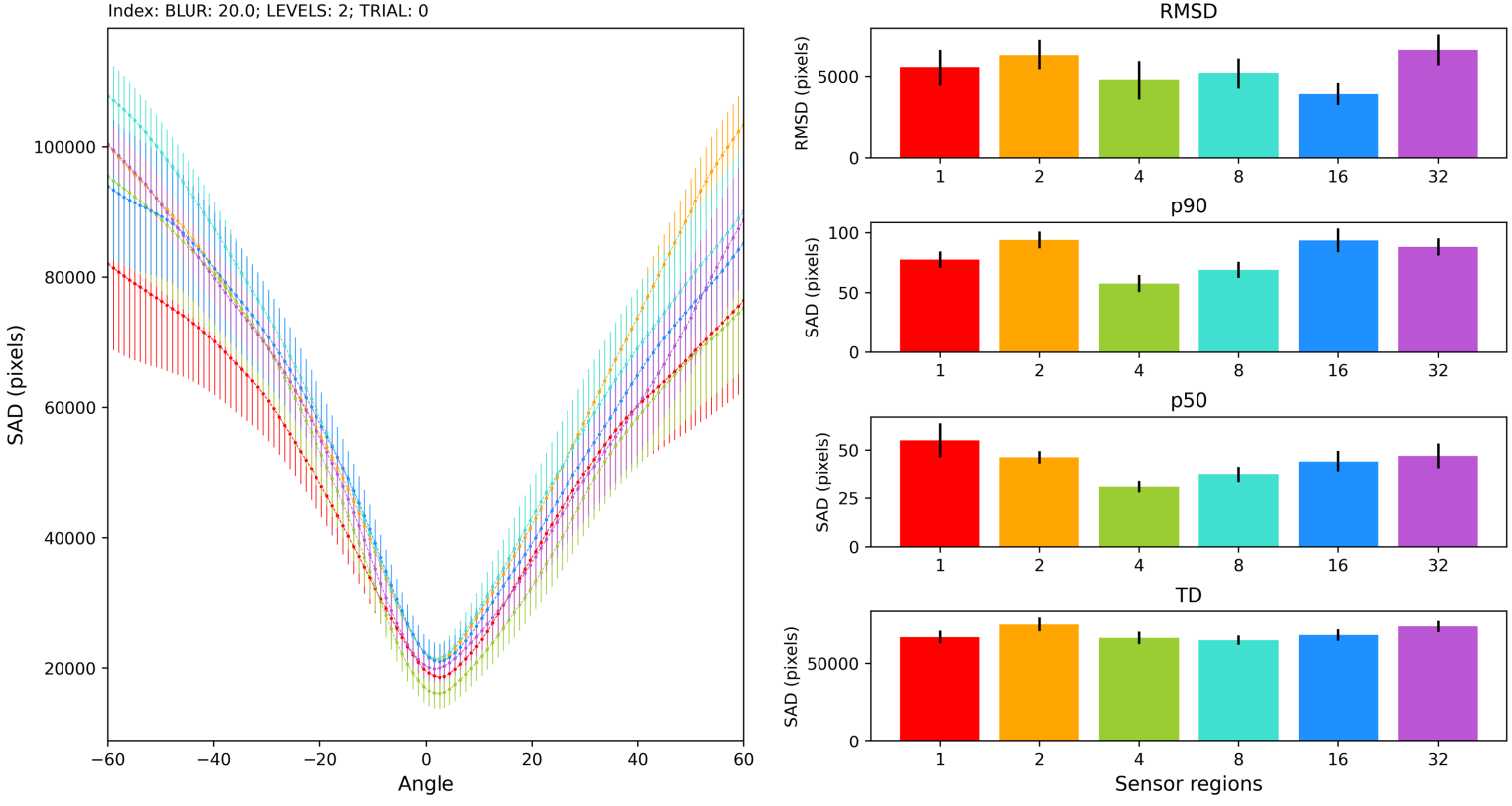
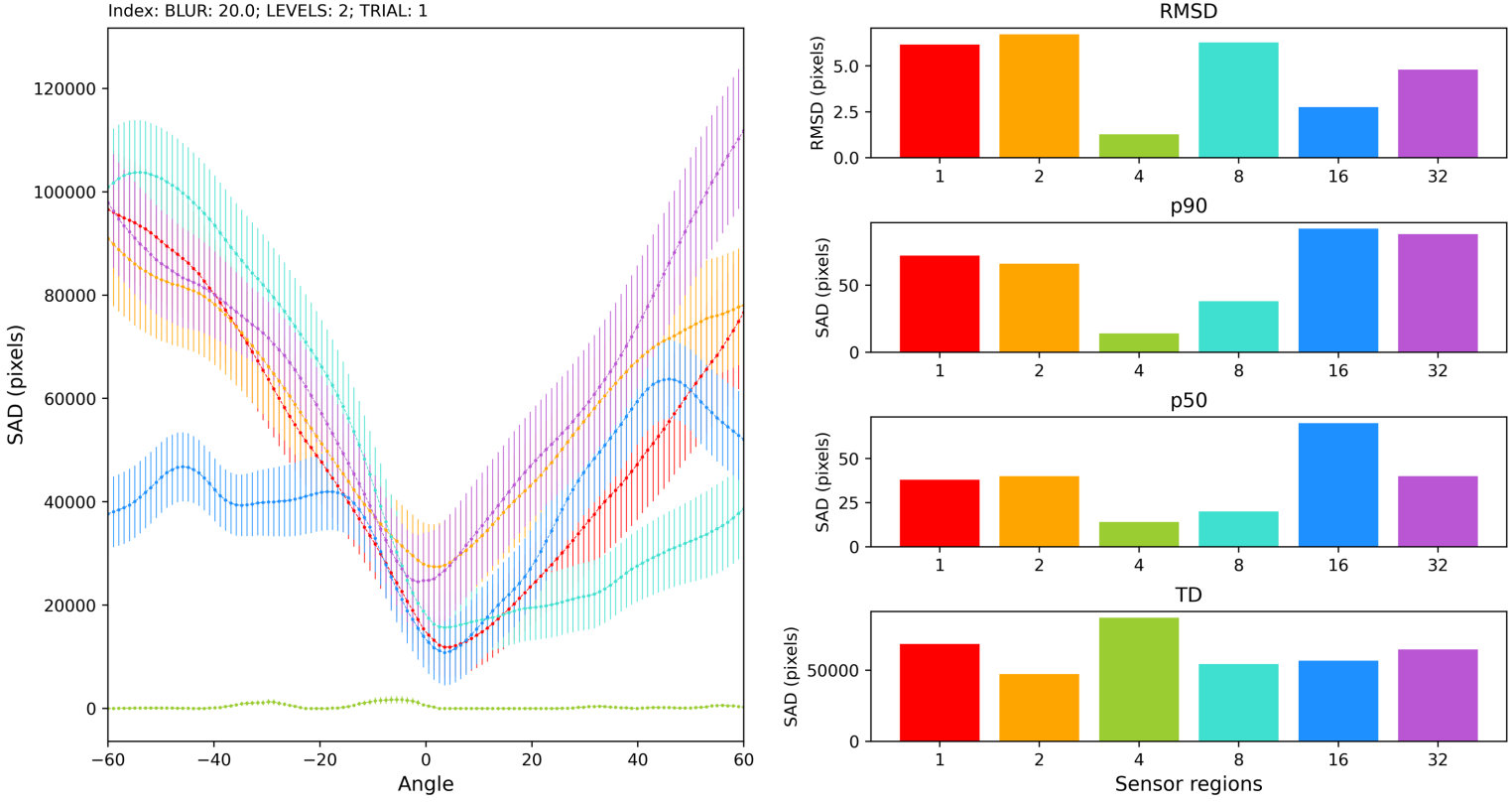
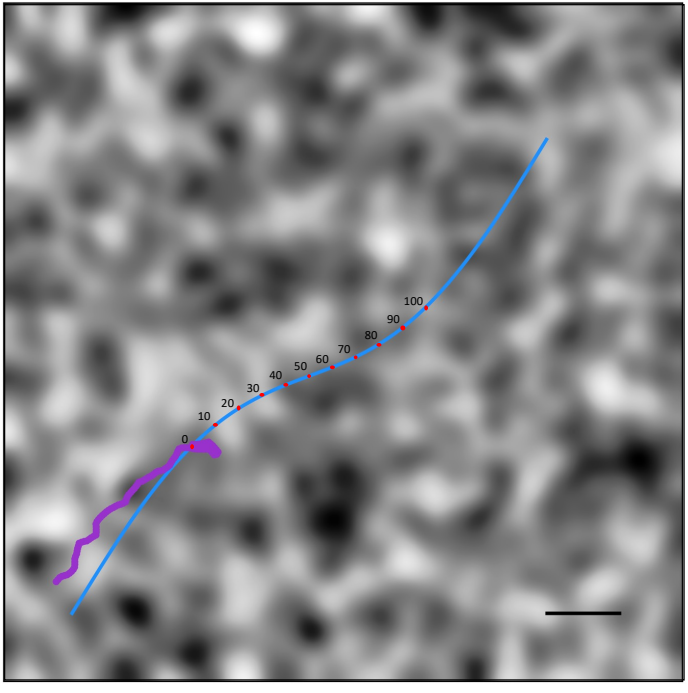
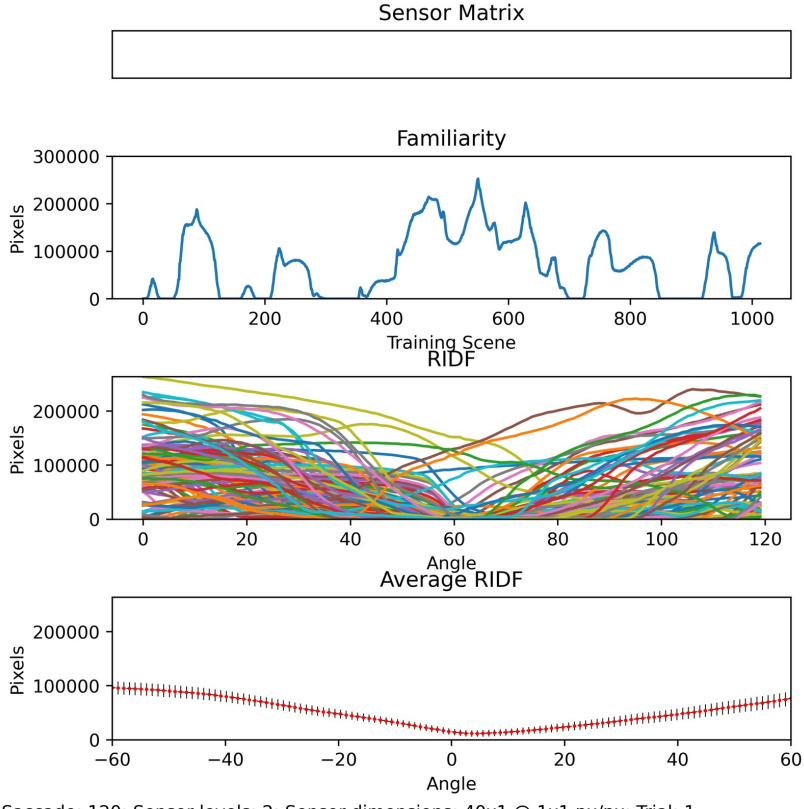

Index: BLUR: 20.0; LEVELS: 2; TRIAL: 0
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
5000
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
SAD (pixels)
50
25
0
TD
SAD (pixels)
50000
0
Sensor regions


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 1
SAD (pixels)
120000
100000
80000
60000
40000
20000
0
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
5.0
2.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
50
0
p50
SAD (pixels)
50
25
0
TD
SAD (pixels)
50000
0
Sensor regions

0%

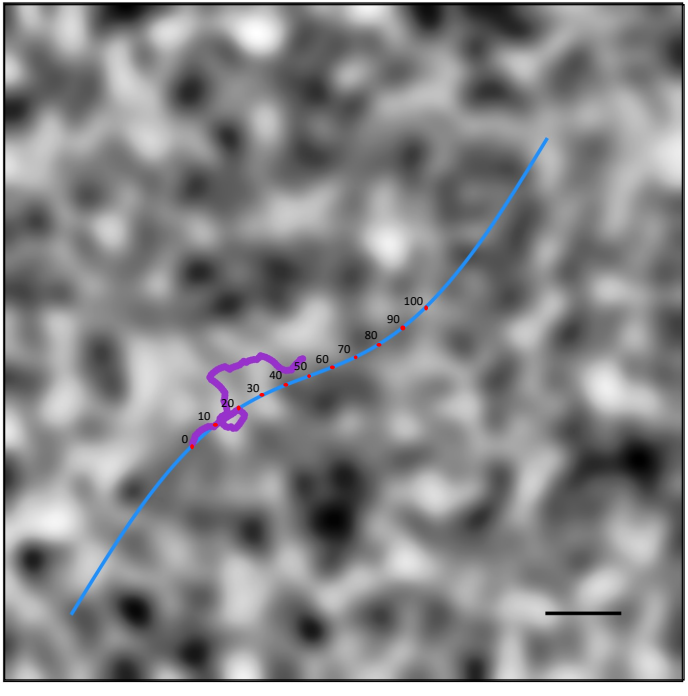


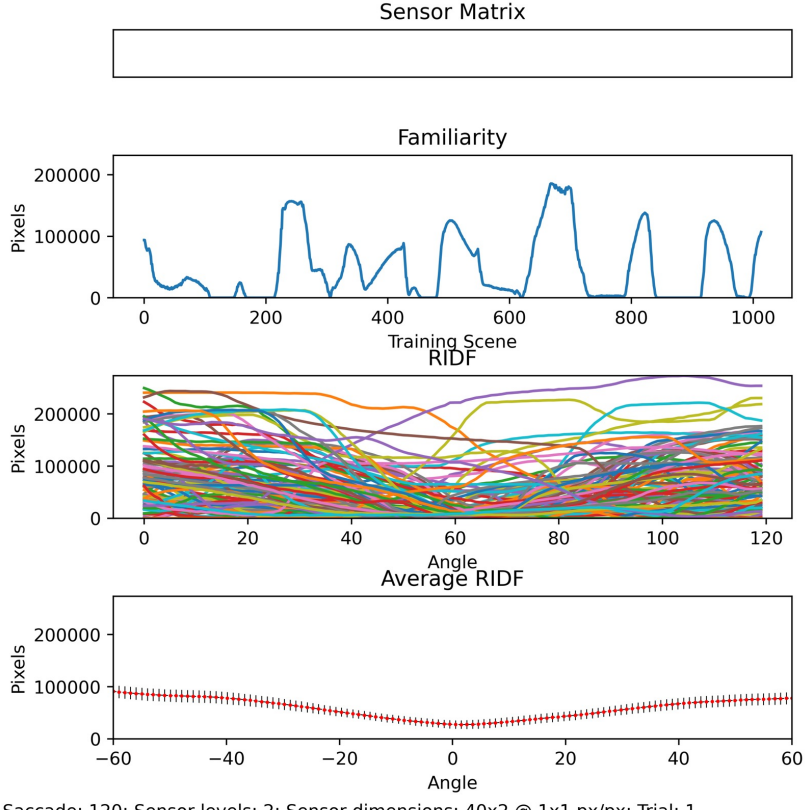


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2465.04; RMSD/dist: 6.163; TD: 68387; p90: 72; p50: 38; complete: 0

0%

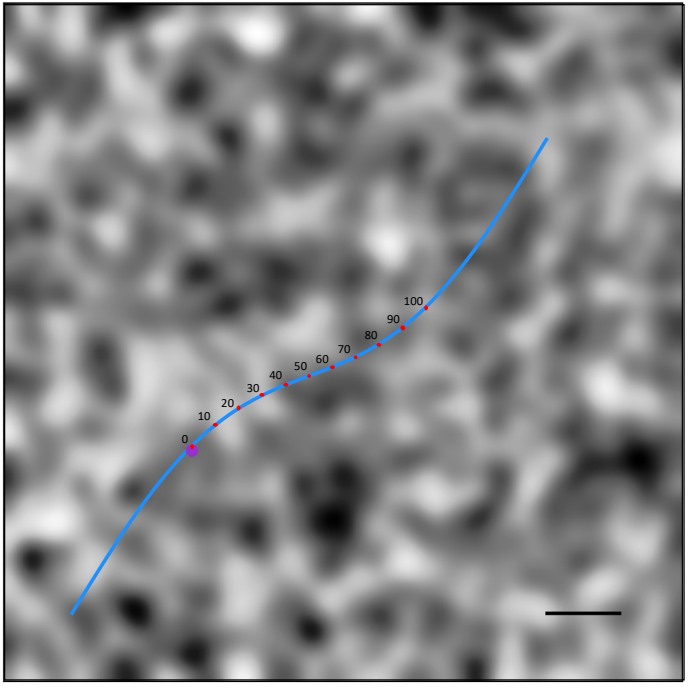


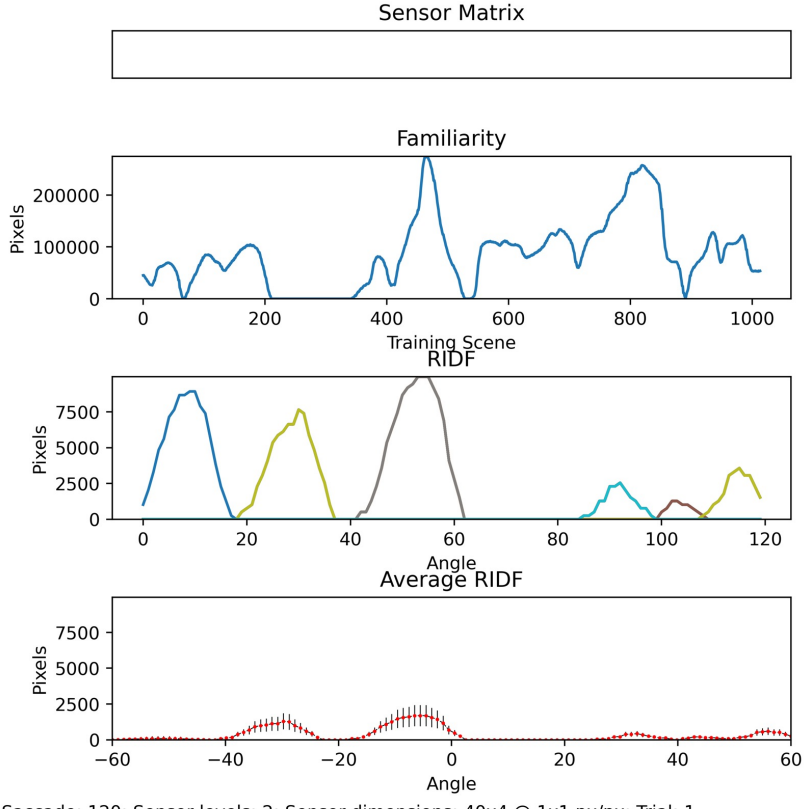


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2690.88; RMSD/dist: 6.727; TD: 47211; p90: 66; p50: 40; complete: 0

0%

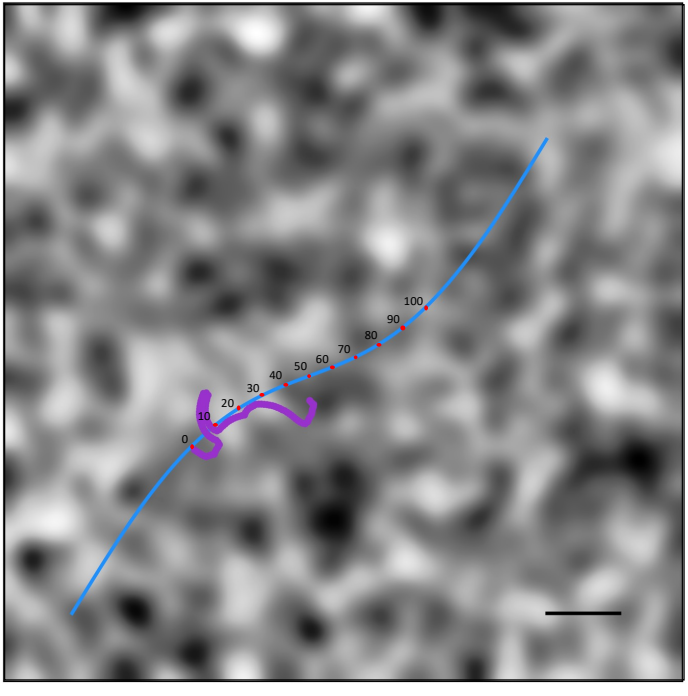


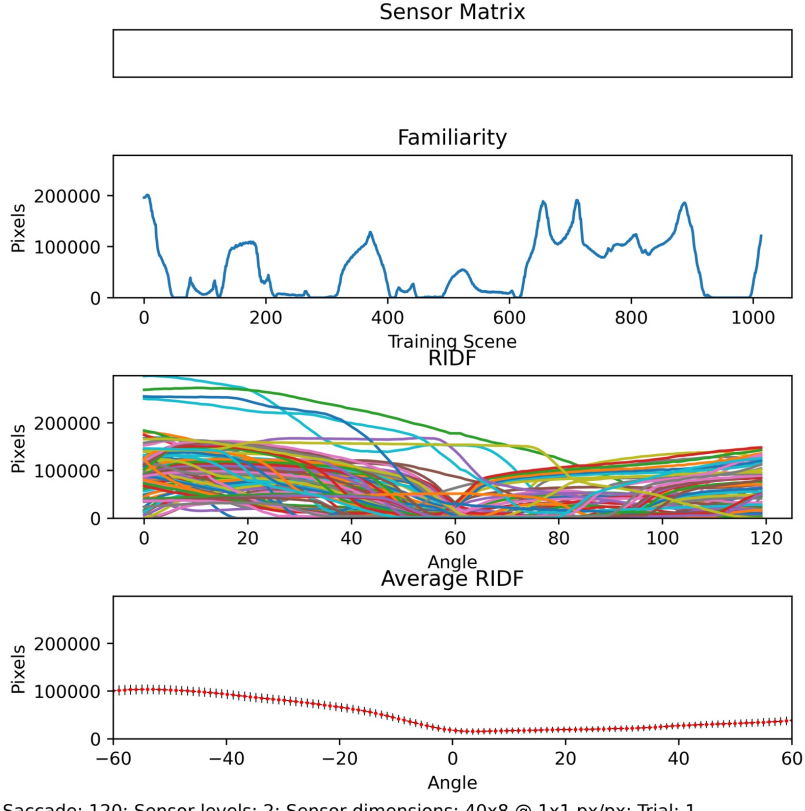


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 507.24; RMSD/dist: 1.268; TD: 86819; p90: 14; p50: 14; complete: 0

0%

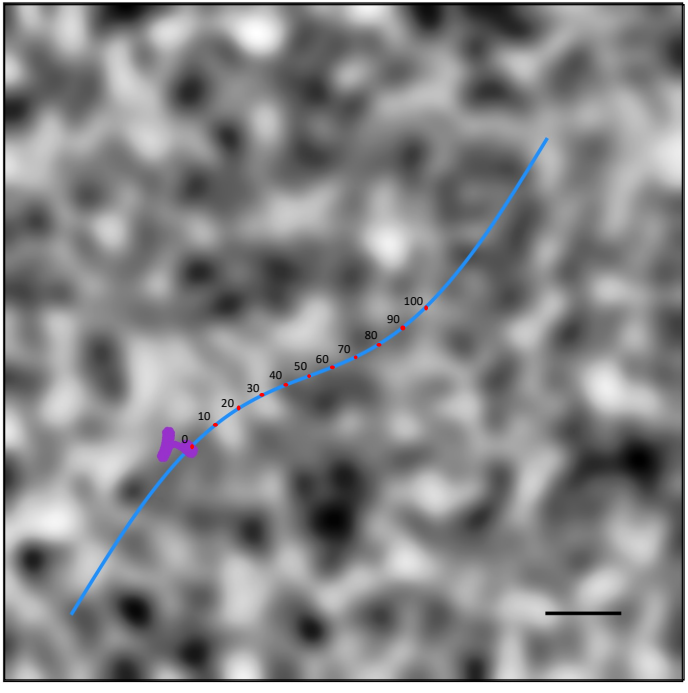


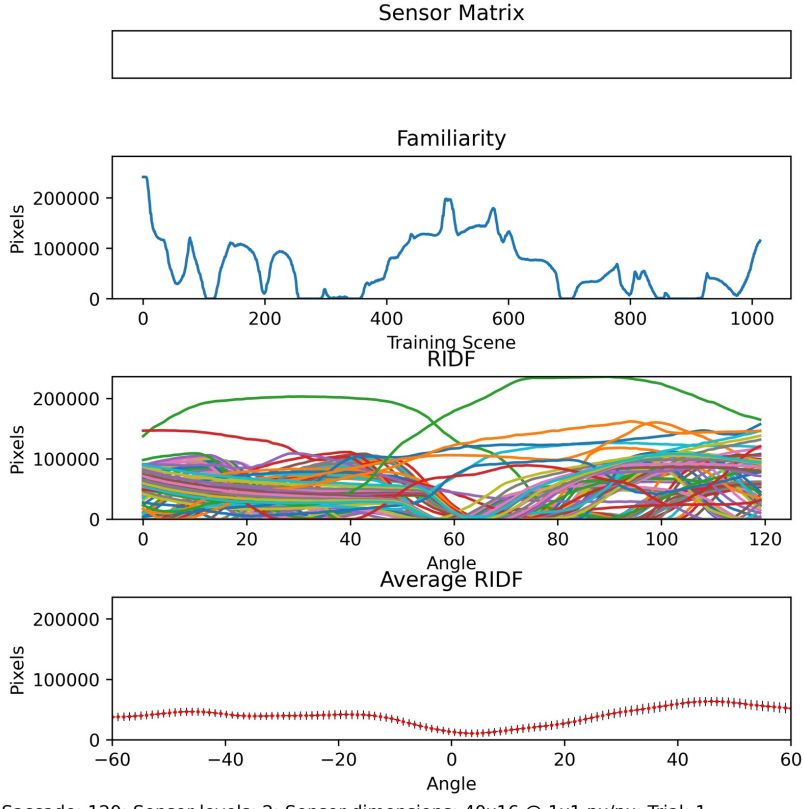


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2511.09; RMSD/dist: 6.278; TD: 54268; p90: 38; p50: 20; complete: 0

0%

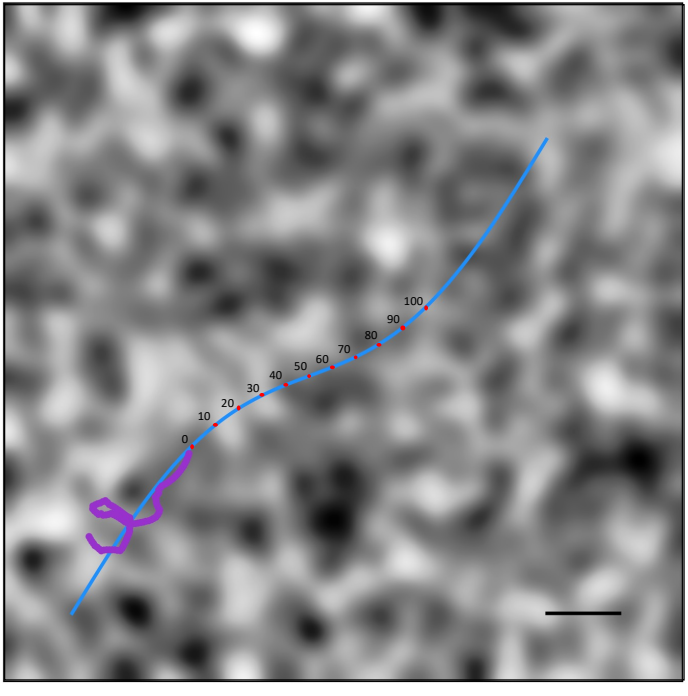


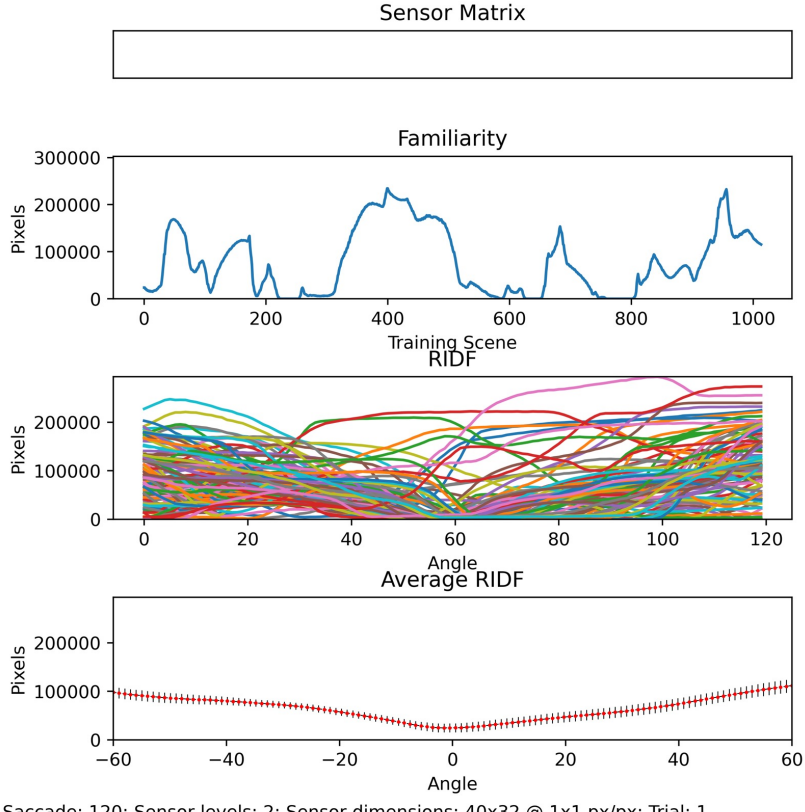


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

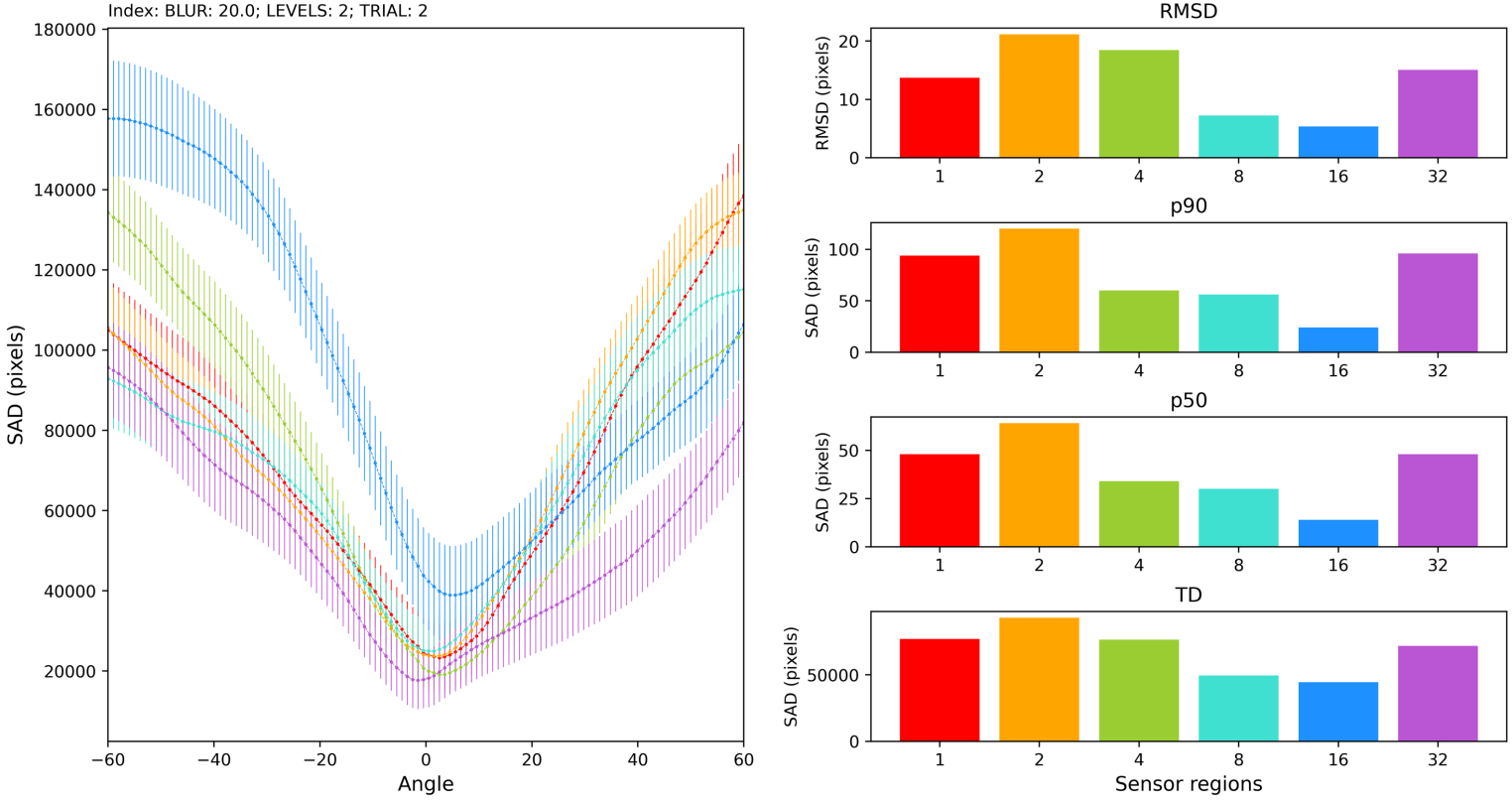
Navigation stats: RMSD error: 1102.67; RMSD/dist: 2.757; TD: 56684; p90: 92; p50: 70; complete: 0

