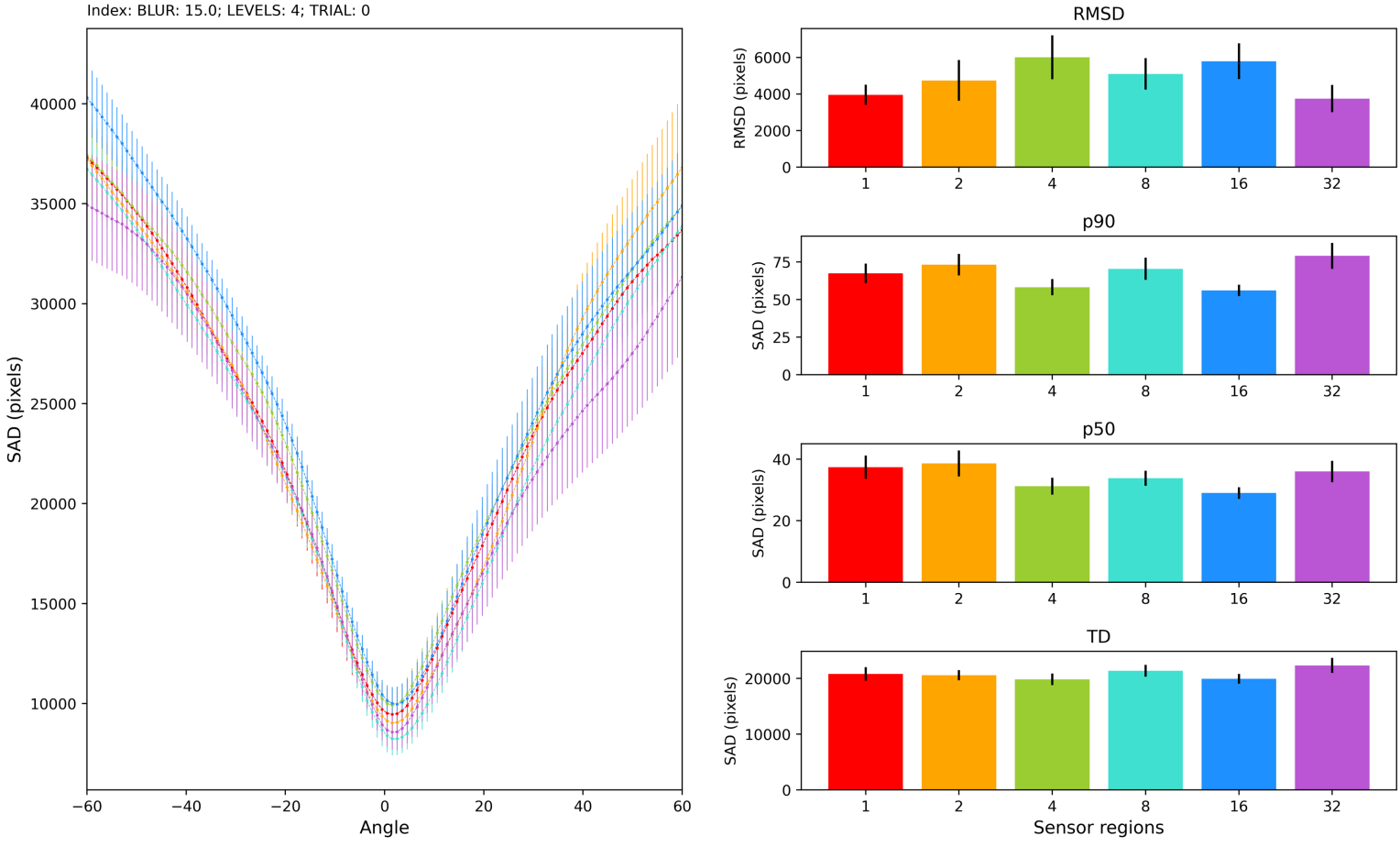
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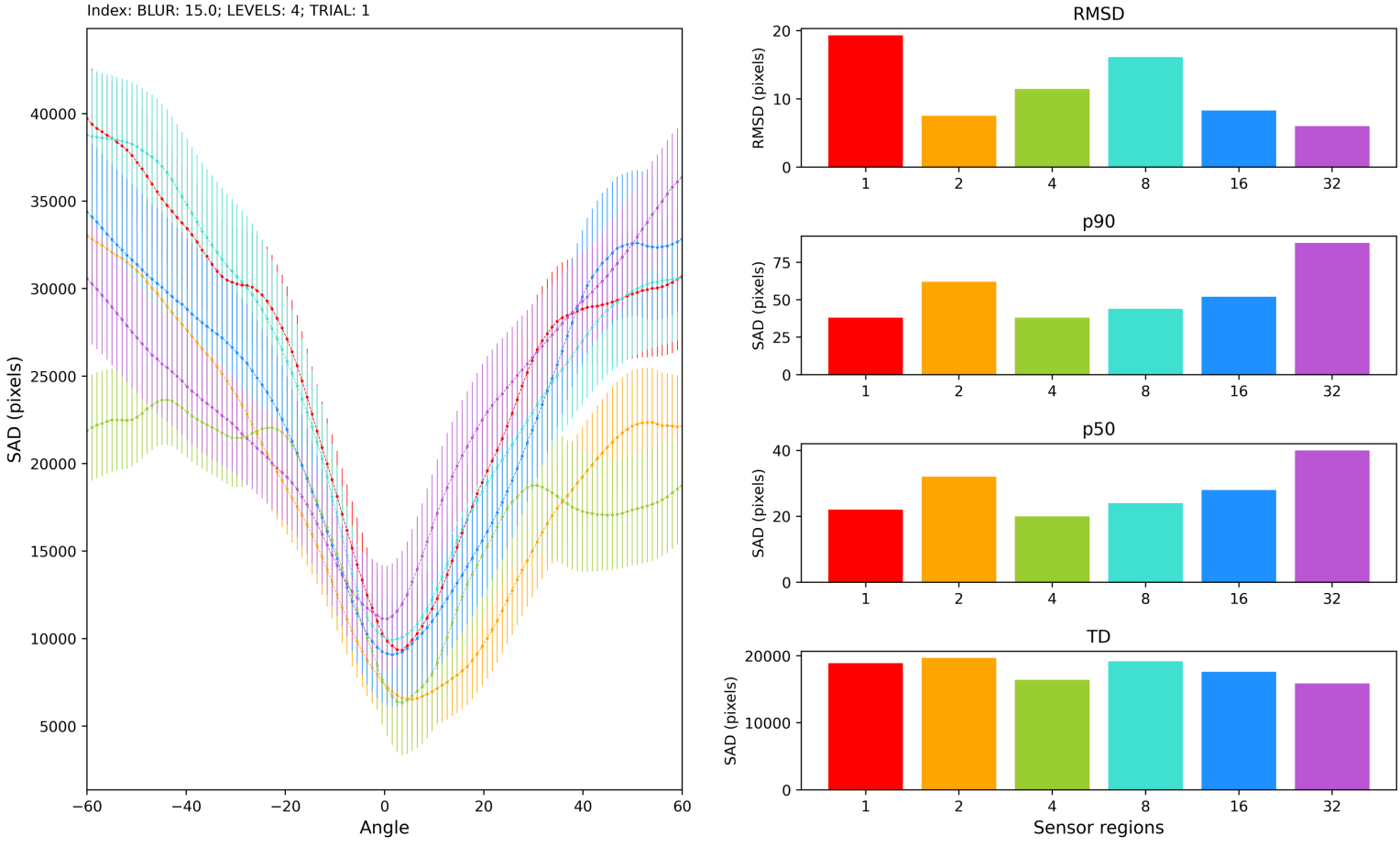
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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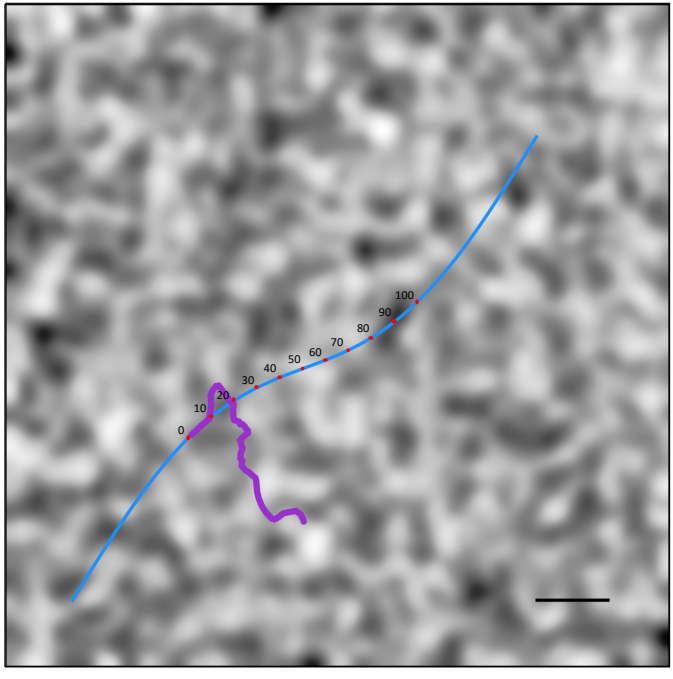
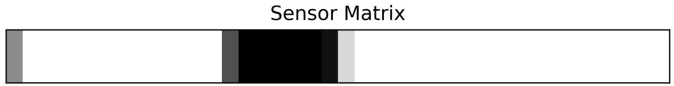
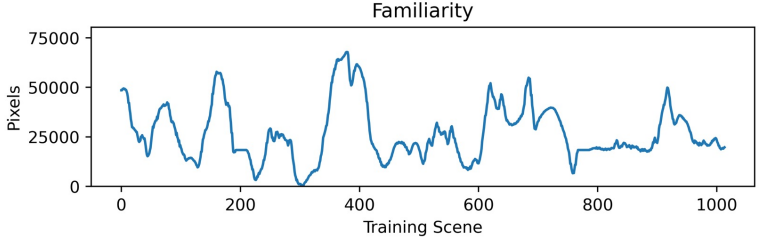
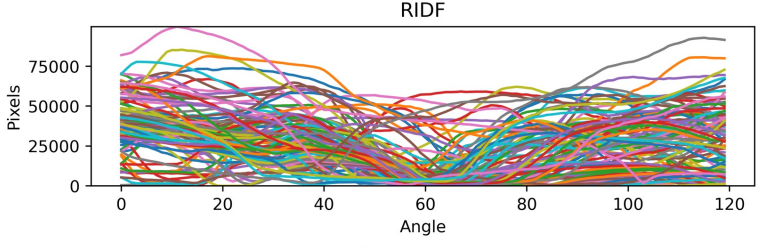
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

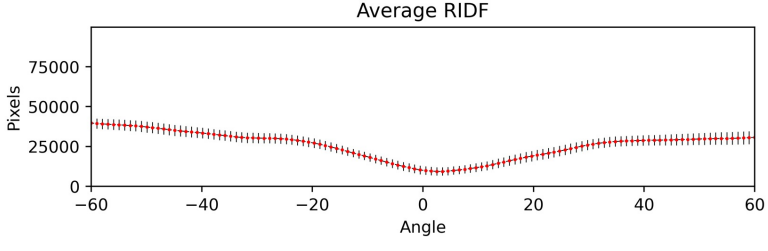
10%







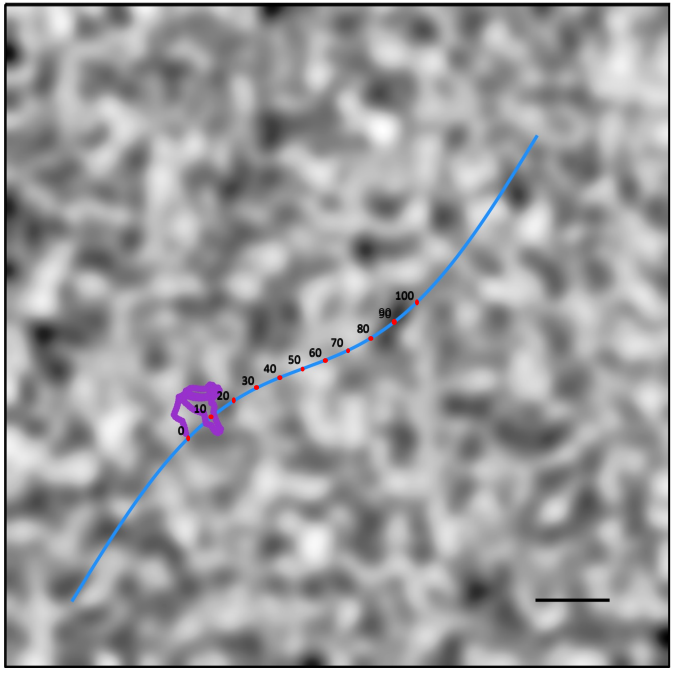


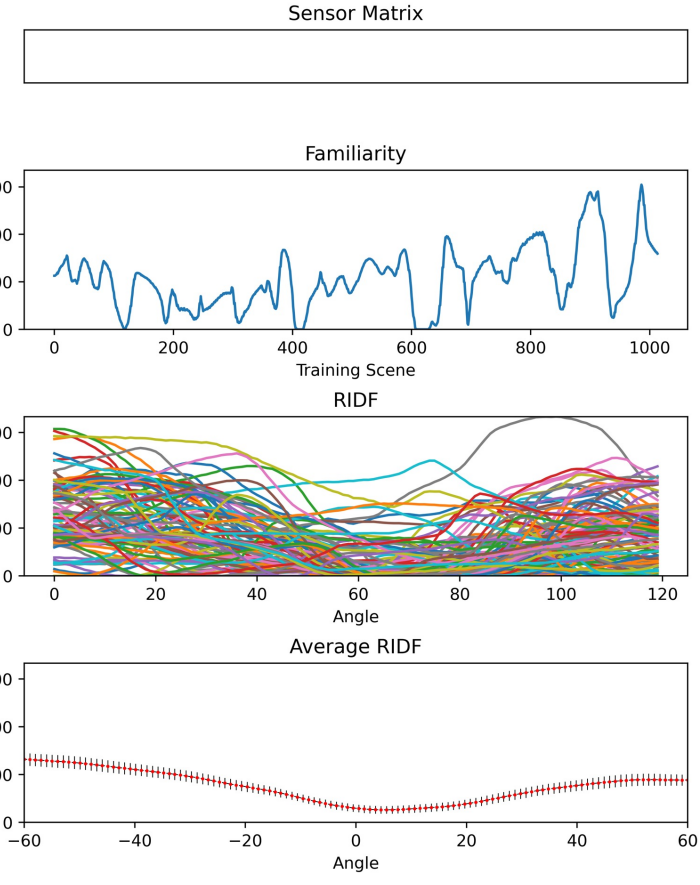


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 7737.36; RMSD/dist: 19.343; TD: 18889; p90: 38; p50: 22; complete: 0

0%

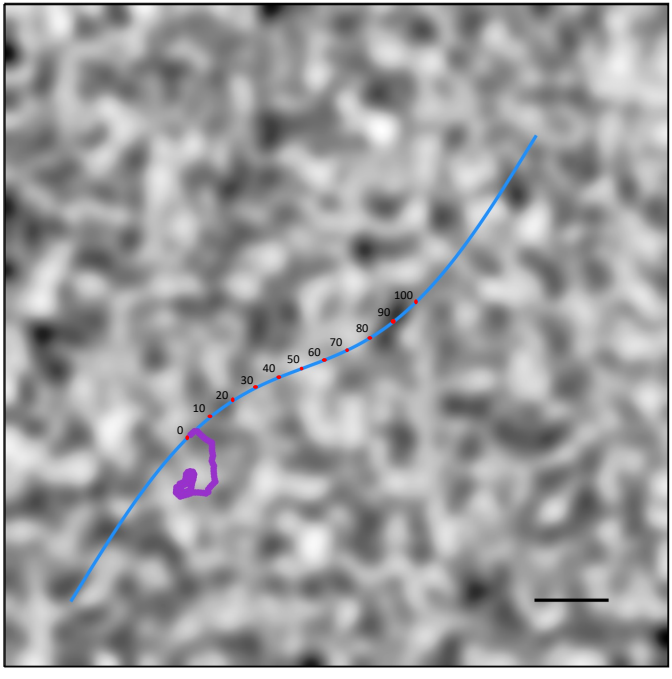


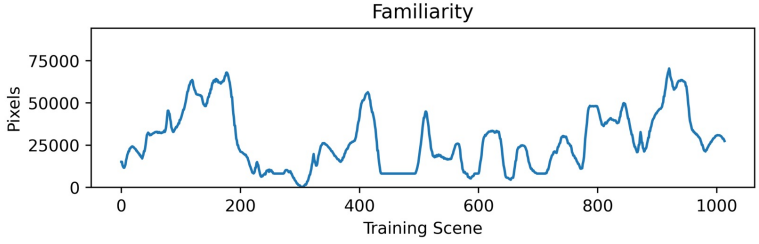


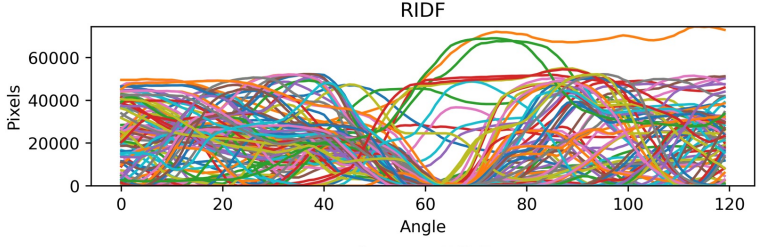
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

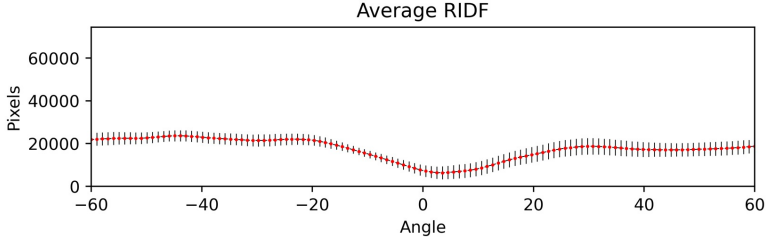
Navigation stats: RMSD error: 3005.31; RMSD/dist: 7.513; TD: 19665; p90: 62; p50: 32; complete: 0

0%





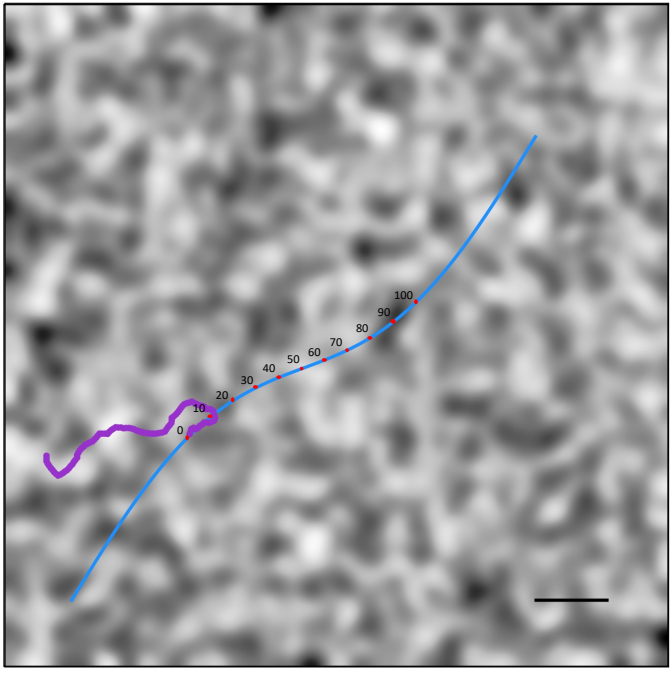


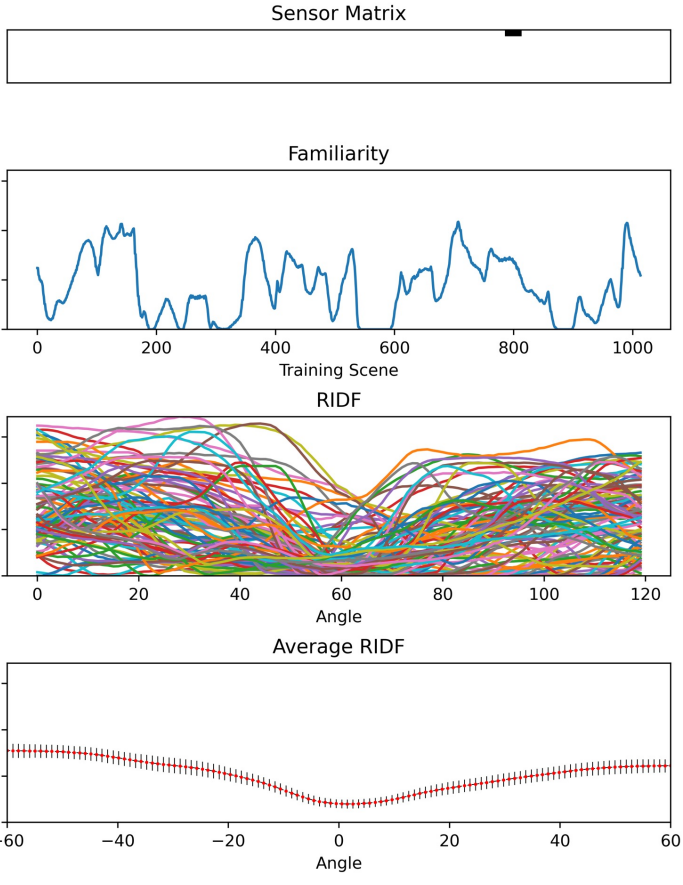


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4580.94; RMSD/dist: 11.452; TD: 16403; p90: 38; p50: 20; complete: 0

0%

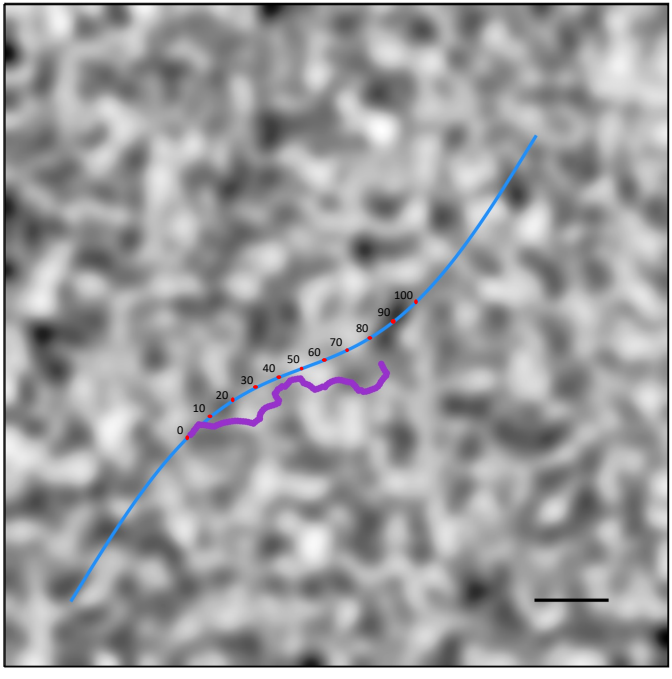


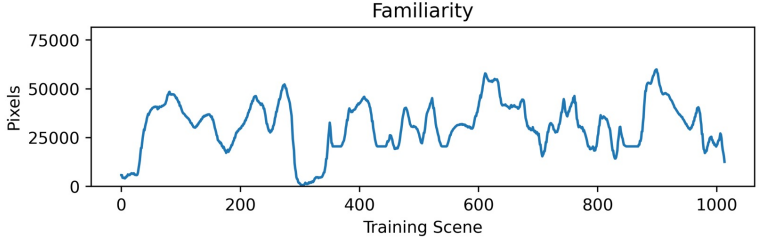


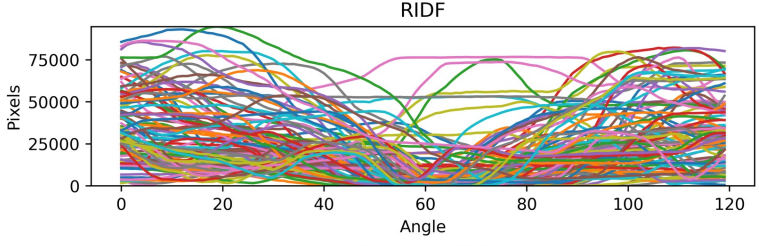
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

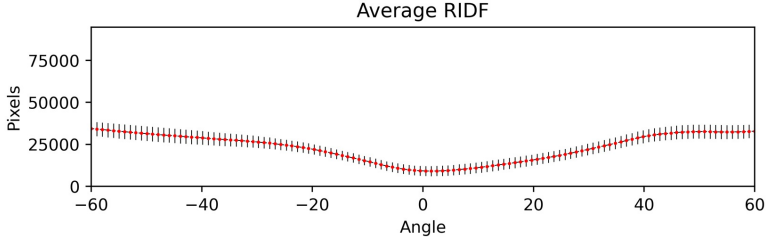
Navigation stats: RMSD error: 6459.50; RMSD/dist: 16.149; TD: 19175; p90: 44; p50: 24; complete: 0

0%





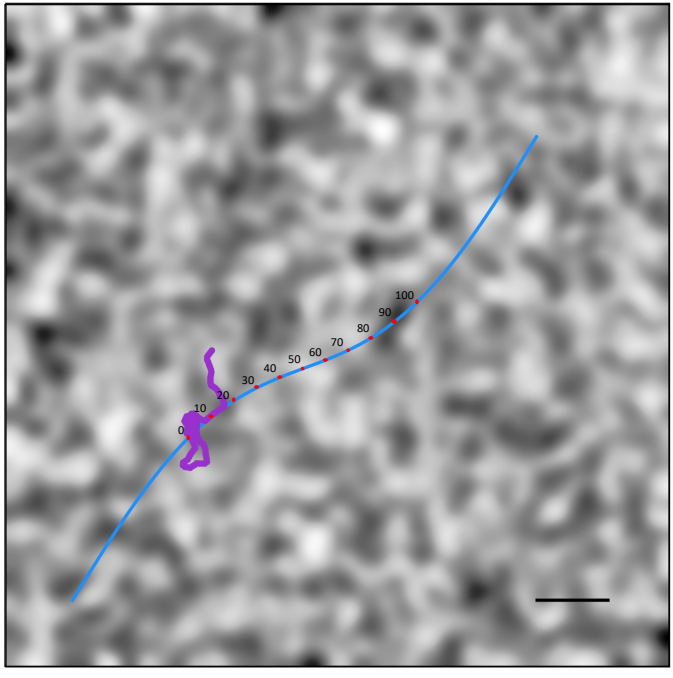


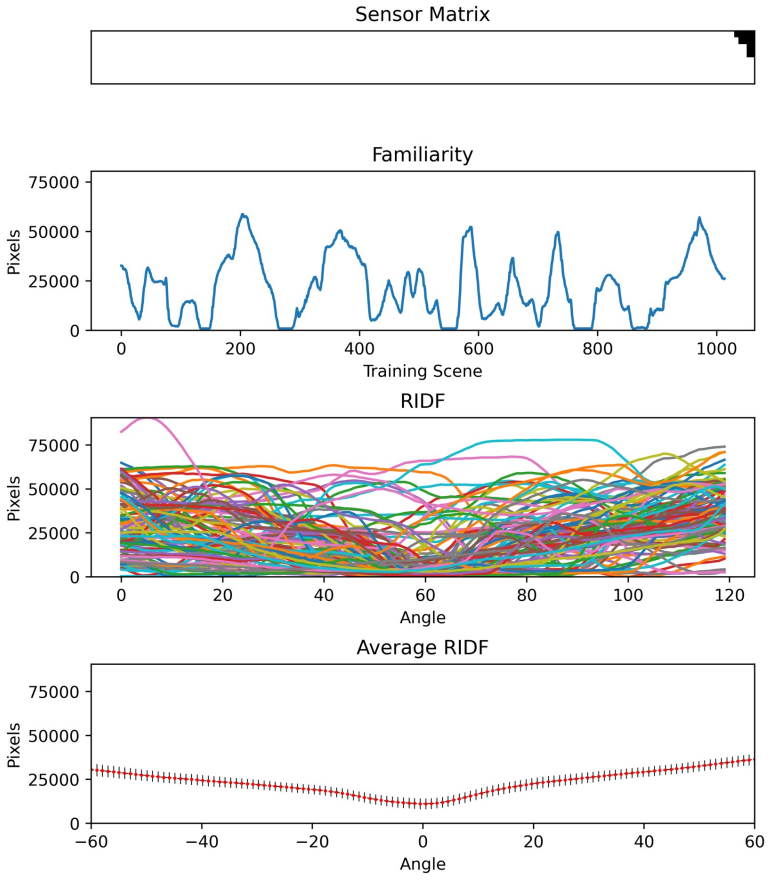


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3322.05; RMSD/dist: 8.305; TD: 17593; p90: 52; p50: 28; complete: 0

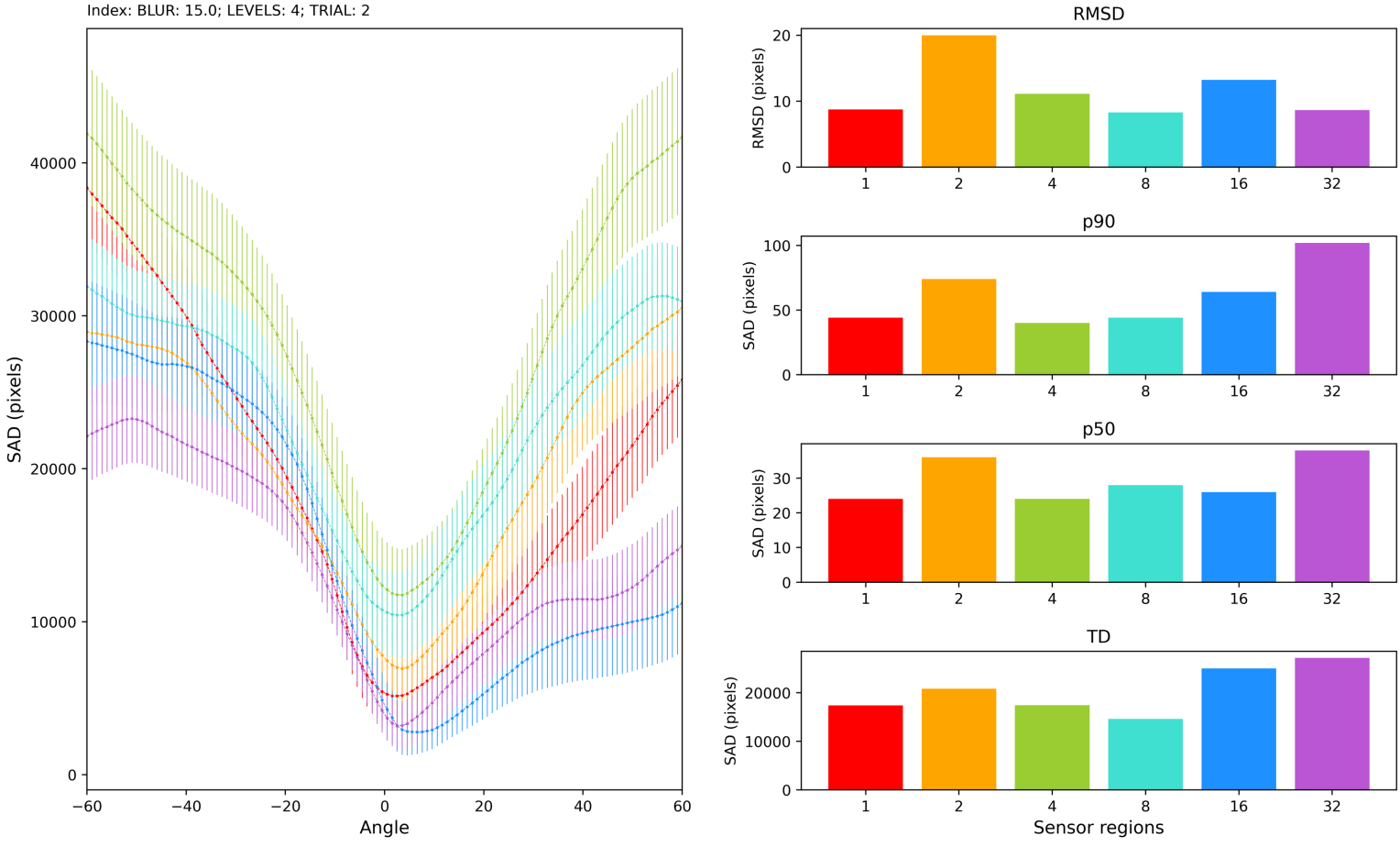
0%



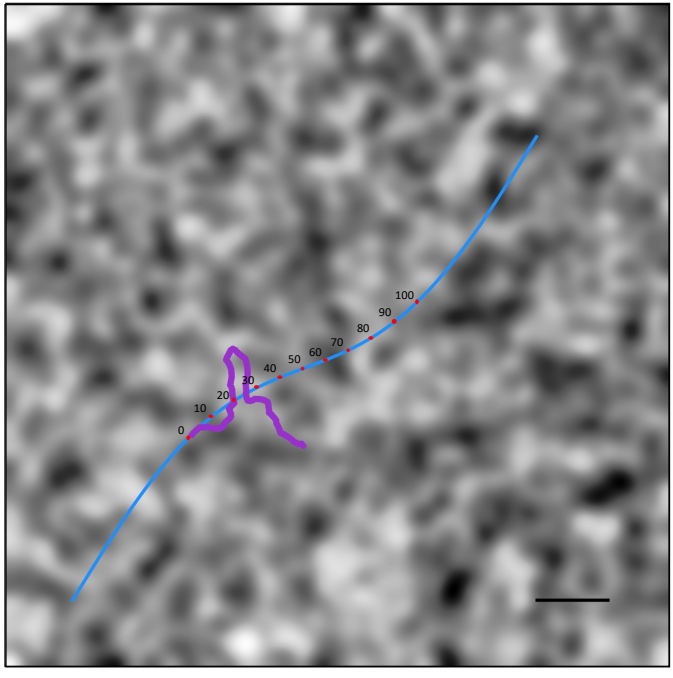


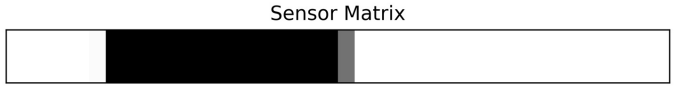
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

