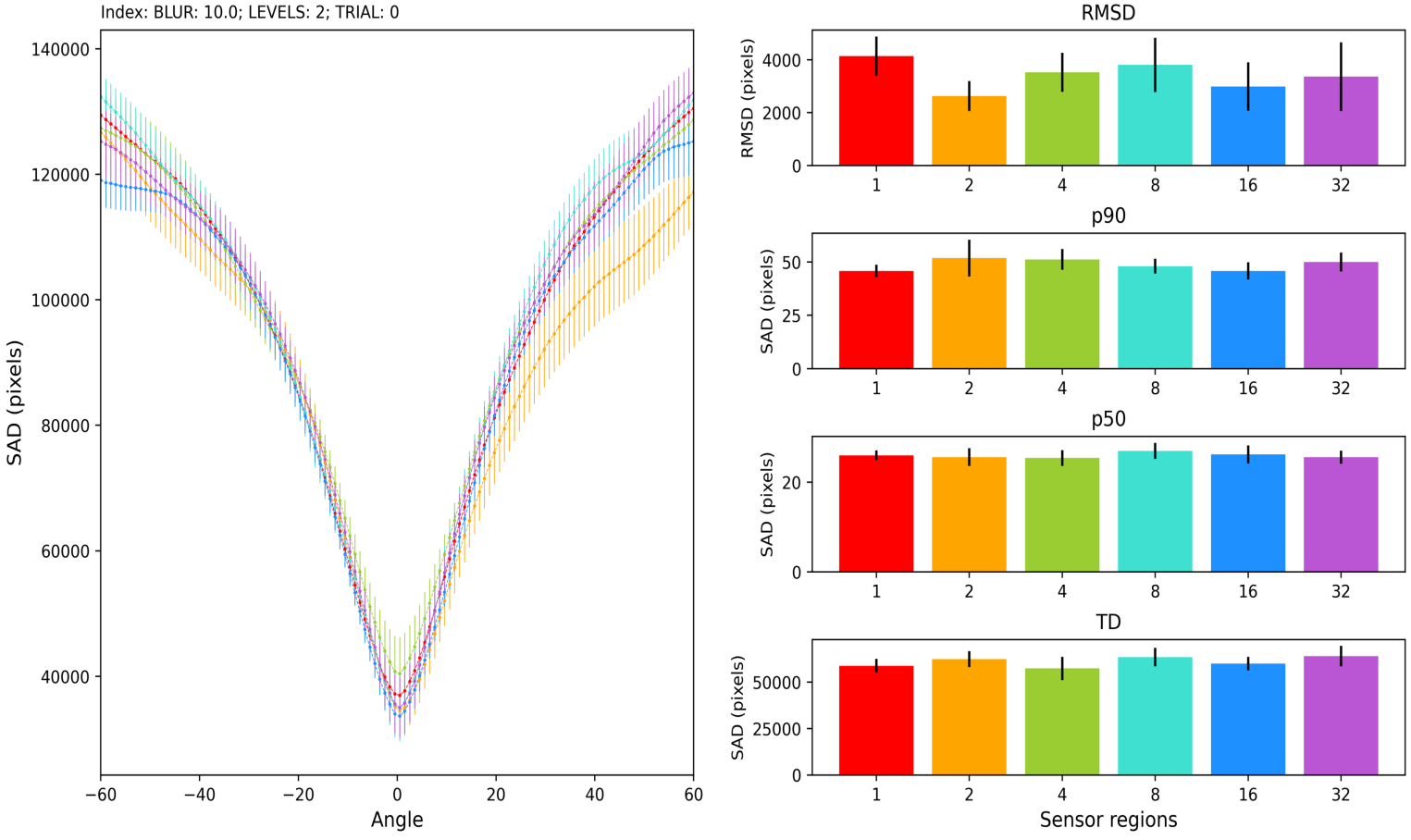
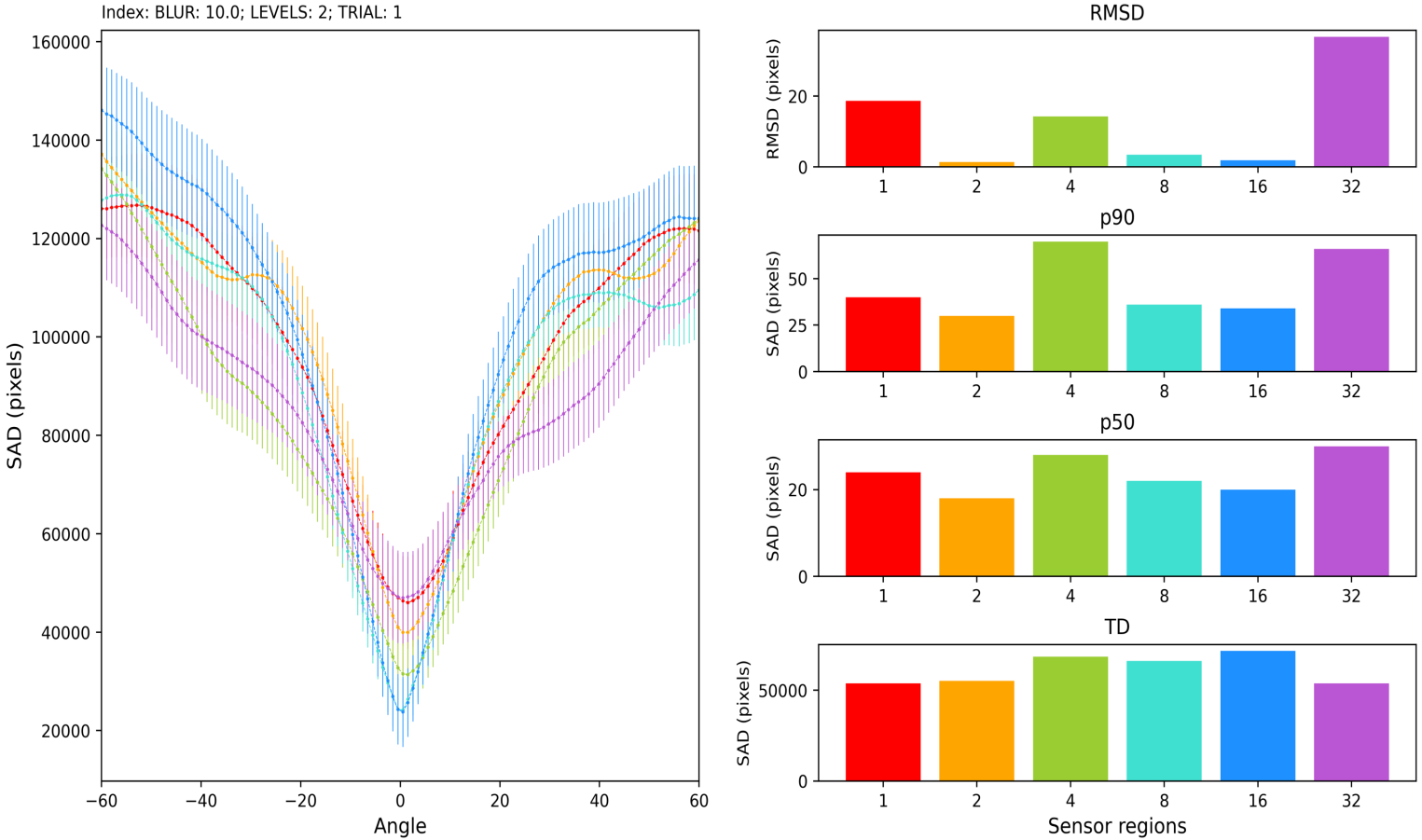

Index: BLUR: 10.0; LEVELS: 2; TRIAL: 0
SAD (pixels)
140000
120000
100000
80000
60000
40000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4000
2000
0
p90
SAD (pixels)
50
25
0
p50
SAD (pixels)
20
0
TD
SAD (pixels)
50000
25000
0
1
2
4
8
16
32
Sensor regions


Index: BLUR: 10.0; LEVELS: 2; TRIAL: 1
SAD (pixels)
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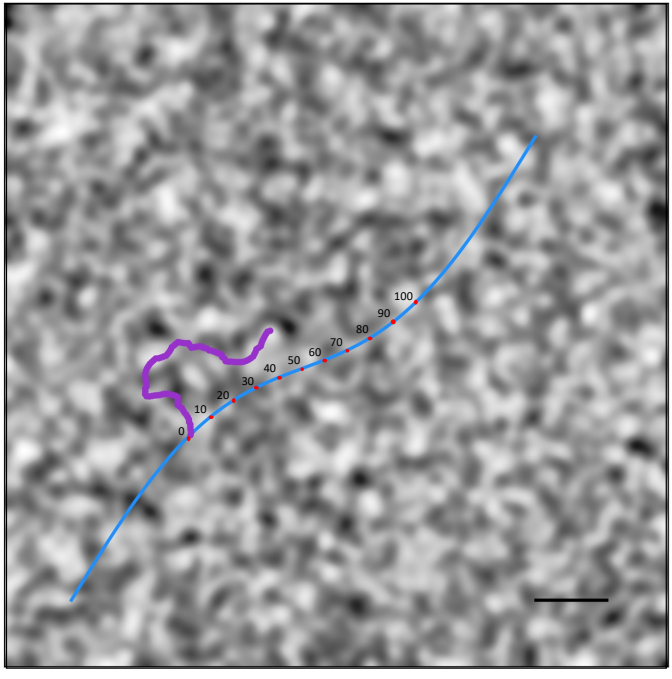
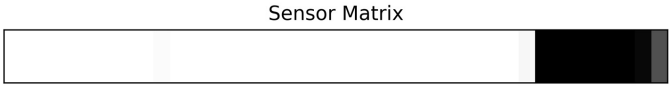
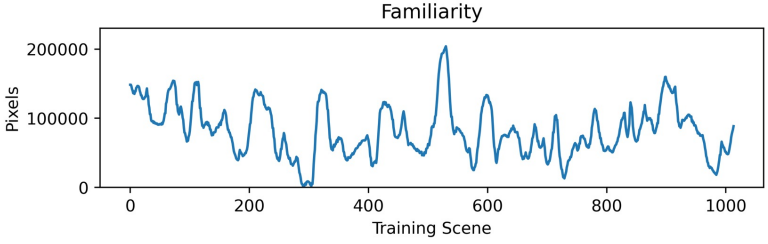
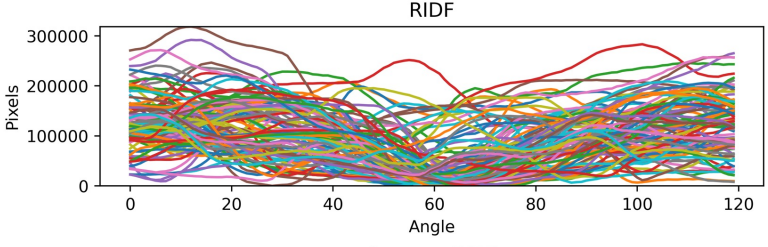
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
0
1
2
4
8
16
32
p90
SAD (pixels)
50
25
0
p50
20
TD
50000
Sensor regions

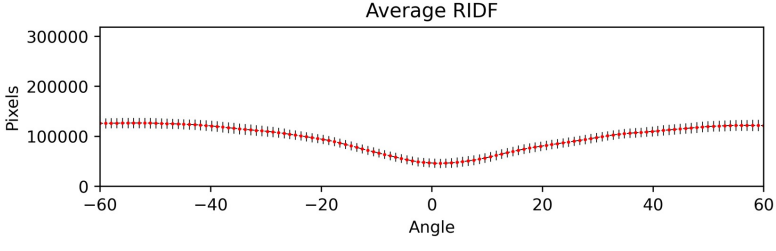
0%







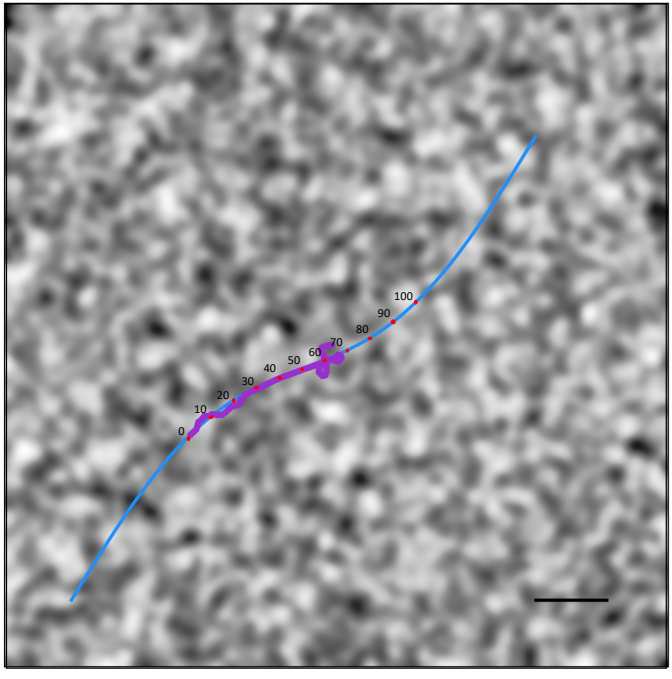


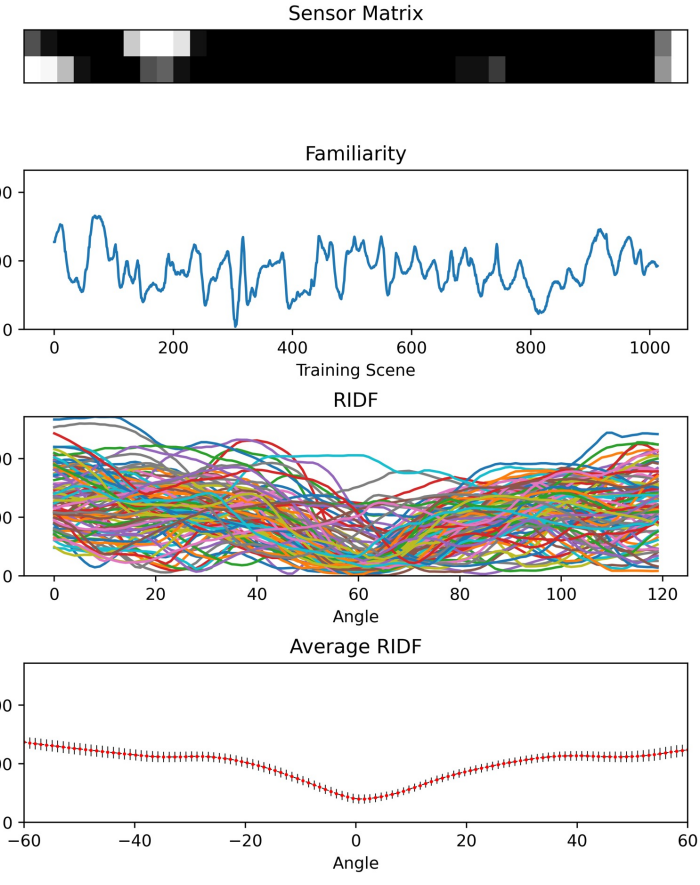


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 7485.82; RMSD/dist: 18.715; TD: 53698; p90: 40; p50: 24; complete: 0

30%

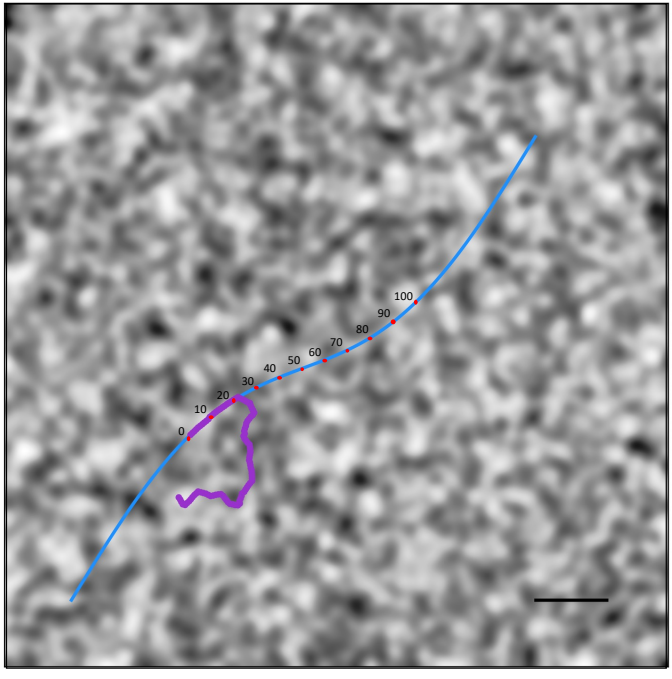


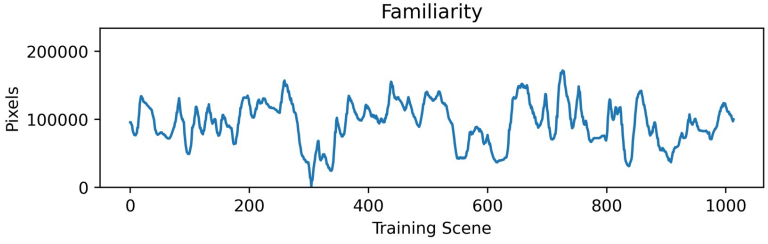


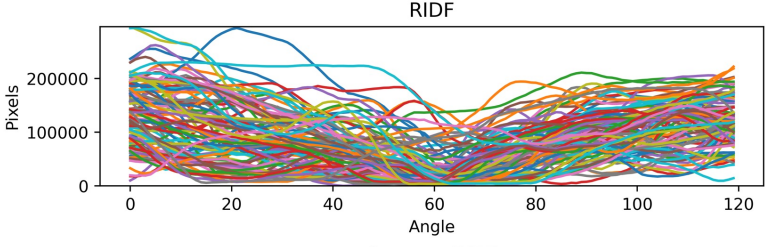
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

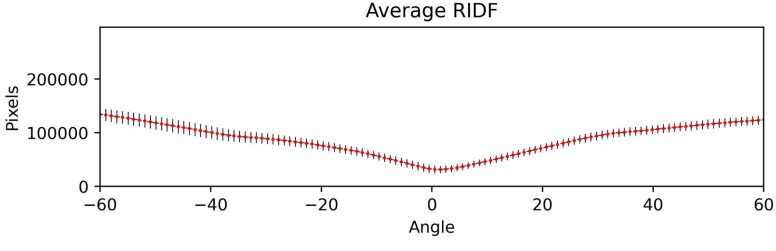
Navigation stats: RMSD error: 550.69; RMSD/dist: 1.377; TD: 55152; p90: 30; p50: 18; complete: 0

20%





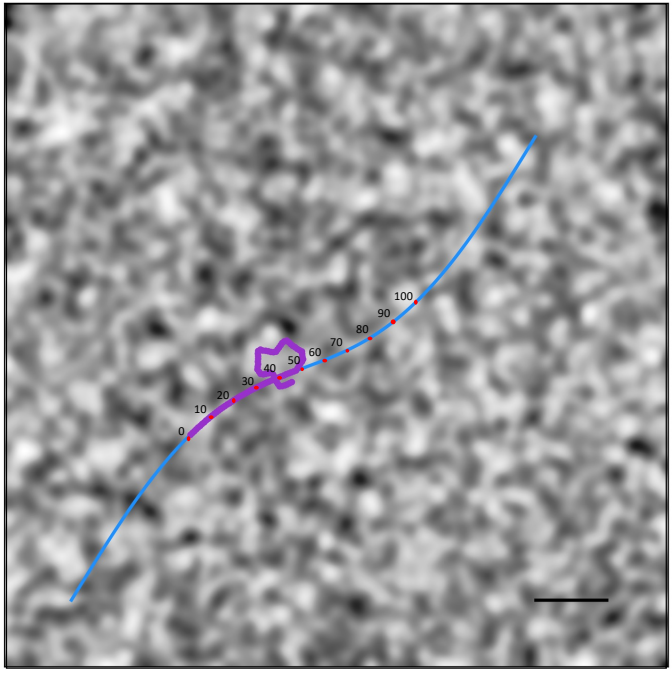


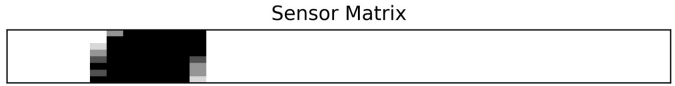


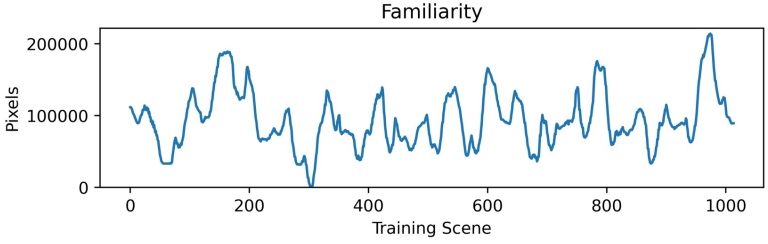
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

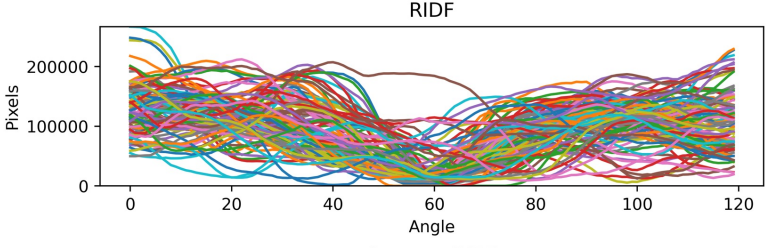
Navigation stats: RMSD error: 5713.38; RMSD/dist: 14.283; TD: 68412; p90: 70; p50: 28; complete: 0

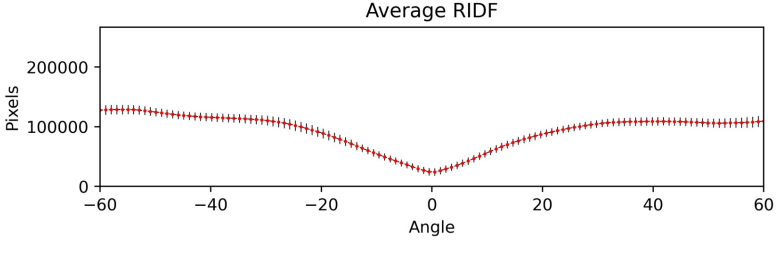
50%







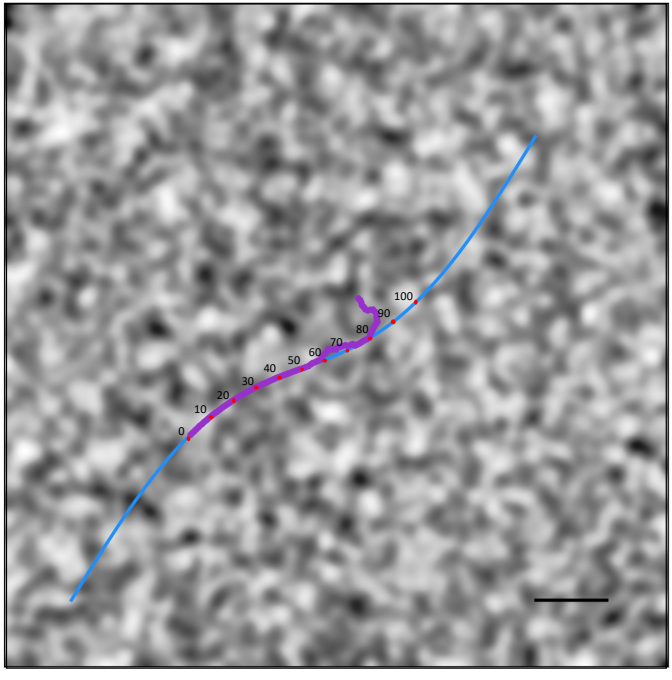


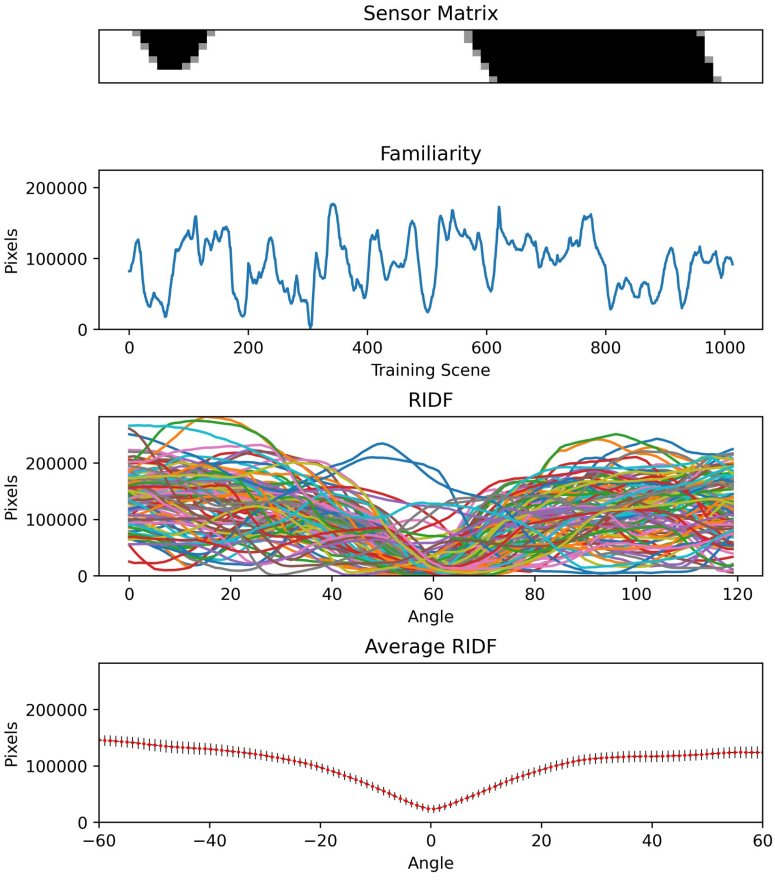


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1378.72; RMSD/dist: 3.447; TD: 65994; p90: 36; p50: 22; complete: 0

60%

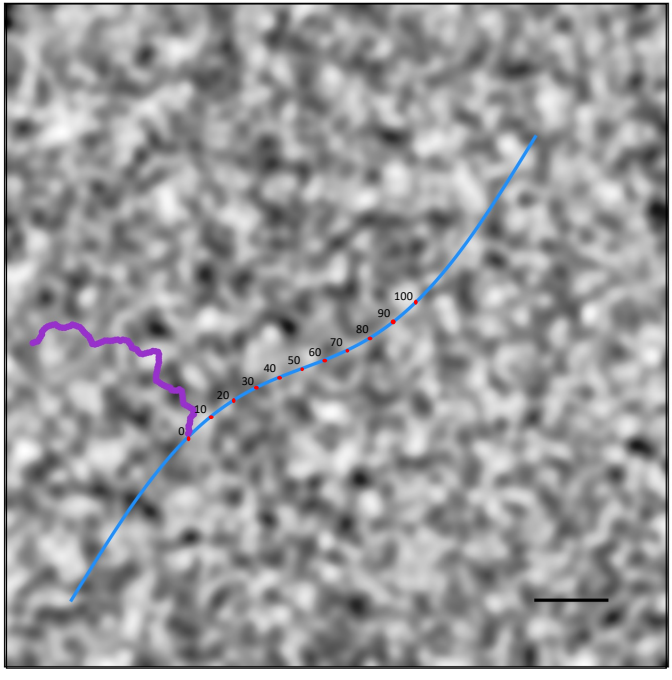


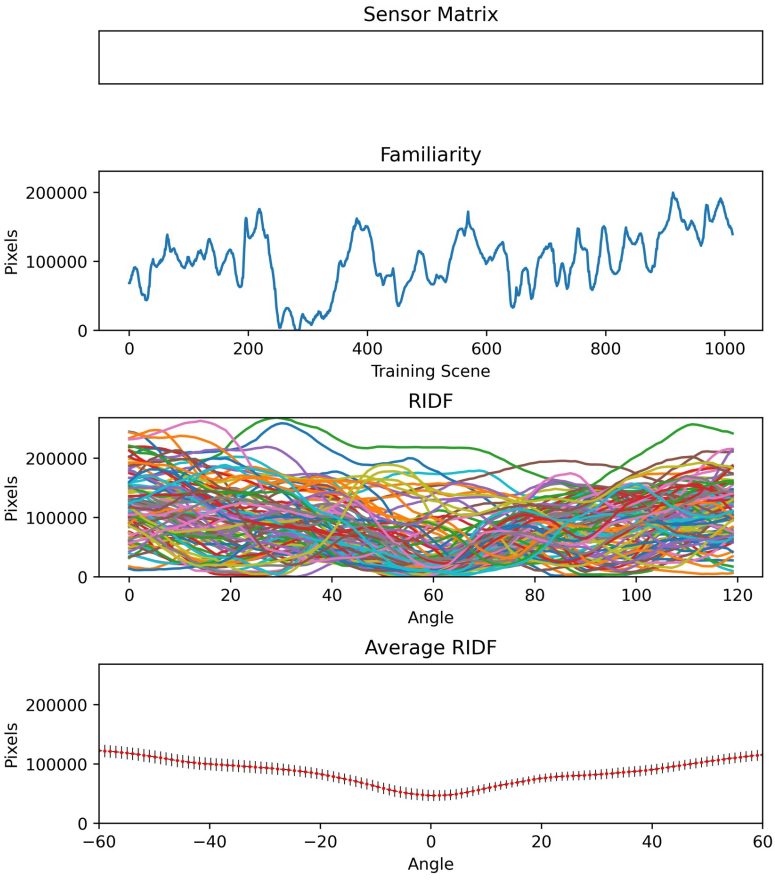


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 744.20; RMSD/dist: 1.860; TD: 71517; p90: 34; p50: 20; complete: 0

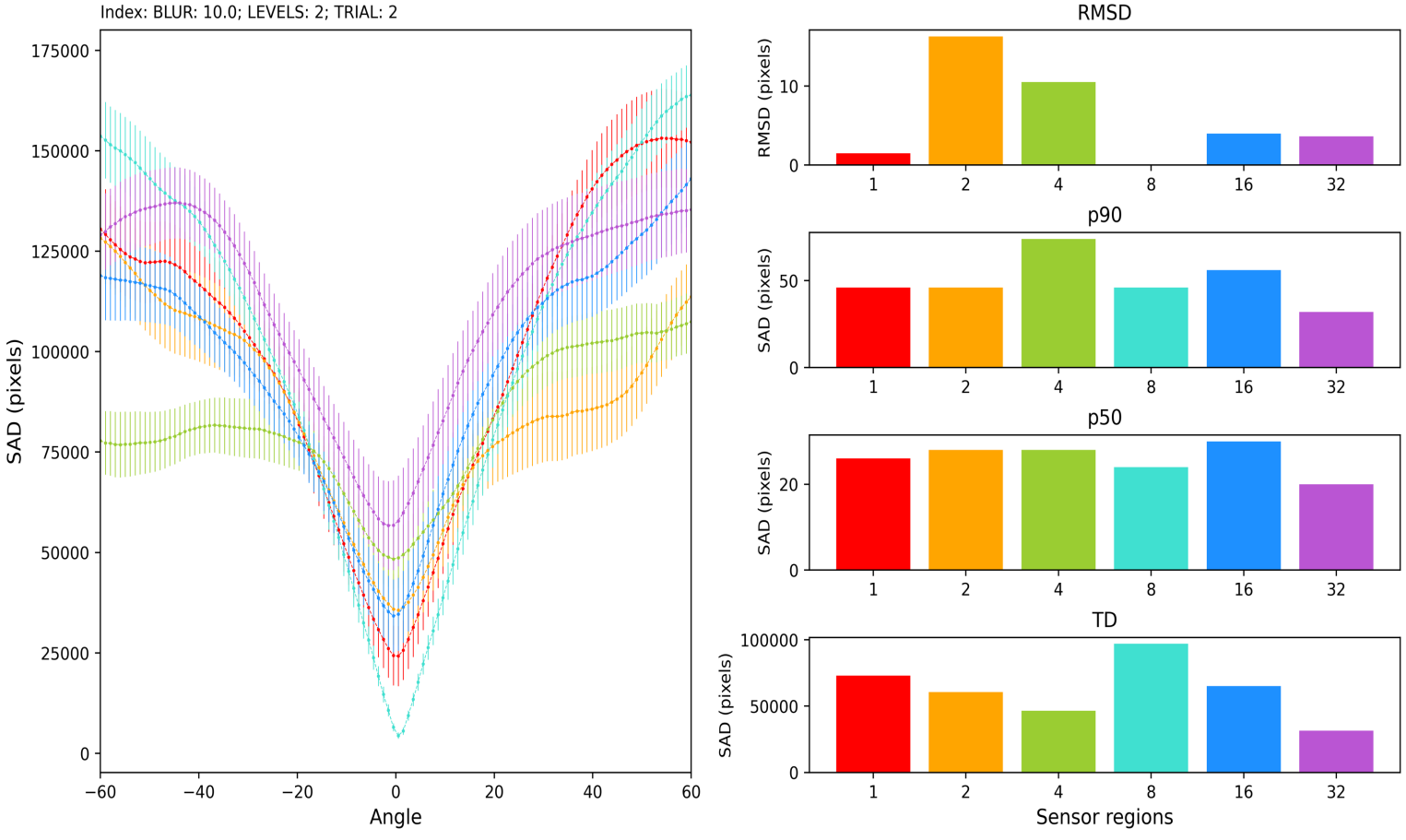
0%



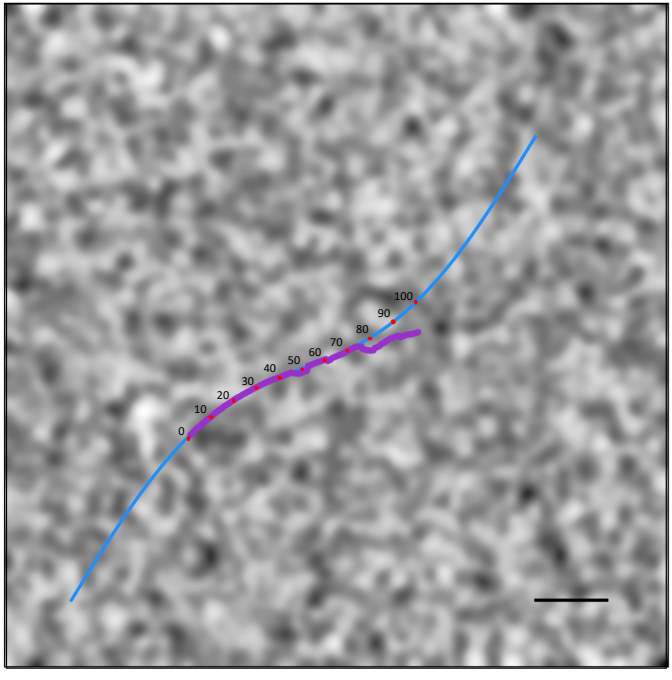


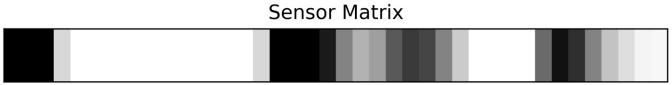
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

