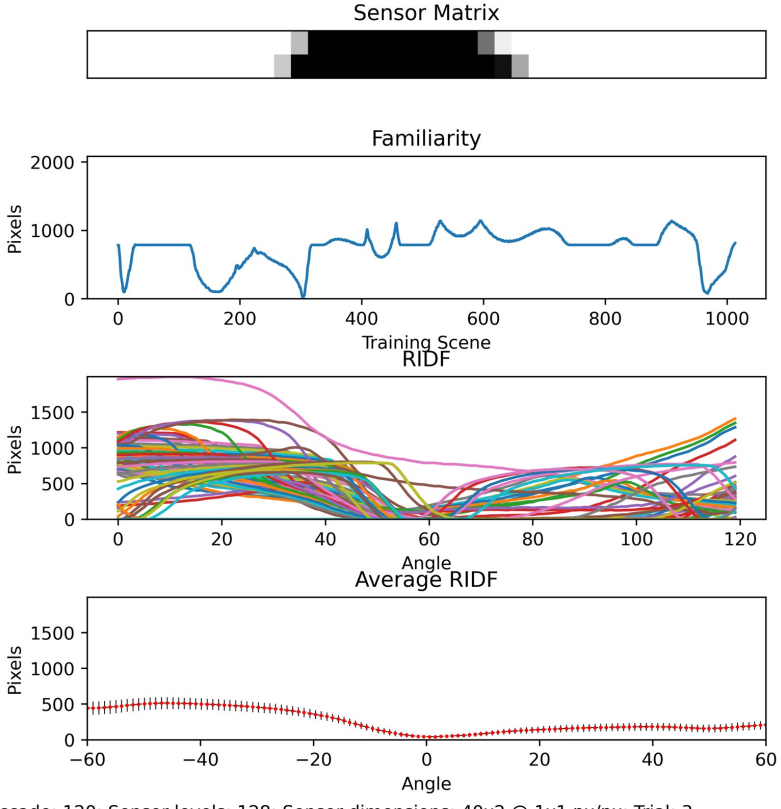
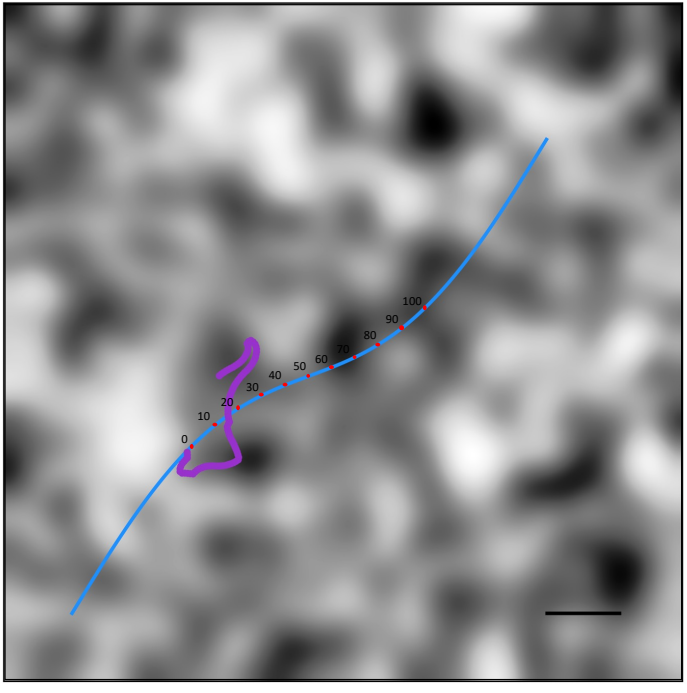
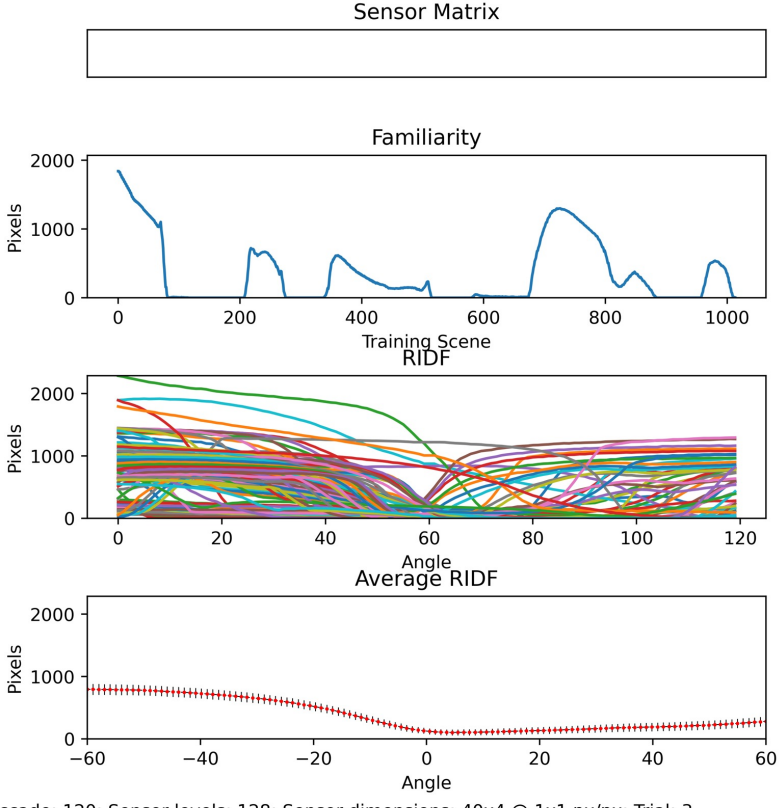




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 5887.44; RMSD/dist: 14.719; TD: 415; p90: 50; p50: 28; complete: 0

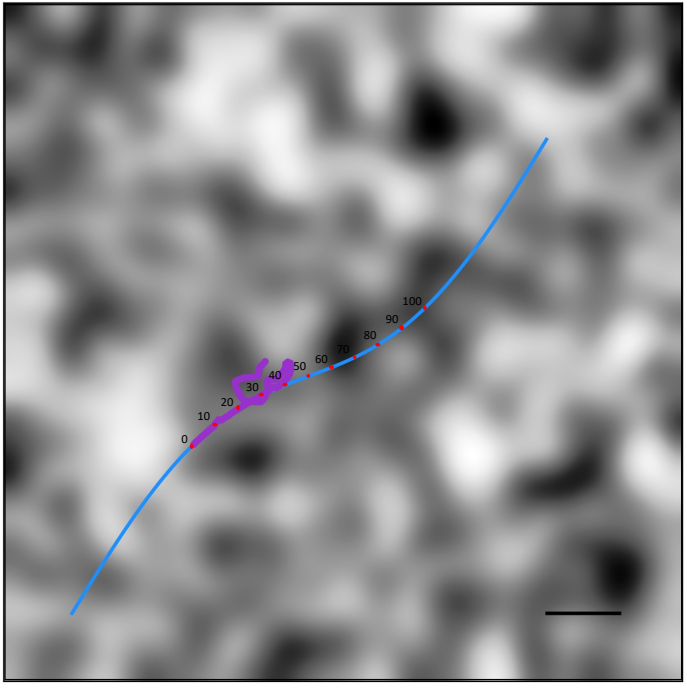
0%

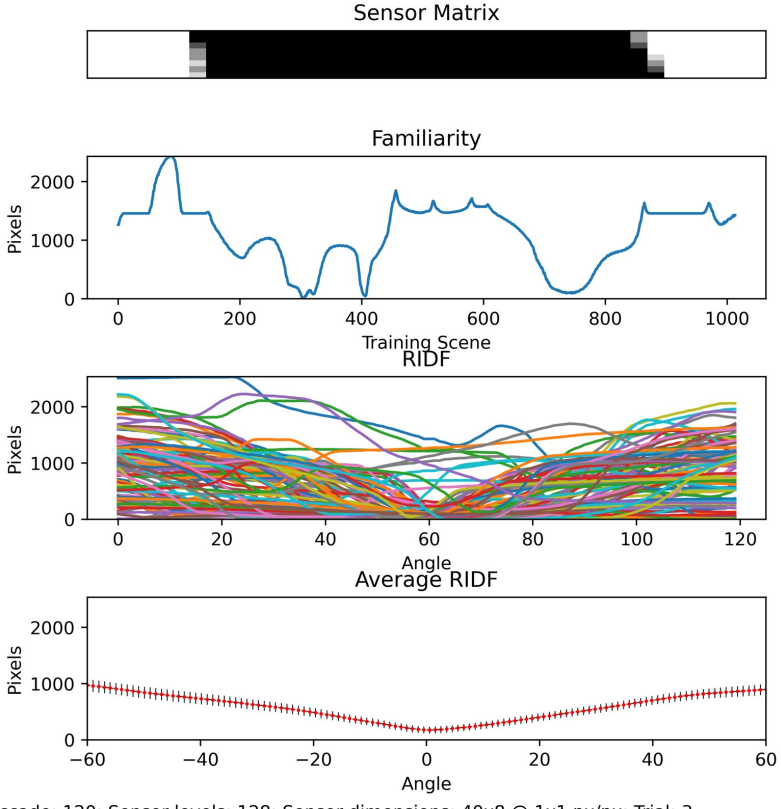




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 3957.20; RMSD/dist: 9.893; TD: 328; p90: 28; p50: 18; complete: 0

30%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 1196.36; RMSD/dist: 2.991; TD: 522; p90: 64; p50: 34; complete: 0

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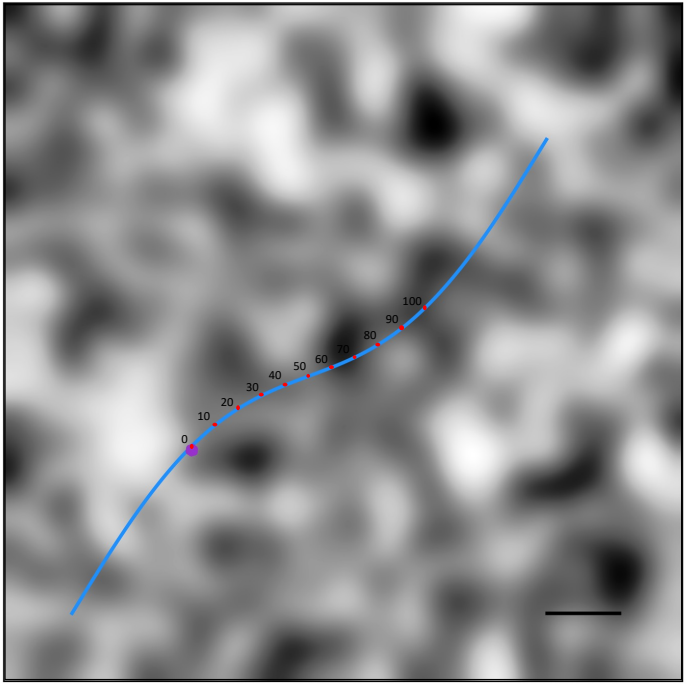

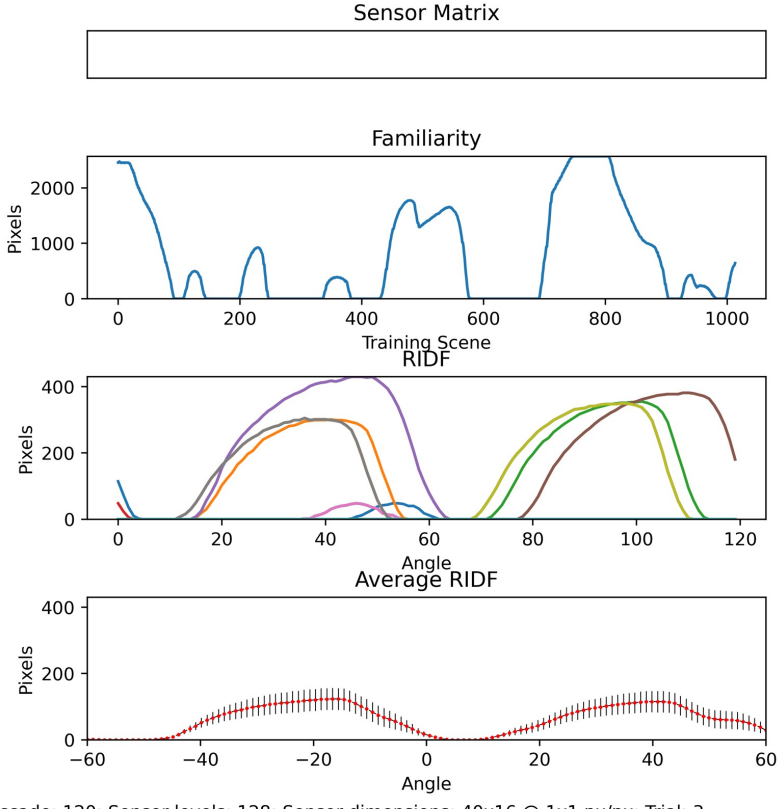

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Navigation stats: RMSD error: 424.91; RMSD/dist: 1.062; TD: 761; p90: 34; p50: 34; complete: 0

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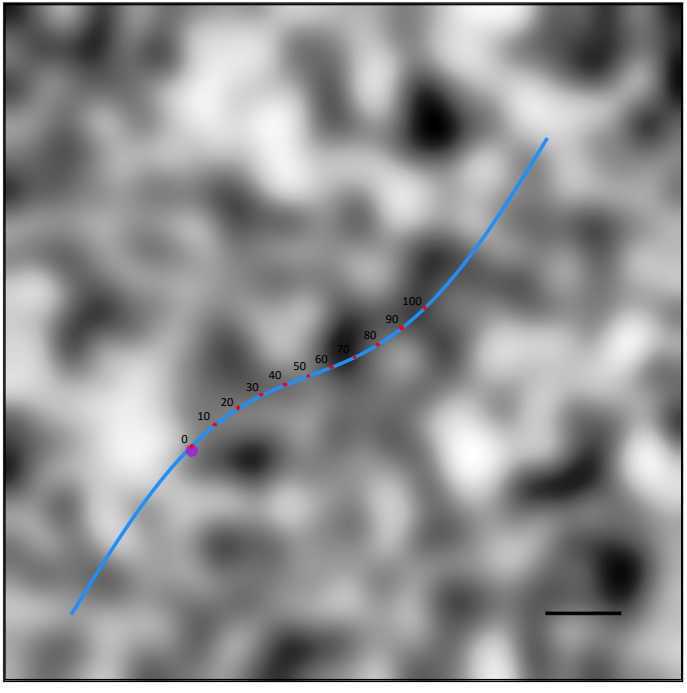

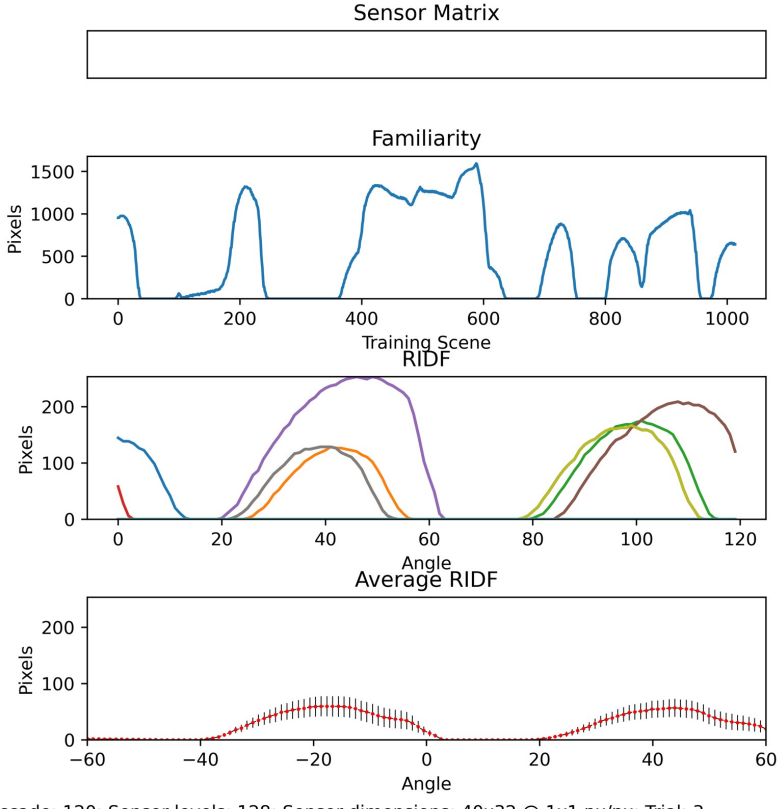

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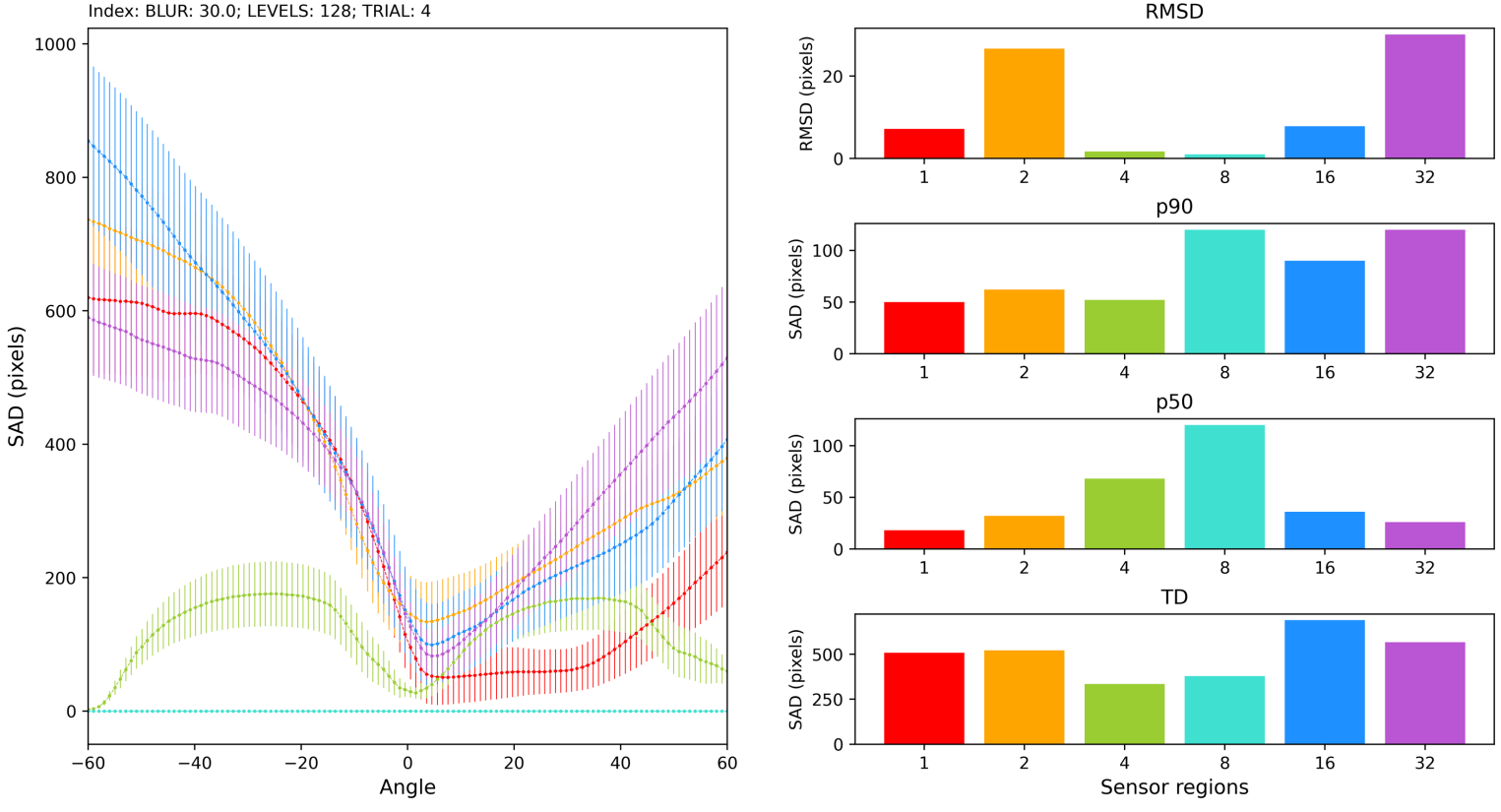
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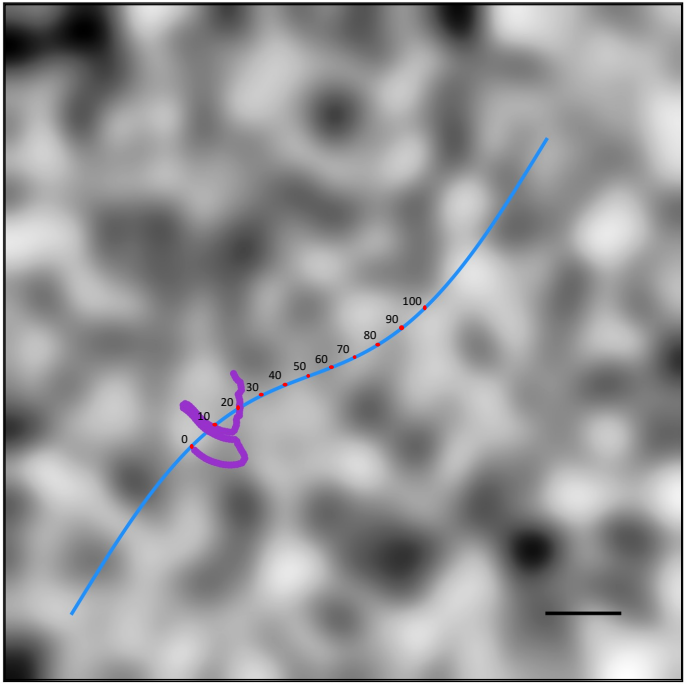
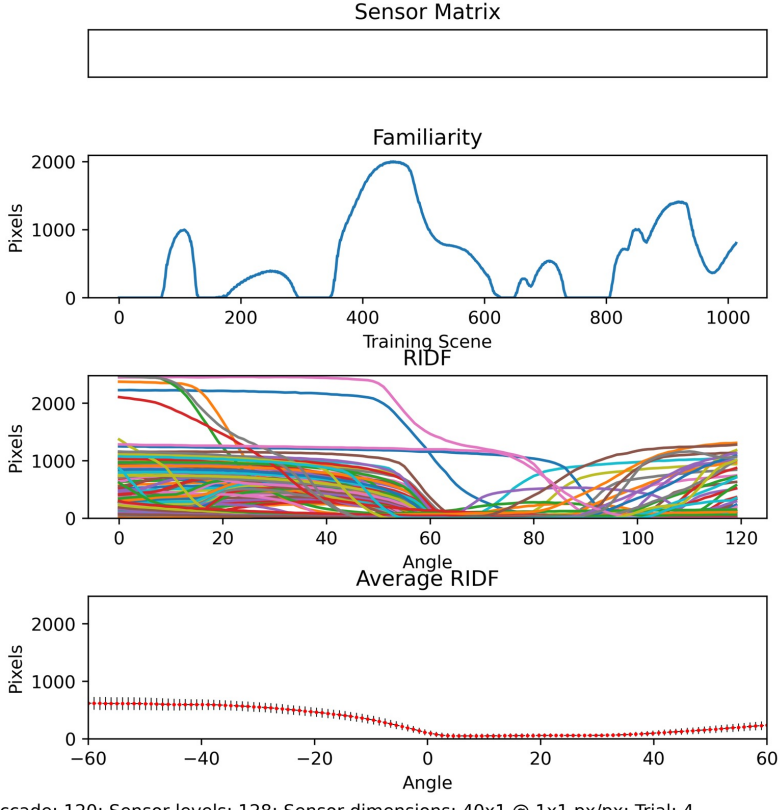
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





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Navigation stats: RMSD error: 2863.70; RMSD/dist: 7.159; TD: 508; p90: 50; p50: 18; complete: 0