0%

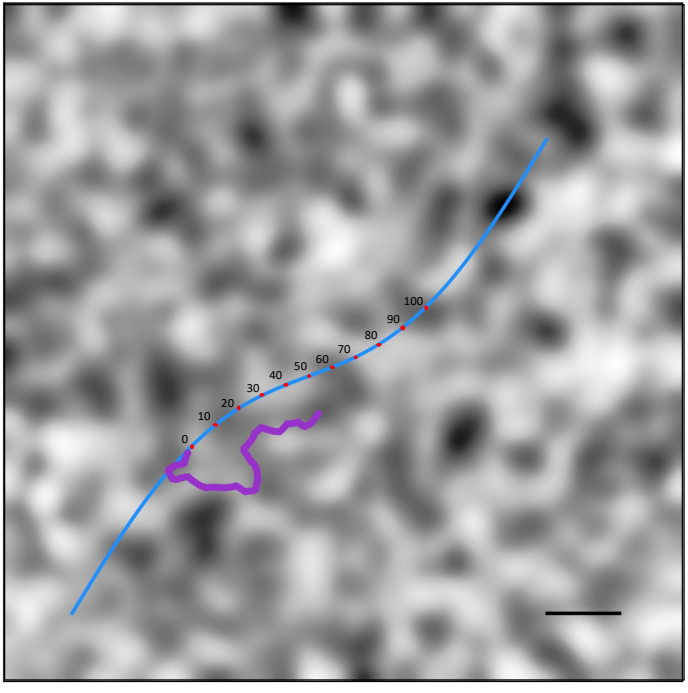


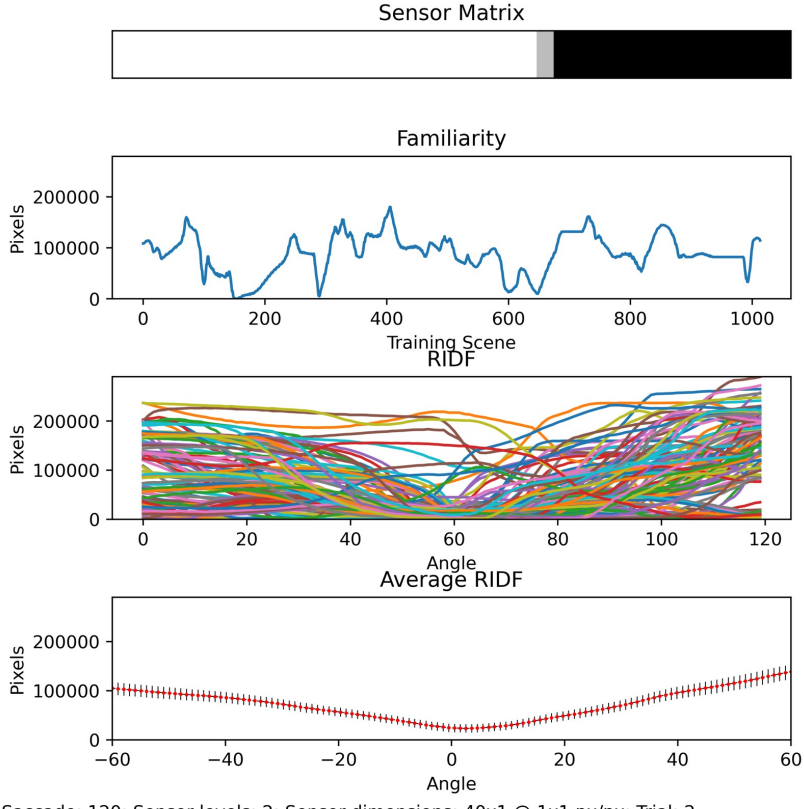


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 1918.47; RMSD/dist: 4.796; TD: 64577; p90: 88; p50: 40; complete: 0


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

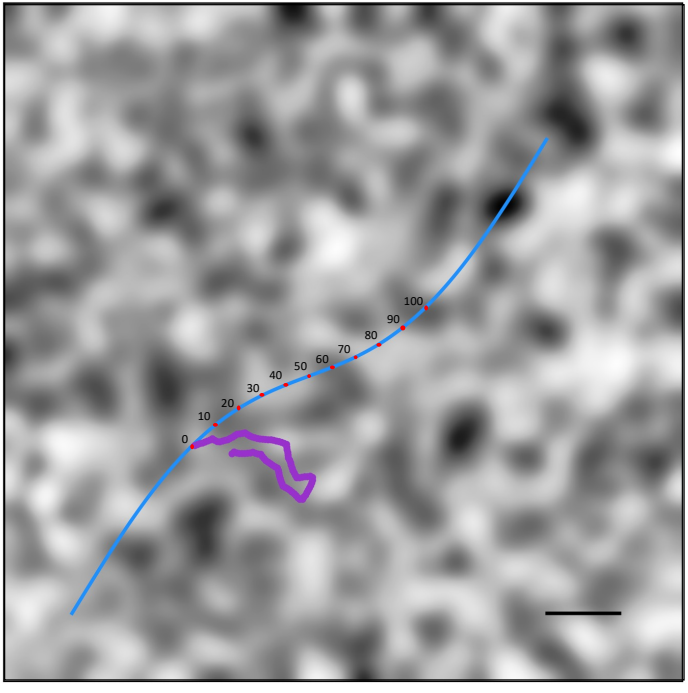


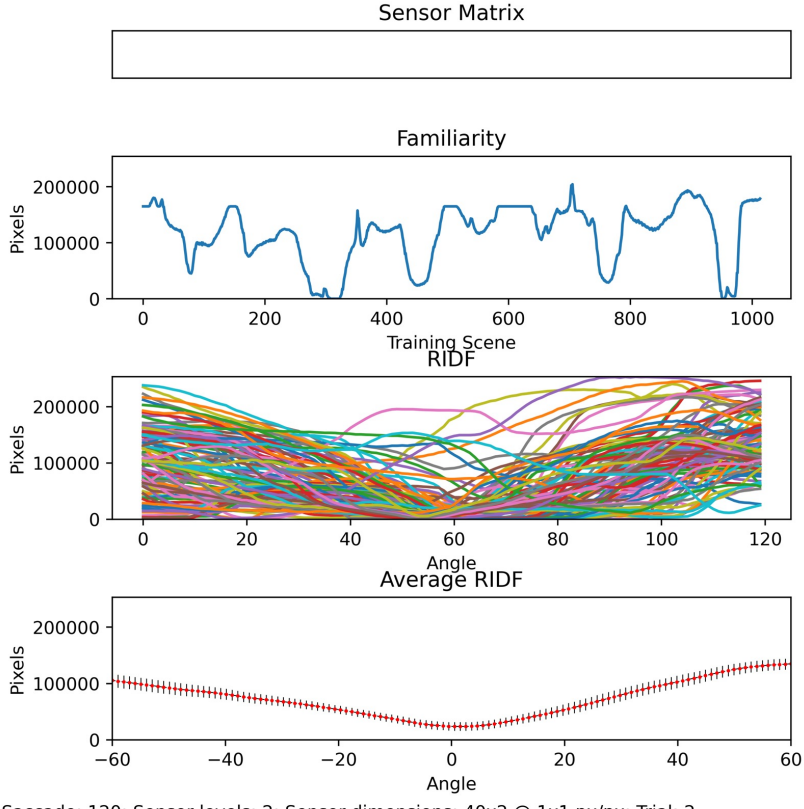


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 5488.00; RMSD/dist: 13.720; TD: 76894; p90: 94; p50: 48; complete: 0

0%

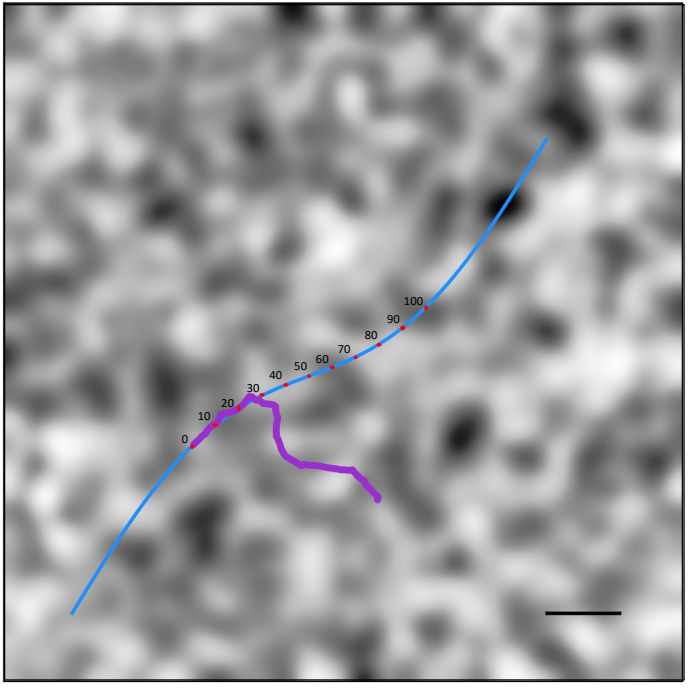


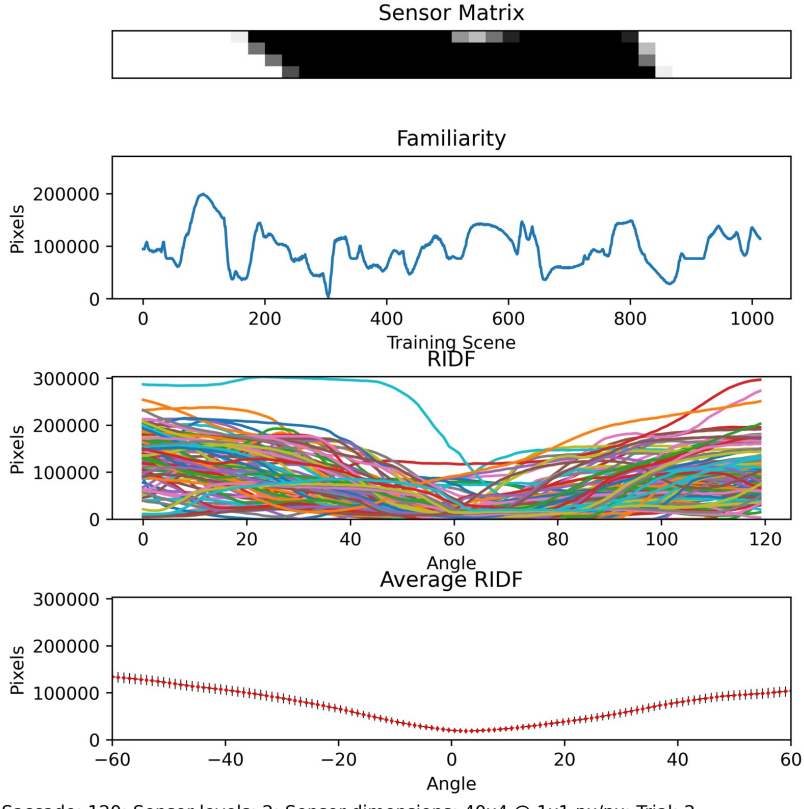


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 8470.82; RMSD/dist: 21.177; TD: 92875; p90: 120; p50: 64; complete: 0

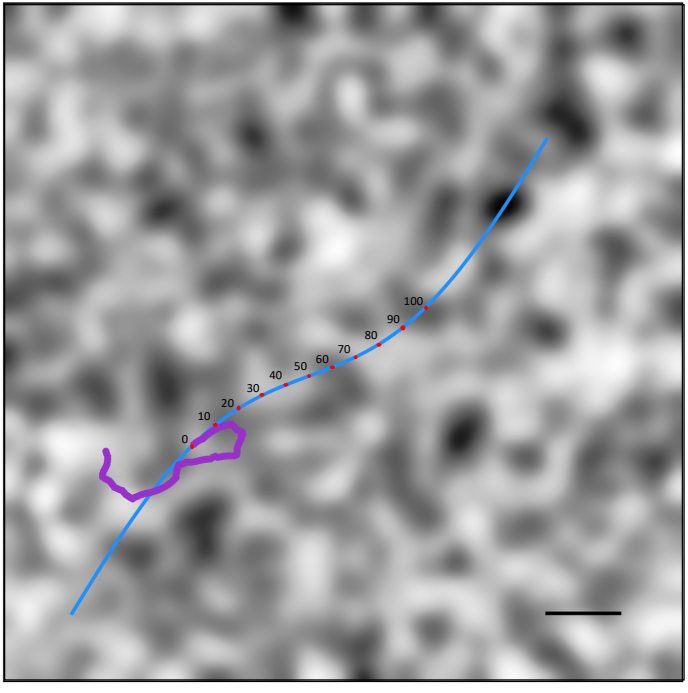
10%

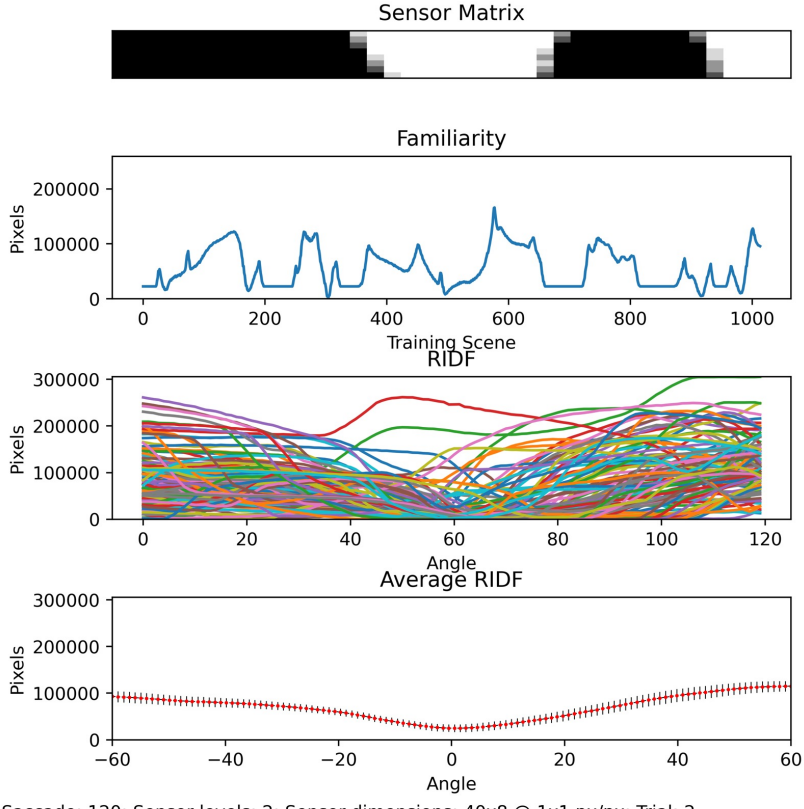




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 7378.61; RMSD/dist: 18.447; TD: 76379; p90: 60; p50: 34; complete: 0

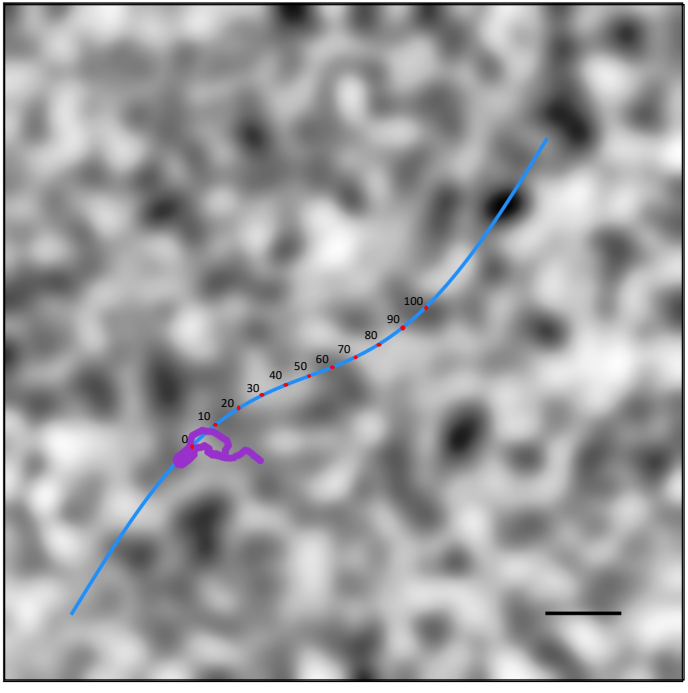
0%

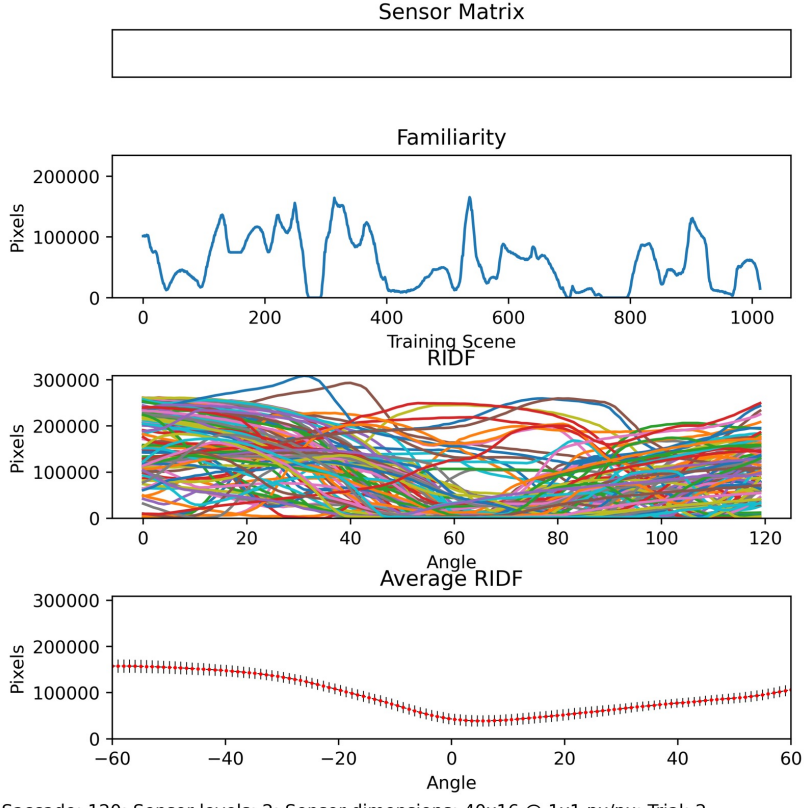




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 2892.75; RMSD/dist: 7.232; TD: 49500; p90: 56; p50: 30; complete: 0

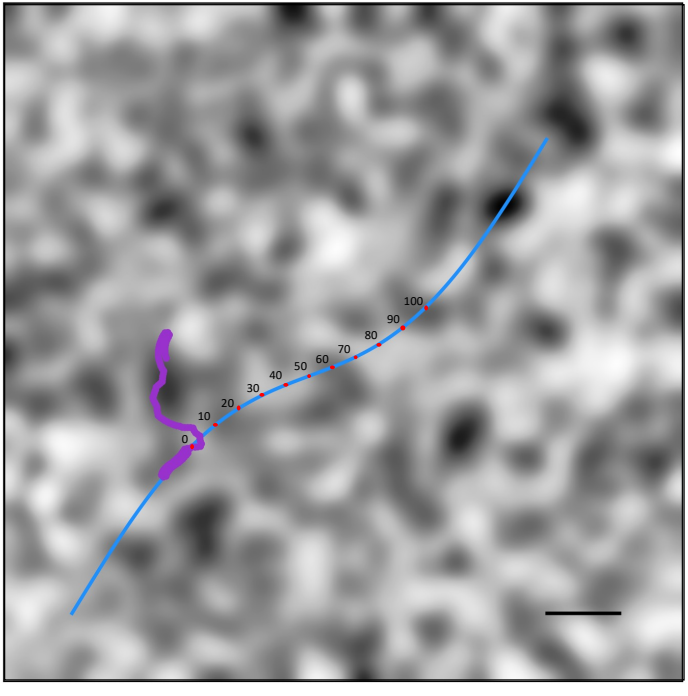
0%

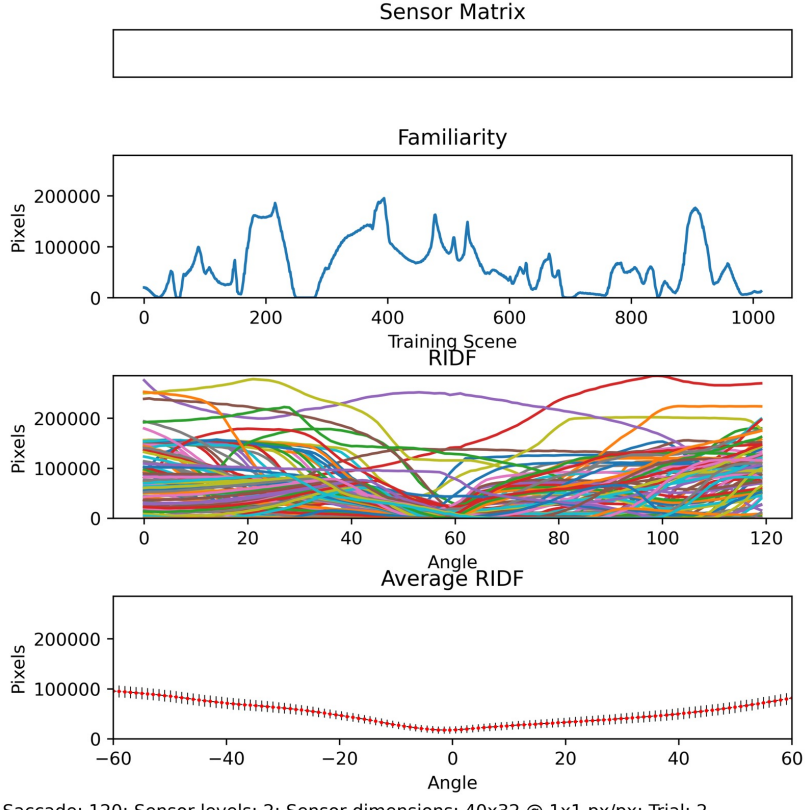




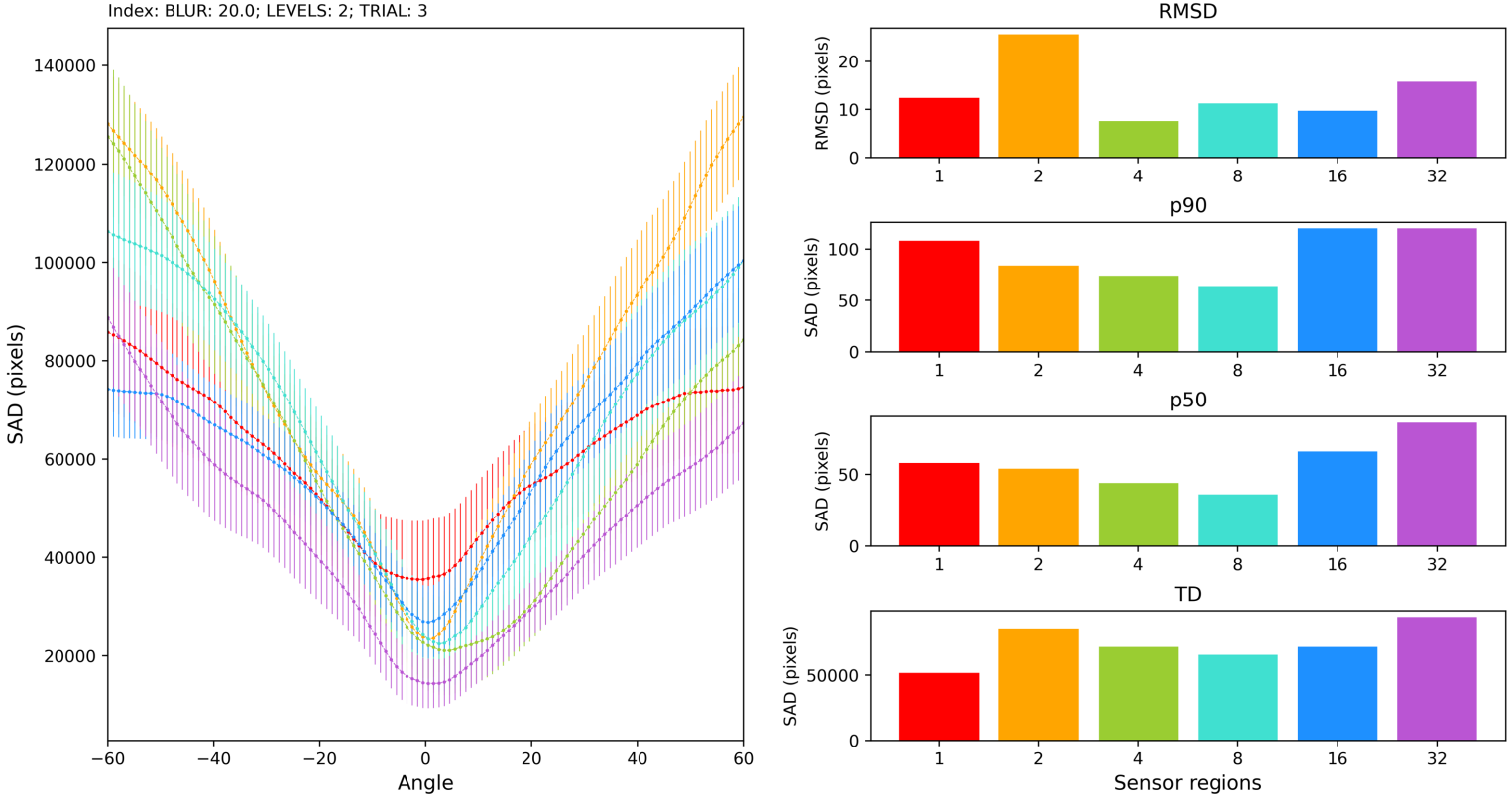
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 2147.01; RMSD/dist: 5.368; TD: 44520; p90: 24; p50: 14; complete: 0

0%

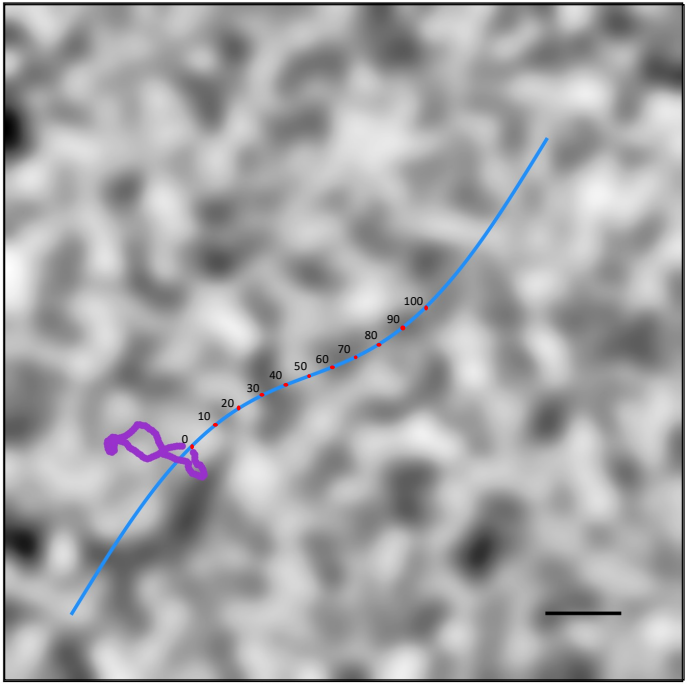


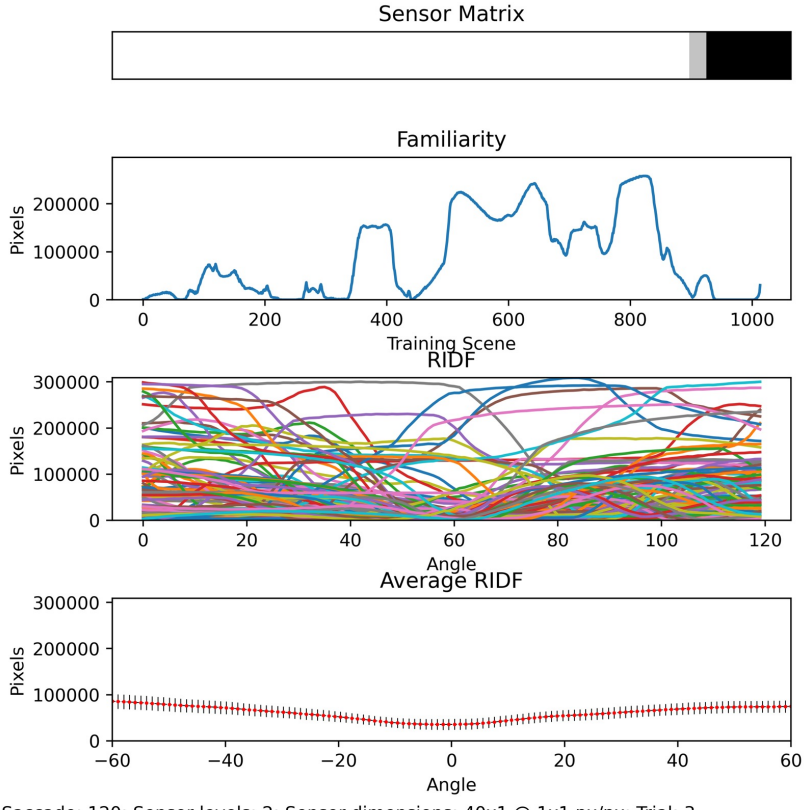


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 6020.76; RMSD/dist: 15.052; TD: 71661; p90: 96; p50: 48; complete: 0


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

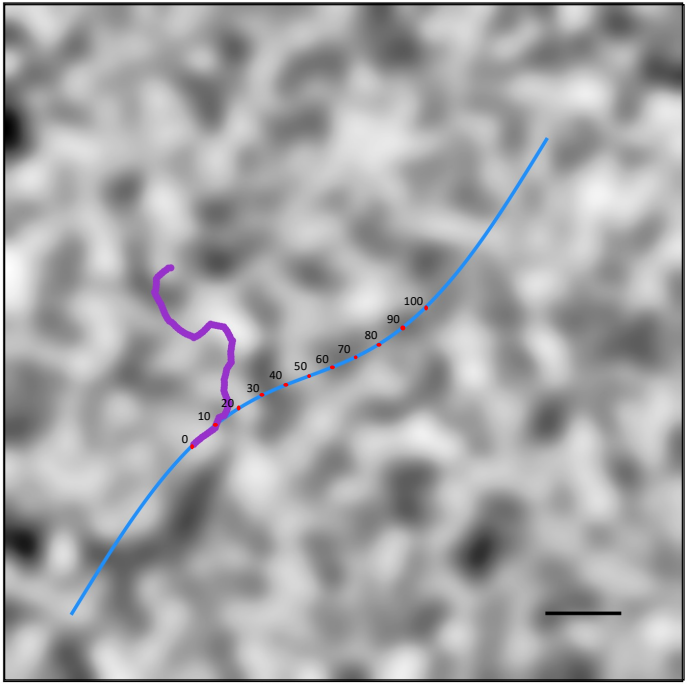
0%

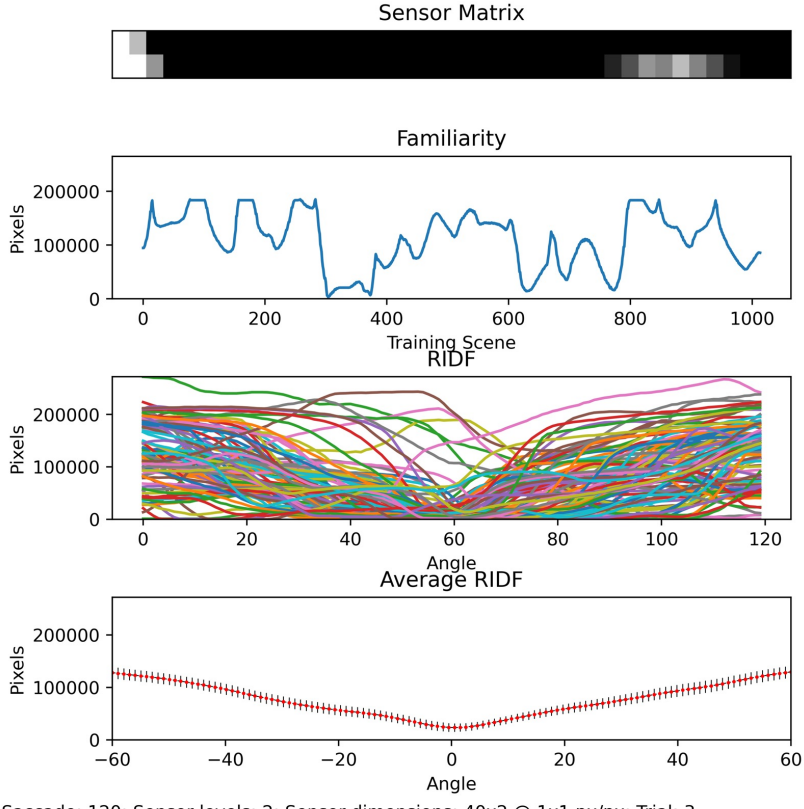




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 4947.23; RMSD/dist: 12.368; TD: 51738; p90: 108; p50: 58; complete: 0