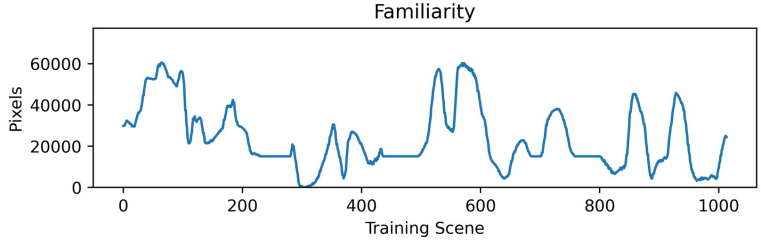
Navigation stats: RMSD error: 2395.42; RMSD/dist: 5.989; TD: 15882; p90: 88; p50: 40; complete: 0

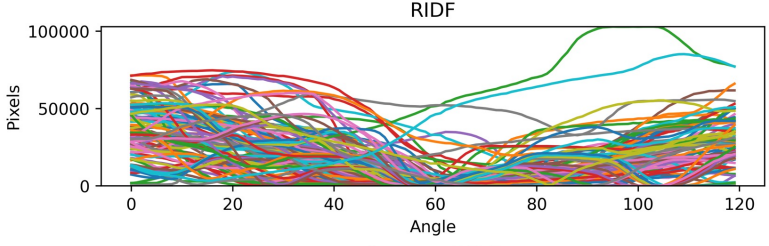

Index: BLUR: 15.0; LEVELS: 4; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

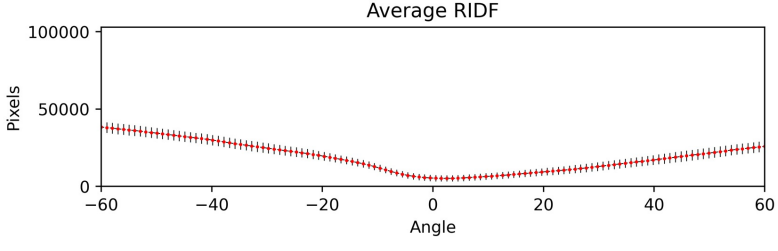
0%







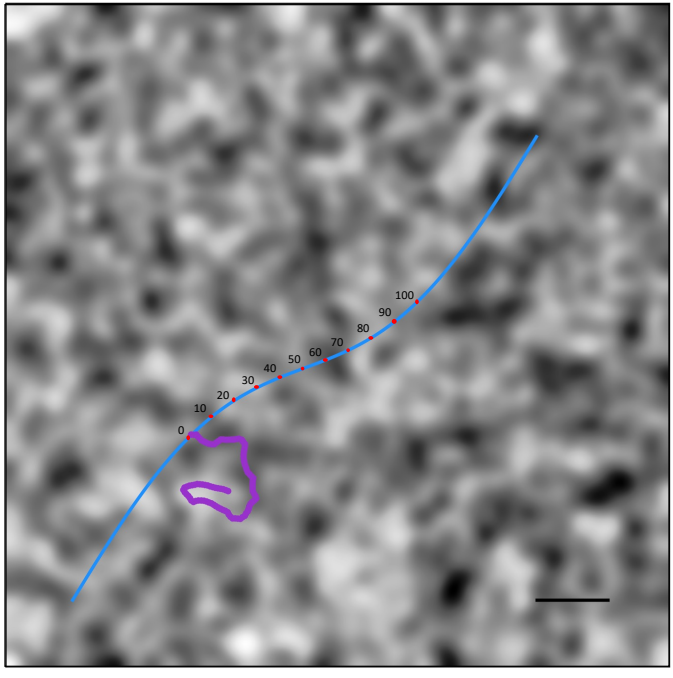


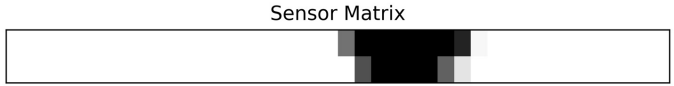


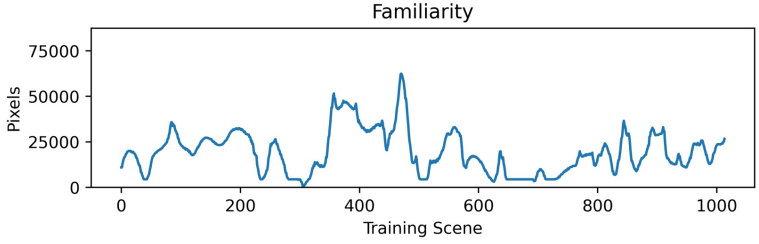
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

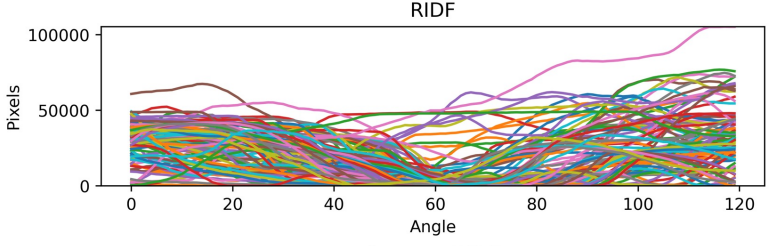
Navigation stats: RMSD error: 3499.62; RMSD/dist: 8.749; TD: 17423; p90: 44; p50: 24; complete: 0

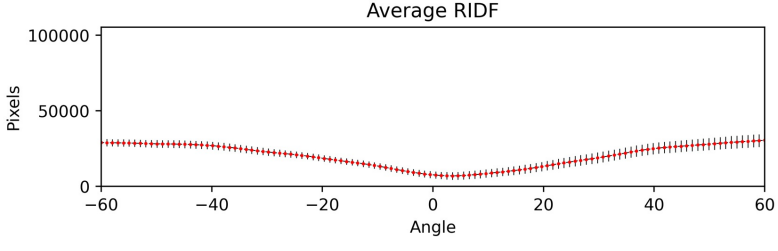
0%







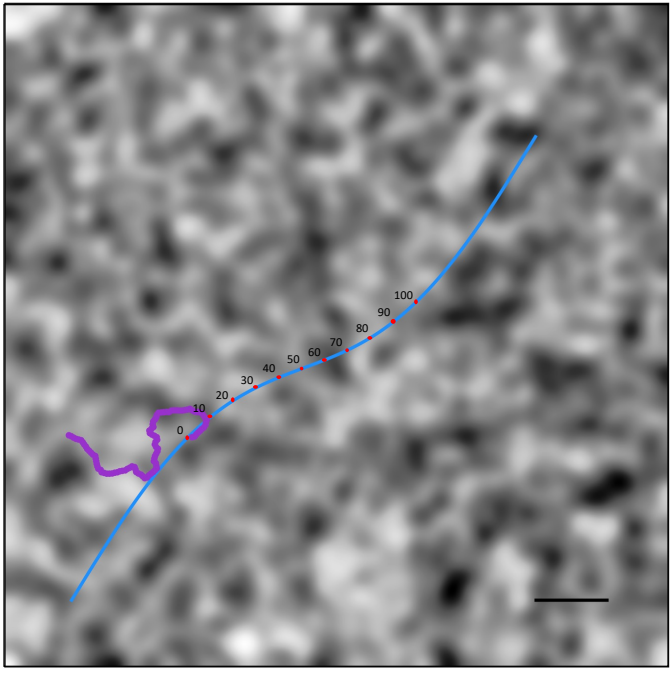


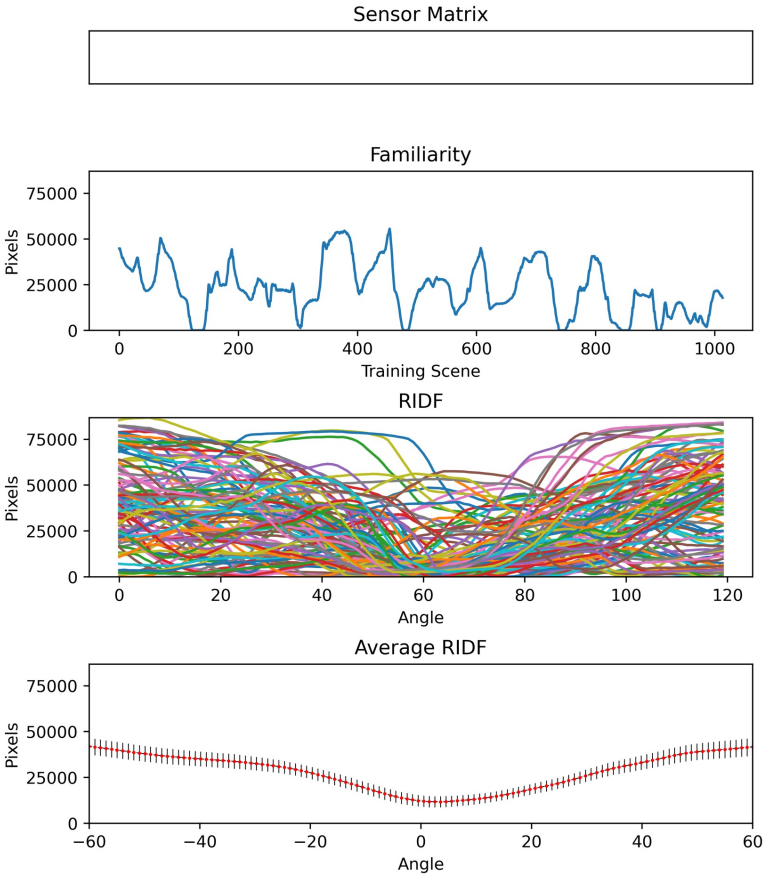


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 8000.52; RMSD/dist: 20.001; TD: 20864; p90: 74; p50: 36; complete: 0

0%

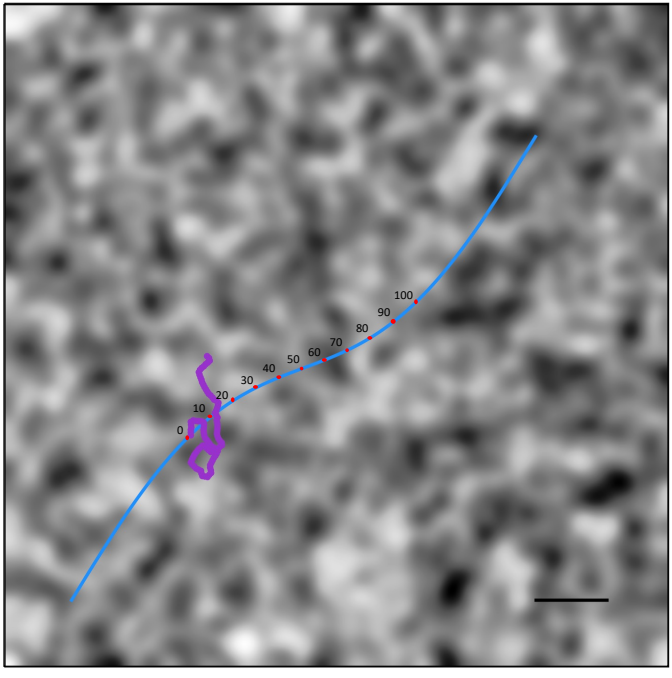


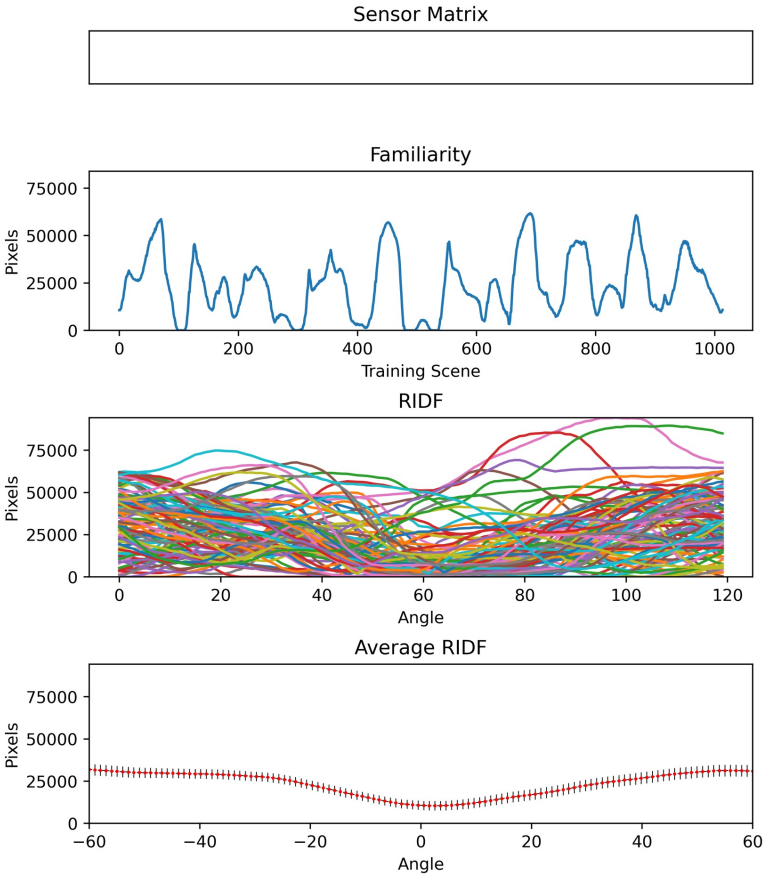


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 4437.72; RMSD/dist: 11.094; TD: 17470; p90: 40; p50: 24; complete: 0

0%

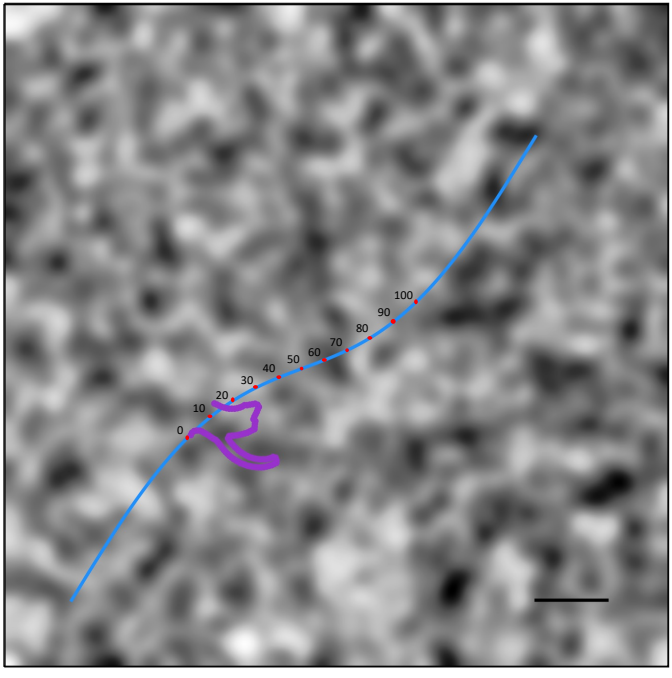


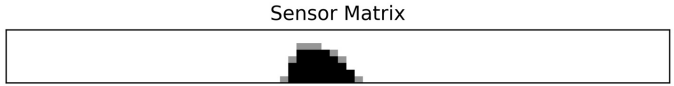


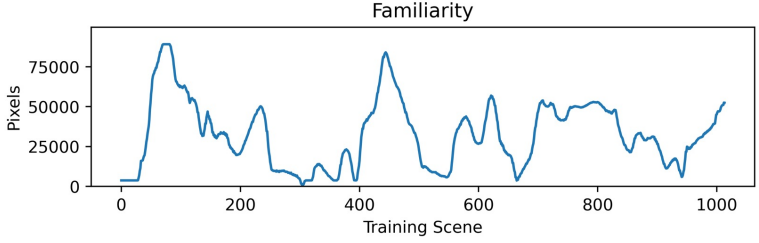
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

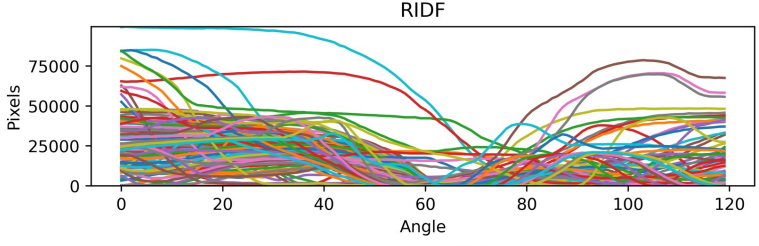
Navigation stats: RMSD error: 3315.45; RMSD/dist: 8.289; TD: 14617; p90: 44; p50: 28; complete: 0

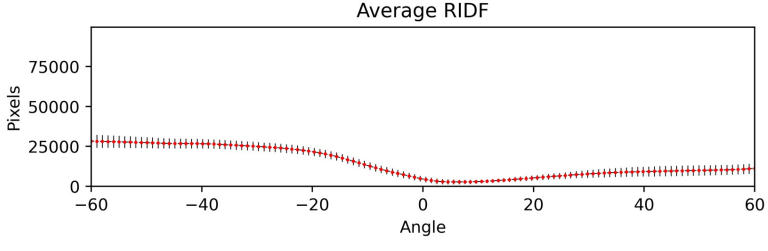
0%







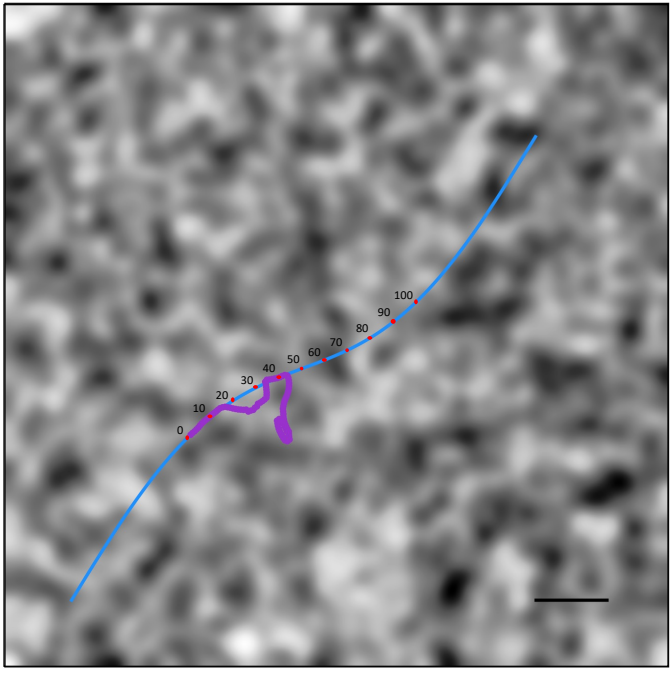


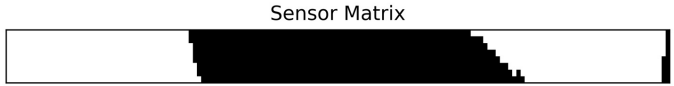


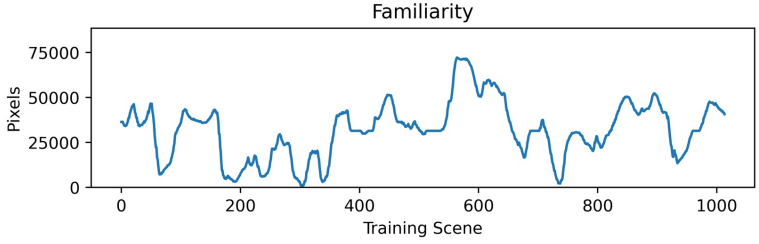
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

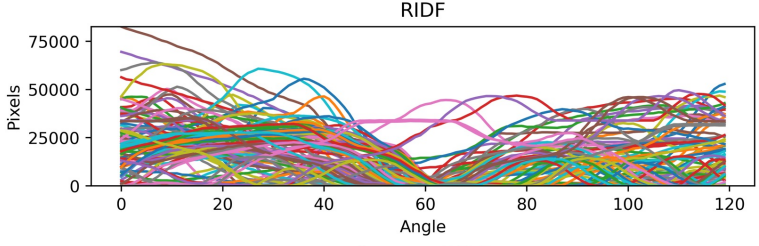
Navigation stats: RMSD error: 5285.19; RMSD/dist: 13.213; TD: 25023; p90: 64; p50: 26; complete: 0

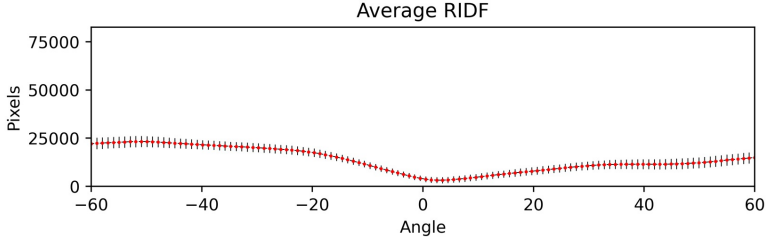
20%





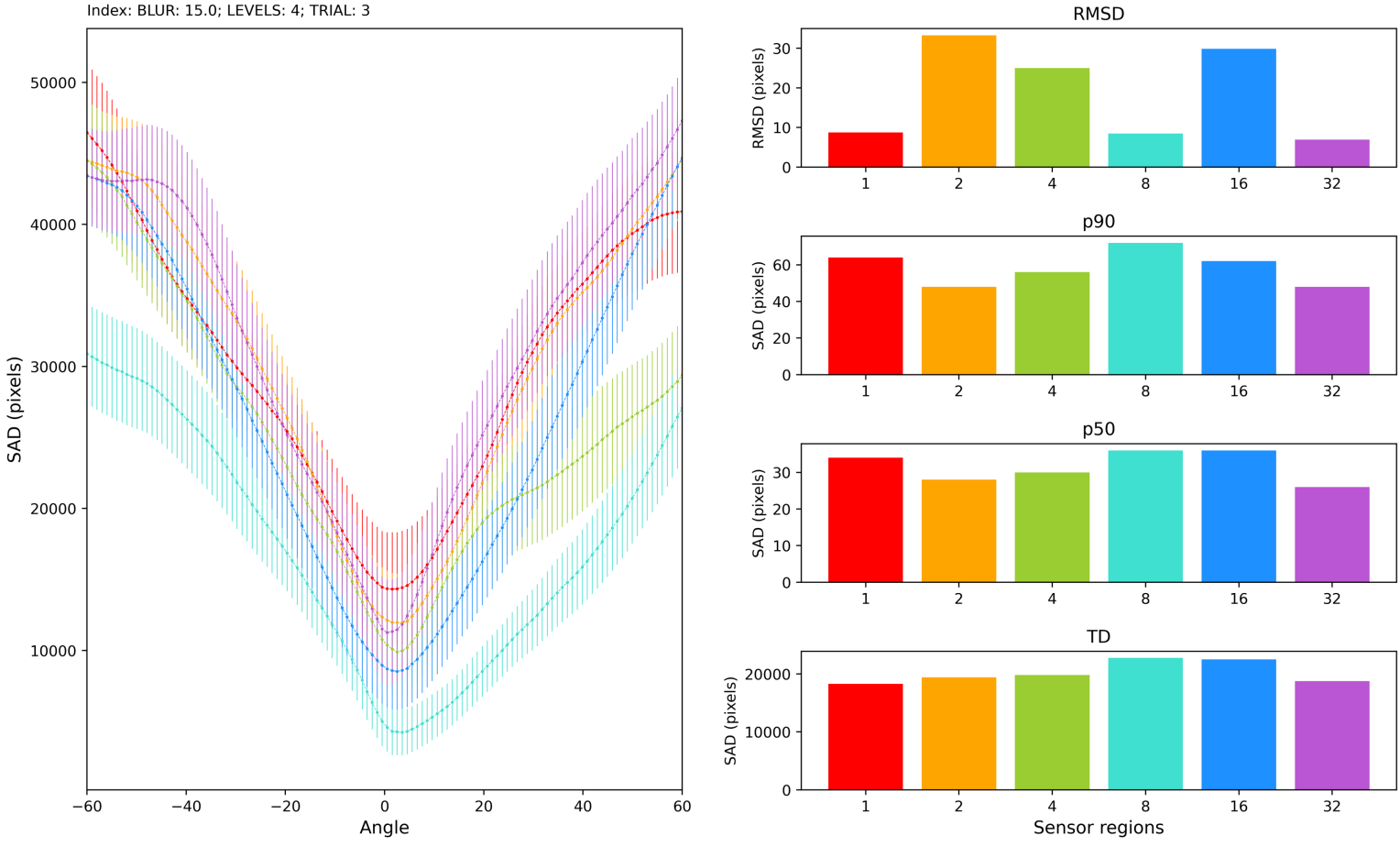




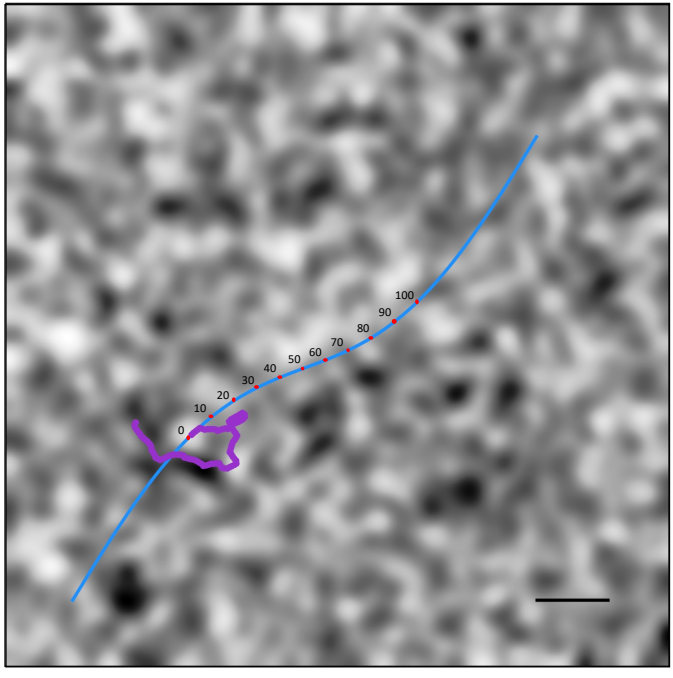


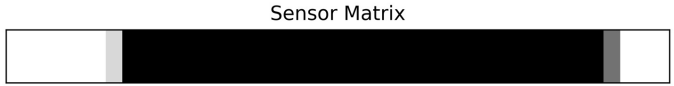
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

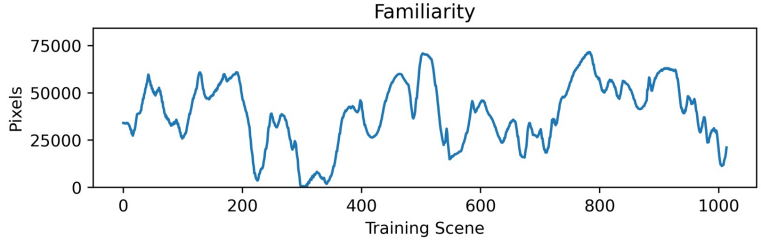
Navigation stats: RMSD error: 3453.60; RMSD/dist: 8.634; TD: 27184; p90: 102; p50: 38; complete: 0

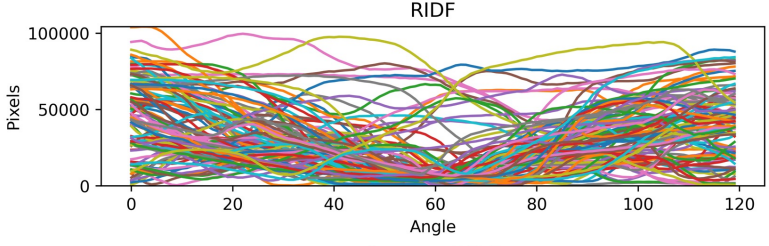

Index: BLUR: 15.0; LEVELS: 4; TRIAL: 3
SAD (pixels)
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
30
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
60
40
20
0
p50
30
20
10
TD
20000
10000
Sensor regions

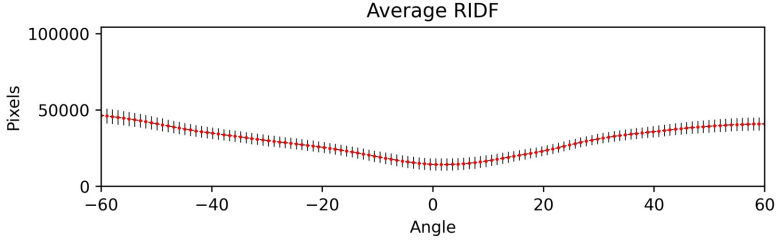
0%







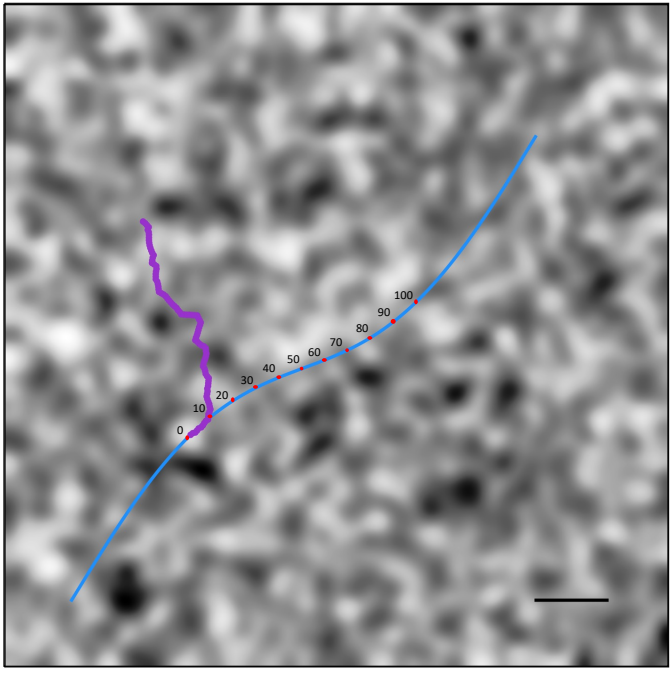


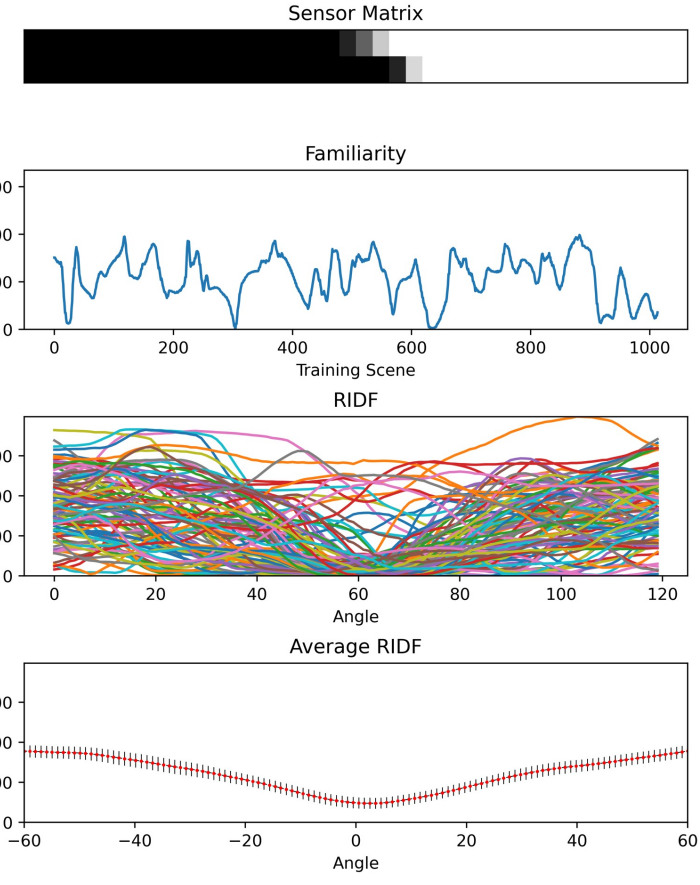


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 3484.91; RMSD/dist: 8.712; TD: 18272; p90: 64; p50: 34; complete: 0

