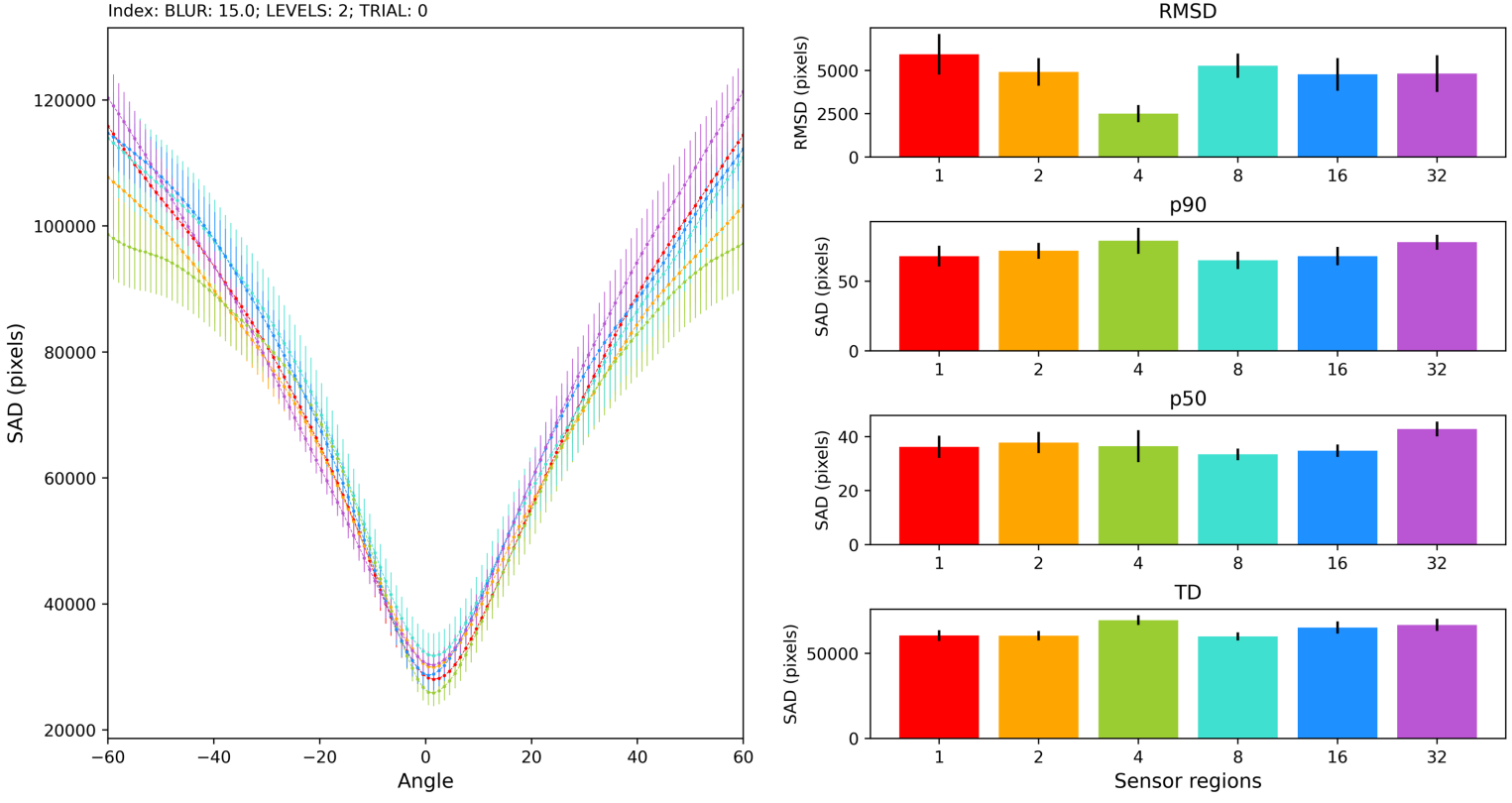
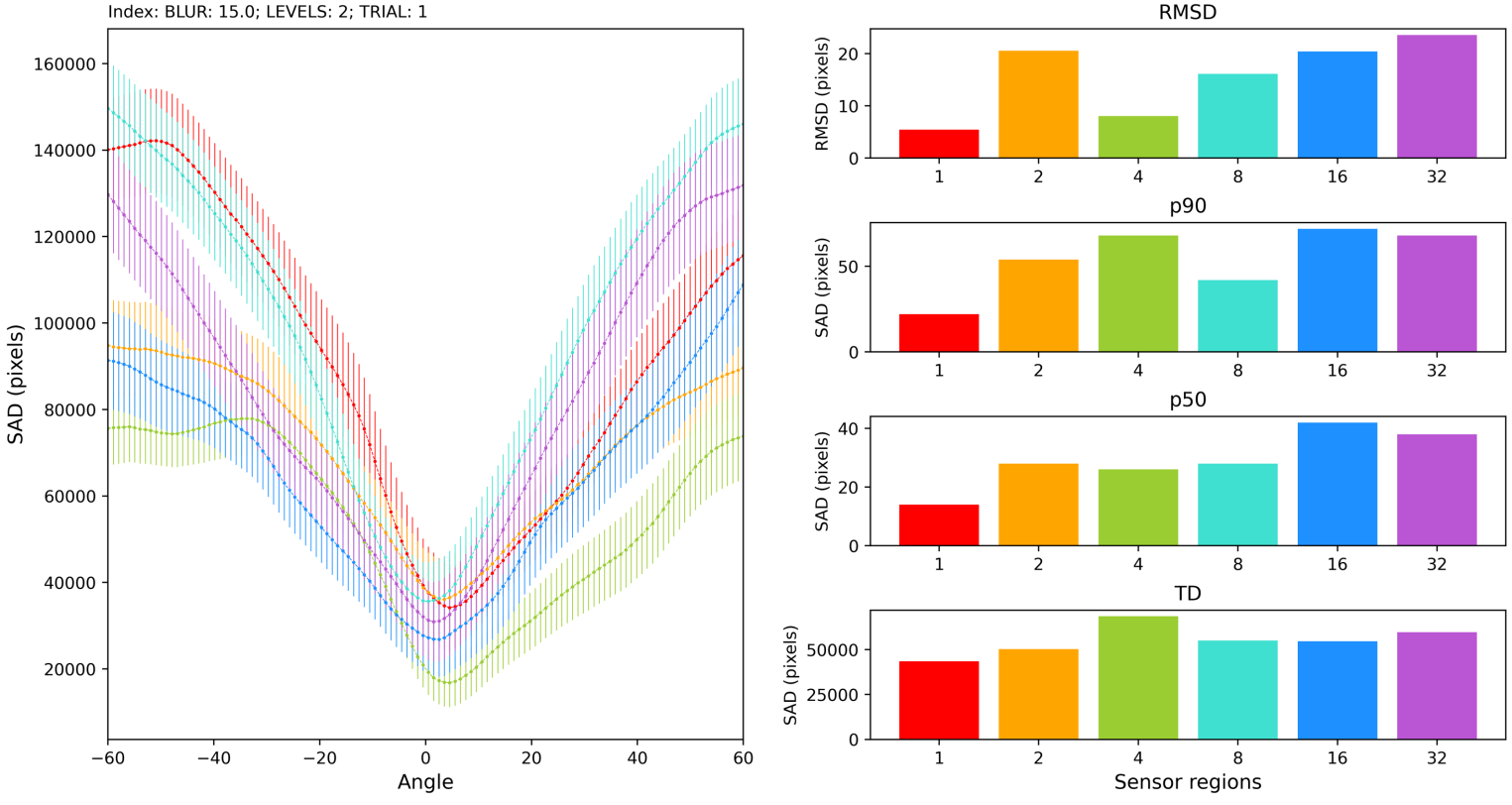

Index: BLUR: 15.0; LEVELS: 2; TRIAL: 0
SAD (pixels)
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
5000
2500
0
1
2
4
8
16
32
p90
SAD (pixels)
50
0
p50
SAD (pixels)
40
20
0
TD
SAD (pixels)
50000
0
Sensor regions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SAD (pixels)
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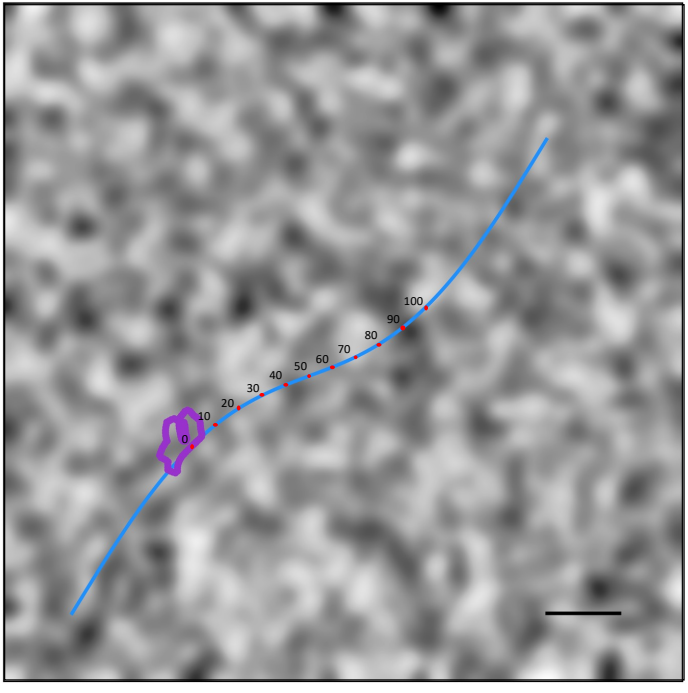
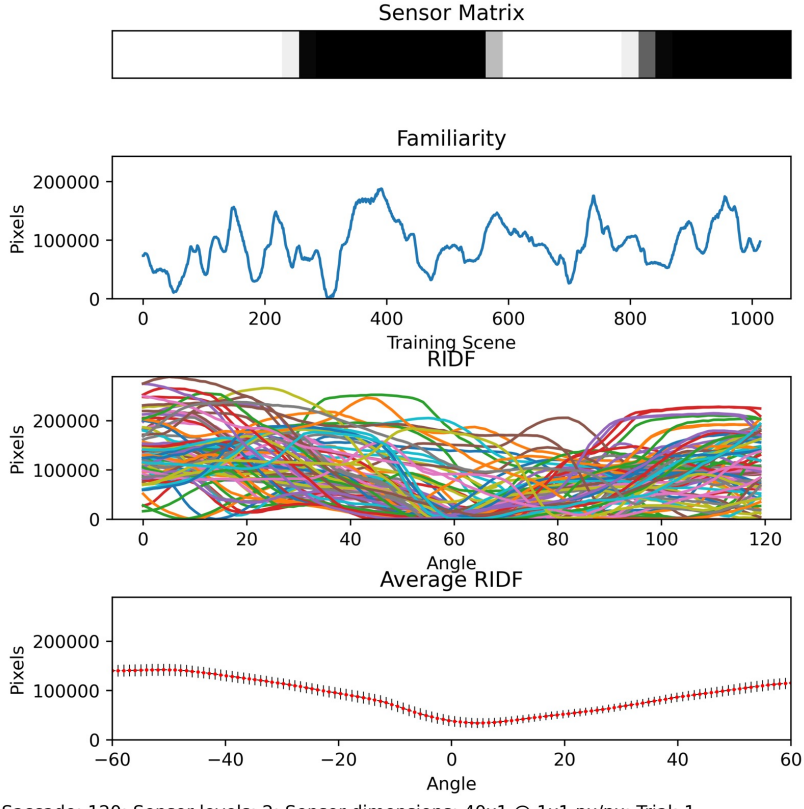
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
50
0
p50
SAD (pixels)
40
20
0
TD
SAD (pixels)
50000
25000
0
Sensor regions

0%

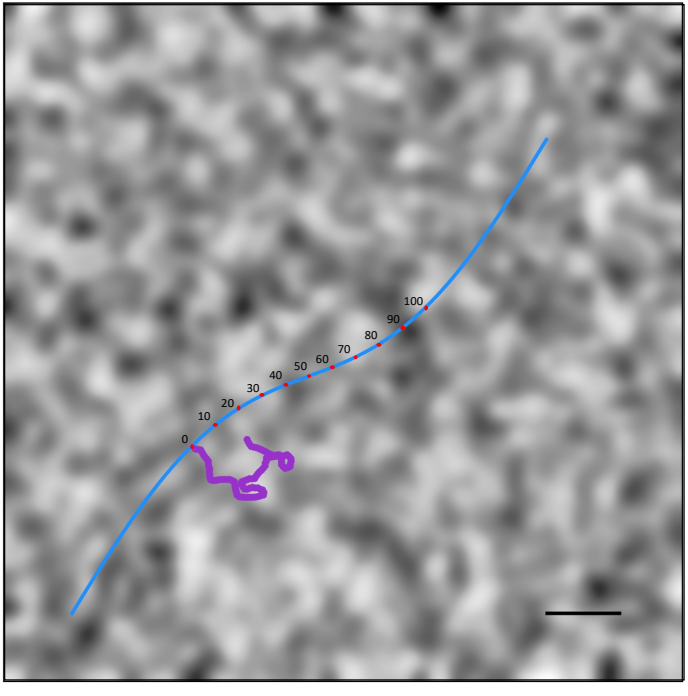


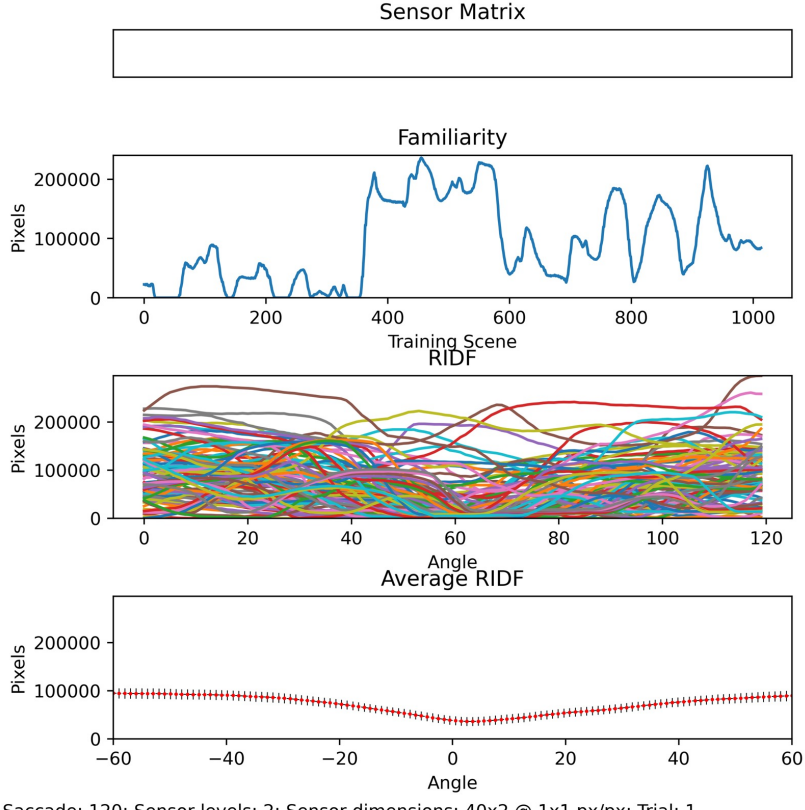


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2176.85; RMSD/dist: 5.442; TD: 43461; p90: 22; p50: 14; complete: 0

0%

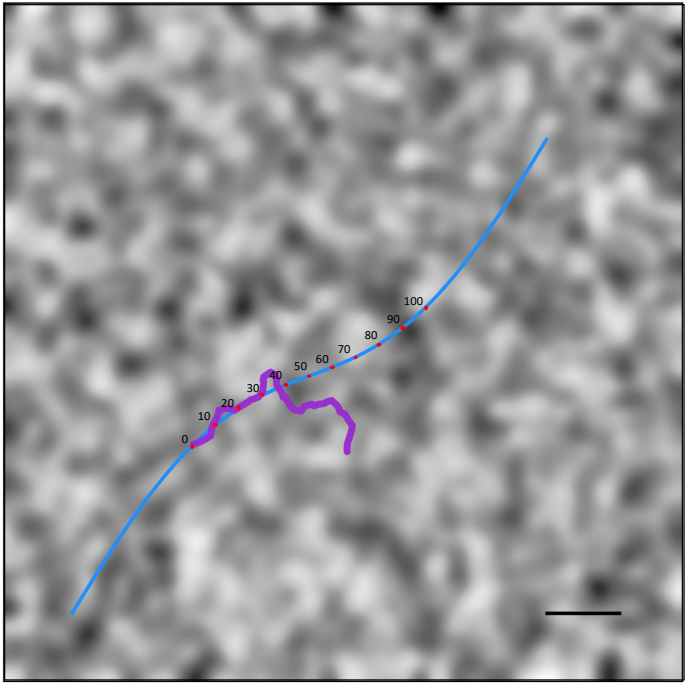


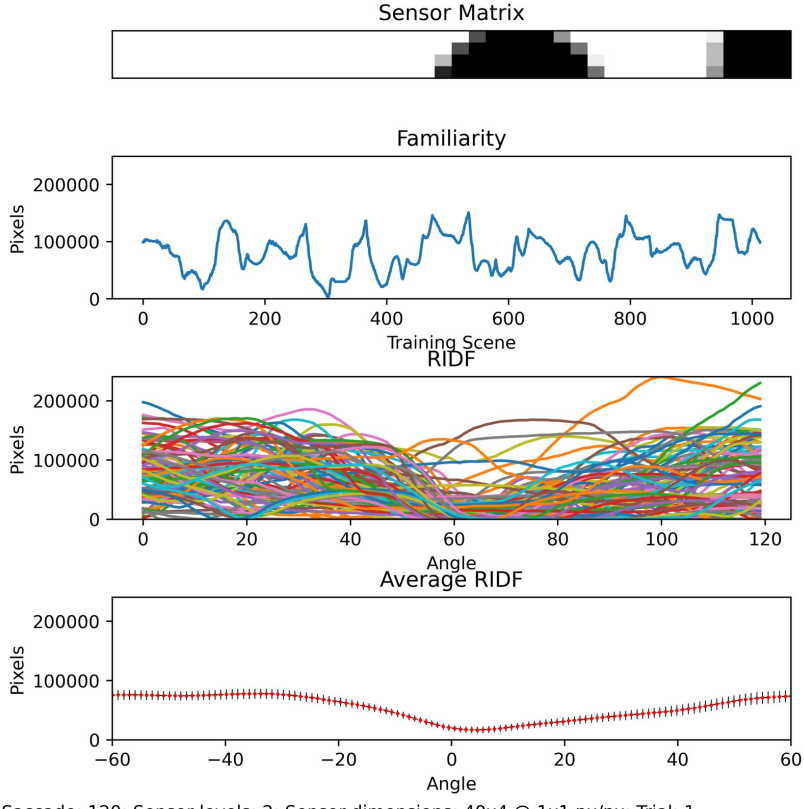


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 8230.38; RMSD/dist: 20.576; TD: 50273; p90: 54; p50: 28; complete: 0

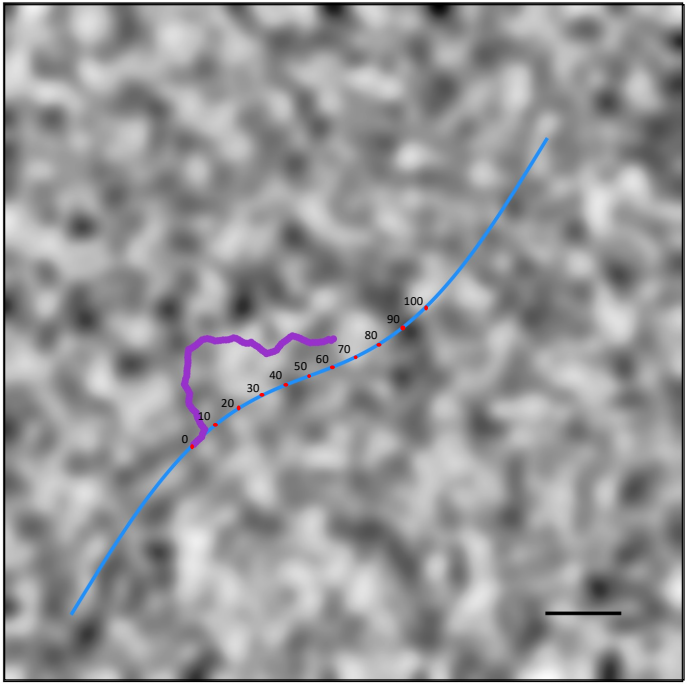
10%

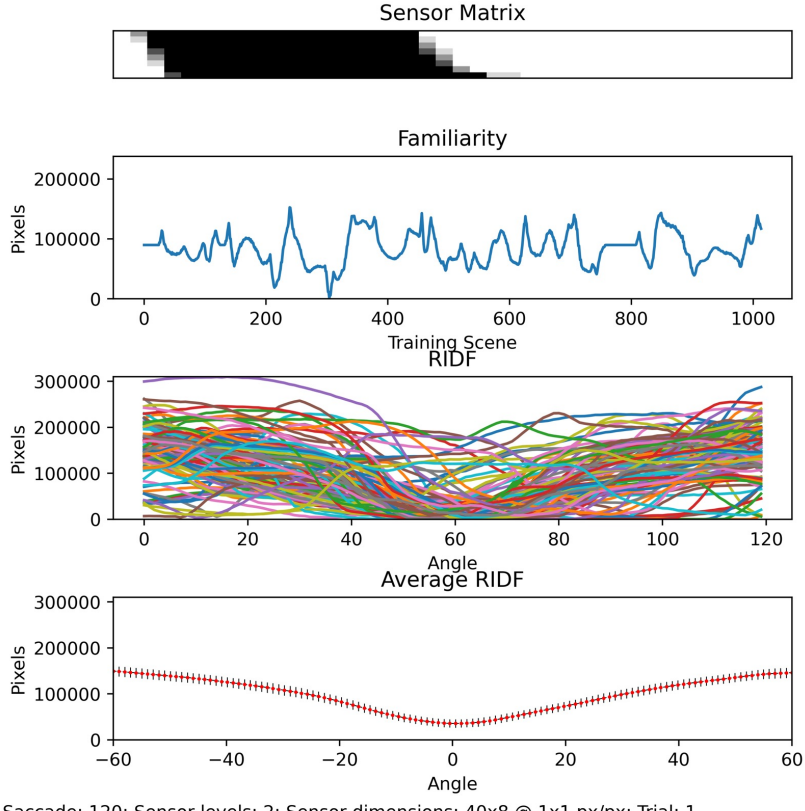




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 3213.26; RMSD/dist: 8.033; TD: 68494; p90: 68; p50: 26; complete: 0

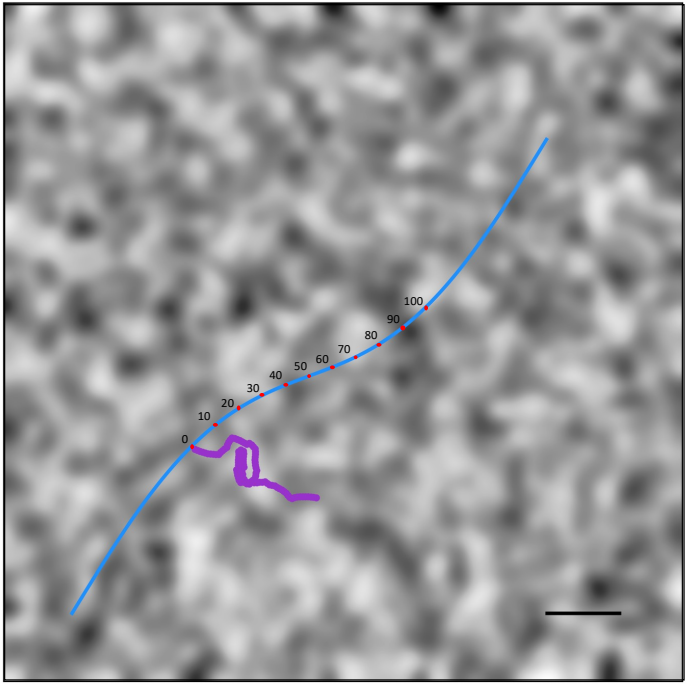
0%

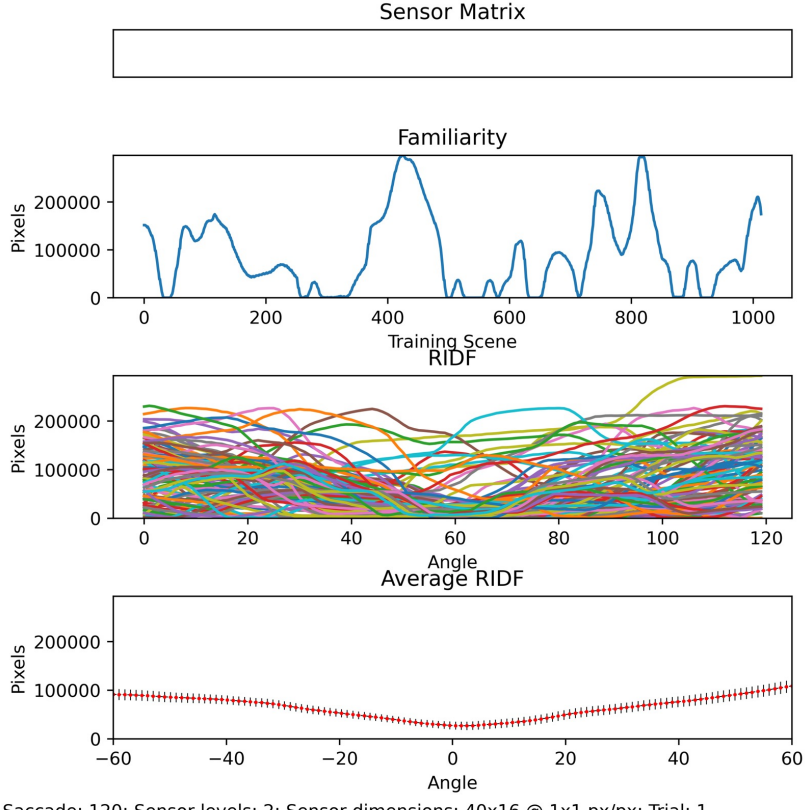




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 6450.51; RMSD/dist: 16.126; TD: 54969; p90: 42; p50: 28; complete: 0

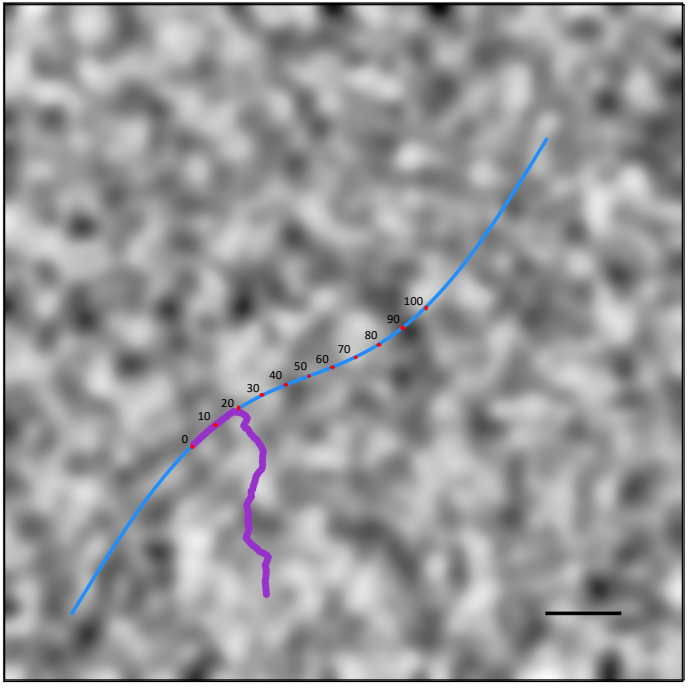
0%

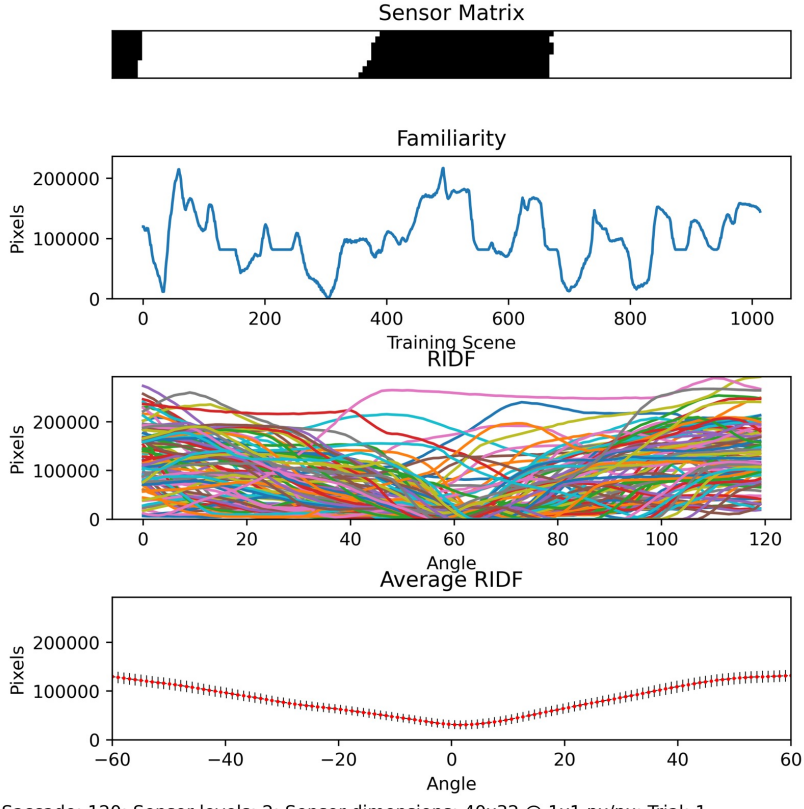




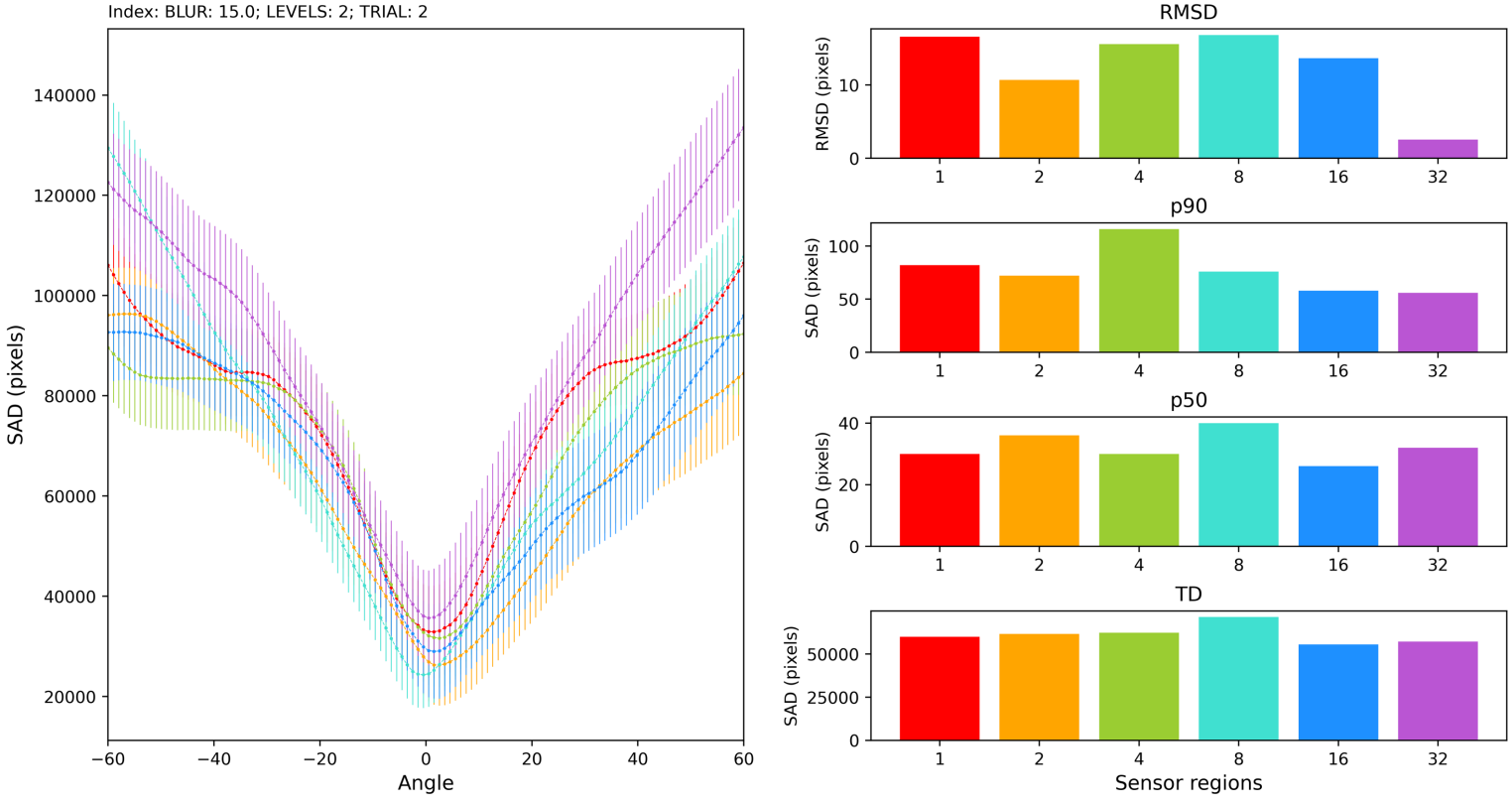
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 8161.44; RMSD/dist: 20.404; TD: 54682; p90: 72; p50: 42; complete: 0

