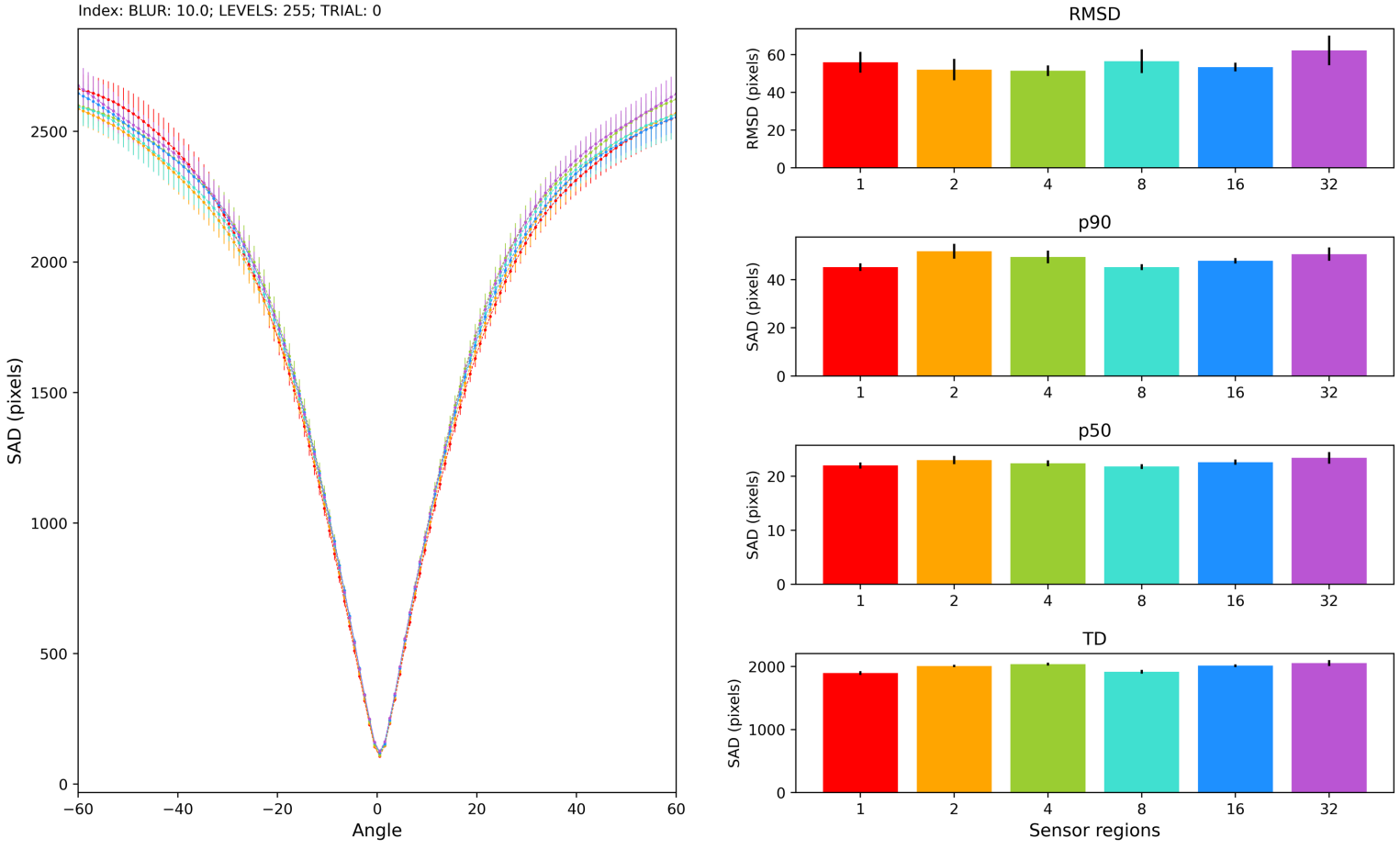
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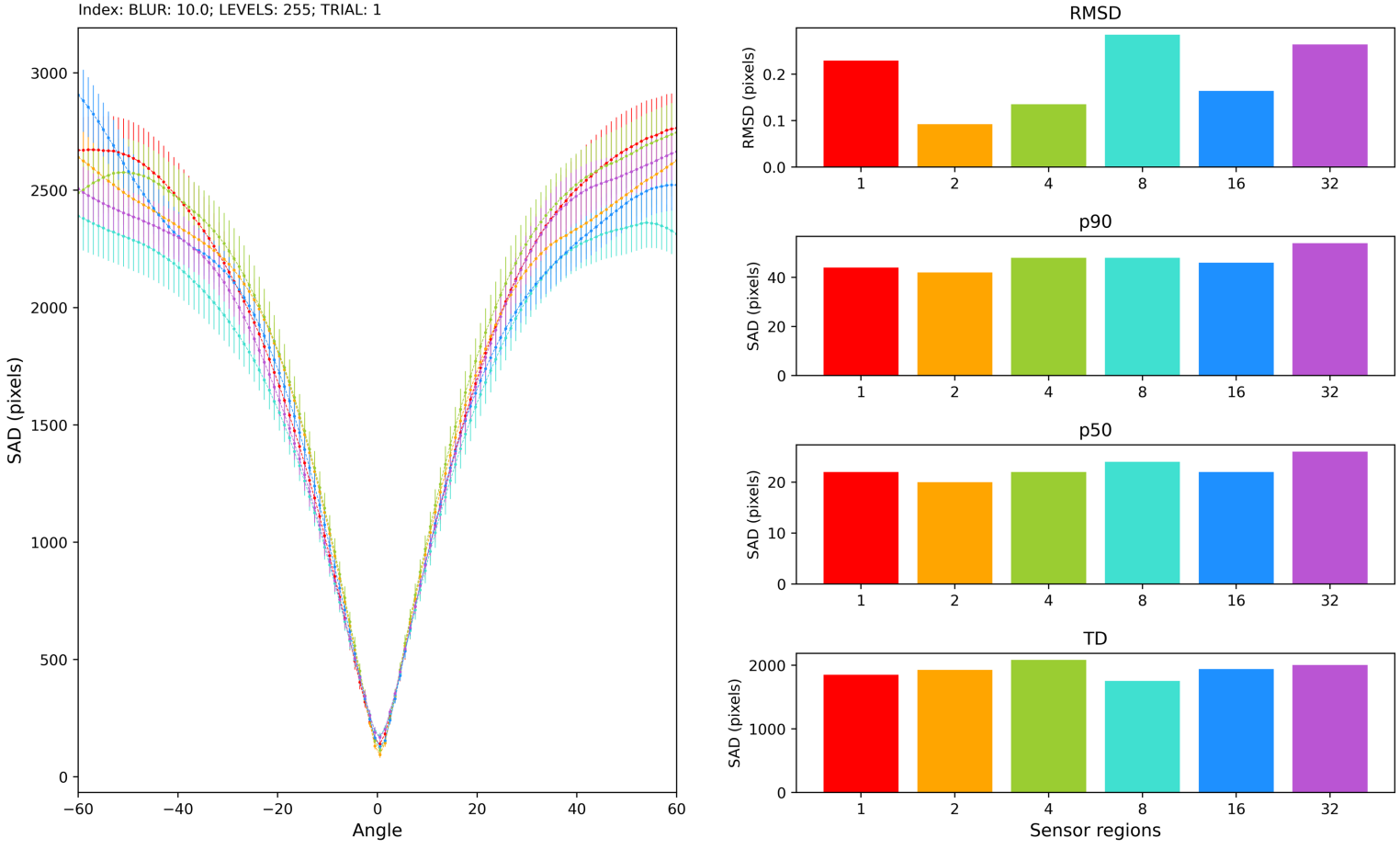
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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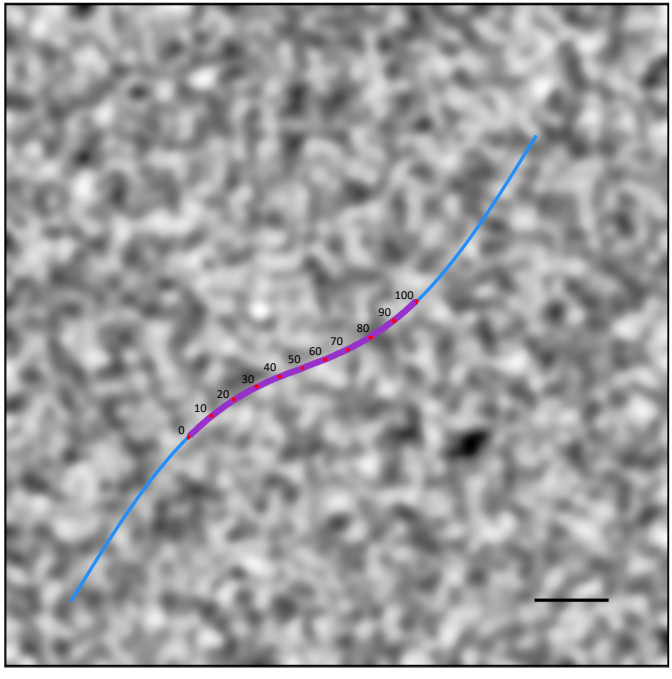
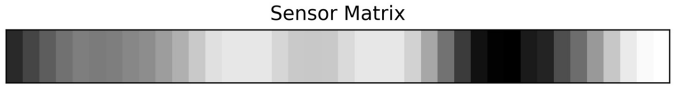
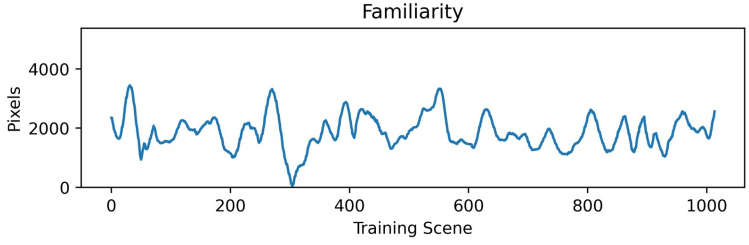
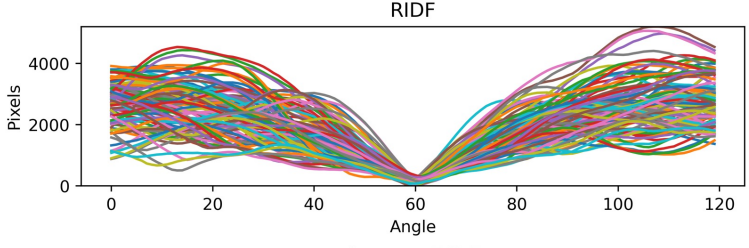
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

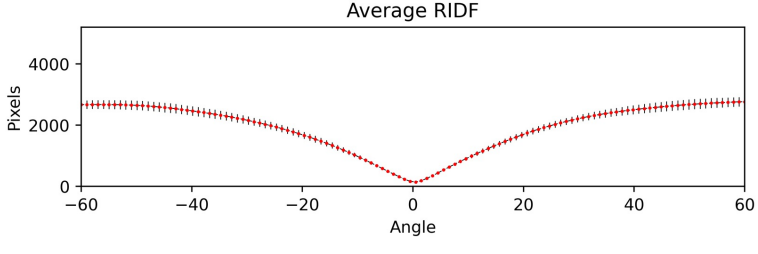
100%







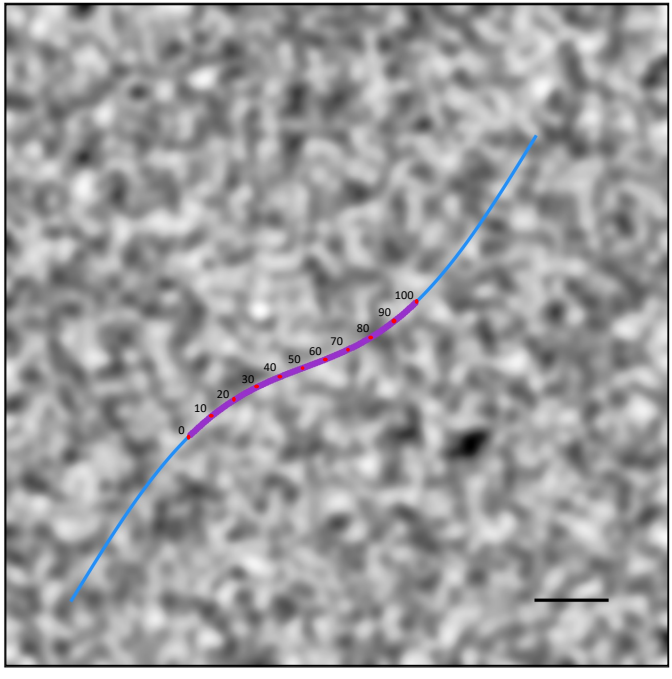


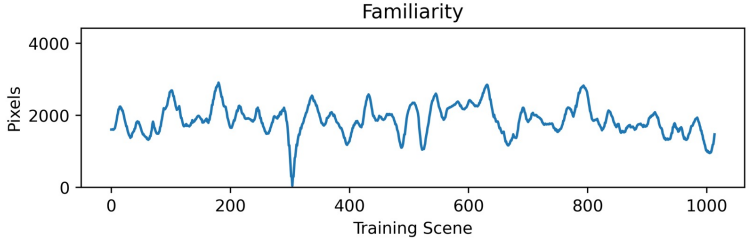


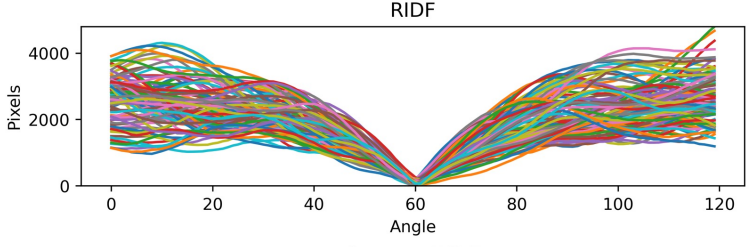
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

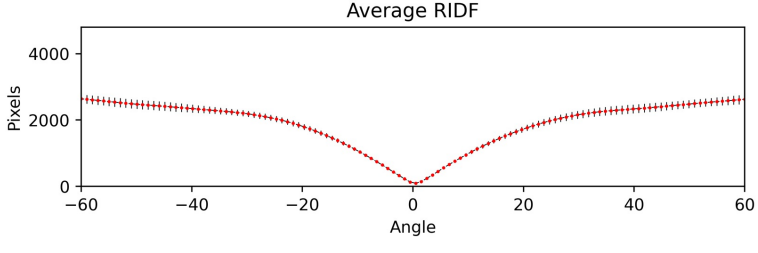
Navigation stats: RMSD error: 91.77; RMSD/dist: 0.229; TD: 1849; p90: 44; p50: 22; complete: 0

100%





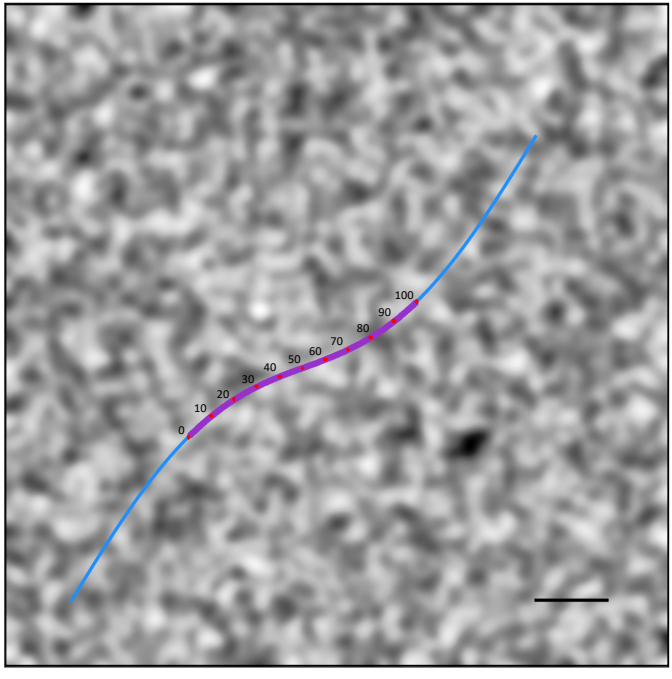


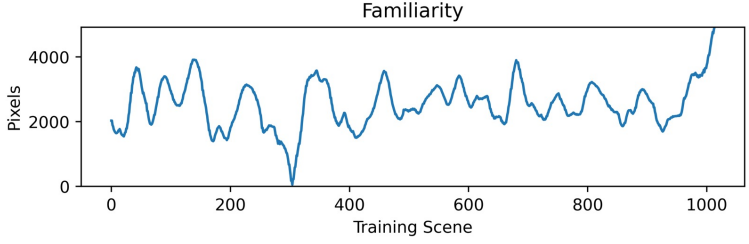


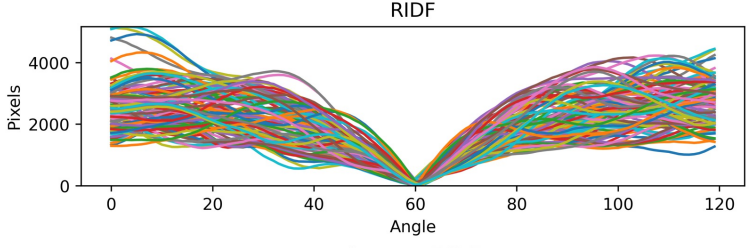
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

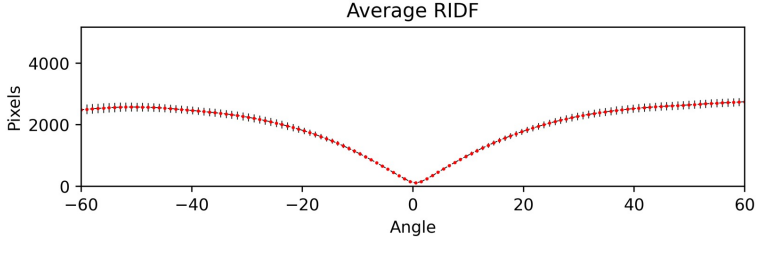
Navigation stats: RMSD error: 36.85; RMSD/dist: 0.092; TD: 1927; p90: 42; p50: 20; complete: 0

100%





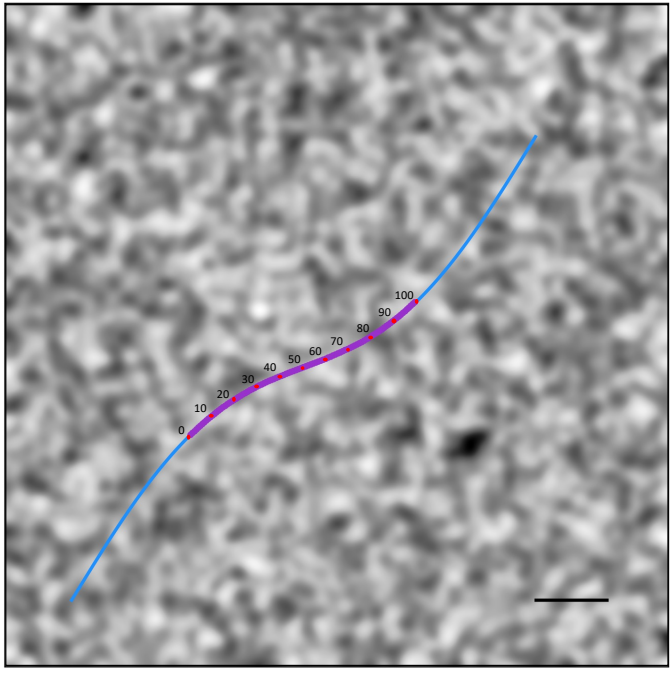


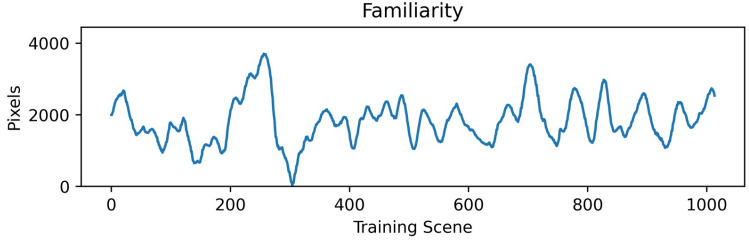


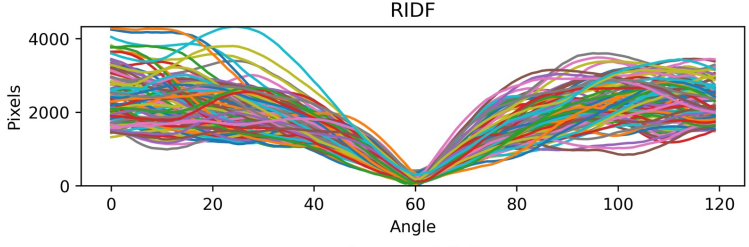
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

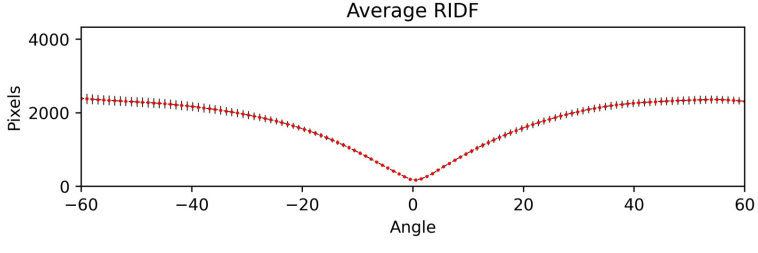
Navigation stats: RMSD error: 54.19; RMSD/dist: 0.135; TD: 2081; p90: 48; p50: 22; complete: 0

100%





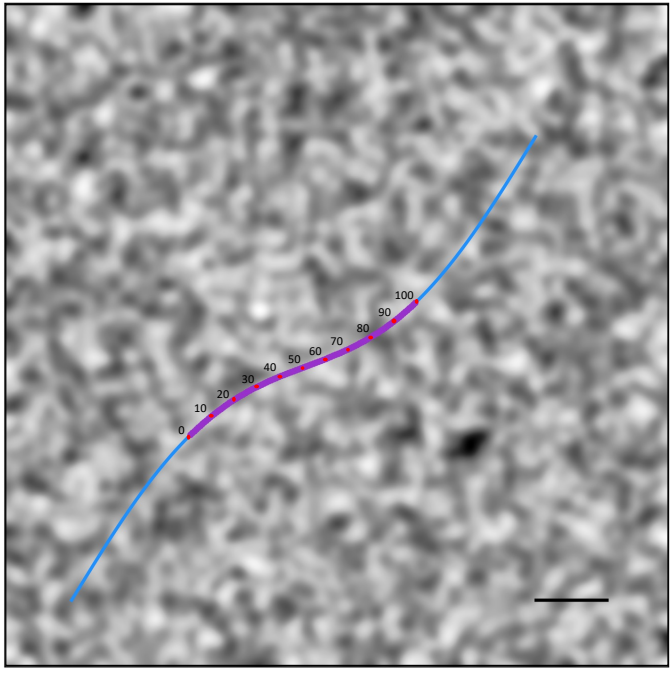


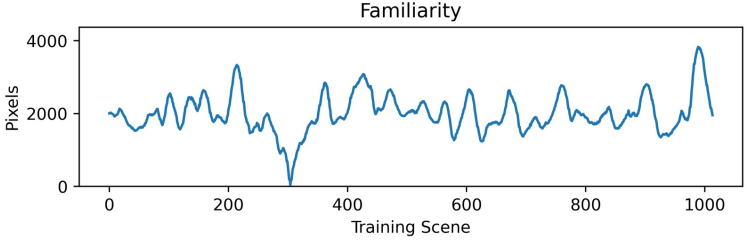


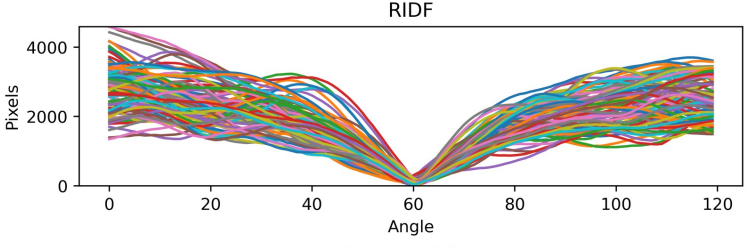
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

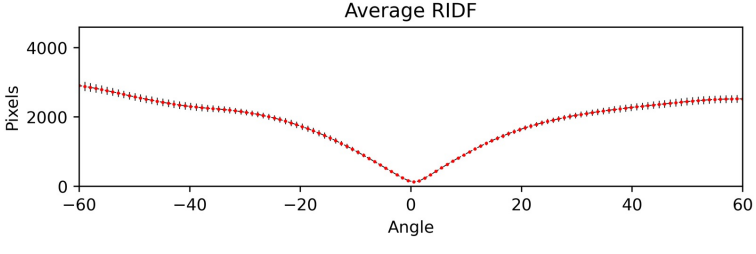
Navigation stats: RMSD error: 113.92; RMSD/dist: 0.285; TD: 1752; p90: 48; p50: 24; complete: 0

100%





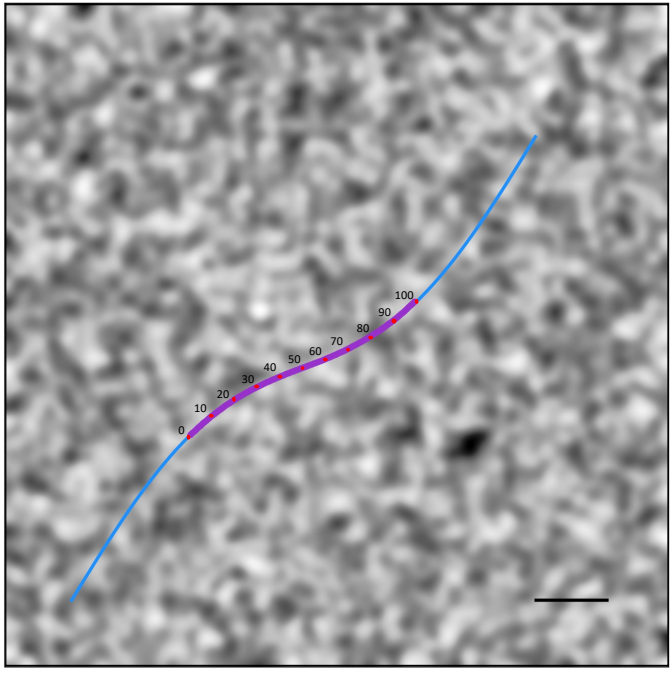


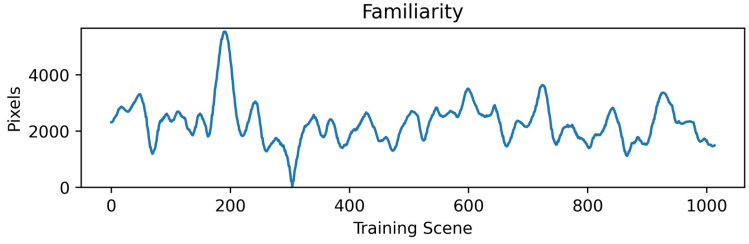


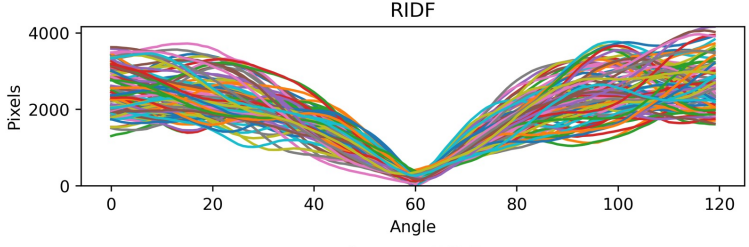
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

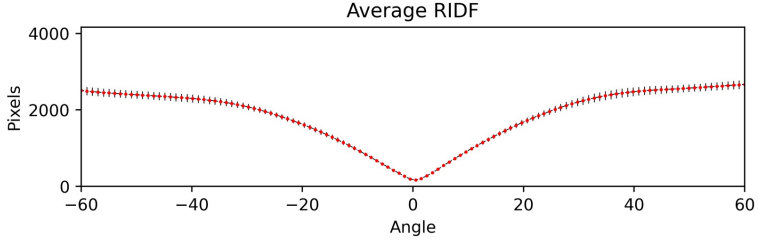
Navigation stats: RMSD error: 65.58; RMSD/dist: 0.164; TD: 1938; p90: 46; p50: 22; complete: 0

100%



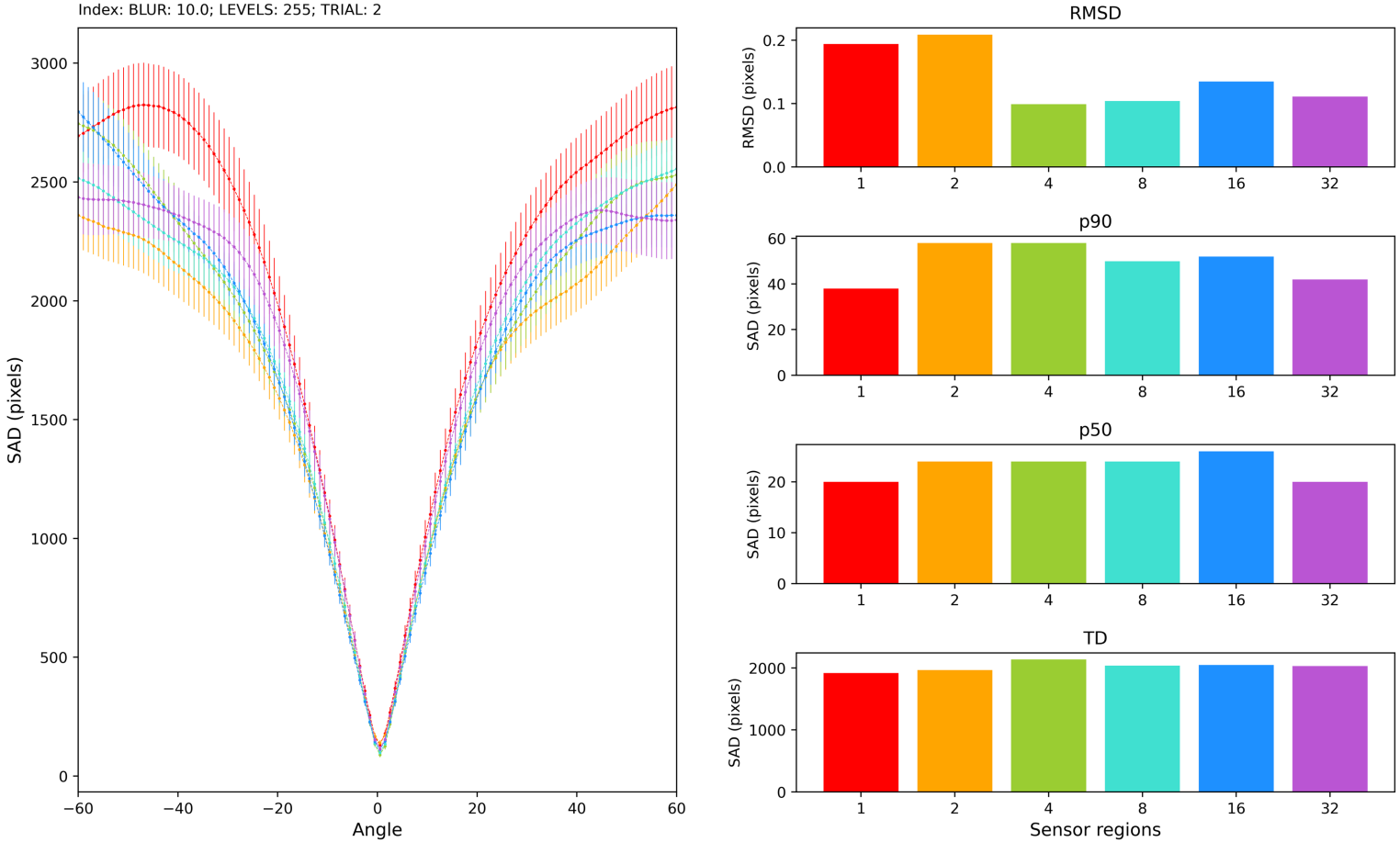




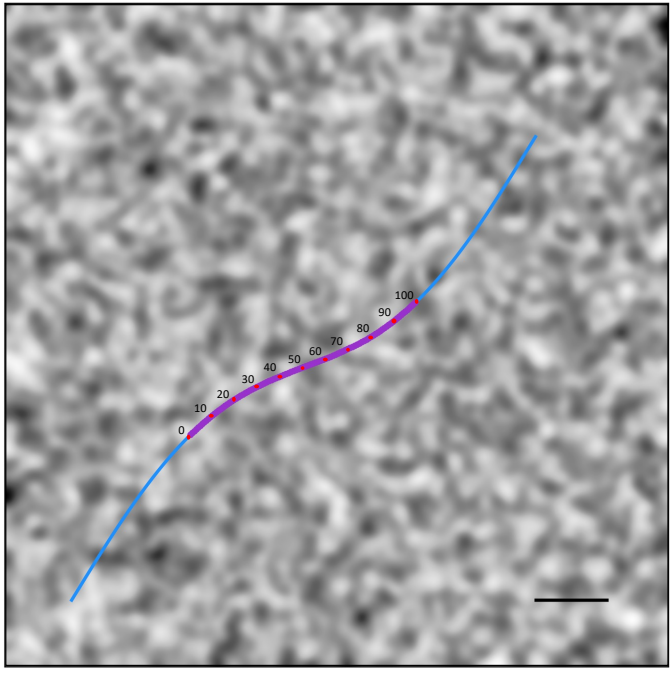


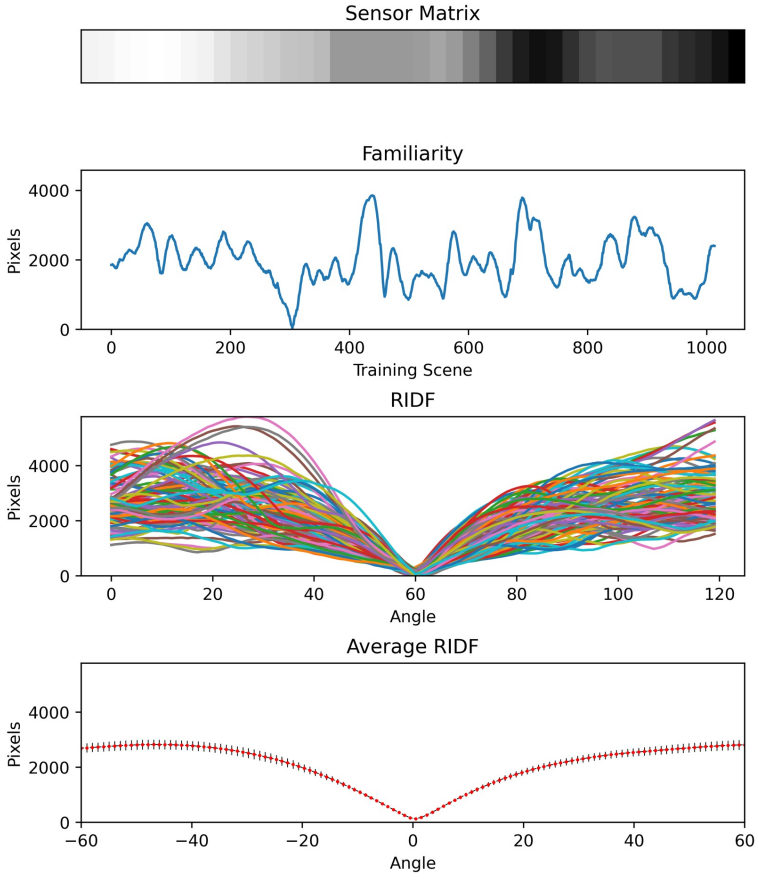
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 105.46; RMSD/dist: 0.264; TD: 2002; p90: 54; p50: 26; complete: 0


