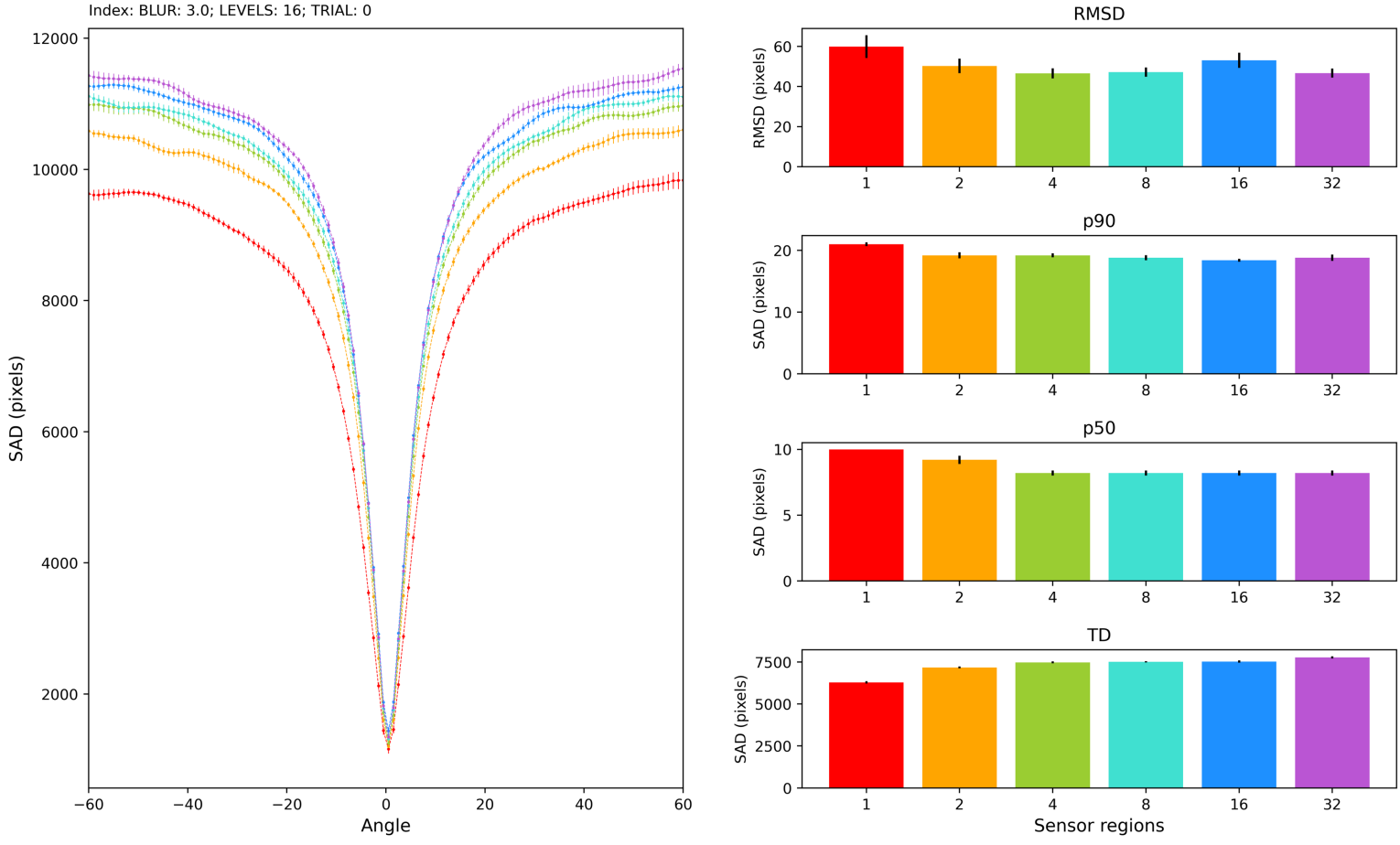
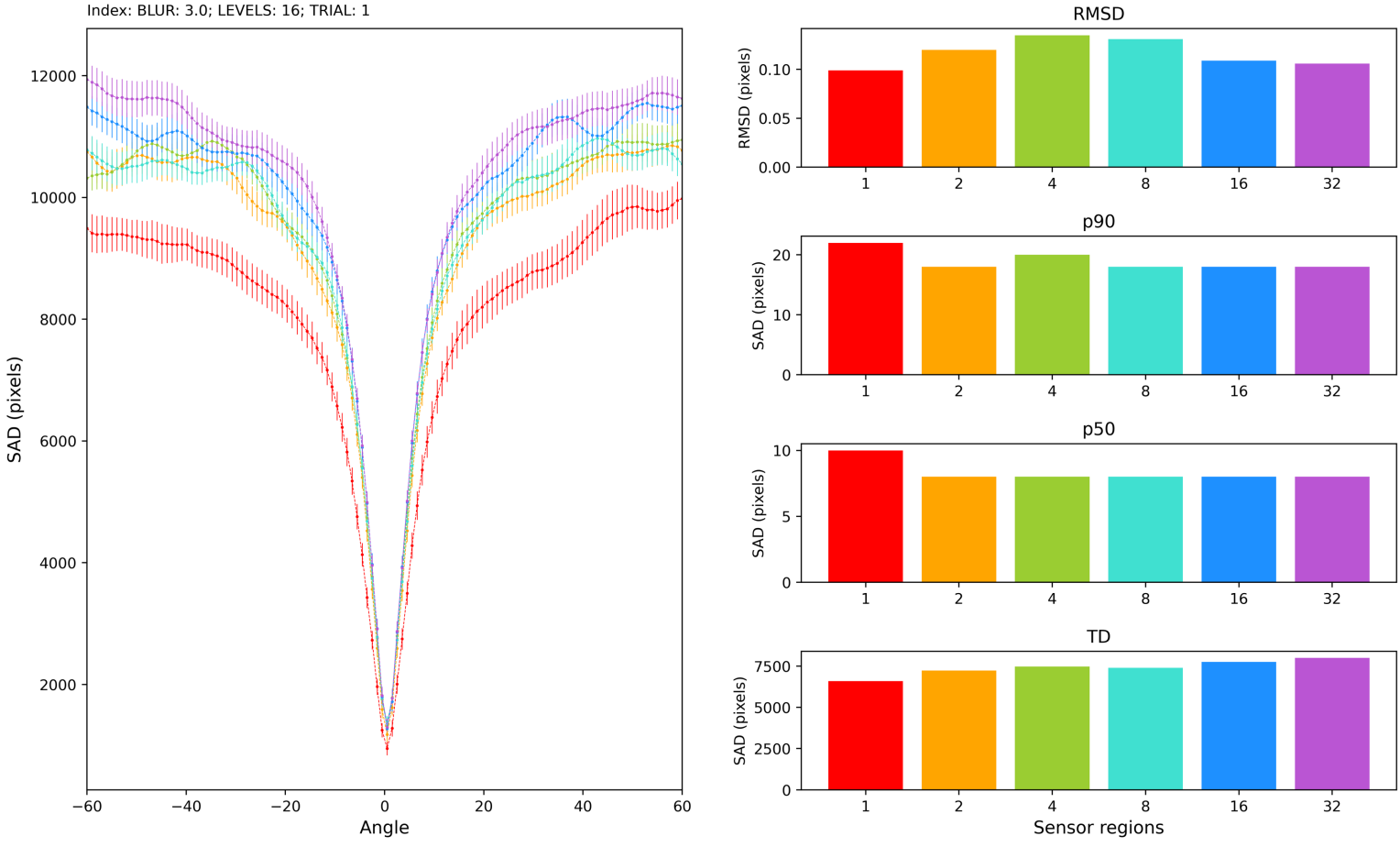
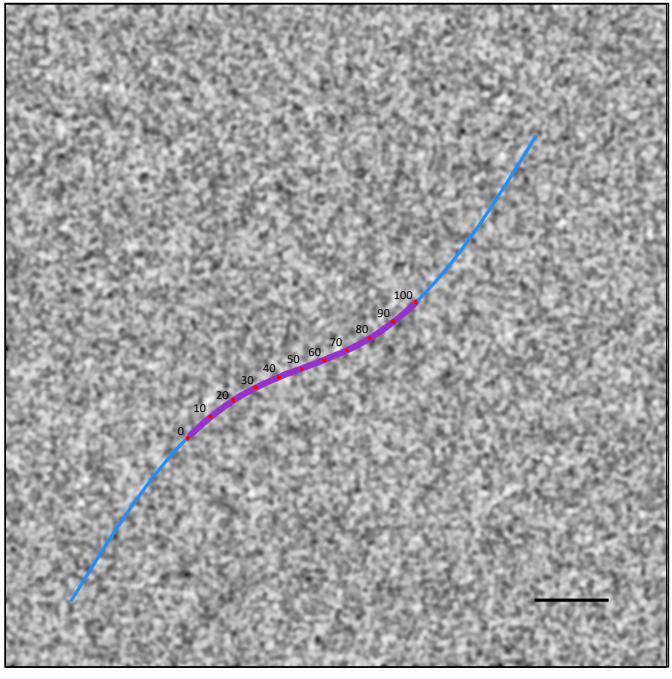
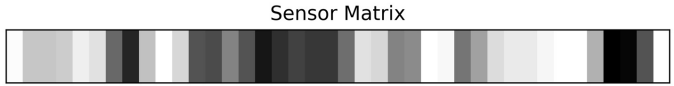
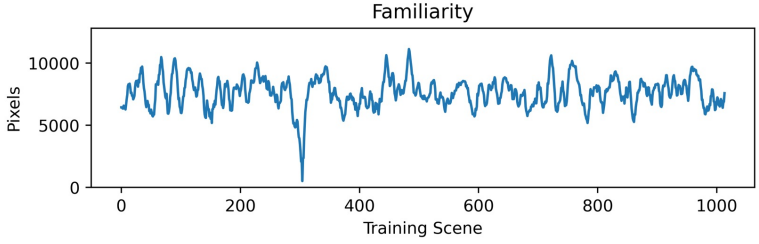

Index: BLUR: 3.0; LEVELS: 16; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

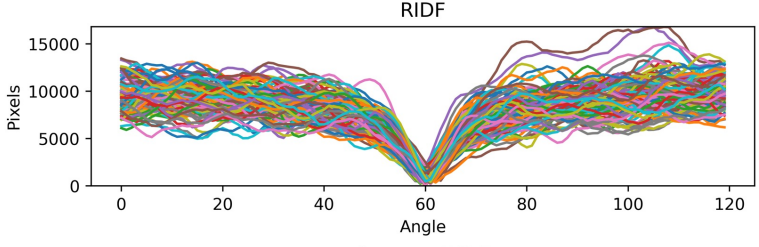

Index: BLUR: 3.0; LEVELS: 16; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

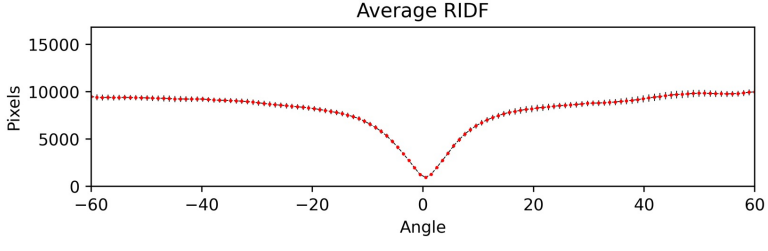
100%







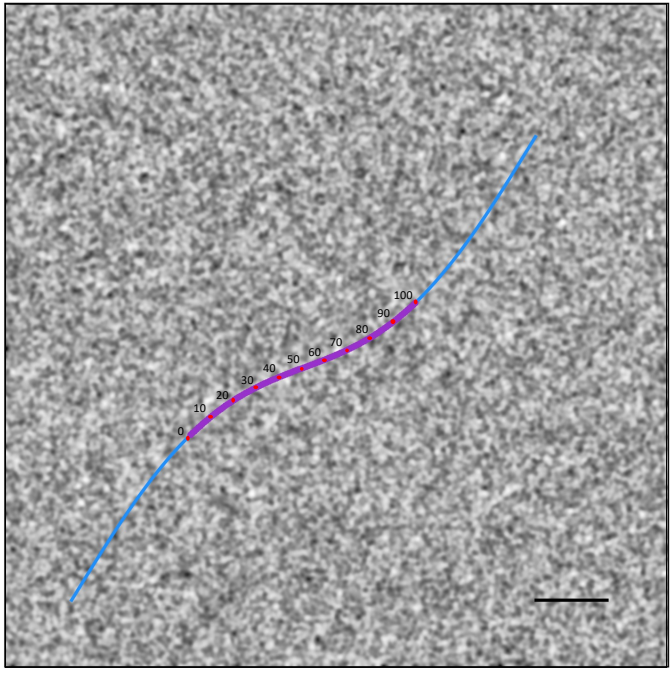


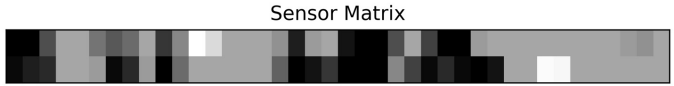


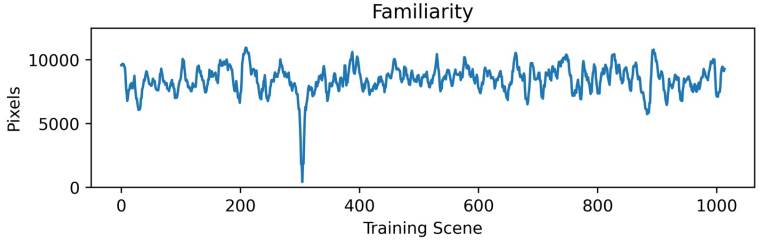
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

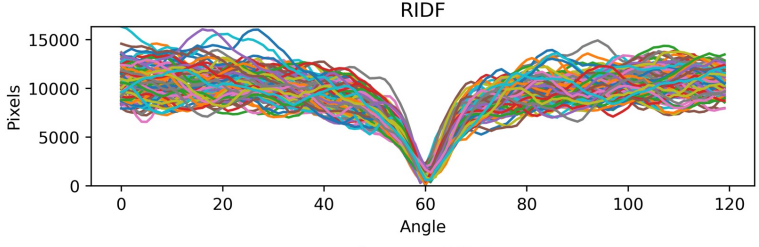
Navigation stats: RMSD error: 39.76; RMSD/dist: 0.099; TD: 6581; p90: 22; p50: 10; complete: 0

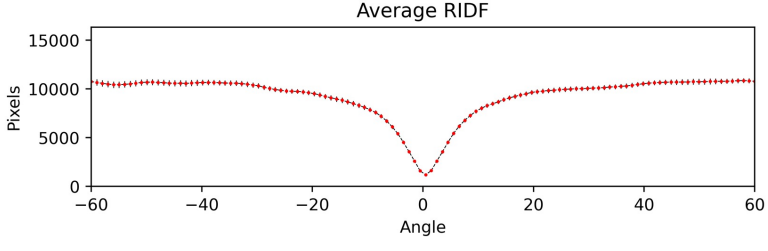
100%







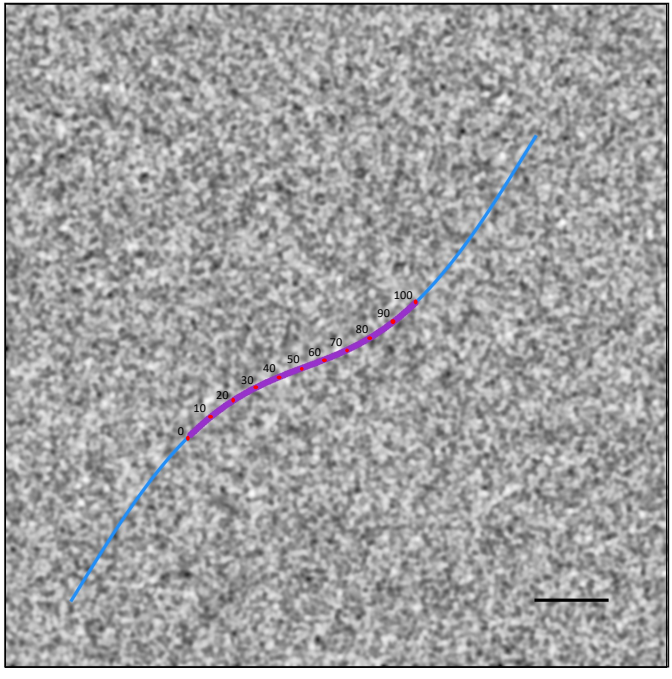


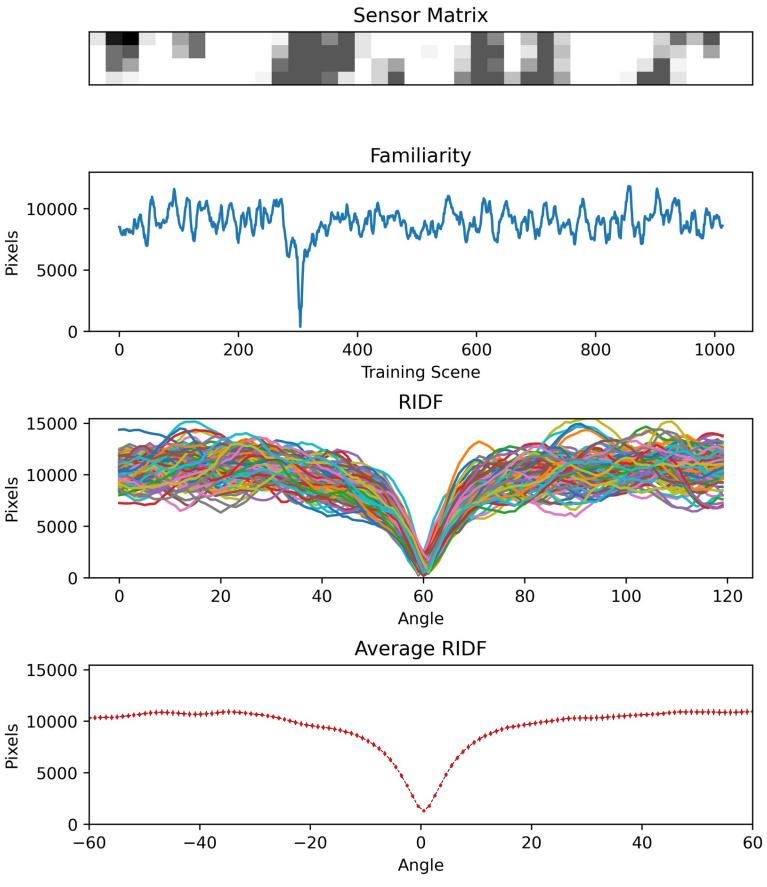


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 47.94; RMSD/dist: 0.120; TD: 7223; p90: 18; p50: 8; complete: 0

100%

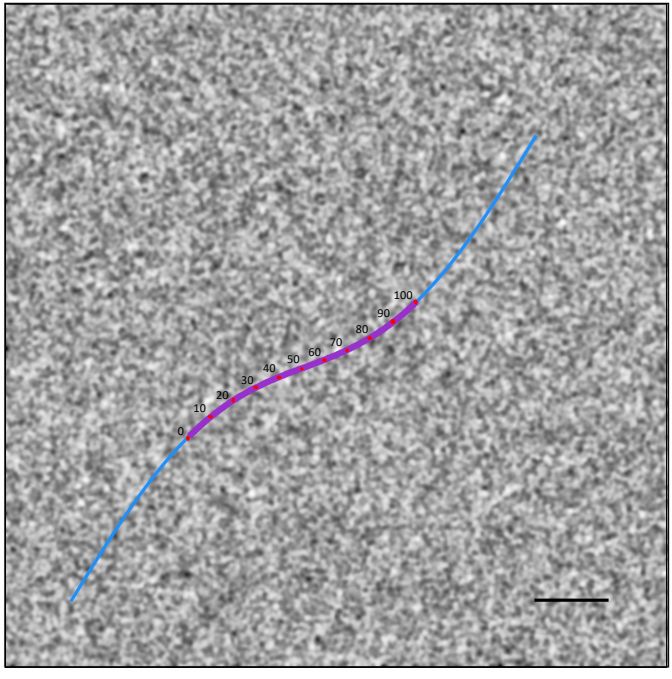


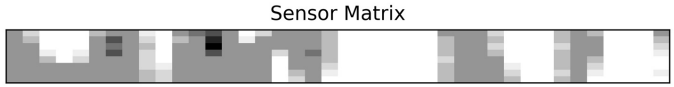


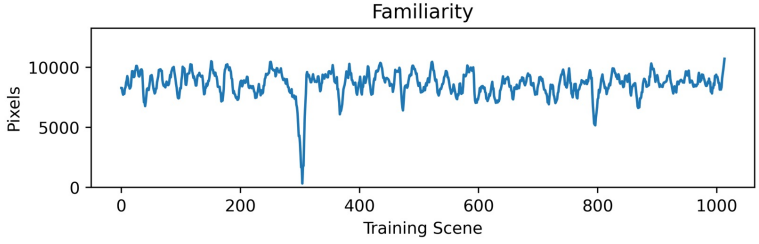
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

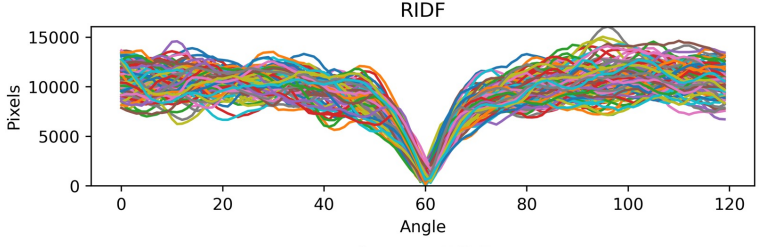
Navigation stats: RMSD error: 54.04; RMSD/dist: 0.135; TD: 7465; p90: 20; p50: 8; complete: 0

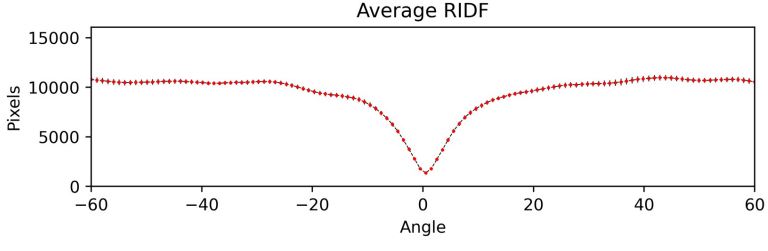
100%







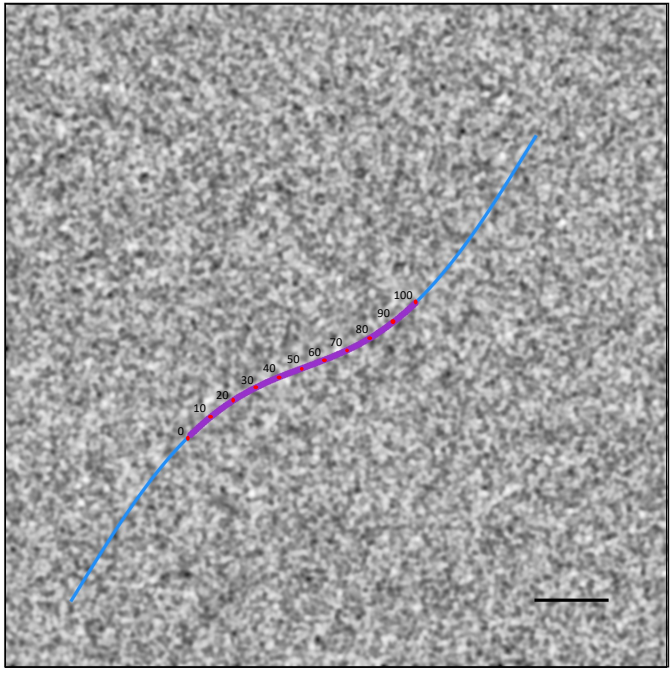


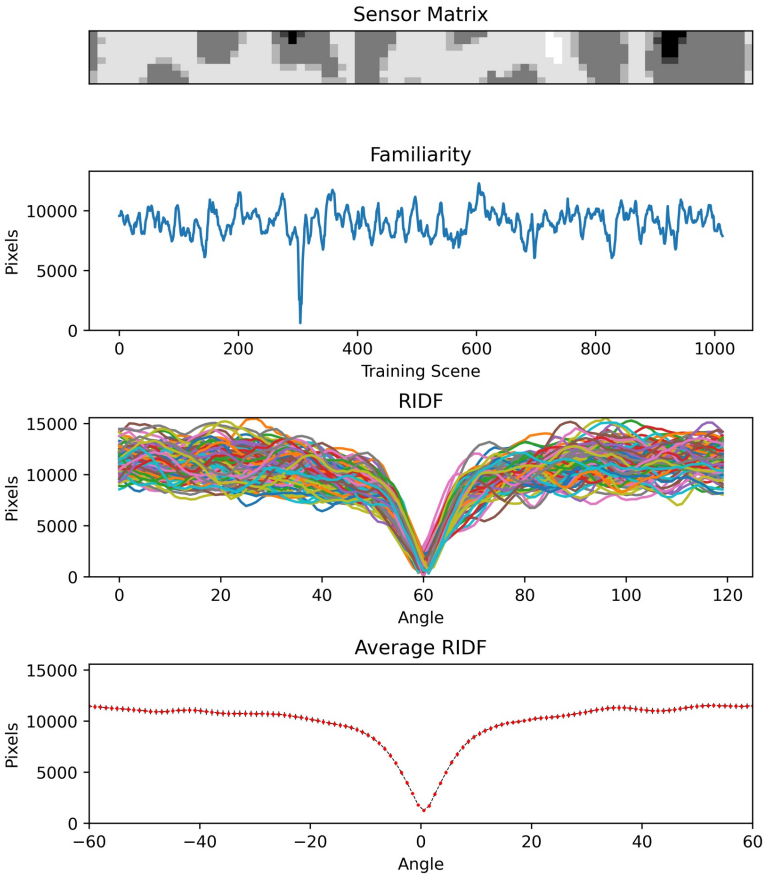


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 52.56; RMSD/dist: 0.131; TD: 7388; p90: 18; p50: 8; complete: 0

100%

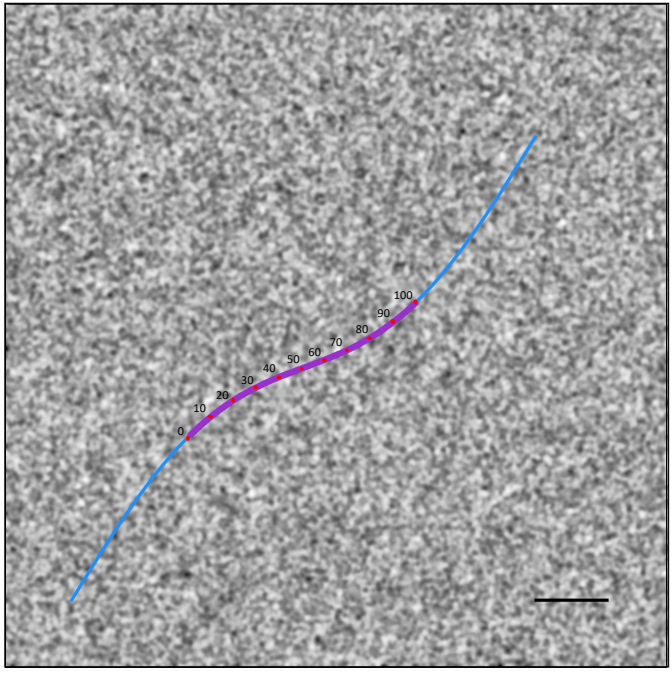


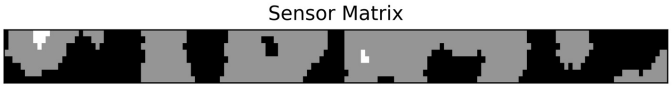


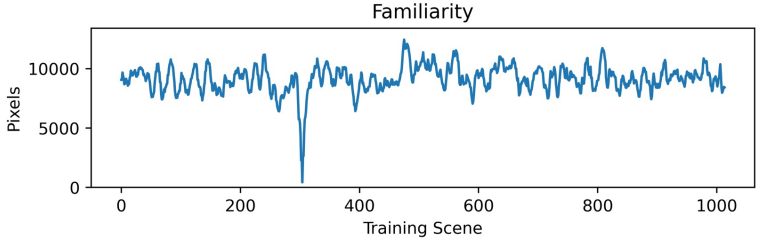
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

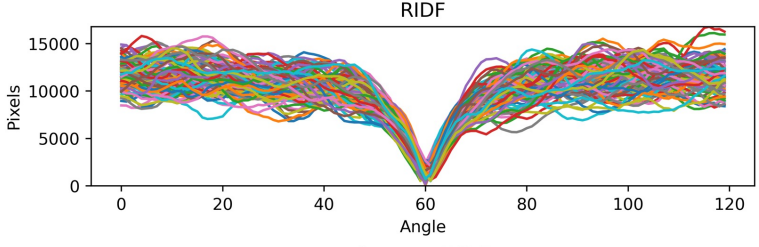
Navigation stats: RMSD error: 43.66; RMSD/dist: 0.109; TD: 7757; p90: 18; p50: 8; complete: 0