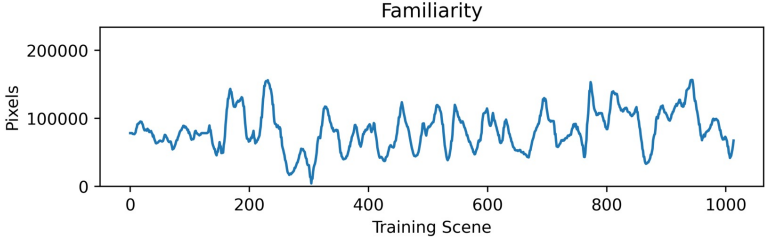
Navigation stats: RMSD error: 14728.96; RMSD/dist: 36.822; TD: 53774; p90: 66; p50: 30; complete: 0

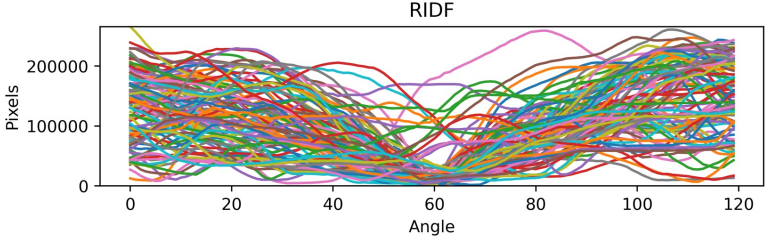

Index: BLUR: 10.0; LEVELS: 2; TRIAL: 2
SAD (pixels)
175000
150000
125000
100000
75000
50000
25000
0
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
50
0
p50
SAD (pixels)
20
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

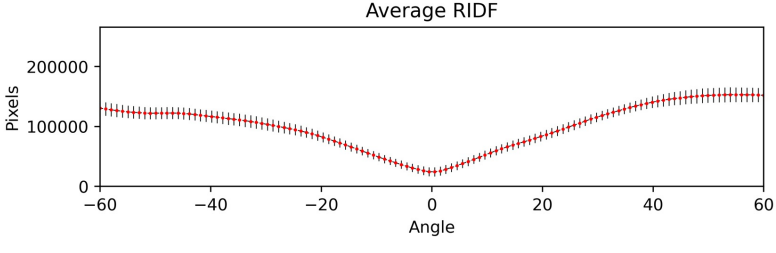
70%







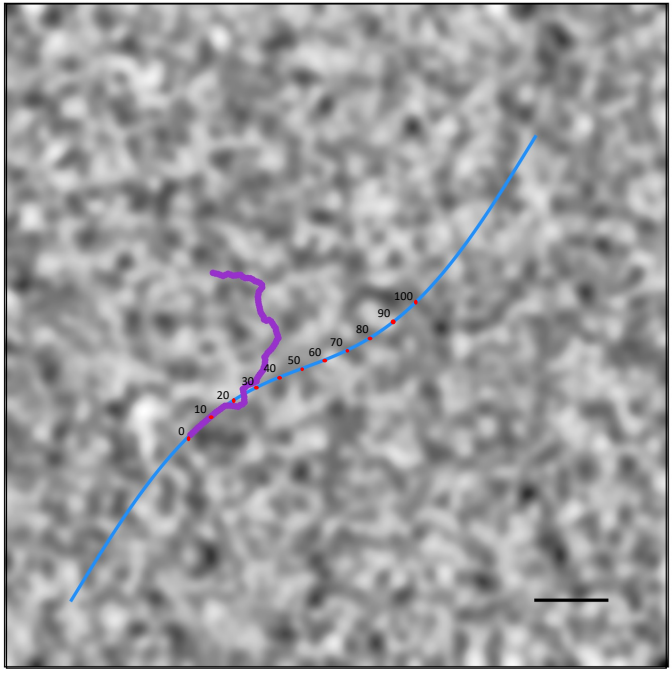


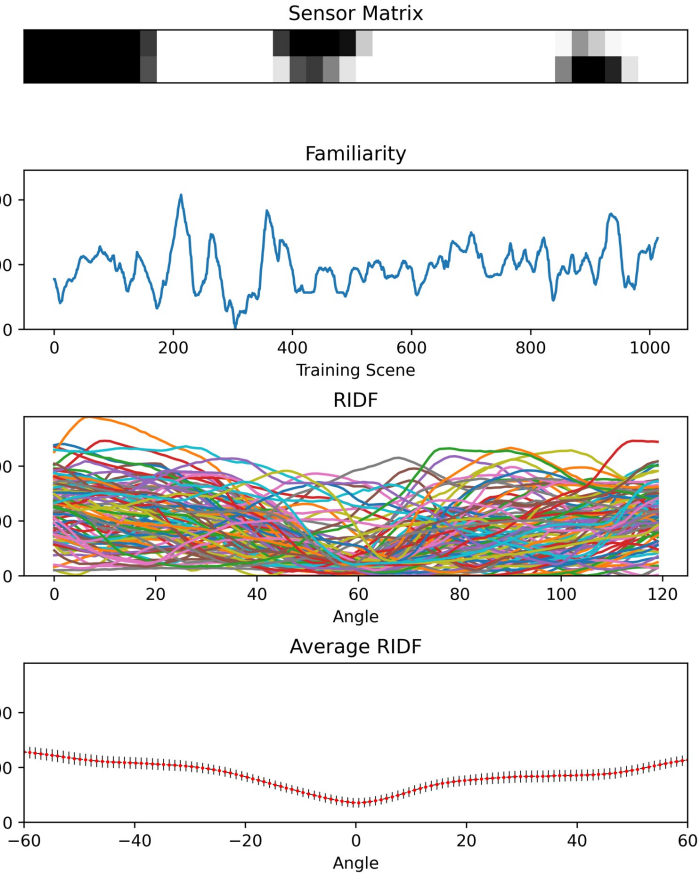


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 586.66; RMSD/dist: 1.467; TD: 72924; p90: 46; p50: 26; complete: 0

10%

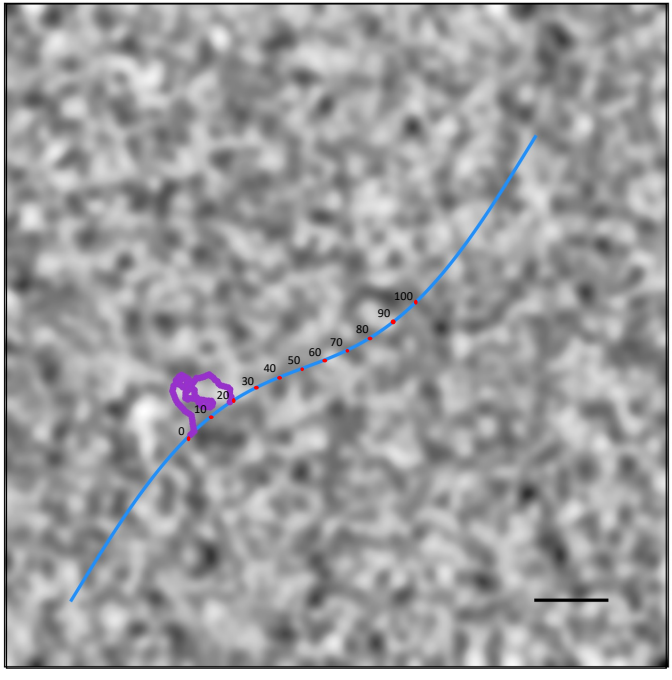


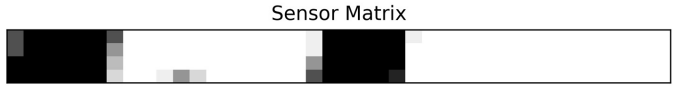


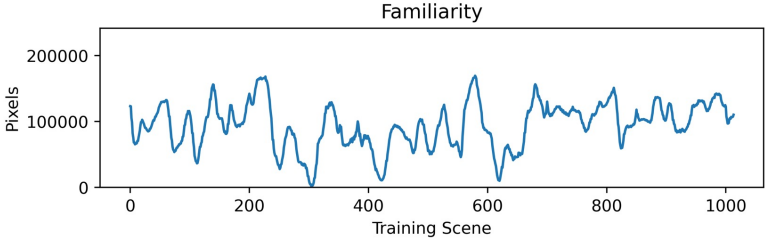
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

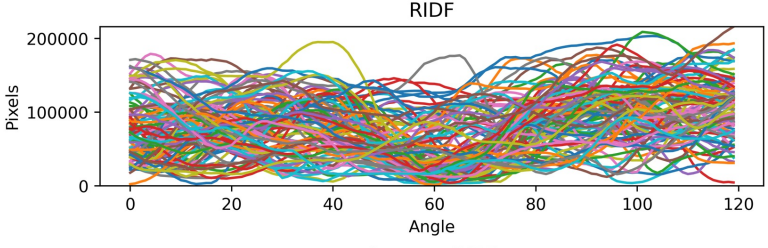
Navigation stats: RMSD error: 6512.23; RMSD/dist: 16.281; TD: 60478; p90: 46; p50: 28; complete: 0

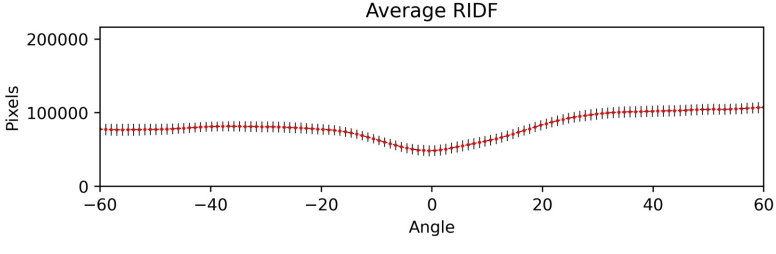
0%







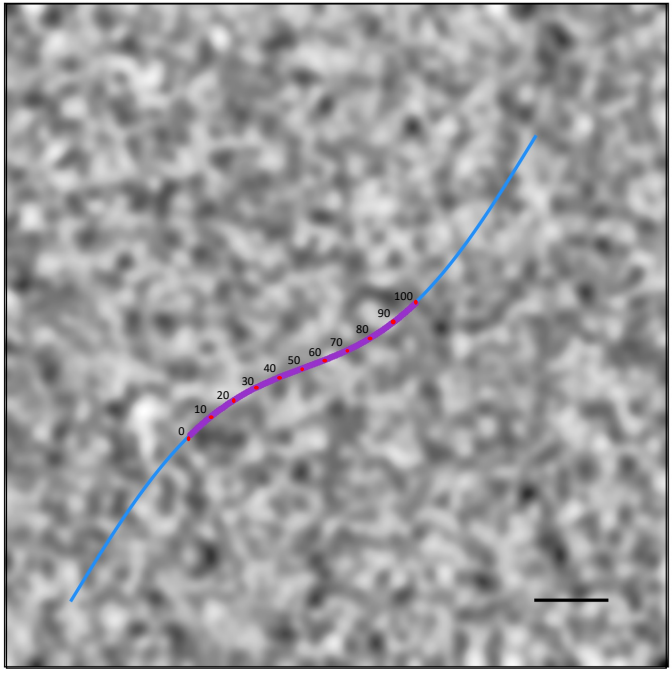


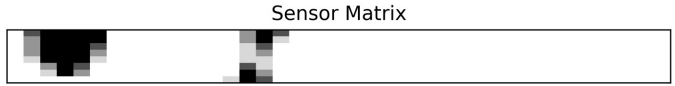


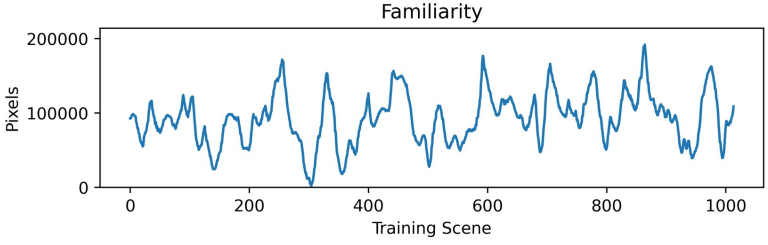
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

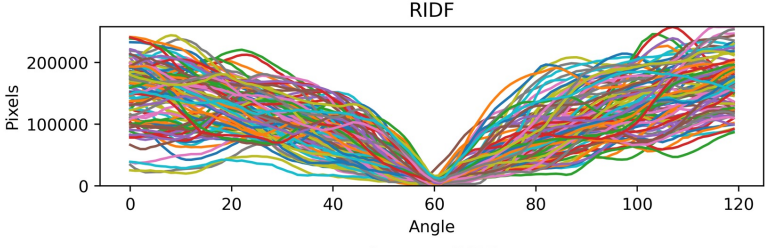
Navigation stats: RMSD error: 4199.43; RMSD/dist: 10.499; TD: 46481; p90: 74; p50: 28; complete: 0

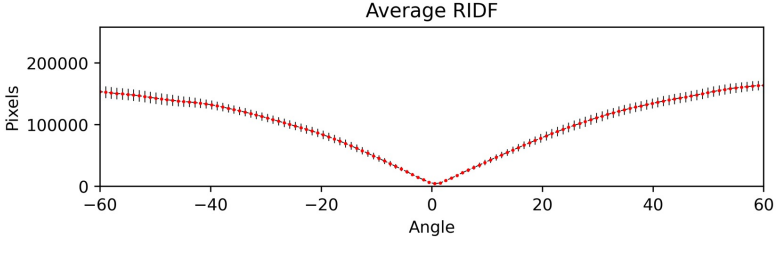
100%







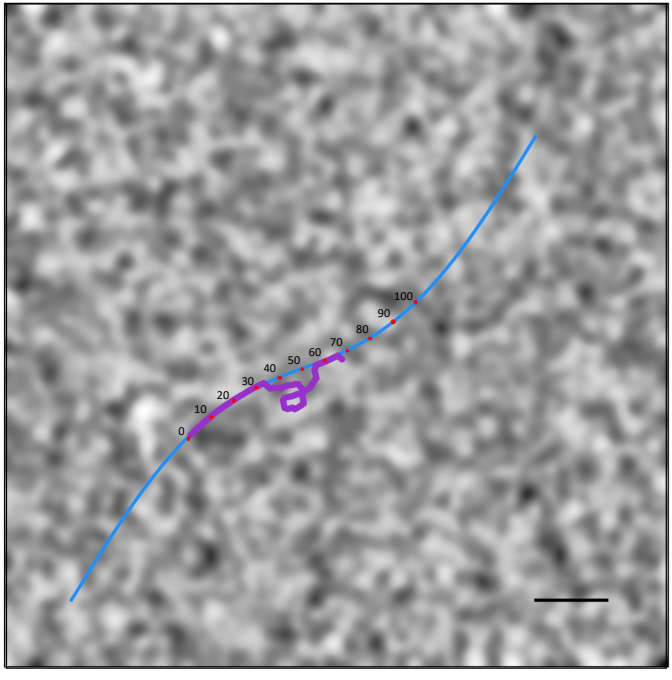


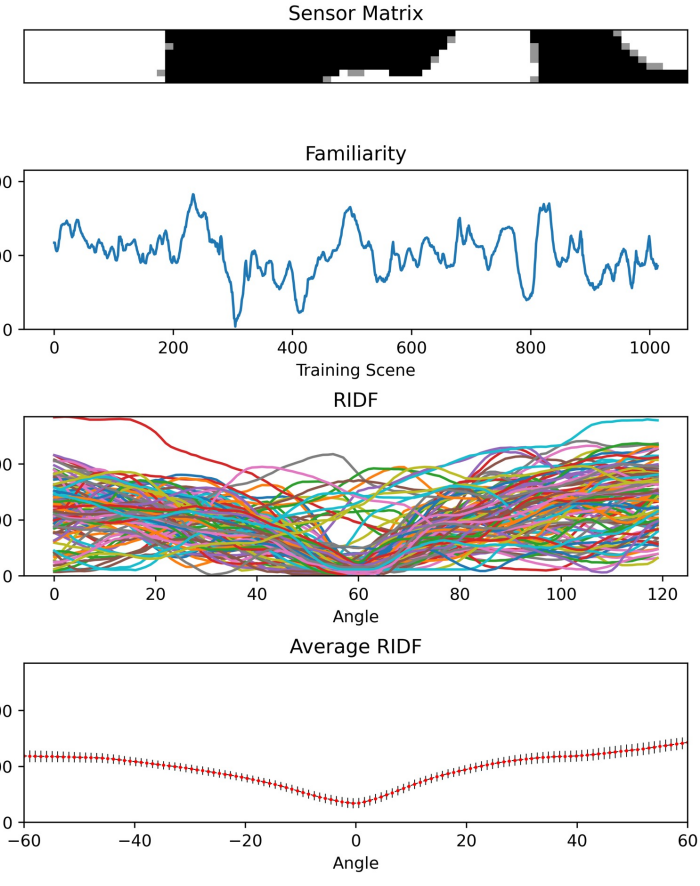


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 27.78; RMSD/dist: 0.069; TD: 96892; p90: 46; p50: 24; complete: 0

40%

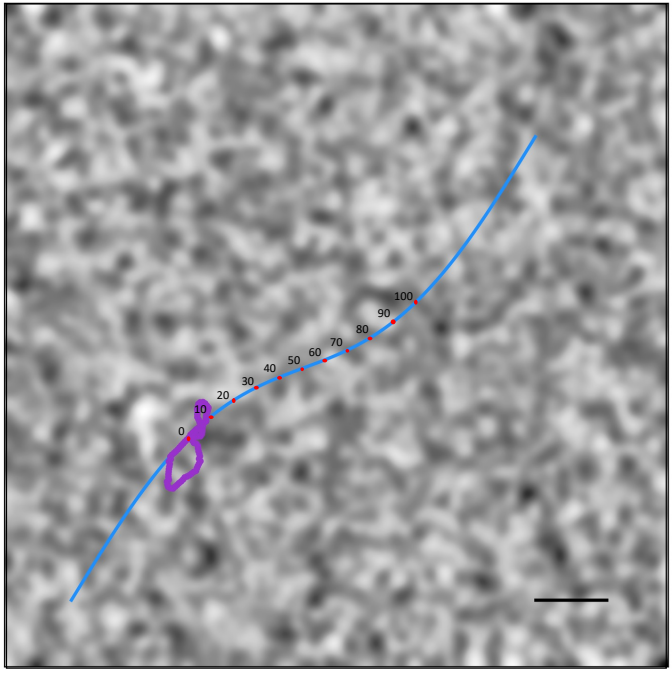


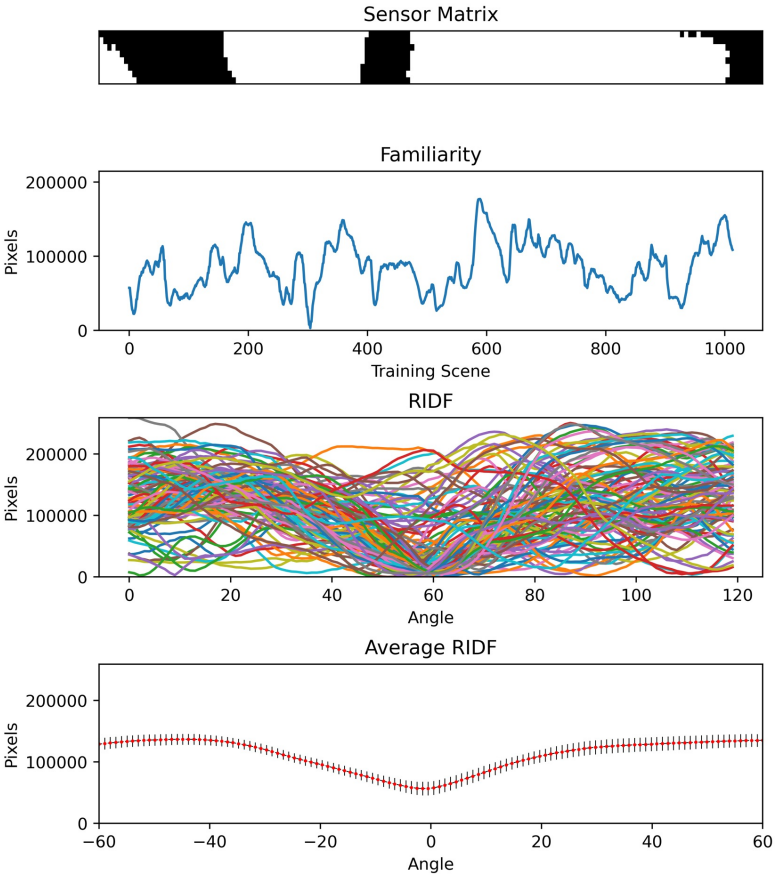


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1590.84; RMSD/dist: 3.977; TD: 64997; p90: 56; p50: 30; complete: 0

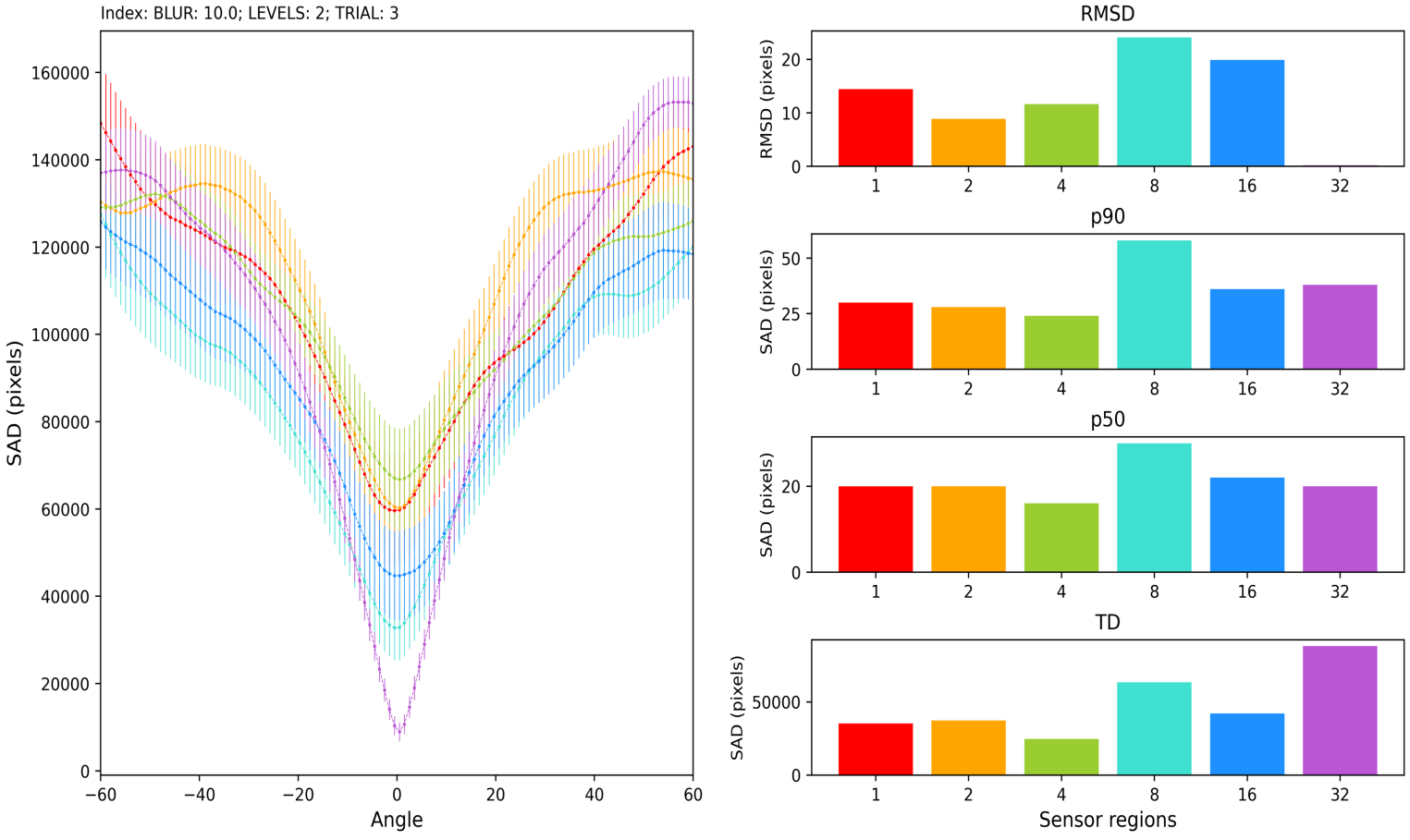
0%



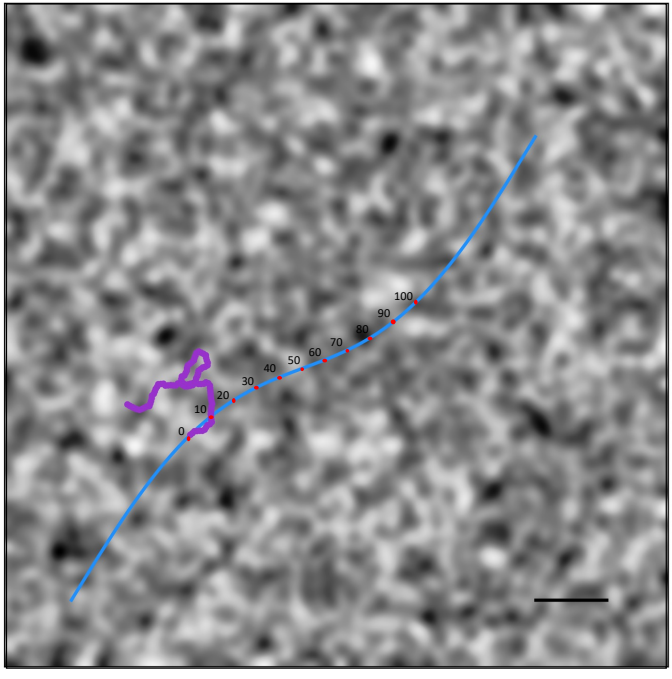


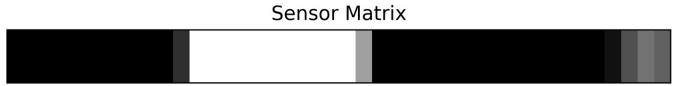
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

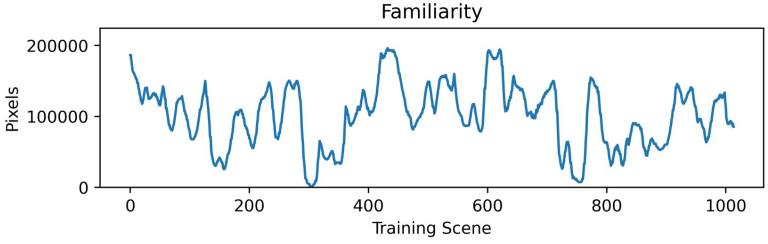
Navigation stats: RMSD error: 1445.87; RMSD/dist: 3.615; TD: 31390; p90: 32; p50: 20; complete: 0

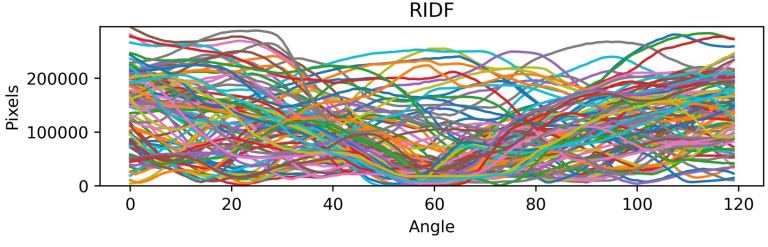

Index: BLUR: 10.0; LEVELS: 2; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

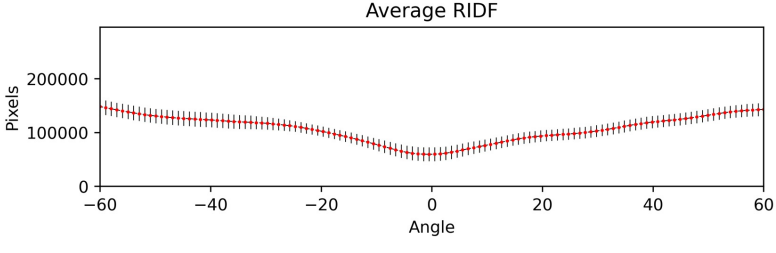
0%







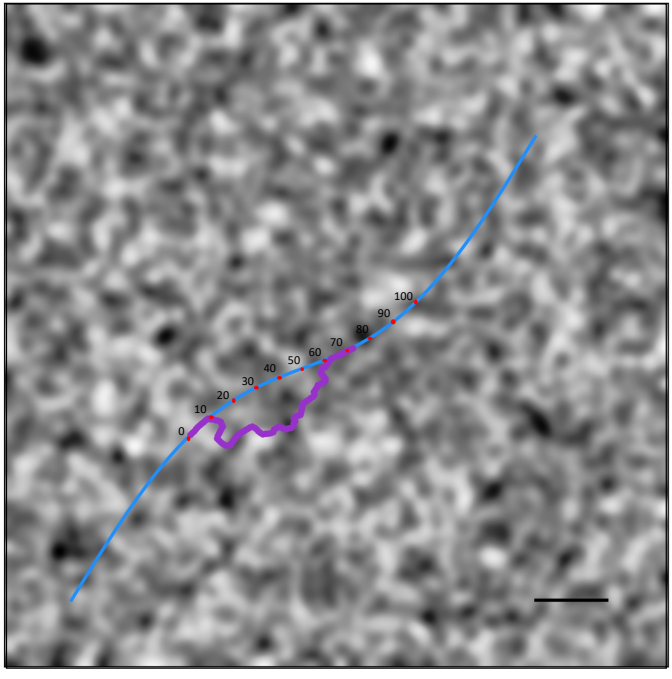


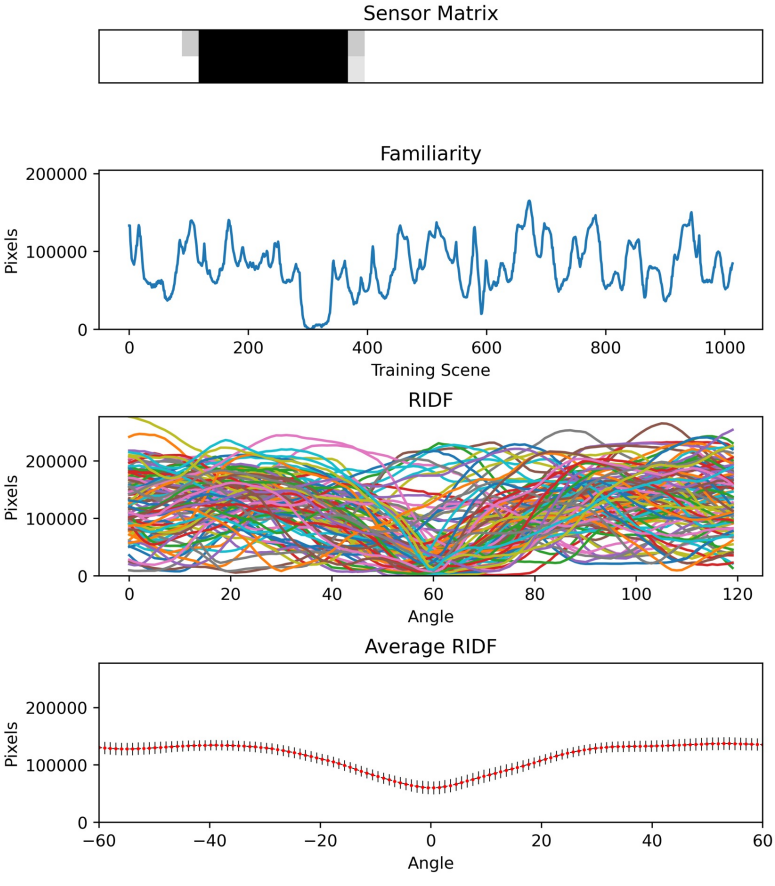


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 5771.79; RMSD/dist: 14.429; TD: 35296; p90: 30; p50: 20; complete: 0

