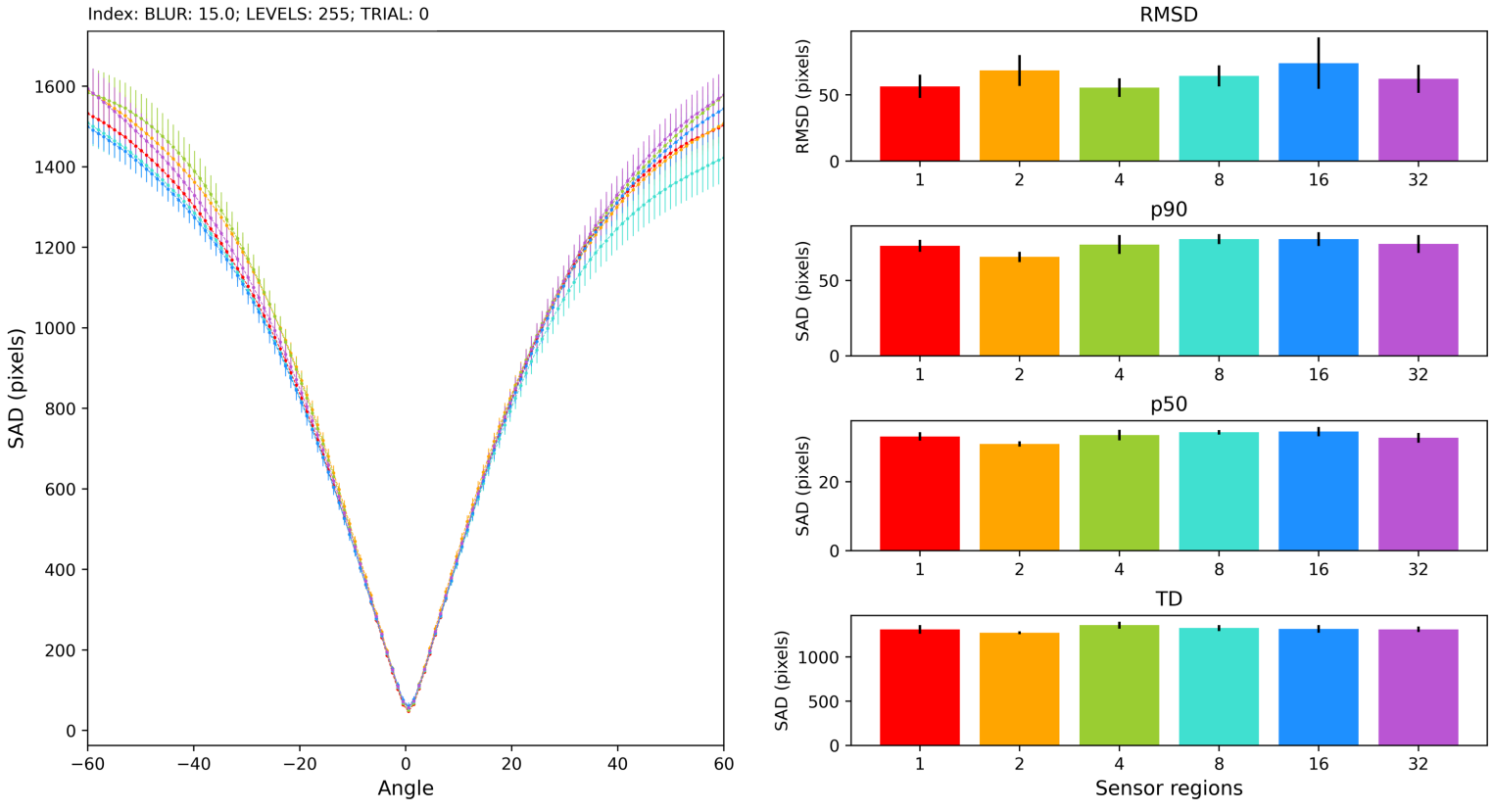
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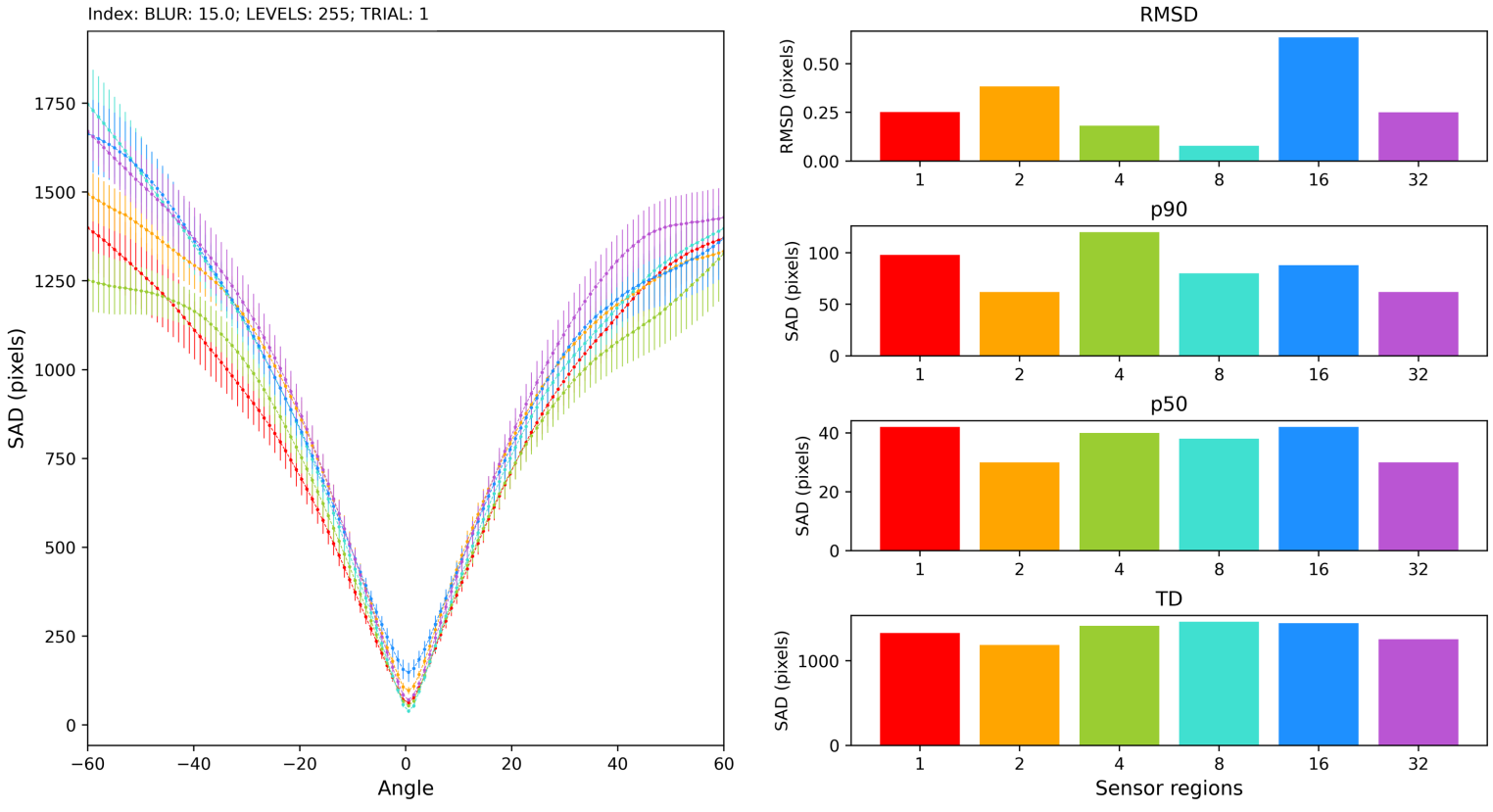
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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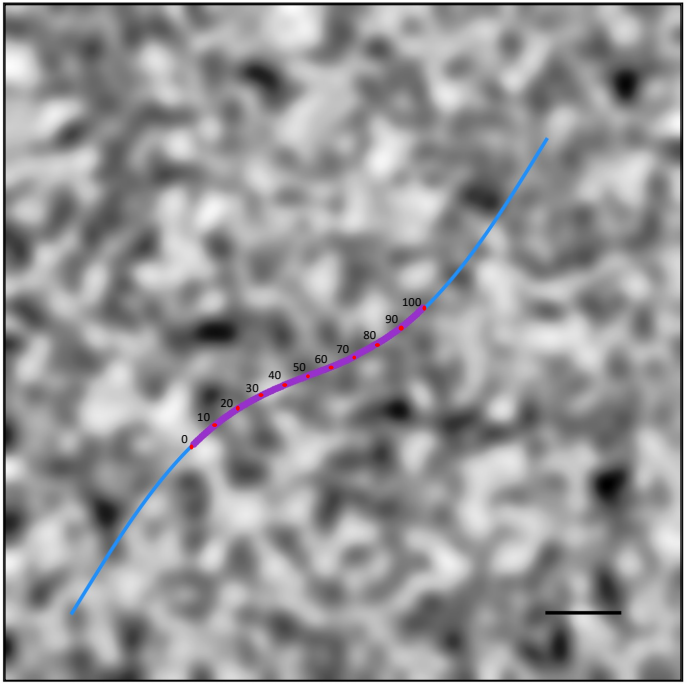
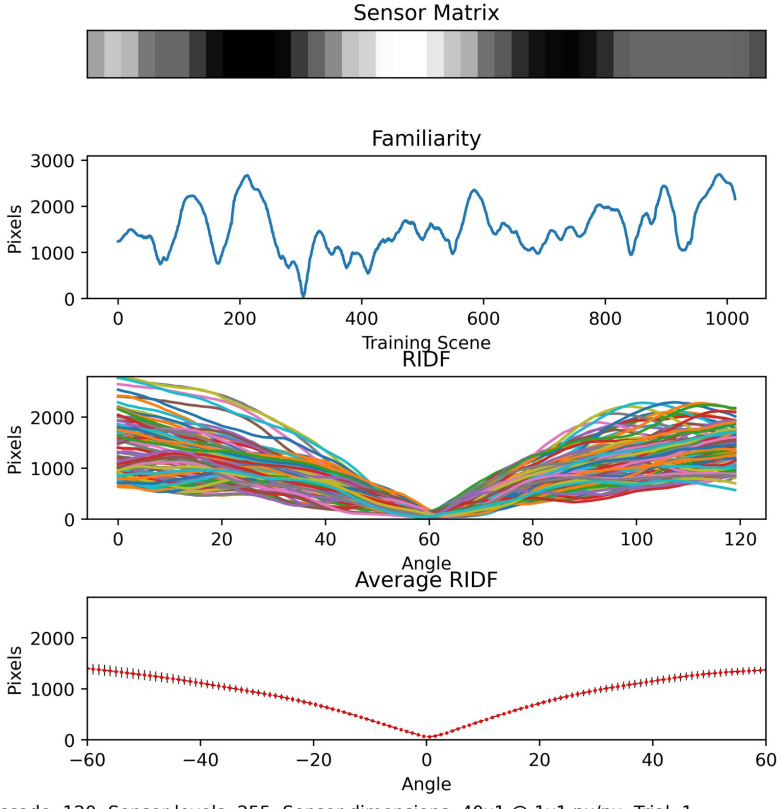
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

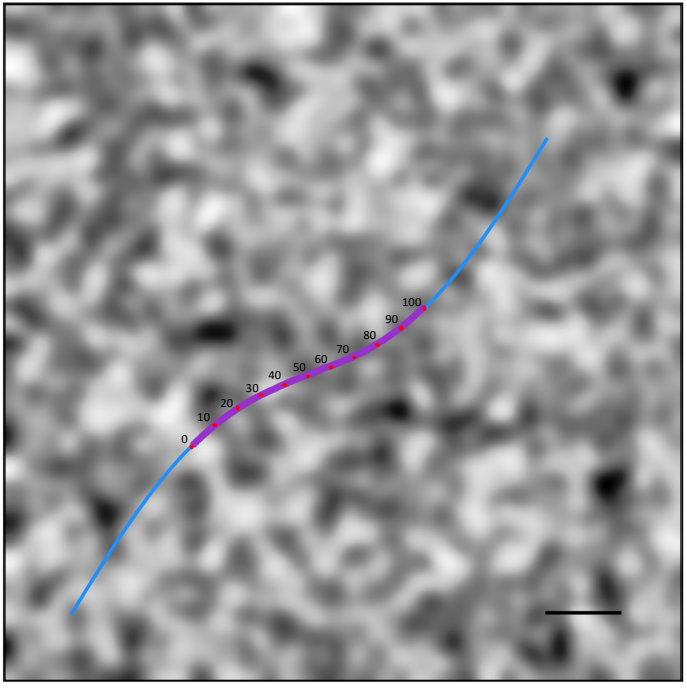


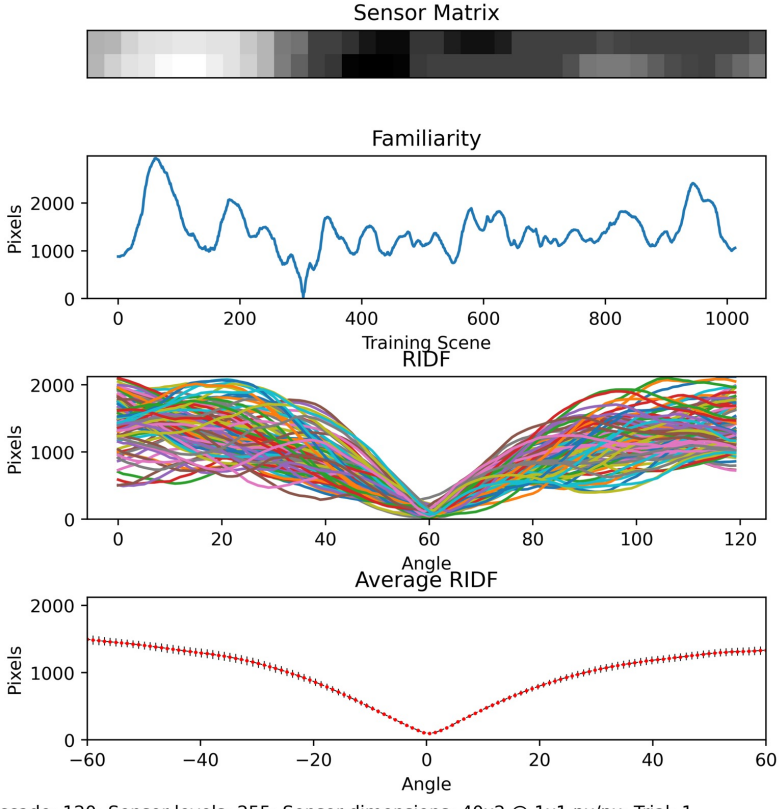


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 100.69; RMSD/dist: 0.252; TD: 1327; p90: 98; p50: 42; complete: 0

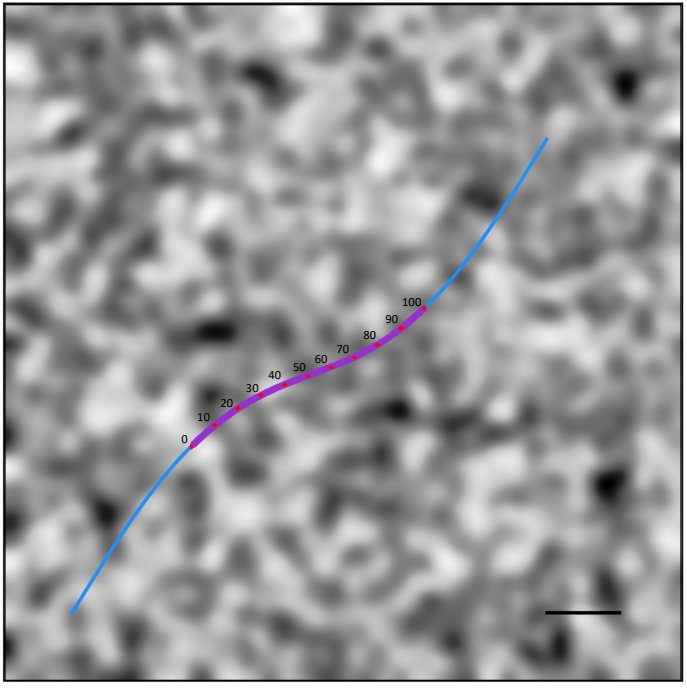
100%

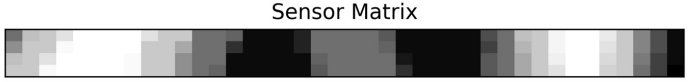


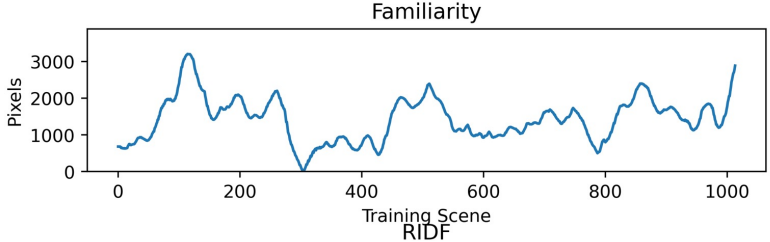


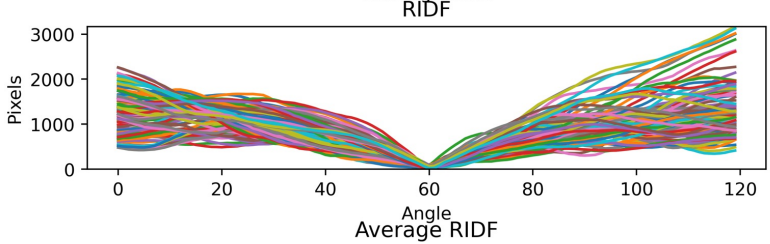
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 153.26; RMSD/dist: 0.383; TD: 1187; p90: 62; p50: 30; complete: 0

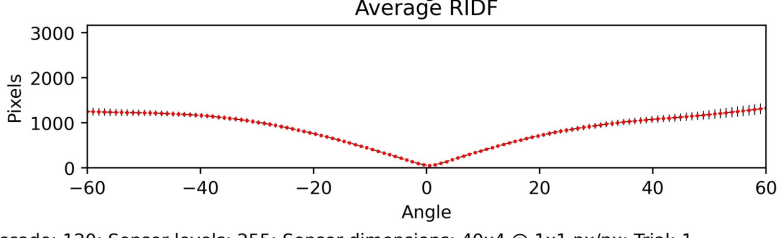
100%











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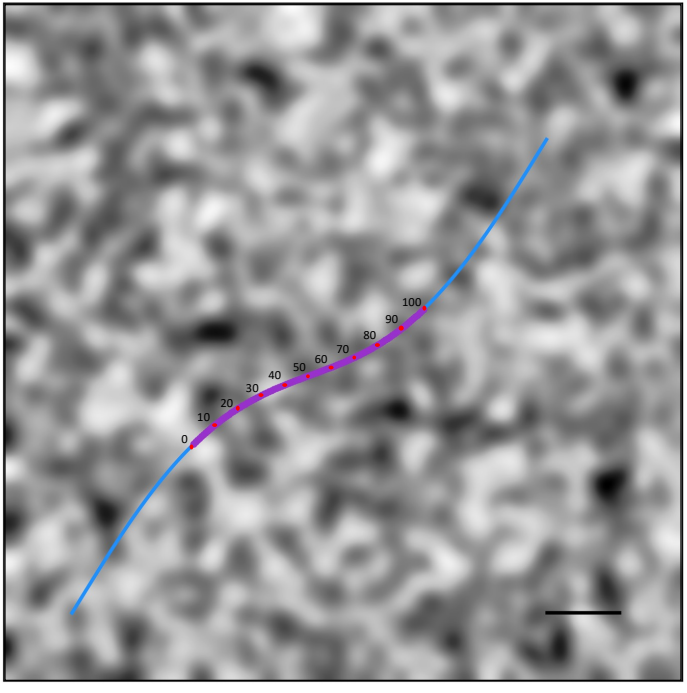
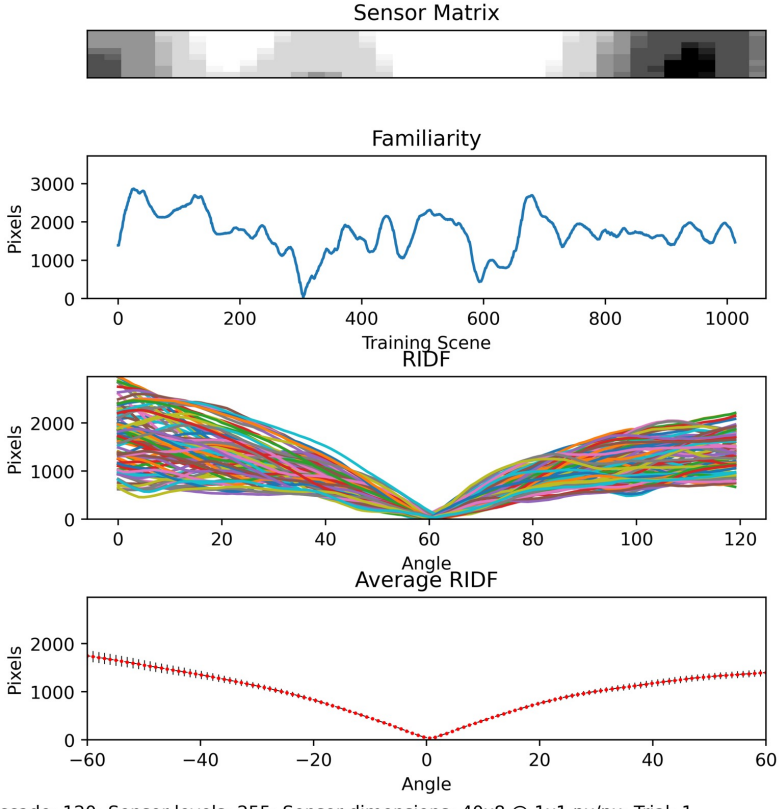
Navigation stats: RMSD error: 72.97; RMSD/dist: 0.182; TD: 1413; p90: 120; p50: 40; complete: 0

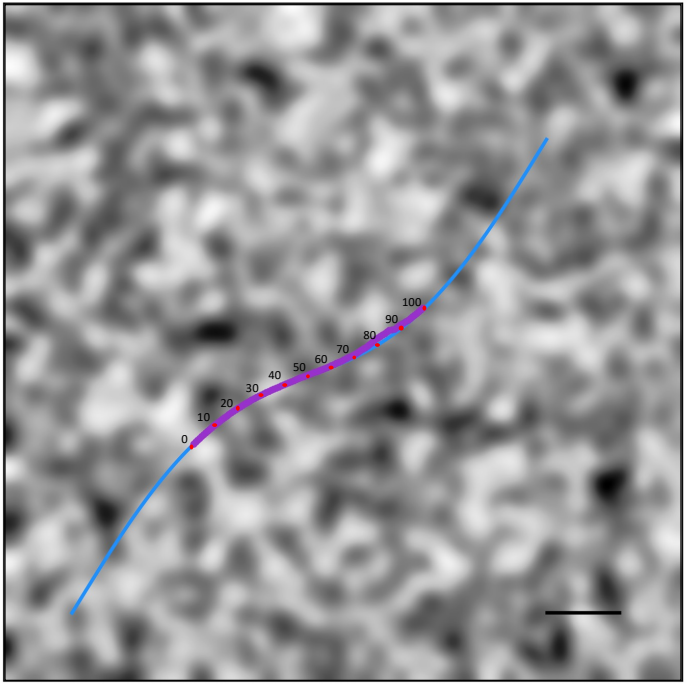
100%

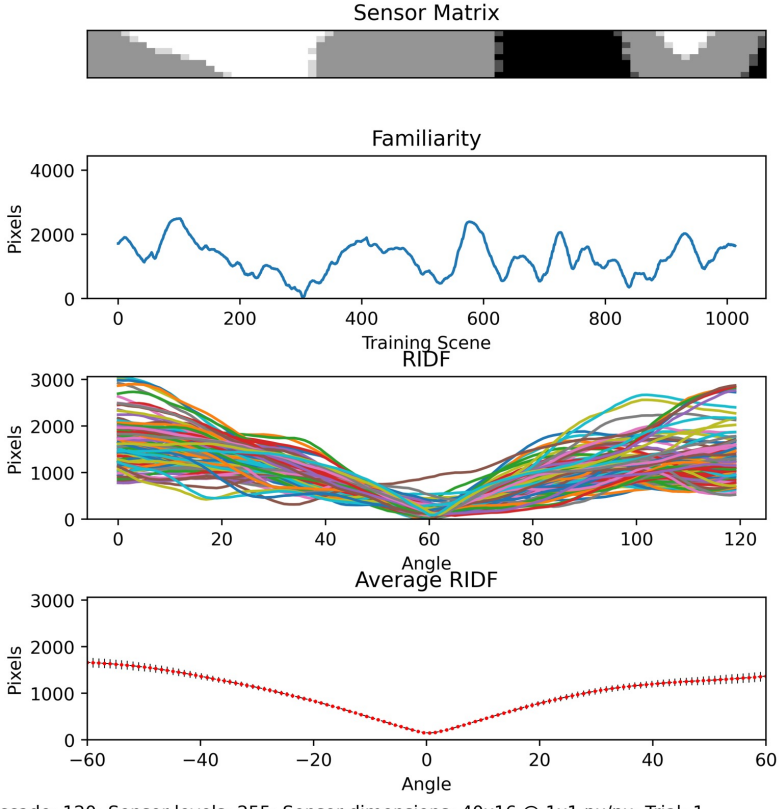




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 31.37; RMSD/dist: 0.078; TD: 1461; p90: 80; p50: 38; complete: 0

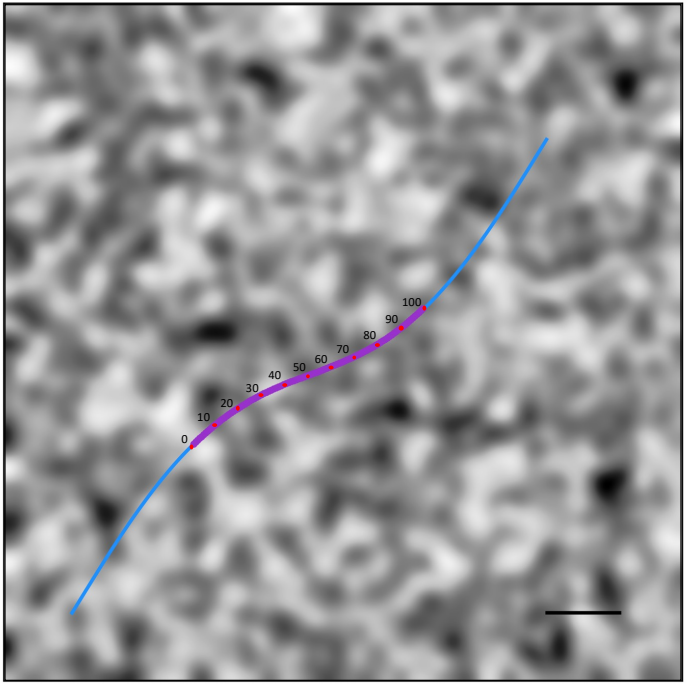
80%

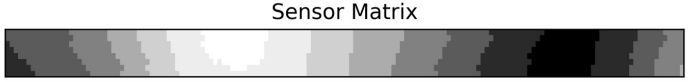


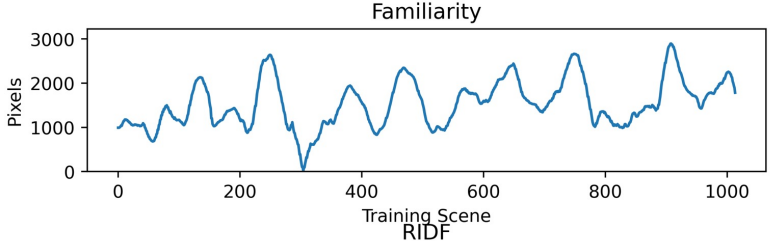


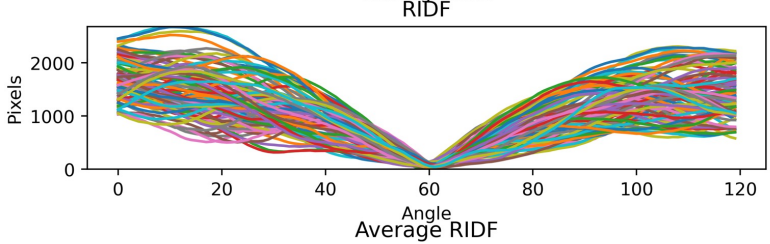
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 254.13; RMSD/dist: 0.635; TD: 1445; p90: 88; p50: 42; complete: 0

