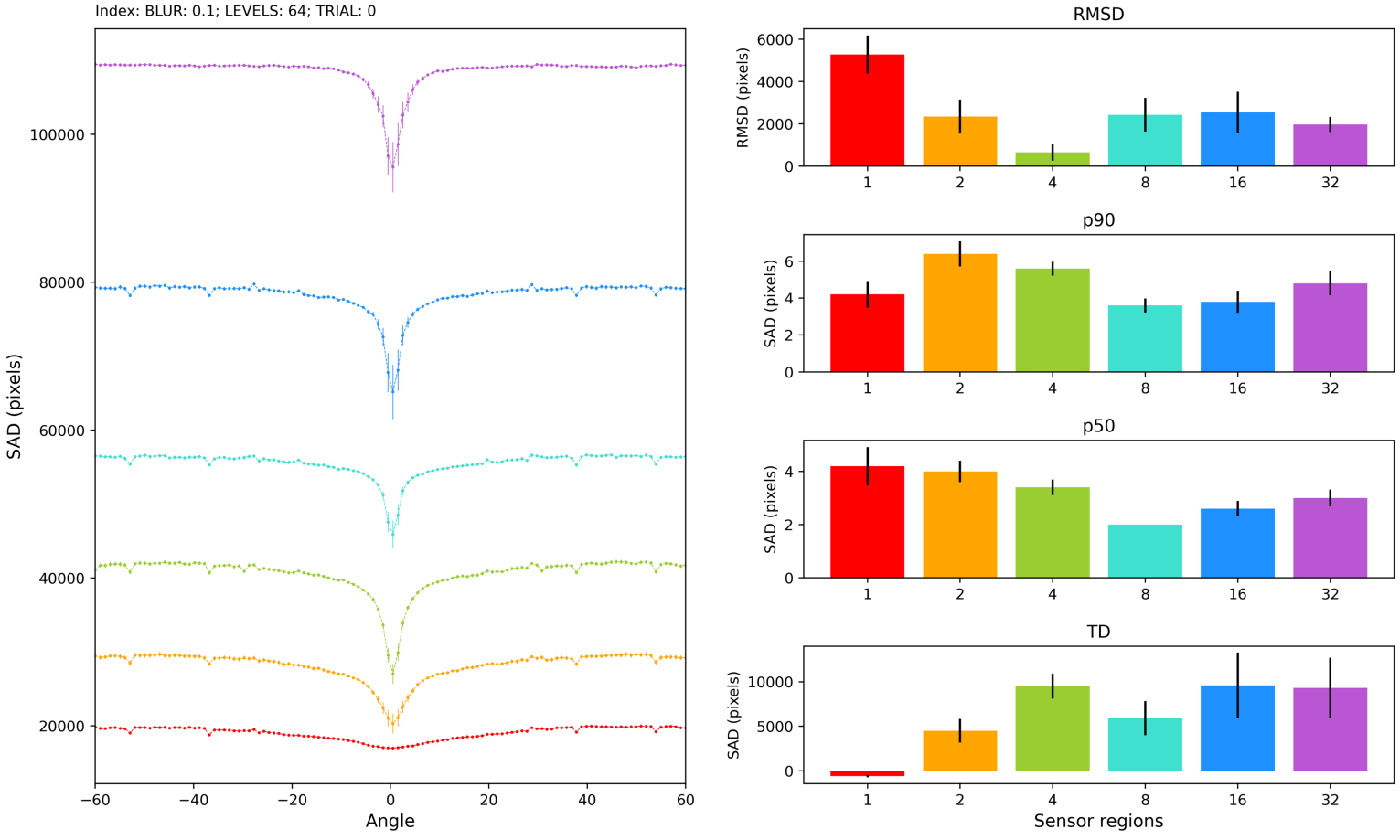
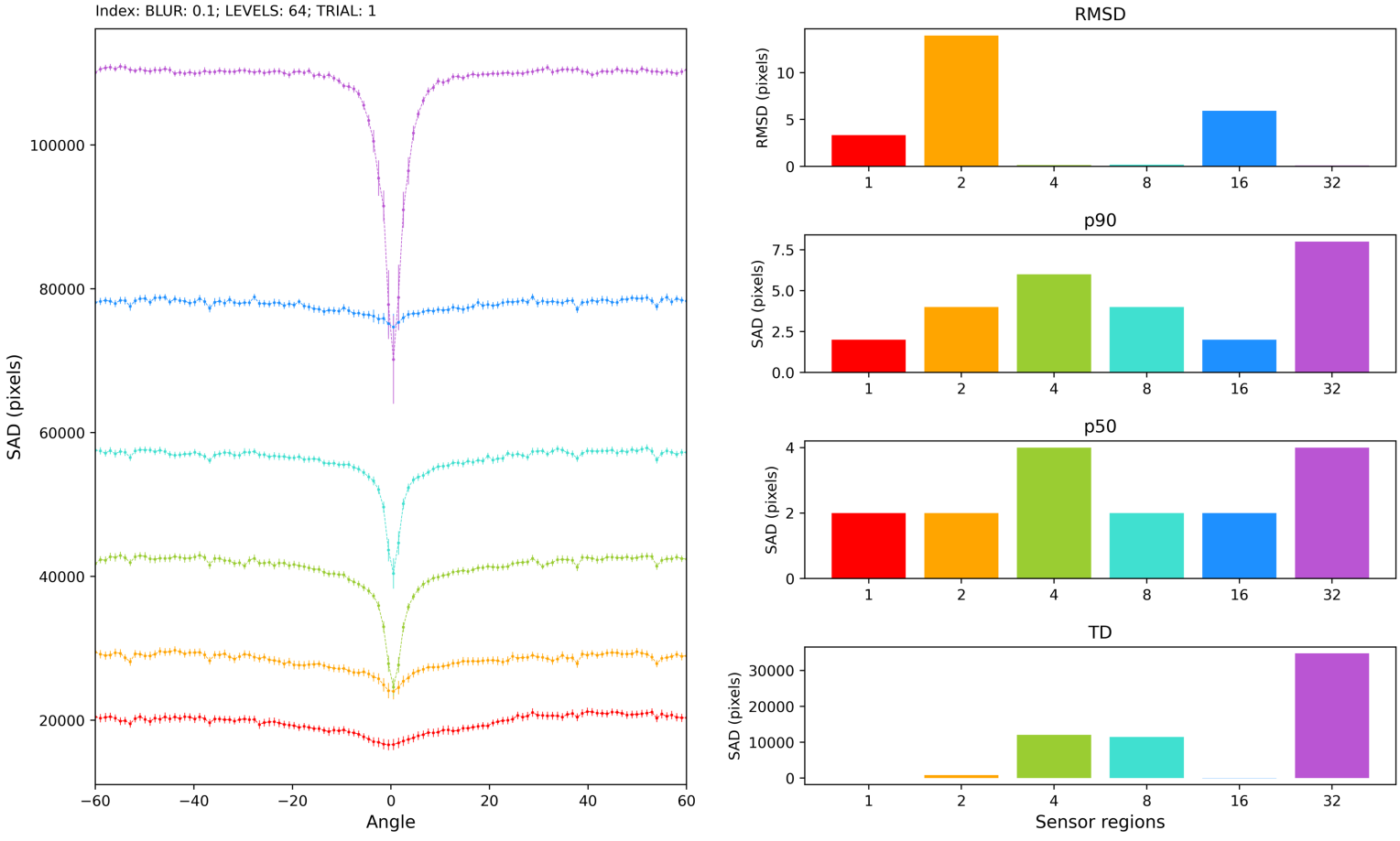

Index: BLUR: 0.1; LEVELS: 64; TRIAL: 0
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
6000
4000
2000
0
1
2
4
8
16
32
p90
SAD (pixels)
6
4
2
0
p50
TD
10000
5000
Sensor regions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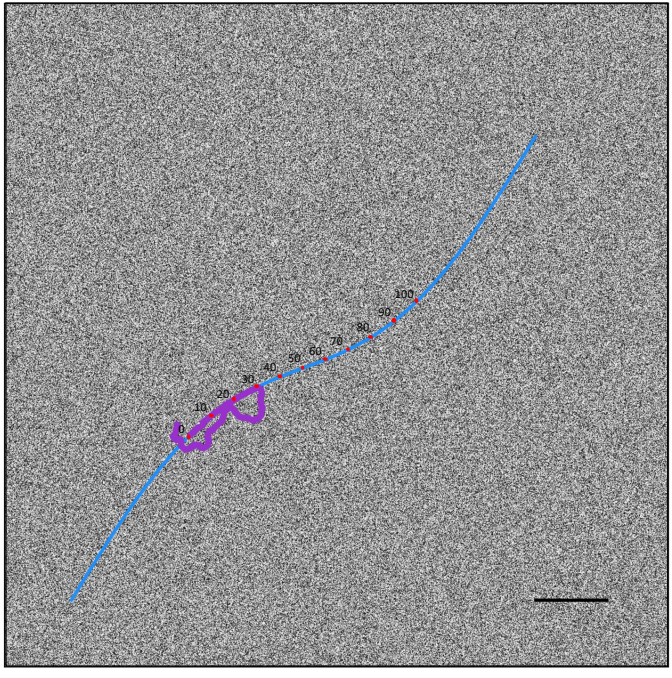
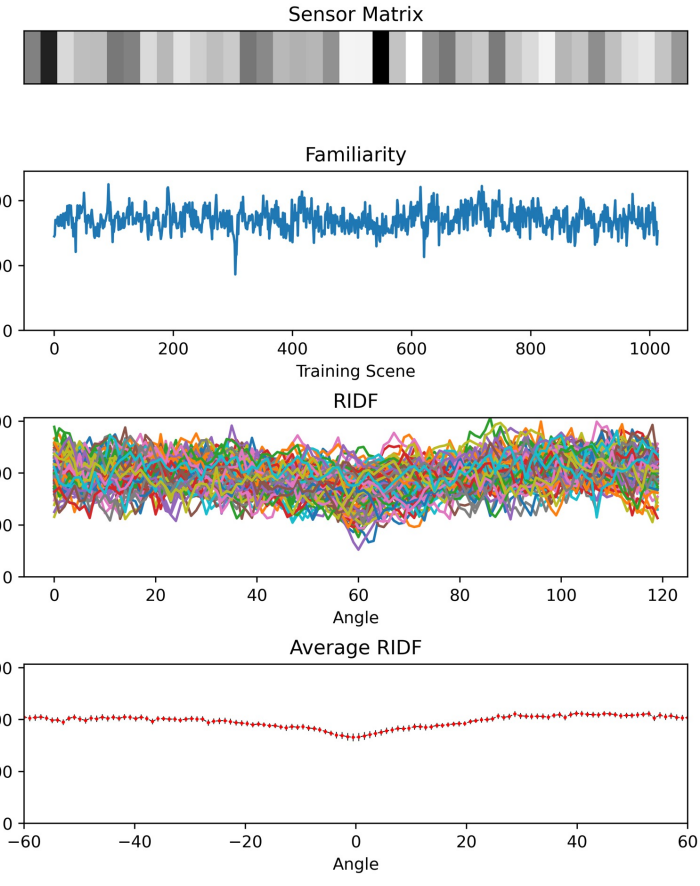
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
4
2
TD
30000
20000
10000
Sensor regions

30%

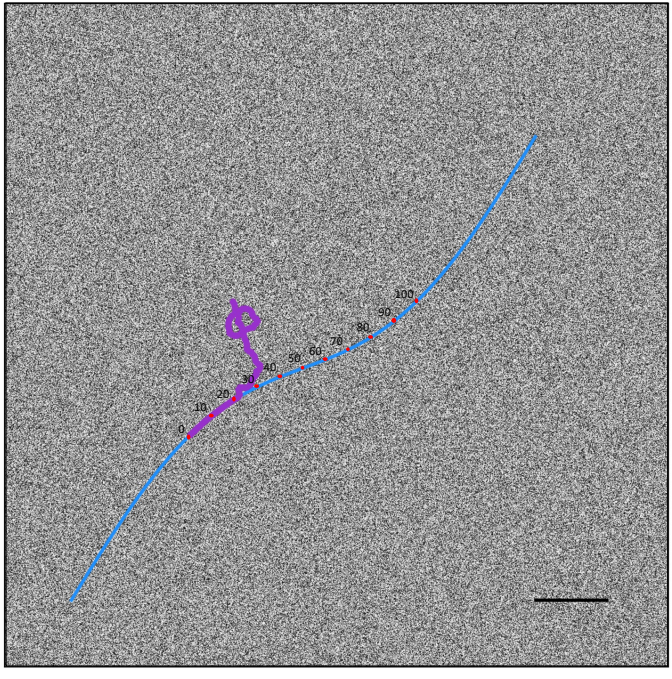


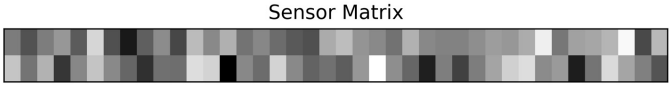


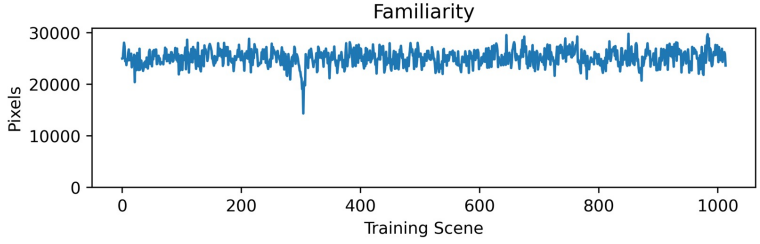
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

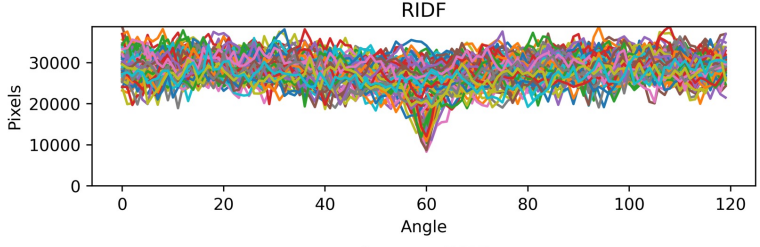
Navigation stats: RMSD error: 1325.81; RMSD/dist: 3.315; TD: -4; p90: 2; p50: 2; complete: 0

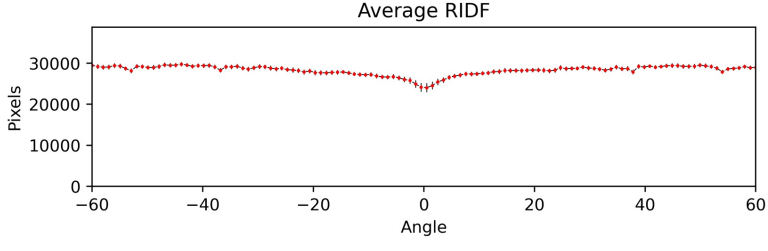
20%







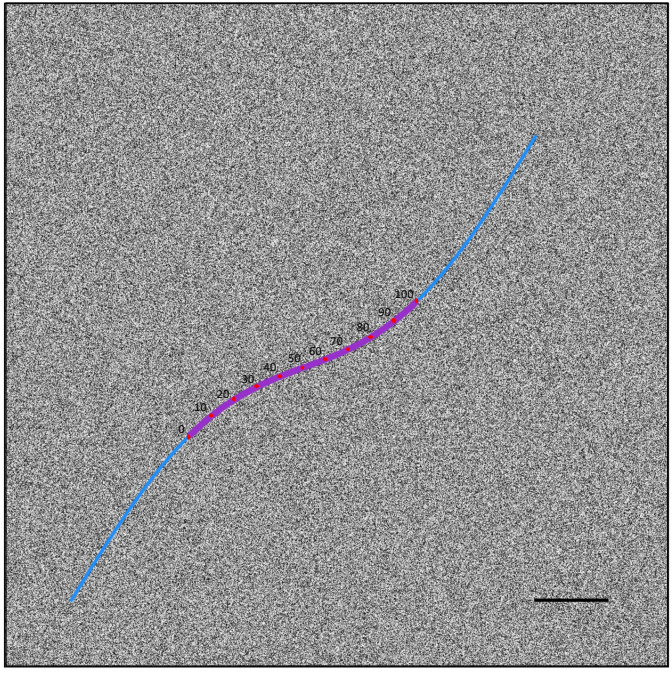


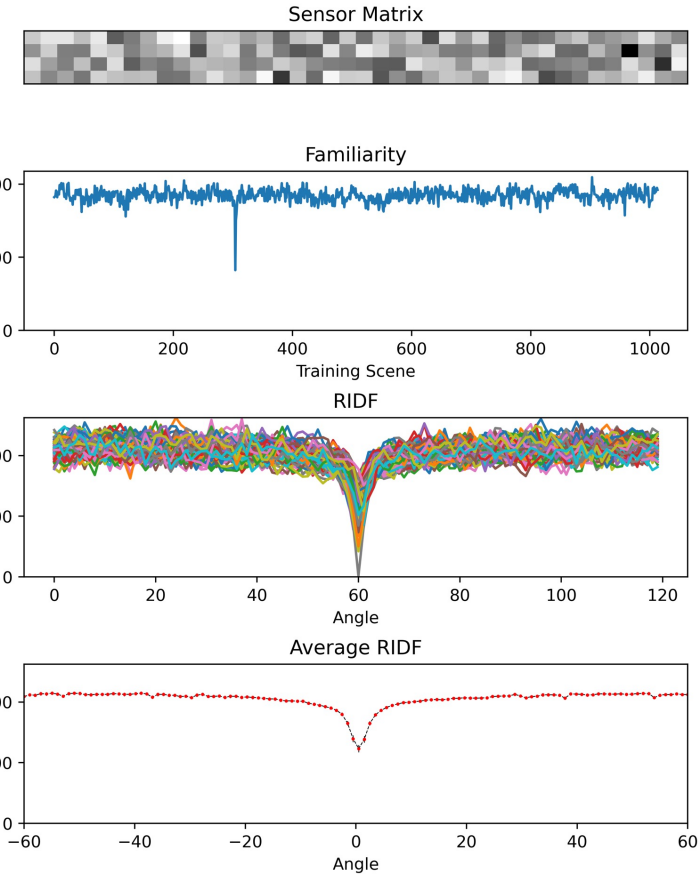


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 5584.24; RMSD/dist: 13.961; TD: 826; p90: 4; p50: 2; complete: 0

100%

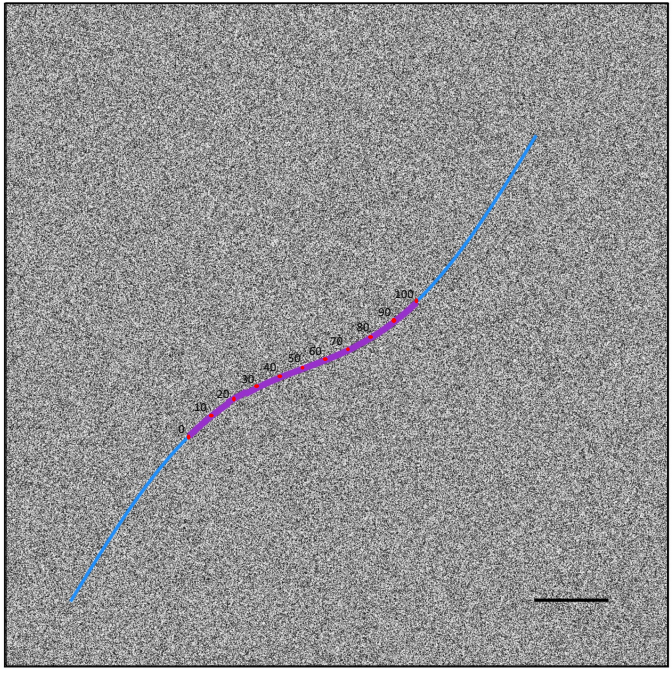


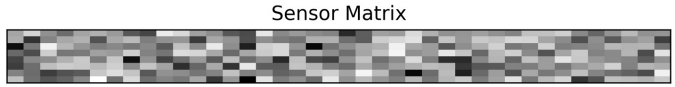


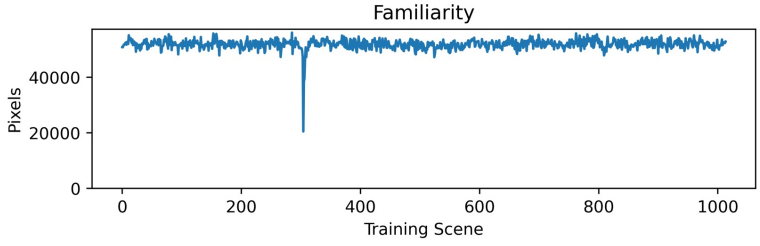
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

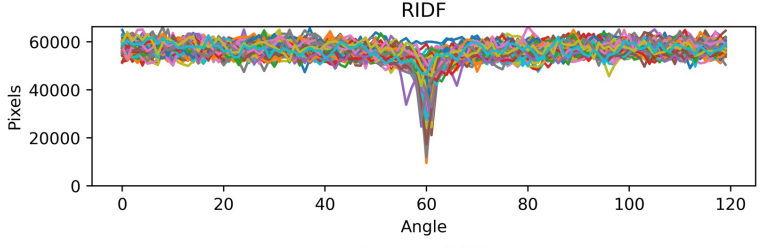
Navigation stats: RMSD error: 53.72; RMSD/dist: 0.134; TD: 12051; p90: 6; p50: 4; complete: 0

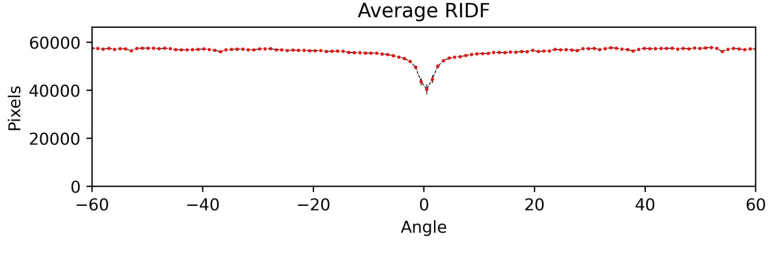
100%







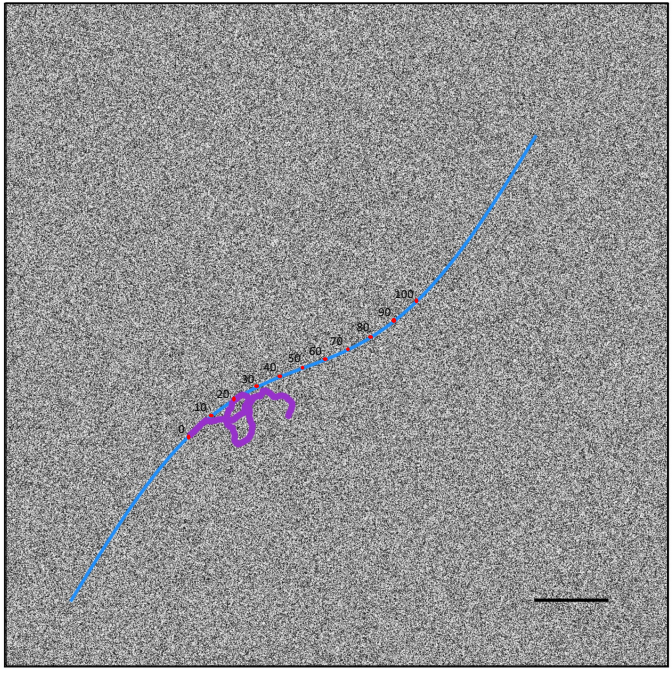


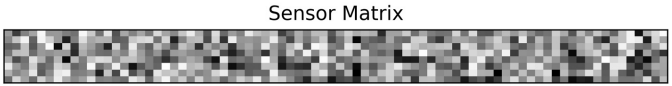


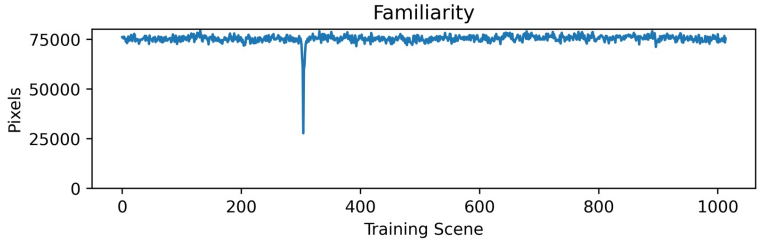
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

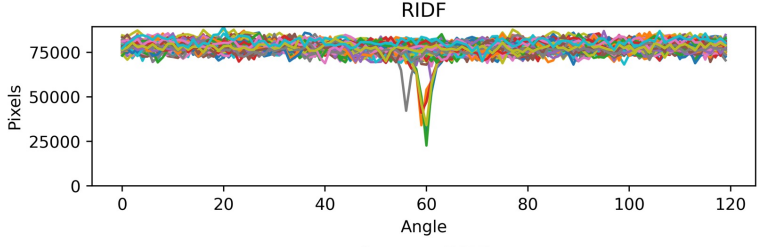
Navigation stats: RMSD error: 68.79; RMSD/dist: 0.172; TD: 11437; p90: 4; p50: 2; complete: 0

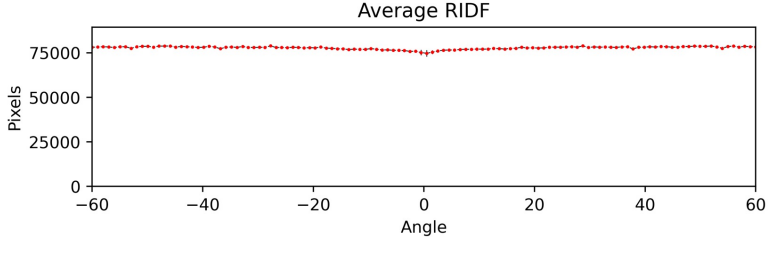
0%







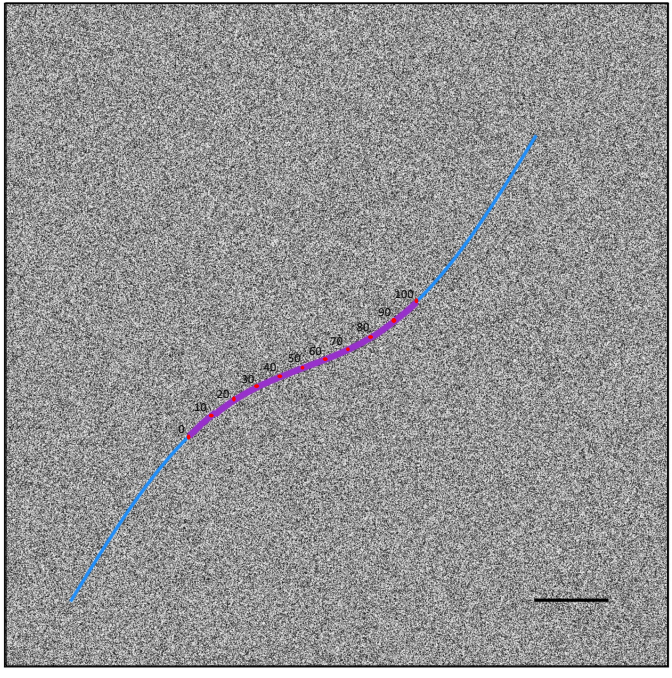


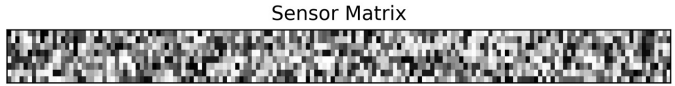


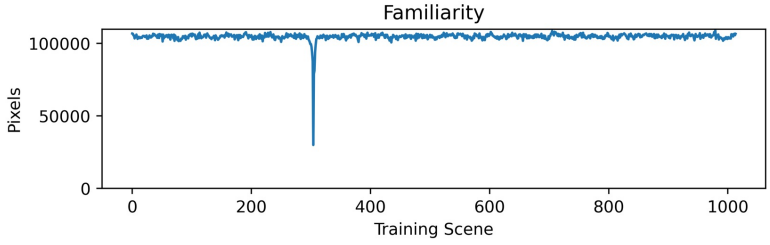
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

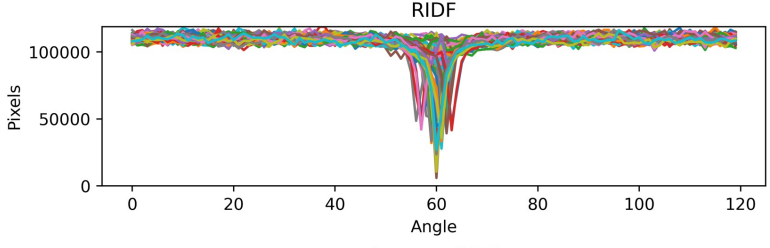
Navigation stats: RMSD error: 2369.89; RMSD/dist: 5.925; TD: -36; p90: 2; p50: 2; complete: 0

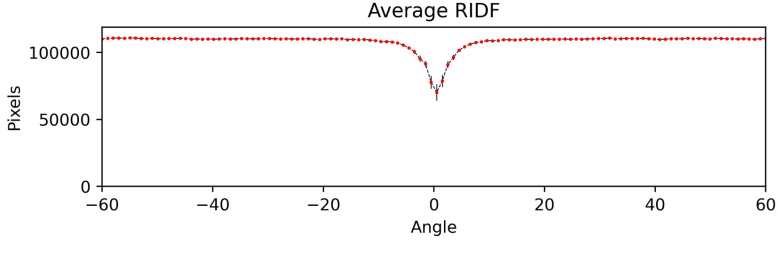
100%





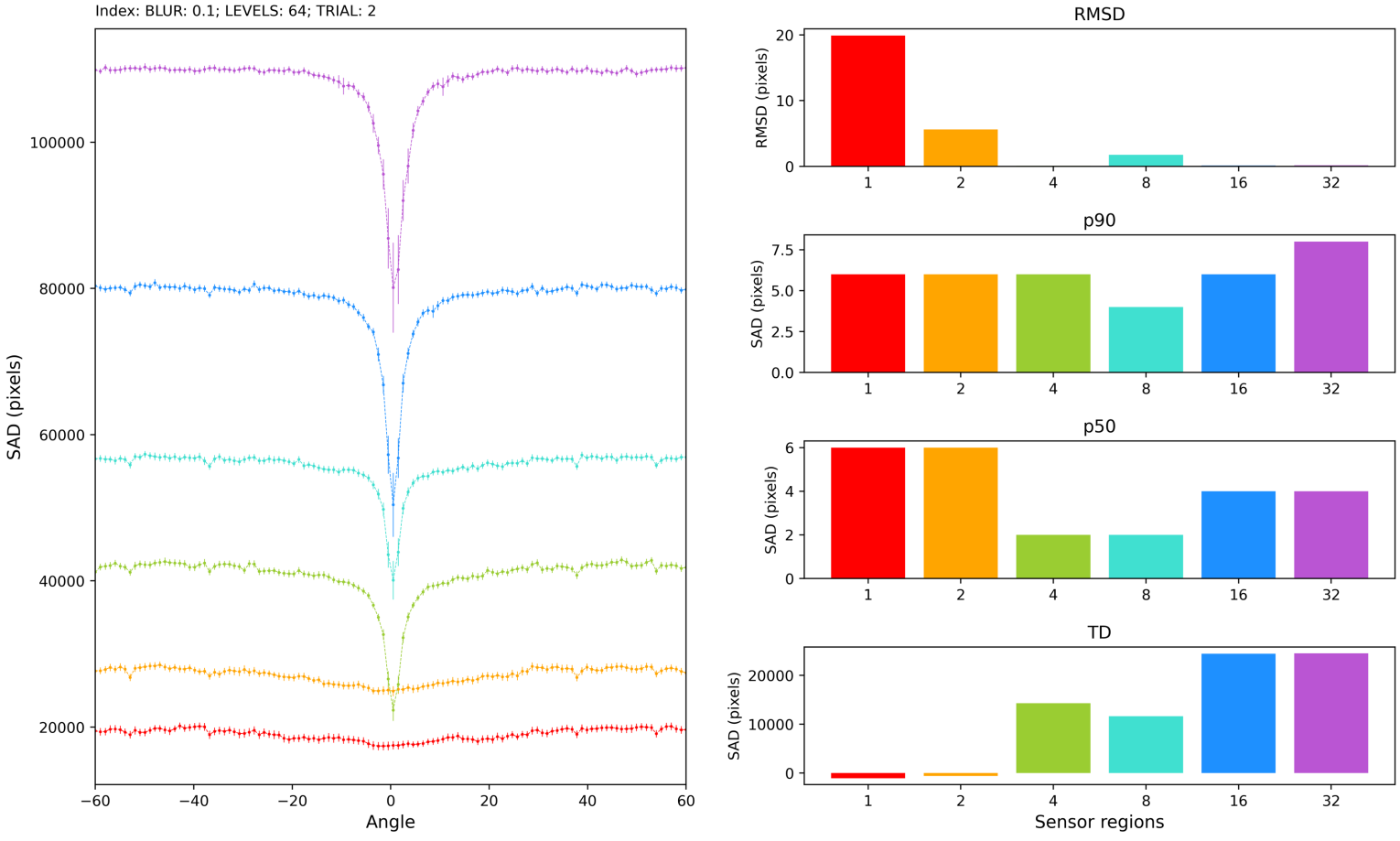




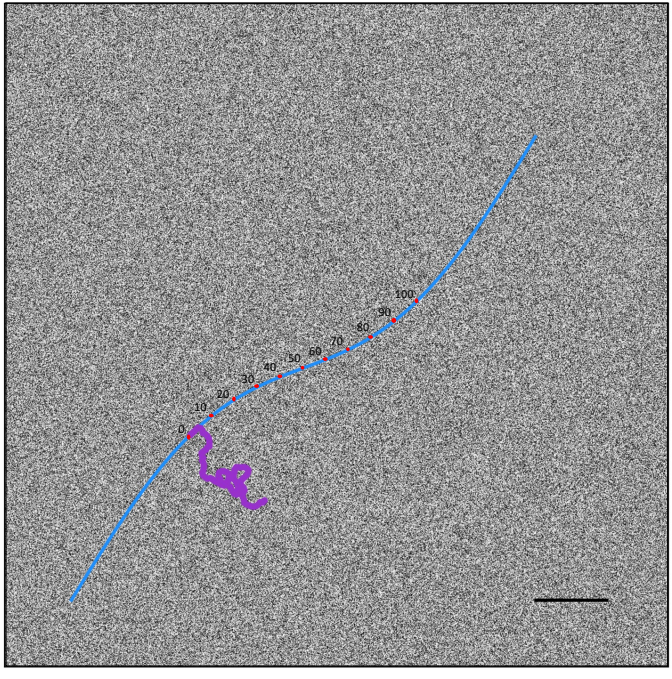


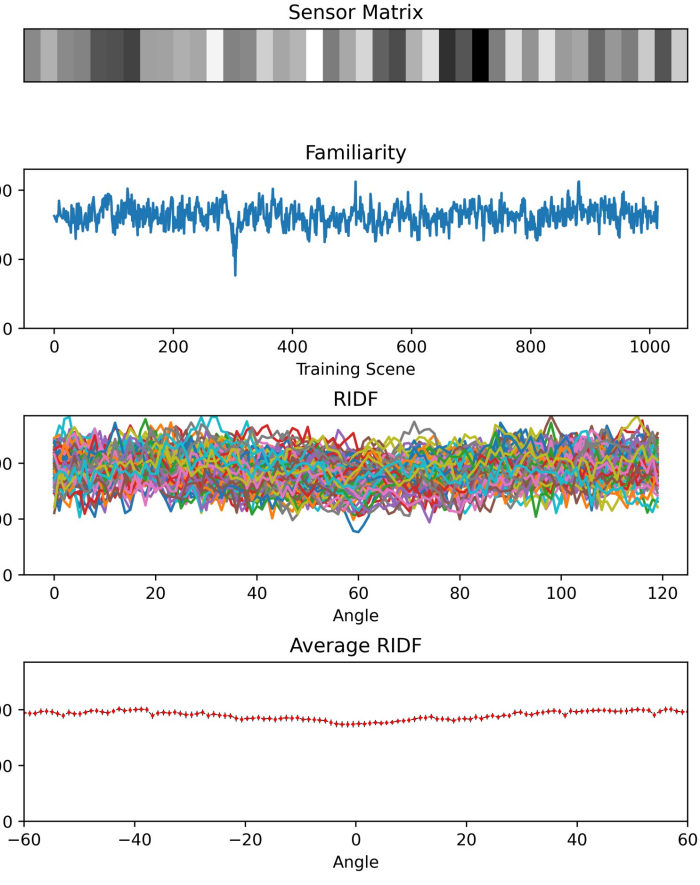
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 33.48; RMSD/dist: 0.084; TD: 34755; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 64; TRIAL: 2
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
6
4
2
TD
20000
10000
Sensor regions

