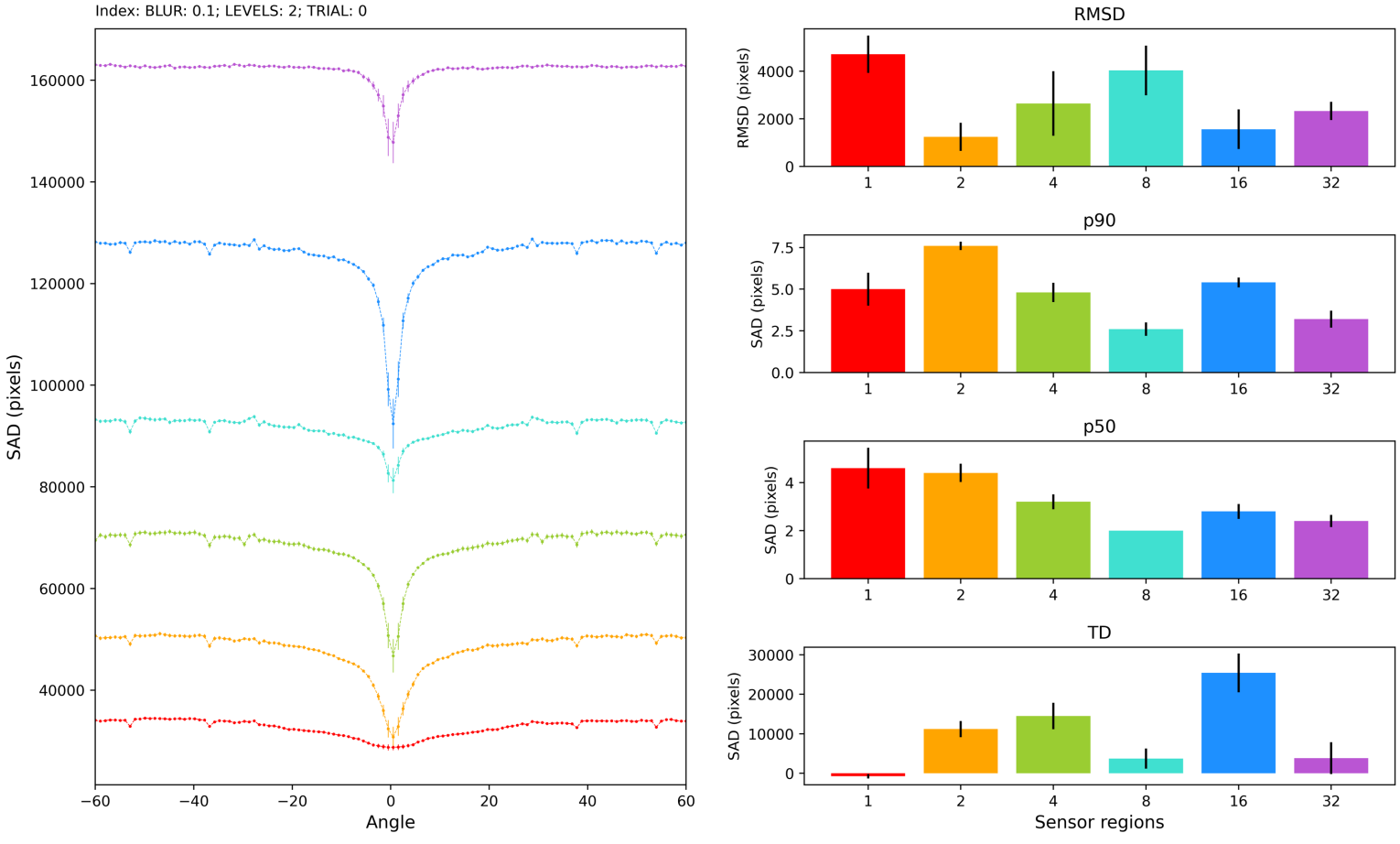
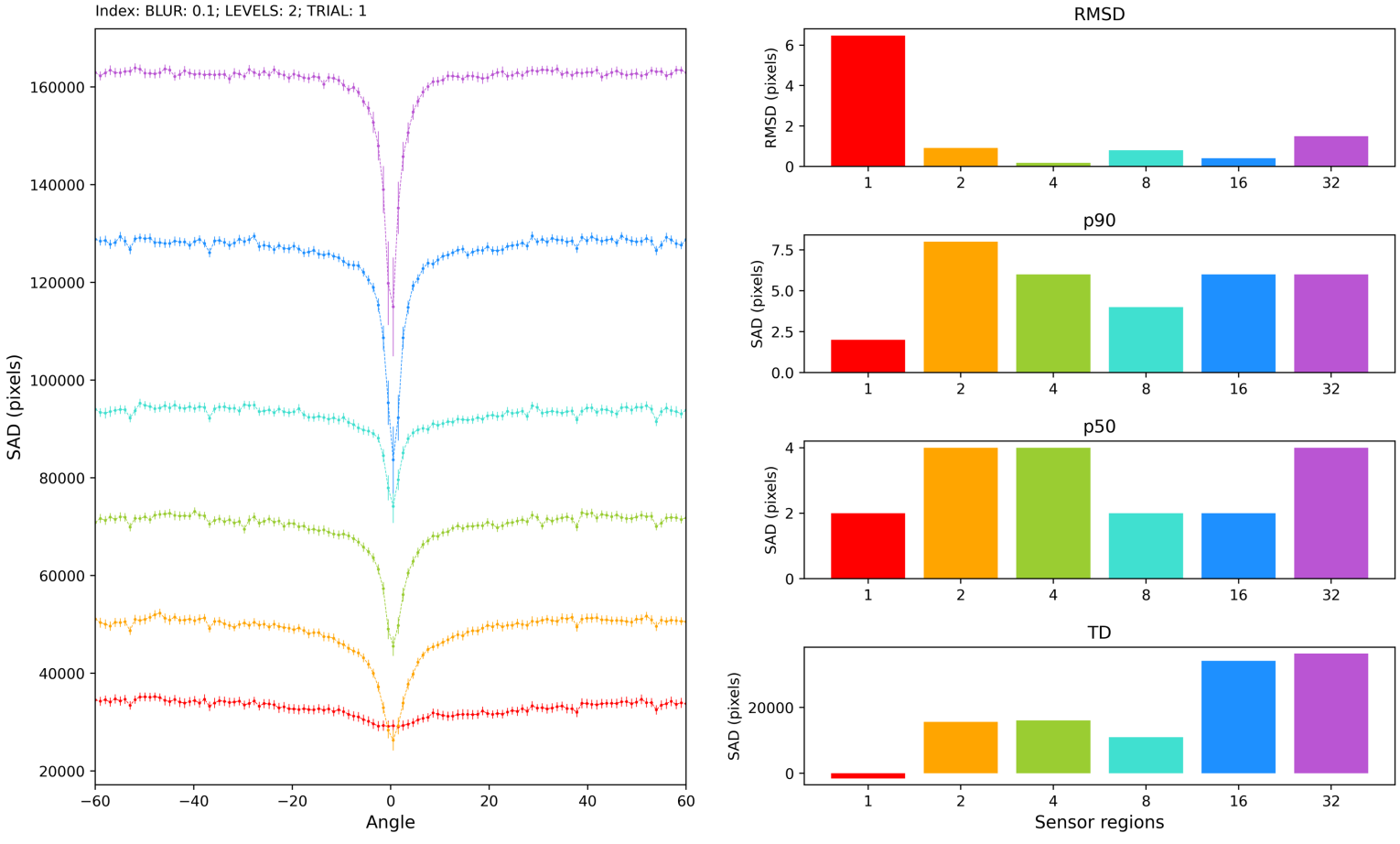
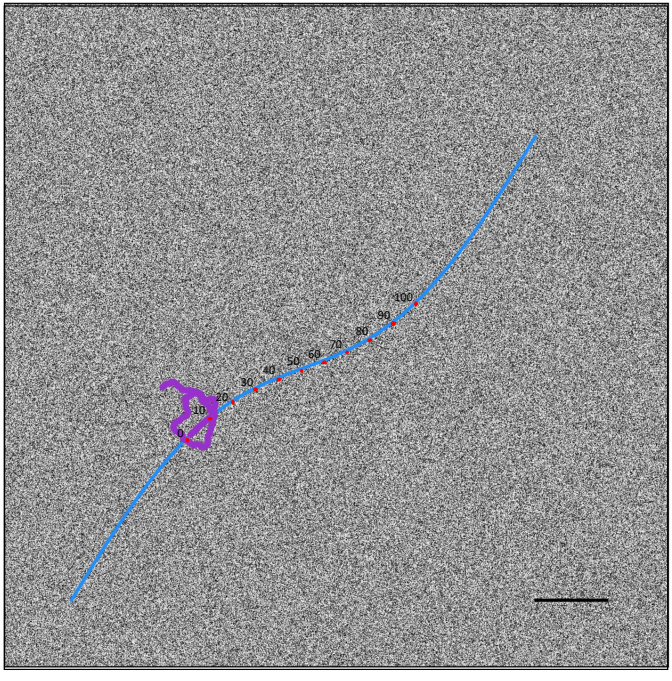
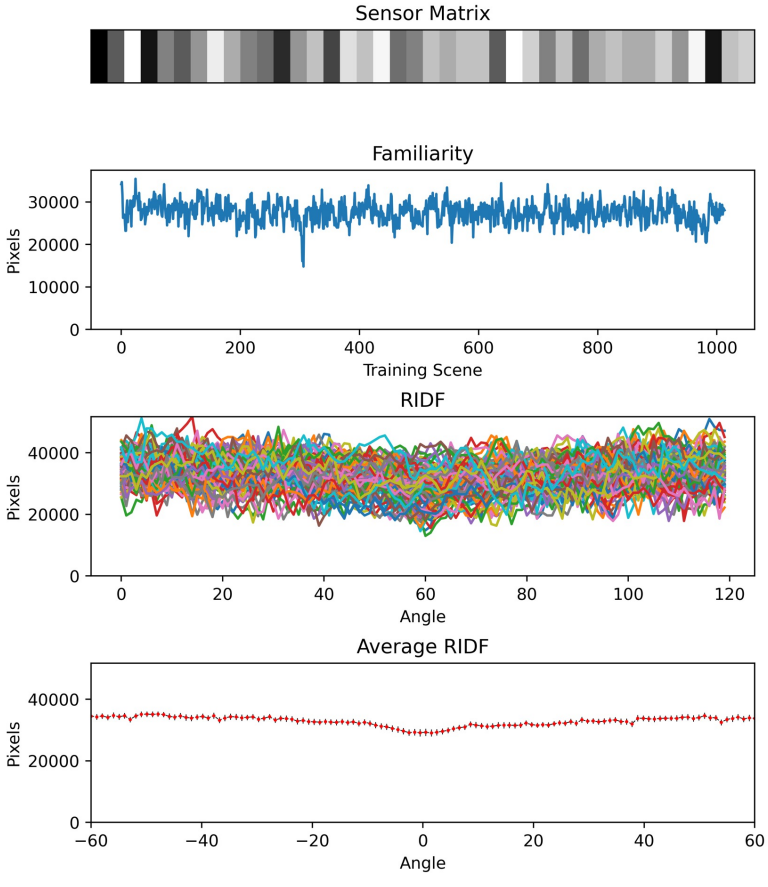

Index: BLUR: 0.1; LEVELS: 2; TRIAL: 0
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4000
2000
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
4
2
TD
30000
20000
10000
Sensor regions


Index: BLUR: 0.1; LEVELS: 2; TRIAL: 1
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
6
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
TD
20000
Sensor regions

10%

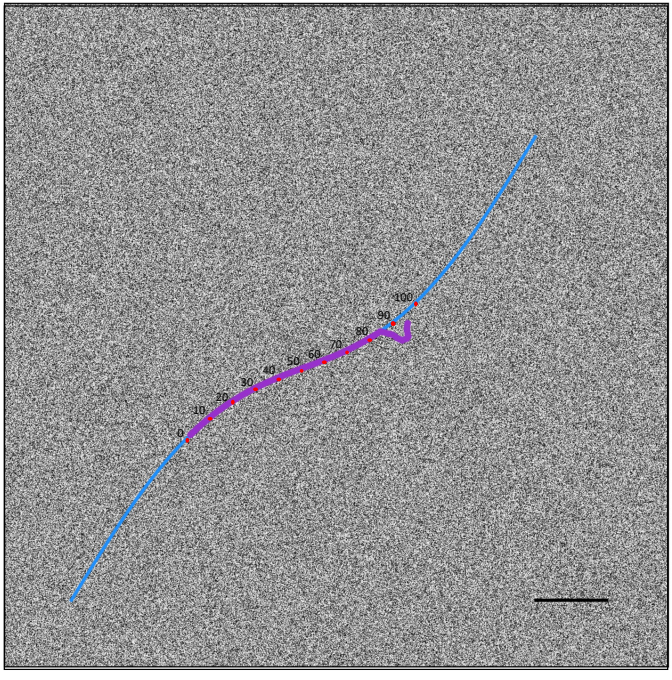


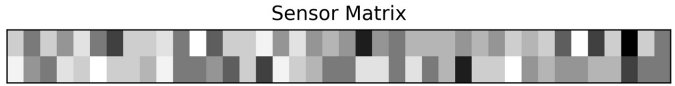



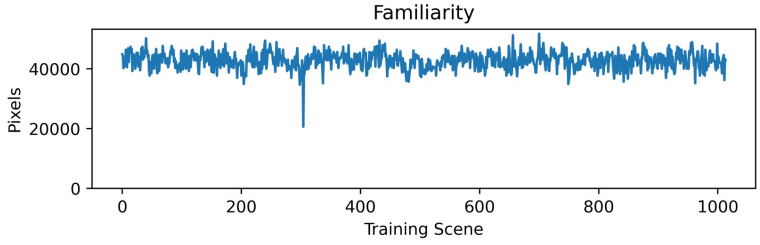

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

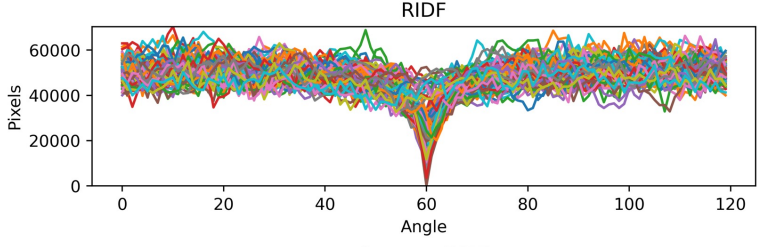
Navigation stats: RMSD error: 2590.94; RMSD/dist: 6.477; TD: -1551; p90: 2; p50: 2; complete: 0

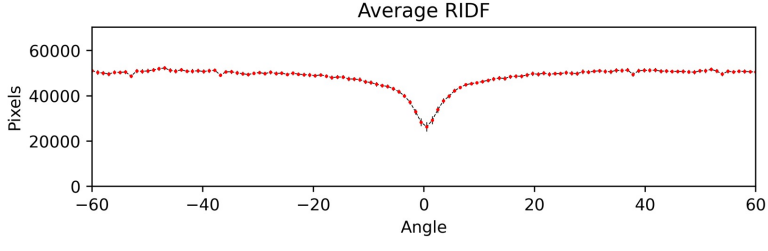
80%



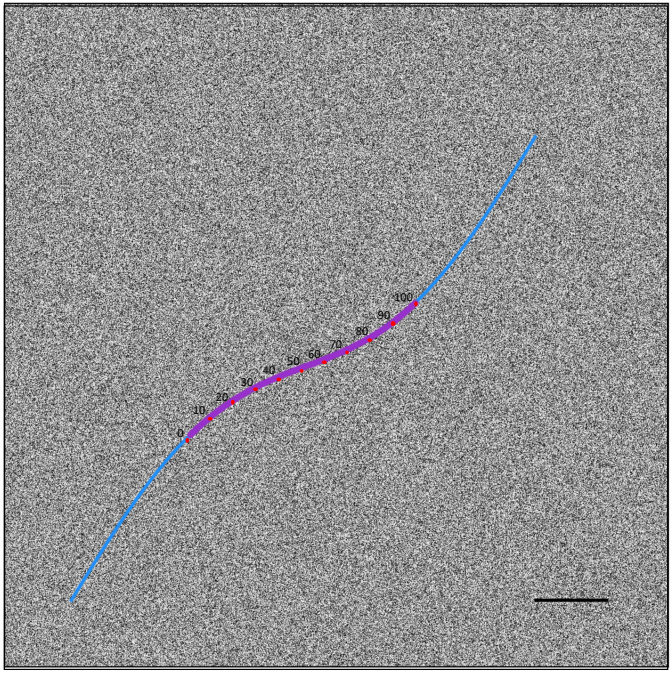



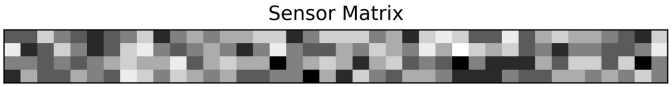



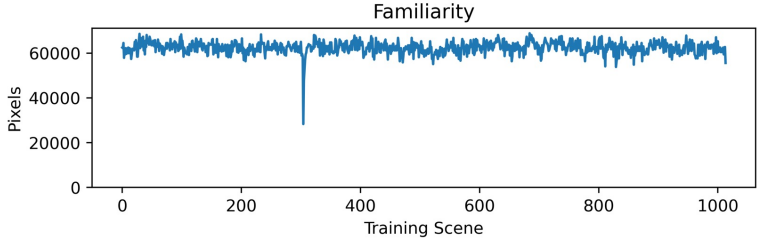

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

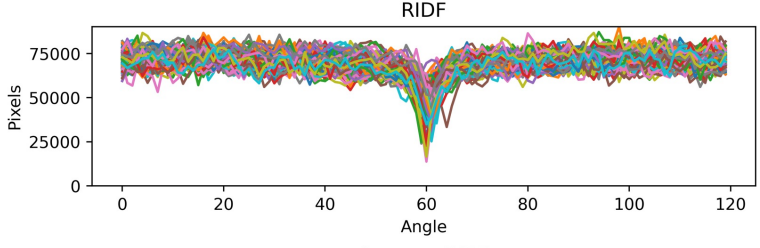
Navigation stats: RMSD error: 365.86; RMSD/dist: 0.915; TD: 15662; p90: 8; p50: 4; complete: 0

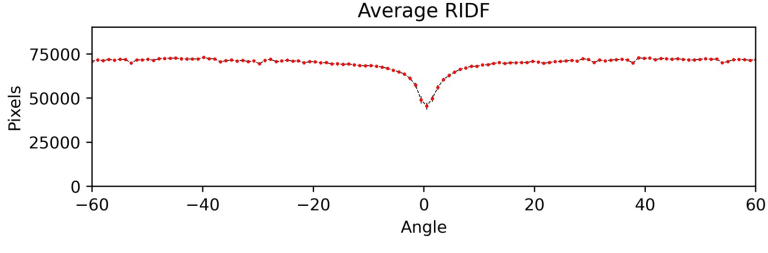
100%



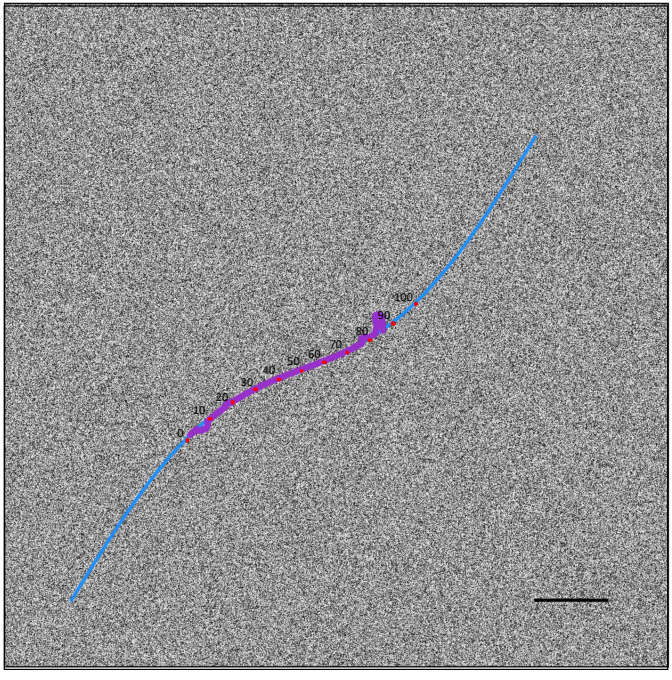



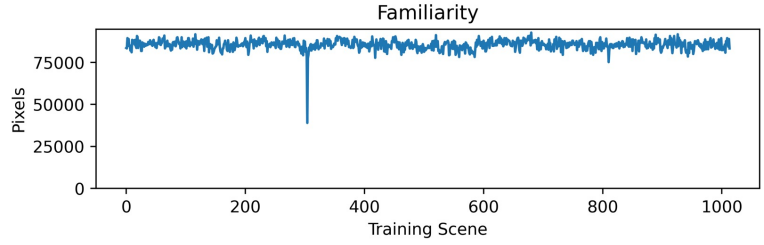



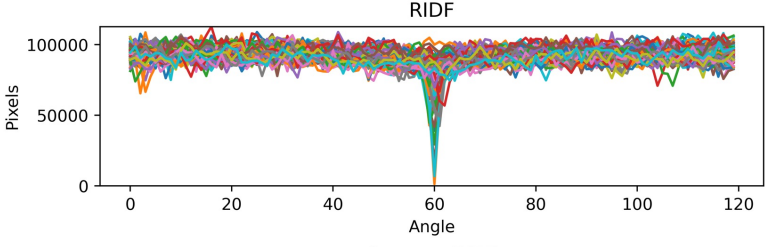

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

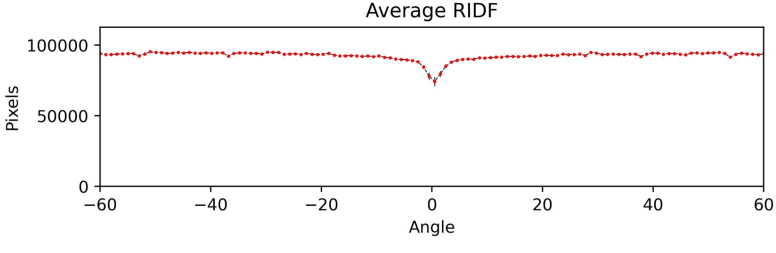
Navigation stats: RMSD error: 69.56; RMSD/dist: 0.174; TD: 16052; p90: 6; p50: 4; complete: 0

80%





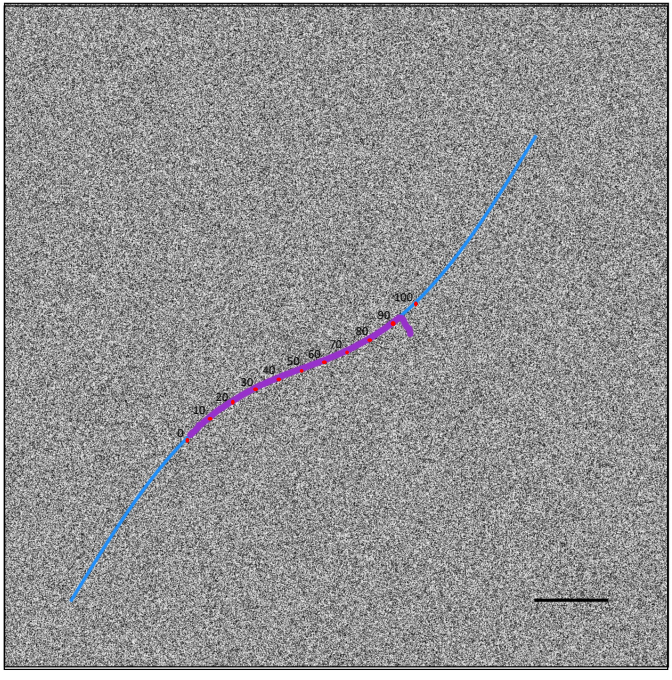



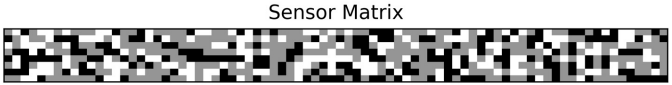



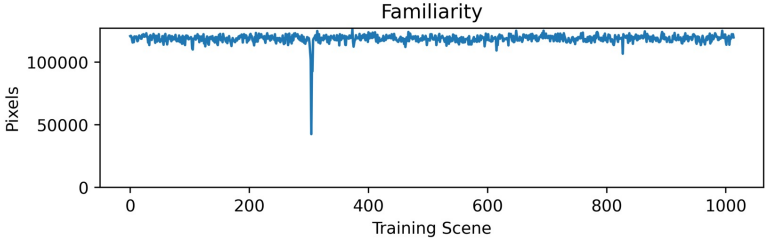

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

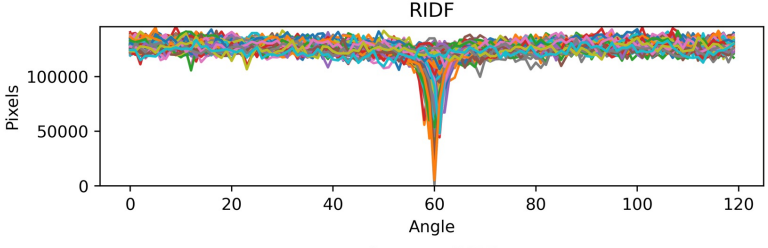
Navigation stats: RMSD error: 318.45; RMSD/dist: 0.796; TD: 11011; p90: 4; p50: 2; complete: 0

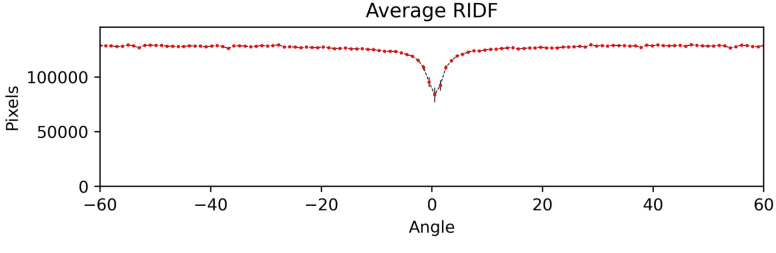
90%



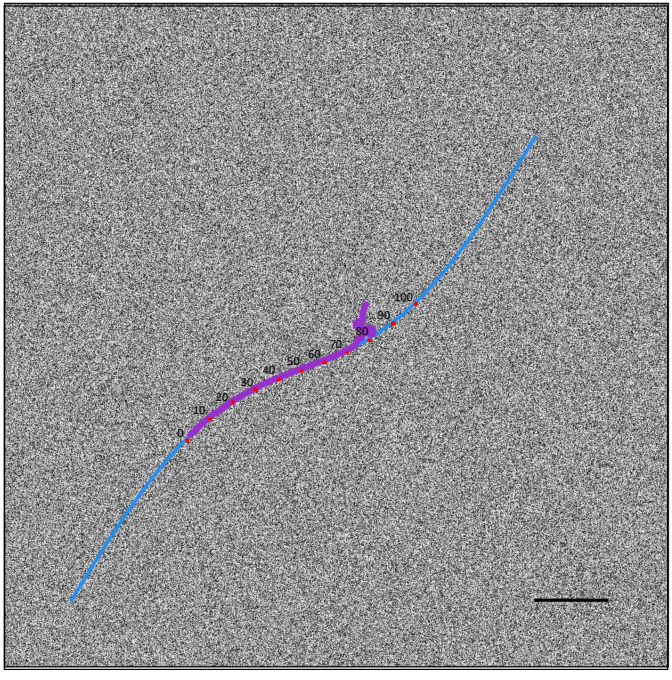



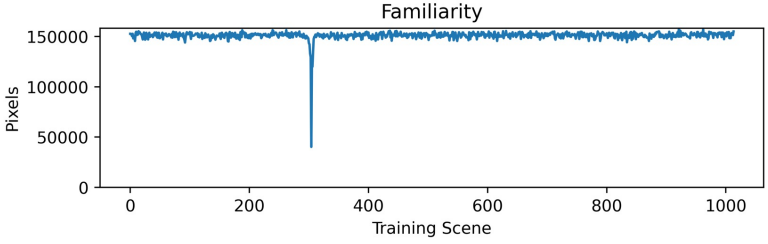



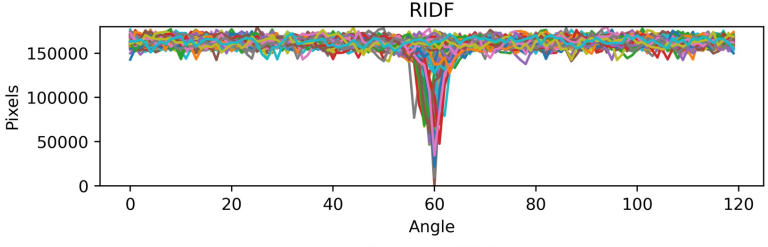

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

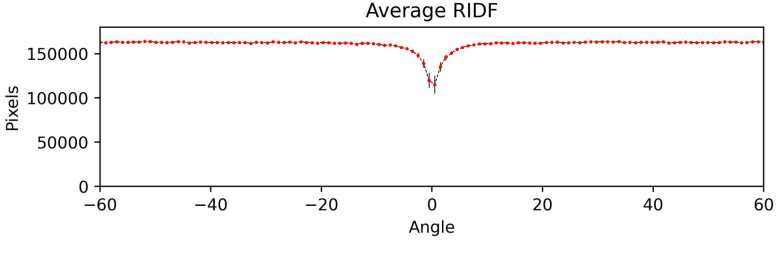
Navigation stats: RMSD error: 161.89; RMSD/dist: 0.405; TD: 34155; p90: 6; p50: 2; complete: 0

70%



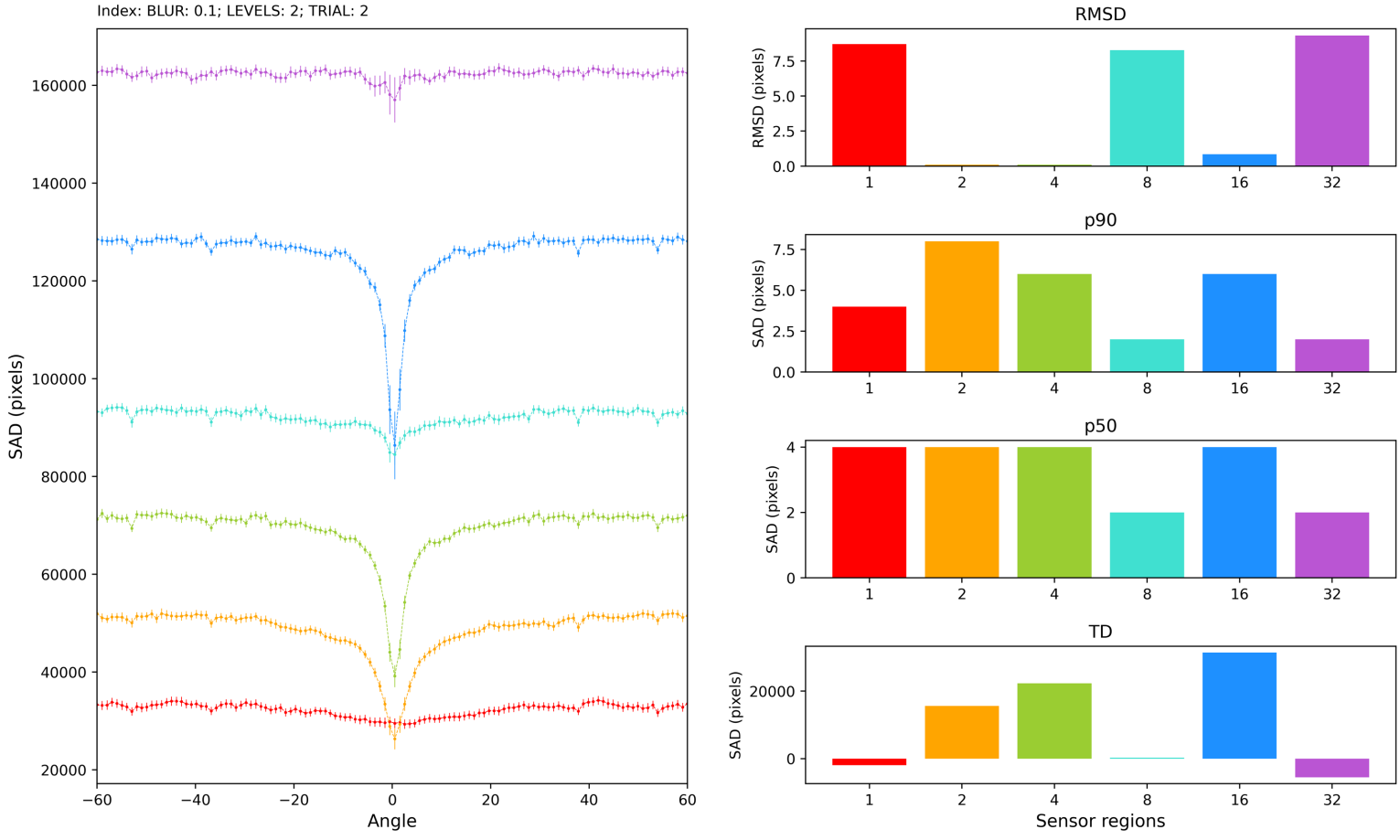


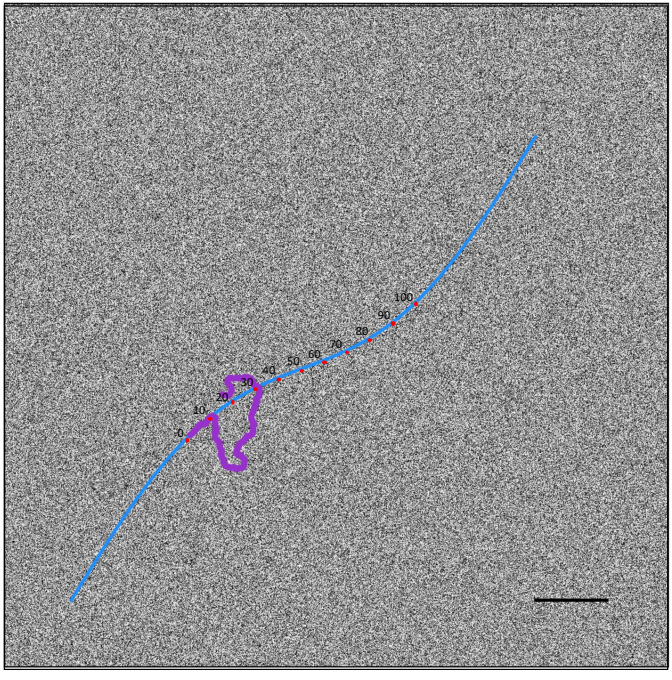



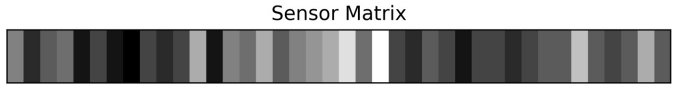

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

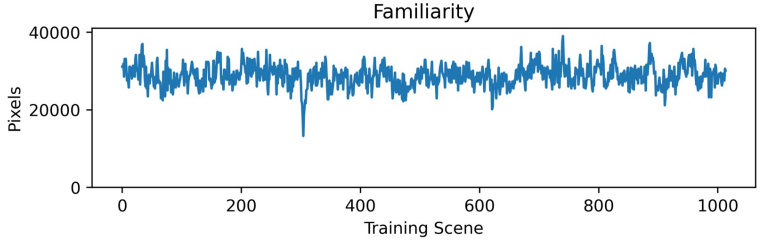
Navigation stats: RMSD error: 596.77; RMSD/dist: 1.492; TD: 36389; p90: 6; p50: 4; complete: 0