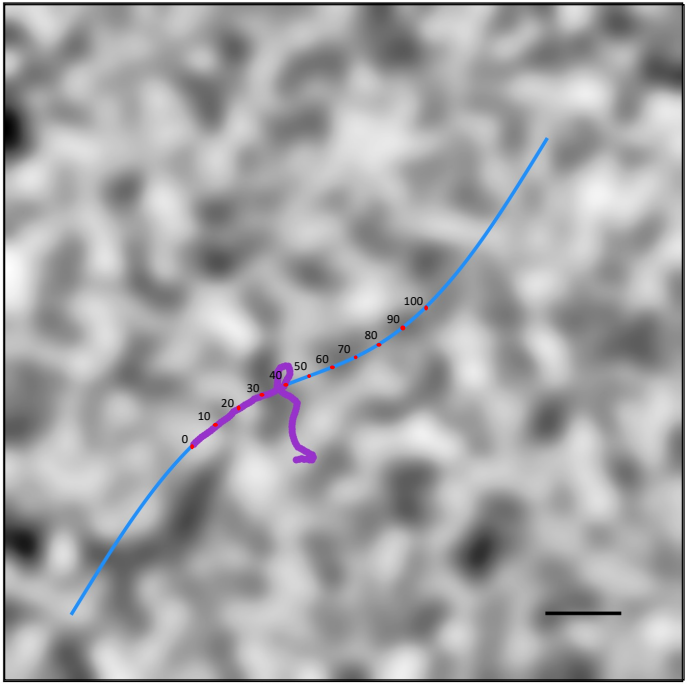
10%

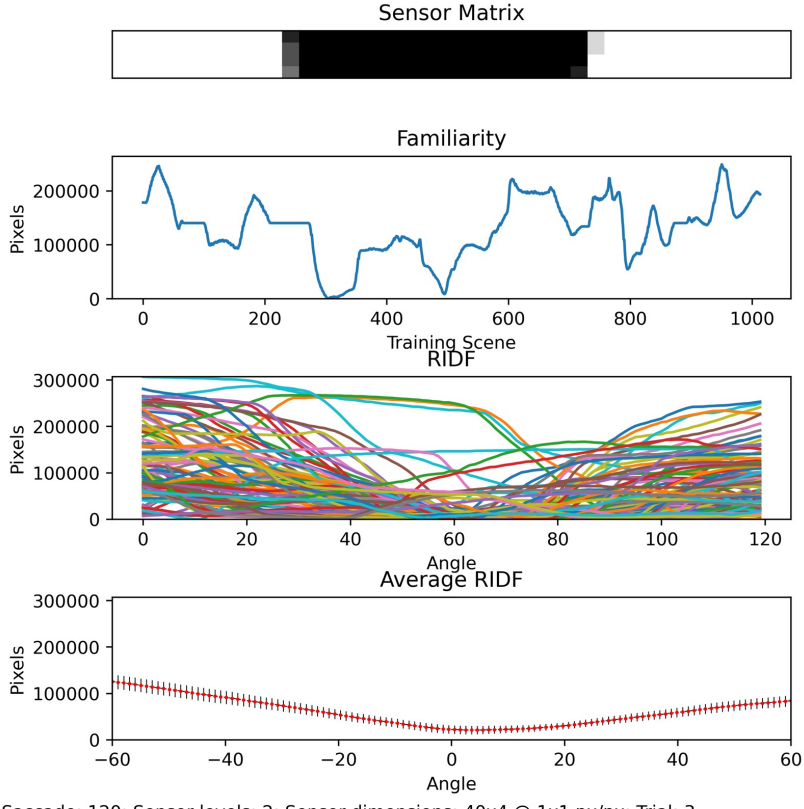




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 10261.19; RMSD/dist: 25.653; TD: 85876; p90: 84; p50: 54; complete: 0

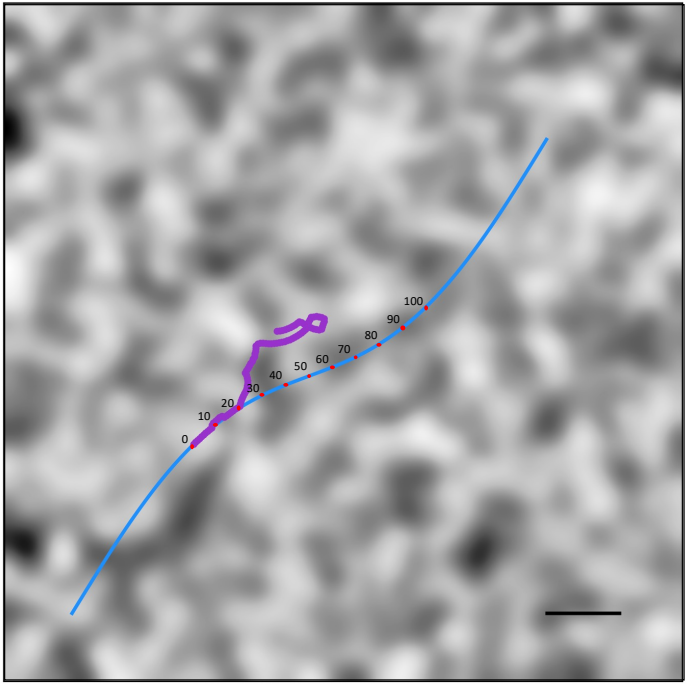
30%

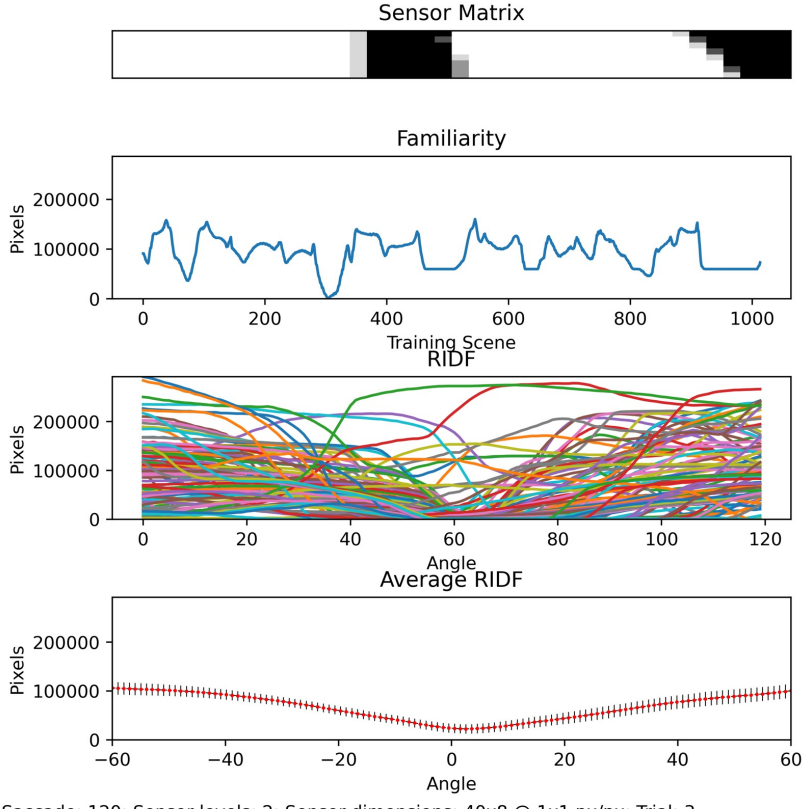




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 3031.97; RMSD/dist: 7.580; TD: 71560; p90: 74; p50: 44; complete: 0

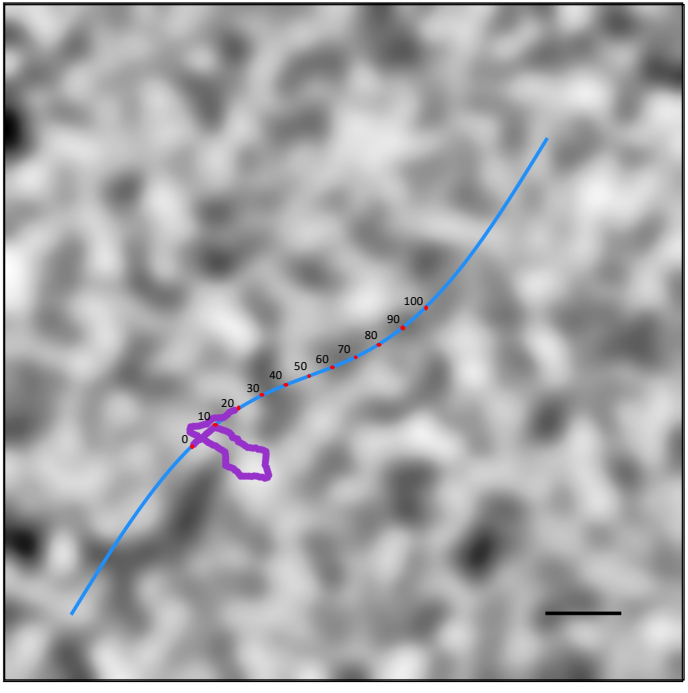
10%

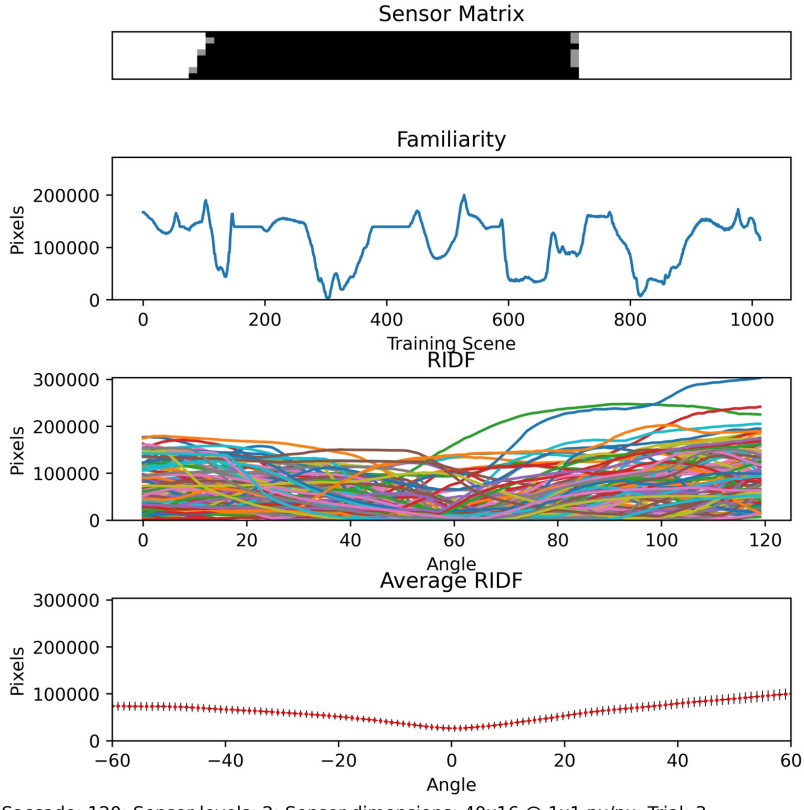




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 4510.52; RMSD/dist: 11.276; TD: 65582; p90: 64; p50: 36; complete: 0

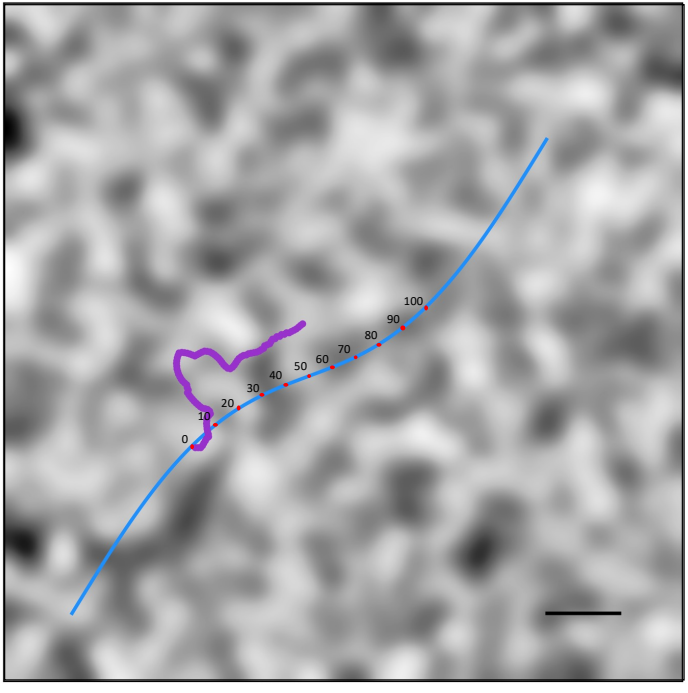
10%

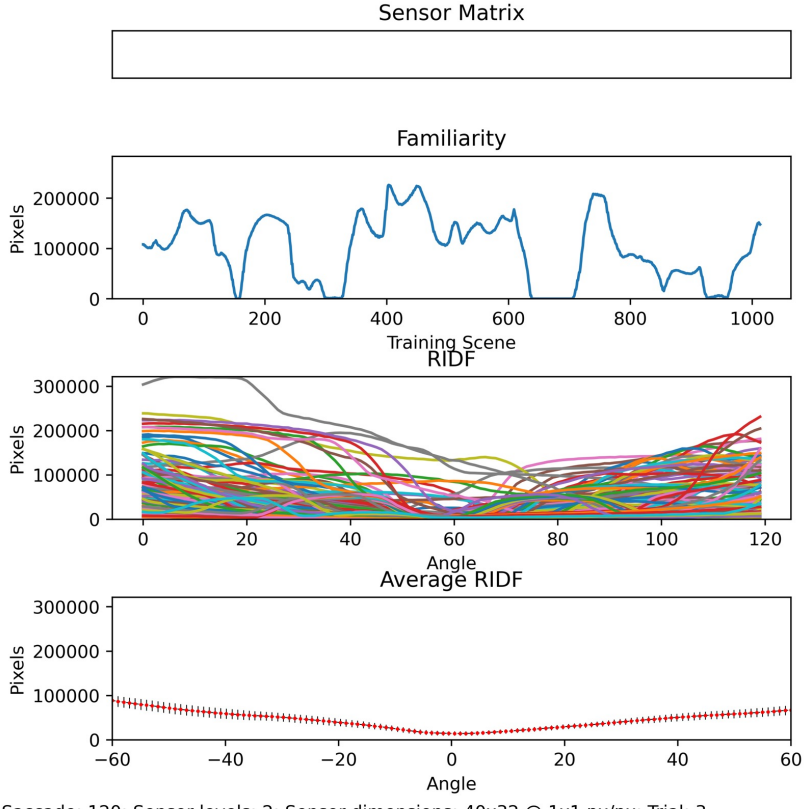




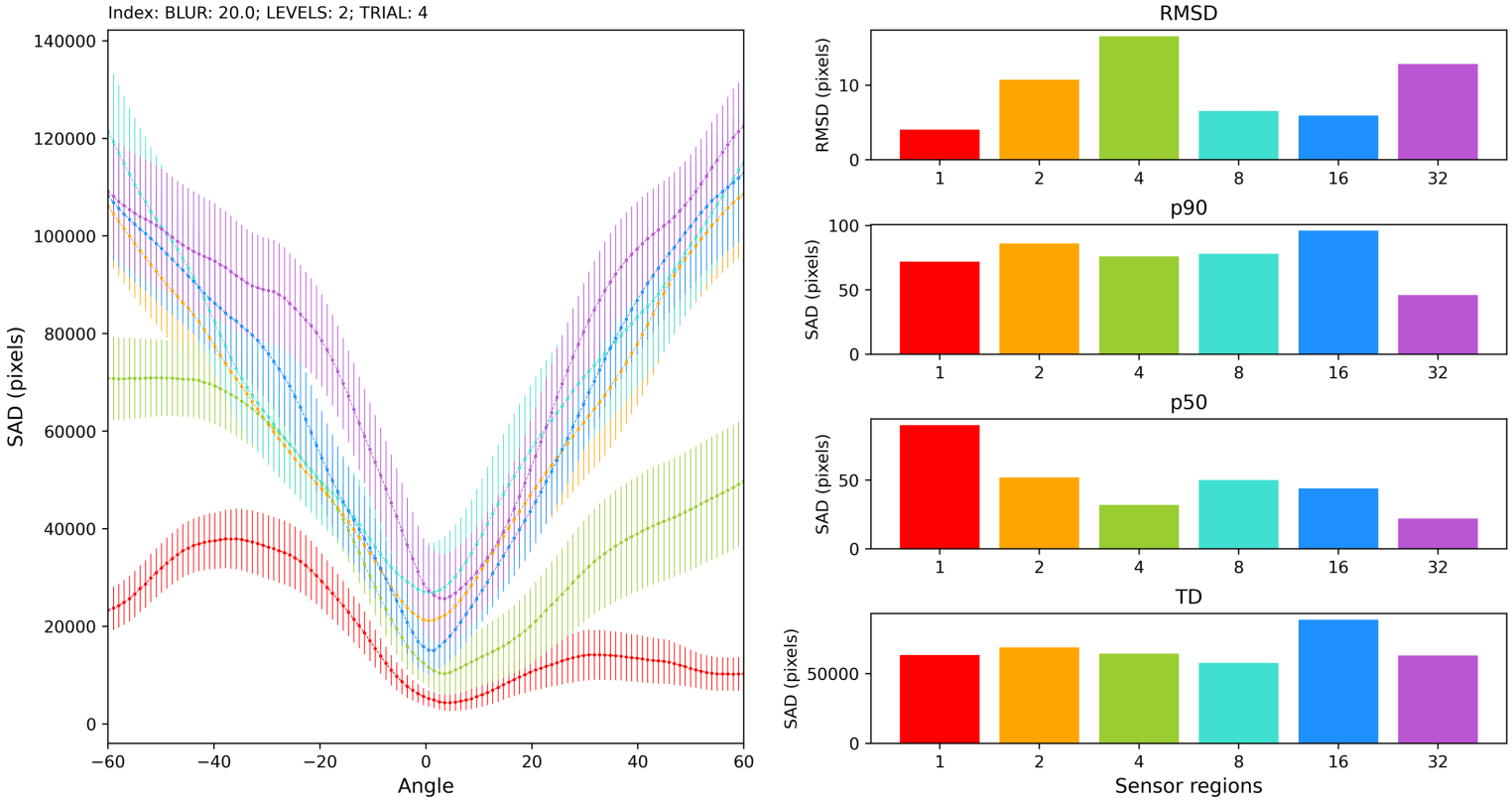
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 3892.38; RMSD/dist: 9.731; TD: 71703; p90: 120; p50: 66; complete: 0

0%

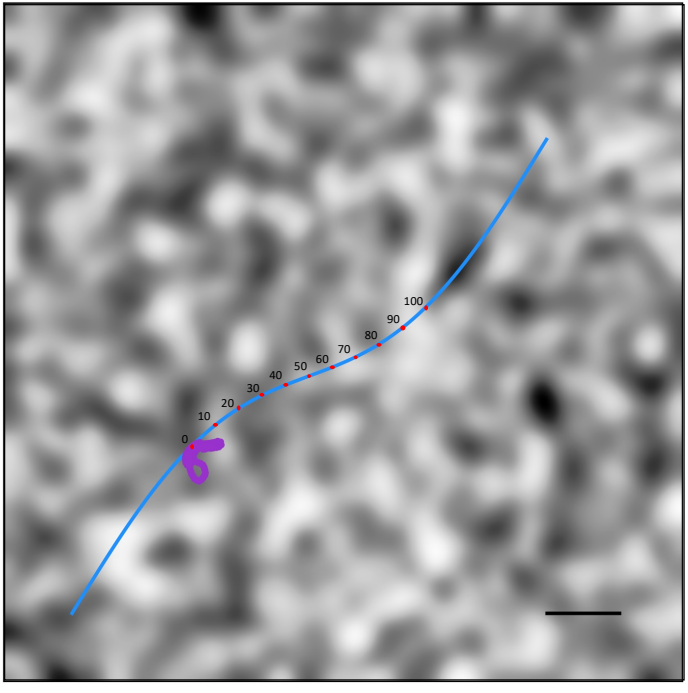


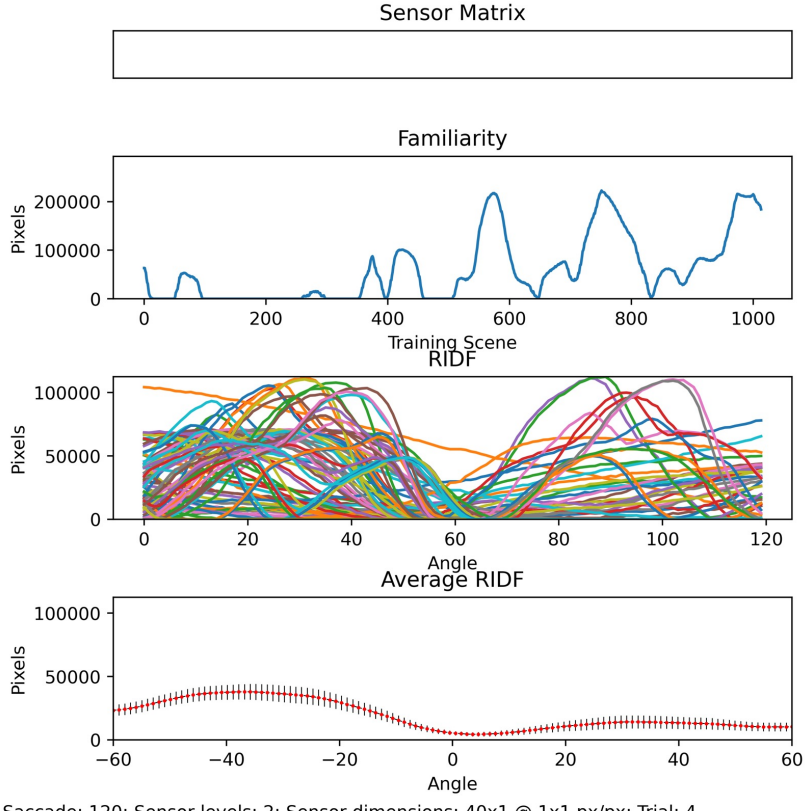


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 6314.84; RMSD/dist: 15.787; TD: 94652; p90: 120; p50: 86; complete: 0


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

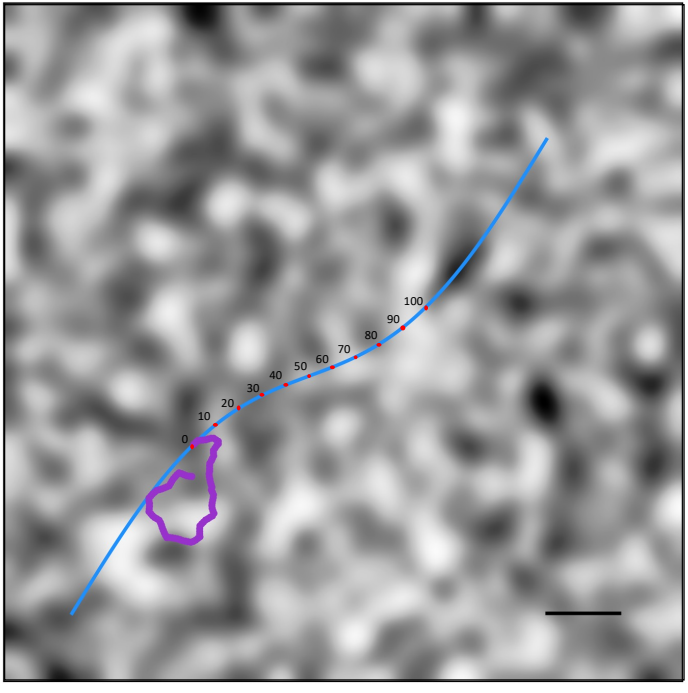
0%

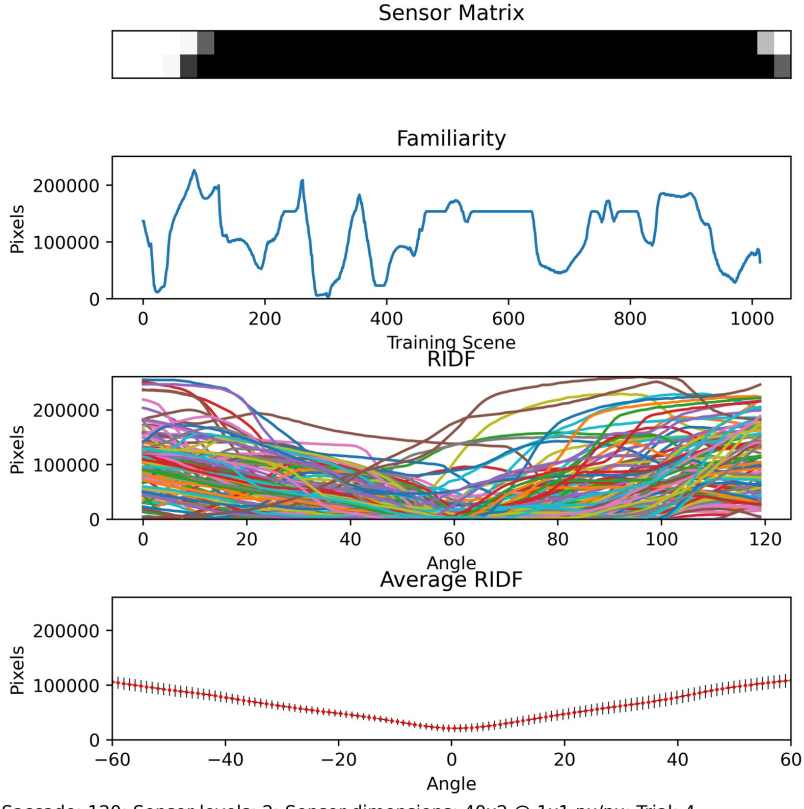




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 1617.53; RMSD/dist: 4.044; TD: 63286; p90: 72; p50: 90; complete: 0

0%

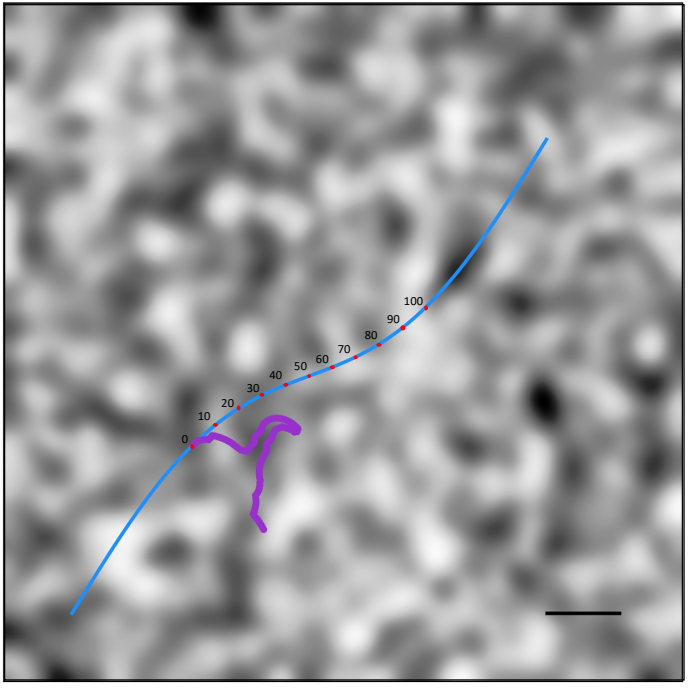


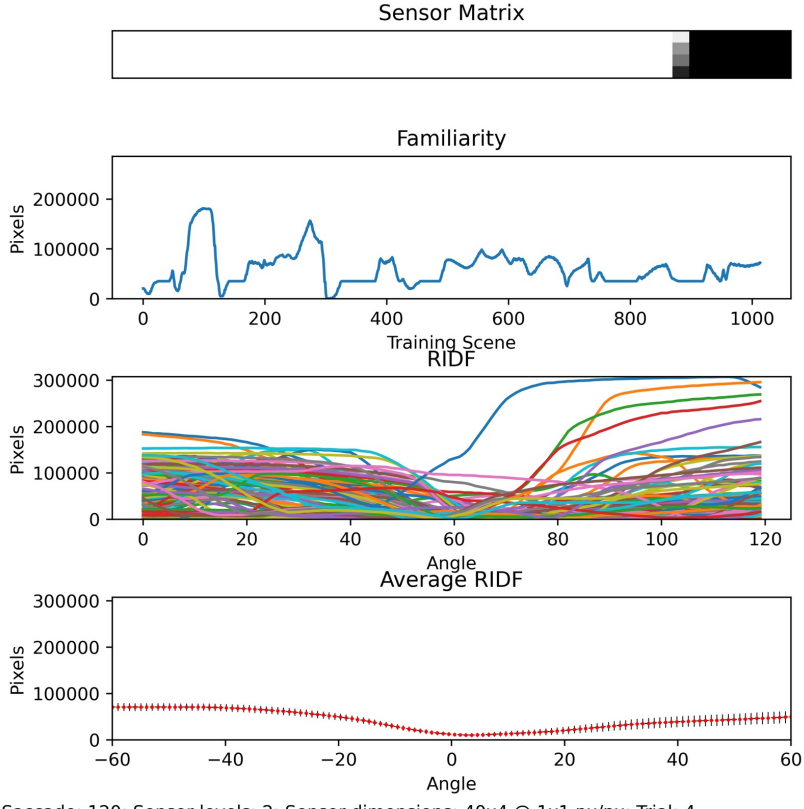


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4283.62; RMSD/dist: 10.709; TD: 68855; p90: 86; p50: 52; complete: 0

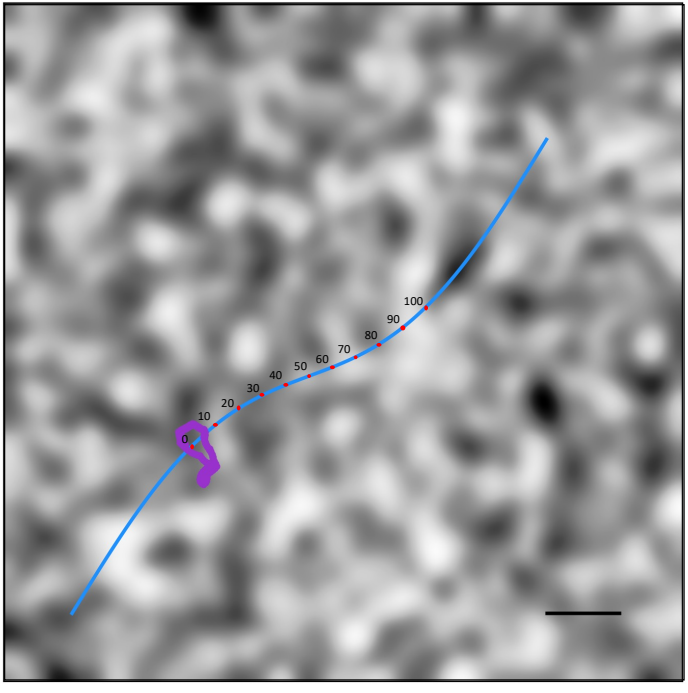
0%

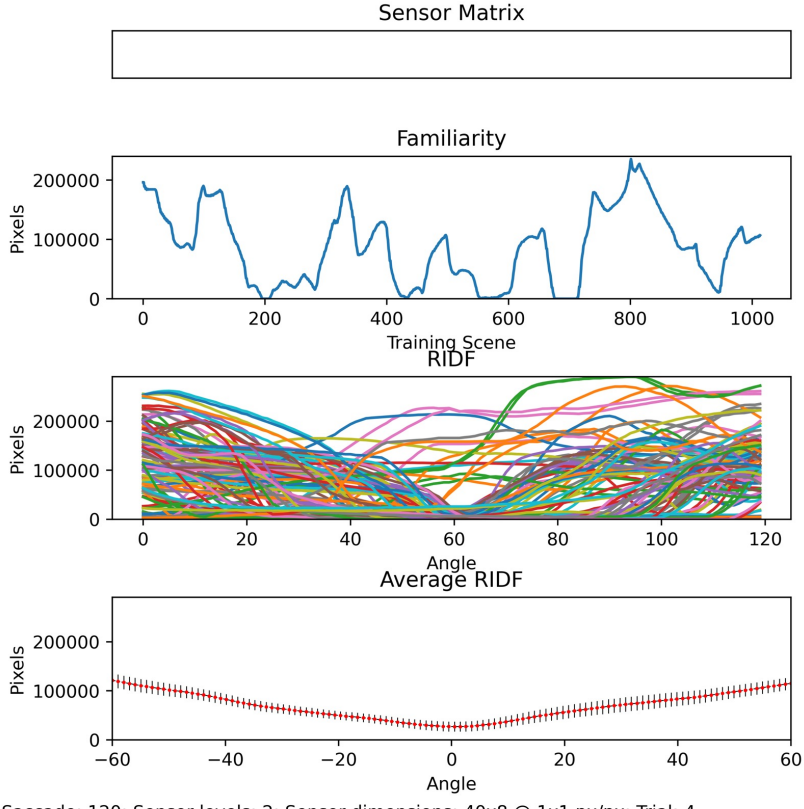




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 6624.32; RMSD/dist: 16.561; TD: 64326; p90: 76; p50: 32; complete: 0