10%

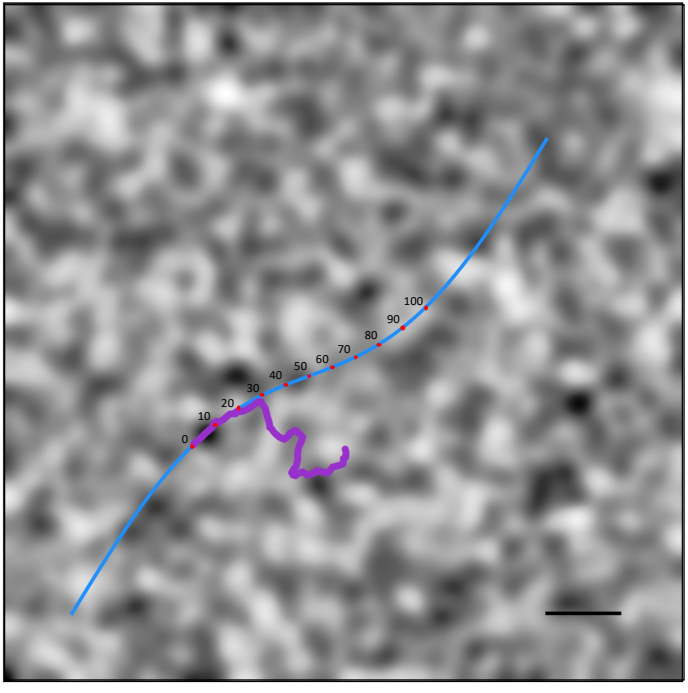


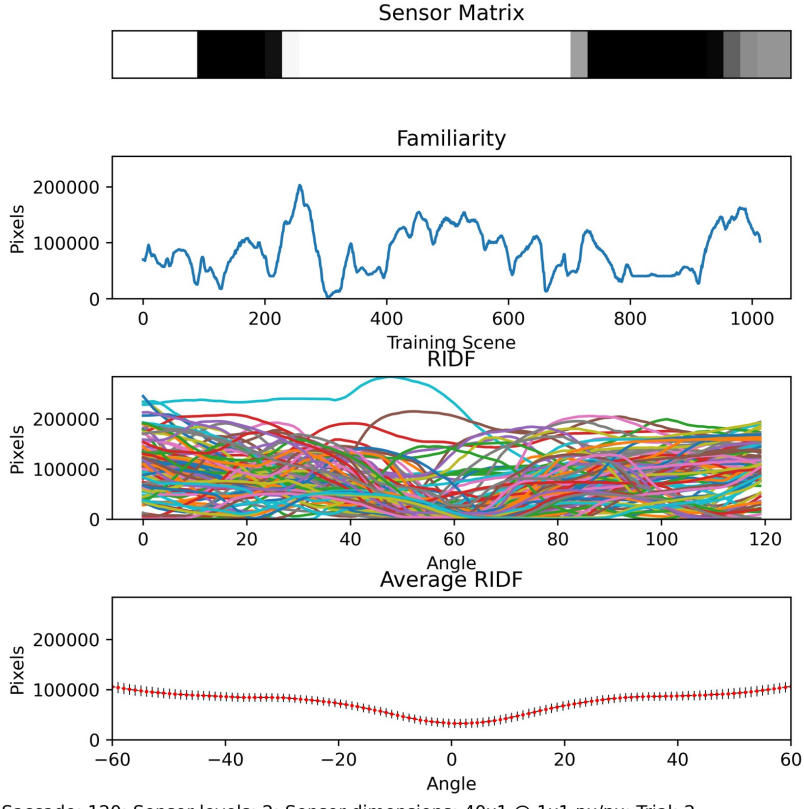


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 9437.57; RMSD/dist: 23.594; TD: 59679; p90: 68; p50: 38; complete: 0


Index: BLUR: 15.0; LEVELS: 2; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

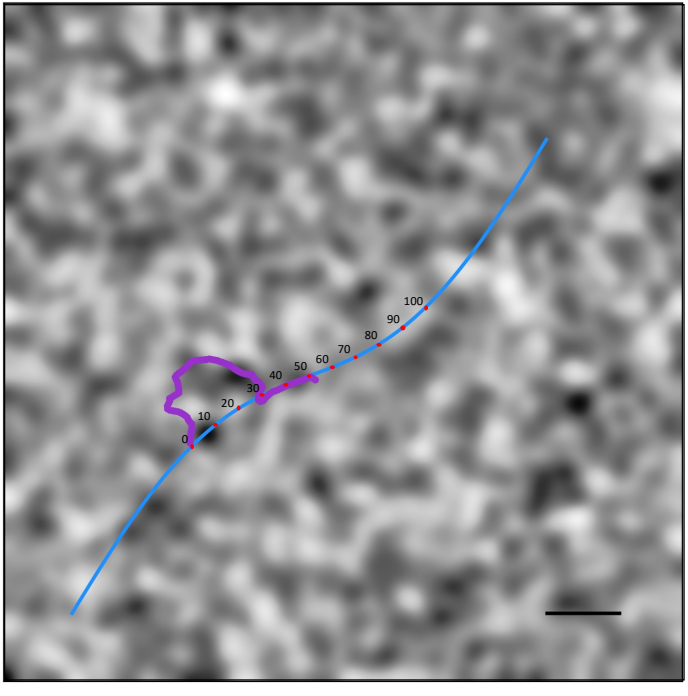
10%

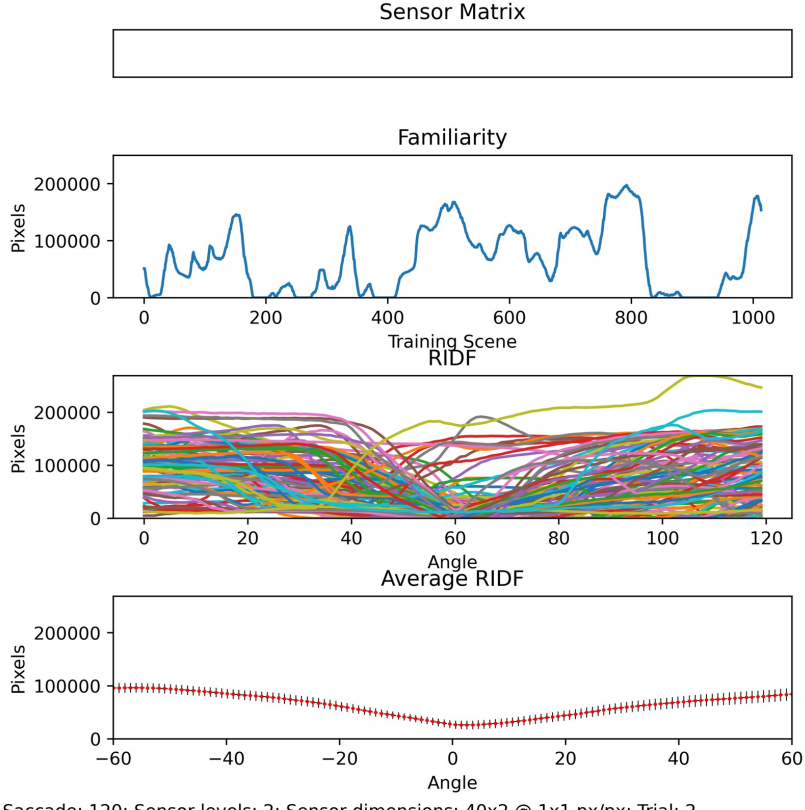




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 6639.11; RMSD/dist: 16.598; TD: 59865; p90: 82; p50: 30; complete: 0

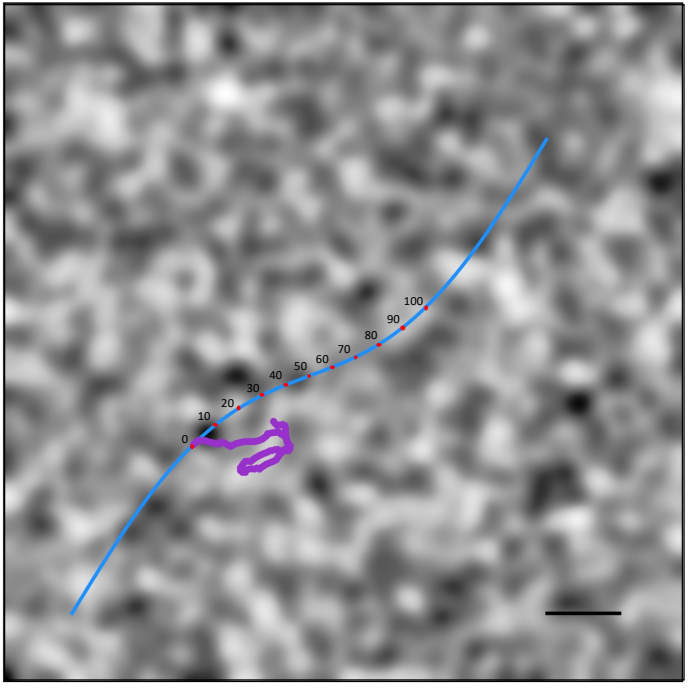
10%

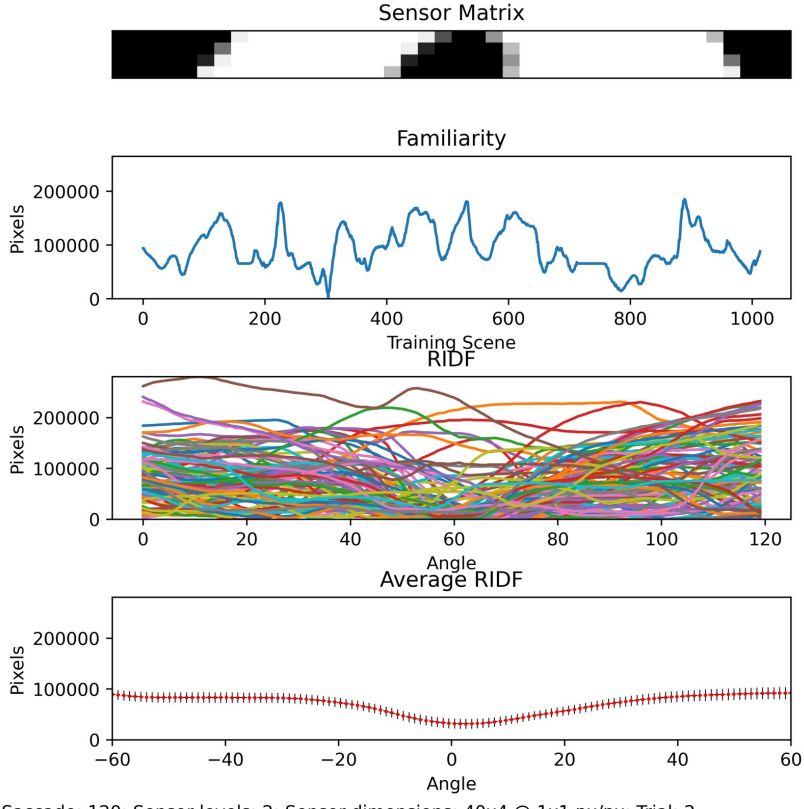




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 4280.98; RMSD/dist: 10.702; TD: 61602; p90: 72; p50: 36; complete: 0

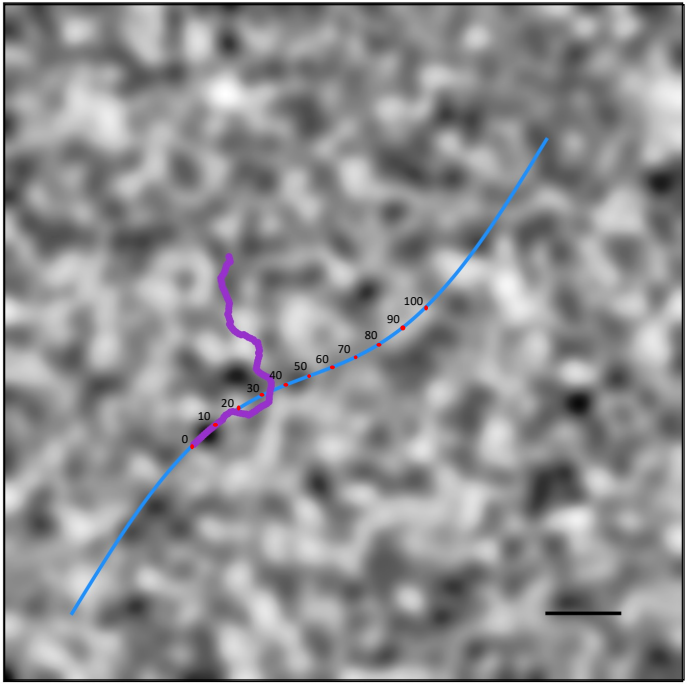
0%

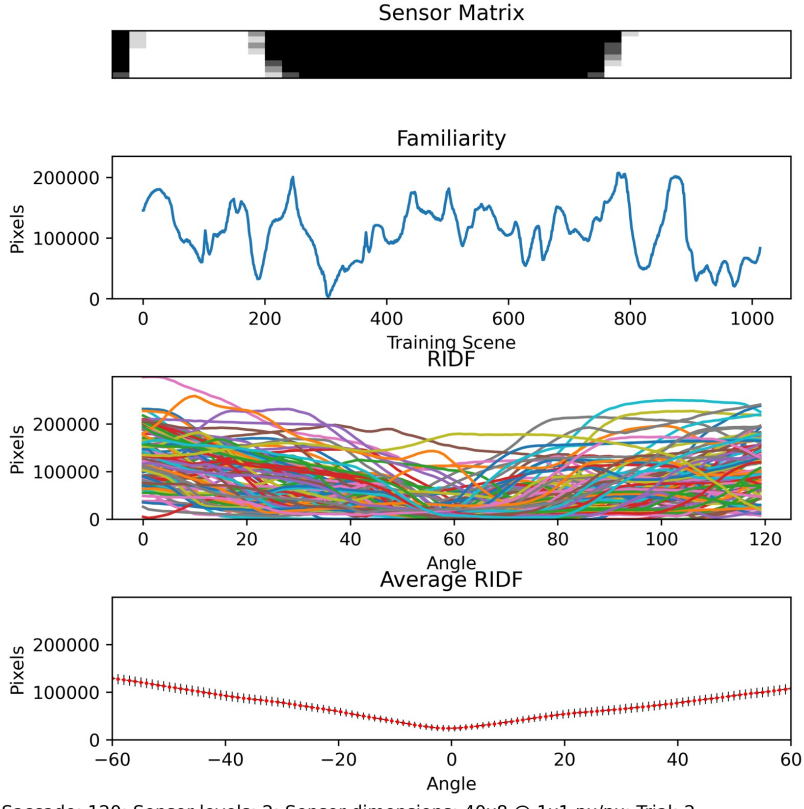




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 6236.58; RMSD/dist: 15.591; TD: 62322; p90: 116; p50: 30; complete: 0

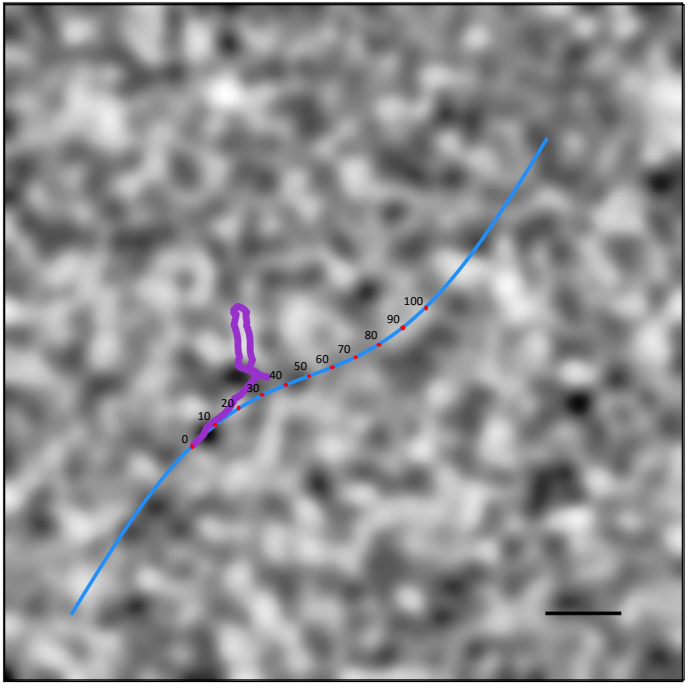
10%

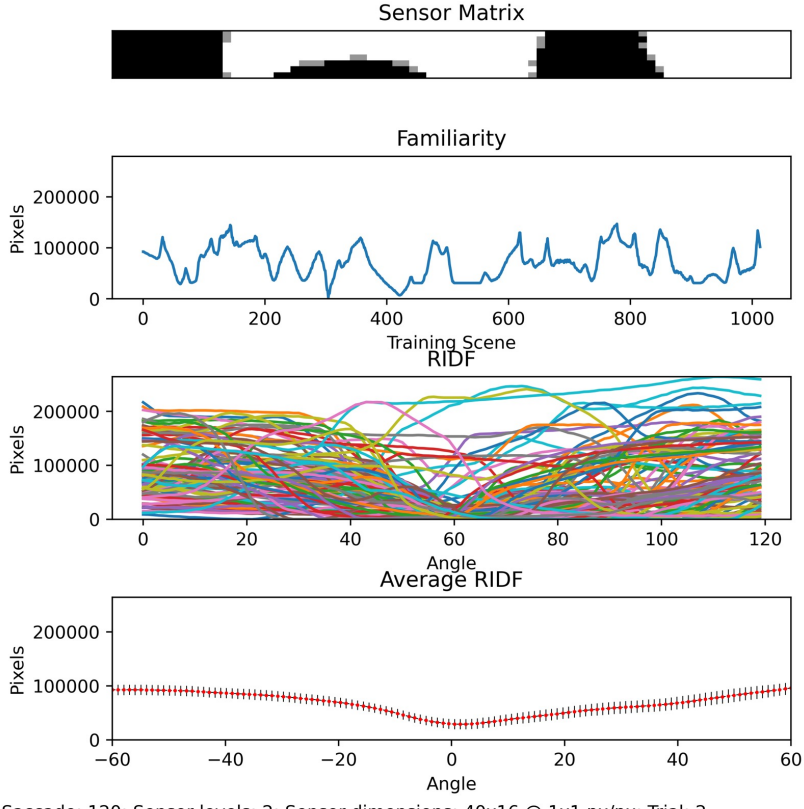




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 6730.03; RMSD/dist: 16.825; TD: 71337; p90: 76; p50: 40; complete: 0

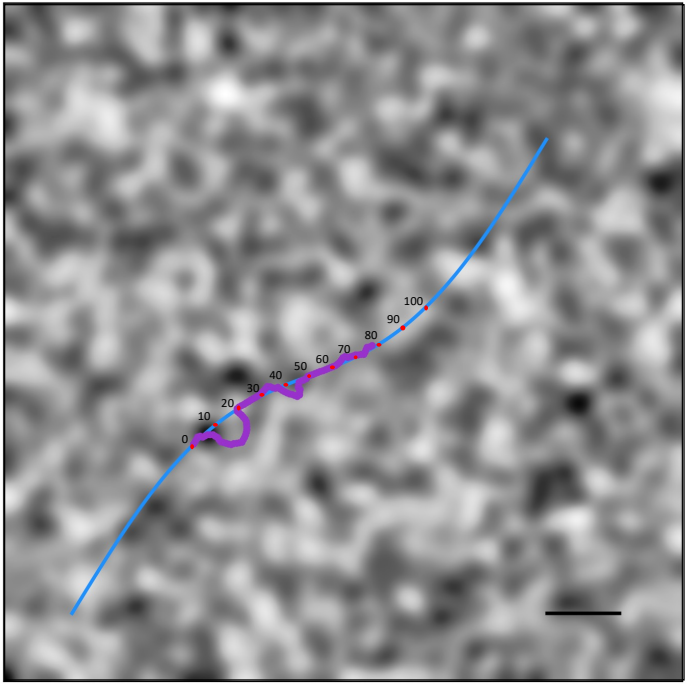
0%

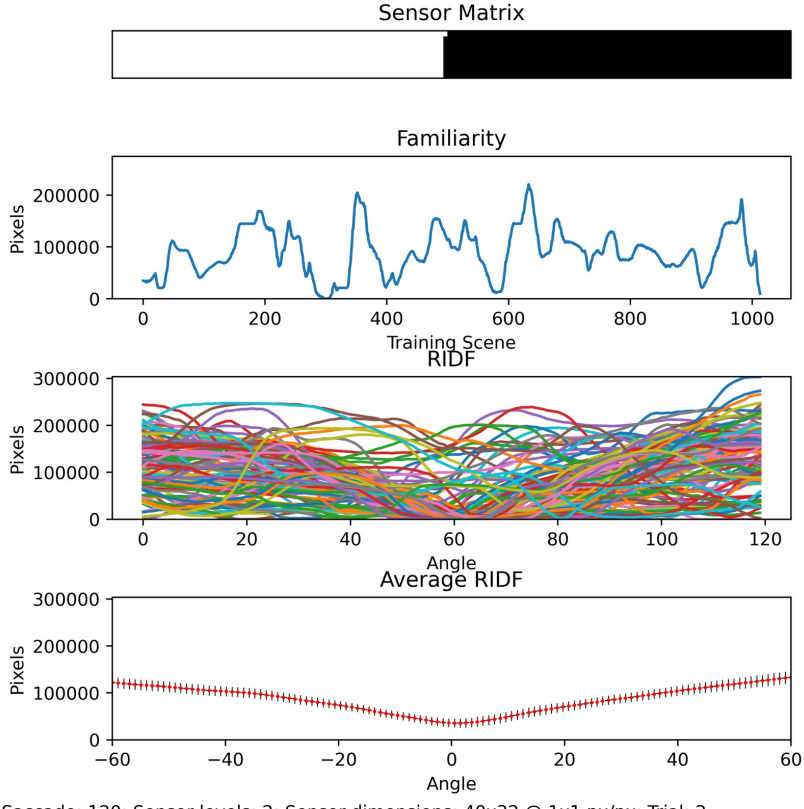




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 5458.19; RMSD/dist: 13.645; TD: 55492; p90: 58; p50: 26; complete: 0

20%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2
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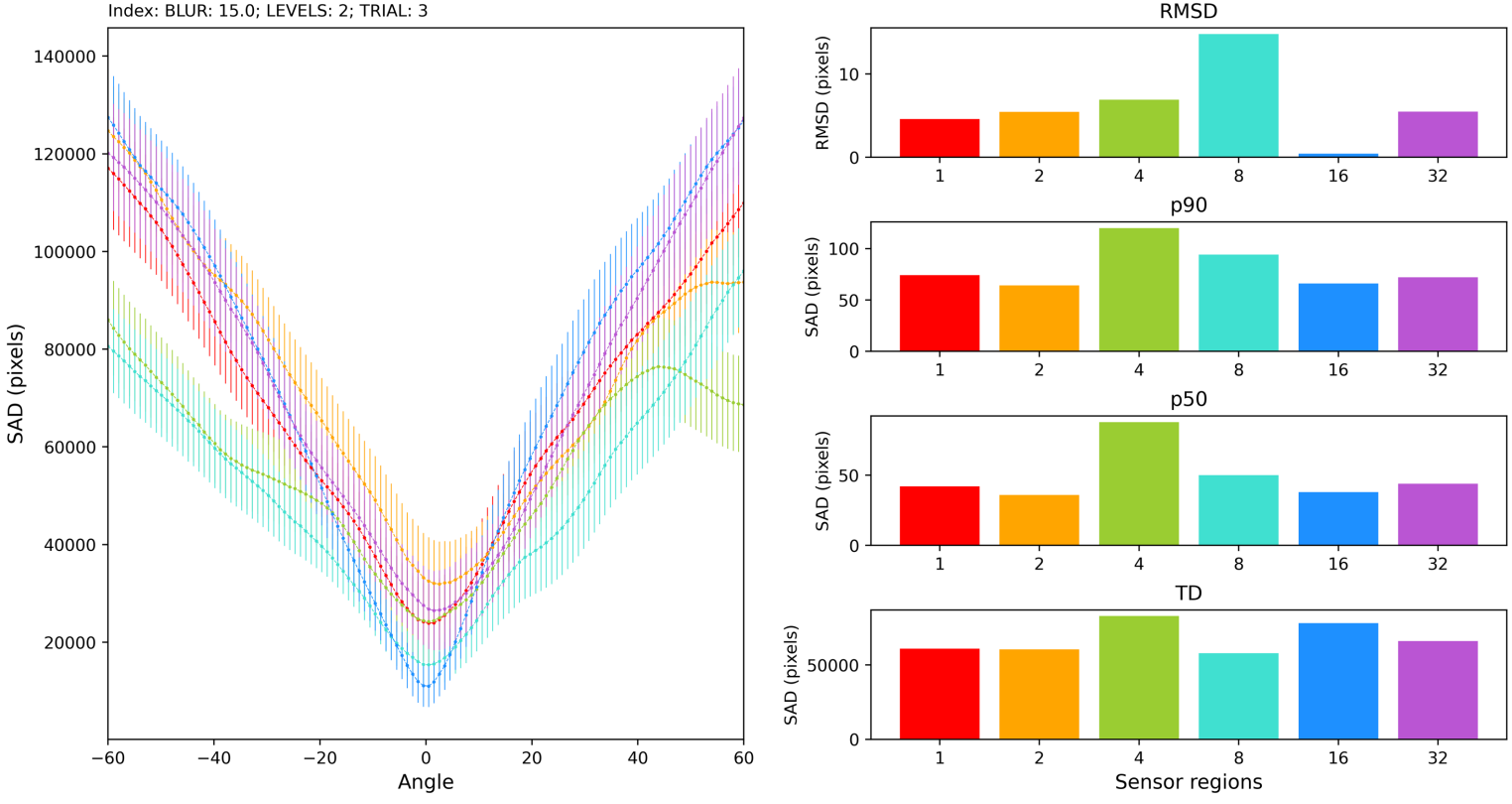
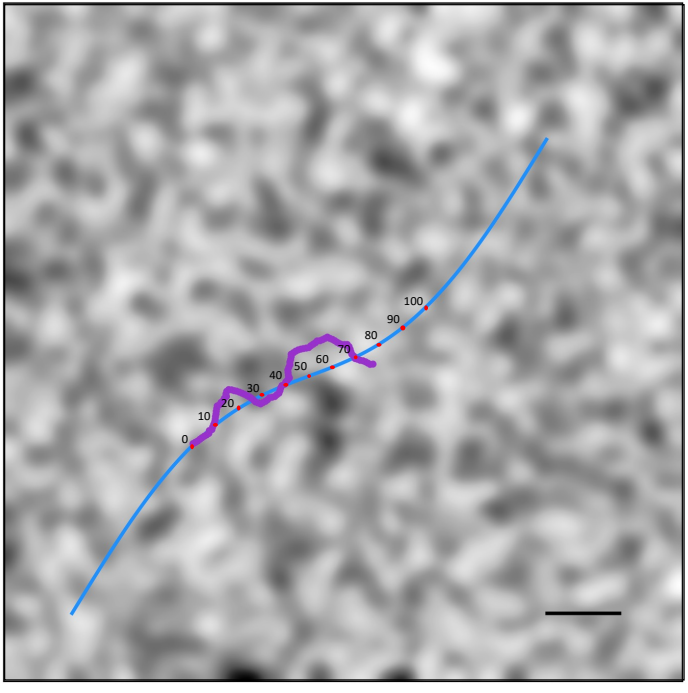
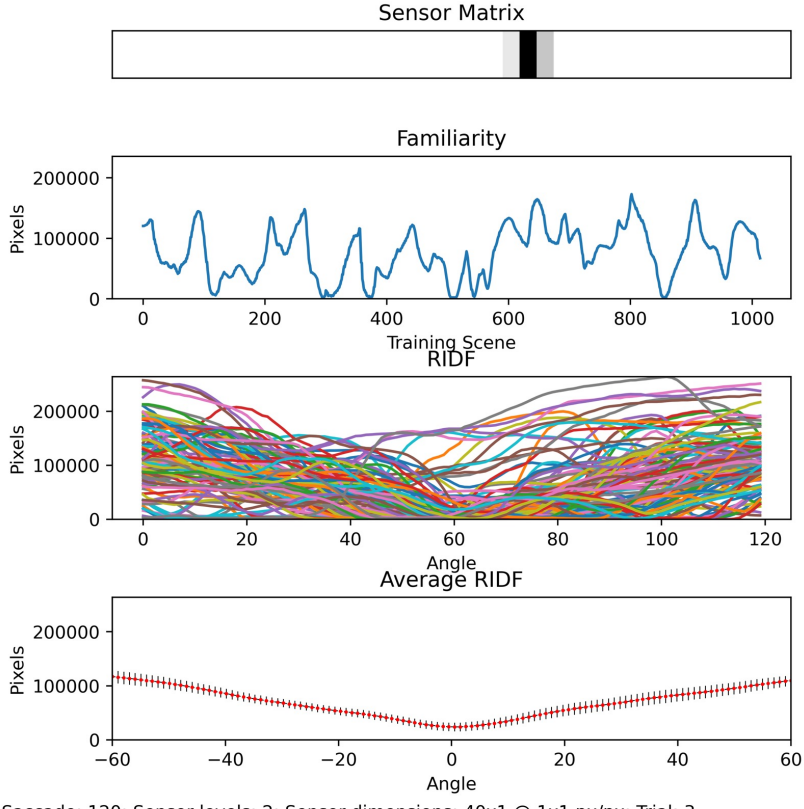

Index: BLUR: 15.0; LEVELS: 2; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

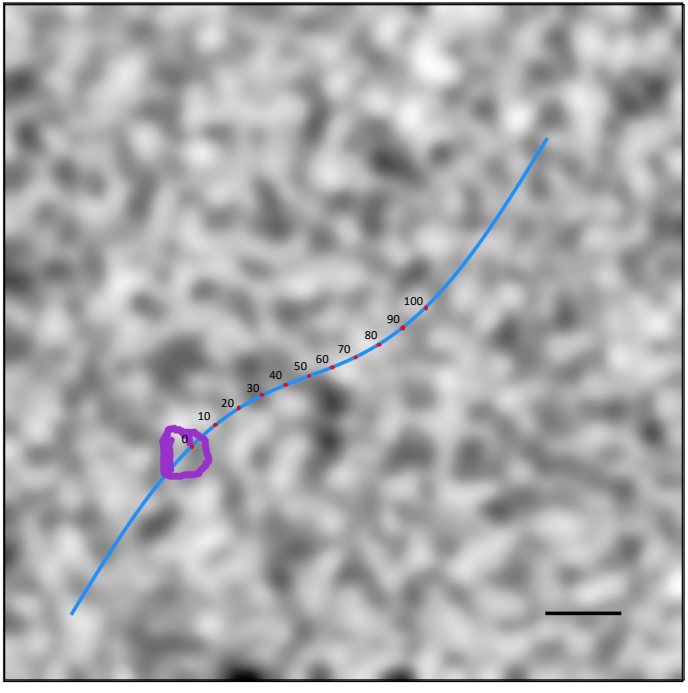


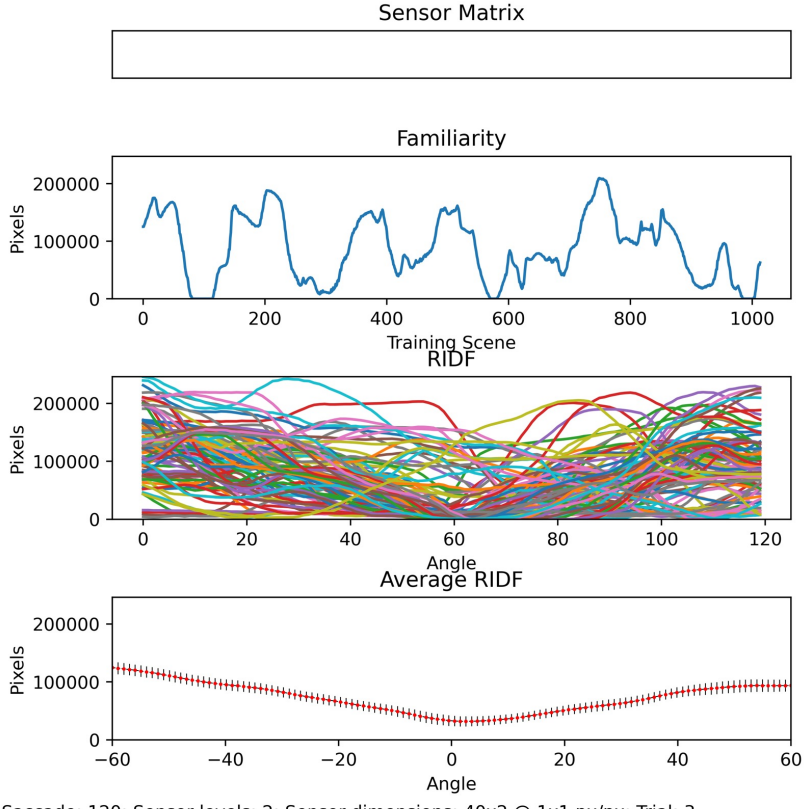


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1832.40; RMSD/dist: 4.581; TD: 60833; p90: 74; p50: 42; complete: 0