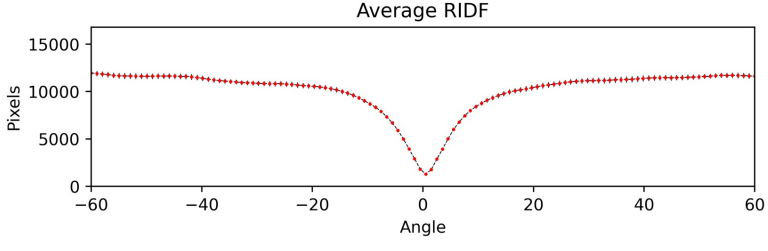
100%





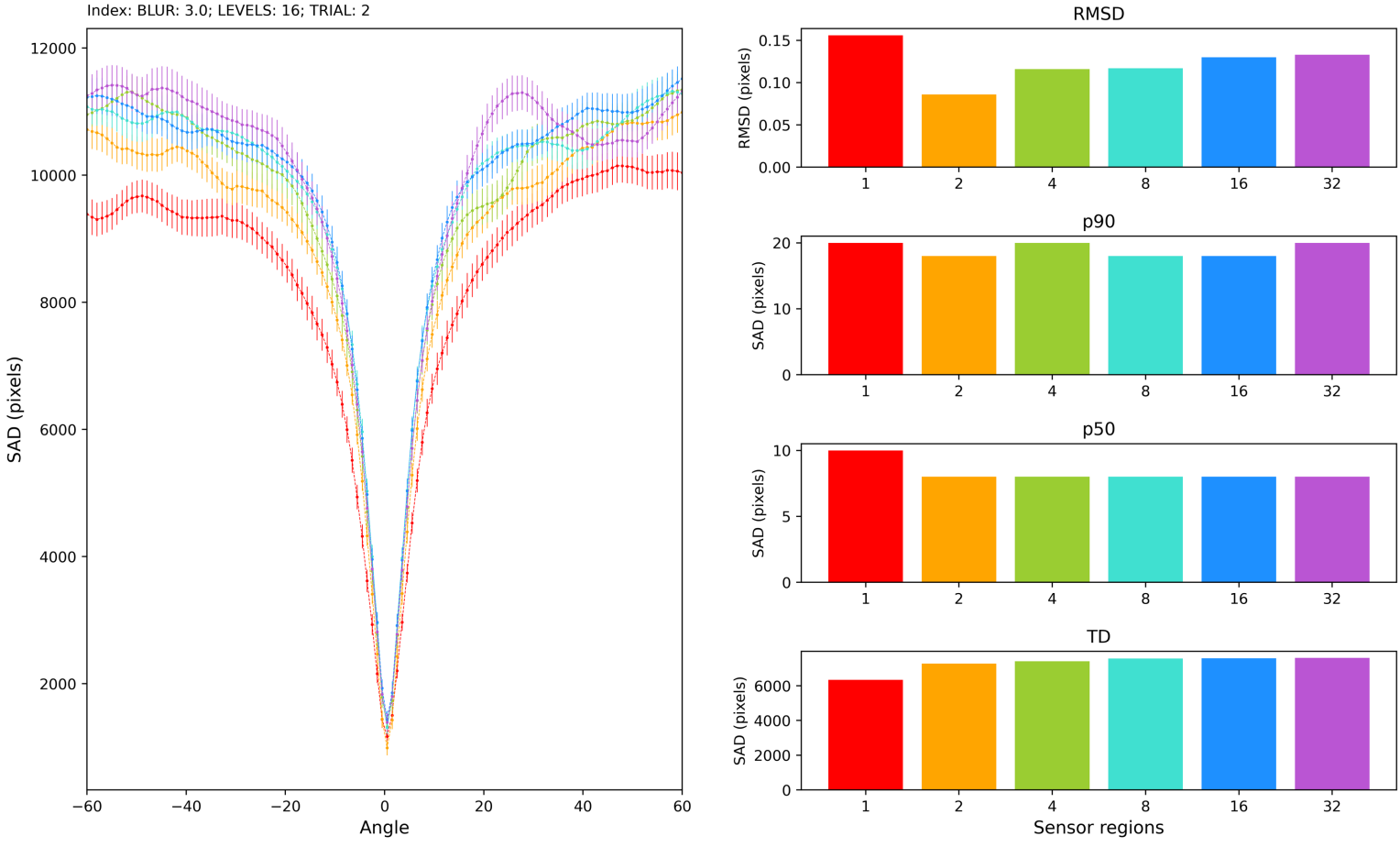




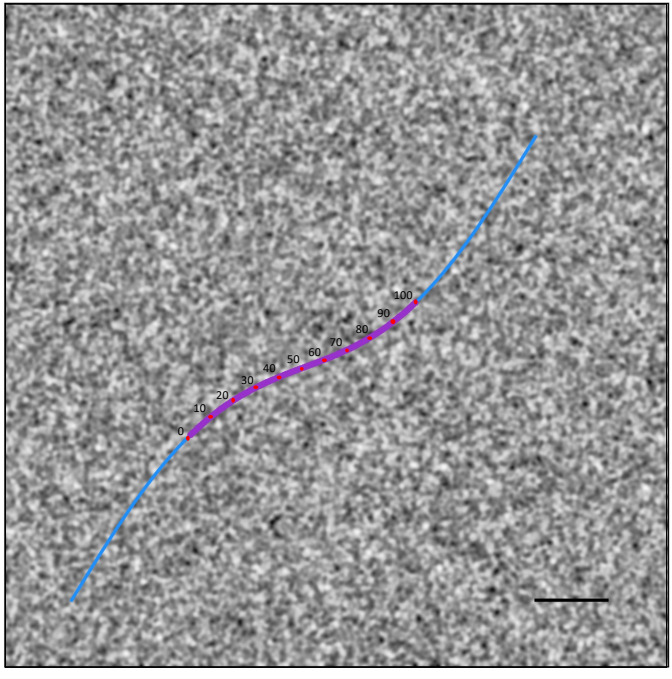


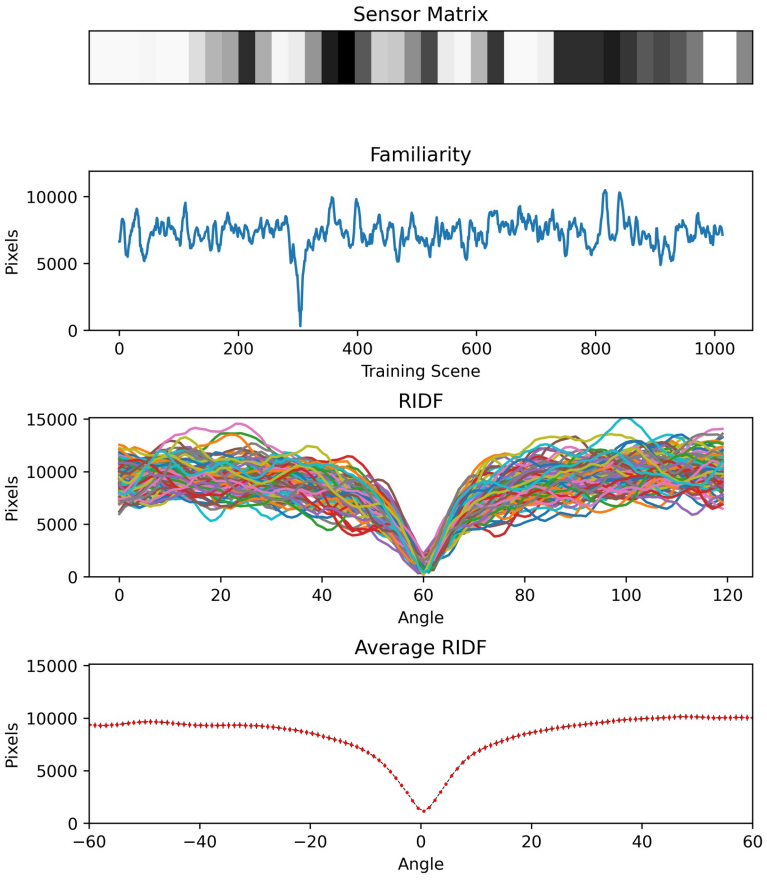
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 42.29; RMSD/dist: 0.106; TD: 7988; p90: 18; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 16; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

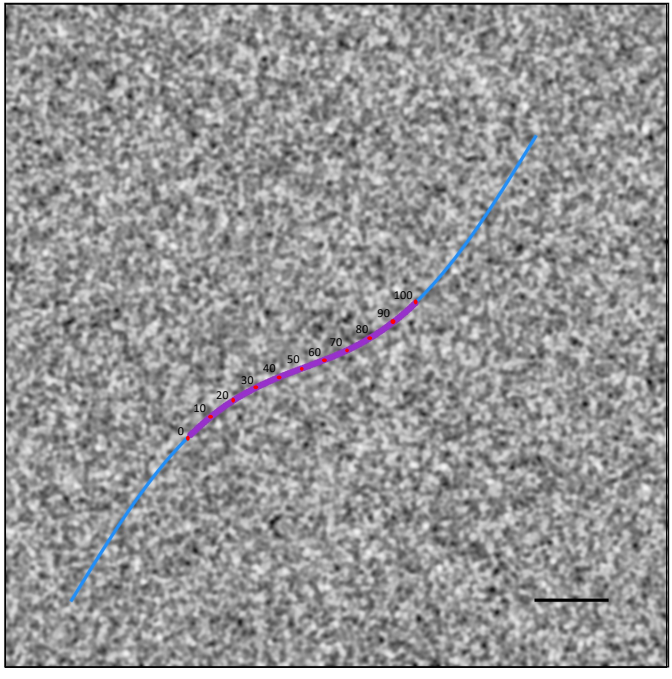


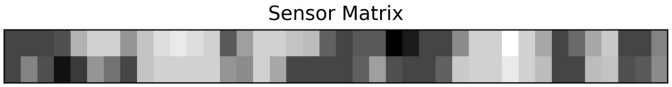


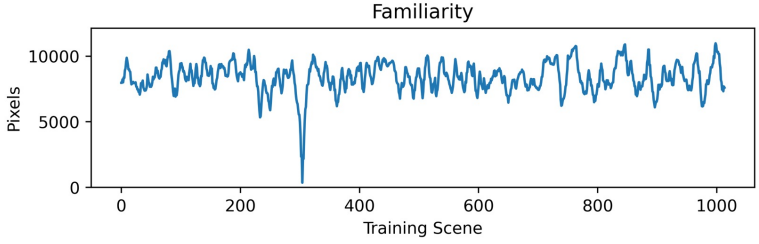
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

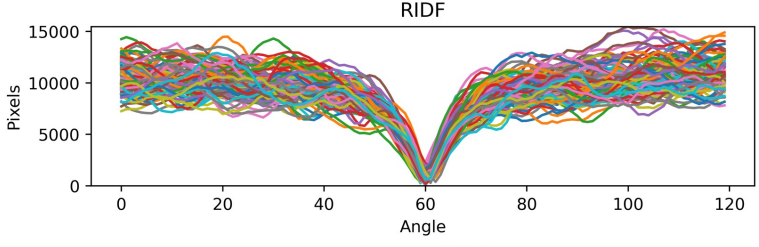
Navigation stats: RMSD error: 62.35; RMSD/dist: 0.156; TD: 6341; p90: 20; p50: 10; complete: 0

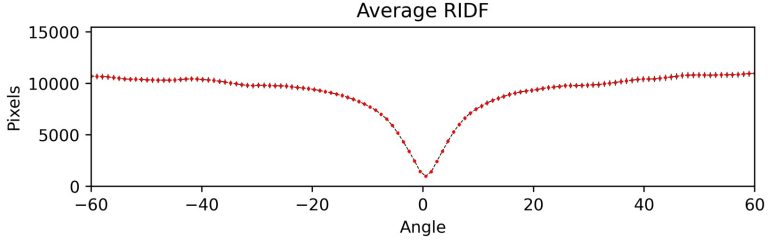
100%







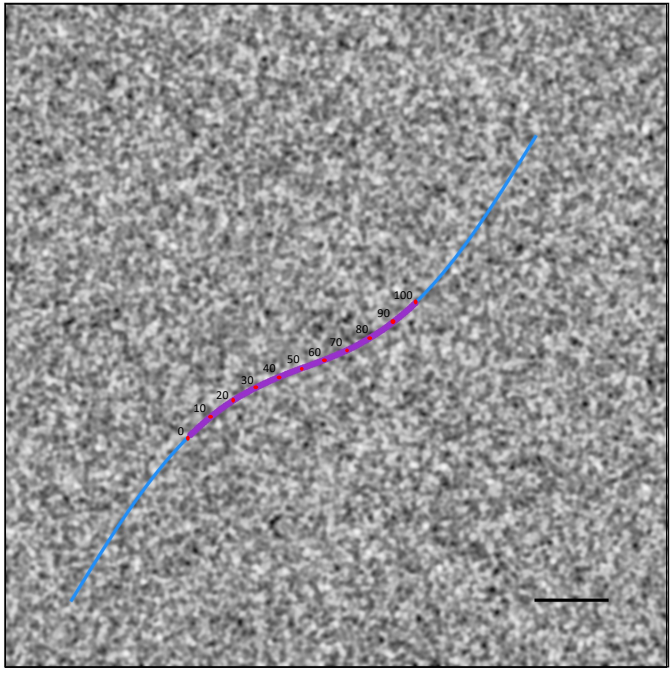


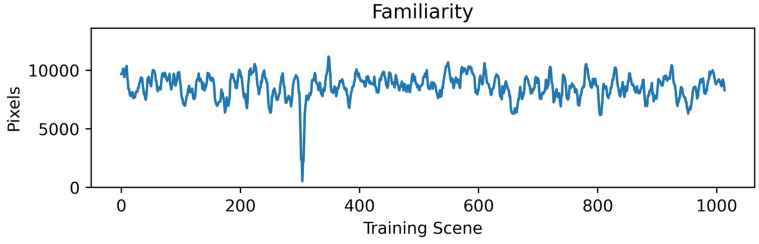


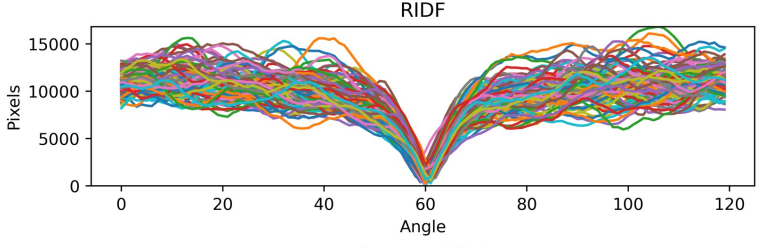
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

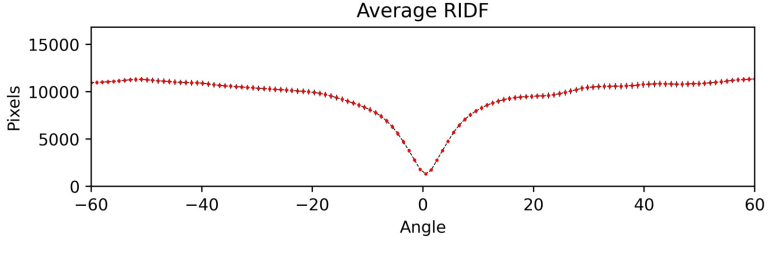
Navigation stats: RMSD error: 34.58; RMSD/dist: 0.086; TD: 7279; p90: 18; p50: 8; complete: 0

100%





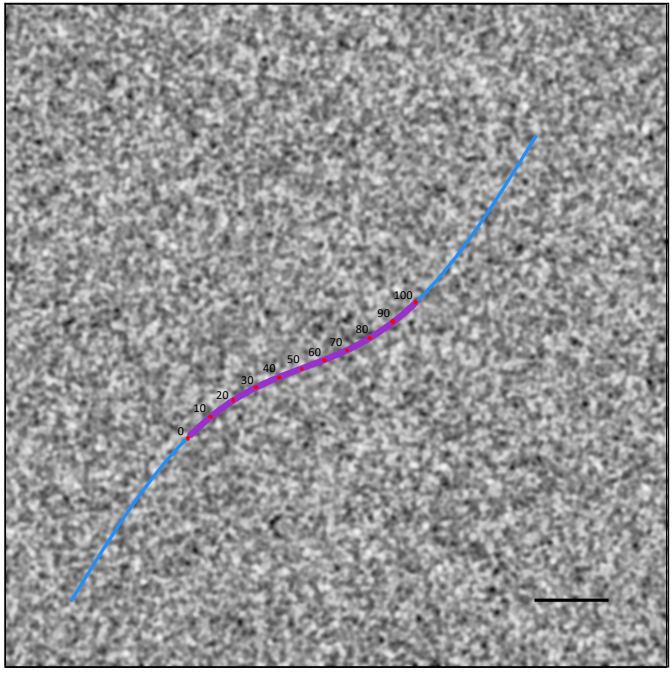


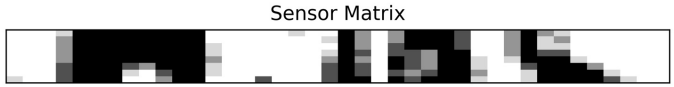


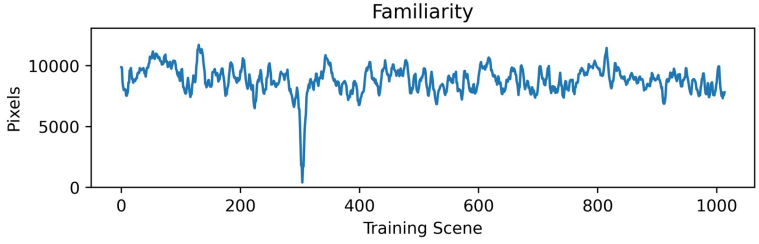
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

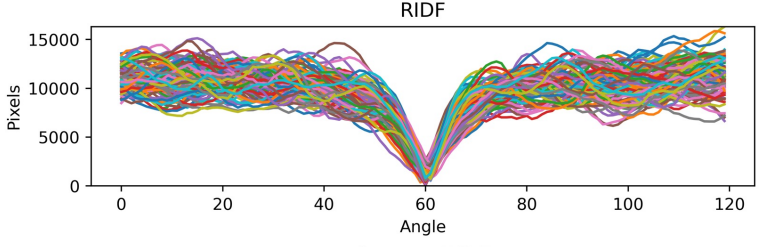
Navigation stats: RMSD error: 46.32; RMSD/dist: 0.116; TD: 7413; p90: 20; p50: 8; complete: 0

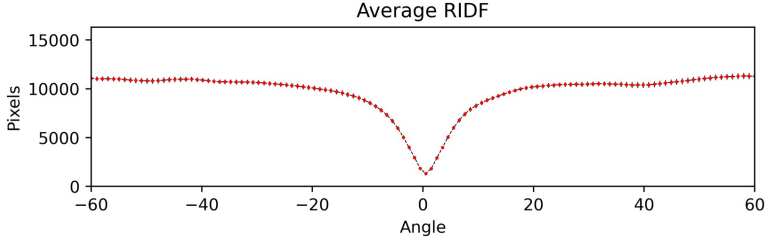
100%







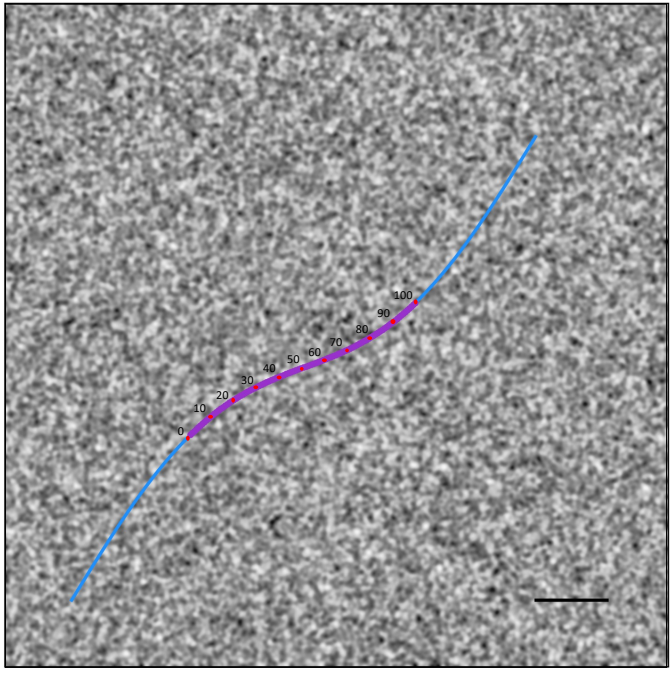


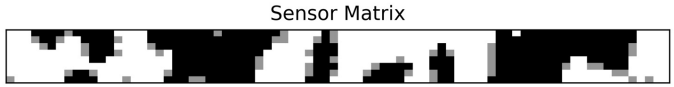


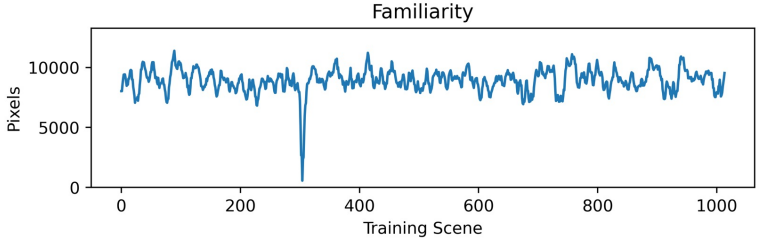
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

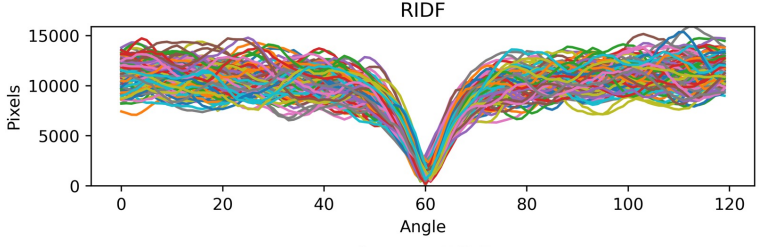
Navigation stats: RMSD error: 46.64; RMSD/dist: 0.117; TD: 7580; p90: 18; p50: 8; complete: 0

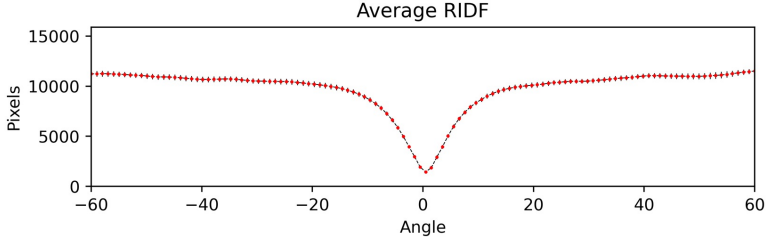
100%







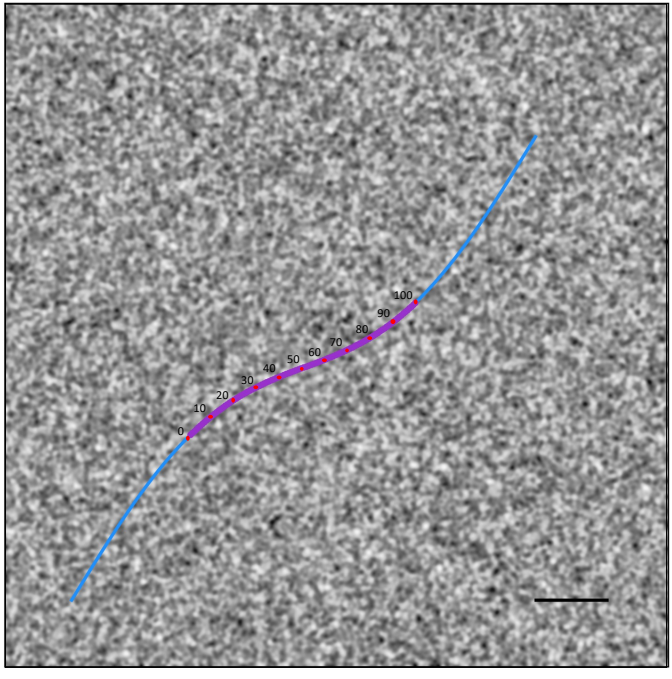


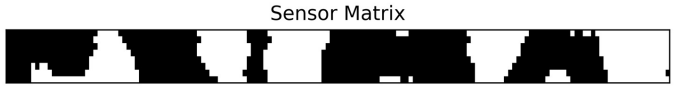


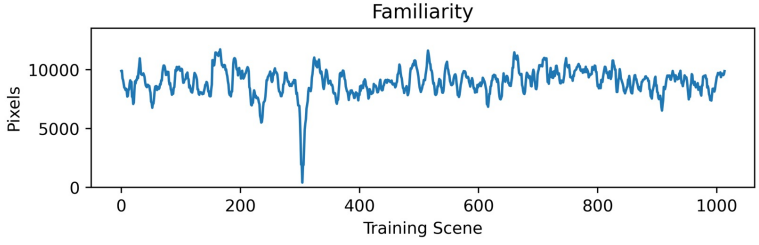
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

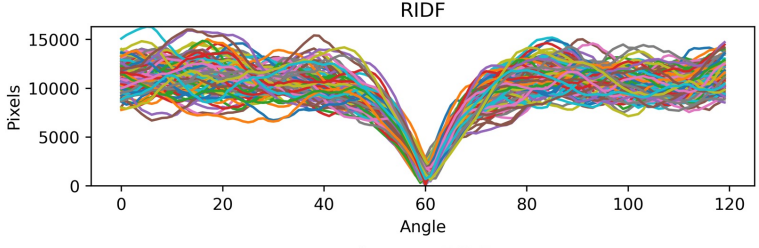
Navigation stats: RMSD error: 51.90; RMSD/dist: 0.130; TD: 7588; p90: 18; p50: 8; complete: 0

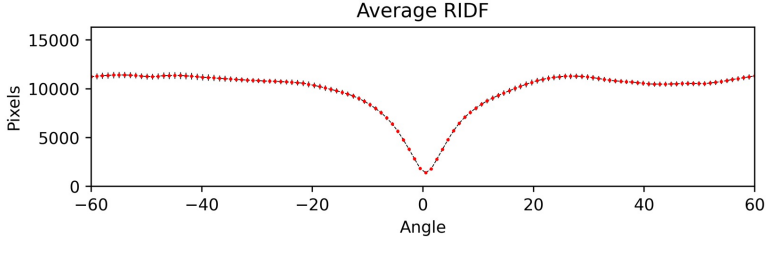
100%





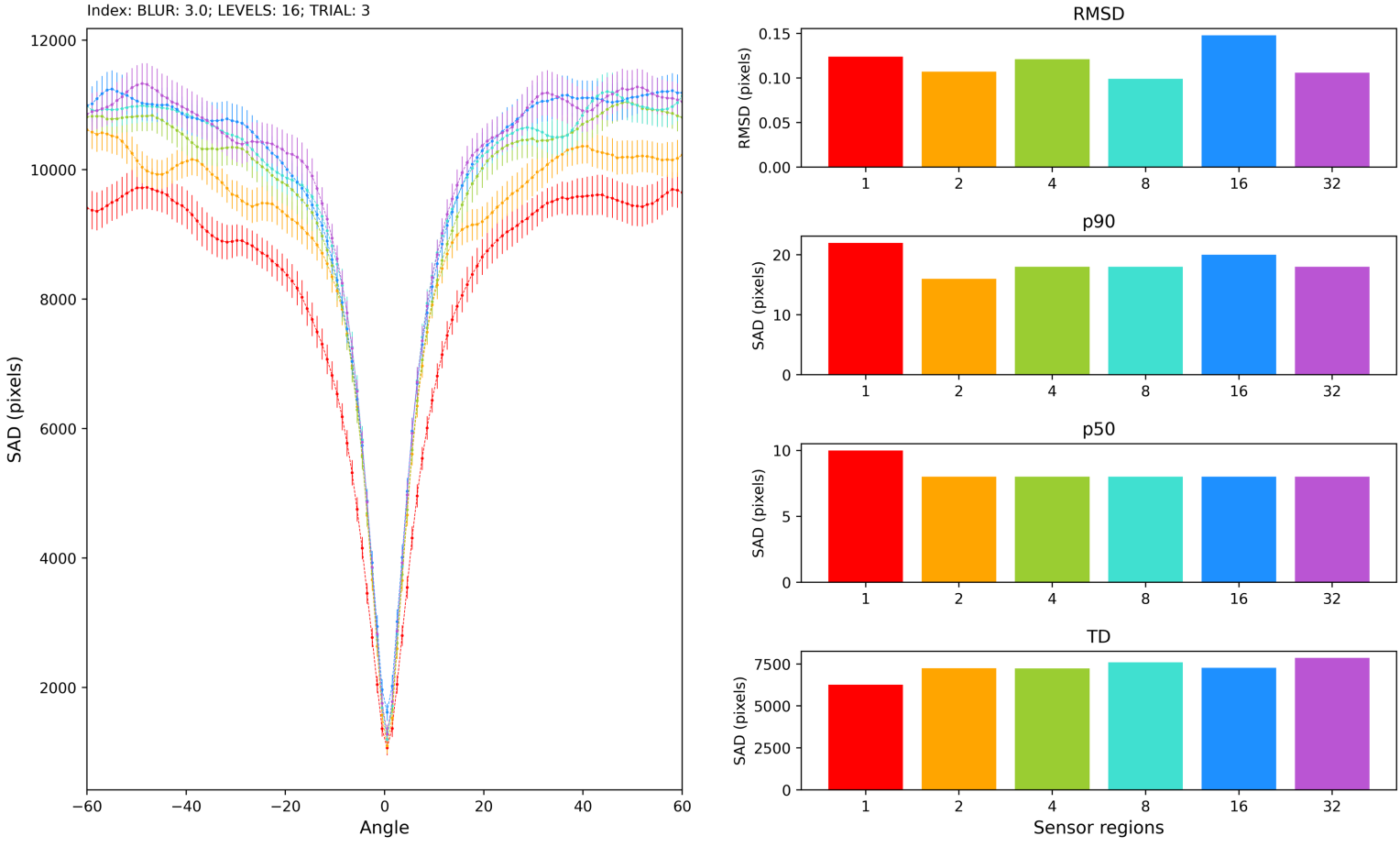




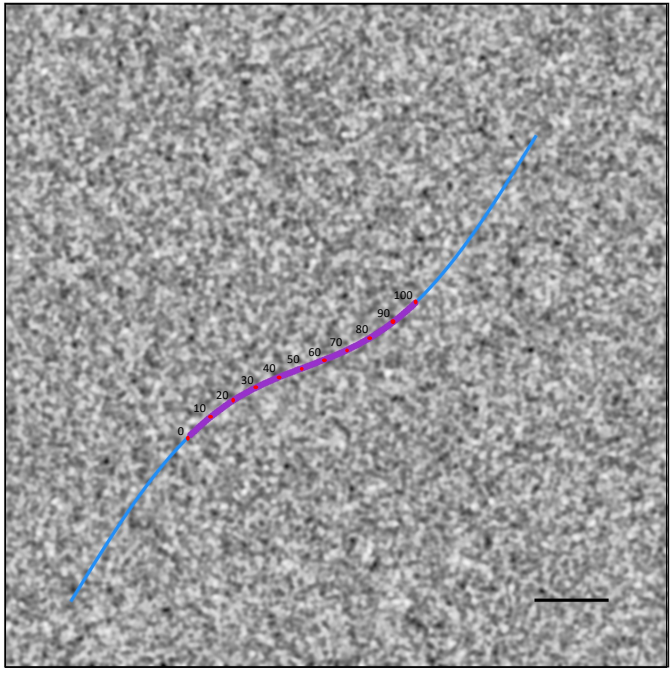


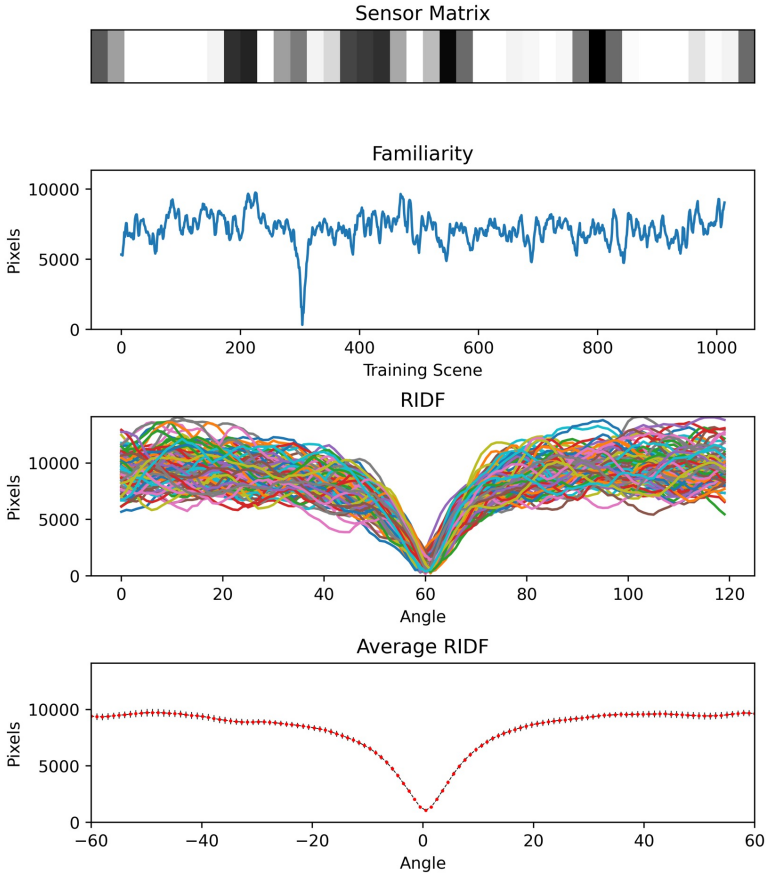
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 53.32; RMSD/dist: 0.133; TD: 7607; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 16; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

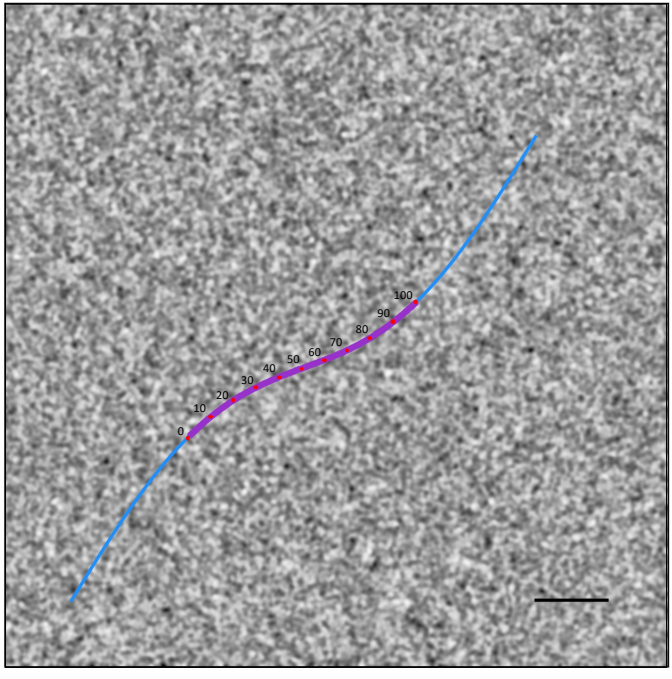


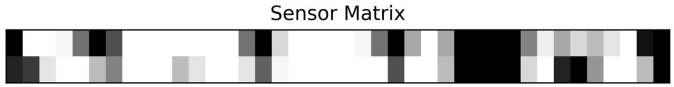


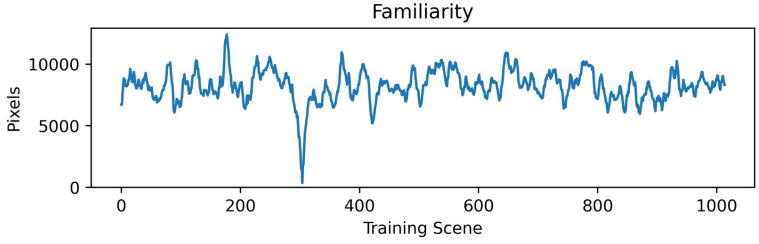
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

