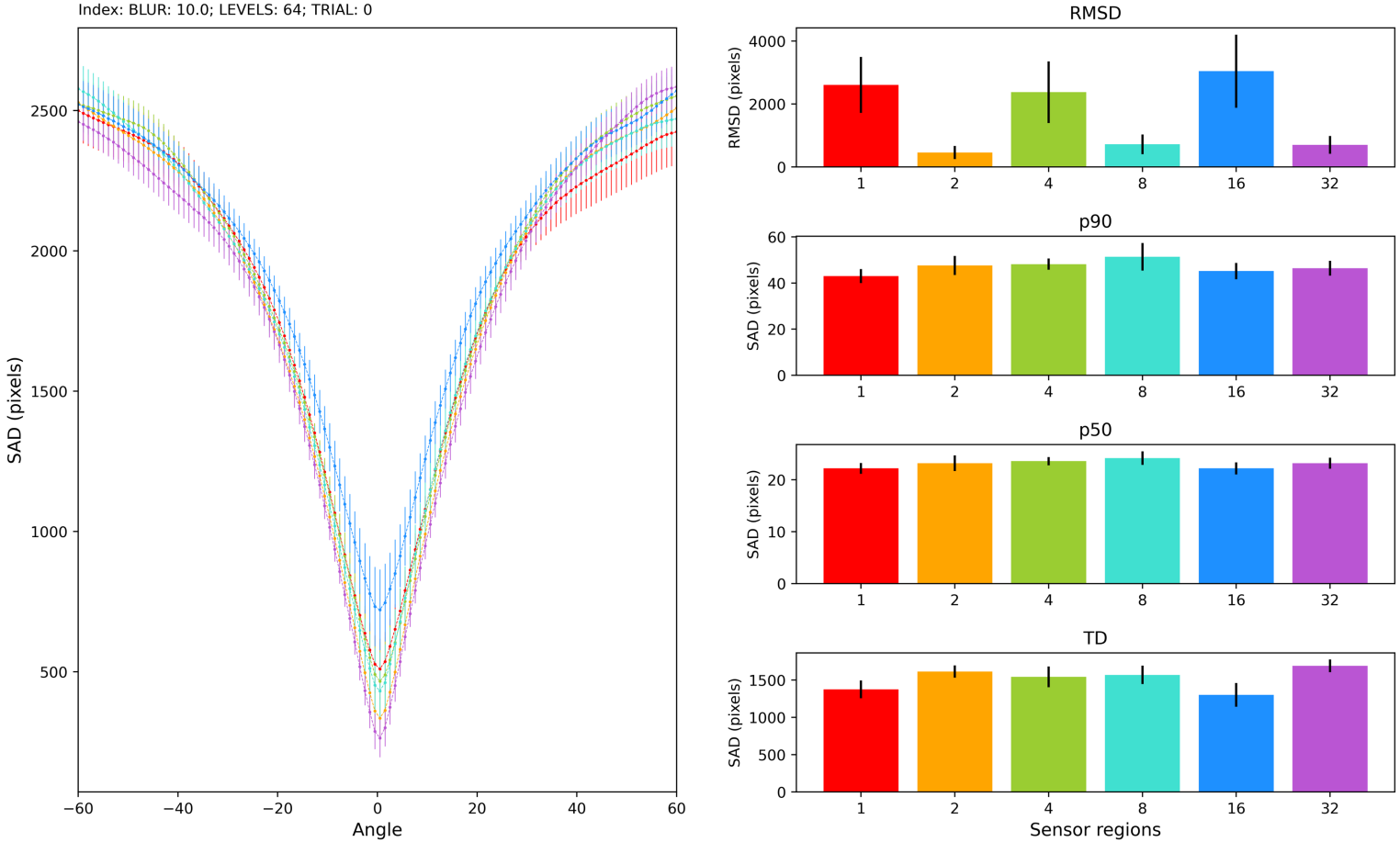
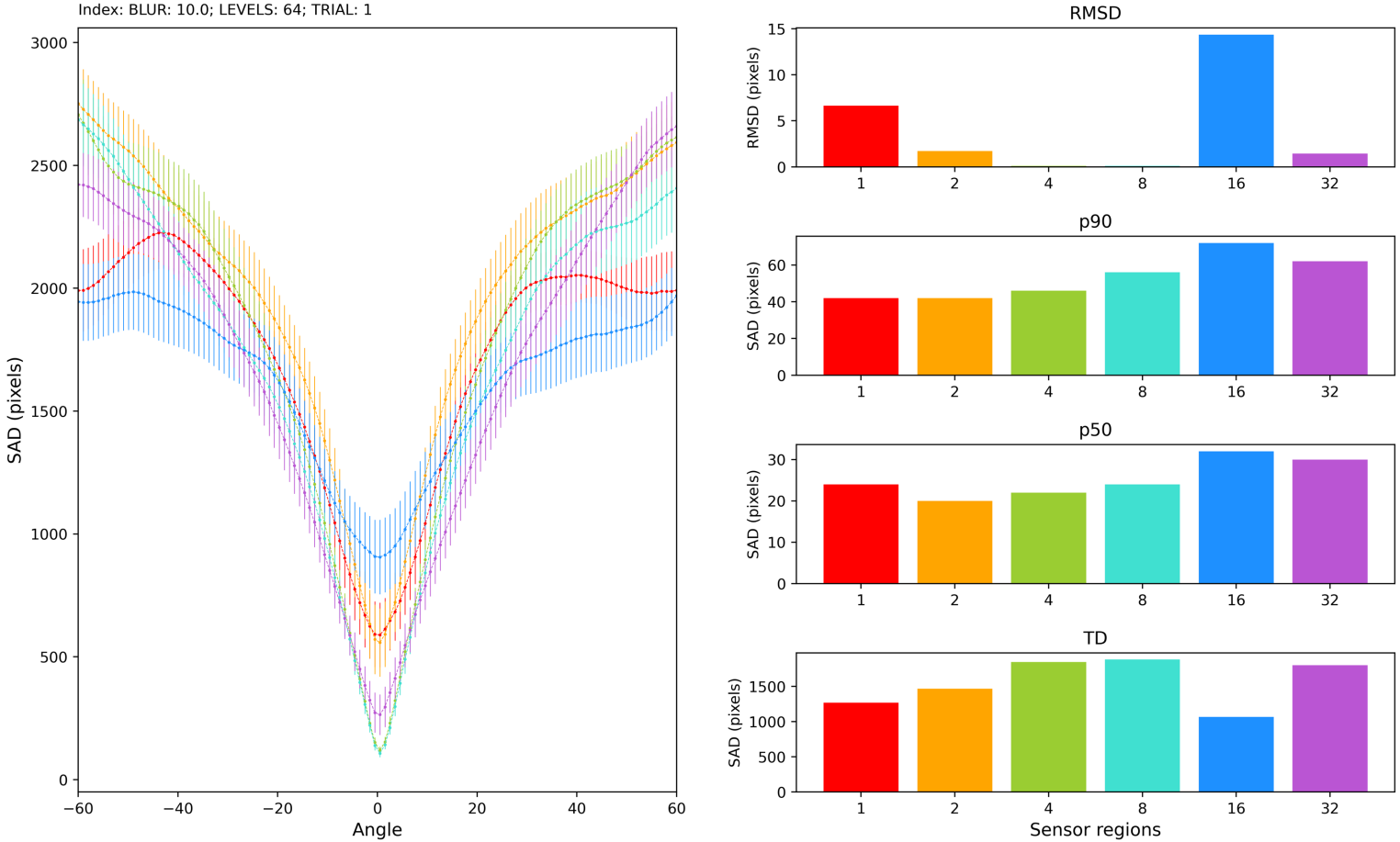

Index: BLUR: 10.0; LEVELS: 64; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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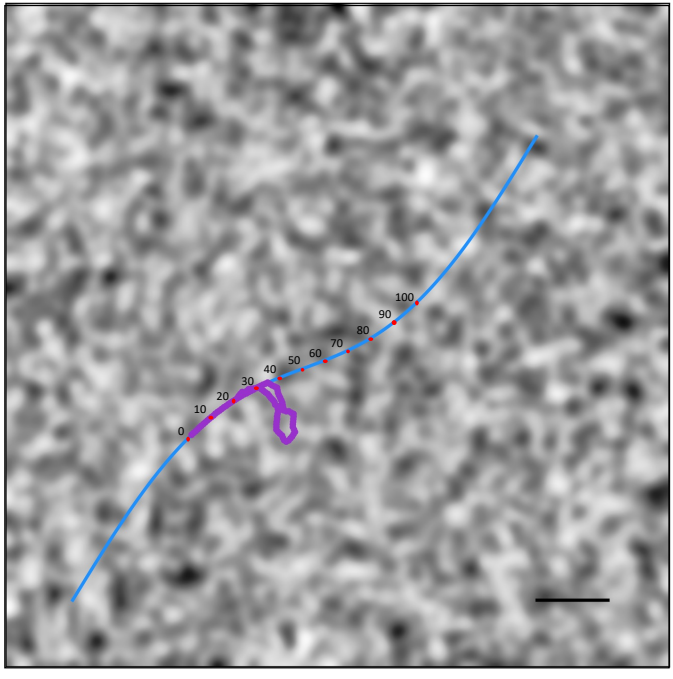
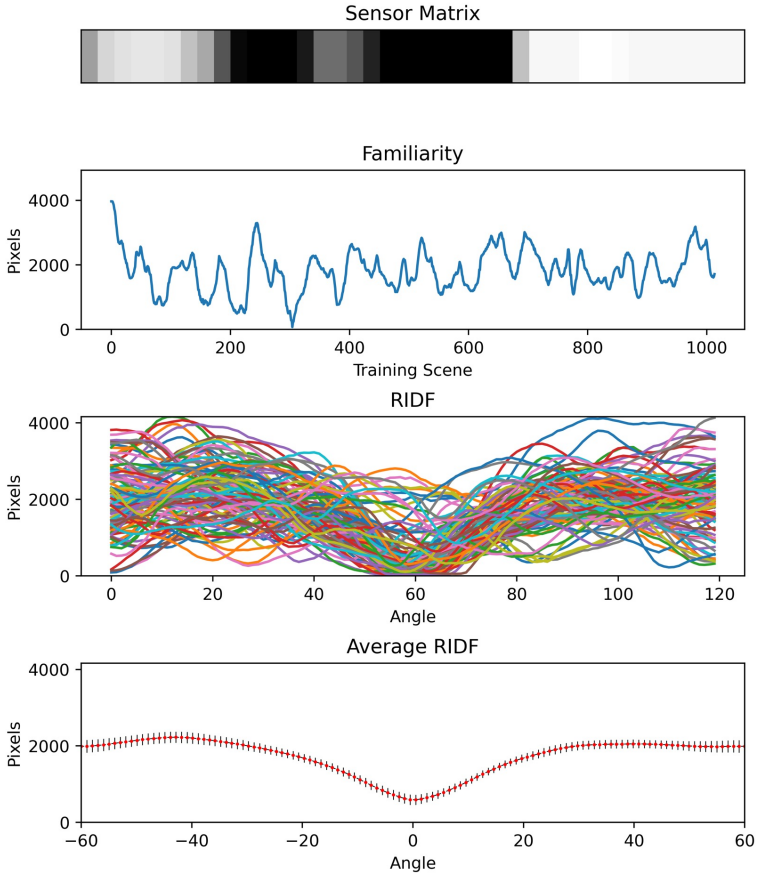
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

30%

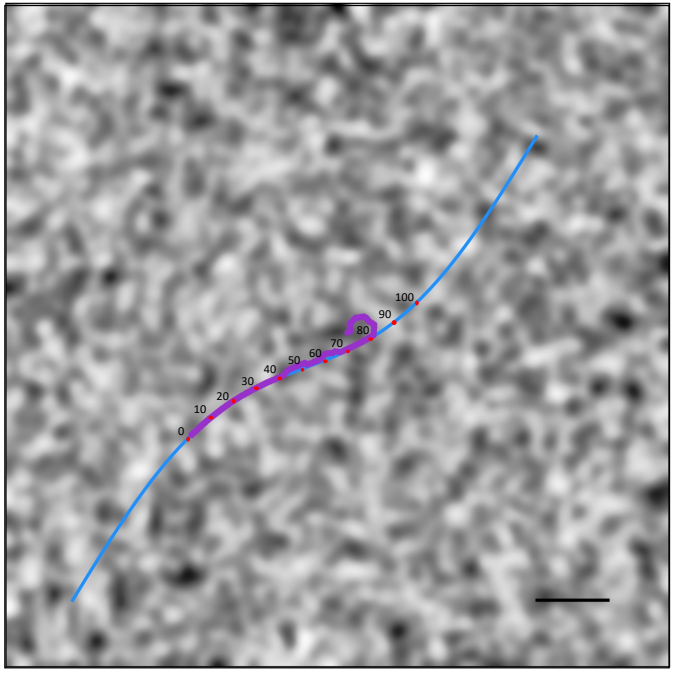


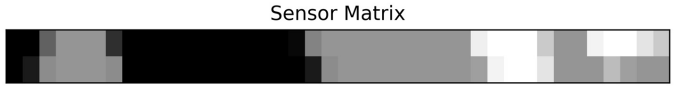


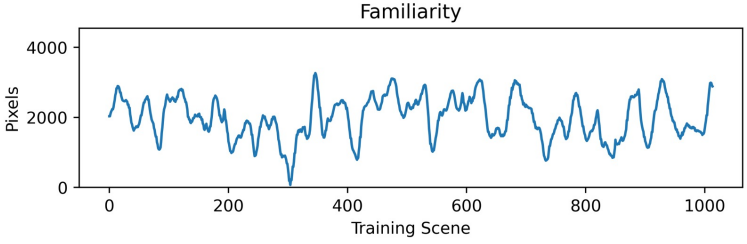
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

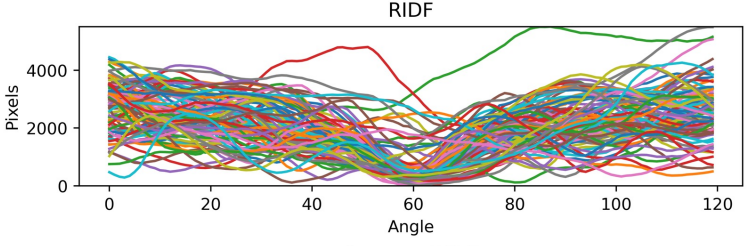
Navigation stats: RMSD error: 2652.79; RMSD/dist: 6.632; TD: 1269; p90: 42; p50: 24; complete: 0

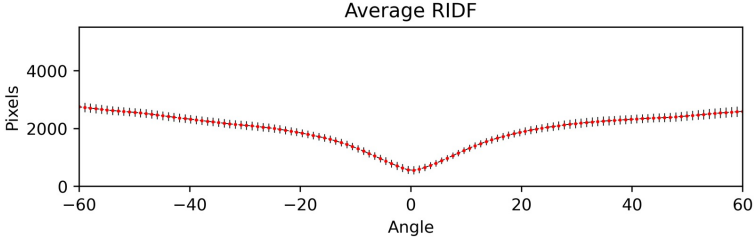
50%







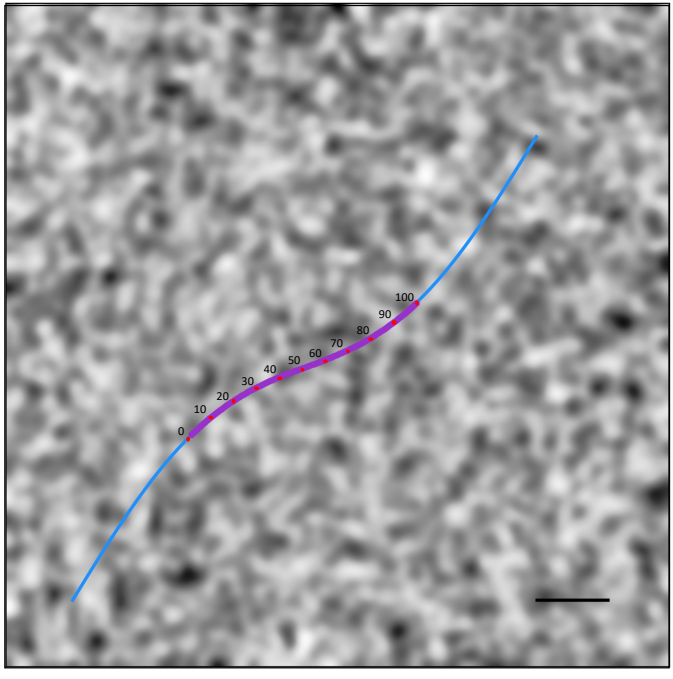


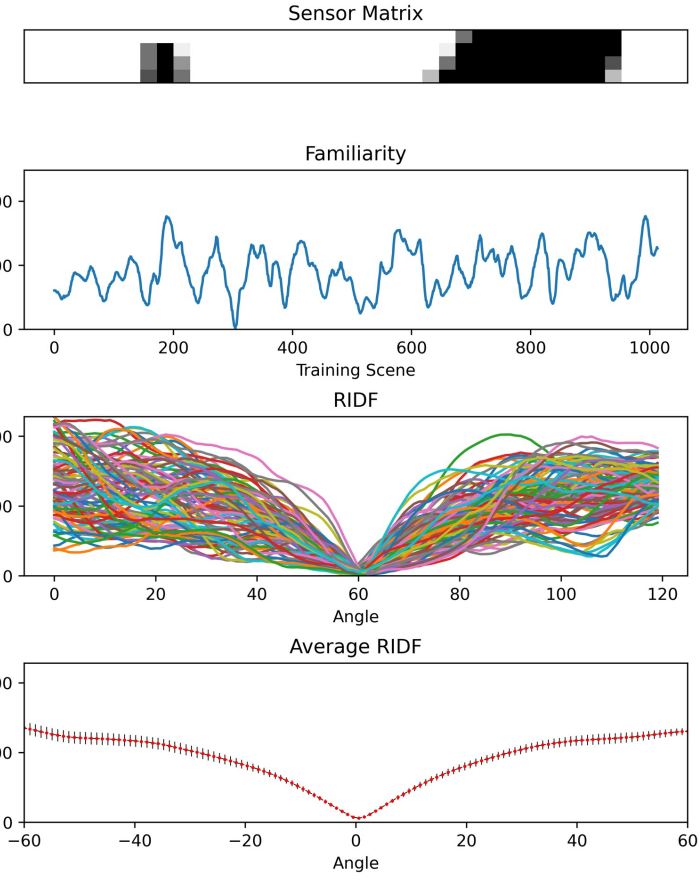


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 683.37; RMSD/dist: 1.708; TD: 1467; p90: 42; p50: 20; complete: 0

100%

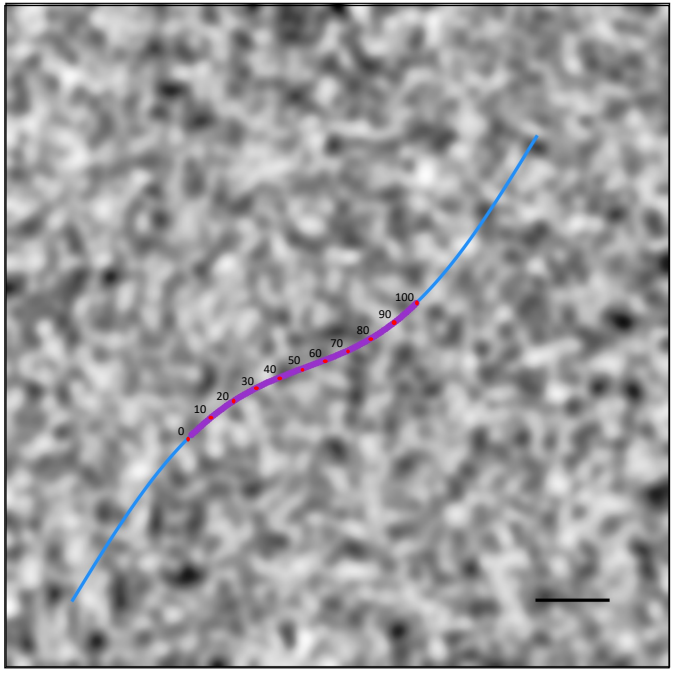


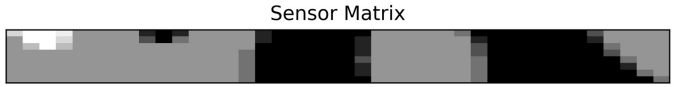


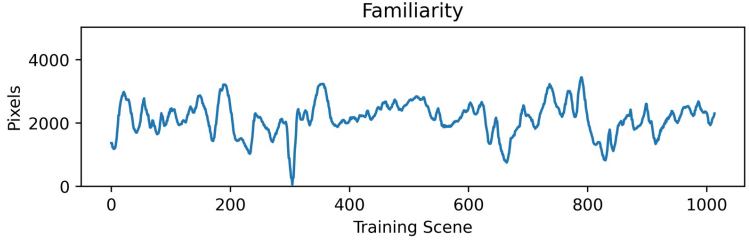
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

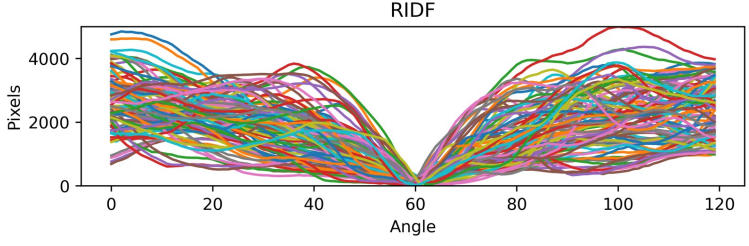
Navigation stats: RMSD error: 47.54; RMSD/dist: 0.119; TD: 1848; p90: 46; p50: 22; complete: 0

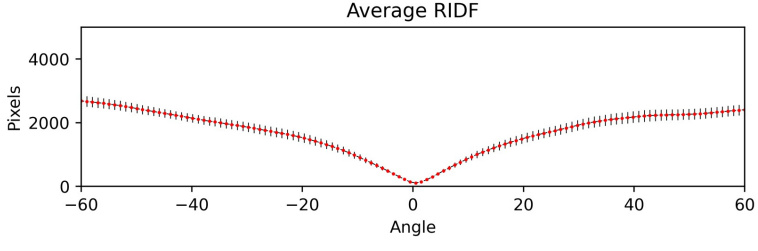
100%







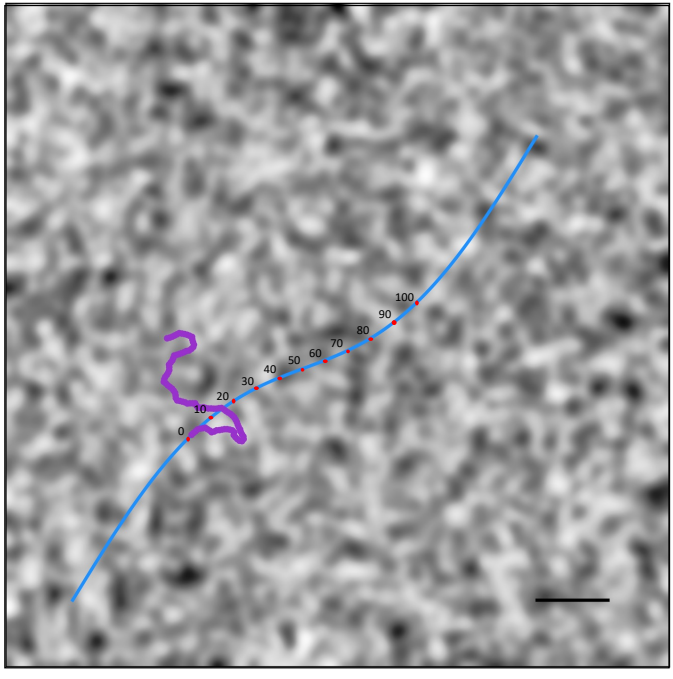


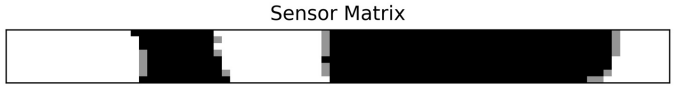


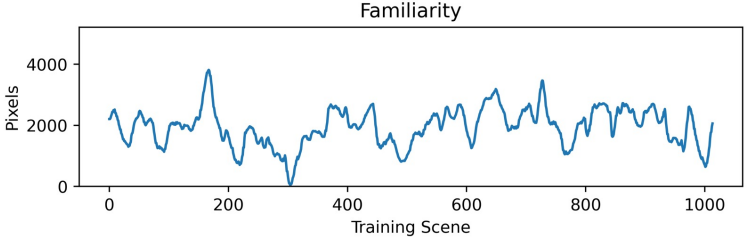
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

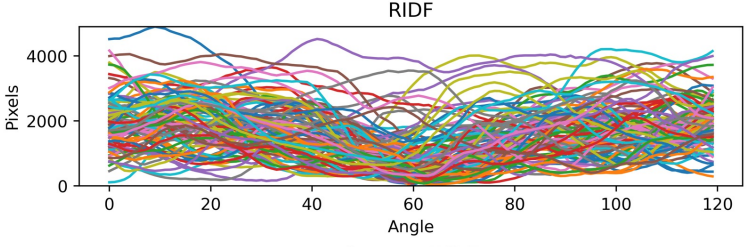
Navigation stats: RMSD error: 41.59; RMSD/dist: 0.104; TD: 1882; p90: 56; p50: 24; complete: 0

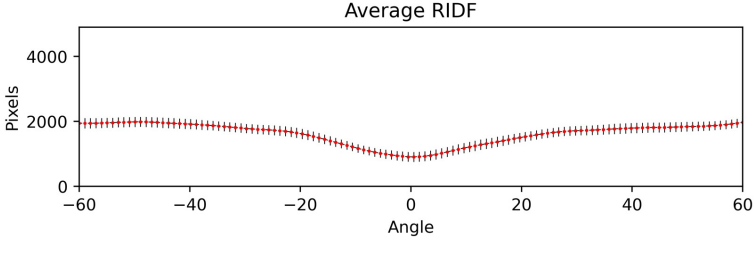
0%







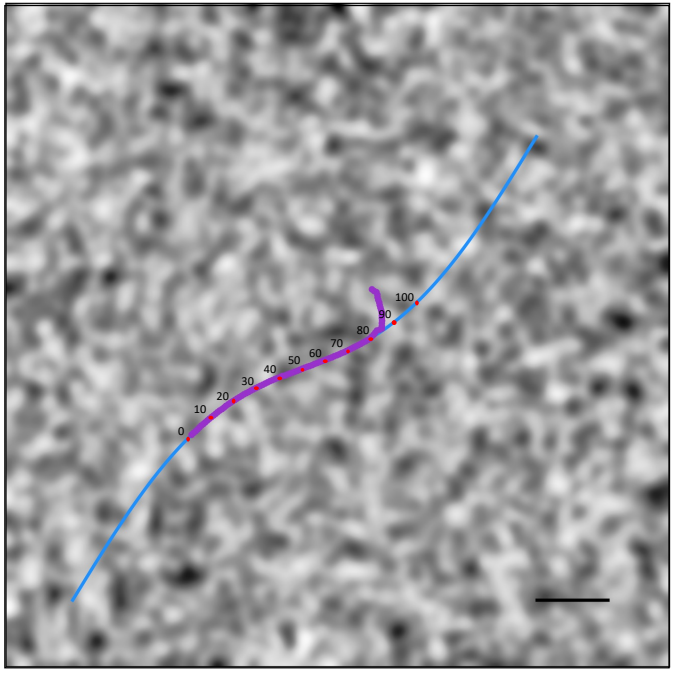


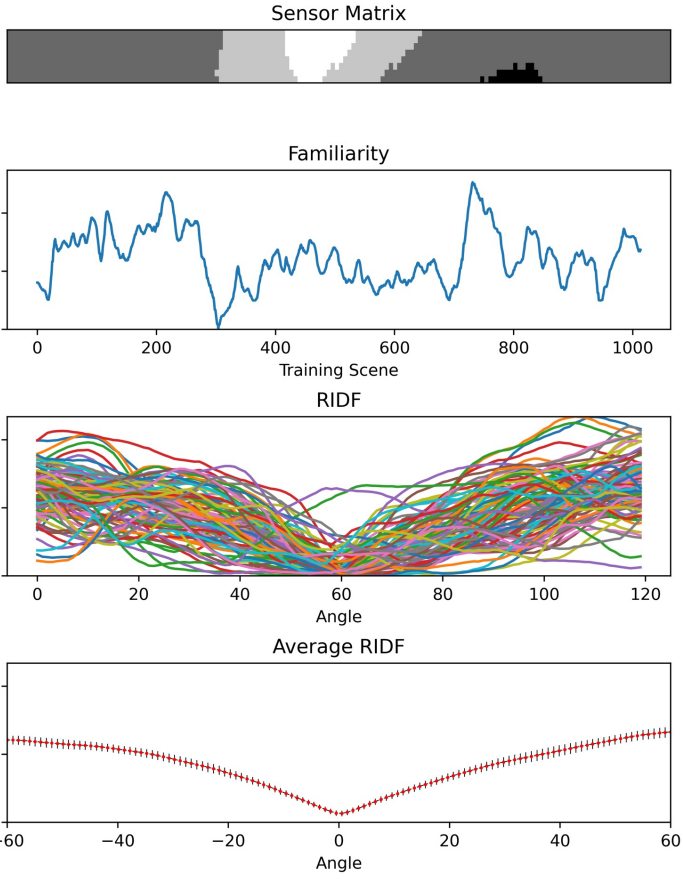


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 5744.83; RMSD/dist: 14.362; TD: 1066; p90: 72; p50: 32; complete: 0