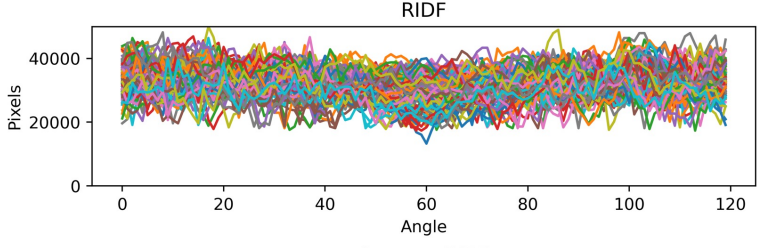

Index: BLUR: 0.1; LEVELS: 2; TRIAL: 2
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
7.5
5.0
2.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
SAD (pixels)
4
2
0
TD
SAD (pixels)
20000
0
Sensor regions

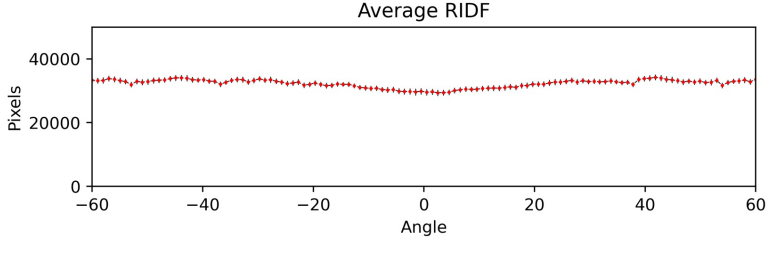
10%



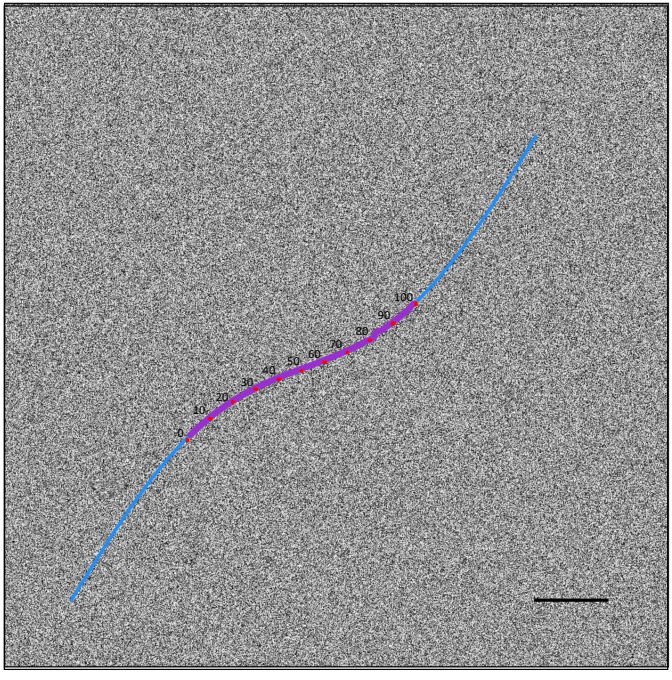



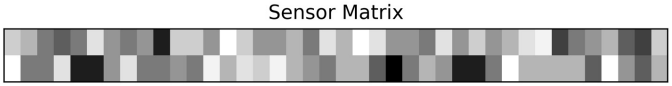



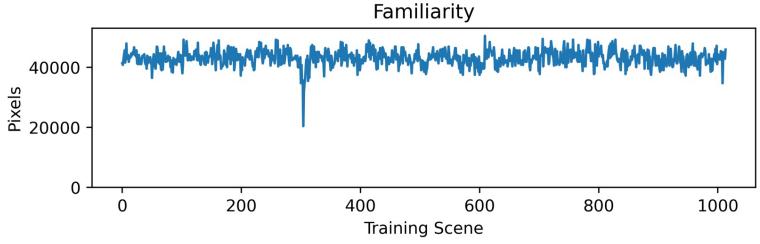

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

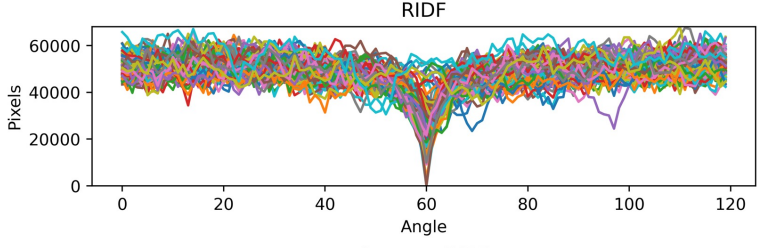
Navigation stats: RMSD error: 3481.67; RMSD/dist: 8.704; TD: -1972; p90: 4; p50: 4; complete: 0

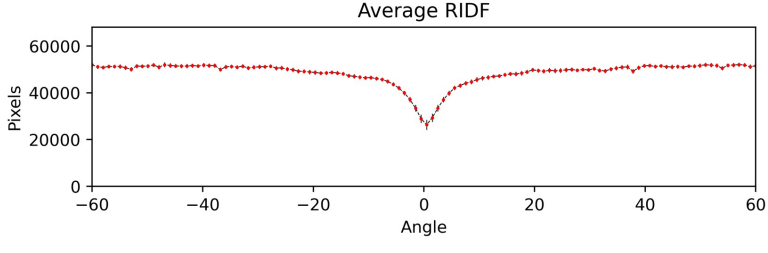
100%



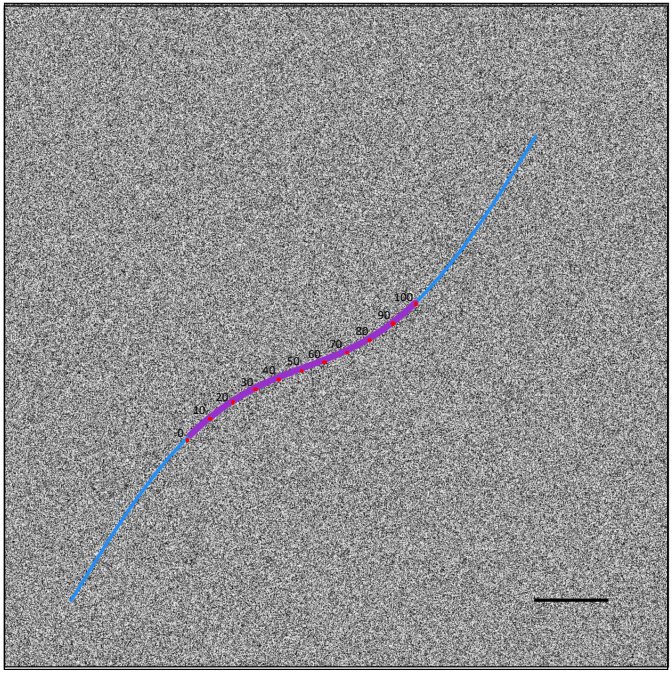



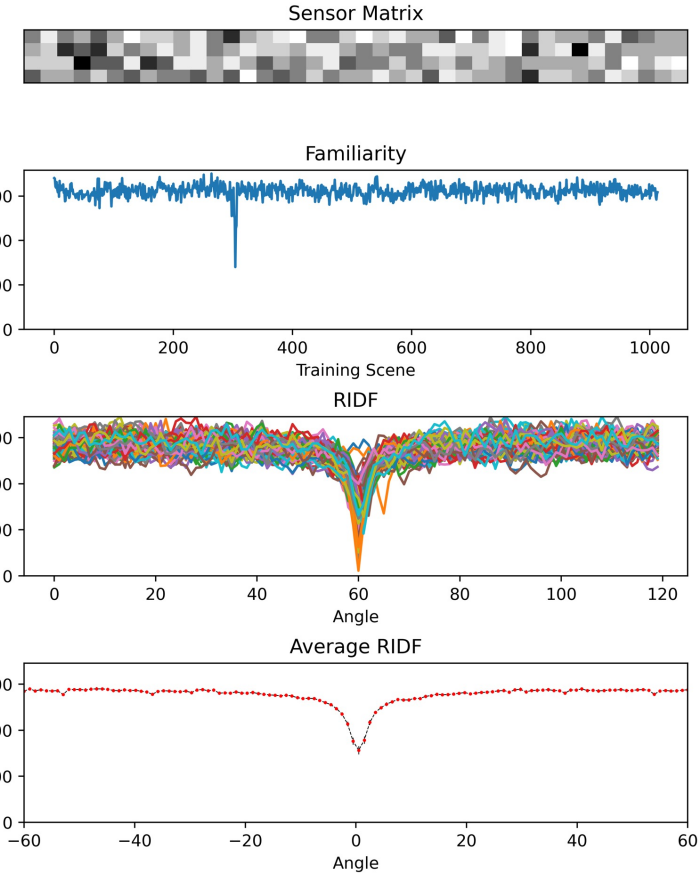




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 40.48; RMSD/dist: 0.101; TD: 15624; p90: 8; p50: 4; complete: 0

100%

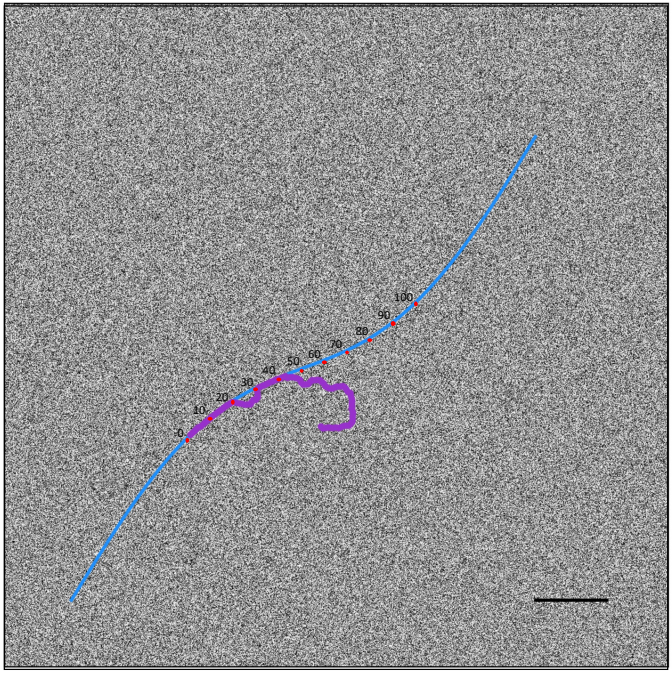


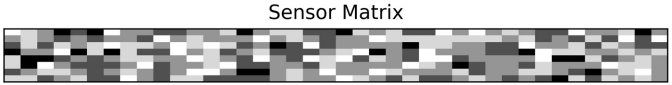



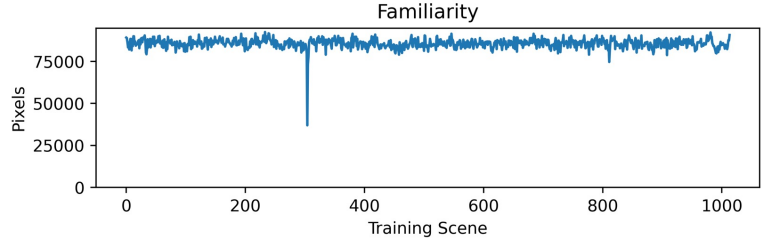

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

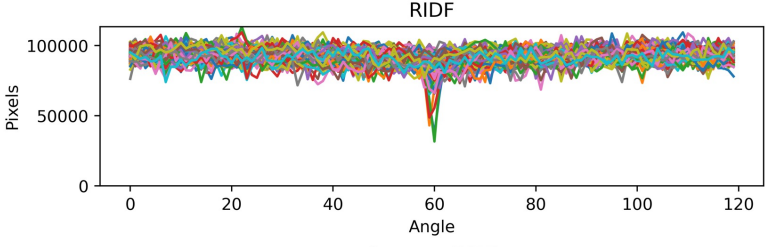
Navigation stats: RMSD error: 39.22; RMSD/dist: 0.098; TD: 22296; p90: 6; p50: 4; complete: 0

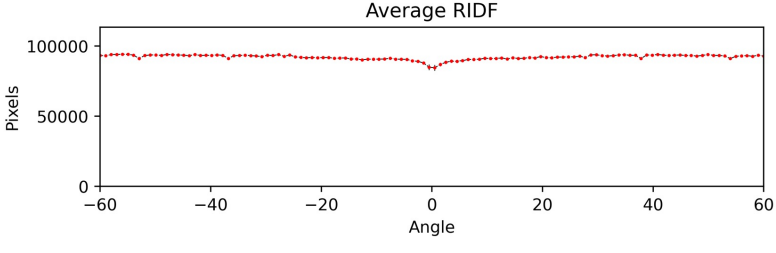
30%



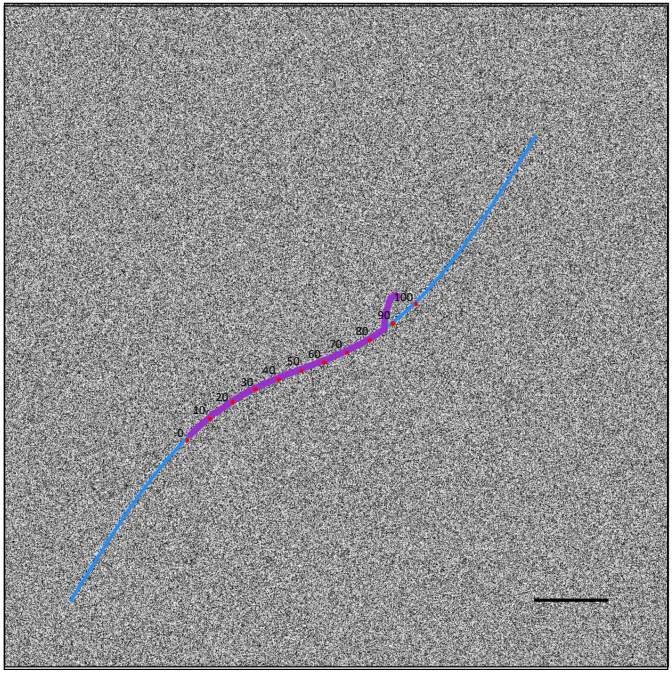



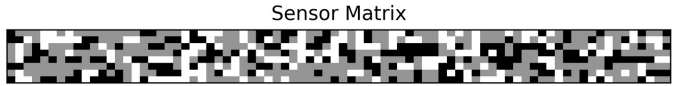



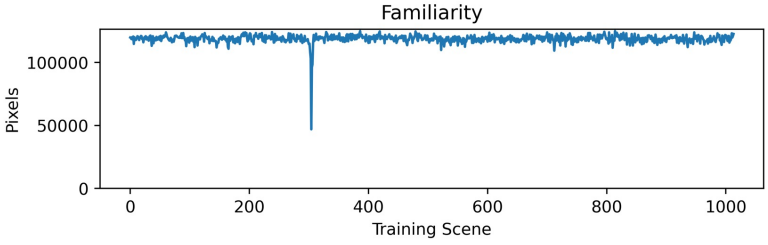

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

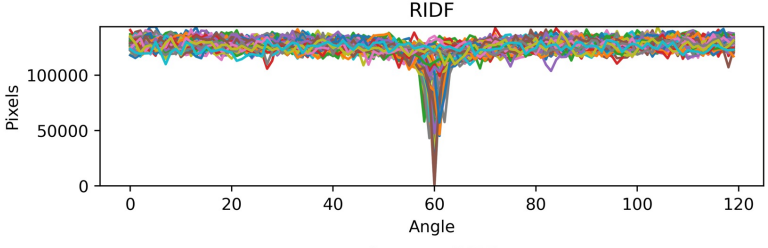
Navigation stats: RMSD error: 3310.63; RMSD/dist: 8.277; TD: 259; p90: 2; p50: 2; complete: 0

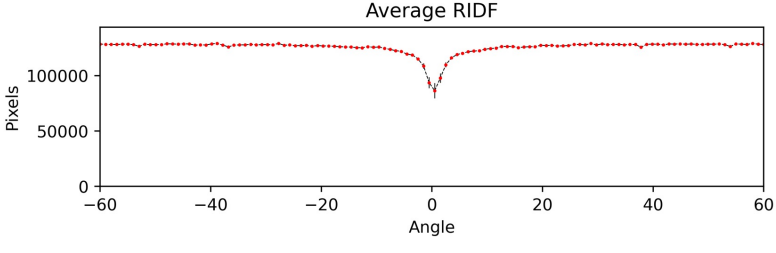
80%



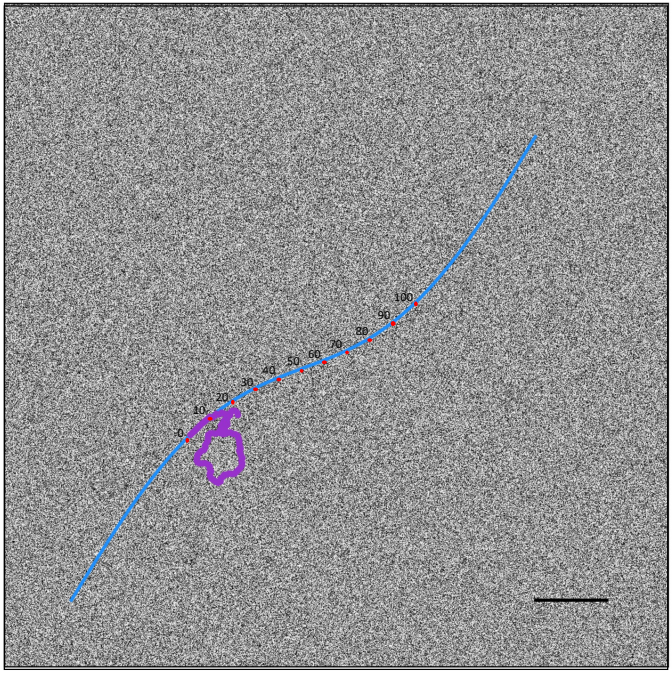



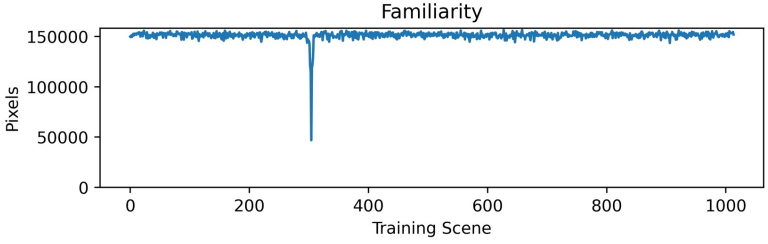



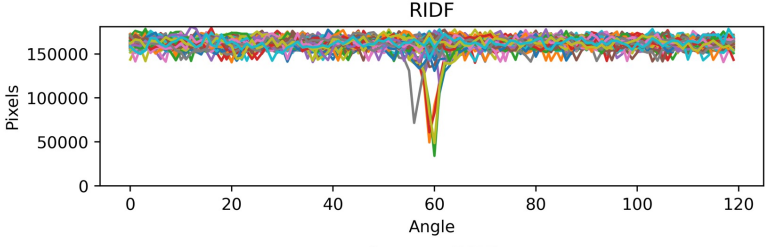

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

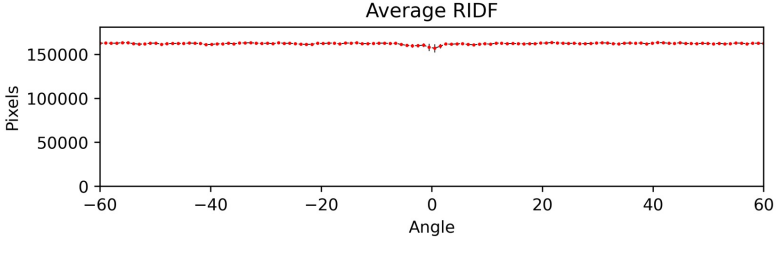
Navigation stats: RMSD error: 336.72; RMSD/dist: 0.842; TD: 31425; p90: 6; p50: 4; complete: 0

10%



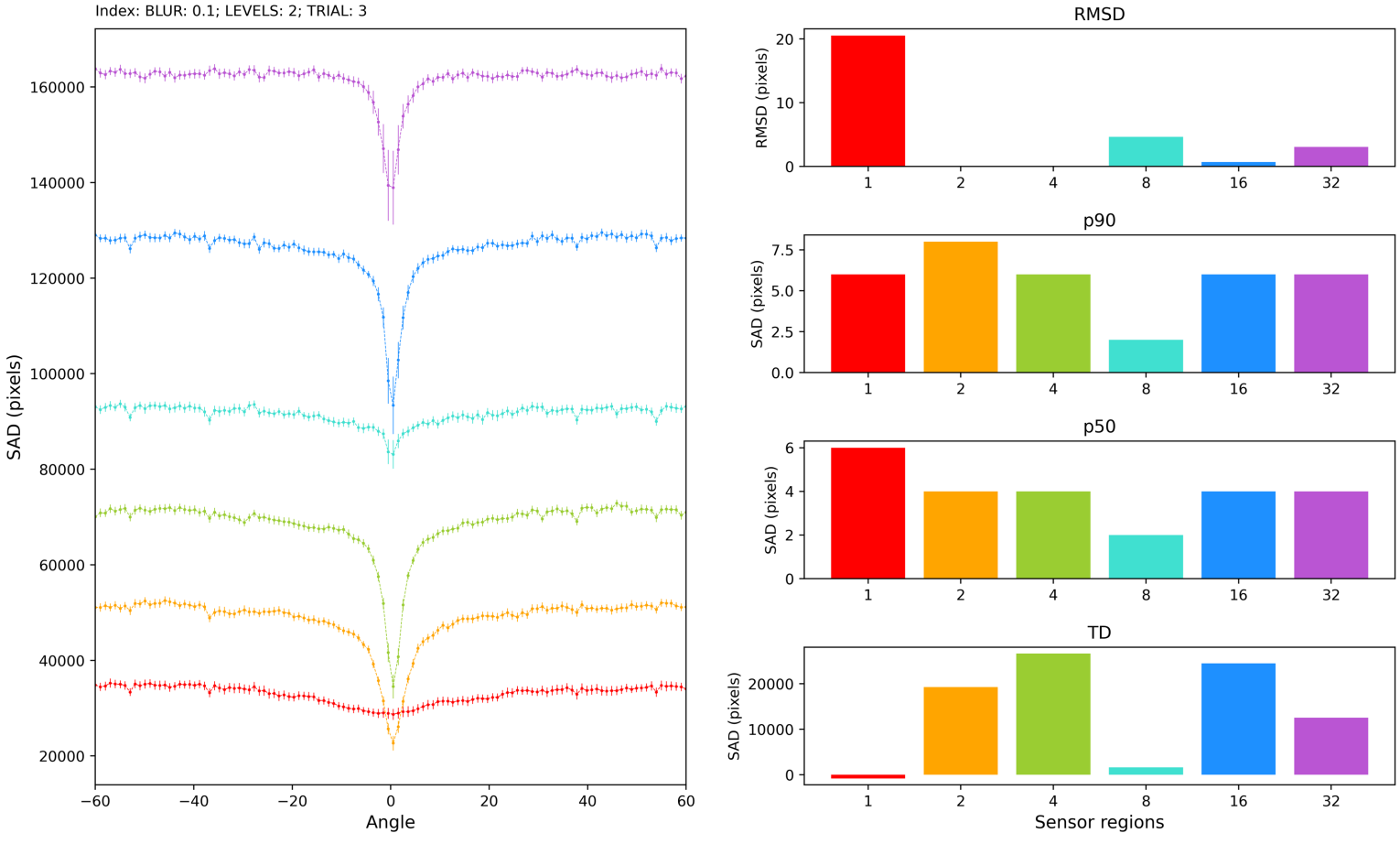


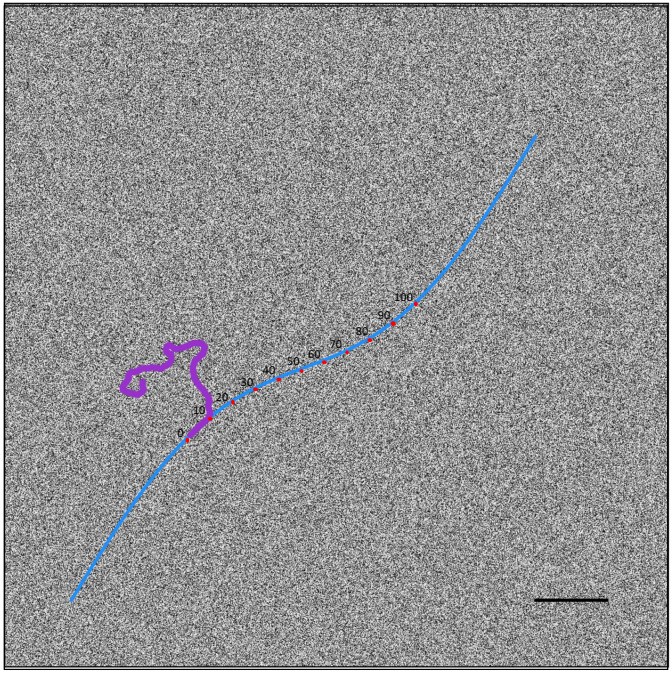



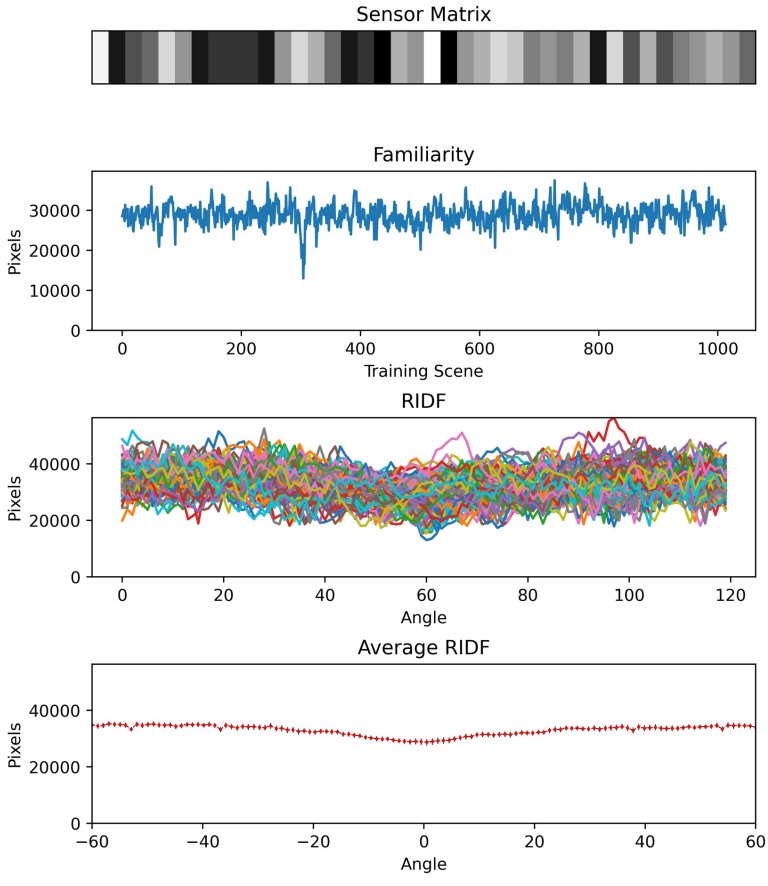

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 3731.08; RMSD/dist: 9.328; TD: -5538; p90: 2; p50: 2; complete: 0


Index: BLUR: 0.1; LEVELS: 2; TRIAL: 3
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
6
4
2
TD
20000
10000
Sensor regions

10%

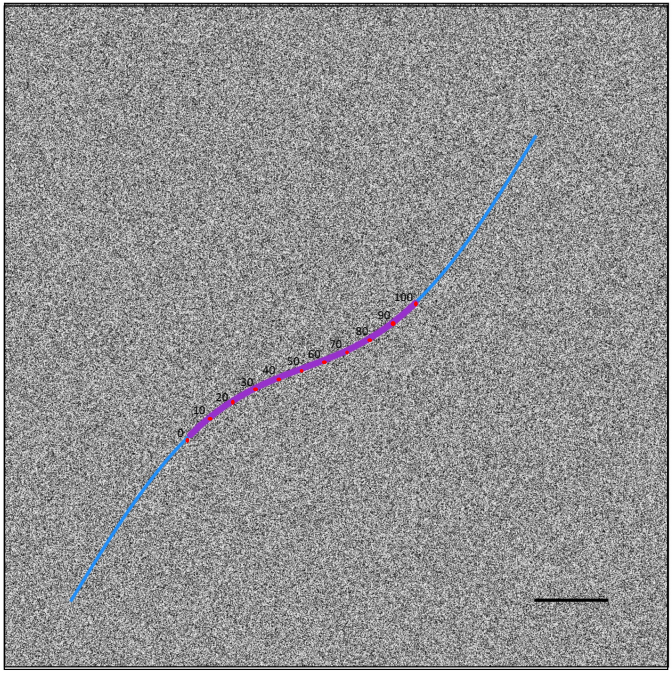


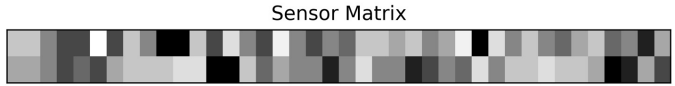



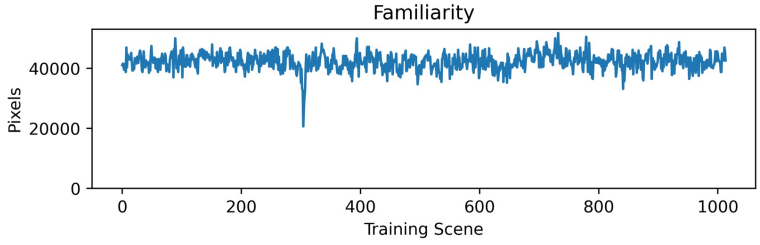

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

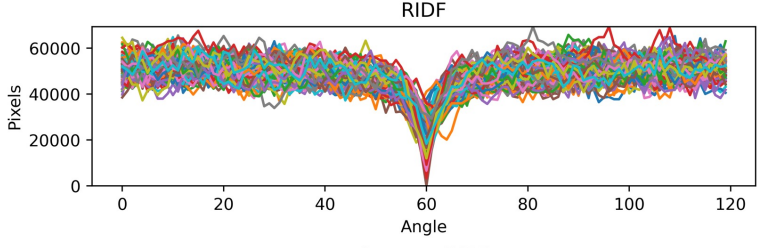
Navigation stats: RMSD error: 8222.62; RMSD/dist: 20.557; TD: -811; p90: 6; p50: 6; complete: 0