0%

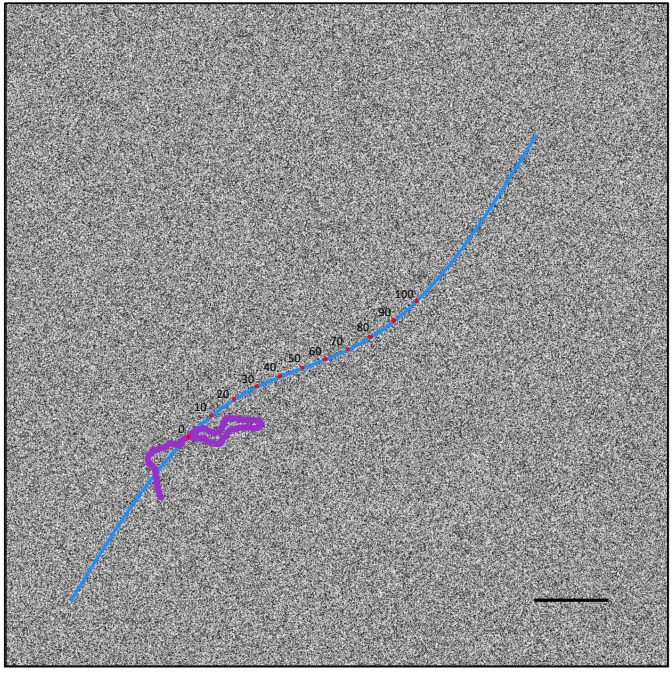


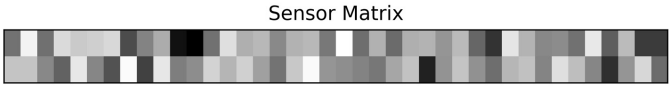


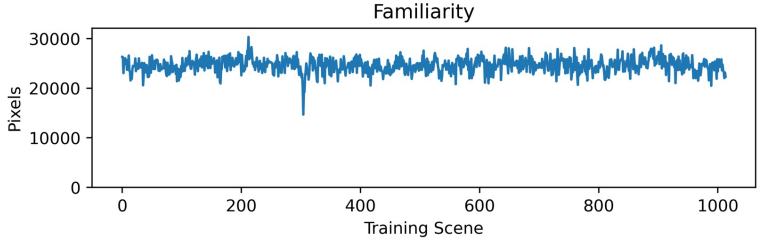
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

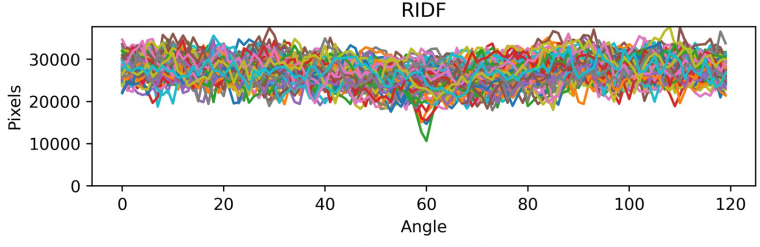
Navigation stats: RMSD error: 7965.78; RMSD/dist: 19.914; TD: -1083; p90: 6; p50: 6; complete: 0

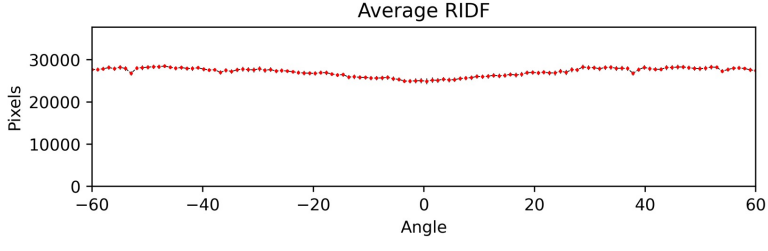
0%







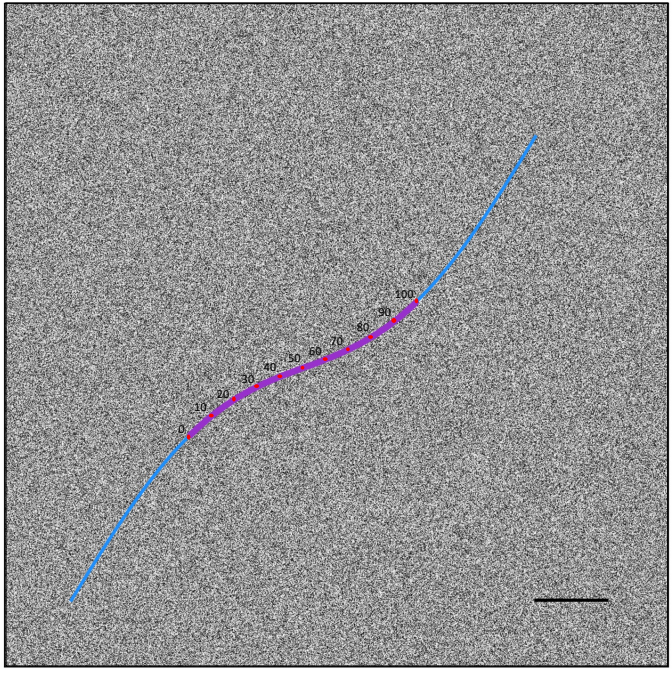


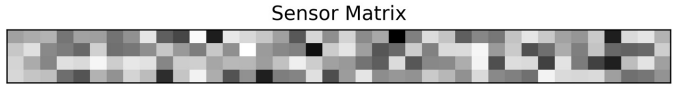


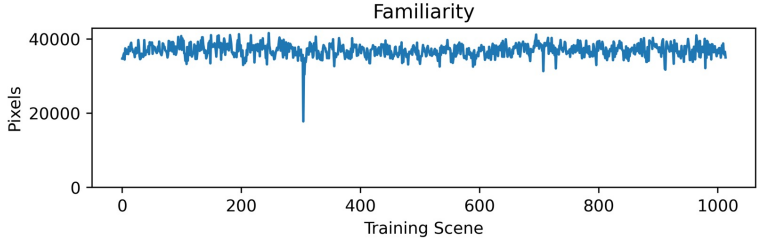
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

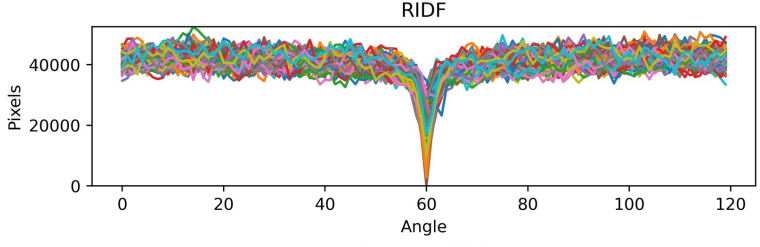
Navigation stats: RMSD error: 2237.16; RMSD/dist: 5.593; TD: -614; p90: 6; p50: 6; complete: 0

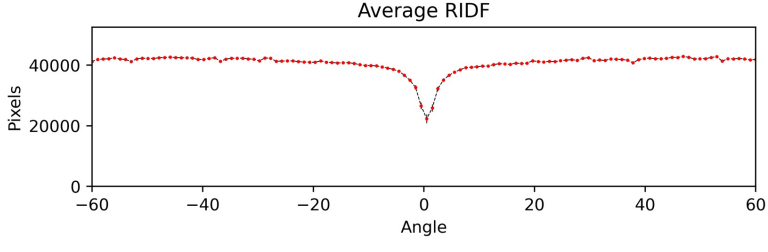
100%







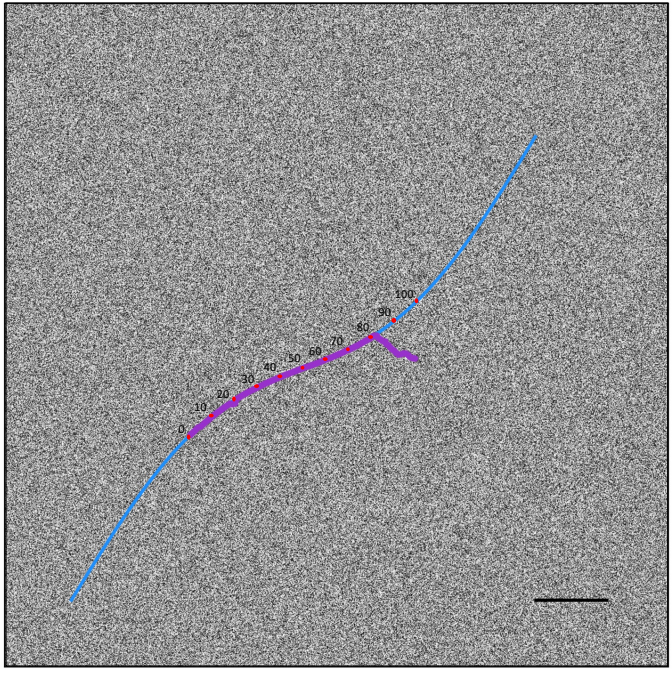


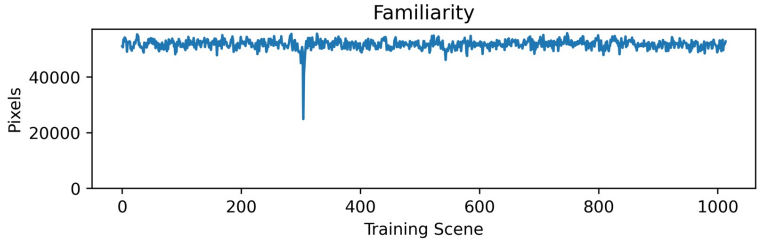


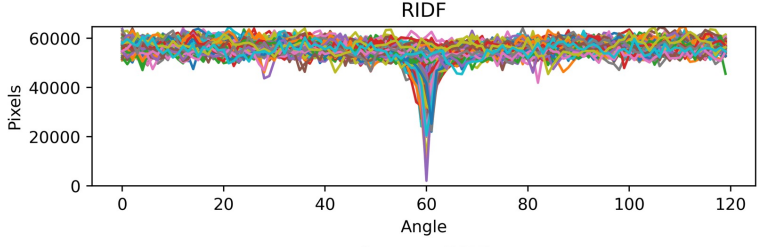
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

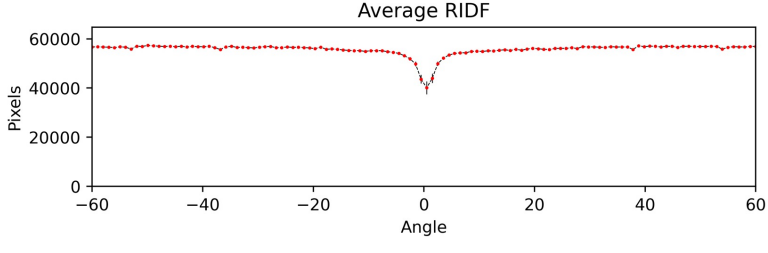
Navigation stats: RMSD error: 38.48; RMSD/dist: 0.096; TD: 14271; p90: 6; p50: 2; complete: 0

80%





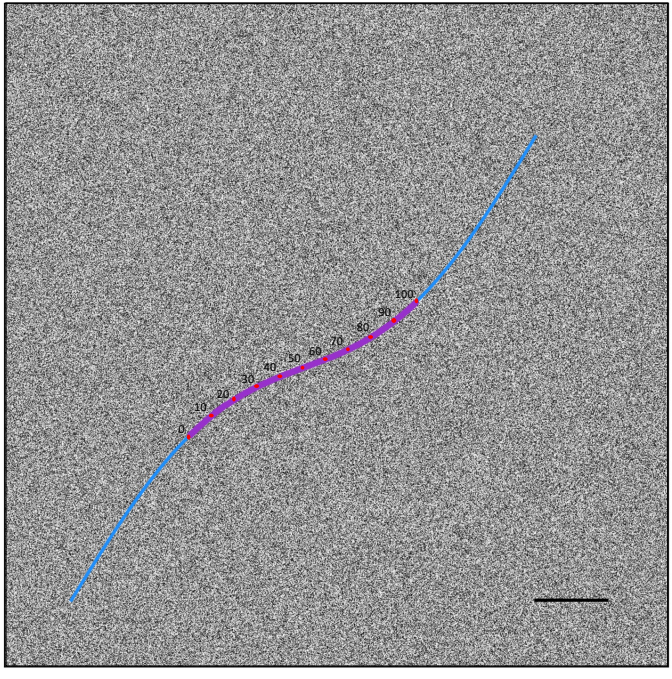


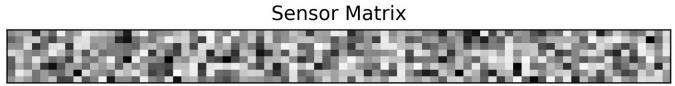


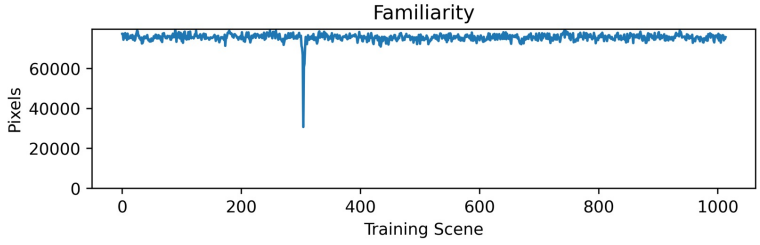
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

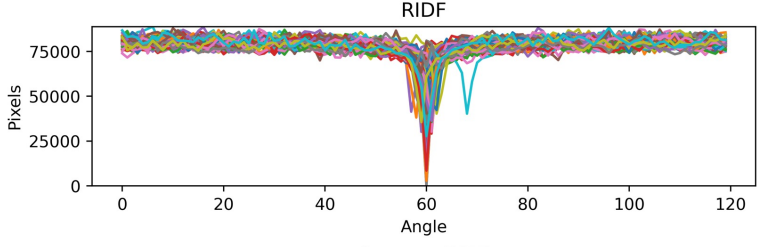
Navigation stats: RMSD error: 696.51; RMSD/dist: 1.741; TD: 11644; p90: 4; p50: 2; complete: 0

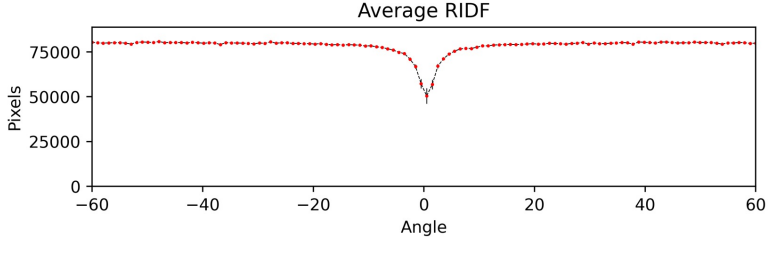
100%







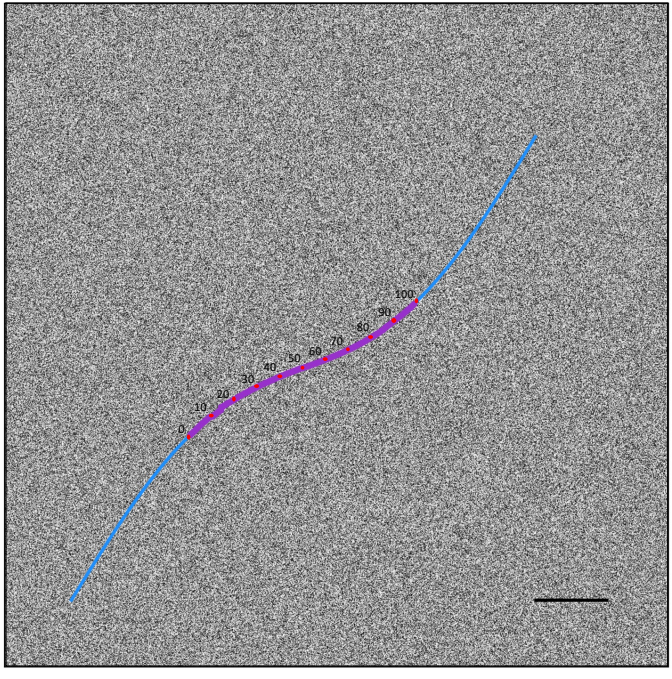


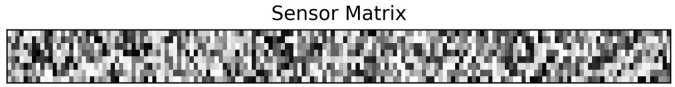


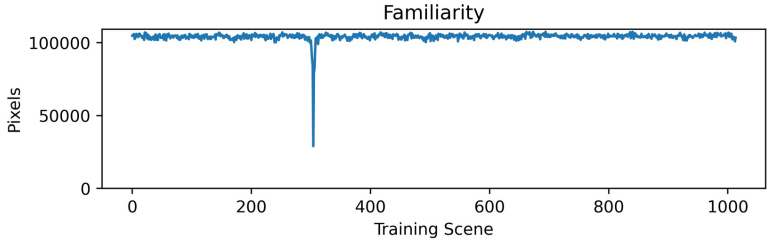
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

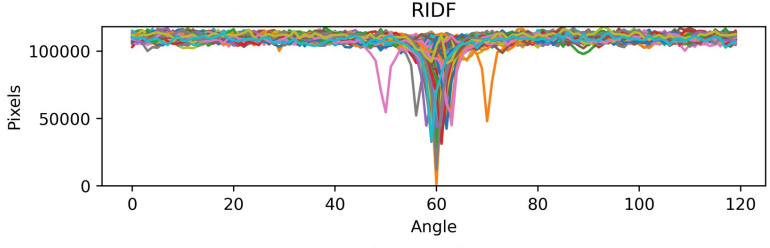
Navigation stats: RMSD error: 42.67; RMSD/dist: 0.107; TD: 24406; p90: 6; p50: 4; complete: 0

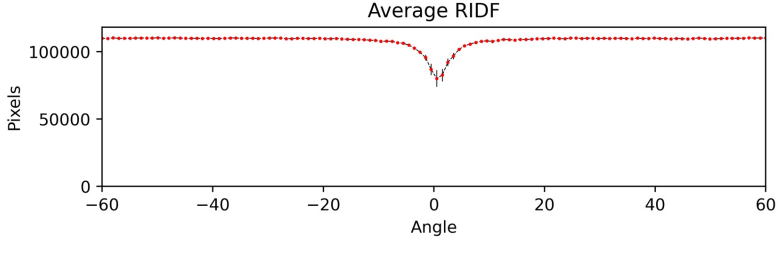
100%





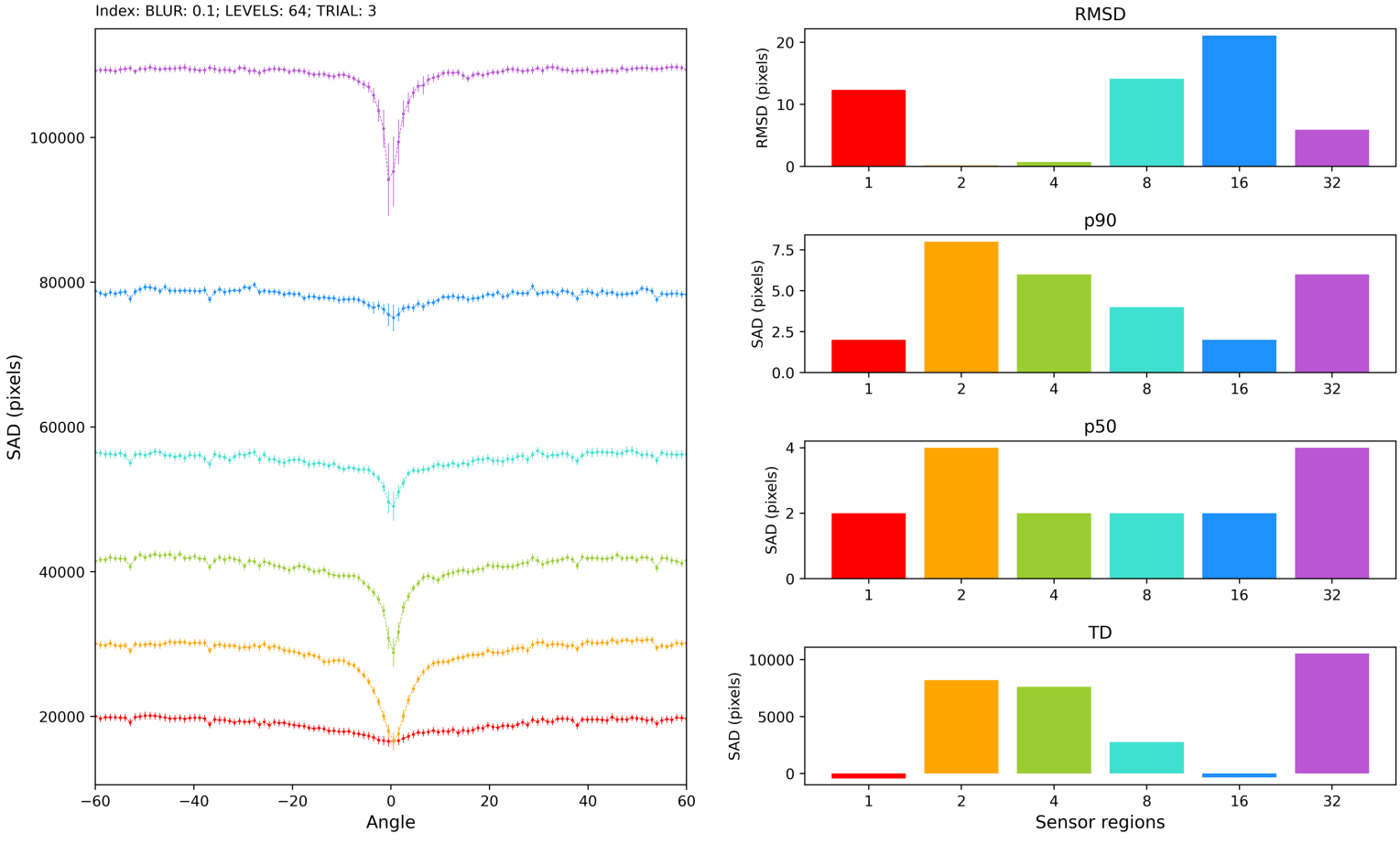




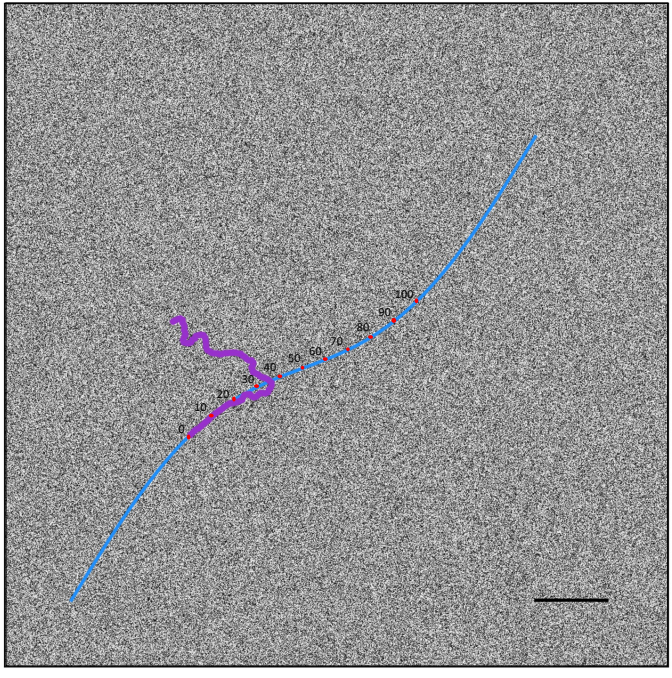


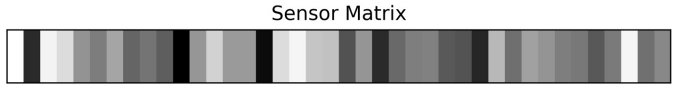
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

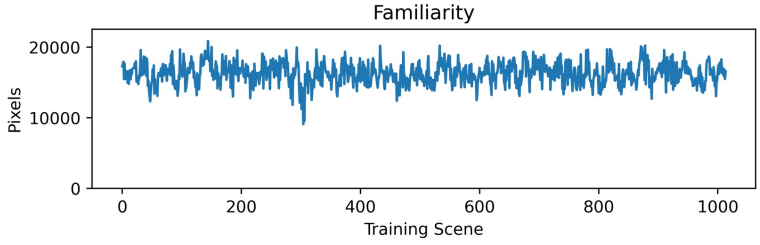
Navigation stats: RMSD error: 53.69; RMSD/dist: 0.134; TD: 24509; p90: 8; p50: 4; complete: 0

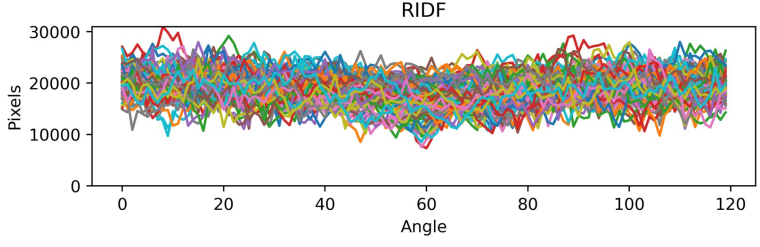

Index: BLUR: 0.1; LEVELS: 64; TRIAL: 3
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
4
2
TD
10000
5000
Sensor regions

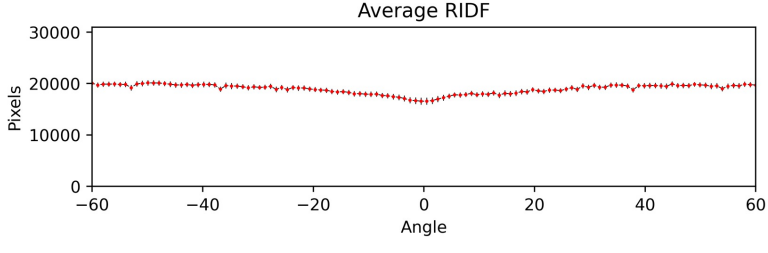
10%







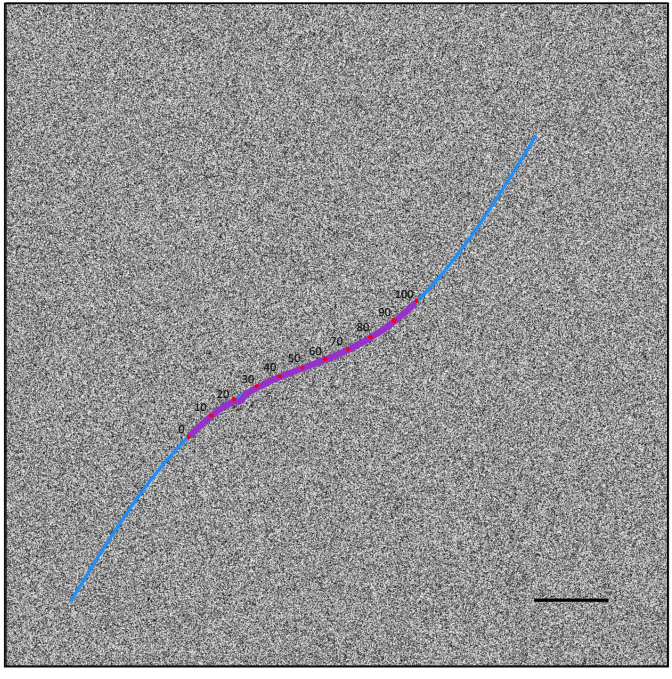


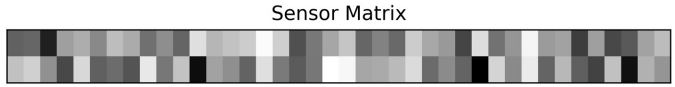


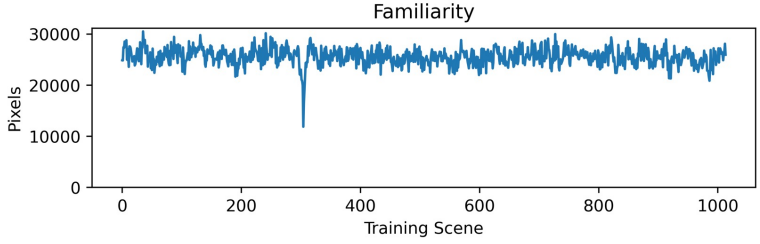
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

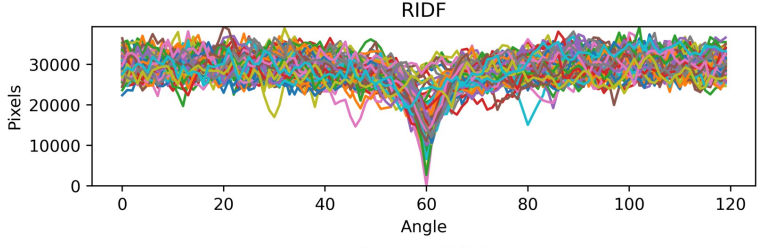
Navigation stats: RMSD error: 4936.09; RMSD/dist: 12.340; TD: -429; p90: 2; p50: 2; complete: 0