0%

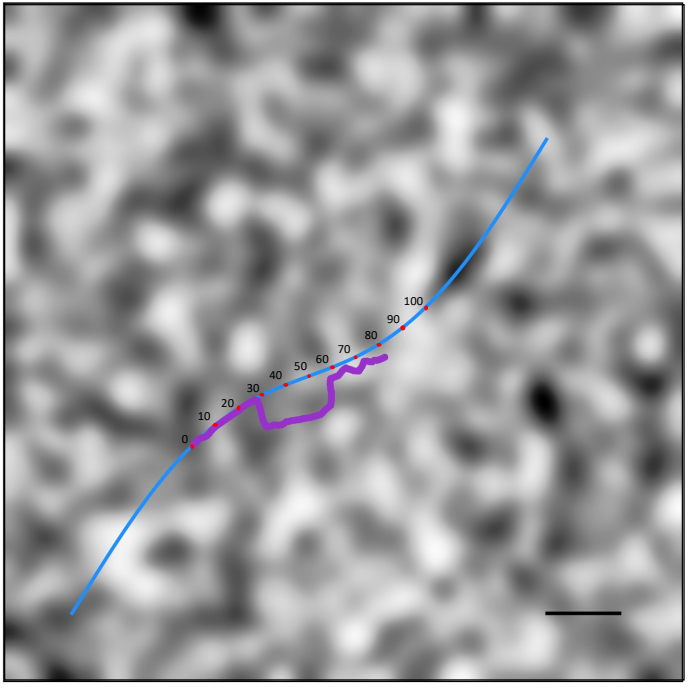


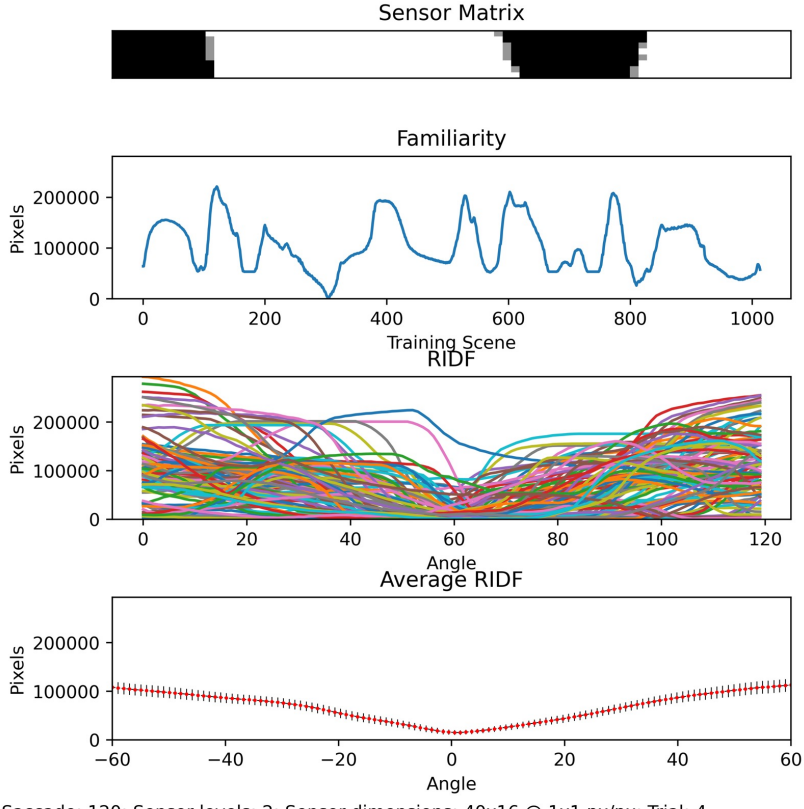


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2612.20; RMSD/dist: 6.530; TD: 57711; p90: 78; p50: 50; complete: 0

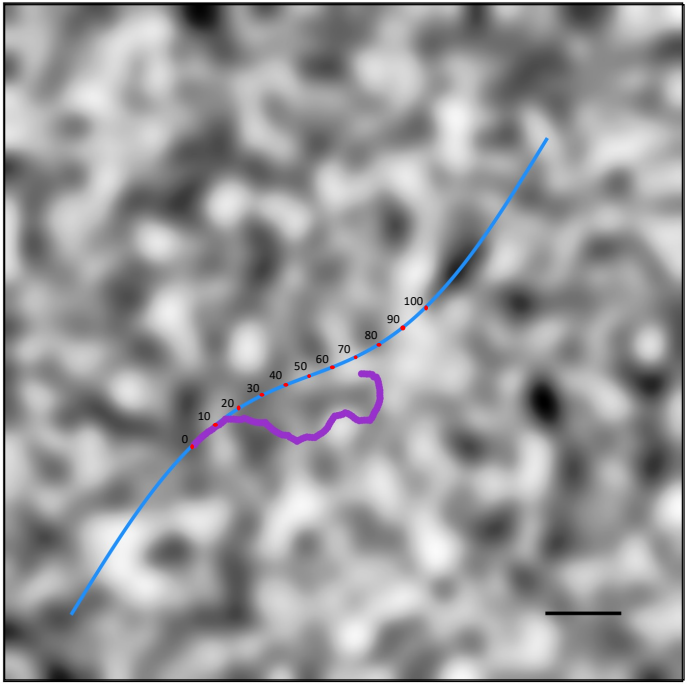
20%

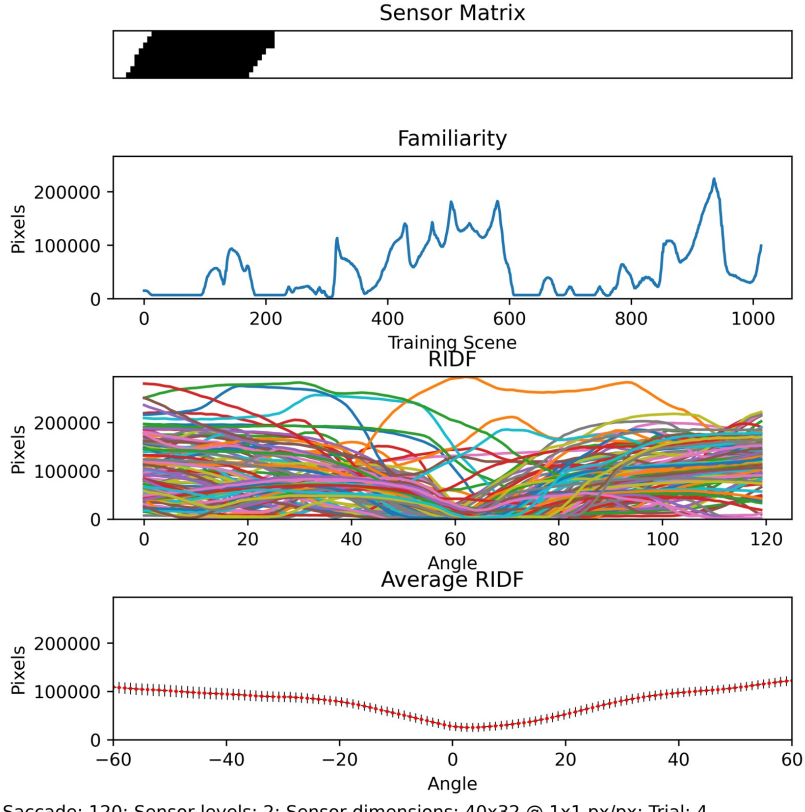




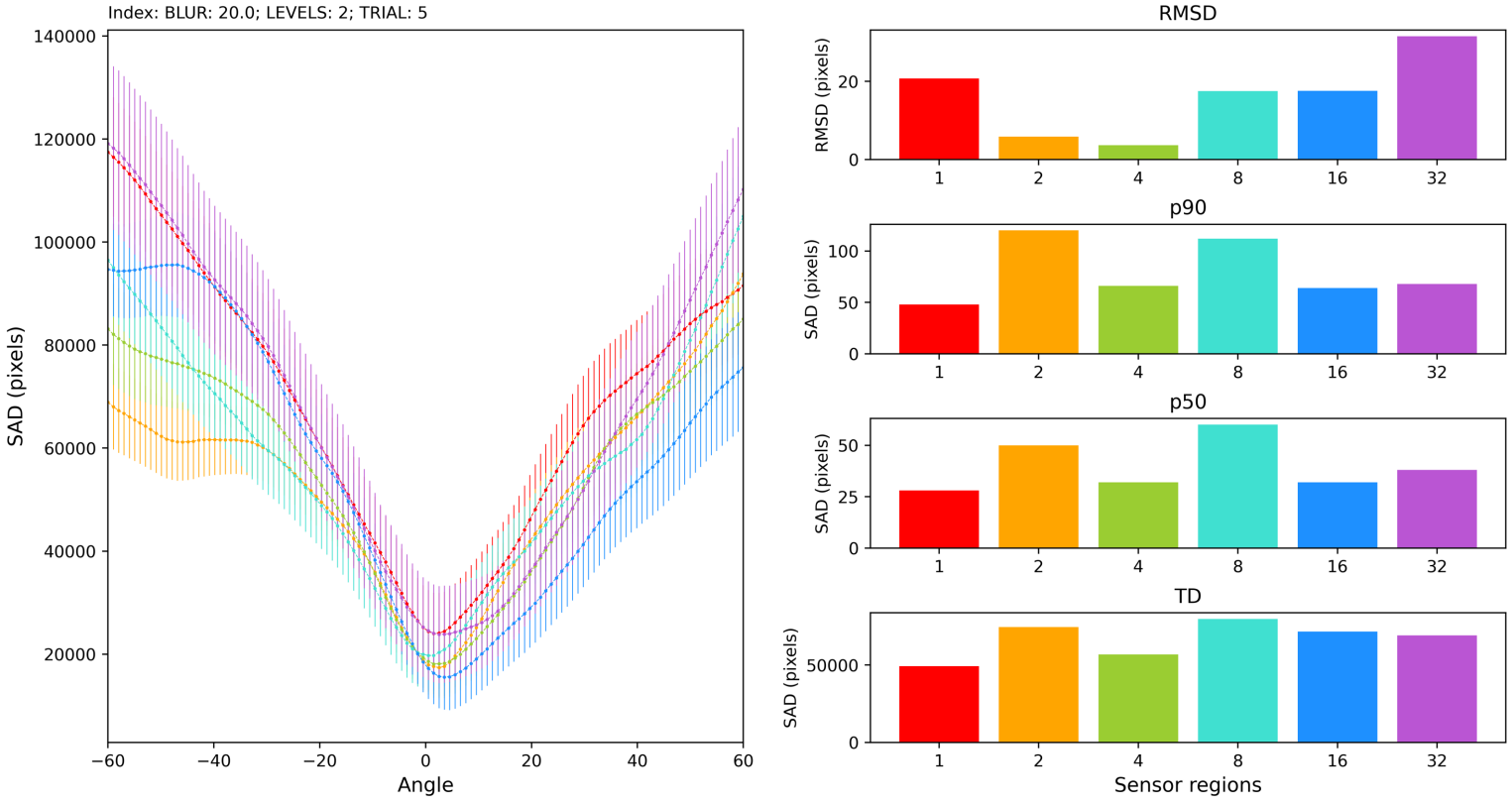
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 2368.56; RMSD/dist: 5.921; TD: 88679; p90: 96; p50: 44; complete: 0

10%

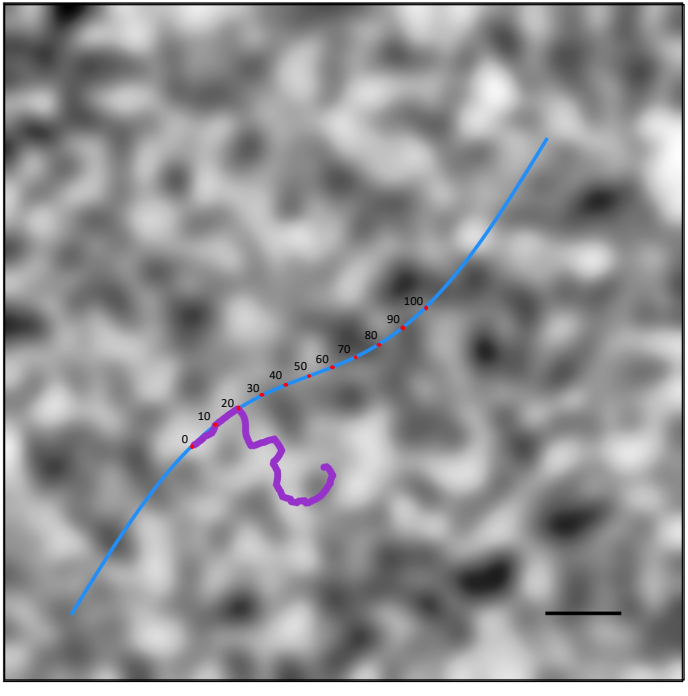


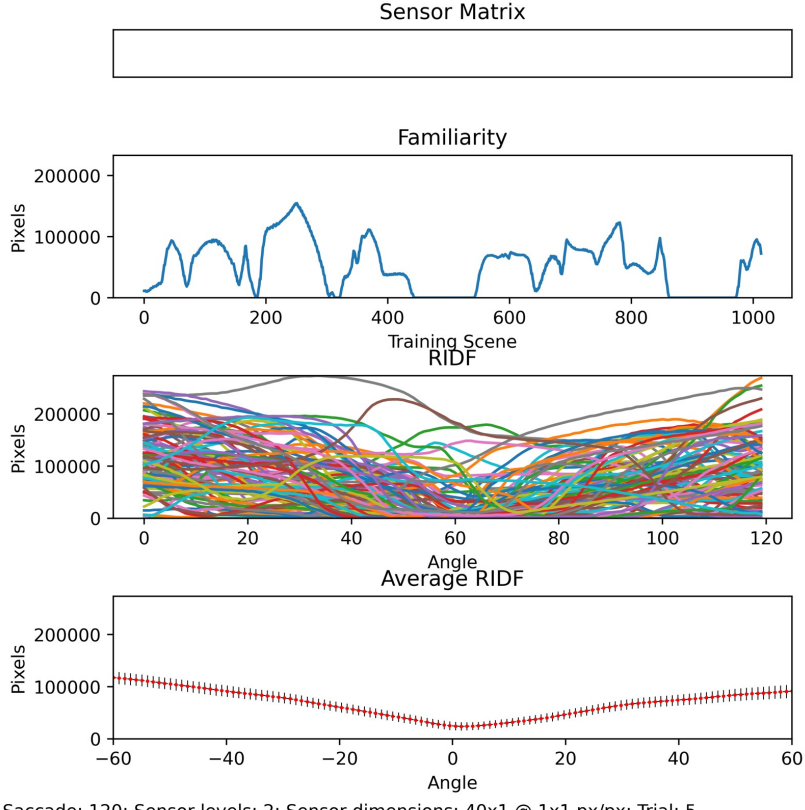


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 5137.66; RMSD/dist: 12.844; TD: 62976; p90: 46; p50: 22; complete: 0


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

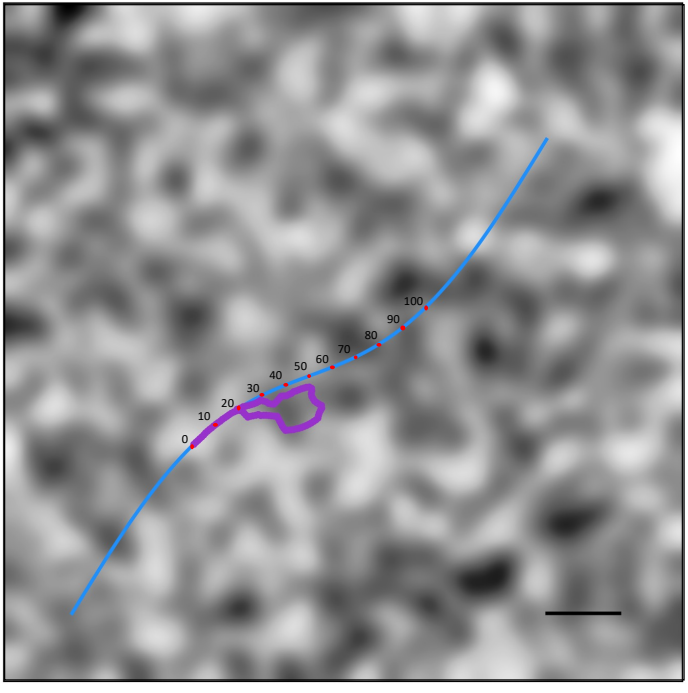


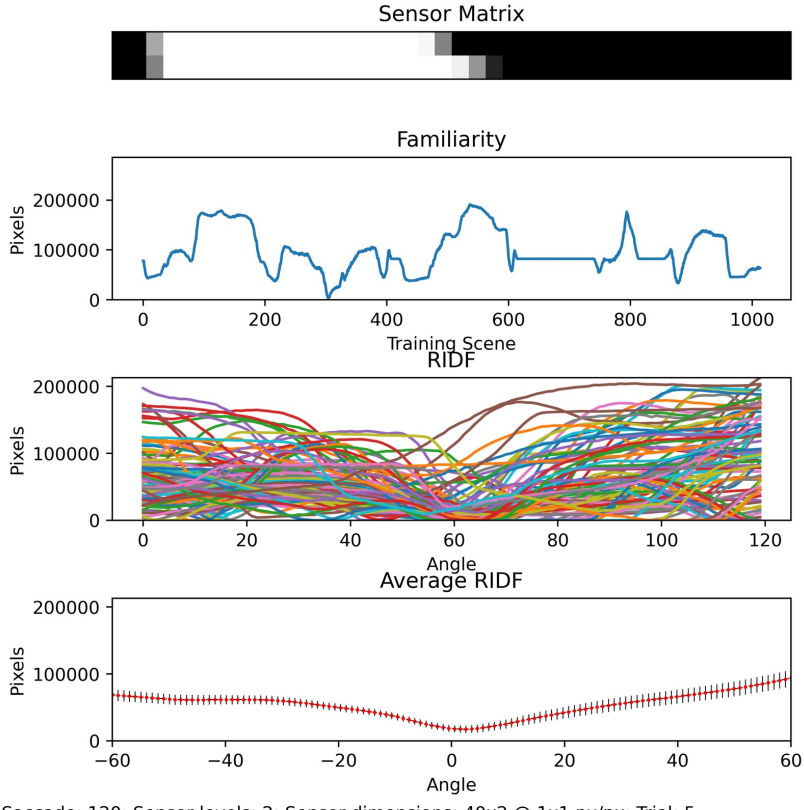


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 8306.41; RMSD/dist: 20.766; TD: 49238; p90: 48; p50: 28; complete: 0

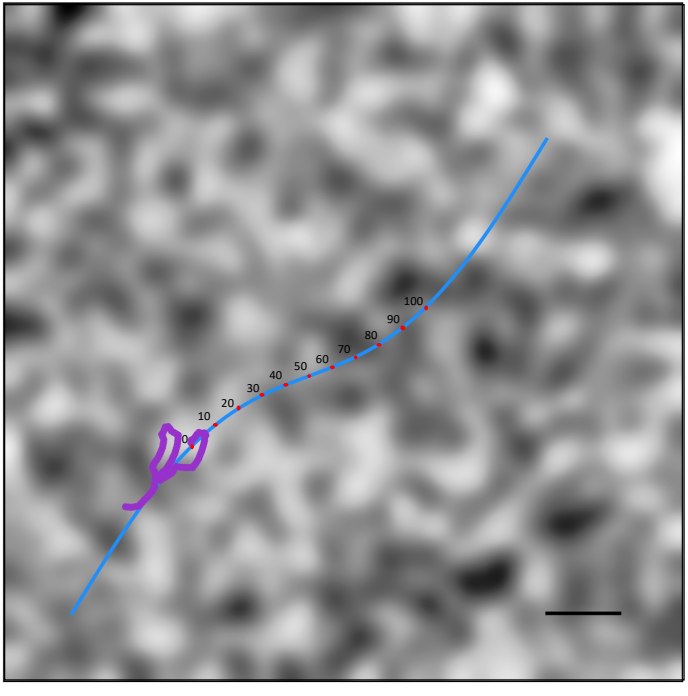
20%

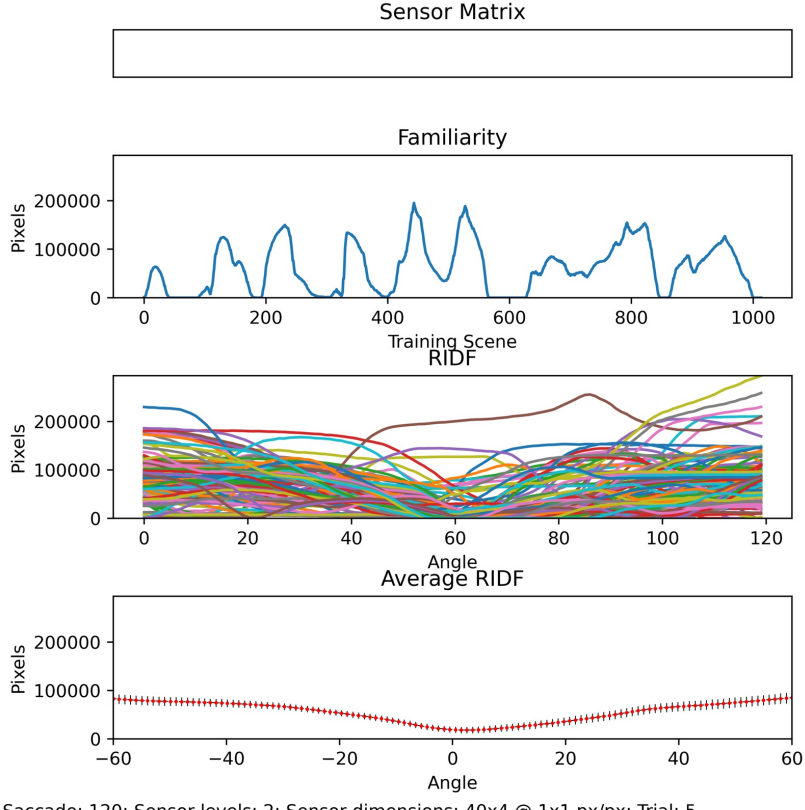




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 2345.96; RMSD/dist: 5.865; TD: 74484; p90: 120; p50: 50; complete: 0

0%

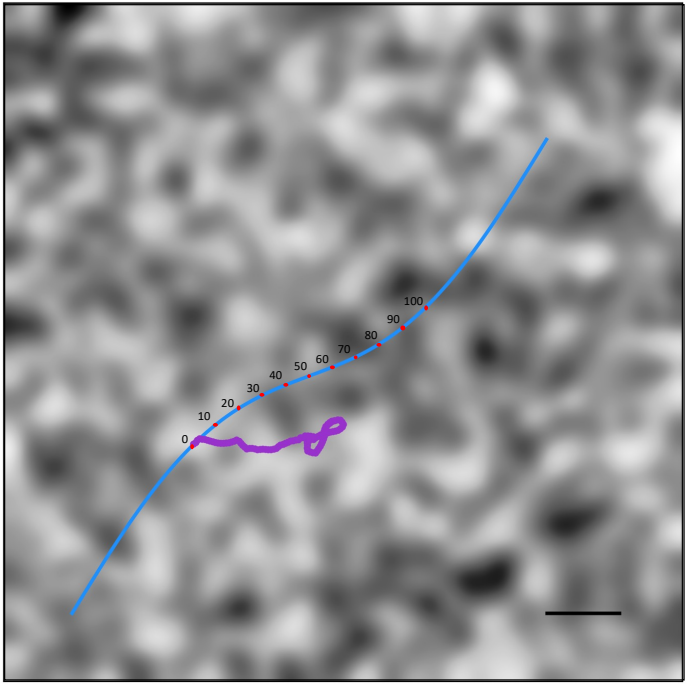


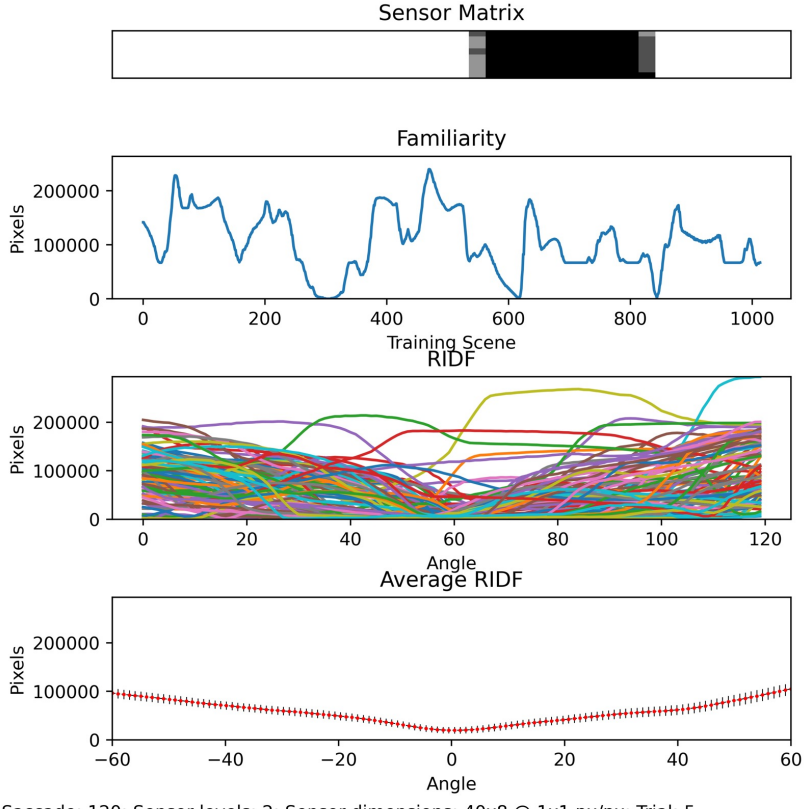


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1464.26; RMSD/dist: 3.661; TD: 56778; p90: 66; p50: 32; complete: 0

0%

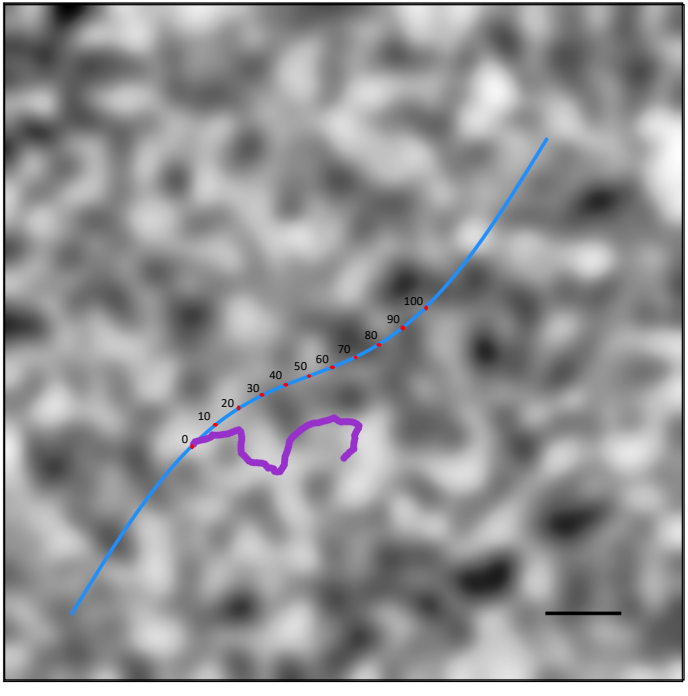


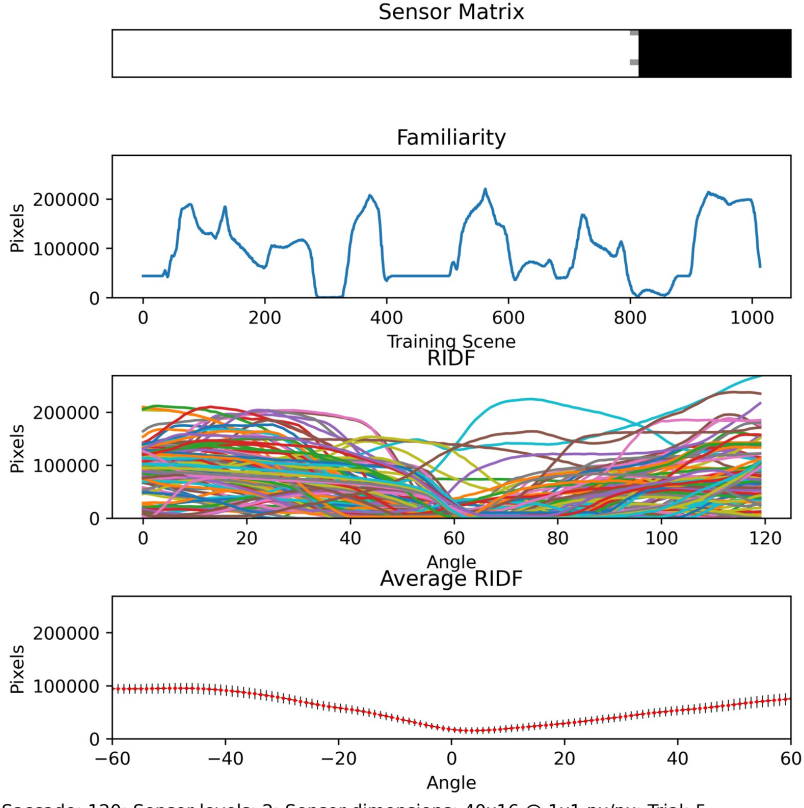


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 7008.28; RMSD/dist: 17.521; TD: 79745; p90: 112; p50: 60; complete: 0