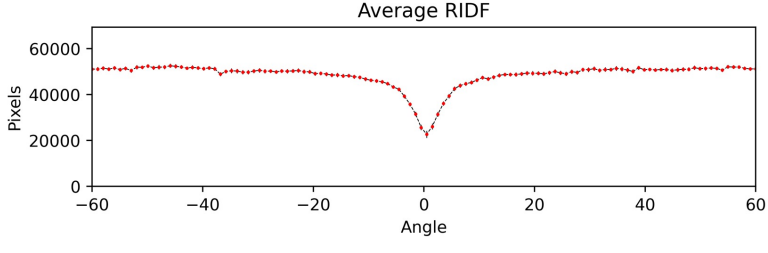
100%



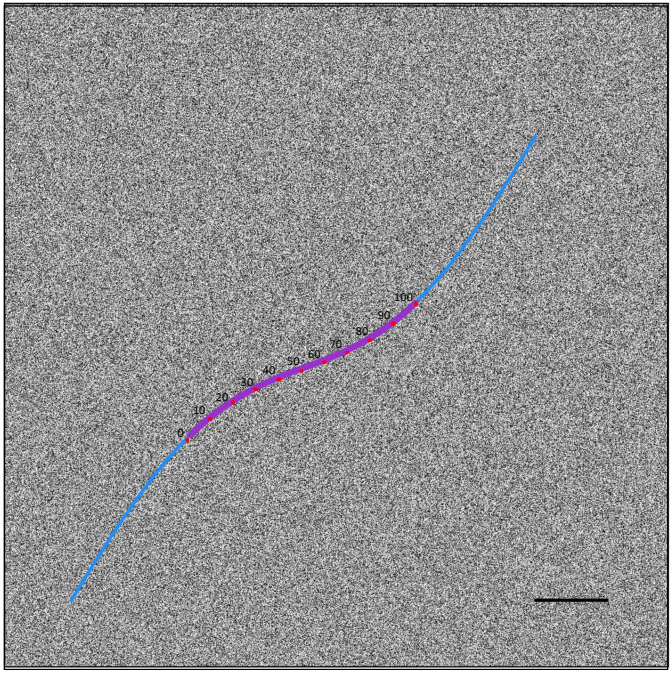



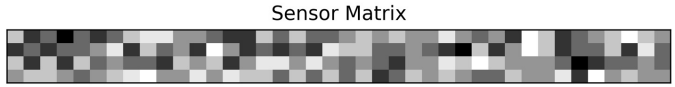



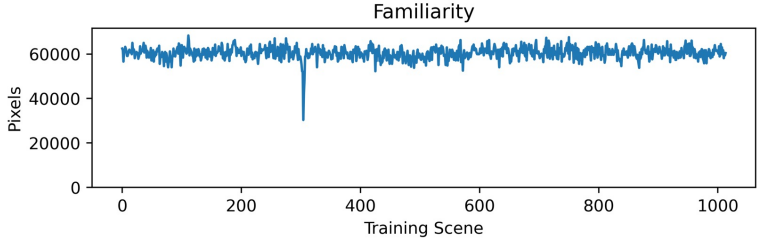

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

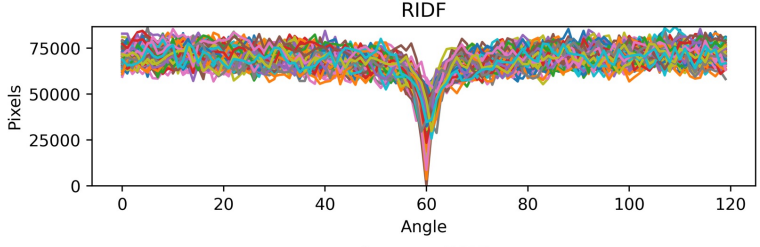
Navigation stats: RMSD error: 24.17; RMSD/dist: 0.060; TD: 19237; p90: 8; p50: 4; complete: 0

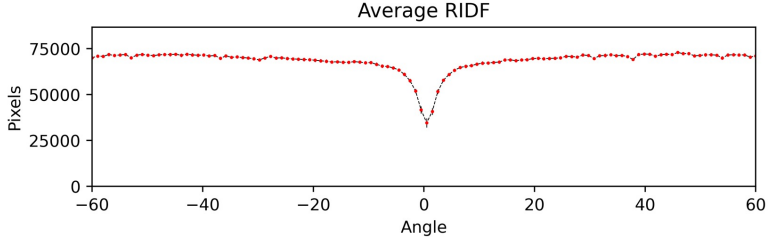
100%



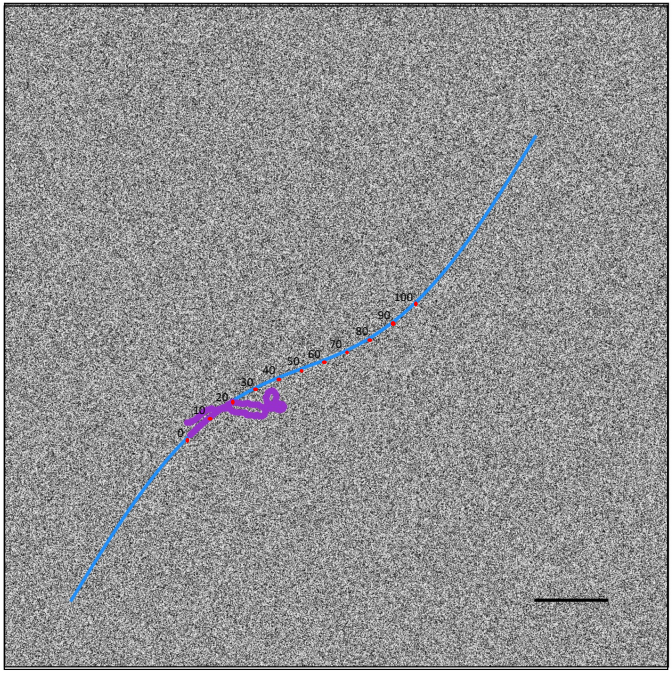



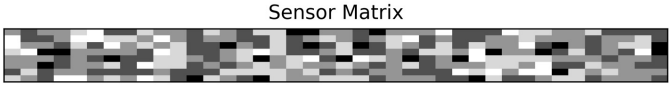



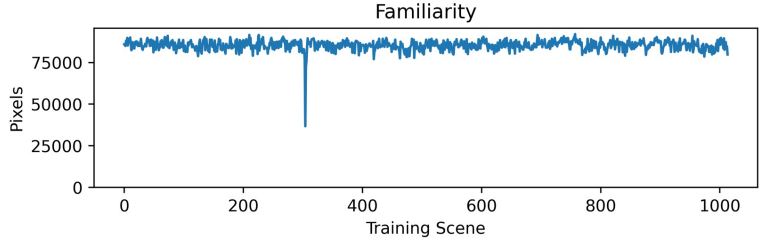

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

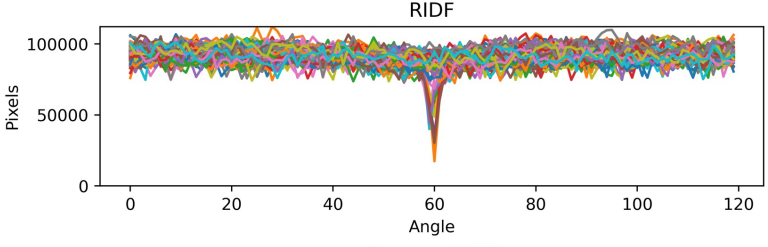
Navigation stats: RMSD error: 24.50; RMSD/dist: 0.061; TD: 26614; p90: 6; p50: 4; complete: 0

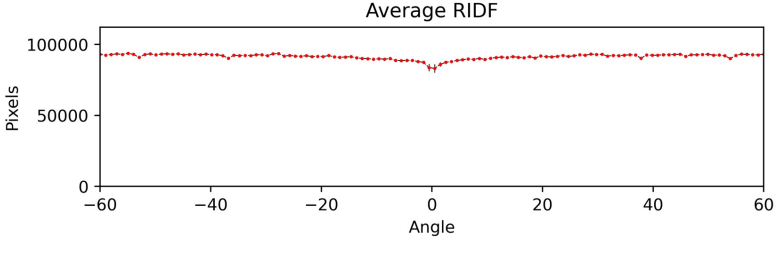
20%



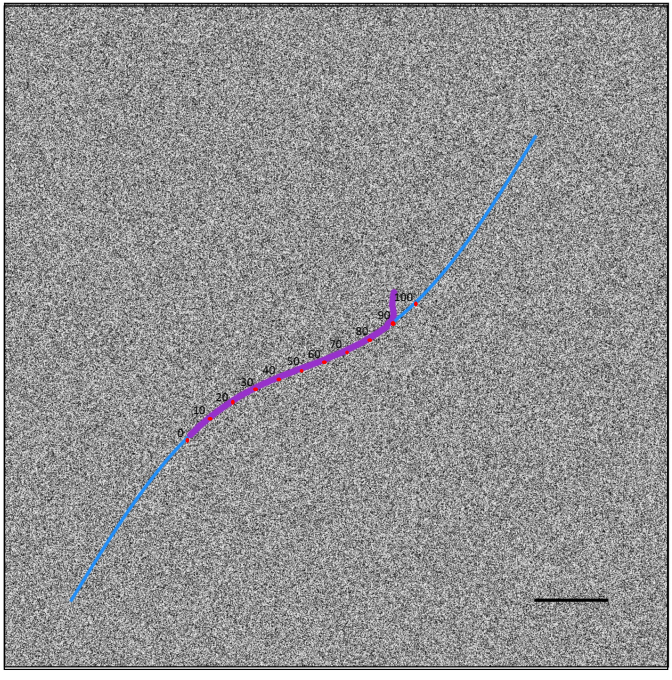



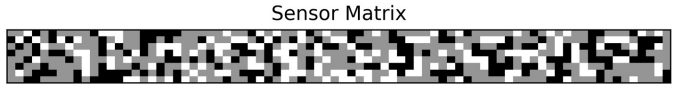



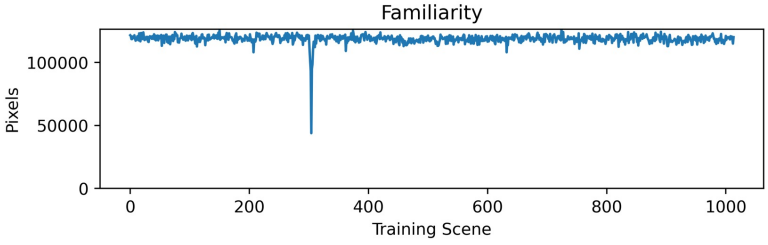

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

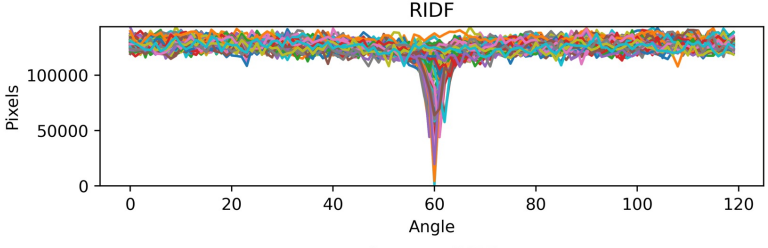
Navigation stats: RMSD error: 1850.69; RMSD/dist: 4.627; TD: 1609; p90: 2; p50: 2; complete: 0

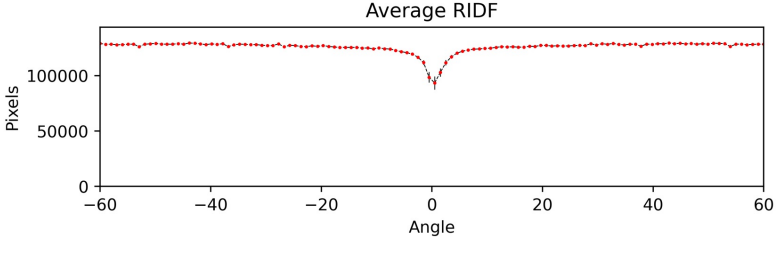
80%



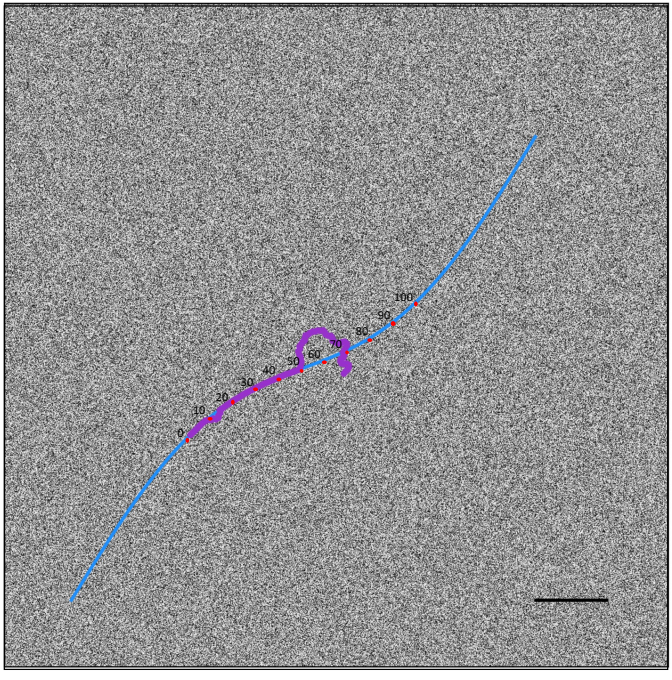



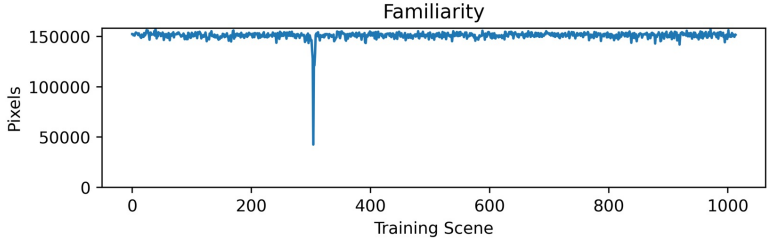



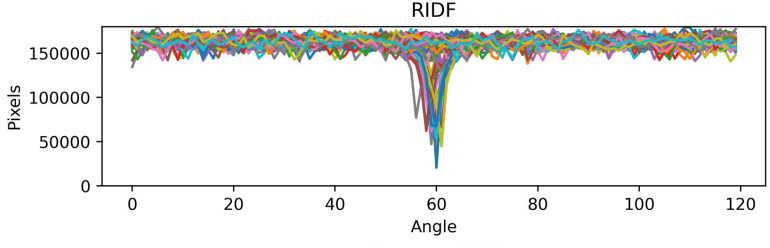

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

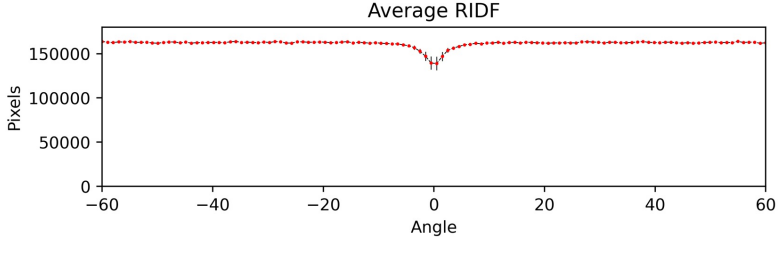
Navigation stats: RMSD error: 272.58; RMSD/dist: 0.681; TD: 24434; p90: 6; p50: 4; complete: 0

50%



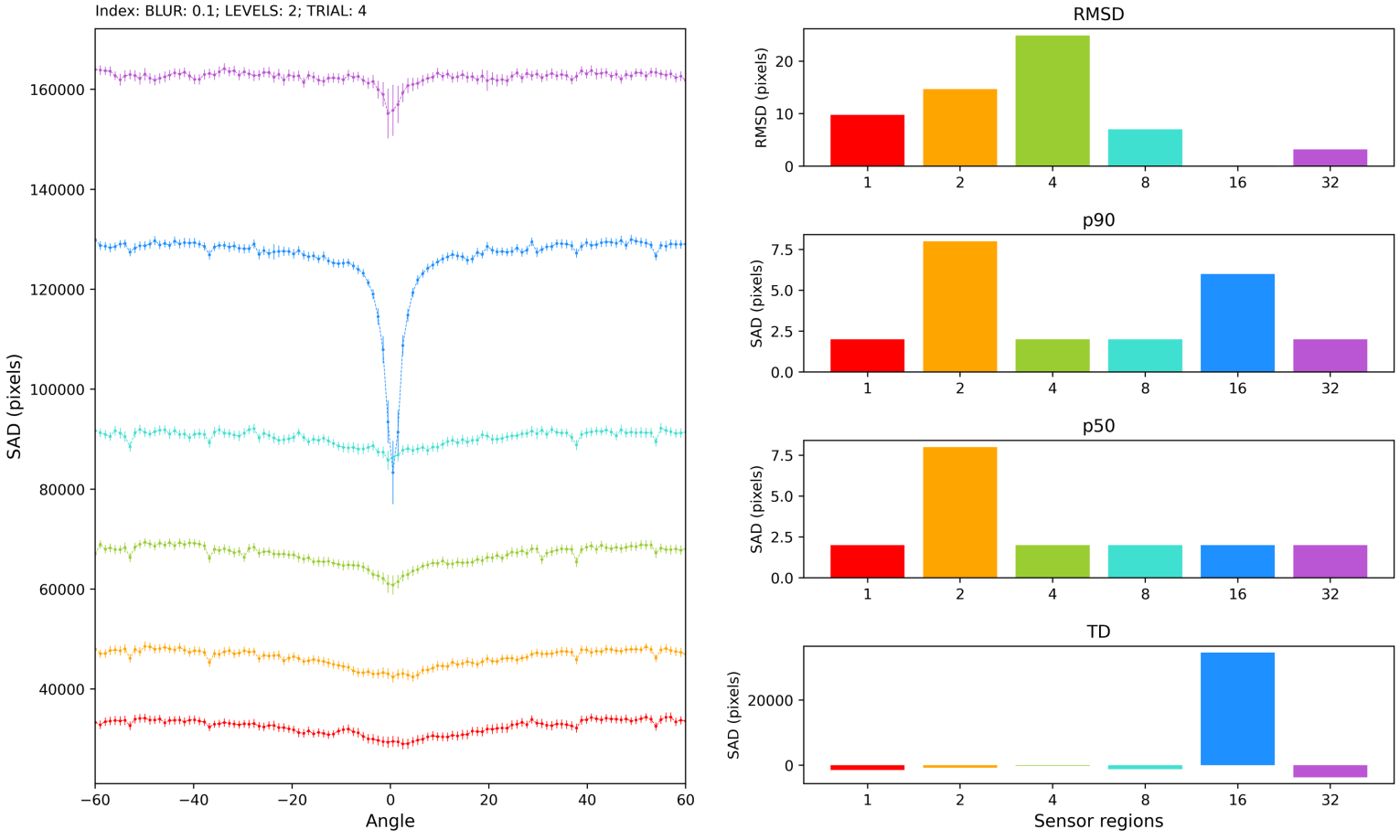


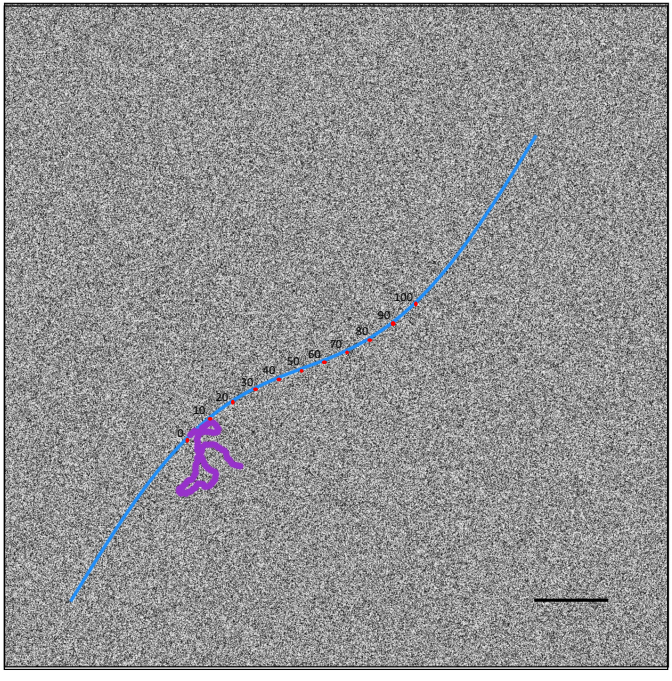



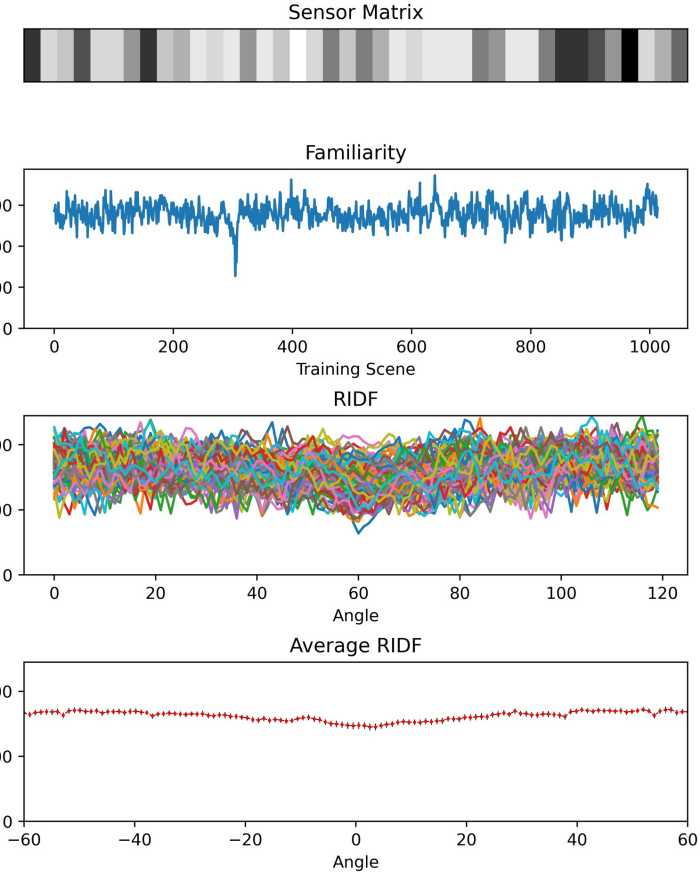

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1225.95; RMSD/dist: 3.065; TD: 12509; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 2; TRIAL: 4
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
TD
20000
Sensor regions

0%

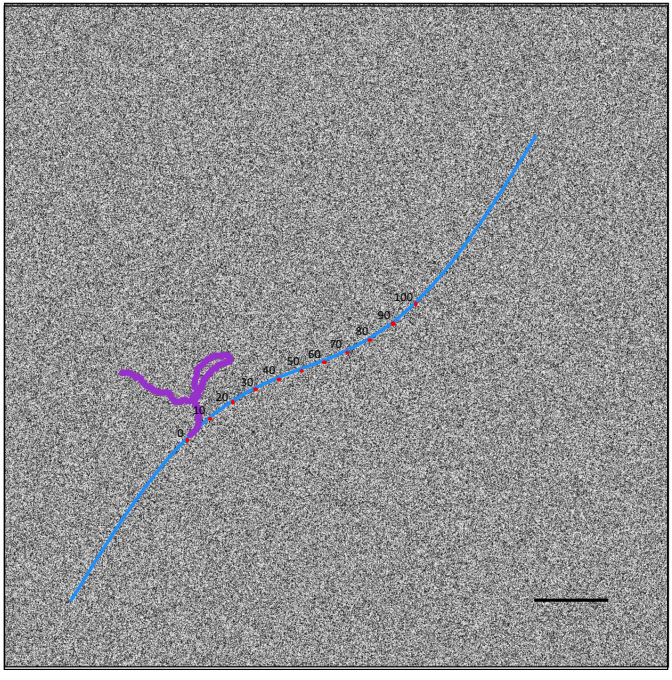


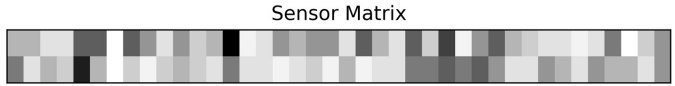



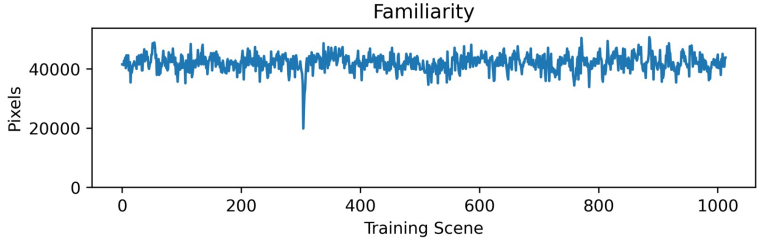

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

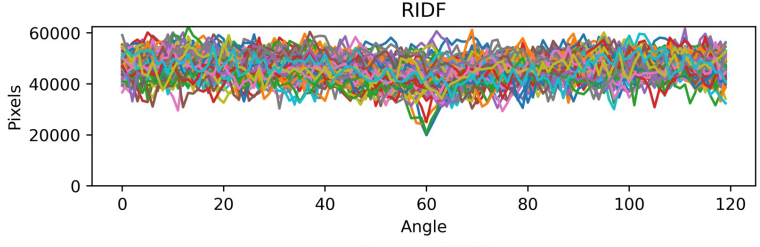
Navigation stats: RMSD error: 3898.21; RMSD/dist: 9.746; TD: -1501; p90: 2; p50: 2; complete: 0

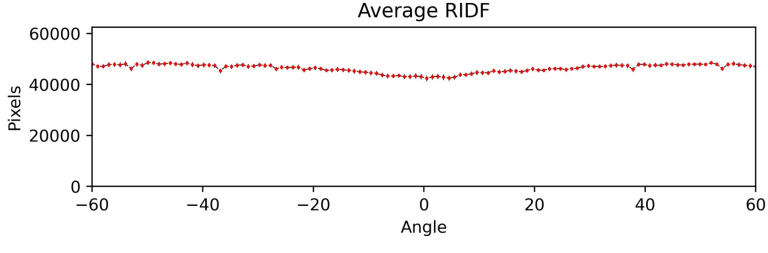
0%



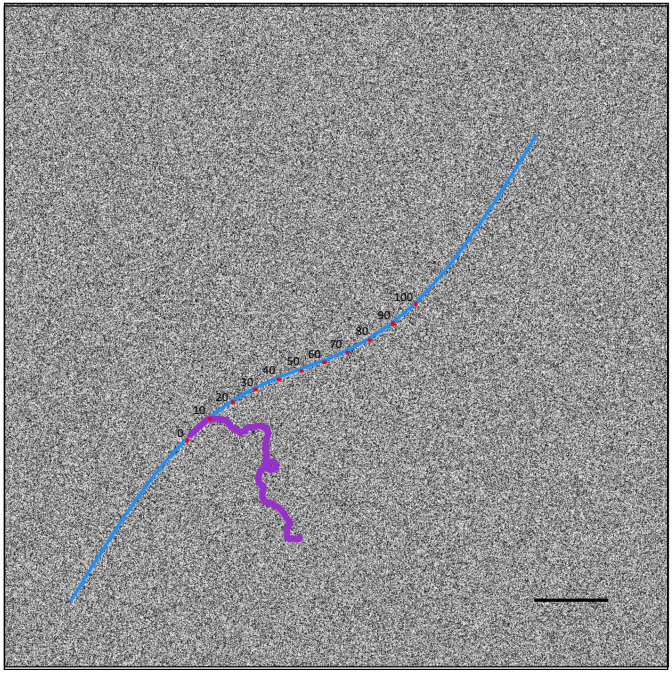



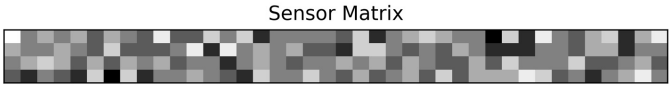



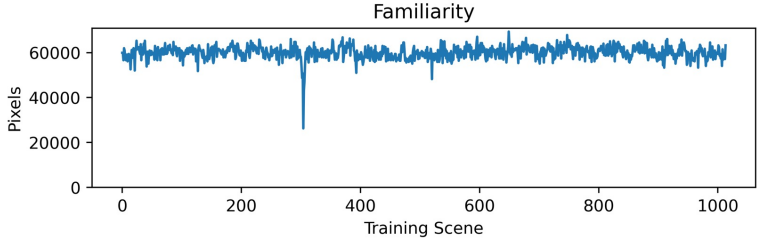

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

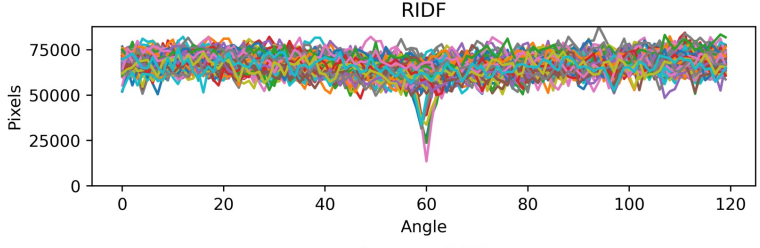
Navigation stats: RMSD error: 5876.68; RMSD/dist: 14.692; TD: -752; p90: 8; p50: 8; complete: 0

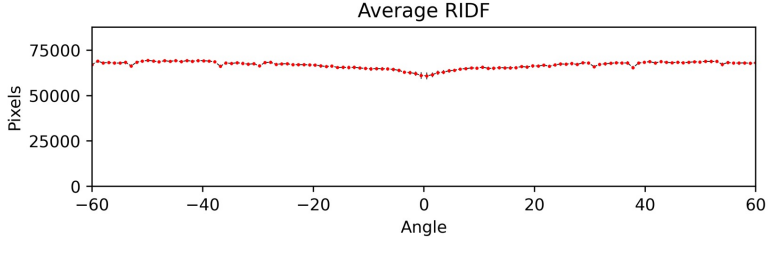
10%



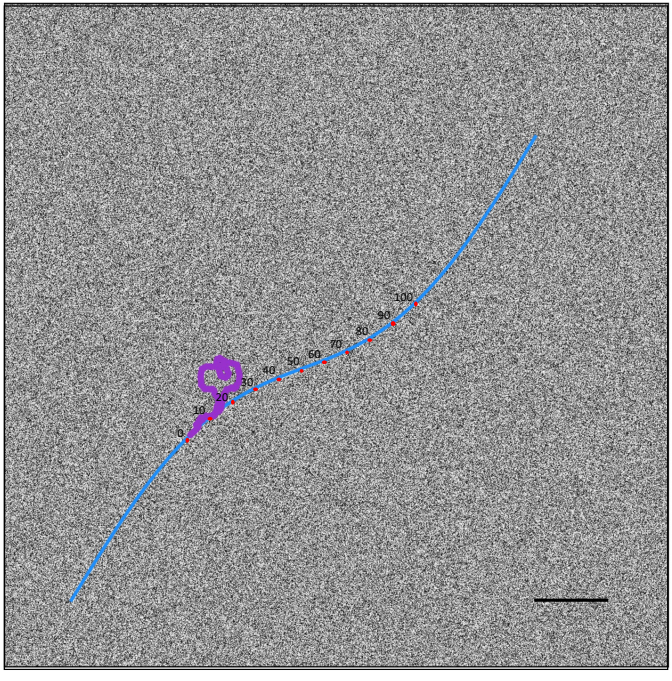



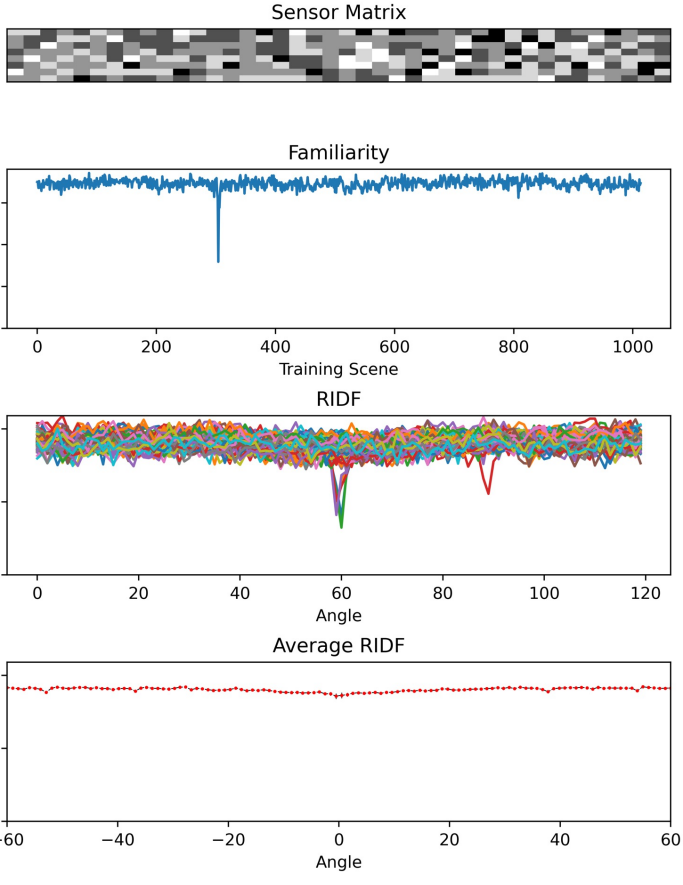




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 9963.65; RMSD/dist: 24.909; TD: -196; p90: 2; p50: 2; complete: 0