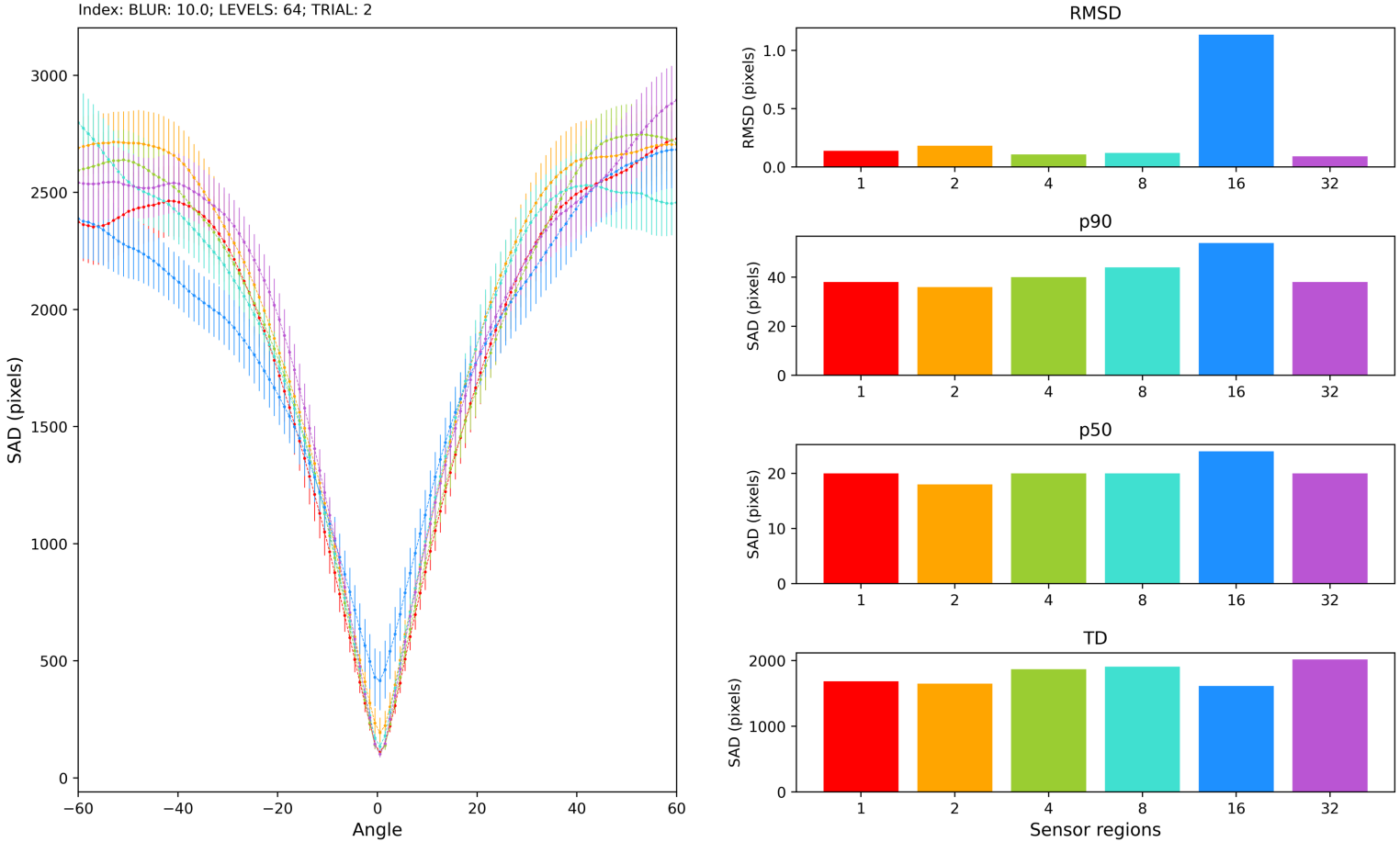
80%



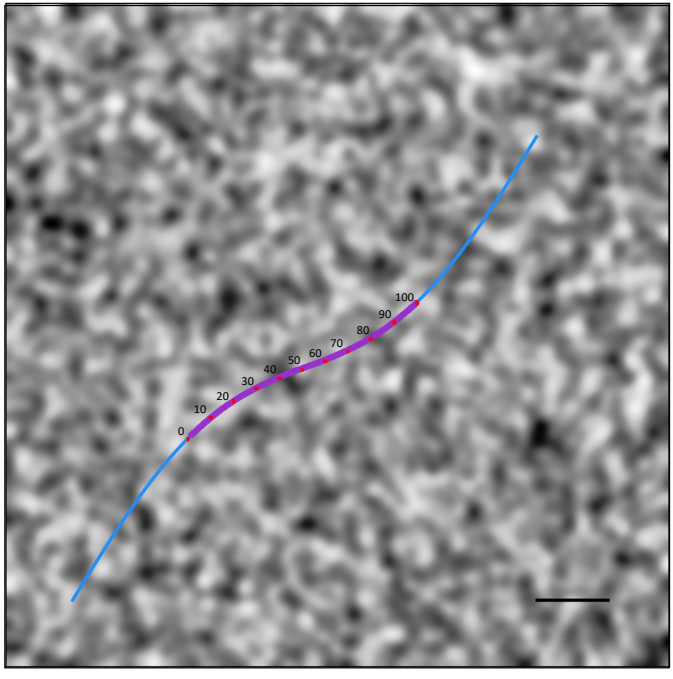


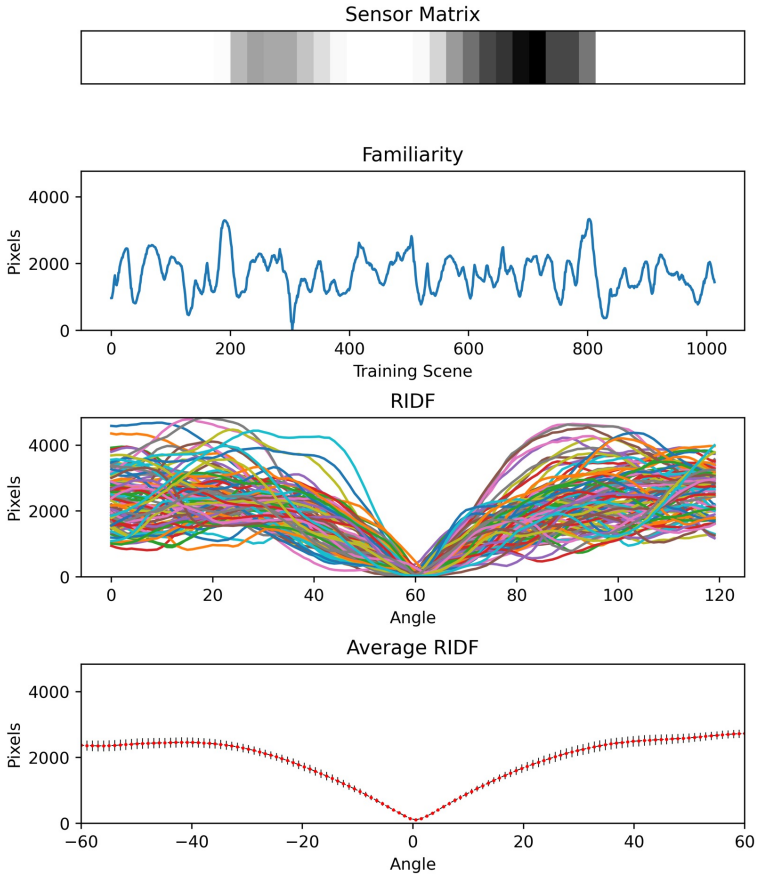
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 580.96; RMSD/dist: 1.452; TD: 1803; p90: 62; p50: 30; complete: 0


Index: BLUR: 10.0; LEVELS: 64; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

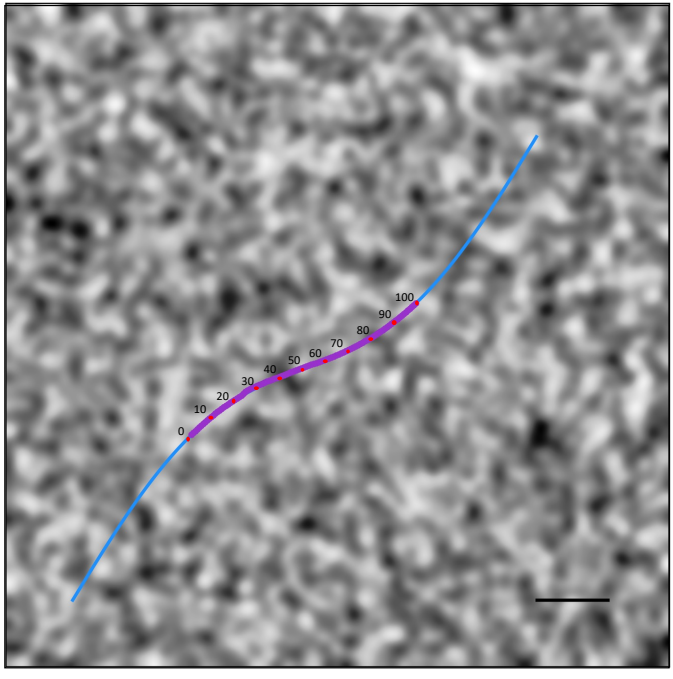


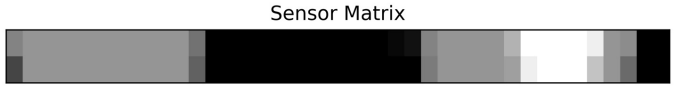


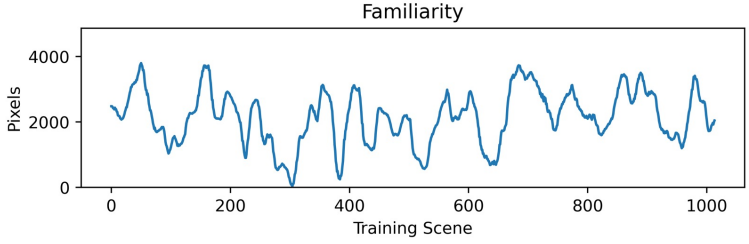
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

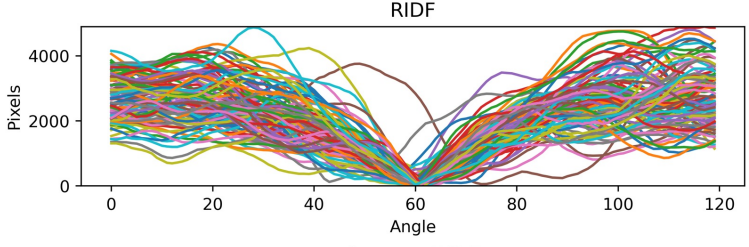
Navigation stats: RMSD error: 54.70; RMSD/dist: 0.137; TD: 1684; p90: 38; p50: 20; complete: 0

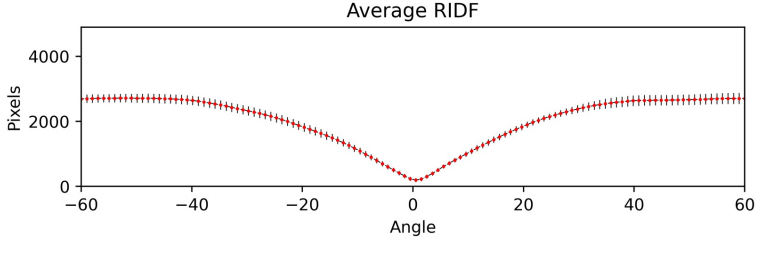
100%







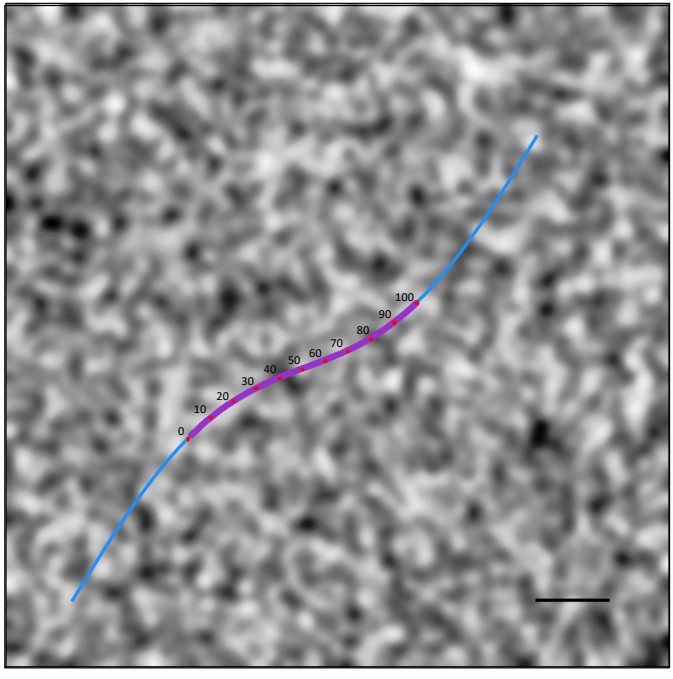


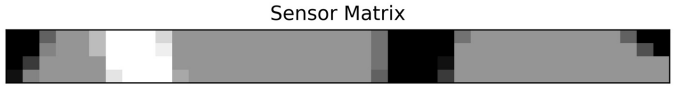


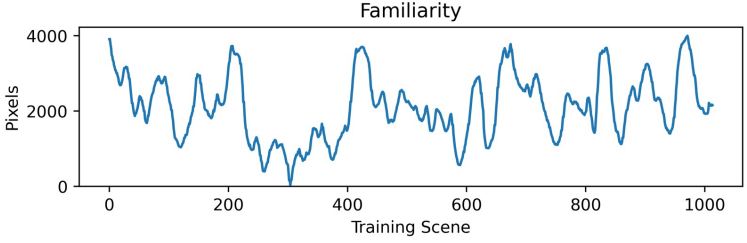
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

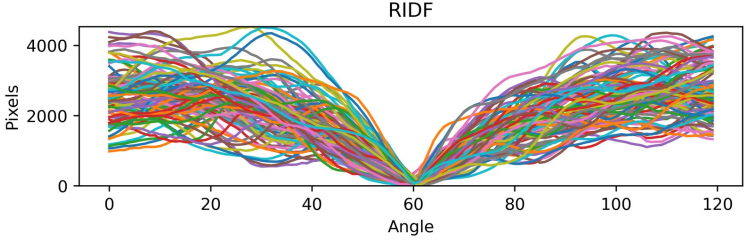
Navigation stats: RMSD error: 72.40; RMSD/dist: 0.181; TD: 1648; p90: 36; p50: 18; complete: 0

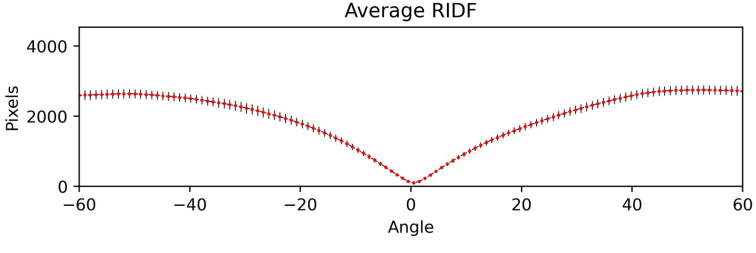
100%







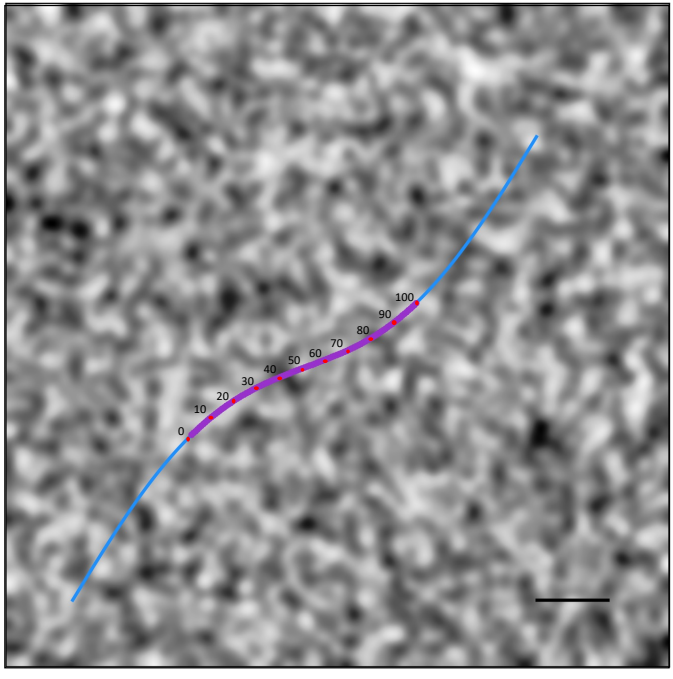


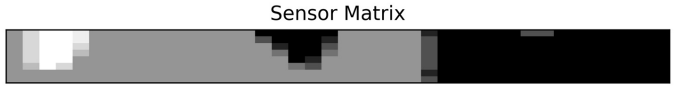


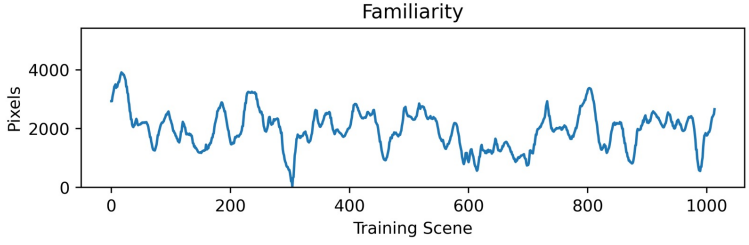
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

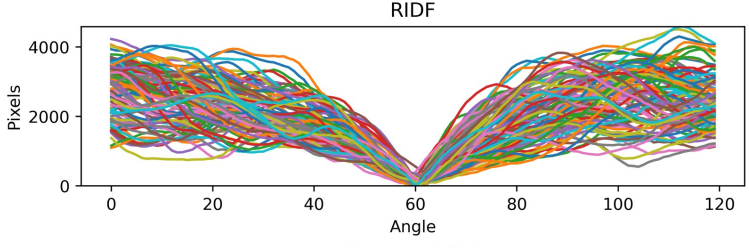
Navigation stats: RMSD error: 42.45; RMSD/dist: 0.106; TD: 1870; p90: 40; p50: 20; complete: 0

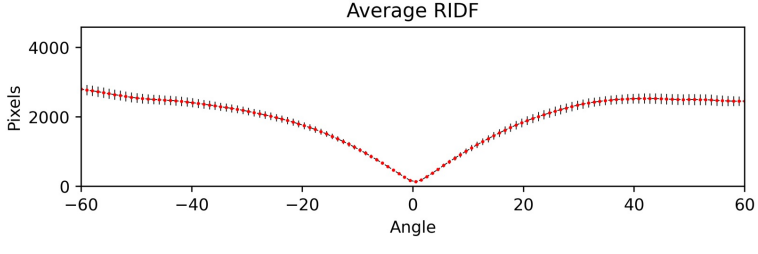
100%







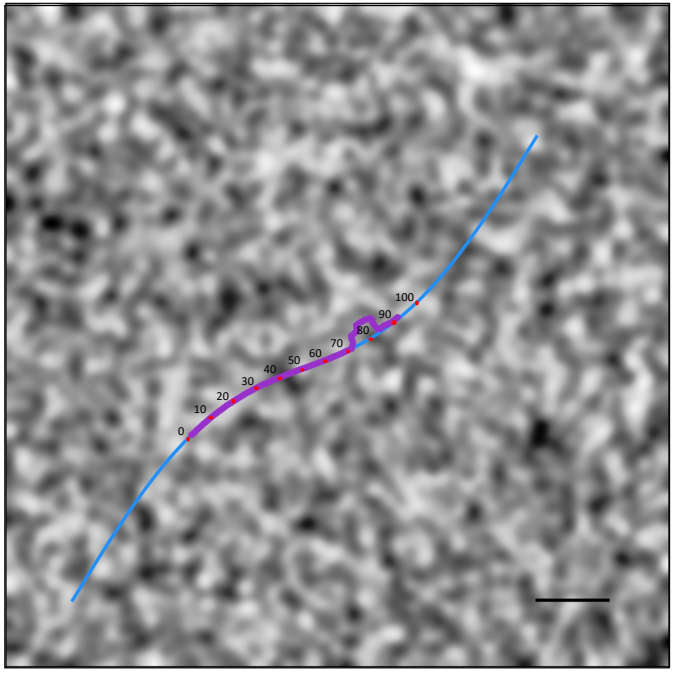


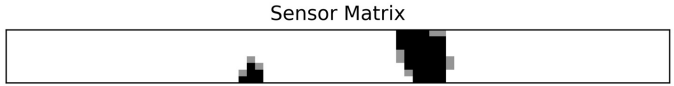


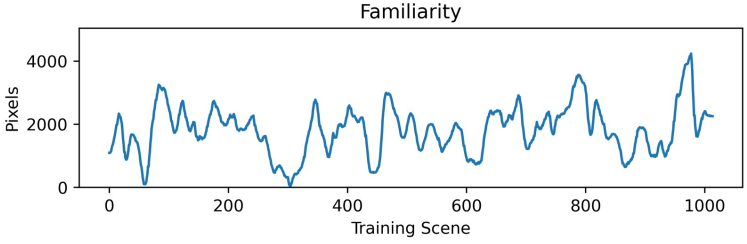
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

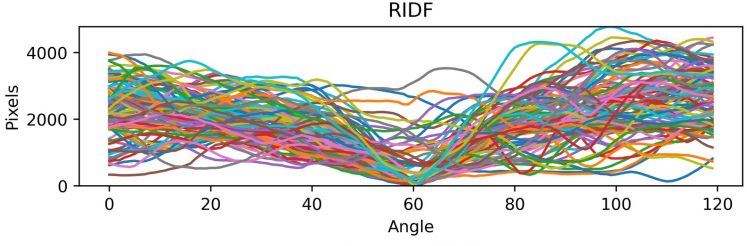
Navigation stats: RMSD error: 47.95; RMSD/dist: 0.120; TD: 1909; p90: 44; p50: 20; complete: 0

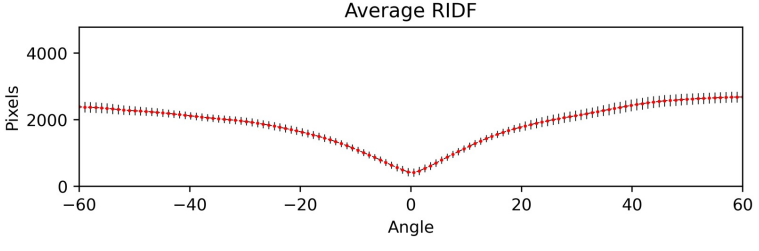
70%







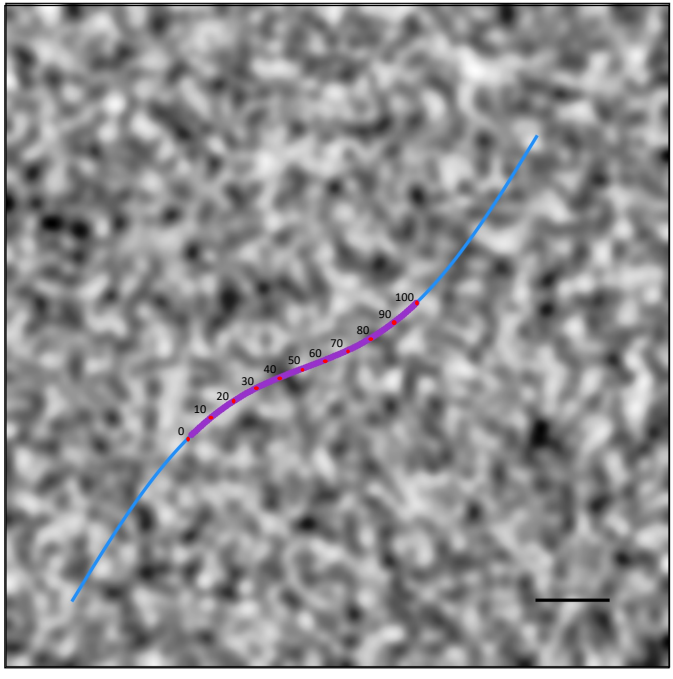


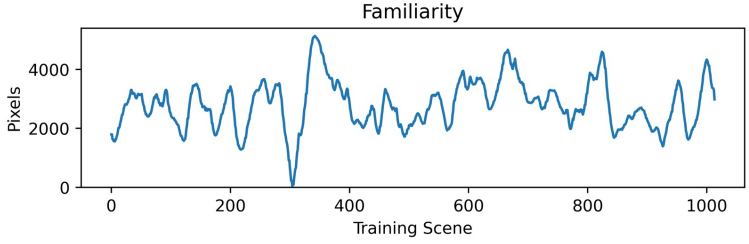


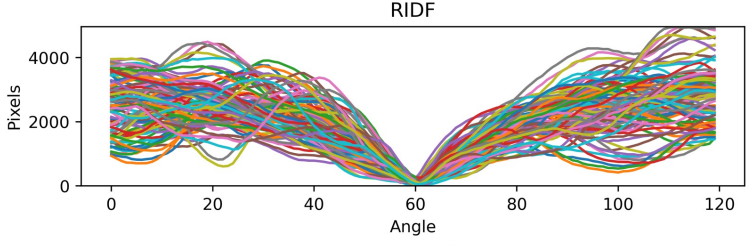
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

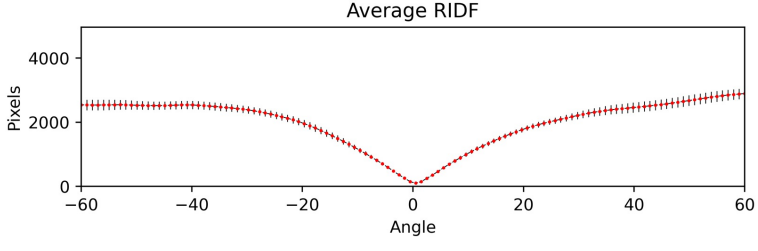
Navigation stats: RMSD error: 454.39; RMSD/dist: 1.136; TD: 1613; p90: 54; p50: 24; complete: 0

100%



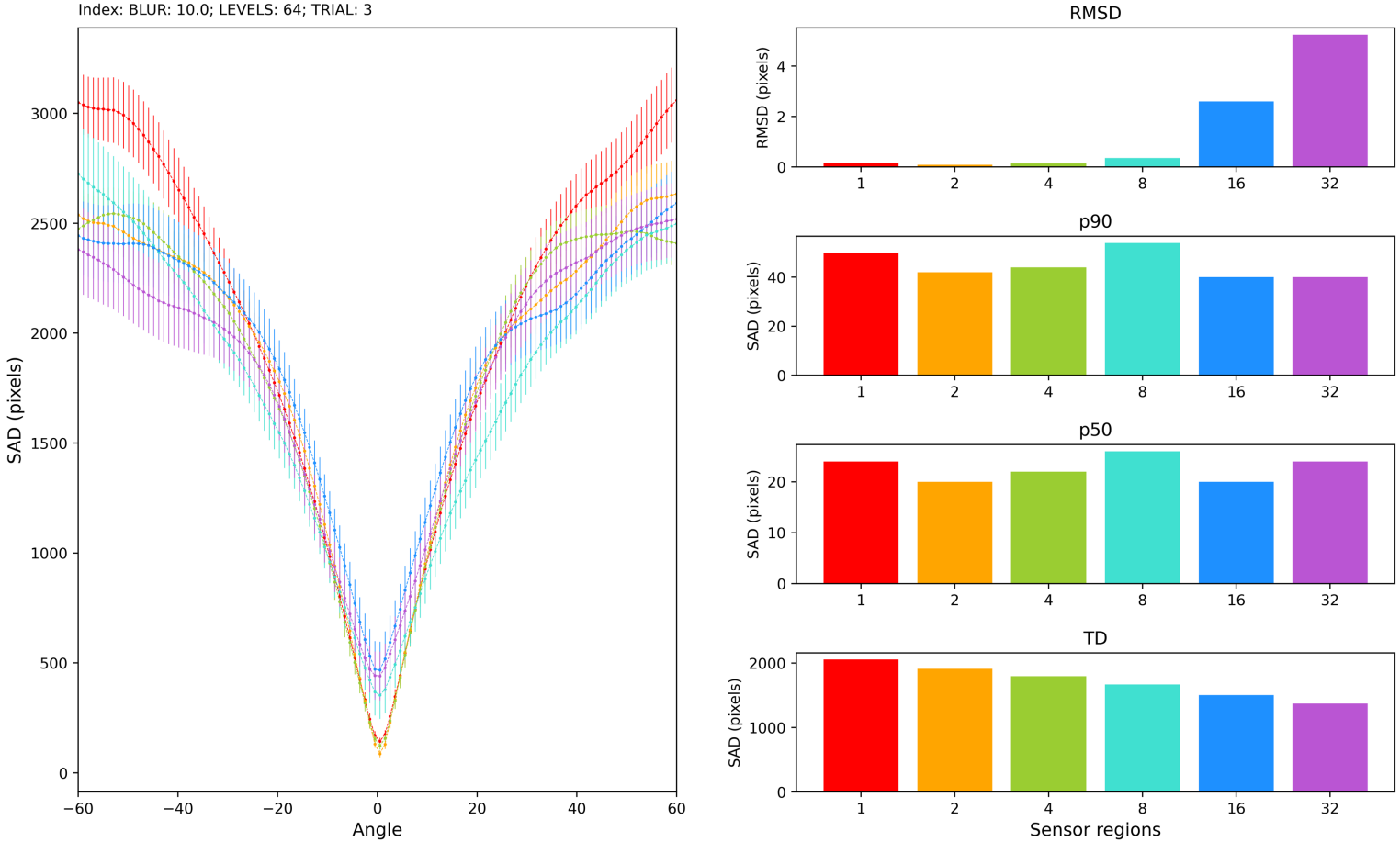




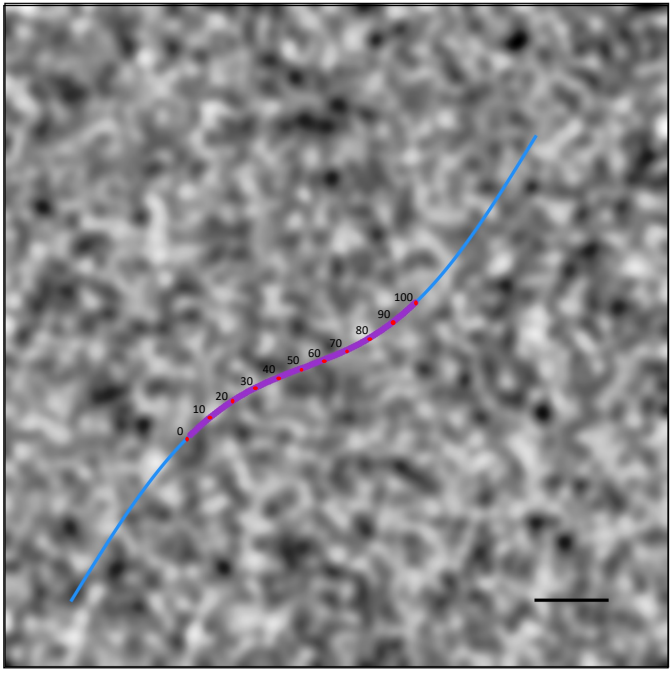


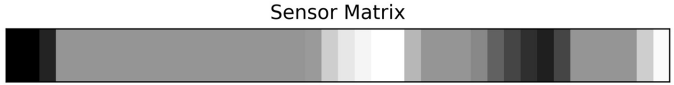
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

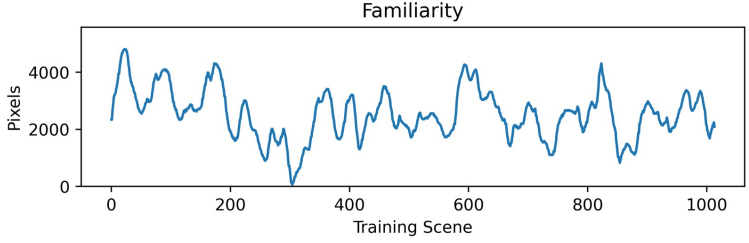
Navigation stats: RMSD error: 36.19; RMSD/dist: 0.090; TD: 2016; p90: 38; p50: 20; complete: 0

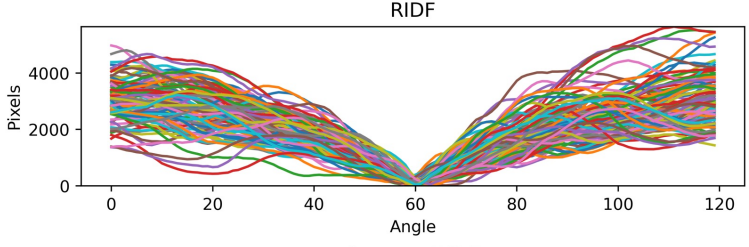

Index: BLUR: 10.0; LEVELS: 64; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

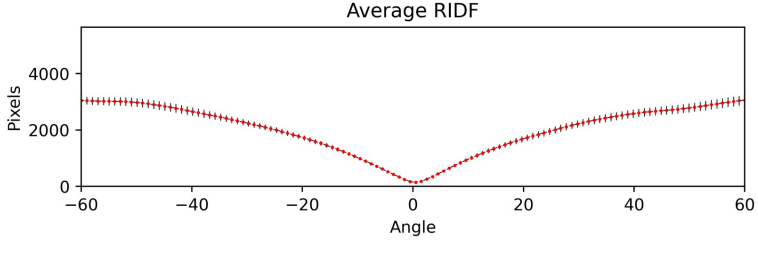
100%







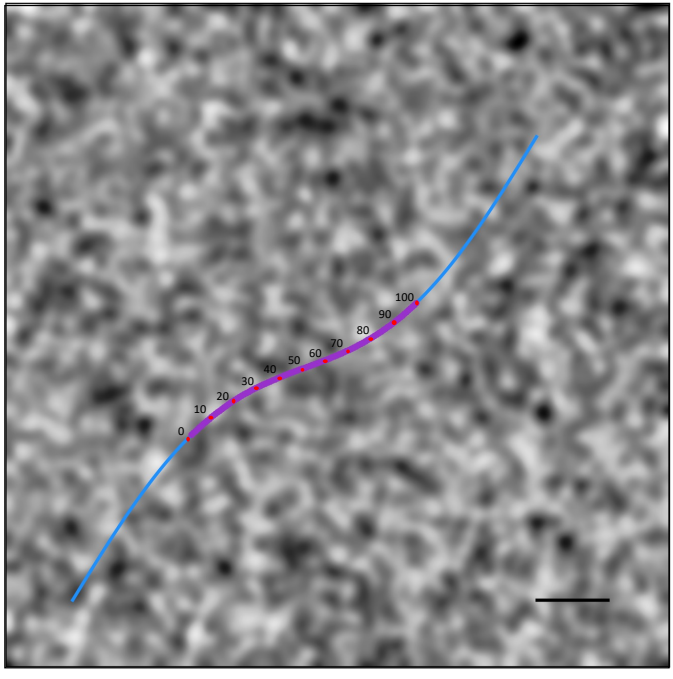


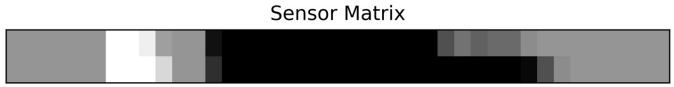


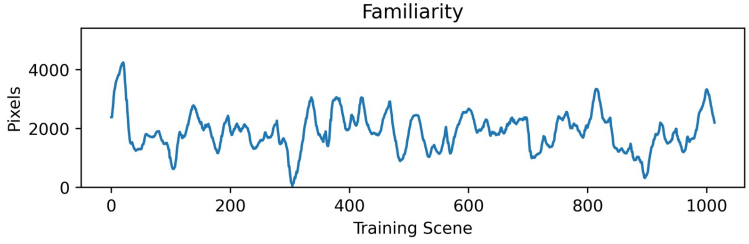
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

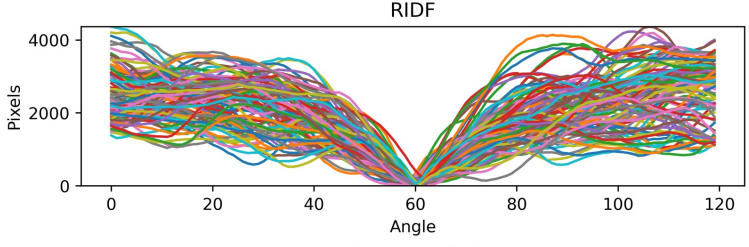
Navigation stats: RMSD error: 64.14; RMSD/dist: 0.160; TD: 2054; p90: 50; p50: 24; complete: 0

