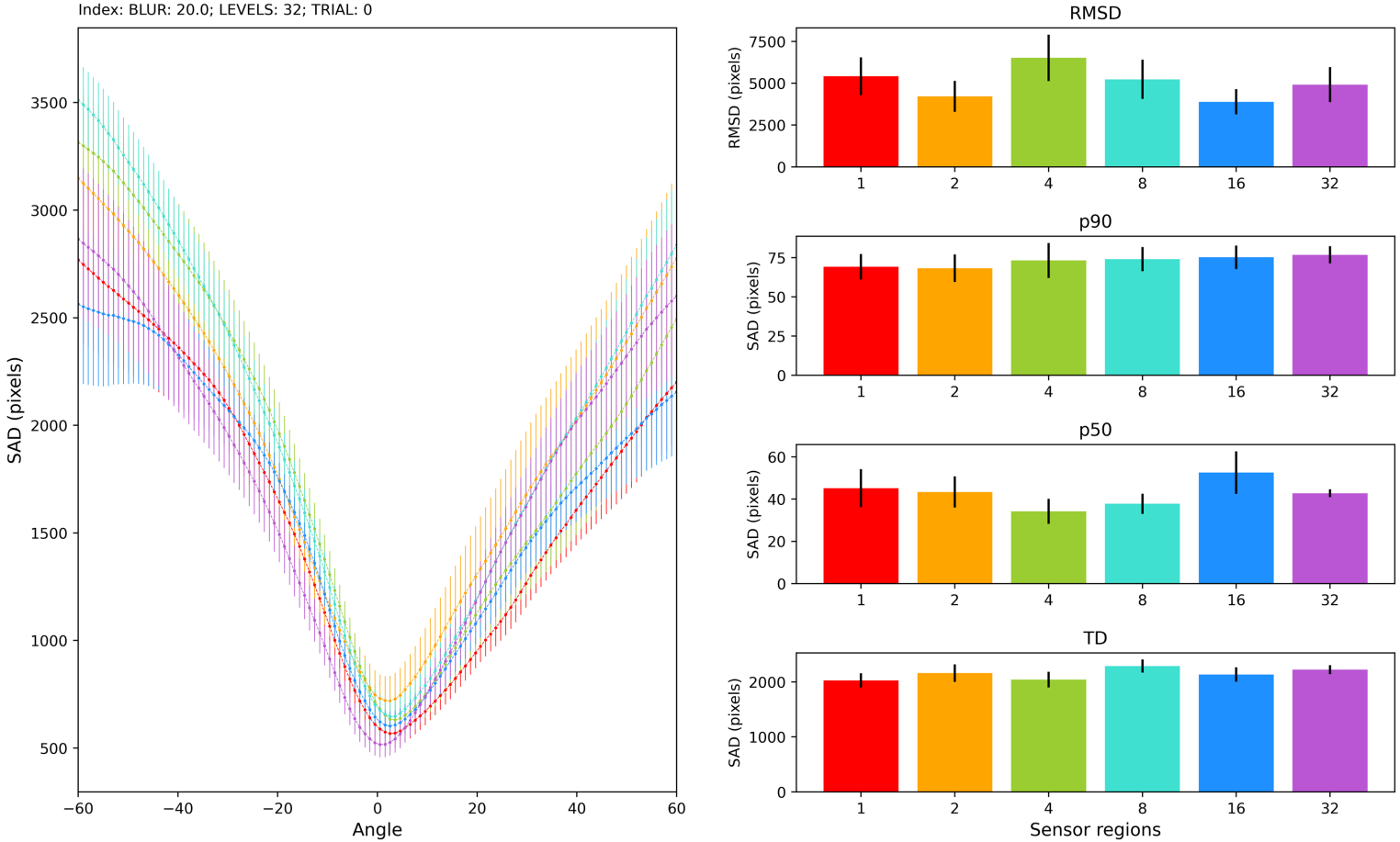
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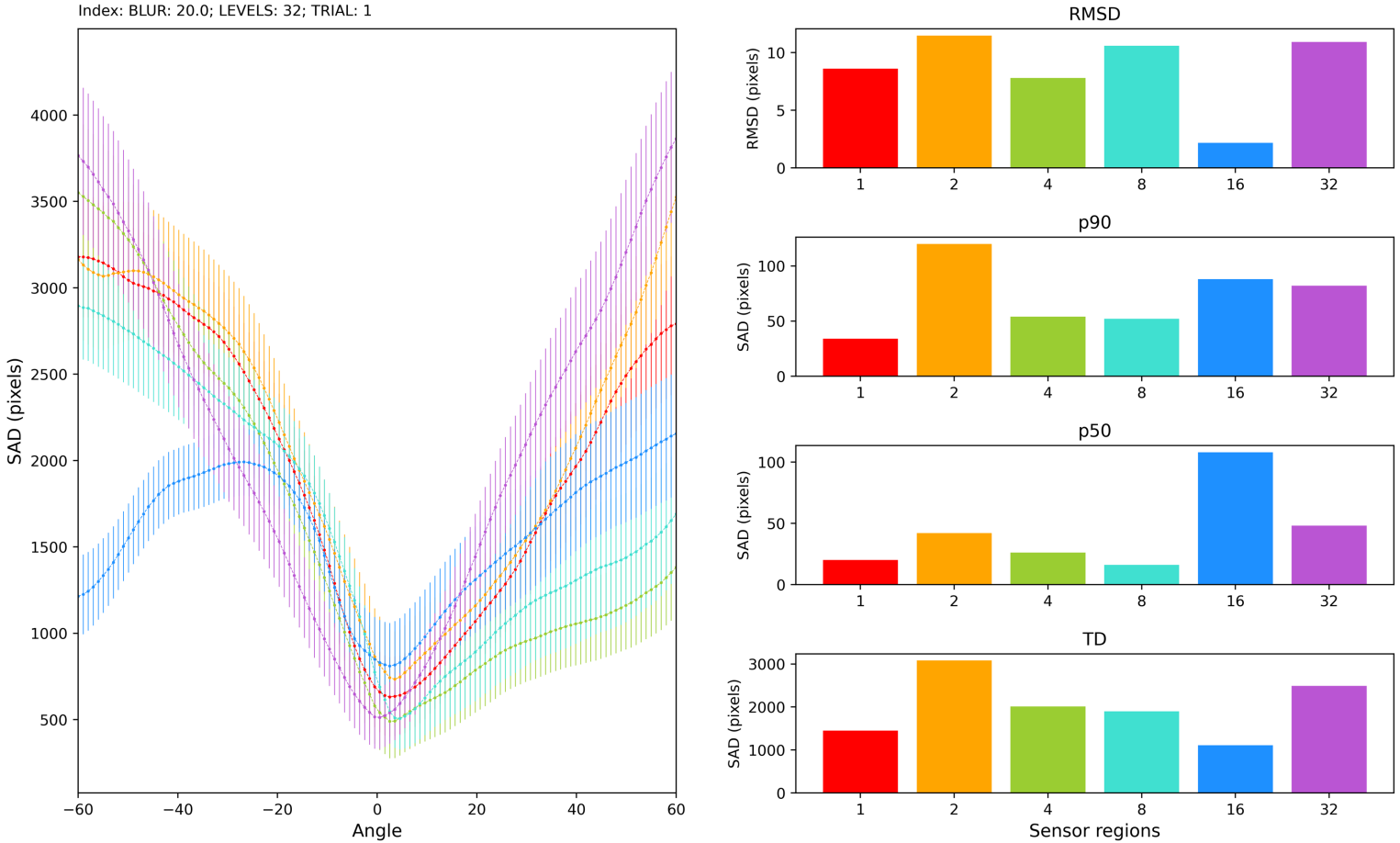
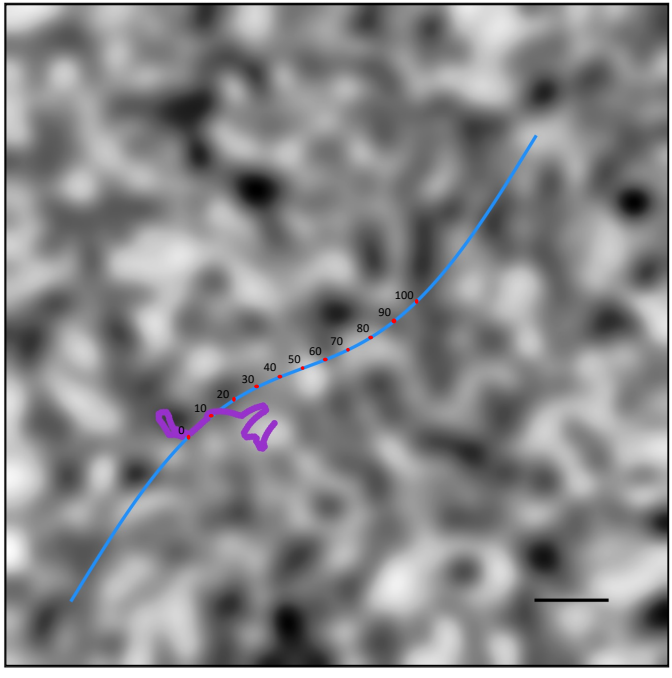
