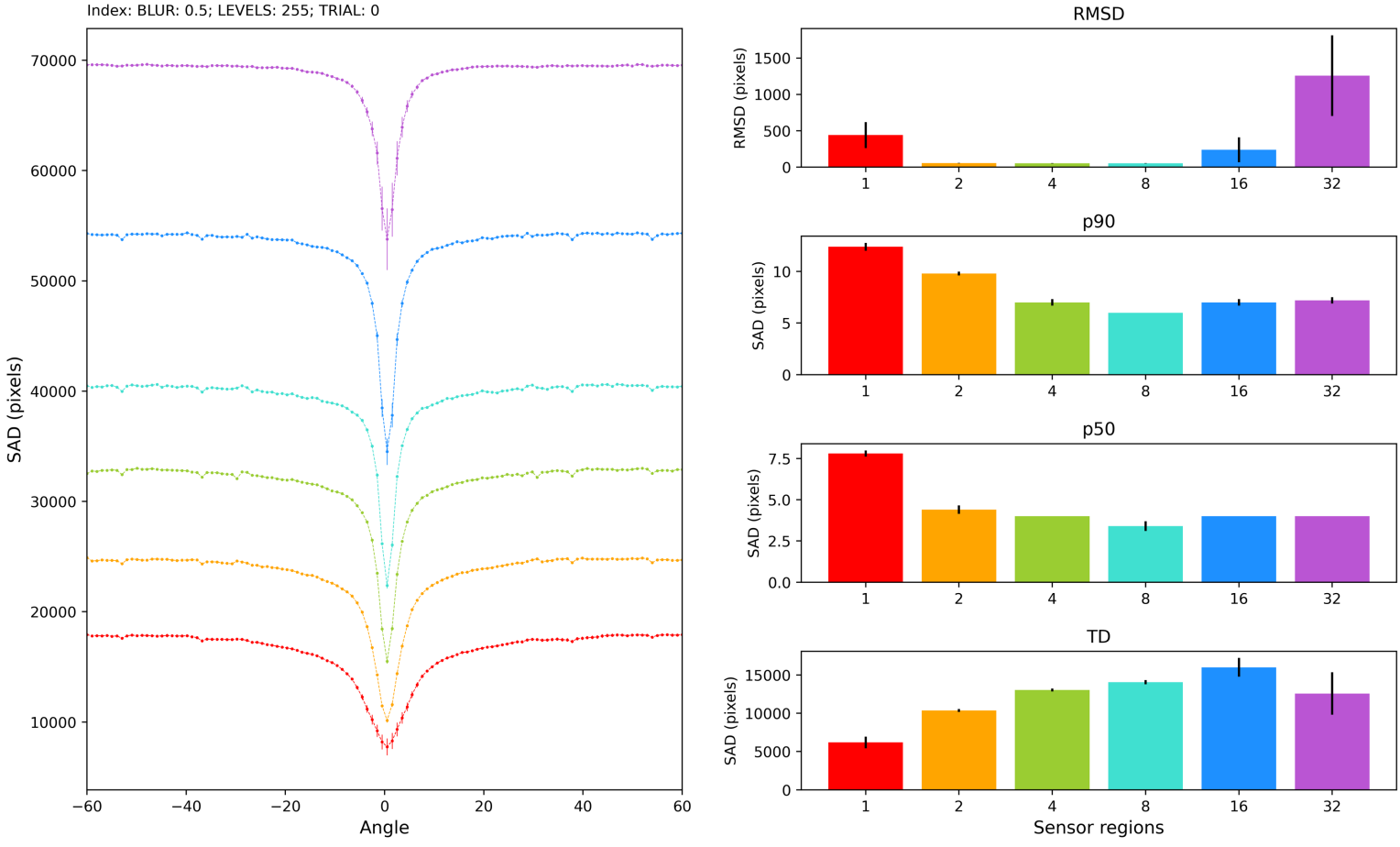
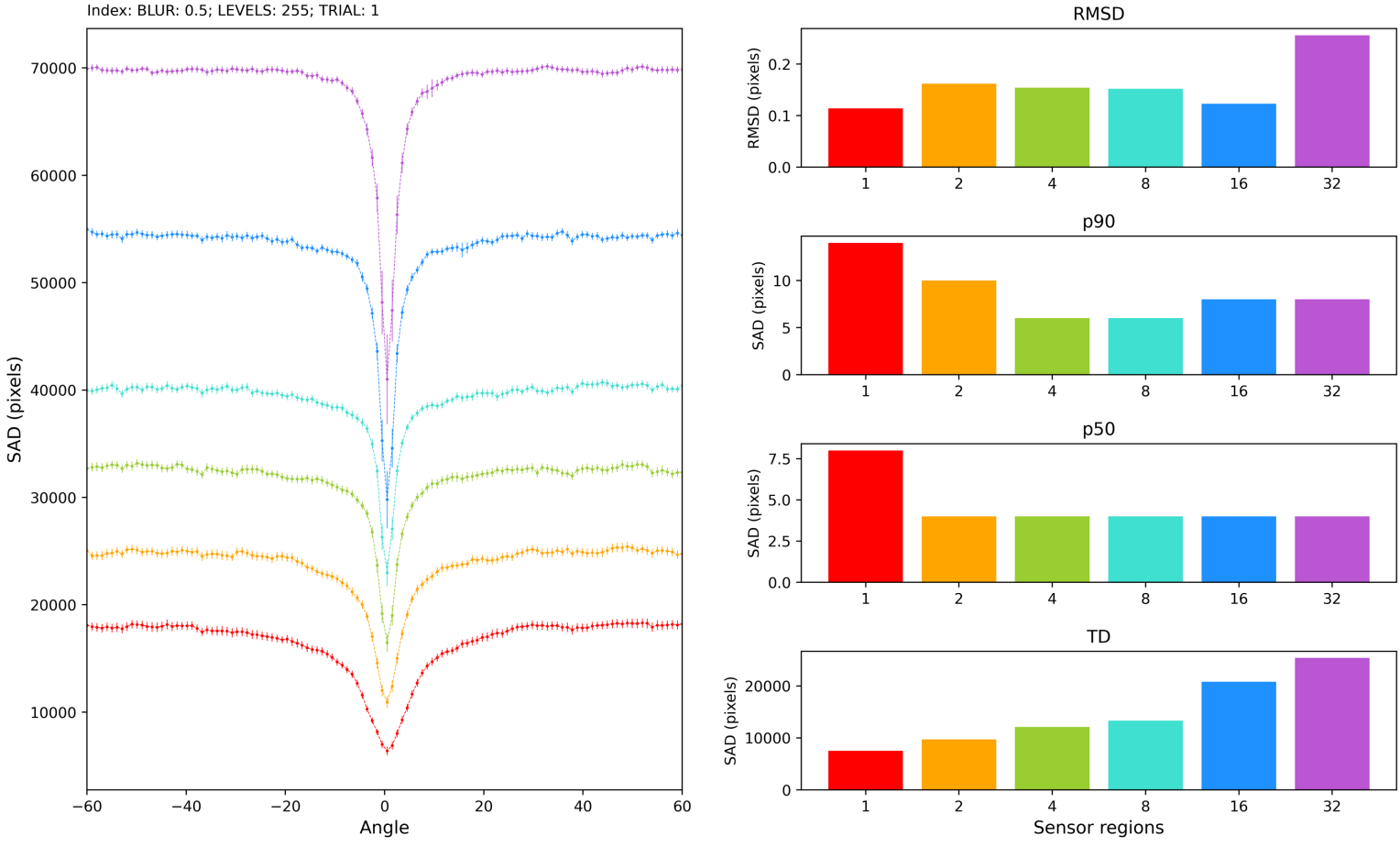

Index: BLUR: 0.5; LEVELS: 255; TRIAL: 0
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
1500
1000
500
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions


Index: BLUR: 0.5; LEVELS: 255; TRIAL: 1
SAD (pixels)
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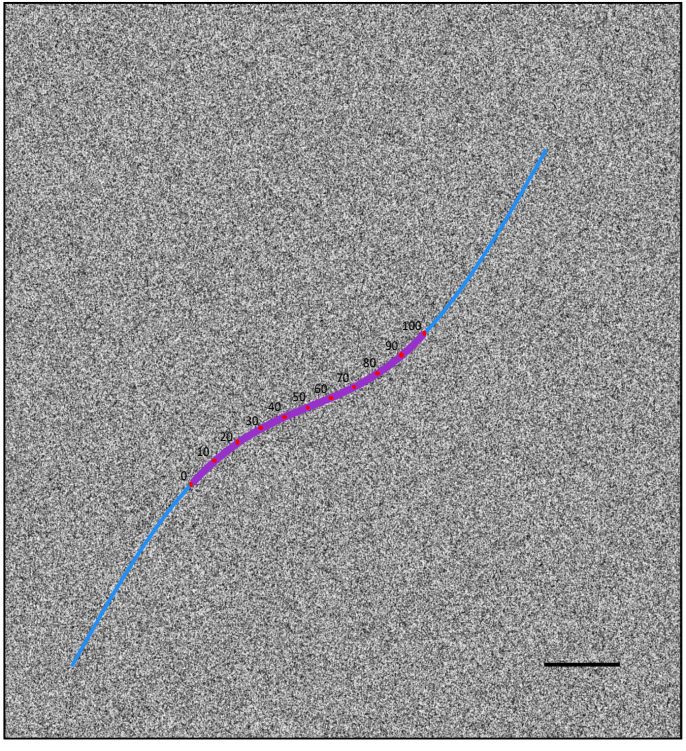
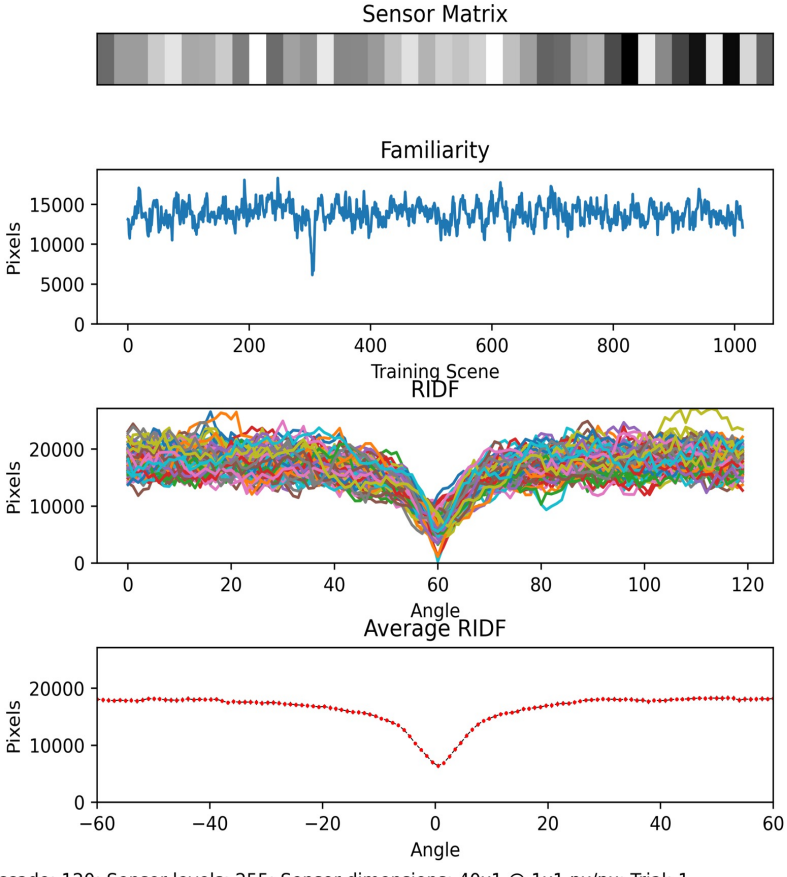
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

100%

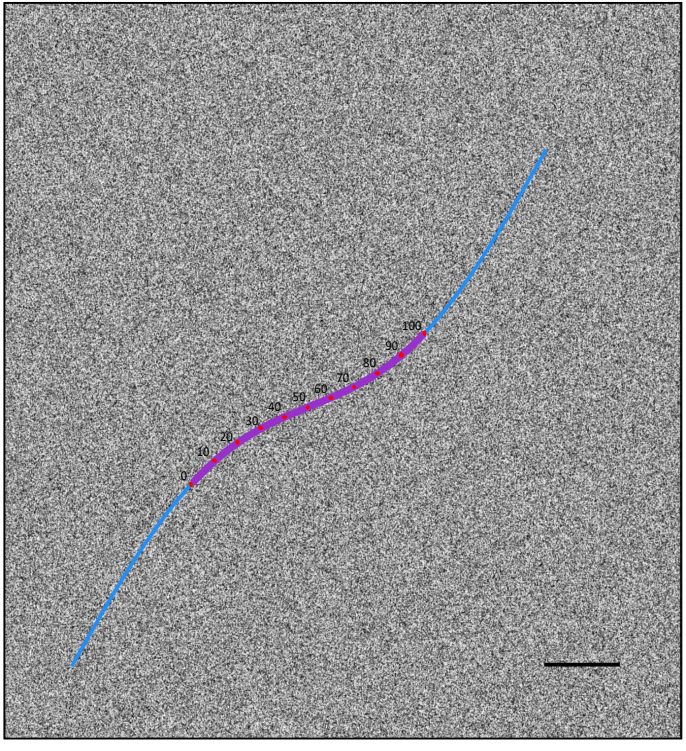


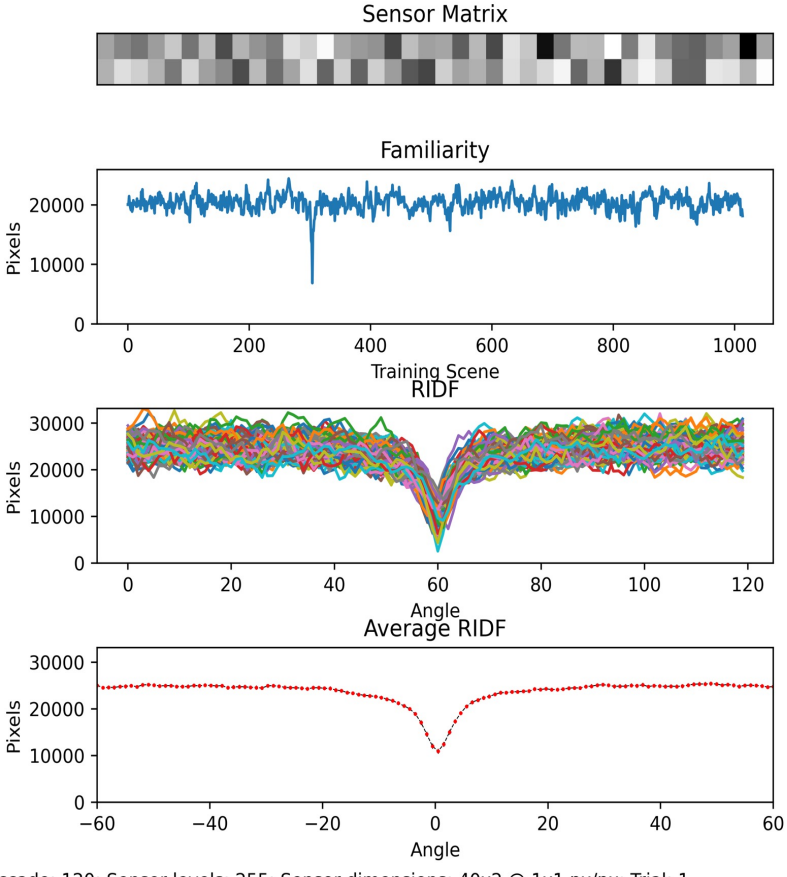


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 45.79; RMSD/dist: 0.114; TD: 7511; p90: 14; p50: 8; complete: 0

100%

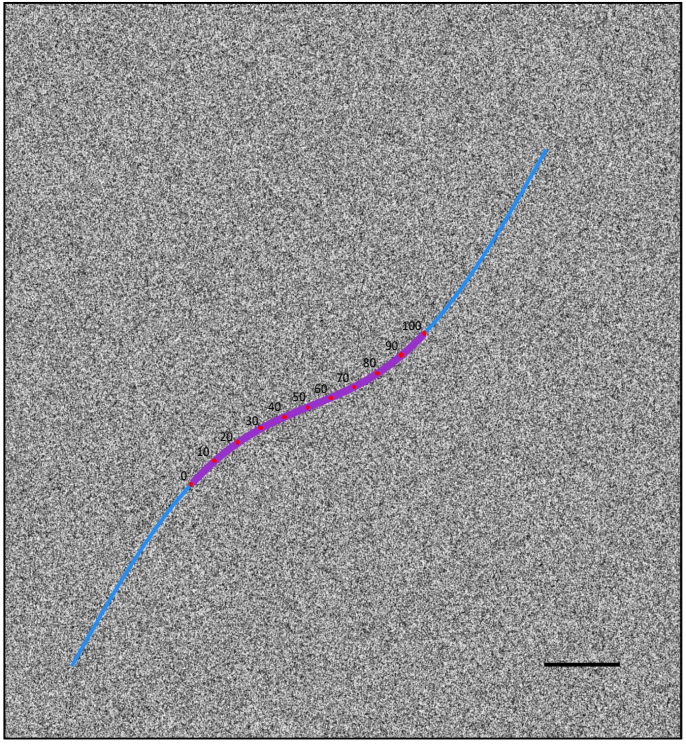


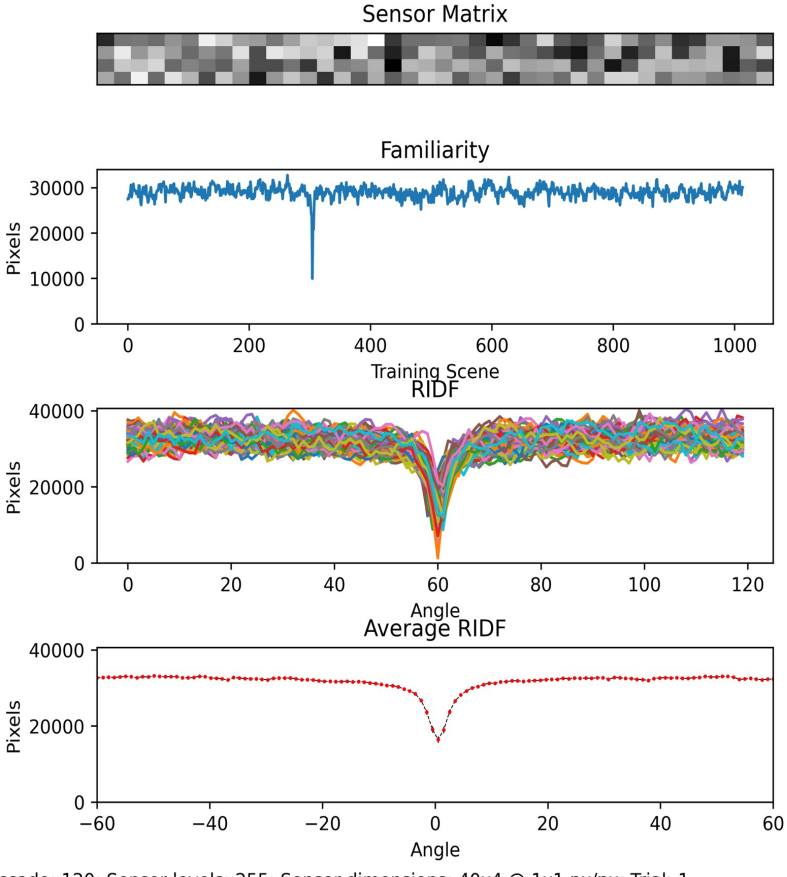


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 64.84; RMSD/dist: 0.162; TD: 9686; p90: 10; p50: 4; complete: 0

100%

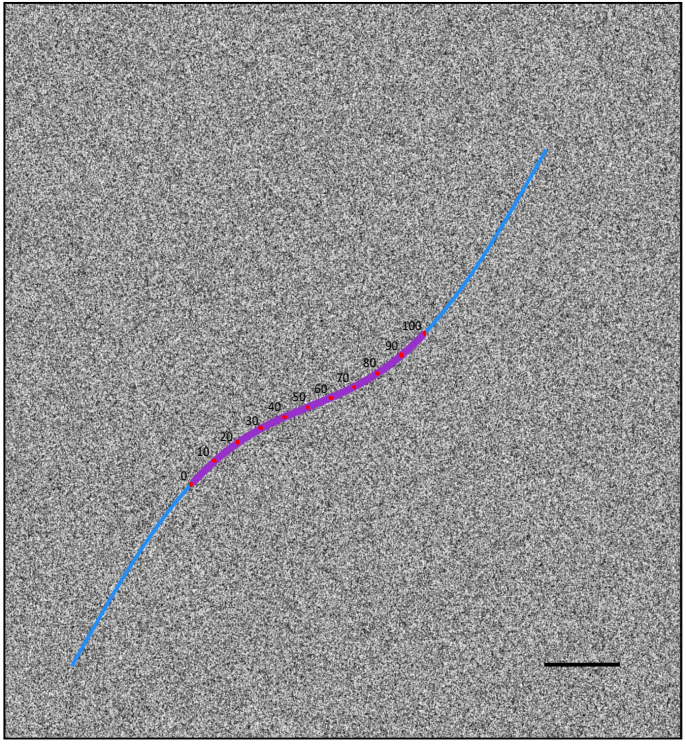


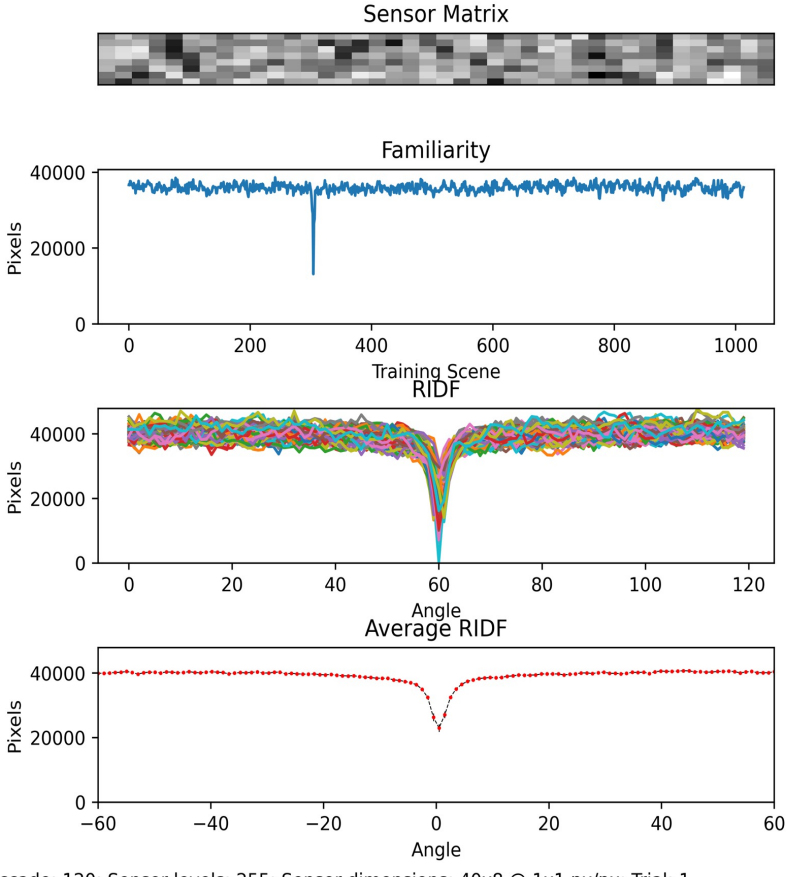


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 61.52; RMSD/dist: 0.154; TD: 12109; p90: 6; p50: 4; complete: 0

100%

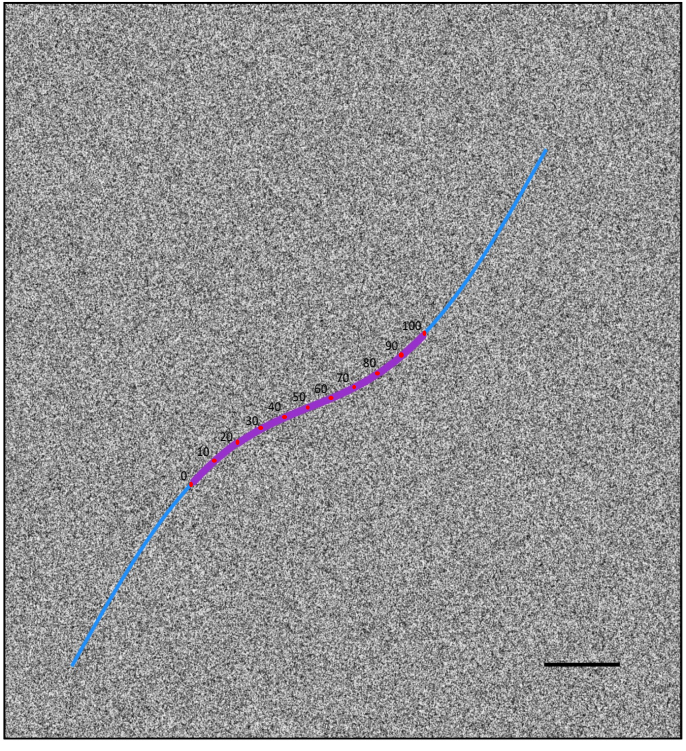


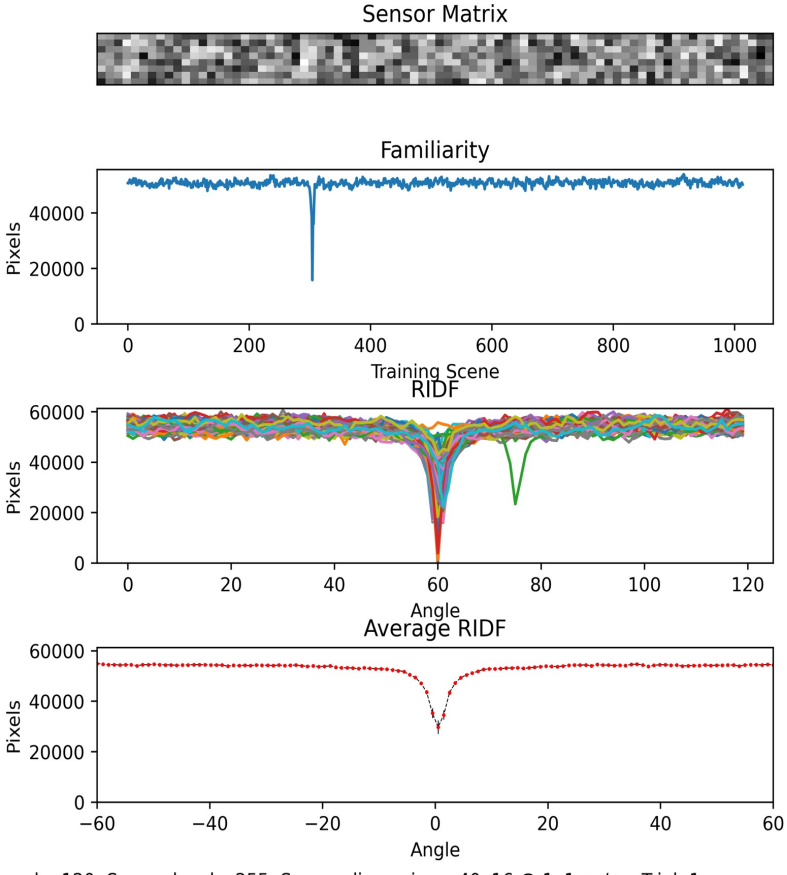


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 60.87; RMSD/dist: 0.152; TD: 13299; p90: 6; p50: 4; complete: 0

100%

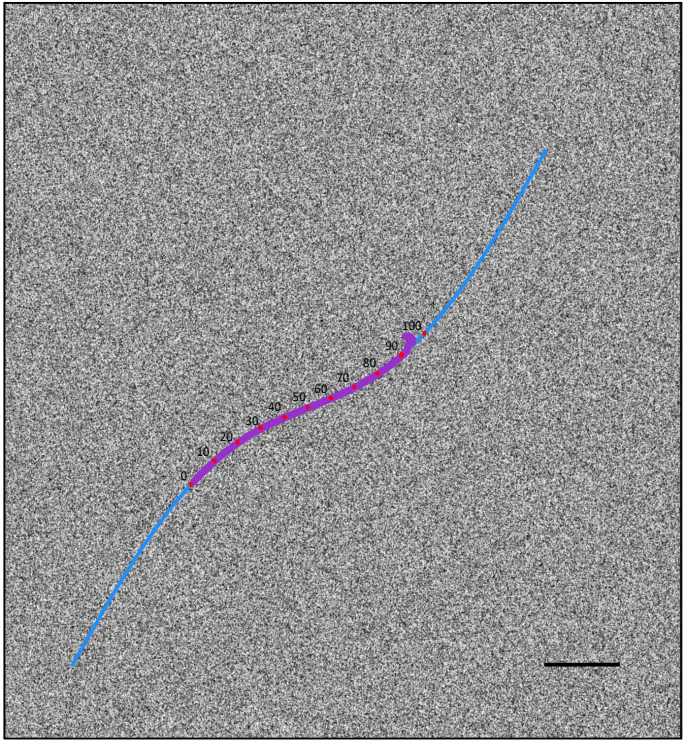


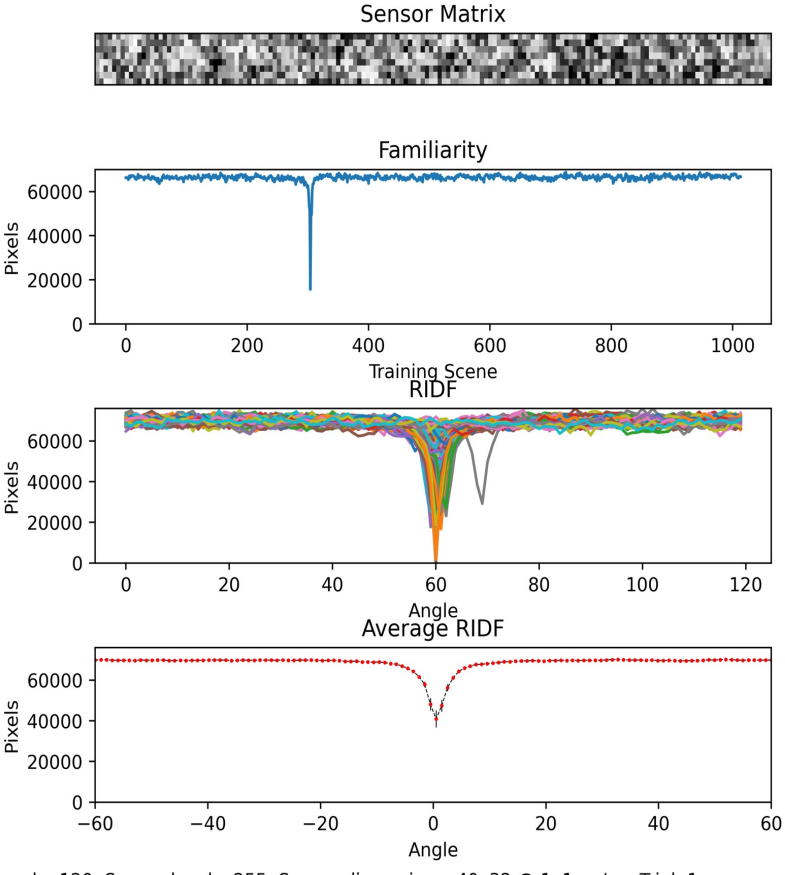


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 49.33; RMSD/dist: 0.123; TD: 20809; p90: 8; p50: 4; complete: 0