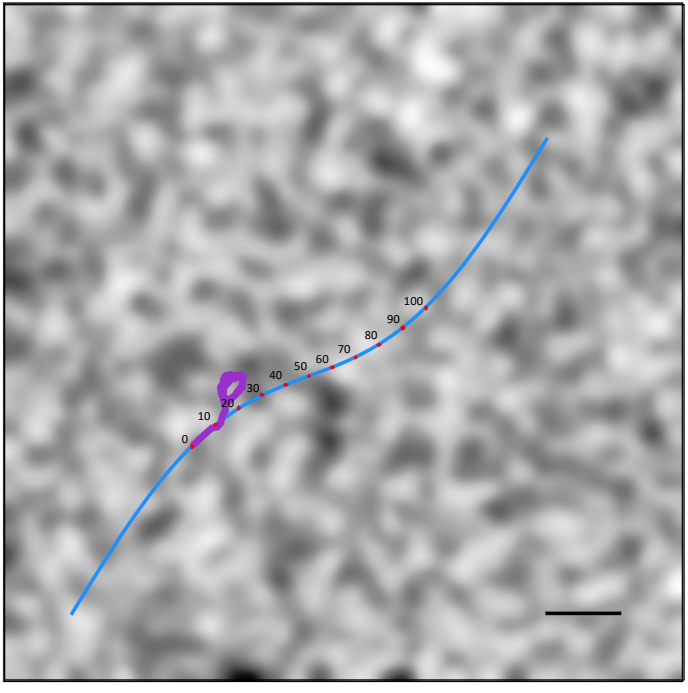
0%

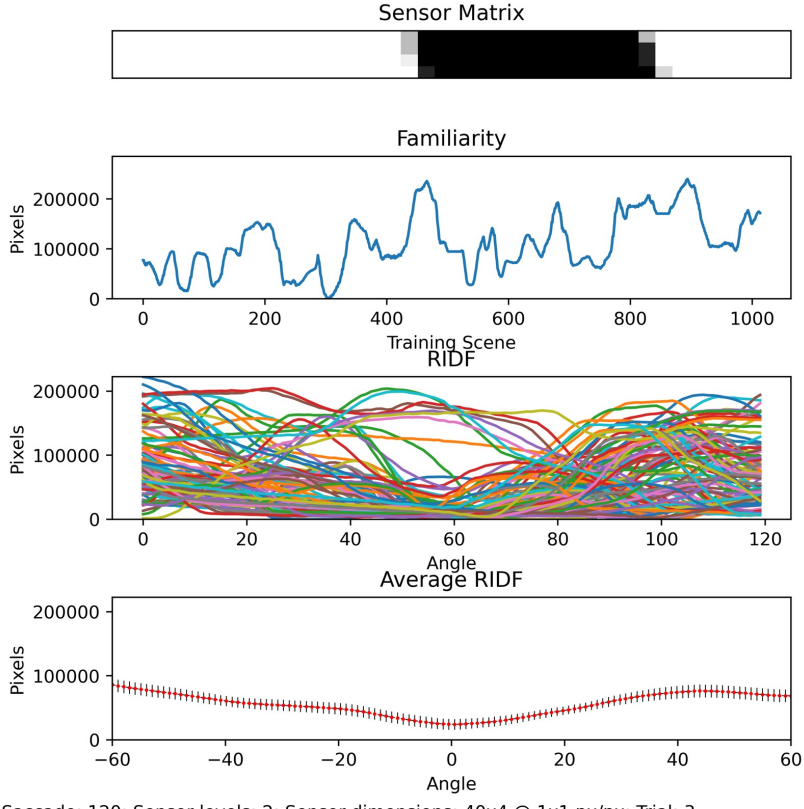




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 2175.35; RMSD/dist: 5.438; TD: 60340; p90: 64; p50: 36; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 2763.49; RMSD/dist: 6.909; TD: 82750; p90: 120; p50: 88; complete: 0

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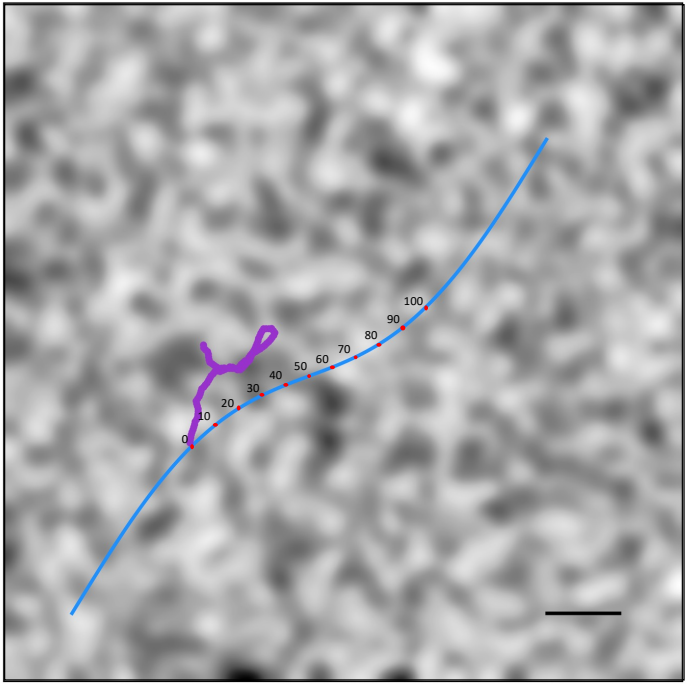
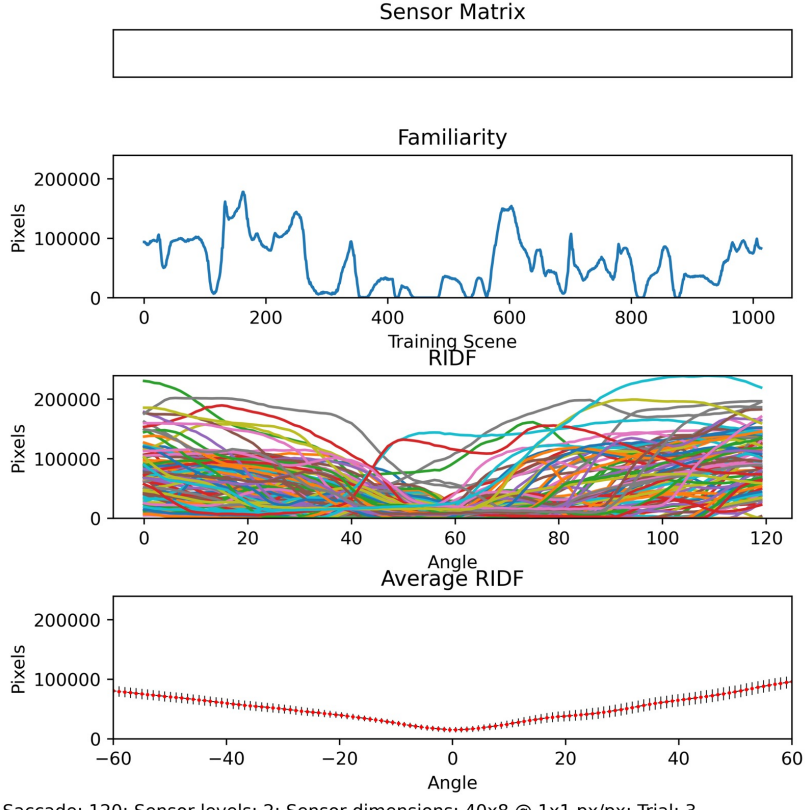
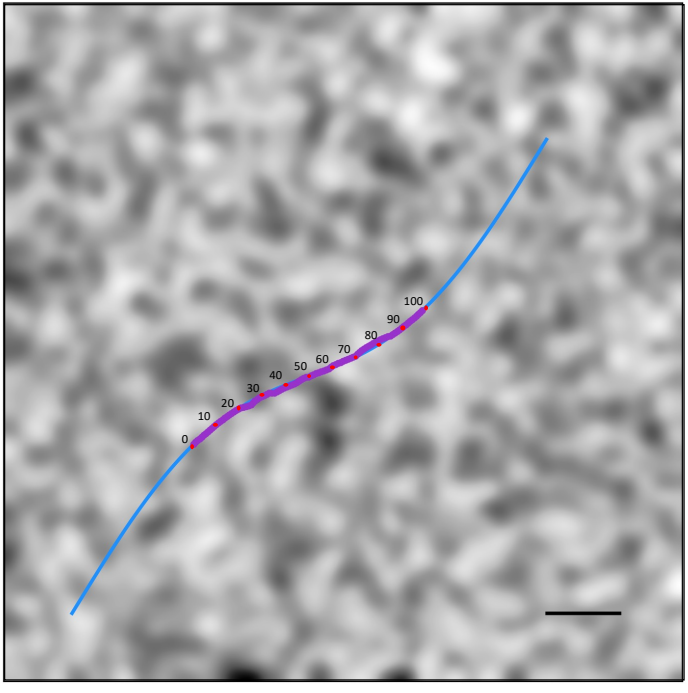
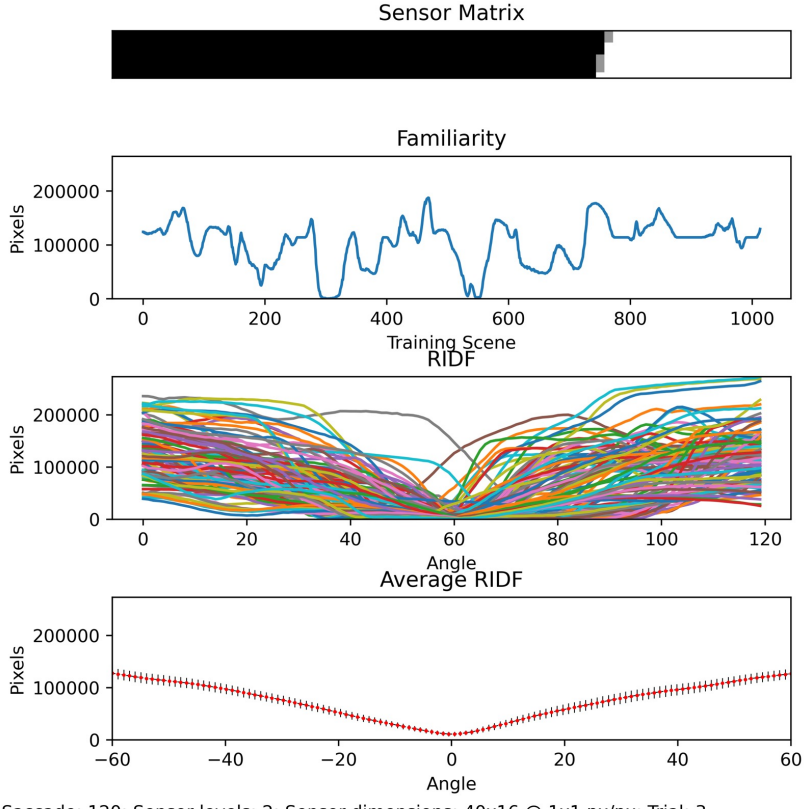




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 5918.42; RMSD/dist: 14.796; TD: 57791; p90: 94; p50: 50; complete: 0

80%





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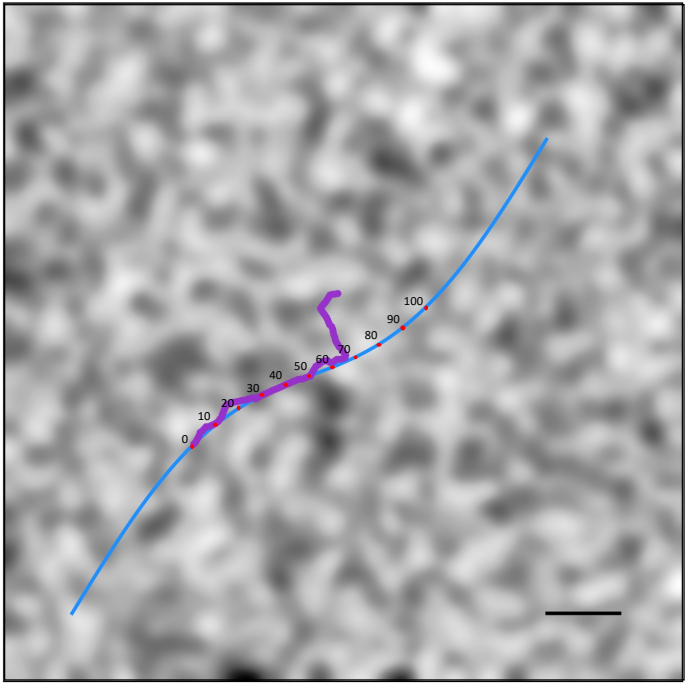
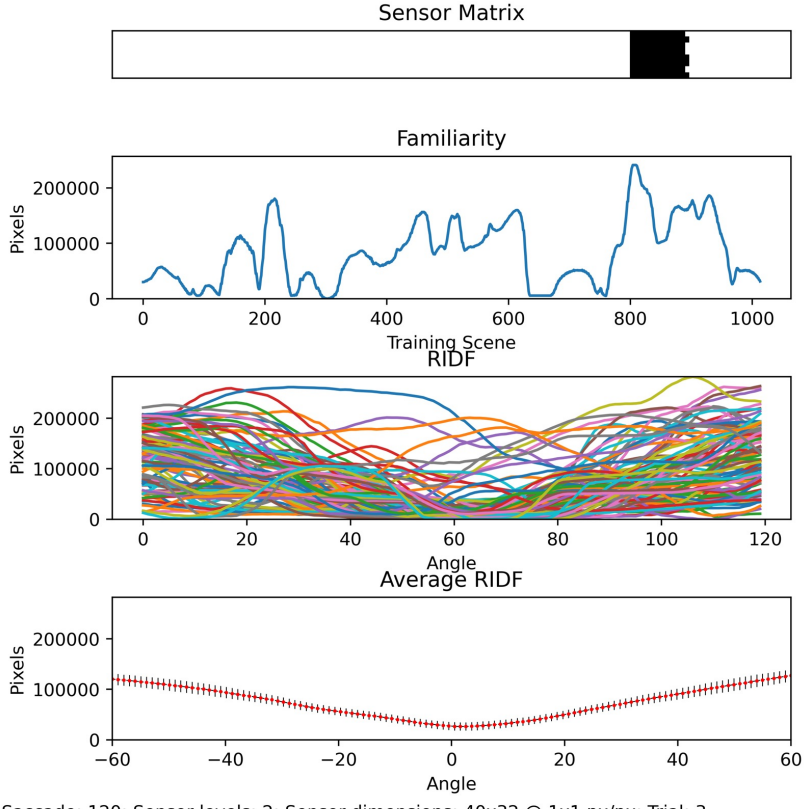
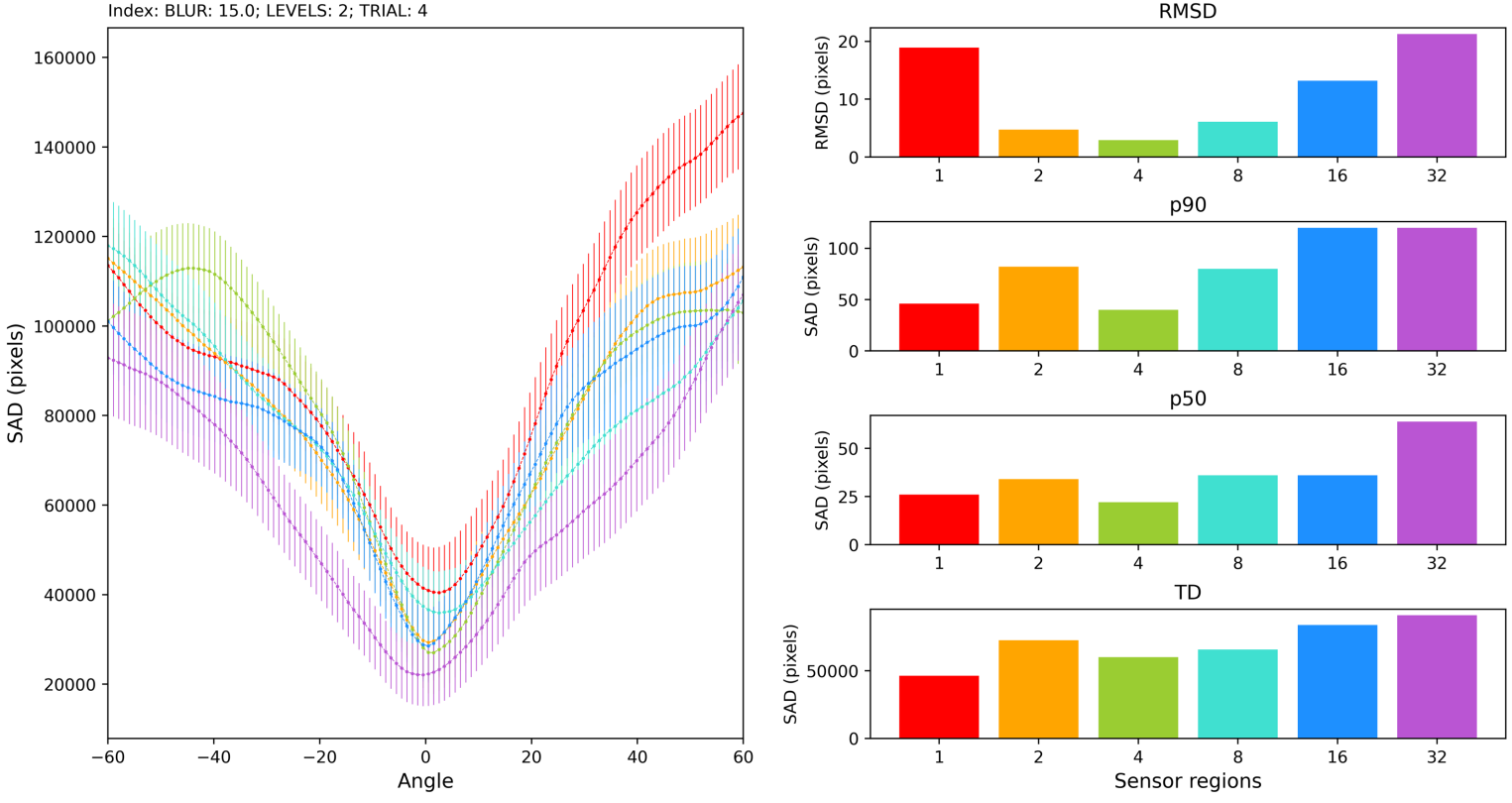
Navigation stats: RMSD error: 174.43; RMSD/dist: 0.436; TD: 78002; p90: 66; p50: 38; complete: 0

20%

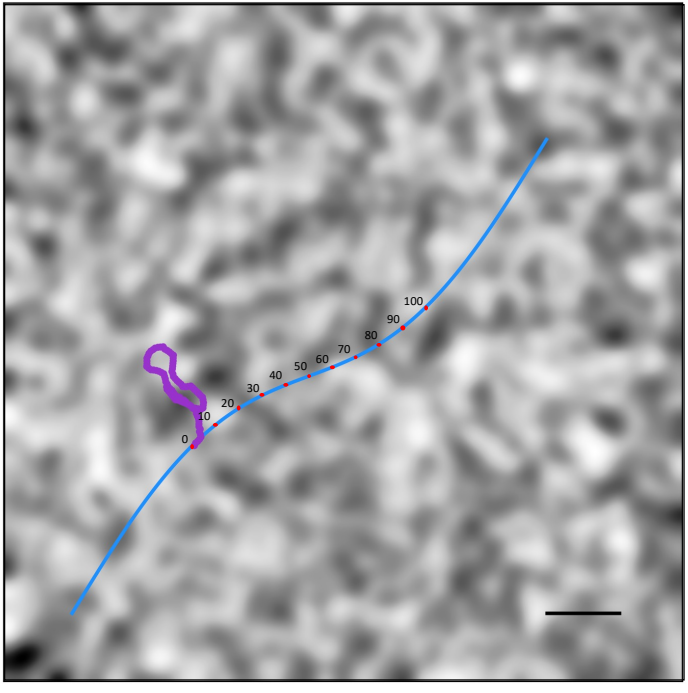


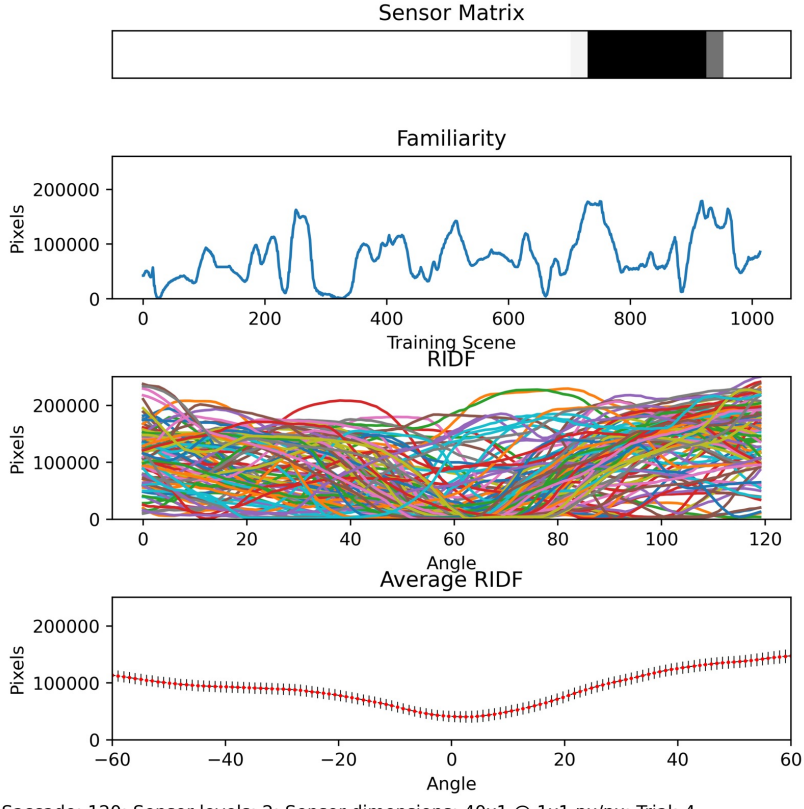


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 2193.29; RMSD/dist: 5.483; TD: 66060; p90: 72; p50: 44; complete: 0


Index: BLUR: 15.0; LEVELS: 2; TRIAL: 4
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
SAD (pixels)
50
25
0
TD
SAD (pixels)
50000
0
Sensor regions

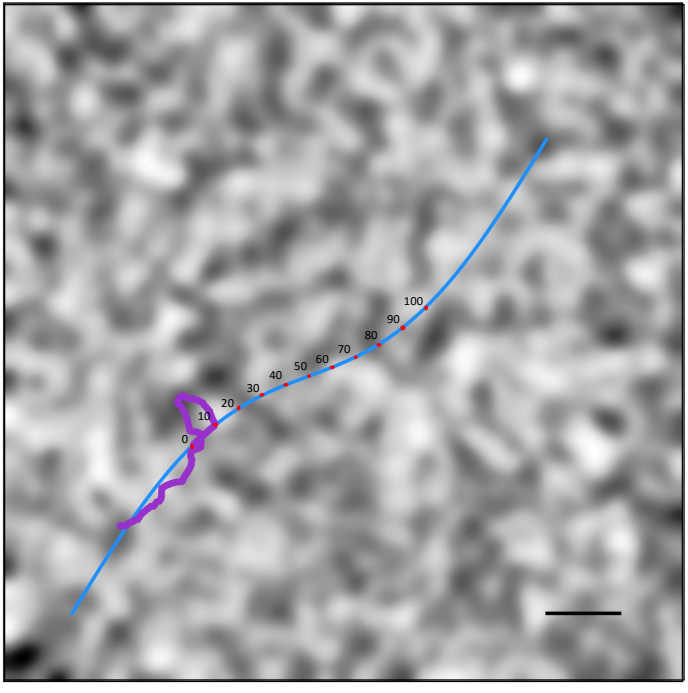
0%

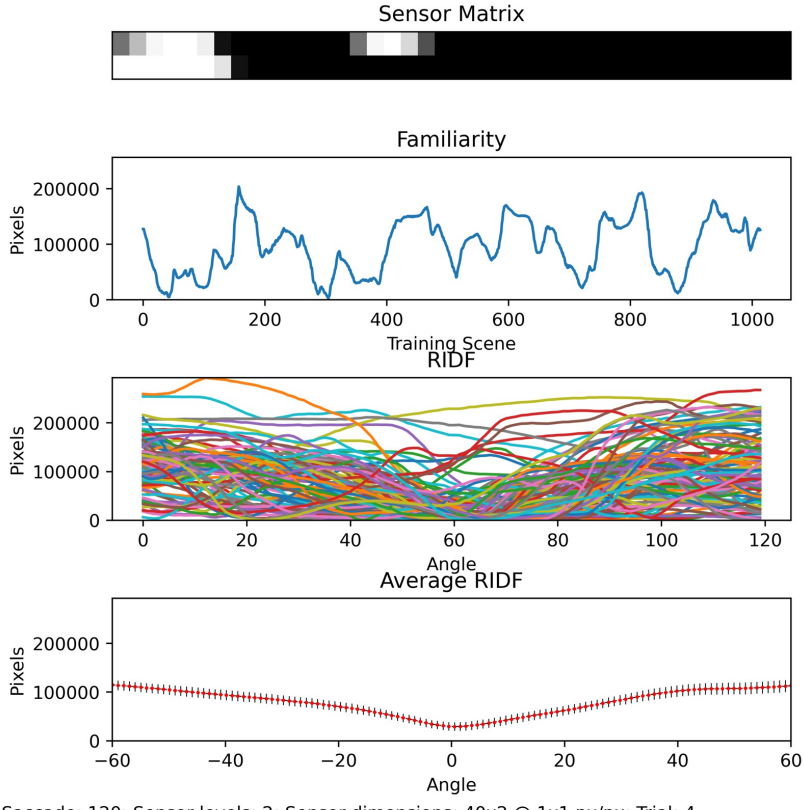




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 7567.04; RMSD/dist: 18.918; TD: 46328; p90: 46; p50: 26; complete: 0

10%

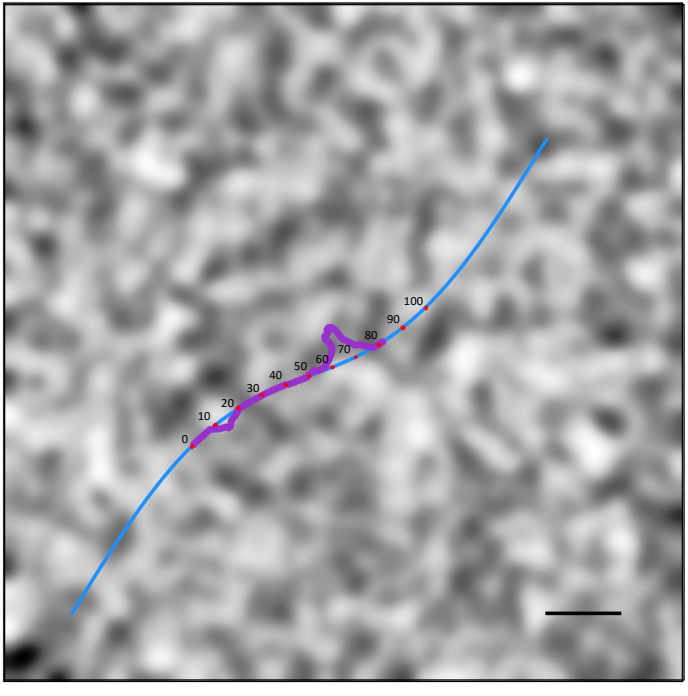


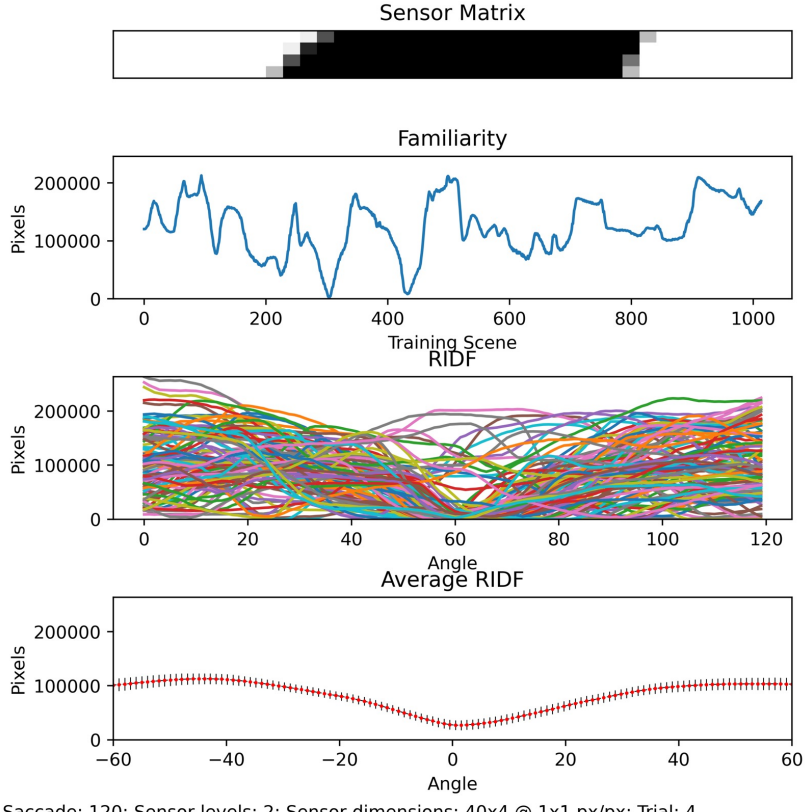


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1901.42; RMSD/dist: 4.754; TD: 72451; p90: 82; p50: 34; complete: 0

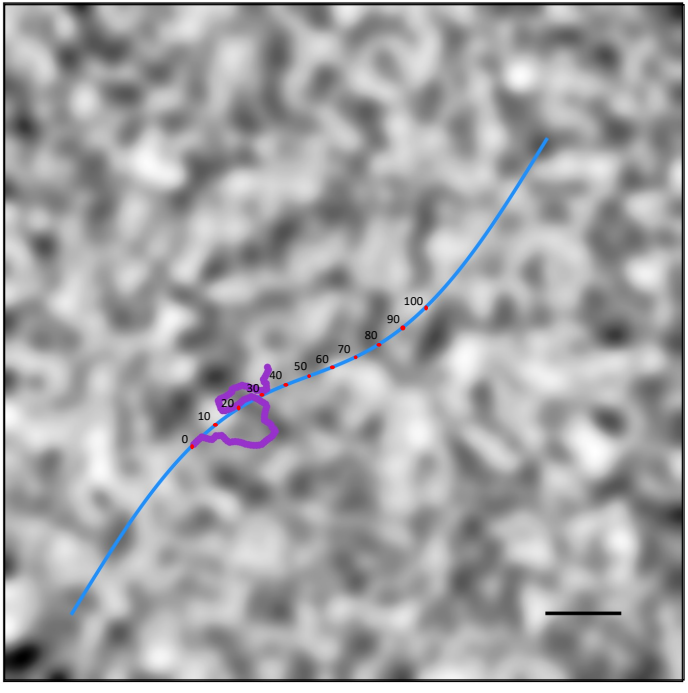
40%

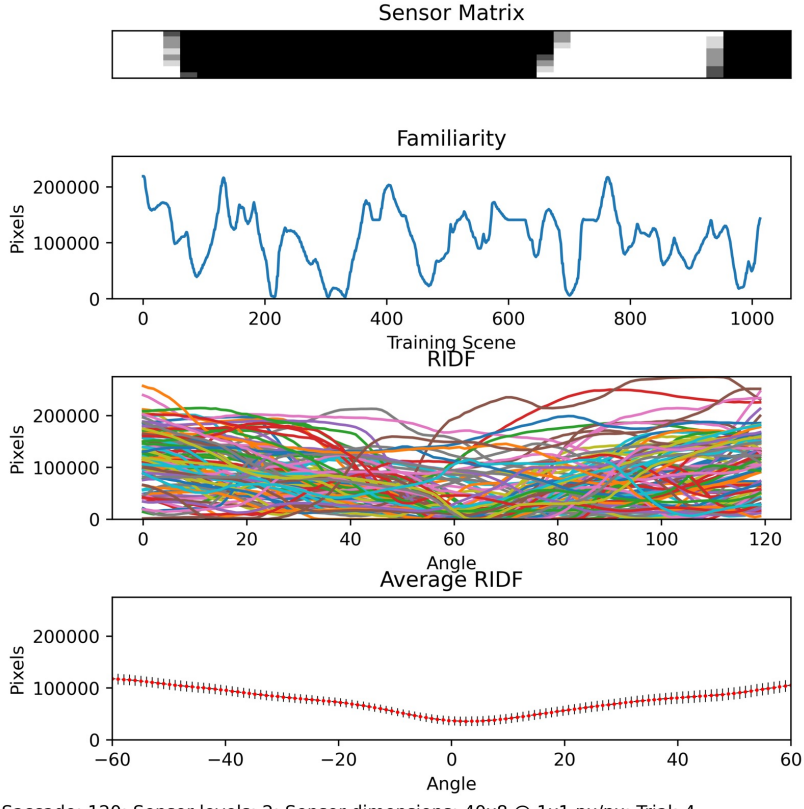




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 1174.50; RMSD/dist: 2.936; TD: 60075; p90: 40; p50: 22; complete: 0