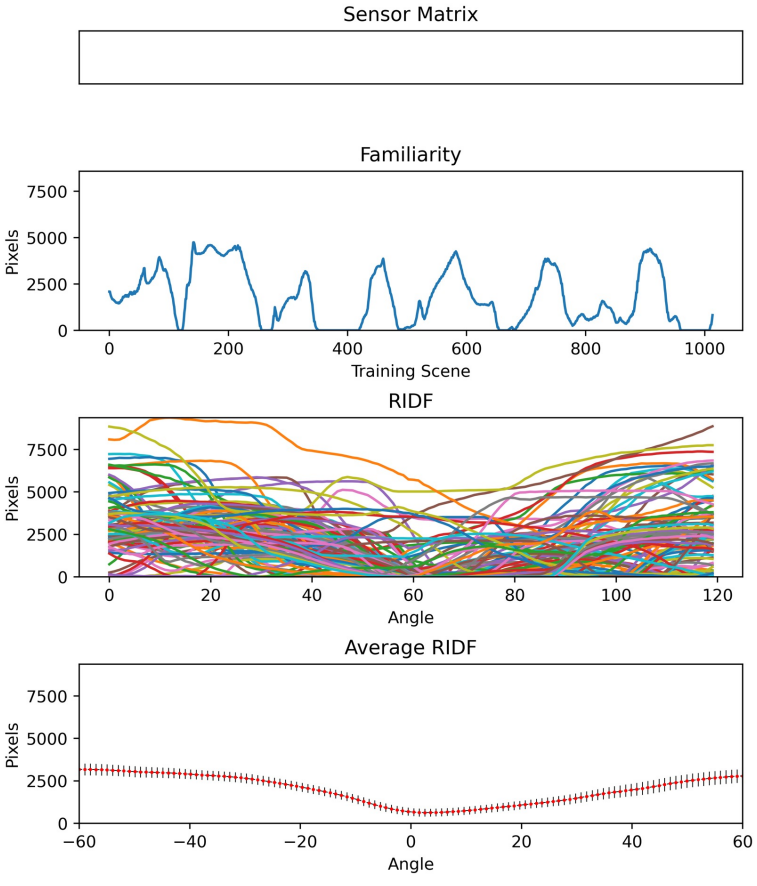
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 20.0; LEVELS: 32; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