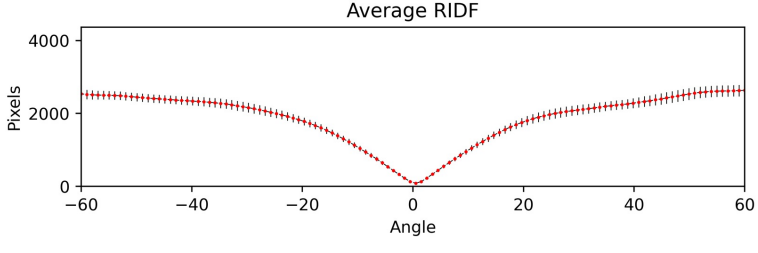
100%







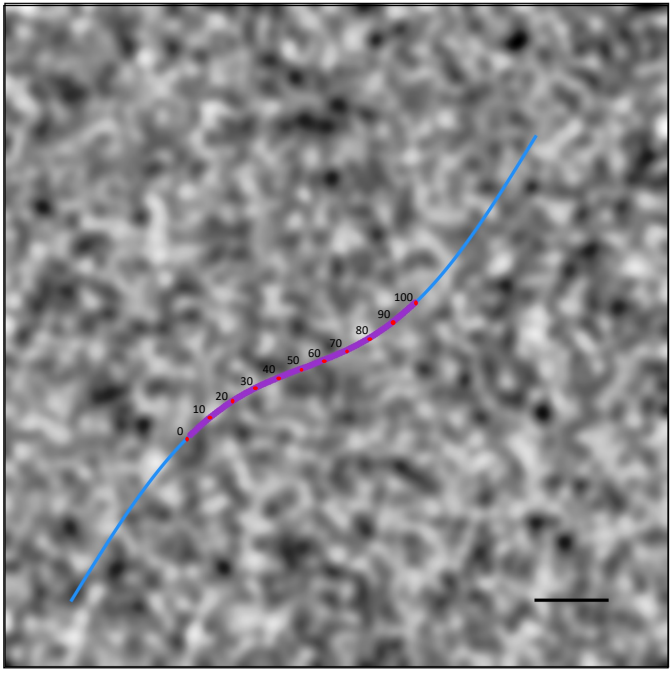


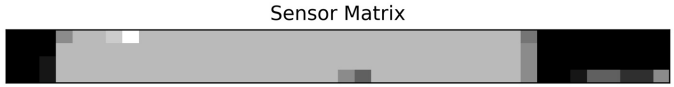


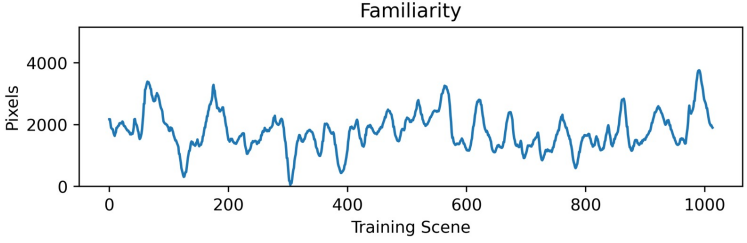
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

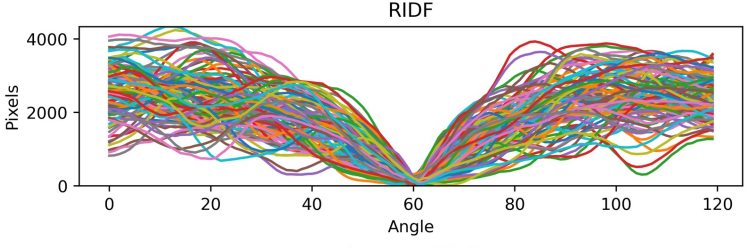
Navigation stats: RMSD error: 31.92; RMSD/dist: 0.080; TD: 1911; p90: 42; p50: 20; complete: 0

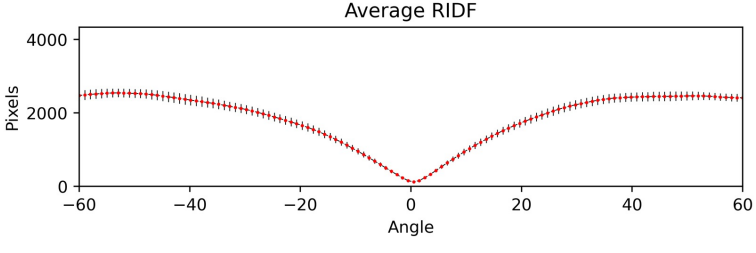
100%







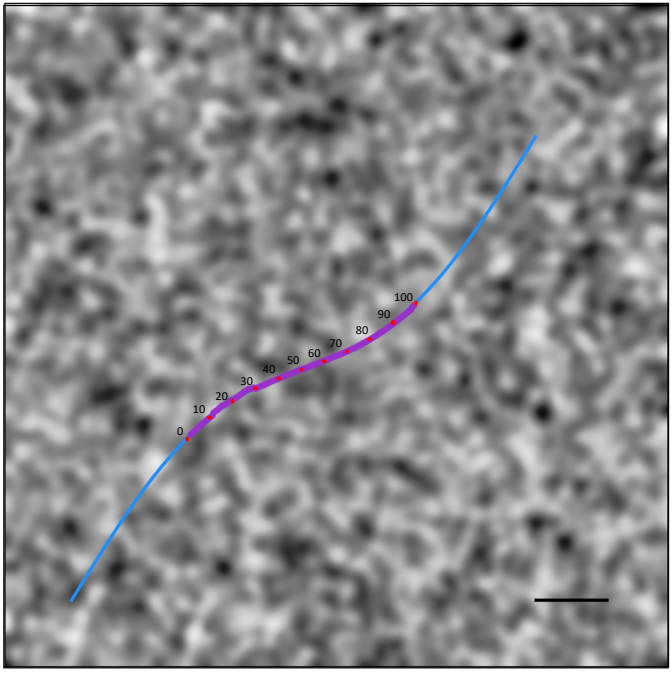


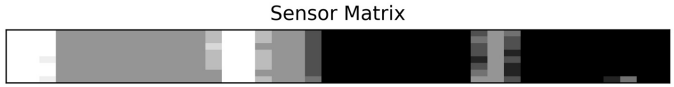


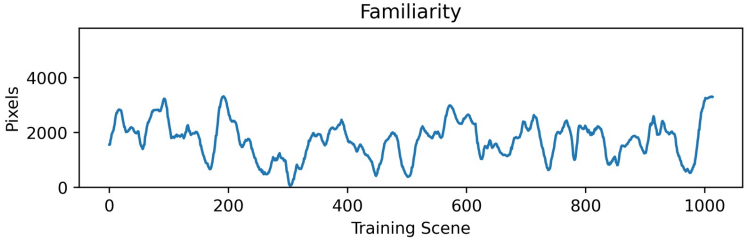
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

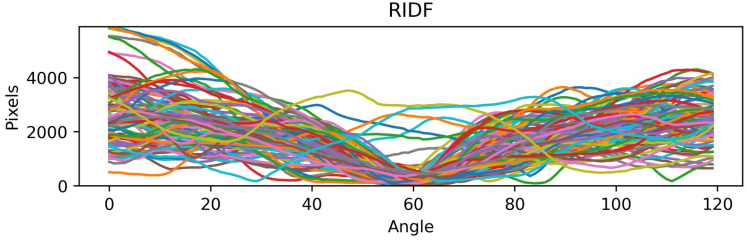
Navigation stats: RMSD error: 57.23; RMSD/dist: 0.143; TD: 1795; p90: 44; p50: 22; complete: 0

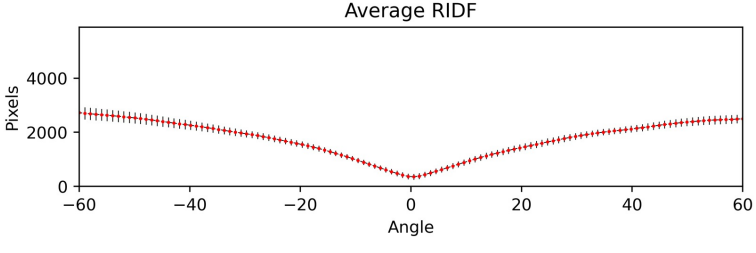
90%







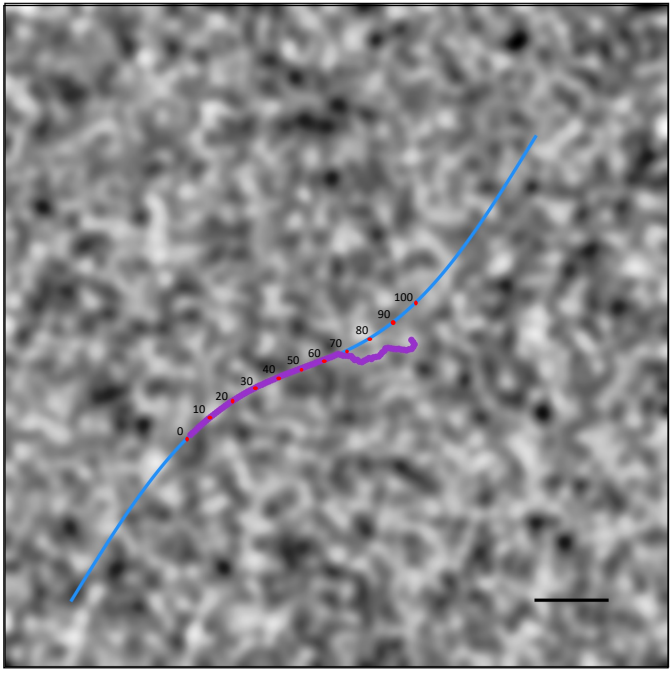


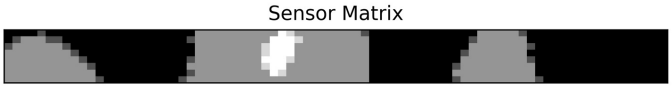


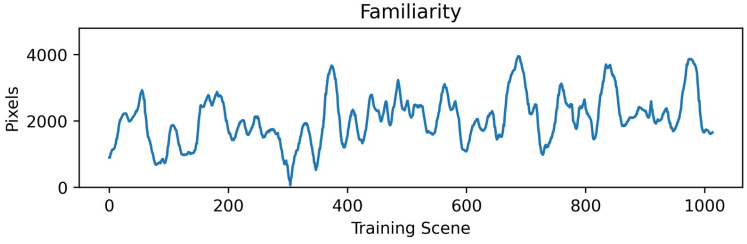
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

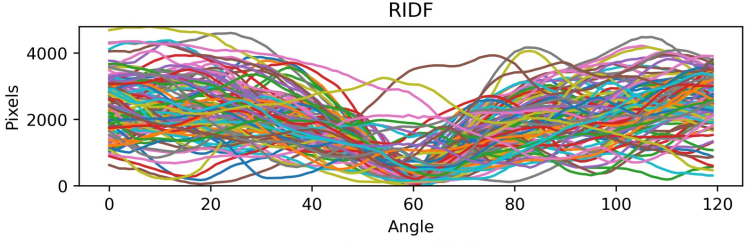
Navigation stats: RMSD error: 139.86; RMSD/dist: 0.350; TD: 1666; p90: 54; p50: 26; complete: 0

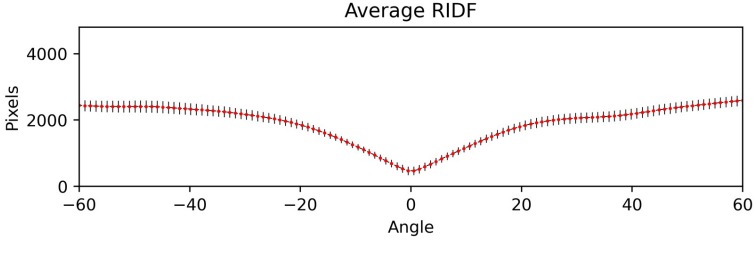
60%







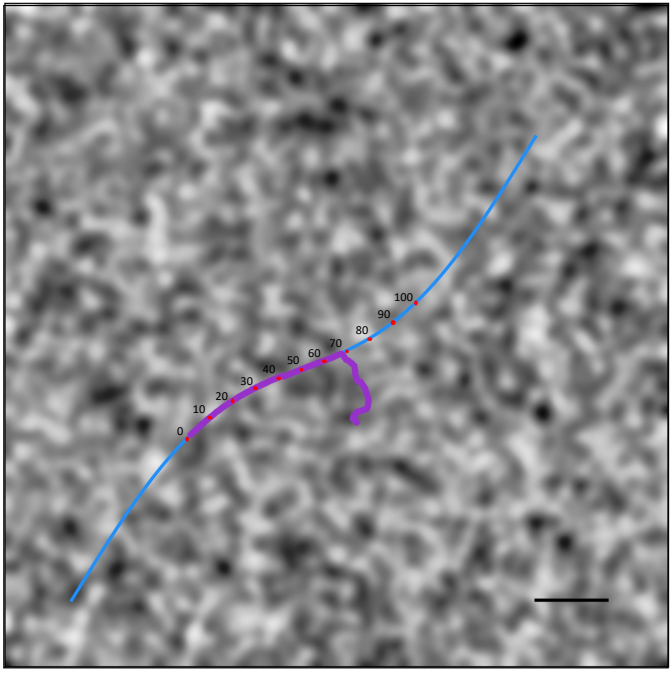


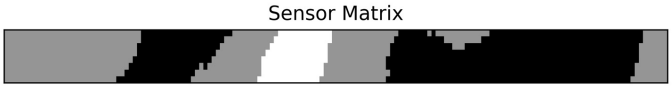


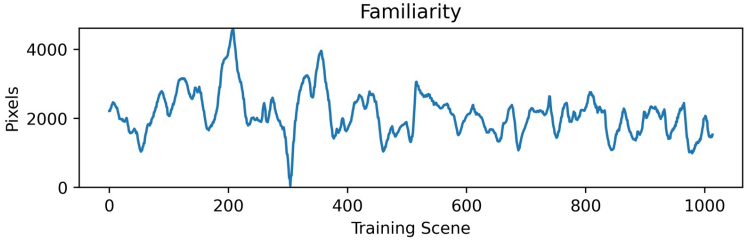
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

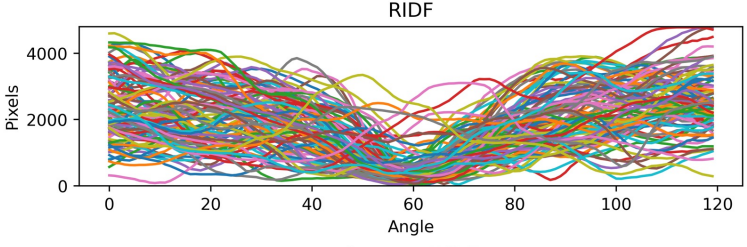
Navigation stats: RMSD error: 1038.46; RMSD/dist: 2.596; TD: 1503; p90: 40; p50: 20; complete: 0

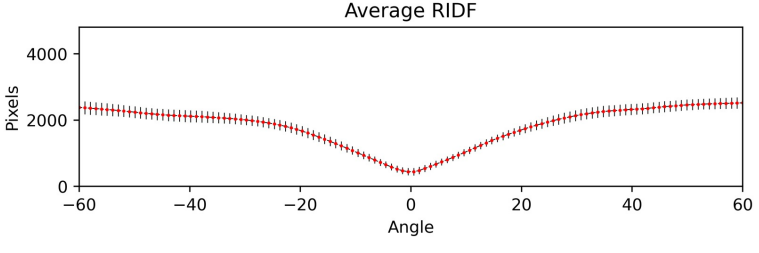
60%





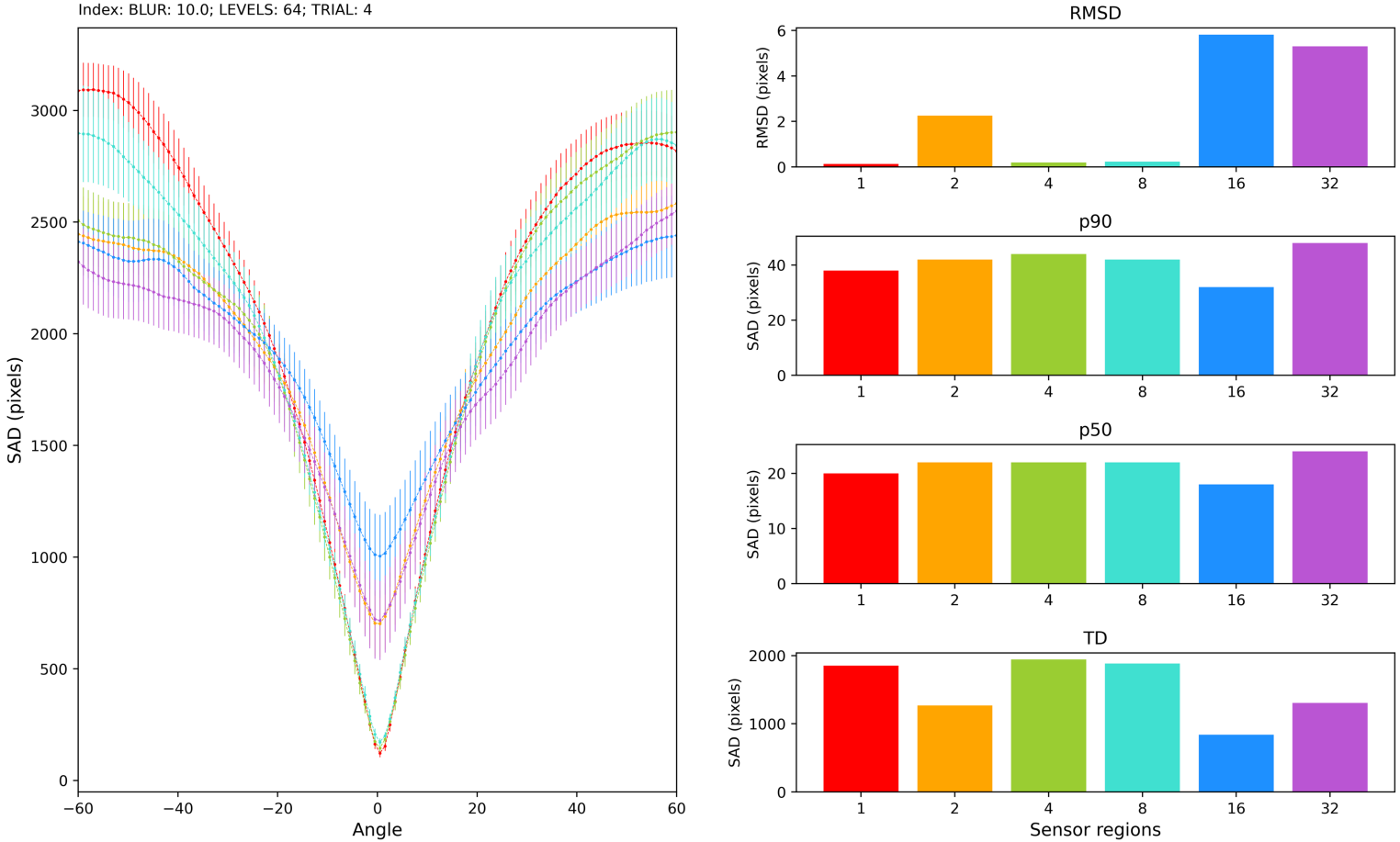




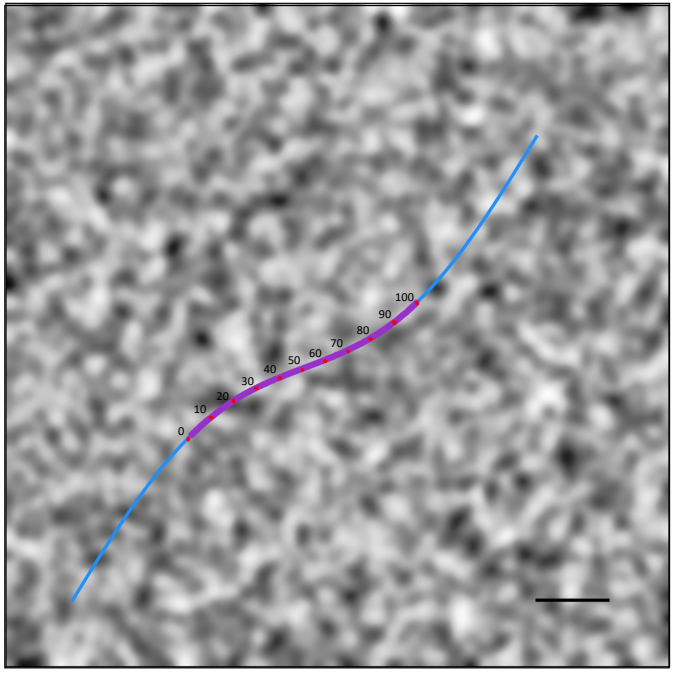


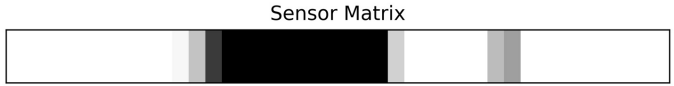
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

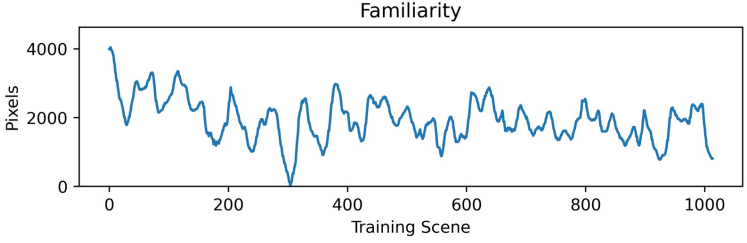
Navigation stats: RMSD error: 2100.43; RMSD/dist: 5.251; TD: 1370; p90: 40; p50: 24; complete: 0

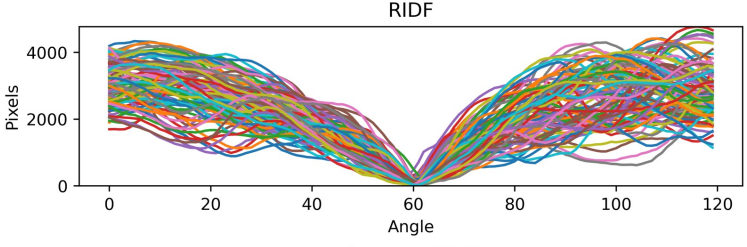

Index: BLUR: 10.0; LEVELS: 64; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

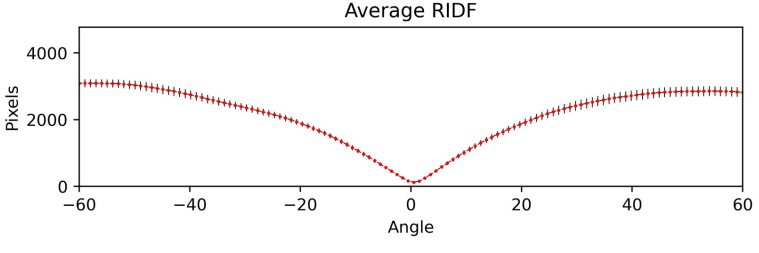
100%







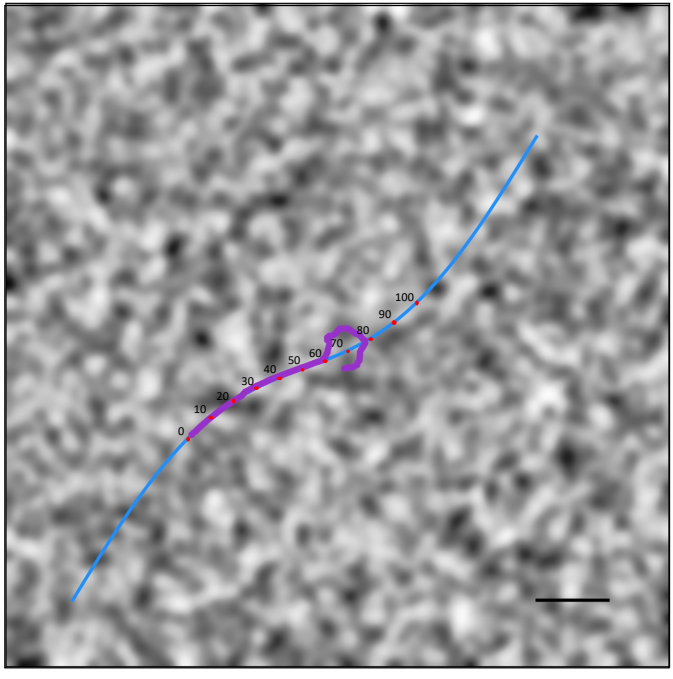


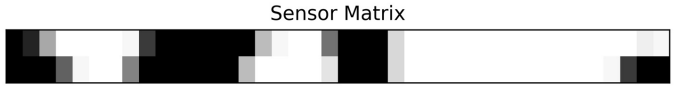


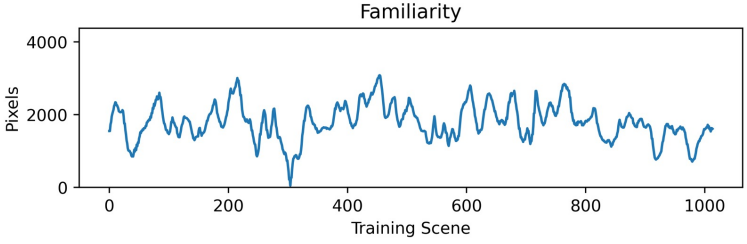
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

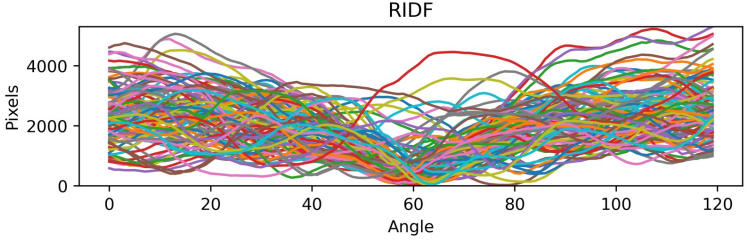
Navigation stats: RMSD error: 49.33; RMSD/dist: 0.123; TD: 1851; p90: 38; p50: 20; complete: 0

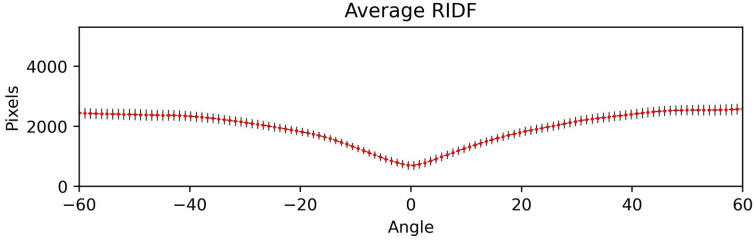
50%







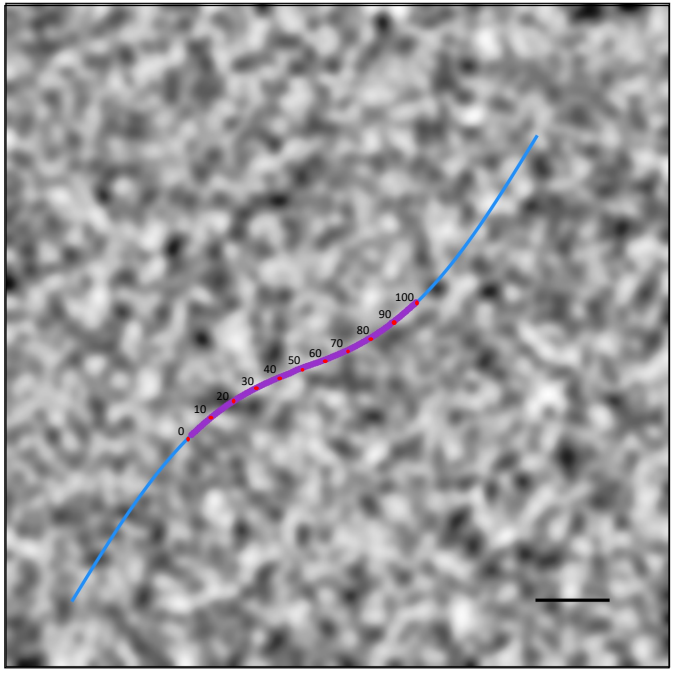


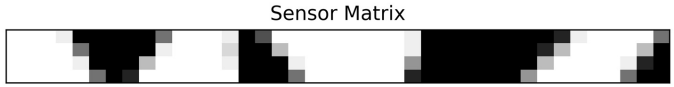


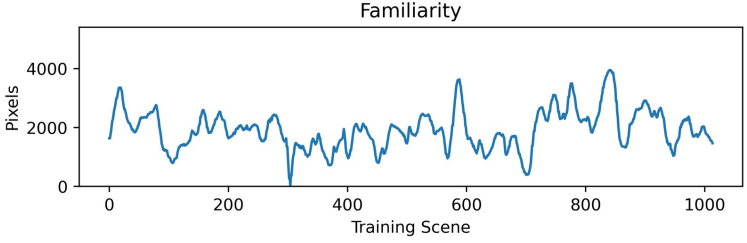
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

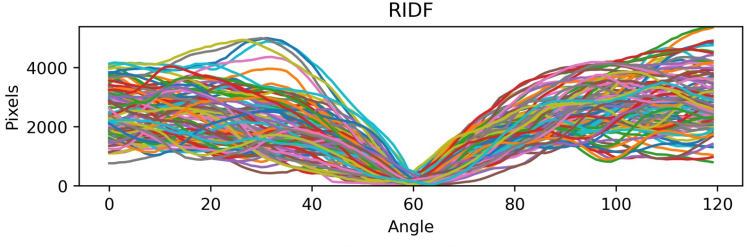
Navigation stats: RMSD error: 903.35; RMSD/dist: 2.258; TD: 1267; p90: 42; p50: 22; complete: 0

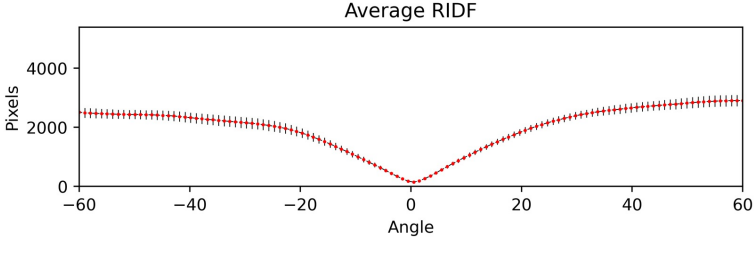
100%







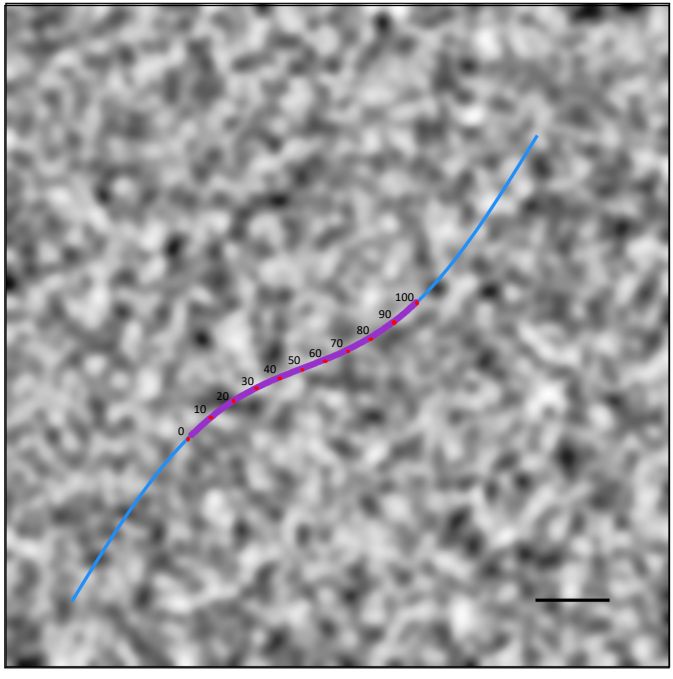


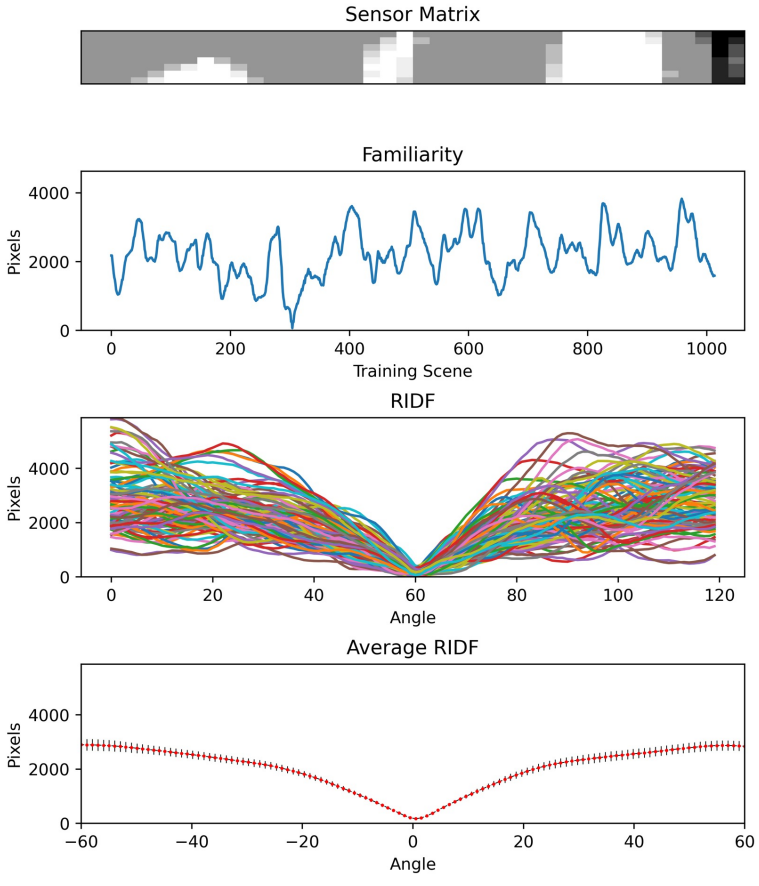


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 78.54; RMSD/dist: 0.196; TD: 1941; p90: 44; p50: 22; complete: 0