10%

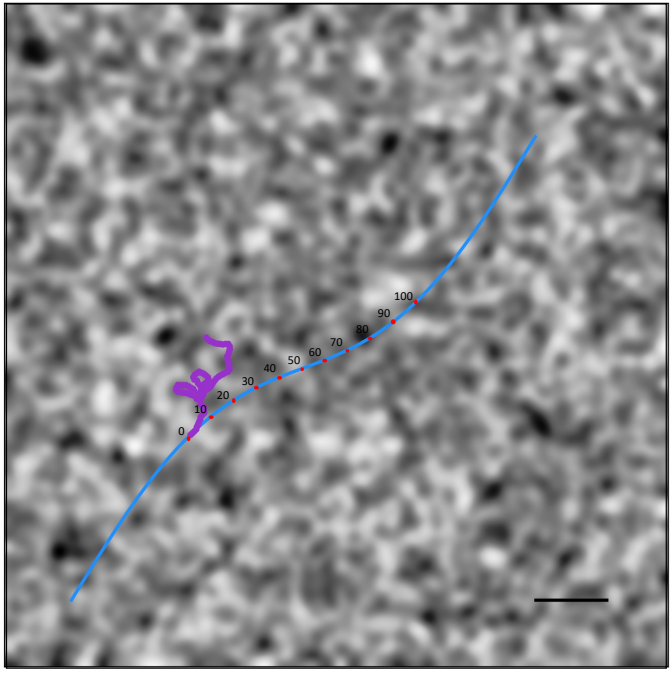


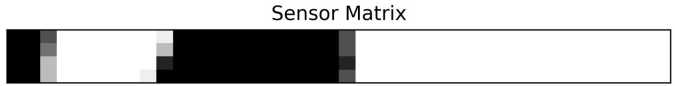


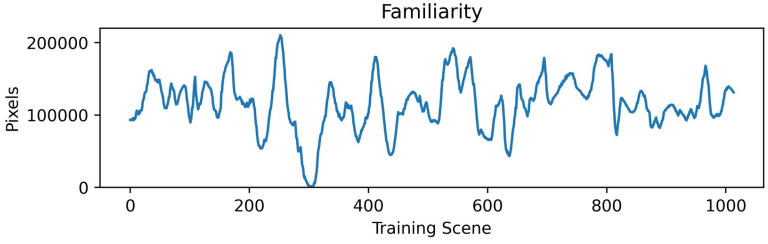
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

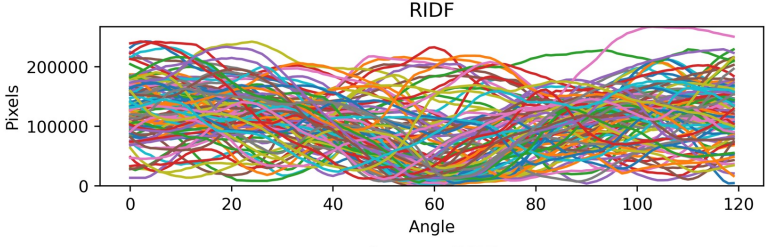
Navigation stats: RMSD error: 3537.64; RMSD/dist: 8.844; TD: 37362; p90: 28; p50: 20; complete: 0

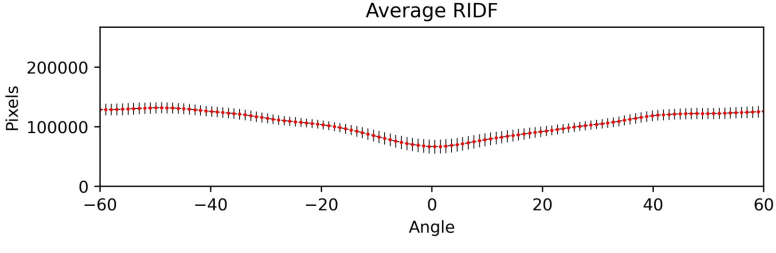
0%







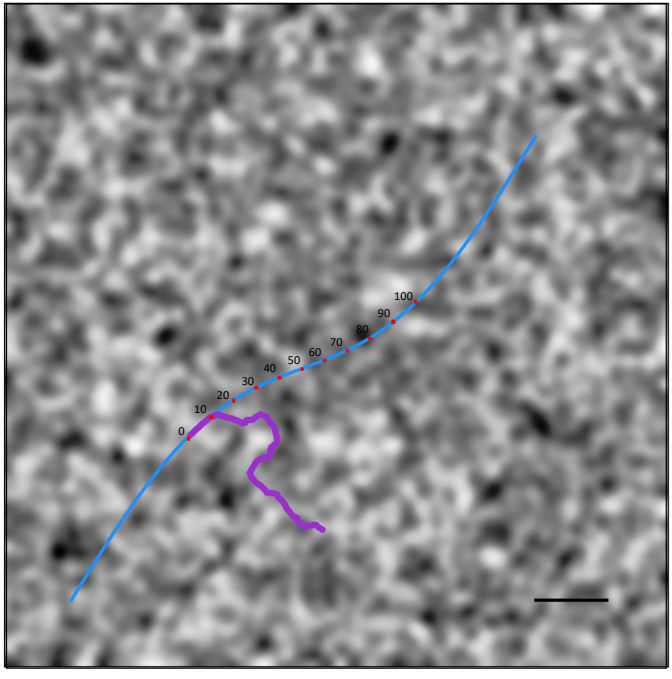


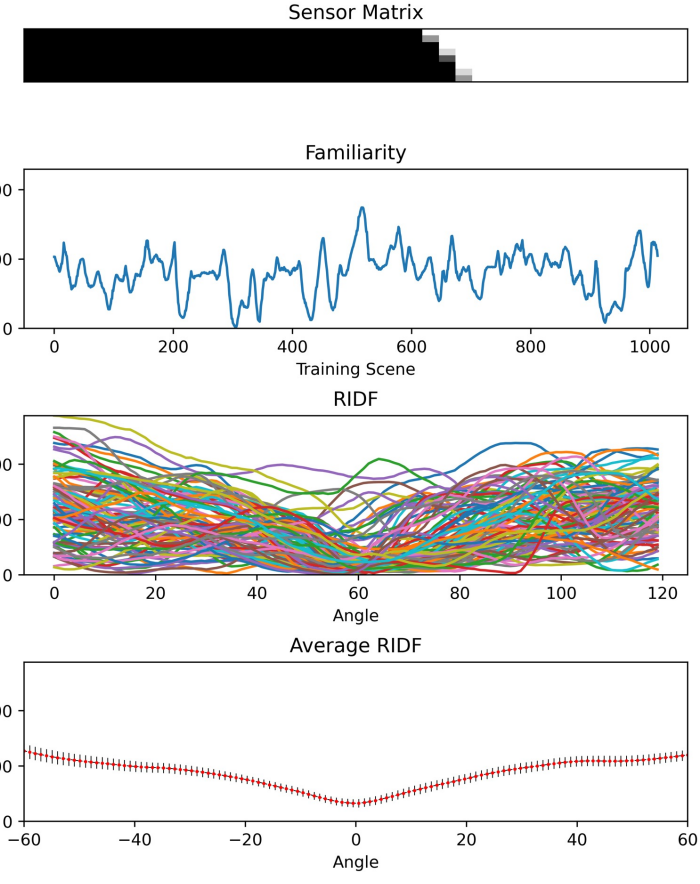


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4640.18; RMSD/dist: 11.600; TD: 24602; p90: 24; p50: 16; complete: 0

10%

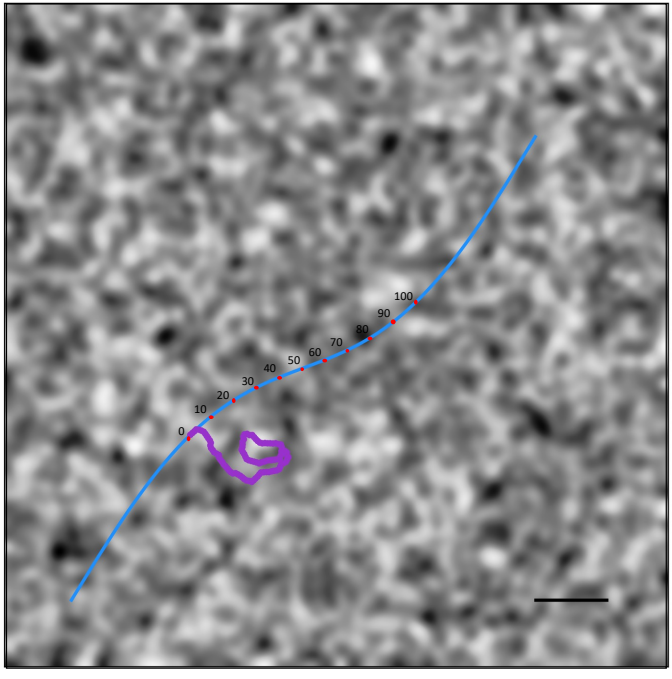


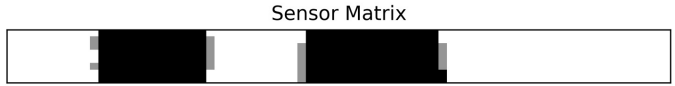


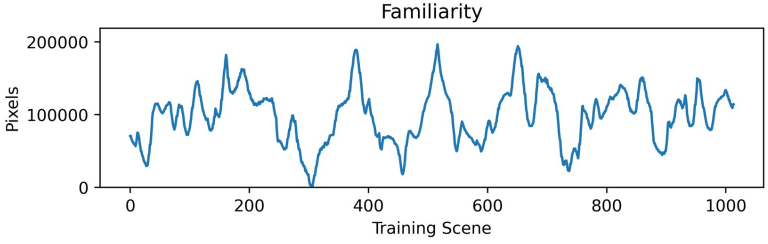
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

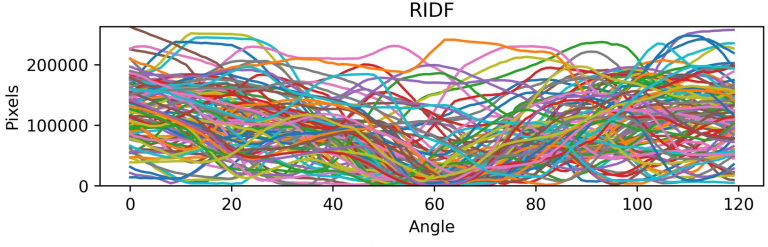
Navigation stats: RMSD error: 9640.35; RMSD/dist: 24.101; TD: 63370; p90: 58; p50: 30; complete: 0

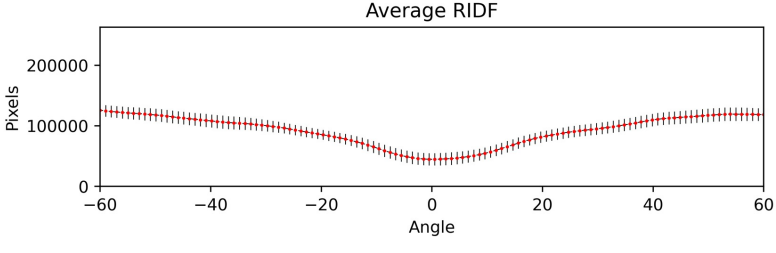
0%







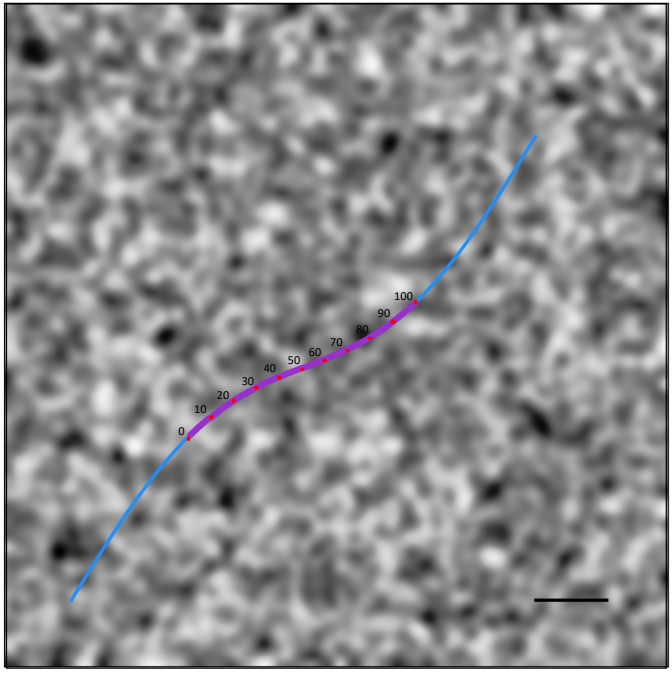


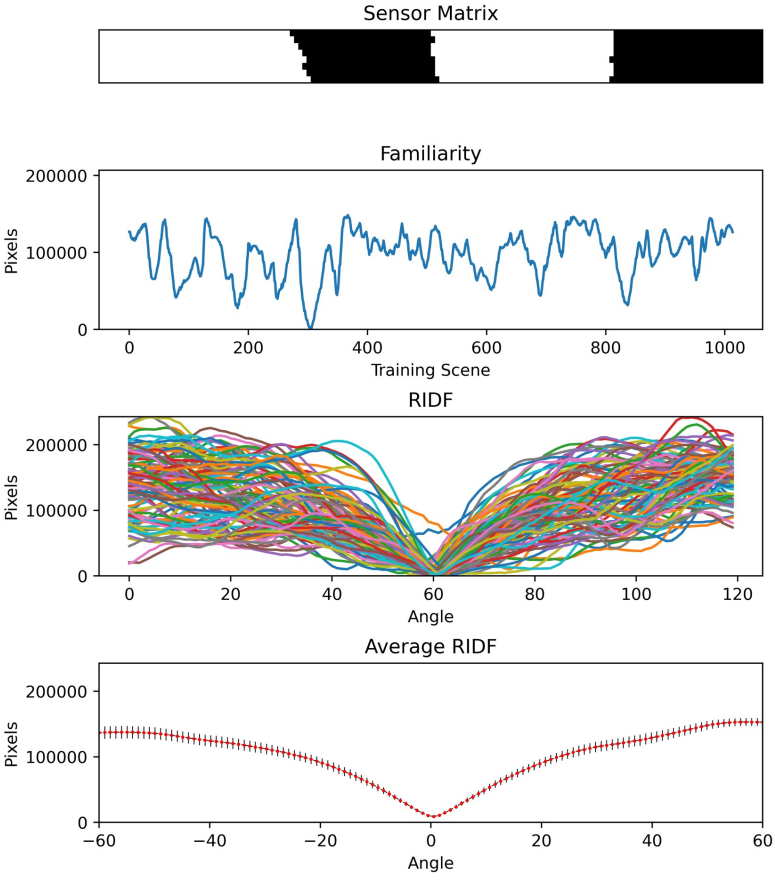


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 7959.20; RMSD/dist: 19.898; TD: 42011; p90: 36; p50: 22; complete: 0

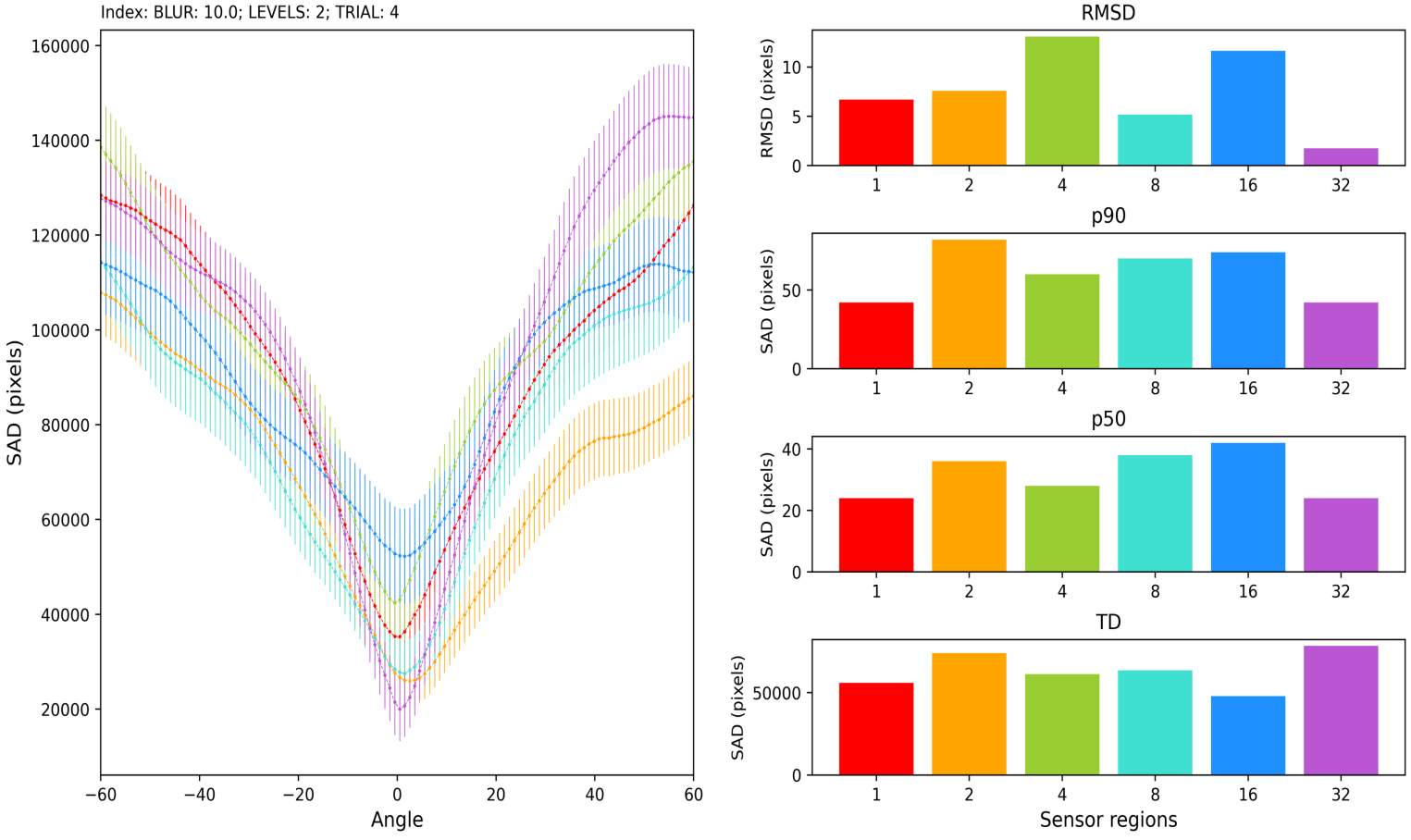
100%



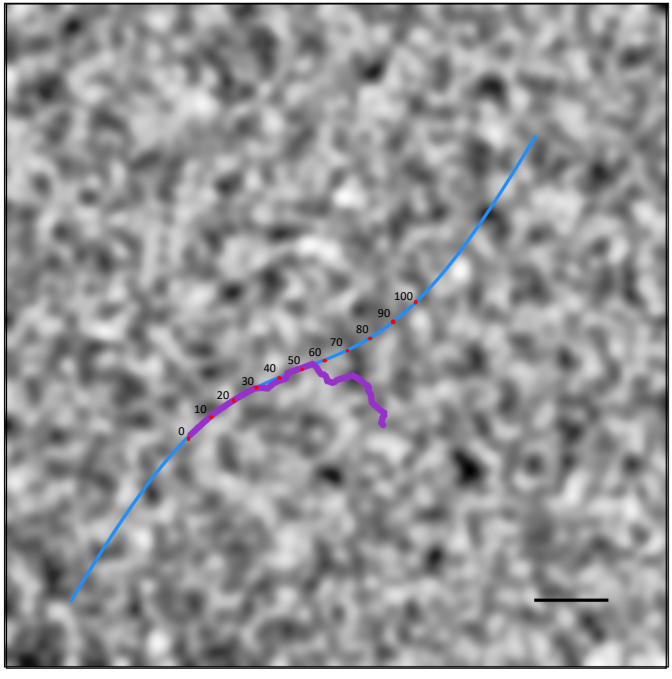


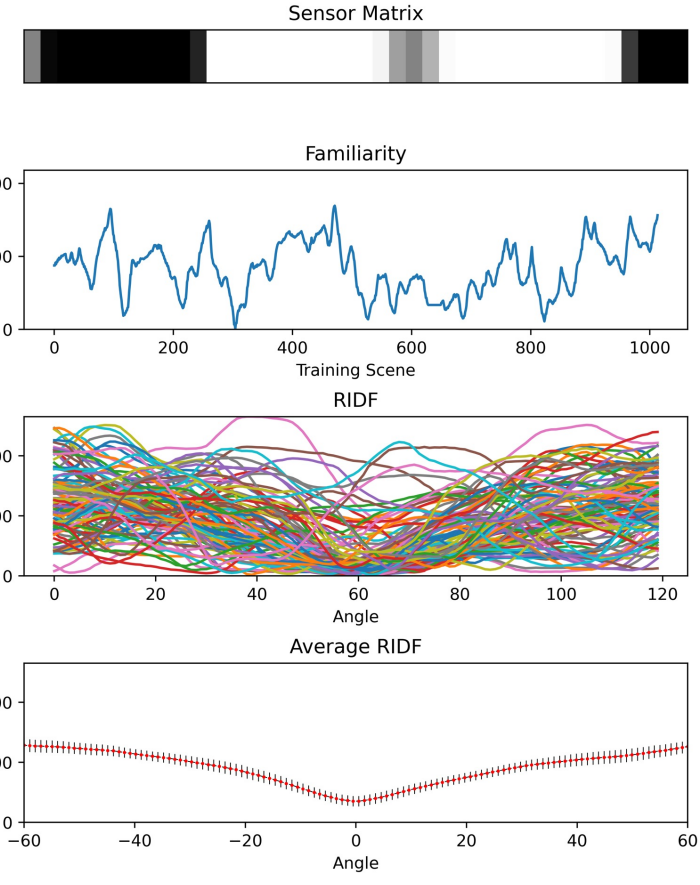
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 67.47; RMSD/dist: 0.169; TD: 88079; p90: 38; p50: 20; complete: 0


Index: BLUR: 10.0; LEVELS: 2; TRIAL: 4
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
p90
SAD (pixels)
50
0
p50
SAD (pixels)
40
20
0
TD
SAD (pixels)
50000
0
1
2
4
8
16
32
Sensor regions

40%

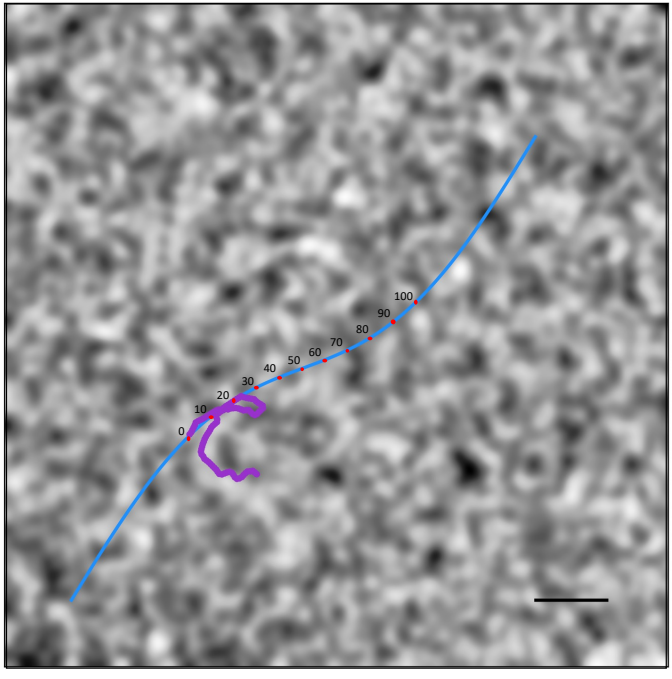


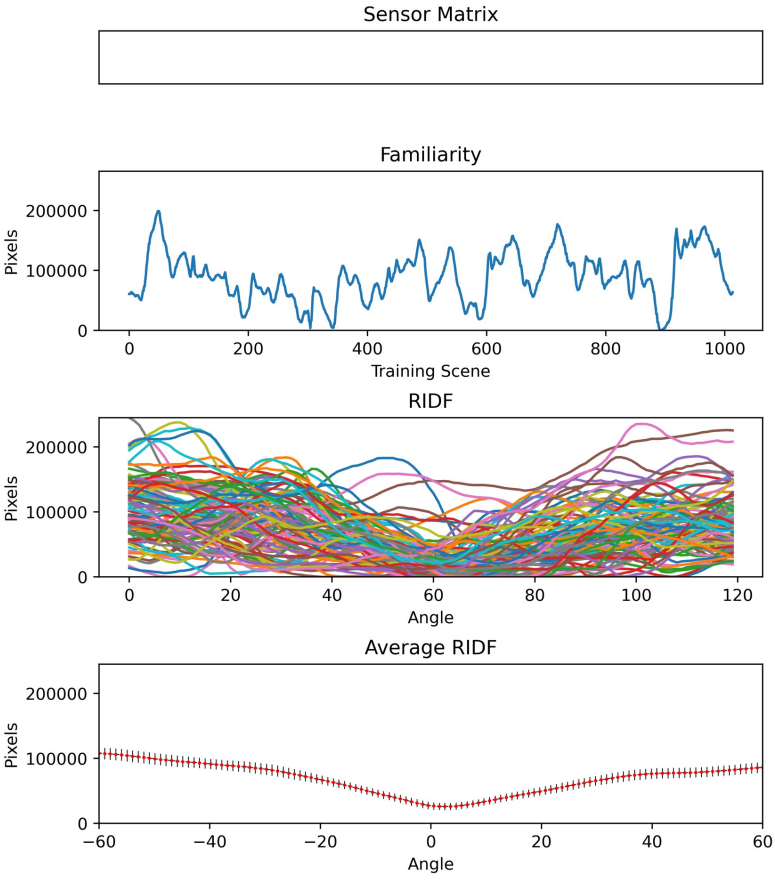


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2678.58; RMSD/dist: 6.696; TD: 55927; p90: 42; p50: 24; complete: 0

10%

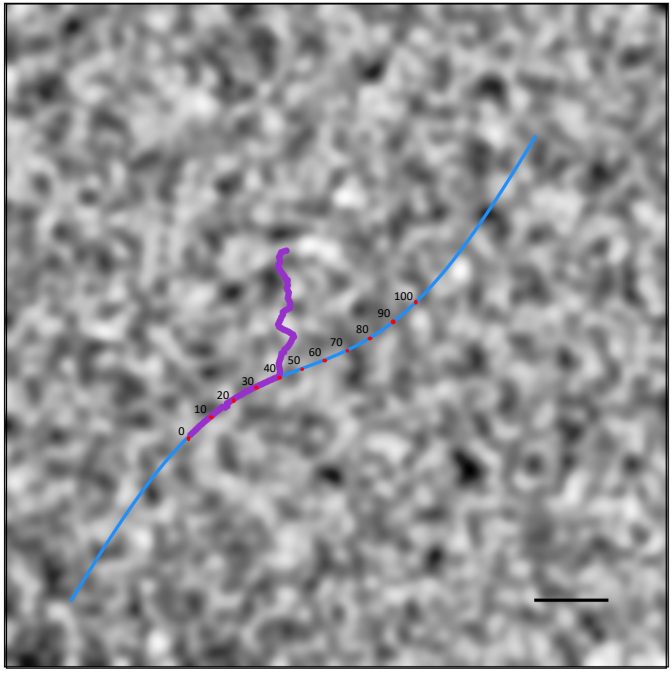


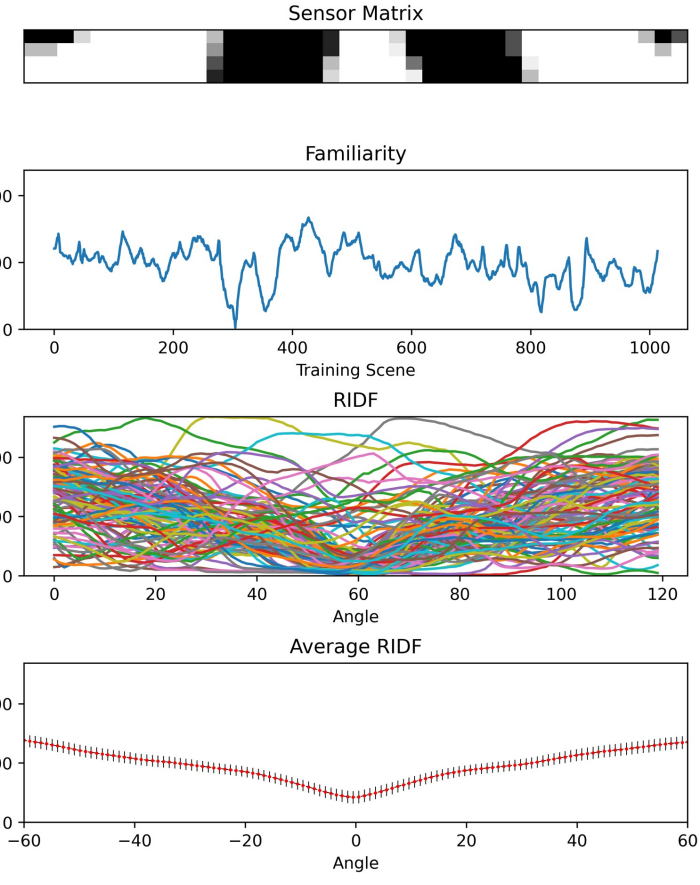


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3034.43; RMSD/dist: 7.586; TD: 73974; p90: 82; p50: 36; complete: 0

40%

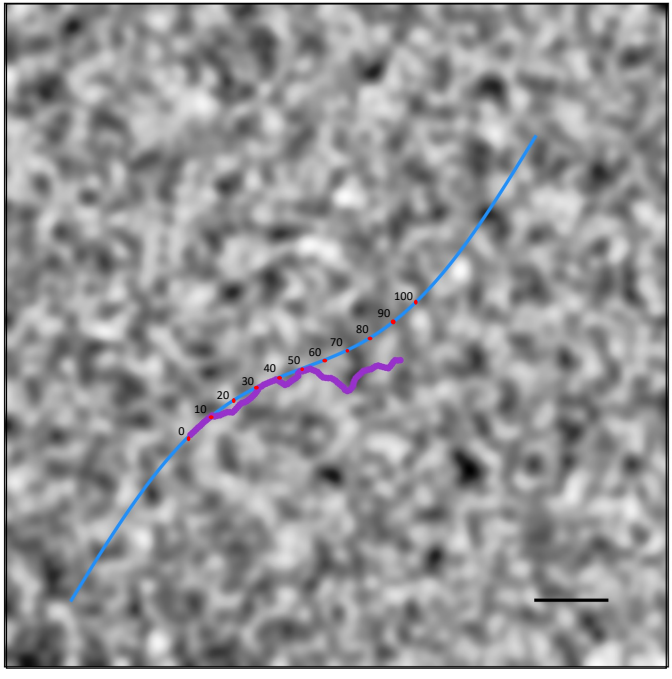


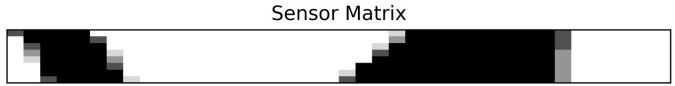


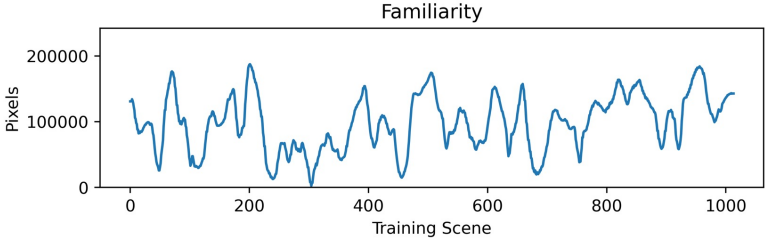
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

