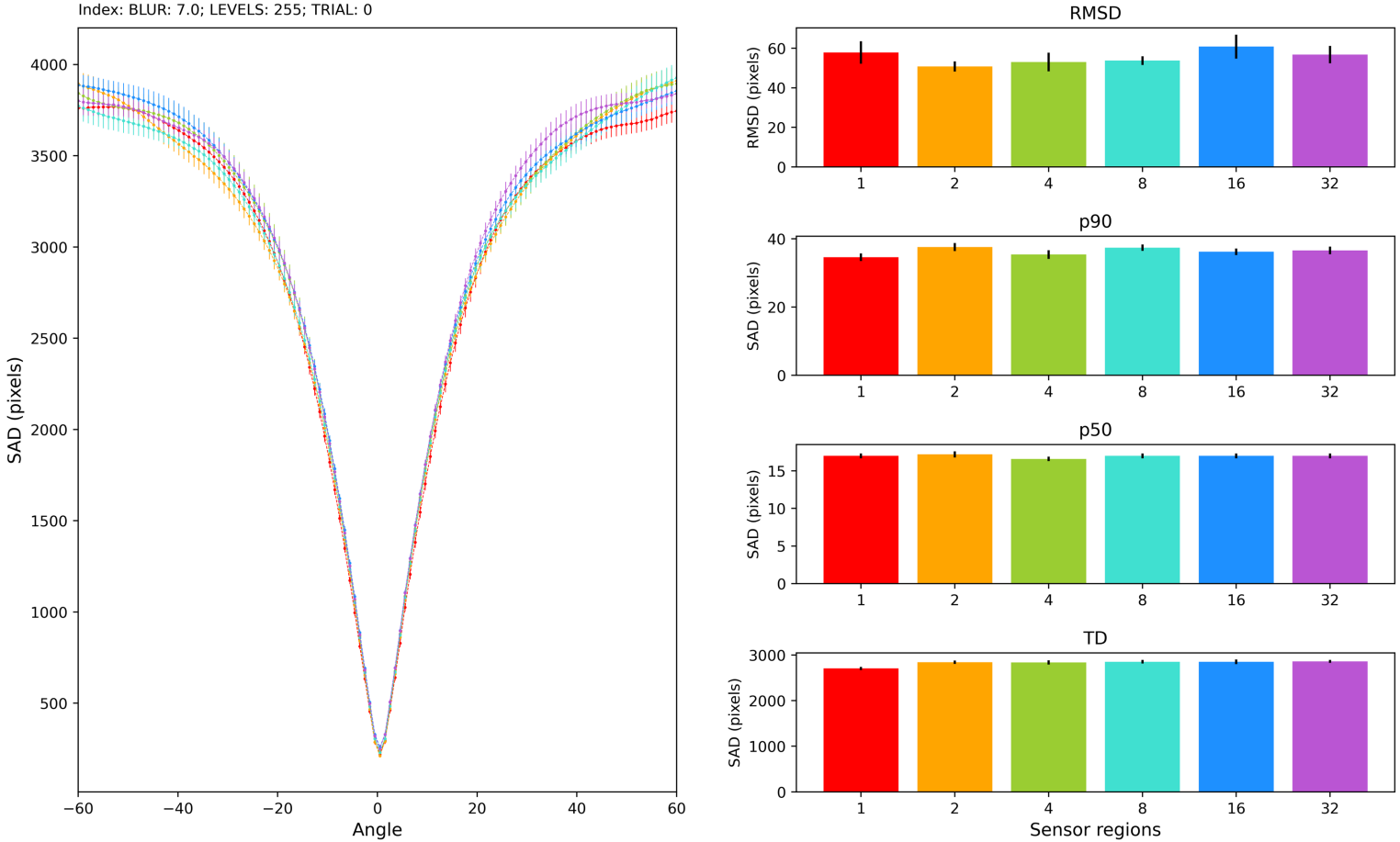
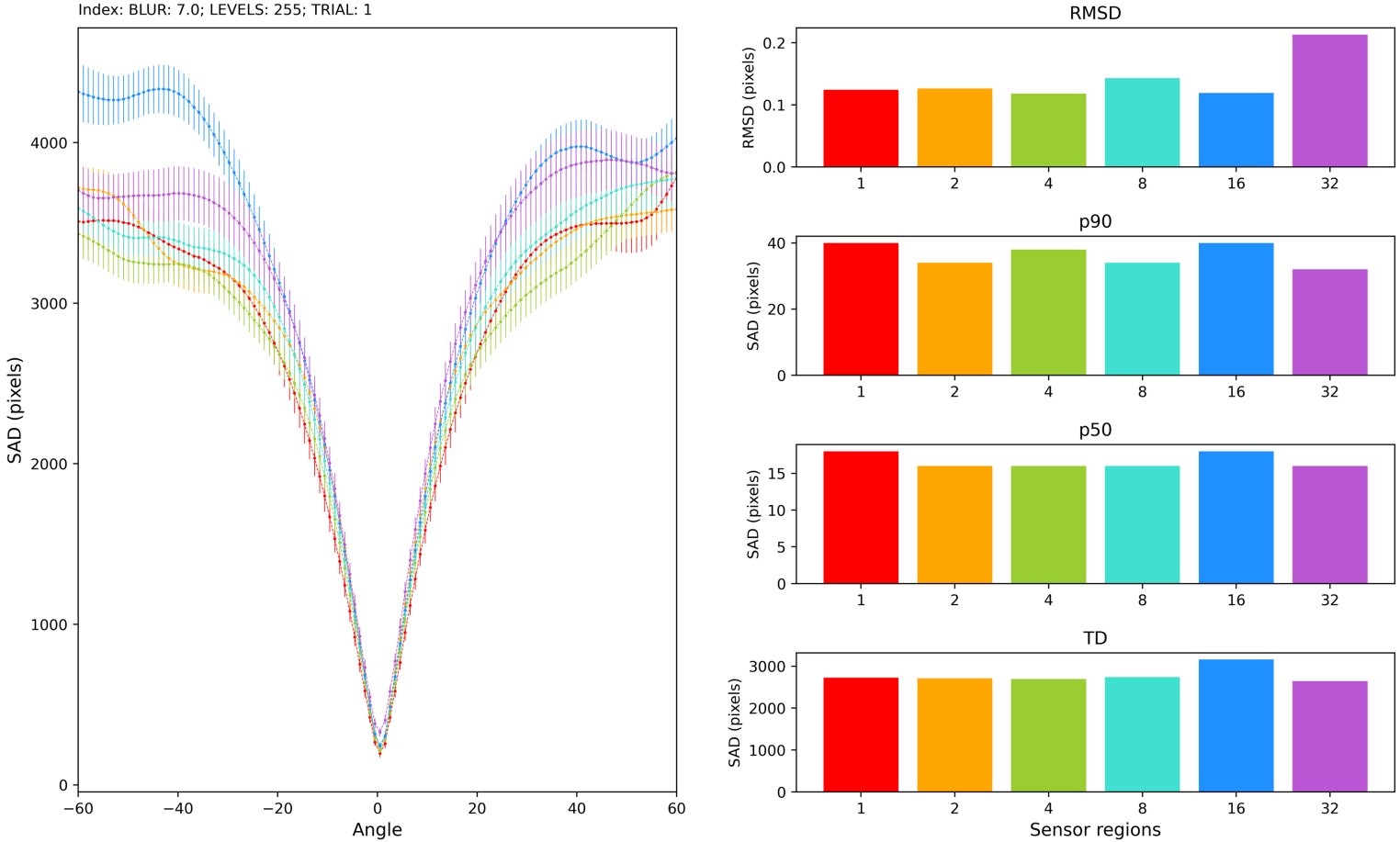

Index: BLUR: 7.0; LEVELS: 255; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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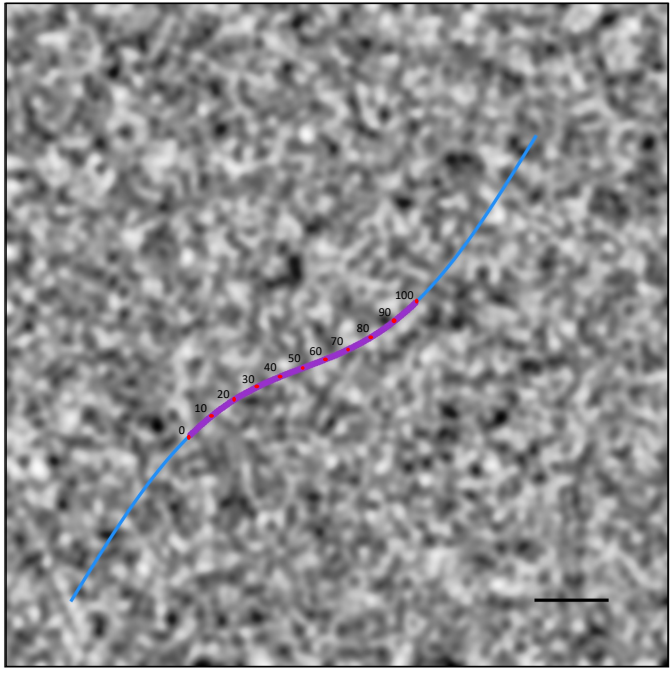
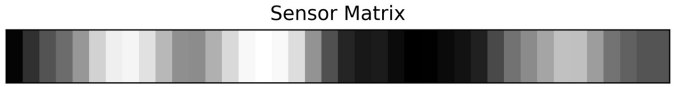
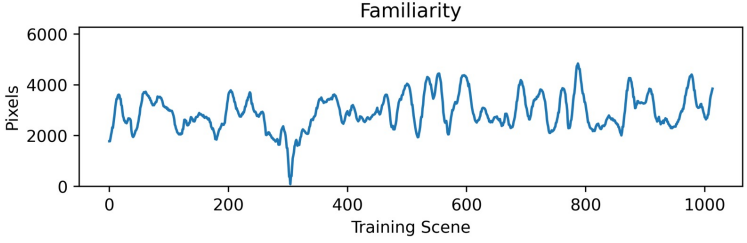
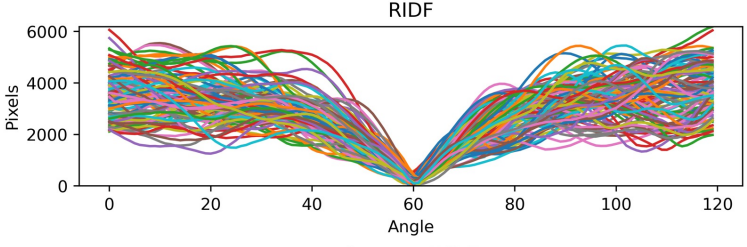
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

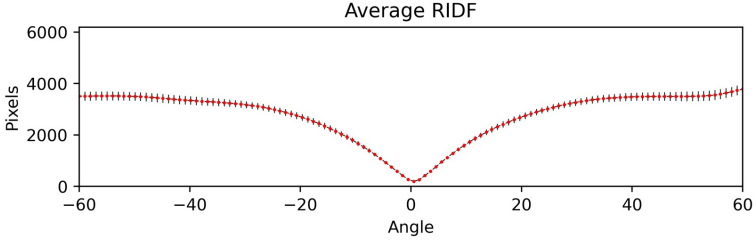
100%







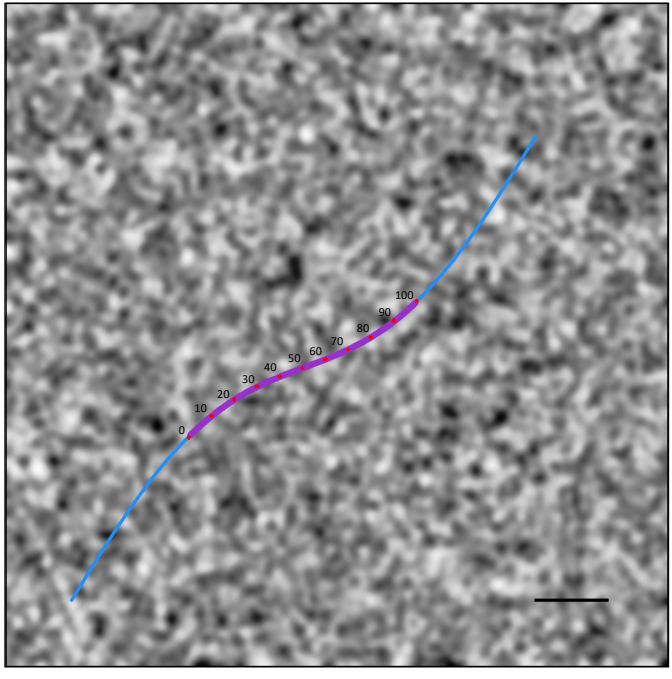


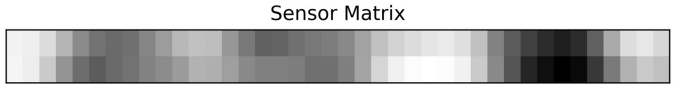


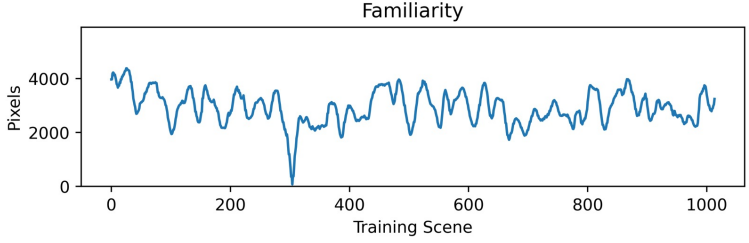
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

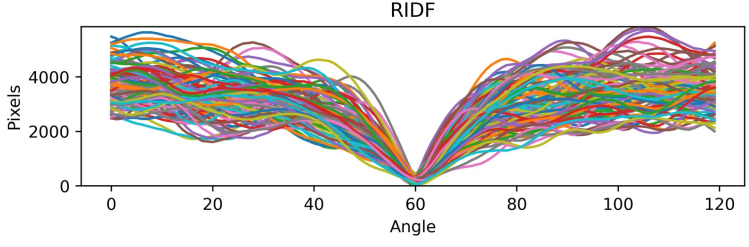
Navigation stats: RMSD error: 49.67; RMSD/dist: 0.124; TD: 2727; p90: 40; p50: 18; complete: 0

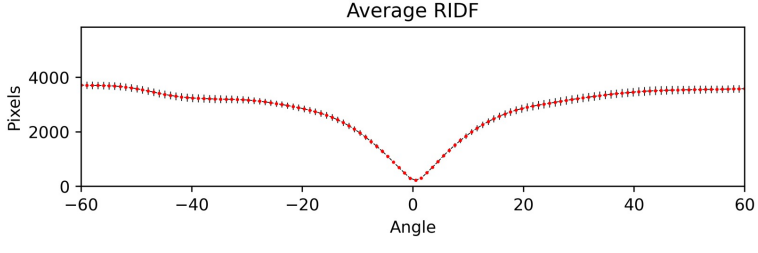
100%







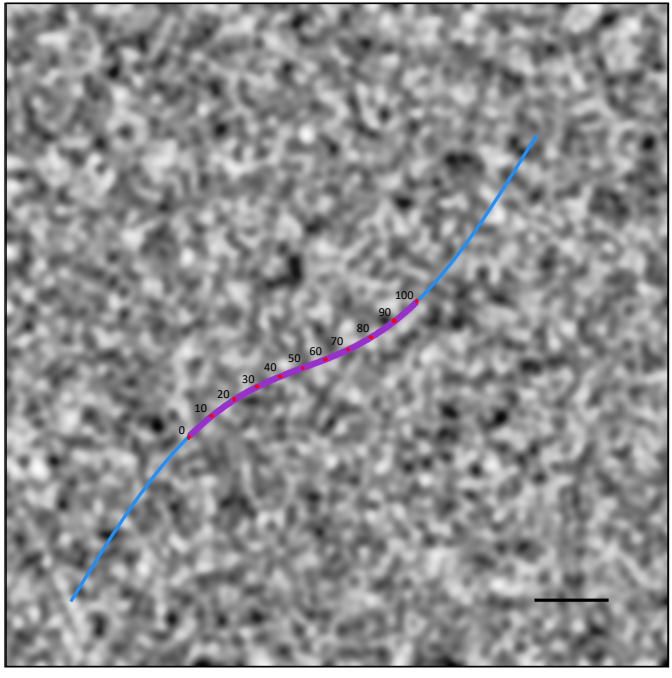


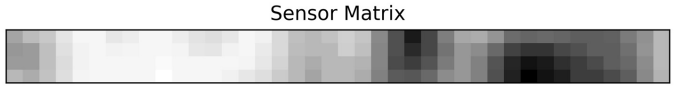


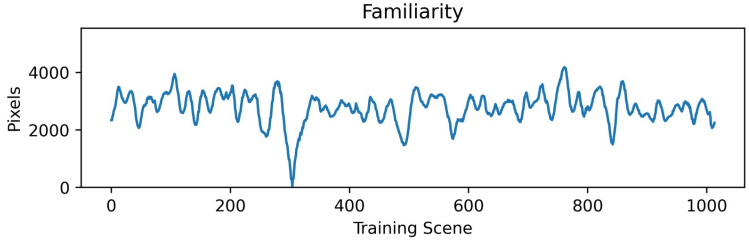
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

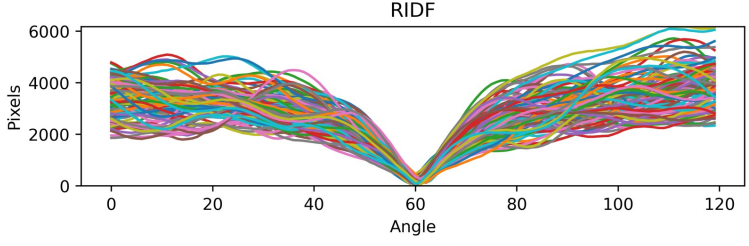
Navigation stats: RMSD error: 50.57; RMSD/dist: 0.126; TD: 2710; p90: 34; p50: 16; complete: 0

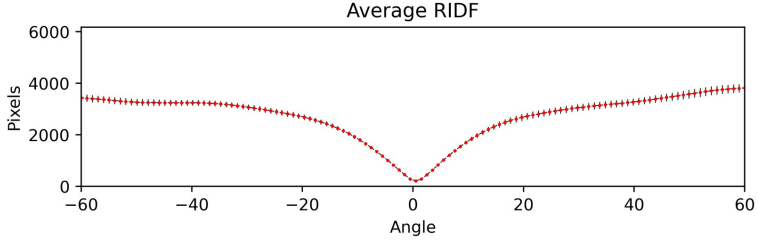
100%







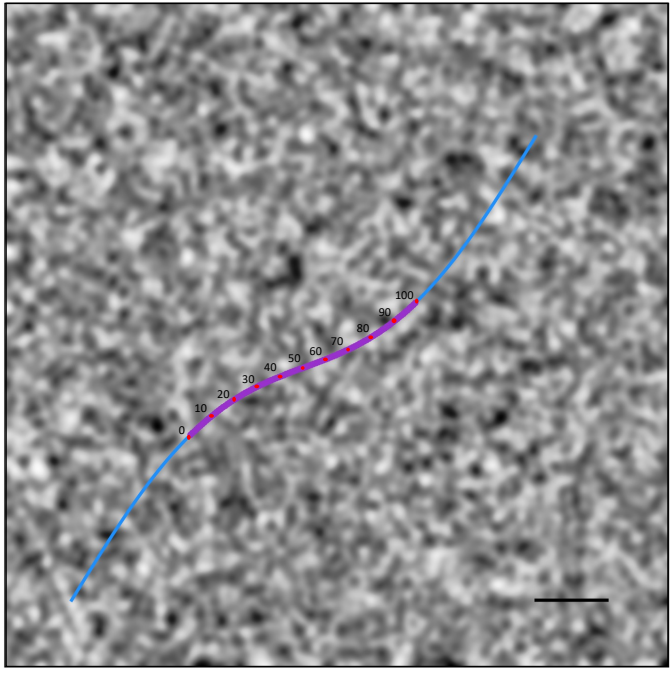


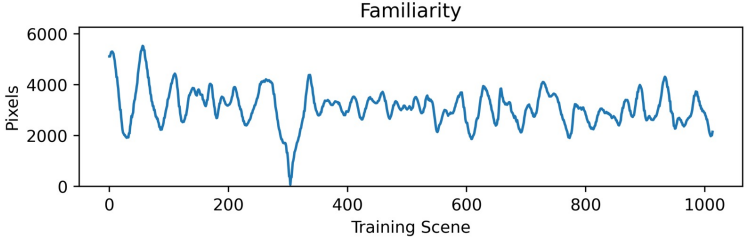


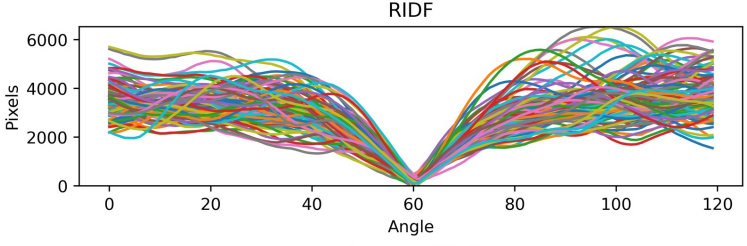
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

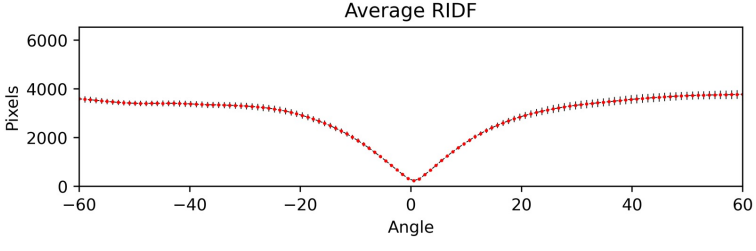
Navigation stats: RMSD error: 47.07; RMSD/dist: 0.118; TD: 2696; p90: 38; p50: 16; complete: 0

100%





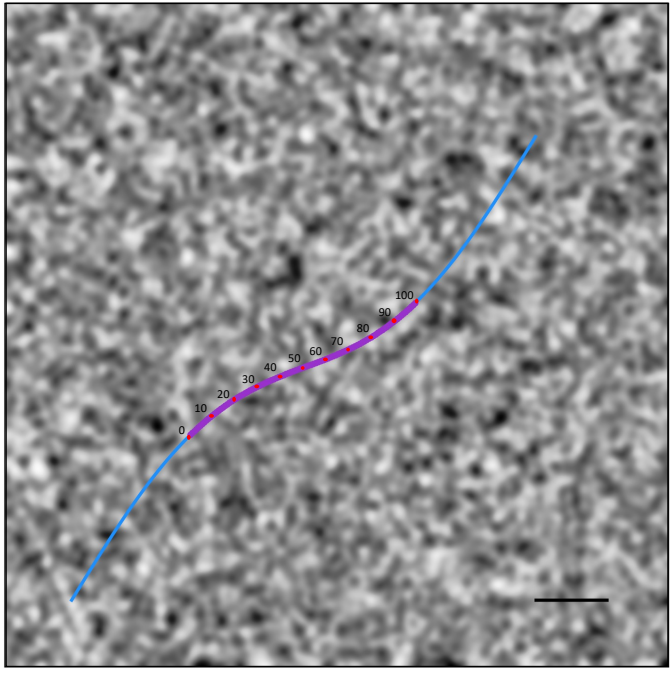


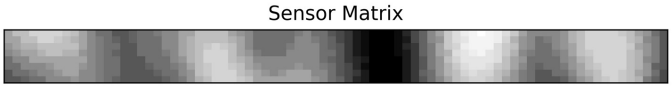


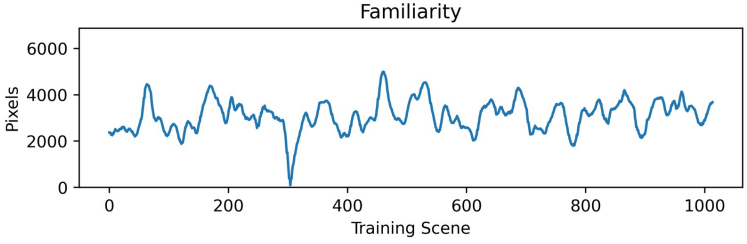
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

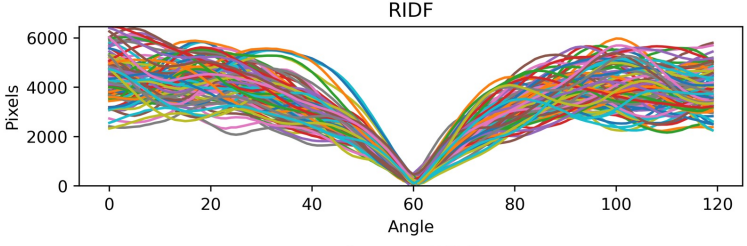
Navigation stats: RMSD error: 57.36; RMSD/dist: 0.143; TD: 2740; p90: 34; p50: 16; complete: 0

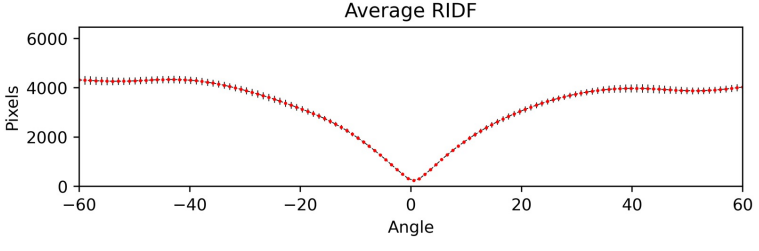
100%







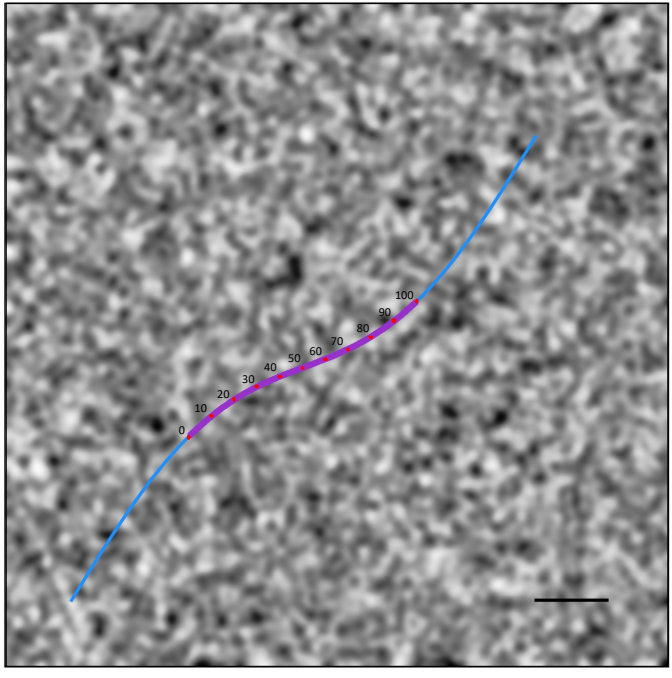


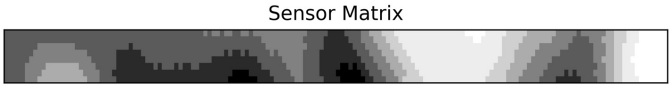


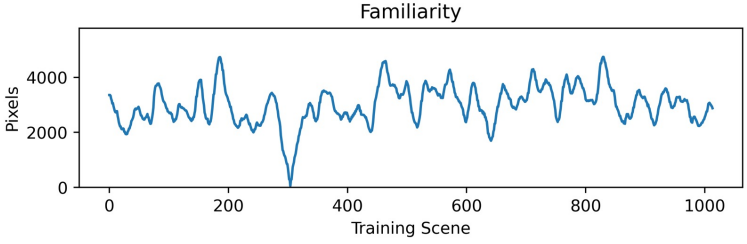
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

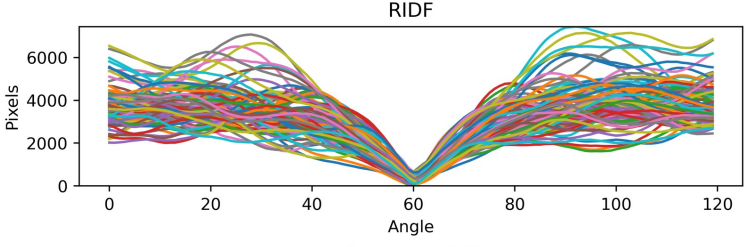
Navigation stats: RMSD error: 47.47; RMSD/dist: 0.119; TD: 3157; p90: 40; p50: 18; complete: 0

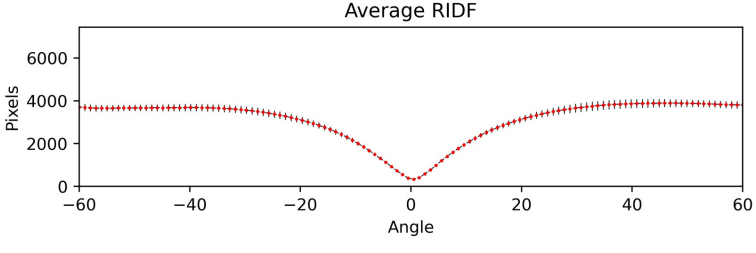
100%





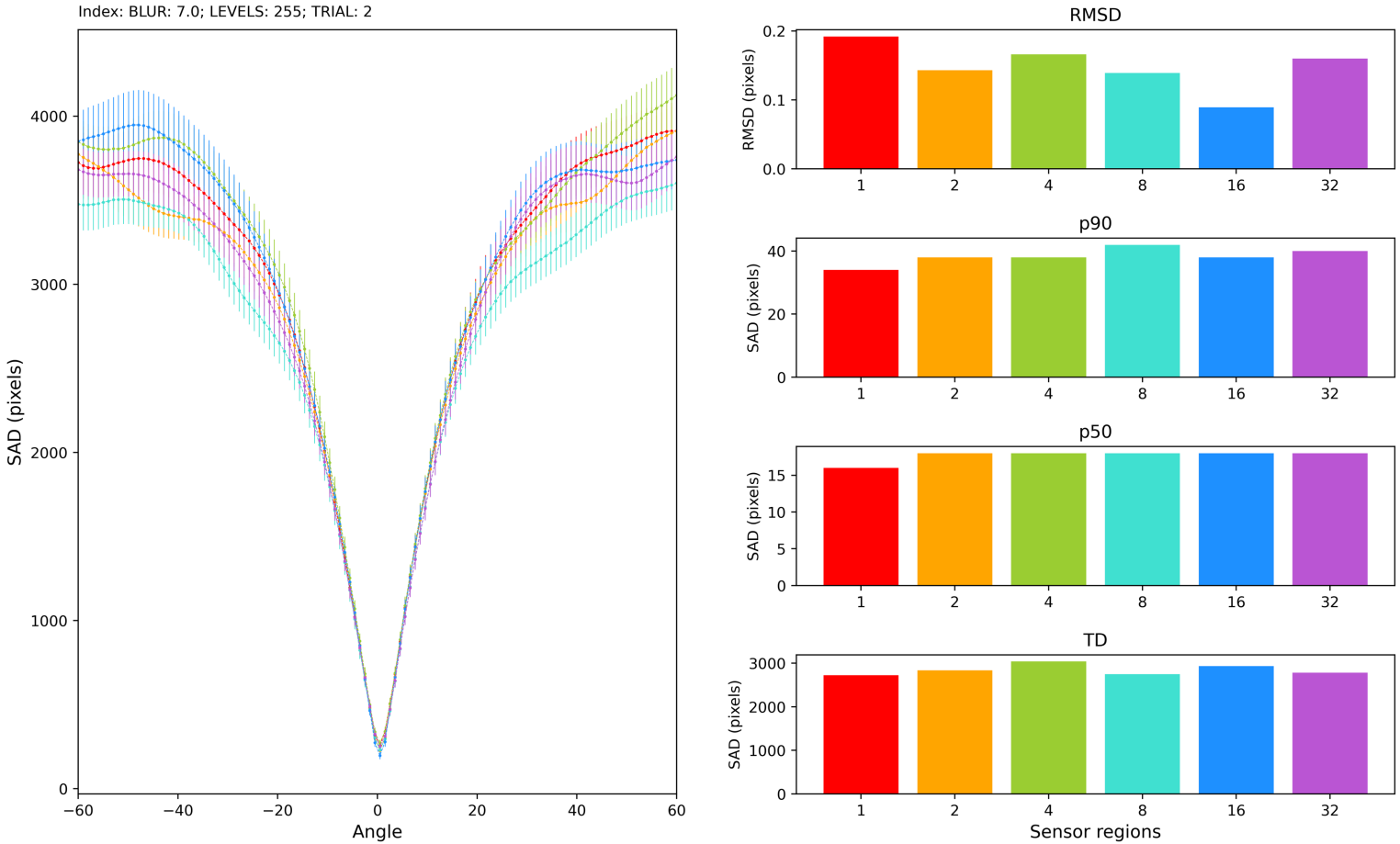




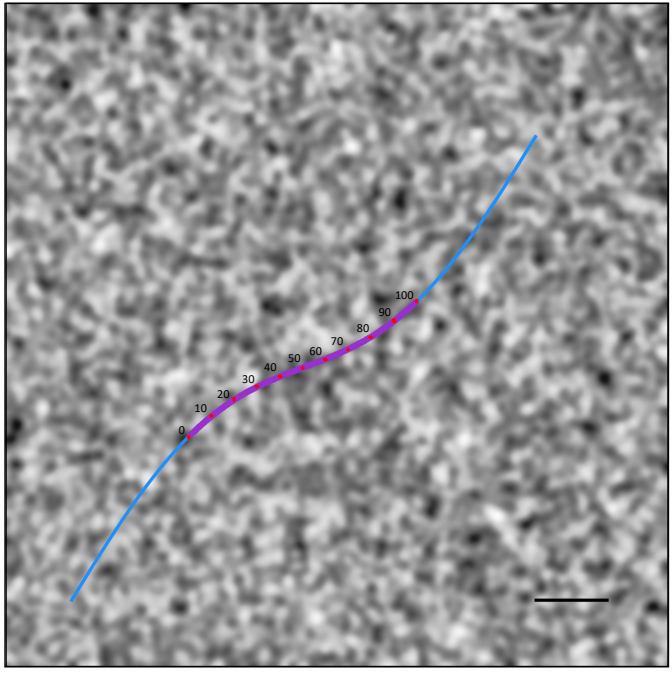


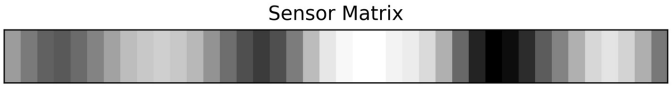
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

