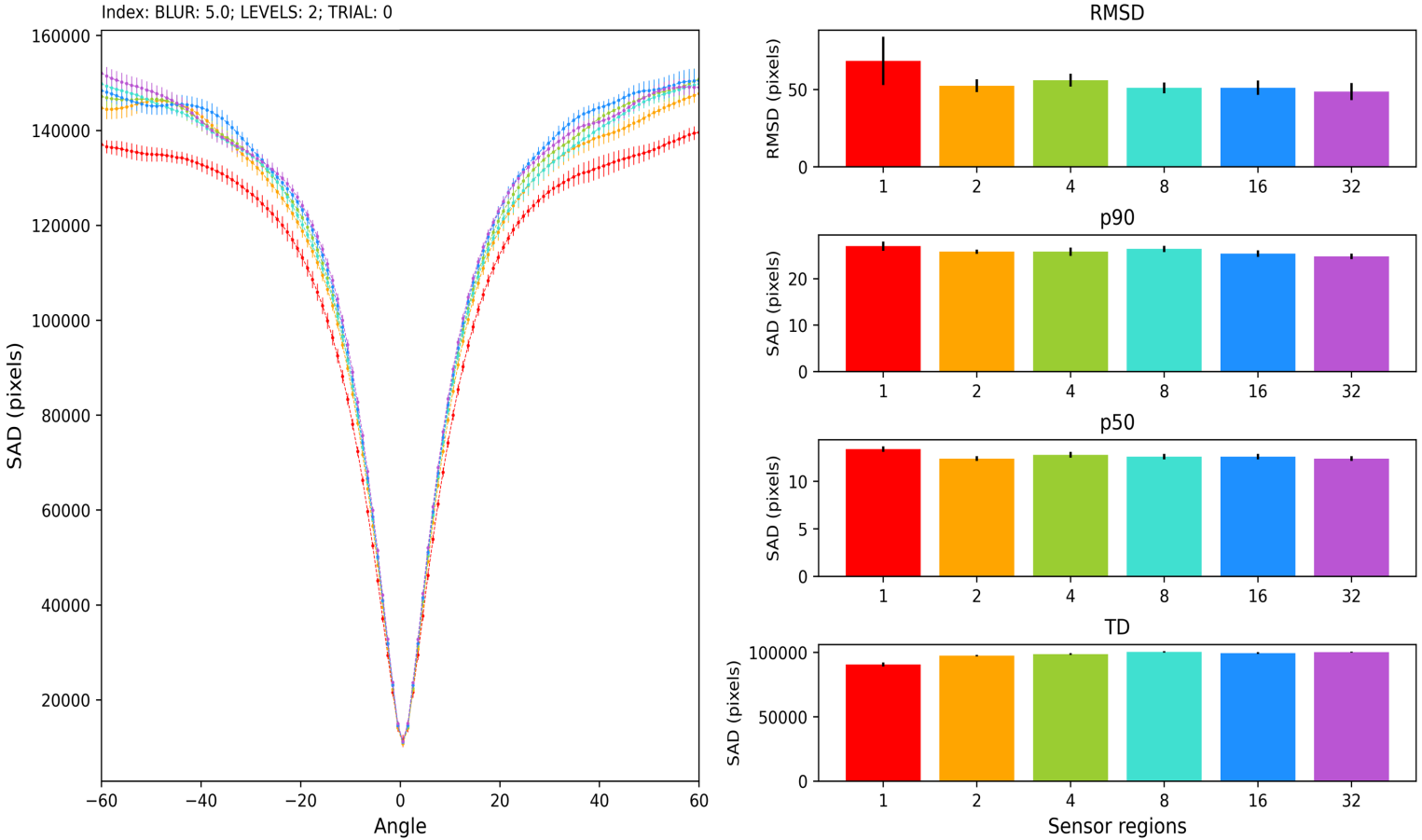
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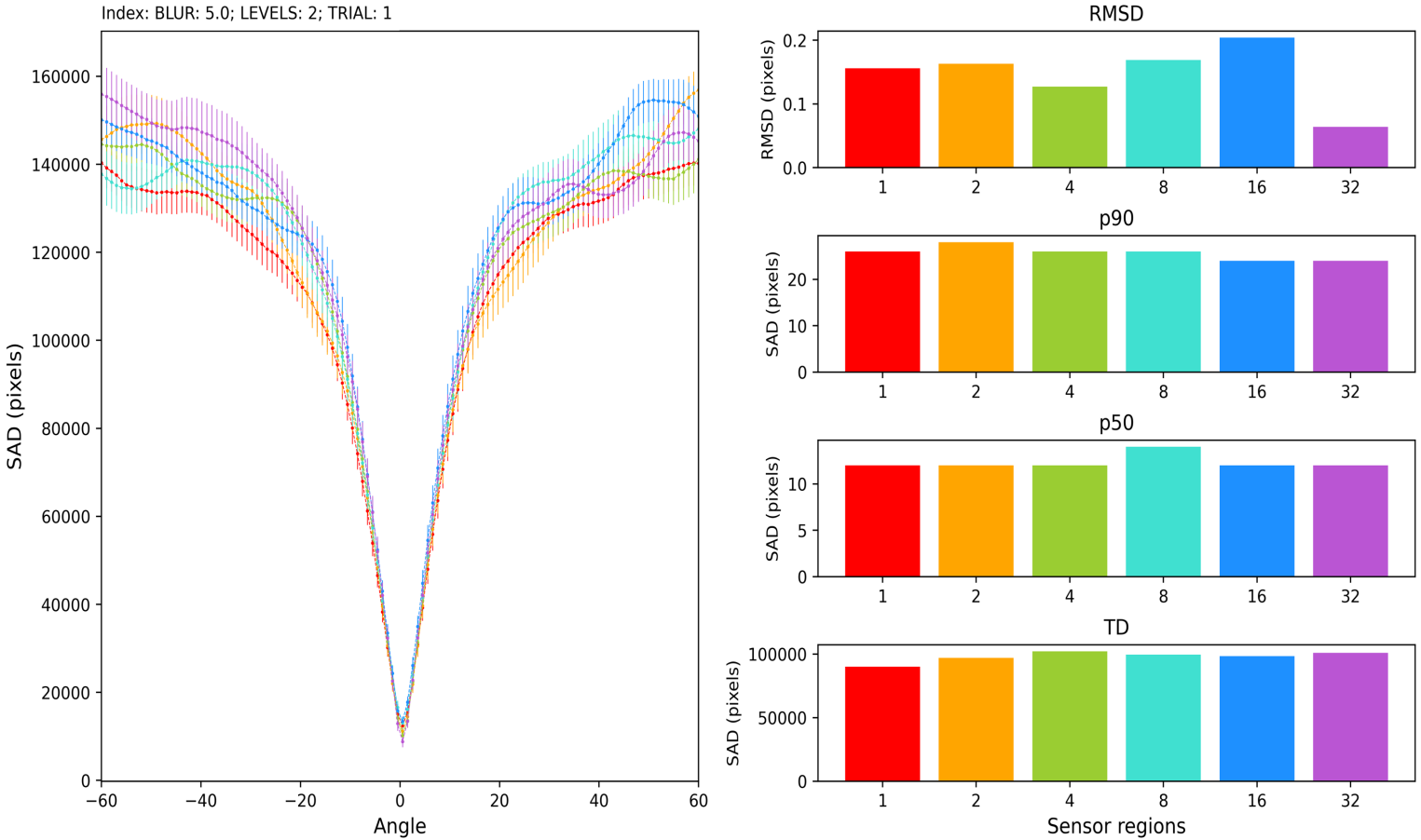
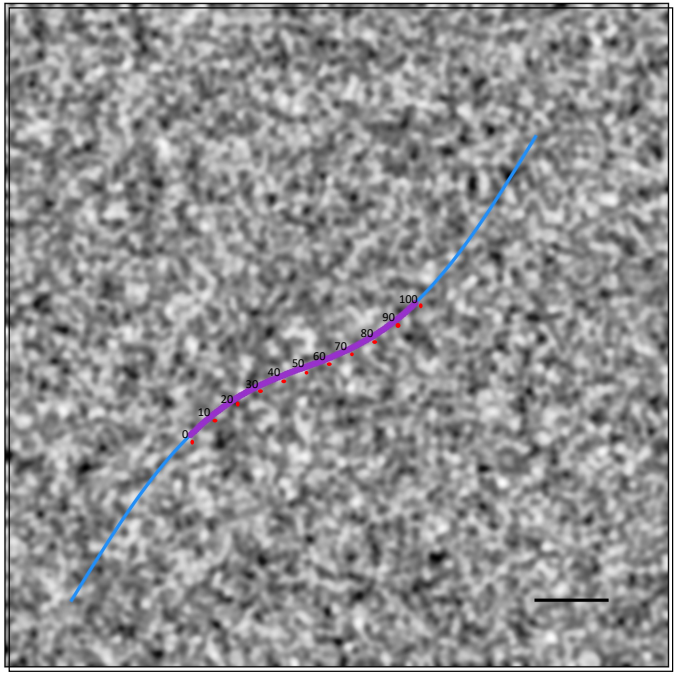
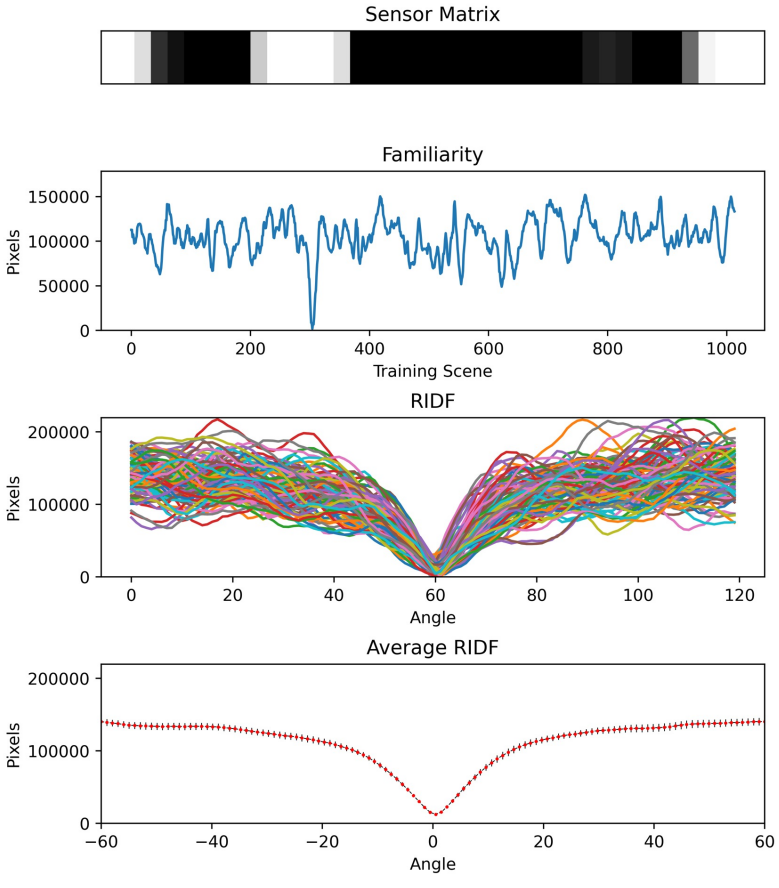
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
50
0
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

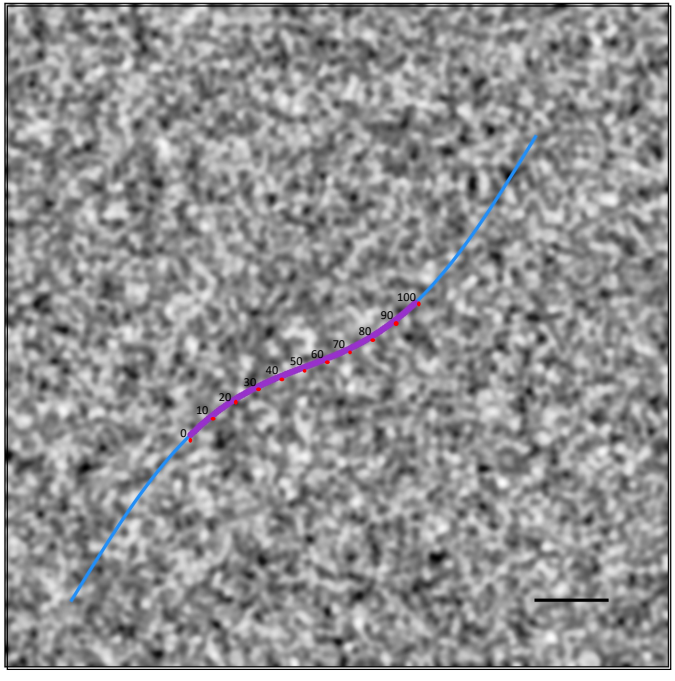


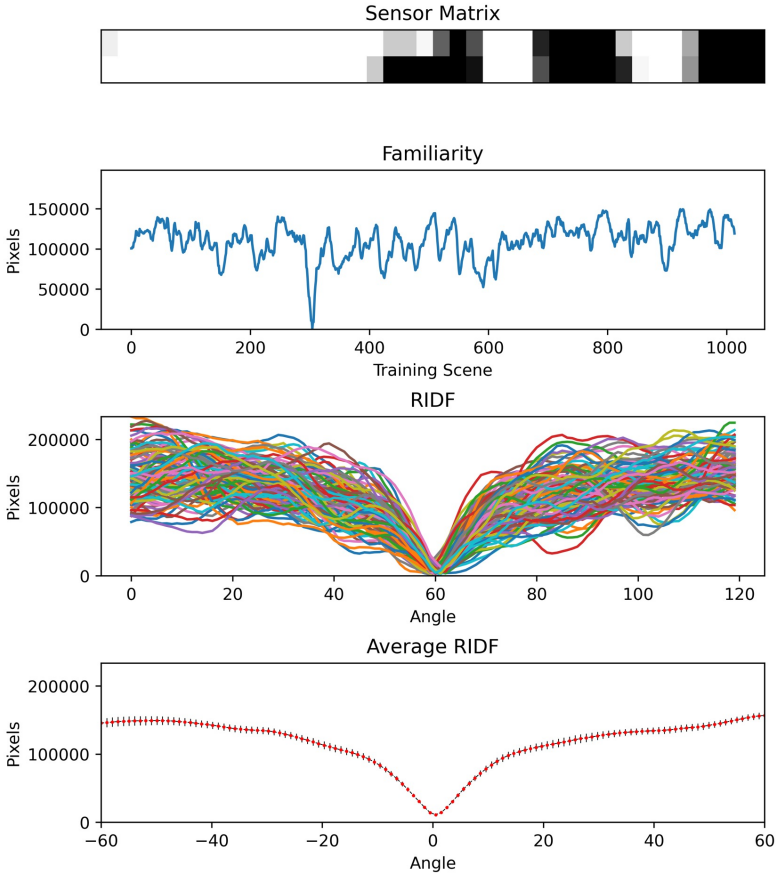


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 62.31; RMSD/dist: 0.156; TD: 90033; p90: 26; p50: 12; complete: 0

100%

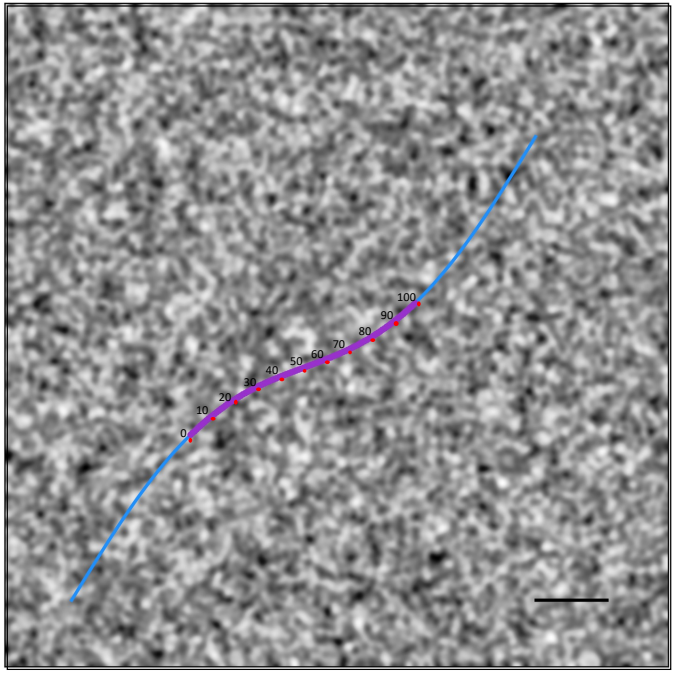


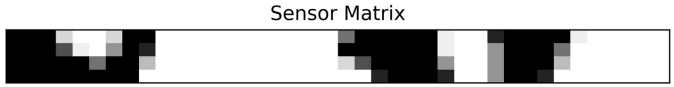


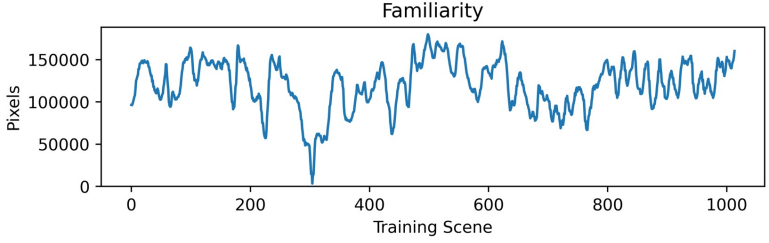
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

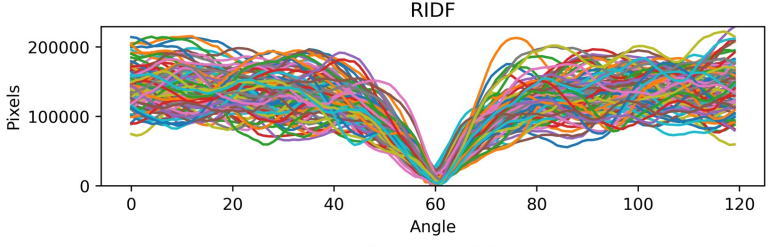
Navigation stats: RMSD error: 65.06; RMSD/dist: 0.163; TD: 96866; p90: 28; p50: 12; complete: 0

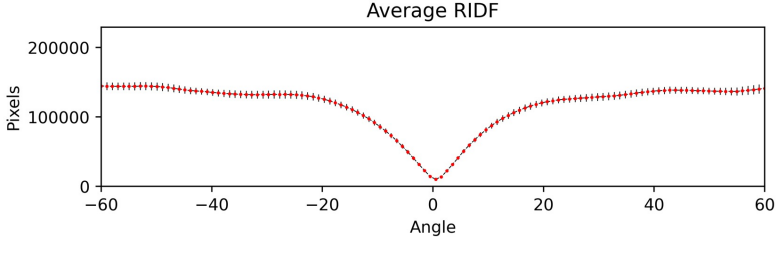
100%







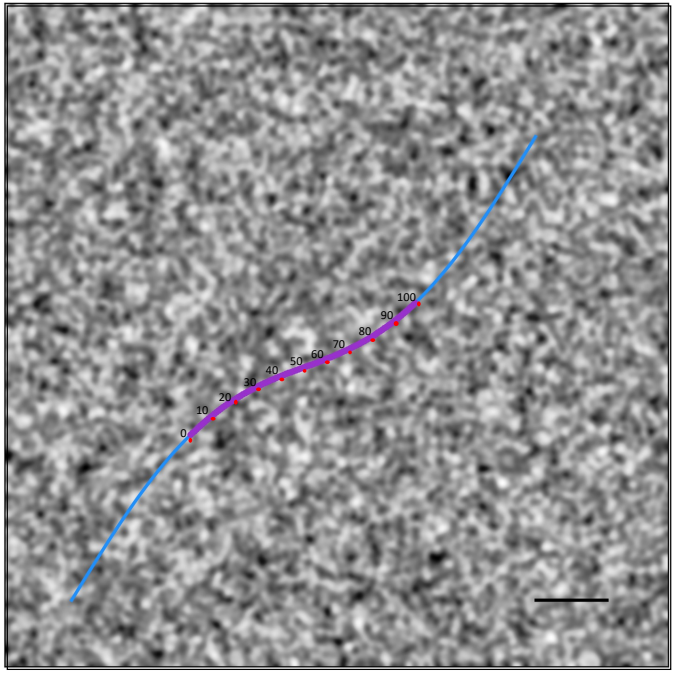


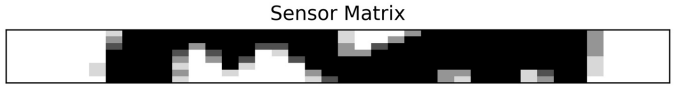


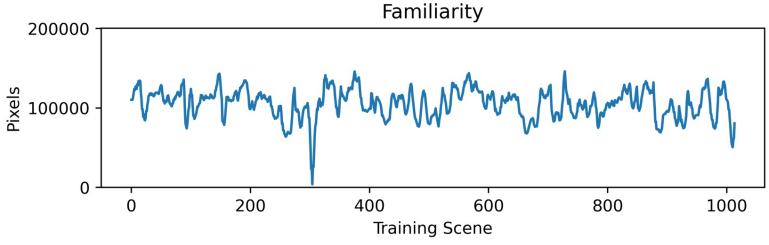
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

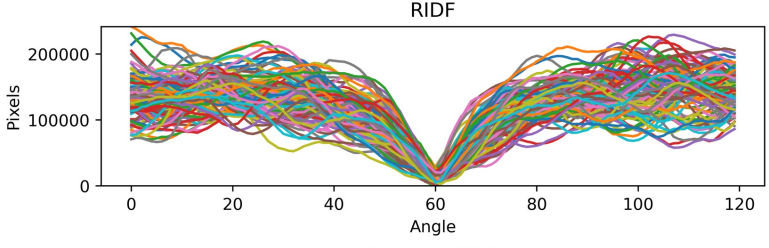
Navigation stats: RMSD error: 50.89; RMSD/dist: 0.127; TD: 102111; p90: 26; p50: 12; complete: 0

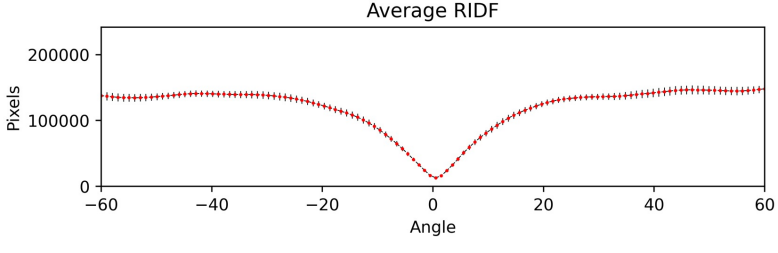
100%







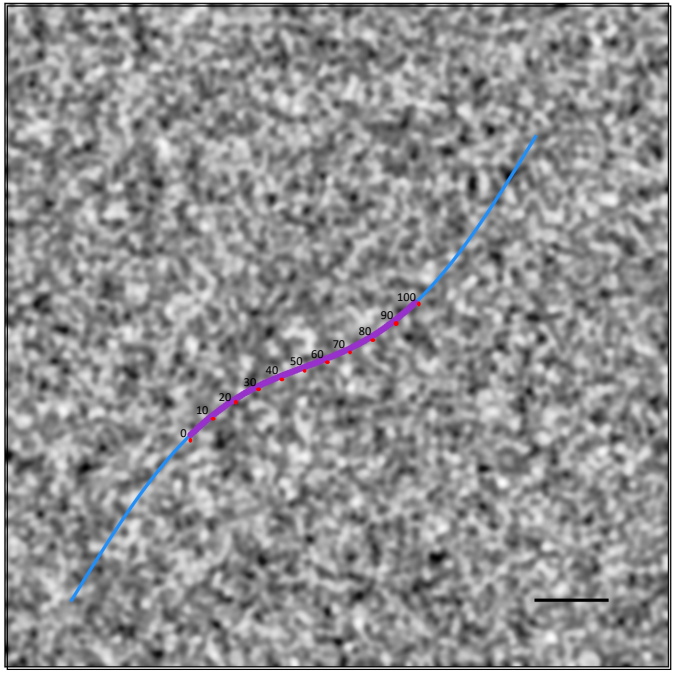


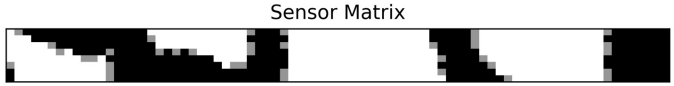


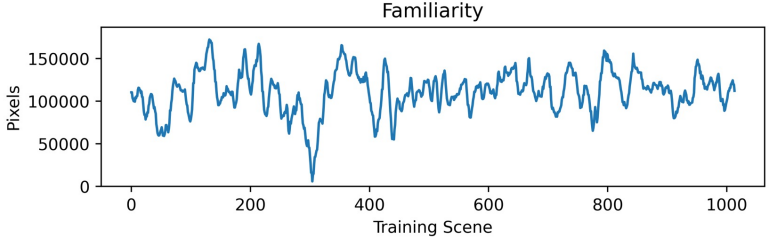
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

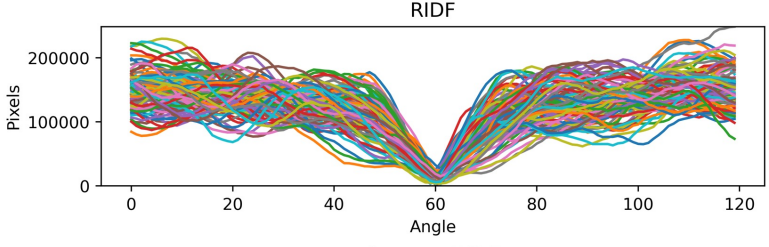
Navigation stats: RMSD error: 67.44; RMSD/dist: 0.169; TD: 99554; p90: 26; p50: 14; complete: 0

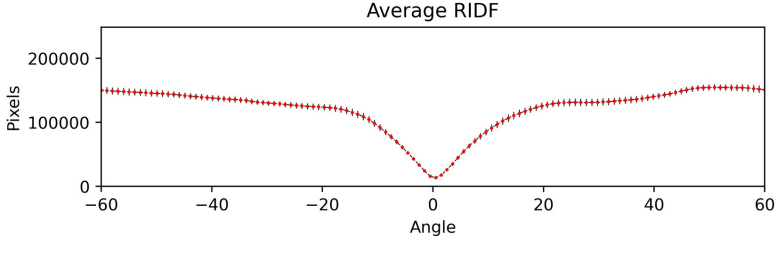
100%







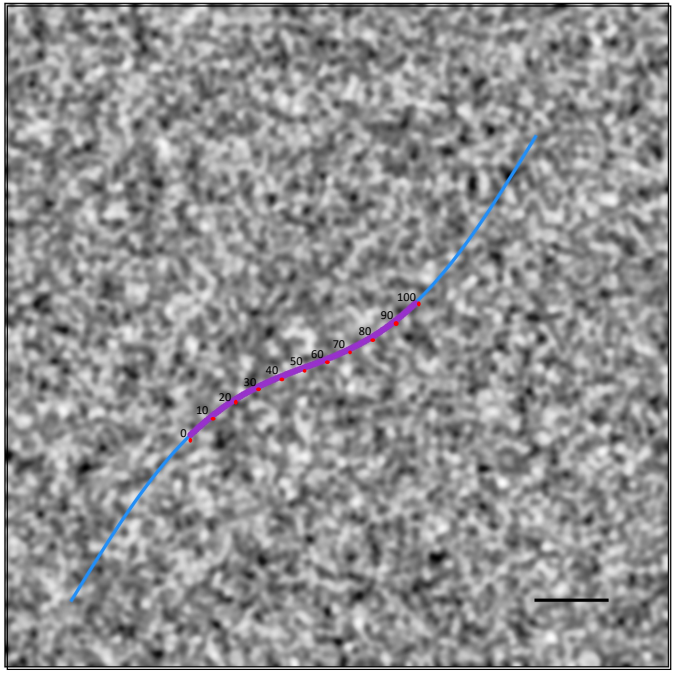


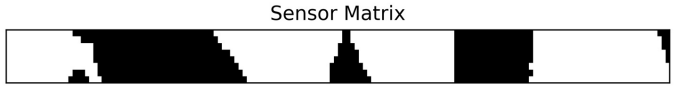


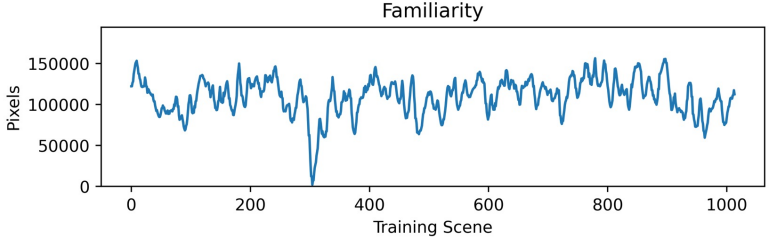
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

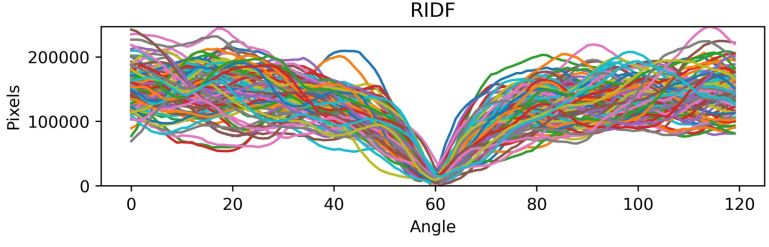
Navigation stats: RMSD error: 81.79; RMSD/dist: 0.204; TD: 98331; p90: 24; p50: 12; complete: 0

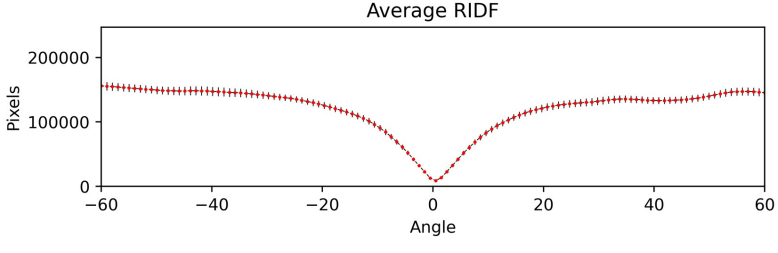
100%





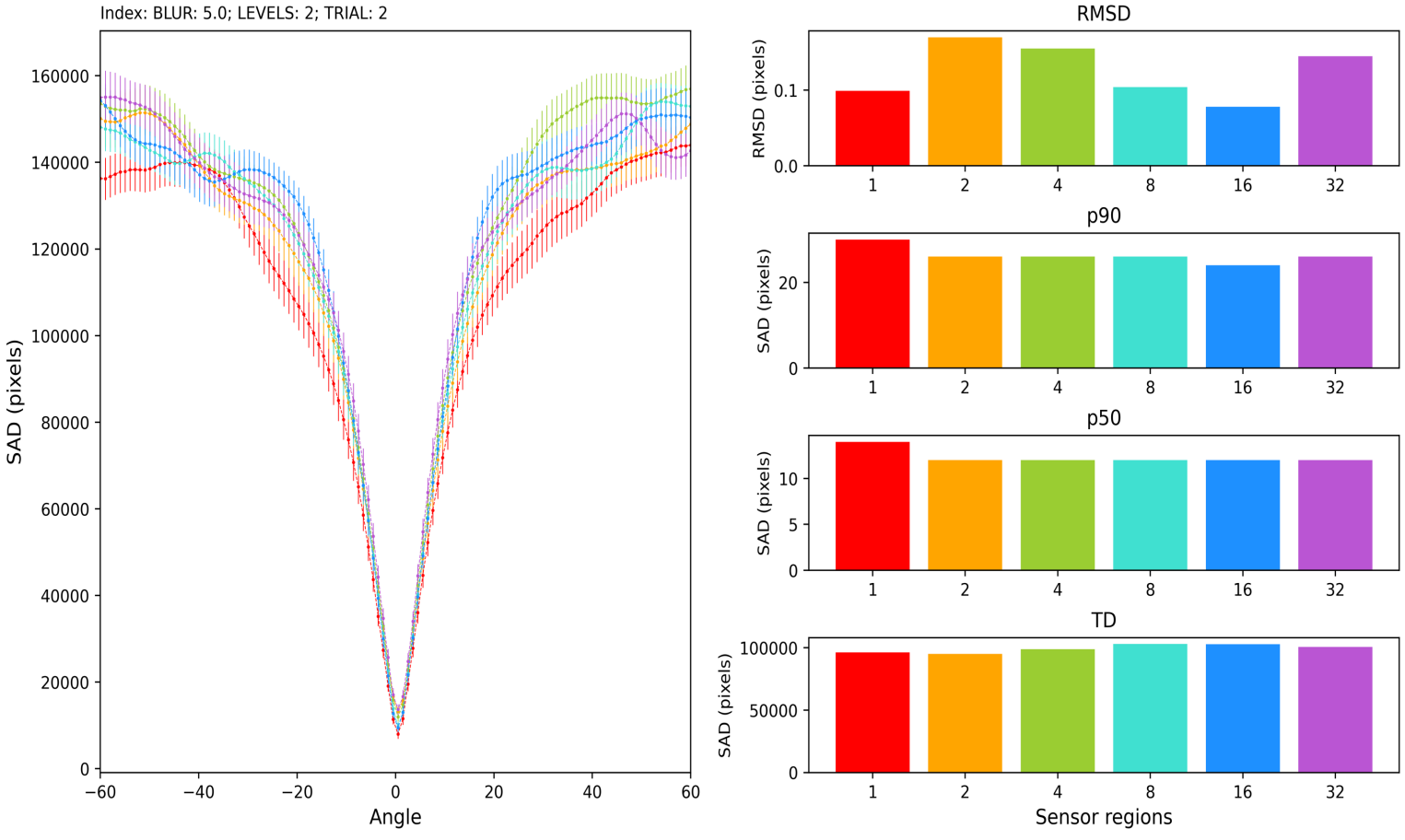




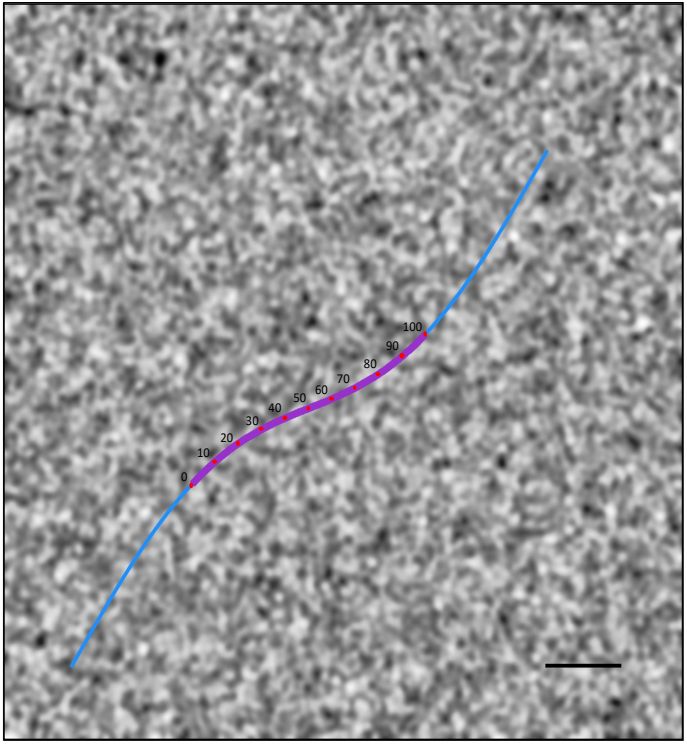


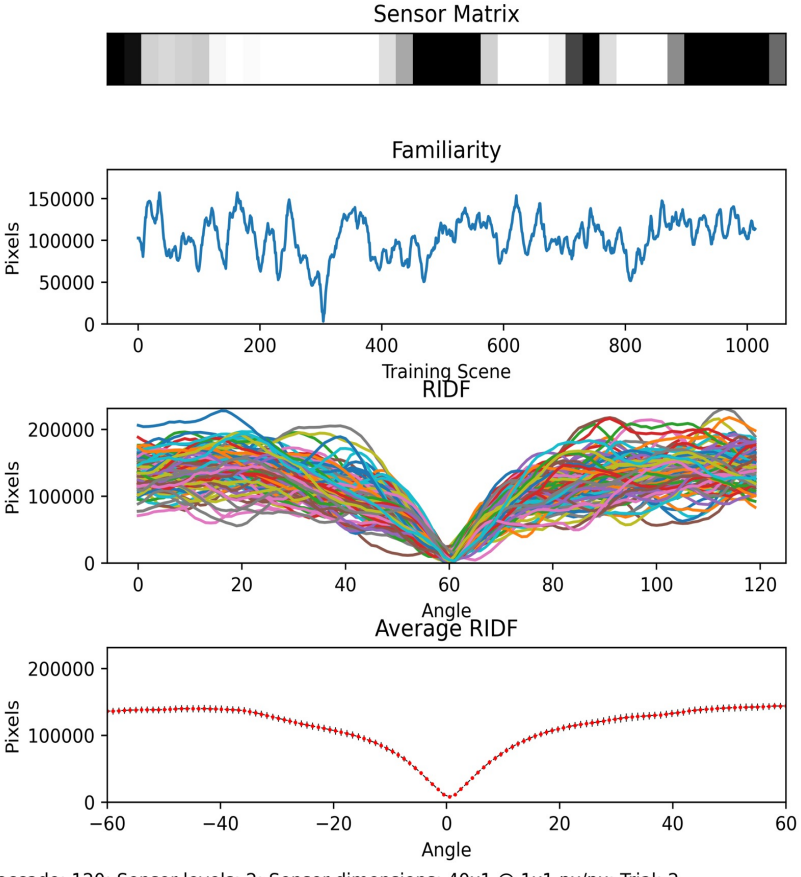
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 25.55; RMSD/dist: 0.064; TD: 100809; p90: 24; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