100%

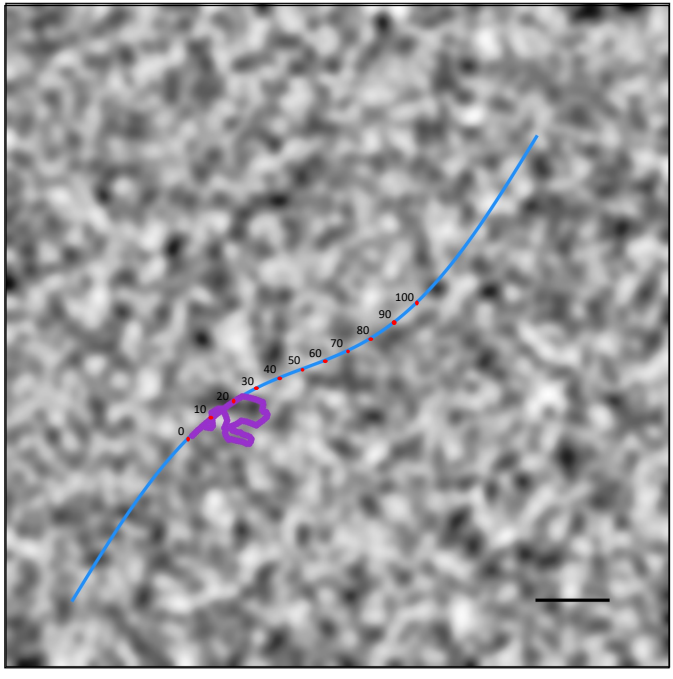


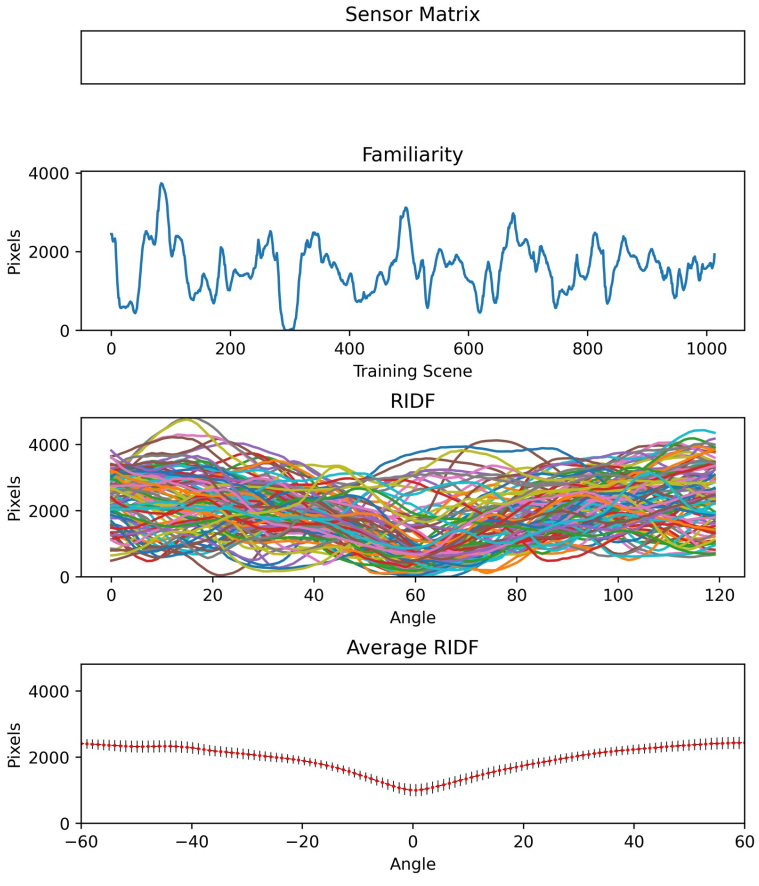


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 93.04; RMSD/dist: 0.233; TD: 1884; p90: 42; p50: 22; complete: 0

20%

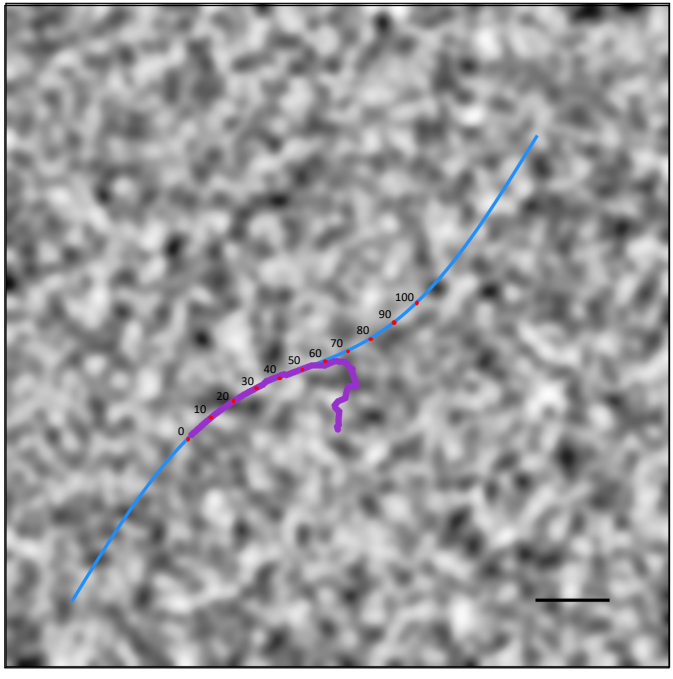


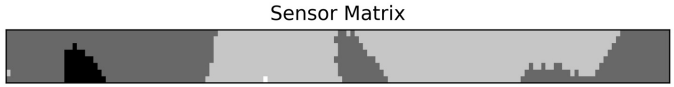


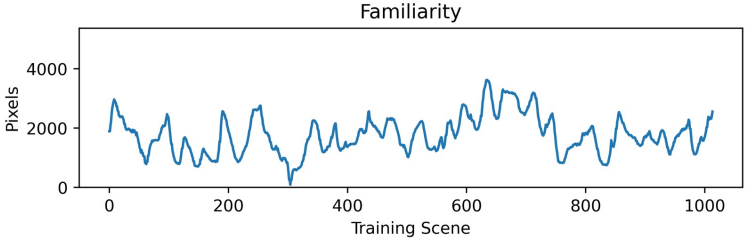
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

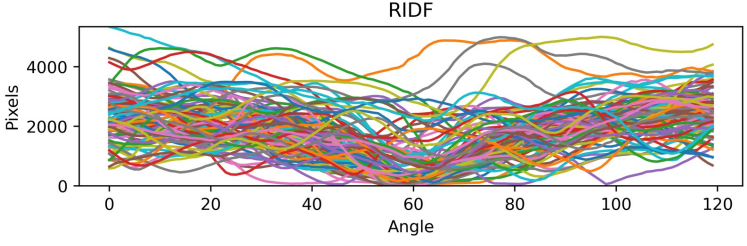
Navigation stats: RMSD error: 2328.03; RMSD/dist: 5.820; TD: 840; p90: 32; p50: 18; complete: 0

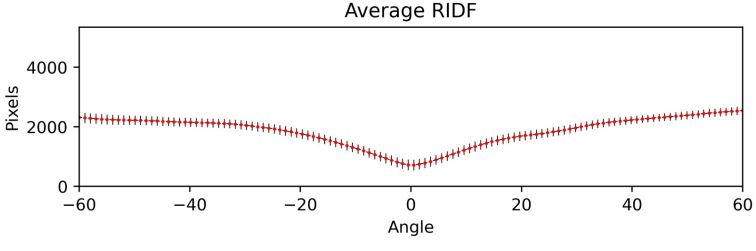
50%





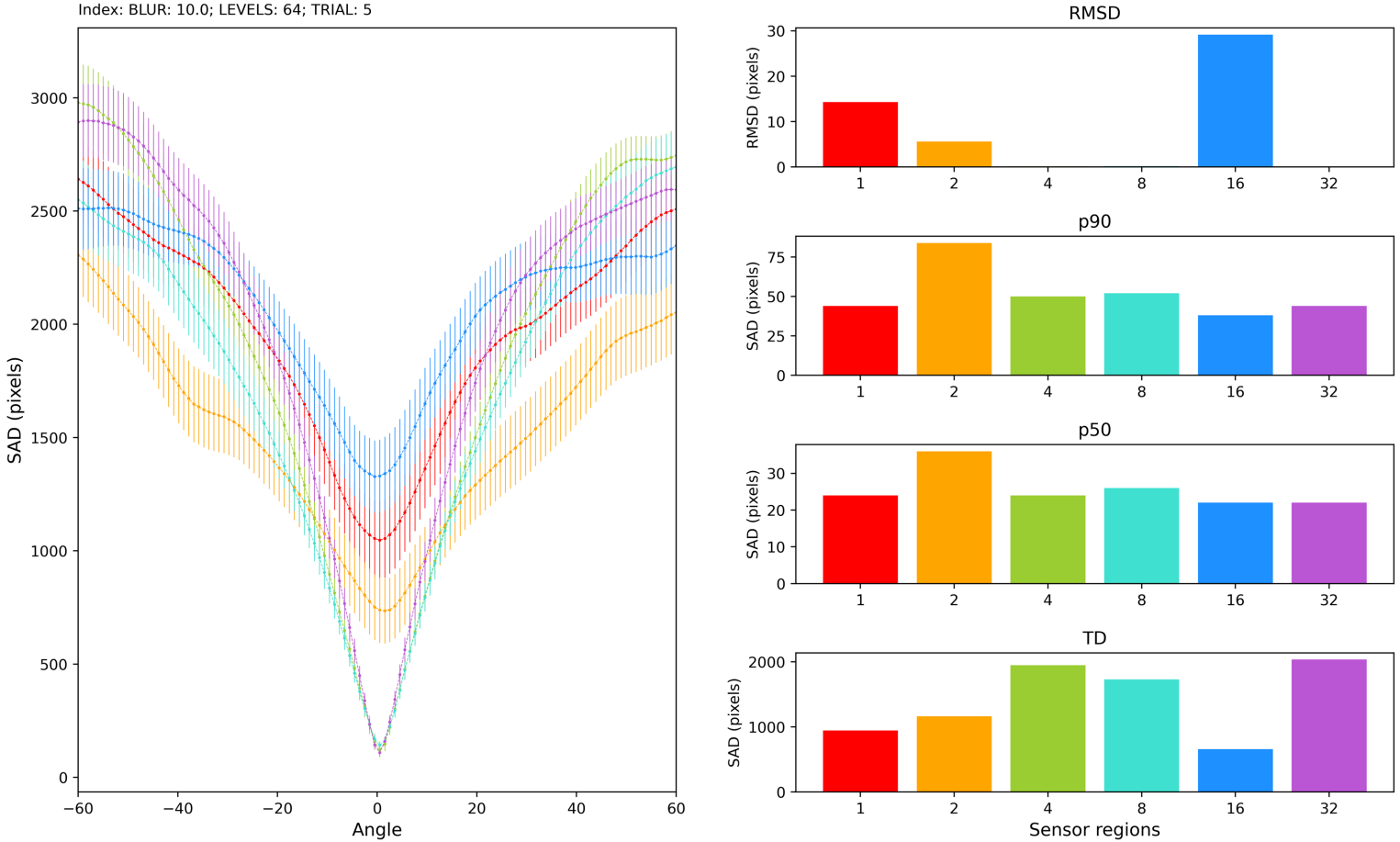




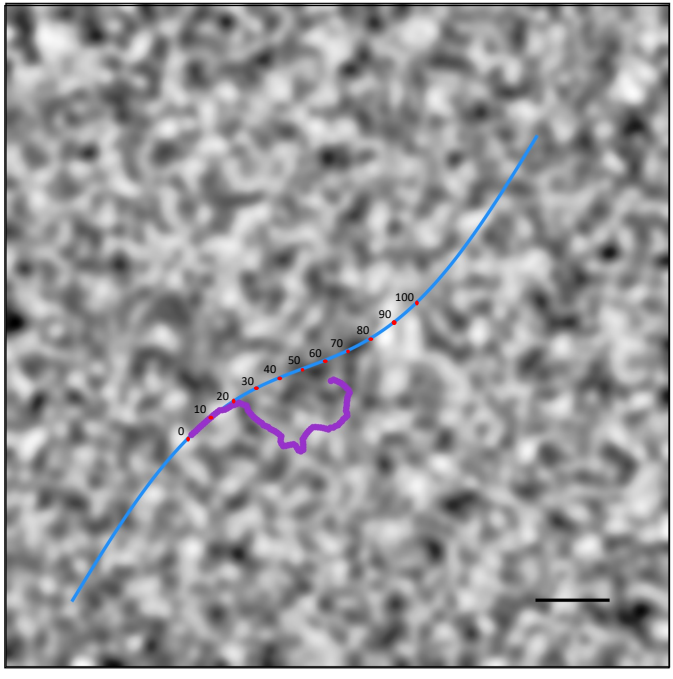


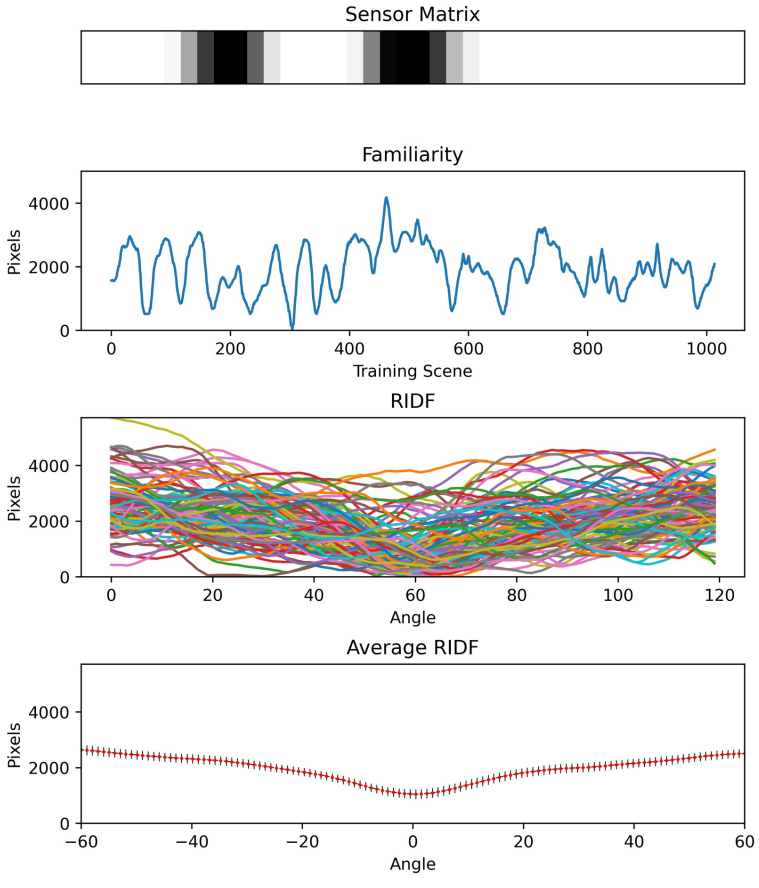
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2121.85; RMSD/dist: 5.305; TD: 1305; p90: 48; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 64; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

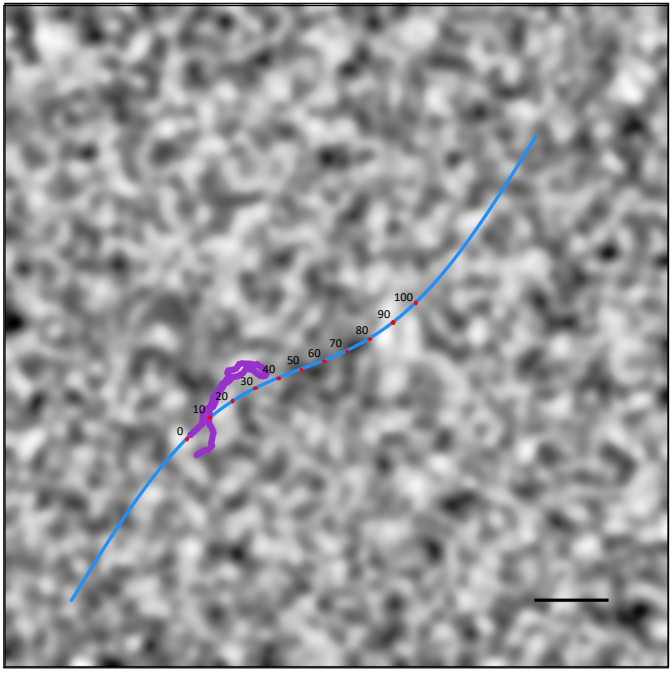


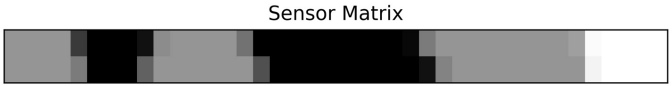


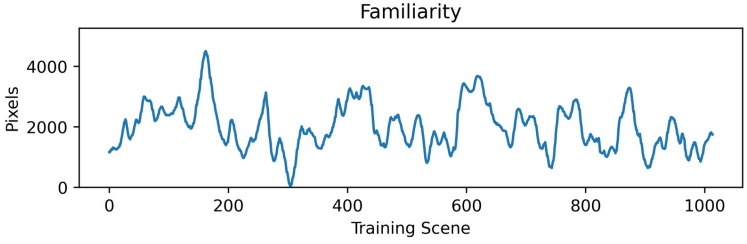
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

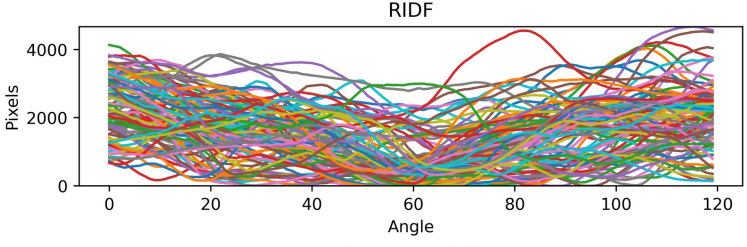
Navigation stats: RMSD error: 5716.38; RMSD/dist: 14.291; TD: 944; p90: 44; p50: 24; complete: 0

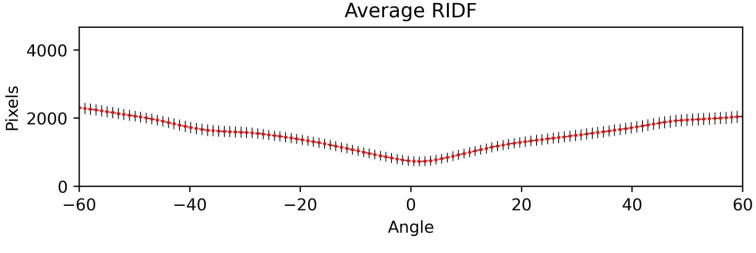
10%







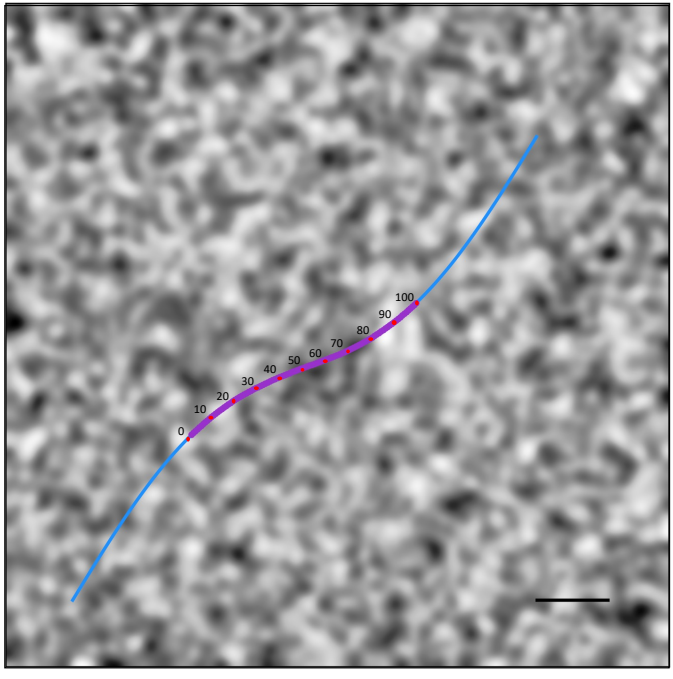


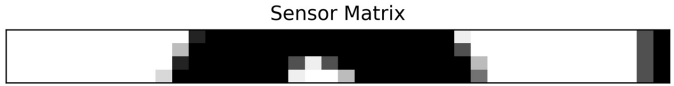


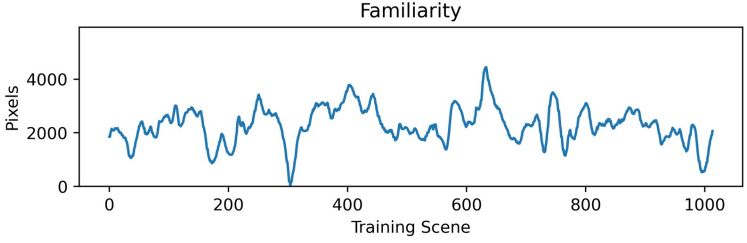
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

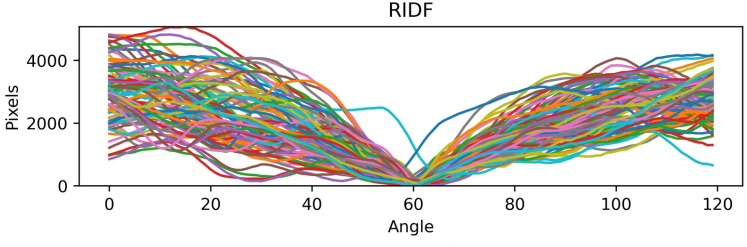
Navigation stats: RMSD error: 2230.66; RMSD/dist: 5.577; TD: 1164; p90: 84; p50: 36; complete: 0

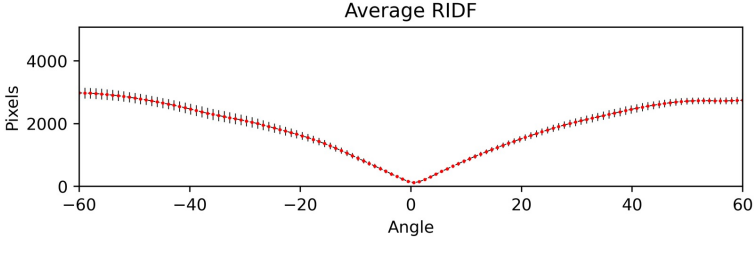
100%







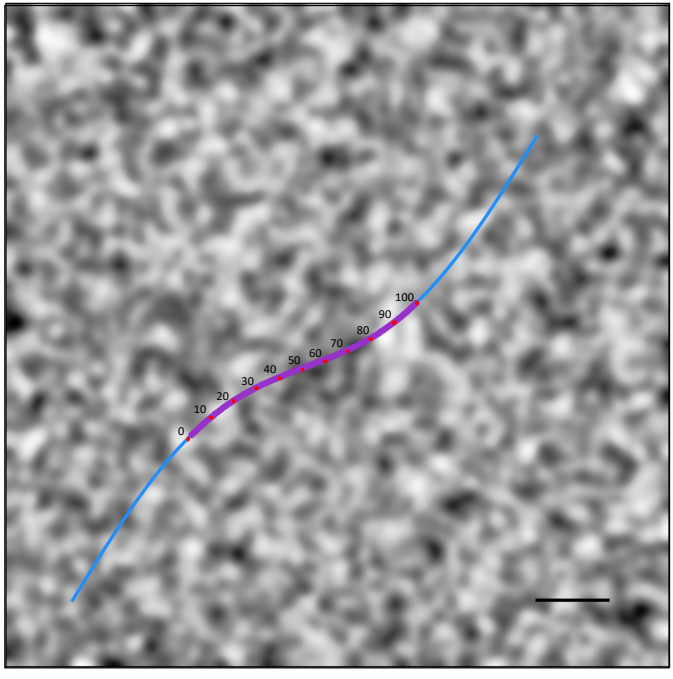


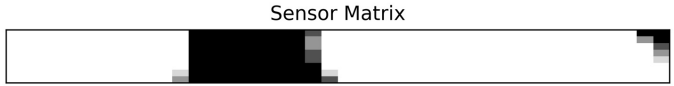


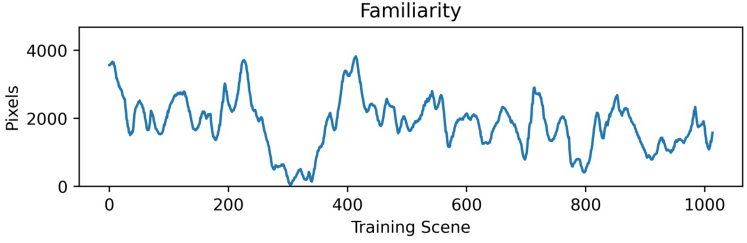
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

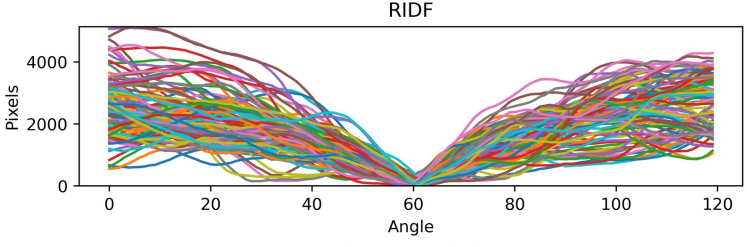
Navigation stats: RMSD error: 40.92; RMSD/dist: 0.102; TD: 1947; p90: 50; p50: 24; complete: 0

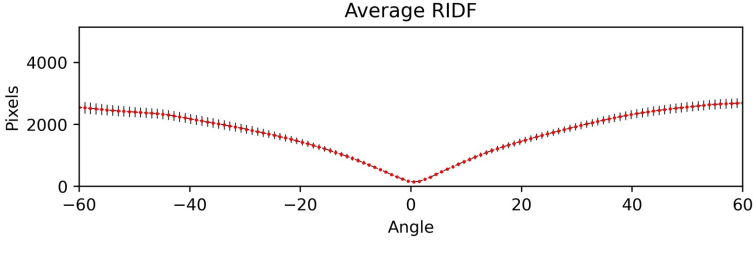
100%







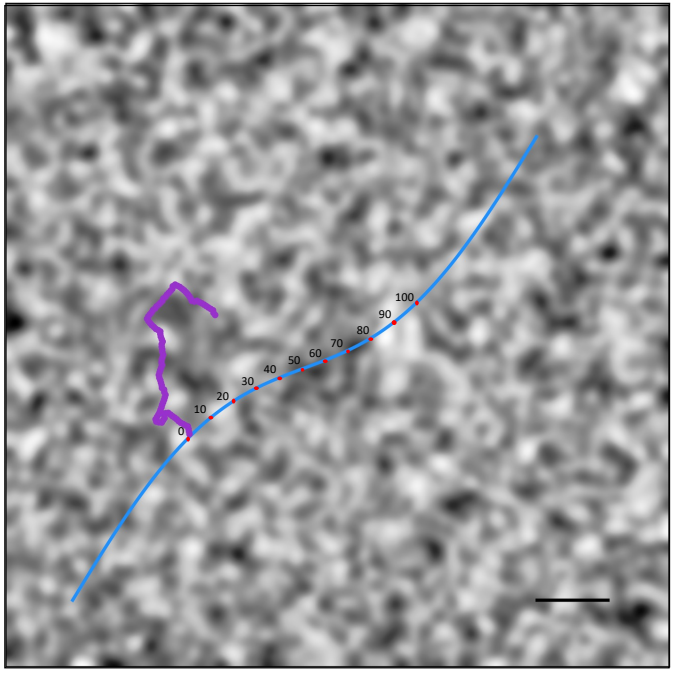


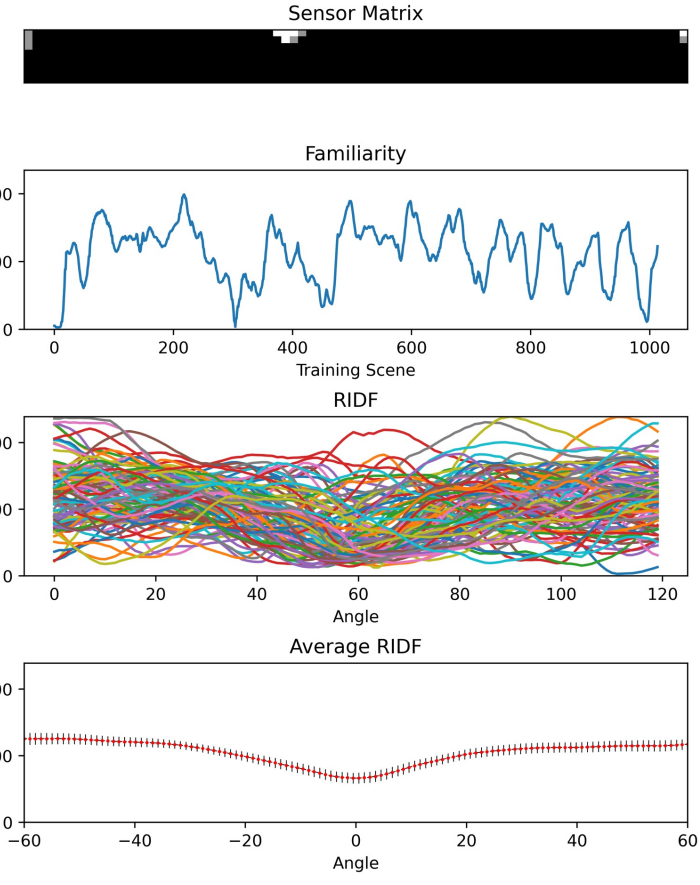


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 75.78; RMSD/dist: 0.189; TD: 1729; p90: 52; p50: 26; complete: 0

100%

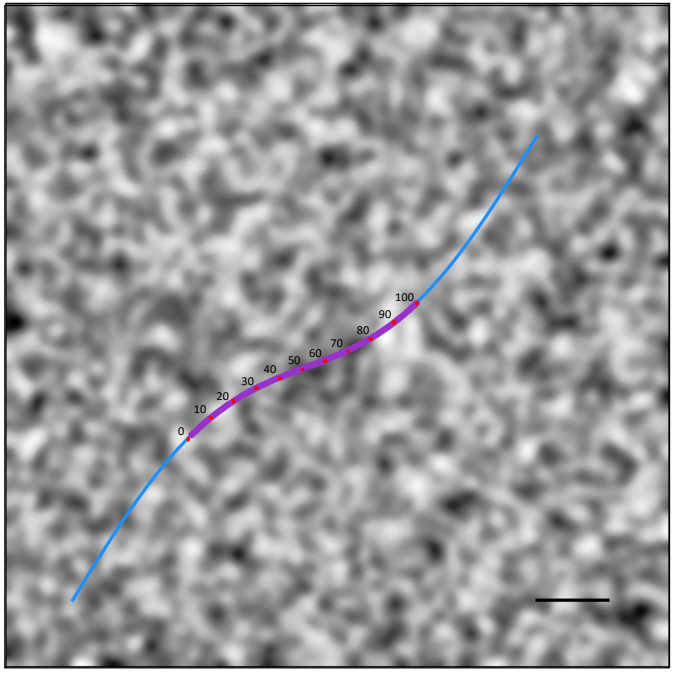


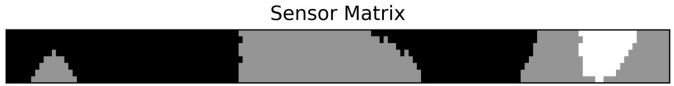


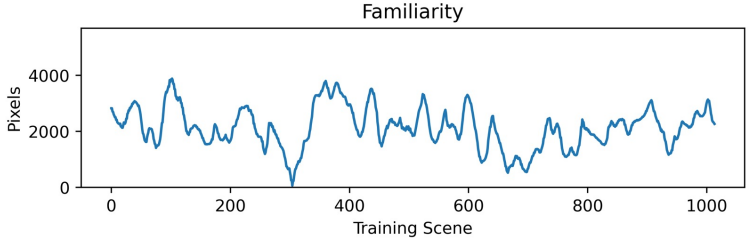
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