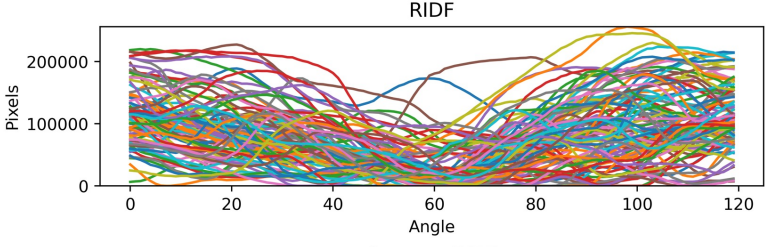
Navigation stats: RMSD error: 5236.00; RMSD/dist: 13.090; TD: 61238; p90: 60; p50: 28; complete: 0

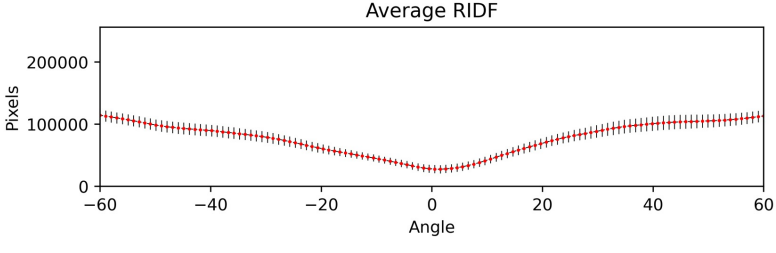
20%







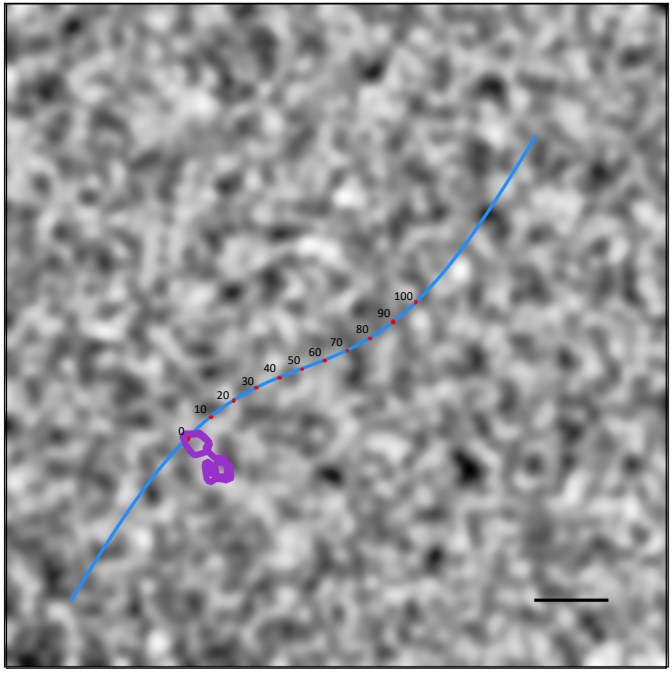


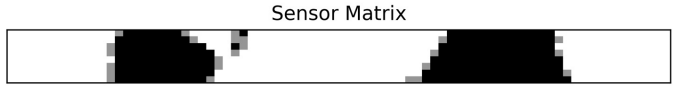


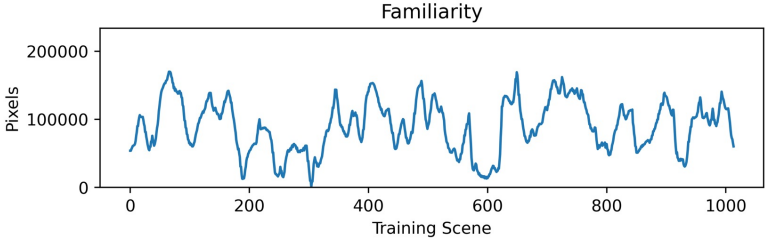
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

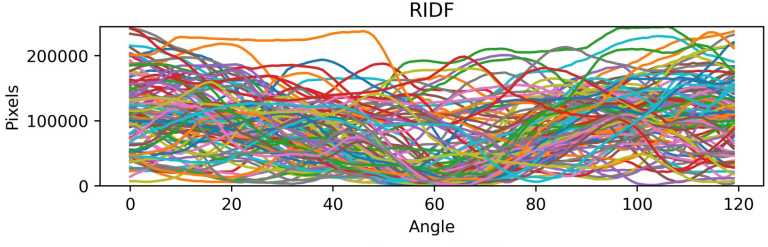
Navigation stats: RMSD error: 2063.01; RMSD/dist: 5.158; TD: 63510; p90: 70; p50: 38; complete: 0

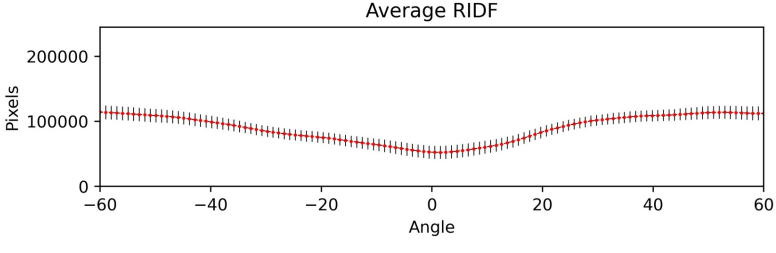
0%







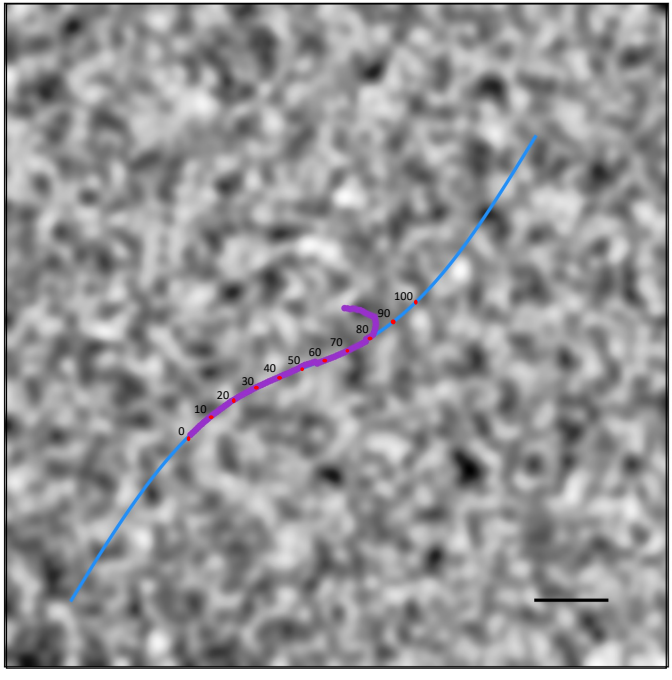


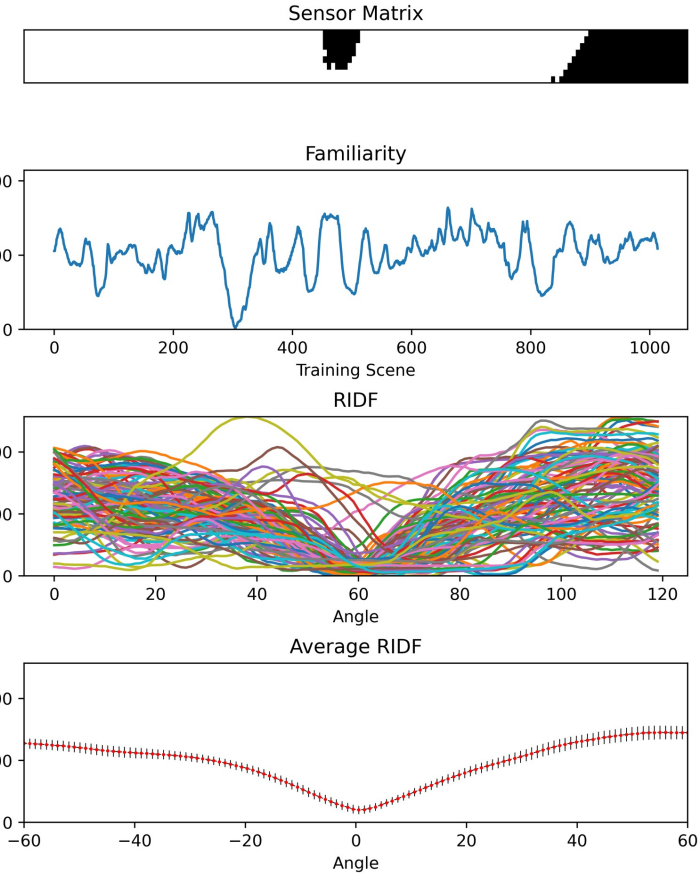


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4652.21; RMSD/dist: 11.631; TD: 47877; p90: 74; p50: 42; complete: 0

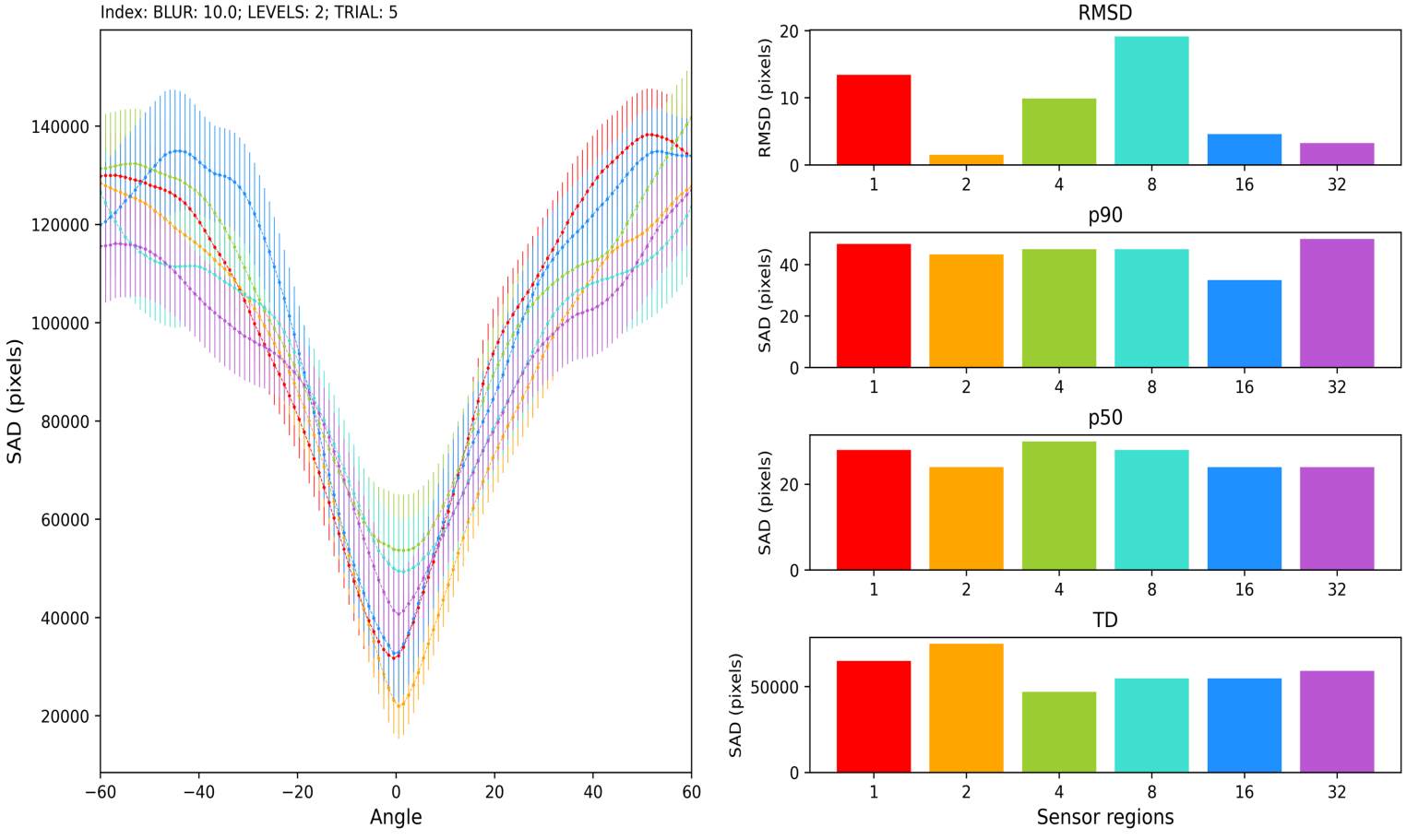
80%



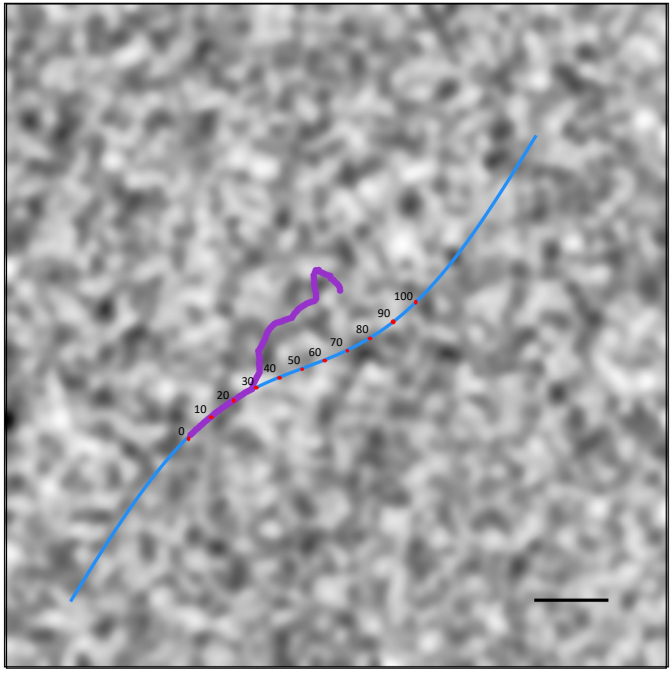


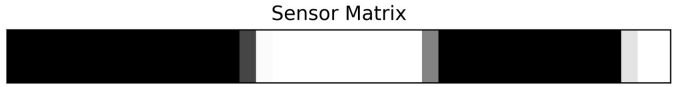
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

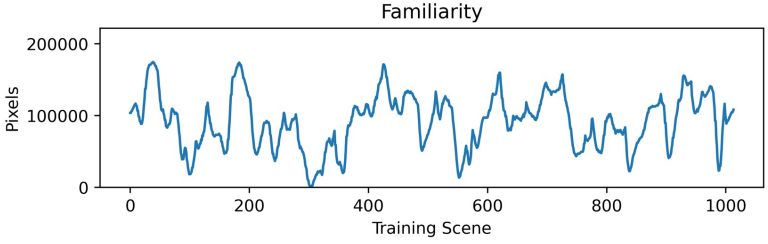
Navigation stats: RMSD error: 693.78; RMSD/dist: 1.734; TD: 78327; p90: 42; p50: 24; complete: 0

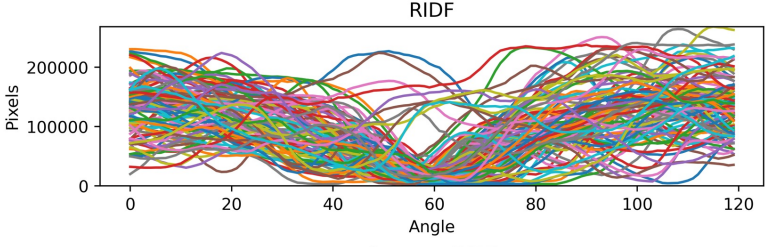

Index: BLUR: 10.0; LEVELS: 2; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

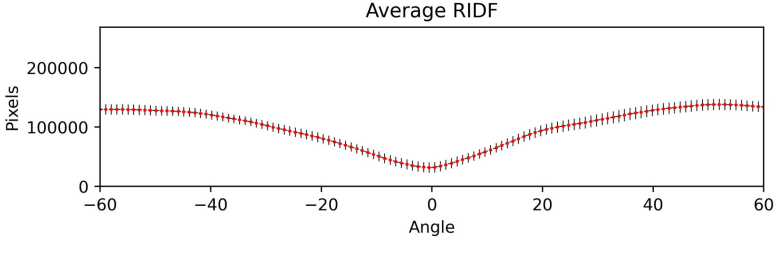
30%







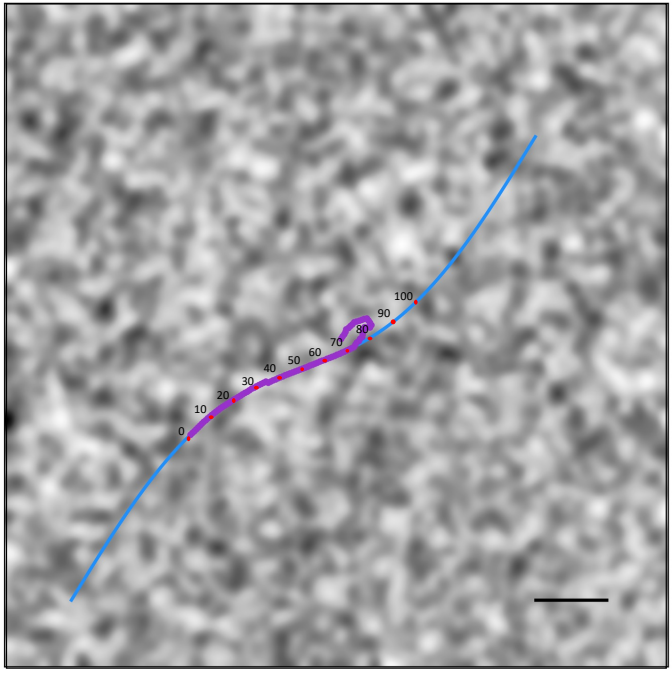


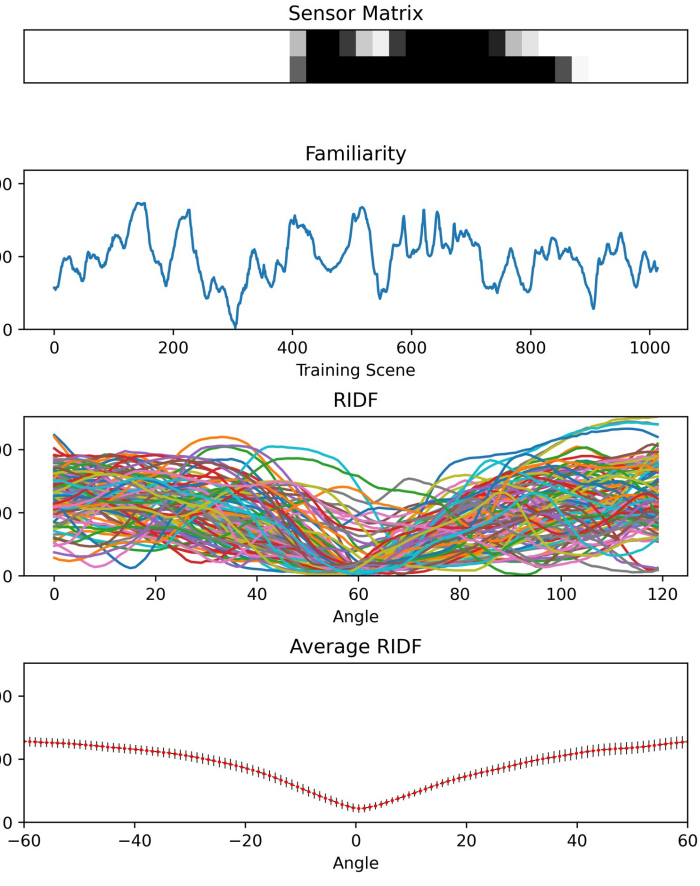


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5365.76; RMSD/dist: 13.414; TD: 64994; p90: 48; p50: 28; complete: 0

70%

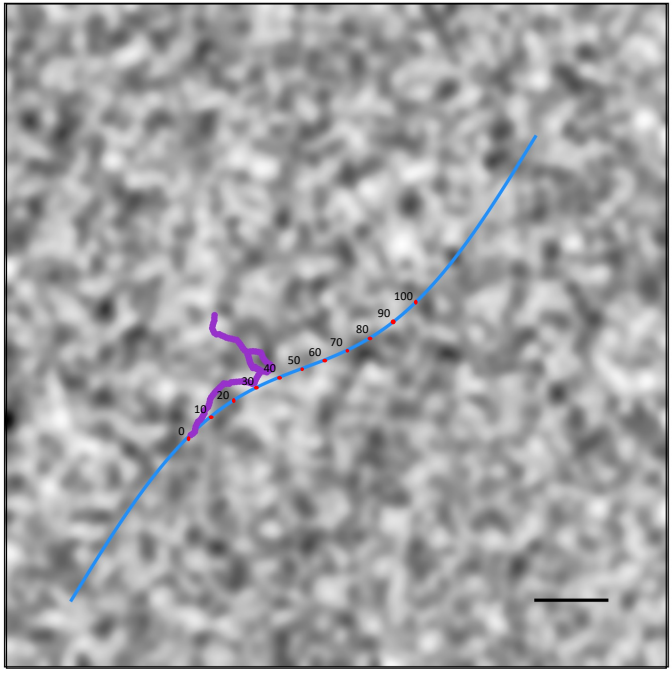


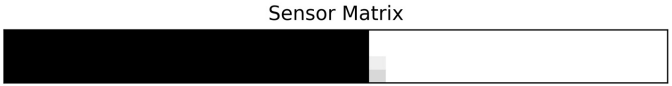


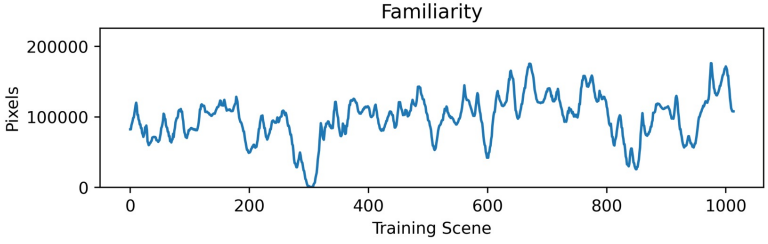
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

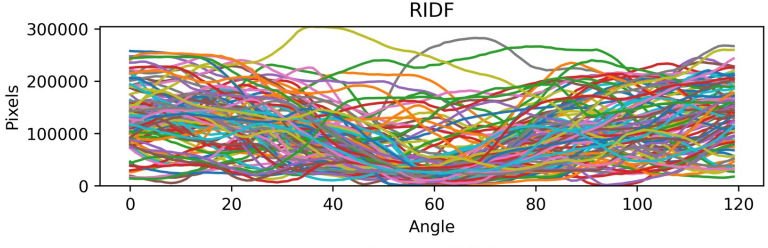
Navigation stats: RMSD error: 613.15; RMSD/dist: 1.533; TD: 74980; p90: 44; p50: 24; complete: 0

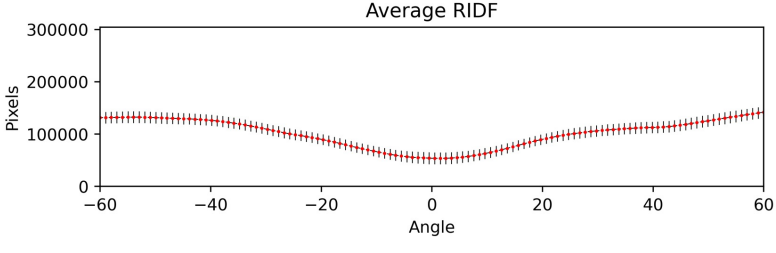
0%







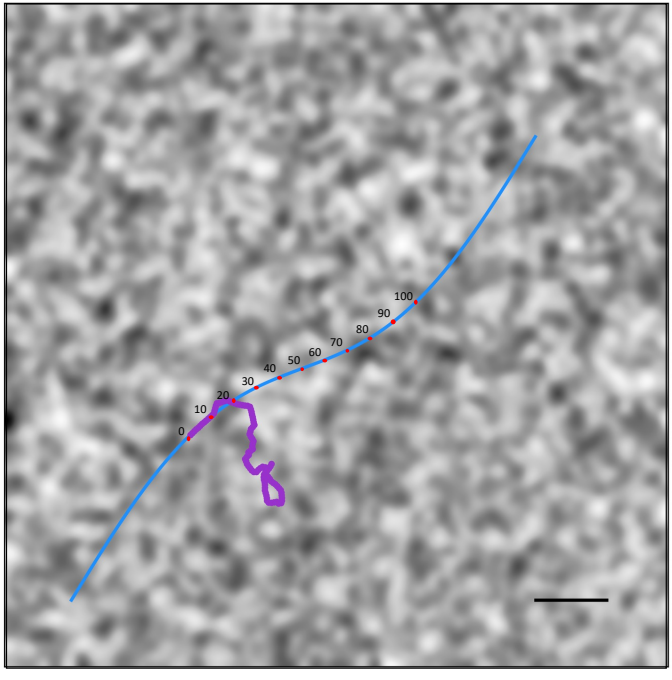


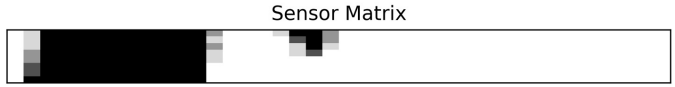


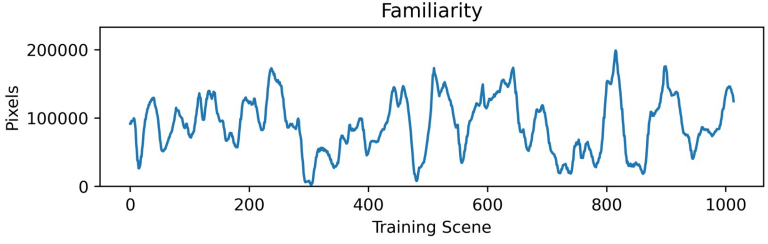
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

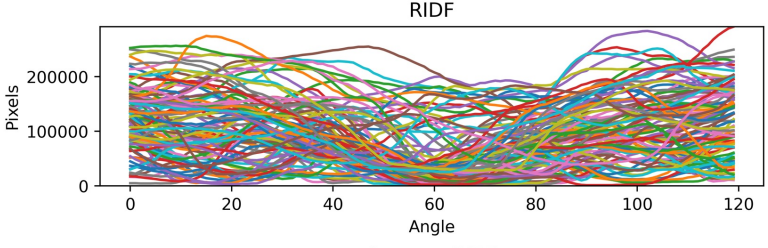
Navigation stats: RMSD error: 3954.38; RMSD/dist: 9.886; TD: 47074; p90: 46; p50: 30; complete: 0

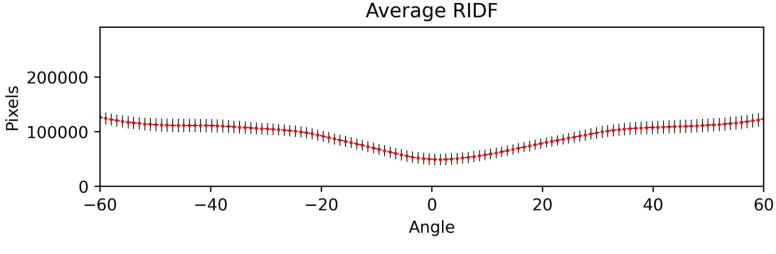
10%







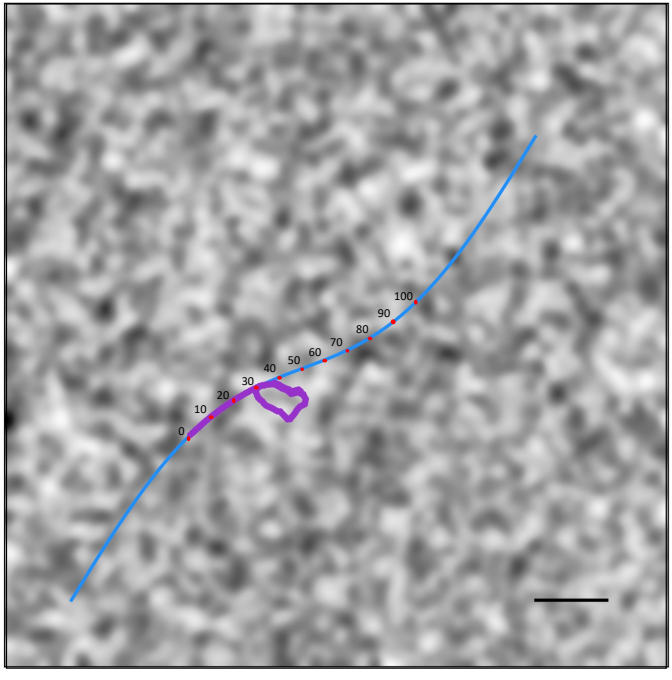


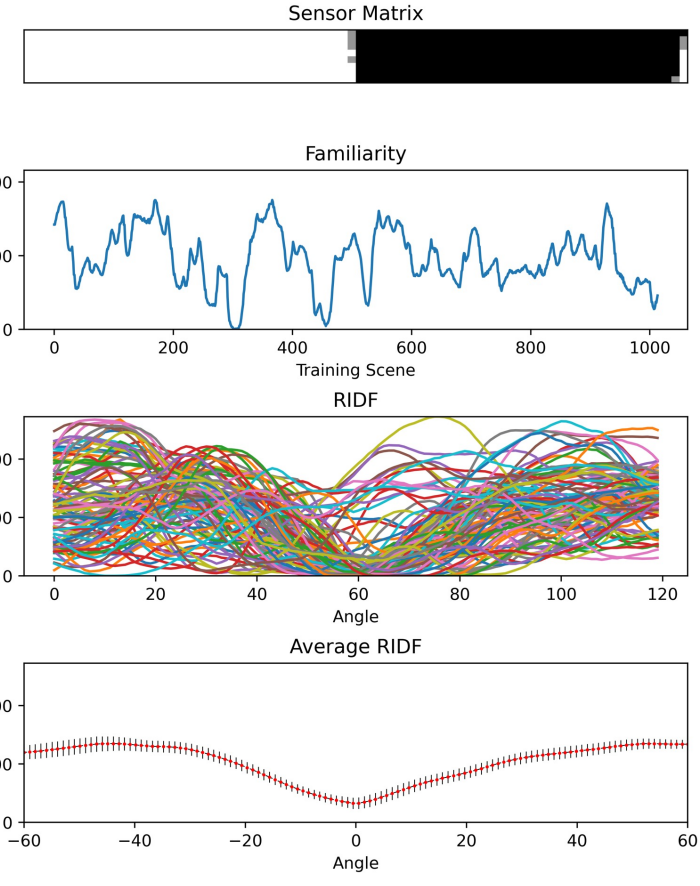


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 7662.55; RMSD/dist: 19.156; TD: 54809; p90: 46; p50: 28; complete: 0