Index: BLUR: 10.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

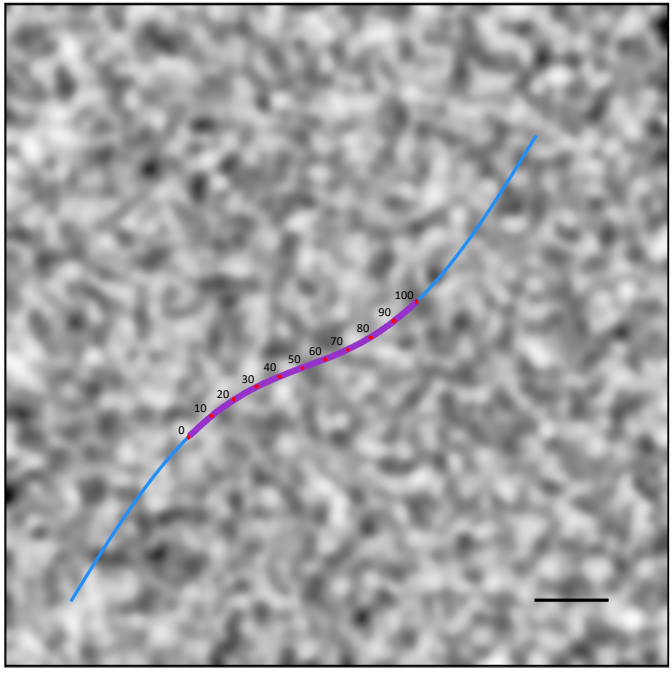


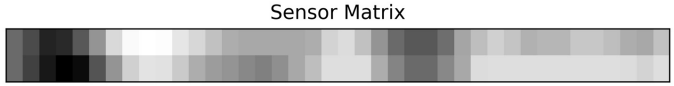


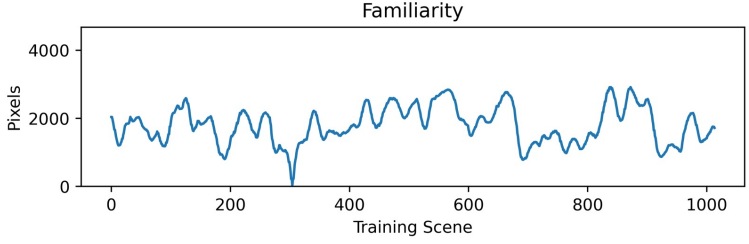
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

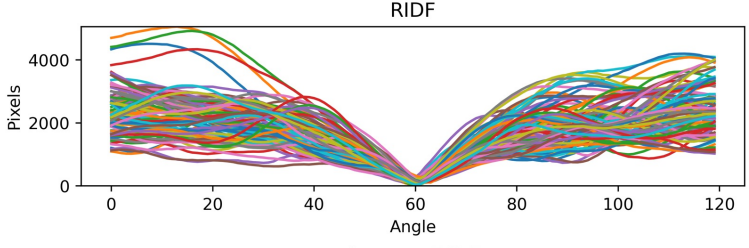
Navigation stats: RMSD error: 77.49; RMSD/dist: 0.194; TD: 1919; p90: 38; p50: 20; complete: 0

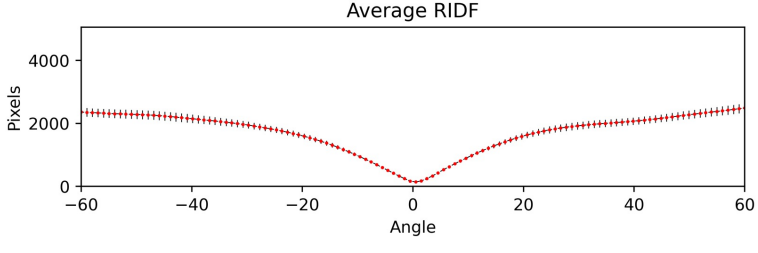
100%







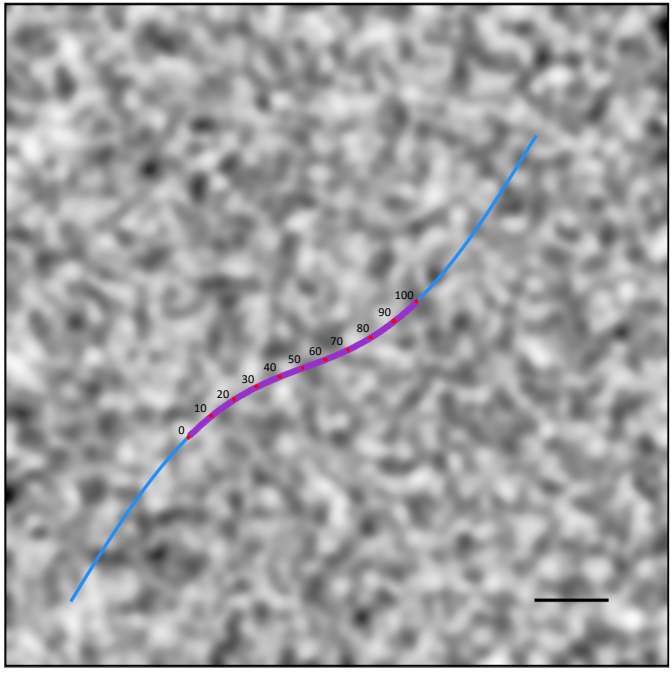


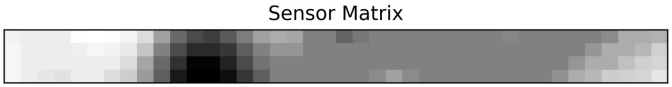


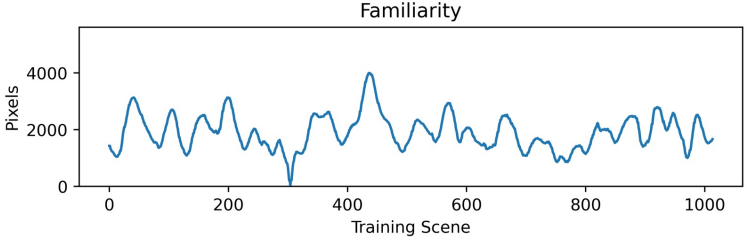
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

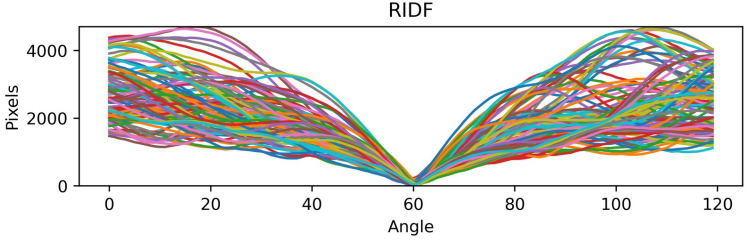
Navigation stats: RMSD error: 83.41; RMSD/dist: 0.209; TD: 1967; p90: 58; p50: 24; complete: 0

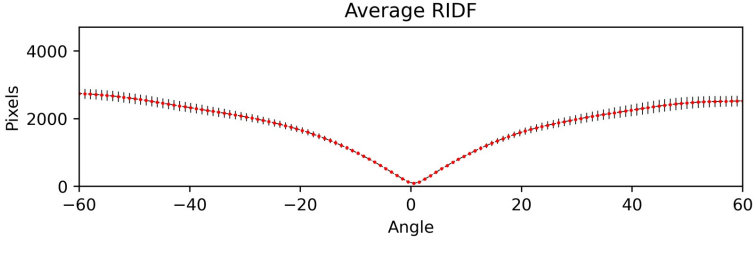
100%







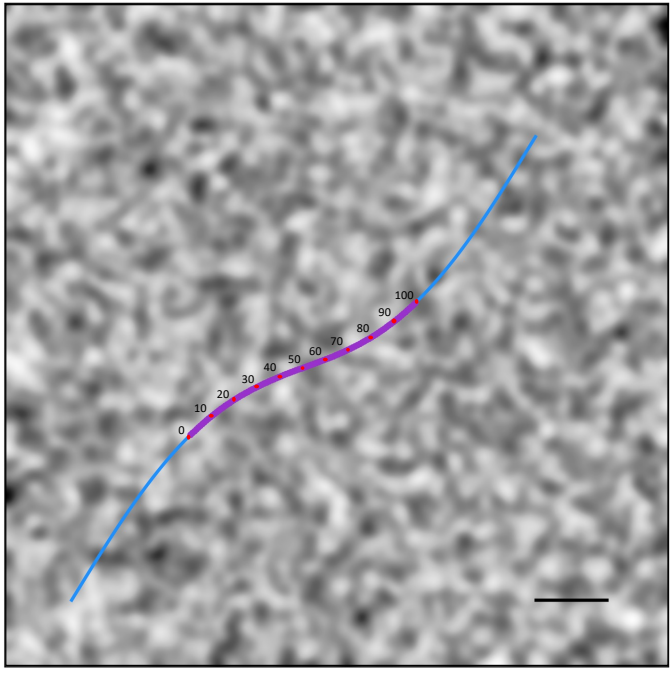


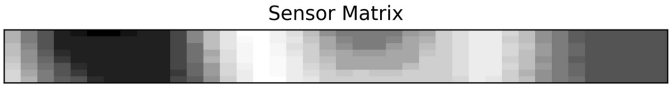


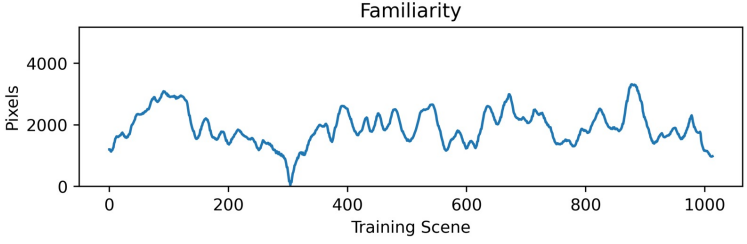
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

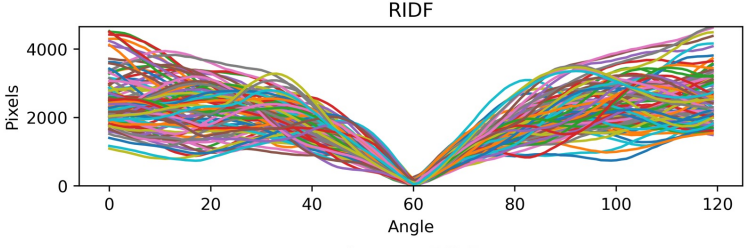
Navigation stats: RMSD error: 39.64; RMSD/dist: 0.099; TD: 2135; p90: 58; p50: 24; complete: 0

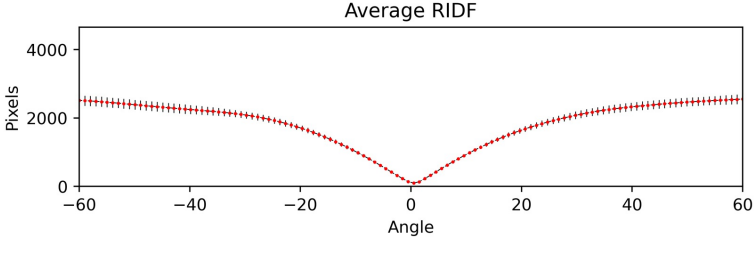
100%







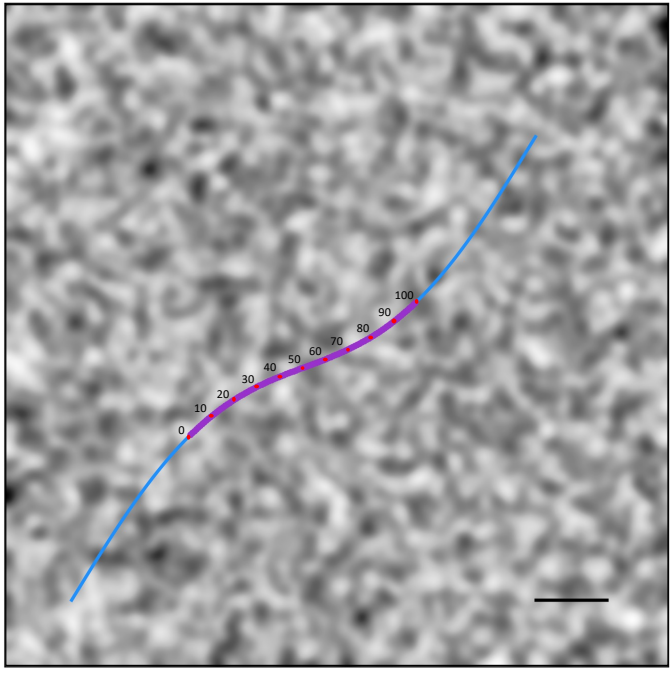


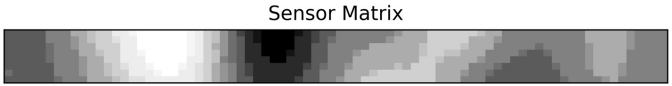


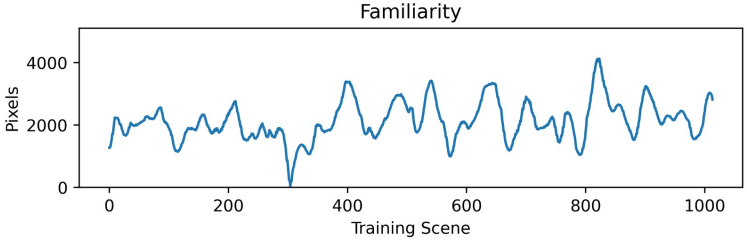
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

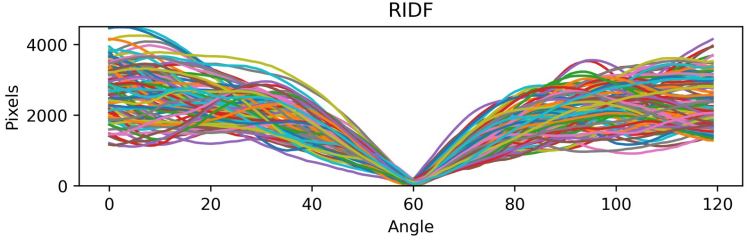
Navigation stats: RMSD error: 41.57; RMSD/dist: 0.104; TD: 2037; p90: 50; p50: 24; complete: 0

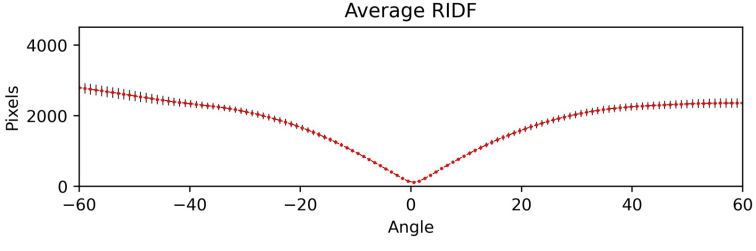
100%







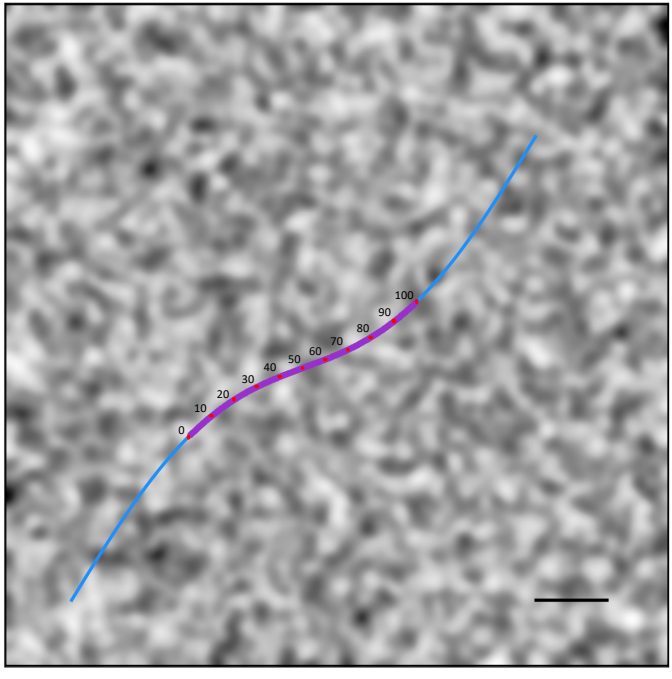


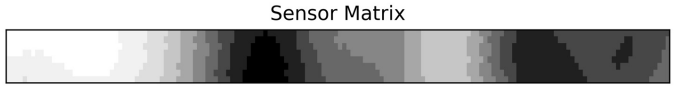


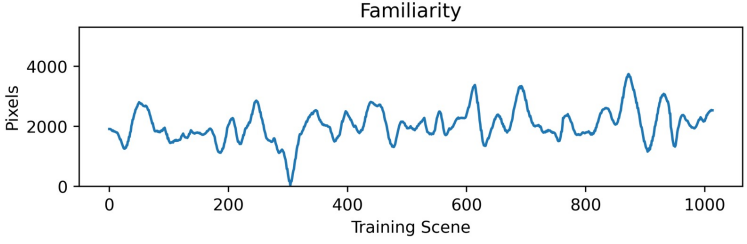
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

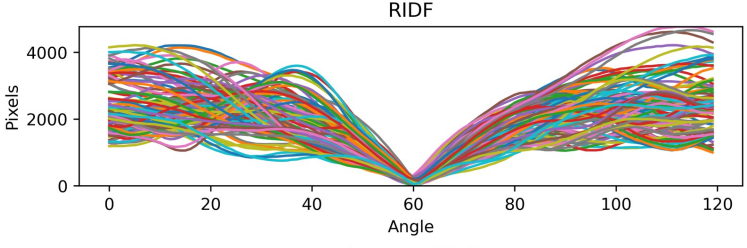
Navigation stats: RMSD error: 54.00; RMSD/dist: 0.135; TD: 2049; p90: 52; p50: 26; complete: 0

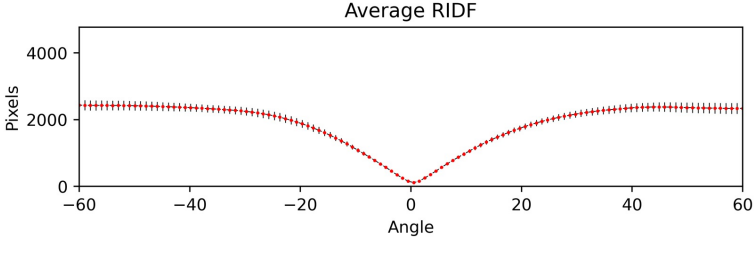
100%





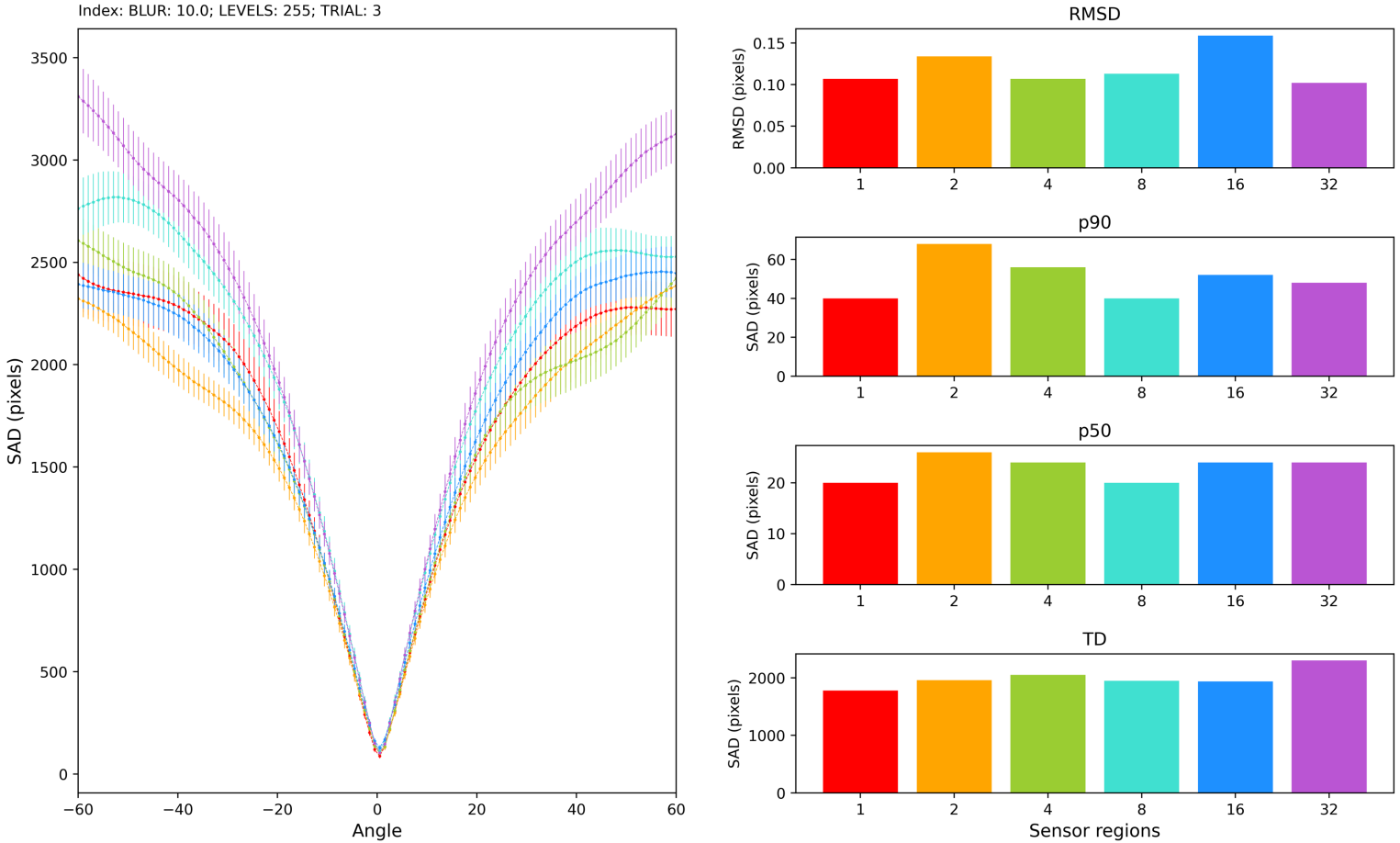




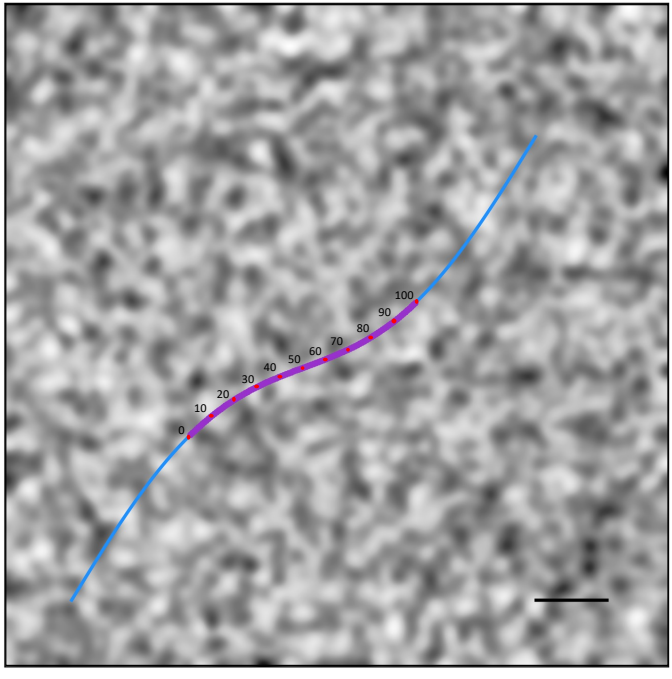


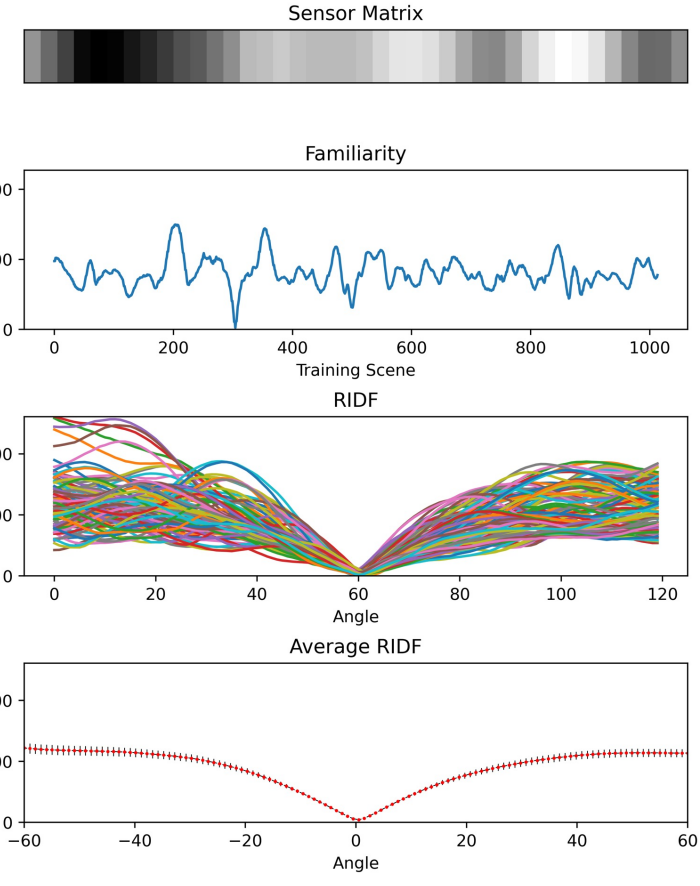
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 44.45; RMSD/dist: 0.111; TD: 2030; p90: 42; p50: 20; complete: 0


Index: BLUR: 10.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

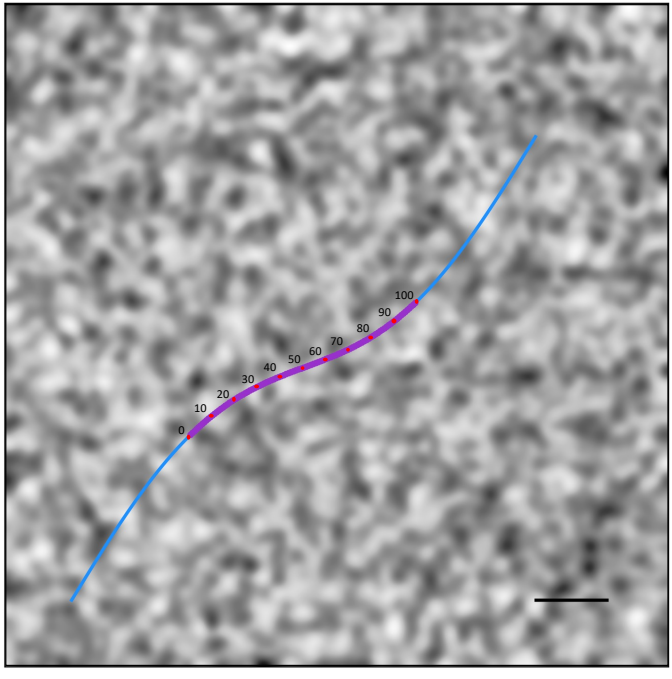


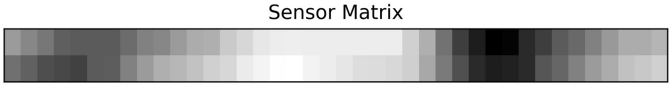


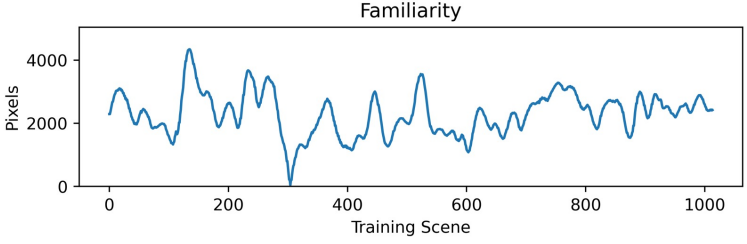
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

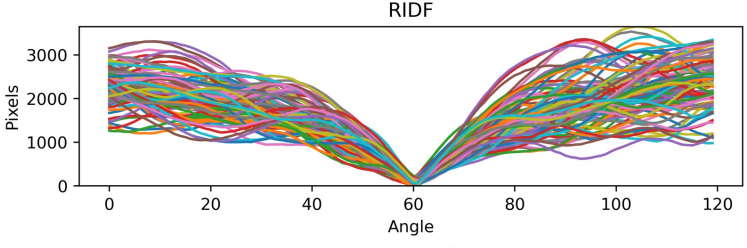
Navigation stats: RMSD error: 42.71; RMSD/dist: 0.107; TD: 1778; p90: 40; p50: 20; complete: 0