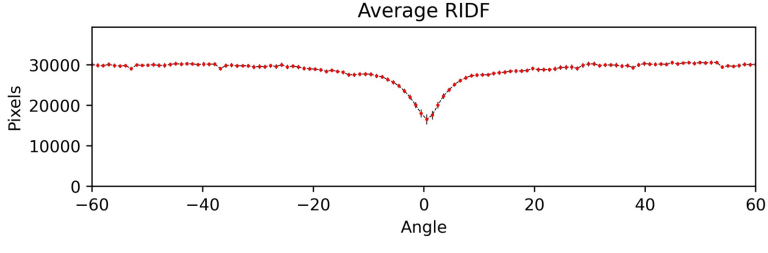
90%







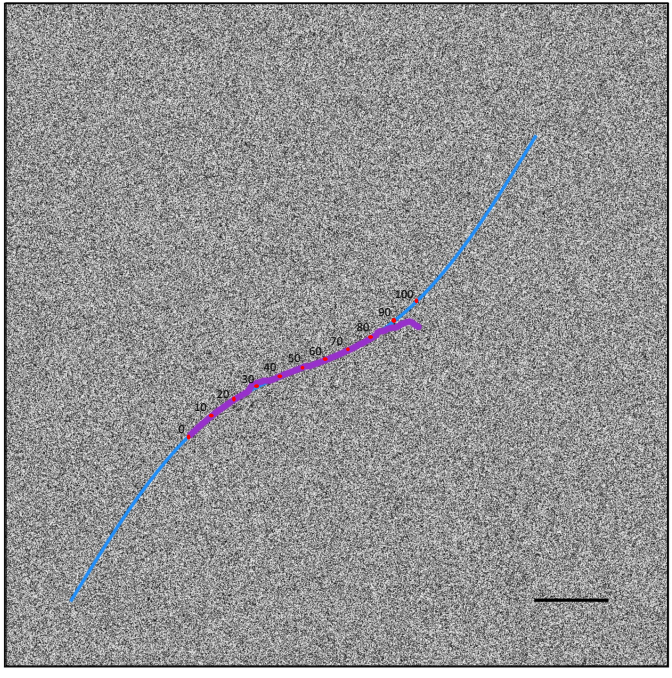


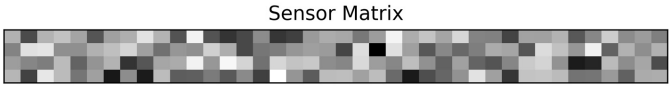


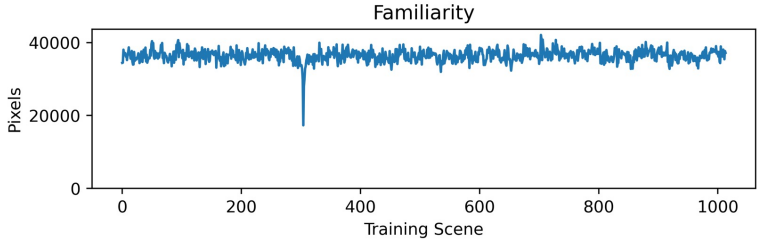
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

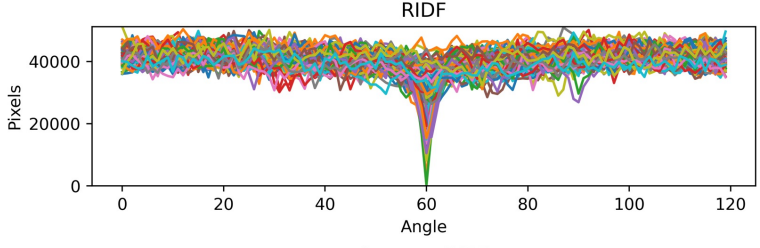
Navigation stats: RMSD error: 62.21; RMSD/dist: 0.156; TD: 8185; p90: 8; p50: 4; complete: 0

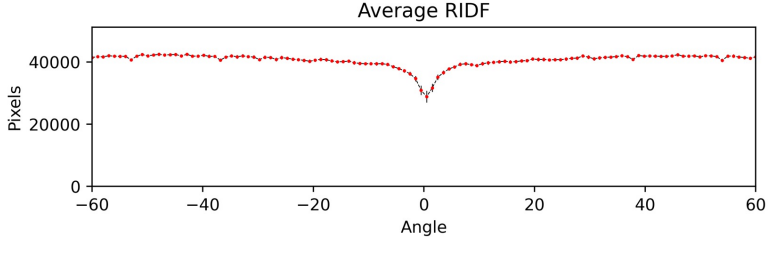
70%







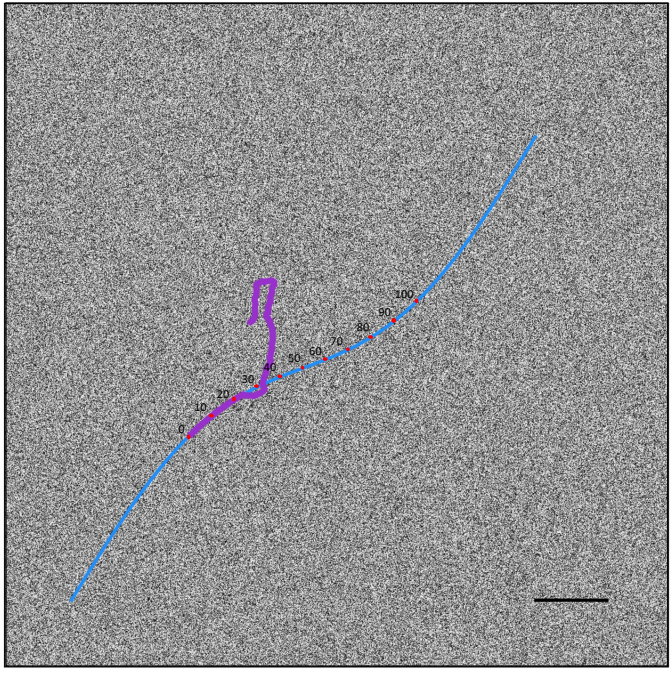


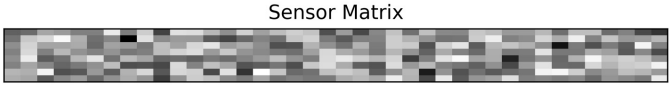


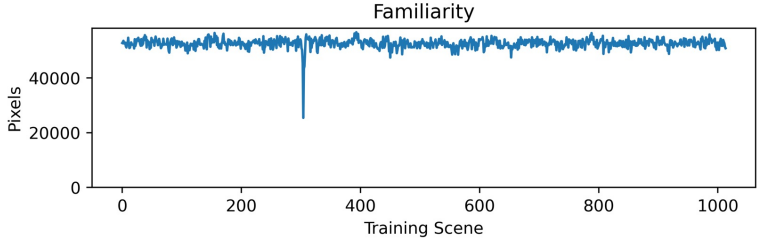
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

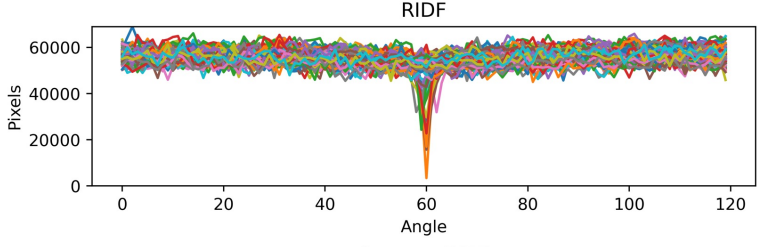
Navigation stats: RMSD error: 282.30; RMSD/dist: 0.706; TD: 7613; p90: 6; p50: 2; complete: 0

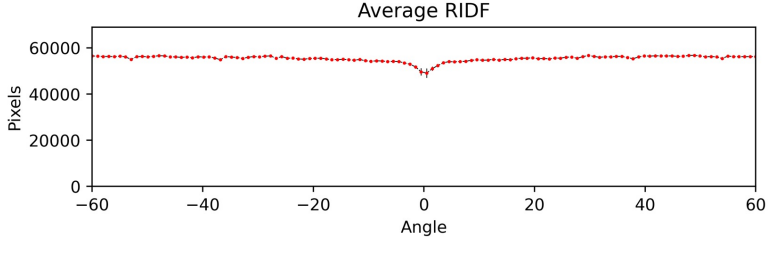
20%







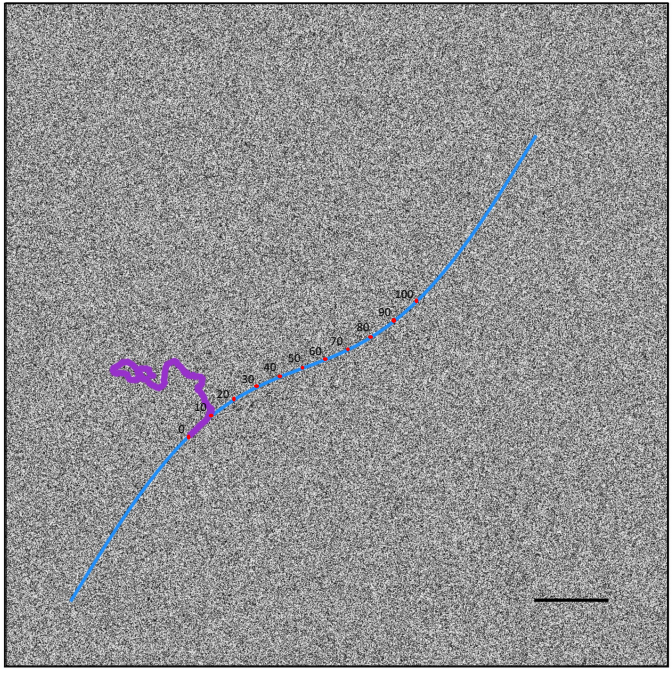


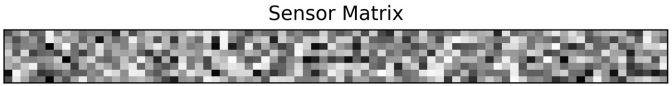


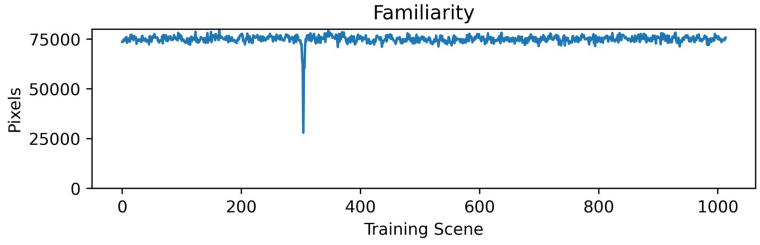
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

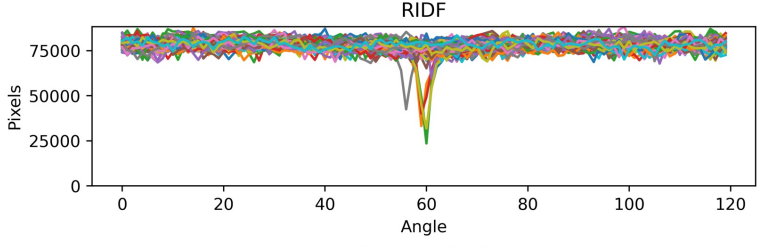
Navigation stats: RMSD error: 5645.25; RMSD/dist: 14.113; TD: 2771; p90: 4; p50: 2; complete: 0

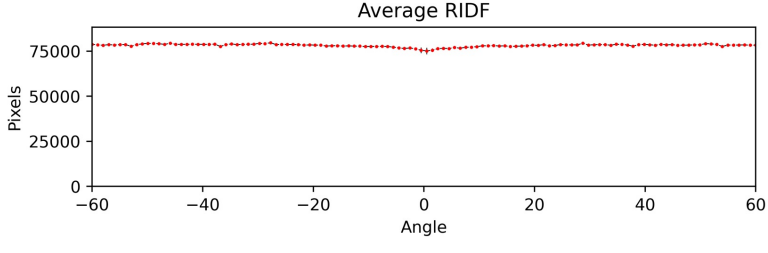
10%







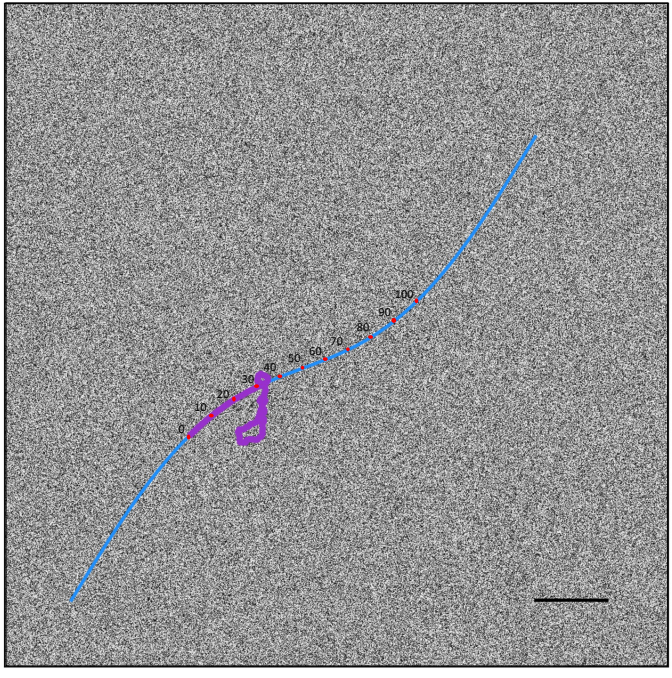


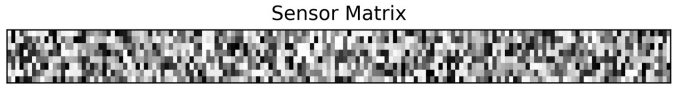


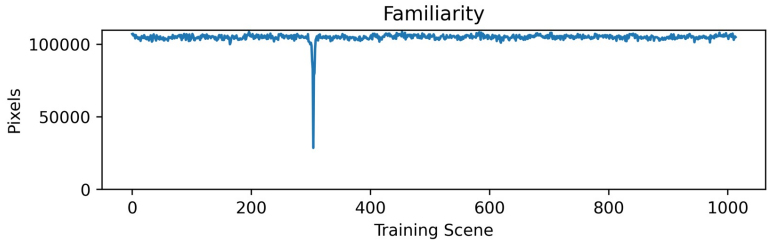
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

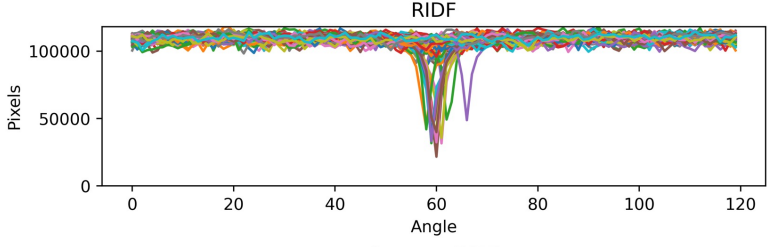
Navigation stats: RMSD error: 8444.64; RMSD/dist: 21.112; TD: -346; p90: 2; p50: 2; complete: 0

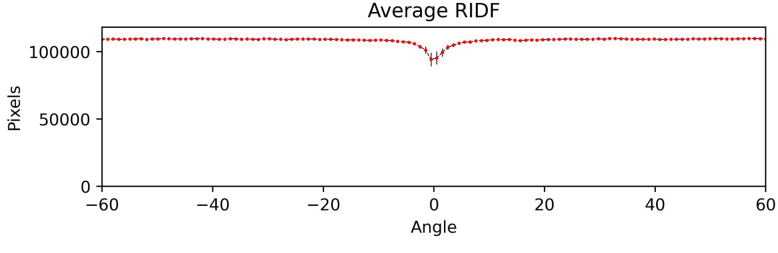
30%





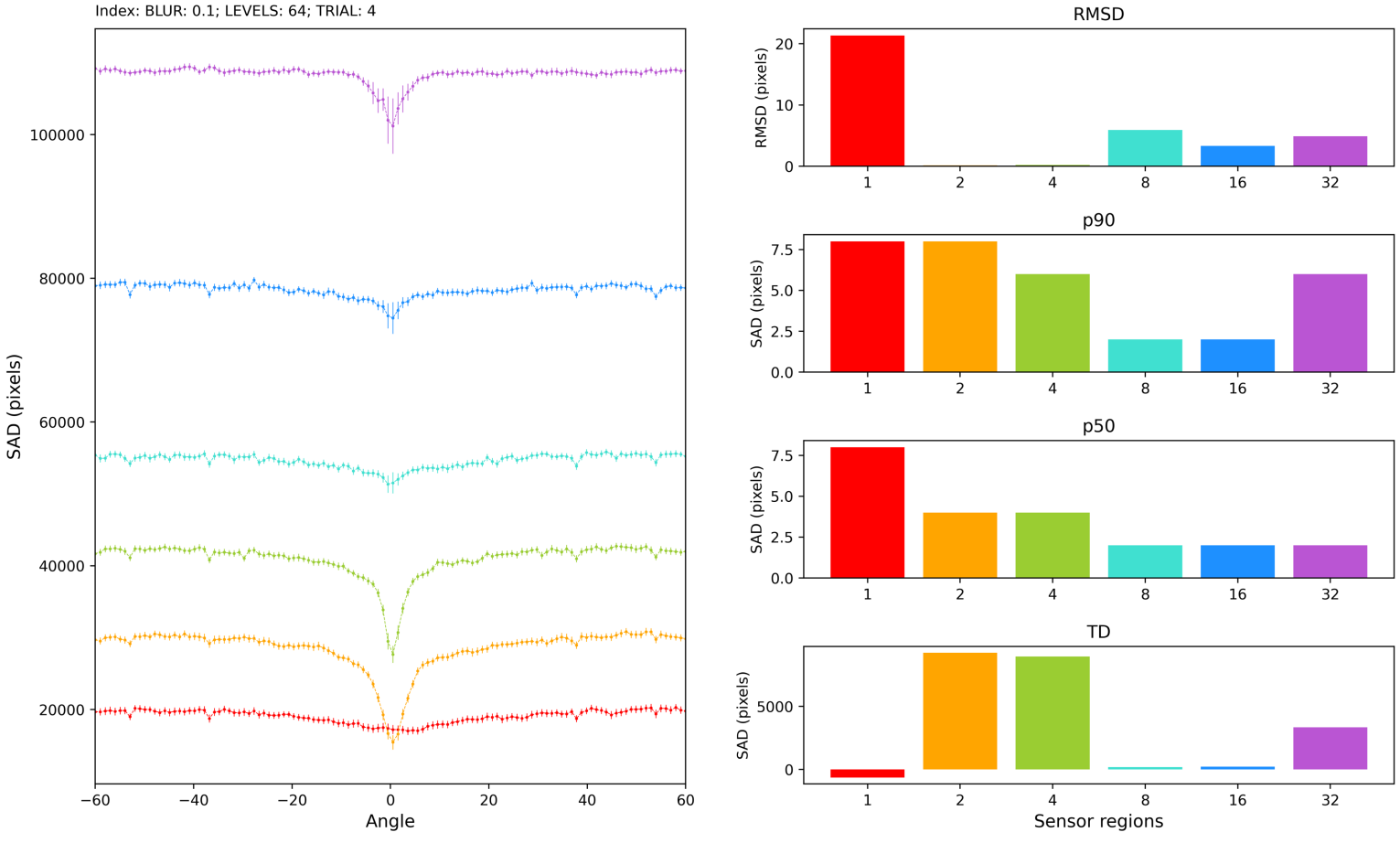




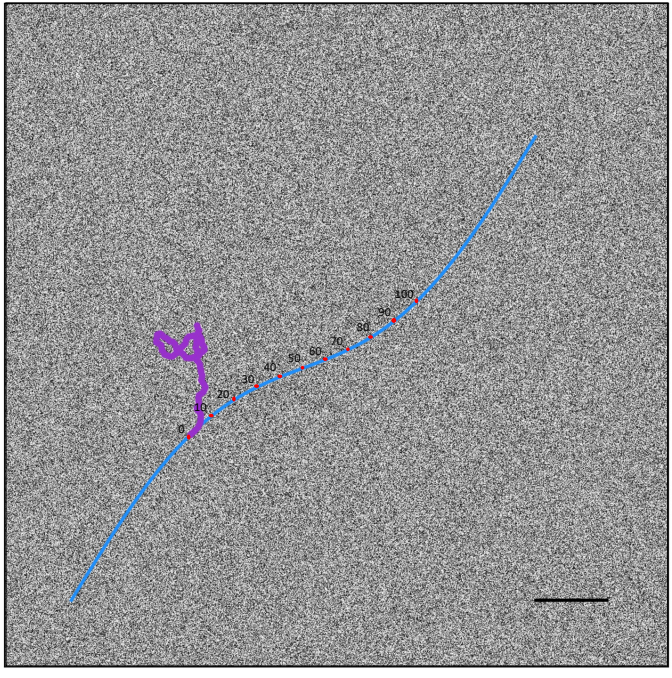


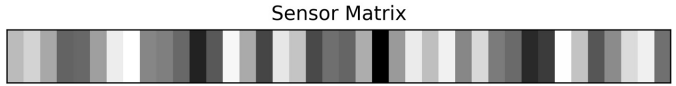
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

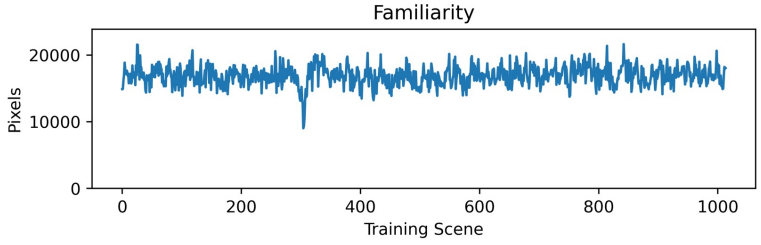
Navigation stats: RMSD error: 2360.85; RMSD/dist: 5.902; TD: 10528; p90: 6; p50: 4; complete: 0

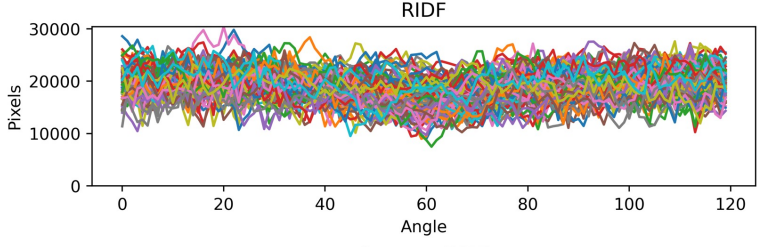

Index: BLUR: 0.1; LEVELS: 64; TRIAL: 4
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
TD
5000
Sensor regions

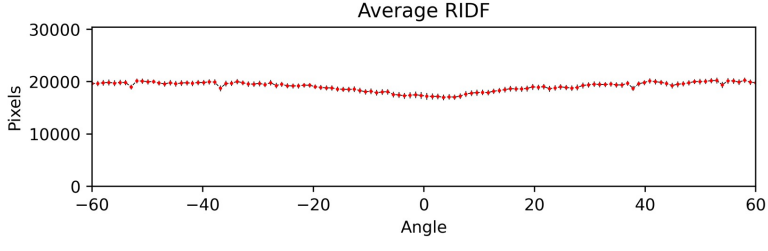
0%







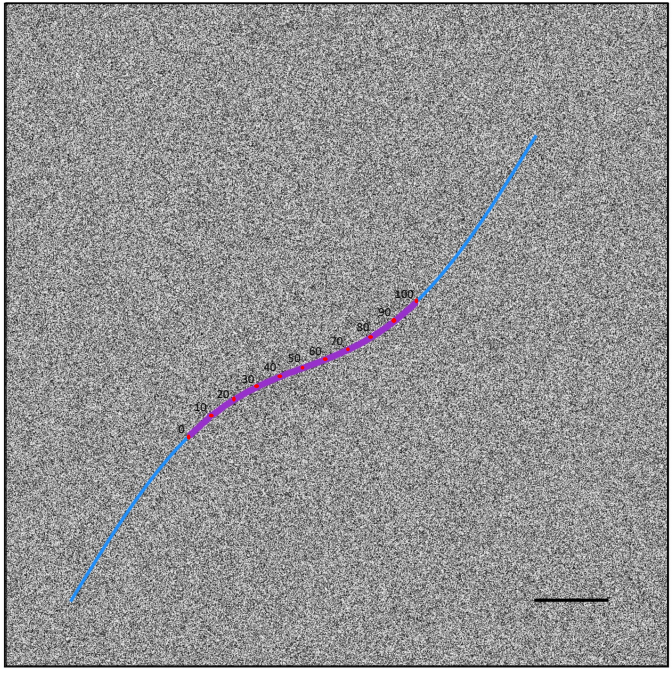


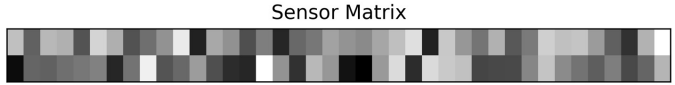


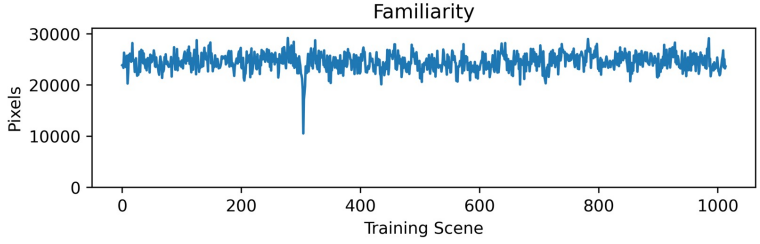
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

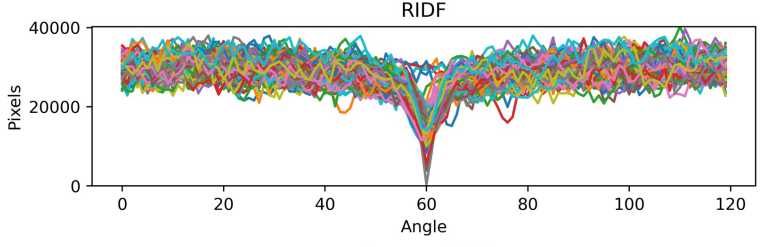
Navigation stats: RMSD error: 8545.30; RMSD/dist: 21.363; TD: -637; p90: 8; p50: 8; complete: 0

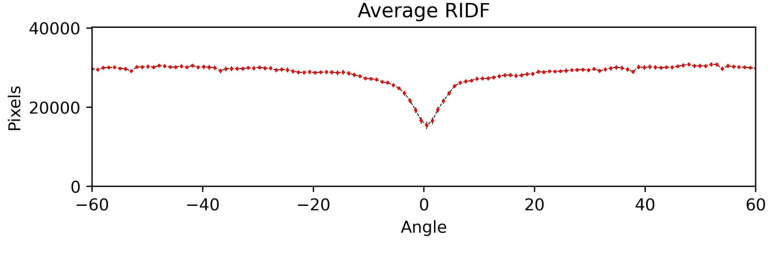
100%







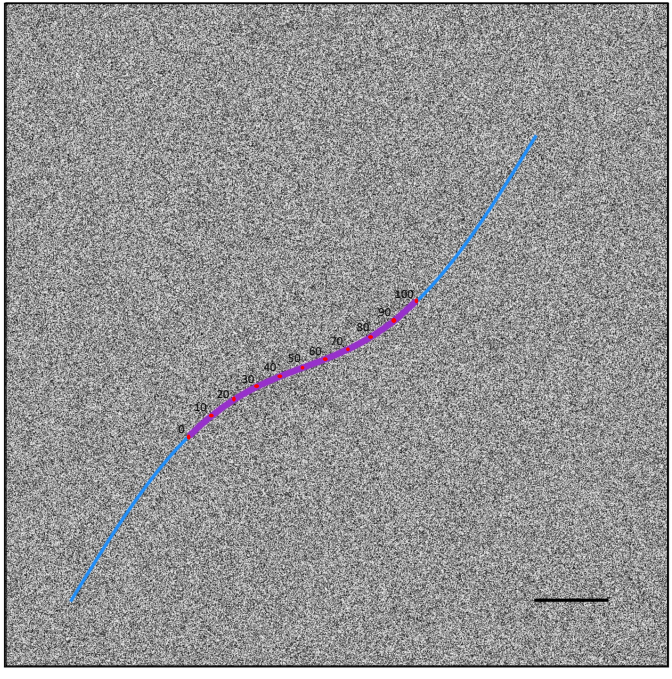


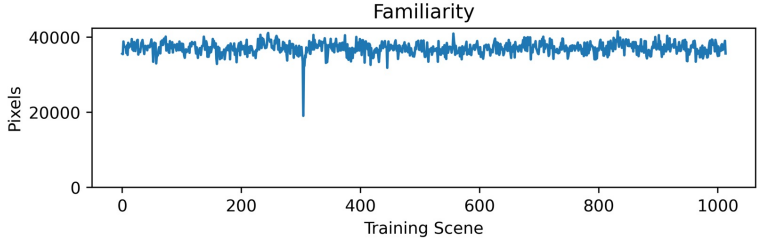


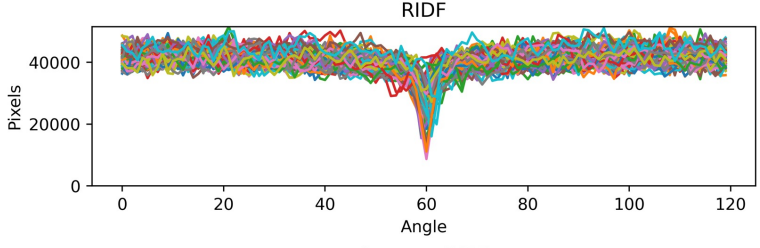
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

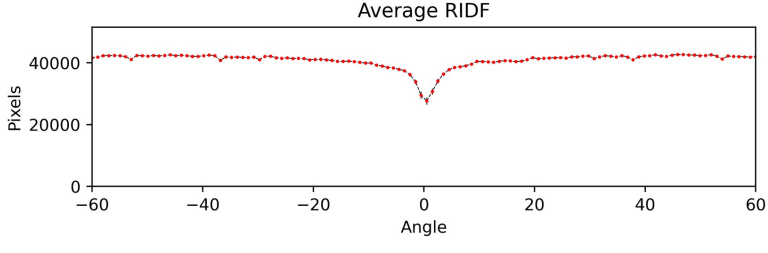
Navigation stats: RMSD error: 48.39; RMSD/dist: 0.121; TD: 9238; p90: 8; p50: 4; complete: 0

100%





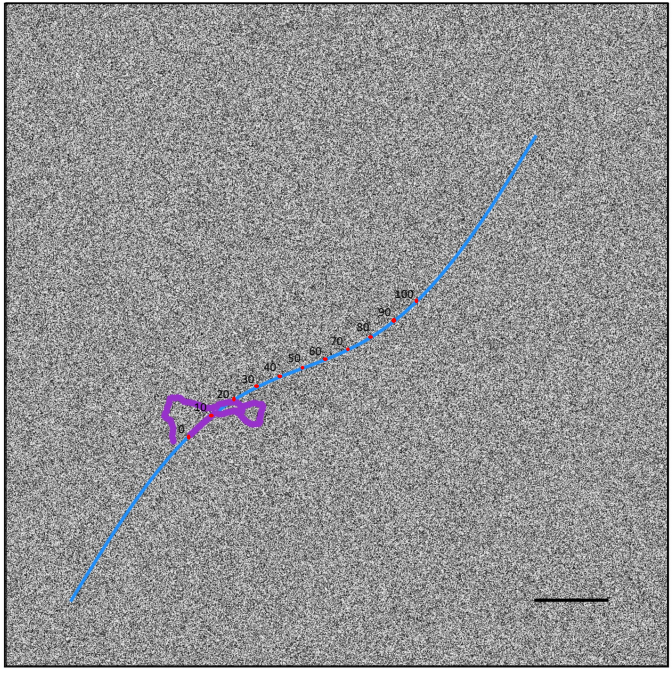


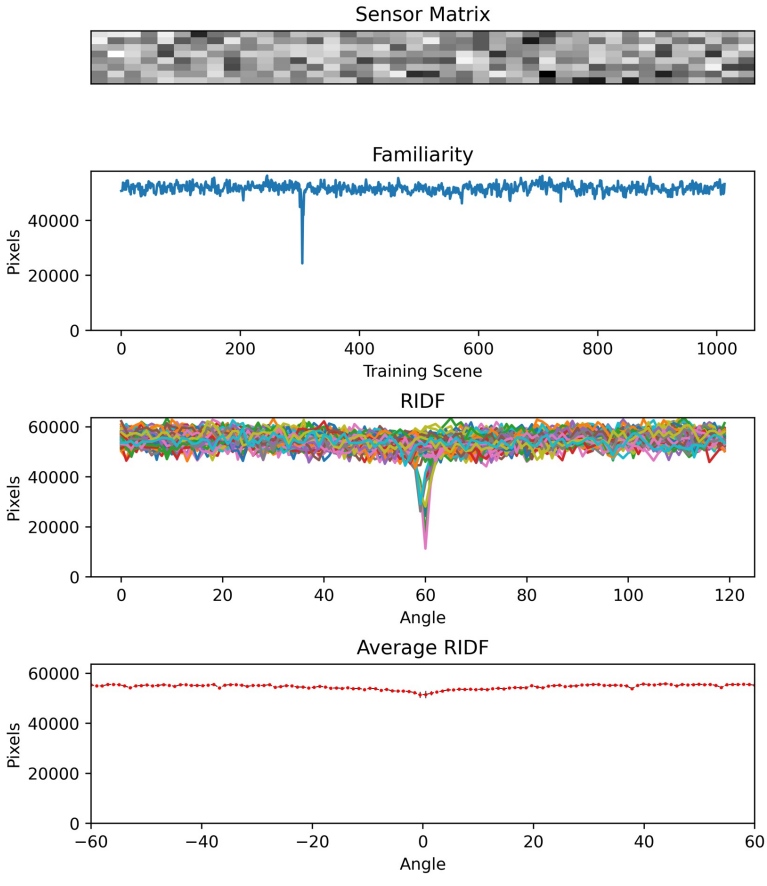


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 81.83; RMSD/dist: 0.205; TD: 8945; p90: 6; p50: 4; complete: 0