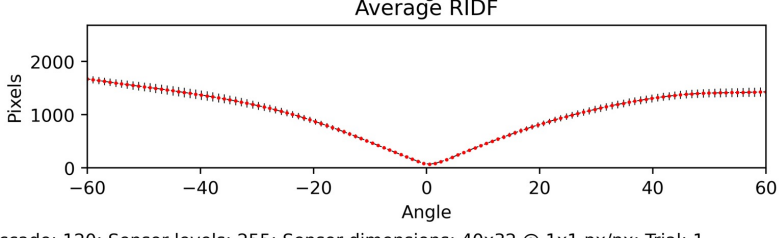
100%











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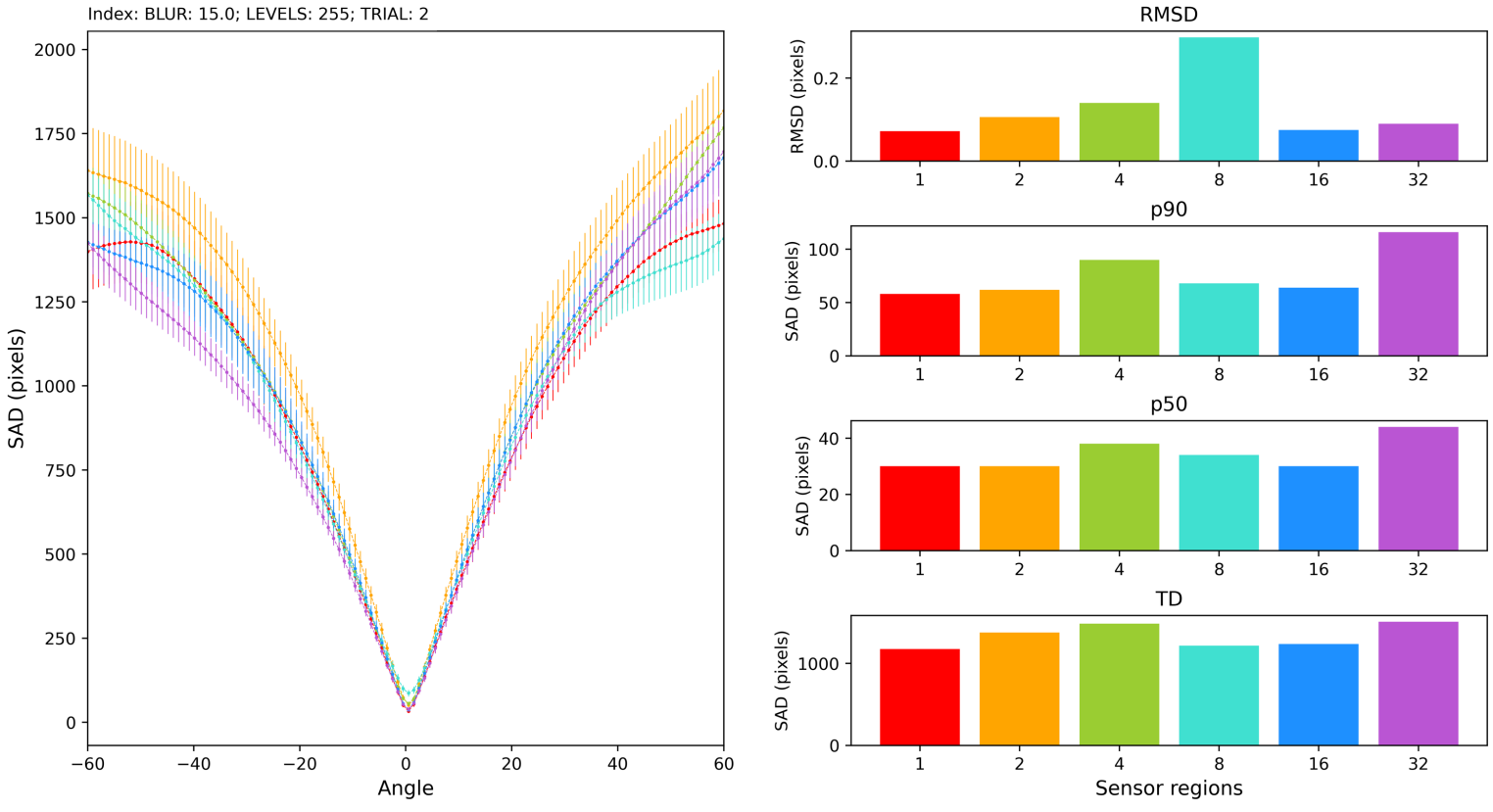
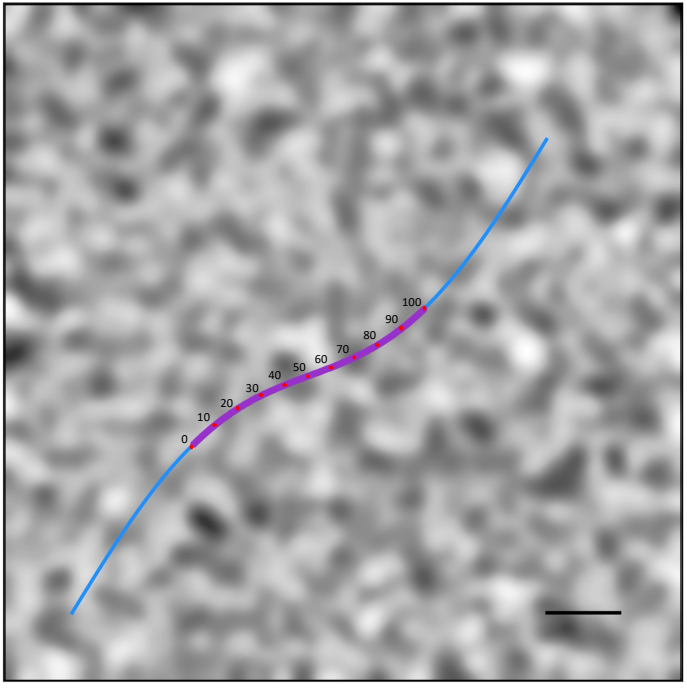
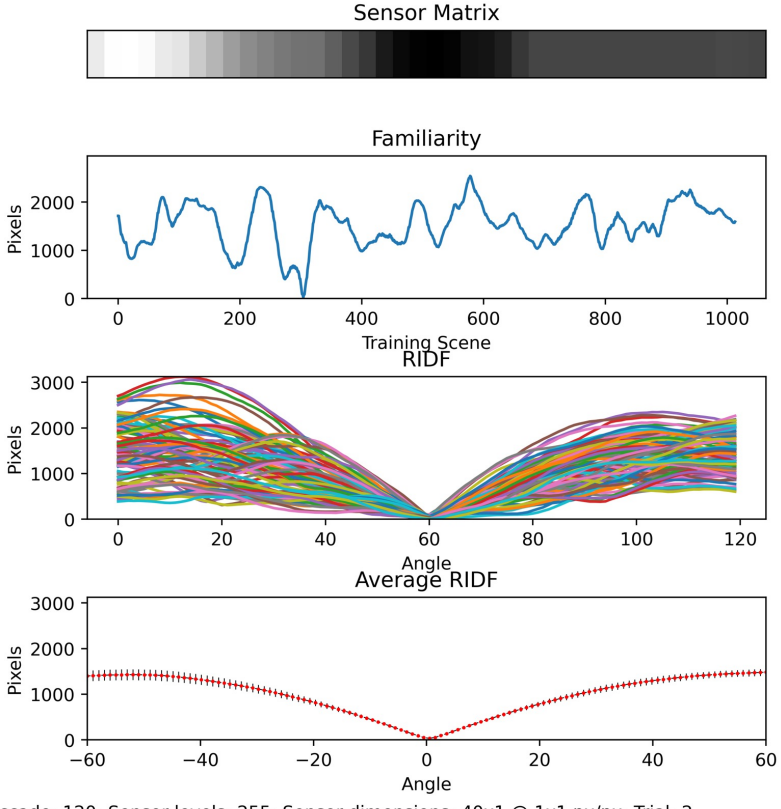
Navigation stats: RMSD error: 100.40; RMSD/dist: 0.251; TD: 1254; p90: 62; p50: 30; complete: 0


Index: BLUR: 15.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%





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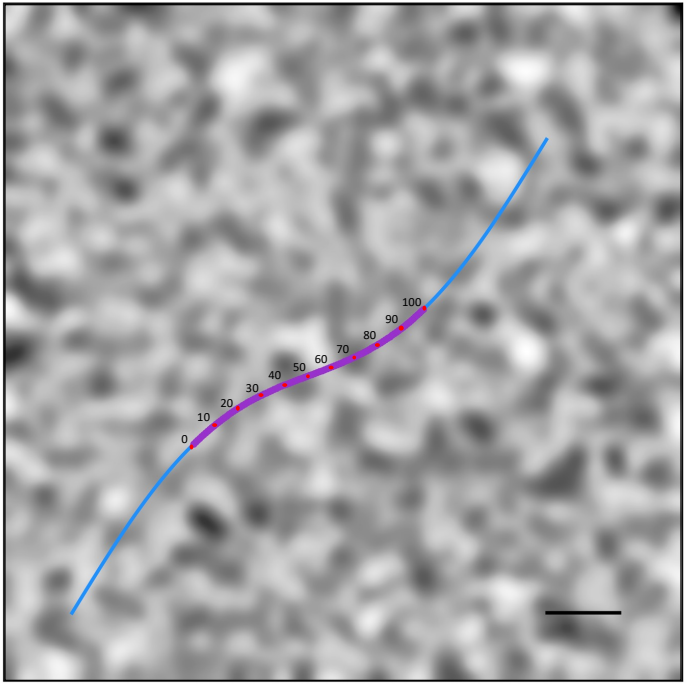
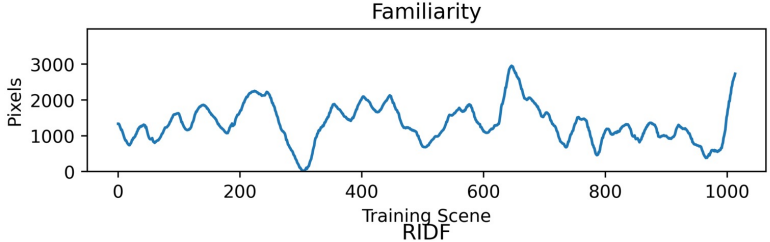
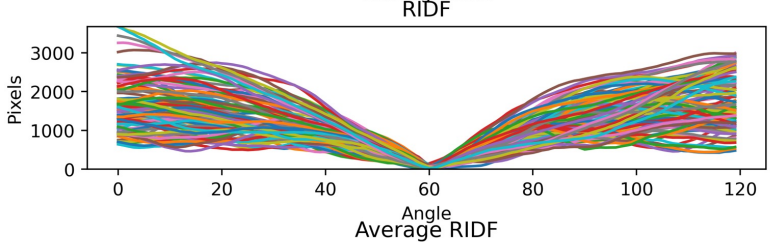
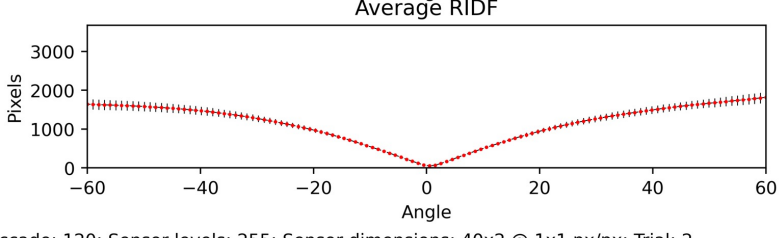
Navigation stats: RMSD error: 28.69; RMSD/dist: 0.072; TD: 1177; p90: 58; p50: 30; complete: 0

100%



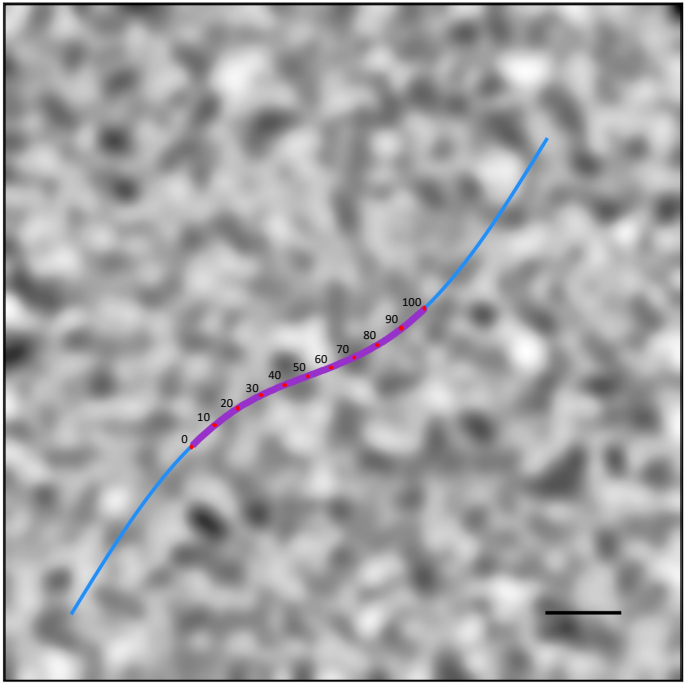


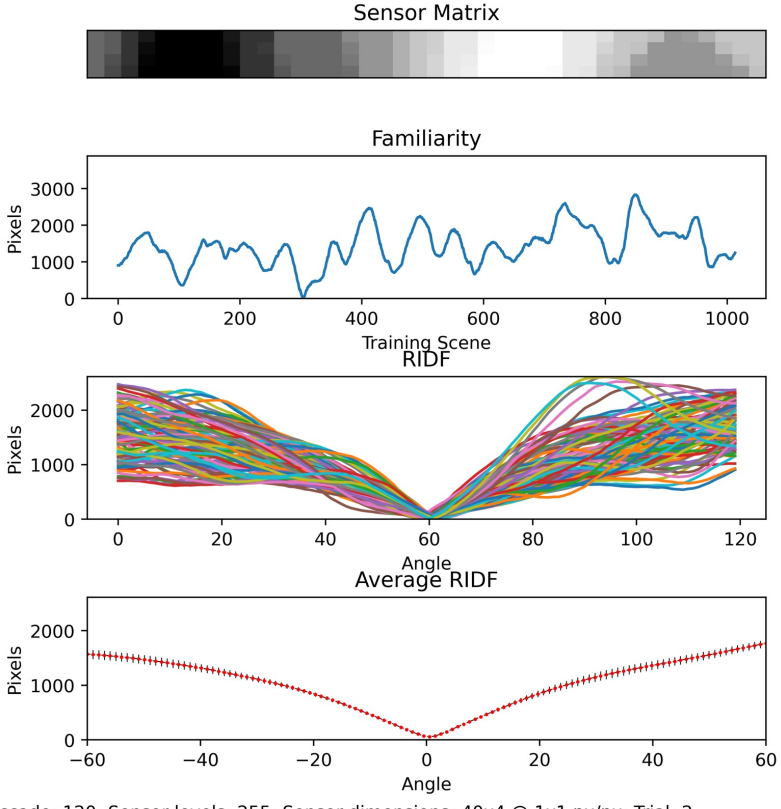




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 42.49; RMSD/dist: 0.106; TD: 1378; p90: 62; p50: 30; complete: 0

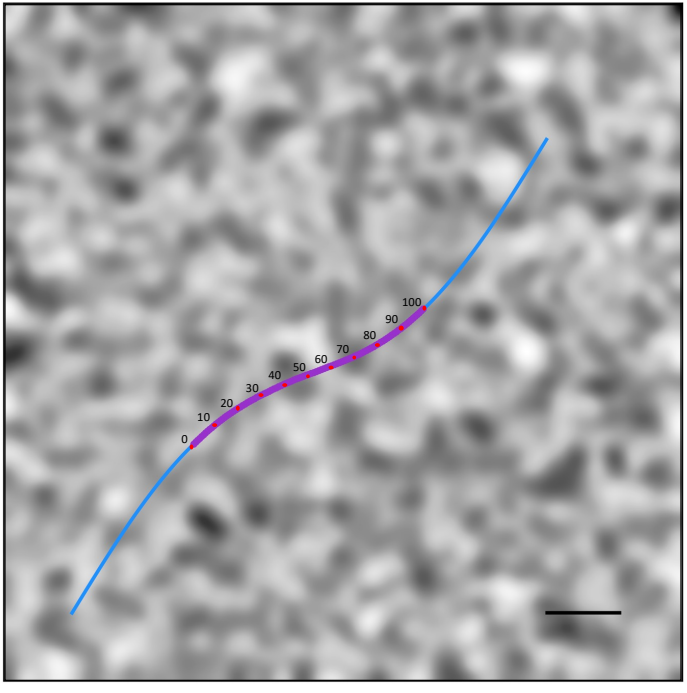
100%

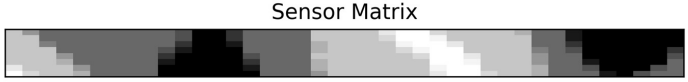


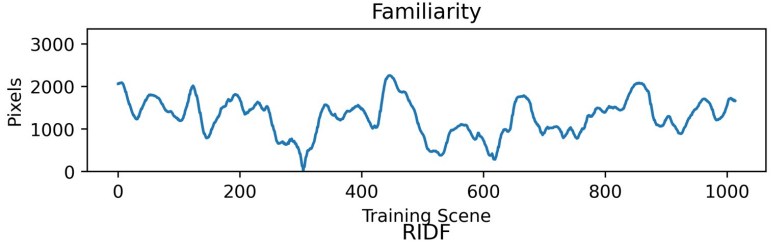


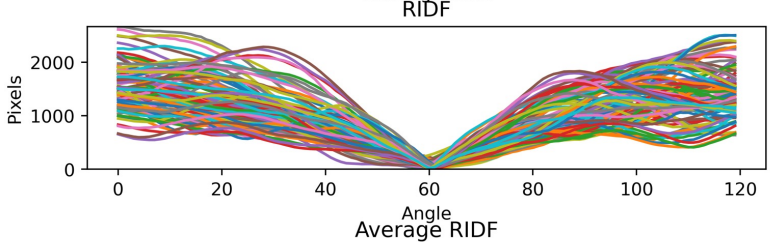
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 55.89; RMSD/dist: 0.140; TD: 1485; p90: 90; p50: 38; complete: 0

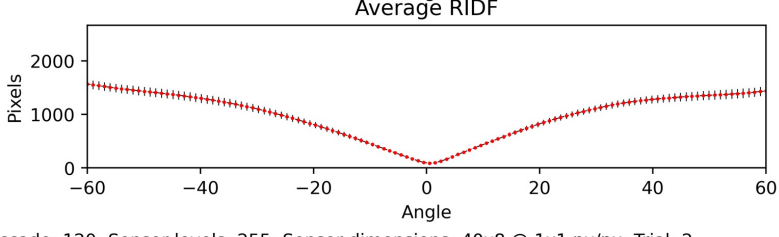
100%





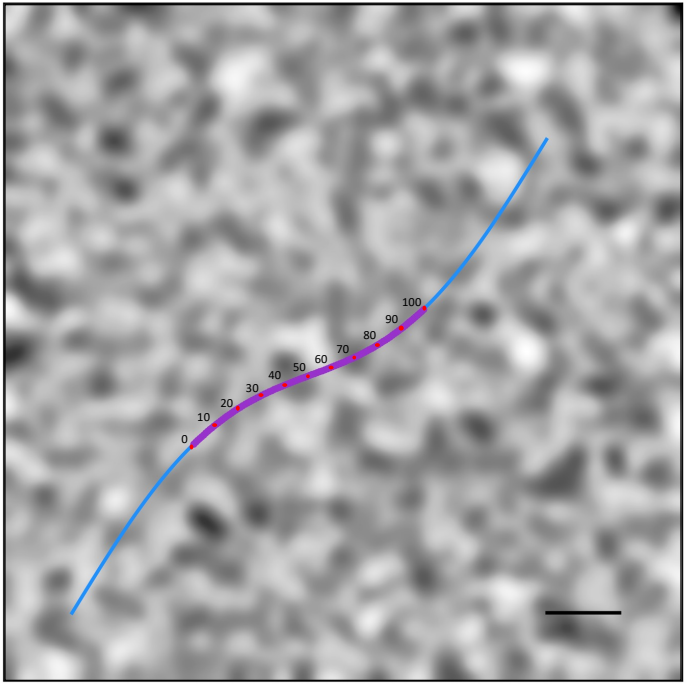


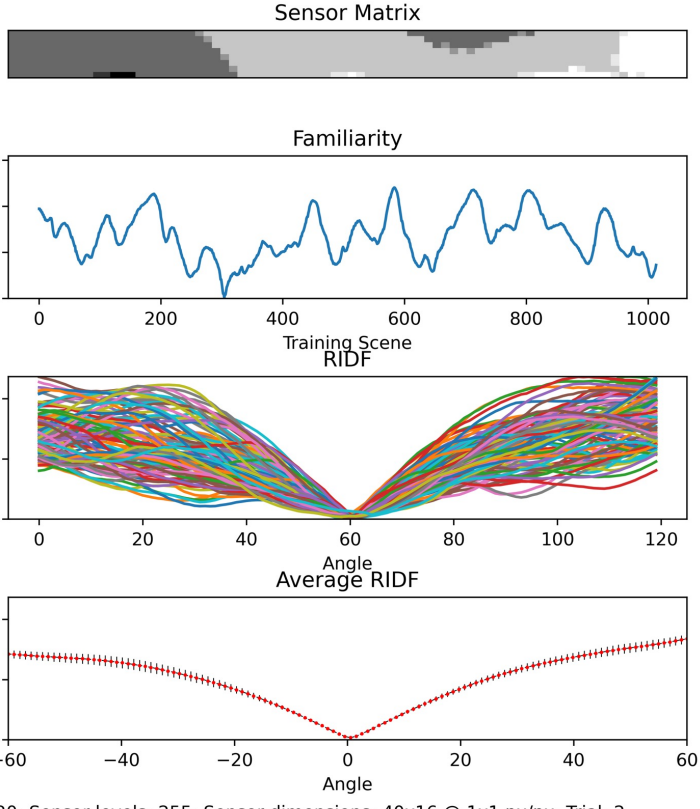




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 119.11; RMSD/dist: 0.298; TD: 1216; p90: 68; p50: 34; complete: 0

100%





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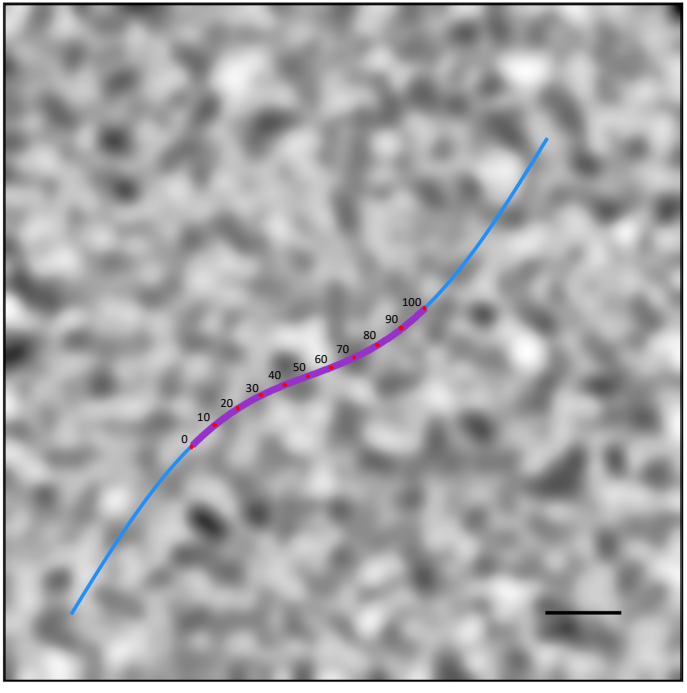
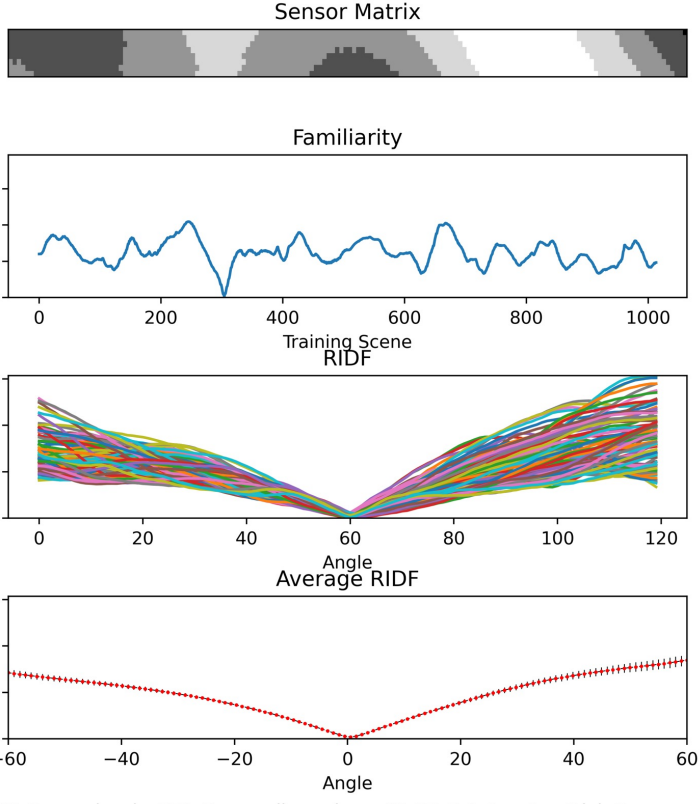
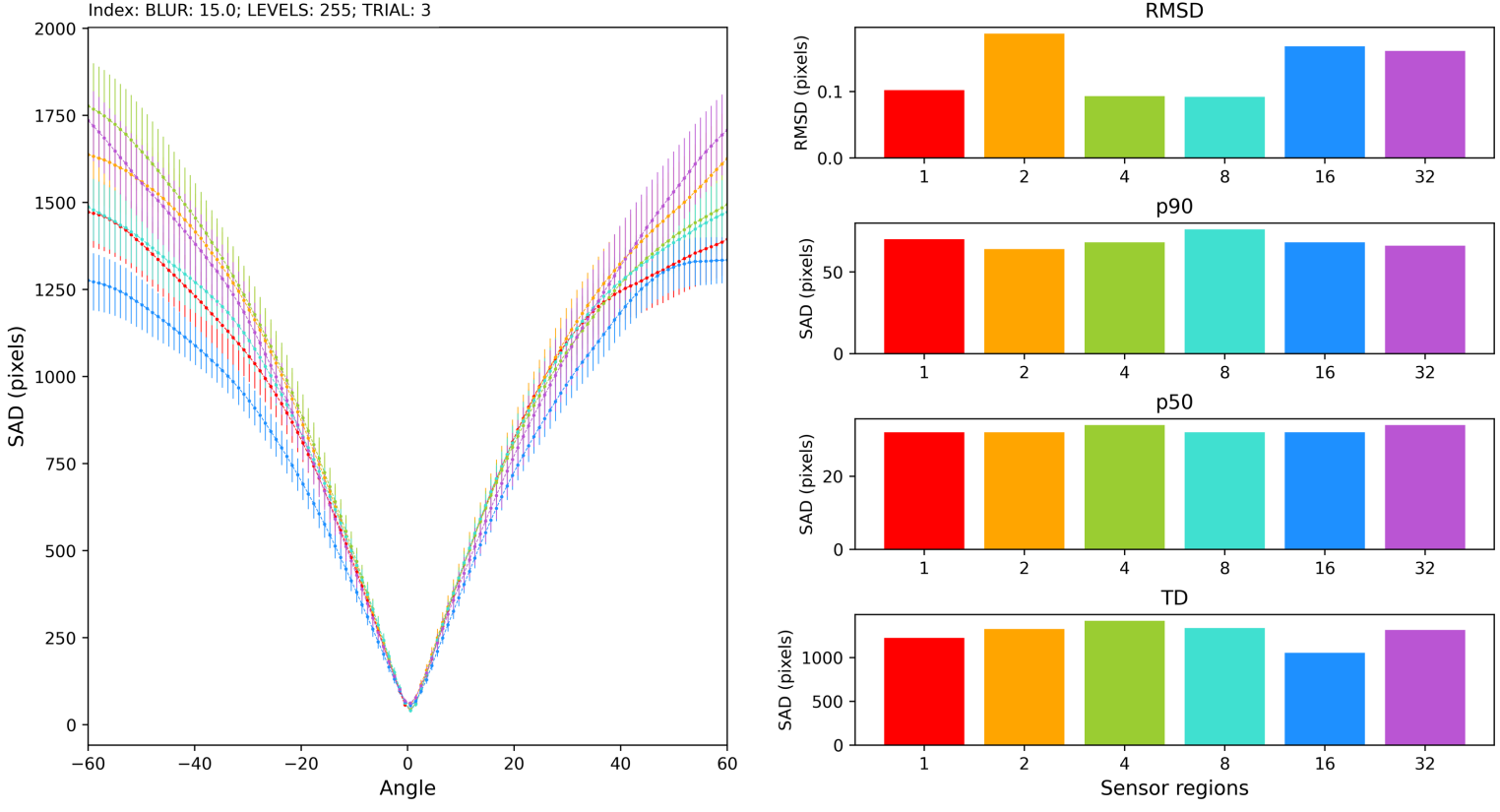
Navigation stats: RMSD error: 30.09; RMSD/dist: 0.075; TD: 1236; p90: 64; p50: 30; complete: 0

100%

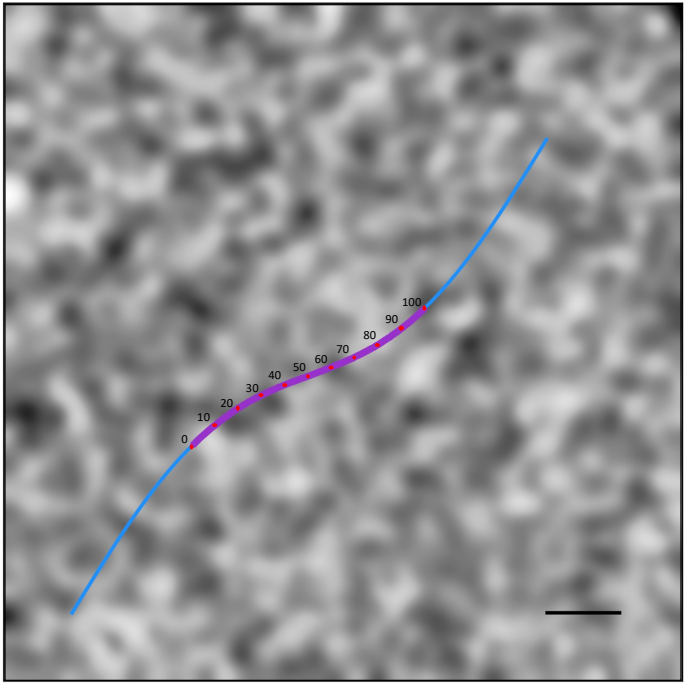


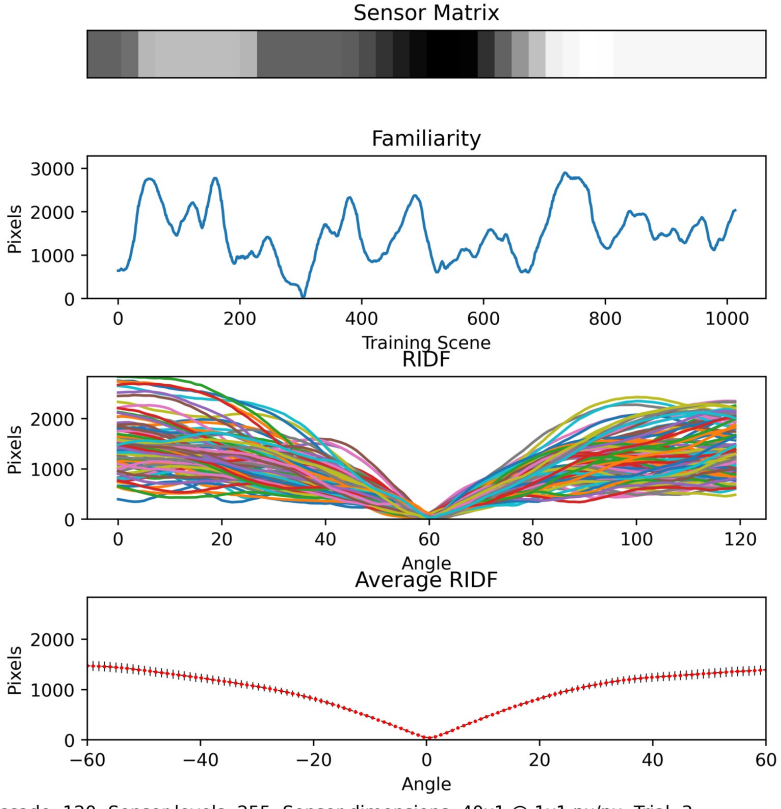


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 35.92; RMSD/dist: 0.090; TD: 1509; p90: 116; p50: 44; complete: 0


Index: BLUR: 15.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

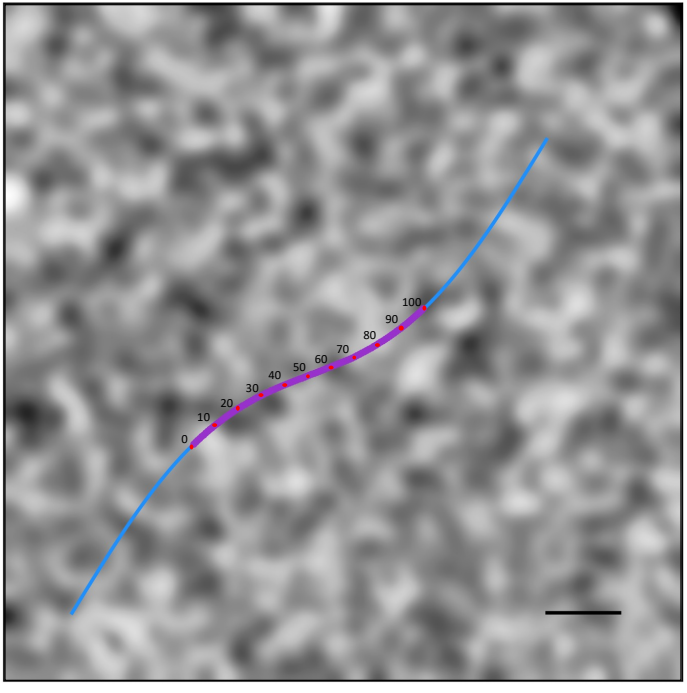
100%

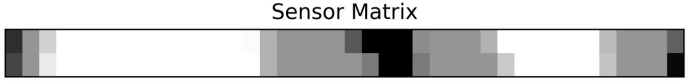


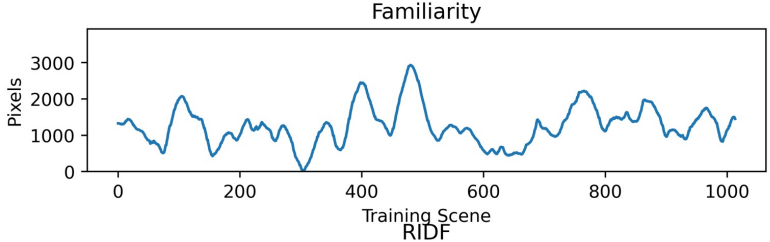


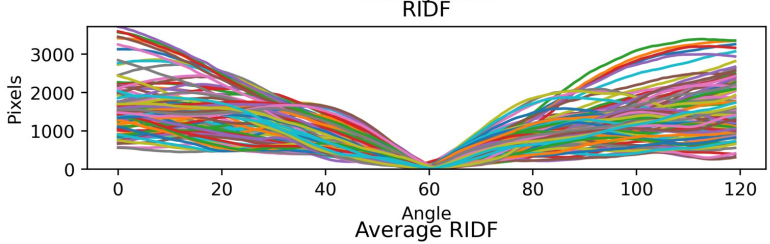
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 40.70; RMSD/dist: 0.102; TD: 1225; p90: 70; p50: 32; complete: 0