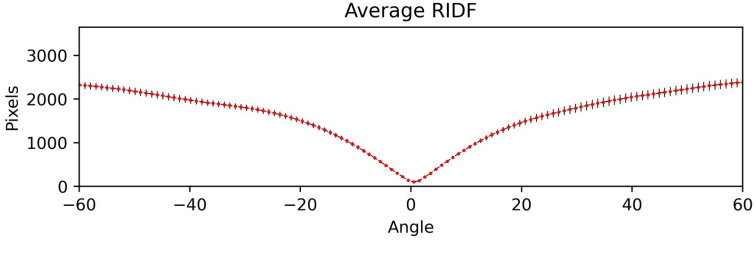
100%







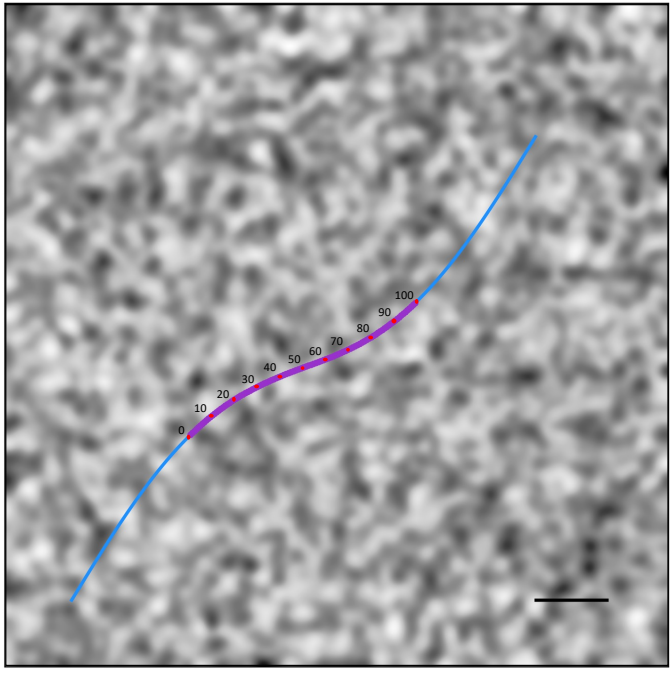


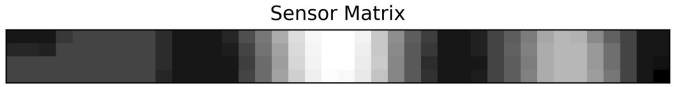


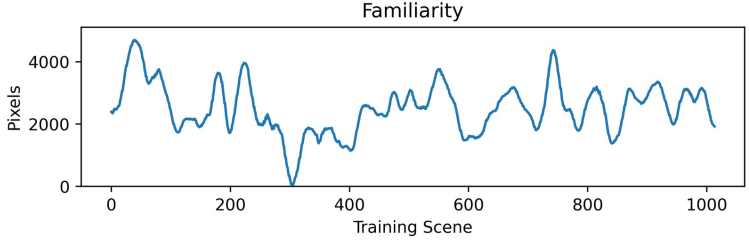
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

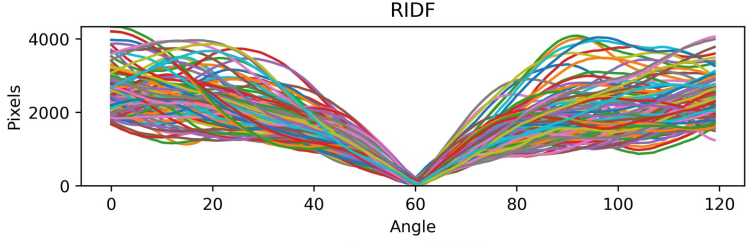
Navigation stats: RMSD error: 53.71; RMSD/dist: 0.134; TD: 1959; p90: 68; p50: 26; complete: 0

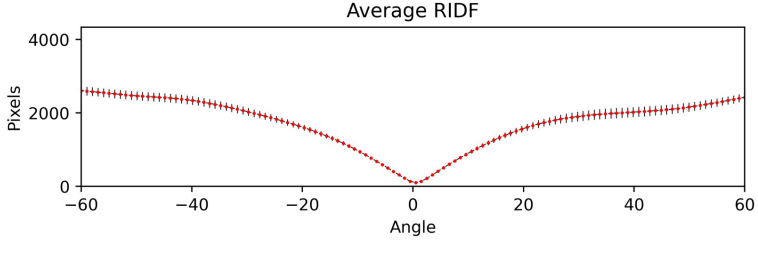
100%







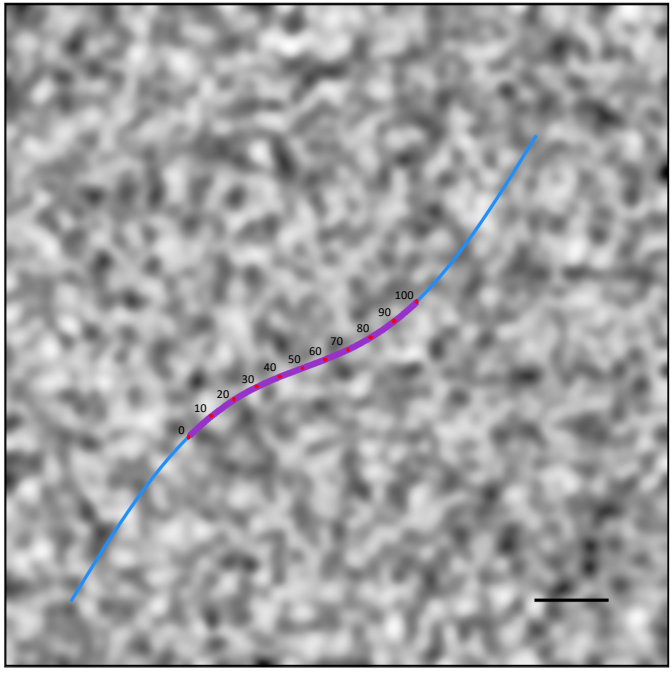


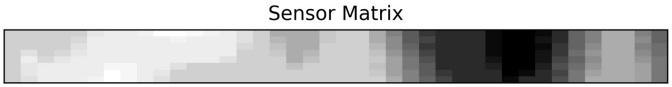


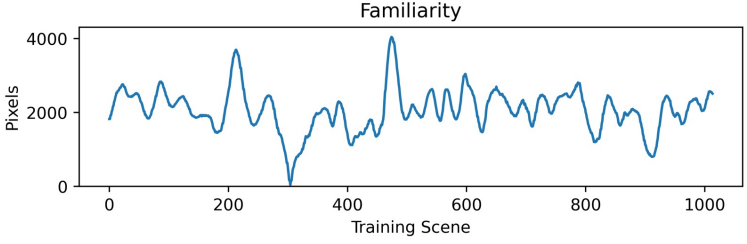
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

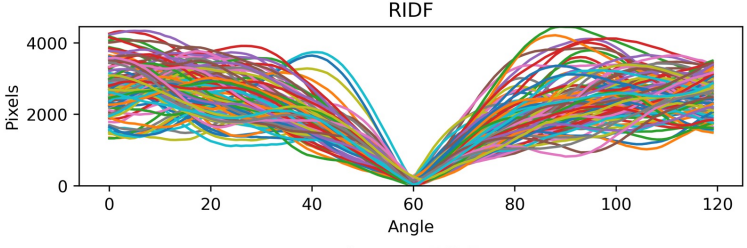
Navigation stats: RMSD error: 42.78; RMSD/dist: 0.107; TD: 2052; p90: 56; p50: 24; complete: 0

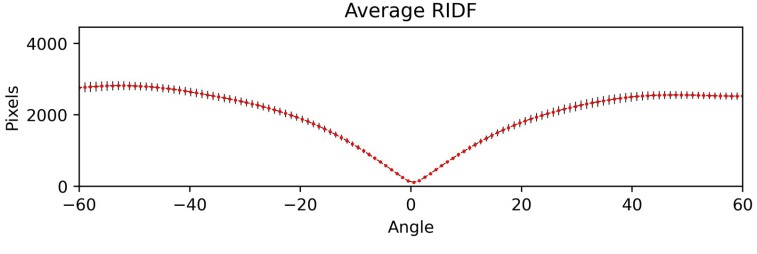
100%







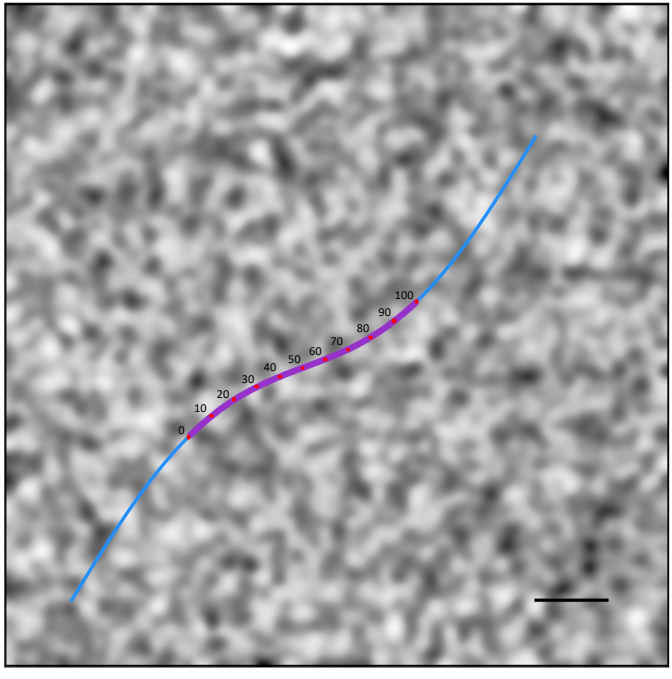


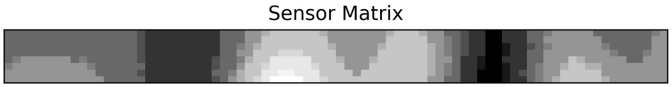


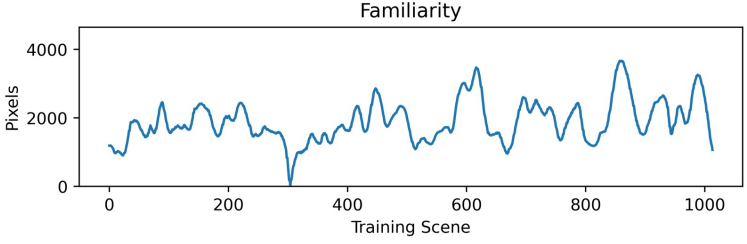
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

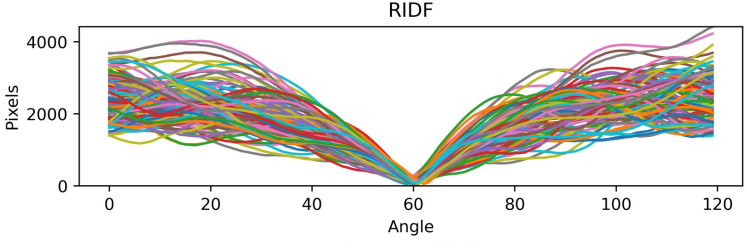
Navigation stats: RMSD error: 45.30; RMSD/dist: 0.113; TD: 1949; p90: 40; p50: 20; complete: 0

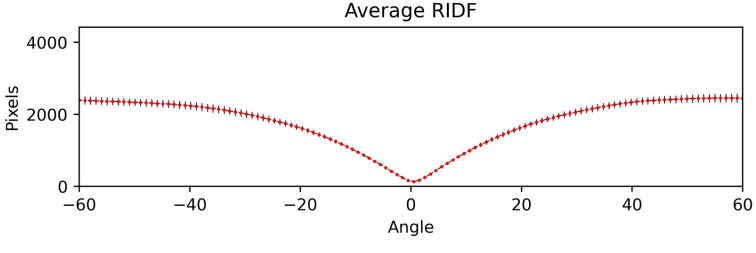
100%







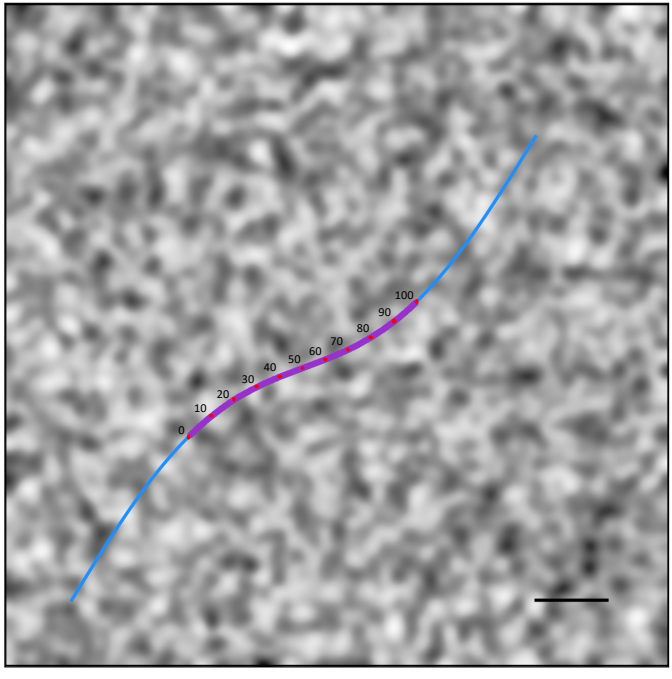


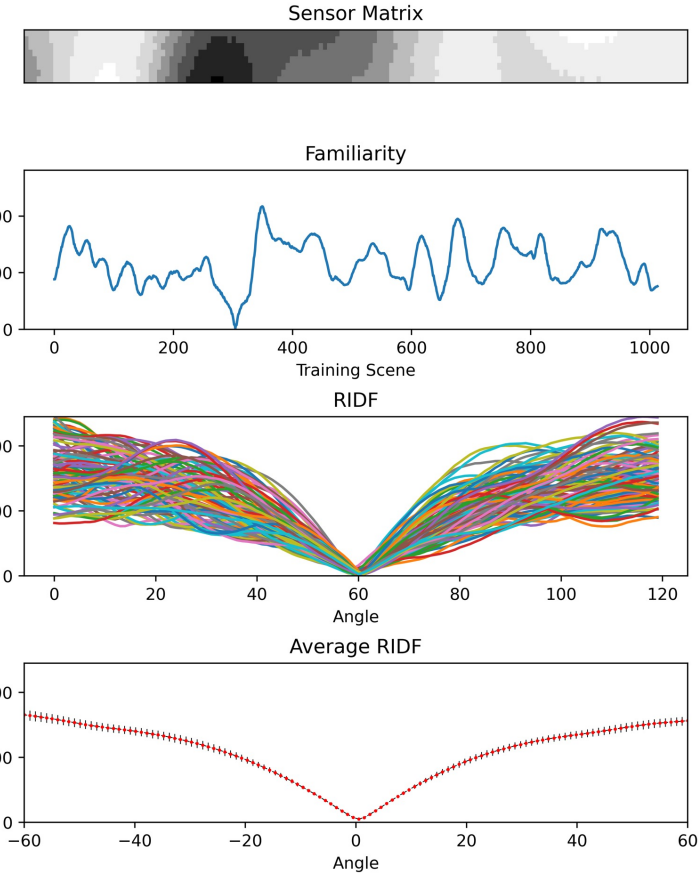


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 63.79; RMSD/dist: 0.159; TD: 1936; p90: 52; p50: 24; complete: 0

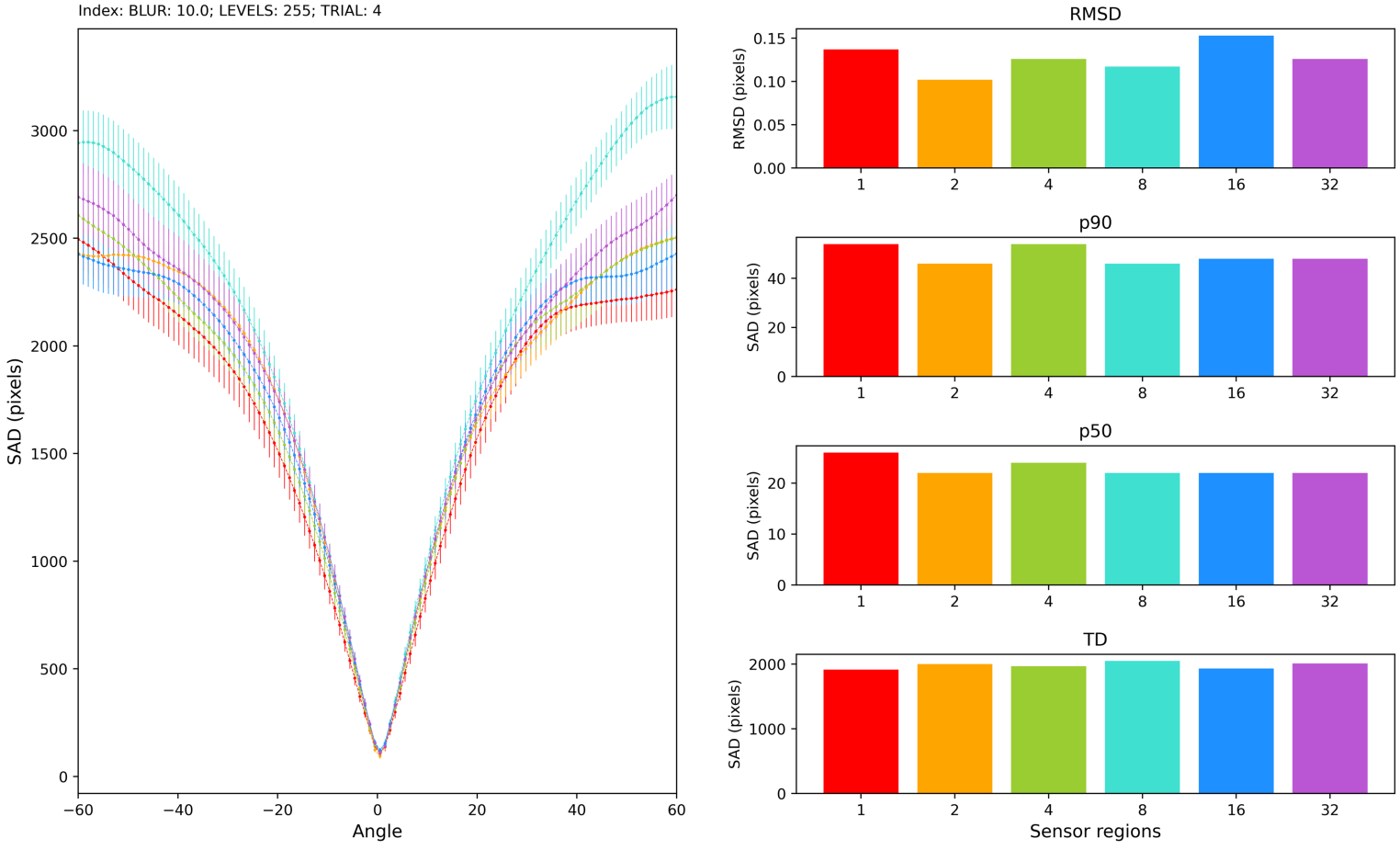
100%



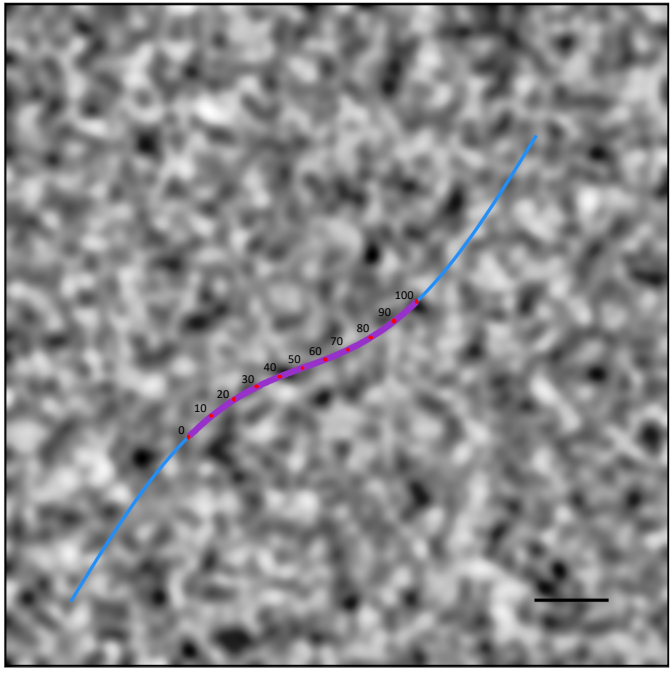


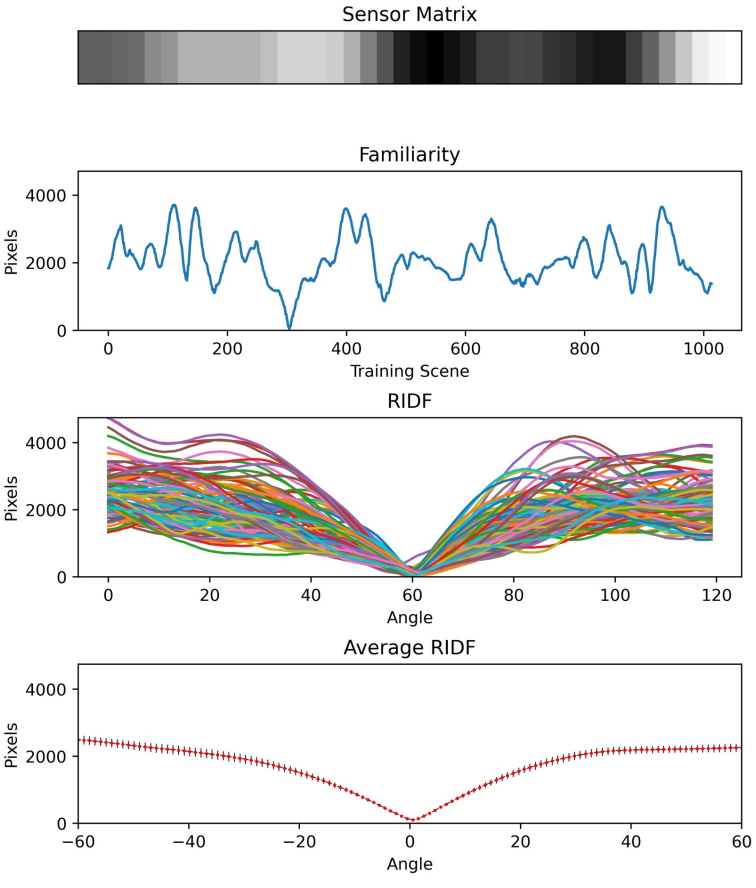
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 40.62; RMSD/dist: 0.102; TD: 2299; p90: 48; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 255; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

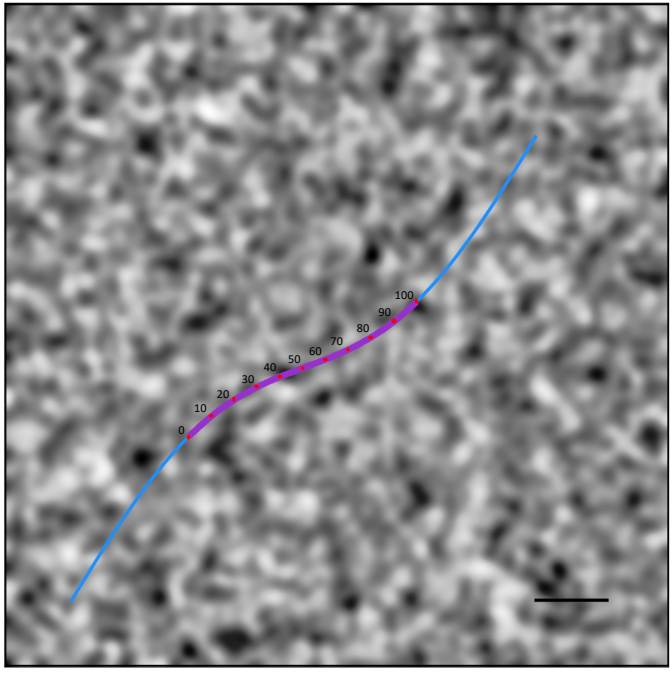


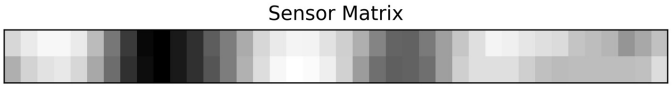


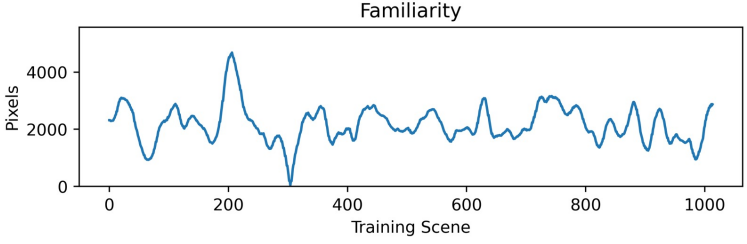
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

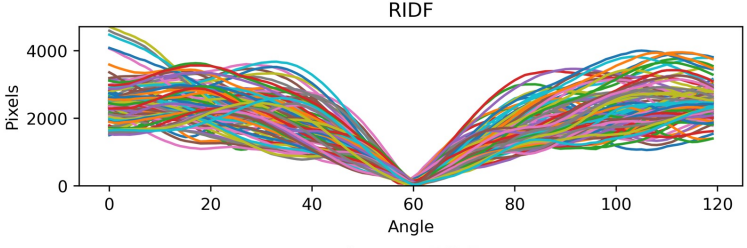
Navigation stats: RMSD error: 54.64; RMSD/dist: 0.137; TD: 1913; p90: 54; p50: 26; complete: 0

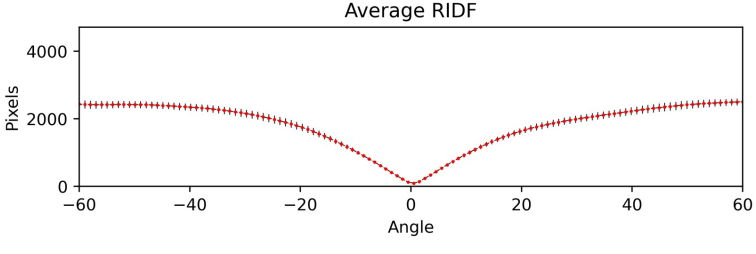
100%







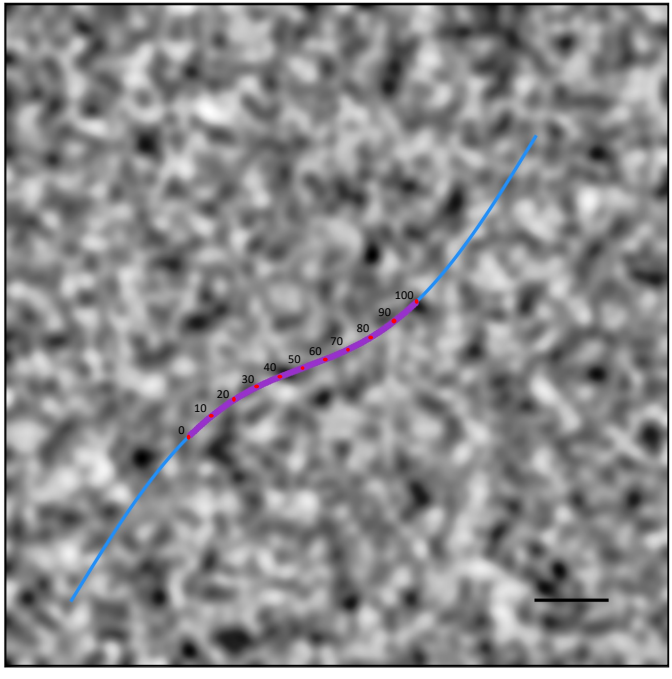


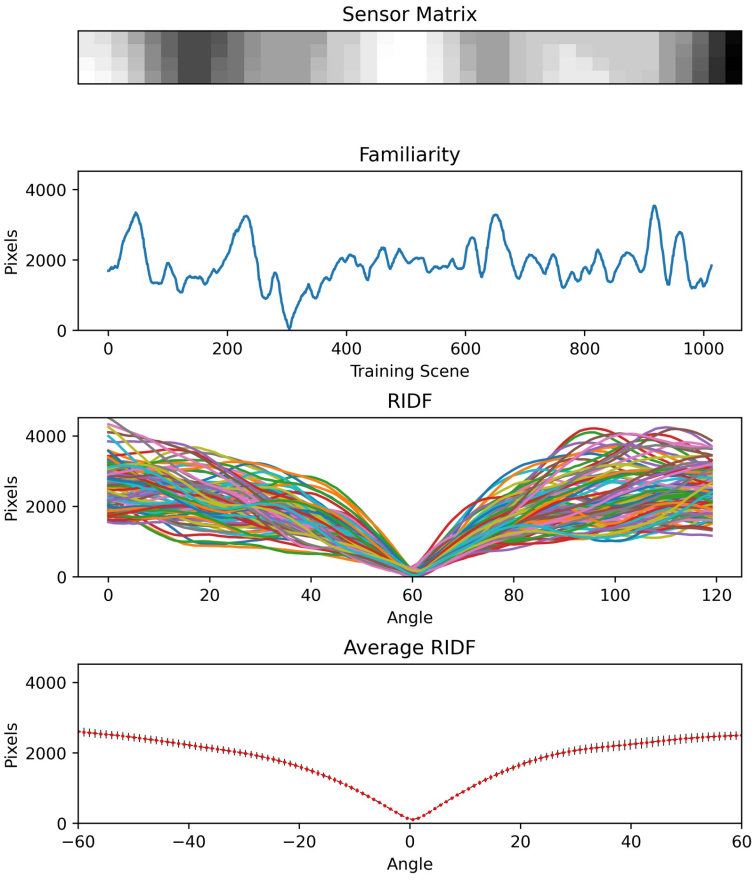


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 40.88; RMSD/dist: 0.102; TD: 2000; p90: 46; p50: 22; complete: 0

100%

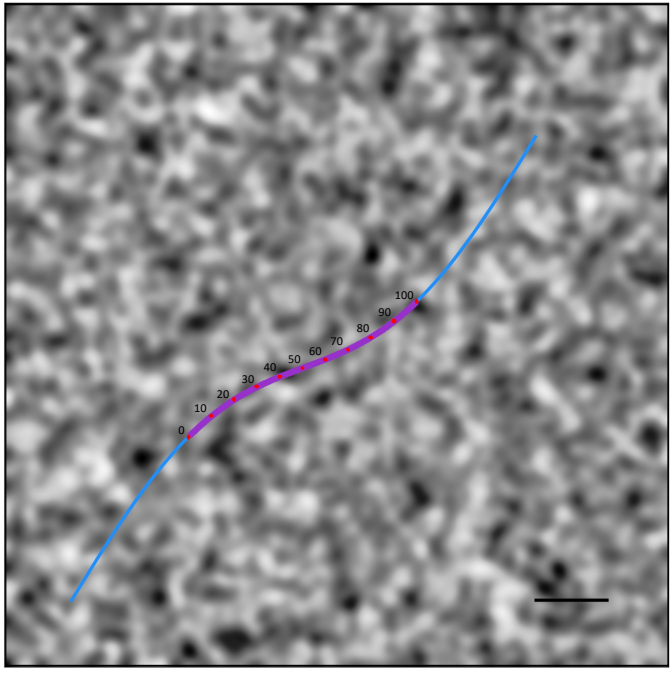


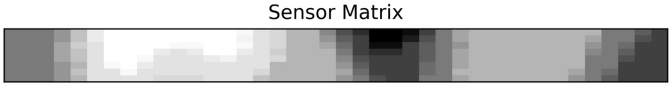


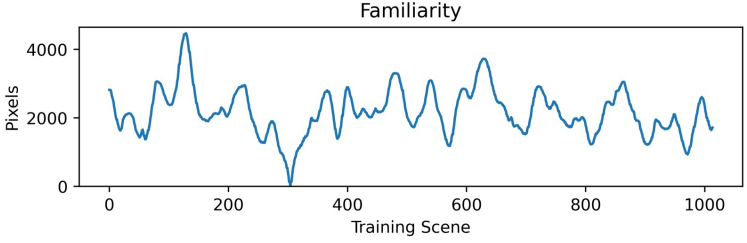
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