10%

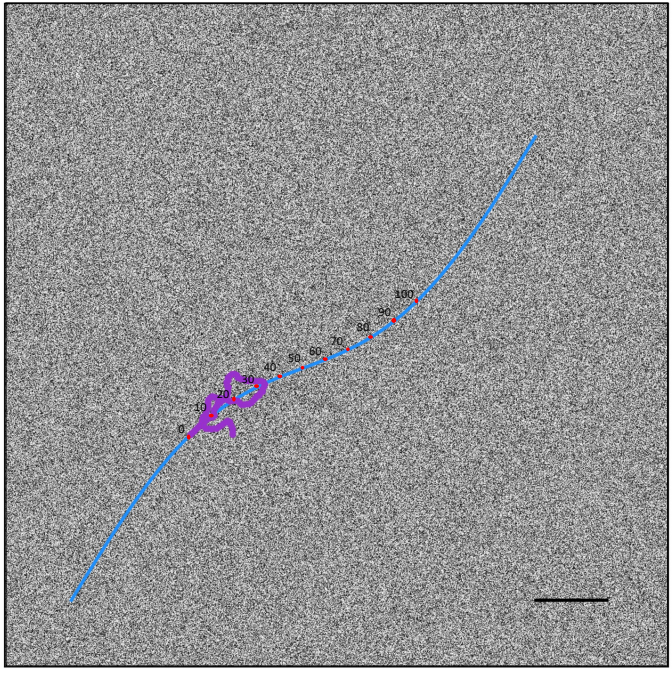


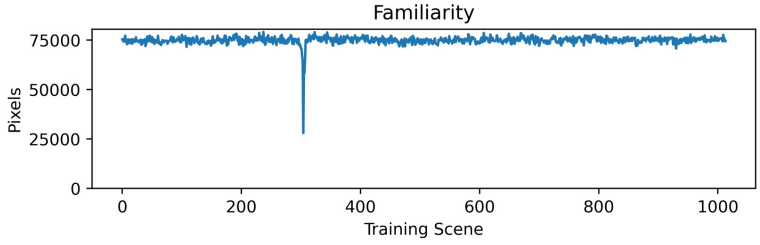


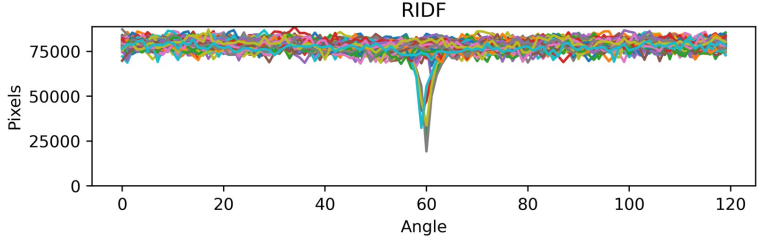
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

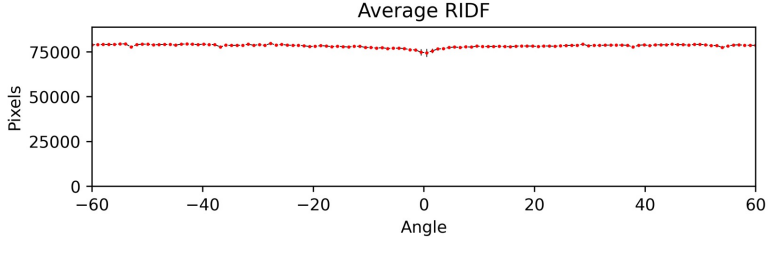
Navigation stats: RMSD error: 2362.46; RMSD/dist: 5.906; TD: 192; p90: 2; p50: 2; complete: 0

10%





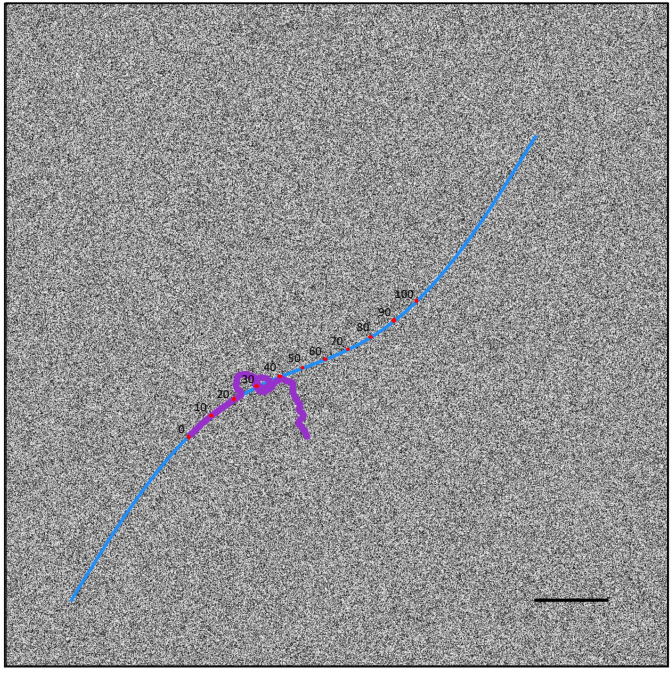


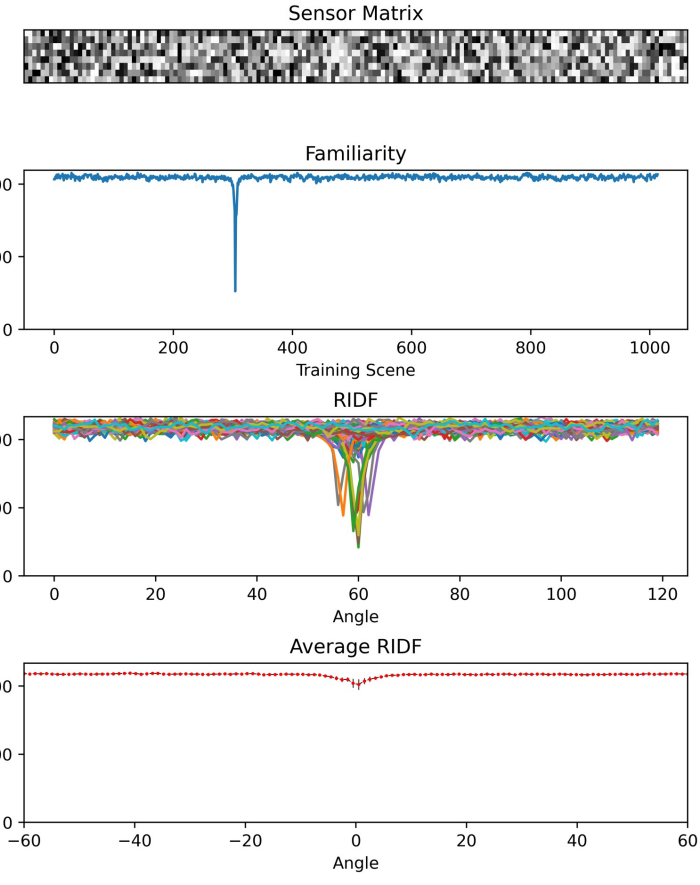


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1323.24; RMSD/dist: 3.308; TD: 216; p90: 2; p50: 2; complete: 0

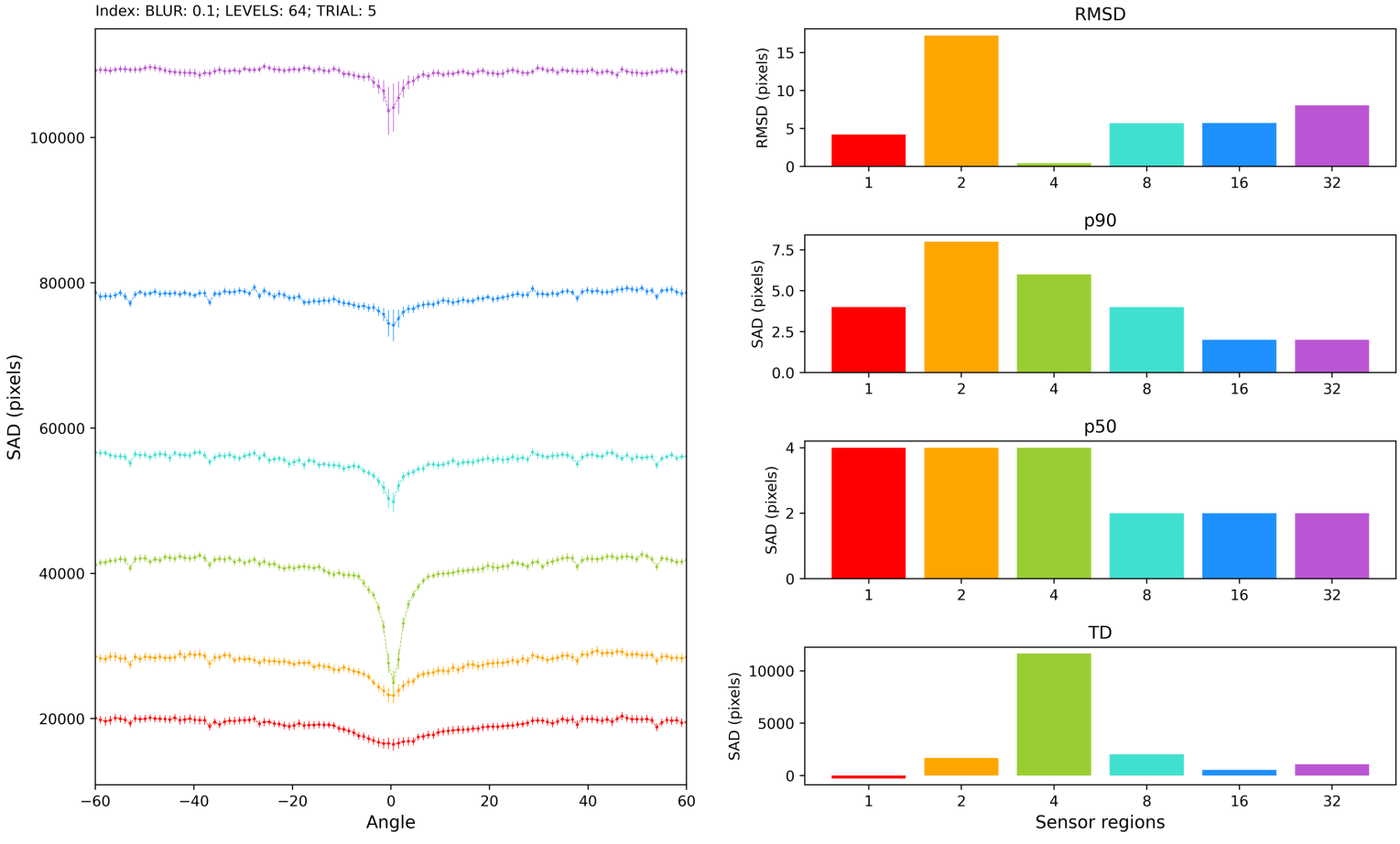
20%



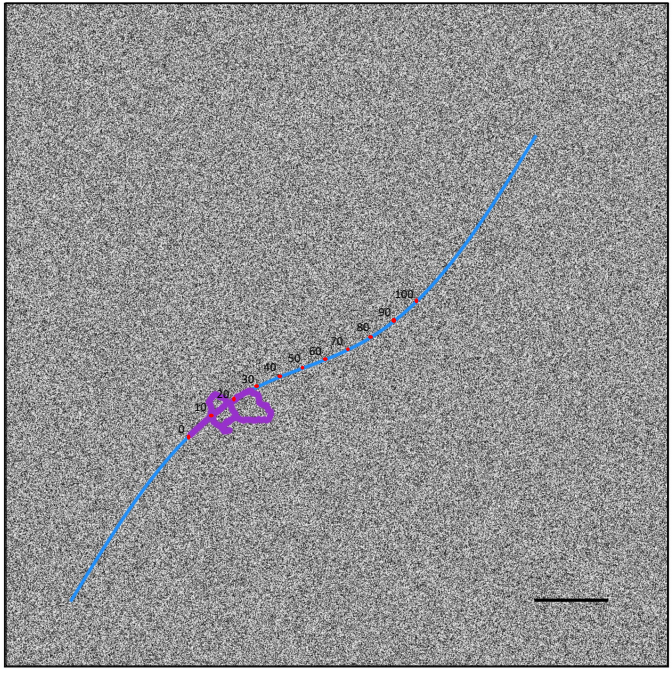


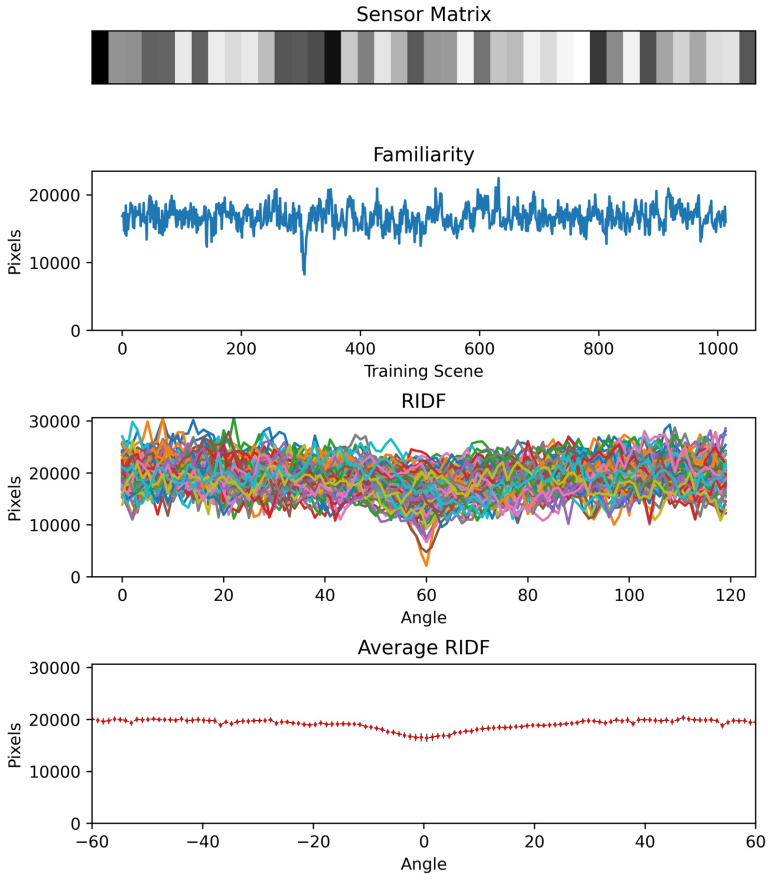
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1955.14; RMSD/dist: 4.888; TD: 3333; p90: 6; p50: 2; complete: 0


Index: BLUR: 0.1; LEVELS: 64; TRIAL: 5
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
15
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
4
2
TD
10000
5000
Sensor regions

20%

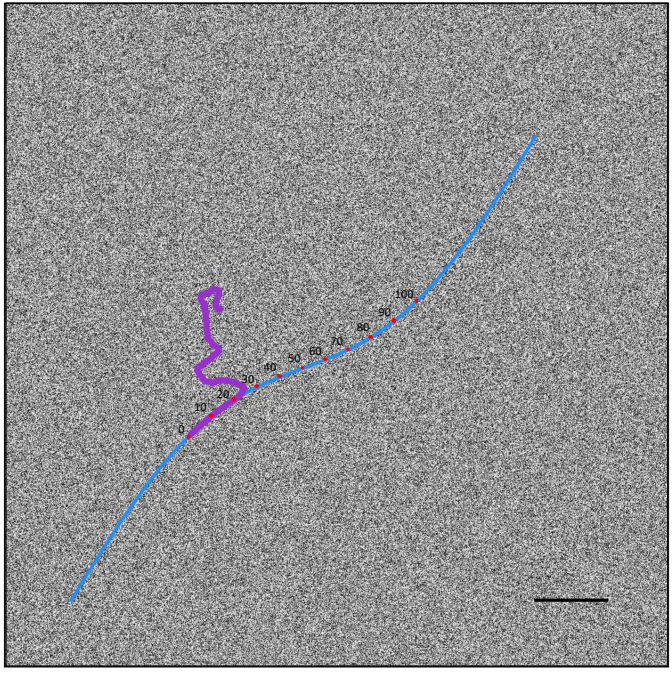


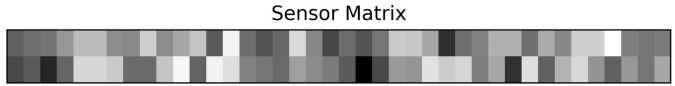


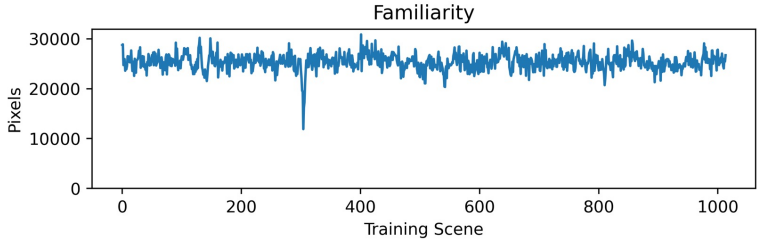
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

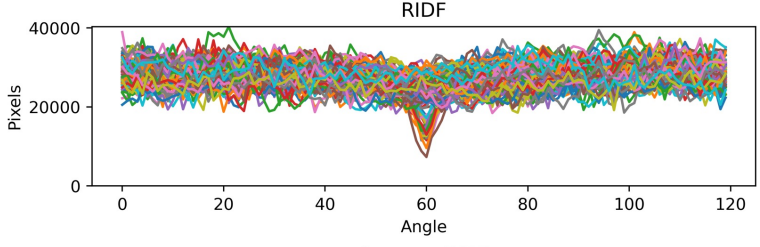
Navigation stats: RMSD error: 1674.59; RMSD/dist: 4.186; TD: -272; p90: 4; p50: 4; complete: 0

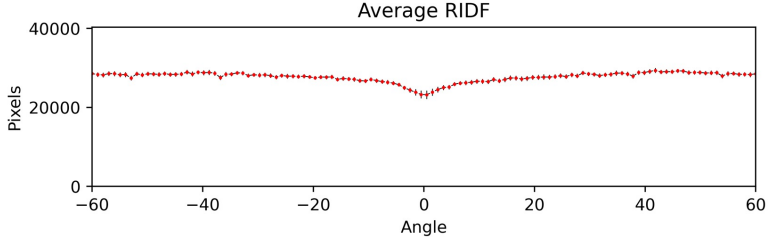
20%







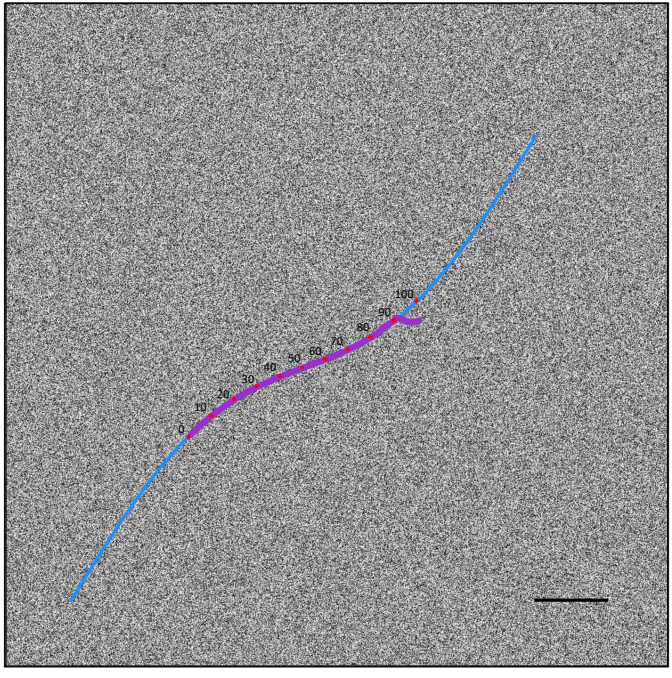


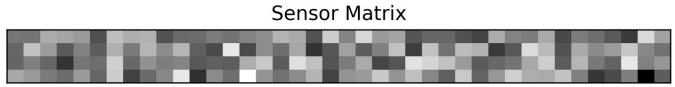


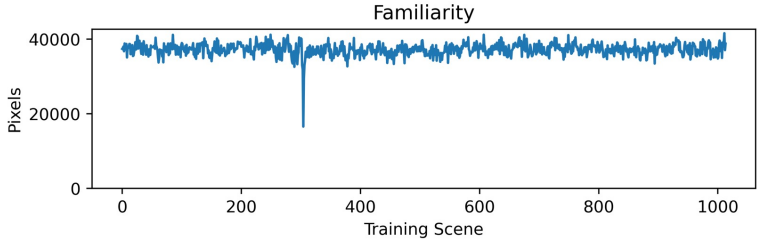
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

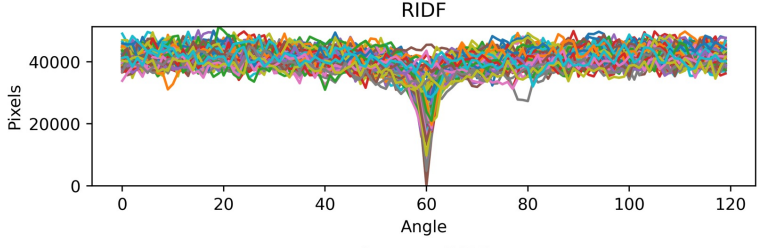
Navigation stats: RMSD error: 6901.15; RMSD/dist: 17.253; TD: 1690; p90: 8; p50: 4; complete: 0

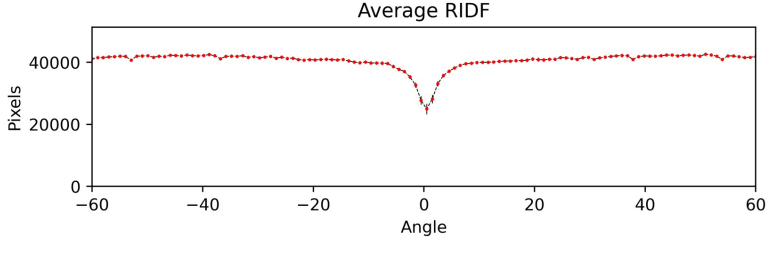
90%







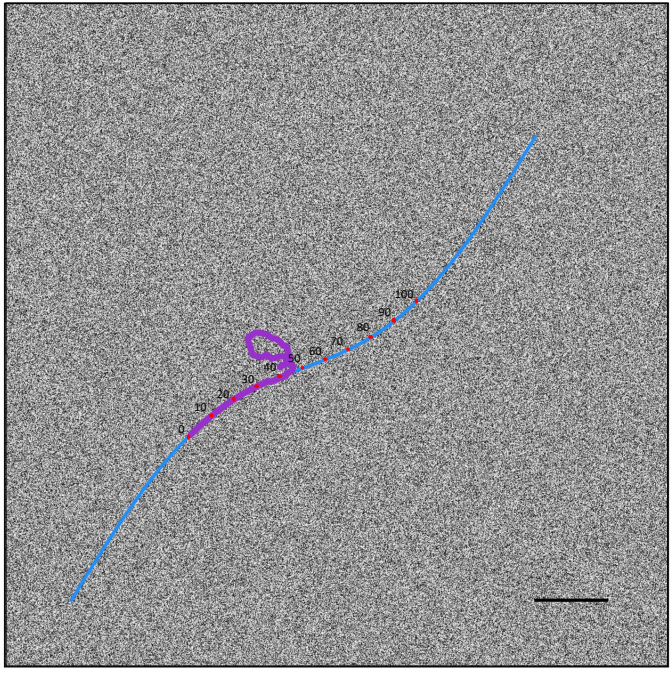


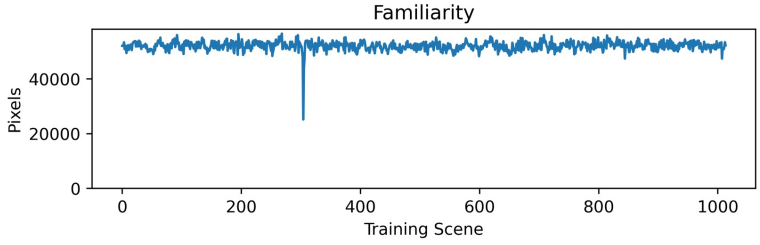


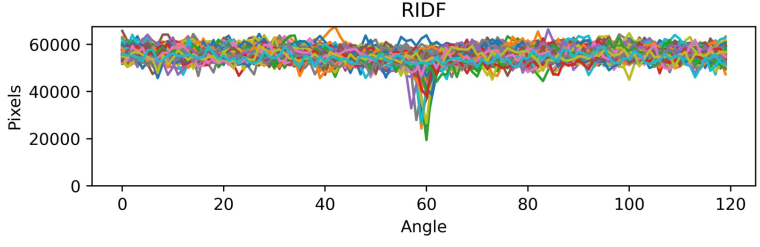
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

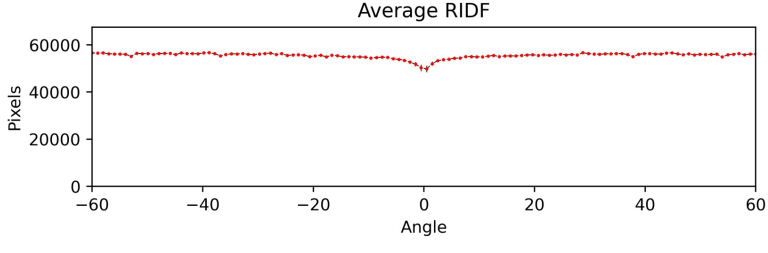
Navigation stats: RMSD error: 164.92; RMSD/dist: 0.412; TD: 11650; p90: 6; p50: 4; complete: 0

30%





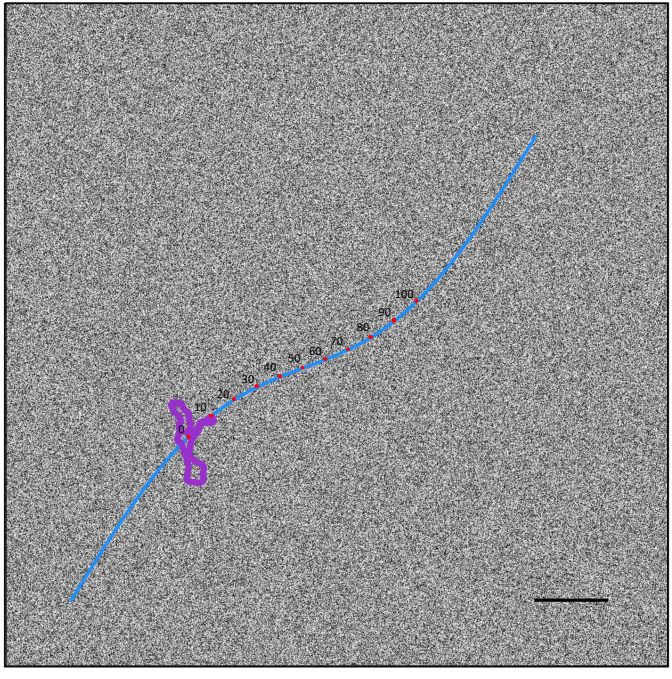


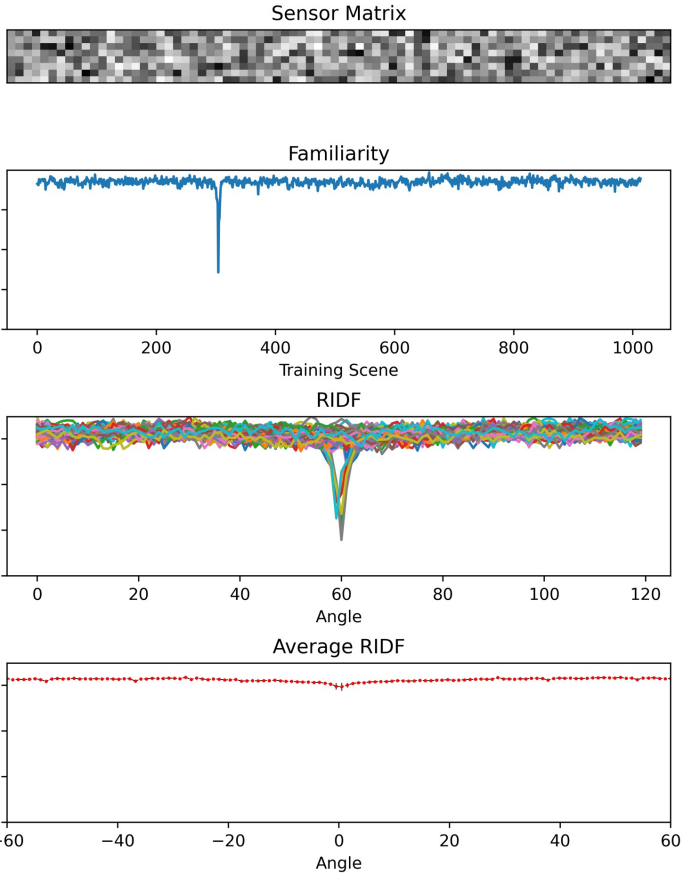


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2277.45; RMSD/dist: 5.694; TD: 2018; p90: 4; p50: 2; complete: 0

0%

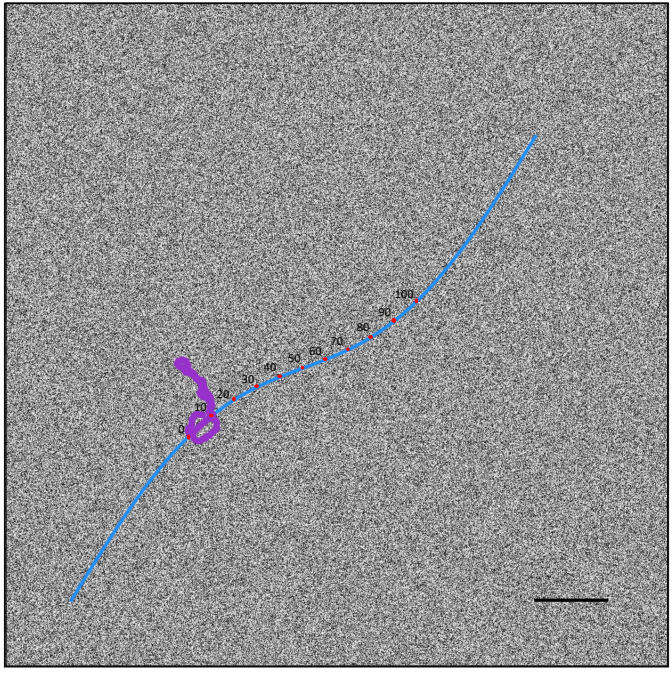


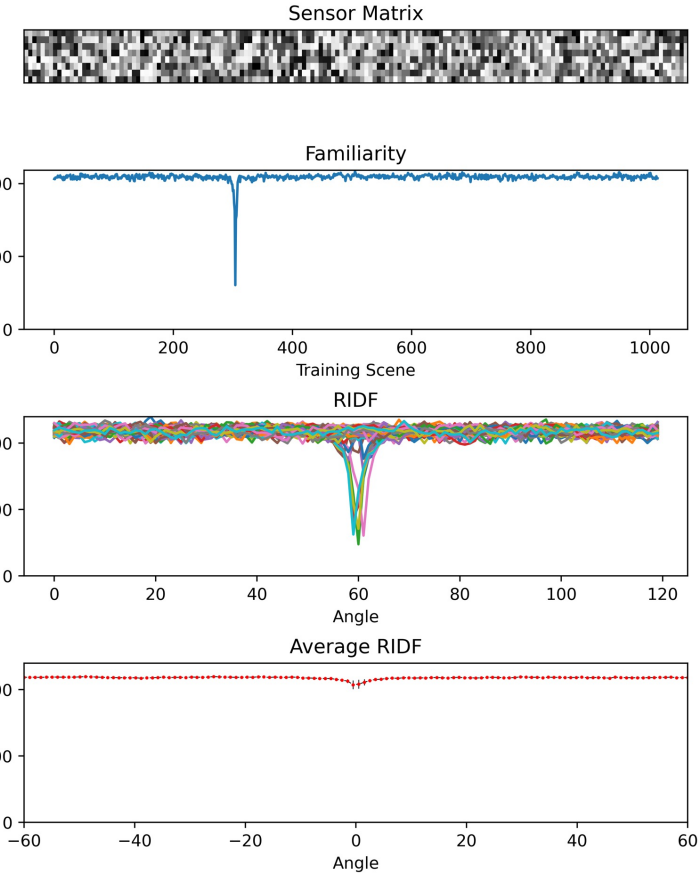


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2290.38; RMSD/dist: 5.726; TD: 543; p90: 2; p50: 2; complete: 0