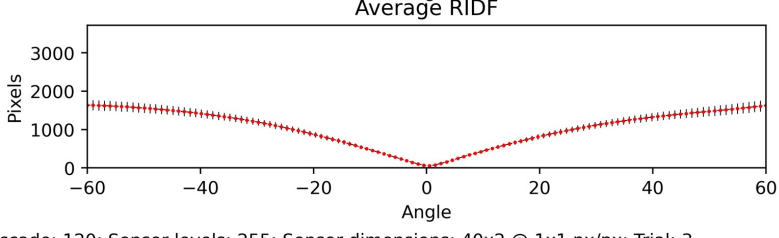
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
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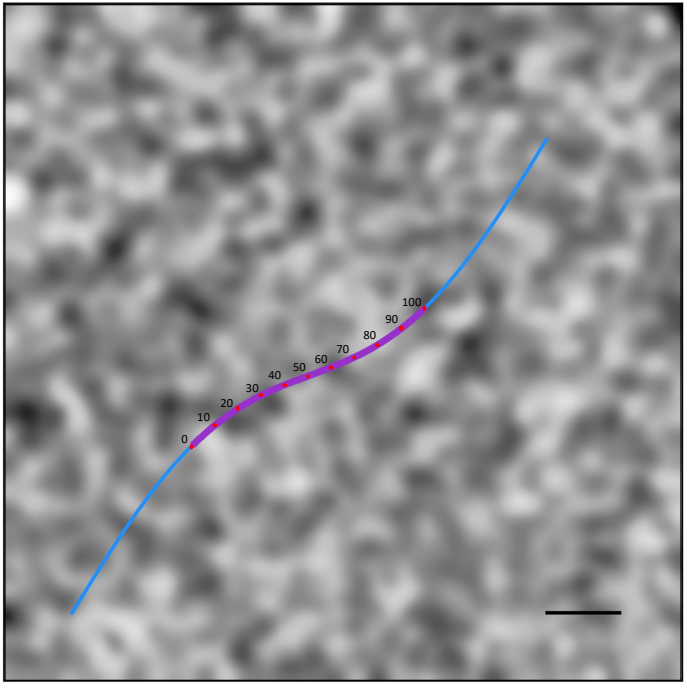
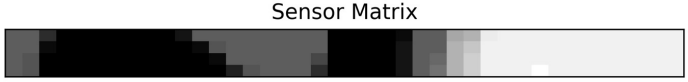
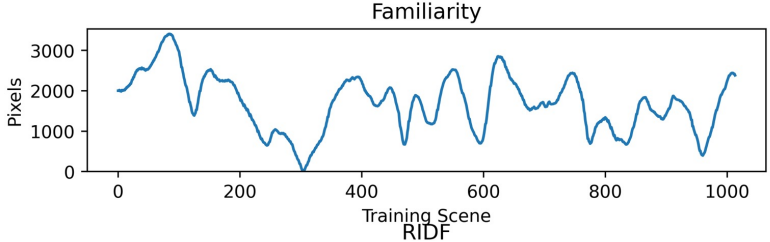
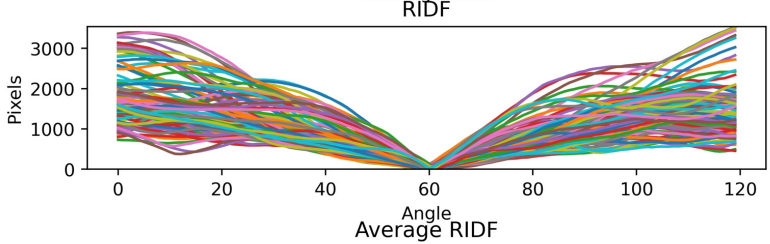
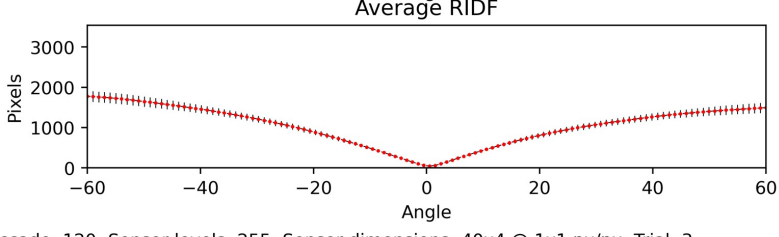
100%











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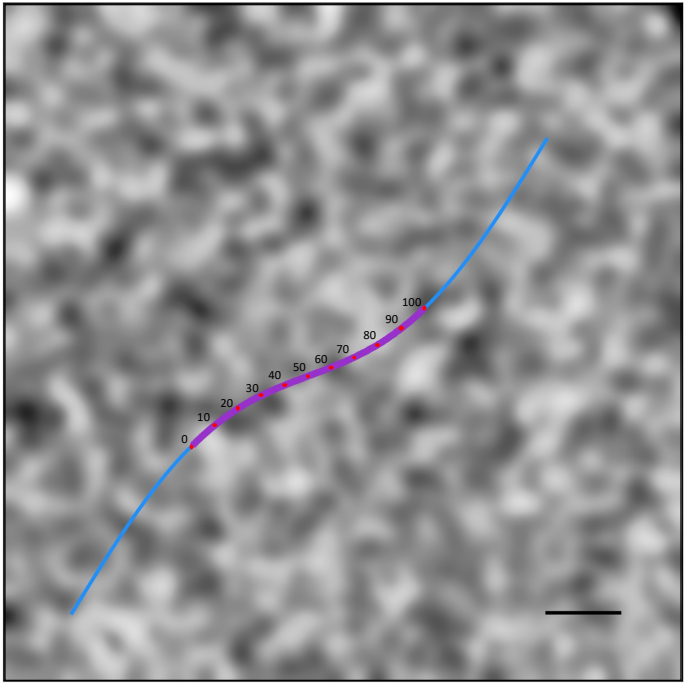
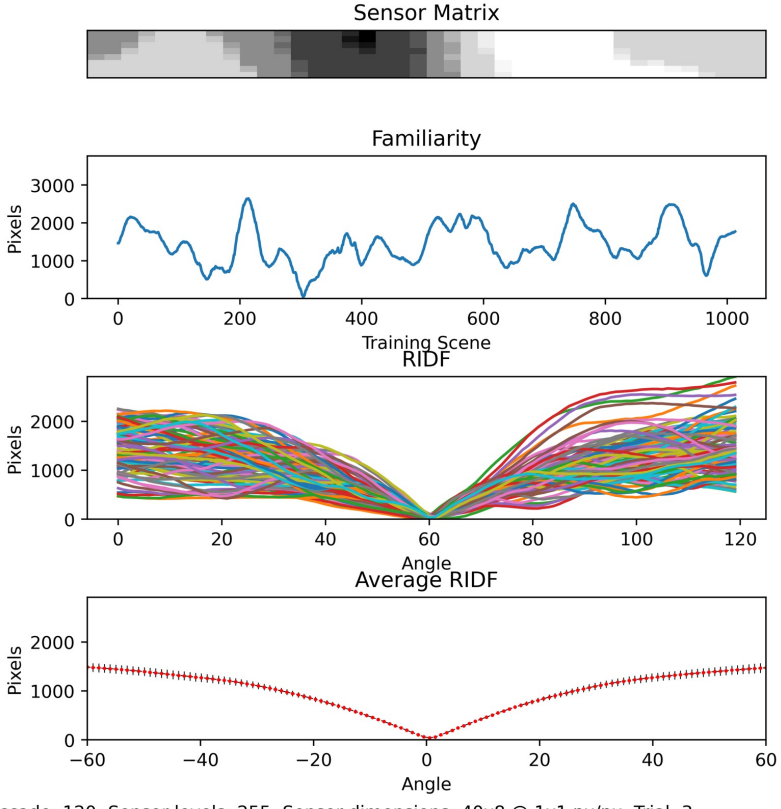
Navigation stats: RMSD error: 37.25; RMSD/dist: 0.093; TD: 1420; p90: 68; p50: 34; complete: 0

100%





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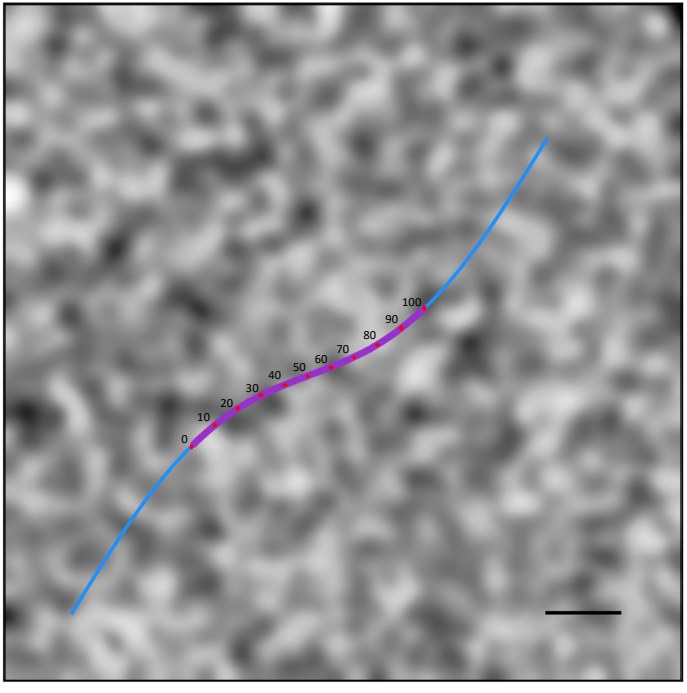
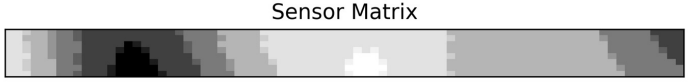
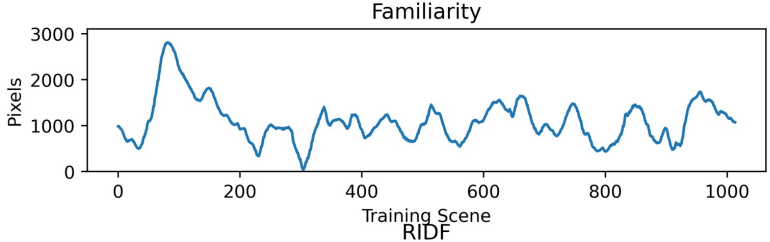
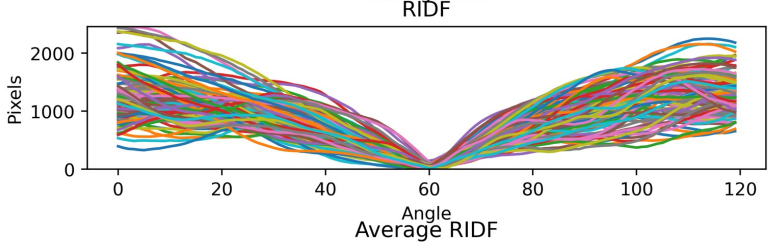
Navigation stats: RMSD error: 36.70; RMSD/dist: 0.092; TD: 1338; p90: 76; p50: 32; complete: 0

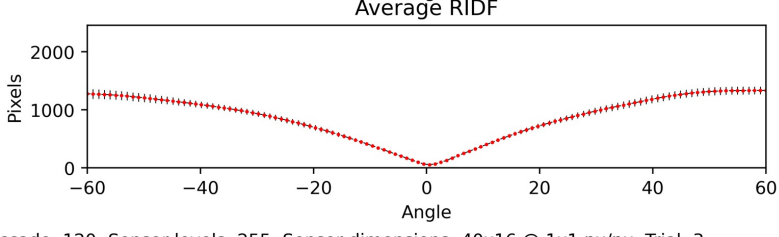
100%











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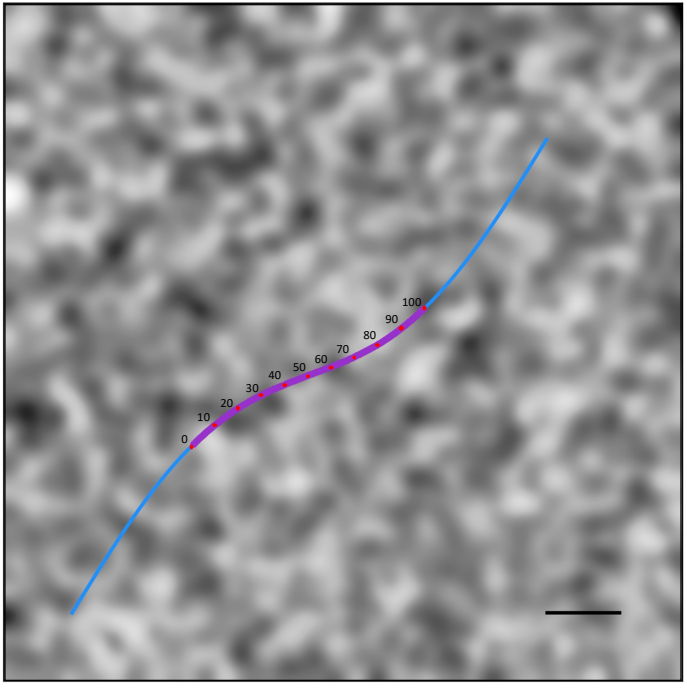
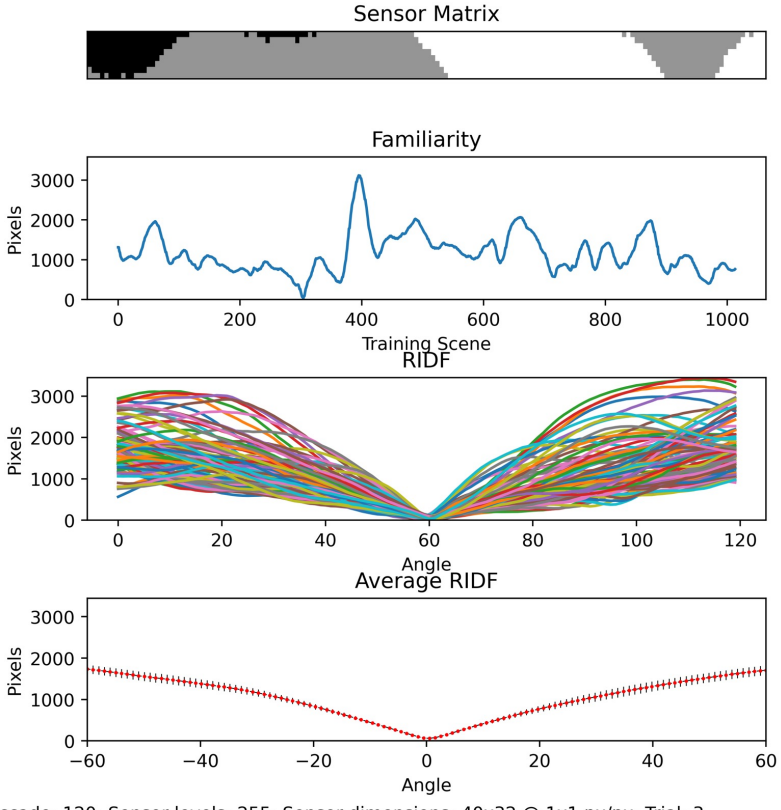
100%





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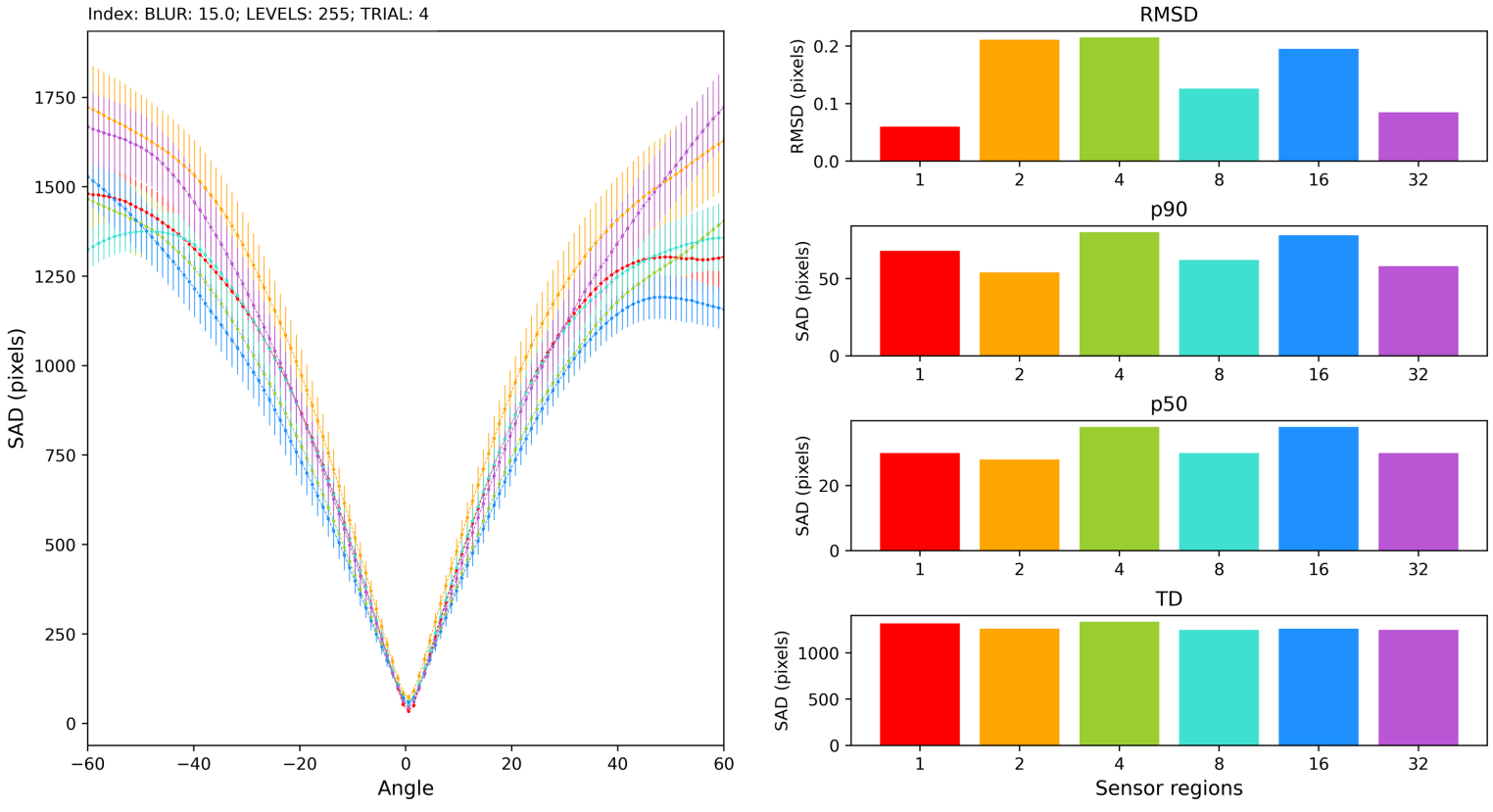
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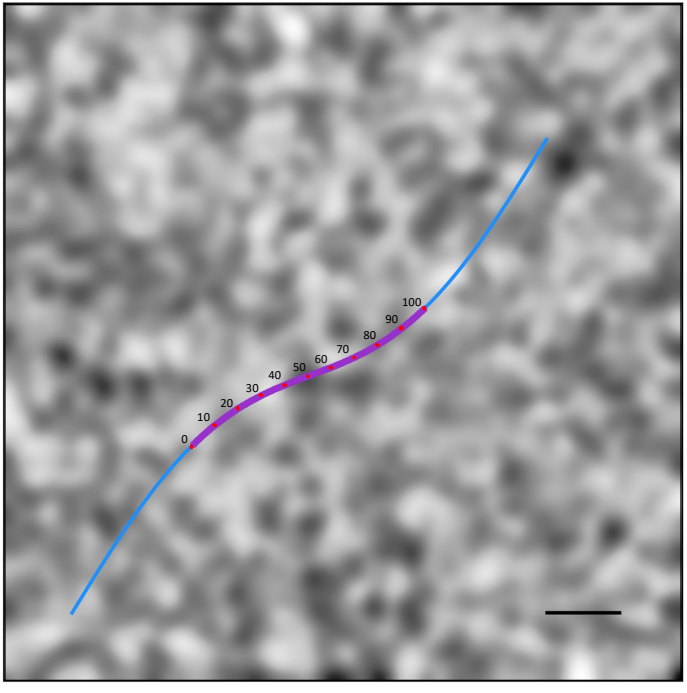
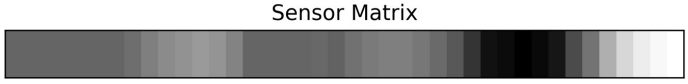
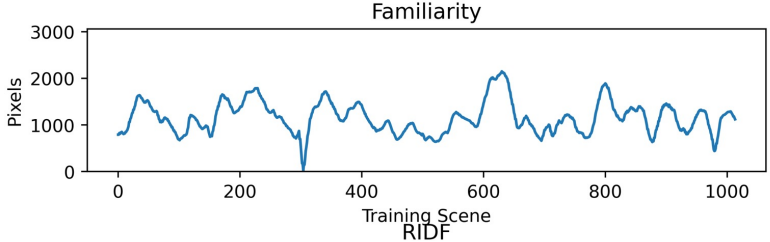
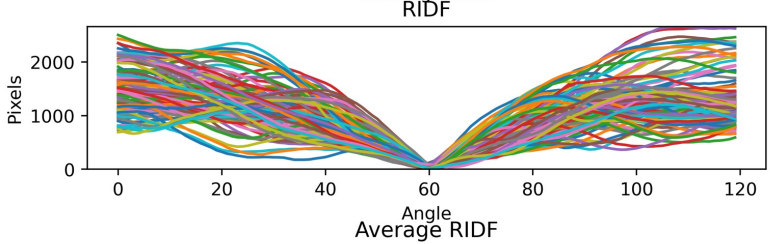
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

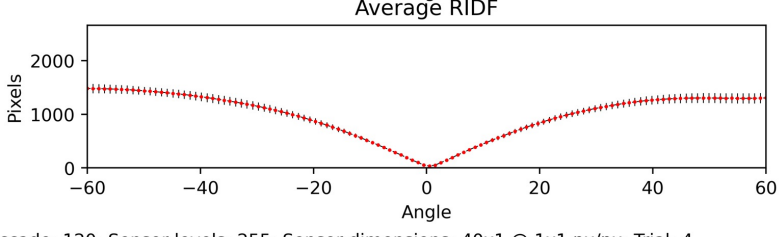
100%











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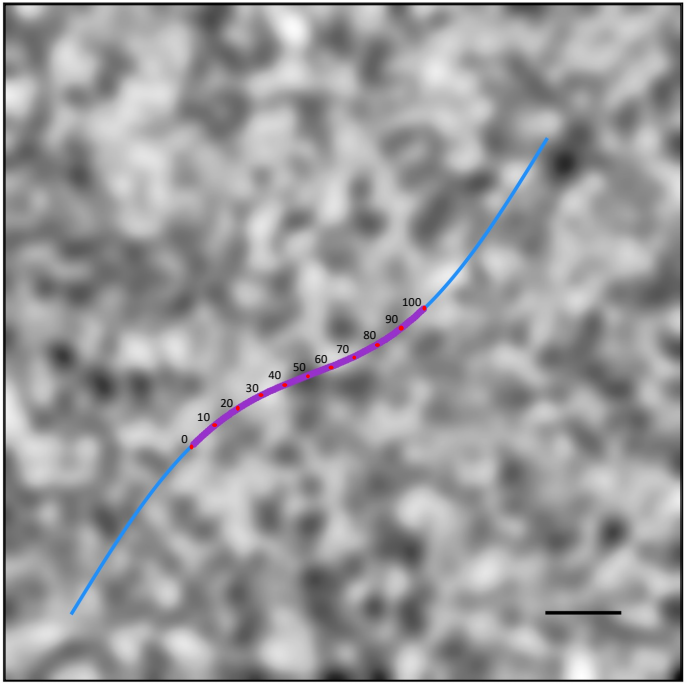
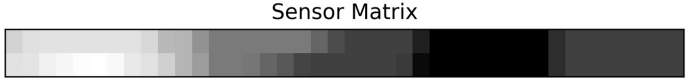
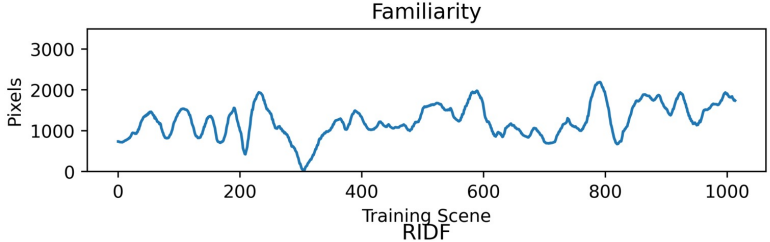
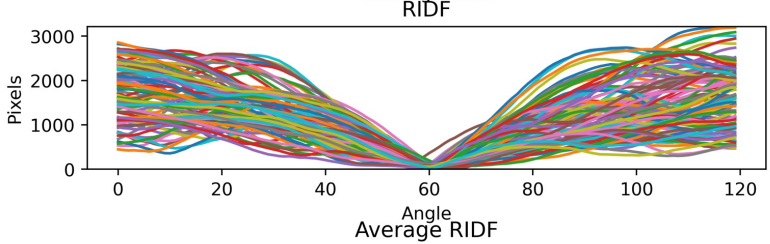
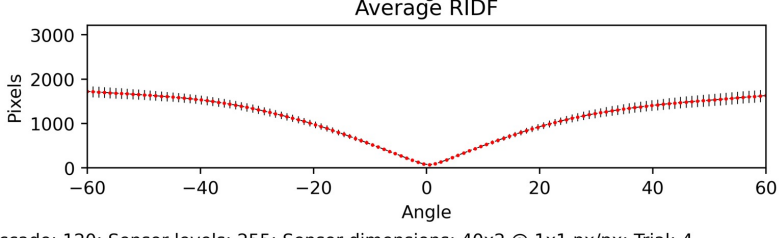
100%











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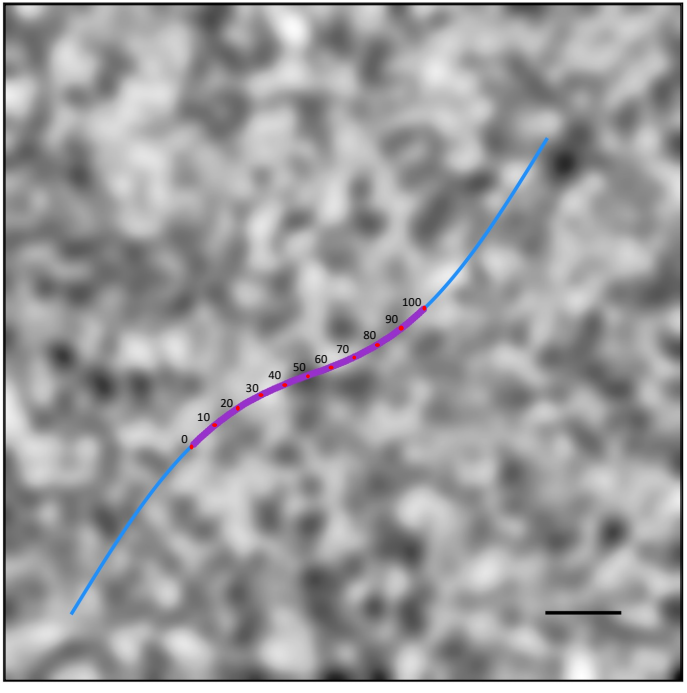
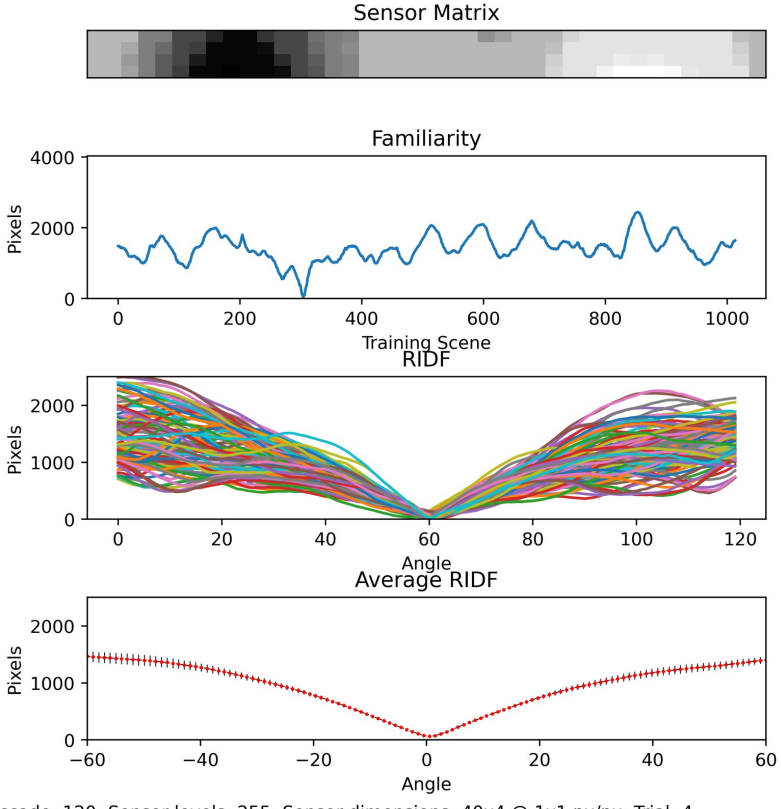
Navigation stats: RMSD error: 84.50; RMSD/dist: 0.211; TD: 1263; p90: 54; p50: 28; complete: 0

100%





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Navigation stats: RMSD error: 86.10; RMSD/dist: 0.215; TD: 1338; p90: 80; p50: 38; complete: 0

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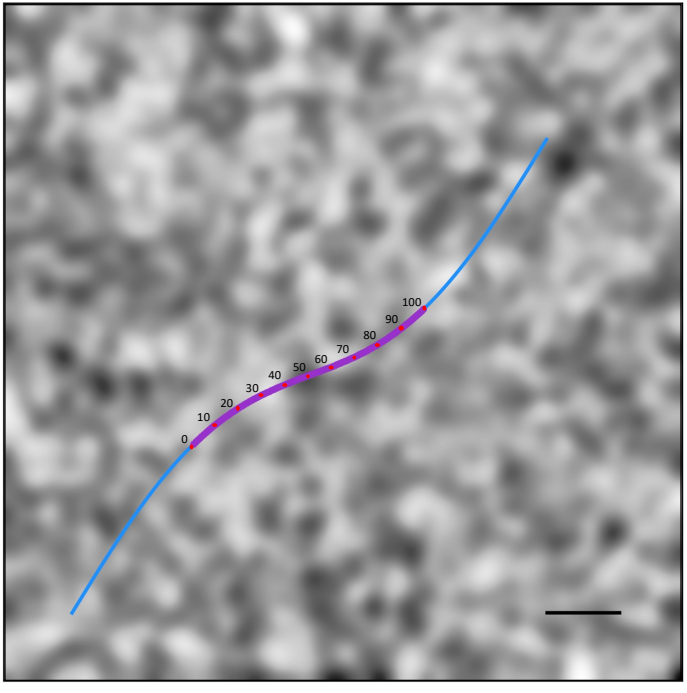