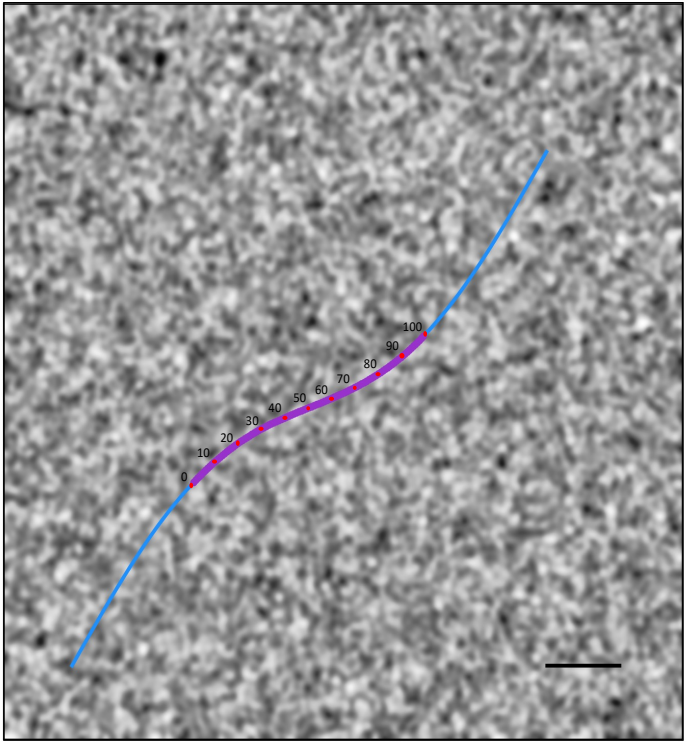


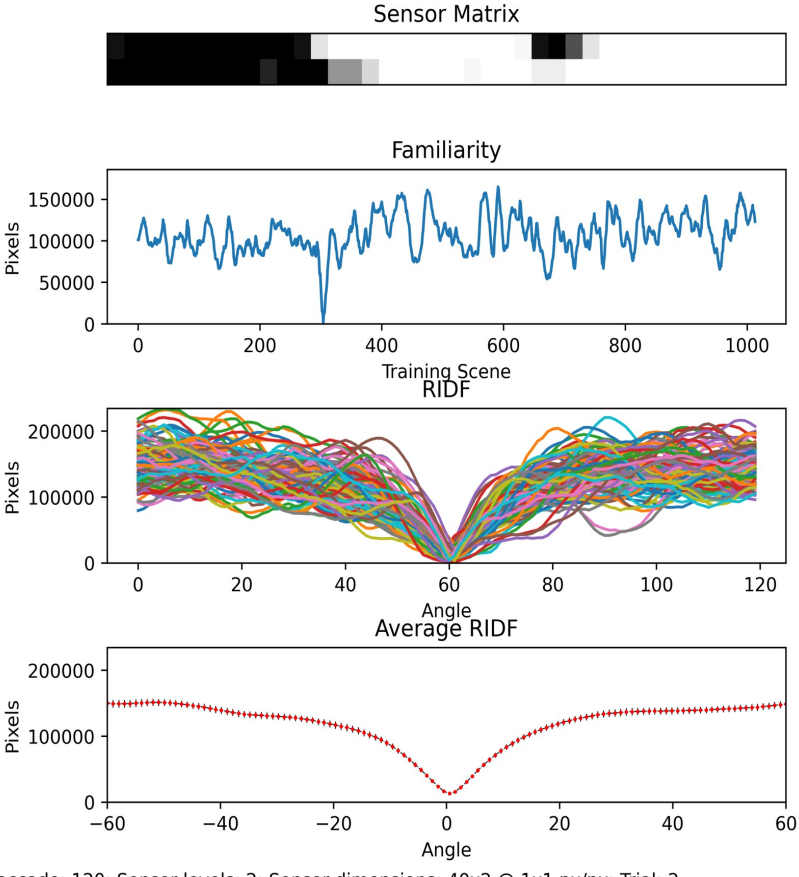


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 39.68; RMSD/dist: 0.099; TD: 96285; p90: 30; p50: 14; complete: 0

100%

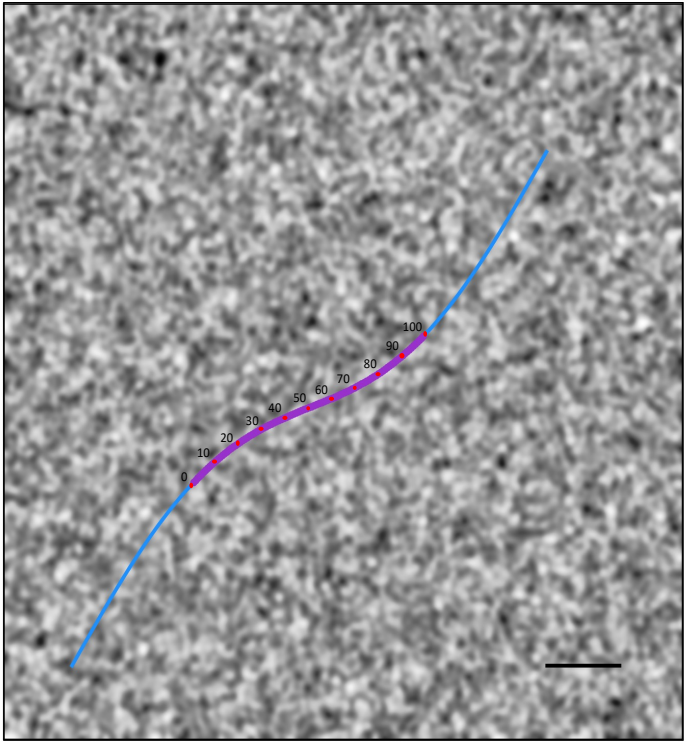


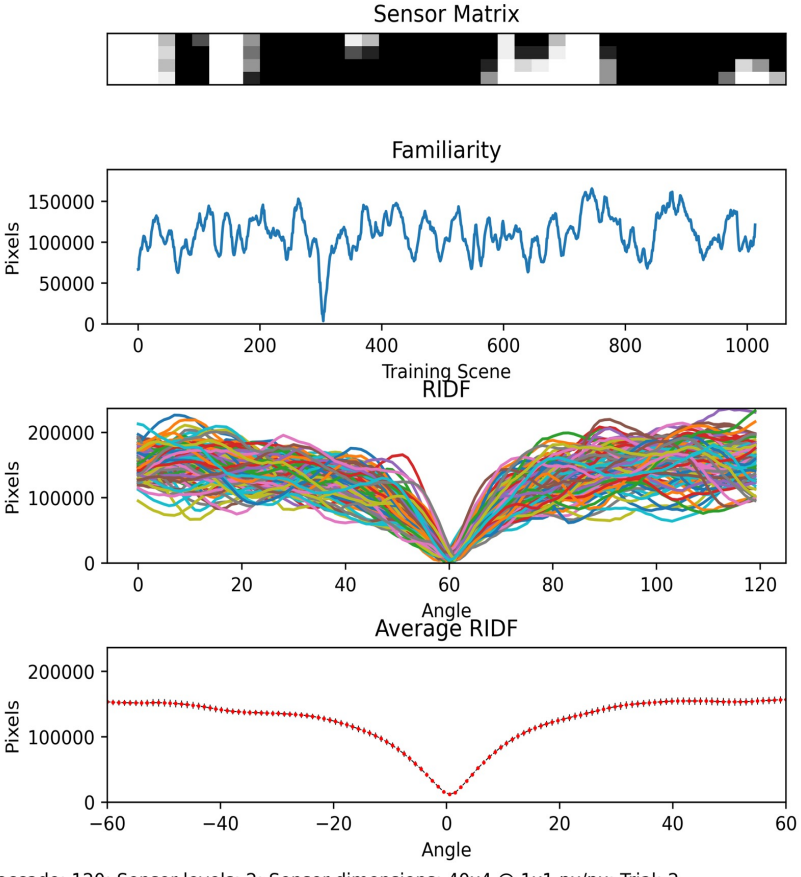


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 68.03; RMSD/dist: 0.170; TD: 95017; p90: 26; p50: 12; complete: 0

100%

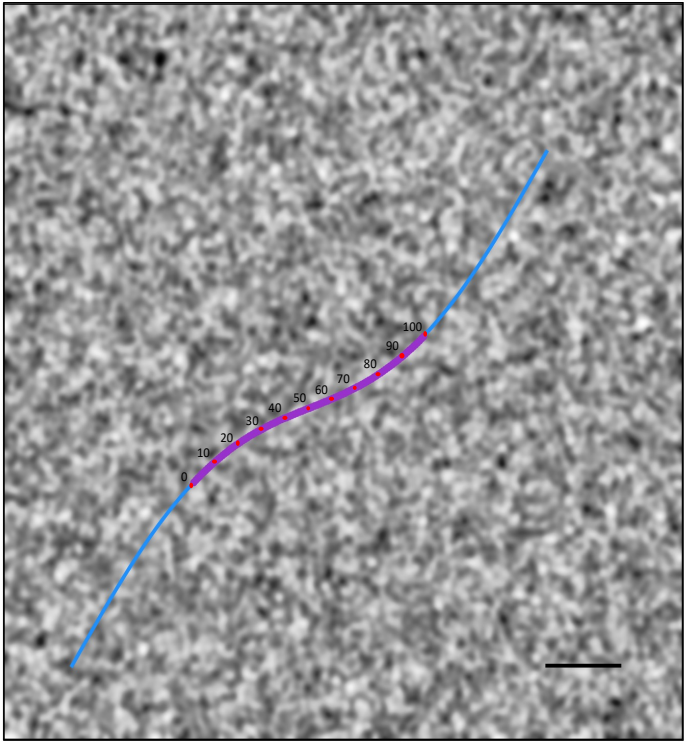


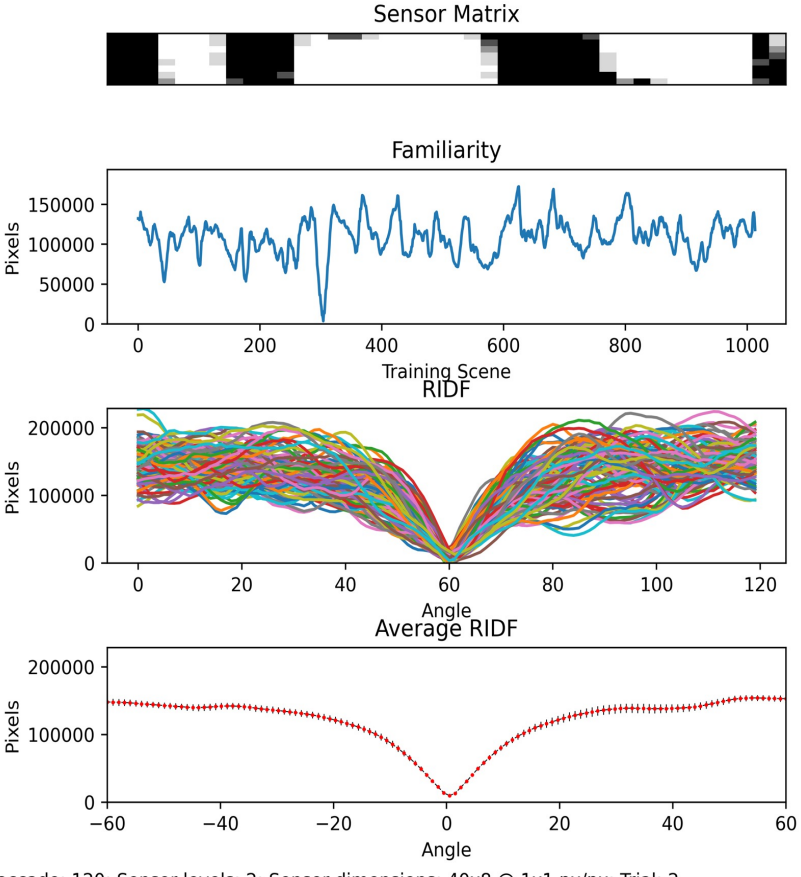


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 61.84; RMSD/dist: 0.155; TD: 98907; p90: 26; p50: 12; complete: 0

100%

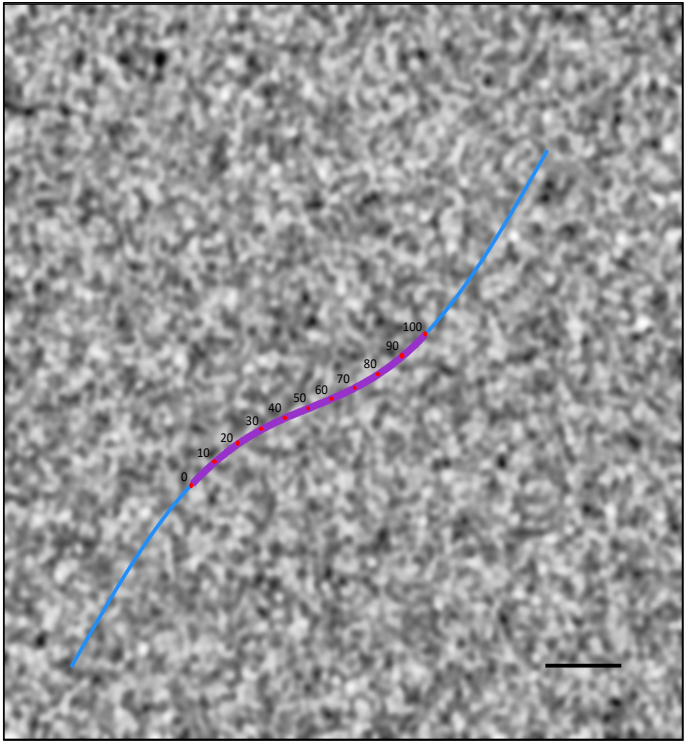


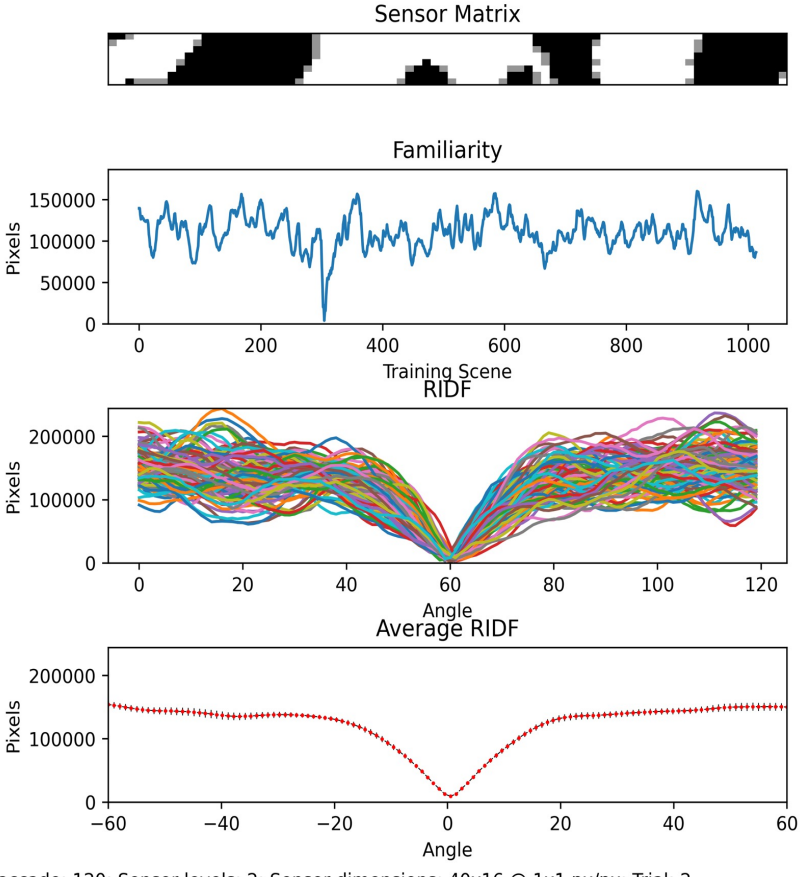


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 41.52; RMSD/dist: 0.104; TD: 102908; p90: 26; p50: 12; complete: 0

100%

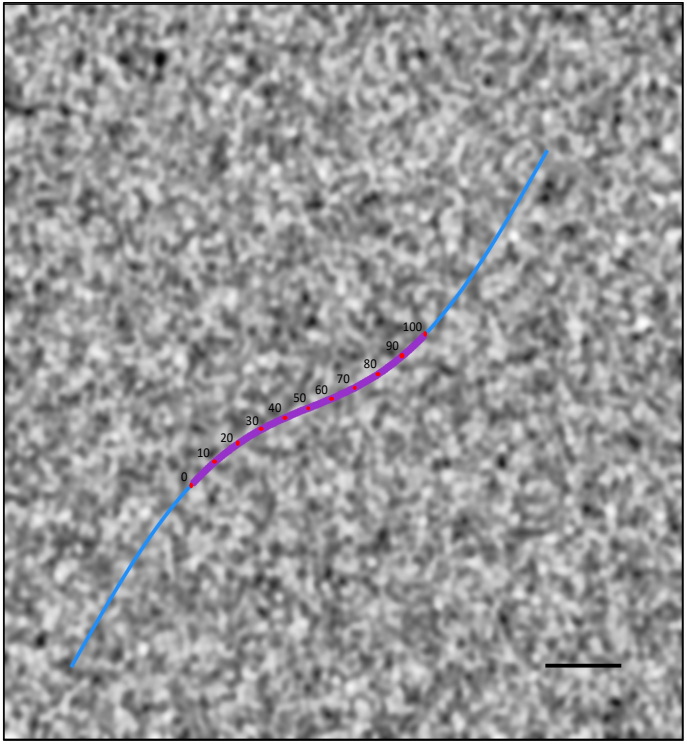


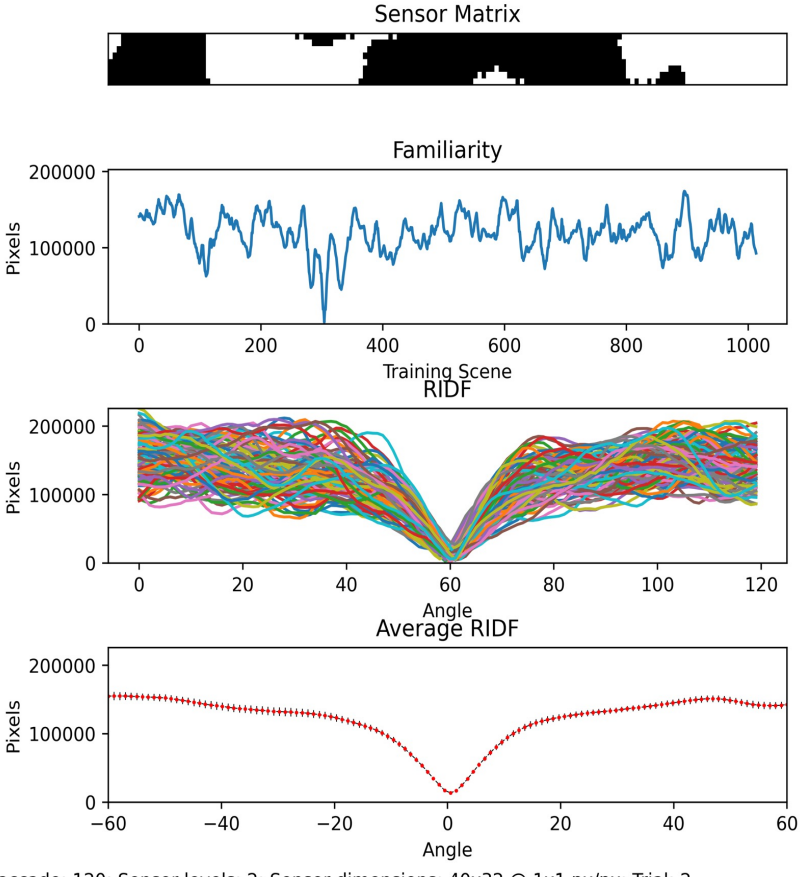


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 31.26; RMSD/dist: 0.078; TD: 102784; p90: 24; p50: 12; complete: 0

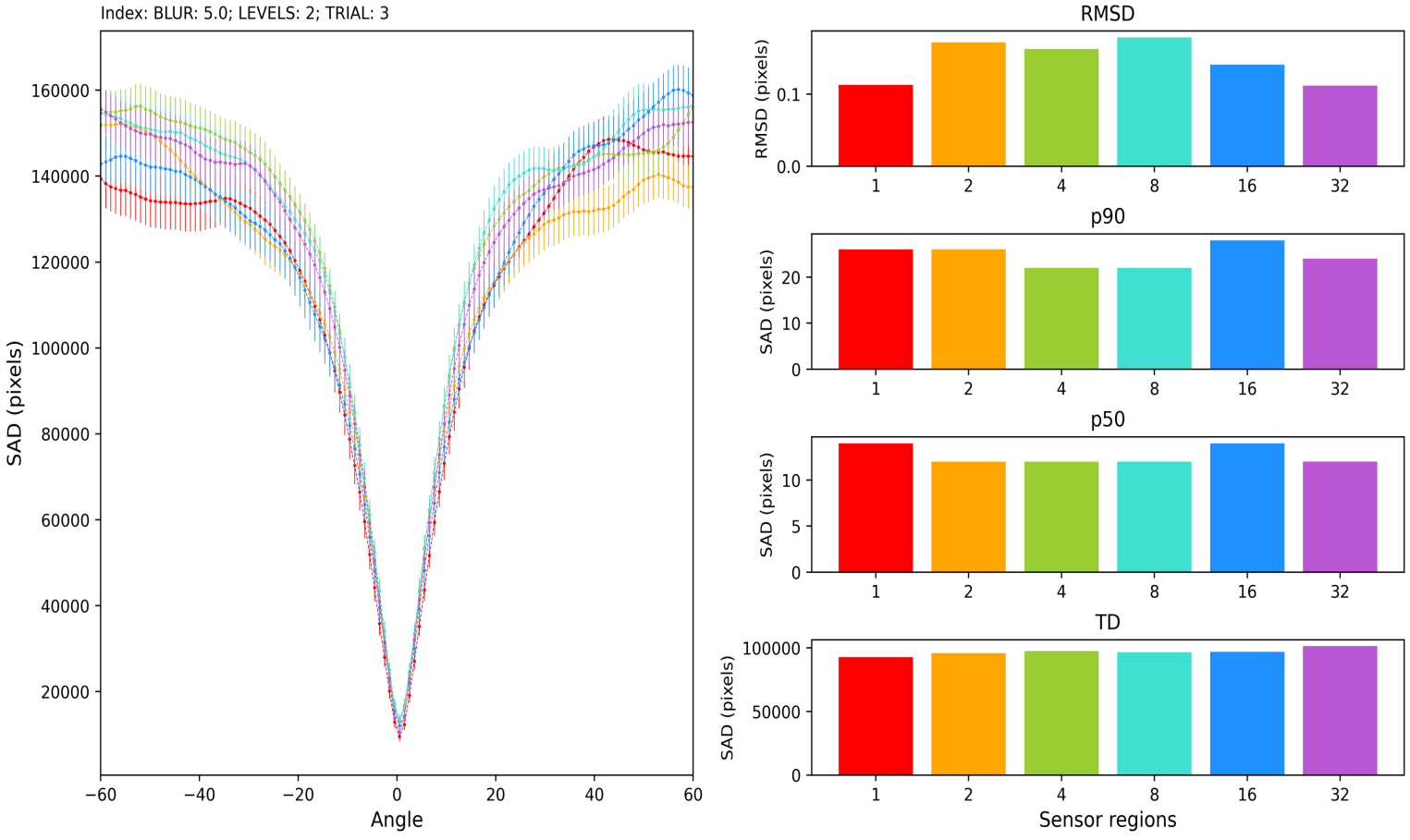
100%



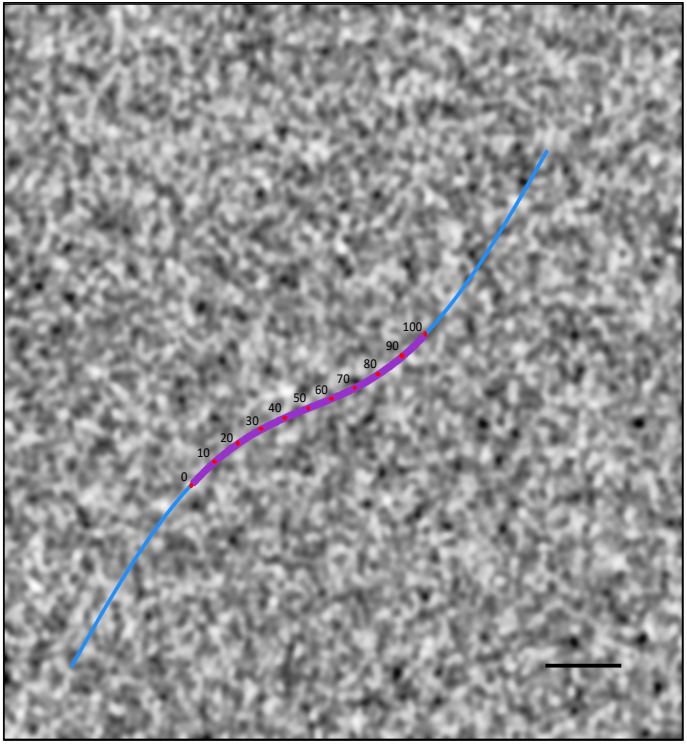


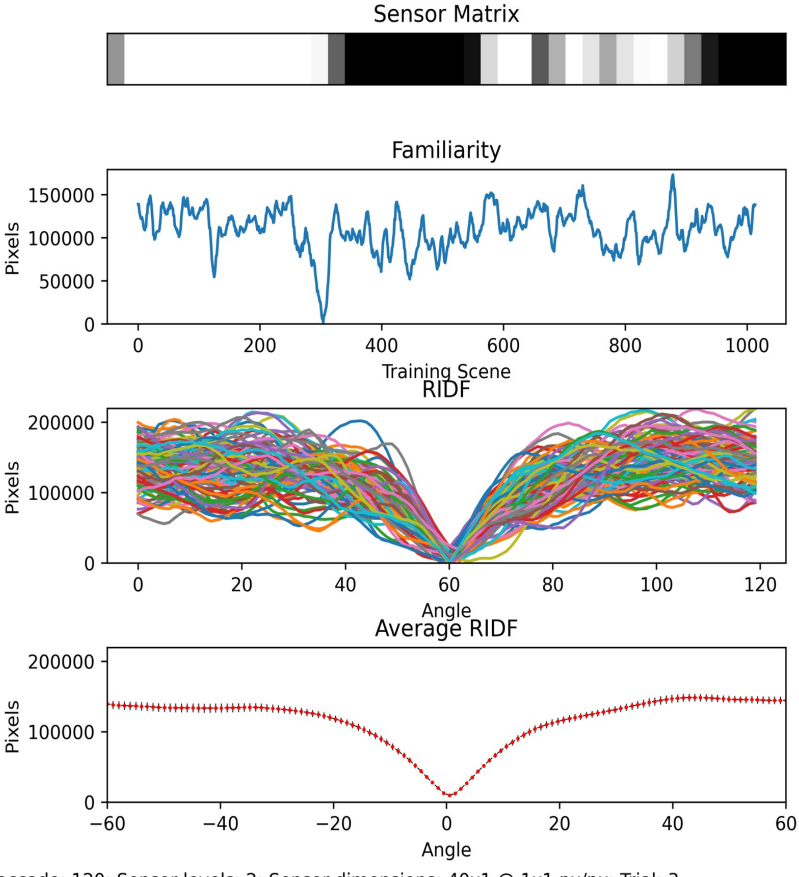
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 57.97; RMSD/dist: 0.145; TD: 100547; p90: 26; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 3
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

100%

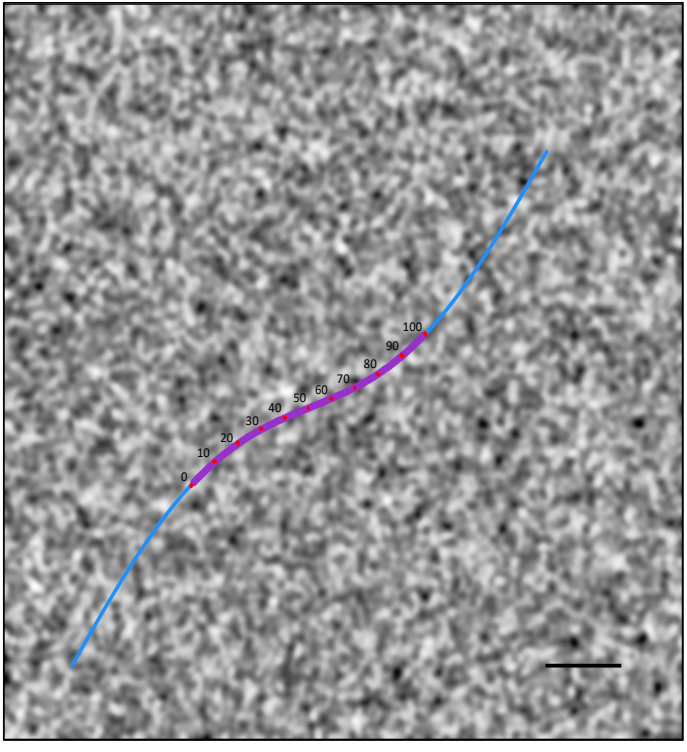


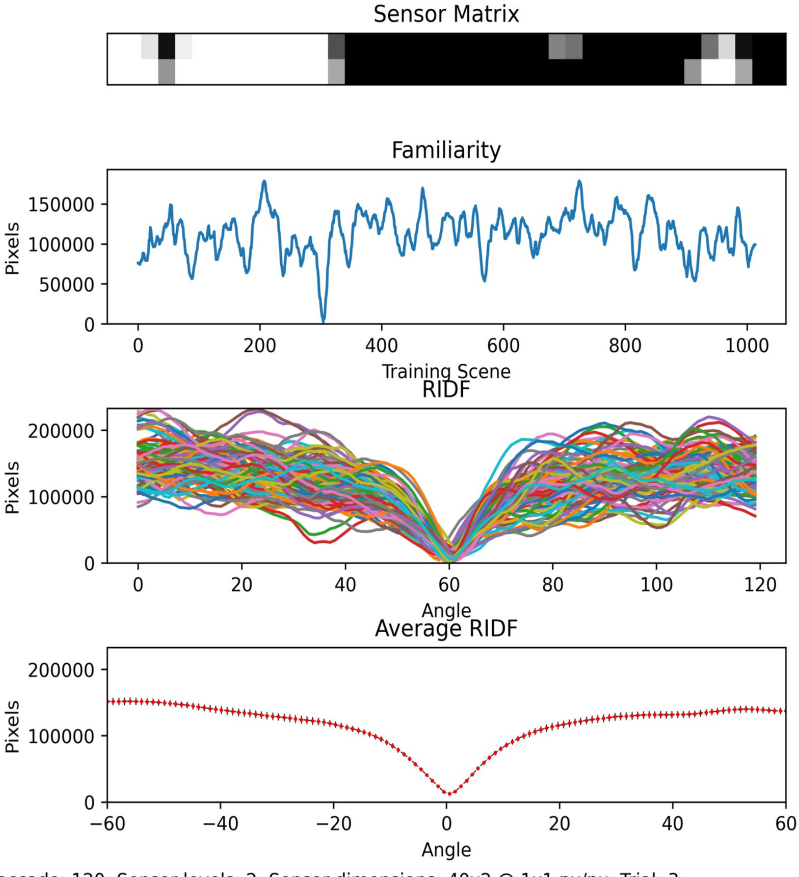


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 45.04; RMSD/dist: 0.113; TD: 92699; p90: 26; p50: 14; complete: 0