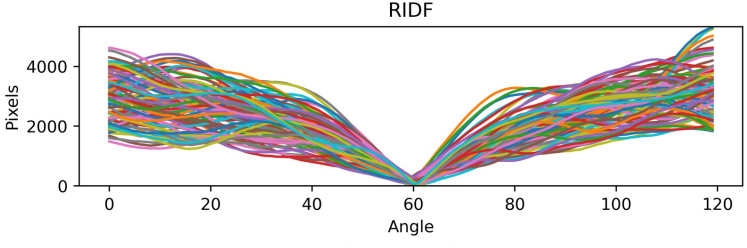
Navigation stats: RMSD error: 50.39; RMSD/dist: 0.126; TD: 1968; p90: 54; p50: 24; complete: 0

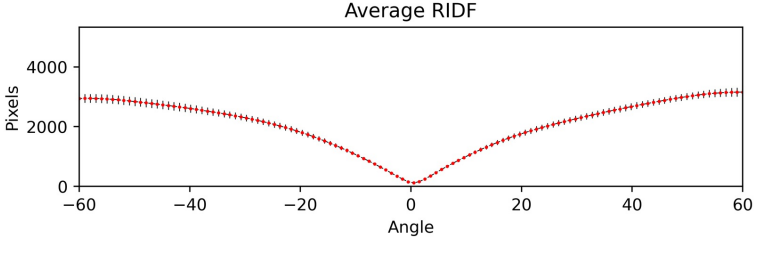
100%







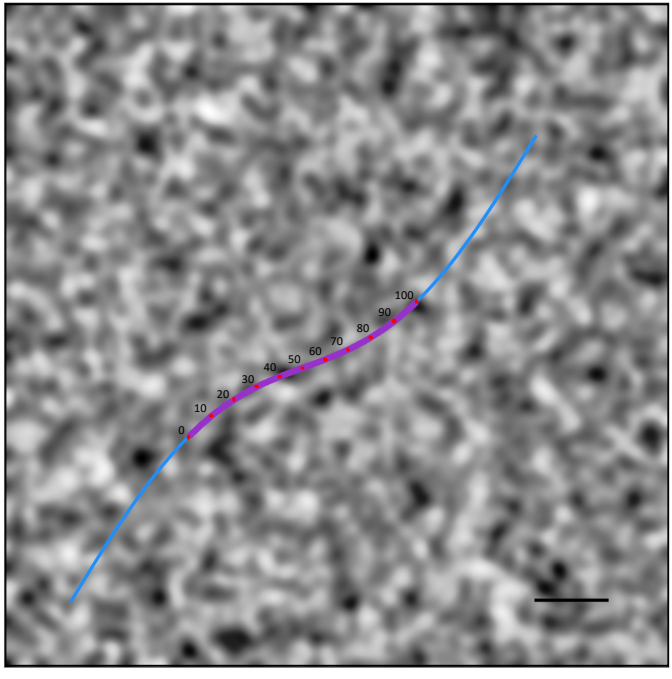


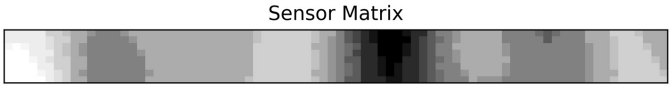


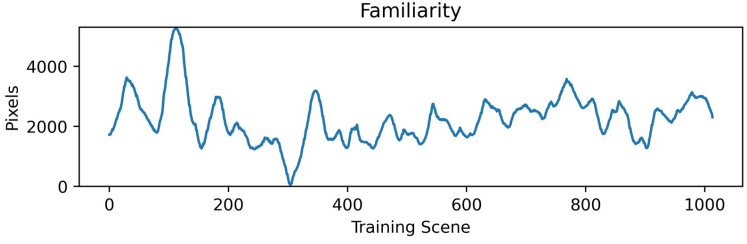
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

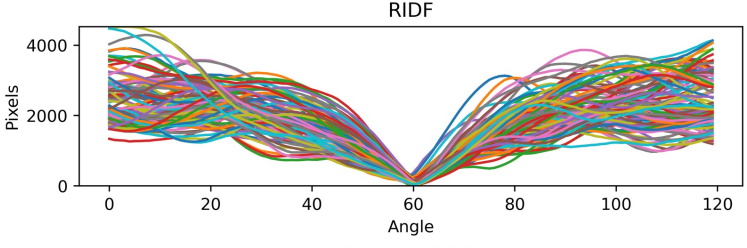
Navigation stats: RMSD error: 46.62; RMSD/dist: 0.117; TD: 2047; p90: 46; p50: 22; complete: 0

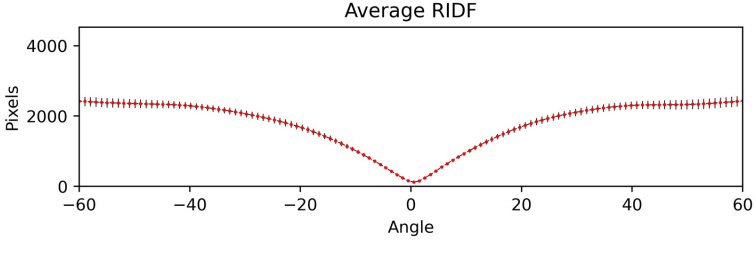
100%







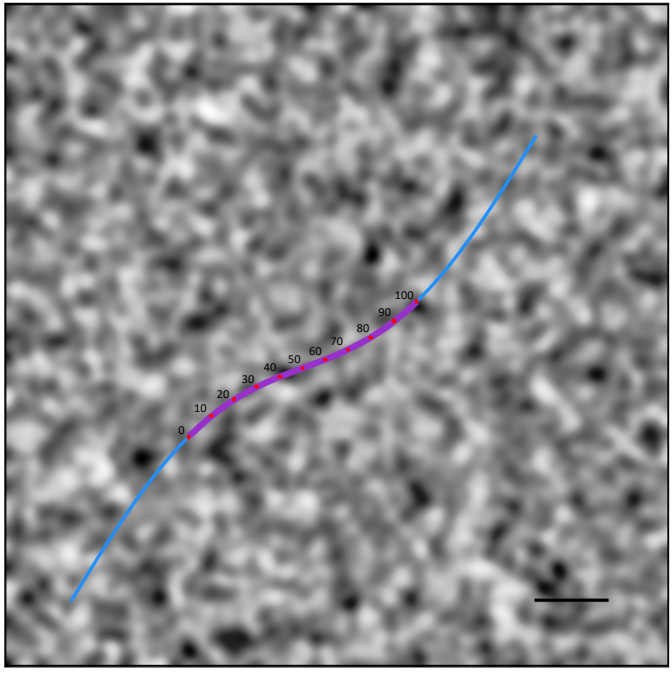


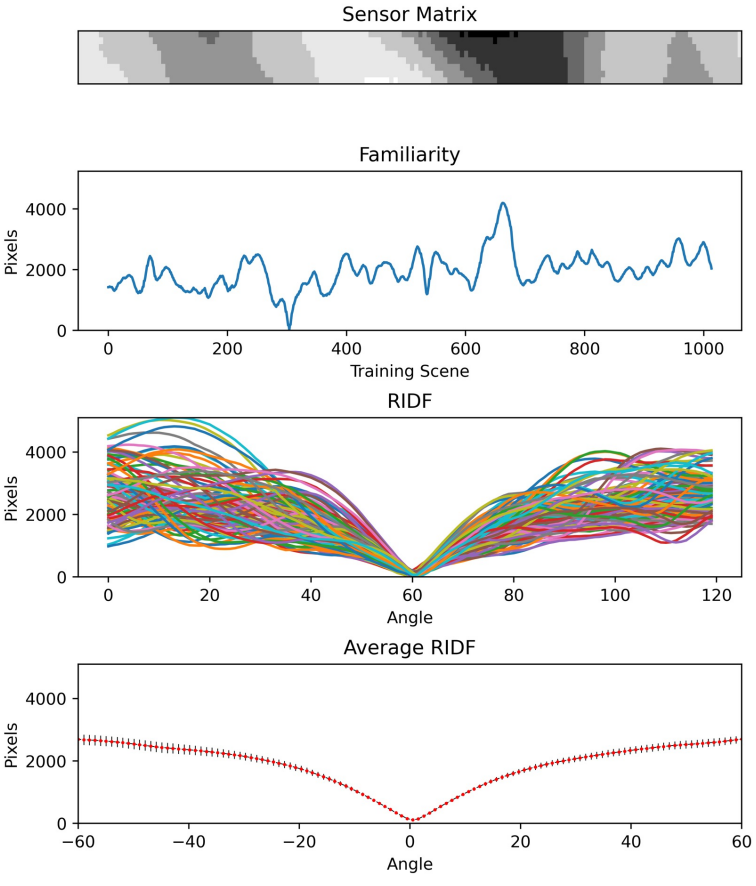


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 61.05; RMSD/dist: 0.153; TD: 1930; p90: 48; p50: 22; complete: 0

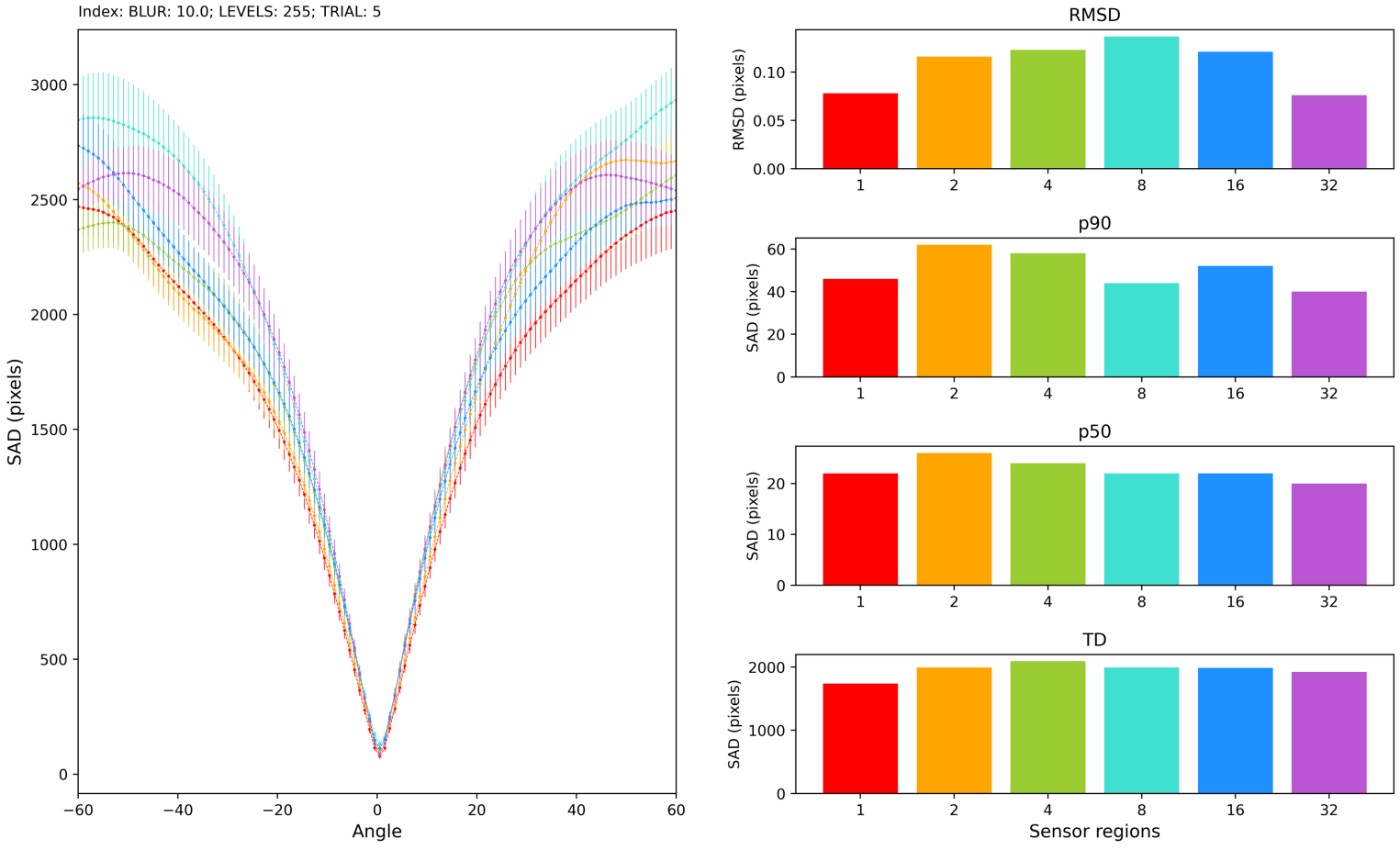
100%



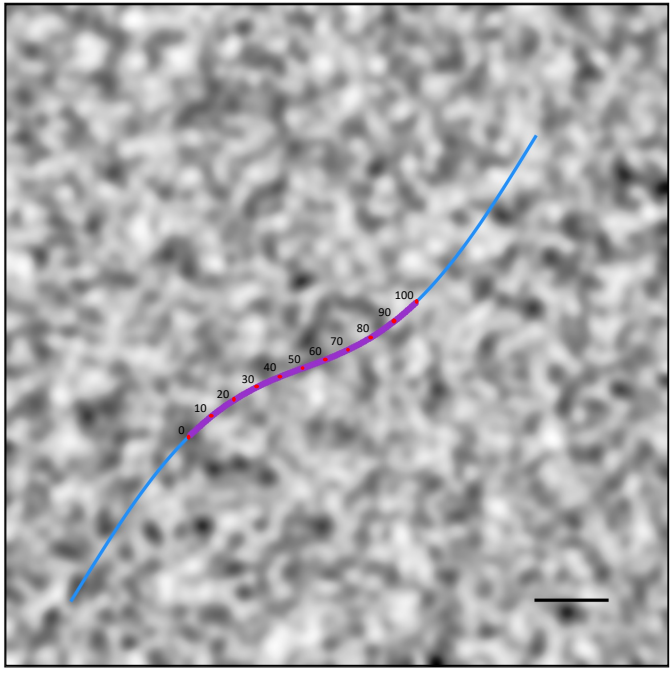


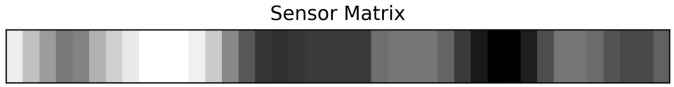
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

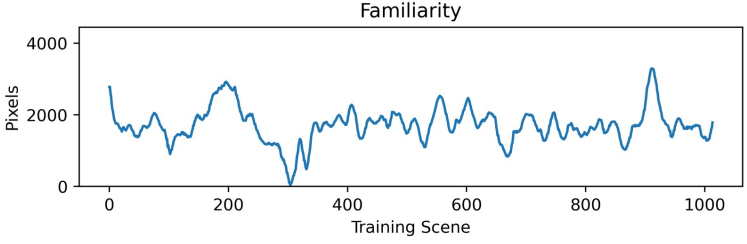
Navigation stats: RMSD error: 50.36; RMSD/dist: 0.126; TD: 2009; p90: 48; p50: 22; complete: 0

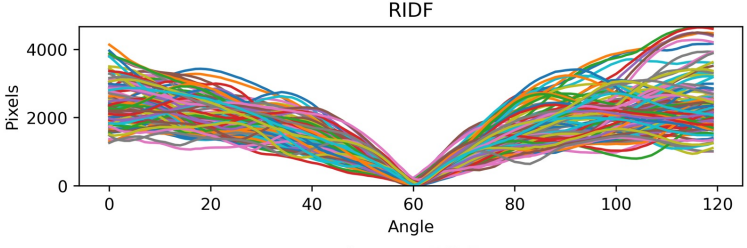

Index: BLUR: 10.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

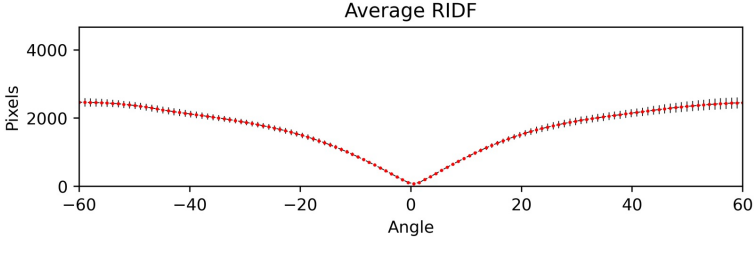
100%







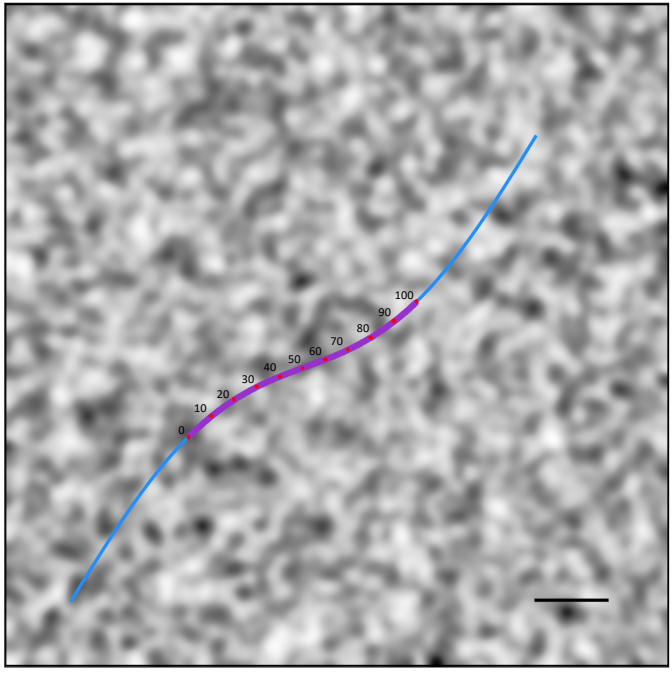


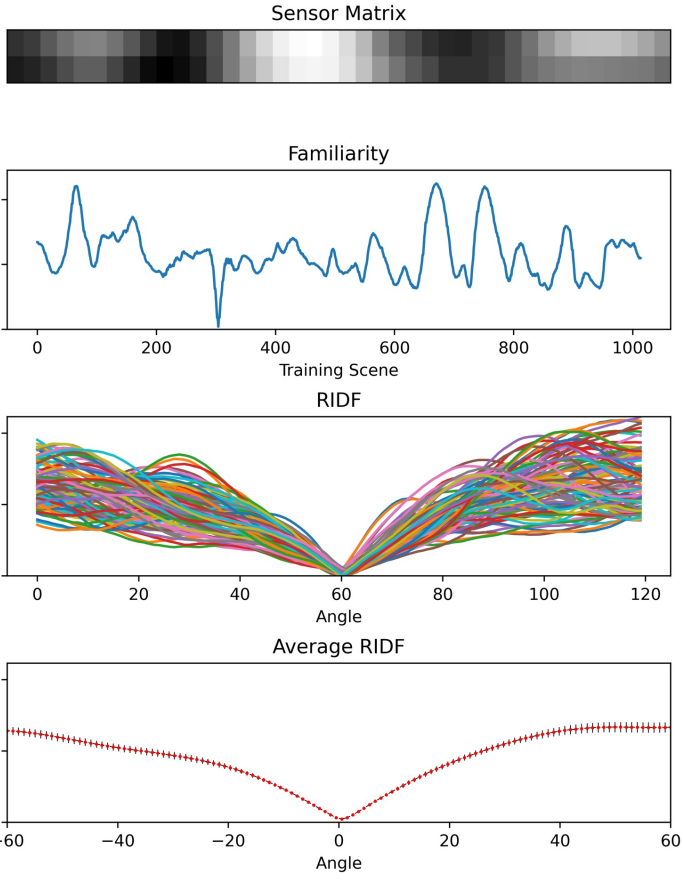


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 31.23; RMSD/dist: 0.078; TD: 1737; p90: 46; p50: 22; complete: 0

100%

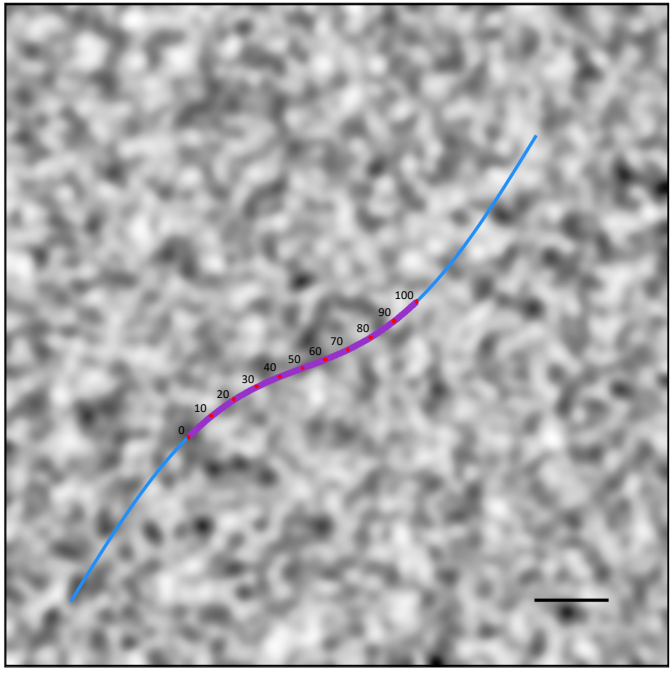


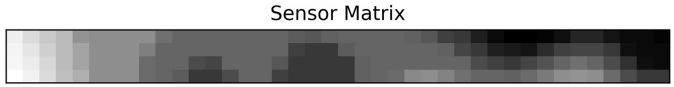


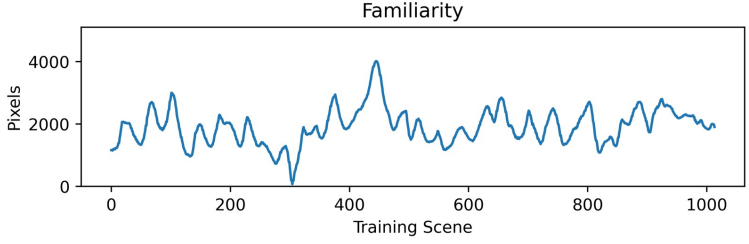
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

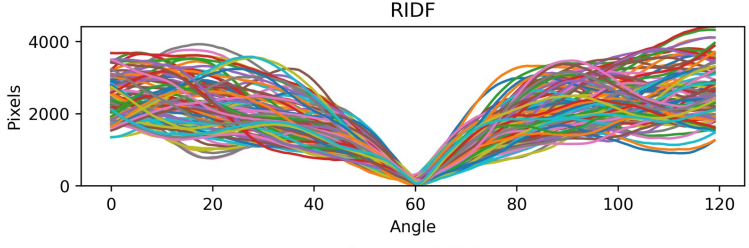
Navigation stats: RMSD error: 46.22; RMSD/dist: 0.116; TD: 1994; p90: 62; p50: 26; complete: 0

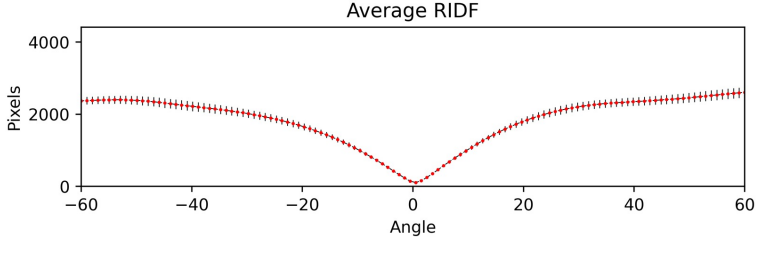
100%







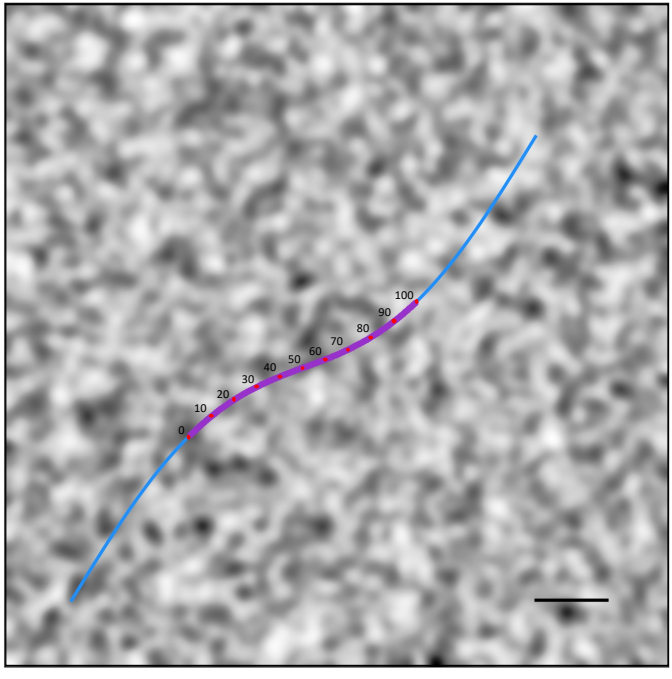


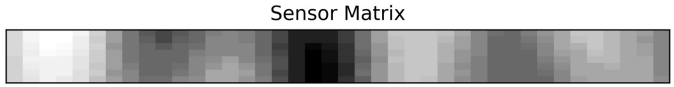


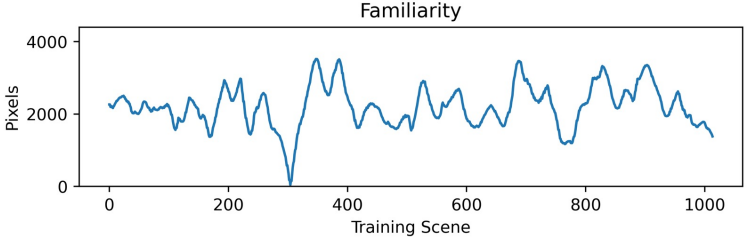
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

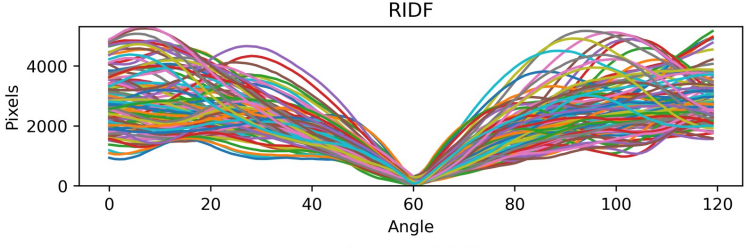
Navigation stats: RMSD error: 49.38; RMSD/dist: 0.123; TD: 2092; p90: 58; p50: 24; complete: 0

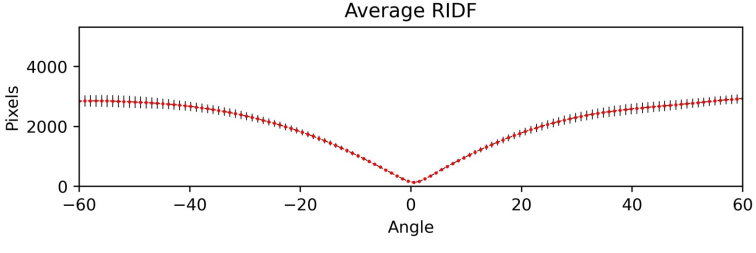
100%







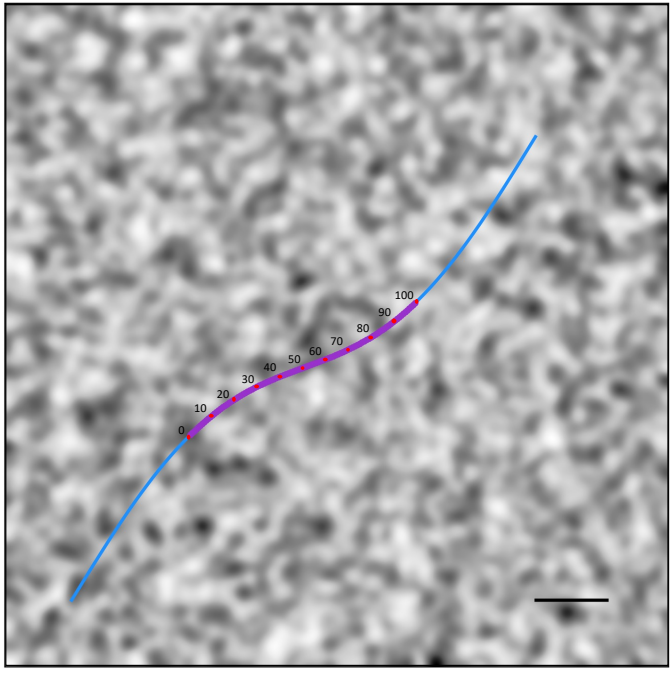


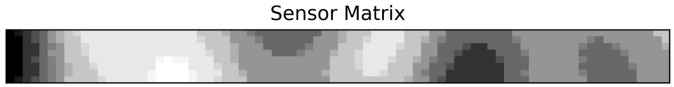


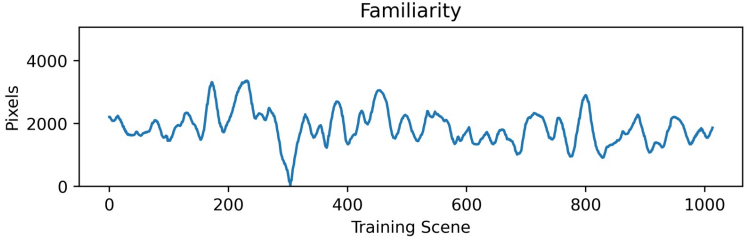
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

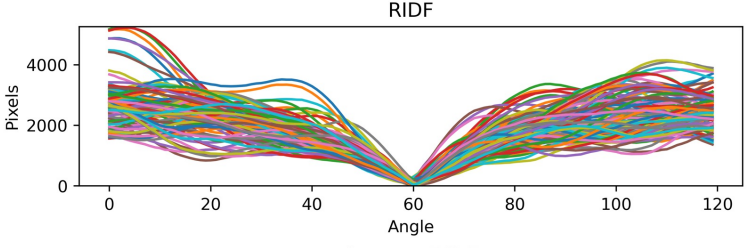
Navigation stats: RMSD error: 54.91; RMSD/dist: 0.137; TD: 1993; p90: 44; p50: 22; complete: 0

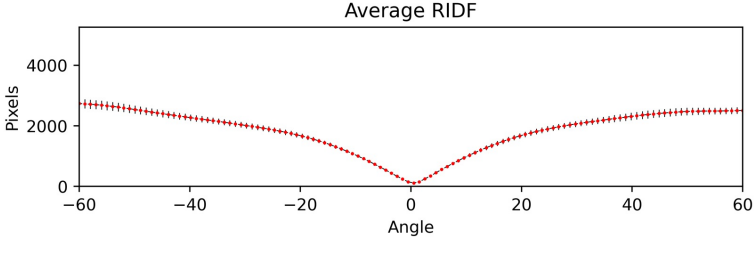
100%







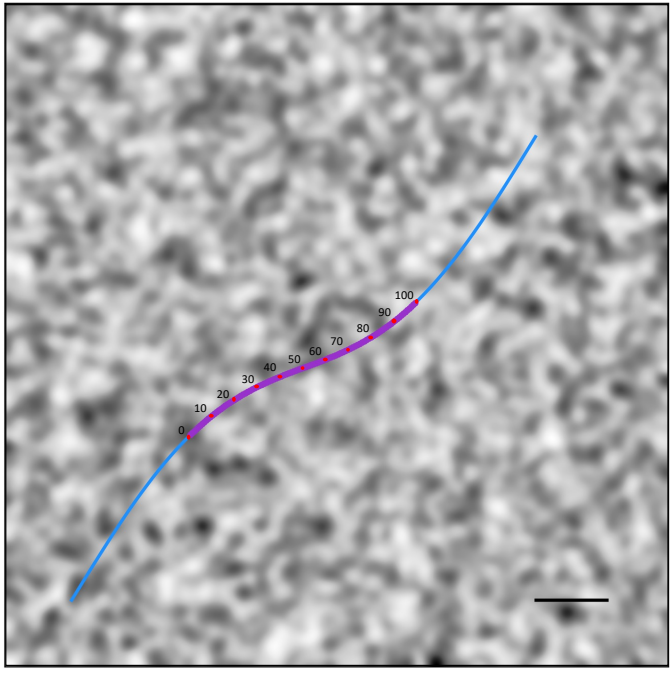


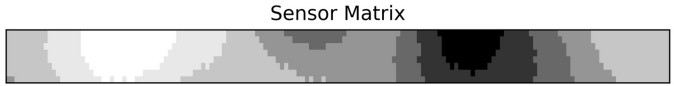


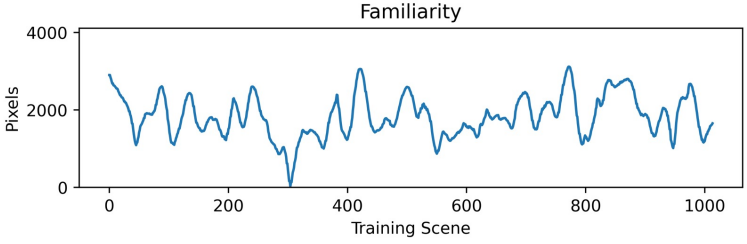
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