10%

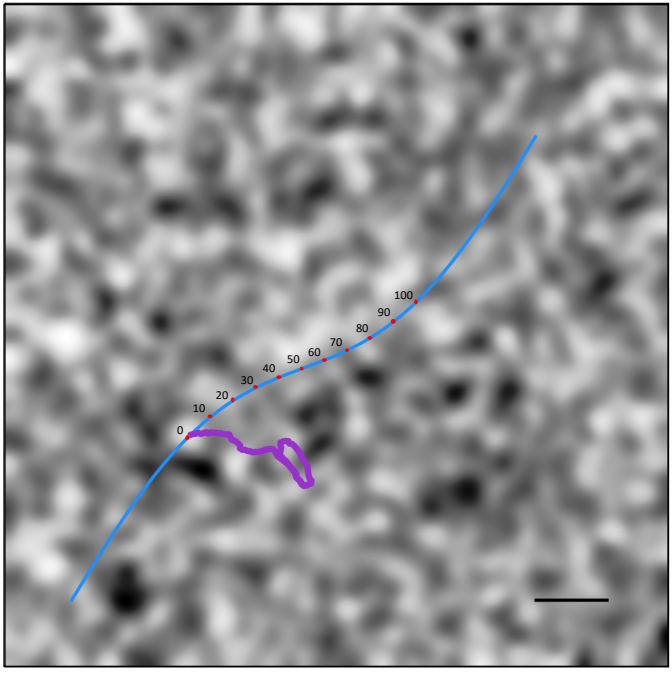


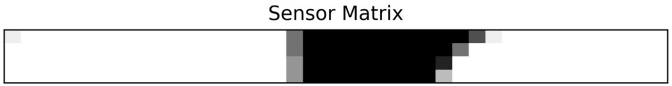


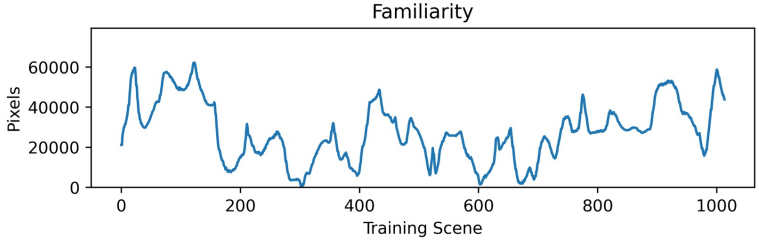
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

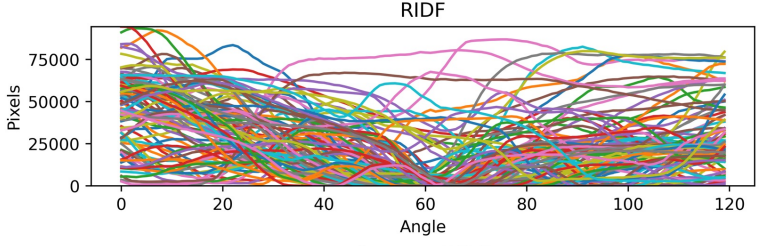
Navigation stats: RMSD error: 13316.57; RMSD/dist: 33.291; TD: 19430; p90: 48; p50: 28; complete: 0

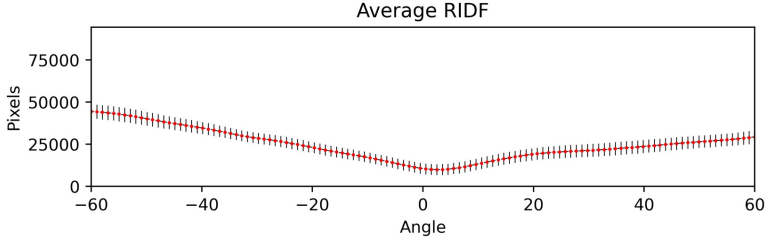
0%







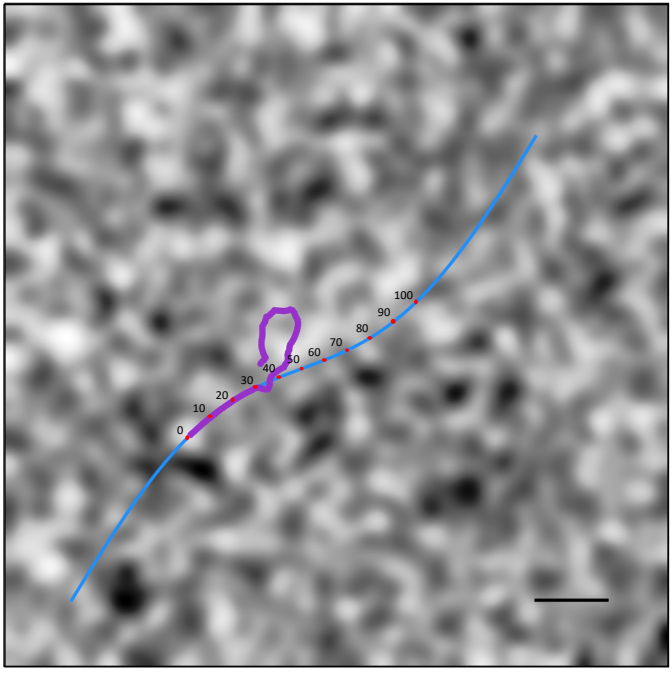


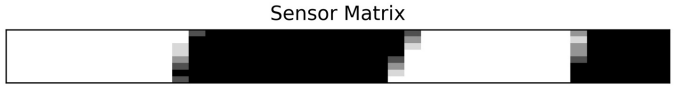


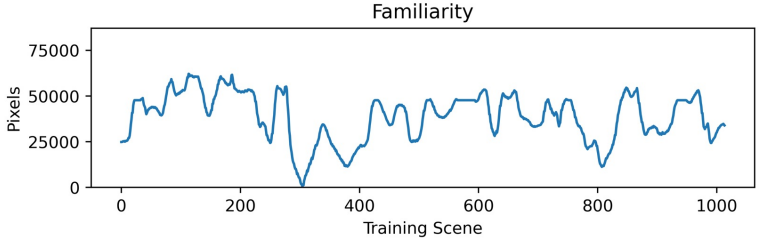
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

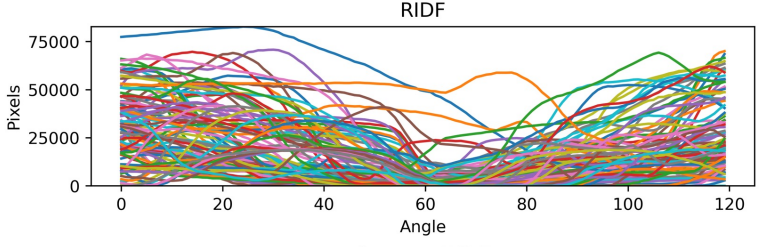
Navigation stats: RMSD error: 9995.14; RMSD/dist: 24.988; TD: 19804; p90: 56; p50: 30; complete: 0

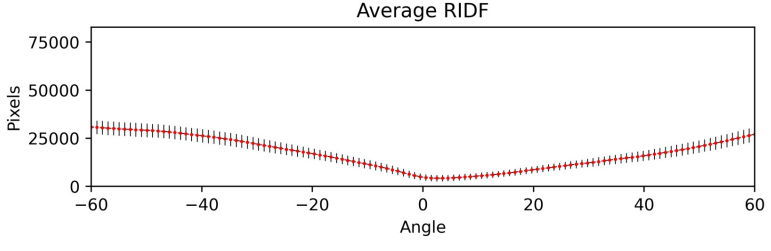
30%







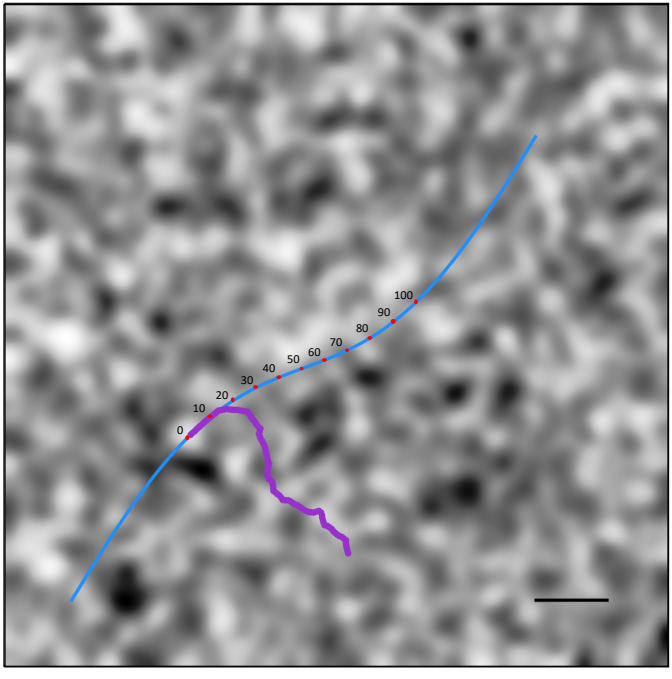


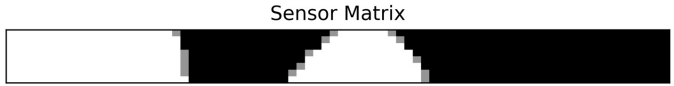


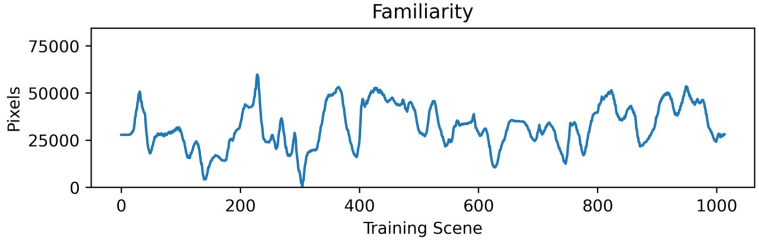
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

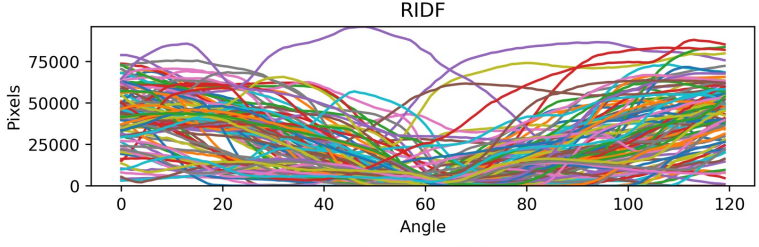
Navigation stats: RMSD error: 3378.73; RMSD/dist: 8.447; TD: 22749; p90: 72; p50: 36; complete: 0

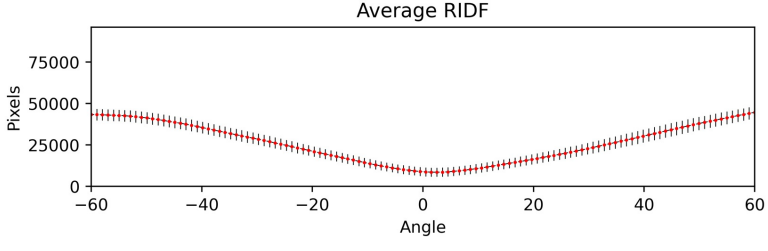
10%







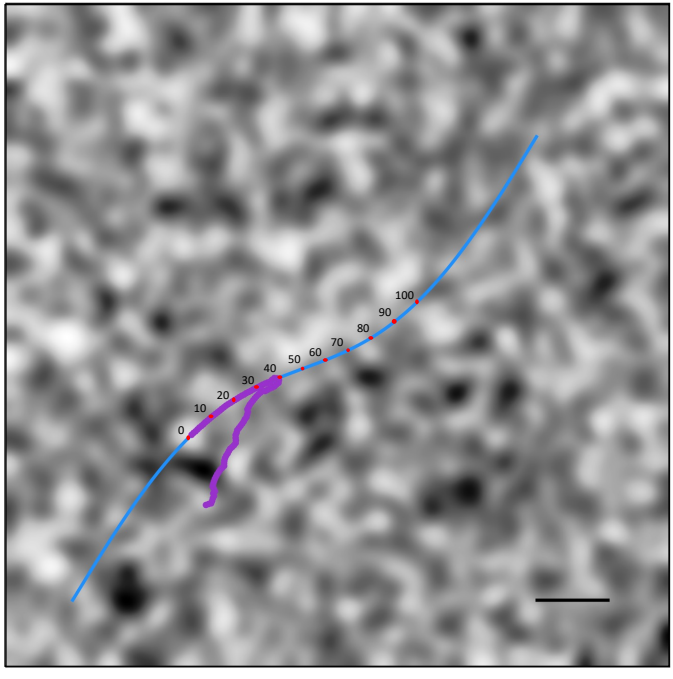


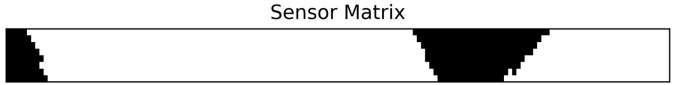


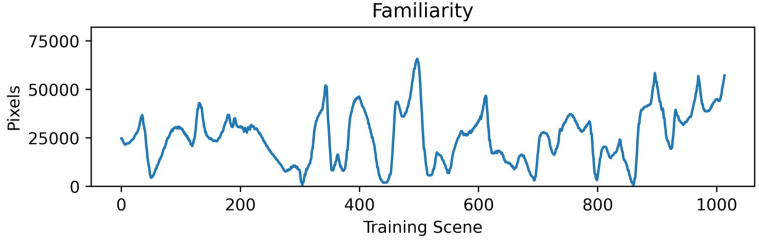
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

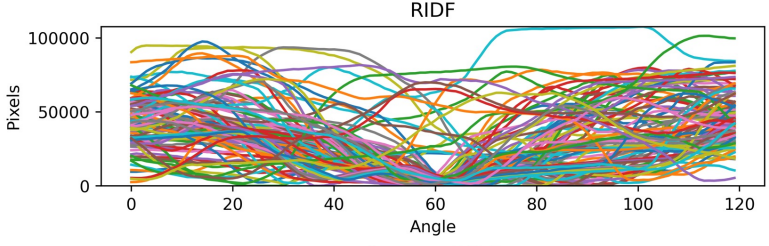
Navigation stats: RMSD error: 11933.11; RMSD/dist: 29.833; TD: 22523; p90: 62; p50: 36; complete: 0

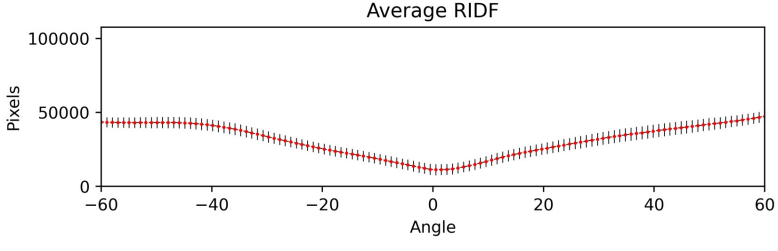
40%





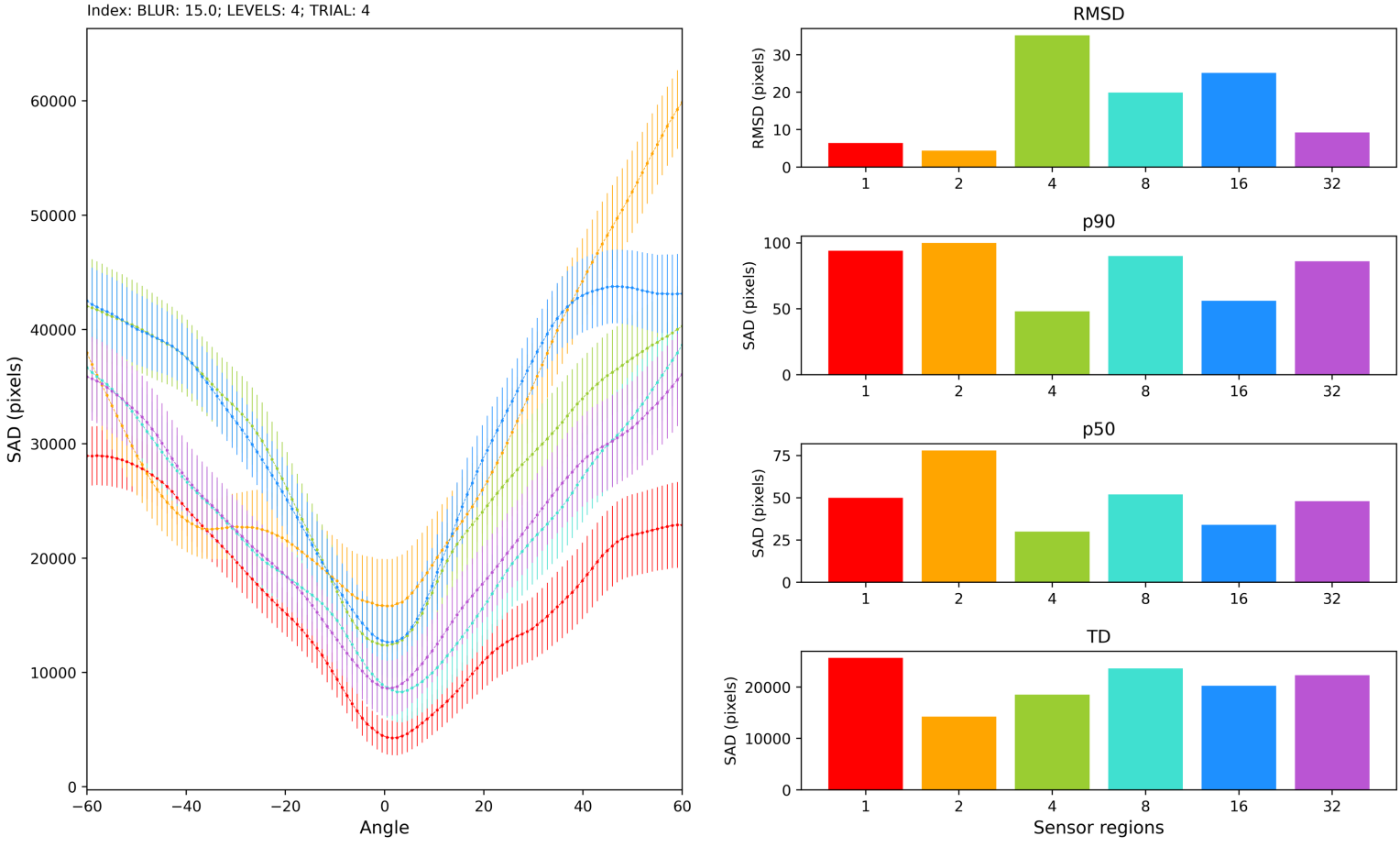




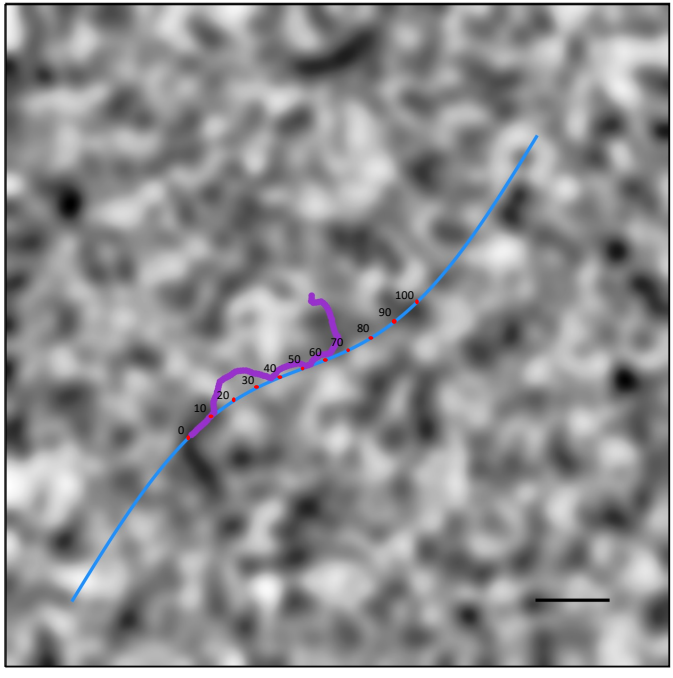


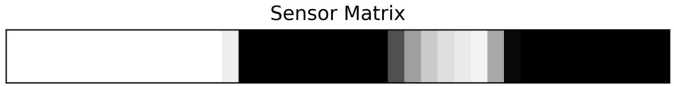
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

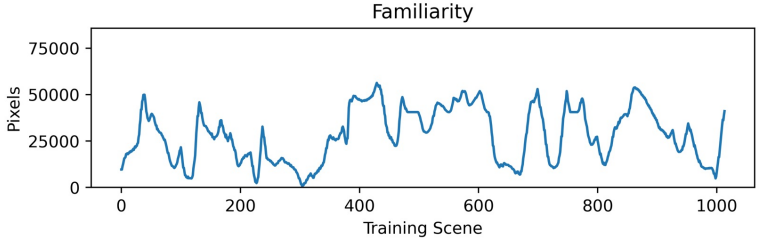
Navigation stats: RMSD error: 2763.48; RMSD/dist: 6.909; TD: 18773; p90: 48; p50: 26; complete: 0

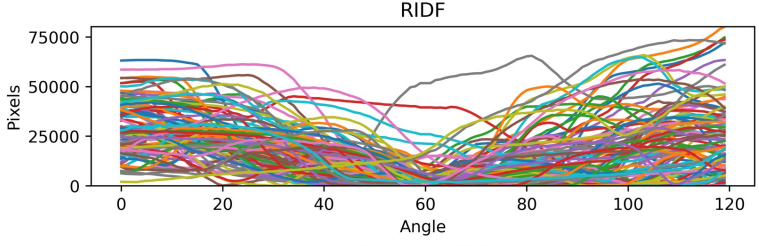

Index: BLUR: 15.0; LEVELS: 4; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

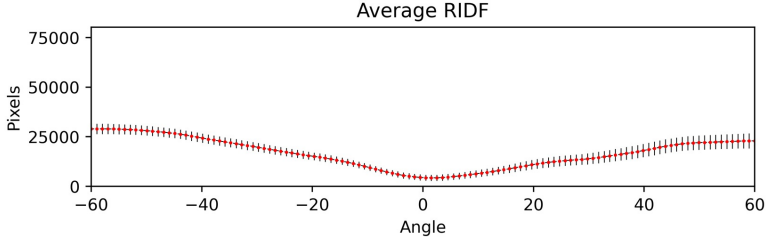
10%







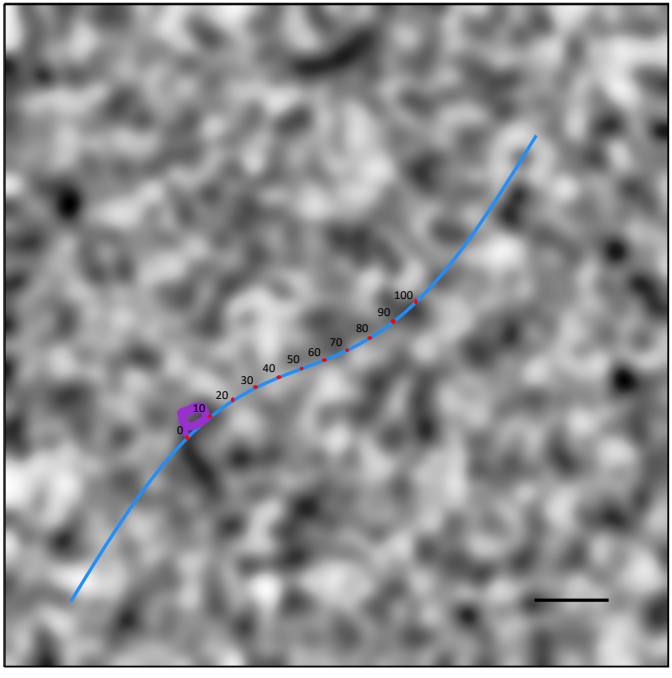


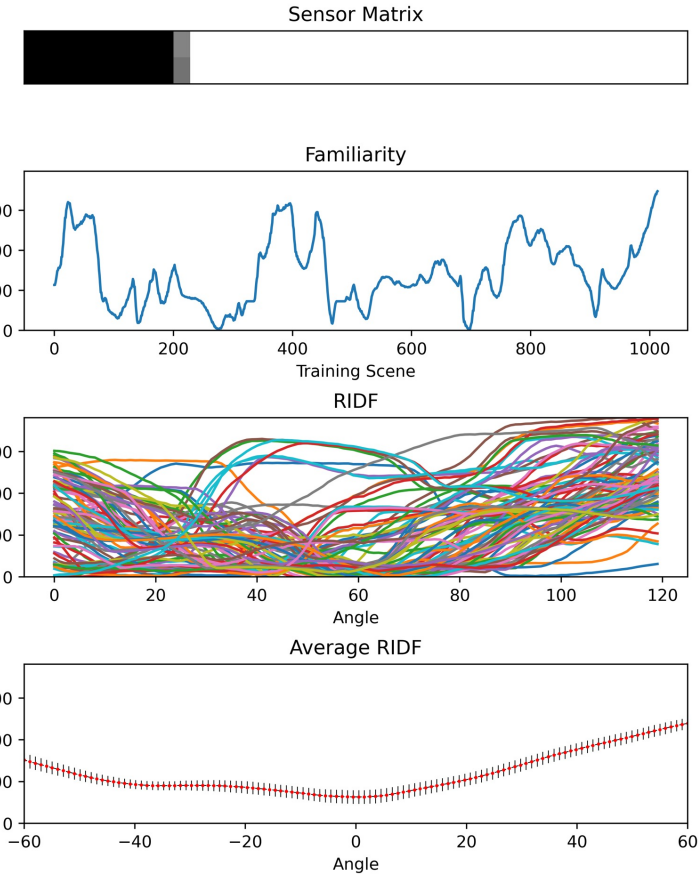


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2561.98; RMSD/dist: 6.405; TD: 25667; p90: 94; p50: 50; complete: 0

0%

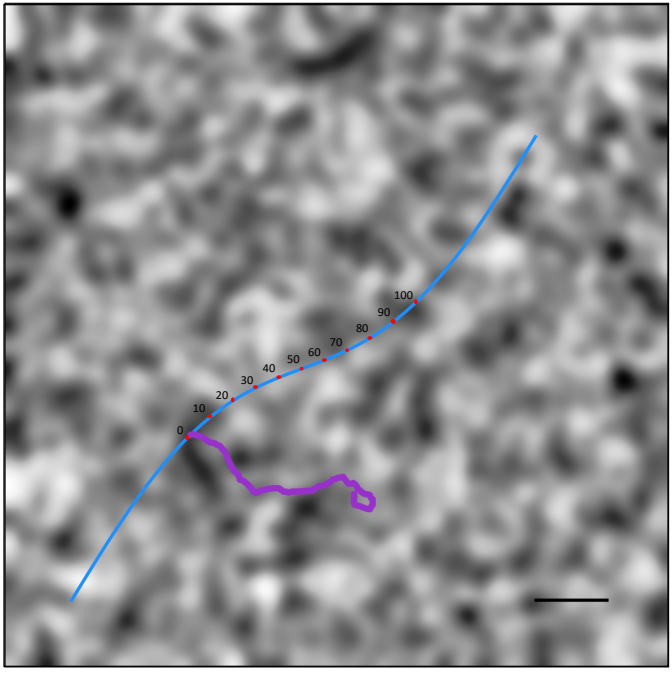


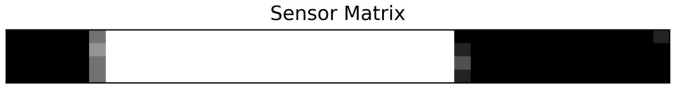


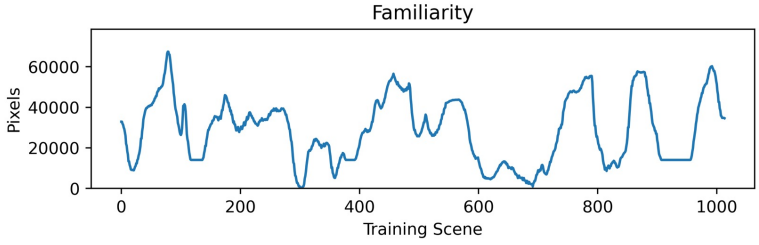
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

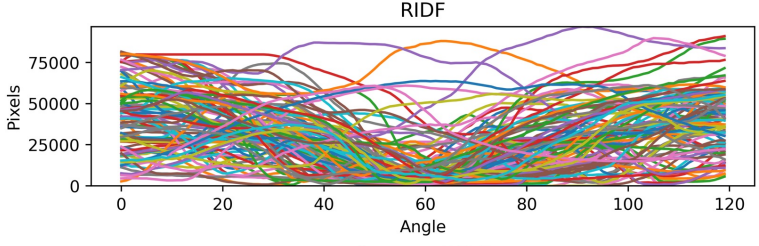
Navigation stats: RMSD error: 1756.96; RMSD/dist: 4.392; TD: 14271; p90: 100; p50: 78; complete: 0

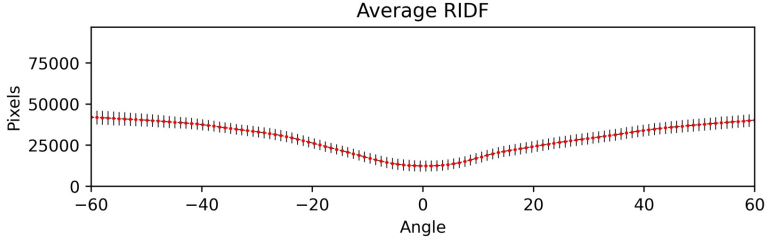
0%







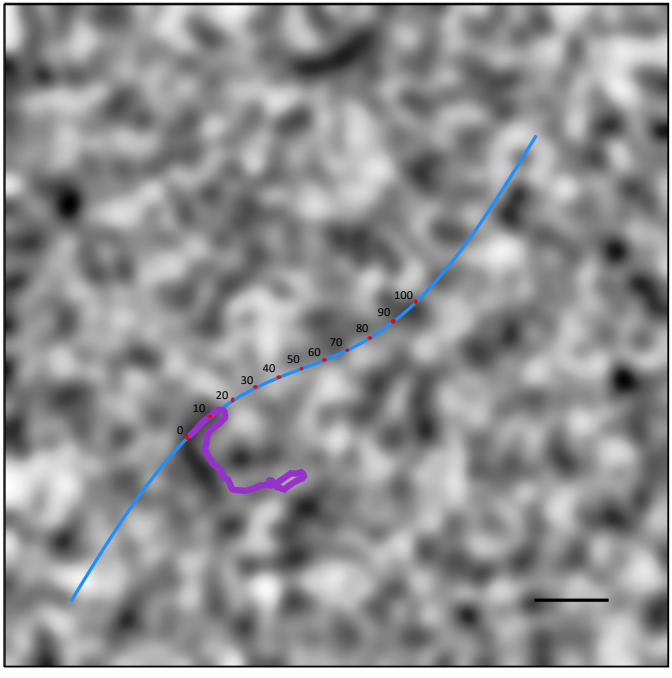


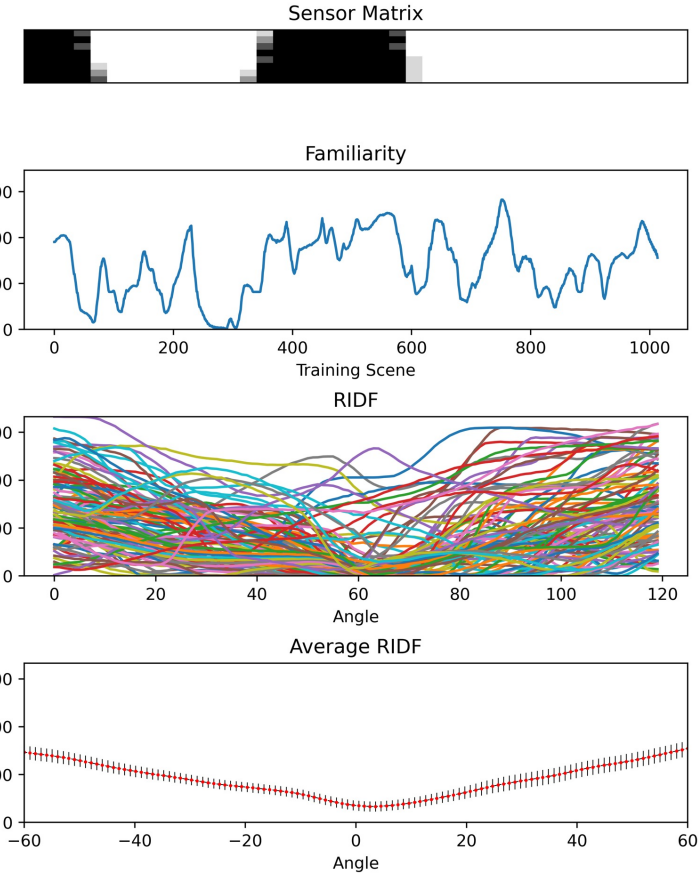


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 14084.15; RMSD/dist: 35.210; TD: 18535; p90: 48; p50: 30; complete: 0