10%

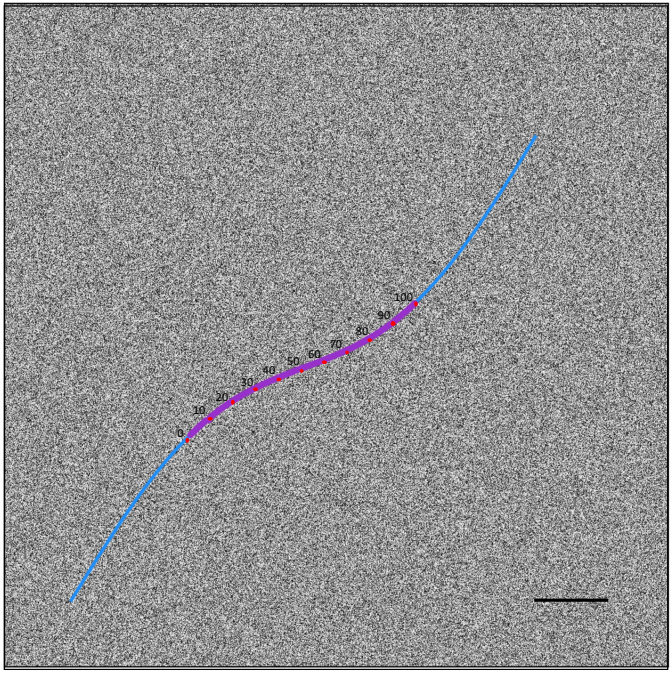


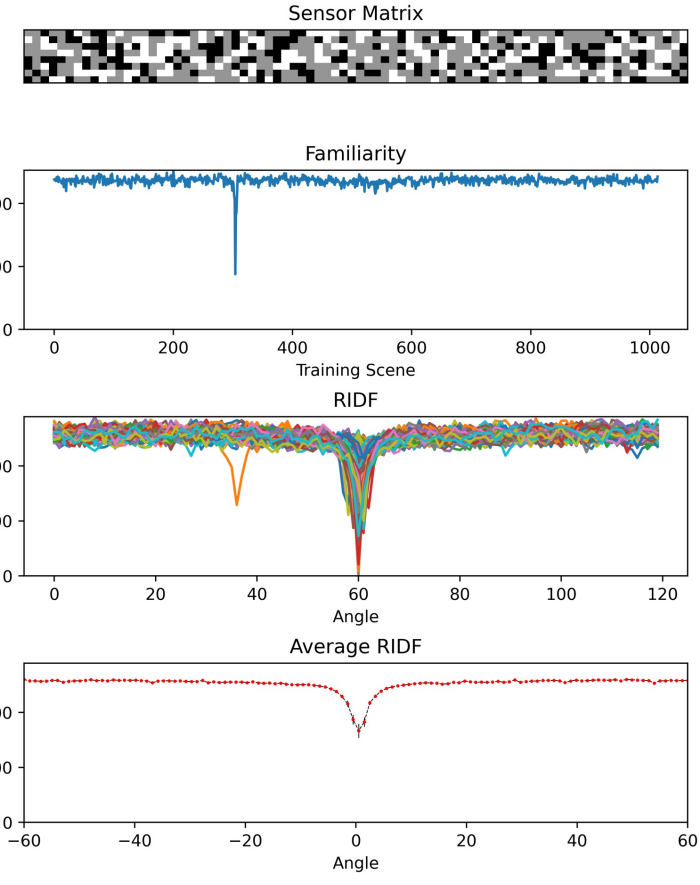




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2805.56; RMSD/dist: 7.014; TD: -1200; p90: 2; p50: 2; complete: 0

100%

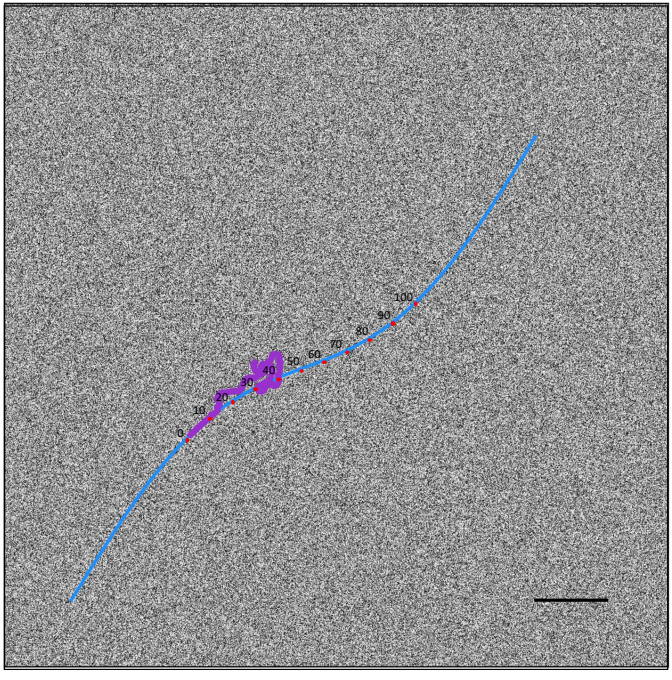


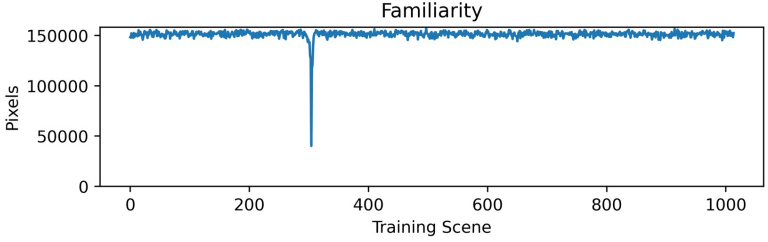



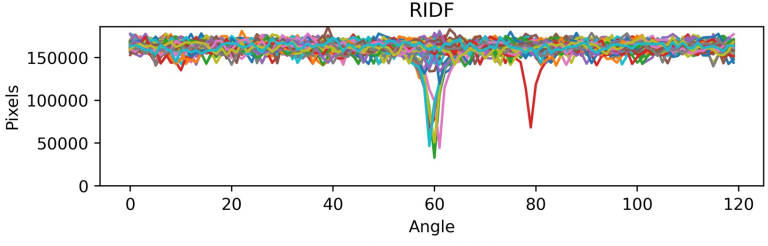

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

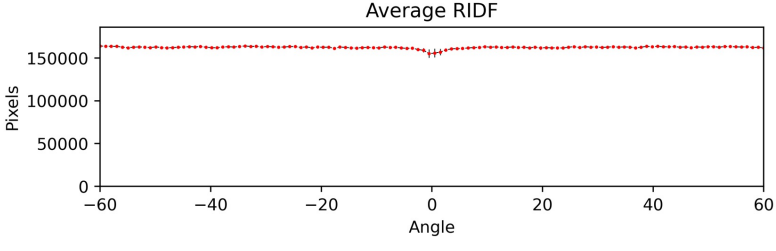
Navigation stats: RMSD error: 35.48; RMSD/dist: 0.089; TD: 34631; p90: 6; p50: 2; complete: 0

10%



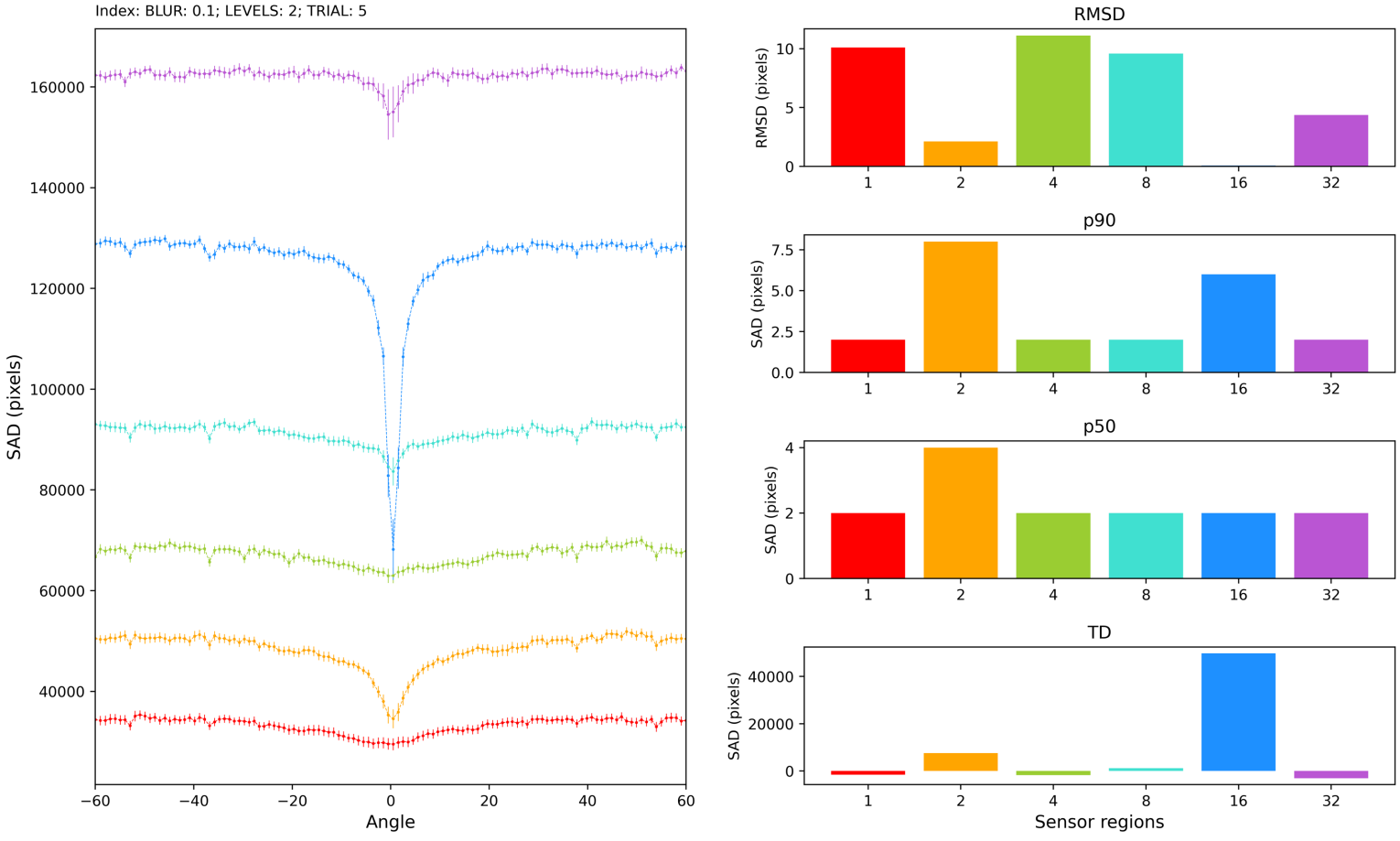


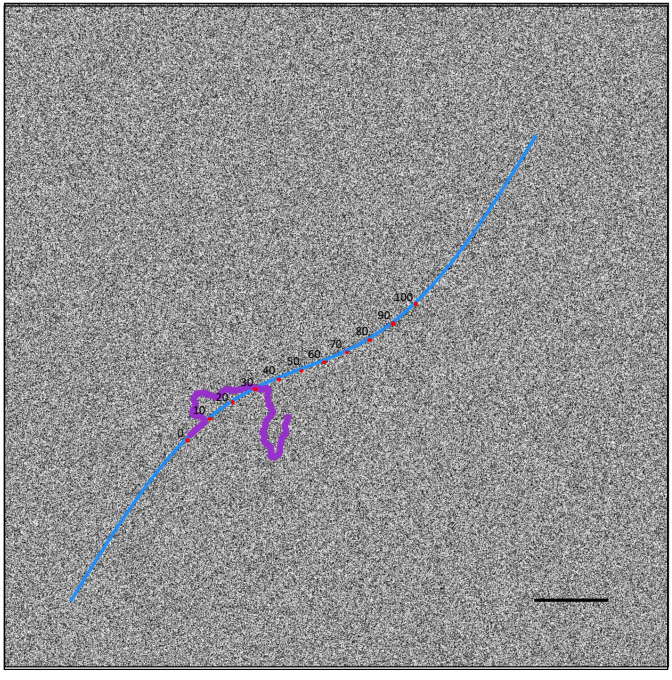



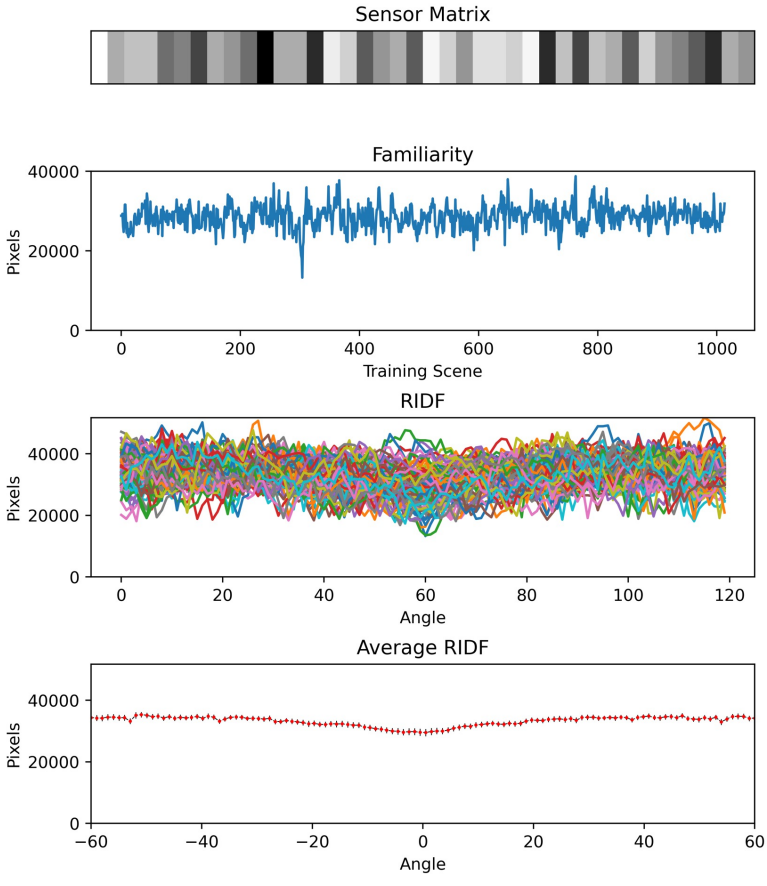

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1277.49; RMSD/dist: 3.194; TD: -3722; p90: 2; p50: 2; complete: 0


Index: BLUR: 0.1; LEVELS: 2; TRIAL: 5
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
4
2
TD
40000
20000
Sensor regions

10%

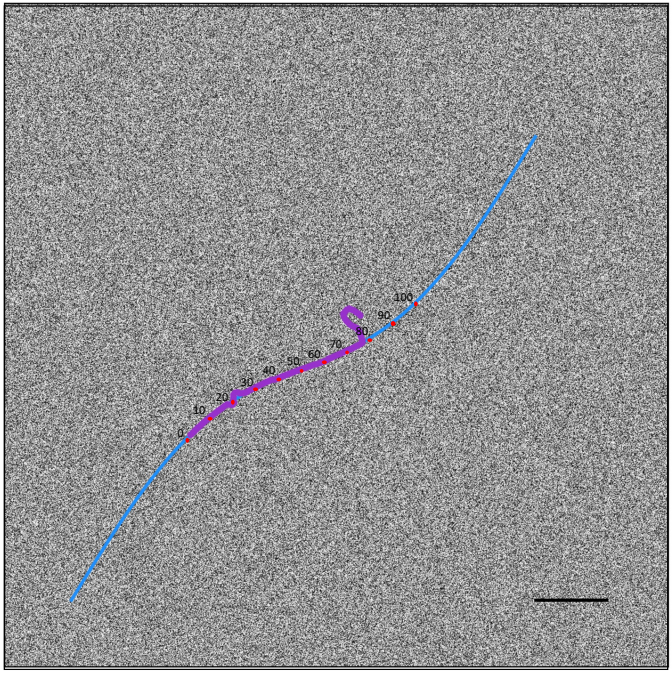


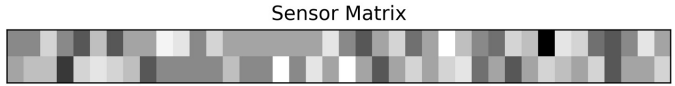



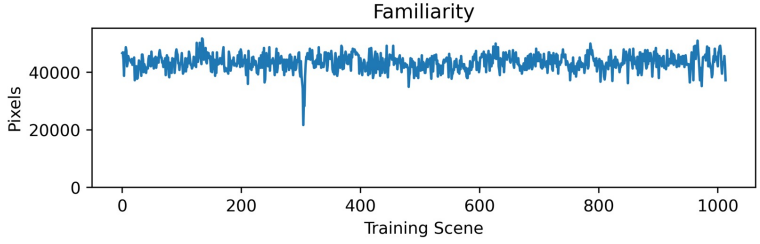

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

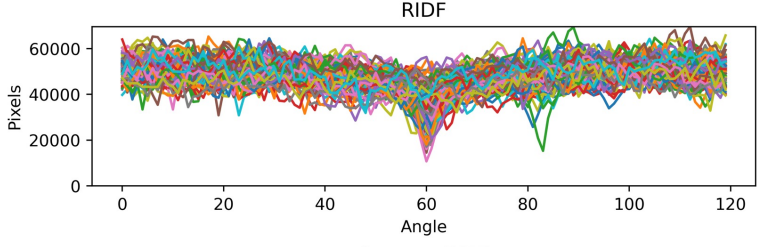
Navigation stats: RMSD error: 4041.47; RMSD/dist: 10.104; TD: -1604; p90: 2; p50: 2; complete: 0

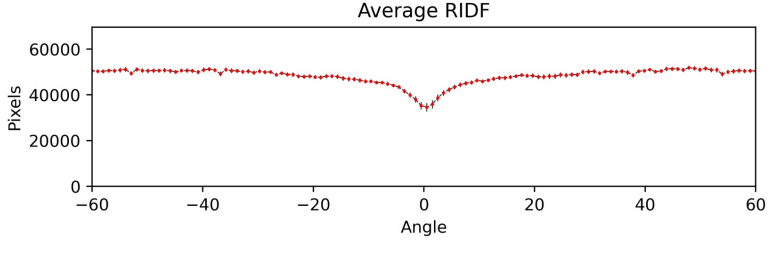
70%



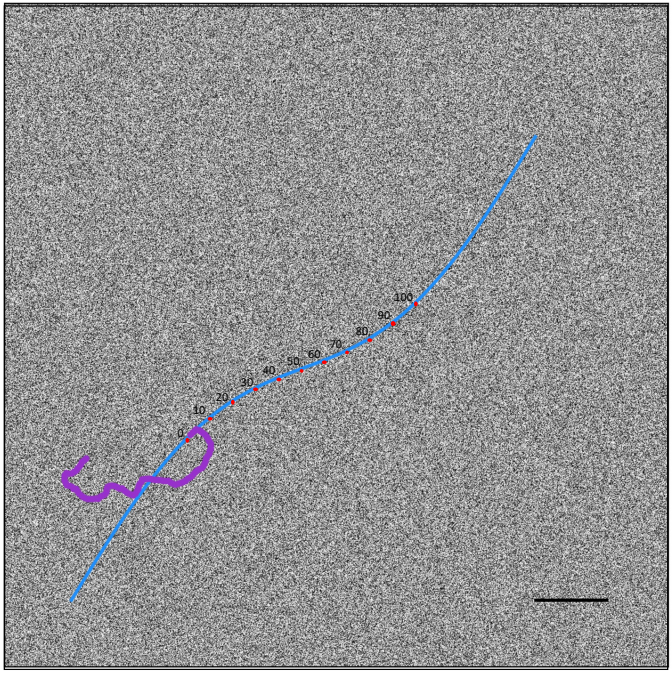



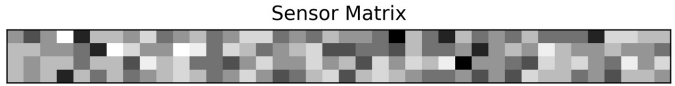



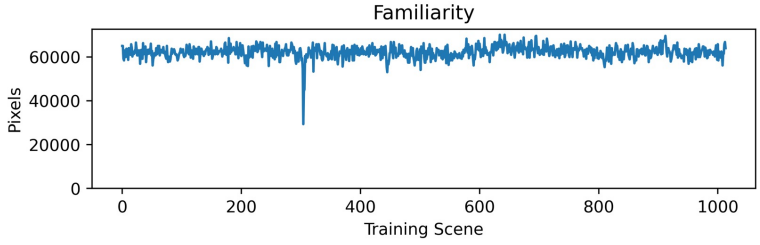

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

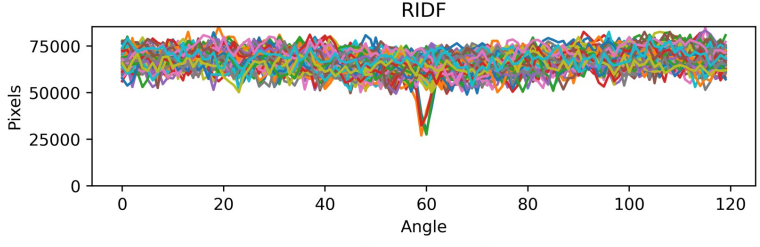
Navigation stats: RMSD error: 848.55; RMSD/dist: 2.121; TD: 7534; p90: 8; p50: 4; complete: 0

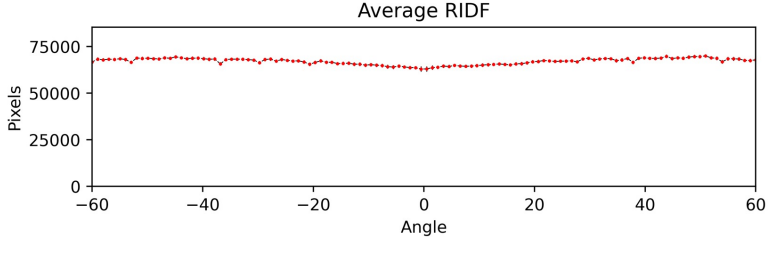
0%



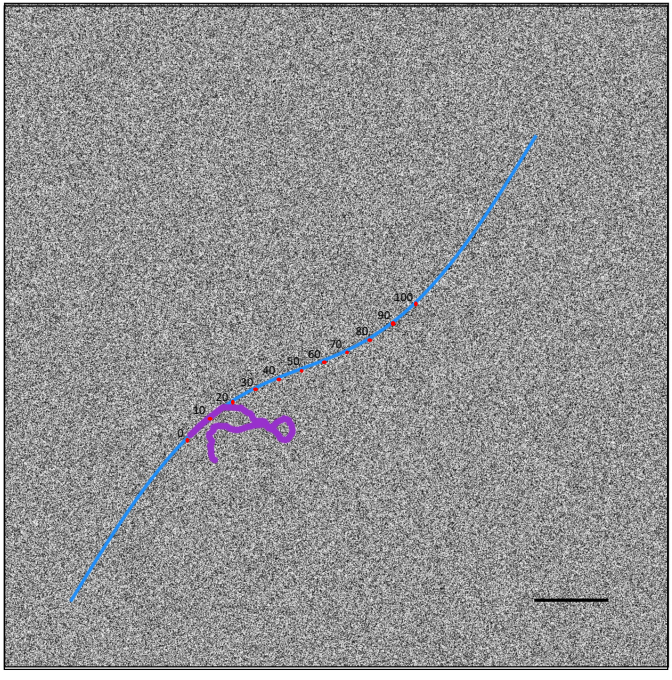



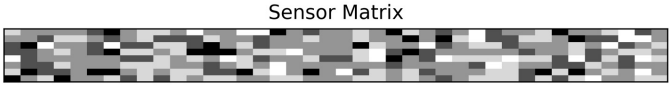



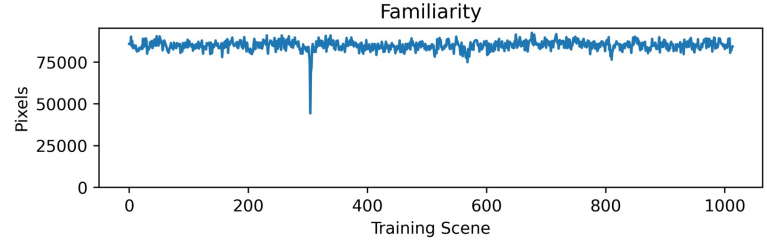

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

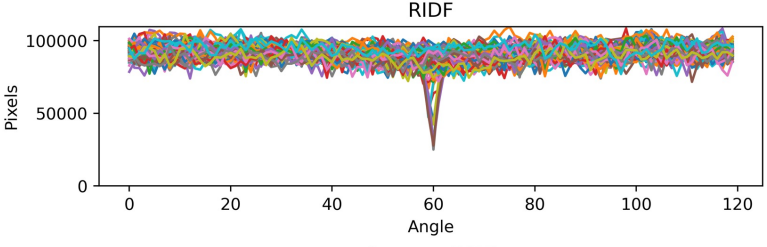
Navigation stats: RMSD error: 4448.65; RMSD/dist: 11.122; TD: -1722; p90: 2; p50: 2; complete: 0

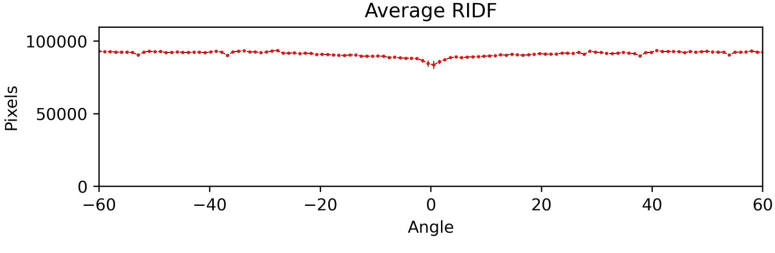
10%



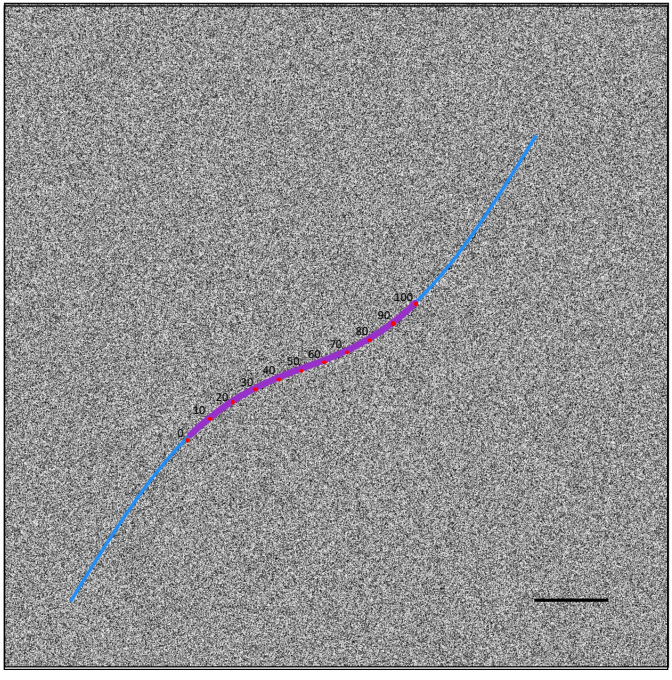



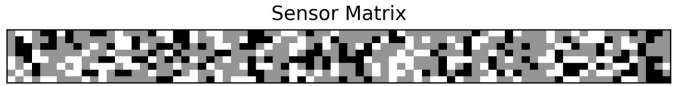



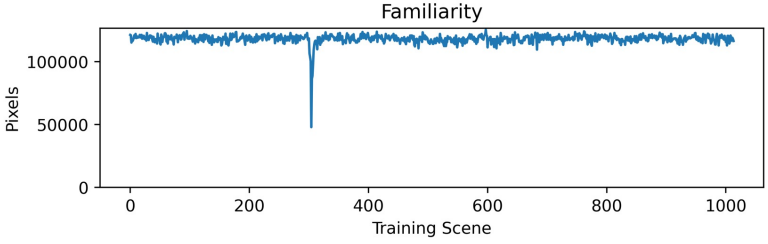

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

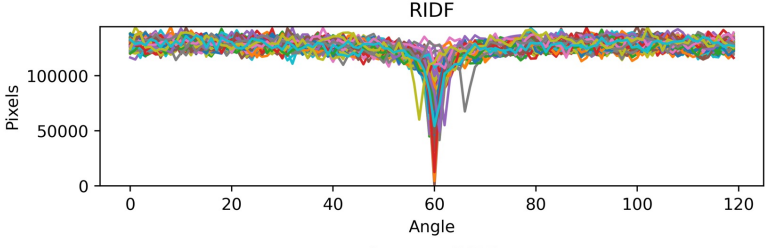
Navigation stats: RMSD error: 3830.69; RMSD/dist: 9.577; TD: 1144; p90: 2; p50: 2; complete: 0

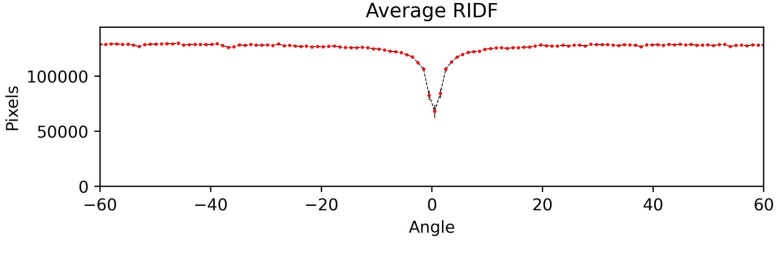
100%



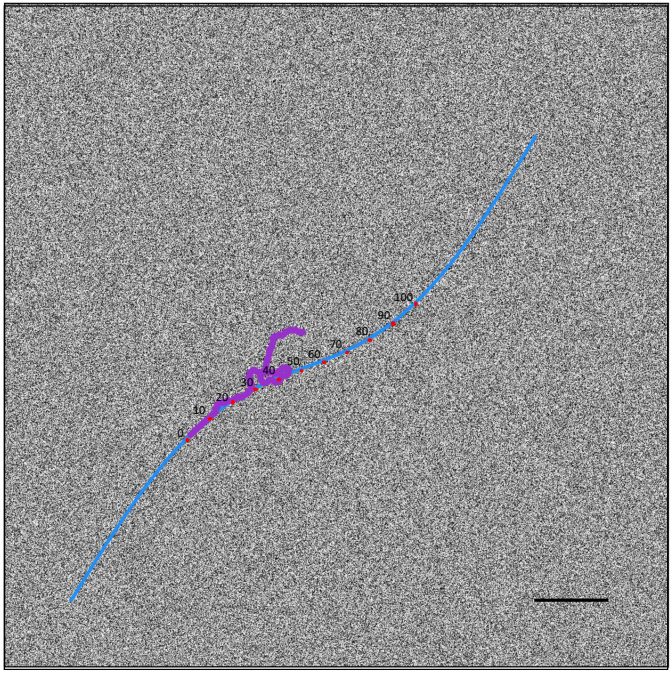



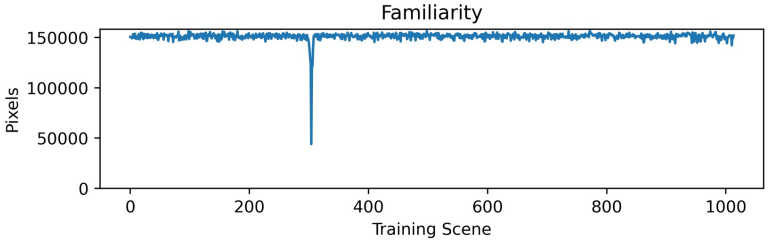



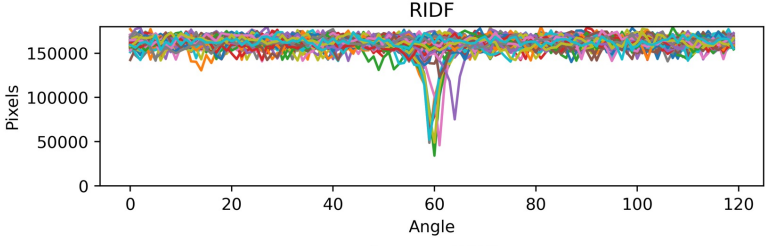

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

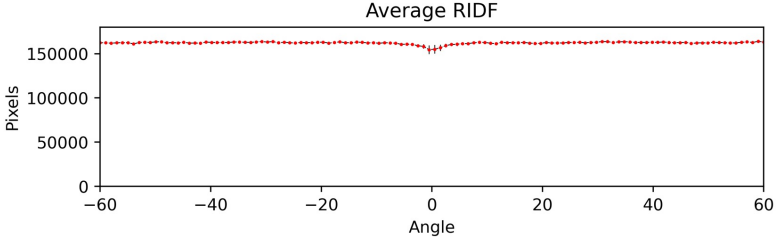
Navigation stats: RMSD error: 26.89; RMSD/dist: 0.067; TD: 49733; p90: 6; p50: 2; complete: 0