100%

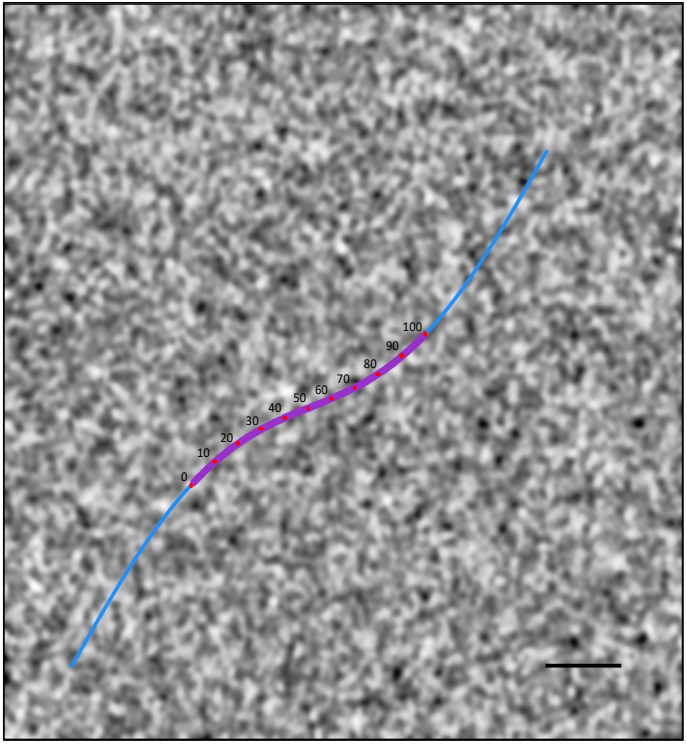


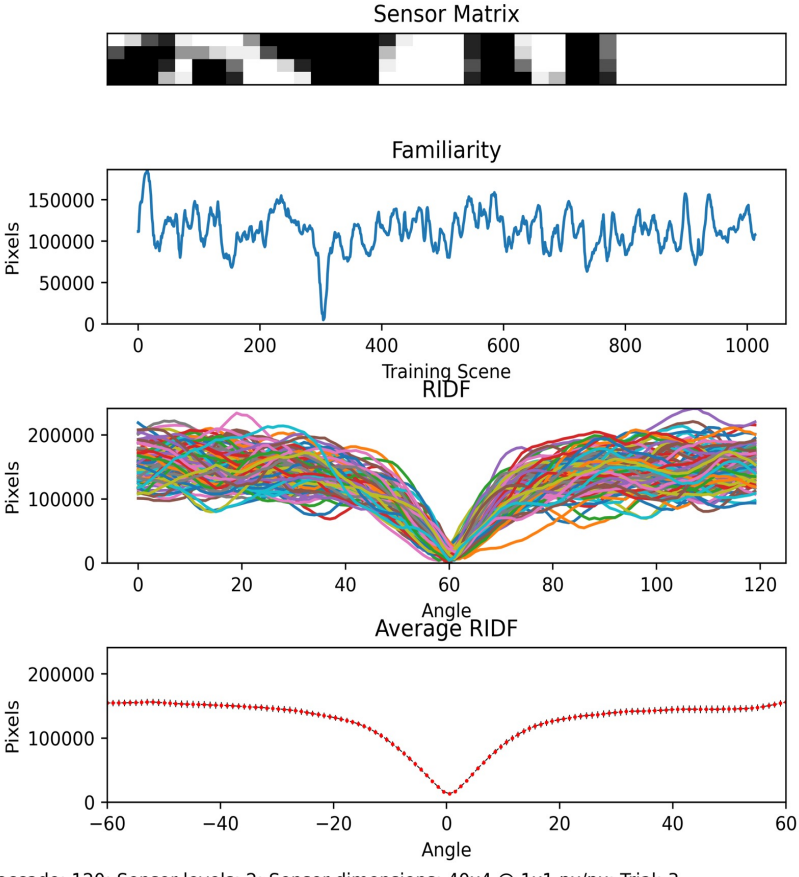


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 68.72; RMSD/dist: 0.172; TD: 95940; p90: 26; p50: 12; complete: 0

100%

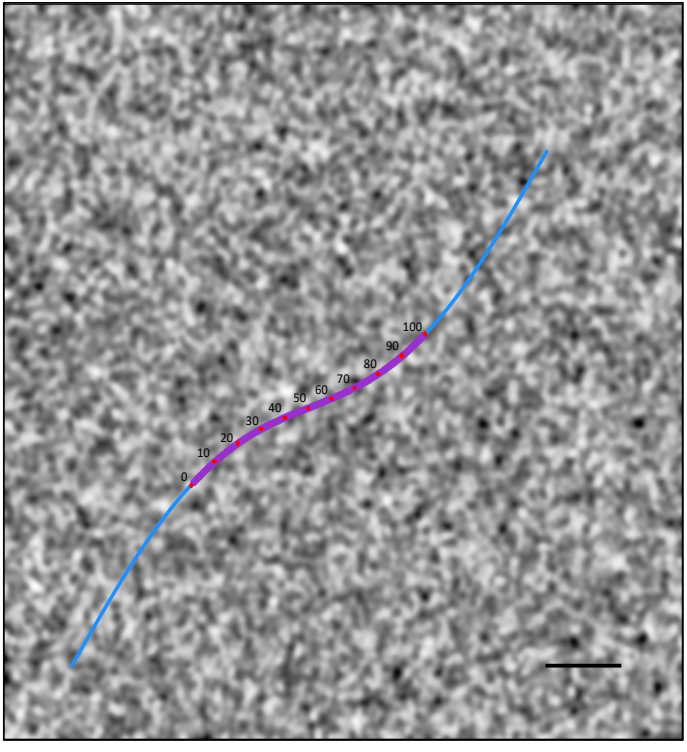


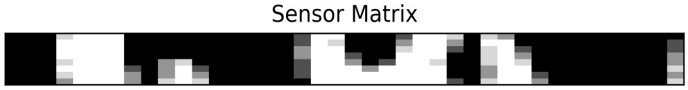


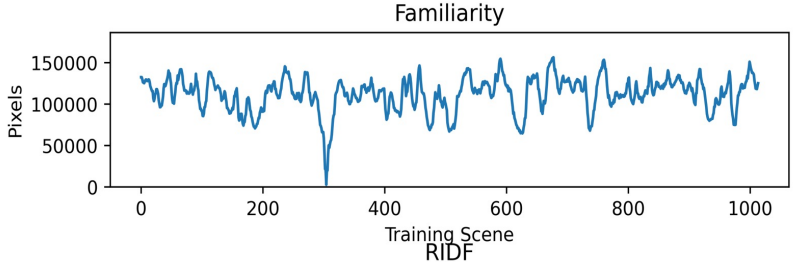
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

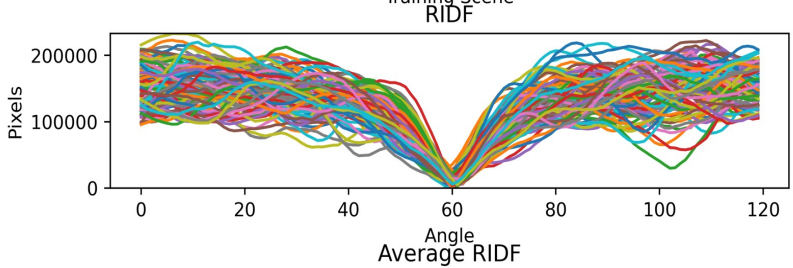
Navigation stats: RMSD error: 65.26; RMSD/dist: 0.163; TD: 97441; p90: 22; p50: 12; complete: 0

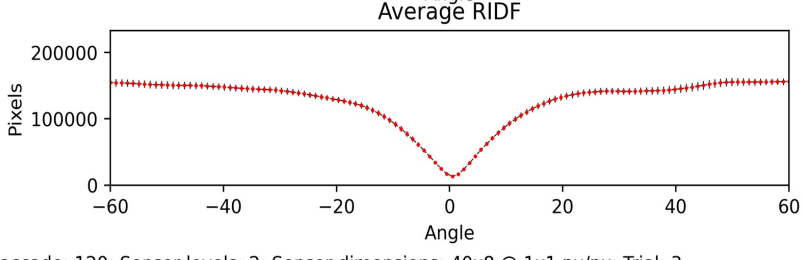
100%







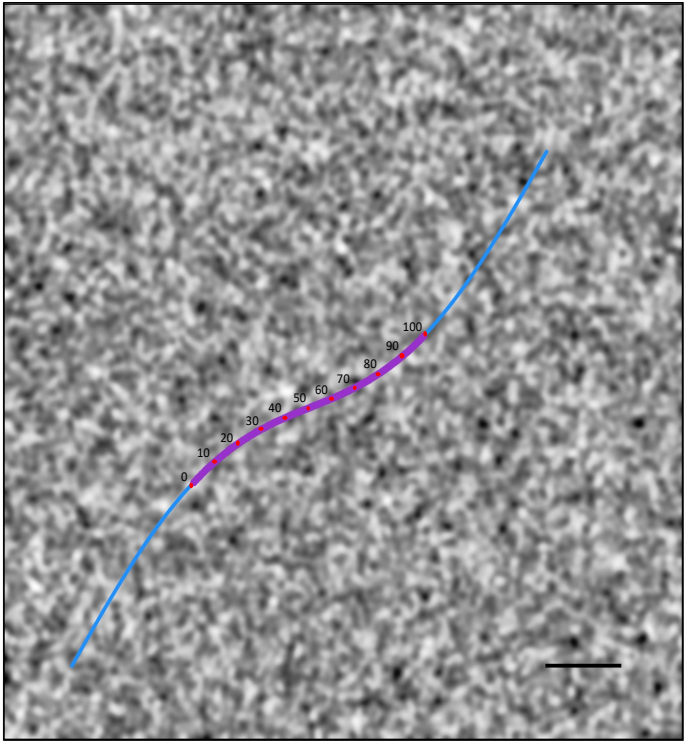


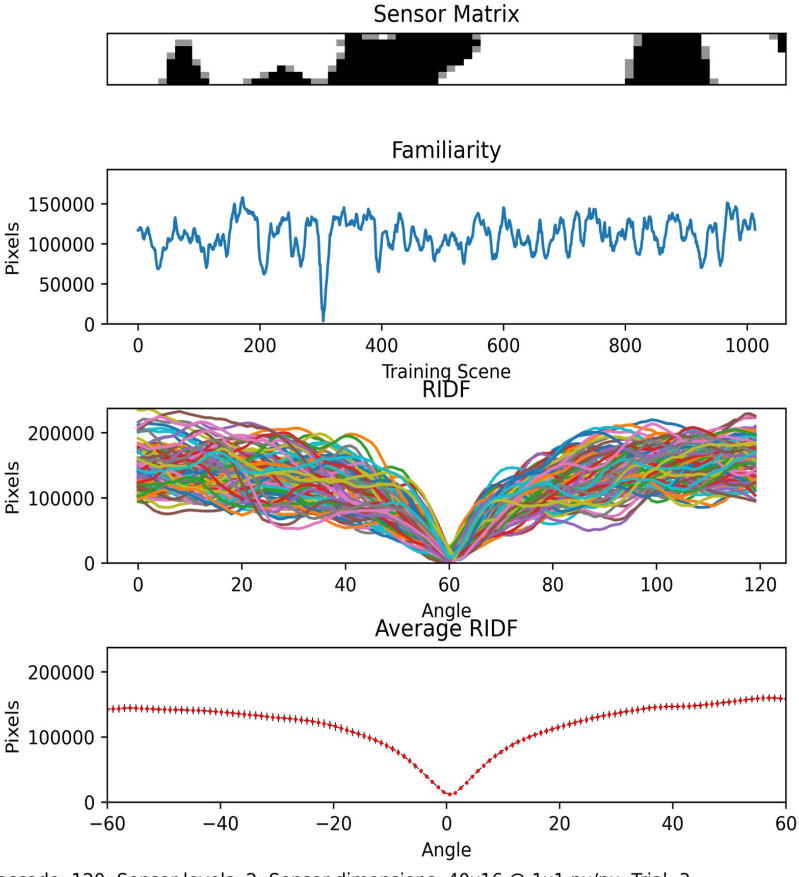


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 71.54; RMSD/dist: 0.179; TD: 96548; p90: 22; p50: 12; complete: 0

100%

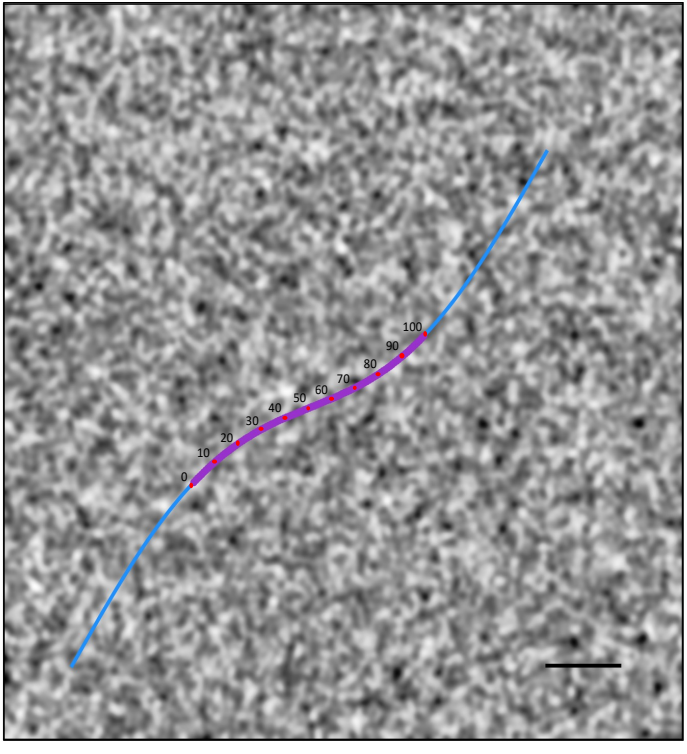


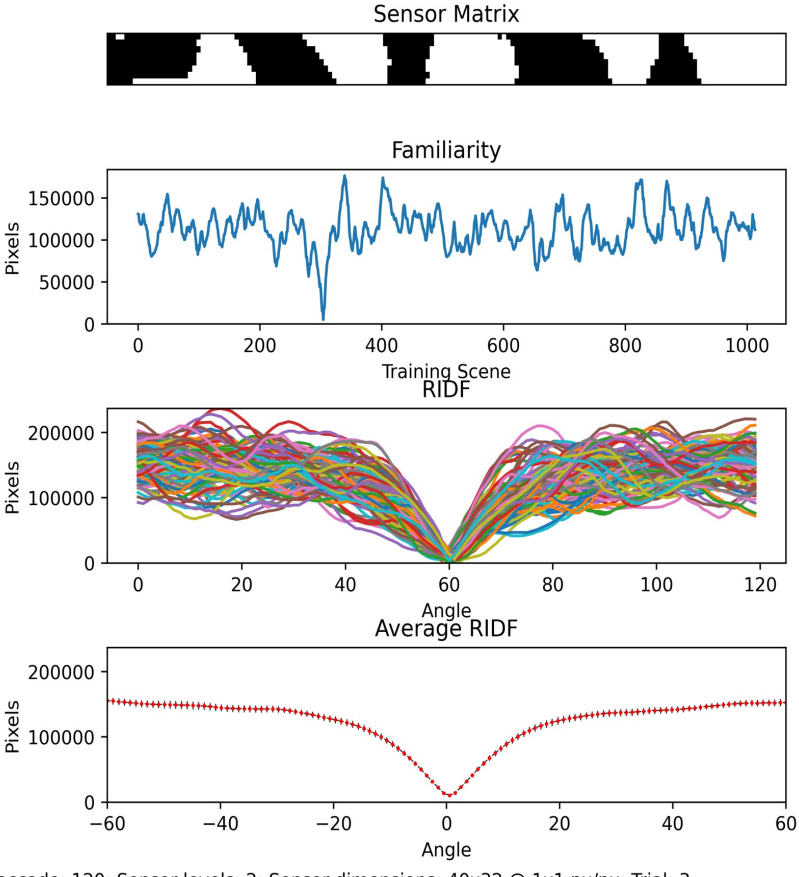


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 56.34; RMSD/dist: 0.141; TD: 96923; p90: 28; p50: 14; complete: 0

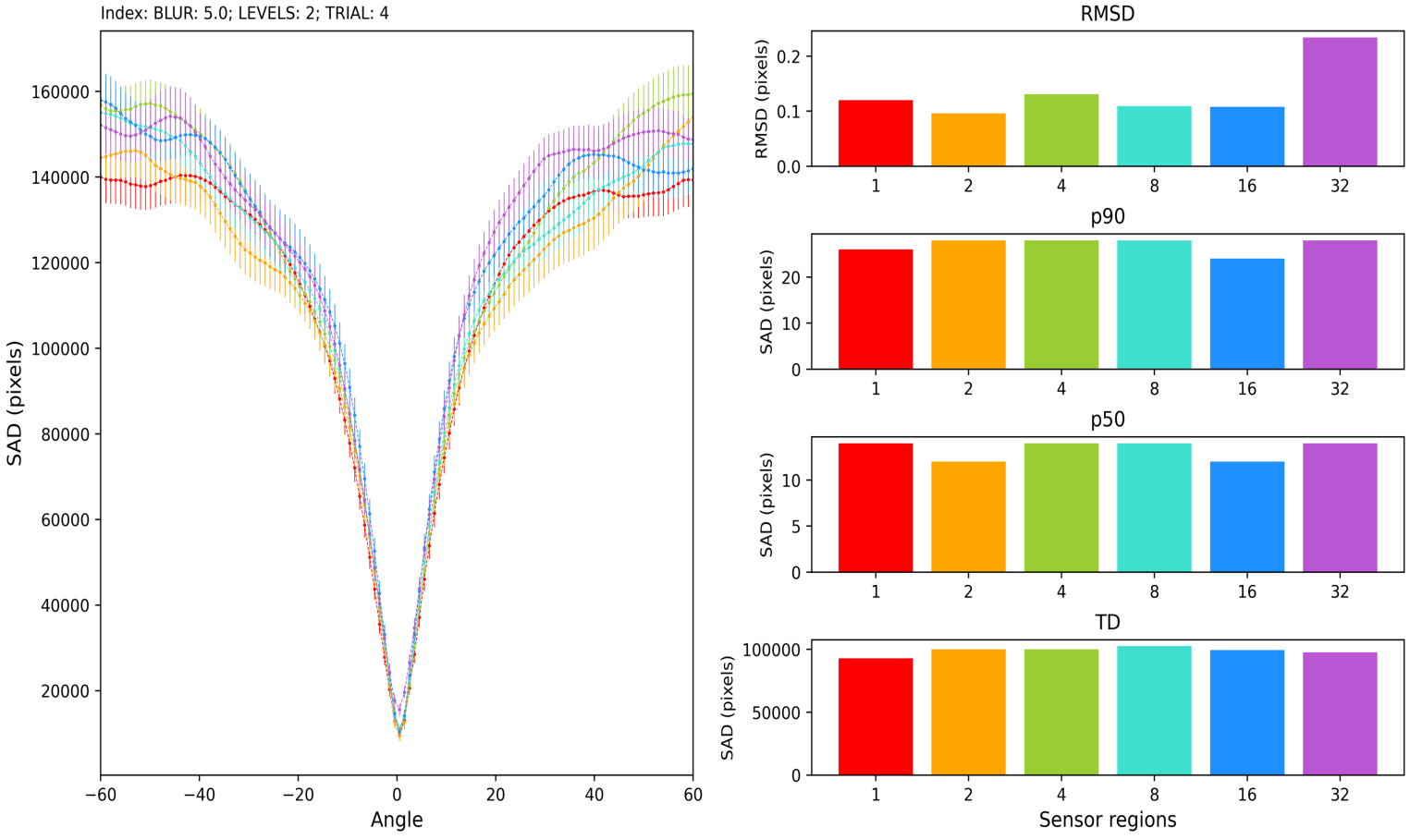
100%



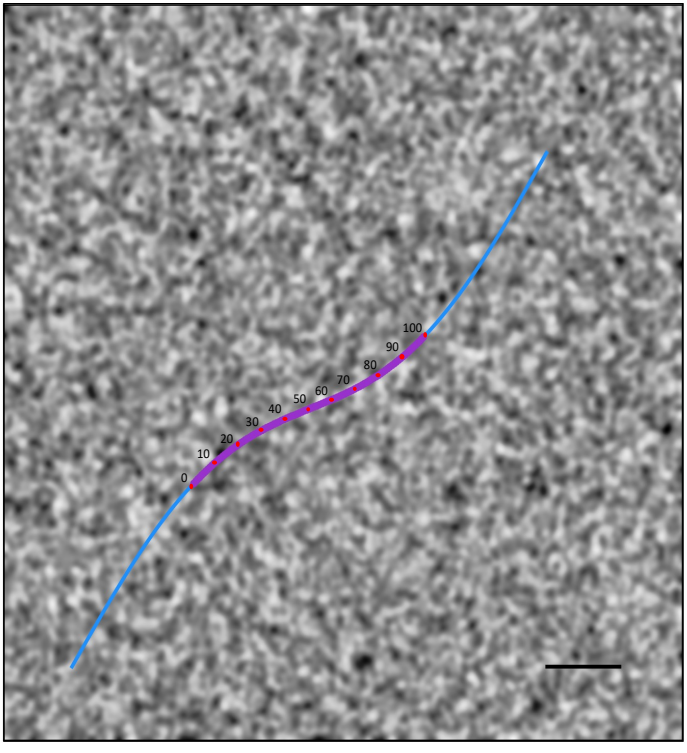


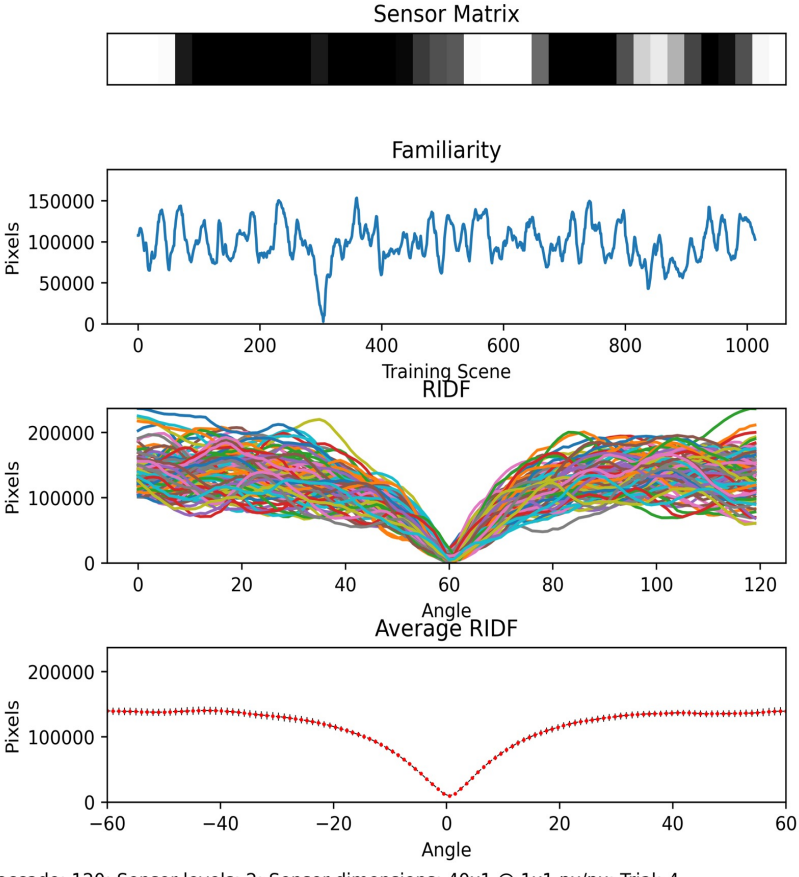
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 44.62; RMSD/dist: 0.112; TD: 101312; p90: 24; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 4
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

100%

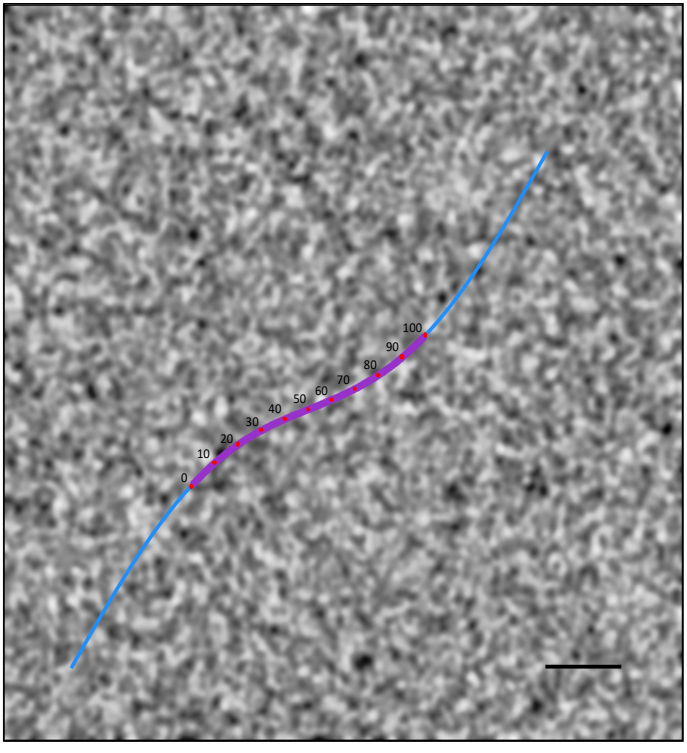


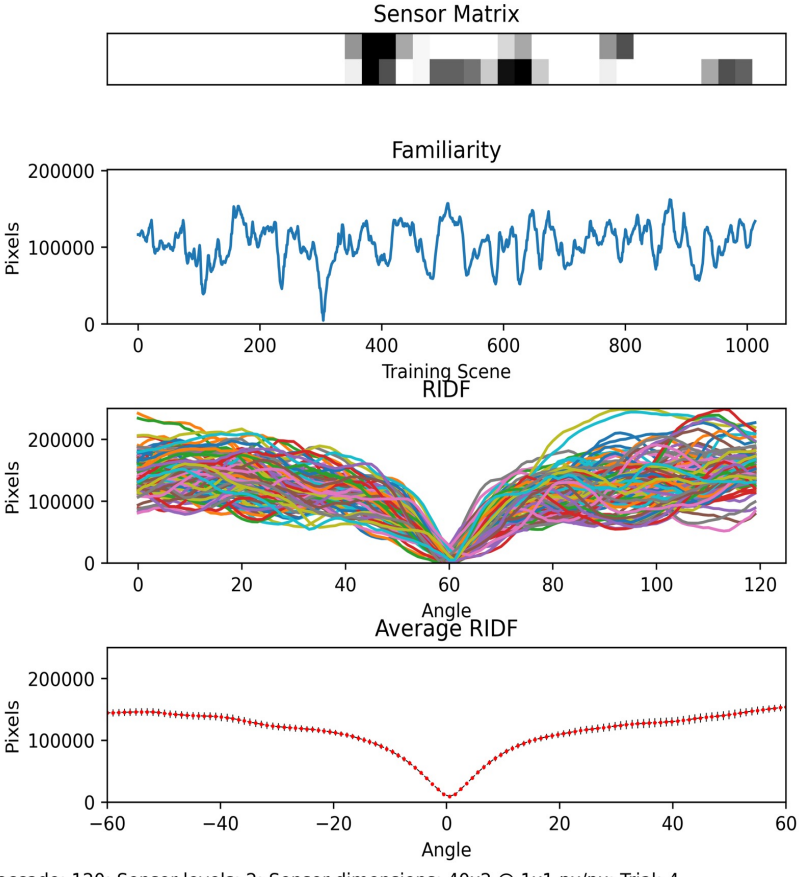


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 48.08; RMSD/dist: 0.120; TD: 92725; p90: 26; p50: 14; complete: 0

100%

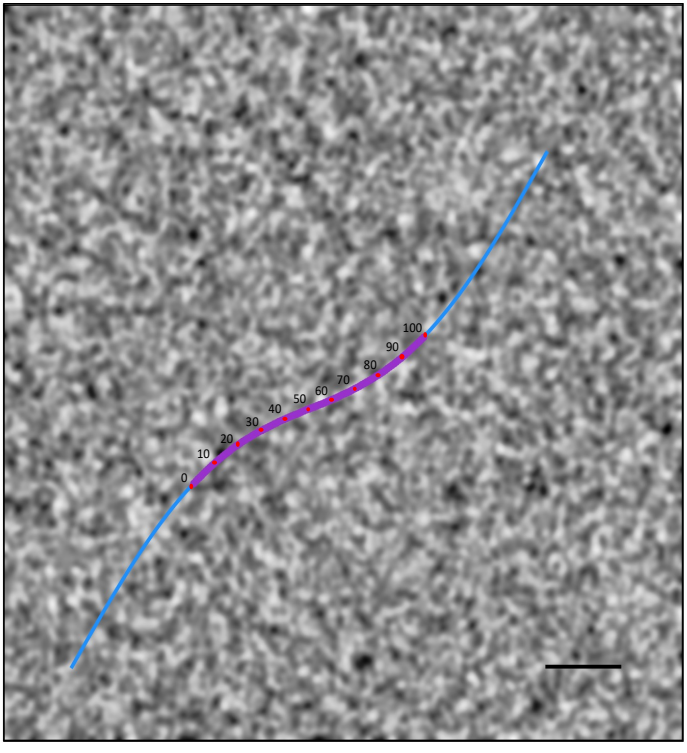


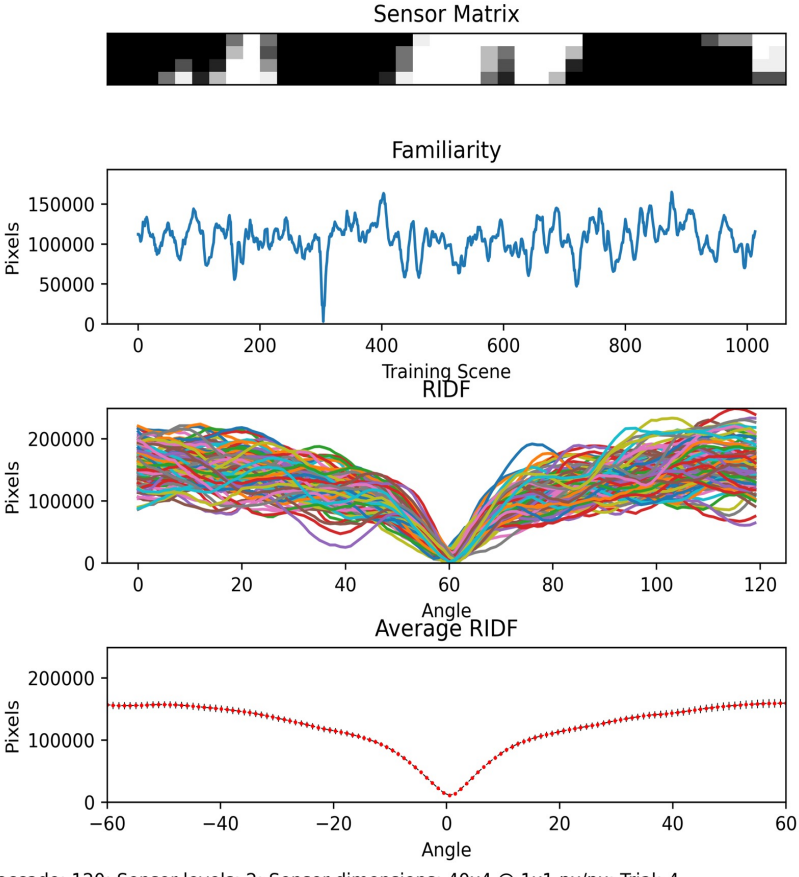


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 38.49; RMSD/dist: 0.096; TD: 99879; p90: 28; p50: 12; complete: 0

100%

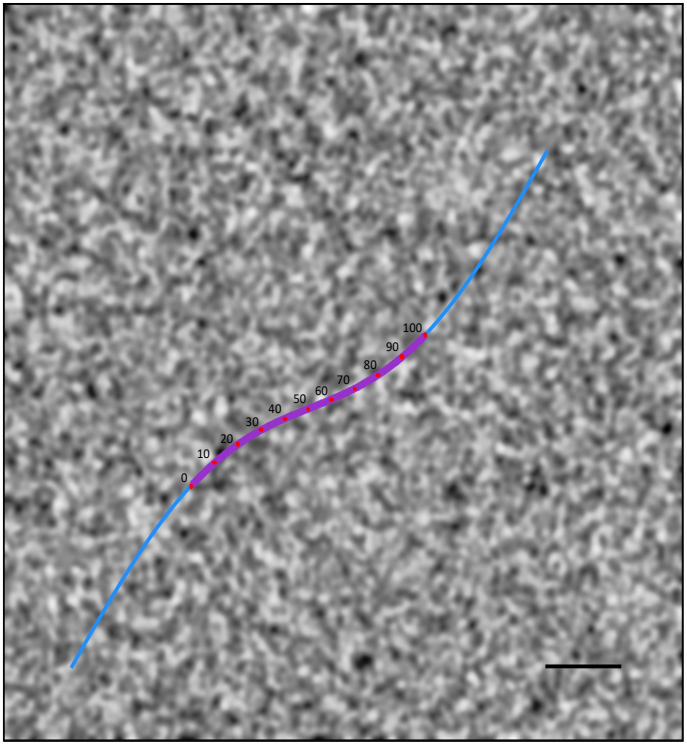


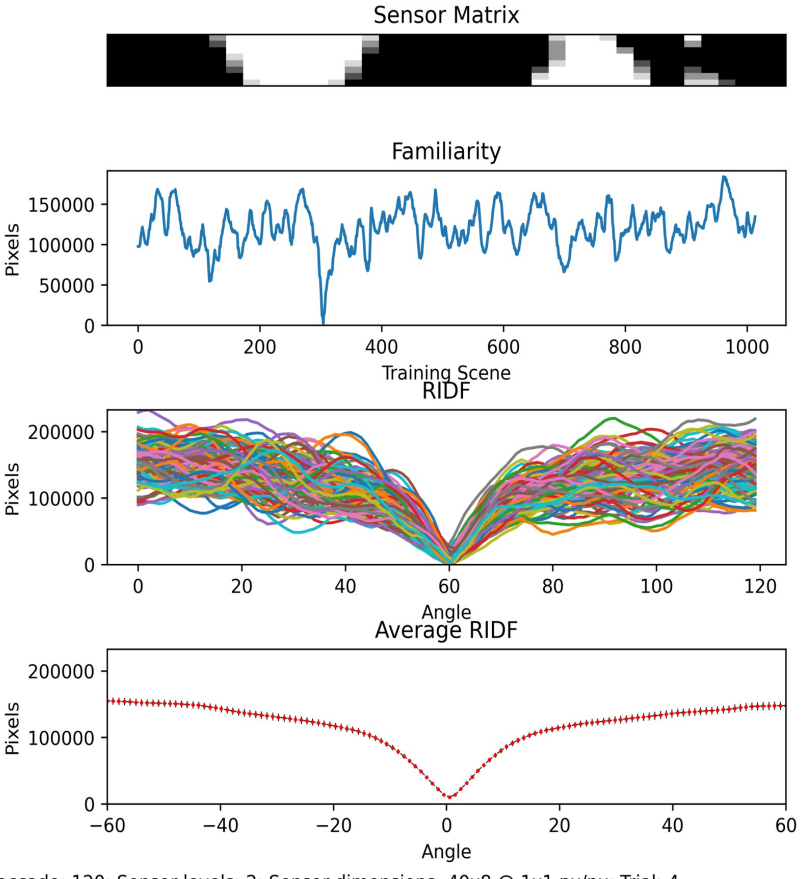


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 52.59; RMSD/dist: 0.131; TD: 100005; p90: 28; p50: 14; complete: 0