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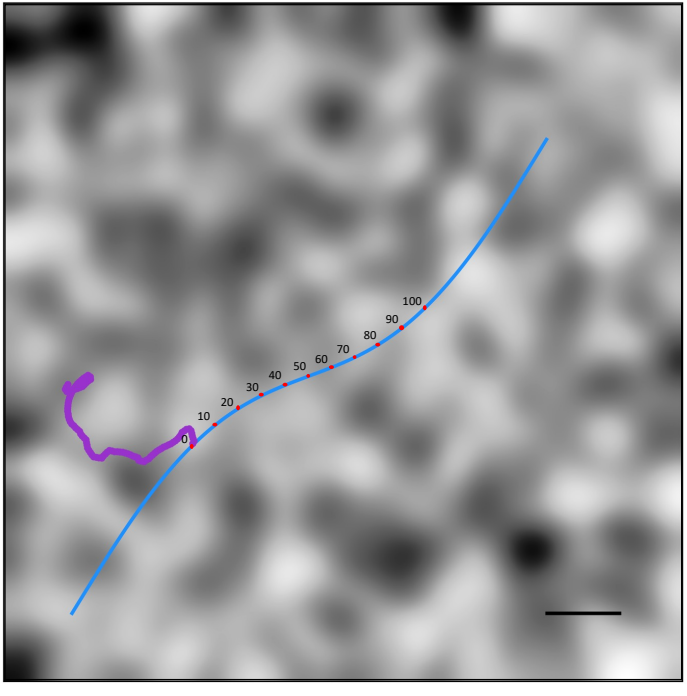

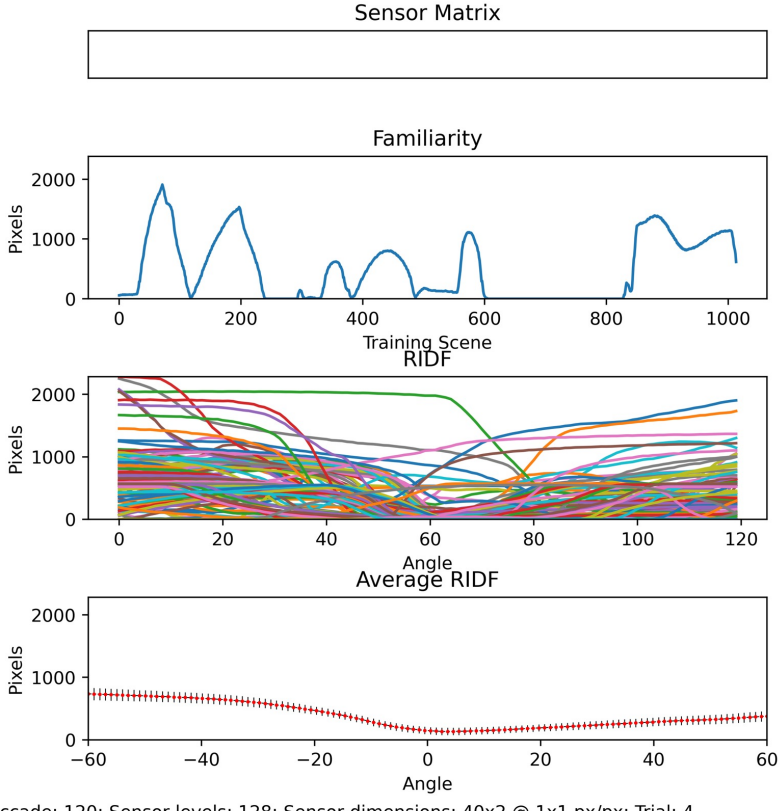

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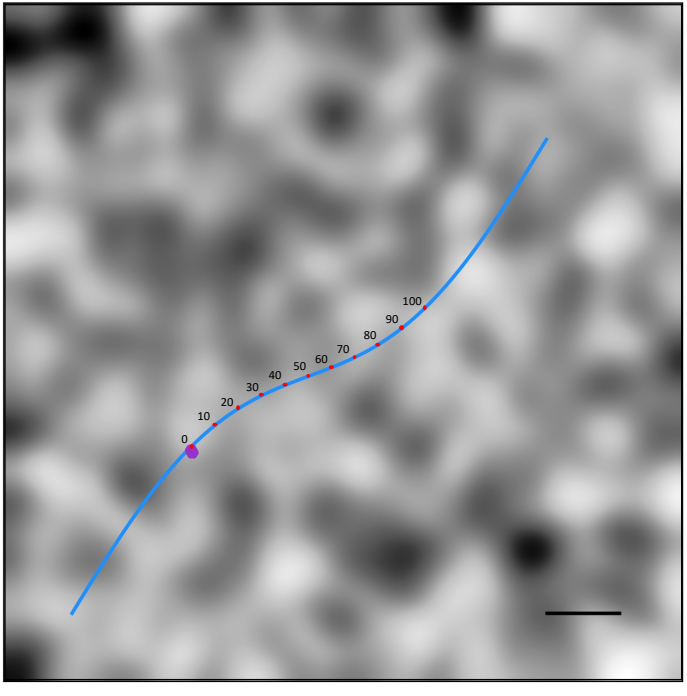

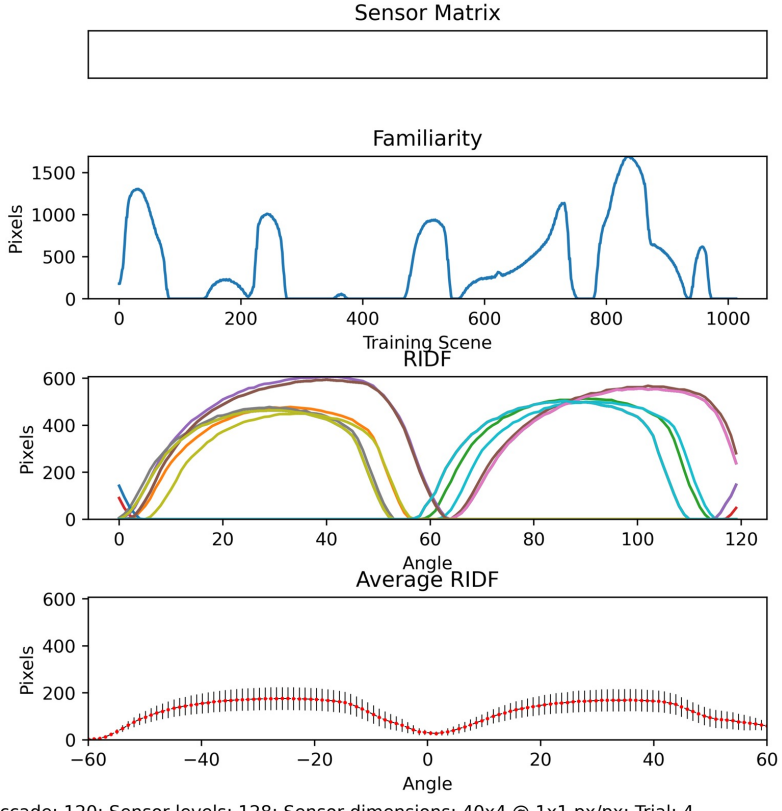

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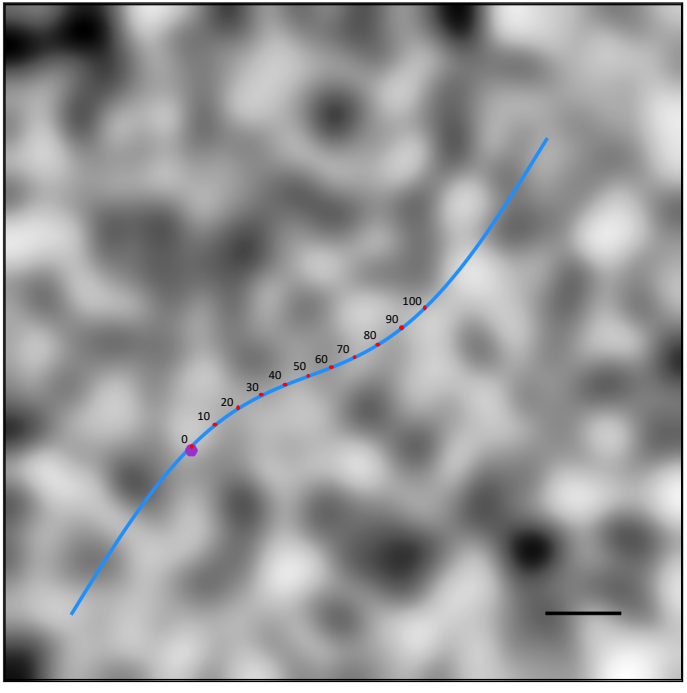

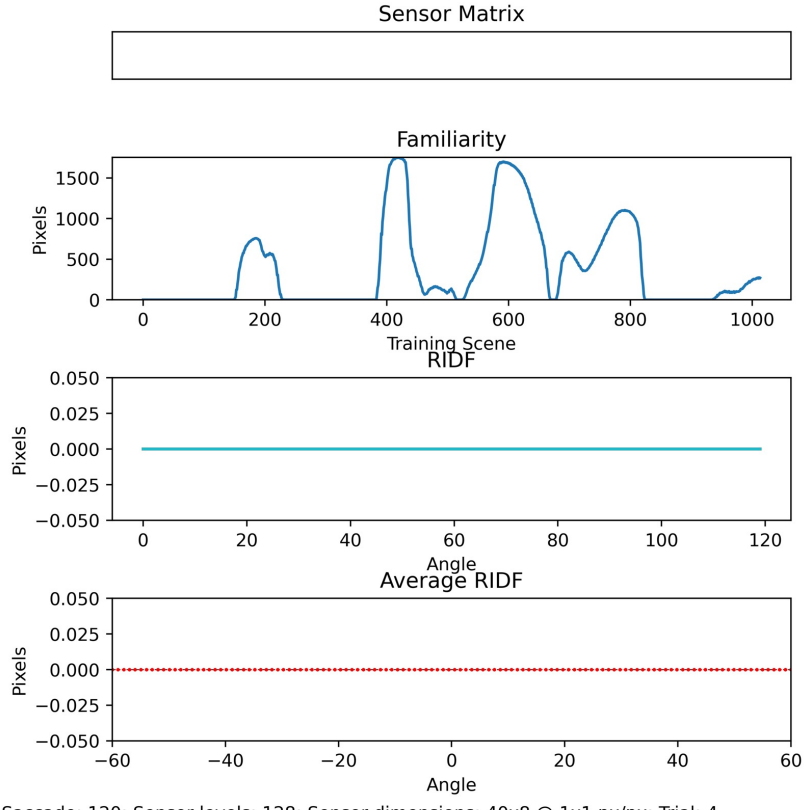

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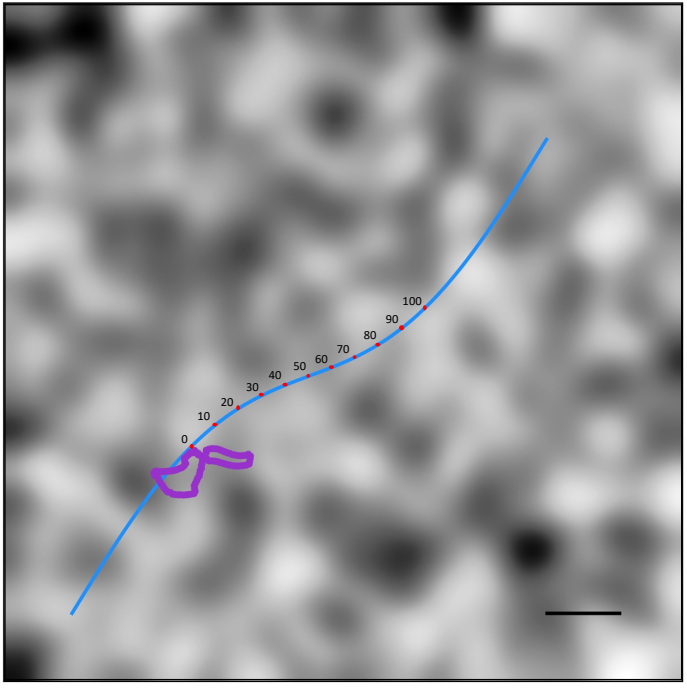

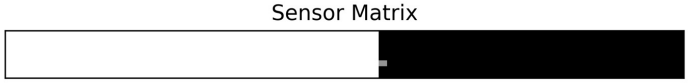

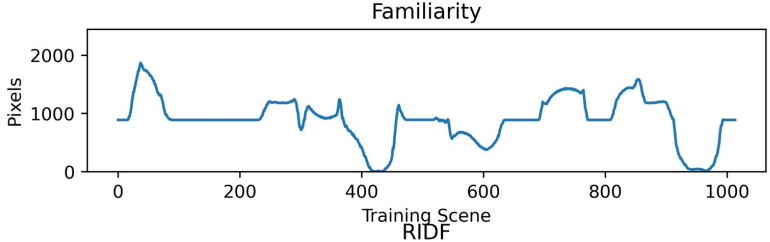

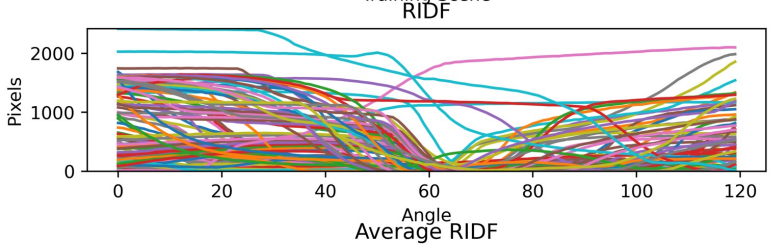

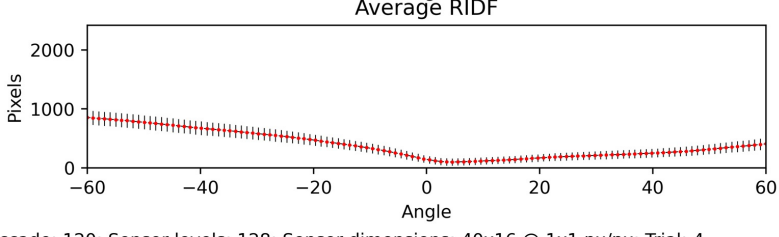

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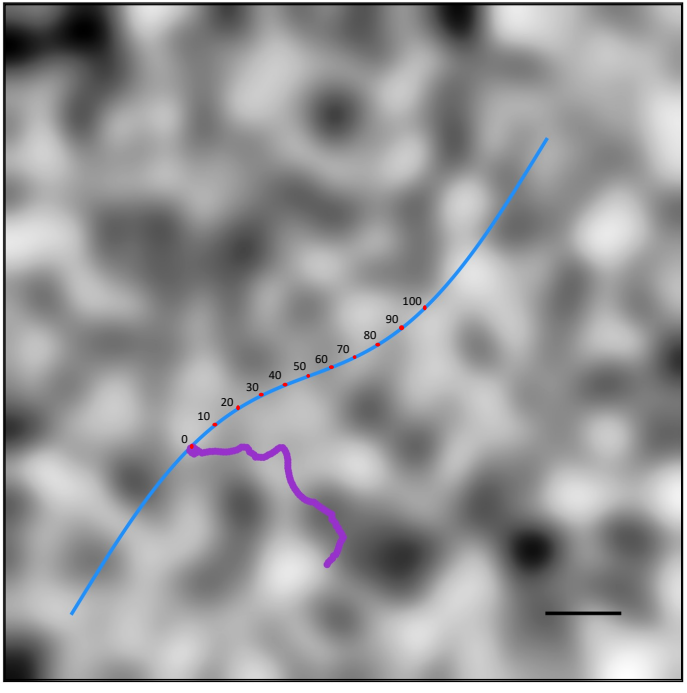

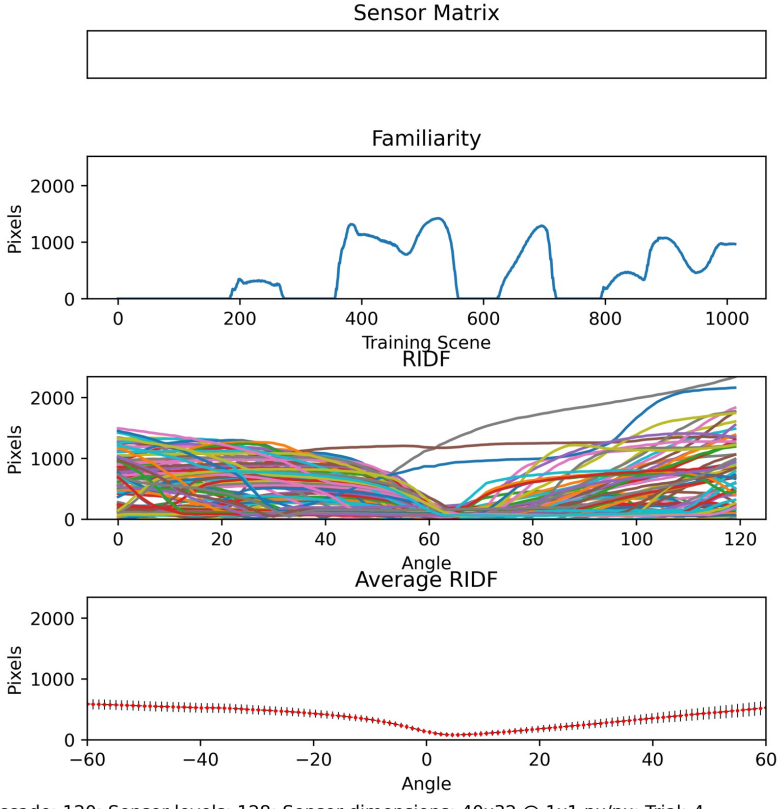

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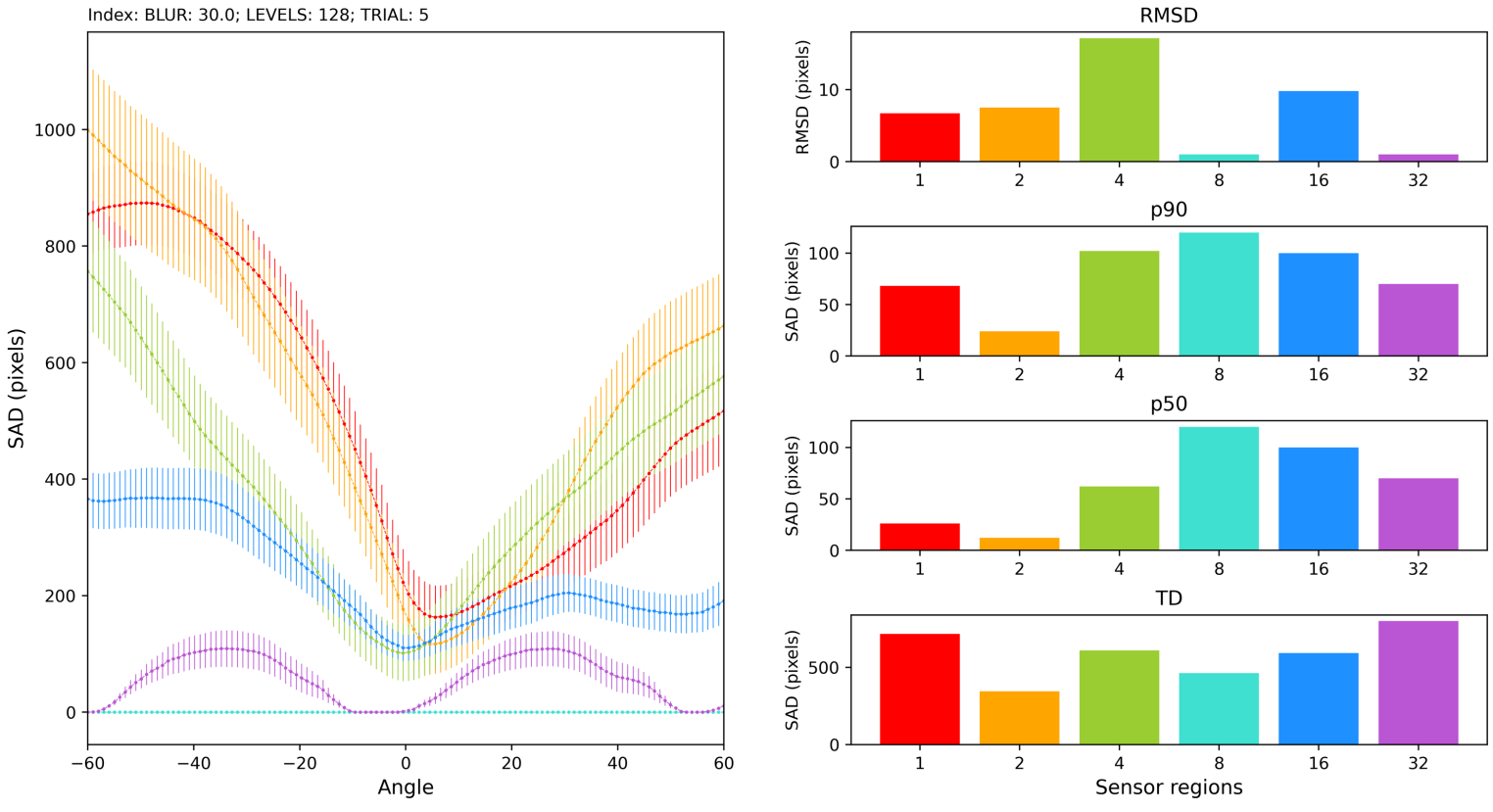
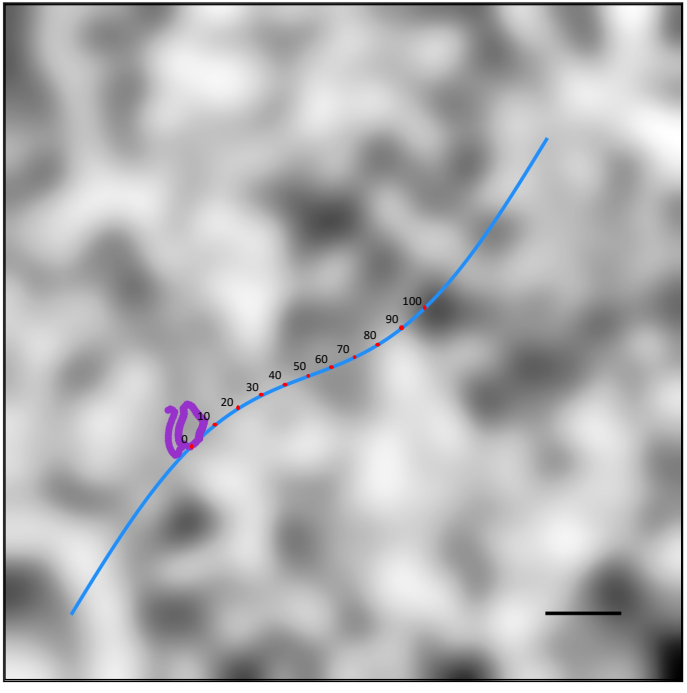
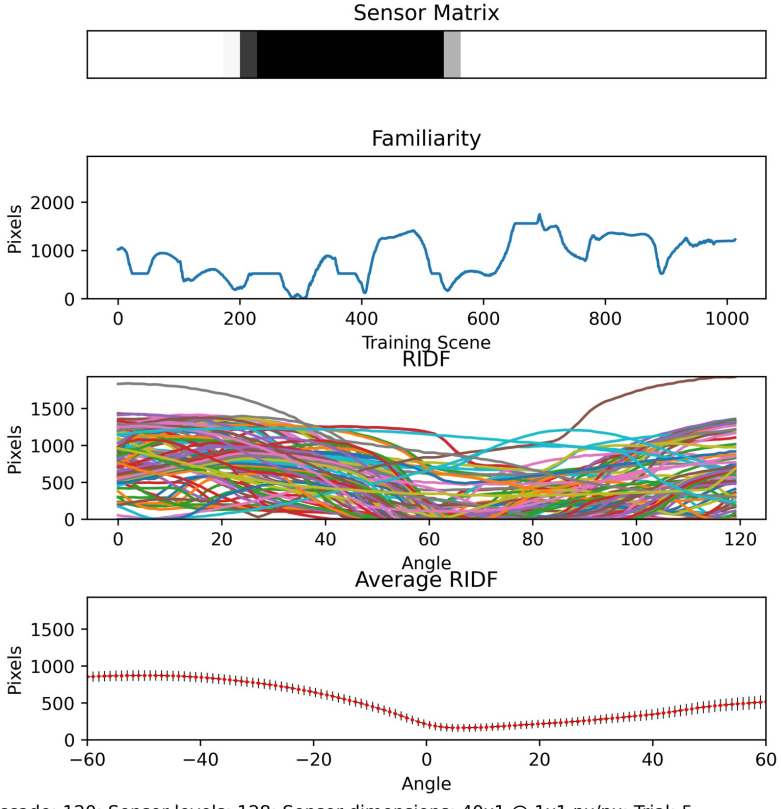