30%



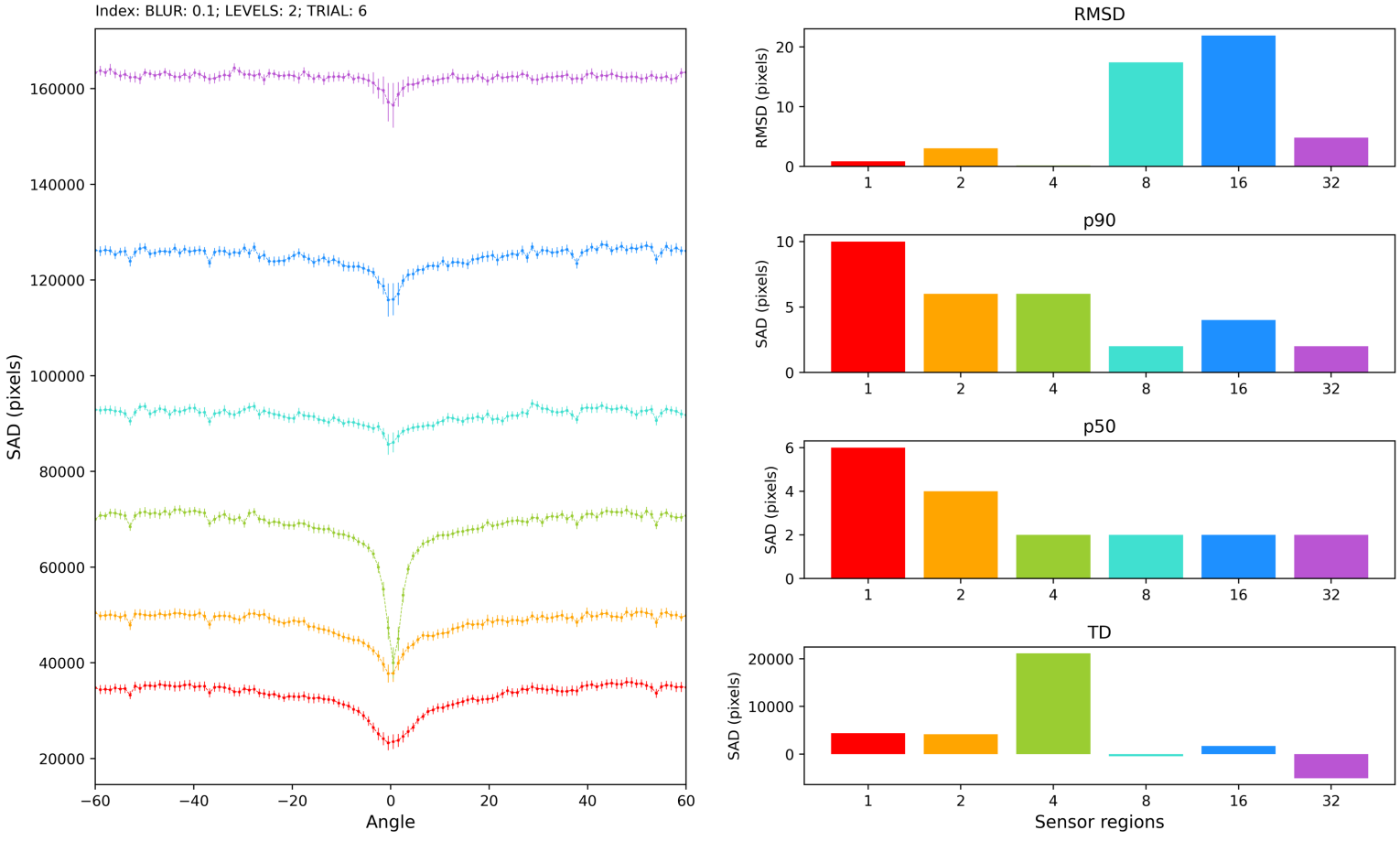


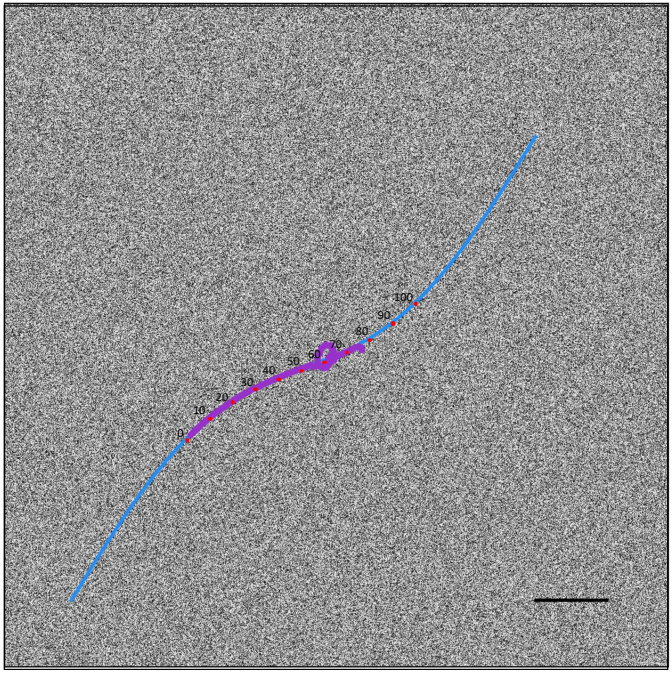



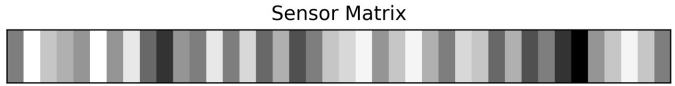

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

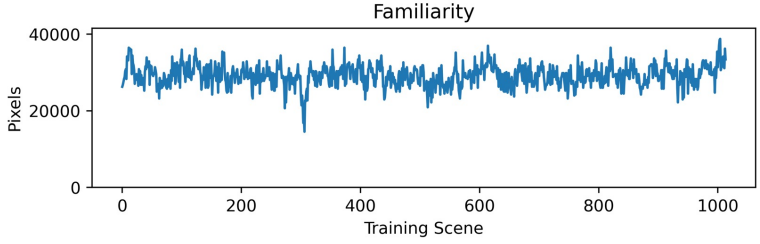
Navigation stats: RMSD error: 1747.11; RMSD/dist: 4.368; TD: -3055; p90: 2; p50: 2; complete: 0

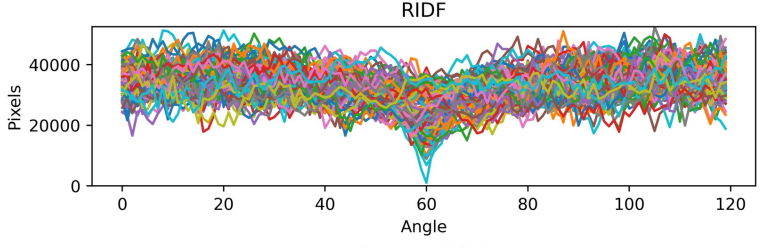

Index: BLUR: 0.1; LEVELS: 2; TRIAL: 6
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
6
4
2
TD
20000
10000
Sensor regions

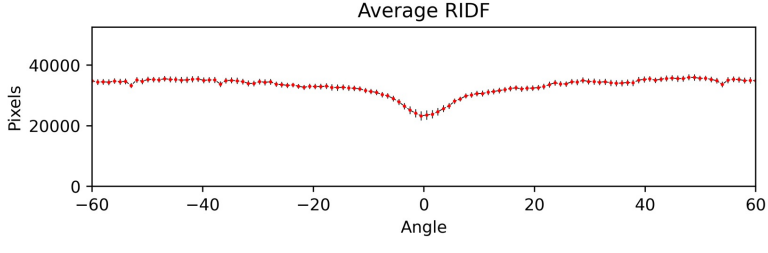
70%



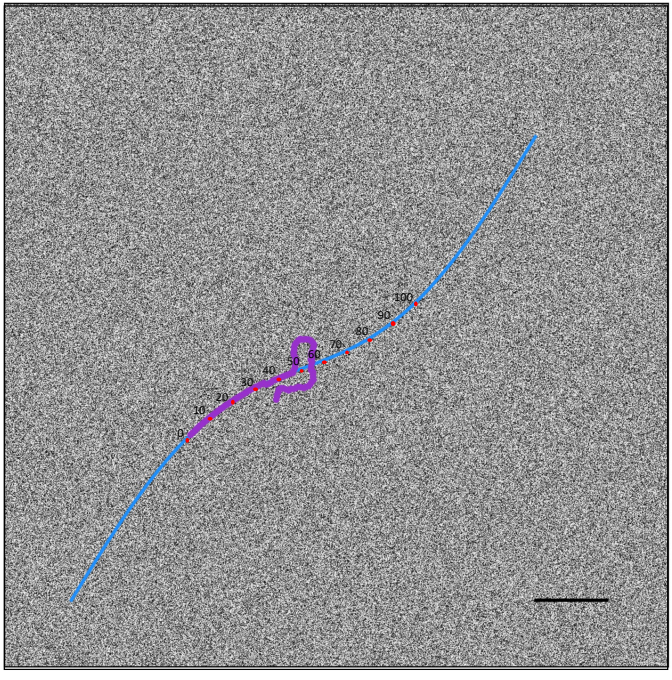



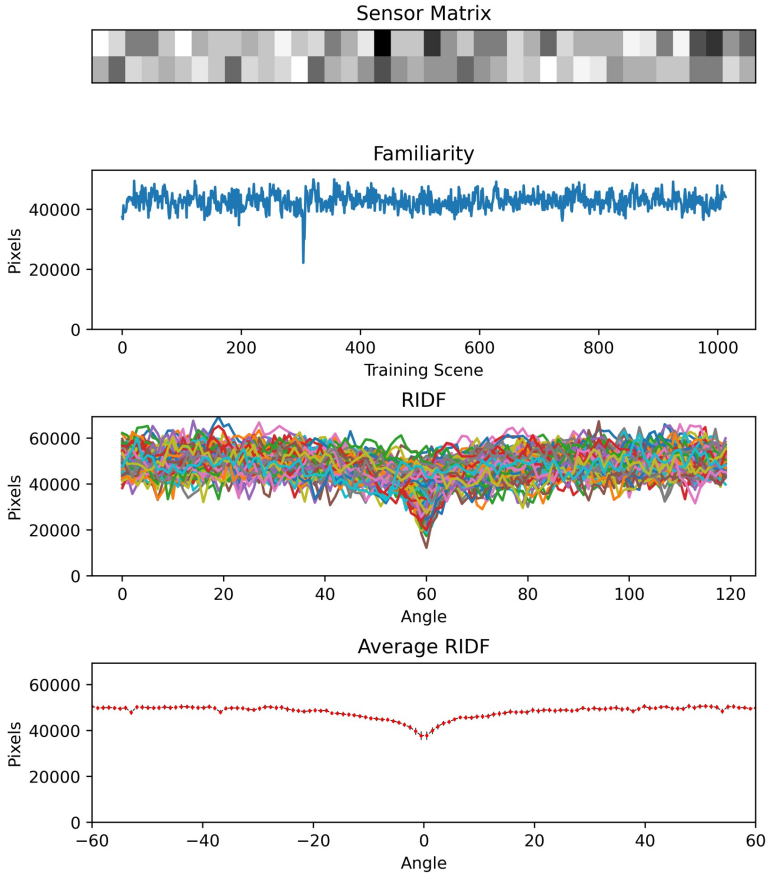




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 333.03; RMSD/dist: 0.833; TD: 4393; p90: 10; p50: 6; complete: 0

40%

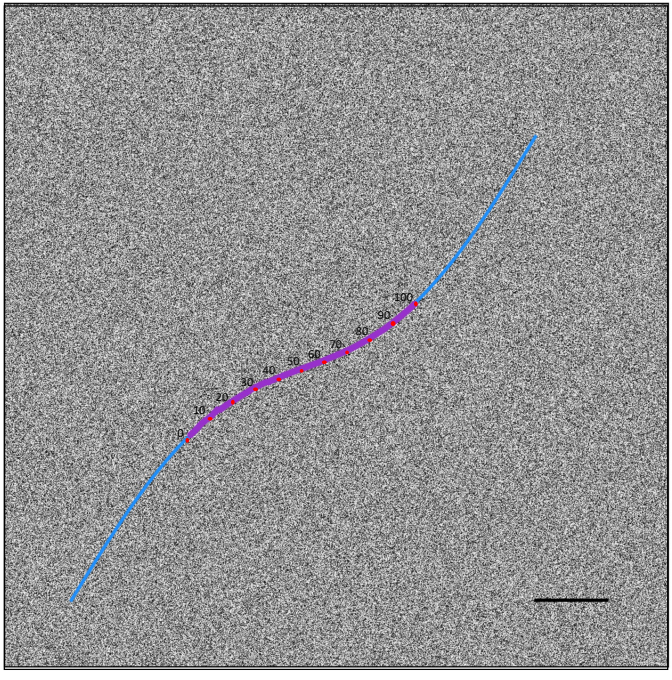


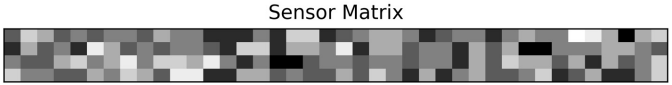



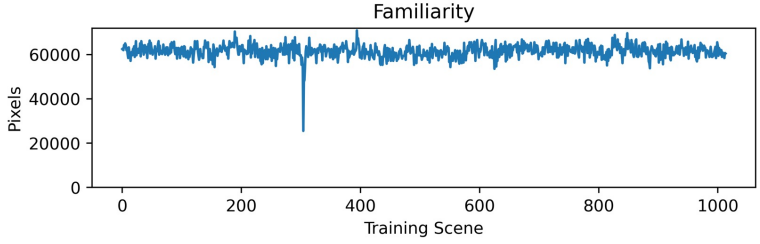

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

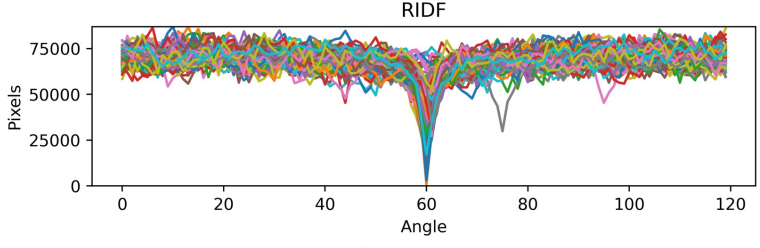
Navigation stats: RMSD error: 1206.43; RMSD/dist: 3.016; TD: 4160; p90: 6; p50: 4; complete: 0

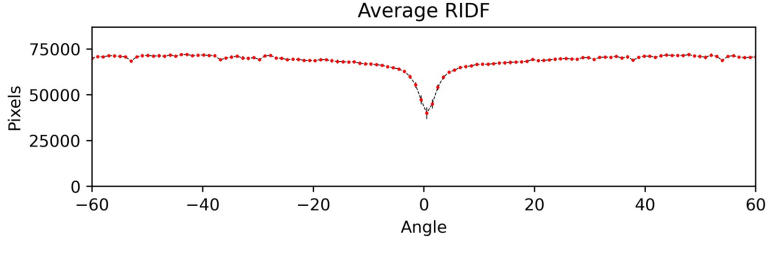
100%



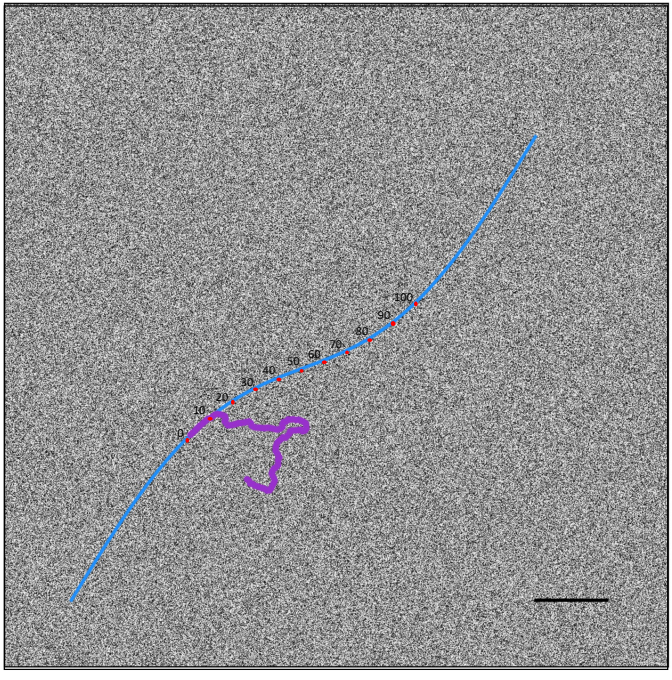



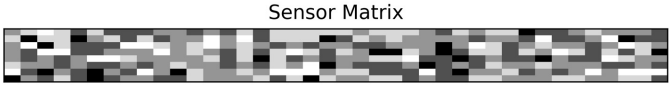



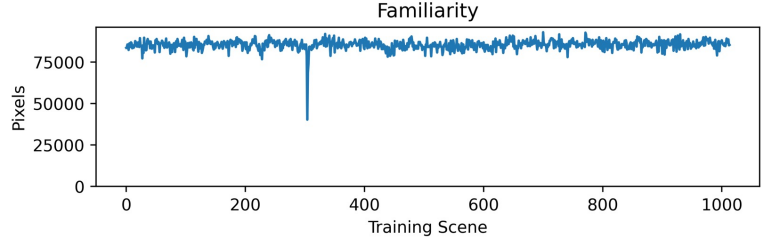

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

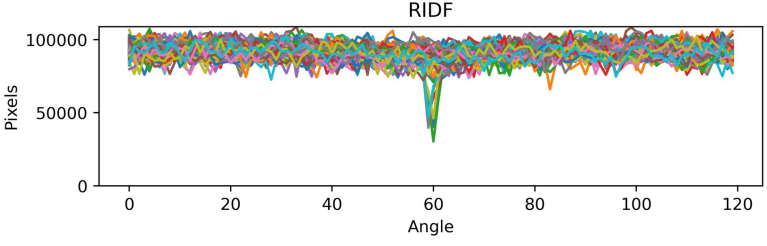
Navigation stats: RMSD error: 50.33; RMSD/dist: 0.126; TD: 21137; p90: 6; p50: 2; complete: 0

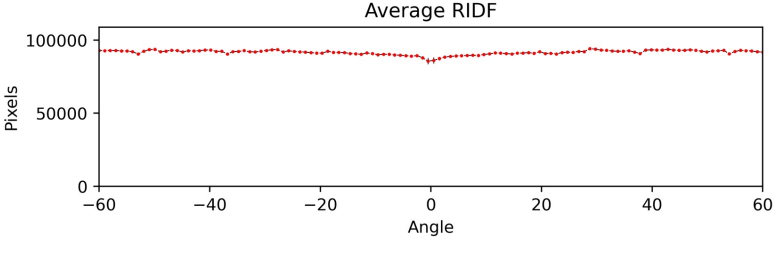
10%



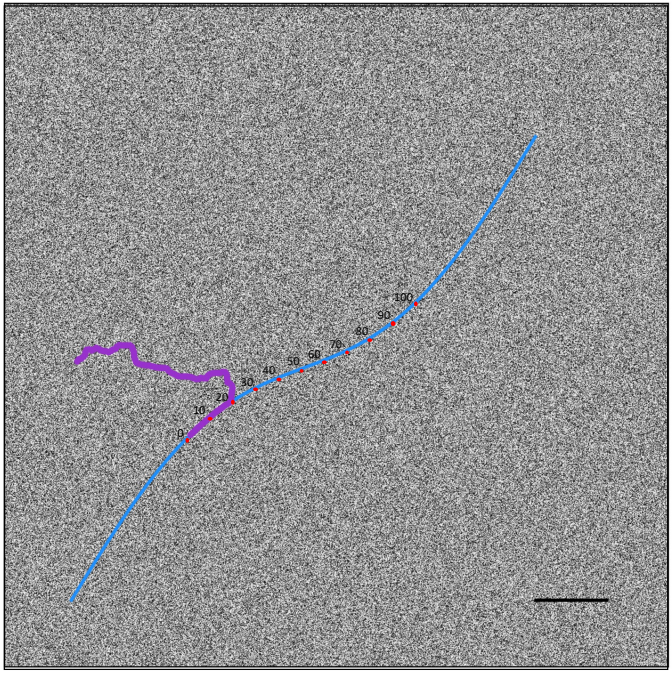



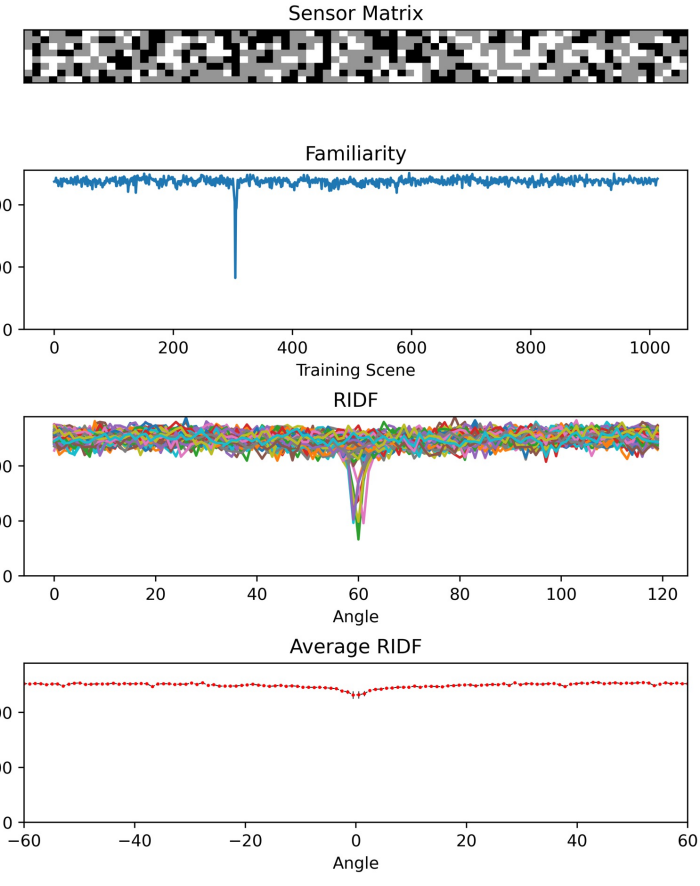




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 6965.34; RMSD/dist: 17.413; TD: -450; p90: 2; p50: 2; complete: 0

20%

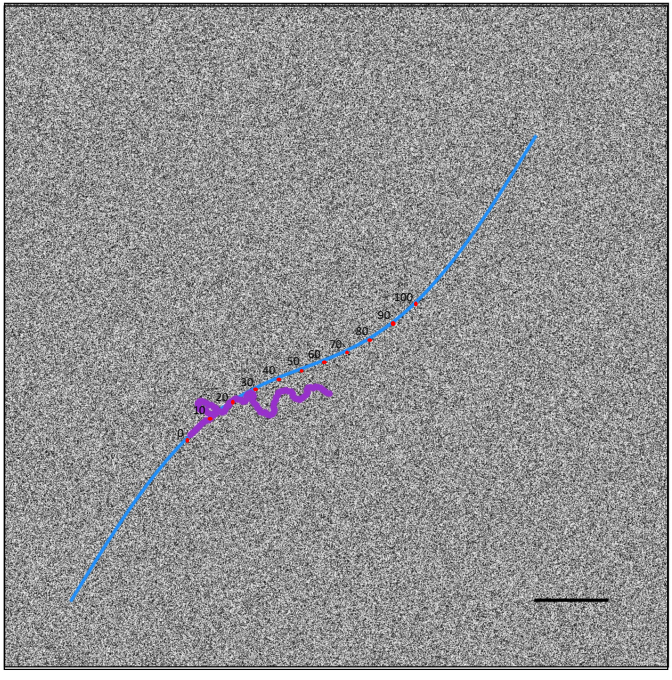


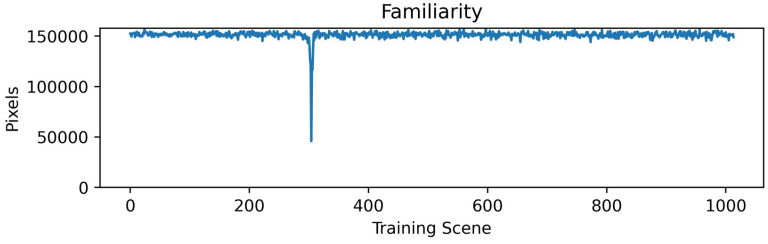



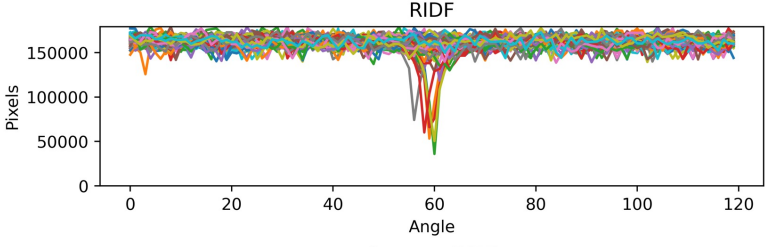

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

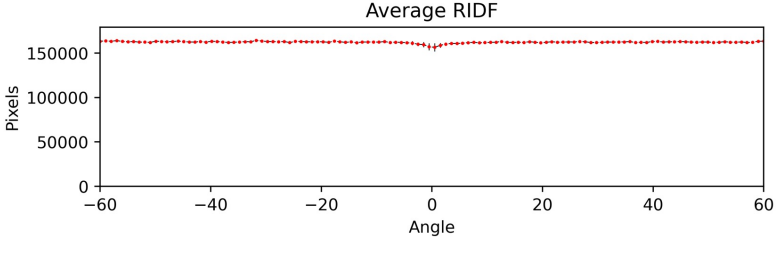
Navigation stats: RMSD error: 8770.41; RMSD/dist: 21.926; TD: 1734; p90: 4; p50: 2; complete: 0

10%



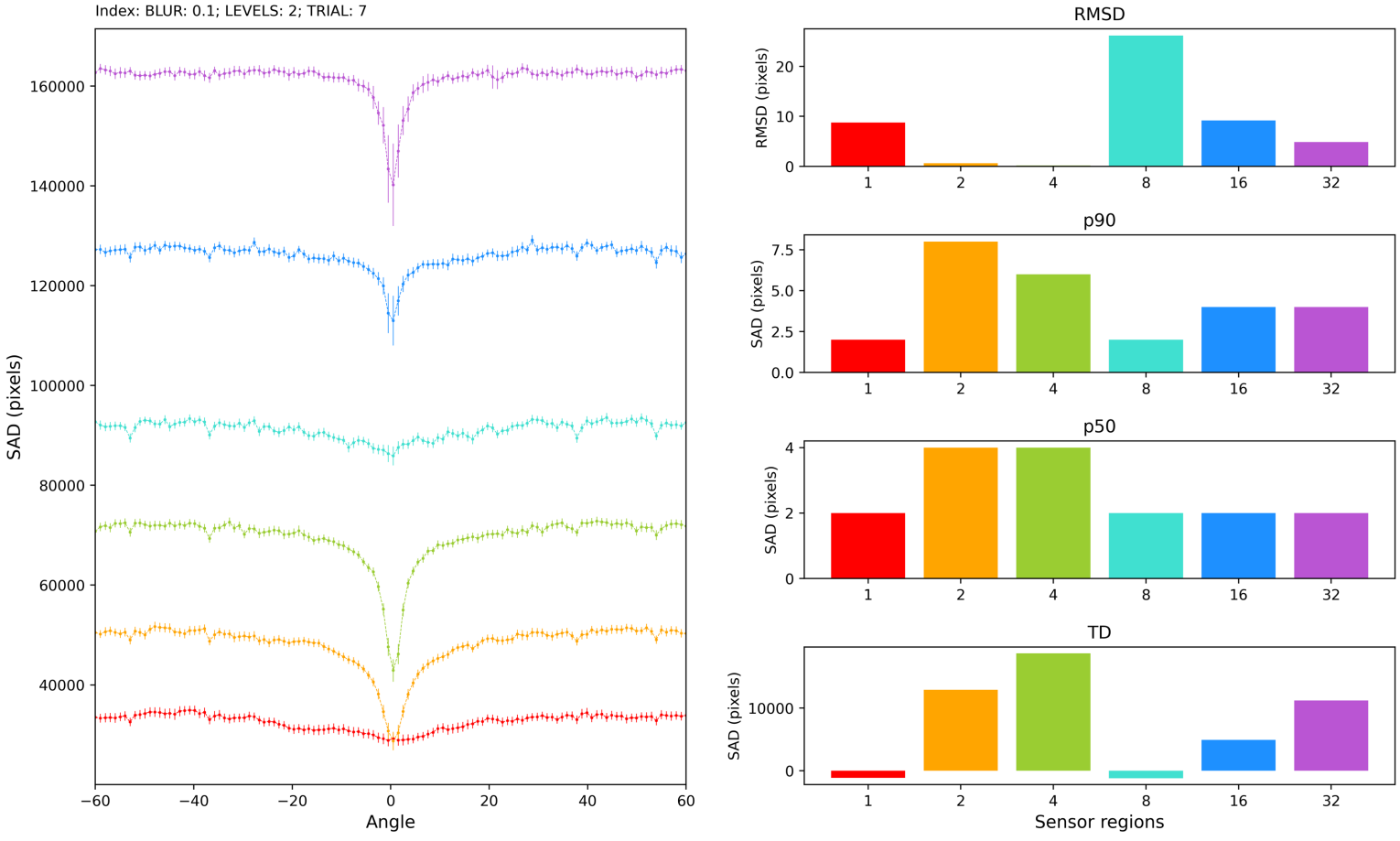


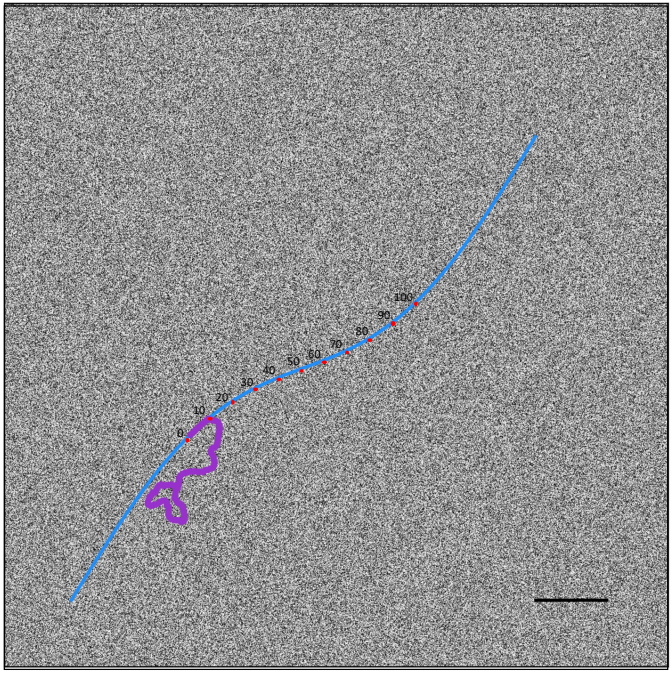



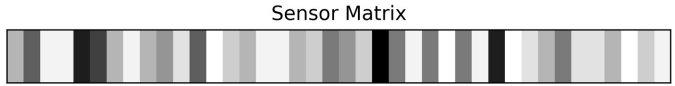

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

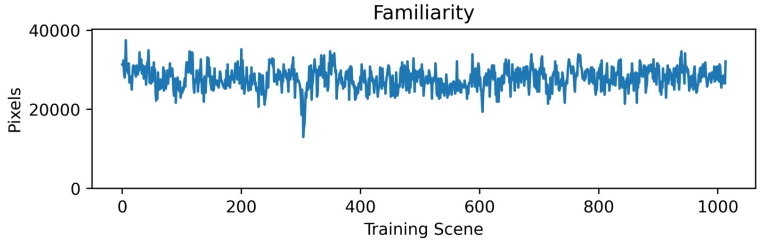
Navigation stats: RMSD error: 1915.07; RMSD/dist: 4.788; TD: -5048; p90: 2; p50: 2; complete: 0