100%

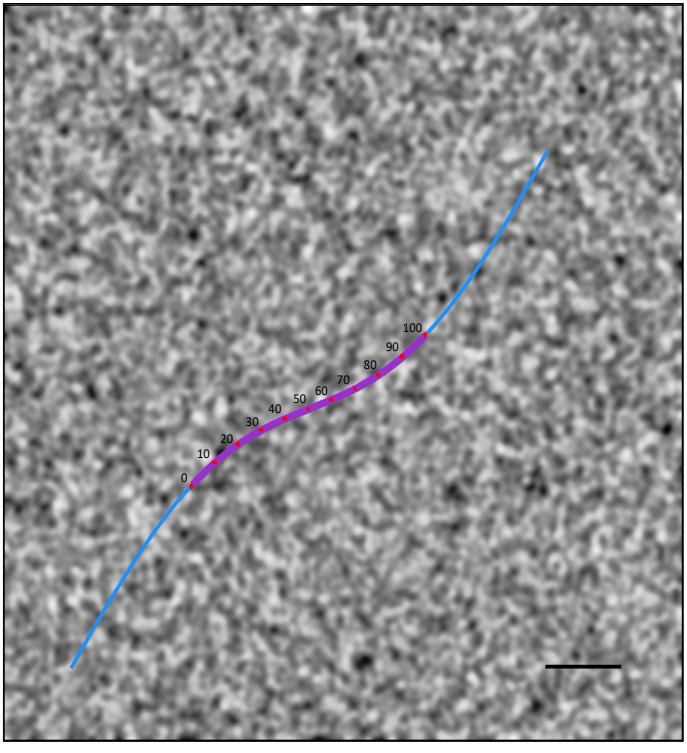


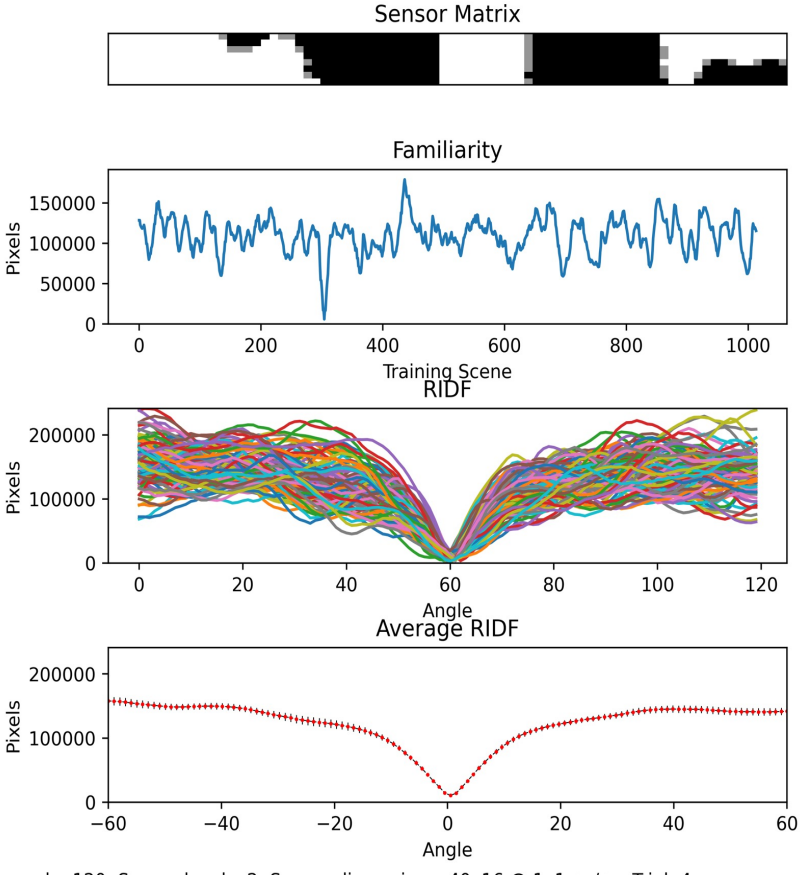


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 43.51; RMSD/dist: 0.109; TD: 102430; p90: 28; p50: 14; complete: 0

100%

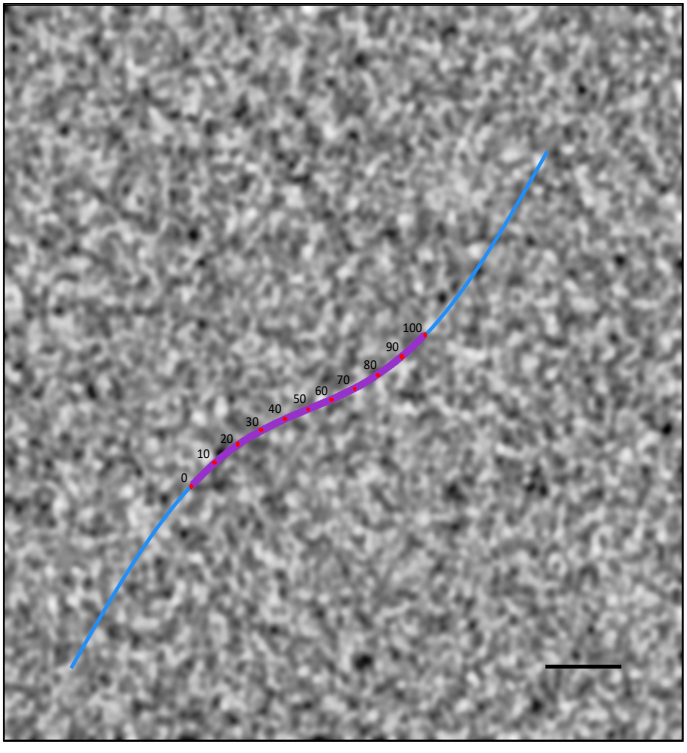


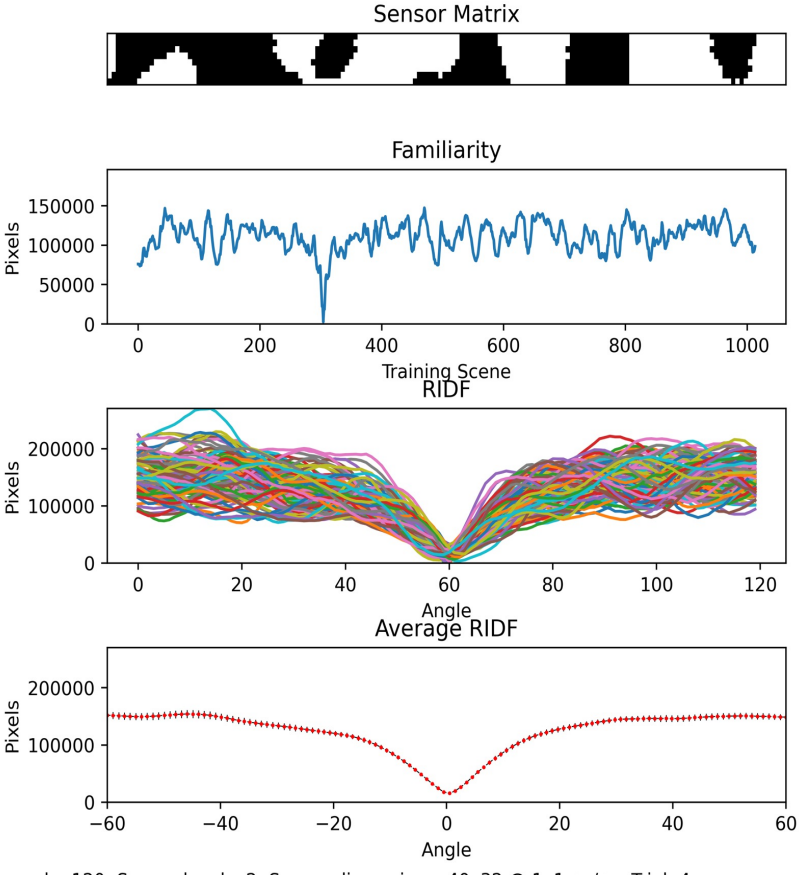


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 43.17; RMSD/dist: 0.108; TD: 99358; p90: 24; p50: 12; complete: 0

100%





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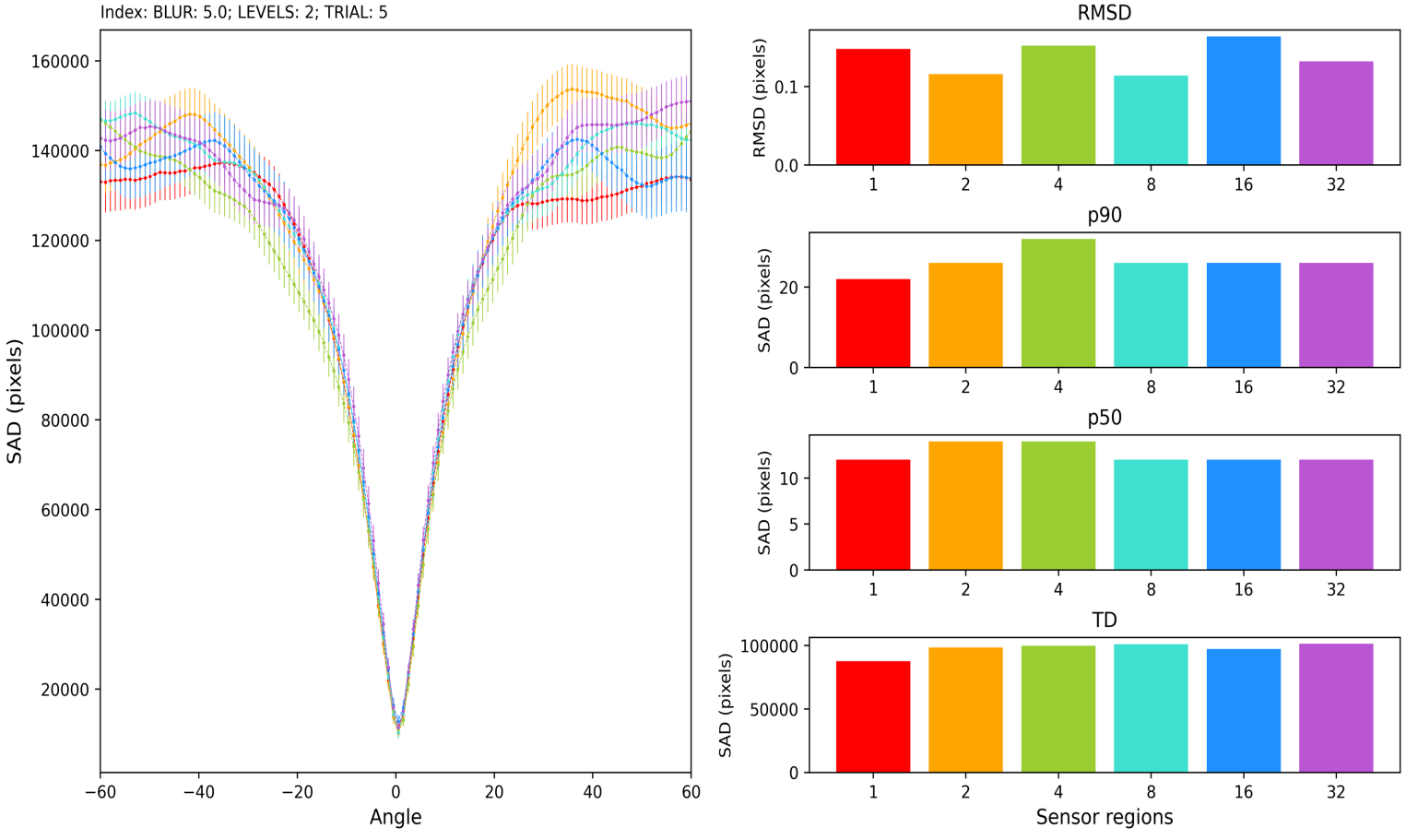
Navigation stats: RMSD error: 93.63; RMSD/dist: 0.234; TD: 97597; p90: 28; p50: 14; complete: 0


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 5
SAD (pixels)
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140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
20
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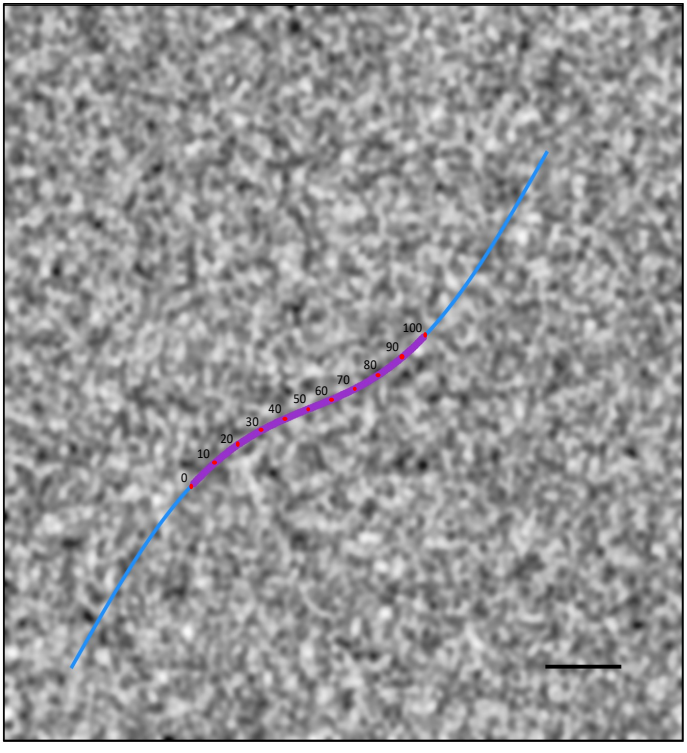
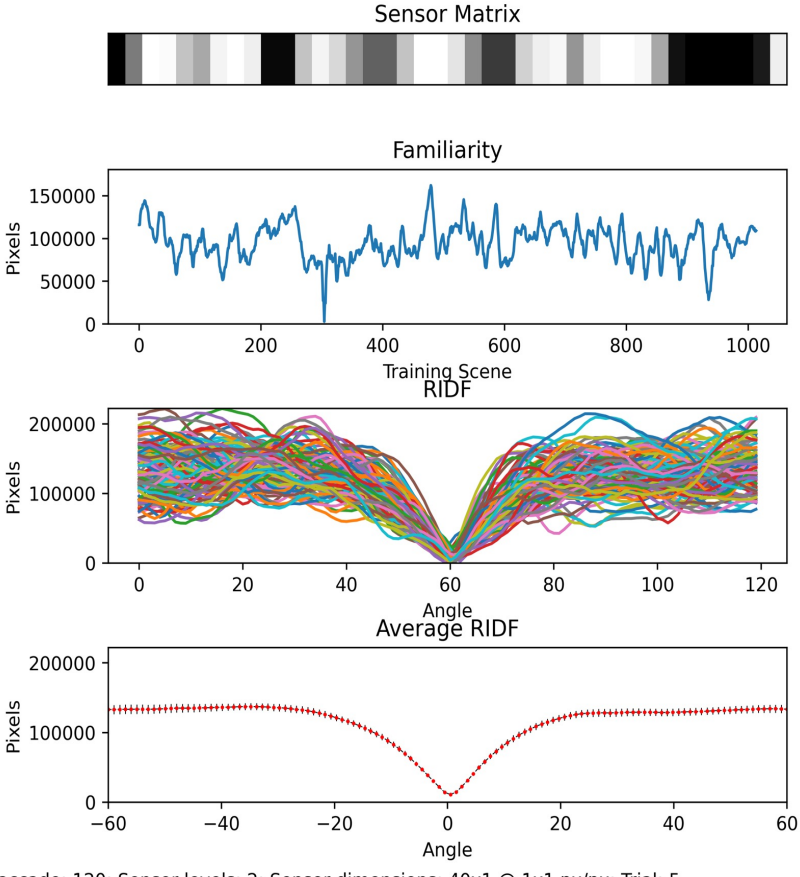
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

100%

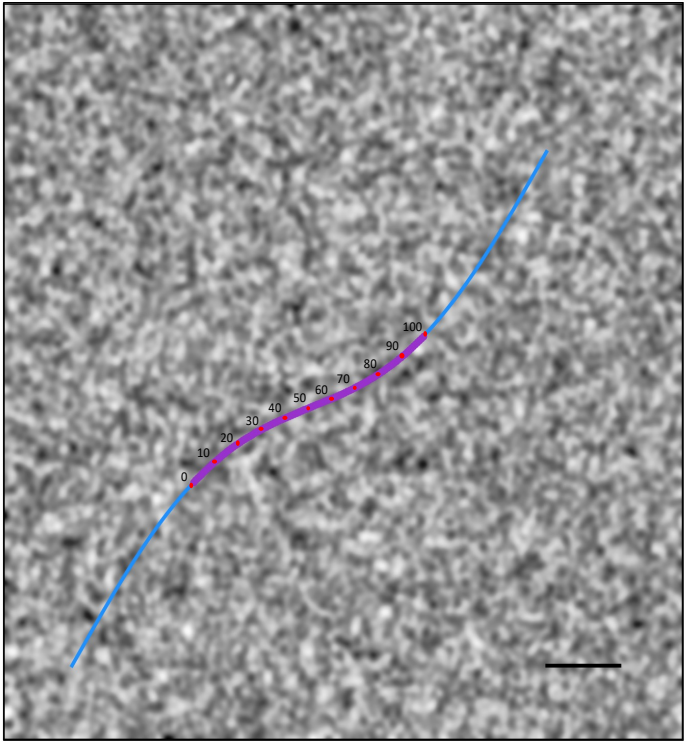


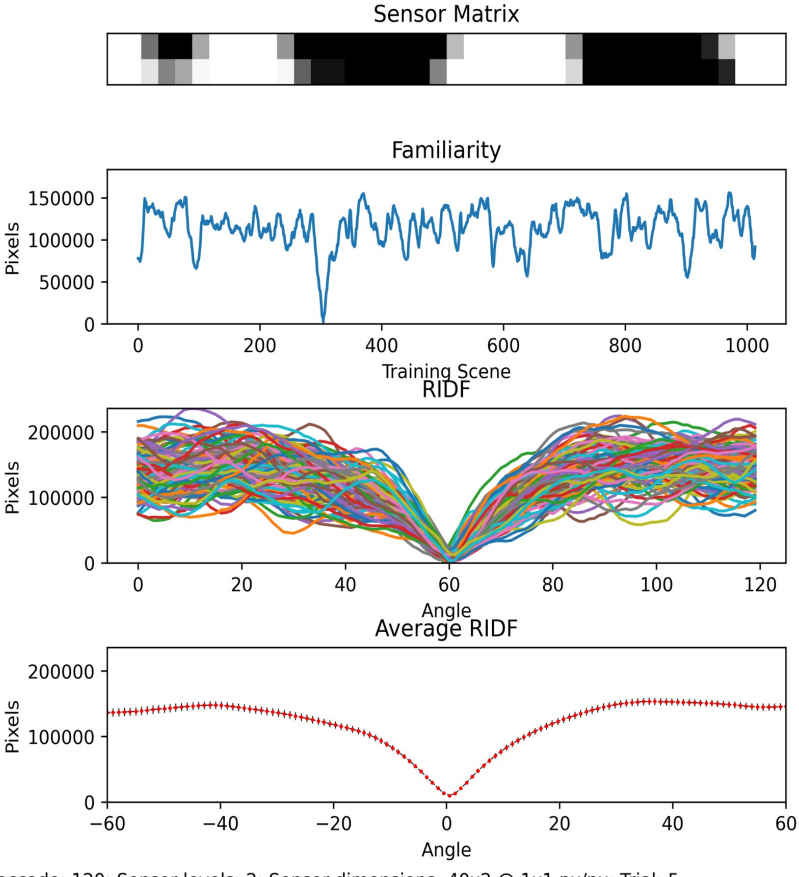


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 59.33; RMSD/dist: 0.148; TD: 87629; p90: 22; p50: 12; complete: 0

100%

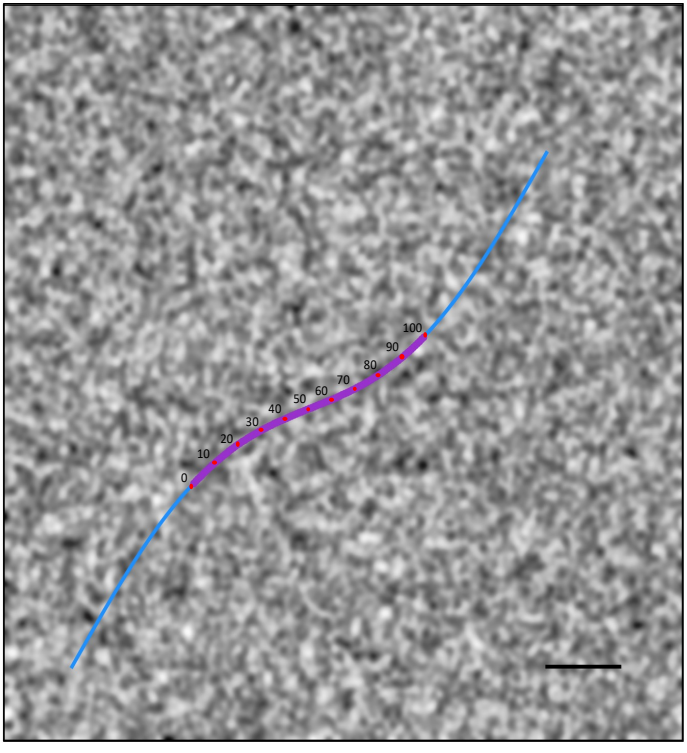


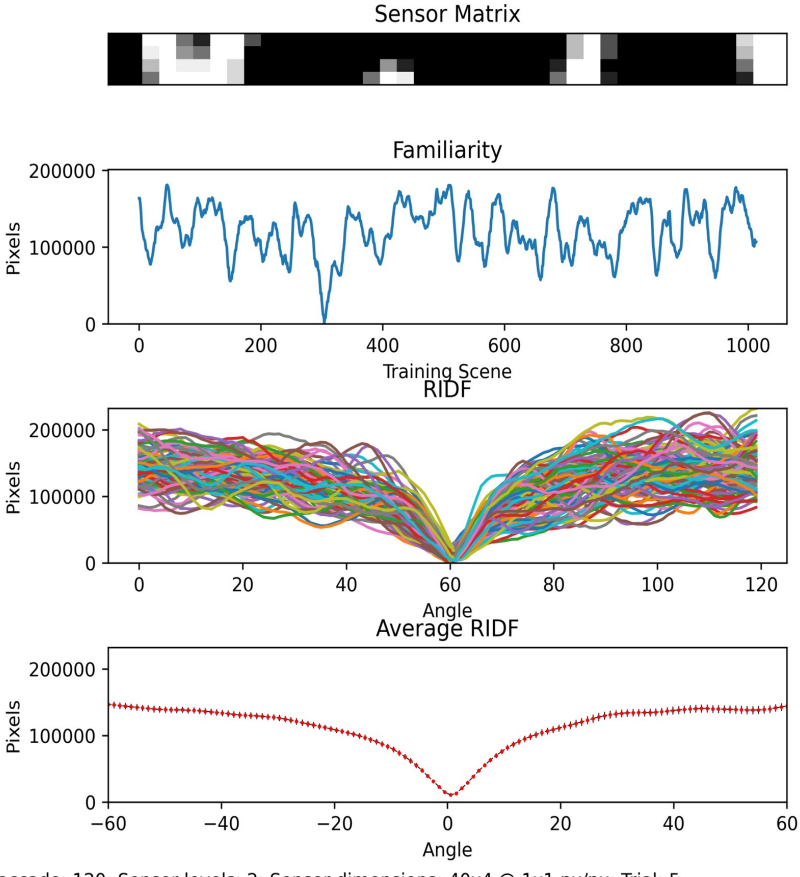


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 46.52; RMSD/dist: 0.116; TD: 98445; p90: 26; p50: 14; complete: 0

100%

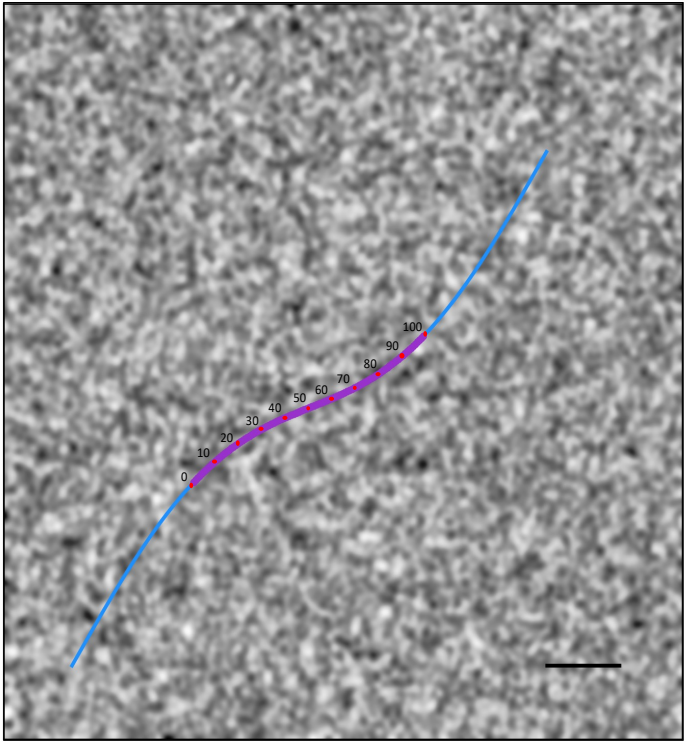


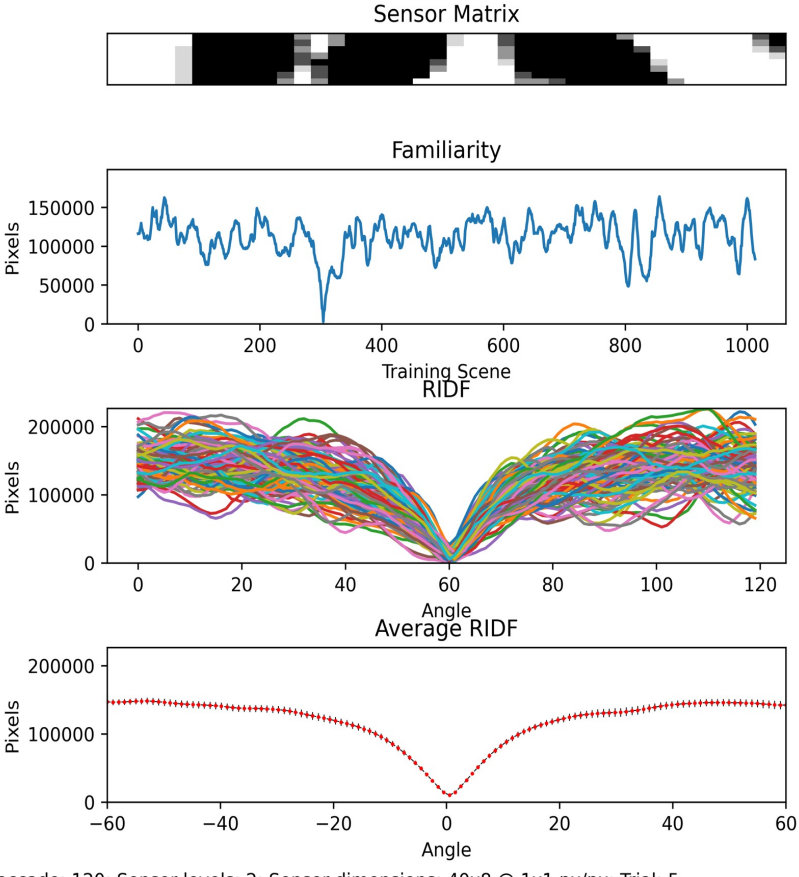


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 60.89; RMSD/dist: 0.152; TD: 99787; p90: 32; p50: 14; complete: 0

100%

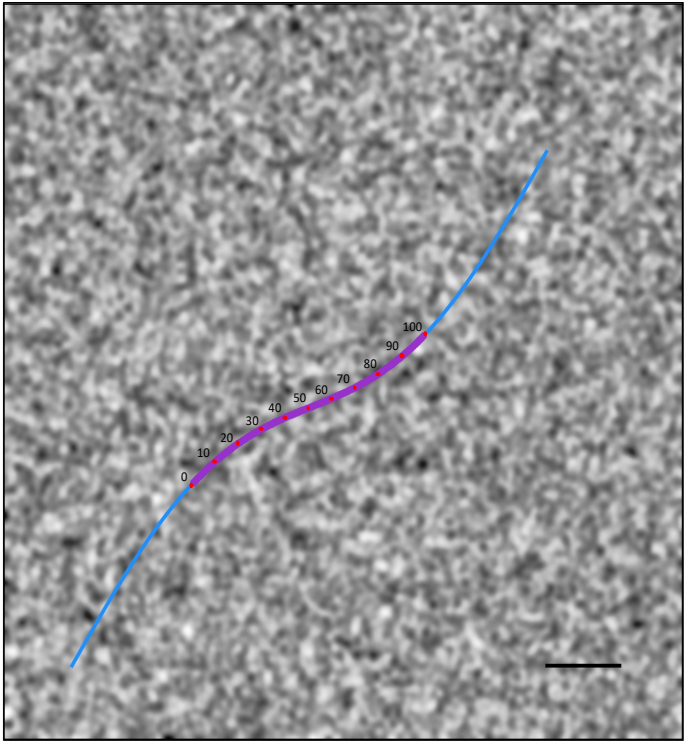


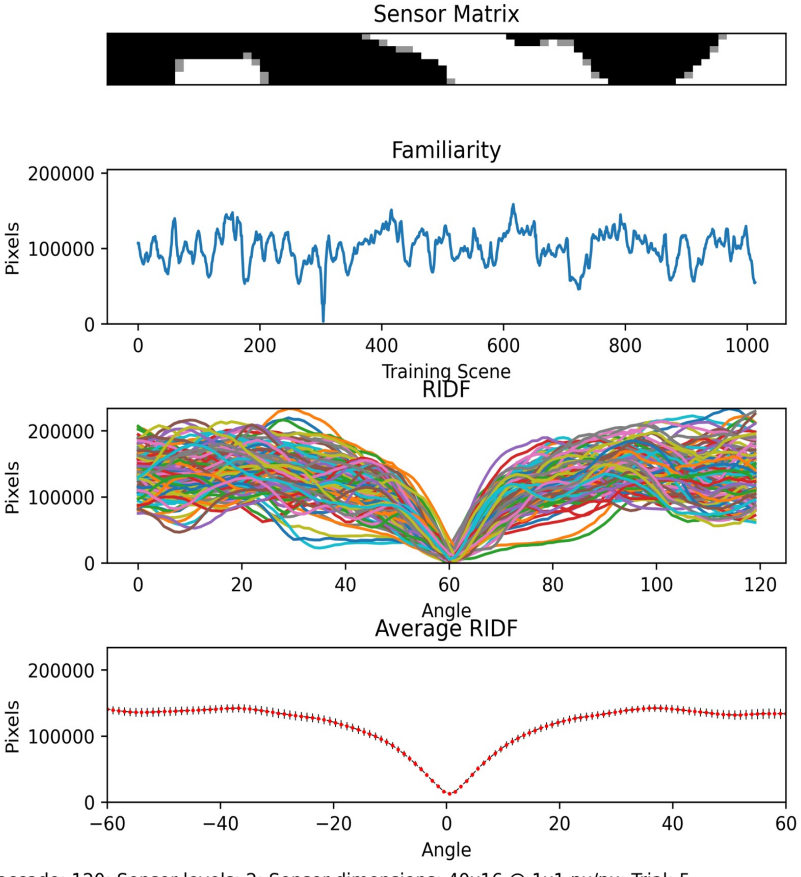


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 45.72; RMSD/dist: 0.114; TD: 101001; p90: 26; p50: 12; complete: 0

100%

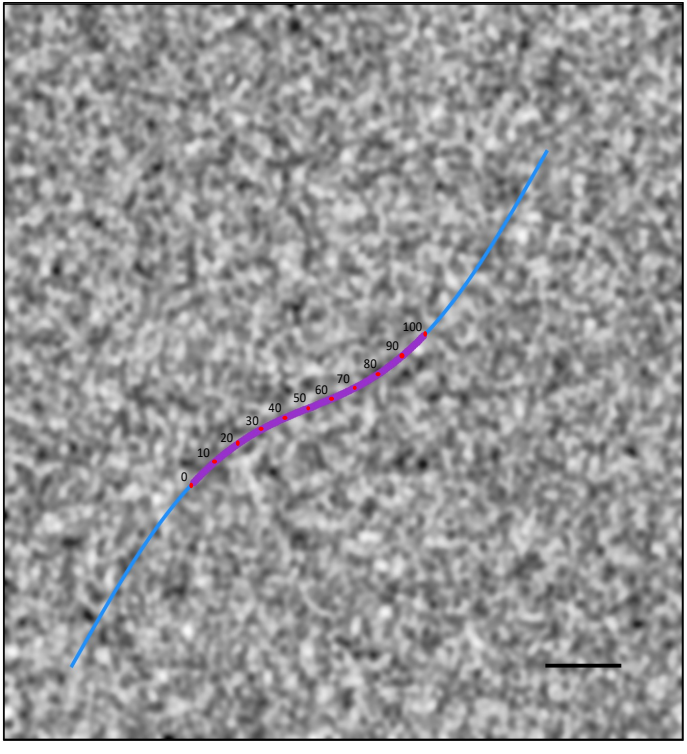


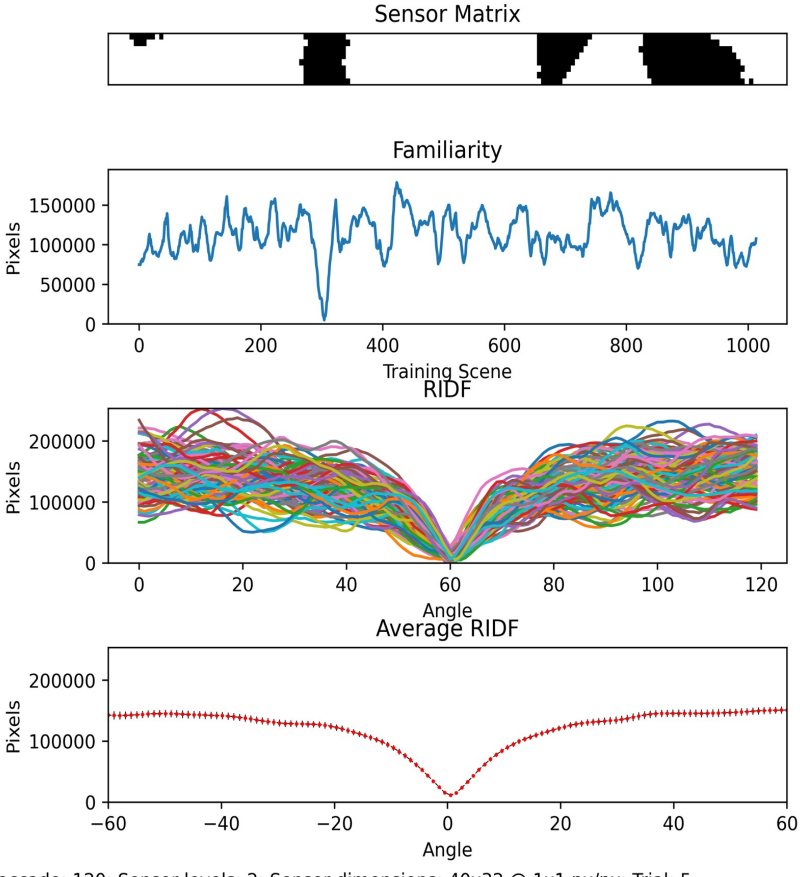


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 65.59; RMSD/dist: 0.164; TD: 97287; p90: 26; p50: 12; complete: 0