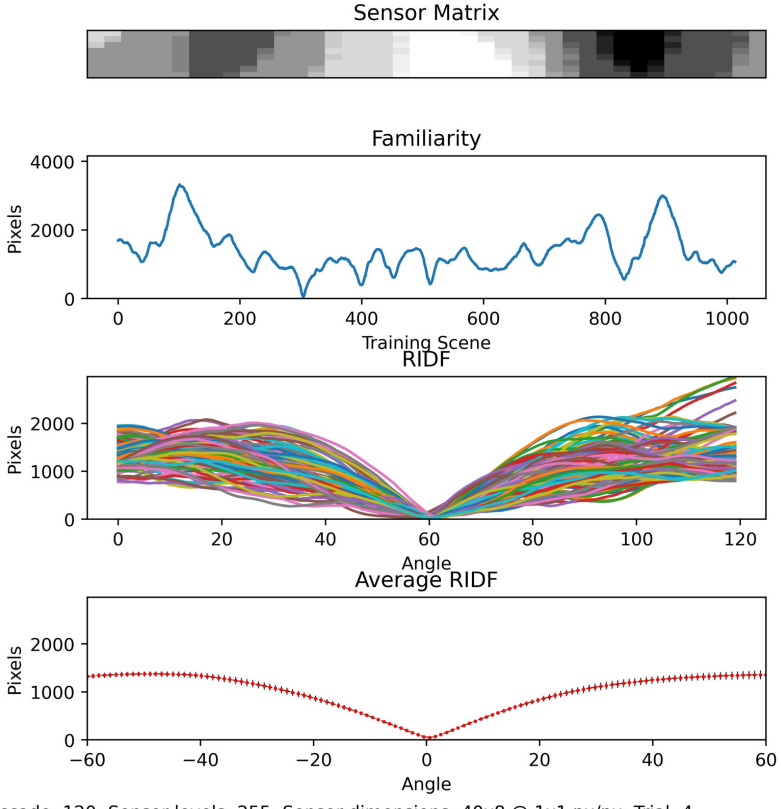

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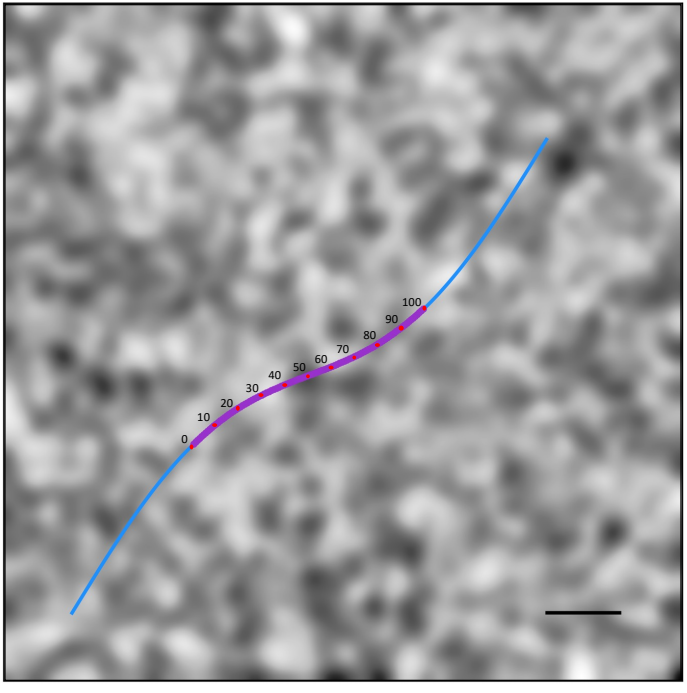
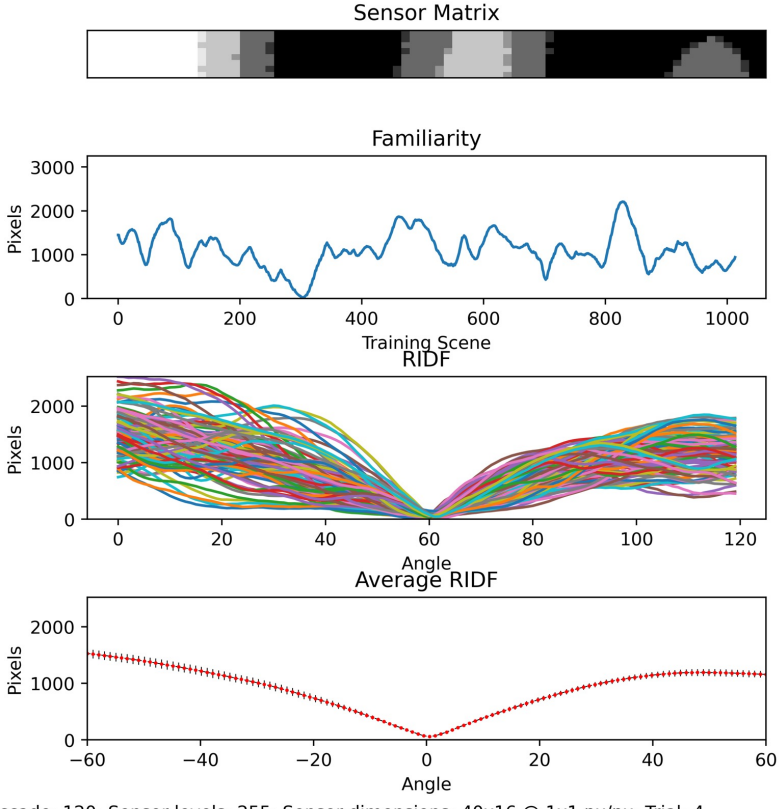
100%





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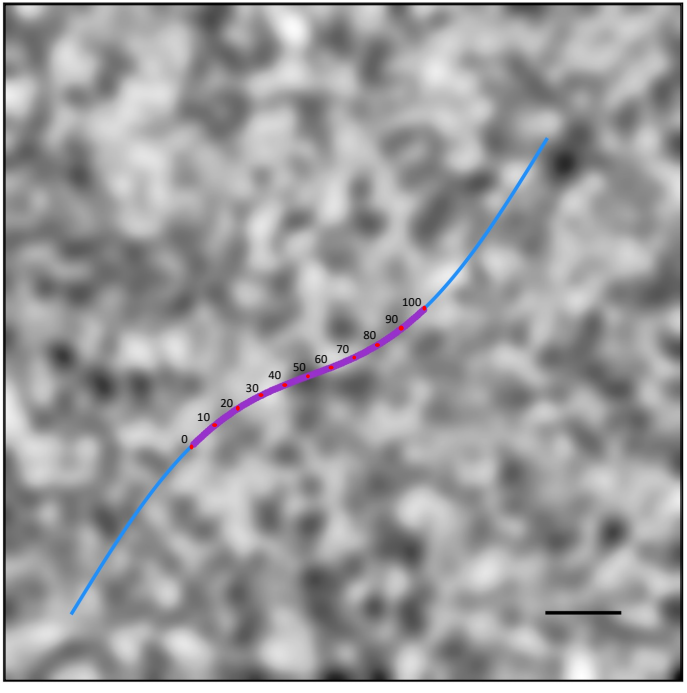
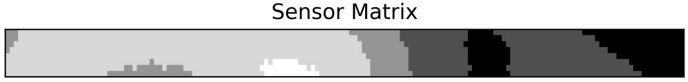
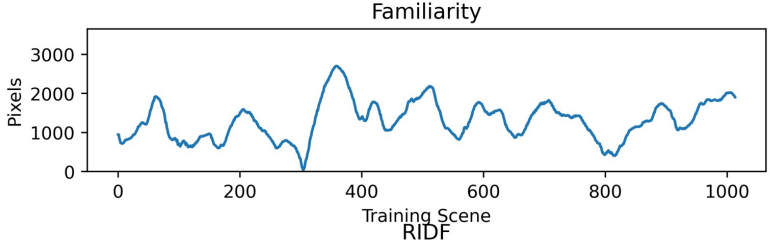
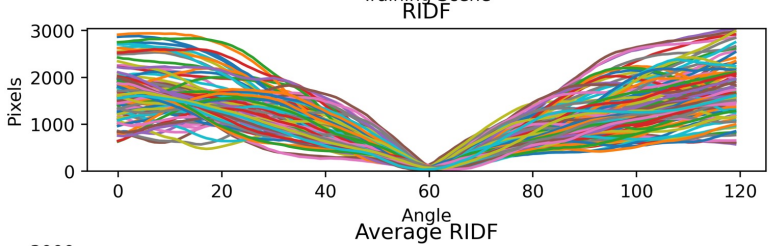
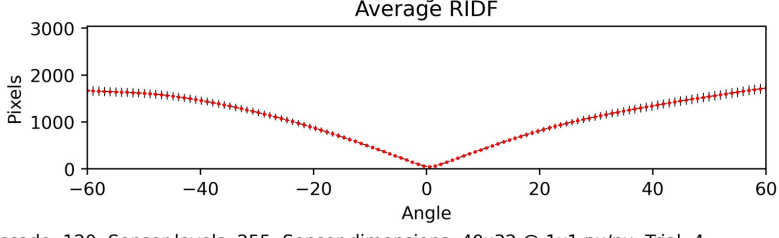
100%











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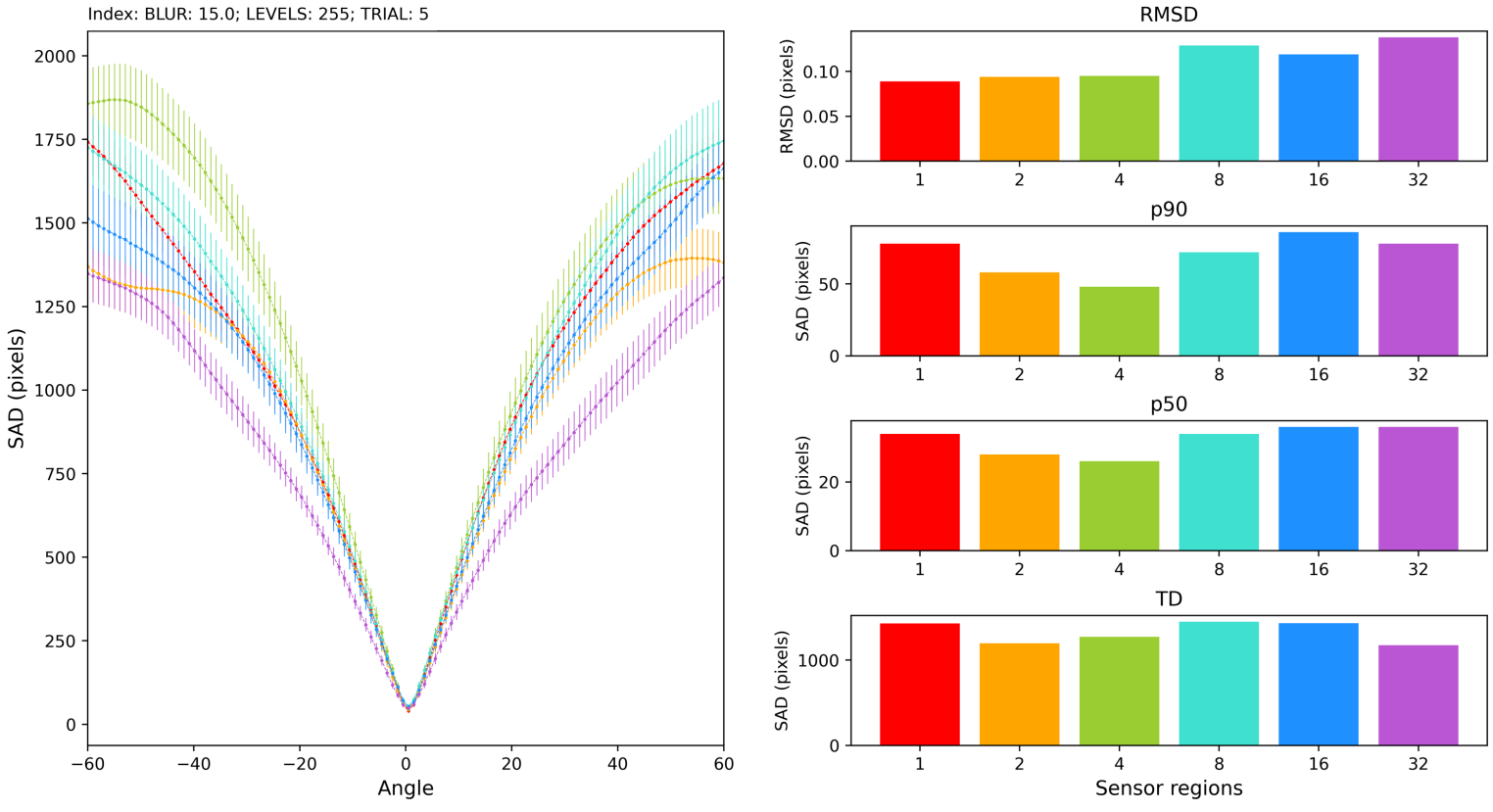
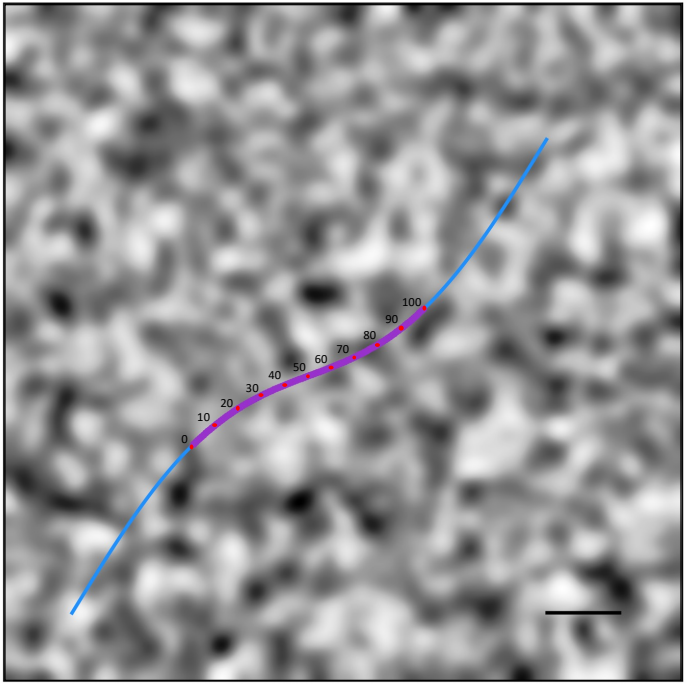
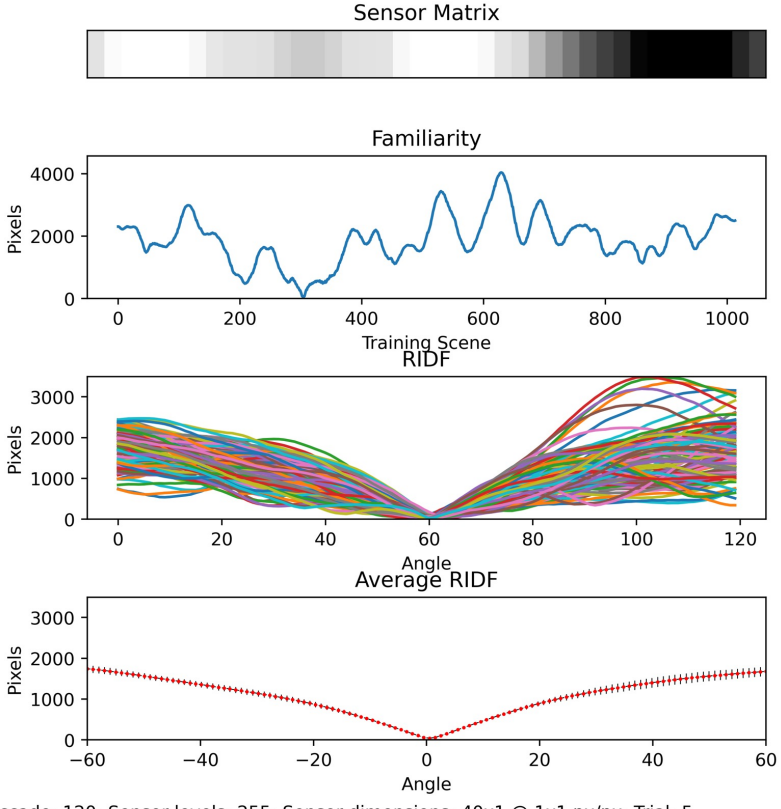

Index: BLUR: 15.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%





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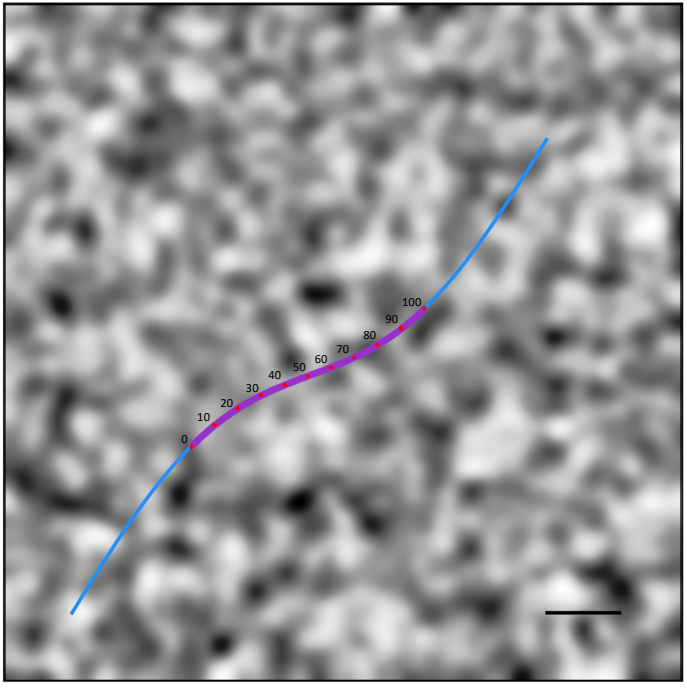
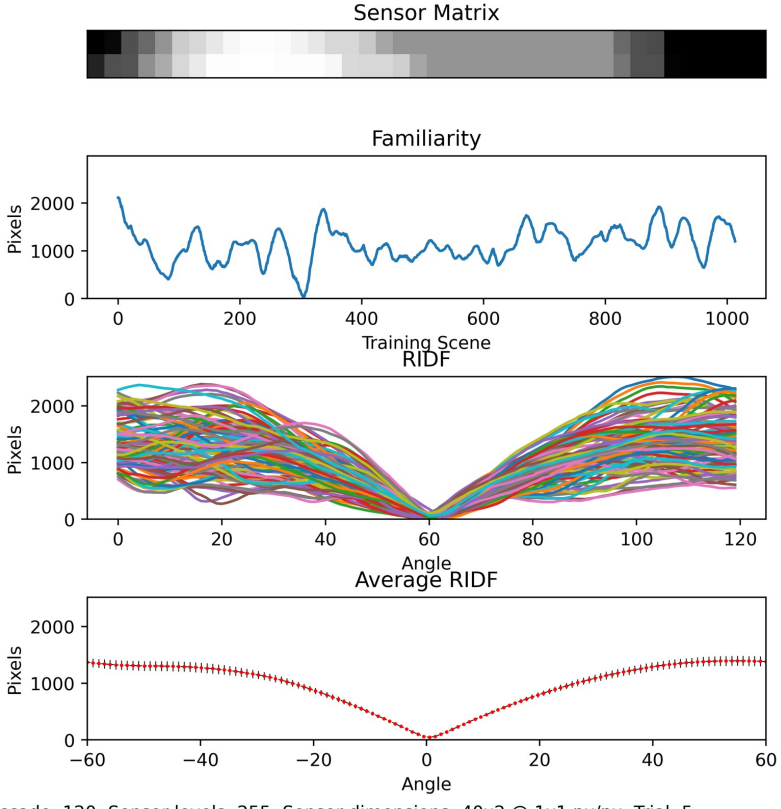
Navigation stats: RMSD error: 35.50; RMSD/dist: 0.089; TD: 1431; p90: 78; p50: 34; complete: 0

100%





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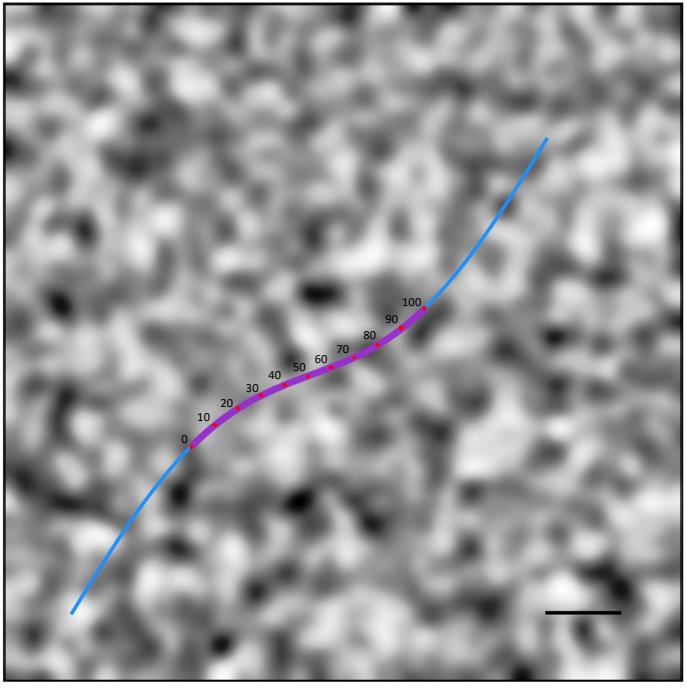
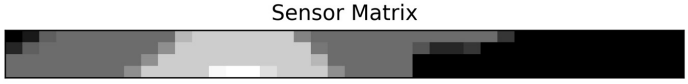
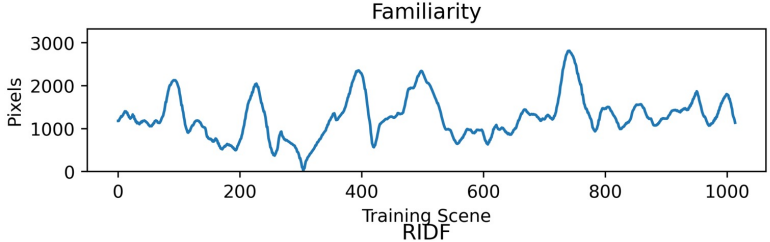
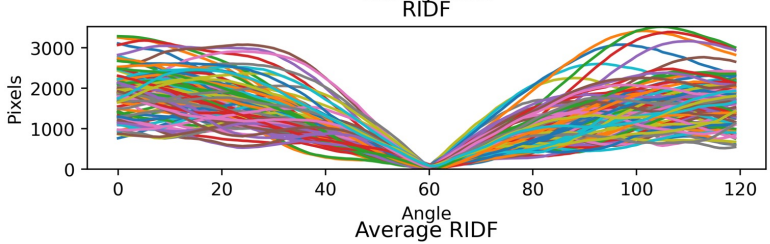
Navigation stats: RMSD error: 37.42; RMSD/dist: 0.094; TD: 1197; p90: 58; p50: 28; complete: 0

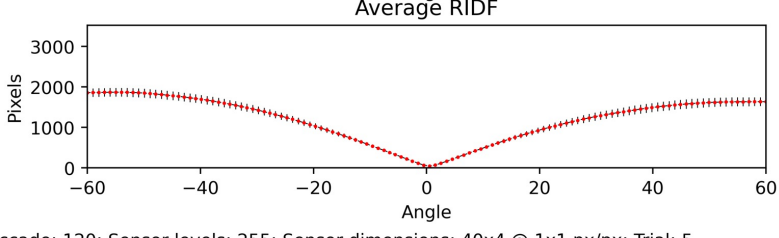
100%





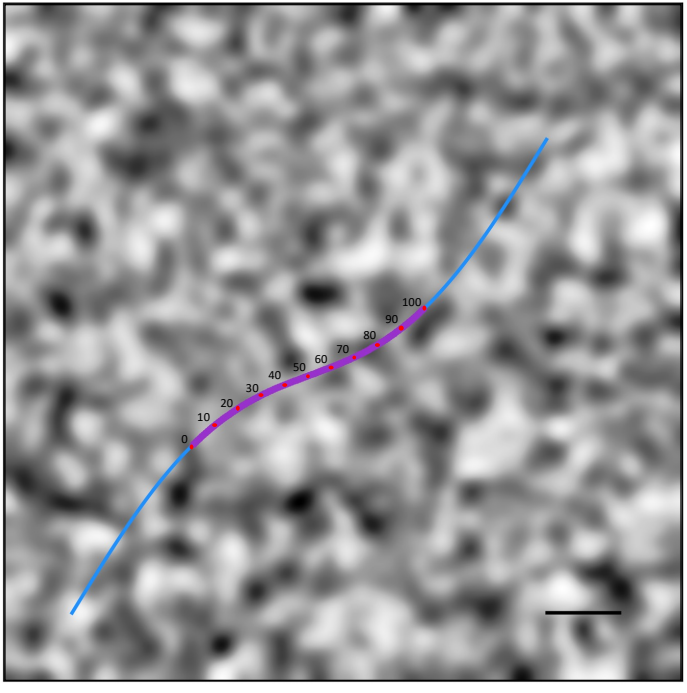


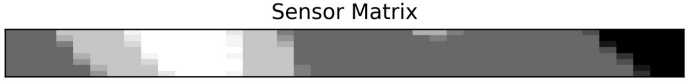


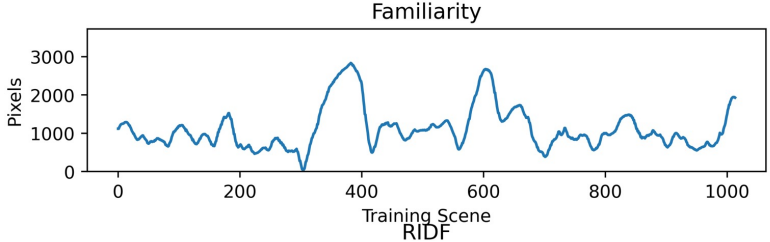


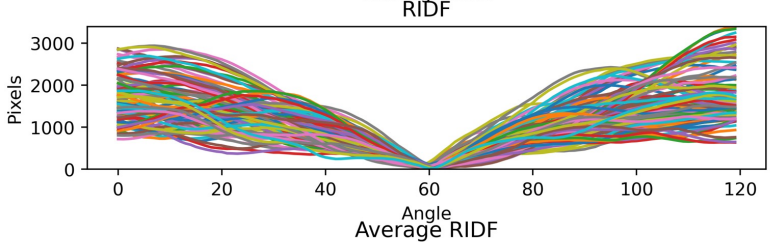
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 37.82; RMSD/dist: 0.095; TD: 1275; p90: 48; p50: 26; complete: 0

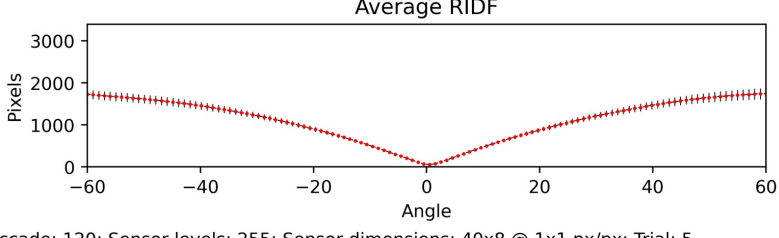
100%





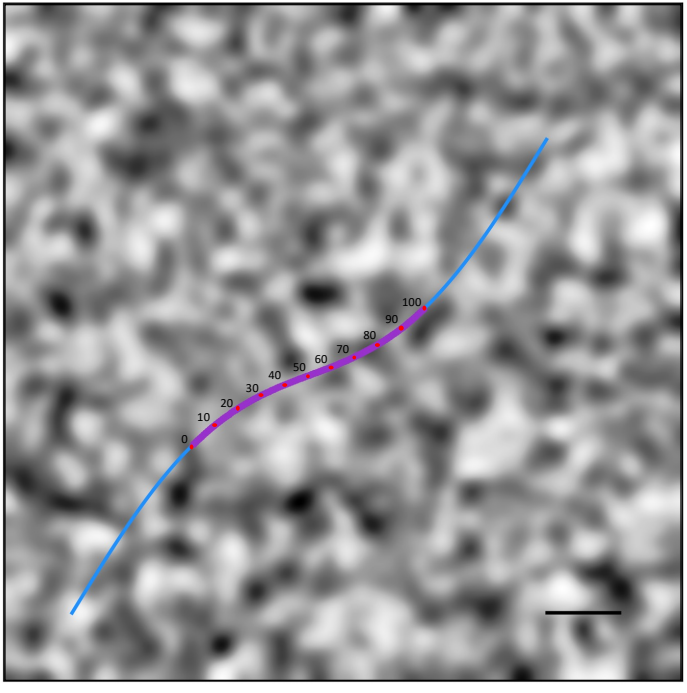


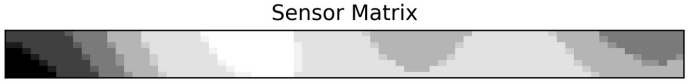


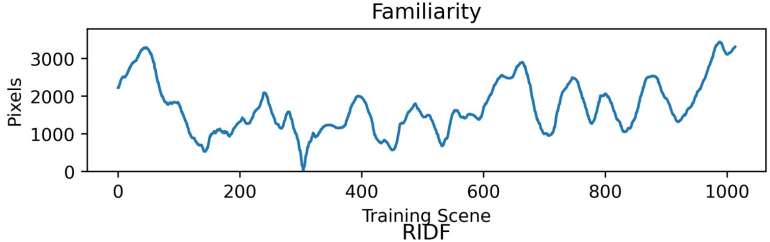


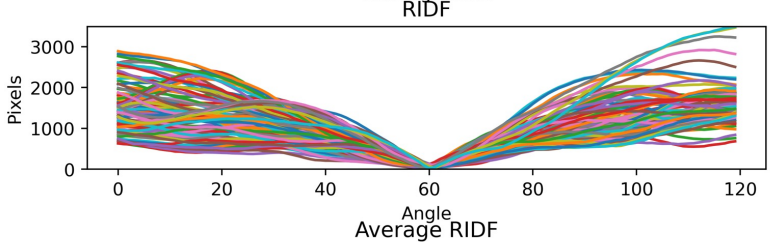
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 51.68; RMSD/dist: 0.129; TD: 1451; p90: 72; p50: 34; complete: 0

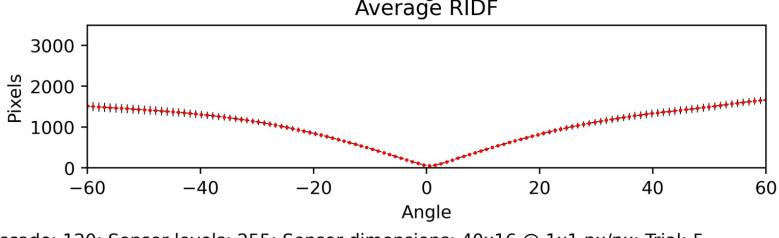
100%





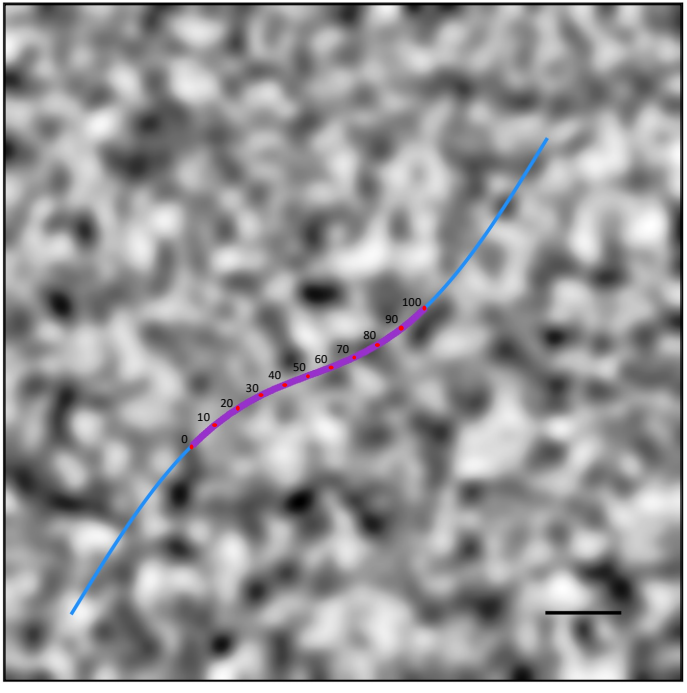


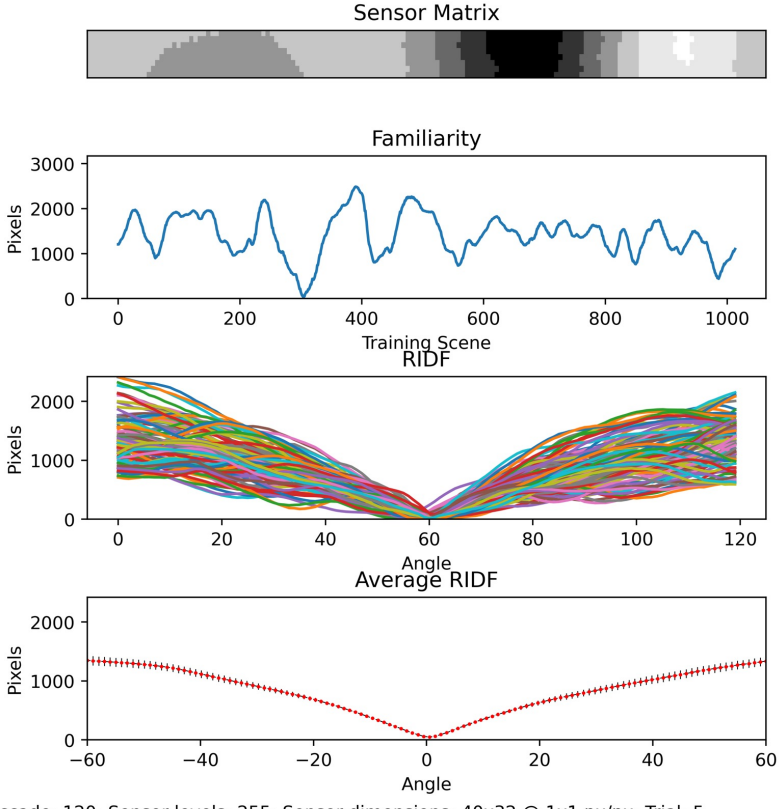




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 47.41; RMSD/dist: 0.119; TD: 1435; p90: 86; p50: 36; complete: 0