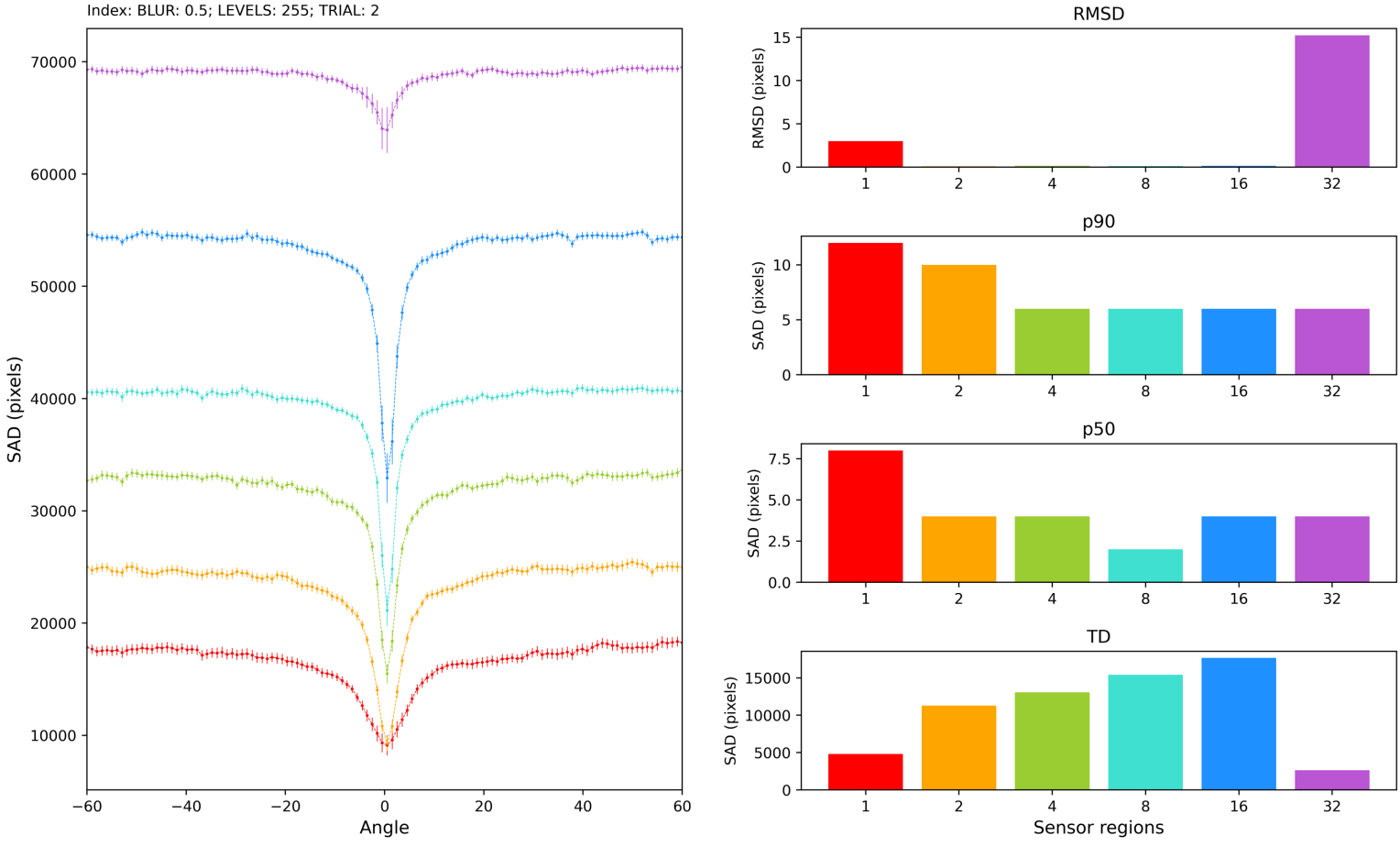
90%



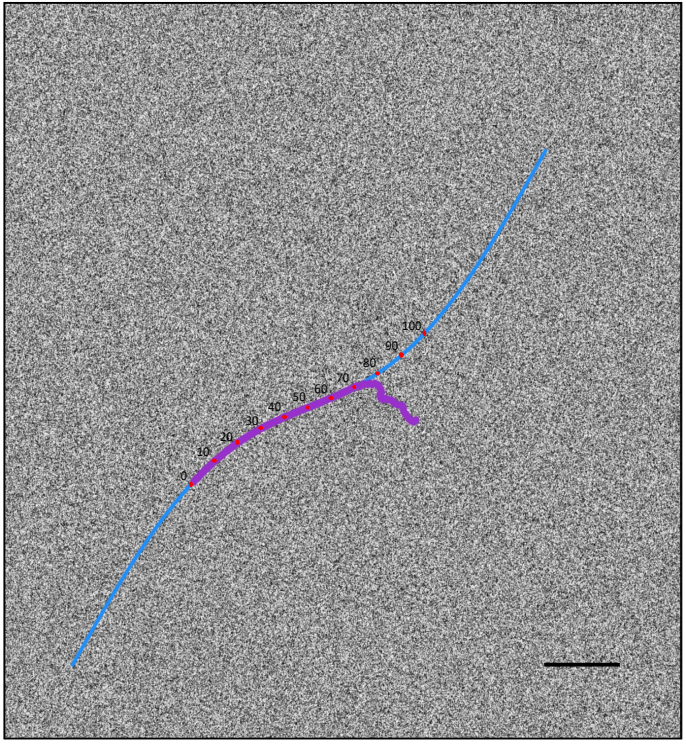


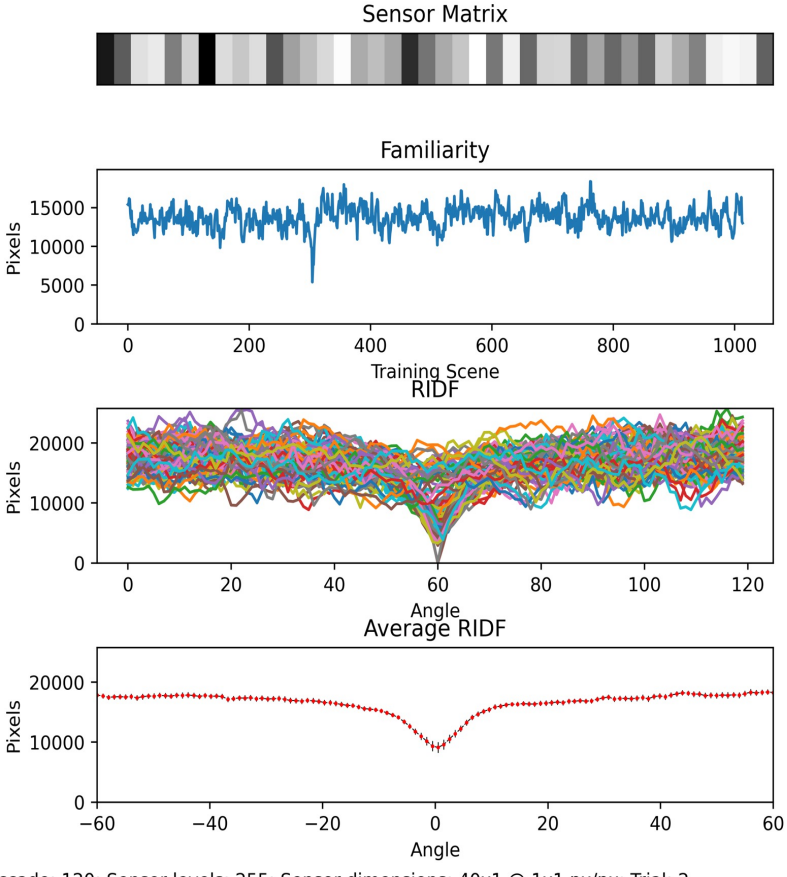
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 102.25; RMSD/dist: 0.256; TD: 25369; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 255; TRIAL: 2
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
15
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

70%

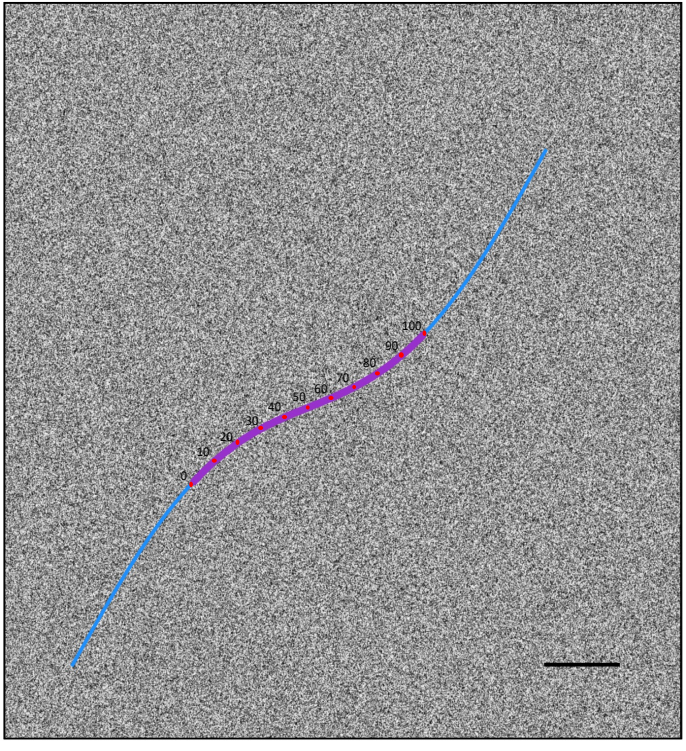


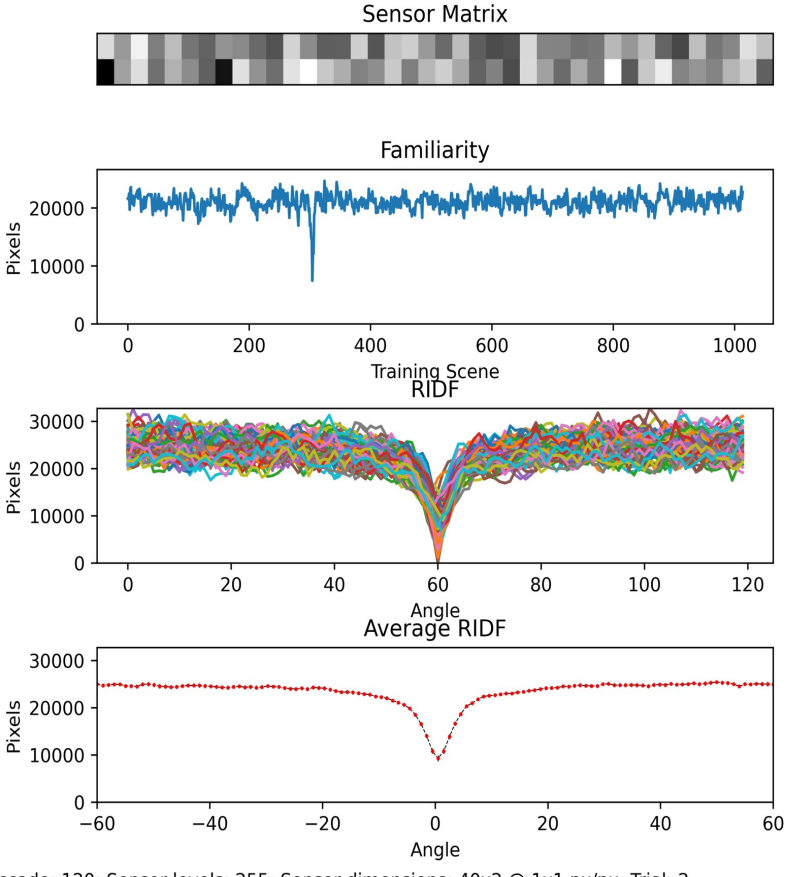


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1197.73; RMSD/dist: 2.994; TD: 4812; p90: 12; p50: 8; complete: 0

100%

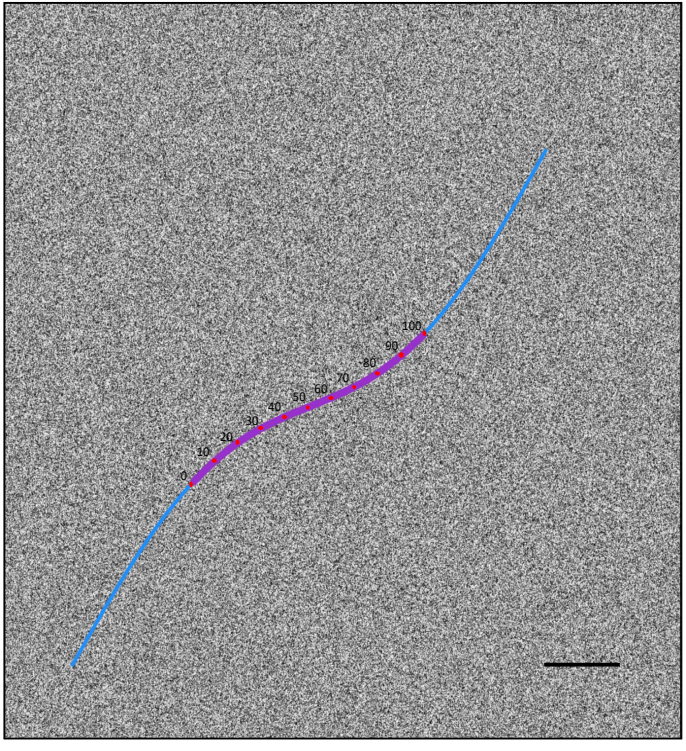


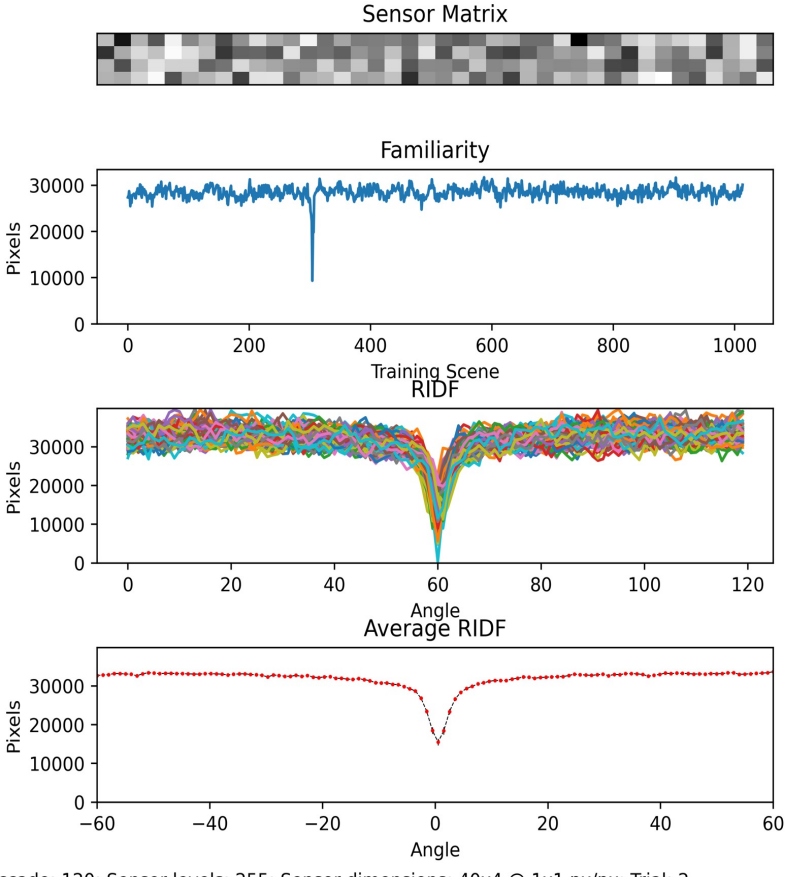


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 39.80; RMSD/dist: 0.100; TD: 11281; p90: 10; p50: 4; complete: 0

100%

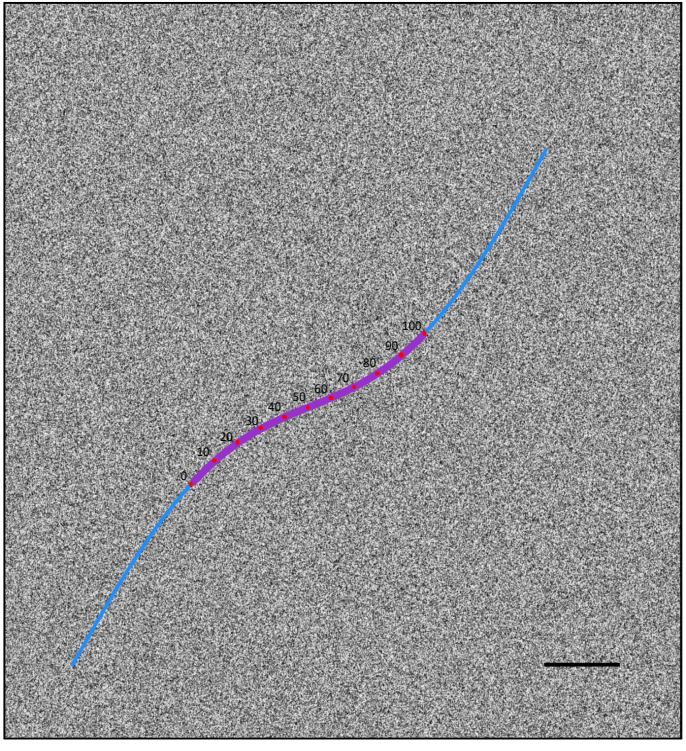


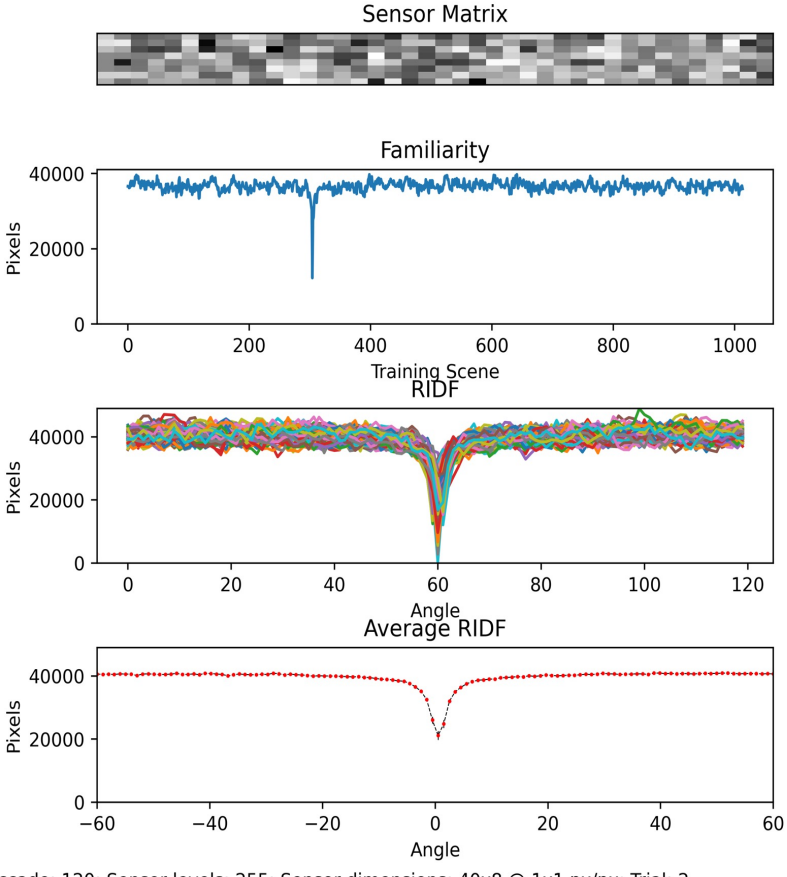


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 53.76; RMSD/dist: 0.134; TD: 13067; p90: 6; p50: 4; complete: 0

100%

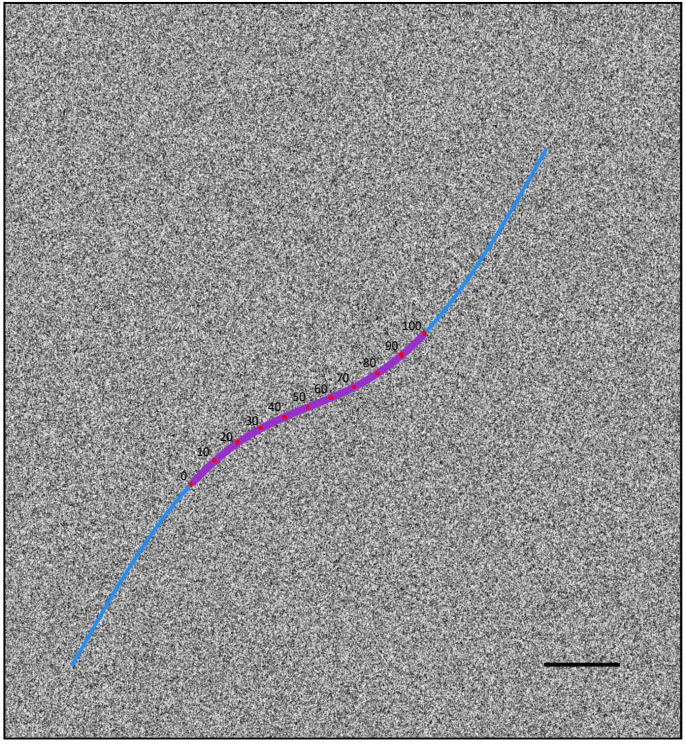


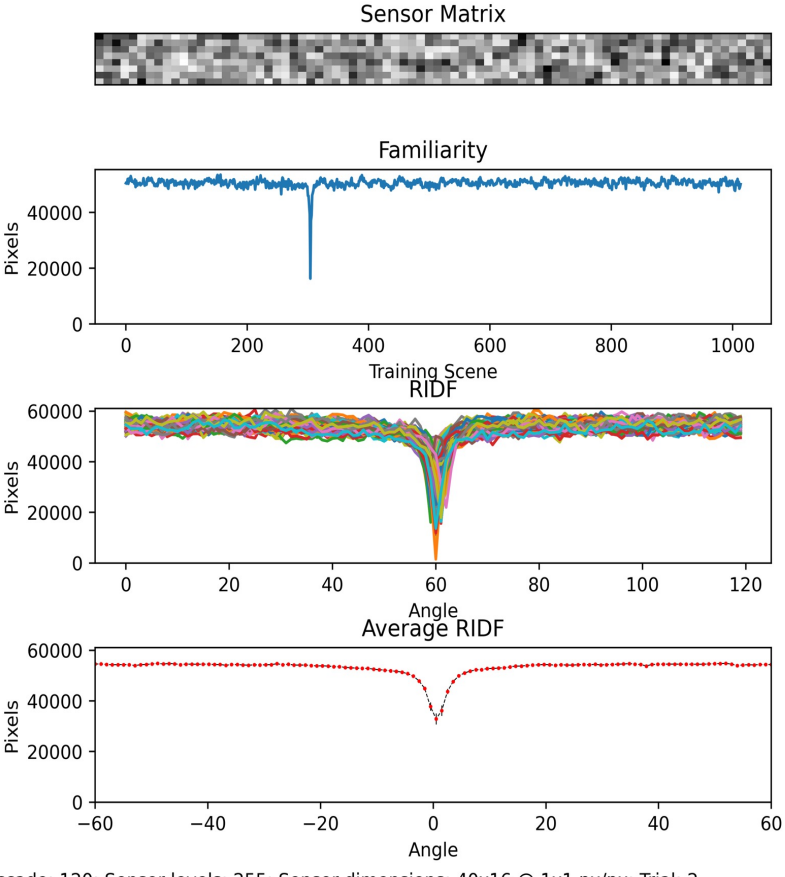


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 41.75; RMSD/dist: 0.104; TD: 15403; p90: 6; p50: 2; complete: 0

100%

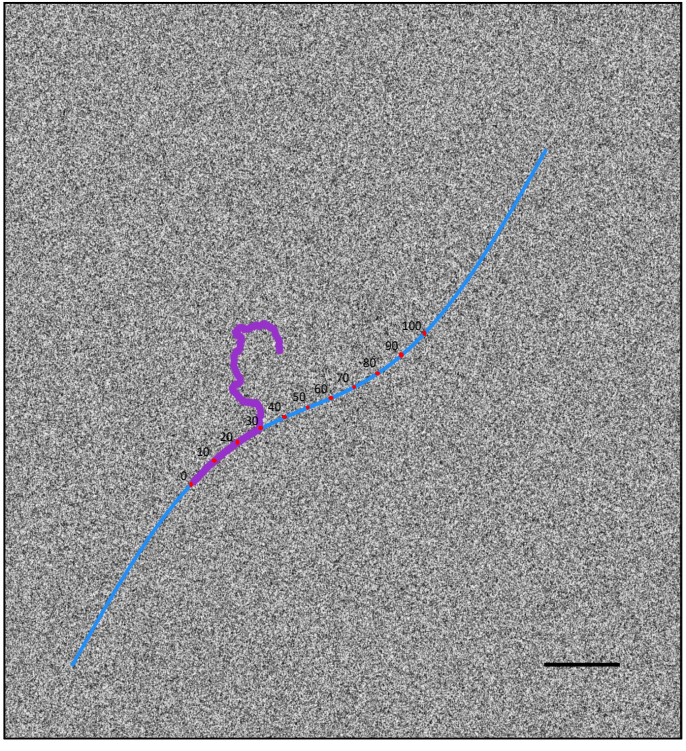


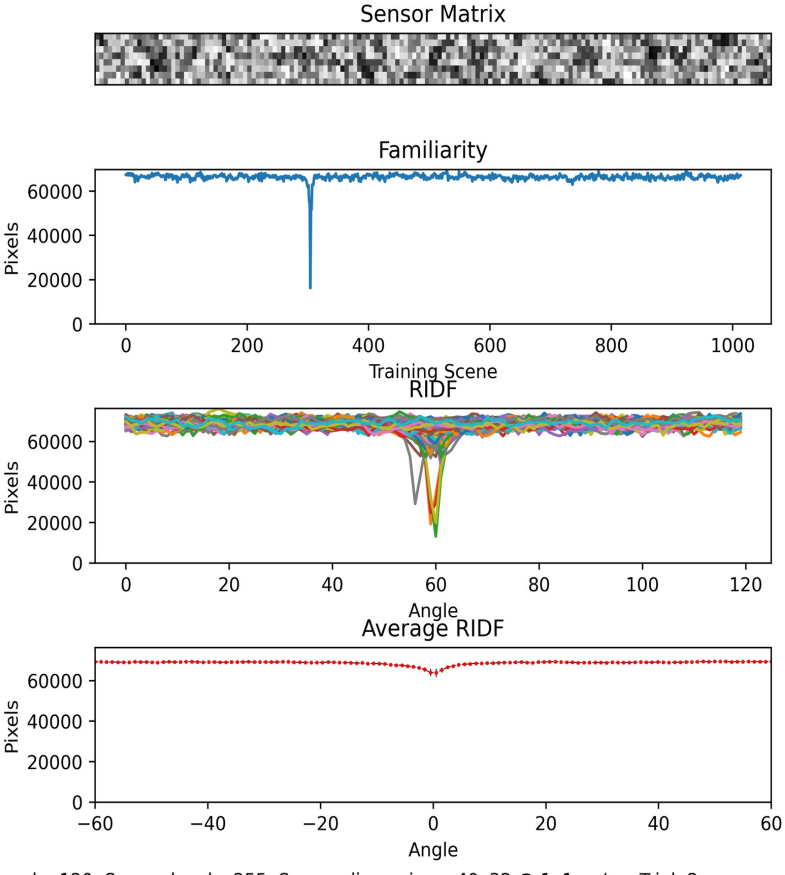


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 56.74; RMSD/dist: 0.142; TD: 17662; p90: 6; p50: 4; complete: 0

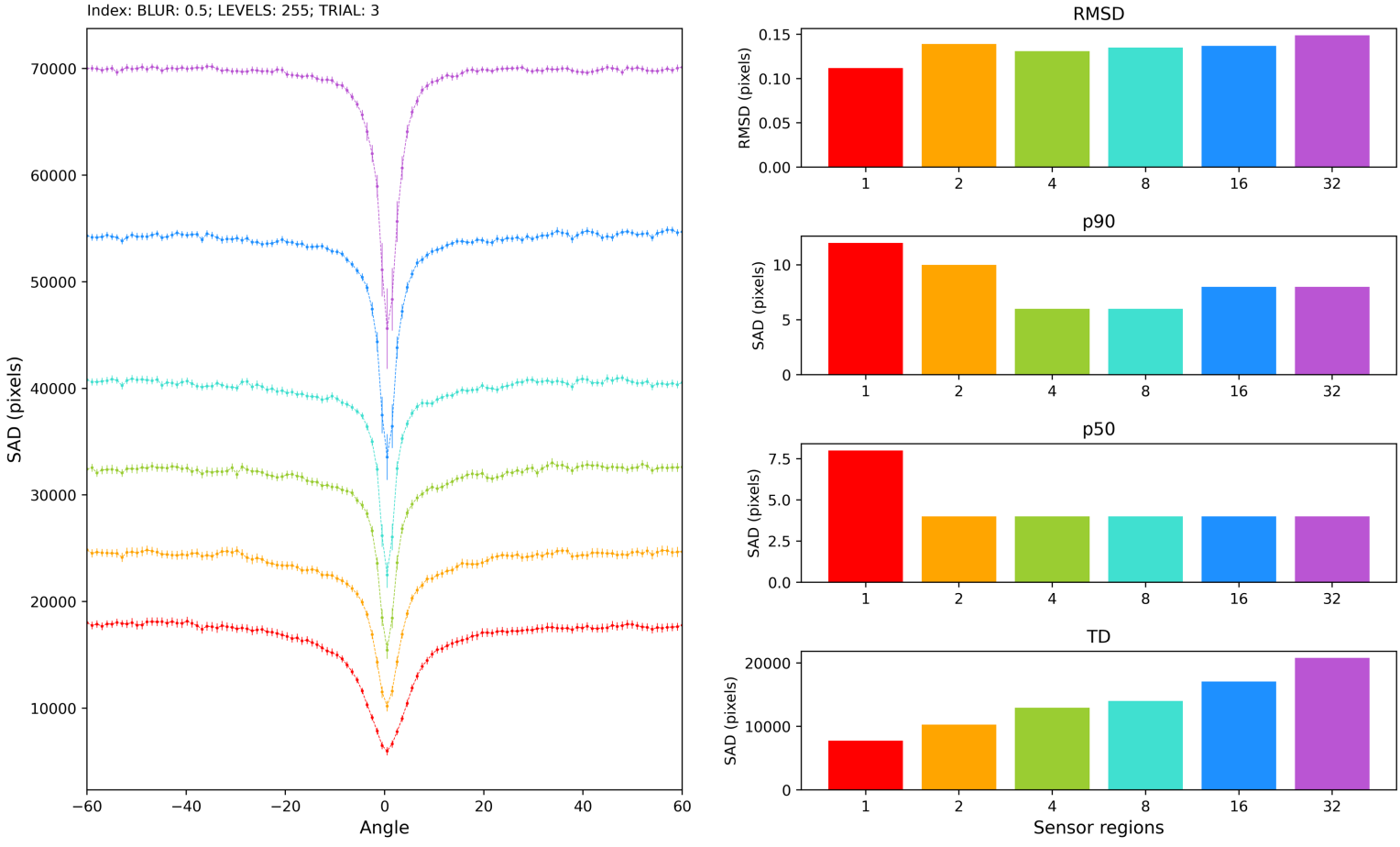
30%



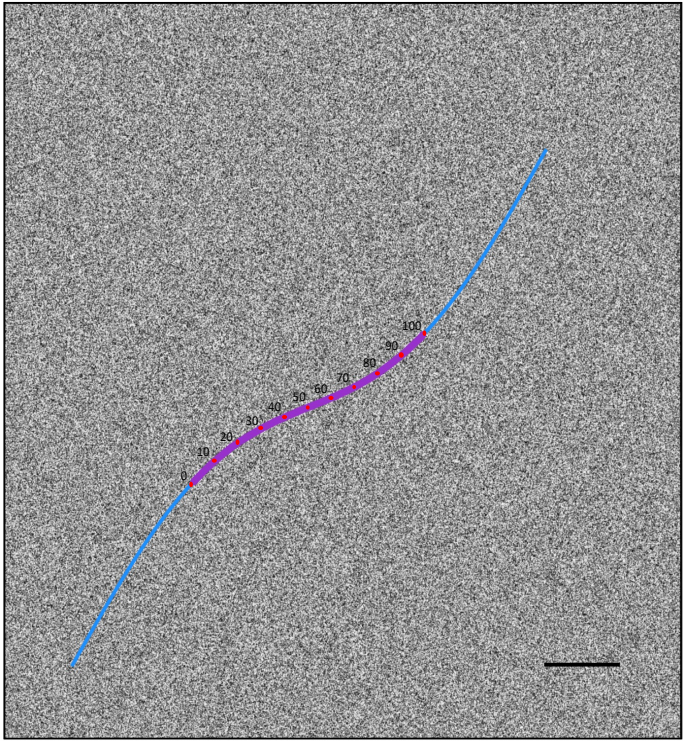


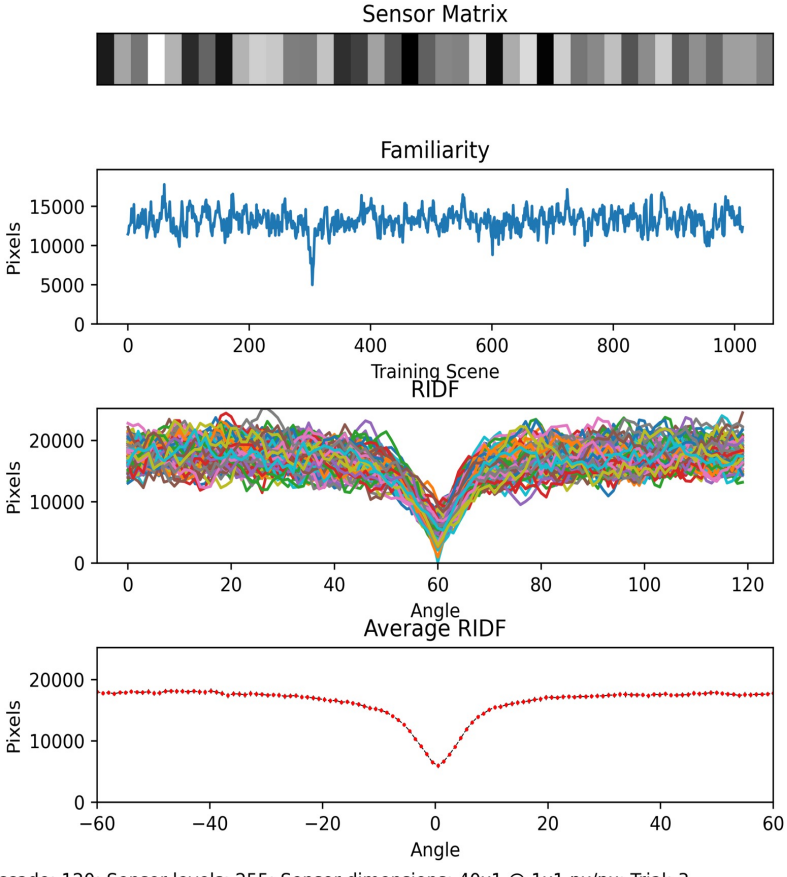
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 6092.43; RMSD/dist: 15.231; TD: 2630; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 255; TRIAL: 3
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

100%

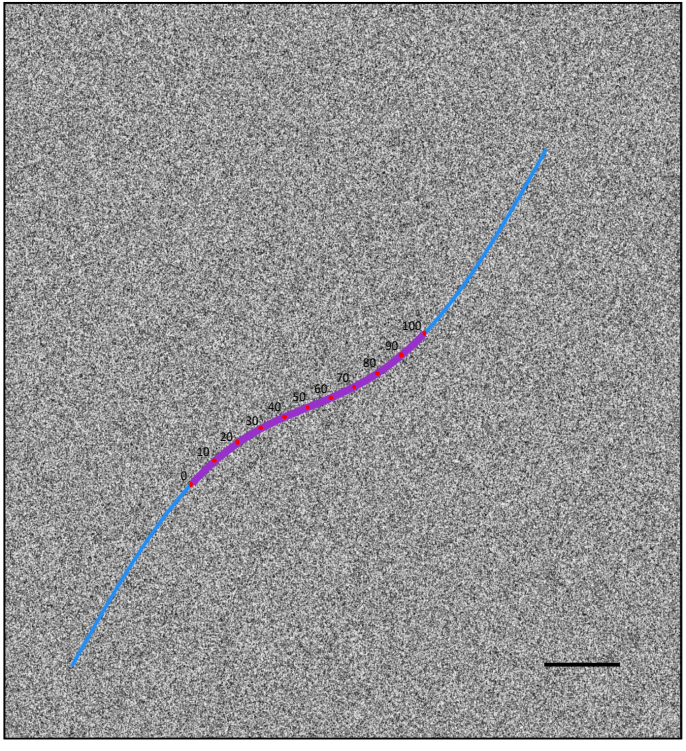


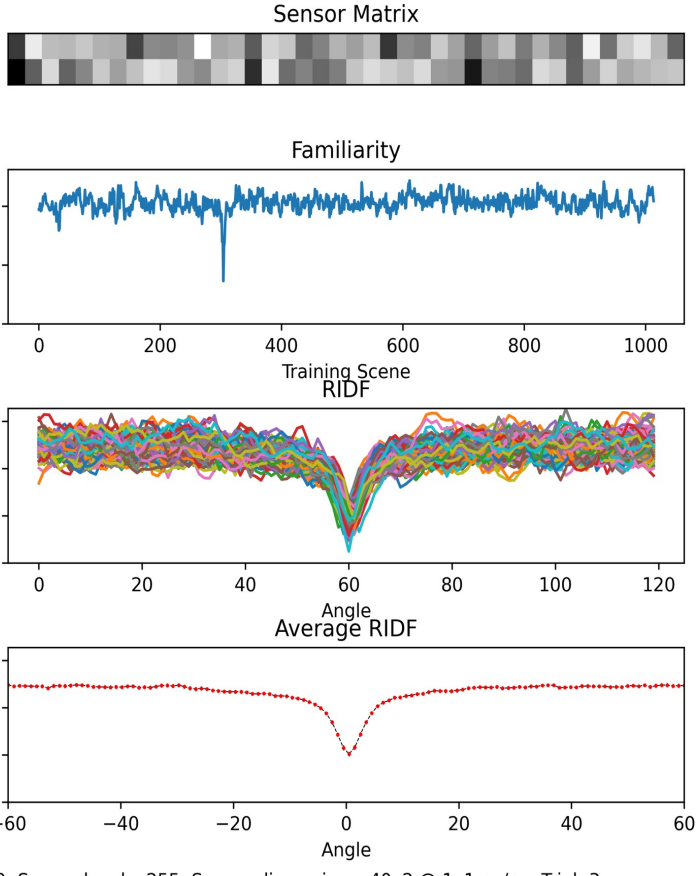


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 44.93; RMSD/dist: 0.112; TD: 7726; p90: 12; p50: 8; complete: 0