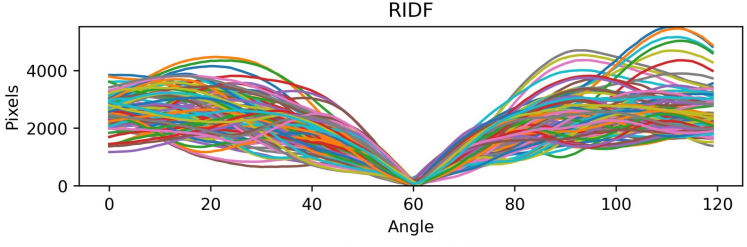
Navigation stats: RMSD error: 48.32; RMSD/dist: 0.121; TD: 1987; p90: 52; p50: 22; complete: 0

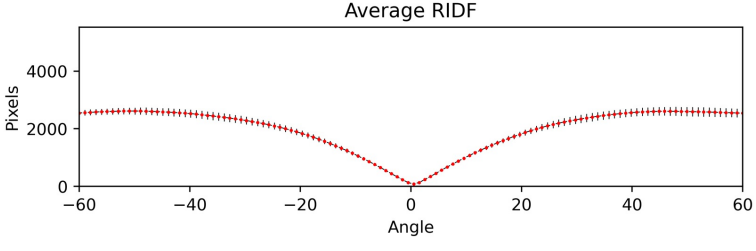
100%





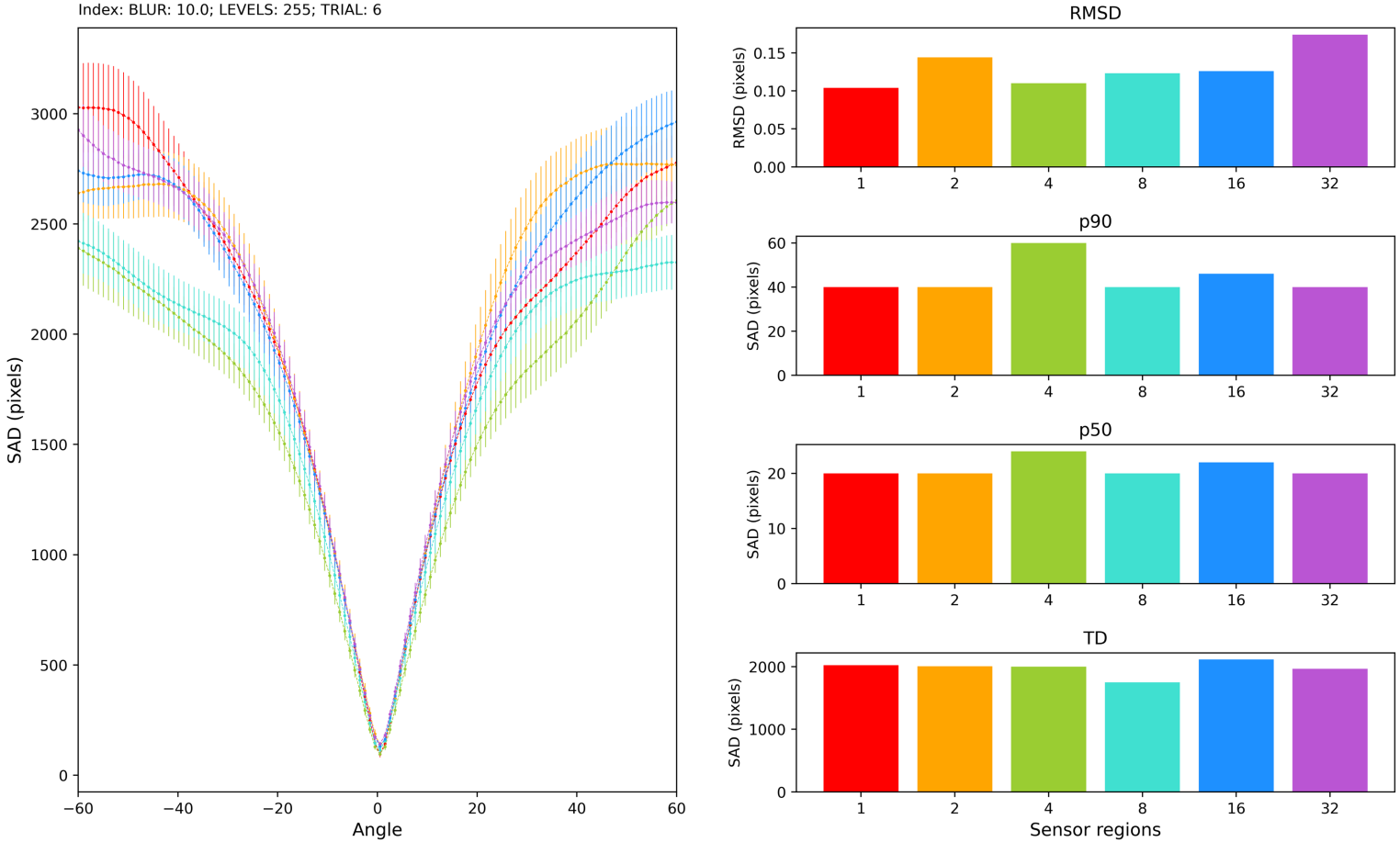




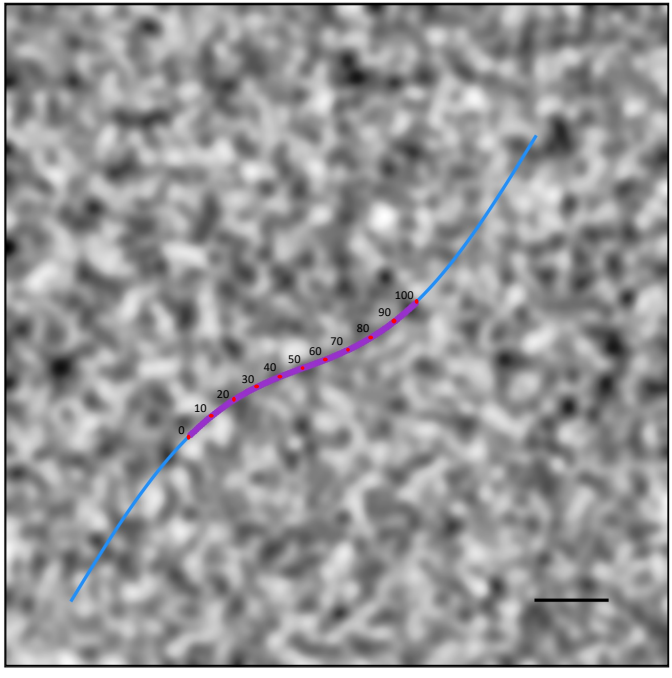


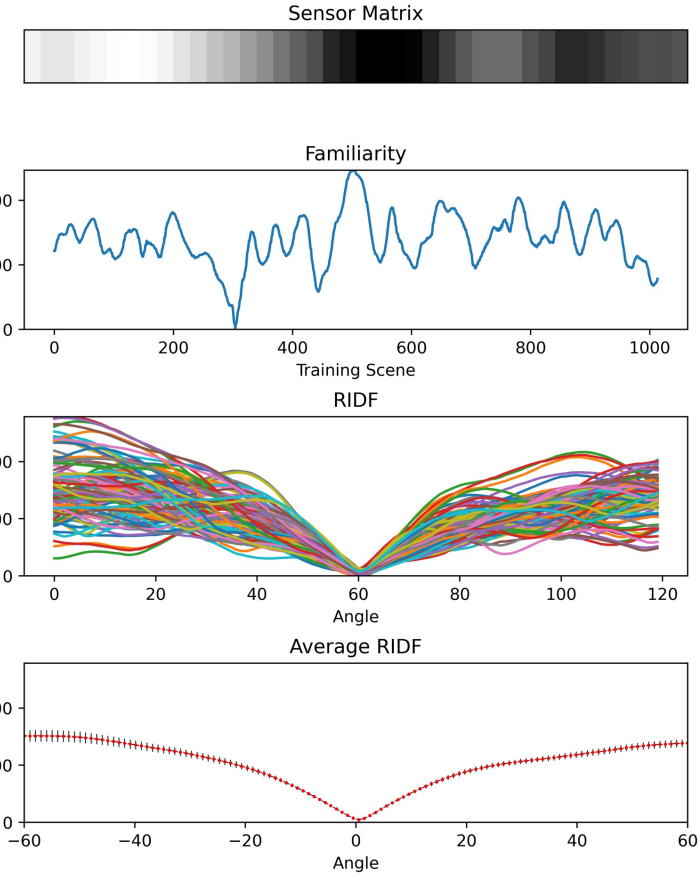
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 30.32; RMSD/dist: 0.076; TD: 1924; p90: 40; p50: 20; complete: 0


Index: BLUR: 10.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

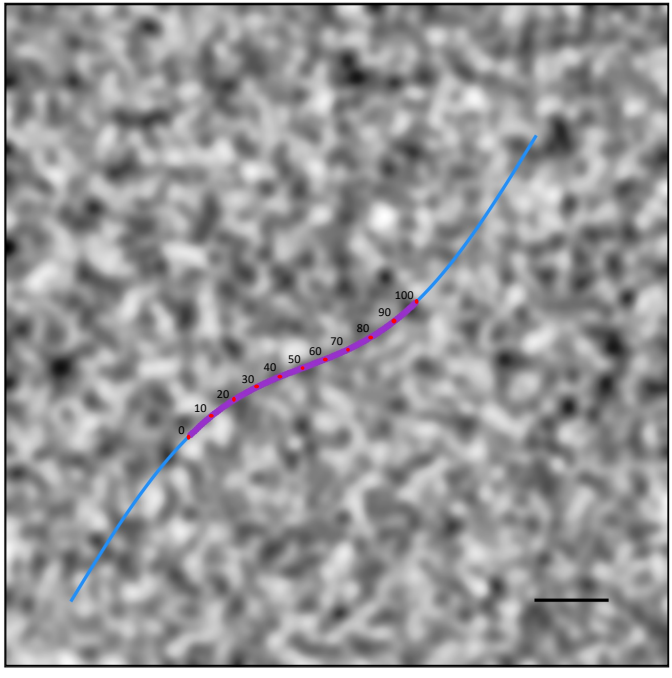


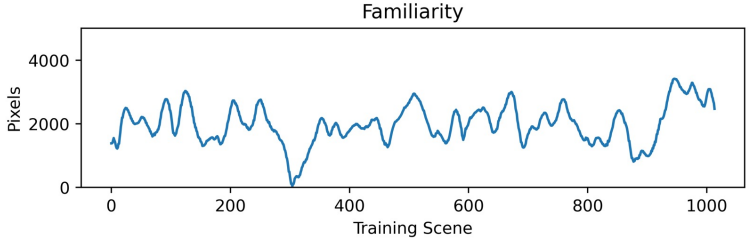


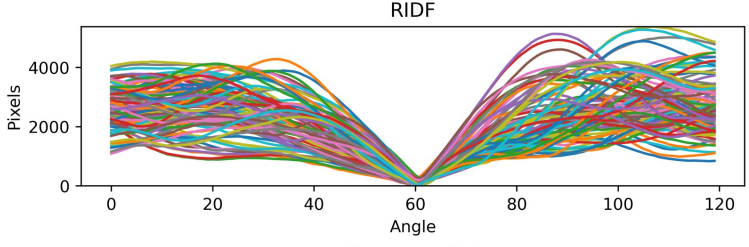
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

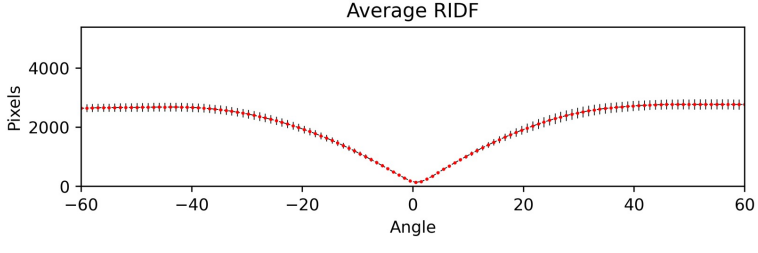
Navigation stats: RMSD error: 41.46; RMSD/dist: 0.104; TD: 2024; p90: 40; p50: 20; complete: 0

100%





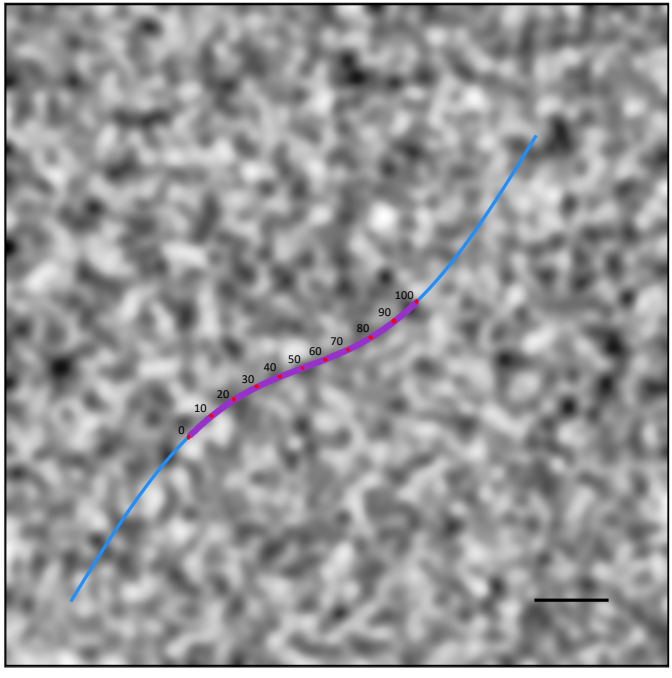


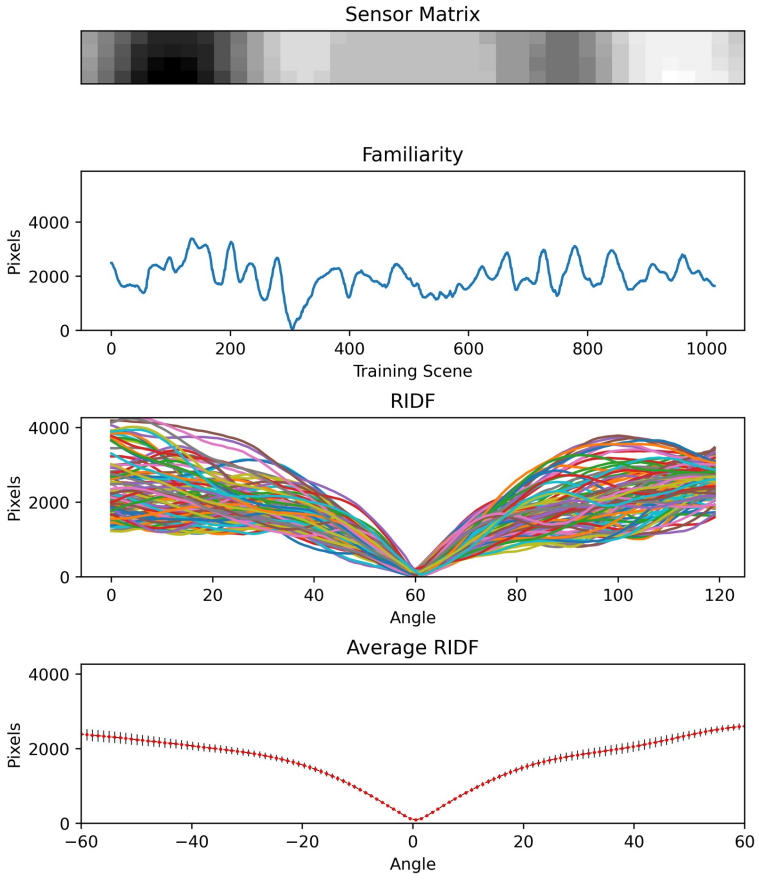


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 57.74; RMSD/dist: 0.144; TD: 2008; p90: 40; p50: 20; complete: 0

100%

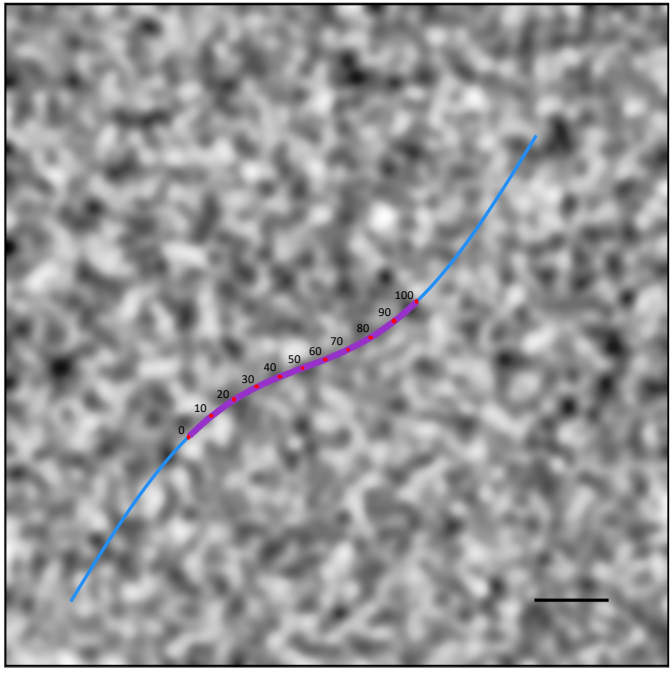


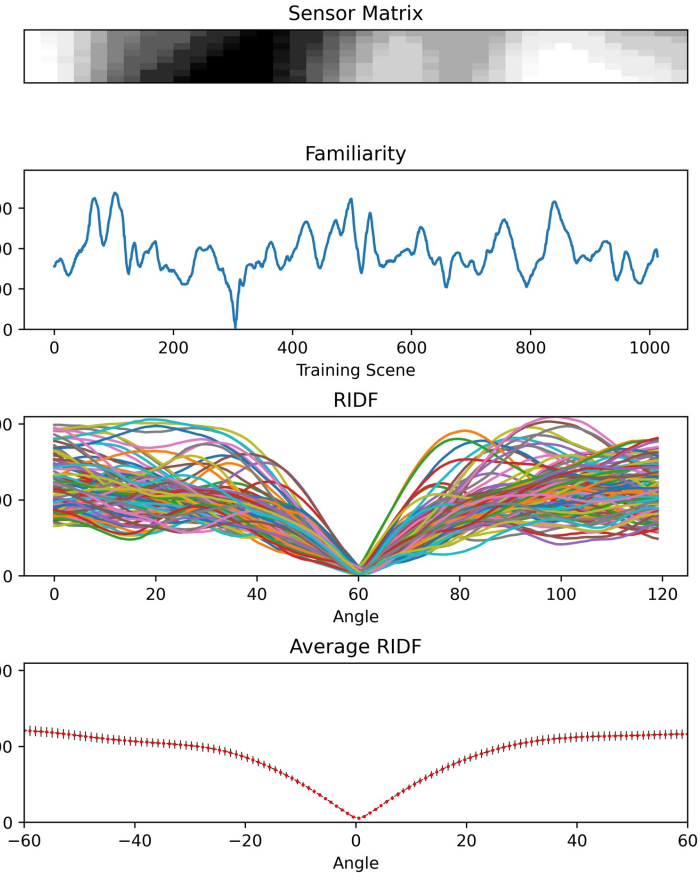


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 44.04; RMSD/dist: 0.110; TD: 1999; p90: 60; p50: 24; complete: 0

100%

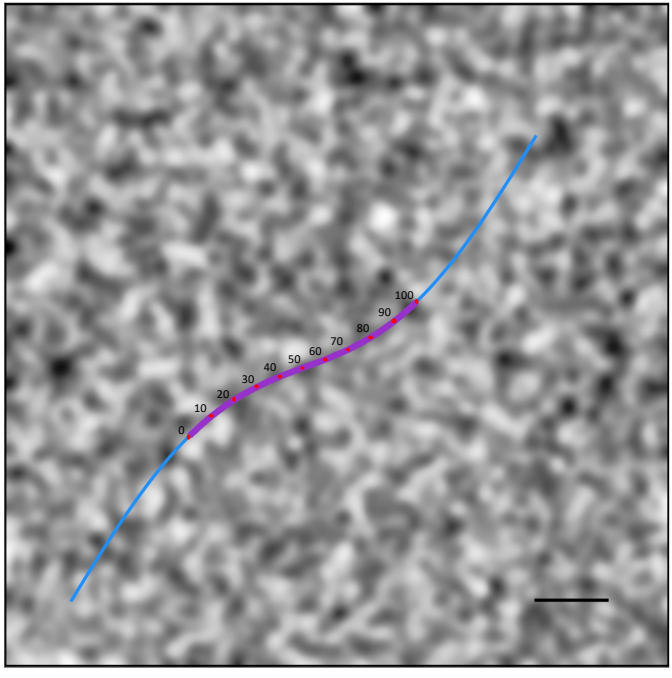


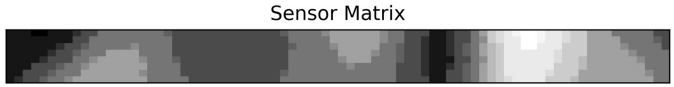


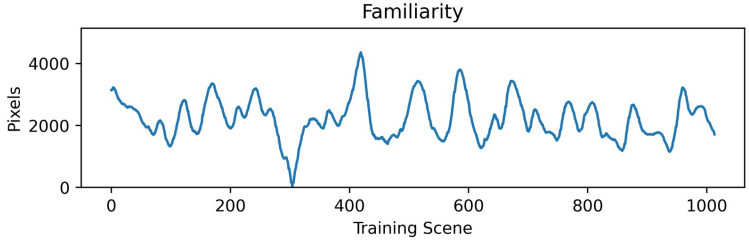
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

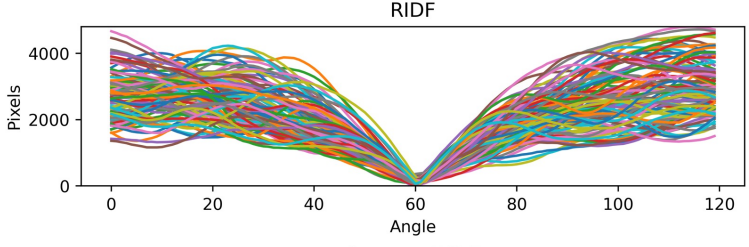
Navigation stats: RMSD error: 49.19; RMSD/dist: 0.123; TD: 1749; p90: 40; p50: 20; complete: 0

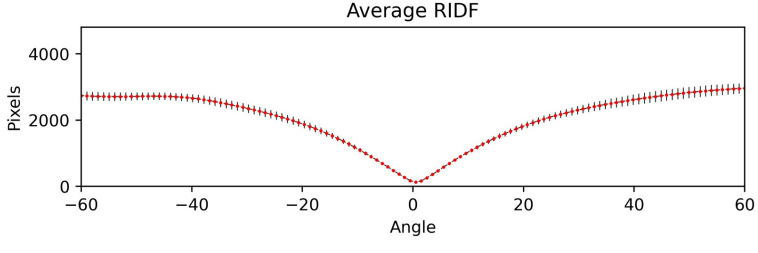
100%







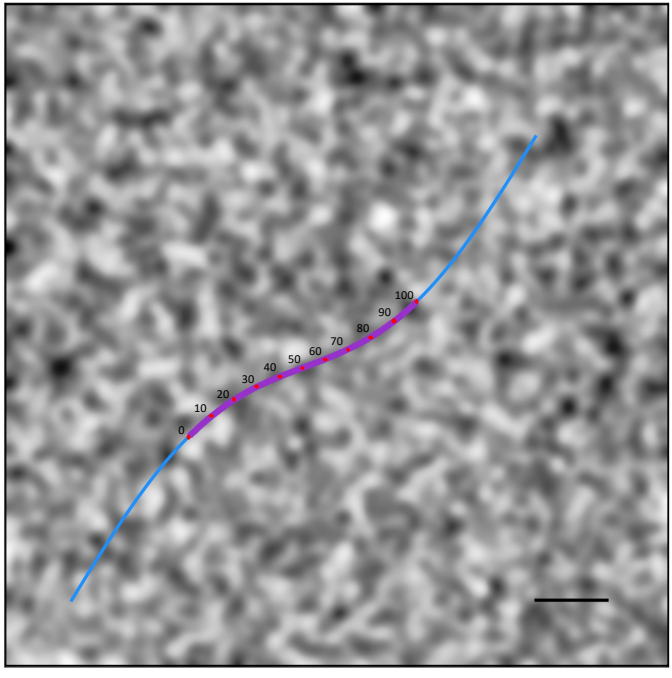


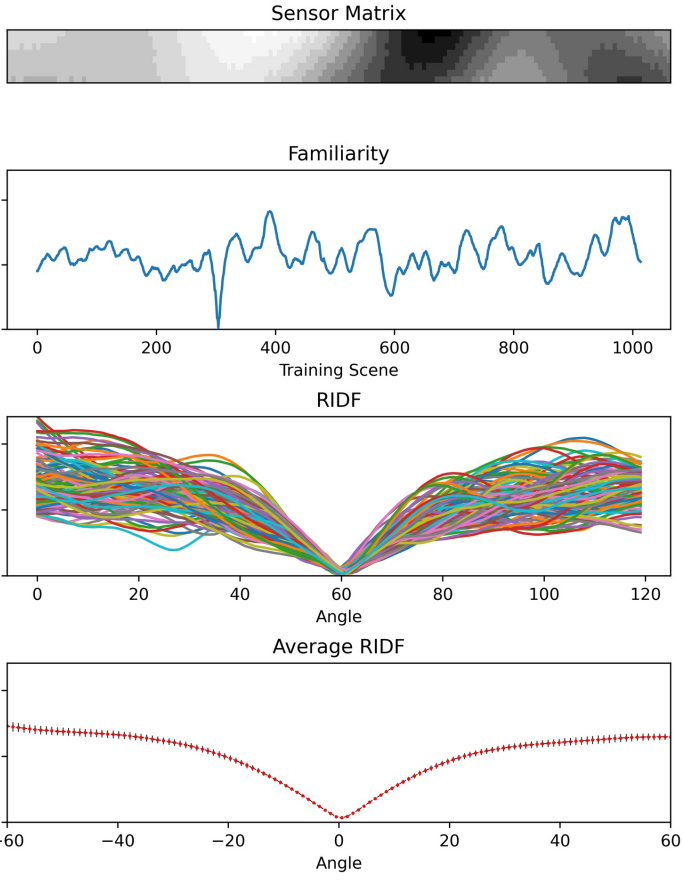


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 50.42; RMSD/dist: 0.126; TD: 2114; p90: 46; p50: 22; complete: 0

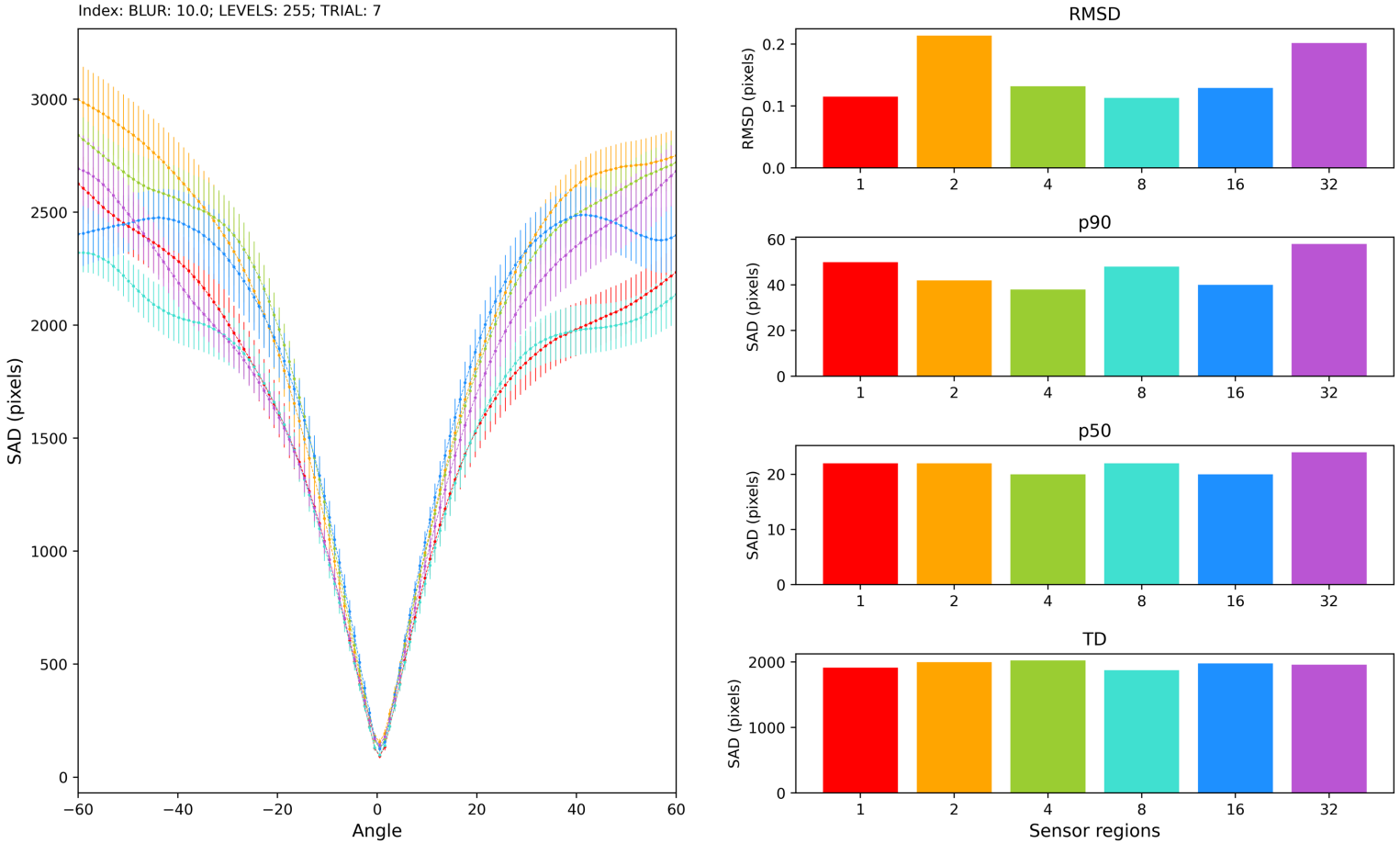
100%



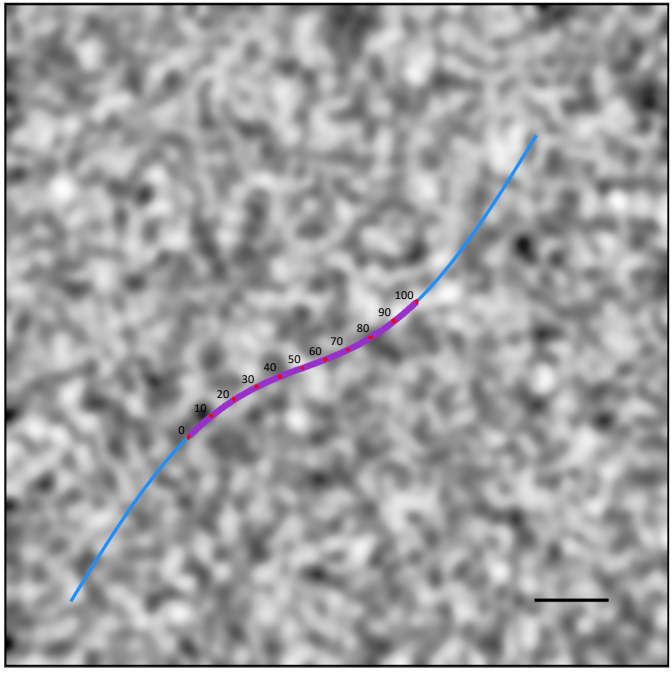


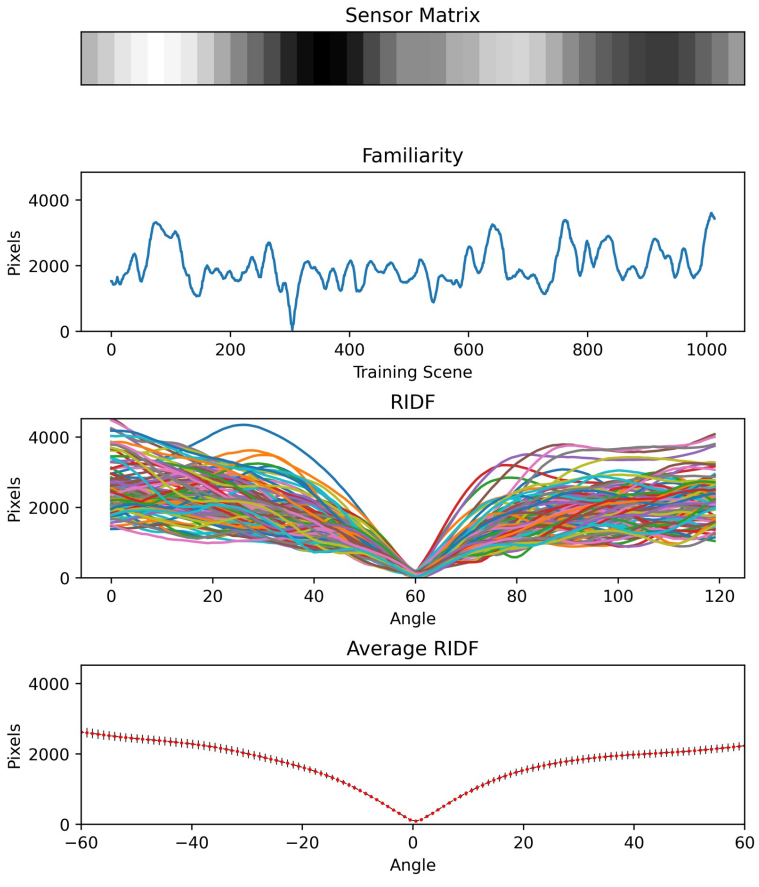
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 69.70; RMSD/dist: 0.174; TD: 1965; p90: 40; p50: 20; complete: 0