100%





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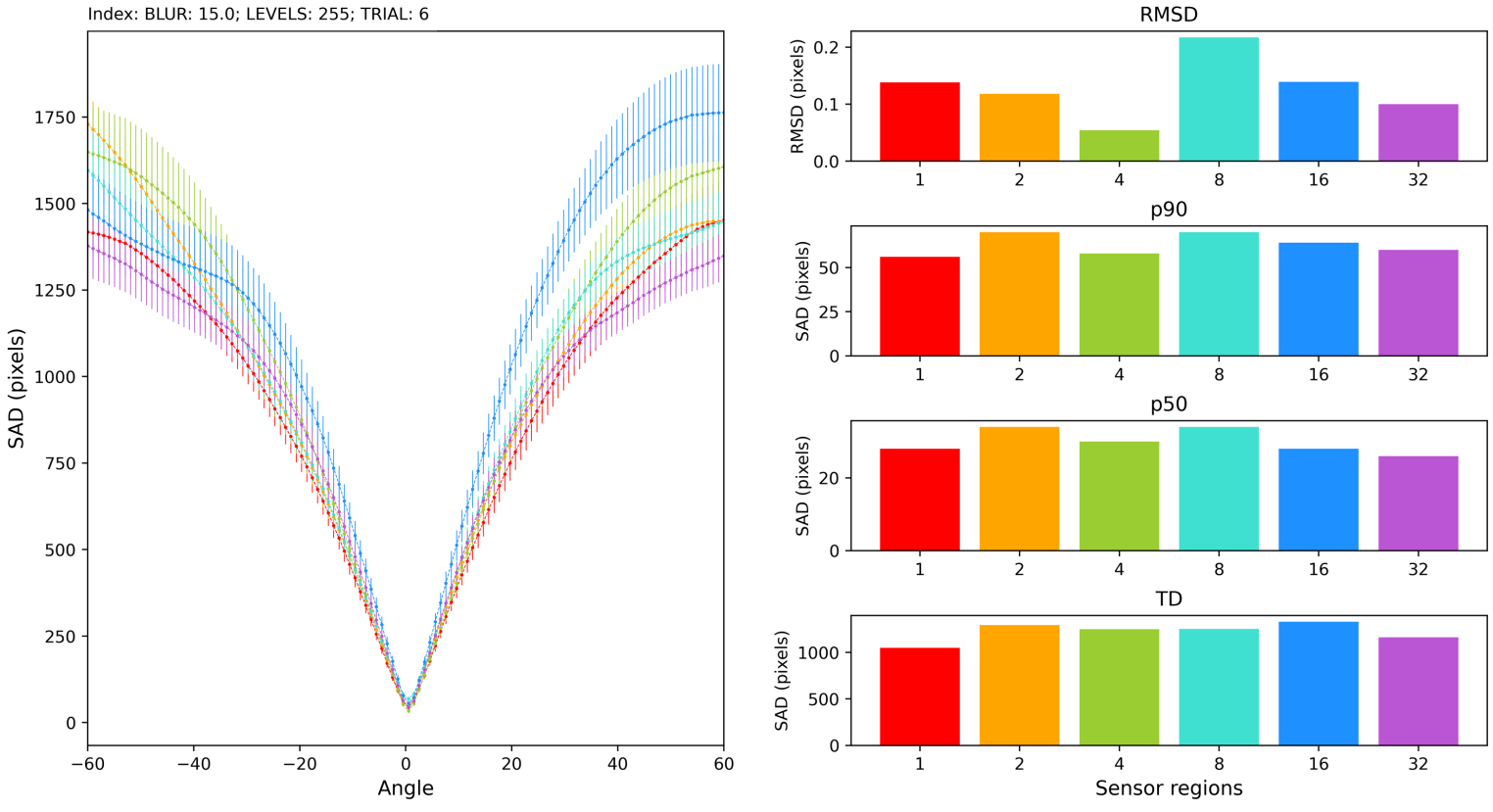
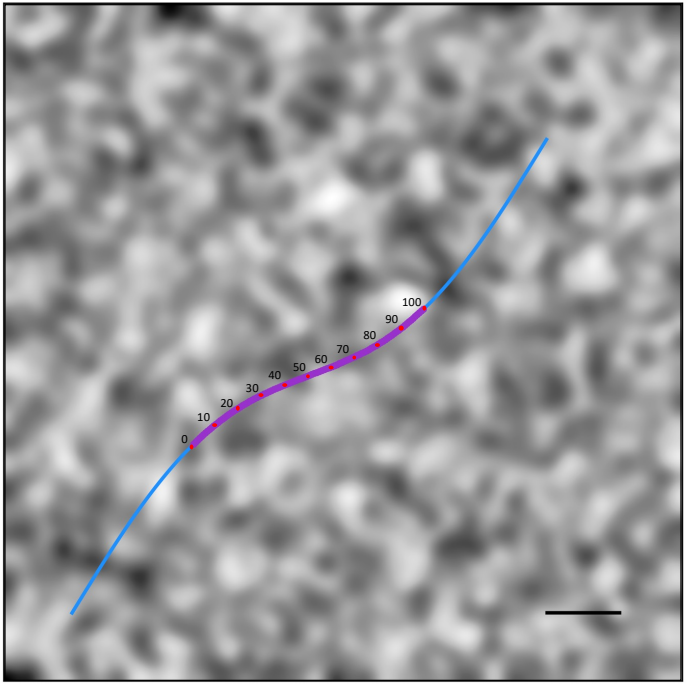
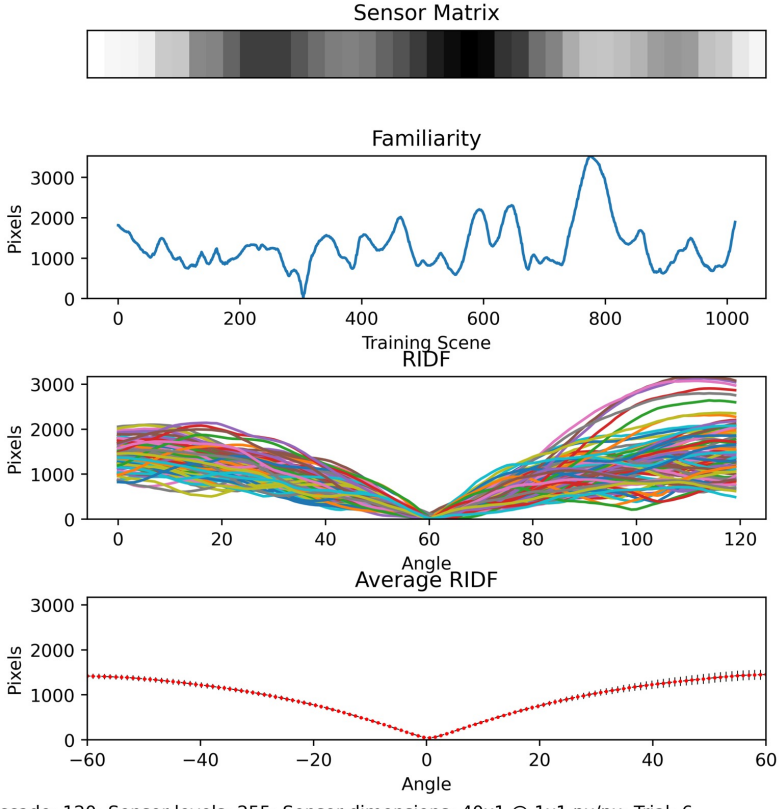
Navigation stats: RMSD error: 55.06; RMSD/dist: 0.138; TD: 1176; p90: 78; p50: 36; complete: 0


Index: BLUR: 15.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

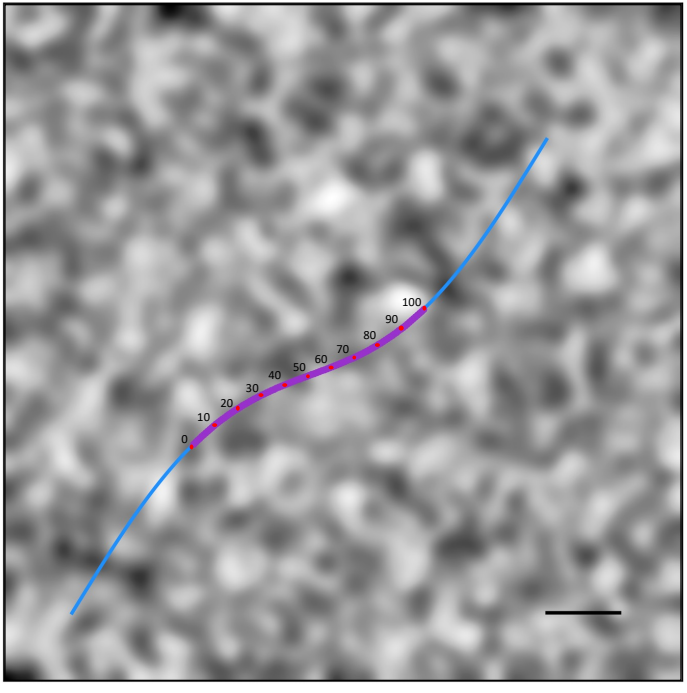
100%

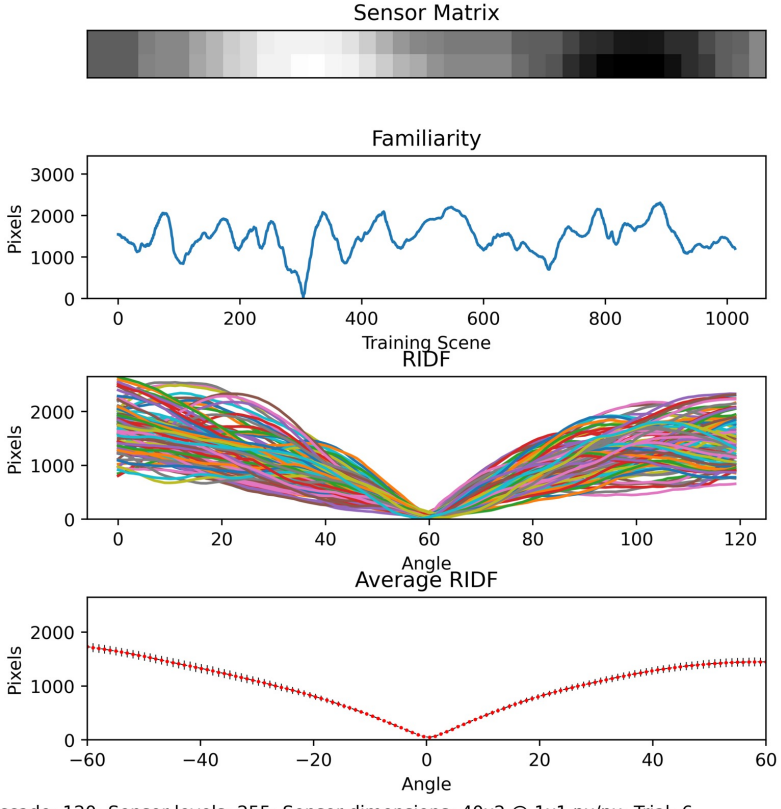




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 55.32; RMSD/dist: 0.138; TD: 1051; p90: 56; p50: 28; complete: 0

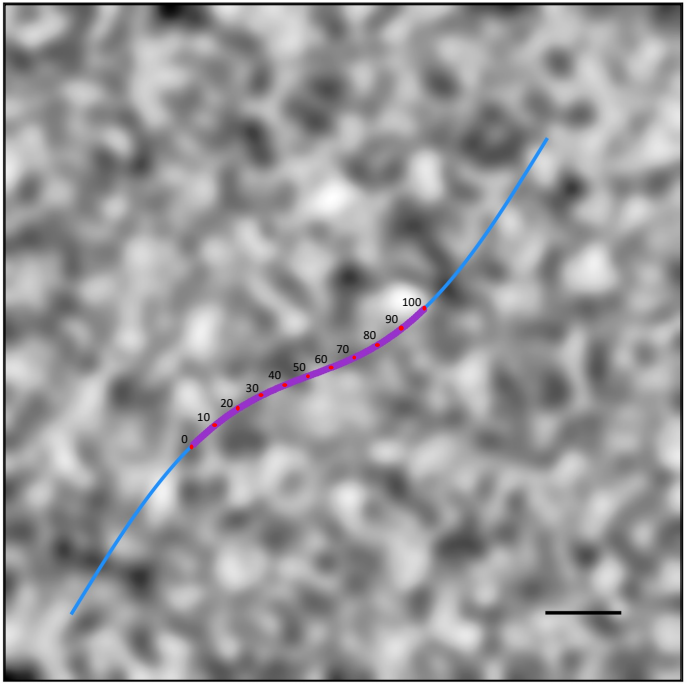
100%

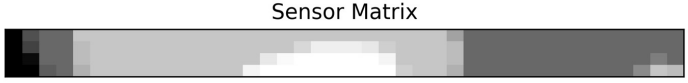


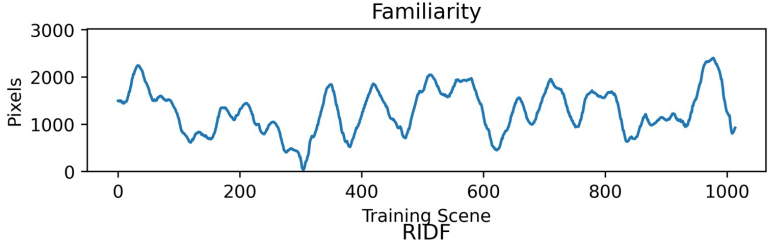


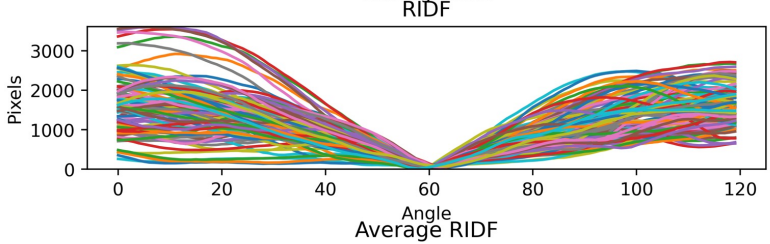
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 47.21; RMSD/dist: 0.118; TD: 1295; p90: 70; p50: 34; complete: 0

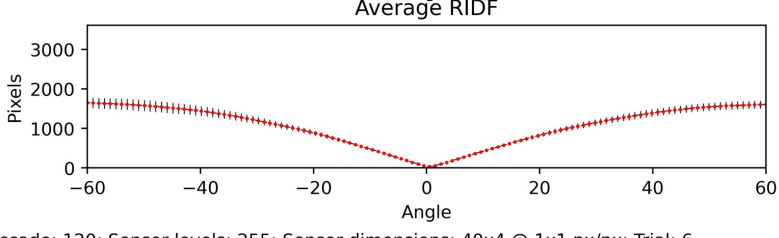
100%







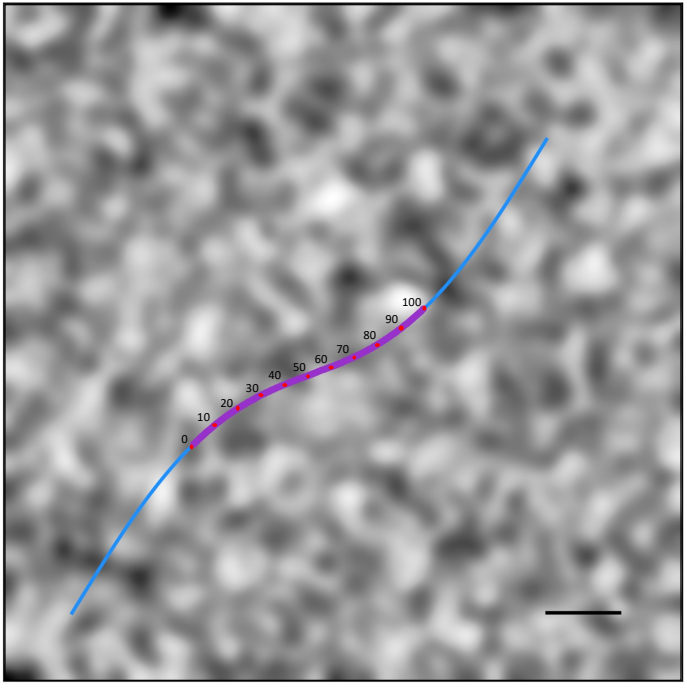


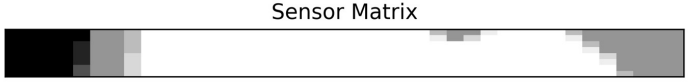


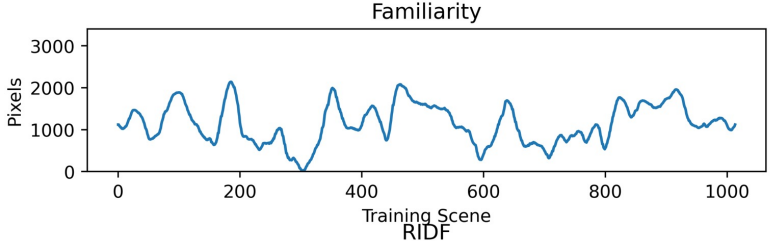
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

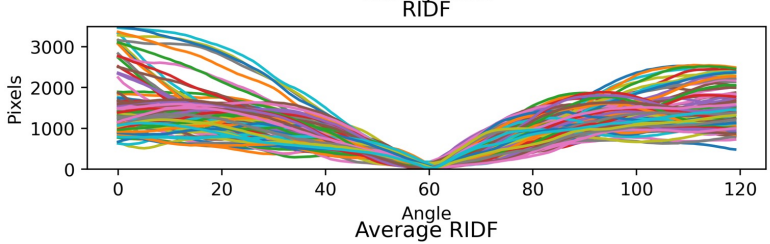
Navigation stats: RMSD error: 21.49; RMSD/dist: 0.054; TD: 1252; p90: 58; p50: 30; complete: 0

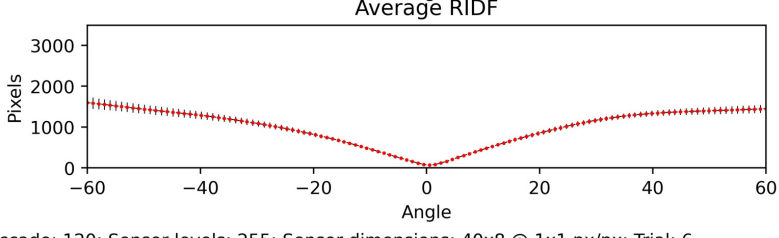
100%





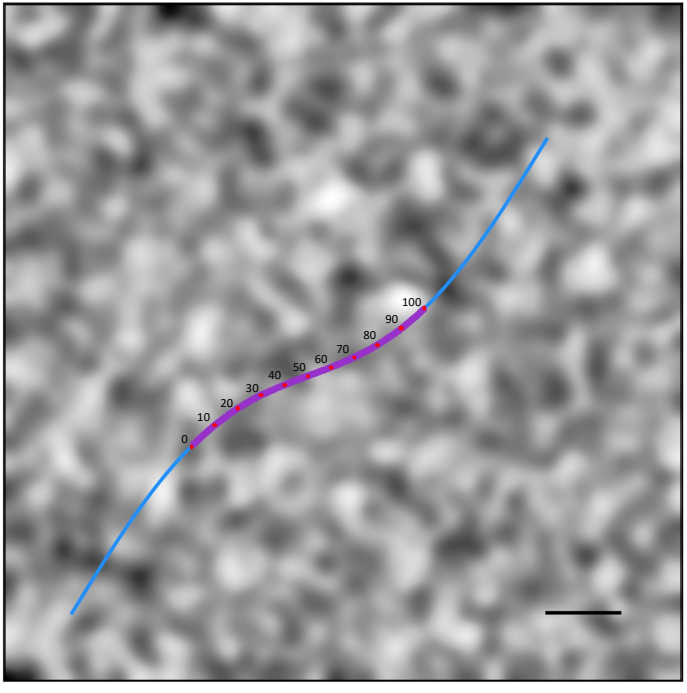


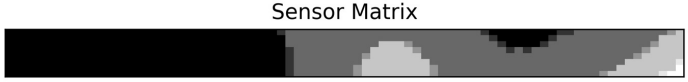


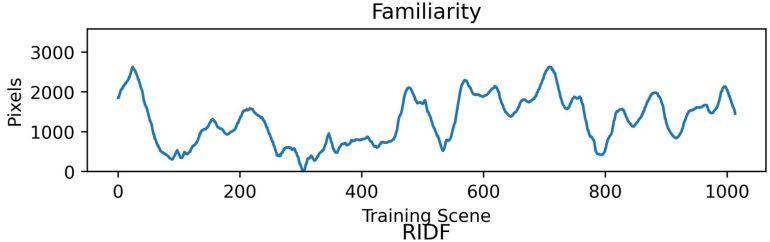


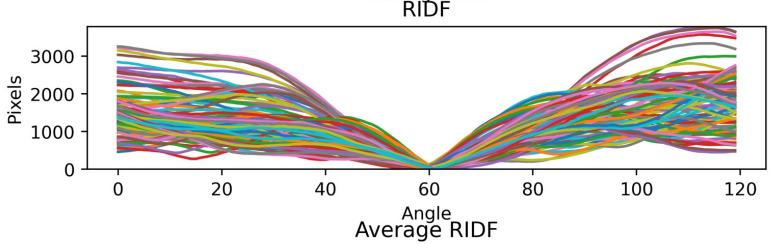
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 86.85; RMSD/dist: 0.217; TD: 1254; p90: 70; p50: 34; complete: 0

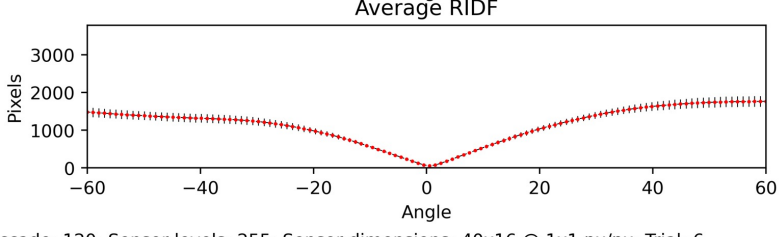
100%





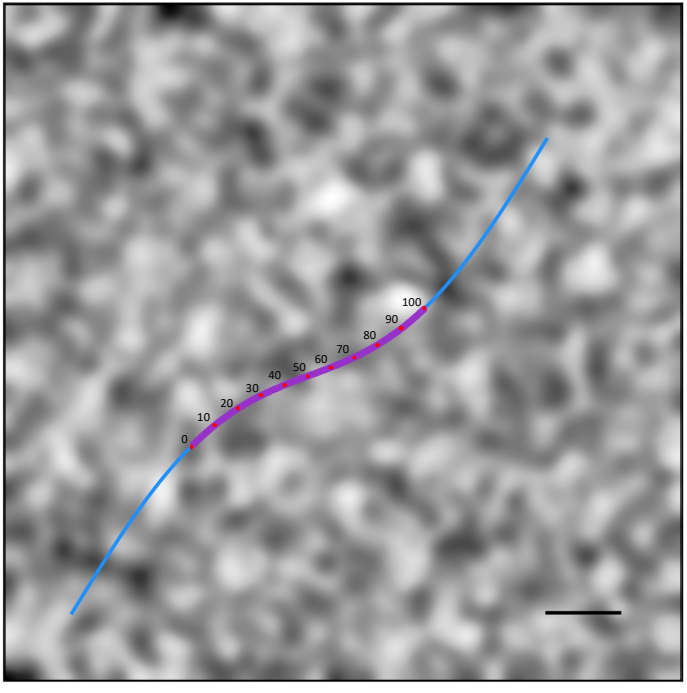


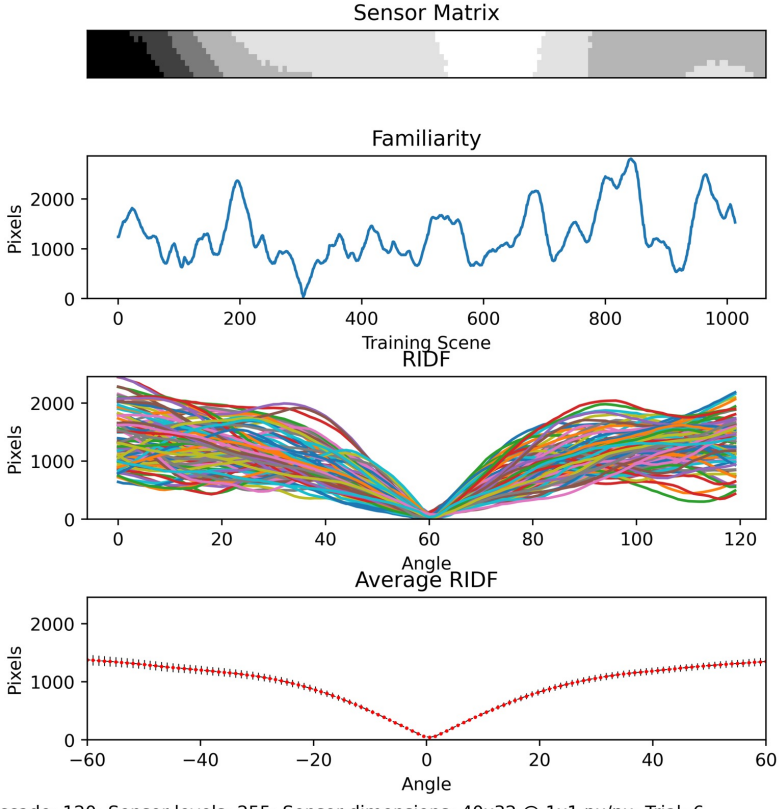




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 55.72; RMSD/dist: 0.139; TD: 1331; p90: 64; p50: 28; complete: 0

100%





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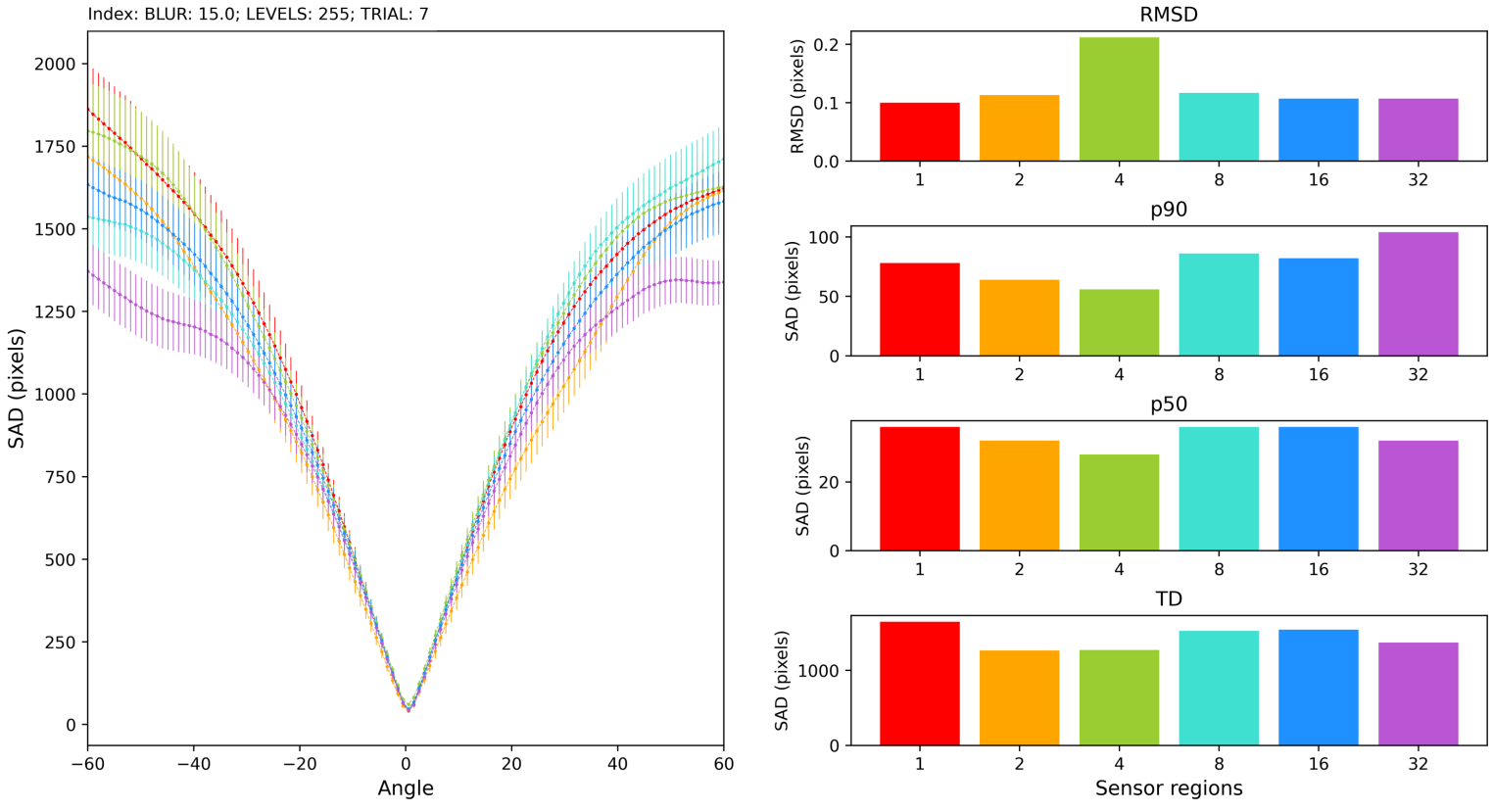
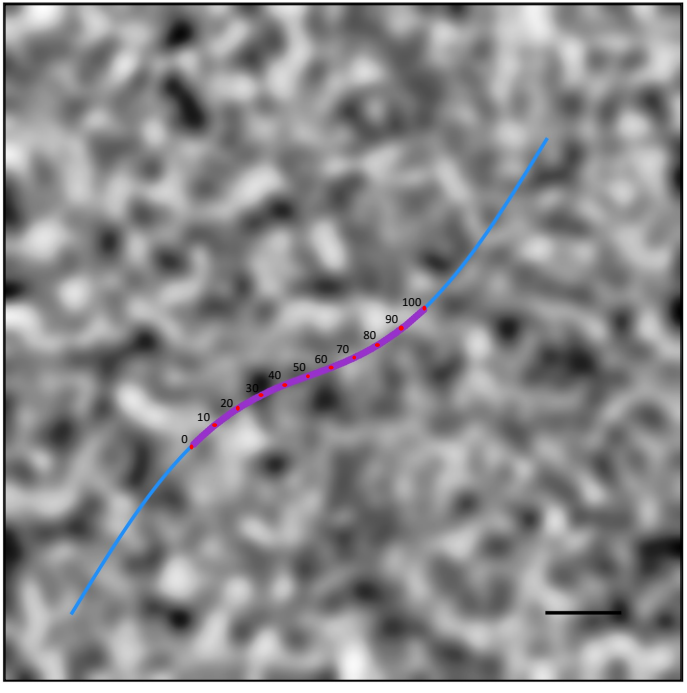
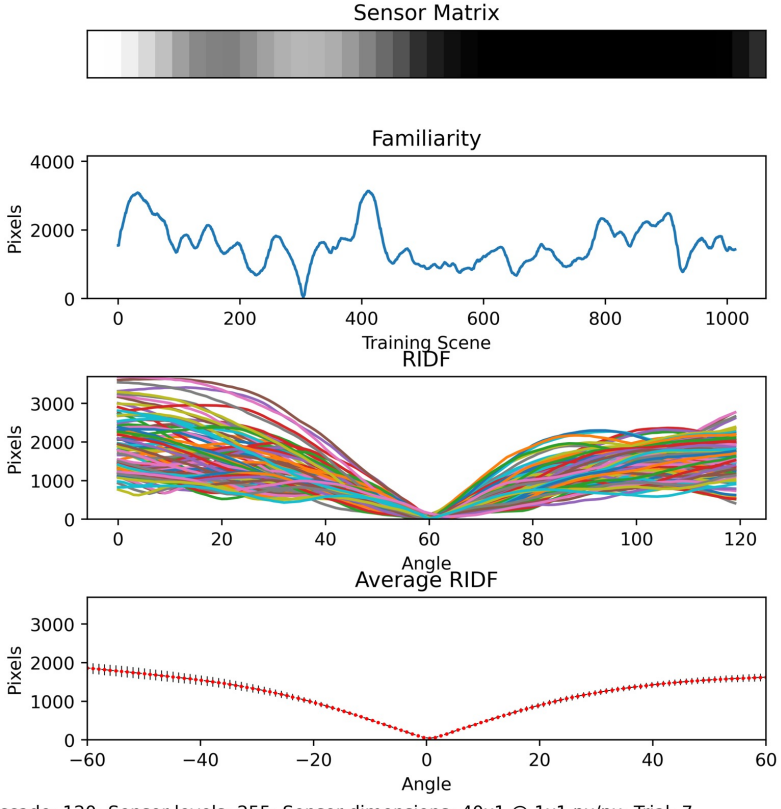