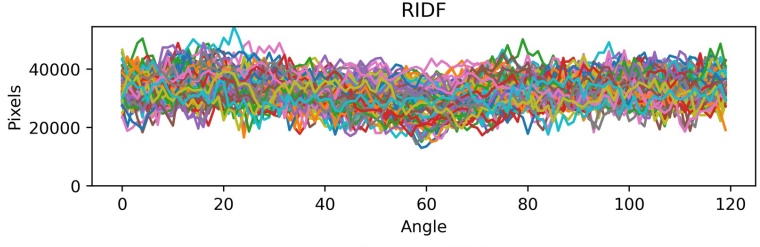

Index: BLUR: 0.1; LEVELS: 2; TRIAL: 7
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
4
2
TD
10000
Sensor regions

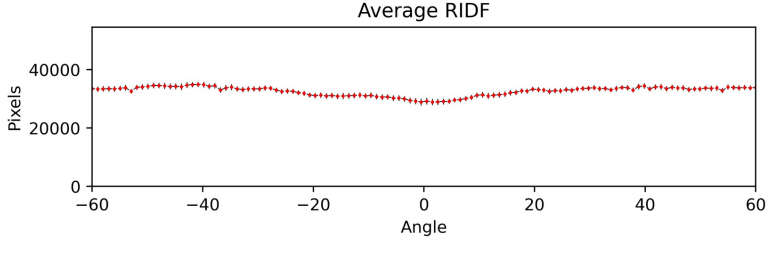
10%



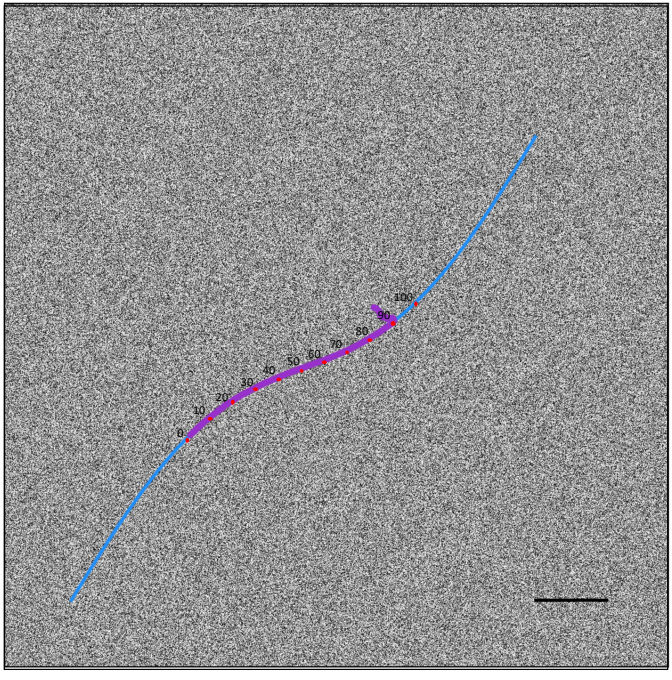



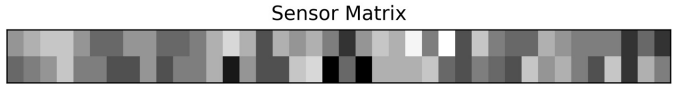



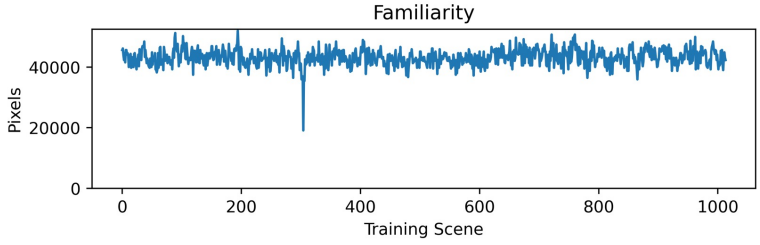

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

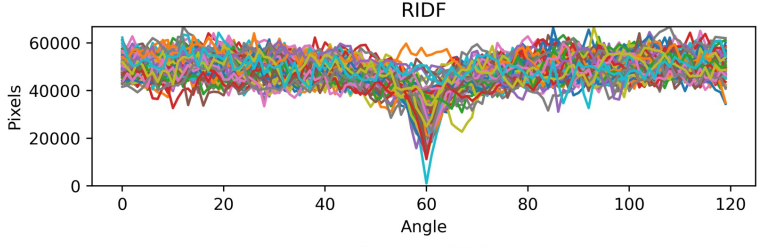
Navigation stats: RMSD error: 3496.01; RMSD/dist: 8.740; TD: -1135; p90: 2; p50: 2; complete: 0

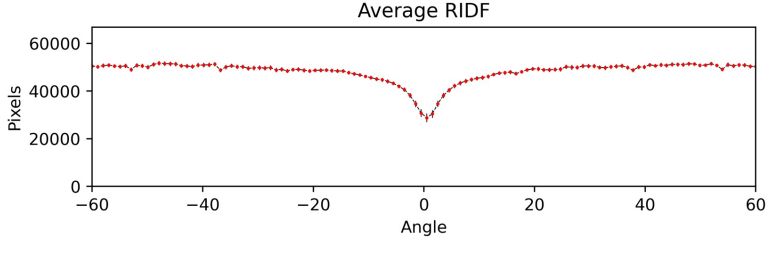
90%



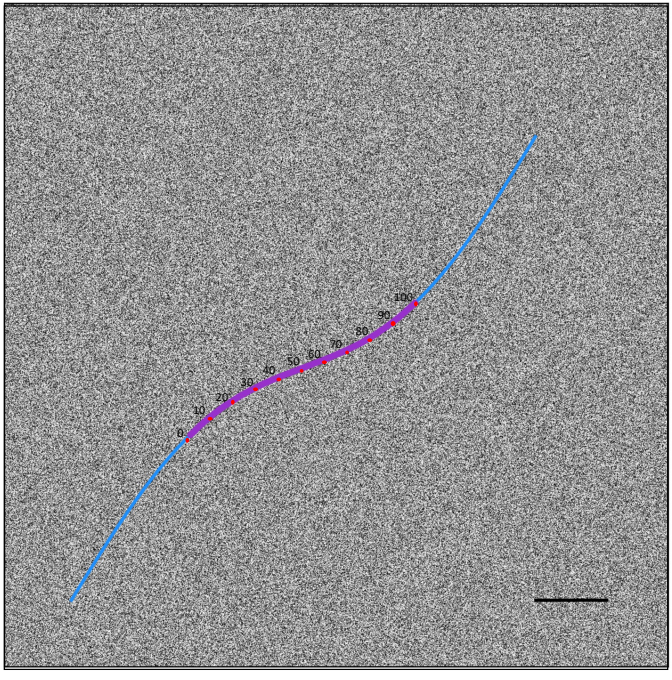



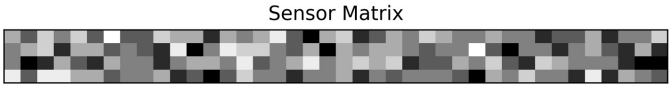



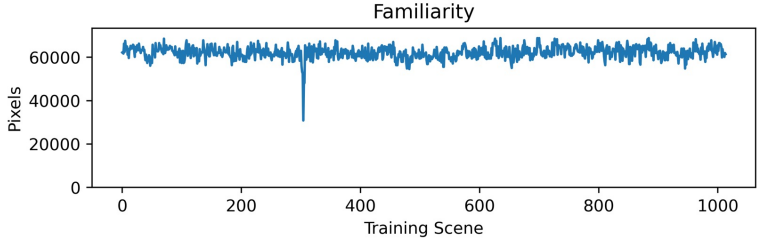

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

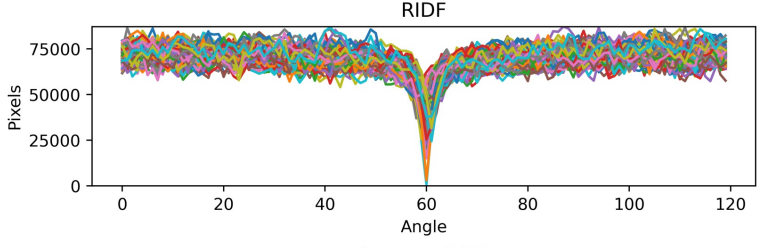
Navigation stats: RMSD error: 241.50; RMSD/dist: 0.604; TD: 12921; p90: 8; p50: 4; complete: 0

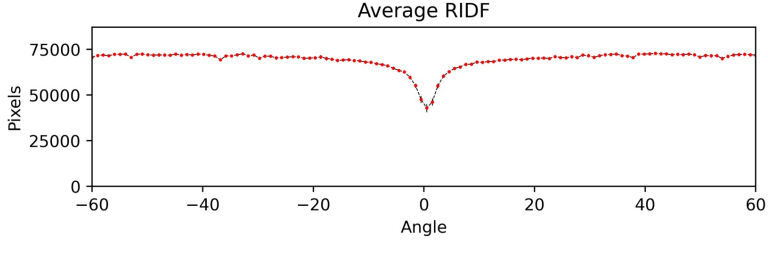
100%



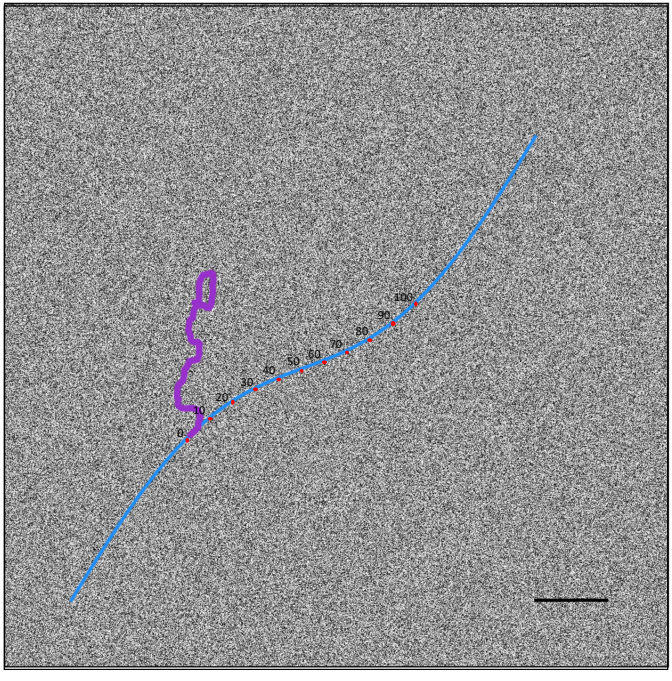



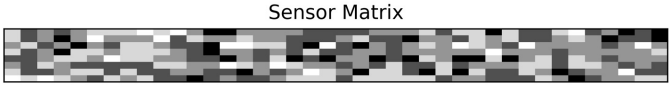



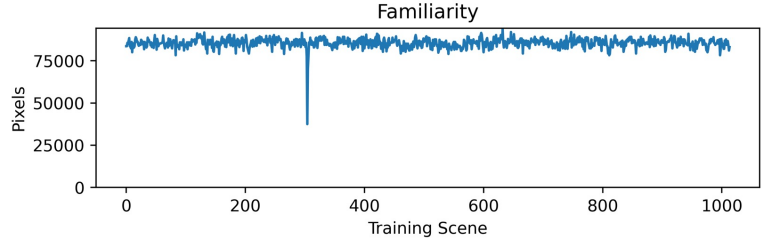

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

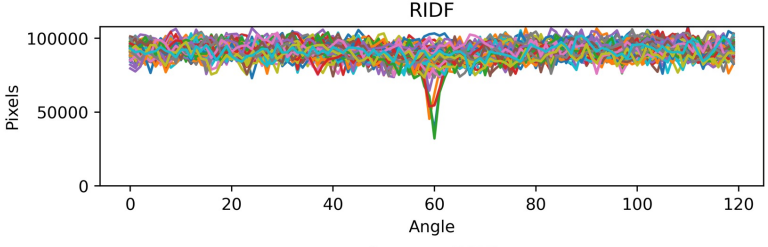
Navigation stats: RMSD error: 57.53; RMSD/dist: 0.144; TD: 18759; p90: 6; p50: 4; complete: 0

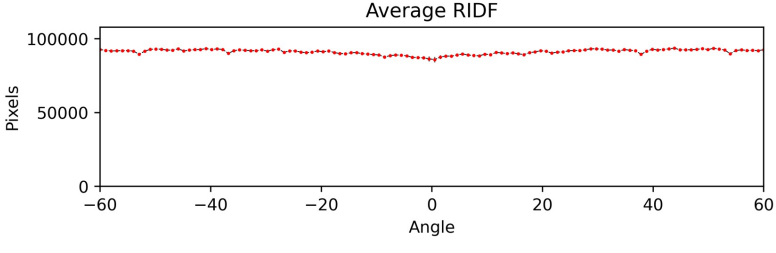
0%



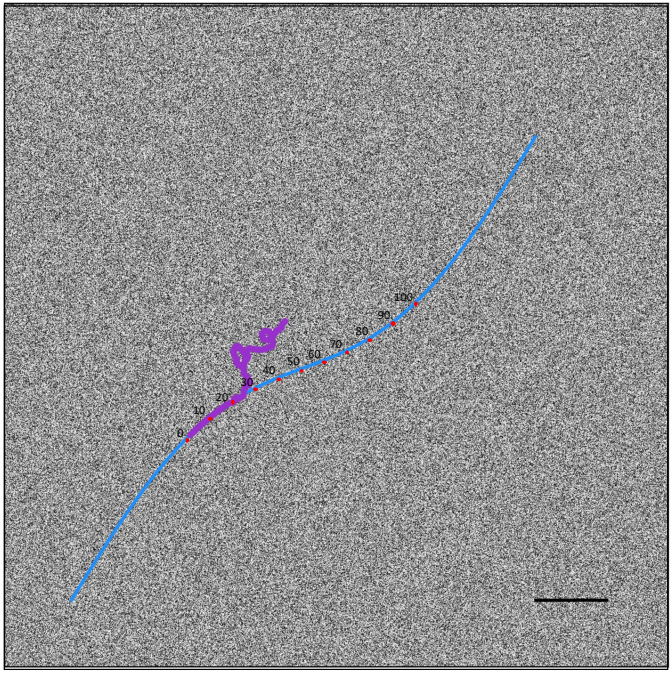



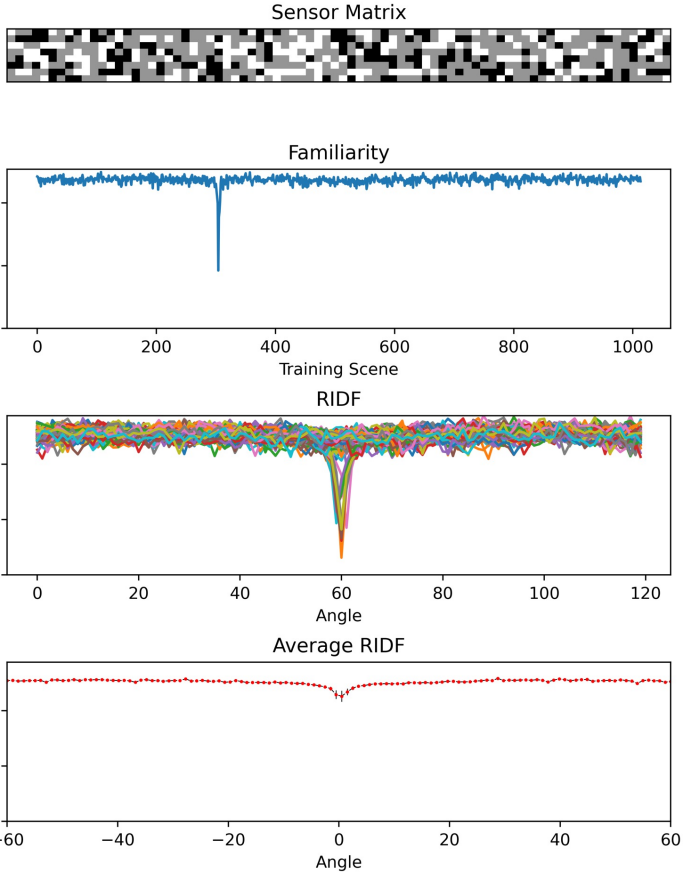




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 10468.08; RMSD/dist: 26.170; TD: -1204; p90: 2; p50: 2; complete: 0

20%

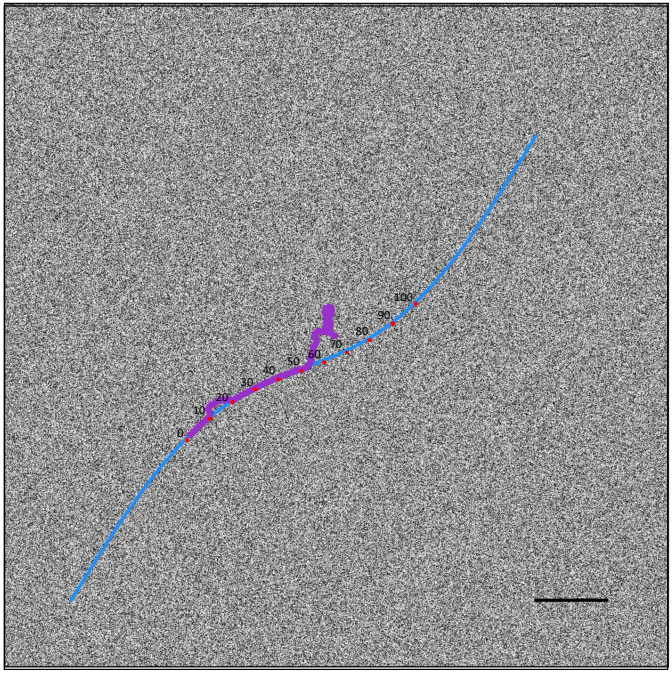


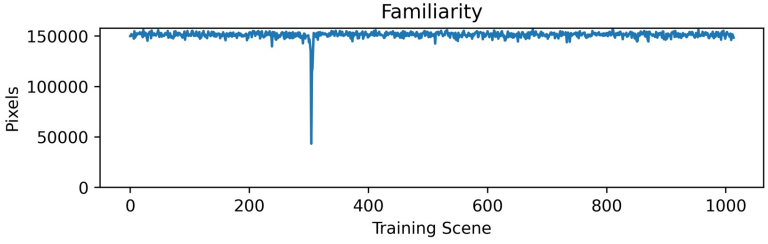



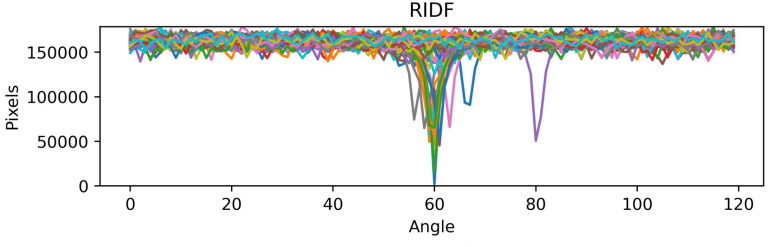

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

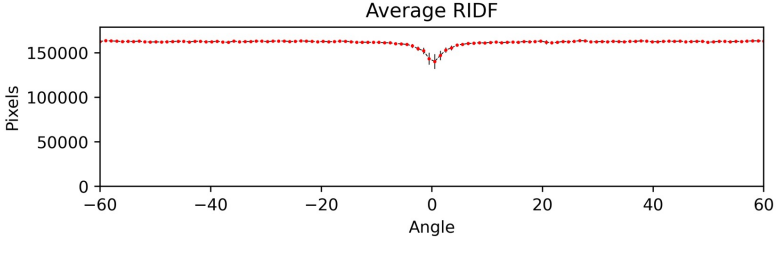
Navigation stats: RMSD error: 3675.46; RMSD/dist: 9.189; TD: 4922; p90: 4; p50: 2; complete: 0

40%



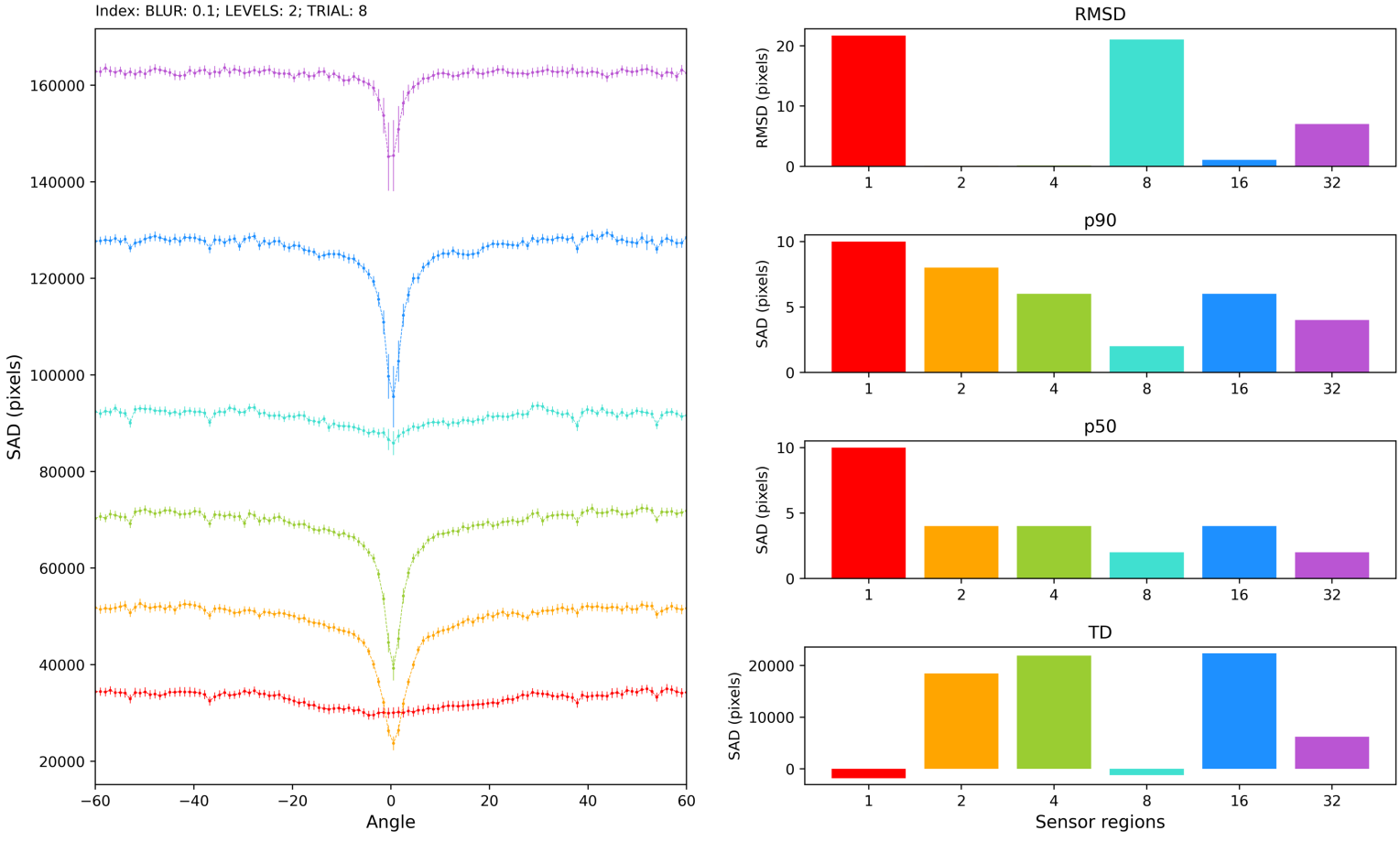


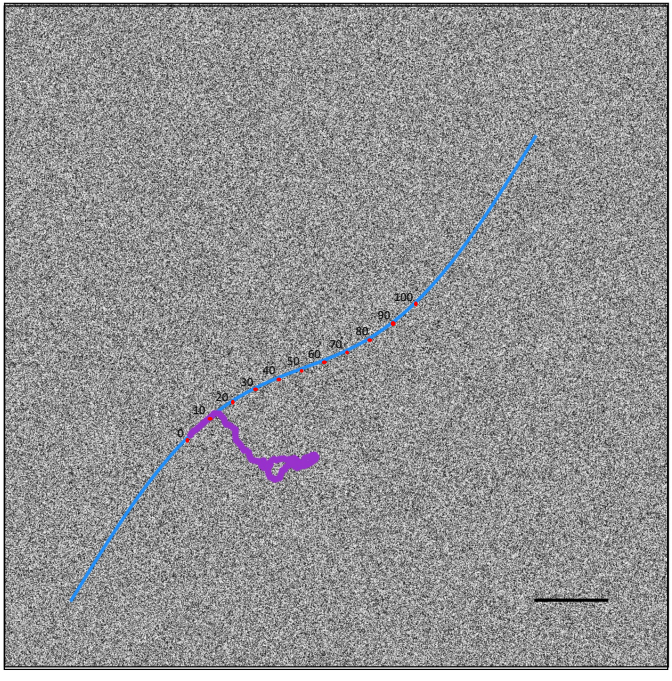



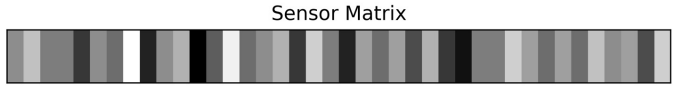

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

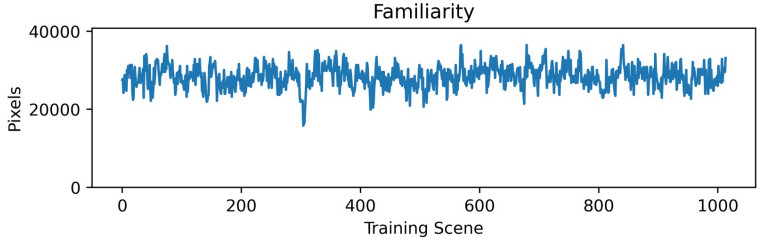
Navigation stats: RMSD error: 1947.25; RMSD/dist: 4.868; TD: 11209; p90: 4; p50: 2; complete: 0

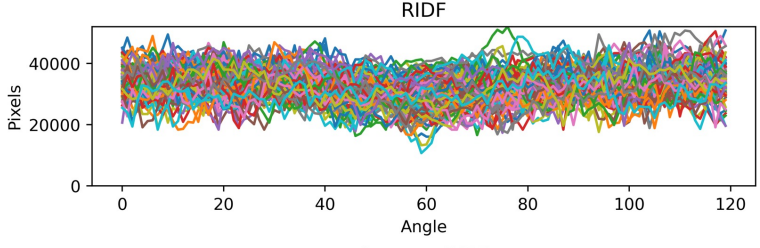

Index: BLUR: 0.1; LEVELS: 2; TRIAL: 8
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
TD
20000
10000
Sensor regions

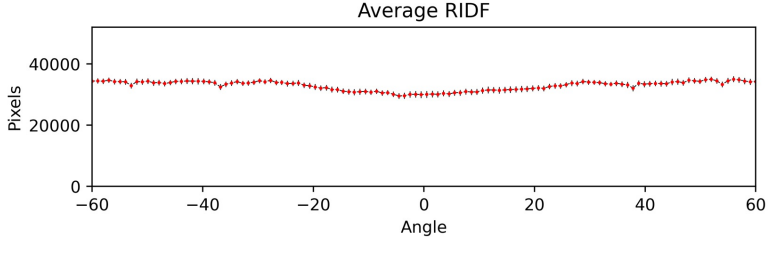
10%



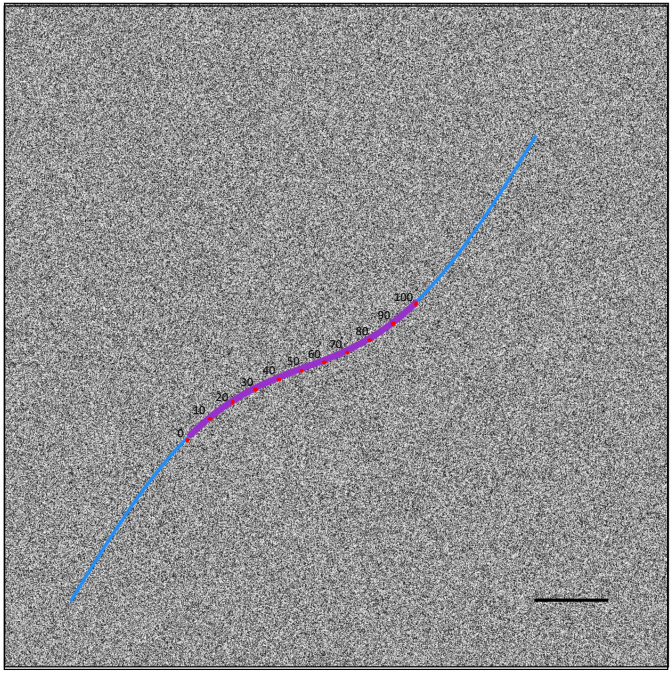



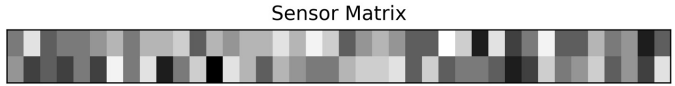



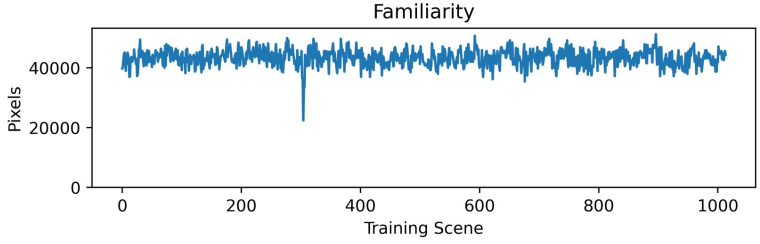

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

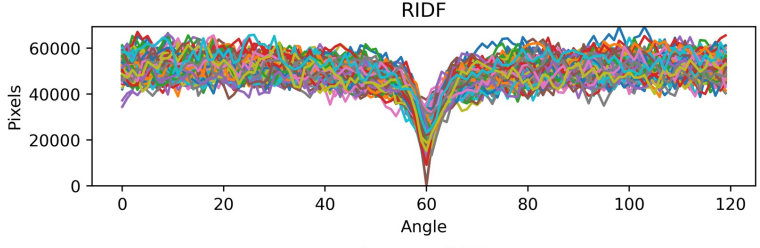
Navigation stats: RMSD error: 8685.96; RMSD/dist: 21.715; TD: -1798; p90: 10; p50: 10; complete: 0