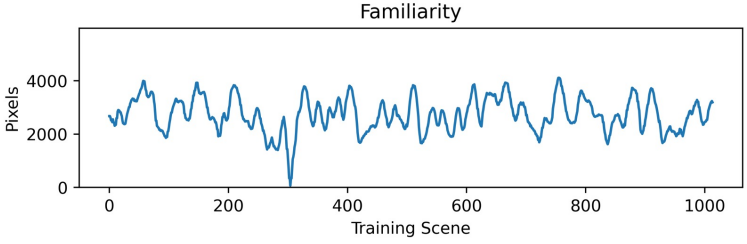
Navigation stats: RMSD error: 85.25; RMSD/dist: 0.213; TD: 2646; p90: 32; p50: 16; complete: 0

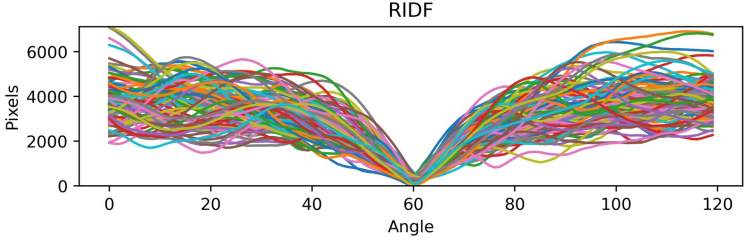

Index: BLUR: 7.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

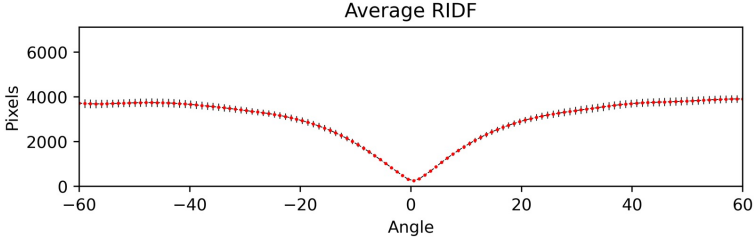
100%







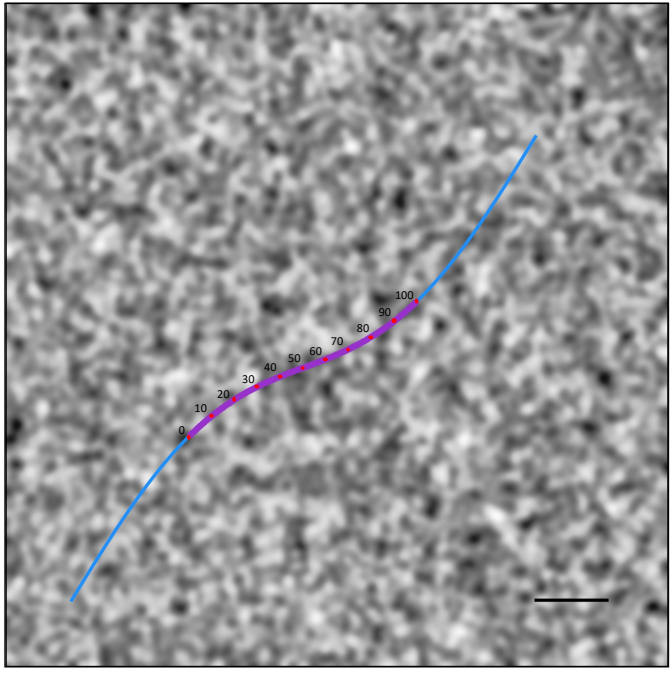


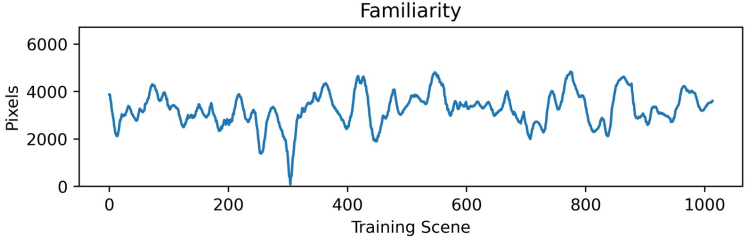


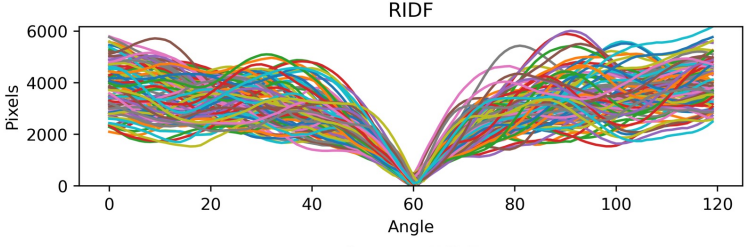
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

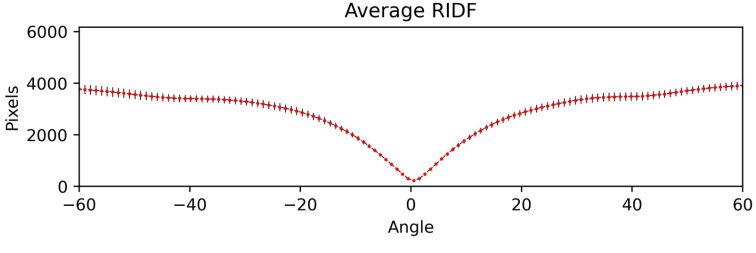
Navigation stats: RMSD error: 76.62; RMSD/dist: 0.192; TD: 2722; p90: 34; p50: 16; complete: 0

100%





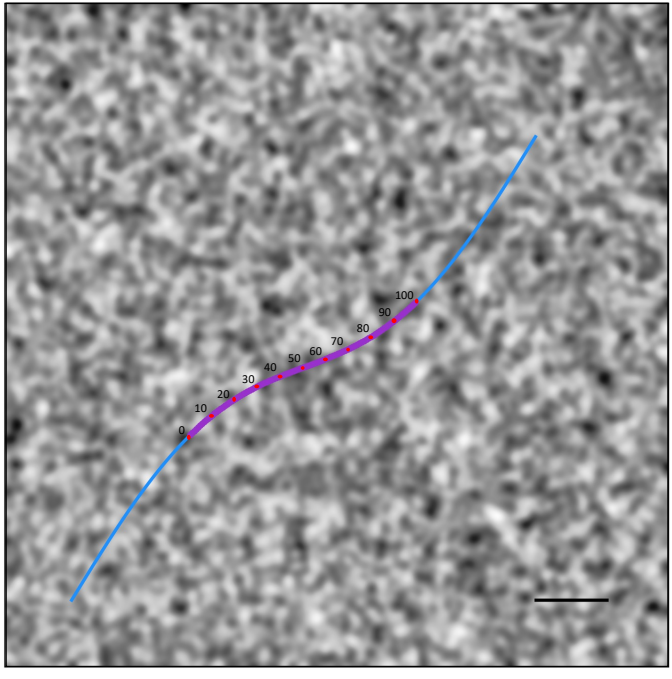


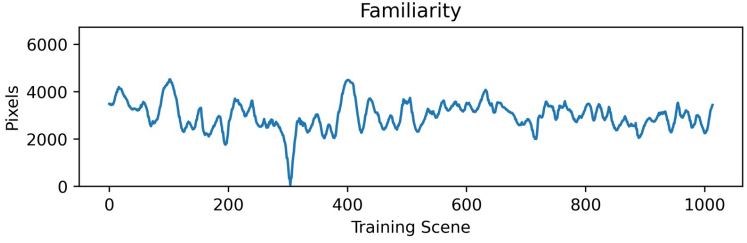


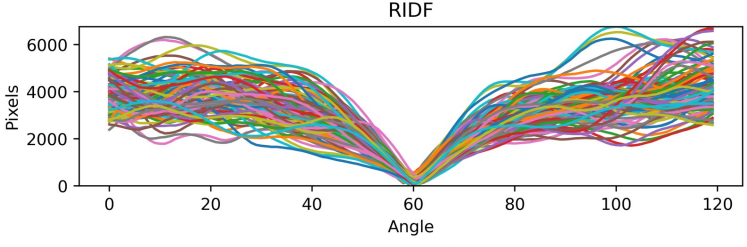
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

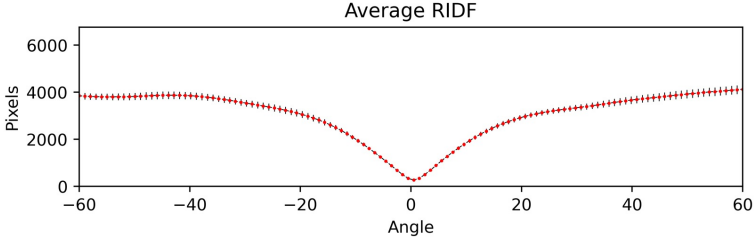
Navigation stats: RMSD error: 57.02; RMSD/dist: 0.143; TD: 2835; p90: 38; p50: 18; complete: 0

100%





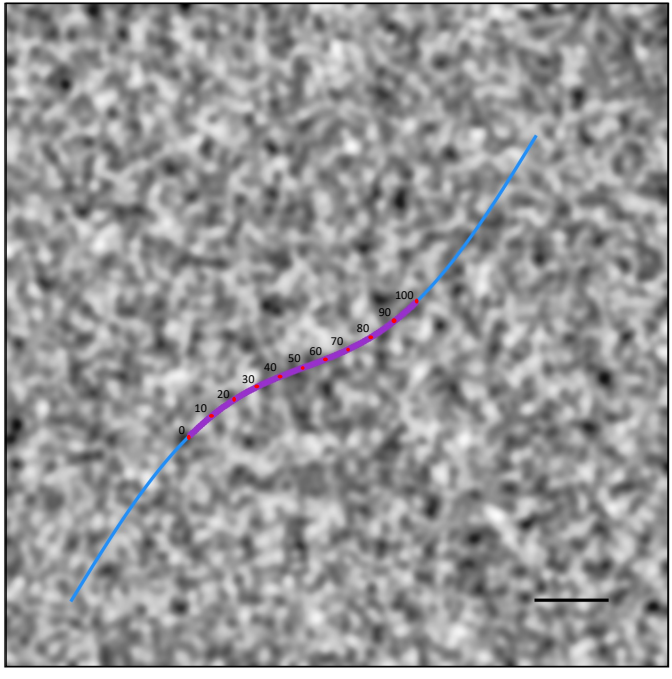


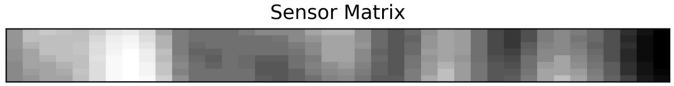


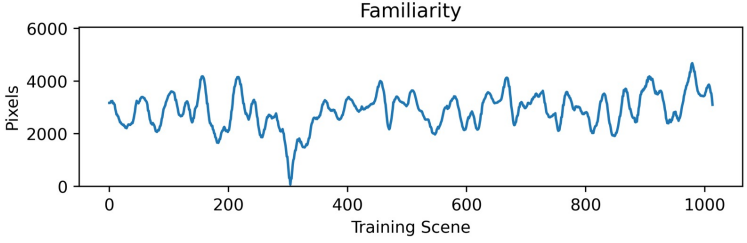
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

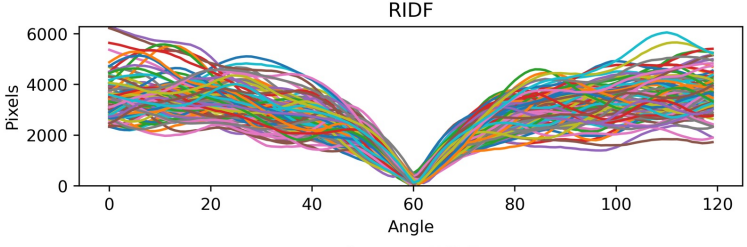
Navigation stats: RMSD error: 66.59; RMSD/dist: 0.166; TD: 3038; p90: 38; p50: 18; complete: 0

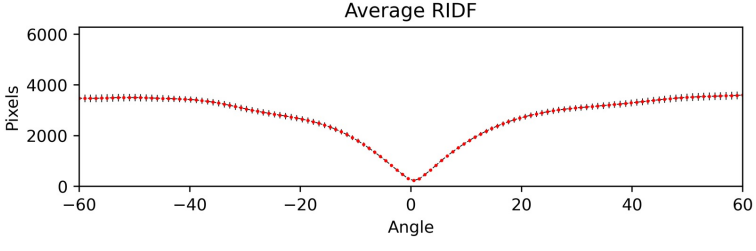
100%







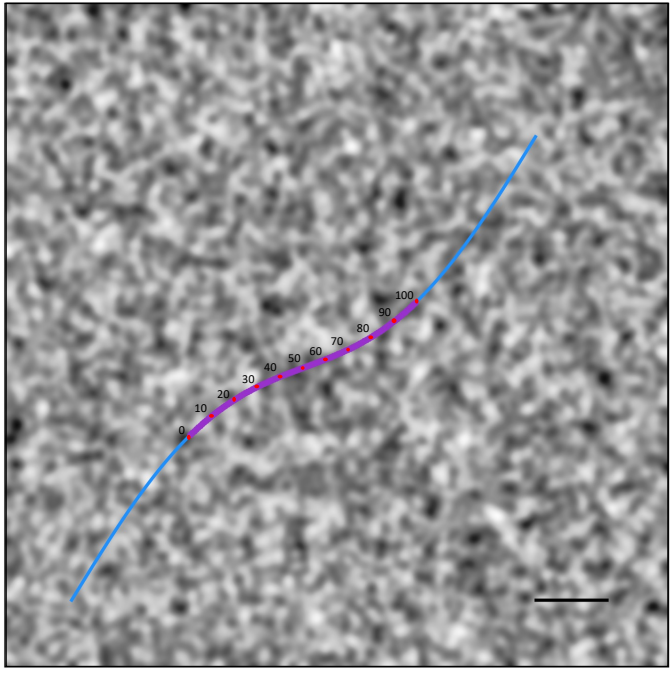


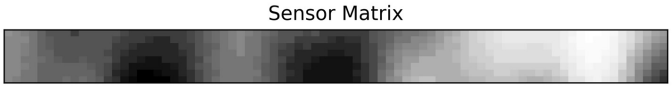


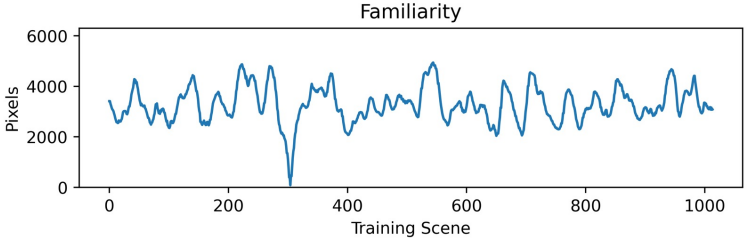
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

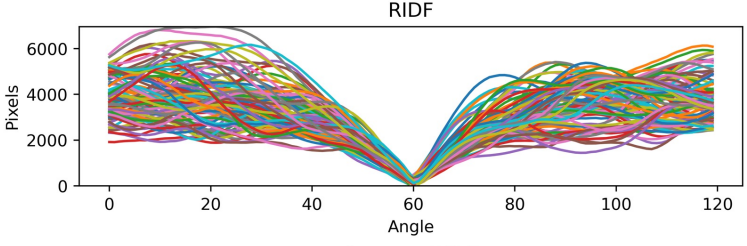
Navigation stats: RMSD error: 55.65; RMSD/dist: 0.139; TD: 2749; p90: 42; p50: 18; complete: 0

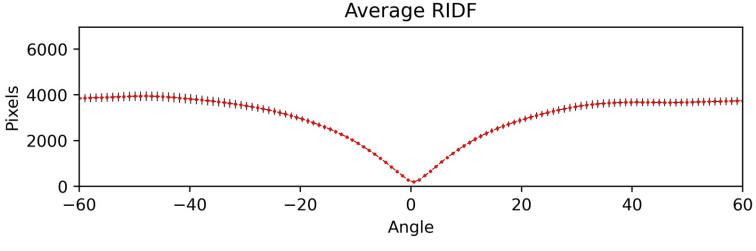
100%







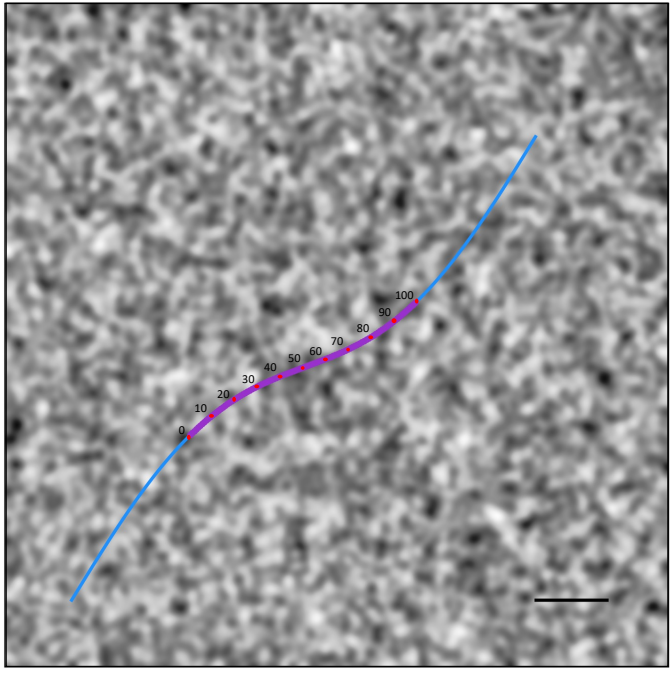


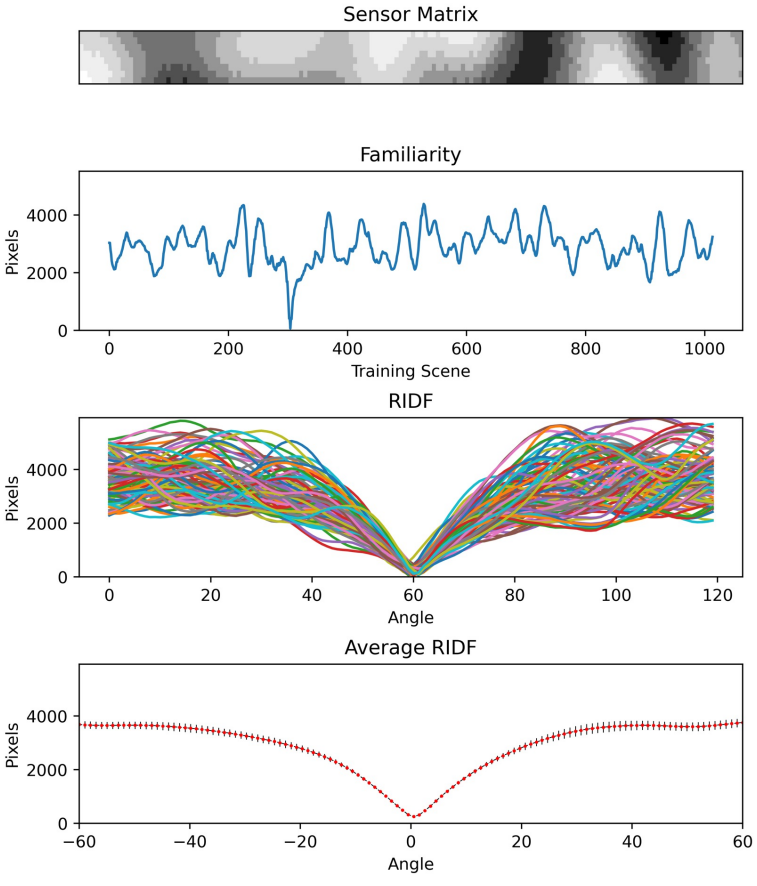


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 35.54; RMSD/dist: 0.089; TD: 2935; p90: 38; p50: 18; complete: 0

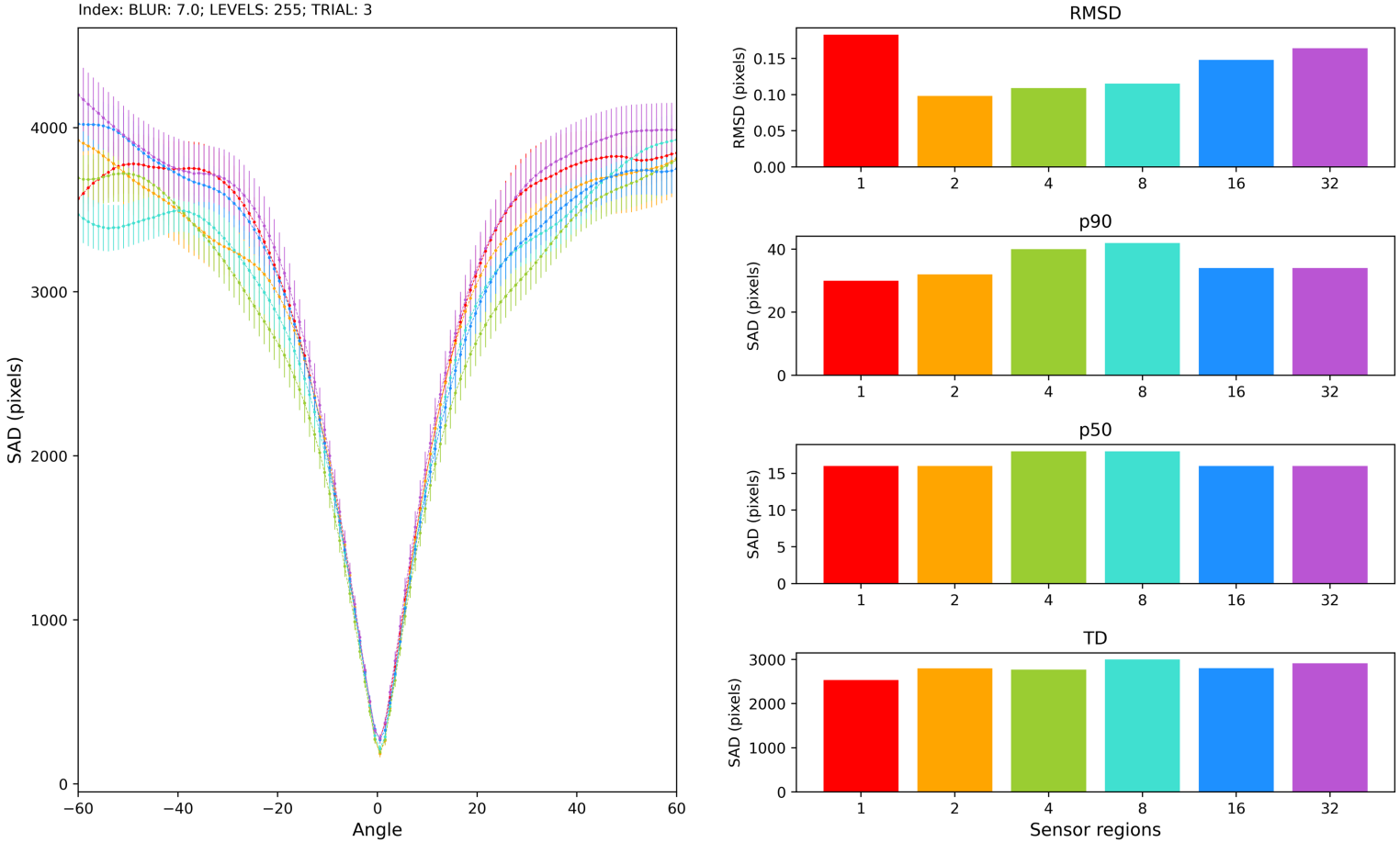
100%



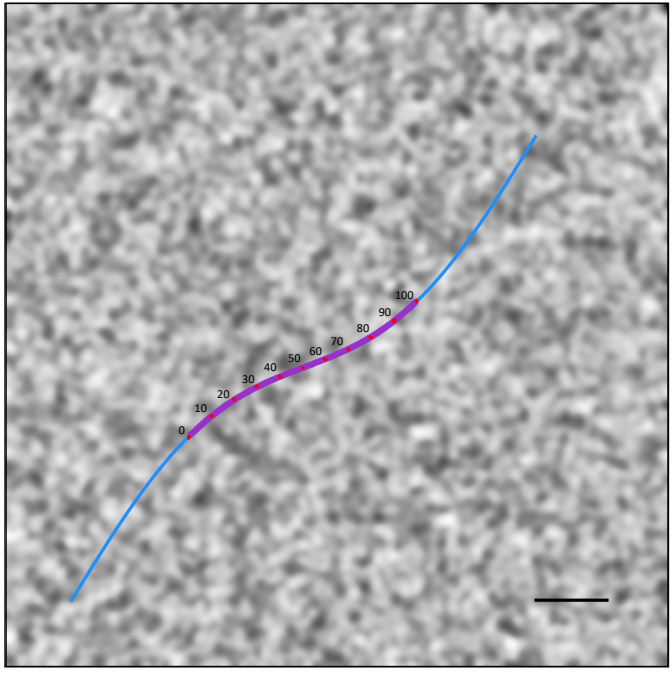


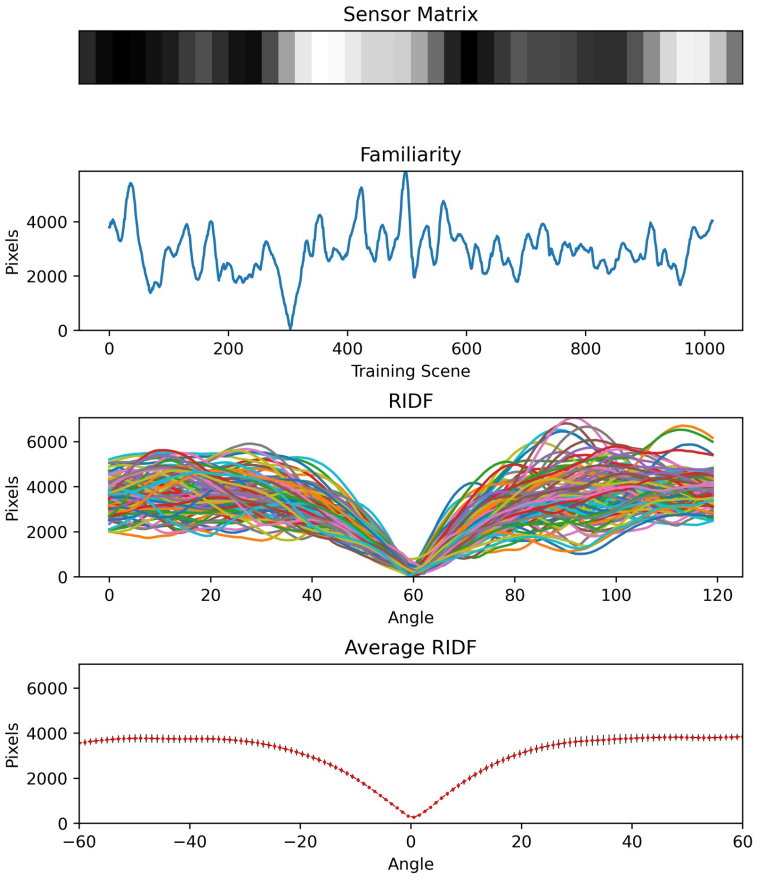
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 64.03; RMSD/dist: 0.160; TD: 2782; p90: 40; p50: 18; complete: 0


Index: BLUR: 7.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

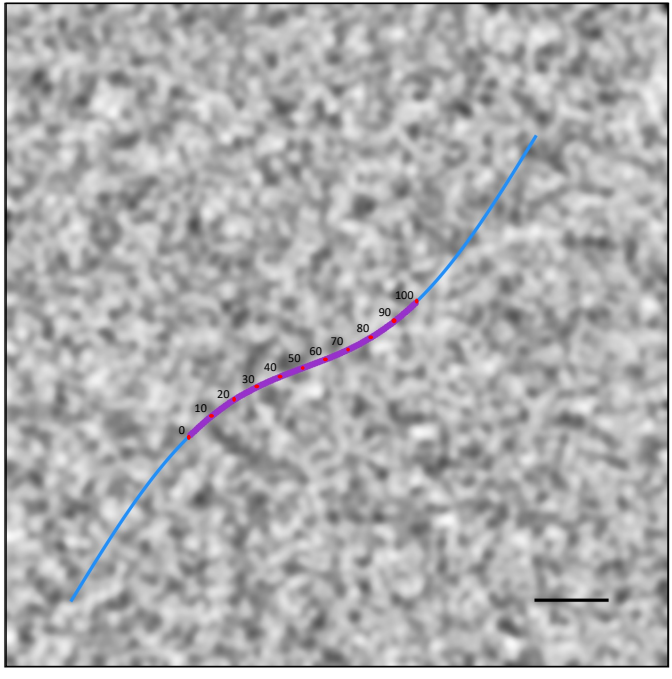


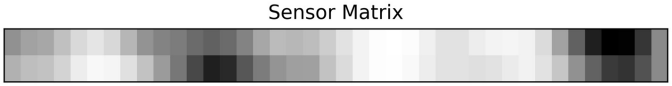


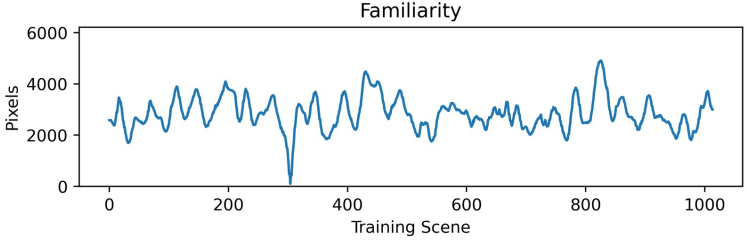
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

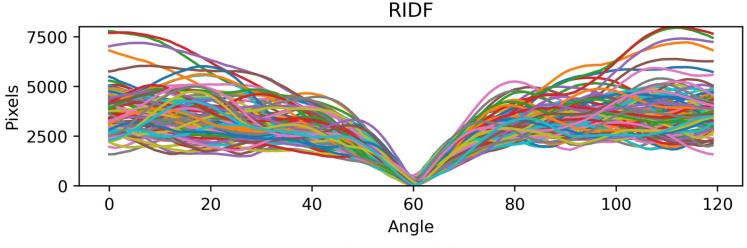
Navigation stats: RMSD error: 73.27; RMSD/dist: 0.183; TD: 2533; p90: 30; p50: 16; complete: 0