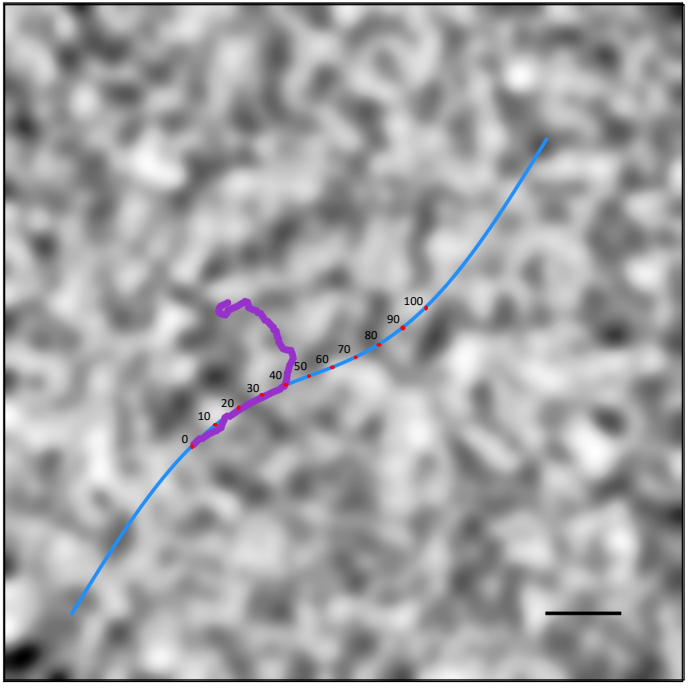
0%

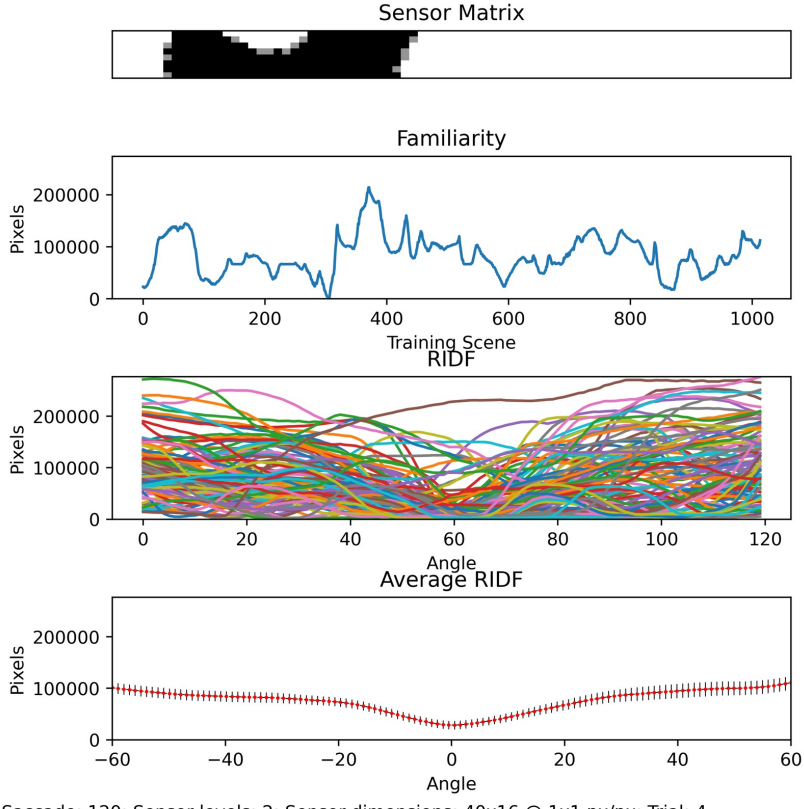




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 2434.87; RMSD/dist: 6.087; TD: 65600; p90: 80; p50: 36; complete: 0

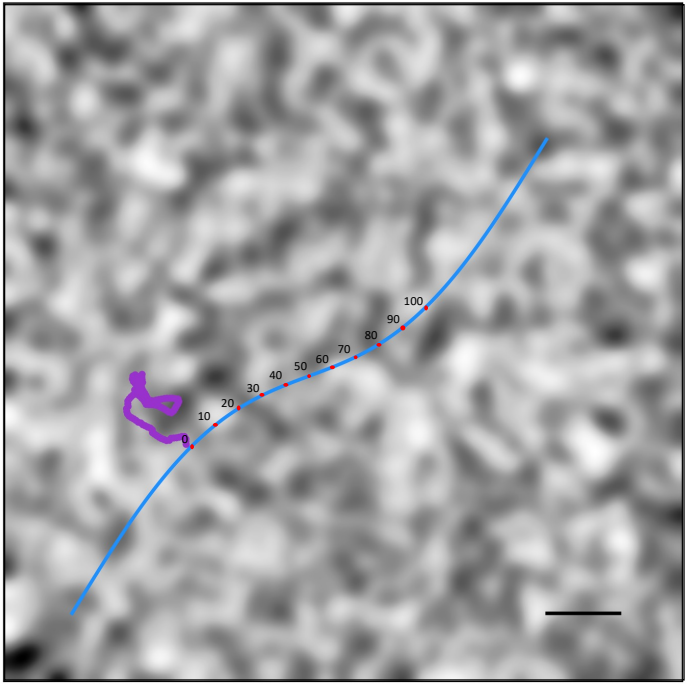
20%

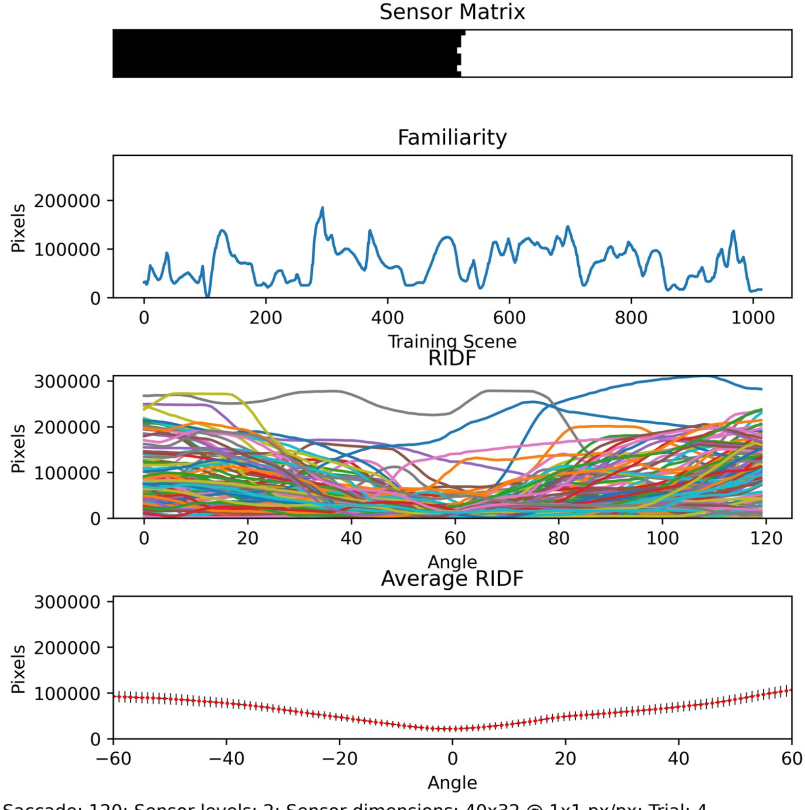




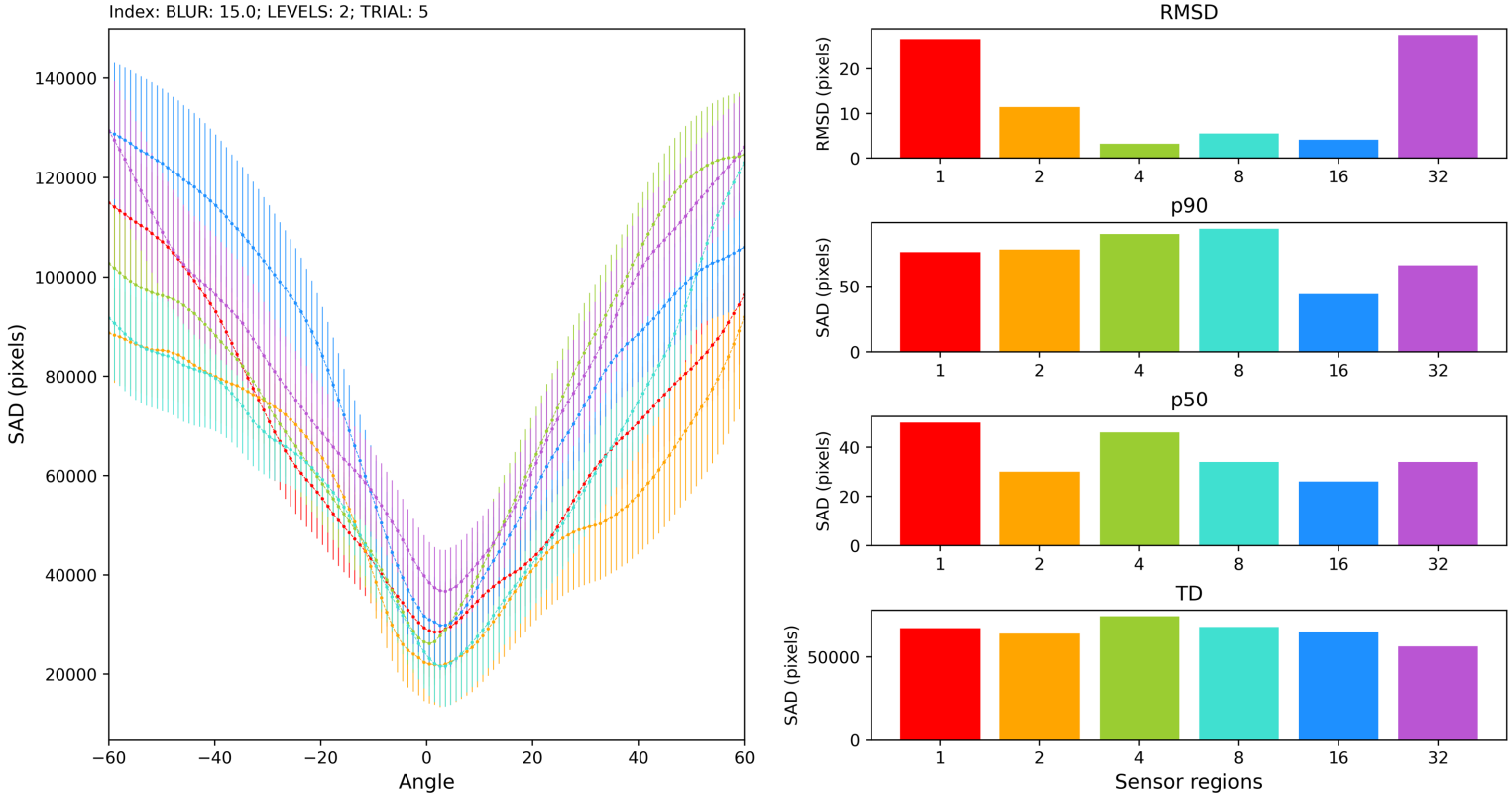
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 5269.65; RMSD/dist: 13.174; TD: 83823; p90: 120; p50: 36; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 8510.57; RMSD/dist: 21.276; TD: 90959; p90: 120; p50: 64; complete: 0


Index: BLUR: 15.0; LEVELS: 2; TRIAL: 5
SAD (pixels)
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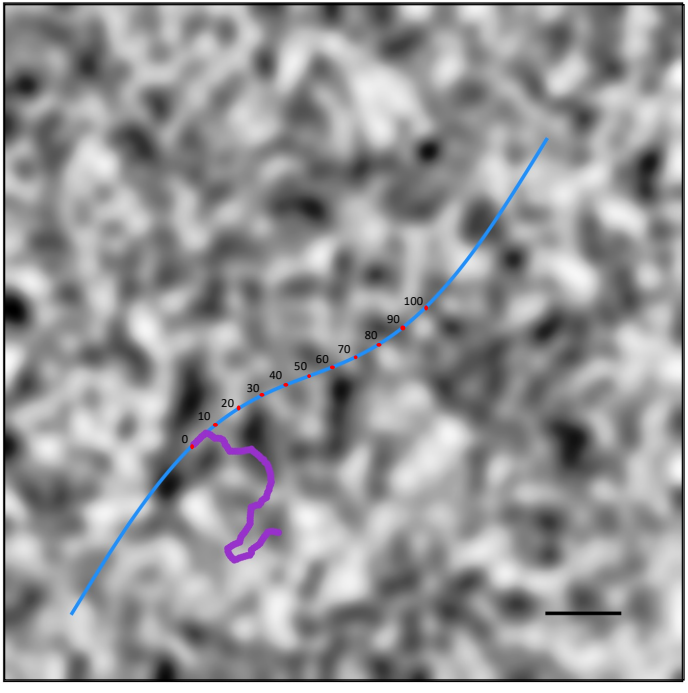
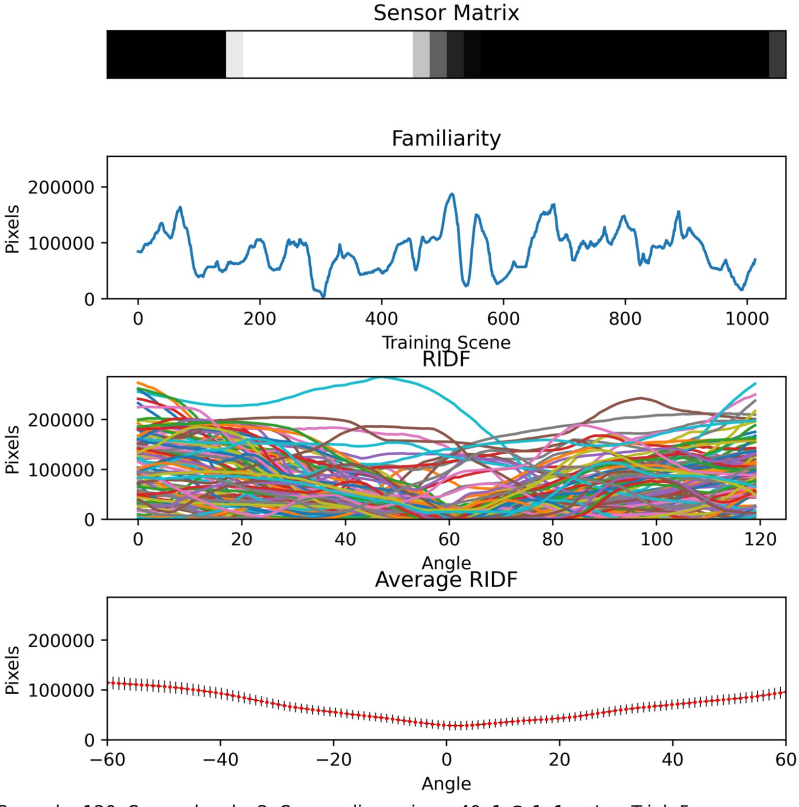
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
50
0
p50
SAD (pixels)
40
20
TD
SAD (pixels)
50000
Sensor regions

0%

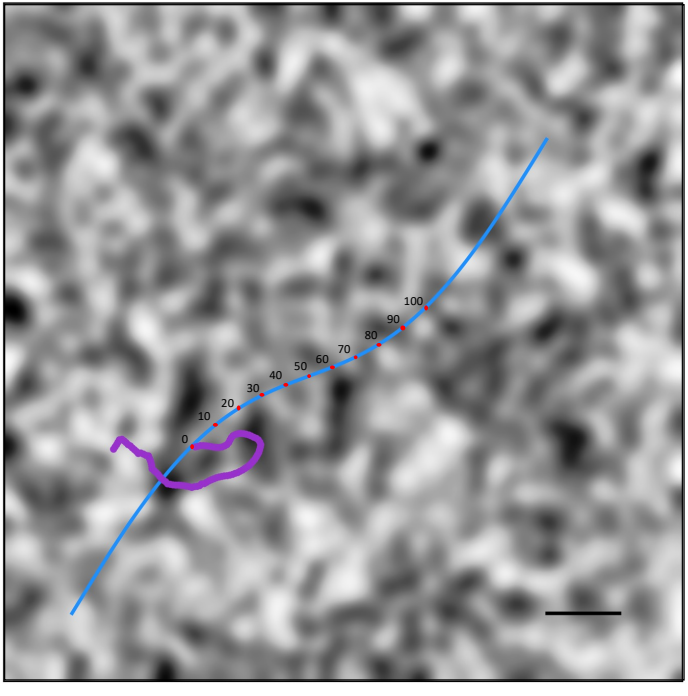


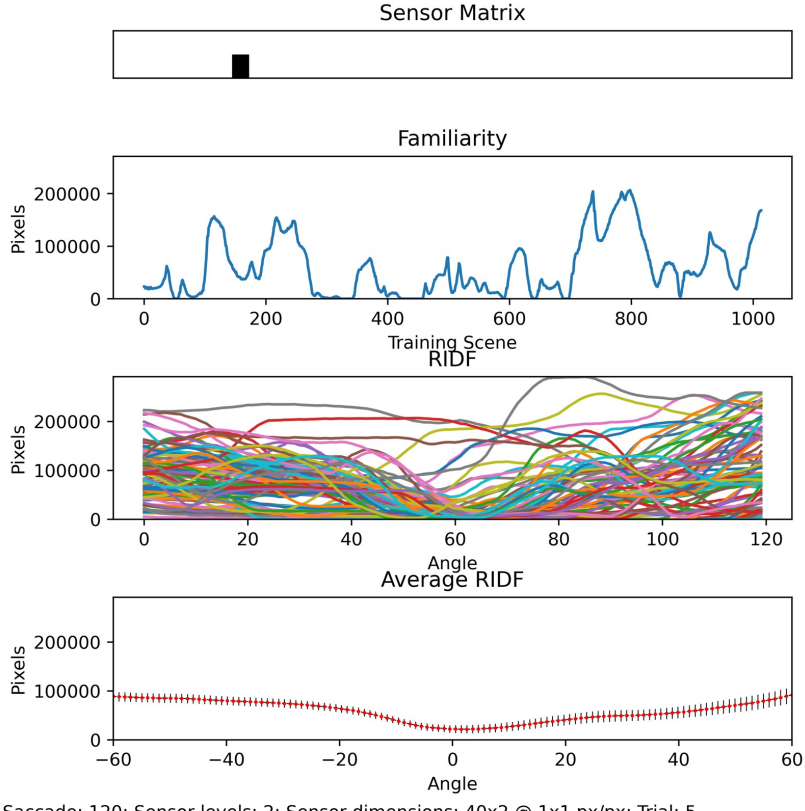


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 10678.07; RMSD/dist: 26.695; TD: 67554; p90: 76; p50: 50; complete: 0

0%

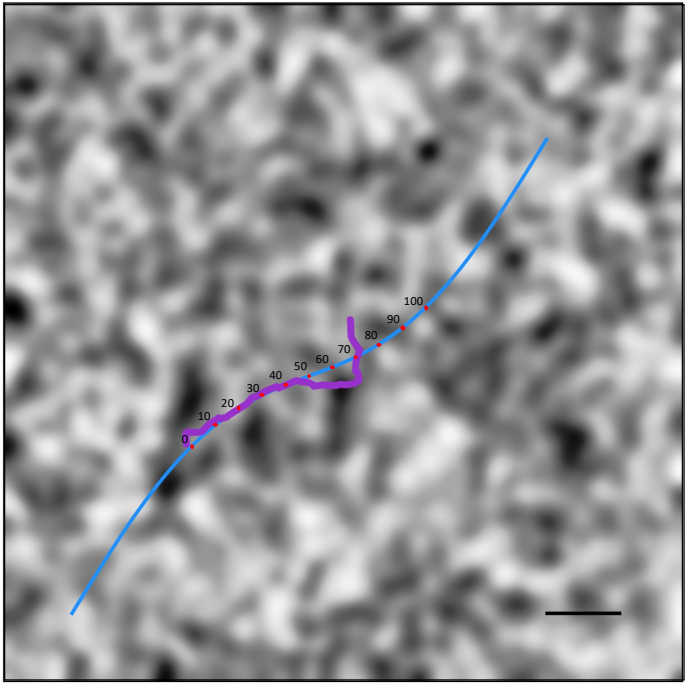


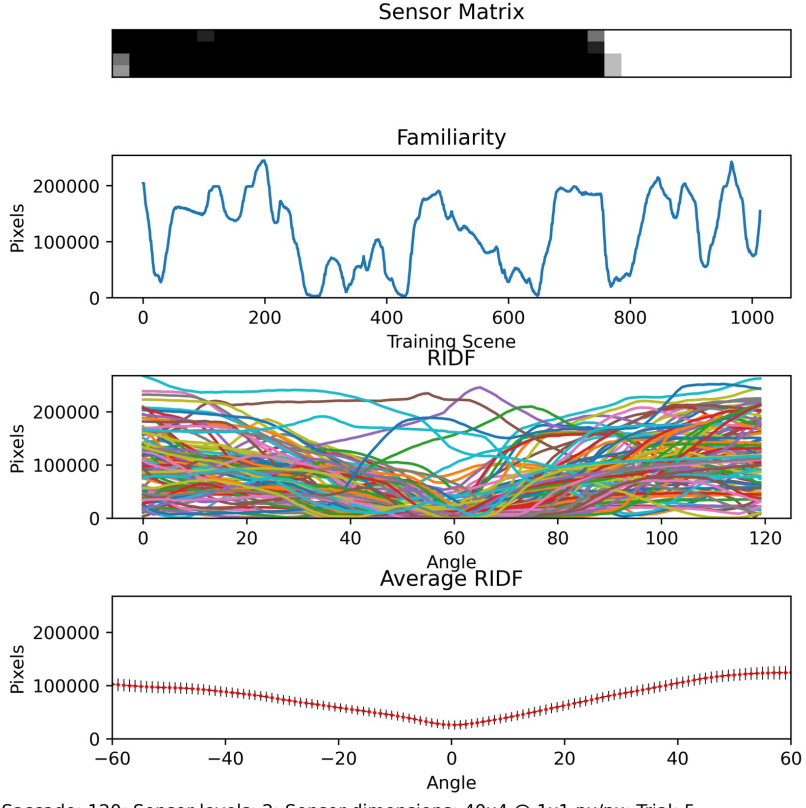


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 4568.75; RMSD/dist: 11.422; TD: 64150; p90: 78; p50: 30; complete: 0

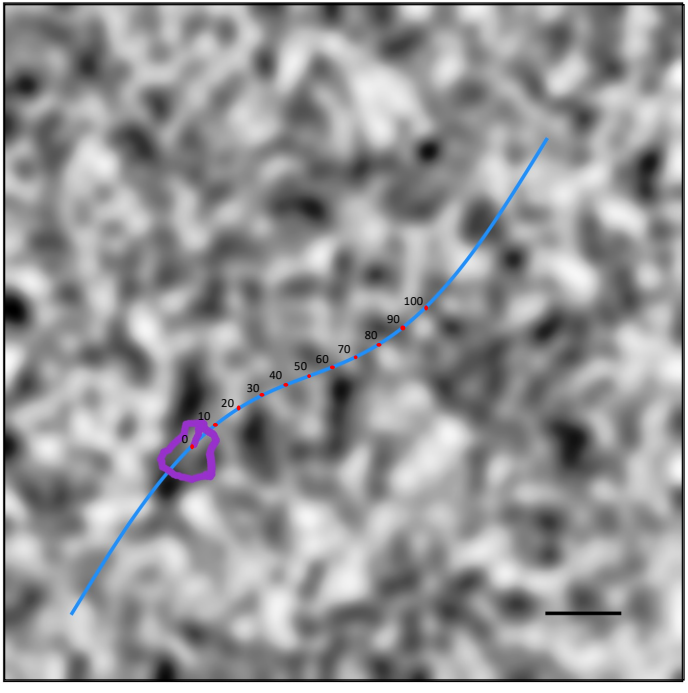
20%

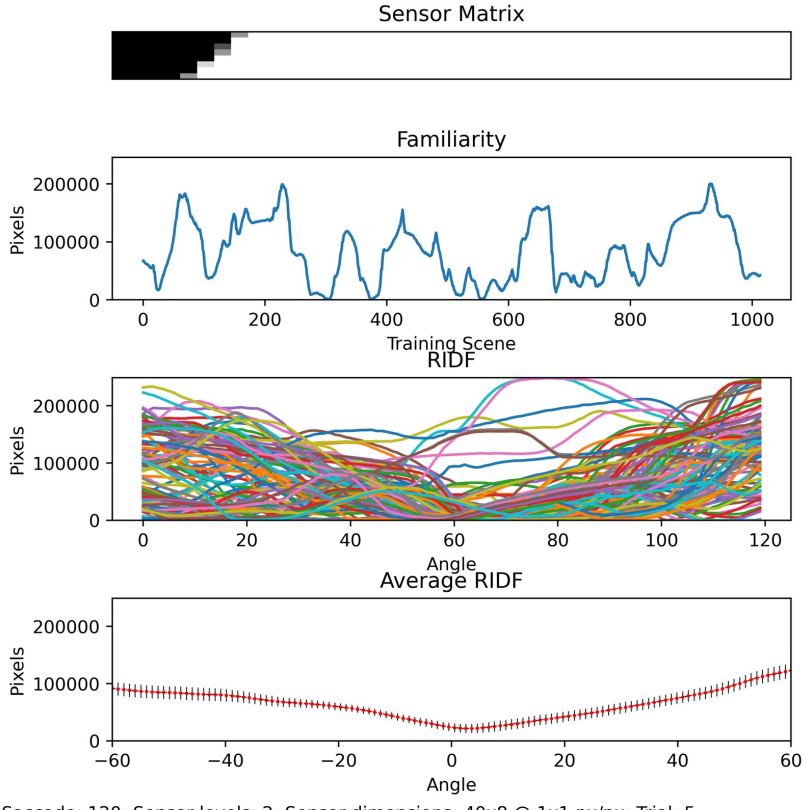




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 1289.18; RMSD/dist: 3.223; TD: 74707; p90: 90; p50: 46; complete: 0

0%

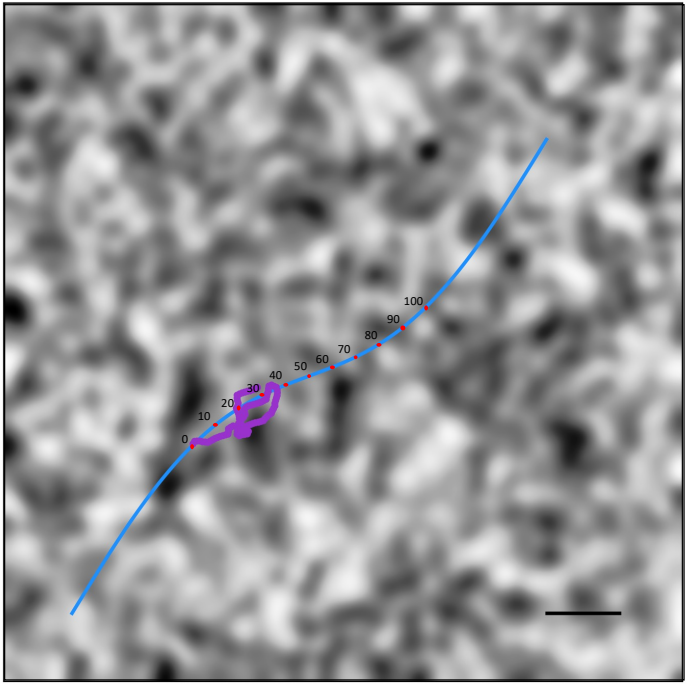


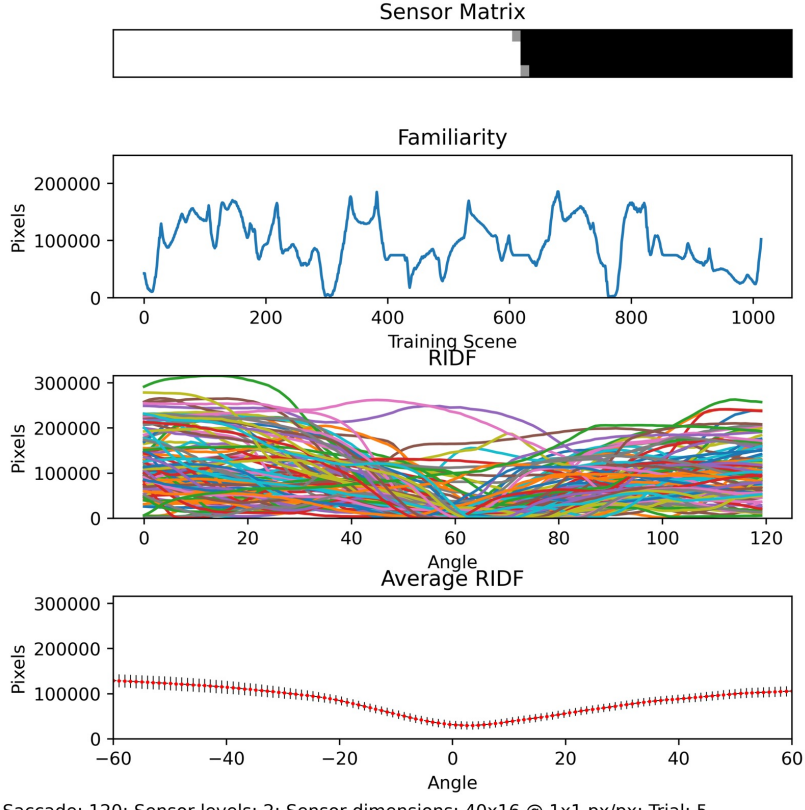


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2194.65; RMSD/dist: 5.487; TD: 68251; p90: 94; p50: 34; complete: 0