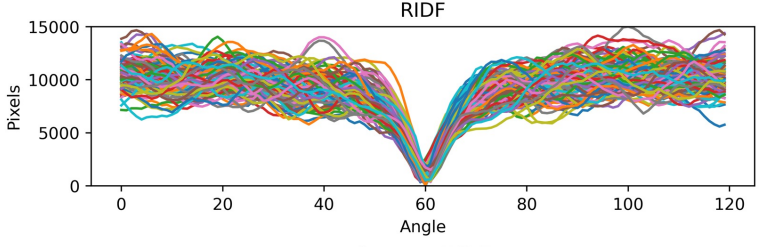
Navigation stats: RMSD error: 49.78; RMSD/dist: 0.124; TD: 6266; p90: 22; p50: 10; complete: 0

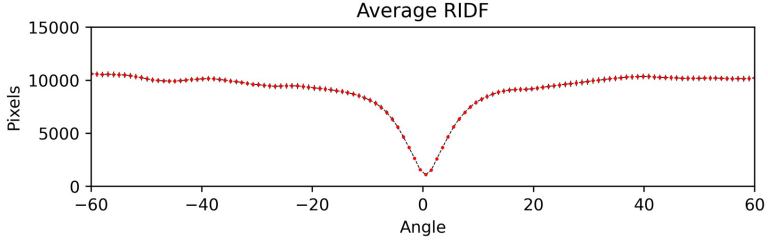
100%







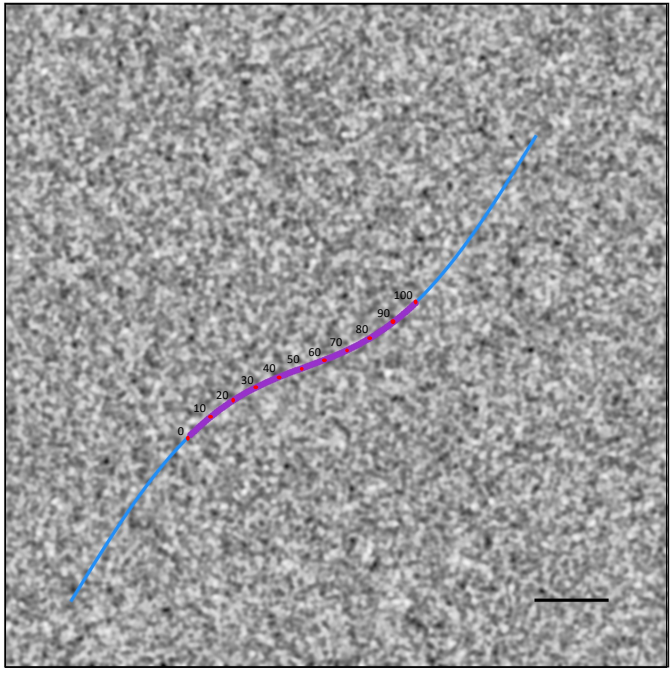


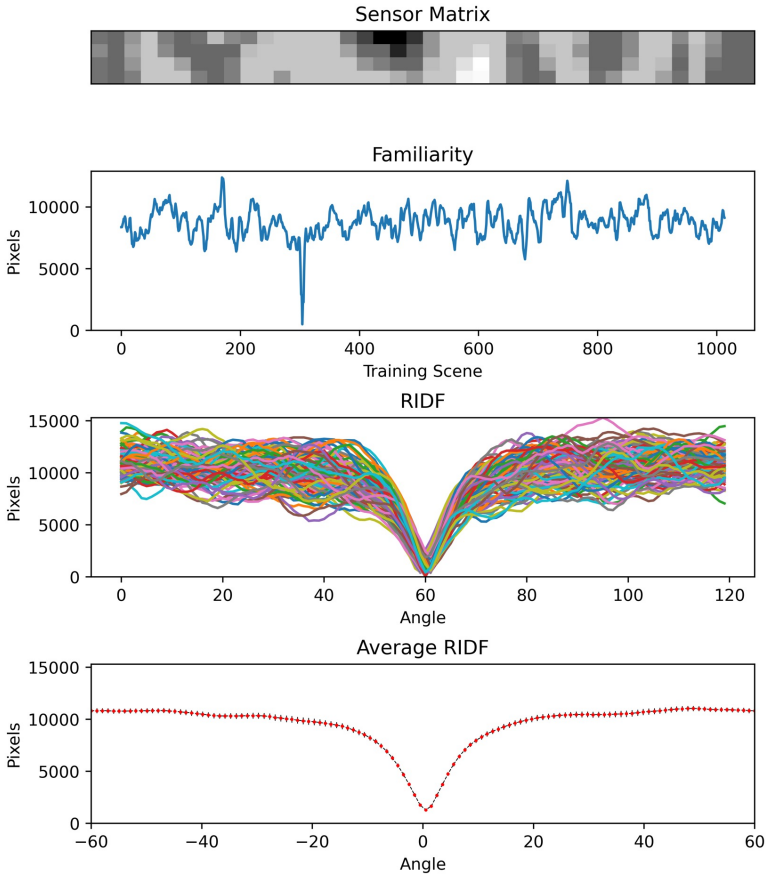


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 42.89; RMSD/dist: 0.107; TD: 7246; p90: 16; p50: 8; complete: 0

100%

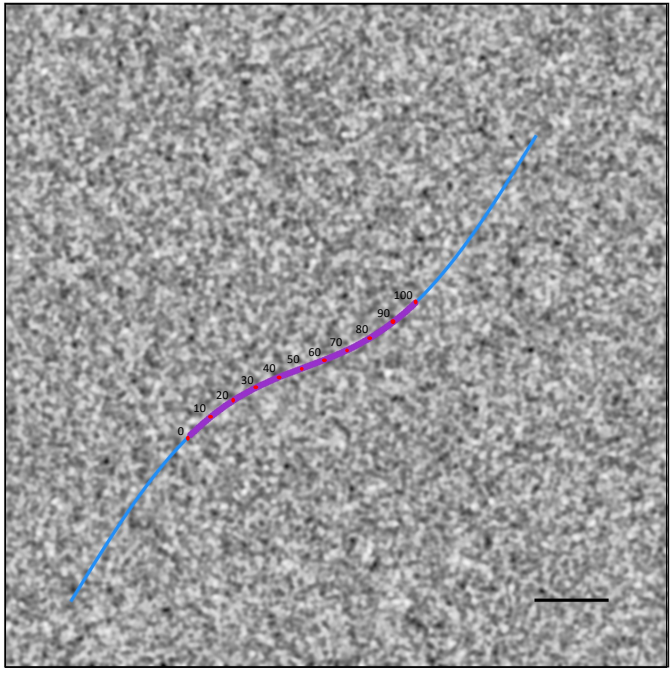


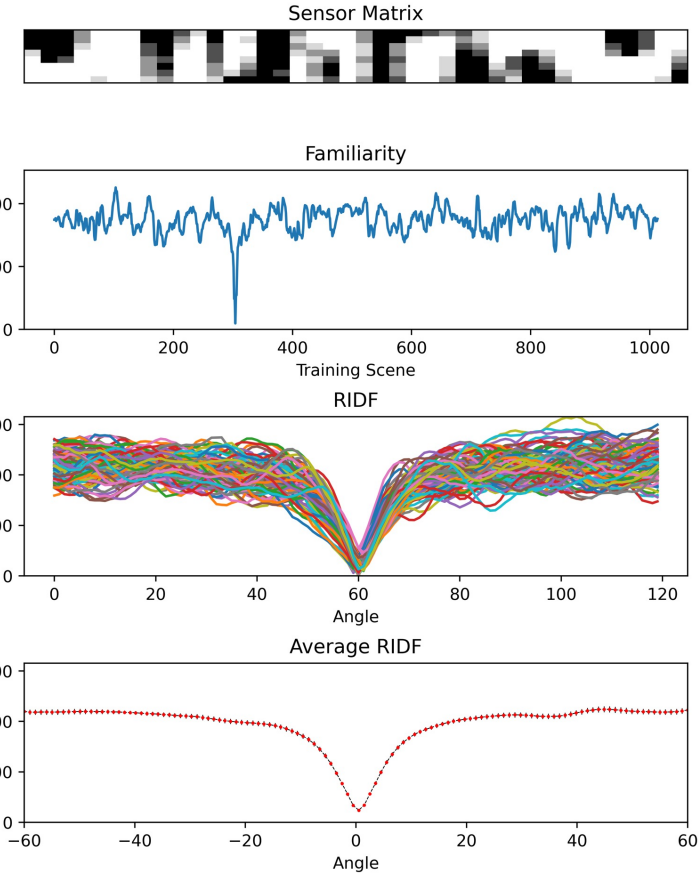


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 48.49; RMSD/dist: 0.121; TD: 7241; p90: 18; p50: 8; complete: 0

100%

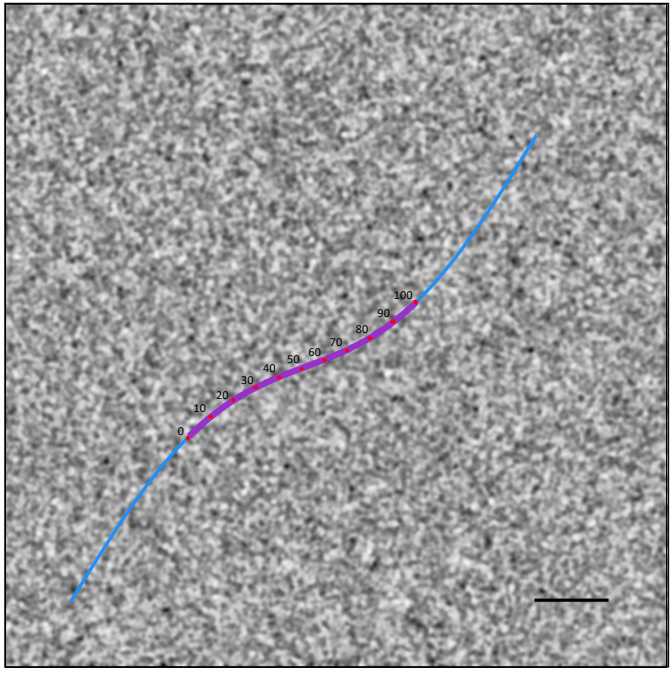


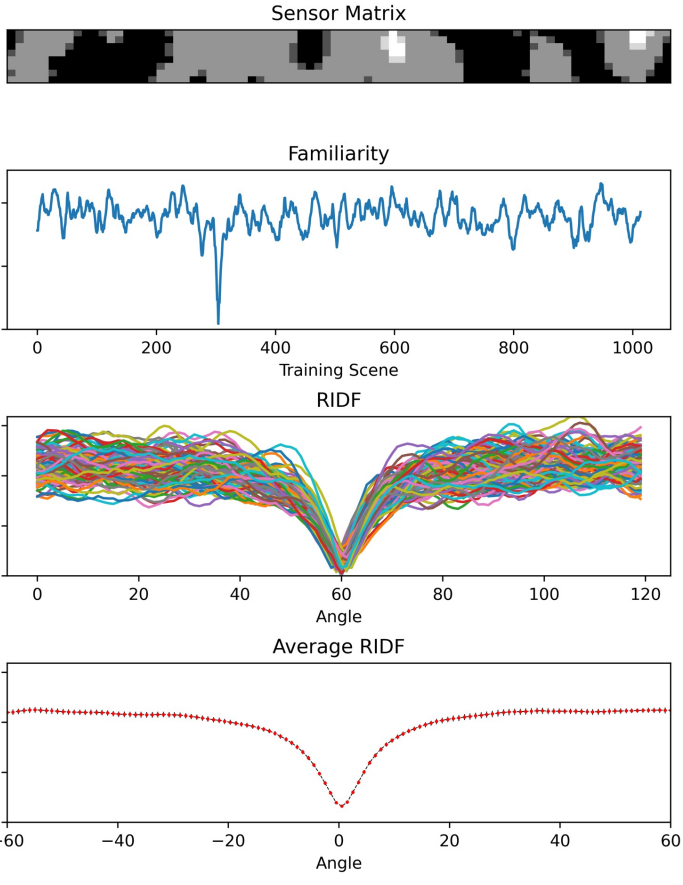


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 39.54; RMSD/dist: 0.099; TD: 7597; p90: 18; p50: 8; complete: 0

100%

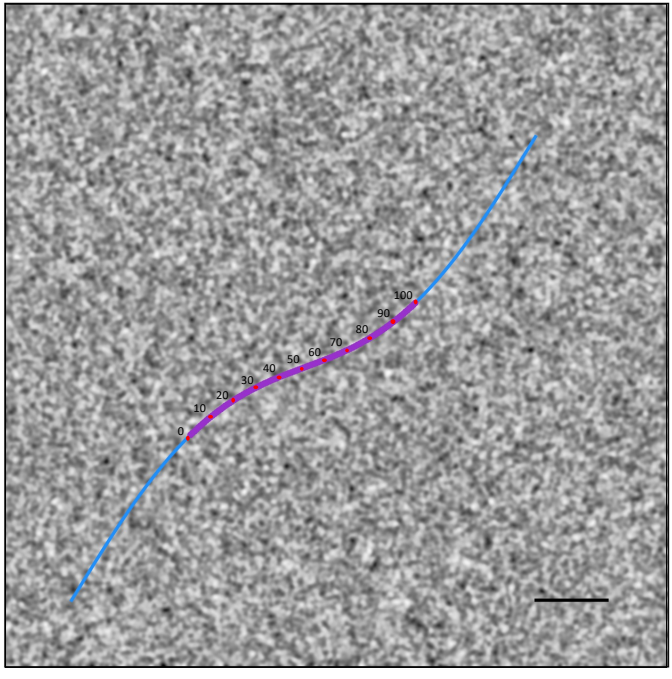


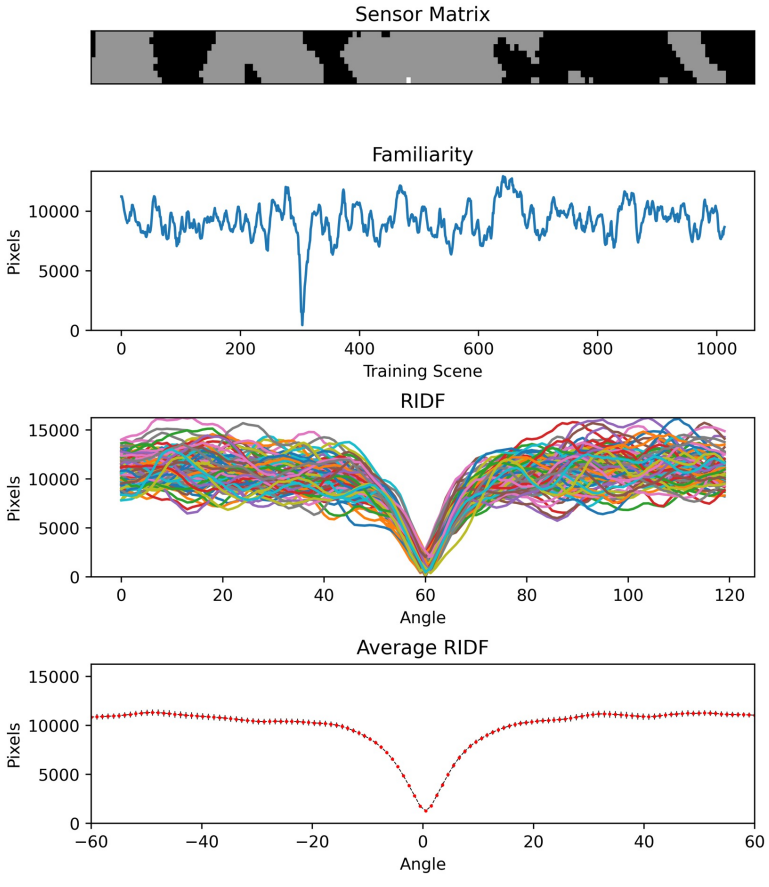


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 59.33; RMSD/dist: 0.148; TD: 7275; p90: 20; p50: 8; complete: 0

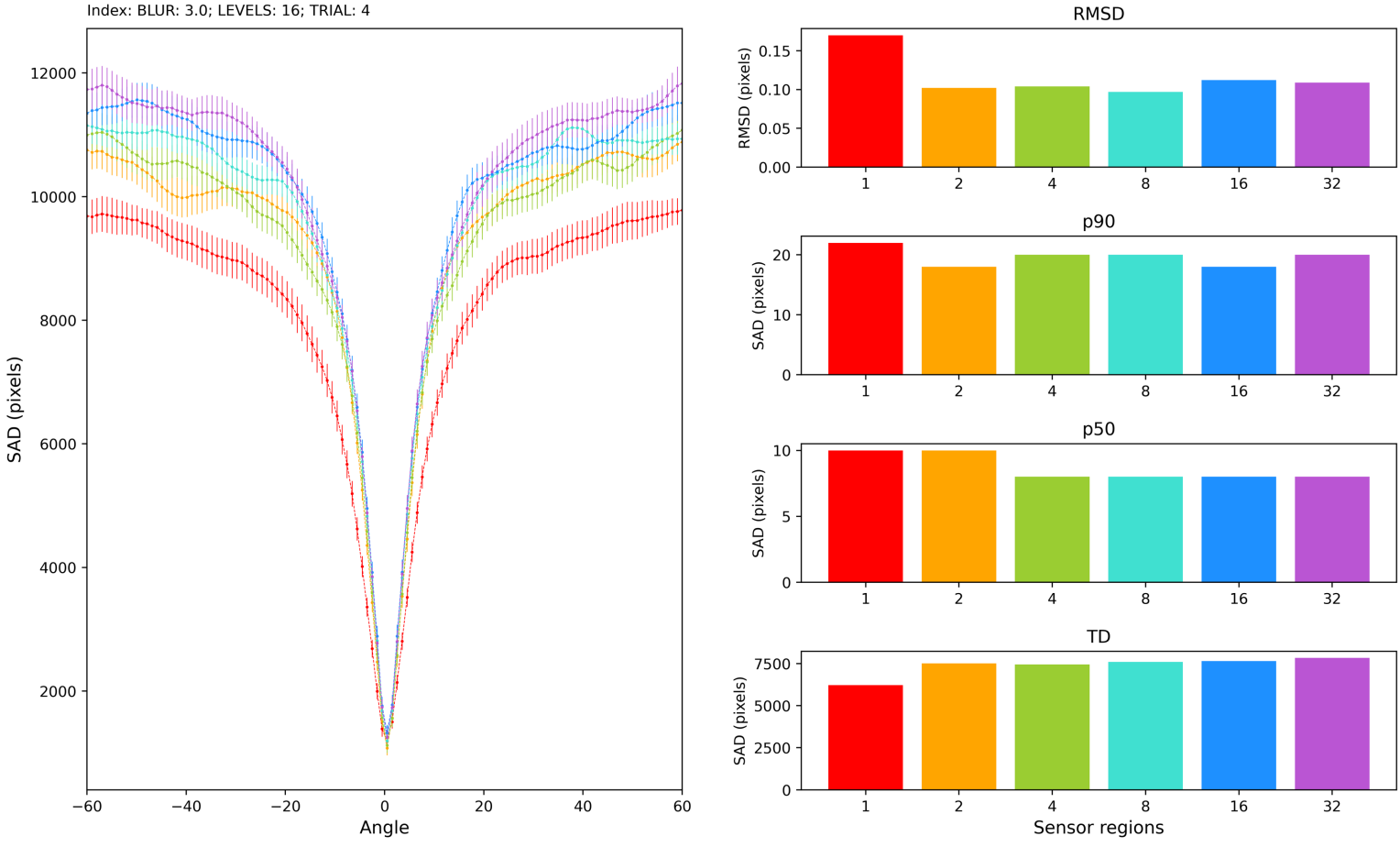
100%



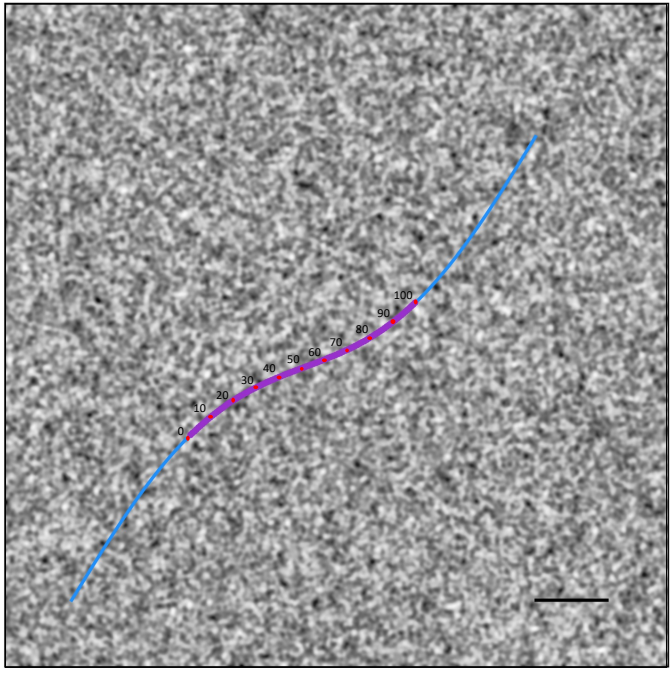


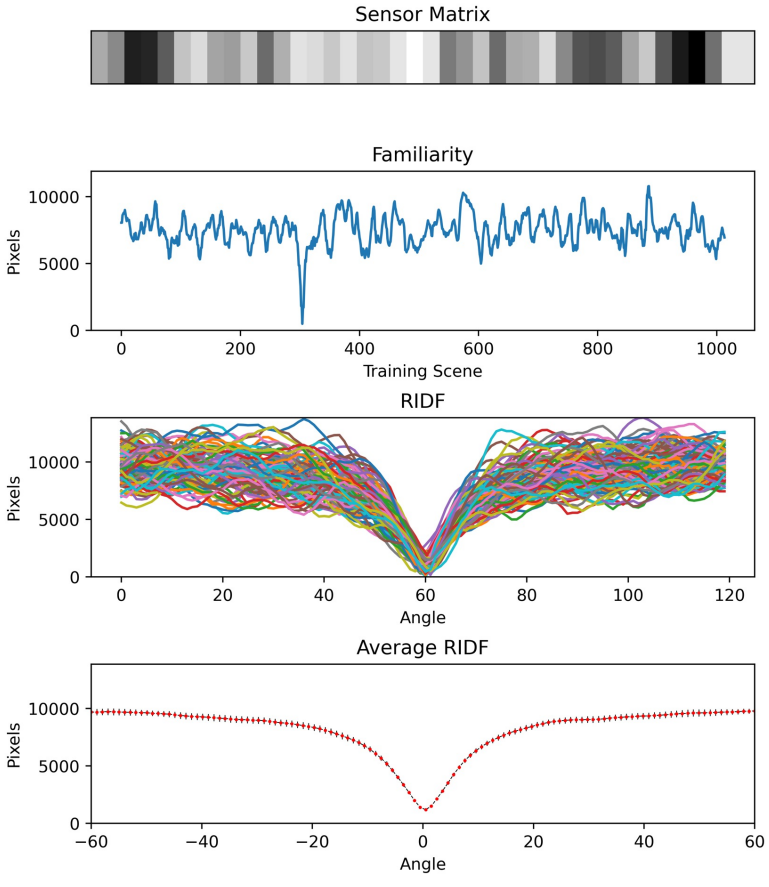
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 42.43; RMSD/dist: 0.106; TD: 7858; p90: 18; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 16; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

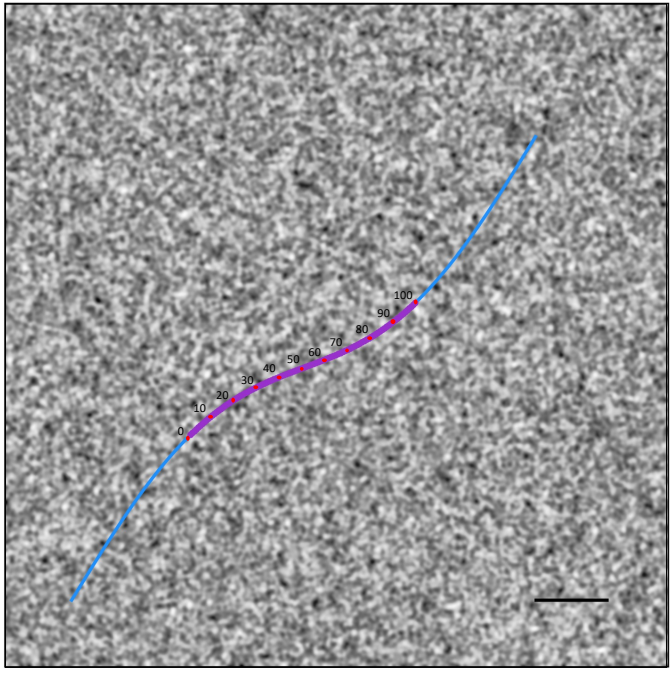


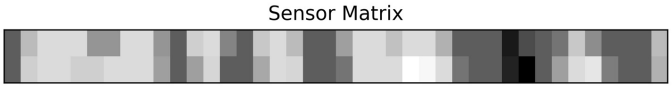


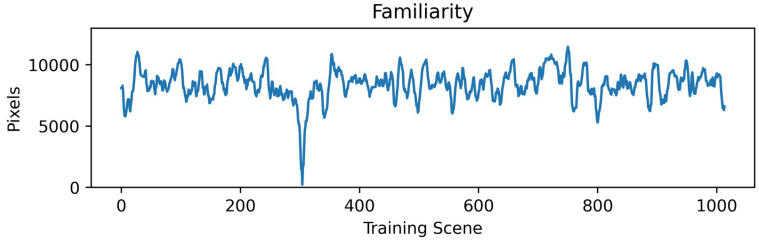
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

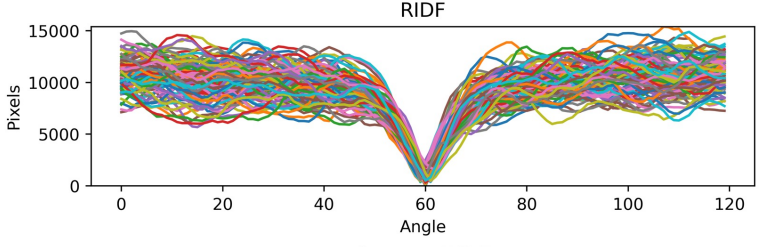
Navigation stats: RMSD error: 67.94; RMSD/dist: 0.170; TD: 6217; p90: 22; p50: 10; complete: 0

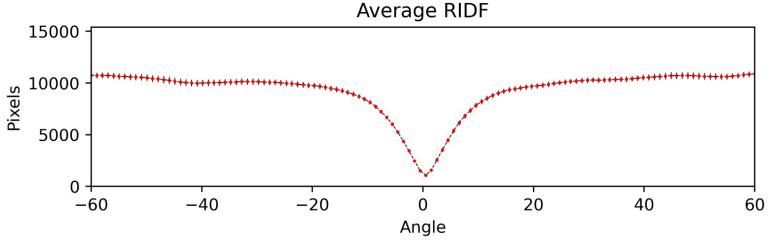
100%







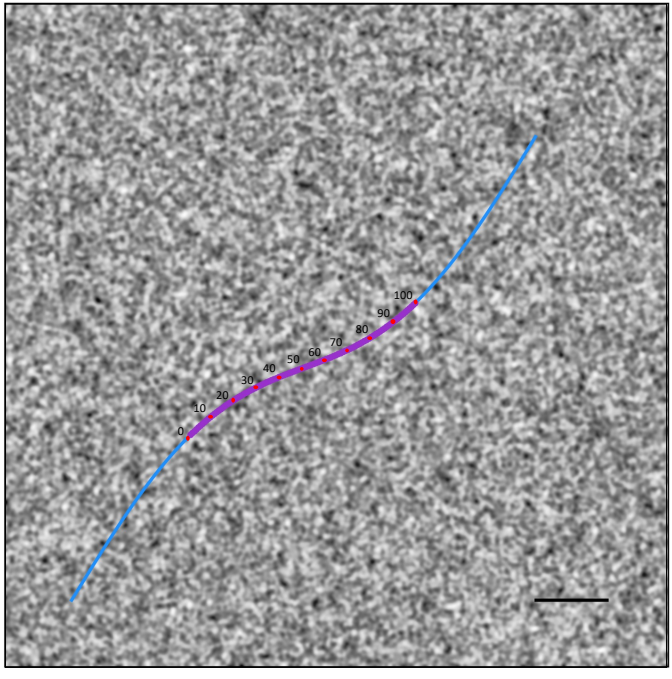


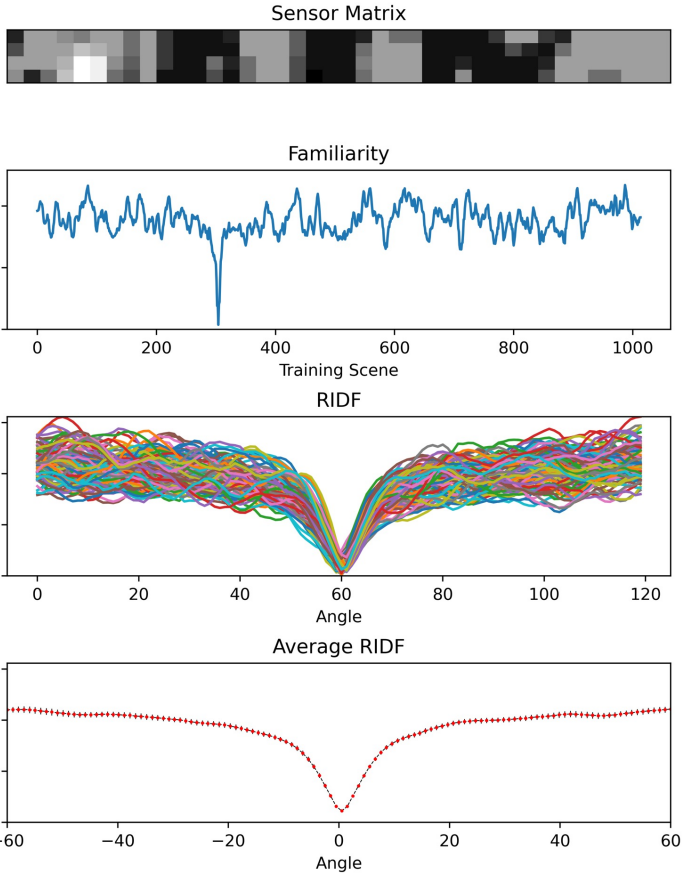


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 40.86; RMSD/dist: 0.102; TD: 7511; p90: 18; p50: 10; complete: 0

100%

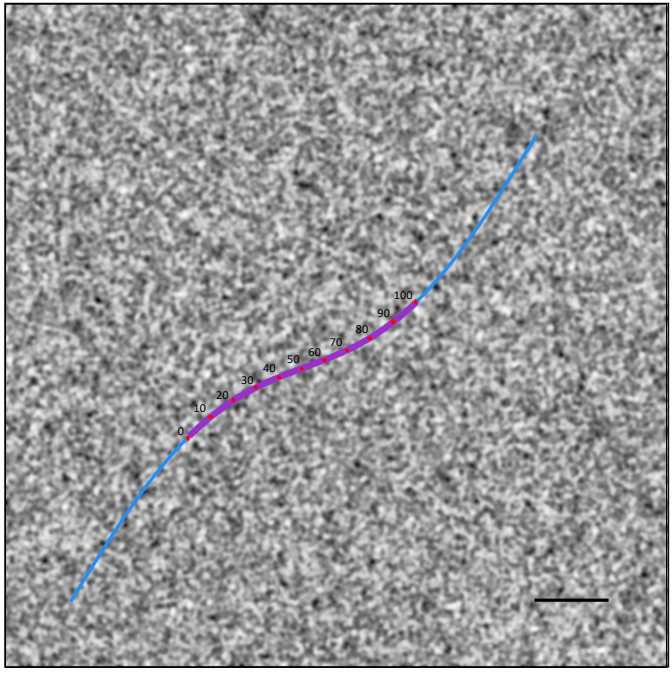


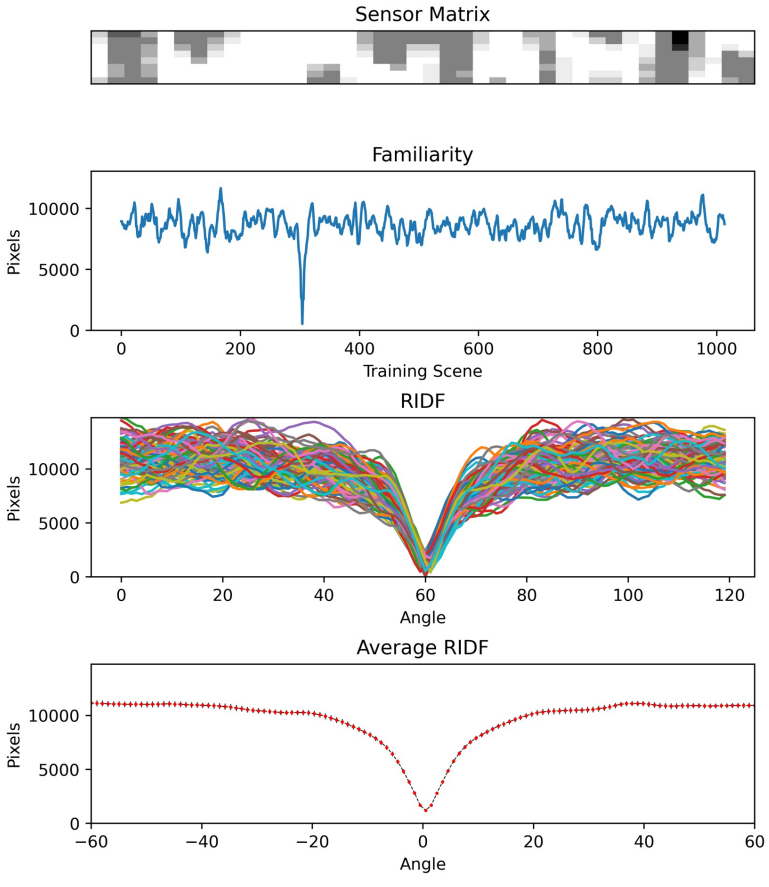


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 41.62; RMSD/dist: 0.104; TD: 7451; p90: 20; p50: 8; complete: 0