30%

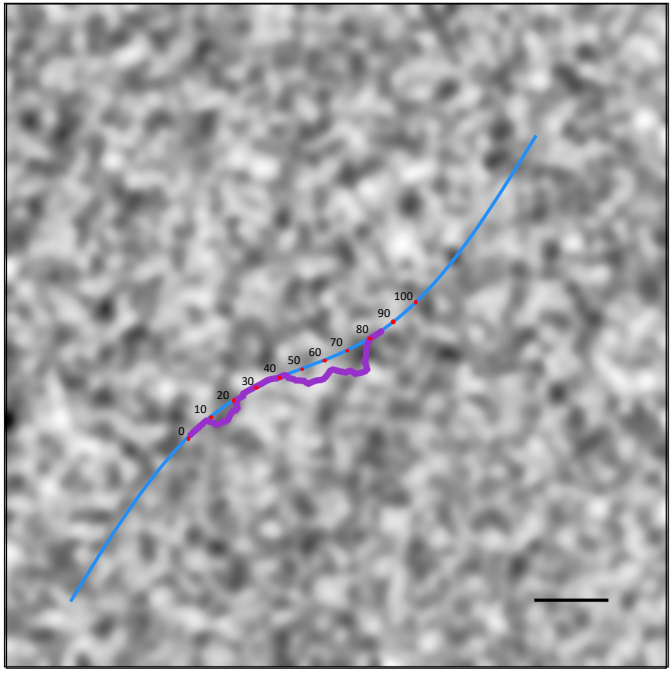


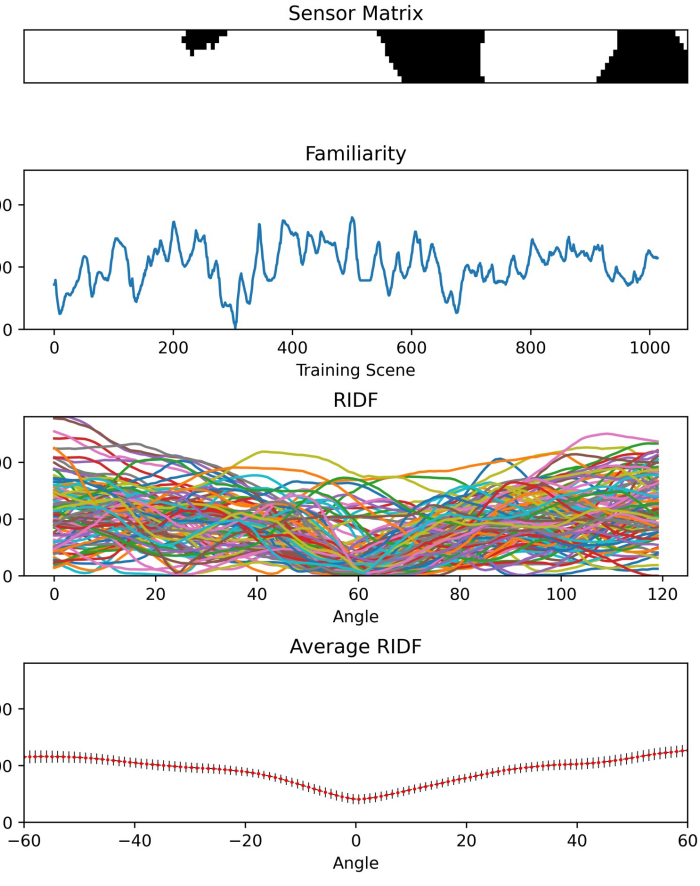


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1838.47; RMSD/dist: 4.596; TD: 54799; p90: 34; p50: 24; complete: 0

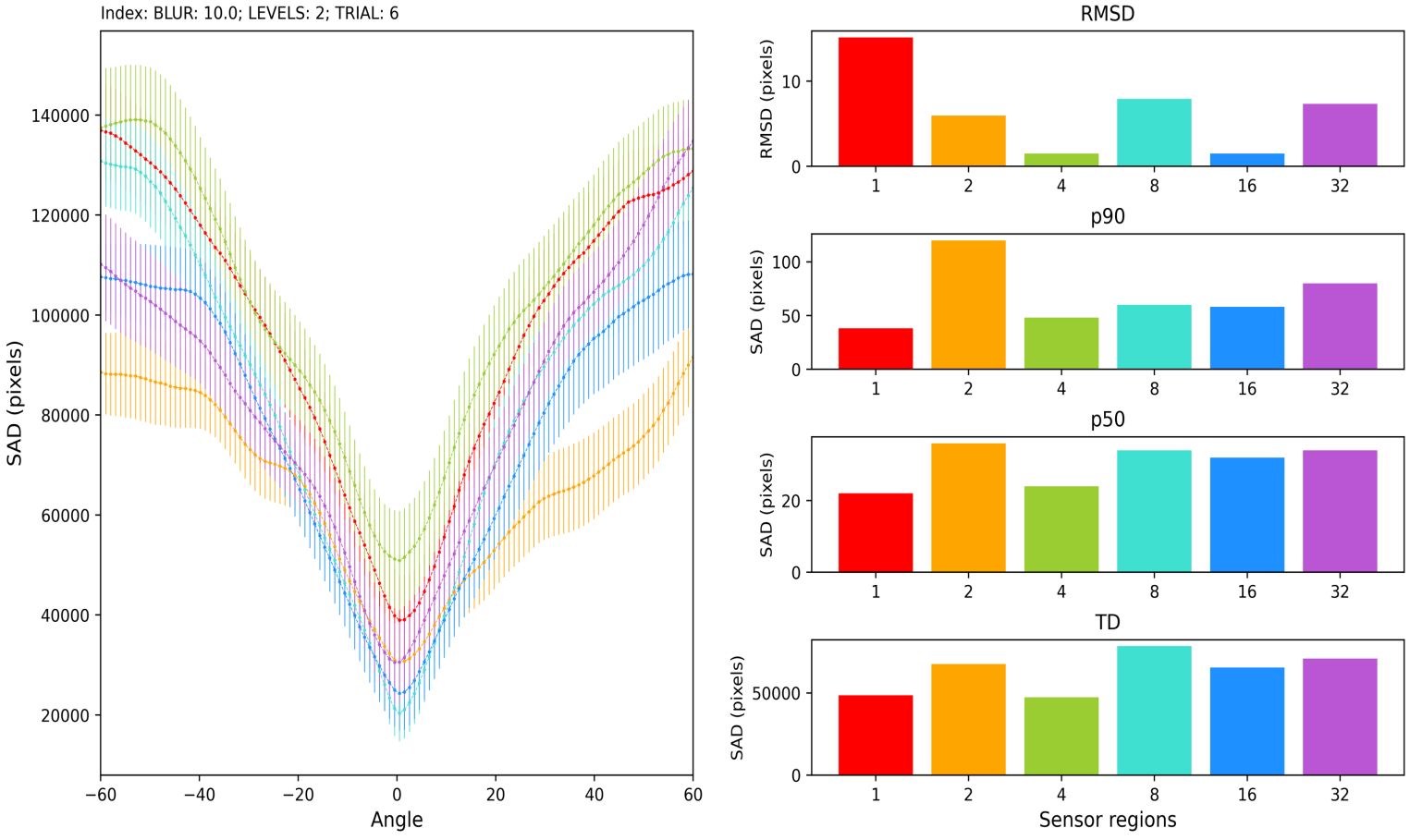
30%



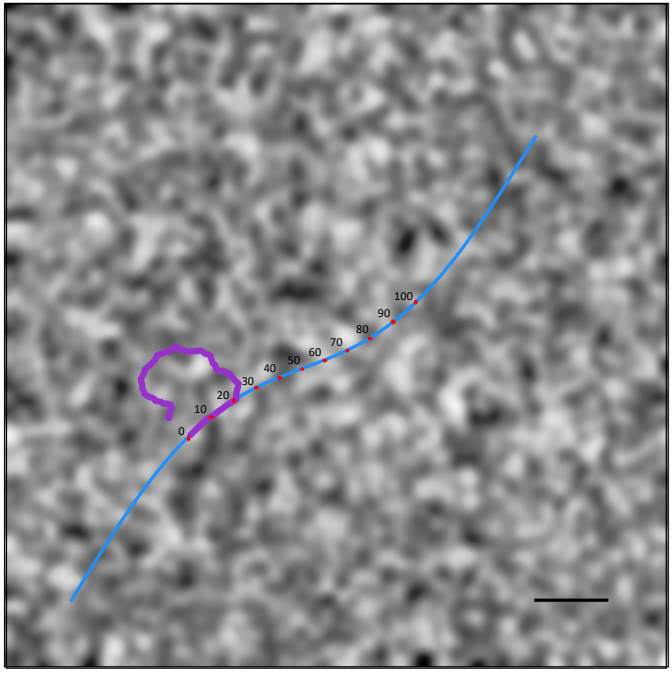


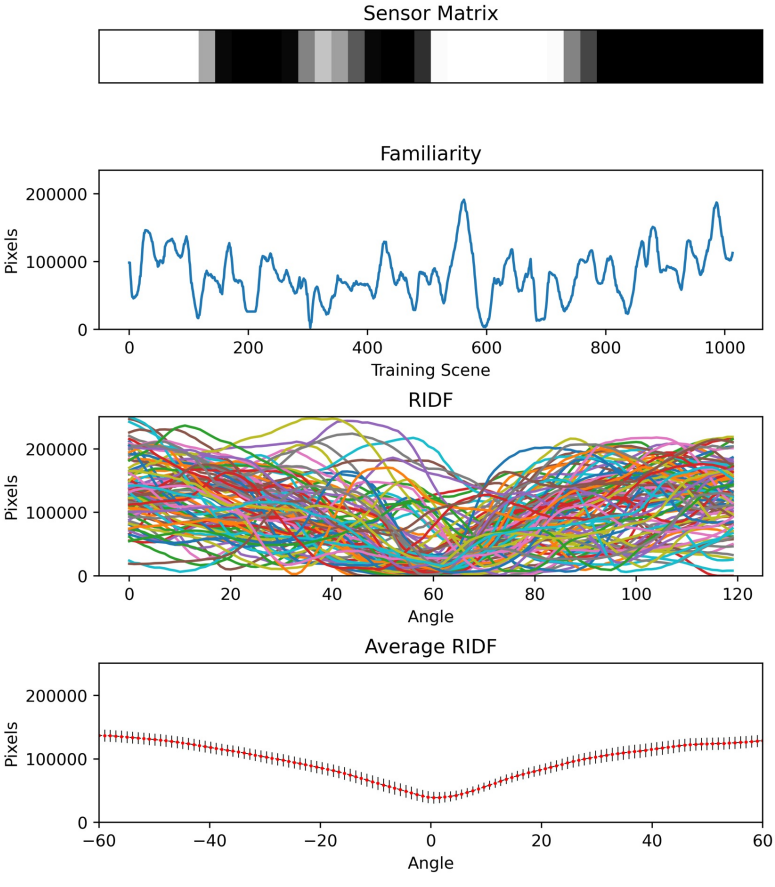
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1304.26; RMSD/dist: 3.261; TD: 59275; p90: 50; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 2; TRIAL: 6
SAD (pixels)
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
20
TD
50000
Sensor regions

20%

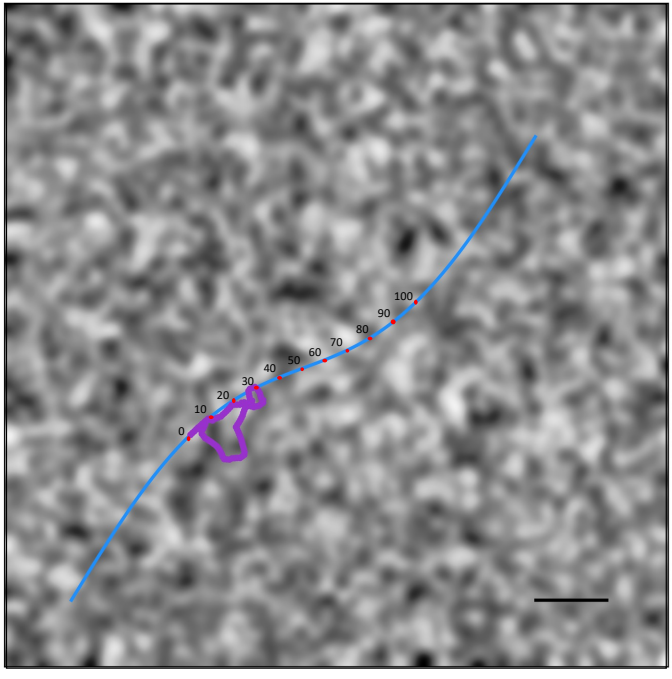


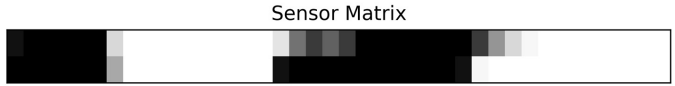


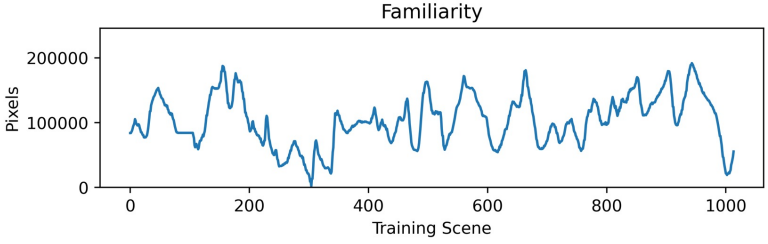
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

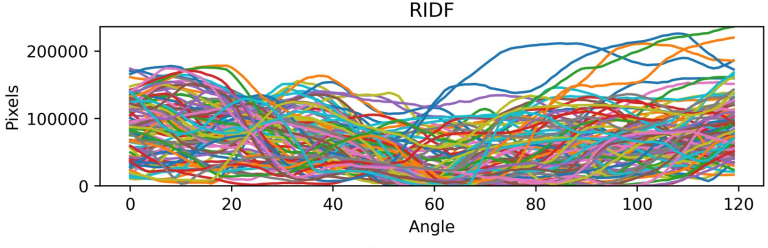
Navigation stats: RMSD error: 6064.01; RMSD/dist: 15.160; TD: 48522; p90: 38; p50: 22; complete: 0

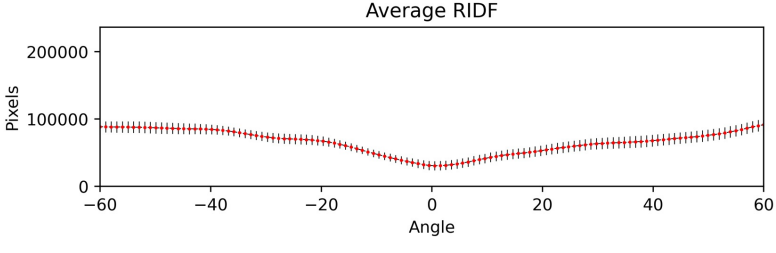
10%







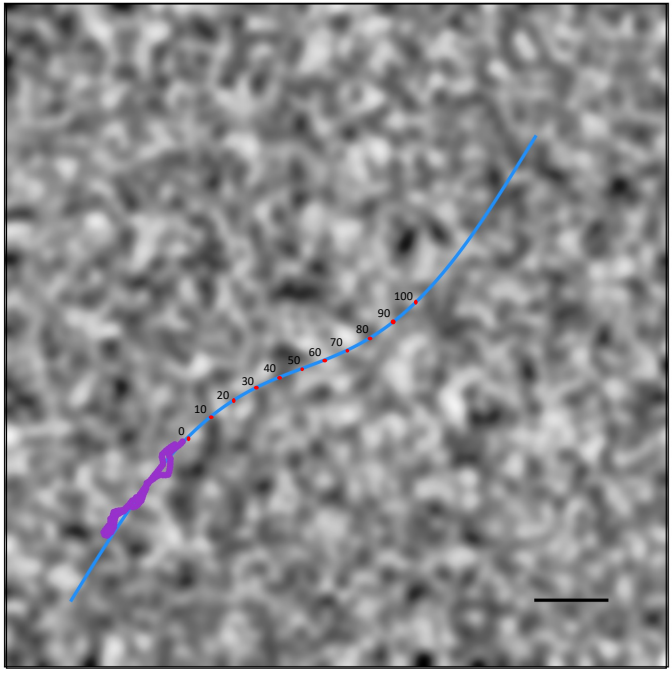


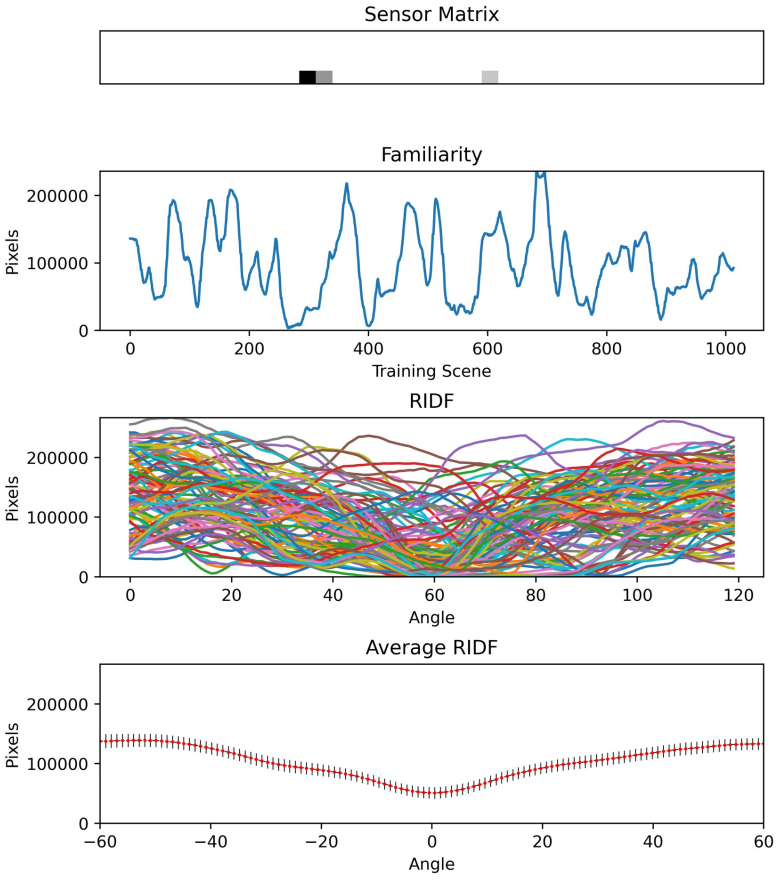


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2387.34; RMSD/dist: 5.968; TD: 67617; p90: 120; p50: 36; complete: 0

0%

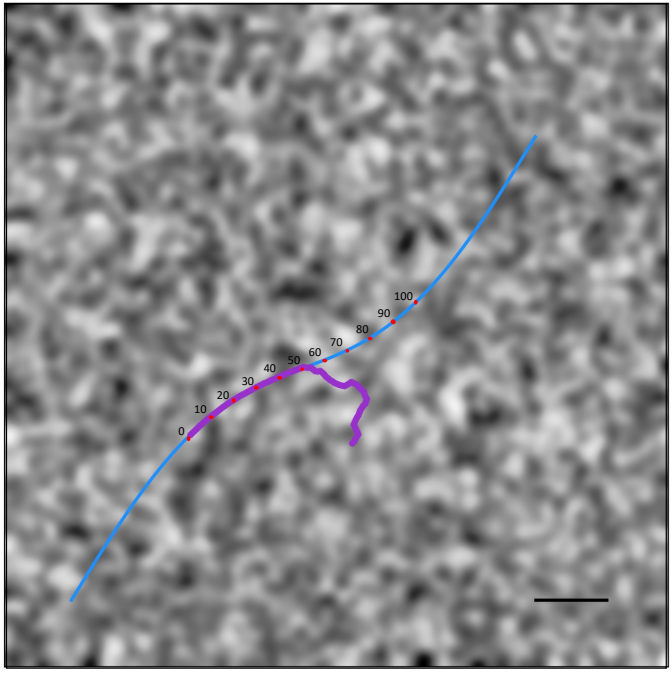


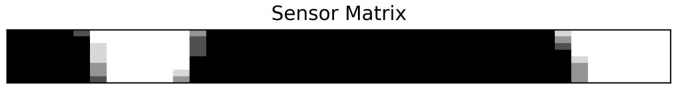


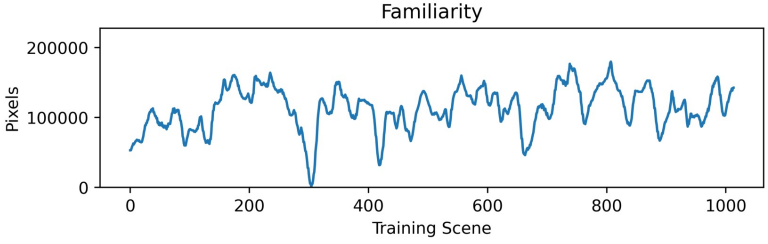
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

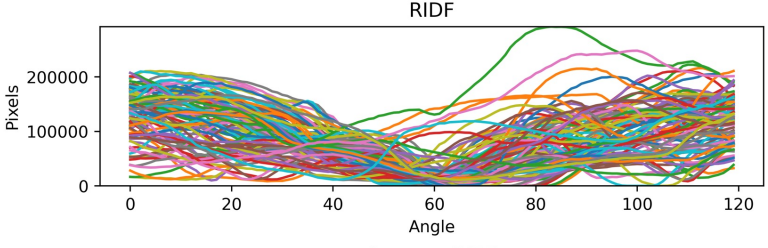
Navigation stats: RMSD error: 595.51; RMSD/dist: 1.489; TD: 47308; p90: 48; p50: 24; complete: 0

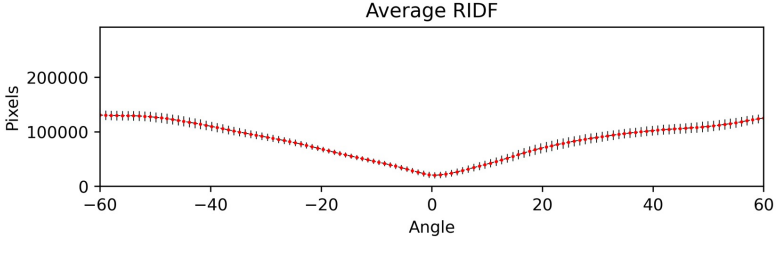
50%







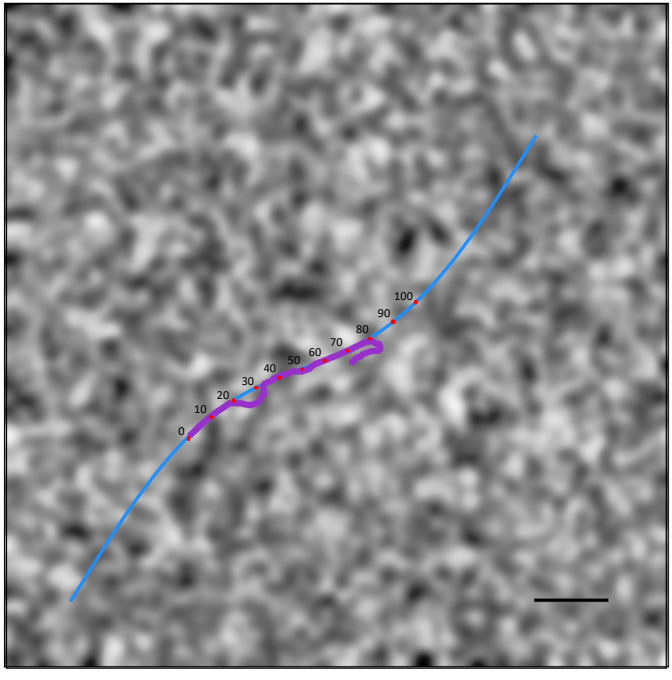


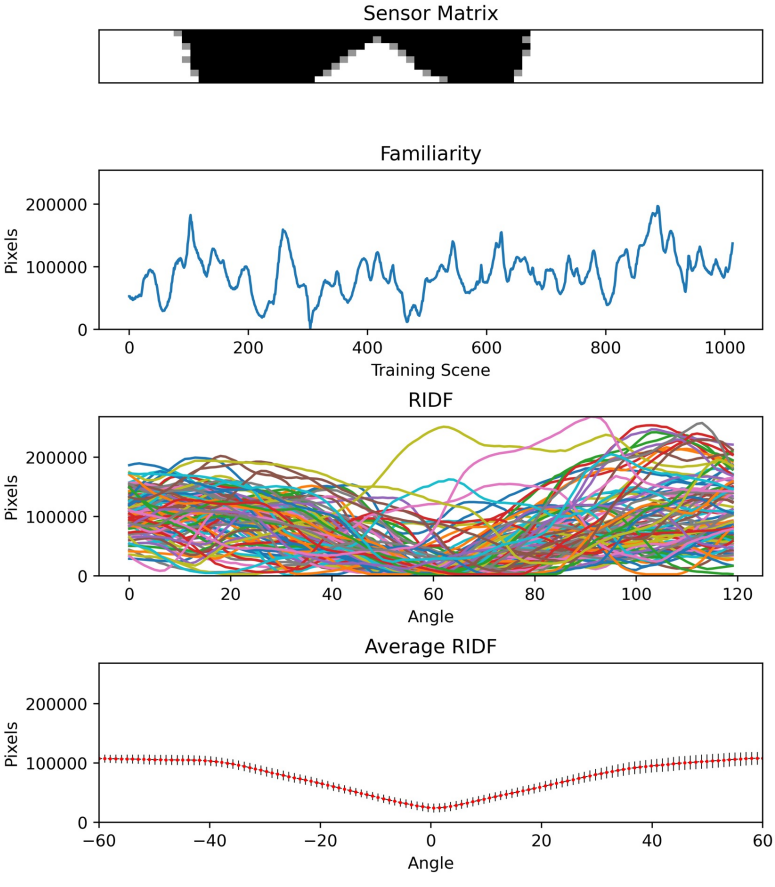


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3173.25; RMSD/dist: 7.933; TD: 78441; p90: 60; p50: 34; complete: 0

60%

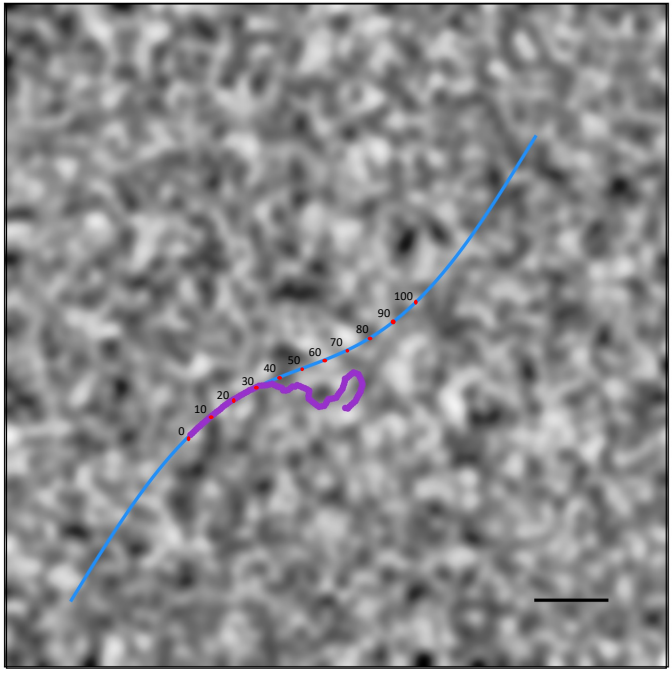


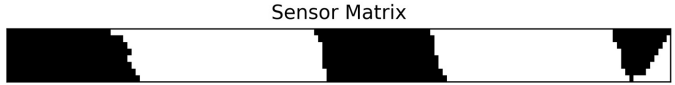


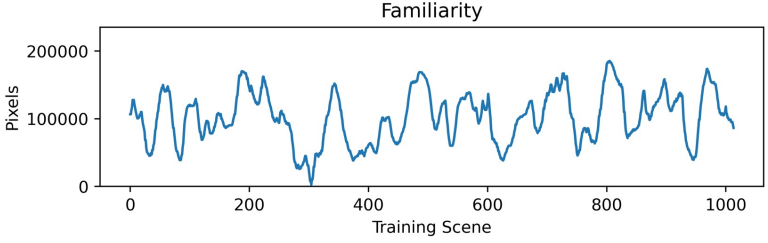
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

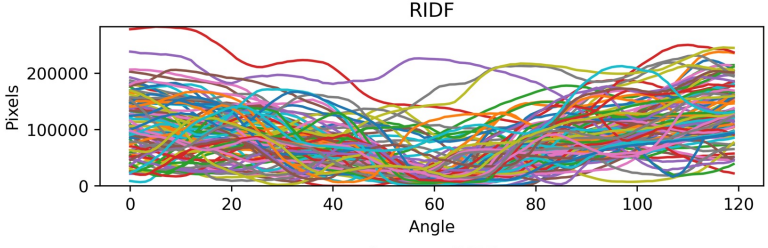
Navigation stats: RMSD error: 594.47; RMSD/dist: 1.486; TD: 65411; p90: 58; p50: 32; complete: 0

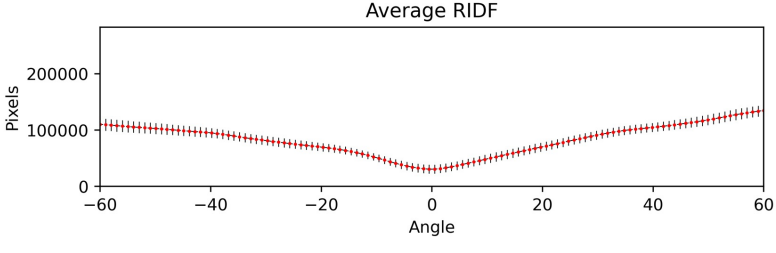
30%





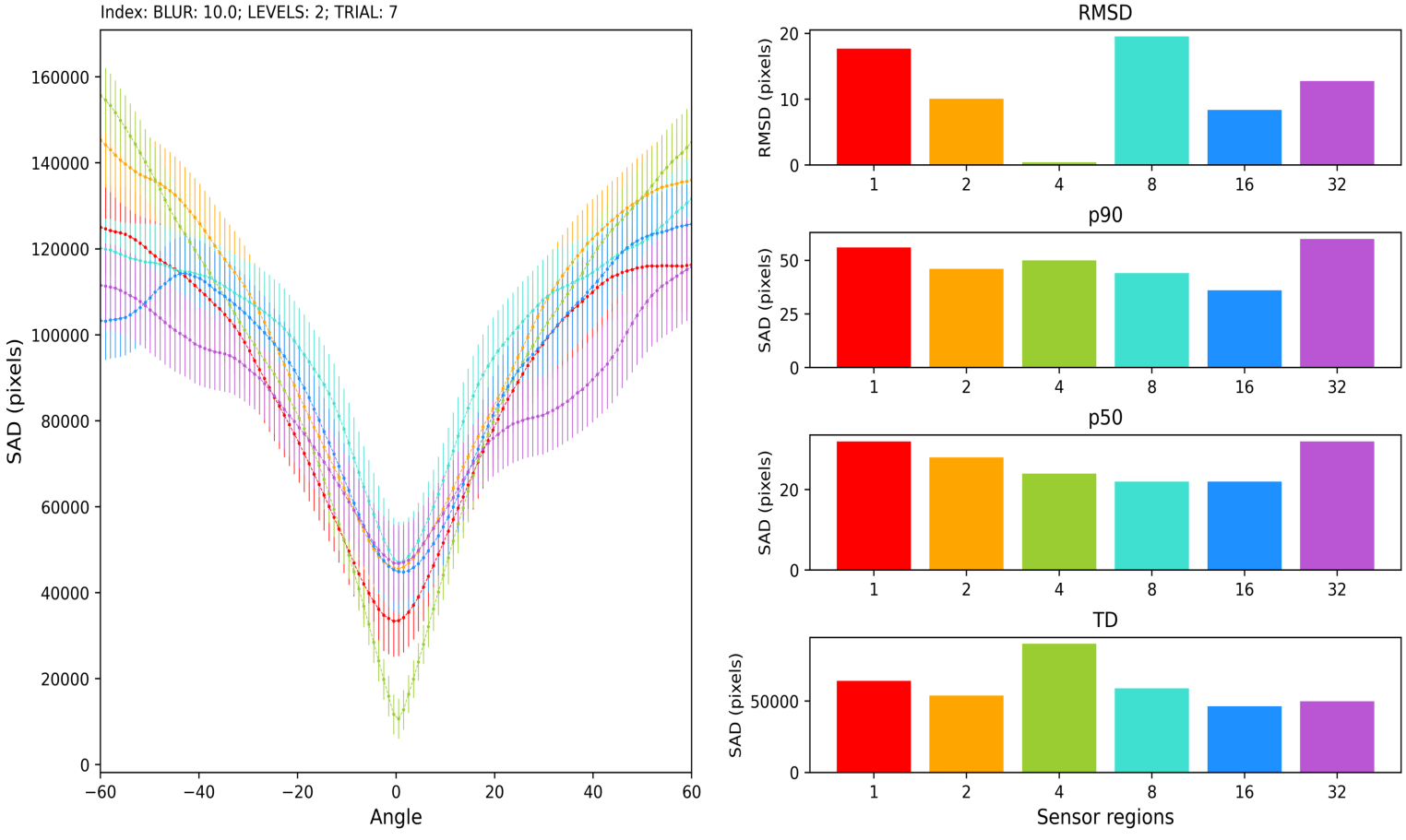




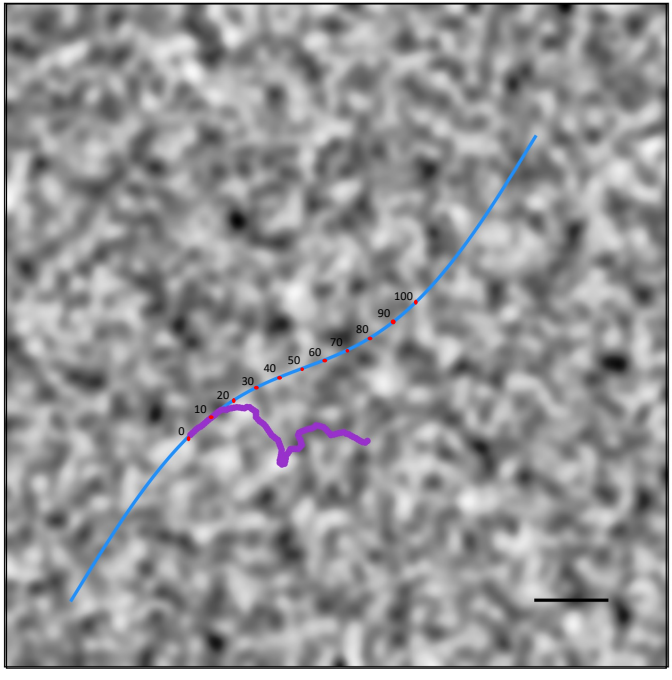


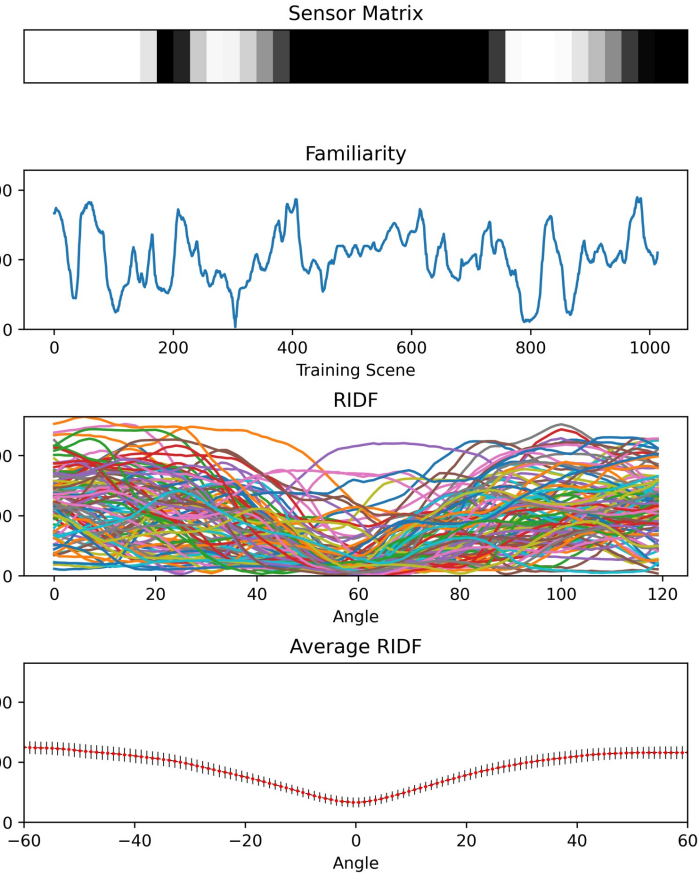
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2934.10; RMSD/dist: 7.335; TD: 70863; p90: 80; p50: 34; complete: 0