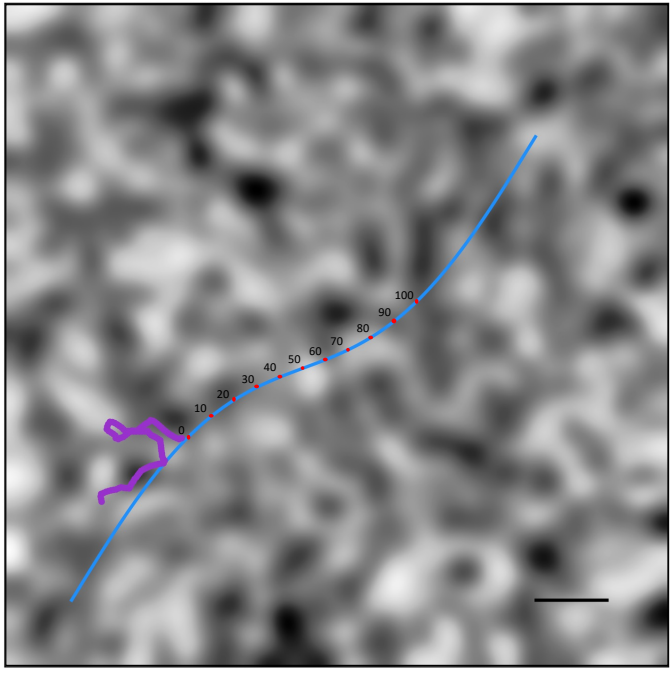


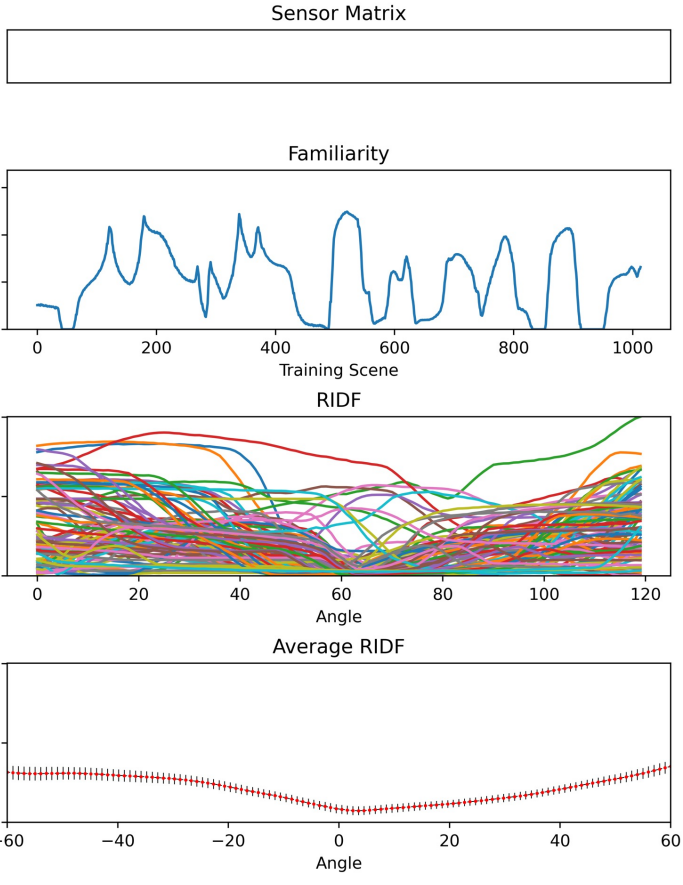


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3444.43; RMSD/dist: 8.611; TD: 1450; p90: 34; p50: 20; complete: 0