100%

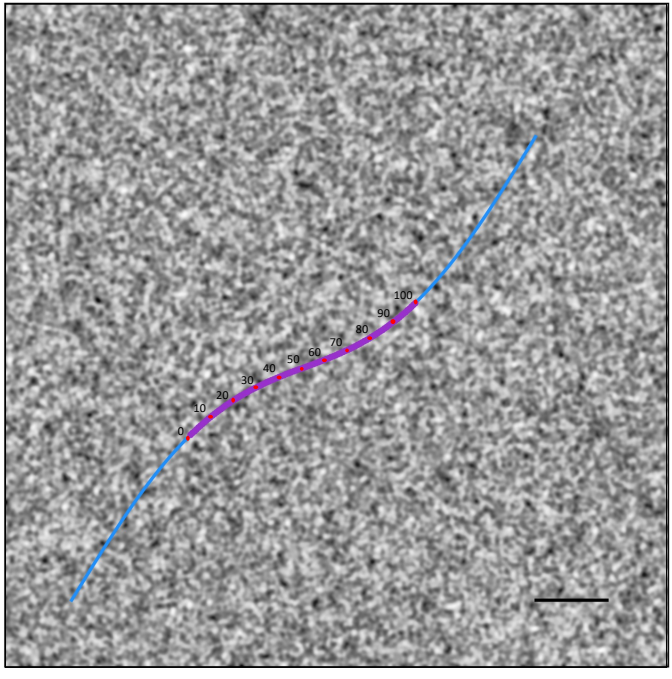


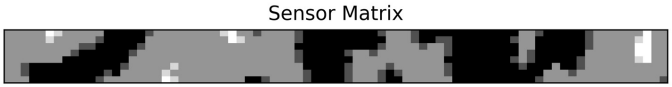


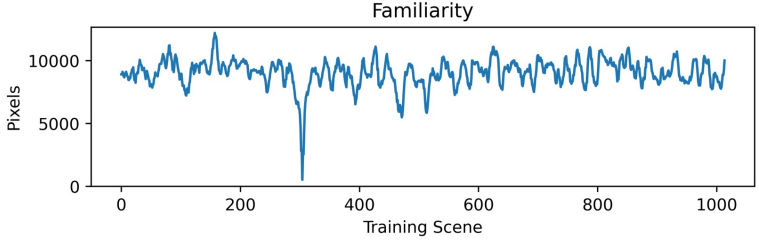
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

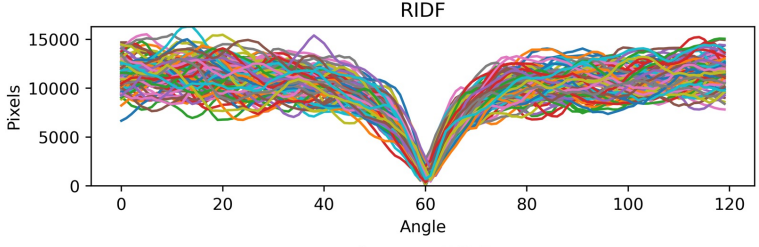
Navigation stats: RMSD error: 38.89; RMSD/dist: 0.097; TD: 7603; p90: 20; p50: 8; complete: 0

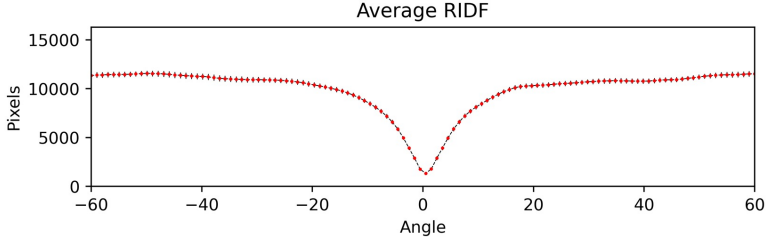
100%







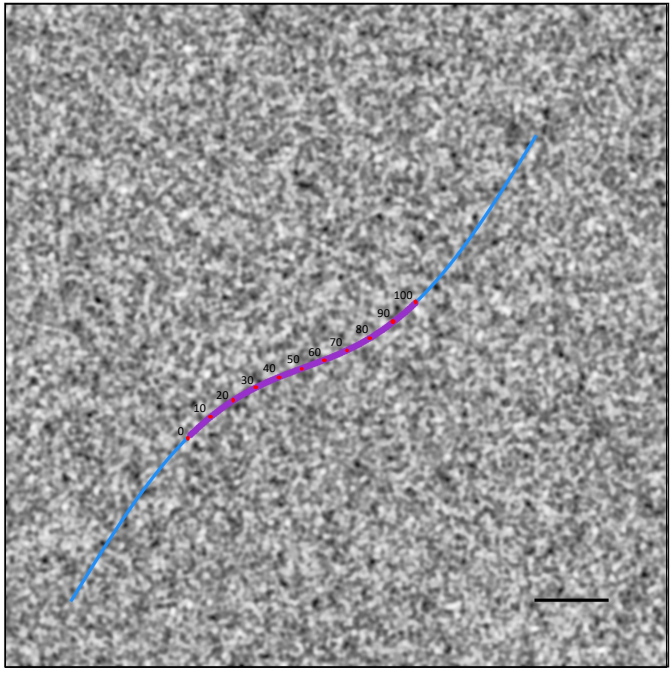


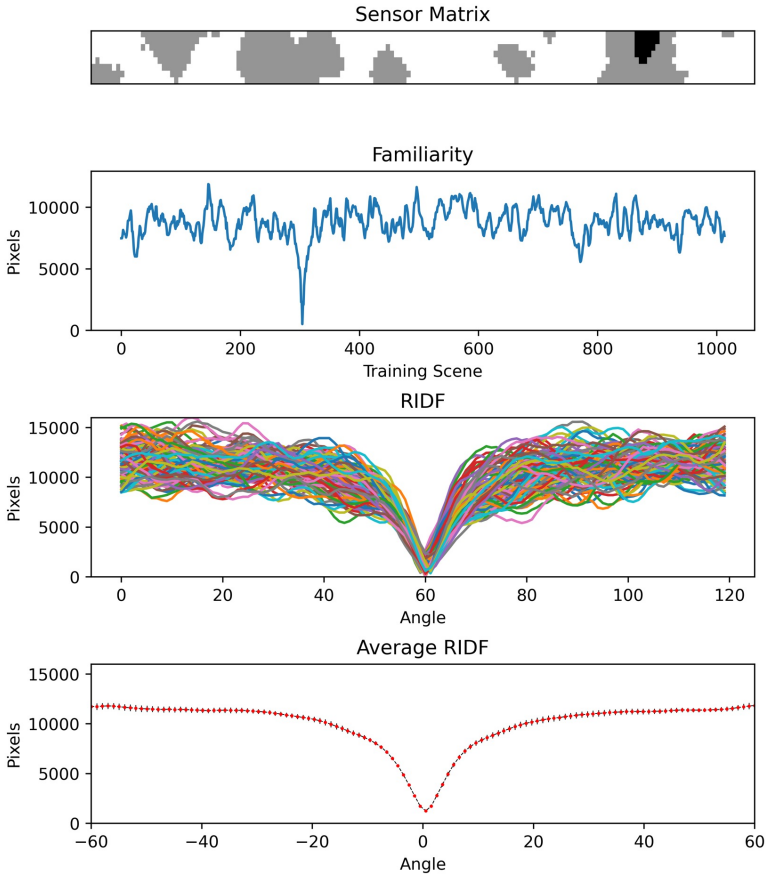


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 44.87; RMSD/dist: 0.112; TD: 7653; p90: 18; p50: 8; complete: 0

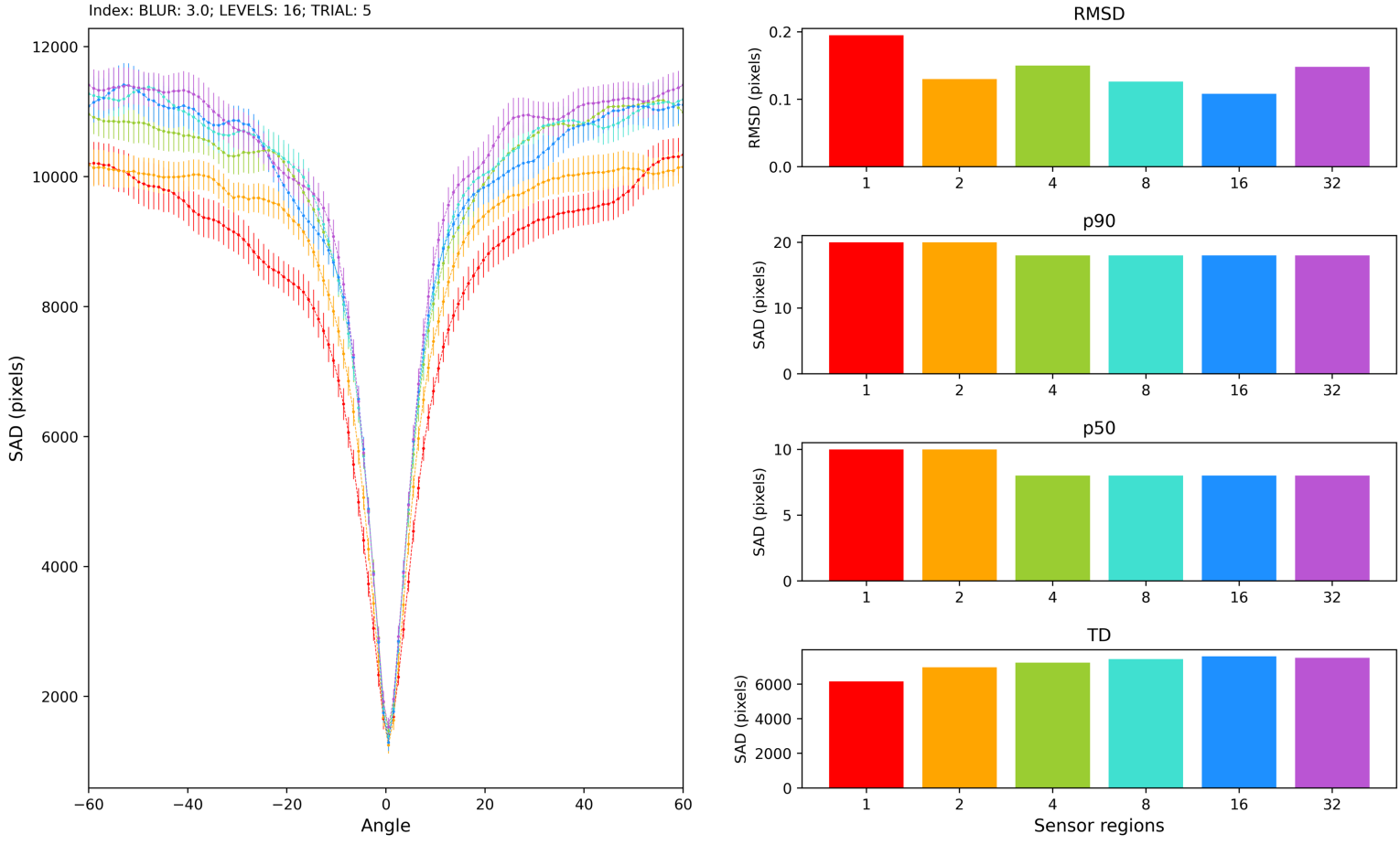
100%



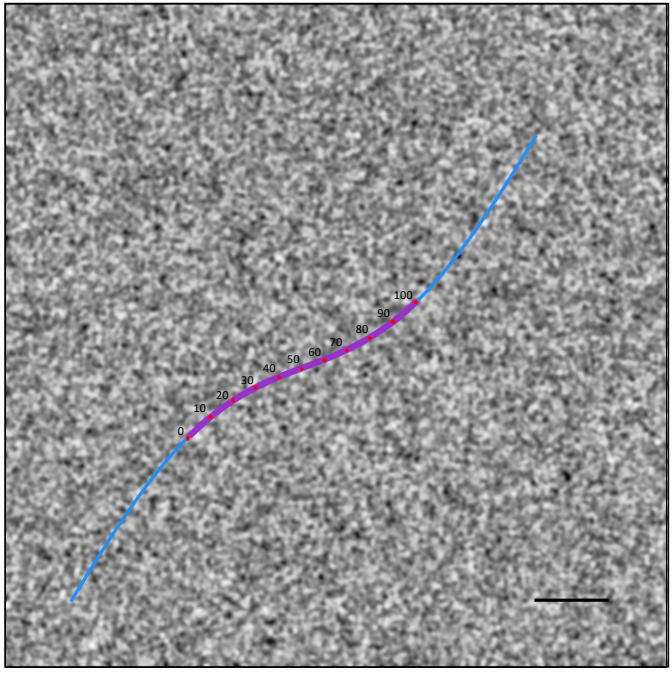


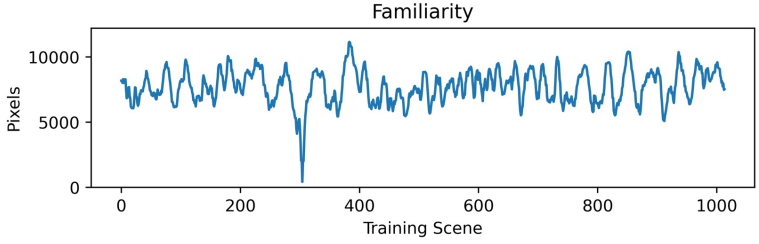
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

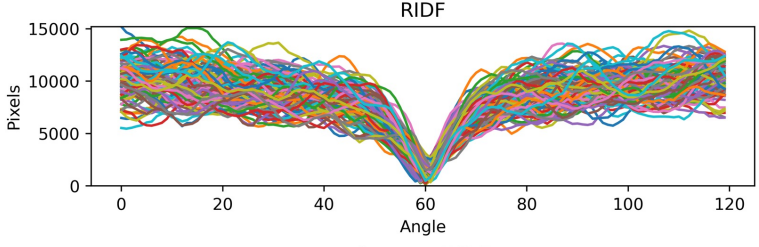
Navigation stats: RMSD error: 43.55; RMSD/dist: 0.109; TD: 7835; p90: 20; p50: 8; complete: 0

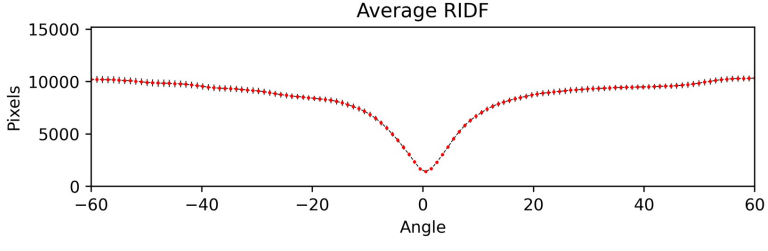

Index: BLUR: 3.0; LEVELS: 16; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%





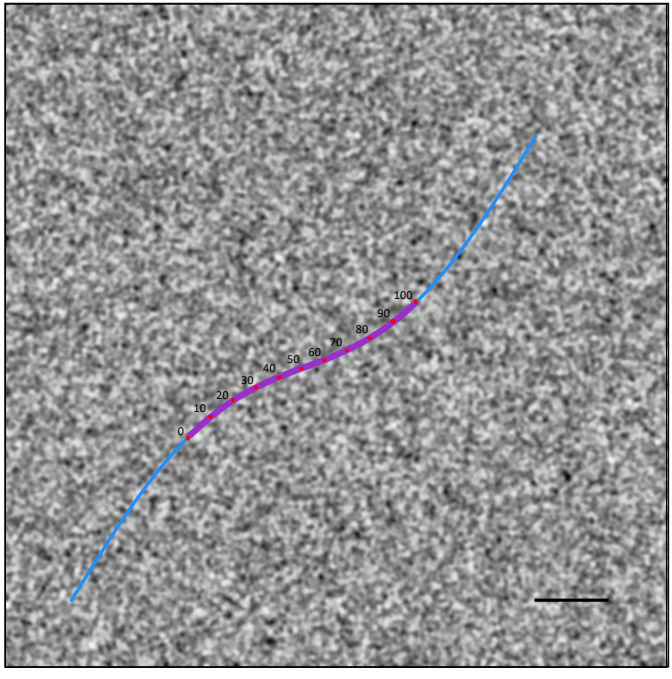


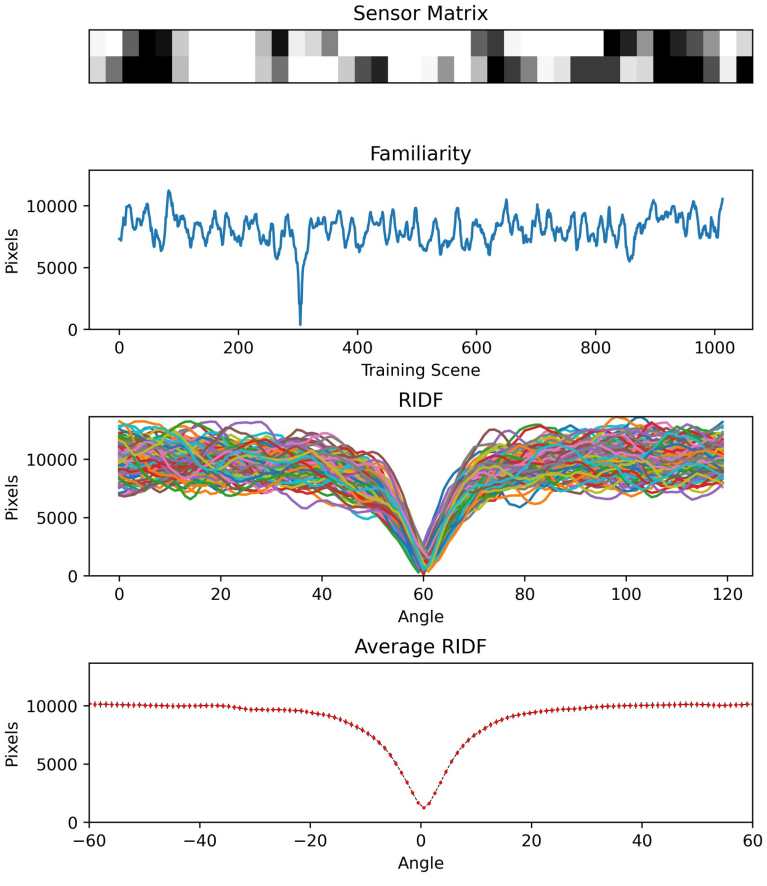


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 78.09; RMSD/dist: 0.195; TD: 6155; p90: 20; p50: 10; complete: 0

100%

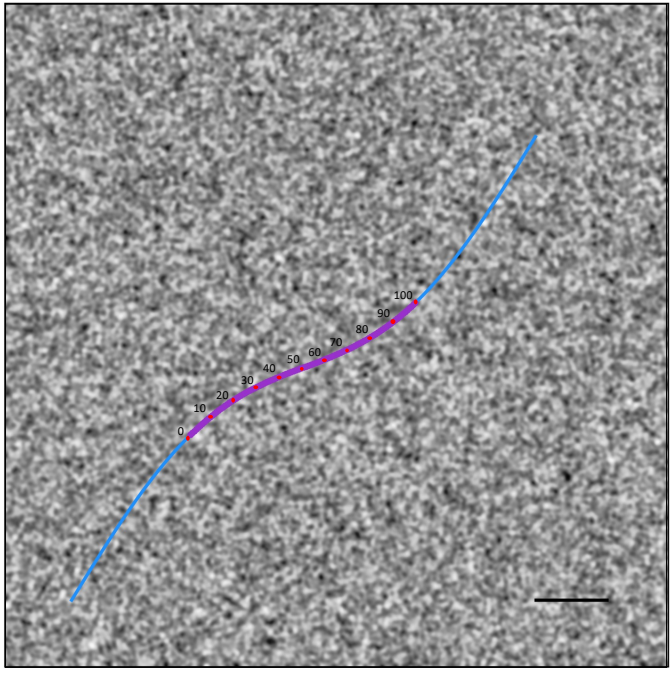


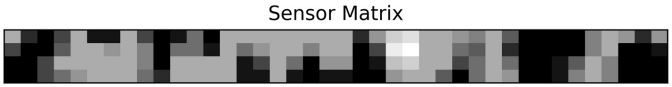


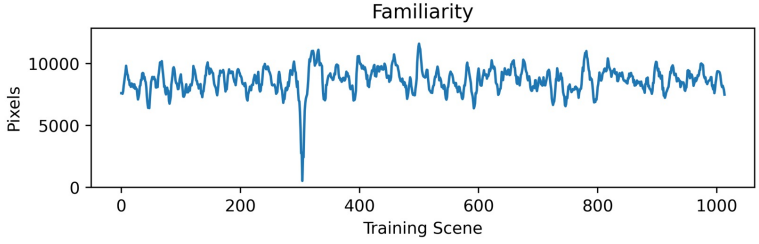
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

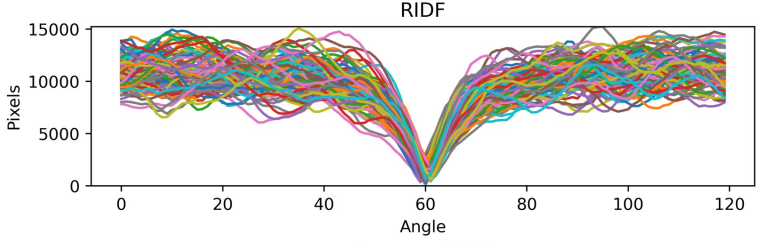
Navigation stats: RMSD error: 52.09; RMSD/dist: 0.130; TD: 6970; p90: 20; p50: 10; complete: 0

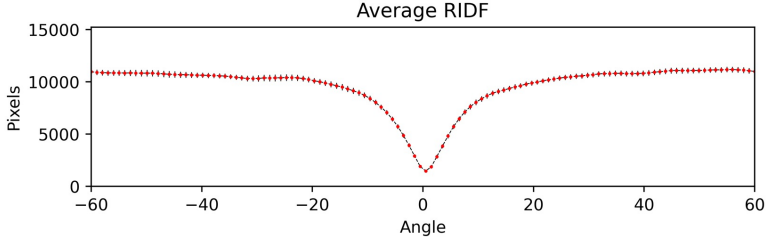
100%







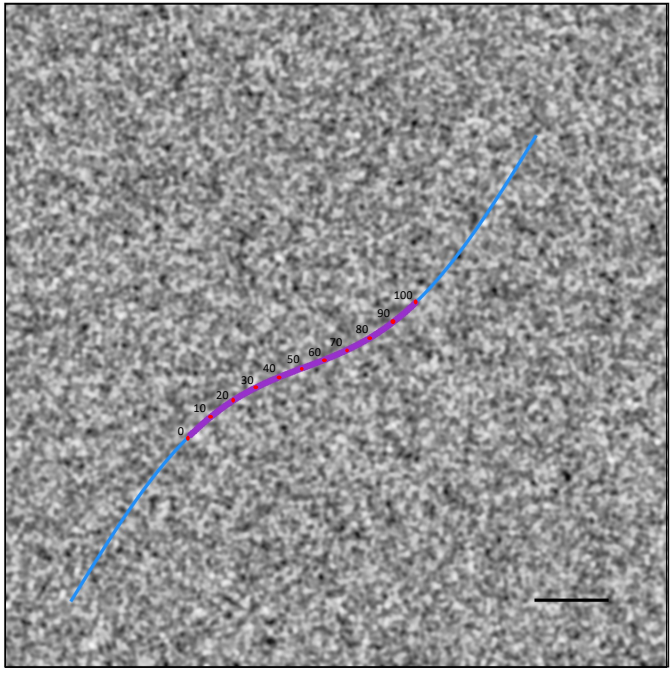


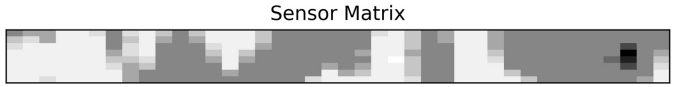


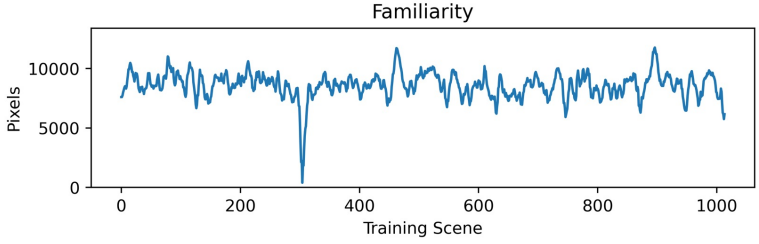
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

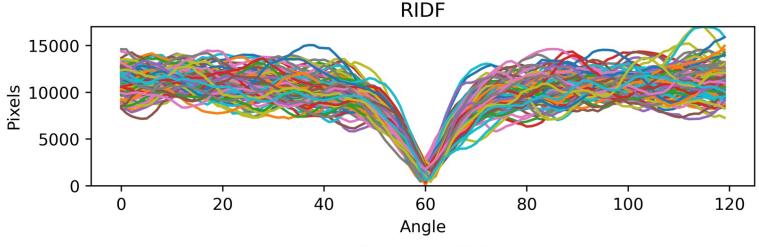
Navigation stats: RMSD error: 59.92; RMSD/dist: 0.150; TD: 7242; p90: 18; p50: 8; complete: 0

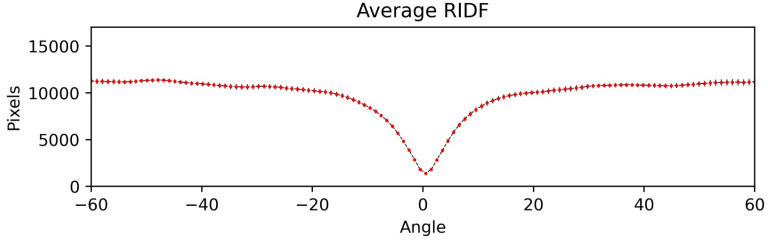
100%







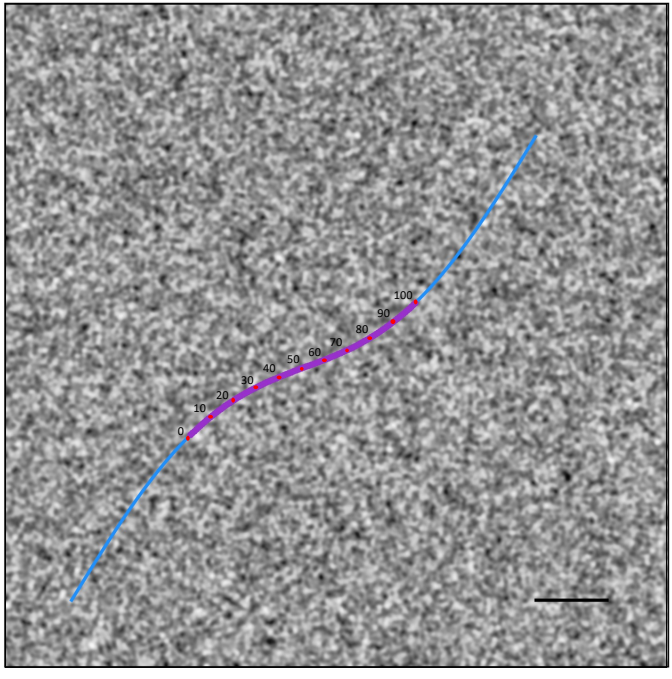


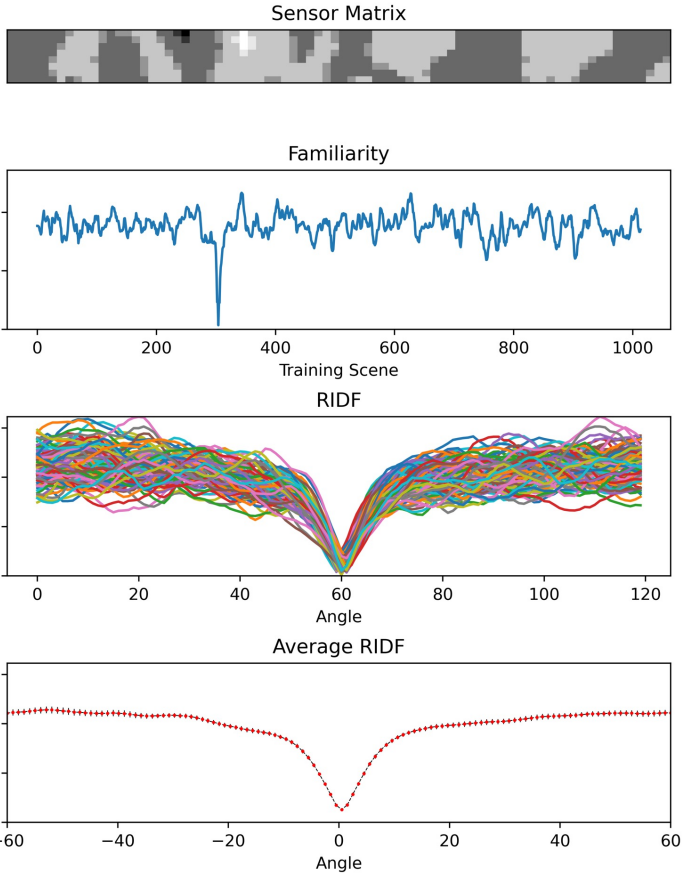


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 50.24; RMSD/dist: 0.126; TD: 7447; p90: 18; p50: 8; complete: 0

100%

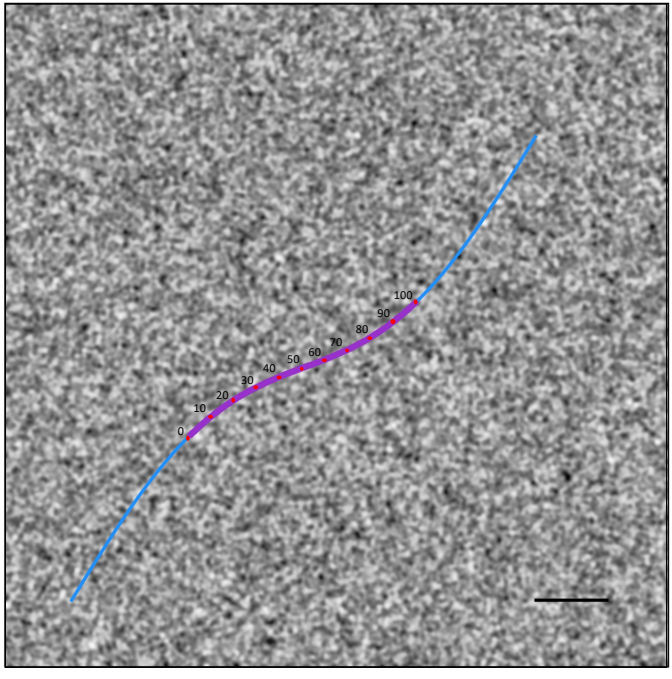


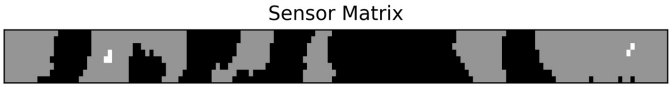


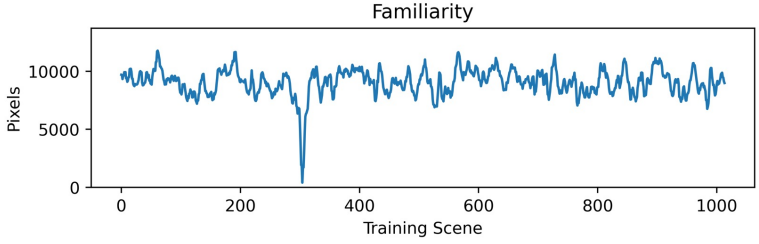
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