10%

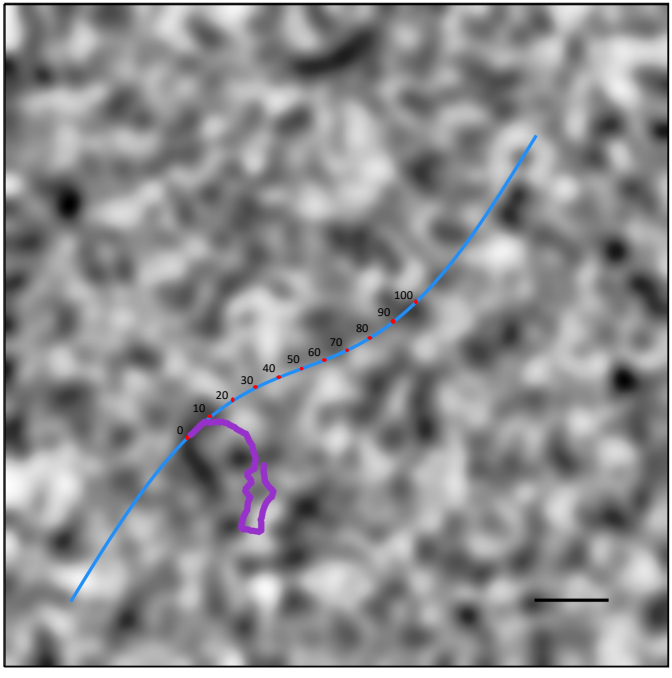


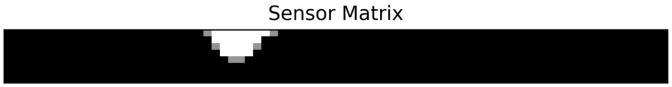


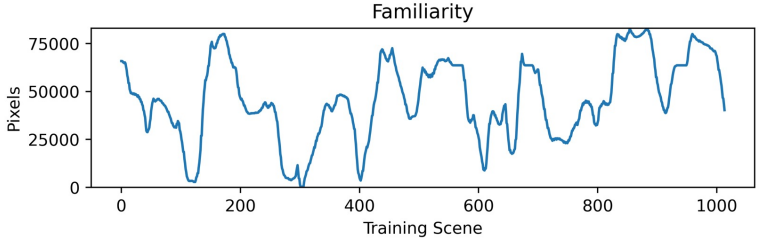
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

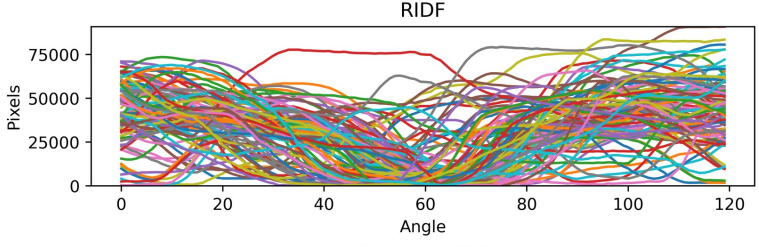
Navigation stats: RMSD error: 7965.93; RMSD/dist: 19.915; TD: 23620; p90: 90; p50: 52; complete: 0

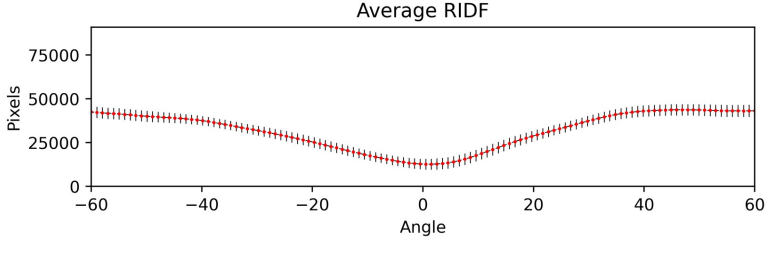
0%







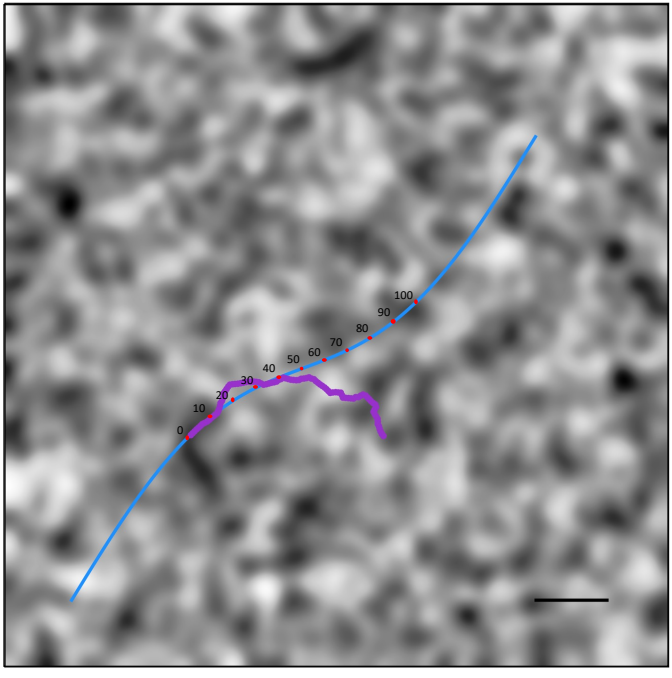


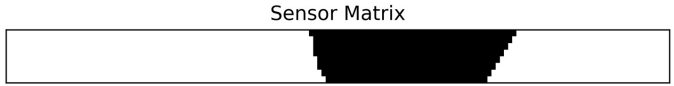


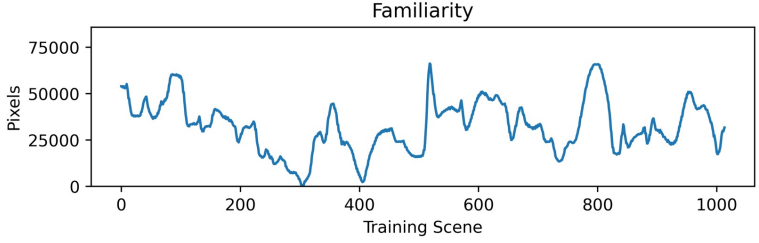
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

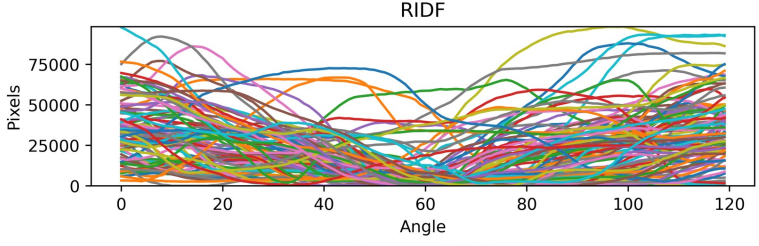
Navigation stats: RMSD error: 10053.51; RMSD/dist: 25.134; TD: 20252; p90: 56; p50: 34; complete: 0

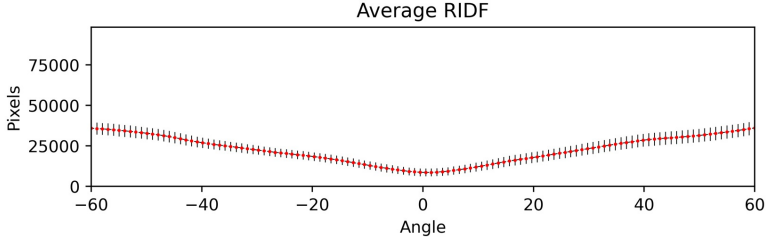
10%





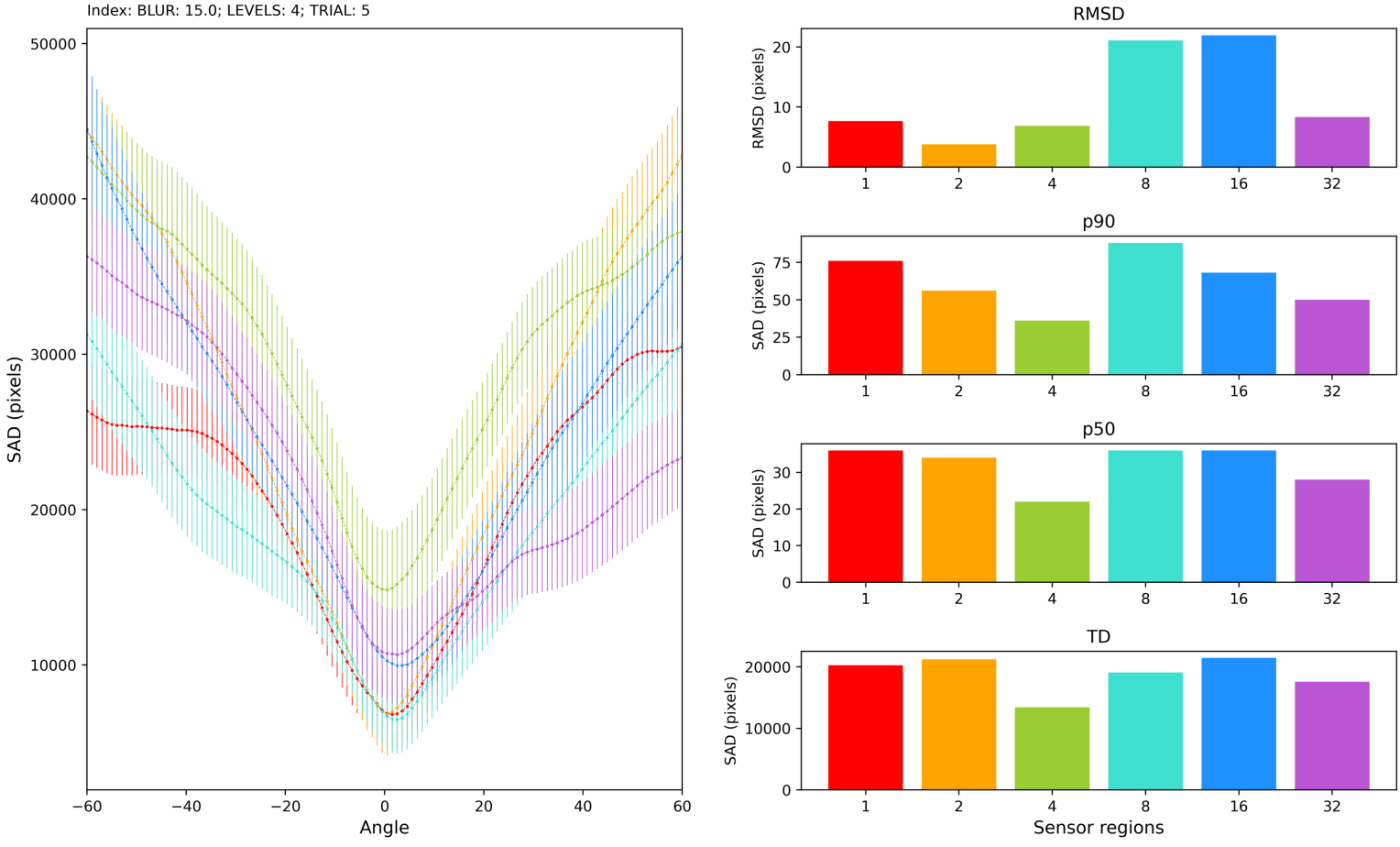




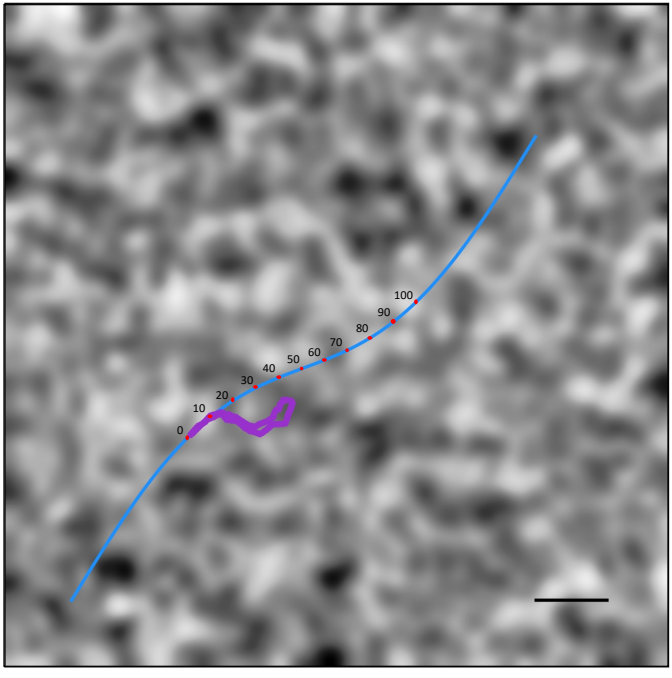


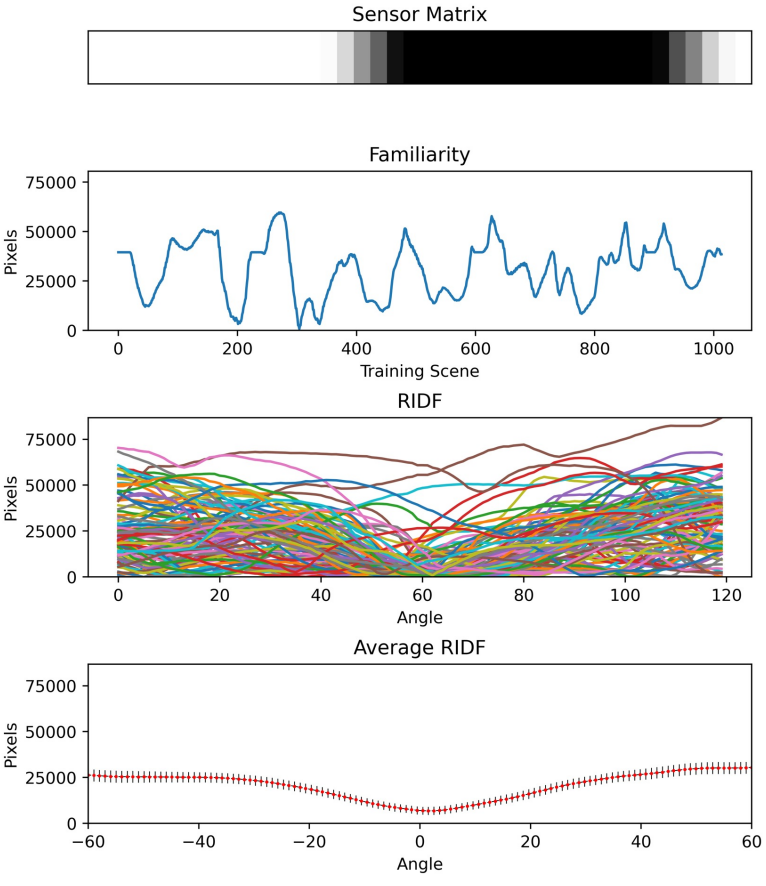
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3696.40; RMSD/dist: 9.241; TD: 22325; p90: 86; p50: 48; complete: 0


Index: BLUR: 15.0; LEVELS: 4; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

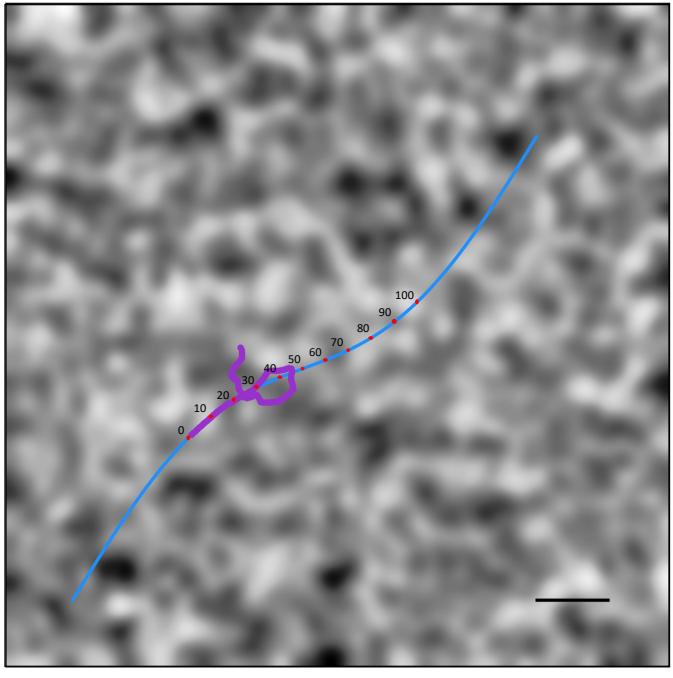


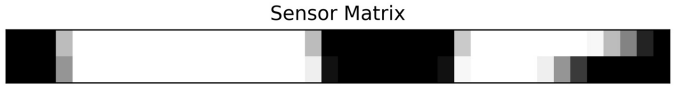


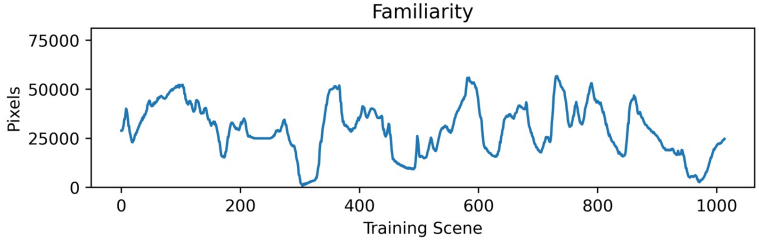
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

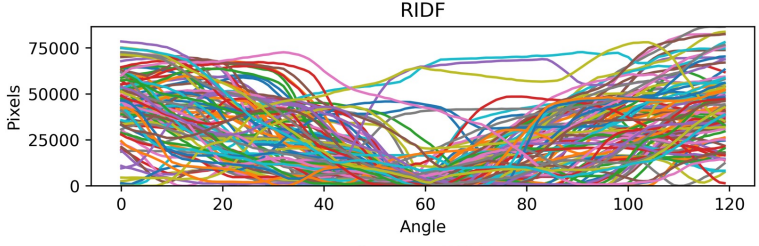
Navigation stats: RMSD error: 3066.96; RMSD/dist: 7.667; TD: 20243; p90: 76; p50: 36; complete: 0

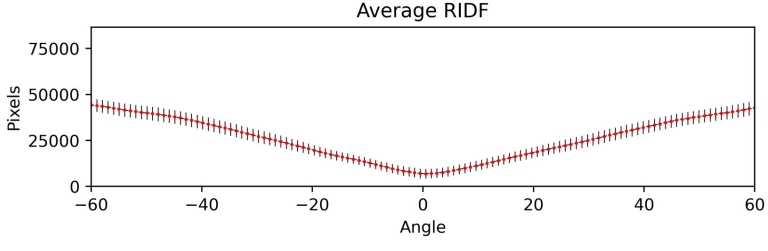
30%







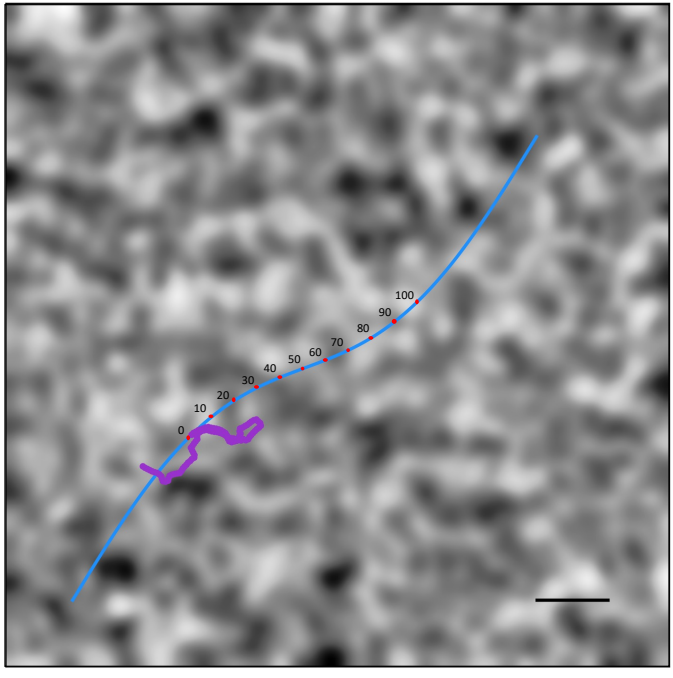


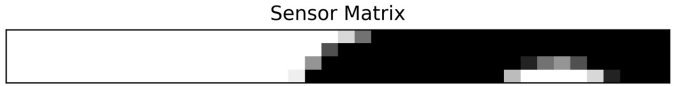


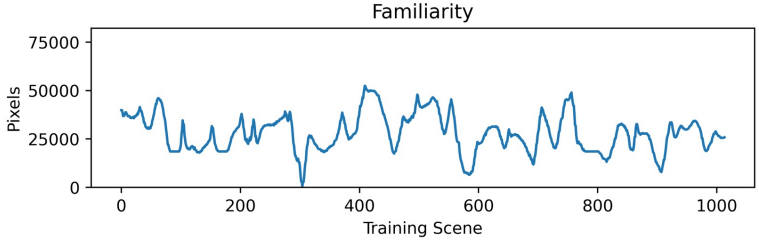
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

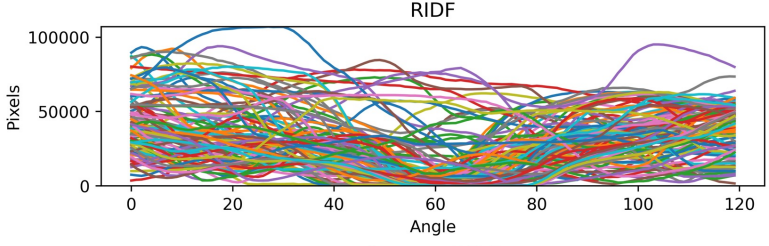
Navigation stats: RMSD error: 1511.37; RMSD/dist: 3.778; TD: 21235; p90: 56; p50: 34; complete: 0

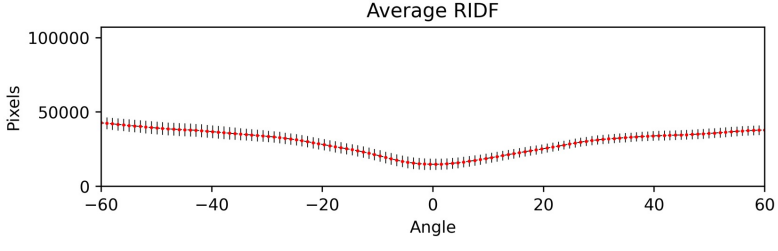
0%







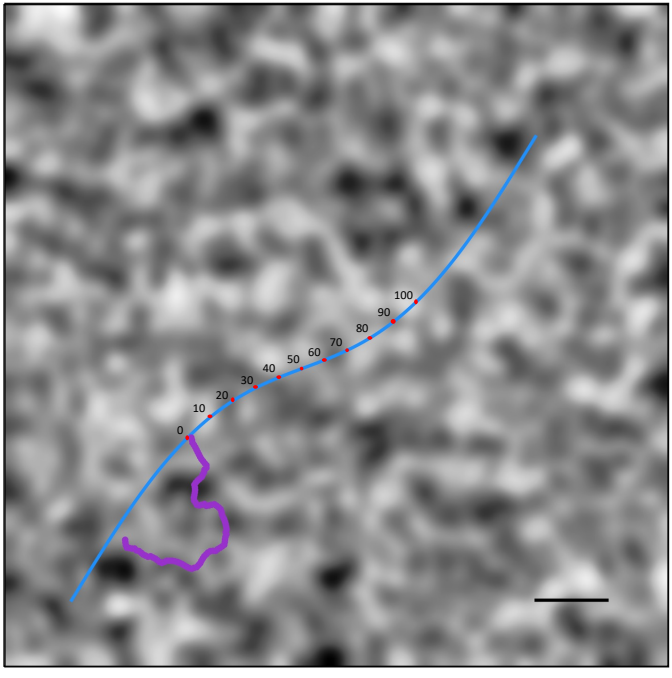


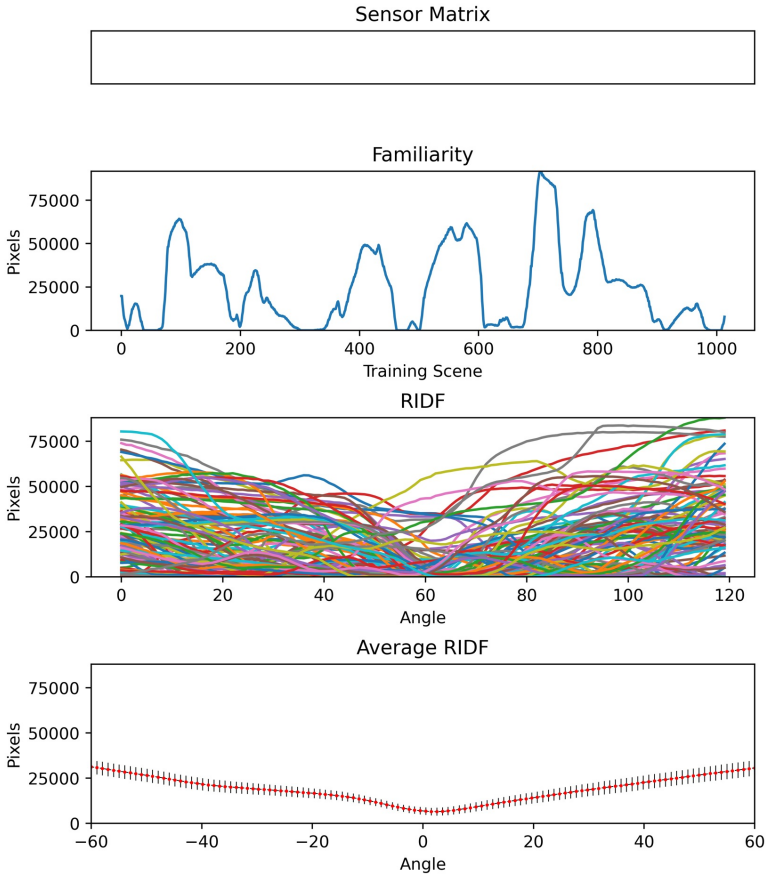


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2738.71; RMSD/dist: 6.847; TD: 13421; p90: 36; p50: 22; complete: 0

0%

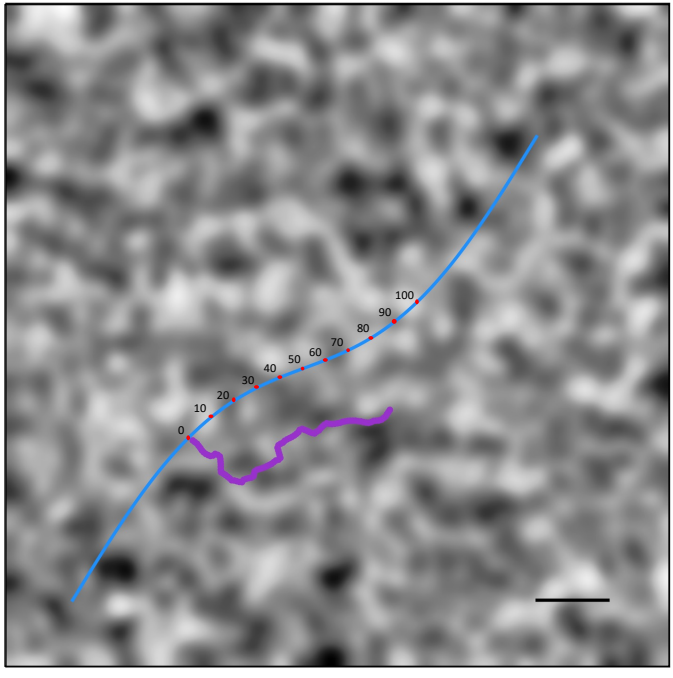


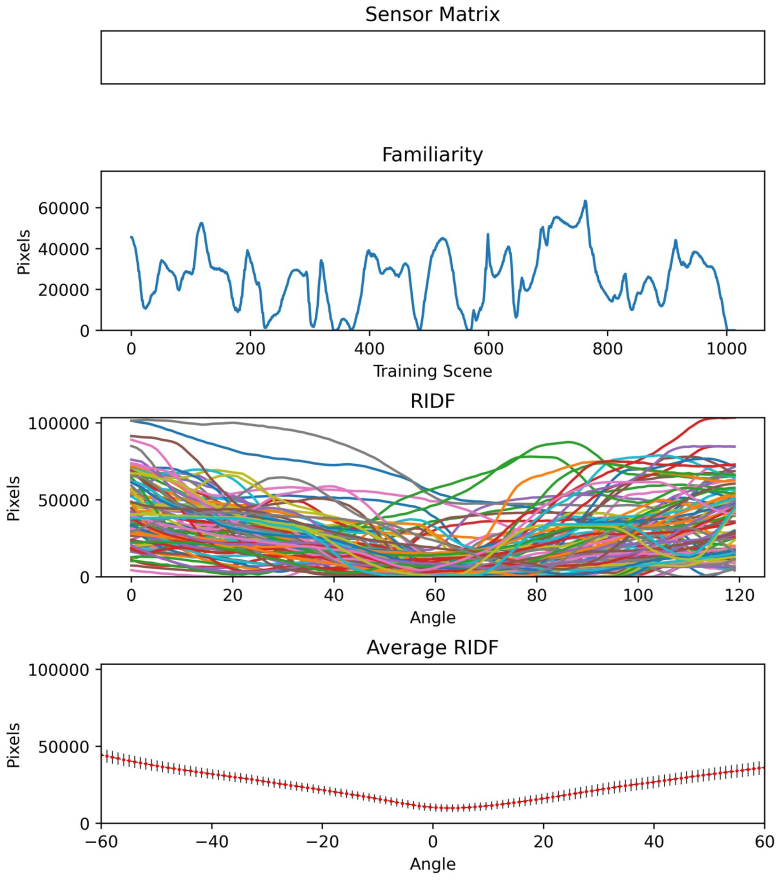


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 8432.87; RMSD/dist: 21.082; TD: 19092; p90: 88; p50: 36; complete: 0

0%

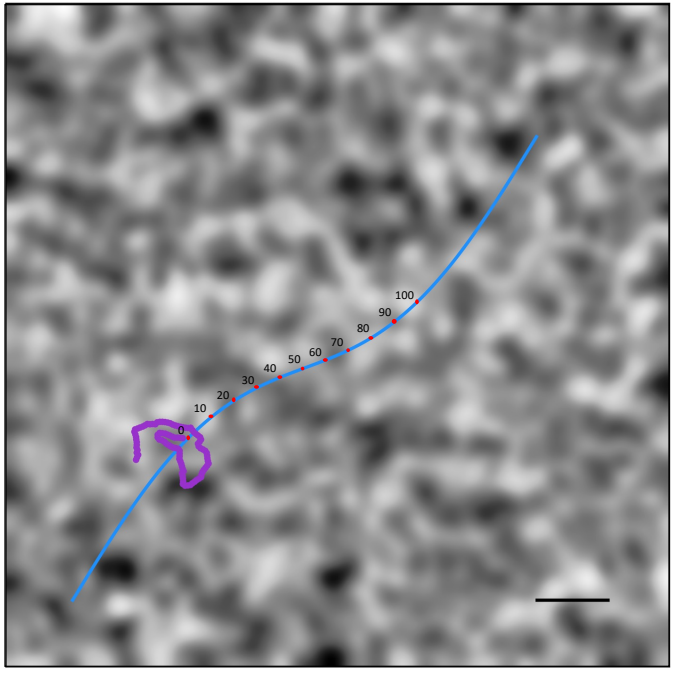


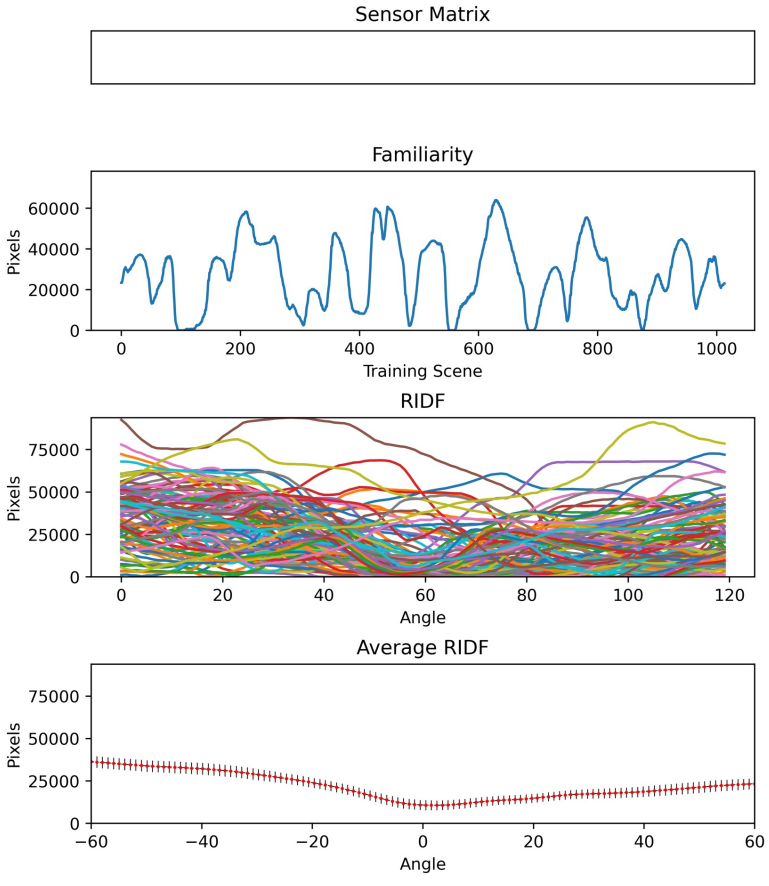


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 8781.79; RMSD/dist: 21.954; TD: 21443; p90: 68; p50: 36; complete: 0