Index: BLUR: 10.0; LEVELS: 255; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

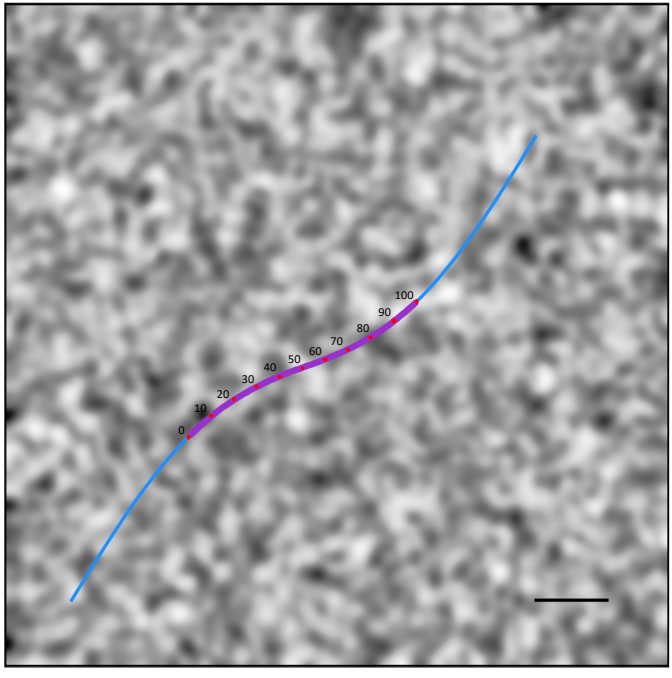


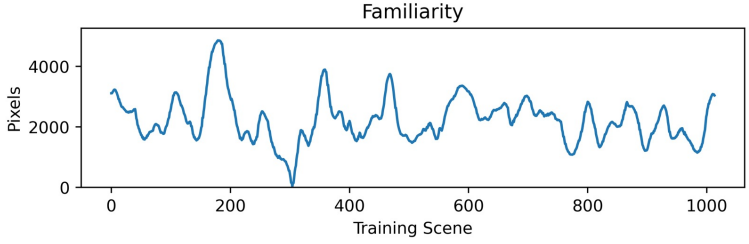


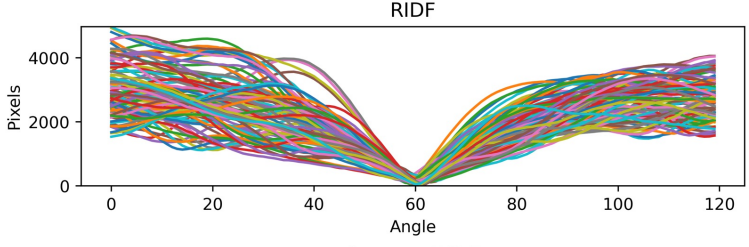
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

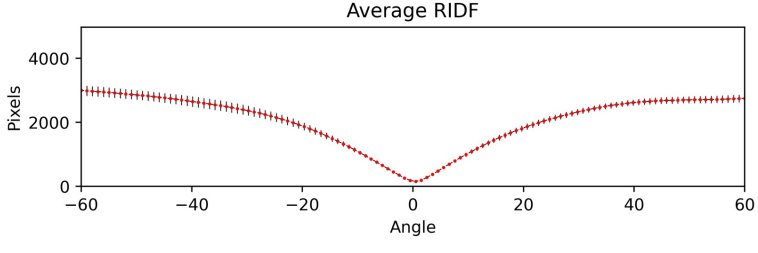
Navigation stats: RMSD error: 45.96; RMSD/dist: 0.115; TD: 1910; p90: 50; p50: 22; complete: 0

100%





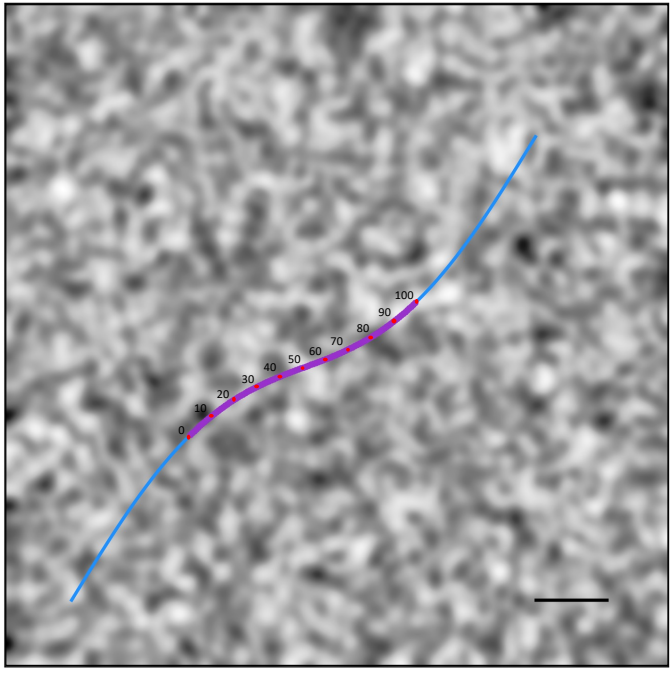


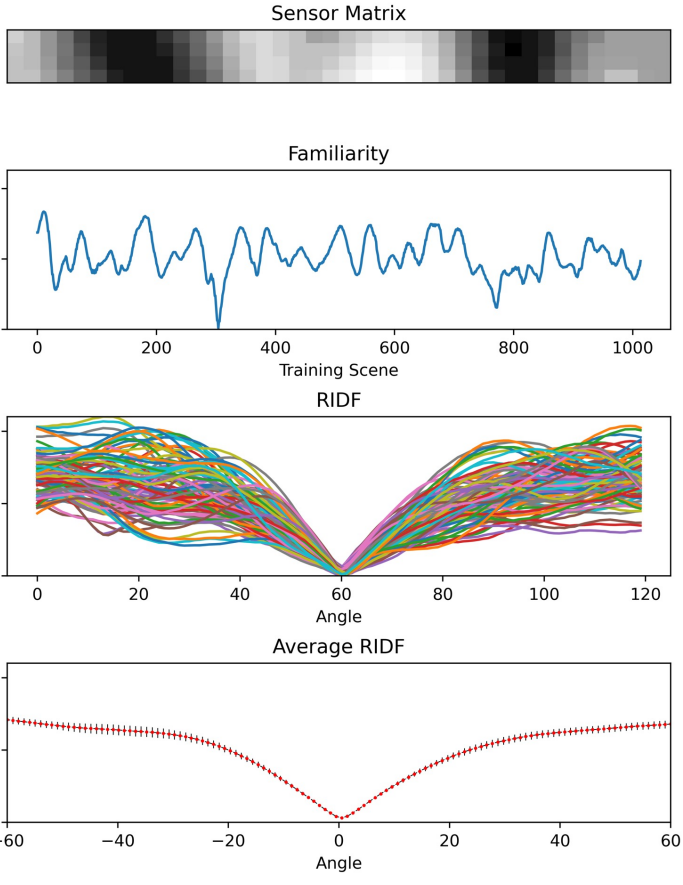


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 85.75; RMSD/dist: 0.214; TD: 1996; p90: 42; p50: 22; complete: 0

100%

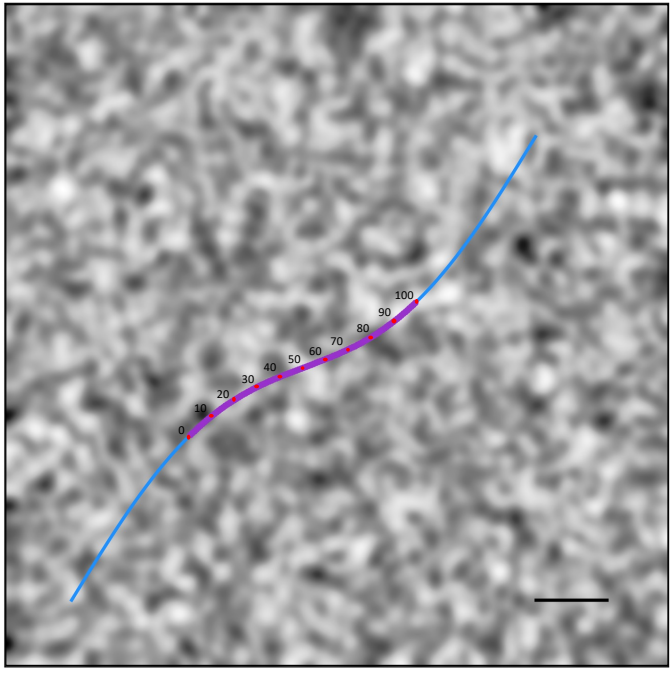


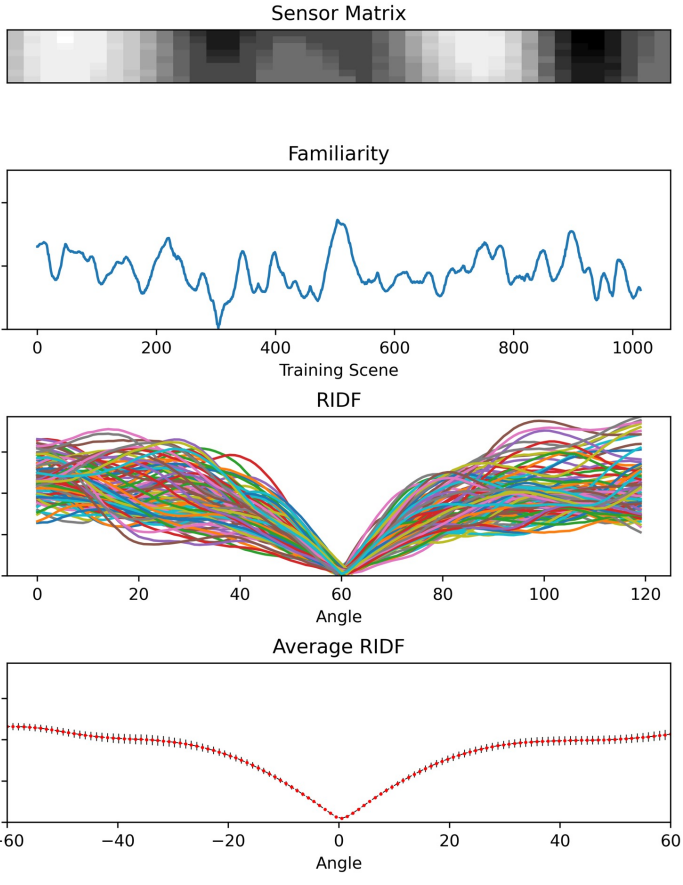


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 52.67; RMSD/dist: 0.132; TD: 2020; p90: 38; p50: 20; complete: 0

100%

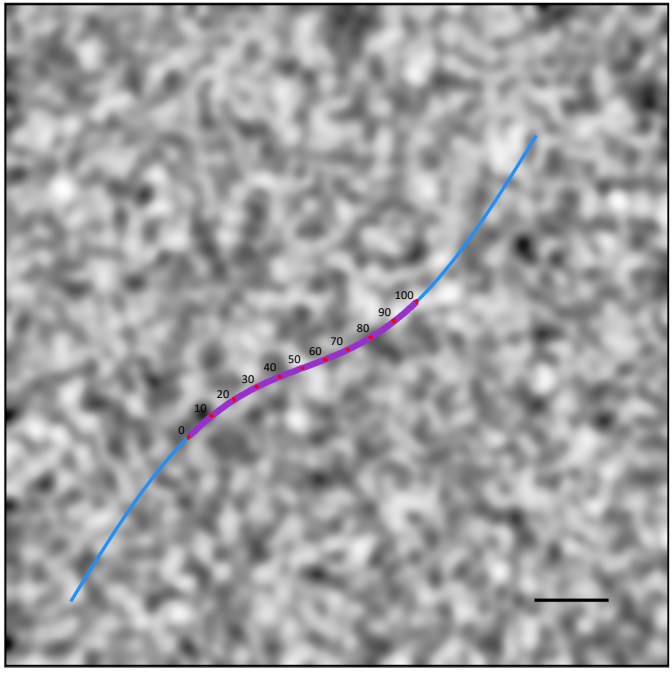


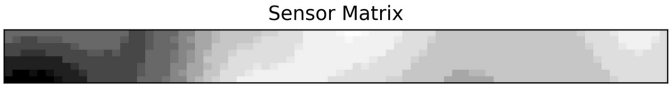


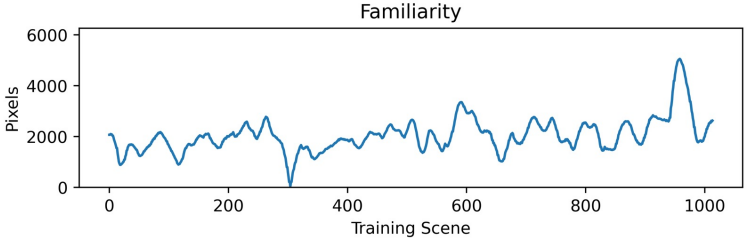
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

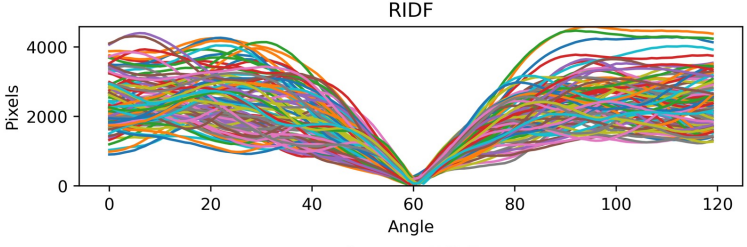
Navigation stats: RMSD error: 45.20; RMSD/dist: 0.113; TD: 1874; p90: 48; p50: 22; complete: 0

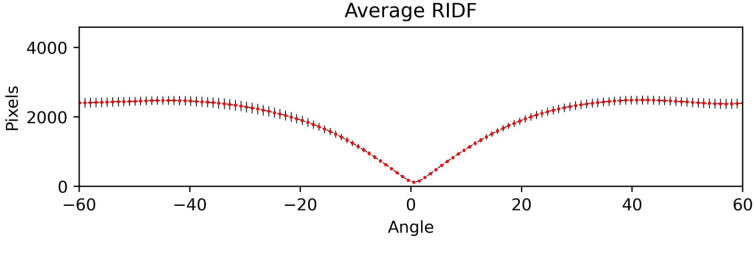
100%







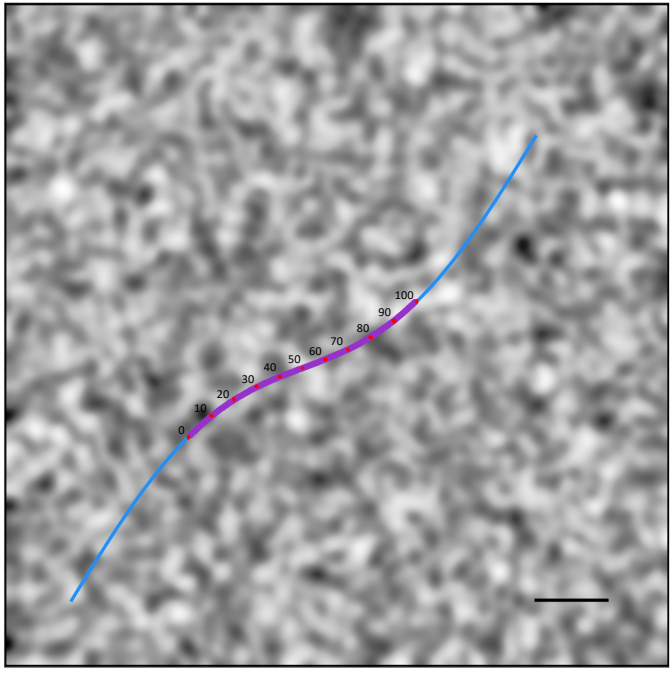


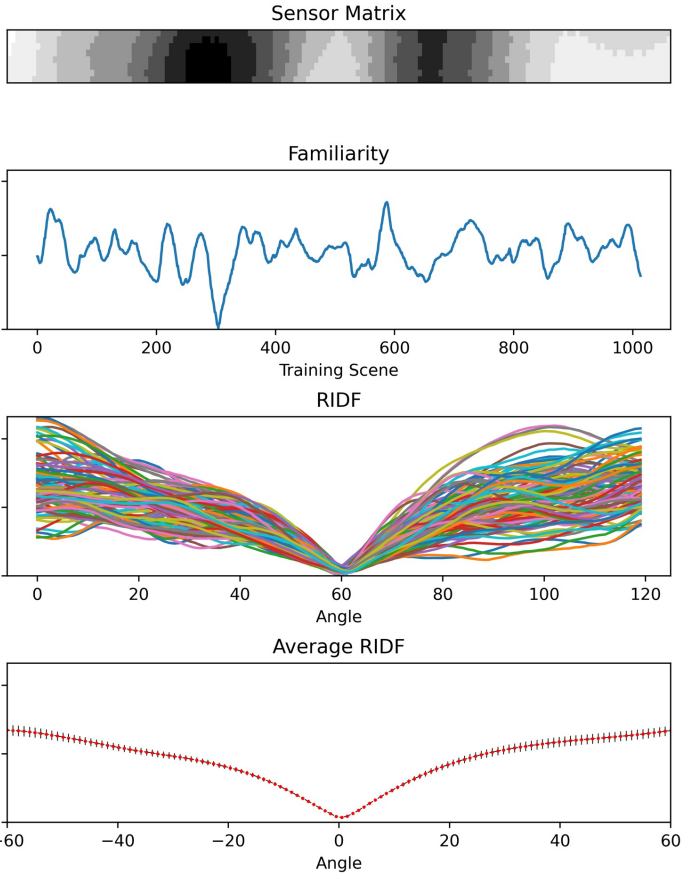


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 51.40; RMSD/dist: 0.129; TD: 1977; p90: 40; p50: 20; complete: 0

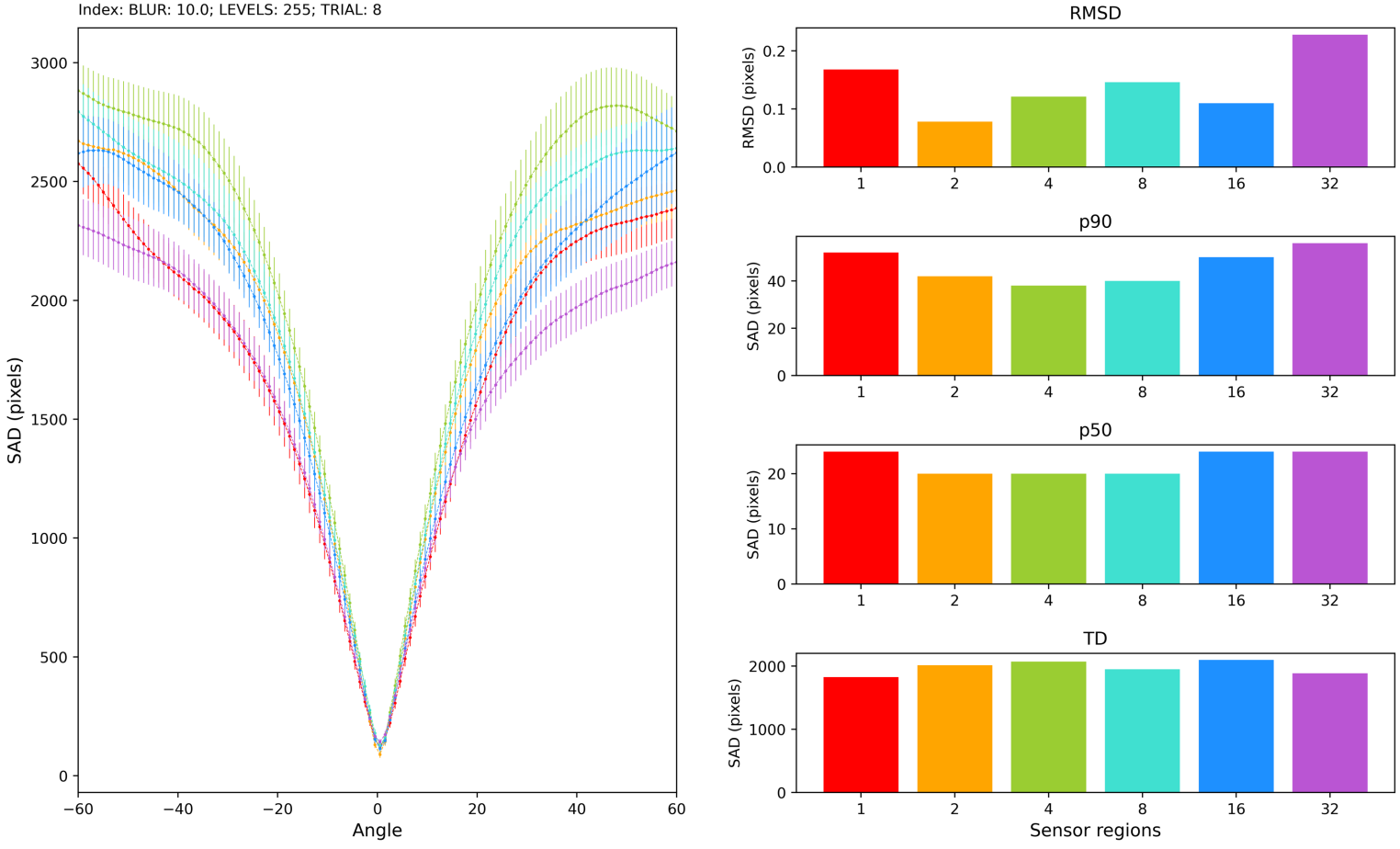
100%



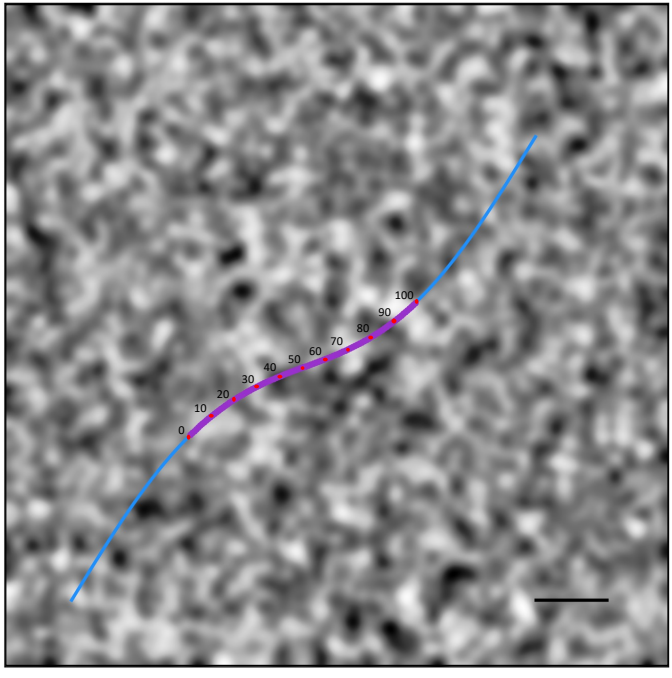


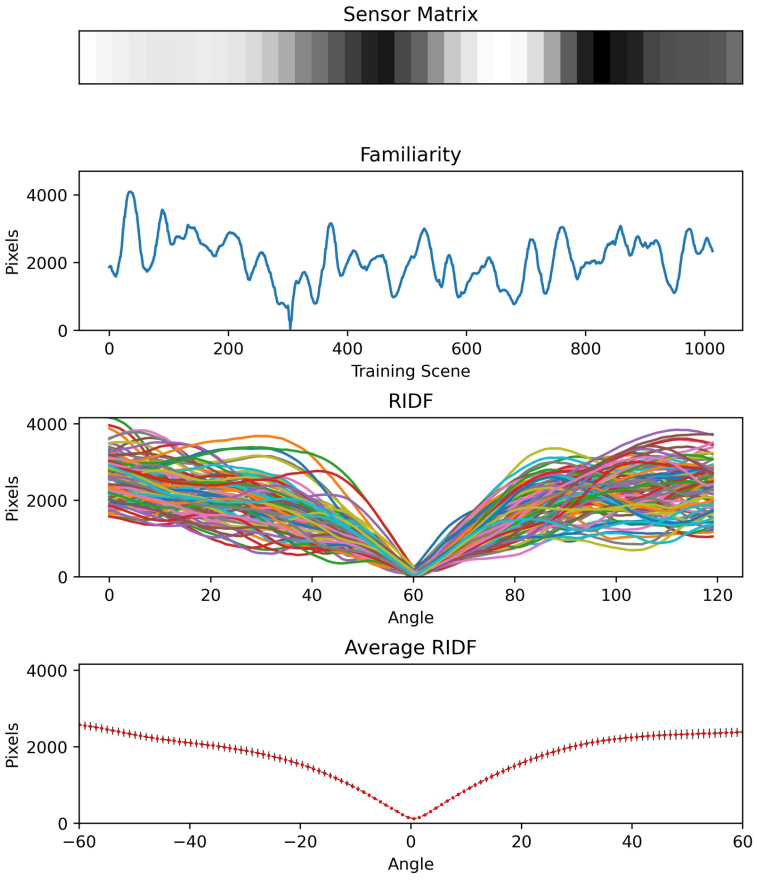
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 80.71; RMSD/dist: 0.202; TD: 1958; p90: 58; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 255; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

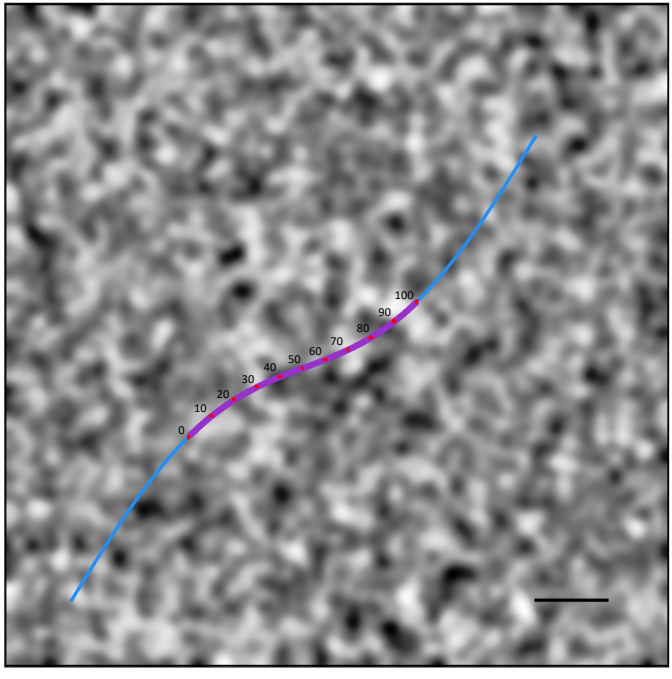


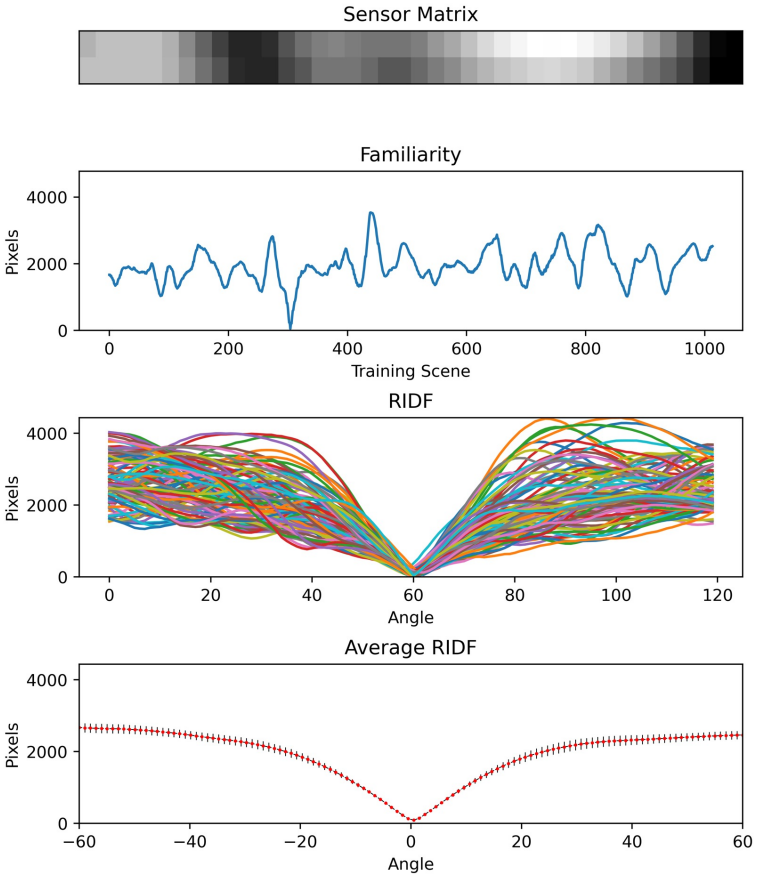


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 67.35; RMSD/dist: 0.168; TD: 1826; p90: 52; p50: 24; complete: 0