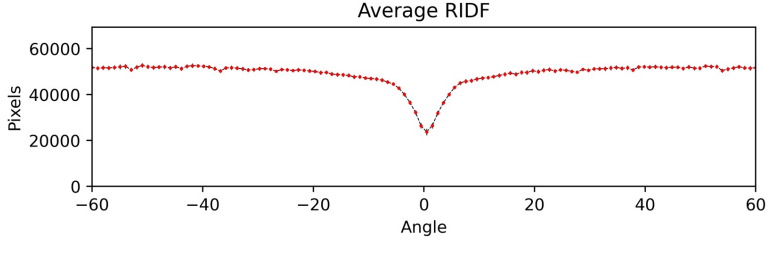
100%

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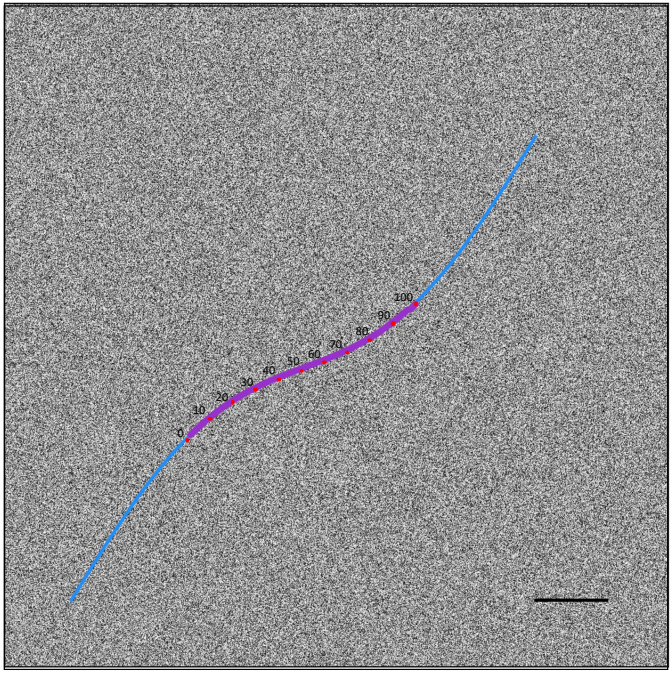
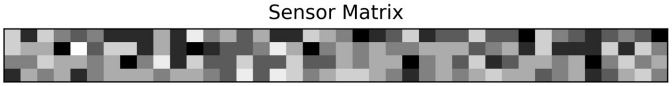
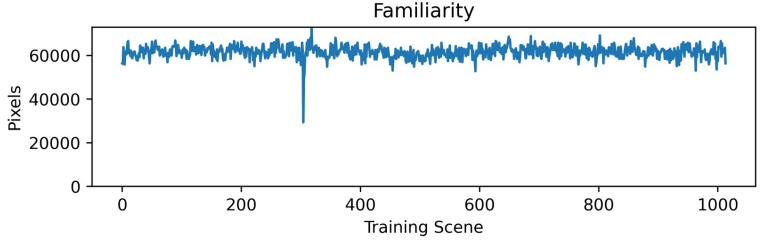
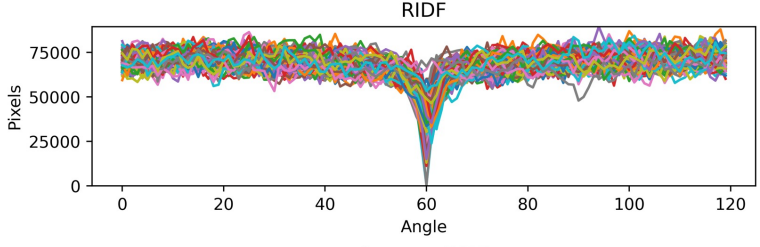
Navigation stats: RMSD error: 30.73; RMSD/dist: 0.077; TD: 18469; p90: 8; p50: 4; complete: 0

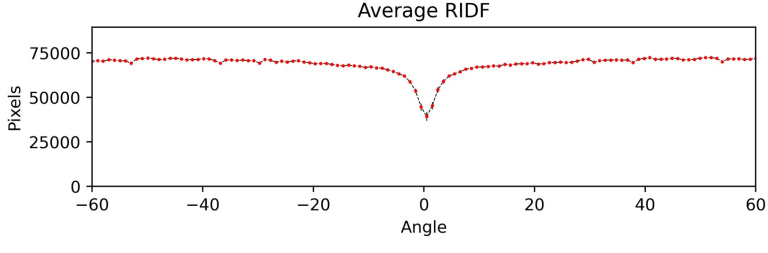
100%



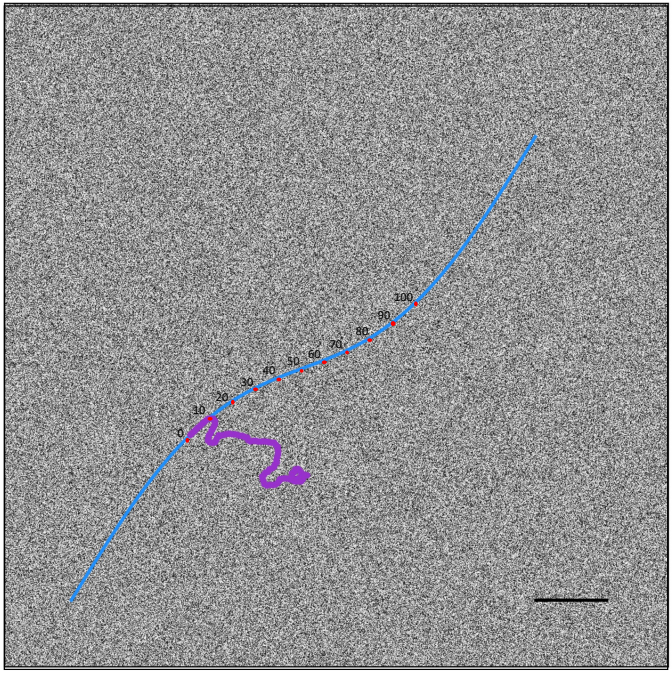



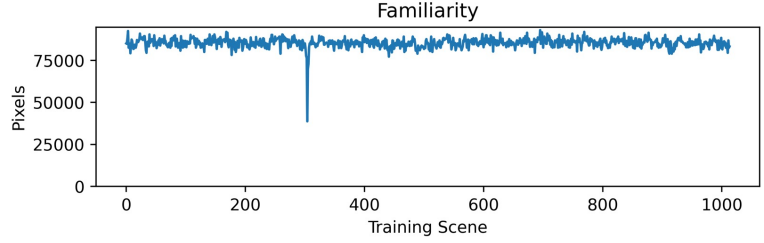



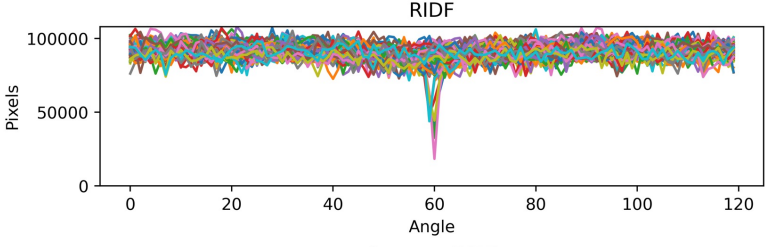

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

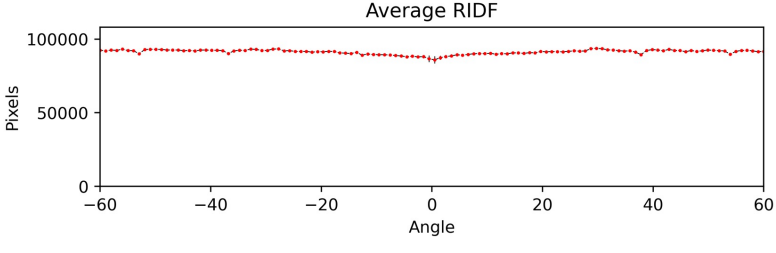
Navigation stats: RMSD error: 54.98; RMSD/dist: 0.137; TD: 21880; p90: 6; p50: 4; complete: 0

10%





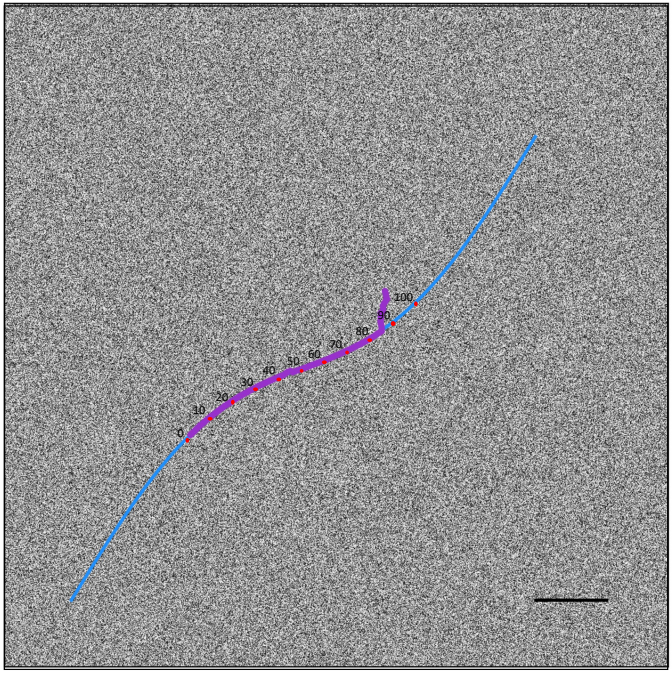



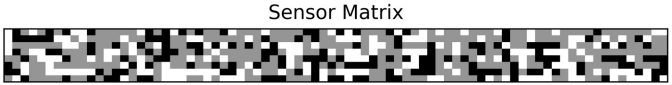



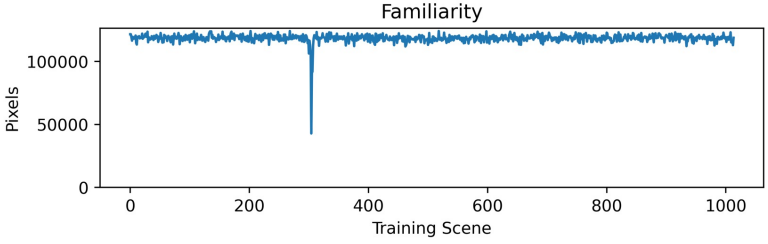

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

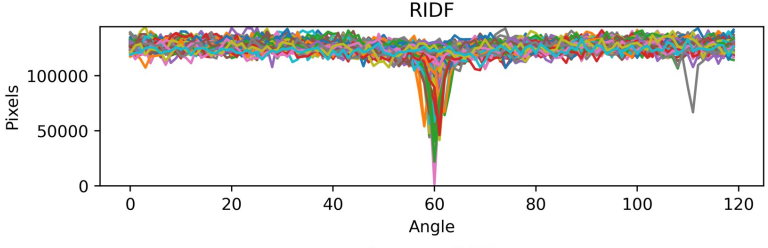
Navigation stats: RMSD error: 8412.89; RMSD/dist: 21.032; TD: -1179; p90: 2; p50: 2; complete: 0

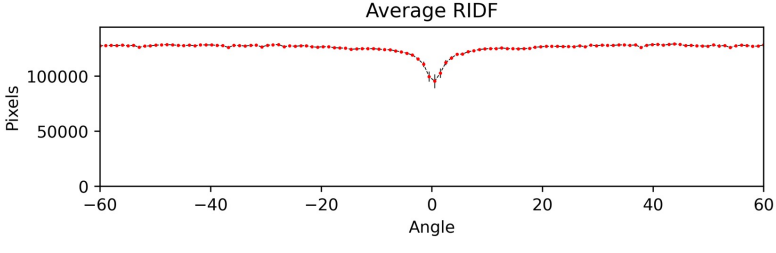
80%



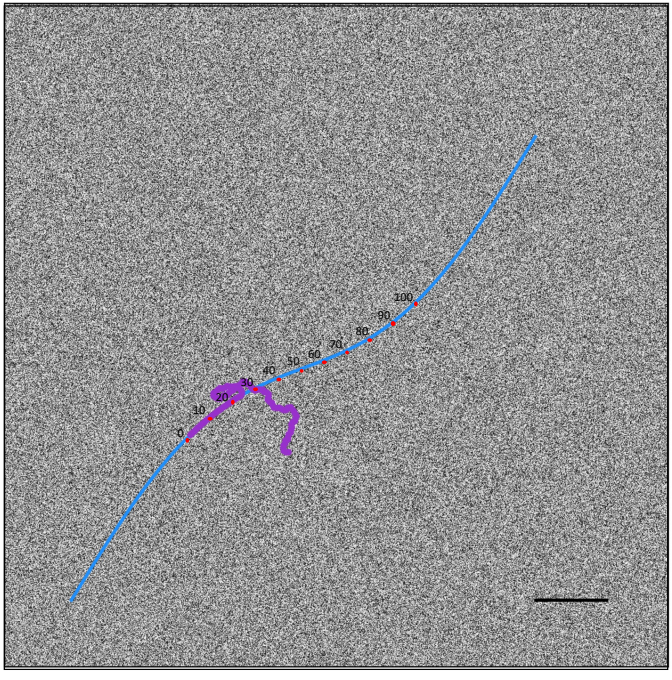



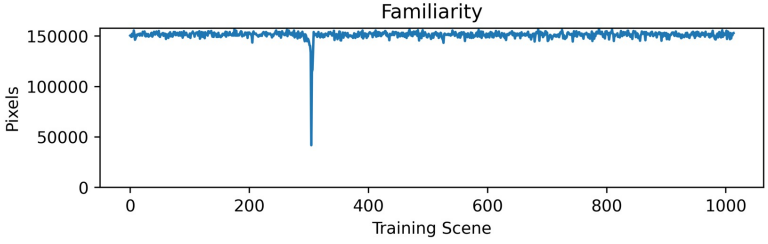



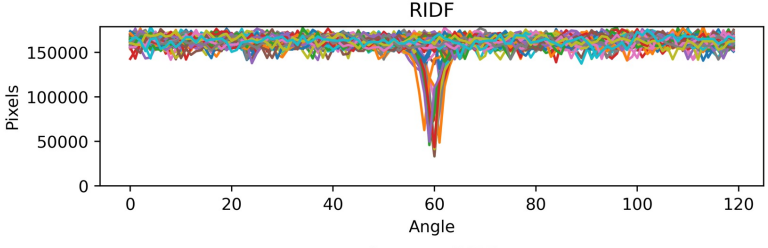

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

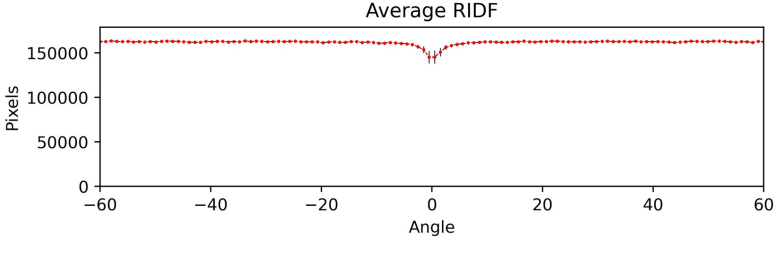
Navigation stats: RMSD error: 423.84; RMSD/dist: 1.060; TD: 22336; p90: 6; p50: 4; complete: 0

20%



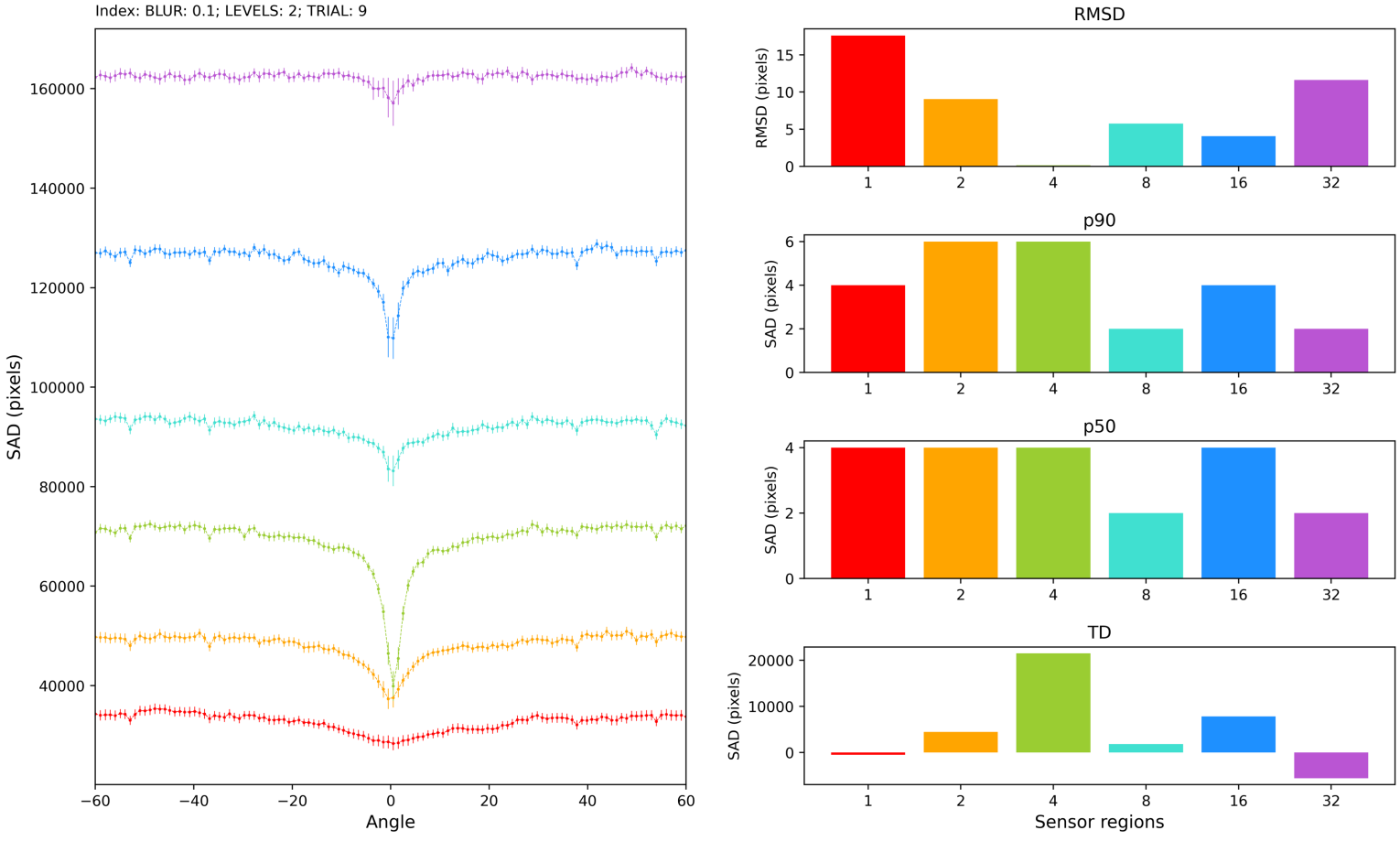


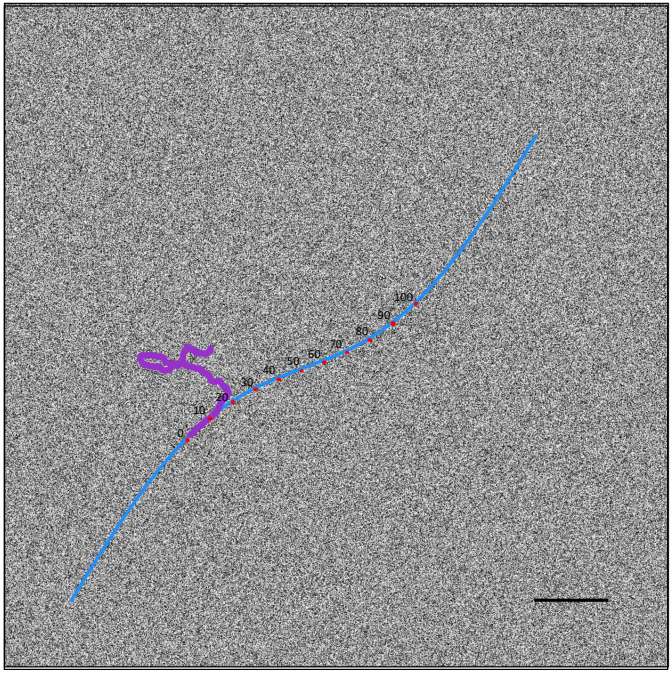



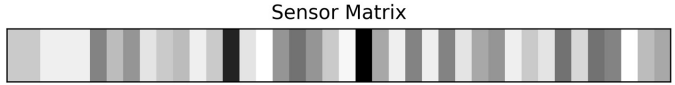

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

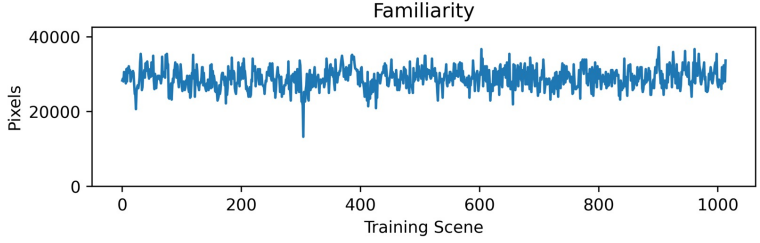
Navigation stats: RMSD error: 2805.11; RMSD/dist: 7.013; TD: 6230; p90: 4; p50: 2; complete: 0

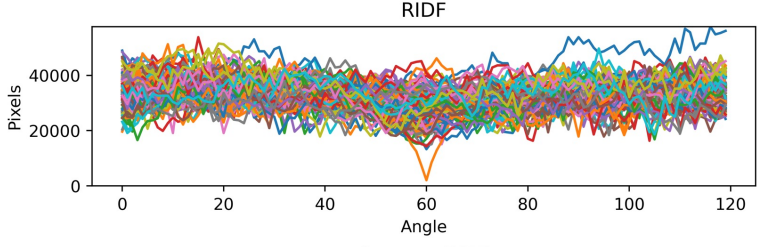

Index: BLUR: 0.1; LEVELS: 2; TRIAL: 9
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
15
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
6
4
2
0
p50
TD
20000
10000
Sensor regions

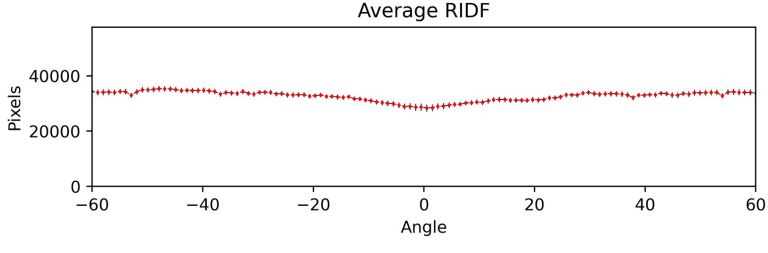
10%



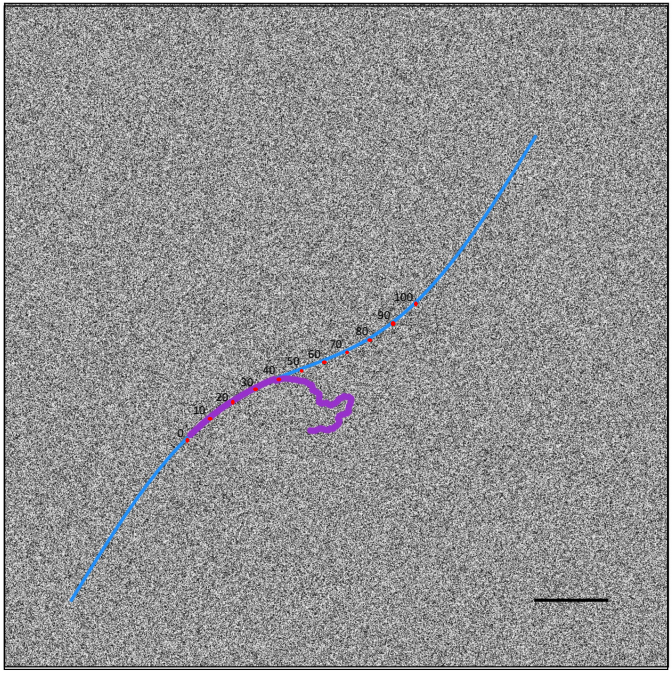



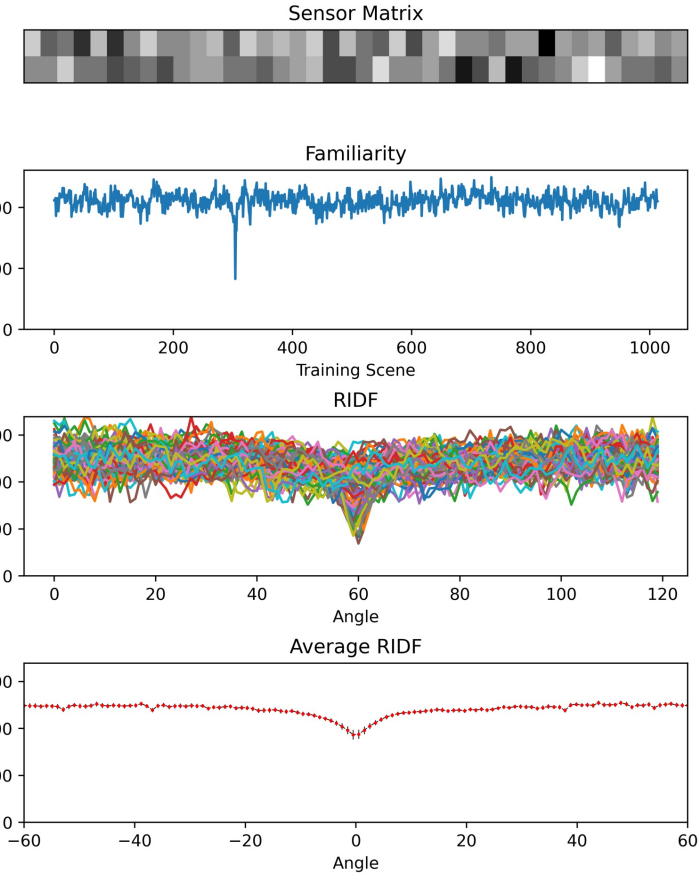




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 7045.28; RMSD/dist: 17.613; TD: -483; p90: 4; p50: 4; complete: 0

40%

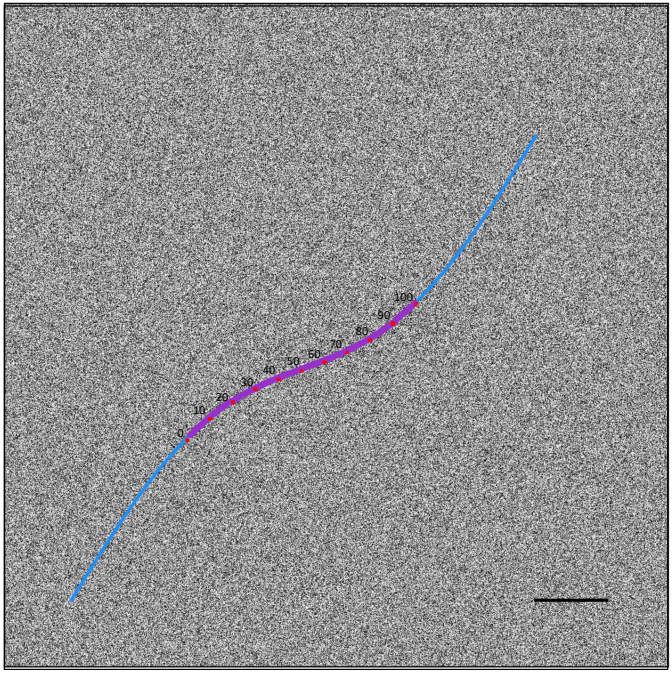


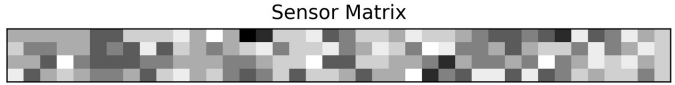



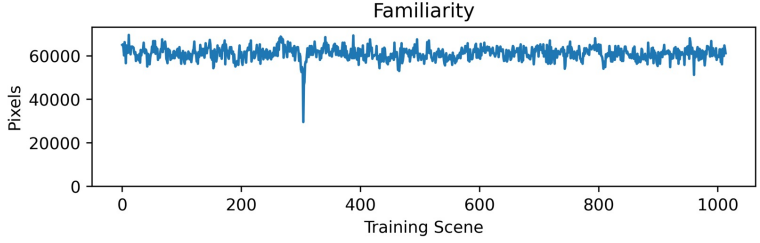

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

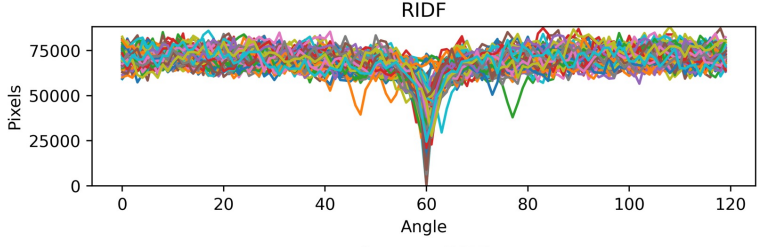
Navigation stats: RMSD error: 3623.57; RMSD/dist: 9.059; TD: 4448; p90: 6; p50: 4; complete: 0

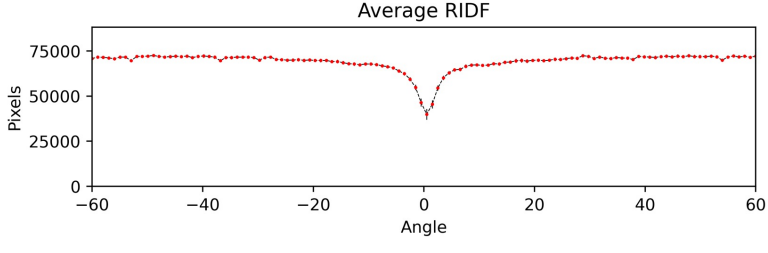
100%



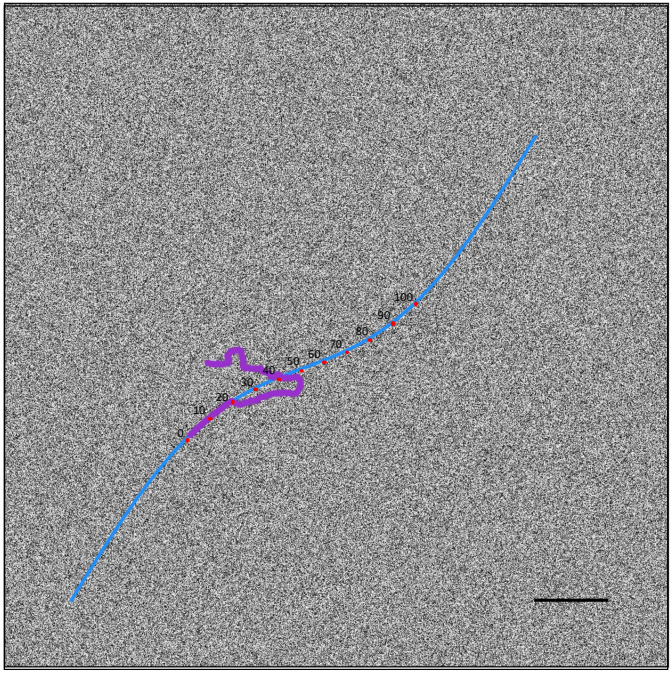



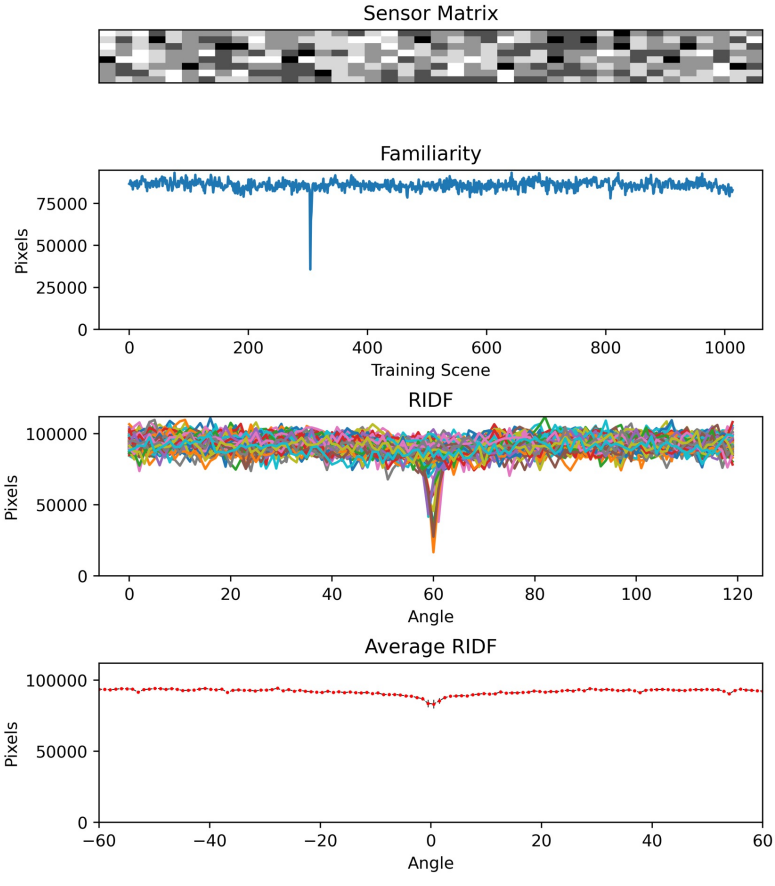




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 52.53; RMSD/dist: 0.131; TD: 21503; p90: 6; p50: 4; complete: 0