Index: BLUR: 30.0; LEVELS: 128; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

0%





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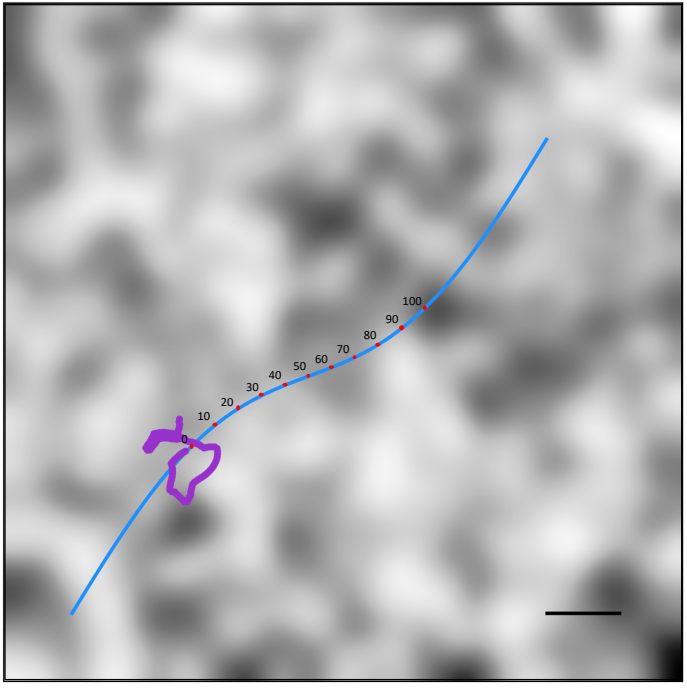

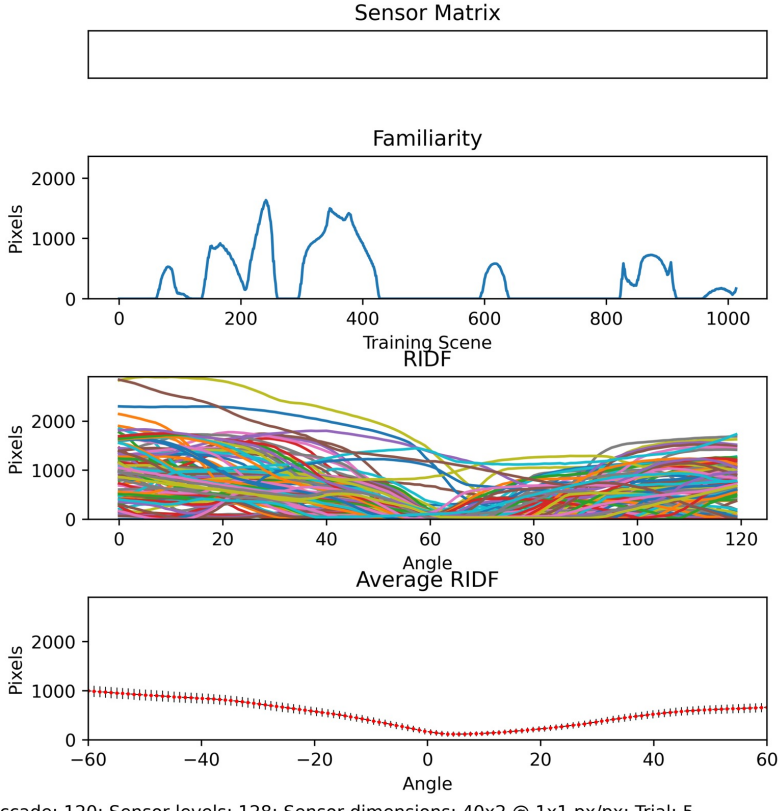

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Navigation stats: RMSD error: 3005.05; RMSD/dist: 7.513; TD: 344; p90: 24; p50: 12; complete: 0

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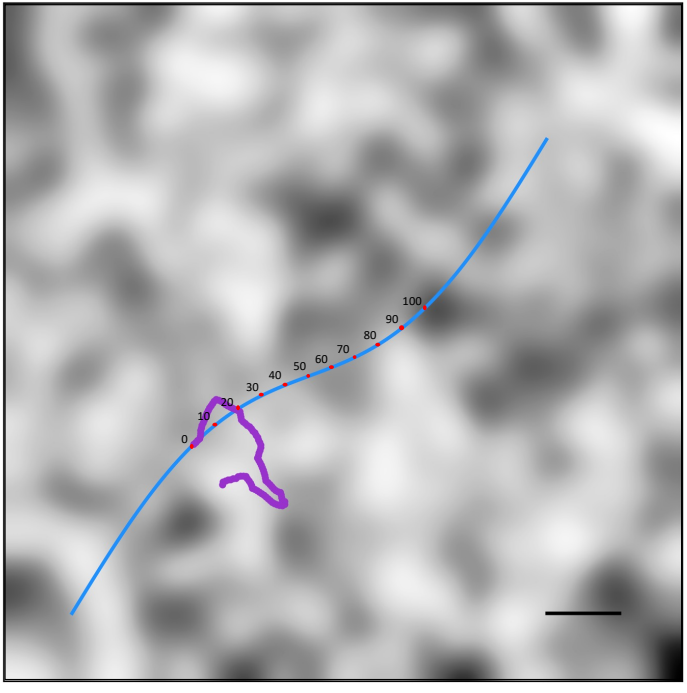

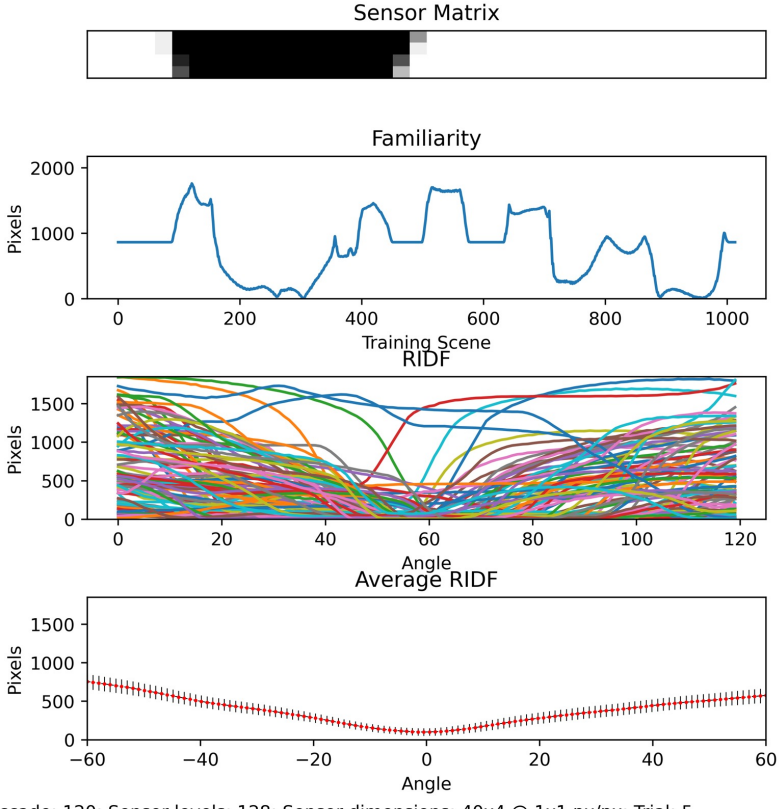

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Navigation stats: RMSD error: 6853.20; RMSD/dist: 17.133; TD: 610; p90: 102; p50: 62; complete: 0

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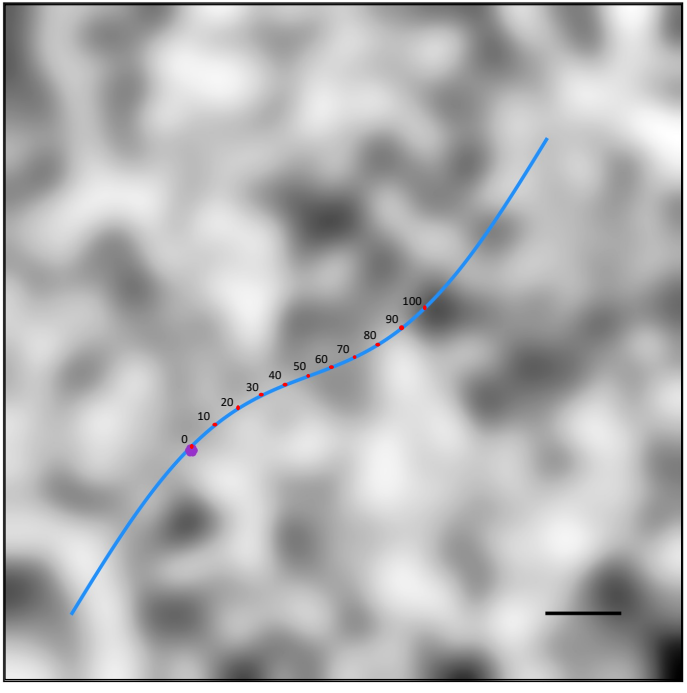

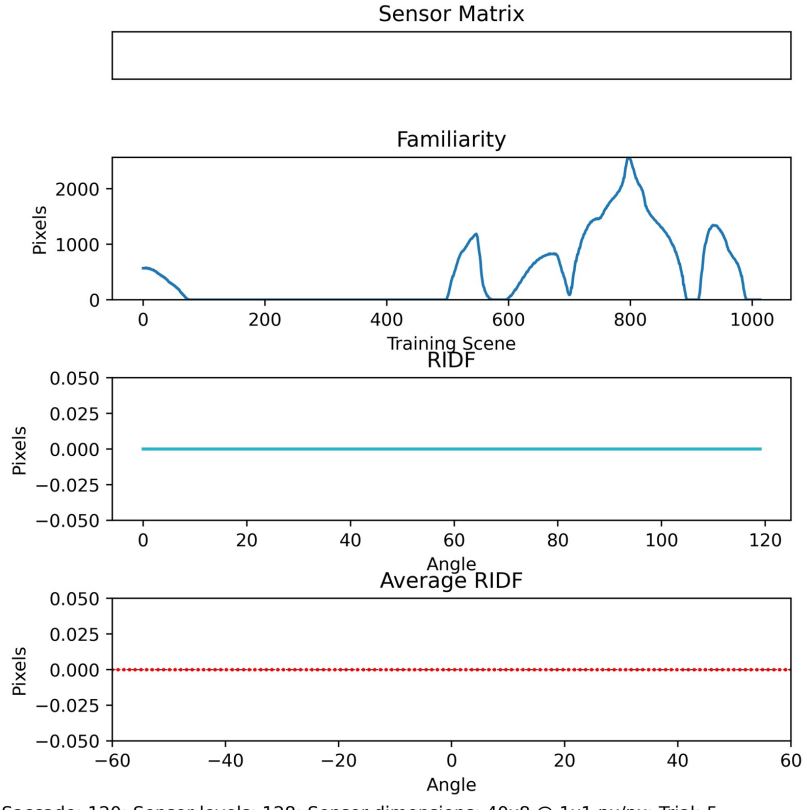

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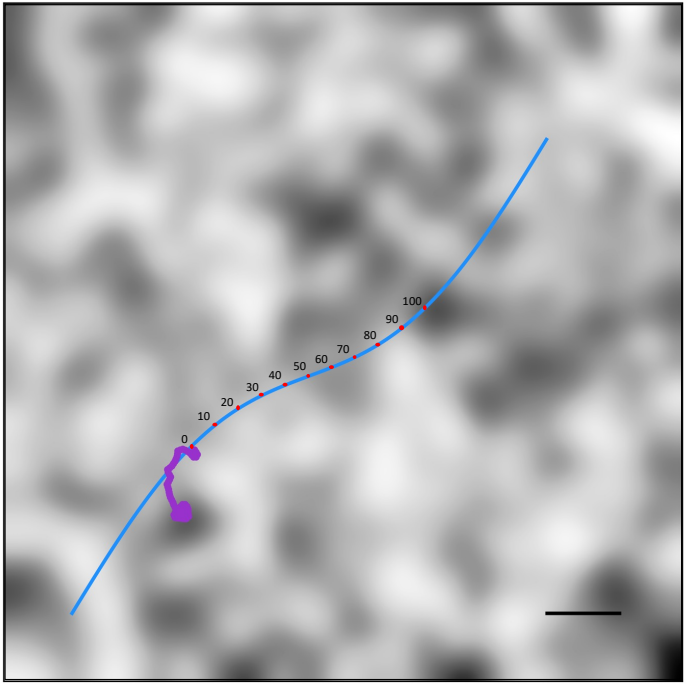
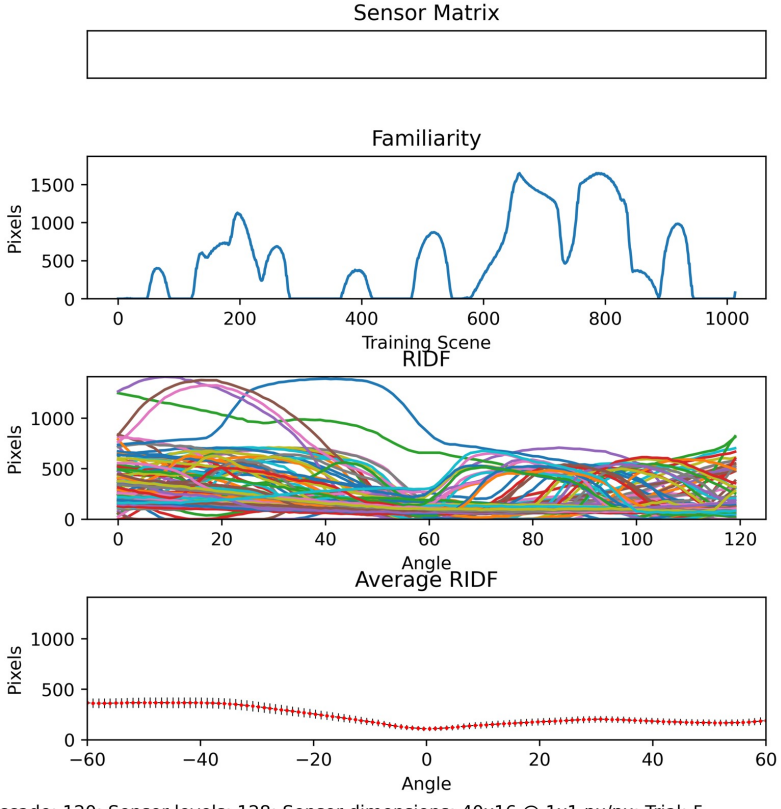
Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 463; p90: 120; p50: 120; complete: 0

0%





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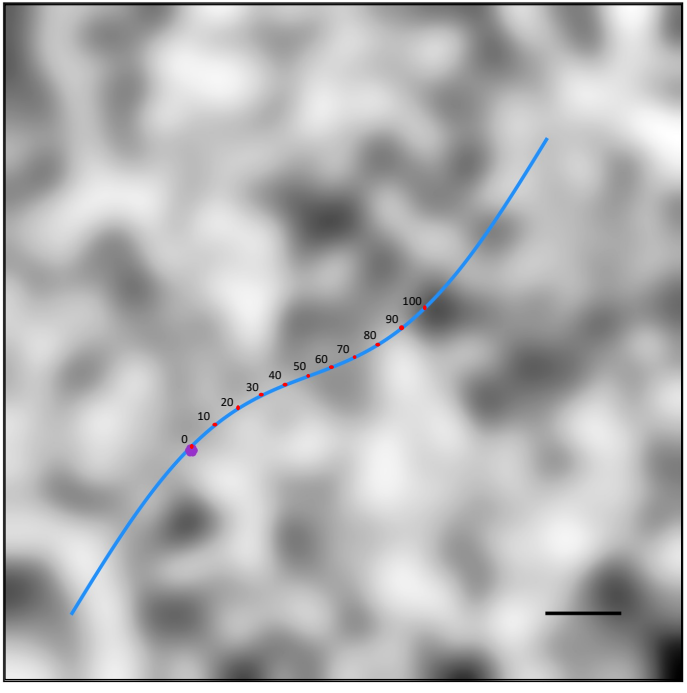

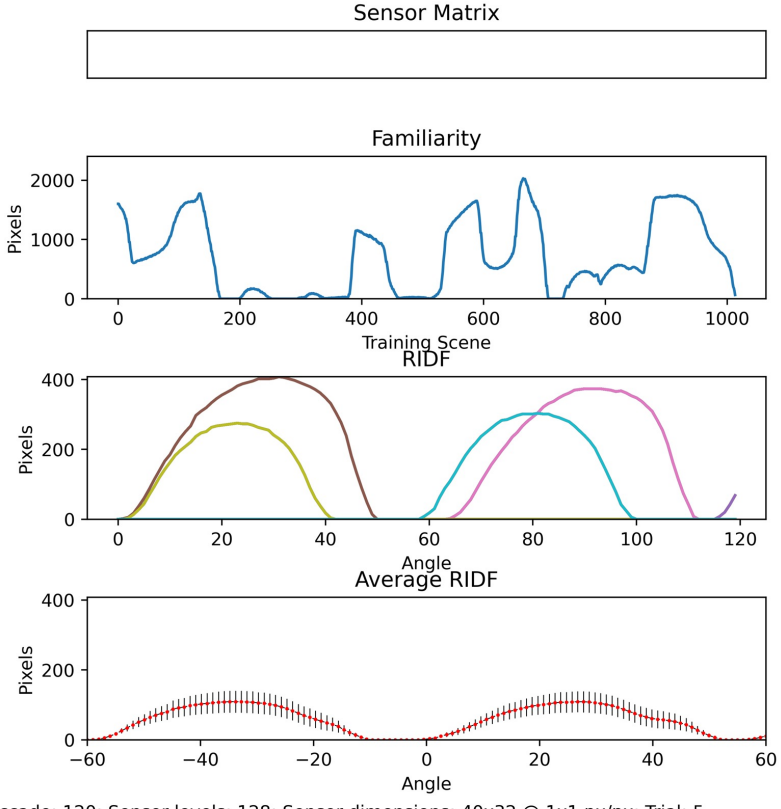

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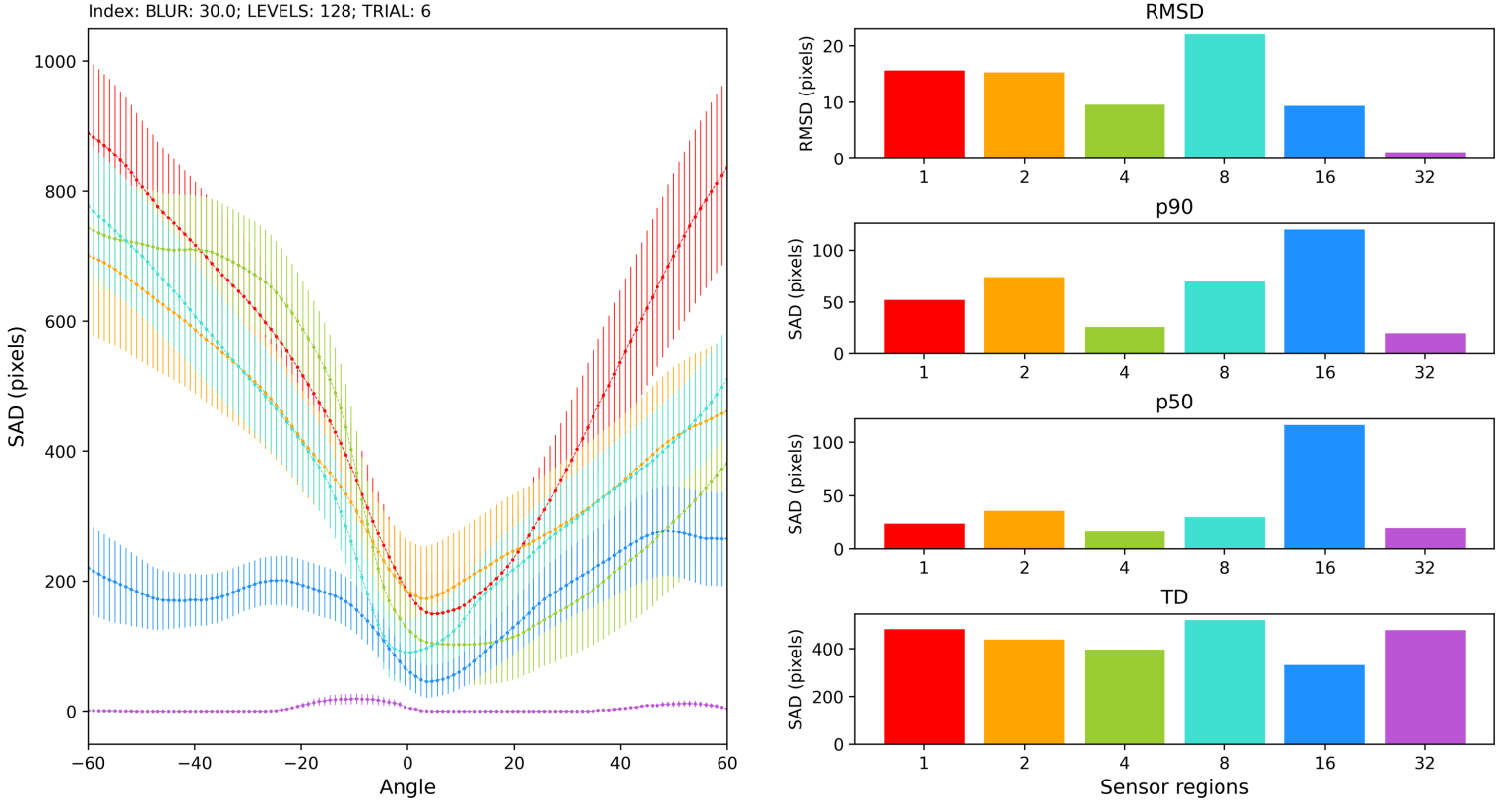
Index: BLUR: 30.0; LEVELS: 128; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

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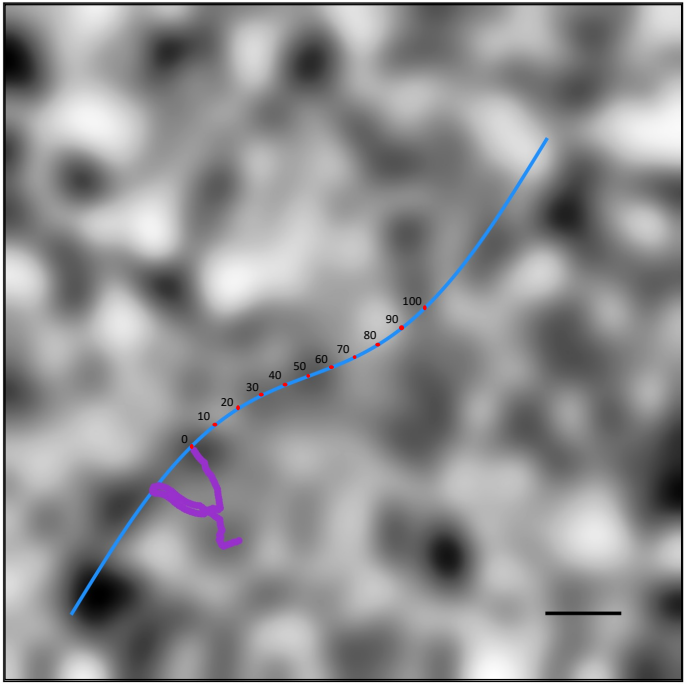