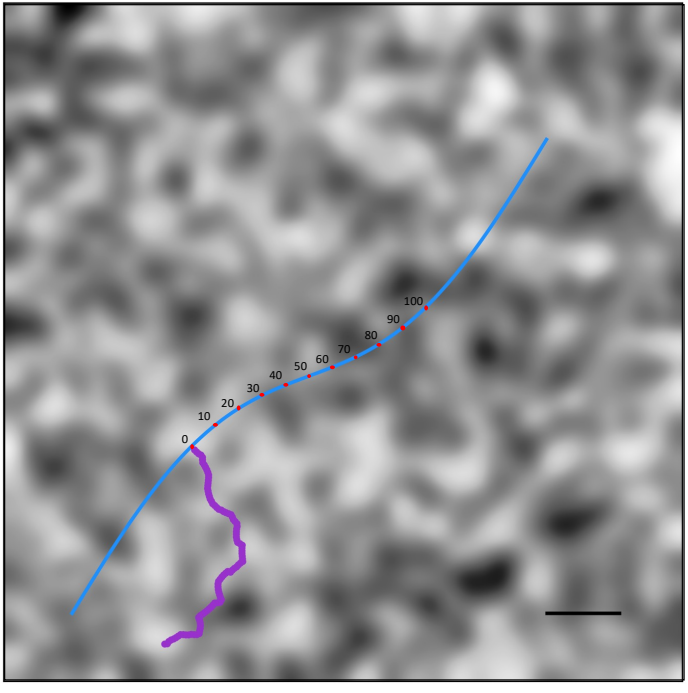
0%

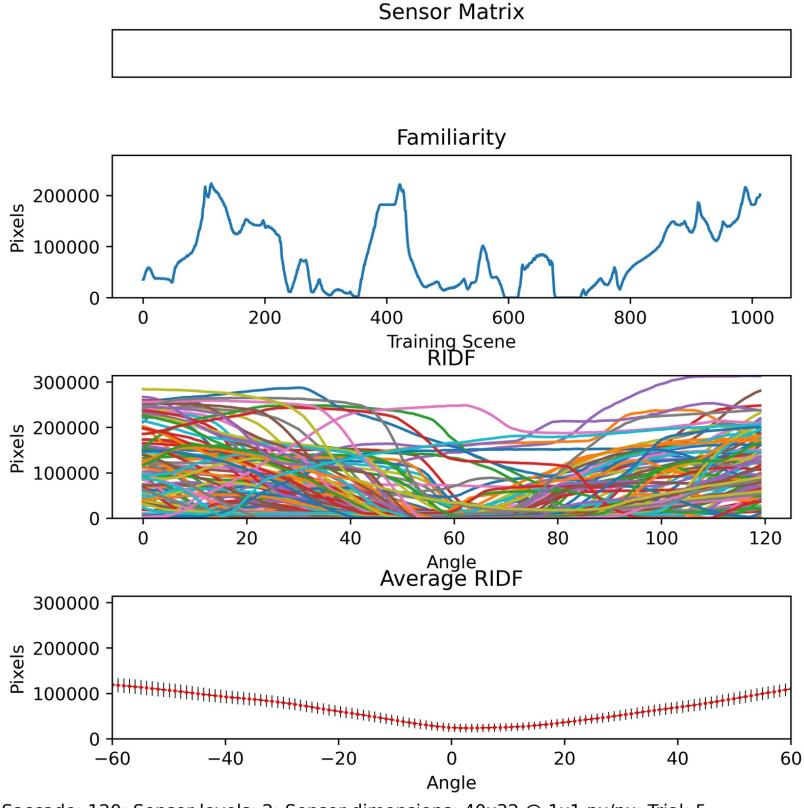




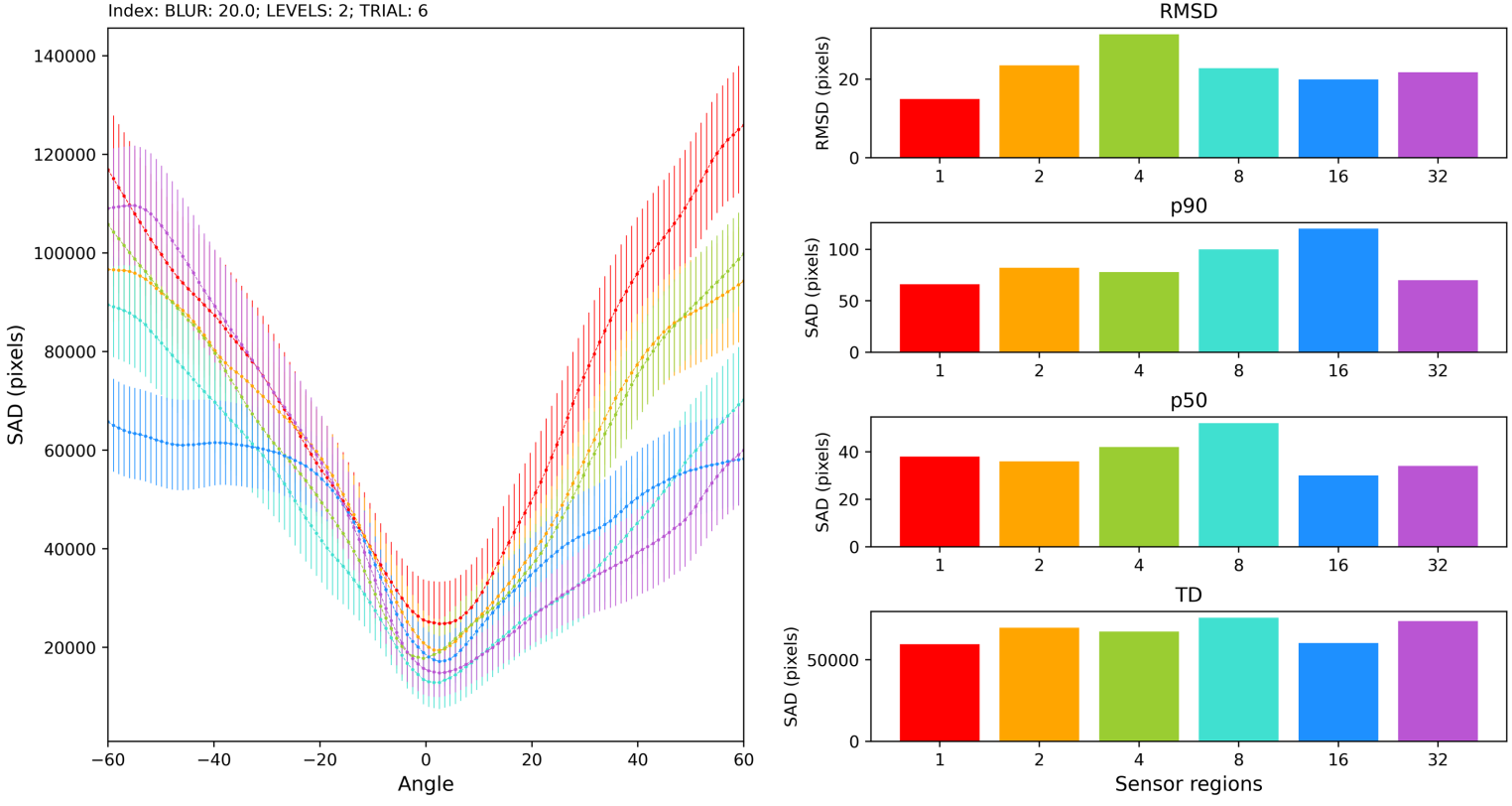
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 7028.59; RMSD/dist: 17.571; TD: 71553; p90: 64; p50: 32; complete: 0

0%

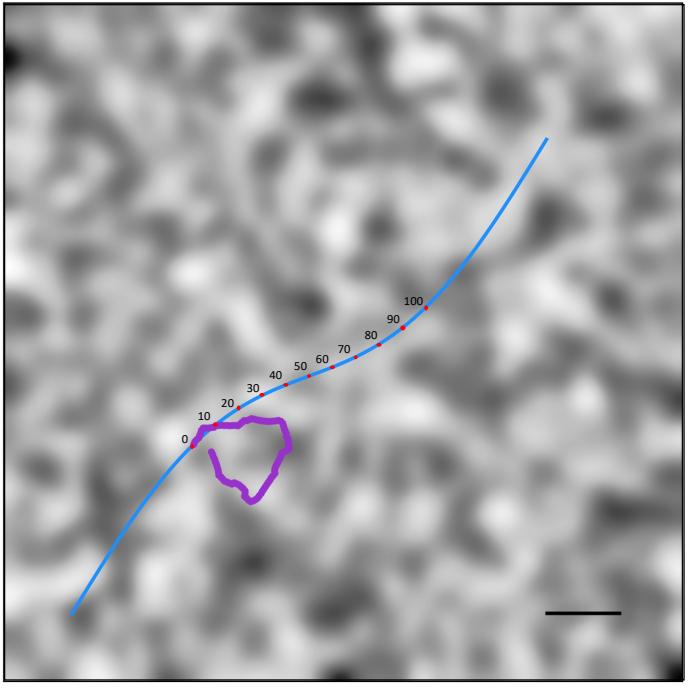


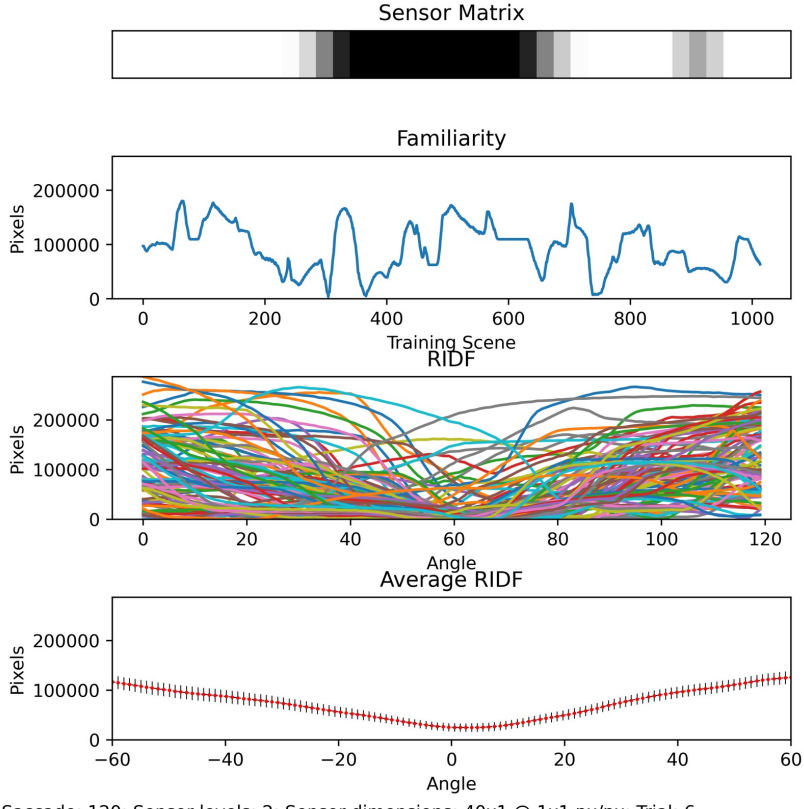


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 12636.54; RMSD/dist: 31.591; TD: 69161; p90: 68; p50: 38; complete: 0


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

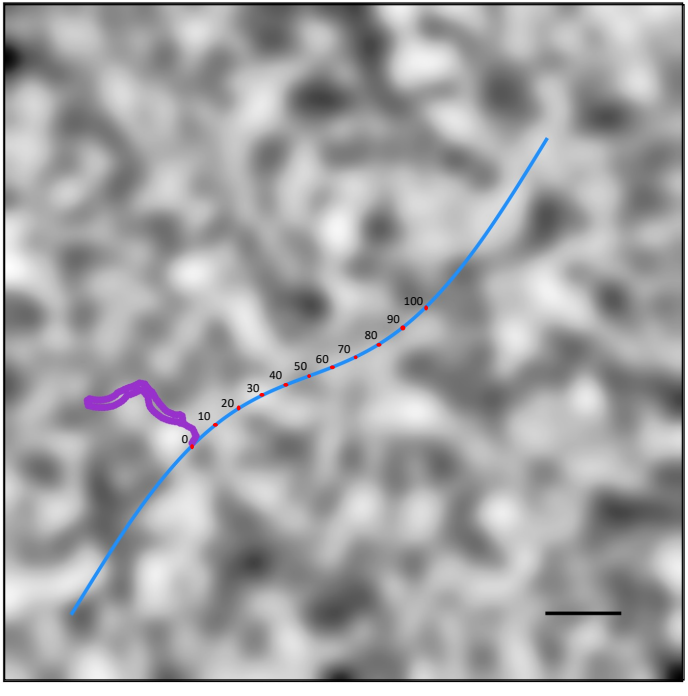
0%

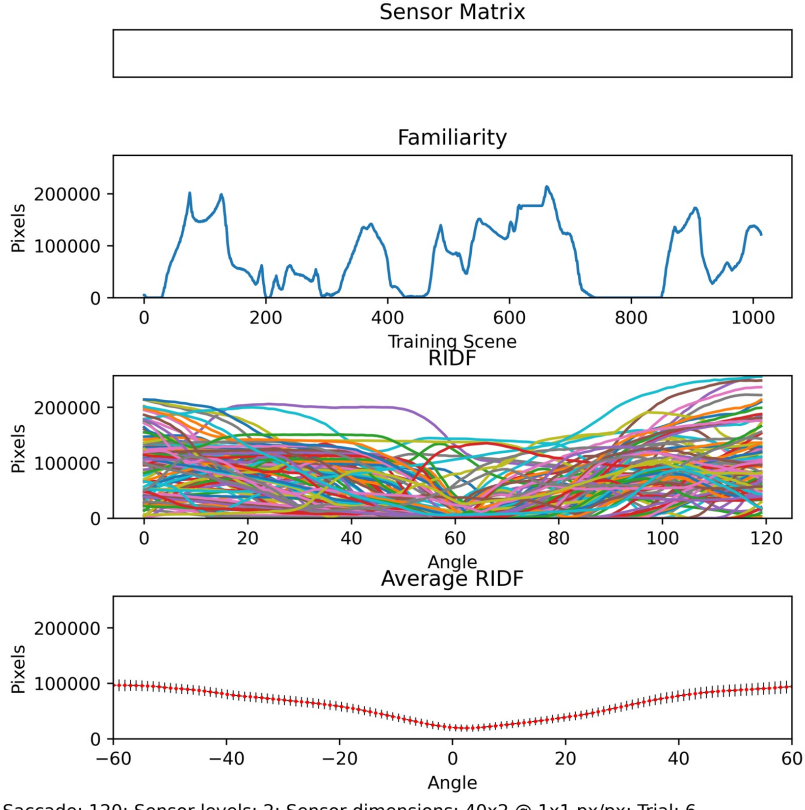




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 5986.73; RMSD/dist: 14.967; TD: 59611; p90: 66; p50: 38; complete: 0

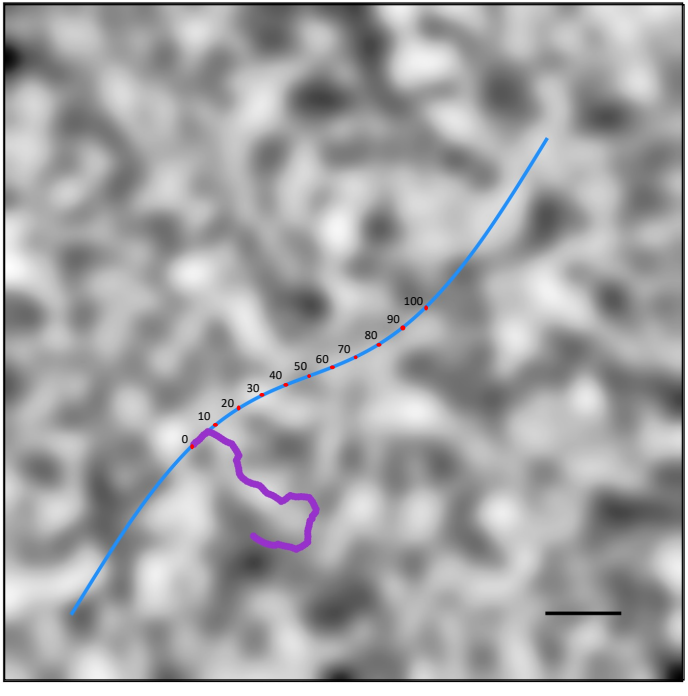
0%

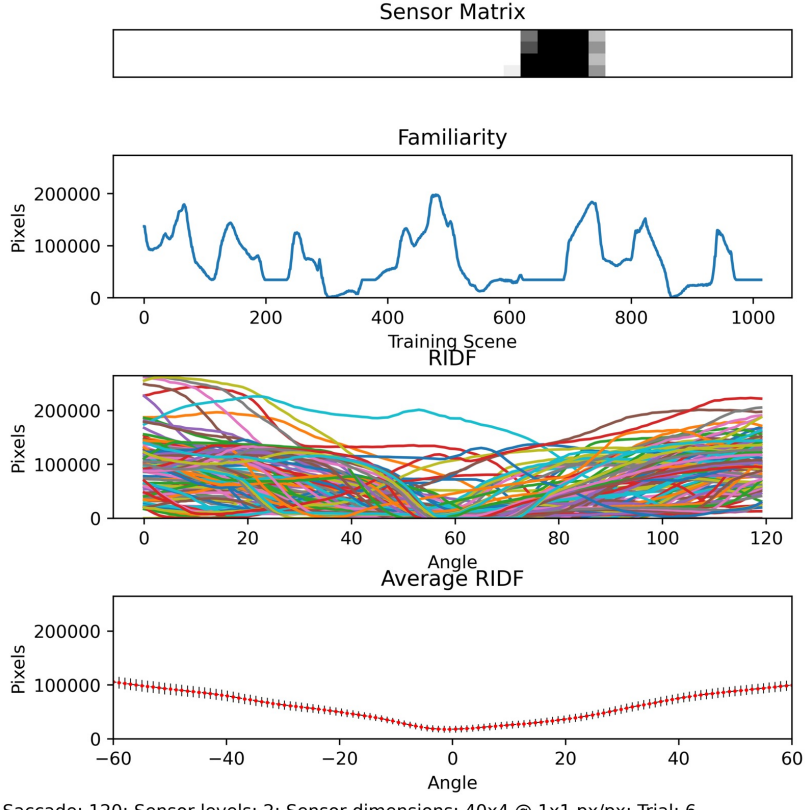




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 9400.06; RMSD/dist: 23.500; TD: 69676; p90: 82; p50: 36; complete: 0

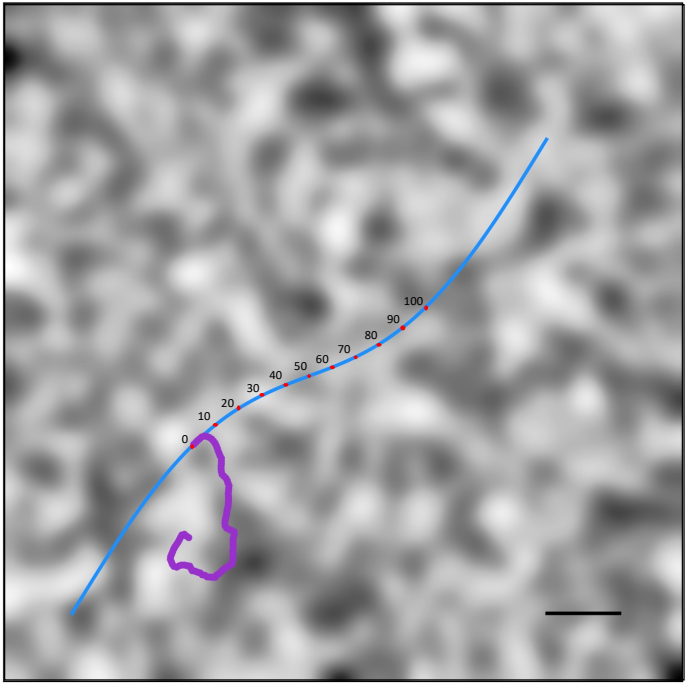
0%

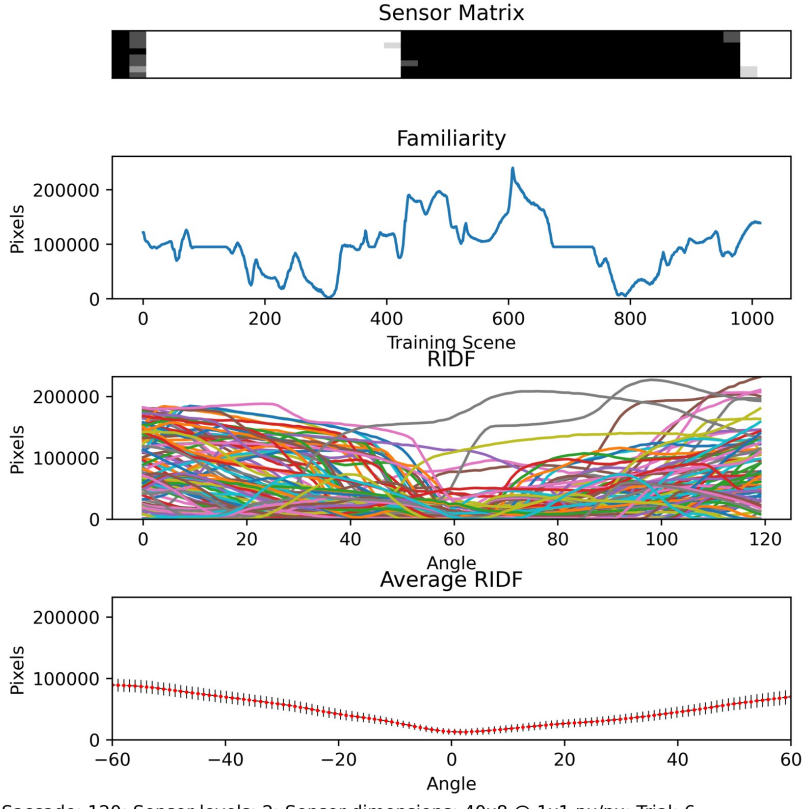




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 12569.99; RMSD/dist: 31.425; TD: 67288; p90: 78; p50: 42; complete: 0

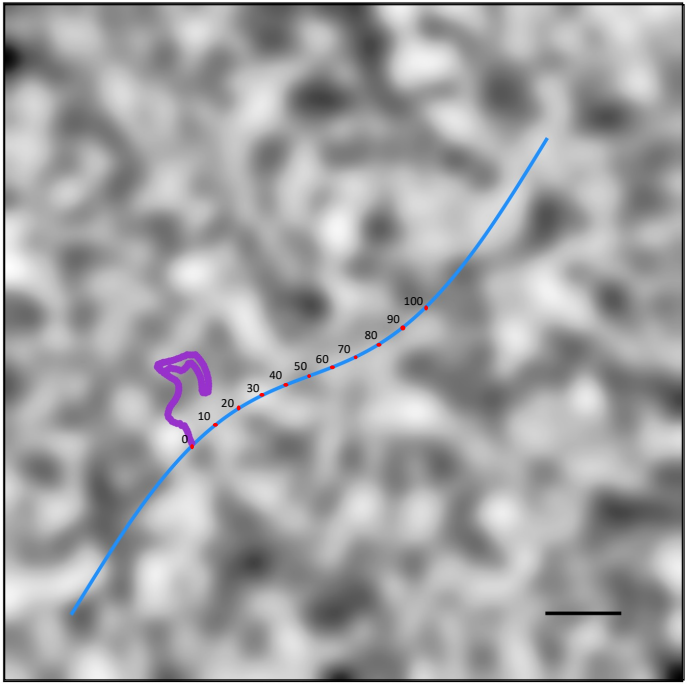
0%

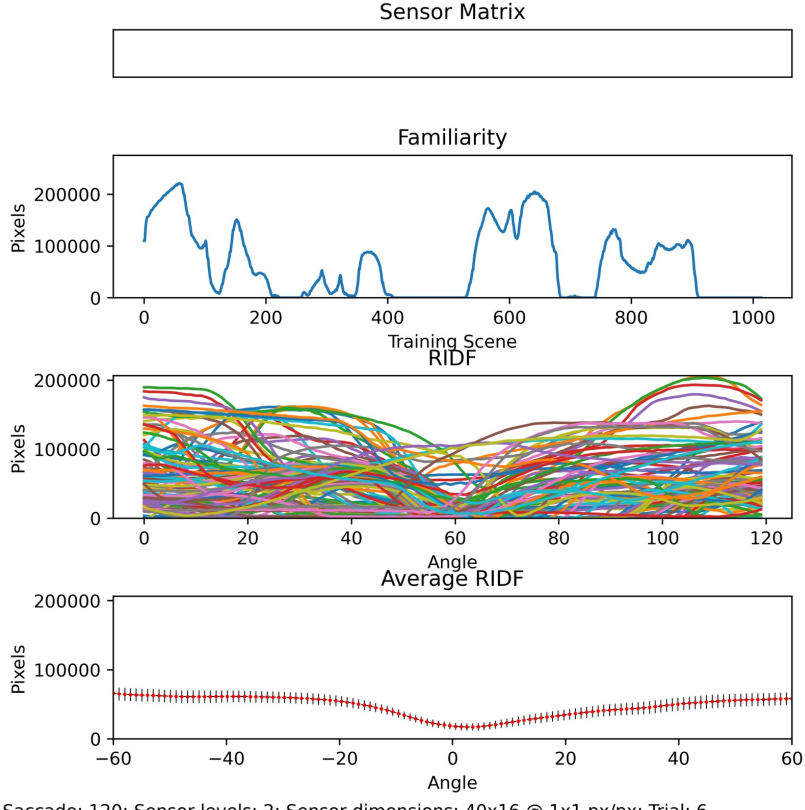




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 9117.06; RMSD/dist: 22.793; TD: 75813; p90: 100; p50: 52; complete: 0

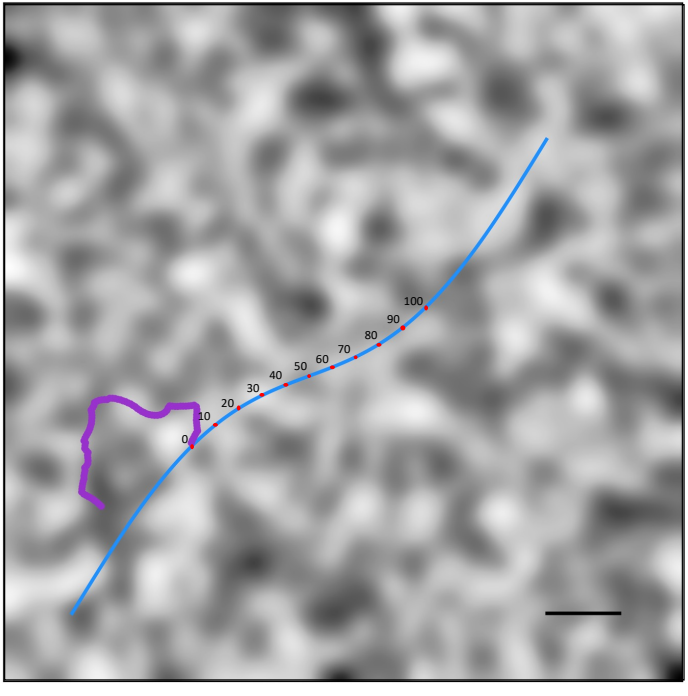
0%

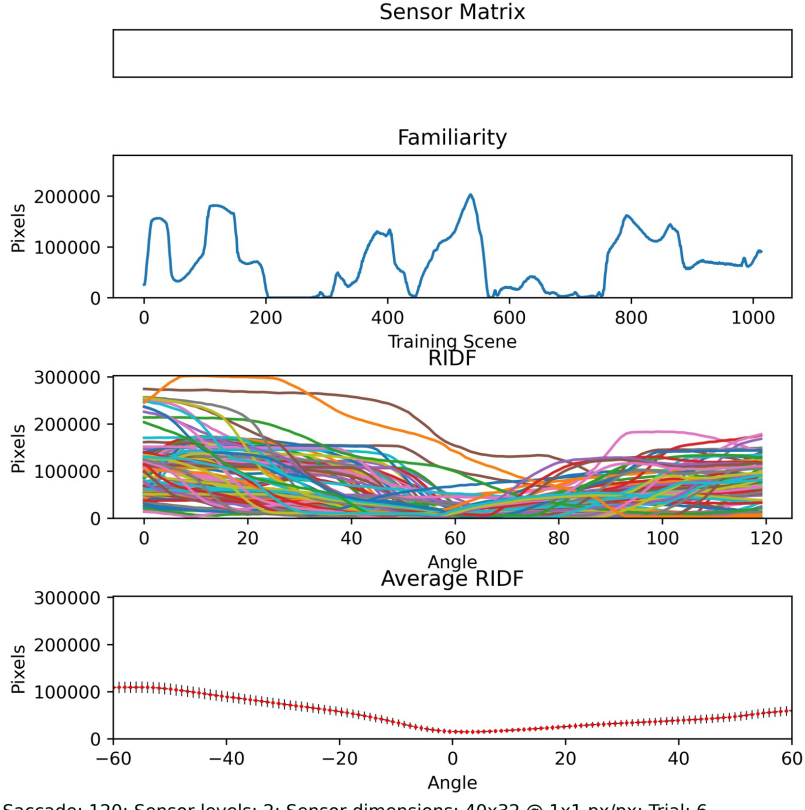




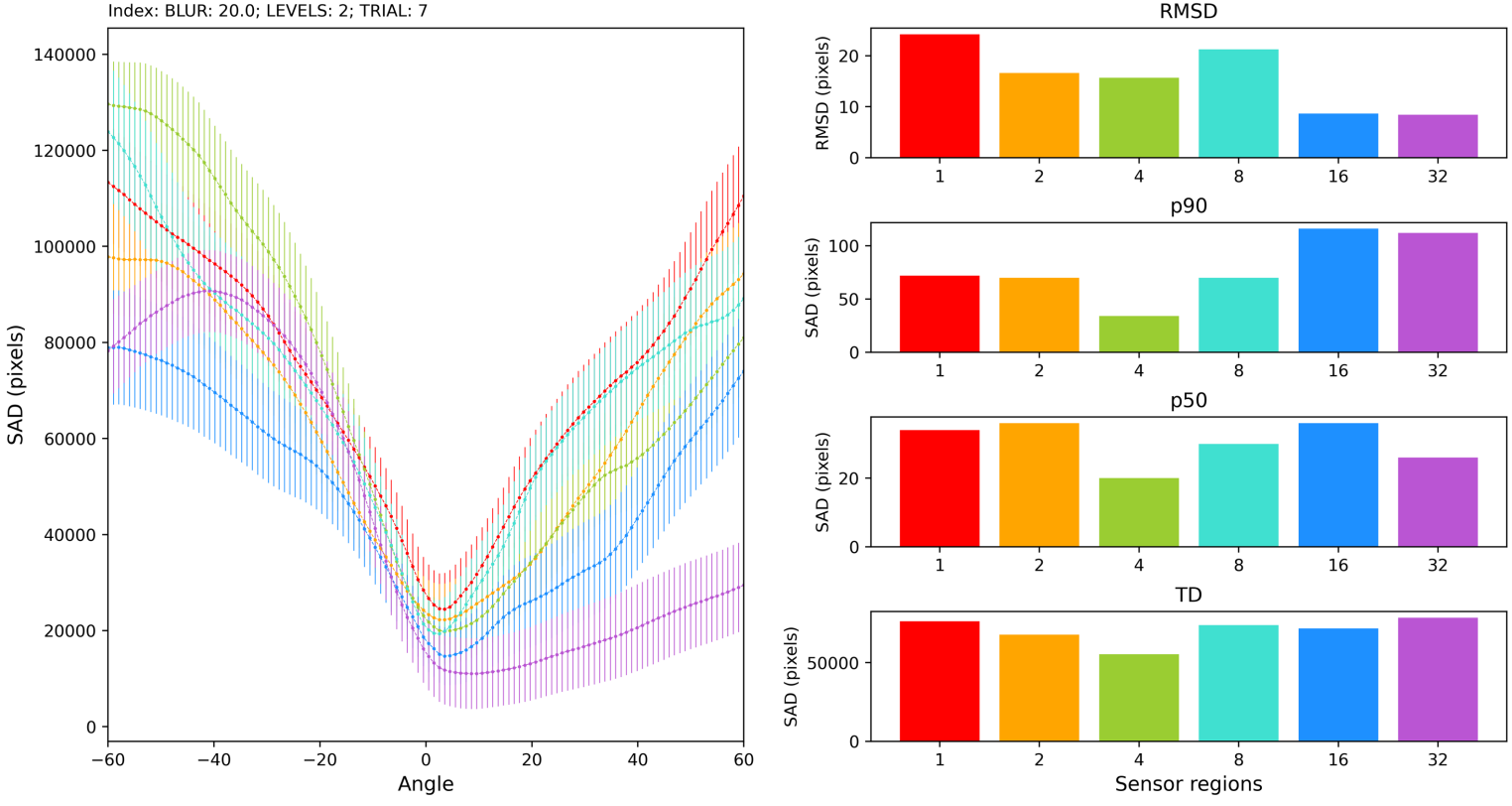
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 7972.05; RMSD/dist: 19.930; TD: 60269; p90: 120; p50: 30; complete: 0