100%

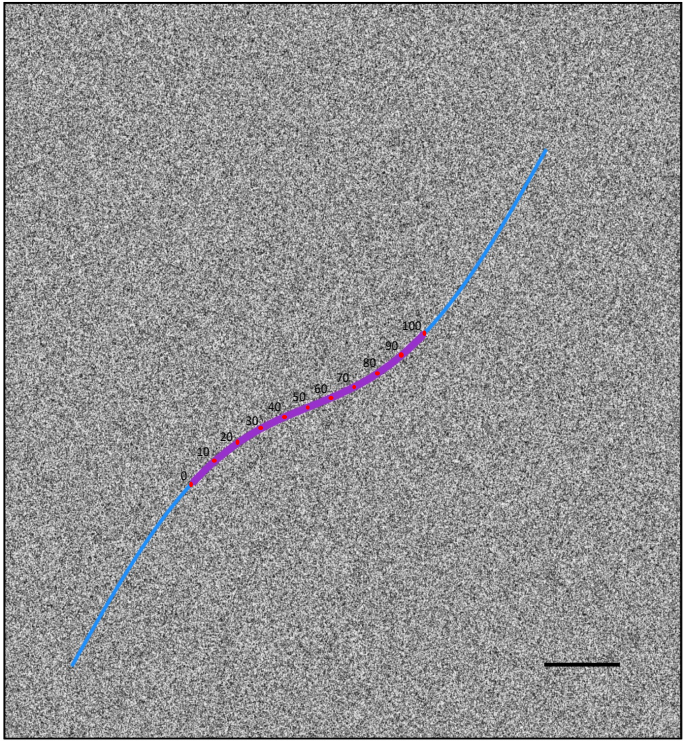


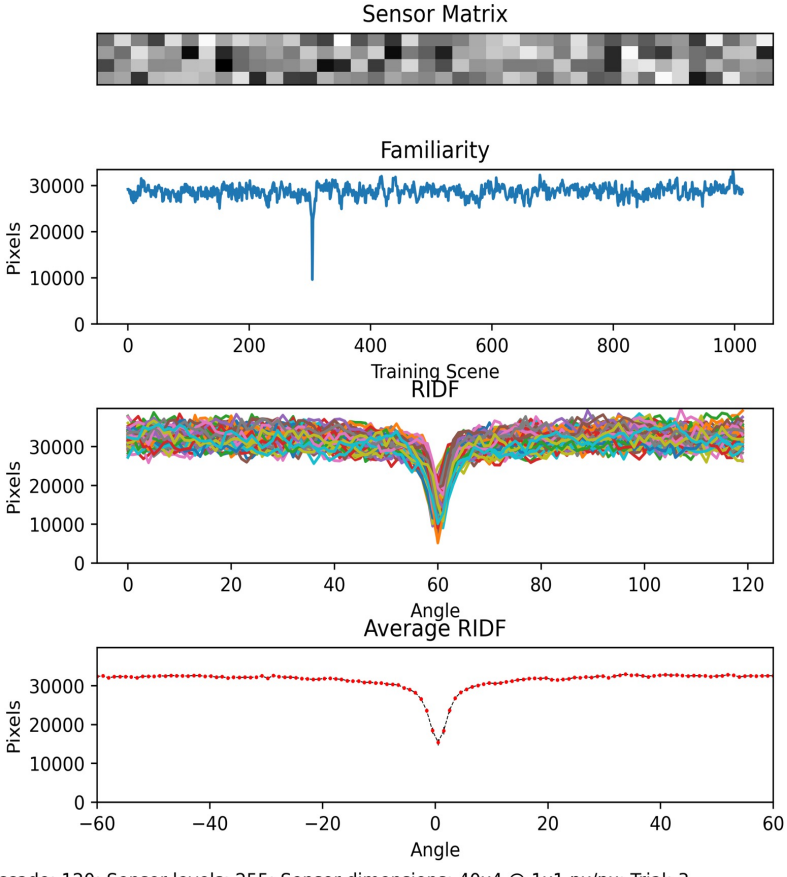


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 55.51; RMSD/dist: 0.139; TD: 10277; p90: 10; p50: 4; complete: 0

100%

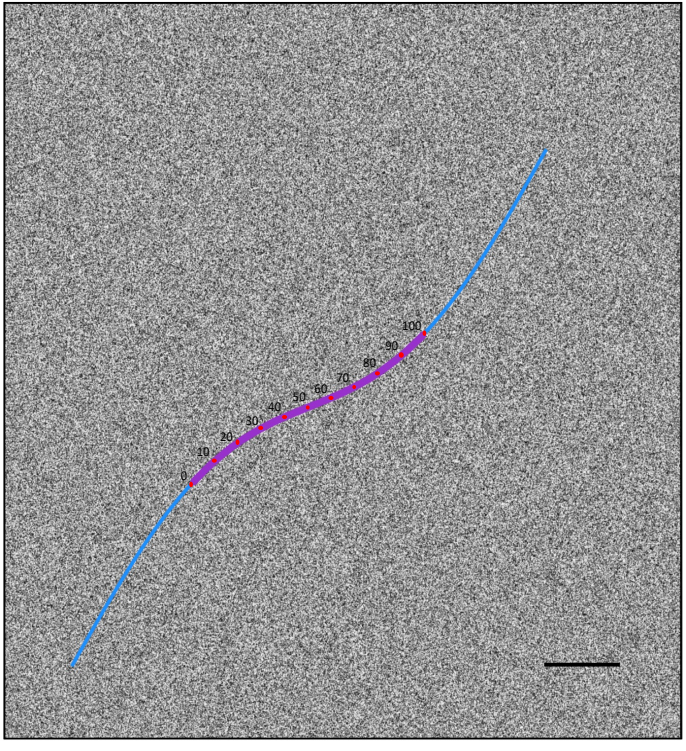


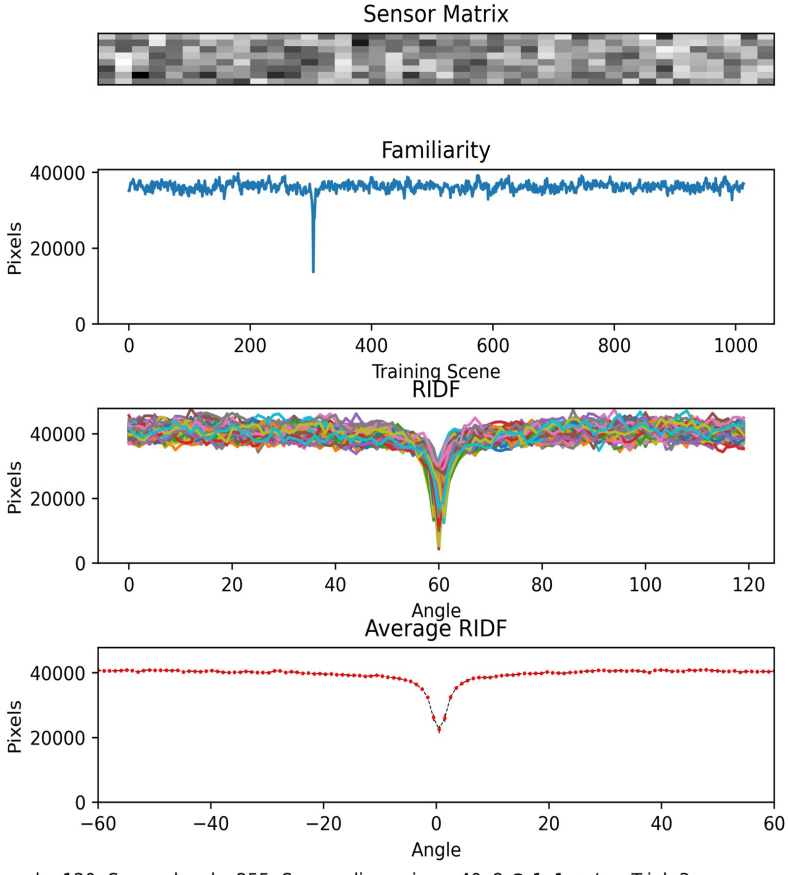


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 52.21; RMSD/dist: 0.131; TD: 12935; p90: 6; p50: 4; complete: 0

100%

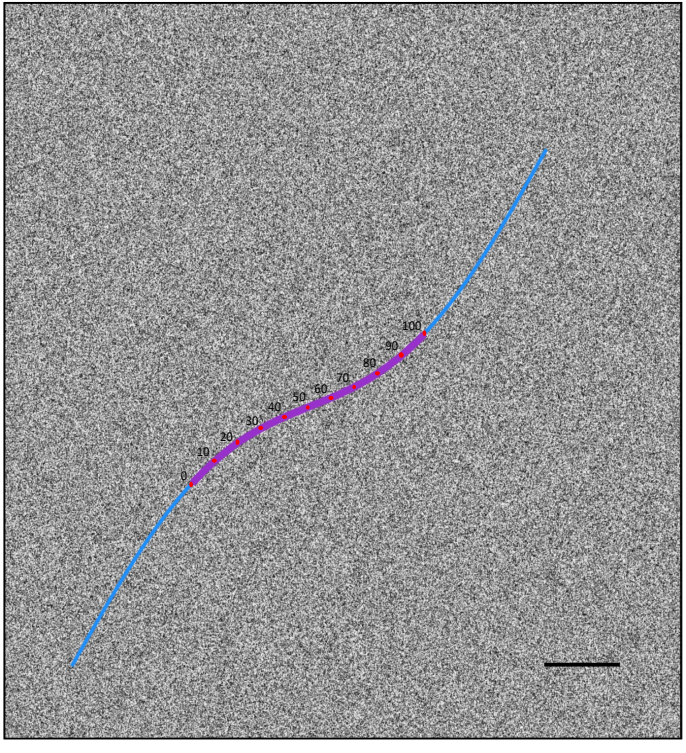


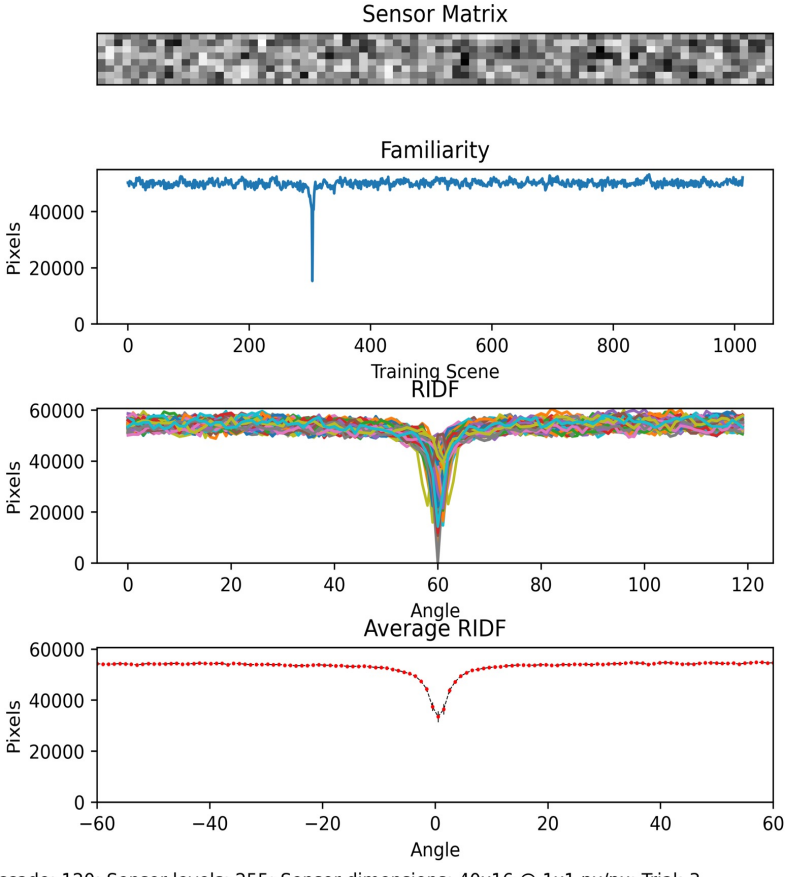


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 54.12; RMSD/dist: 0.135; TD: 14008; p90: 6; p50: 4; complete: 0

100%

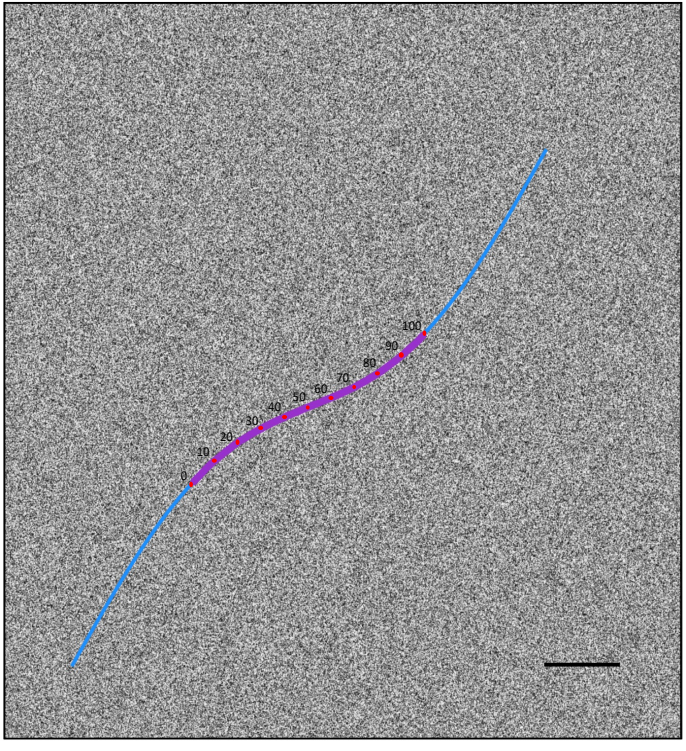


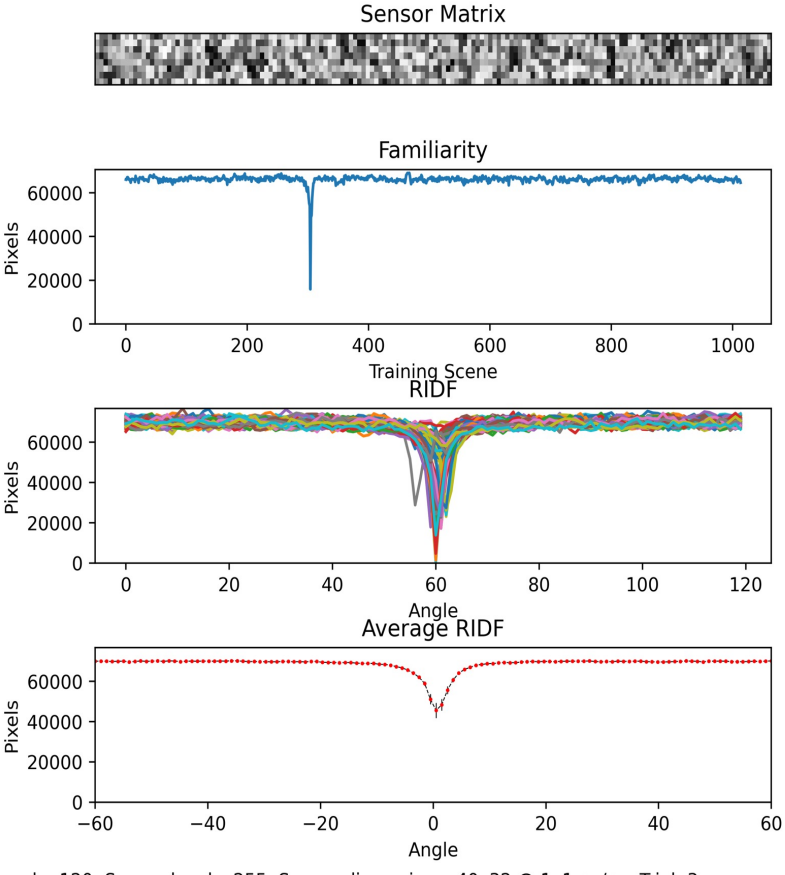


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 54.97; RMSD/dist: 0.137; TD: 17059; p90: 8; p50: 4; complete: 0

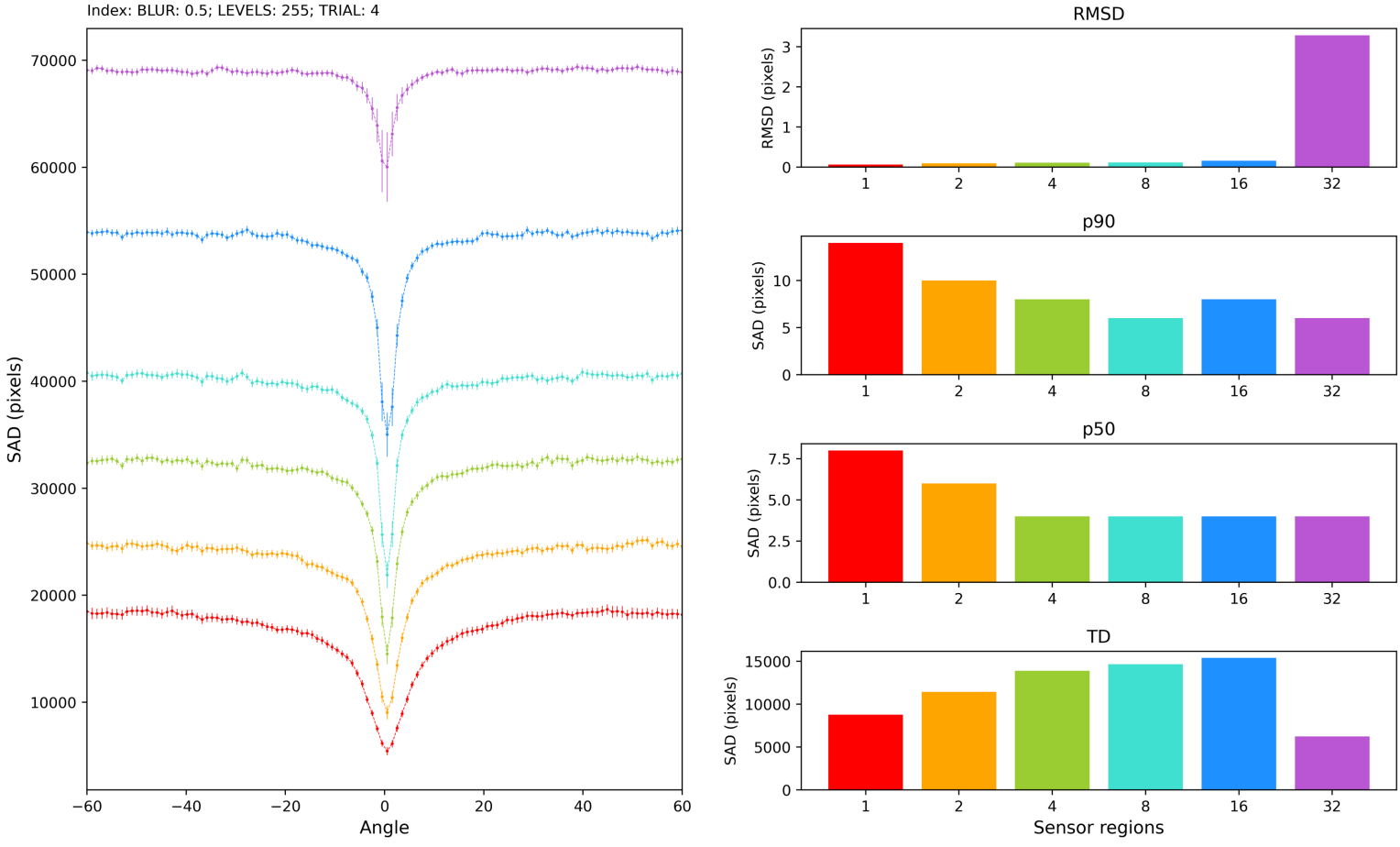
100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 59.42; RMSD/dist: 0.149; TD: 20771; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 255; TRIAL: 4
SAD (pixels)
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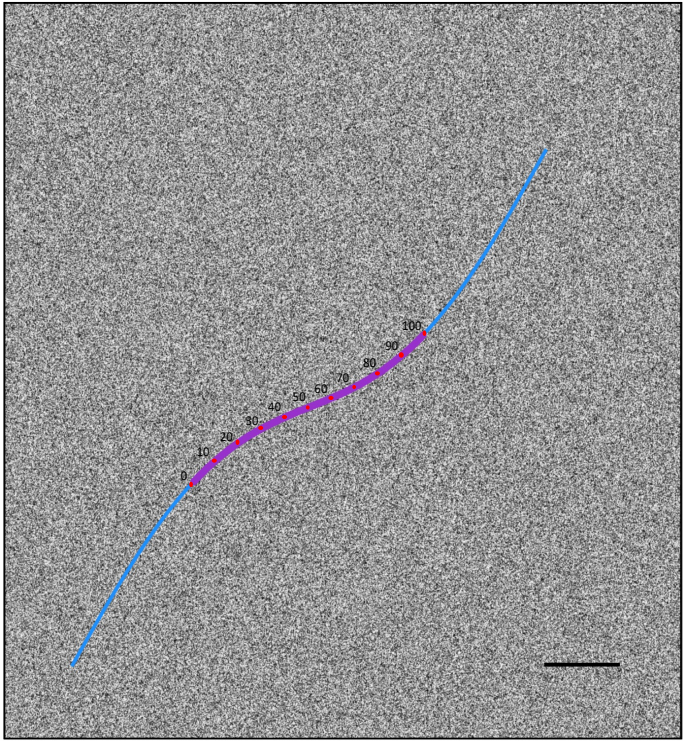
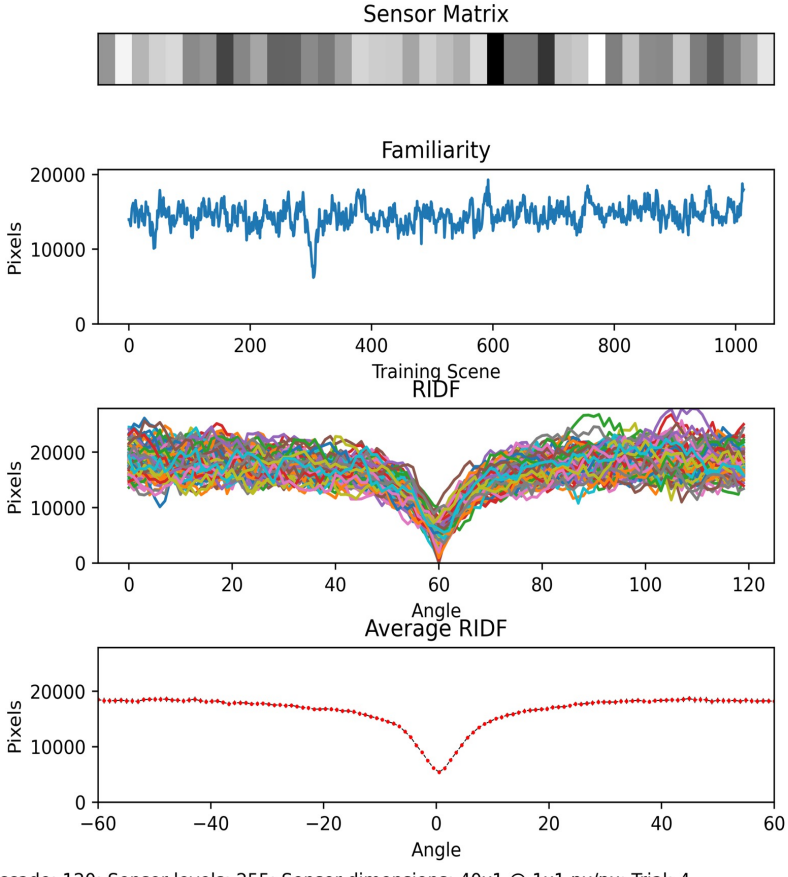
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0
1
2
3
1
2
4
8
16
32
p90
SAD (pixels)
0
5
10
1
2
4
8
16
32
p50
SAD (pixels)
0.0
2.5
5.0
7.5
1
2
4
8
16
32
TD
SAD (pixels)
0
5000
10000
15000
1
2
4
8
16
32
Sensor regions

100%

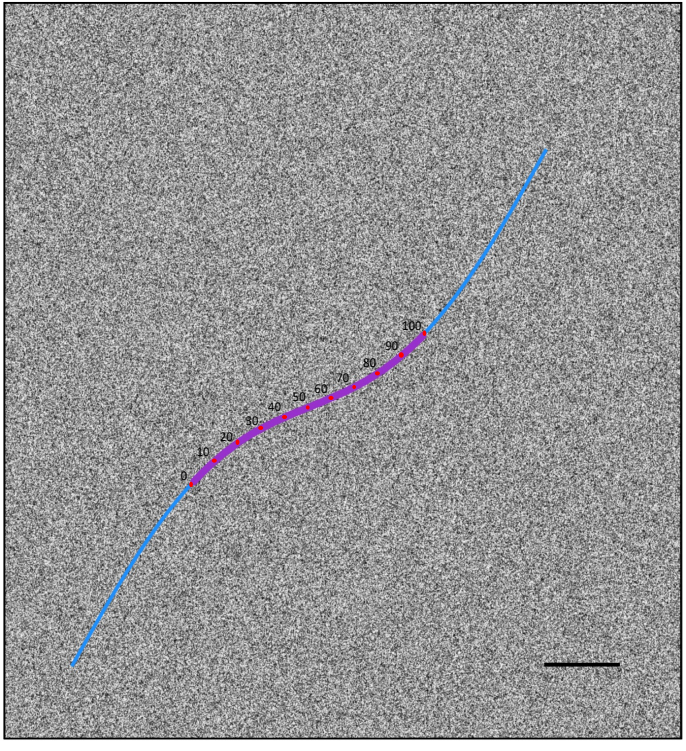


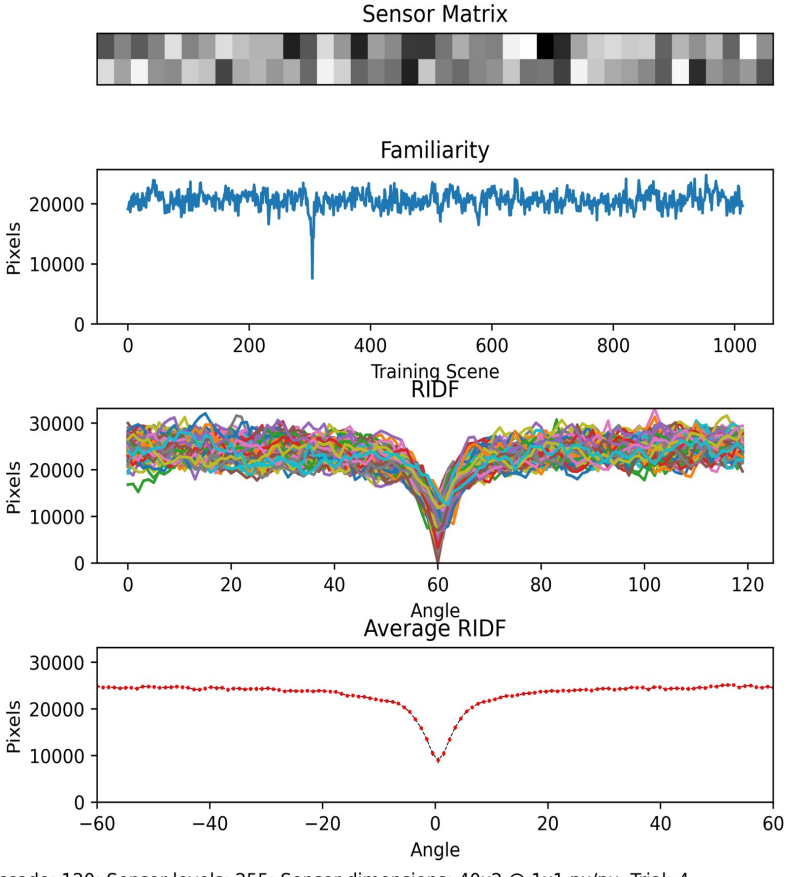


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 23.97; RMSD/dist: 0.060; TD: 8759; p90: 14; p50: 8; complete: 0

100%

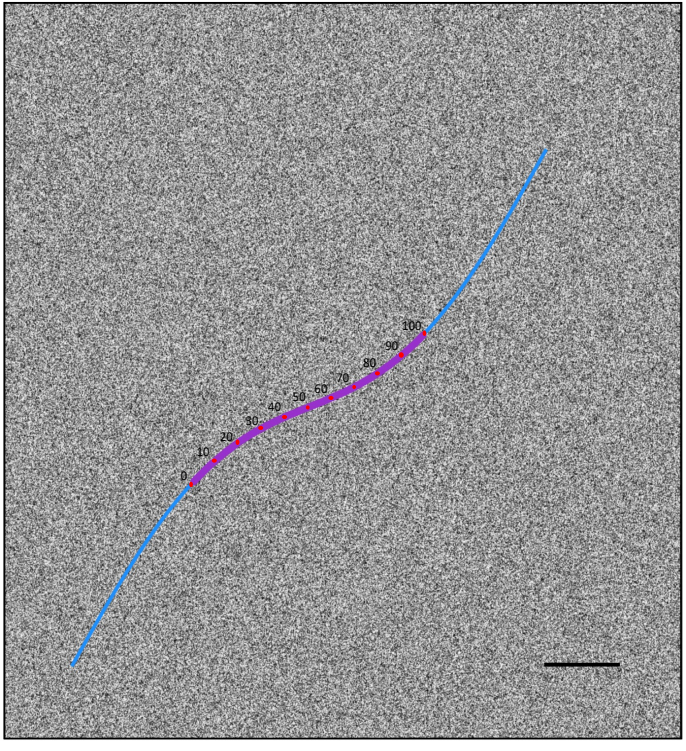


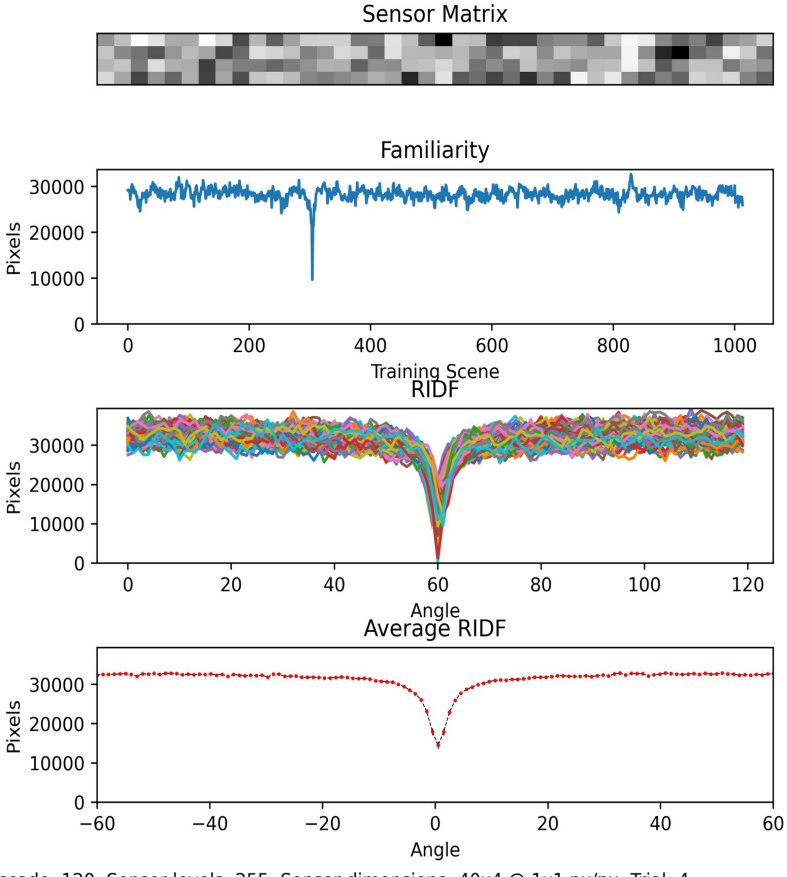


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 37.14; RMSD/dist: 0.093; TD: 11434; p90: 10; p50: 6; complete: 0

100%

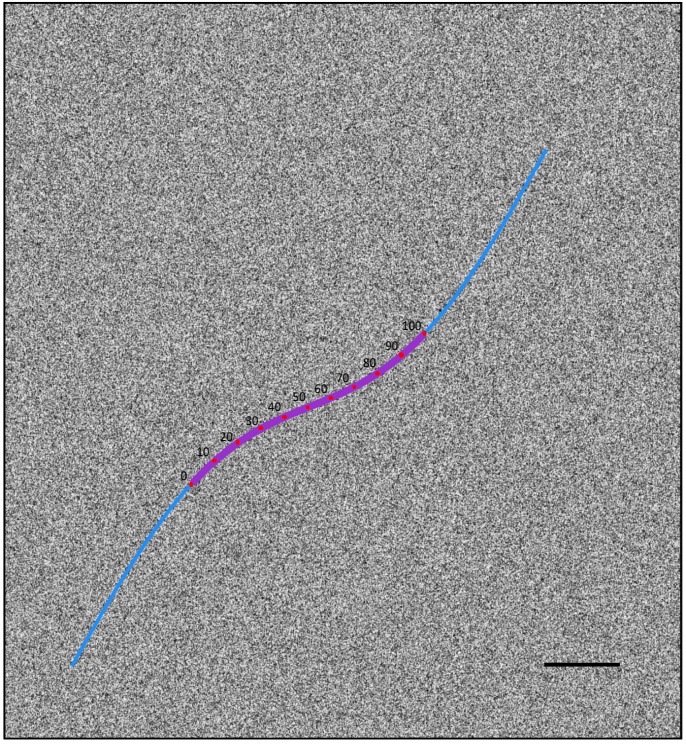


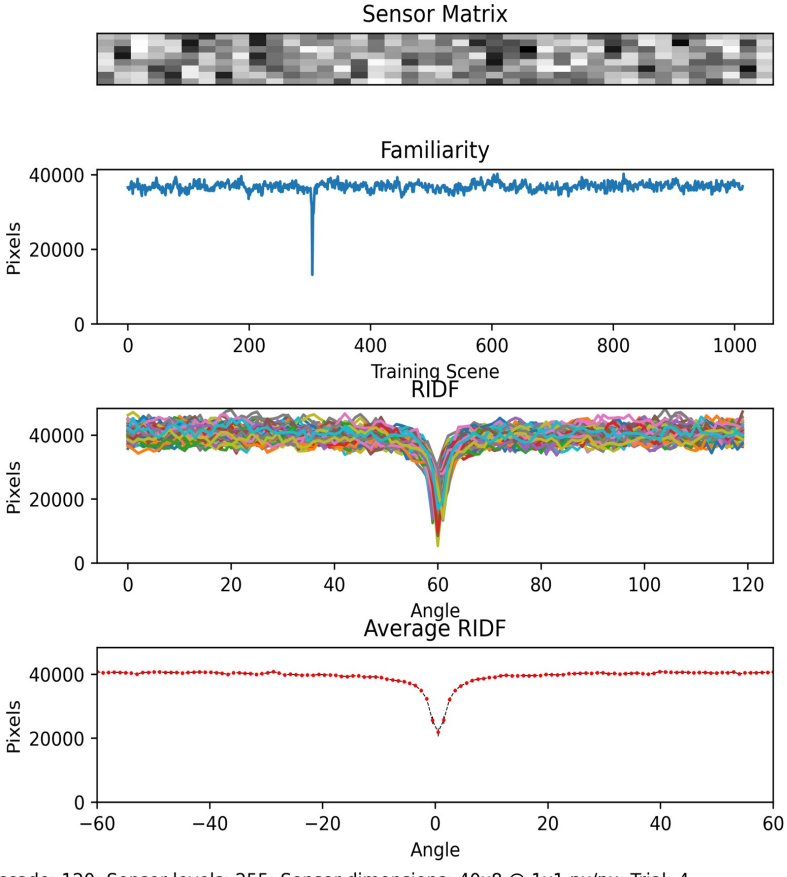


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 42.82; RMSD/dist: 0.107; TD: 13884; p90: 8; p50: 4; complete: 0