Index: BLUR: 10.0; LEVELS: 2; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

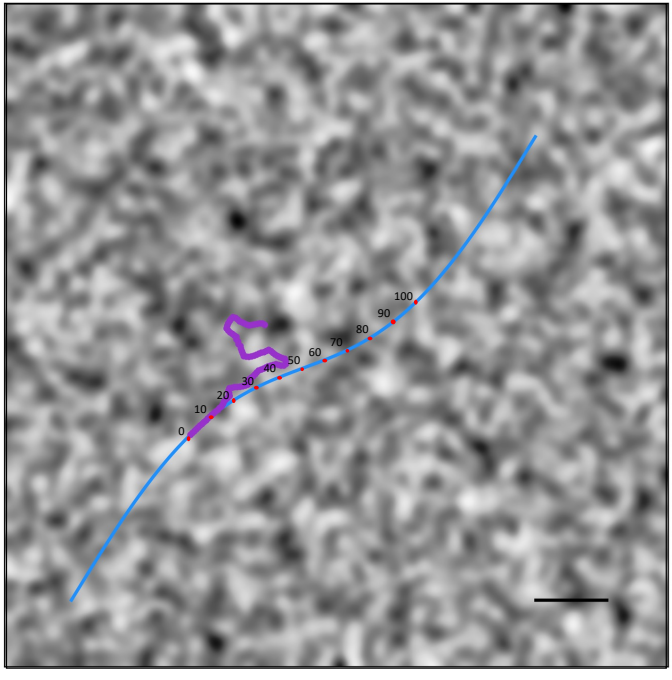


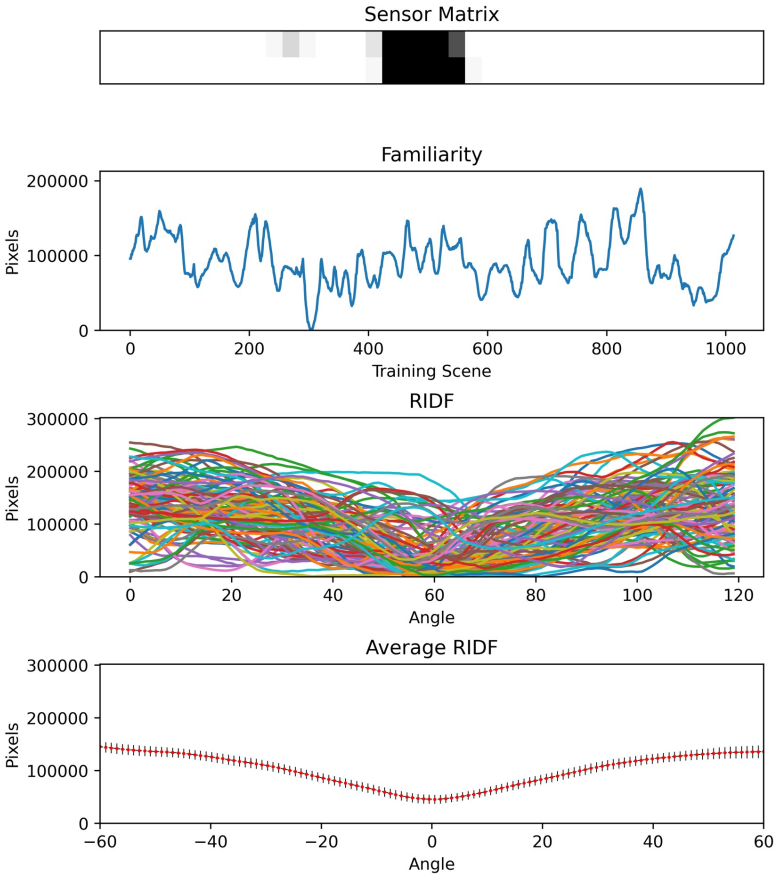


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 7078.12; RMSD/dist: 17.695; TD: 64114; p90: 56; p50: 32; complete: 0

10%

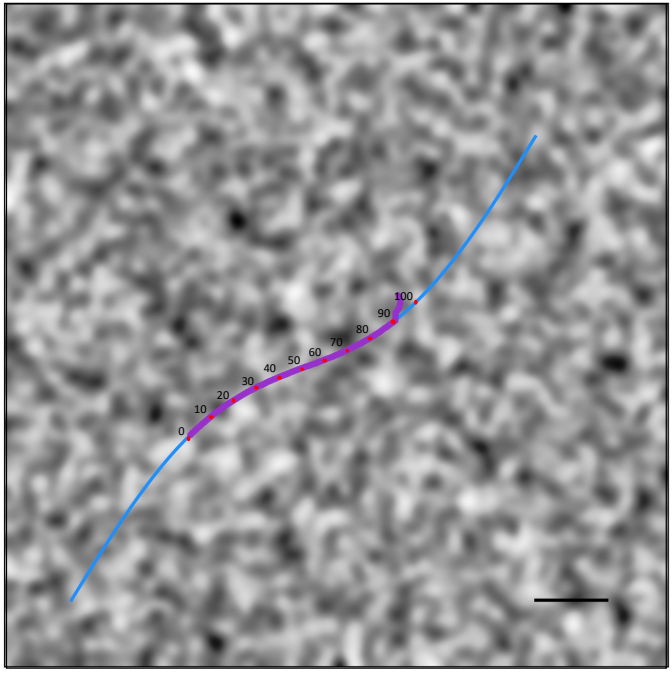


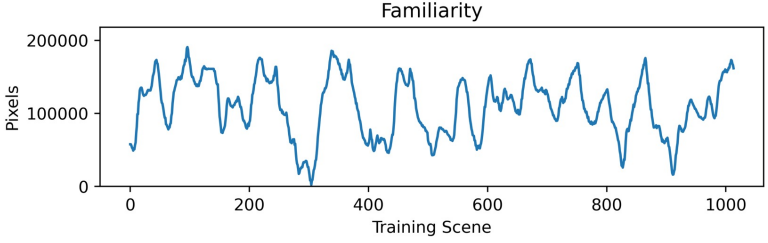


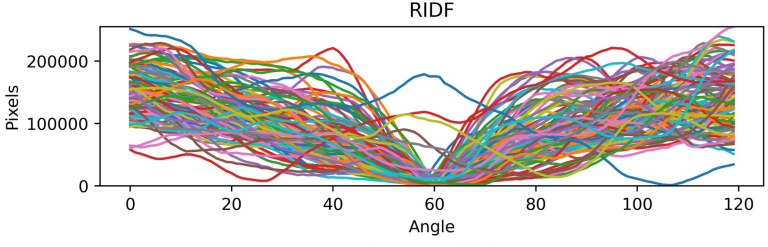
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

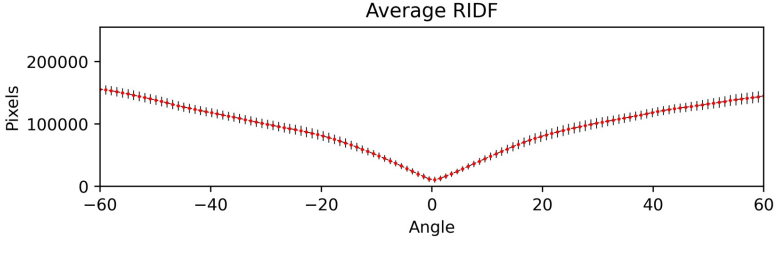
Navigation stats: RMSD error: 4028.36; RMSD/dist: 10.071; TD: 53802; p90: 46; p50: 28; complete: 0

90%





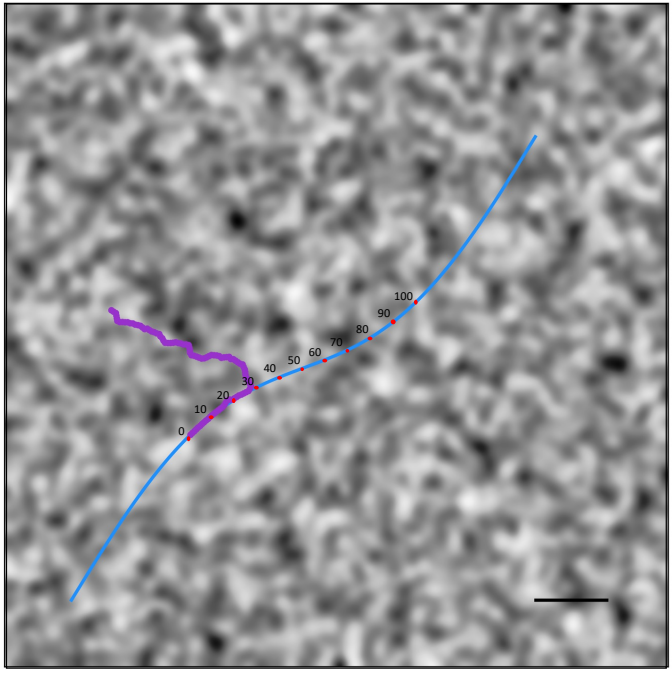


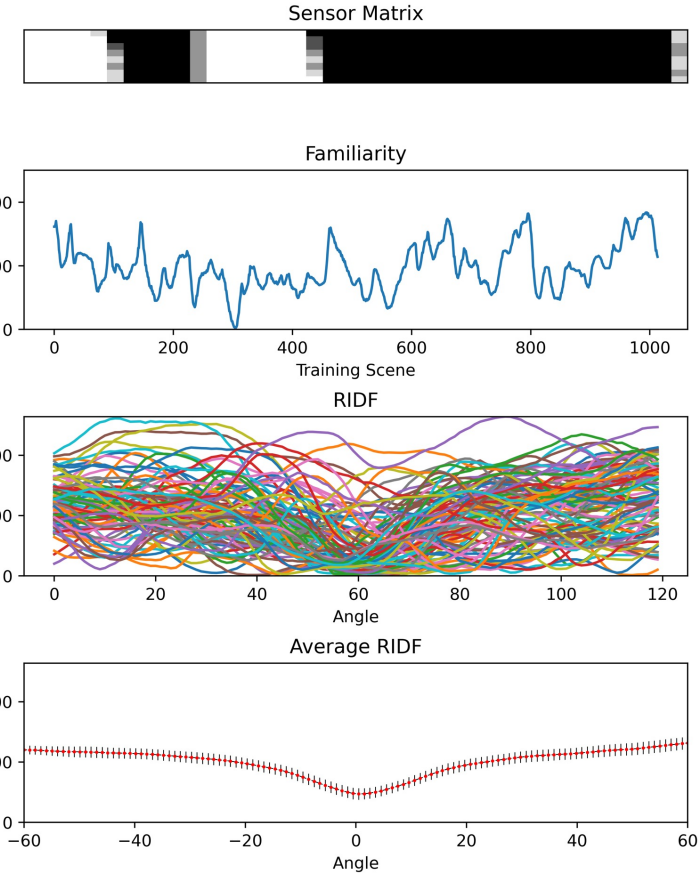


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 163.26; RMSD/dist: 0.408; TD: 89969; p90: 50; p50: 24; complete: 0

20%

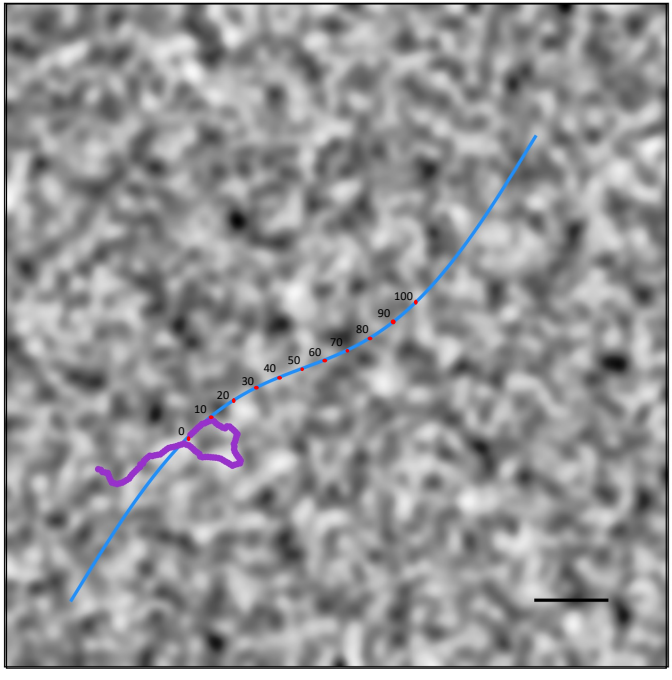


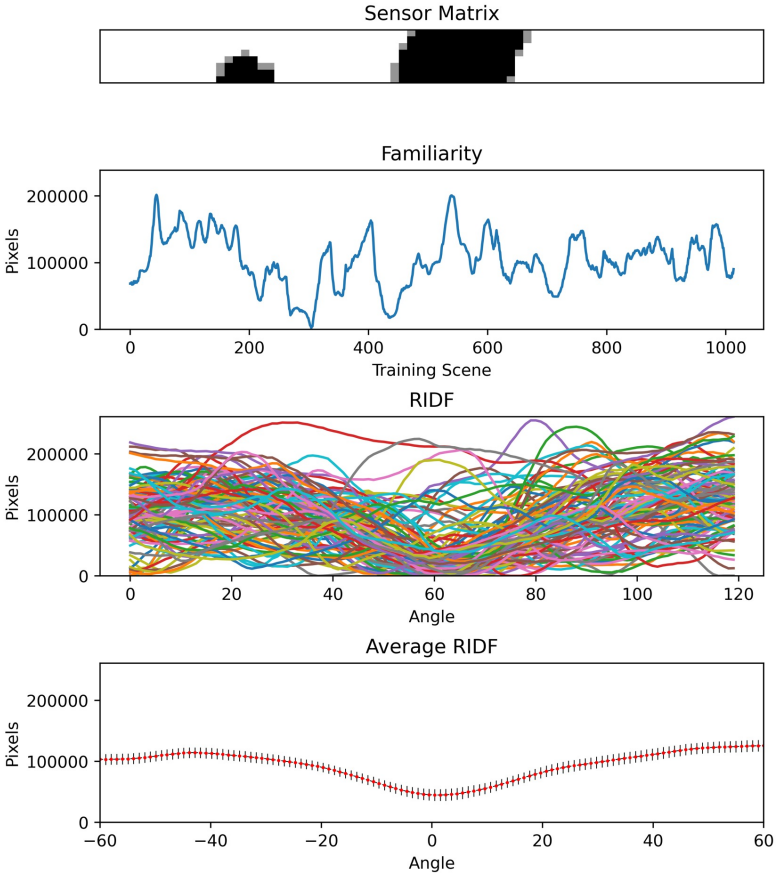


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 7817.48; RMSD/dist: 19.544; TD: 58814; p90: 44; p50: 22; complete: 0

10%

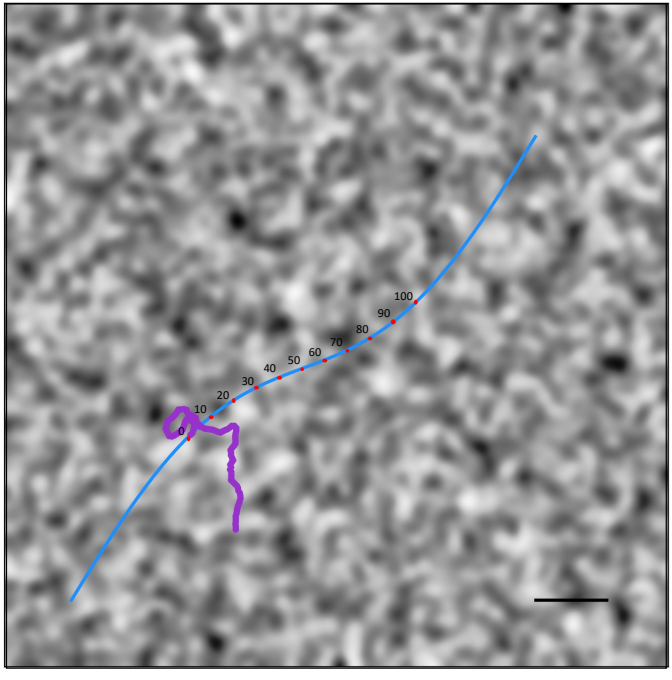


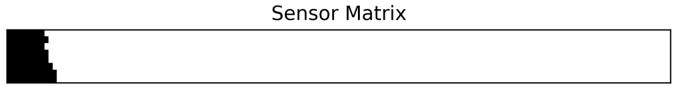


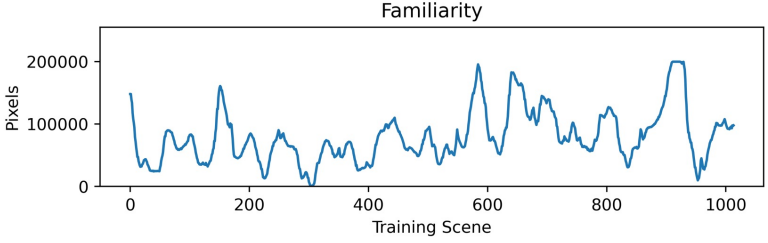
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

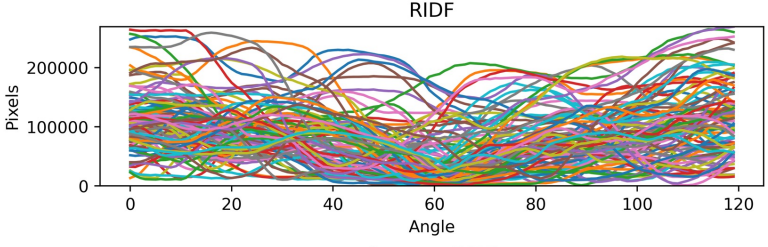
Navigation stats: RMSD error: 3345.08; RMSD/dist: 8.363; TD: 46271; p90: 36; p50: 22; complete: 0

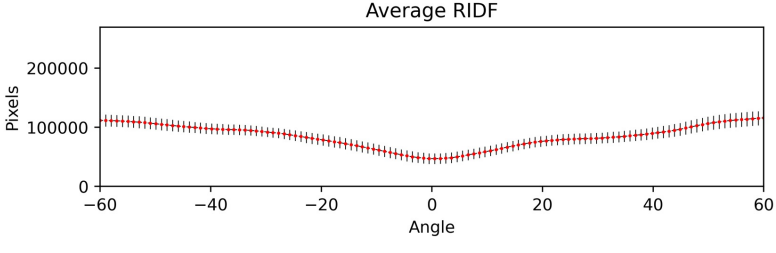
0%





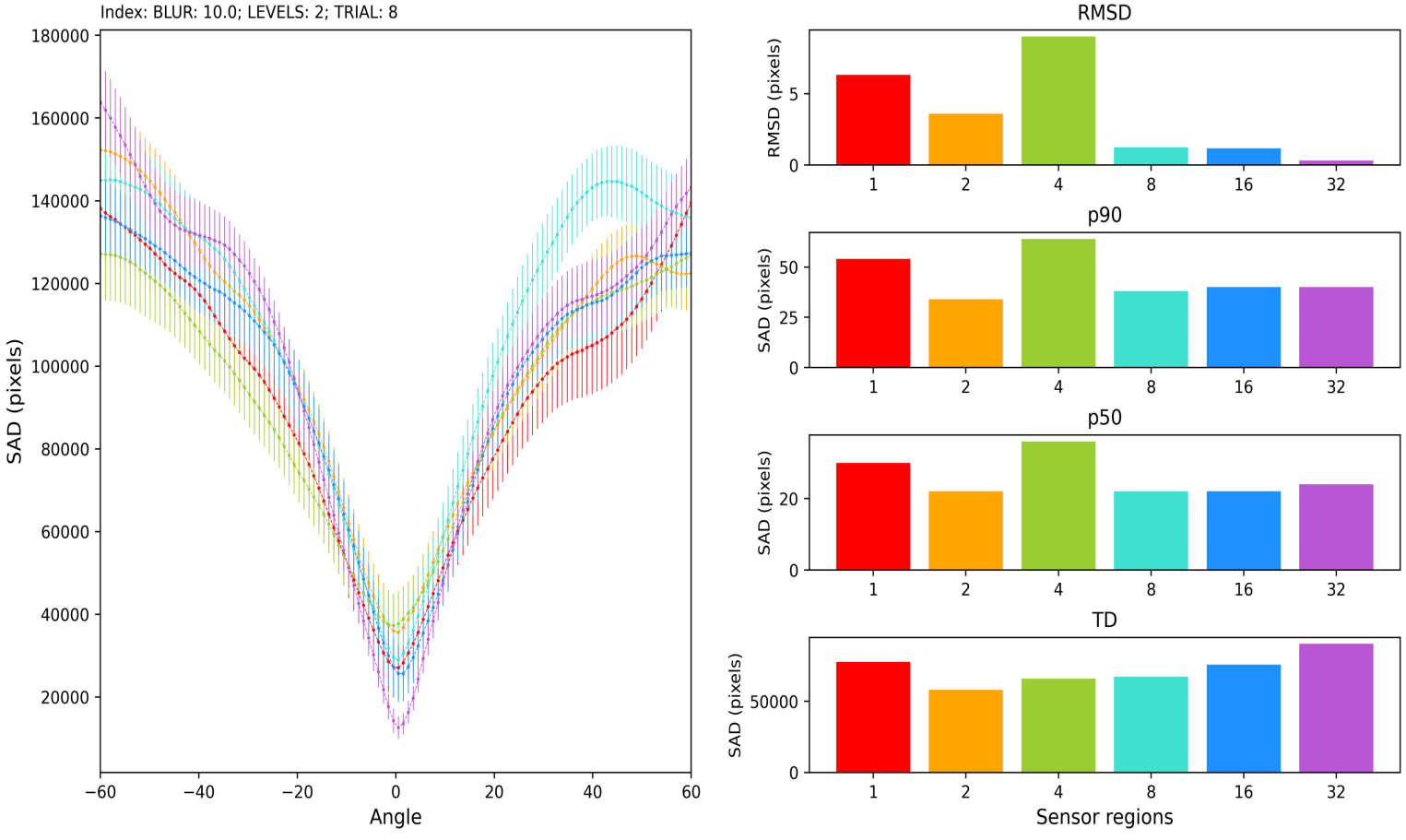




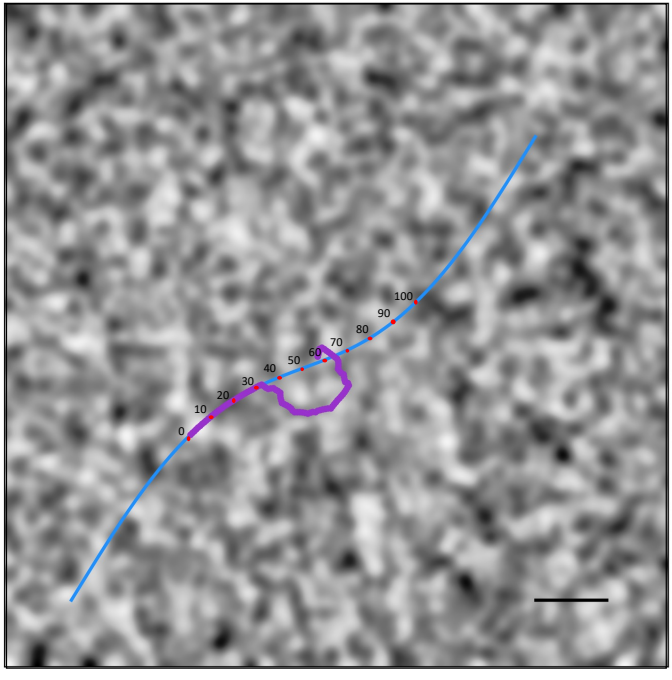


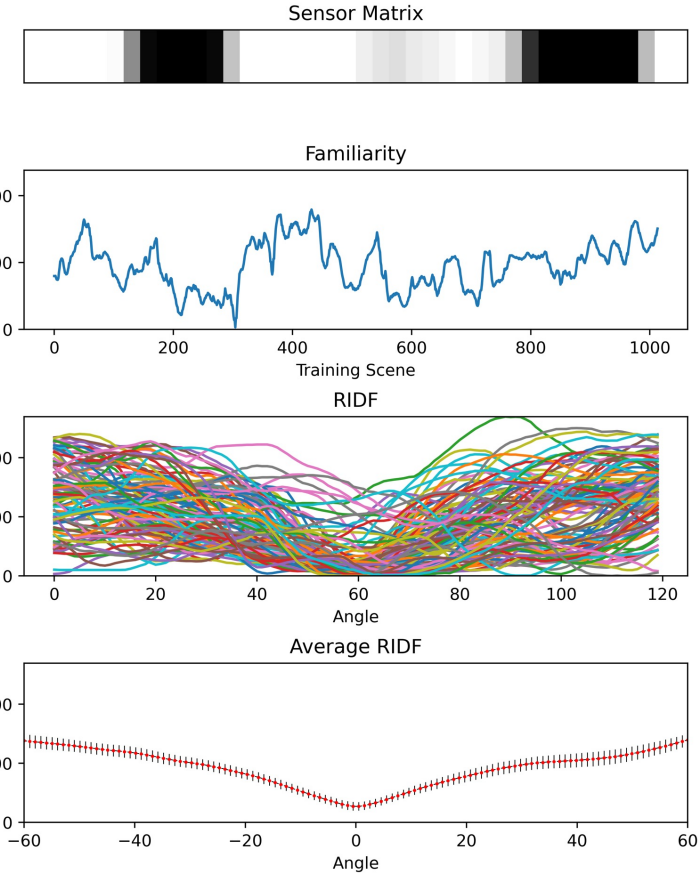
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 5098.80; RMSD/dist: 12.747; TD: 49708; p90: 60; p50: 32; complete: 0


Index: BLUR: 10.0; LEVELS: 2; TRIAL: 8
SAD (pixels)
180000
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
5
0
1
2
4
8
16
32
p90
SAD (pixels)
50
25
0
p50
20
TD
50000
Sensor regions

30%

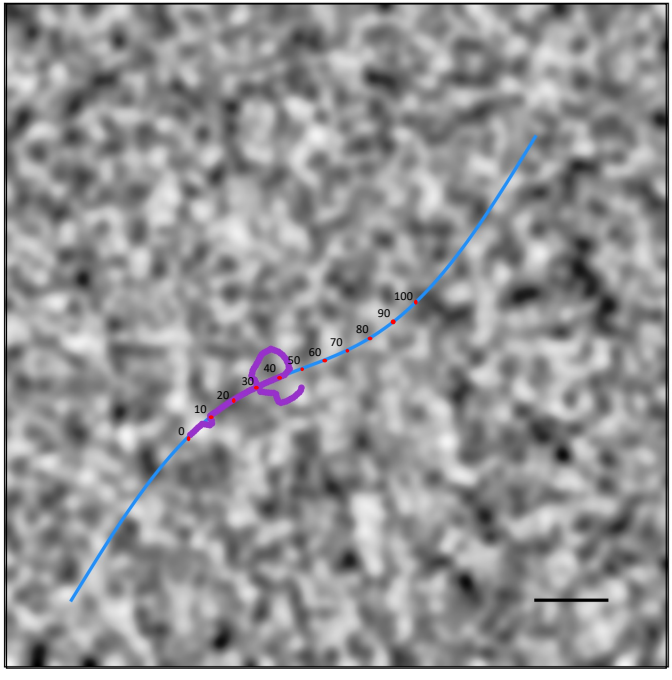


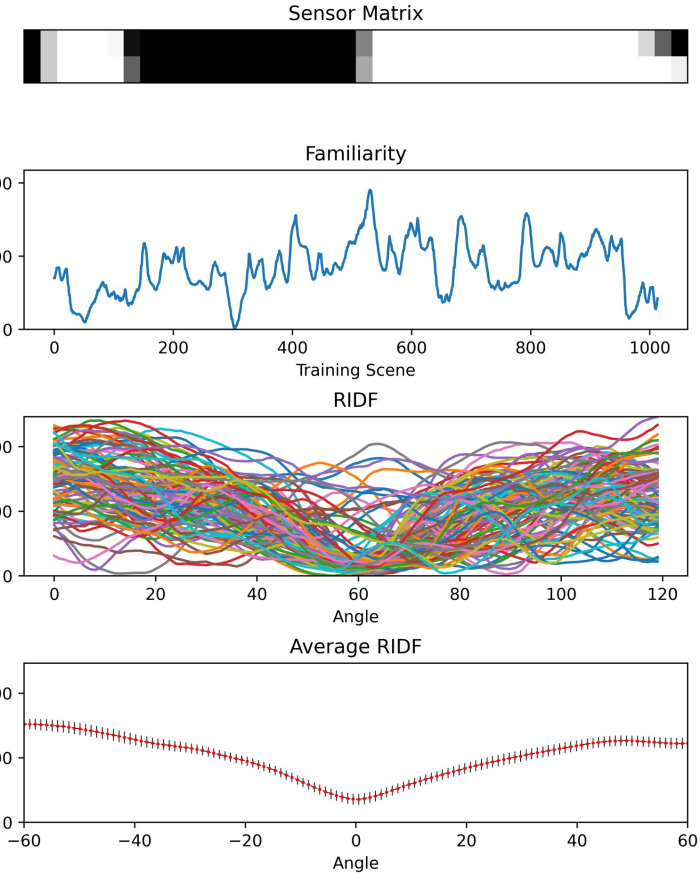


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2528.80; RMSD/dist: 6.322; TD: 77507; p90: 54; p50: 30; complete: 0