0%





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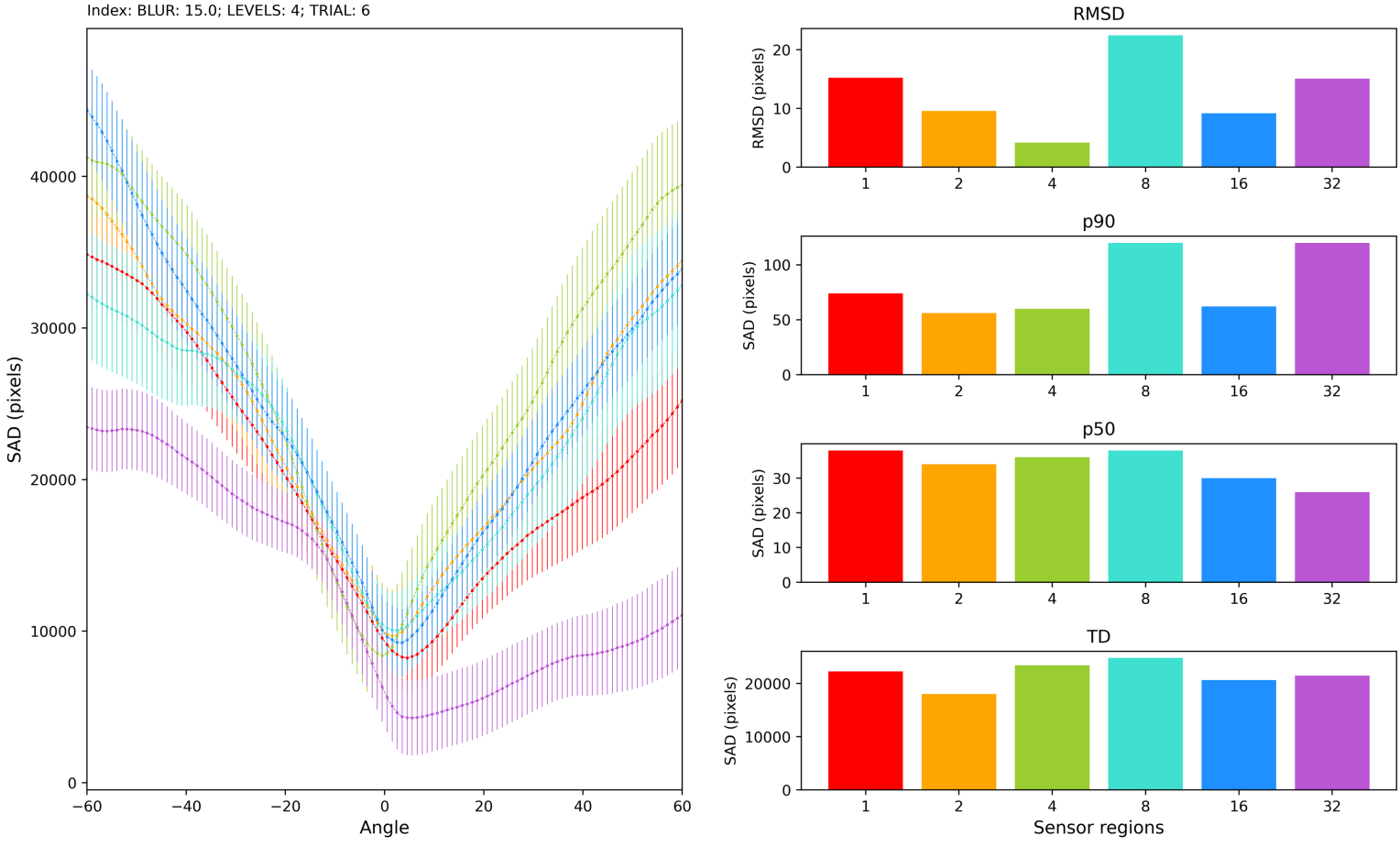
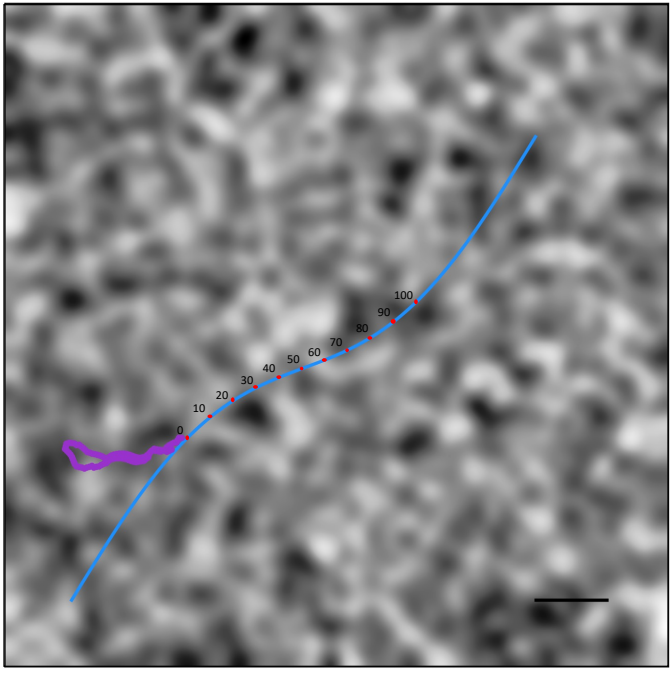
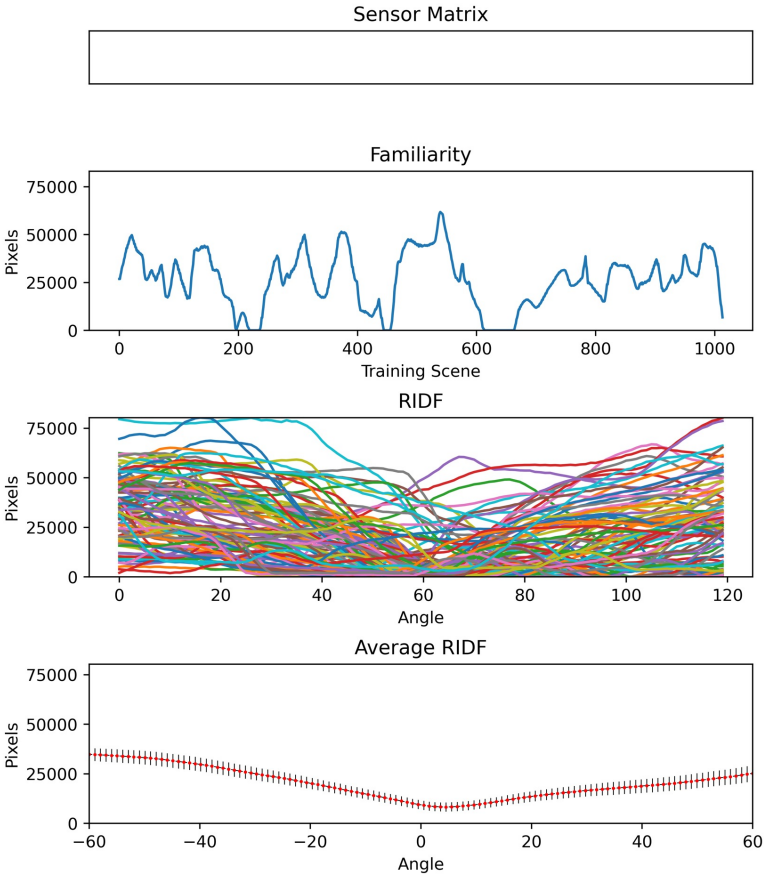
Navigation stats: RMSD error: 3334.18; RMSD/dist: 8.335; TD: 17592; p90: 50; p50: 28; complete: 0


Index: BLUR: 15.0; LEVELS: 4; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

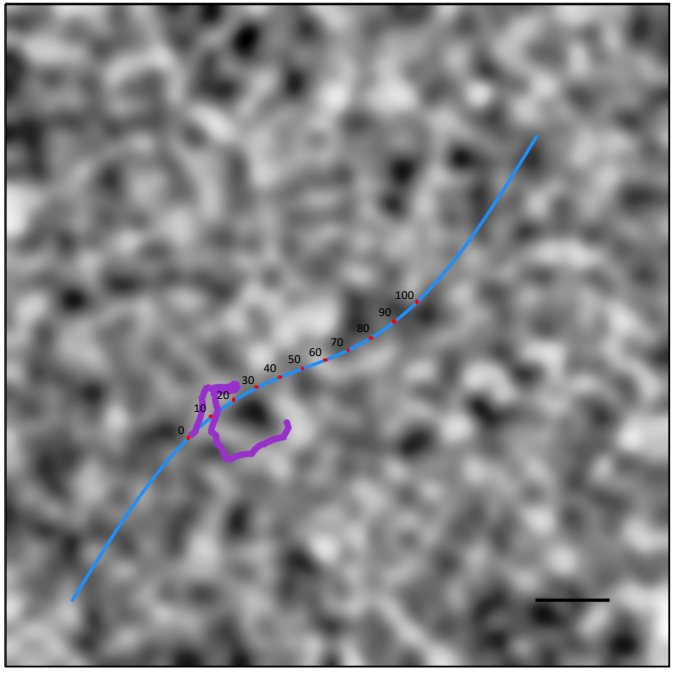


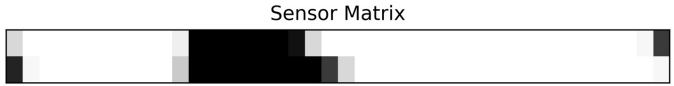


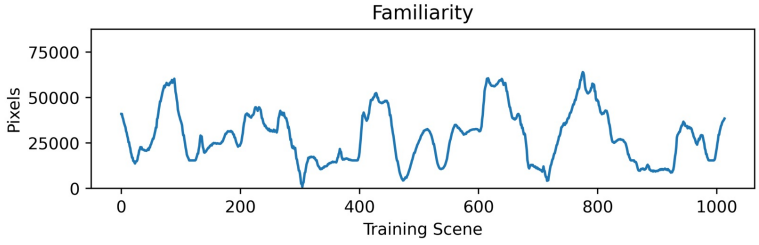
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

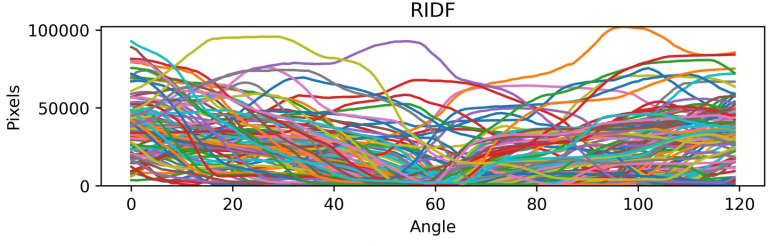
Navigation stats: RMSD error: 6081.57; RMSD/dist: 15.204; TD: 22261; p90: 74; p50: 38; complete: 0

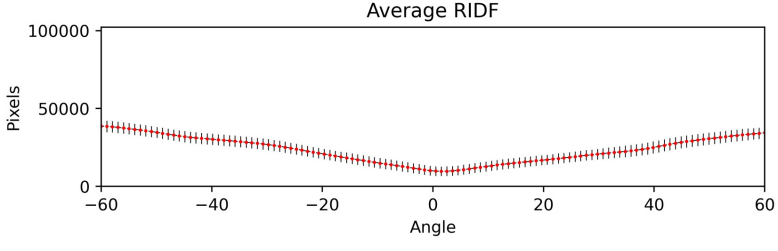
0%







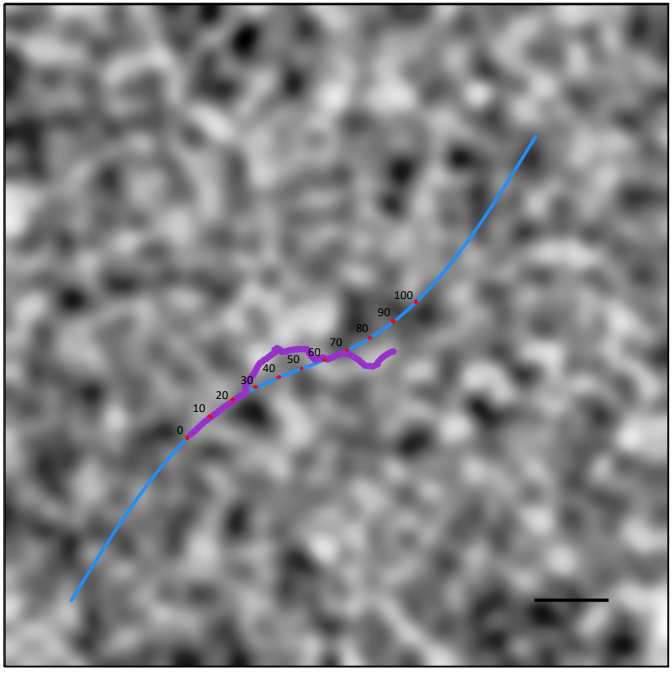


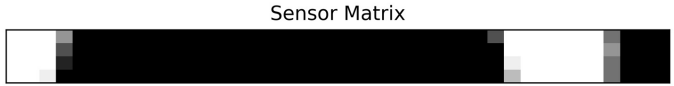


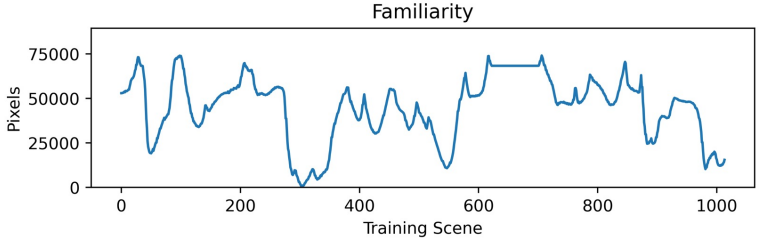
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

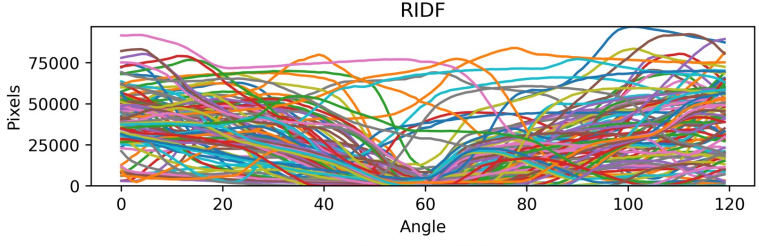
Navigation stats: RMSD error: 3829.39; RMSD/dist: 9.573; TD: 18026; p90: 56; p50: 34; complete: 0

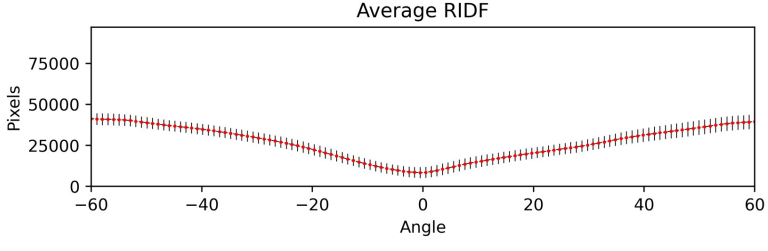
30%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1663.81; RMSD/dist: 4.160; TD: 23436; p90: 60; p50: 36; complete: 0

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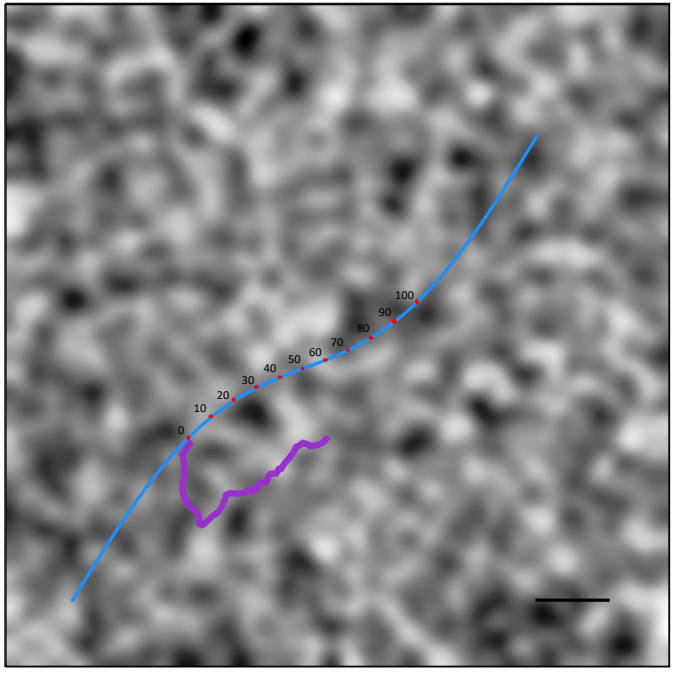
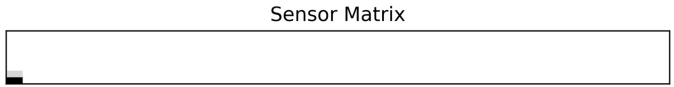
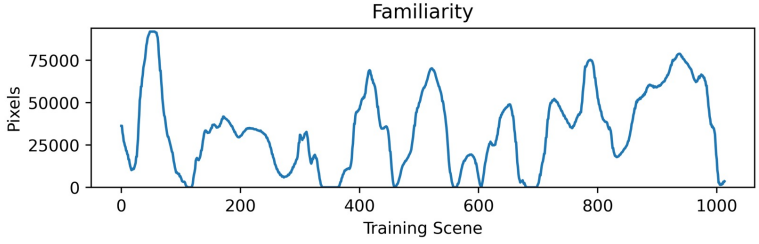
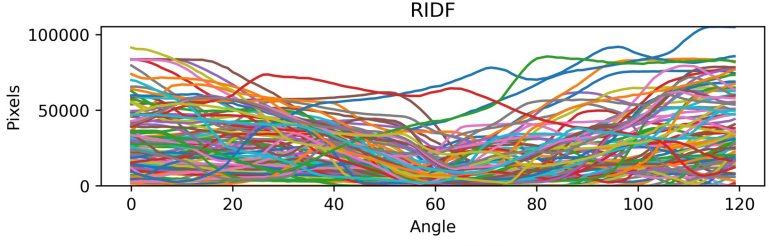
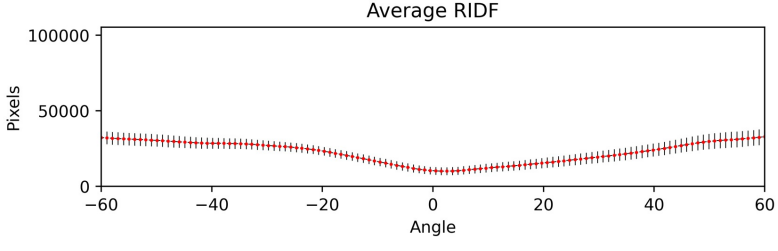






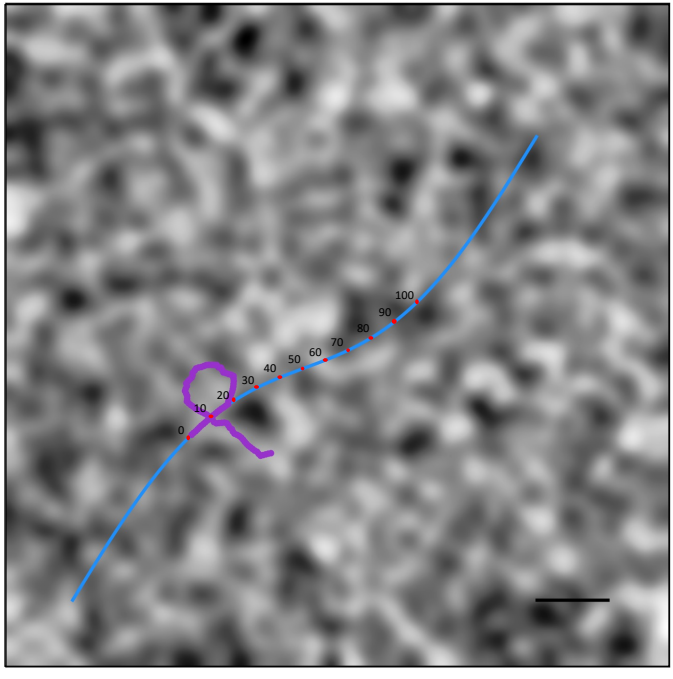


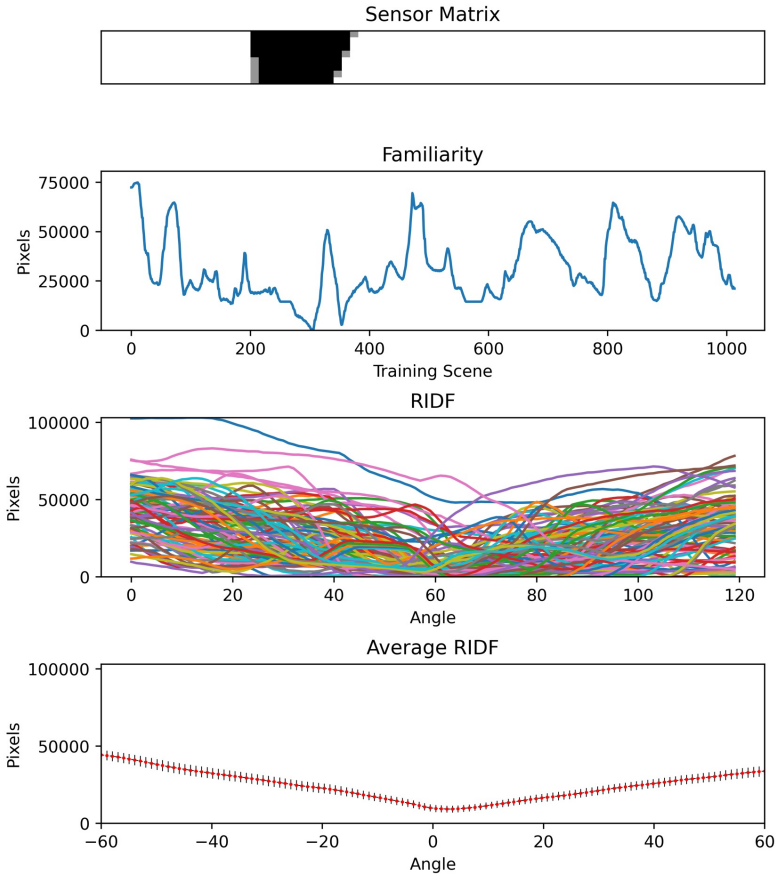


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 8982.42; RMSD/dist: 22.456; TD: 24795; p90: 120; p50: 38; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3670.32; RMSD/dist: 9.176; TD: 20627; p90: 62; p50: 30; complete: 0

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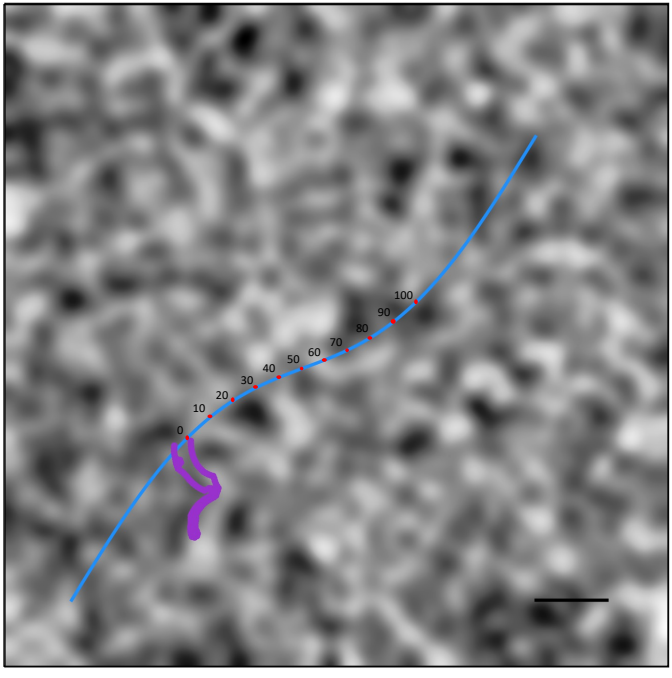
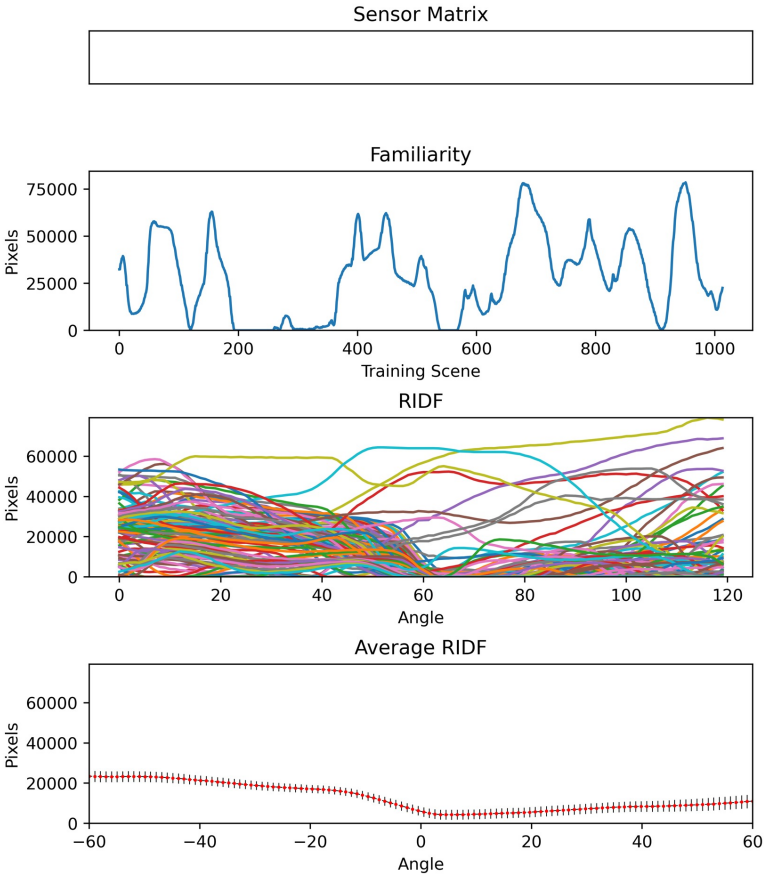
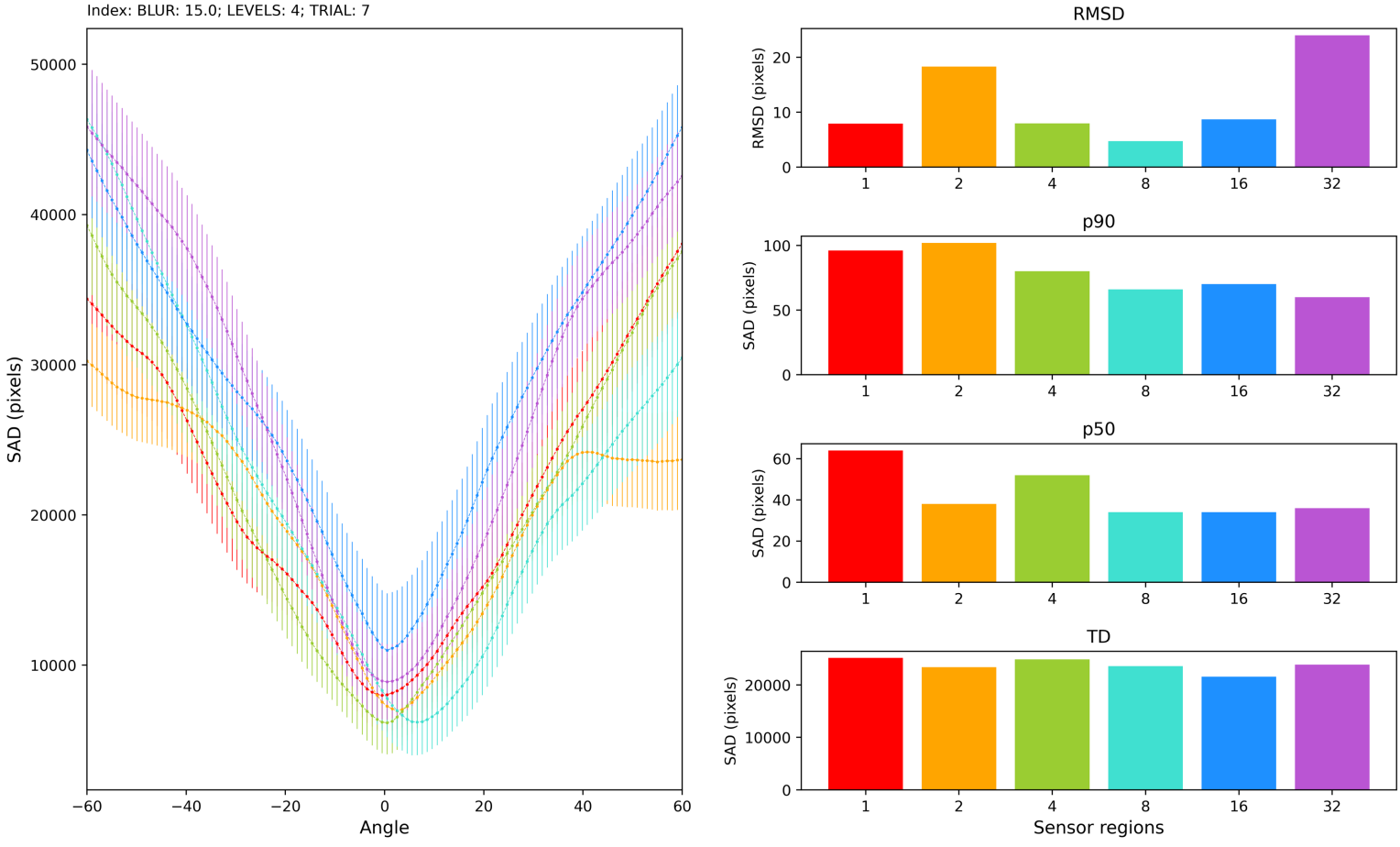


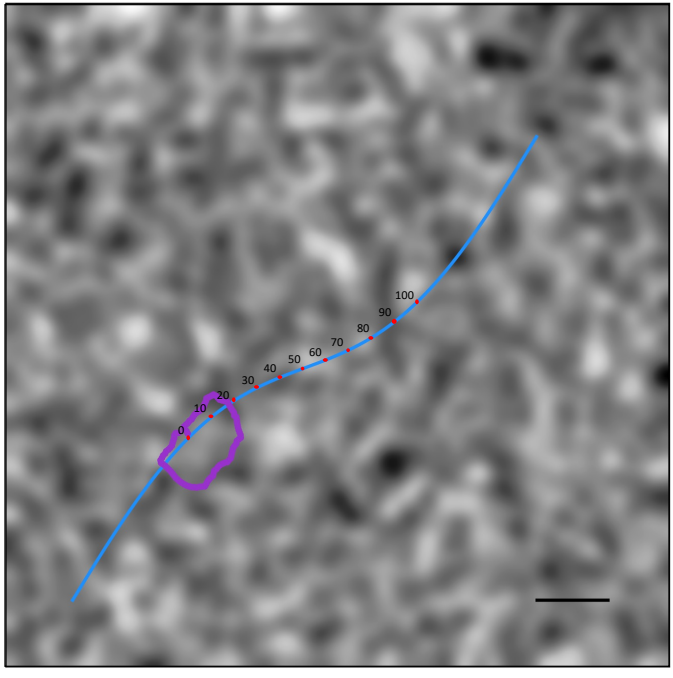


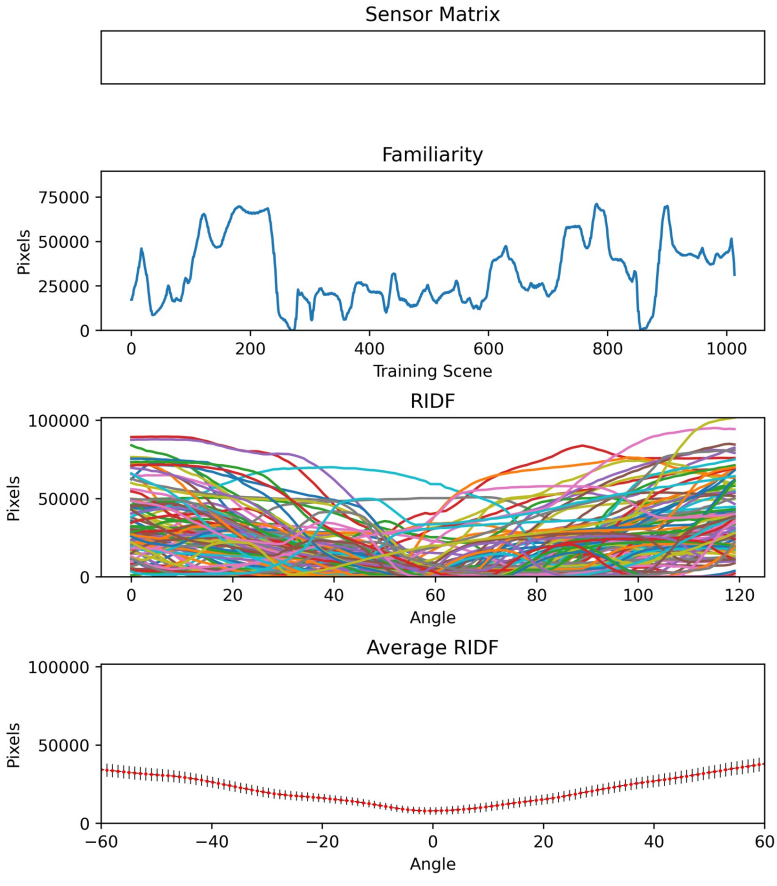
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 6020.58; RMSD/dist: 15.051; TD: 21496; p90: 120; p50: 26; complete: 0