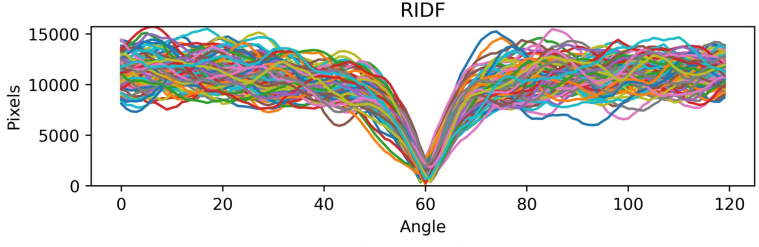
Navigation stats: RMSD error: 43.22; RMSD/dist: 0.108; TD: 7596; p90: 18; p50: 8; complete: 0

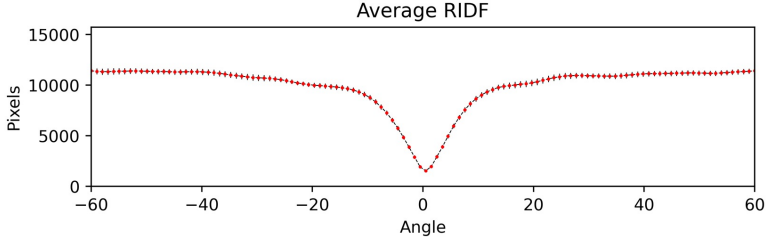
100%





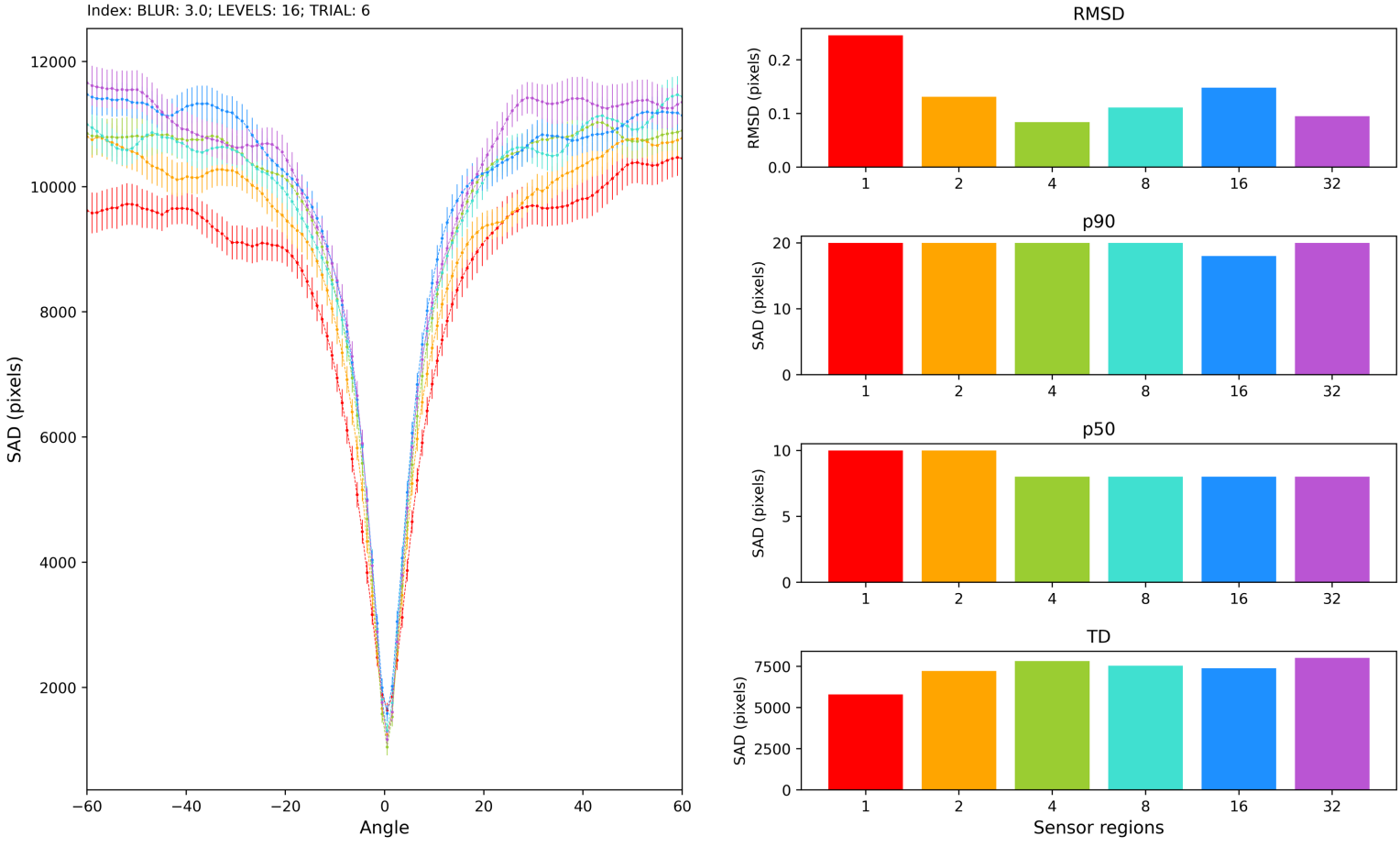




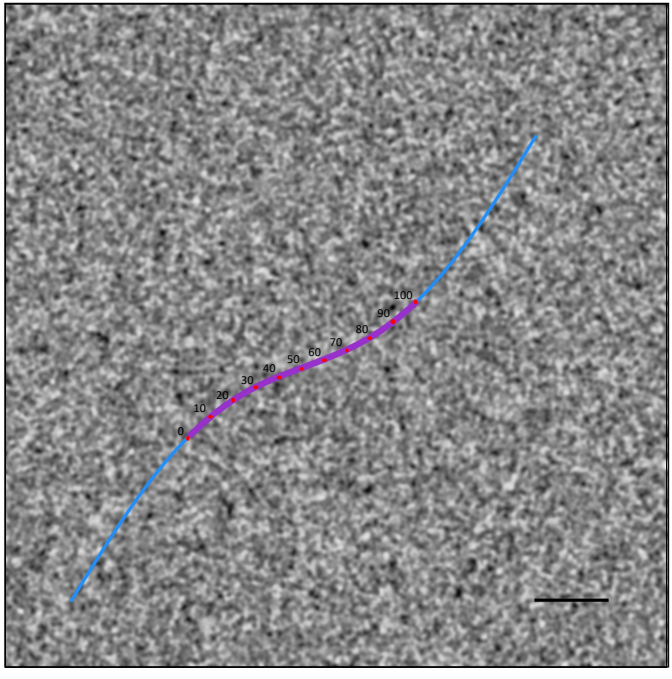


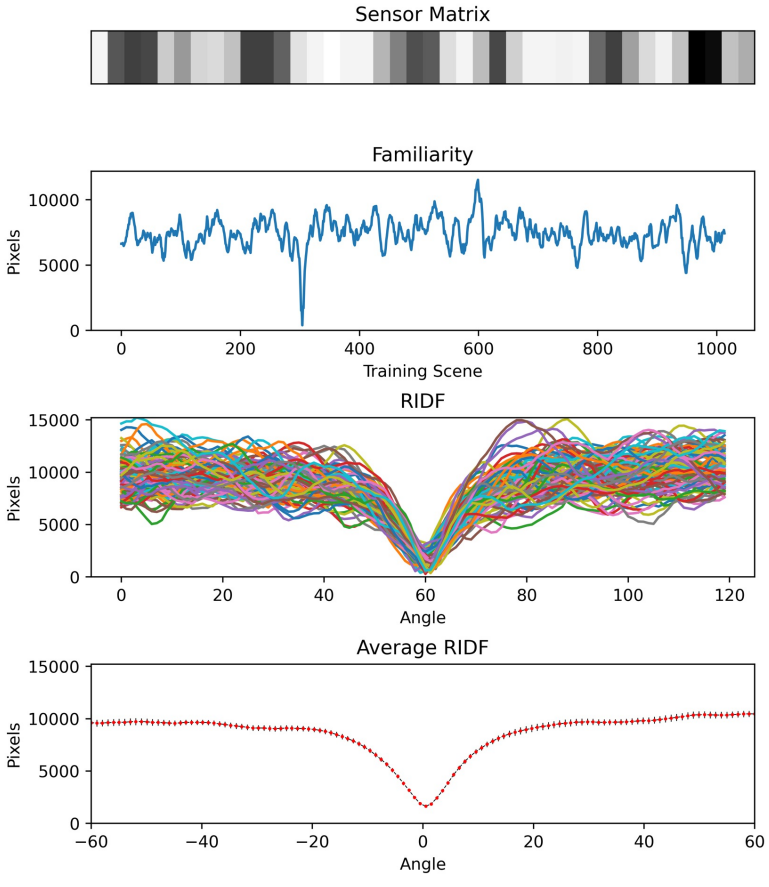
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 59.33; RMSD/dist: 0.148; TD: 7518; p90: 18; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 16; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

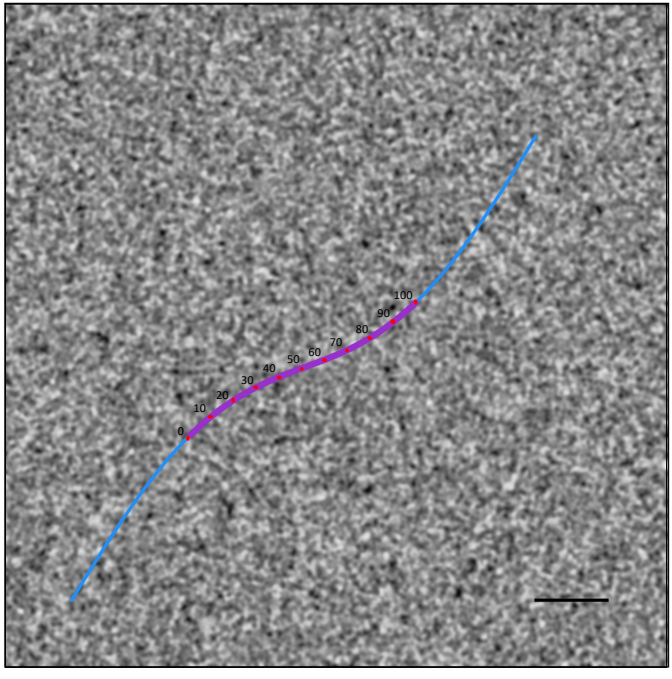


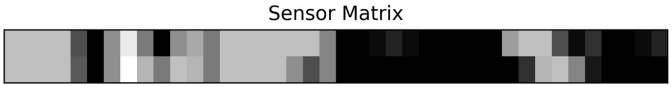


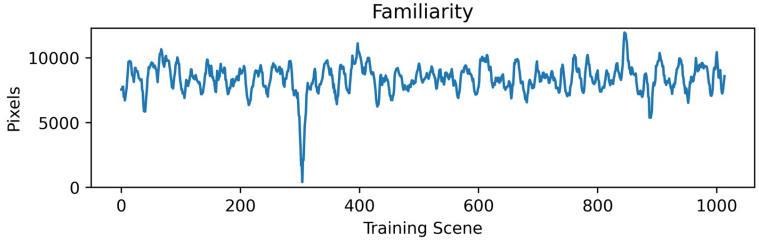
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

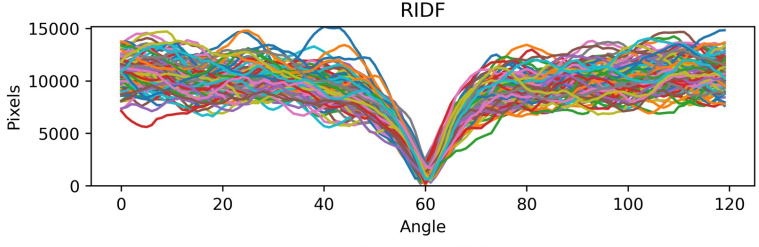
Navigation stats: RMSD error: 98.46; RMSD/dist: 0.246; TD: 5796; p90: 20; p50: 10; complete: 0

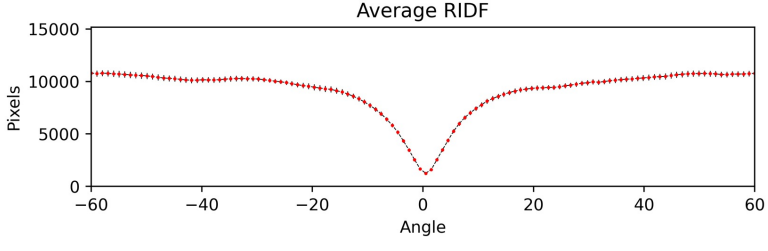
100%







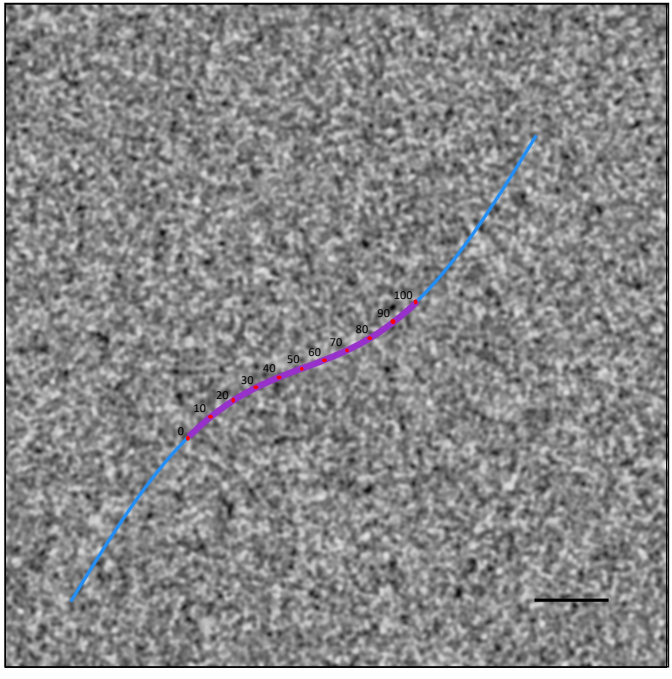


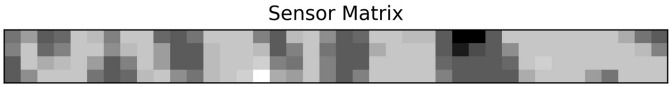


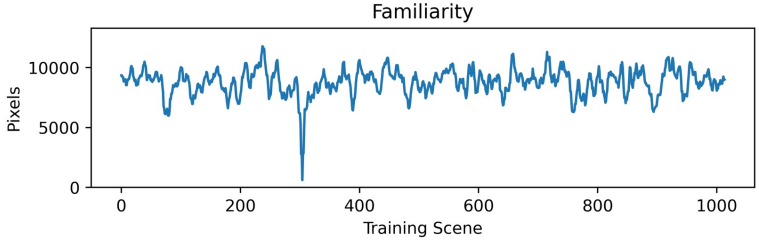
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

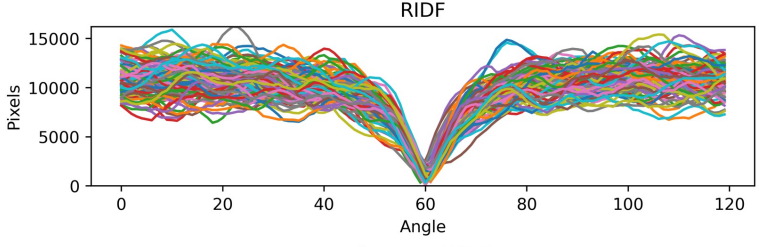
Navigation stats: RMSD error: 52.22; RMSD/dist: 0.131; TD: 7227; p90: 20; p50: 10; complete: 0

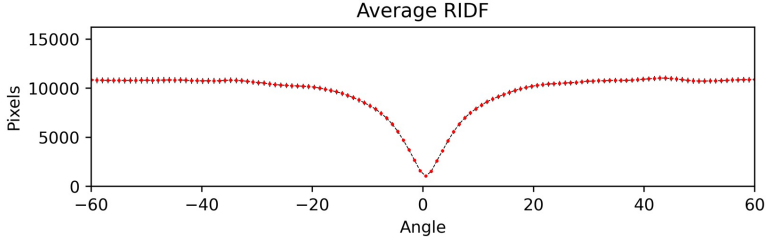
100%







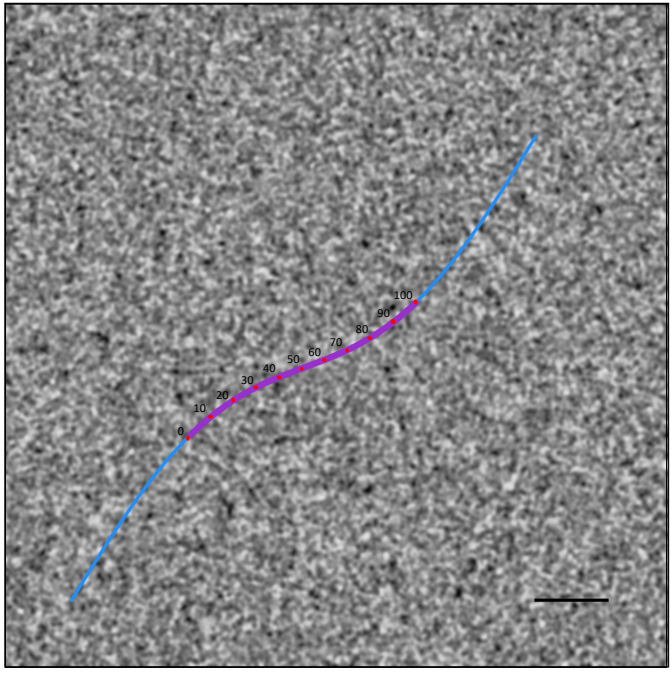


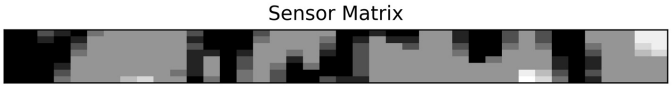


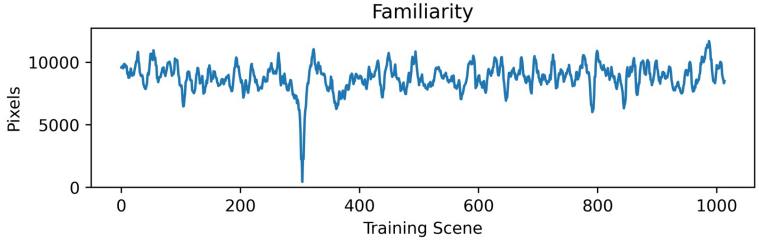
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

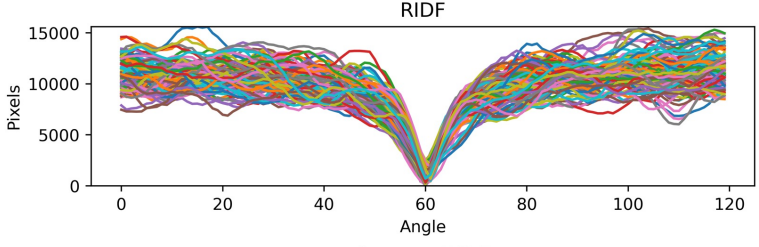
Navigation stats: RMSD error: 33.53; RMSD/dist: 0.084; TD: 7827; p90: 20; p50: 8; complete: 0

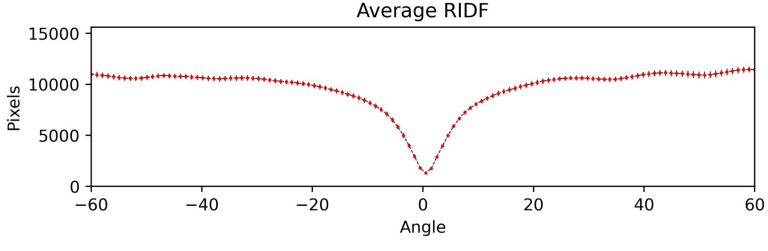
100%







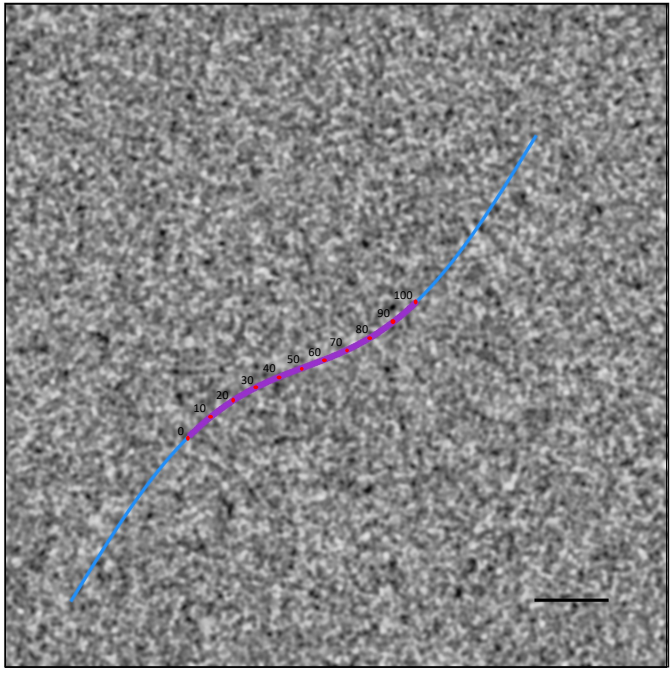


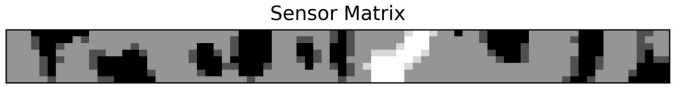


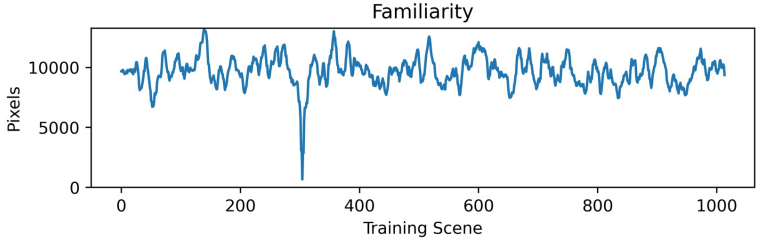
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

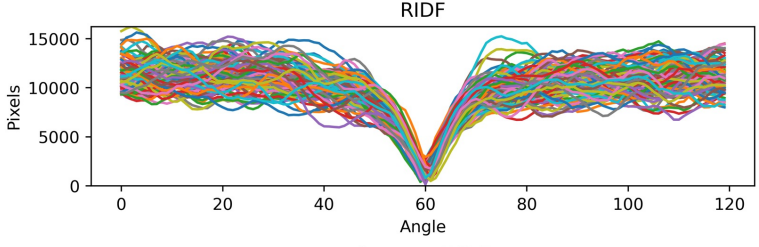
Navigation stats: RMSD error: 44.20; RMSD/dist: 0.111; TD: 7547; p90: 20; p50: 8; complete: 0

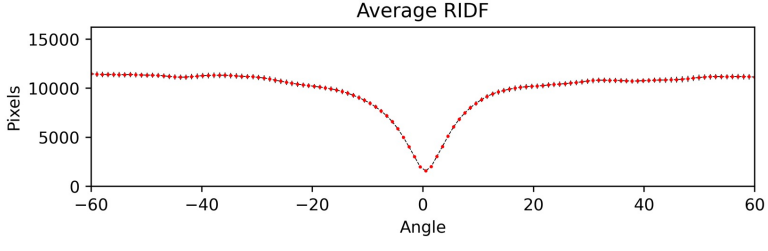
100%







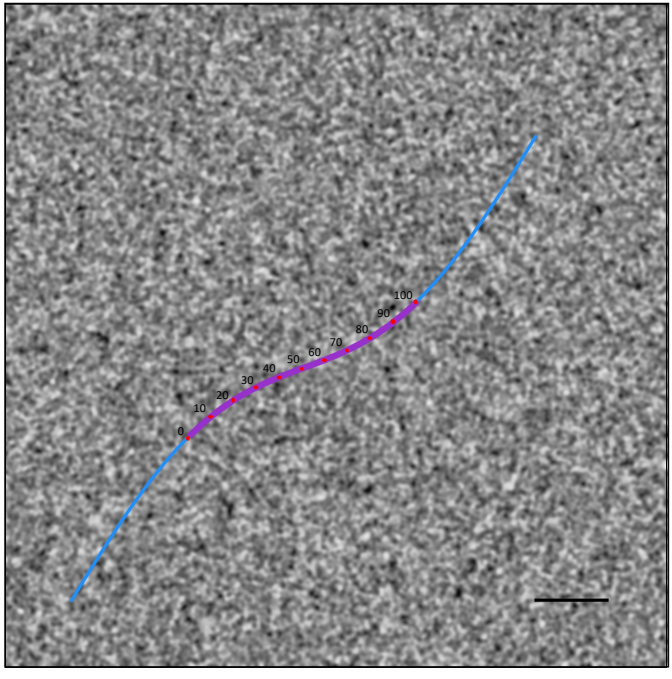


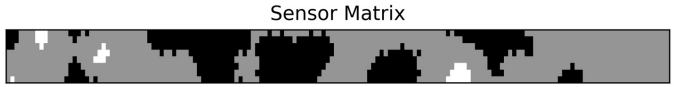


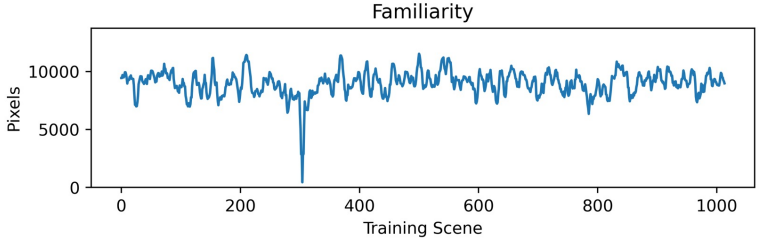
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

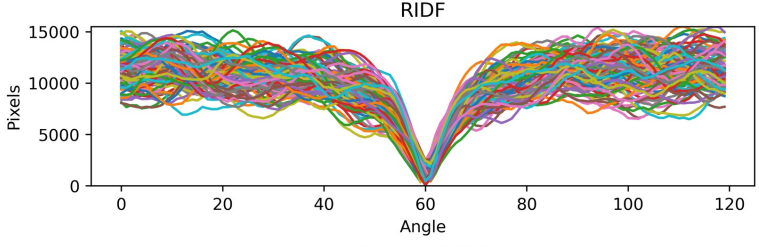
Navigation stats: RMSD error: 59.26; RMSD/dist: 0.148; TD: 7387; p90: 18; p50: 8; complete: 0

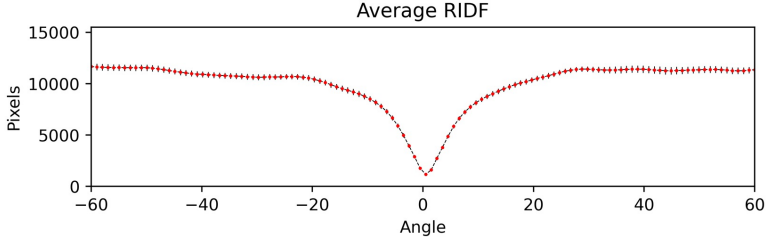
100%





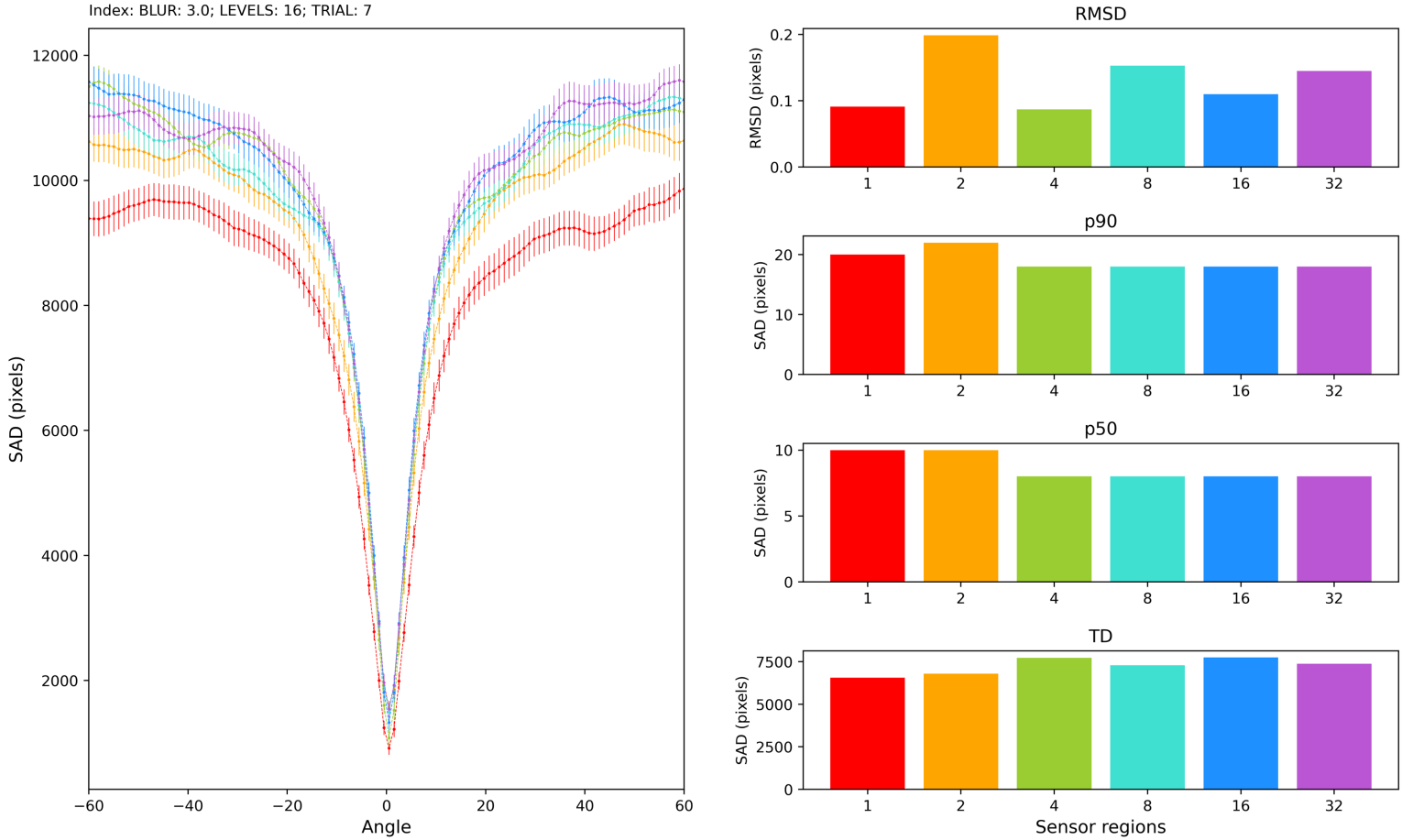




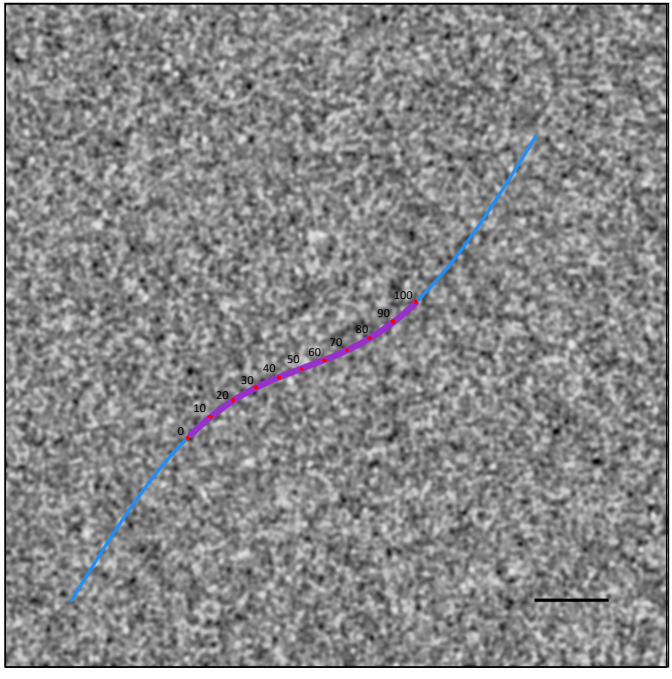


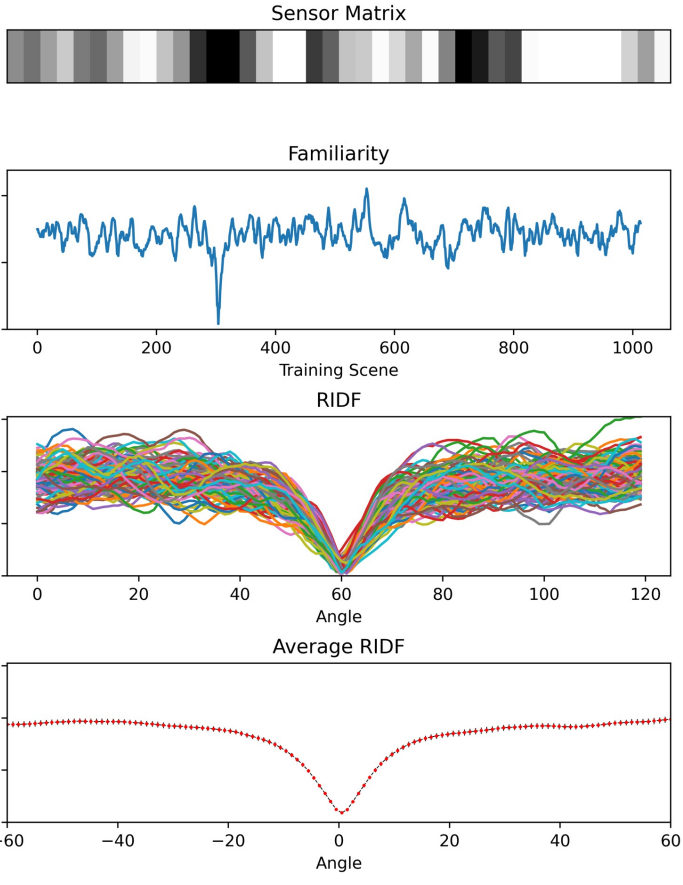
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 37.89; RMSD/dist: 0.095; TD: 8010; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 16; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