100%

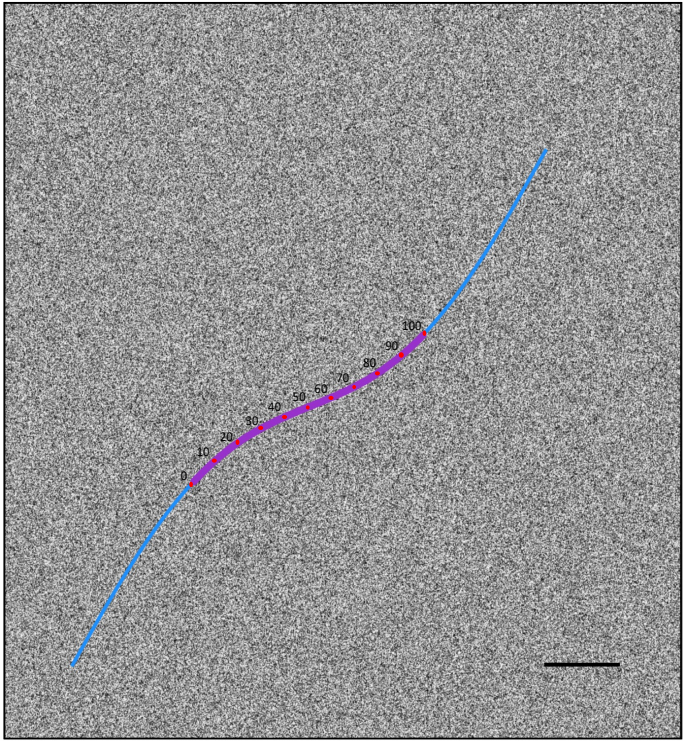


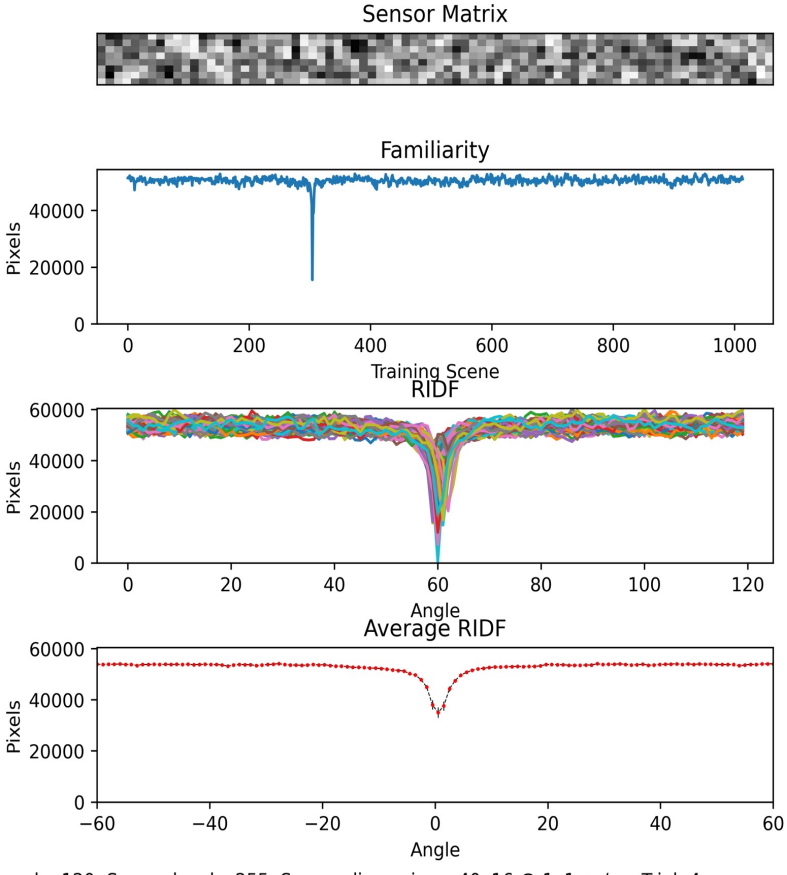


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 45.96; RMSD/dist: 0.115; TD: 14637; p90: 6; p50: 4; complete: 0

100%

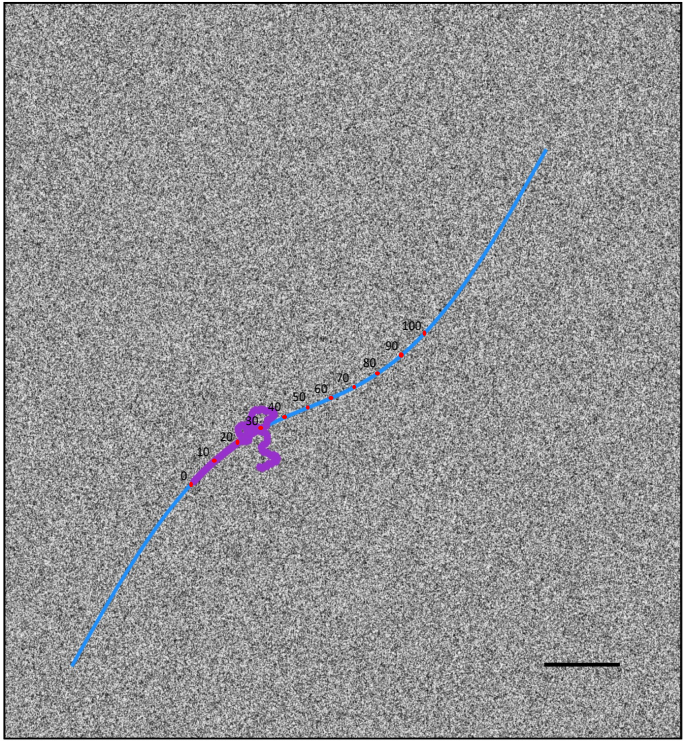


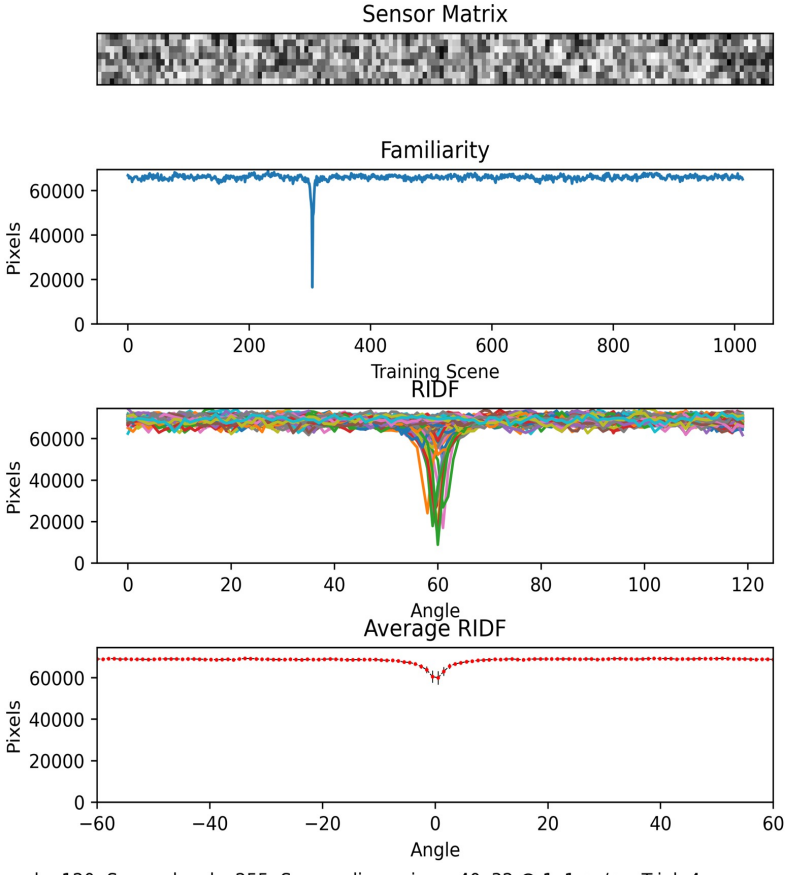


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 61.43; RMSD/dist: 0.154; TD: 15376; p90: 8; p50: 4; complete: 0

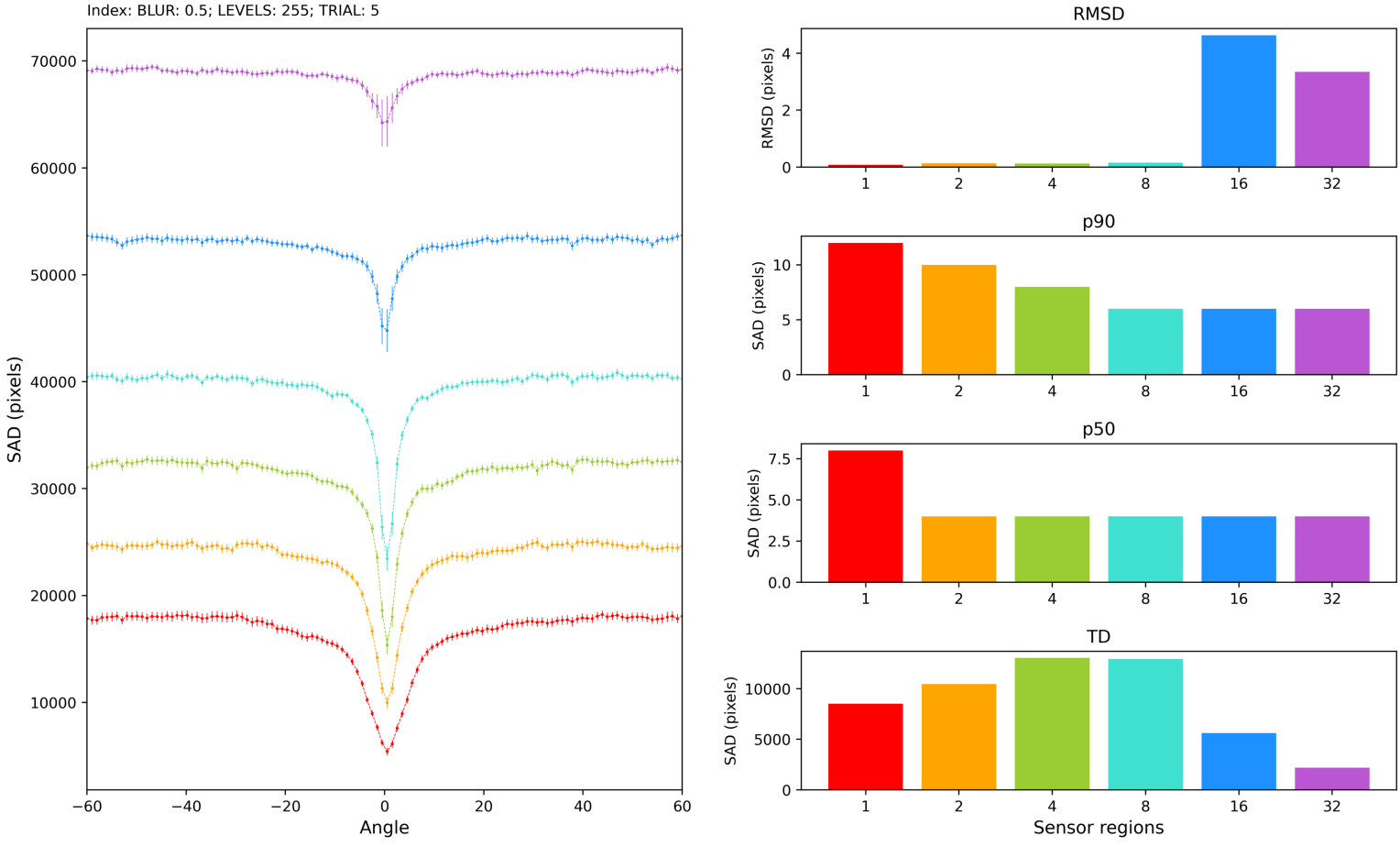
30%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1314.68; RMSD/dist: 3.287; TD: 6213; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 255; TRIAL: 5
SAD (pixels)
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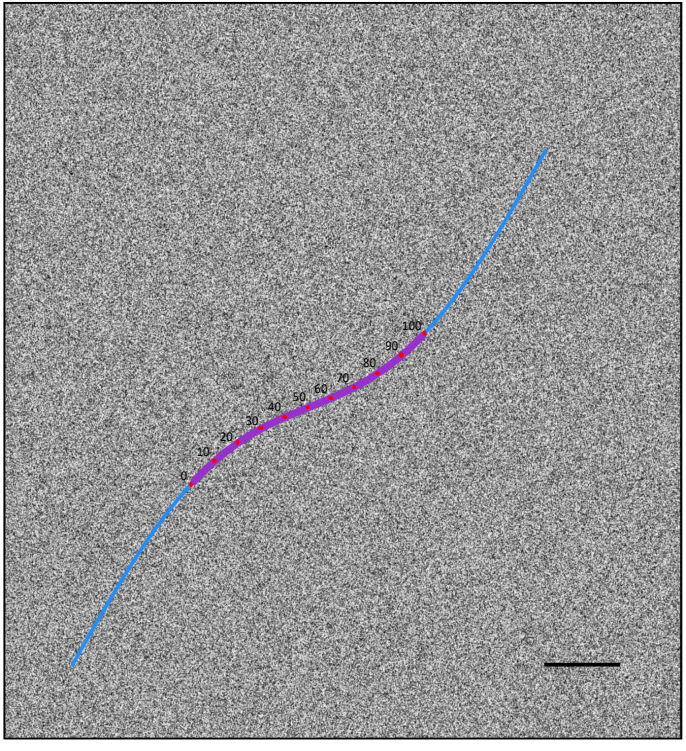
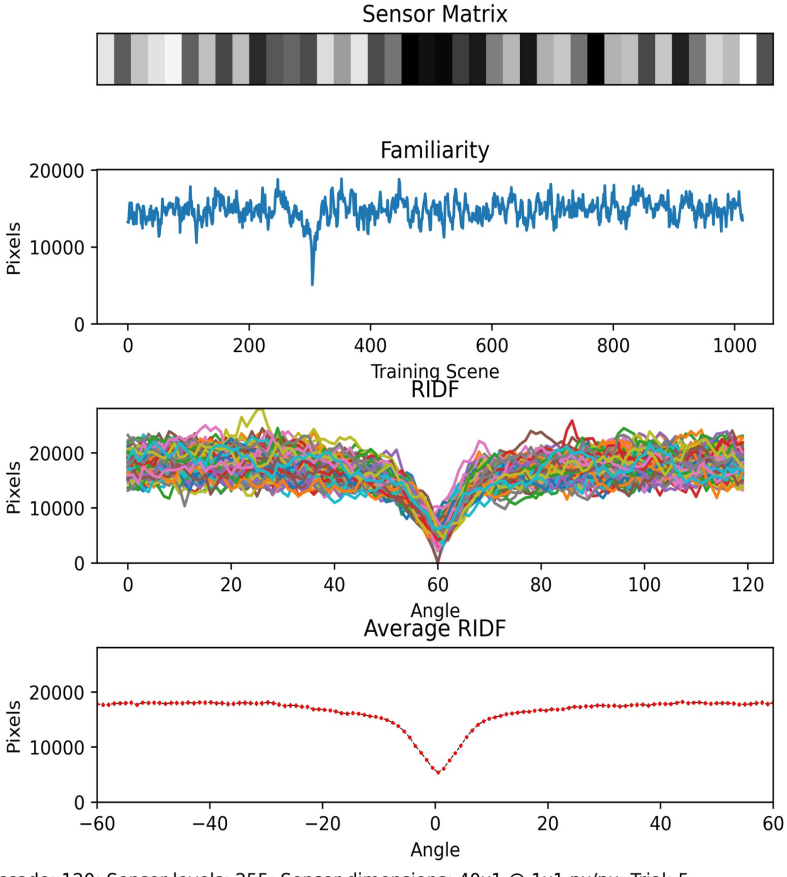
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
10000
5000
0
Sensor regions

100%

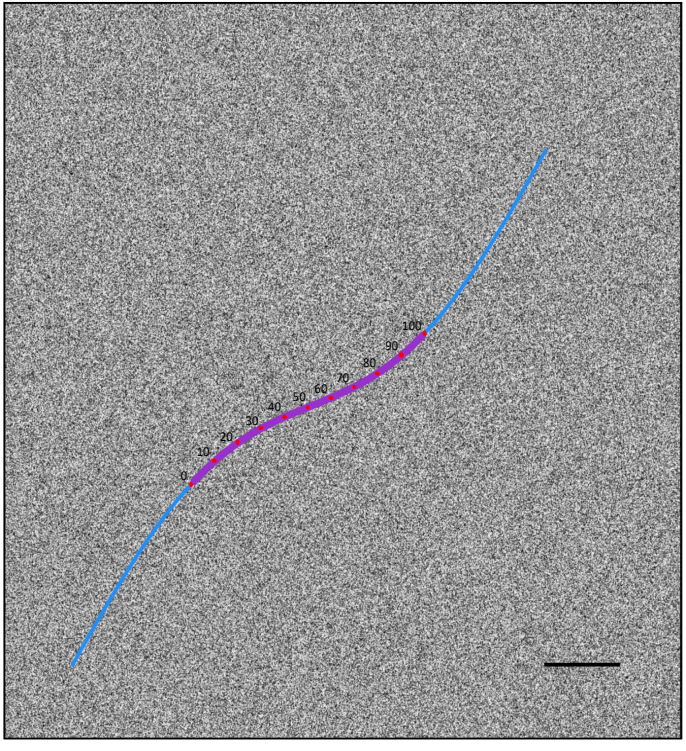


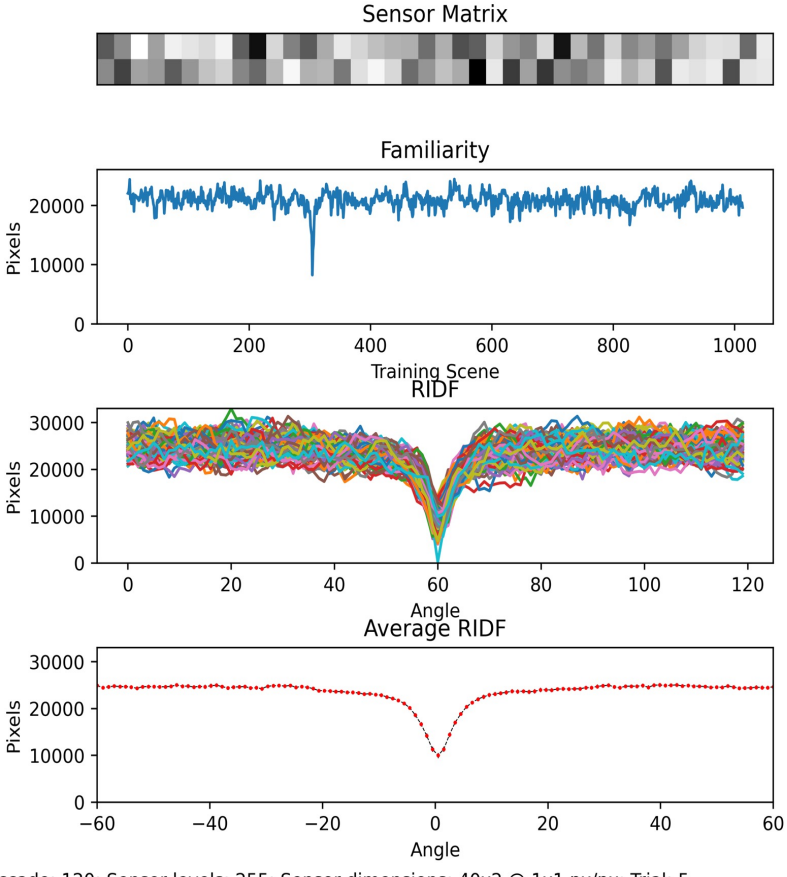


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 31.17; RMSD/dist: 0.078; TD: 8523; p90: 12; p50: 8; complete: 0

100%

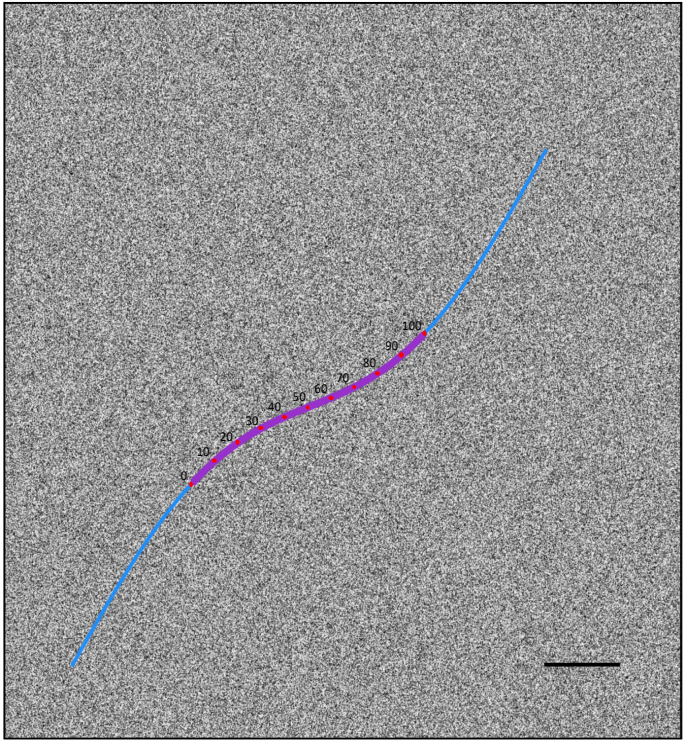


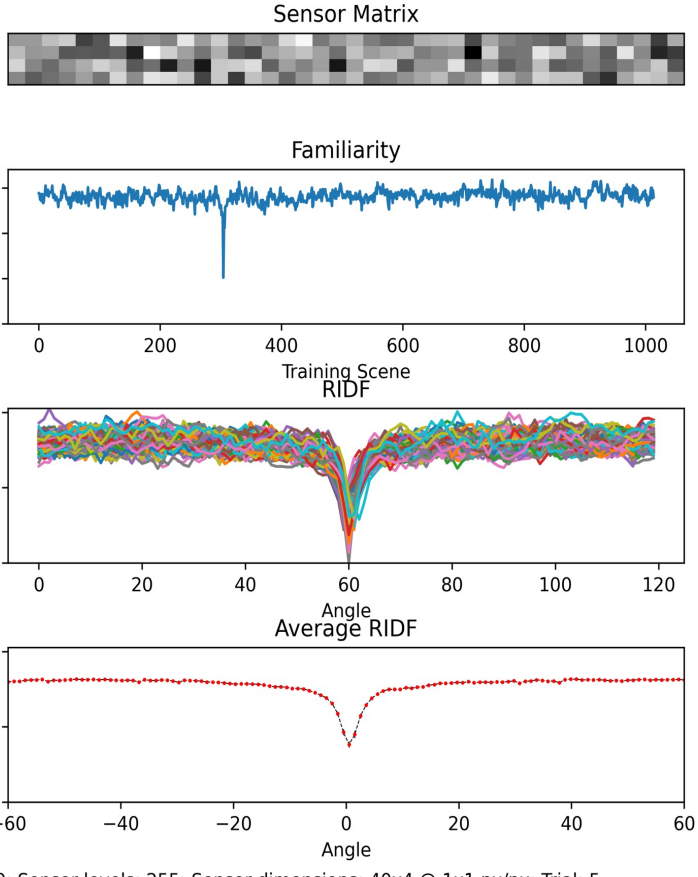


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 52.75; RMSD/dist: 0.132; TD: 10456; p90: 10; p50: 4; complete: 0

100%

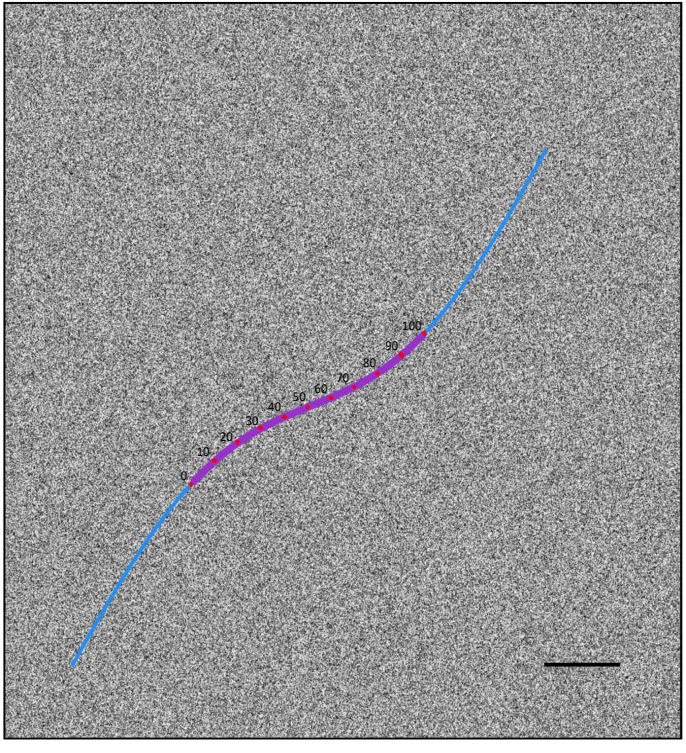


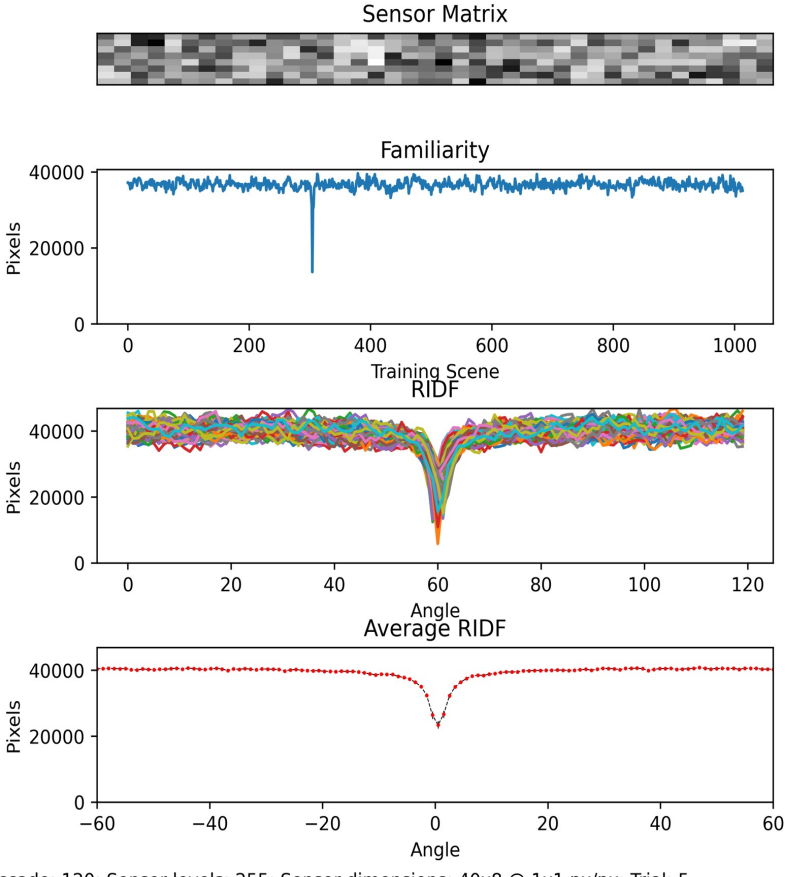


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 50.03; RMSD/dist: 0.125; TD: 13048; p90: 8; p50: 4; complete: 0

100%

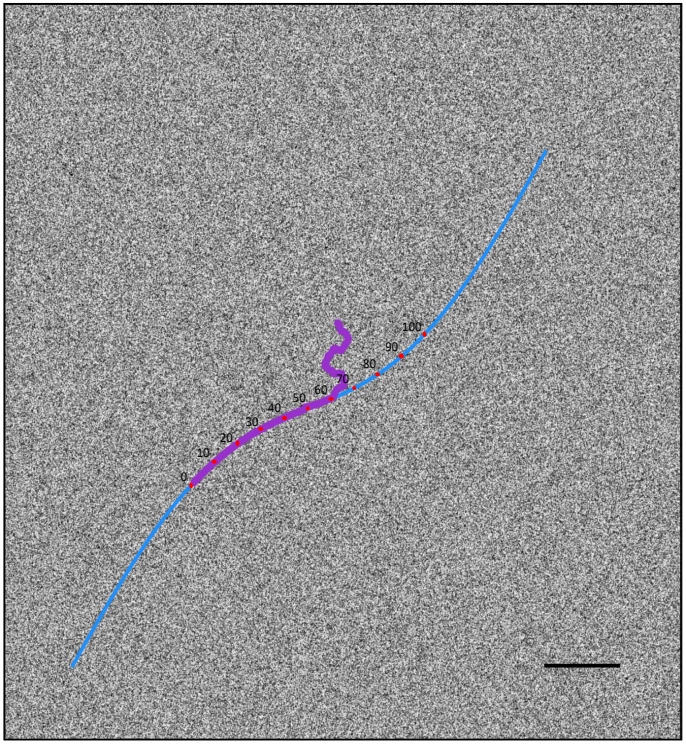


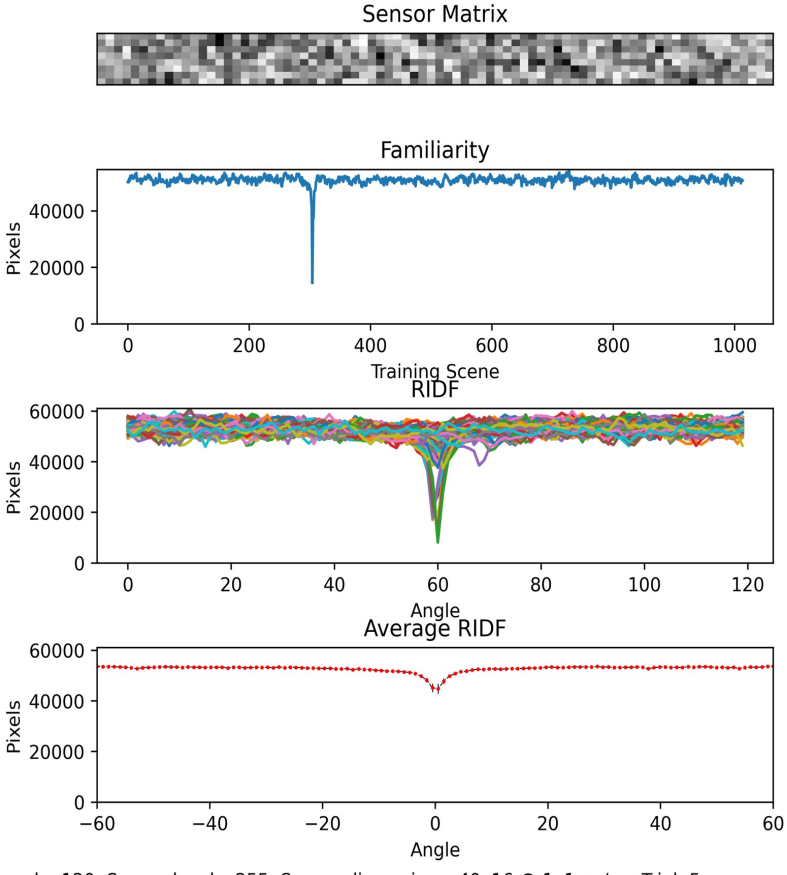


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 62.01; RMSD/dist: 0.155; TD: 12952; p90: 6; p50: 4; complete: 0

60%

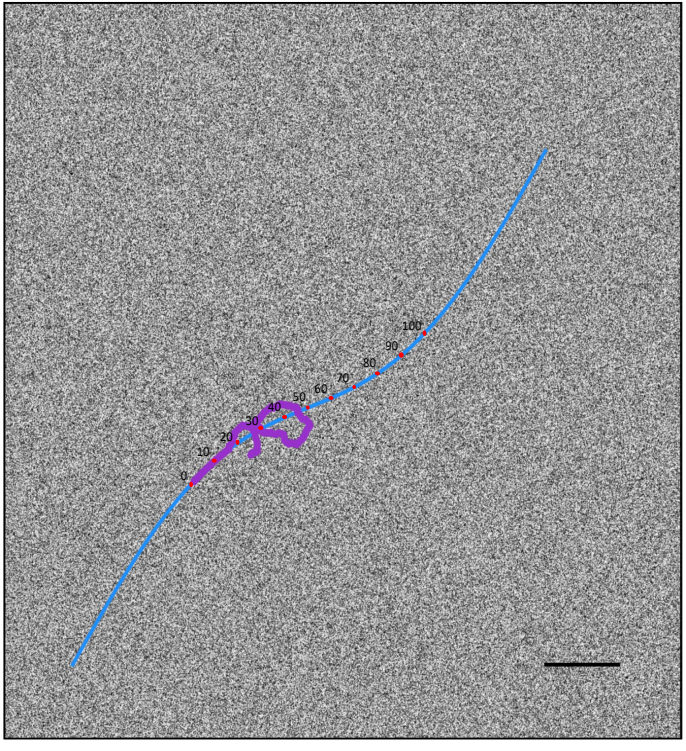


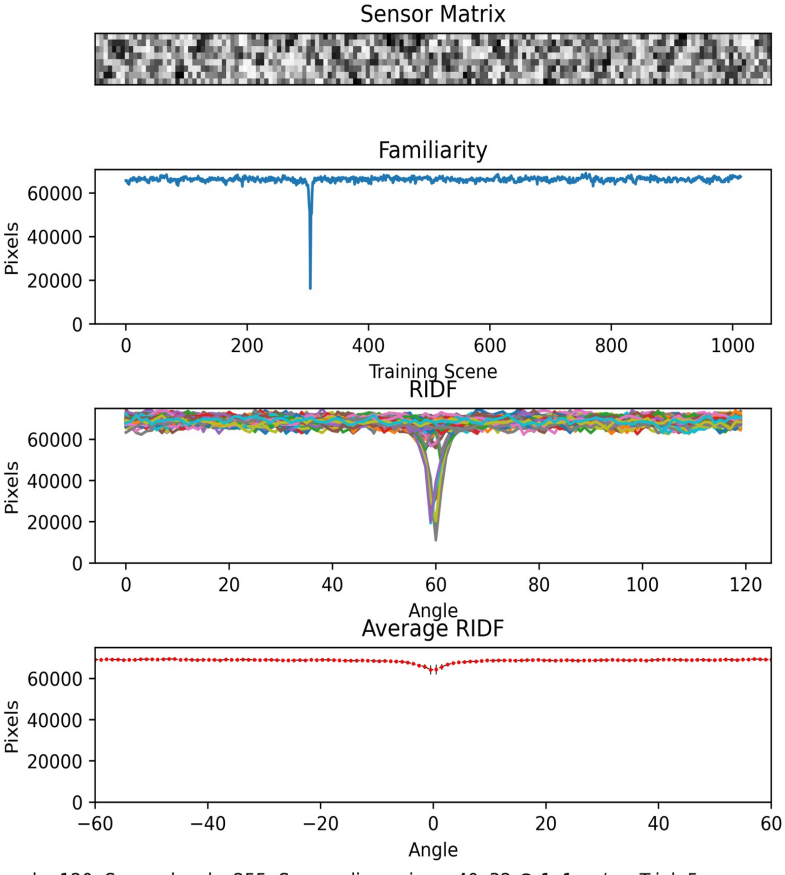


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1854.01; RMSD/dist: 4.635; TD: 5626; p90: 6; p50: 4; complete: 0