0%

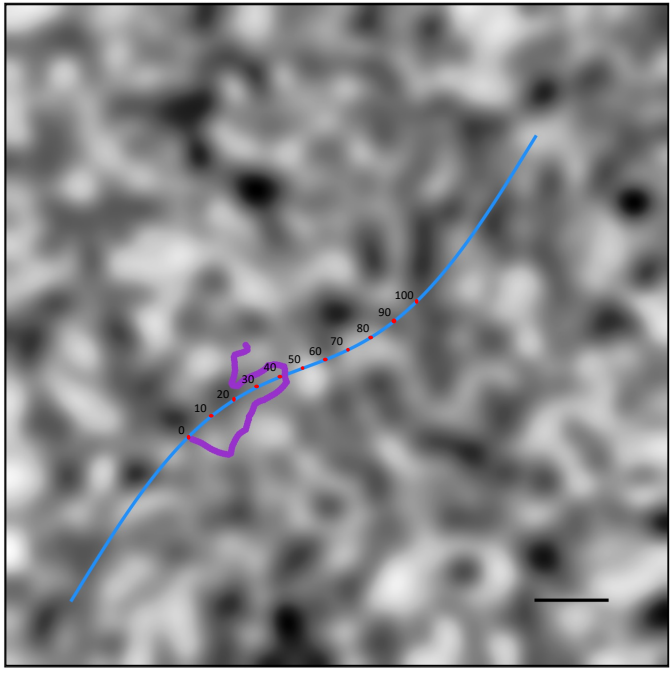


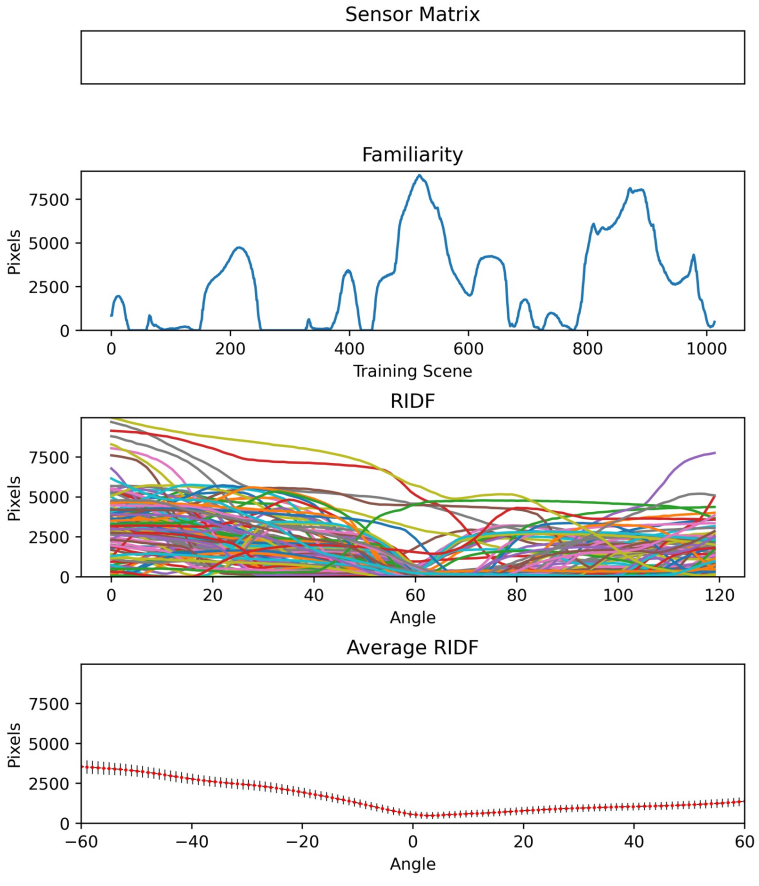


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4592.86; RMSD/dist: 11.482; TD: 3079; p90: 120; p50: 42; complete: 0