40%

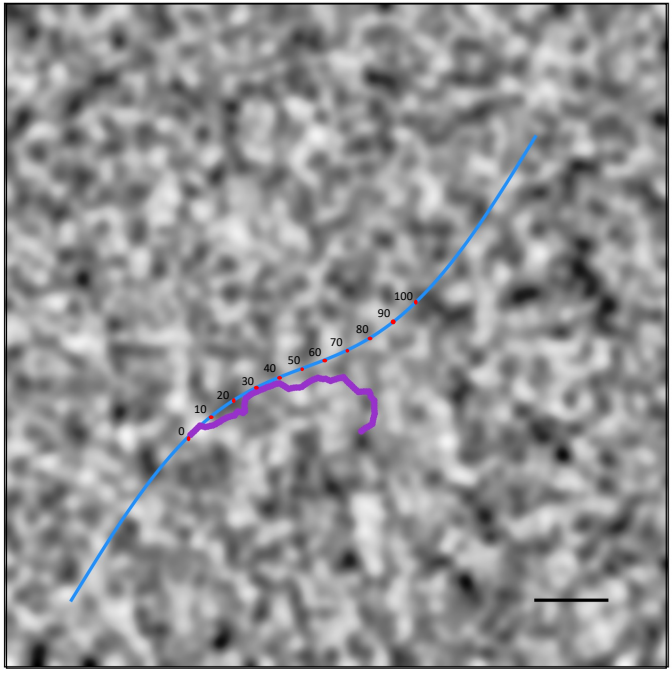


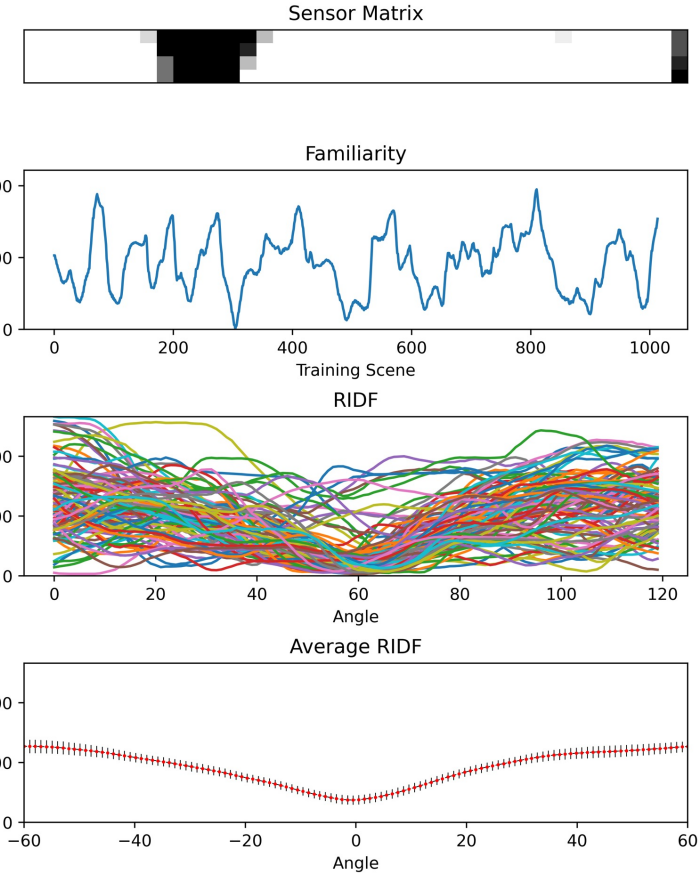


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1438.99; RMSD/dist: 3.597; TD: 57962; p90: 34; p50: 22; complete: 0

0%

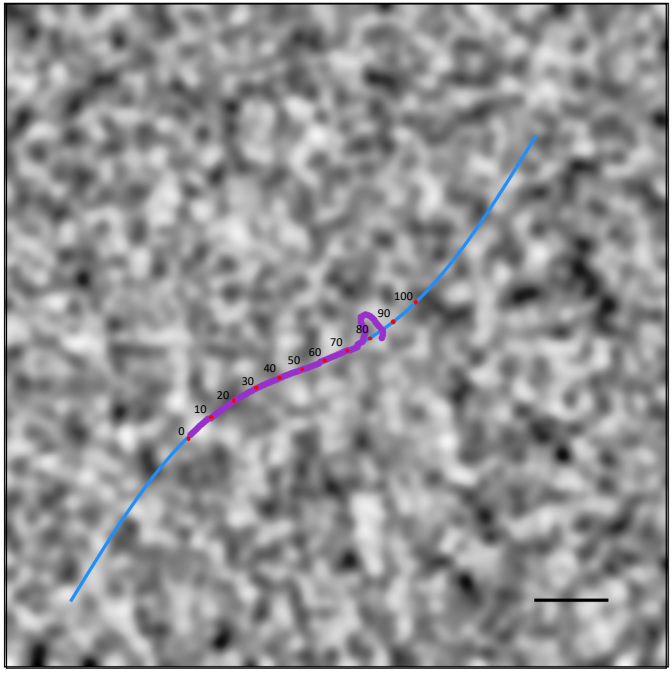


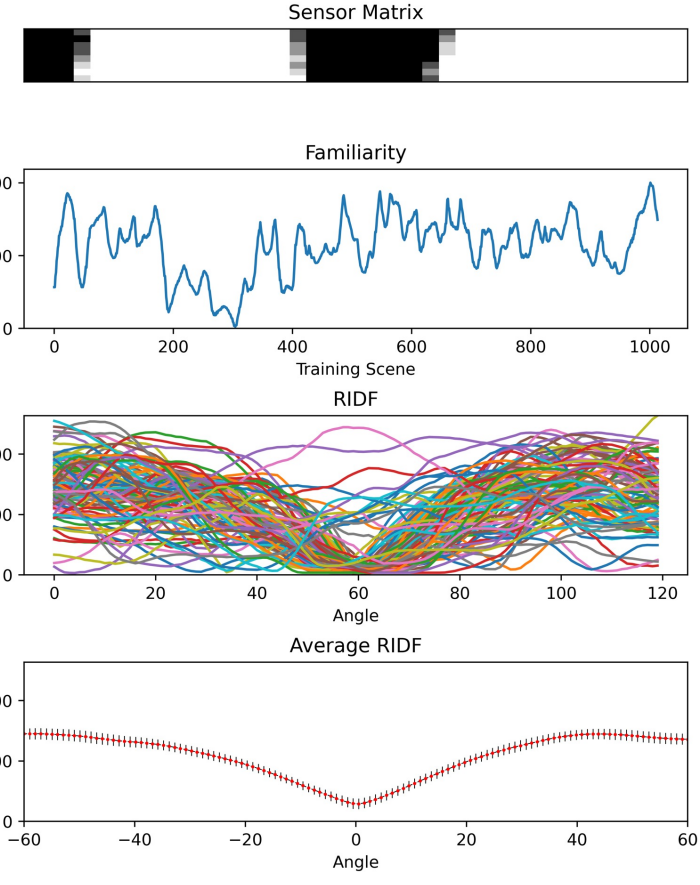


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3605.97; RMSD/dist: 9.015; TD: 65911; p90: 64; p50: 36; complete: 0

70%

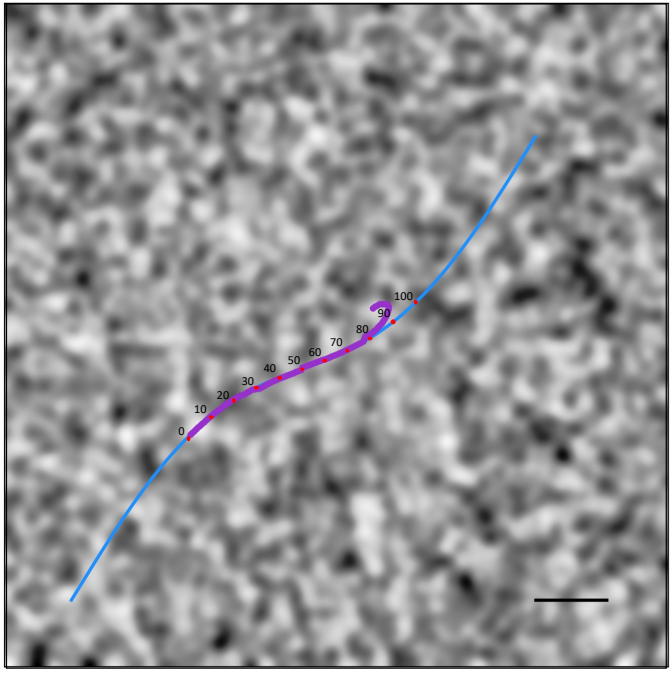


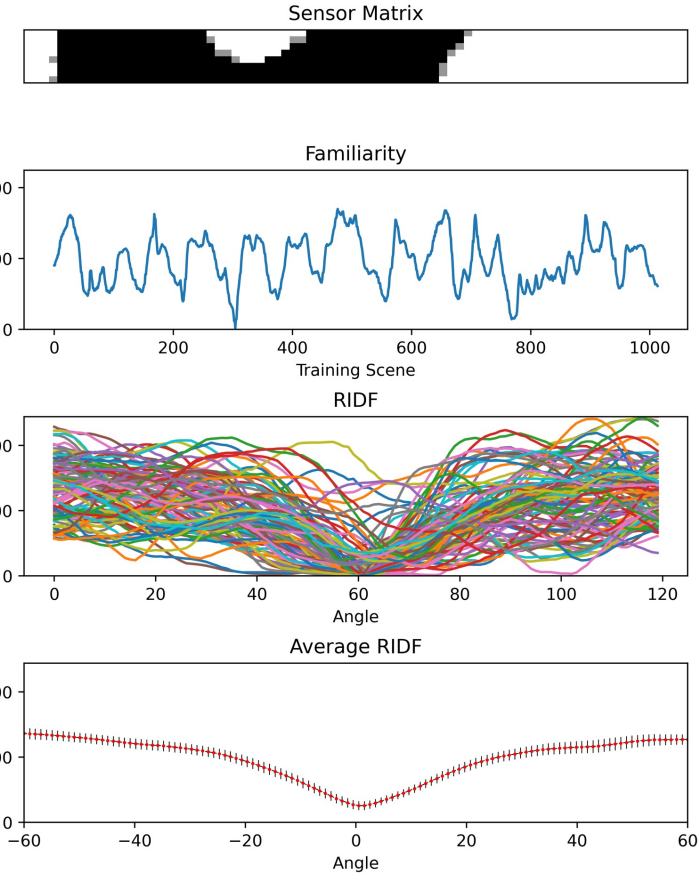


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 492.25; RMSD/dist: 1.231; TD: 67232; p90: 38; p50: 22; complete: 0

70%

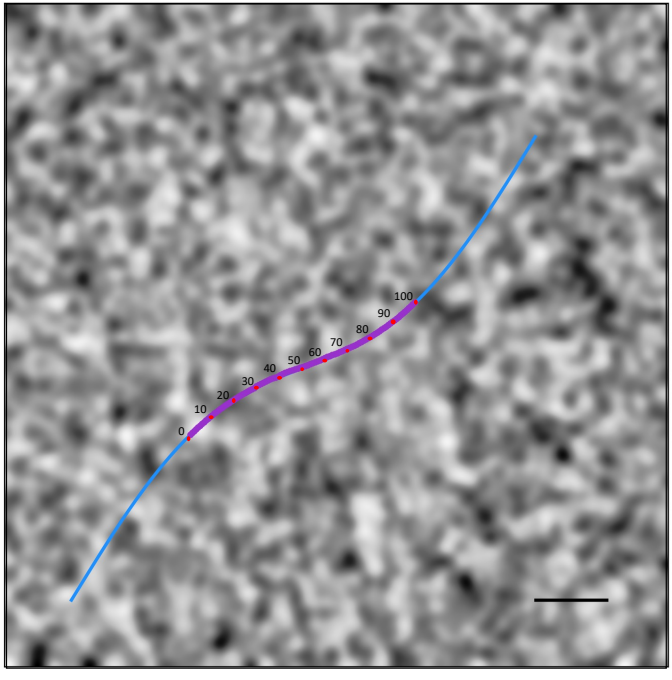


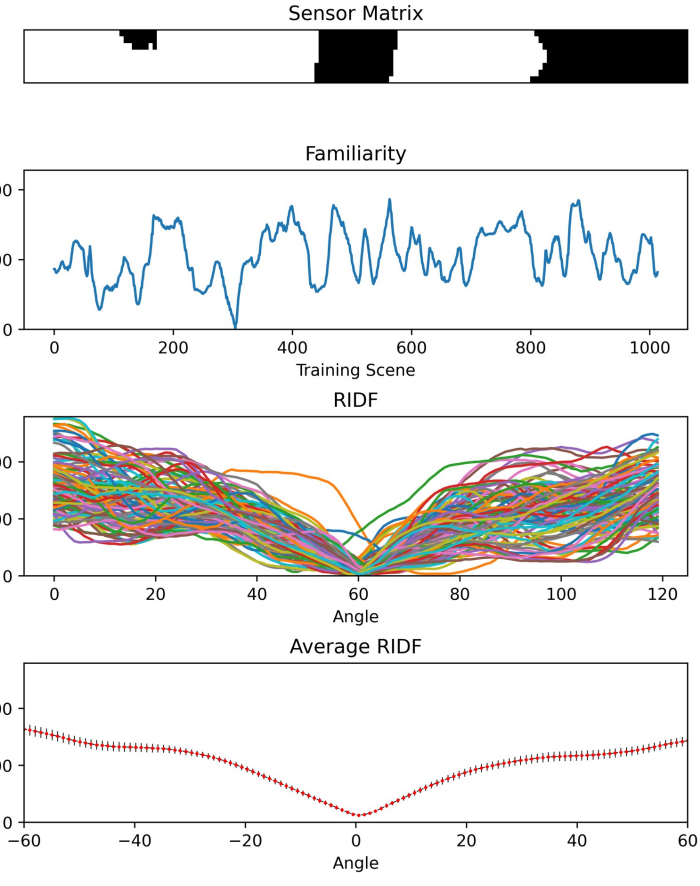


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 466.98; RMSD/dist: 1.167; TD: 75665; p90: 40; p50: 22; complete: 0

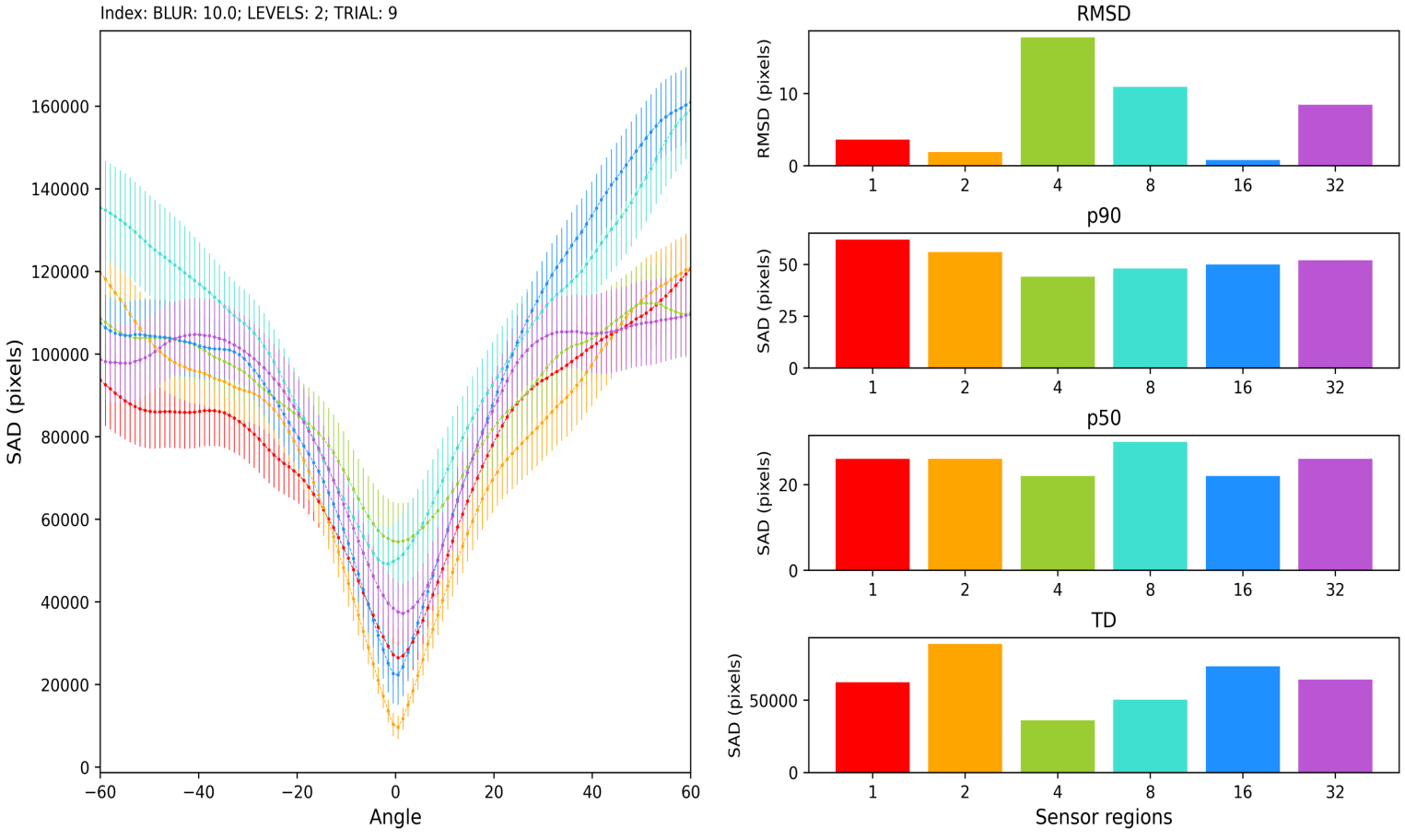
100%



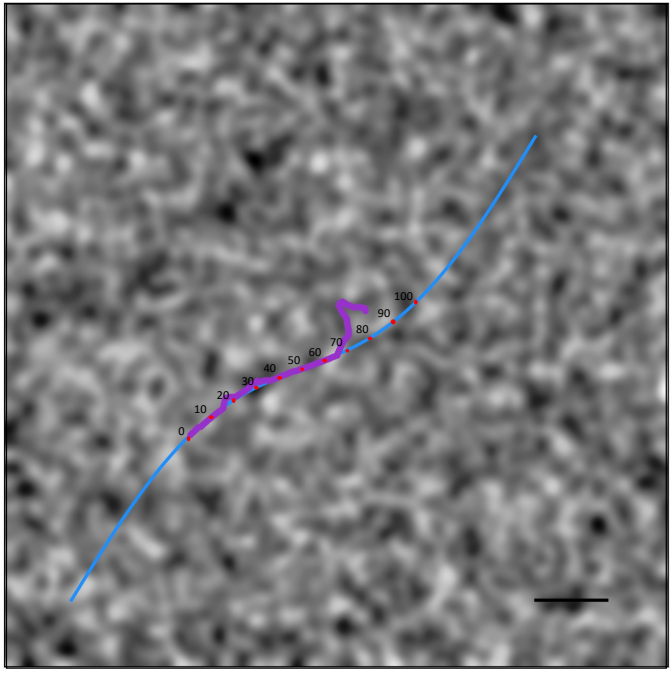


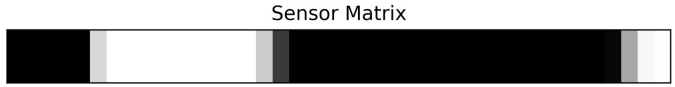
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

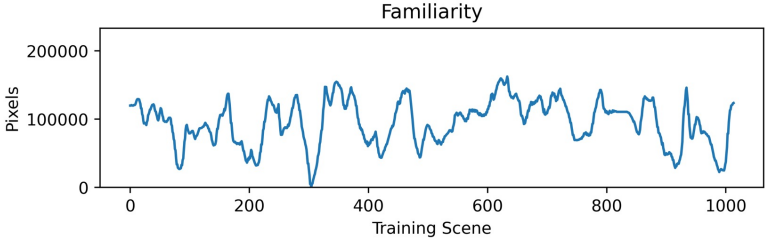
Navigation stats: RMSD error: 127.73; RMSD/dist: 0.319; TD: 90252; p90: 40; p50: 24; complete: 0

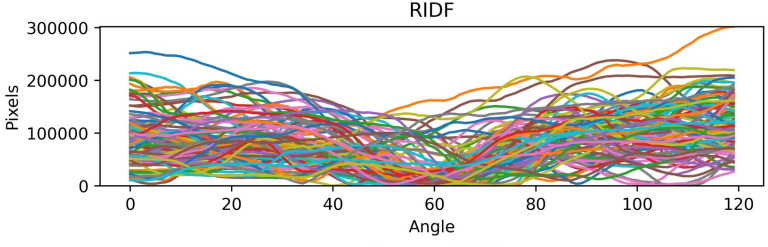

Index: BLUR: 10.0; LEVELS: 2; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

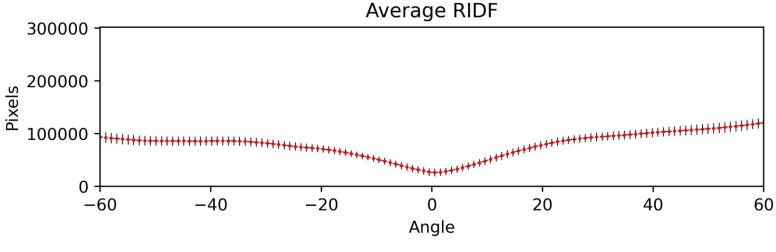
50%







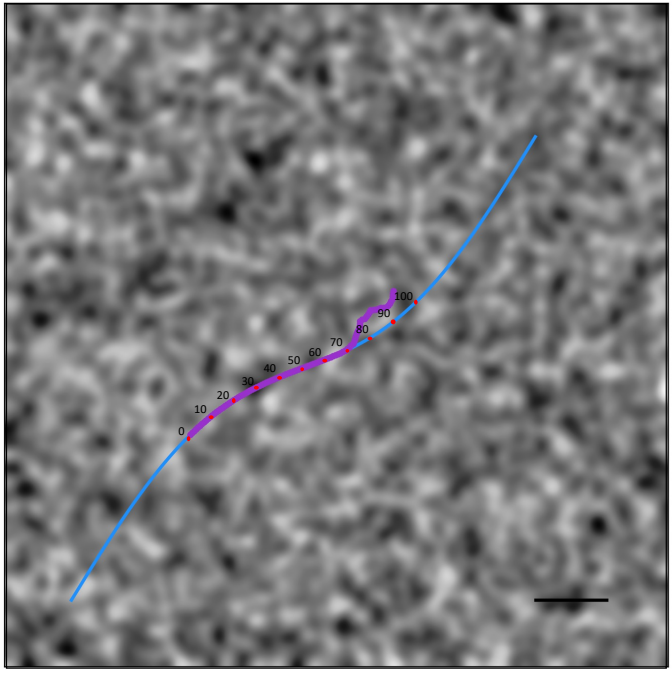


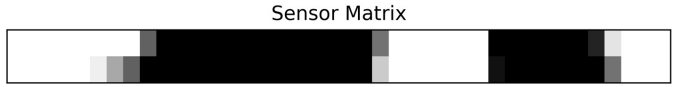


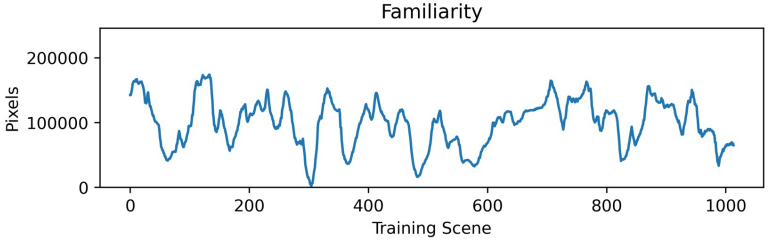
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

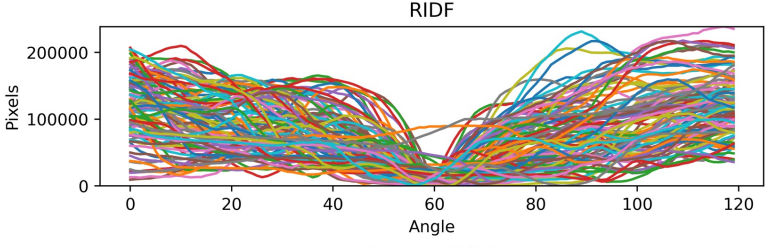
Navigation stats: RMSD error: 1445.77; RMSD/dist: 3.614; TD: 62409; p90: 62; p50: 26; complete: 0

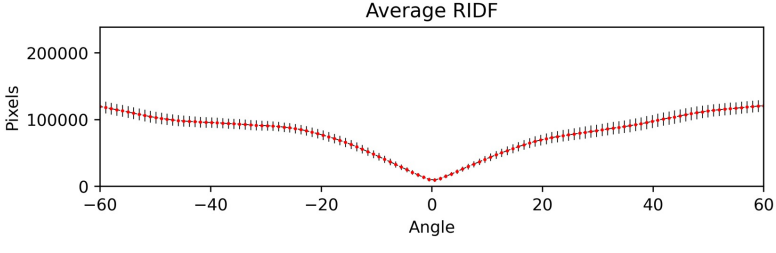
70%







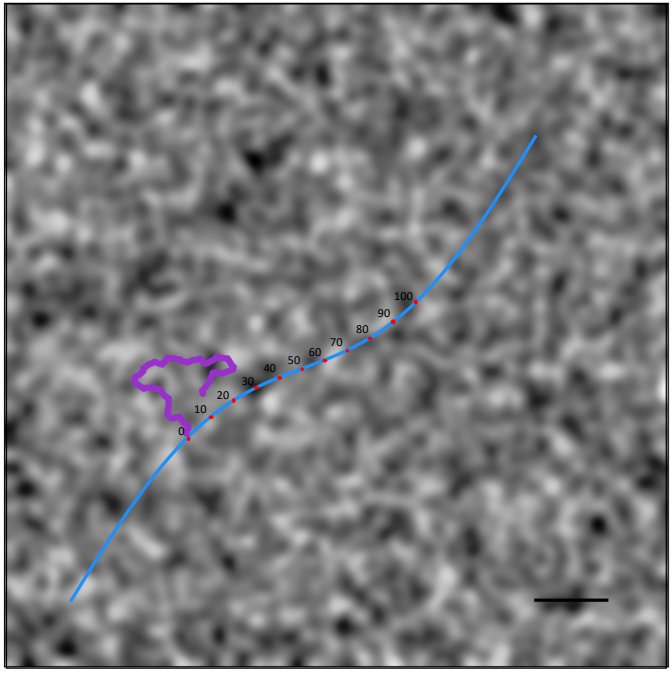


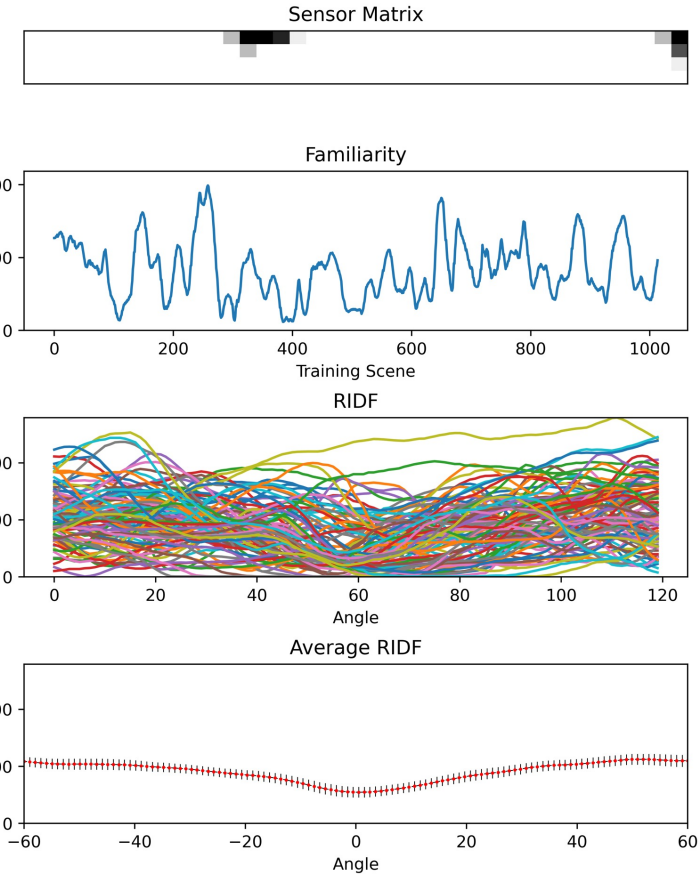


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 751.63; RMSD/dist: 1.879; TD: 88906; p90: 56; p50: 26; complete: 0

0%

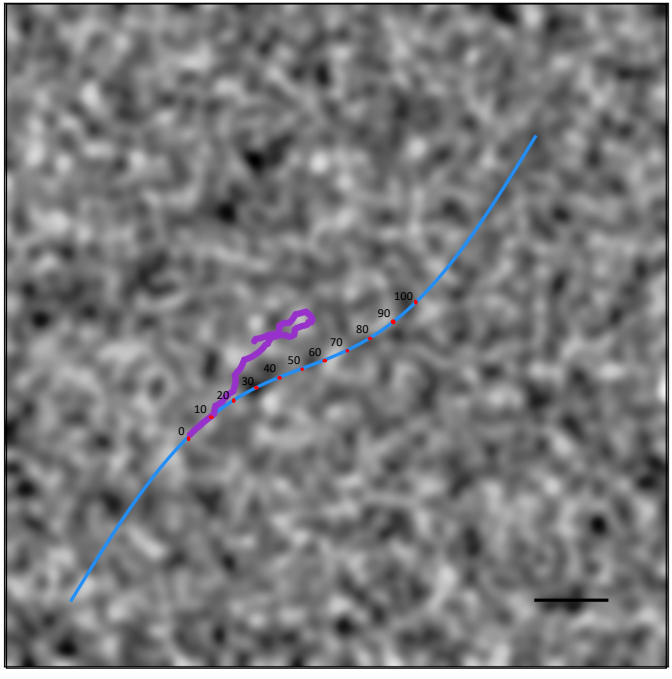


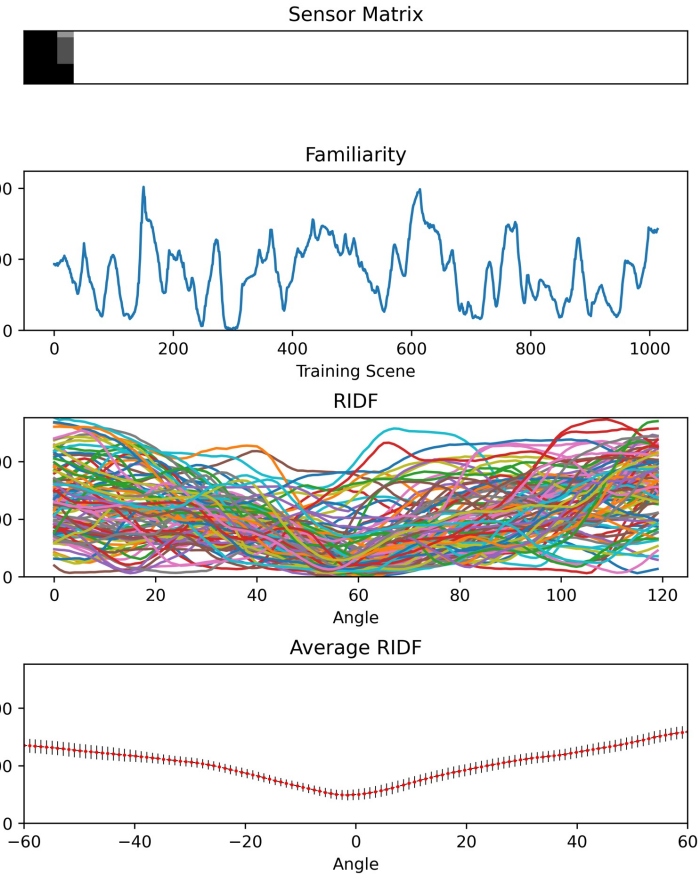


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 7131.29; RMSD/dist: 17.828; TD: 36090; p90: 44; p50: 22; complete: 0