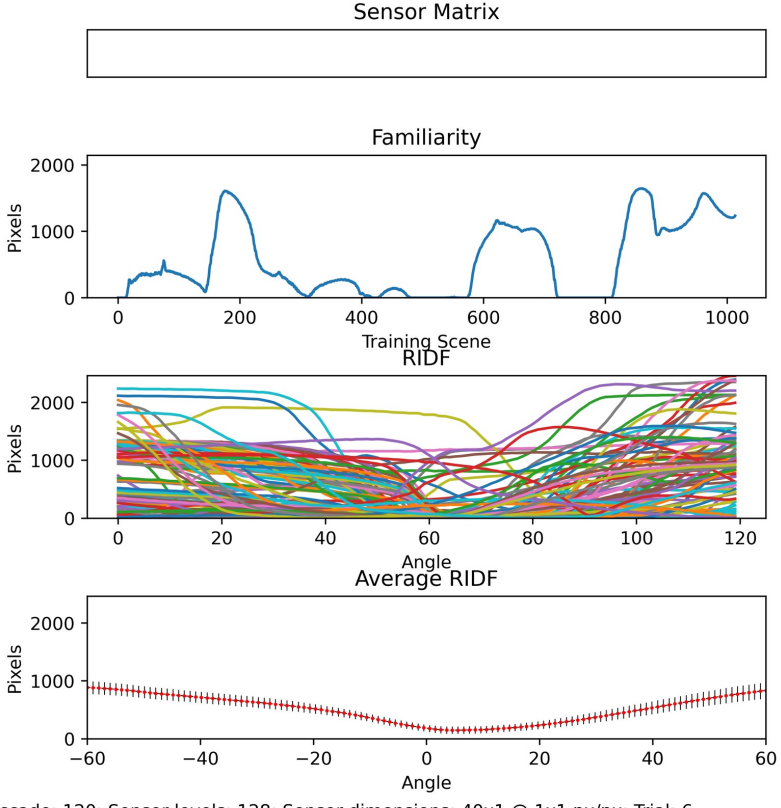

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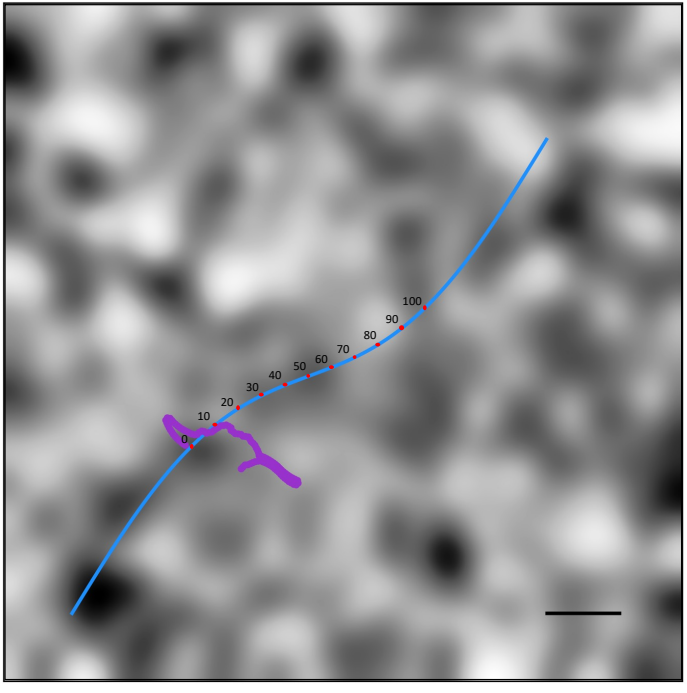

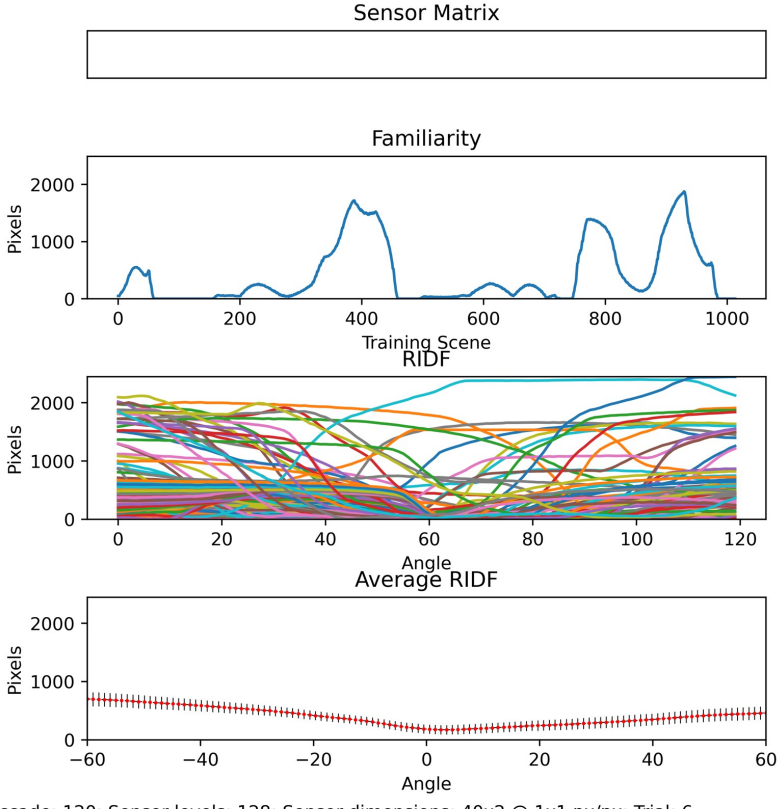

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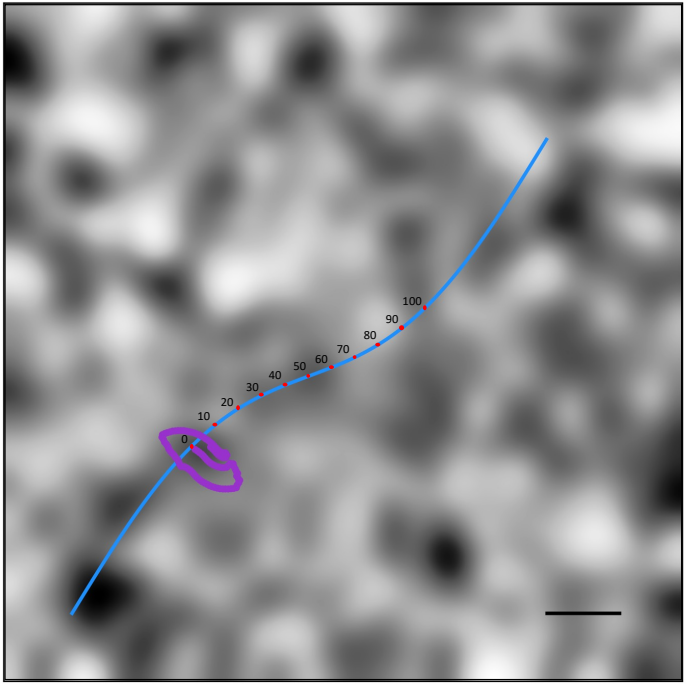

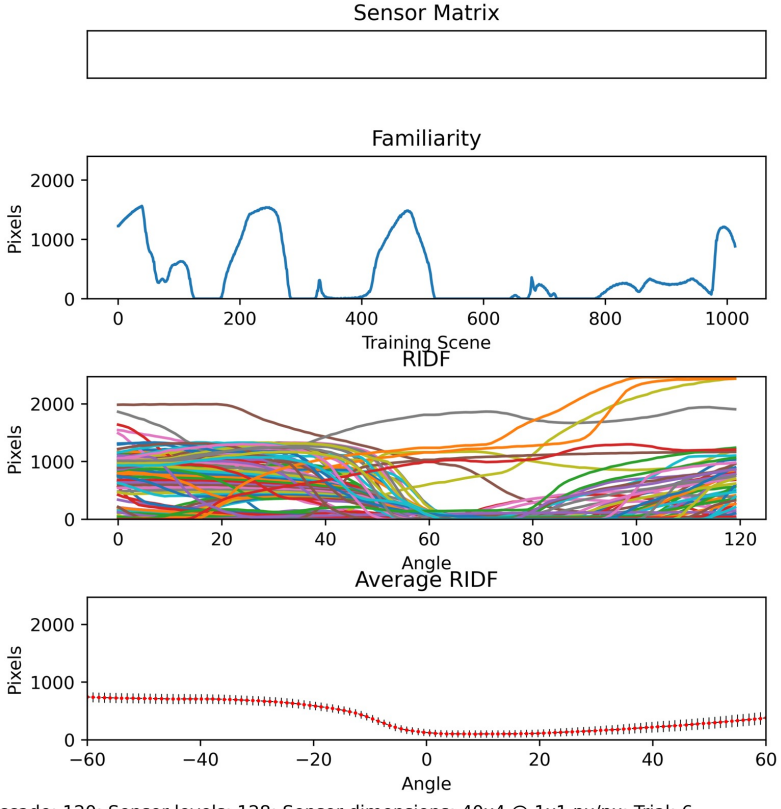

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Navigation stats: RMSD error: 3824.05; RMSD/dist: 9.560; TD: 396; p90: 26; p50: 16; complete: 0

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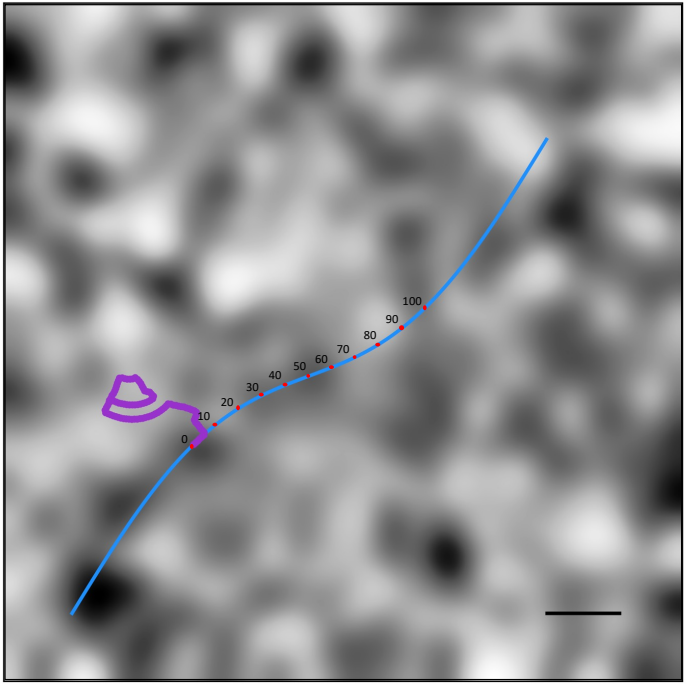

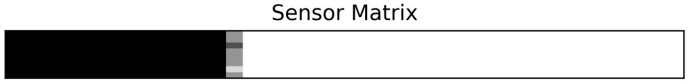

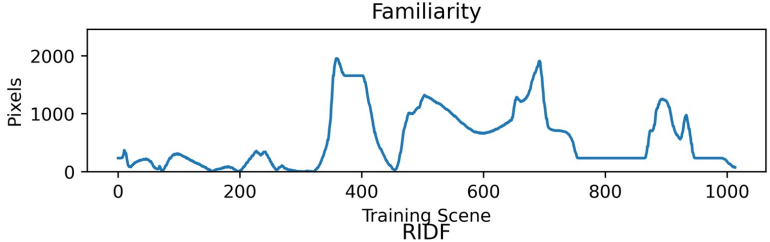

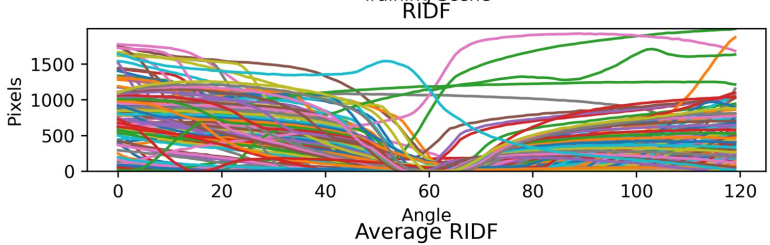

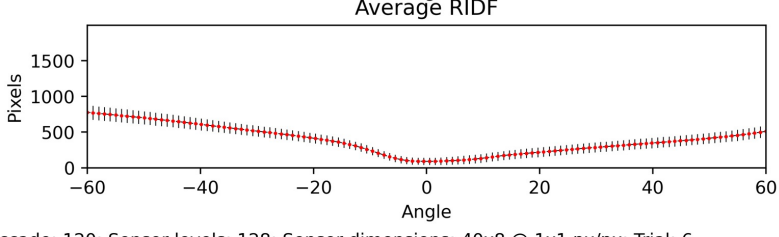

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 8828.79; RMSD/dist: 22.072; TD: 519; p90: 70; p50: 30; complete: 0

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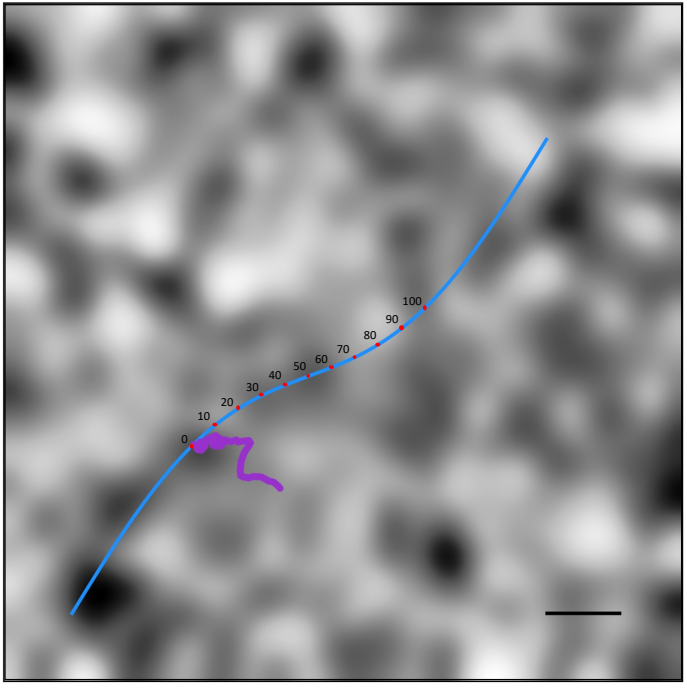

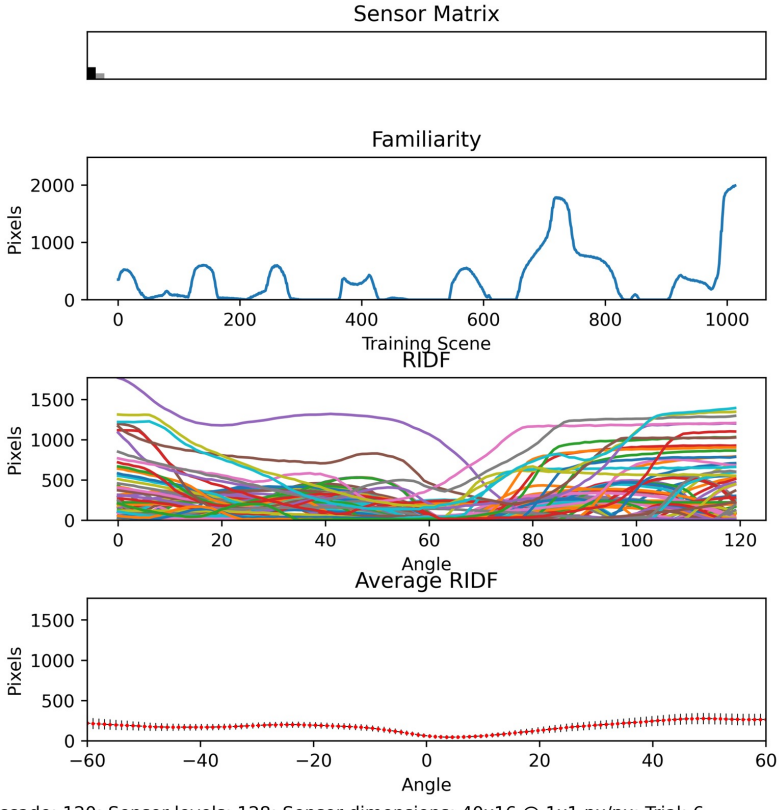

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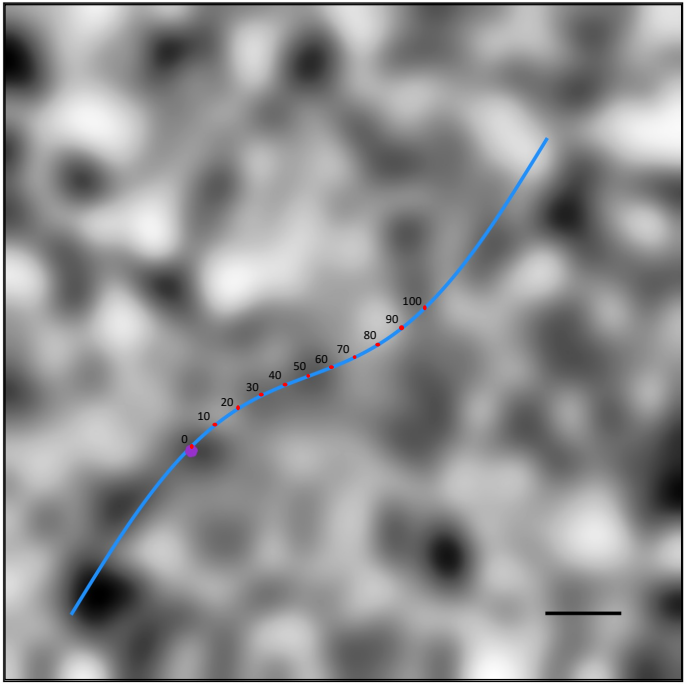

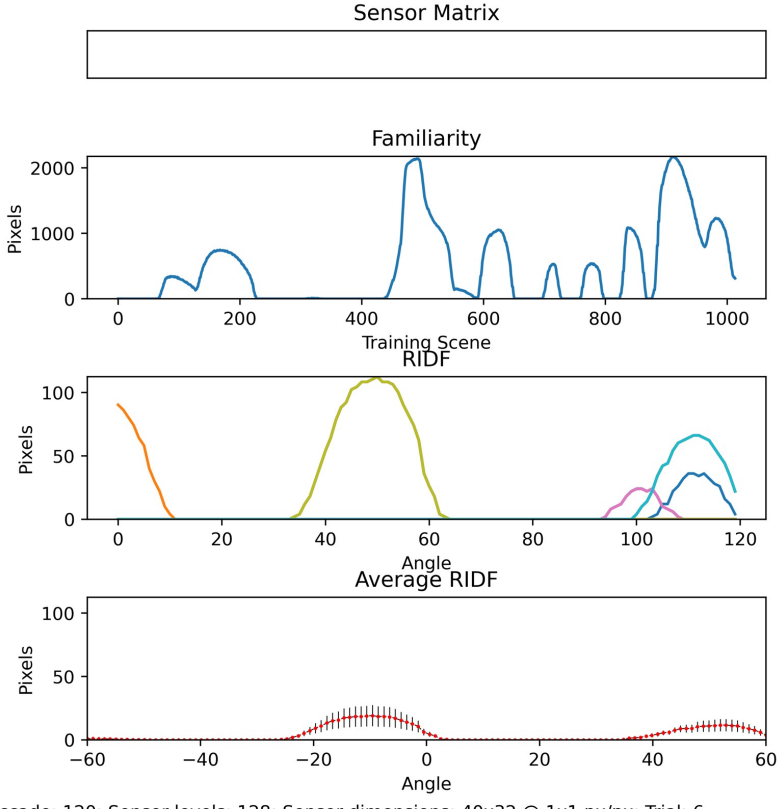

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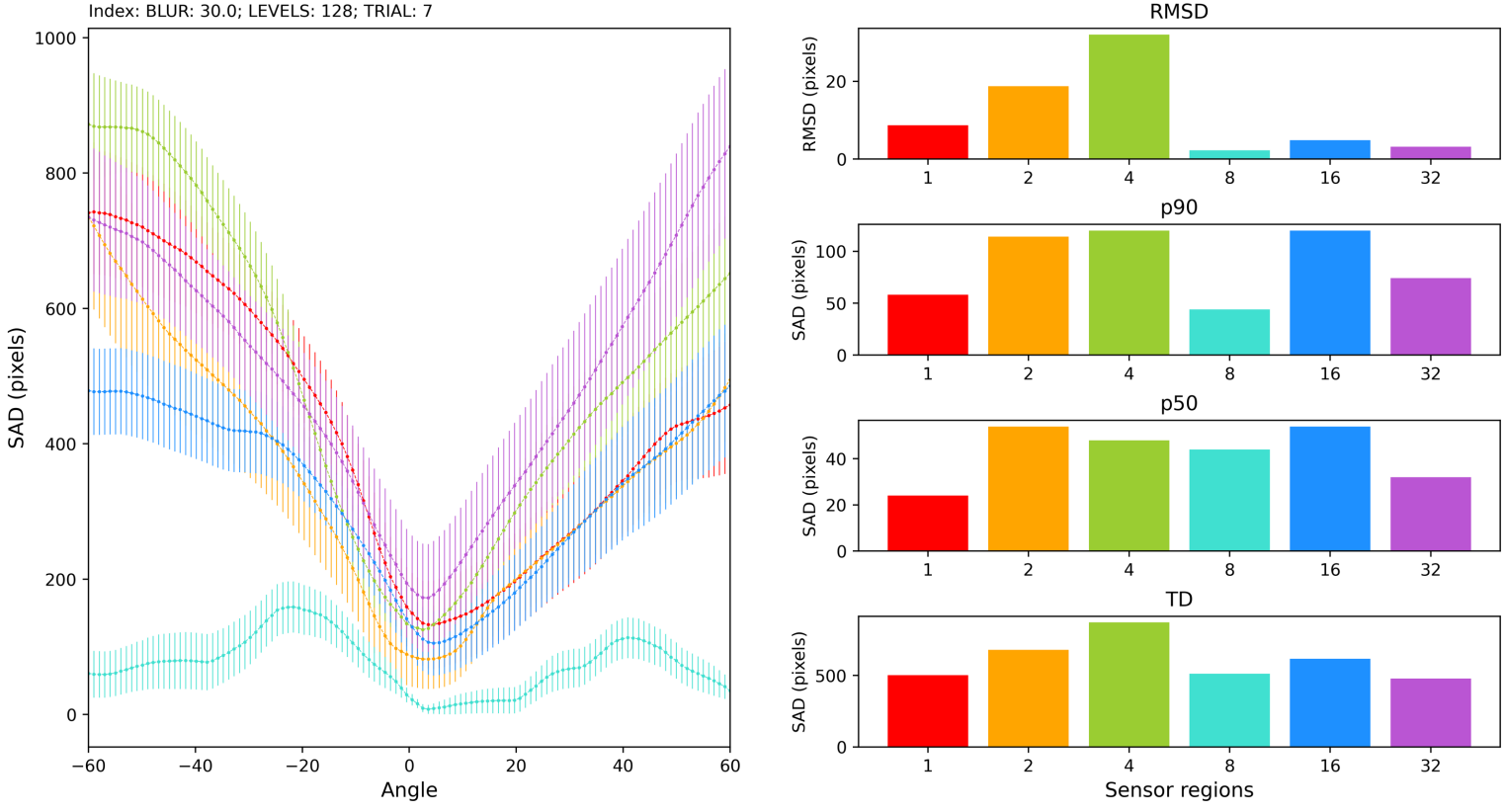
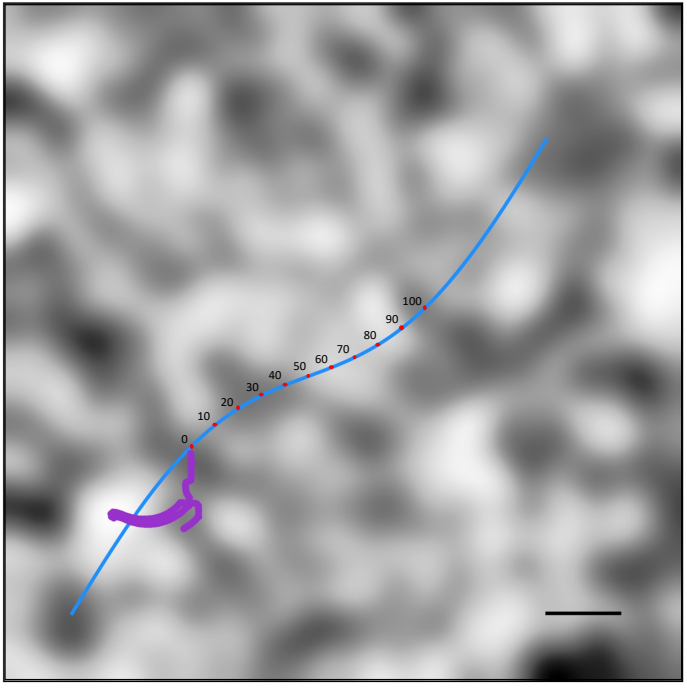
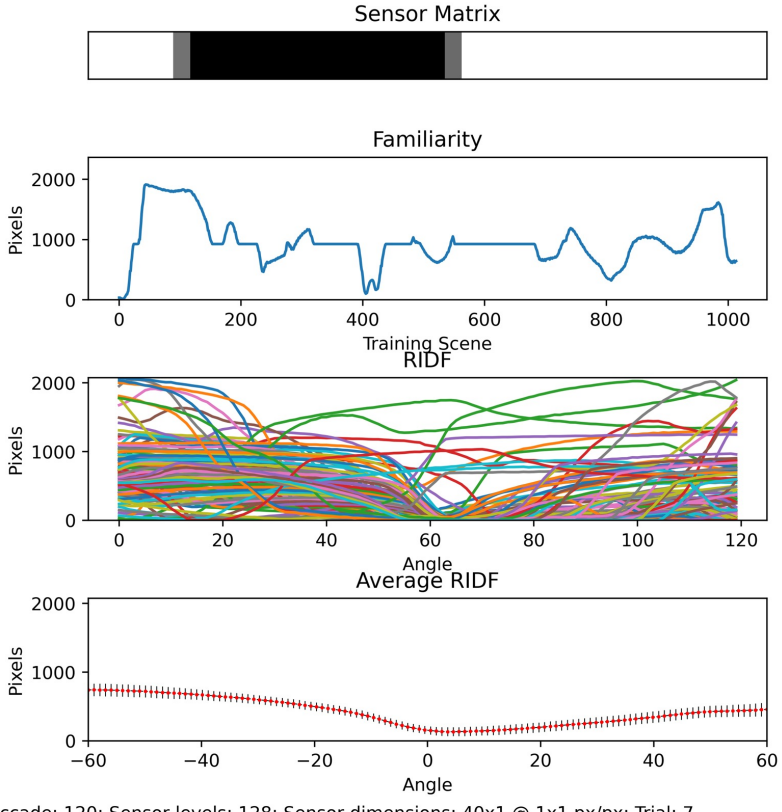
Navigation stats: RMSD error: 450.44; RMSD/dist: 1.126; TD: 477; p90: 20; p50: 20; complete: 0