0%

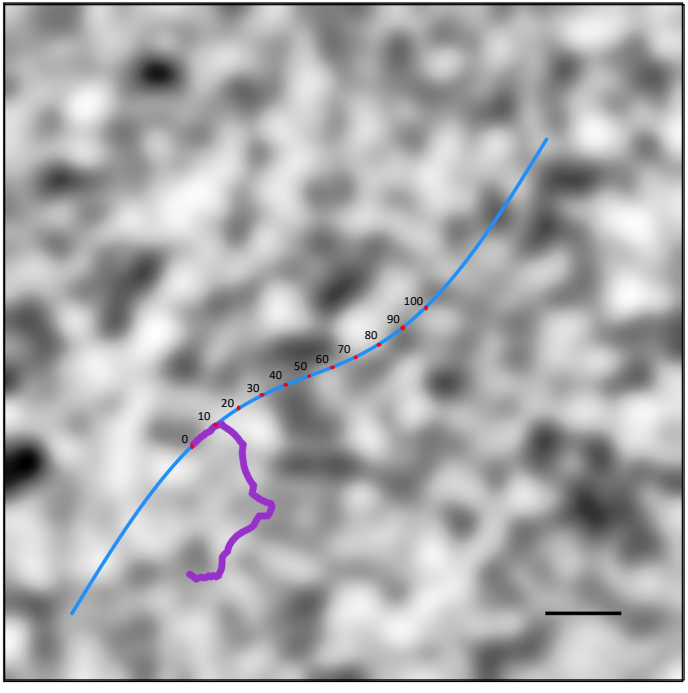


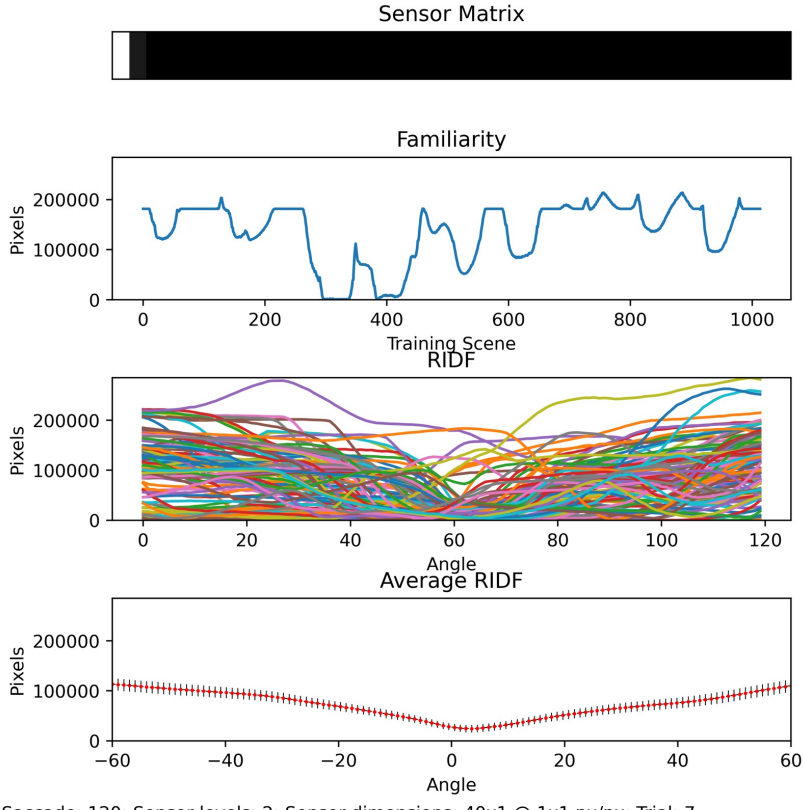


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 8686.68; RMSD/dist: 21.717; TD: 73847; p90: 70; p50: 34; complete: 0


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

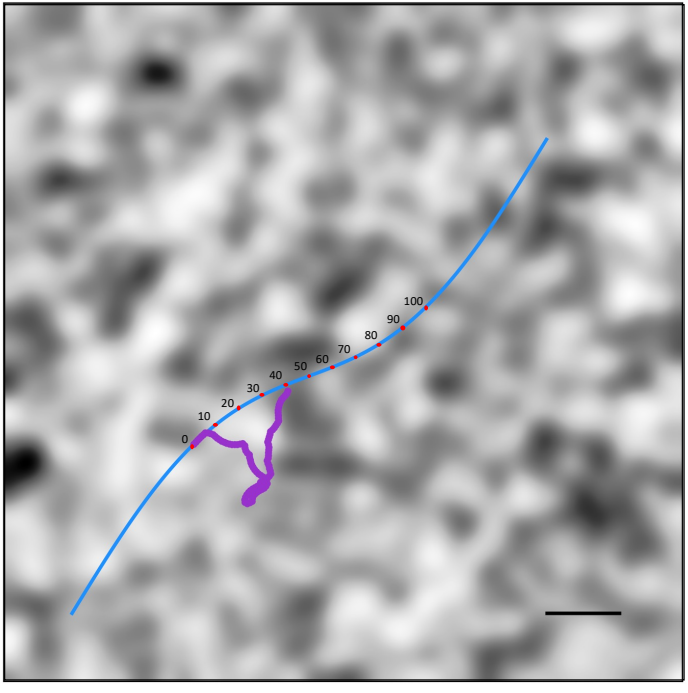
10%

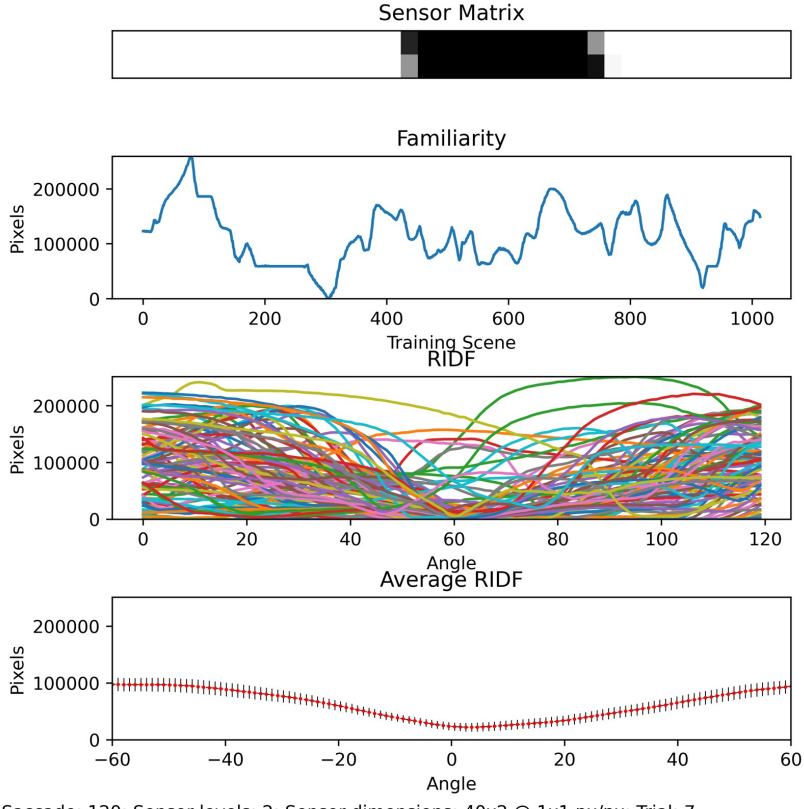




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 9687.52; RMSD/dist: 24.219; TD: 76302; p90: 72; p50: 34; complete: 0

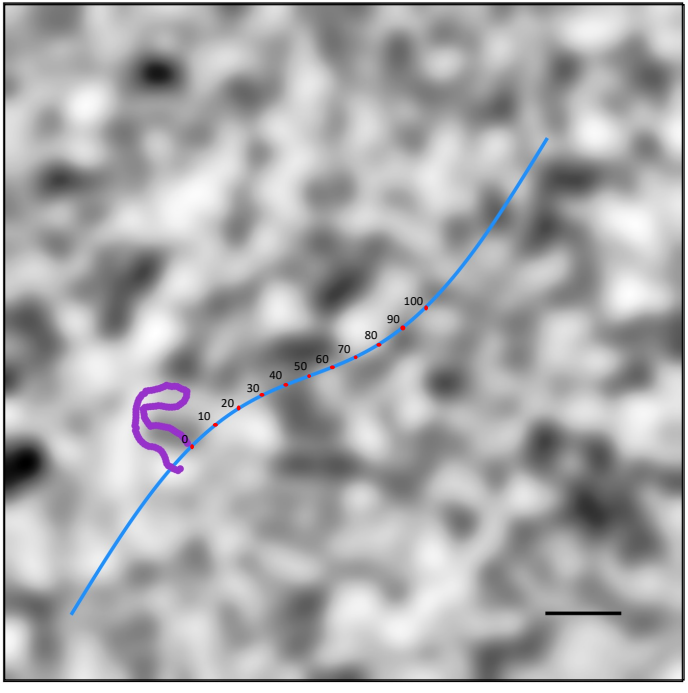
0%

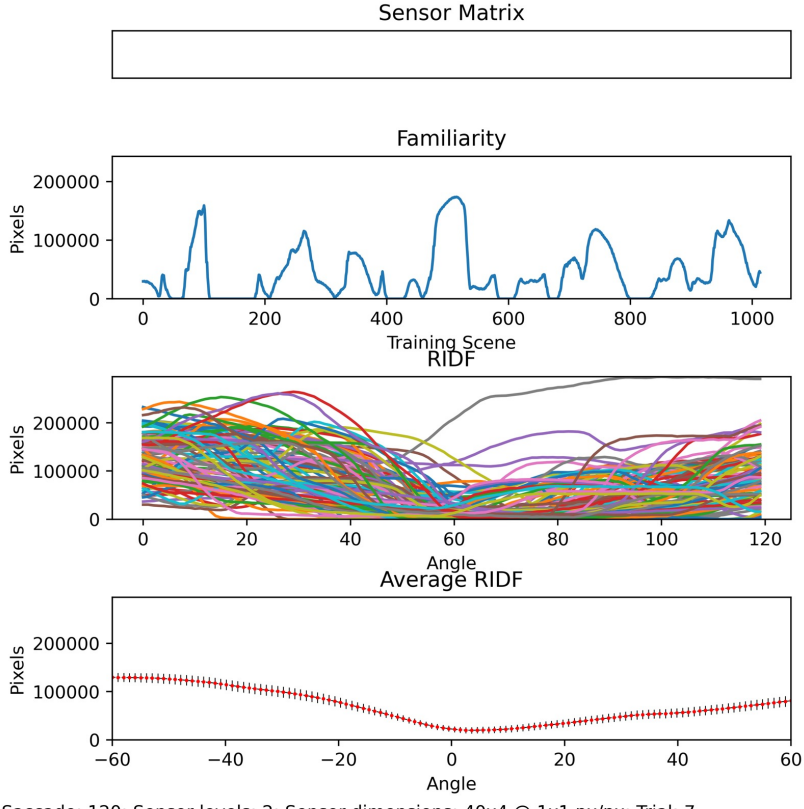




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 6652.09; RMSD/dist: 16.630; TD: 67750; p90: 70; p50: 36; complete: 0

0%

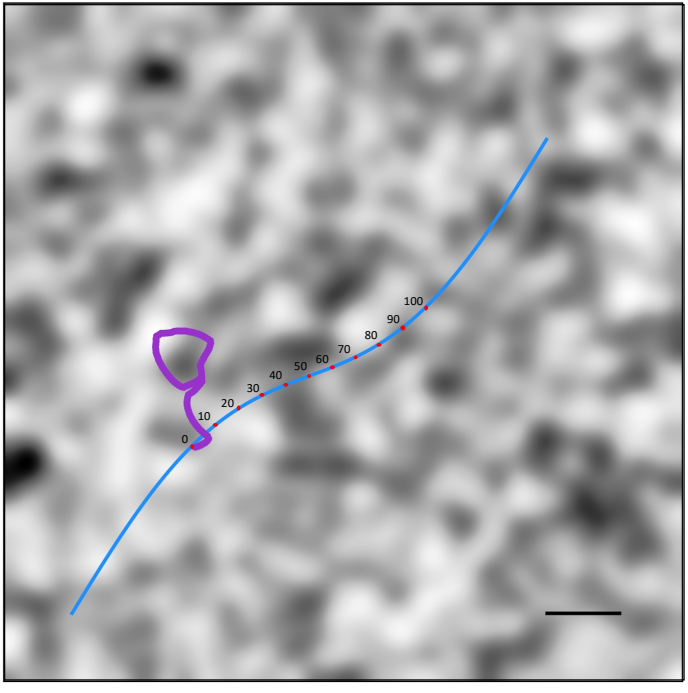


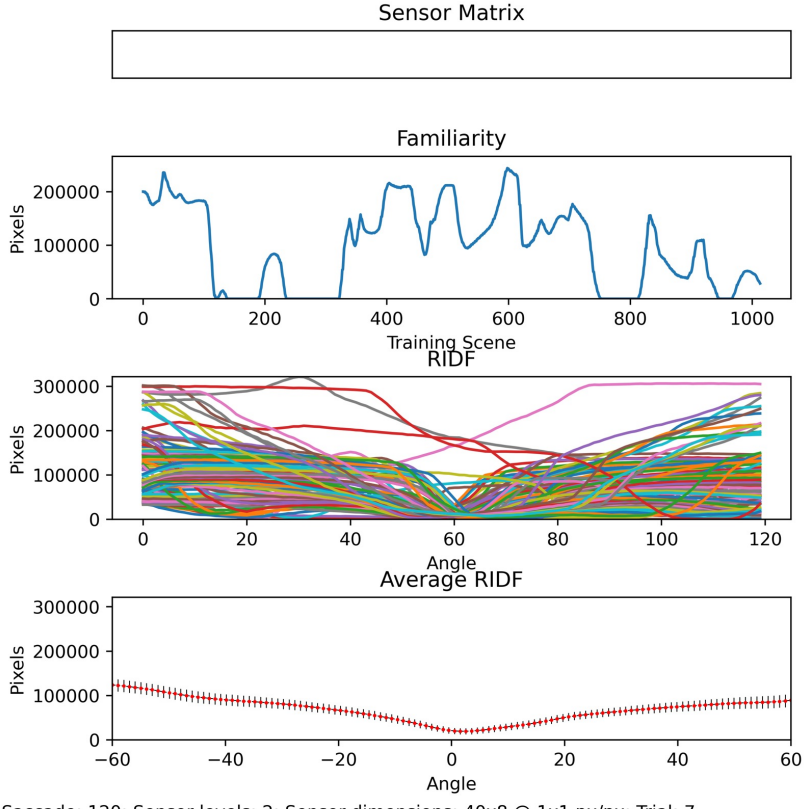


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 6271.07; RMSD/dist: 15.678; TD: 55274; p90: 34; p50: 20; complete: 0

0%

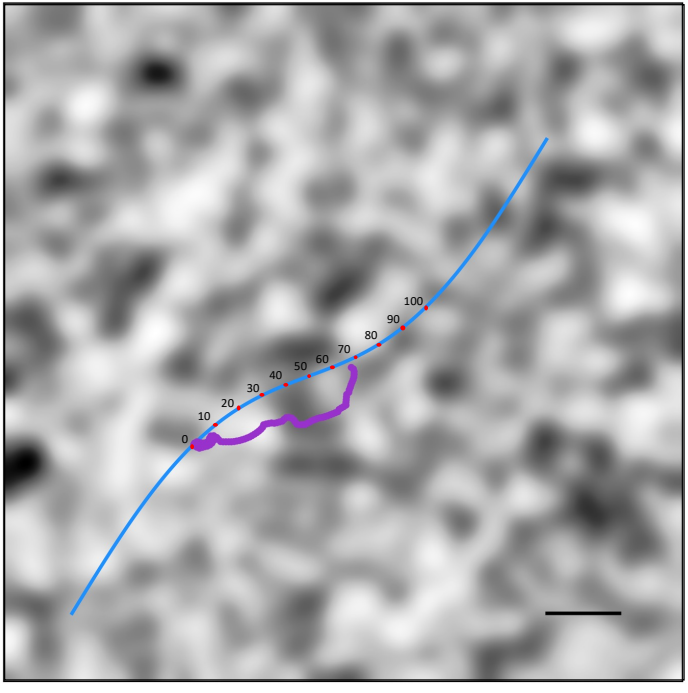


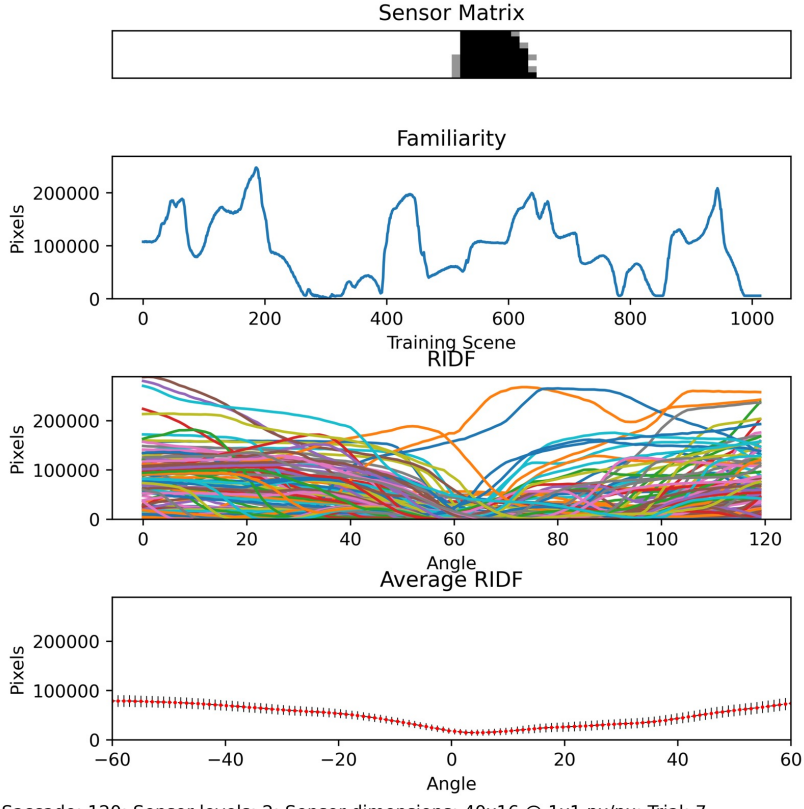


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 8499.49; RMSD/dist: 21.249; TD: 73826; p90: 70; p50: 30; complete: 0

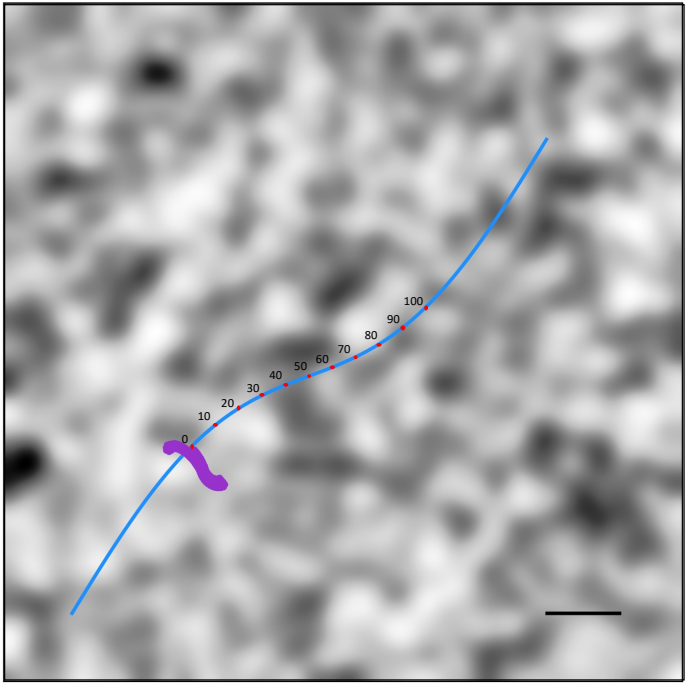
0%

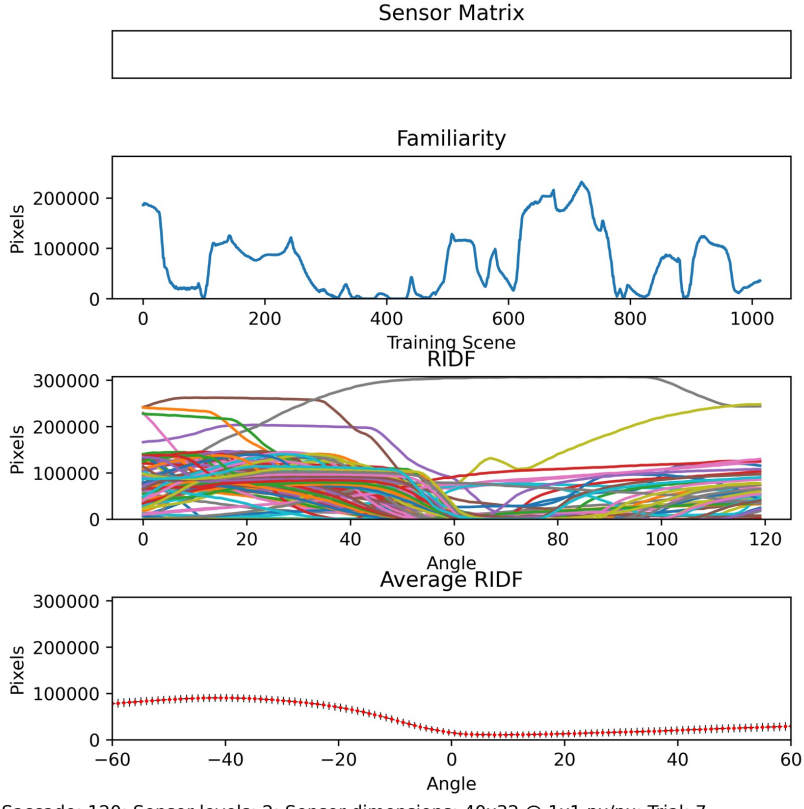




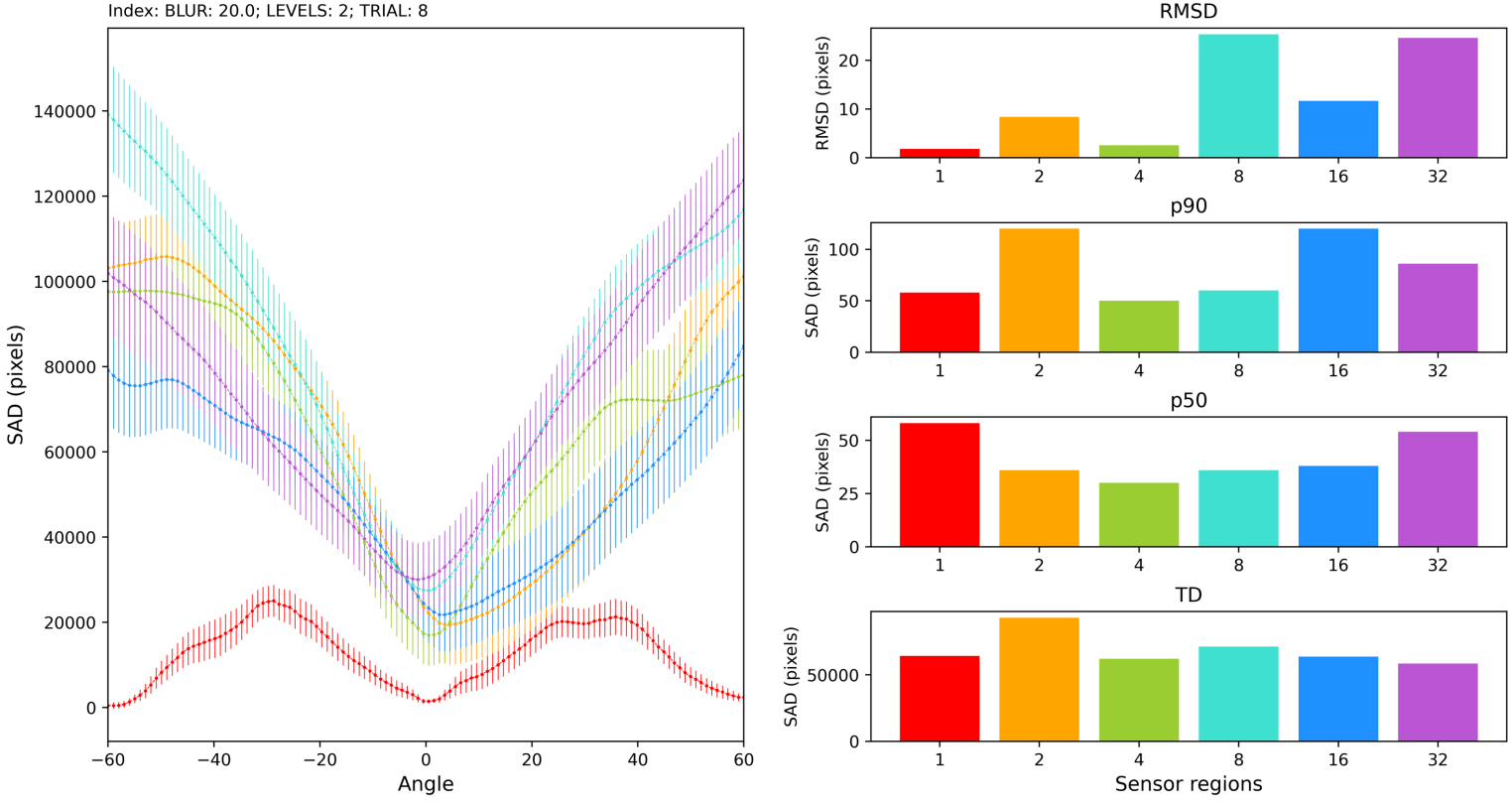
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 3469.92; RMSD/dist: 8.675; TD: 71700; p90: 116; p50: 36; complete: 0

0%

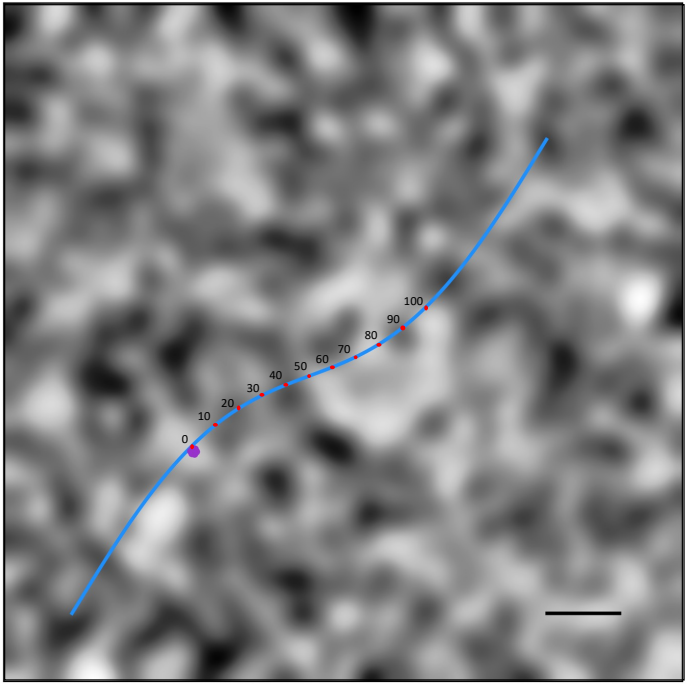


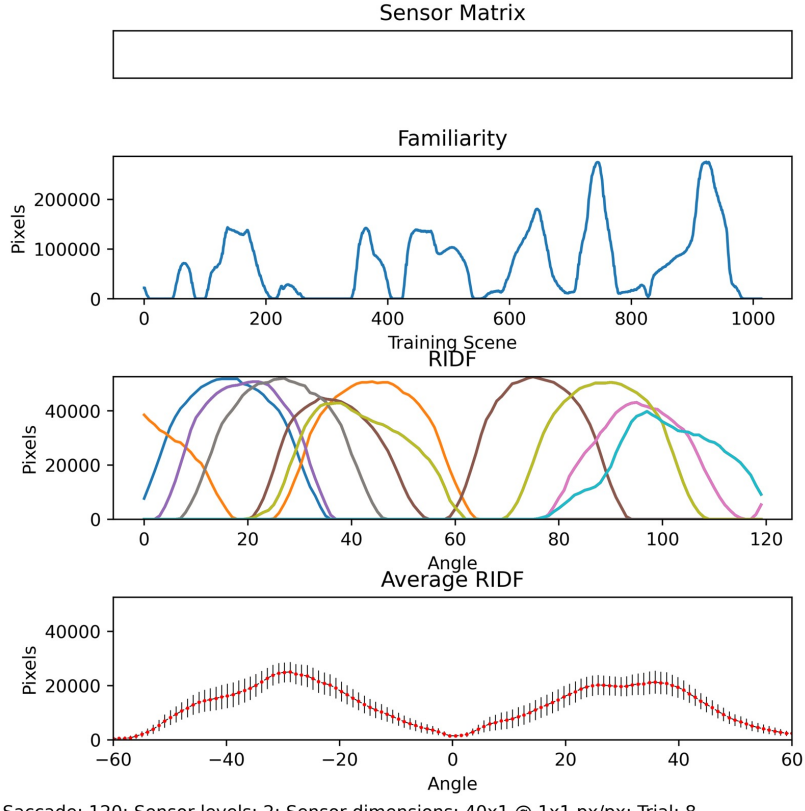


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 3374.46; RMSD/dist: 8.436; TD: 78491; p90: 112; p50: 26; complete: 0


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

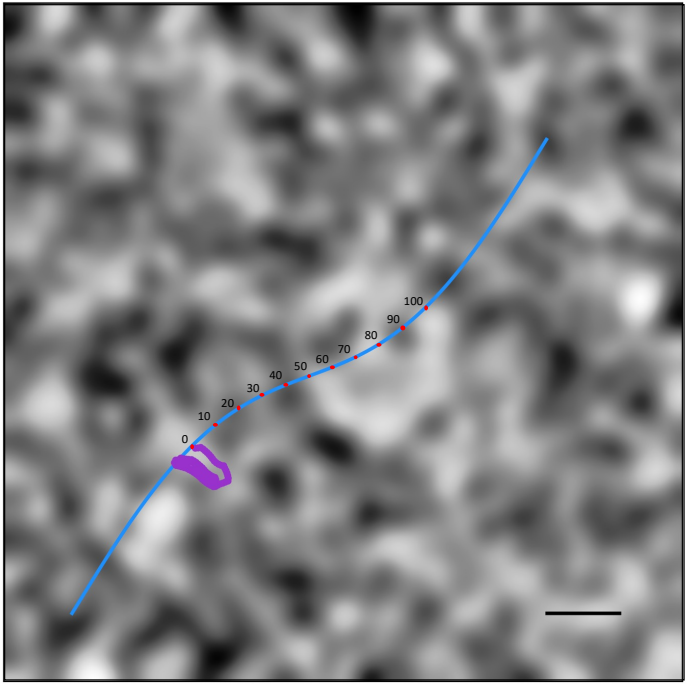
0%

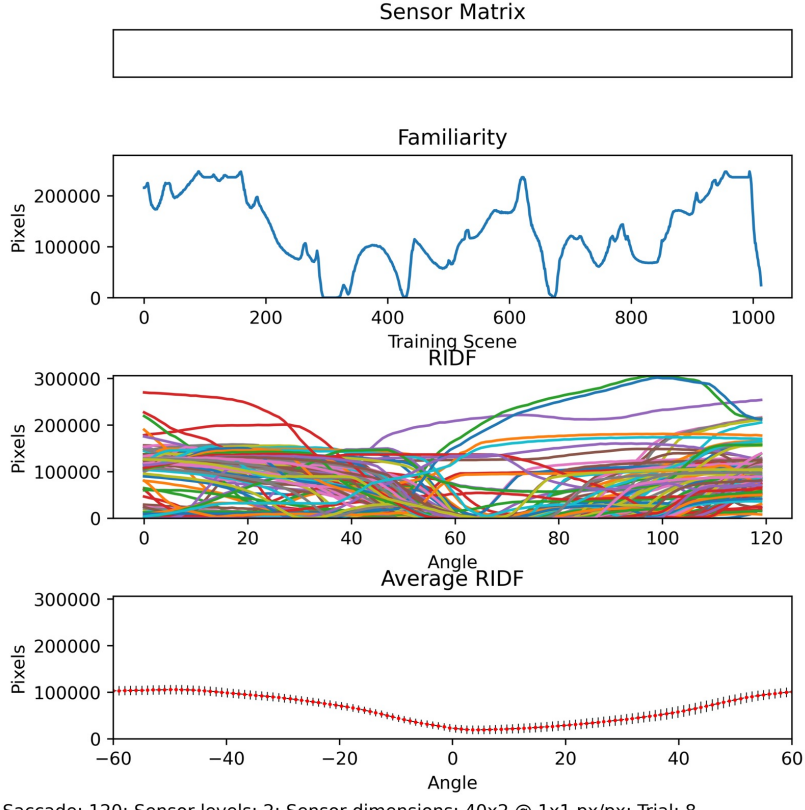




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 725.90; RMSD/dist: 1.815; TD: 64226; p90: 58; p50: 58; complete: 0