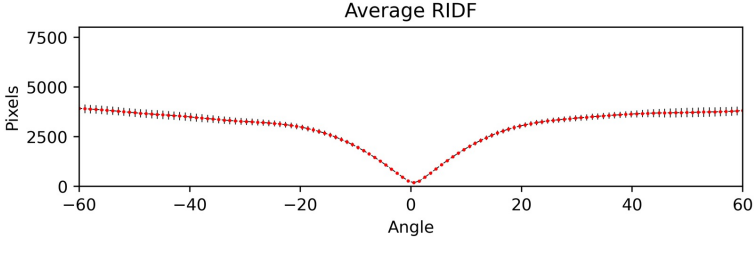
100%







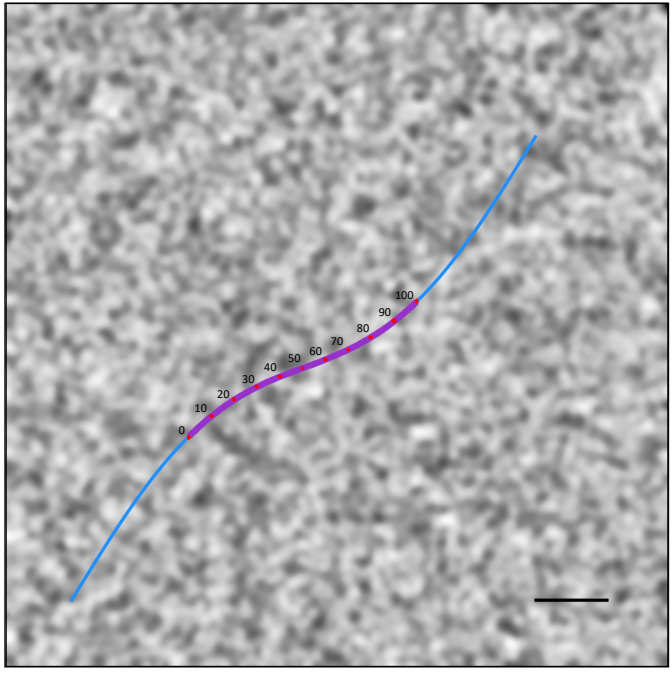


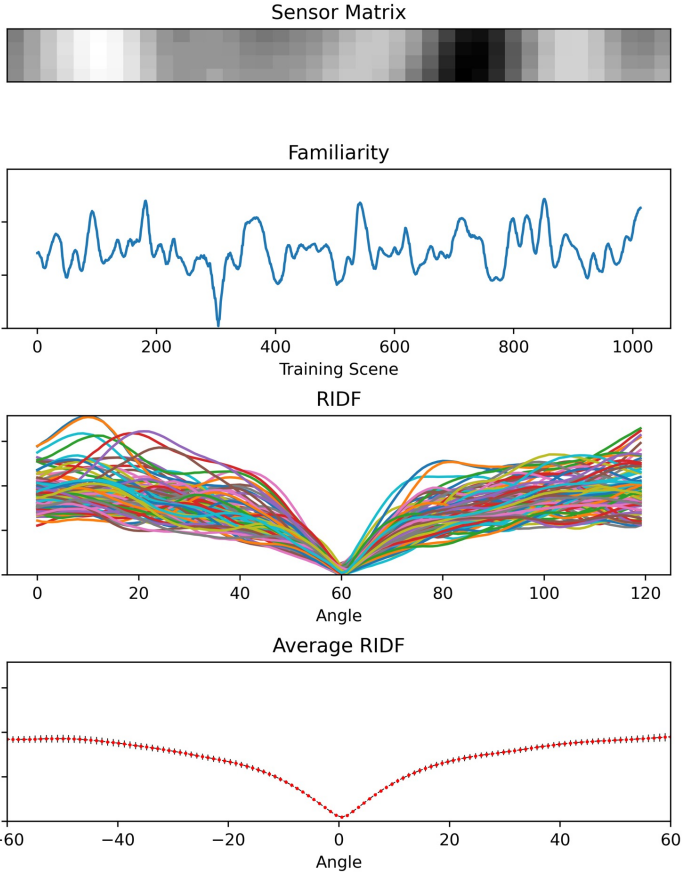


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 39.36; RMSD/dist: 0.098; TD: 2800; p90: 32; p50: 16; complete: 0

100%

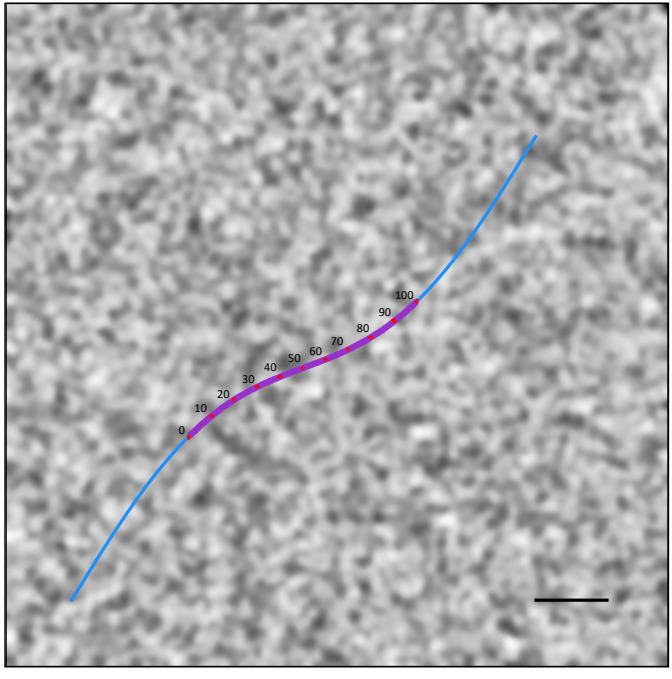


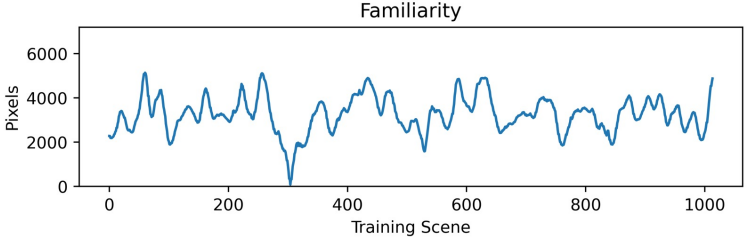


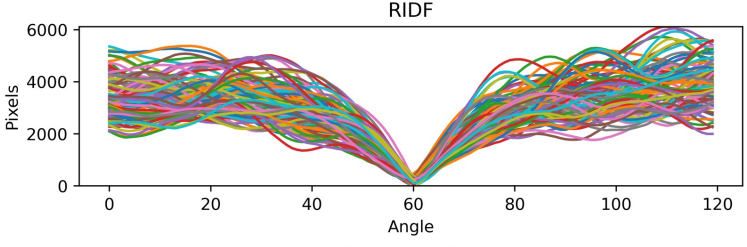
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

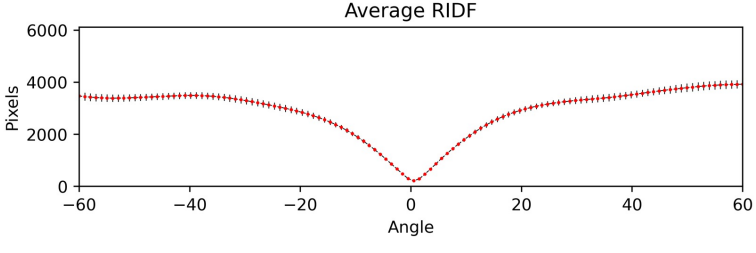
Navigation stats: RMSD error: 43.58; RMSD/dist: 0.109; TD: 2771; p90: 40; p50: 18; complete: 0

100%





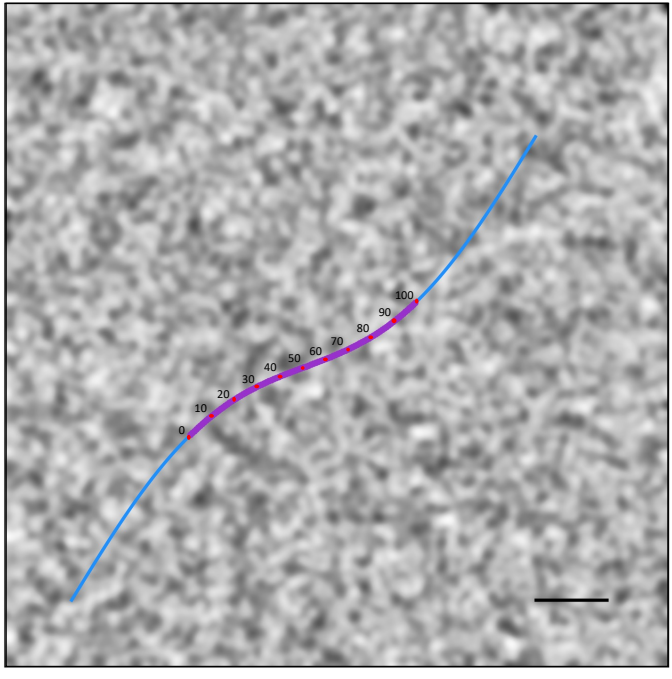


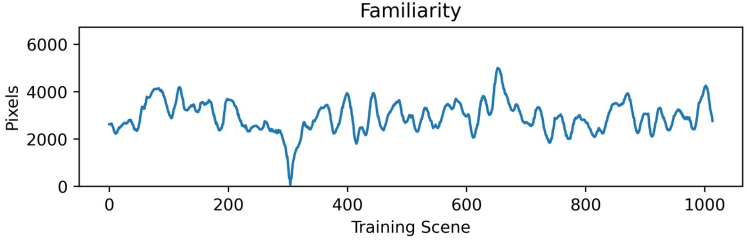


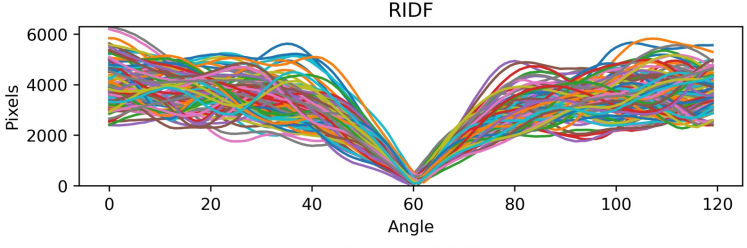
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

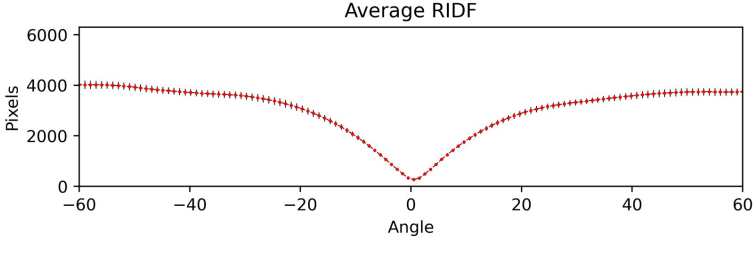
Navigation stats: RMSD error: 46.01; RMSD/dist: 0.115; TD: 2999; p90: 42; p50: 18; complete: 0

100%





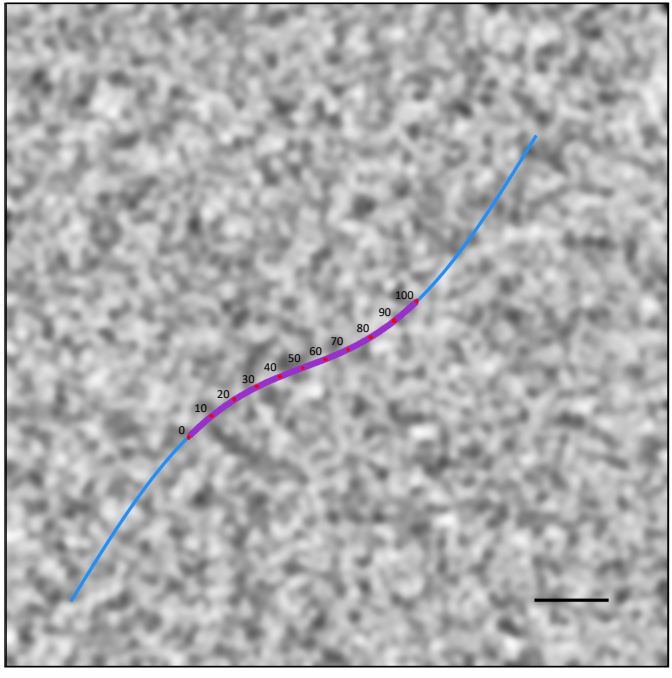


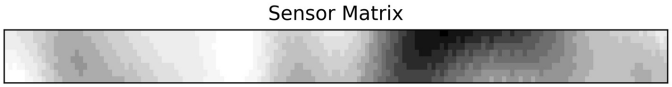


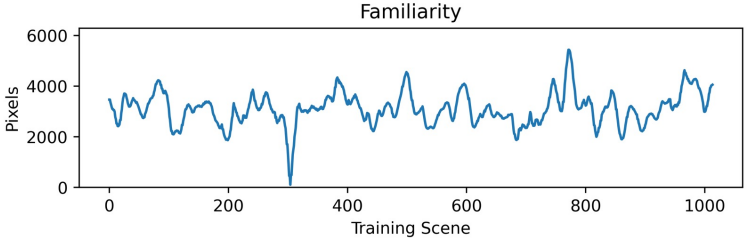
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

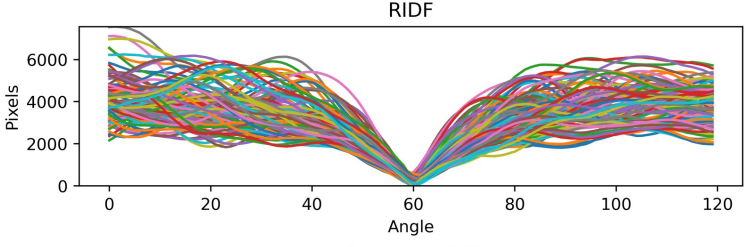
Navigation stats: RMSD error: 59.29; RMSD/dist: 0.148; TD: 2802; p90: 34; p50: 16; complete: 0

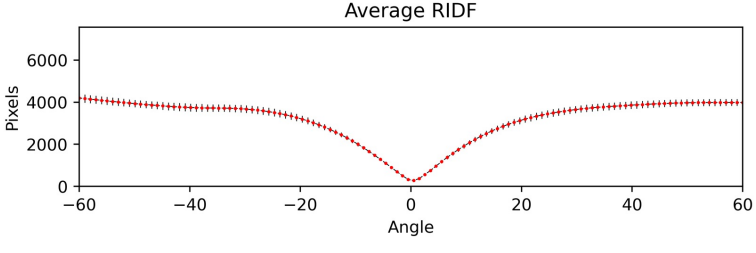
100%





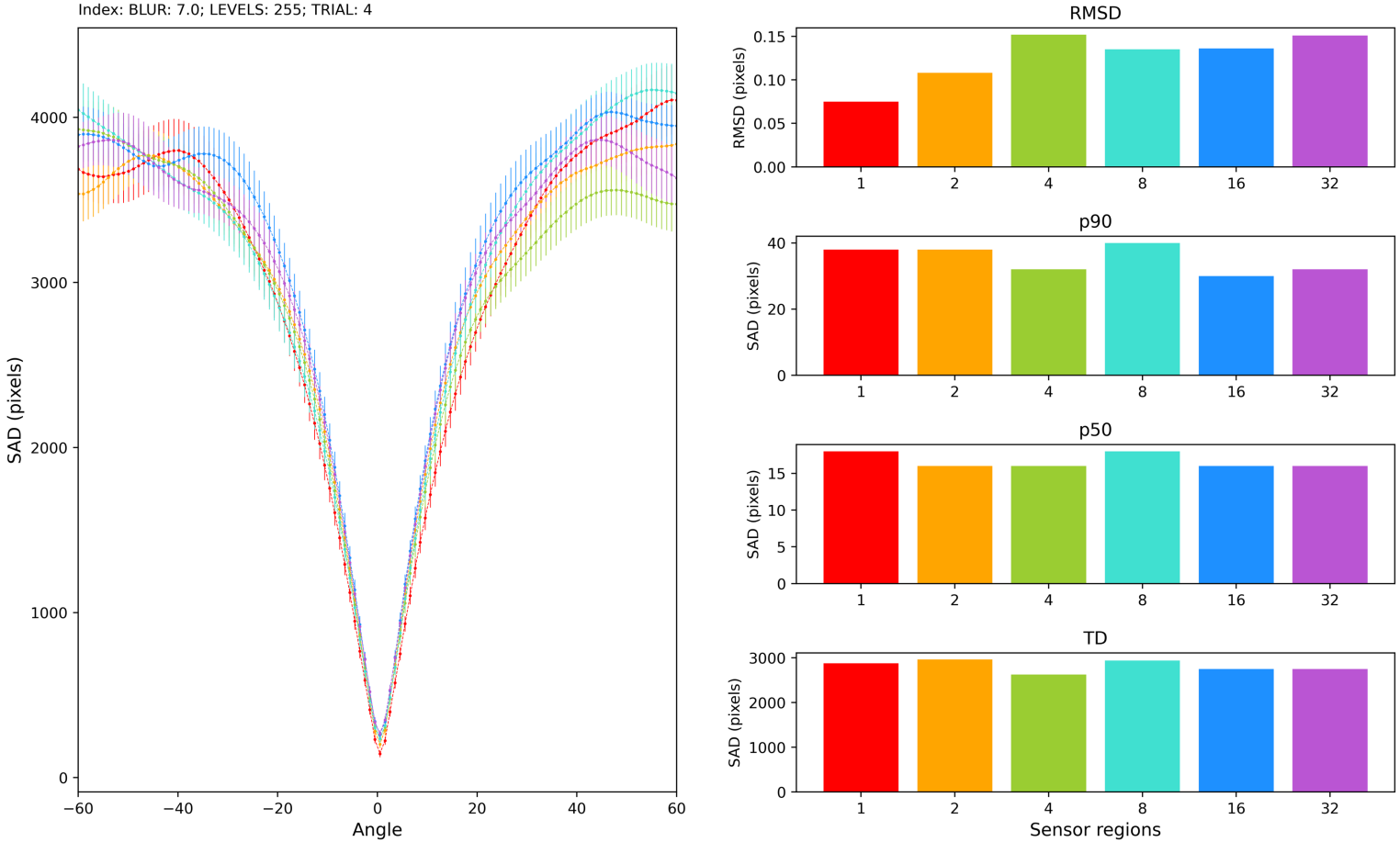




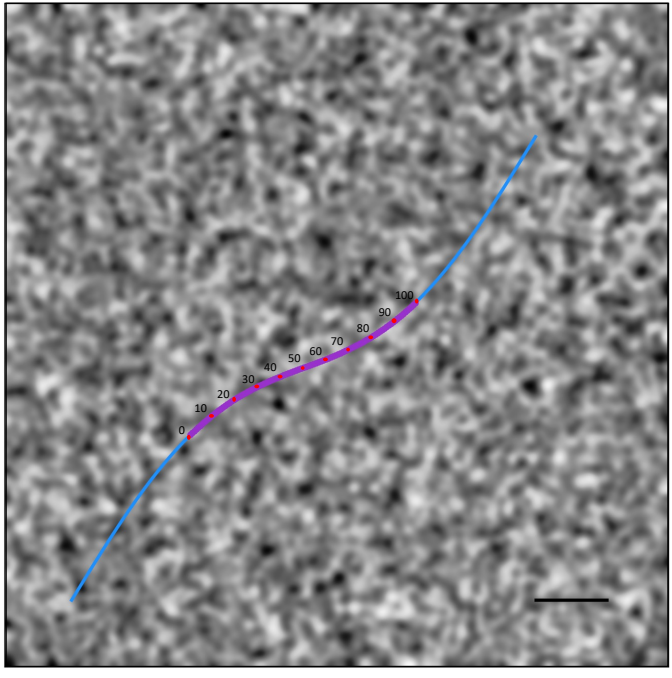


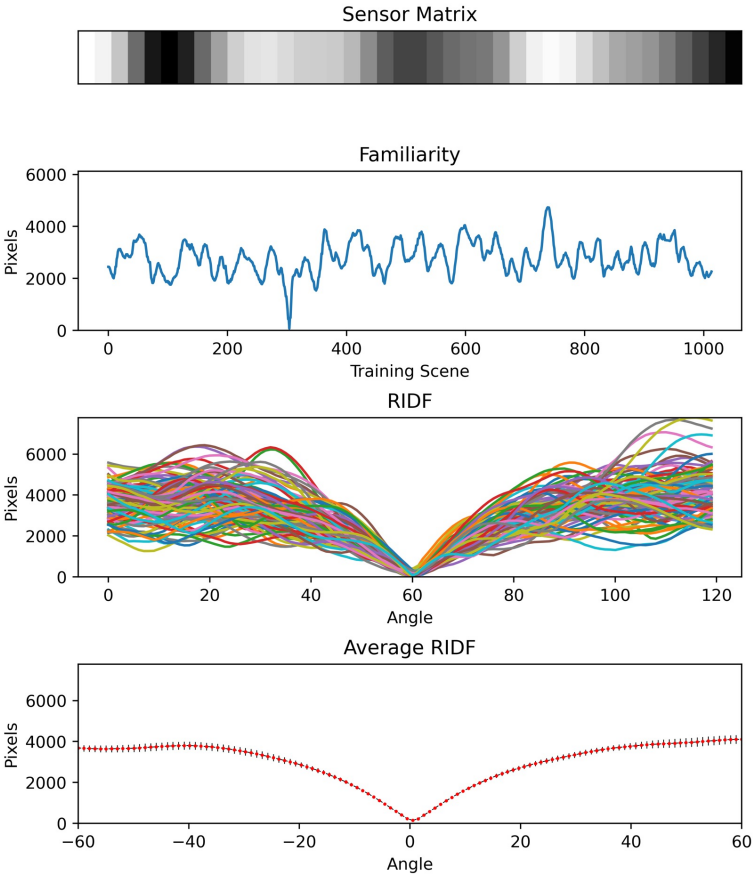
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 65.64; RMSD/dist: 0.164; TD: 2913; p90: 34; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 255; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

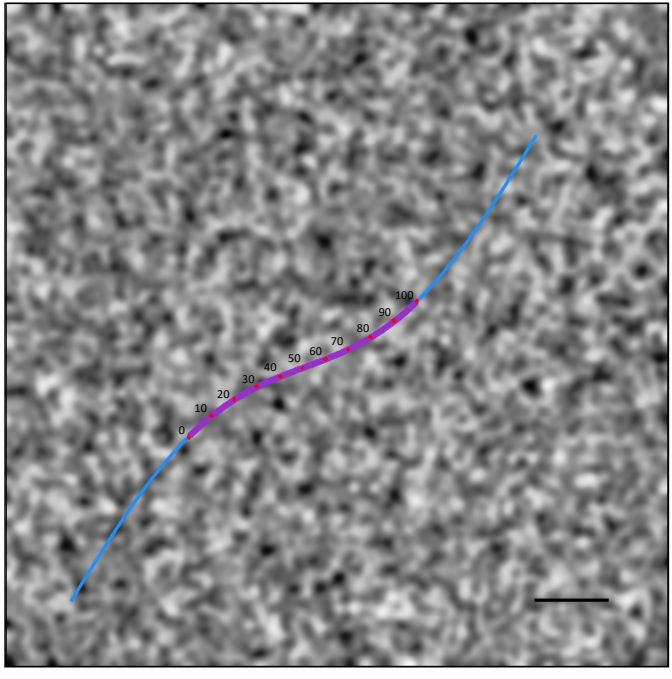


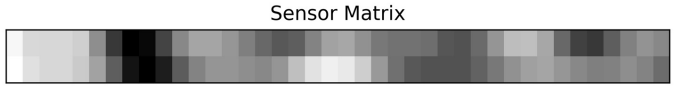


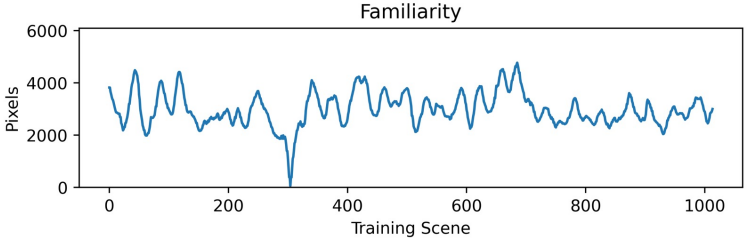
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

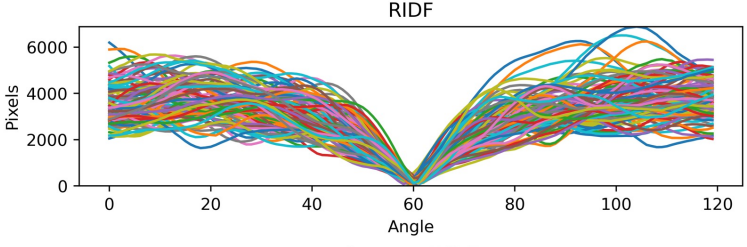
Navigation stats: RMSD error: 29.86; RMSD/dist: 0.075; TD: 2878; p90: 38; p50: 18; complete: 0

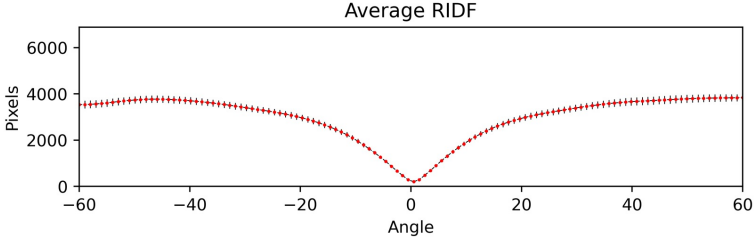
100%







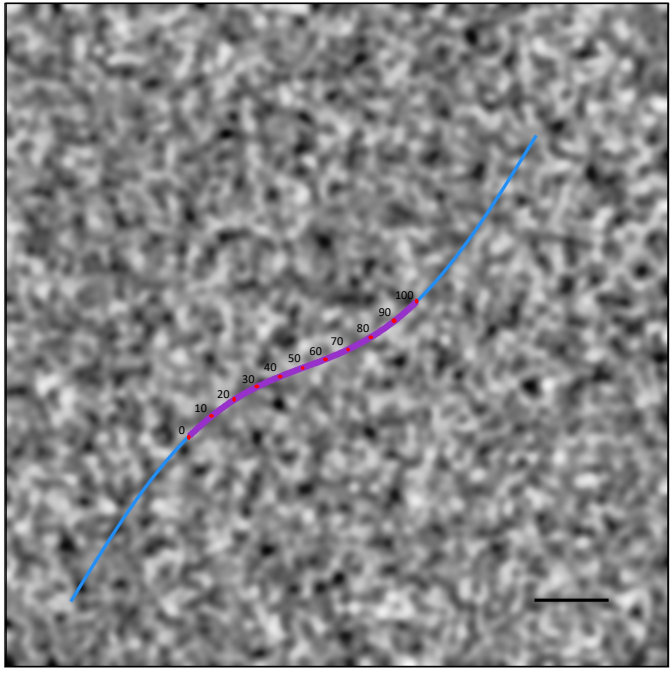


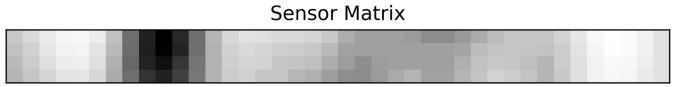


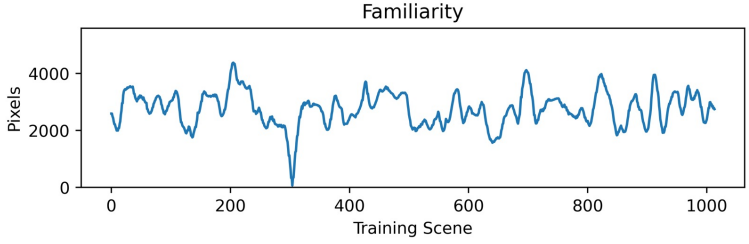
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

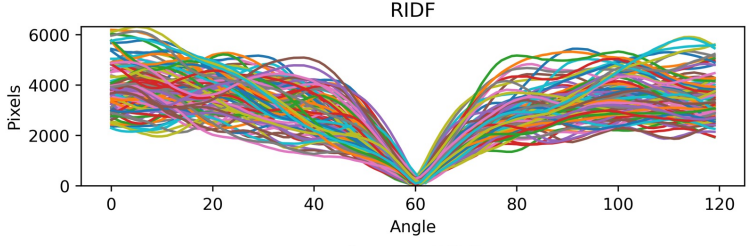
Navigation stats: RMSD error: 43.01; RMSD/dist: 0.108; TD: 2961; p90: 38; p50: 16; complete: 0

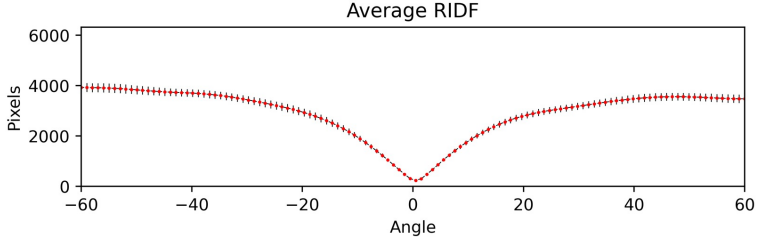
100%







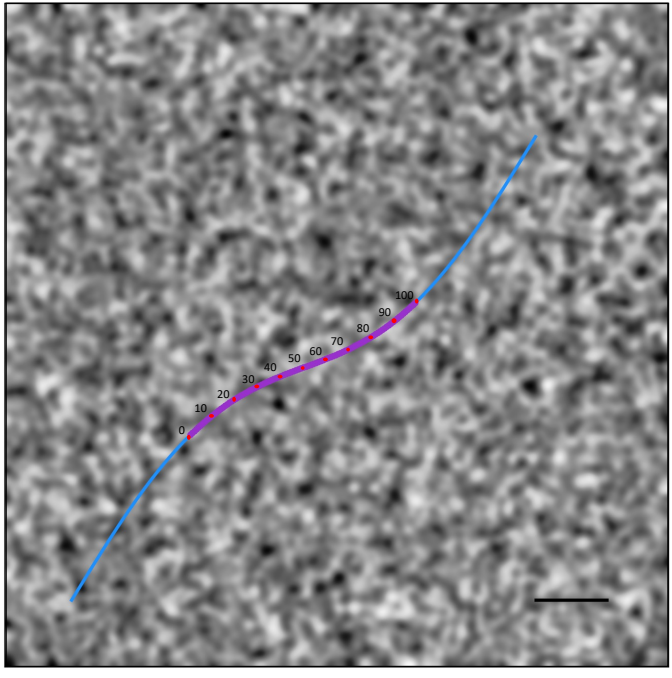


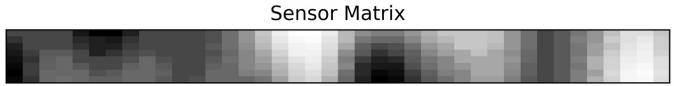


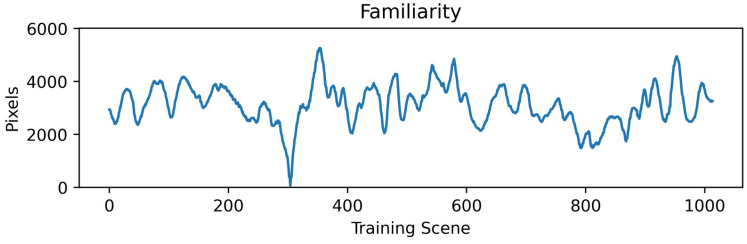
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

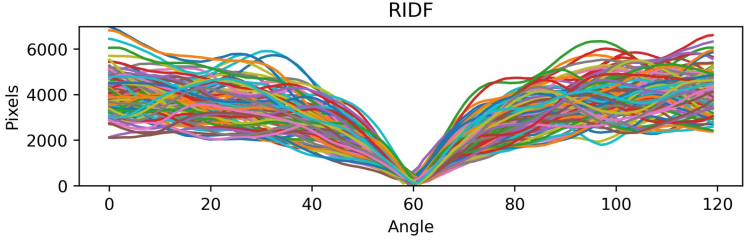
Navigation stats: RMSD error: 60.86; RMSD/dist: 0.152; TD: 2626; p90: 32; p50: 16; complete: 0