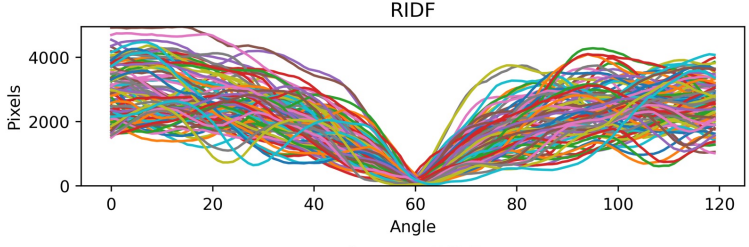
Navigation stats: RMSD error: 11664.36; RMSD/dist: 29.161; TD: 657; p90: 38; p50: 22; complete: 0

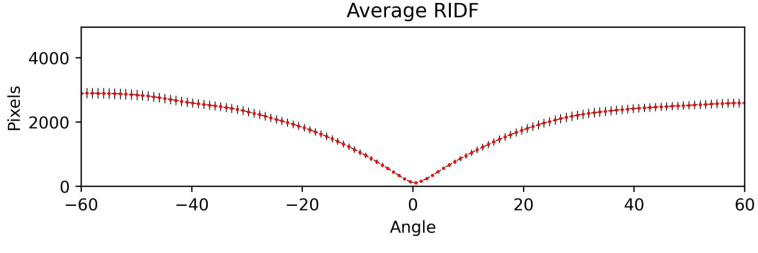
100%





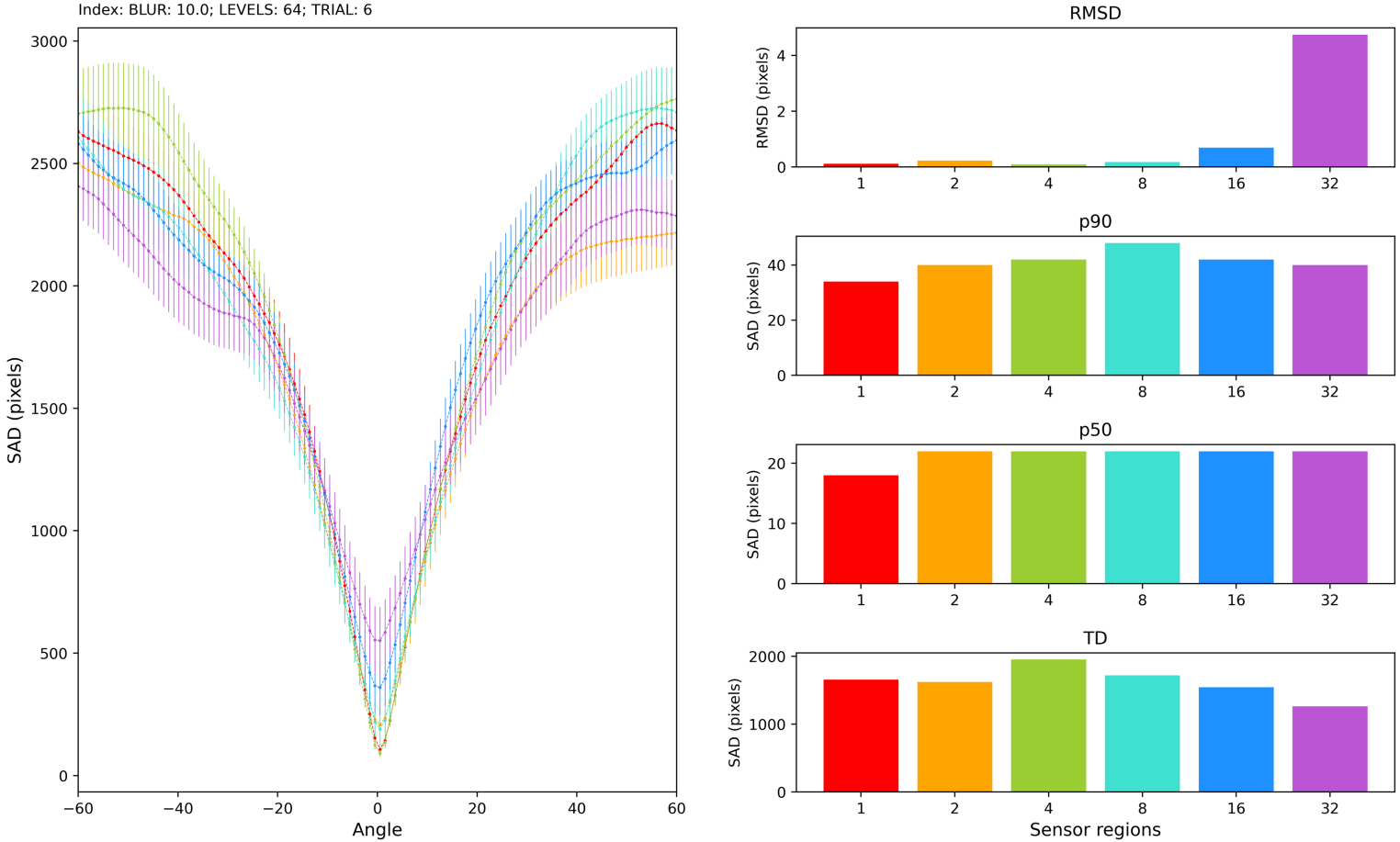




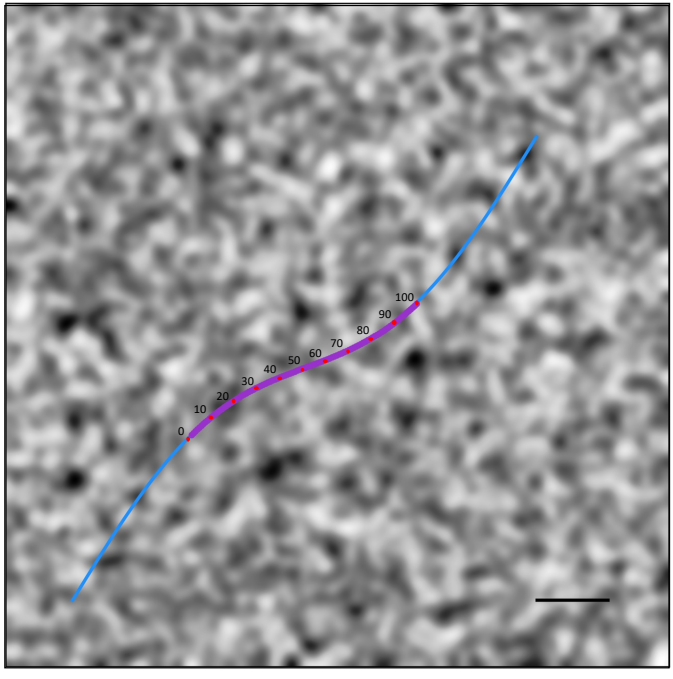


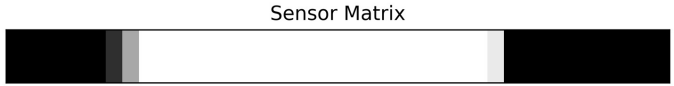
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

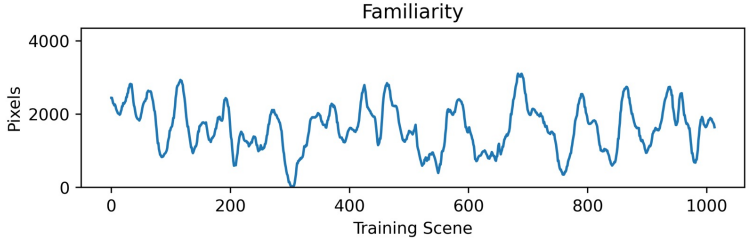
Navigation stats: RMSD error: 34.67; RMSD/dist: 0.087; TD: 2035; p90: 44; p50: 22; complete: 0

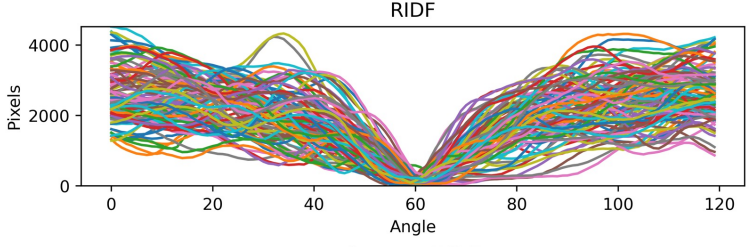

Index: BLUR: 10.0; LEVELS: 64; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

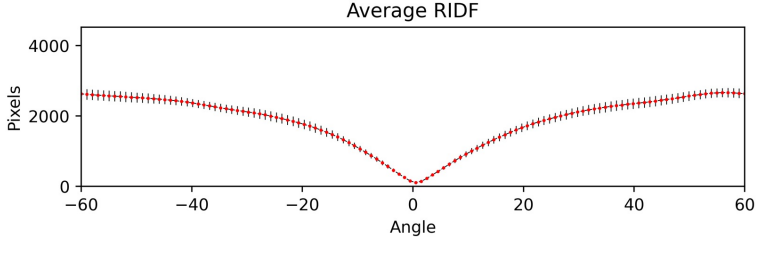
100%







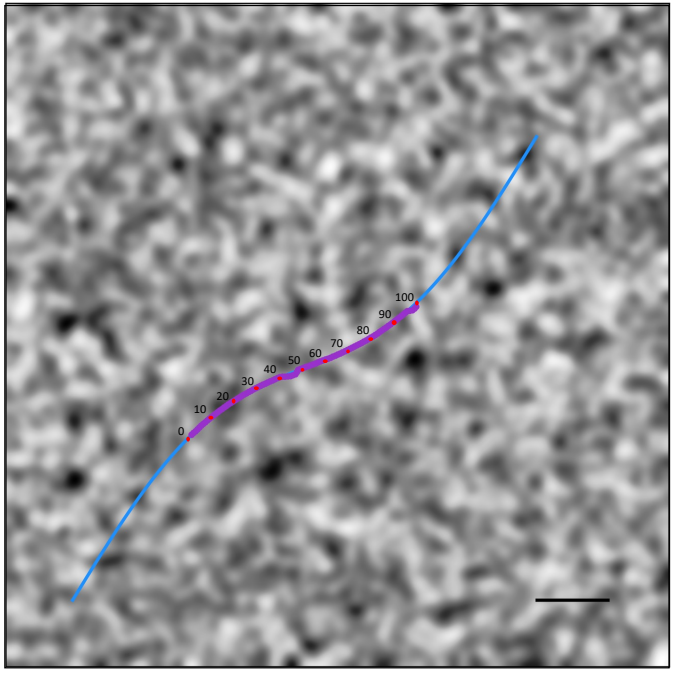


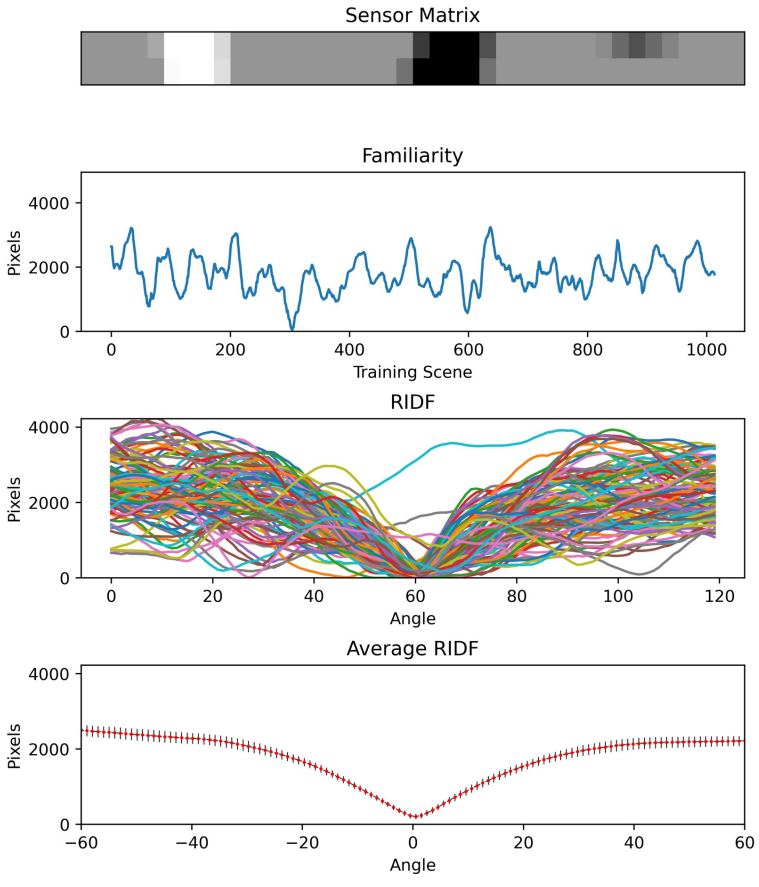


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 44.97; RMSD/dist: 0.112; TD: 1657; p90: 34; p50: 18; complete: 0

90%

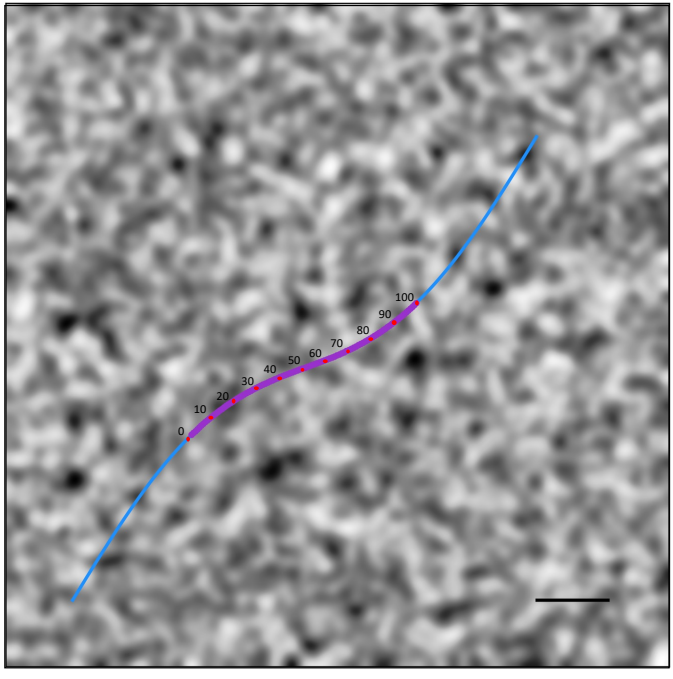


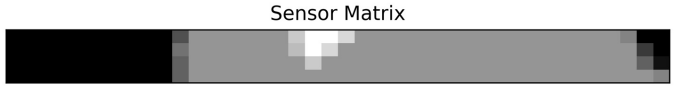


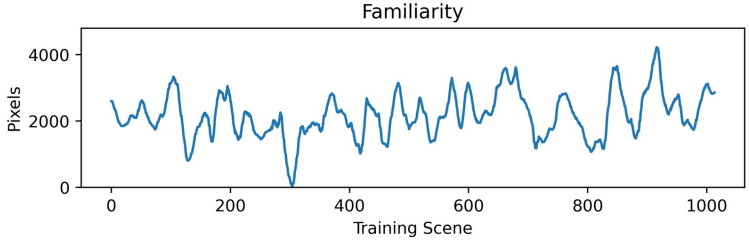
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

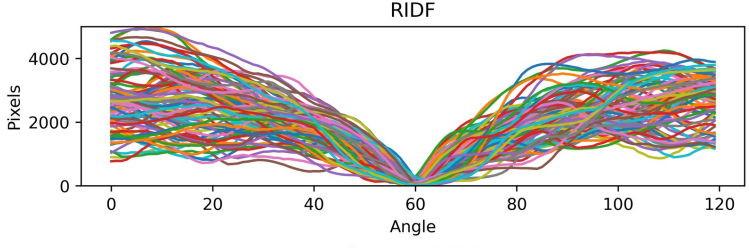
Navigation stats: RMSD error: 89.59; RMSD/dist: 0.224; TD: 1623; p90: 40; p50: 22; complete: 0

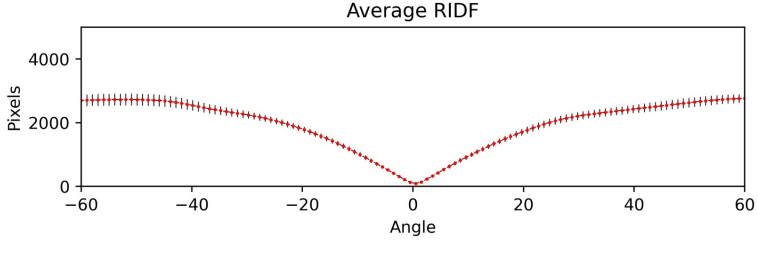
100%







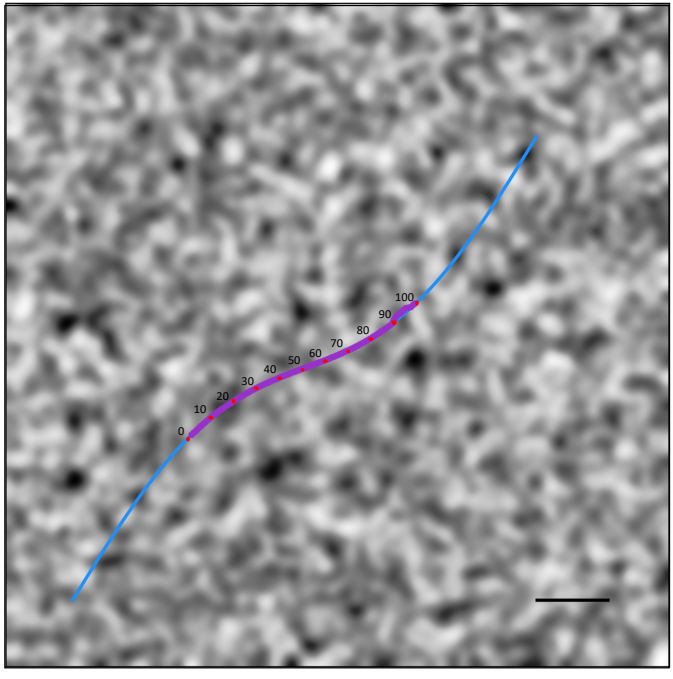


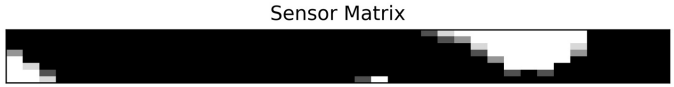


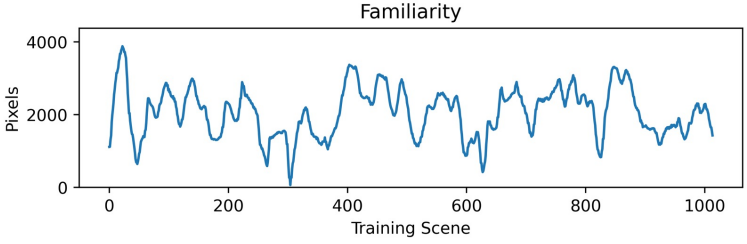
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

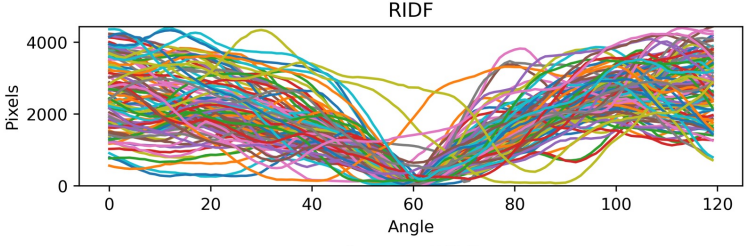
Navigation stats: RMSD error: 36.16; RMSD/dist: 0.090; TD: 1953; p90: 42; p50: 22; complete: 0

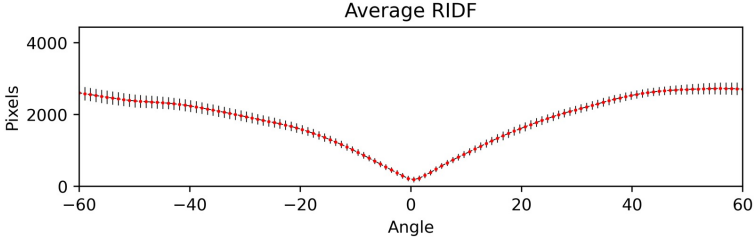
90%







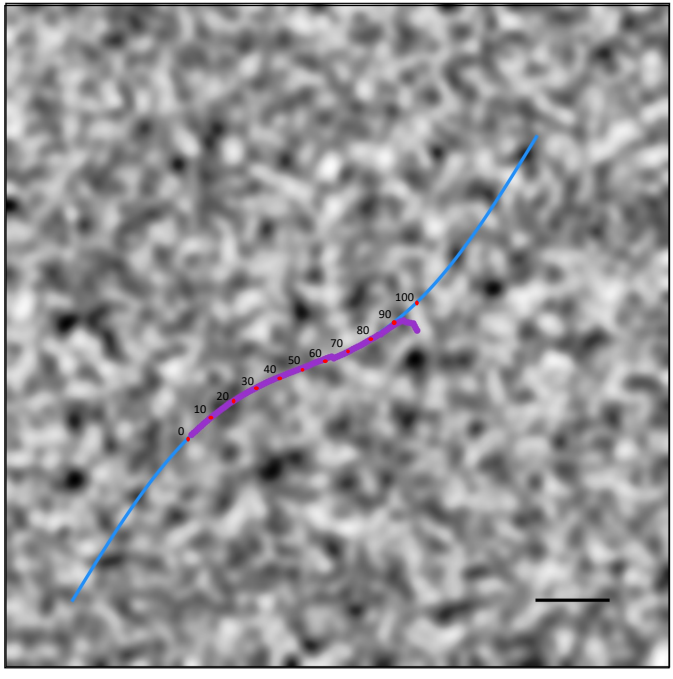


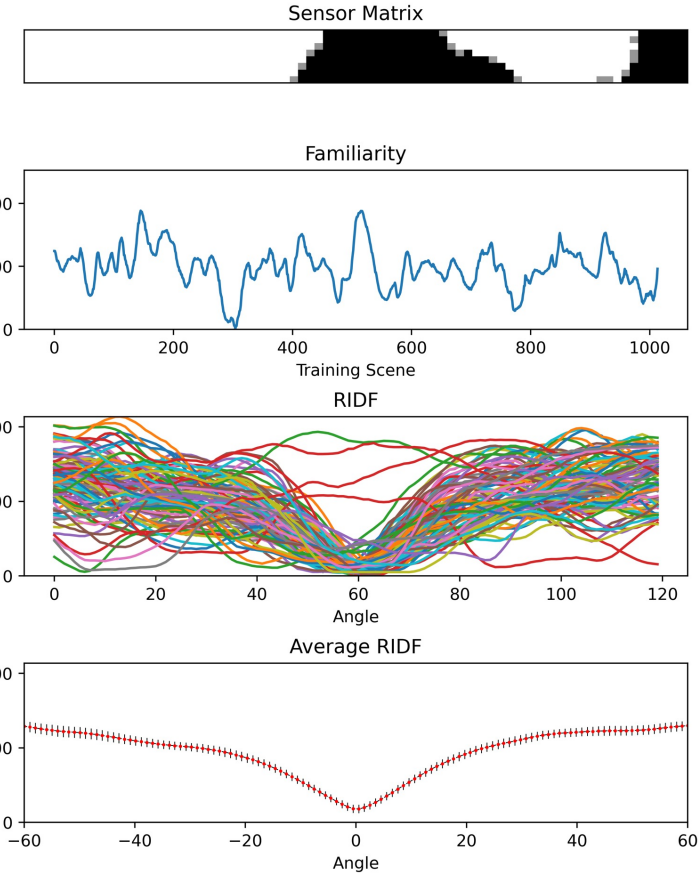


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 68.65; RMSD/dist: 0.172; TD: 1721; p90: 48; p50: 22; complete: 0

80%

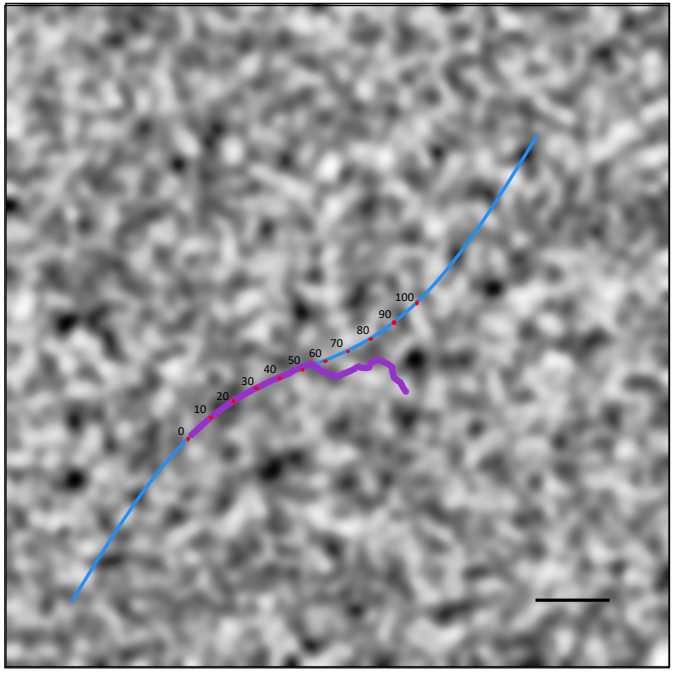


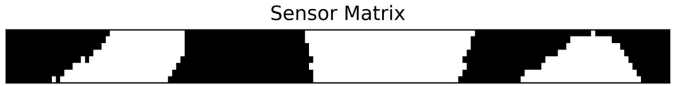


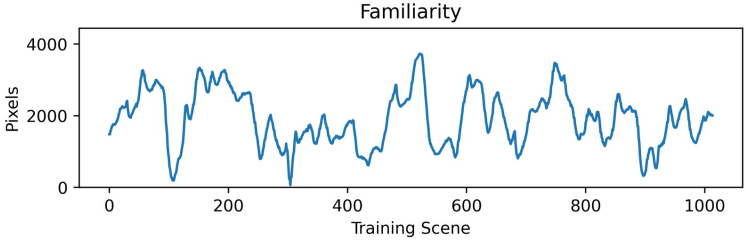
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

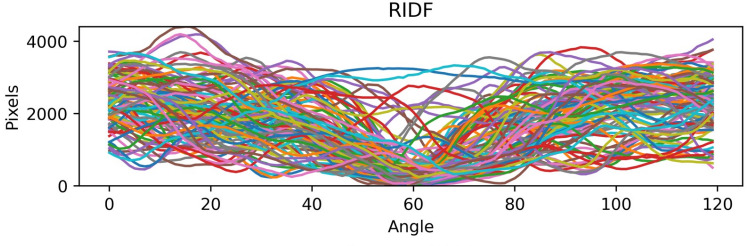
Navigation stats: RMSD error: 275.43; RMSD/dist: 0.689; TD: 1545; p90: 42; p50: 22; complete: 0

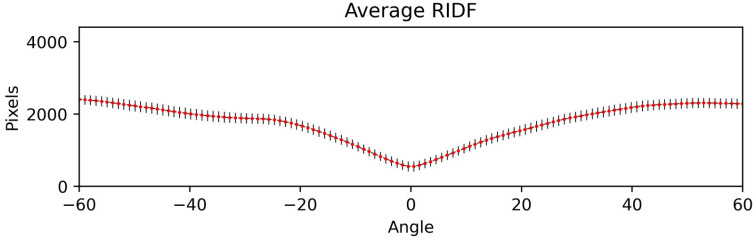
50%





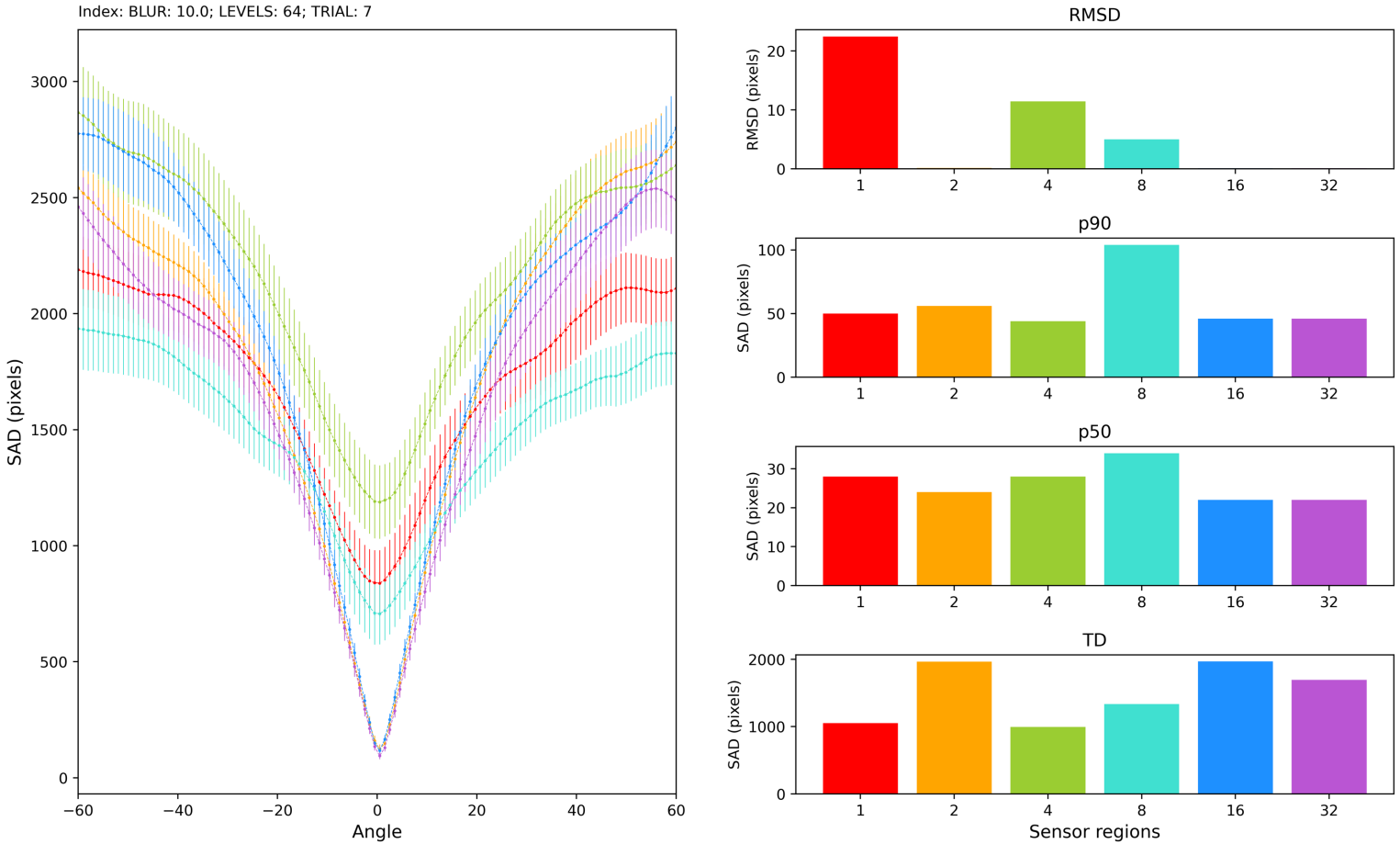




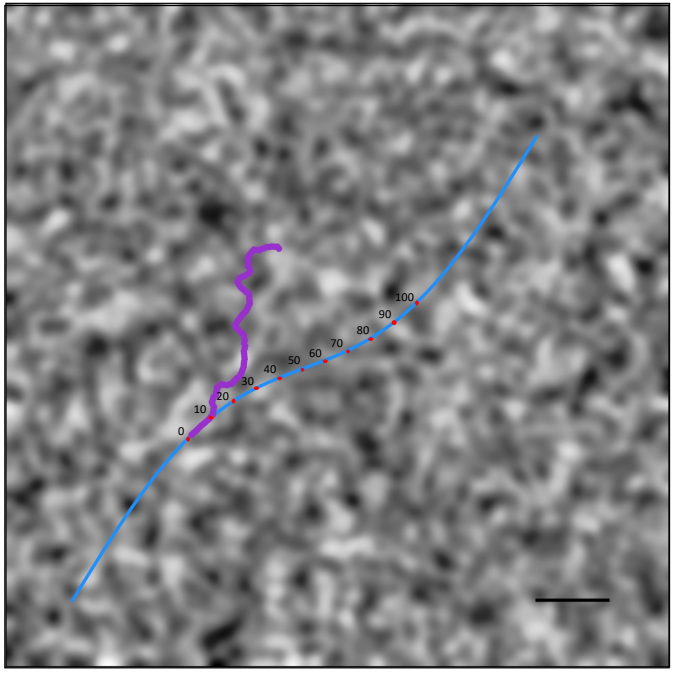


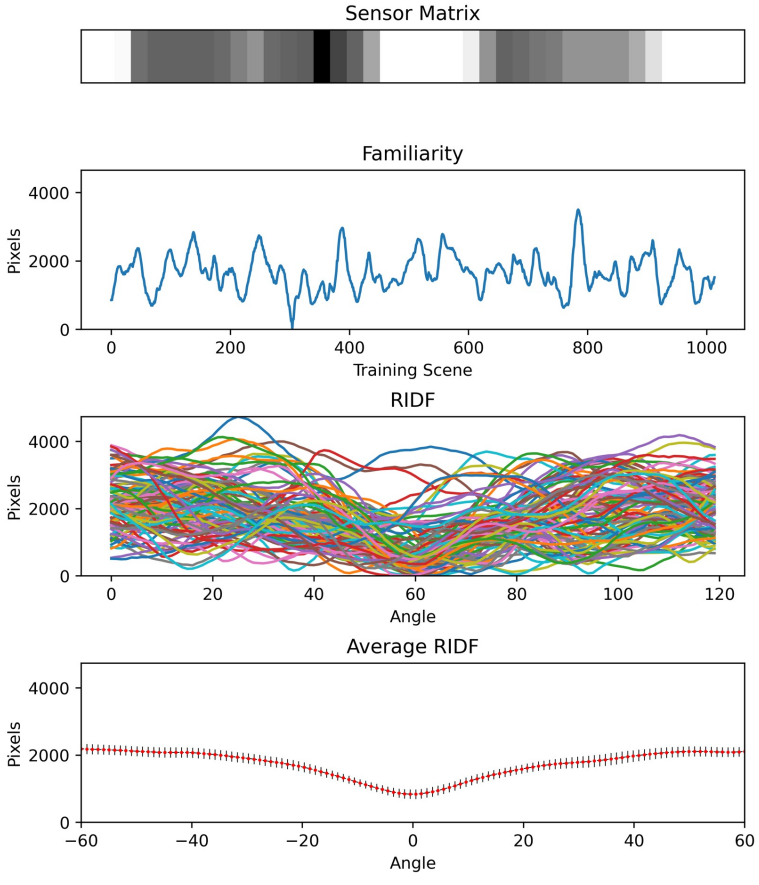
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1897.84; RMSD/dist: 4.745; TD: 1262; p90: 40; p50: 22; complete: 0