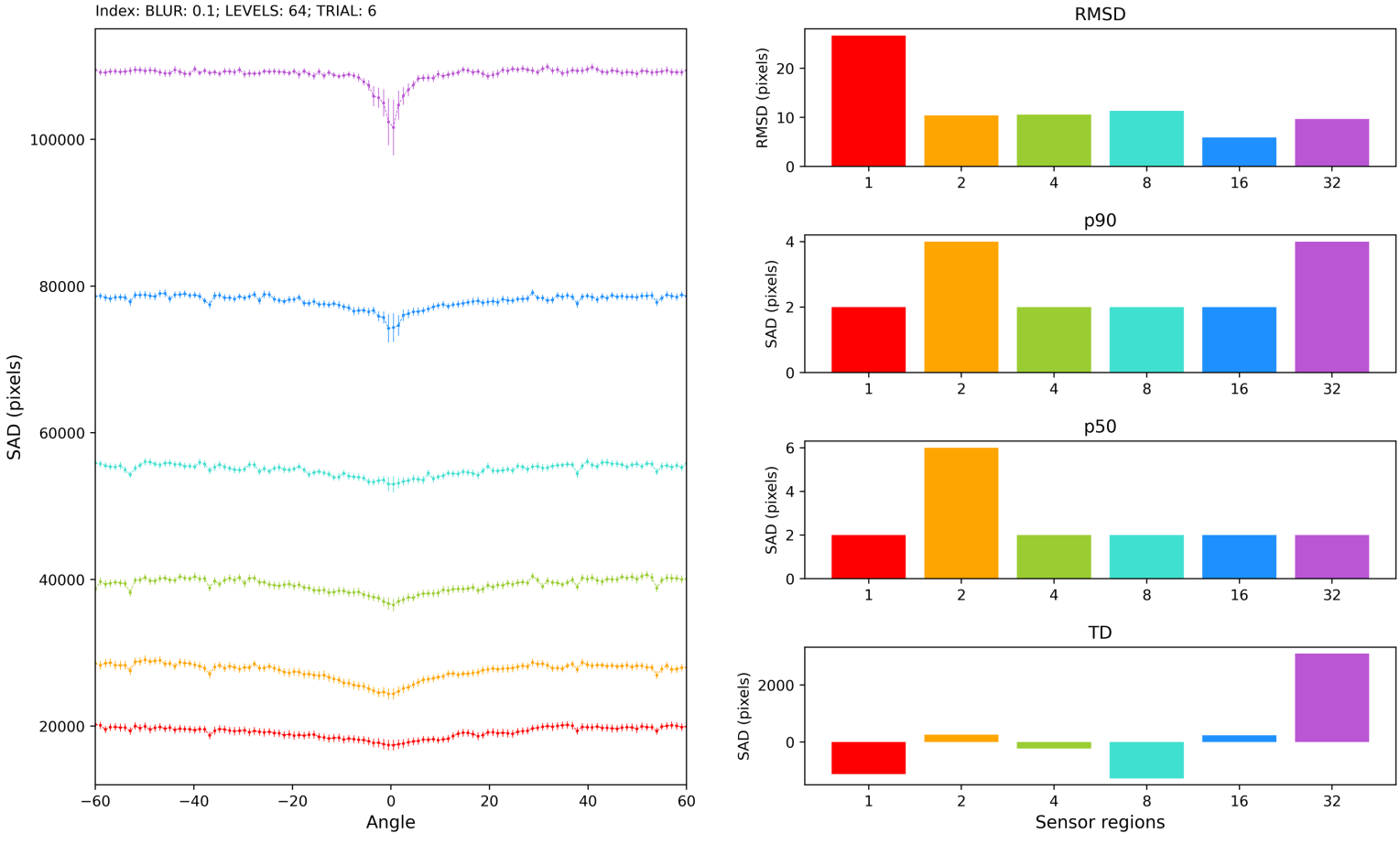
10%



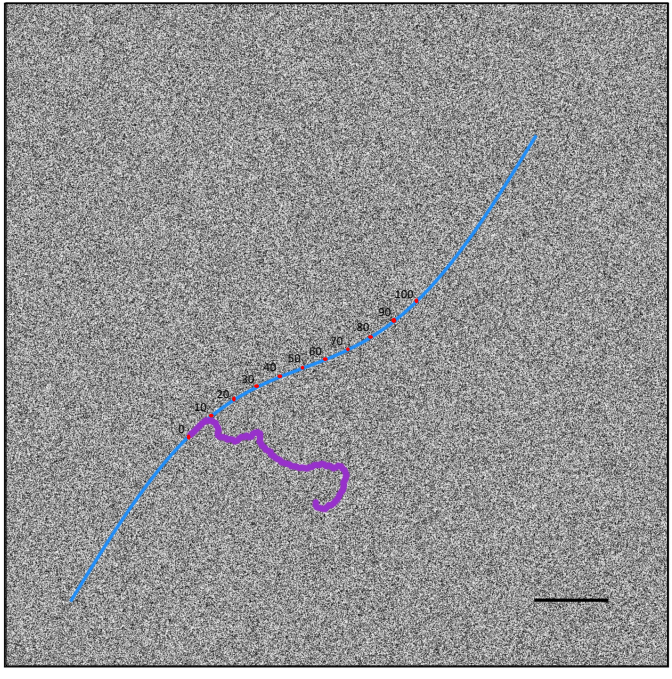


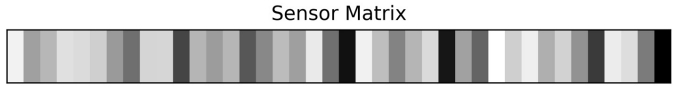
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

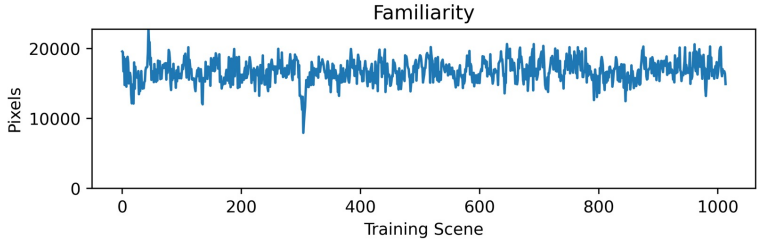
Navigation stats: RMSD error: 3212.68; RMSD/dist: 8.032; TD: 1094; p90: 2; p50: 2; complete: 0

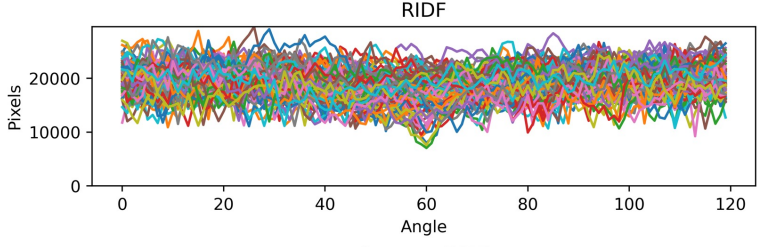

Index: BLUR: 0.1; LEVELS: 64; TRIAL: 6
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
4
2
0
p50
6
TD
2000
Sensor regions

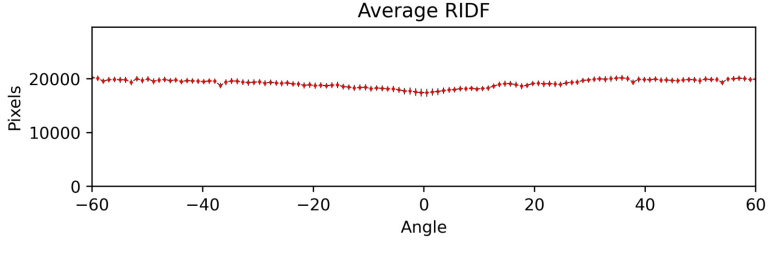
0%







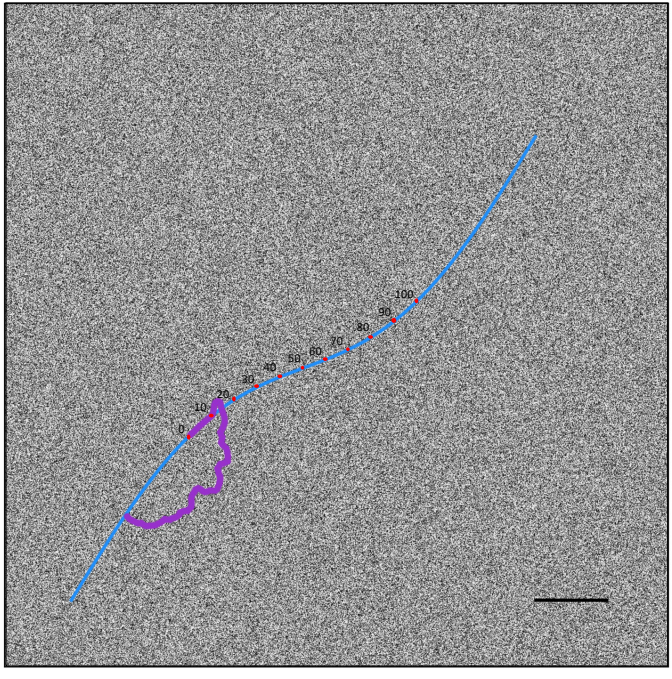


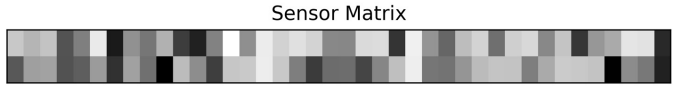


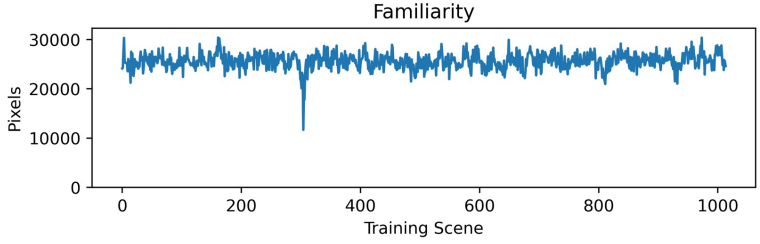
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

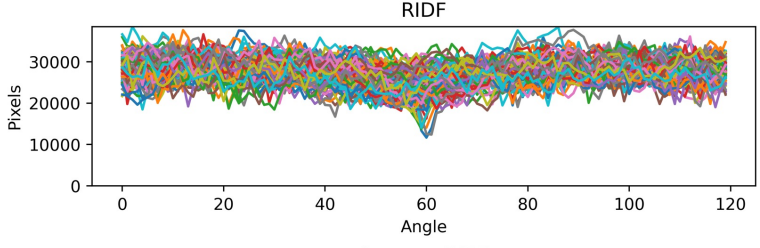
Navigation stats: RMSD error: 10686.99; RMSD/dist: 26.717; TD: -1128; p90: 2; p50: 2; complete: 0

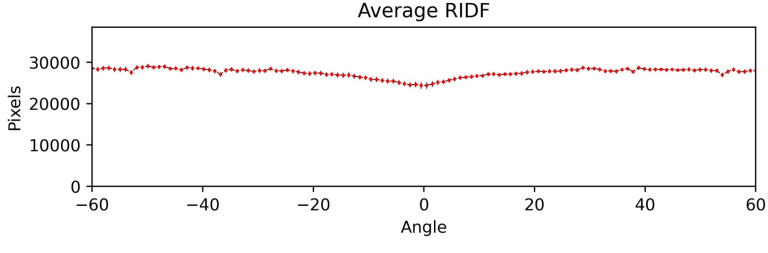
10%







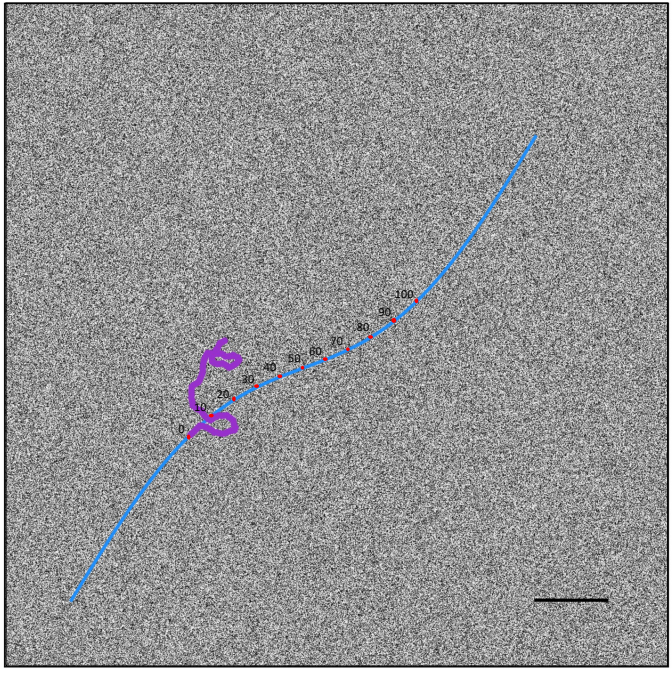


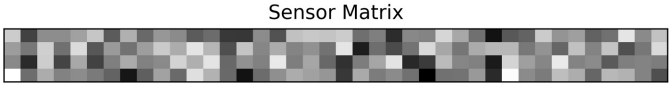


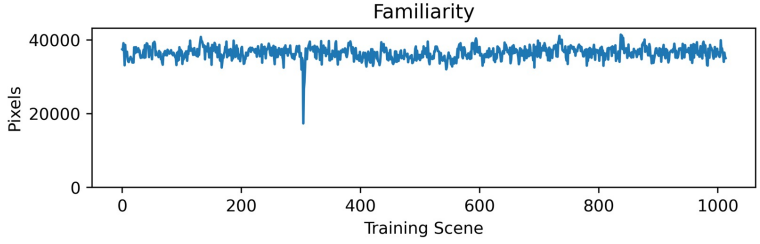
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

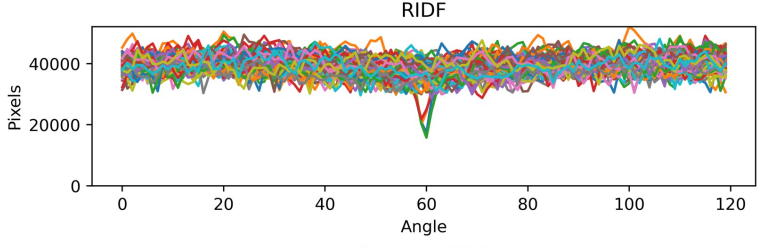
Navigation stats: RMSD error: 4153.94; RMSD/dist: 10.385; TD: 253; p90: 4; p50: 6; complete: 0

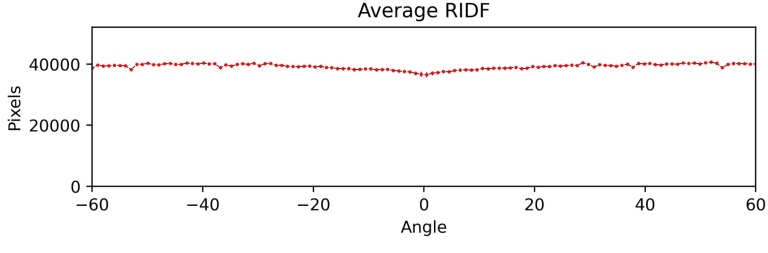
0%











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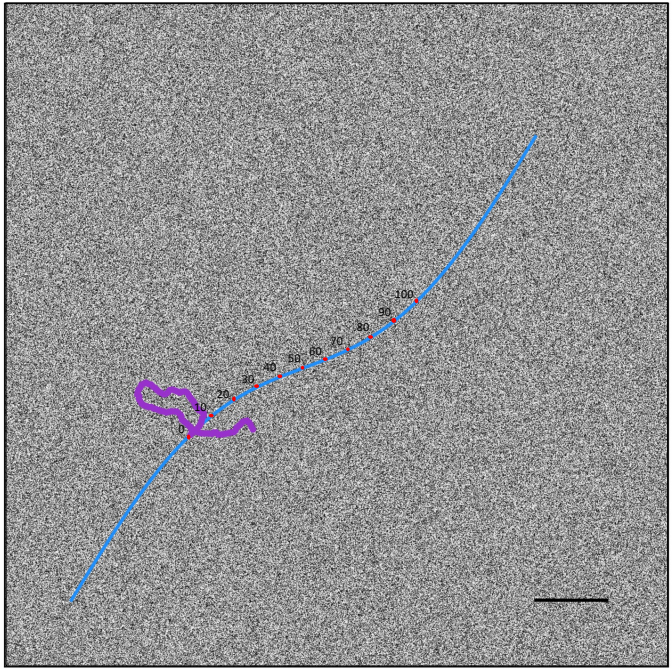
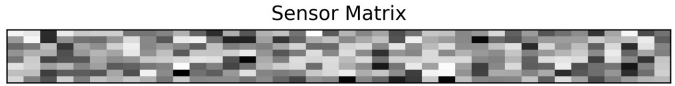
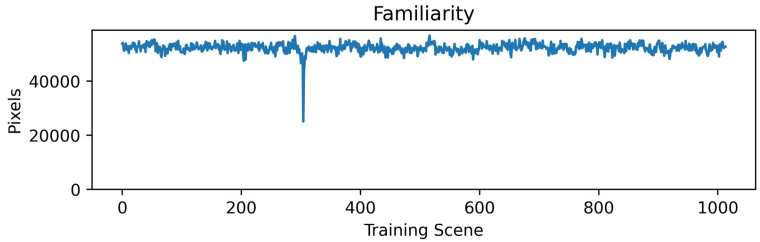
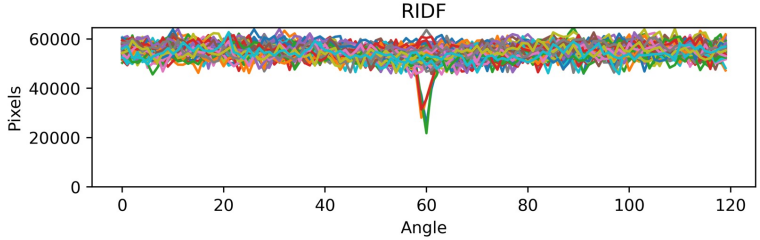
Navigation stats: RMSD error: 4230.98; RMSD/dist: 10.577; TD: -228; p90: 2; p50: 2; complete: 0

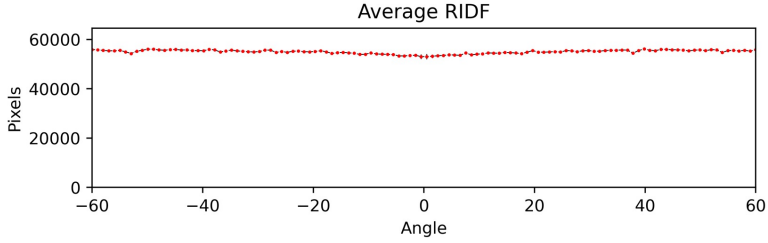
0%







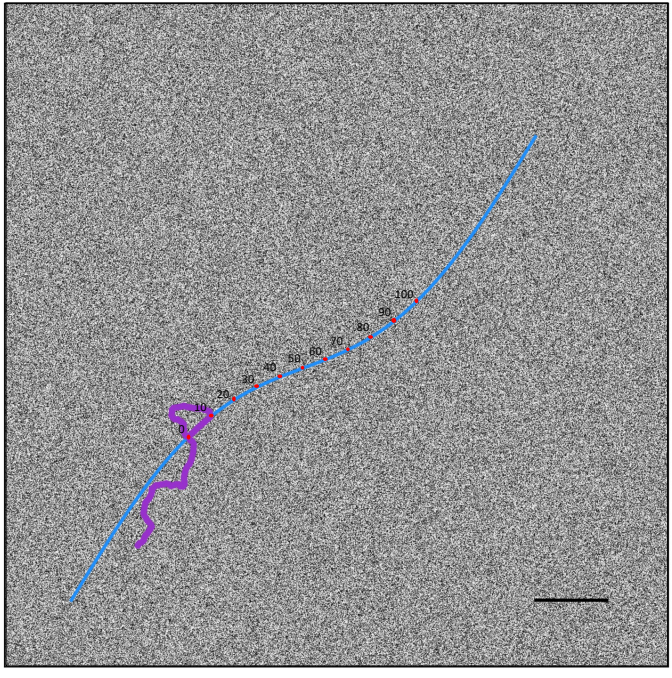


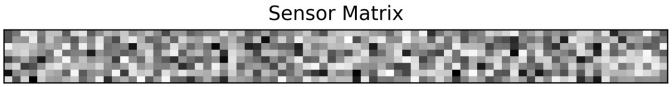


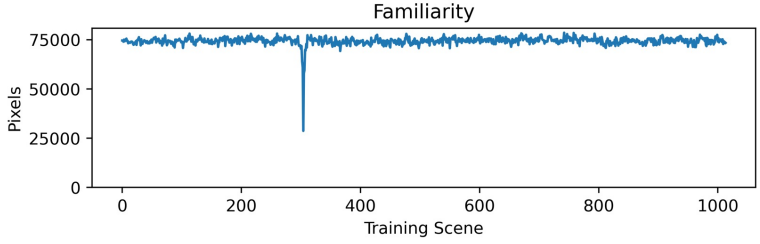
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

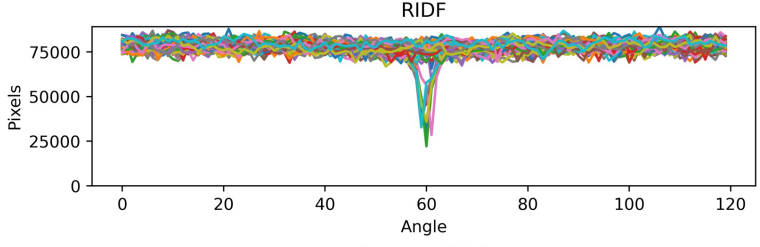
Navigation stats: RMSD error: 4532.43; RMSD/dist: 11.331; TD: -1284; p90: 2; p50: 2; complete: 0

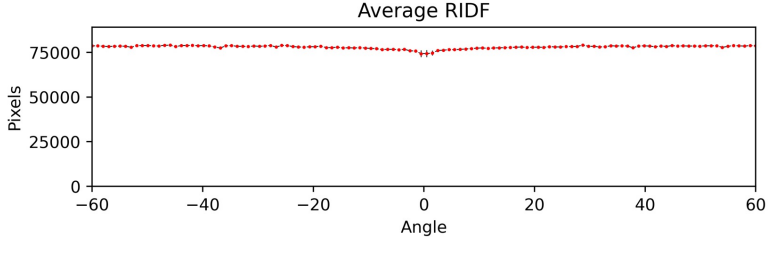
10%







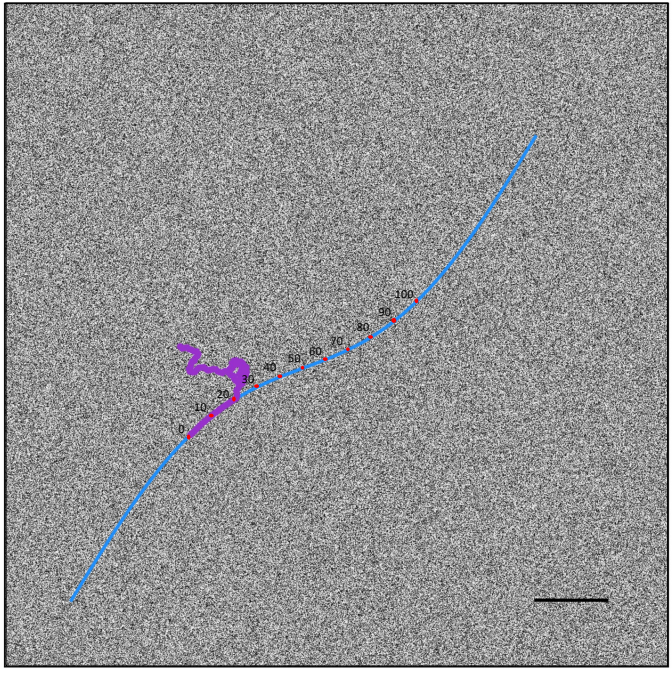


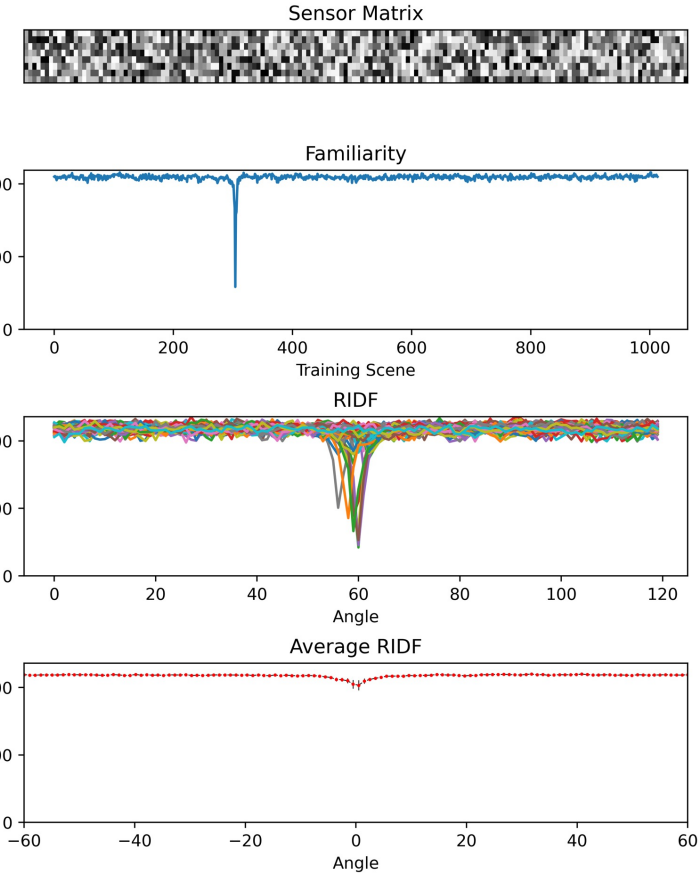


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2355.02; RMSD/dist: 5.888; TD: 232; p90: 2; p50: 2; complete: 0

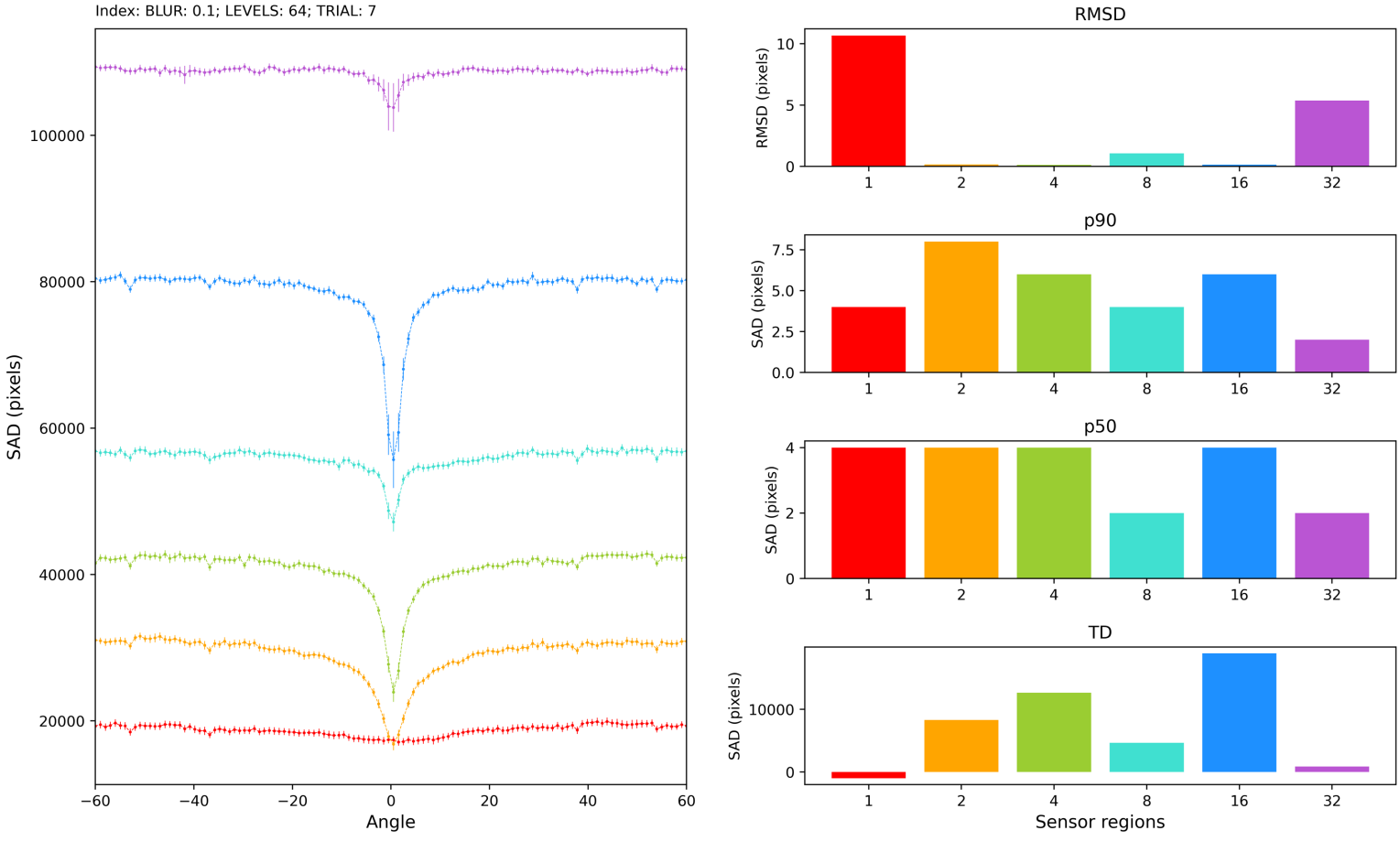
20%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3859.13; RMSD/dist: 9.648; TD: 3107; p90: 4; p50: 2; complete: 0