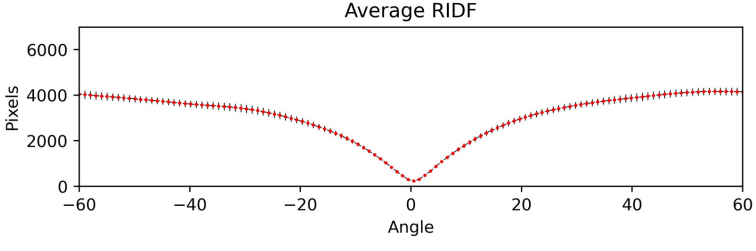
100%







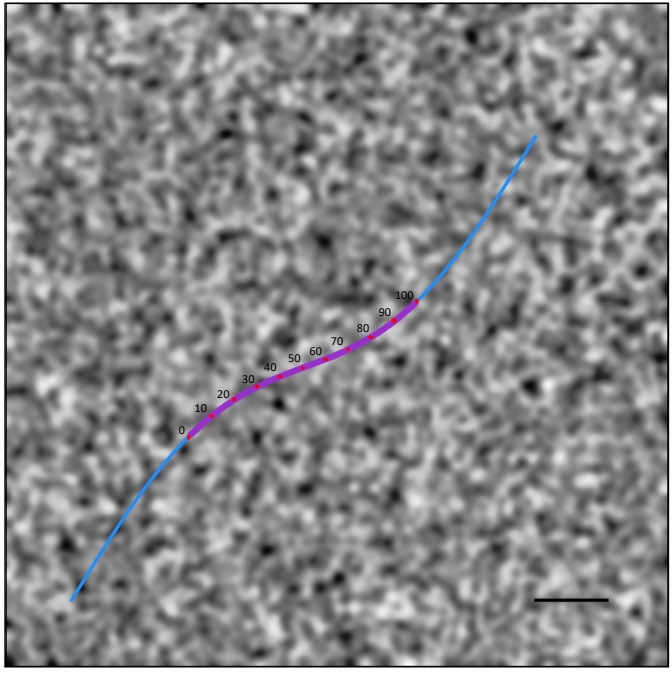


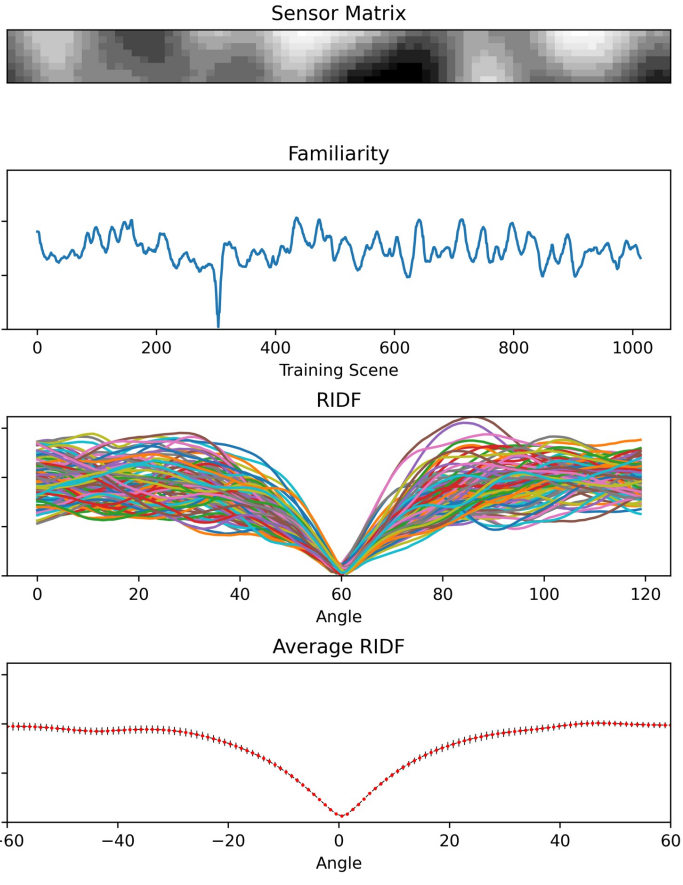


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 53.89; RMSD/dist: 0.135; TD: 2941; p90: 40; p50: 18; complete: 0

100%

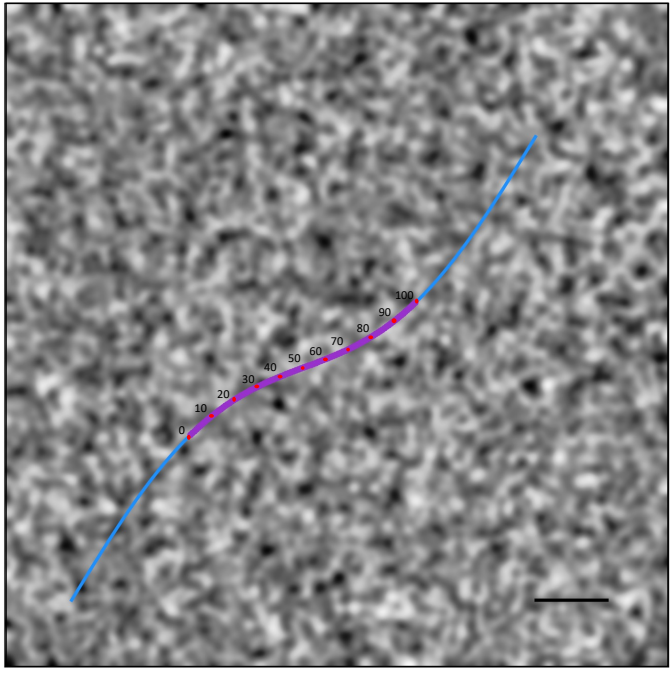


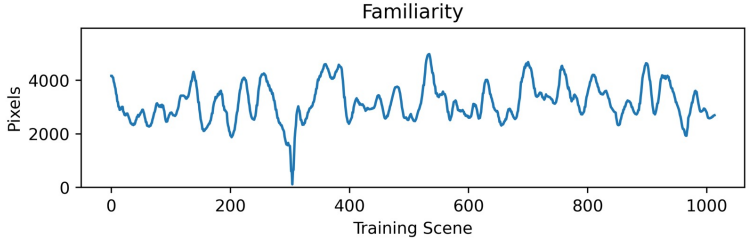


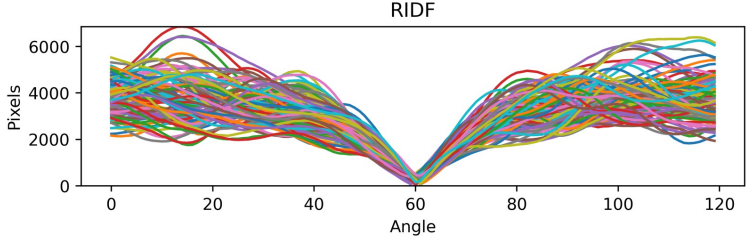
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

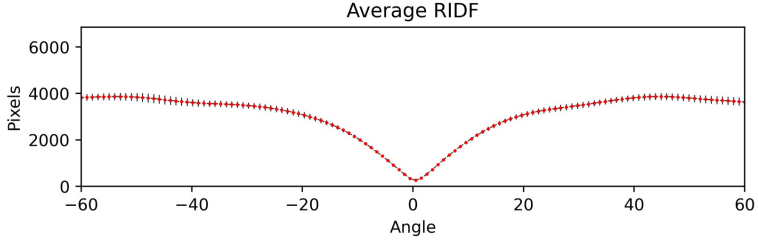
Navigation stats: RMSD error: 54.23; RMSD/dist: 0.136; TD: 2751; p90: 30; p50: 16; complete: 0

100%



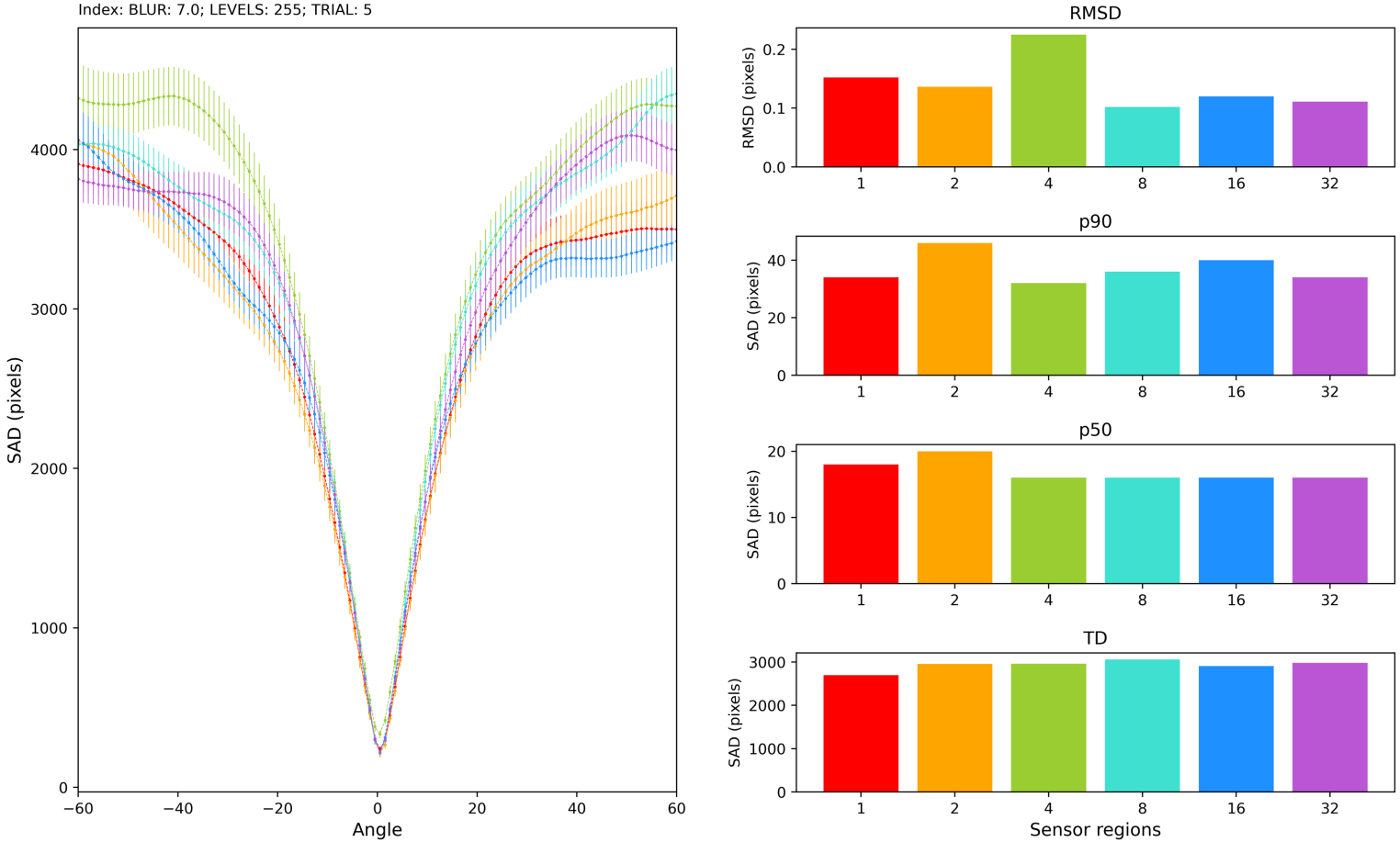




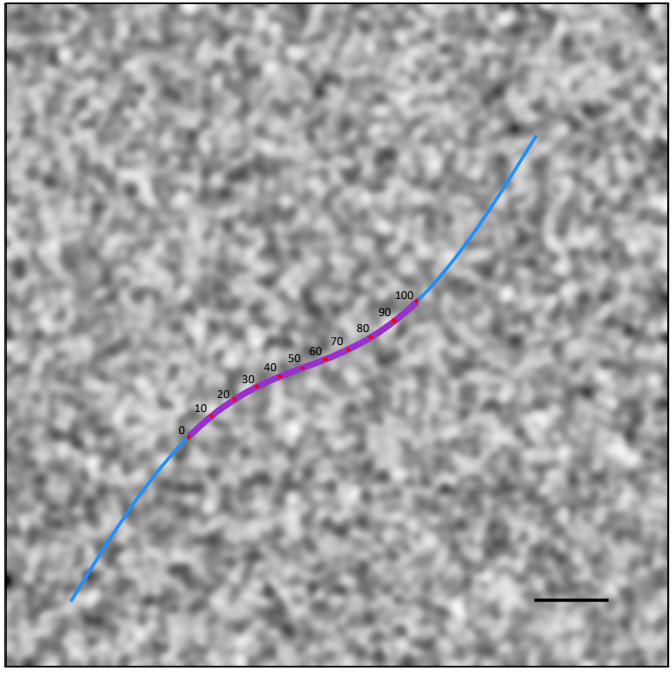


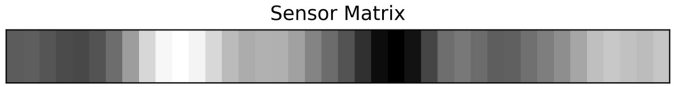
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

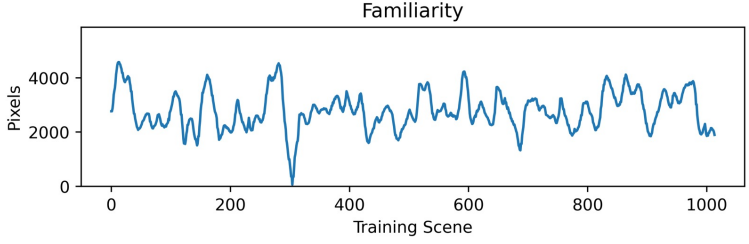
Navigation stats: RMSD error: 60.55; RMSD/dist: 0.151; TD: 2750; p90: 32; p50: 16; complete: 0

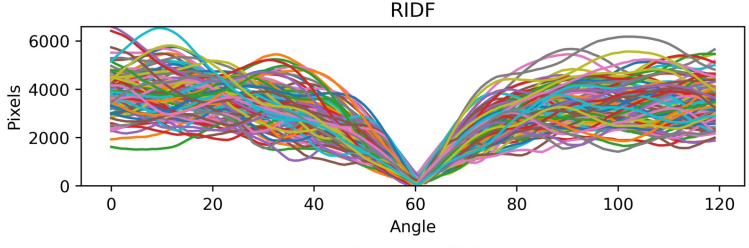

Index: BLUR: 7.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

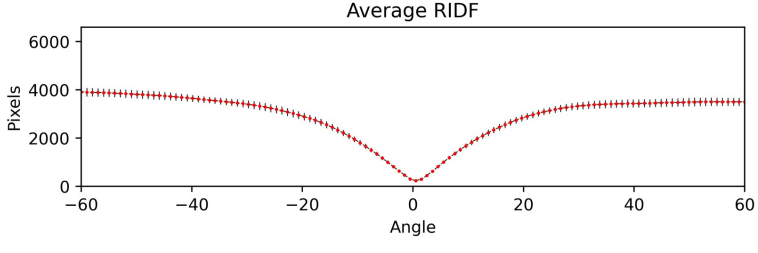
100%







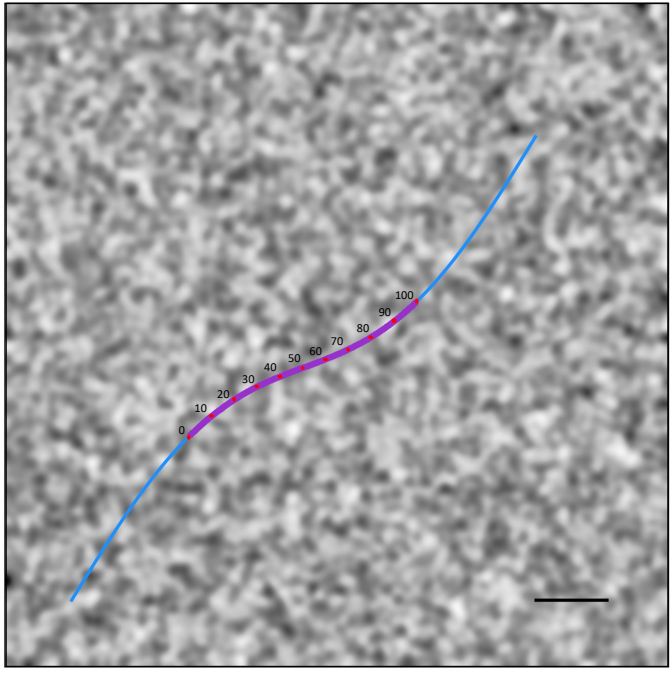


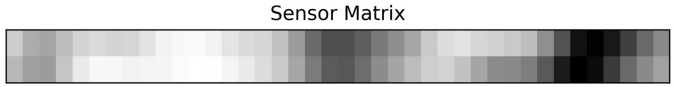


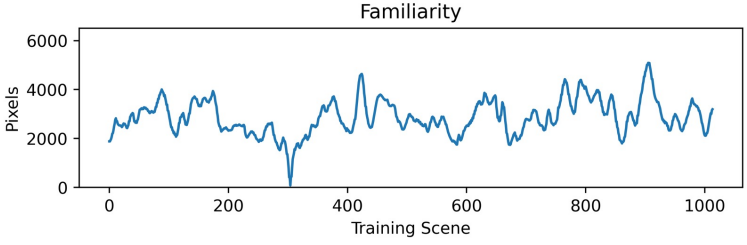
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

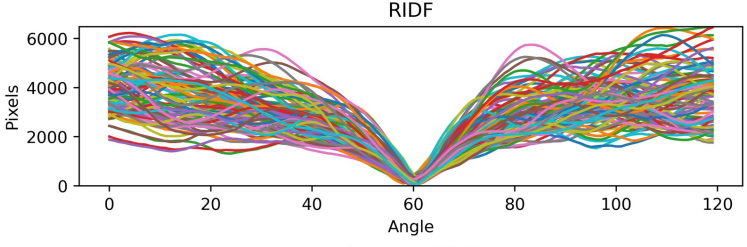
Navigation stats: RMSD error: 60.89; RMSD/dist: 0.152; TD: 2698; p90: 34; p50: 18; complete: 0

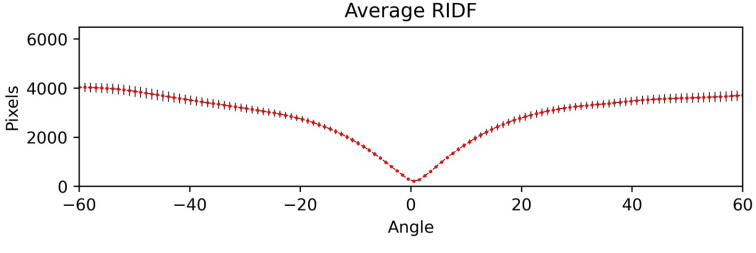
100%







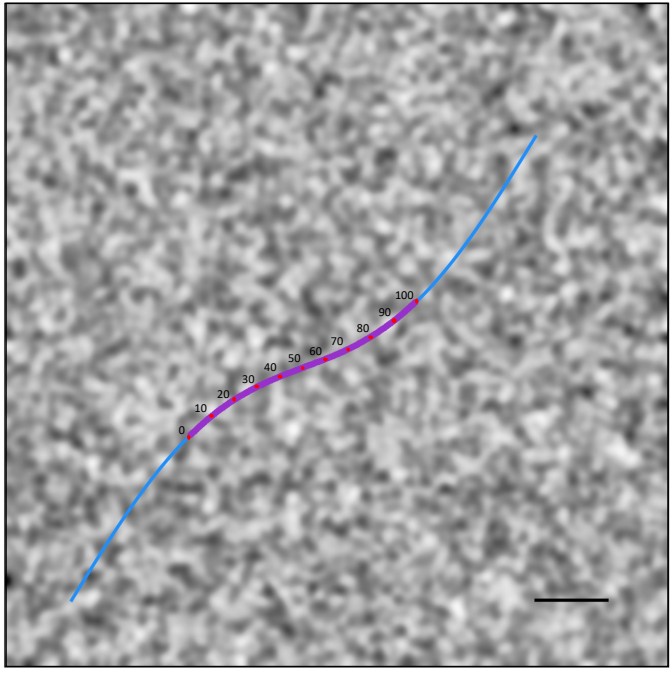


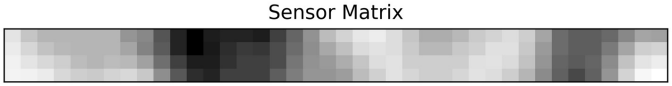


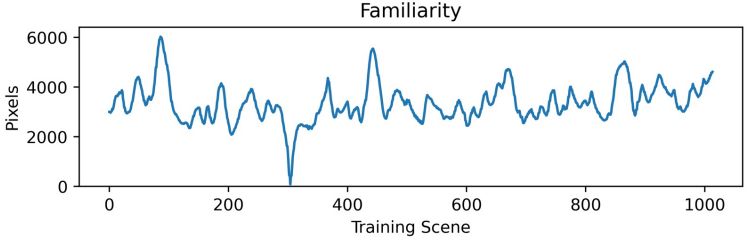
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

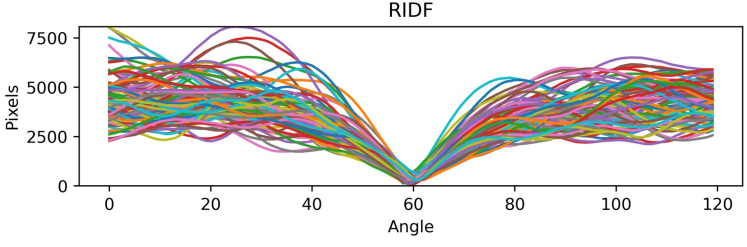
Navigation stats: RMSD error: 54.32; RMSD/dist: 0.136; TD: 2958; p90: 46; p50: 20; complete: 0

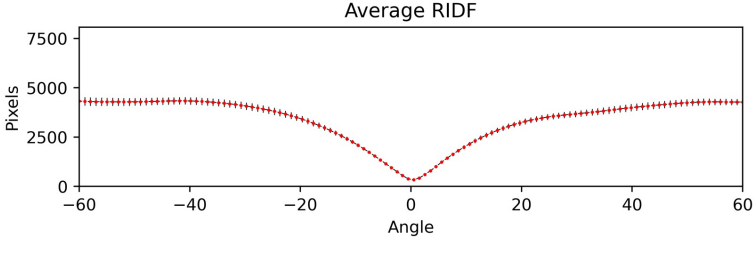
100%







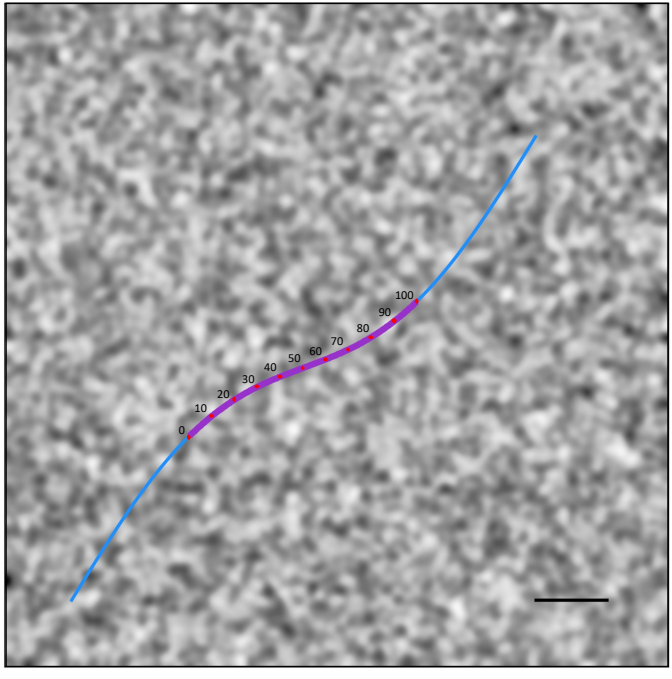


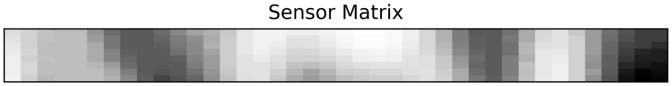


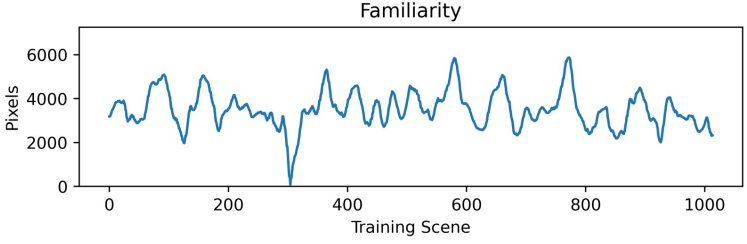
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

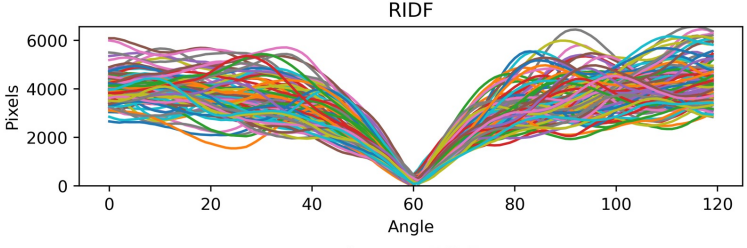
Navigation stats: RMSD error: 89.90; RMSD/dist: 0.225; TD: 2964; p90: 32; p50: 16; complete: 0

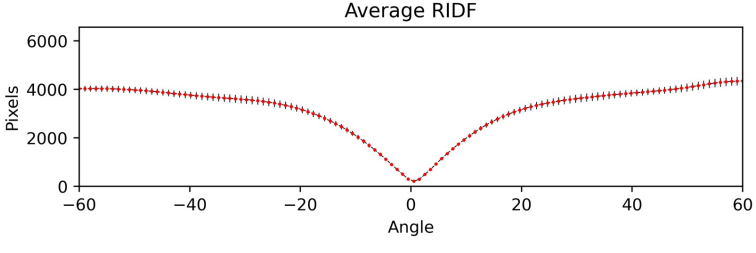
100%







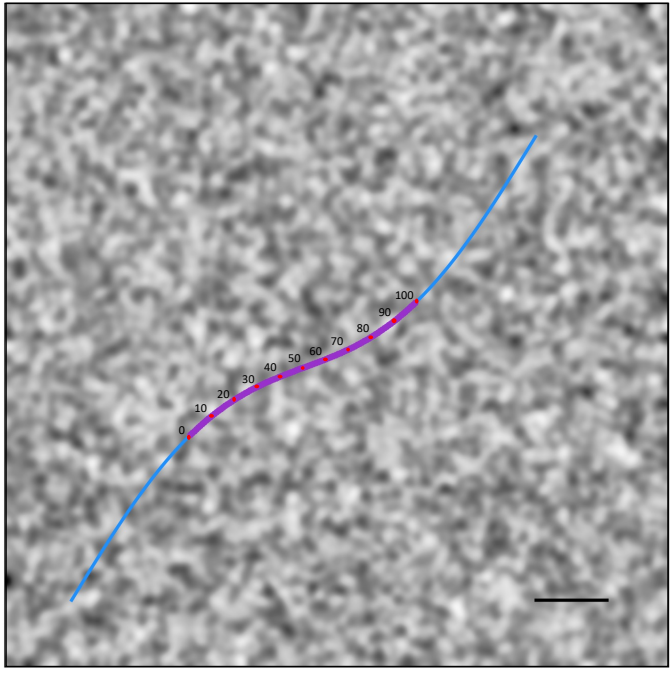


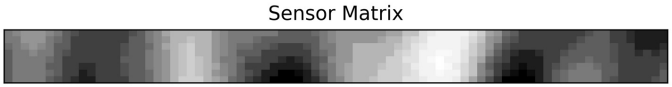


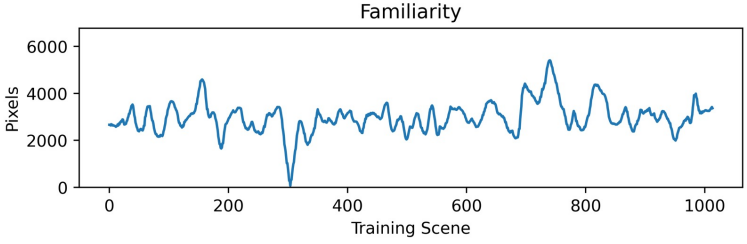
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

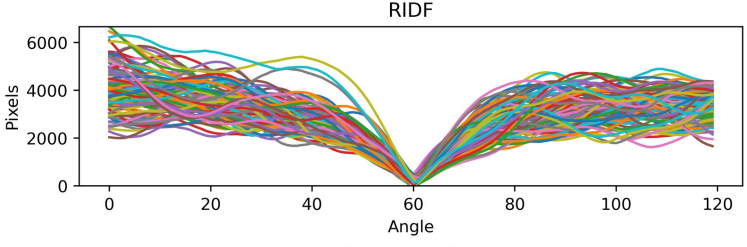
Navigation stats: RMSD error: 40.74; RMSD/dist: 0.102; TD: 3058; p90: 36; p50: 16; complete: 0

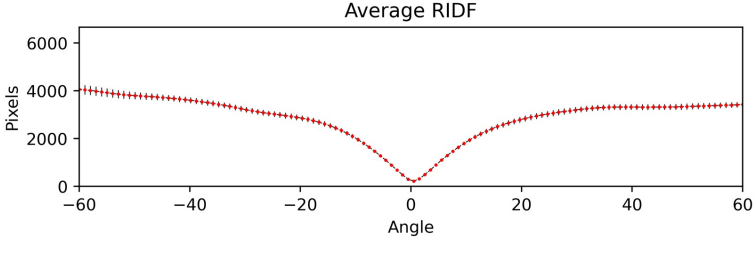
100%







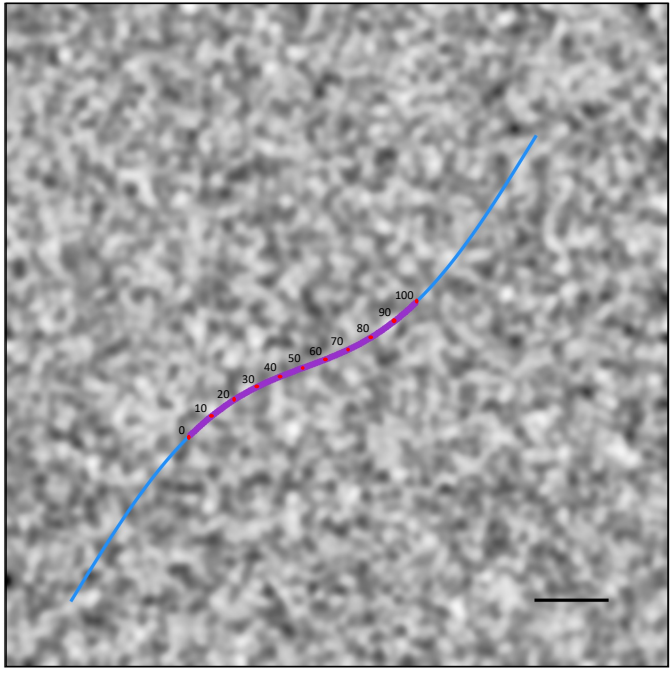


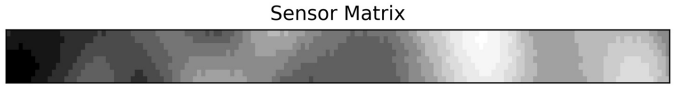


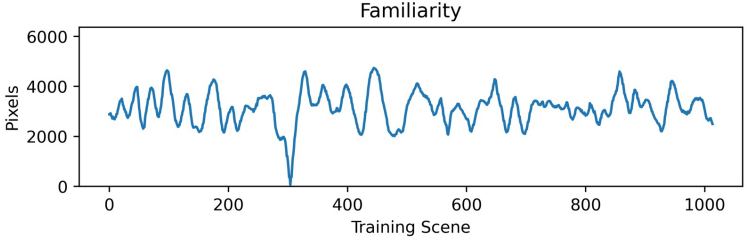
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