Index: BLUR: 10.0; LEVELS: 64; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

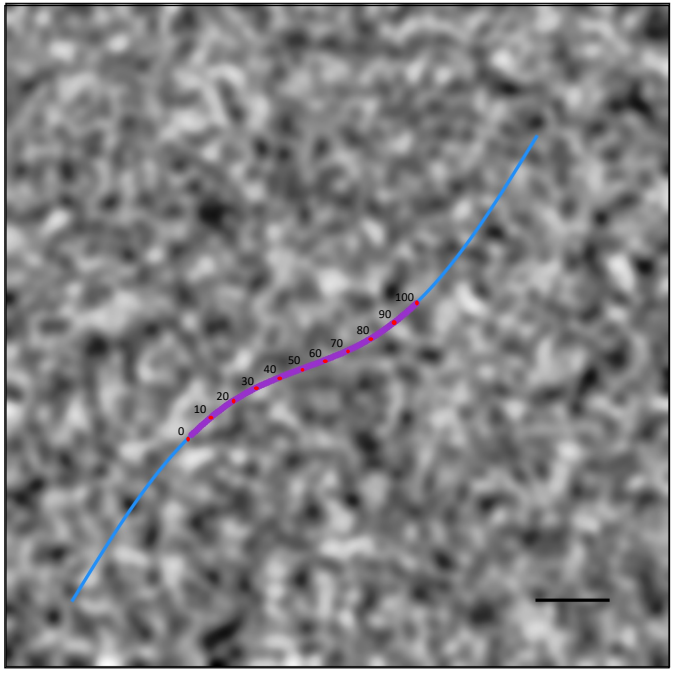


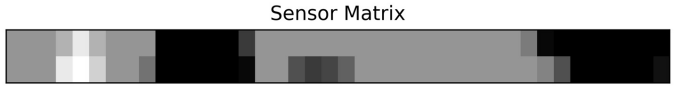


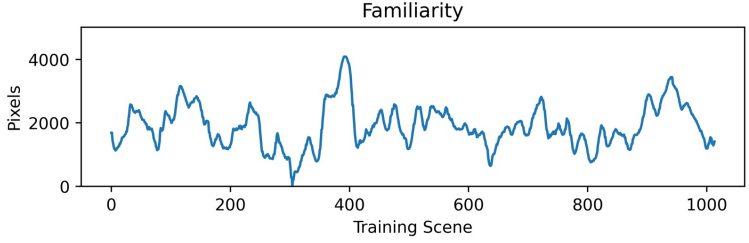
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

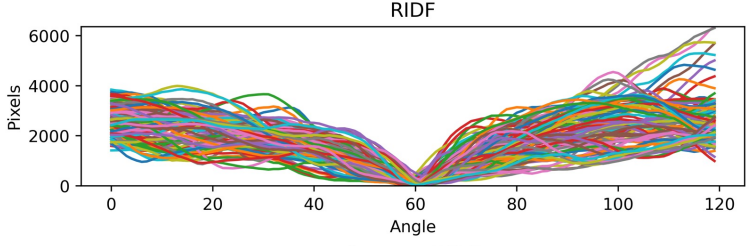
Navigation stats: RMSD error: 8985.44; RMSD/dist: 22.464; TD: 1050; p90: 50; p50: 28; complete: 0

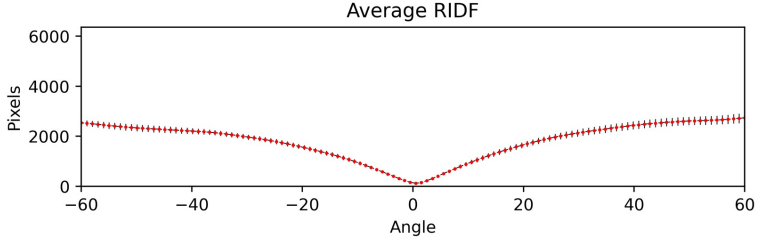
100%







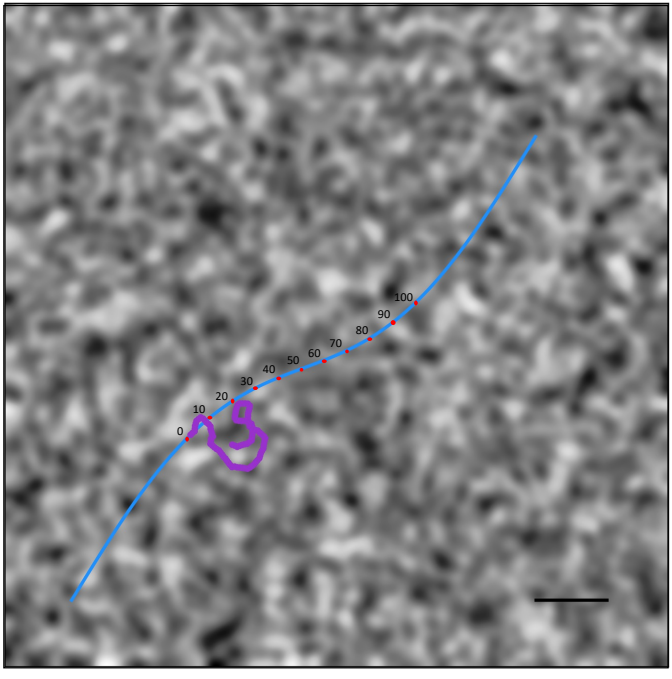


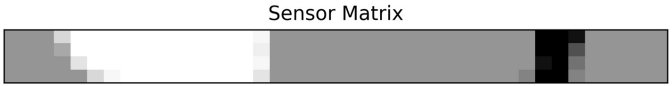


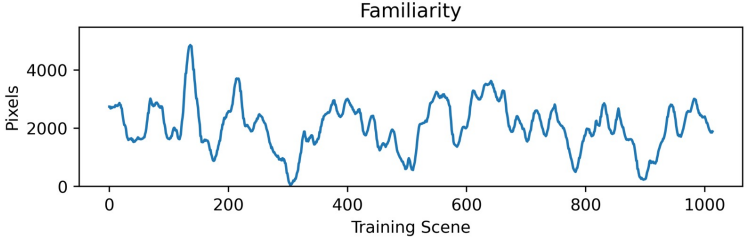
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

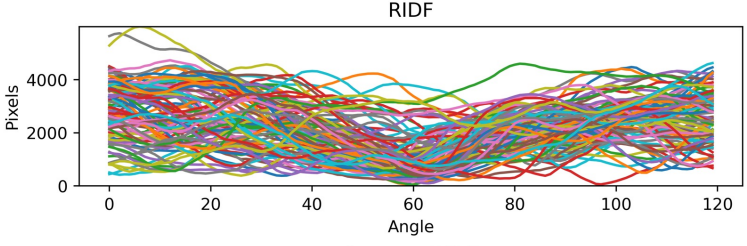
Navigation stats: RMSD error: 54.08; RMSD/dist: 0.135; TD: 1965; p90: 56; p50: 24; complete: 0

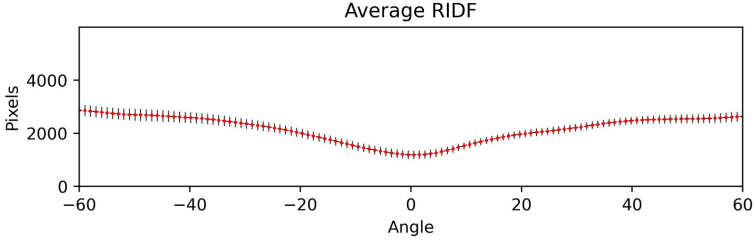
0%







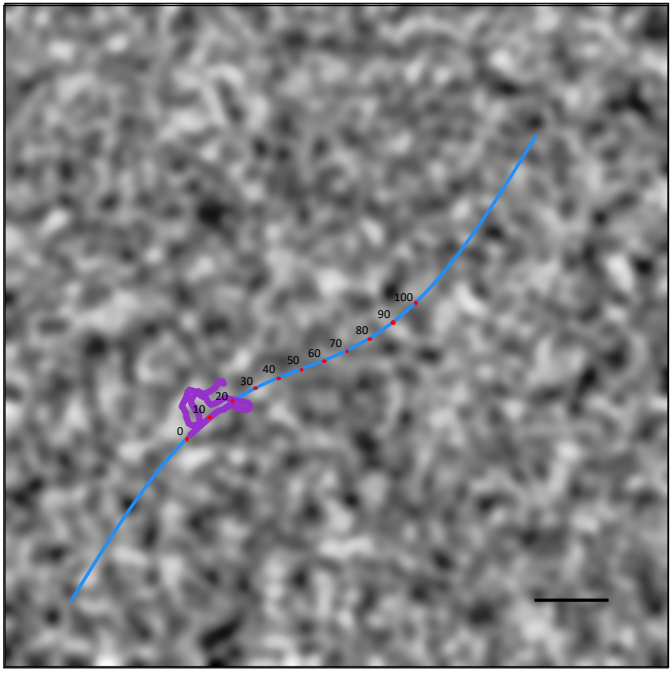


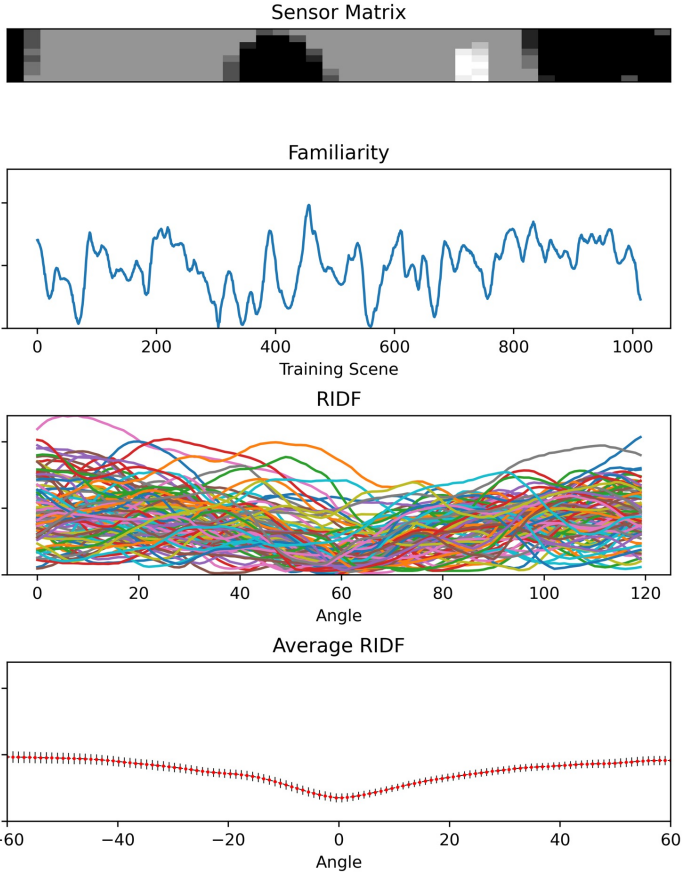


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 4573.94; RMSD/dist: 11.435; TD: 994; p90: 44; p50: 28; complete: 0

10%

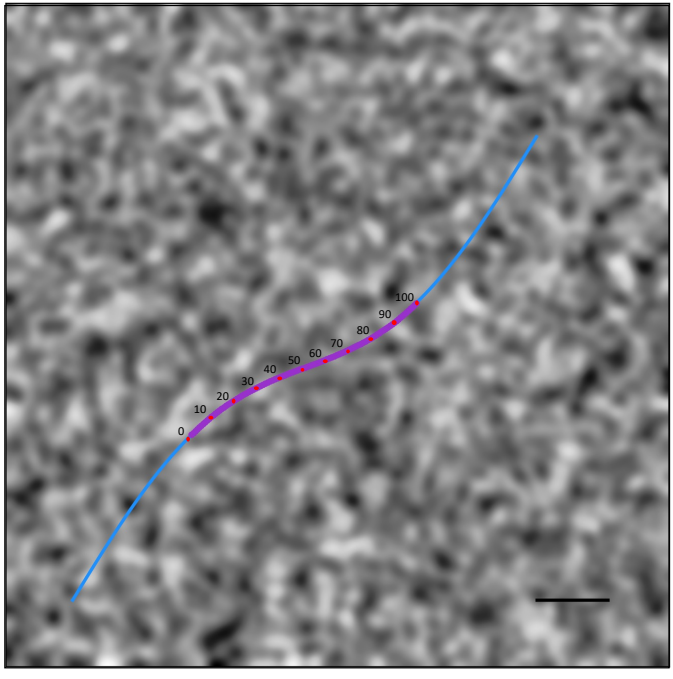


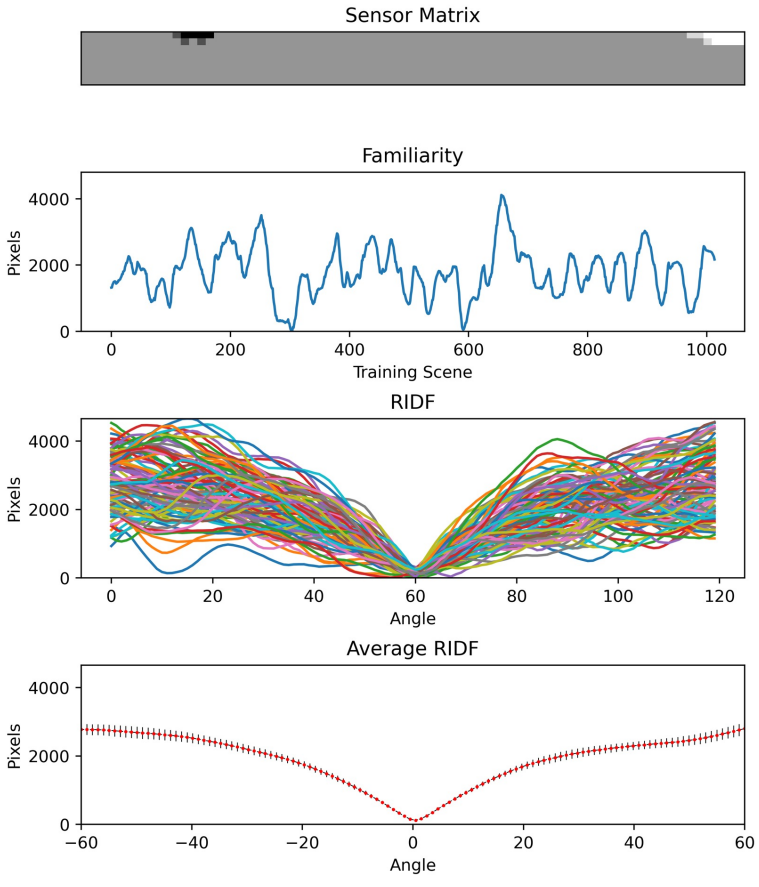


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2002.66; RMSD/dist: 5.007; TD: 1335; p90: 104; p50: 34; complete: 0

100%

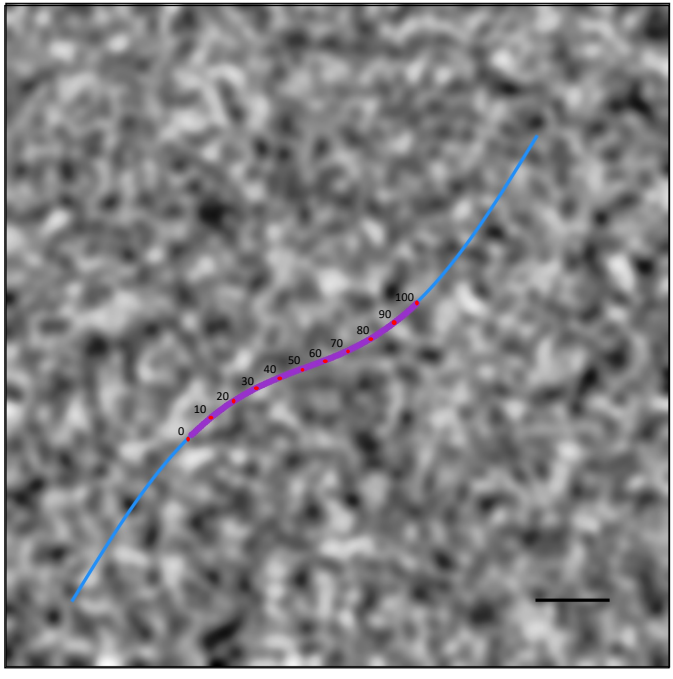


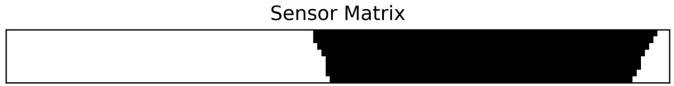


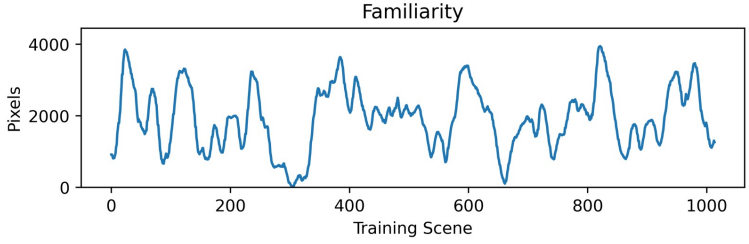
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

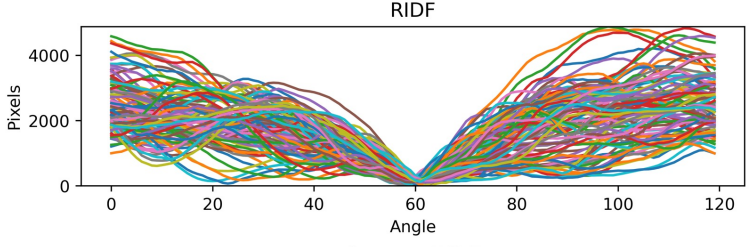
Navigation stats: RMSD error: 42.91; RMSD/dist: 0.107; TD: 1967; p90: 46; p50: 22; complete: 0

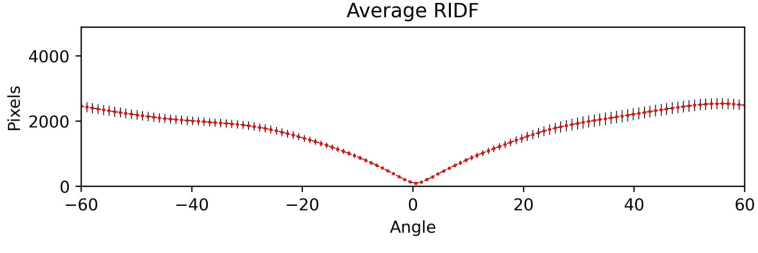
100%





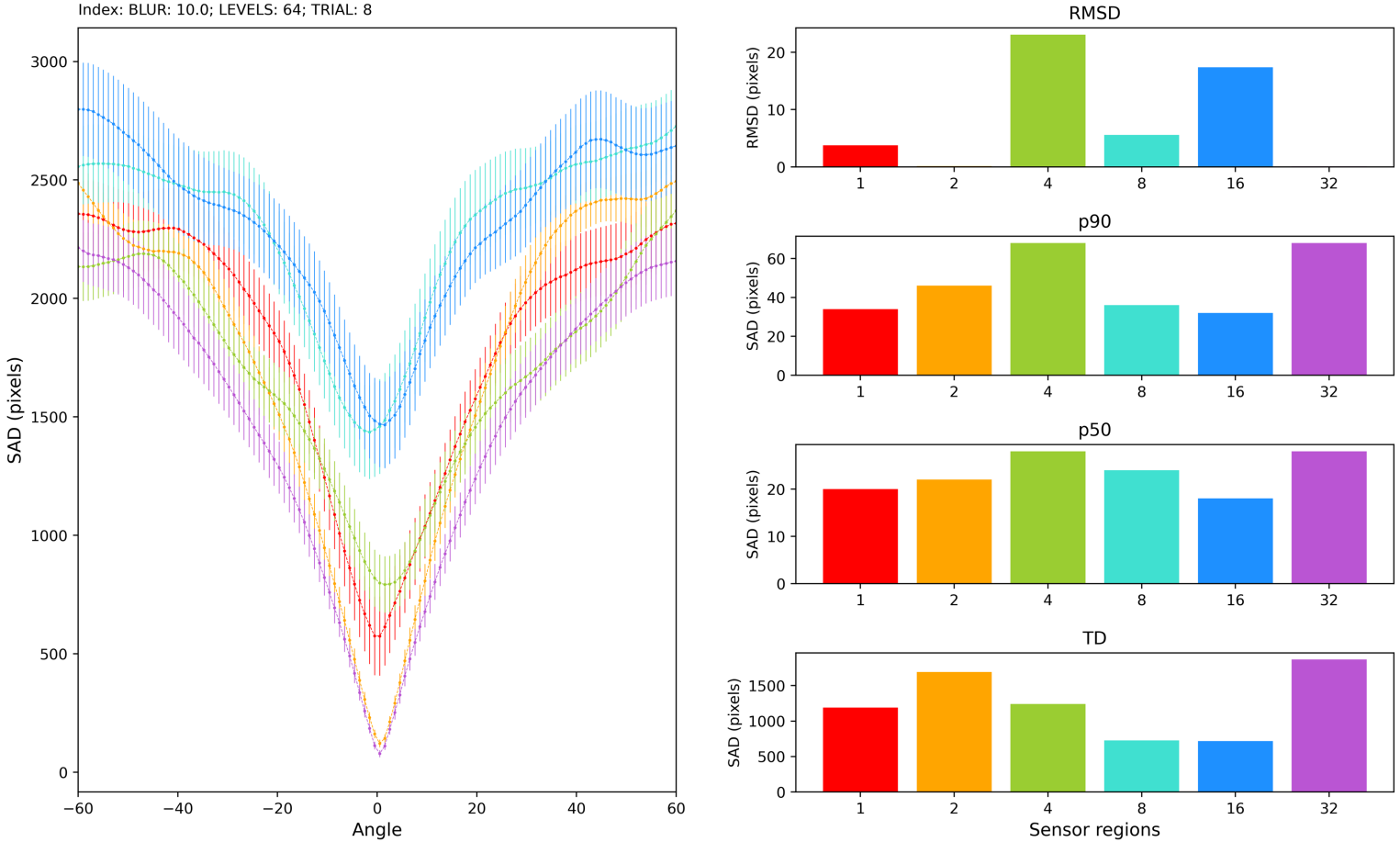




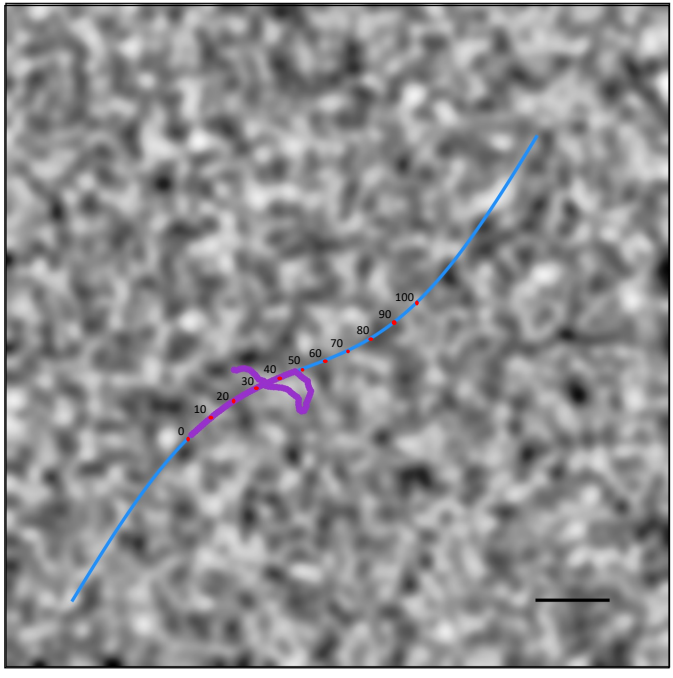


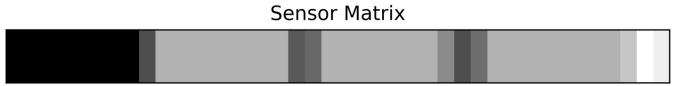
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

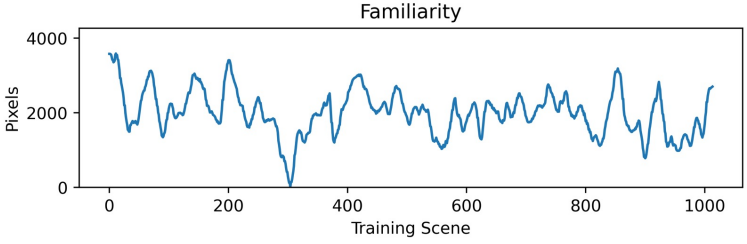
Navigation stats: RMSD error: 38.91; RMSD/dist: 0.097; TD: 1695; p90: 46; p50: 22; complete: 0

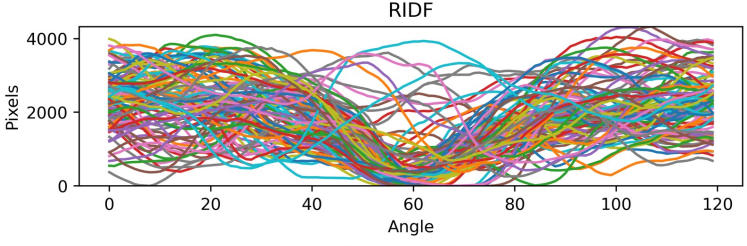

Index: BLUR: 10.0; LEVELS: 64; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

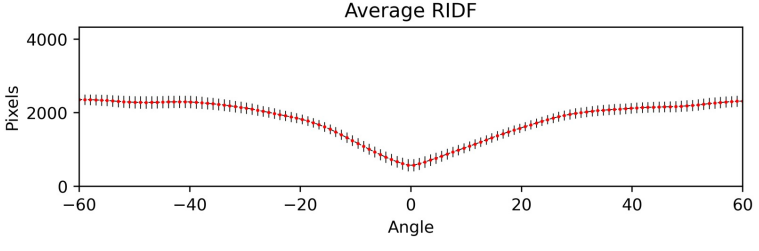
40%







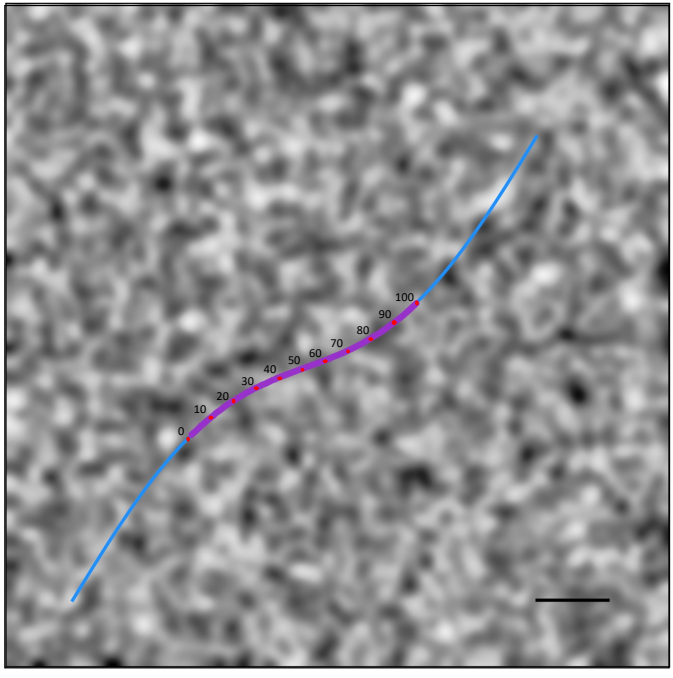


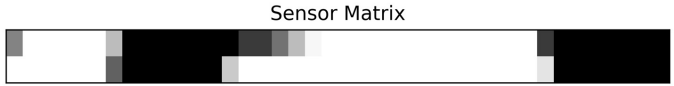


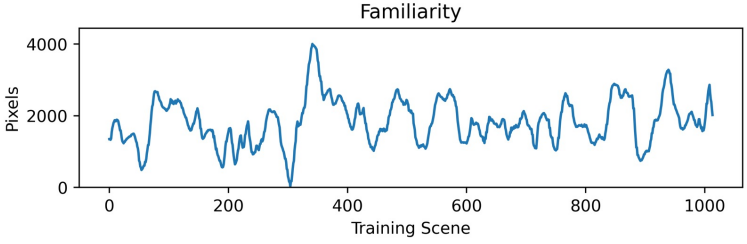
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

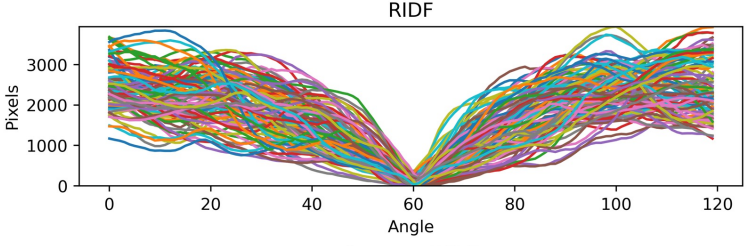
Navigation stats: RMSD error: 1502.23; RMSD/dist: 3.756; TD: 1191; p90: 34; p50: 20; complete: 0