Index: BLUR: 0.1; LEVELS: 64; TRIAL: 7
SAD (pixels)
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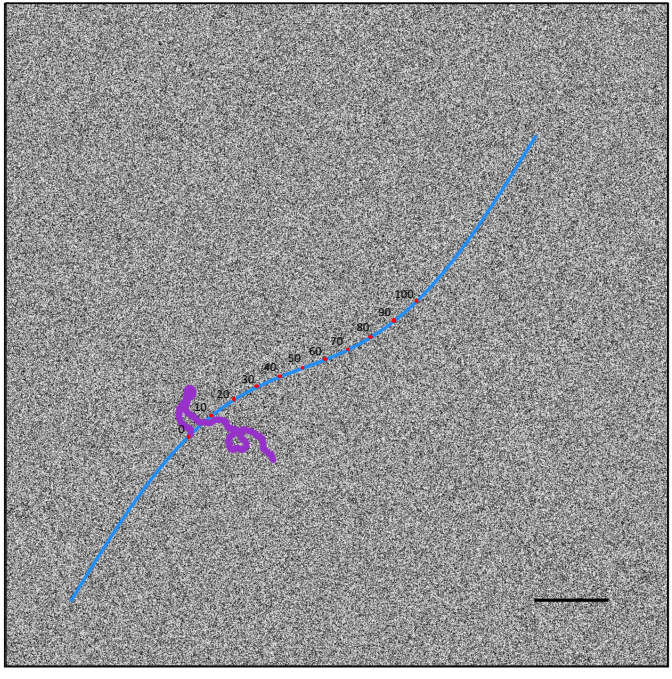
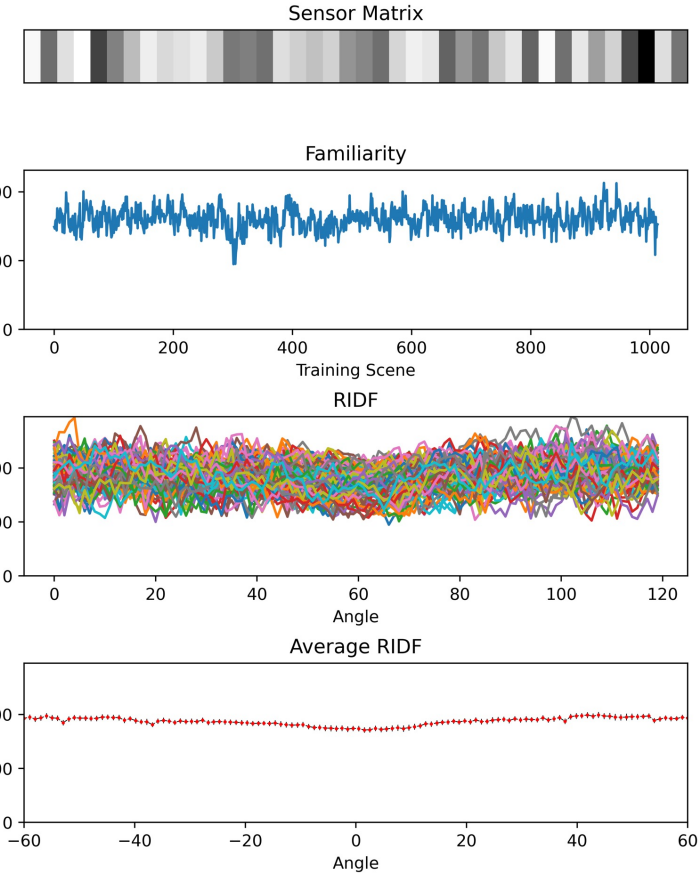
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
4
2
TD
10000
Sensor regions

0%

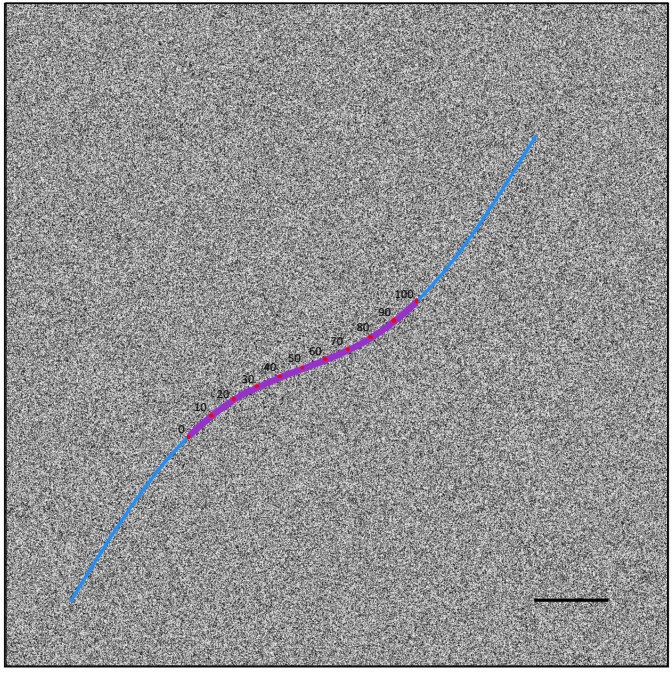


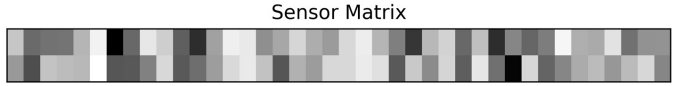


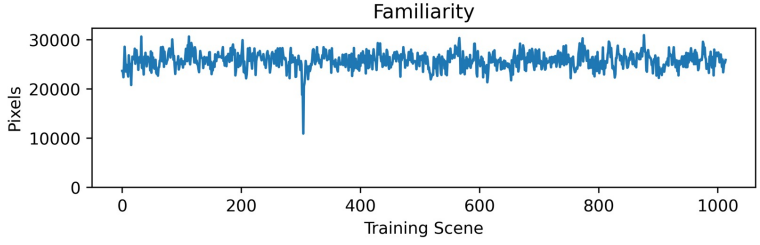
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

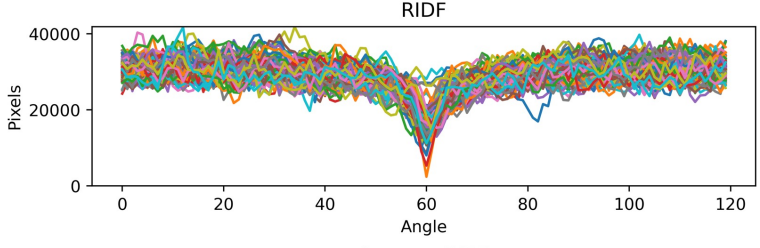
Navigation stats: RMSD error: 4273.24; RMSD/dist: 10.683; TD: -988; p90: 4; p50: 4; complete: 0

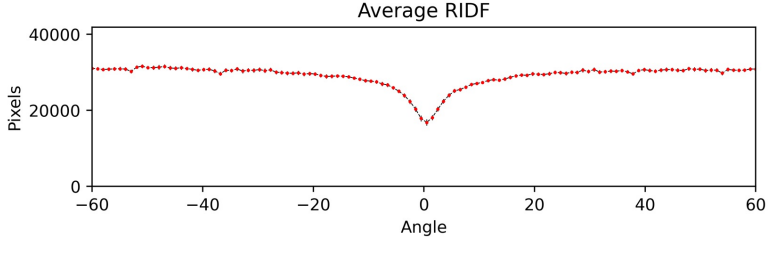
100%







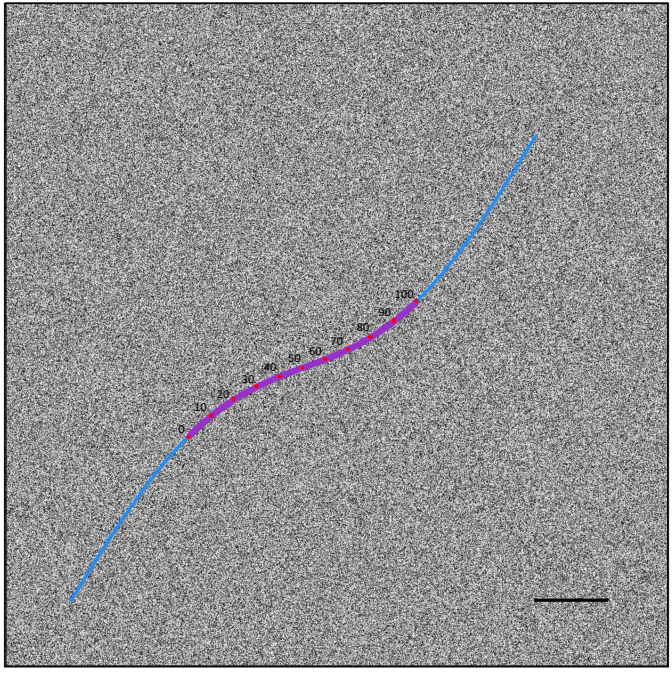


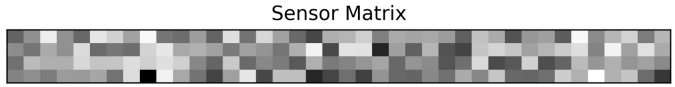


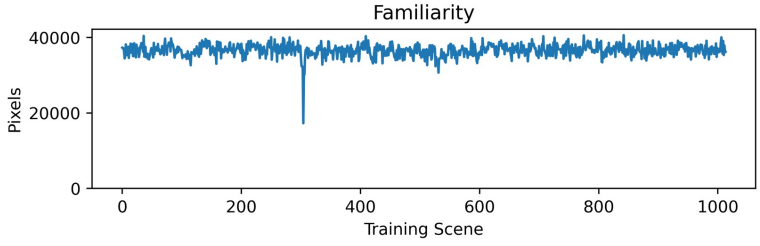
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

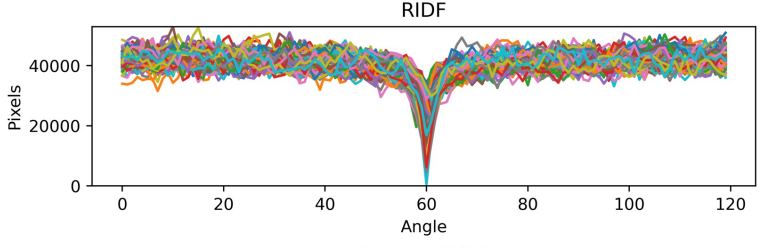
Navigation stats: RMSD error: 56.35; RMSD/dist: 0.141; TD: 8302; p90: 8; p50: 4; complete: 0

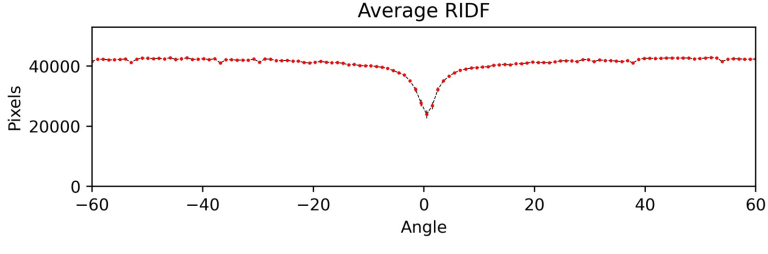
100%







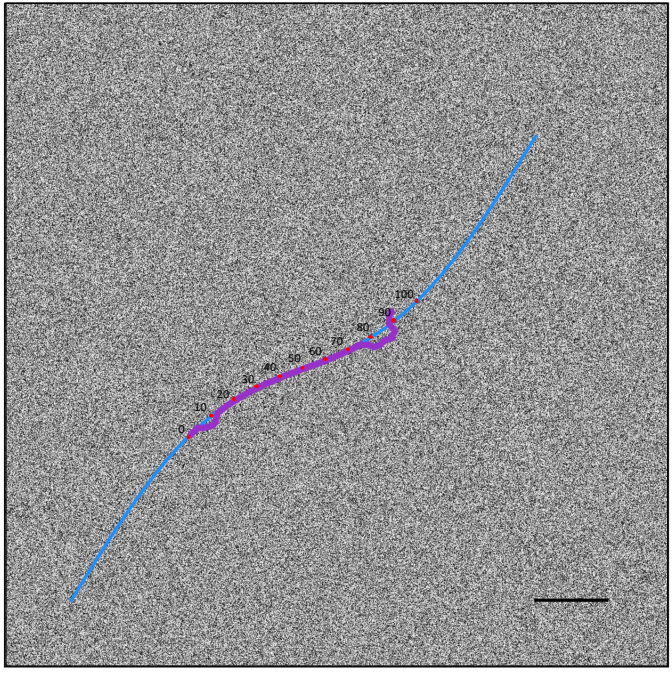


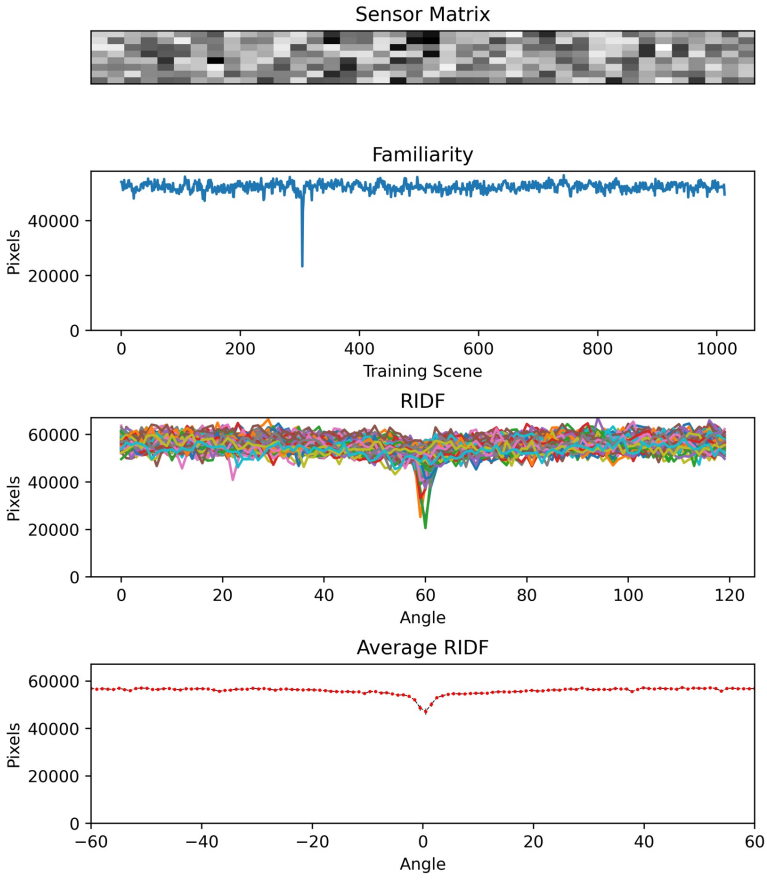


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 46.15; RMSD/dist: 0.115; TD: 12665; p90: 6; p50: 4; complete: 0

60%

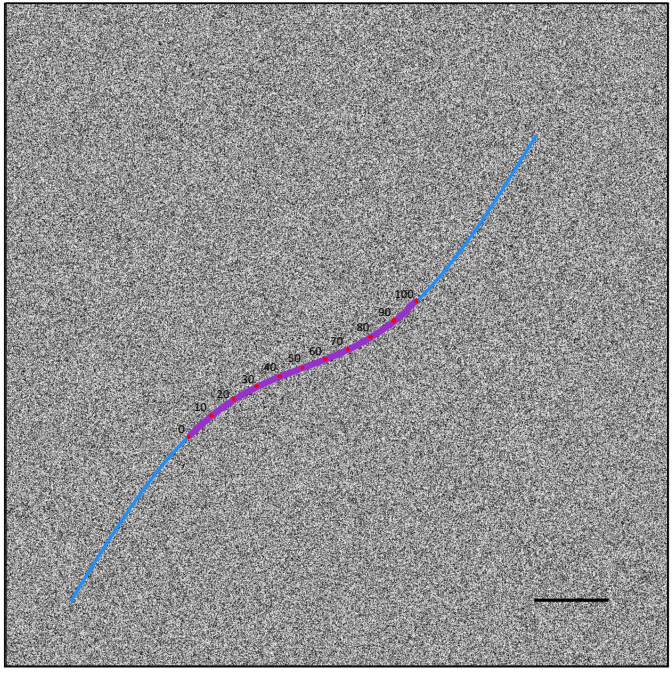


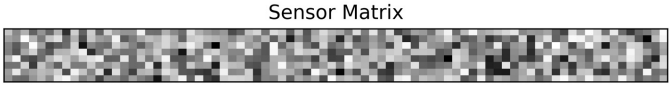


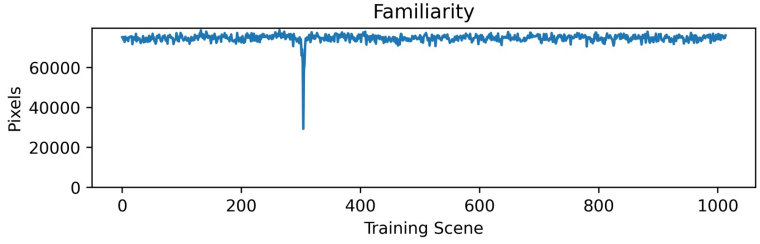
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

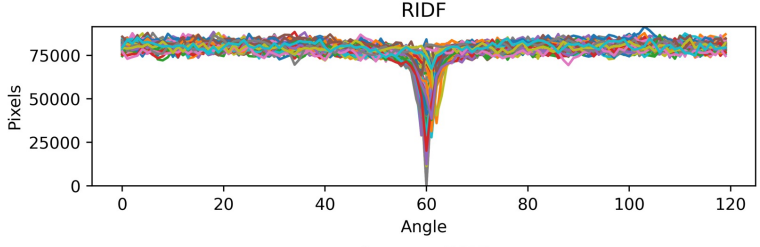
Navigation stats: RMSD error: 424.40; RMSD/dist: 1.061; TD: 4658; p90: 4; p50: 2; complete: 0

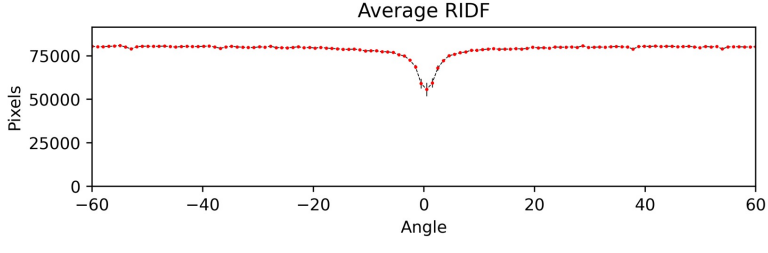
100%







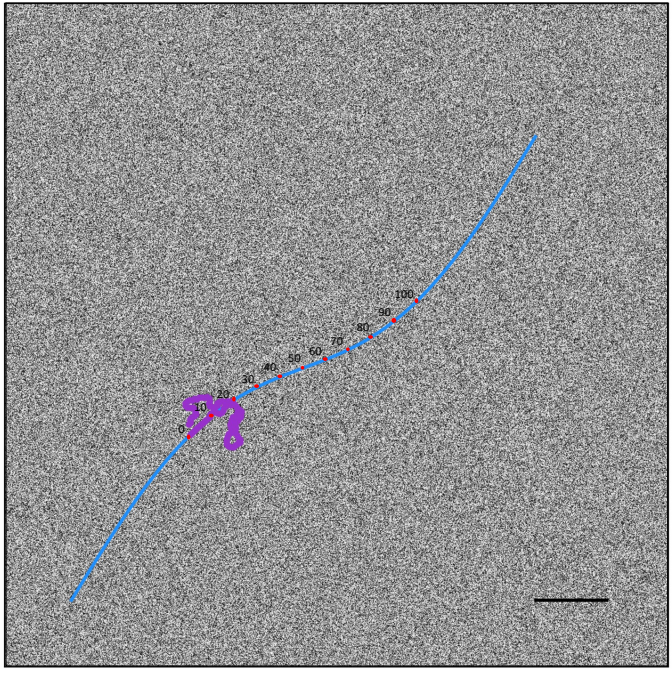


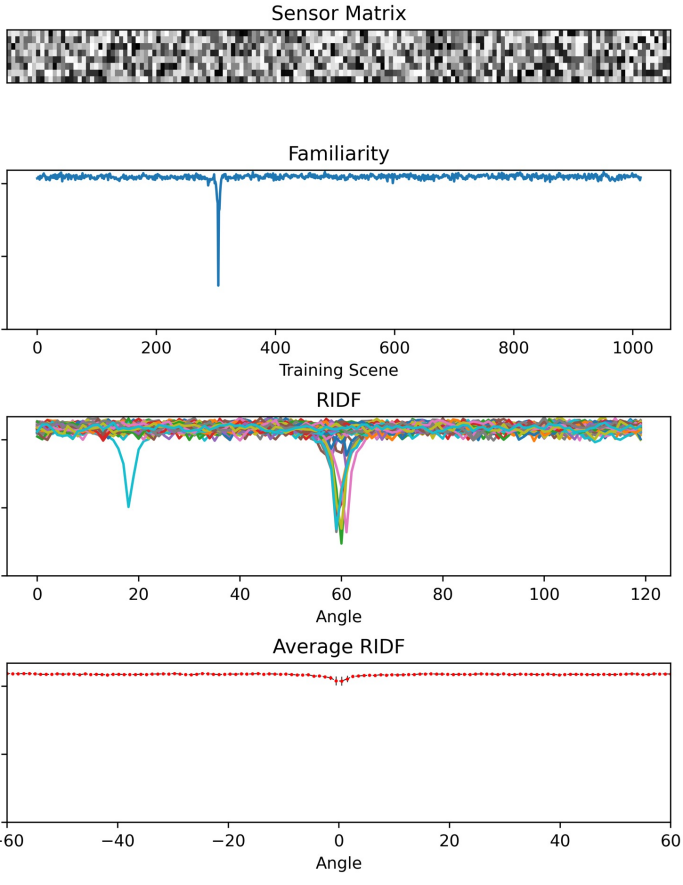


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 54.28; RMSD/dist: 0.136; TD: 18939; p90: 6; p50: 4; complete: 0

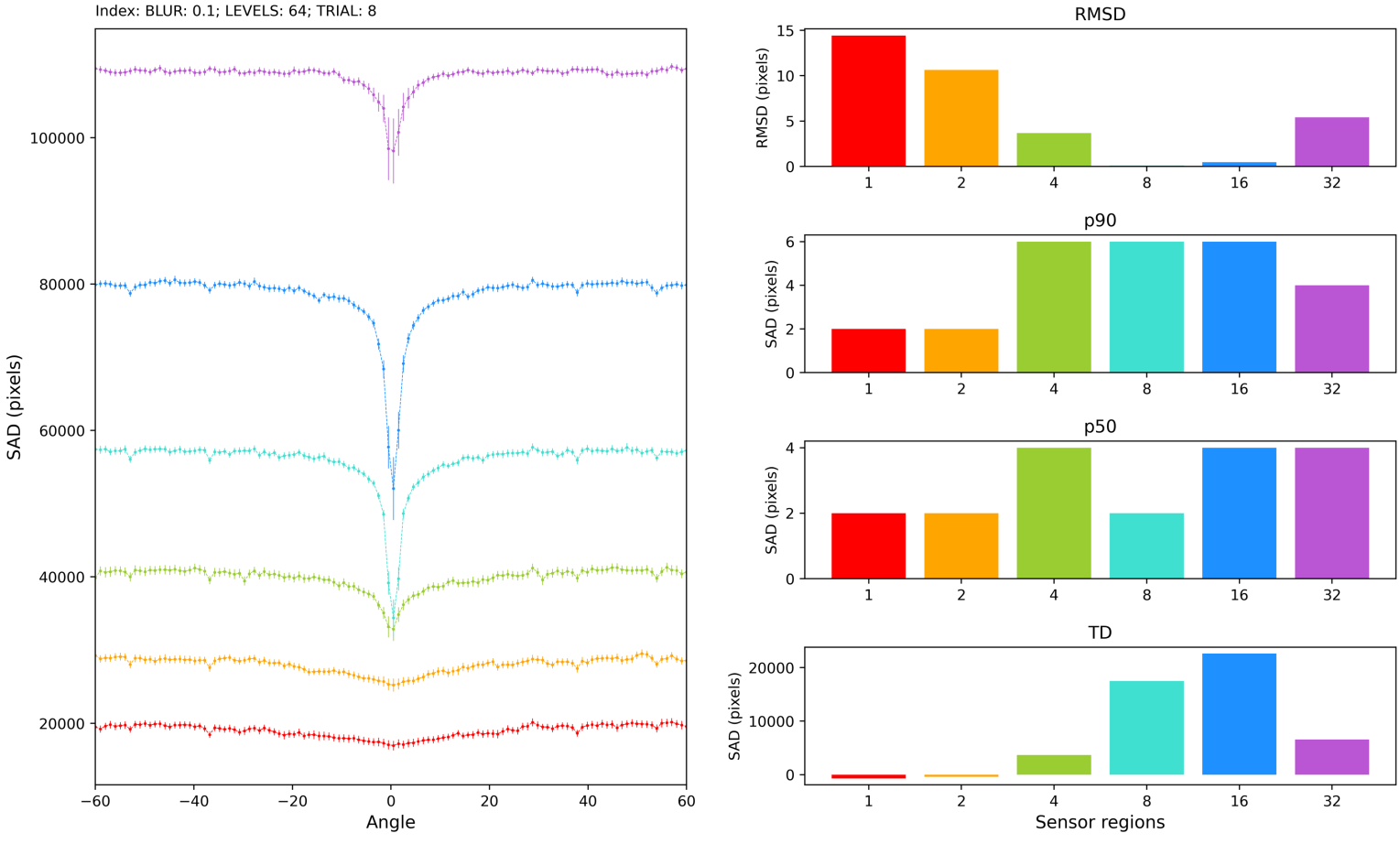
10%



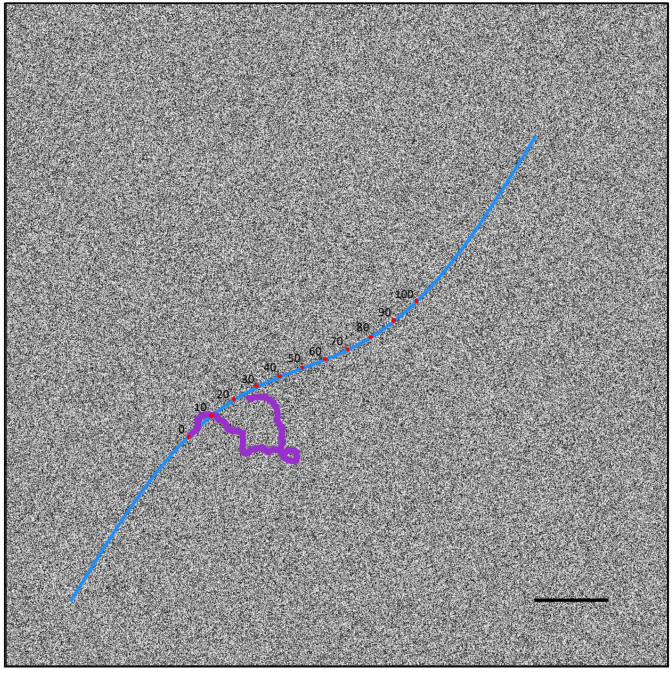


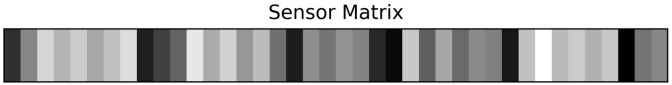
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

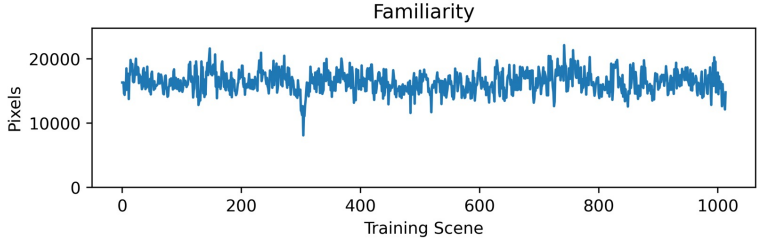
Navigation stats: RMSD error: 2145.36; RMSD/dist: 5.363; TD: 889; p90: 2; p50: 2; complete: 0

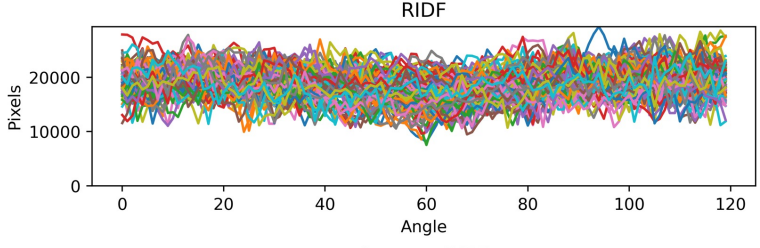

Index: BLUR: 0.1; LEVELS: 64; TRIAL: 8
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
15
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
6
4
2
0
p50
TD
20000
10000
Sensor regions

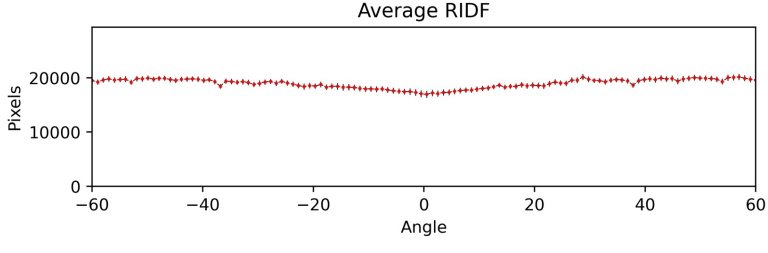
0%







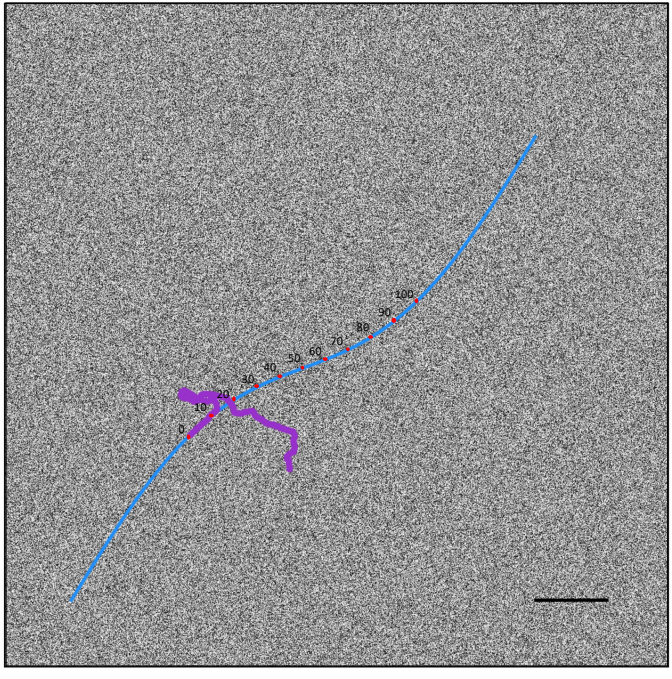


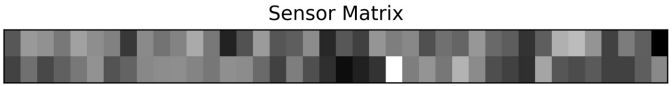


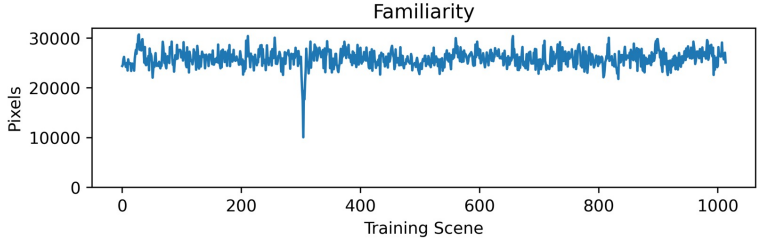
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

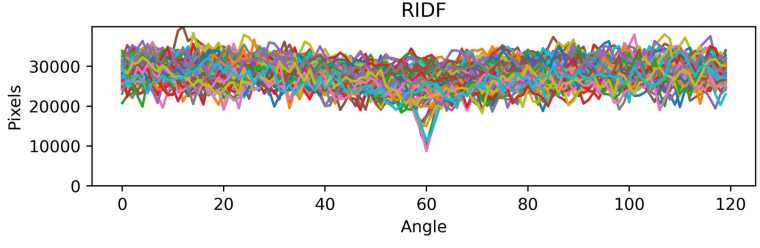
Navigation stats: RMSD error: 5774.42; RMSD/dist: 14.436; TD: -714; p90: 2; p50: 2; complete: 0

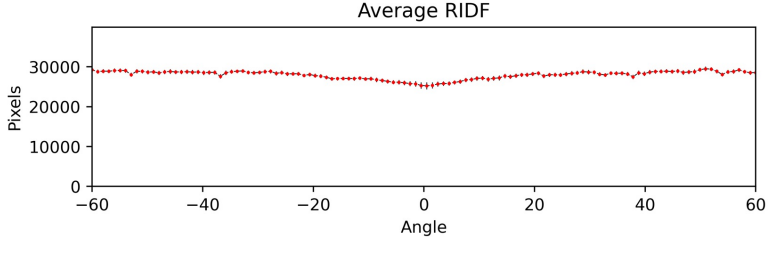
10%











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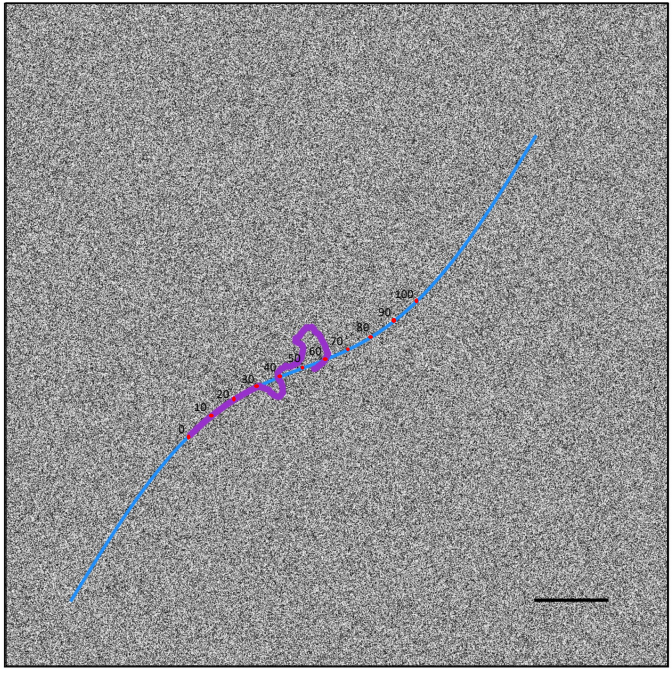
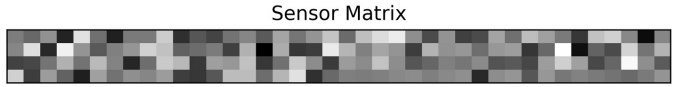
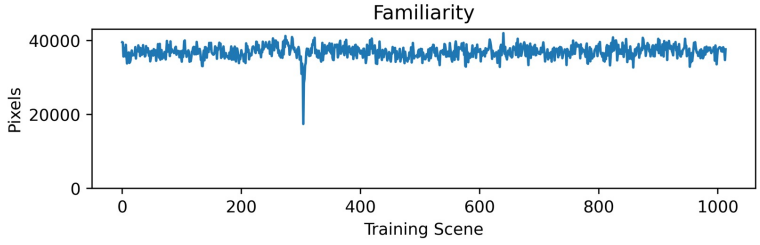
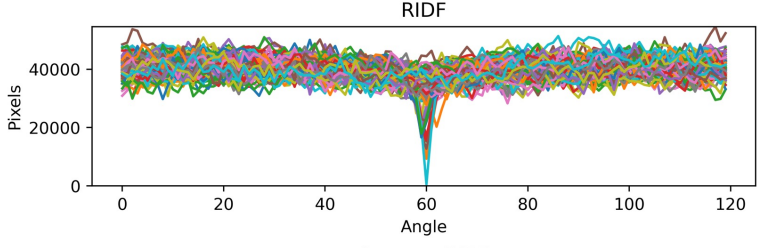
Navigation stats: RMSD error: 4251.52; RMSD/dist: 10.629; TD: -404; p90: 2; p50: 2; complete: 0