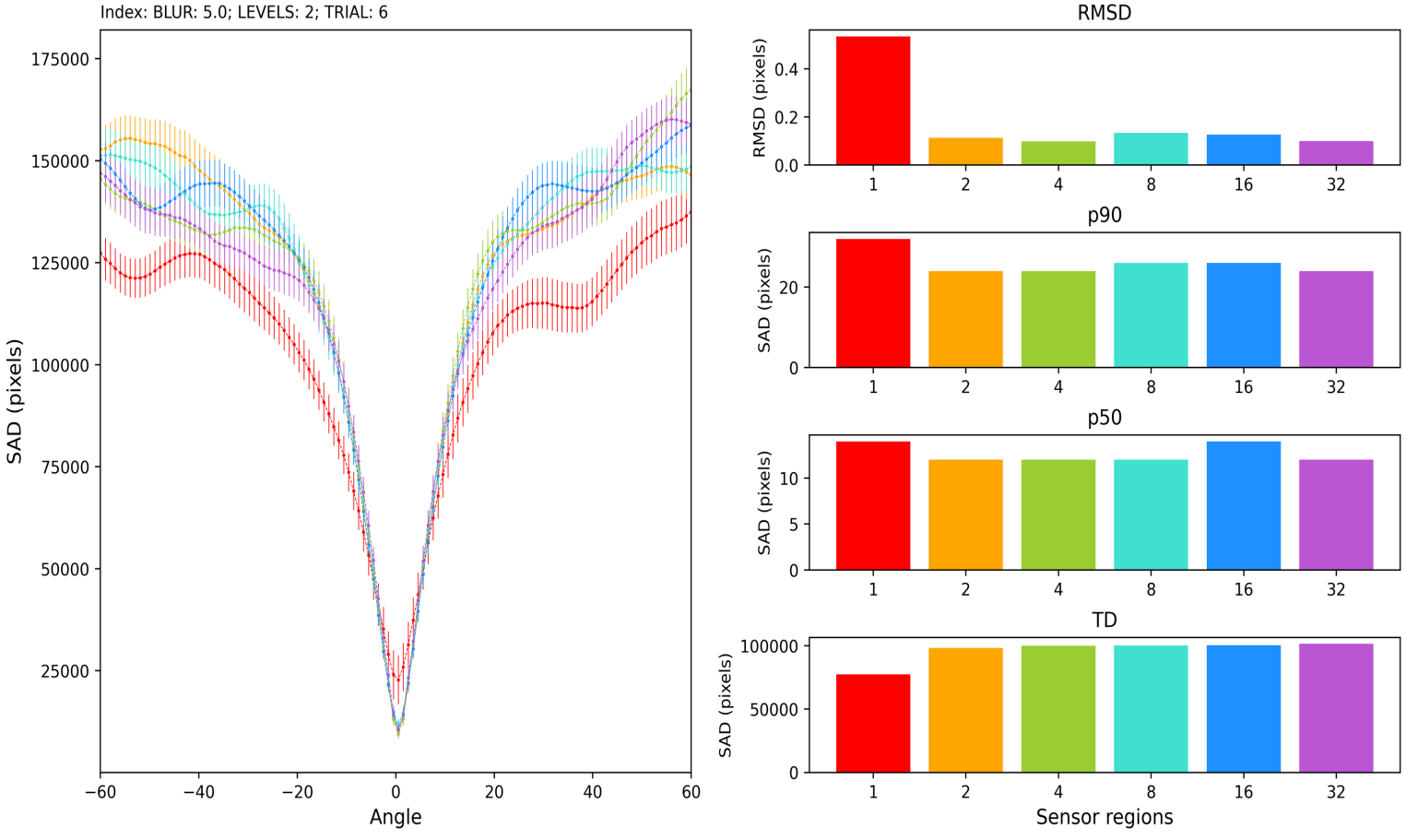
100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 52.67; RMSD/dist: 0.132; TD: 101255; p90: 26; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 6
SAD (pixels)
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150000
125000
100000
75000
50000
25000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.4
0.2
0.0
1
2
4
8
16
32
p90
SAD (pixels)
20
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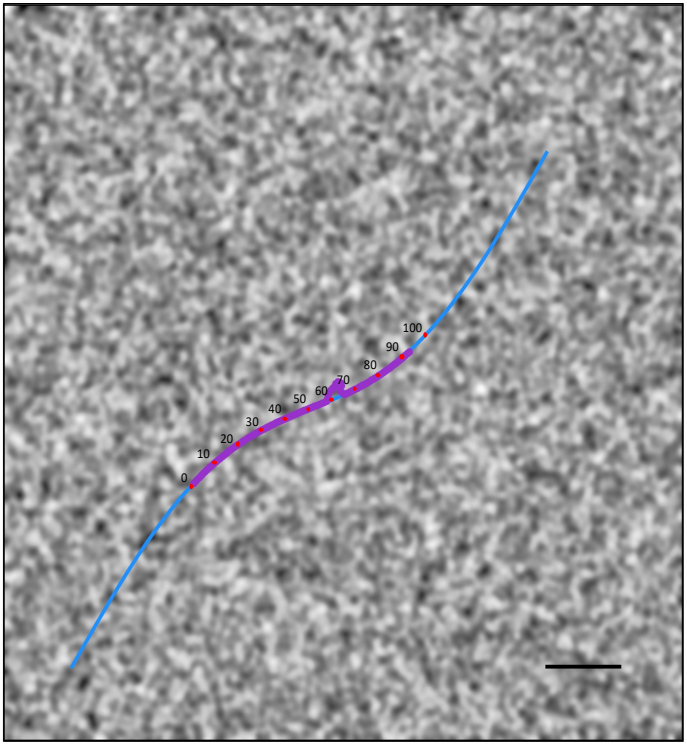
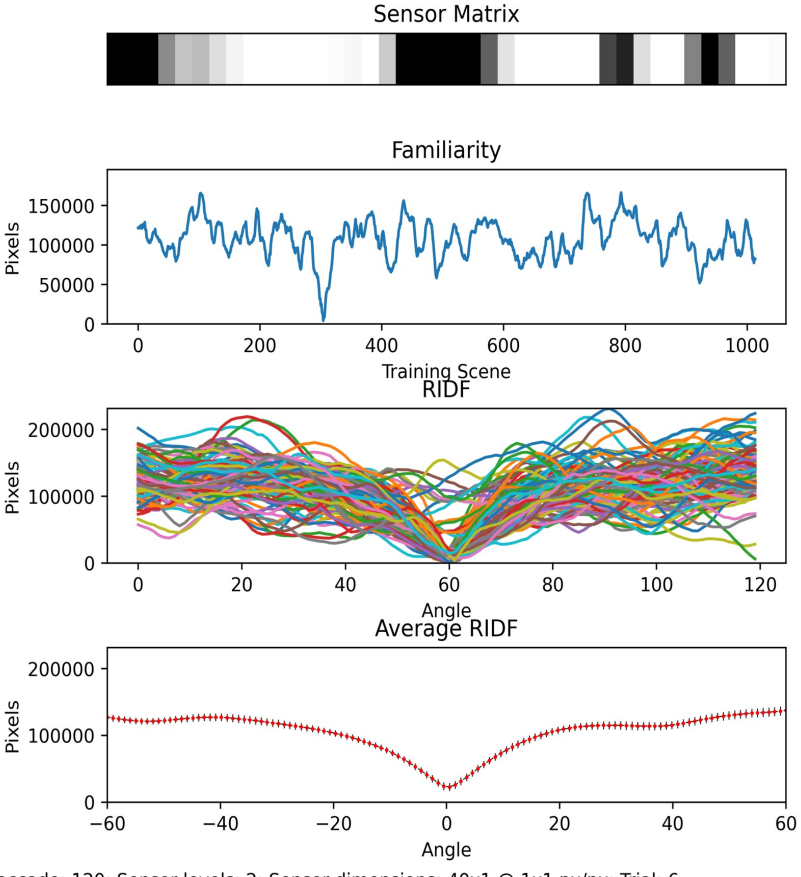
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

80%

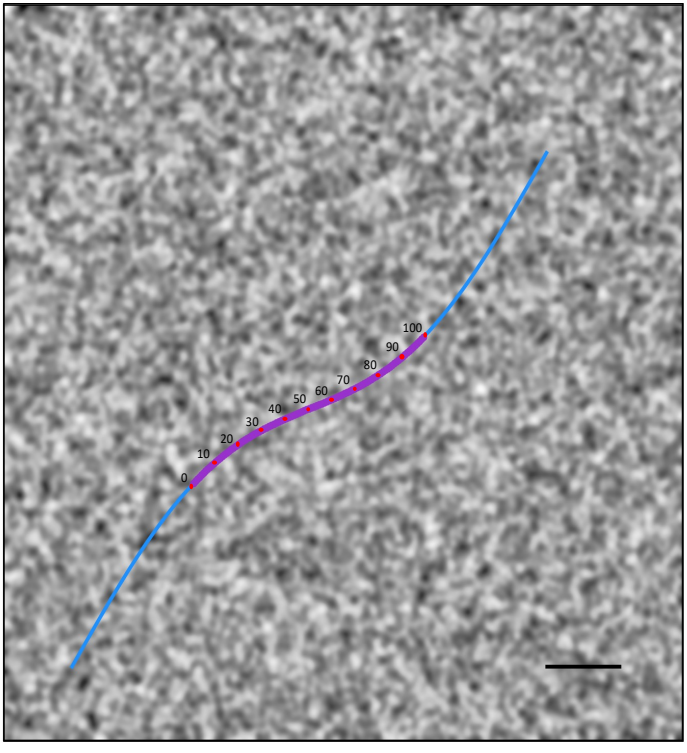


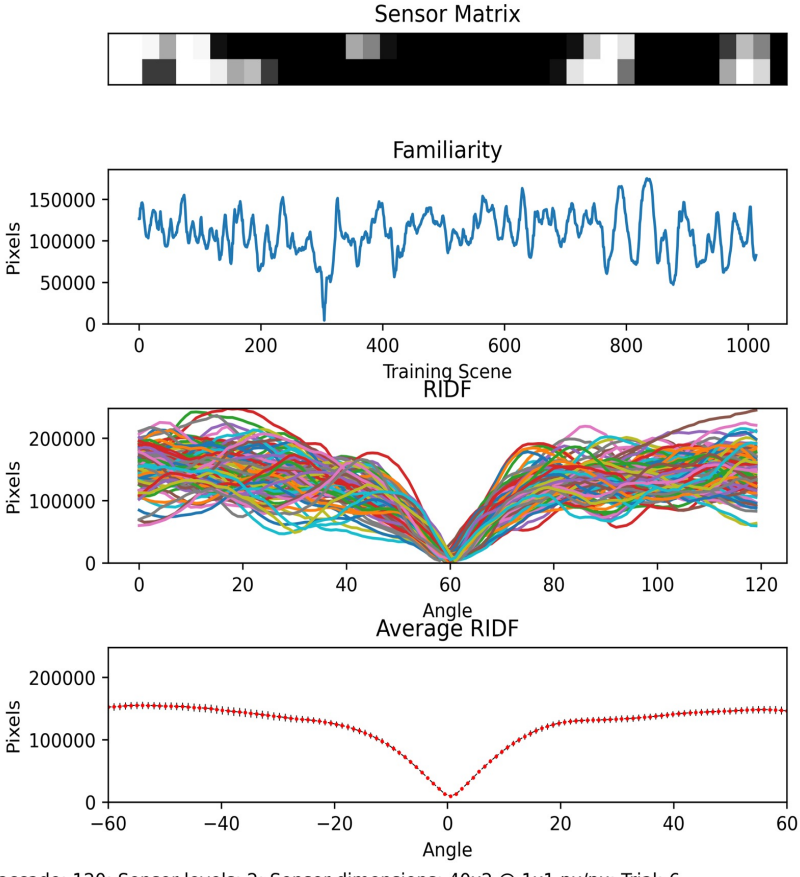


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 213.93; RMSD/dist: 0.535; TD: 77433; p90: 32; p50: 14; complete: 0

100%

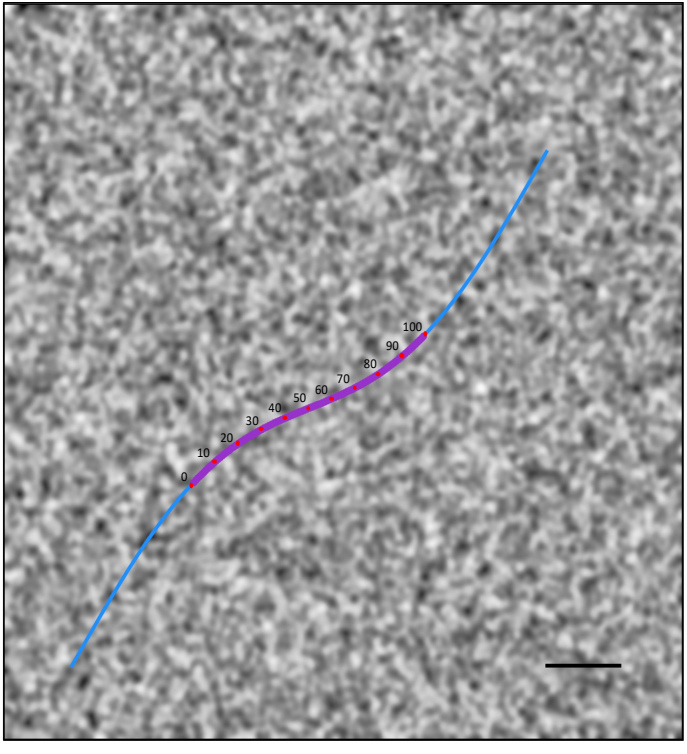


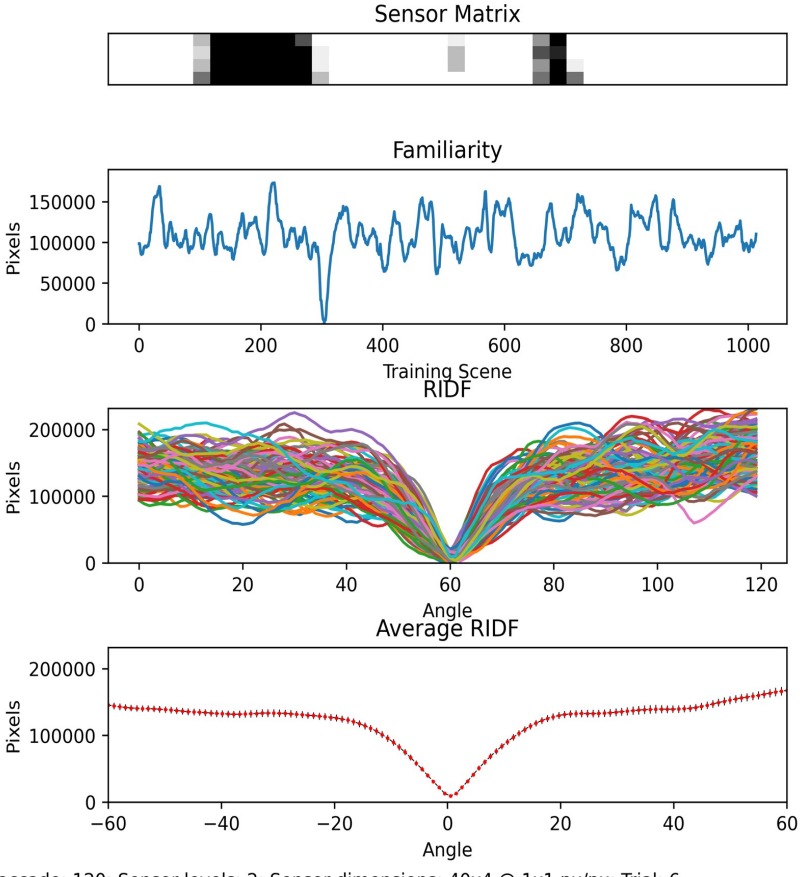


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 45.35; RMSD/dist: 0.113; TD: 98128; p90: 24; p50: 12; complete: 0

100%

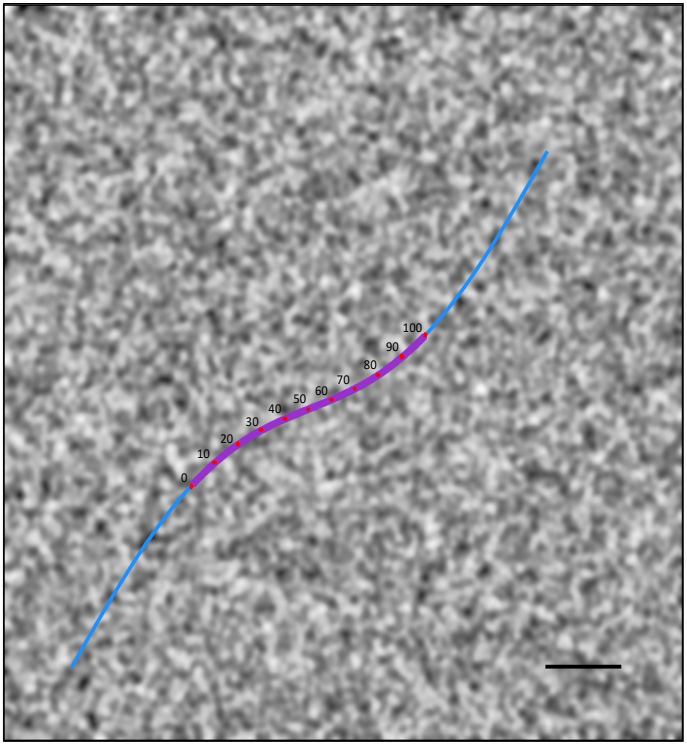


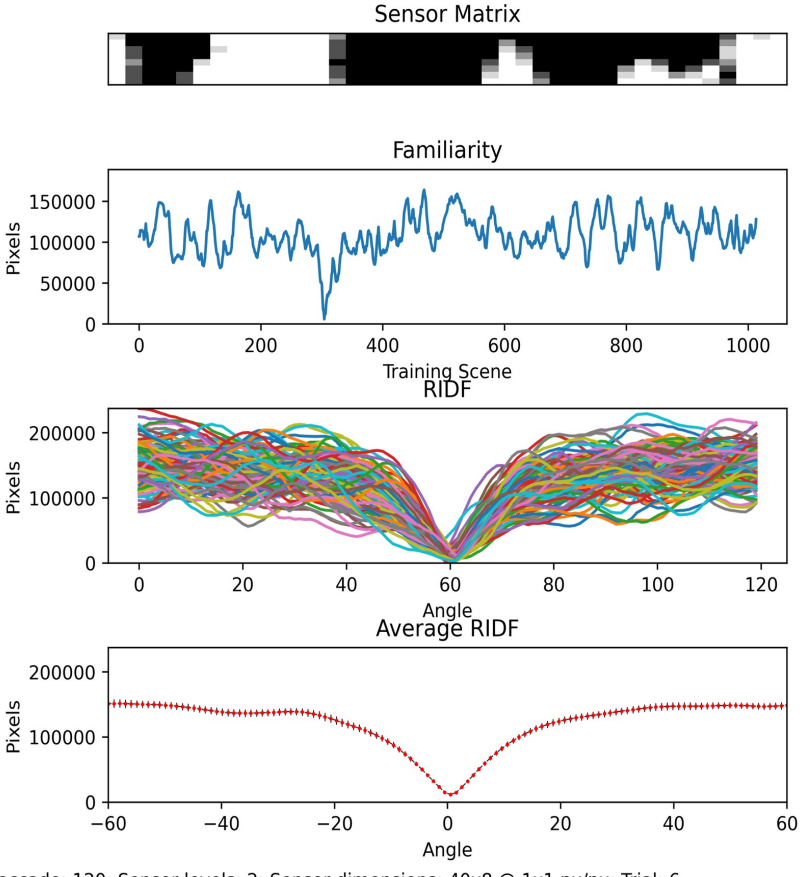


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 39.07; RMSD/dist: 0.098; TD: 99901; p90: 24; p50: 12; complete: 0

100%

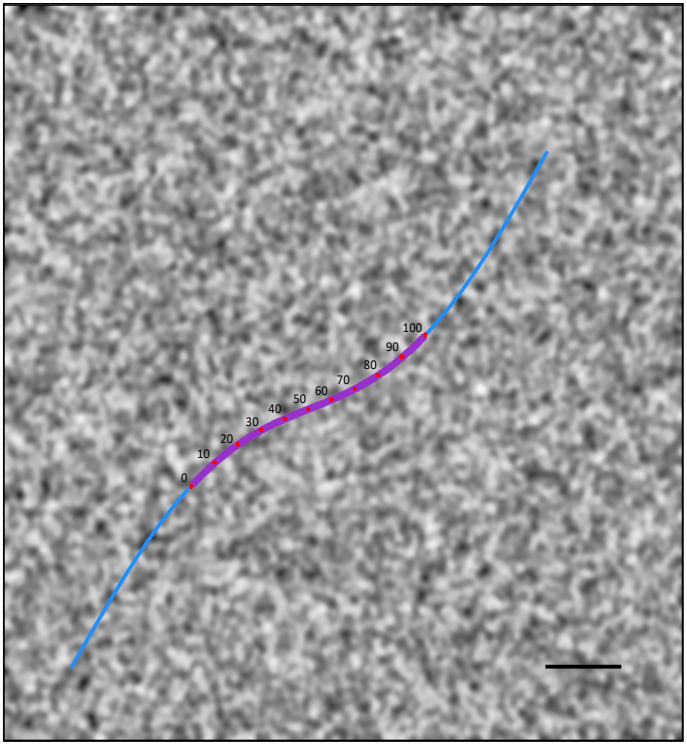


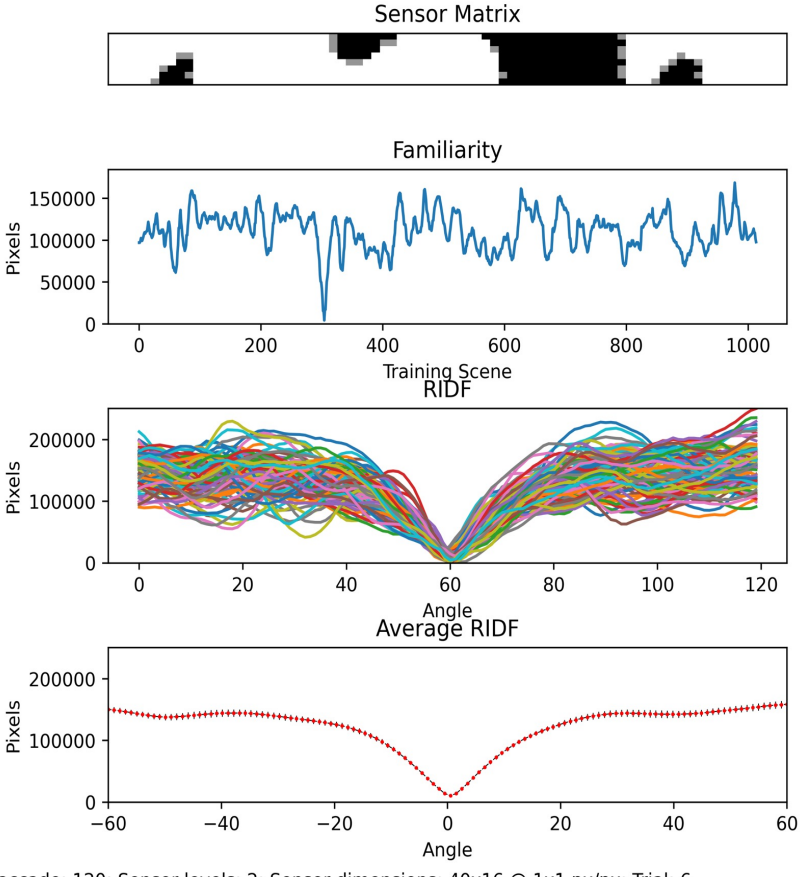


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 53.58; RMSD/dist: 0.134; TD: 100091; p90: 26; p50: 12; complete: 0

100%

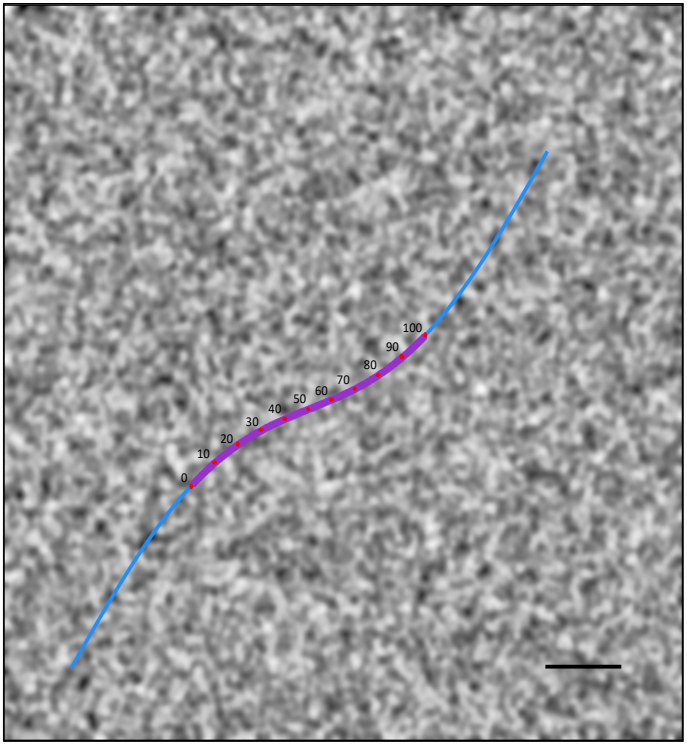


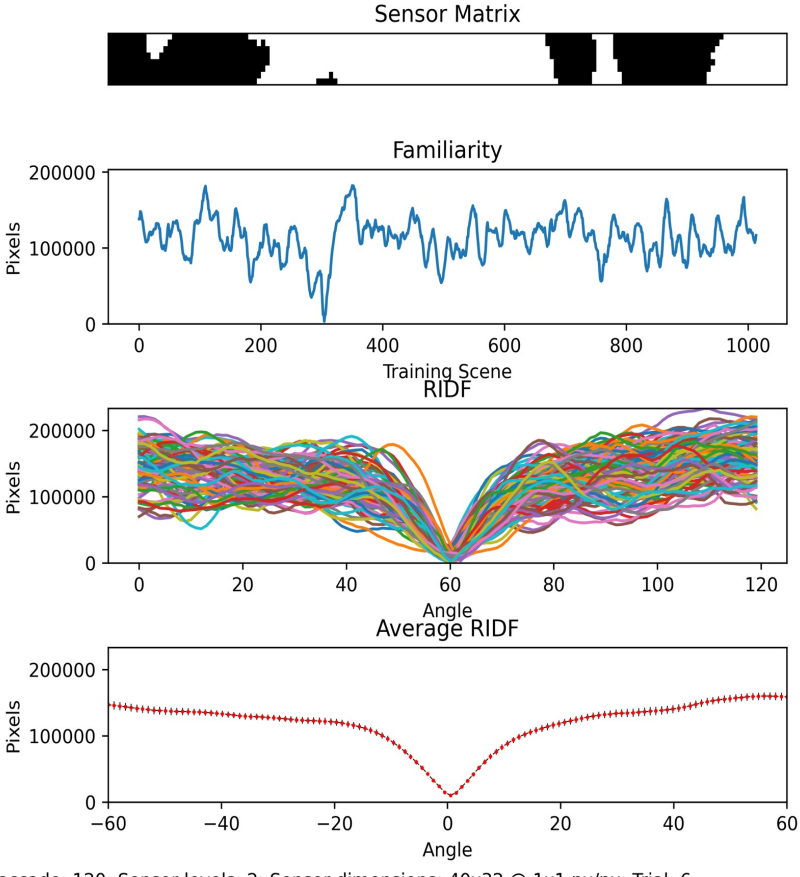


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 50.38; RMSD/dist: 0.126; TD: 100293; p90: 26; p50: 14; complete: 0

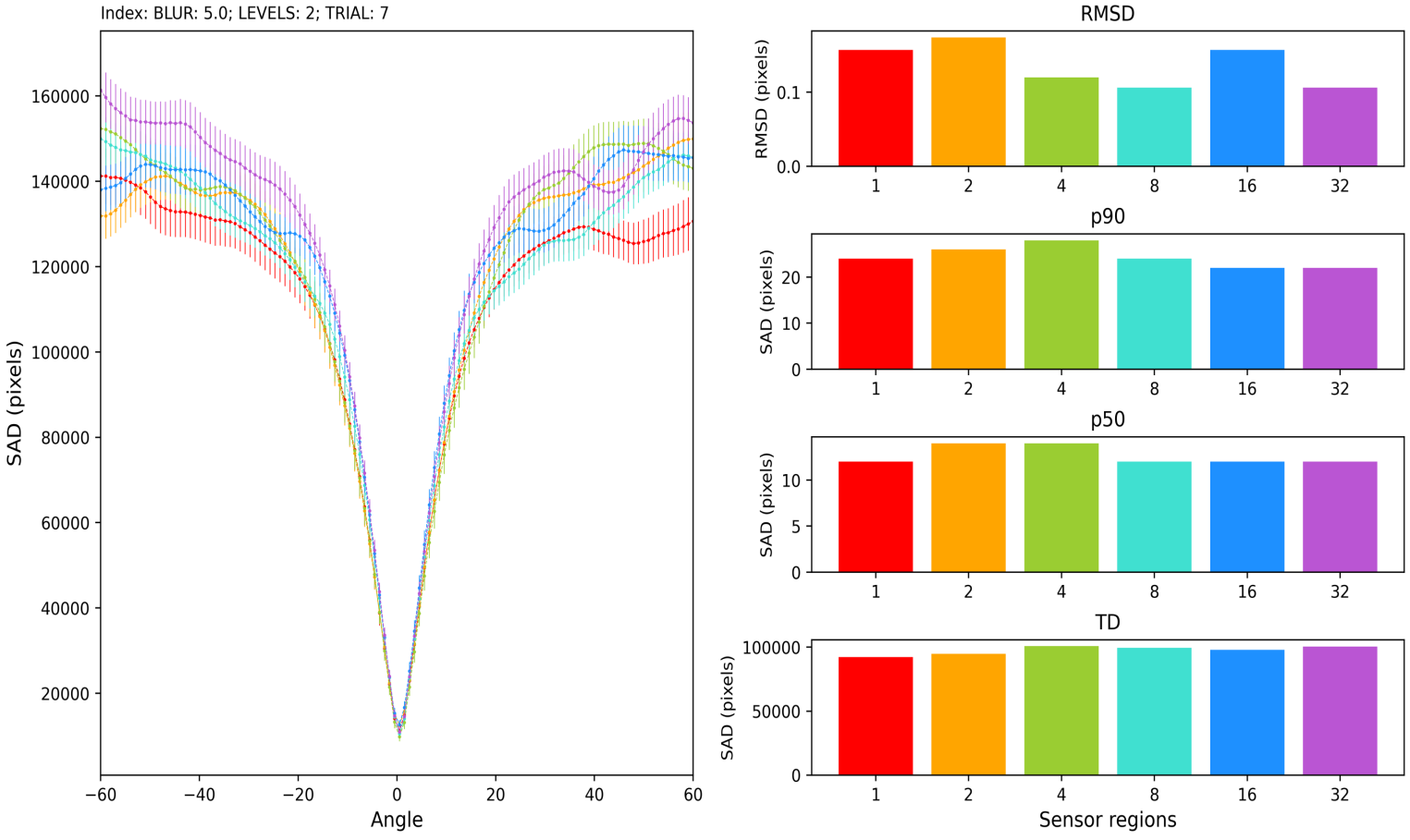
100%



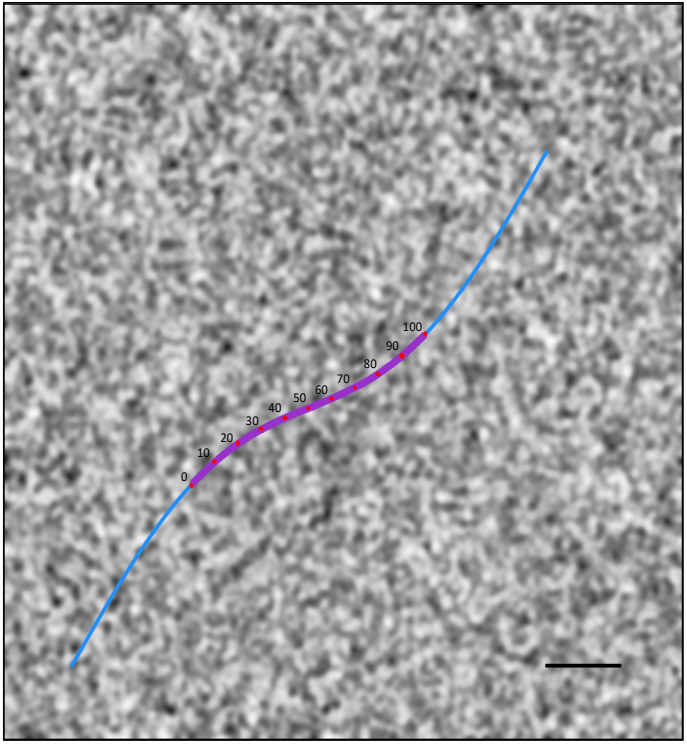


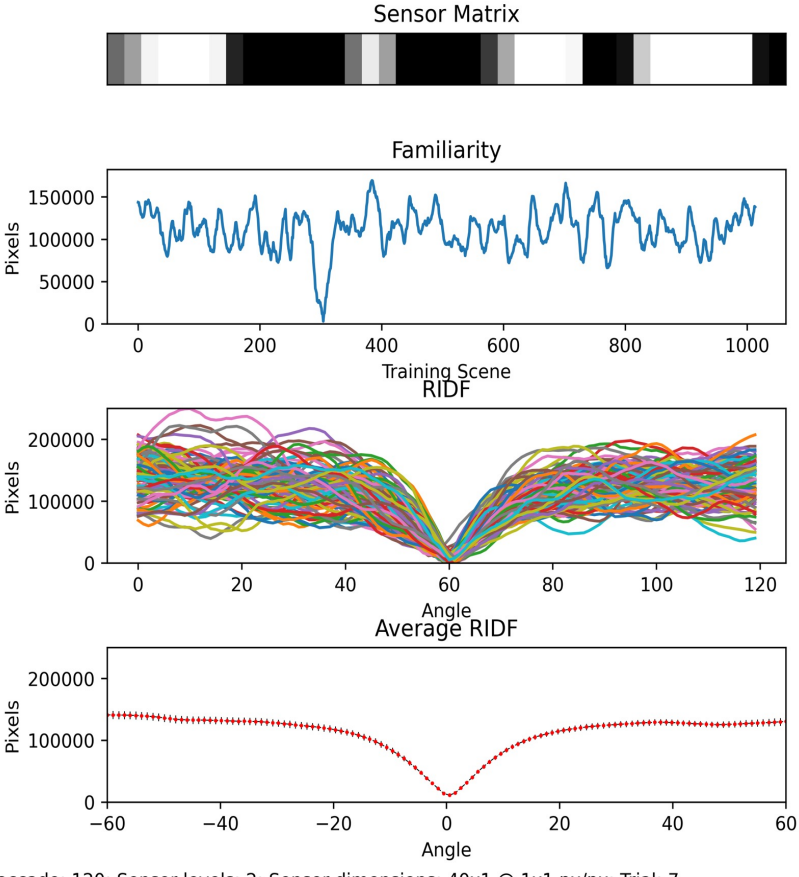
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 39.67; RMSD/dist: 0.099; TD: 101414; p90: 24; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 7
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