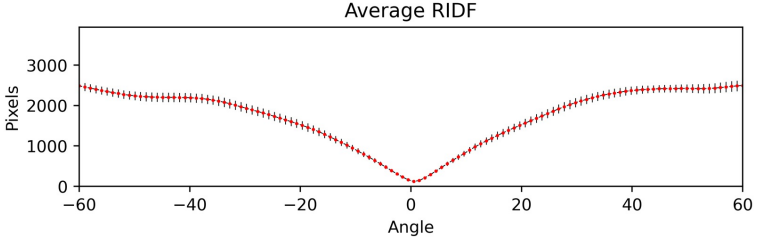
100%







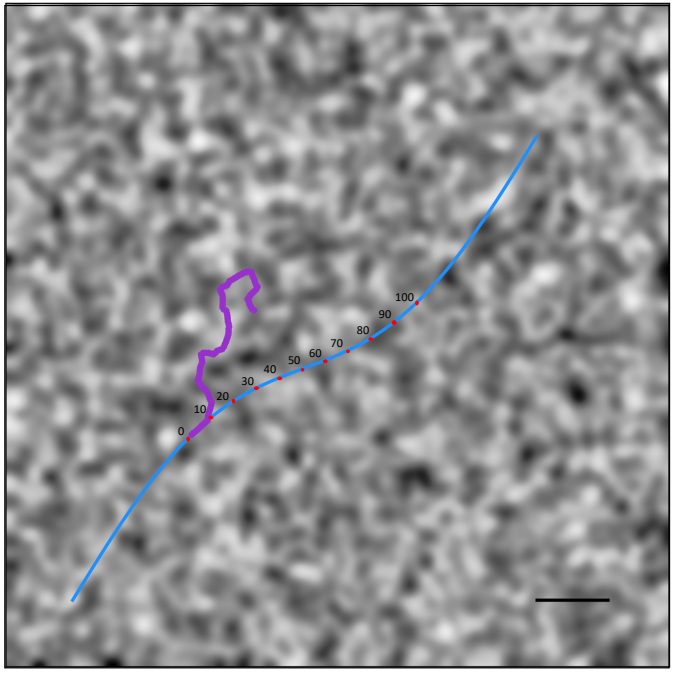


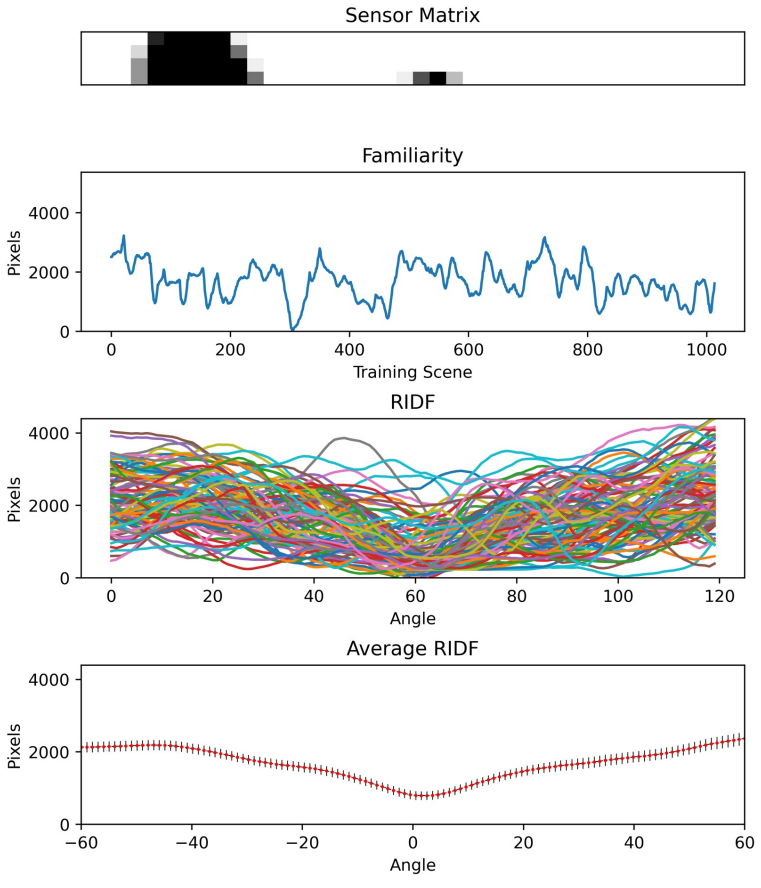


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 56.86; RMSD/dist: 0.142; TD: 1693; p90: 46; p50: 22; complete: 0

10%

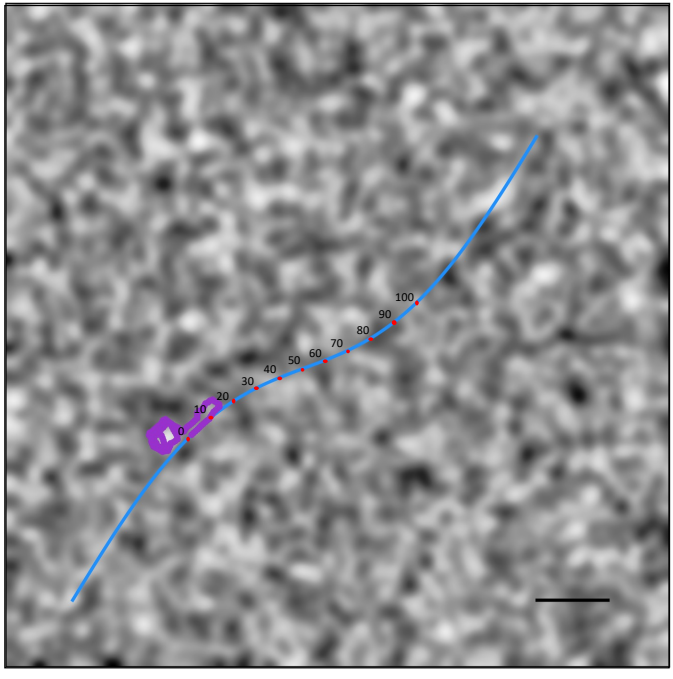


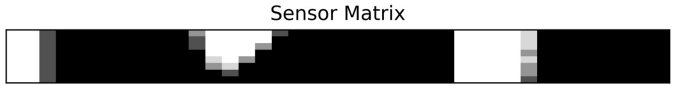


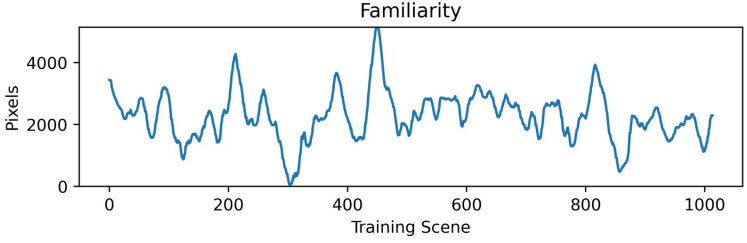
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

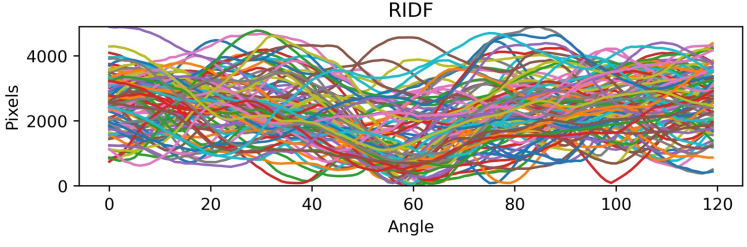
Navigation stats: RMSD error: 9238.91; RMSD/dist: 23.097; TD: 1240; p90: 68; p50: 28; complete: 0

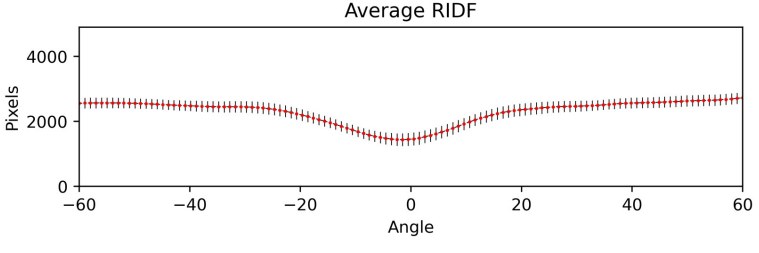
10%







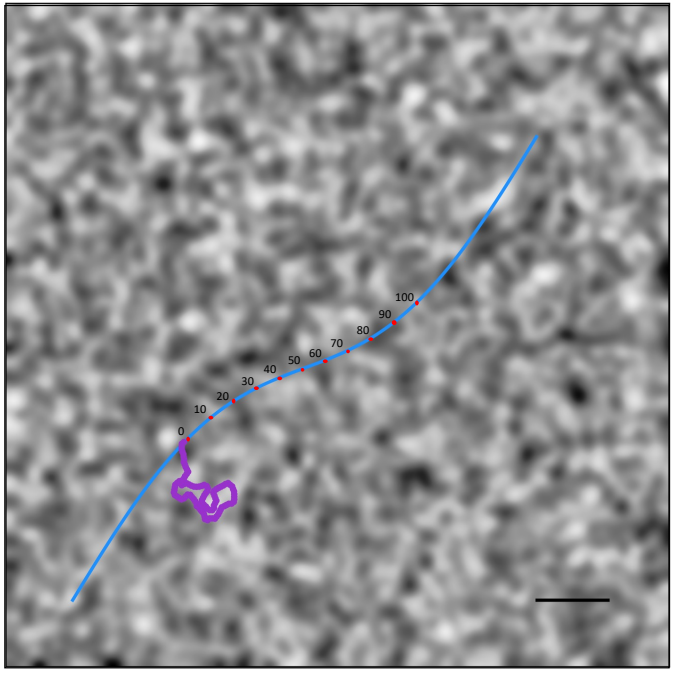


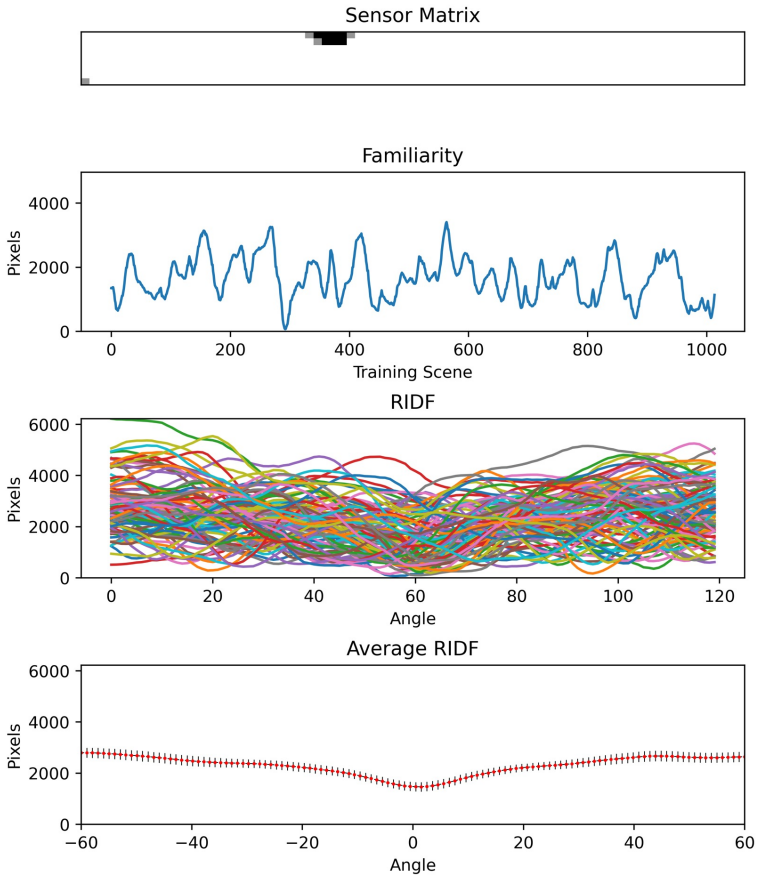


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2231.31; RMSD/dist: 5.578; TD: 726; p90: 36; p50: 24; complete: 0

100%

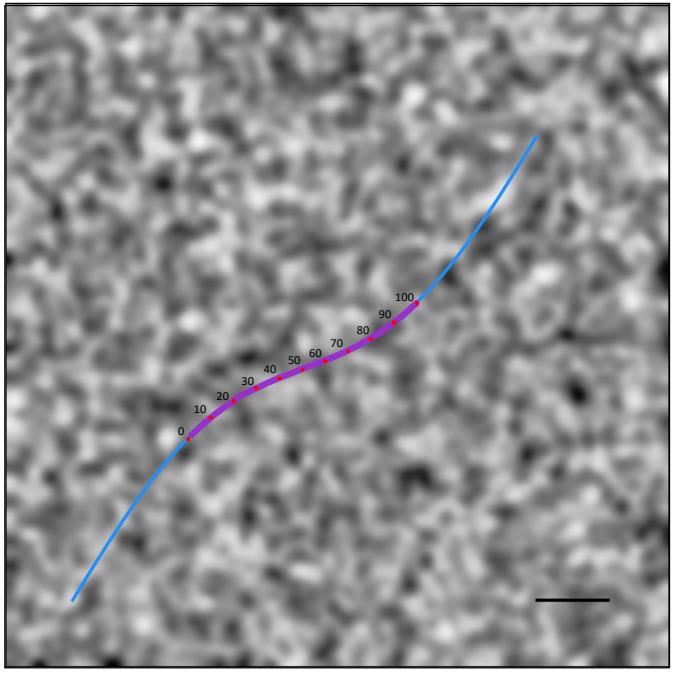


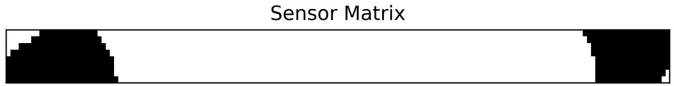


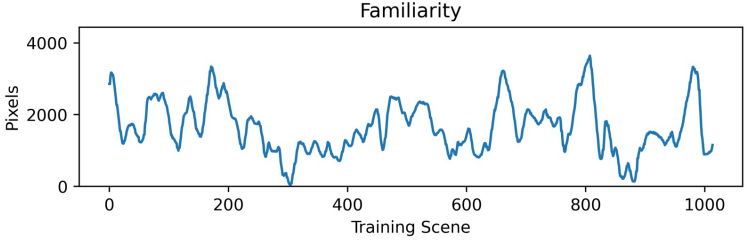
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

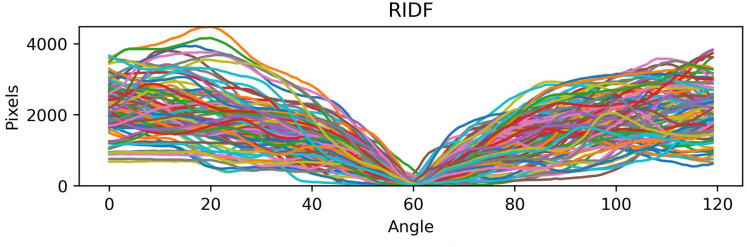
Navigation stats: RMSD error: 6953.47; RMSD/dist: 17.384; TD: 718; p90: 32; p50: 18; complete: 0

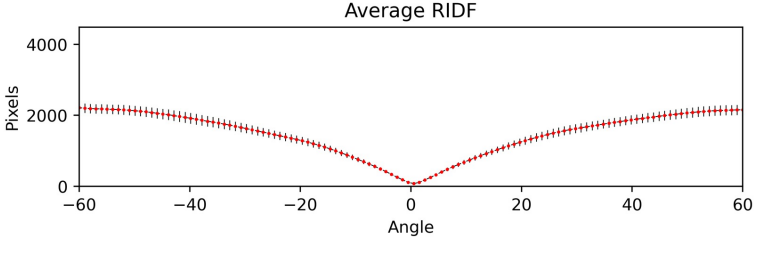
100%





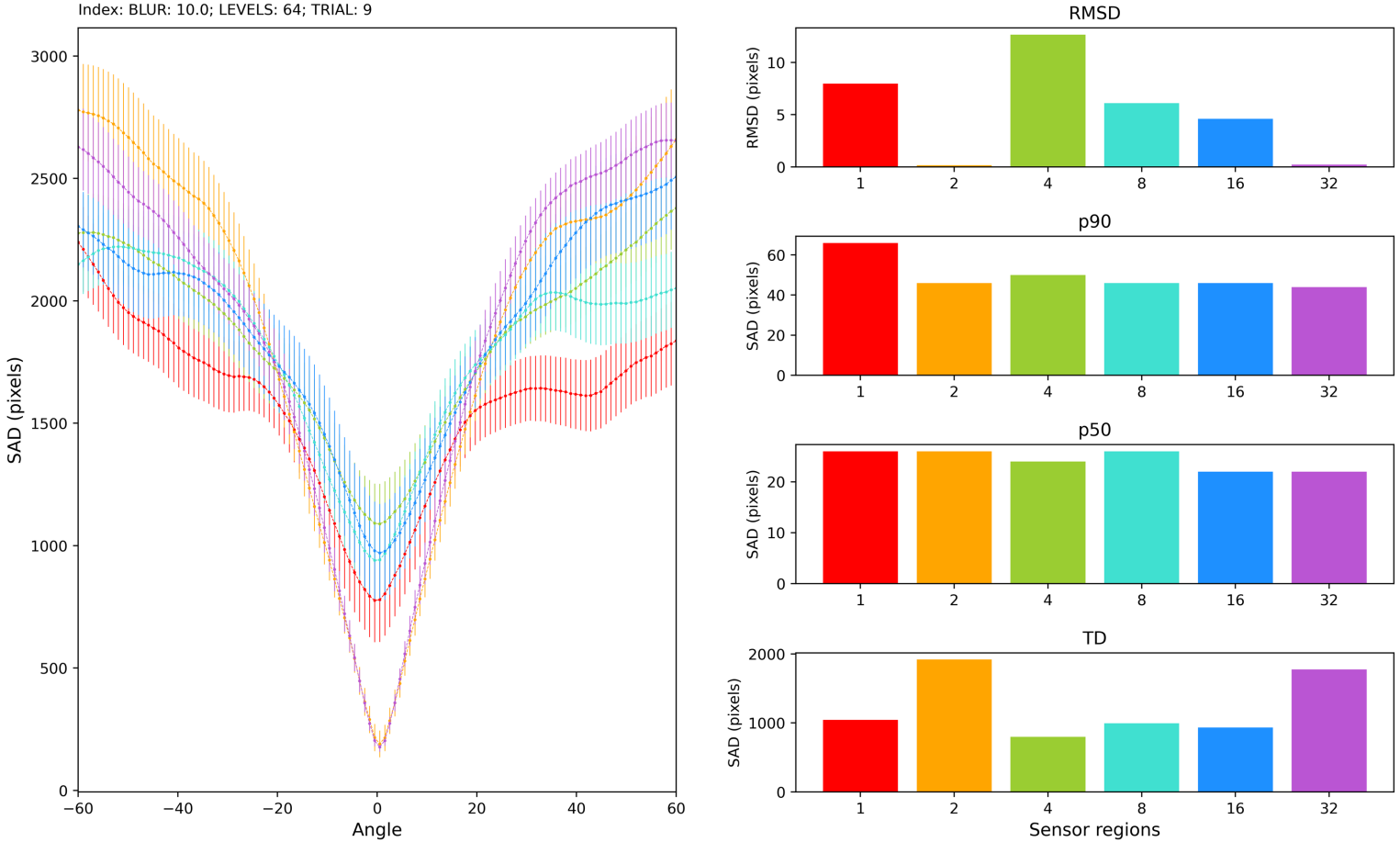




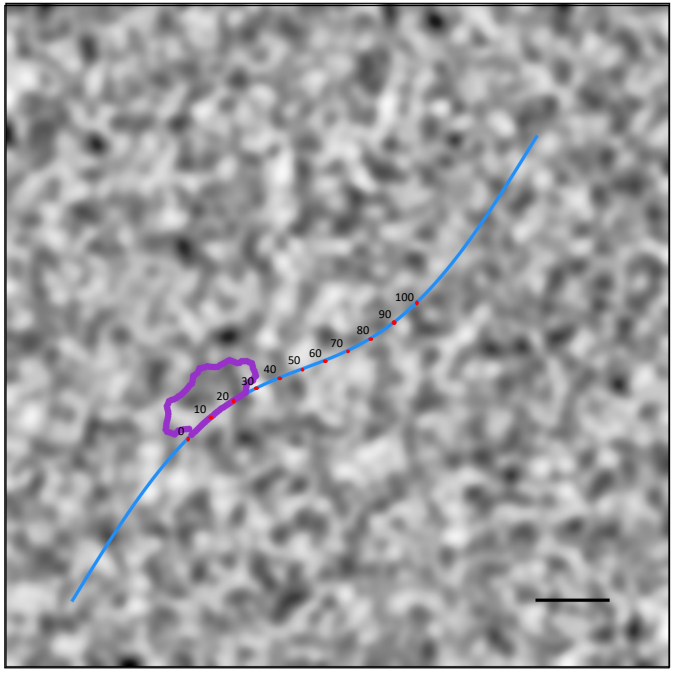


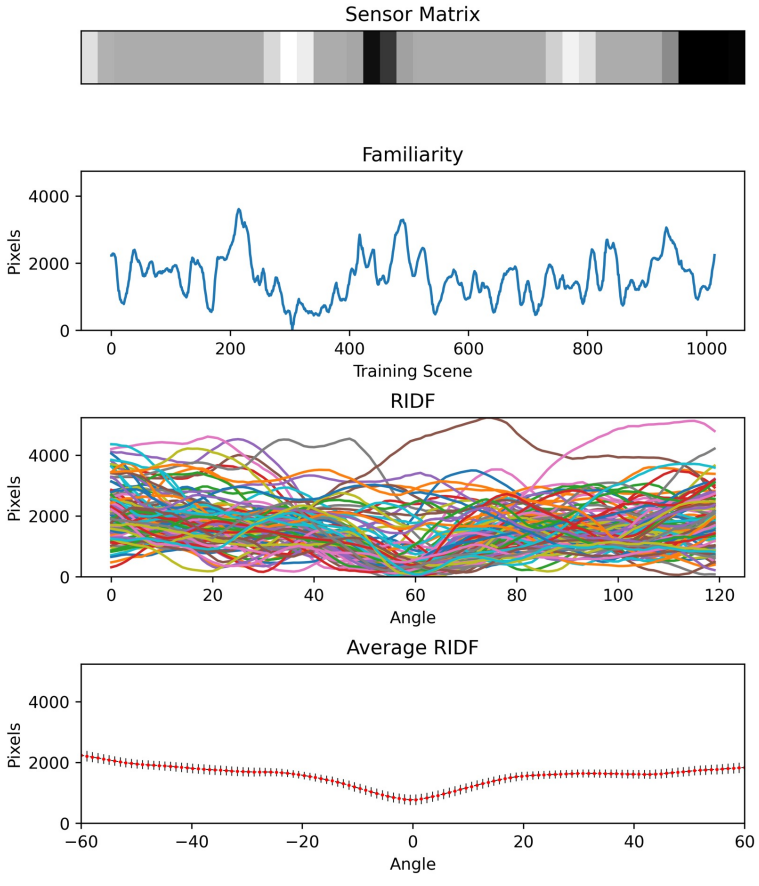
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 44.15; RMSD/dist: 0.110; TD: 1868; p90: 68; p50: 28; complete: 0


Index: BLUR: 10.0; LEVELS: 64; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

20%

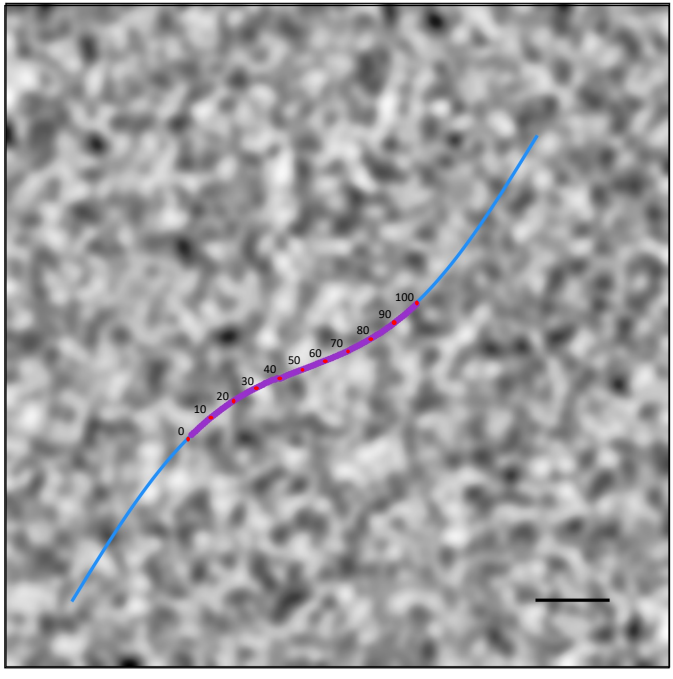


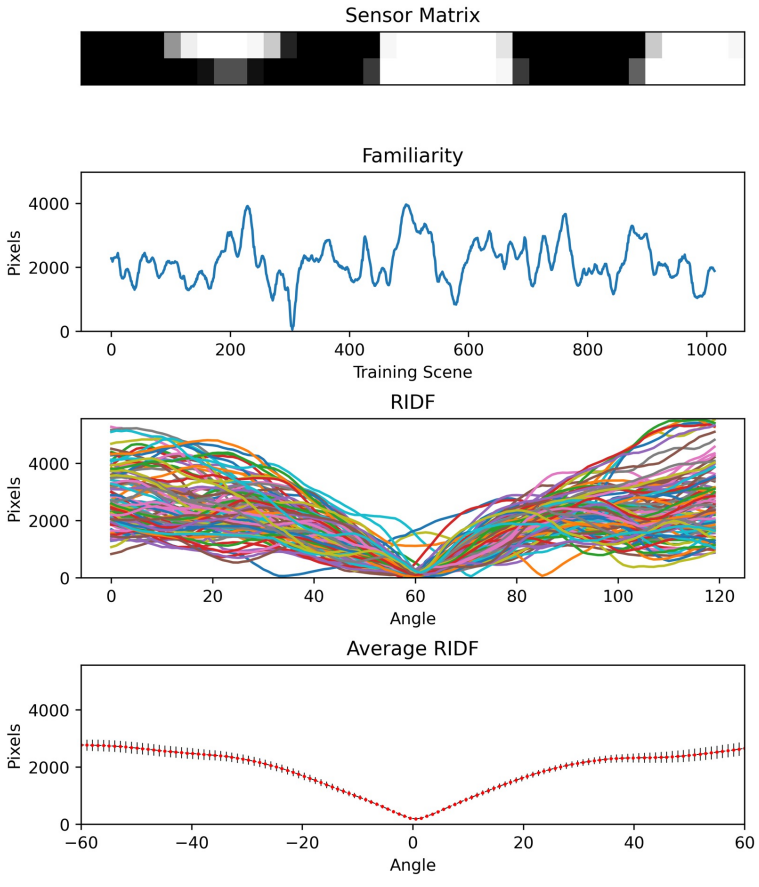


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3188.56; RMSD/dist: 7.971; TD: 1045; p90: 66; p50: 26; complete: 0

100%

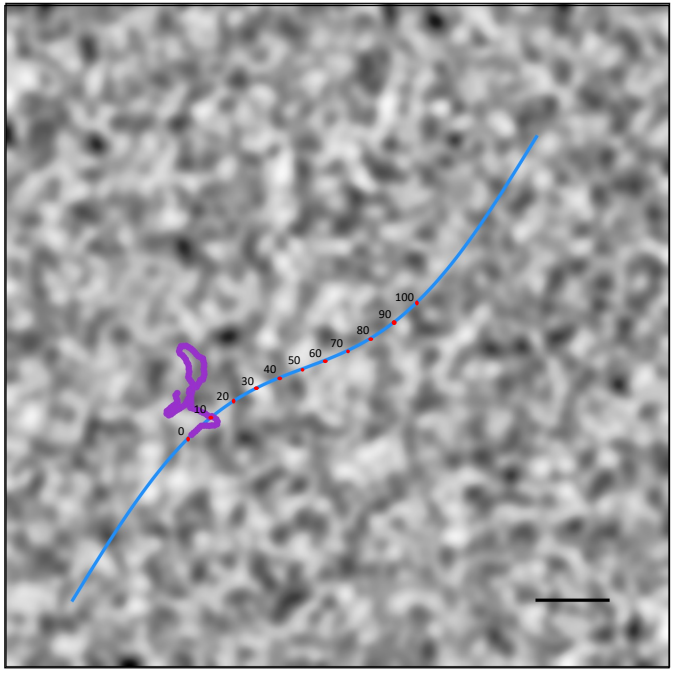


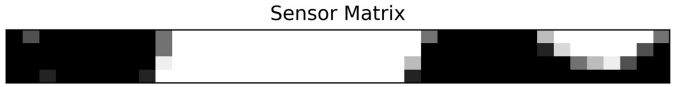


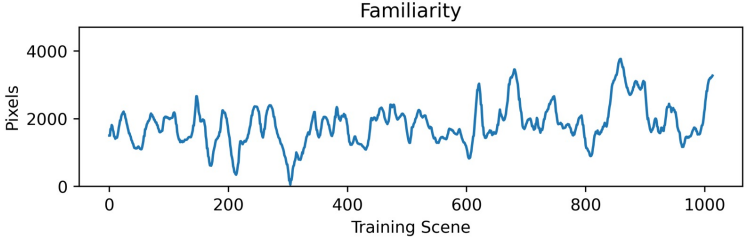
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

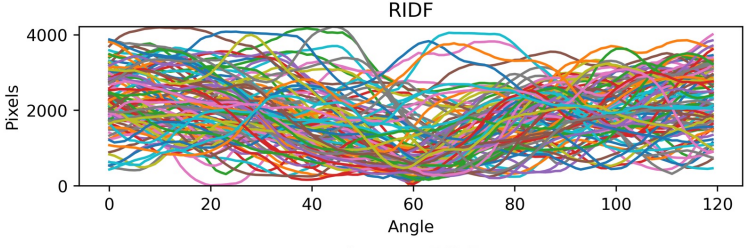
Navigation stats: RMSD error: 64.44; RMSD/dist: 0.161; TD: 1918; p90: 46; p50: 26; complete: 0

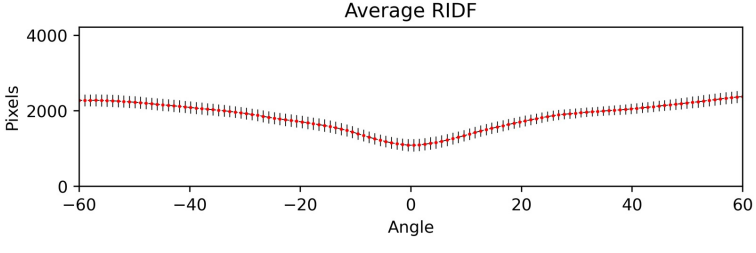
0%







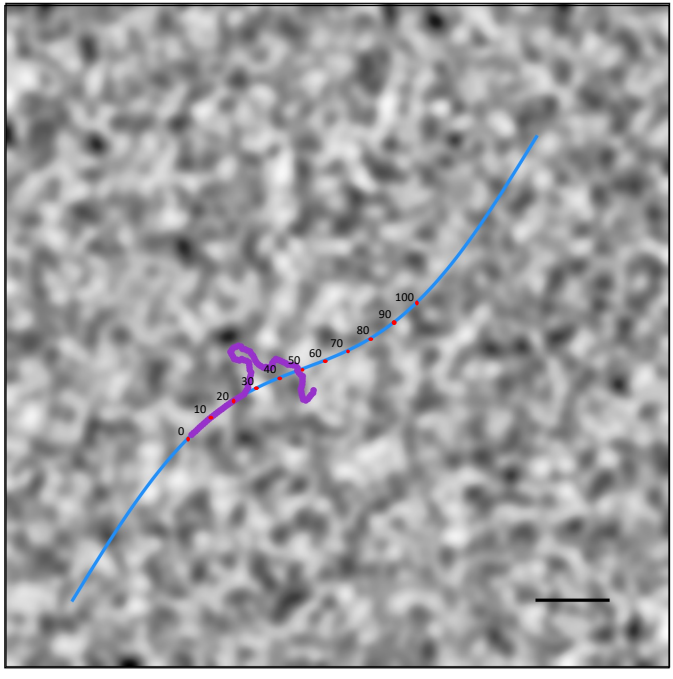


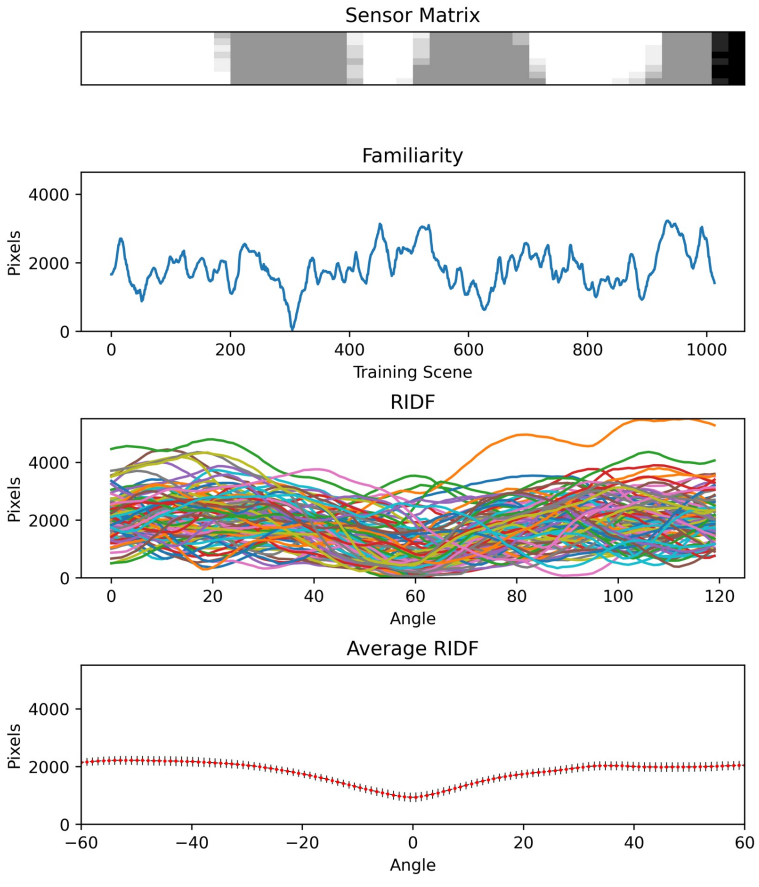


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 5069.21; RMSD/dist: 12.673; TD: 798; p90: 50; p50: 24; complete: 0