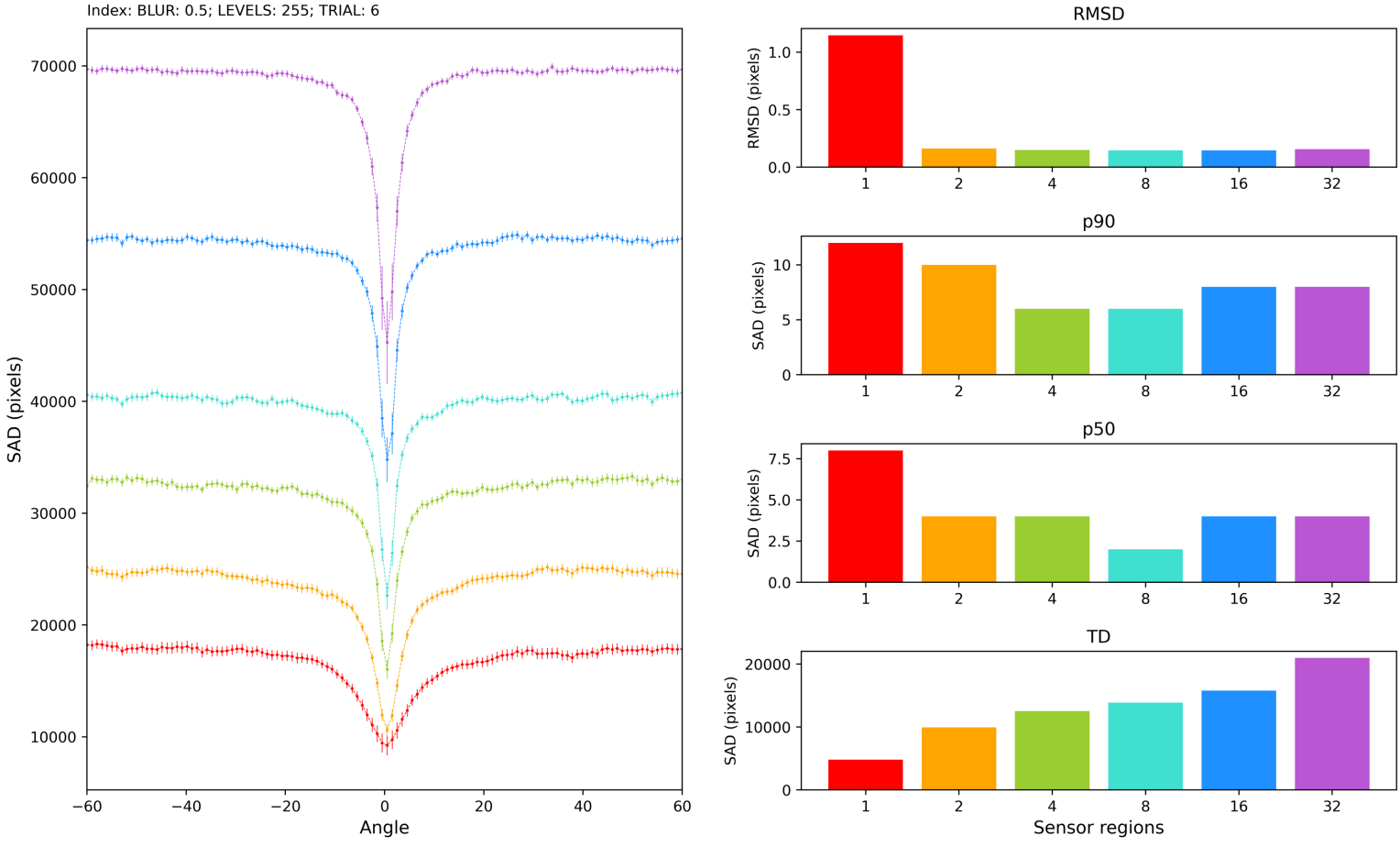
10%



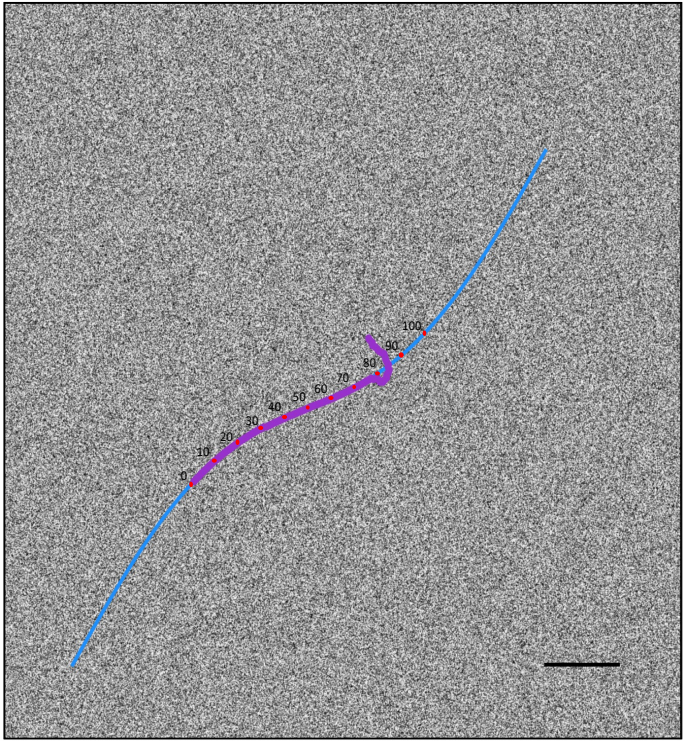


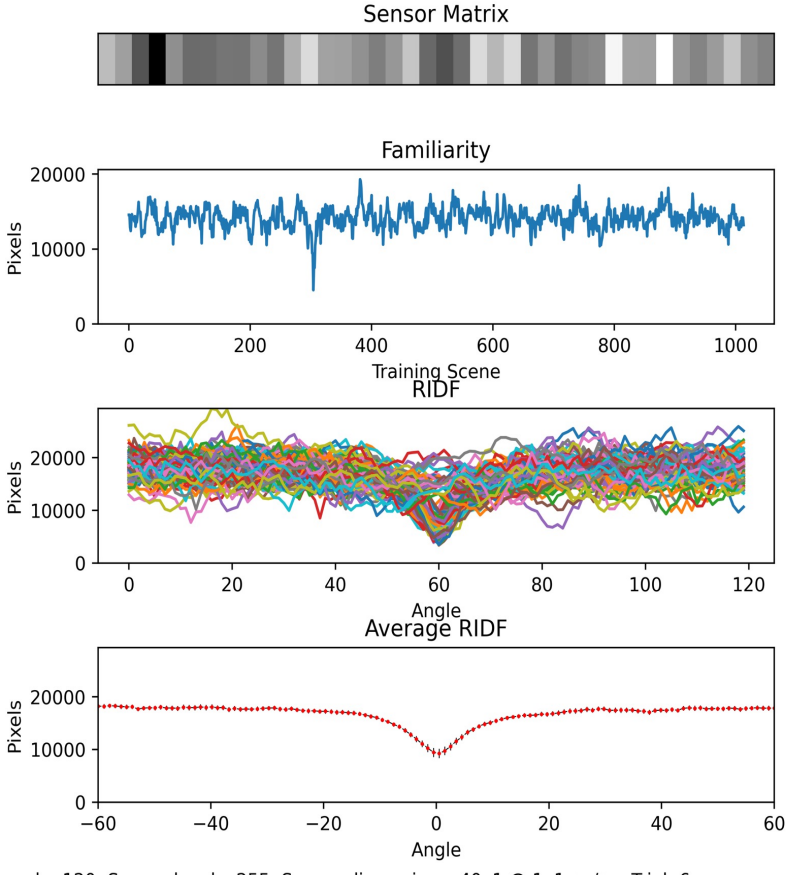
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1339.40; RMSD/dist: 3.349; TD: 2188; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 255; TRIAL: 6
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
1.0
0.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

70%

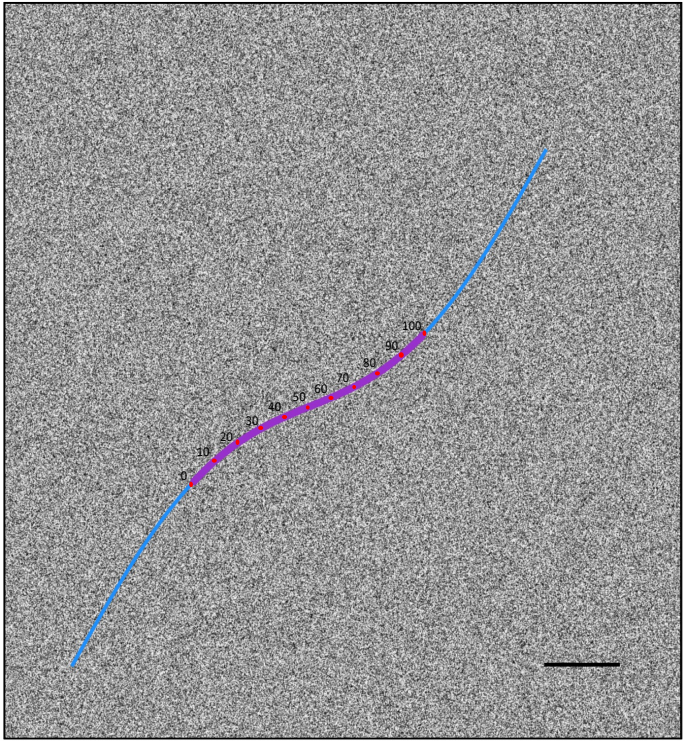


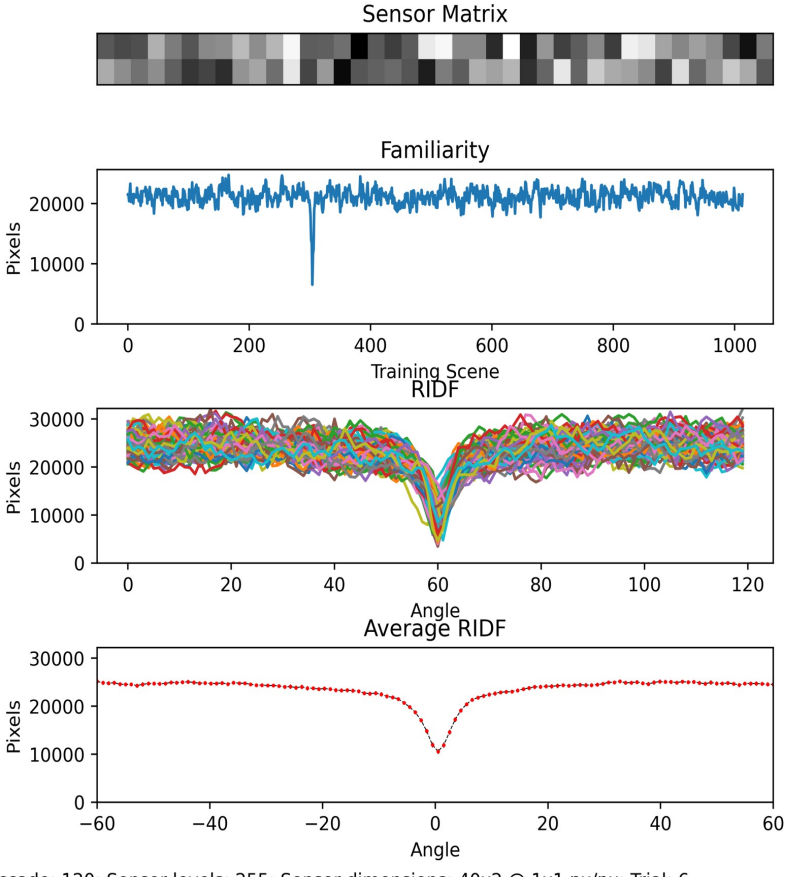


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 458.74; RMSD/dist: 1.147; TD: 4776; p90: 12; p50: 8; complete: 0

100%

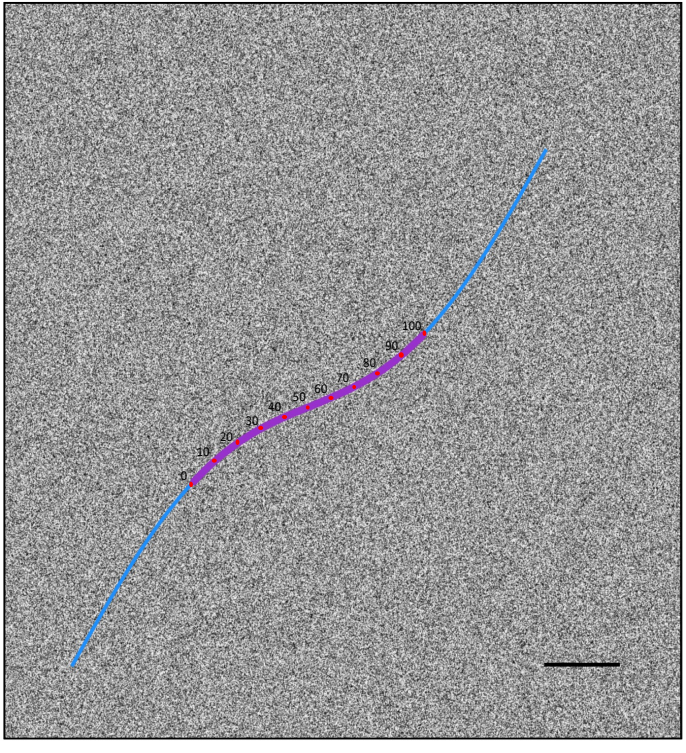


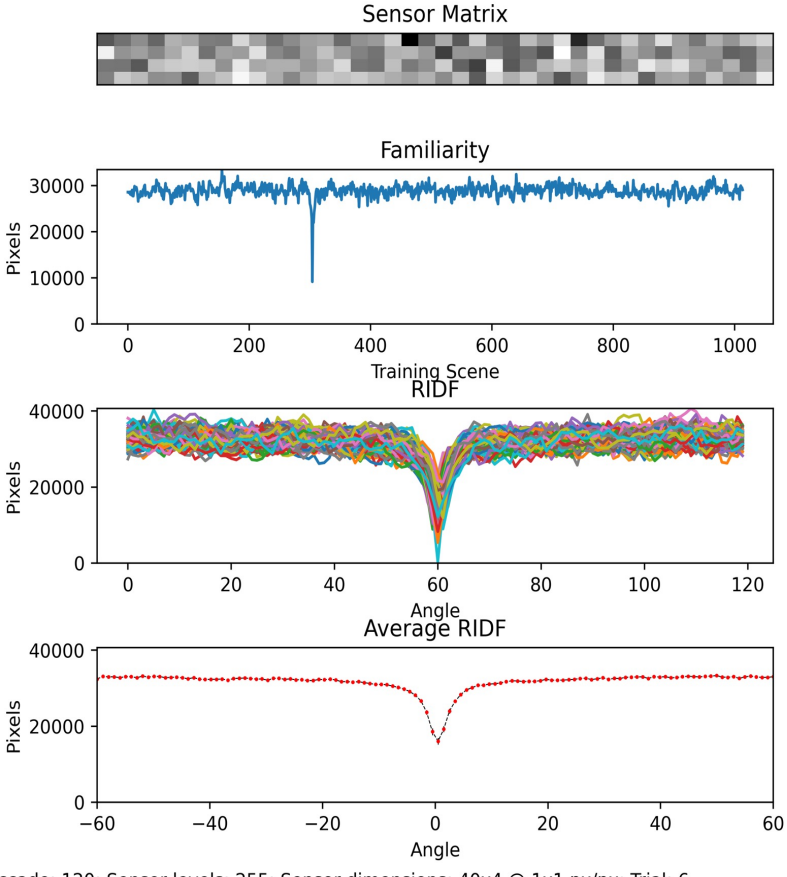


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 64.37; RMSD/dist: 0.161; TD: 9932; p90: 10; p50: 4; complete: 0

100%

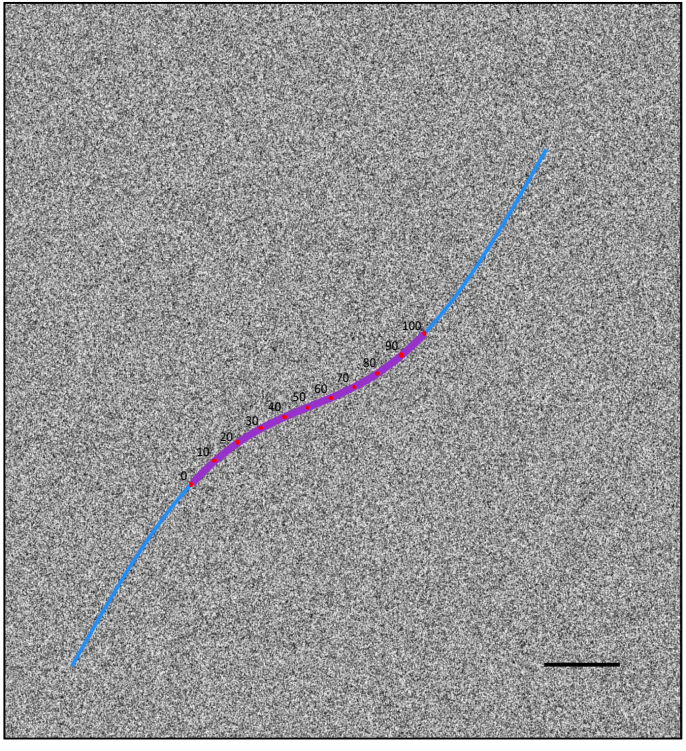


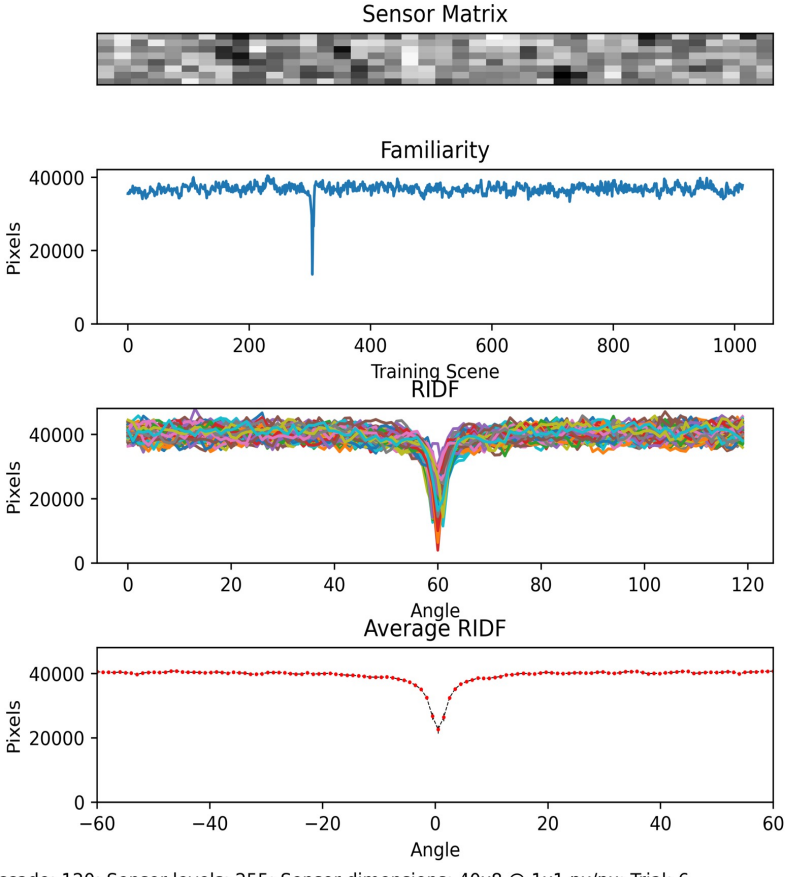


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 59.32; RMSD/dist: 0.148; TD: 12515; p90: 6; p50: 4; complete: 0

100%

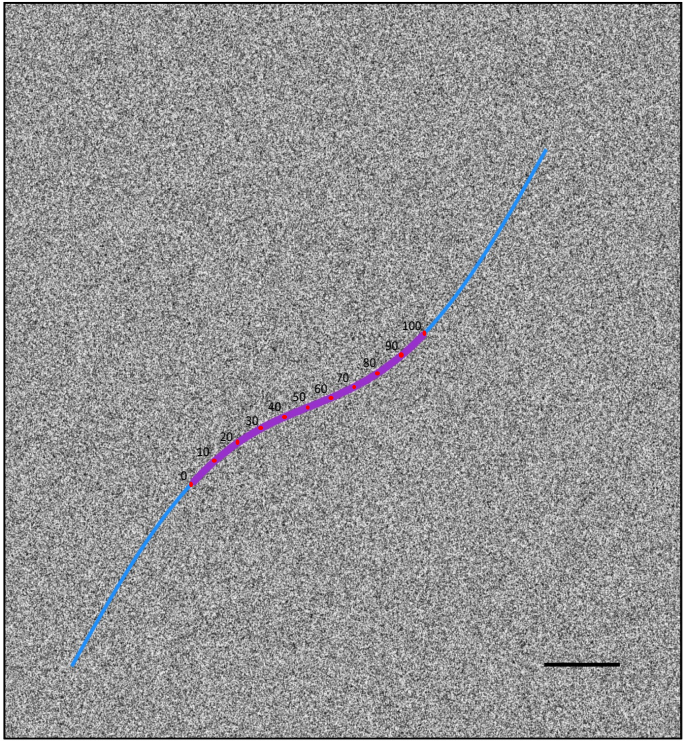


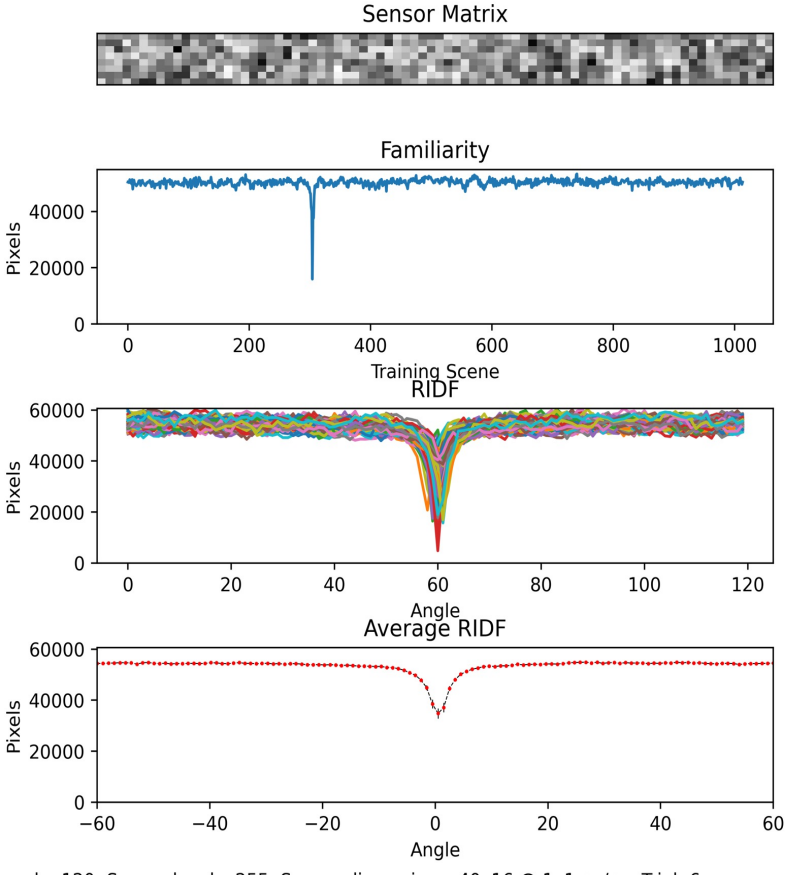


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 57.75; RMSD/dist: 0.144; TD: 13882; p90: 6; p50: 2; complete: 0

100%

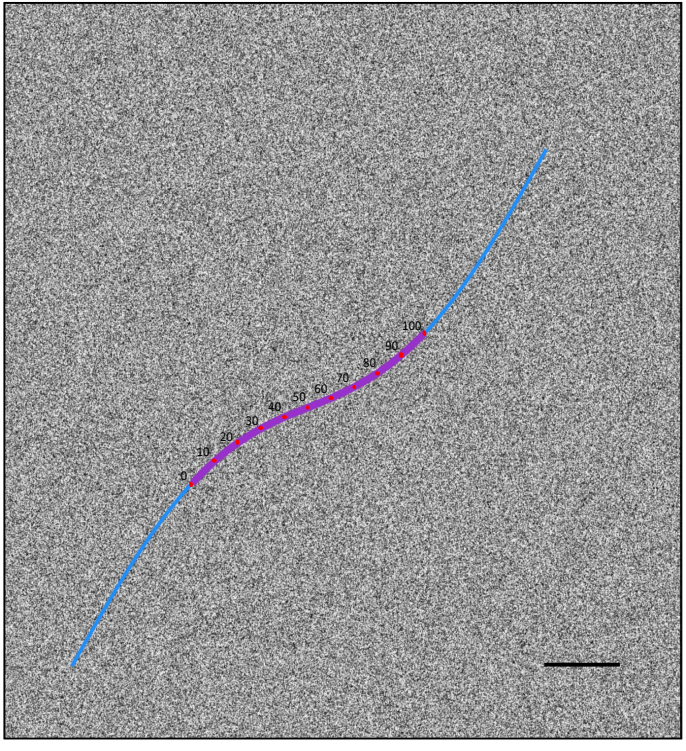


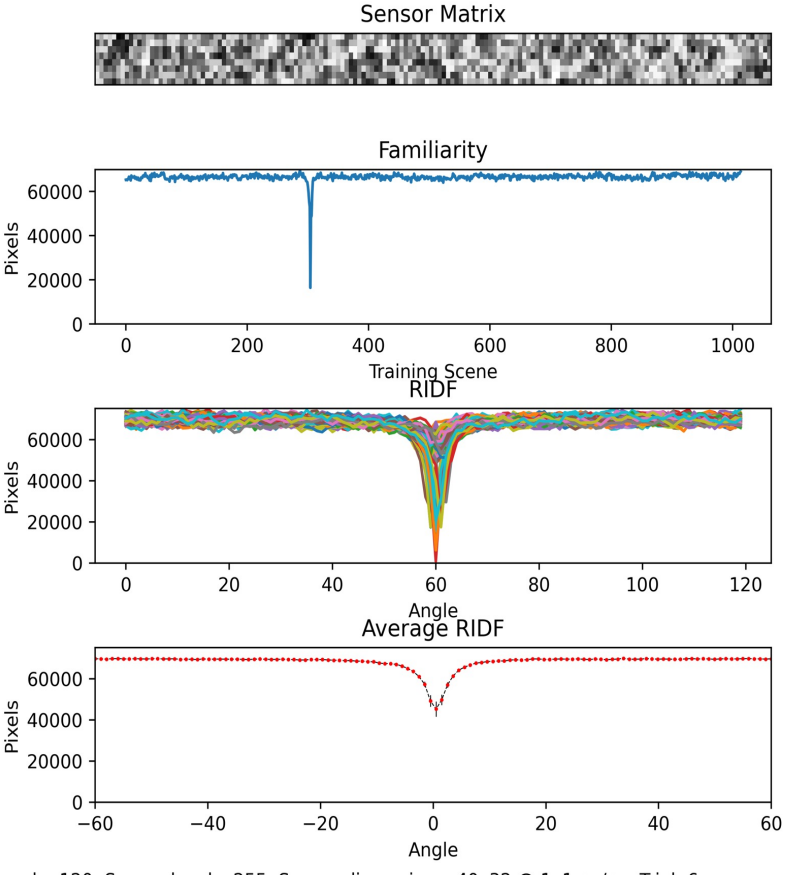


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 58.05; RMSD/dist: 0.145; TD: 15768; p90: 8; p50: 4; complete: 0

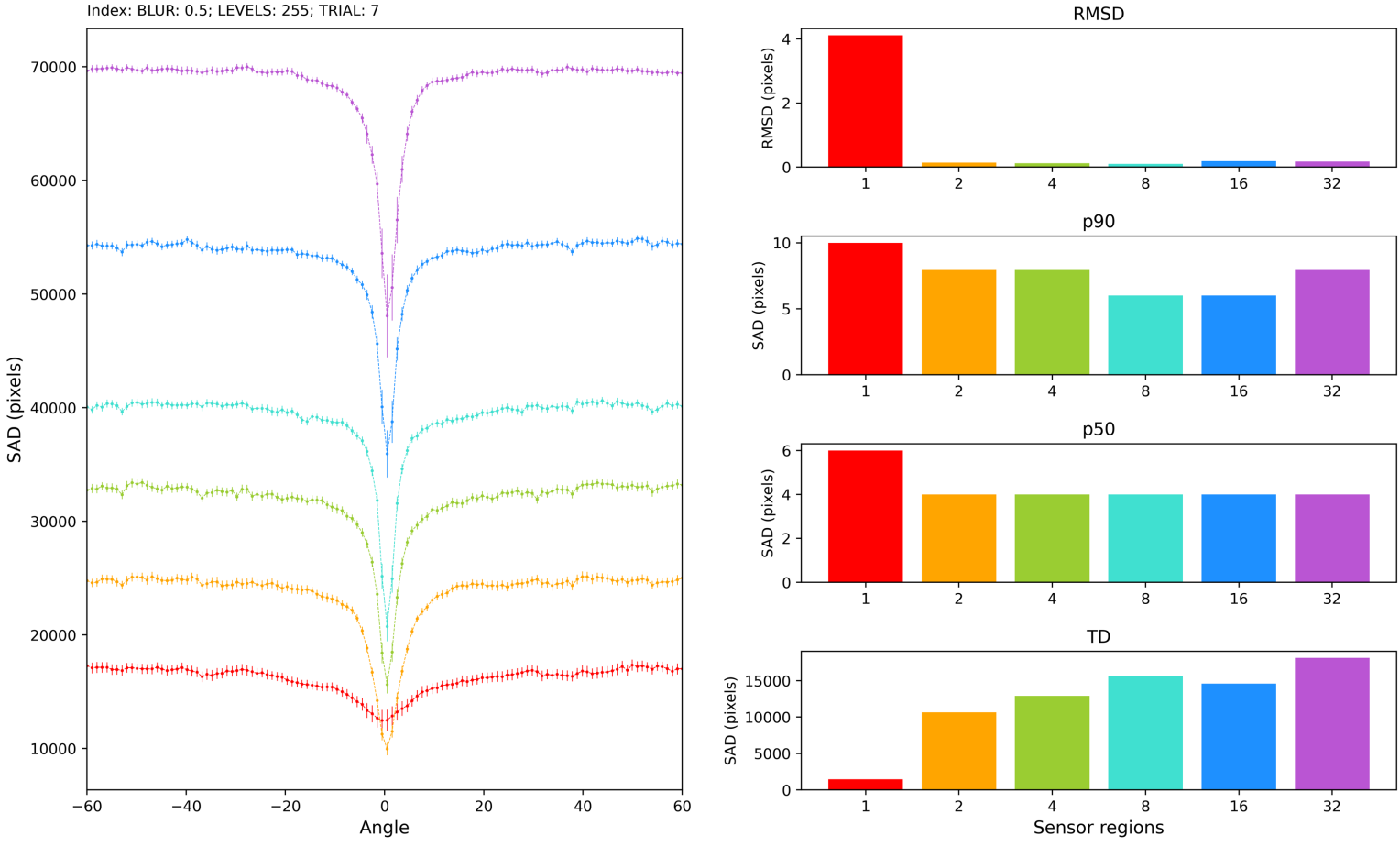
100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 62.22; RMSD/dist: 0.156; TD: 20974; p90: 8; p50: 4; complete: 0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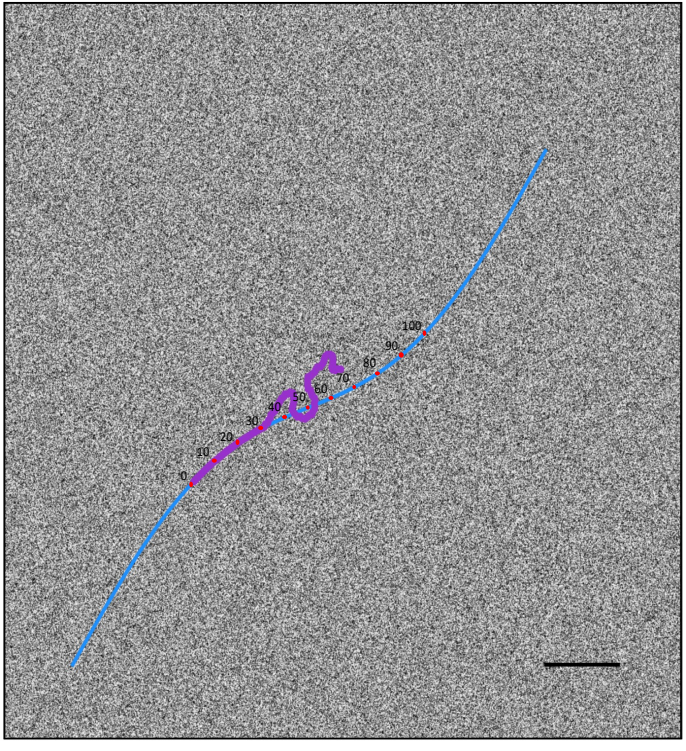
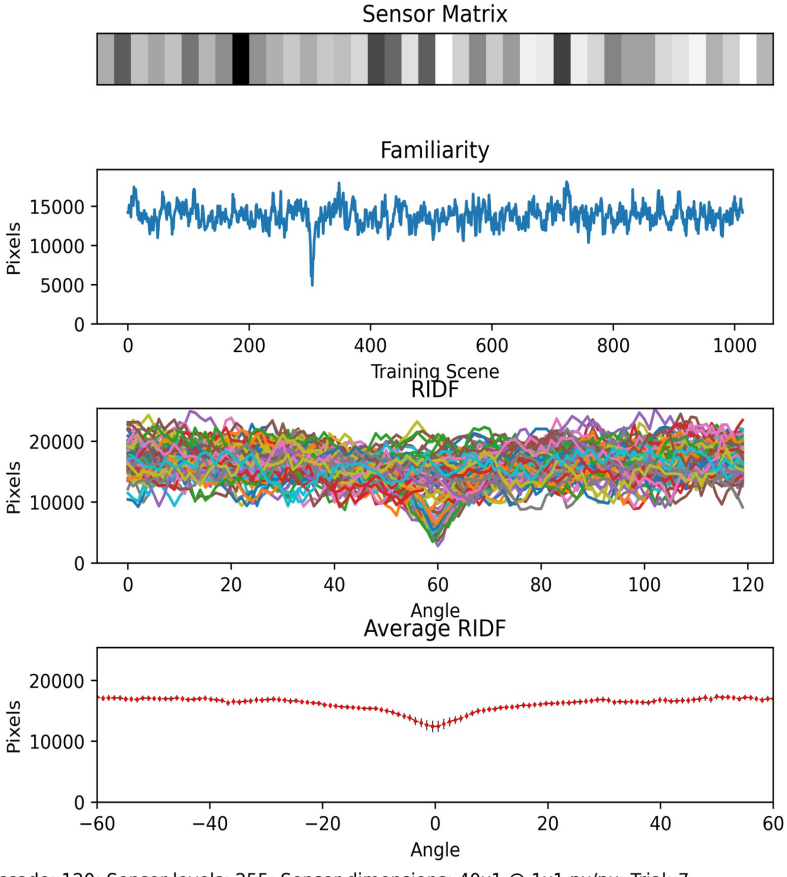
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
6
4
2
0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