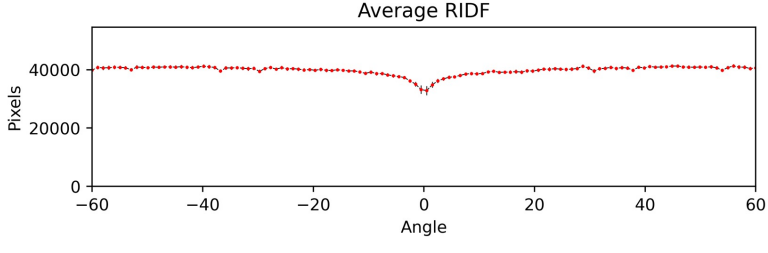
40%











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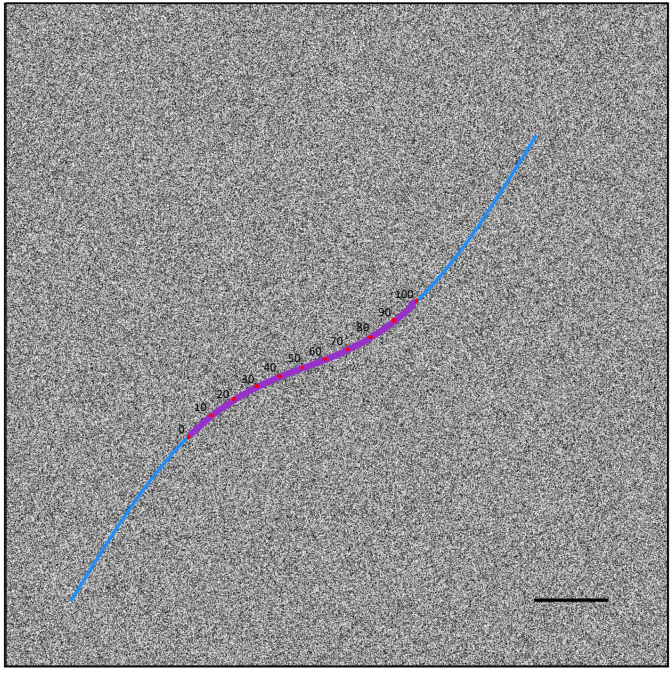
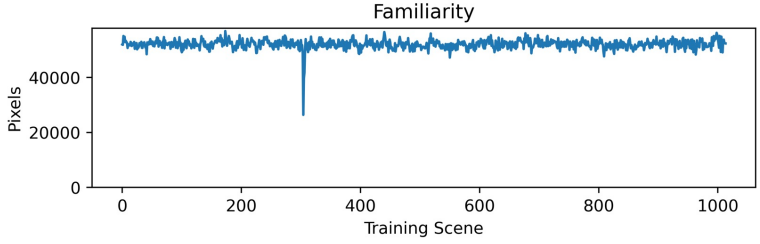
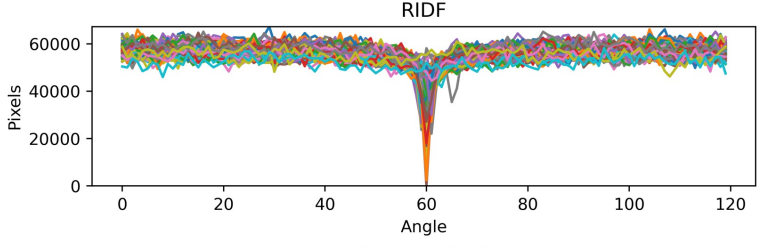
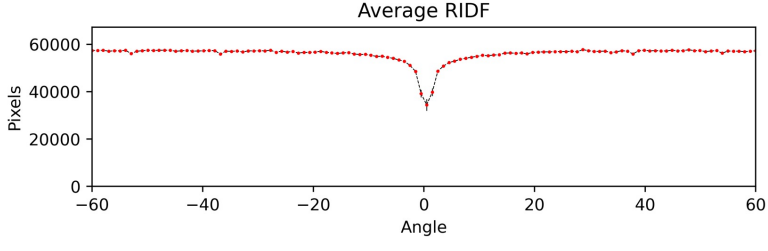
Navigation stats: RMSD error: 1469.59; RMSD/dist: 3.674; TD: 3654; p90: 6; p50: 4; complete: 0

100%





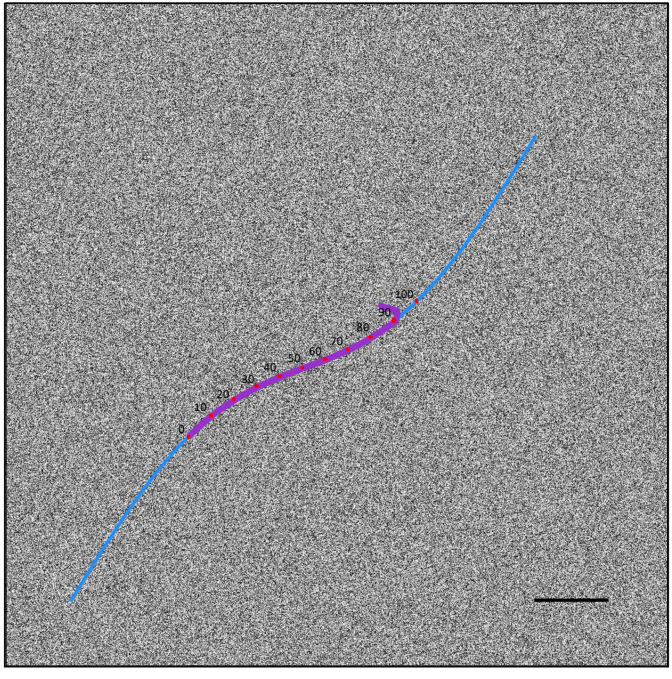


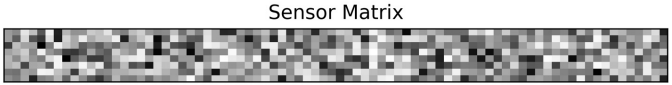


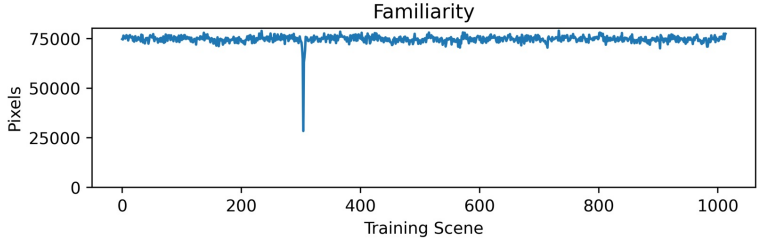
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

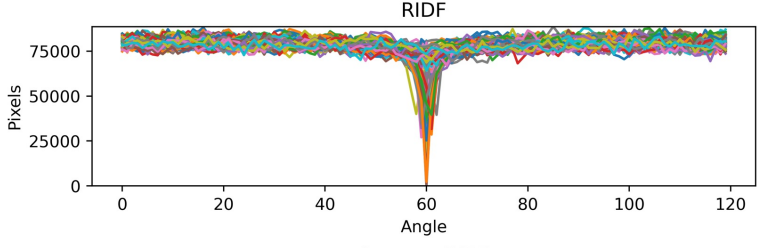
Navigation stats: RMSD error: 31.84; RMSD/dist: 0.080; TD: 17494; p90: 6; p50: 2; complete: 0

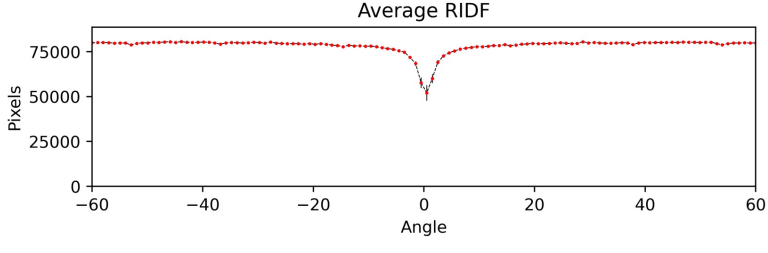
90%







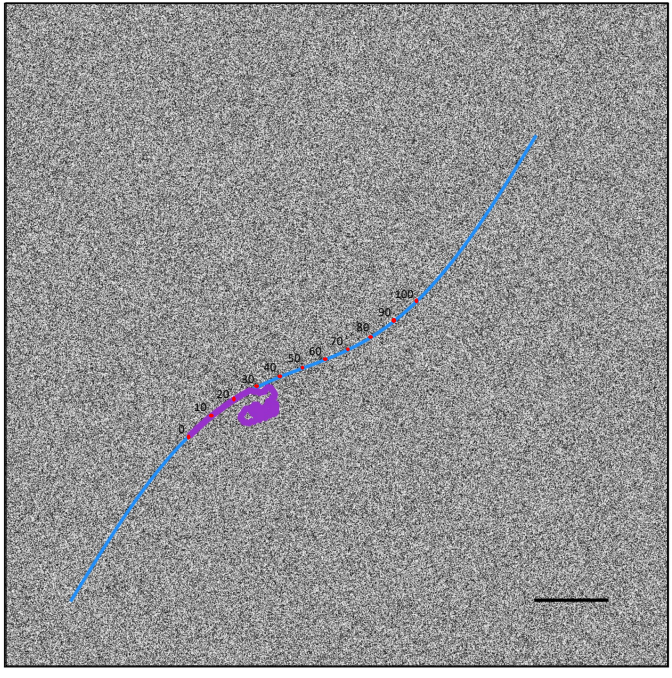


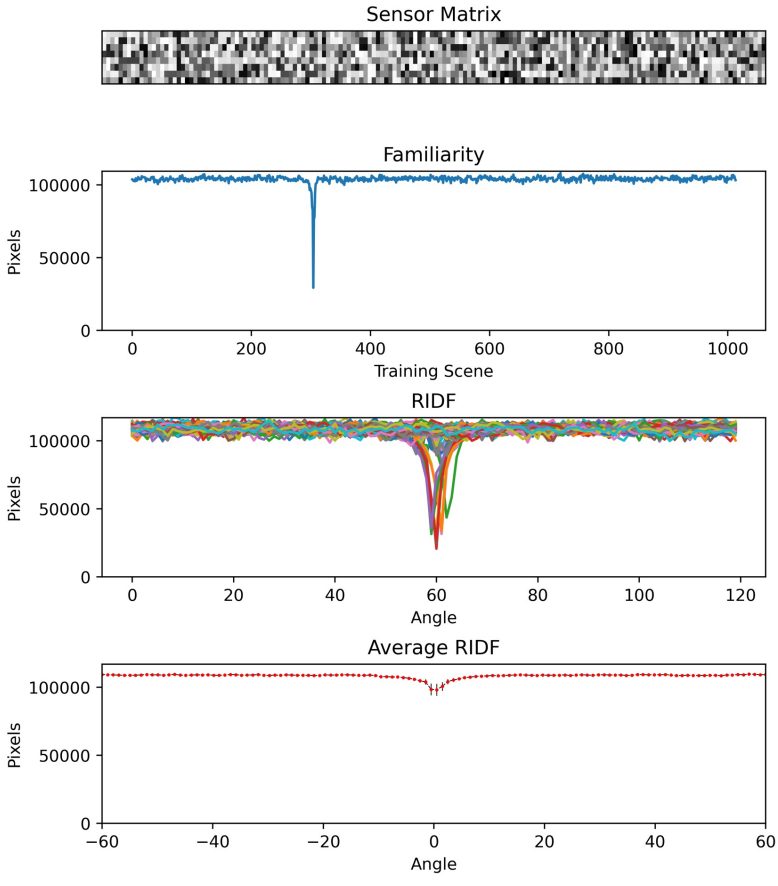


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 180.70; RMSD/dist: 0.452; TD: 22625; p90: 6; p50: 4; complete: 0

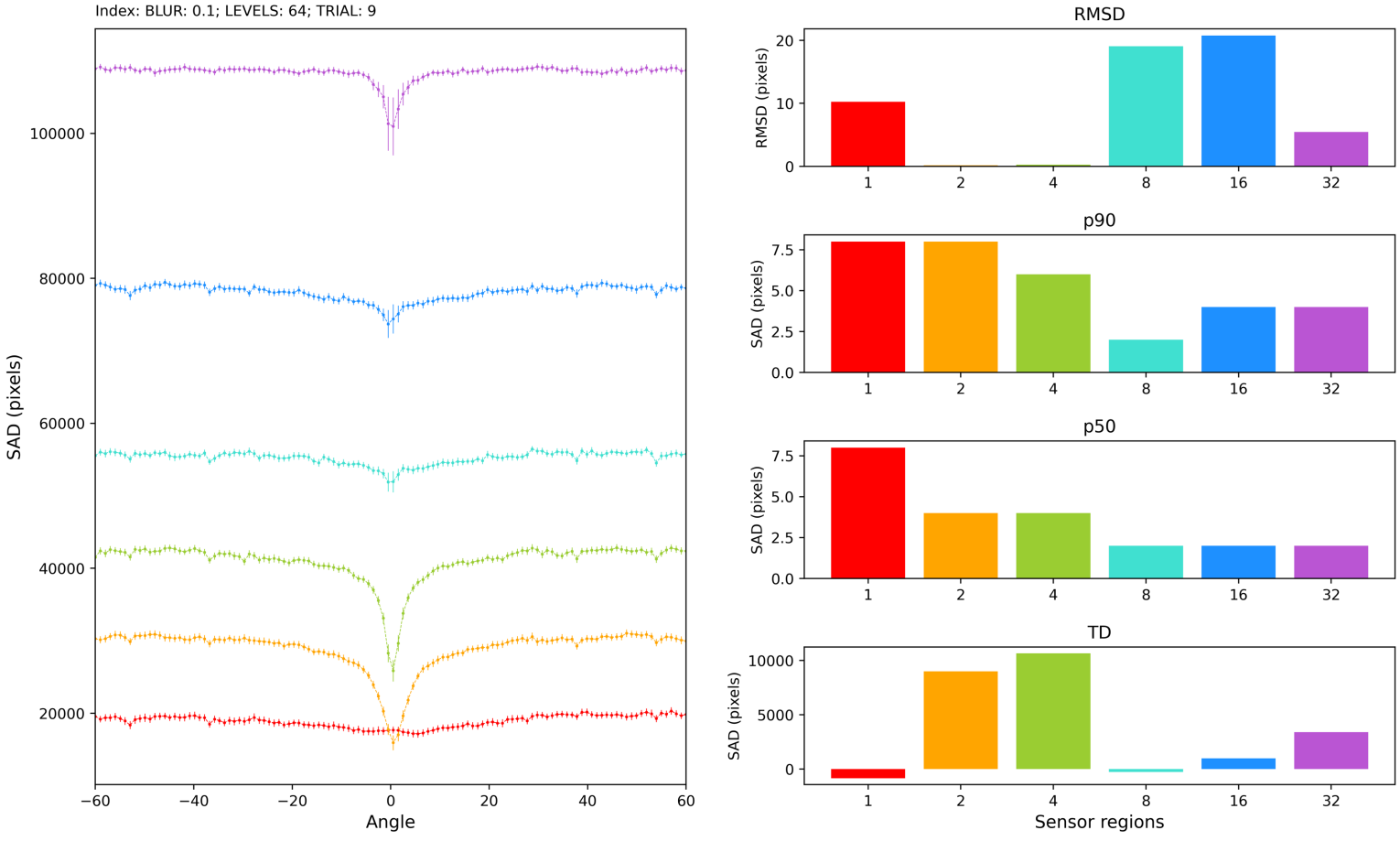
20%



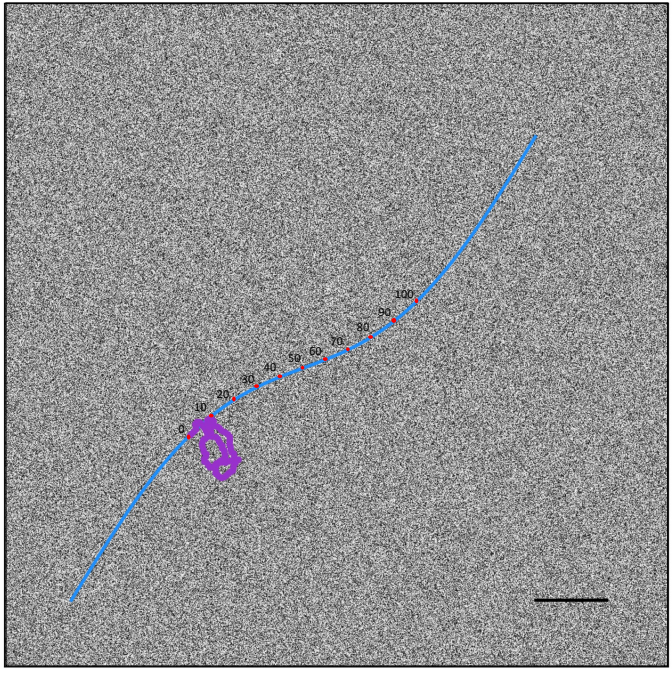


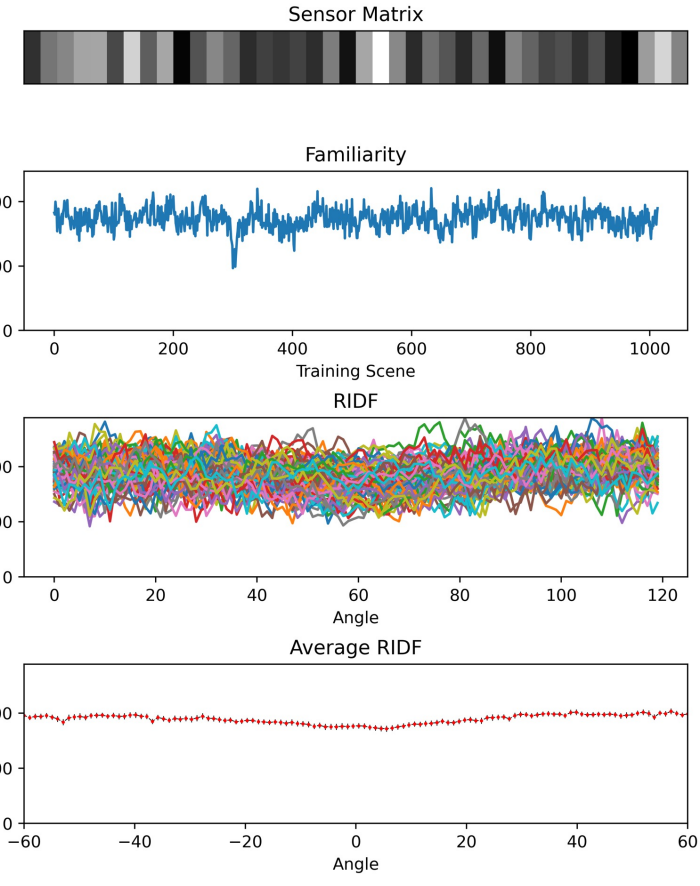
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2160.54; RMSD/dist: 5.401; TD: 6568; p90: 4; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 64; TRIAL: 9
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
p50
TD
10000
5000
Sensor regions

0%

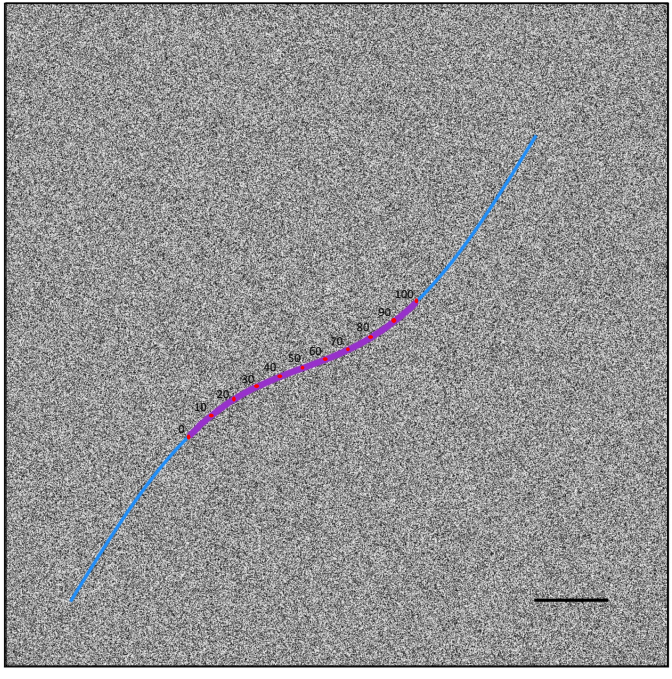


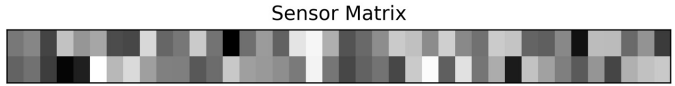


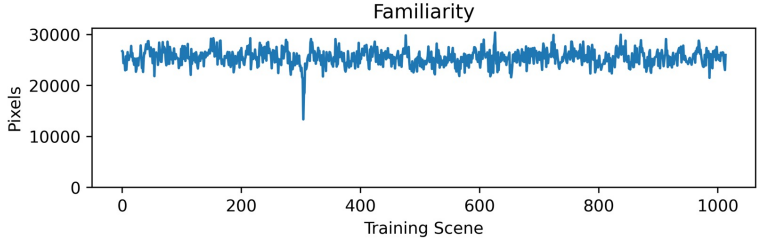
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

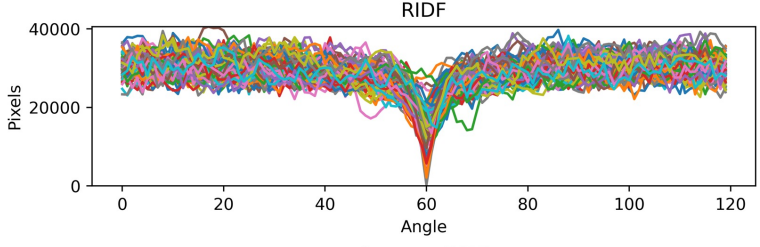
Navigation stats: RMSD error: 4097.02; RMSD/dist: 10.243; TD: -847; p90: 8; p50: 8; complete: 0

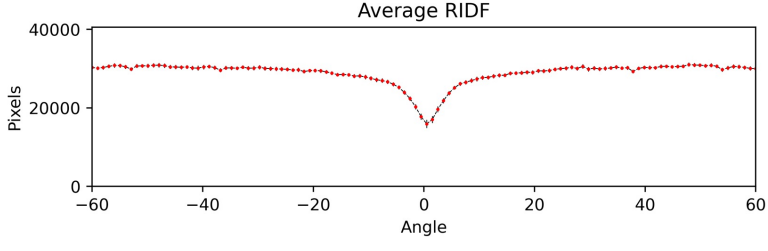
100%







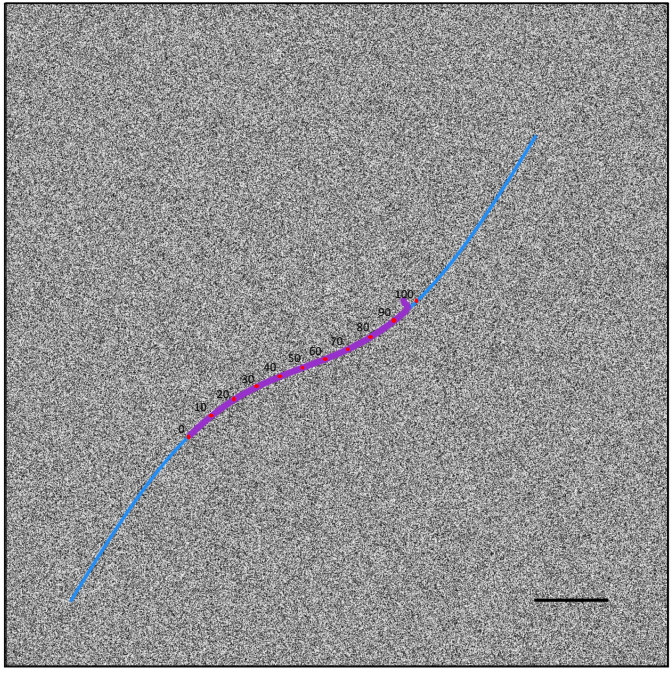


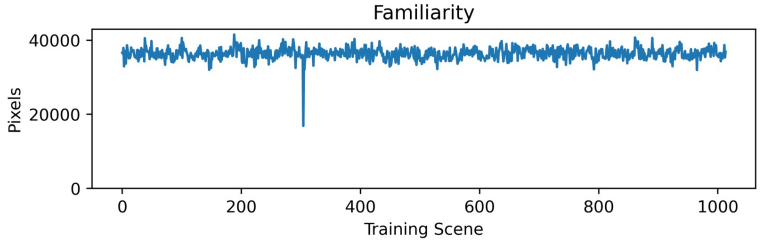


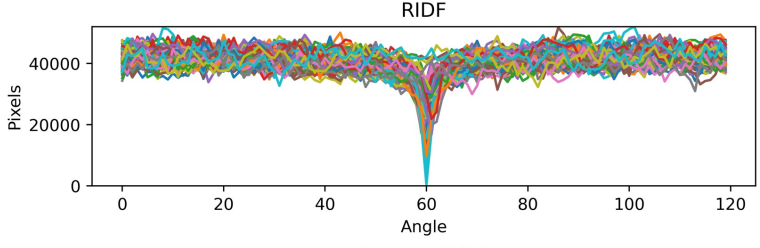
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

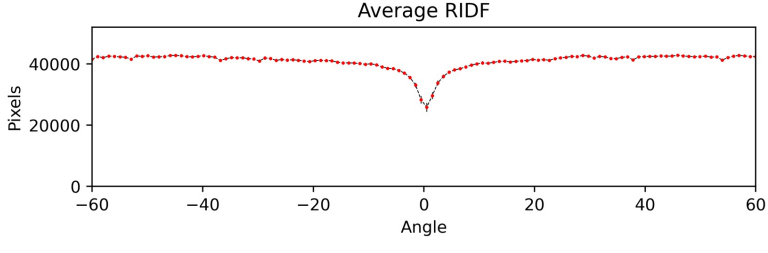
Navigation stats: RMSD error: 62.20; RMSD/dist: 0.156; TD: 8987; p90: 8; p50: 4; complete: 0

90%





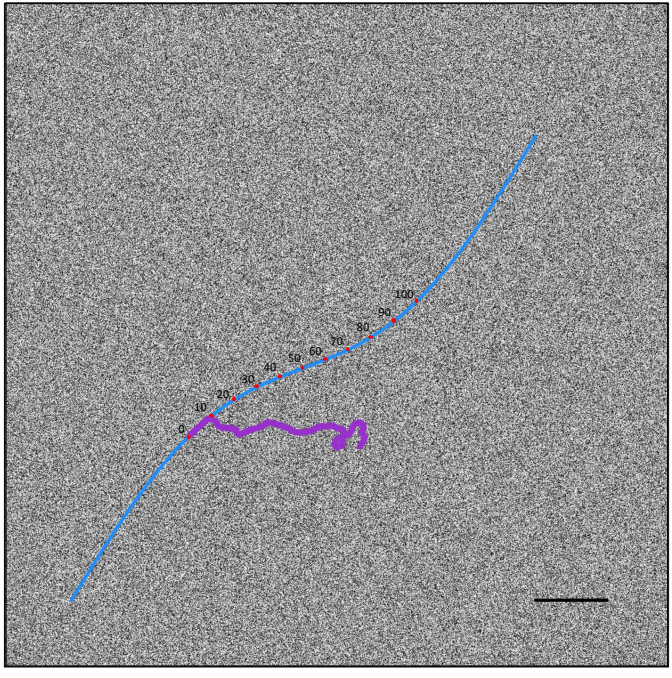


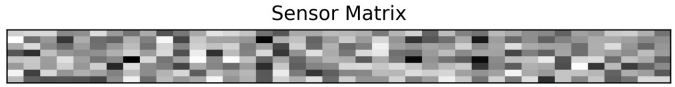


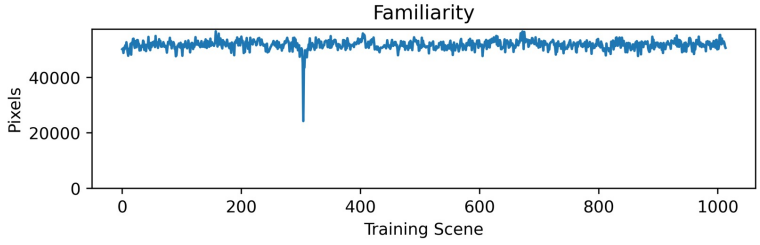
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

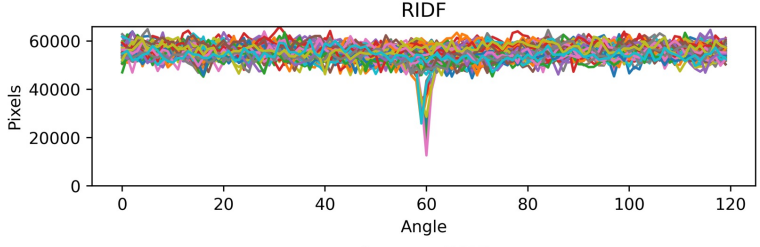
Navigation stats: RMSD error: 98.44; RMSD/dist: 0.246; TD: 10652; p90: 6; p50: 4; complete: 0

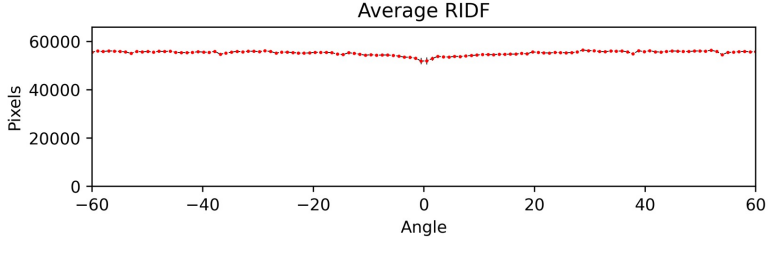
0%







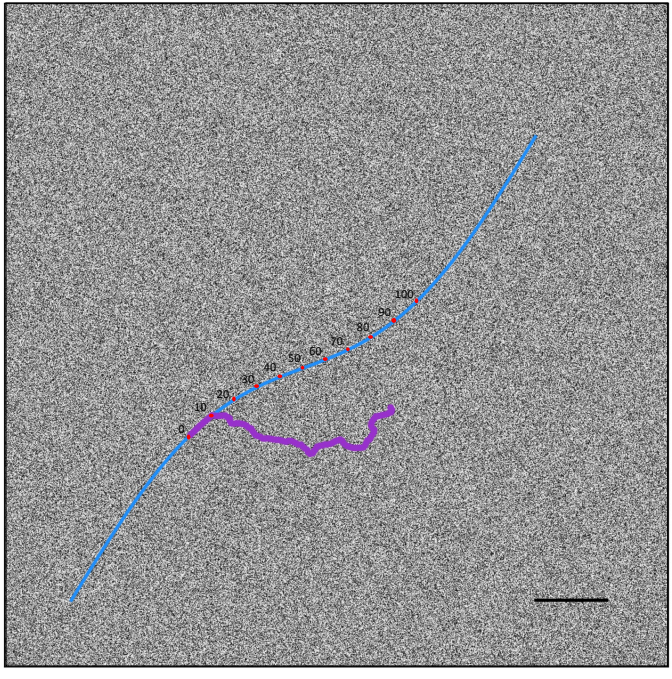


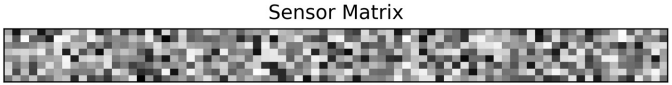


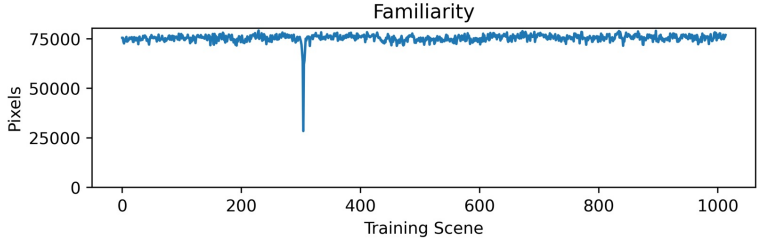
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