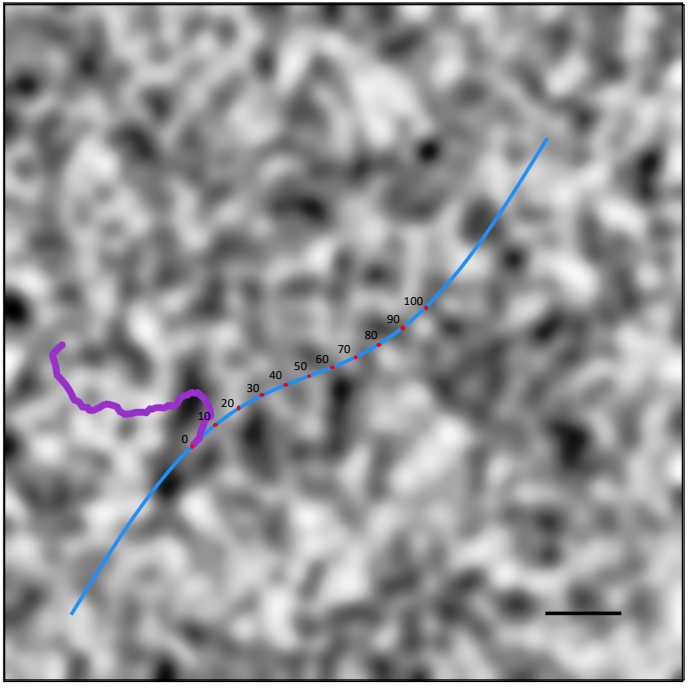
0%

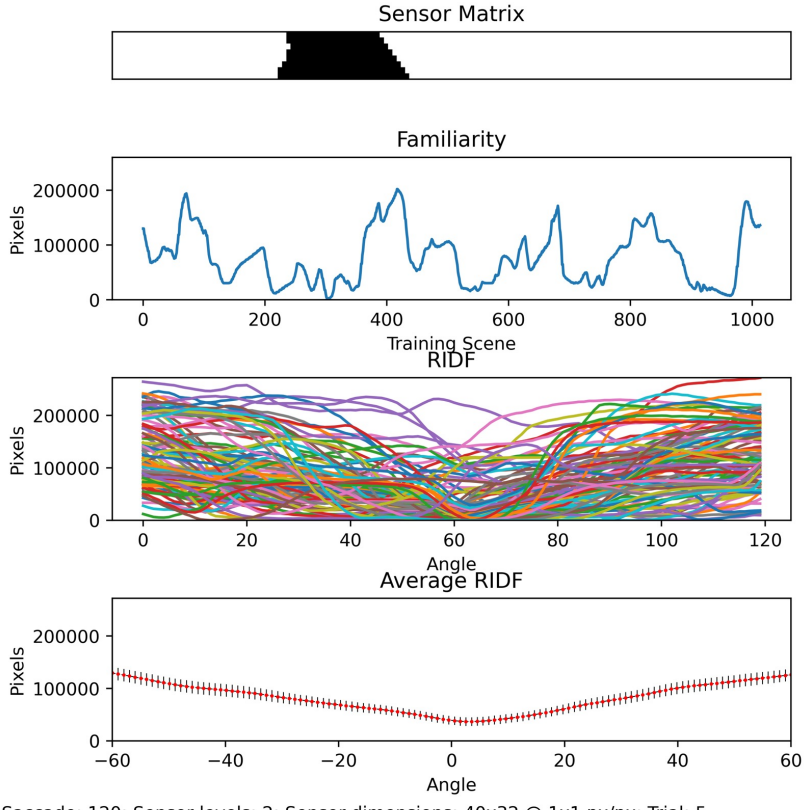




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 1634.75; RMSD/dist: 4.087; TD: 65325; p90: 44; p50: 26; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5
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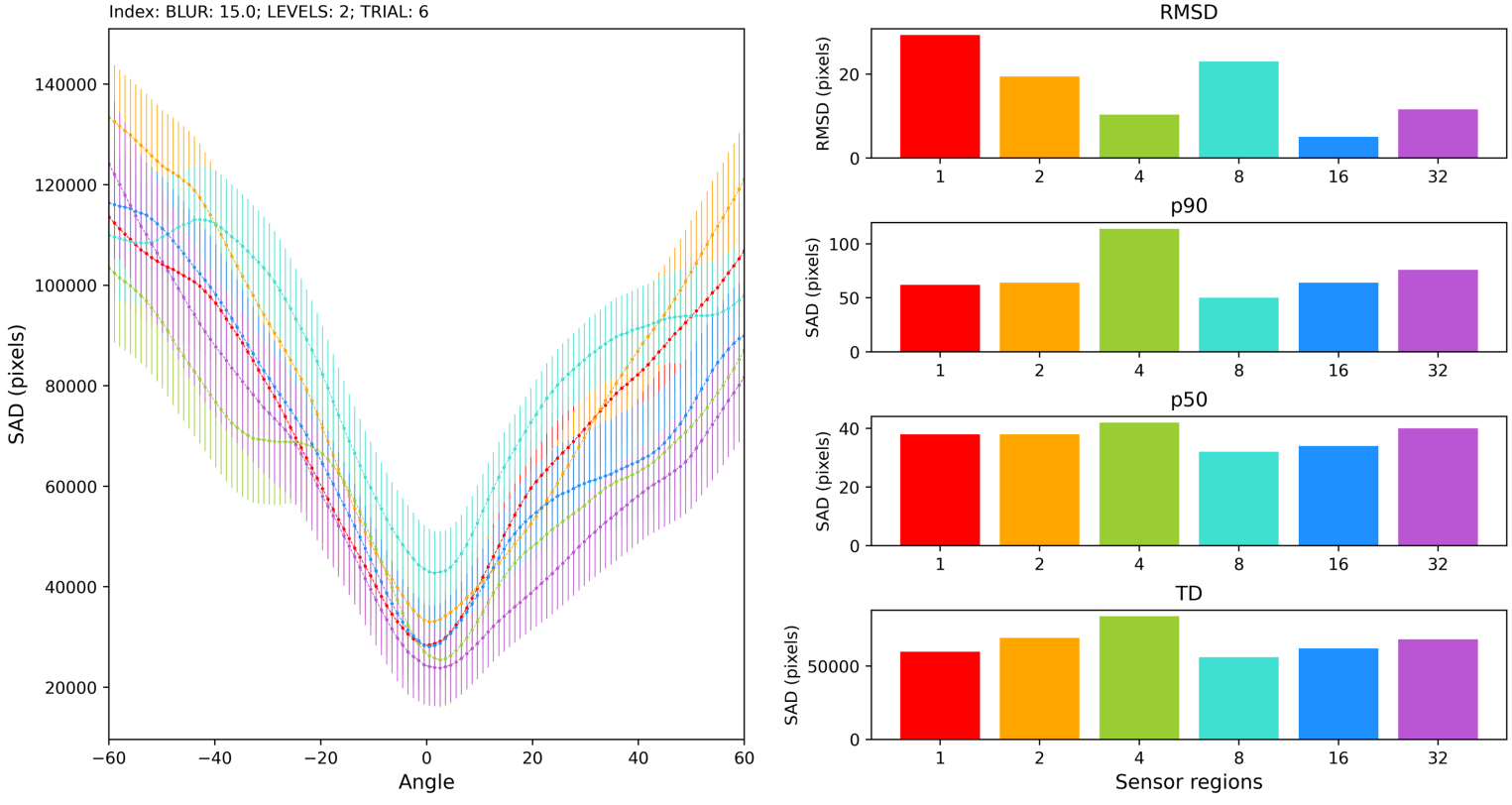
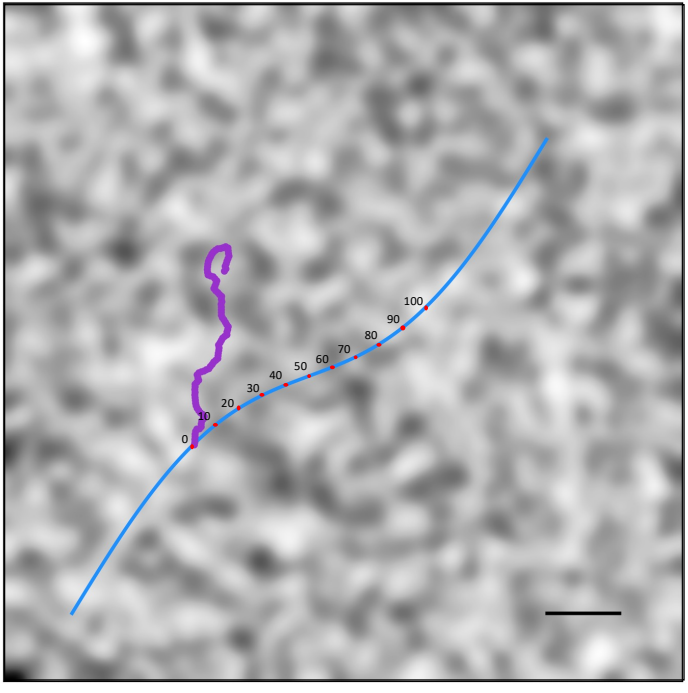
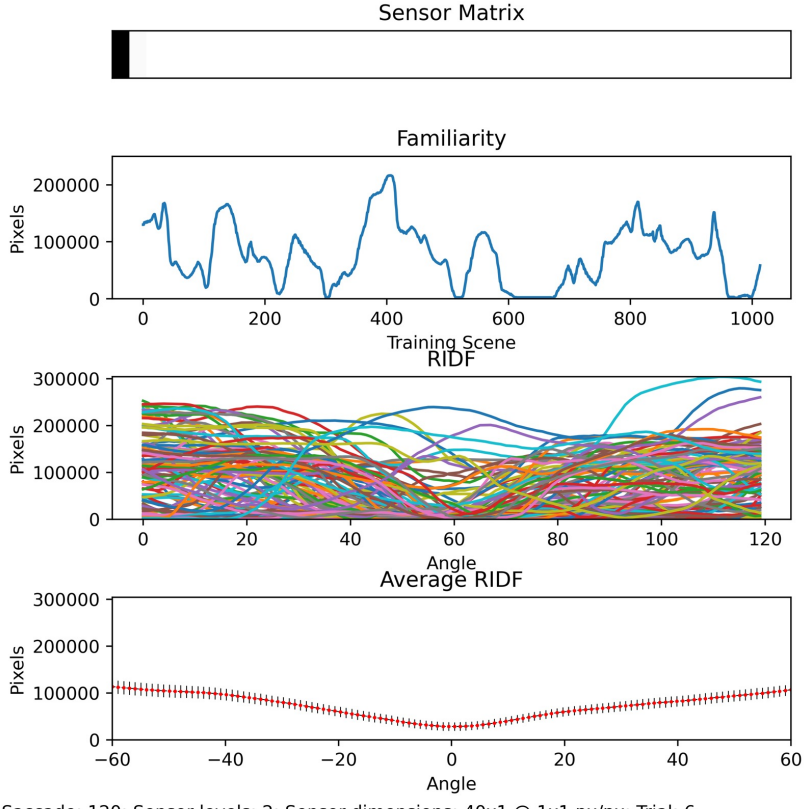

Index: BLUR: 15.0; LEVELS: 2; TRIAL: 6
SAD (pixels)
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
40
20
TD
50000
Sensor regions

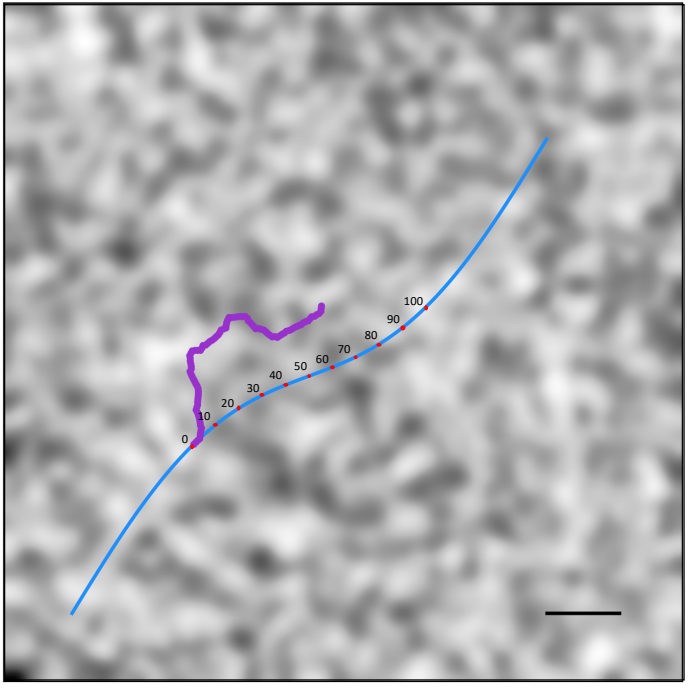
0%

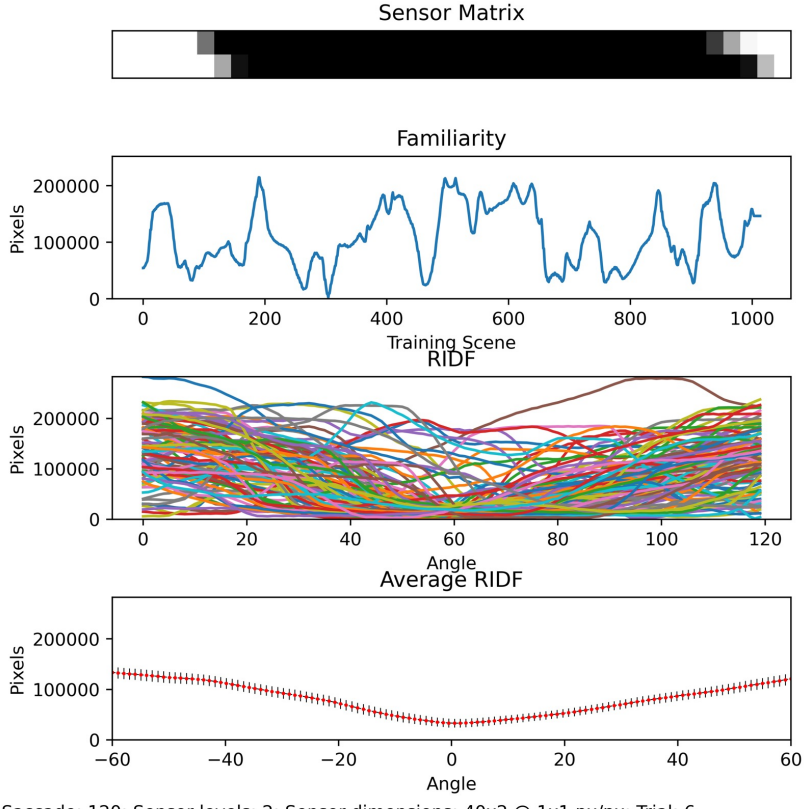




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 11740.05; RMSD/dist: 29.350; TD: 59699; p90: 62; p50: 38; complete: 0

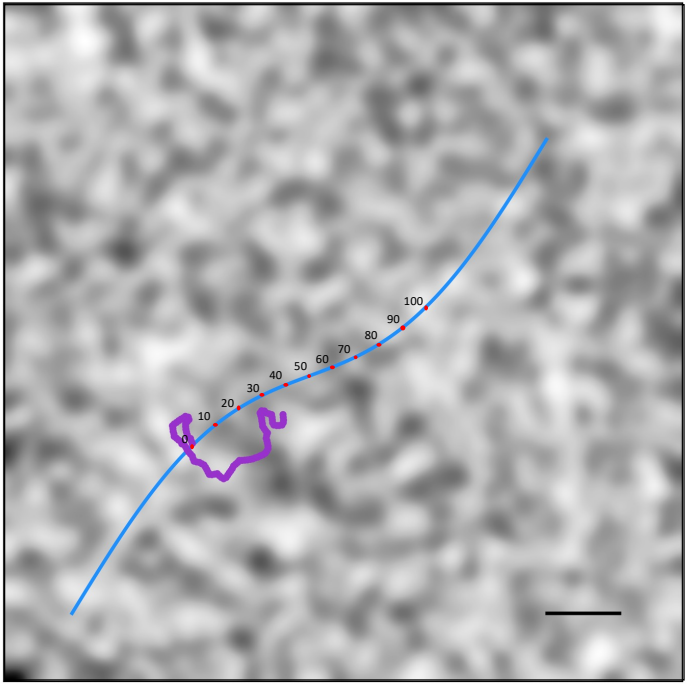
0%

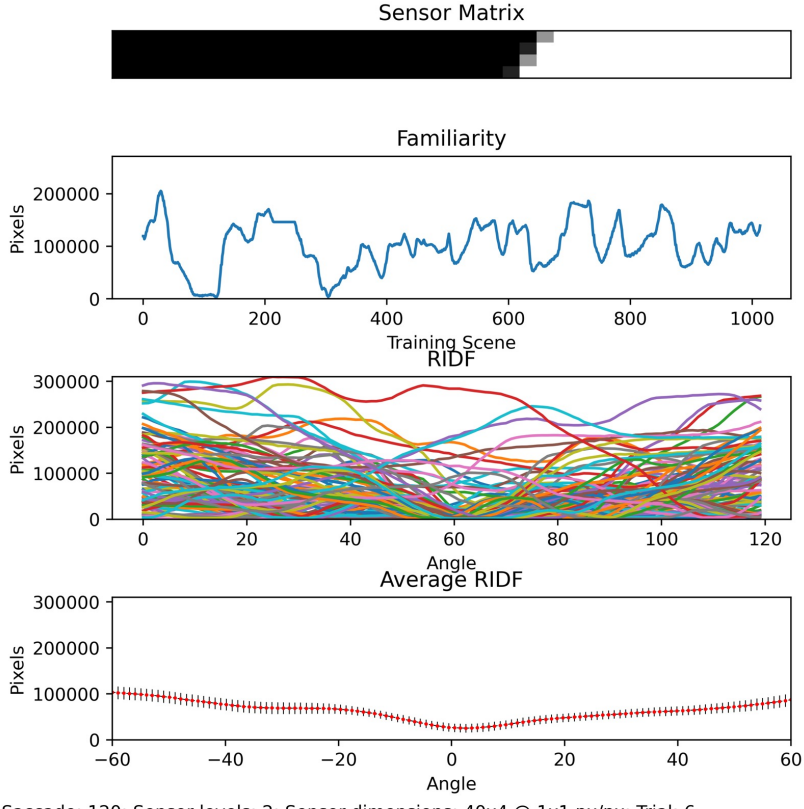




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 7783.76; RMSD/dist: 19.459; TD: 69165; p90: 64; p50: 38; complete: 0

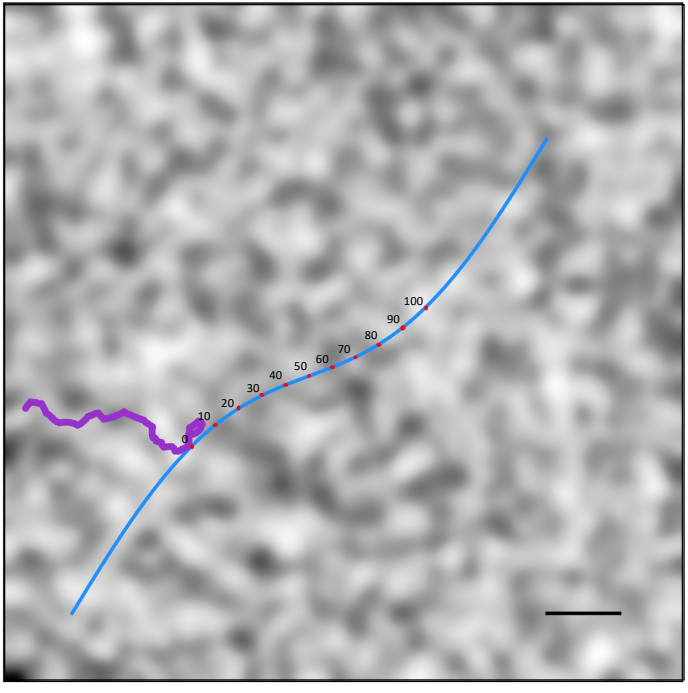
0%

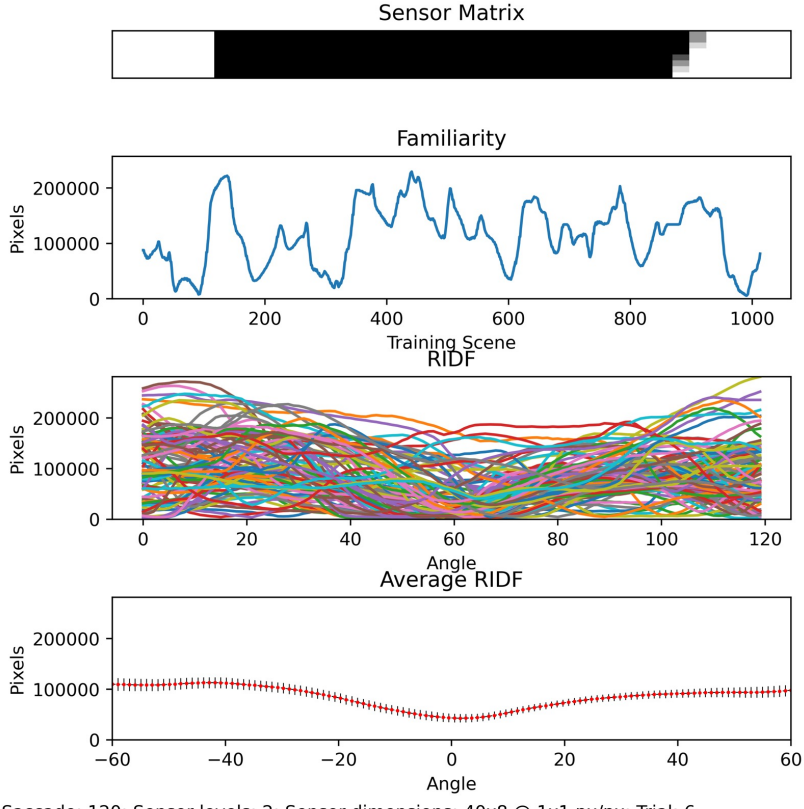




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 4147.19; RMSD/dist: 10.368; TD: 83818; p90: 114; p50: 42; complete: 0

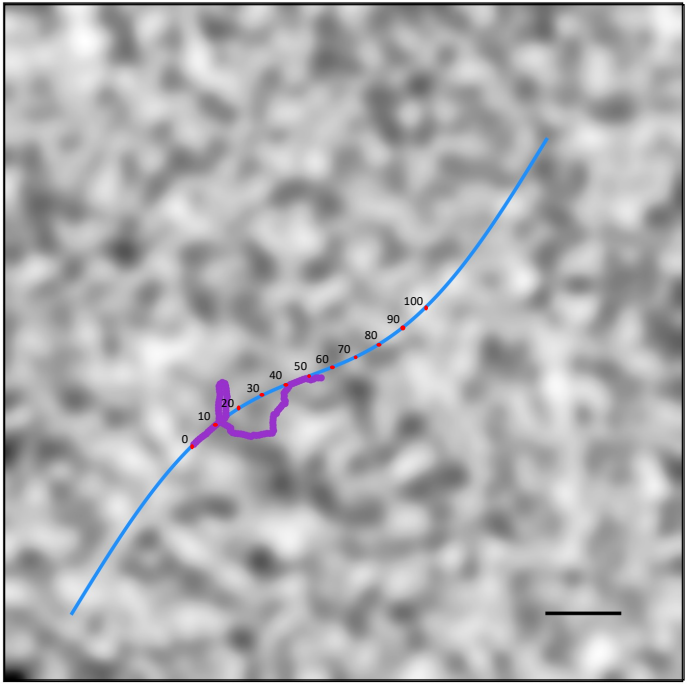
0%

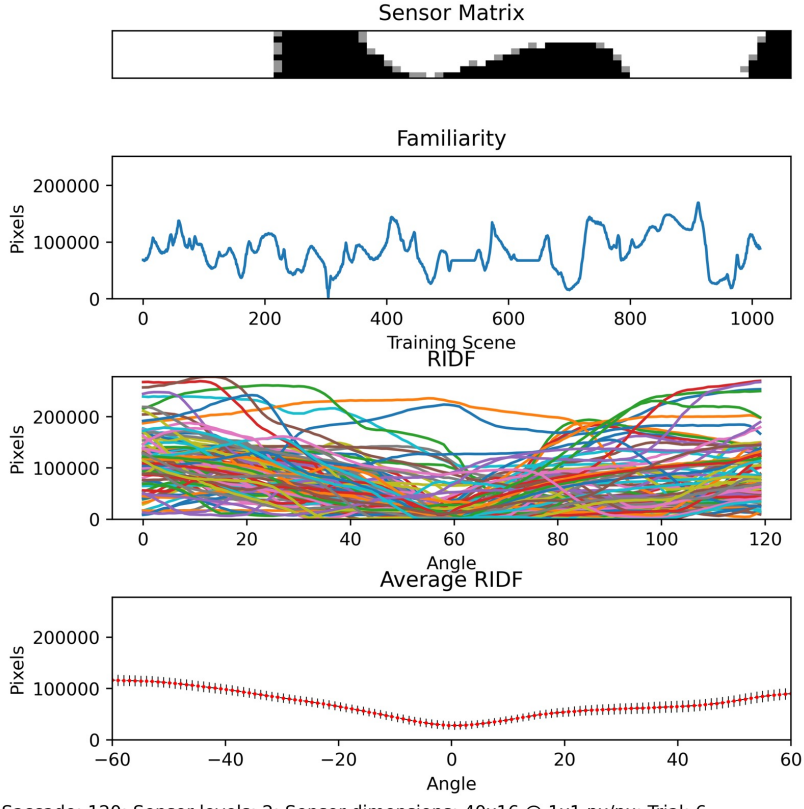




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 9197.39; RMSD/dist: 22.993; TD: 56042; p90: 50; p50: 32; complete: 0

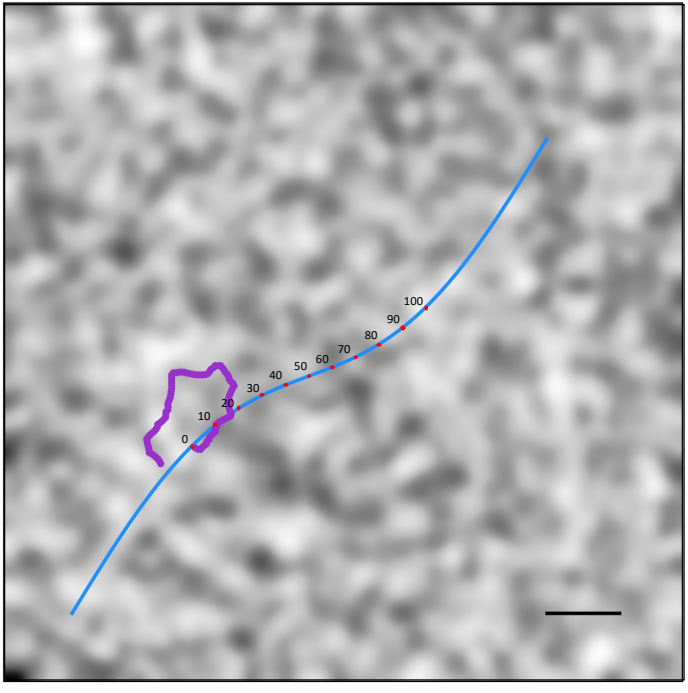
10%

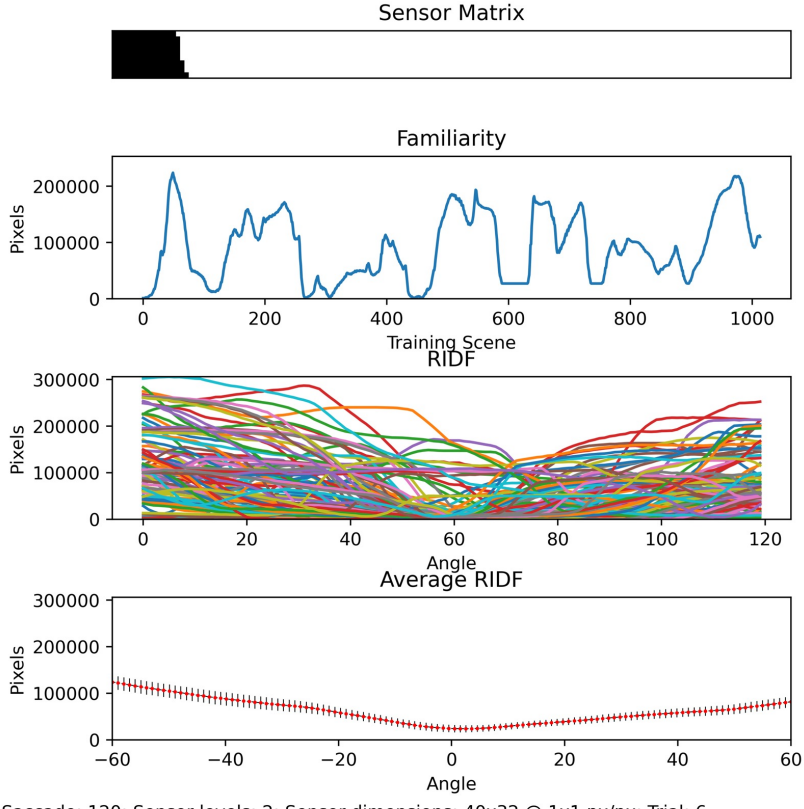




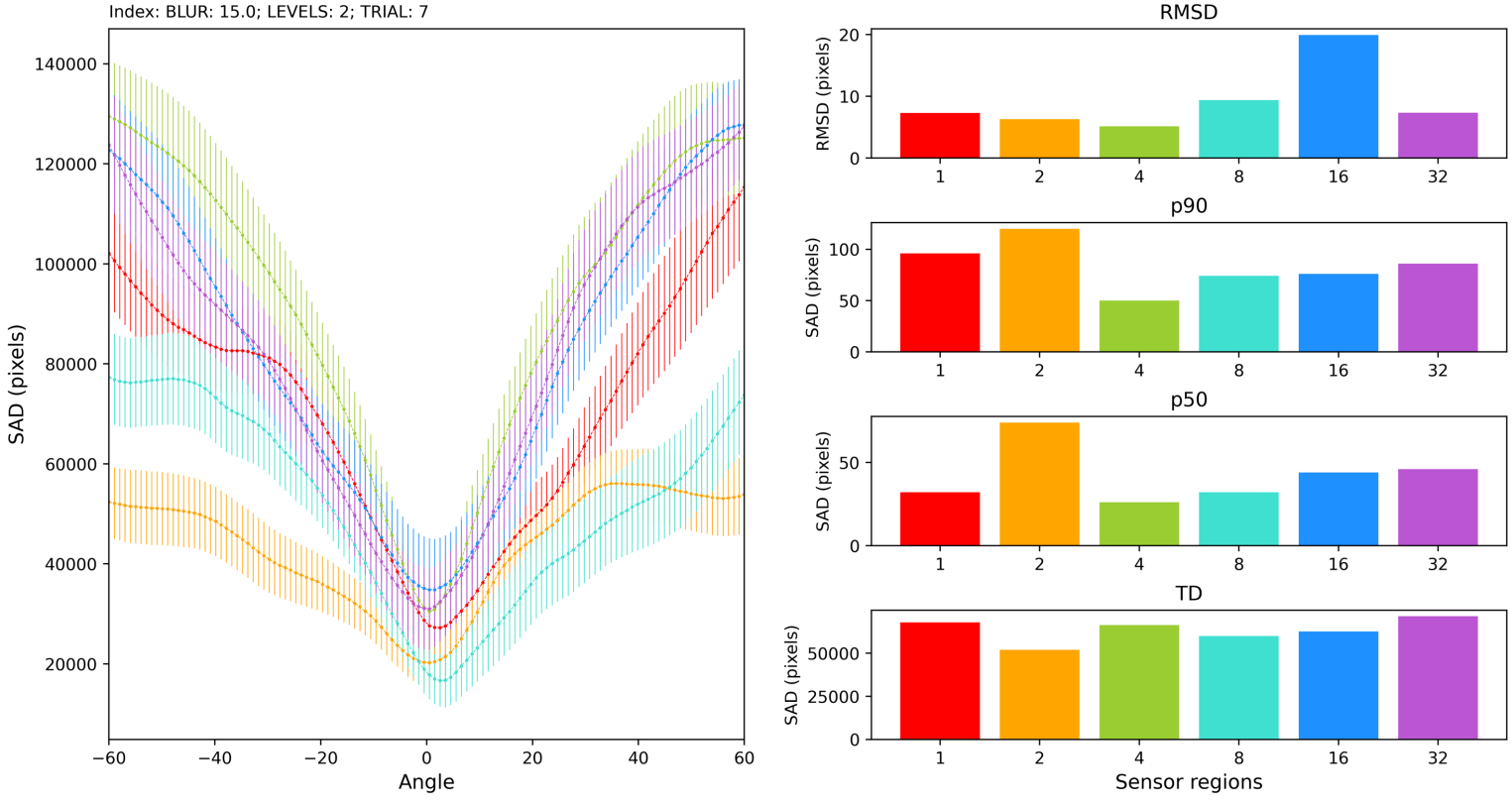
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 2031.68; RMSD/dist: 5.079; TD: 62011; p90: 64; p50: 34; complete: 0