Index: BLUR: 15.0; LEVELS: 4; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

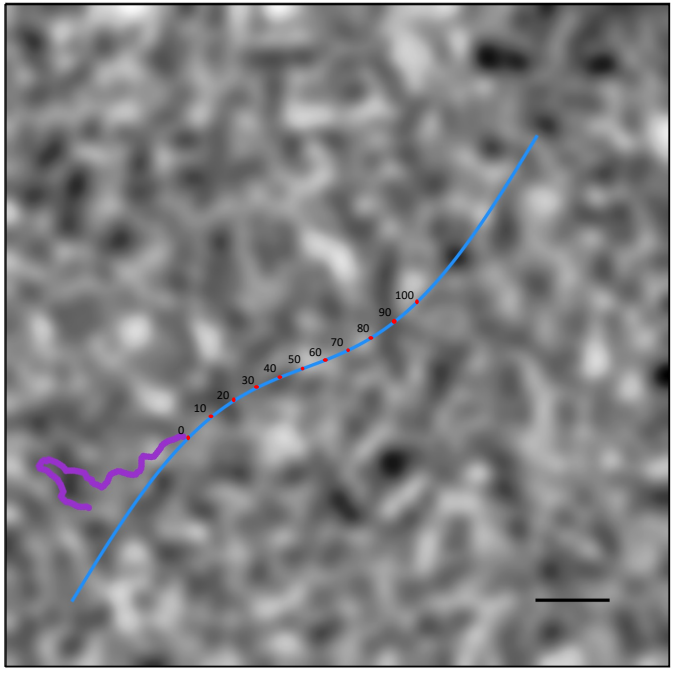


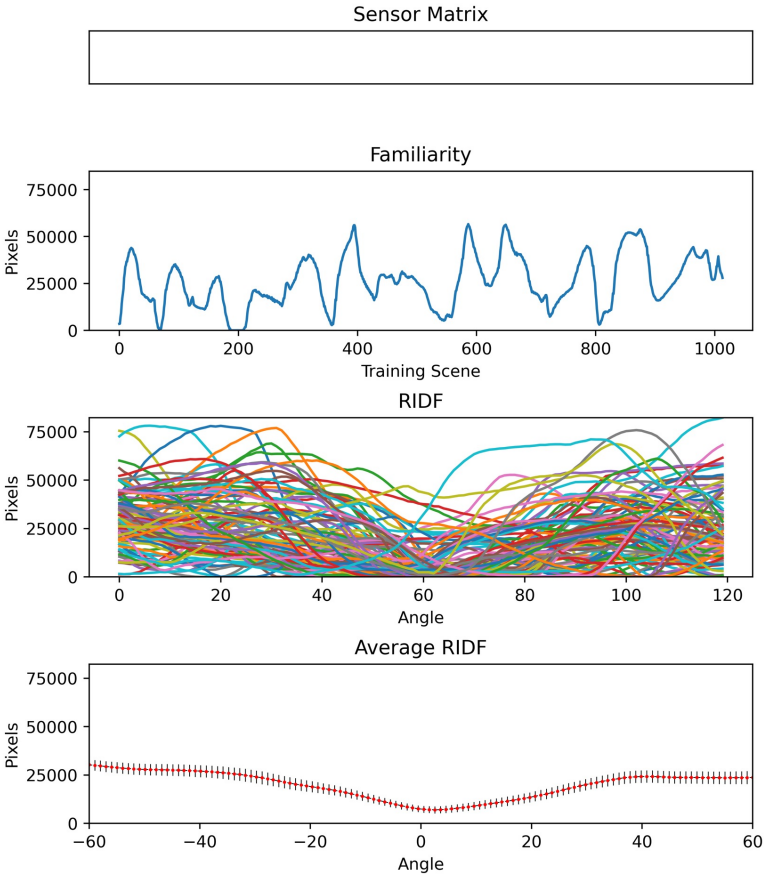


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3171.08; RMSD/dist: 7.928; TD: 25129; p90: 96; p50: 64; complete: 0

0%

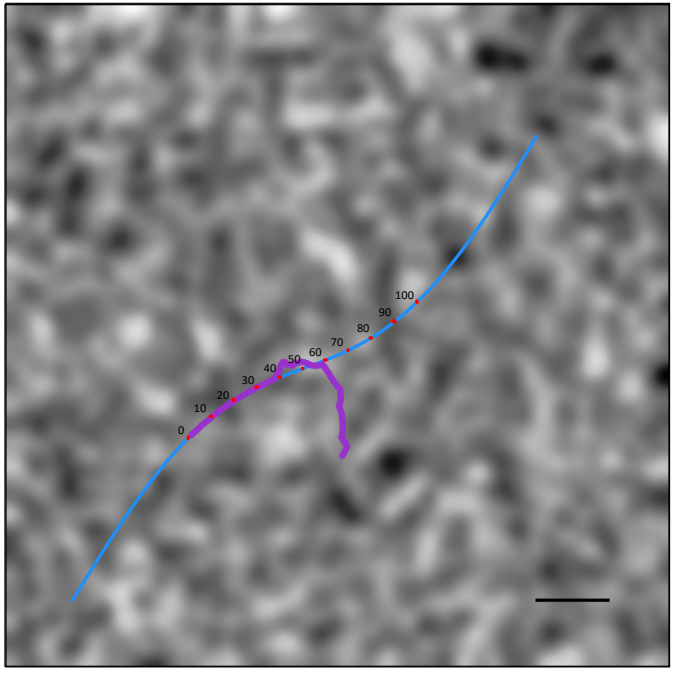


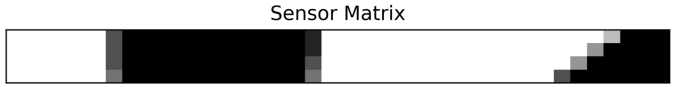


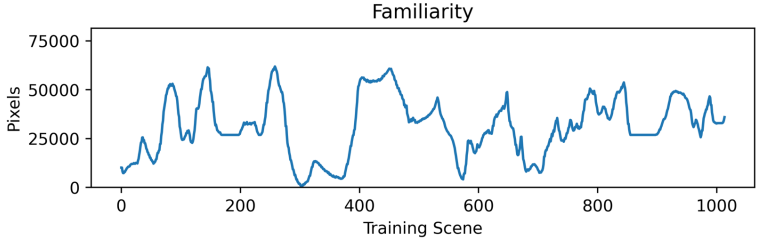
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

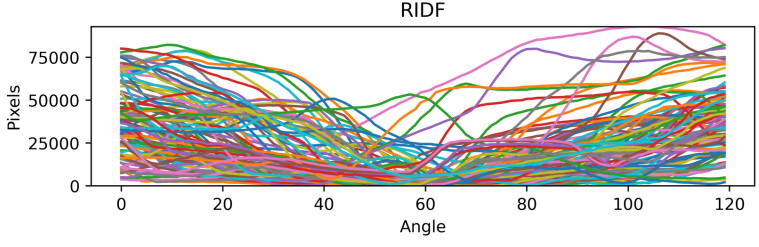
Navigation stats: RMSD error: 7321.63; RMSD/dist: 18.304; TD: 23368; p90: 102; p50: 38; complete: 0

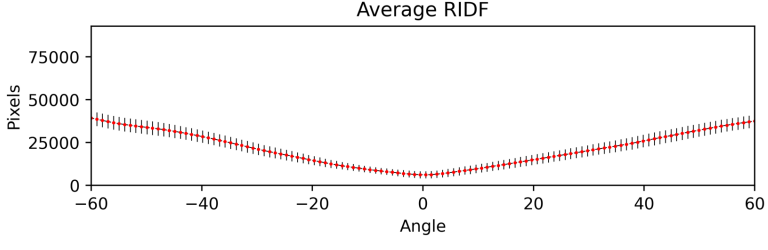
40%







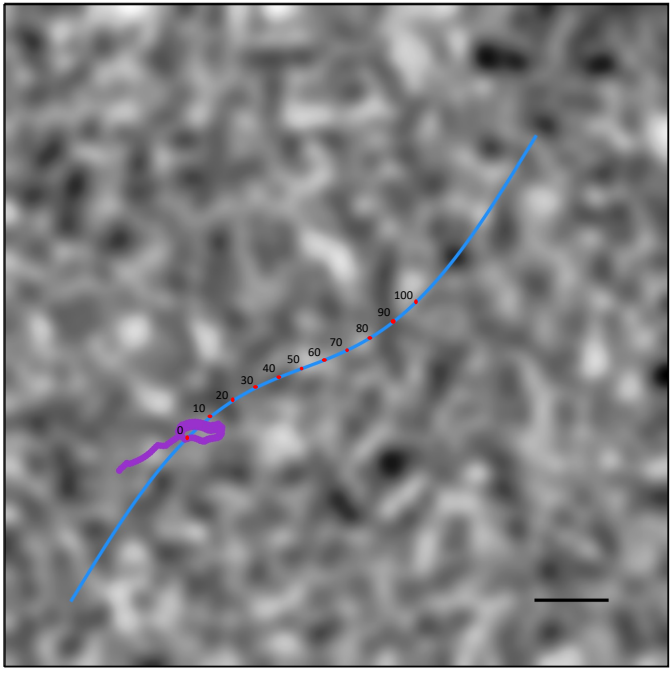


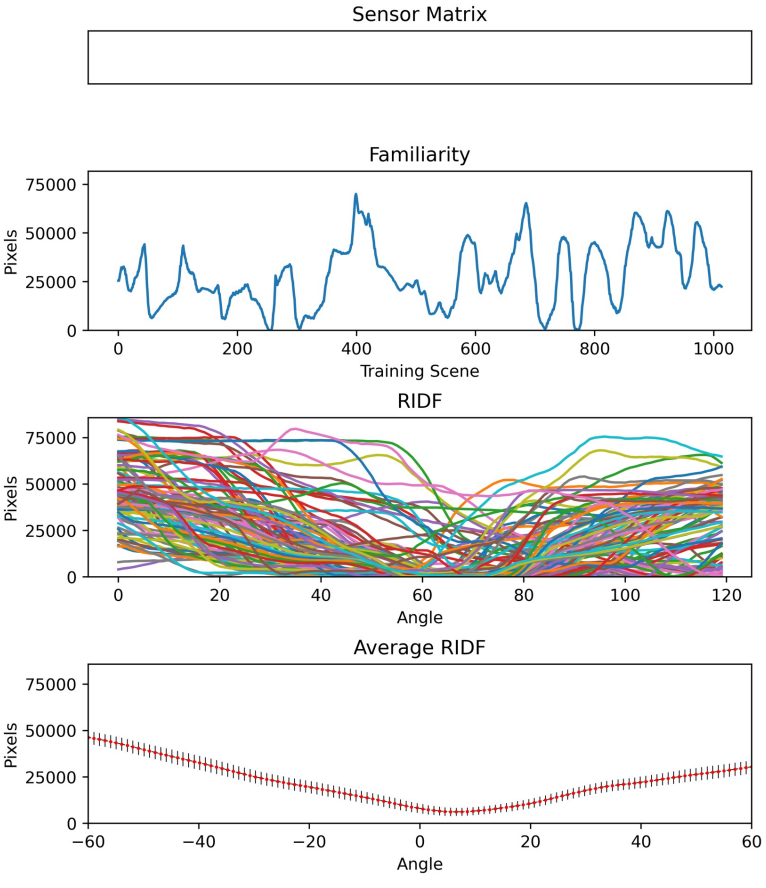


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3184.97; RMSD/dist: 7.962; TD: 24875; p90: 80; p50: 52; complete: 0

0%

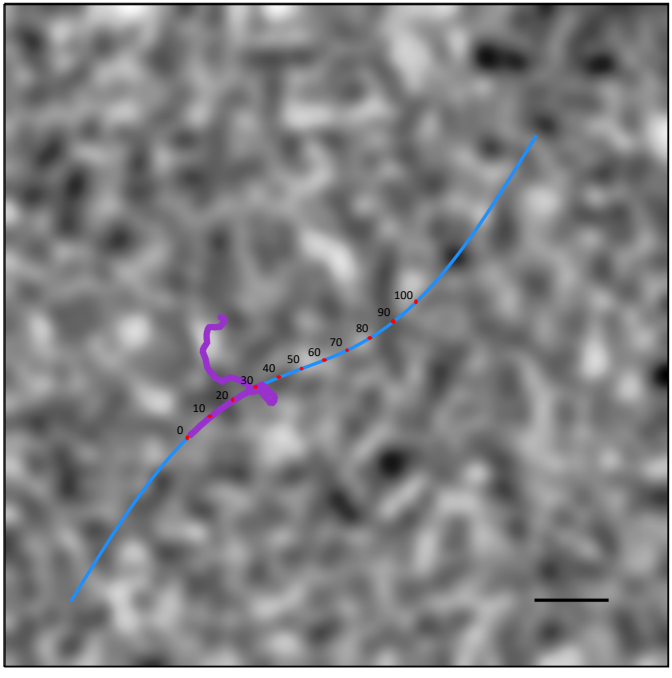


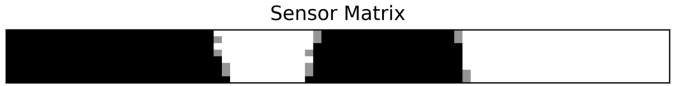


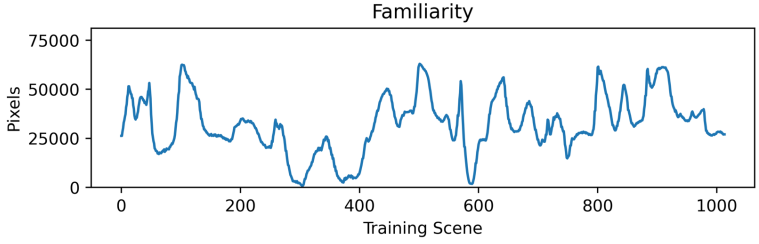
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

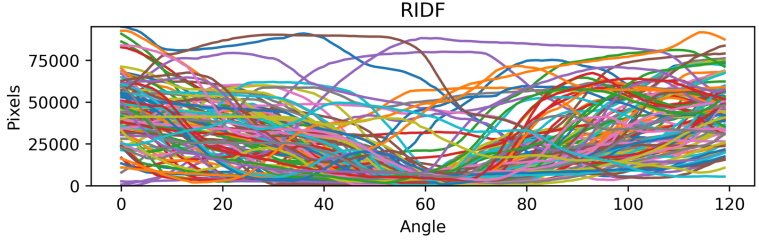
Navigation stats: RMSD error: 1896.93; RMSD/dist: 4.742; TD: 23567; p90: 66; p50: 34; complete: 0

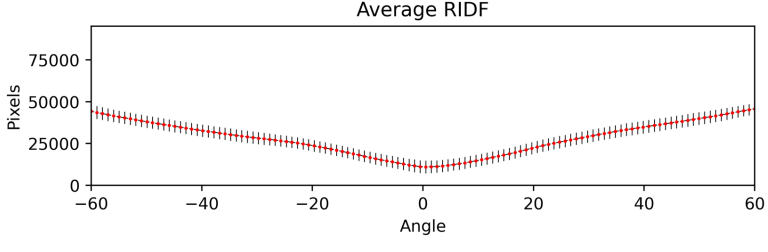
30%







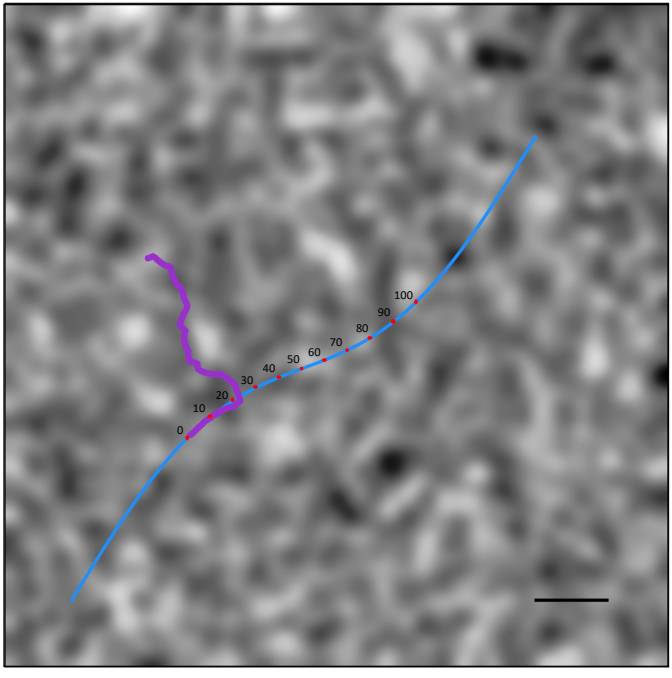


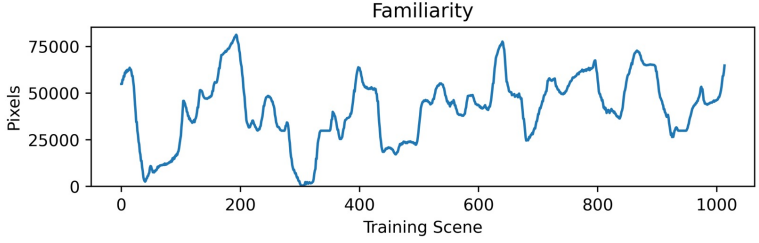


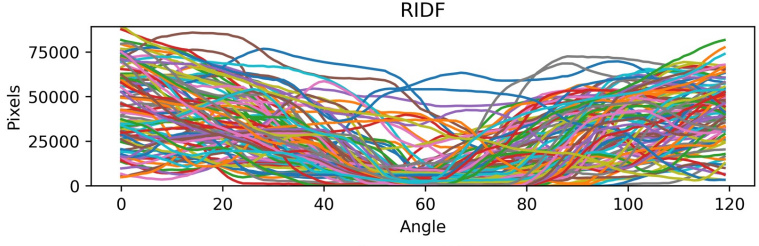
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

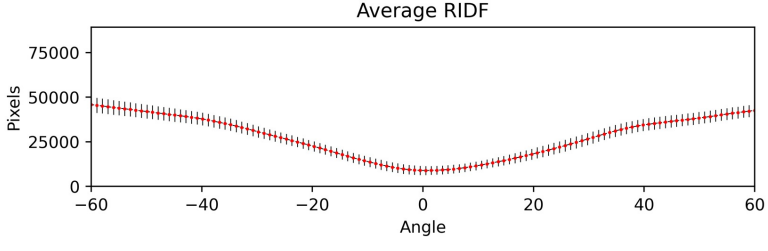
Navigation stats: RMSD error: 3479.74; RMSD/dist: 8.699; TD: 21546; p90: 70; p50: 34; complete: 0

10%



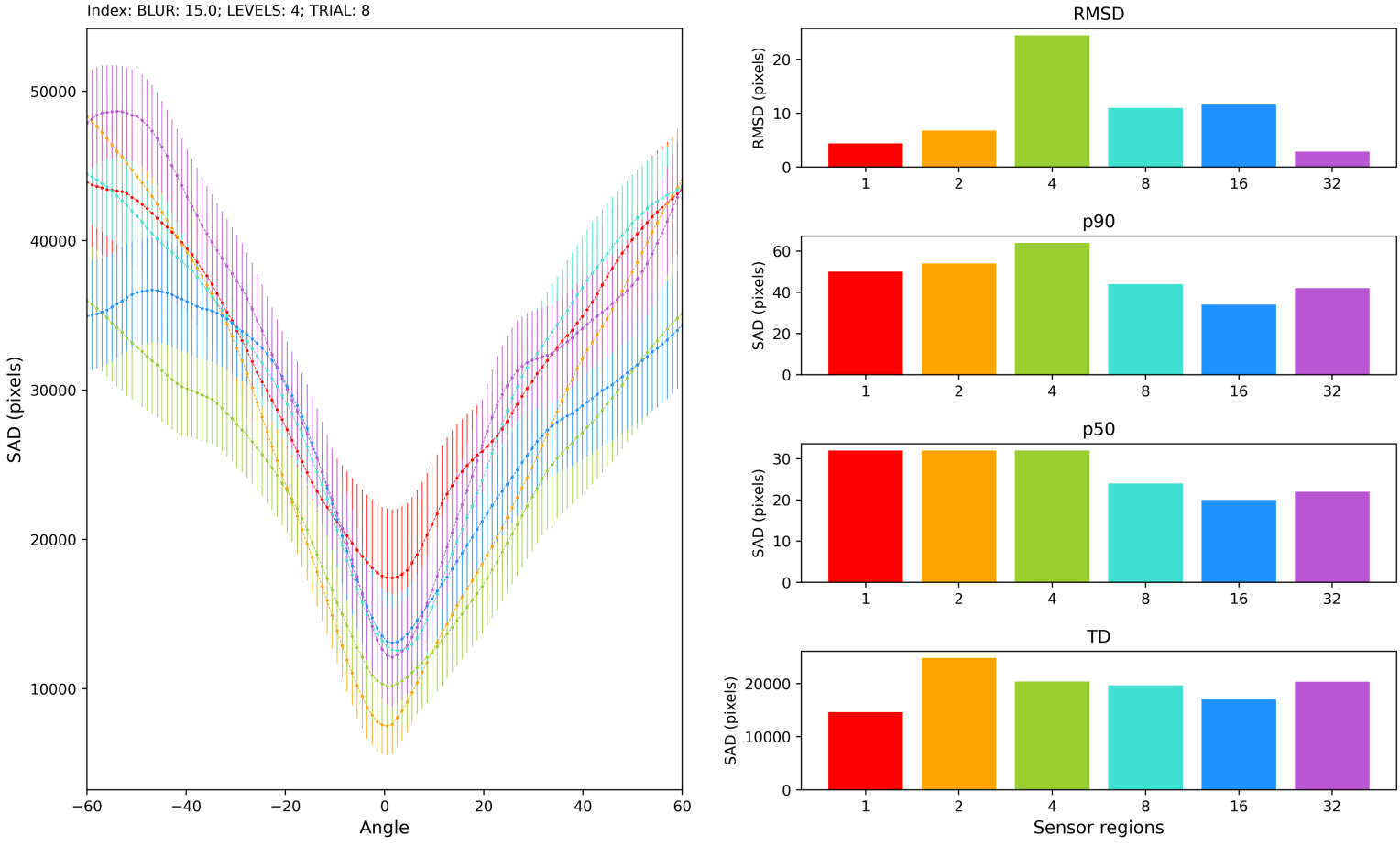




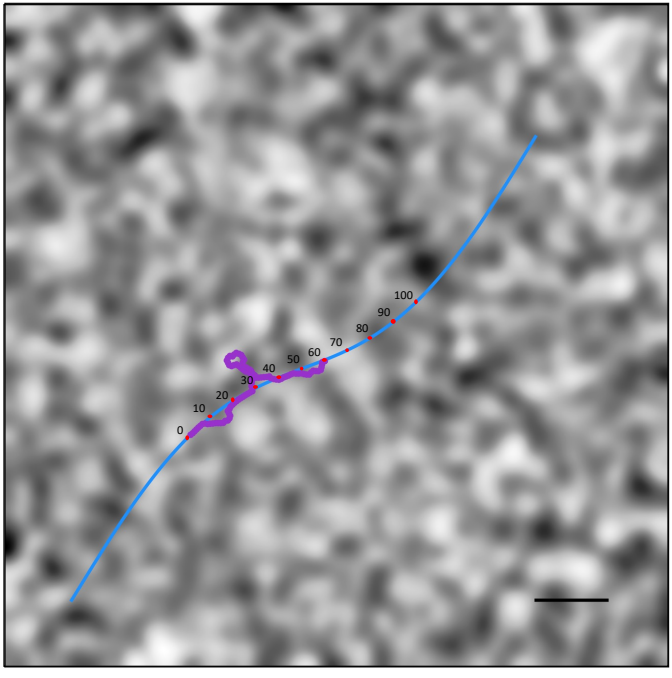


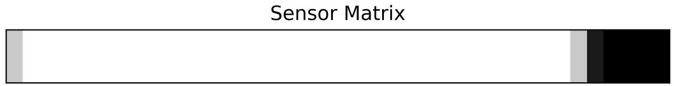
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

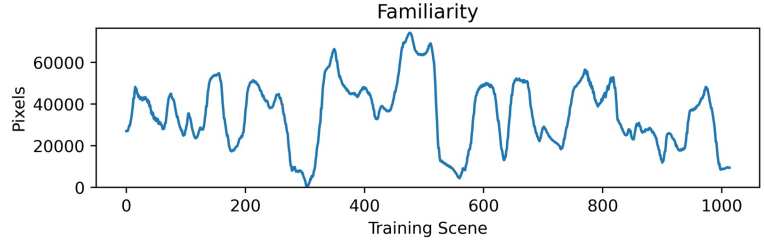
Navigation stats: RMSD error: 9614.37; RMSD/dist: 24.036; TD: 23860; p90: 60; p50: 36; complete: 0

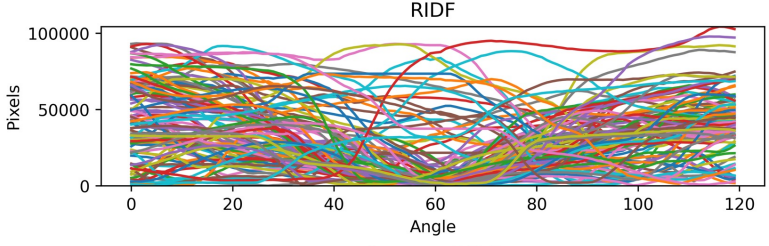

Index: BLUR: 15.0; LEVELS: 4; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

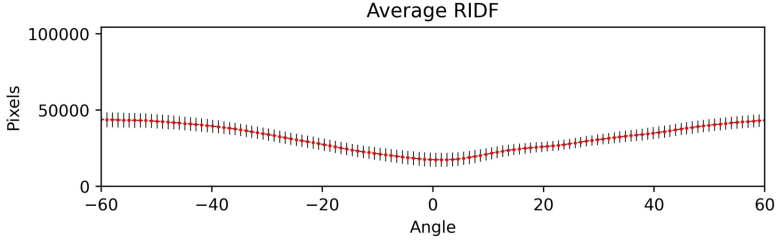
20%







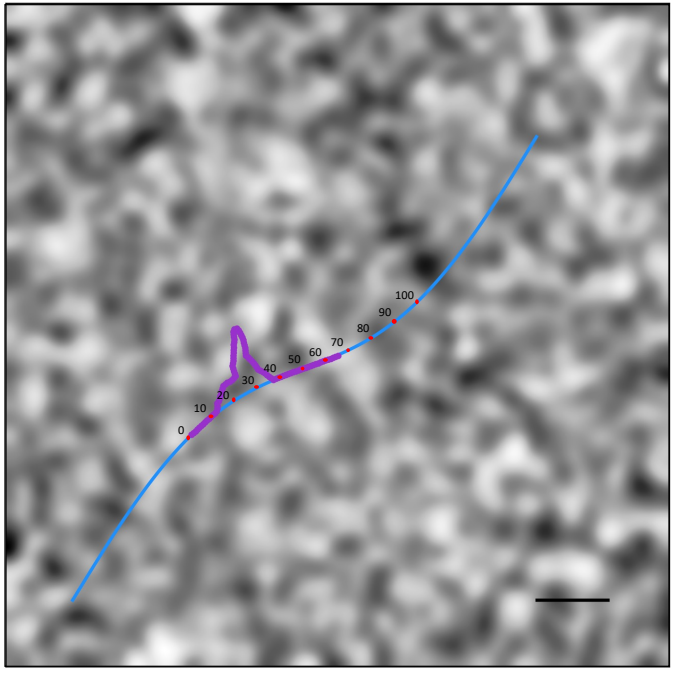


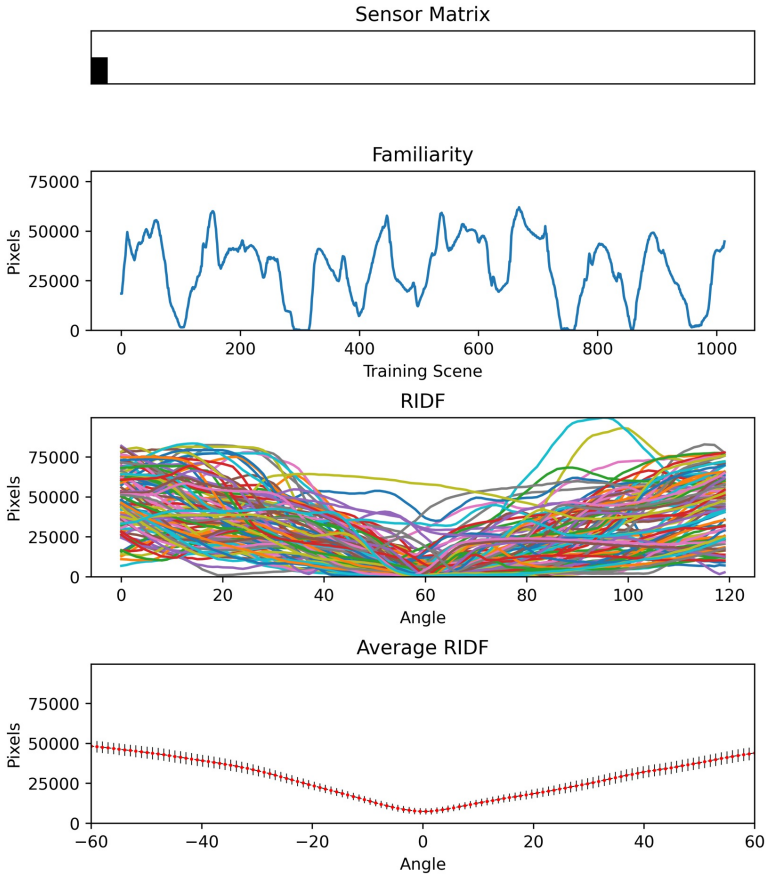


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1755.87; RMSD/dist: 4.390; TD: 14631; p90: 50; p50: 32; complete: 0

30%

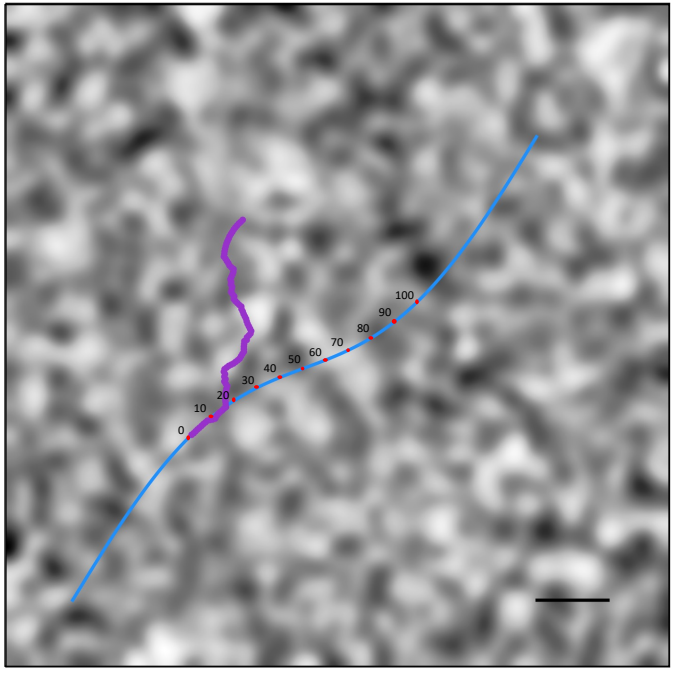


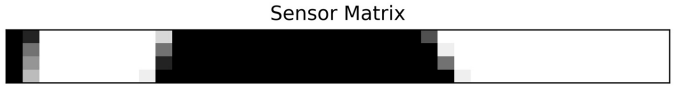


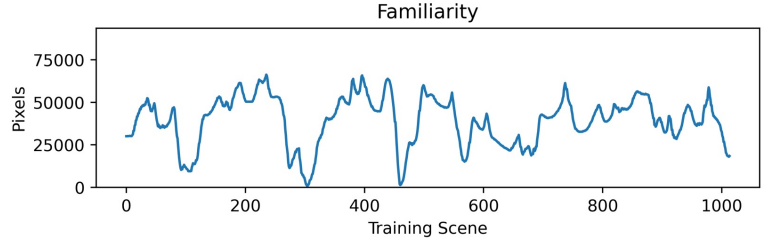
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