0%

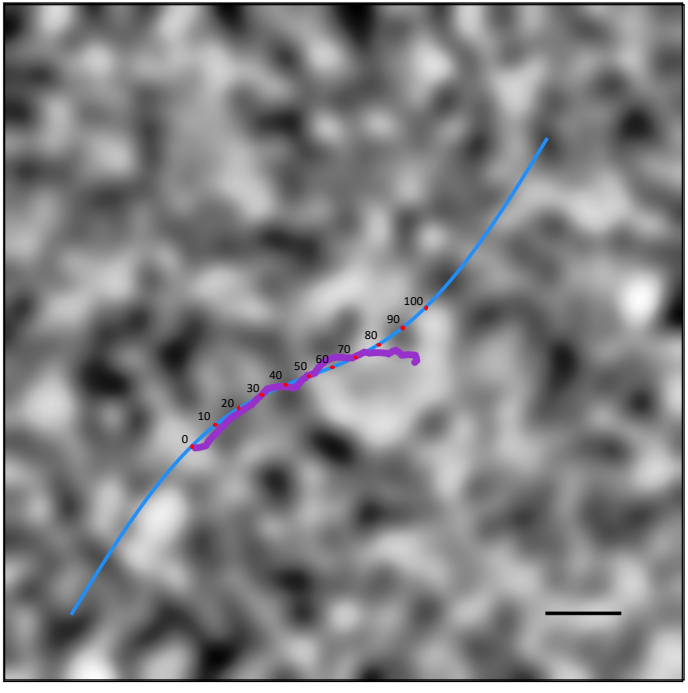


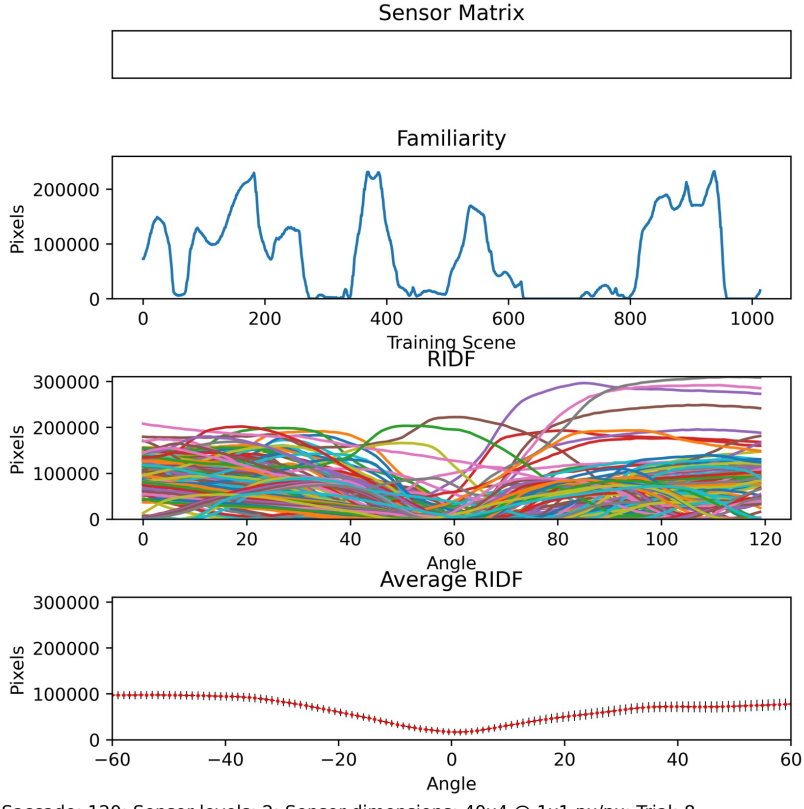


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3358.54; RMSD/dist: 8.396; TD: 92897; p90: 120; p50: 36; complete: 0

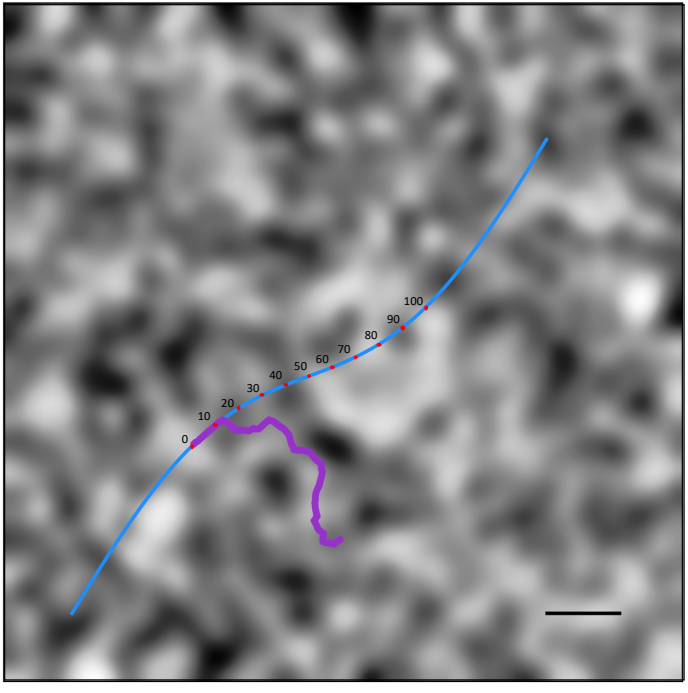
0%

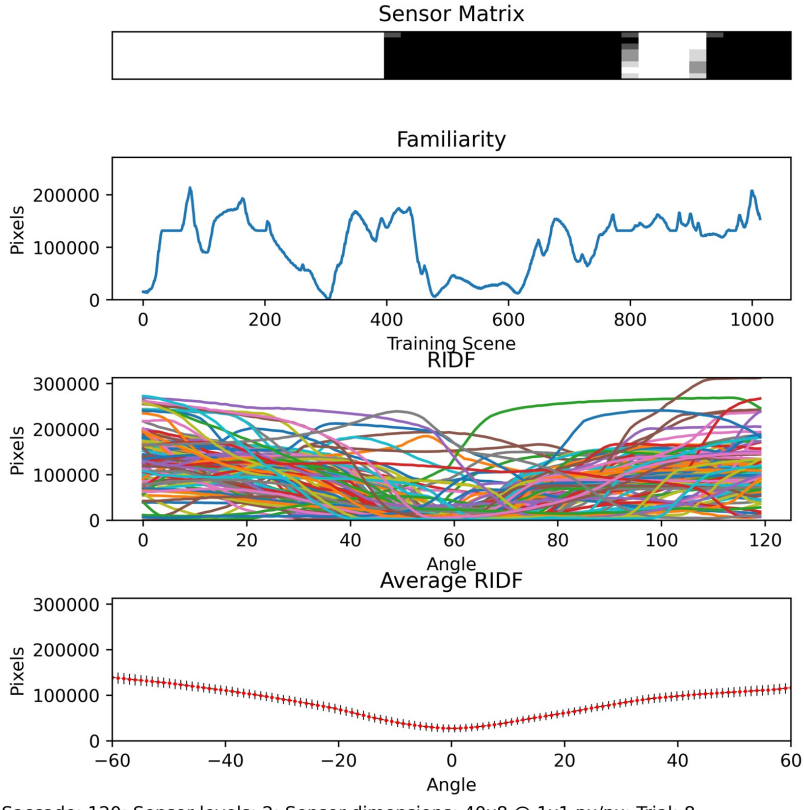




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 1020.31; RMSD/dist: 2.551; TD: 62125; p90: 50; p50: 30; complete: 0

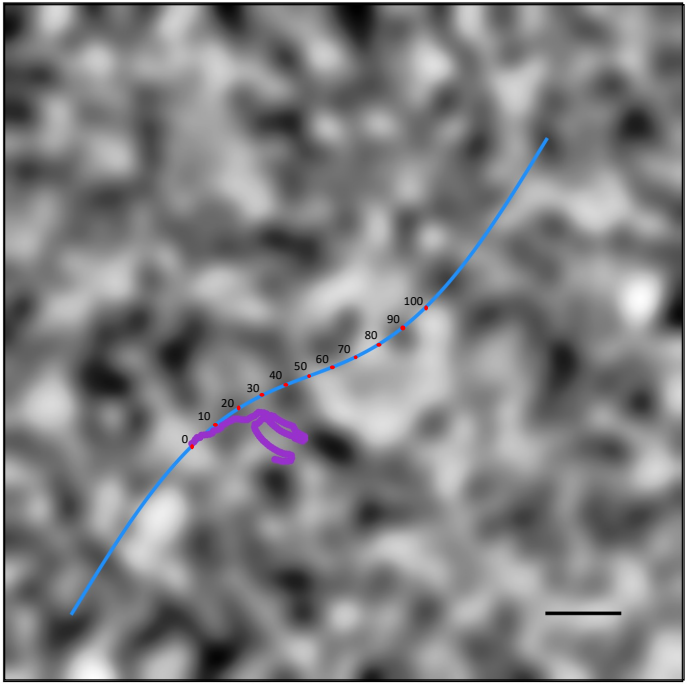
10%

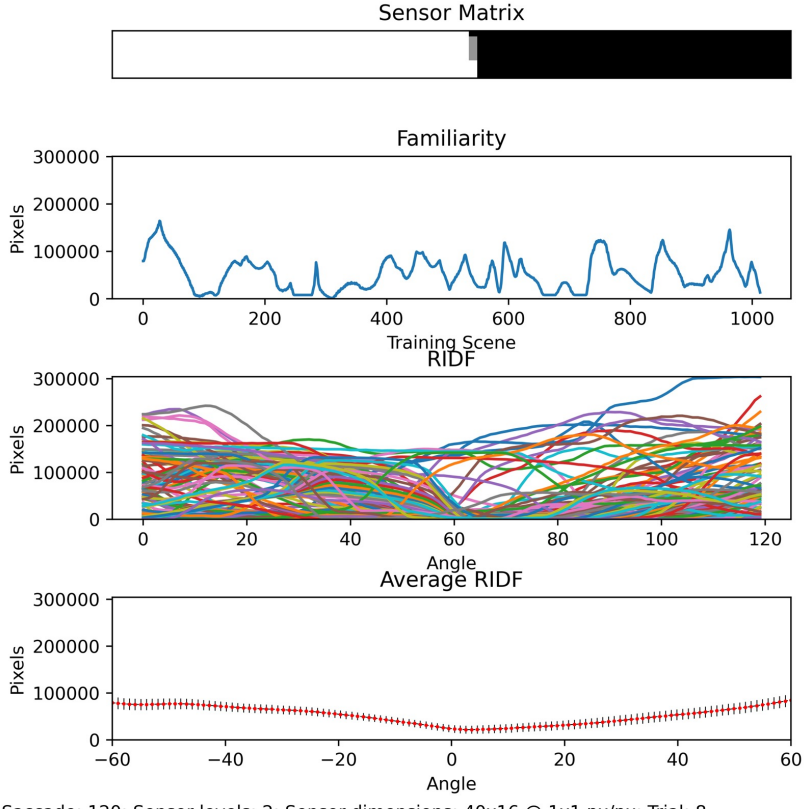




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 10144.12; RMSD/dist: 25.360; TD: 71265; p90: 60; p50: 36; complete: 0

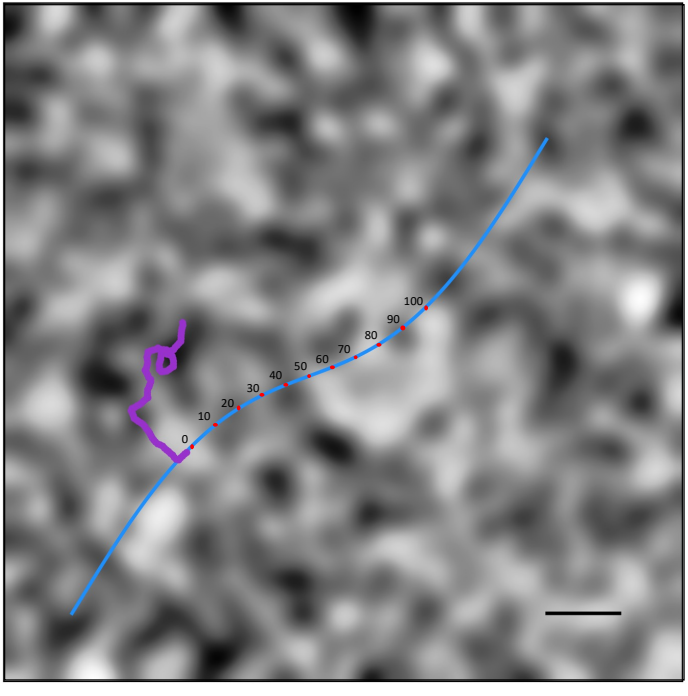
0%

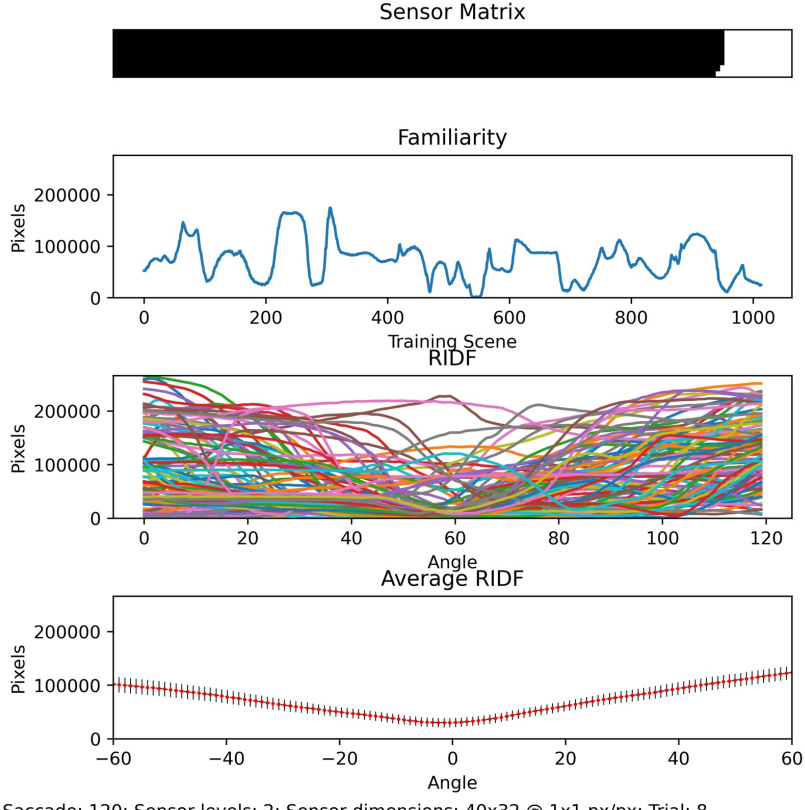




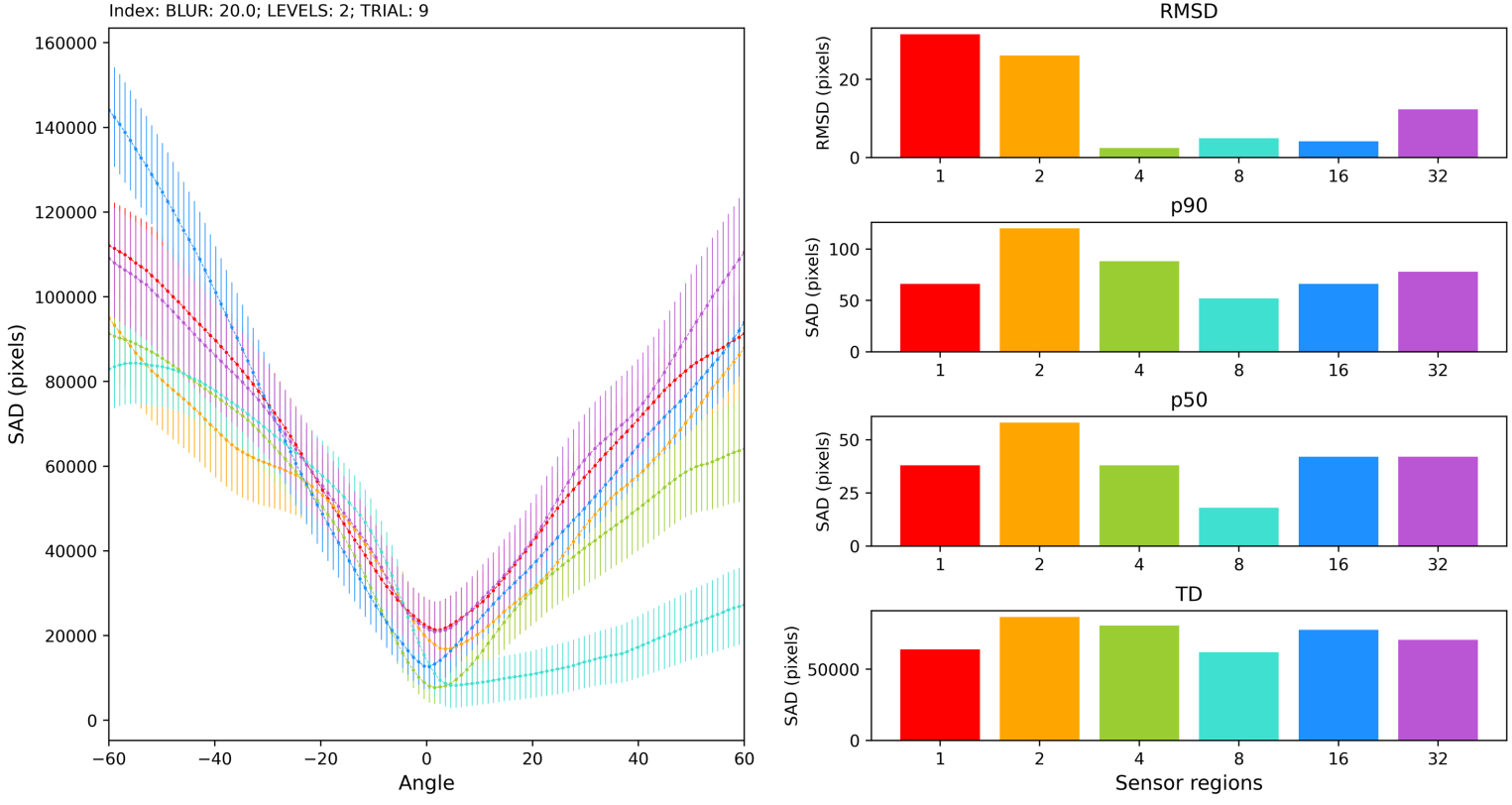
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 4673.42; RMSD/dist: 11.684; TD: 63648; p90: 120; p50: 38; complete: 0

0%

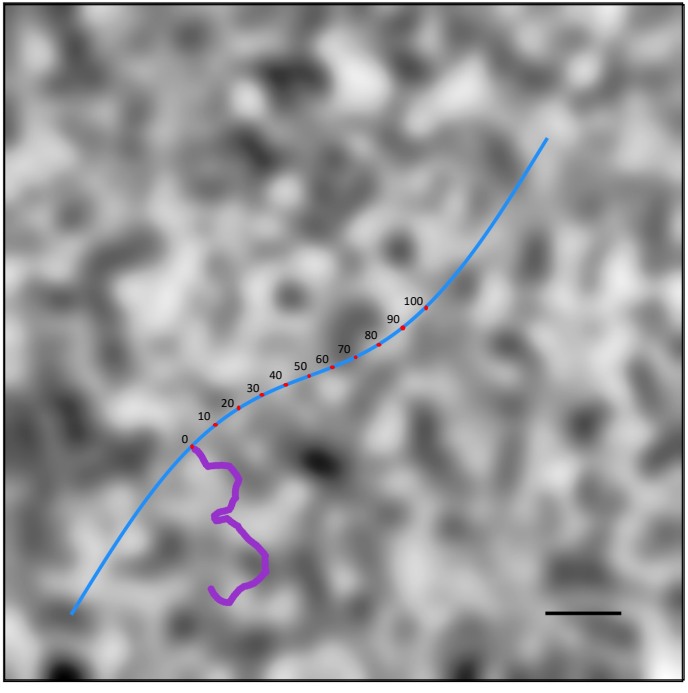


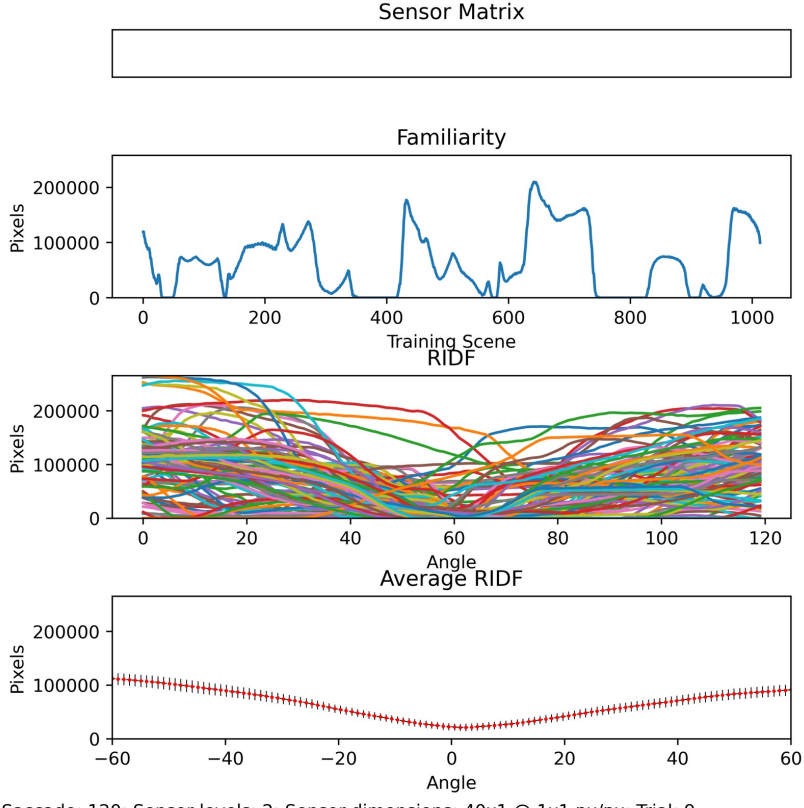


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 9846.83; RMSD/dist: 24.617; TD: 58513; p90: 86; p50: 54; complete: 0


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

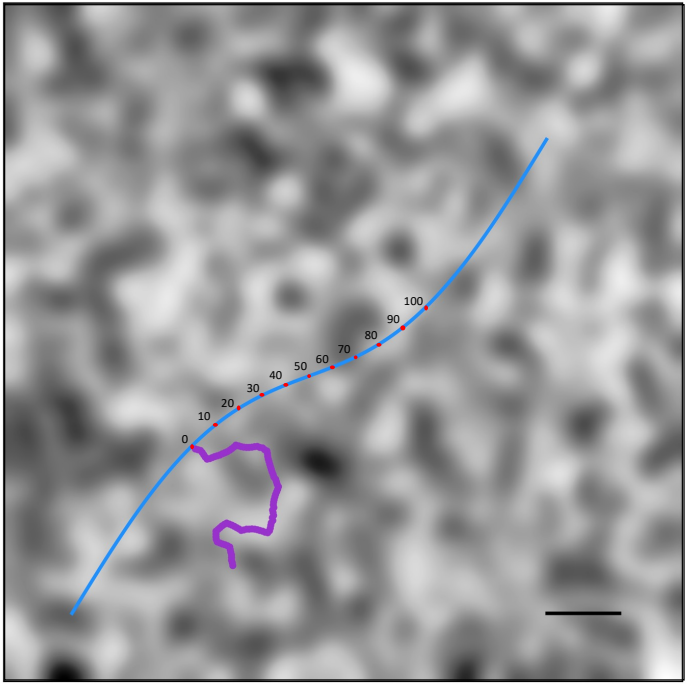
0%

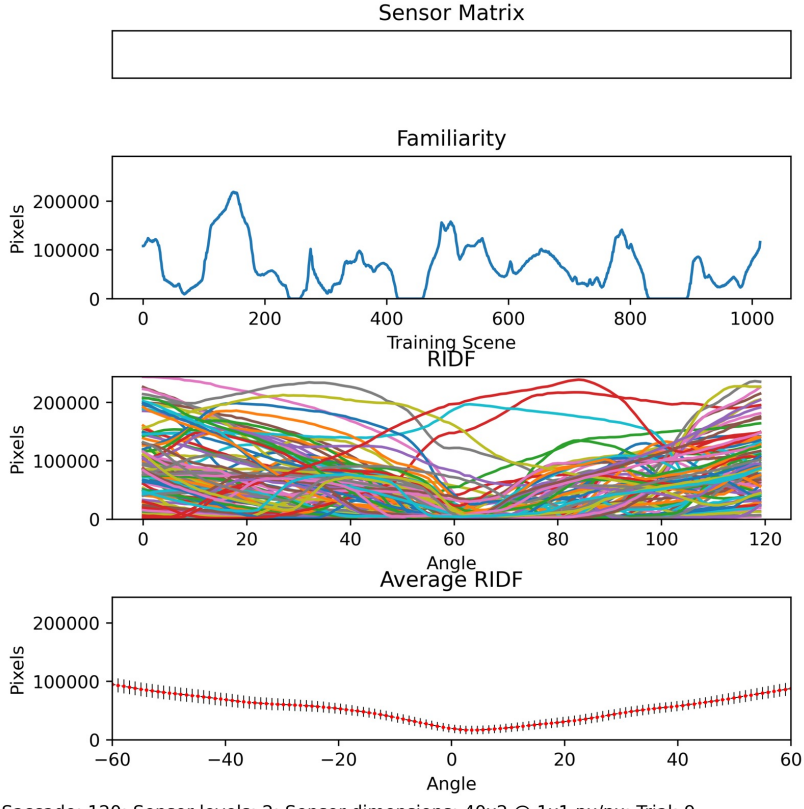




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 12636.23; RMSD/dist: 31.591; TD: 63998; p90: 66; p50: 38; complete: 0

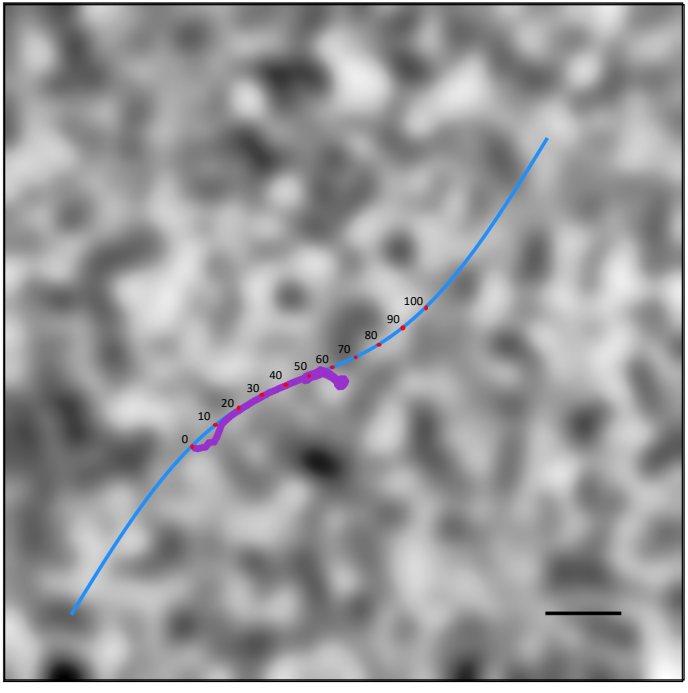
0%

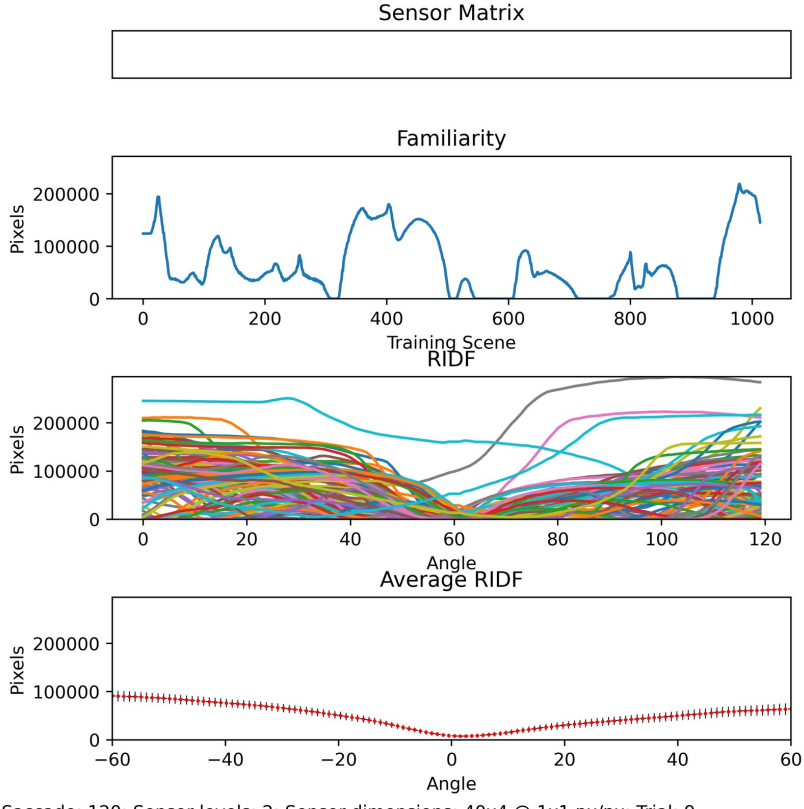




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 10459.86; RMSD/dist: 26.150; TD: 86703; p90: 120; p50: 58; complete: 0

30%

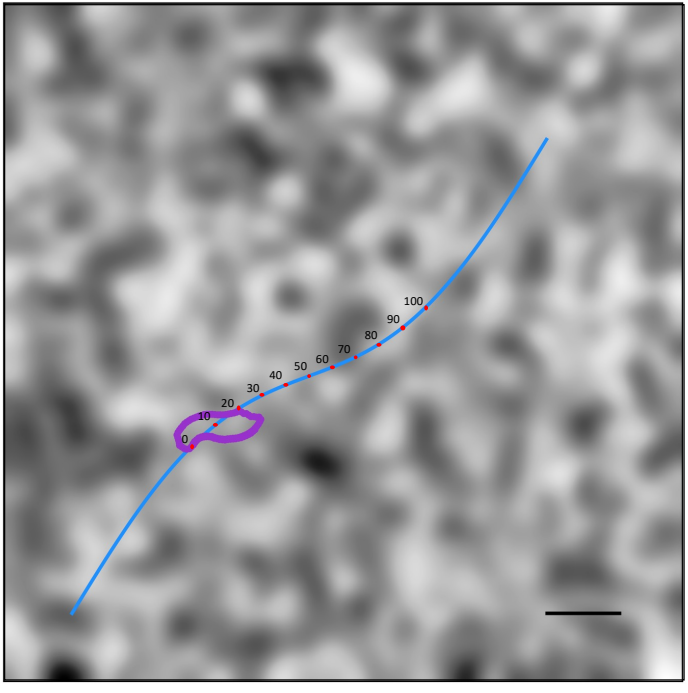


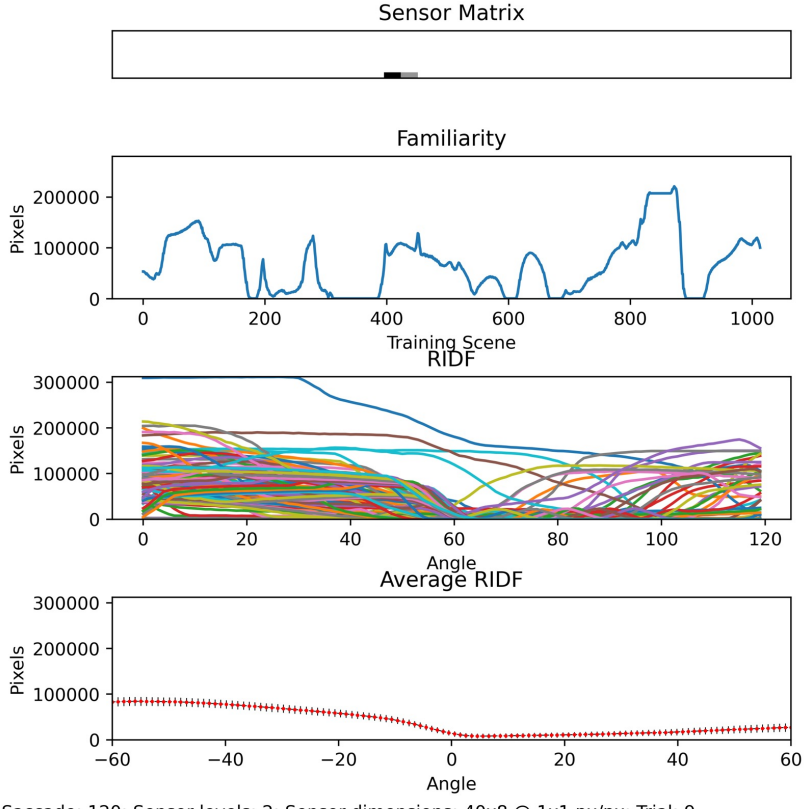


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 982.12; RMSD/dist: 2.455; TD: 80769; p90: 88; p50: 38; complete: 0