30%

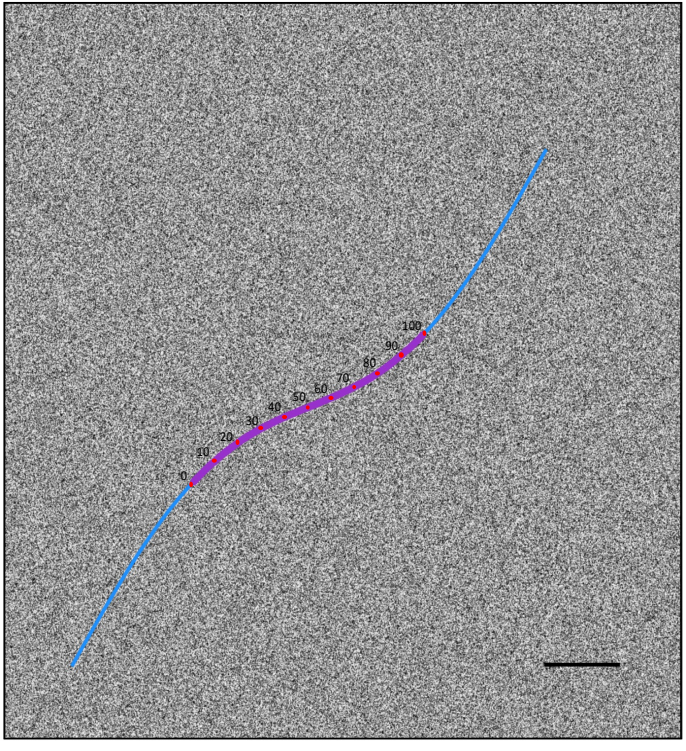


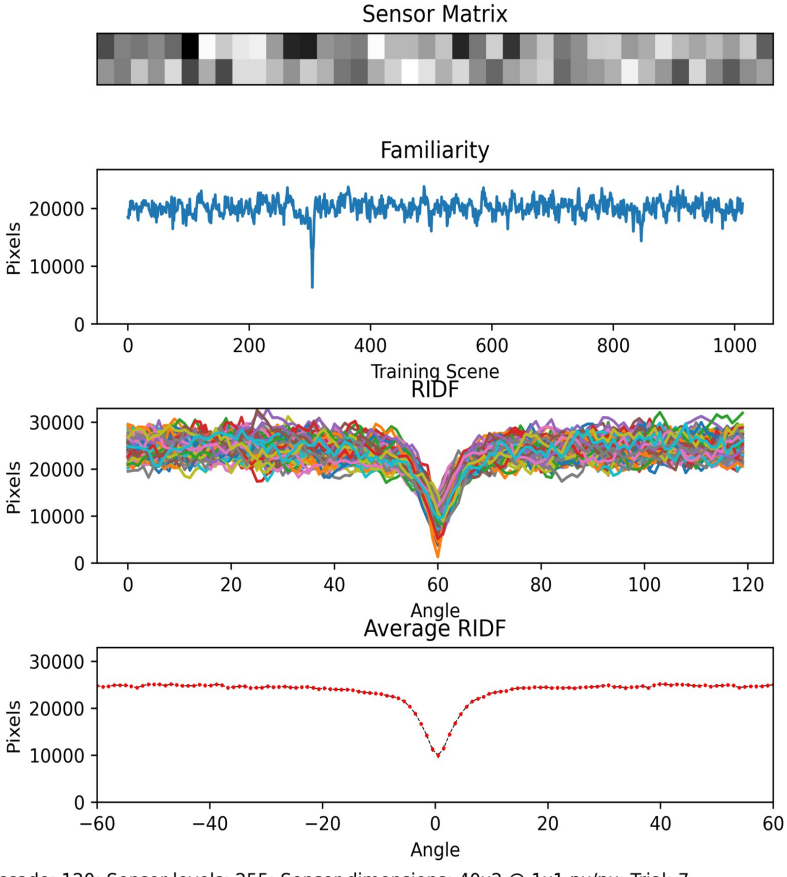


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1647.39; RMSD/dist: 4.118; TD: 1437; p90: 10; p50: 6; complete: 0

100%

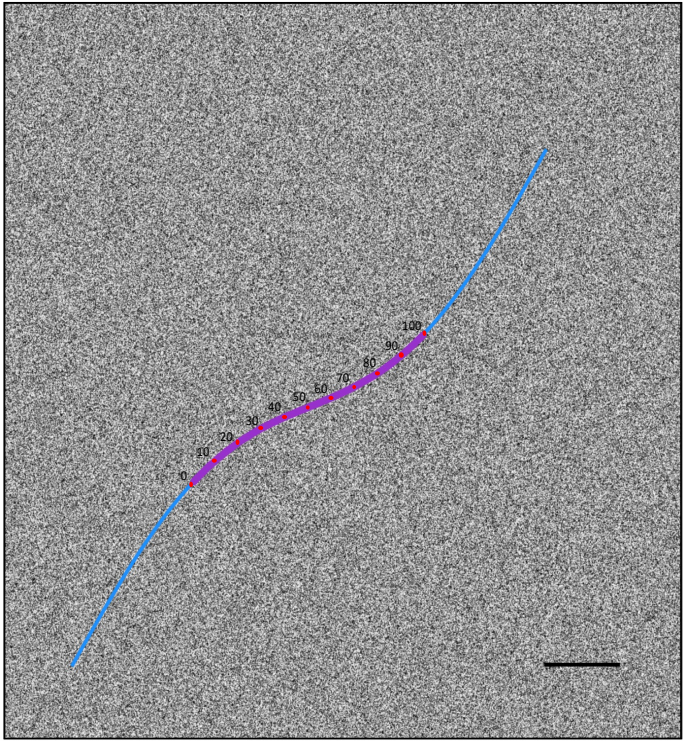


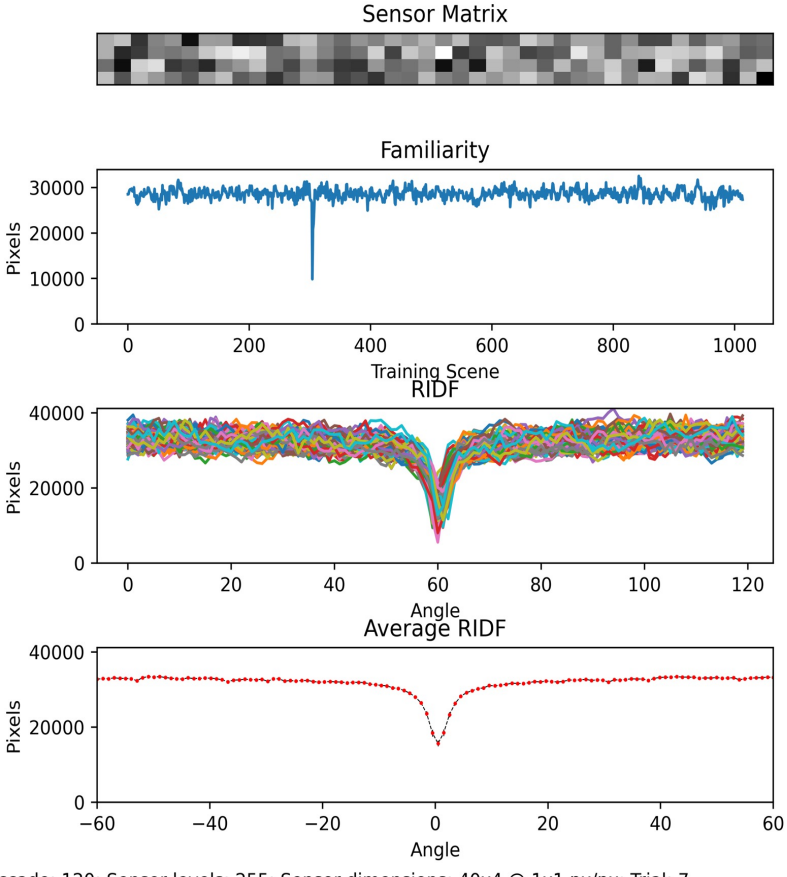


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 54.42; RMSD/dist: 0.136; TD: 10660; p90: 8; p50: 4; complete: 0

100%

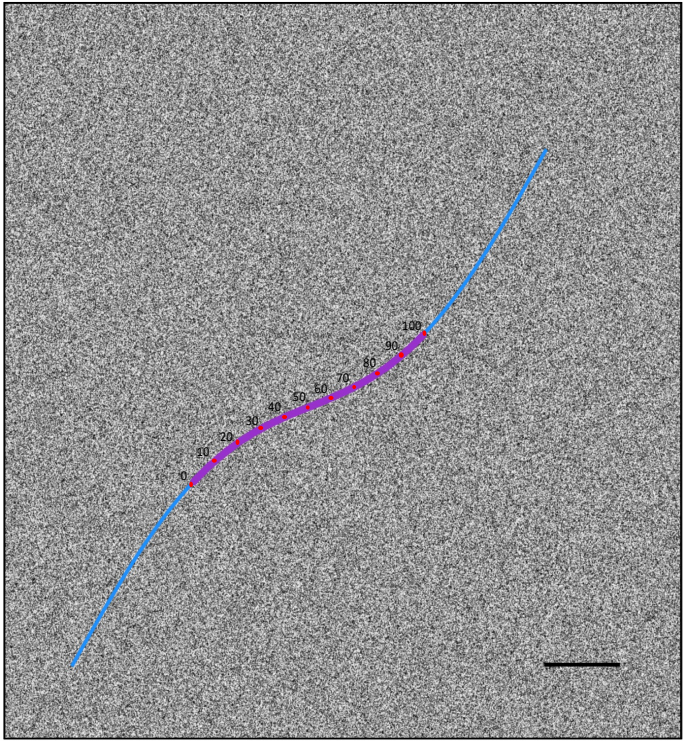


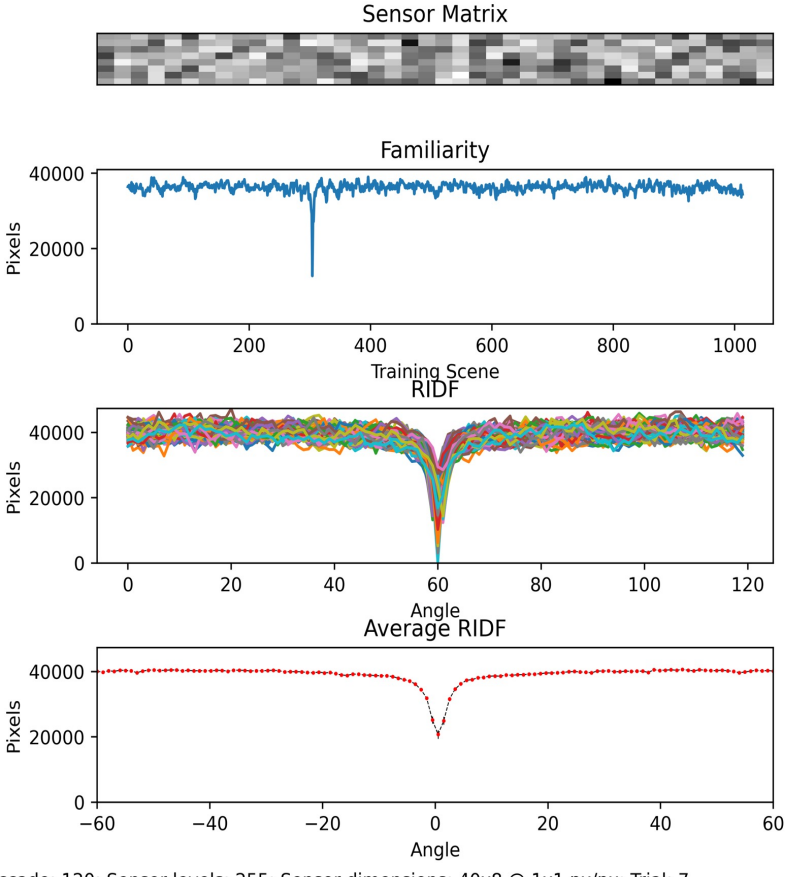


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 46.50; RMSD/dist: 0.116; TD: 12920; p90: 8; p50: 4; complete: 0

100%

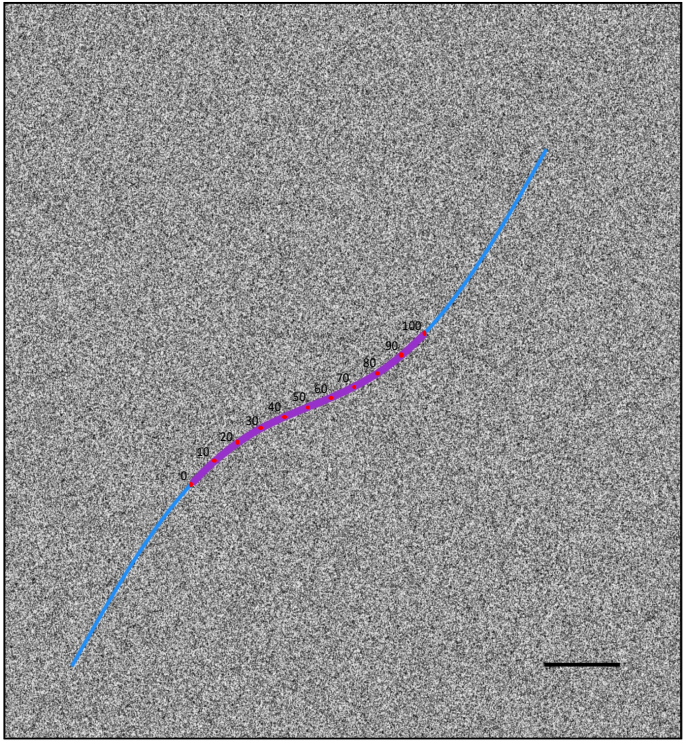


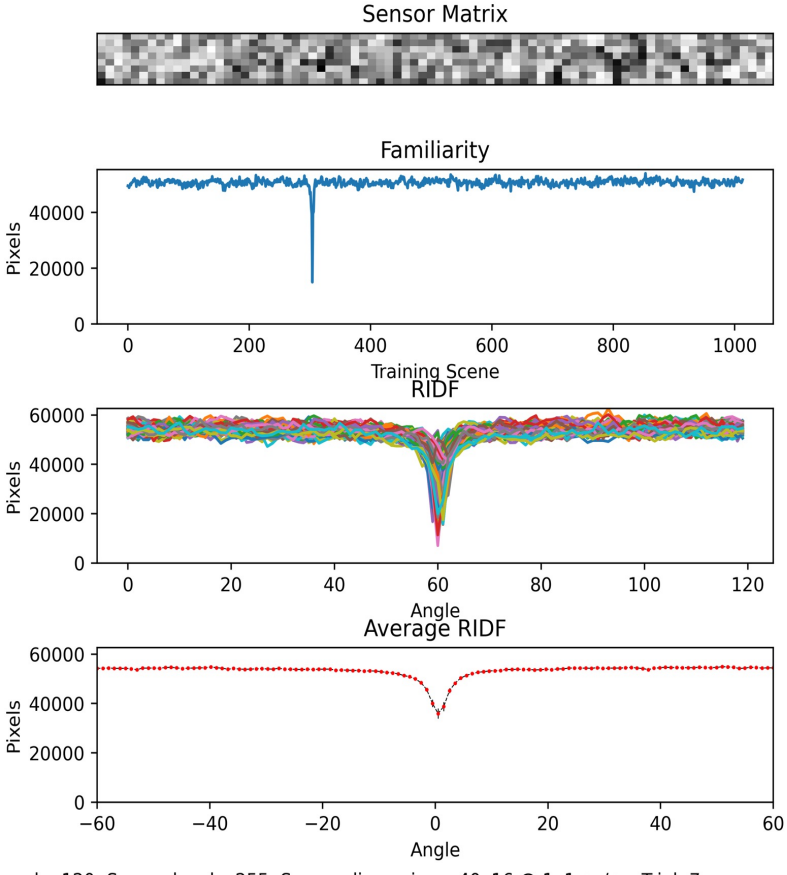


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 38.70; RMSD/dist: 0.097; TD: 15619; p90: 6; p50: 4; complete: 0

100%

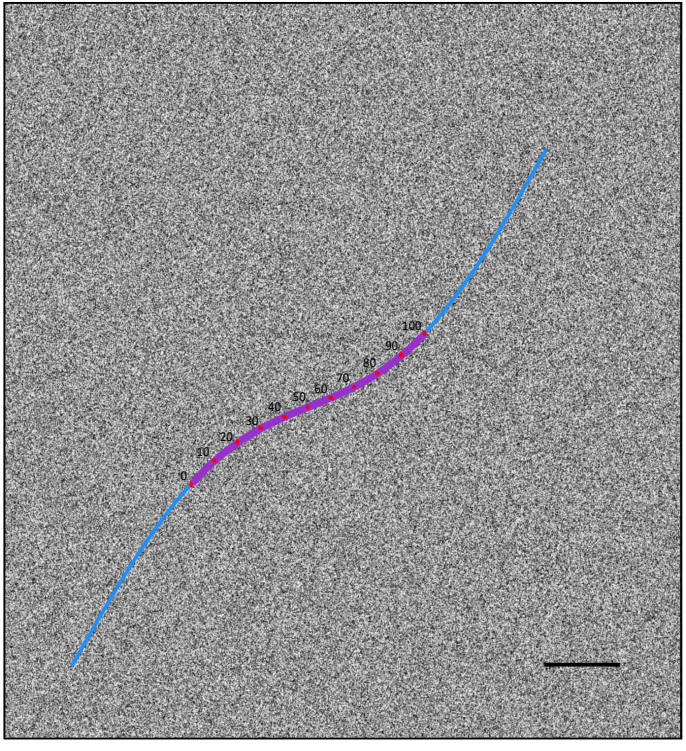


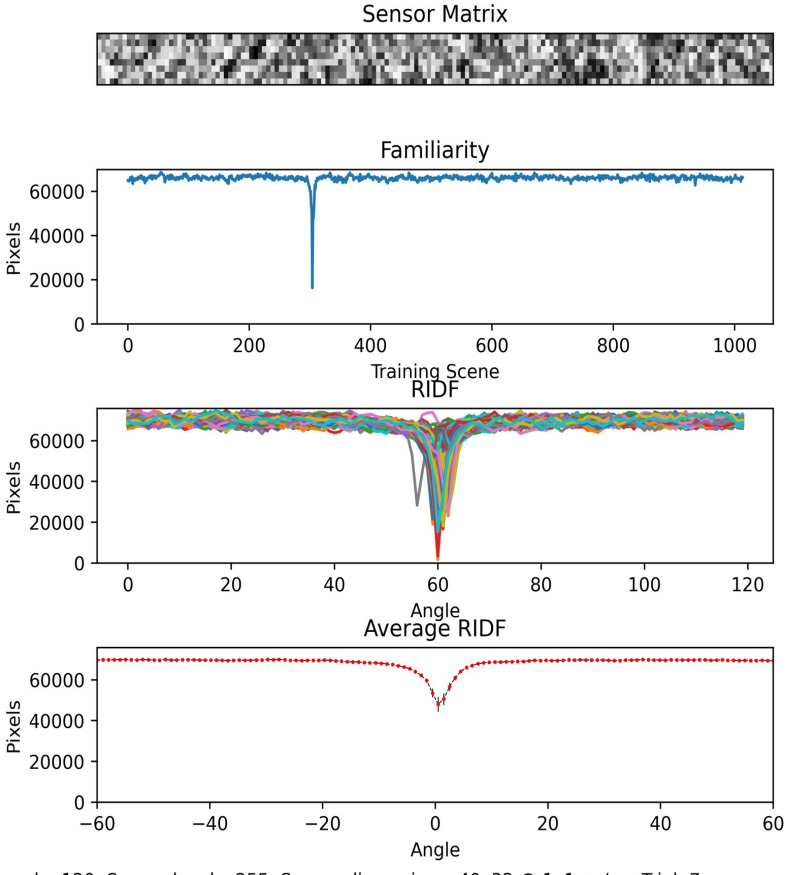


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 72.60; RMSD/dist: 0.182; TD: 14617; p90: 6; p50: 4; complete: 0

100%





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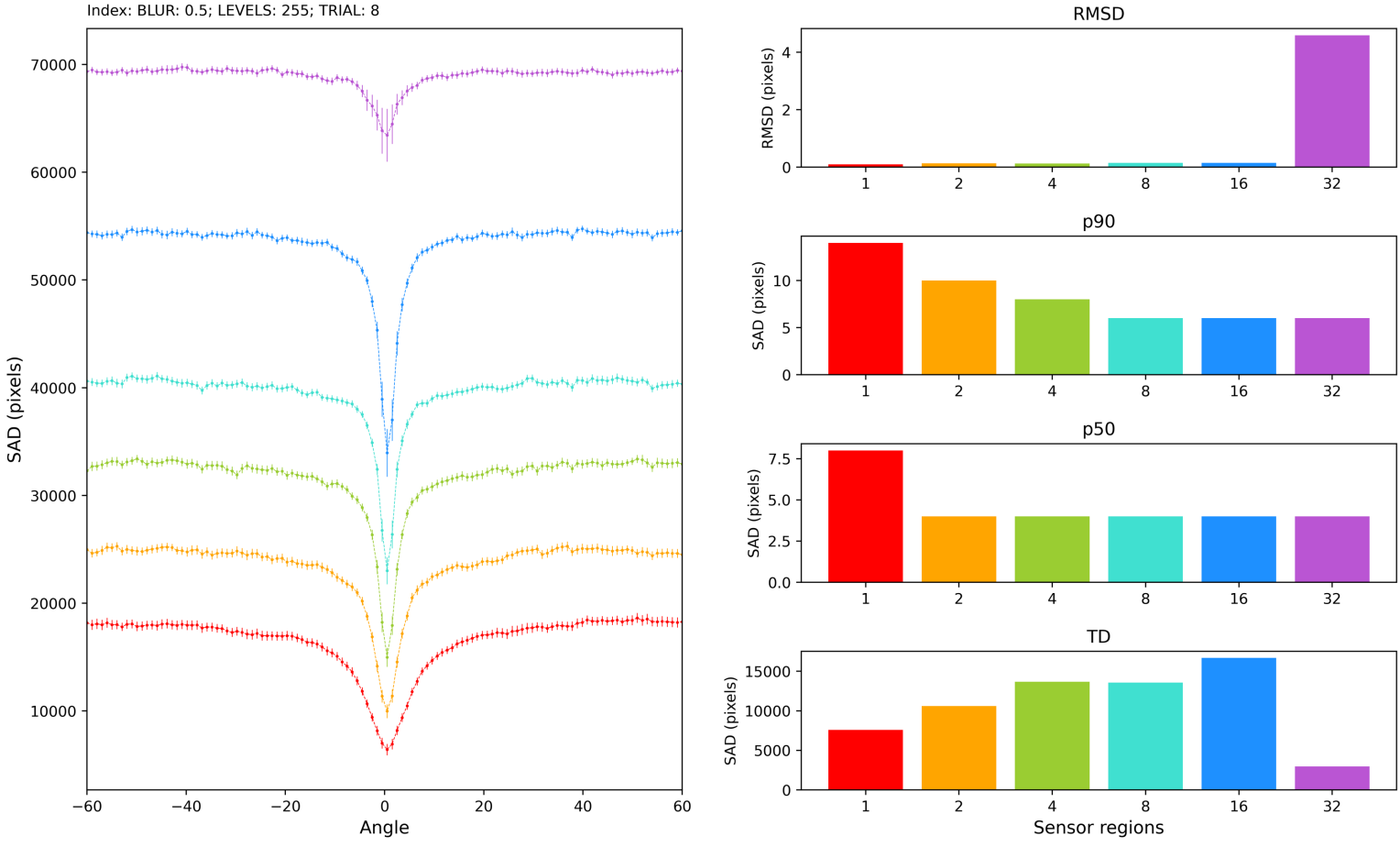
Navigation stats: RMSD error: 68.11; RMSD/dist: 0.170; TD: 18133; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 255; TRIAL: 8
SAD (pixels)
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40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
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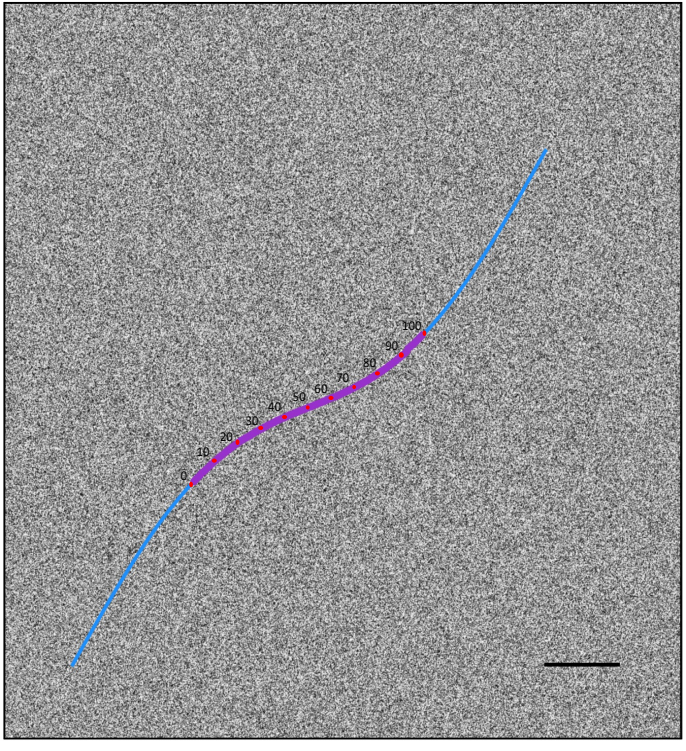
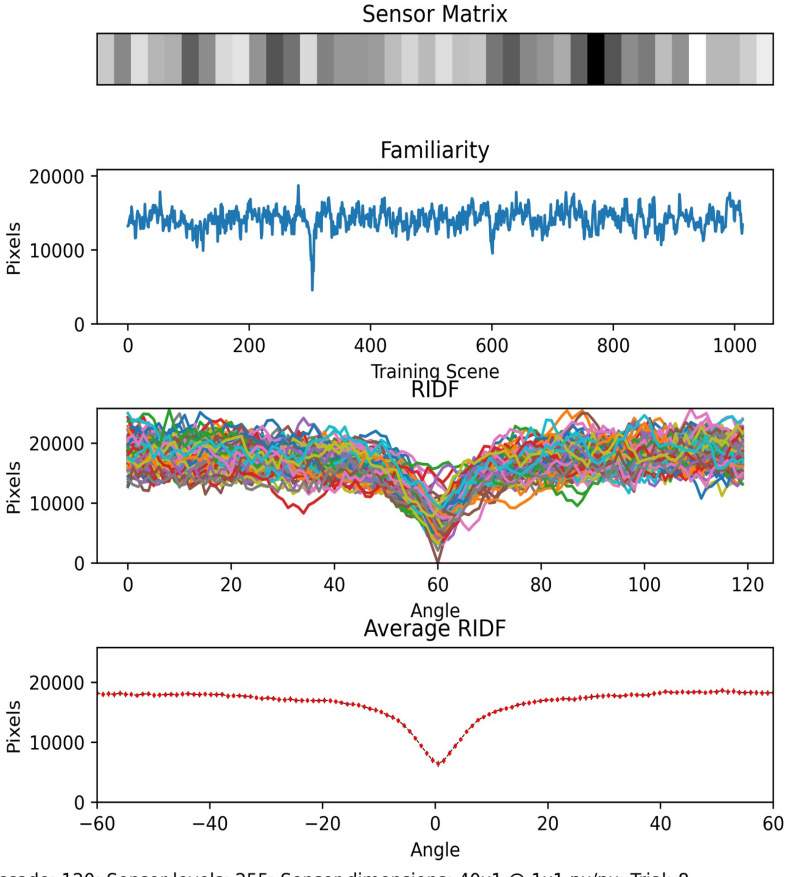
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

100%

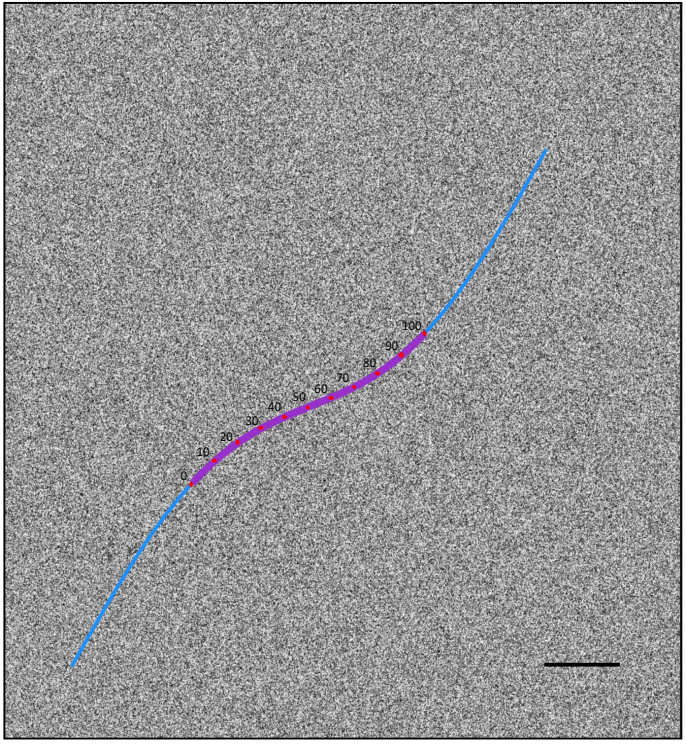


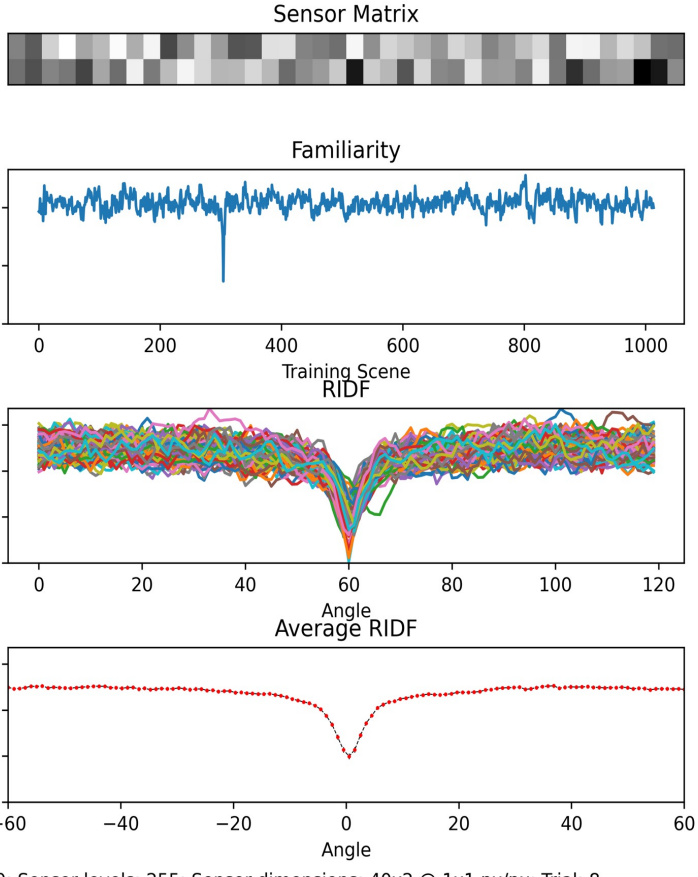


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 37.39; RMSD/dist: 0.093; TD: 7584; p90: 14; p50: 8; complete: 0