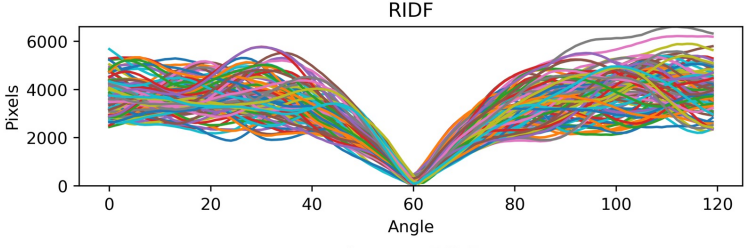
Navigation stats: RMSD error: 48.06; RMSD/dist: 0.120; TD: 2909; p90: 40; p50: 16; complete: 0

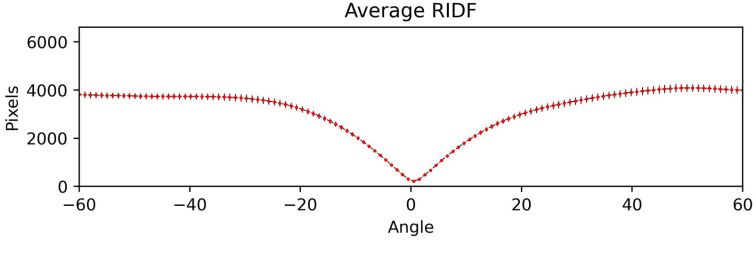
100%





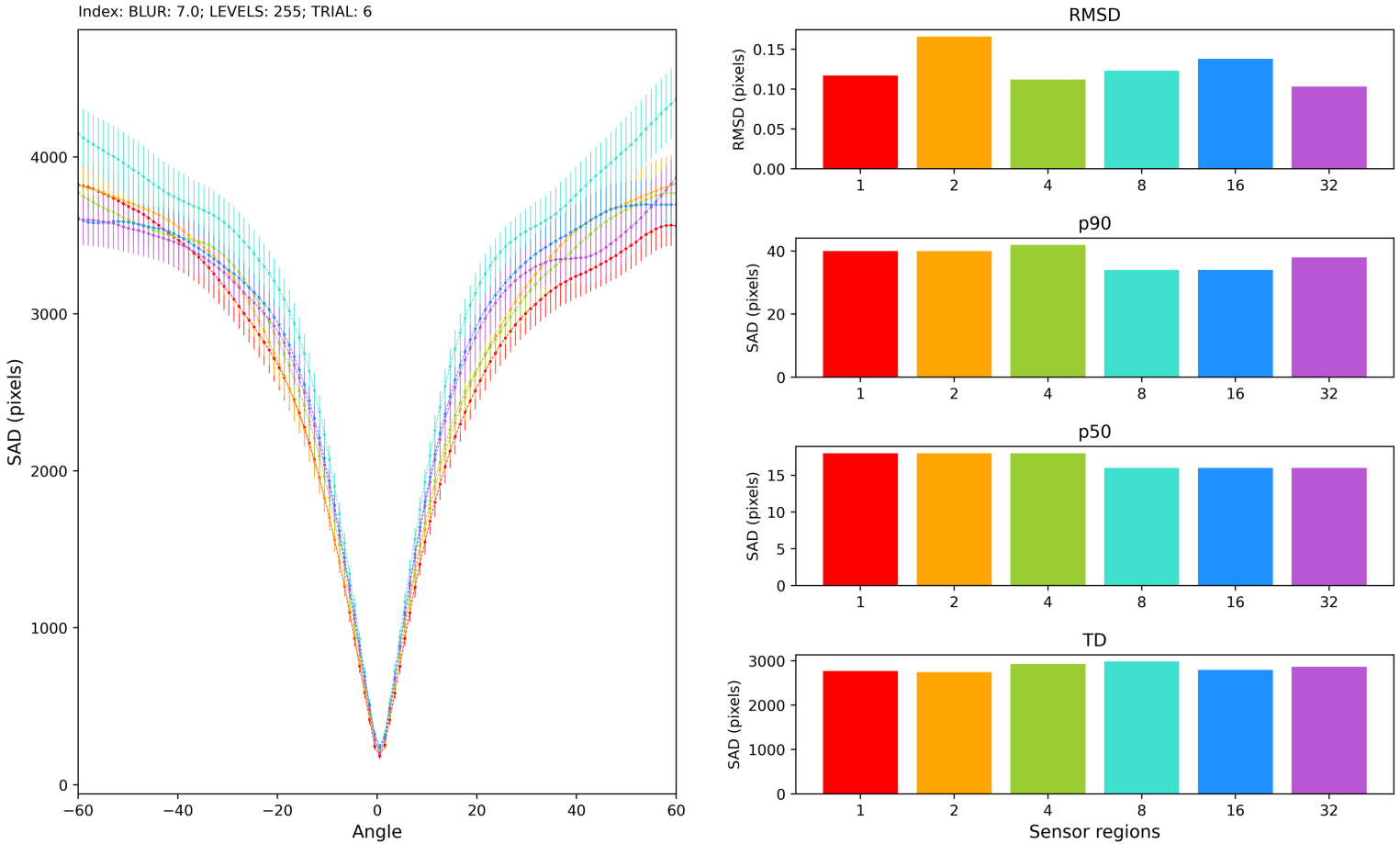




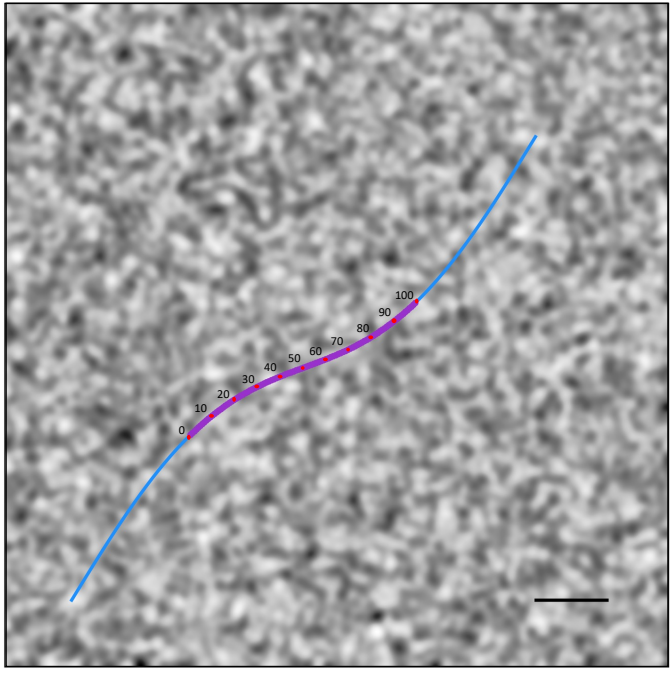


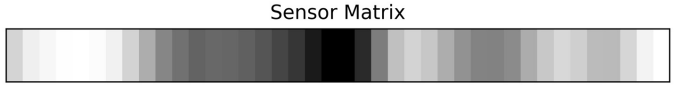
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

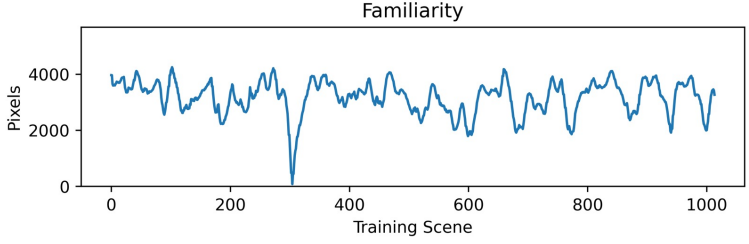
Navigation stats: RMSD error: 44.50; RMSD/dist: 0.111; TD: 2980; p90: 34; p50: 16; complete: 0

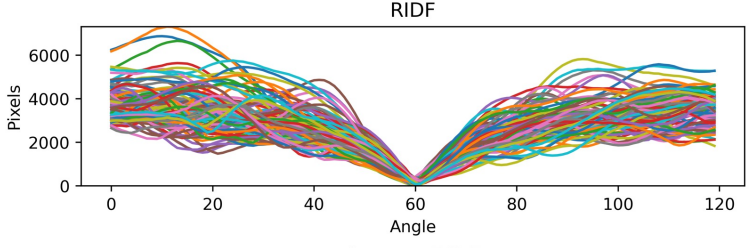

Index: BLUR: 7.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

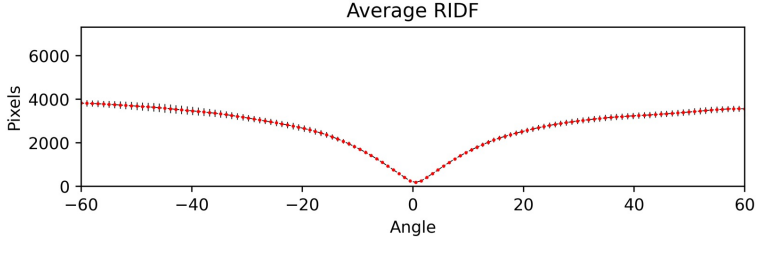
100%







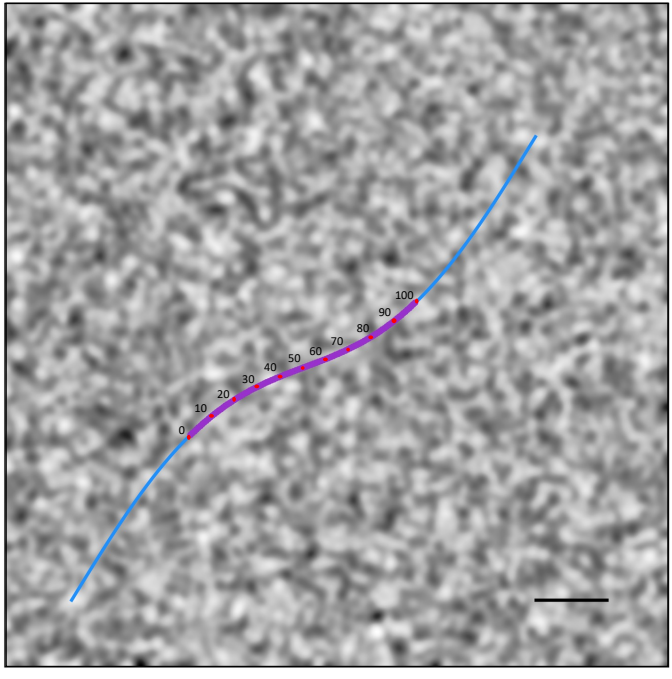


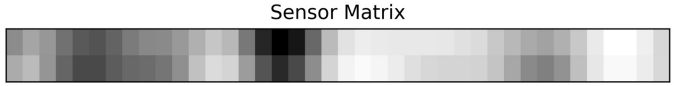


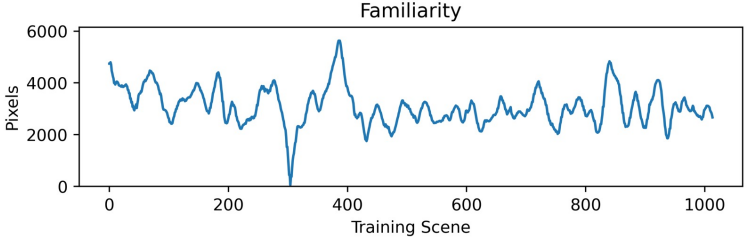
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

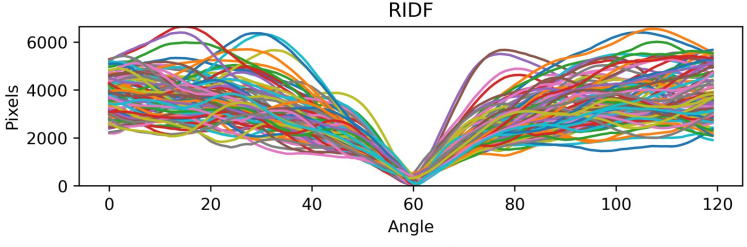
Navigation stats: RMSD error: 46.76; RMSD/dist: 0.117; TD: 2772; p90: 40; p50: 18; complete: 0

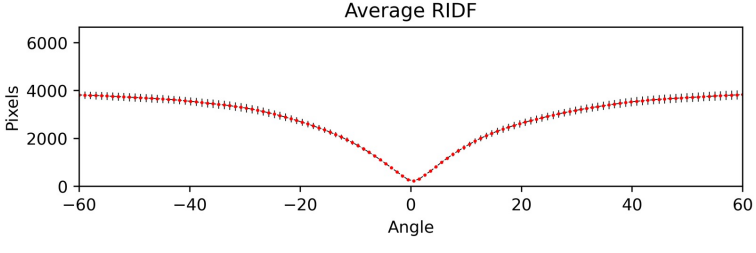
100%







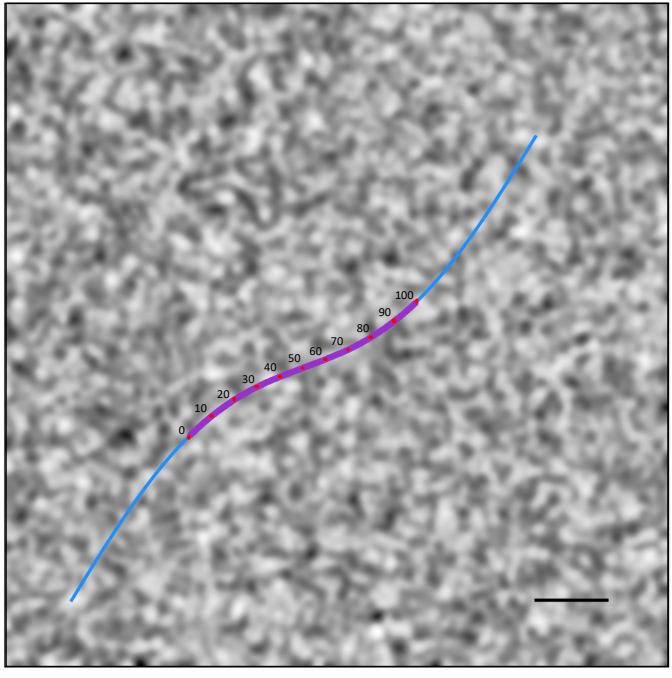


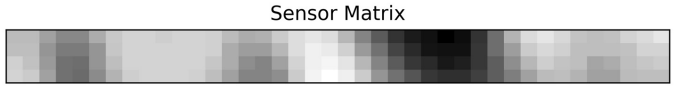


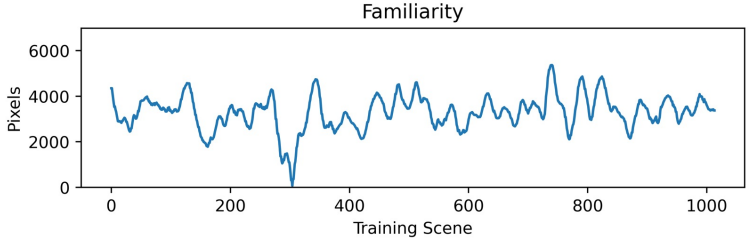
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

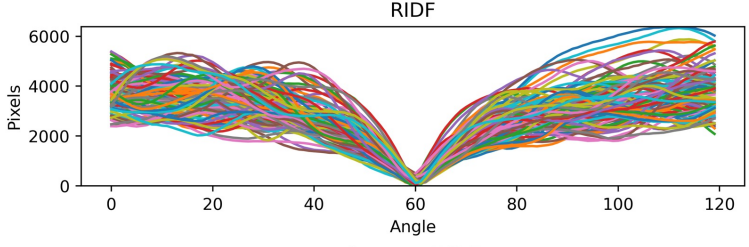
Navigation stats: RMSD error: 66.34; RMSD/dist: 0.166; TD: 2747; p90: 40; p50: 18; complete: 0

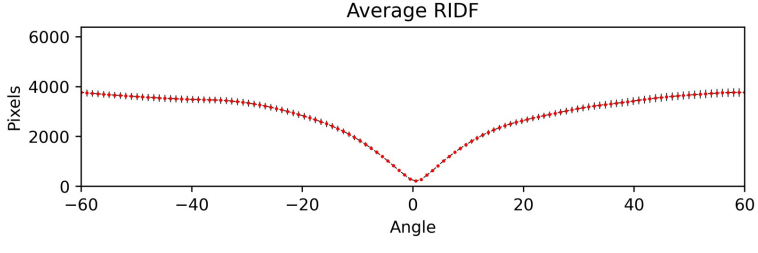
100%











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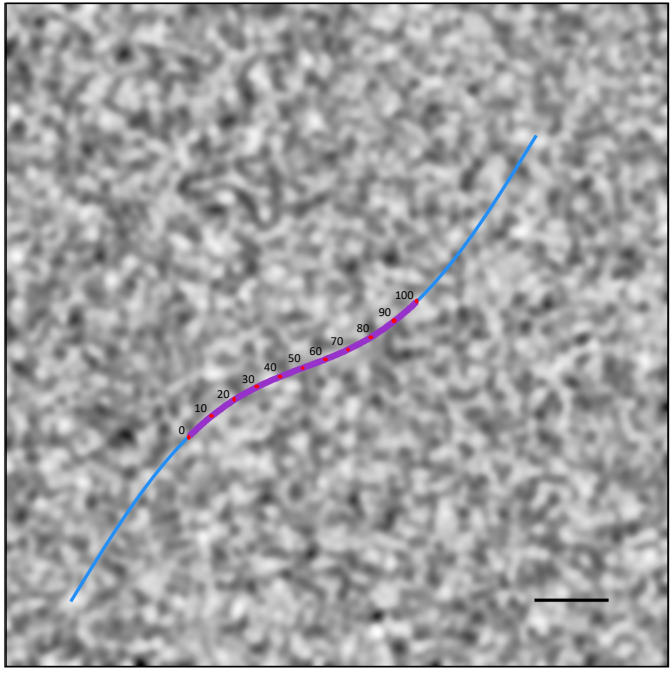
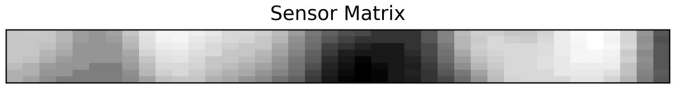
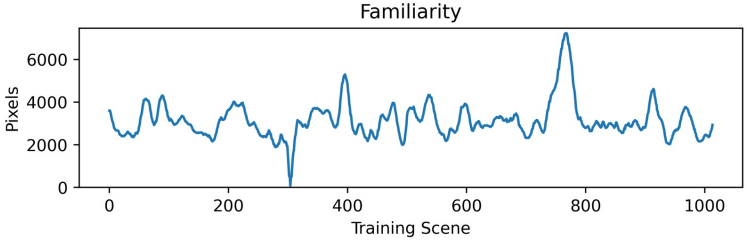
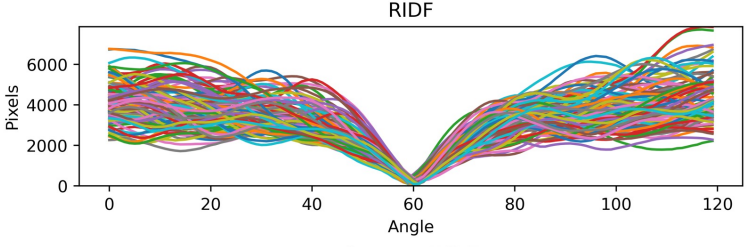
Navigation stats: RMSD error: 44.80; RMSD/dist: 0.112; TD: 2929; p90: 42; p50: 18; complete: 0

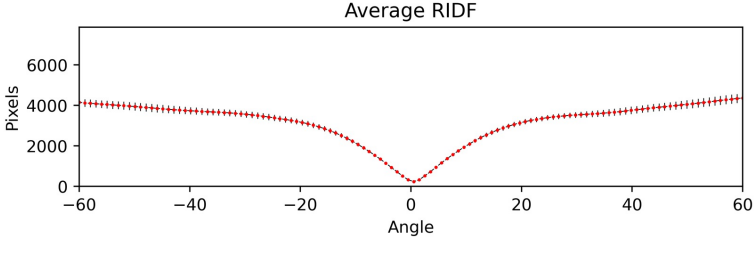
100%







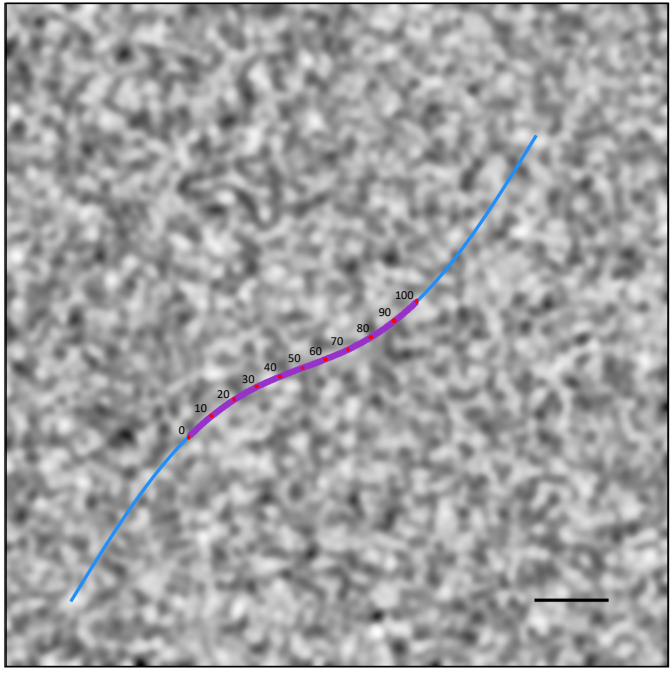


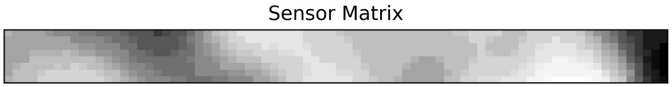


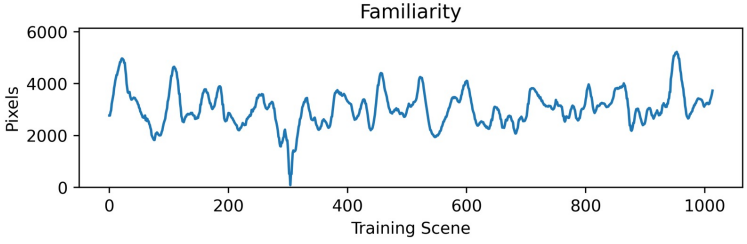
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

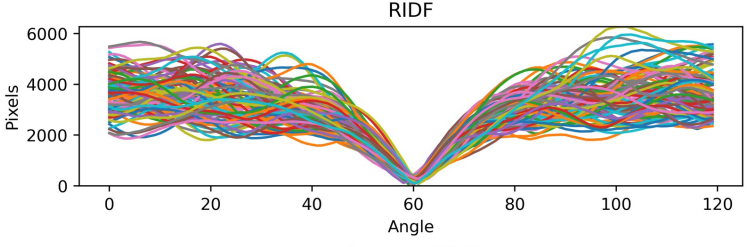
Navigation stats: RMSD error: 49.25; RMSD/dist: 0.123; TD: 2984; p90: 34; p50: 16; complete: 0

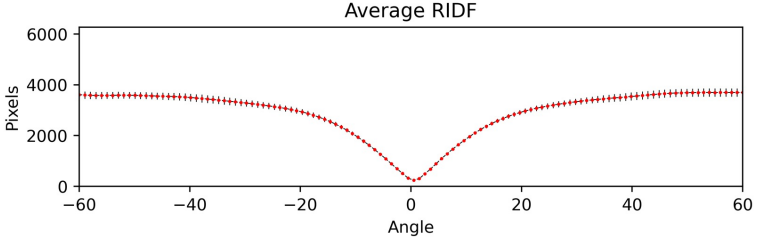
100%







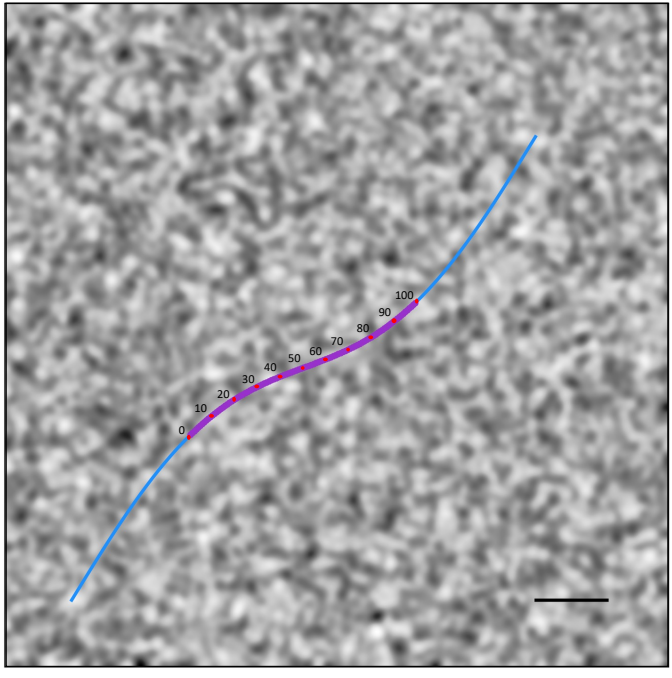


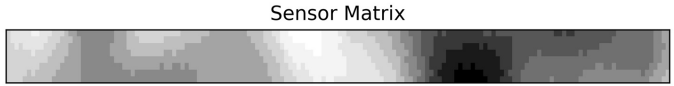


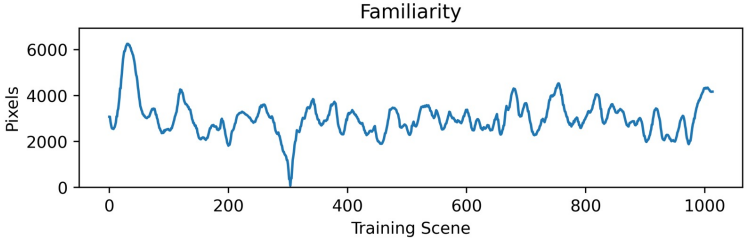
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

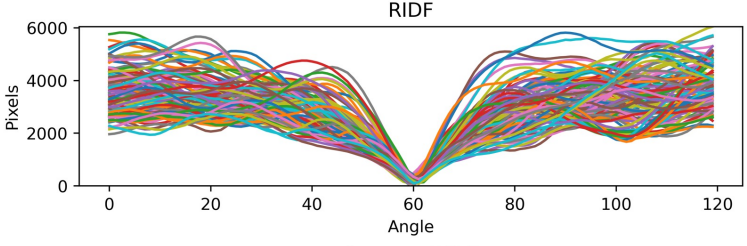
Navigation stats: RMSD error: 55.32; RMSD/dist: 0.138; TD: 2797; p90: 34; p50: 16; complete: 0

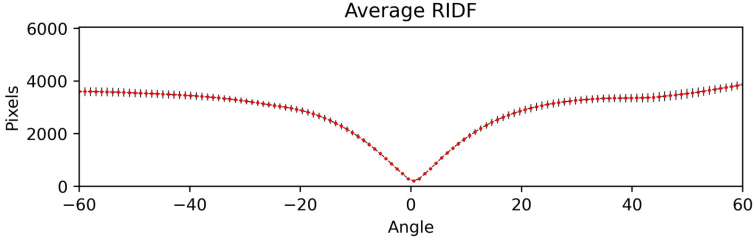
100%





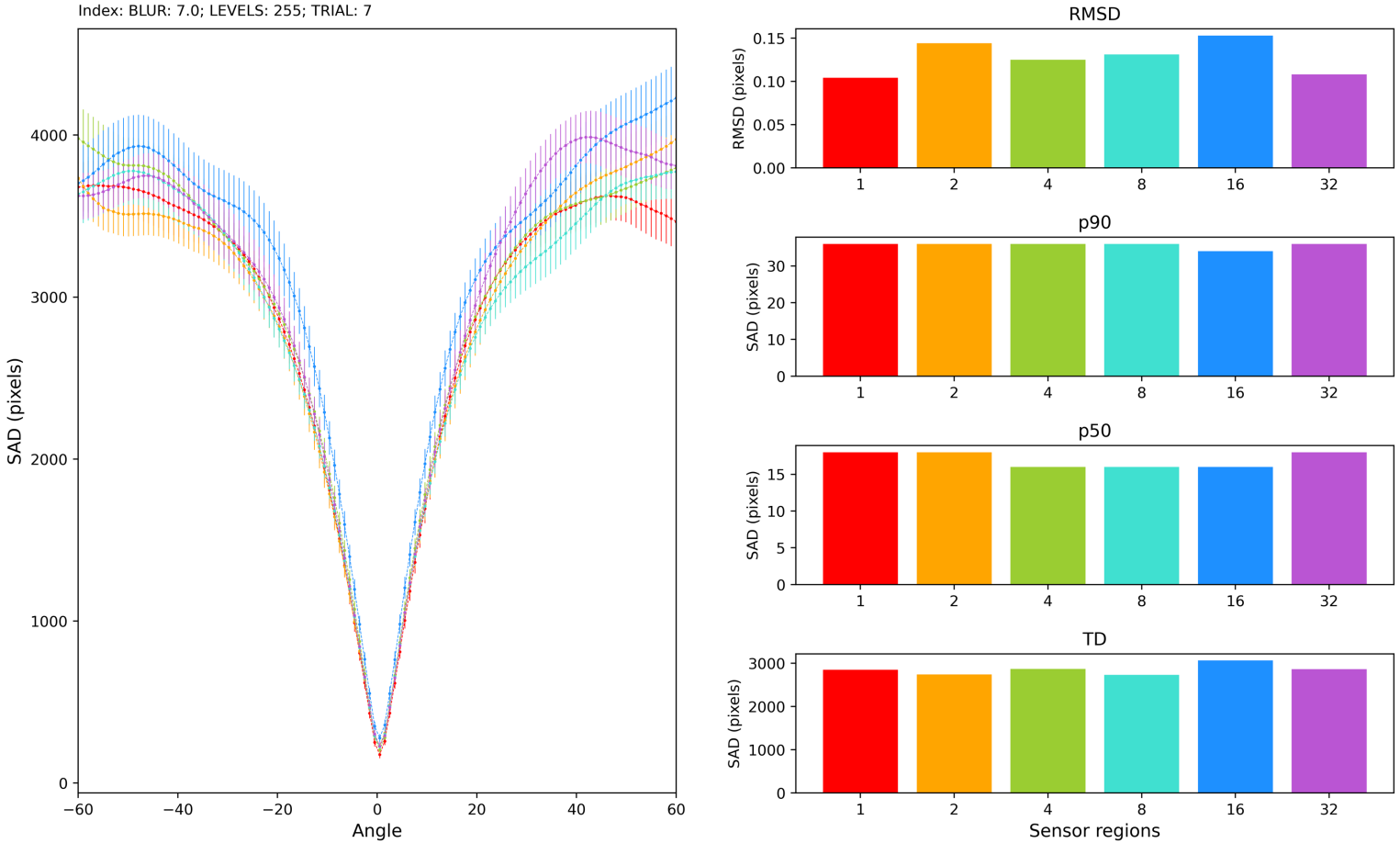




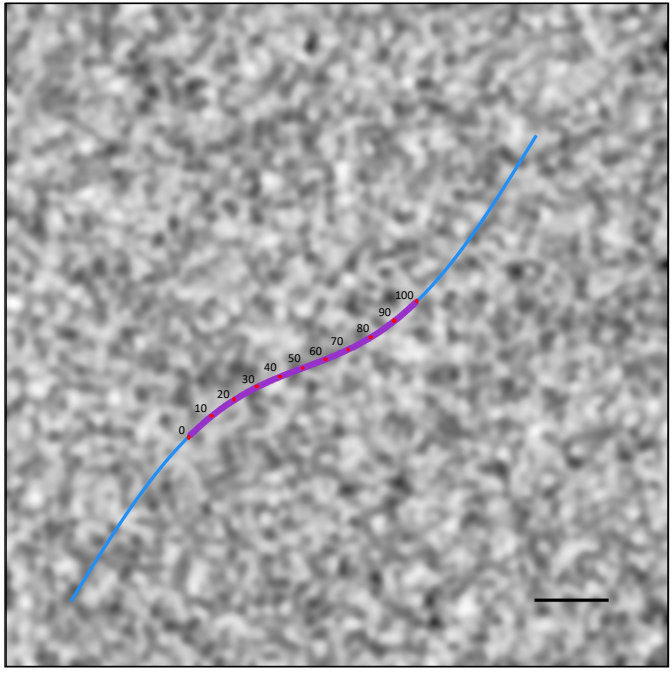


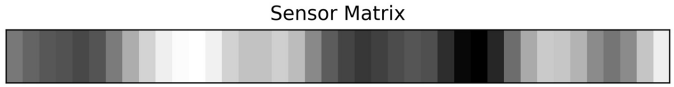
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