Index: BLUR: 15.0; LEVELS: 255; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%





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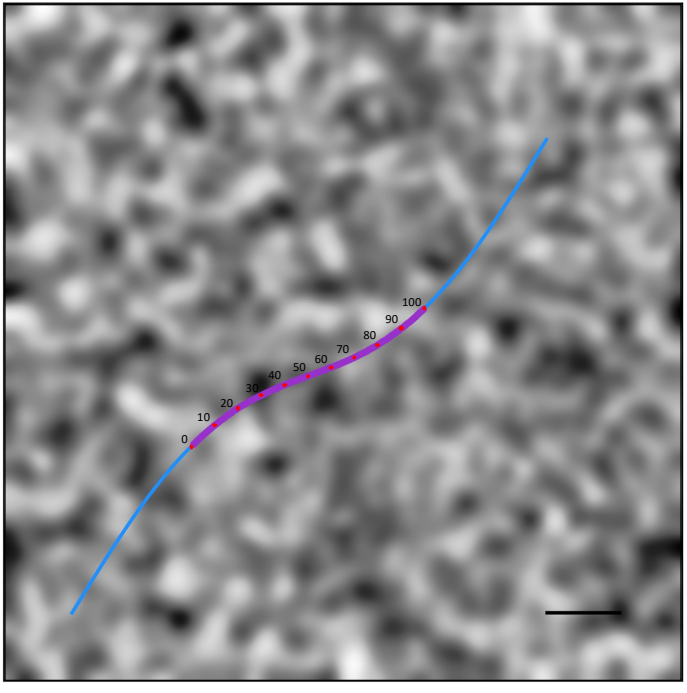
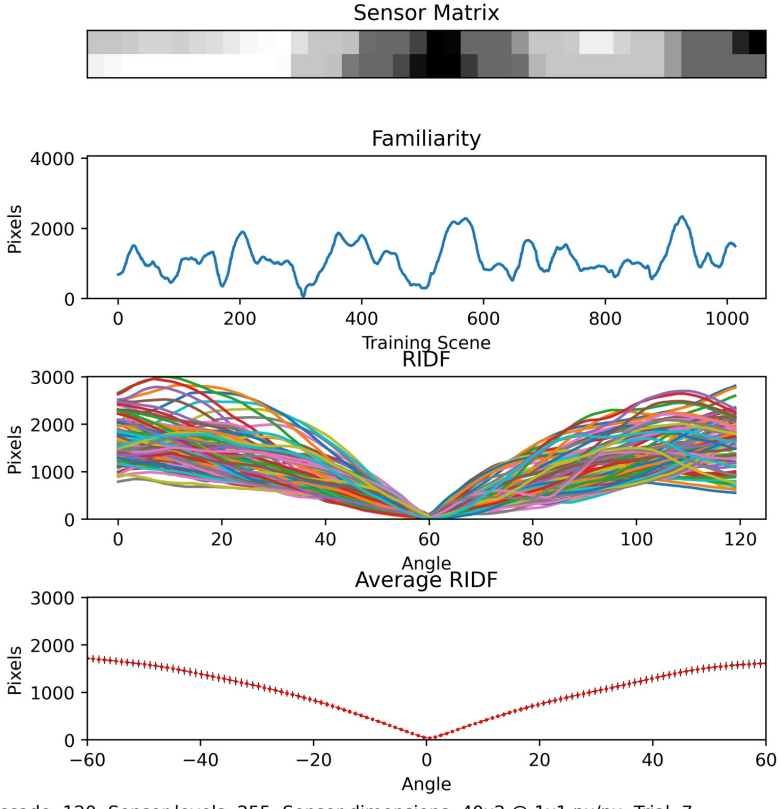
Navigation stats: RMSD error: 39.93; RMSD/dist: 0.100; TD: 1647; p90: 78; p50: 36; complete: 0

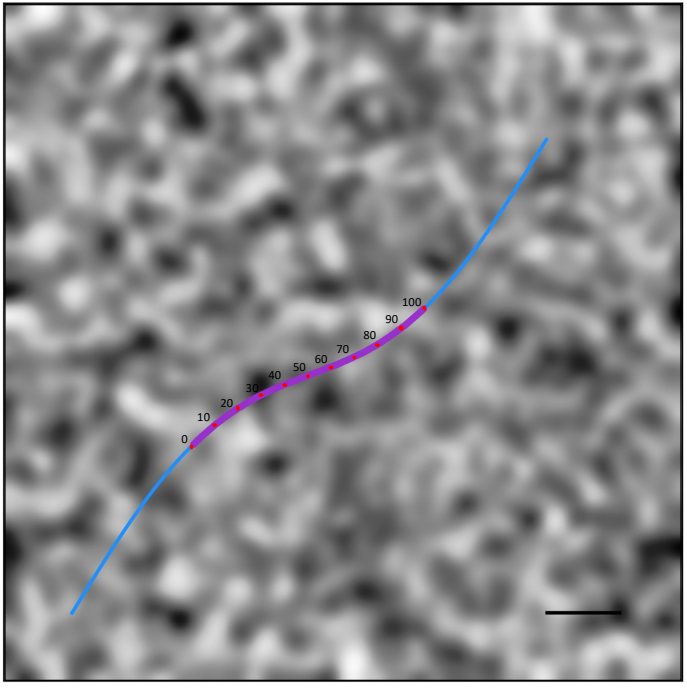
100%

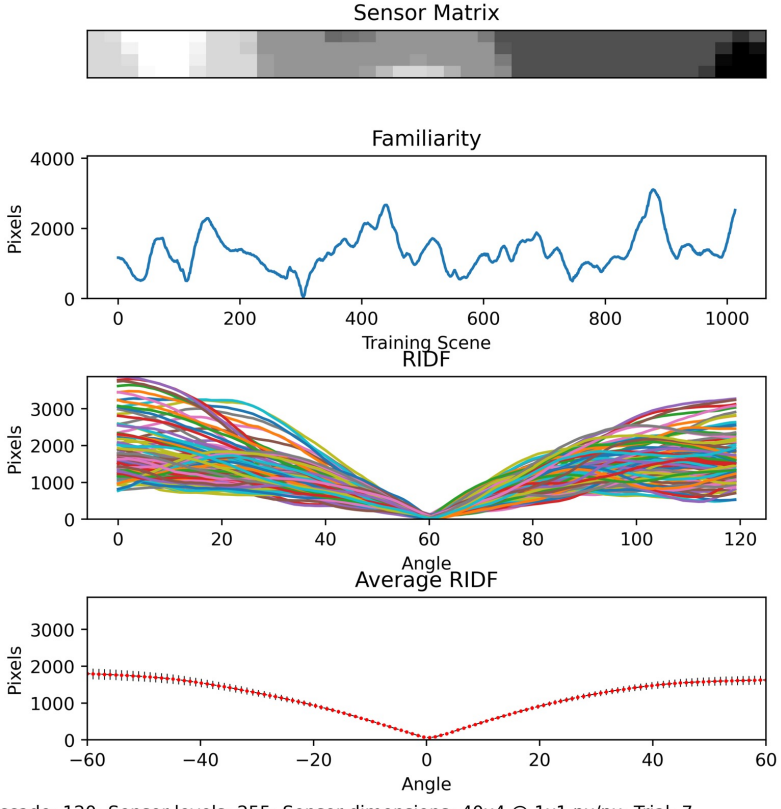




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 45.05; RMSD/dist: 0.113; TD: 1263; p90: 64; p50: 32; complete: 0

100%





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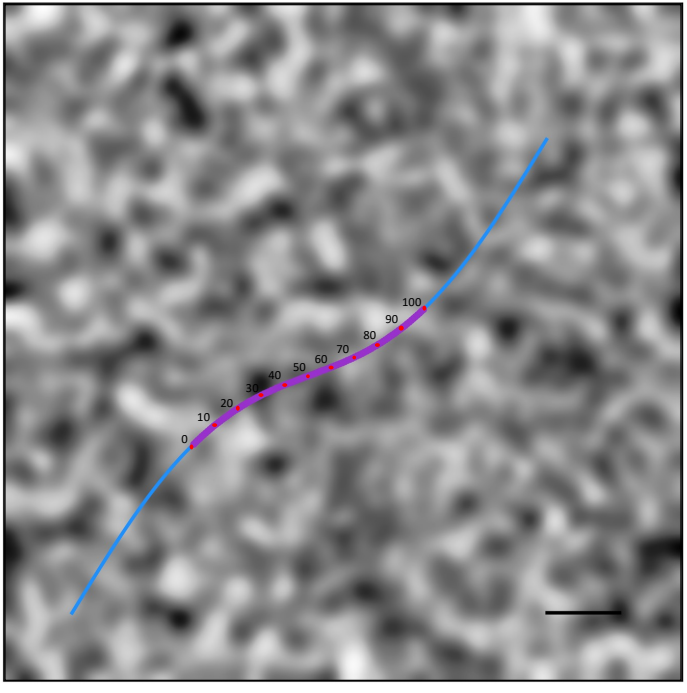
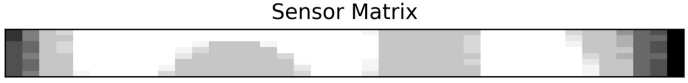
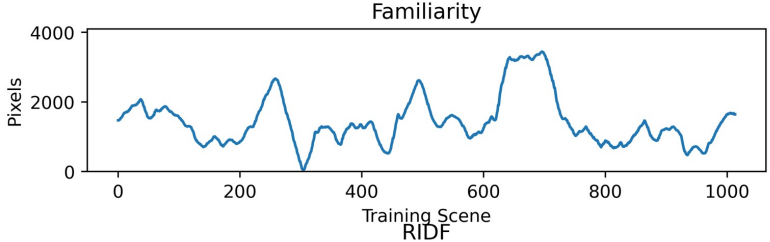
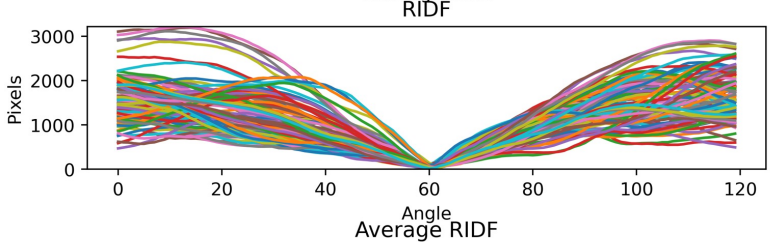
Navigation stats: RMSD error: 84.62; RMSD/dist: 0.212; TD: 1272; p90: 56; p50: 28; complete: 0

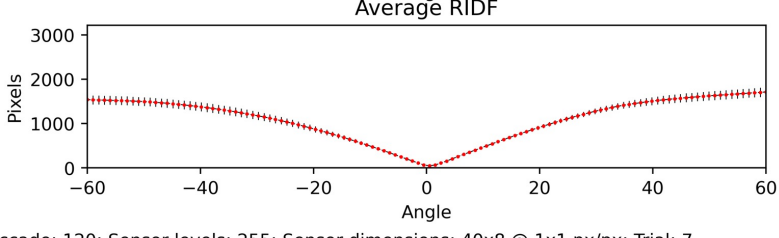
100%





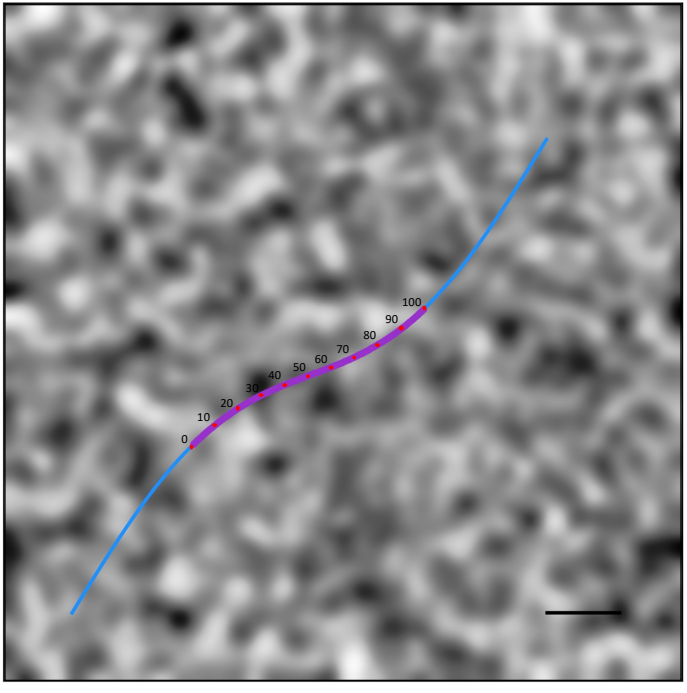


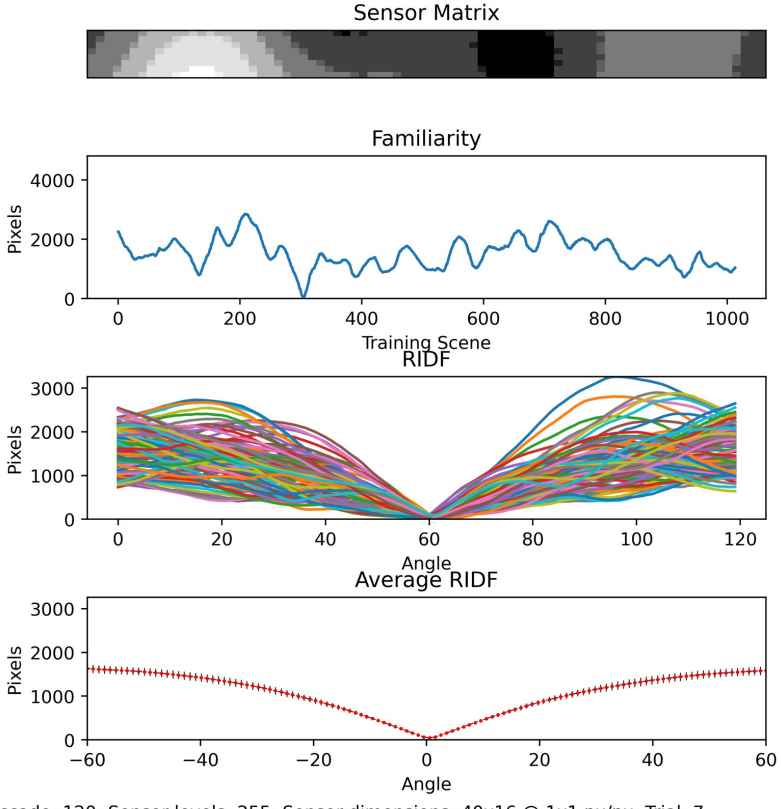




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 46.99; RMSD/dist: 0.117; TD: 1524; p90: 86; p50: 36; complete: 0

100%

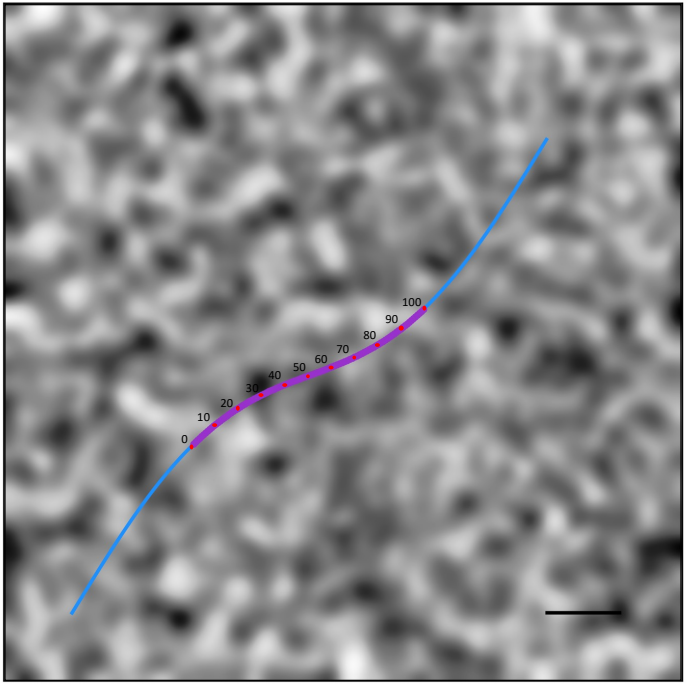


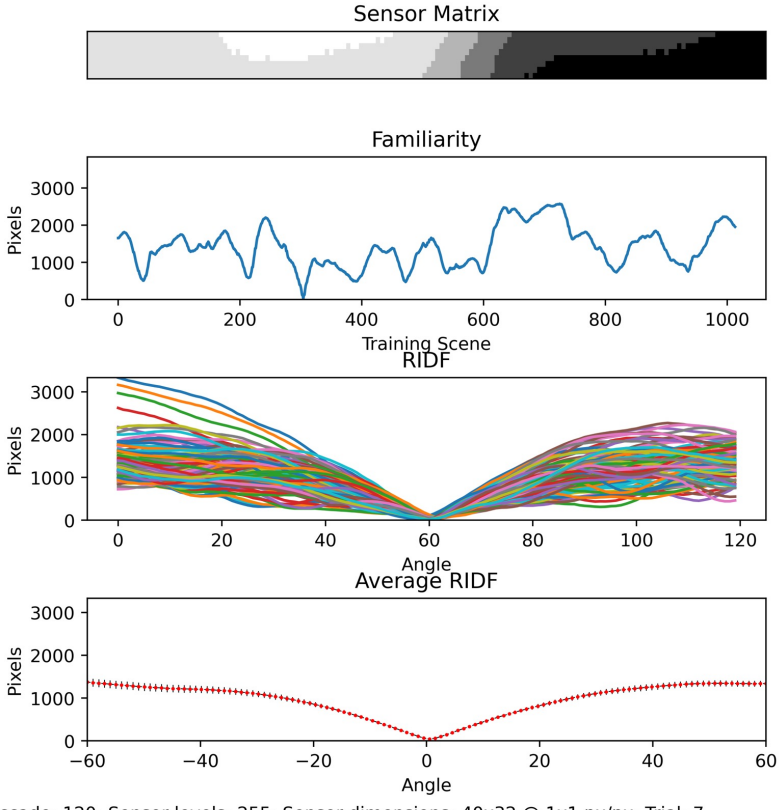


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

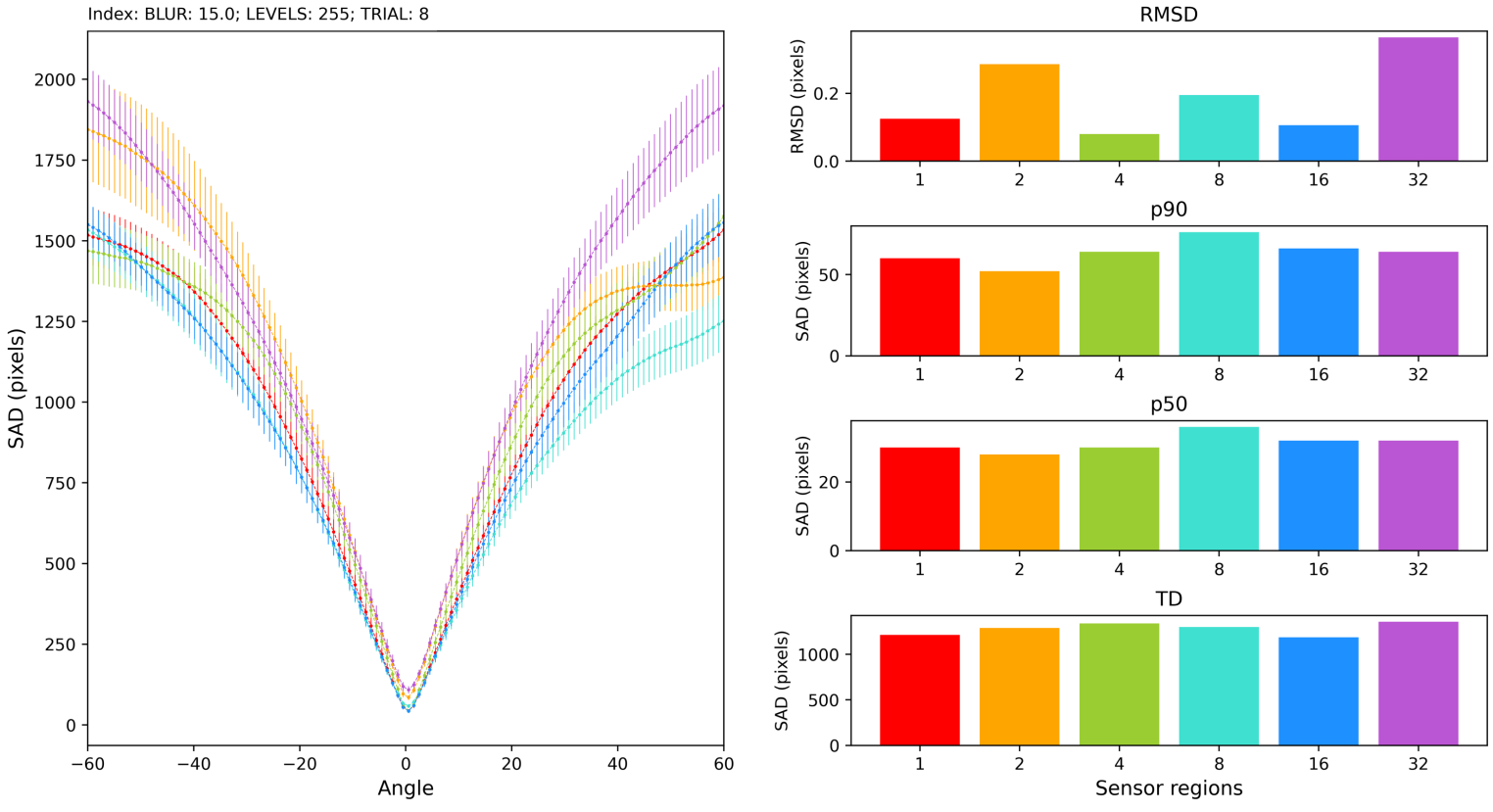
Navigation stats: RMSD error: 42.98; RMSD/dist: 0.107; TD: 1542; p90: 82; p50: 36; complete: 0

100%

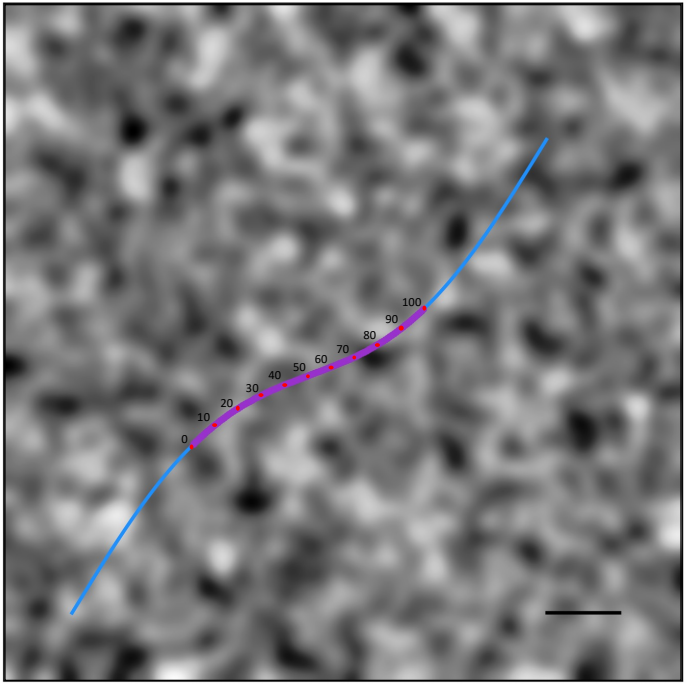


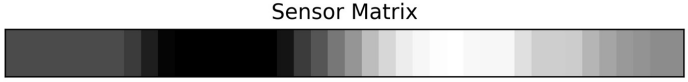


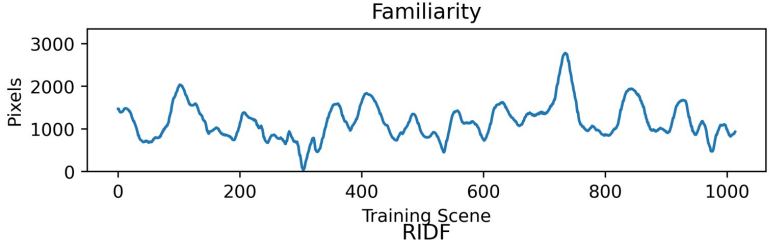
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 42.69; RMSD/dist: 0.107; TD: 1370; p90: 104; p50: 32; complete: 0

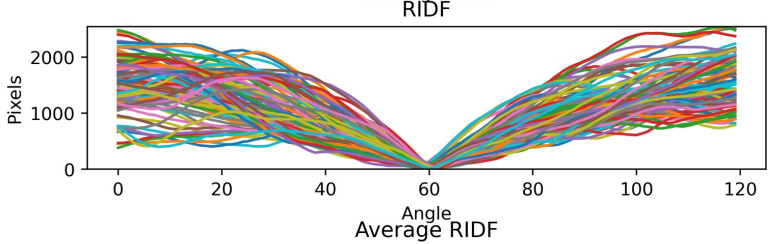

Index: BLUR: 15.0; LEVELS: 255; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

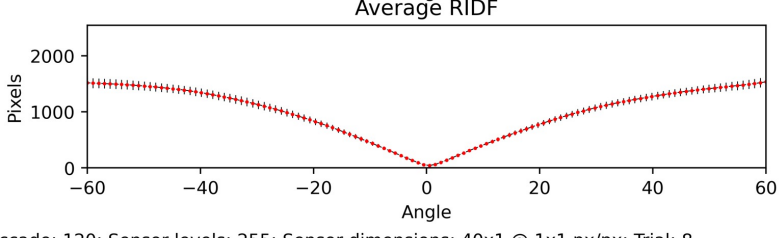
100%





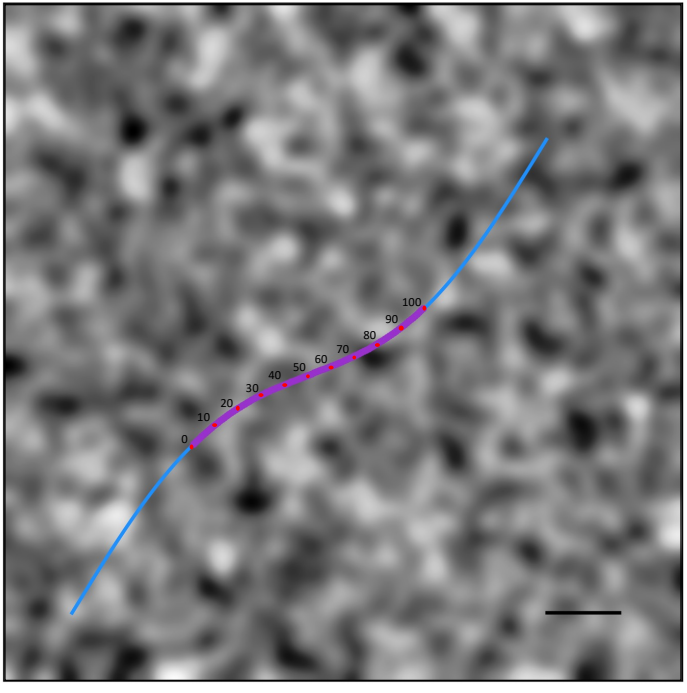


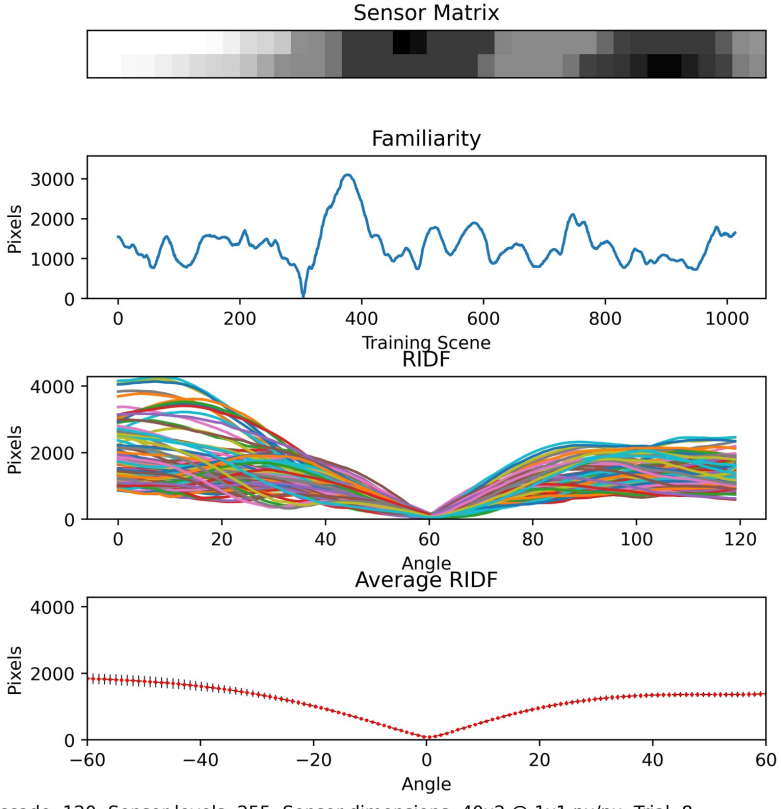




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 49.97; RMSD/dist: 0.125; TD: 1214; p90: 60; p50: 30; complete: 0