100%

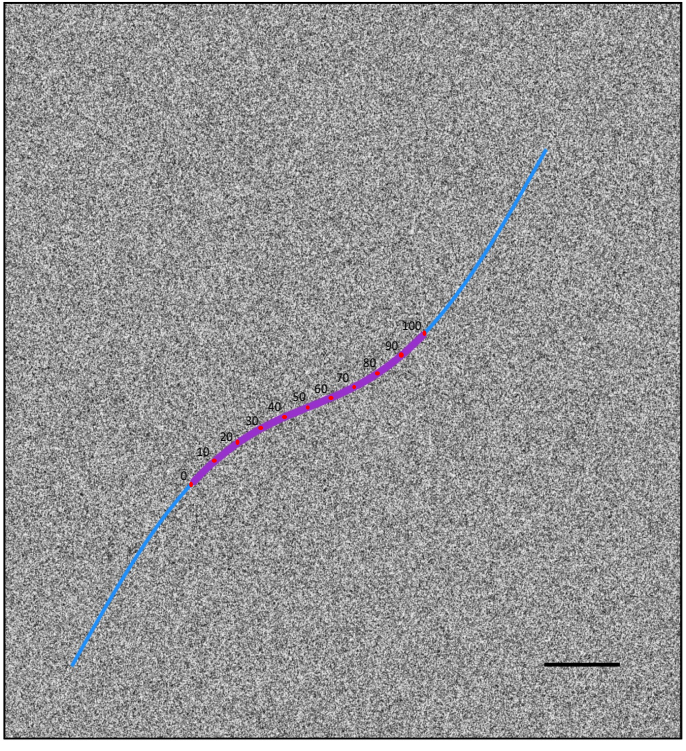


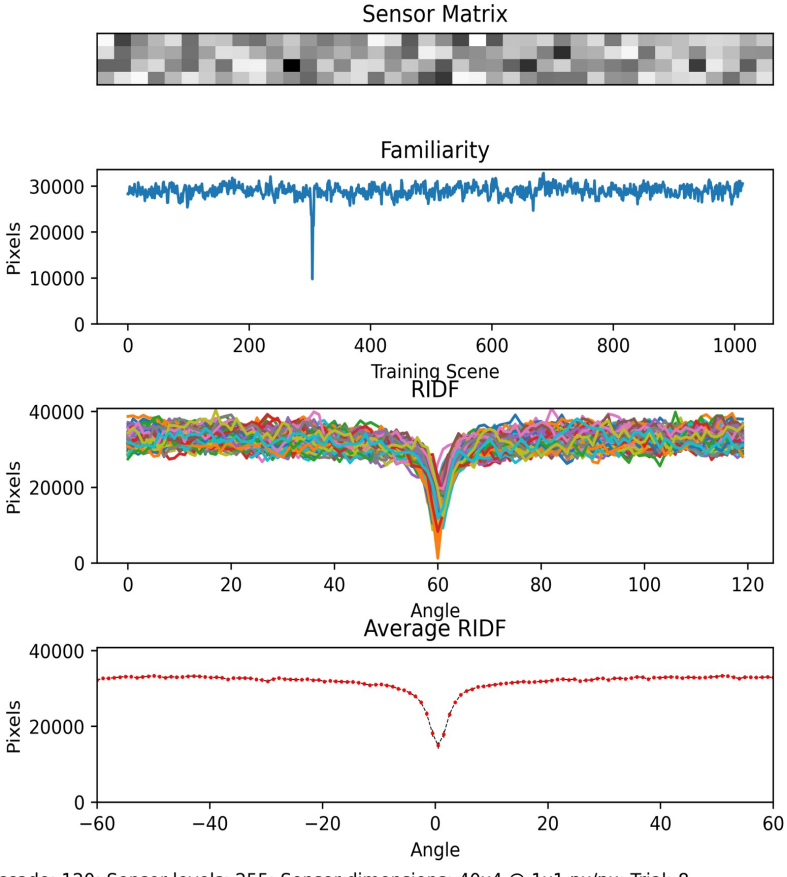


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 53.30; RMSD/dist: 0.133; TD: 10615; p90: 10; p50: 4; complete: 0

100%

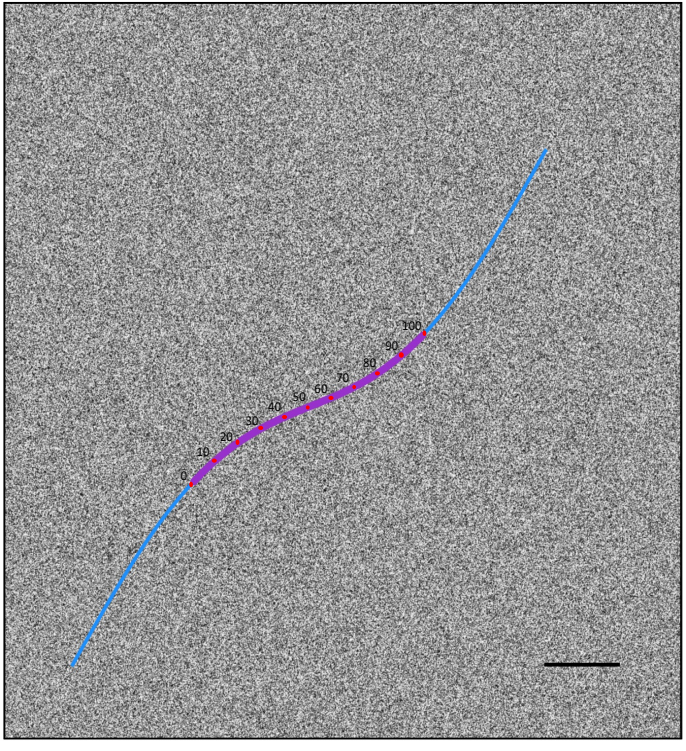


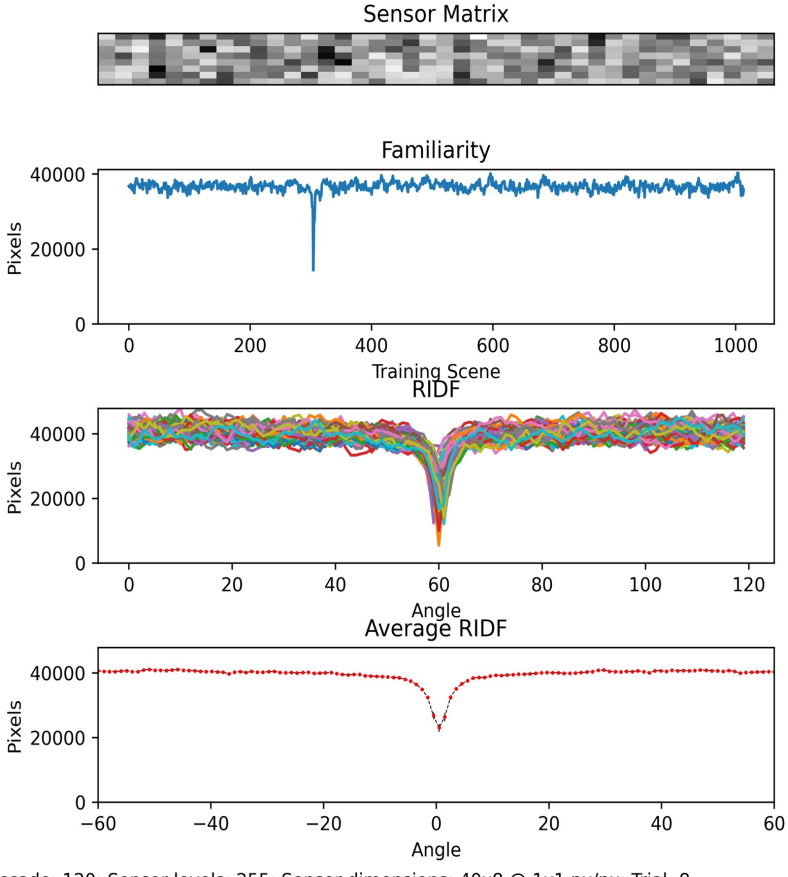


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 47.94; RMSD/dist: 0.120; TD: 13669; p90: 8; p50: 4; complete: 0

100%

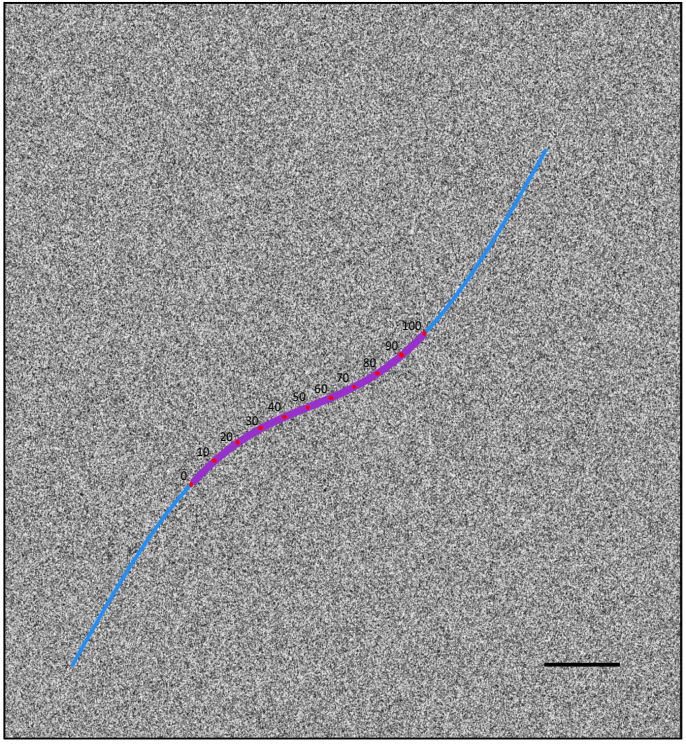


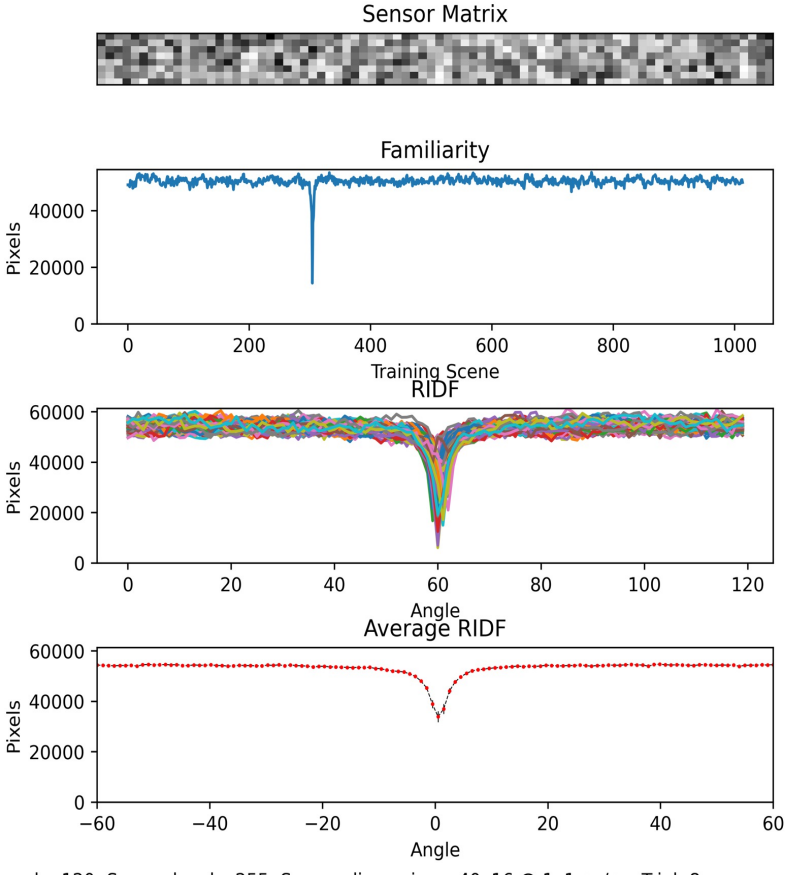


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 57.42; RMSD/dist: 0.144; TD: 13581; p90: 6; p50: 4; complete: 0

100%

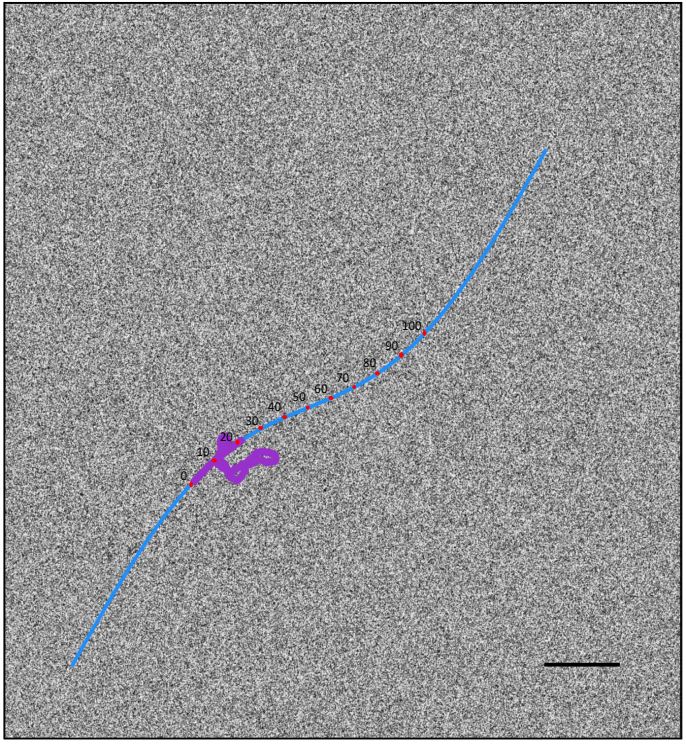


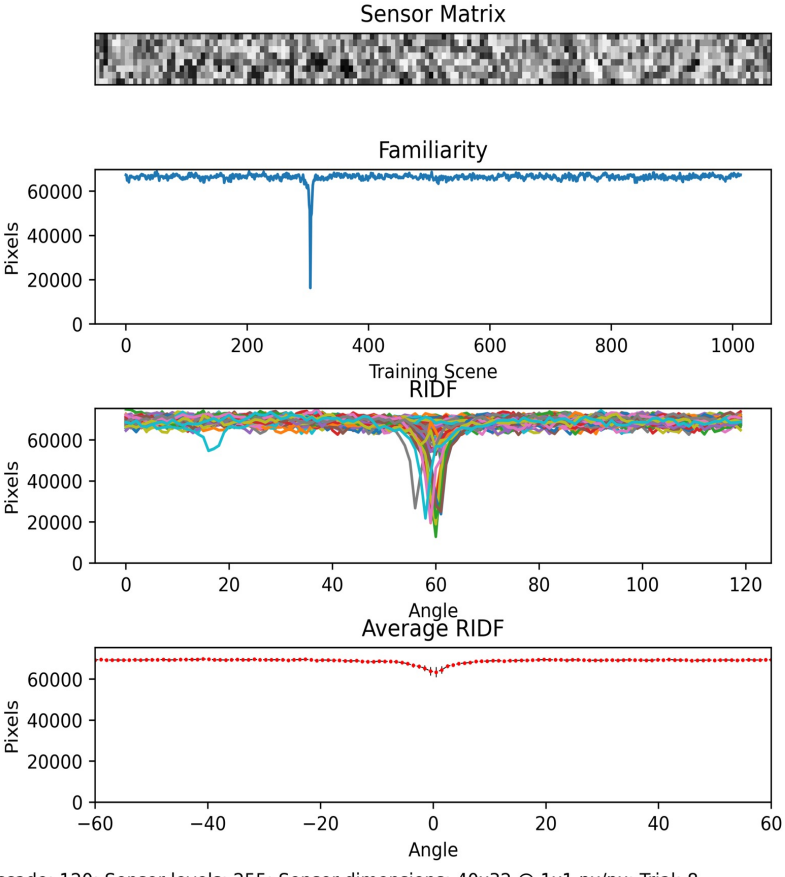


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 58.47; RMSD/dist: 0.146; TD: 16683; p90: 6; p50: 4; complete: 0

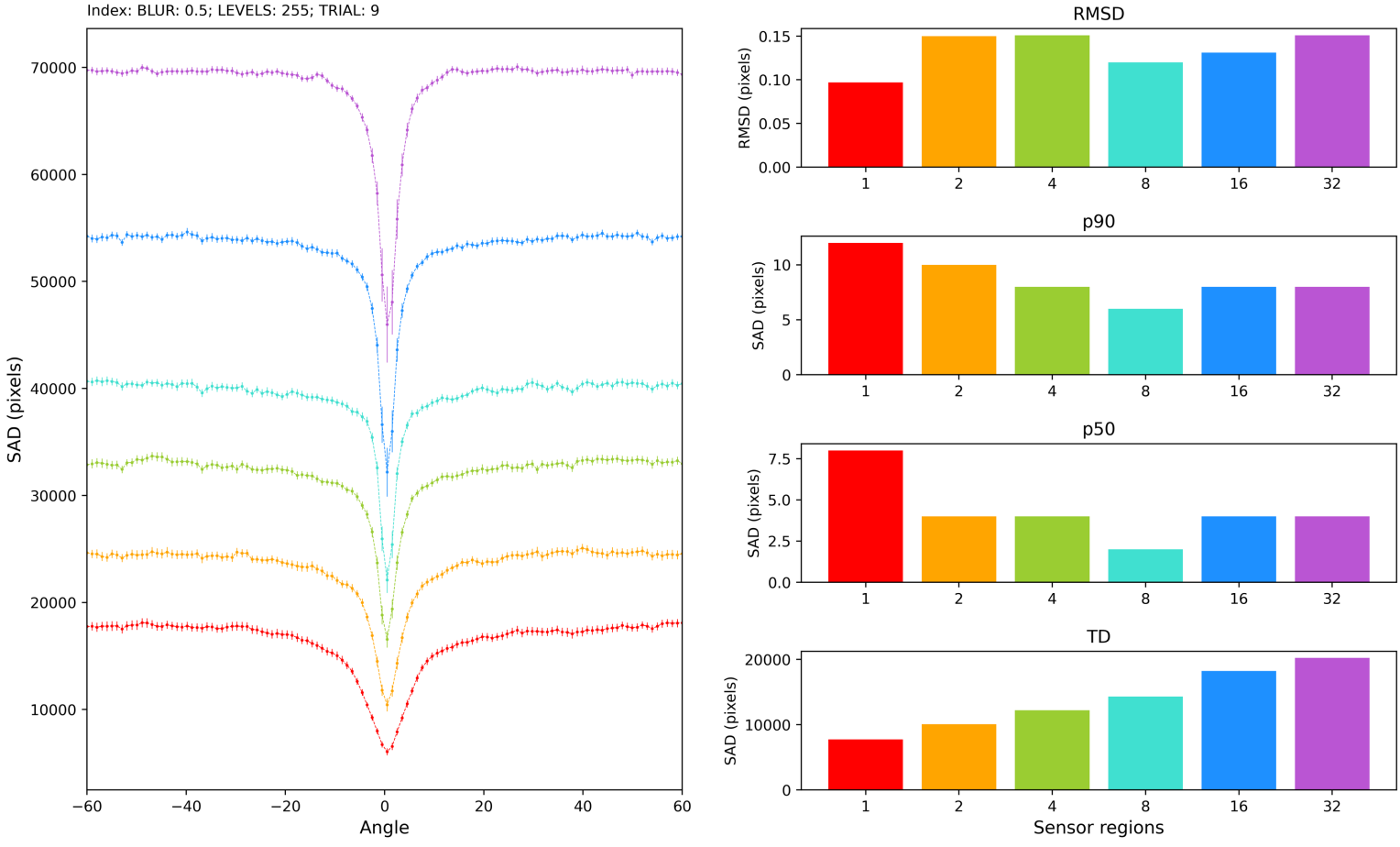
20%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1837.71; RMSD/dist: 4.594; TD: 2966; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 255; TRIAL: 9
SAD (pixels)
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40000
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20000
10000
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−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
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TD
SAD (pixels)
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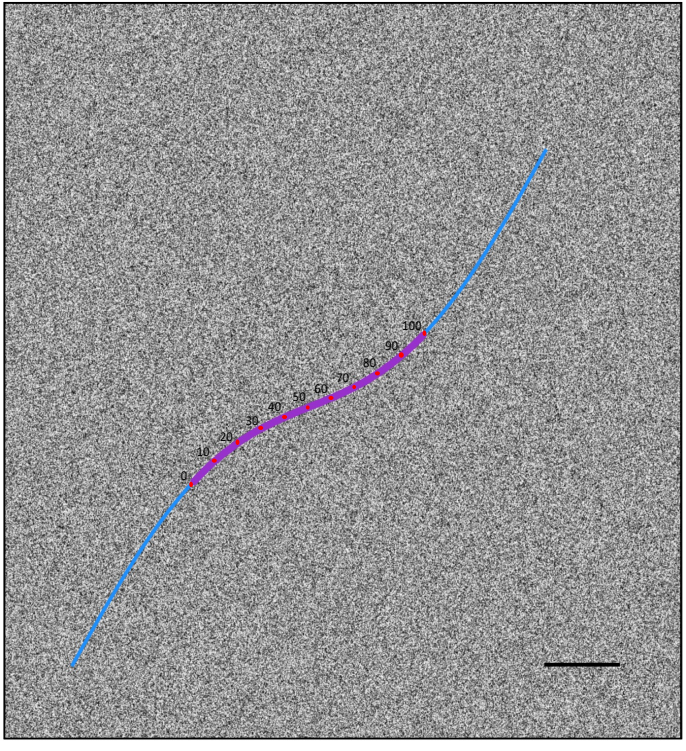
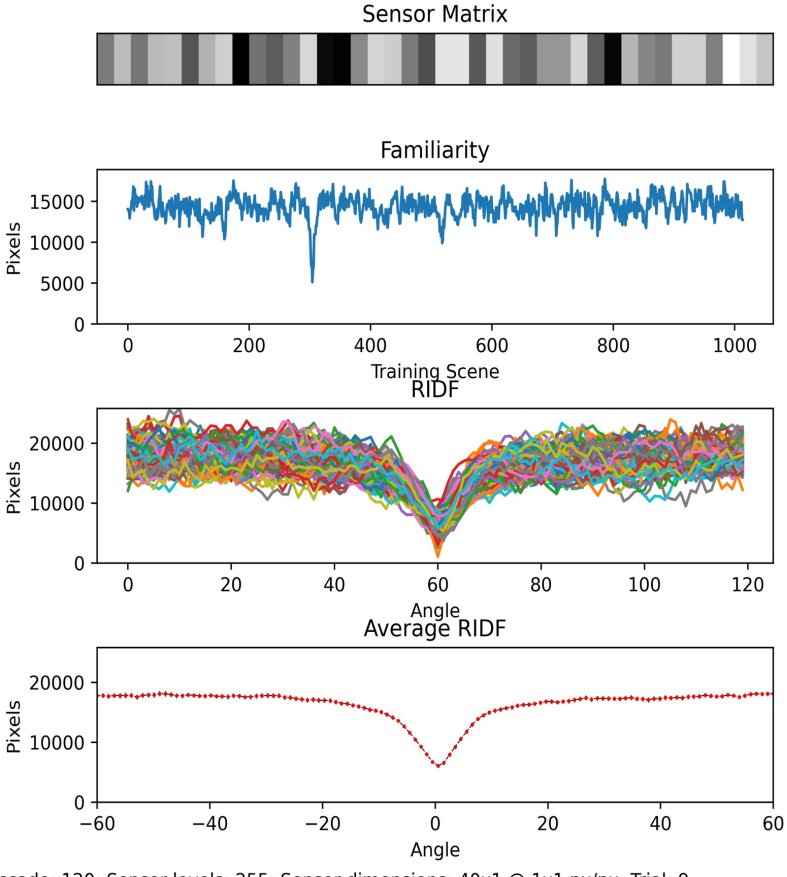
0
Sensor regions

100%

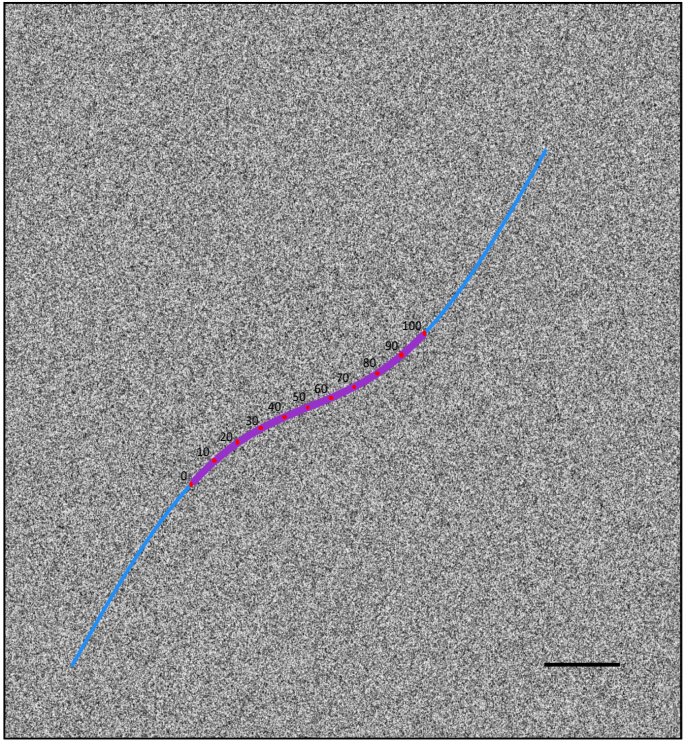


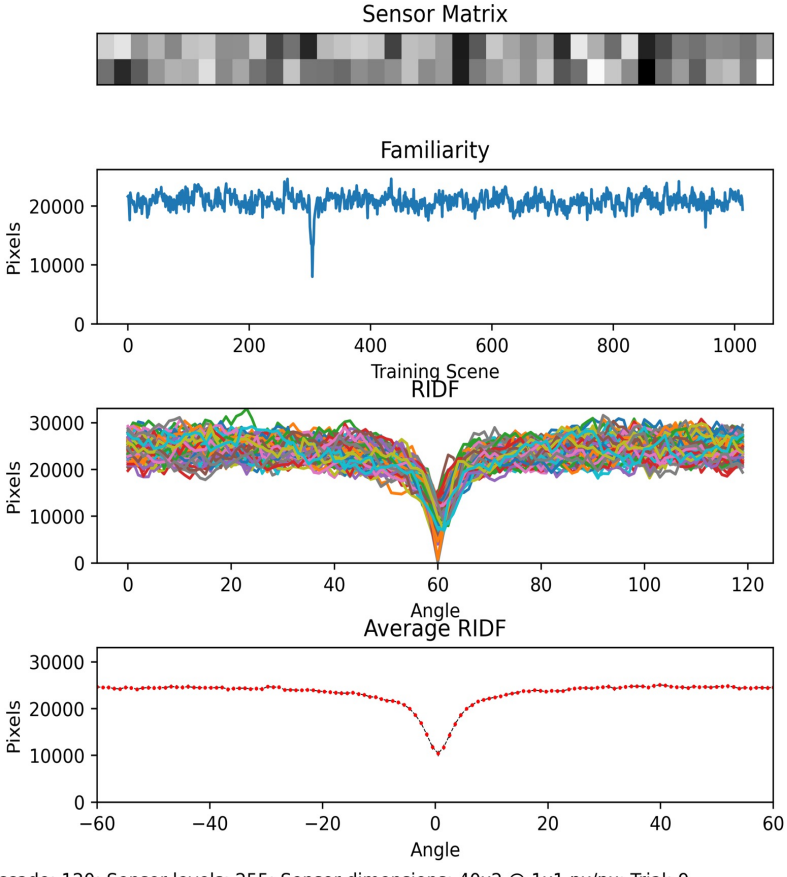


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 38.89; RMSD/dist: 0.097; TD: 7739; p90: 12; p50: 8; complete: 0

100%

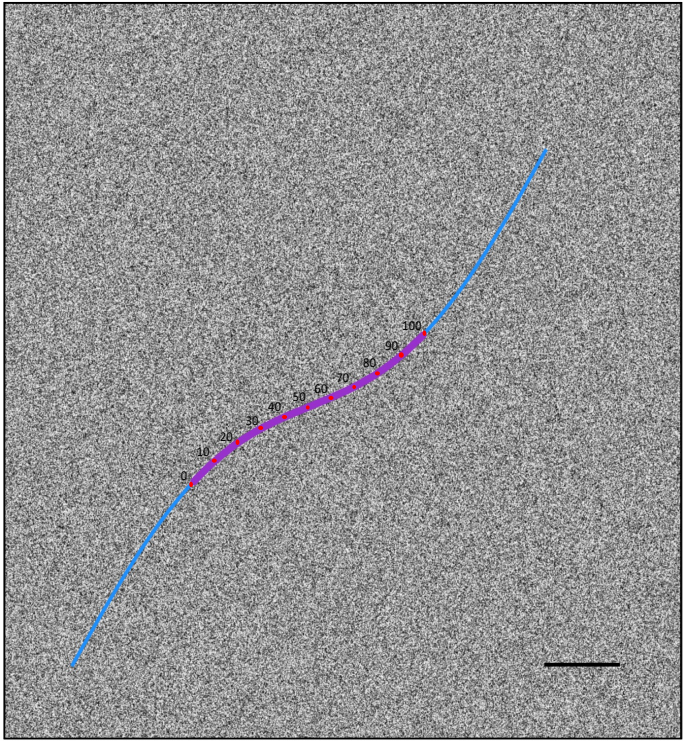


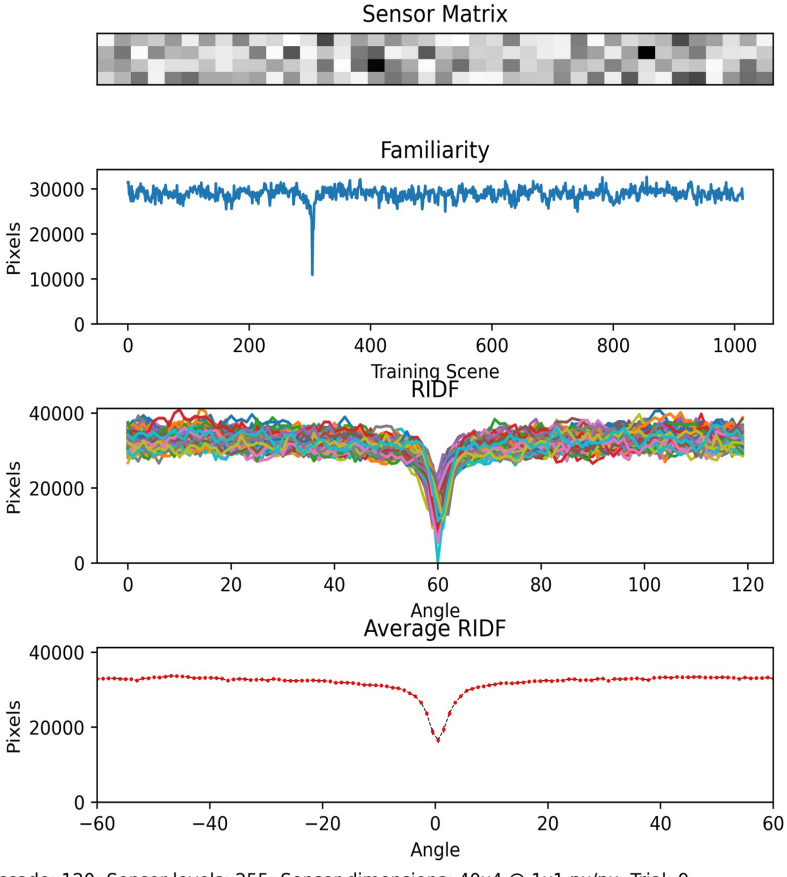


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 59.80; RMSD/dist: 0.150; TD: 10051; p90: 10; p50: 4; complete: 0

100%

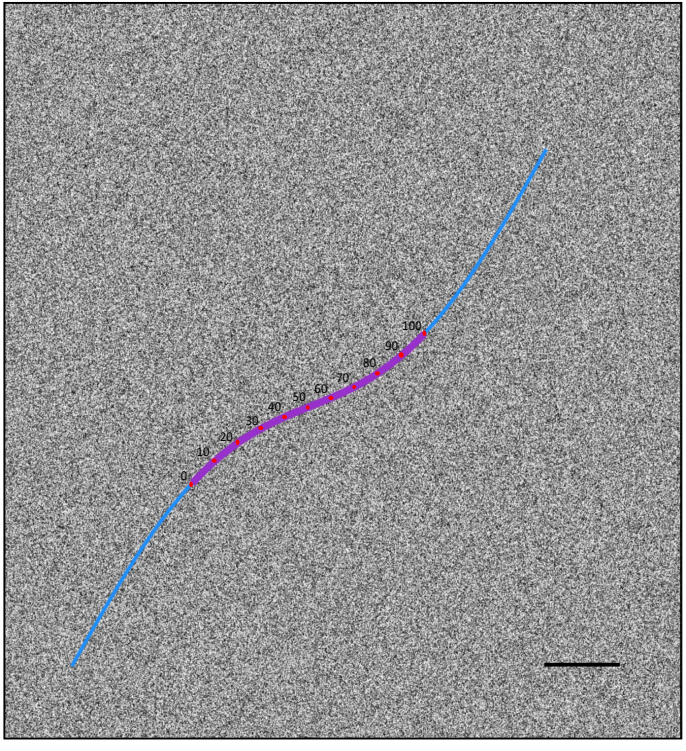


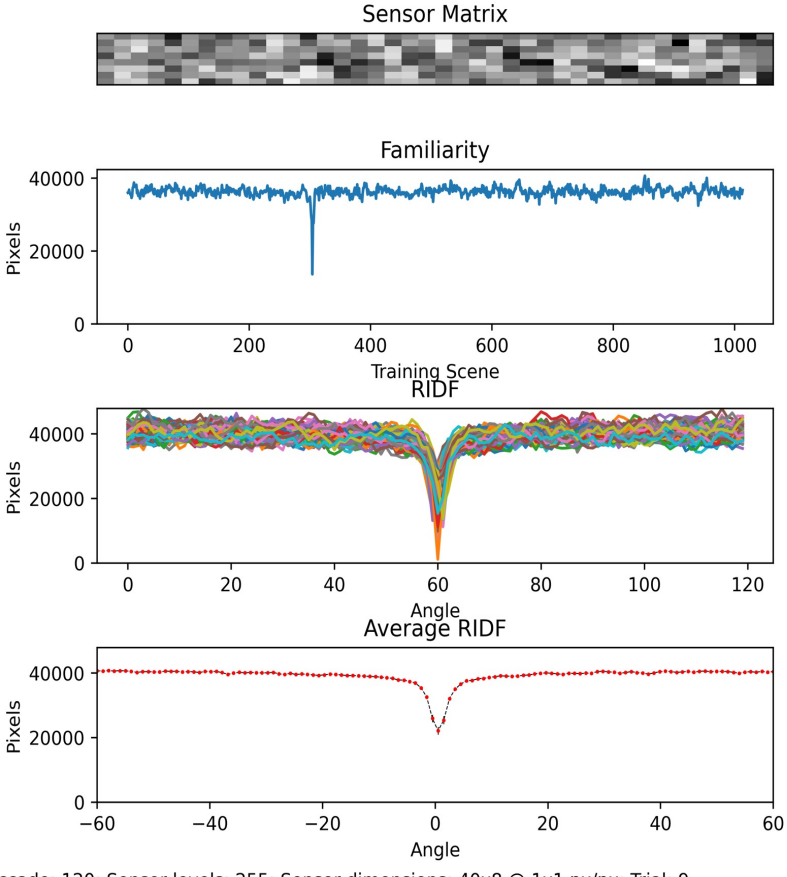


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 60.23; RMSD/dist: 0.151; TD: 12192; p90: 8; p50: 4; complete: 0