100%

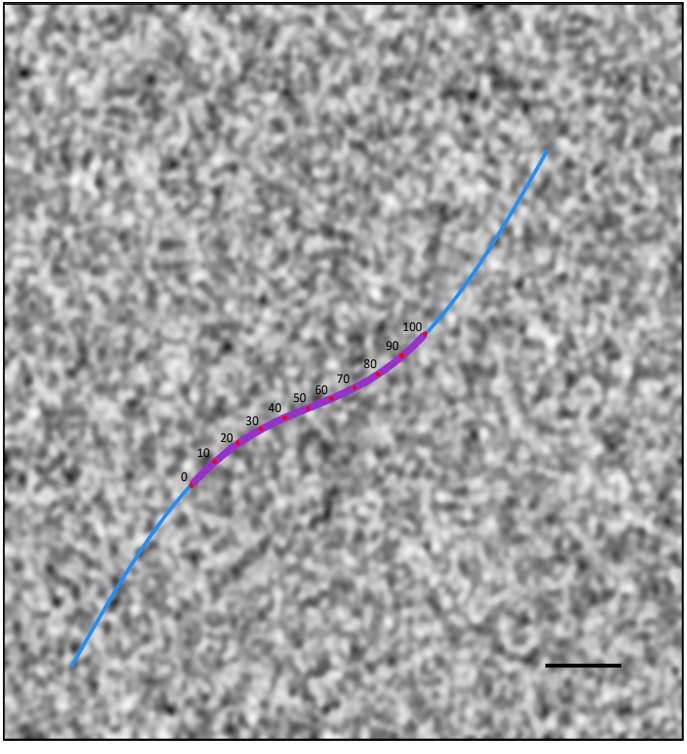


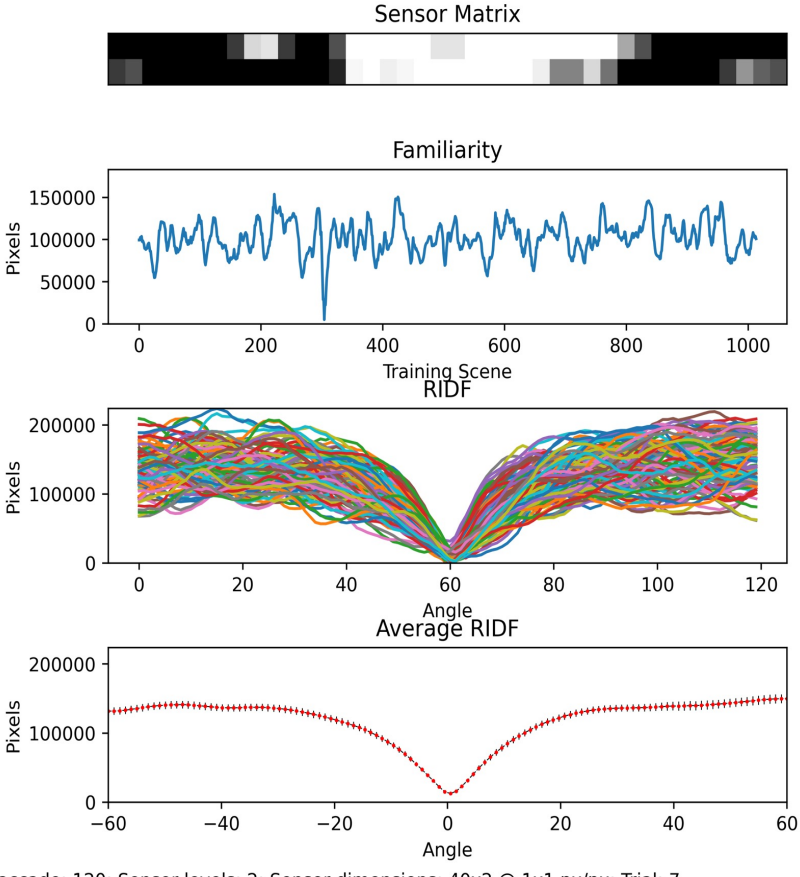


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 62.61; RMSD/dist: 0.157; TD: 92332; p90: 24; p50: 12; complete: 0

100%

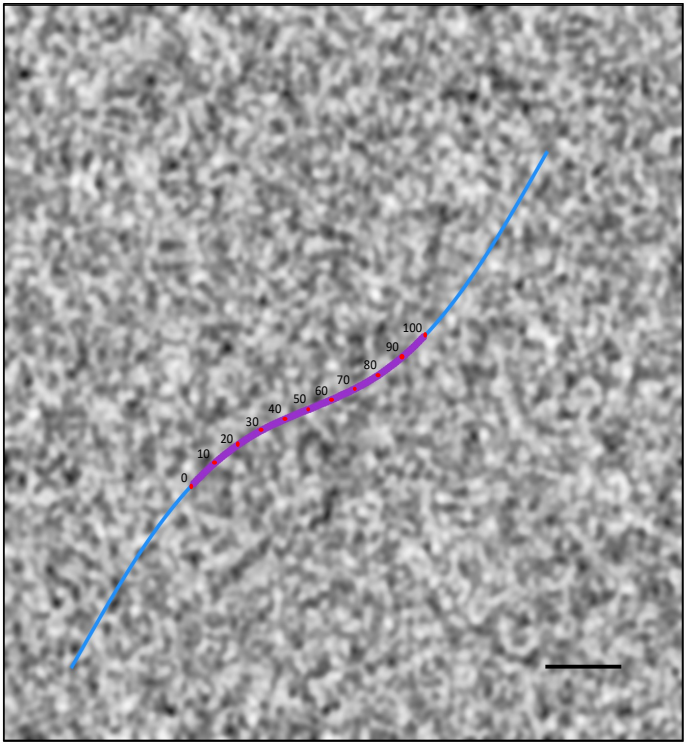


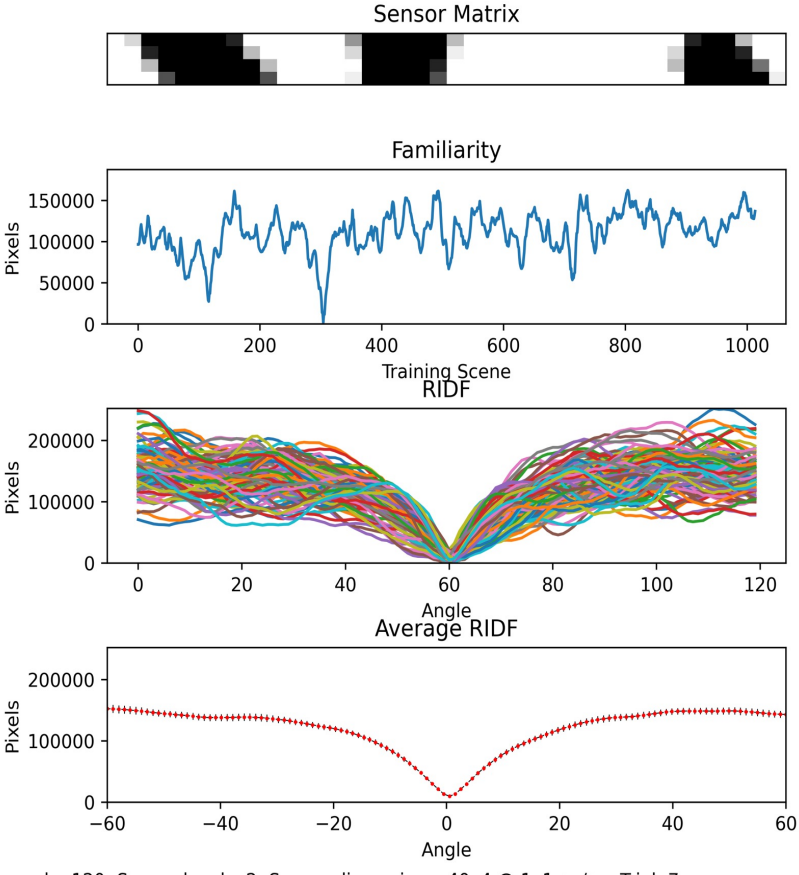


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 69.74; RMSD/dist: 0.174; TD: 94906; p90: 26; p50: 14; complete: 0

100%

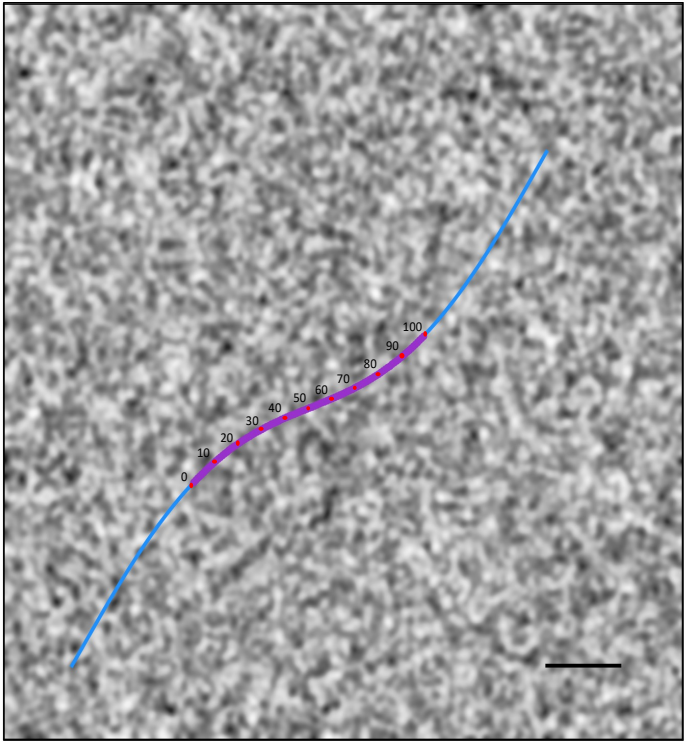


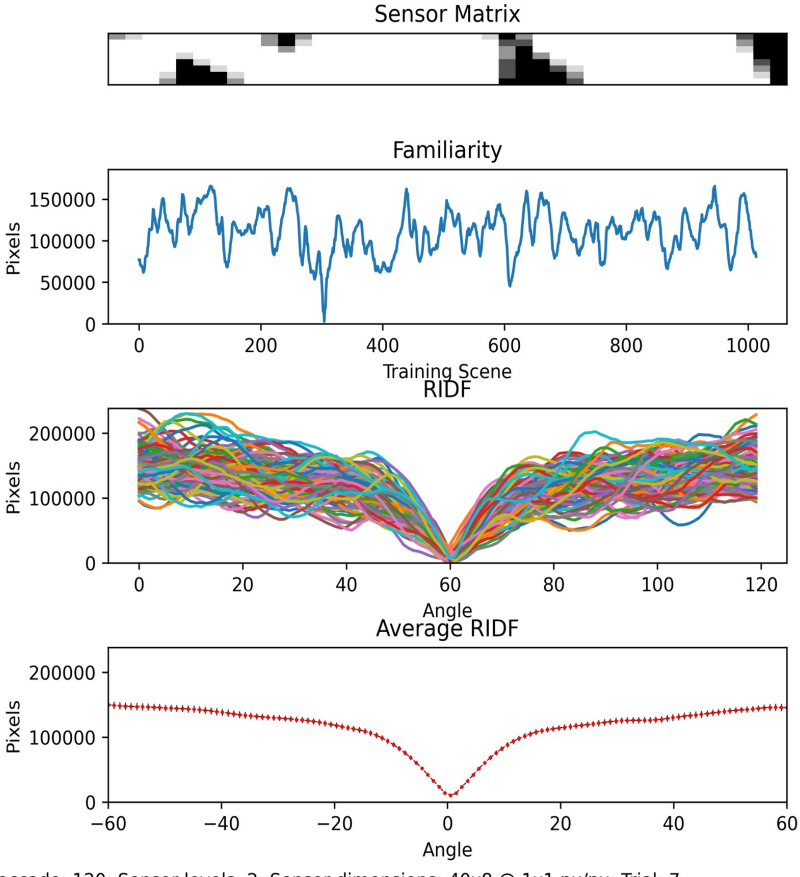


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 47.95; RMSD/dist: 0.120; TD: 100776; p90: 28; p50: 14; complete: 0

100%

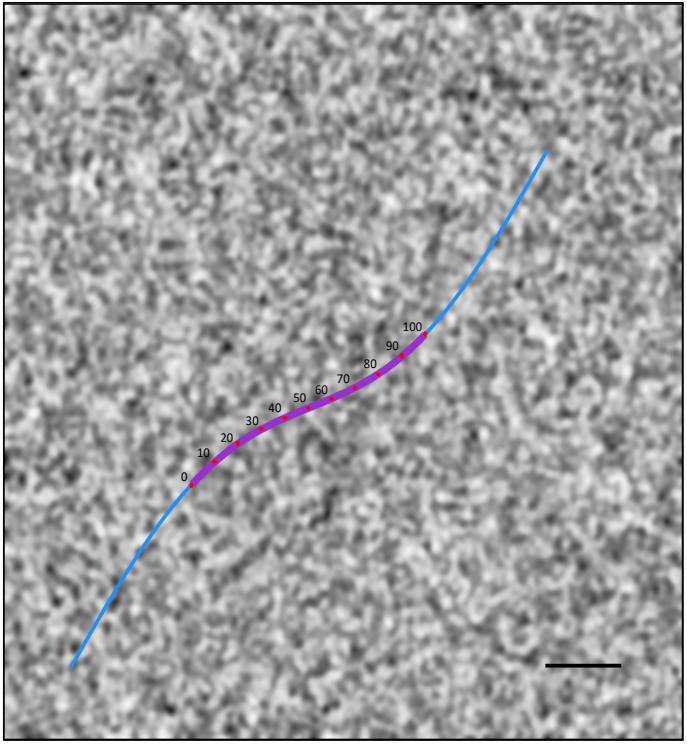


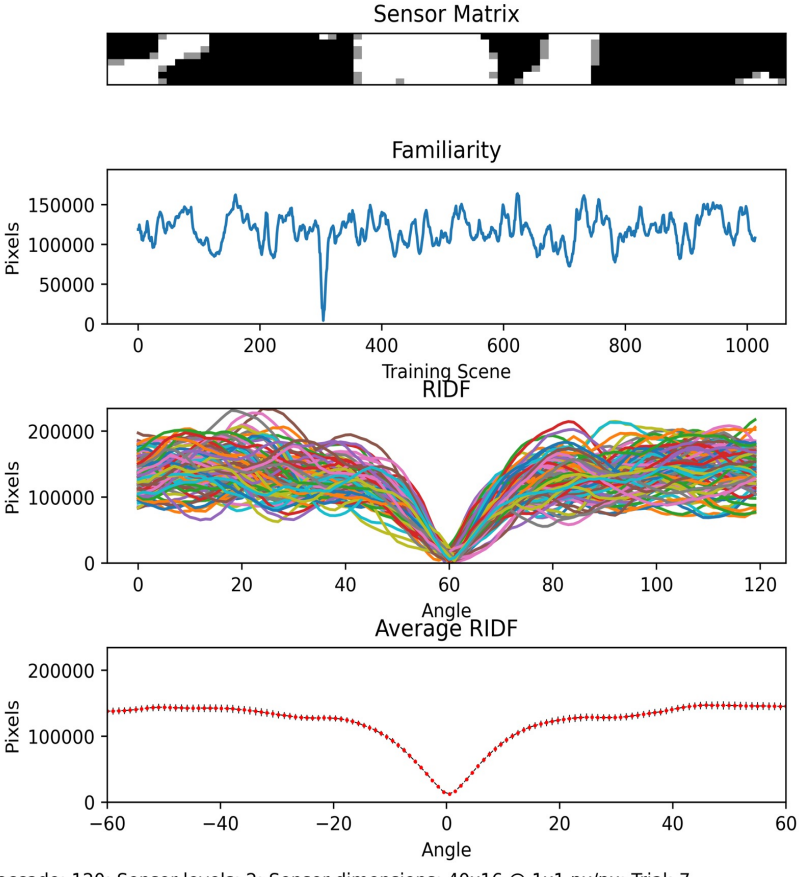


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 42.49; RMSD/dist: 0.106; TD: 99463; p90: 24; p50: 12; complete: 0

100%

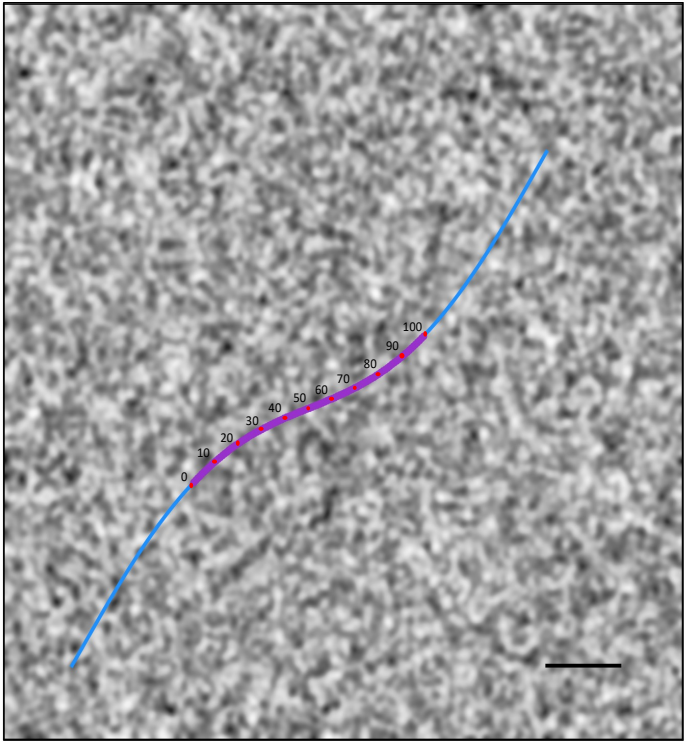


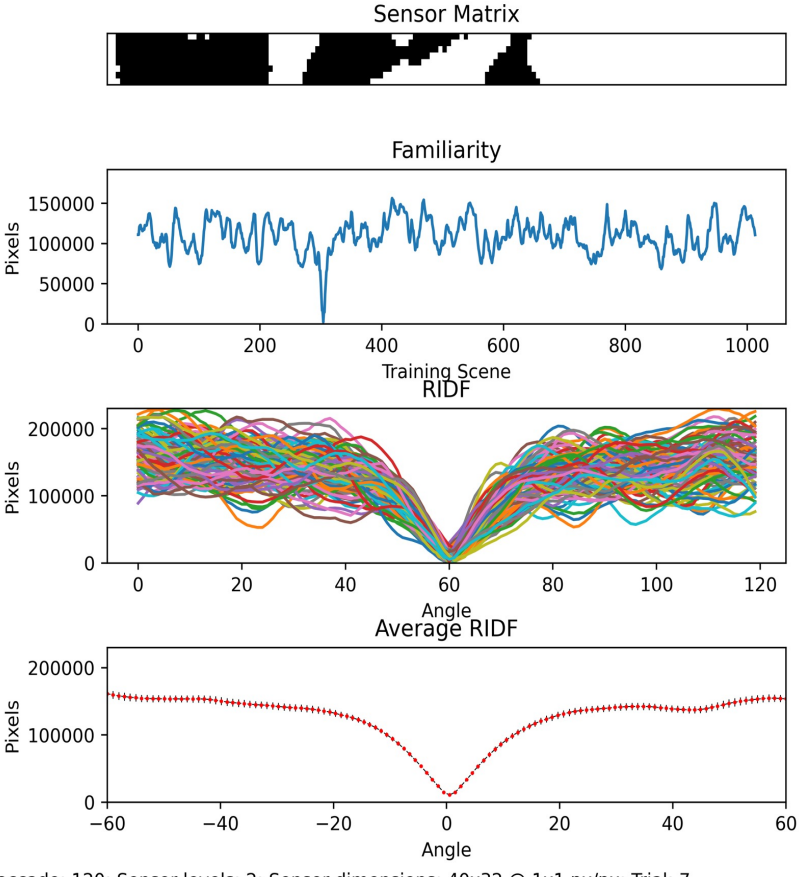


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 62.72; RMSD/dist: 0.157; TD: 97948; p90: 22; p50: 12; complete: 0

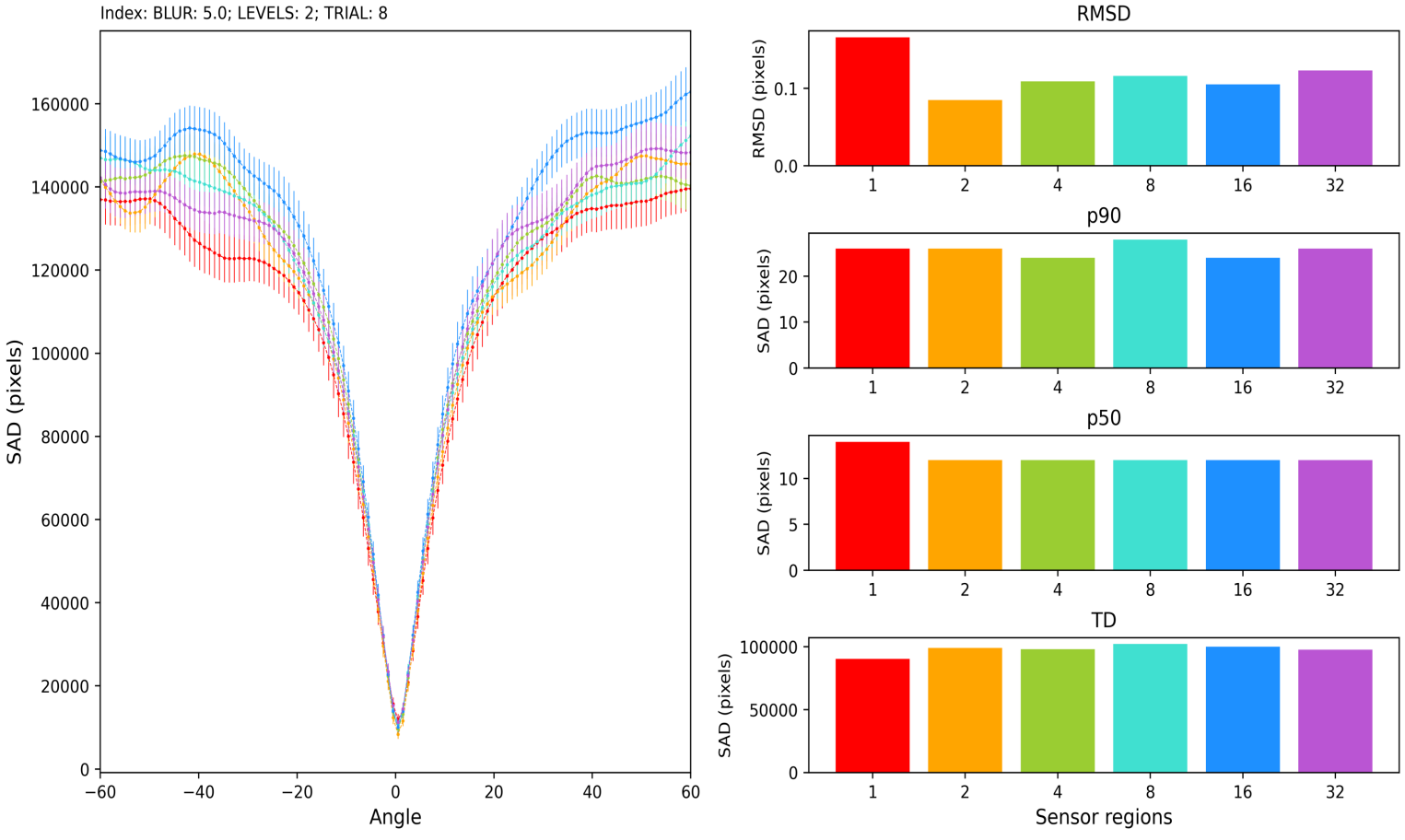
100%



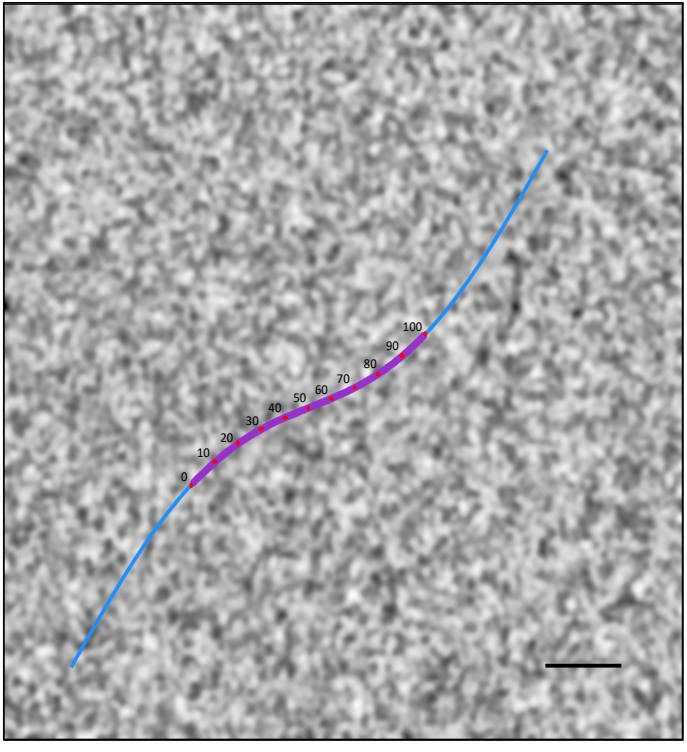


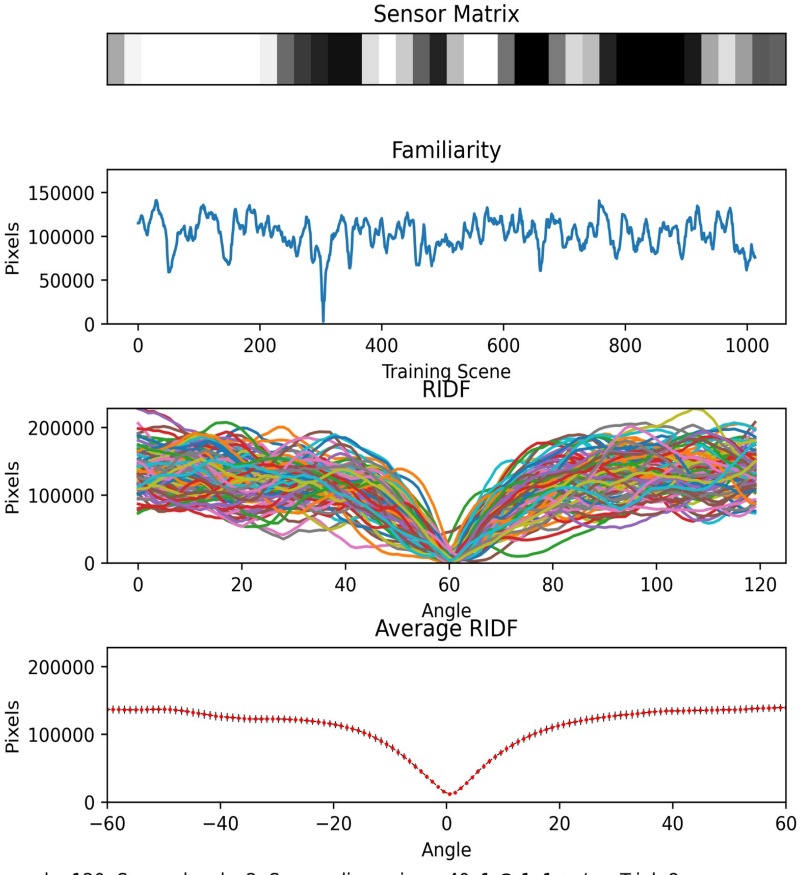
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 42.50; RMSD/dist: 0.106; TD: 100458; p90: 22; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

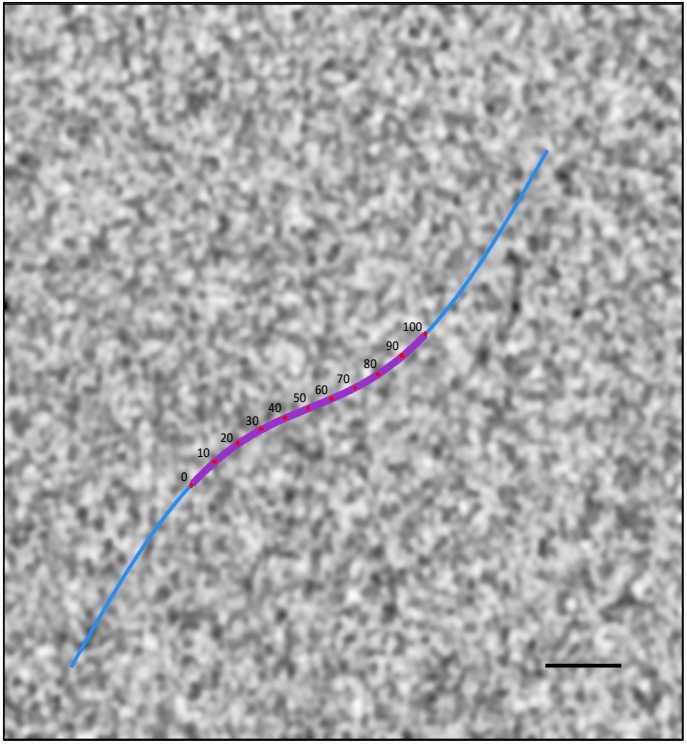


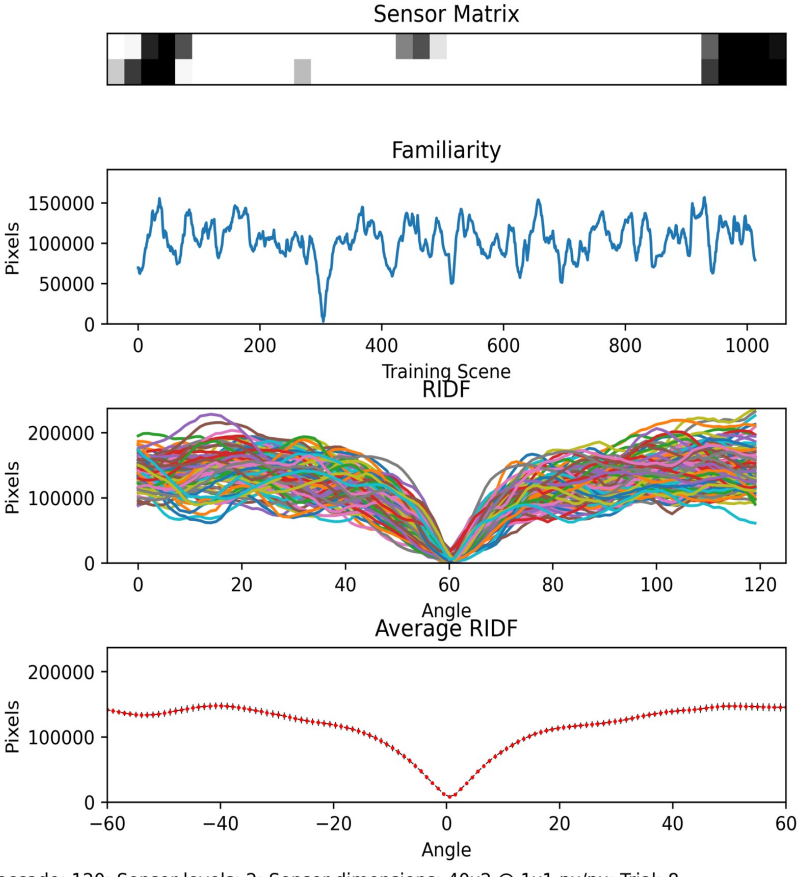


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 66.55; RMSD/dist: 0.166; TD: 90299; p90: 26; p50: 14; complete: 0