20%

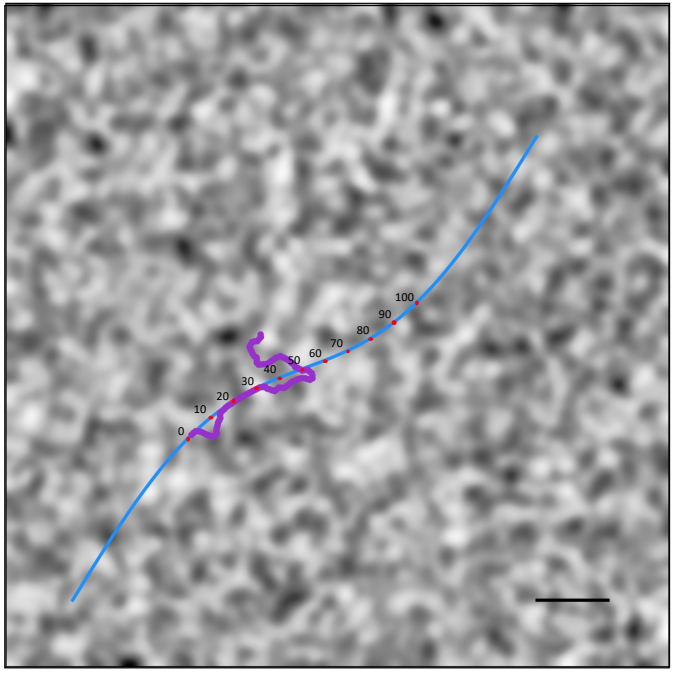


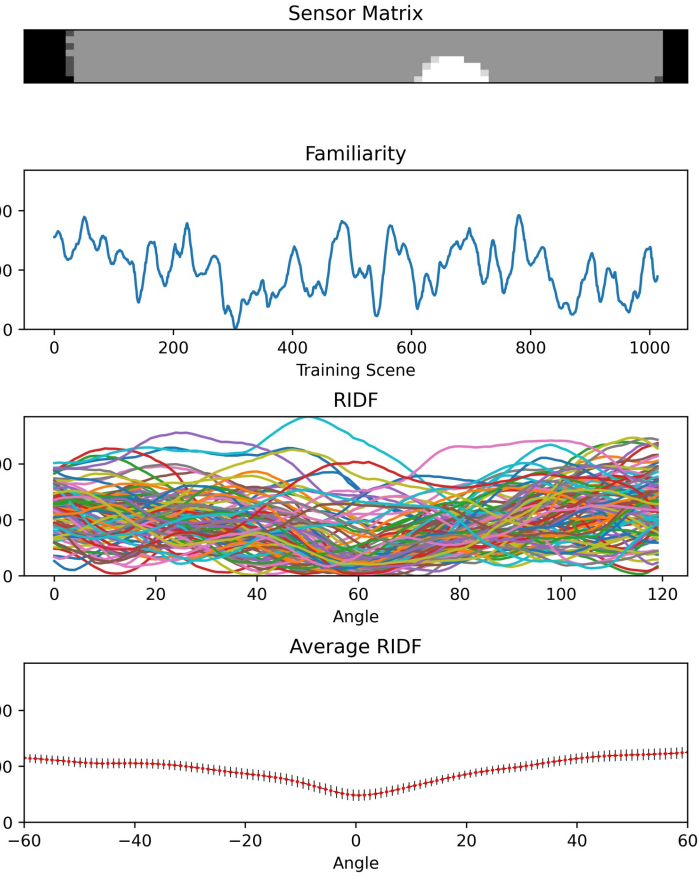


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2441.56; RMSD/dist: 6.104; TD: 995; p90: 46; p50: 26; complete: 0

20%

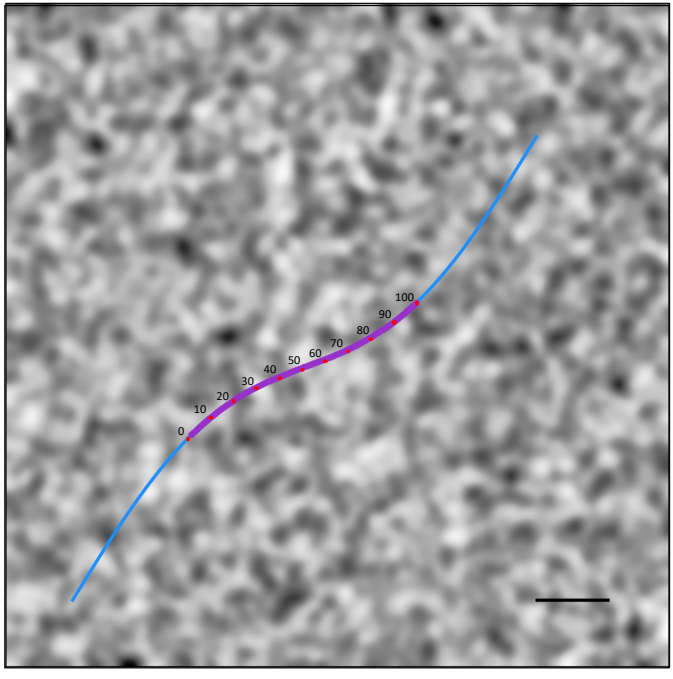


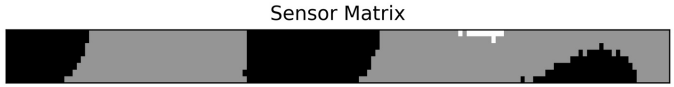


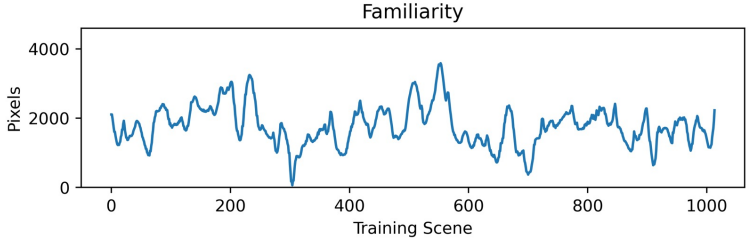
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

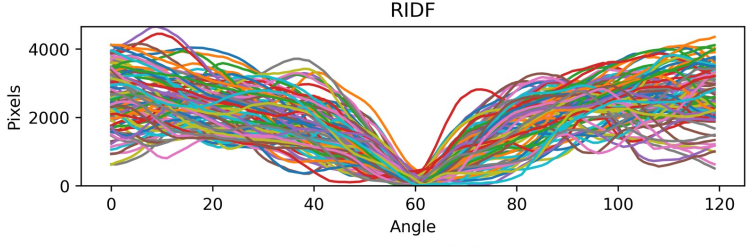
Navigation stats: RMSD error: 1843.57; RMSD/dist: 4.609; TD: 934; p90: 46; p50: 22; complete: 0

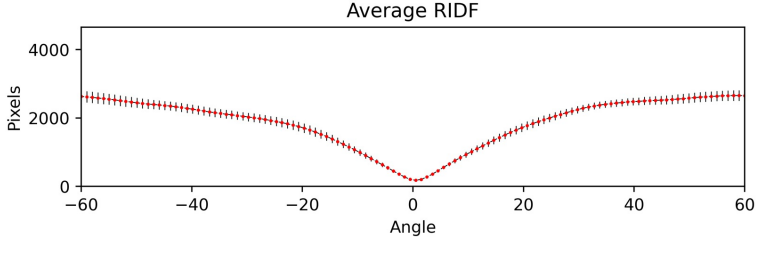
100%





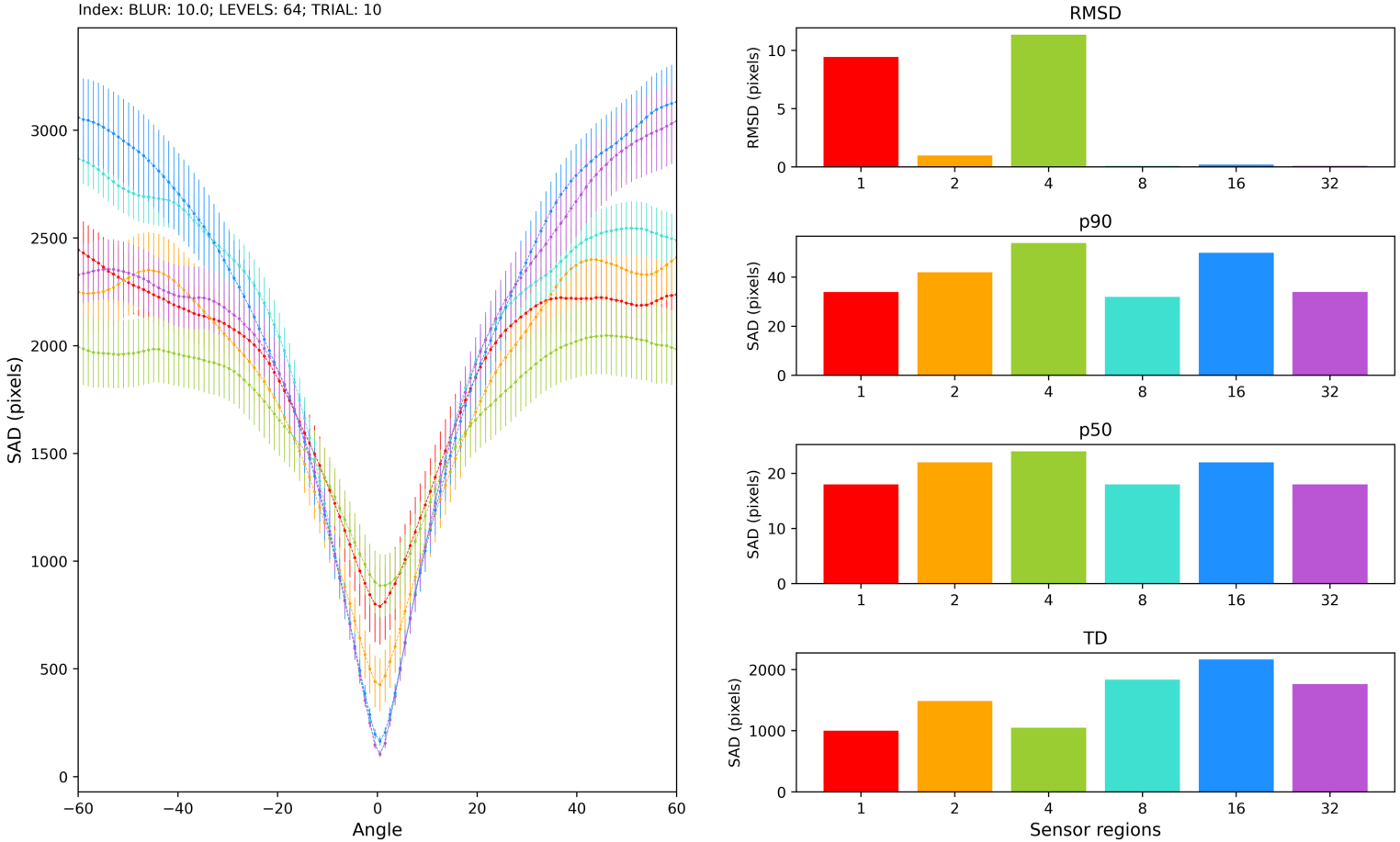




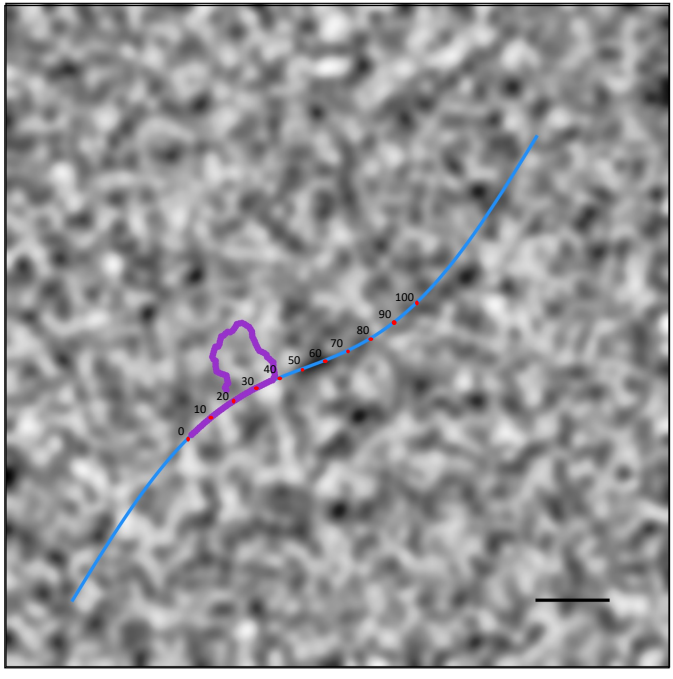


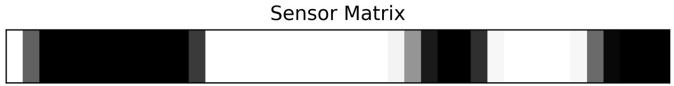
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

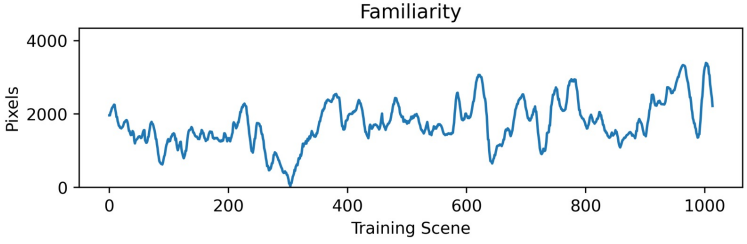
Navigation stats: RMSD error: 84.16; RMSD/dist: 0.210; TD: 1776; p90: 44; p50: 22; complete: 0

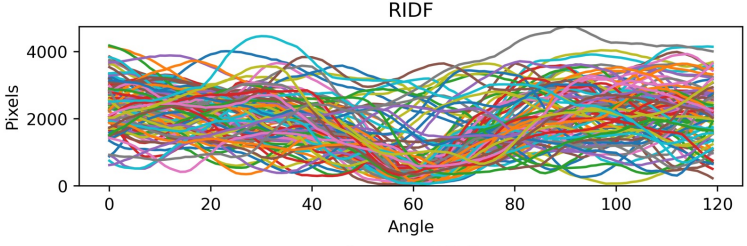

Index: BLUR: 10.0; LEVELS: 64; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

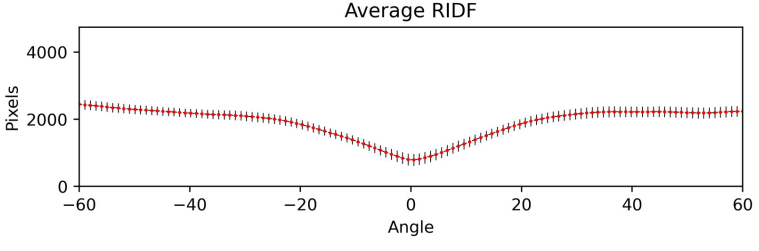
30%







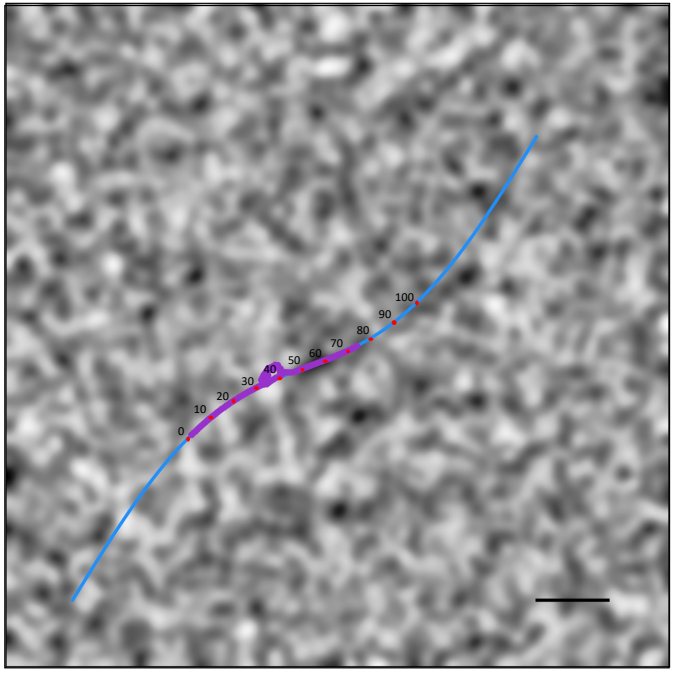


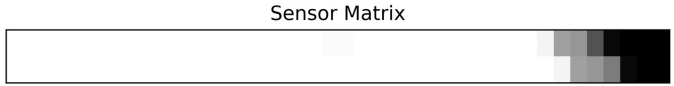


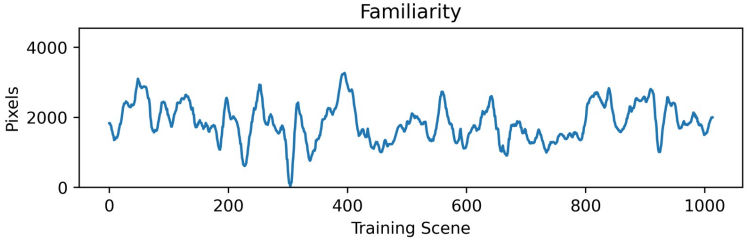
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

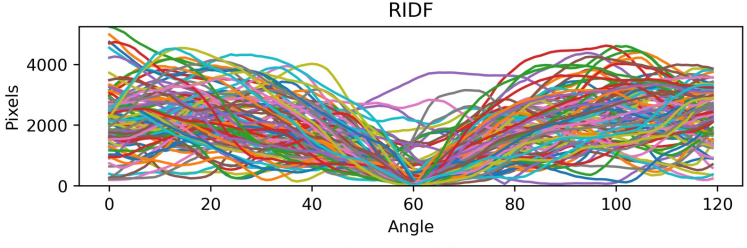
Navigation stats: RMSD error: 3775.78; RMSD/dist: 9.439; TD: 1000; p90: 34; p50: 18; complete: 0

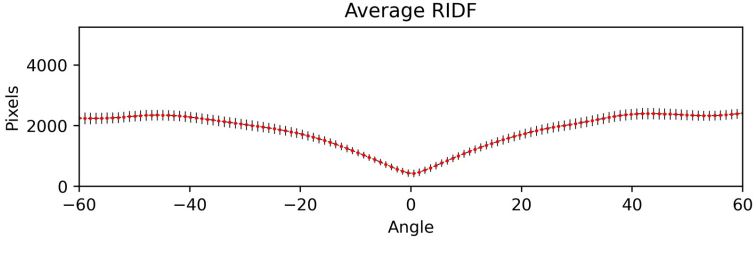
70%







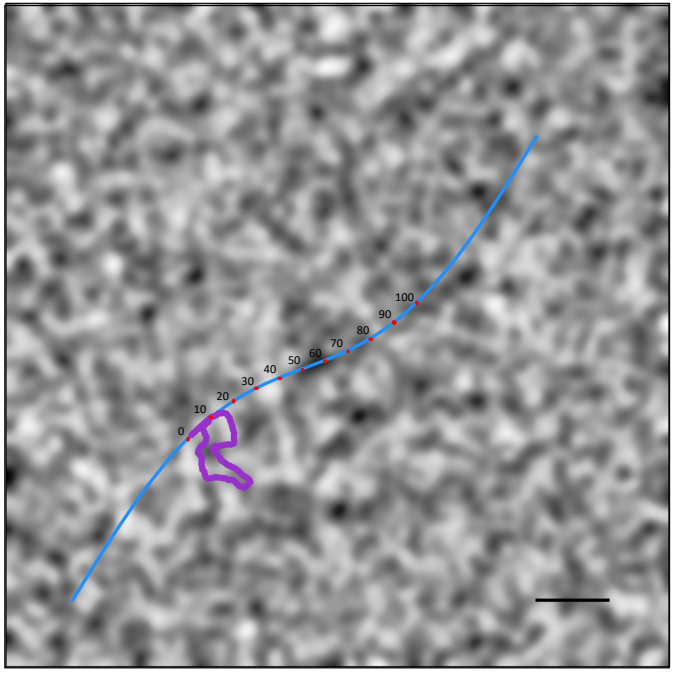


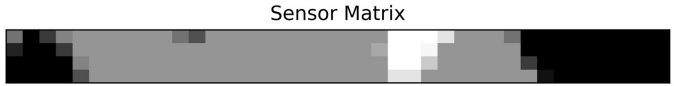


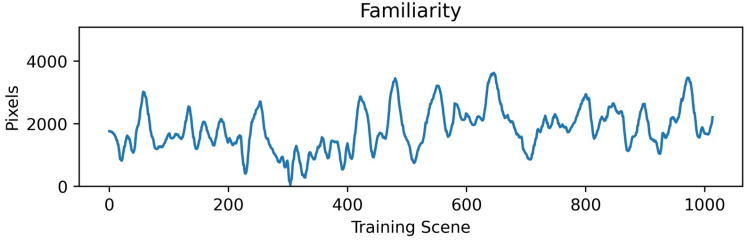
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

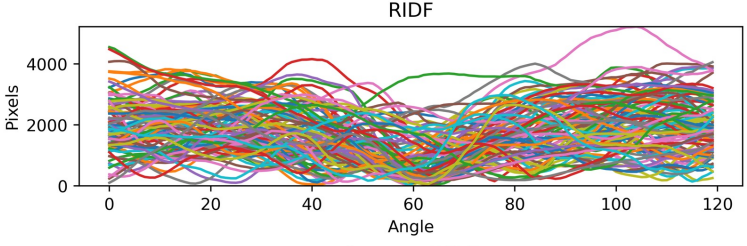
Navigation stats: RMSD error: 390.25; RMSD/dist: 0.976; TD: 1486; p90: 42; p50: 22; complete: 0

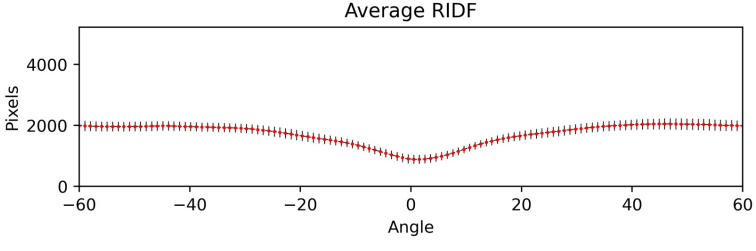
10%







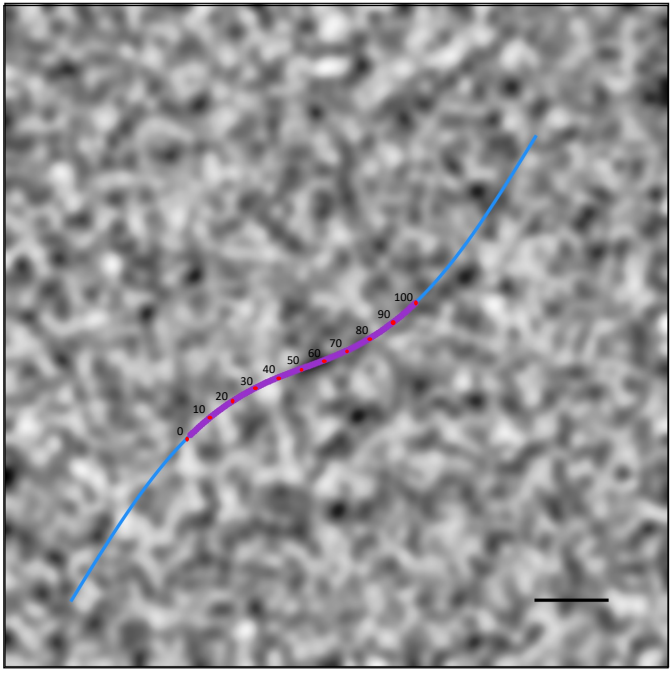


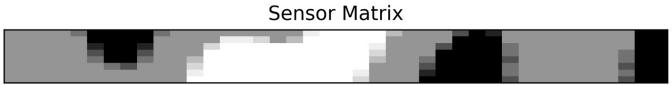


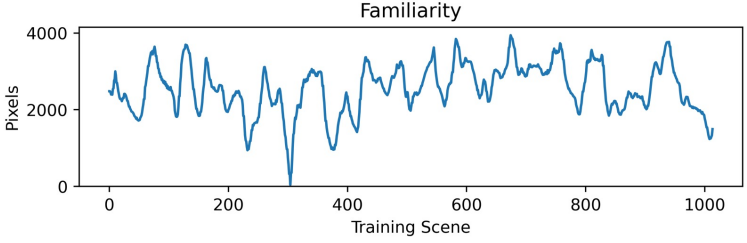
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

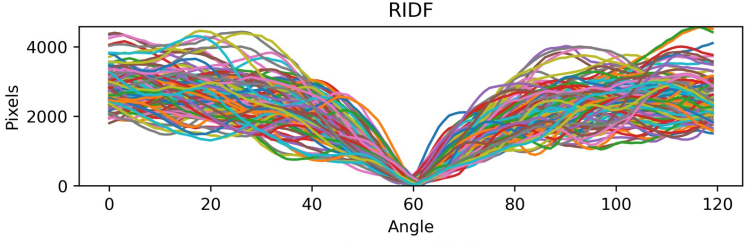
Navigation stats: RMSD error: 4544.26; RMSD/dist: 11.361; TD: 1050; p90: 54; p50: 24; complete: 0

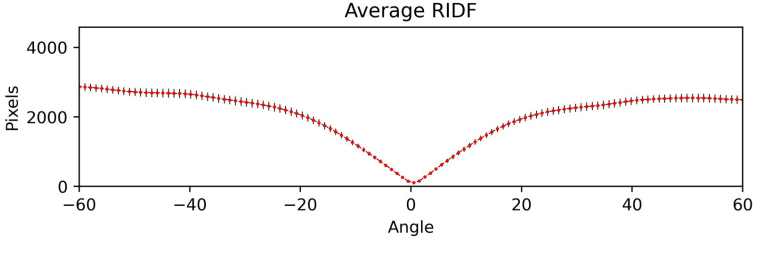
100%







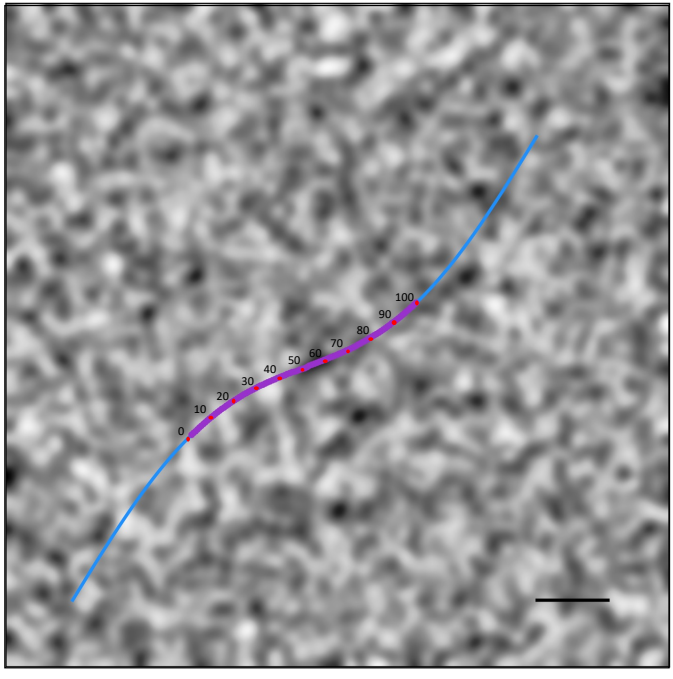


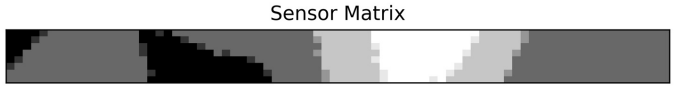


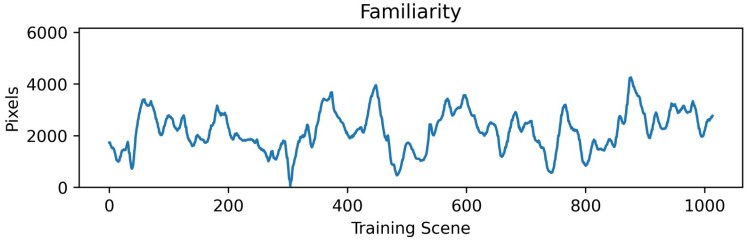
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

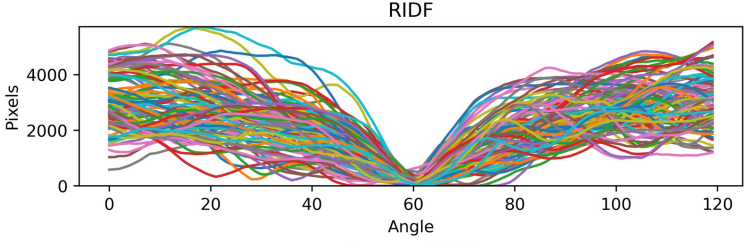
Navigation stats: RMSD error: 35.12; RMSD/dist: 0.088; TD: 1837; p90: 32; p50: 18; complete: 0

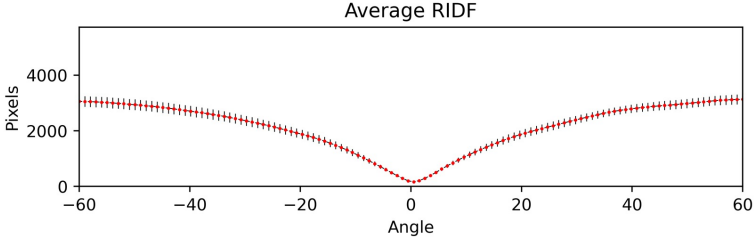
100%







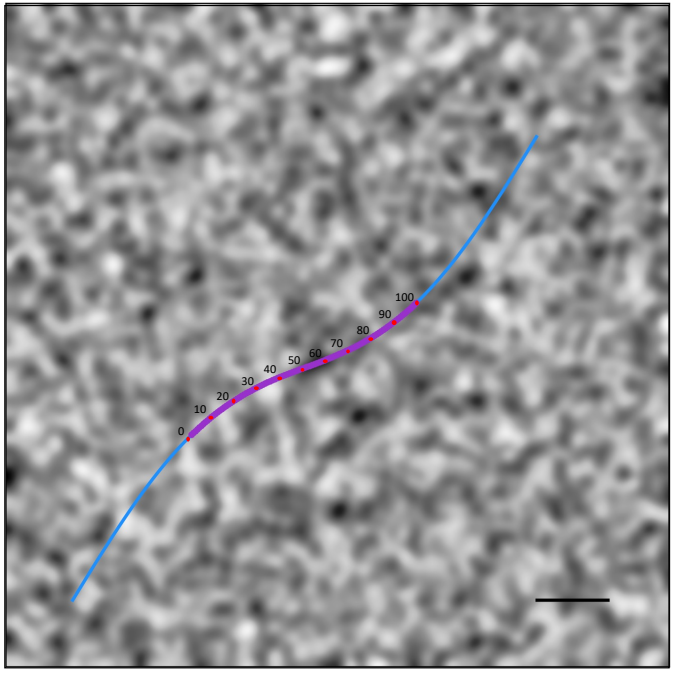


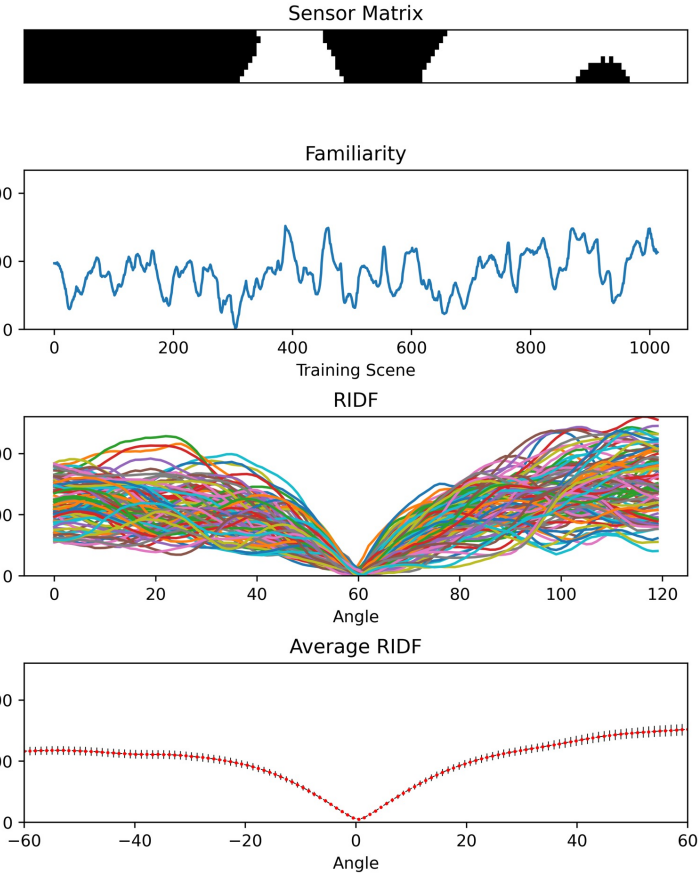


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 75.86; RMSD/dist: 0.190; TD: 2164; p90: 50; p50: 22; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 37.35; RMSD/dist: 0.093; TD: 1765; p90: 34; p50: 18; complete: 0