10%

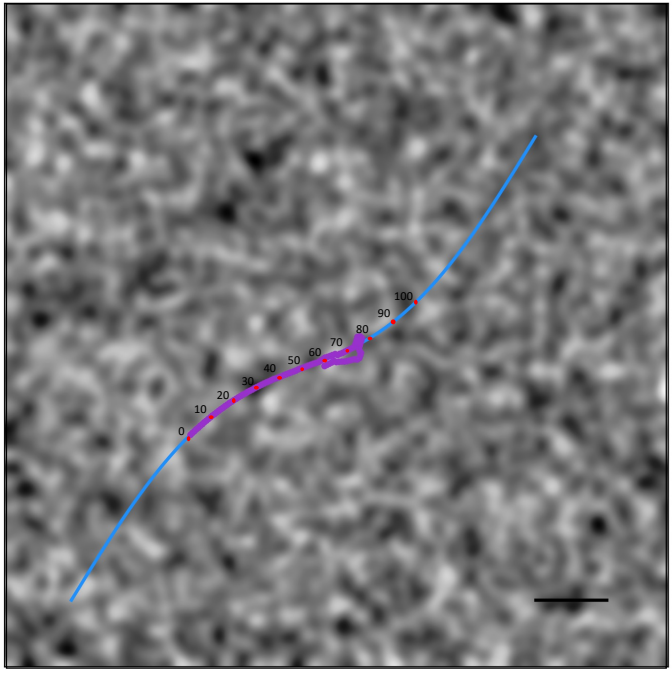


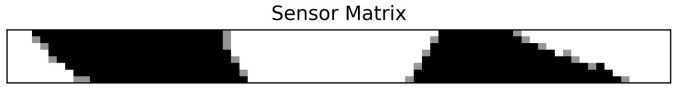


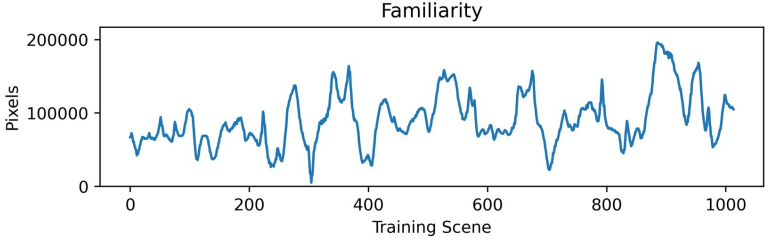
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

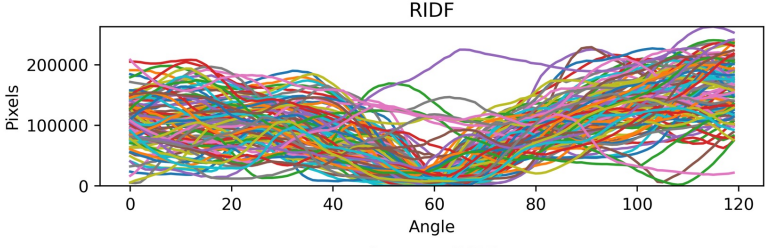
Navigation stats: RMSD error: 4379.38; RMSD/dist: 10.948; TD: 50441; p90: 48; p50: 30; complete: 0

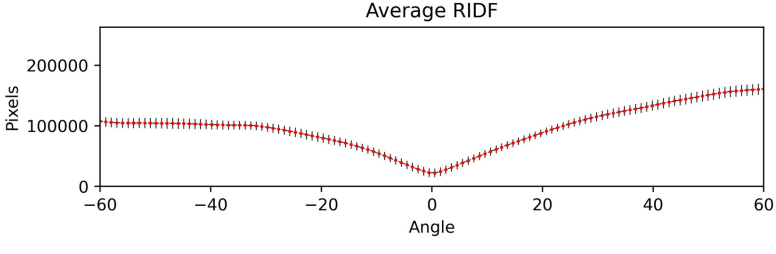
70%







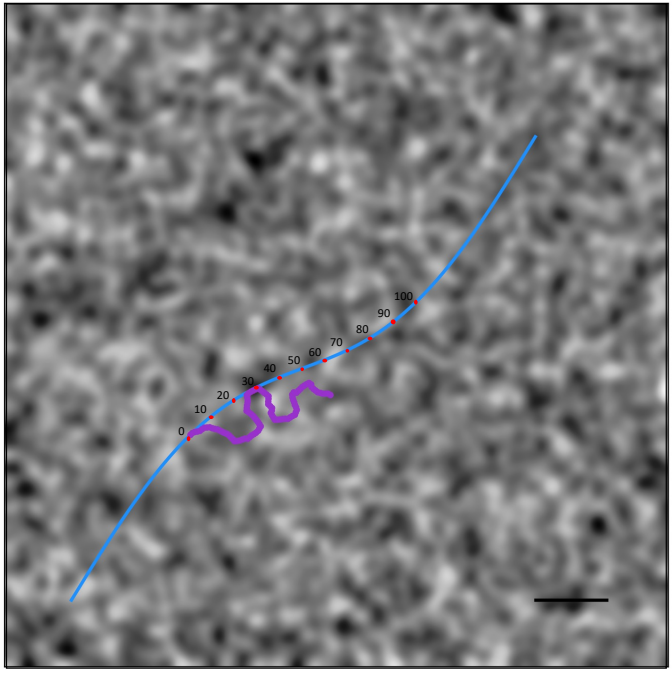


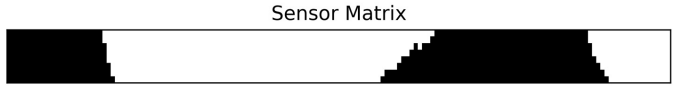


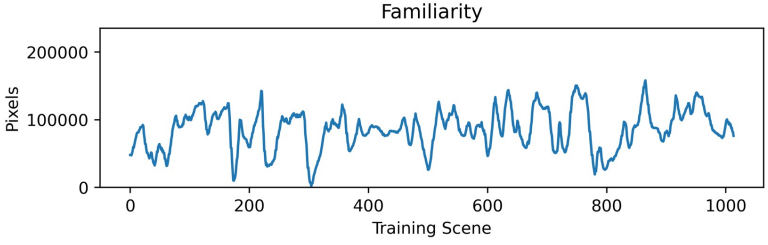
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

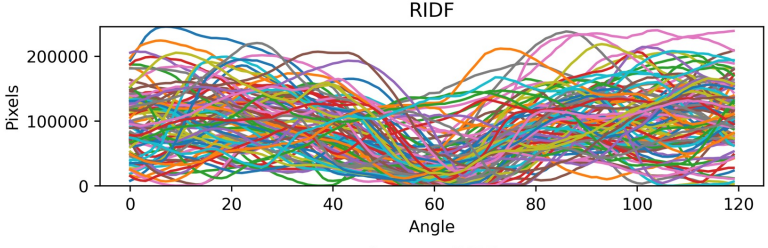
Navigation stats: RMSD error: 320.91; RMSD/dist: 0.802; TD: 73502; p90: 50; p50: 22; complete: 0

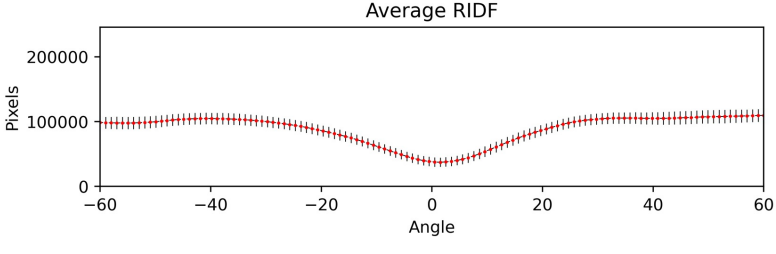
0%





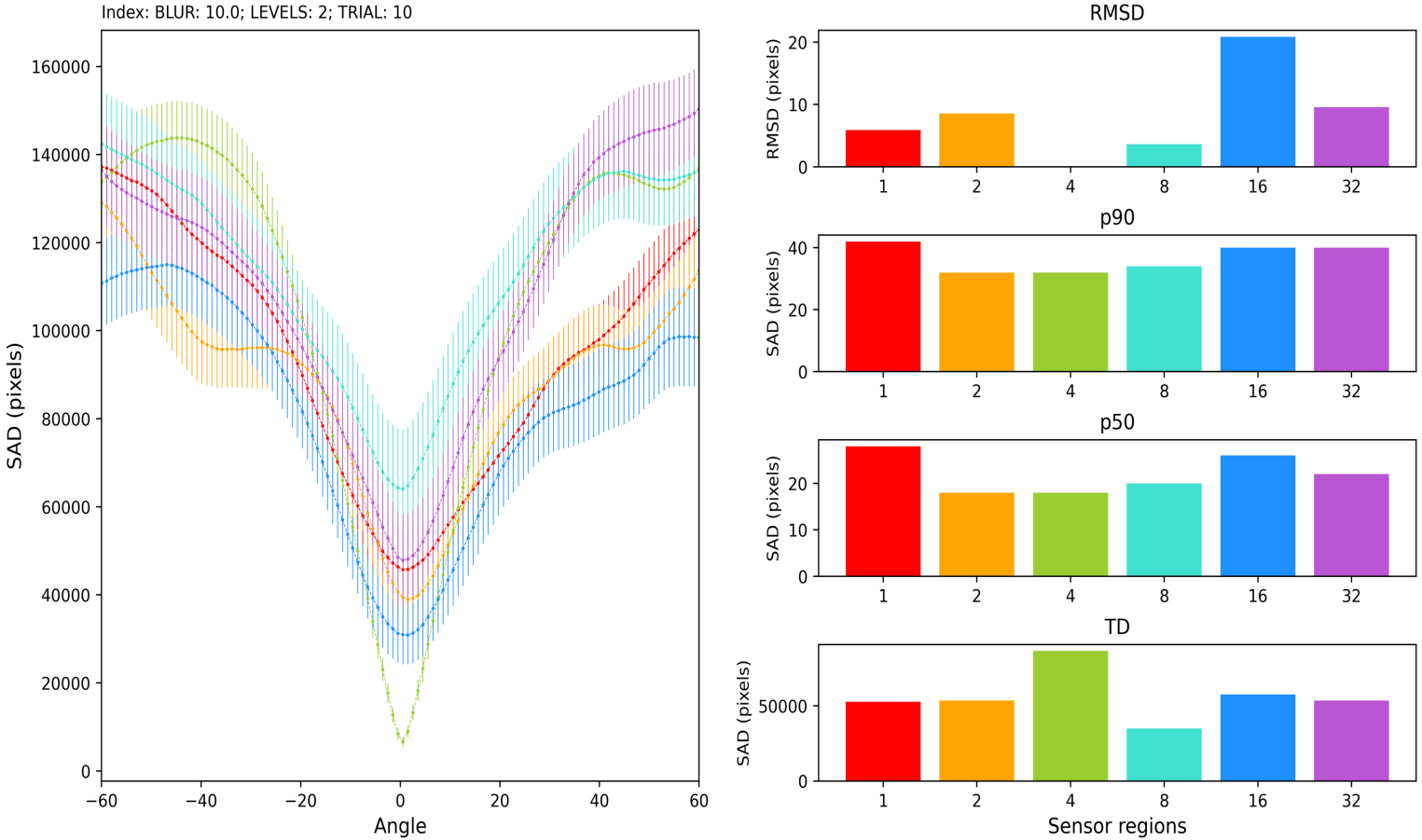




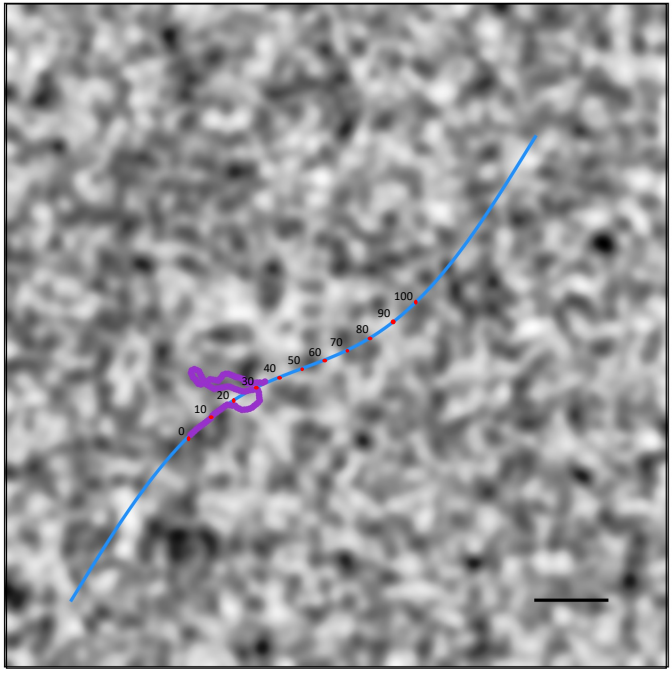


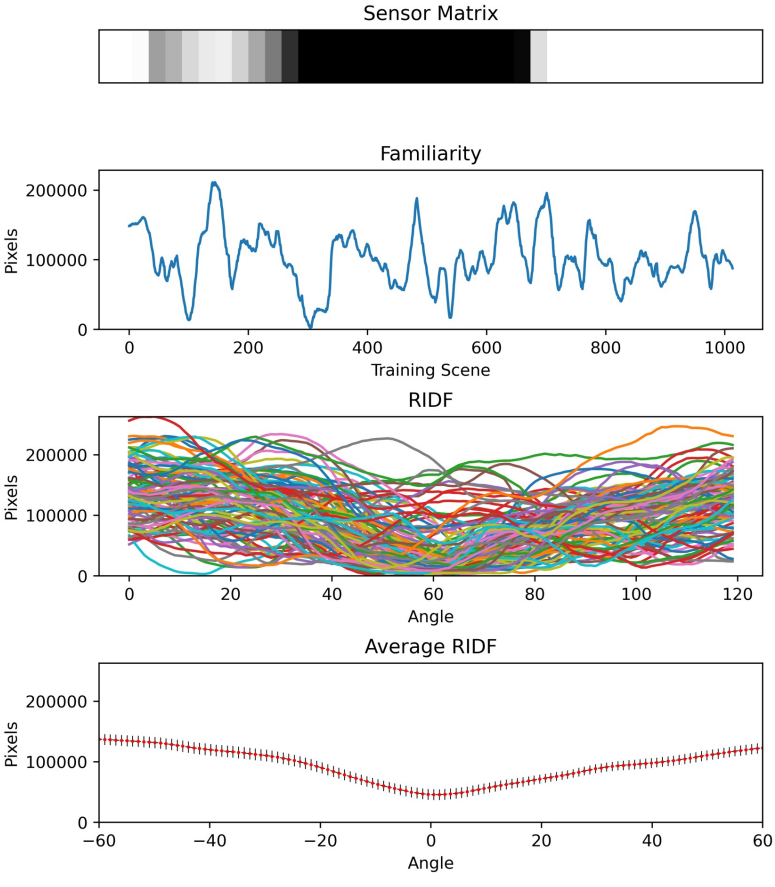
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3387.42; RMSD/dist: 8.469; TD: 64346; p90: 52; p50: 26; complete: 0


Index: BLUR: 10.0; LEVELS: 2; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

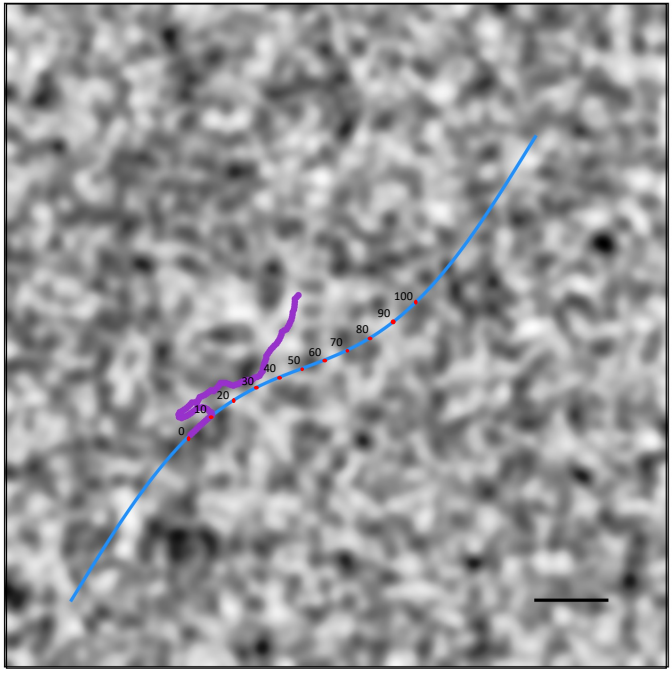


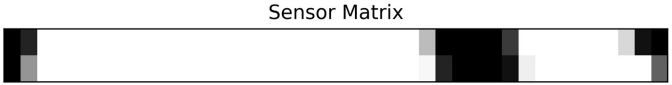


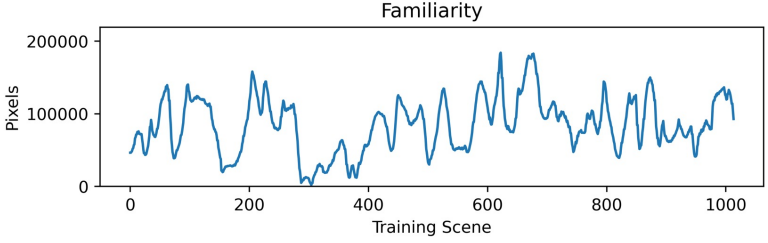
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

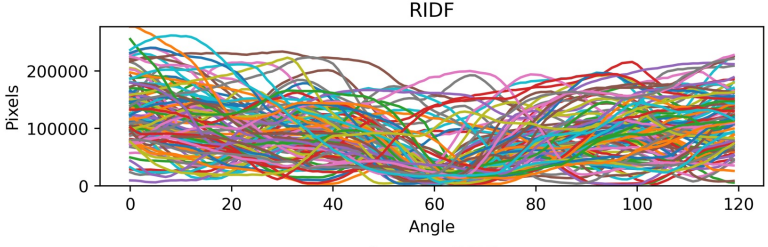
Navigation stats: RMSD error: 2350.63; RMSD/dist: 5.877; TD: 52763; p90: 42; p50: 28; complete: 0

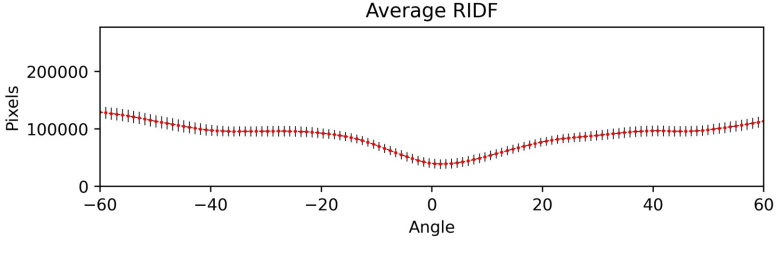
10%







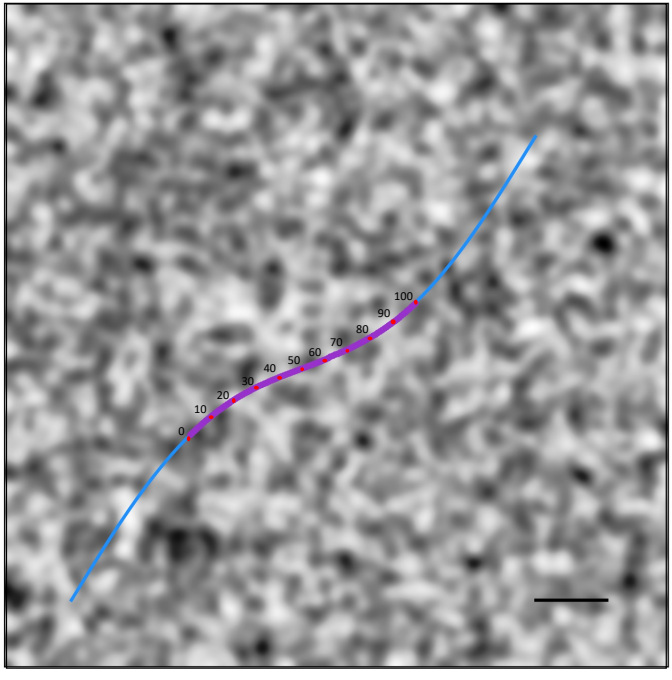


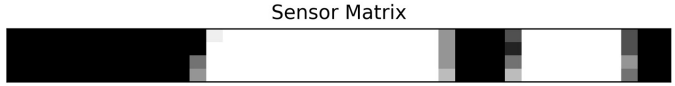


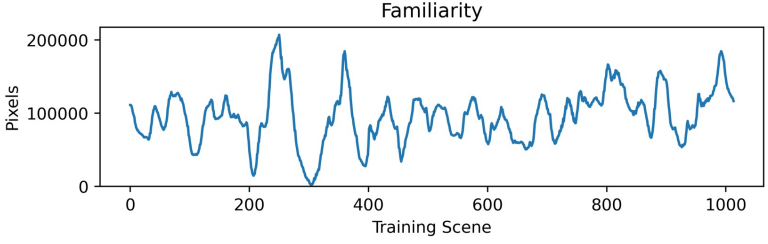
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

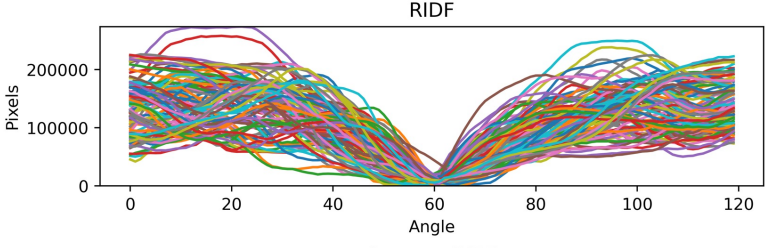
Navigation stats: RMSD error: 3421.79; RMSD/dist: 8.554; TD: 53474; p90: 32; p50: 18; complete: 0

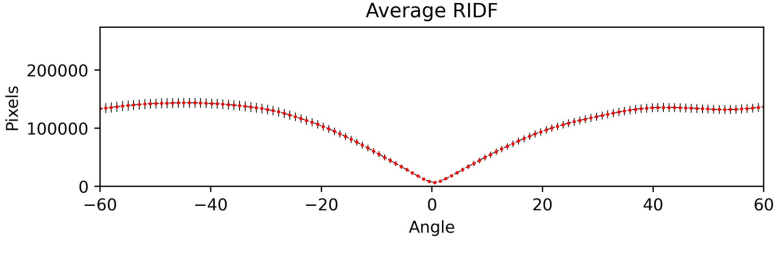
100%







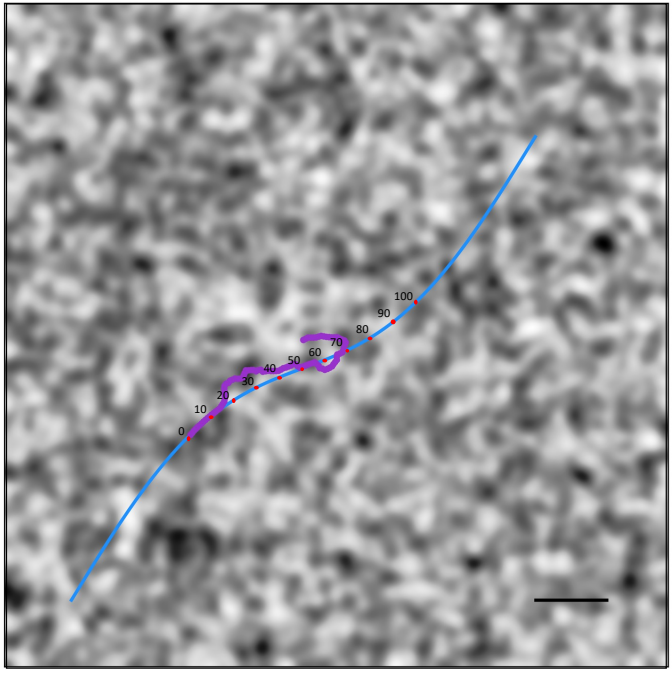


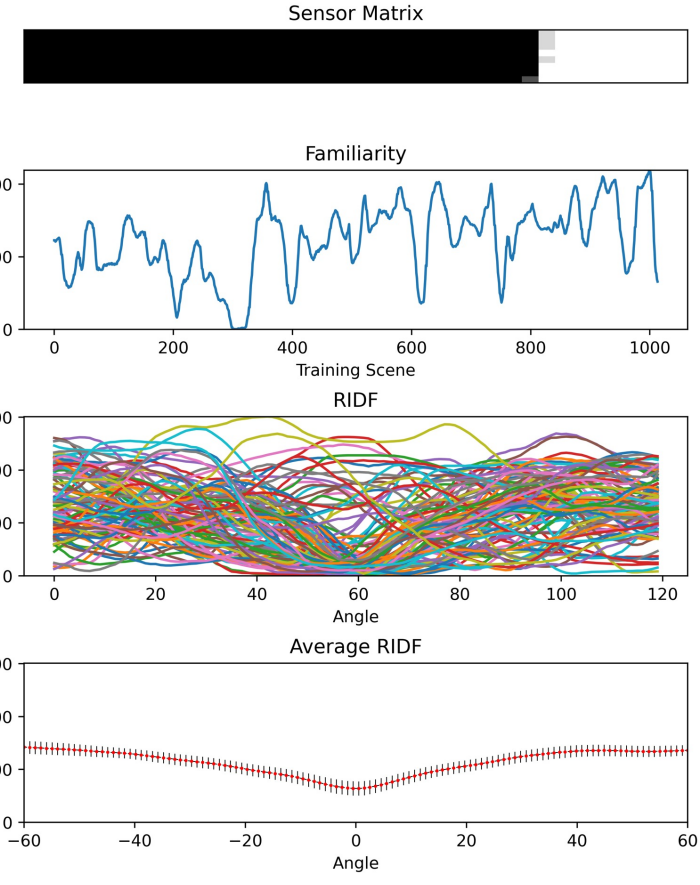


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 45.48; RMSD/dist: 0.114; TD: 86488; p90: 32; p50: 18; complete: 0

20%

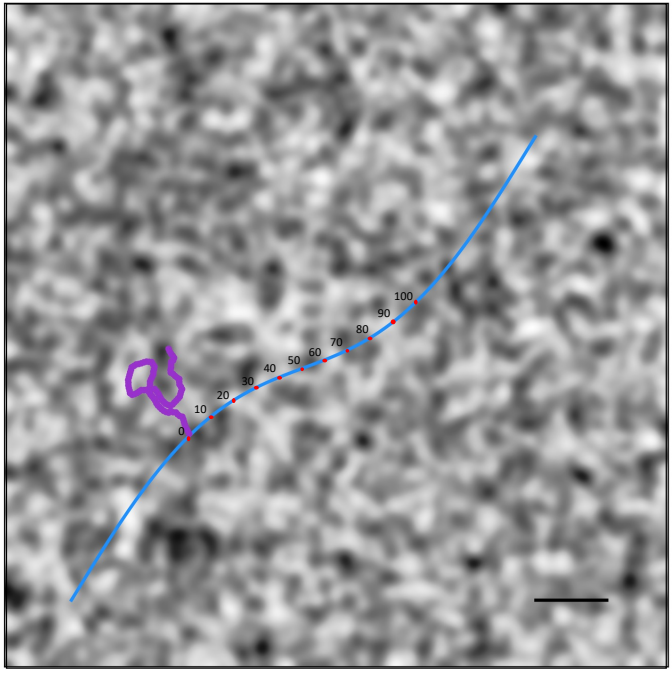


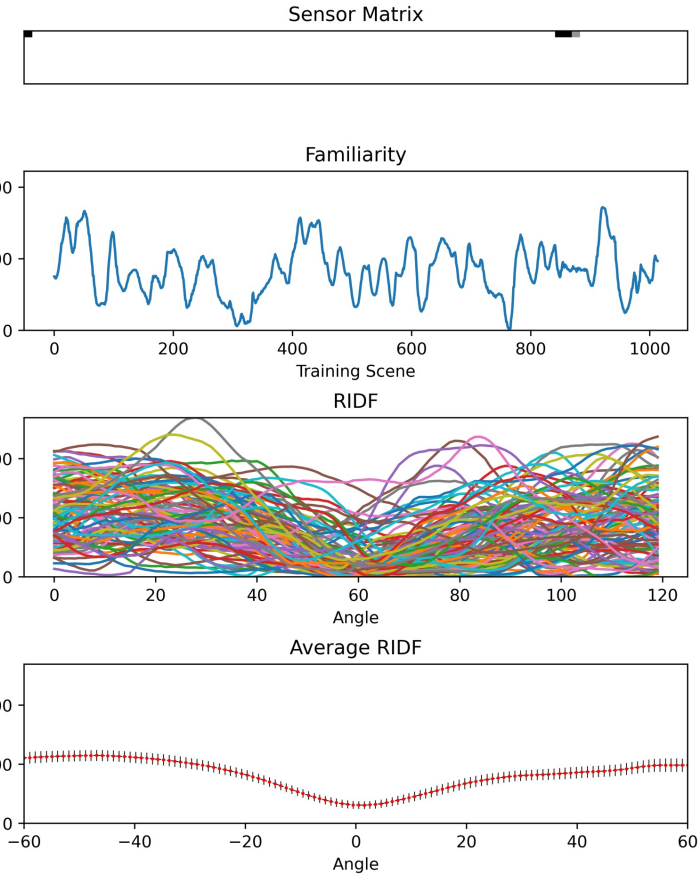


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1445.62; RMSD/dist: 3.614; TD: 34877; p90: 34; p50: 20; complete: 0

0%

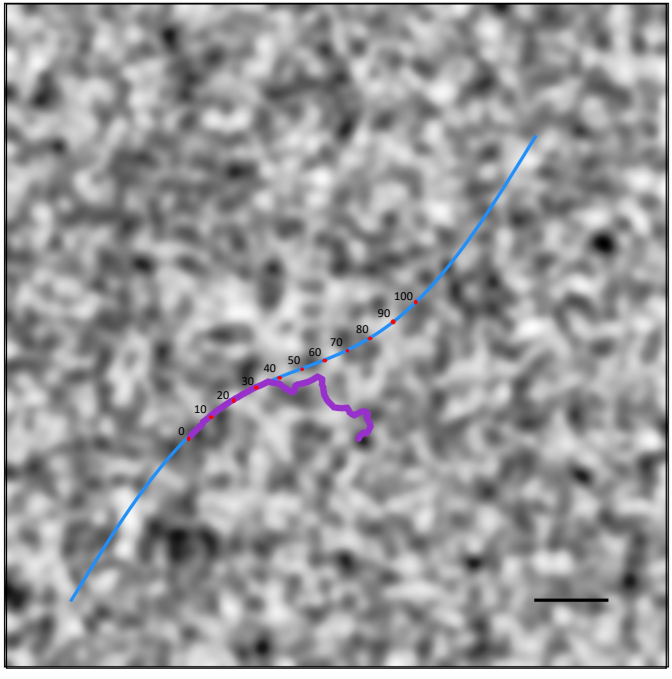


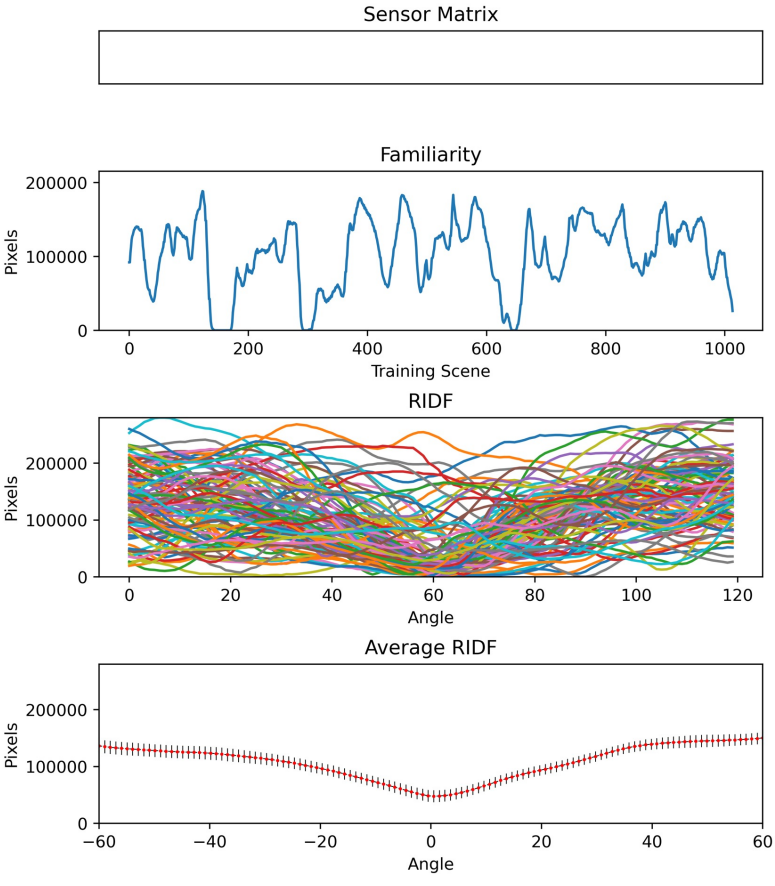


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 8343.00; RMSD/dist: 20.858; TD: 57566; p90: 40; p50: 26; complete: 0

30%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3828.19; RMSD/dist: 9.570; TD: 53579; p90: 40; p50: 22; complete: 0