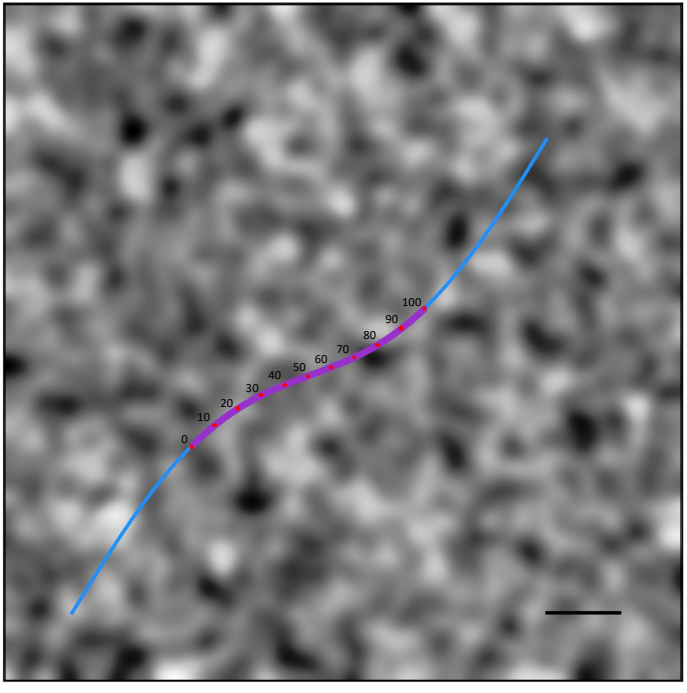
100%

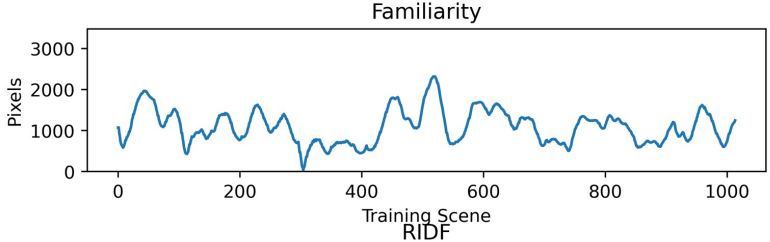


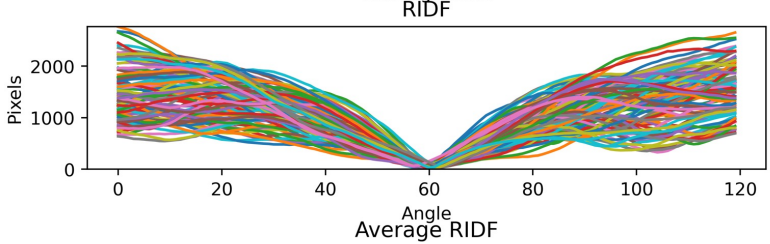


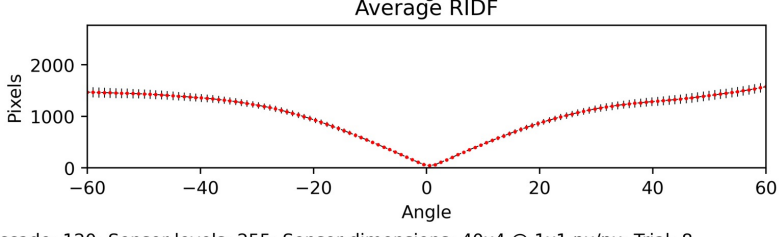
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 114.37; RMSD/dist: 0.286; TD: 1289; p90: 52; p50: 28; complete: 0

100%



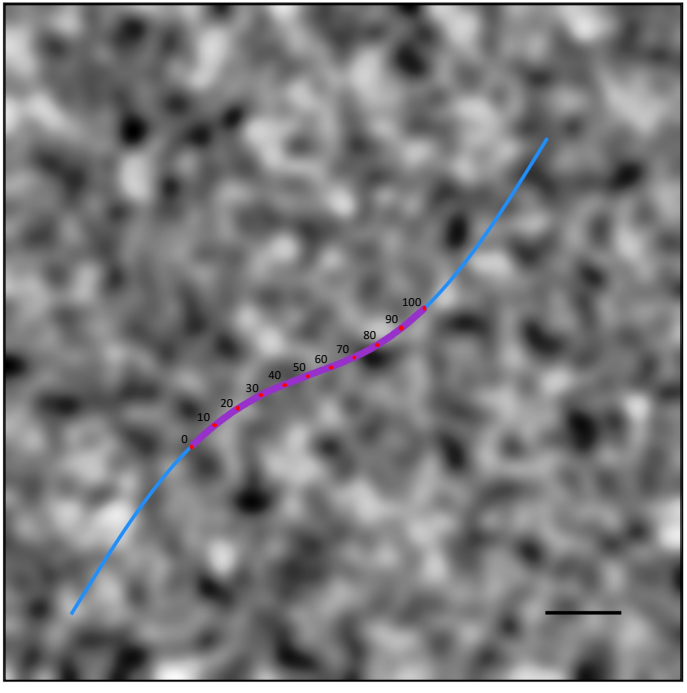


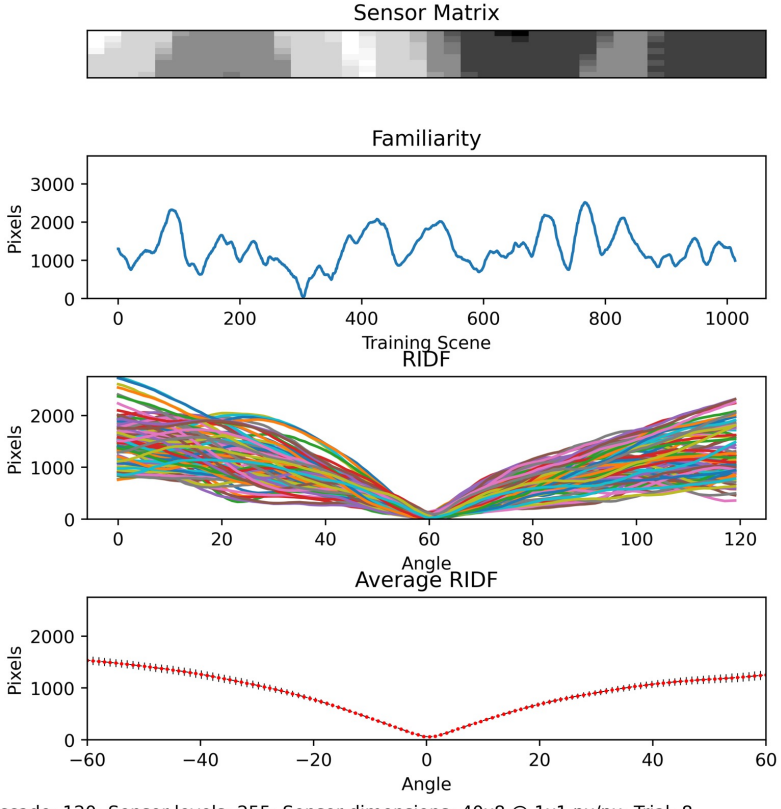




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 32.10; RMSD/dist: 0.080; TD: 1340; p90: 64; p50: 30; complete: 0

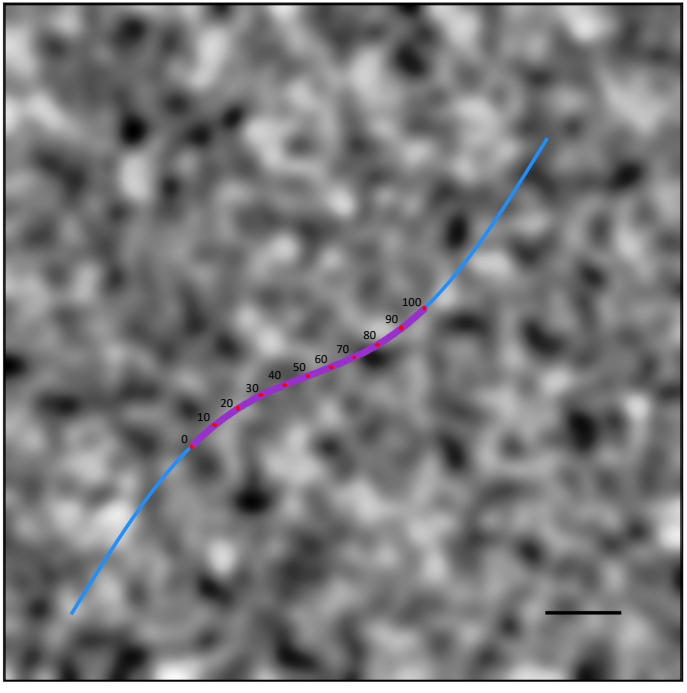
100%

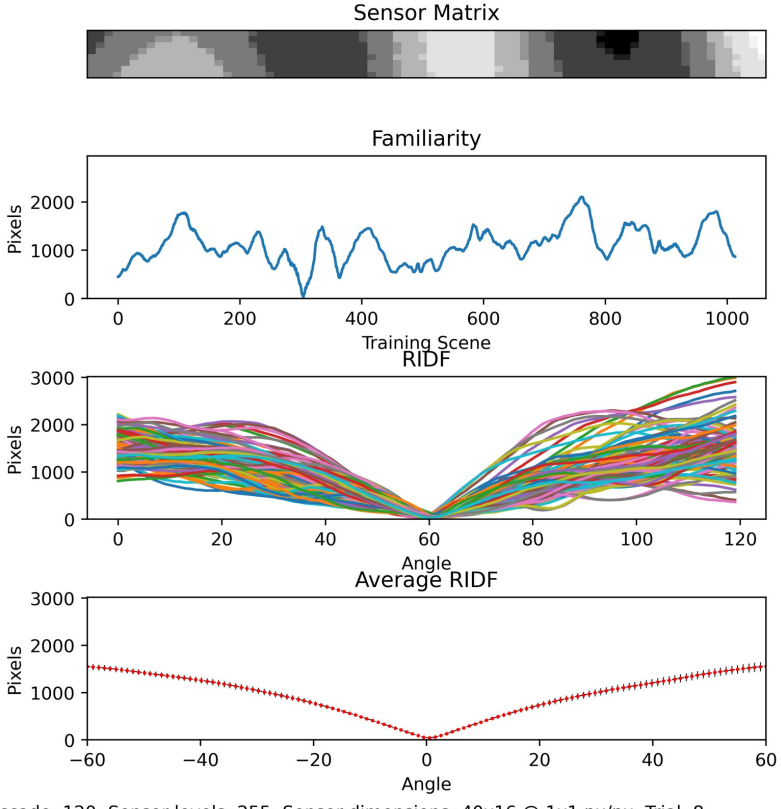




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 78.15; RMSD/dist: 0.195; TD: 1300; p90: 76; p50: 36; complete: 0

100%

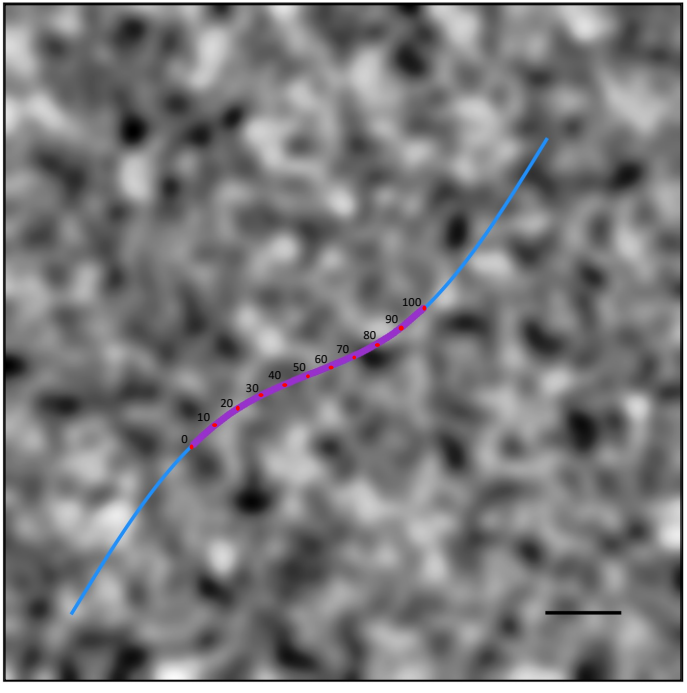


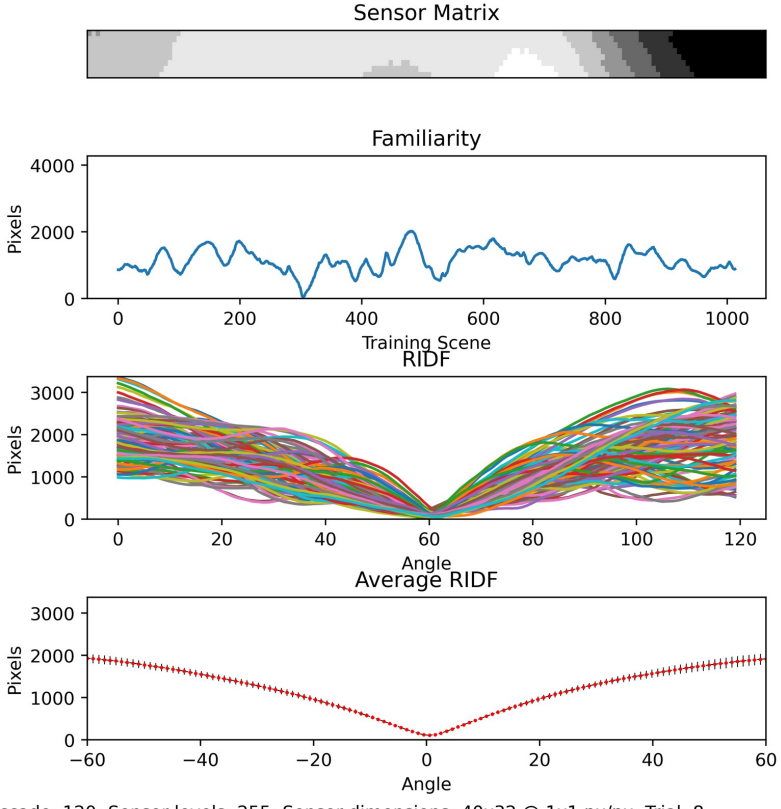


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

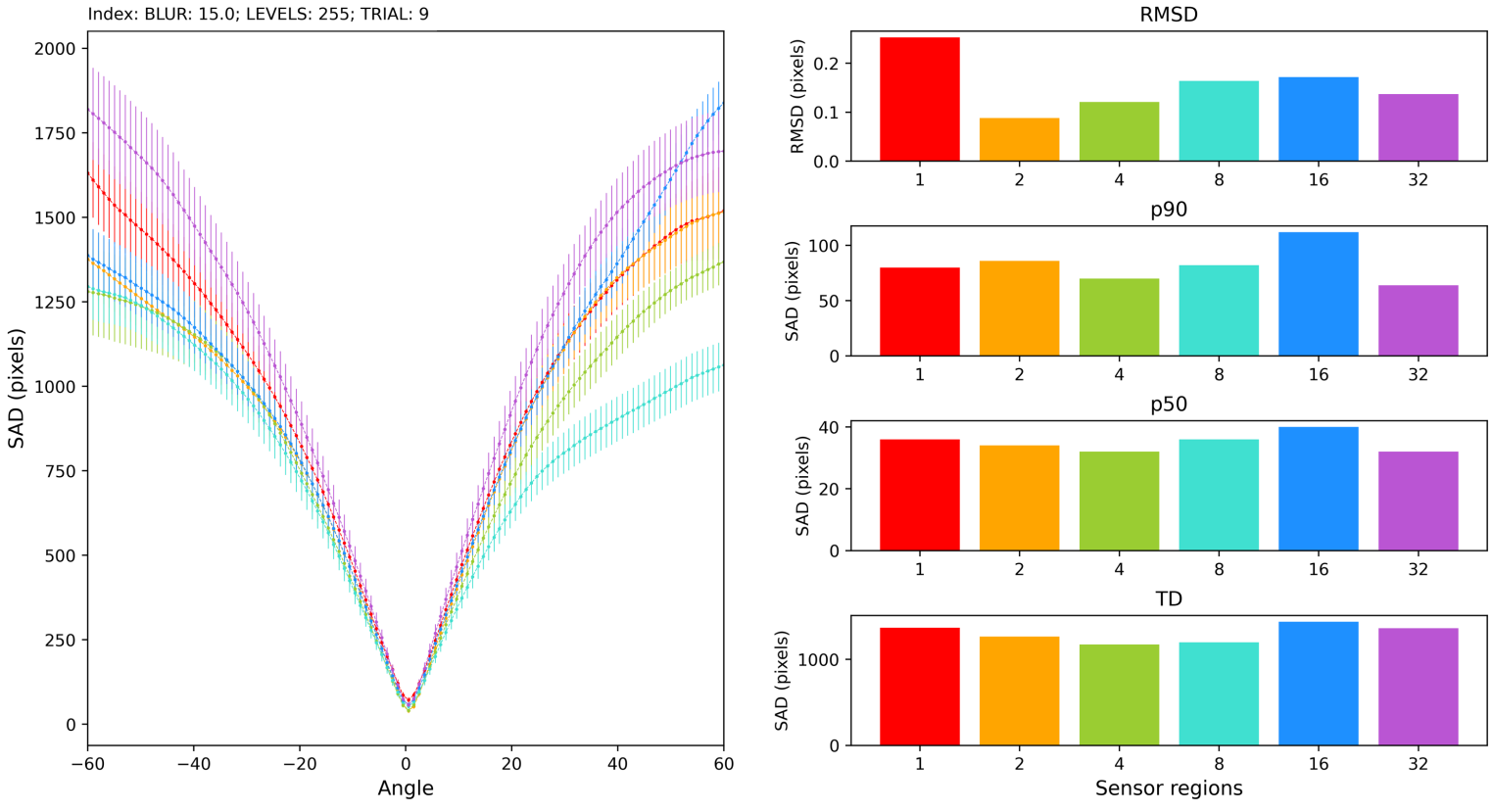
Navigation stats: RMSD error: 42.45; RMSD/dist: 0.106; TD: 1186; p90: 66; p50: 32; complete: 0

100%

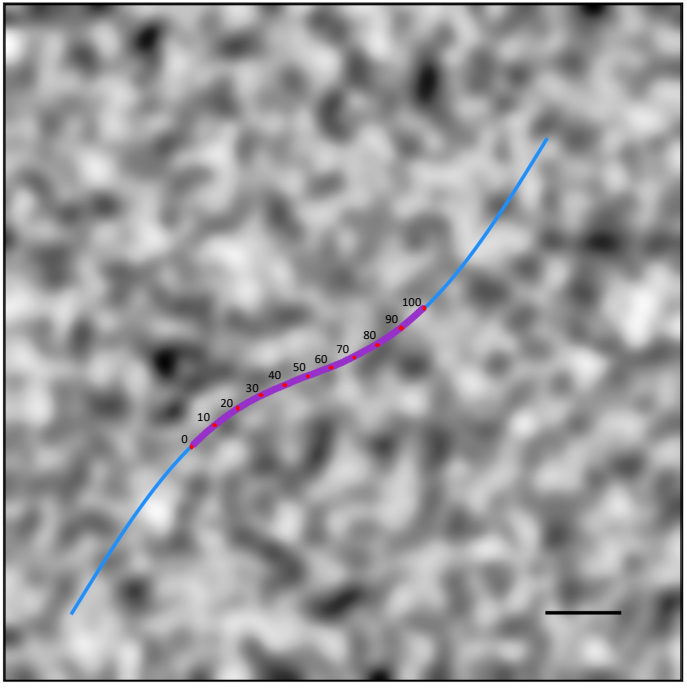


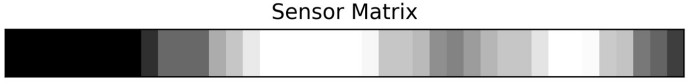


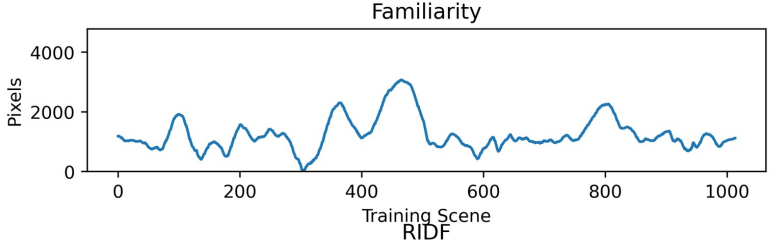
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 146.03; RMSD/dist: 0.365; TD: 1358; p90: 64; p50: 32; complete: 0

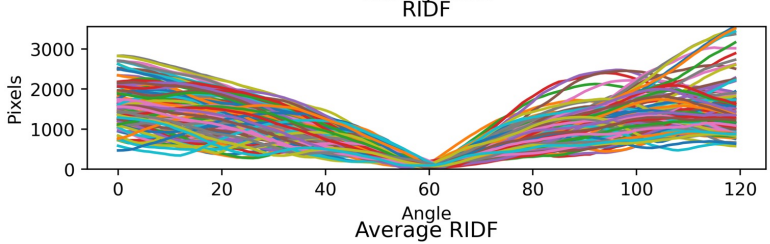

Index: BLUR: 15.0; LEVELS: 255; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

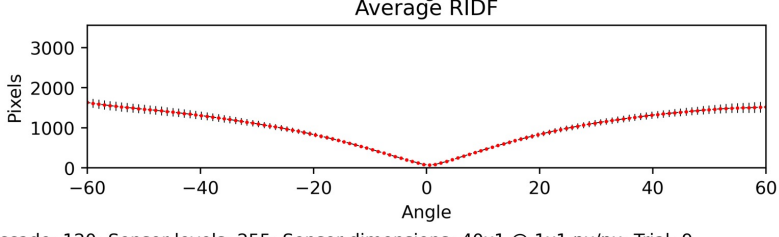
100%





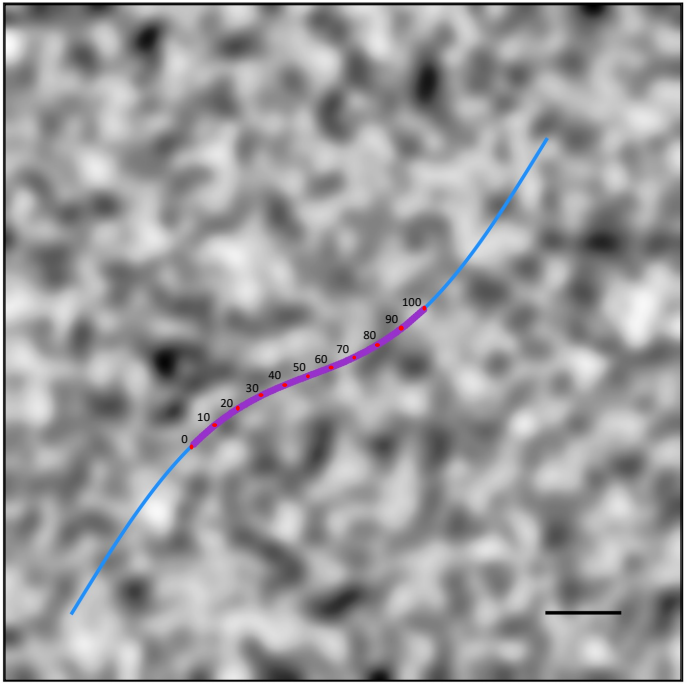


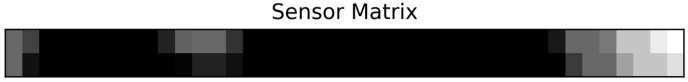


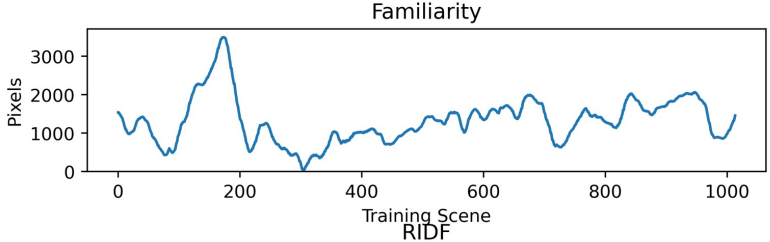


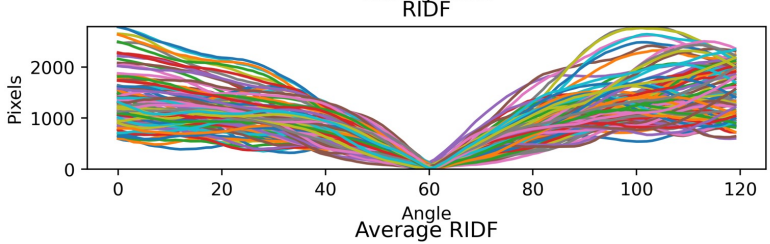
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 101.15; RMSD/dist: 0.253; TD: 1367; p90: 80; p50: 36; complete: 0

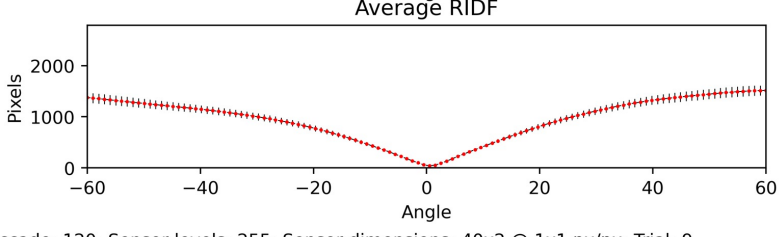
100%





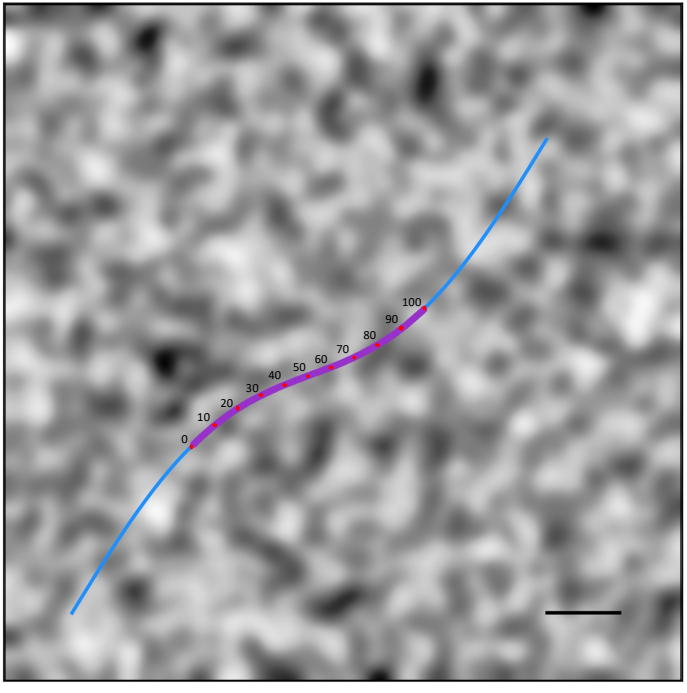


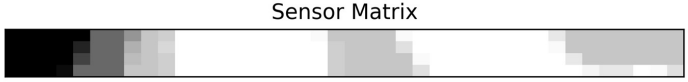


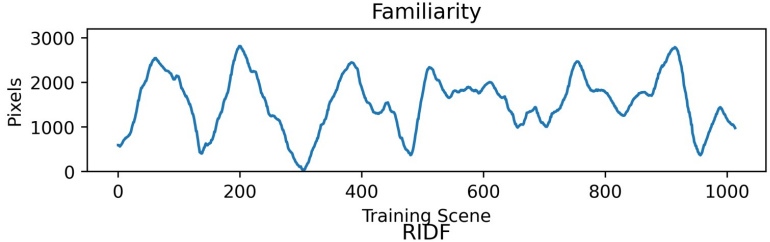


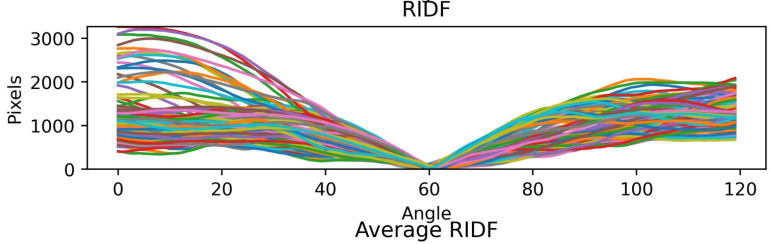
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 35.38; RMSD/dist: 0.088; TD: 1265; p90: 86; p50: 34; complete: 0

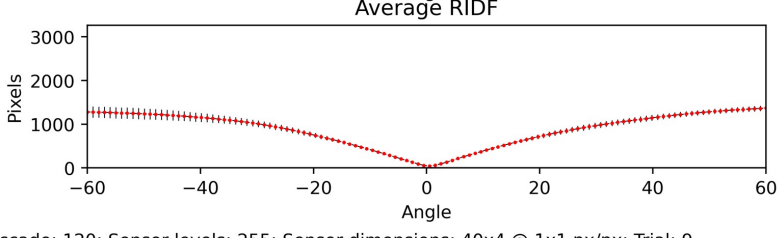
100%





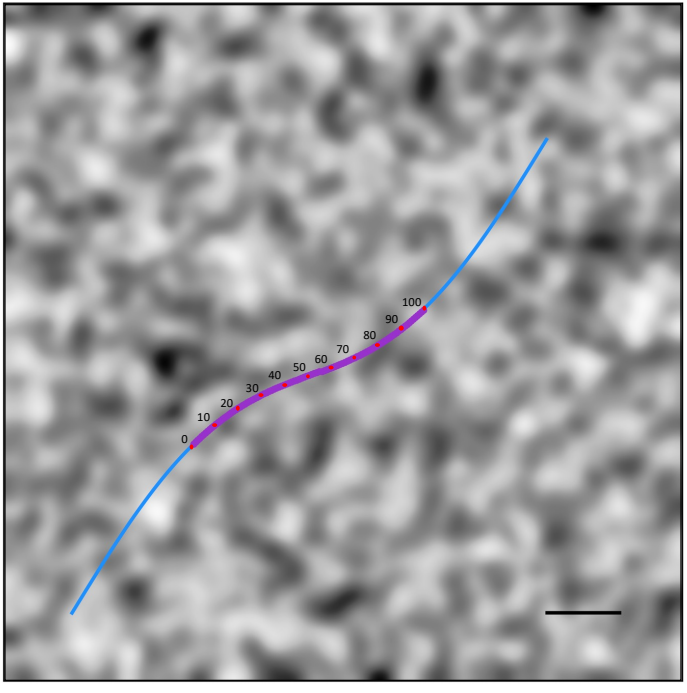


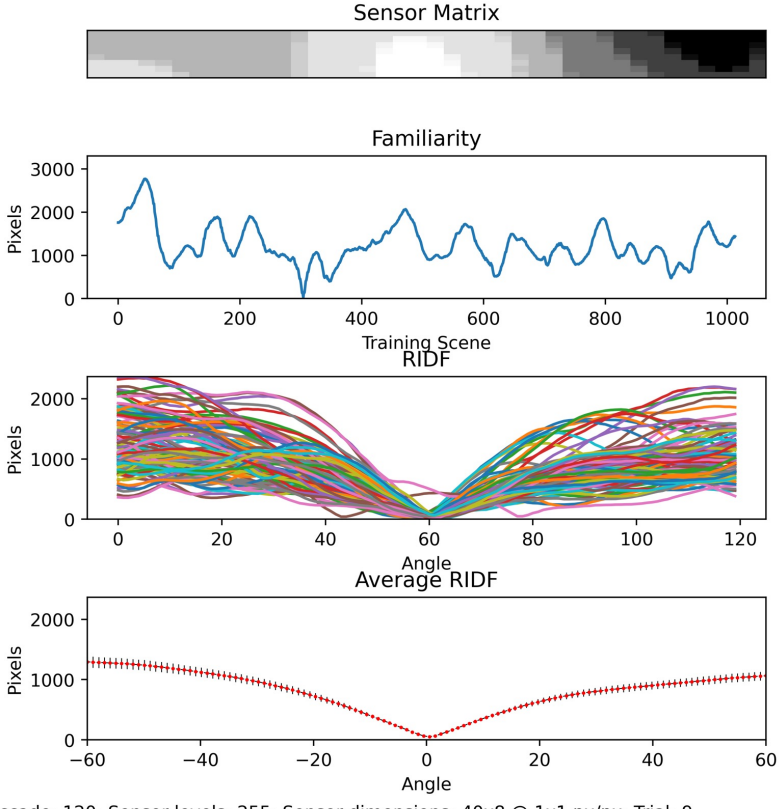




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 48.46; RMSD/dist: 0.121; TD: 1174; p90: 70; p50: 32; complete: 0