Index: BLUR: 30.0; LEVELS: 128; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





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Navigation stats: RMSD error: 3477.94; RMSD/dist: 8.695; TD: 502; p90: 58; p50: 24; complete: 0

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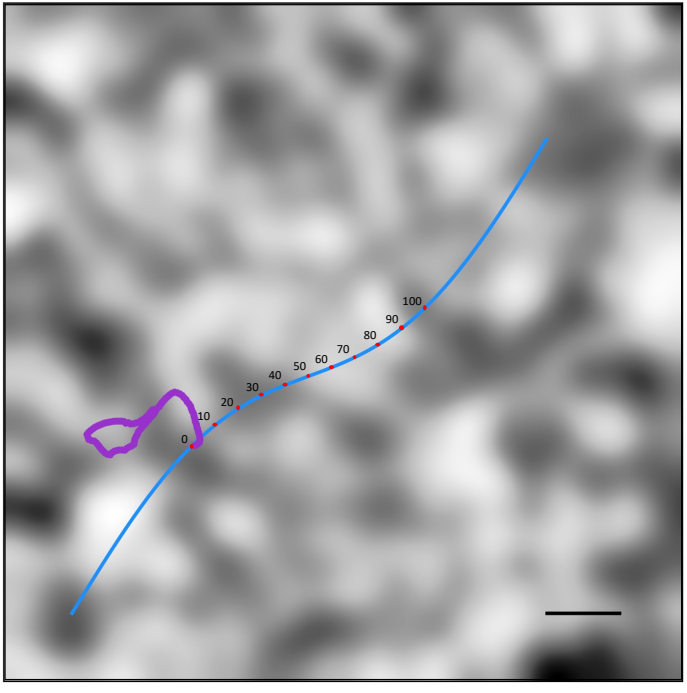

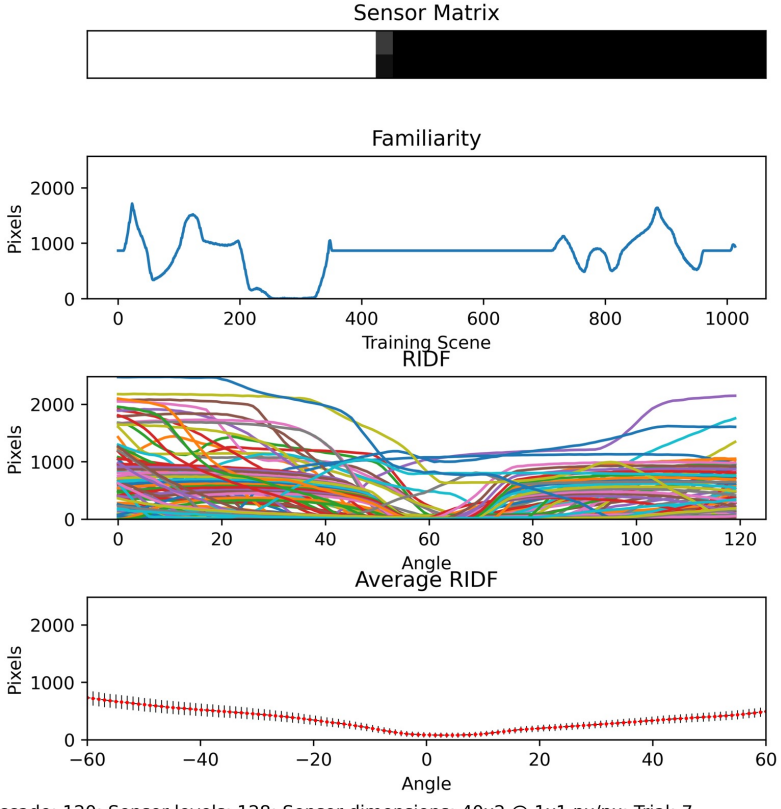

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 7499.88; RMSD/dist: 18.750; TD: 678; p90: 114; p50: 54; complete: 0

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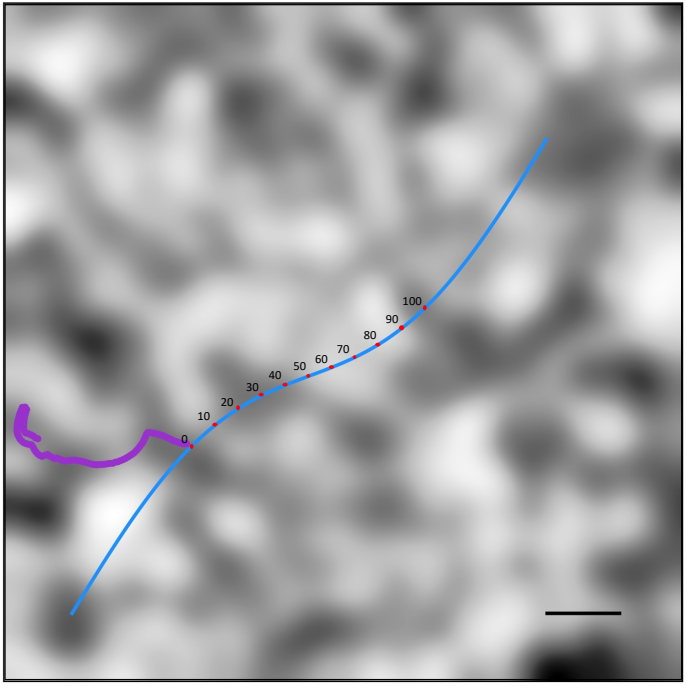

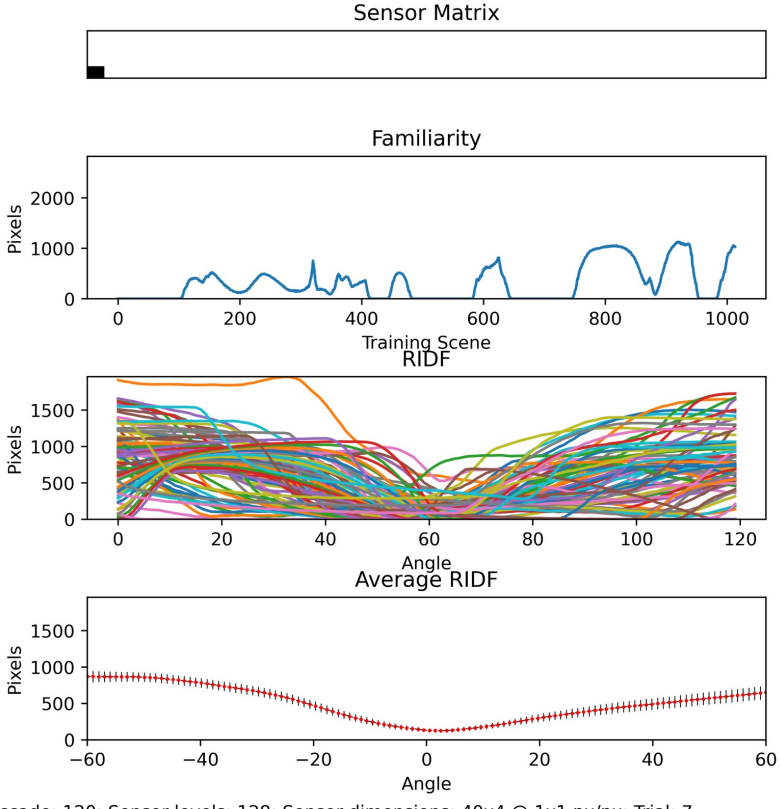

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Navigation stats: RMSD error: 12809.85; RMSD/dist: 32.025; TD: 870; p90: 120; p50: 48; complete: 0

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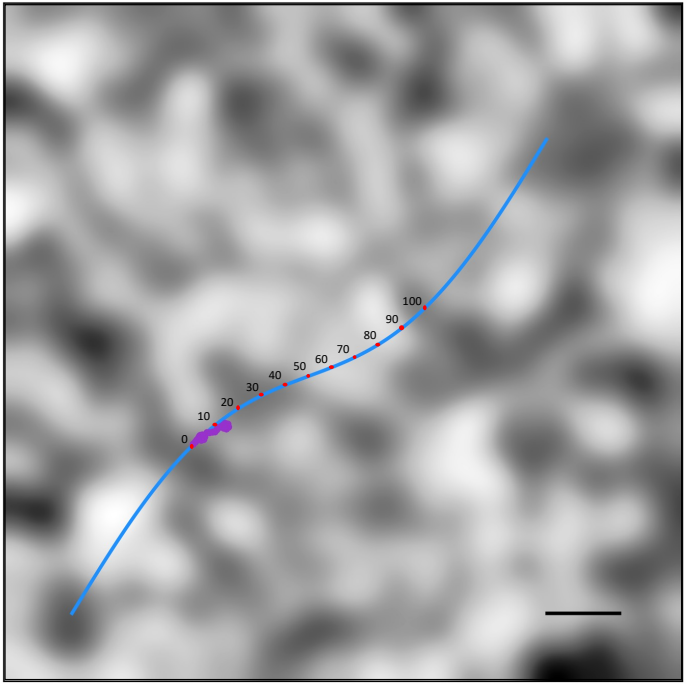
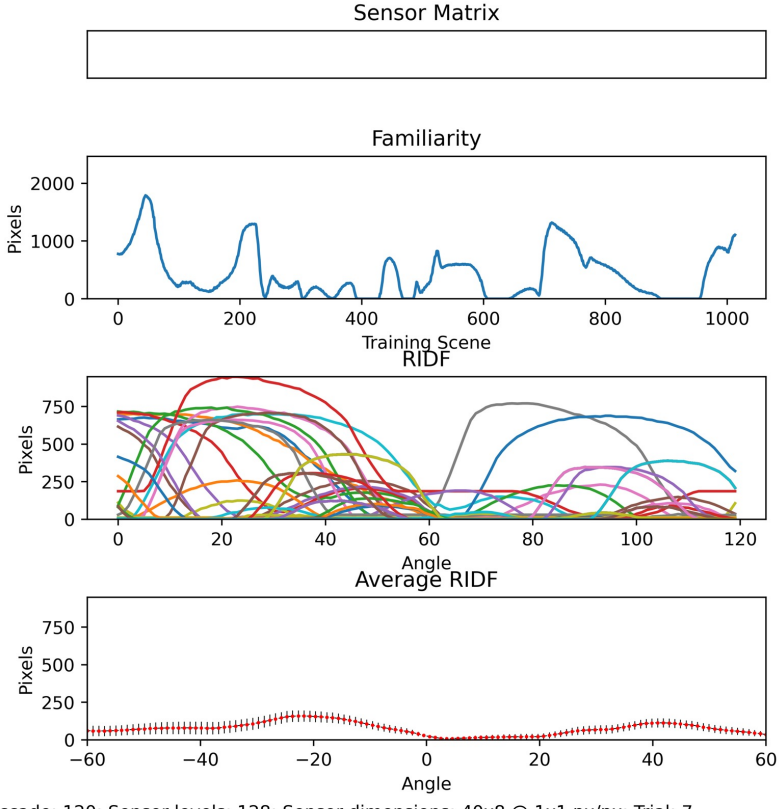
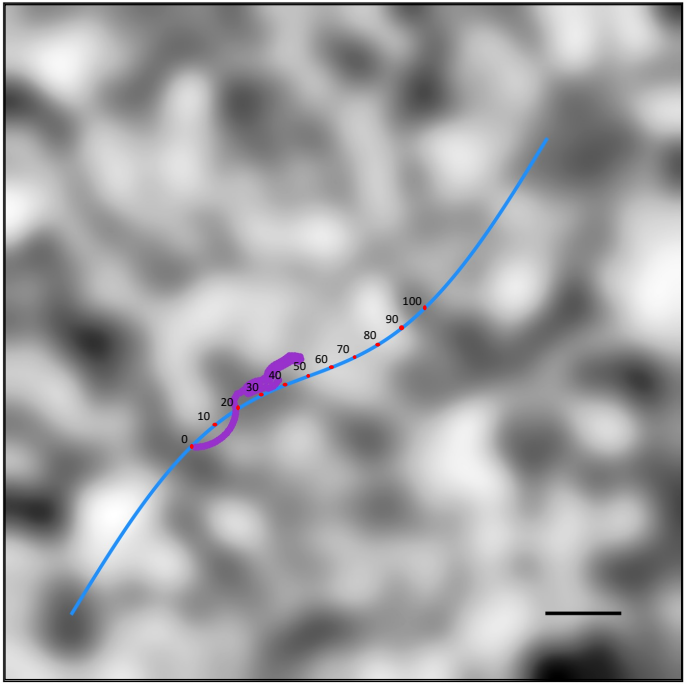
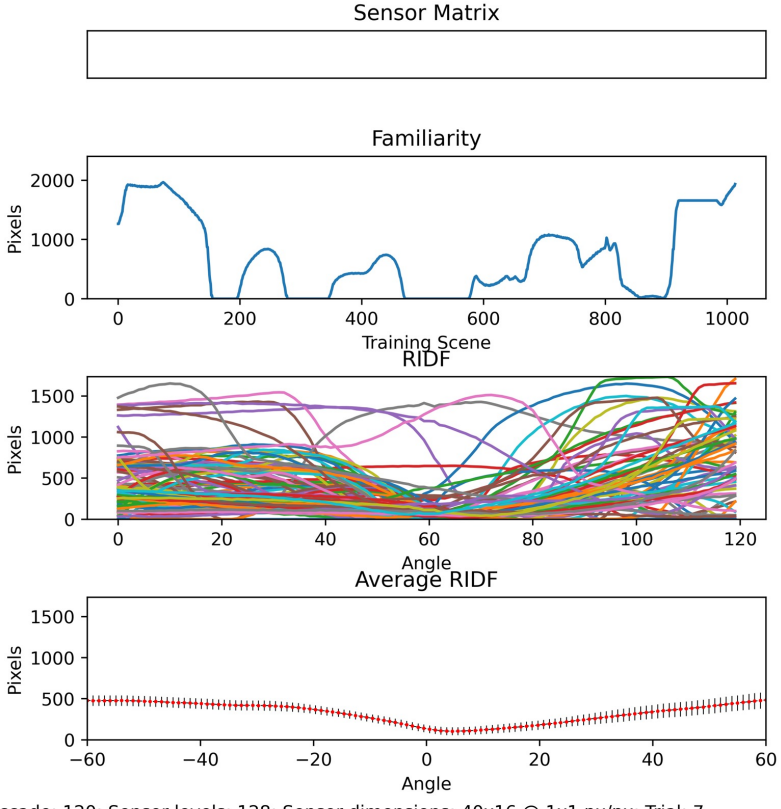




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 894.79; RMSD/dist: 2.237; TD: 512; p90: 44; p50: 44; complete: 0

0%

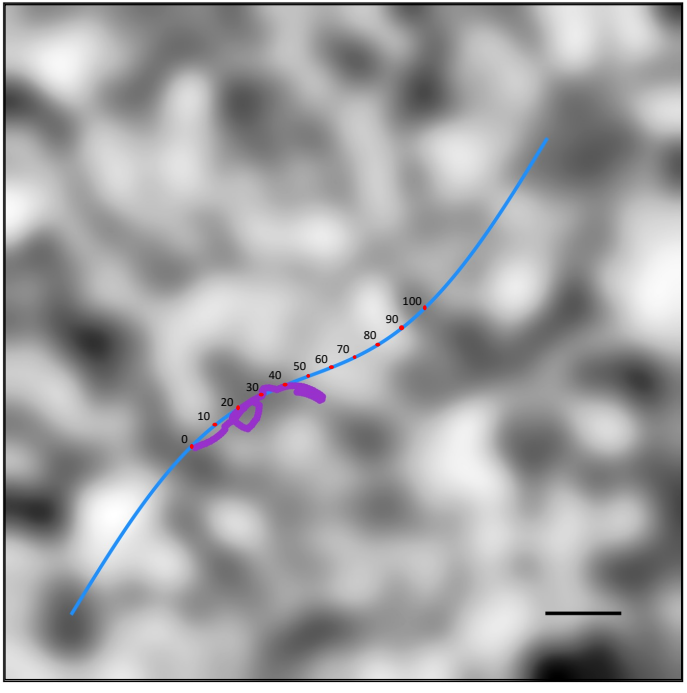


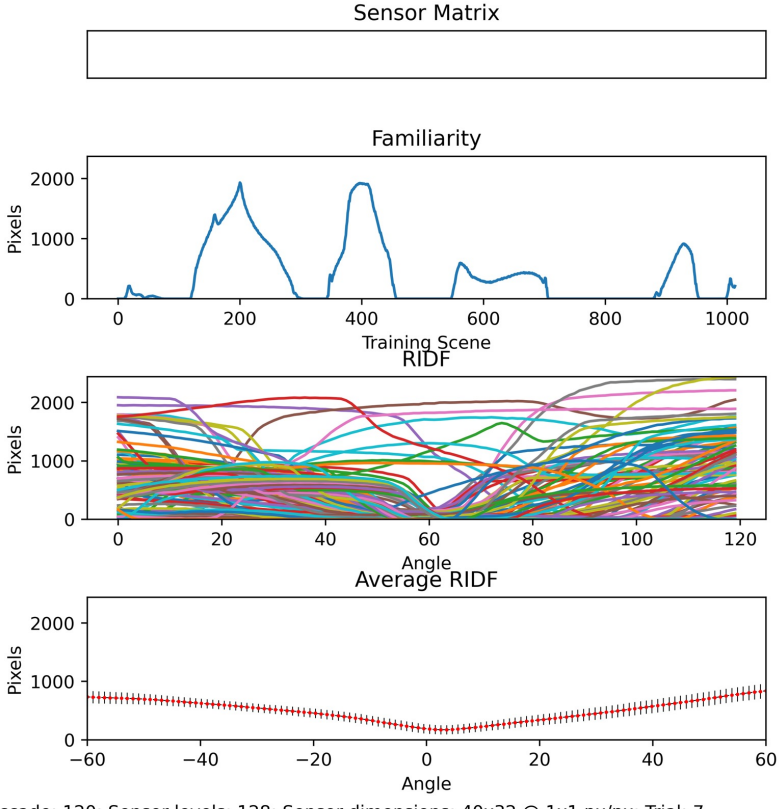


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1938.19; RMSD/dist: 4.845; TD: 617; p90: 120; p50: 54; complete: 0

10%





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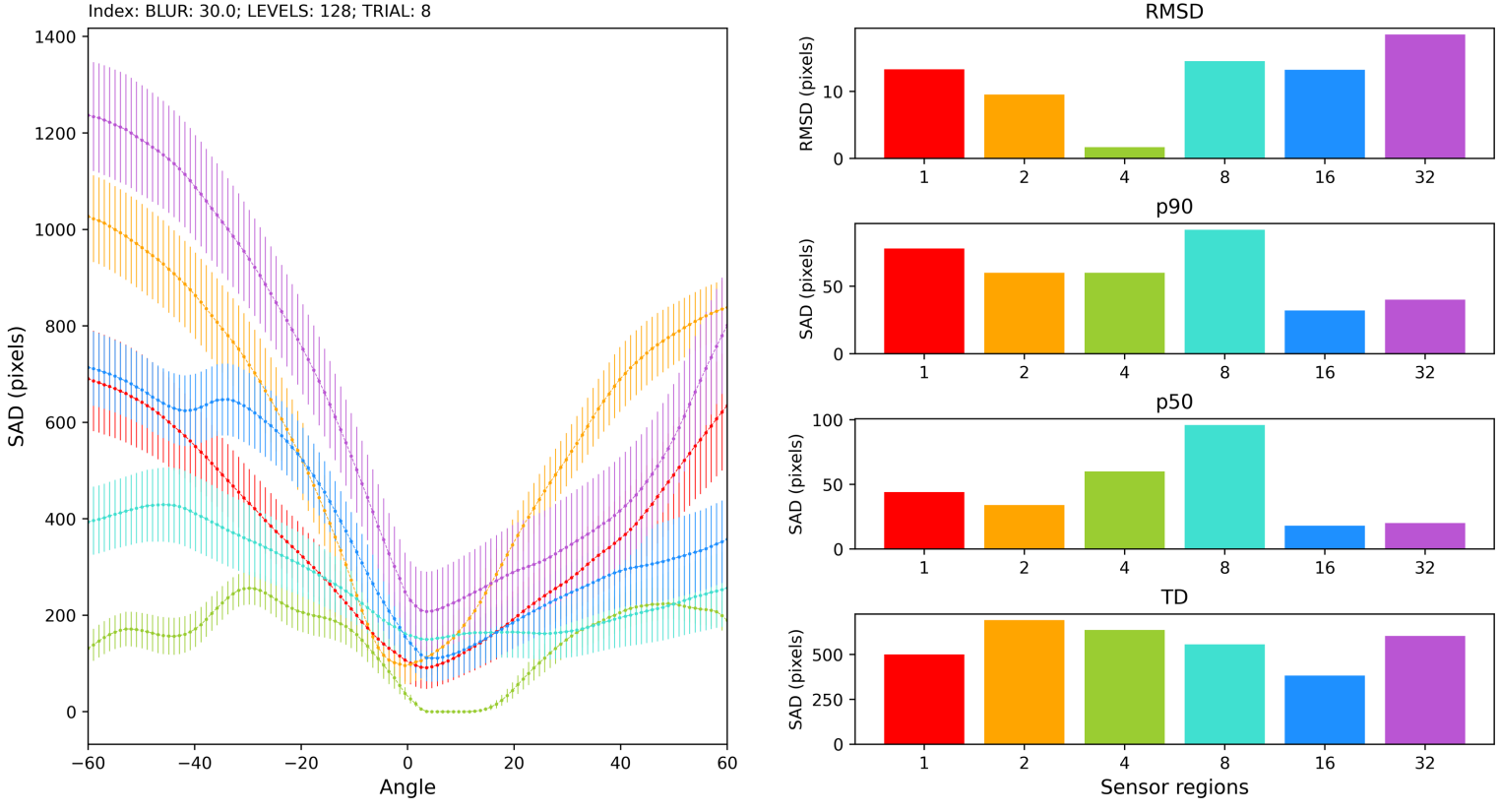
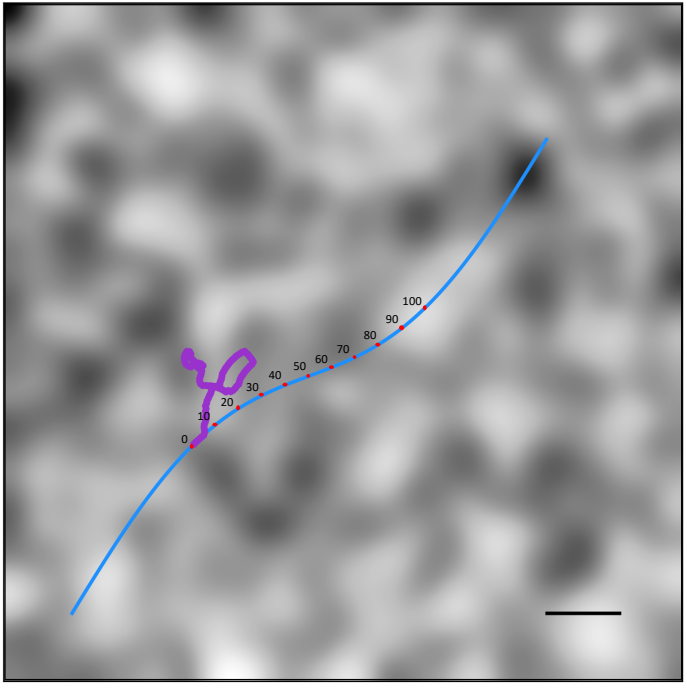
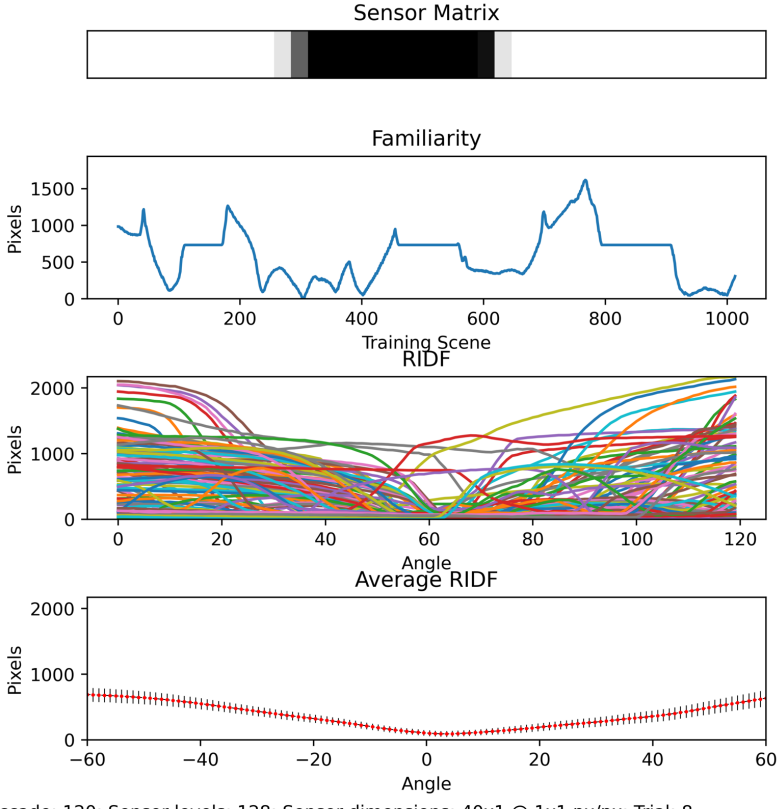
Navigation stats: RMSD error: 1262.48; RMSD/dist: 3.156; TD: 478; p90: 74; p50: 32; complete: 0