100%

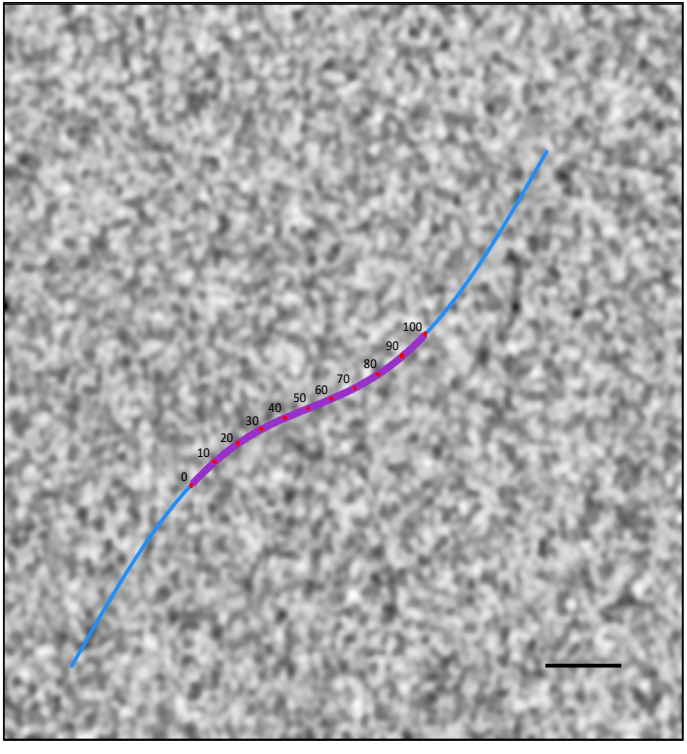


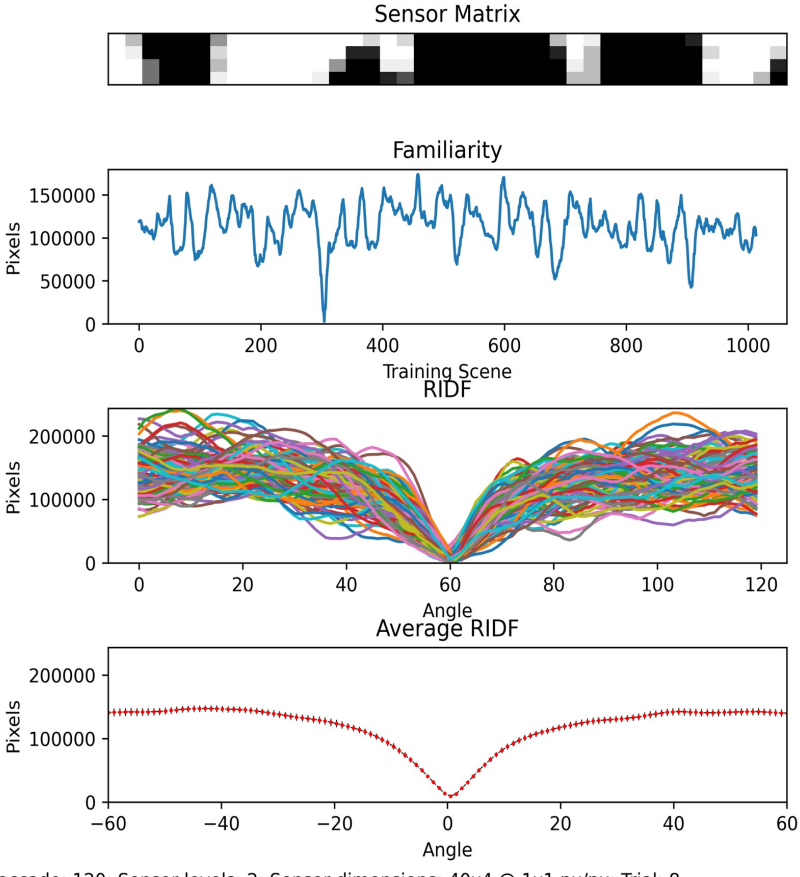


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 33.90; RMSD/dist: 0.085; TD: 99046; p90: 26; p50: 12; complete: 0

100%

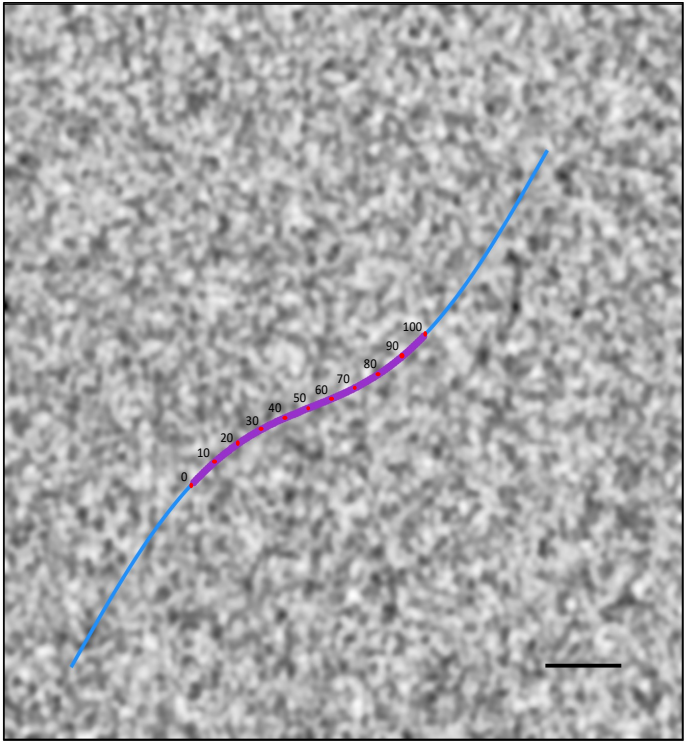


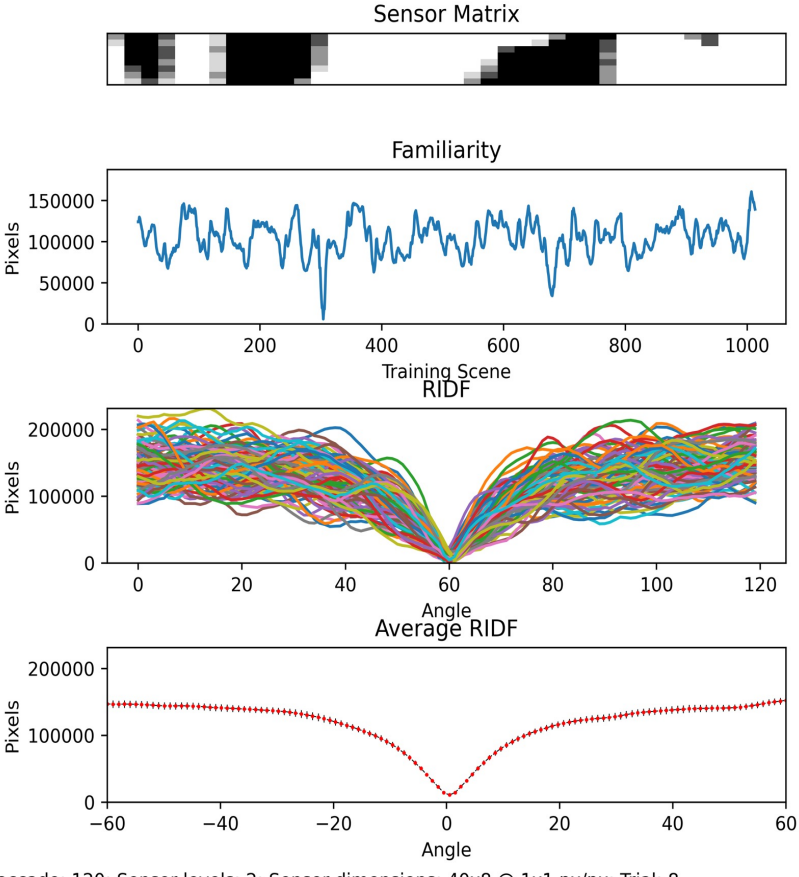


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 43.73; RMSD/dist: 0.109; TD: 98005; p90: 24; p50: 12; complete: 0

100%

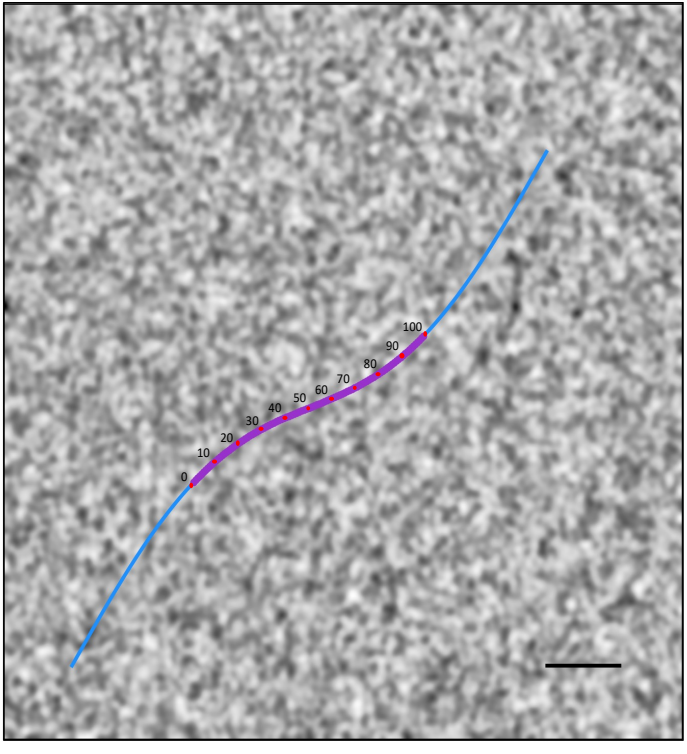


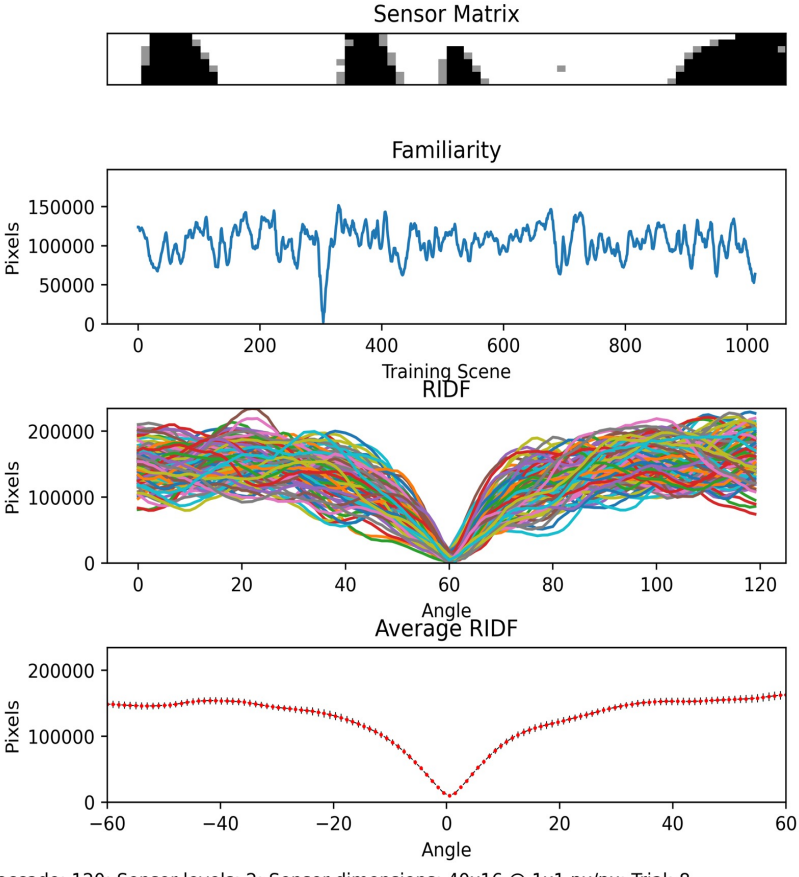


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 46.24; RMSD/dist: 0.116; TD: 102132; p90: 28; p50: 12; complete: 0

100%

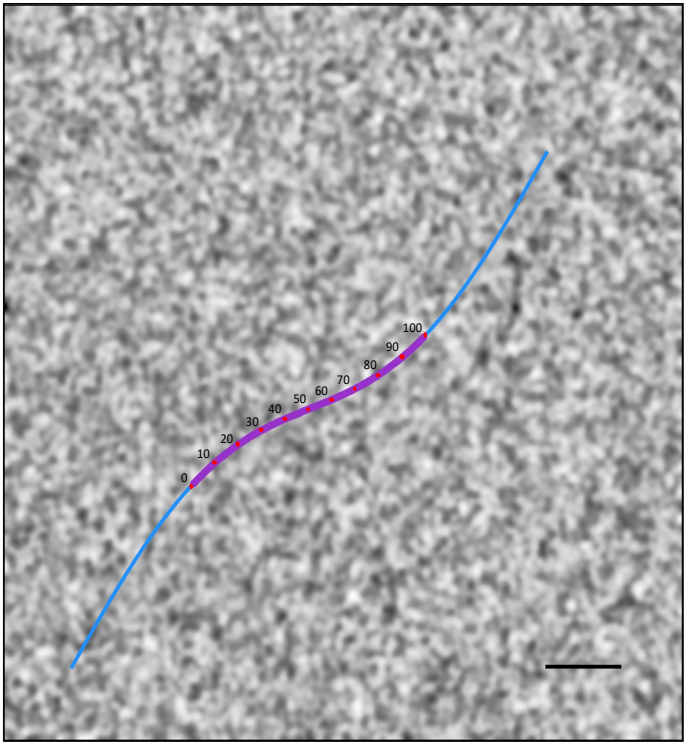


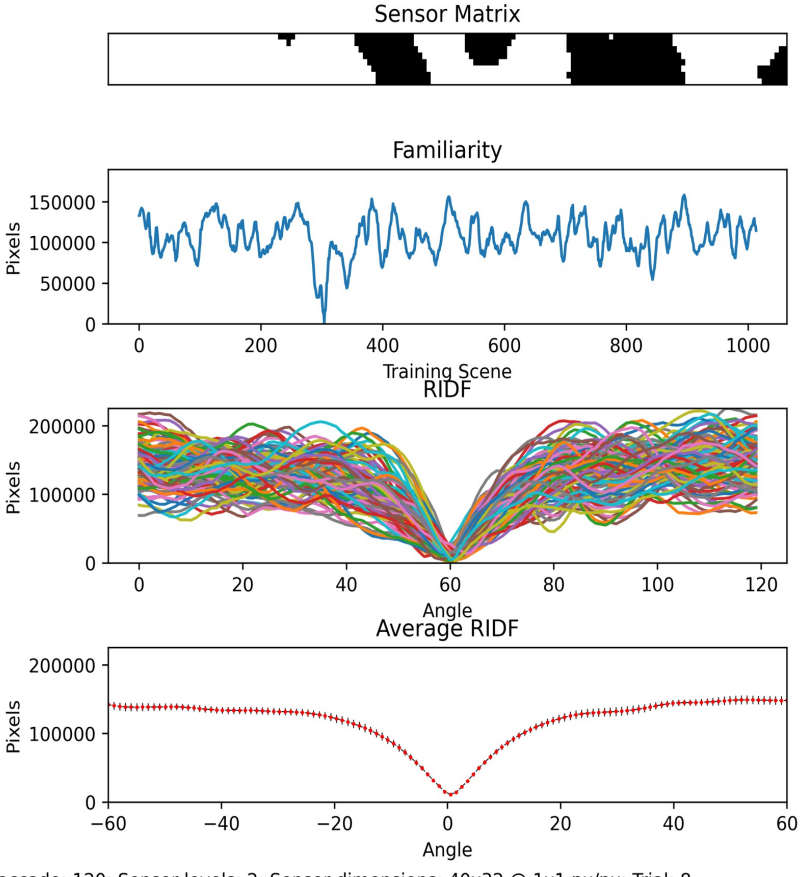


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 42.11; RMSD/dist: 0.105; TD: 100105; p90: 24; p50: 12; complete: 0

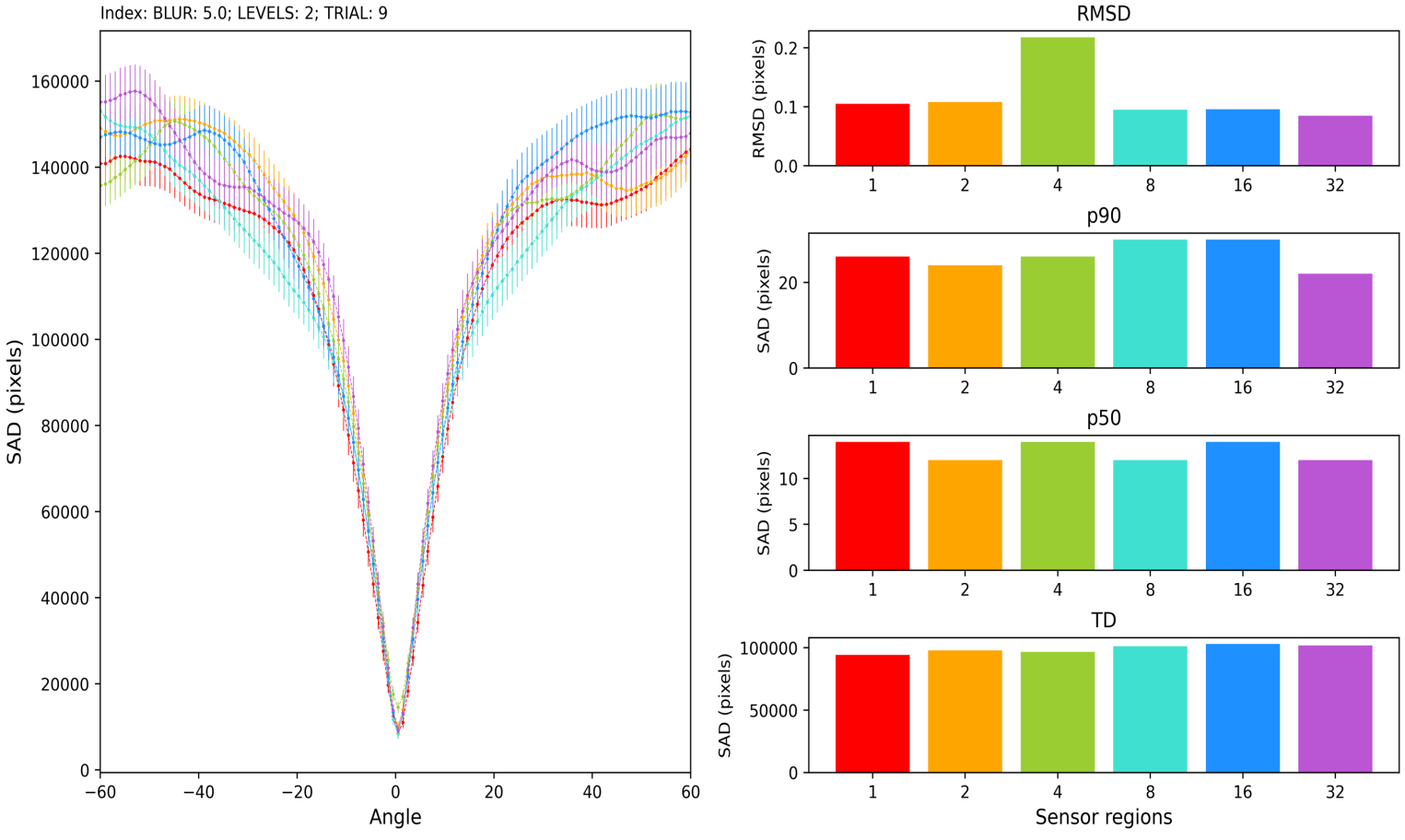
100%



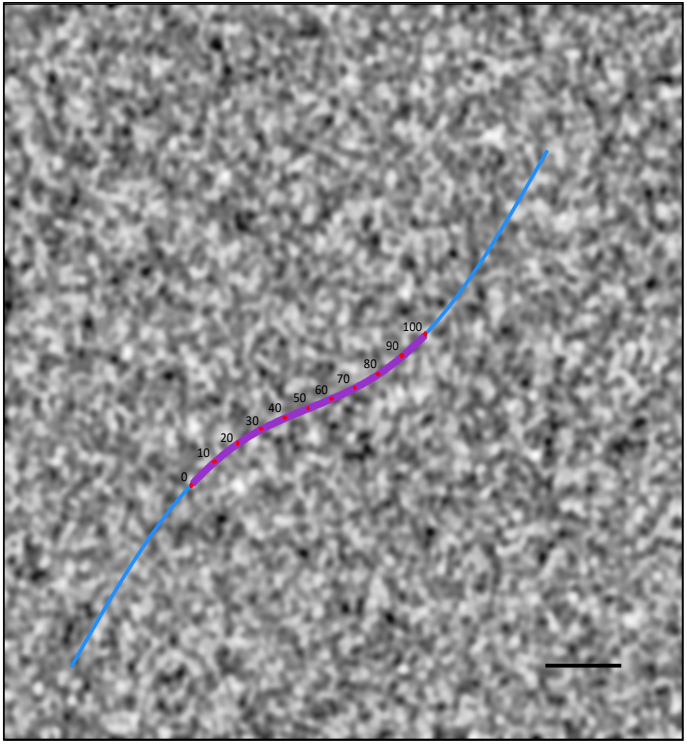


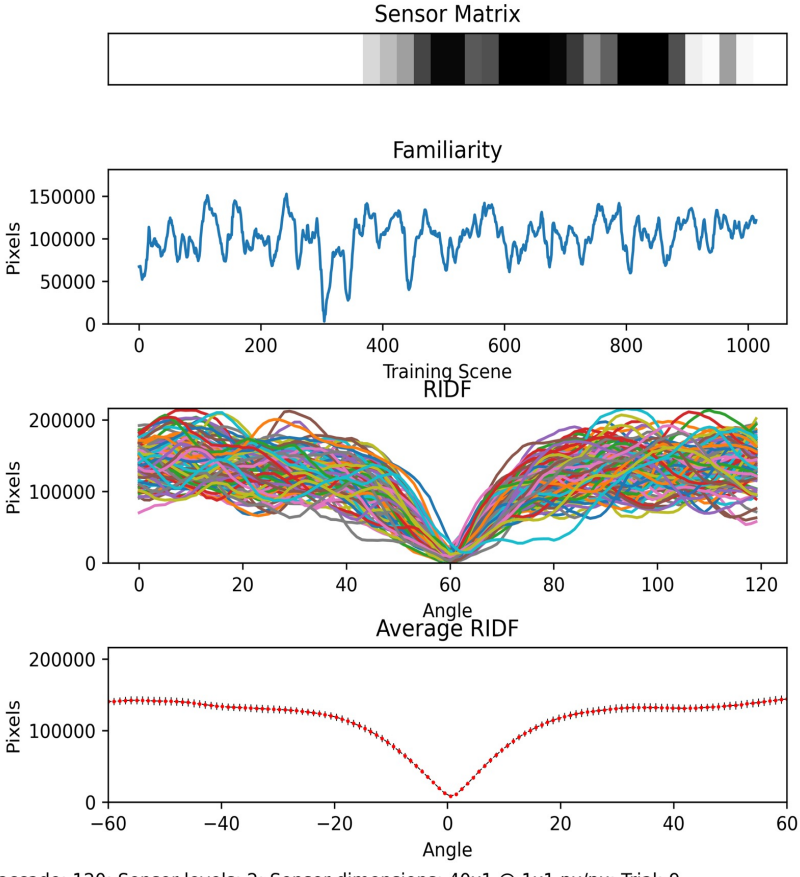
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 49.32; RMSD/dist: 0.123; TD: 97668; p90: 26; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

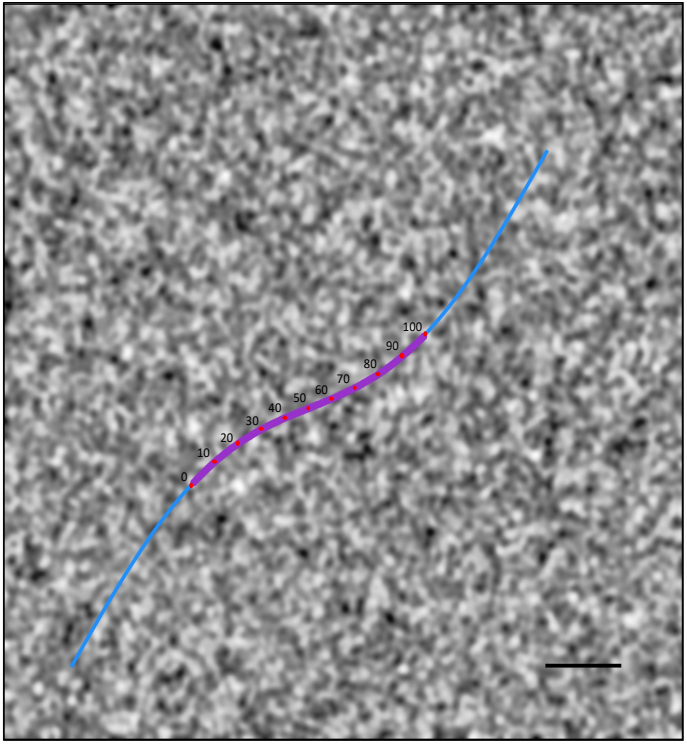


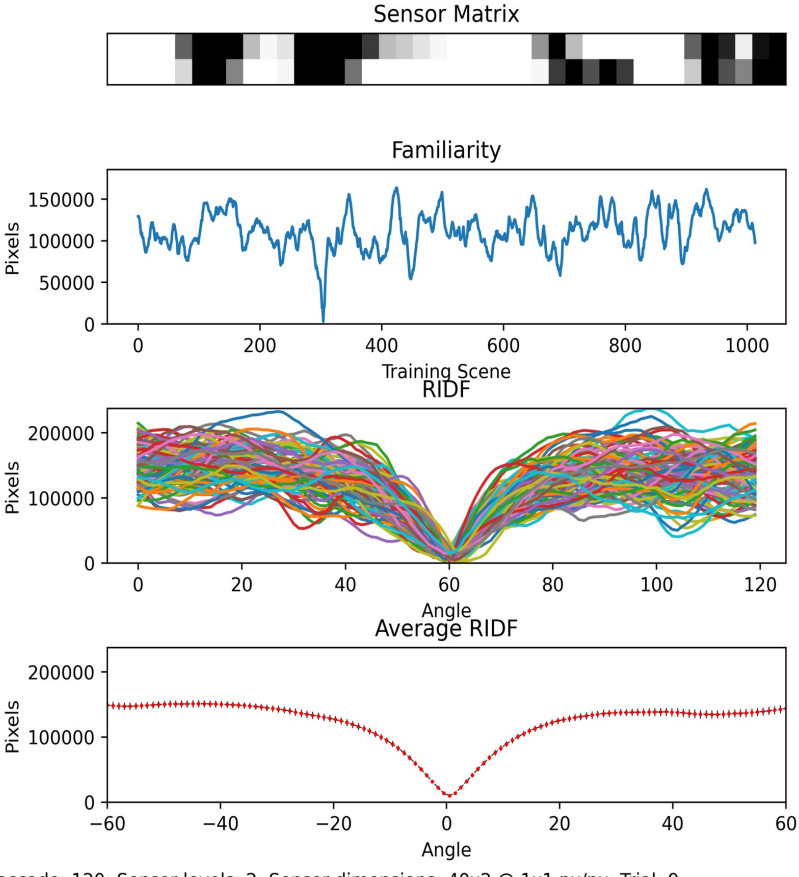


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 41.97; RMSD/dist: 0.105; TD: 94240; p90: 26; p50: 14; complete: 0

100%

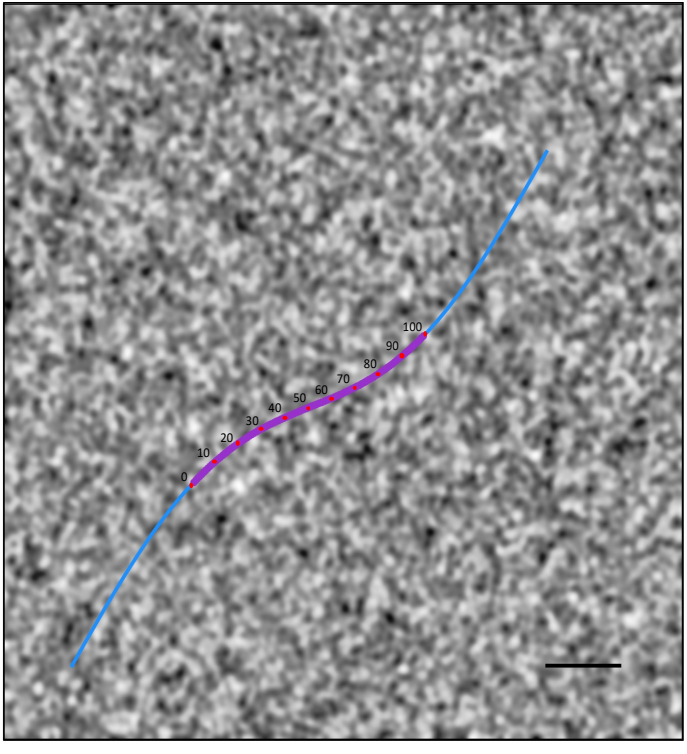


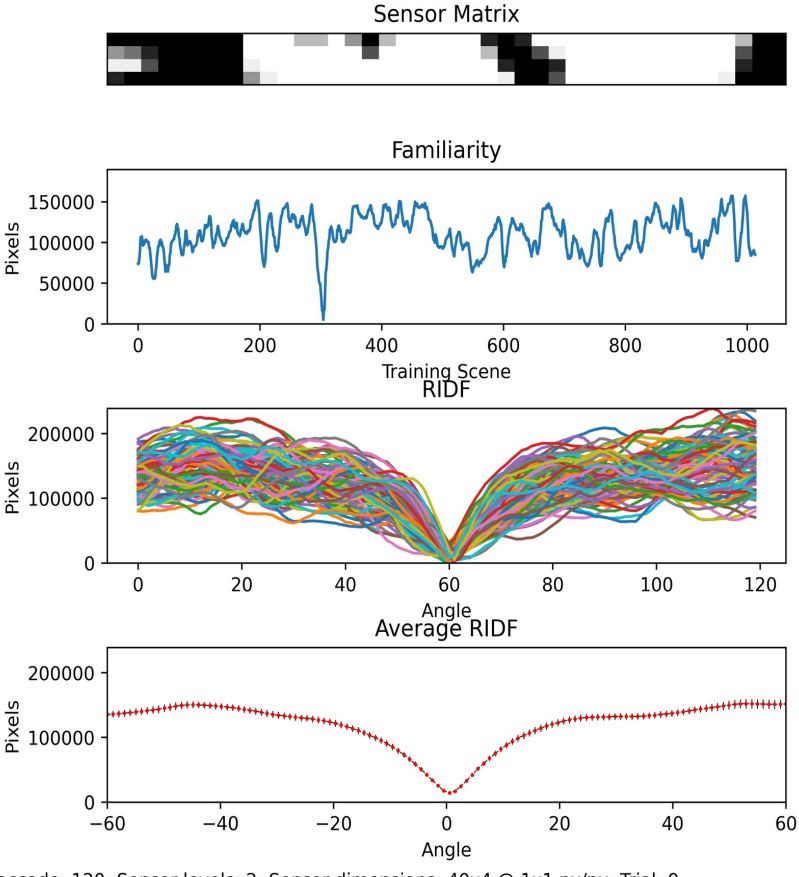


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 43.13; RMSD/dist: 0.108; TD: 97760; p90: 24; p50: 12; complete: 0

100%





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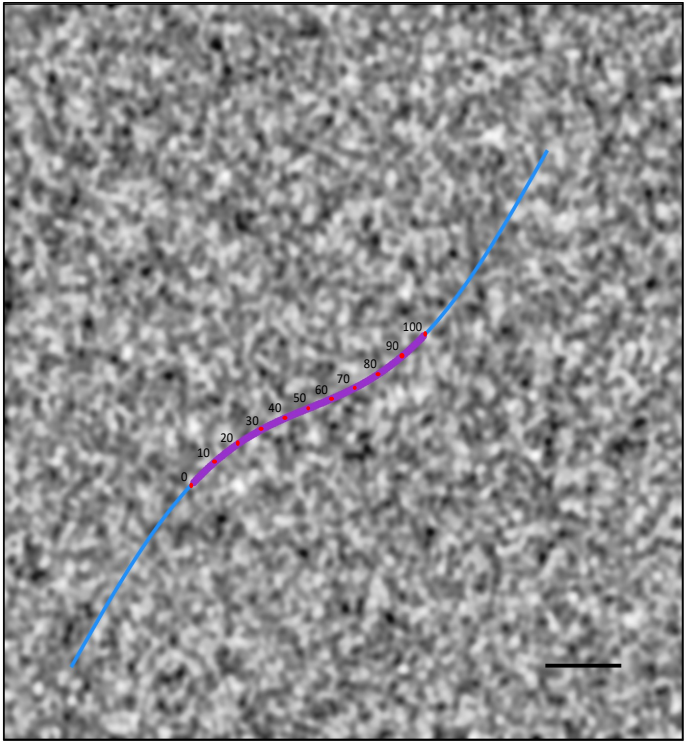
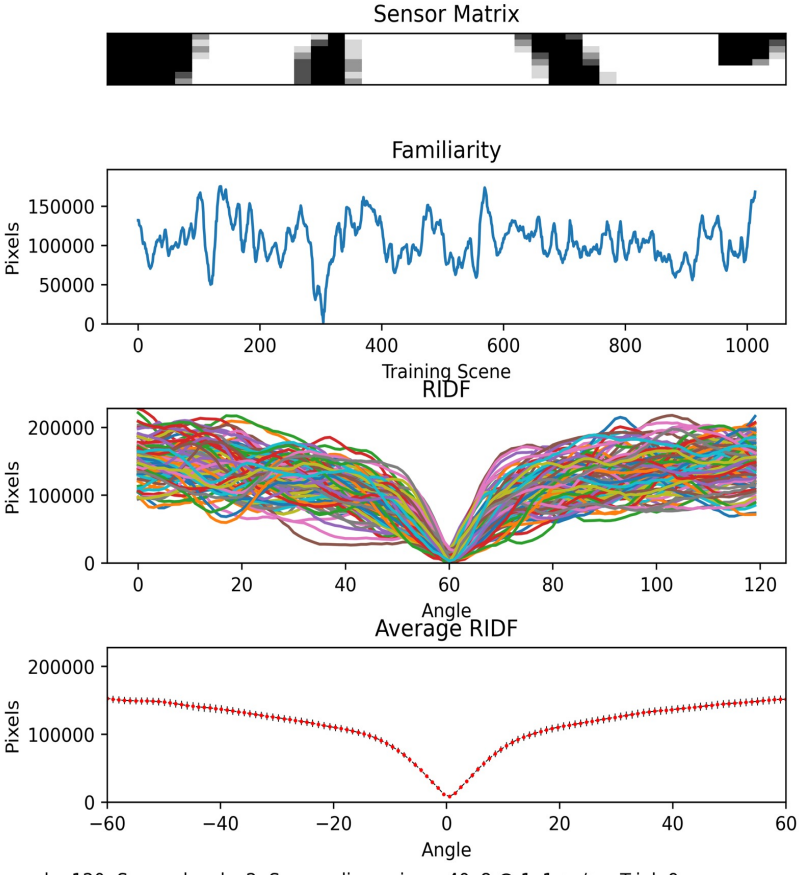
Navigation stats: RMSD error: 87.18; RMSD/dist: 0.218; TD: 96519; p90: 26; p50: 14; complete: 0