100%

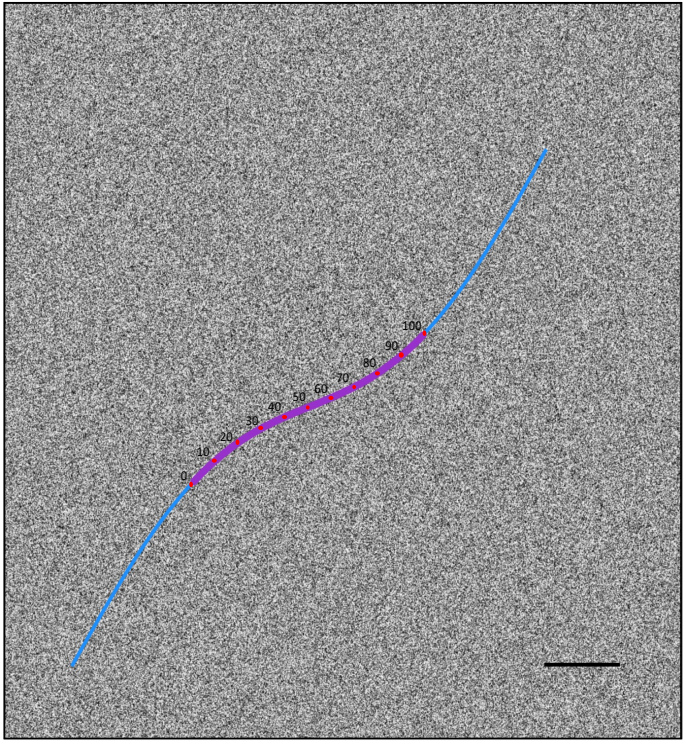


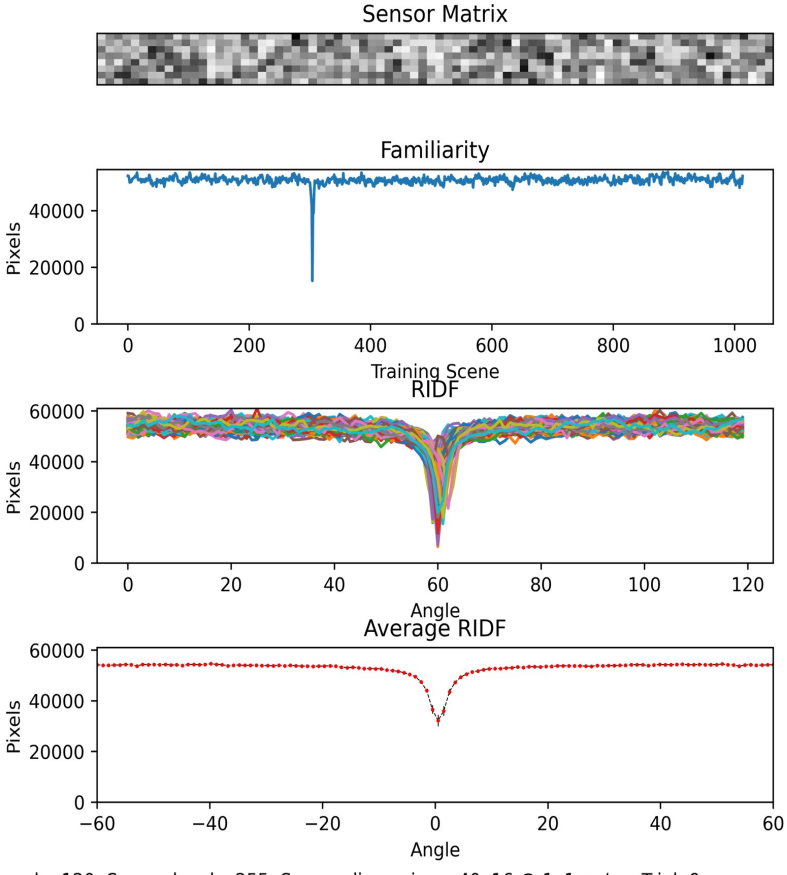


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 48.04; RMSD/dist: 0.120; TD: 14316; p90: 6; p50: 2; complete: 0

100%

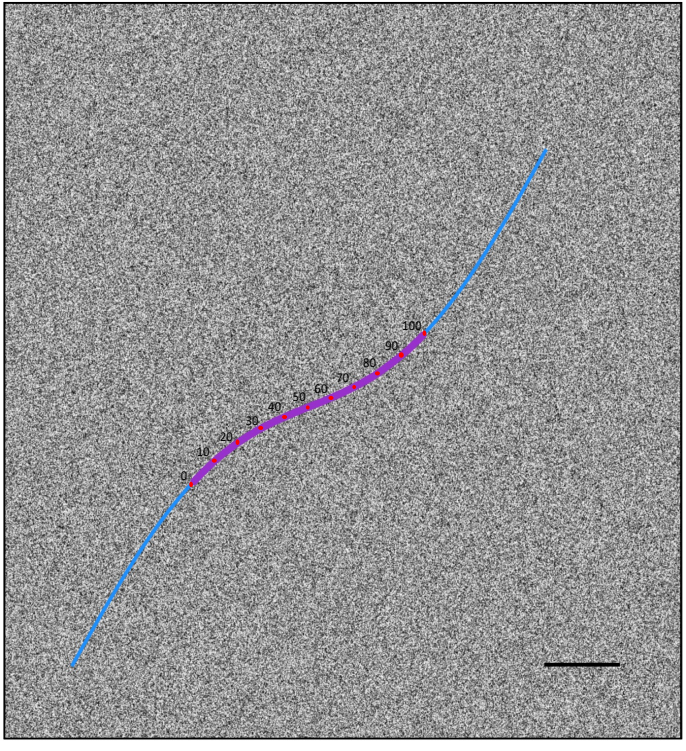


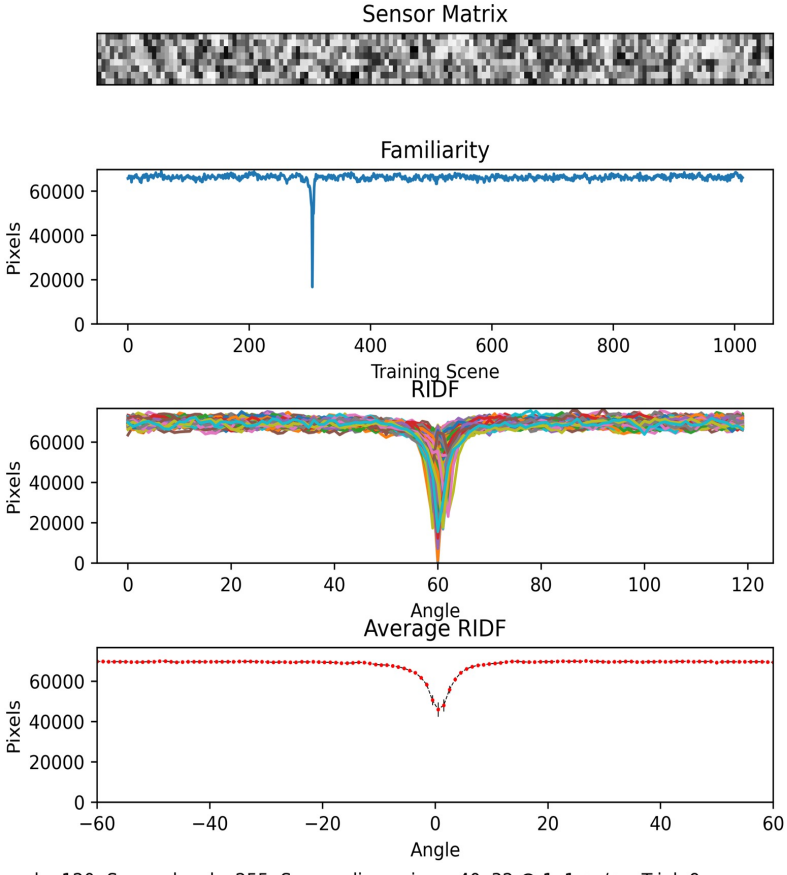


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 52.48; RMSD/dist: 0.131; TD: 18222; p90: 8; p50: 4; complete: 0

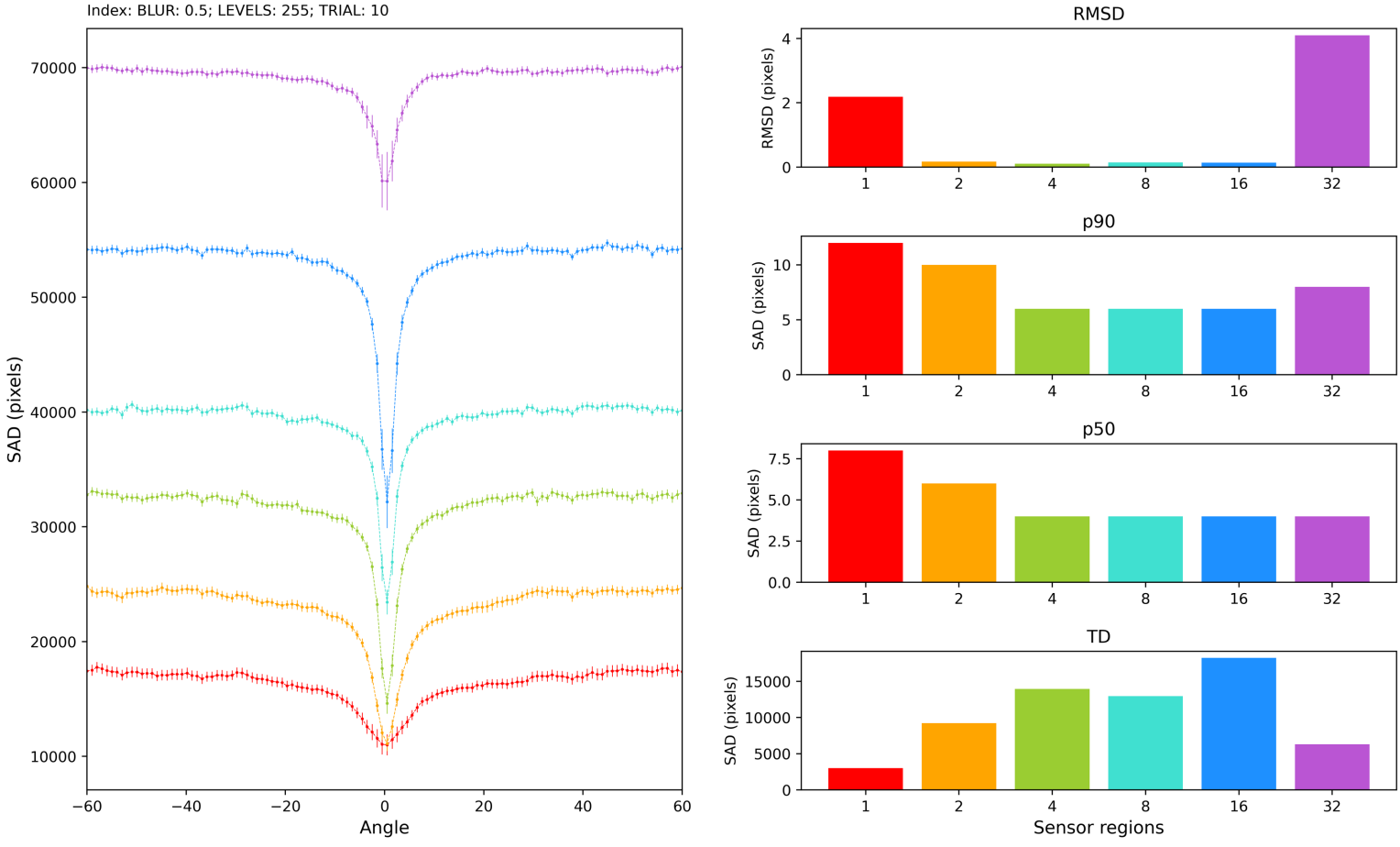
100%



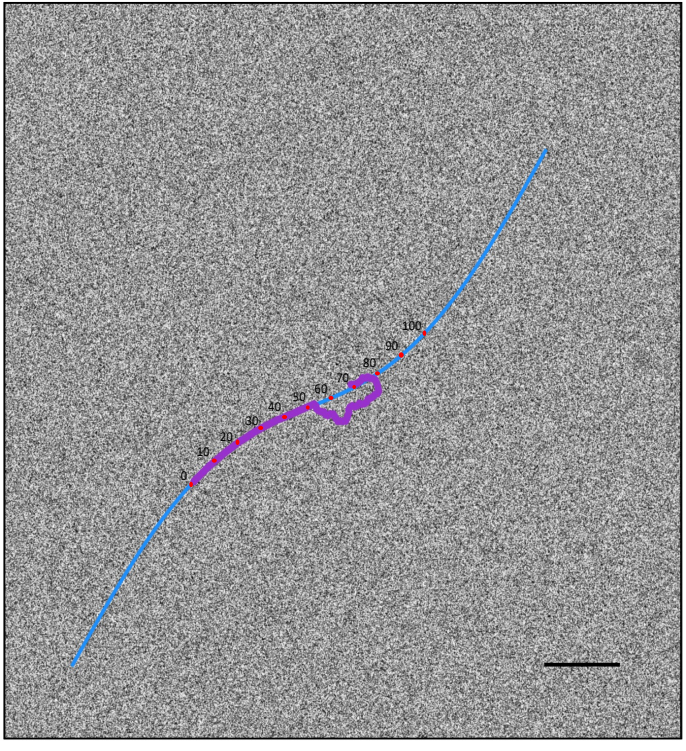


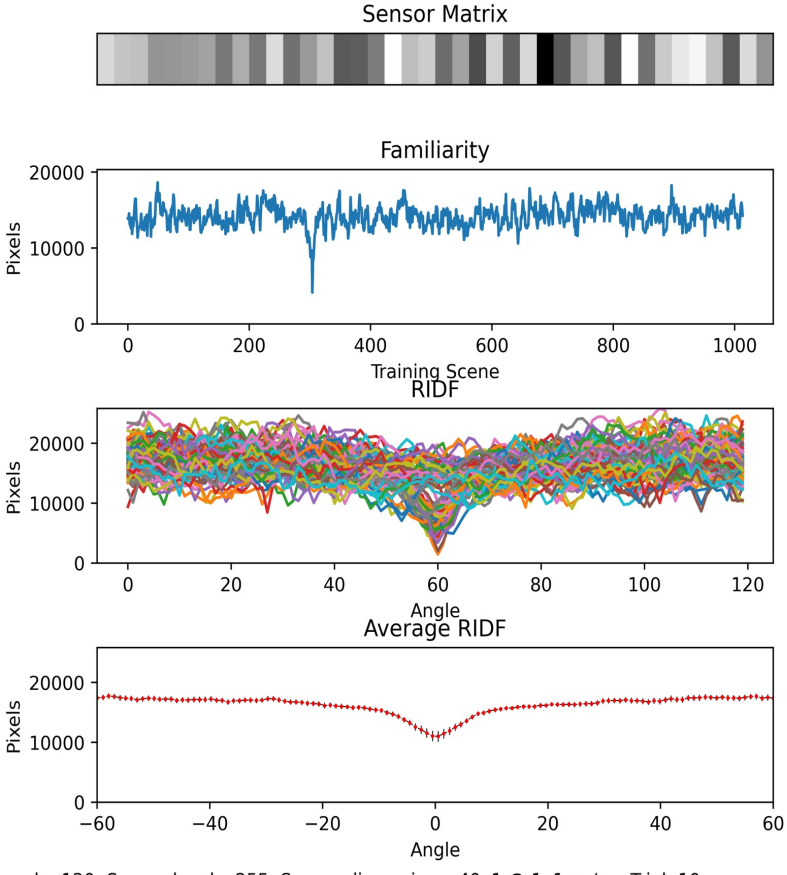
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 60.47; RMSD/dist: 0.151; TD: 20214; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 255; TRIAL: 10
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

50%

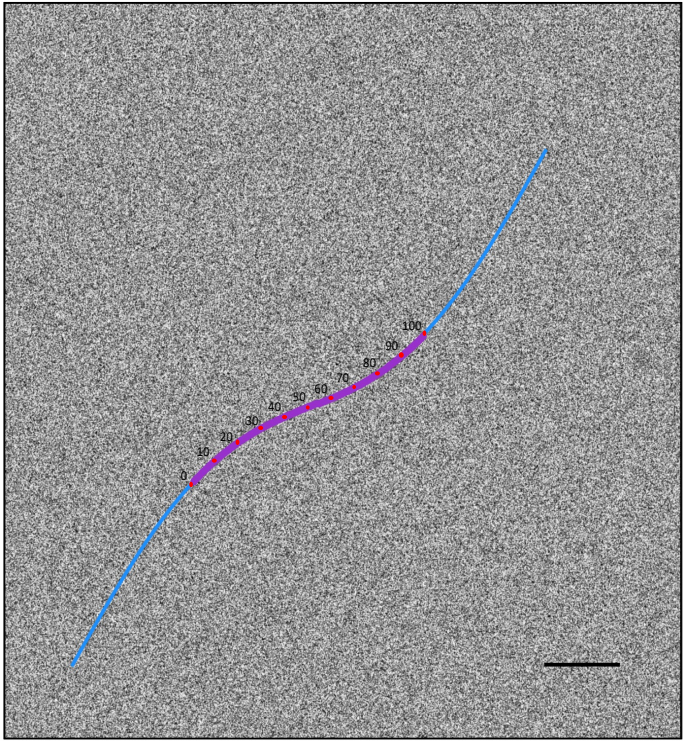


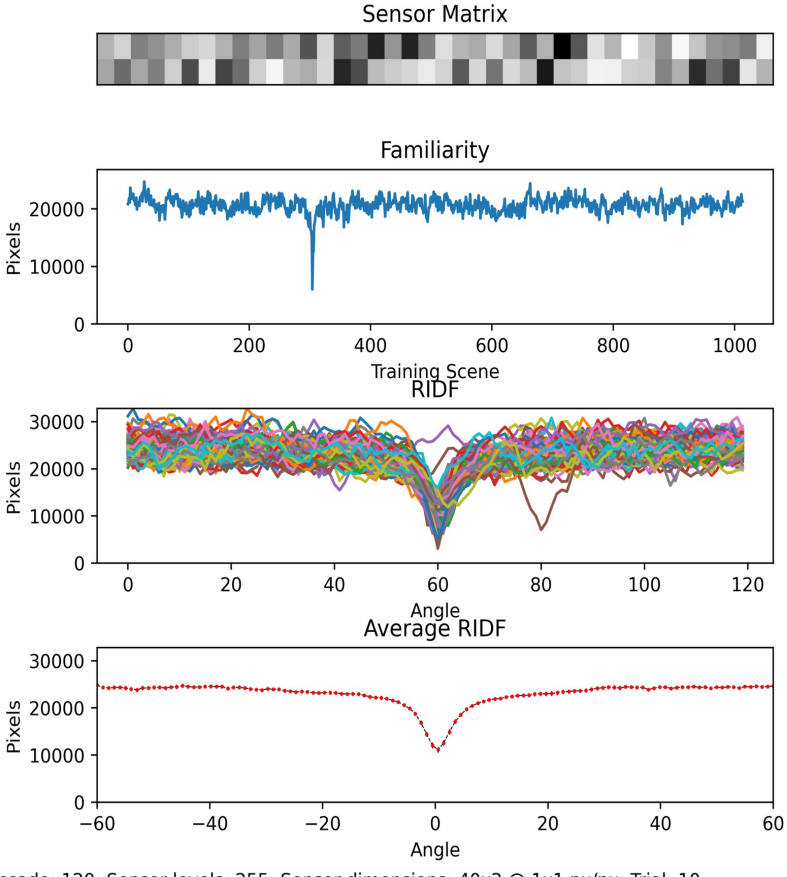


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 874.84; RMSD/dist: 2.187; TD: 2992; p90: 12; p50: 8; complete: 0

100%

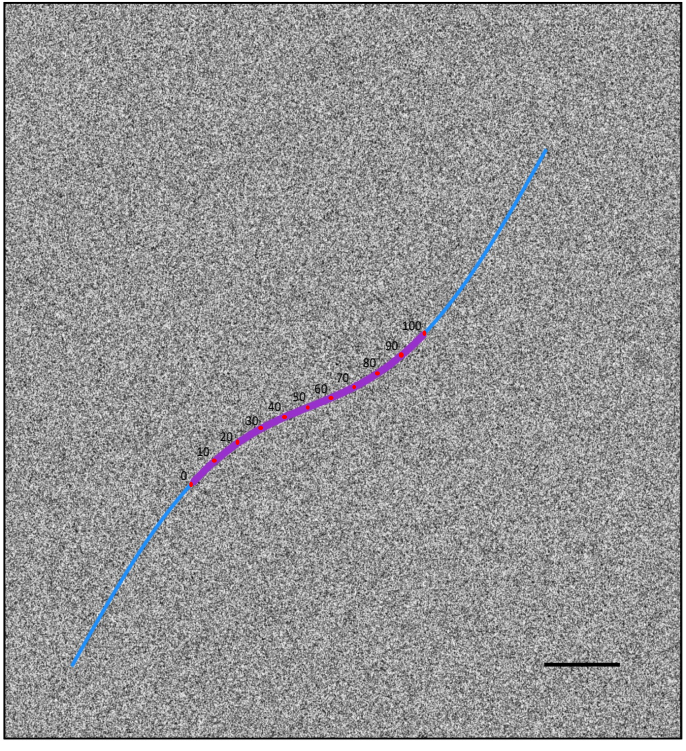


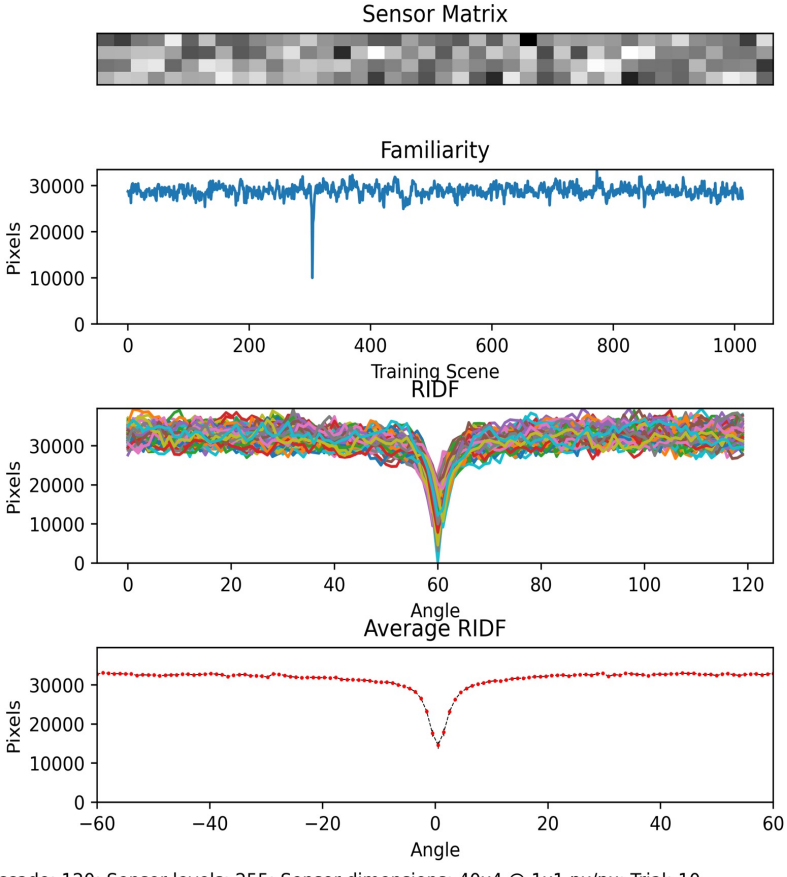


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 67.53; RMSD/dist: 0.169; TD: 9235; p90: 10; p50: 6; complete: 0

100%

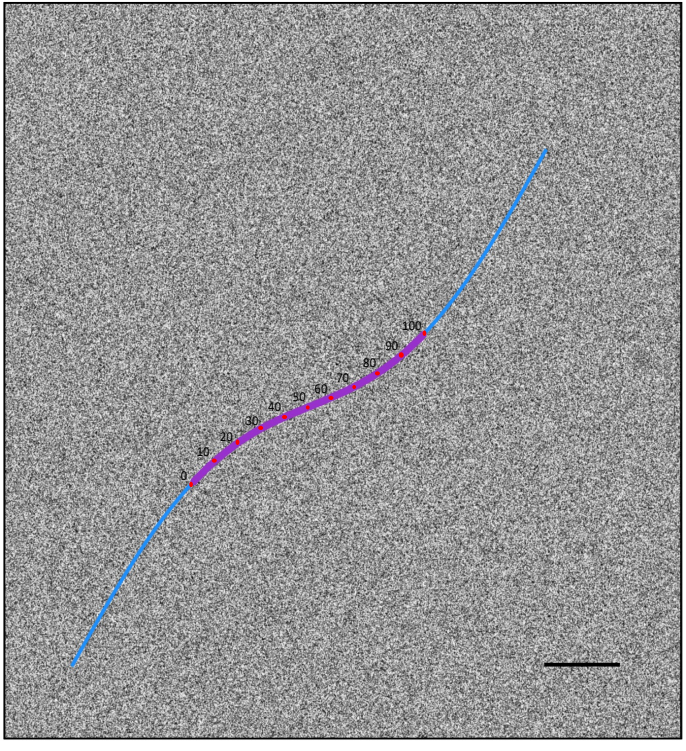


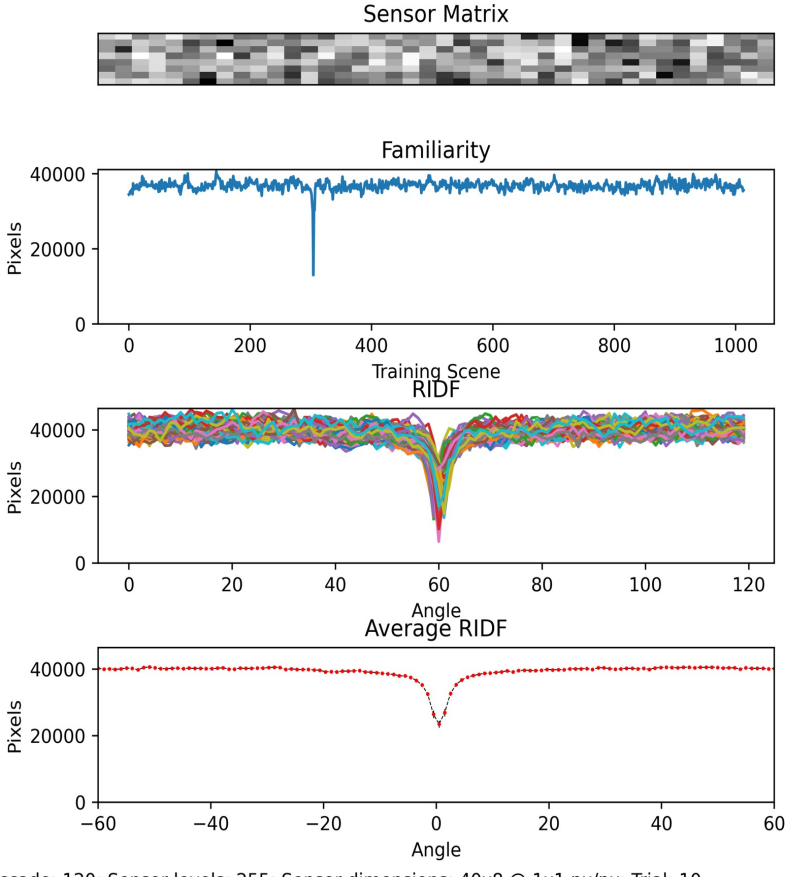


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 42.50; RMSD/dist: 0.106; TD: 13958; p90: 6; p50: 4; complete: 0

100%

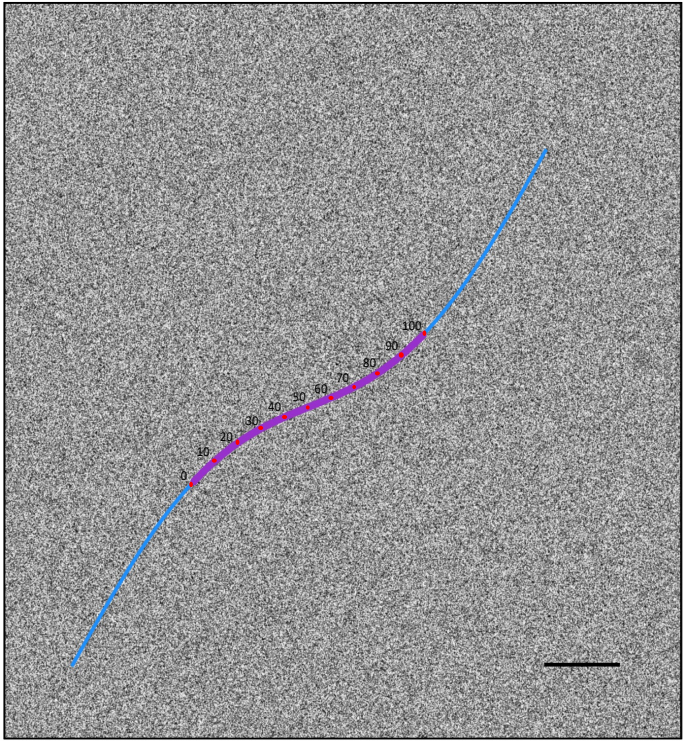


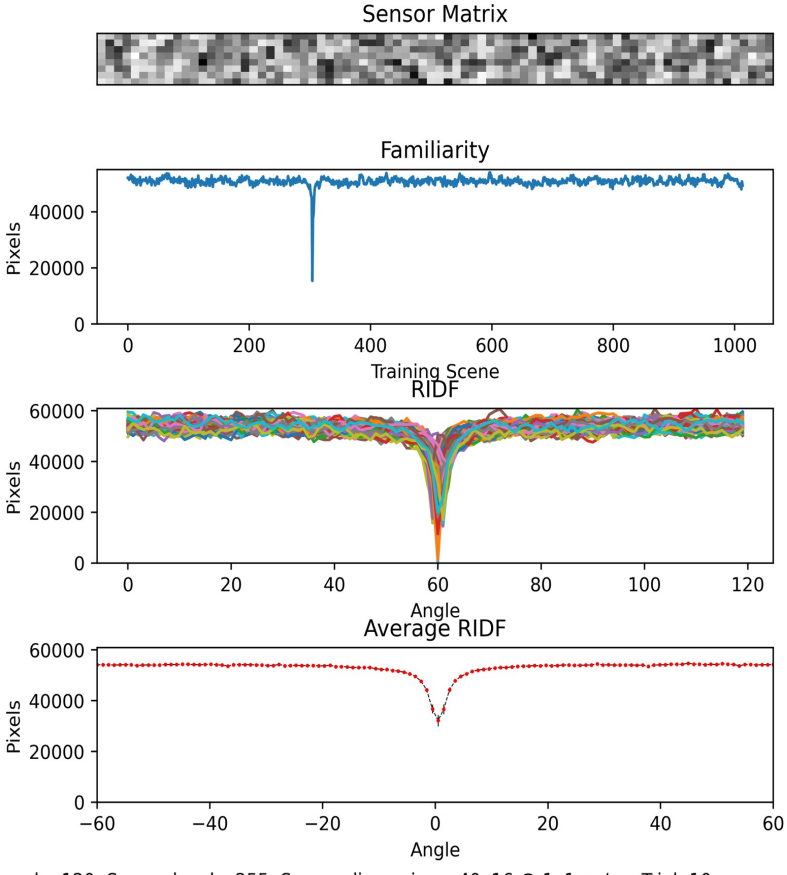


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 55.98; RMSD/dist: 0.140; TD: 12966; p90: 6; p50: 4; complete: 0

100%

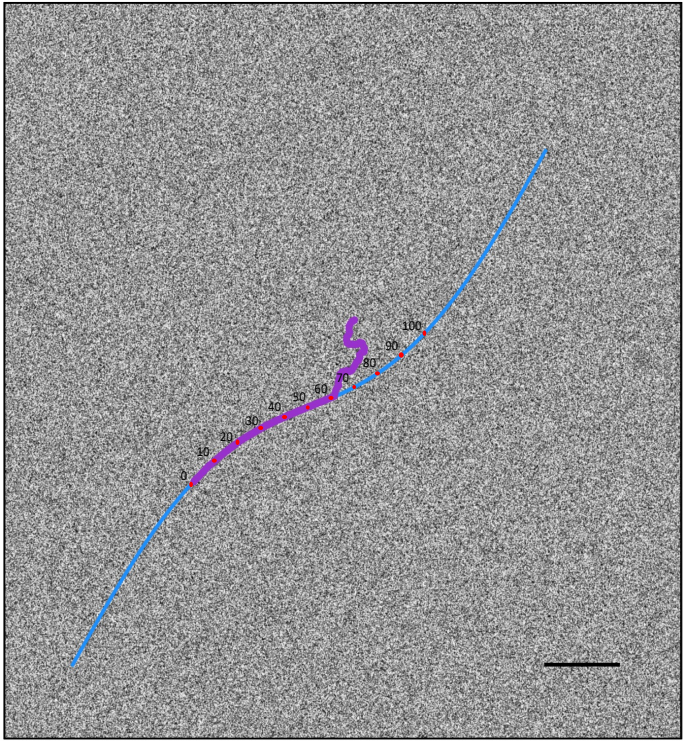


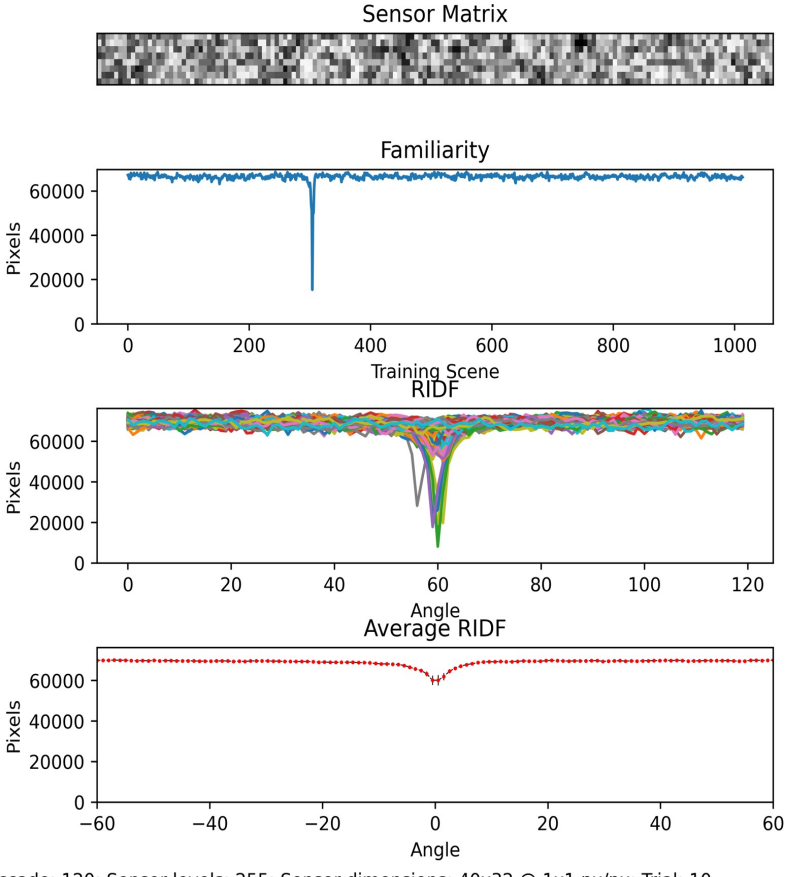


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 54.86; RMSD/dist: 0.137; TD: 18242; p90: 6; p50: 4; complete: 0

60%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1641.14; RMSD/dist: 4.103; TD: 6303; p90: 8; p50: 4; complete: 0