Index: BLUR: 30.0; LEVELS: 128; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





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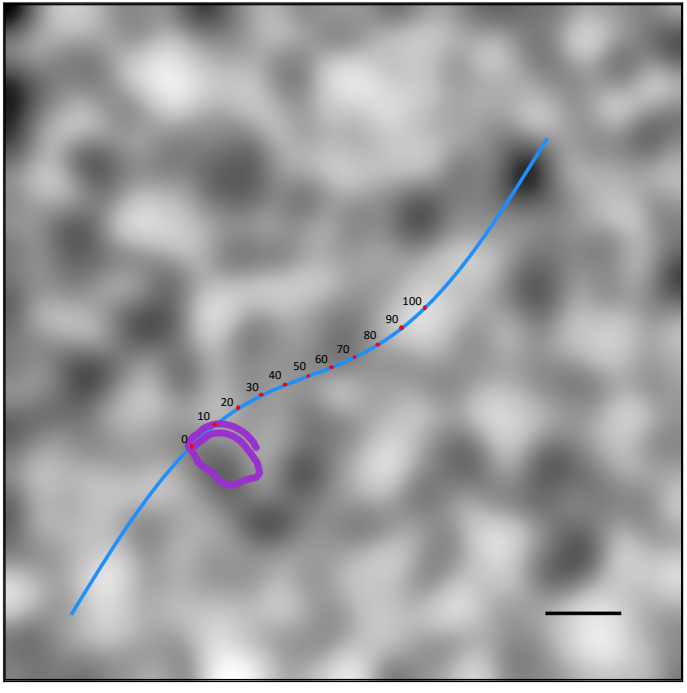
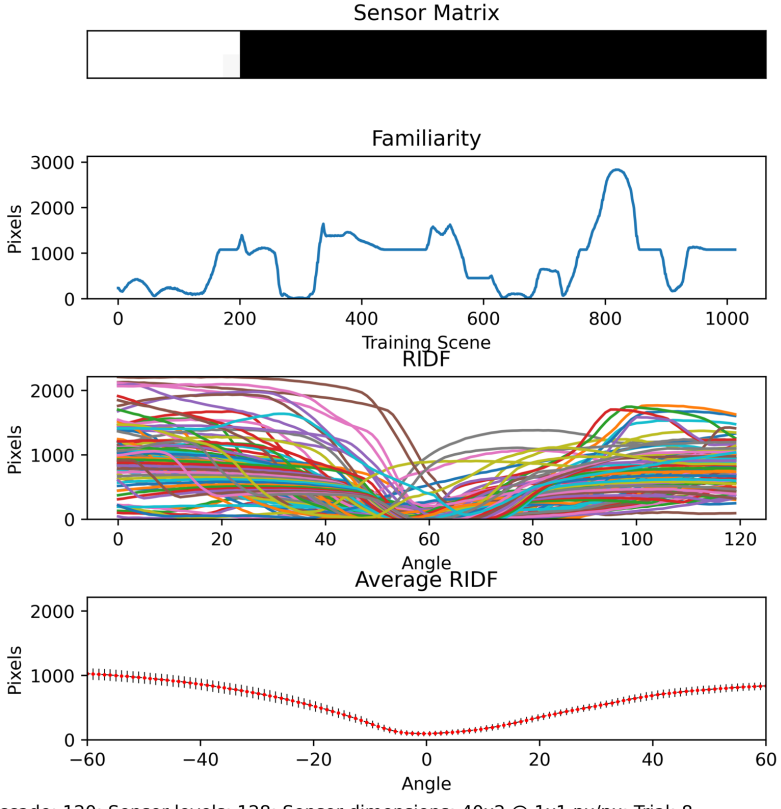
Navigation stats: RMSD error: 5332.45; RMSD/dist: 13.331; TD: 500; p90: 78; p50: 44; complete: 0

0%





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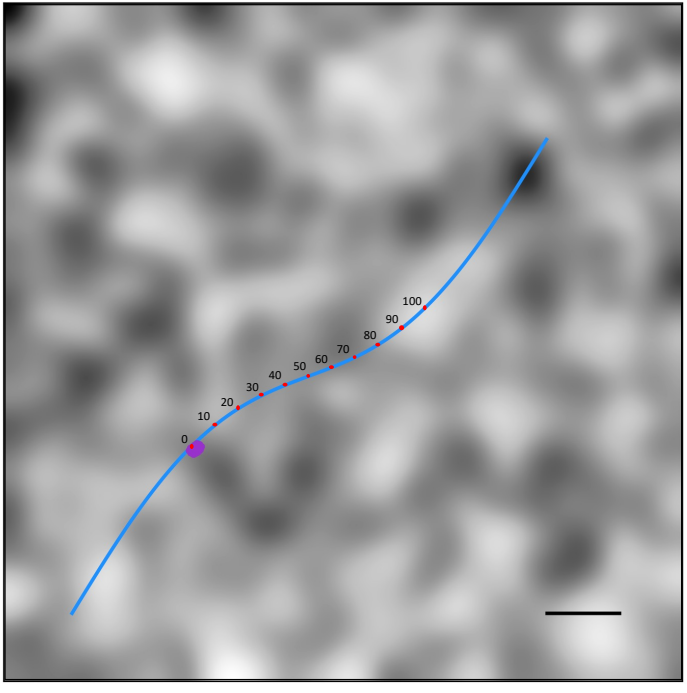
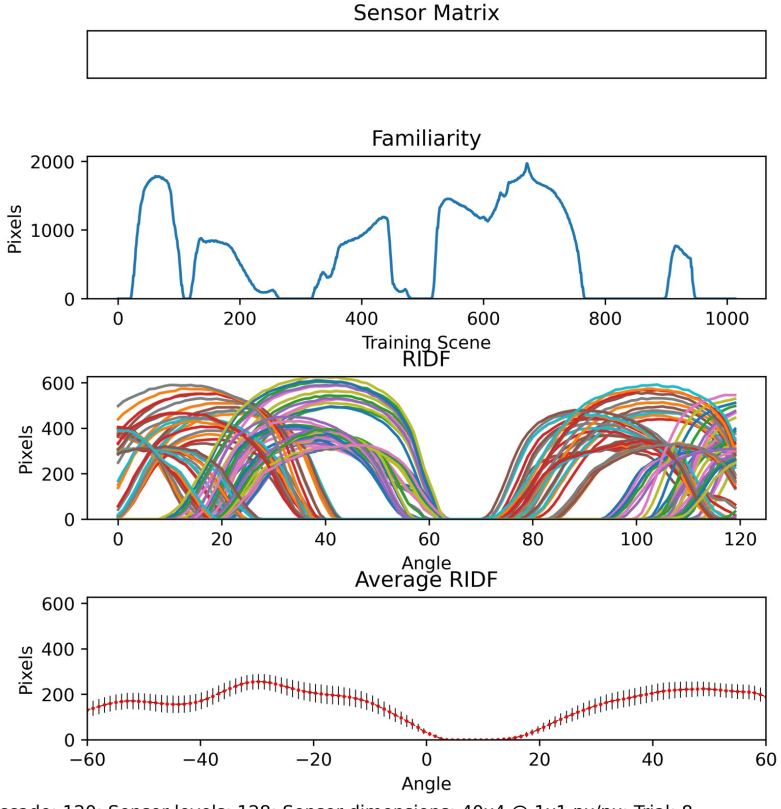
Navigation stats: RMSD error: 3817.88; RMSD/dist: 9.545; TD: 691; p90: 60; p50: 34; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 670.82; RMSD/dist: 1.677; TD: 637; p90: 60; p50: 60; complete: 0

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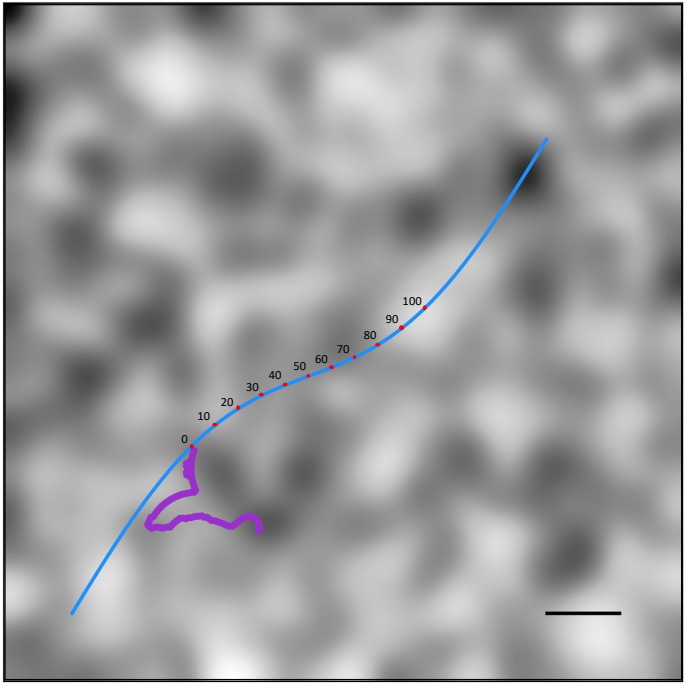

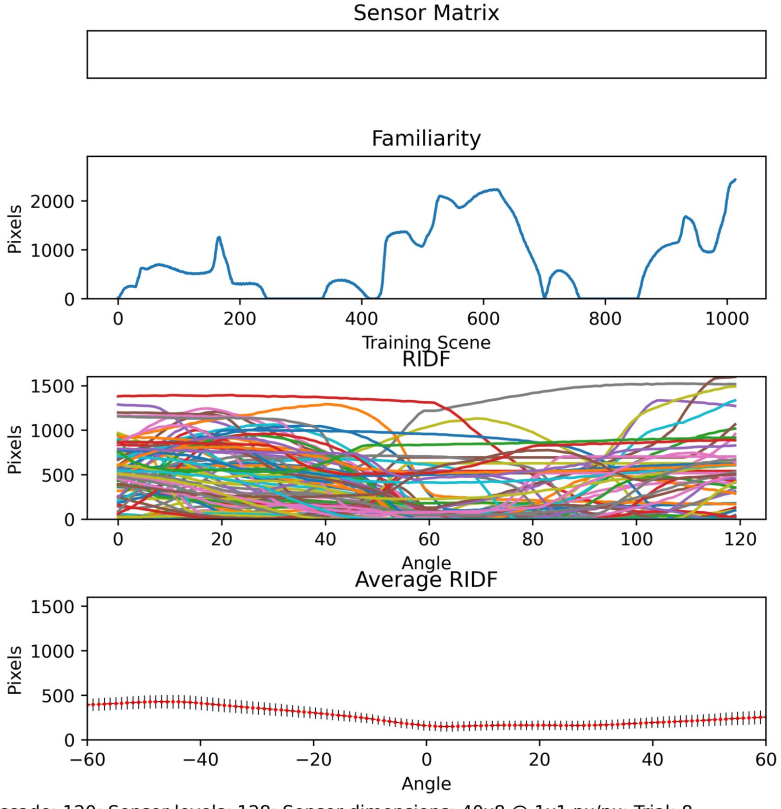

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5810.67; RMSD/dist: 14.527; TD: 557; p90: 92; p50: 96; complete: 0

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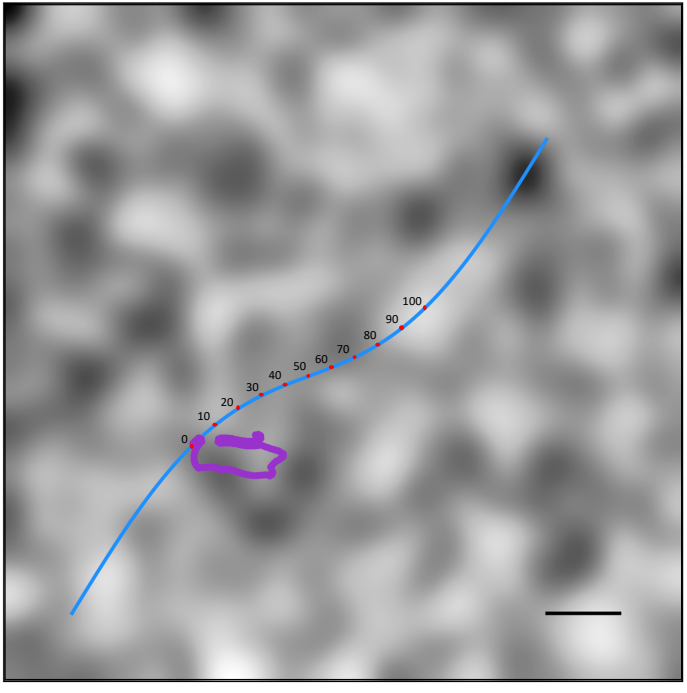
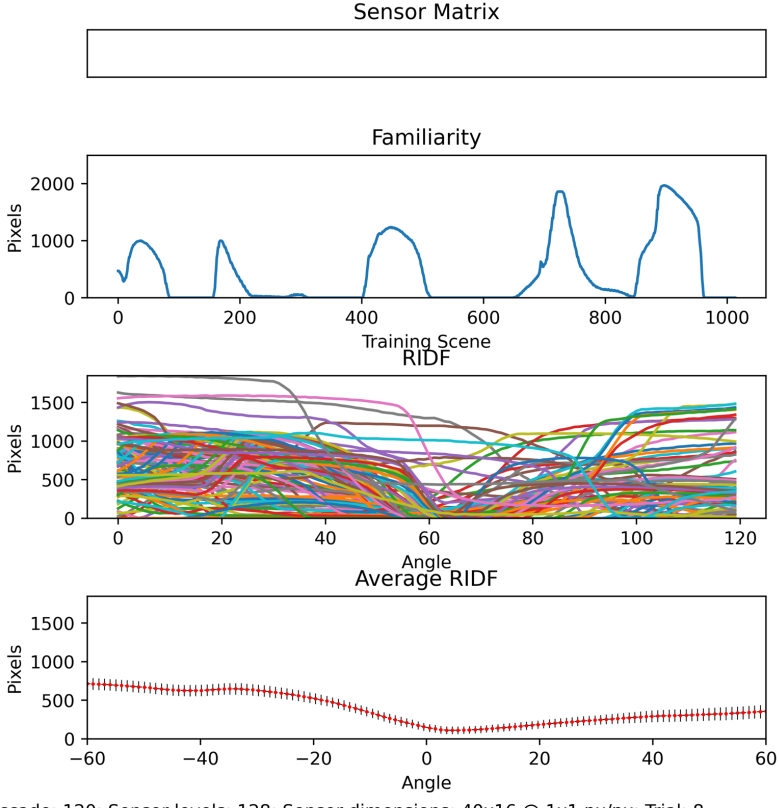
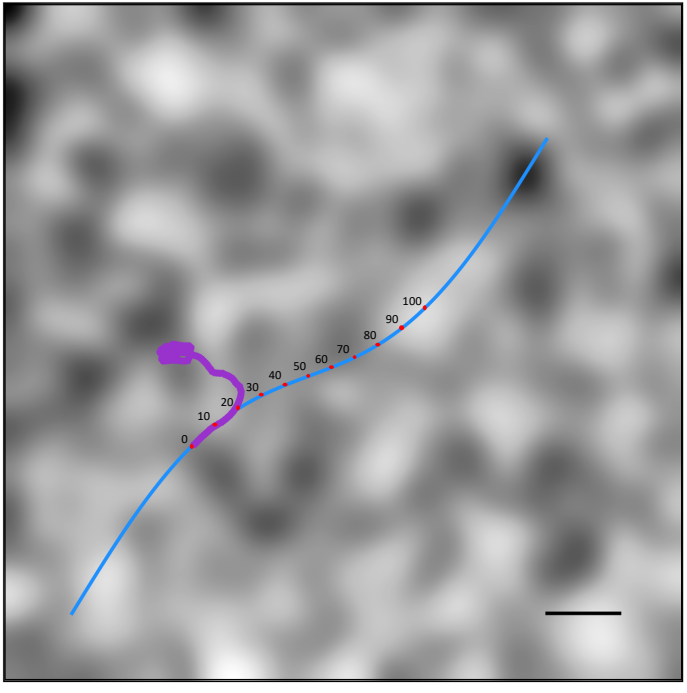


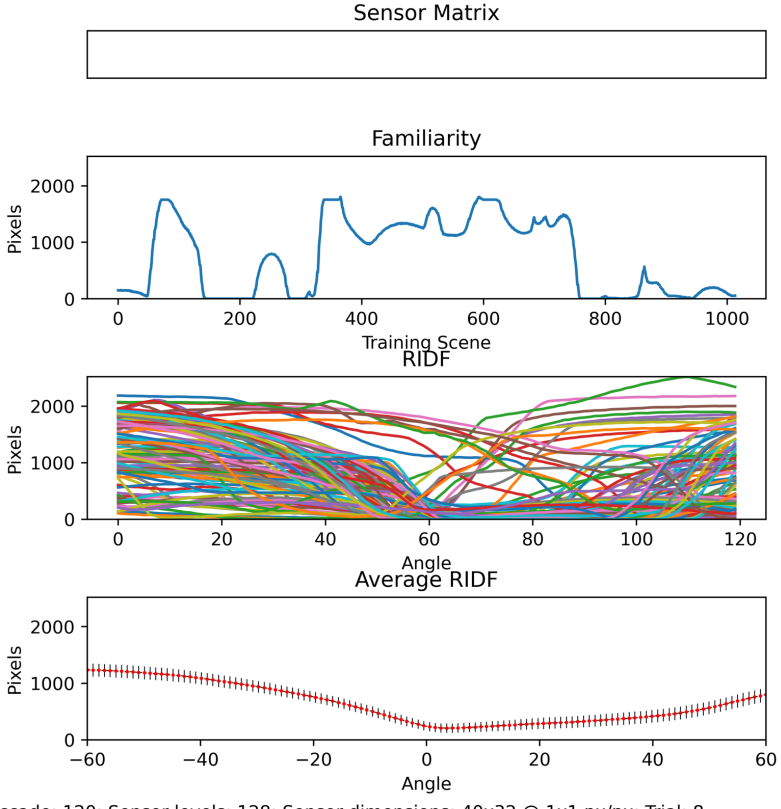


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5304.44; RMSD/dist: 13.261; TD: 383; p90: 32; p50: 18; complete: 0