100%

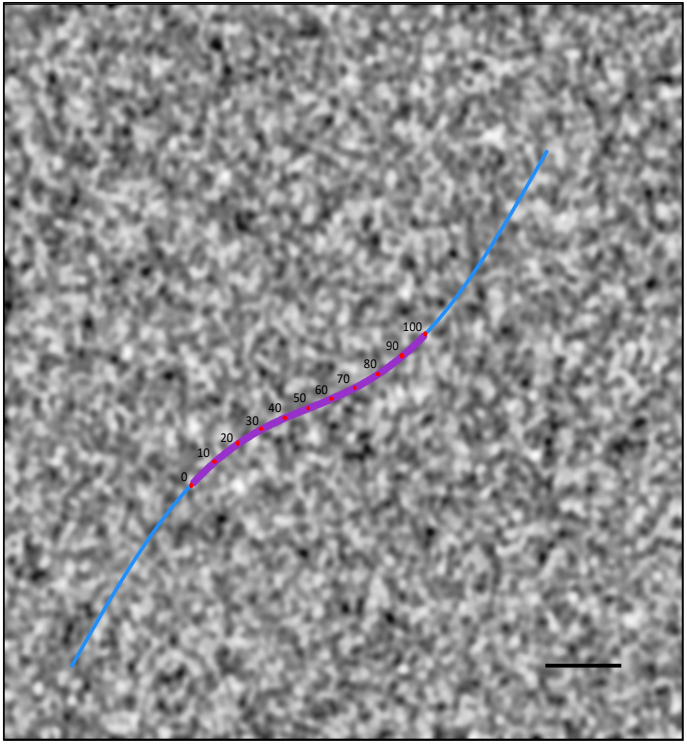


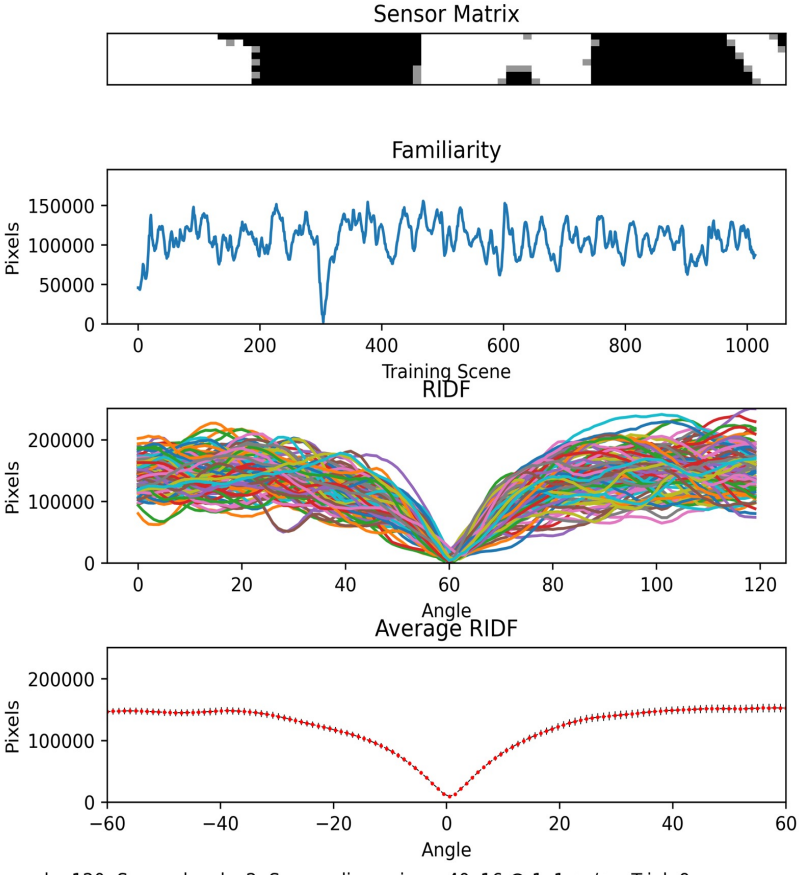


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 38.10; RMSD/dist: 0.095; TD: 101215; p90: 30; p50: 12; complete: 0

100%





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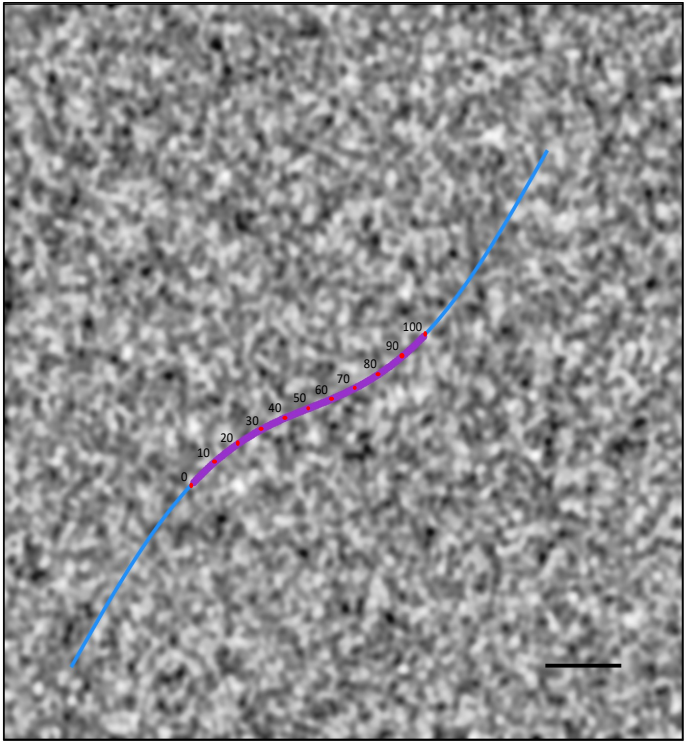
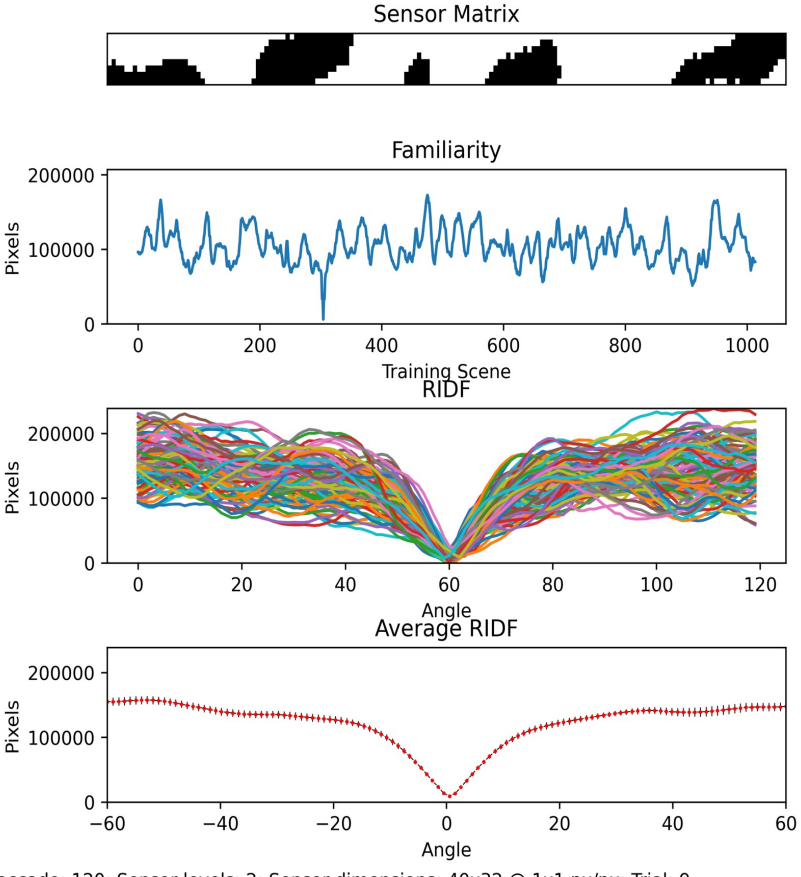
Navigation stats: RMSD error: 38.34; RMSD/dist: 0.096; TD: 102894; p90: 30; p50: 14; complete: 0

100%





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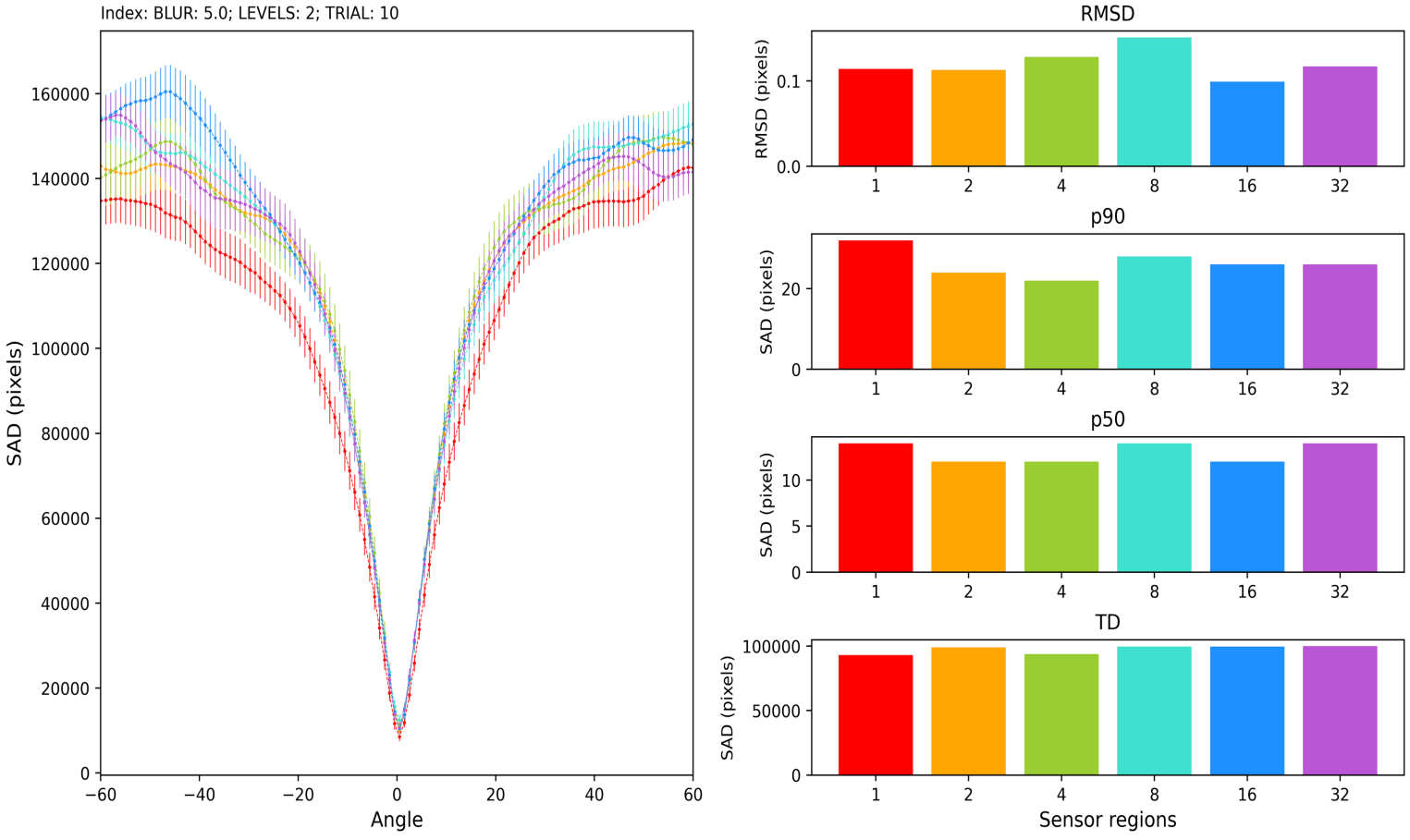
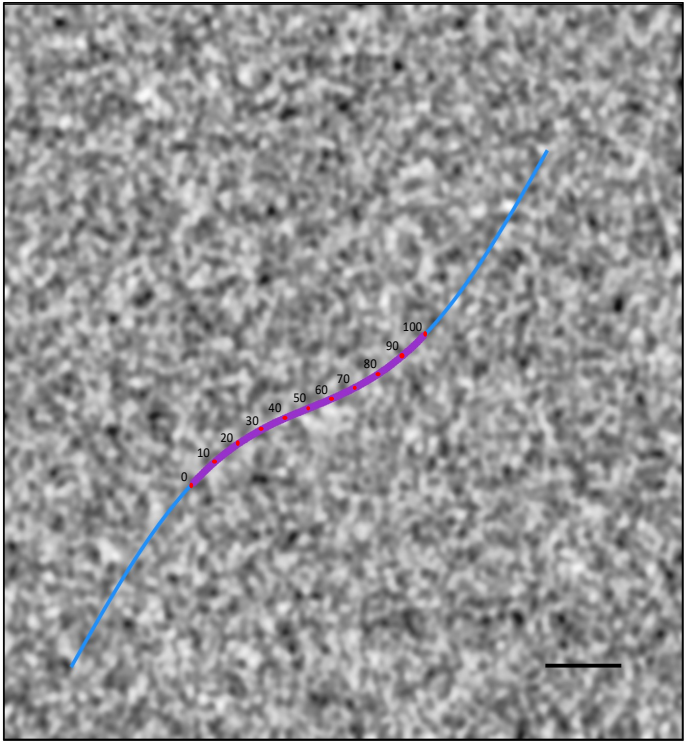
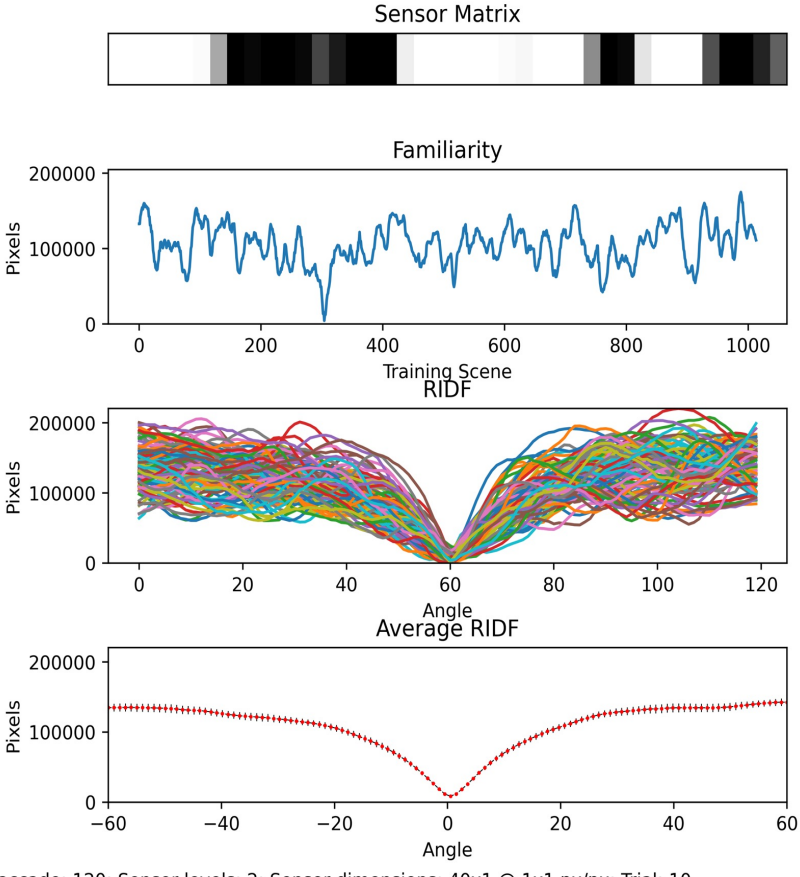
Navigation stats: RMSD error: 33.90; RMSD/dist: 0.085; TD: 101799; p90: 22; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 2; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

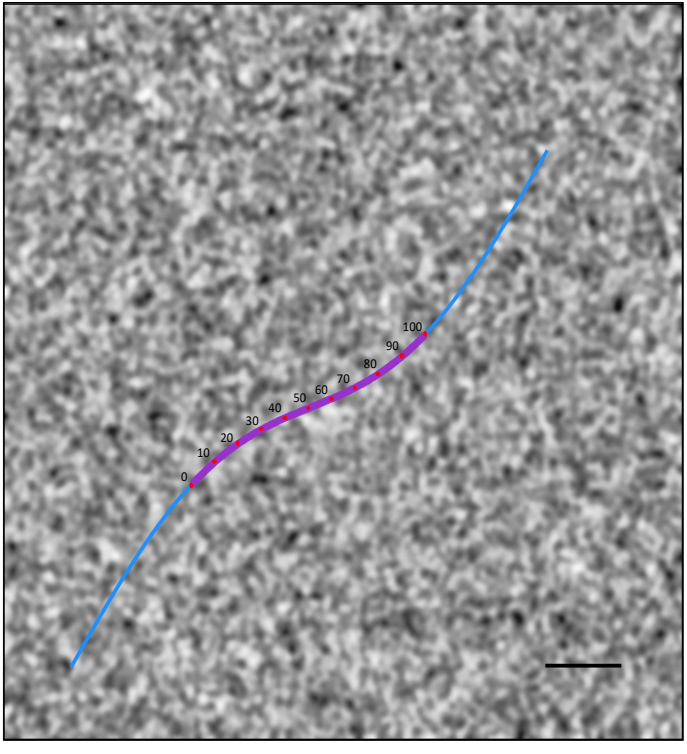


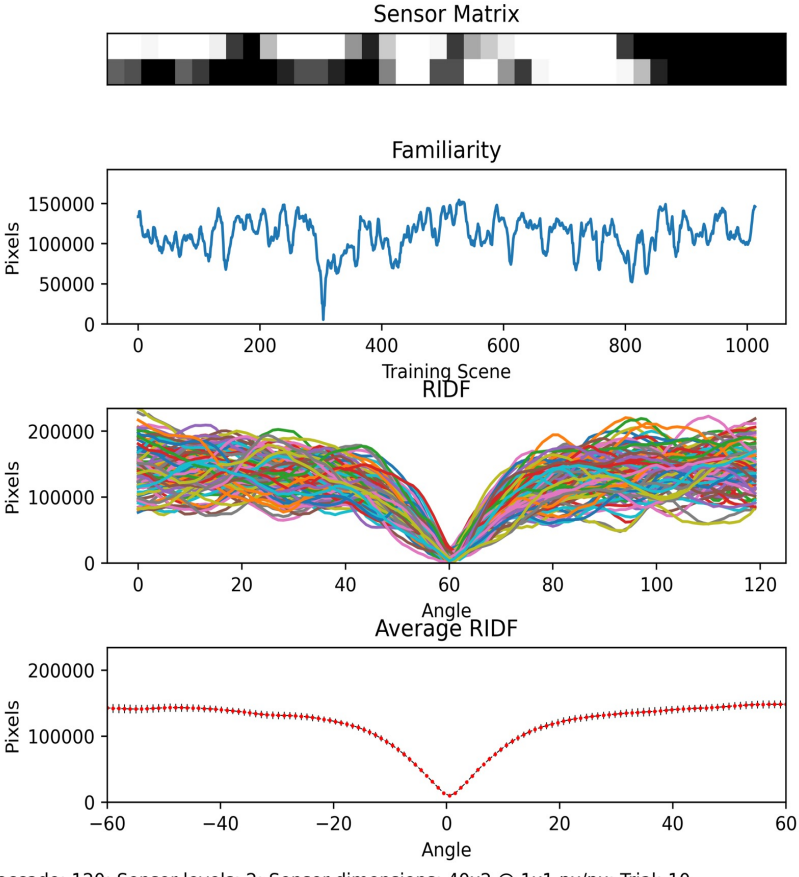


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 45.62; RMSD/dist: 0.114; TD: 93056; p90: 32; p50: 14; complete: 0

100%

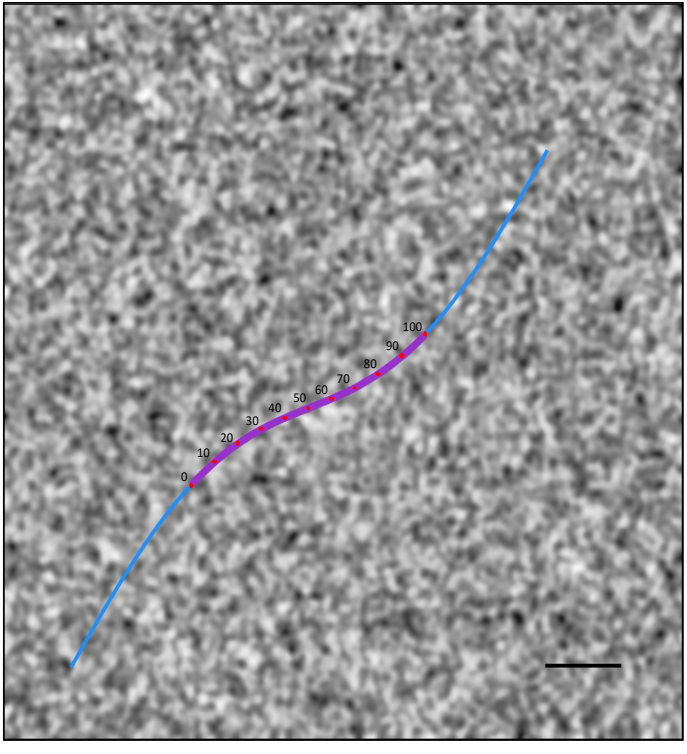


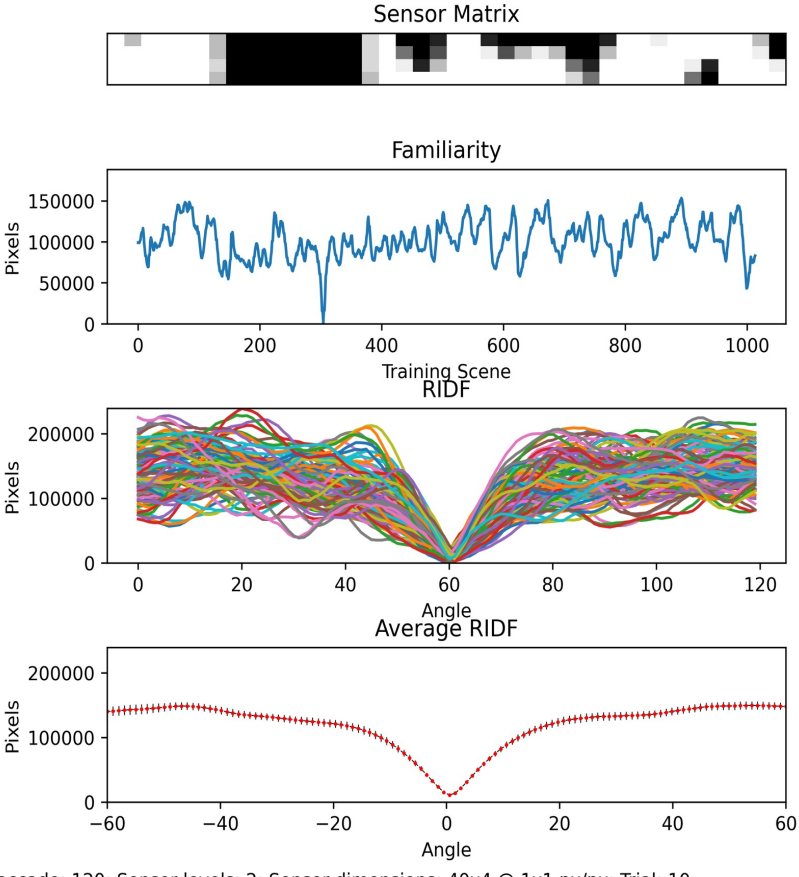


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 45.20; RMSD/dist: 0.113; TD: 99042; p90: 24; p50: 12; complete: 0

100%

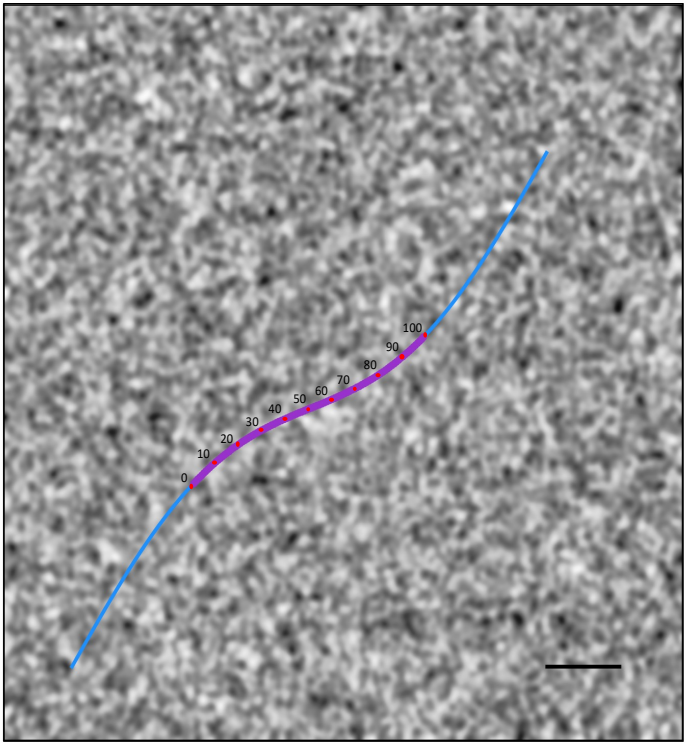


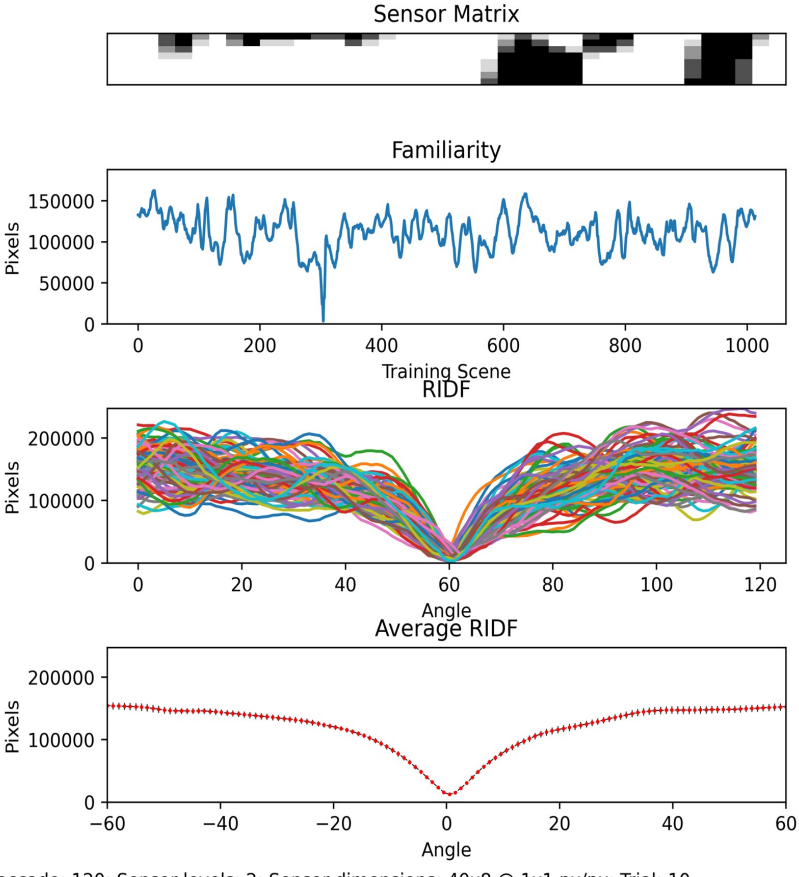


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 51.03; RMSD/dist: 0.128; TD: 93898; p90: 22; p50: 12; complete: 0

100%

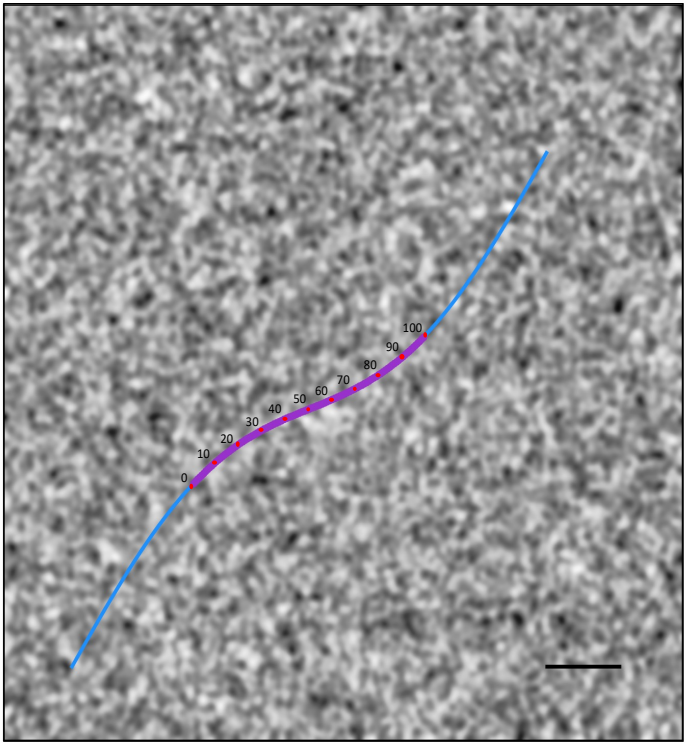


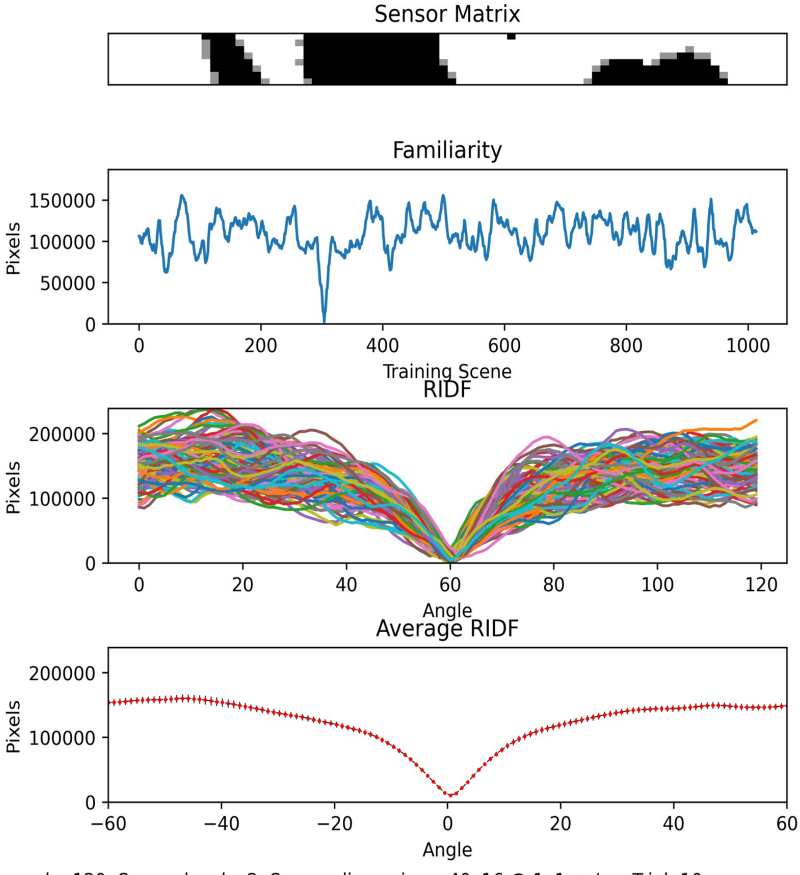


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 60.27; RMSD/dist: 0.151; TD: 99628; p90: 28; p50: 14; complete: 0

100%

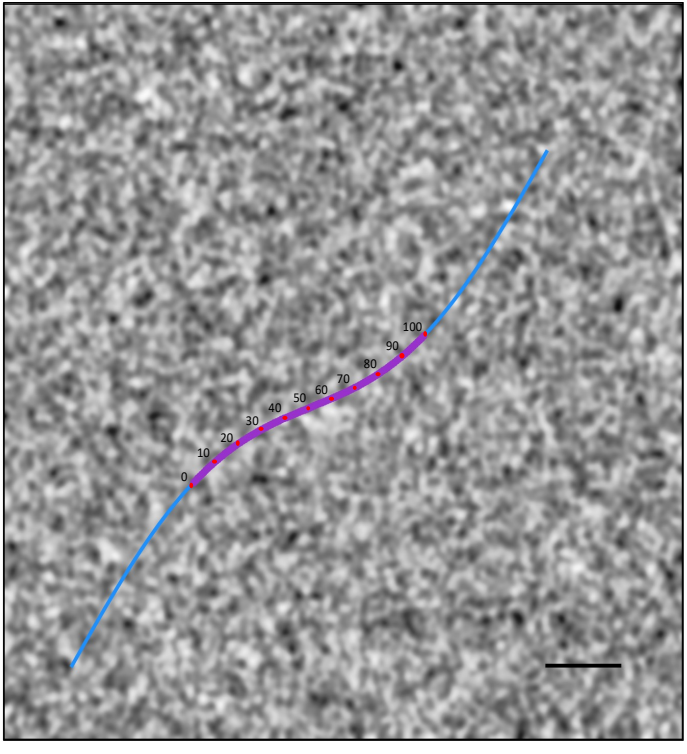


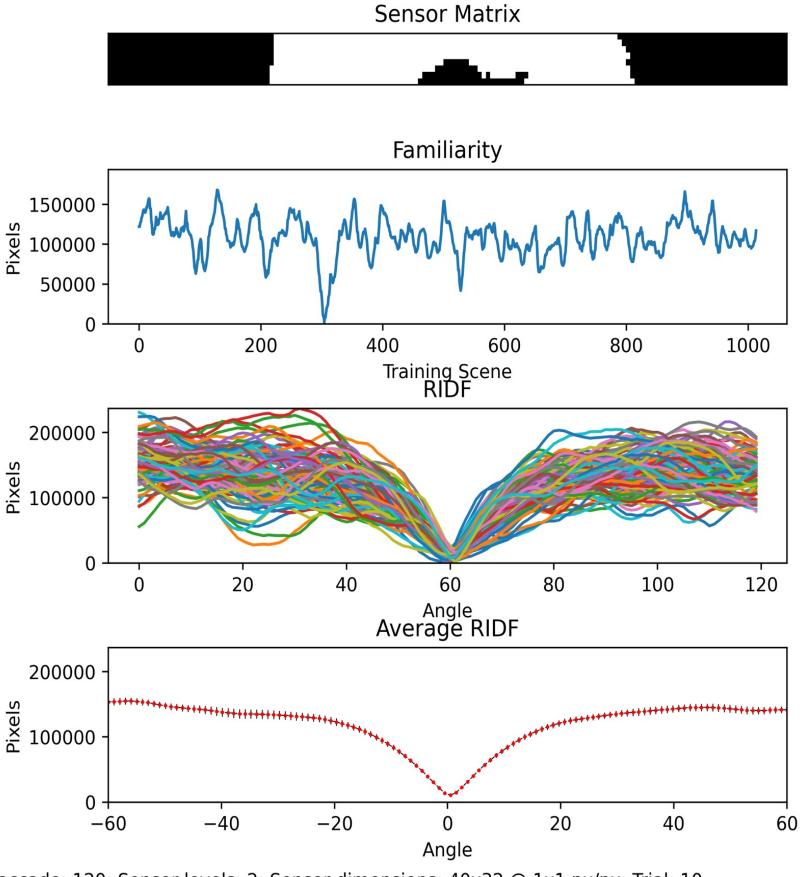


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 39.79; RMSD/dist: 0.099; TD: 99664; p90: 26; p50: 12; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 46.76; RMSD/dist: 0.117; TD: 99971; p90: 26; p50: 14; complete: 0