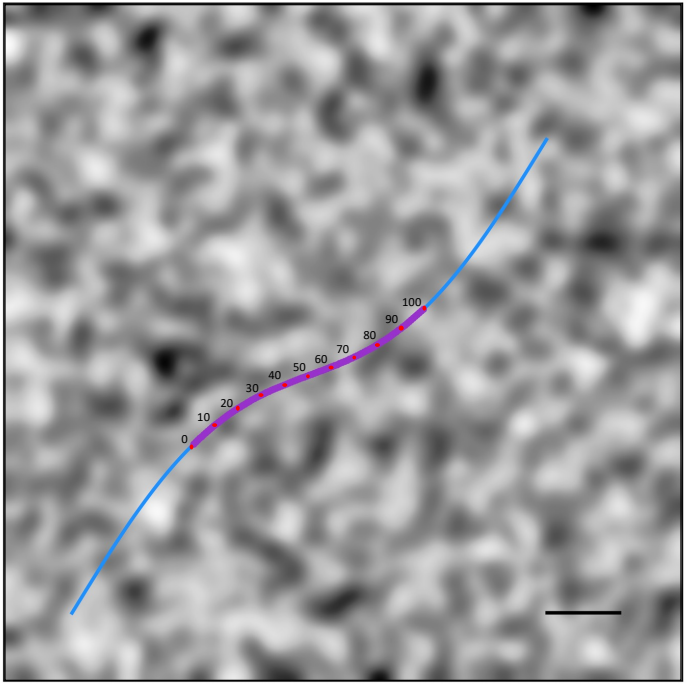
100%

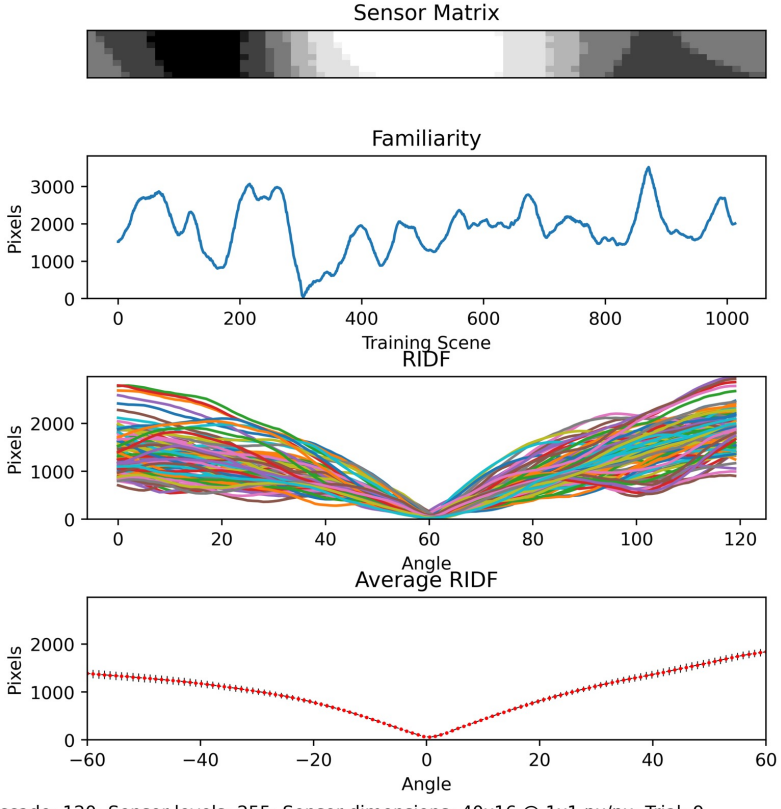




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 65.62; RMSD/dist: 0.164; TD: 1199; p90: 82; p50: 36; complete: 0

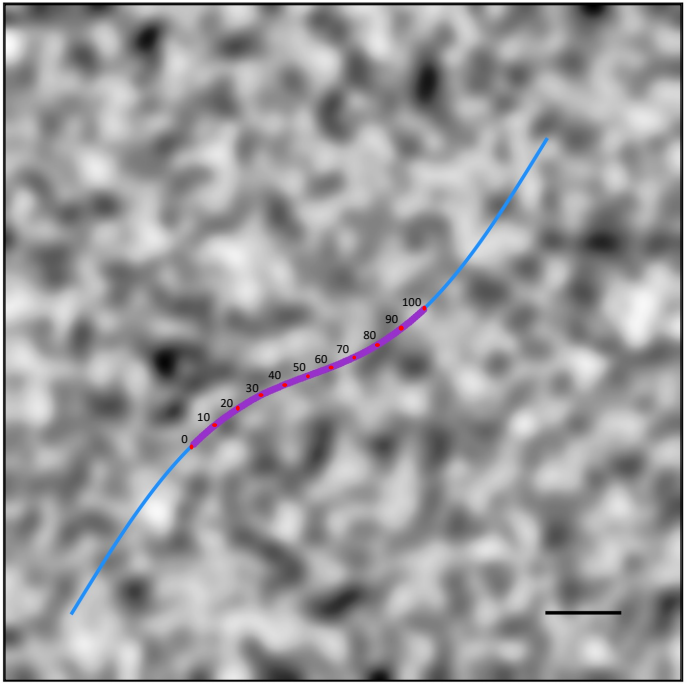
100%

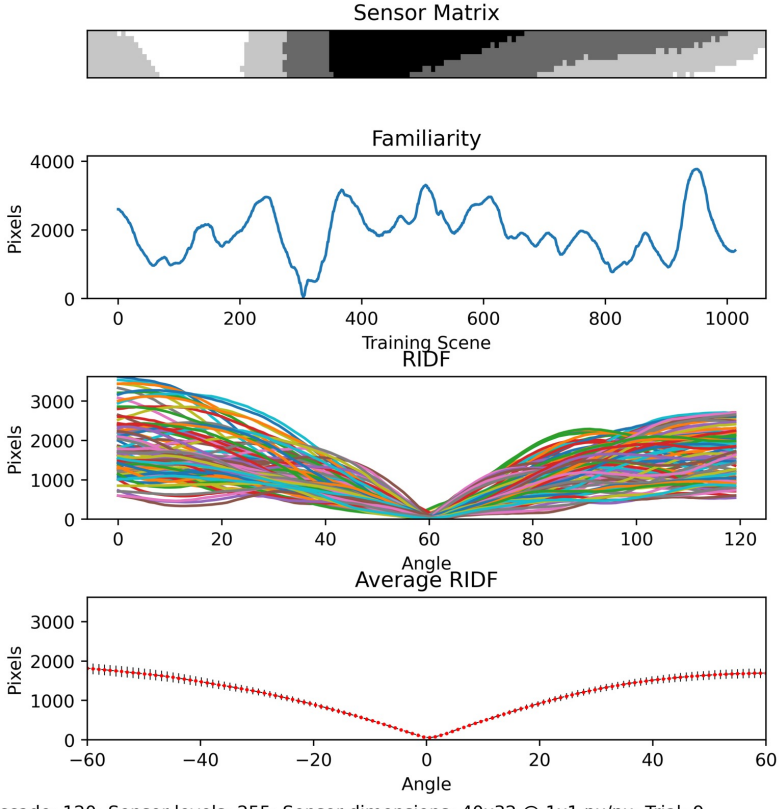




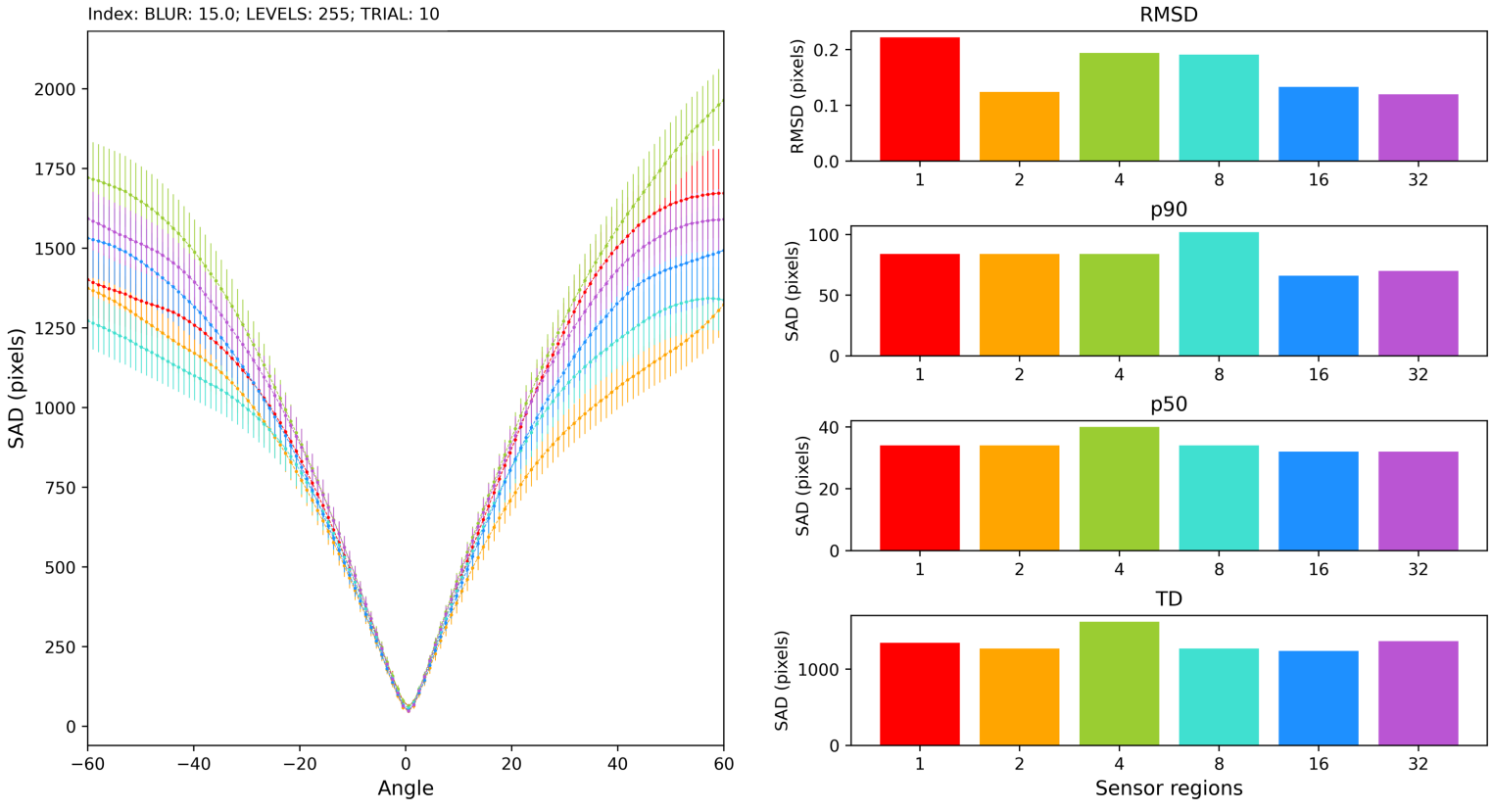
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 68.76; RMSD/dist: 0.172; TD: 1438; p90: 112; p50: 40; complete: 0

100%

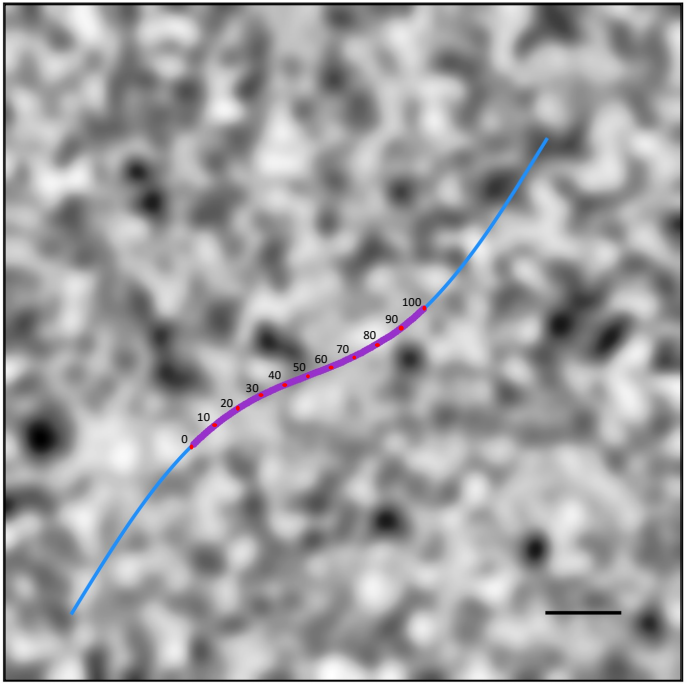


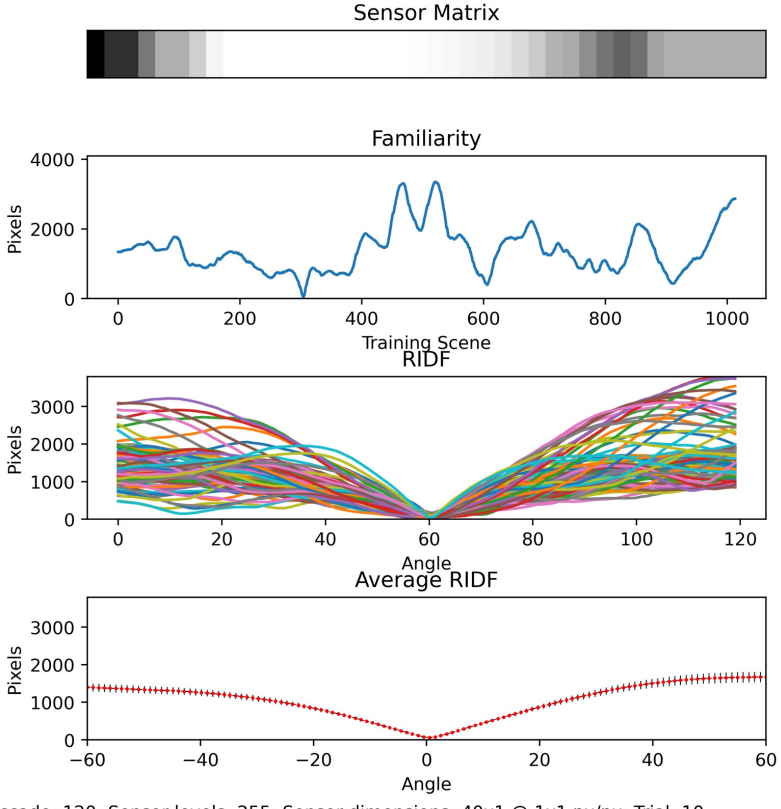


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 54.70; RMSD/dist: 0.137; TD: 1363; p90: 64; p50: 32; complete: 0


Index: BLUR: 15.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

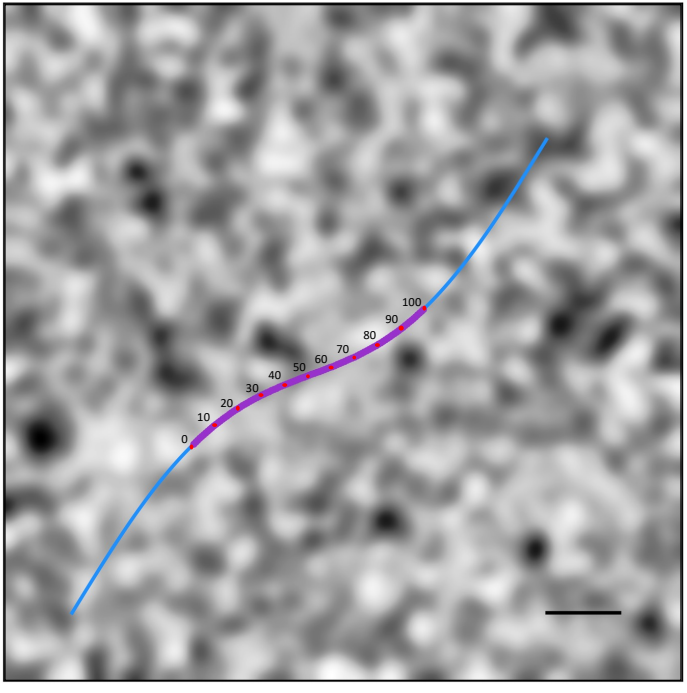
100%

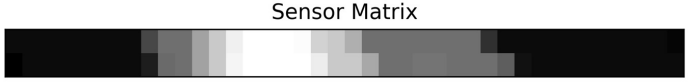


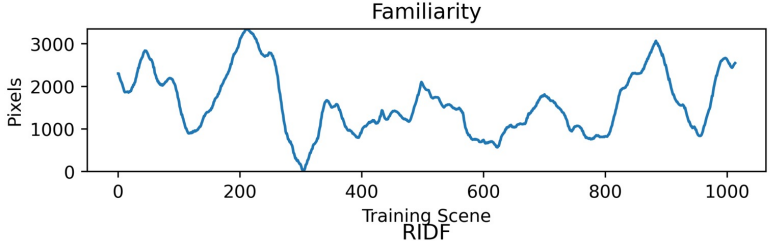


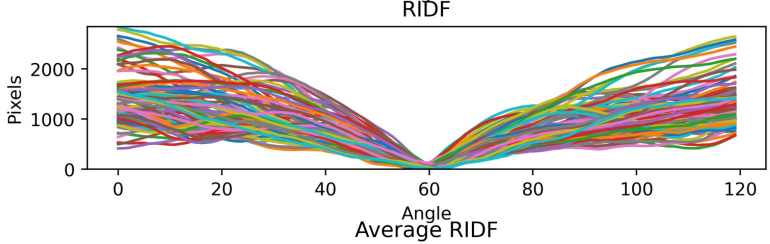
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 88.74; RMSD/dist: 0.222; TD: 1347; p90: 84; p50: 34; complete: 0

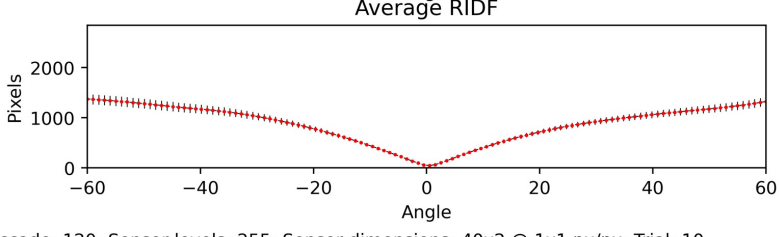
100%





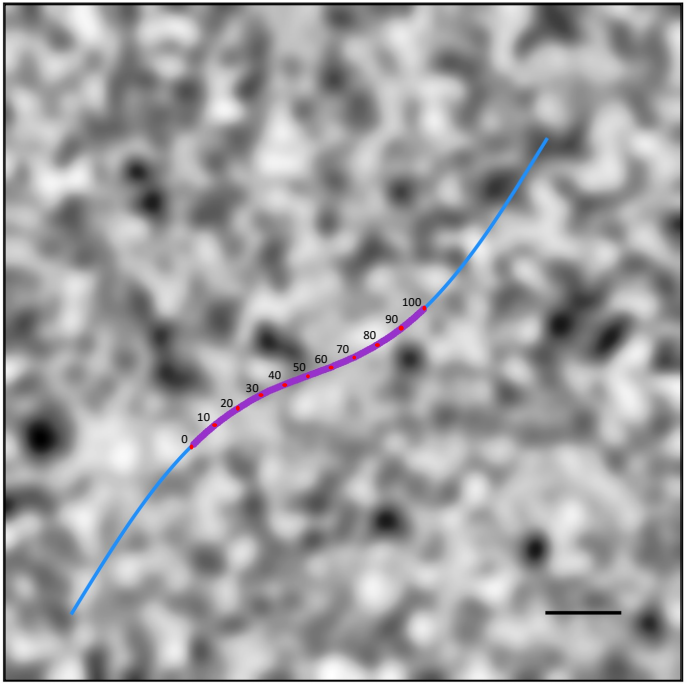


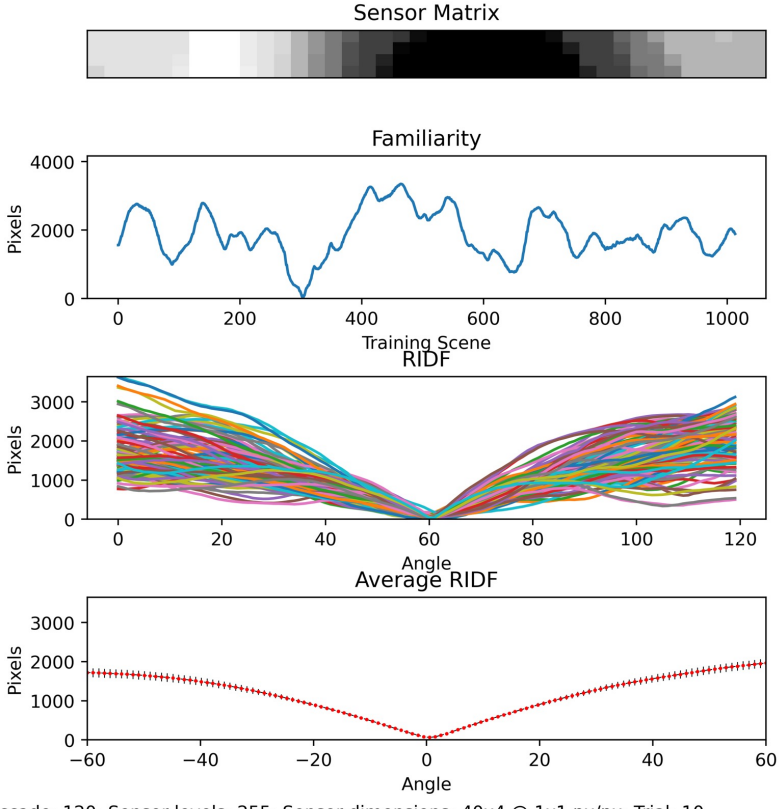




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 49.67; RMSD/dist: 0.124; TD: 1271; p90: 84; p50: 34; complete: 0

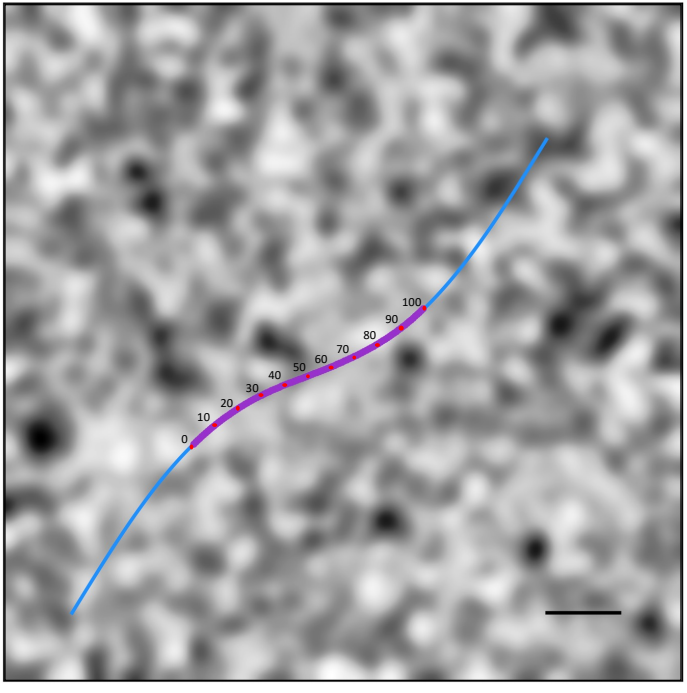
100%

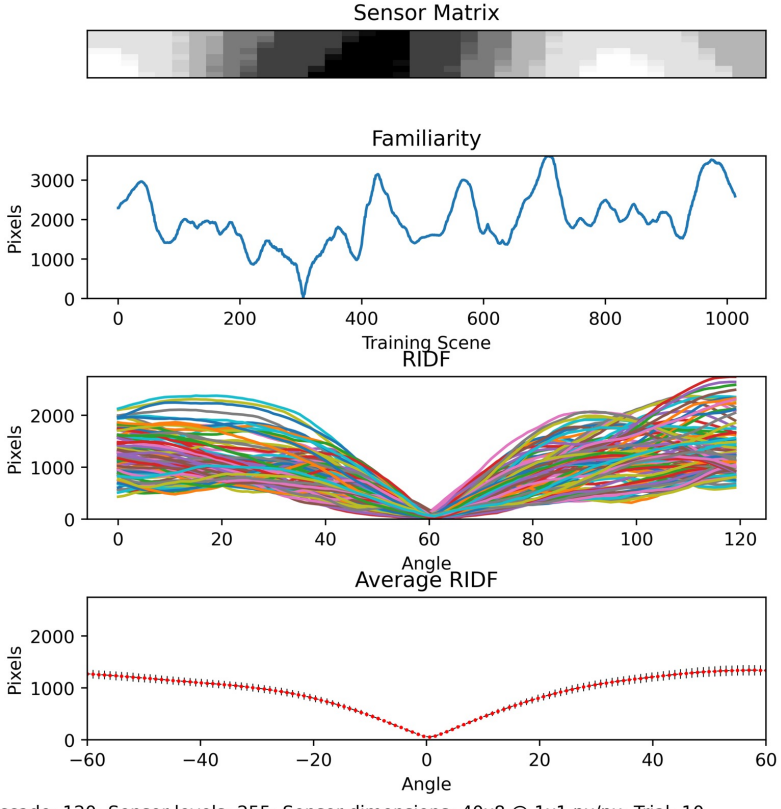




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 77.59; RMSD/dist: 0.194; TD: 1624; p90: 84; p50: 40; complete: 0

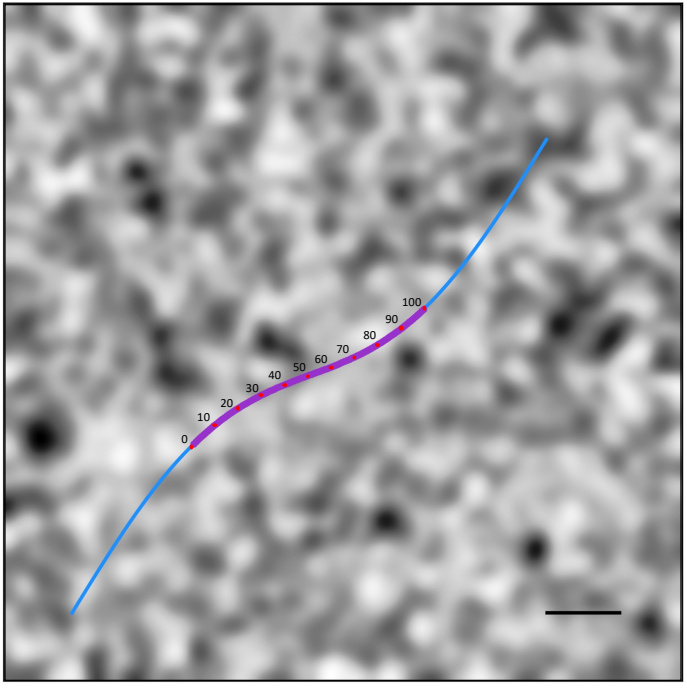
100%

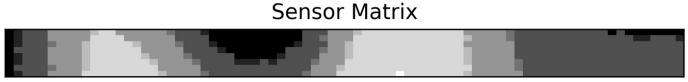


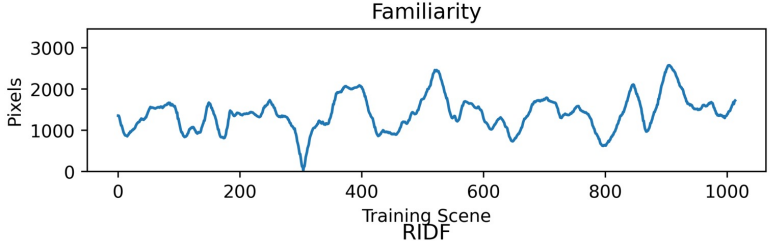


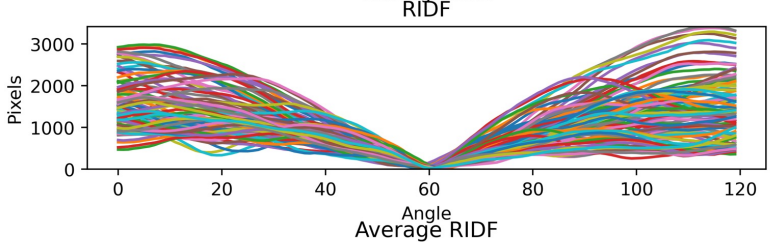
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 76.24; RMSD/dist: 0.191; TD: 1273; p90: 102; p50: 34; complete: 0

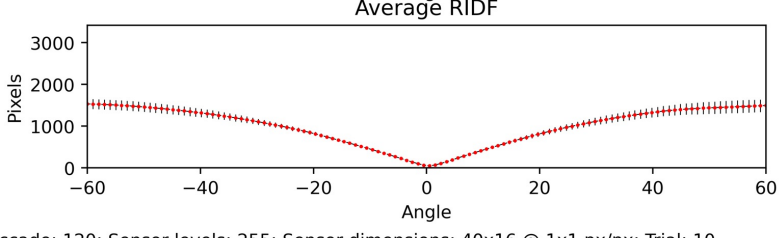
100%





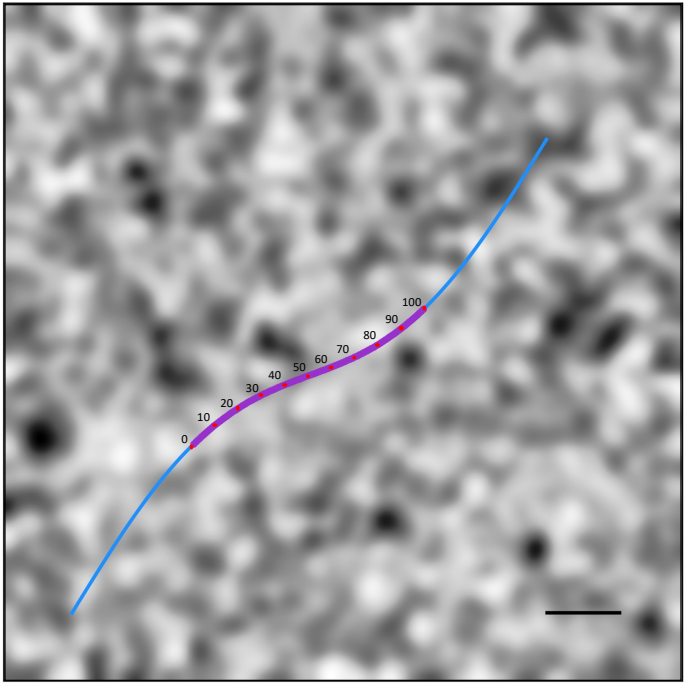


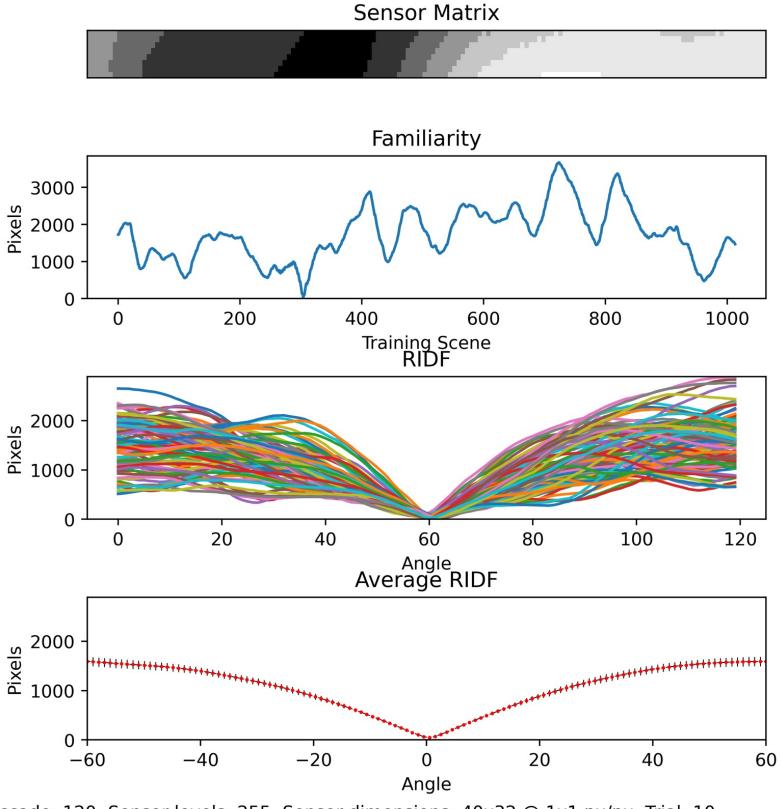




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 53.01; RMSD/dist: 0.133; TD: 1239; p90: 66; p50: 32; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 48.00; RMSD/dist: 0.120; TD: 1369; p90: 70; p50: 32; complete: 0