20%





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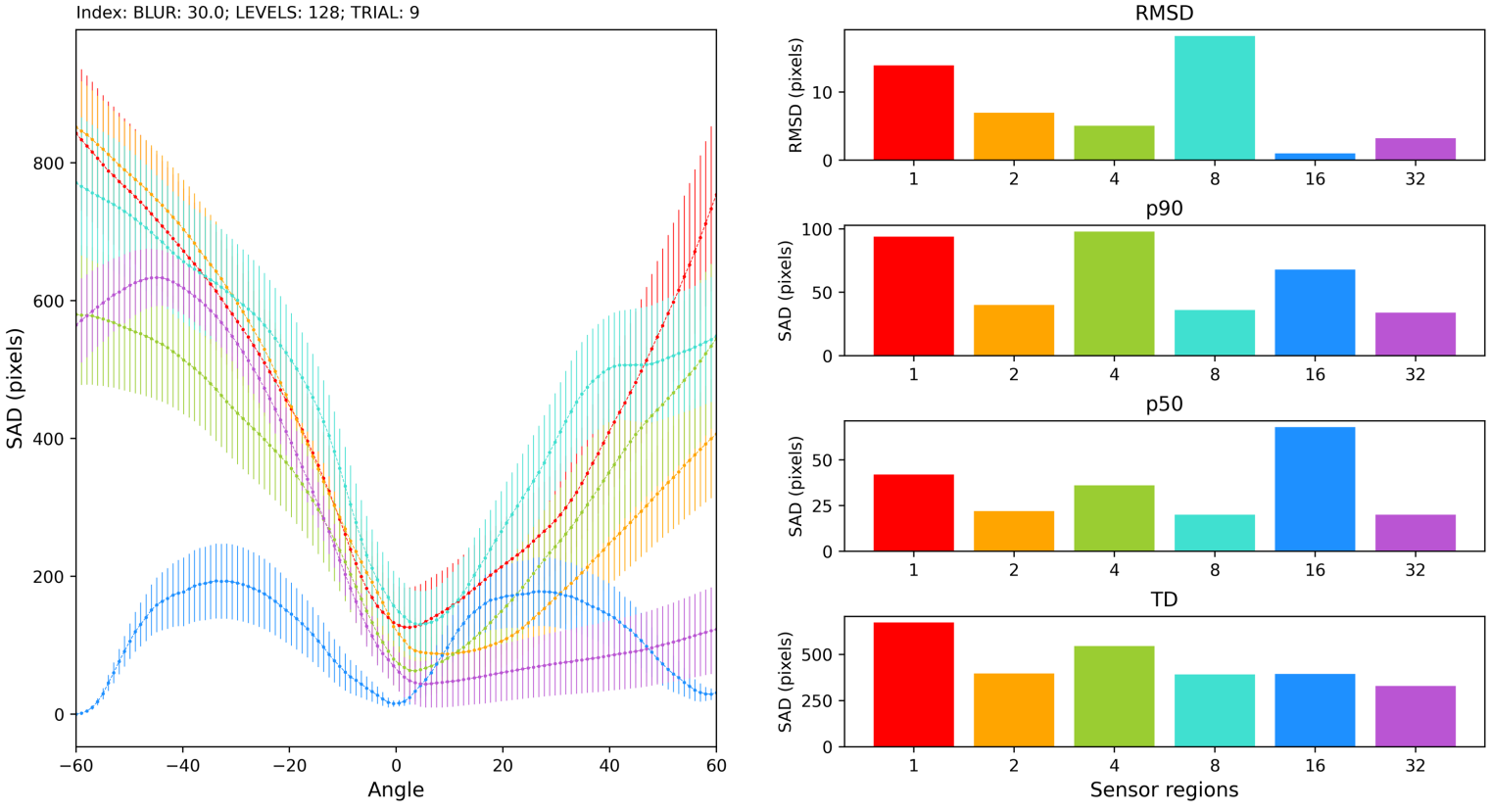
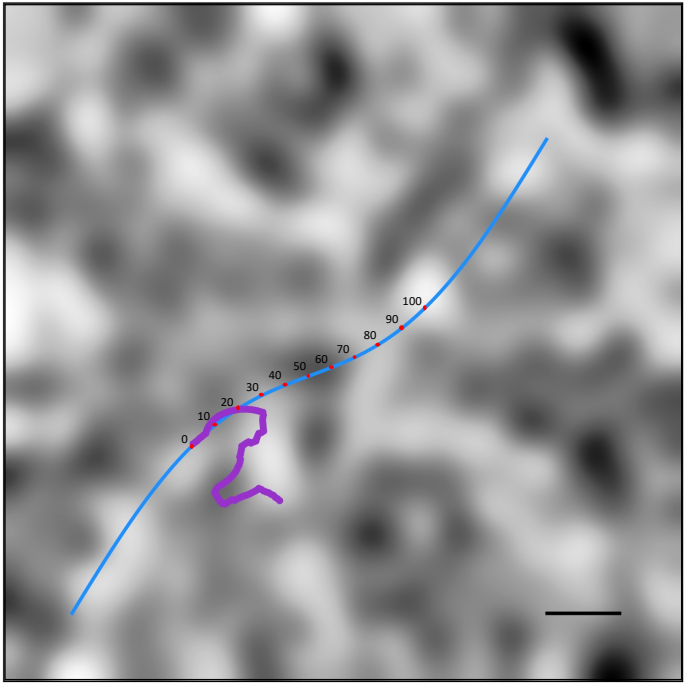
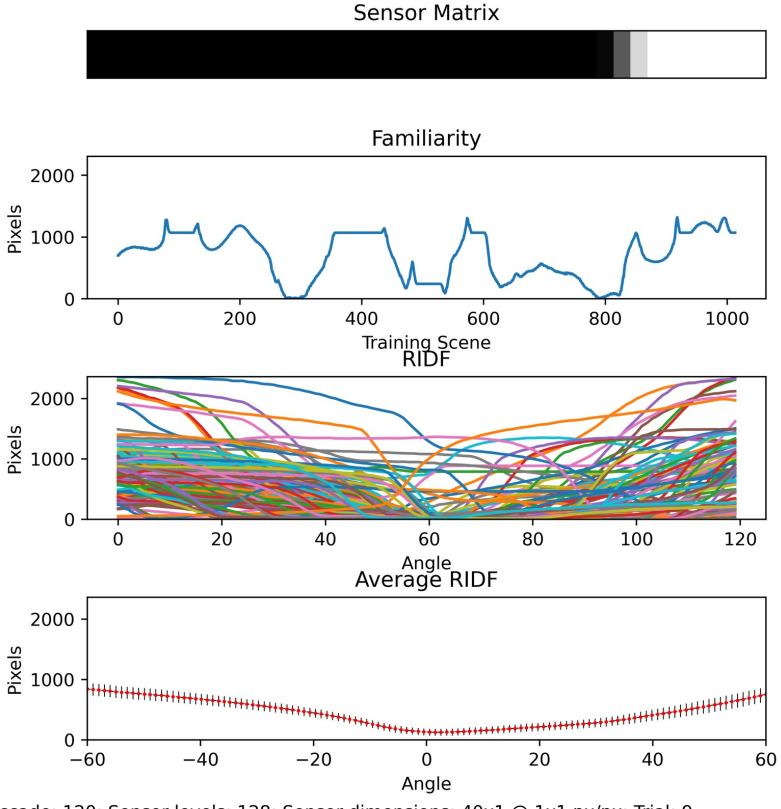

Index: BLUR: 30.0; LEVELS: 128; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

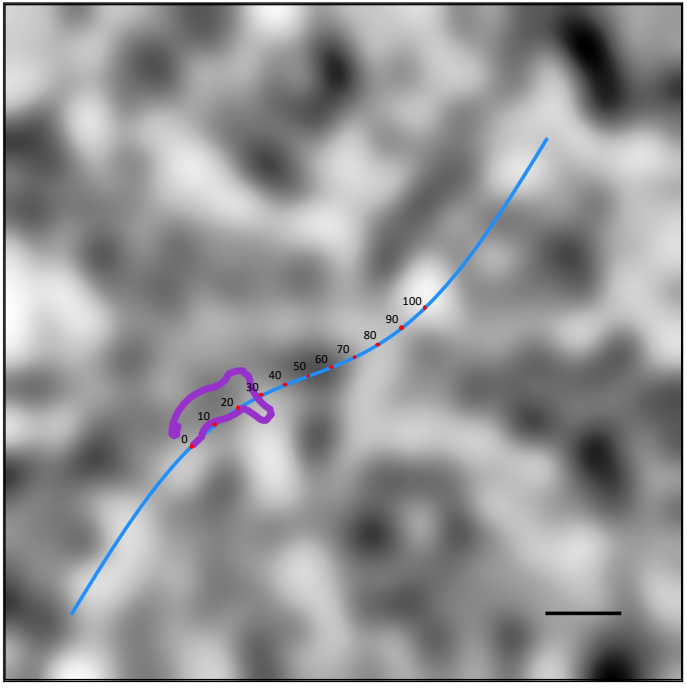
0%

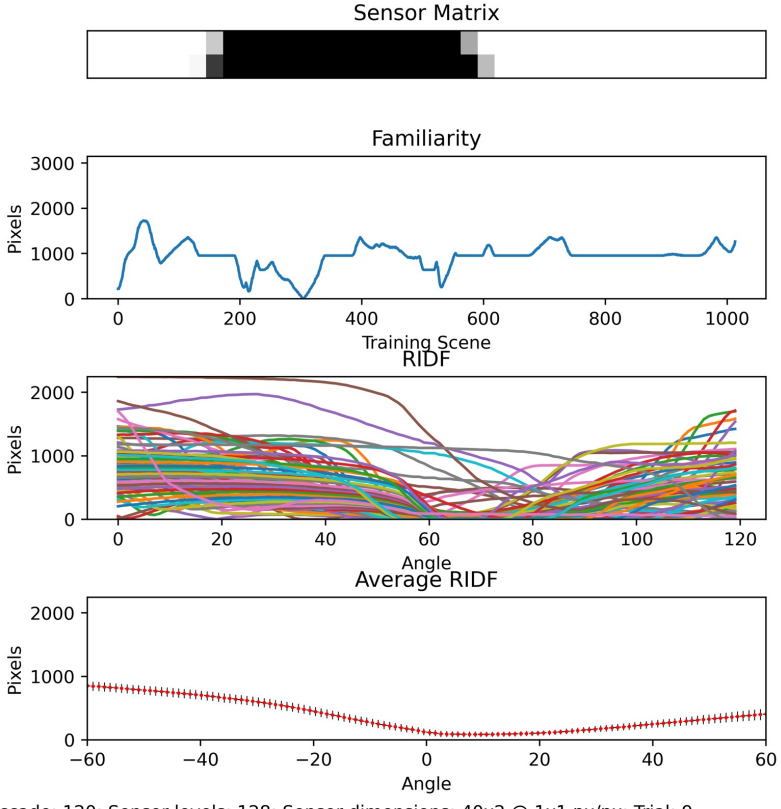




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 5568.94; RMSD/dist: 13.922; TD: 672; p90: 94; p50: 42; complete: 0

10%





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Navigation stats: RMSD error: 2789.04; RMSD/dist: 6.973; TD: 397; p90: 40; p50: 22; complete: 0

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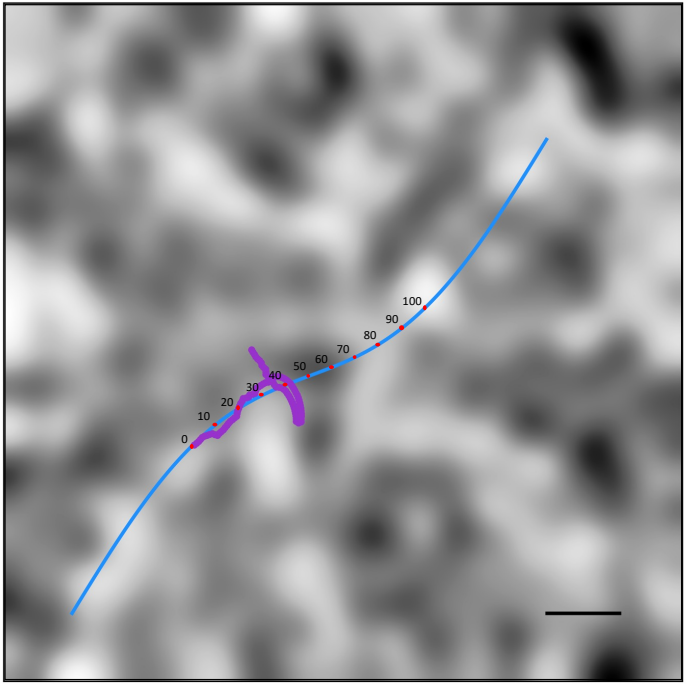

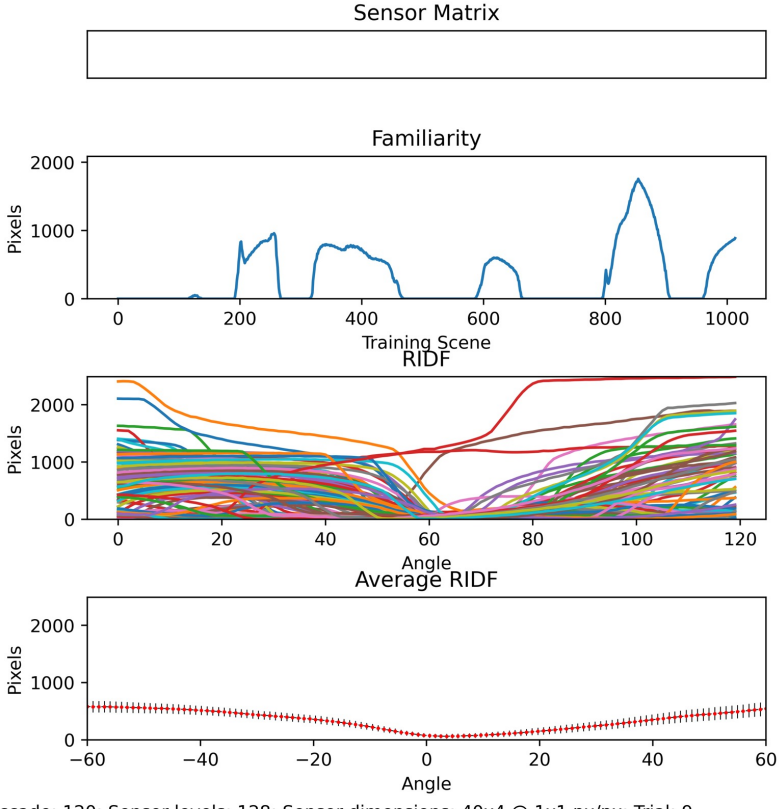

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2024.57; RMSD/dist: 5.061; TD: 545; p90: 98; p50: 36; complete: 0

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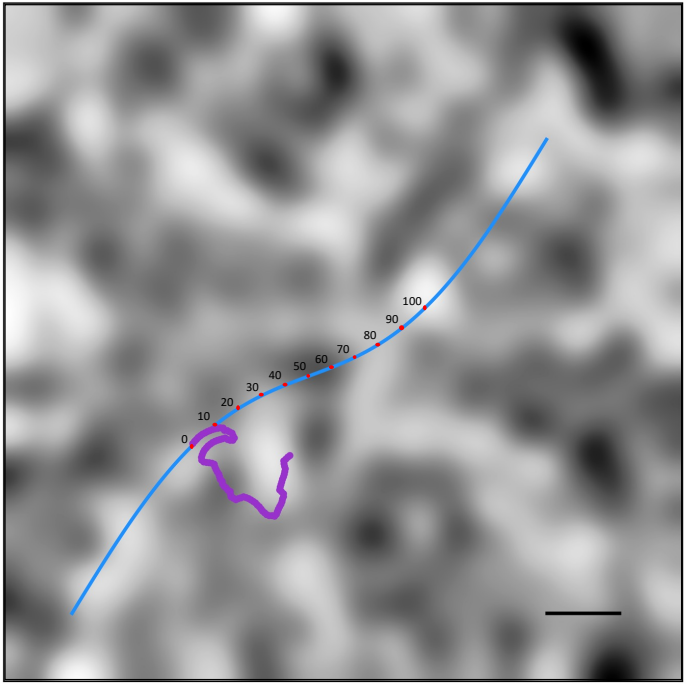

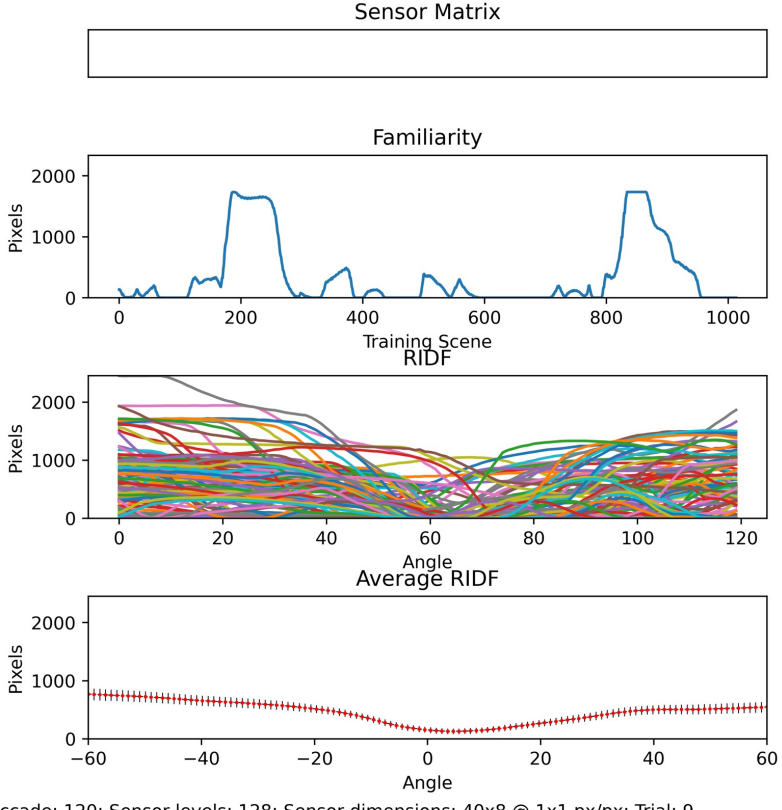

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 7305.82; RMSD/dist: 18.265; TD: 392; p90: 36; p50: 20; complete: 0

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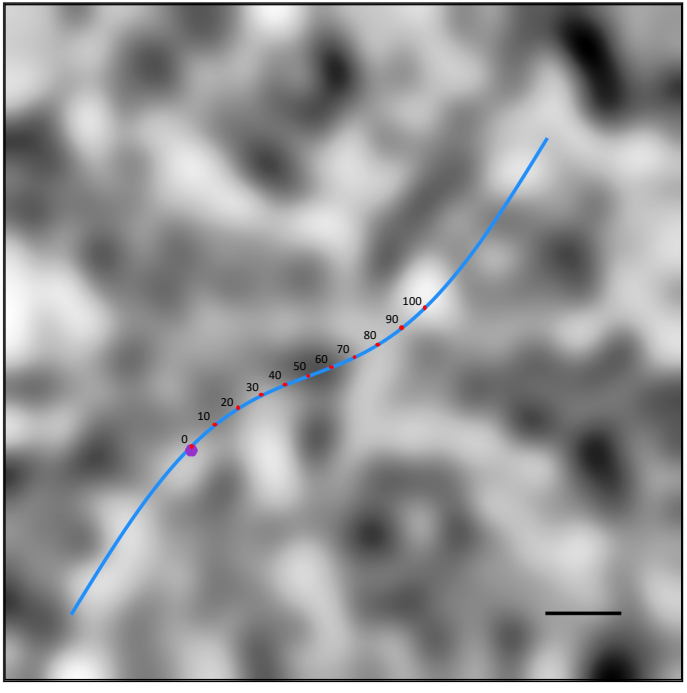

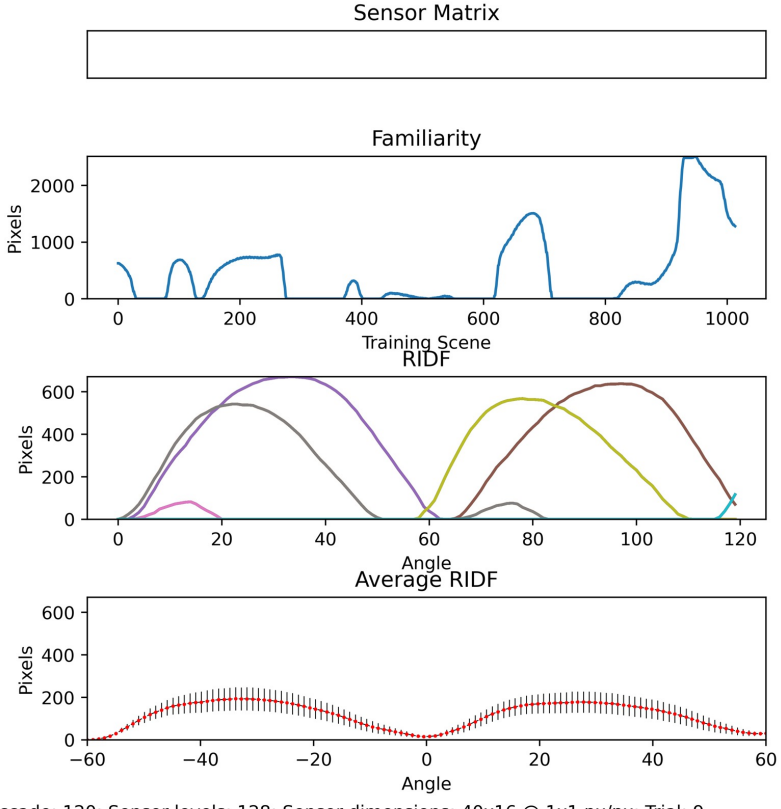

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 394; p90: 68; p50: 68; complete: 0

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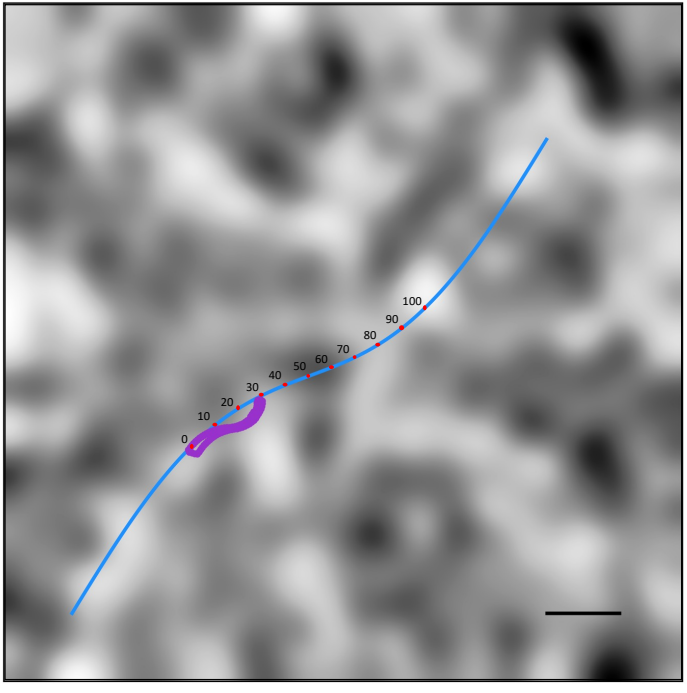
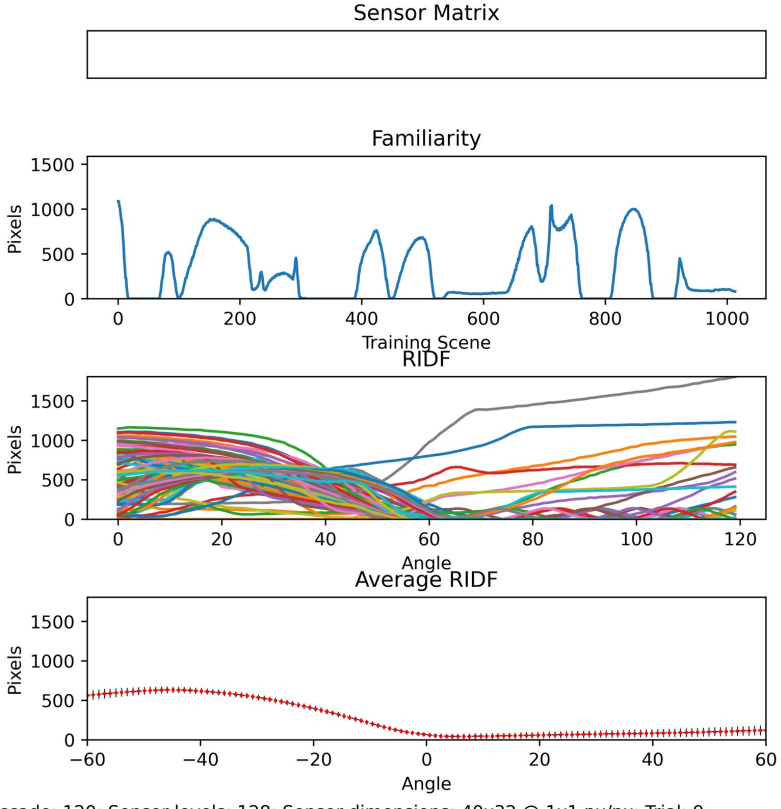
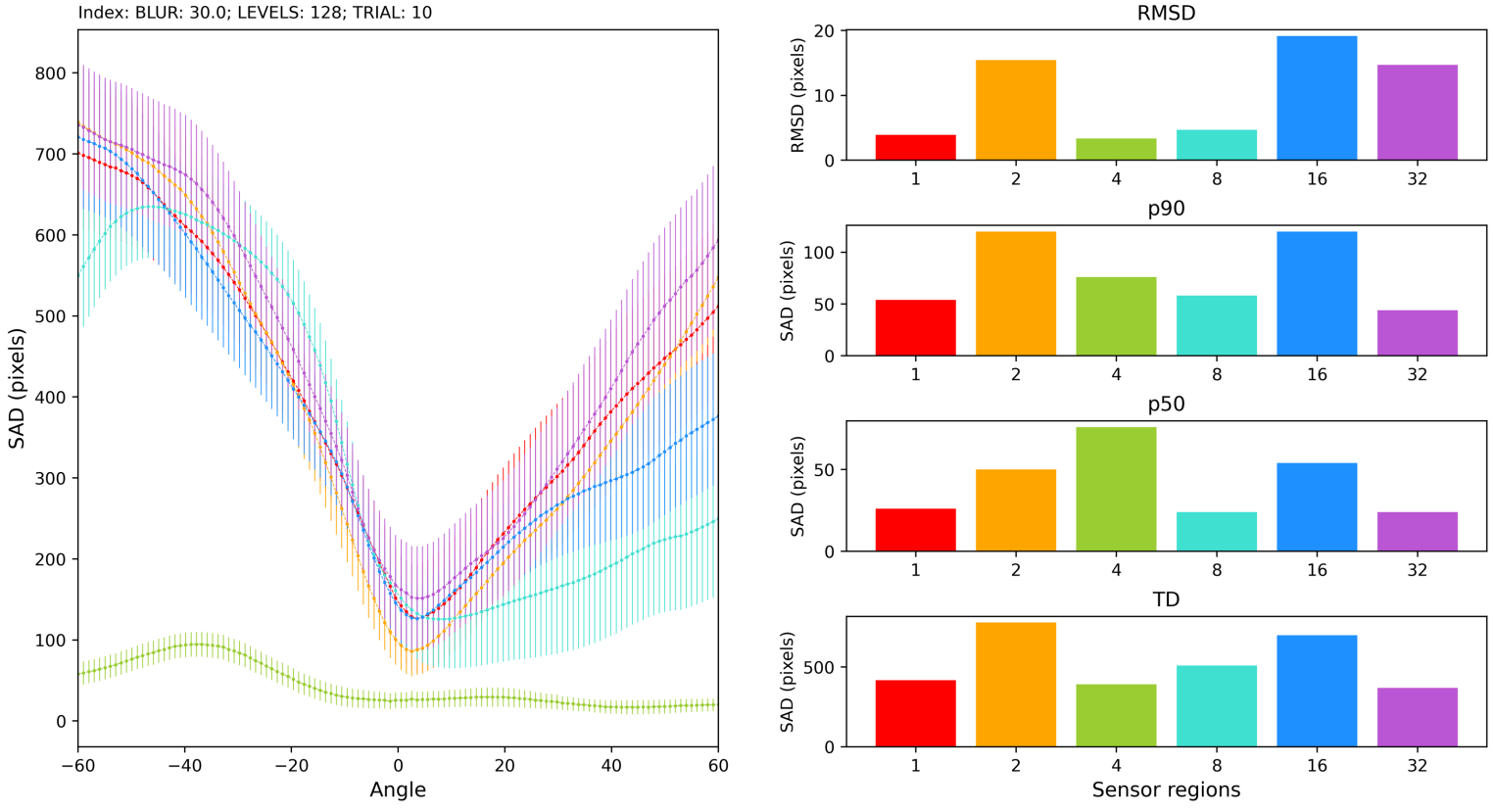