0%

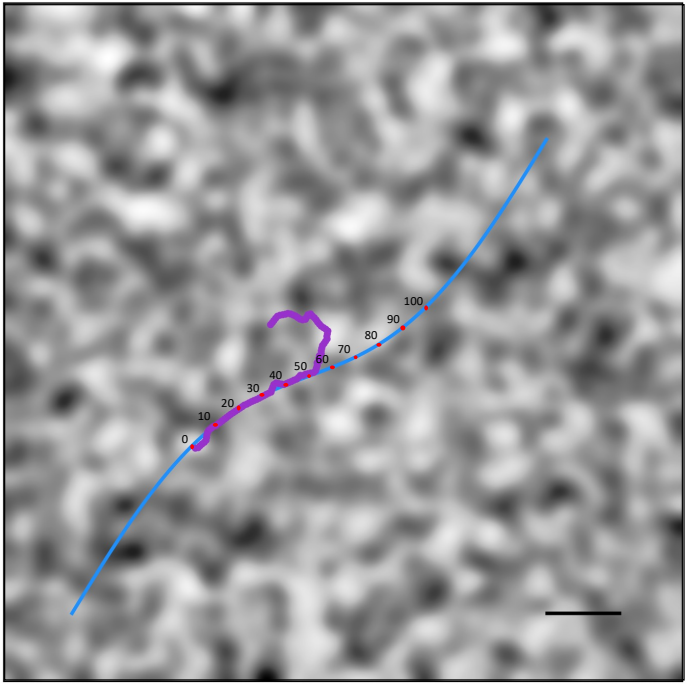


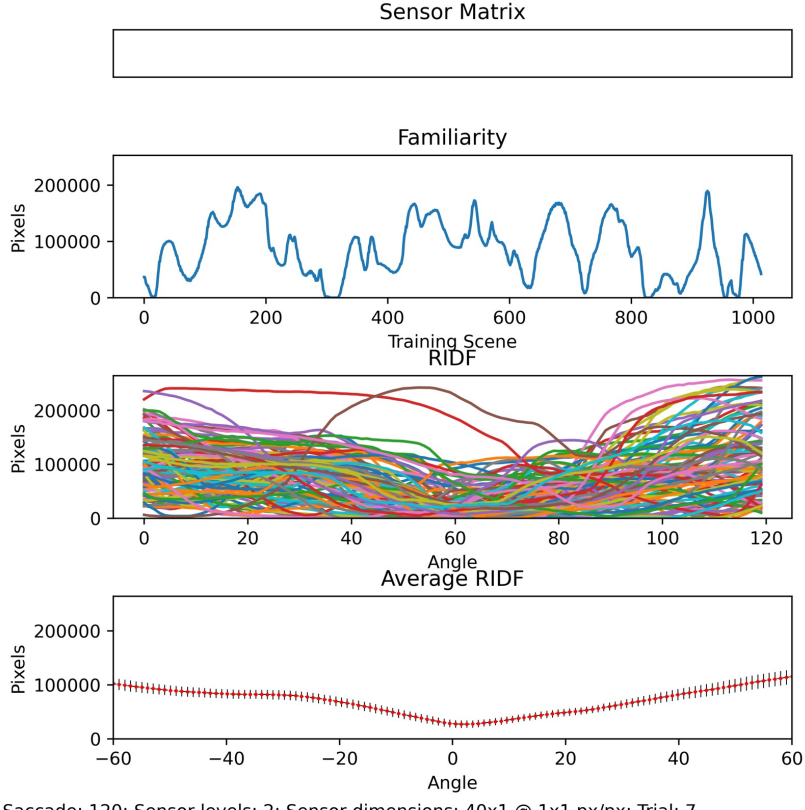


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 4630.82; RMSD/dist: 11.577; TD: 68110; p90: 76; p50: 40; complete: 0


Index: BLUR: 15.0; LEVELS: 2; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

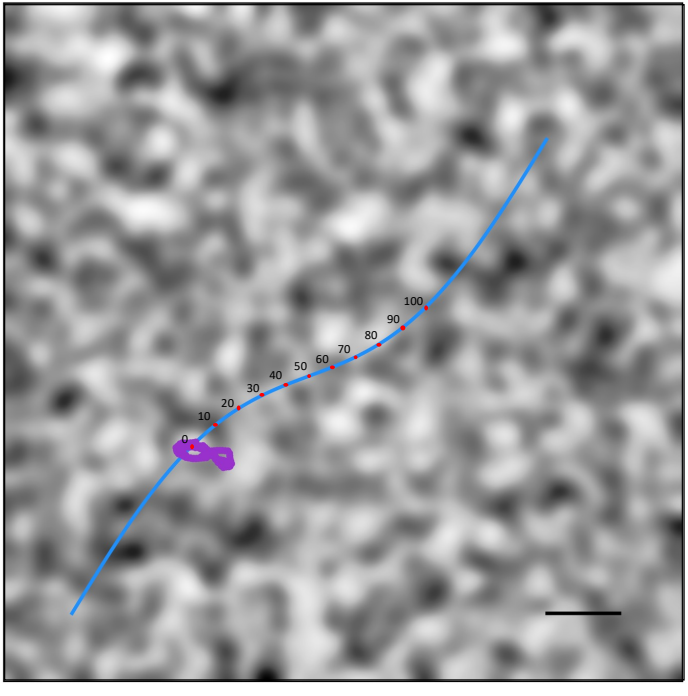
30%

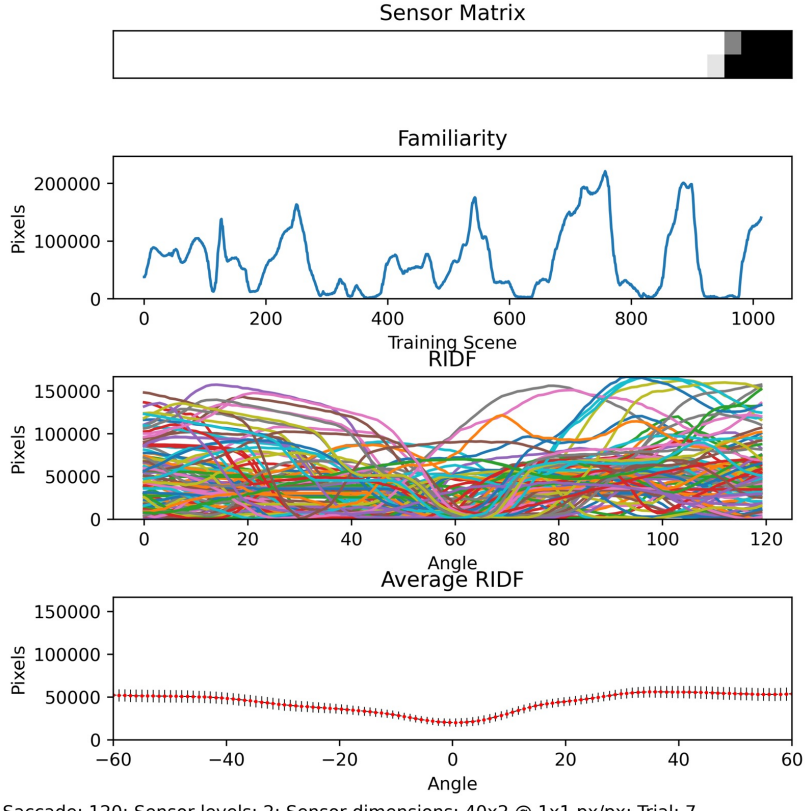




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 2911.76; RMSD/dist: 7.279; TD: 67859; p90: 96; p50: 32; complete: 0

0%

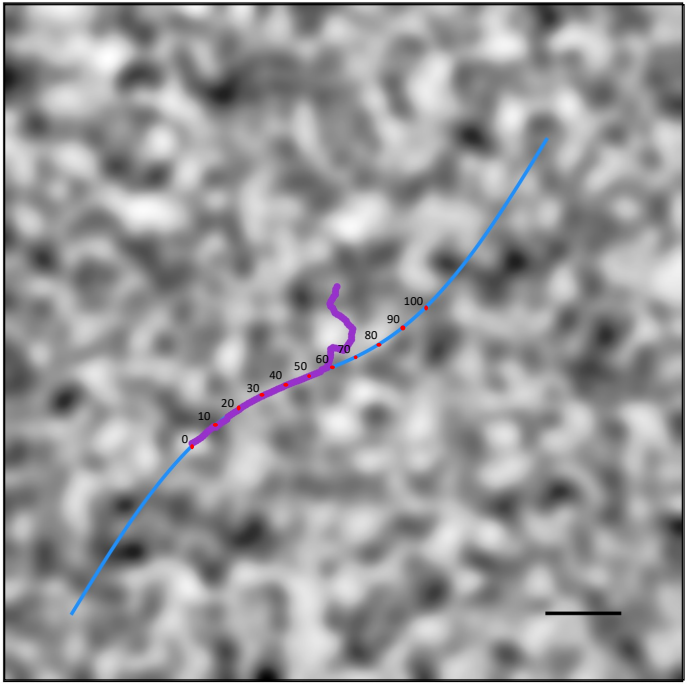


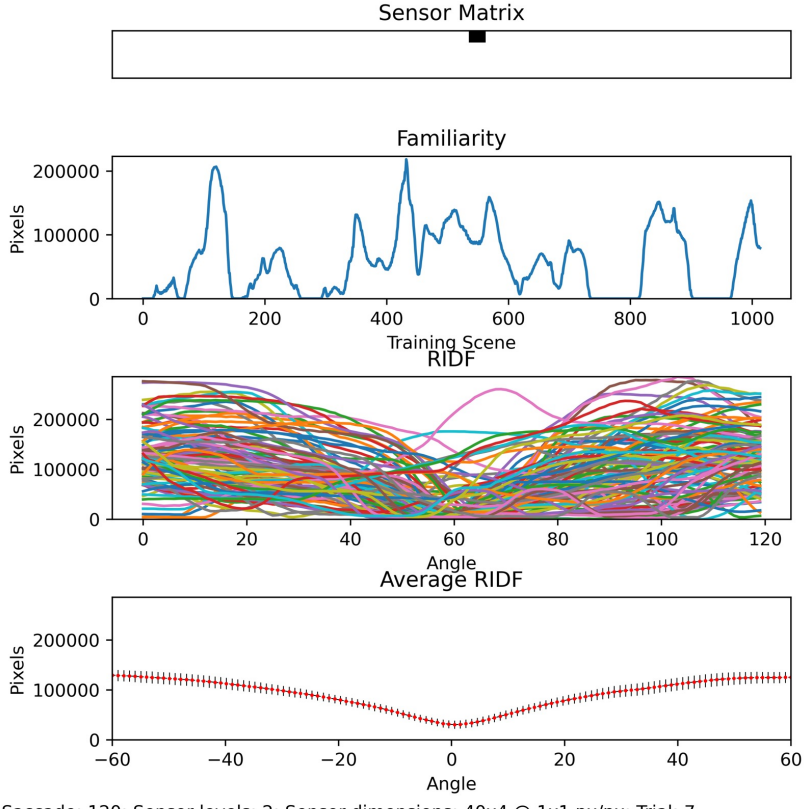


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2516.84; RMSD/dist: 6.292; TD: 51953; p90: 120; p50: 74; complete: 0

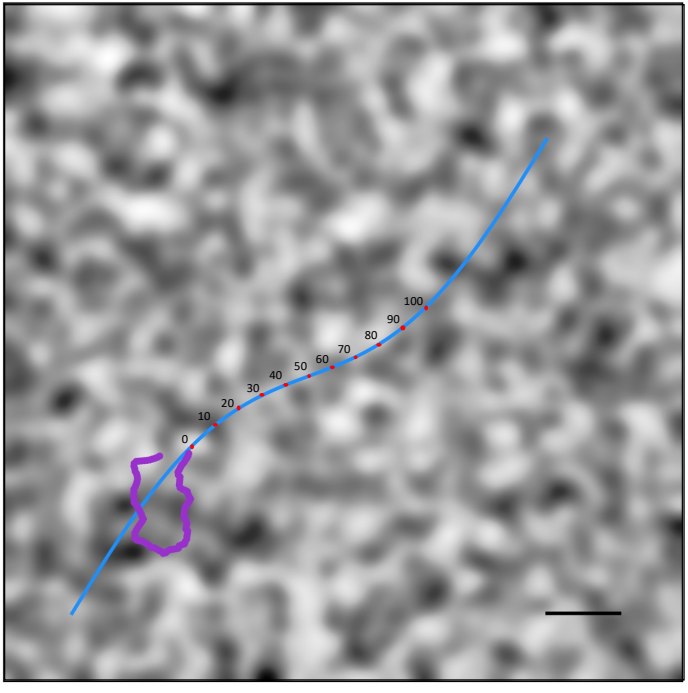
50%

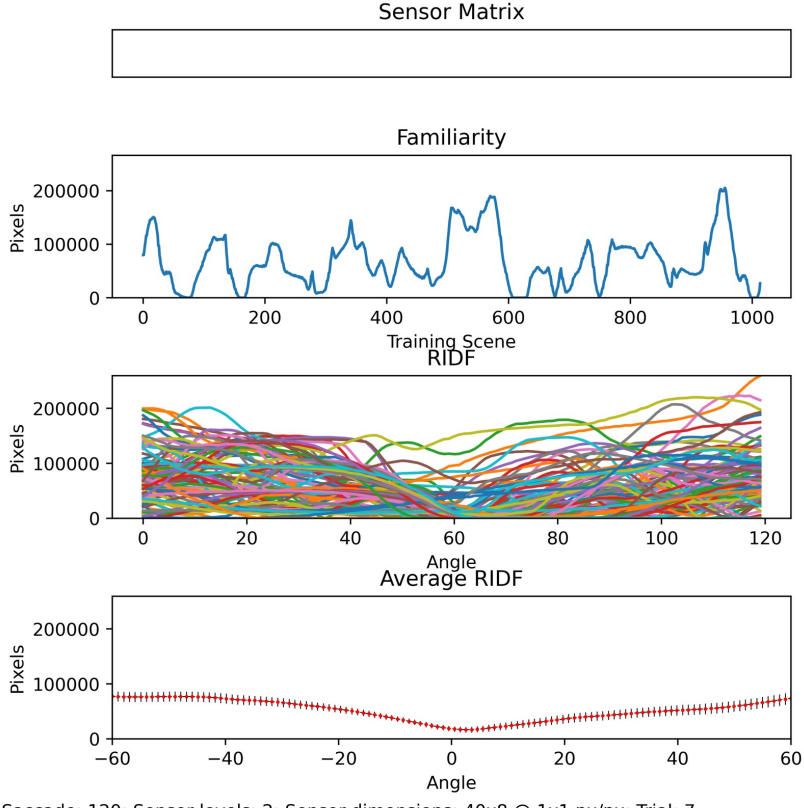




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 2050.45; RMSD/dist: 5.126; TD: 66256; p90: 50; p50: 26; complete: 0

0%

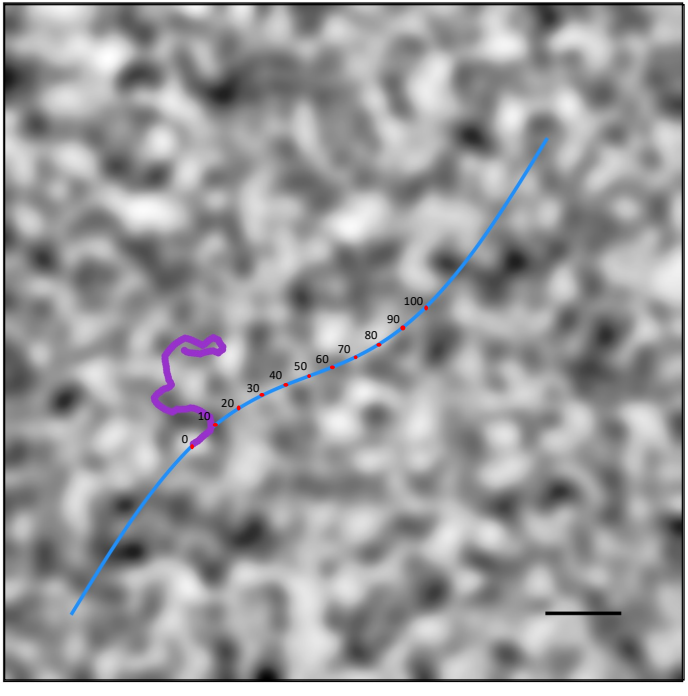


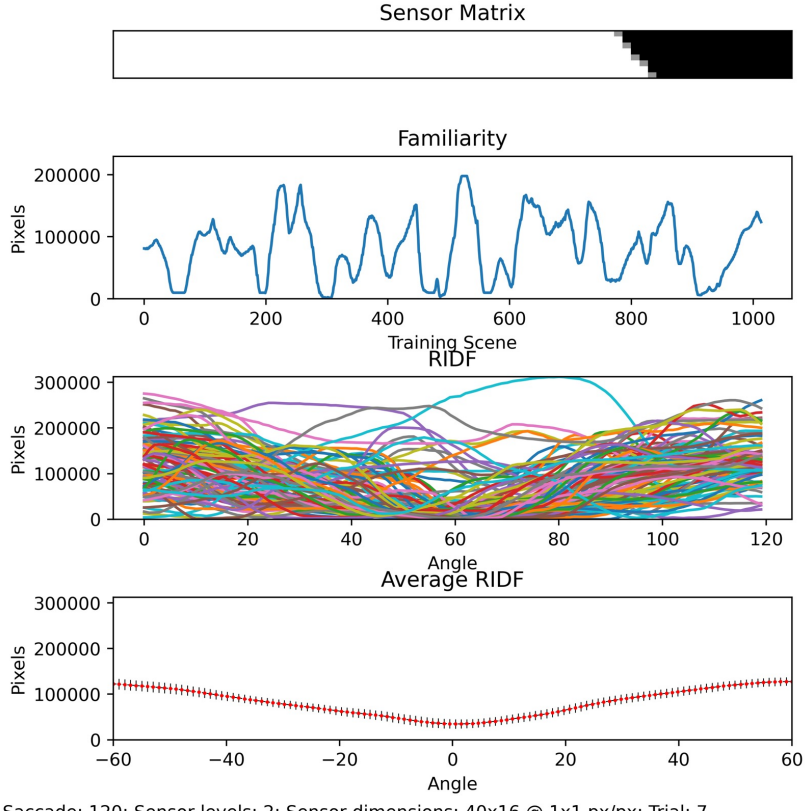


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3744.44; RMSD/dist: 9.361; TD: 59970; p90: 74; p50: 32; complete: 0

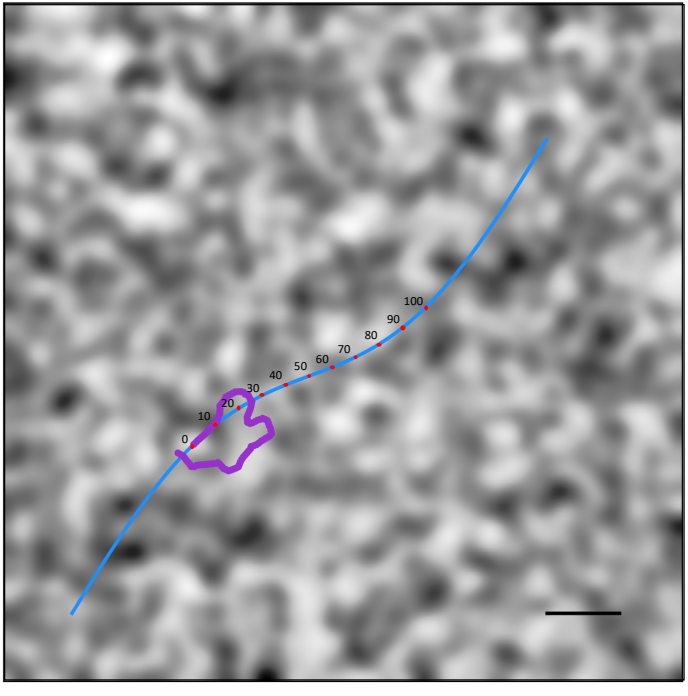
10%

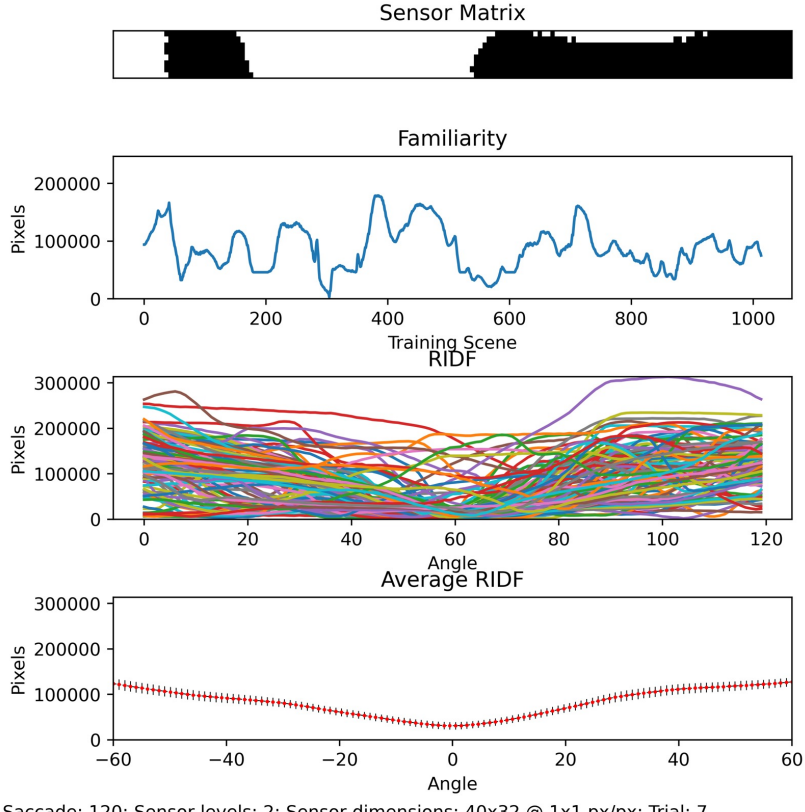




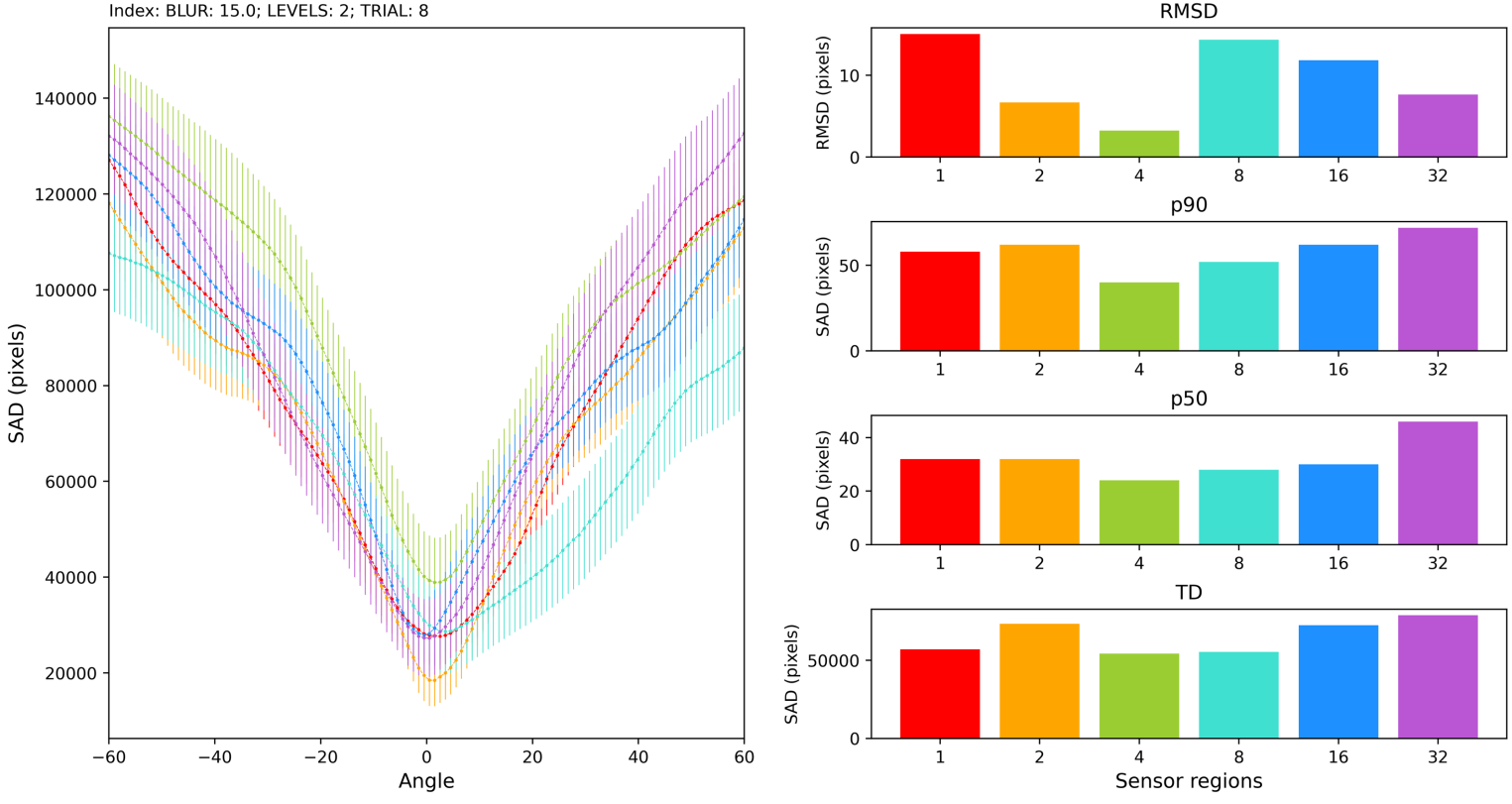
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 7969.44; RMSD/dist: 19.924; TD: 62560; p90: 76; p50: 44; complete: 0

10%

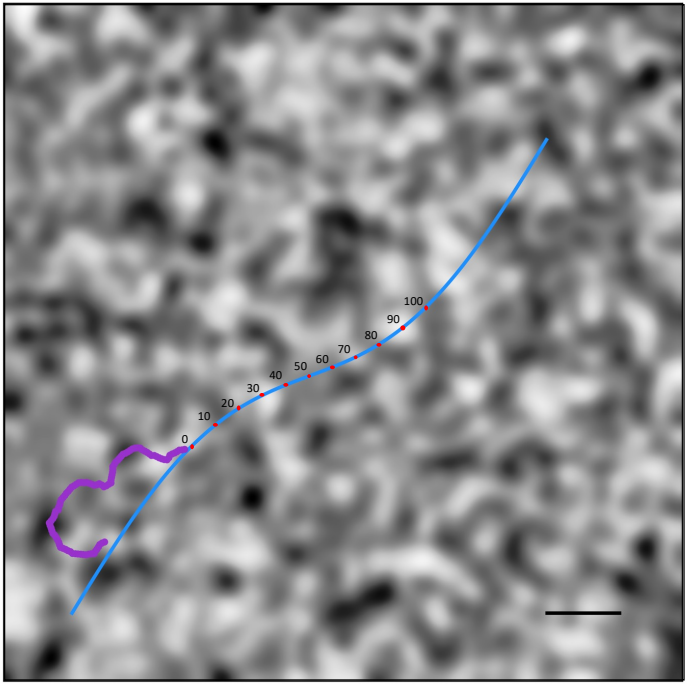


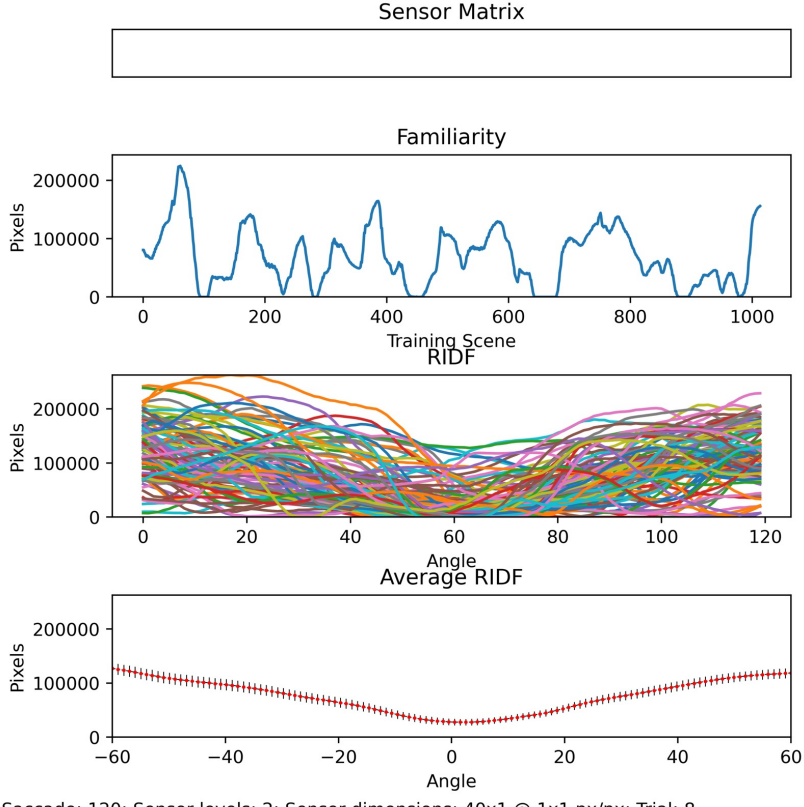


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 2933.17; RMSD/dist: 7.333; TD: 71371; p90: 86; p50: 46; complete: 0


Index: BLUR: 15.0; LEVELS: 2; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

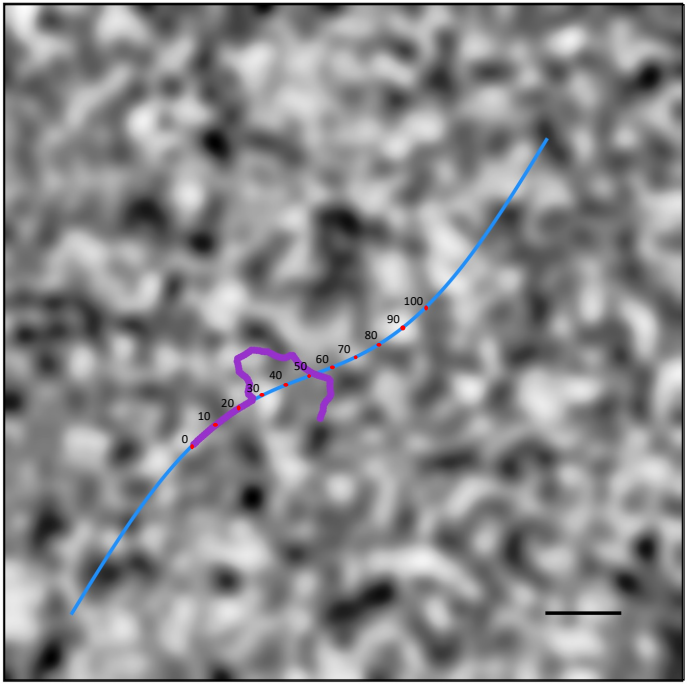
0%

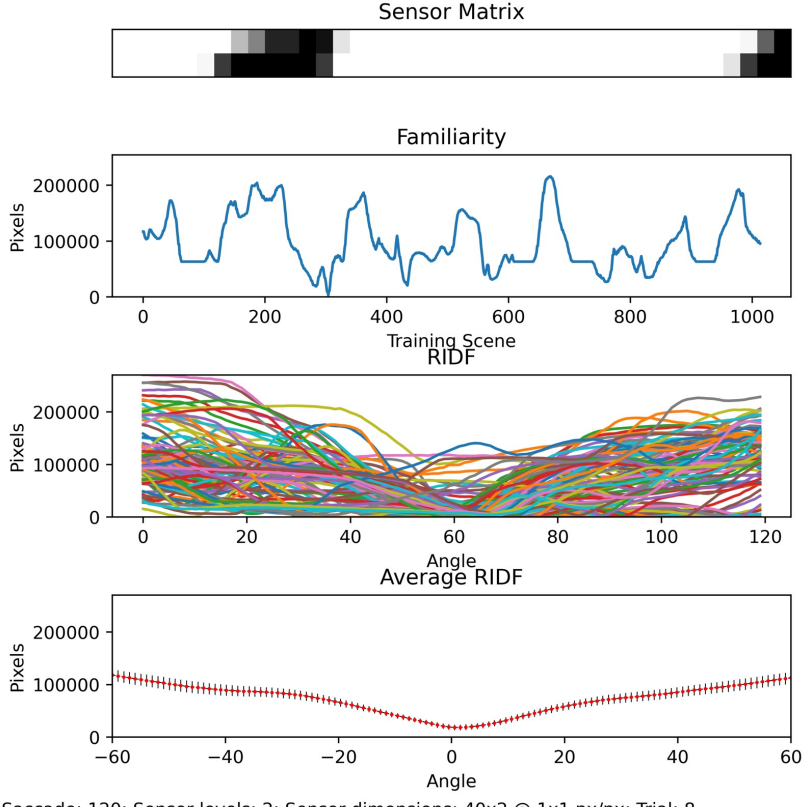




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 6025.83; RMSD/dist: 15.065; TD: 57103; p90: 58; p50: 32; complete: 0