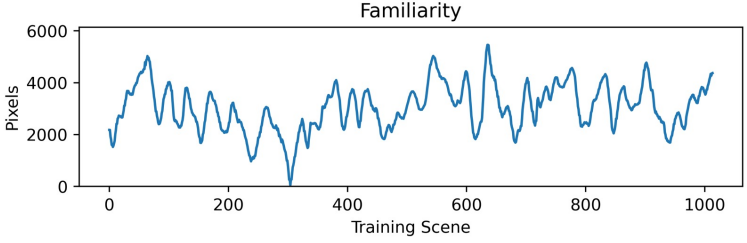
Navigation stats: RMSD error: 41.28; RMSD/dist: 0.103; TD: 2869; p90: 38; p50: 16; complete: 0

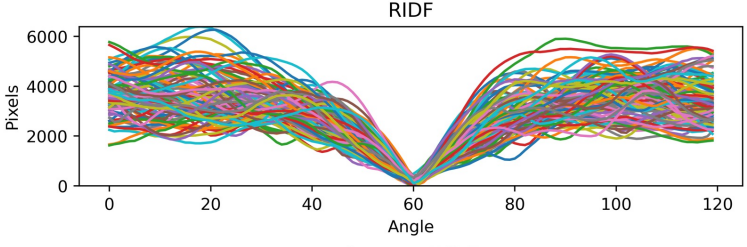

Index: BLUR: 7.0; LEVELS: 255; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

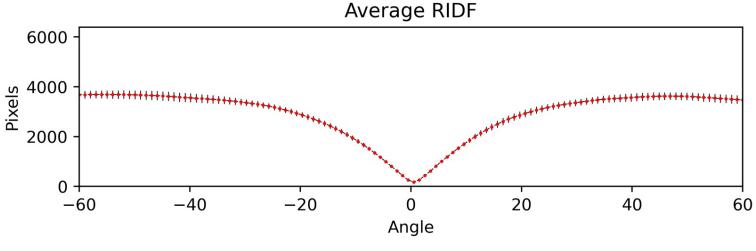
100%







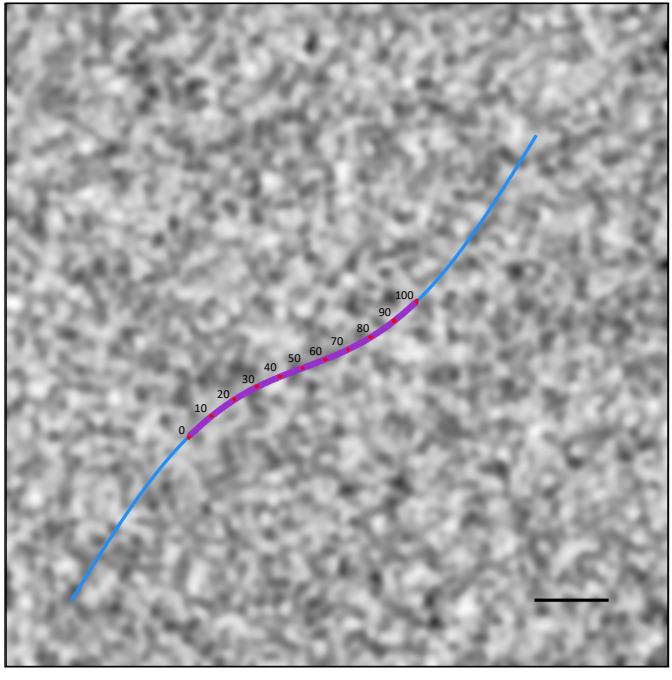


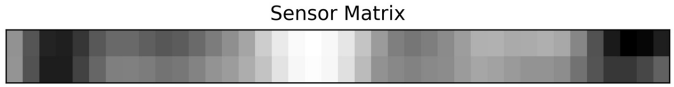


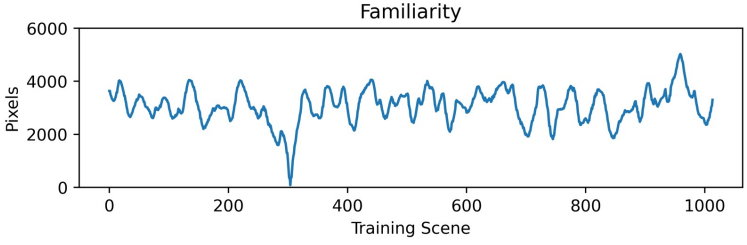
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

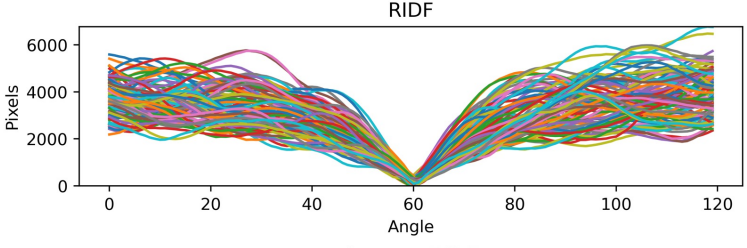
Navigation stats: RMSD error: 41.52; RMSD/dist: 0.104; TD: 2850; p90: 36; p50: 18; complete: 0

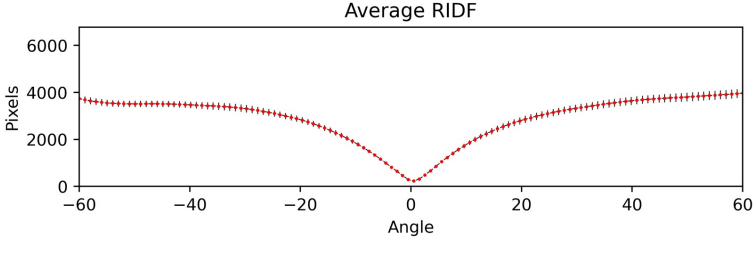
100%







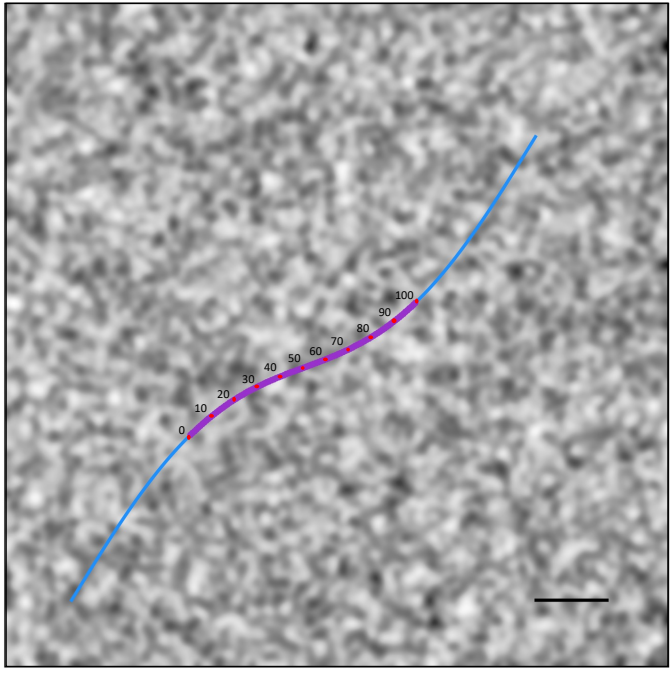


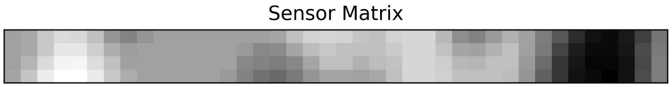


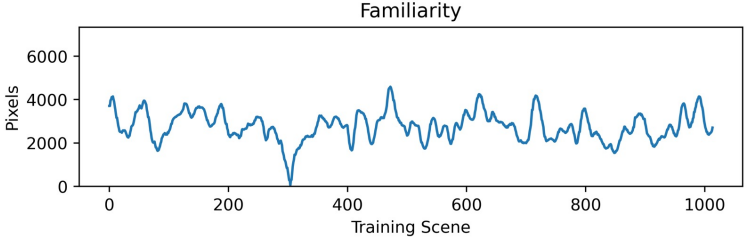
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

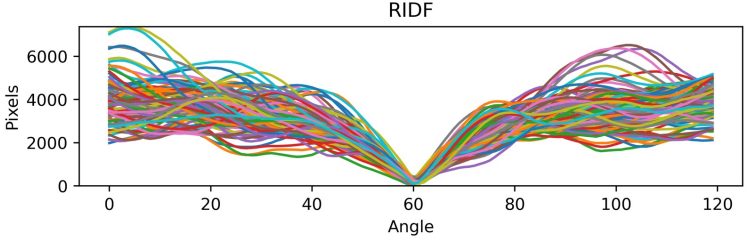
Navigation stats: RMSD error: 57.64; RMSD/dist: 0.144; TD: 2742; p90: 36; p50: 18; complete: 0

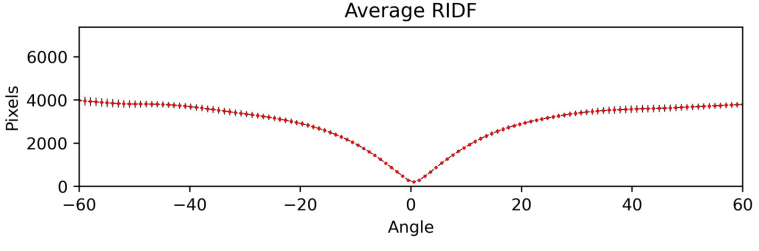
100%







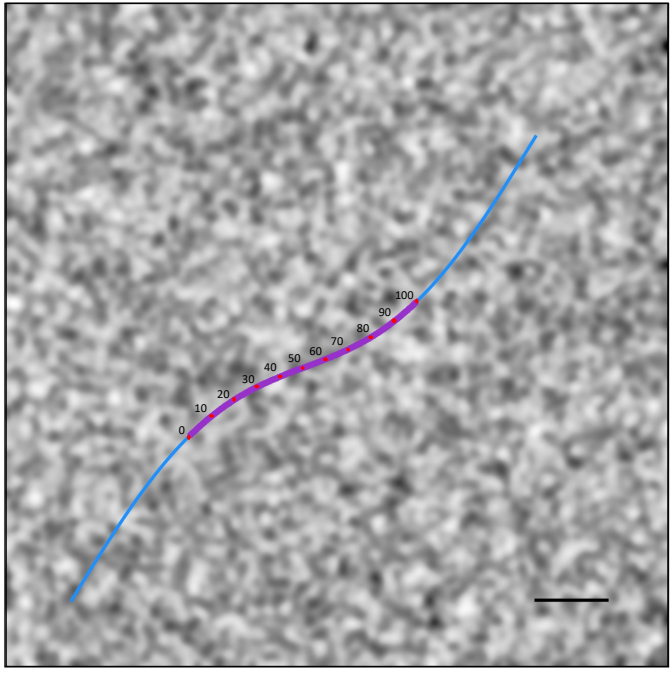


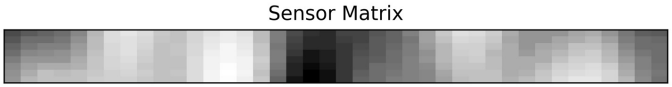


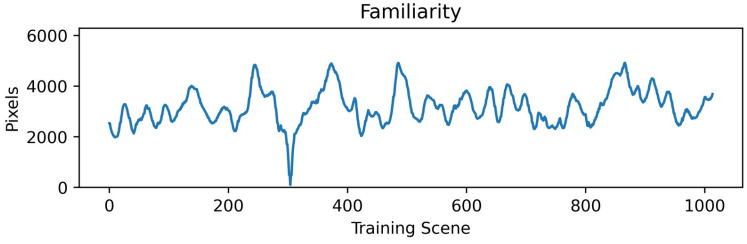
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

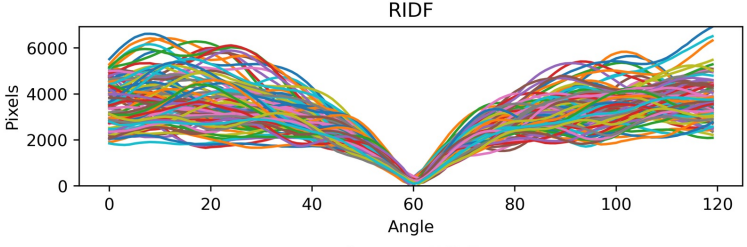
Navigation stats: RMSD error: 50.19; RMSD/dist: 0.125; TD: 2866; p90: 36; p50: 16; complete: 0

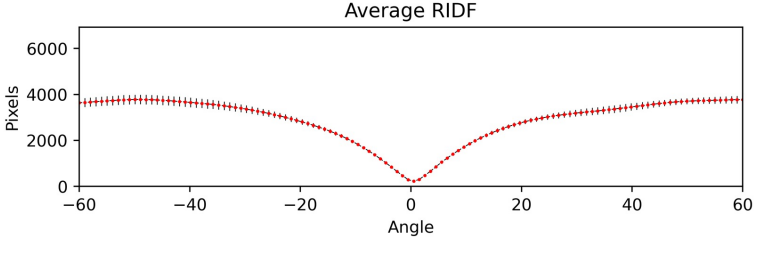
100%







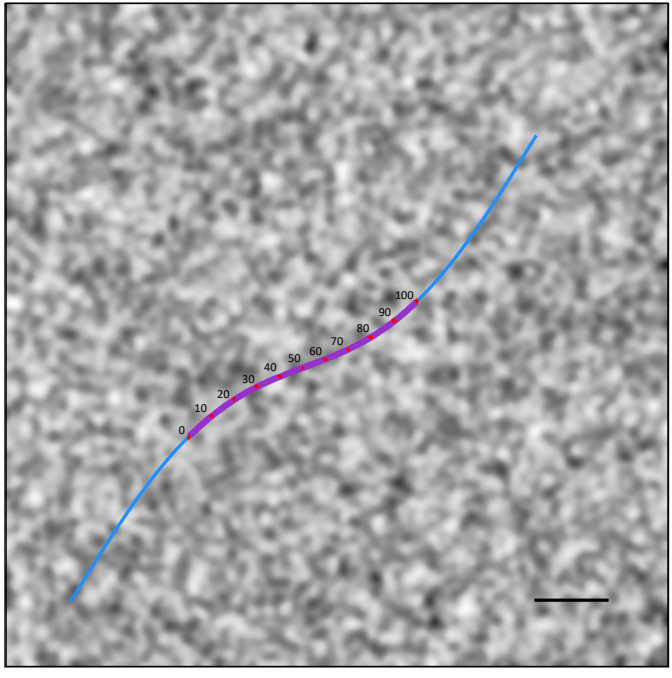


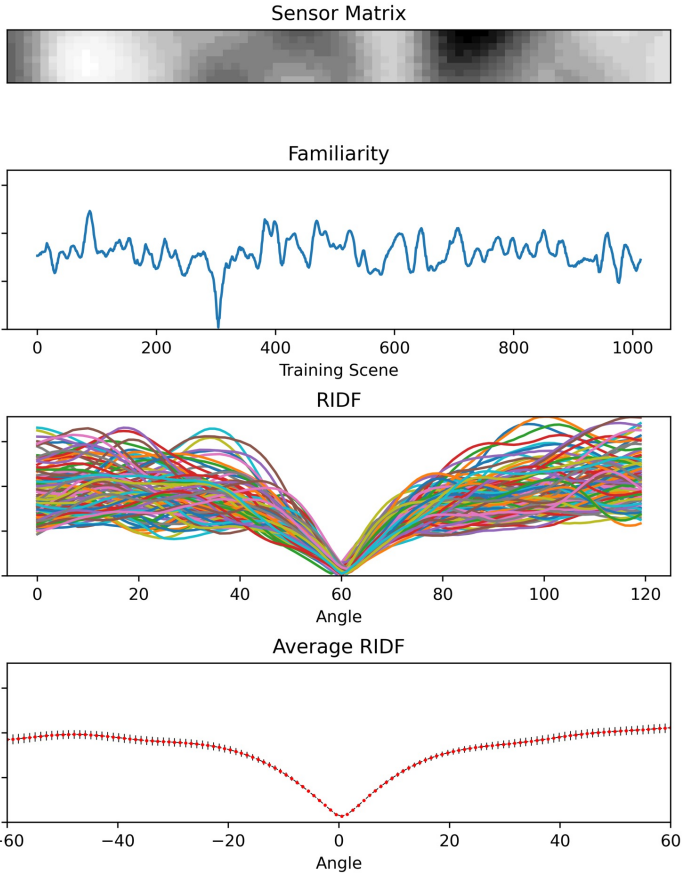


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 52.25; RMSD/dist: 0.131; TD: 2729; p90: 36; p50: 16; complete: 0

100%





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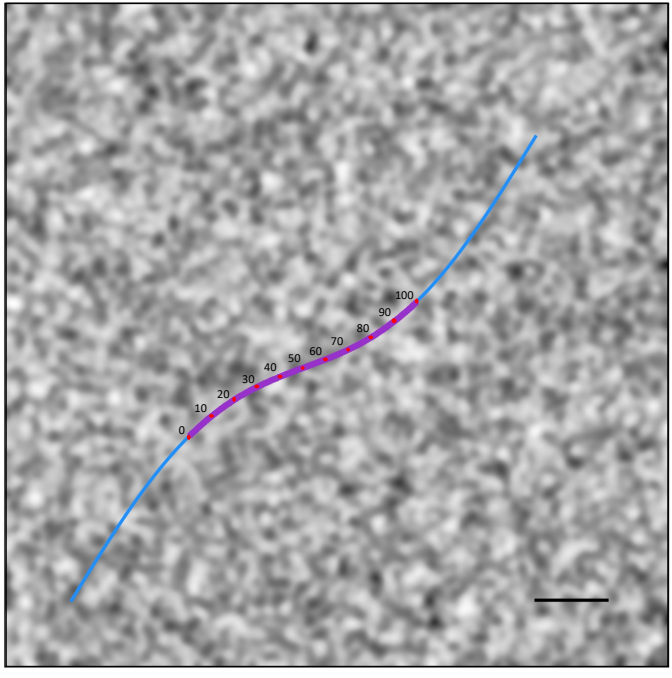
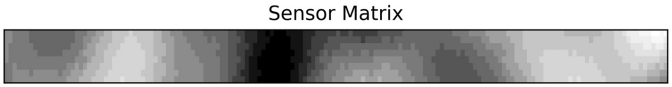
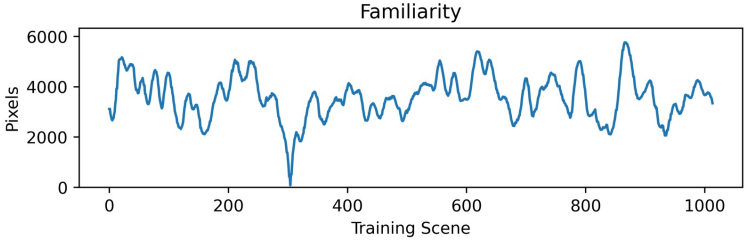
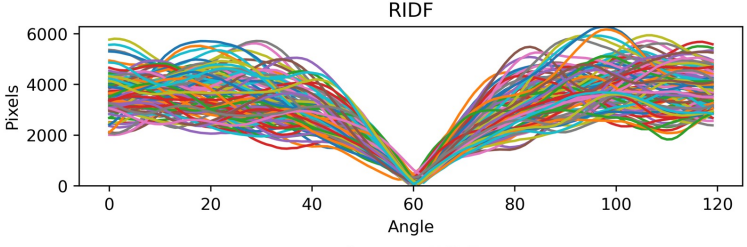
Navigation stats: RMSD error: 61.16; RMSD/dist: 0.153; TD: 3061; p90: 34; p50: 16; complete: 0

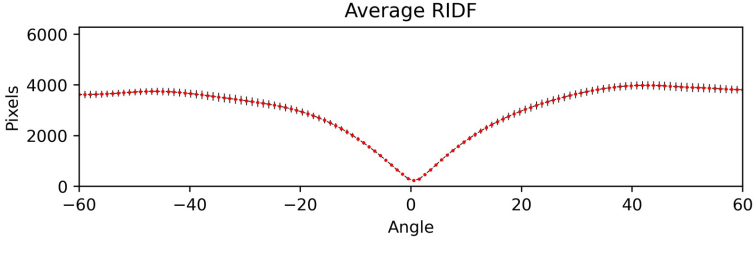
100%





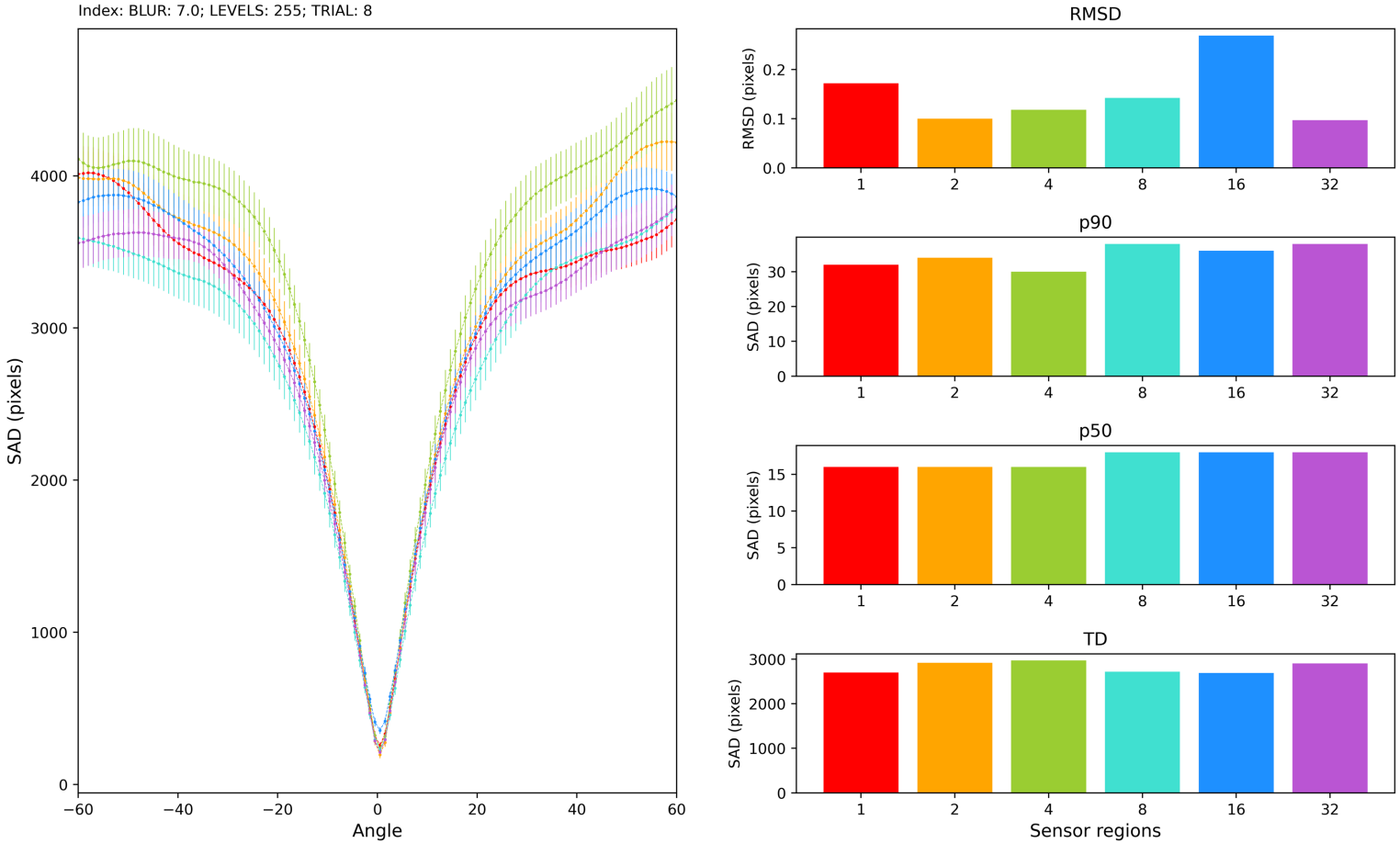




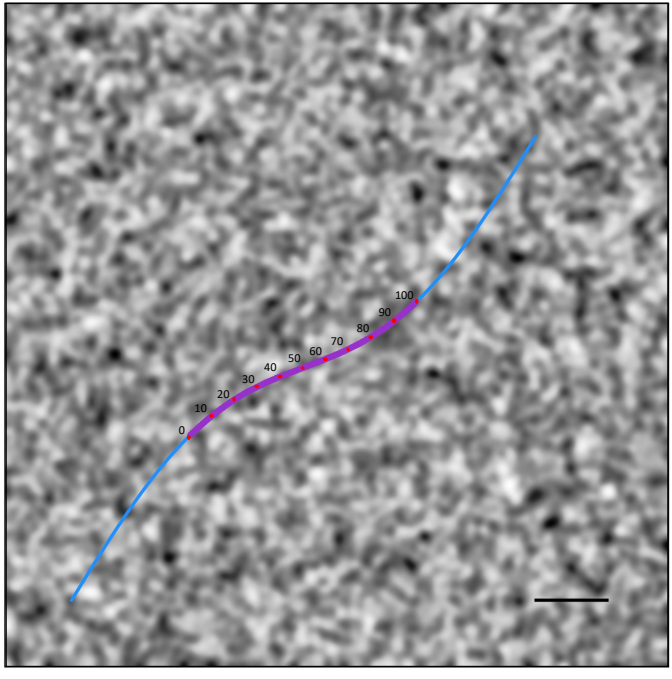


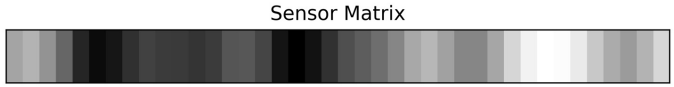
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

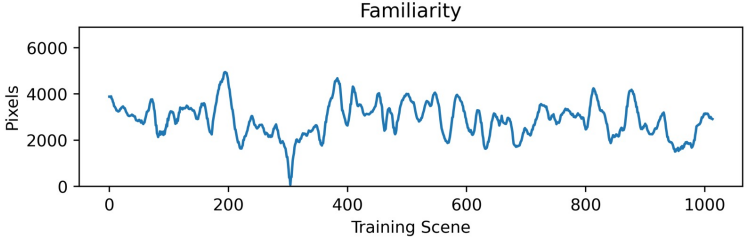
Navigation stats: RMSD error: 43.33; RMSD/dist: 0.108; TD: 2864; p90: 36; p50: 18; complete: 0

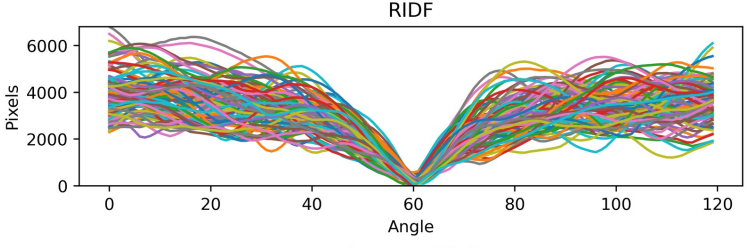

Index: BLUR: 7.0; LEVELS: 255; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

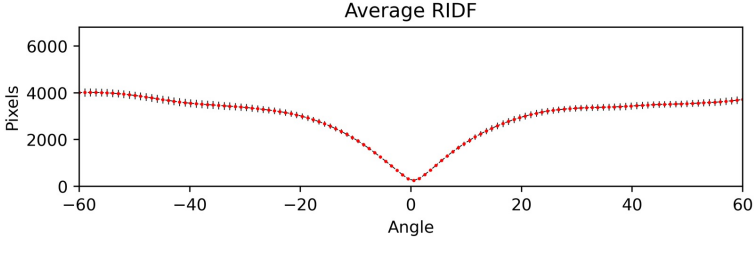
100%







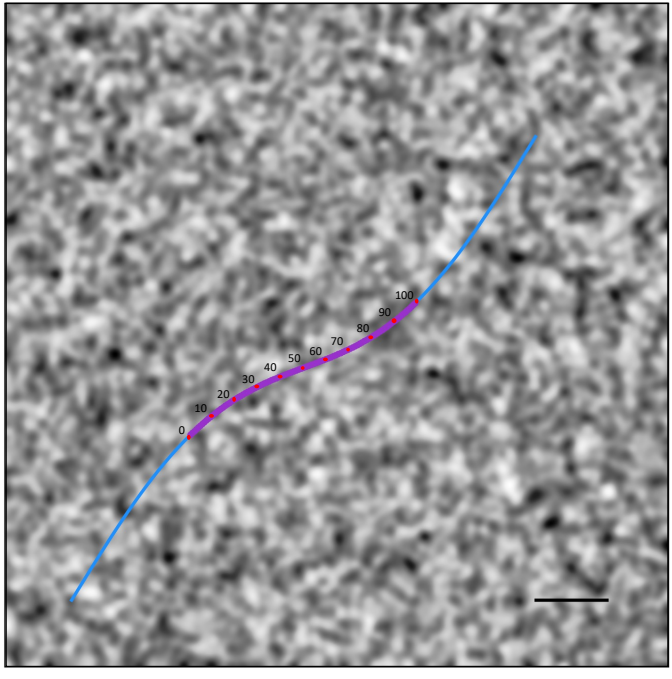


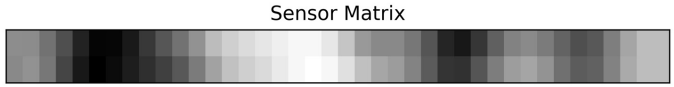


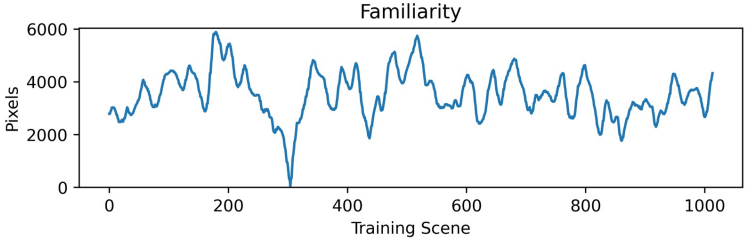
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

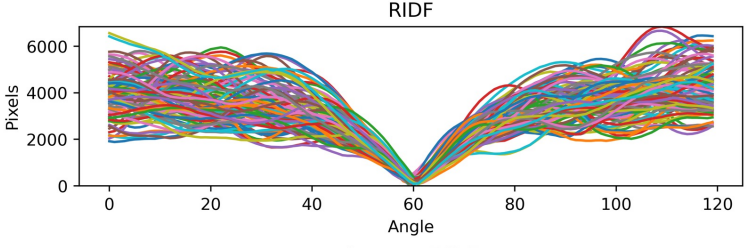
Navigation stats: RMSD error: 68.63; RMSD/dist: 0.172; TD: 2697; p90: 32; p50: 16; complete: 0