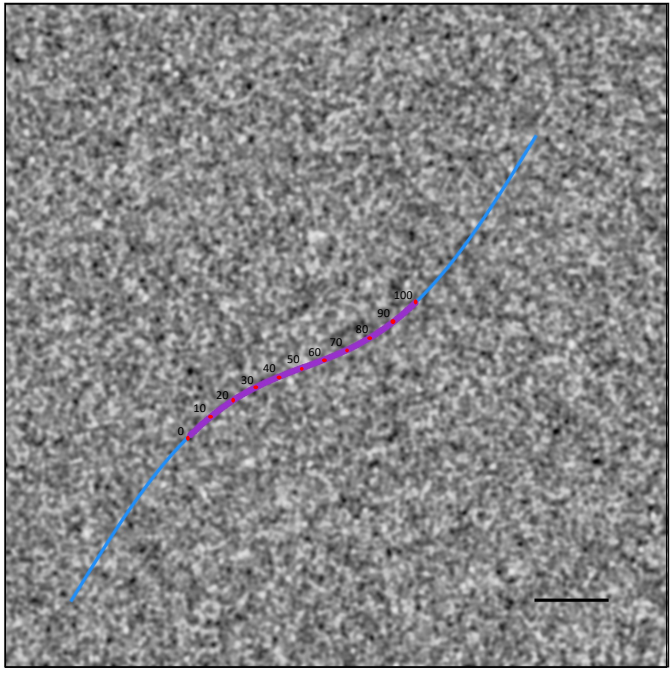


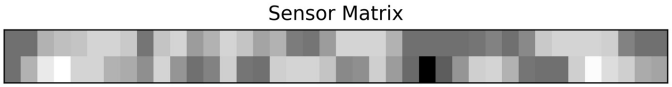


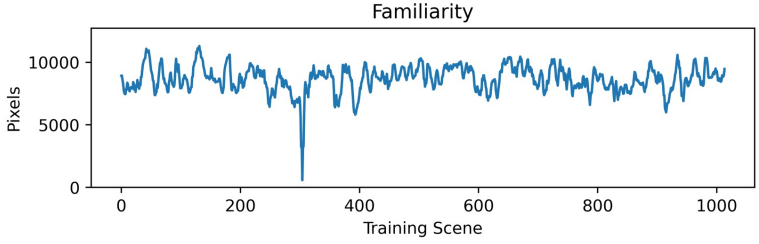
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

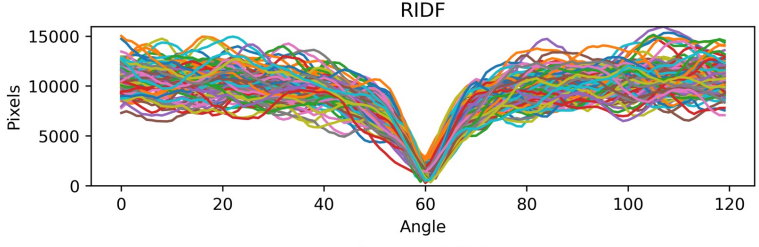
Navigation stats: RMSD error: 36.34; RMSD/dist: 0.091; TD: 6560; p90: 20; p50: 10; complete: 0

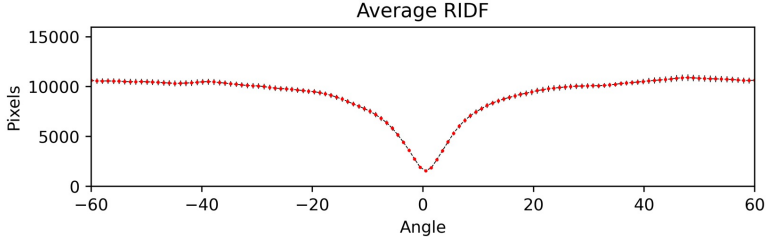
100%







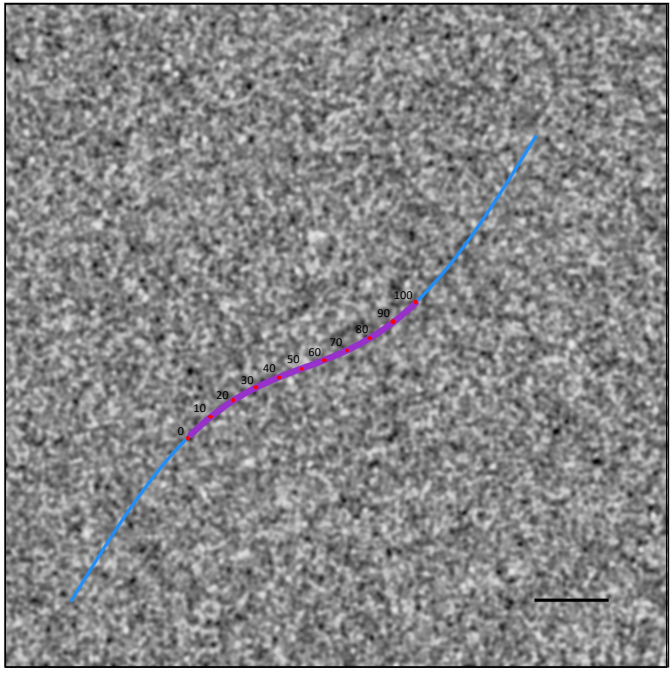


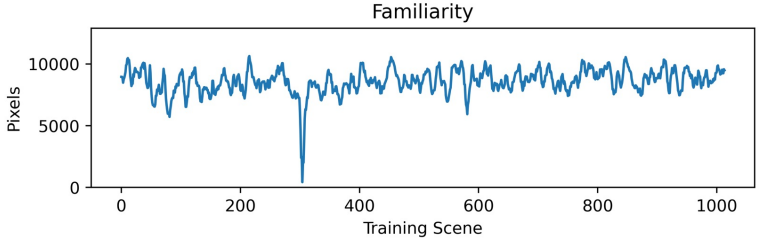


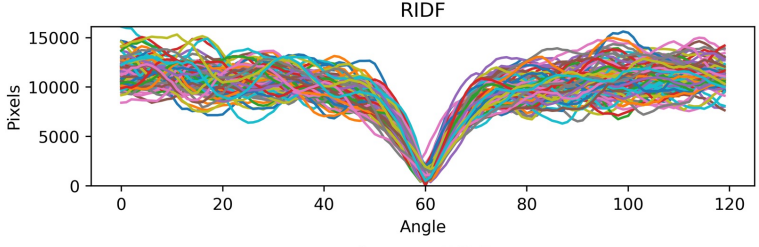
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

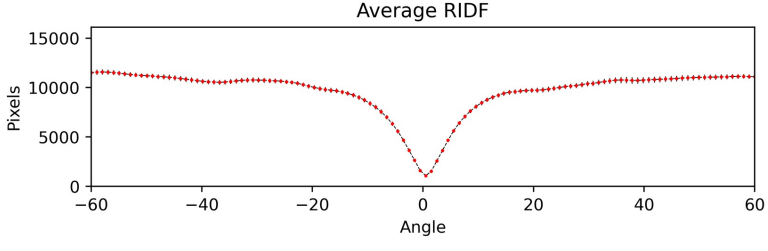
Navigation stats: RMSD error: 79.43; RMSD/dist: 0.199; TD: 6793; p90: 22; p50: 10; complete: 0

100%





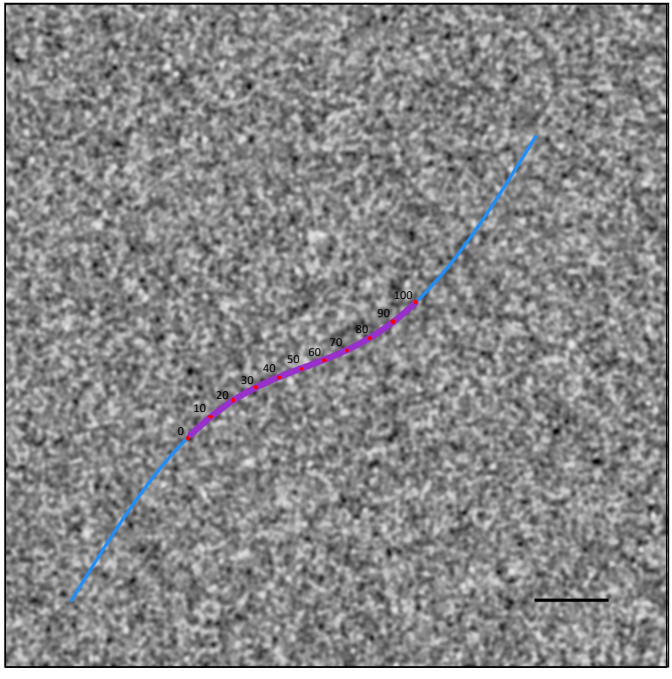


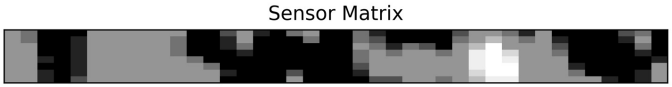


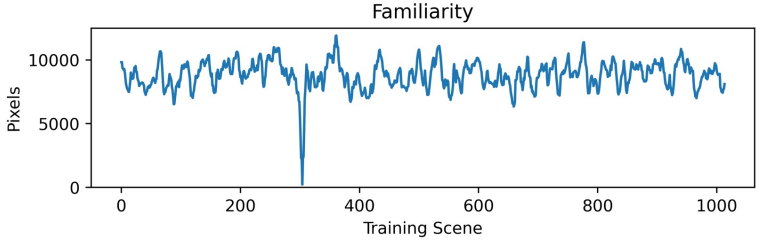
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

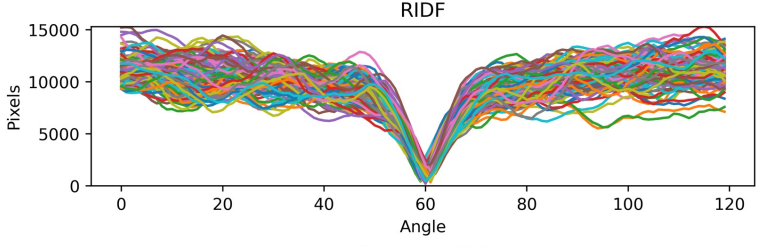
Navigation stats: RMSD error: 34.97; RMSD/dist: 0.087; TD: 7730; p90: 18; p50: 8; complete: 0

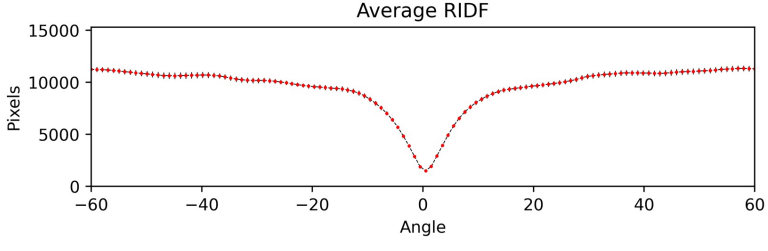
100%







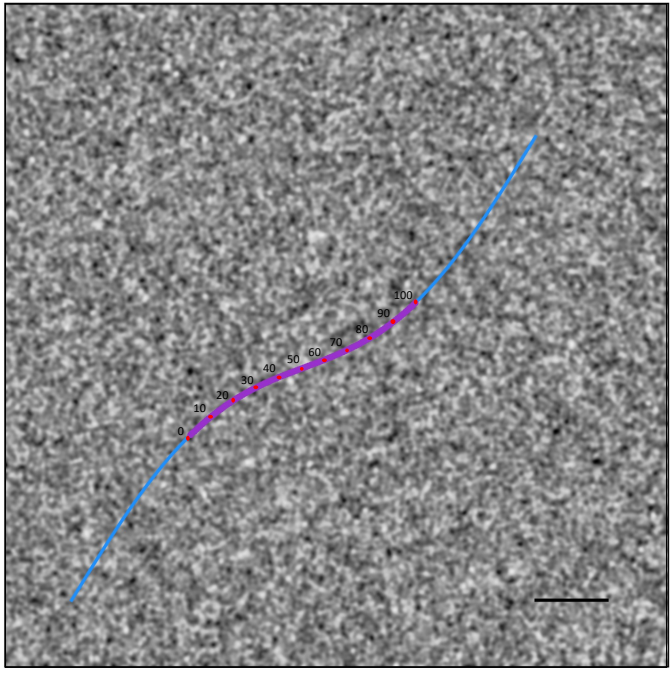


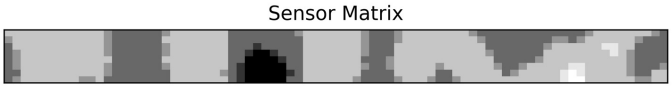


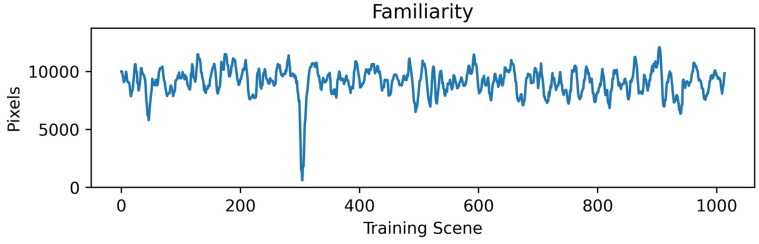
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

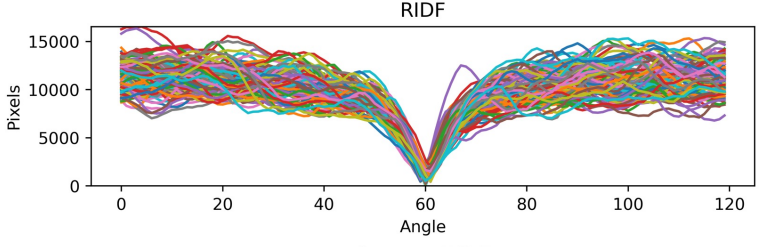
Navigation stats: RMSD error: 61.03; RMSD/dist: 0.153; TD: 7292; p90: 18; p50: 8; complete: 0

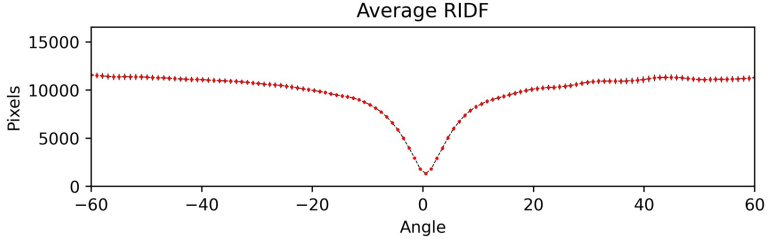
100%





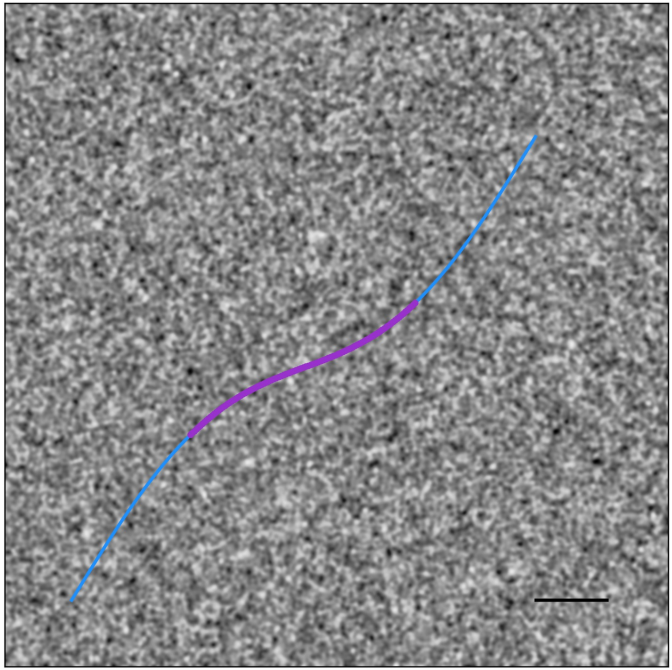


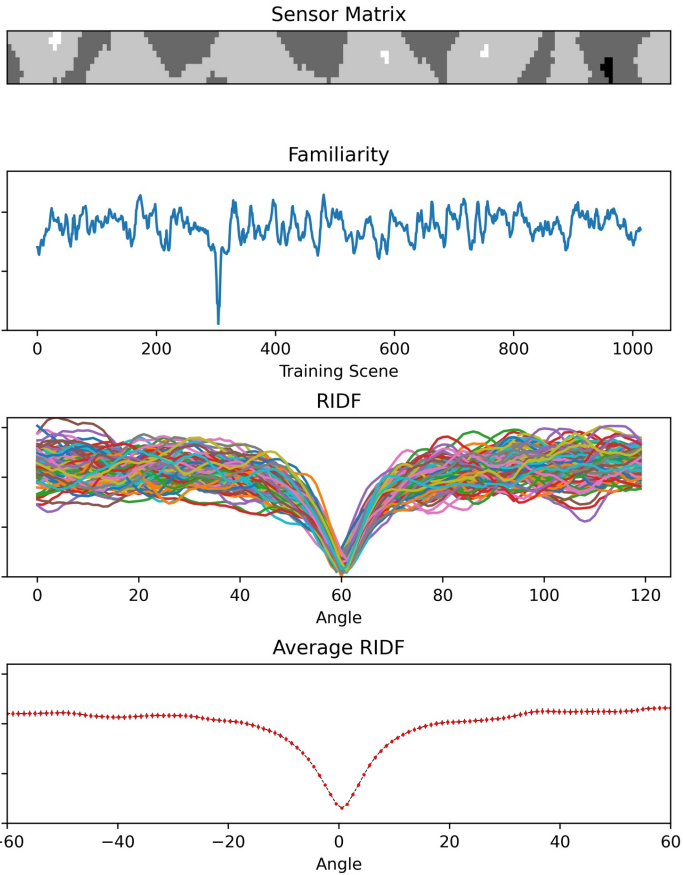




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

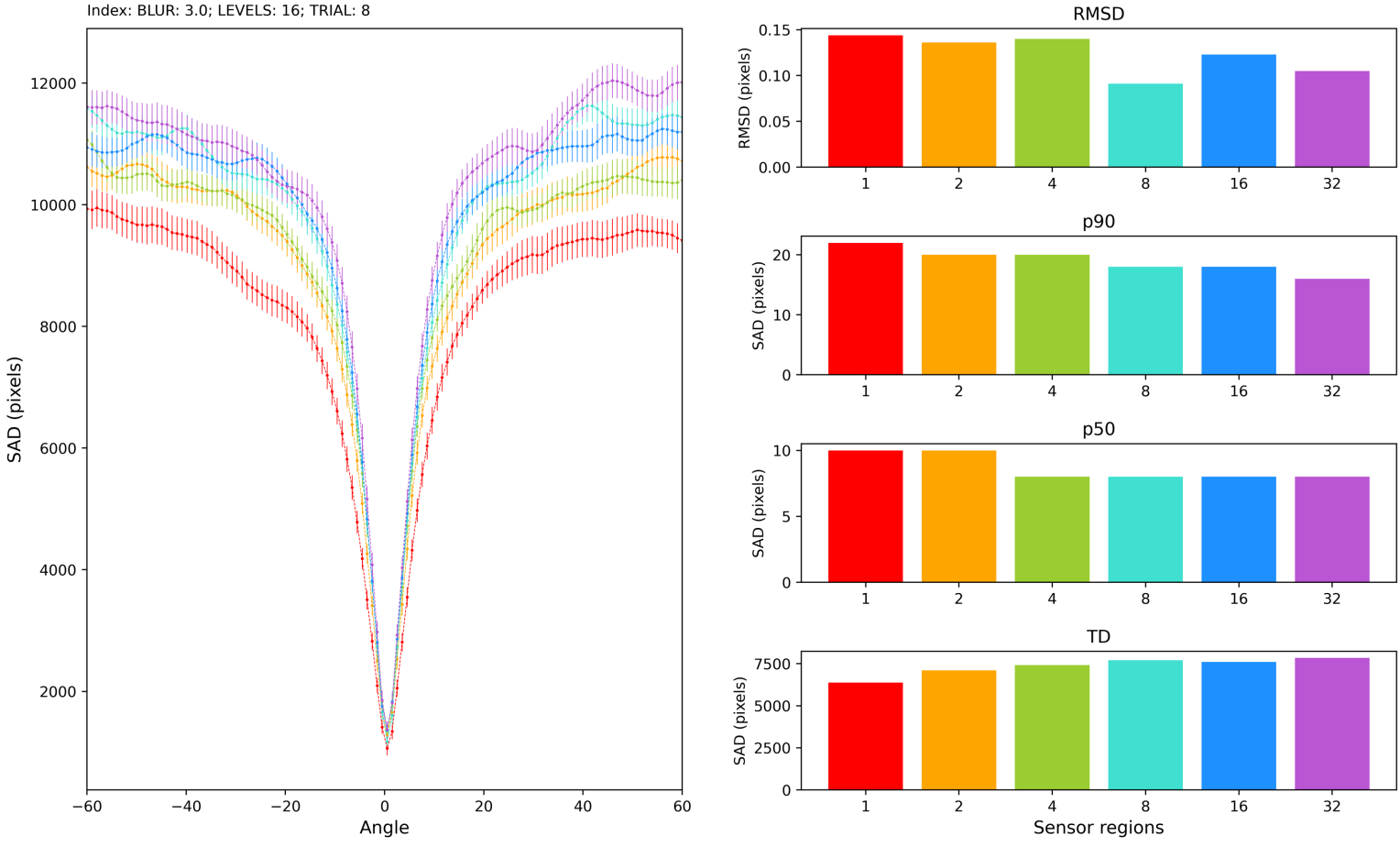
Navigation stats: RMSD error: 44.07; RMSD/dist: 0.110; TD: 7747; p90: 18; p50: 8; complete: 0



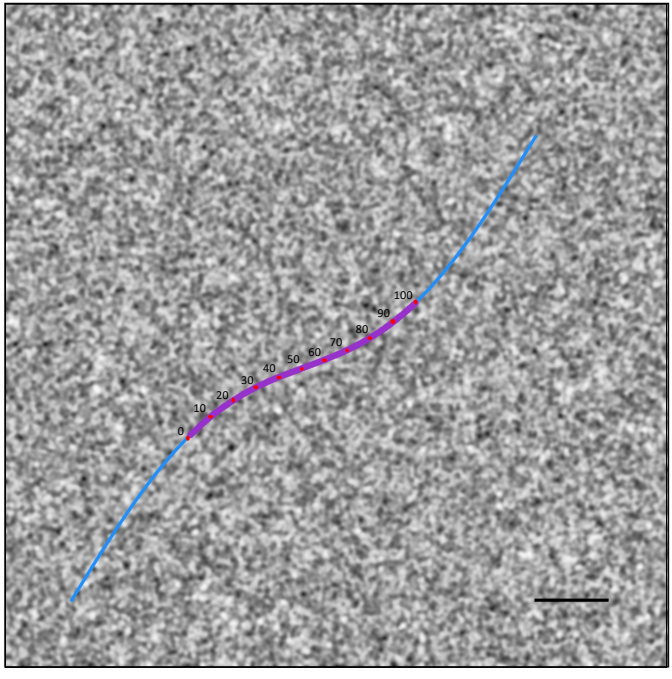


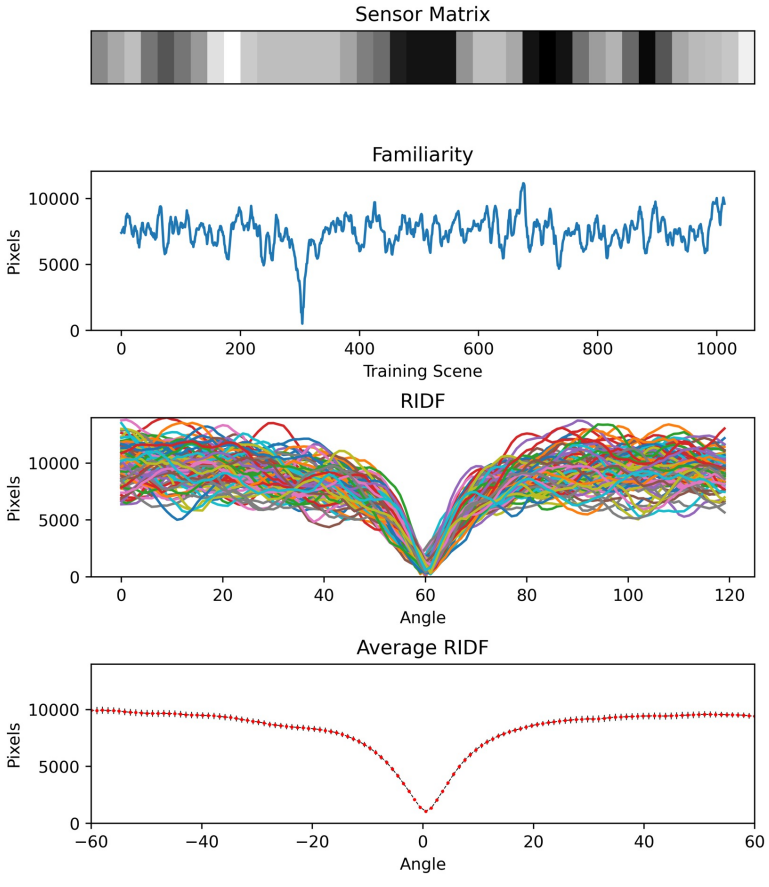
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 57.99; RMSD/dist: 0.145; TD: 7381; p90: 18; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 16; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

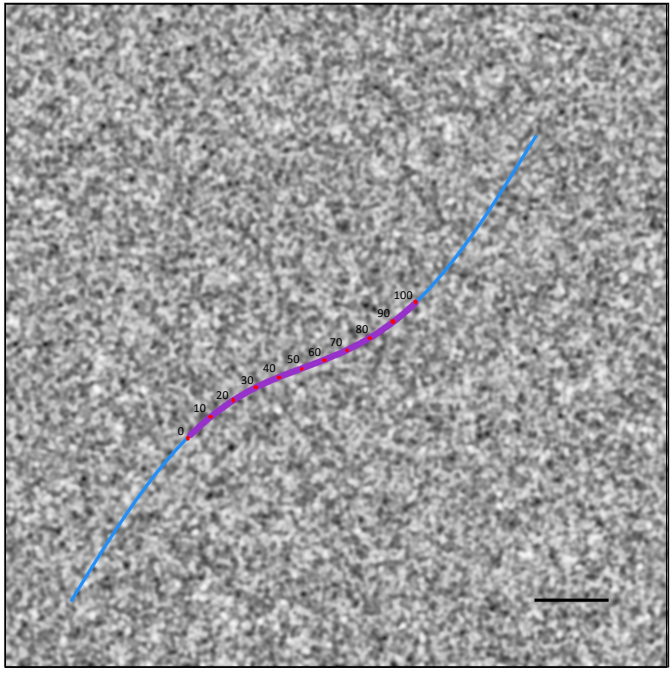


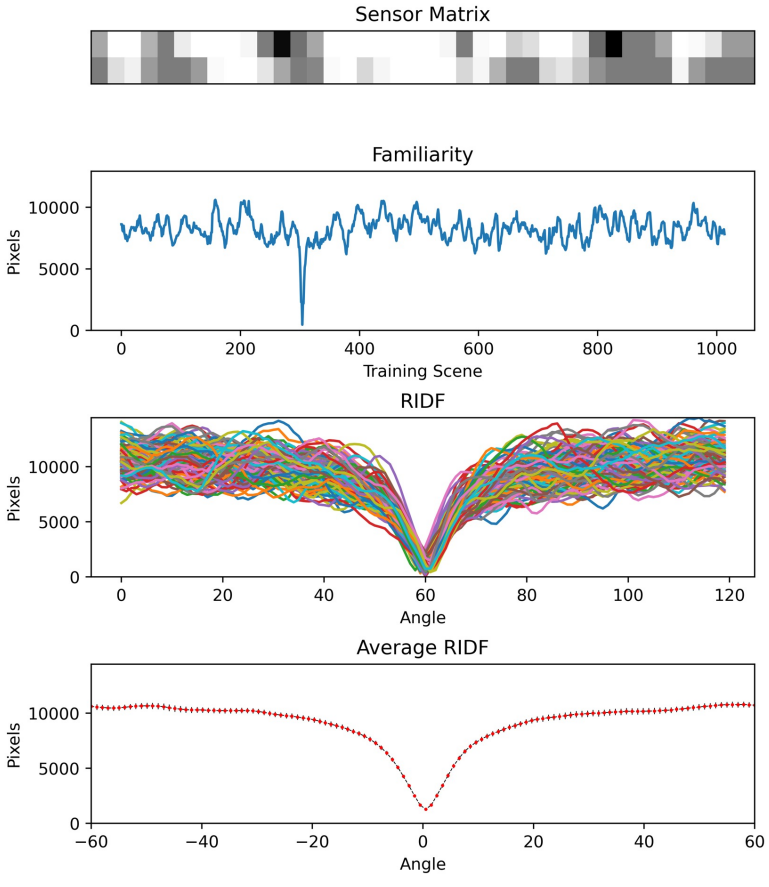


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 57.69; RMSD/dist: 0.144; TD: 6379; p90: 22; p50: 10; complete: 0

100%

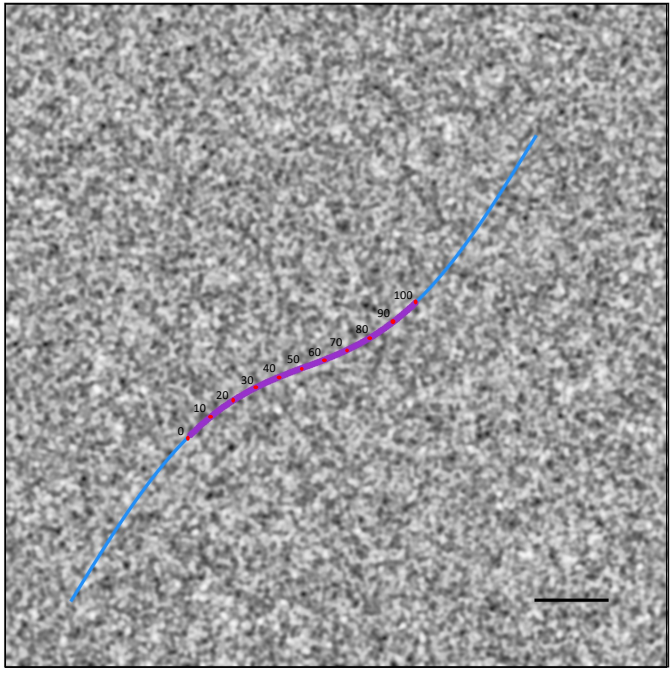


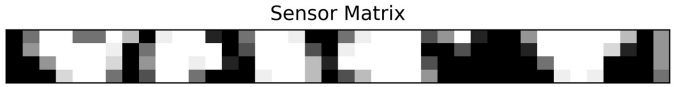


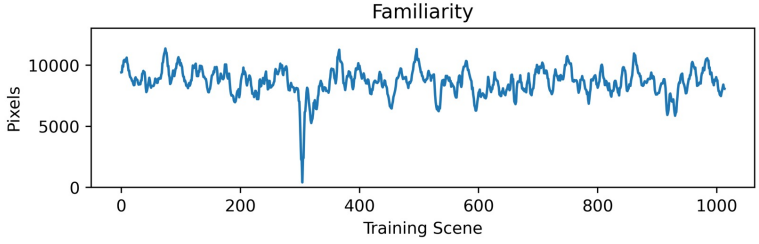
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