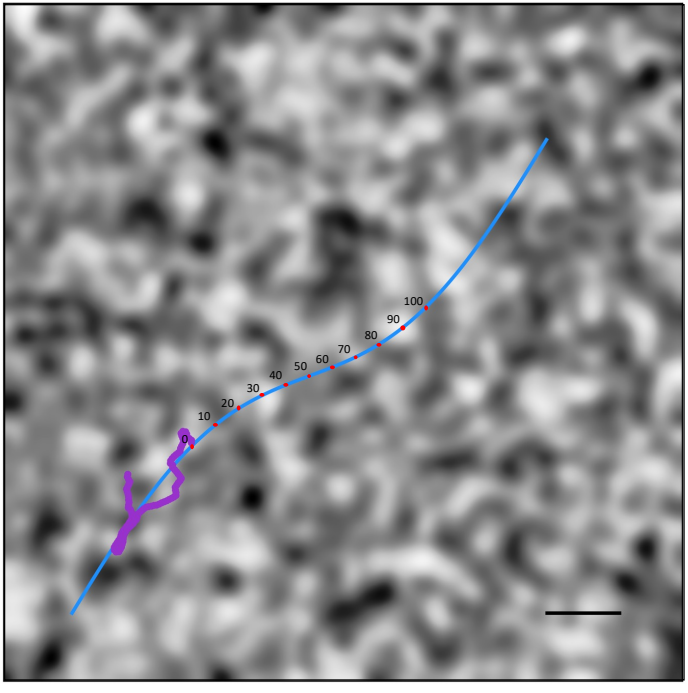
20%

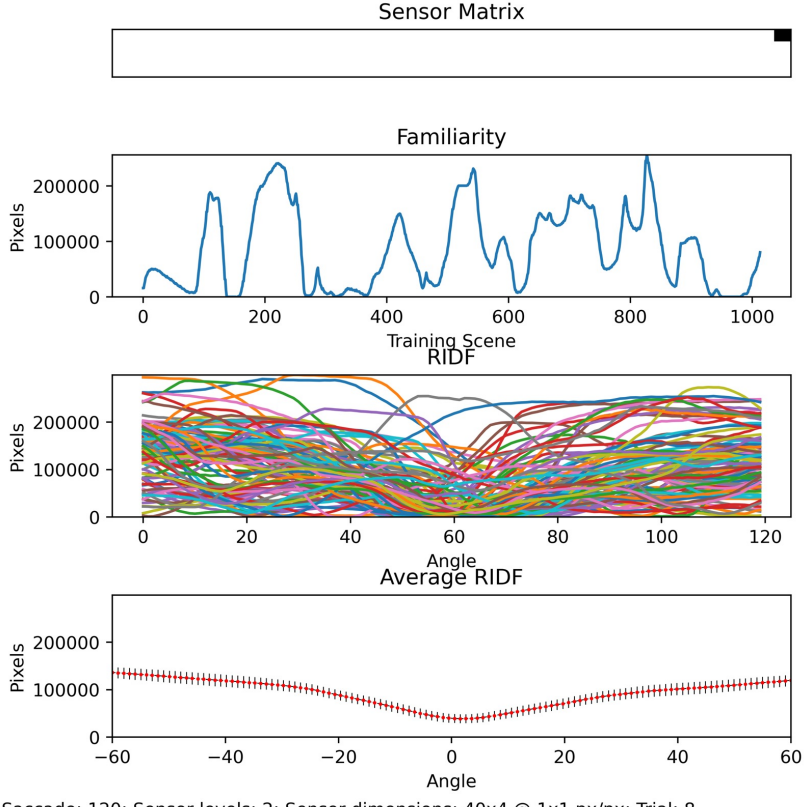




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 2670.71; RMSD/dist: 6.677; TD: 73466; p90: 62; p50: 32; complete: 0

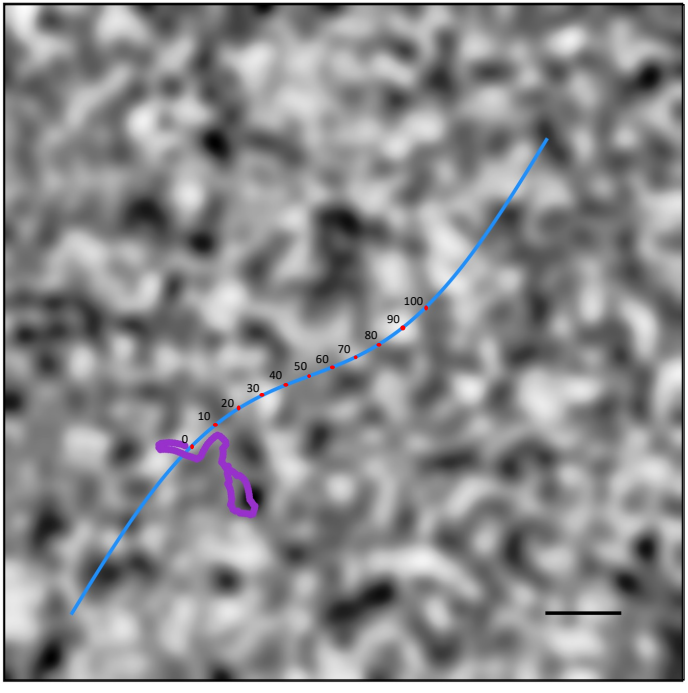
0%

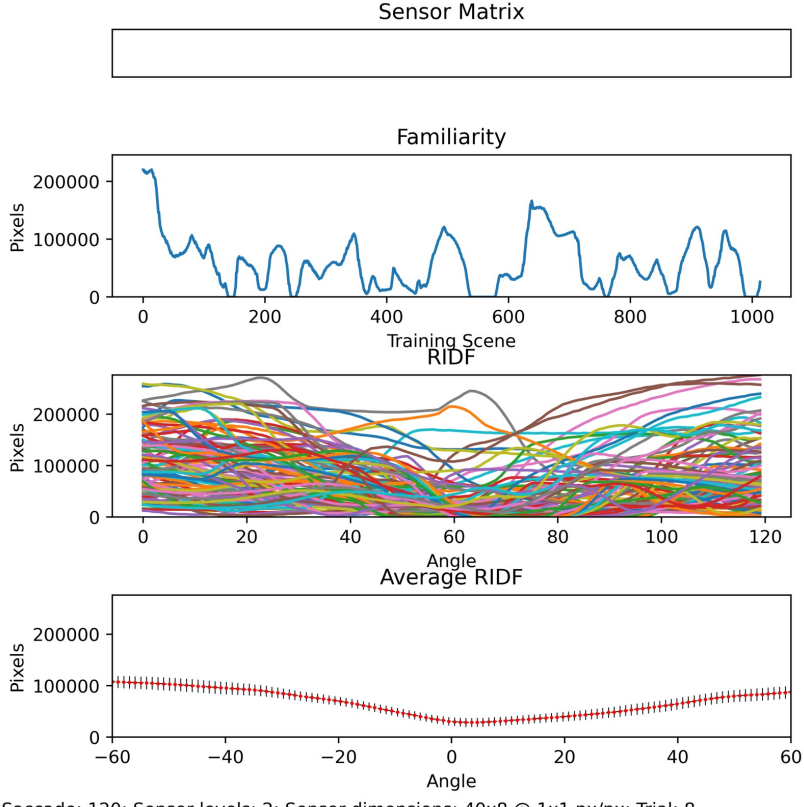




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 1296.32; RMSD/dist: 3.241; TD: 54408; p90: 40; p50: 24; complete: 0

0%

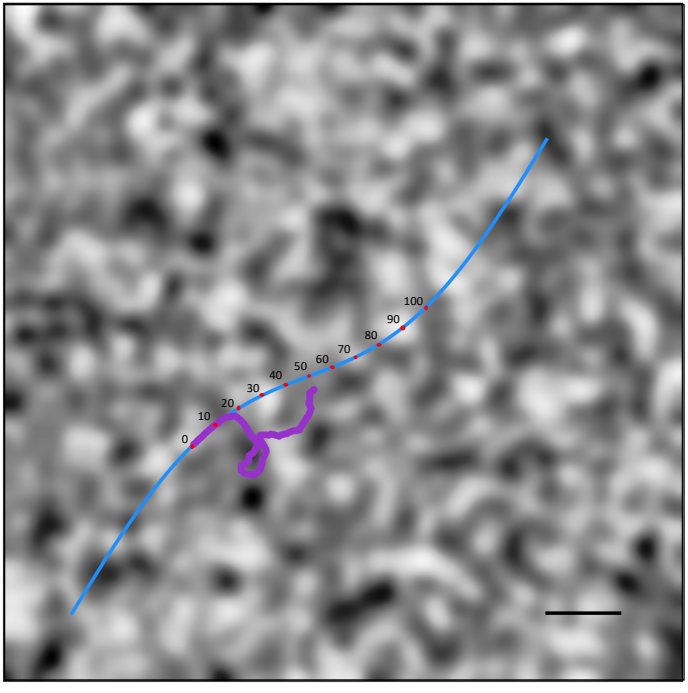


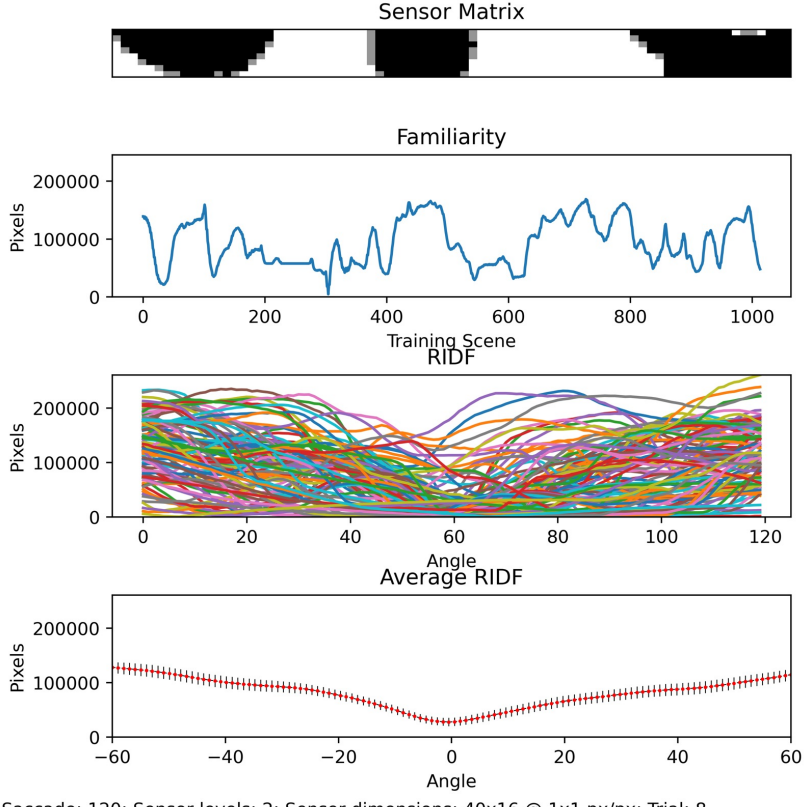


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5742.18; RMSD/dist: 14.355; TD: 55455; p90: 52; p50: 28; complete: 0

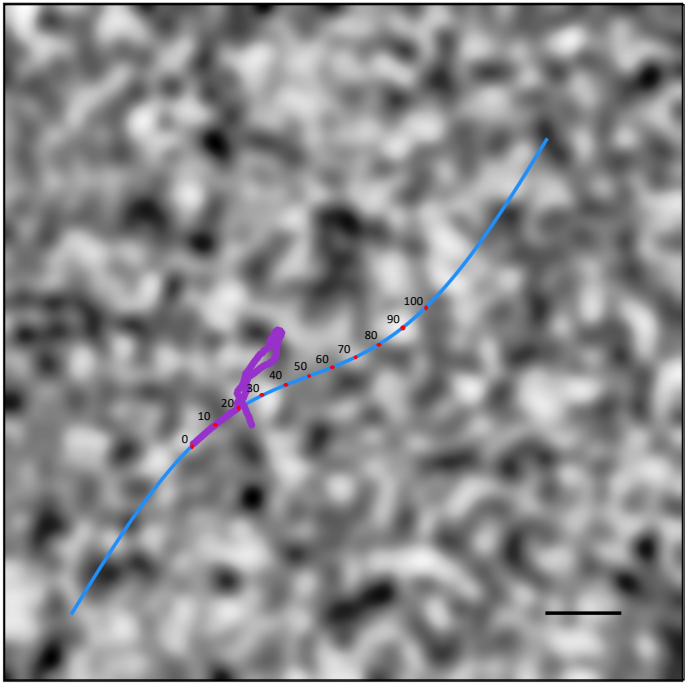
10%

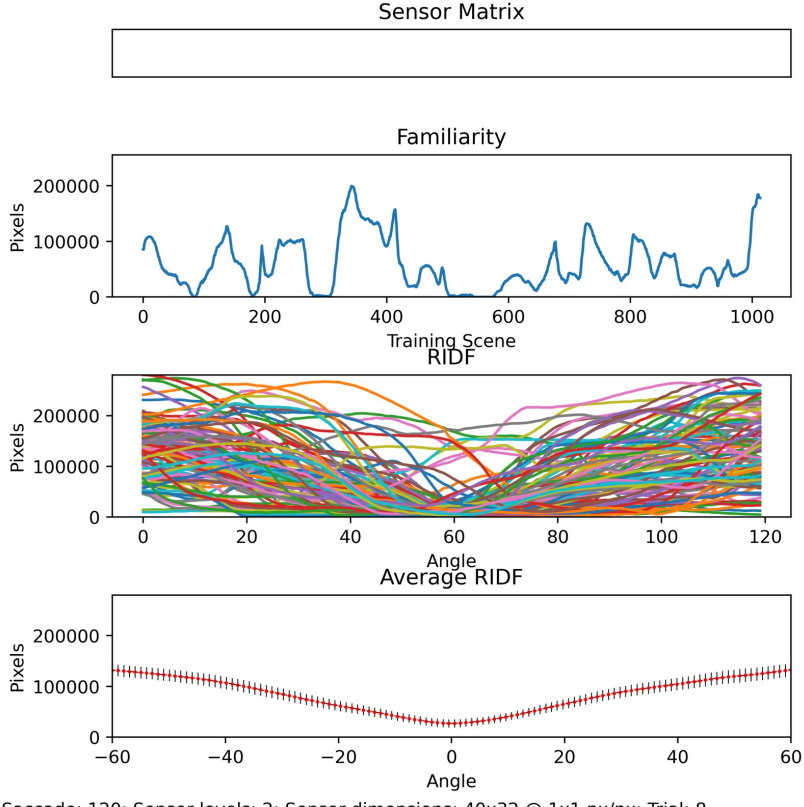




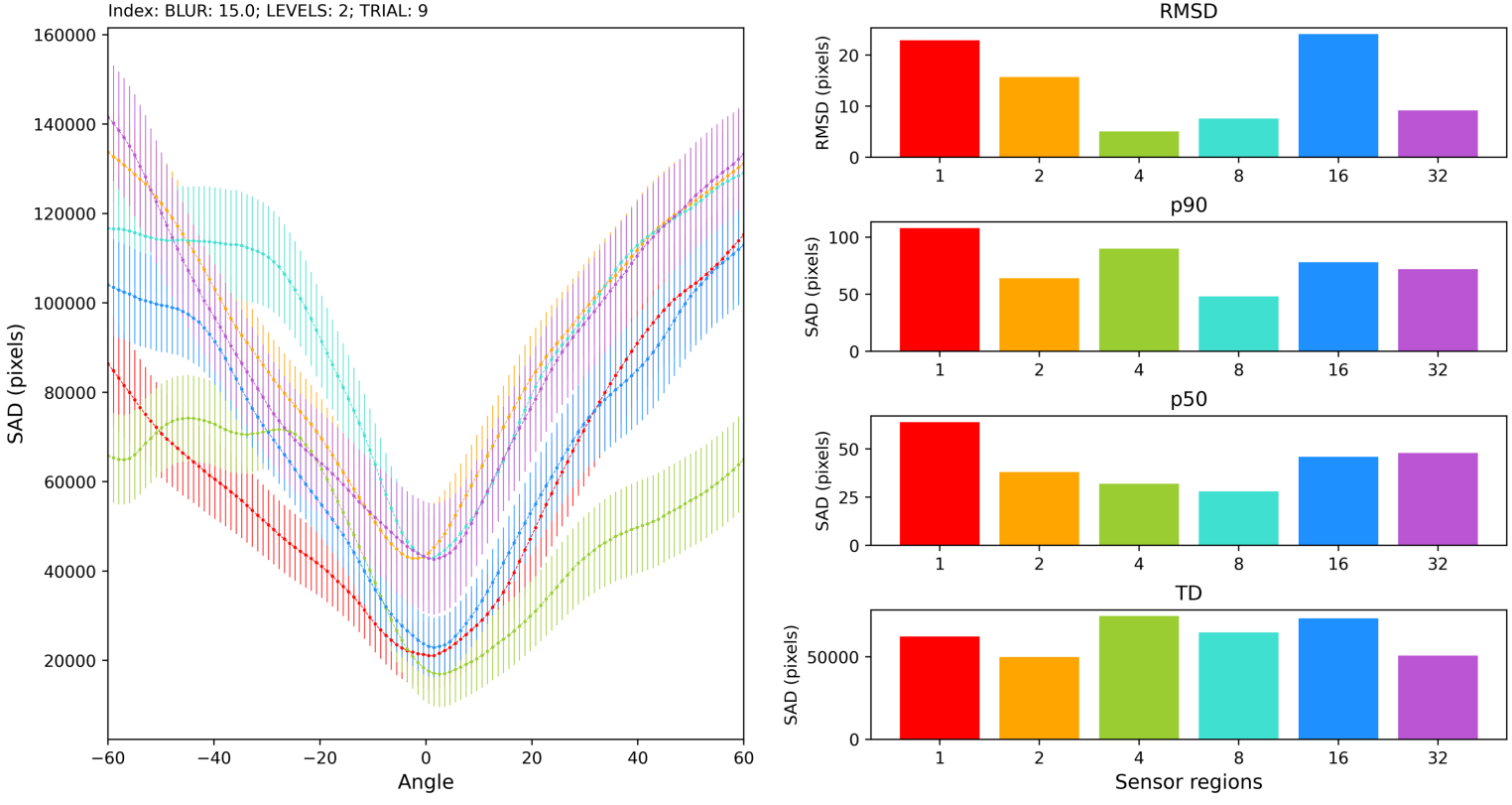
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 4738.61; RMSD/dist: 11.847; TD: 72544; p90: 62; p50: 30; complete: 0

20%

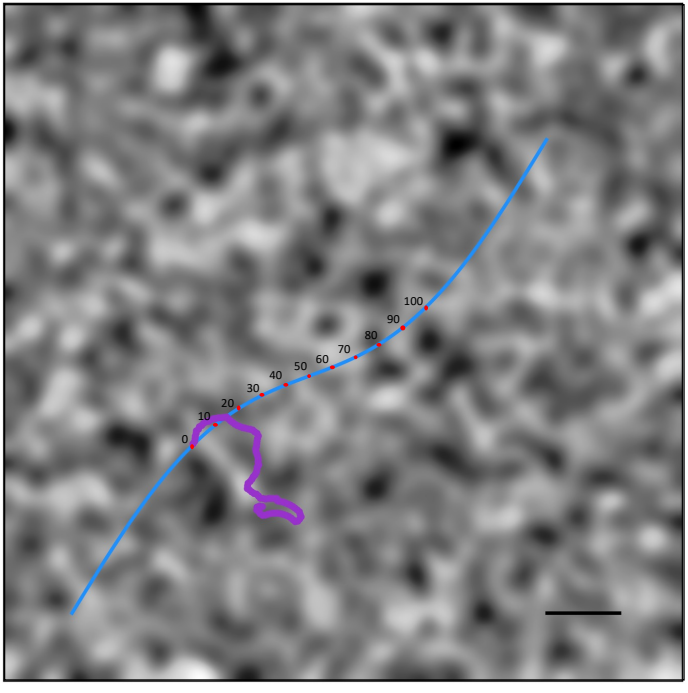


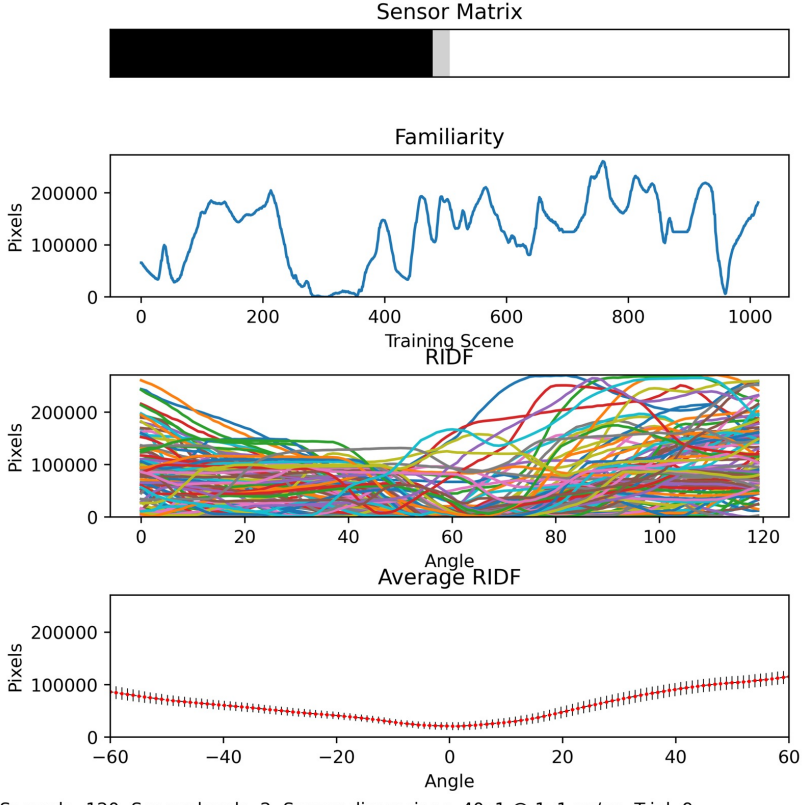


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 3058.19; RMSD/dist: 7.645; TD: 78887; p90: 72; p50: 46; complete: 0


Index: BLUR: 15.0; LEVELS: 2; TRIAL: 9
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
SAD (pixels)
50
25
0
TD
SAD (pixels)
50000
0
Sensor regions

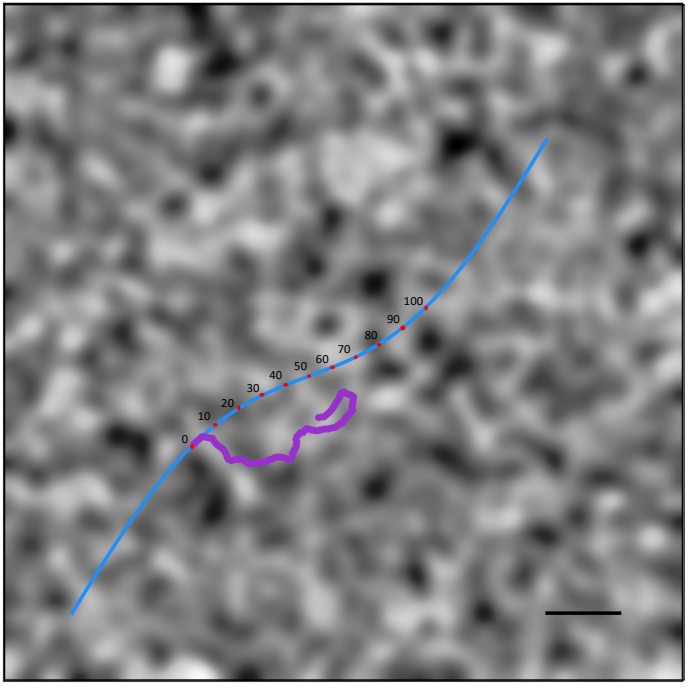
0%

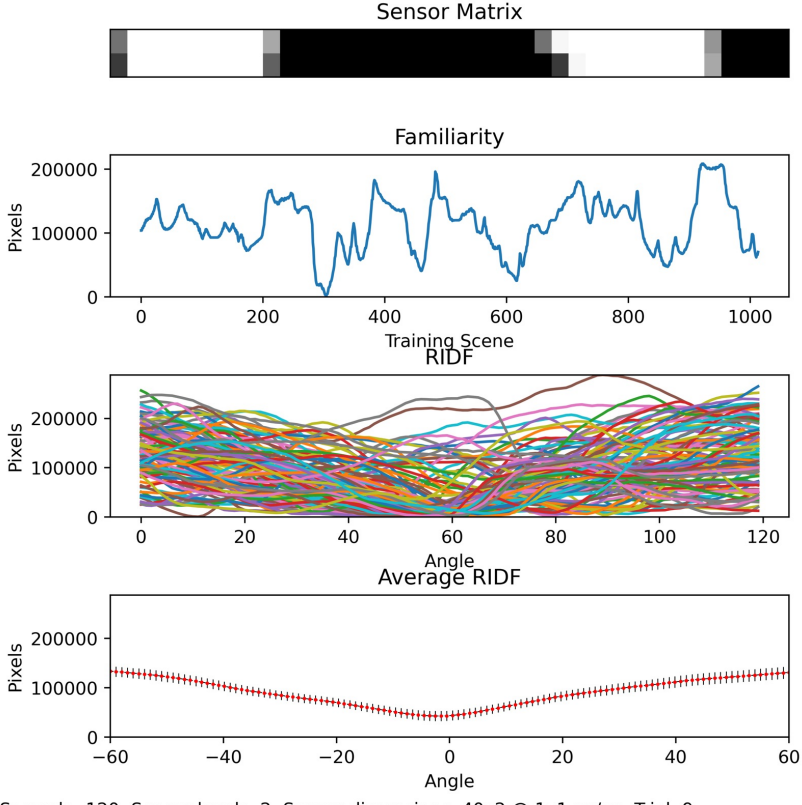




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 9149.65; RMSD/dist: 22.874; TD: 62326; p90: 108; p50: 64; complete: 0

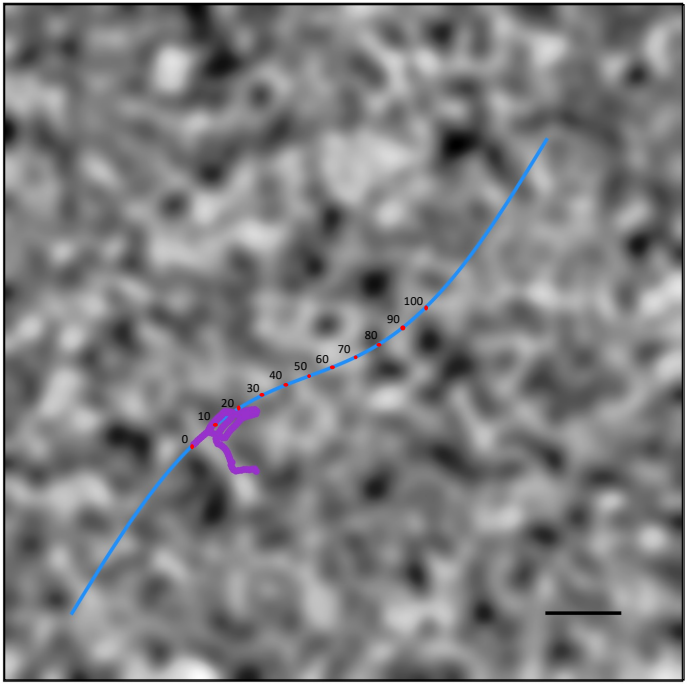
0%

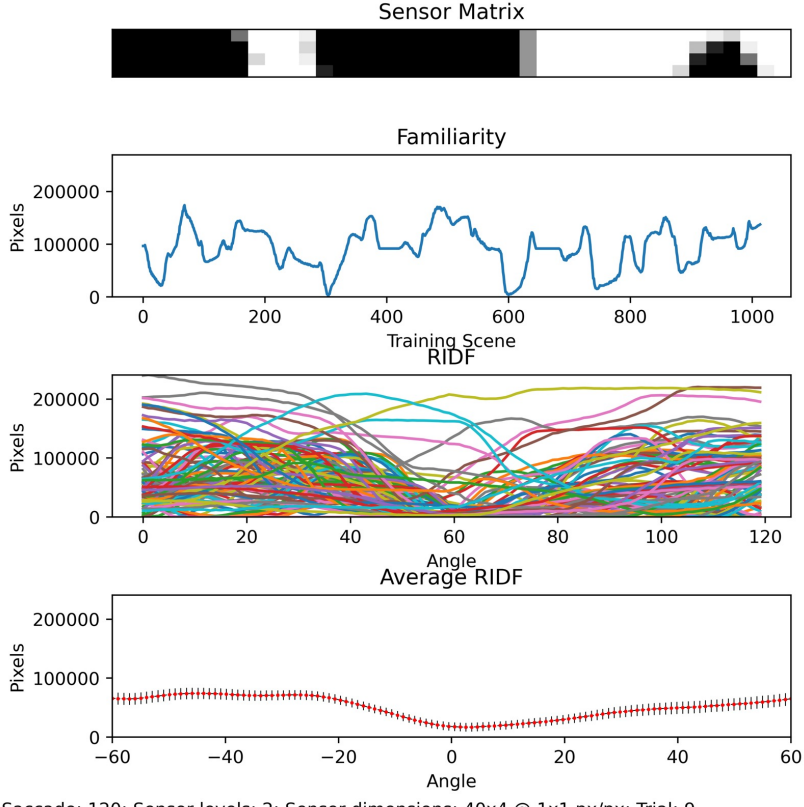




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 6287.17; RMSD/dist: 15.718; TD: 49883; p90: 64; p50: 38; complete: 0

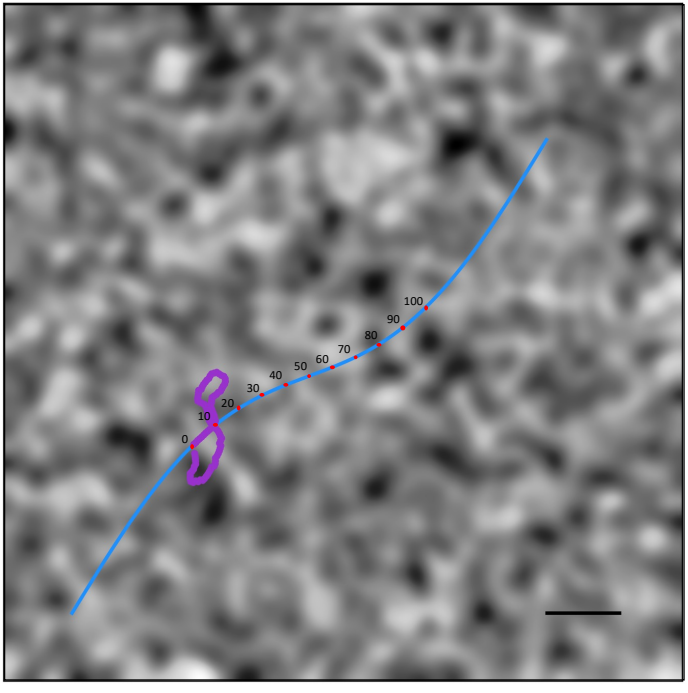
0%

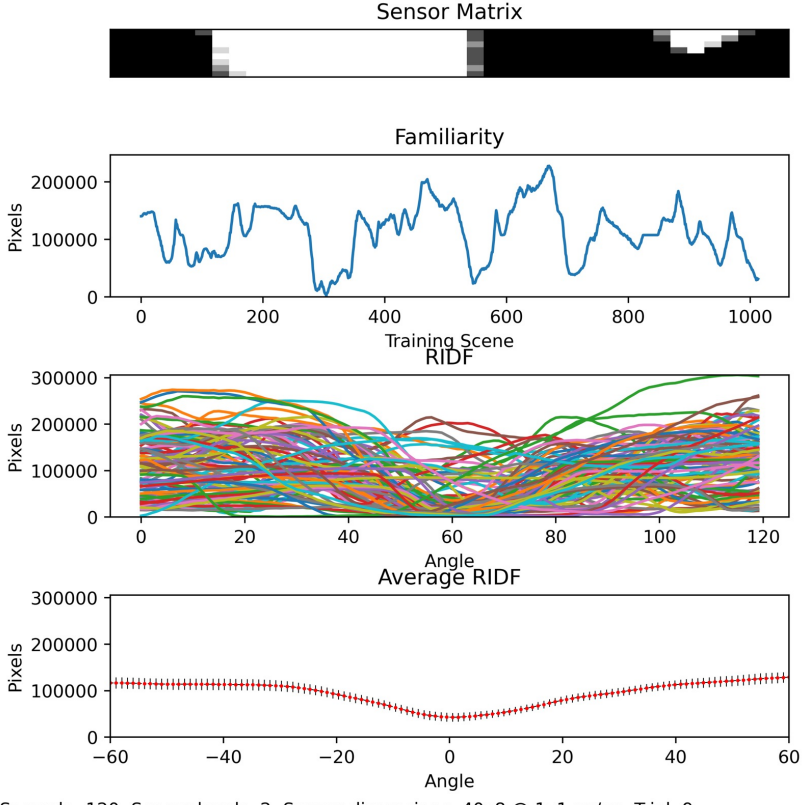




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 2007.85; RMSD/dist: 5.020; TD: 74629; p90: 90; p50: 32; complete: 0