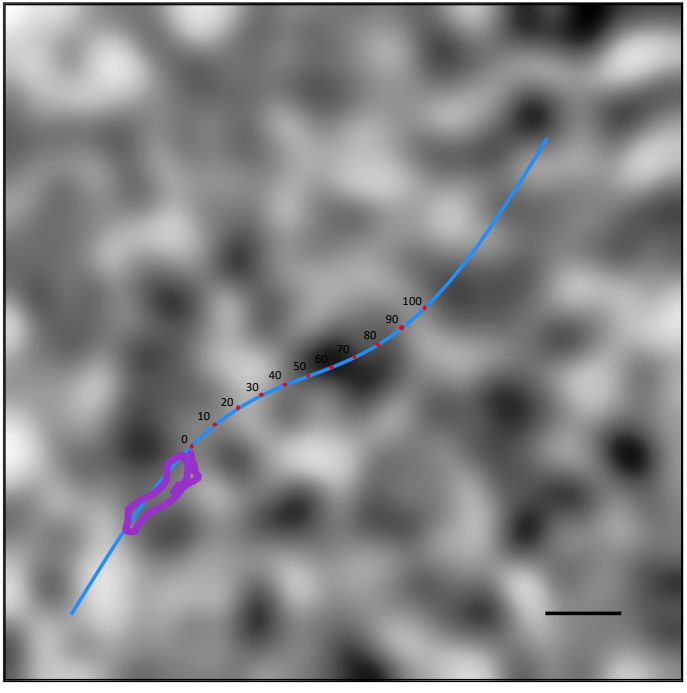


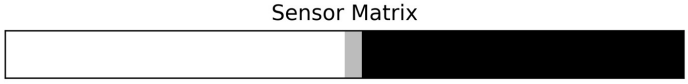
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

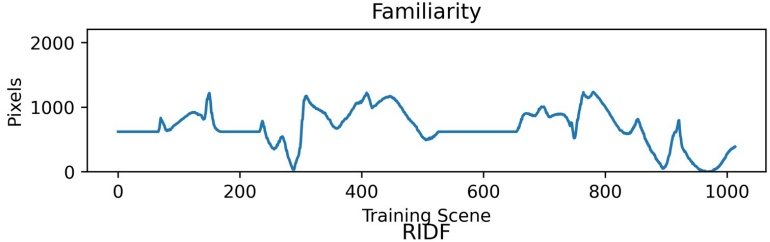
Navigation stats: RMSD error: 1282.51; RMSD/dist: 3.206; TD: 329; p90: 34; p50: 20; complete: 0

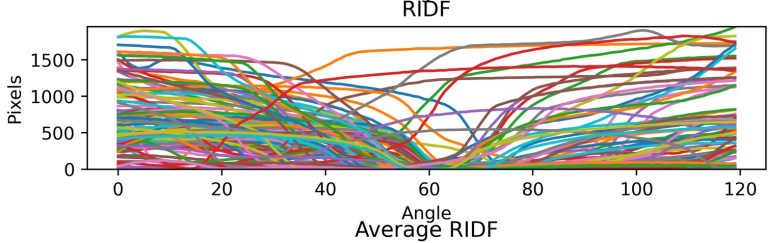

Index: BLUR: 30.0; LEVELS: 128; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
SAD (pixels)
Sensor regions

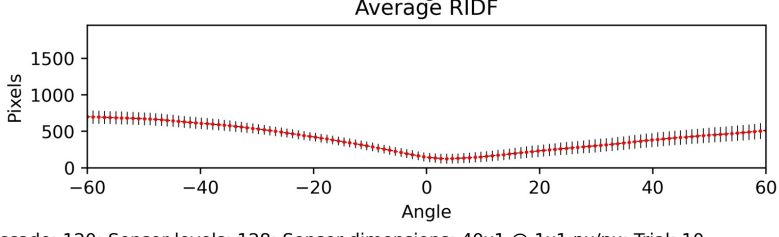
0%





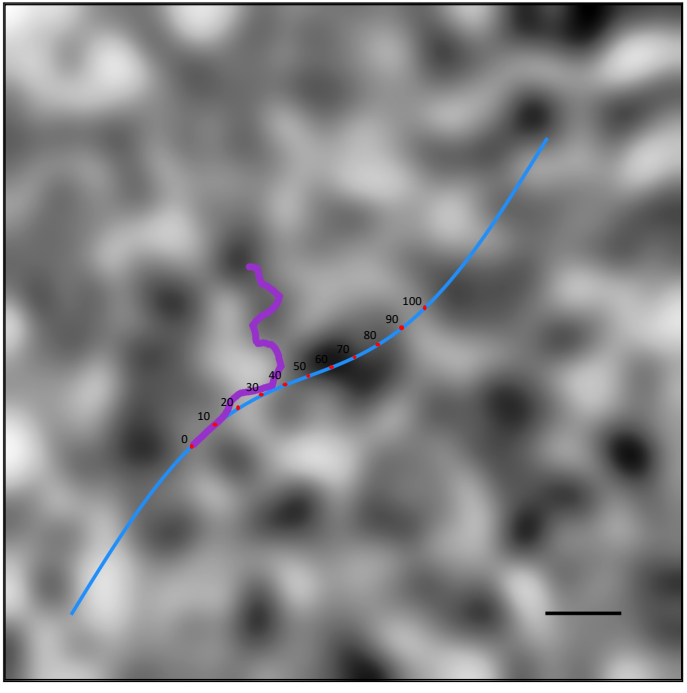


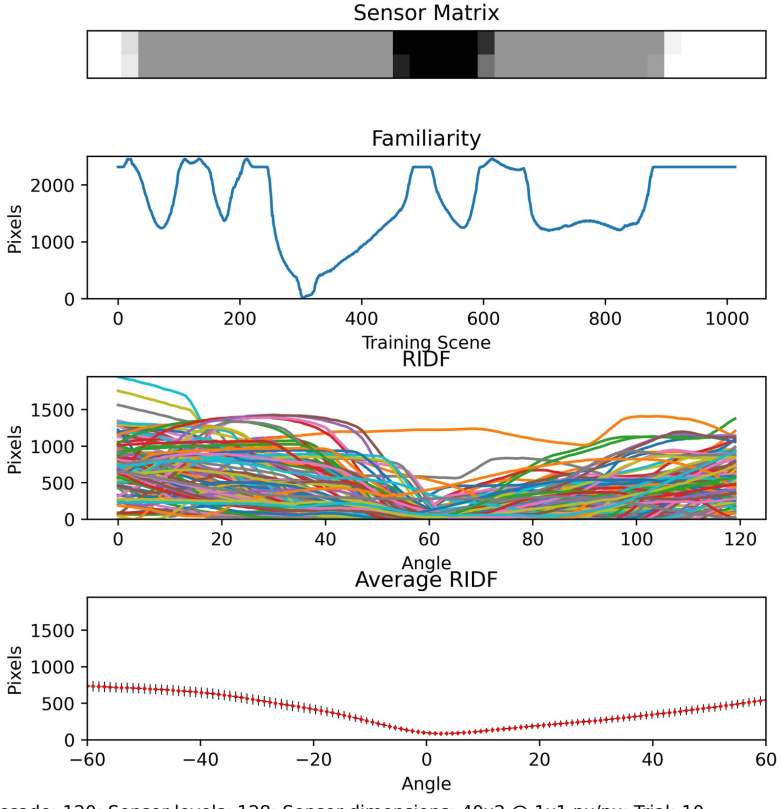




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 1555.42; RMSD/dist: 3.889; TD: 418; p90: 54; p50: 26; complete: 0

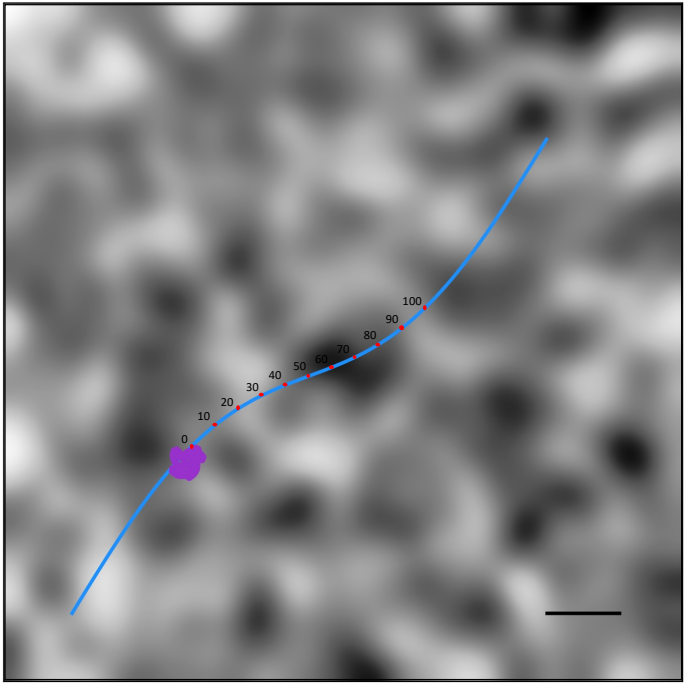
10%

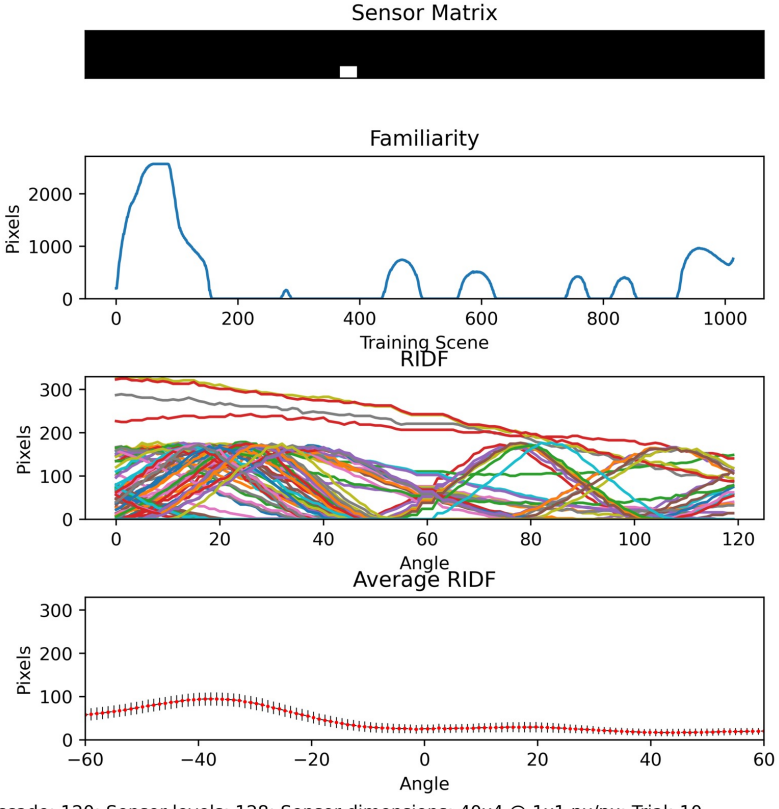




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 6181.27; RMSD/dist: 15.453; TD: 779; p90: 120; p50: 50; complete: 0

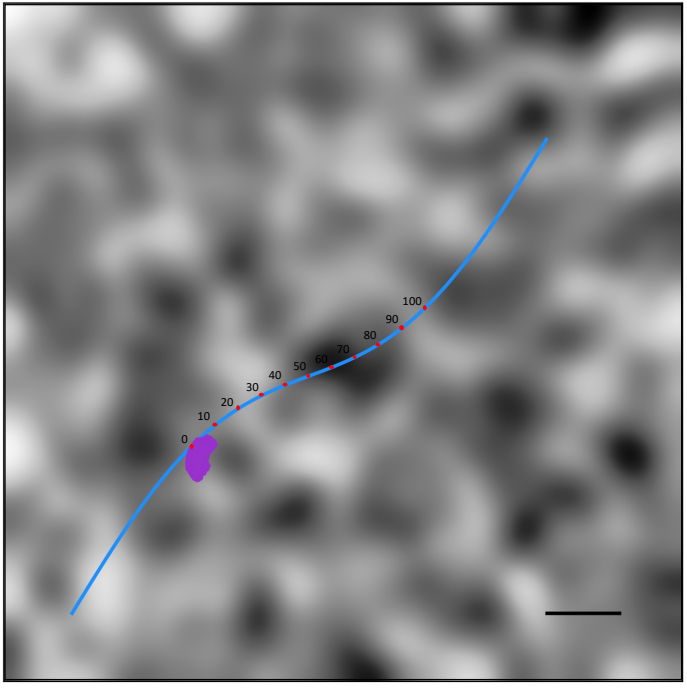
0%

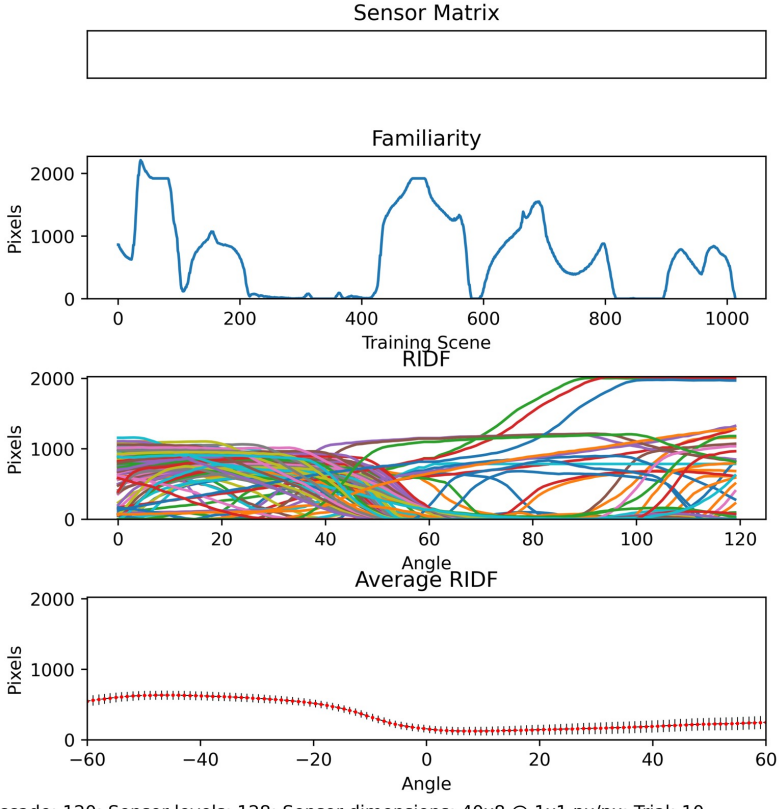




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 1330.83; RMSD/dist: 3.327; TD: 392; p90: 76; p50: 76; complete: 0

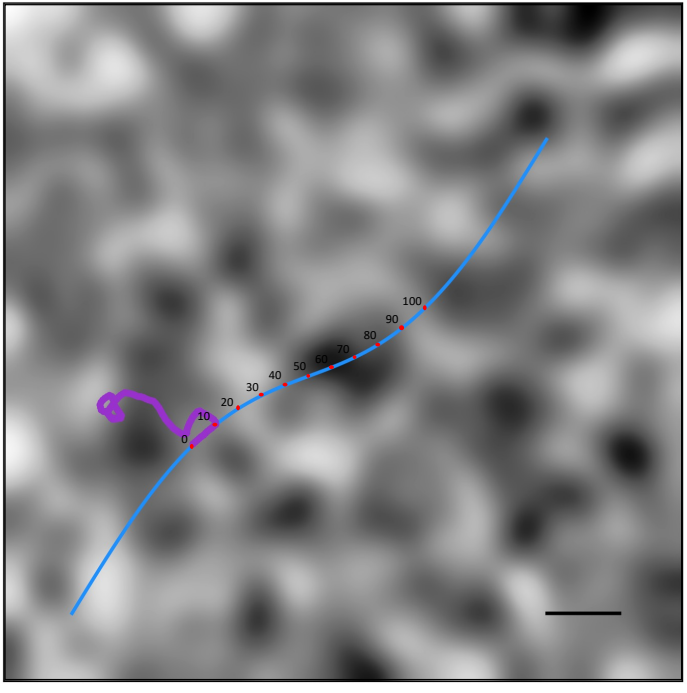
0%

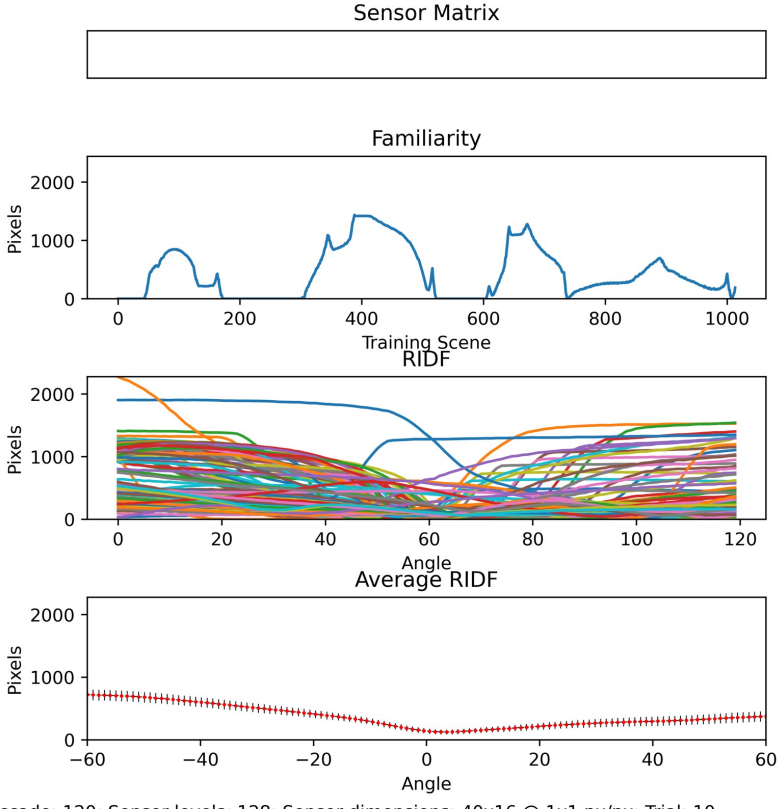




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 1862.96; RMSD/dist: 4.657; TD: 510; p90: 58; p50: 24; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 7668.81; RMSD/dist: 19.172; TD: 699; p90: 120; p50: 54; complete: 0

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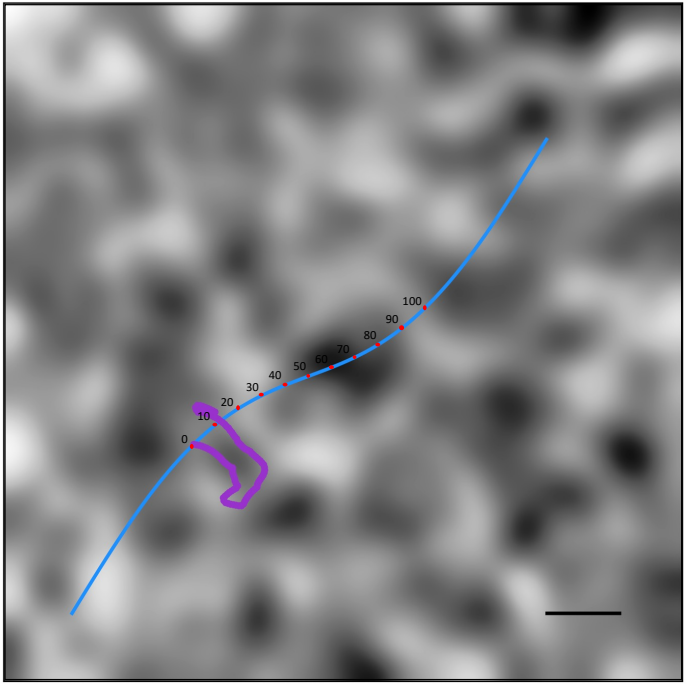

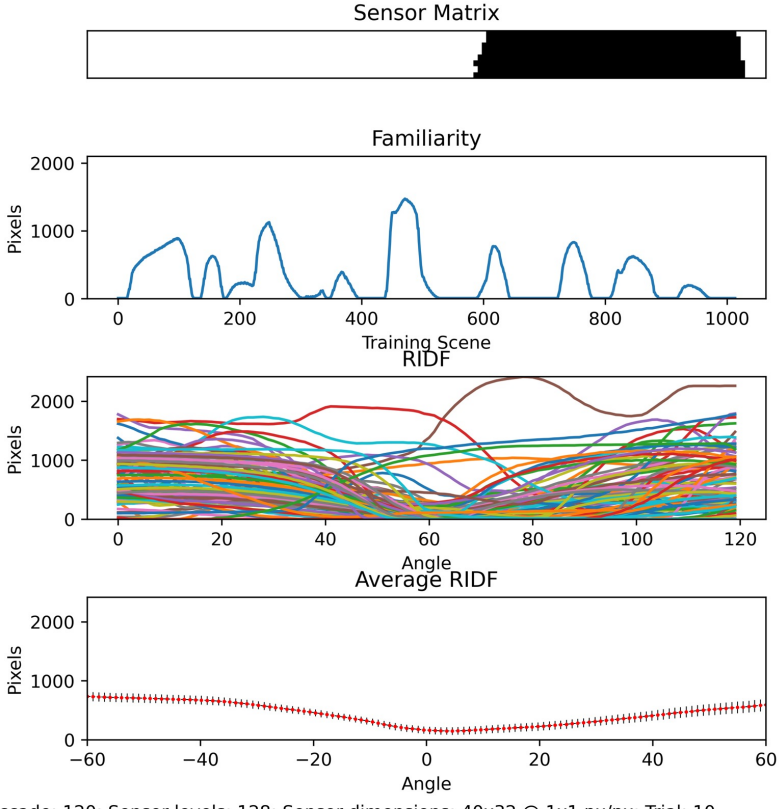

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 5876.61; RMSD/dist: 14.692; TD: 369; p90: 44; p50: 24; complete: 0