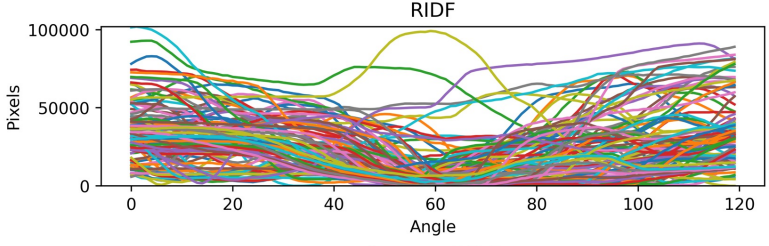
Navigation stats: RMSD error: 2715.45; RMSD/dist: 6.789; TD: 24843; p90: 54; p50: 32; complete: 0

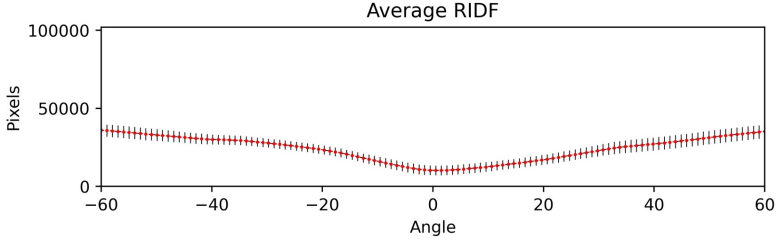
10%







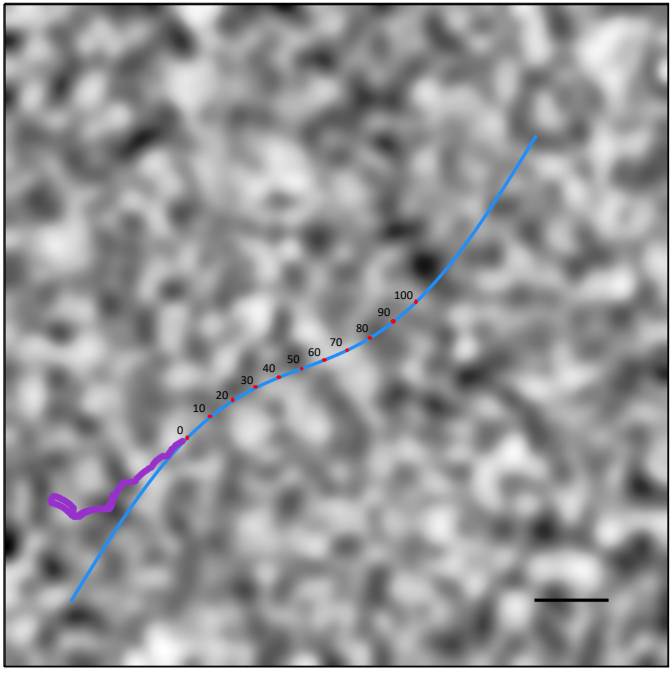


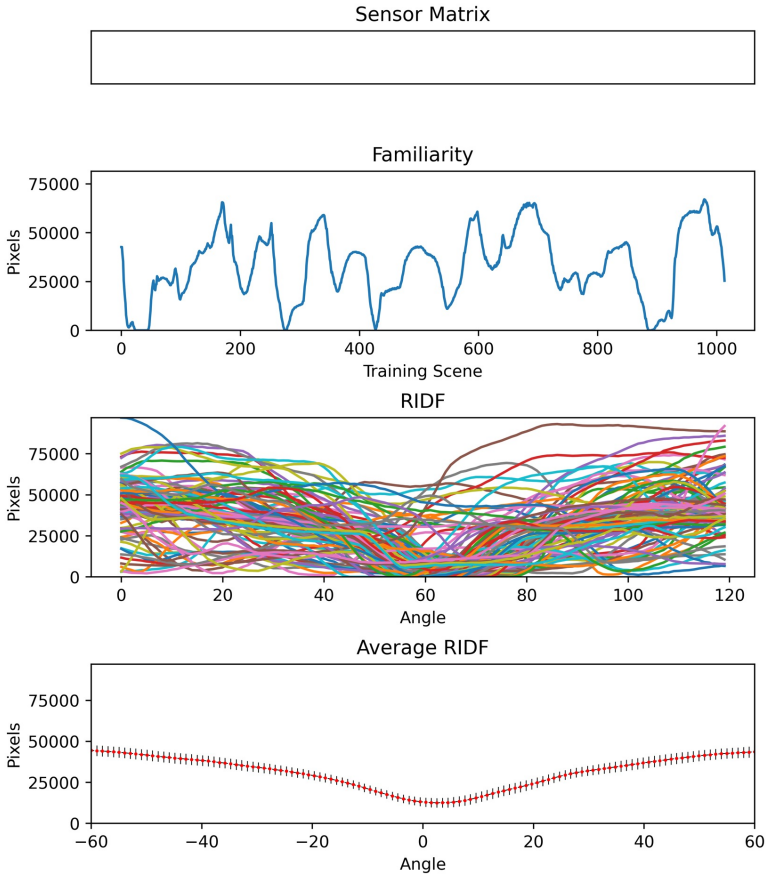


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 9797.38; RMSD/dist: 24.493; TD: 20396; p90: 64; p50: 32; complete: 0

0%

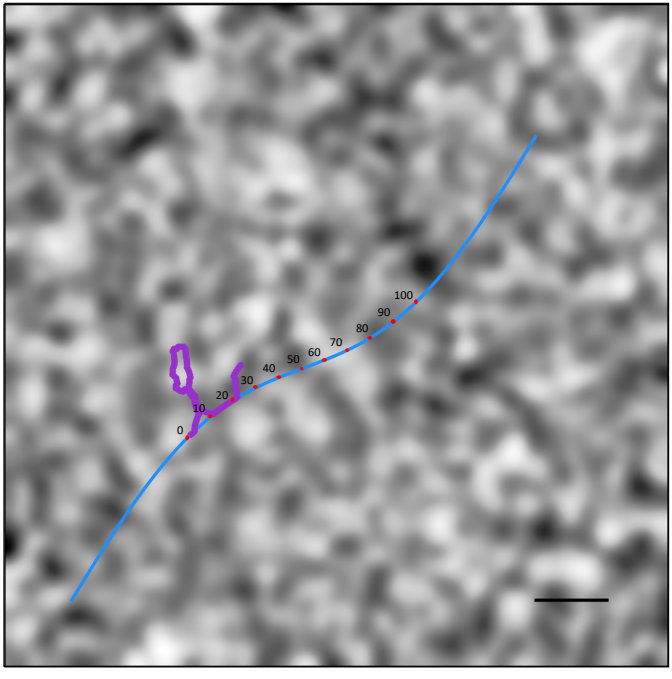


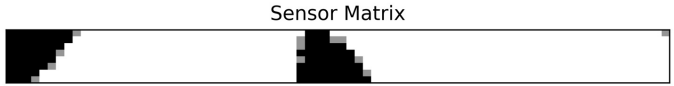


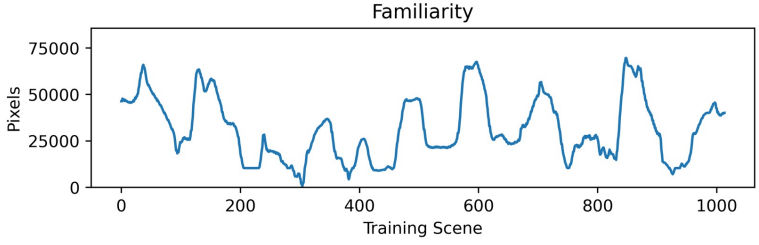
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

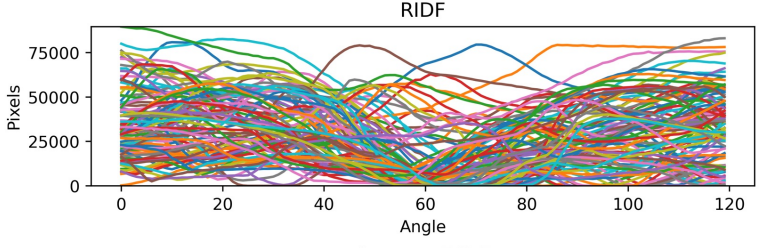
Navigation stats: RMSD error: 4397.22; RMSD/dist: 10.993; TD: 19704; p90: 44; p50: 24; complete: 0

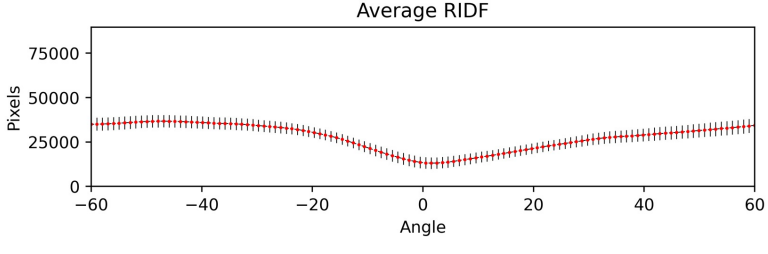
10%







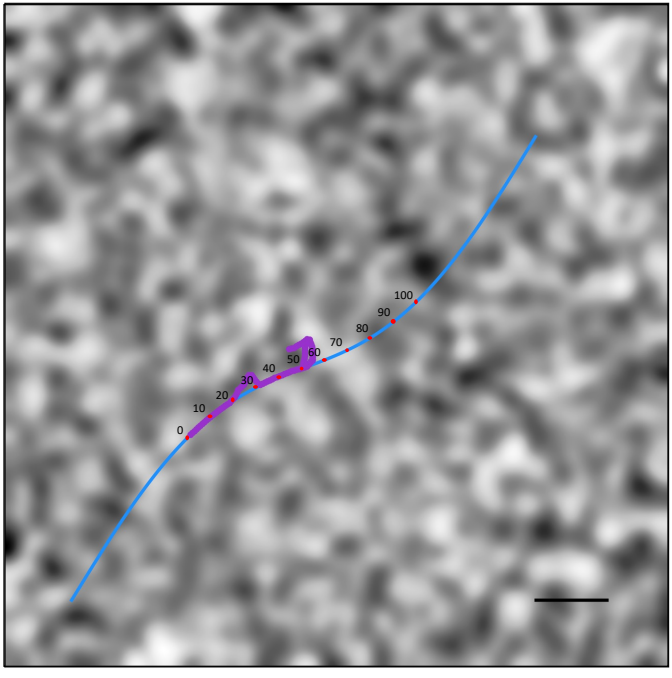


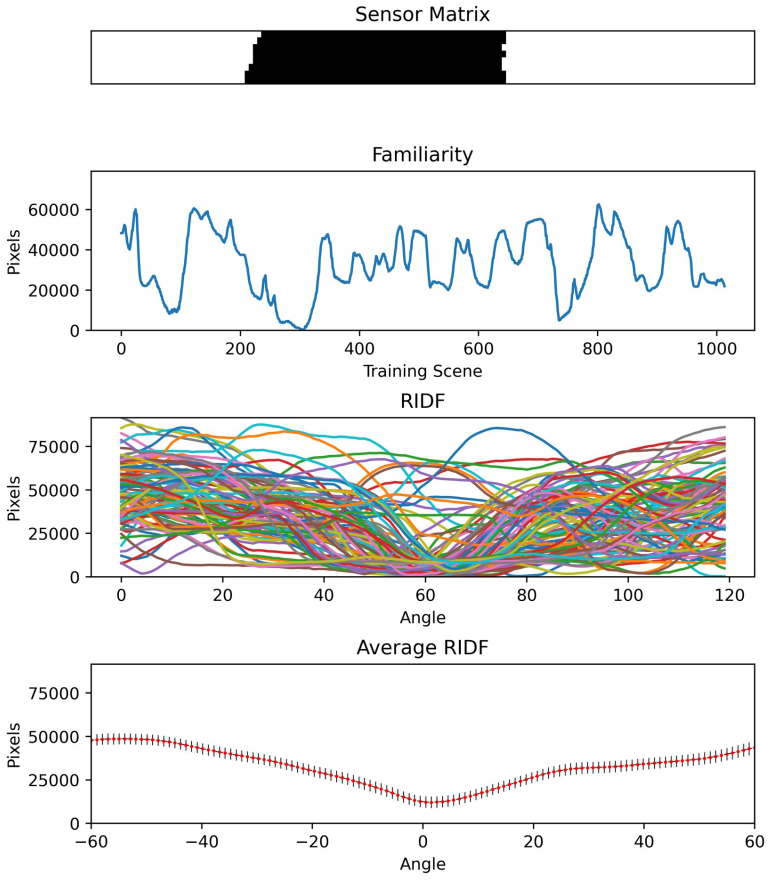


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 4648.30; RMSD/dist: 11.621; TD: 17027; p90: 34; p50: 20; complete: 0

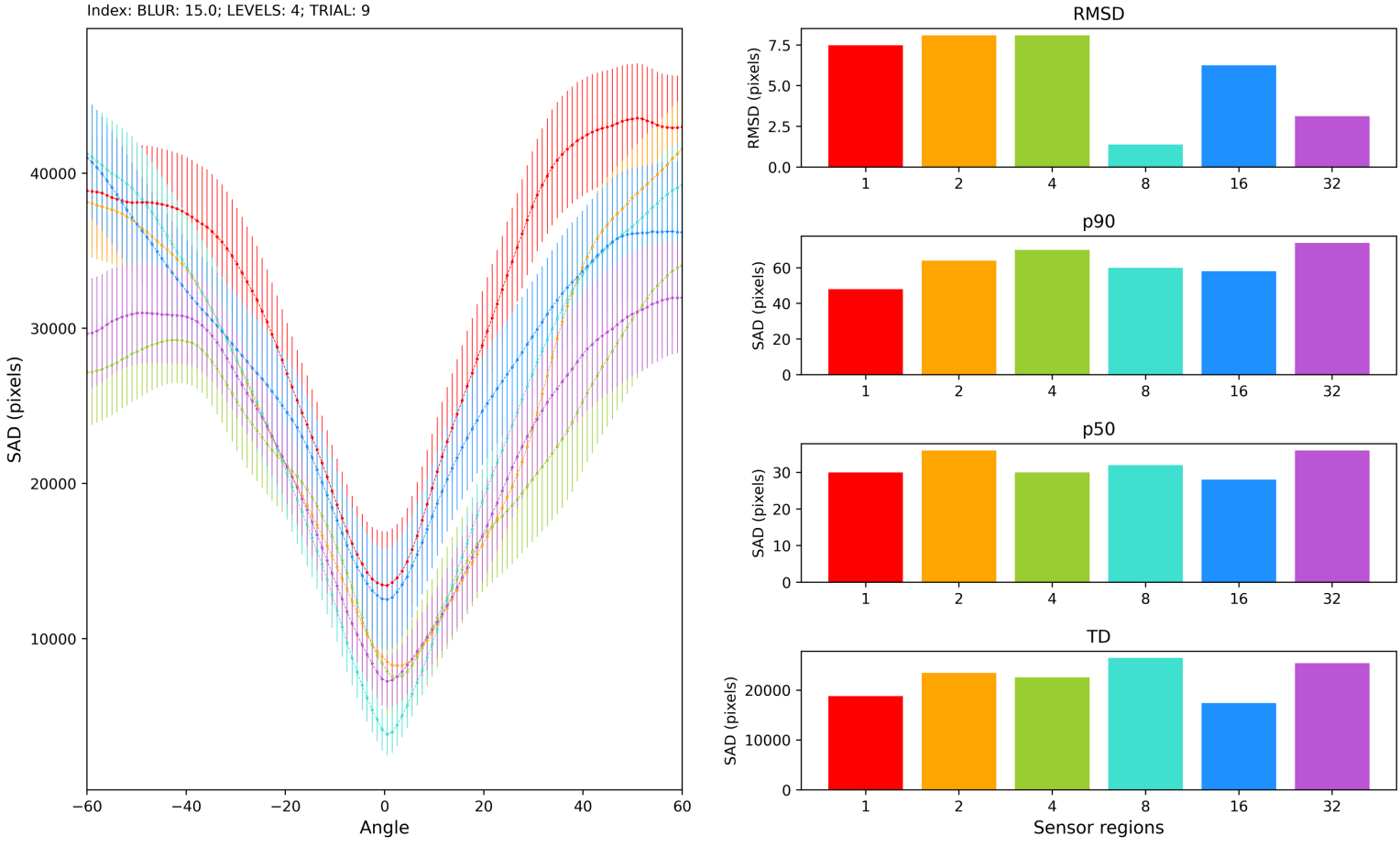
40%



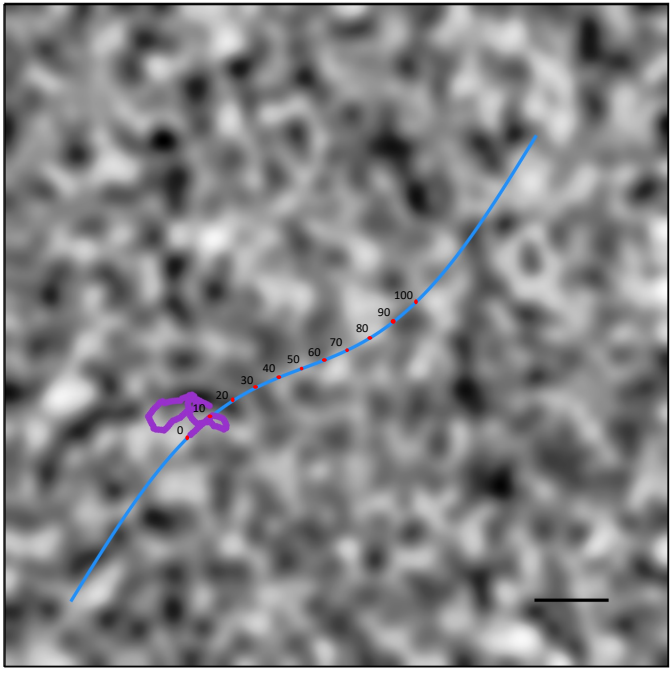


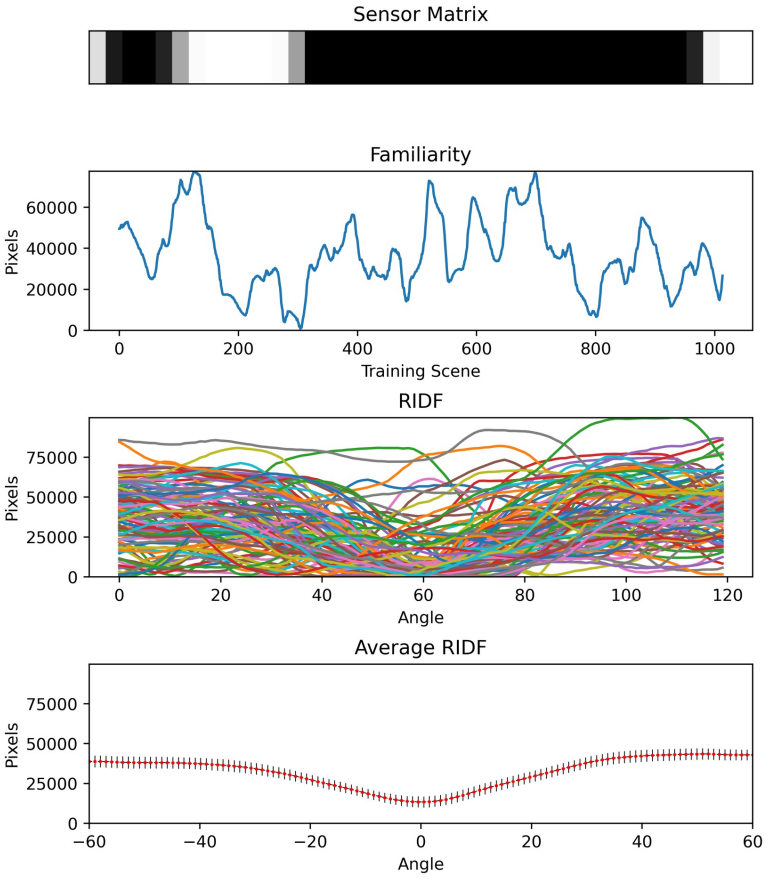
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1146.95; RMSD/dist: 2.867; TD: 20369; p90: 42; p50: 22; complete: 0


Index: BLUR: 15.0; LEVELS: 4; TRIAL: 9
SAD (pixels)
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
7.5
5.0
2.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
60
40
20
0
p50
30
20
10
TD
20000
10000
Sensor regions

10%

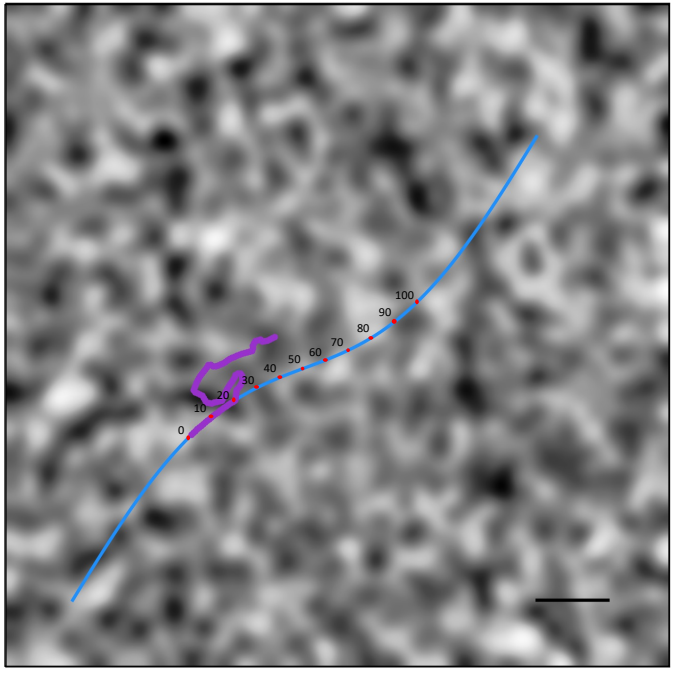


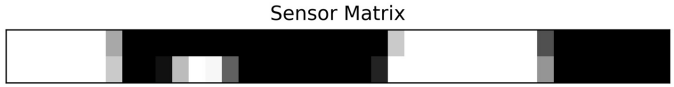


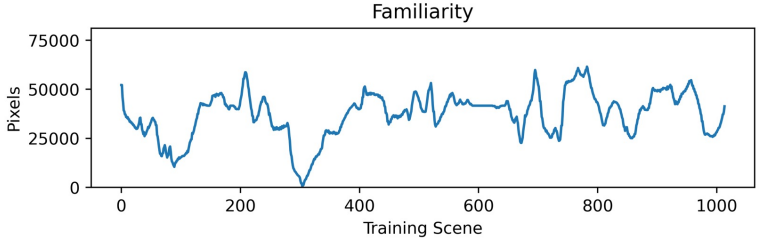
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

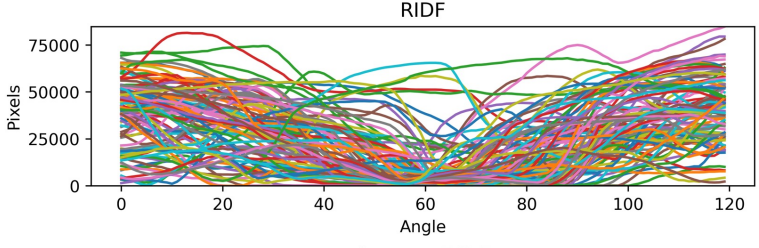
Navigation stats: RMSD error: 2994.63; RMSD/dist: 7.487; TD: 18796; p90: 48; p50: 30; complete: 0

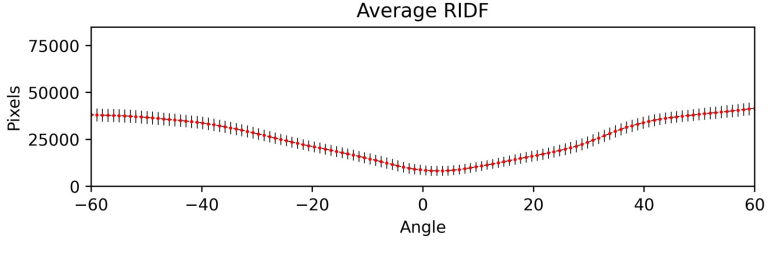
20%







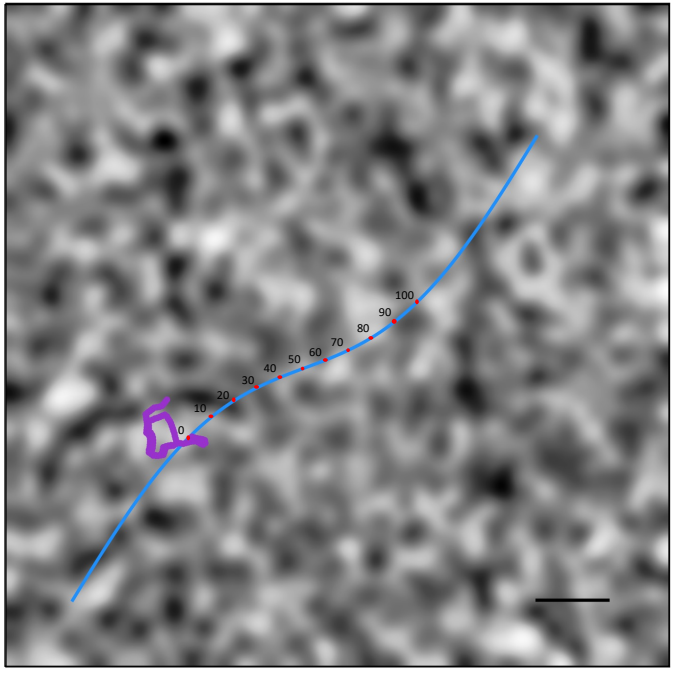


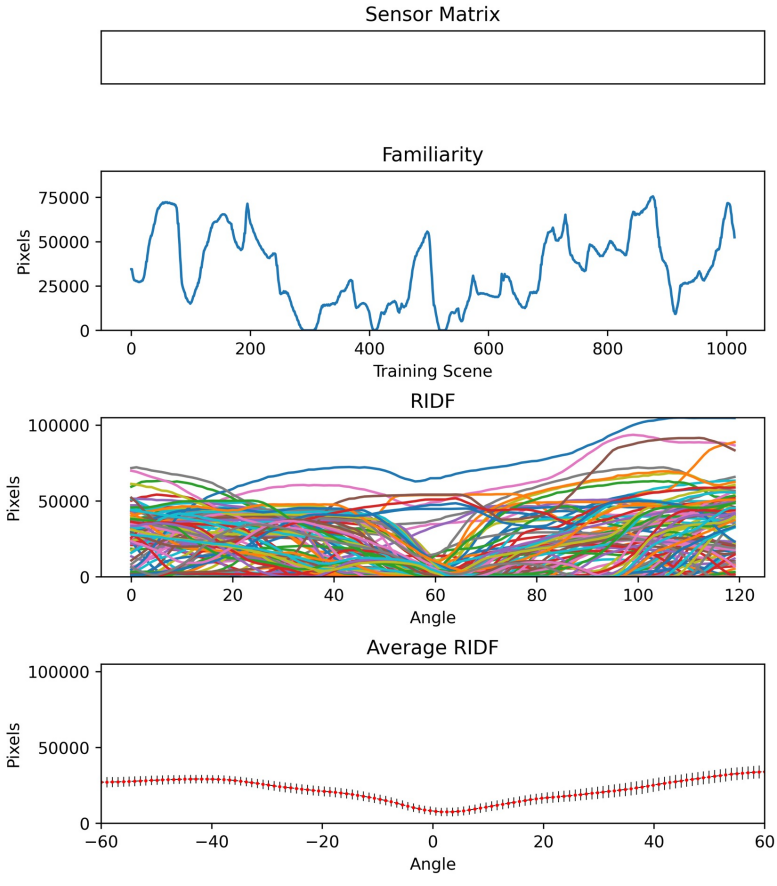


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3235.04; RMSD/dist: 8.088; TD: 23439; p90: 64; p50: 36; complete: 0

0%

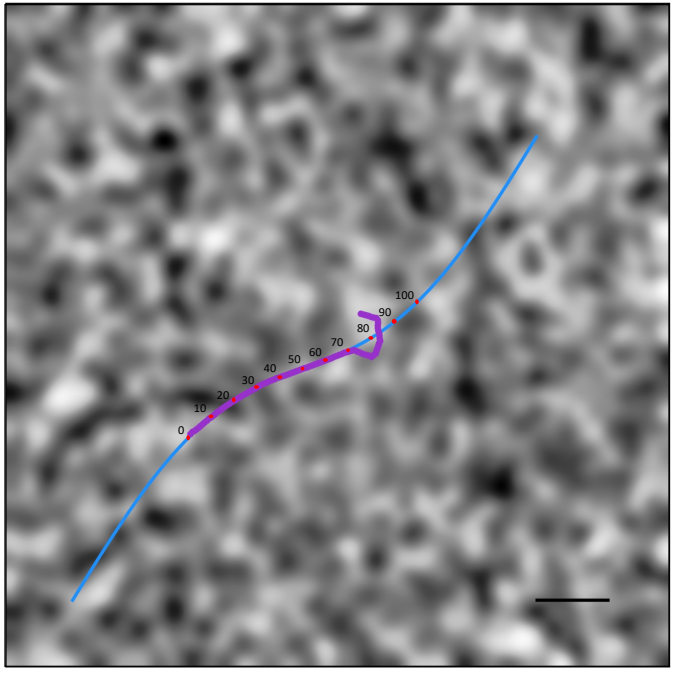


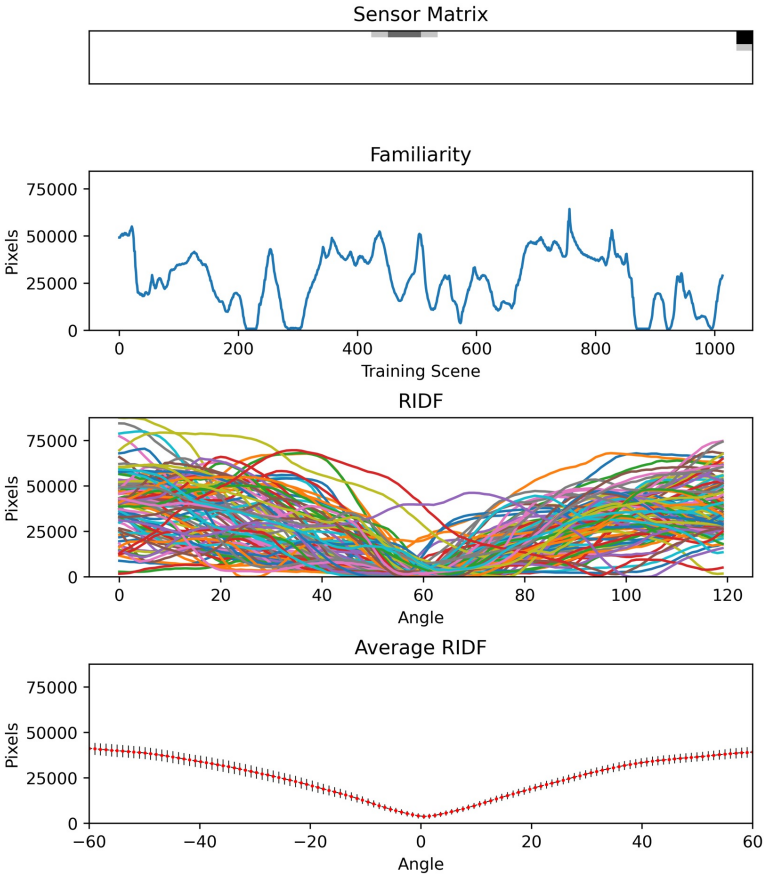


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3239.82; RMSD/dist: 8.100; TD: 22584; p90: 70; p50: 30; complete: 0