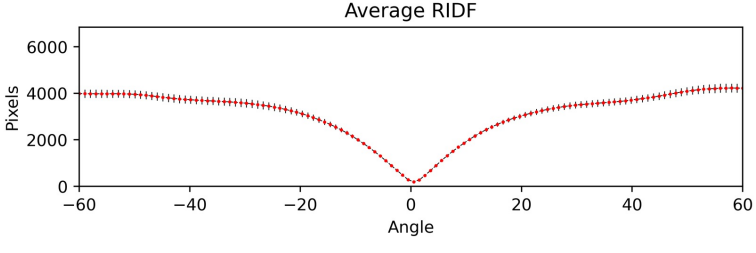
100%







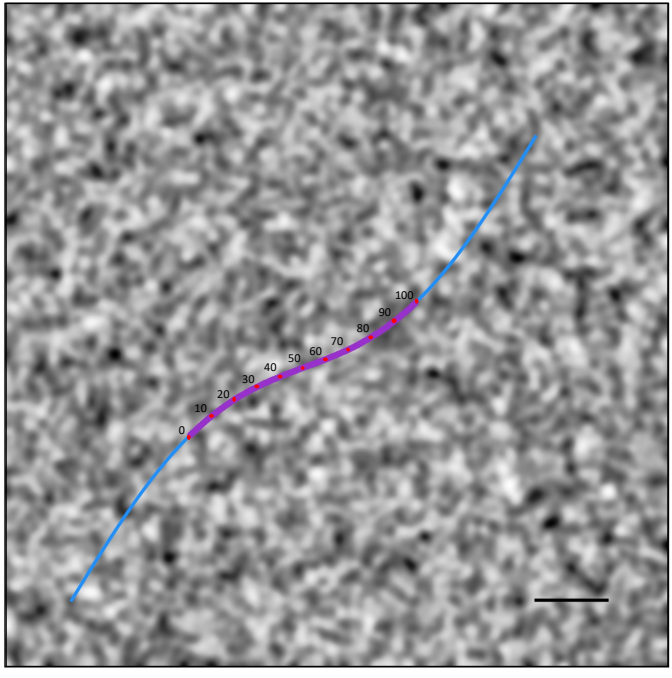


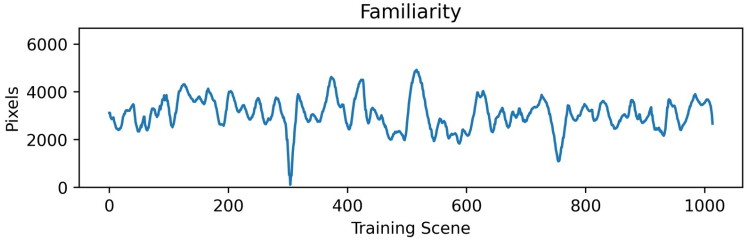


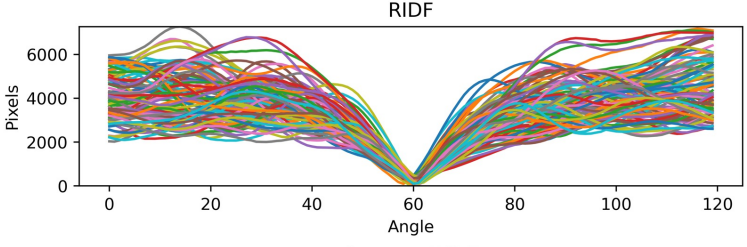
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

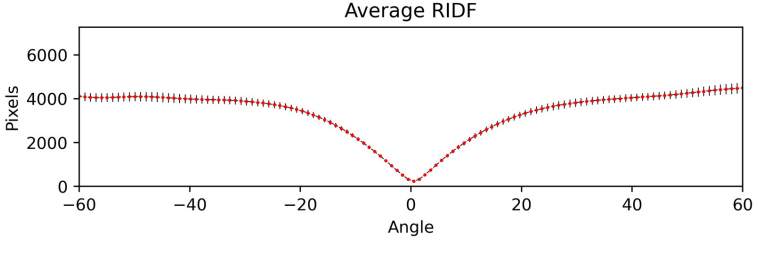
Navigation stats: RMSD error: 39.89; RMSD/dist: 0.100; TD: 2919; p90: 34; p50: 16; complete: 0

100%





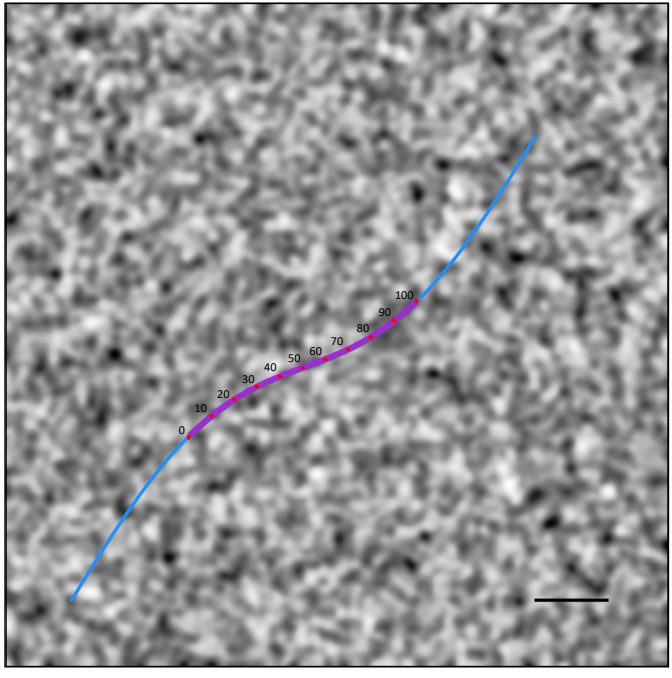


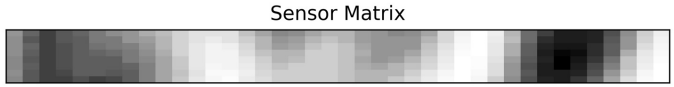


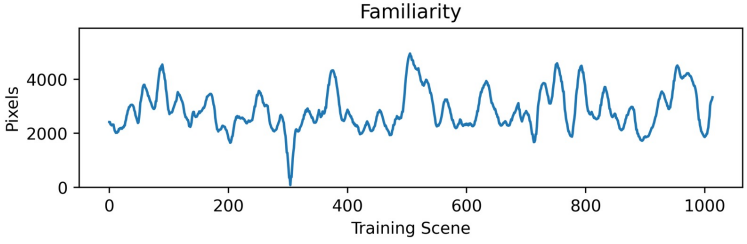
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

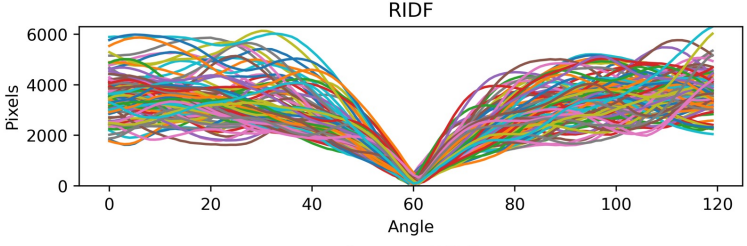
Navigation stats: RMSD error: 47.24; RMSD/dist: 0.118; TD: 2968; p90: 30; p50: 16; complete: 0

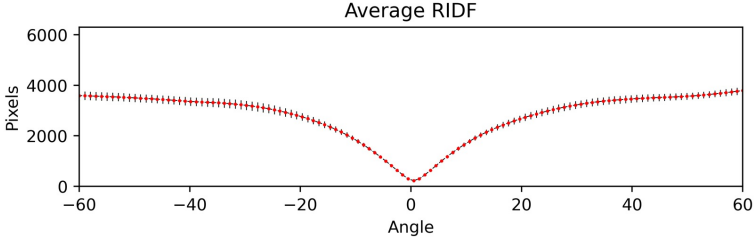
100%







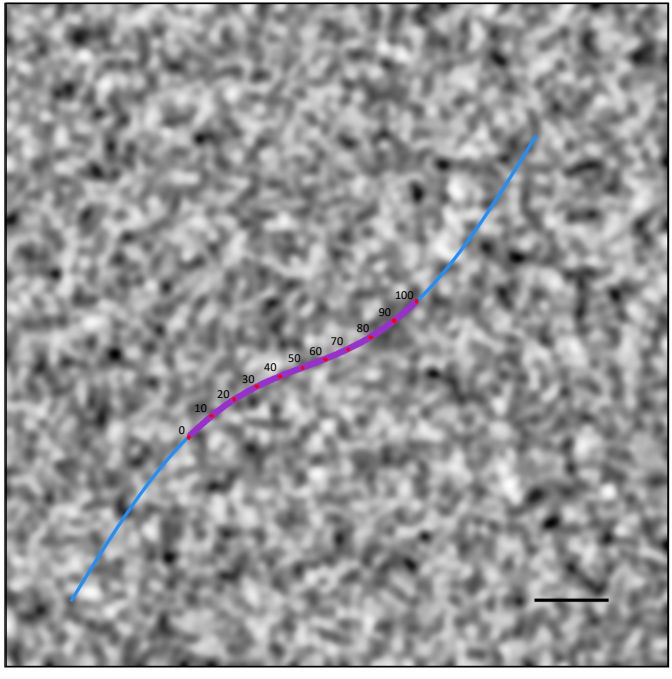


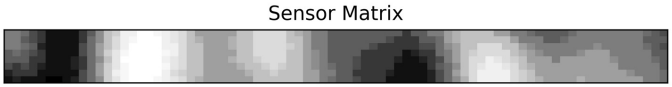


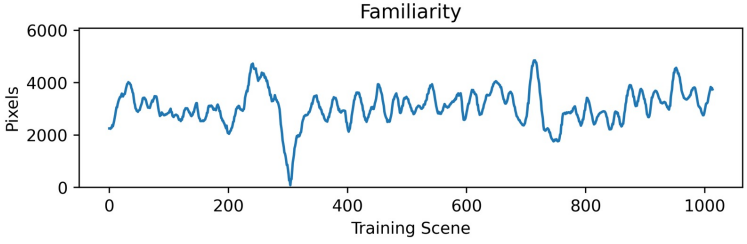
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

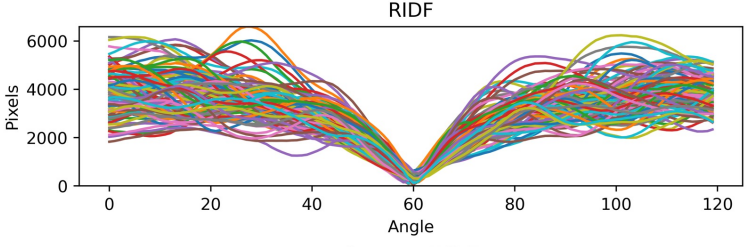
Navigation stats: RMSD error: 56.73; RMSD/dist: 0.142; TD: 2719; p90: 38; p50: 18; complete: 0

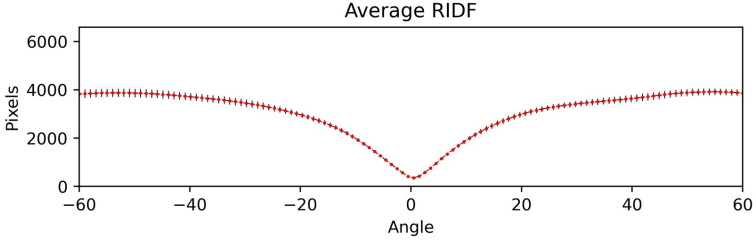
100%







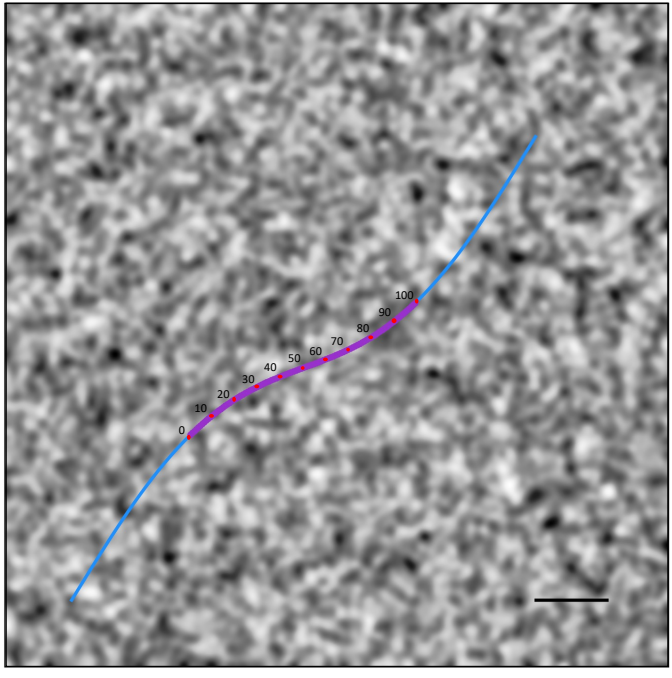


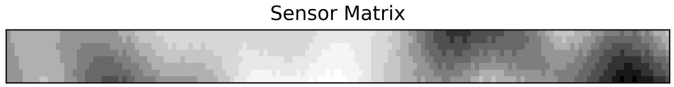


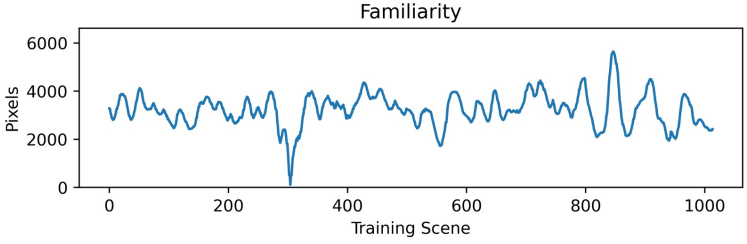
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

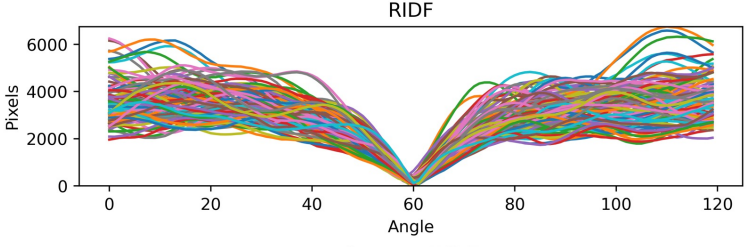
Navigation stats: RMSD error: 107.79; RMSD/dist: 0.269; TD: 2691; p90: 36; p50: 18; complete: 0

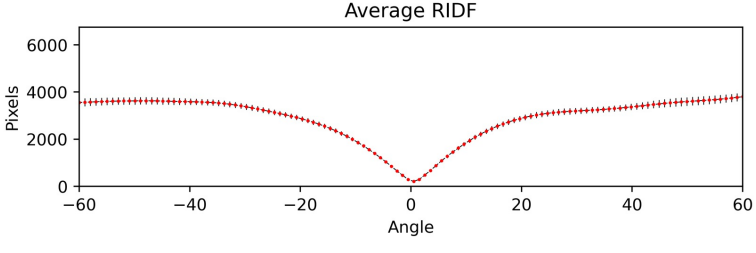
100%





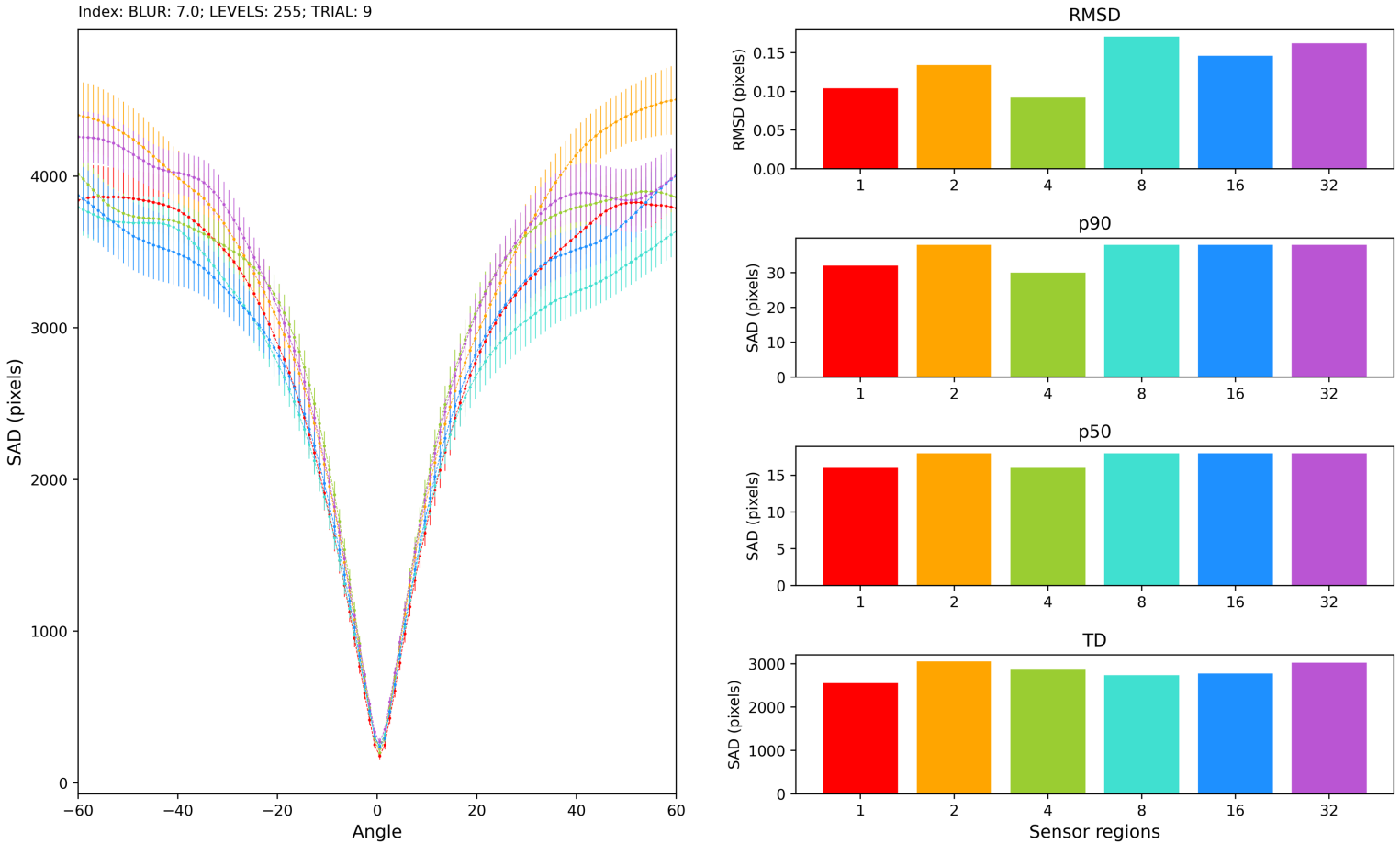




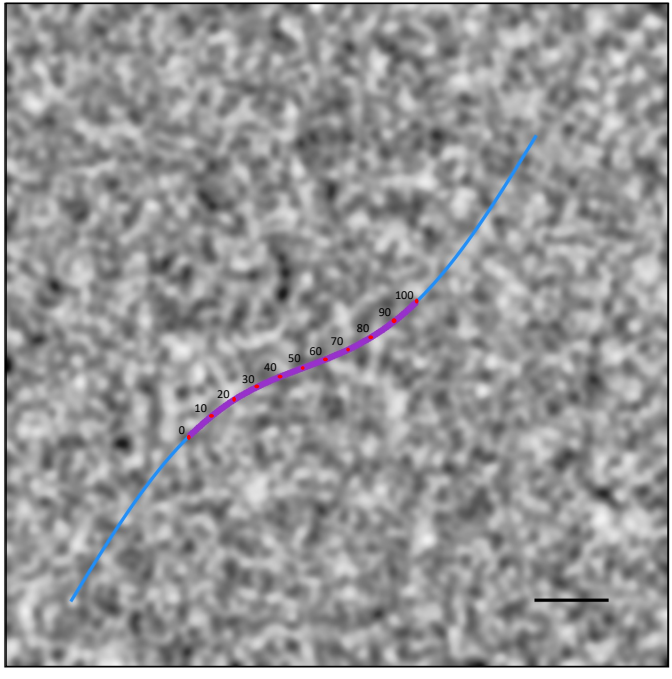


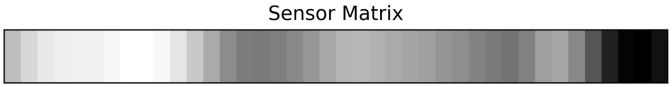
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

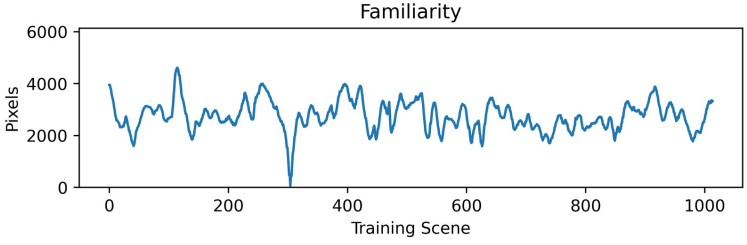
Navigation stats: RMSD error: 38.65; RMSD/dist: 0.097; TD: 2903; p90: 38; p50: 18; complete: 0

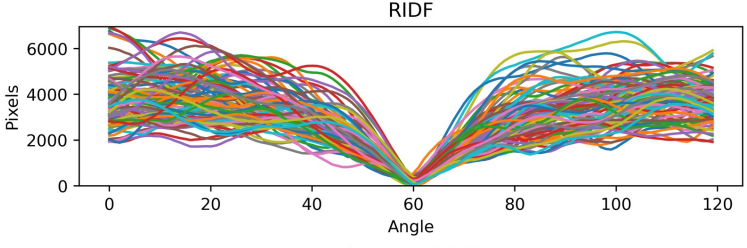

Index: BLUR: 7.0; LEVELS: 255; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

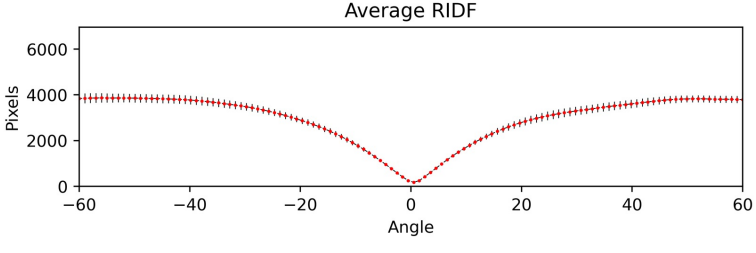
100%







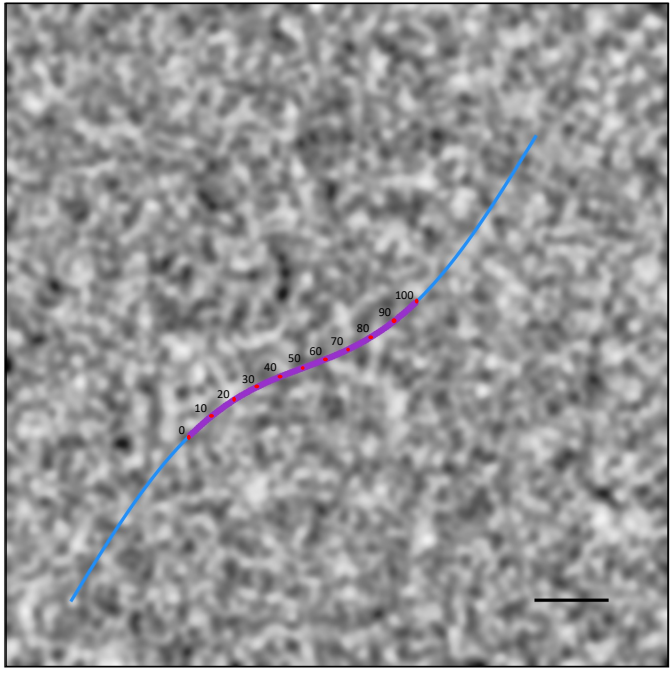


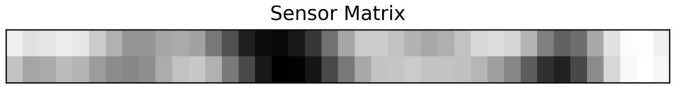


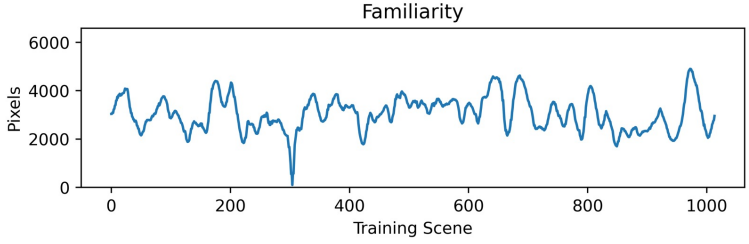
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

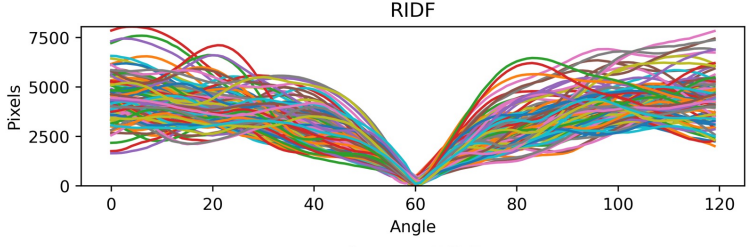
Navigation stats: RMSD error: 41.57; RMSD/dist: 0.104; TD: 2556; p90: 32; p50: 16; complete: 0

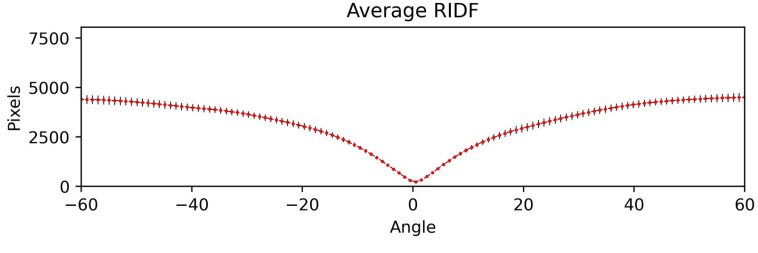
100%







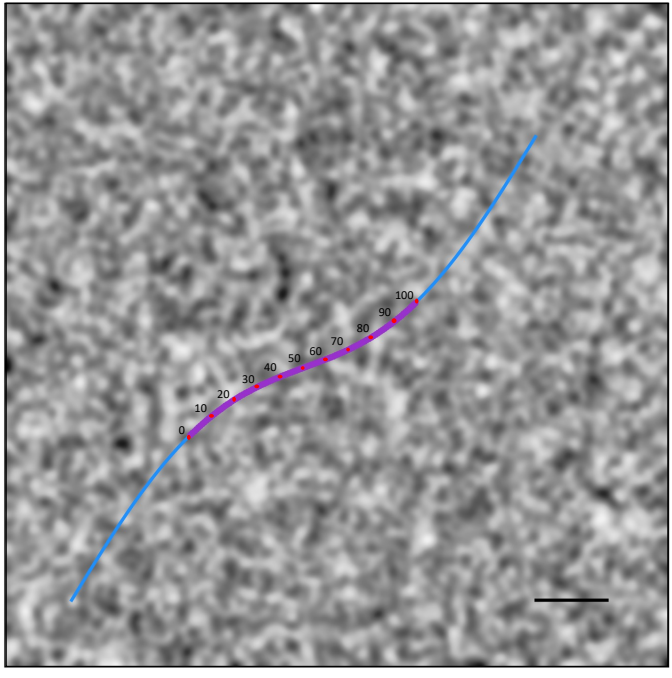


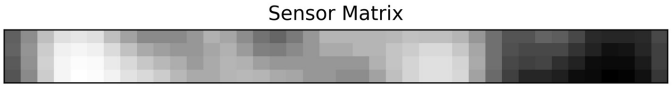


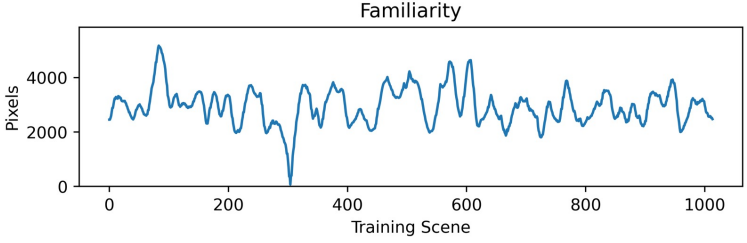
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

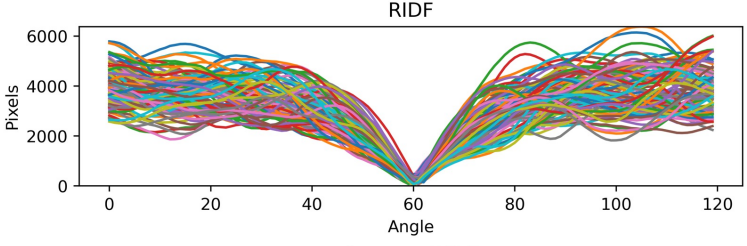
Navigation stats: RMSD error: 53.53; RMSD/dist: 0.134; TD: 3051; p90: 38; p50: 18; complete: 0

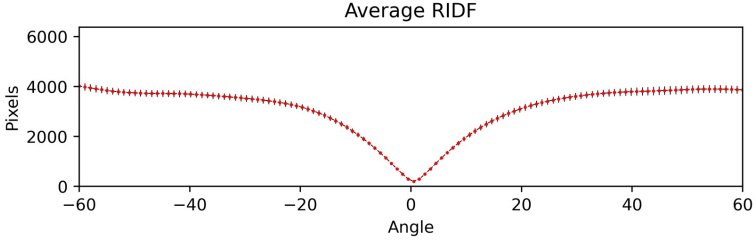
100%







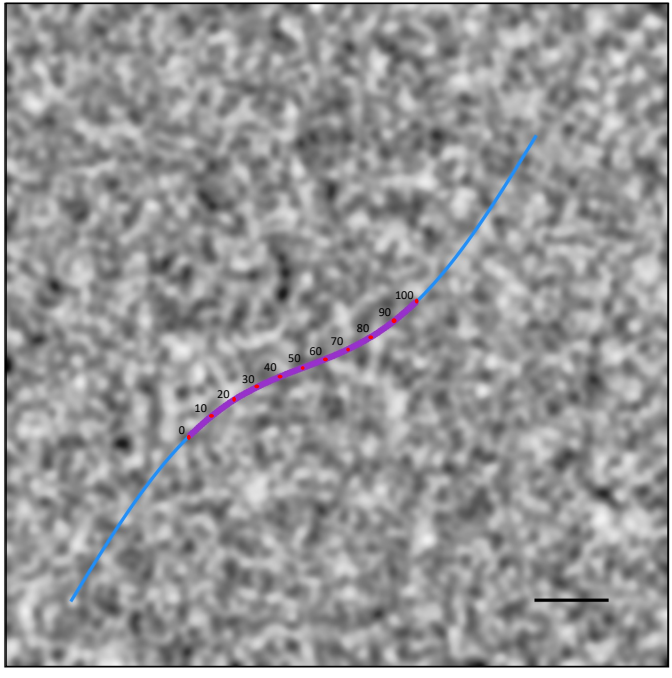


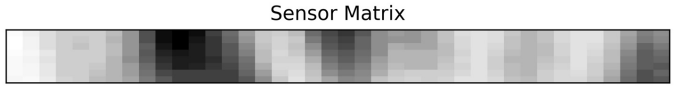


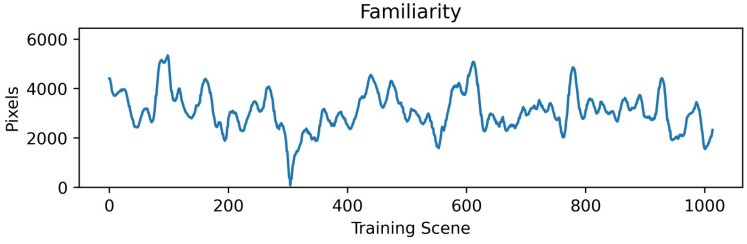
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

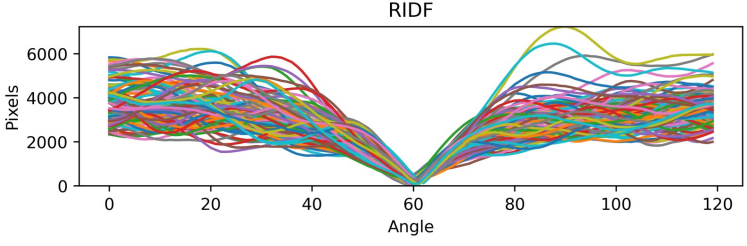
Navigation stats: RMSD error: 36.82; RMSD/dist: 0.092; TD: 2881; p90: 30; p50: 16; complete: 0