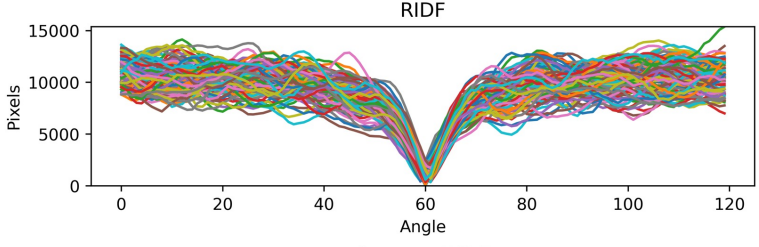
Navigation stats: RMSD error: 54.29; RMSD/dist: 0.136; TD: 7109; p90: 20; p50: 10; complete: 0

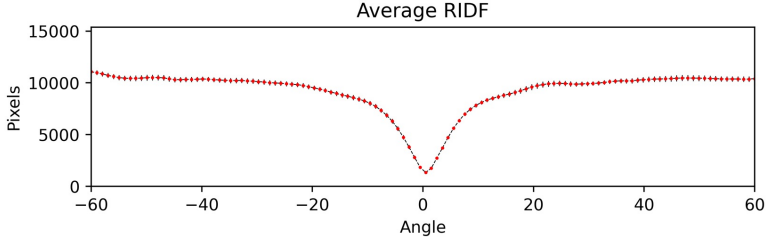
100%







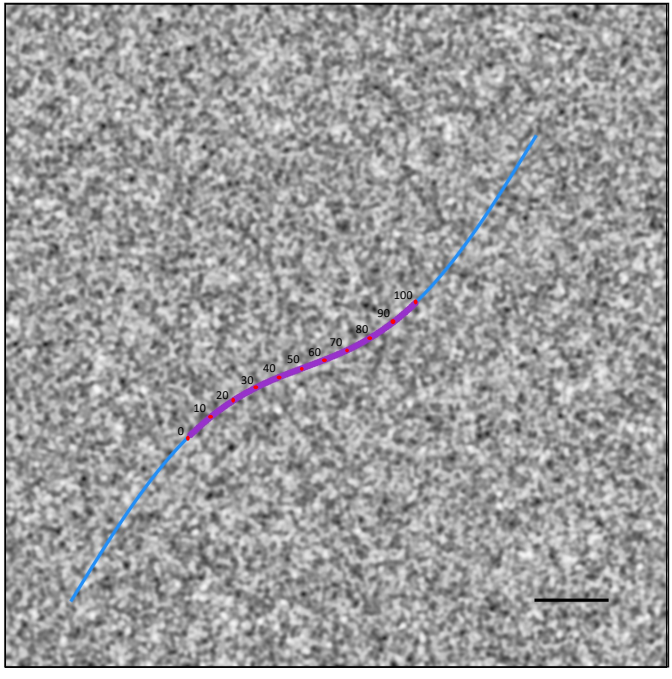


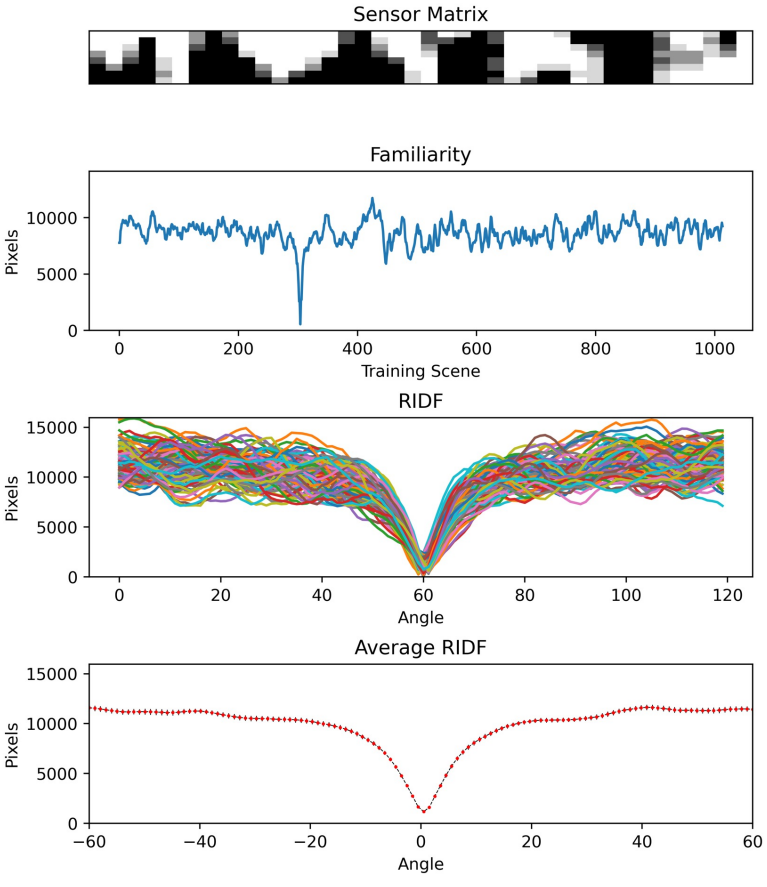


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 55.85; RMSD/dist: 0.140; TD: 7413; p90: 20; p50: 8; complete: 0

100%

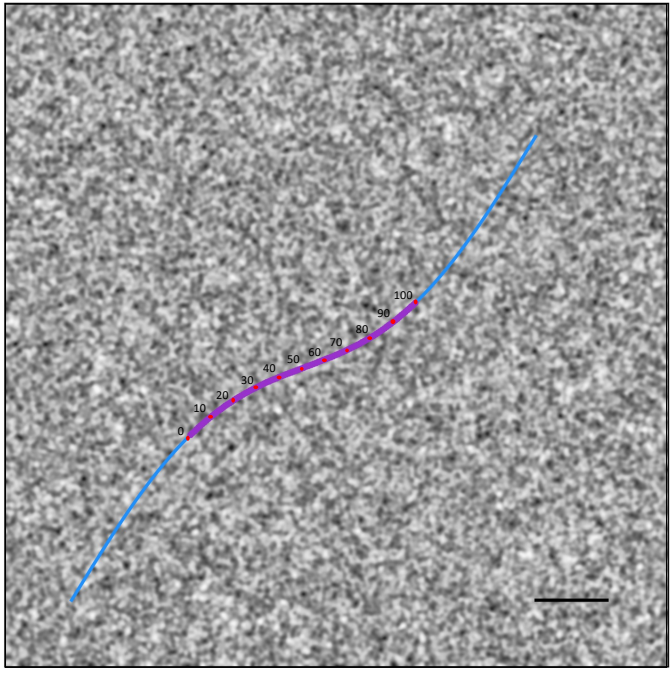


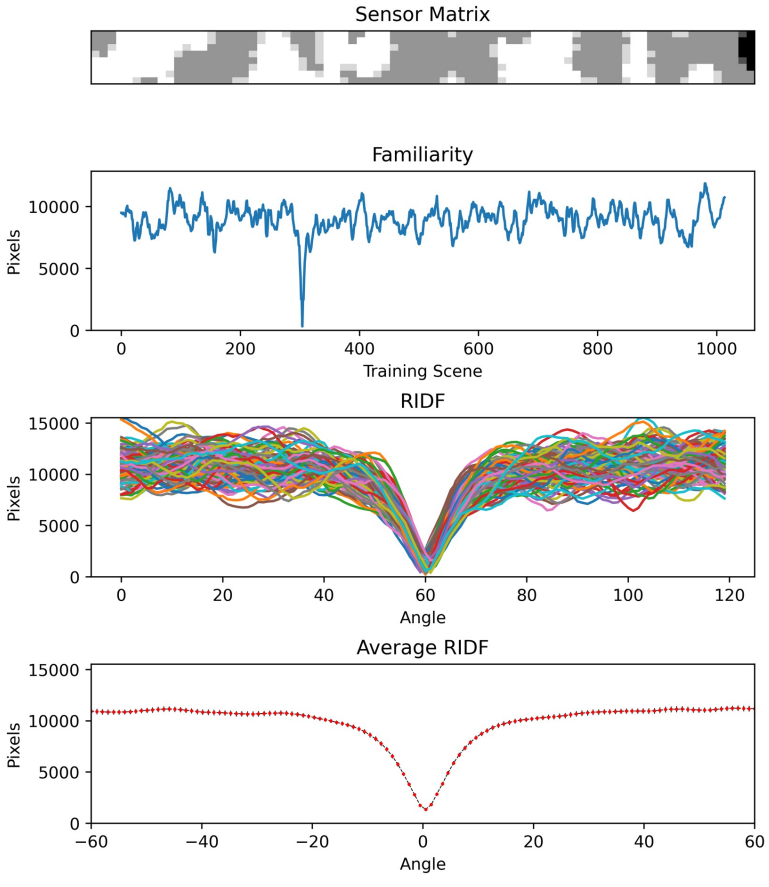


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 36.24; RMSD/dist: 0.091; TD: 7706; p90: 18; p50: 8; complete: 0

100%

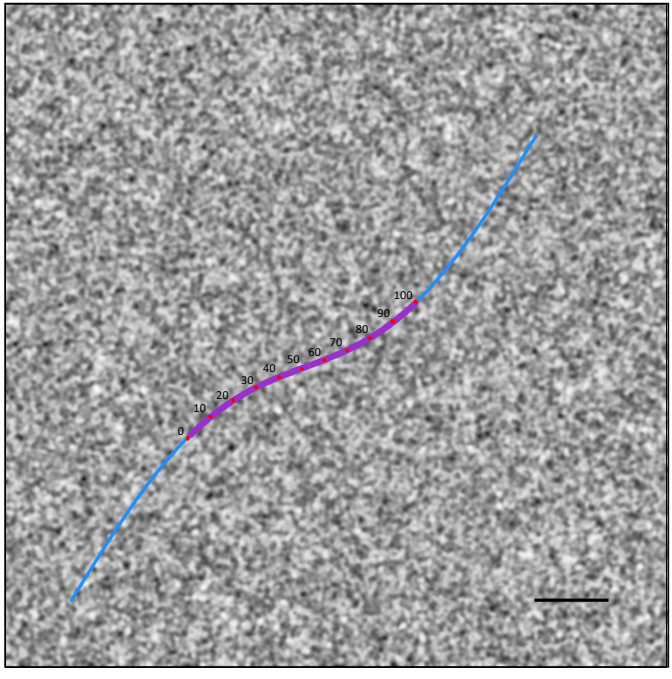


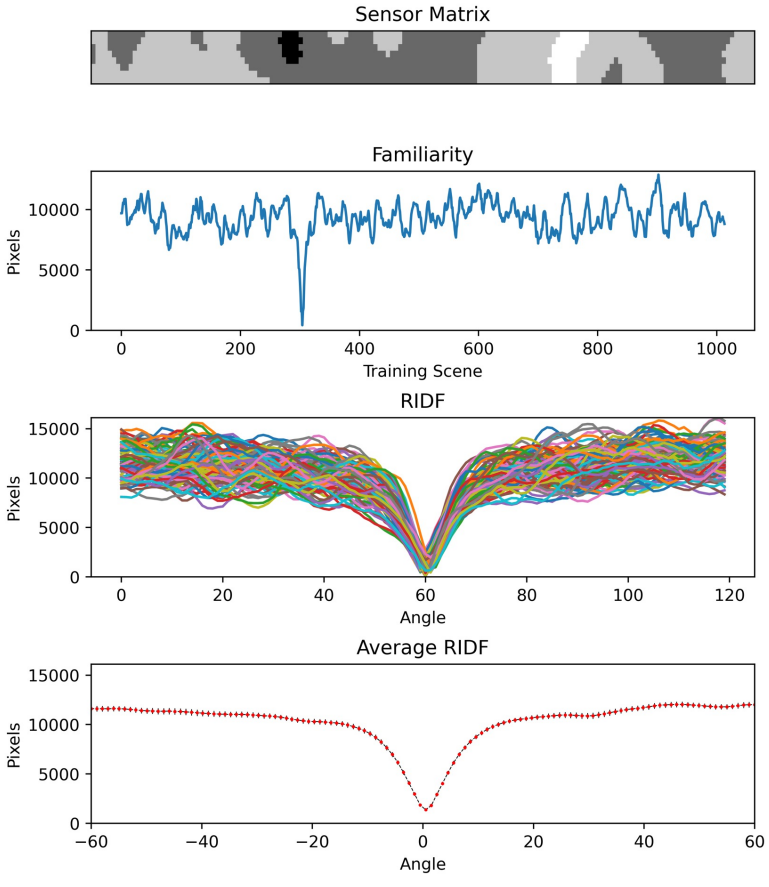


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 49.36; RMSD/dist: 0.123; TD: 7612; p90: 18; p50: 8; complete: 0

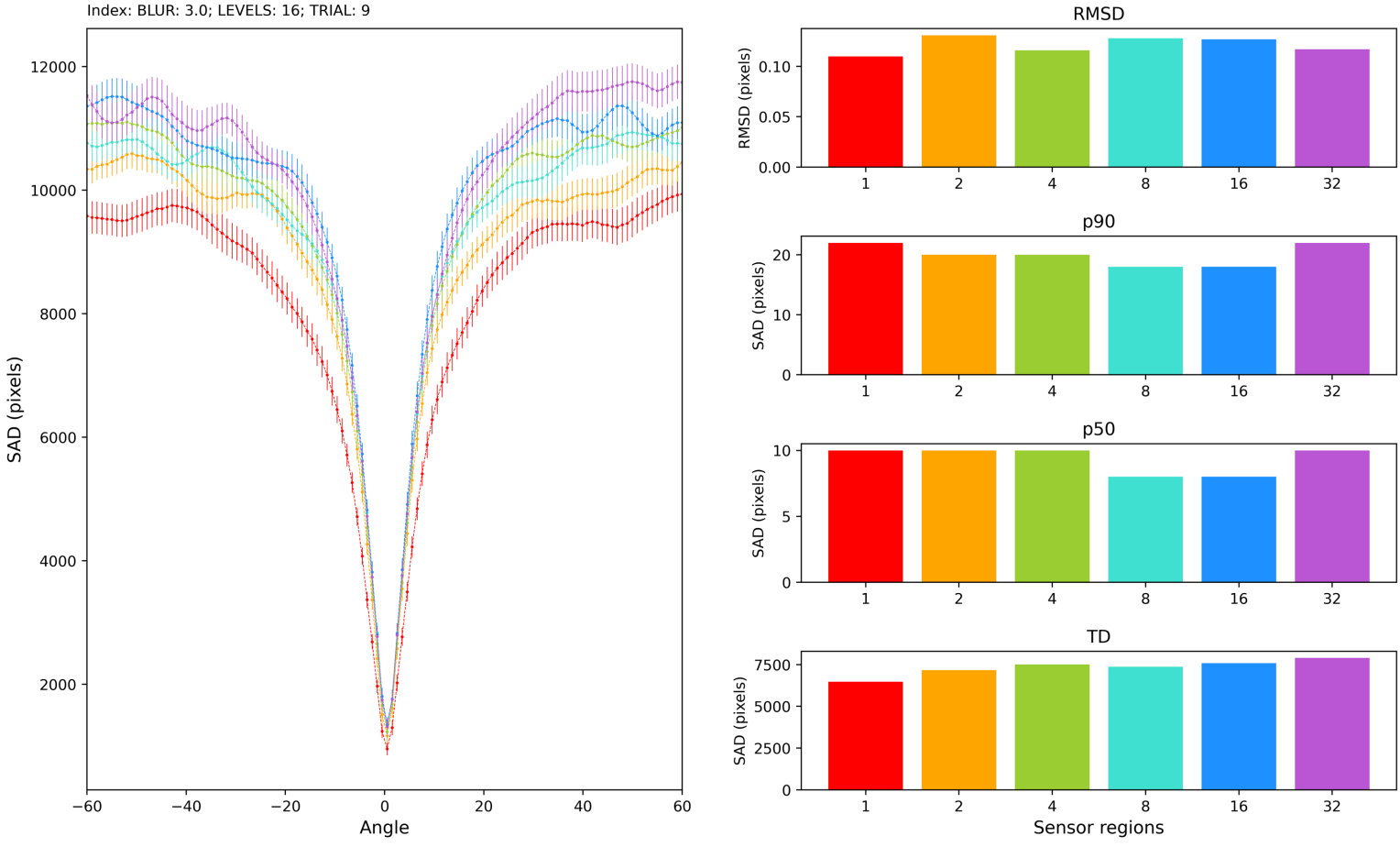
100%



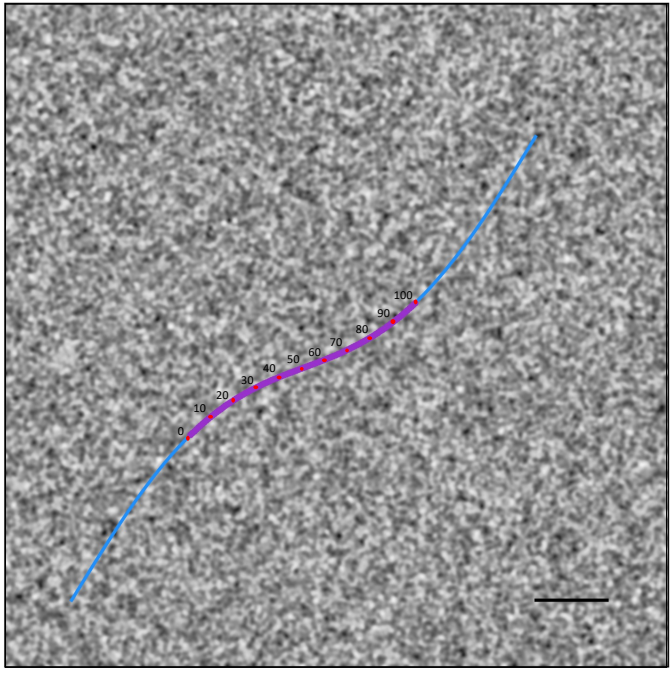


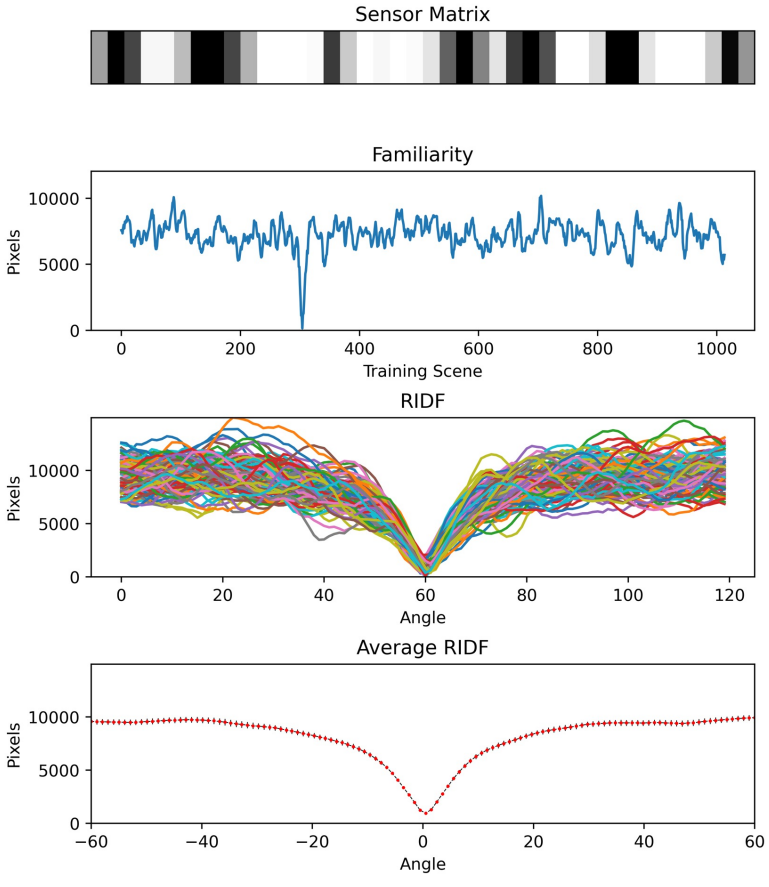
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 42.00; RMSD/dist: 0.105; TD: 7839; p90: 16; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 16; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

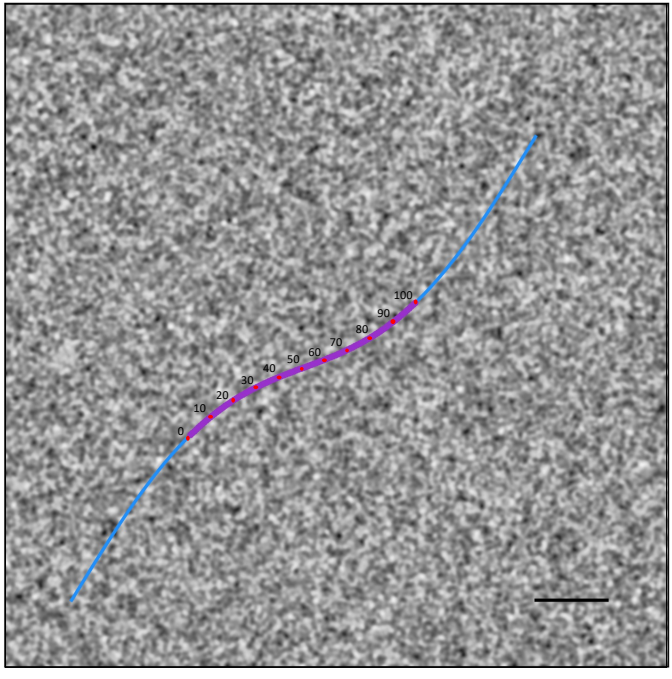


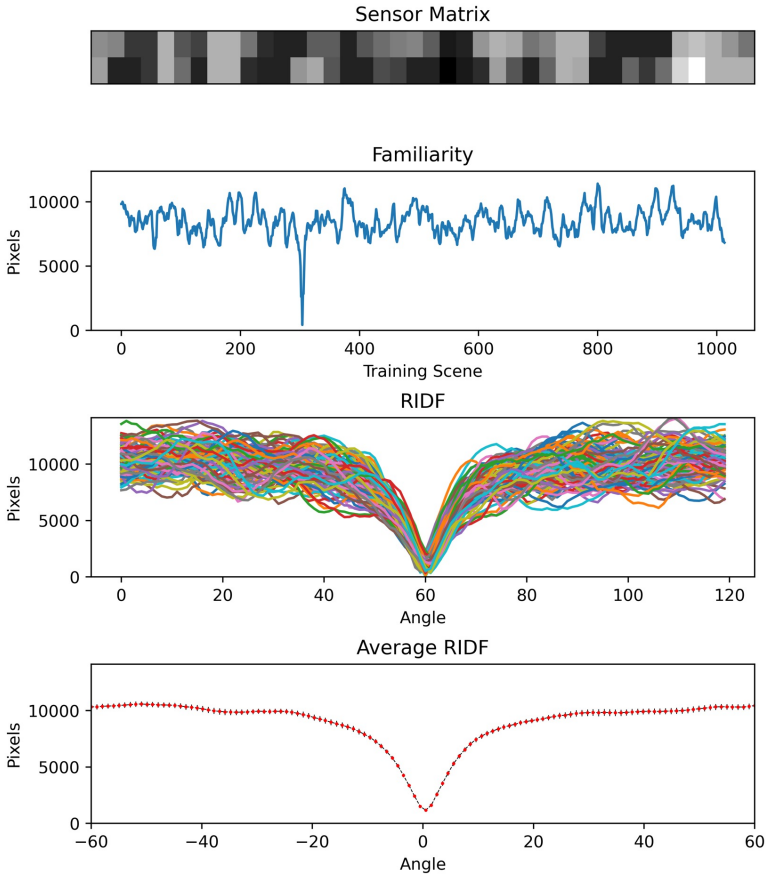


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 44.12; RMSD/dist: 0.110; TD: 6474; p90: 22; p50: 10; complete: 0

100%

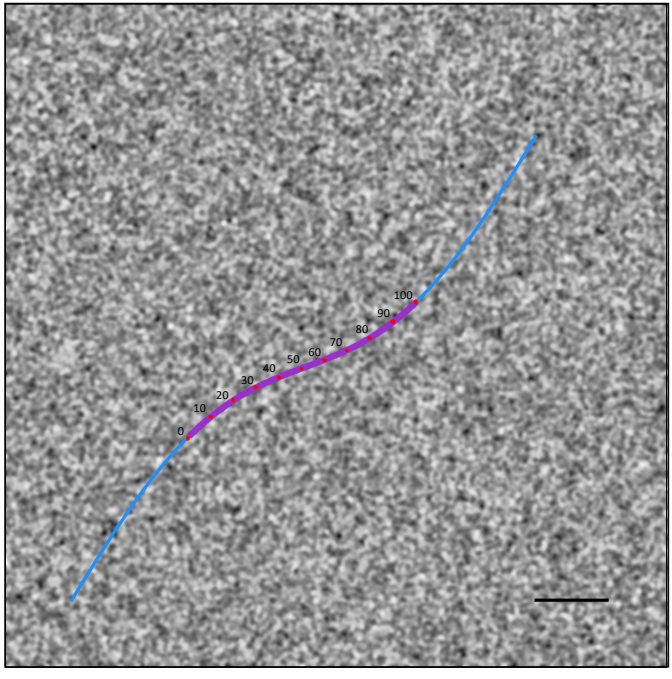


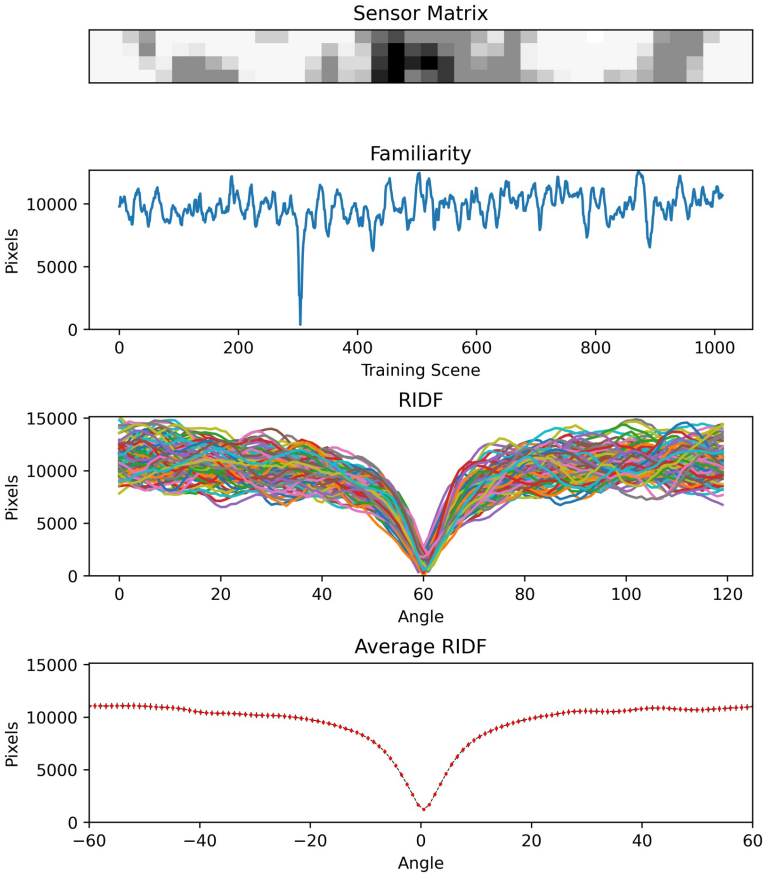


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 52.40; RMSD/dist: 0.131; TD: 7172; p90: 20; p50: 10; complete: 0

100%

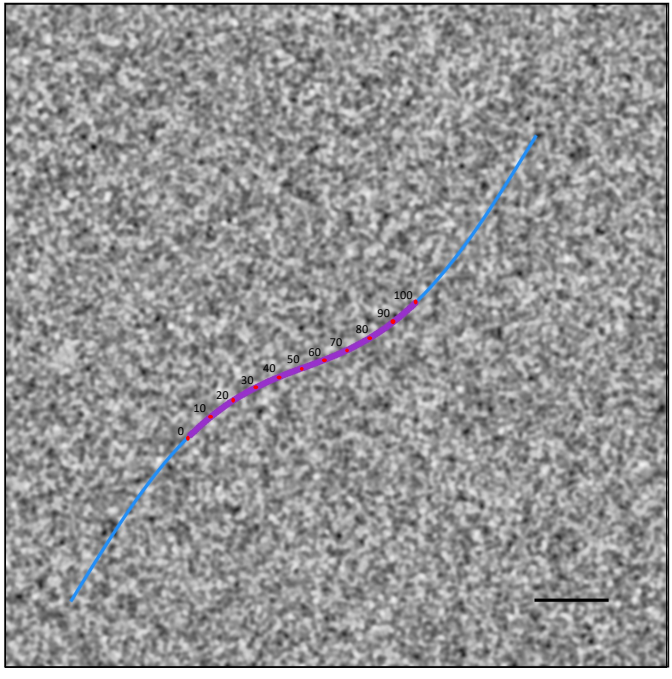


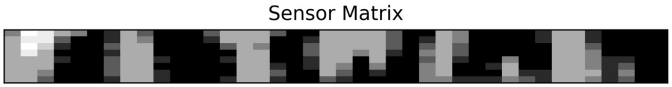


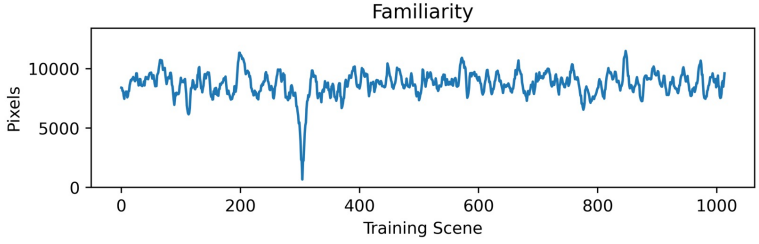
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

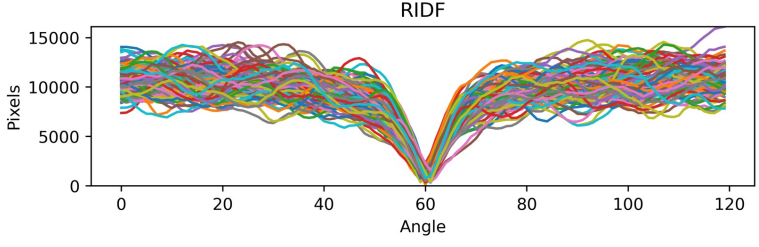
Navigation stats: RMSD error: 46.39; RMSD/dist: 0.116; TD: 7506; p90: 20; p50: 10; complete: 0