0%

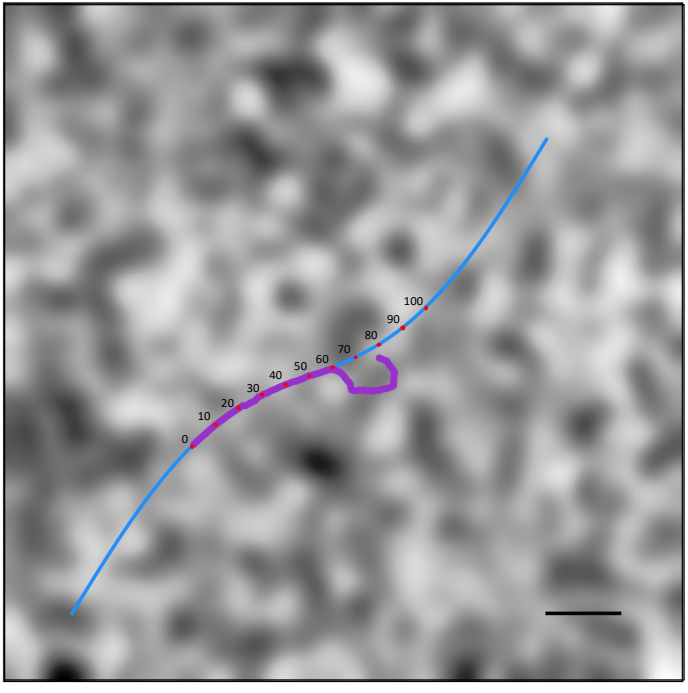


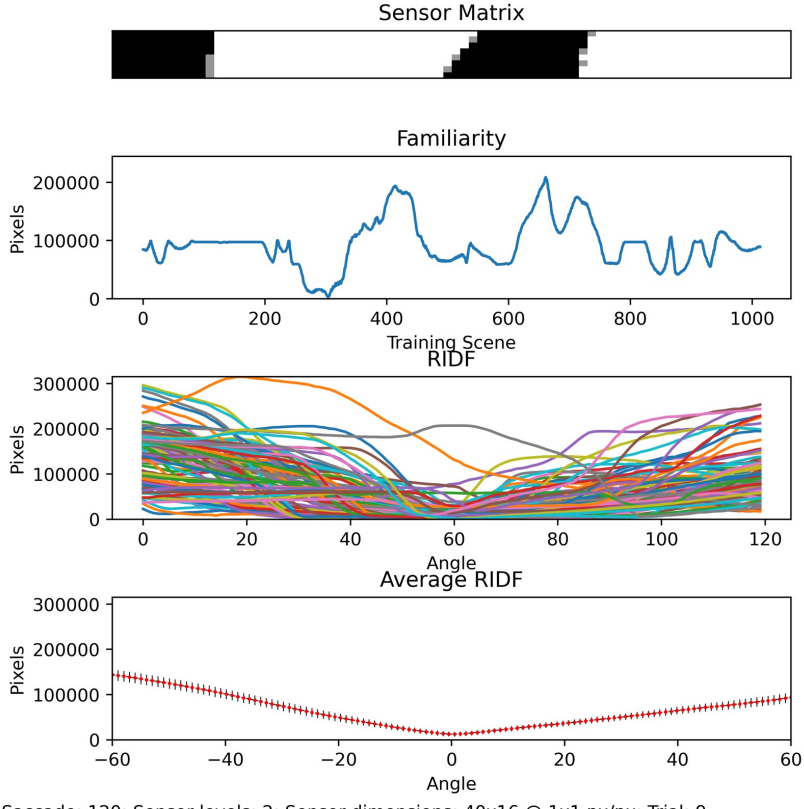


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1969.01; RMSD/dist: 4.923; TD: 61991; p90: 52; p50: 18; complete: 0

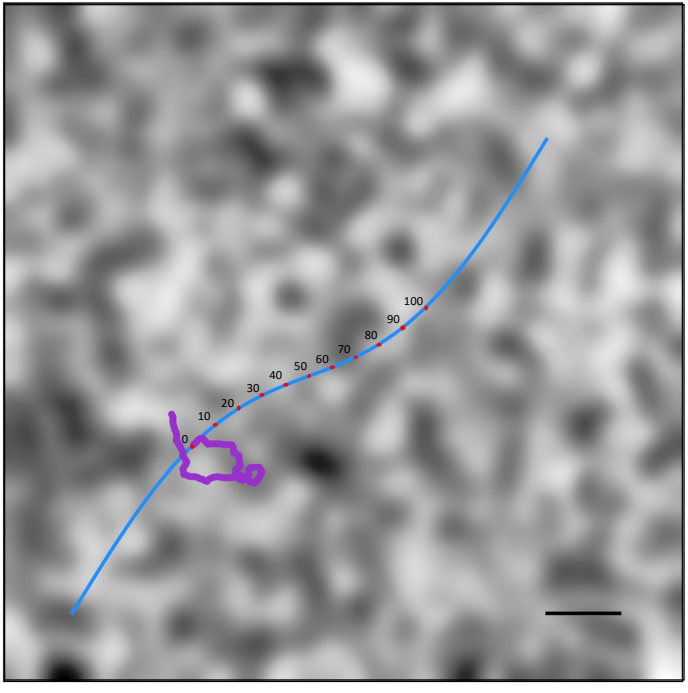
50%

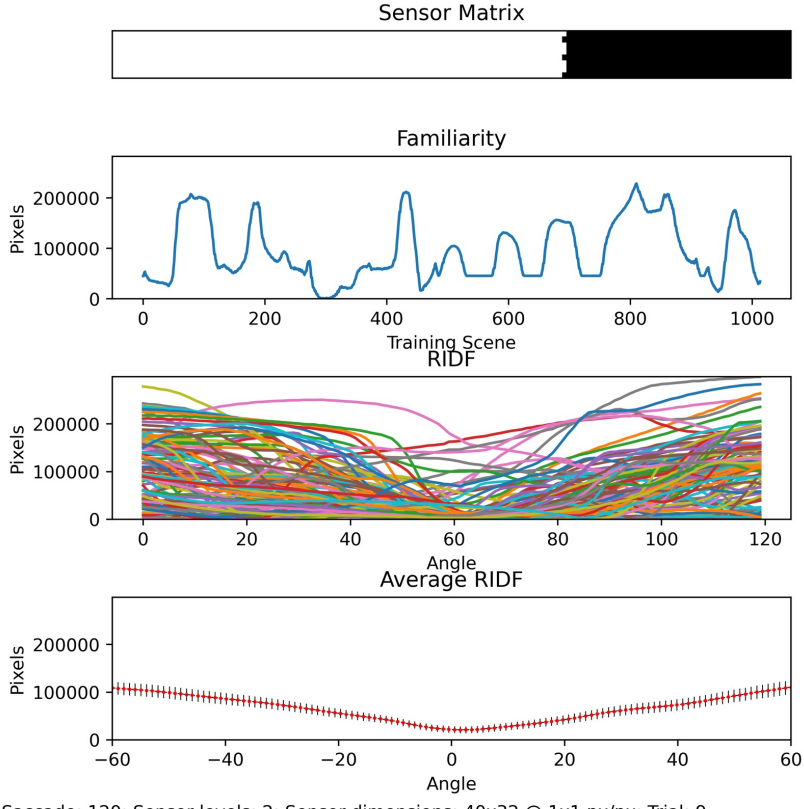




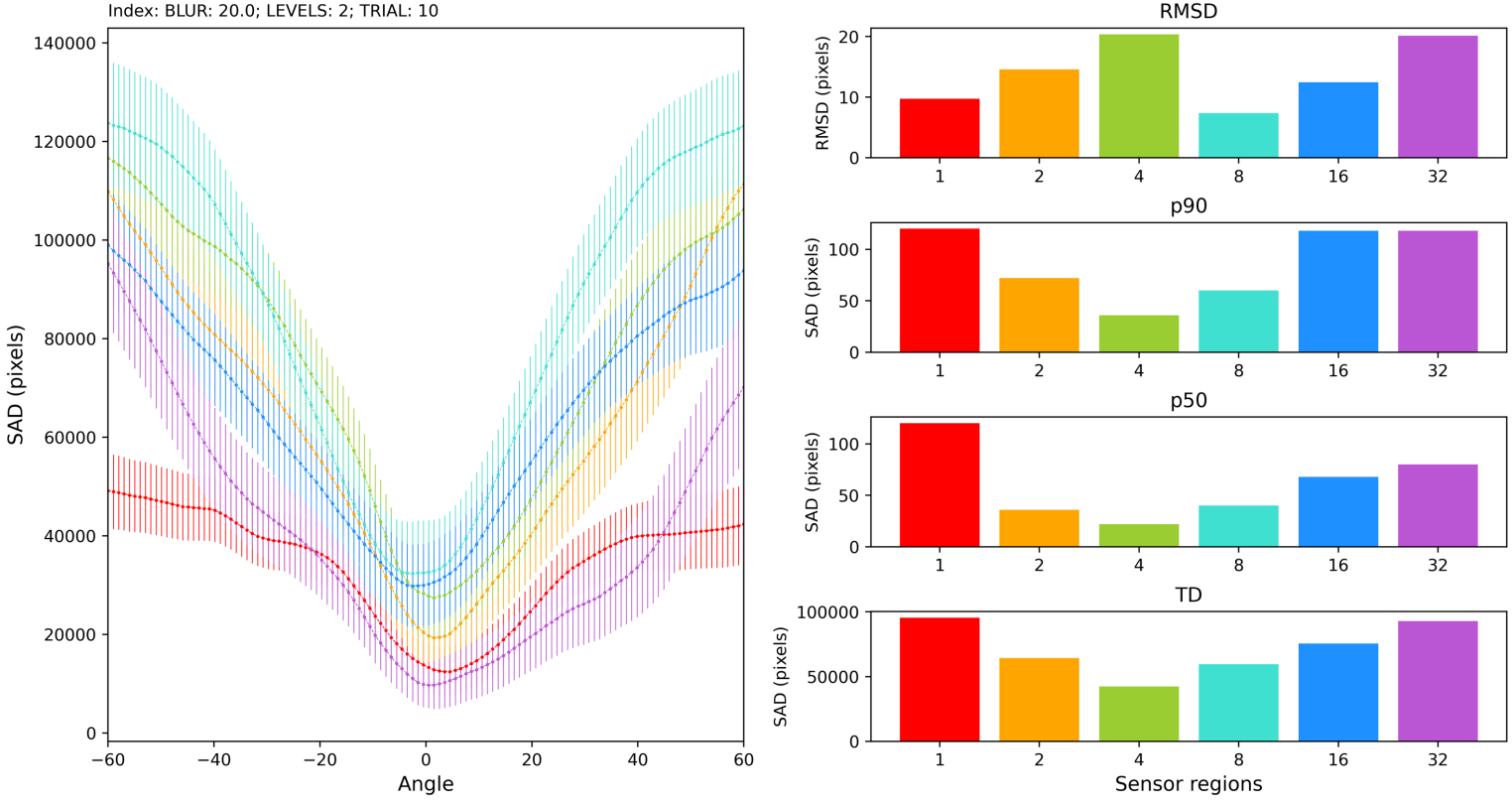
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 1667.08; RMSD/dist: 4.168; TD: 77710; p90: 66; p50: 42; complete: 0

0%

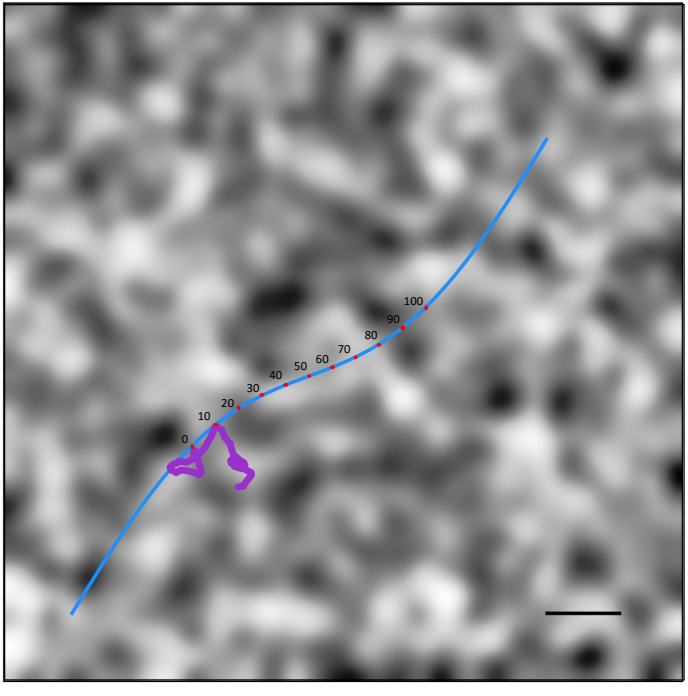


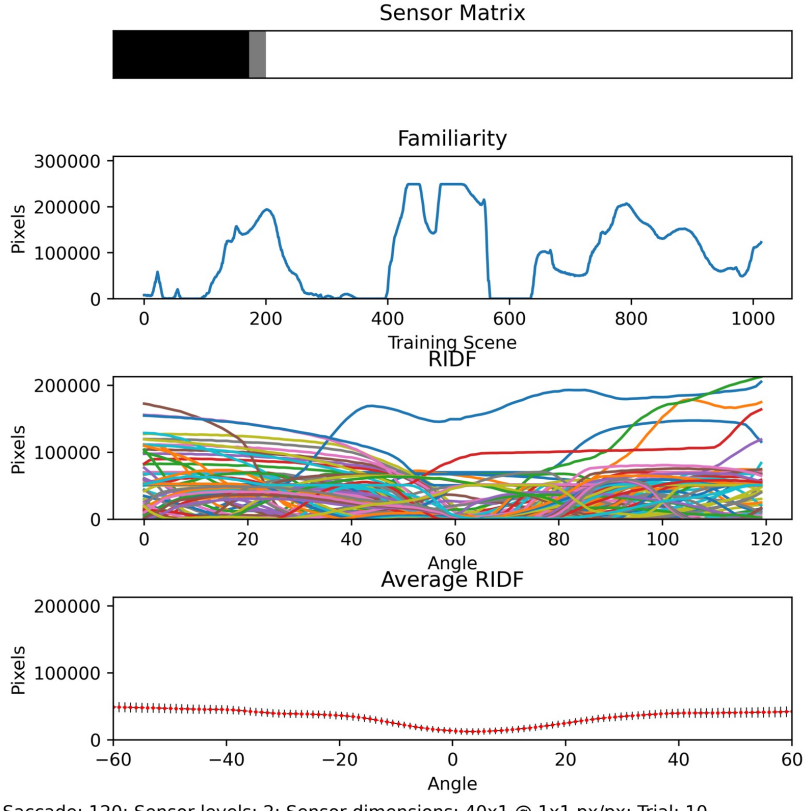


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 4929.63; RMSD/dist: 12.324; TD: 70603; p90: 78; p50: 42; complete: 0


Index: BLUR: 20.0; LEVELS: 2; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

0%

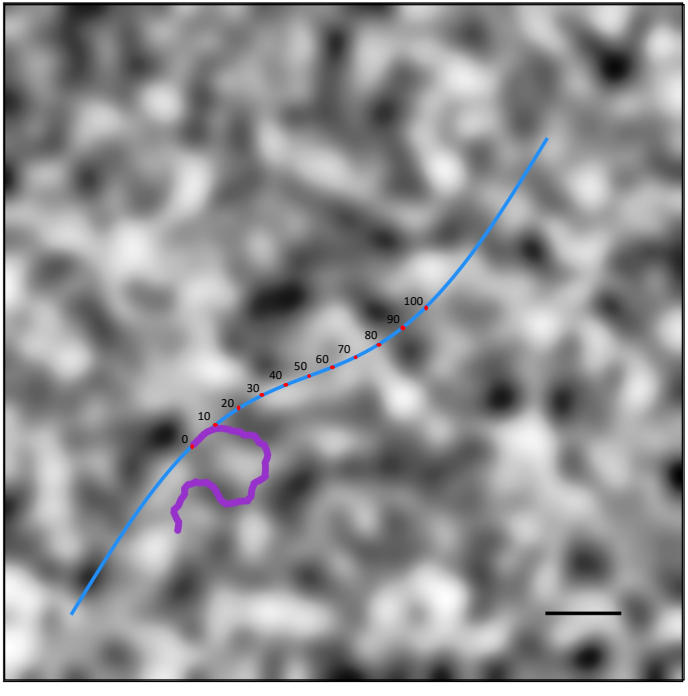


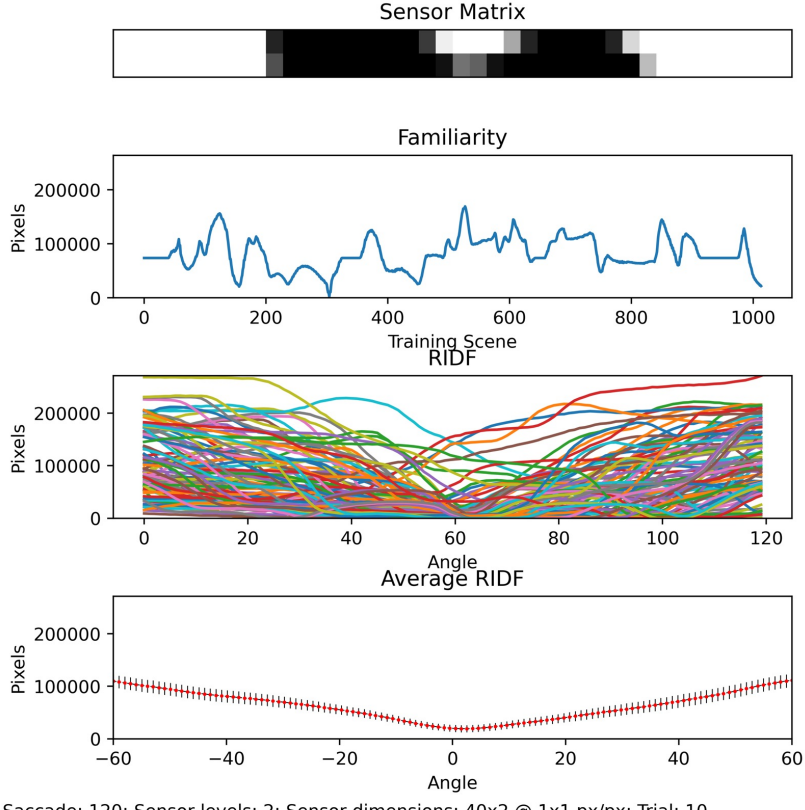


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3899.74; RMSD/dist: 9.749; TD: 95422; p90: 120; p50: 120; complete: 0

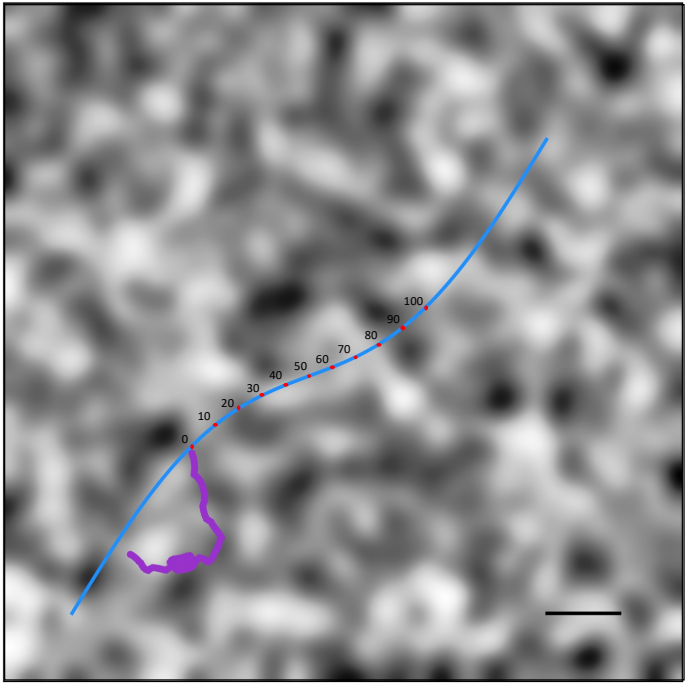
0%

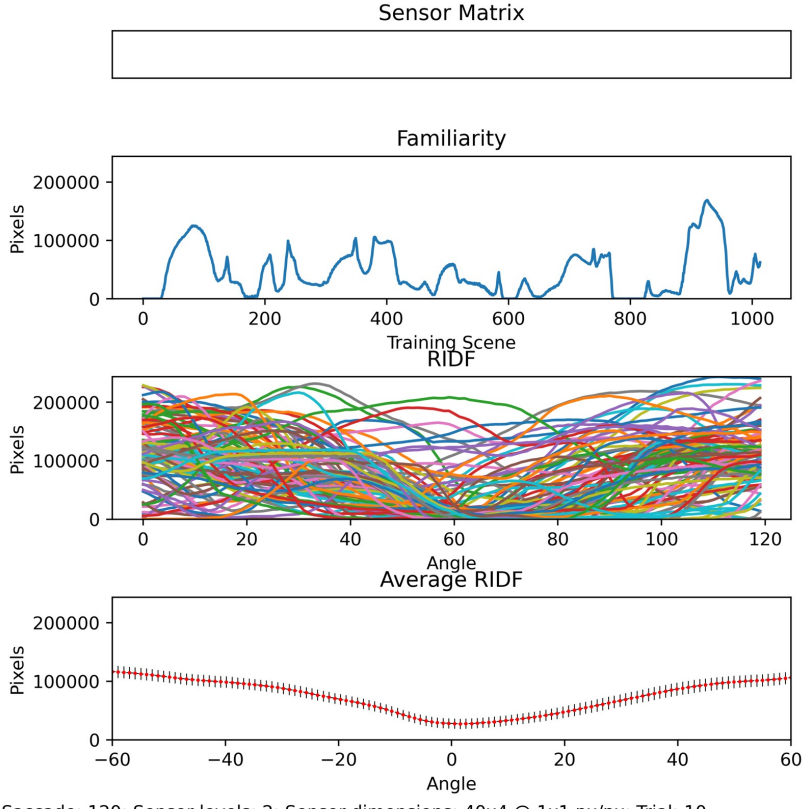




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 5825.86; RMSD/dist: 14.565; TD: 64274; p90: 72; p50: 36; complete: 0

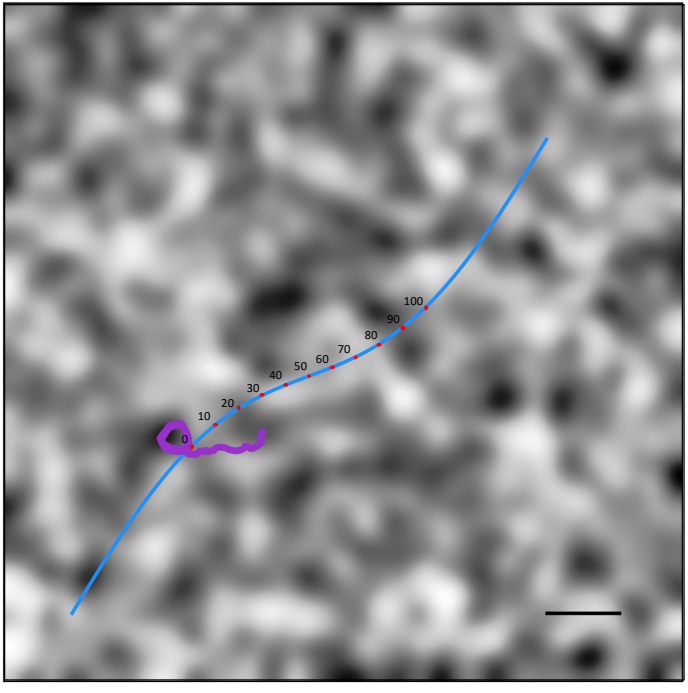
0%

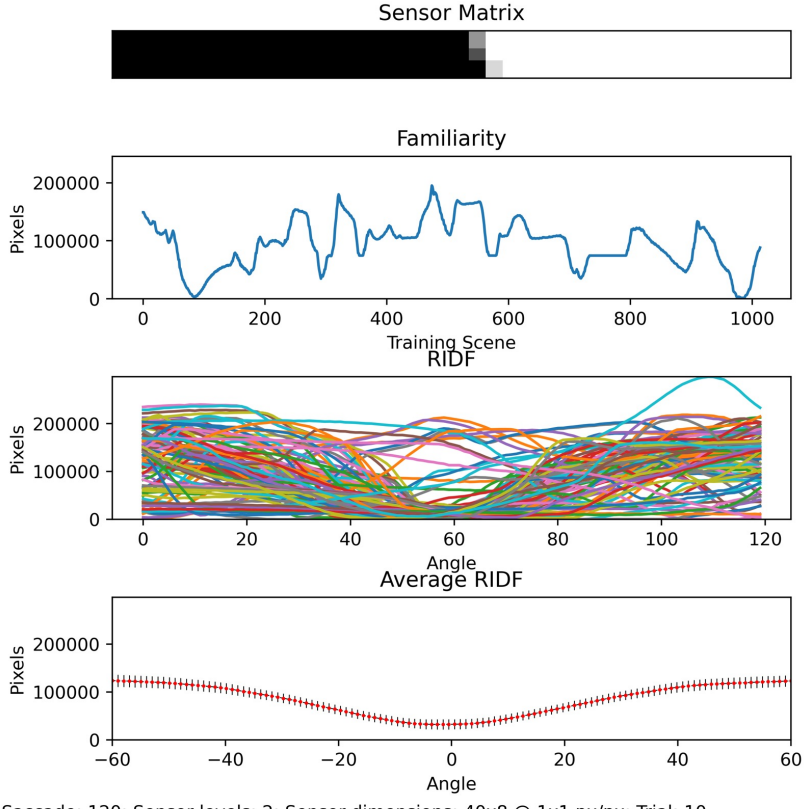




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 8154.84; RMSD/dist: 20.387; TD: 42310; p90: 36; p50: 22; complete: 0

0%

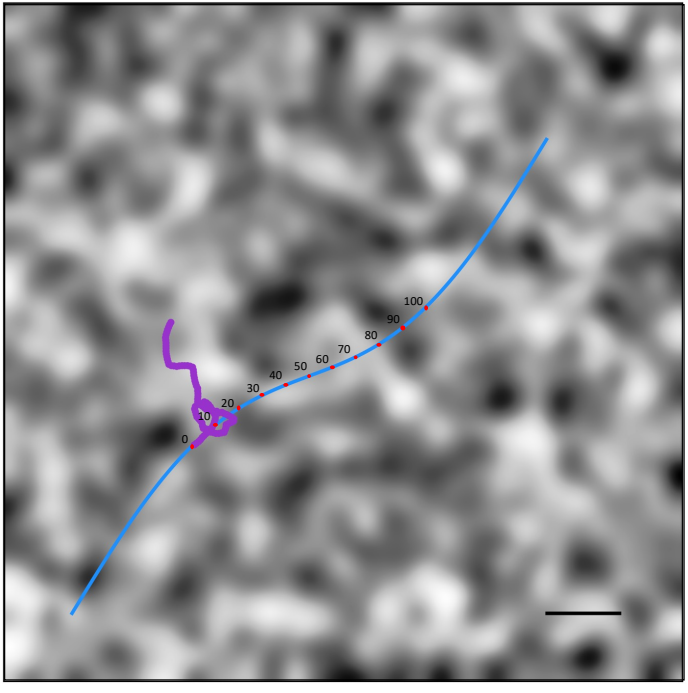


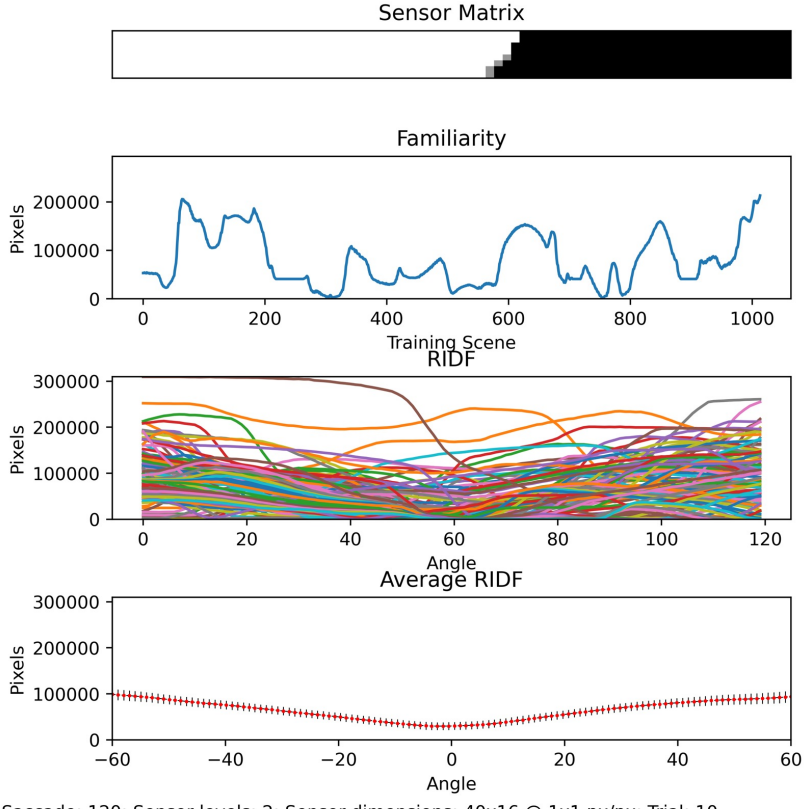


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2945.98; RMSD/dist: 7.365; TD: 59566; p90: 60; p50: 40; complete: 0

10%

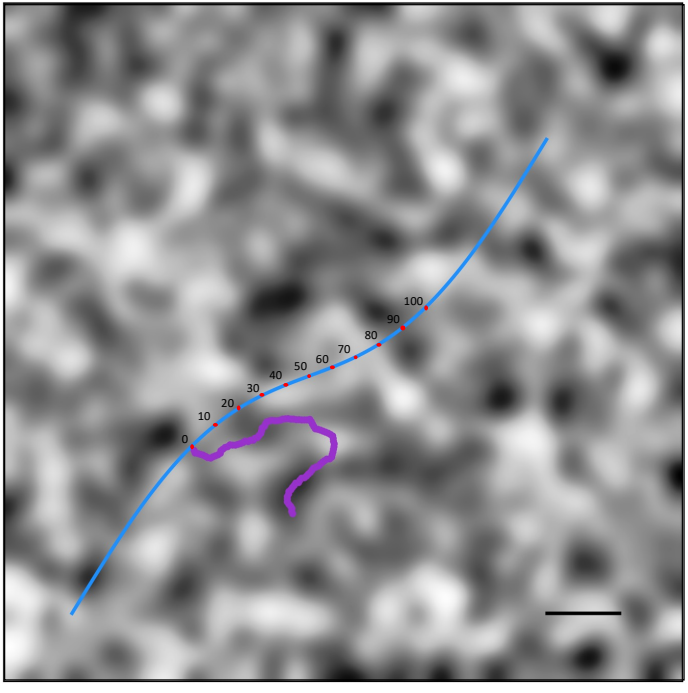


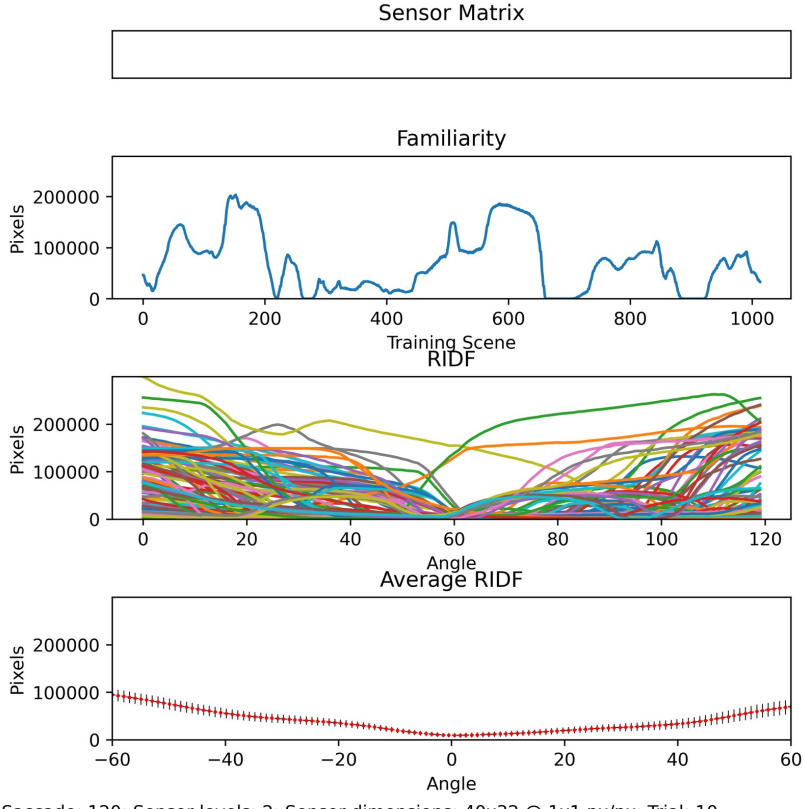


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4977.70; RMSD/dist: 12.444; TD: 75620; p90: 118; p50: 68; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 8054.75; RMSD/dist: 20.137; TD: 92950; p90: 118; p50: 80; complete: 0