20%

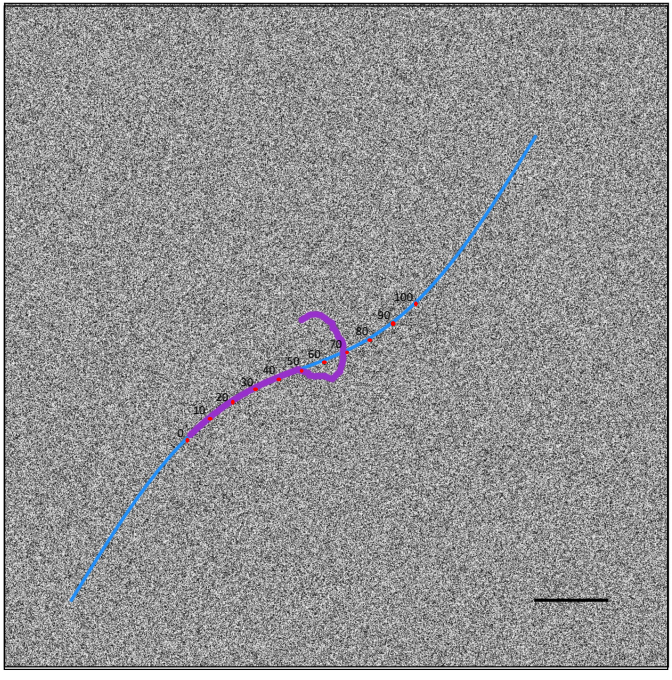


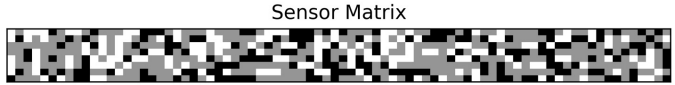



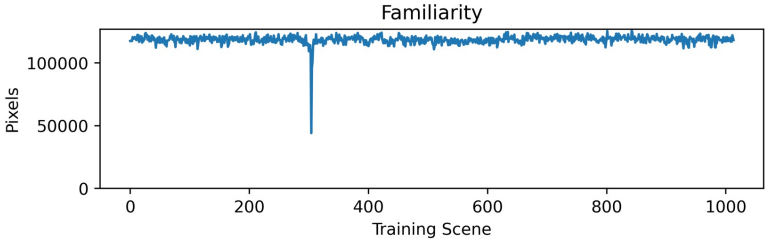

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

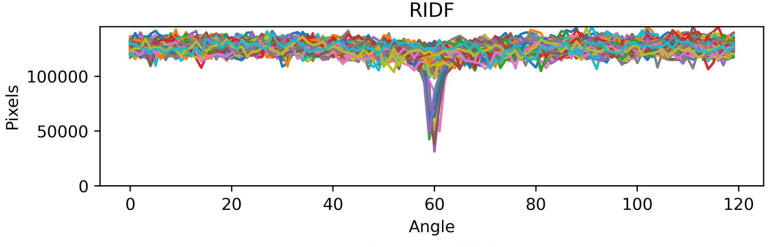
Navigation stats: RMSD error: 2302.21; RMSD/dist: 5.756; TD: 1835; p90: 2; p50: 2; complete: 0

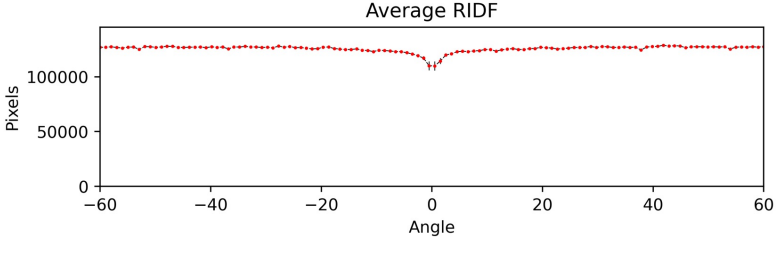
50%



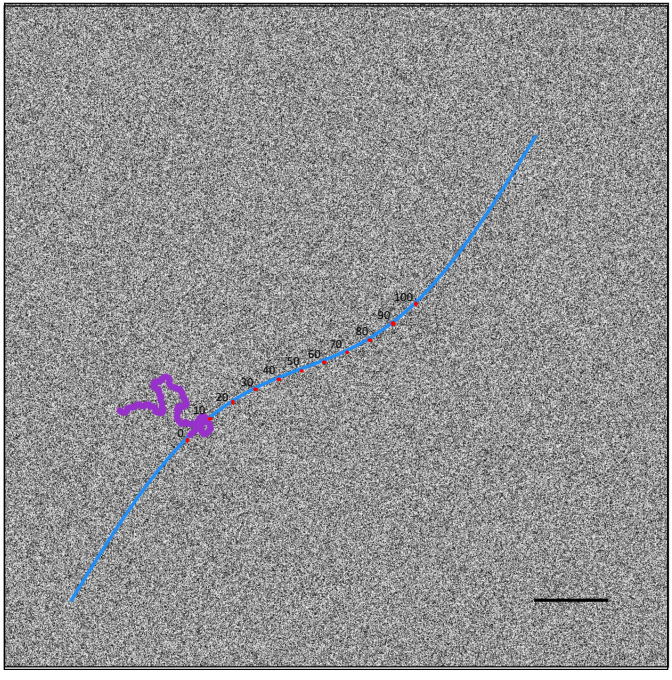



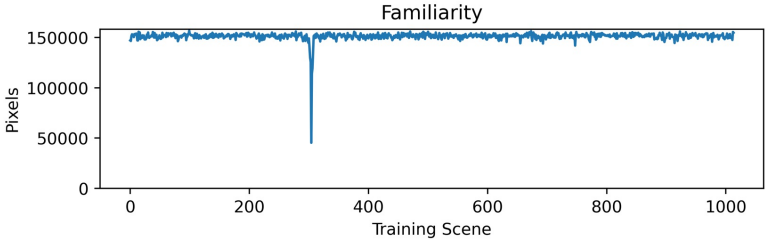



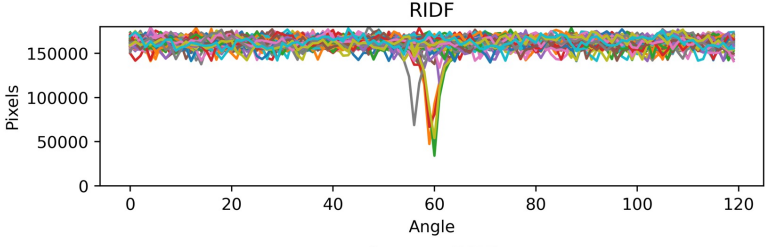

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

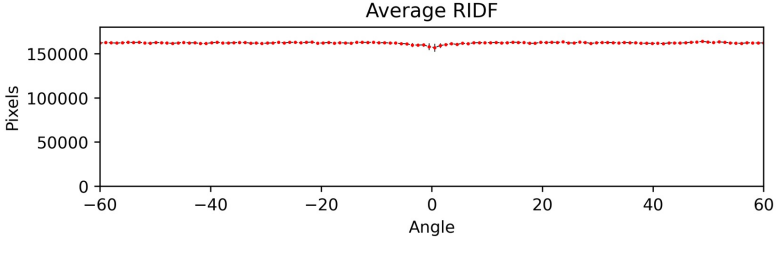
Navigation stats: RMSD error: 1620.32; RMSD/dist: 4.051; TD: 7804; p90: 4; p50: 4; complete: 0

0%



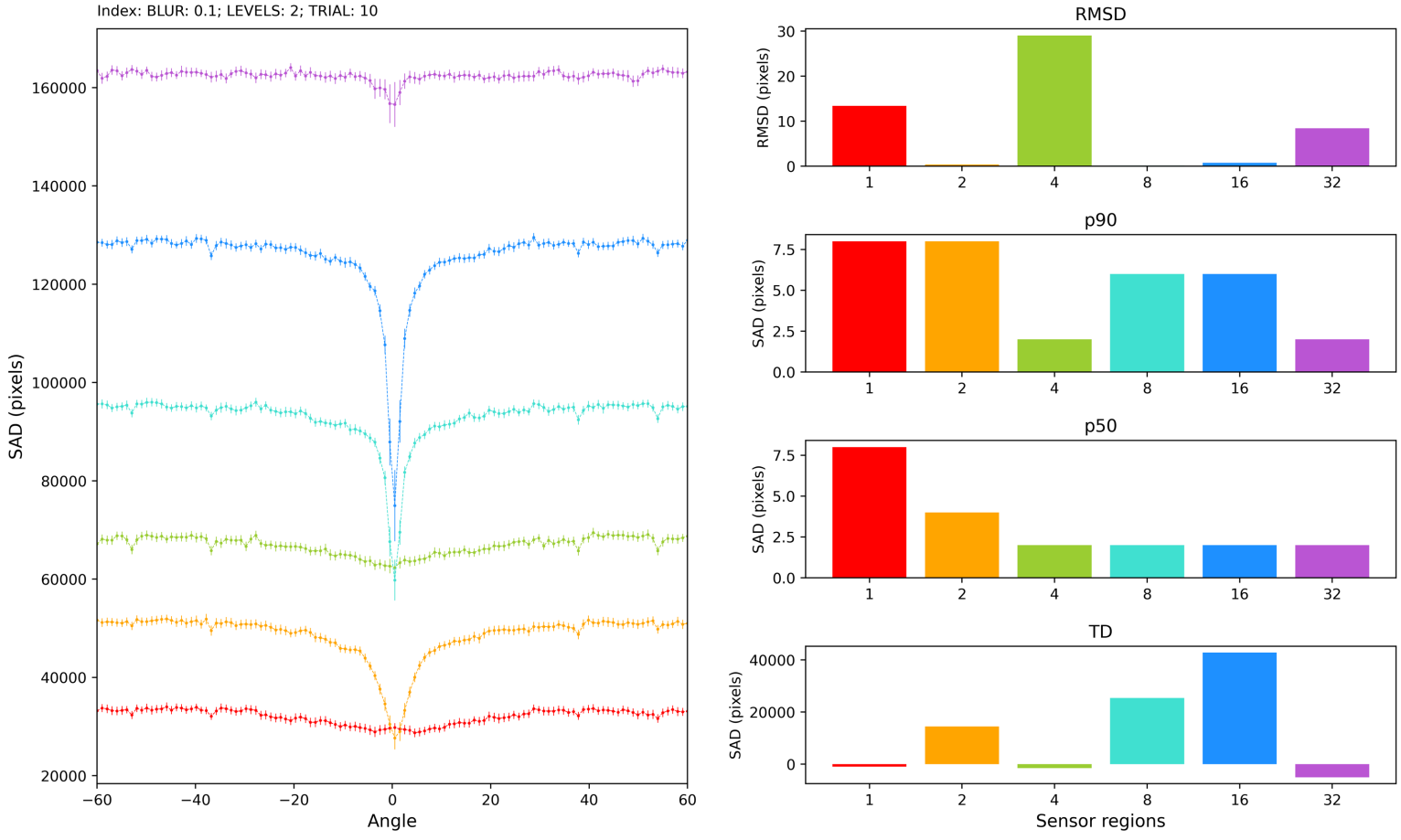


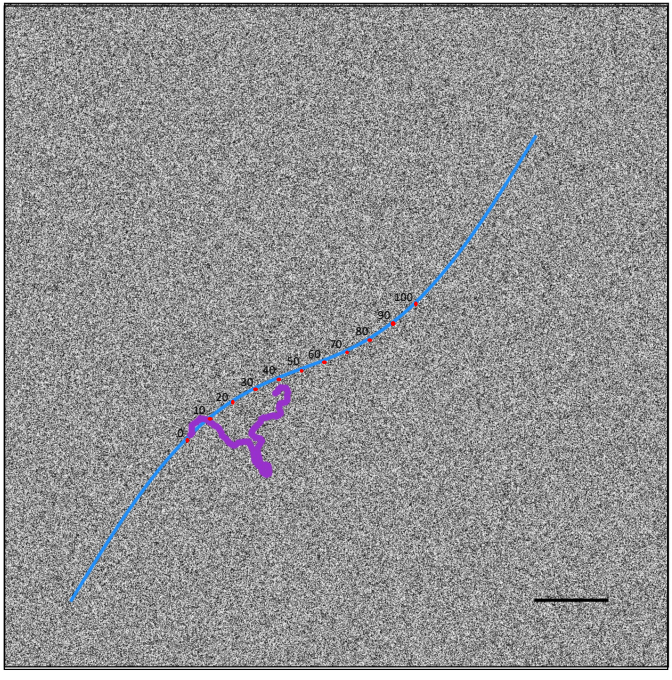



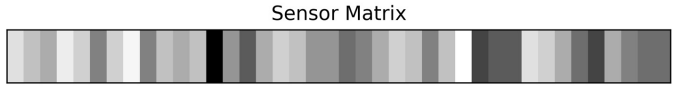

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

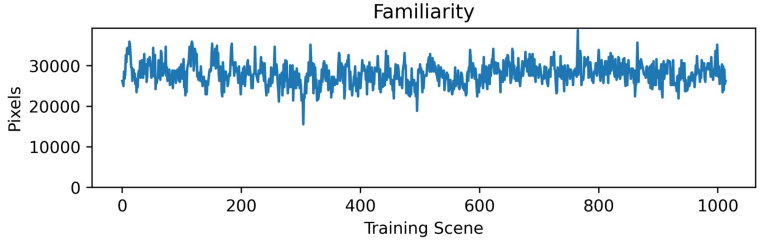
Navigation stats: RMSD error: 4650.98; RMSD/dist: 11.627; TD: -5589; p90: 2; p50: 2; complete: 0

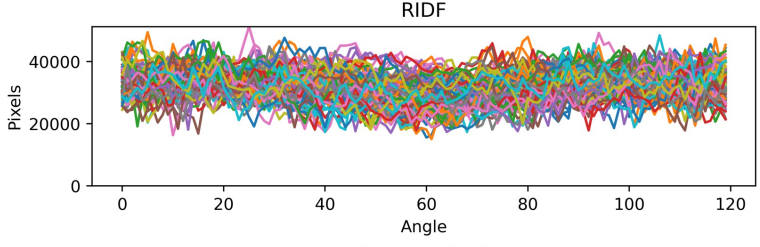

Index: BLUR: 0.1; LEVELS: 2; TRIAL: 10
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
30
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
TD
40000
20000
Sensor regions

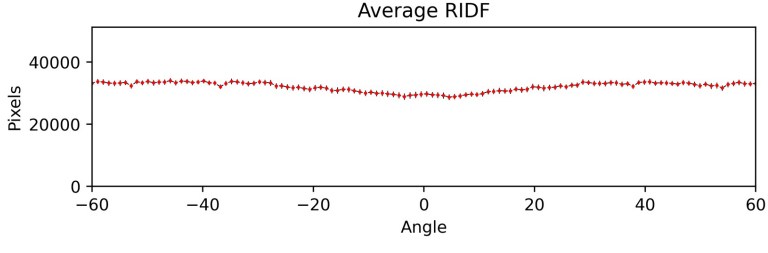
0%



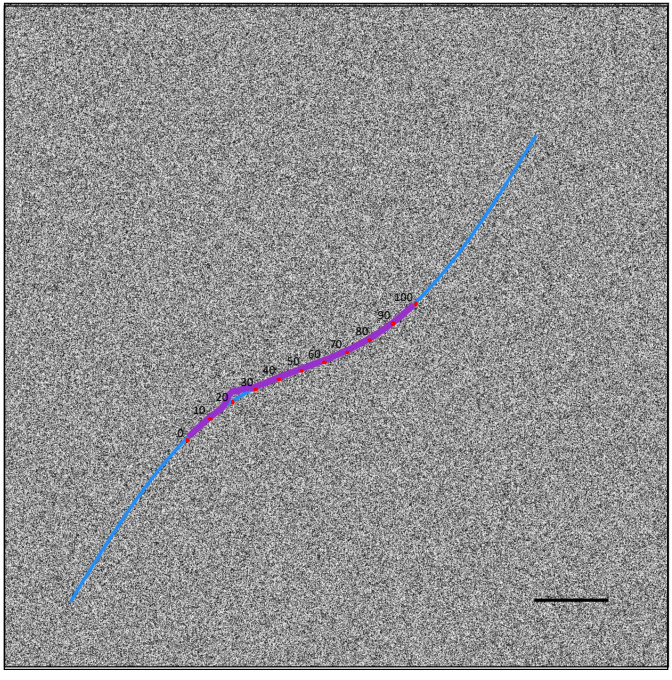



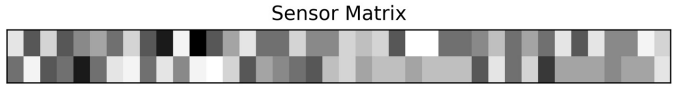



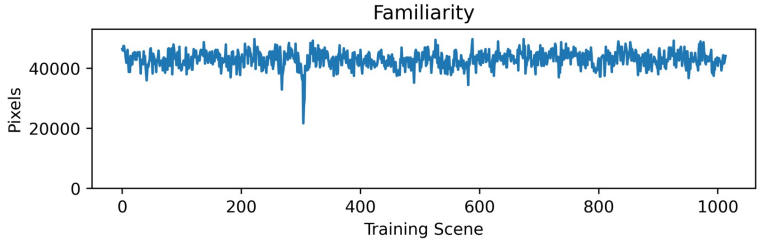

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

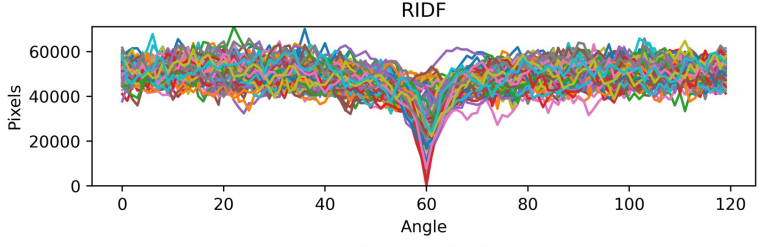
Navigation stats: RMSD error: 5363.80; RMSD/dist: 13.409; TD: -1010; p90: 8; p50: 8; complete: 0

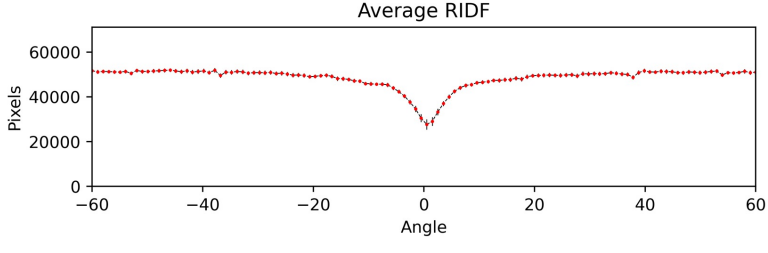
90%



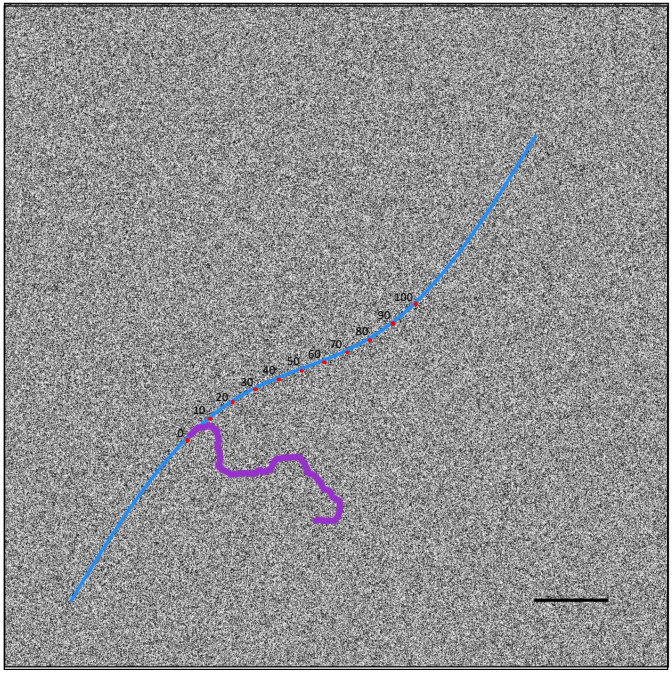



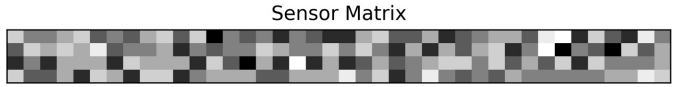



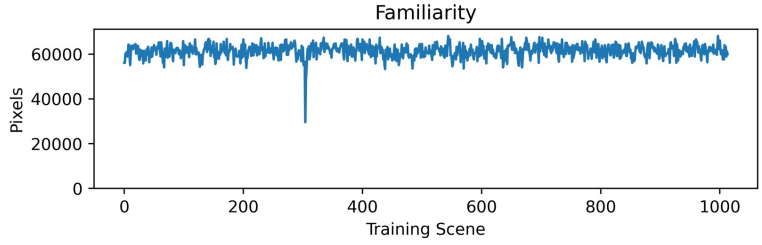

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

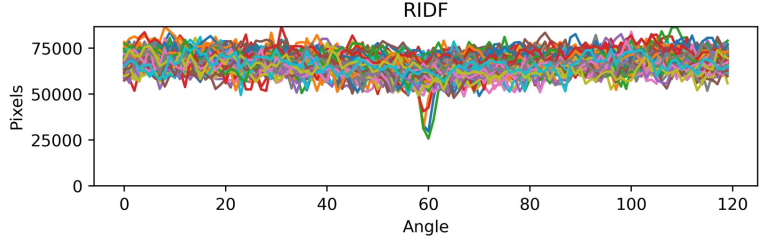
Navigation stats: RMSD error: 150.00; RMSD/dist: 0.375; TD: 14478; p90: 8; p50: 4; complete: 0

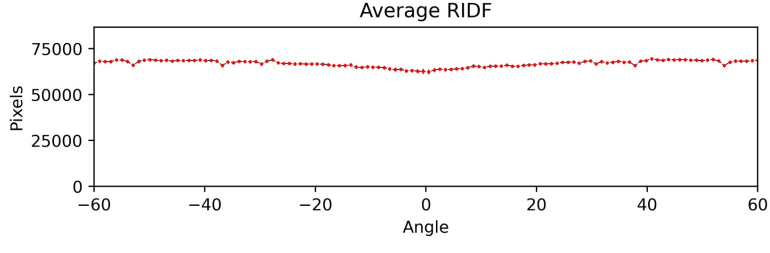
0%



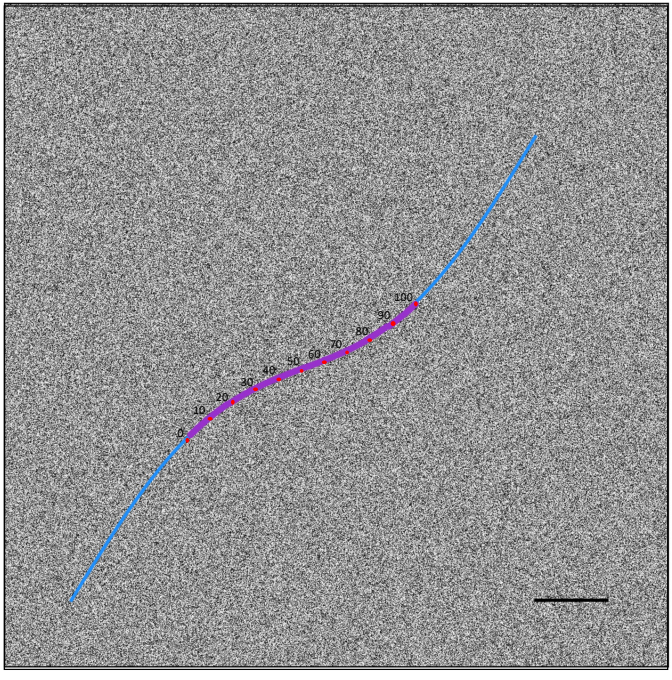



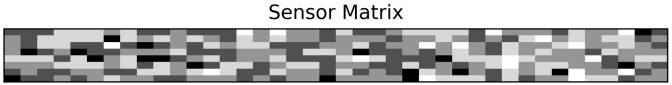



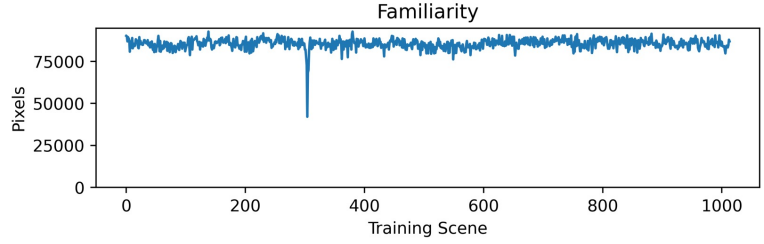

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

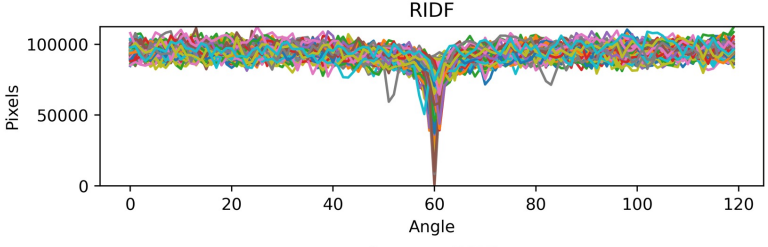
Navigation stats: RMSD error: 11623.42; RMSD/dist: 29.059; TD: -1534; p90: 2; p50: 2; complete: 0

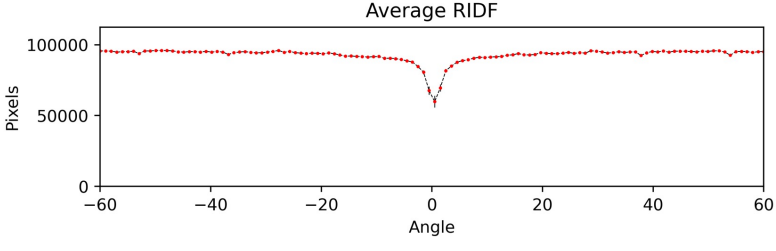
100%



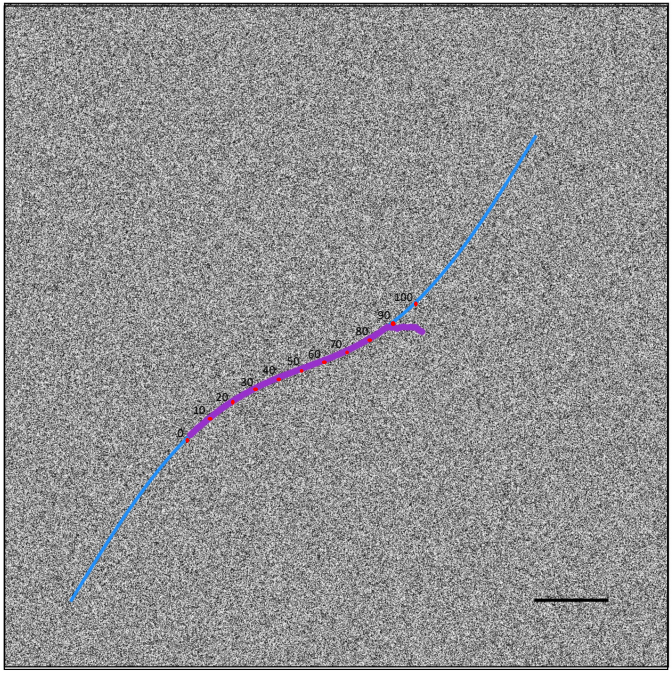



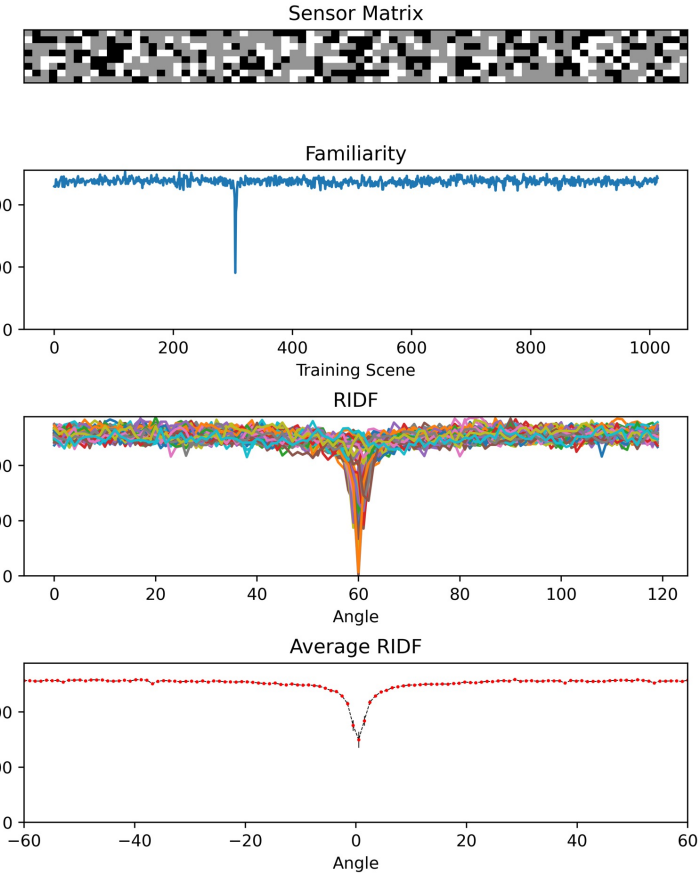




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 44.97; RMSD/dist: 0.112; TD: 25394; p90: 6; p50: 2; complete: 0

80%

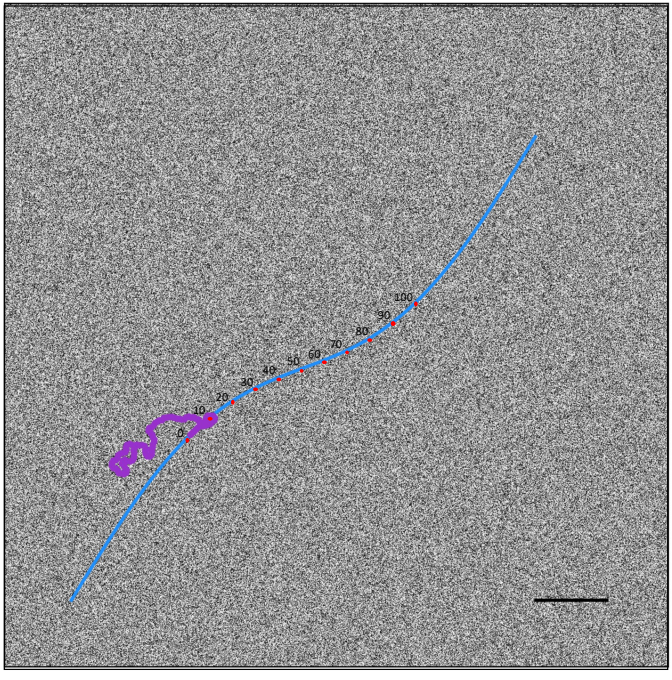


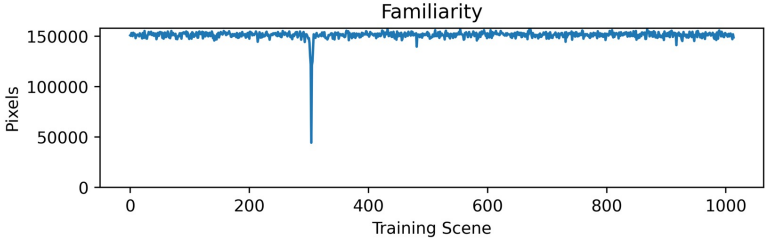



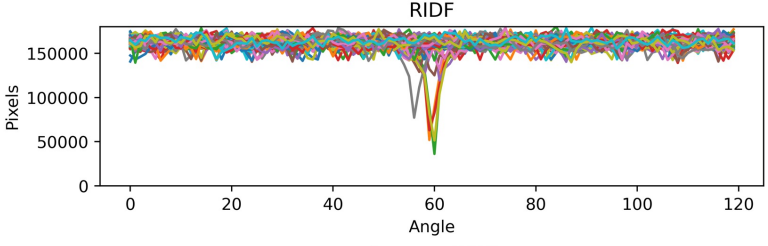

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

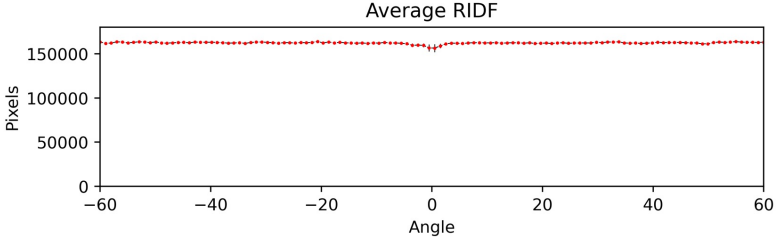
Navigation stats: RMSD error: 291.20; RMSD/dist: 0.728; TD: 42841; p90: 6; p50: 2; complete: 0

10%






Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3367.77; RMSD/dist: 8.419; TD: -5059; p90: 2; p50: 2; complete: 0