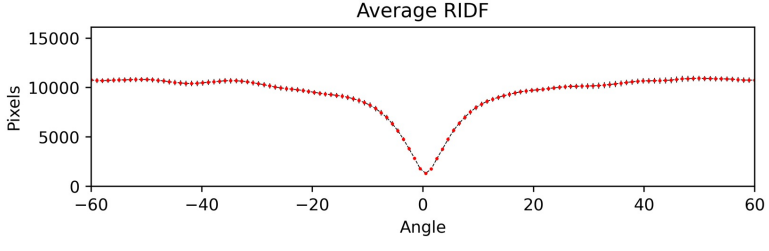
100%







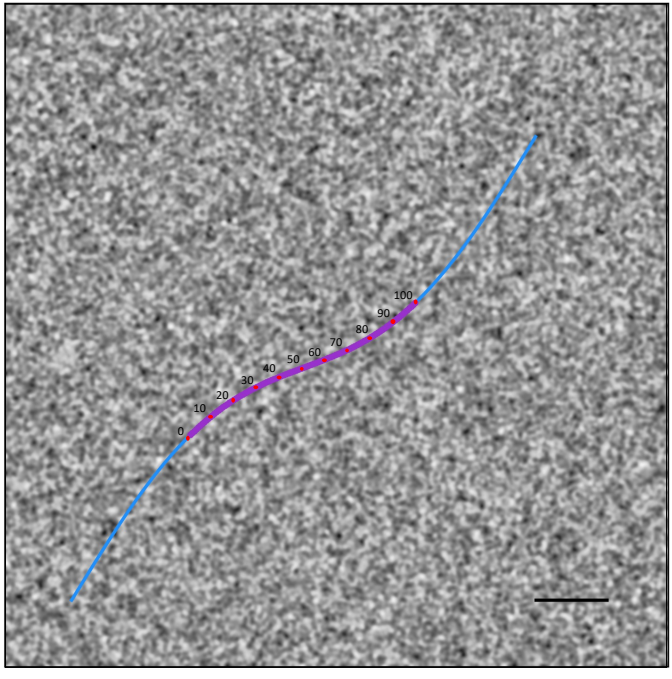


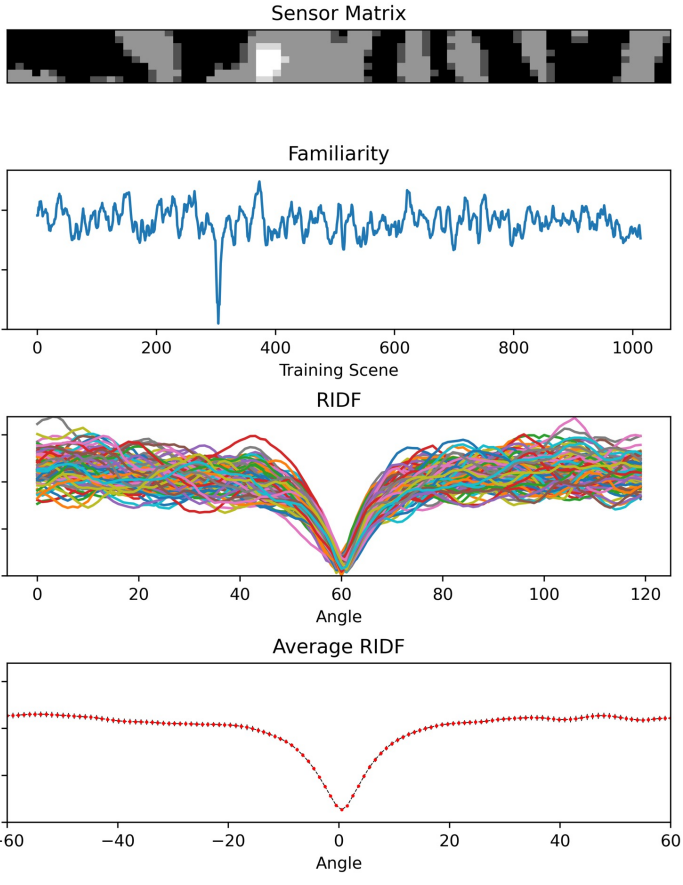


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 51.09; RMSD/dist: 0.128; TD: 7375; p90: 18; p50: 8; complete: 0

100%

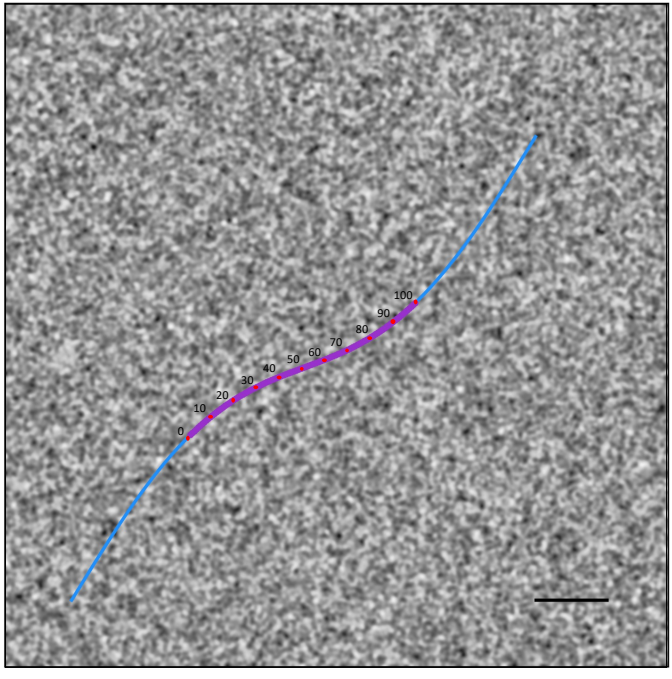


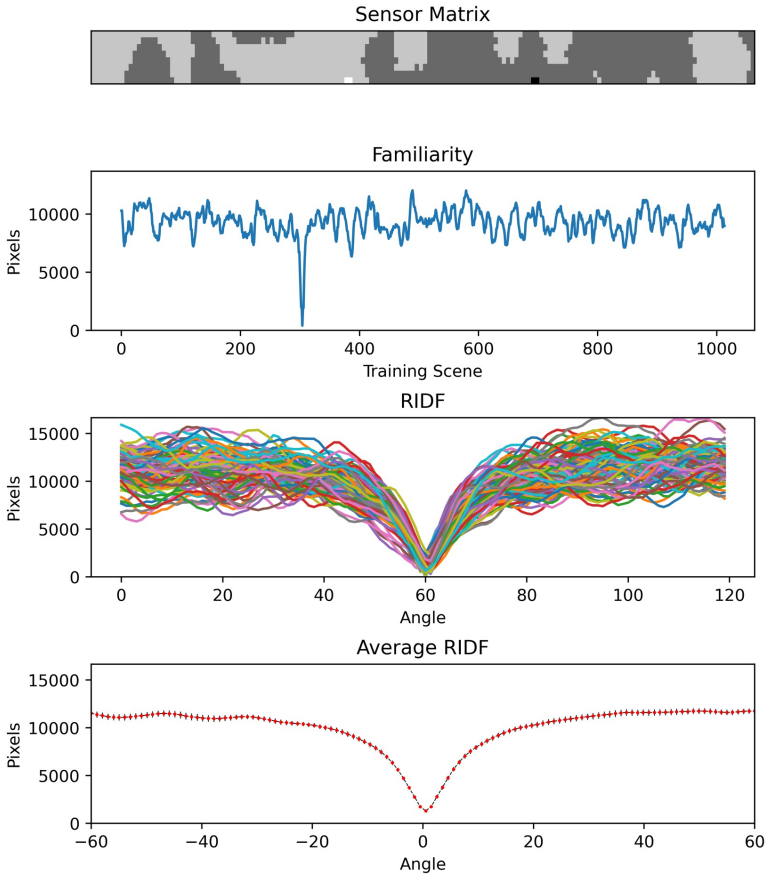


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 50.77; RMSD/dist: 0.127; TD: 7591; p90: 18; p50: 8; complete: 0

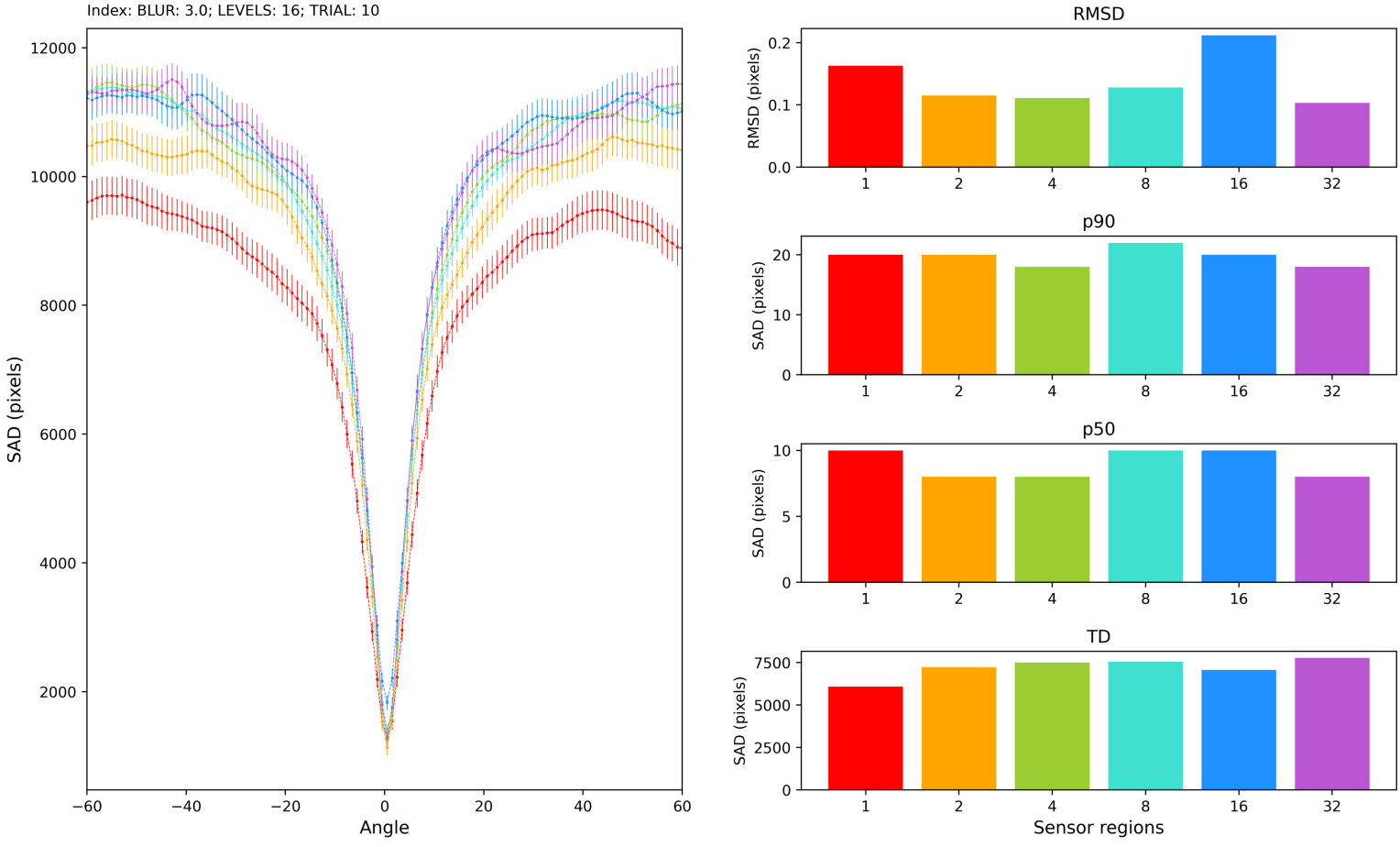
100%



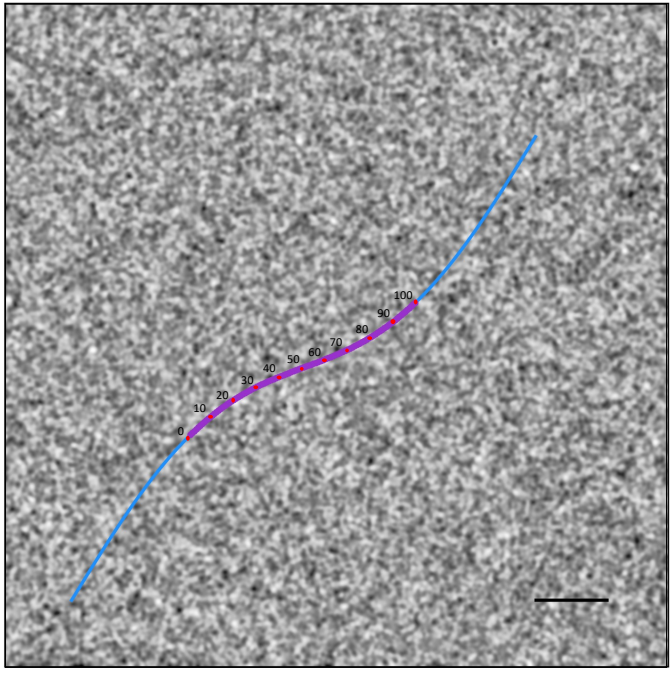


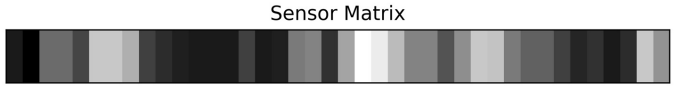
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

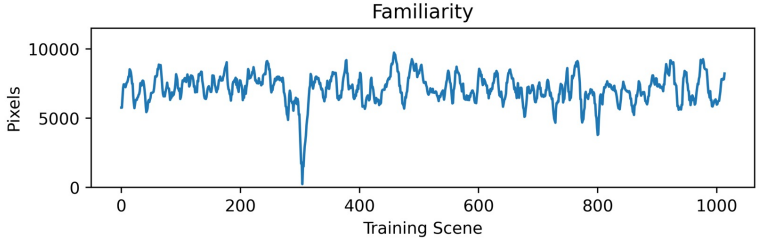
Navigation stats: RMSD error: 46.83; RMSD/dist: 0.117; TD: 7896; p90: 22; p50: 10; complete: 0

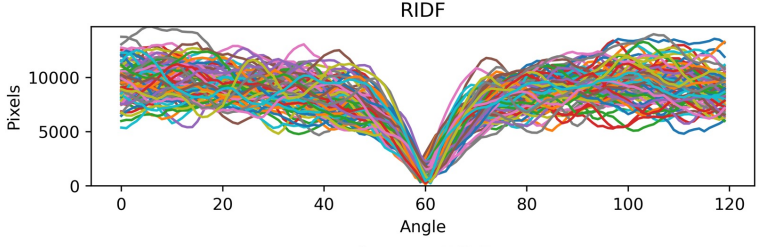

Index: BLUR: 3.0; LEVELS: 16; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

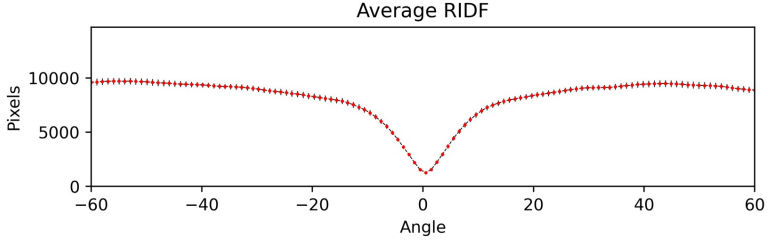
100%







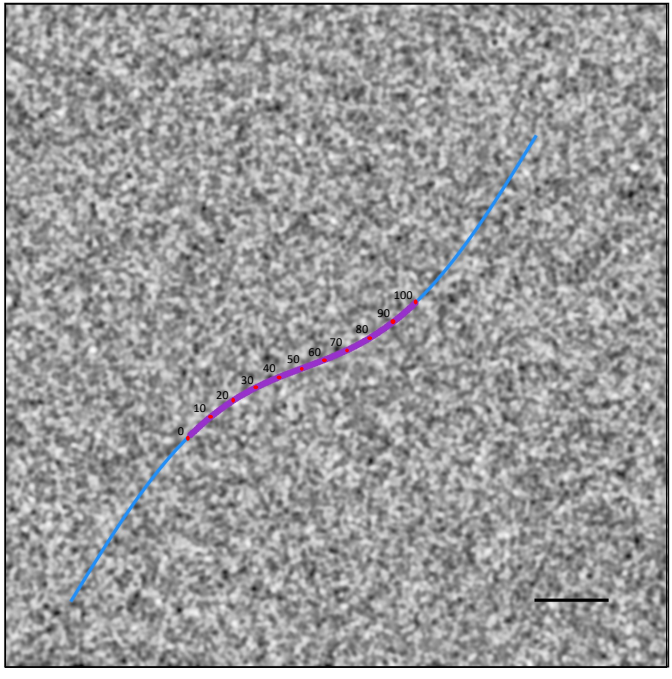


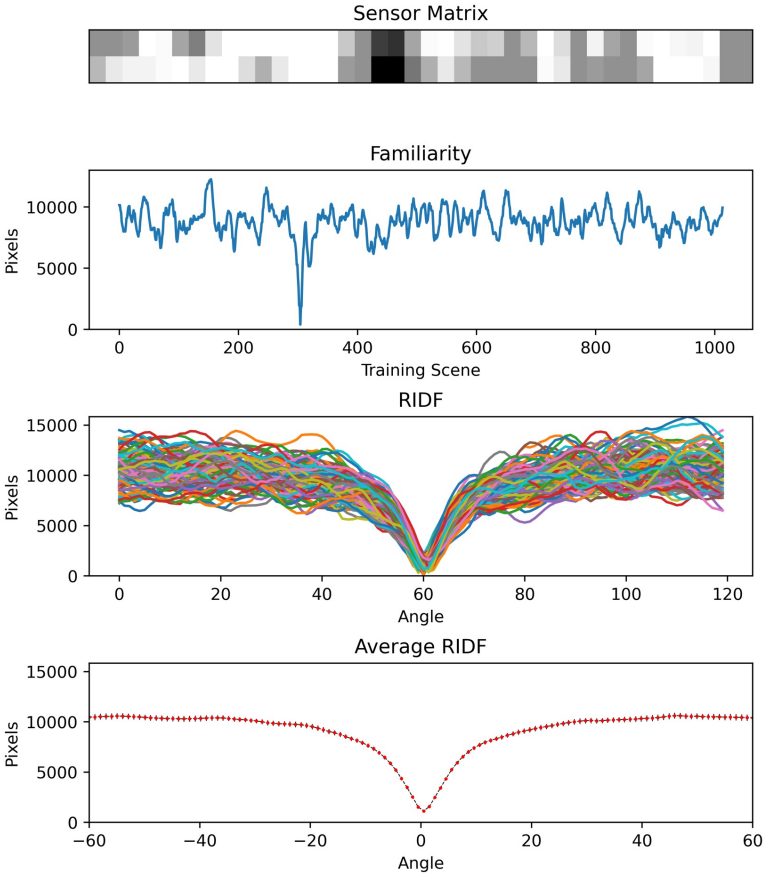


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 65.05; RMSD/dist: 0.163; TD: 6084; p90: 20; p50: 10; complete: 0

100%

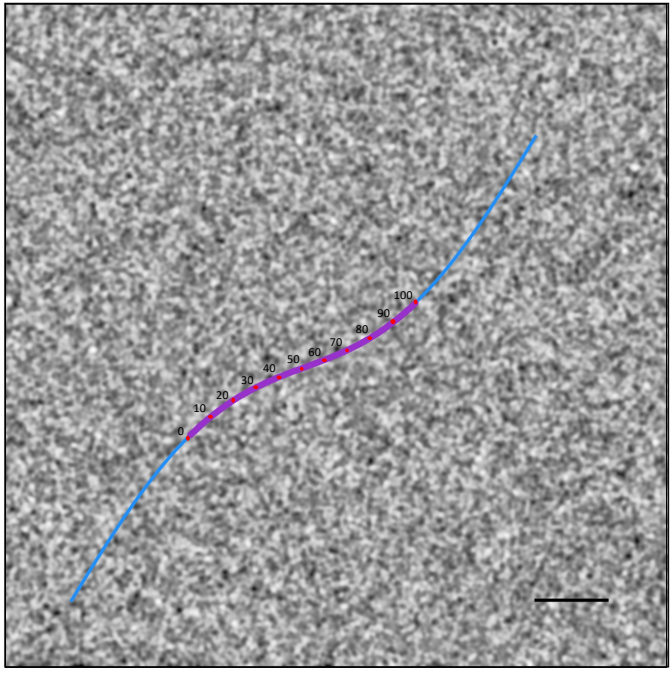


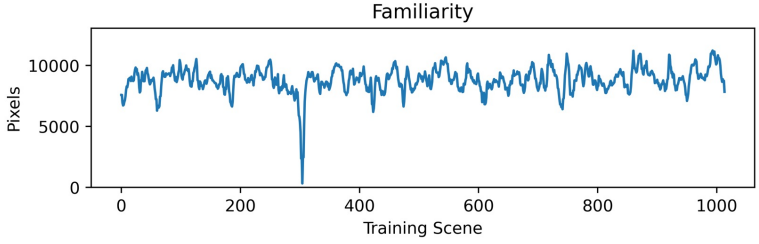


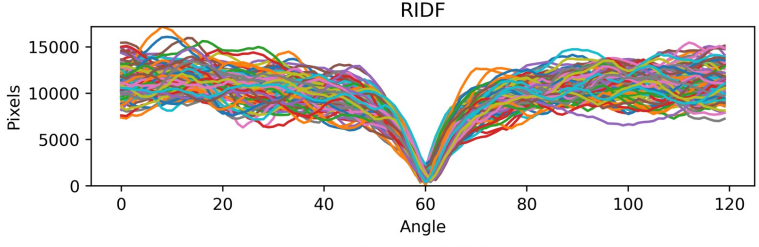
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

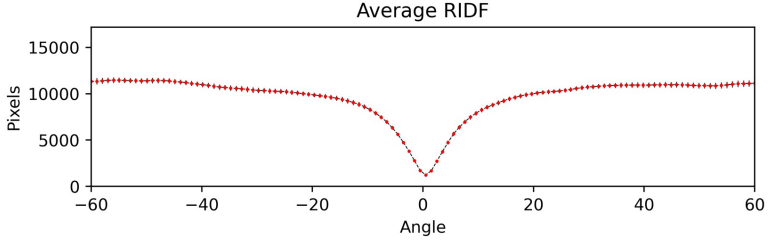
Navigation stats: RMSD error: 46.13; RMSD/dist: 0.115; TD: 7229; p90: 20; p50: 8; complete: 0

100%





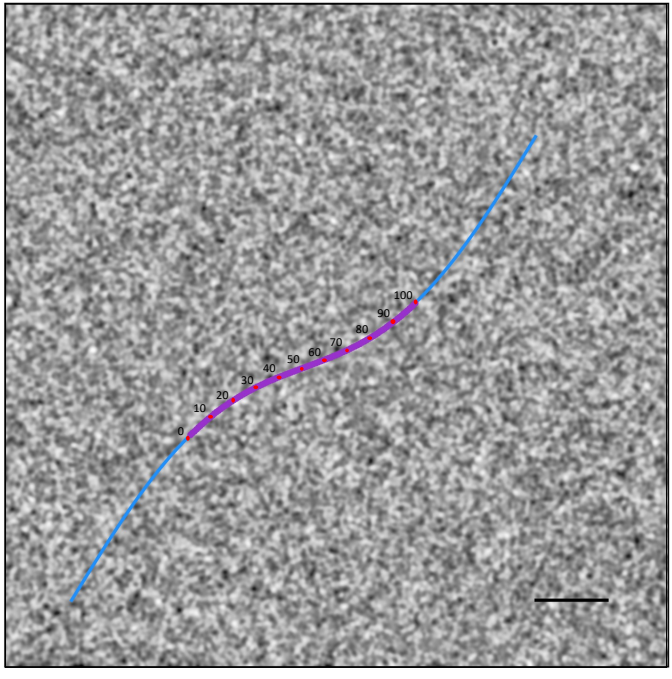


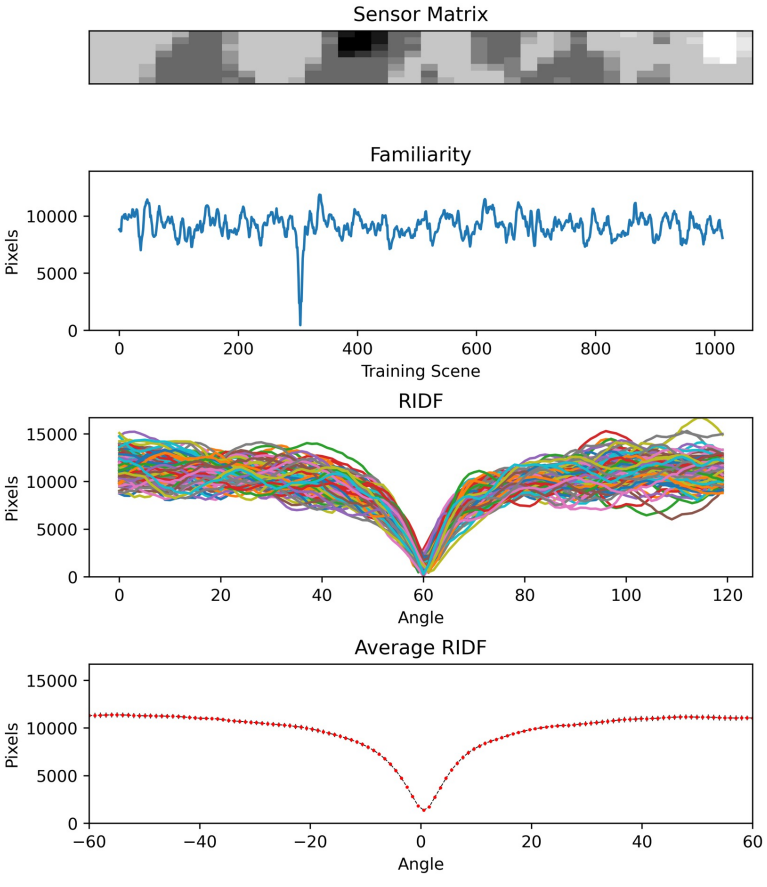


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 44.51; RMSD/dist: 0.111; TD: 7497; p90: 18; p50: 8; complete: 0

100%

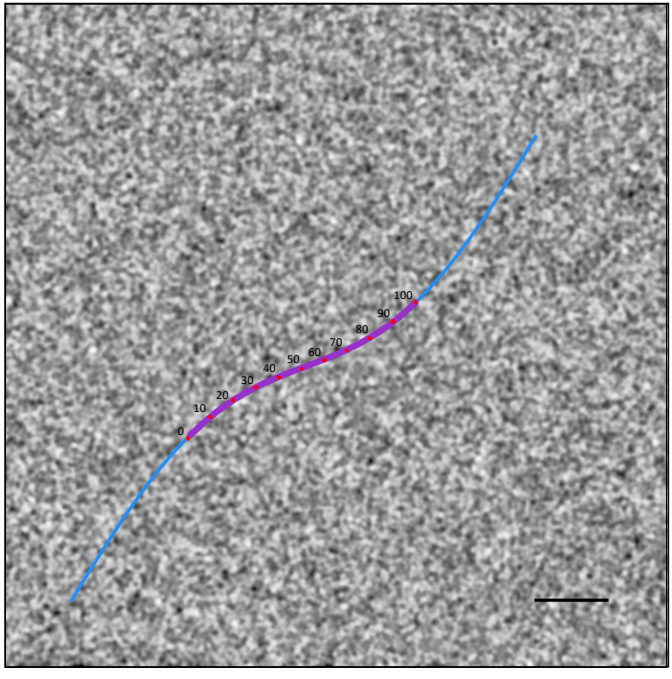


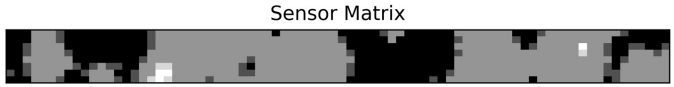


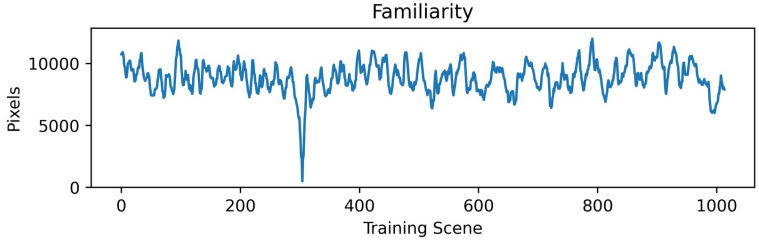
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

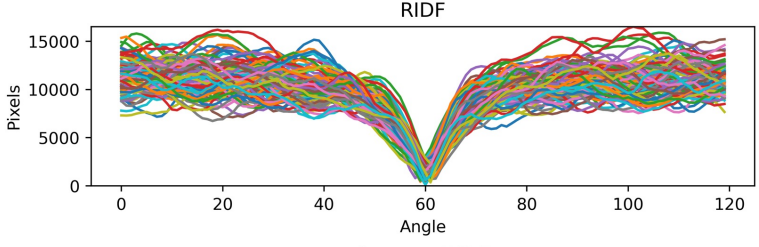
Navigation stats: RMSD error: 51.39; RMSD/dist: 0.128; TD: 7550; p90: 22; p50: 10; complete: 0

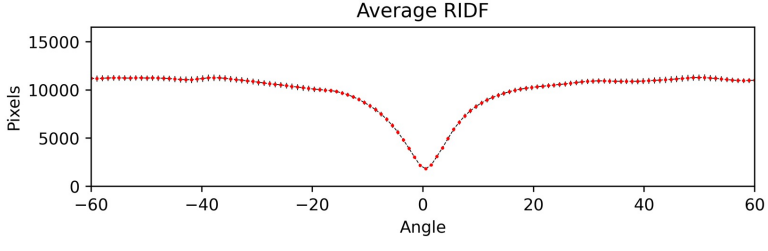
100%







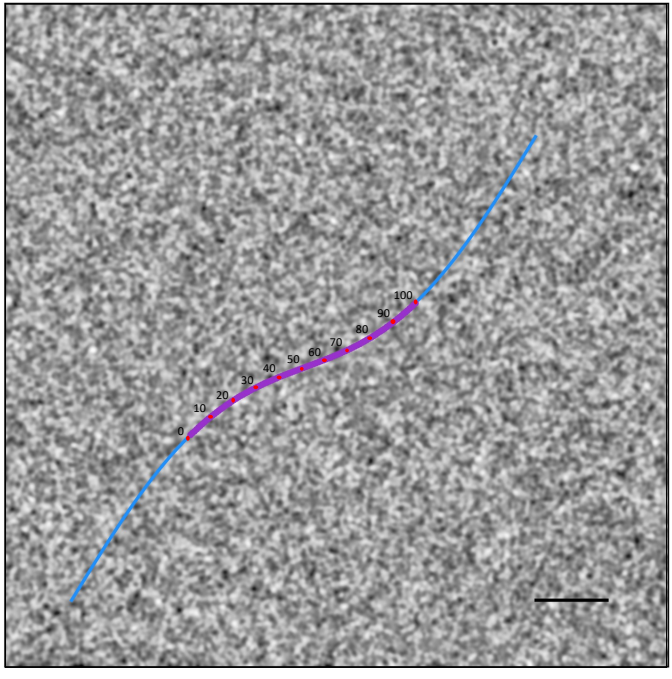


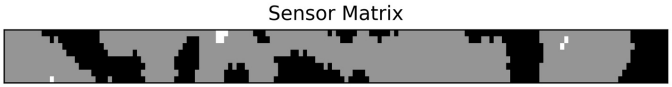


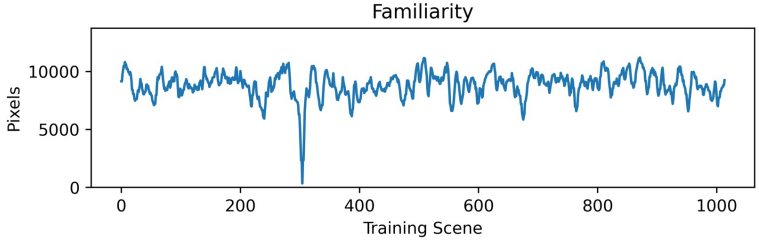
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

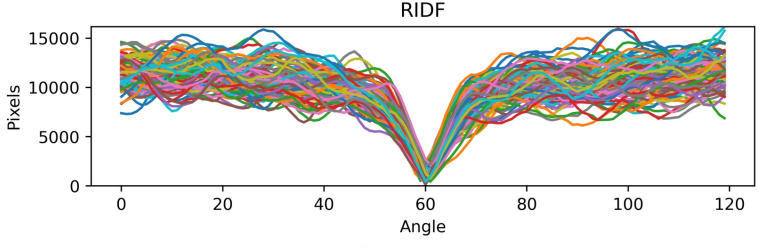
Navigation stats: RMSD error: 84.68; RMSD/dist: 0.212; TD: 7068; p90: 20; p50: 10; complete: 0

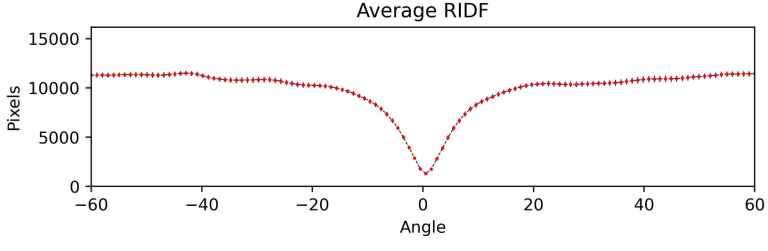
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 41.36; RMSD/dist: 0.103; TD: 7767; p90: 18; p50: 8; complete: 0