70%

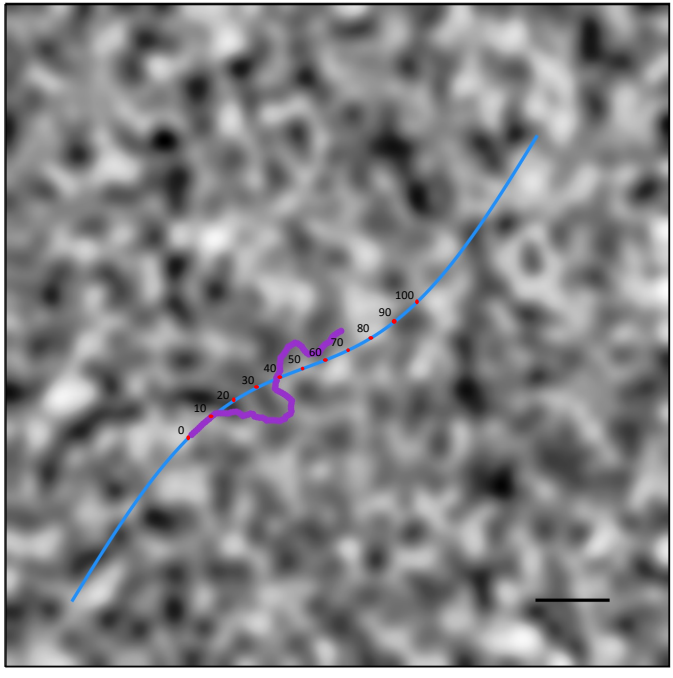


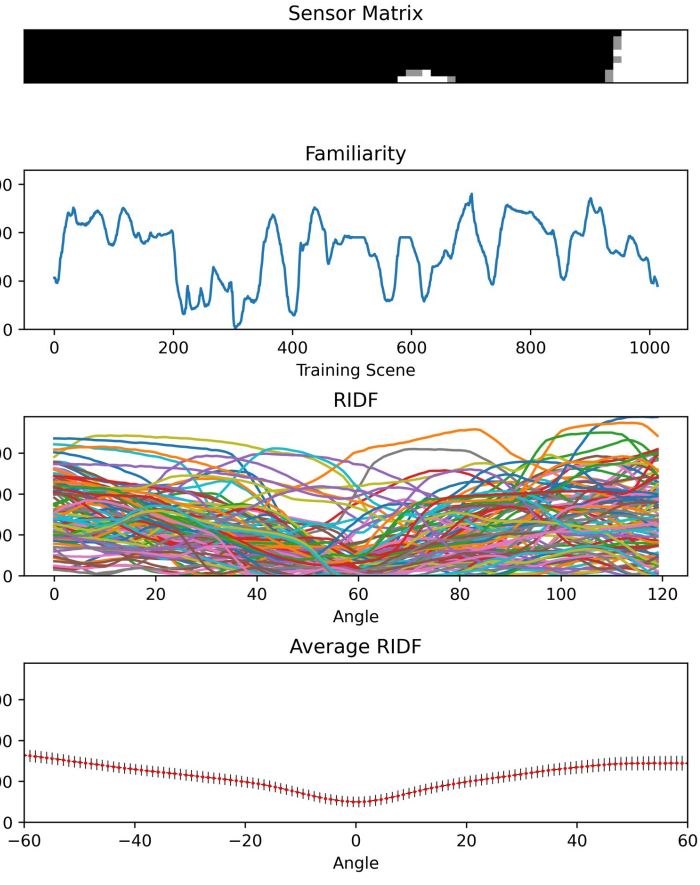


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 555.48; RMSD/dist: 1.389; TD: 26441; p90: 60; p50: 32; complete: 0

10%

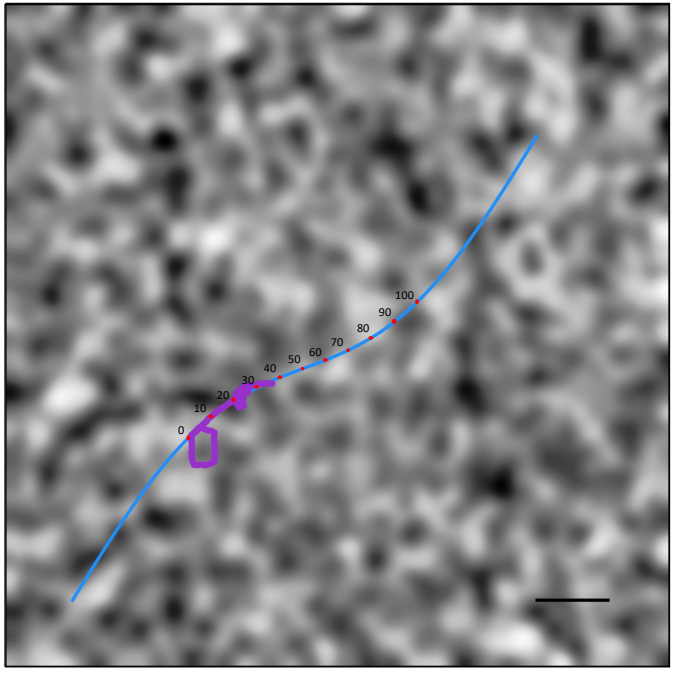


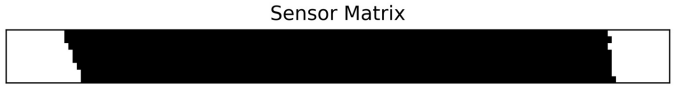


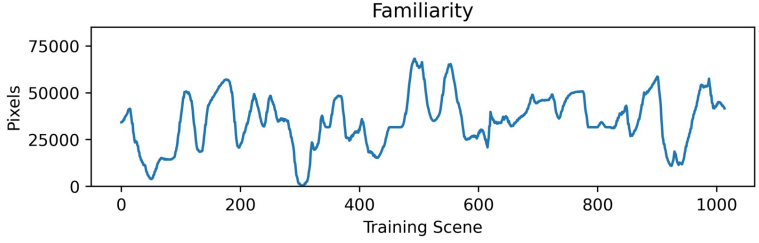
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

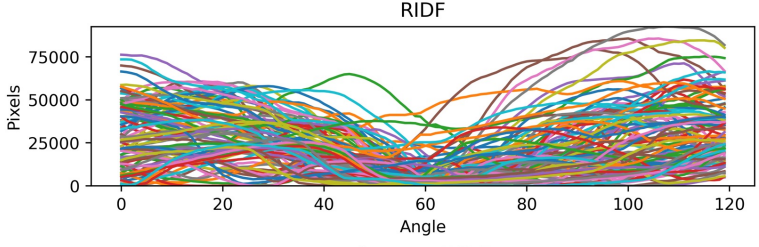
Navigation stats: RMSD error: 2498.05; RMSD/dist: 6.245; TD: 17410; p90: 58; p50: 28; complete: 0

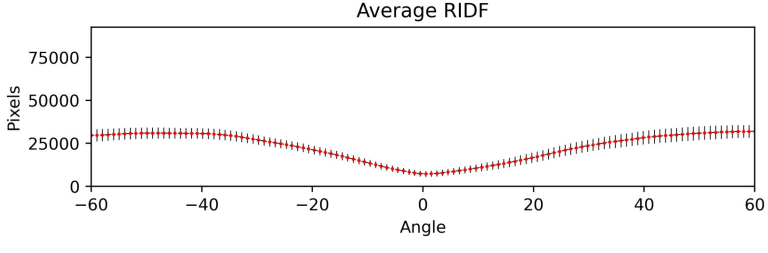
20%





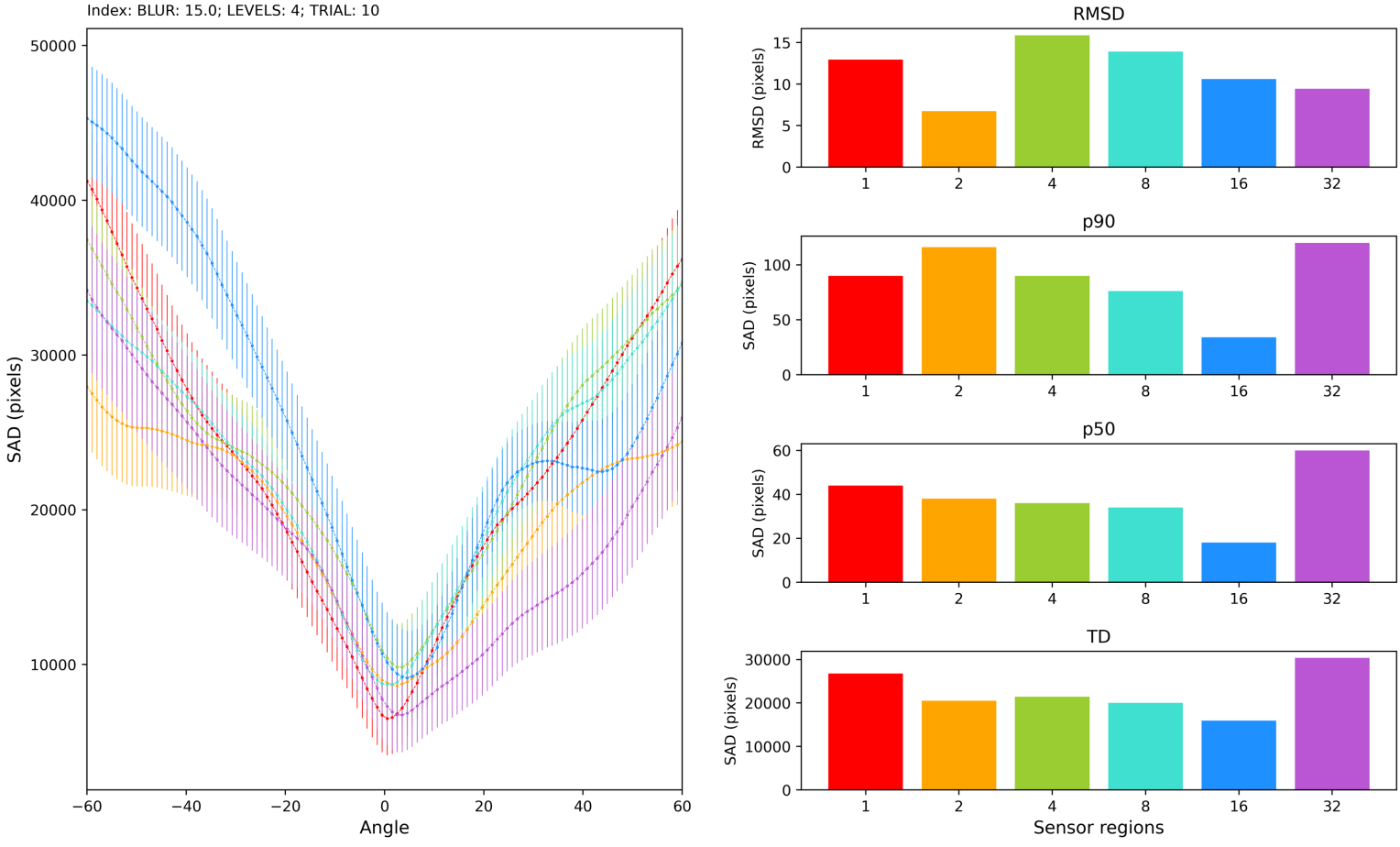




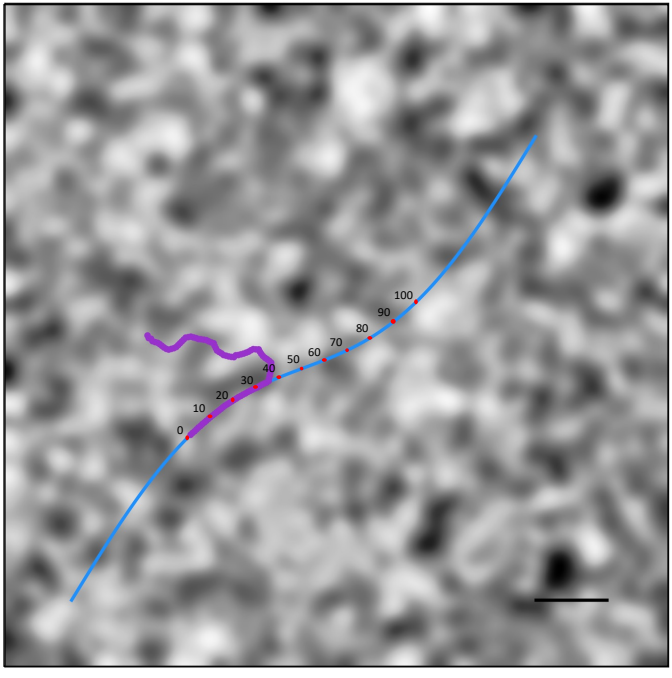


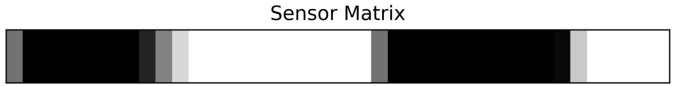
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

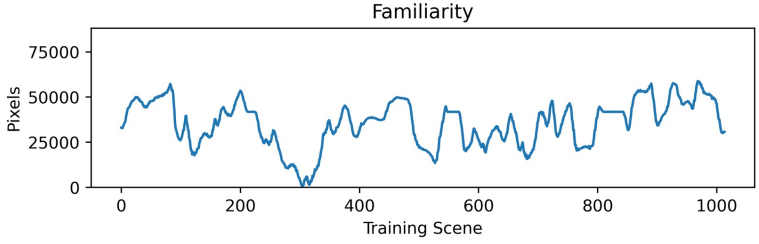
Navigation stats: RMSD error: 1252.07; RMSD/dist: 3.130; TD: 25408; p90: 74; p50: 36; complete: 0

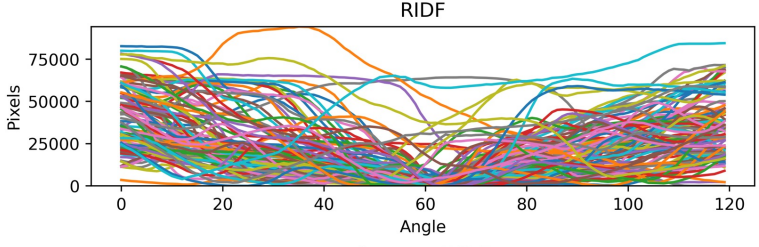

Index: BLUR: 15.0; LEVELS: 4; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

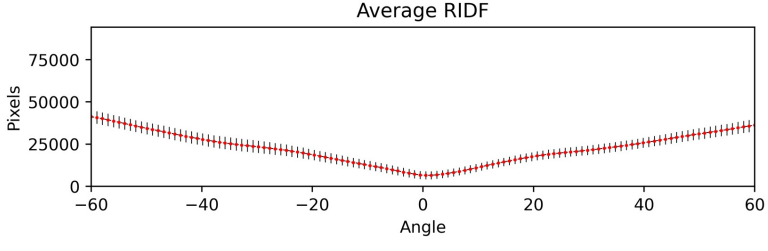
30%







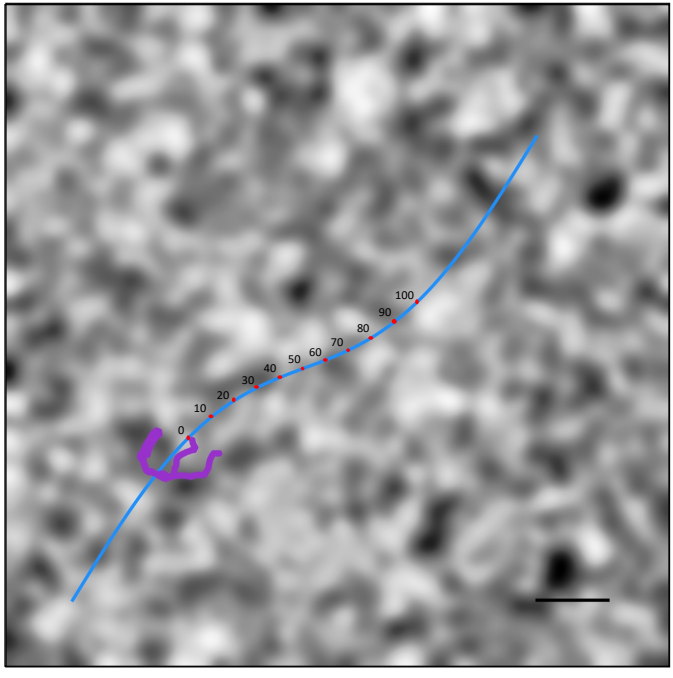


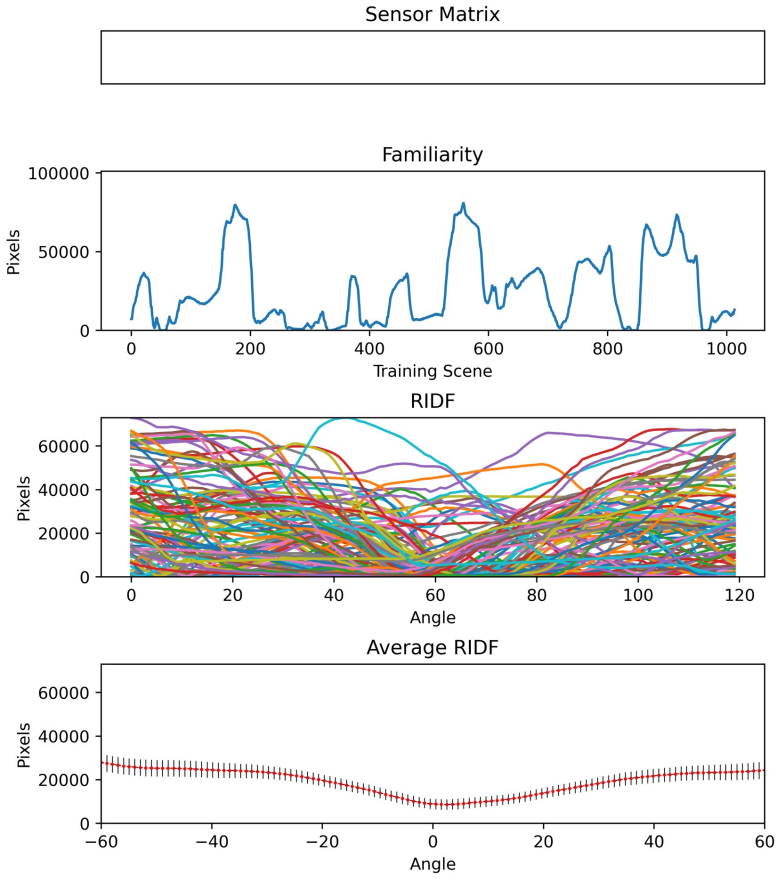


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 5178.86; RMSD/dist: 12.947; TD: 26786; p90: 90; p50: 44; complete: 0

0%

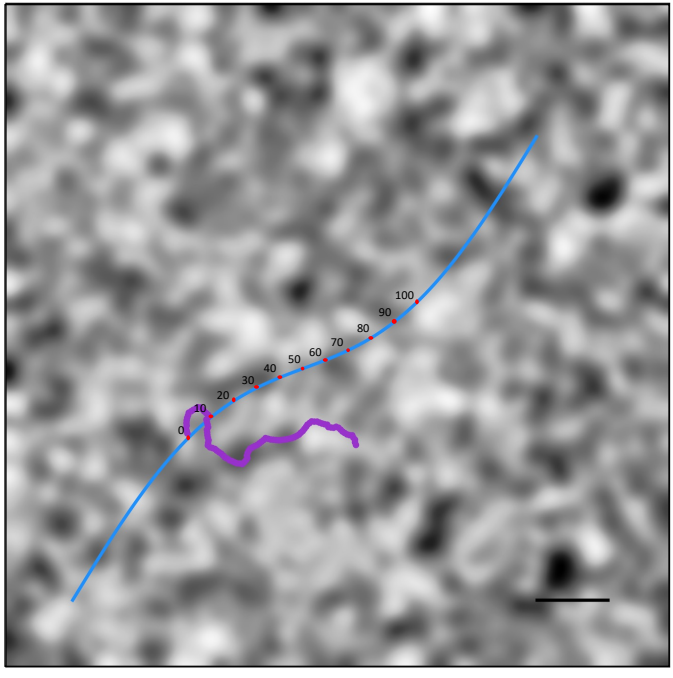


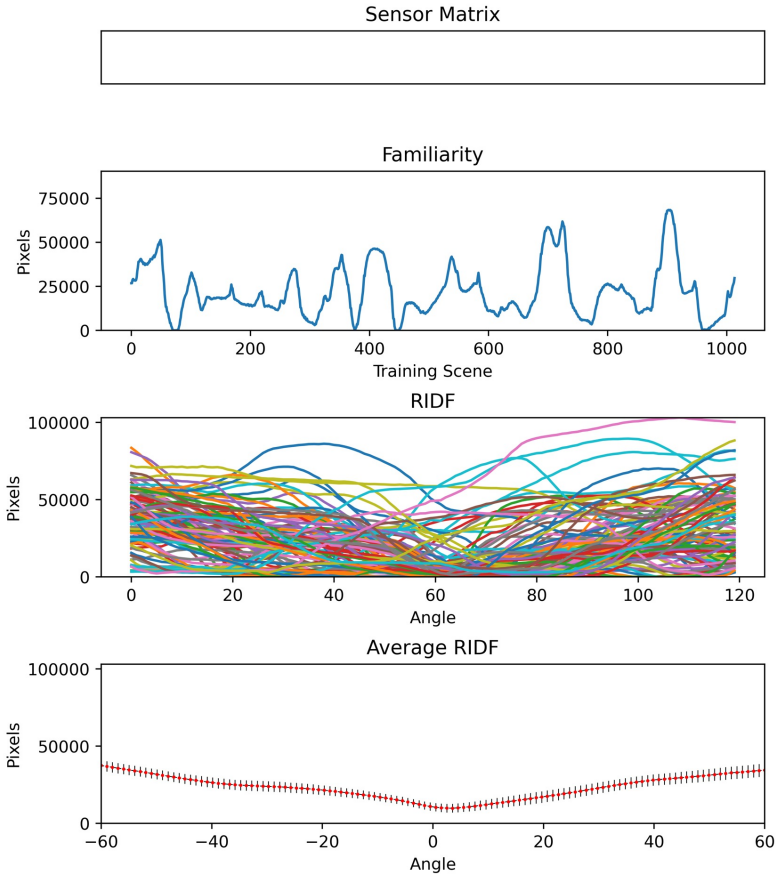


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2691.31; RMSD/dist: 6.728; TD: 20516; p90: 116; p50: 38; complete: 0

0%

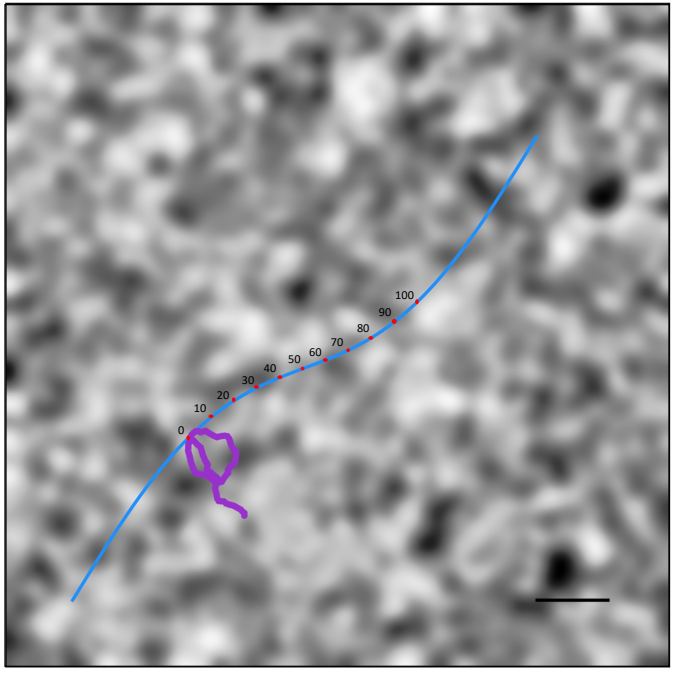


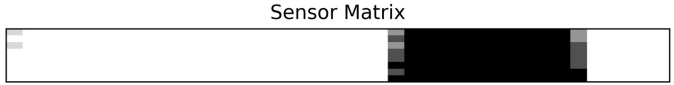


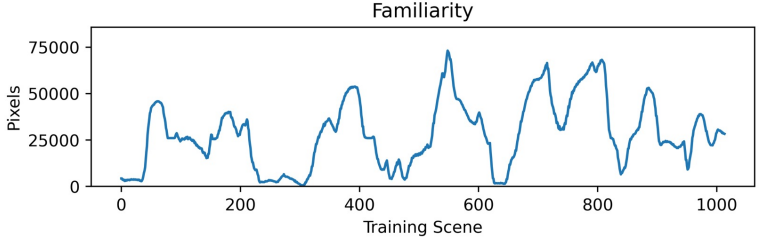
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

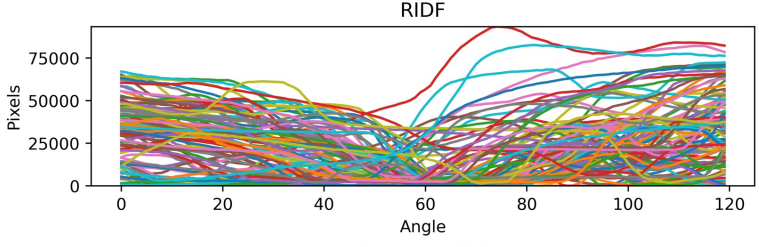
Navigation stats: RMSD error: 6354.24; RMSD/dist: 15.886; TD: 21419; p90: 90; p50: 36; complete: 0

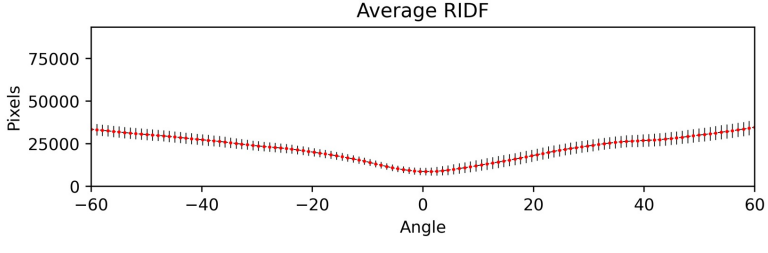
0%







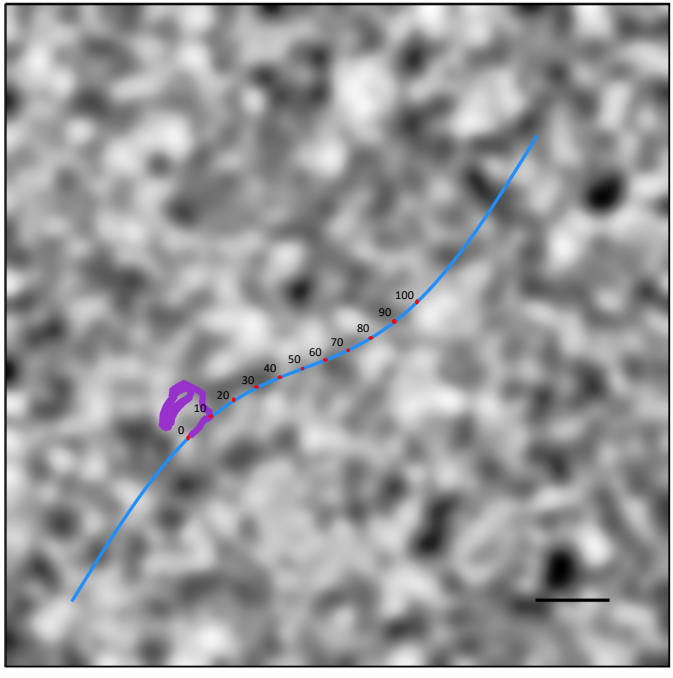


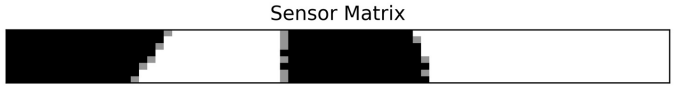


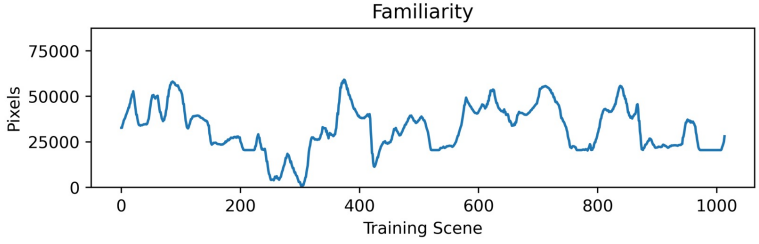
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

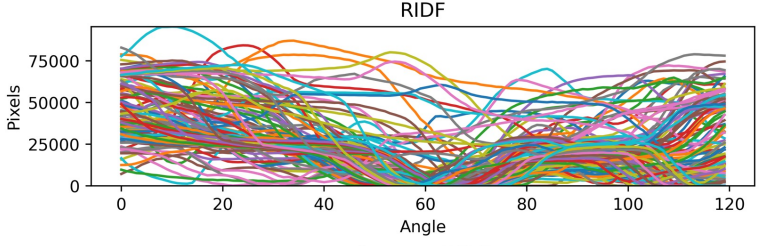
Navigation stats: RMSD error: 5570.54; RMSD/dist: 13.926; TD: 19998; p90: 76; p50: 34; complete: 0

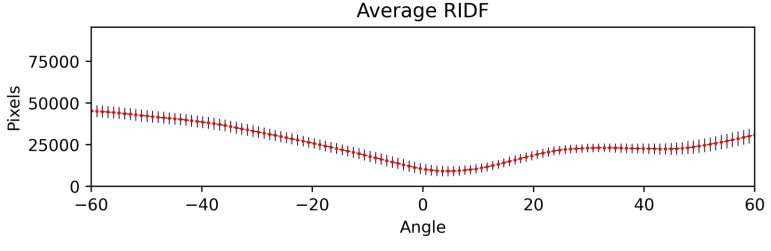
10%







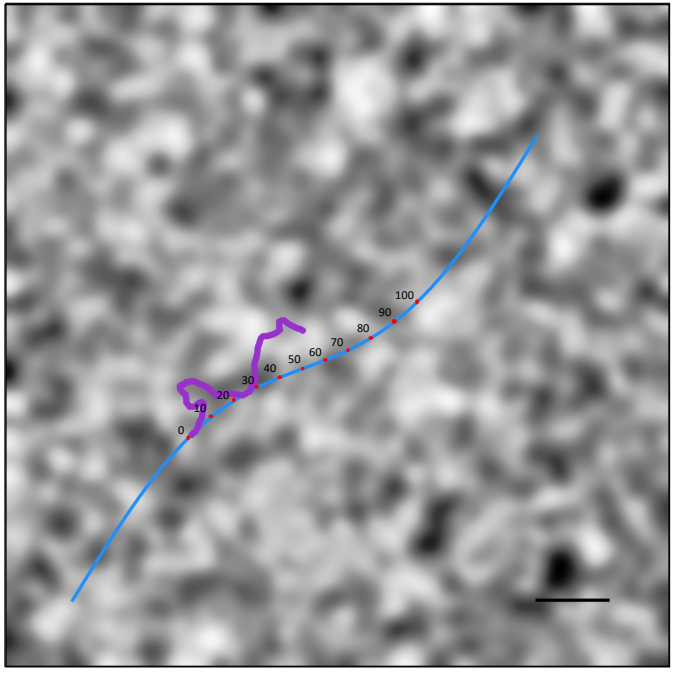


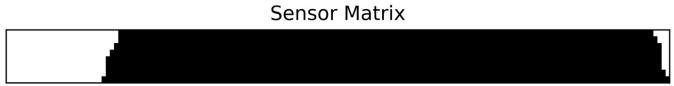


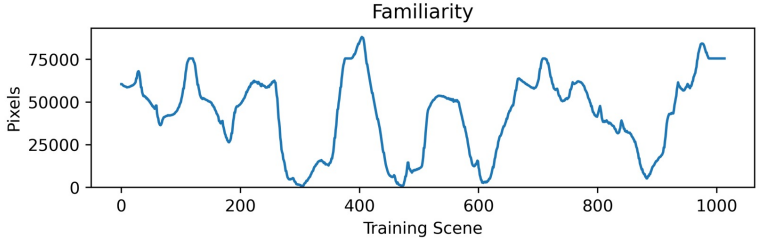
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

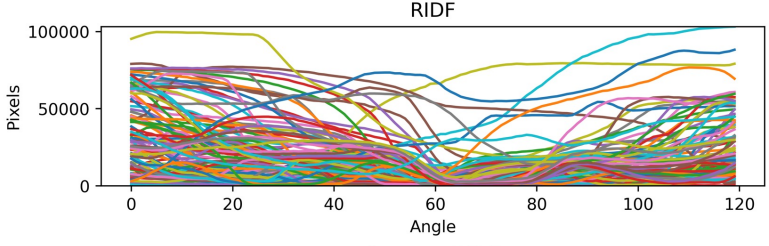
Navigation stats: RMSD error: 4241.82; RMSD/dist: 10.605; TD: 15903; p90: 34; p50: 18; complete: 0

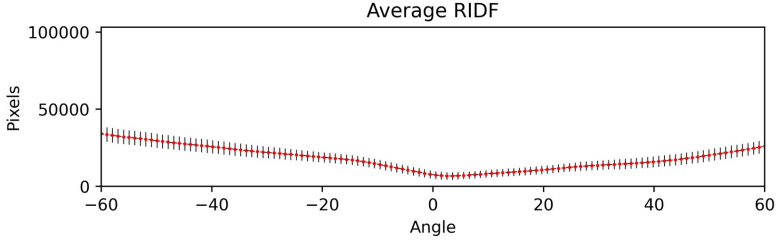
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3773.03; RMSD/dist: 9.433; TD: 30341; p90: 120; p50: 60; complete: 0