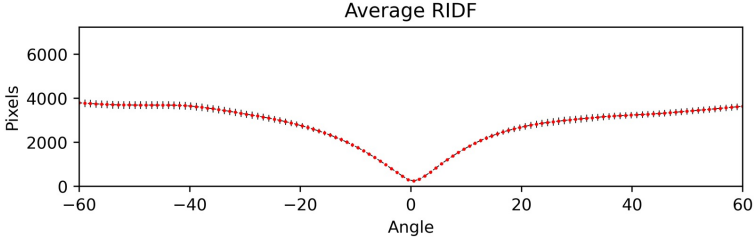
100%







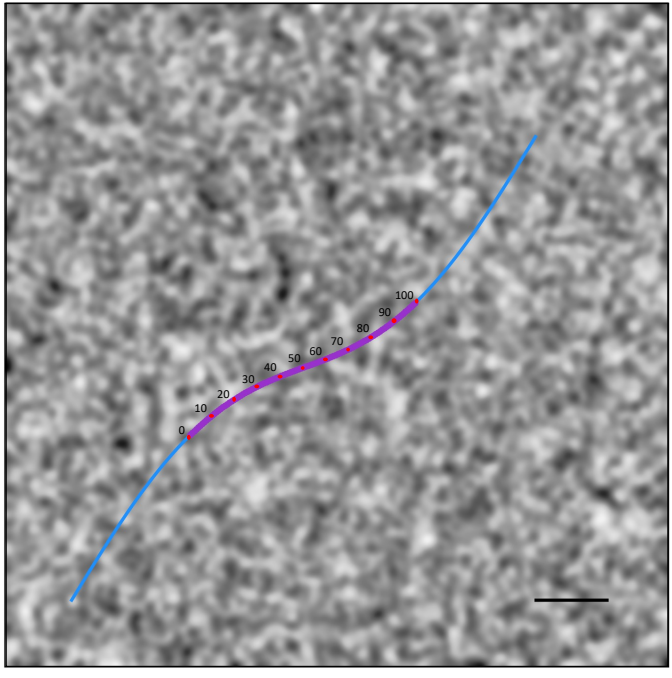


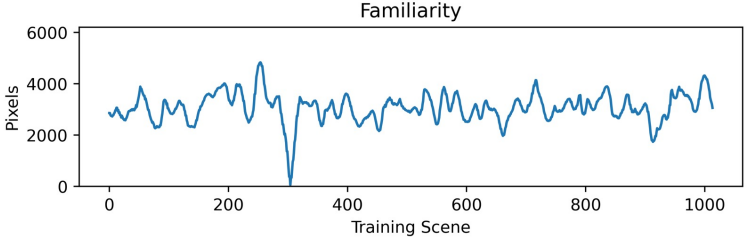


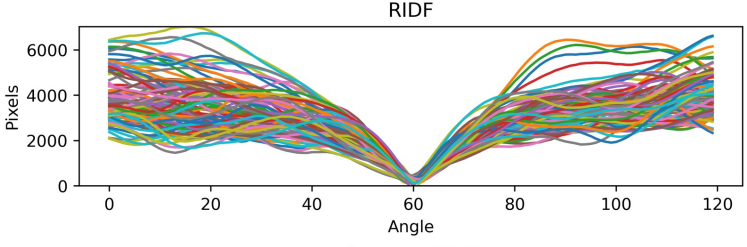
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

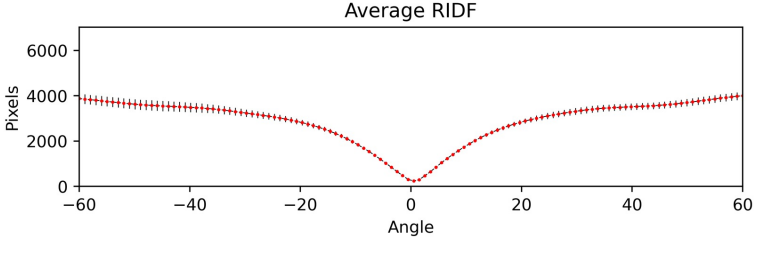
Navigation stats: RMSD error: 68.30; RMSD/dist: 0.171; TD: 2737; p90: 38; p50: 18; complete: 0

100%





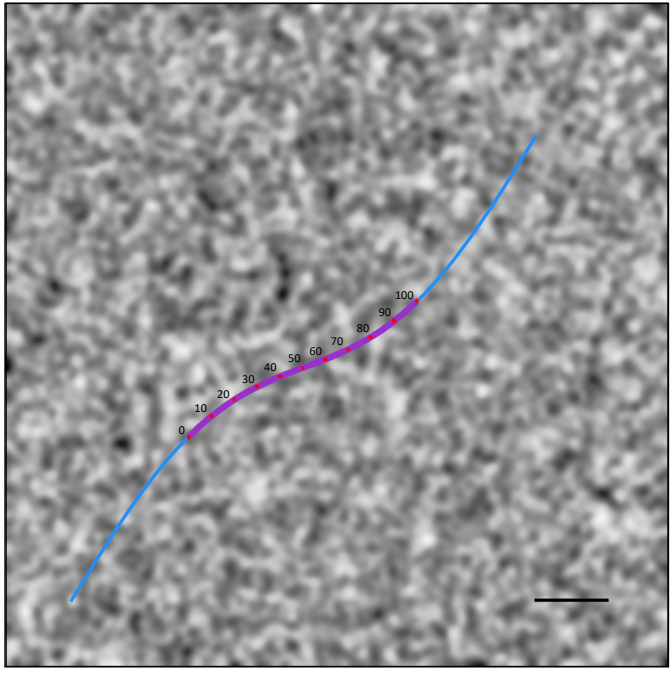


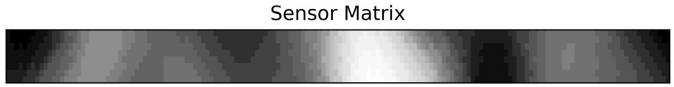


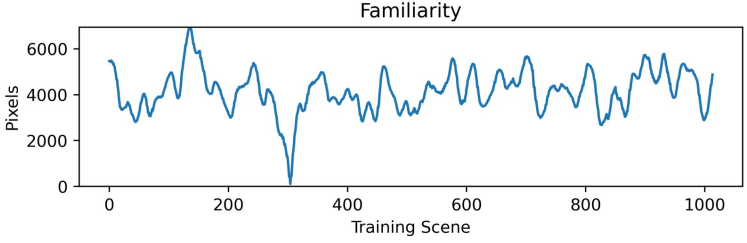
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

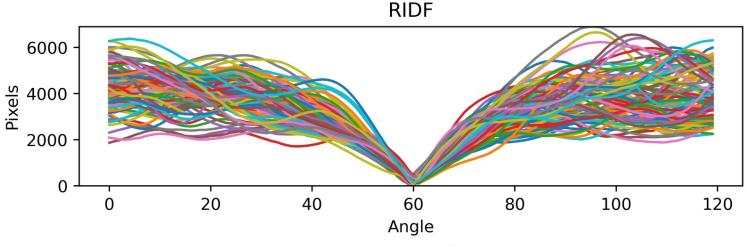
Navigation stats: RMSD error: 58.29; RMSD/dist: 0.146; TD: 2777; p90: 38; p50: 18; complete: 0

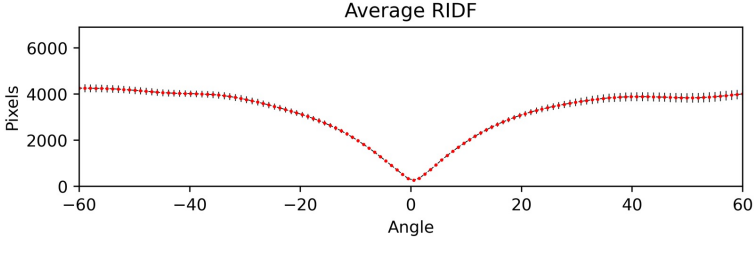
100%





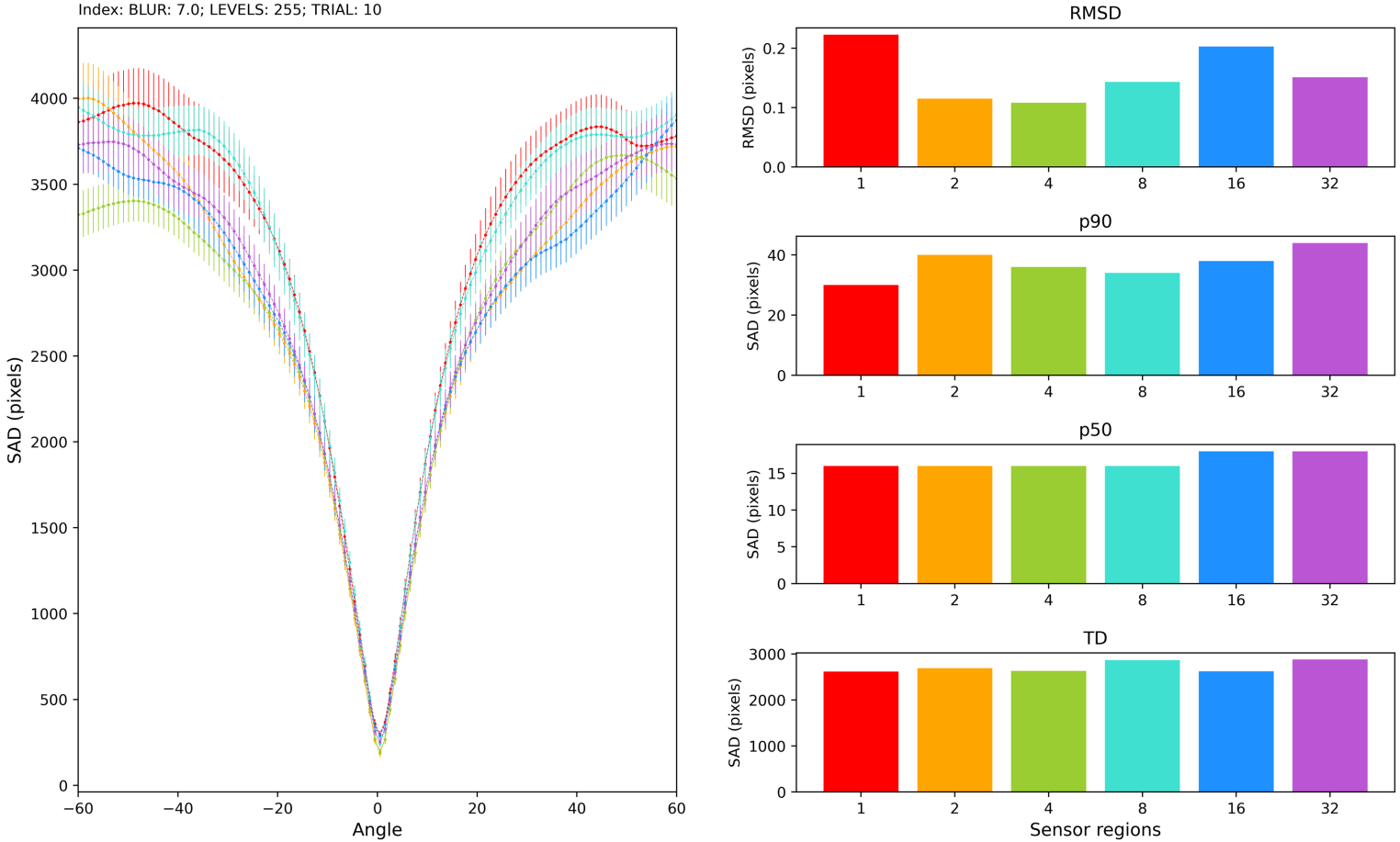




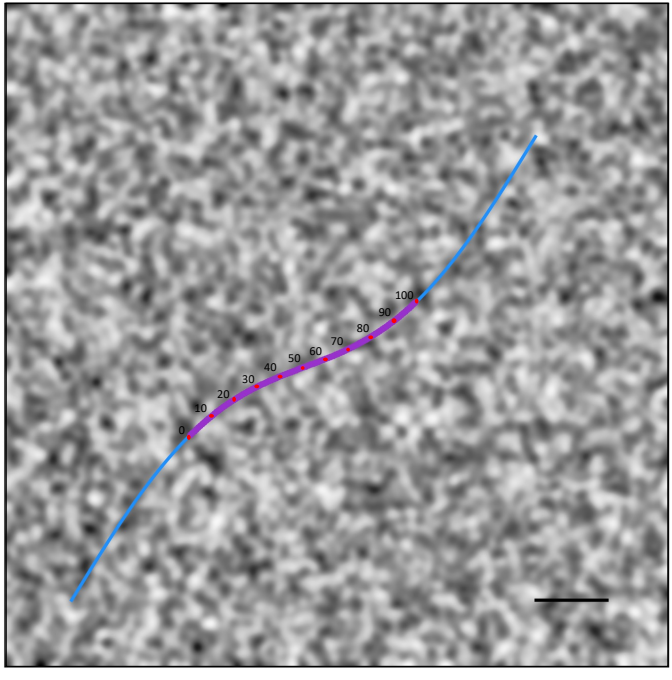


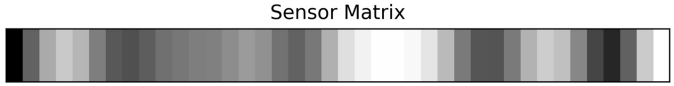
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

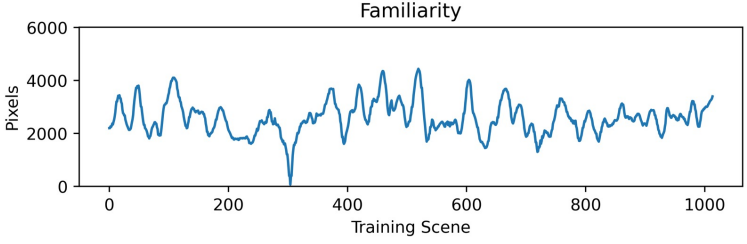
Navigation stats: RMSD error: 64.62; RMSD/dist: 0.162; TD: 3025; p90: 38; p50: 18; complete: 0

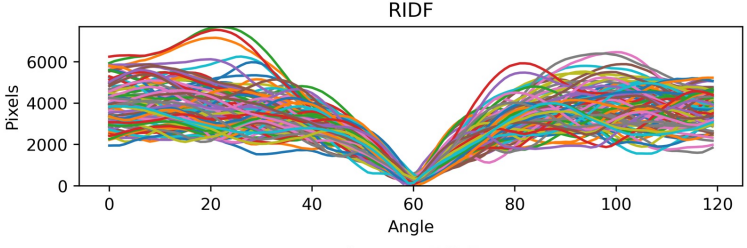

Index: BLUR: 7.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

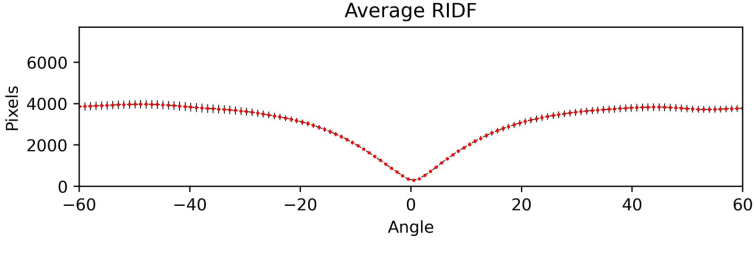
100%







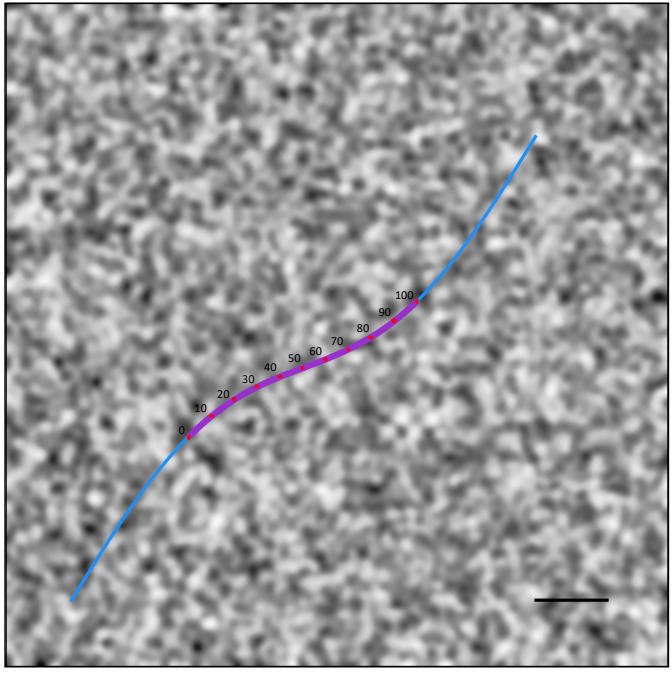


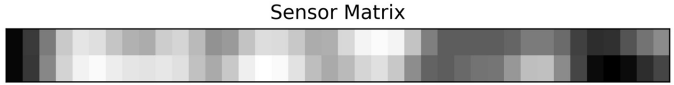


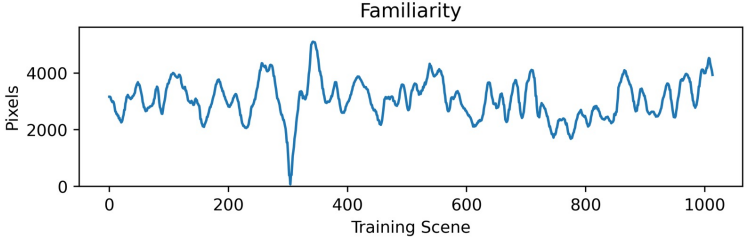
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

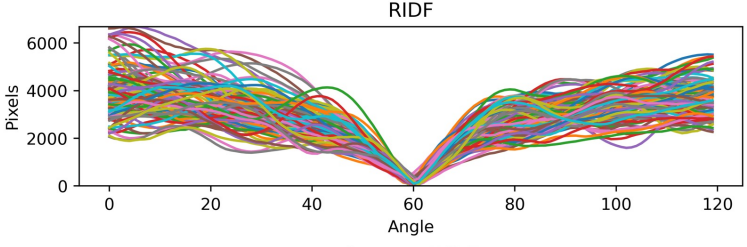
Navigation stats: RMSD error: 89.40; RMSD/dist: 0.223; TD: 2617; p90: 30; p50: 16; complete: 0

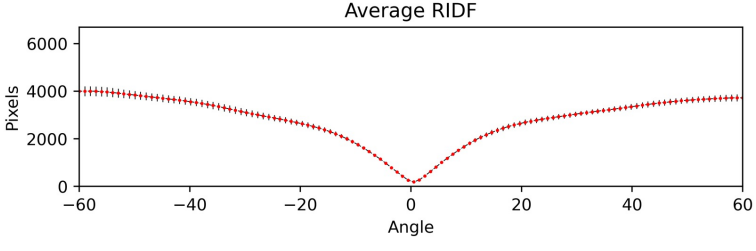
100%







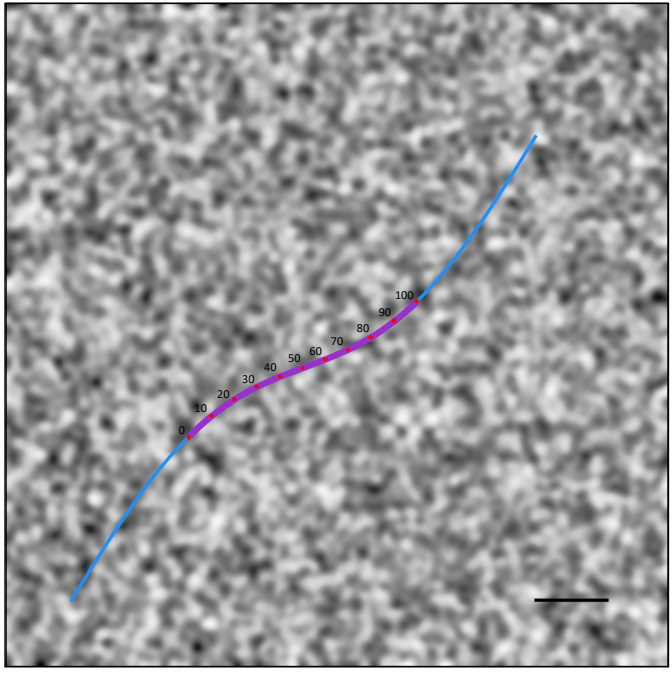


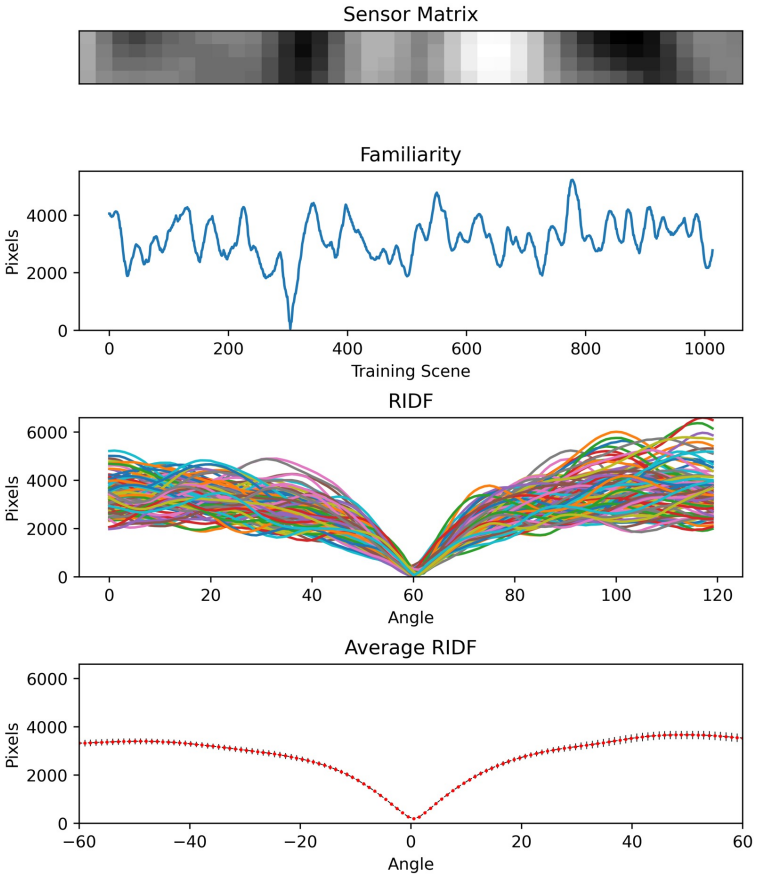


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 46.15; RMSD/dist: 0.115; TD: 2691; p90: 40; p50: 16; complete: 0

100%

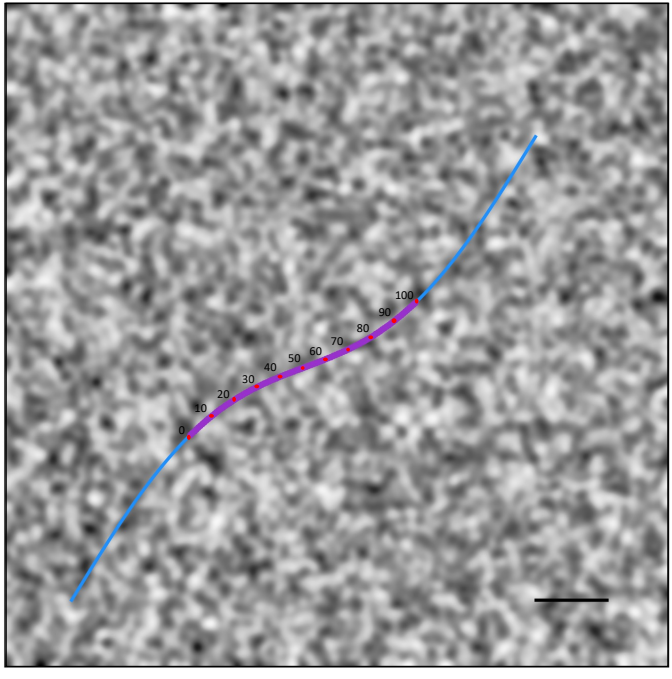


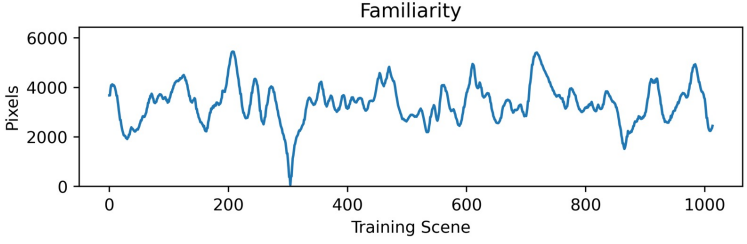


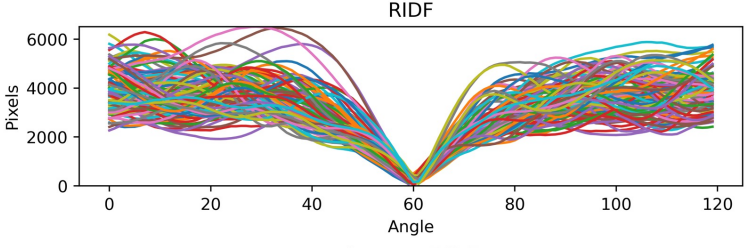
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

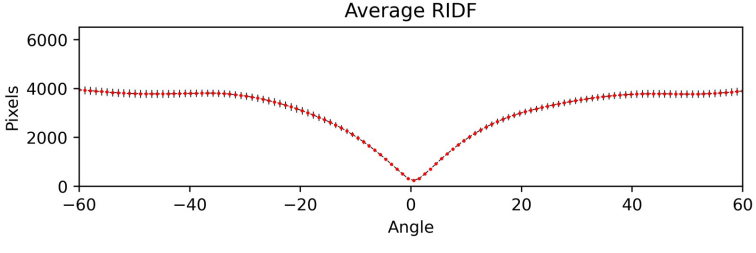
Navigation stats: RMSD error: 43.27; RMSD/dist: 0.108; TD: 2630; p90: 36; p50: 16; complete: 0

100%





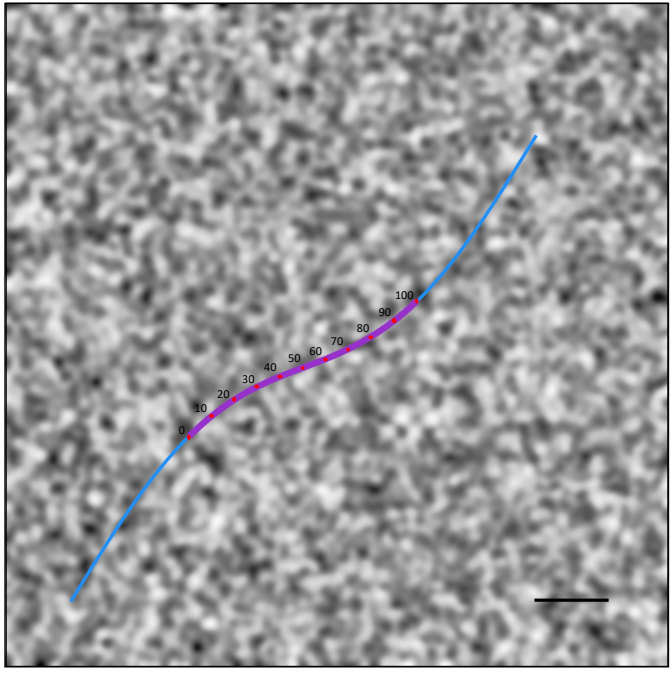


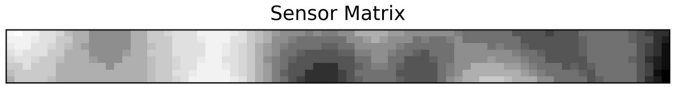


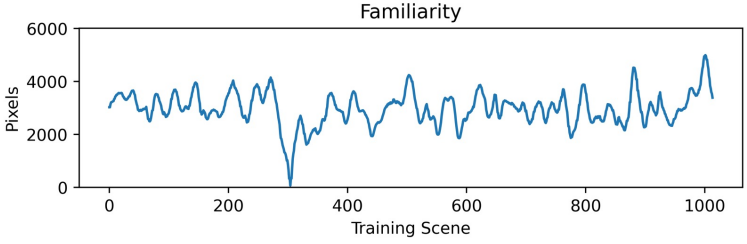
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

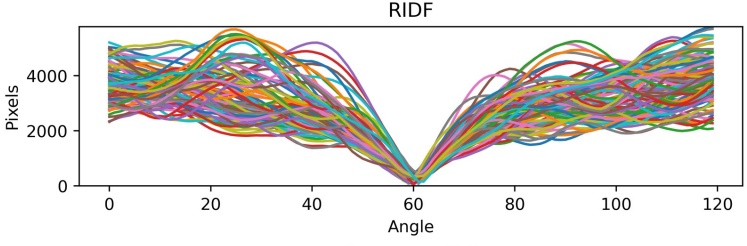
Navigation stats: RMSD error: 57.09; RMSD/dist: 0.143; TD: 2865; p90: 34; p50: 16; complete: 0

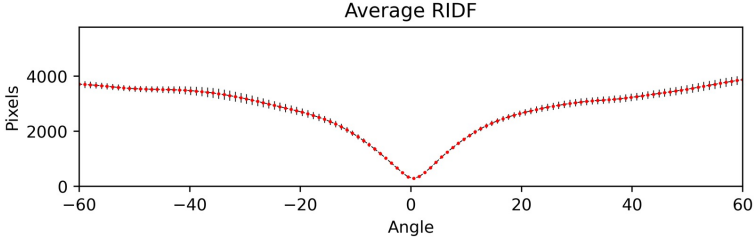
100%







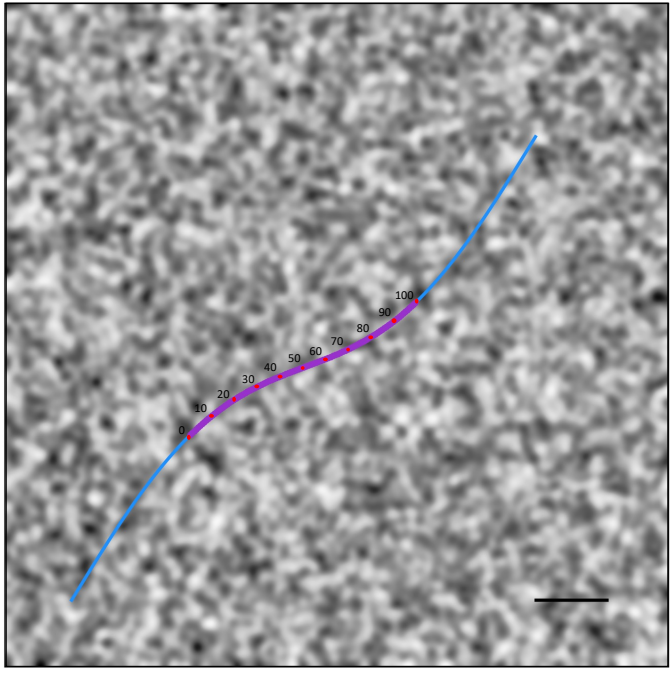


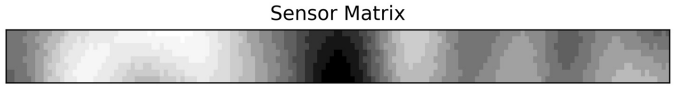


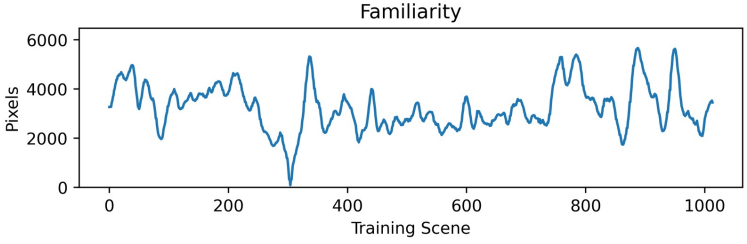
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

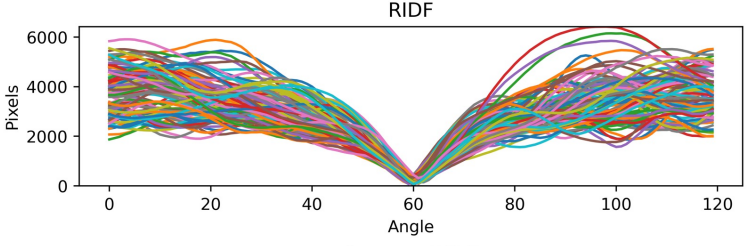
Navigation stats: RMSD error: 81.19; RMSD/dist: 0.203; TD: 2620; p90: 38; p50: 18; complete: 0

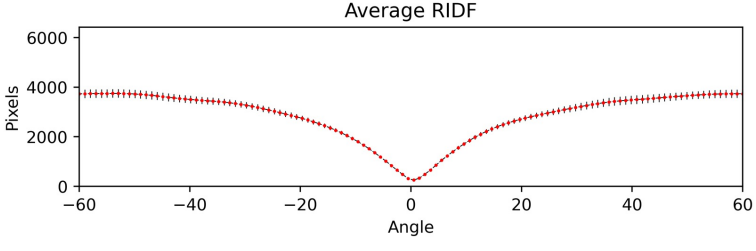
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 60.34; RMSD/dist: 0.151; TD: 2878; p90: 44; p50: 18; complete: 0