100%

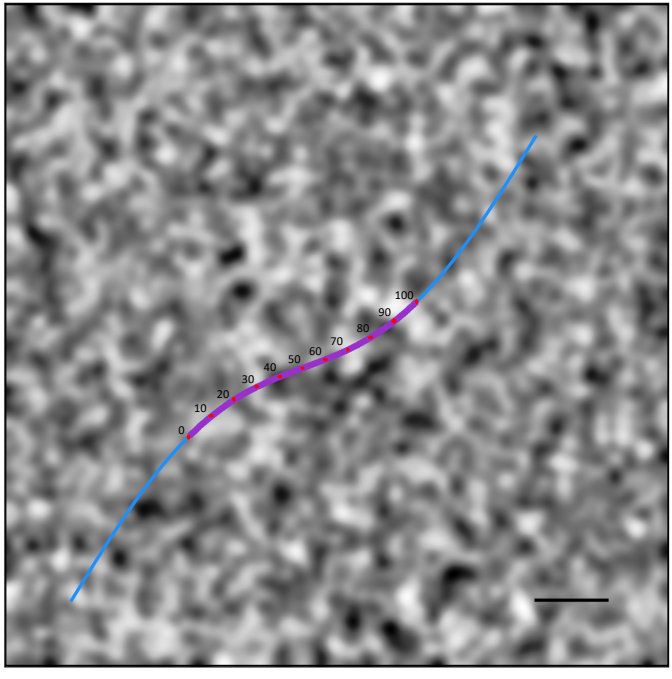


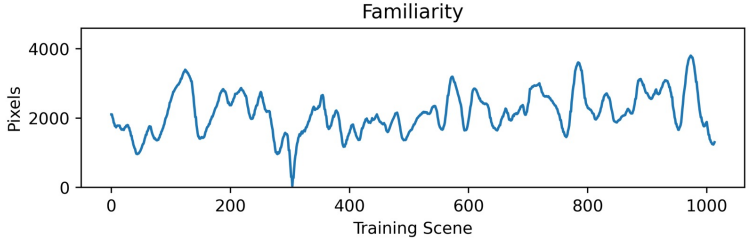


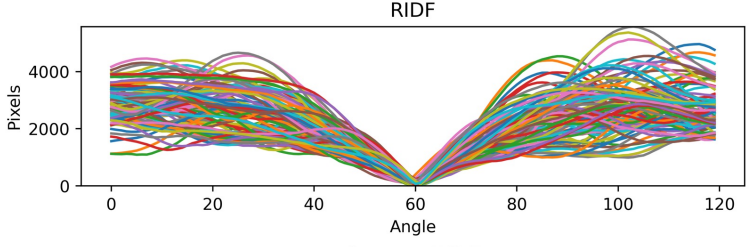
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

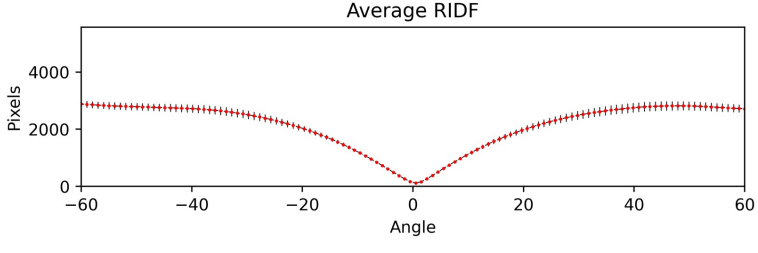
Navigation stats: RMSD error: 31.21; RMSD/dist: 0.078; TD: 2014; p90: 42; p50: 20; complete: 0

100%





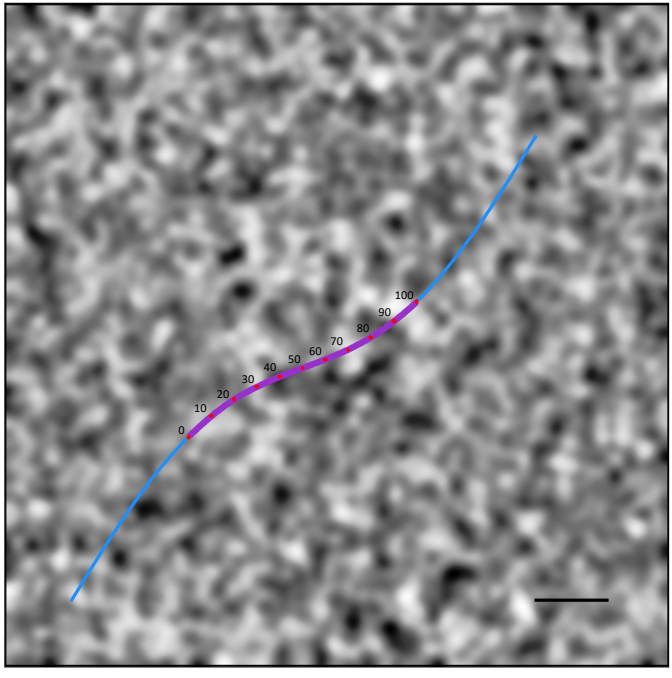


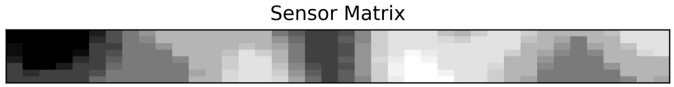


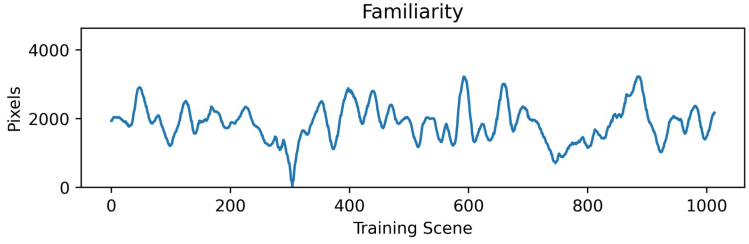
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

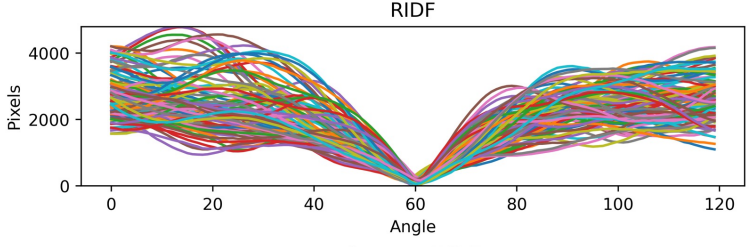
Navigation stats: RMSD error: 48.25; RMSD/dist: 0.121; TD: 2071; p90: 38; p50: 20; complete: 0

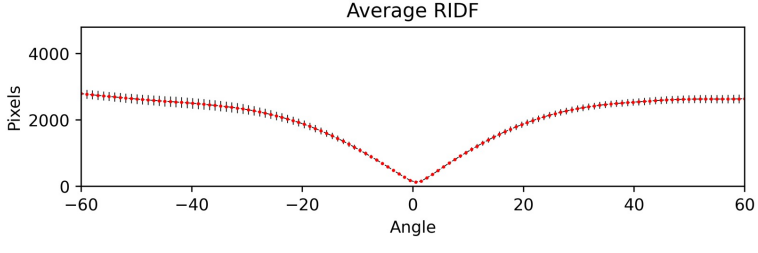
100%







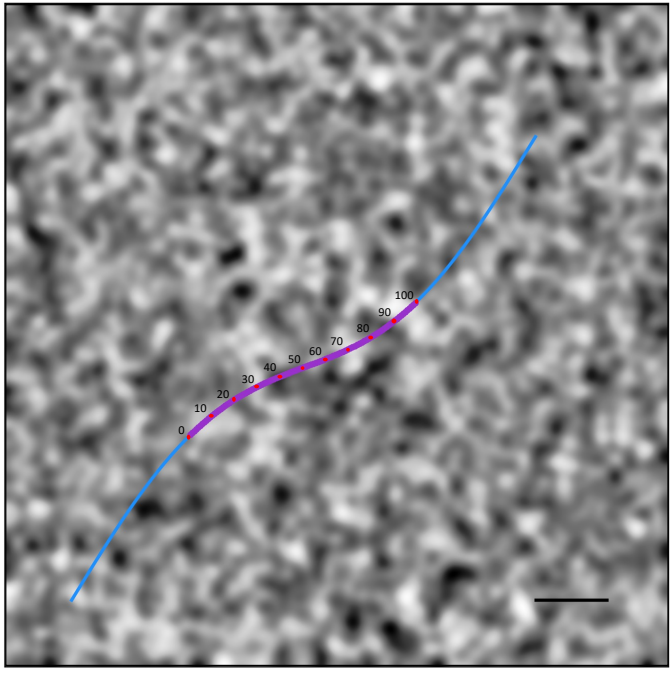


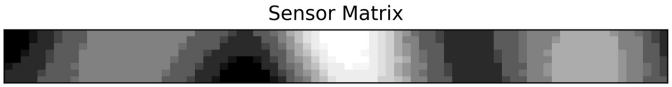


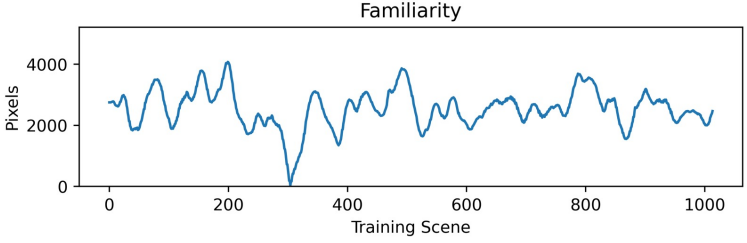
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

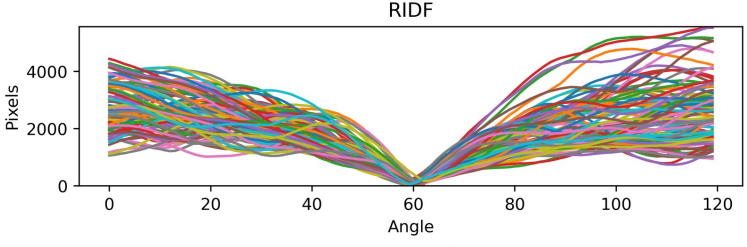
Navigation stats: RMSD error: 58.60; RMSD/dist: 0.146; TD: 1950; p90: 40; p50: 20; complete: 0

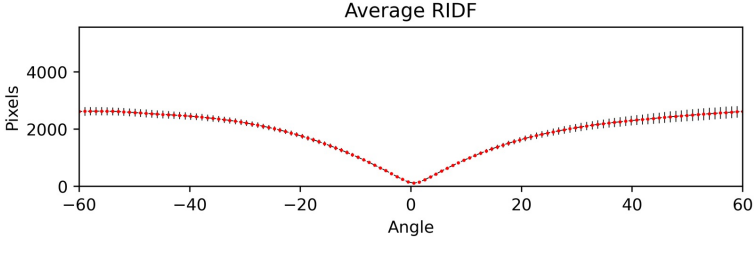
100%







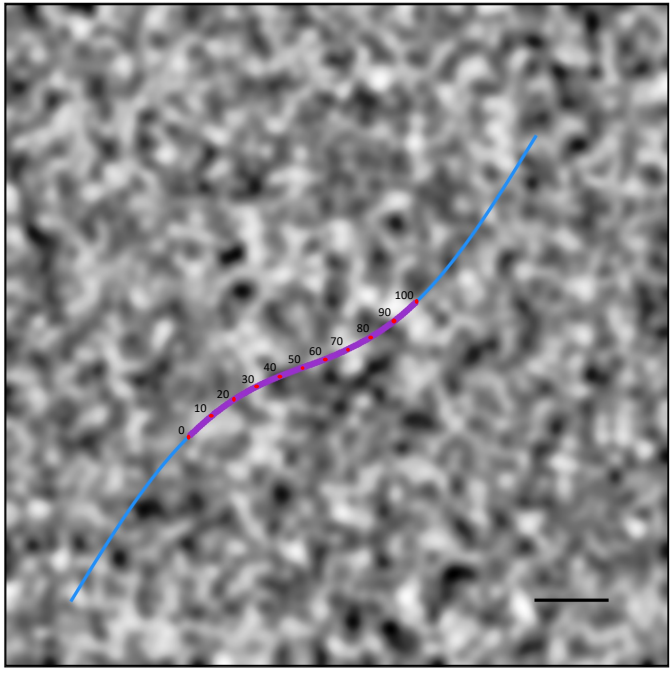


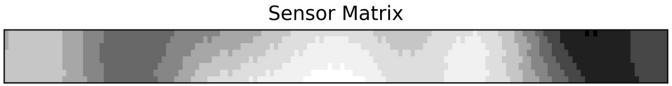


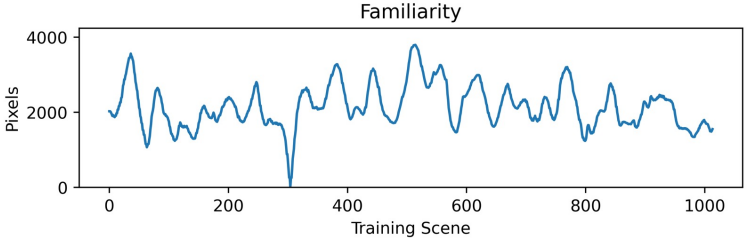
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

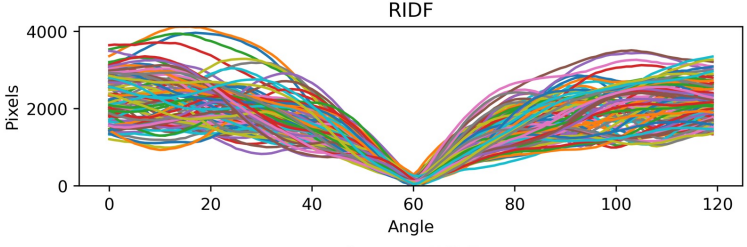
Navigation stats: RMSD error: 44.08; RMSD/dist: 0.110; TD: 2097; p90: 50; p50: 24; complete: 0

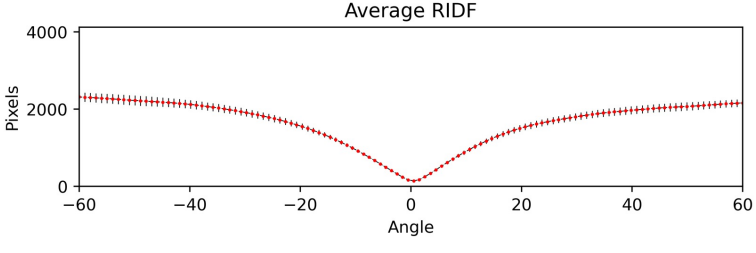
100%





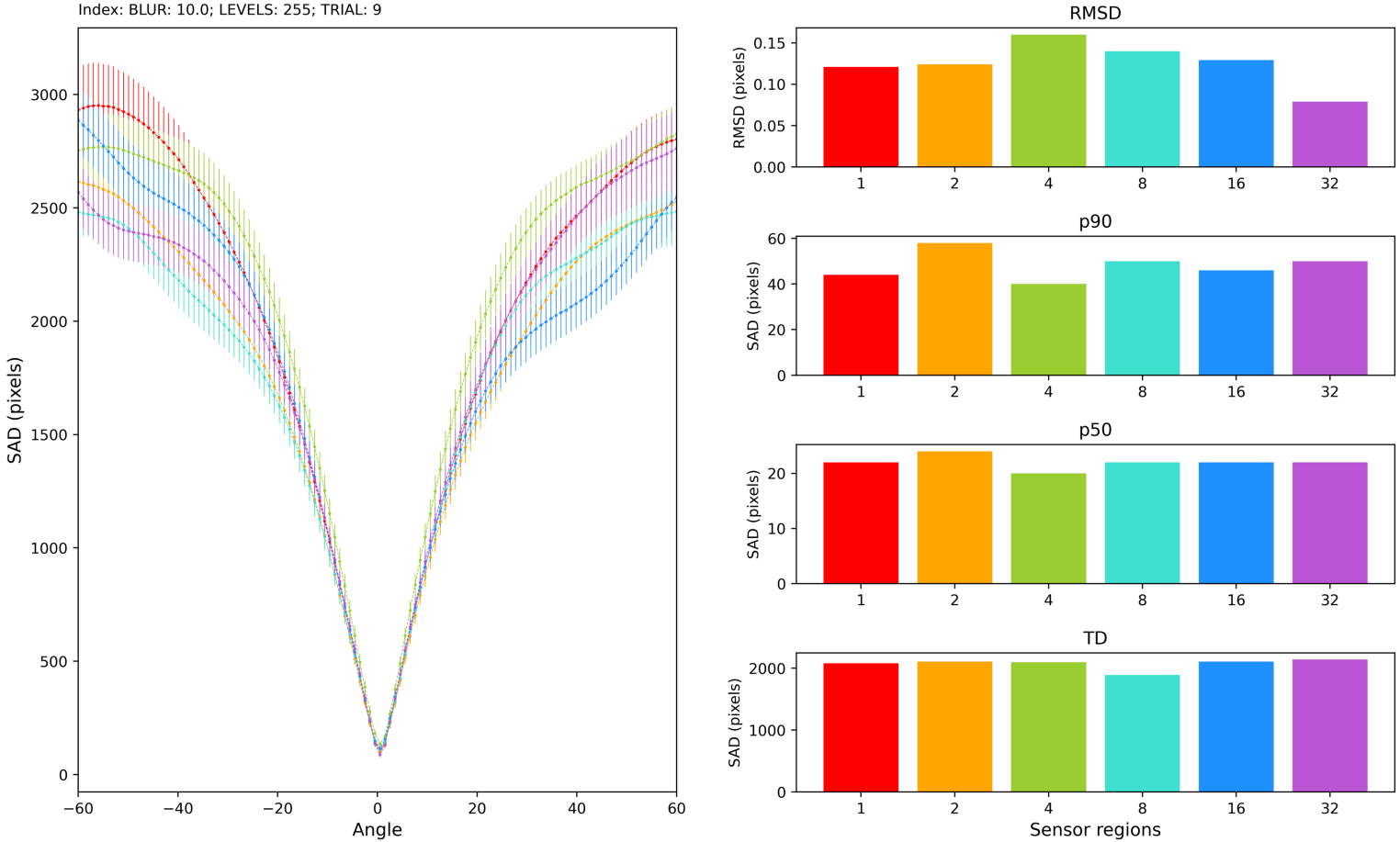




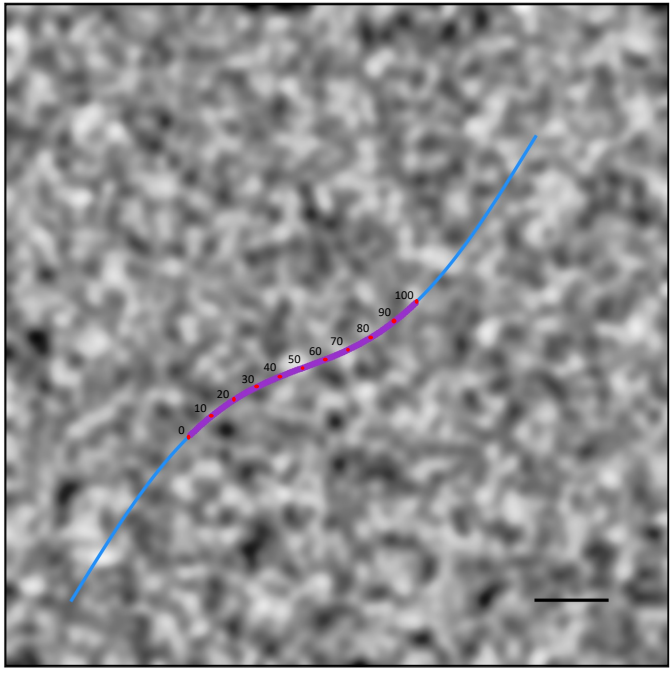


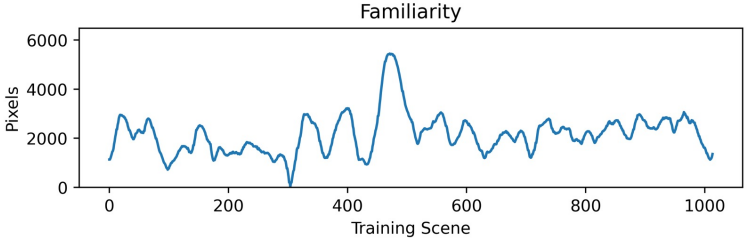
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

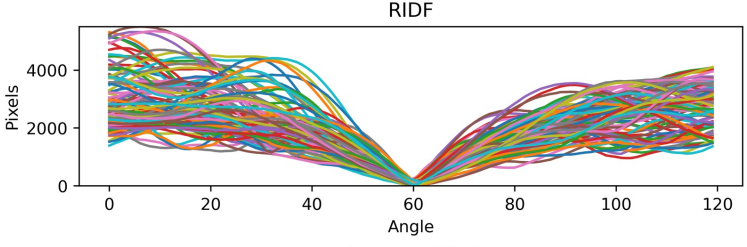
Navigation stats: RMSD error: 91.21; RMSD/dist: 0.228; TD: 1887; p90: 56; p50: 24; complete: 0

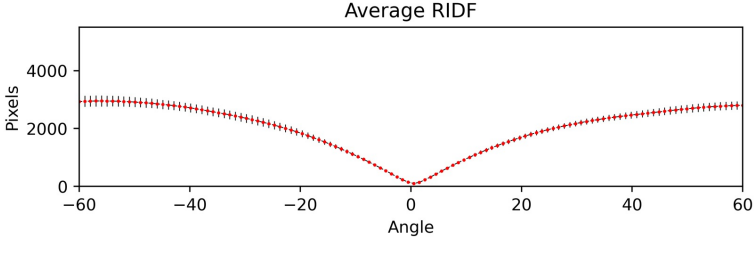

Index: BLUR: 10.0; LEVELS: 255; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%





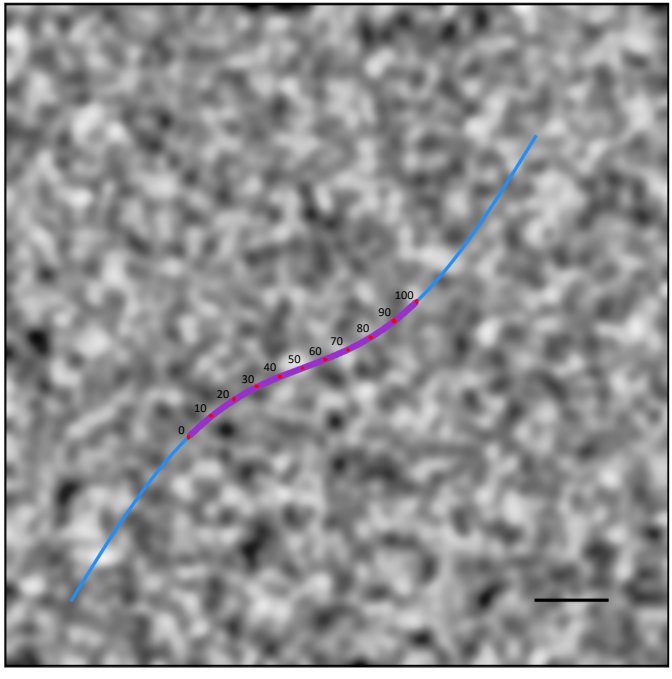


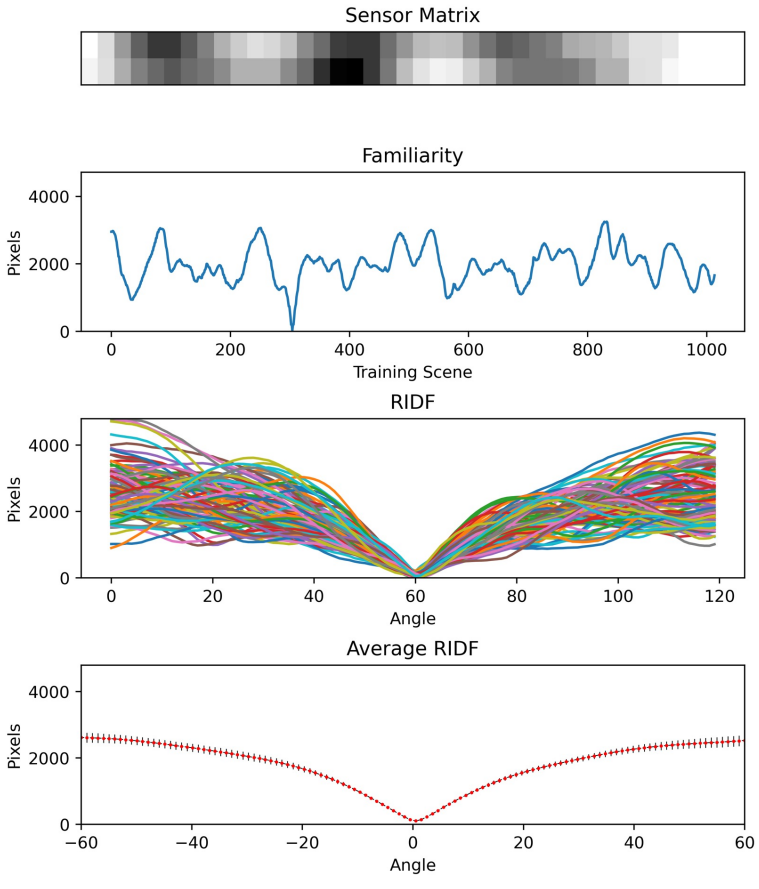


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 48.46; RMSD/dist: 0.121; TD: 2079; p90: 44; p50: 22; complete: 0

100%

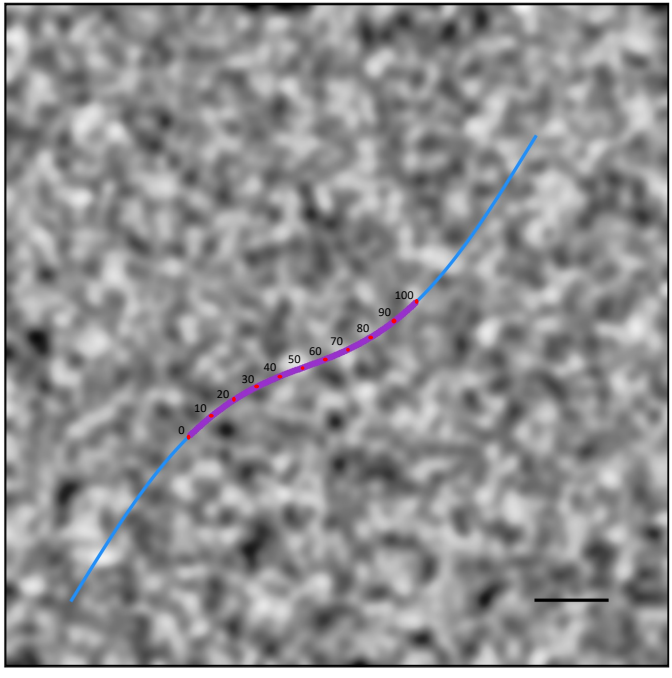


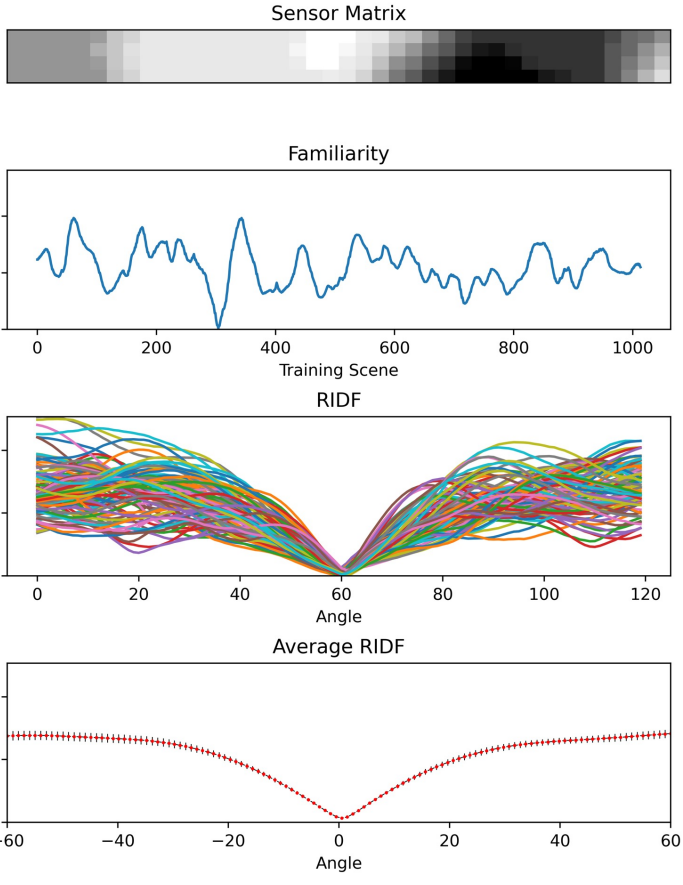


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 49.43; RMSD/dist: 0.124; TD: 2108; p90: 58; p50: 24; complete: 0

100%

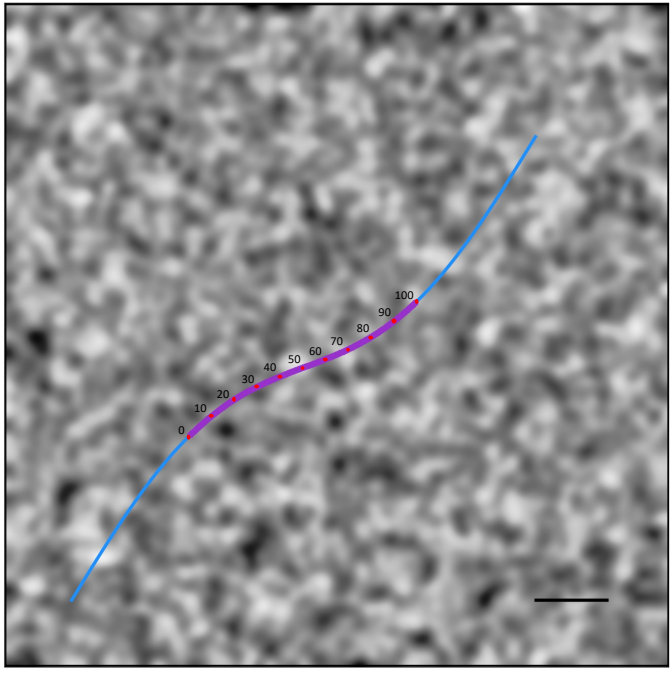


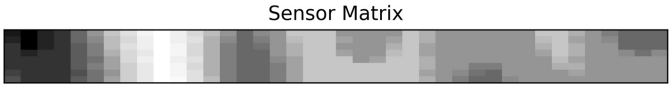


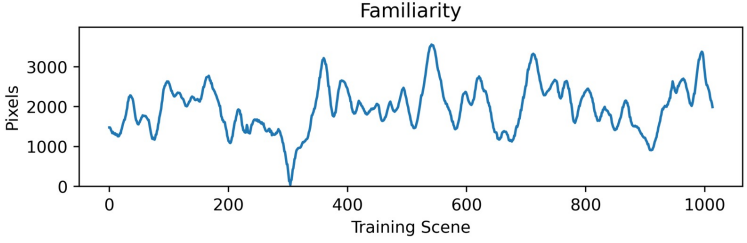
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

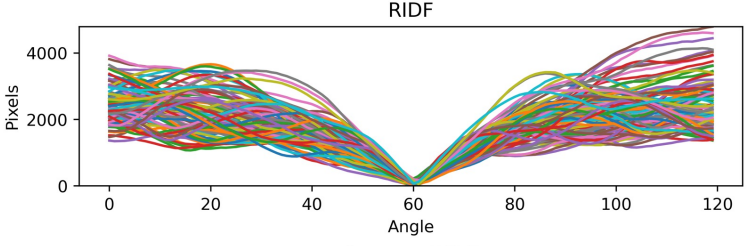
Navigation stats: RMSD error: 63.88; RMSD/dist: 0.160; TD: 2096; p90: 40; p50: 20; complete: 0