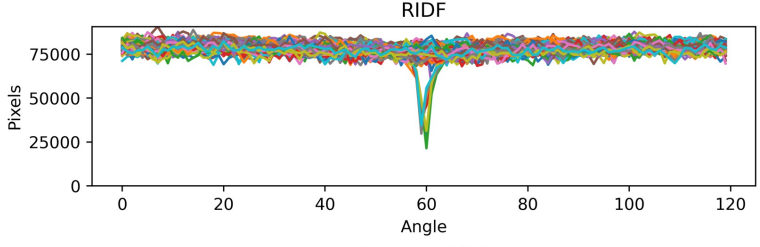
Navigation stats: RMSD error: 7622.84; RMSD/dist: 19.057; TD: -269; p90: 2; p50: 2; complete: 0

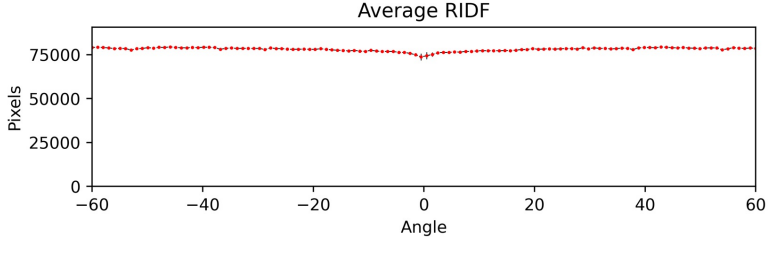
10%







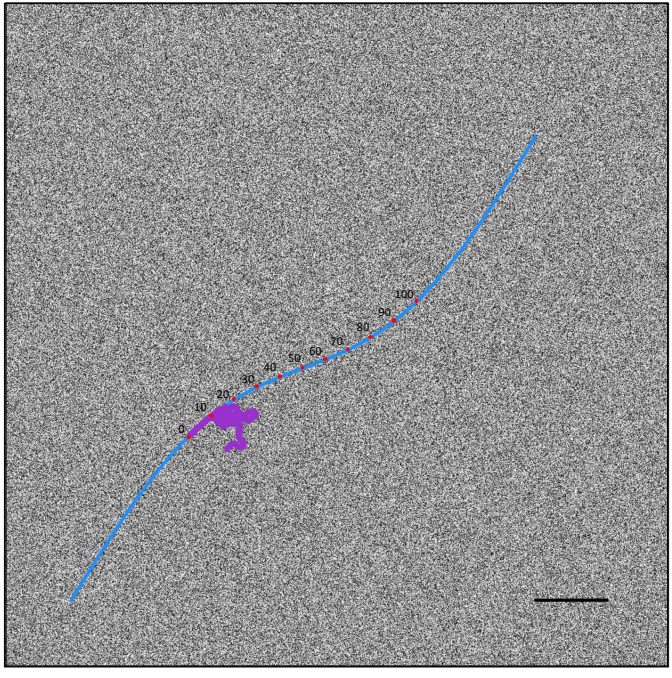


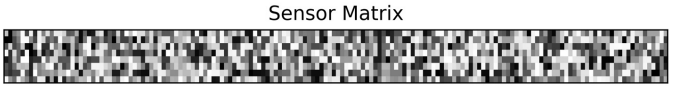


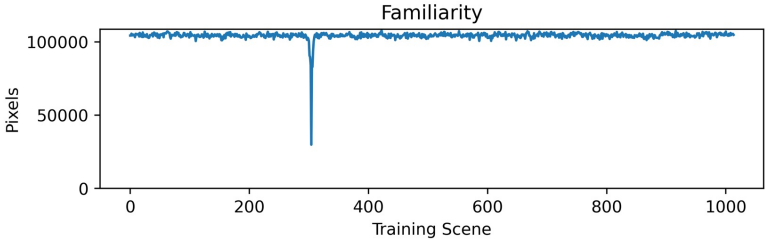
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

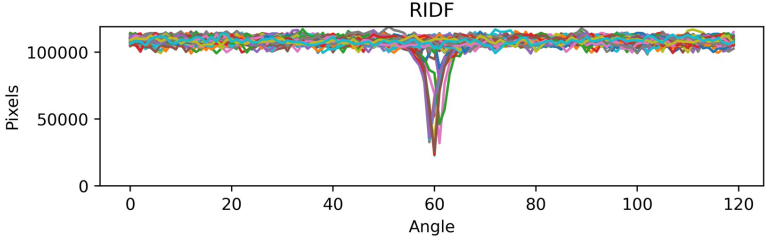
Navigation stats: RMSD error: 8310.21; RMSD/dist: 20.776; TD: 991; p90: 4; p50: 2; complete: 0

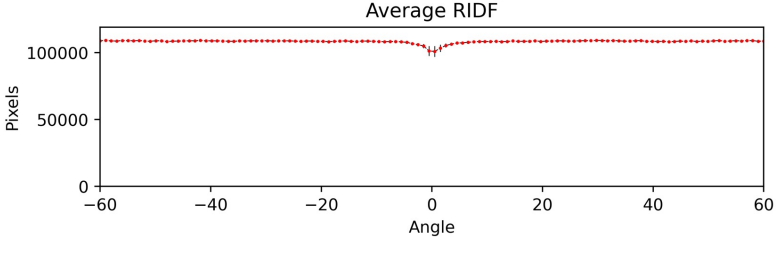
10%





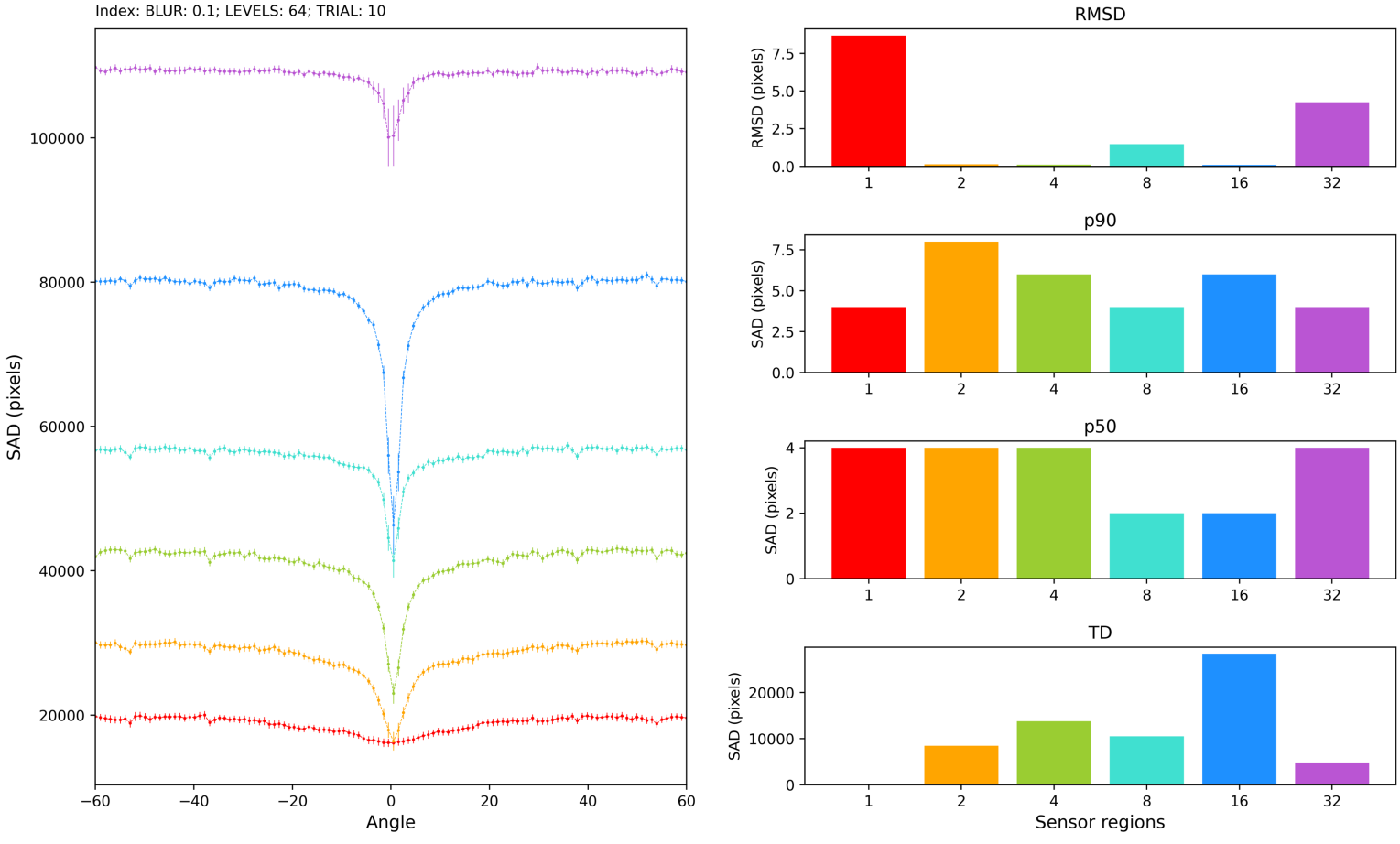




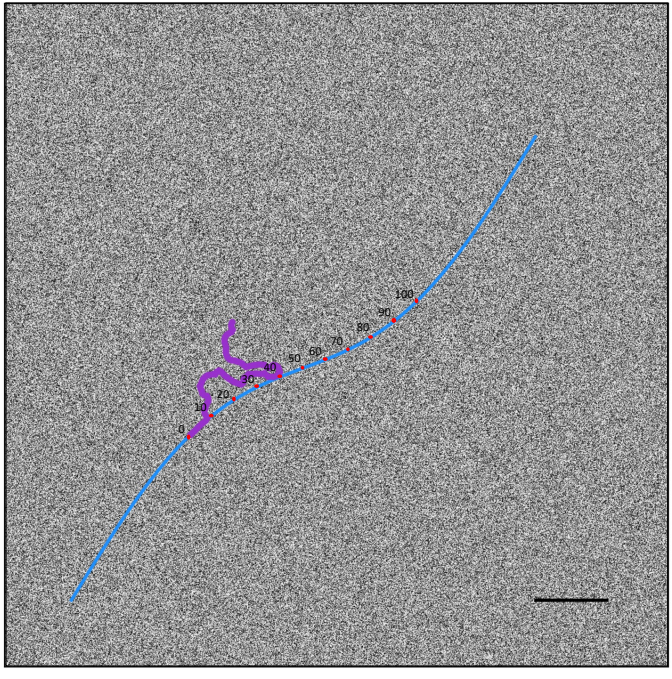


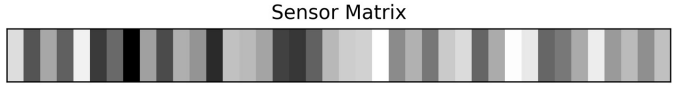
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

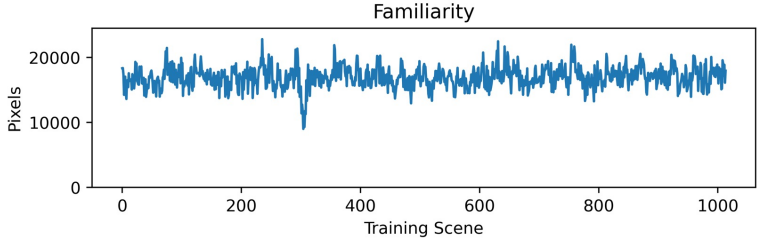
Navigation stats: RMSD error: 2184.46; RMSD/dist: 5.461; TD: 3389; p90: 4; p50: 2; complete: 0

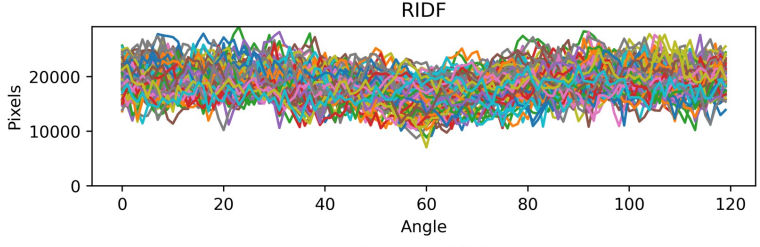

Index: BLUR: 0.1; LEVELS: 64; TRIAL: 10
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
7.5
5.0
2.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
7.5
5.0
2.5
0.0
1
2
4
8
16
32
p50
SAD (pixels)
4
2
0
1
2
4
8
16
32
TD
SAD (pixels)
20000
10000
0
1
2
4
8
16
32
Sensor regions

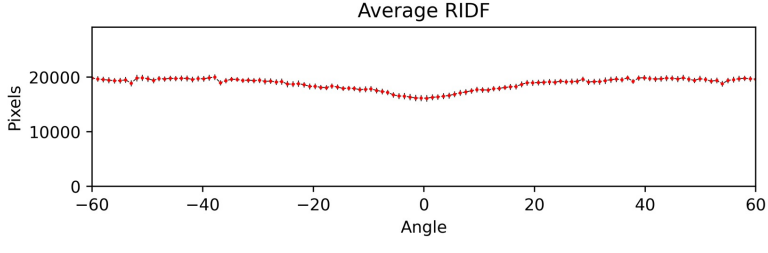
0%







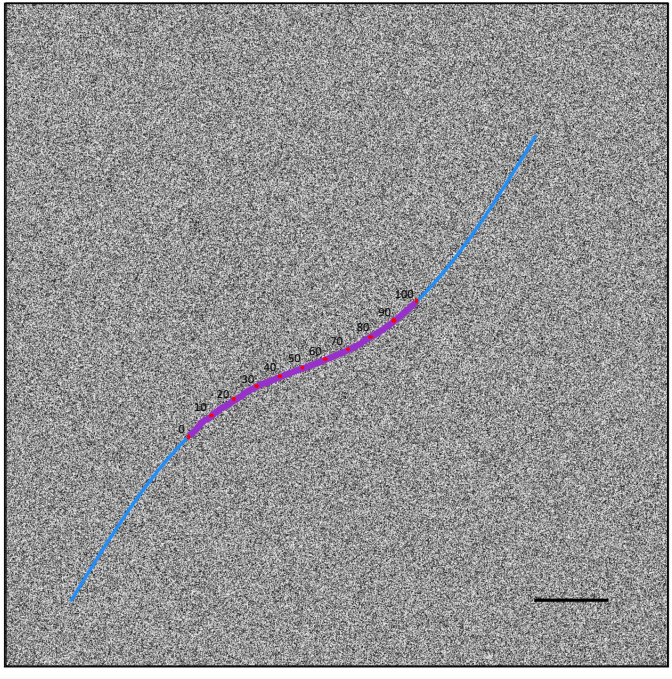


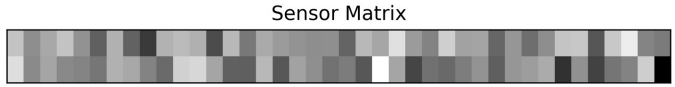


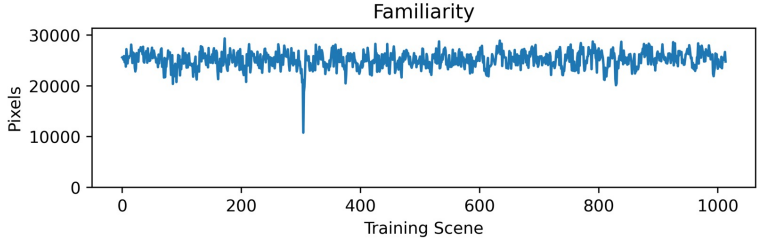
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

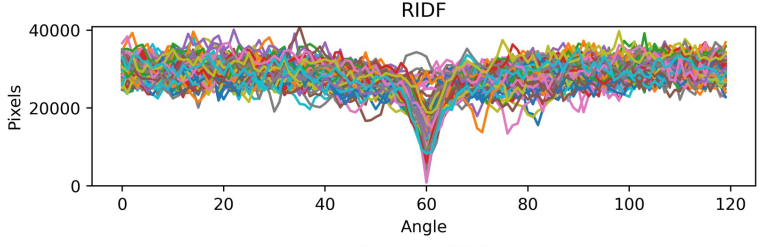
Navigation stats: RMSD error: 3473.65; RMSD/dist: 8.684; TD: 141; p90: 4; p50: 4; complete: 0

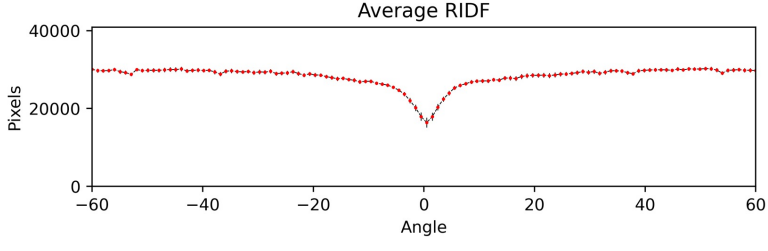
100%







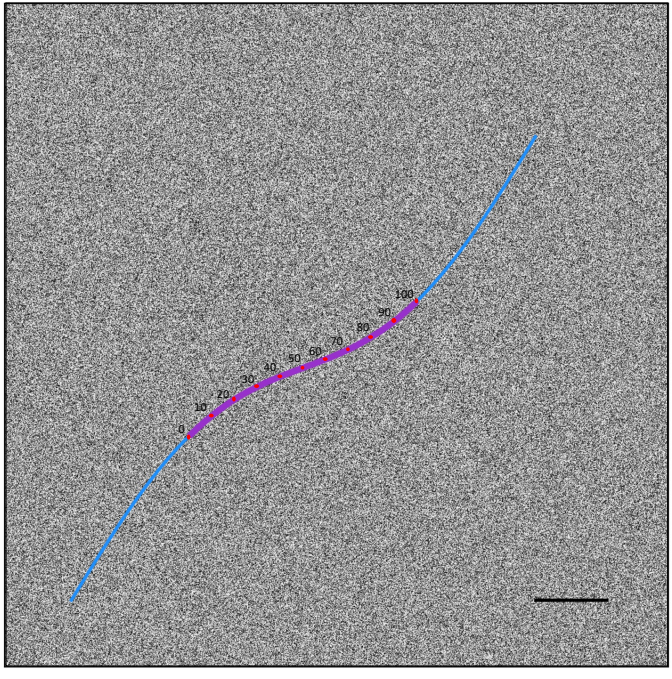


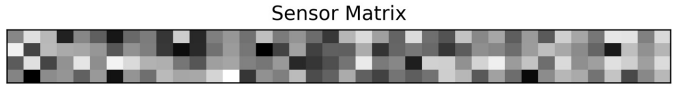


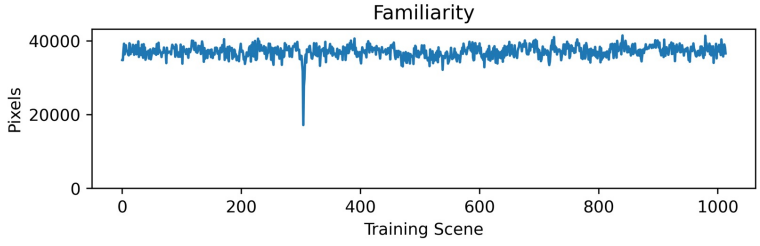
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

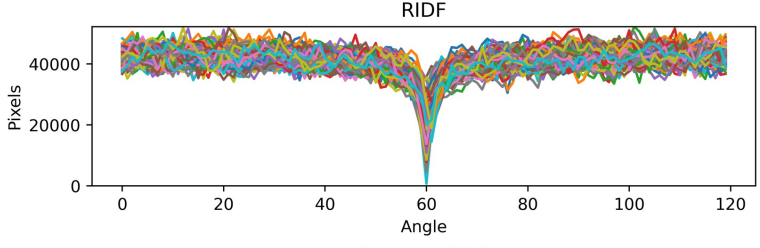
Navigation stats: RMSD error: 54.54; RMSD/dist: 0.136; TD: 8448; p90: 8; p50: 4; complete: 0

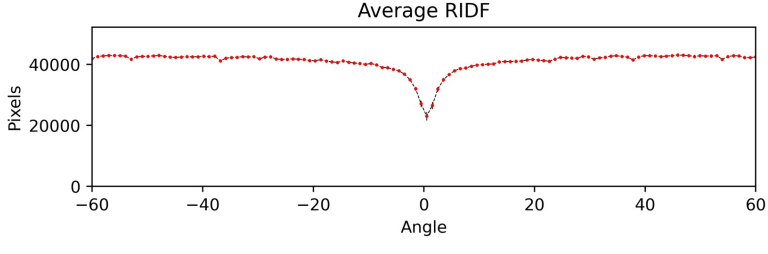
100%







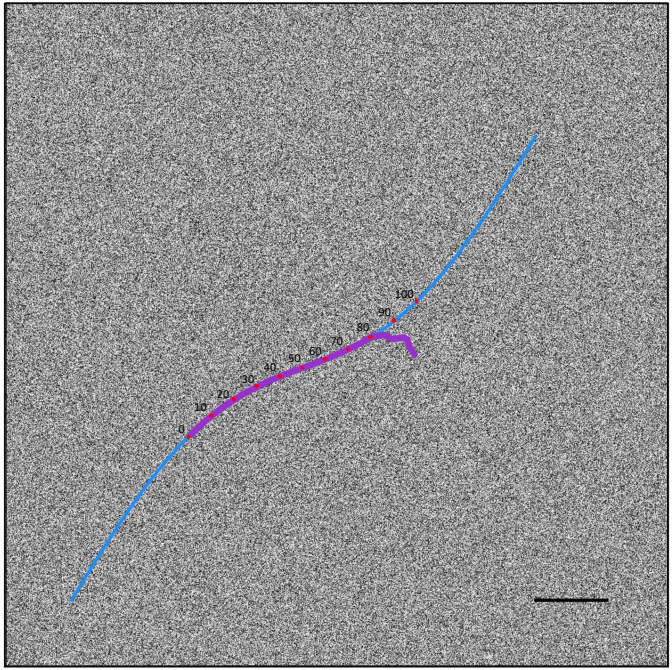


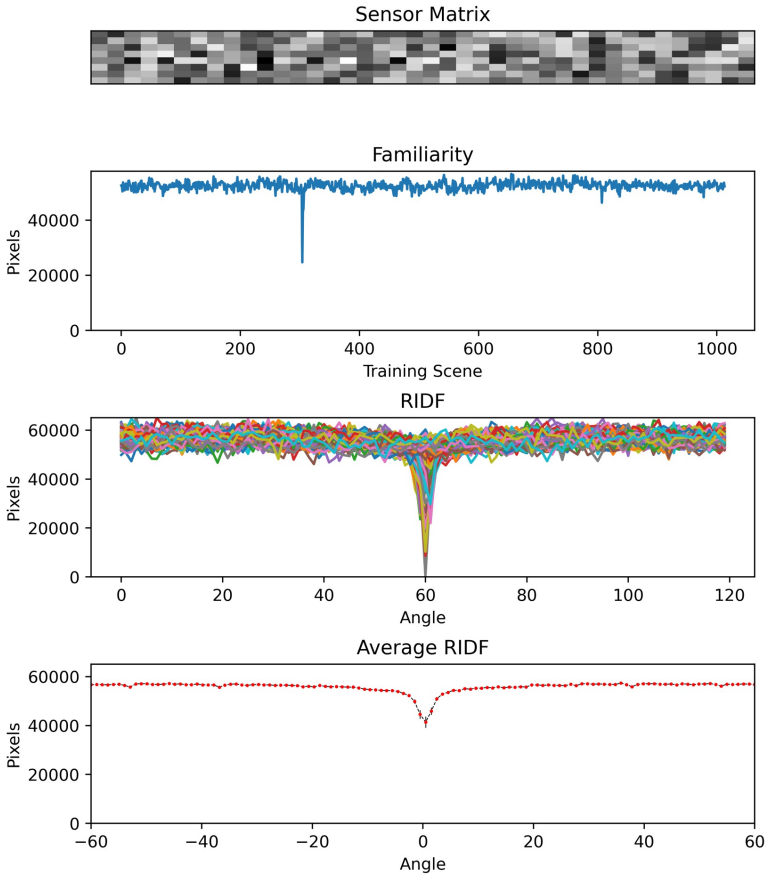


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 45.13; RMSD/dist: 0.113; TD: 13759; p90: 6; p50: 4; complete: 0

80%

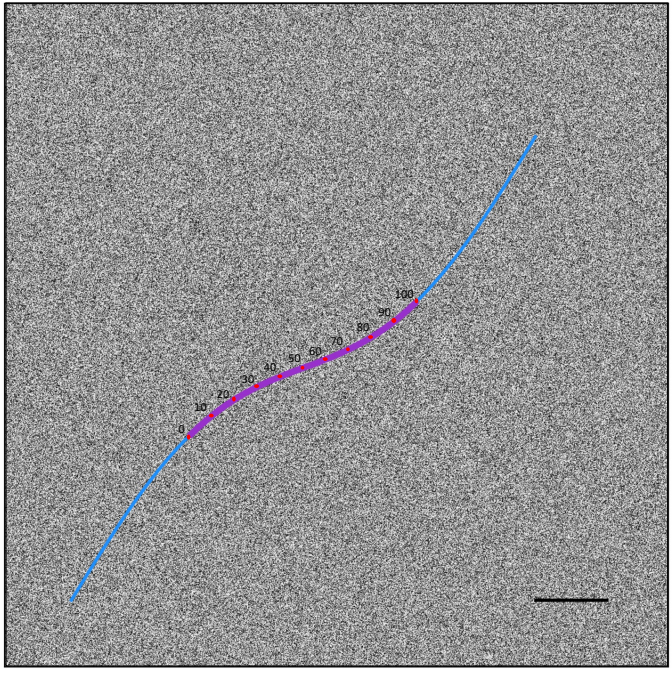


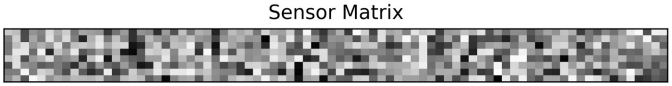


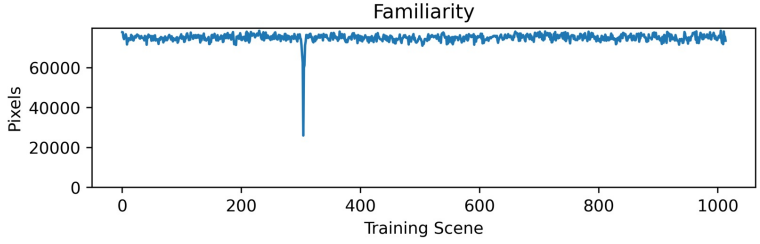
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

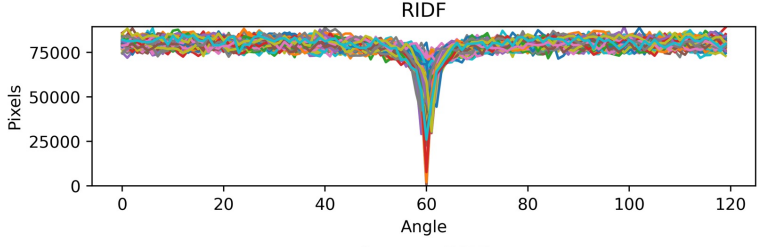
Navigation stats: RMSD error: 589.08; RMSD/dist: 1.473; TD: 10515; p90: 4; p50: 2; complete: 0

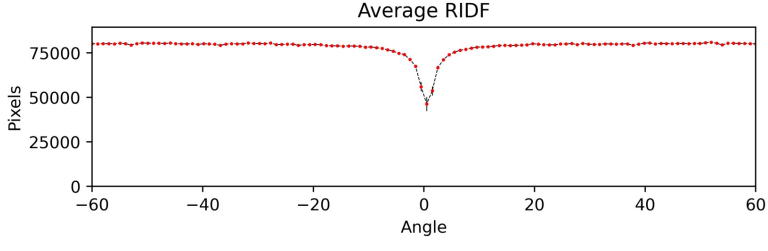
100%







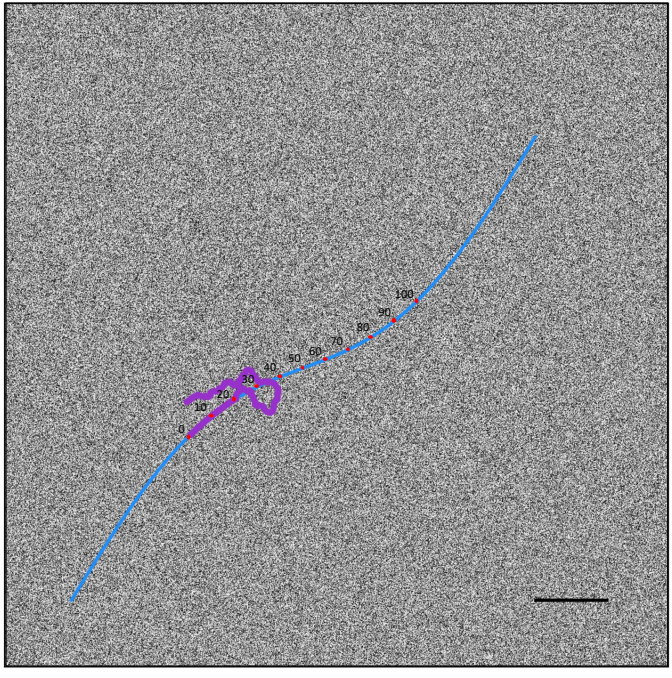


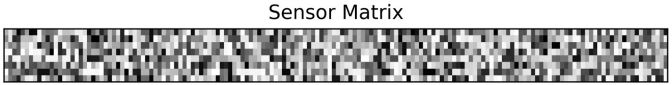


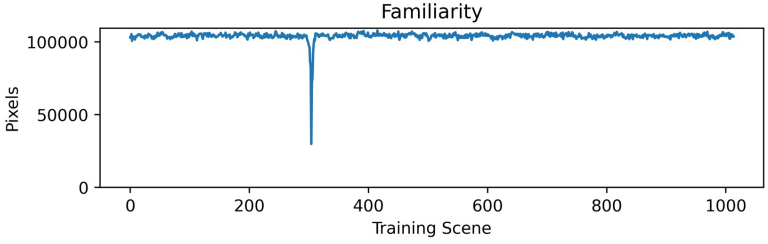
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

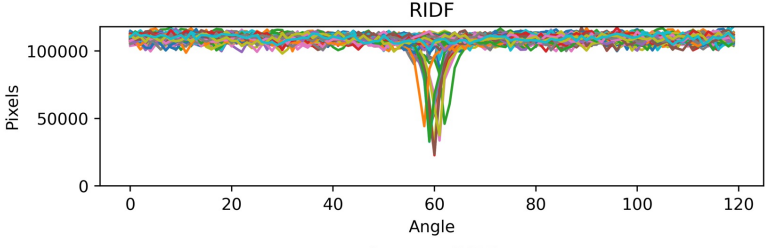
Navigation stats: RMSD error: 35.22; RMSD/dist: 0.088; TD: 28422; p90: 6; p50: 2; complete: 0

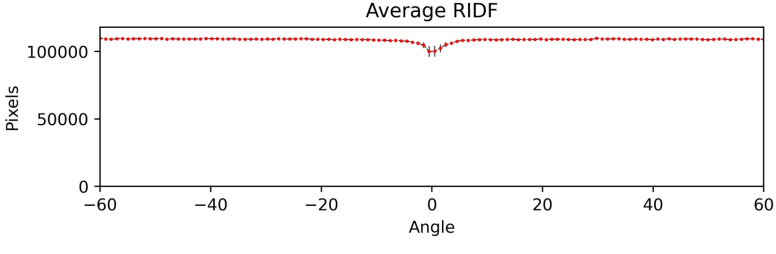
20%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1701.29; RMSD/dist: 4.253; TD: 4814; p90: 4; p50: 4; complete: 0