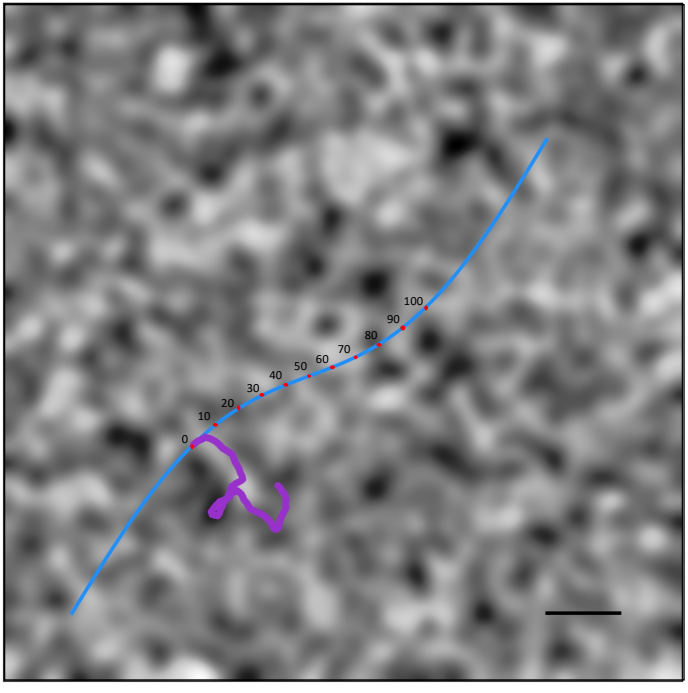
10%

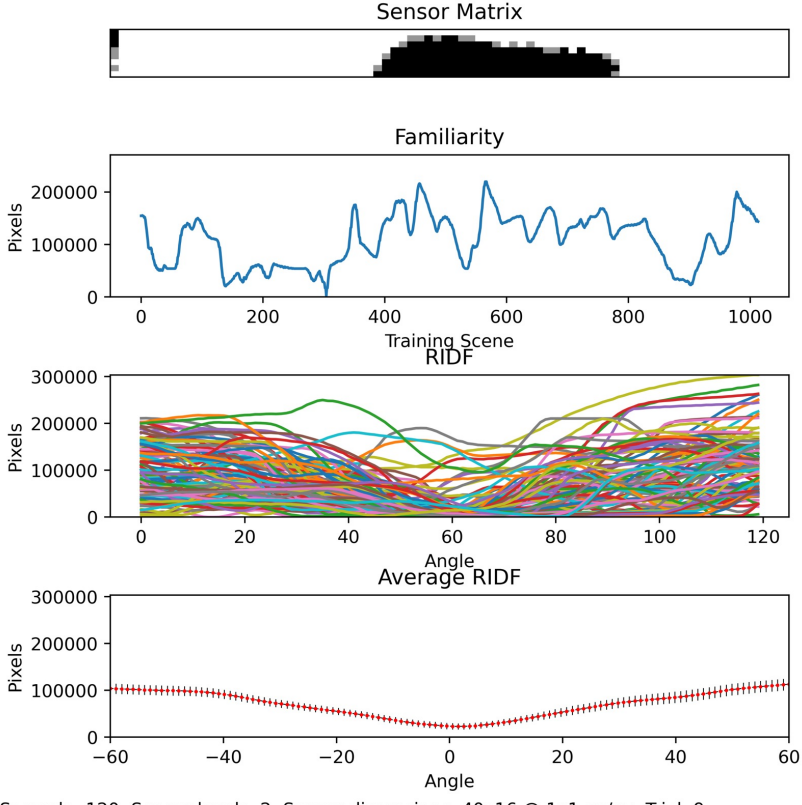




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 3028.86; RMSD/dist: 7.572; TD: 64783; p90: 48; p50: 28; complete: 0

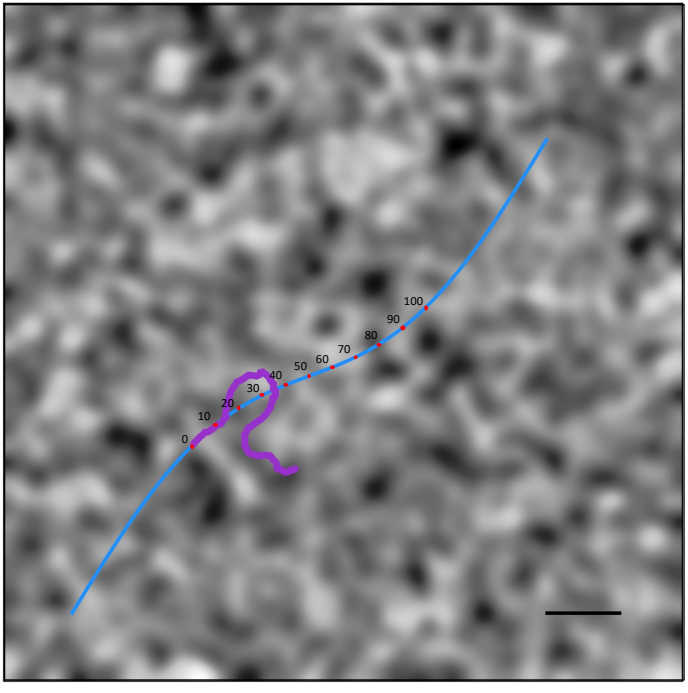
0%

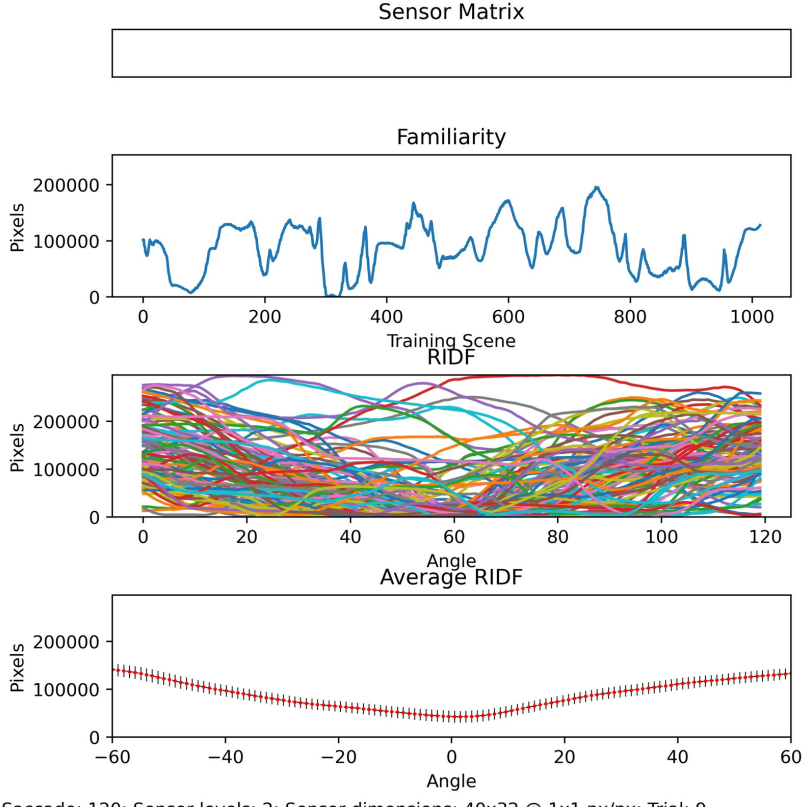




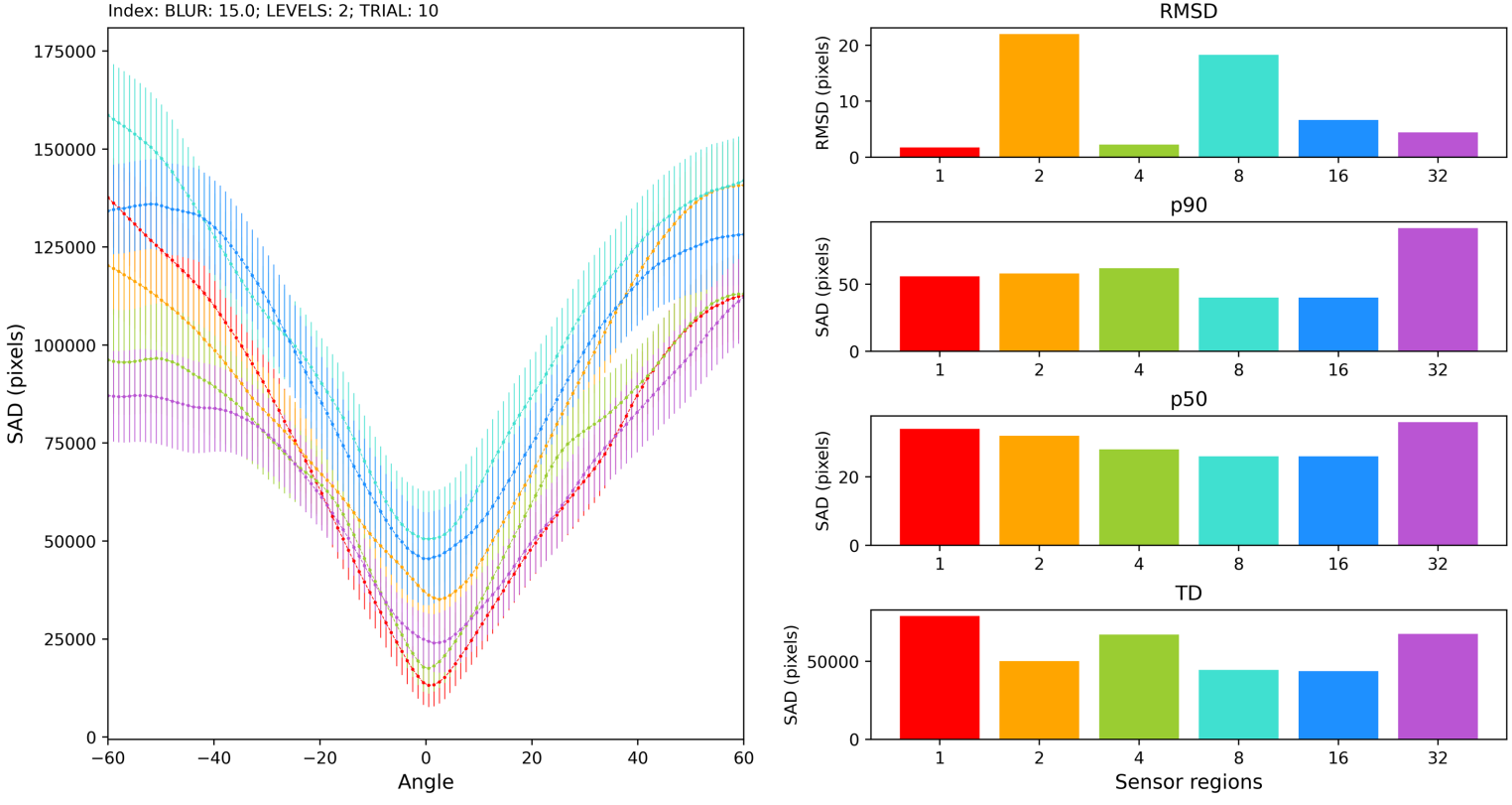
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 9648.54; RMSD/dist: 24.121; TD: 73203; p90: 78; p50: 46; complete: 0

10%

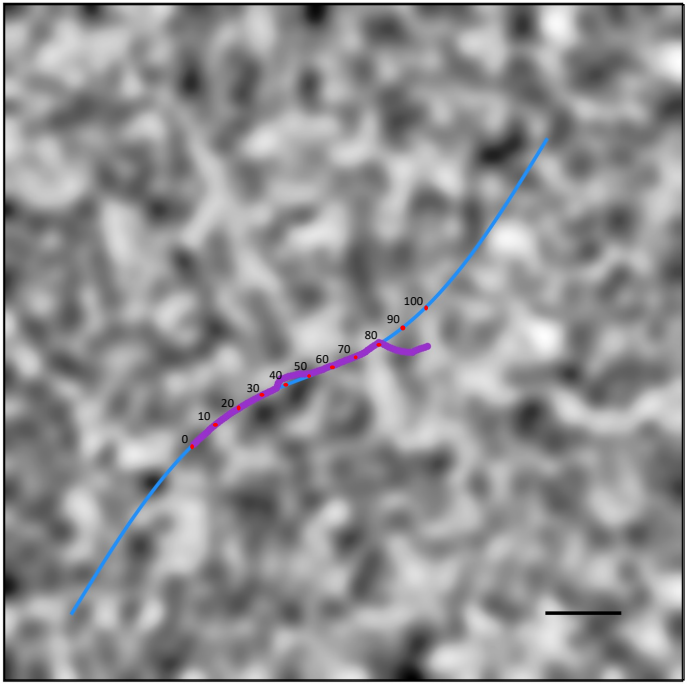


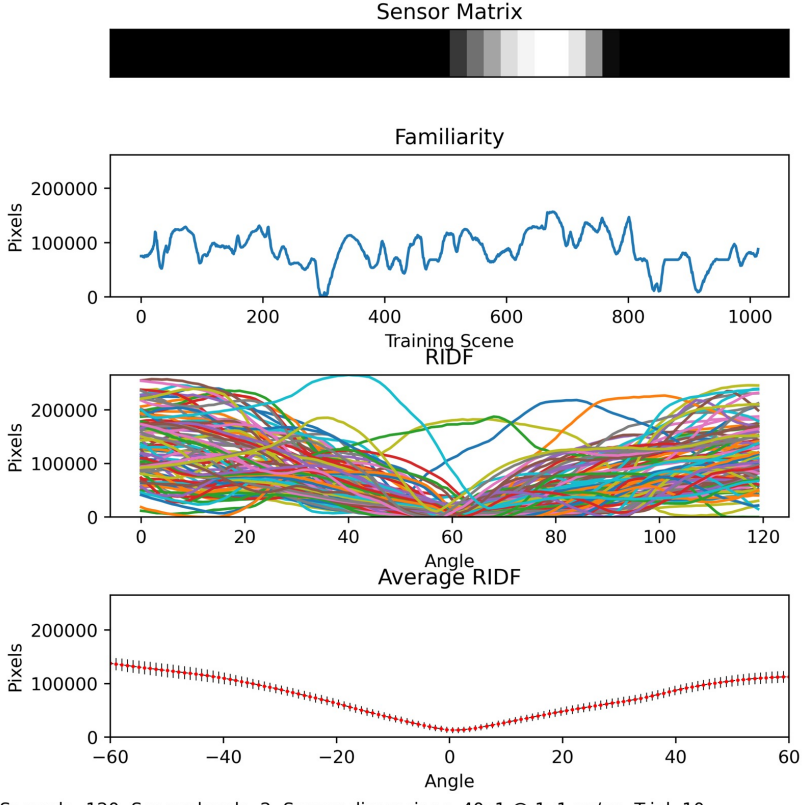


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 3657.07; RMSD/dist: 9.143; TD: 50762; p90: 72; p50: 48; complete: 0


Index: BLUR: 15.0; LEVELS: 2; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

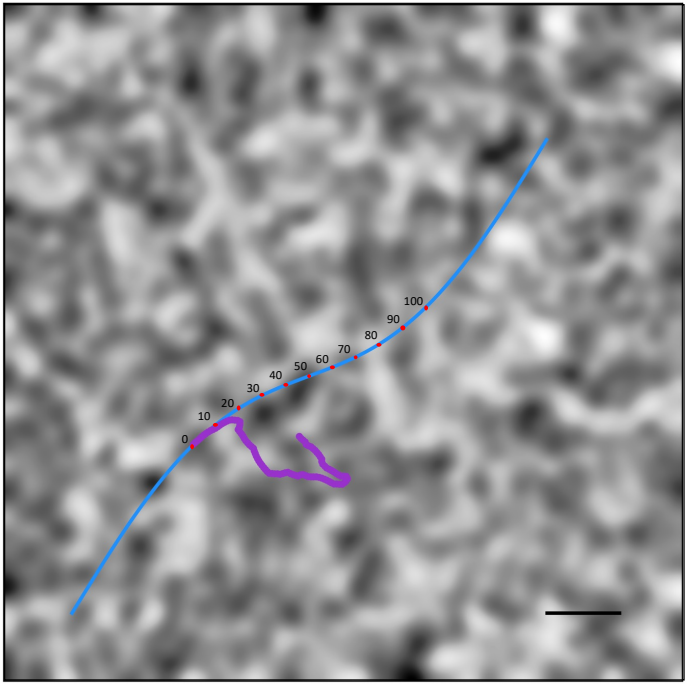
60%

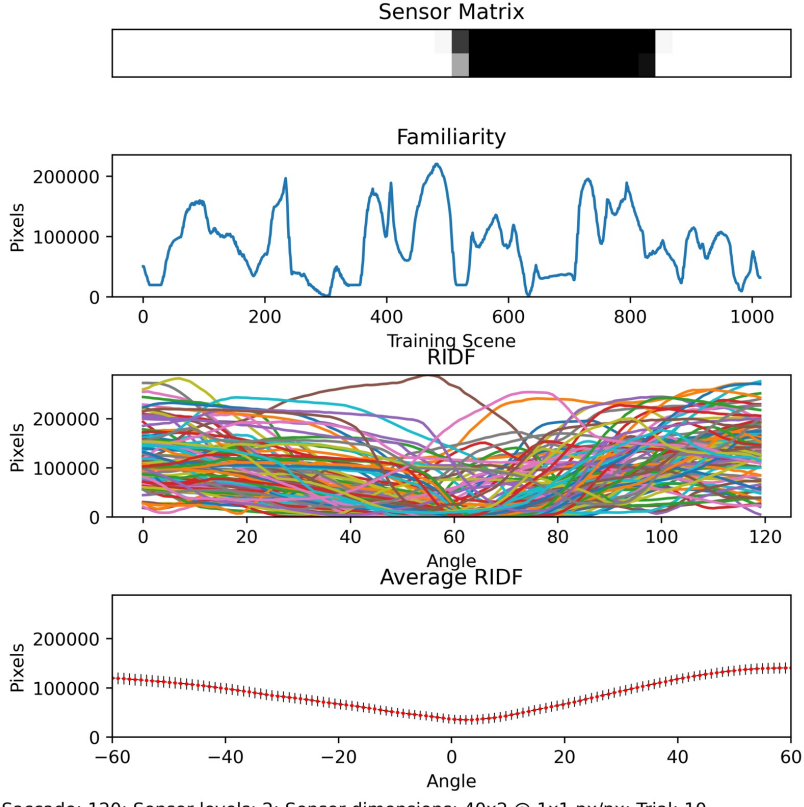




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 691.81; RMSD/dist: 1.730; TD: 79077; p90: 56; p50: 34; complete: 0

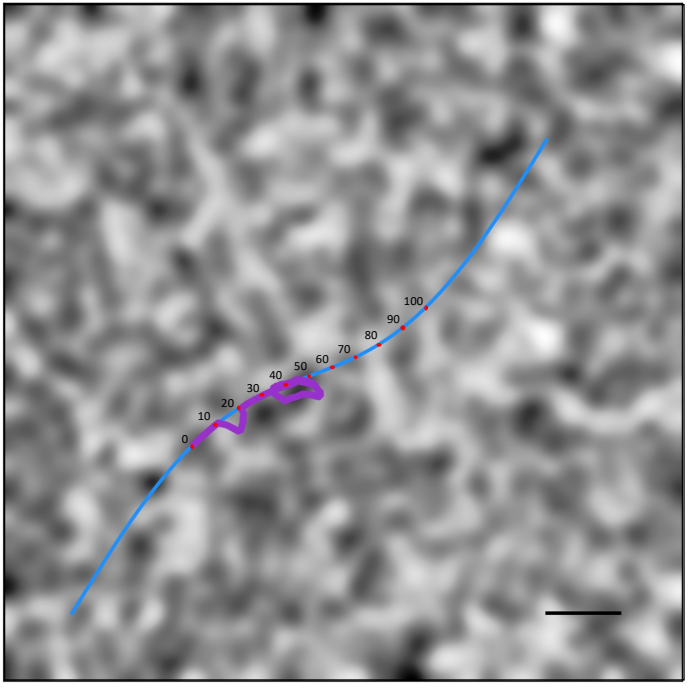
0%

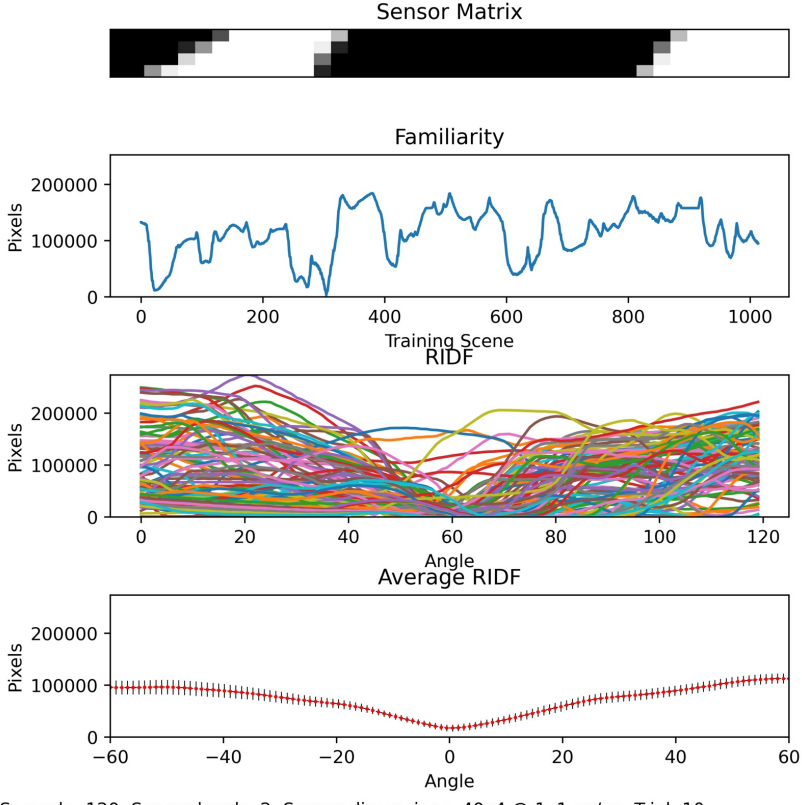




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 8800.61; RMSD/dist: 22.002; TD: 50221; p90: 58; p50: 32; complete: 0

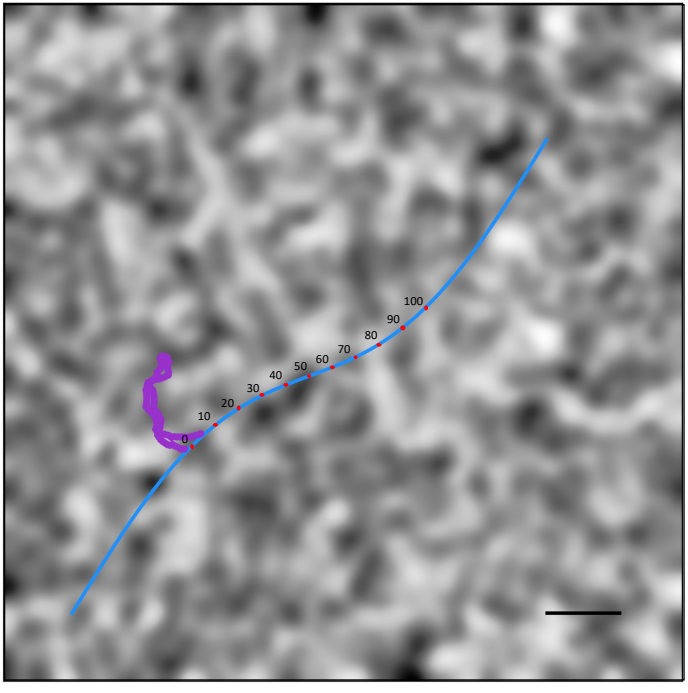
10%

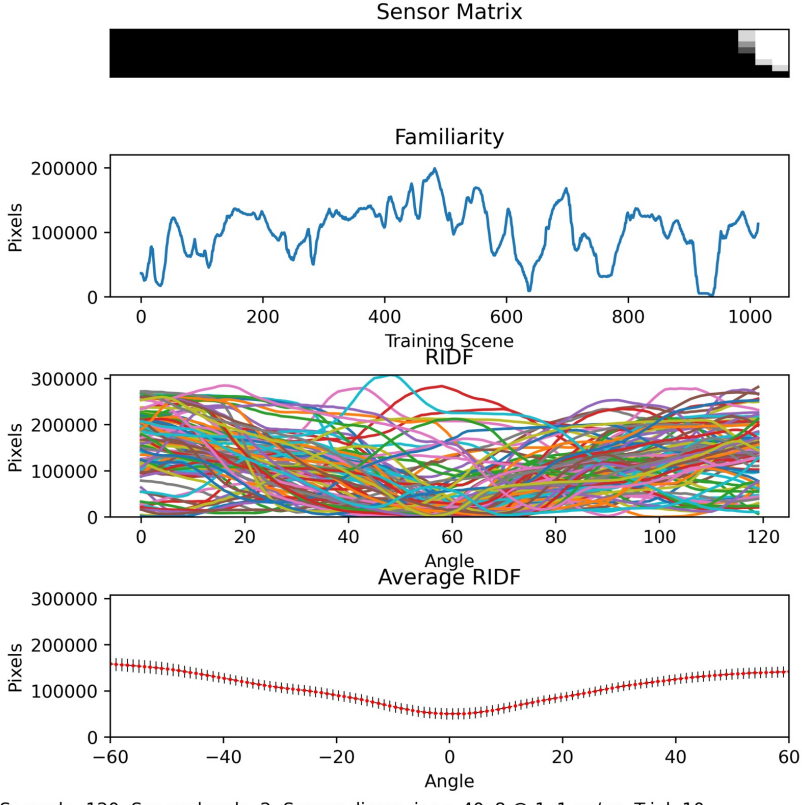




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 899.52; RMSD/dist: 2.249; TD: 67161; p90: 62; p50: 28; complete: 0

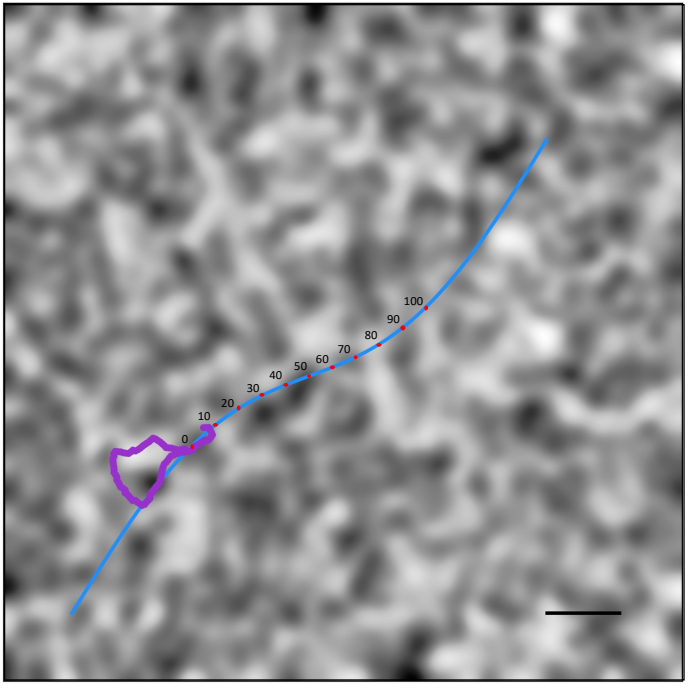
0%

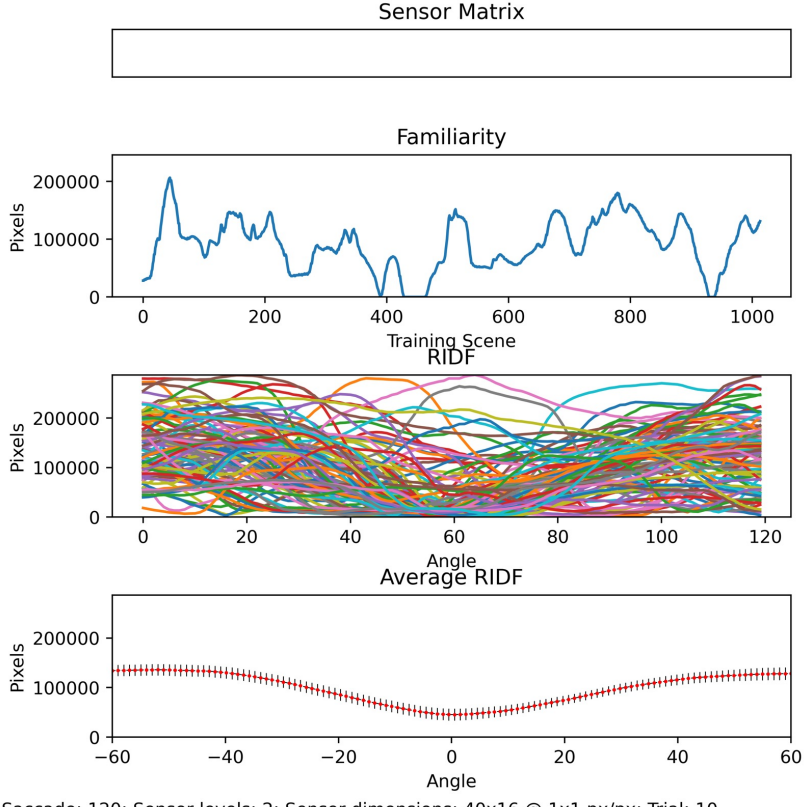




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 7314.07; RMSD/dist: 18.285; TD: 44511; p90: 40; p50: 26; complete: 0

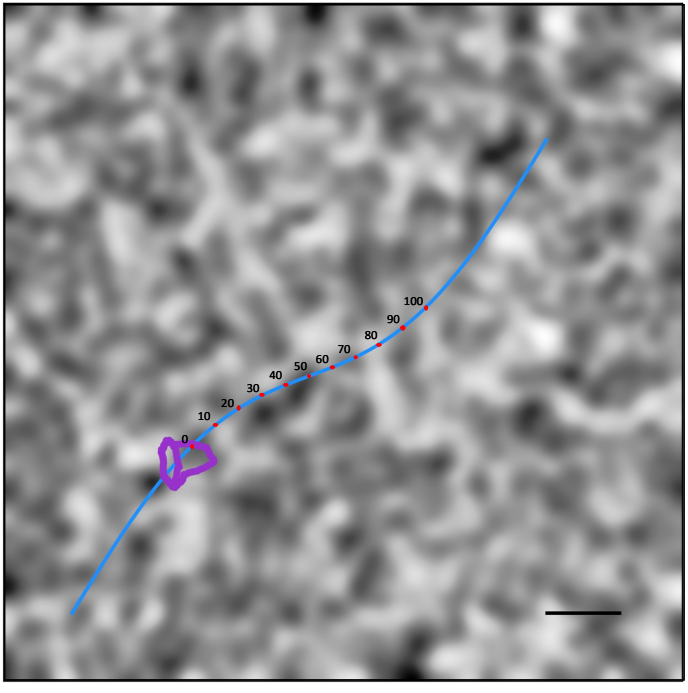
0%

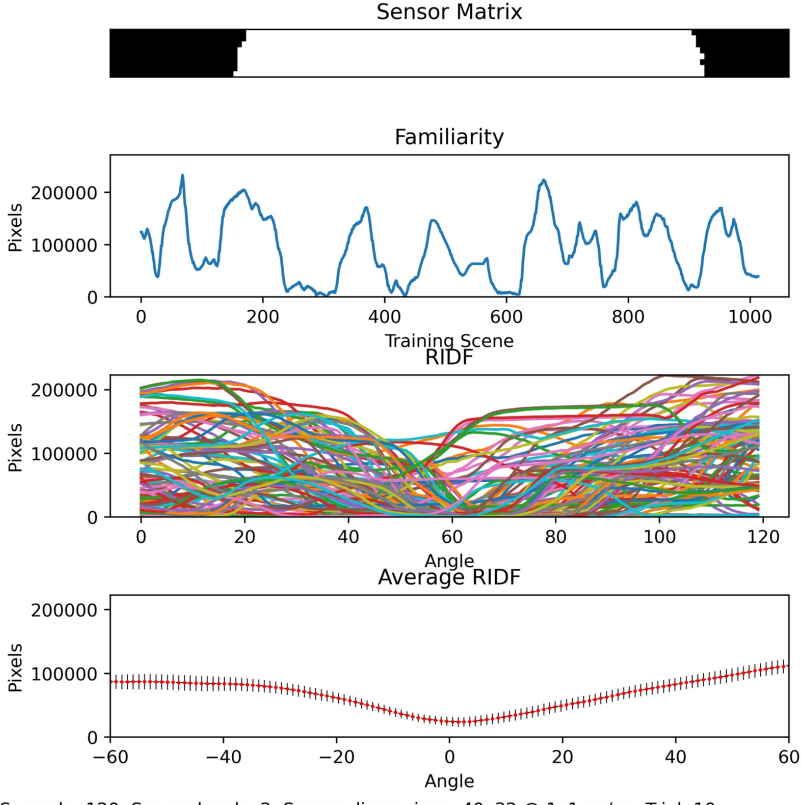




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 2652.78; RMSD/dist: 6.632; TD: 43830; p90: 40; p50: 26; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 1765.45; RMSD/dist: 4.414; TD: 67675; p90: 92; p50: 36; complete: 0