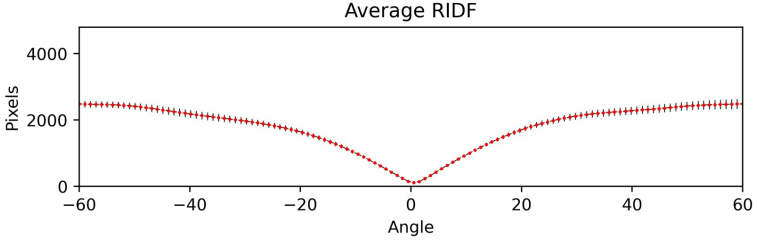
100%







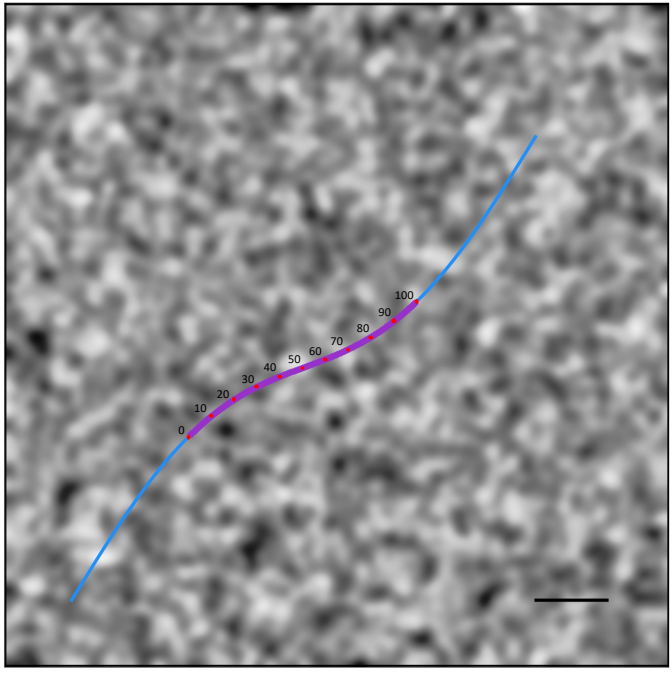


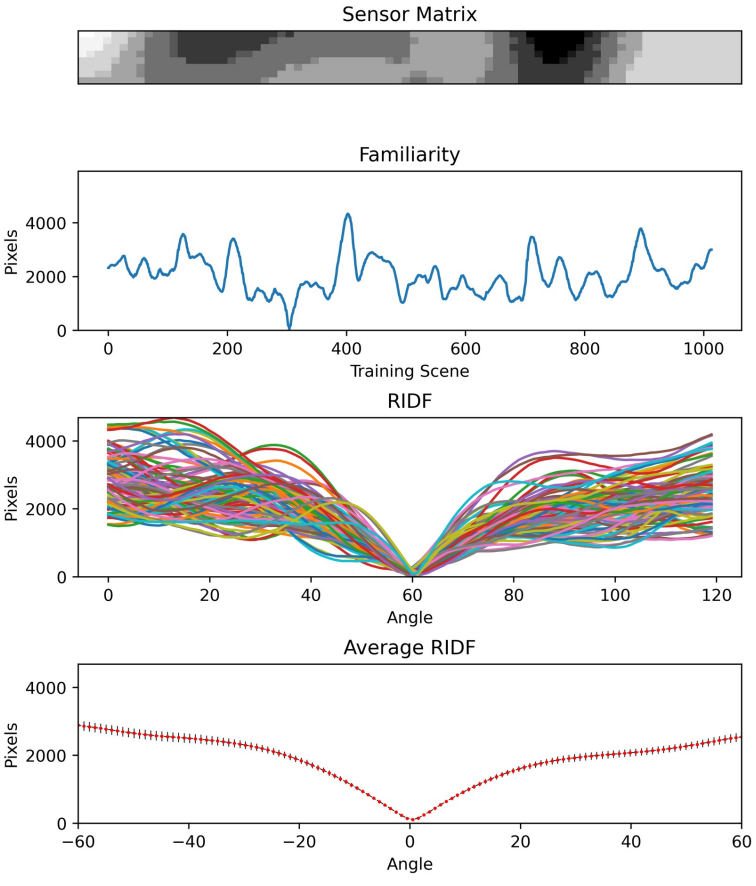


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 55.88; RMSD/dist: 0.140; TD: 1892; p90: 50; p50: 22; complete: 0

100%

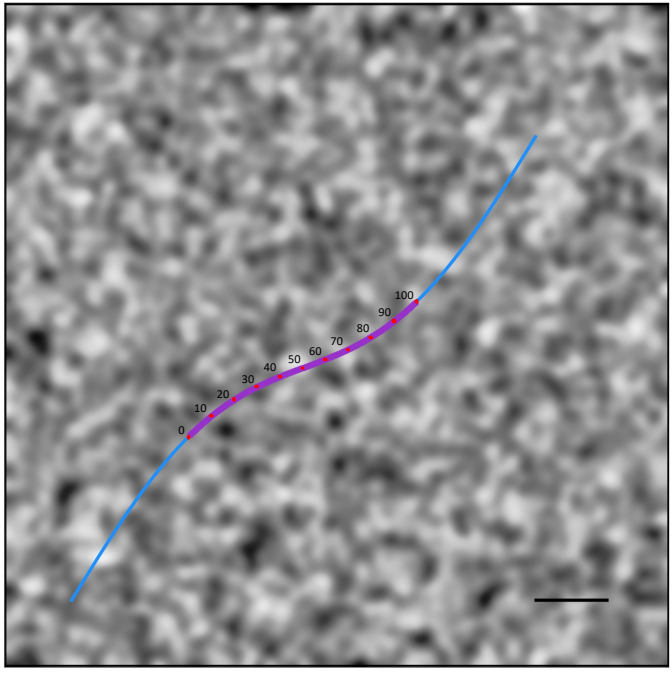


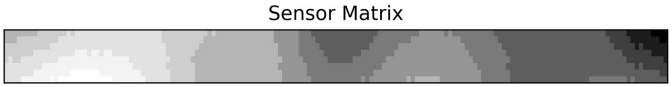


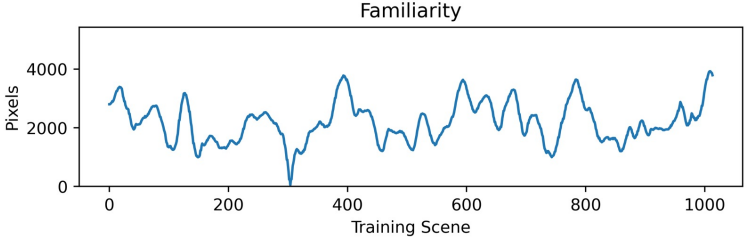
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

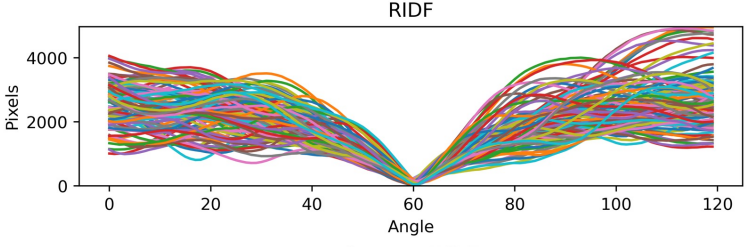
Navigation stats: RMSD error: 51.57; RMSD/dist: 0.129; TD: 2106; p90: 46; p50: 22; complete: 0

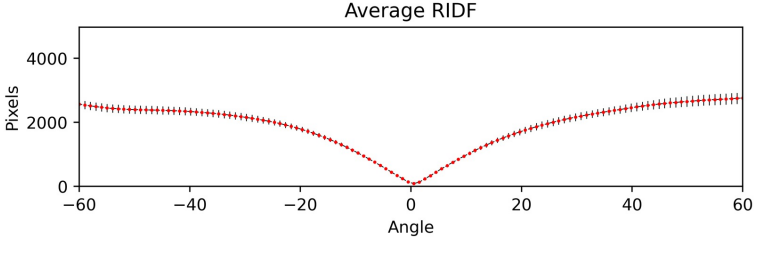
100%





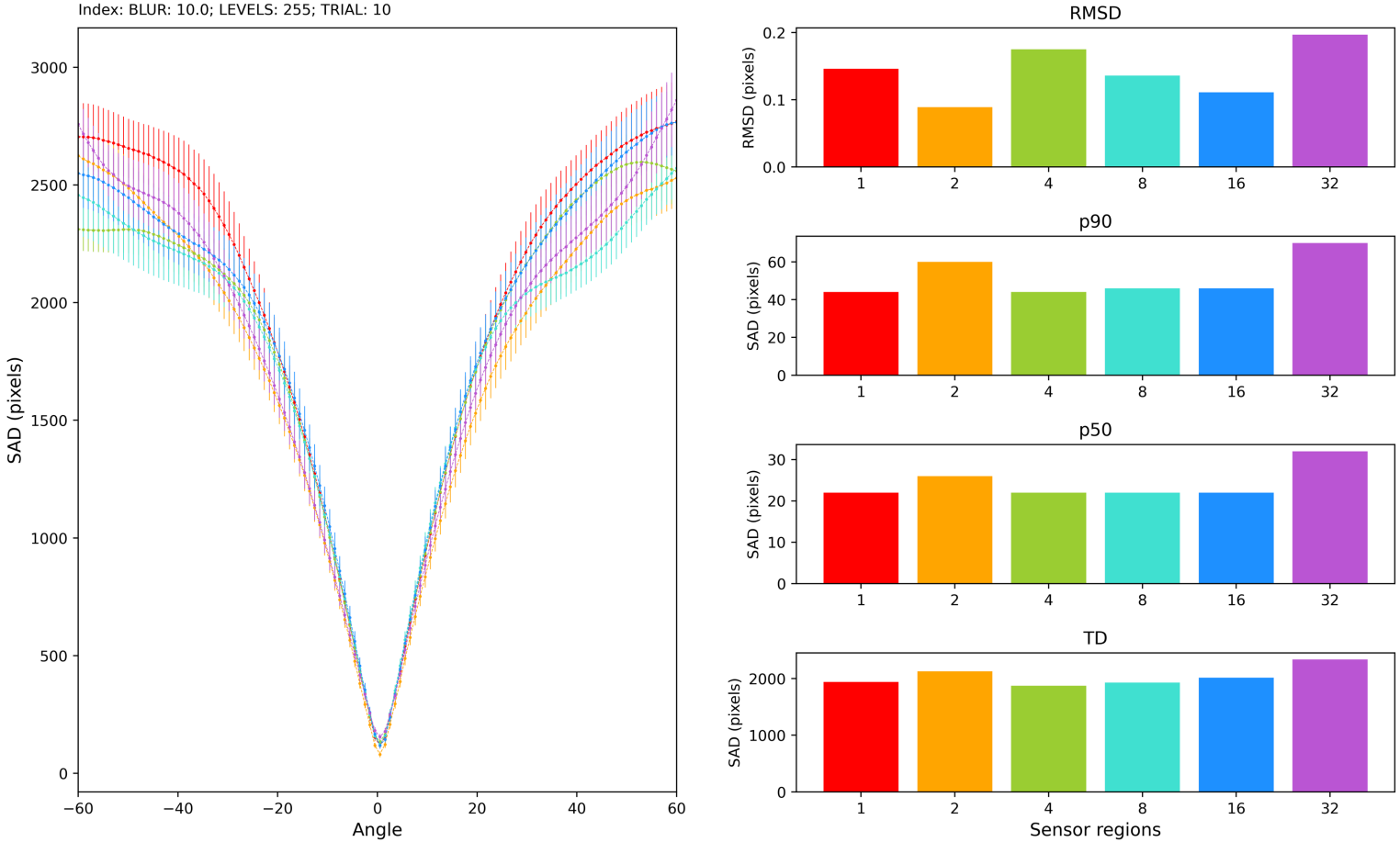




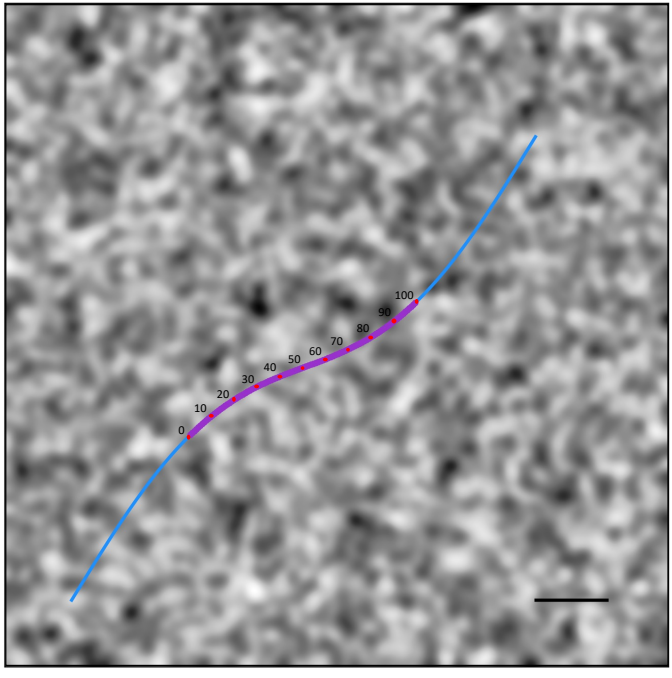


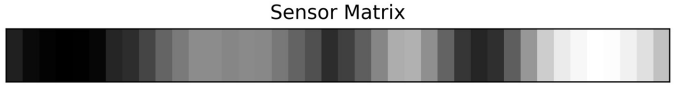
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

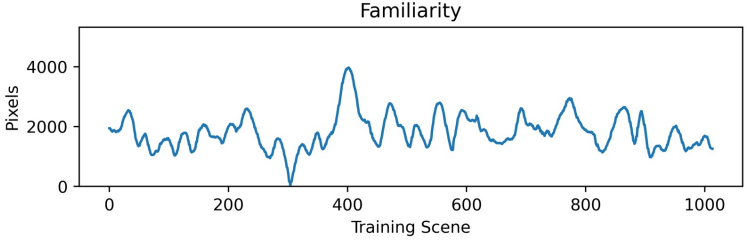
Navigation stats: RMSD error: 31.69; RMSD/dist: 0.079; TD: 2139; p90: 50; p50: 22; complete: 0

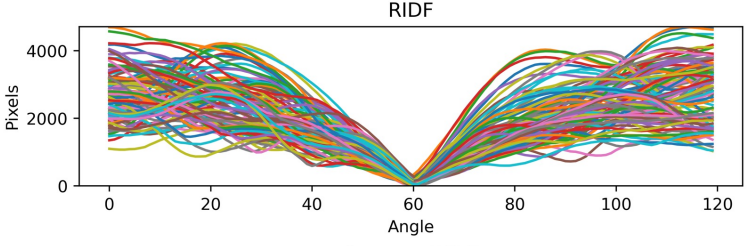

Index: BLUR: 10.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

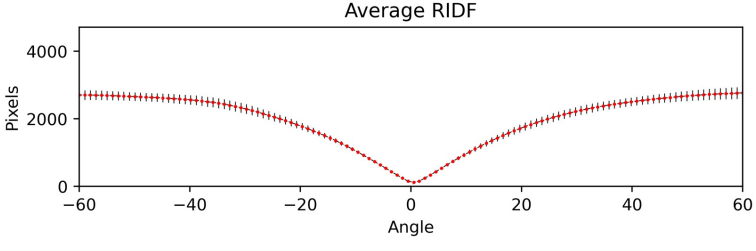
100%







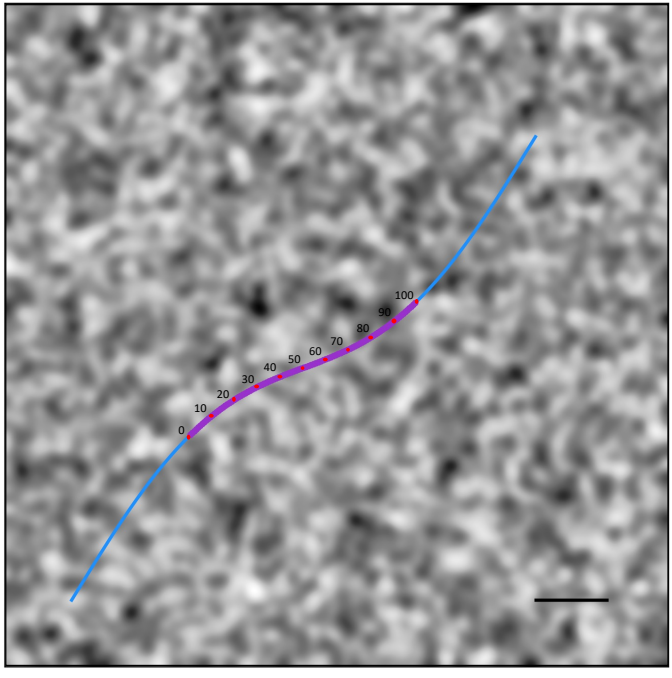


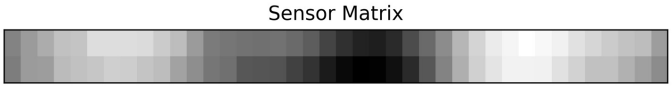


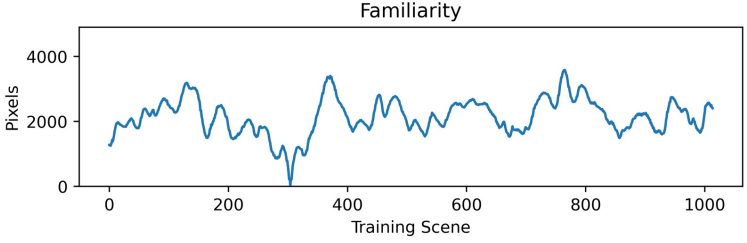
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

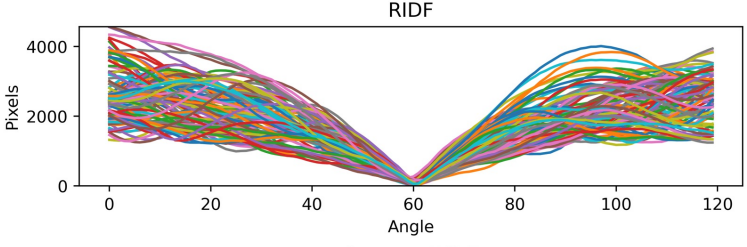
Navigation stats: RMSD error: 58.51; RMSD/dist: 0.146; TD: 1938; p90: 44; p50: 22; complete: 0

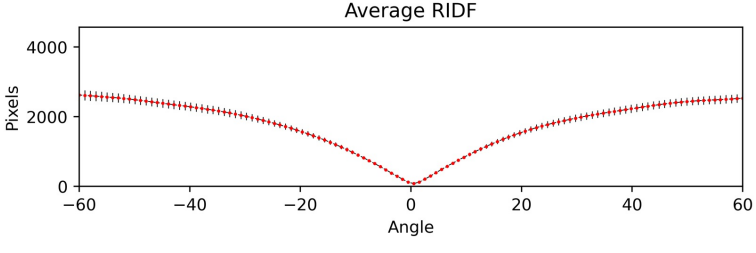
100%







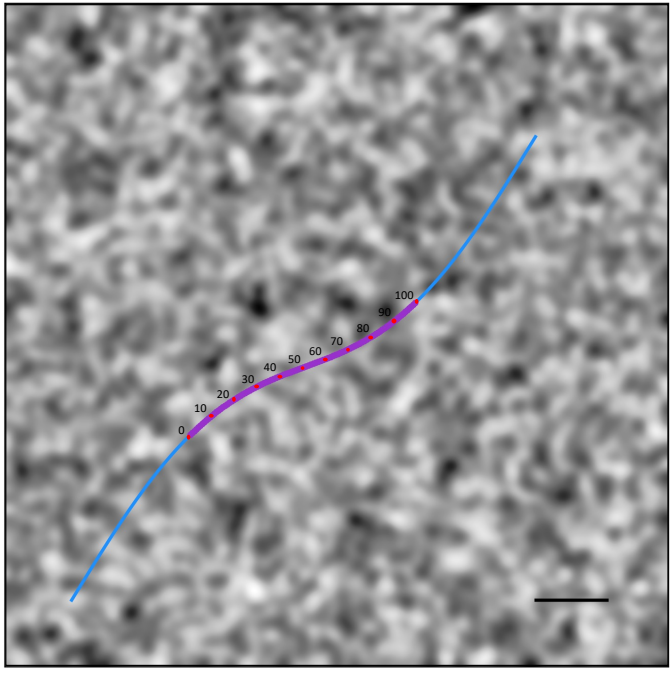


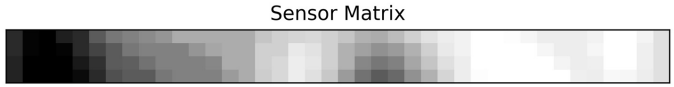


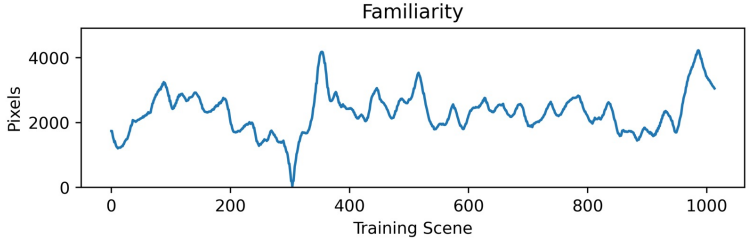
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

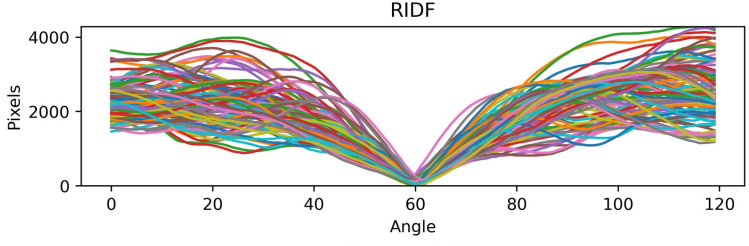
Navigation stats: RMSD error: 35.61; RMSD/dist: 0.089; TD: 2126; p90: 60; p50: 26; complete: 0

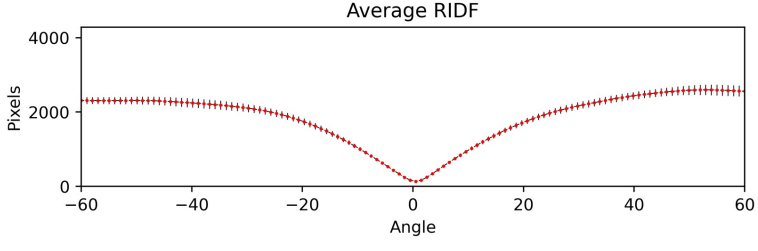
100%







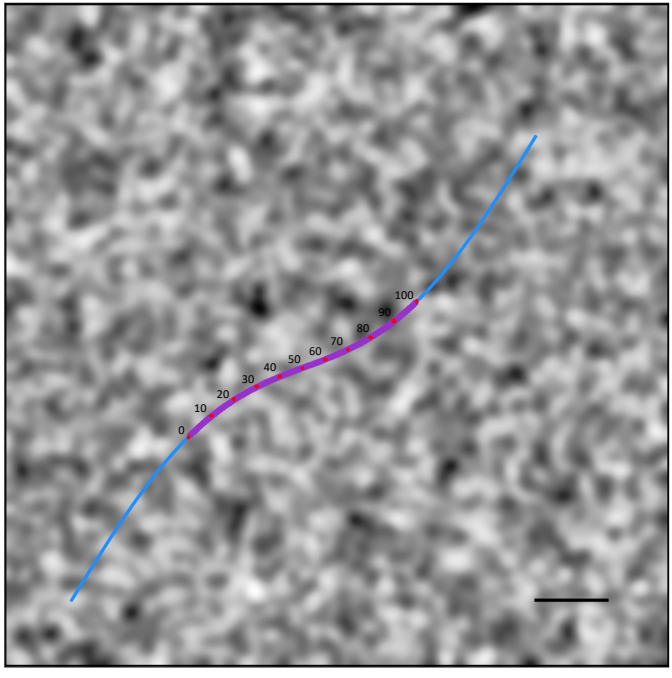


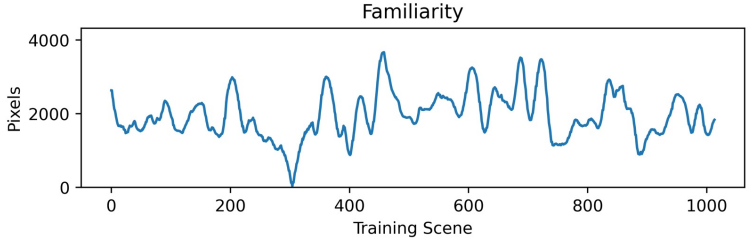


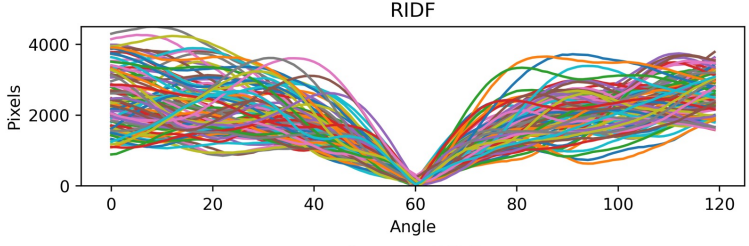
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

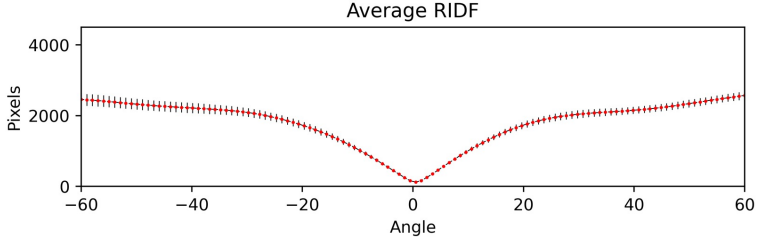
Navigation stats: RMSD error: 69.85; RMSD/dist: 0.175; TD: 1872; p90: 44; p50: 22; complete: 0

100%





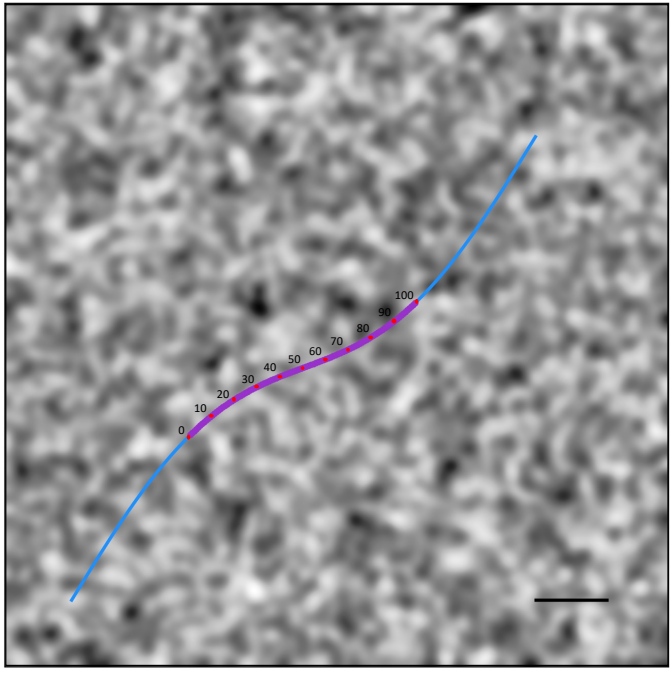


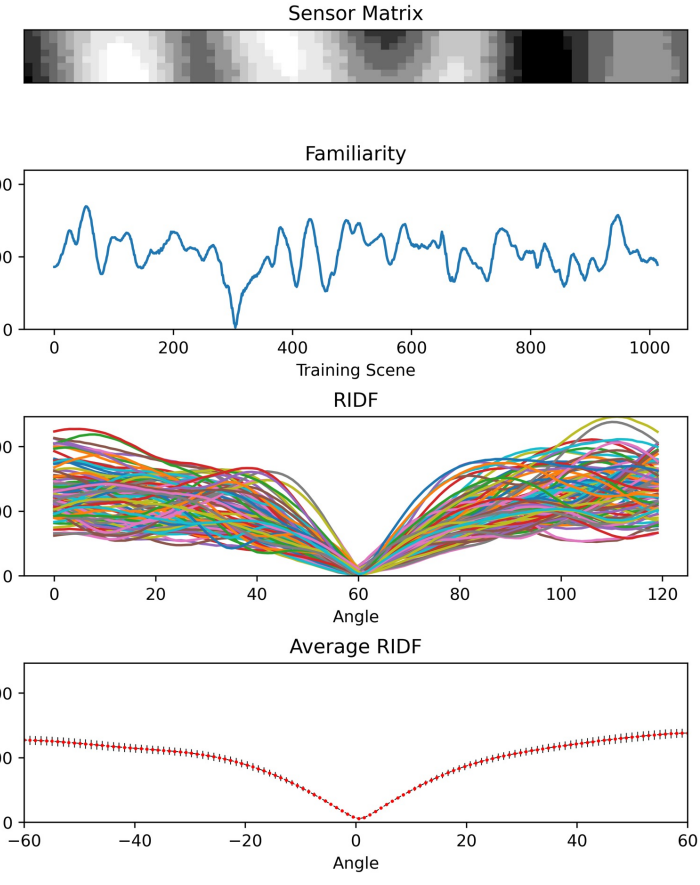


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 54.37; RMSD/dist: 0.136; TD: 1930; p90: 46; p50: 22; complete: 0

100%

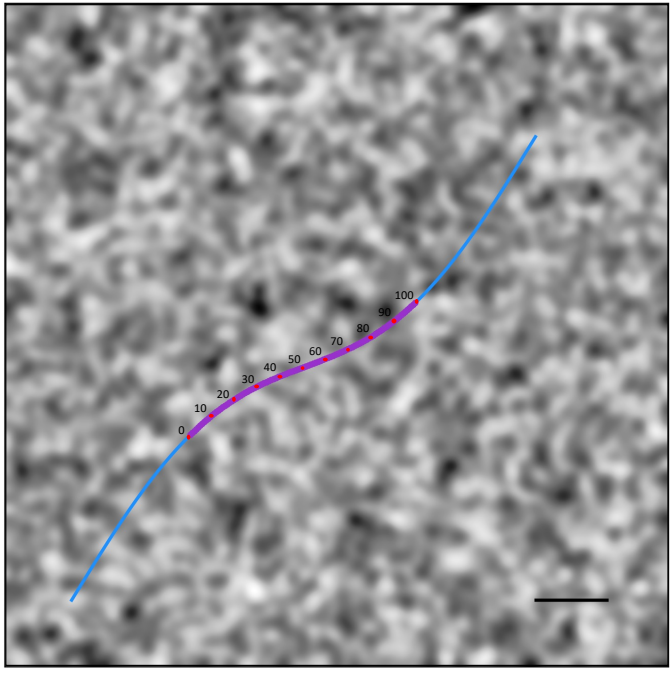


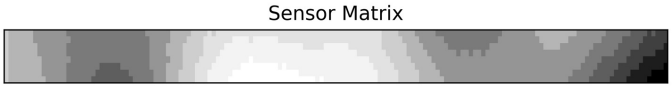


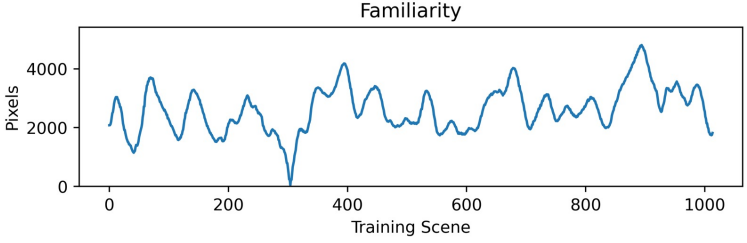
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

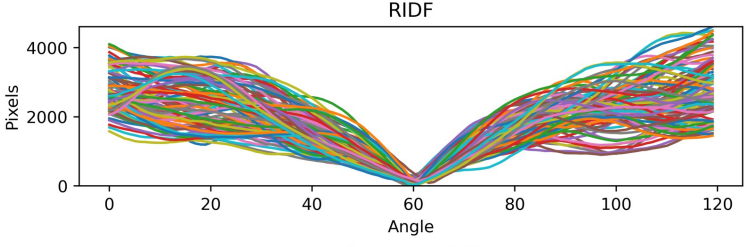
Navigation stats: RMSD error: 44.33; RMSD/dist: 0.111; TD: 2014; p90: 46; p50: 22; complete: 0

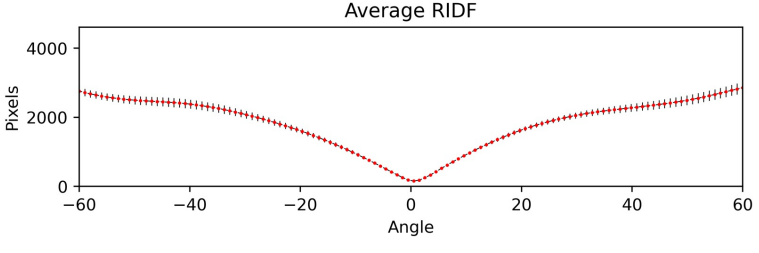
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 78.63; RMSD/dist: 0.197; TD: 2334; p90: 70; p50: 32; complete: 0