0%

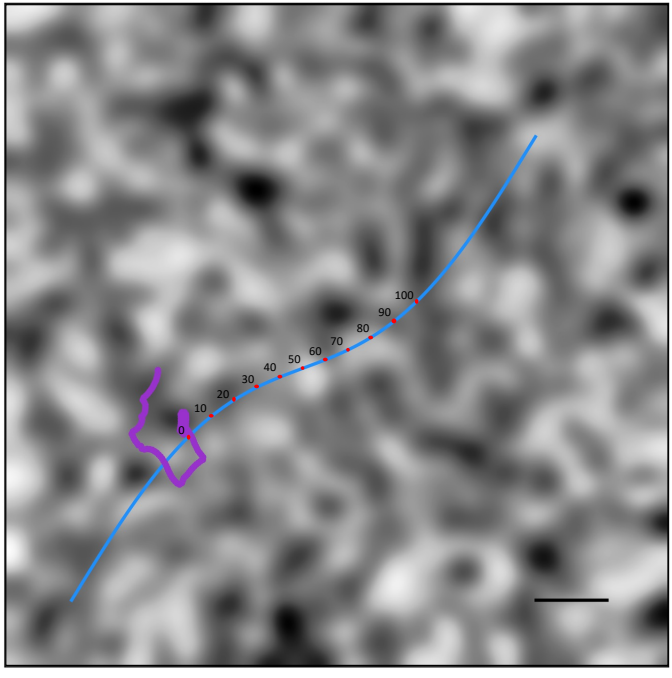


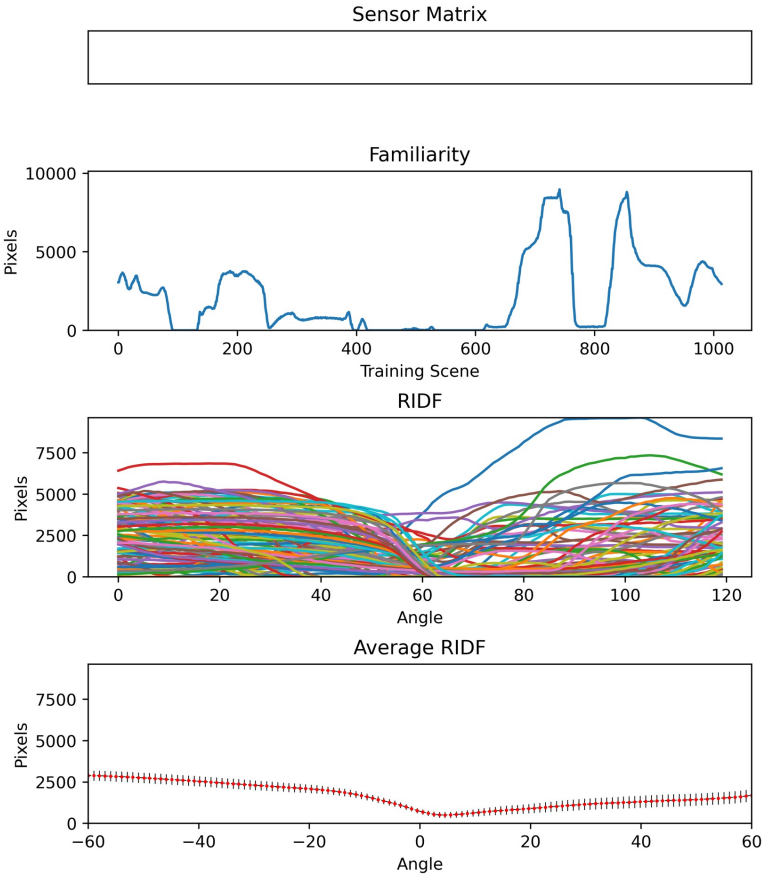


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3117.97; RMSD/dist: 7.795; TD: 2011; p90: 54; p50: 26; complete: 0

0%

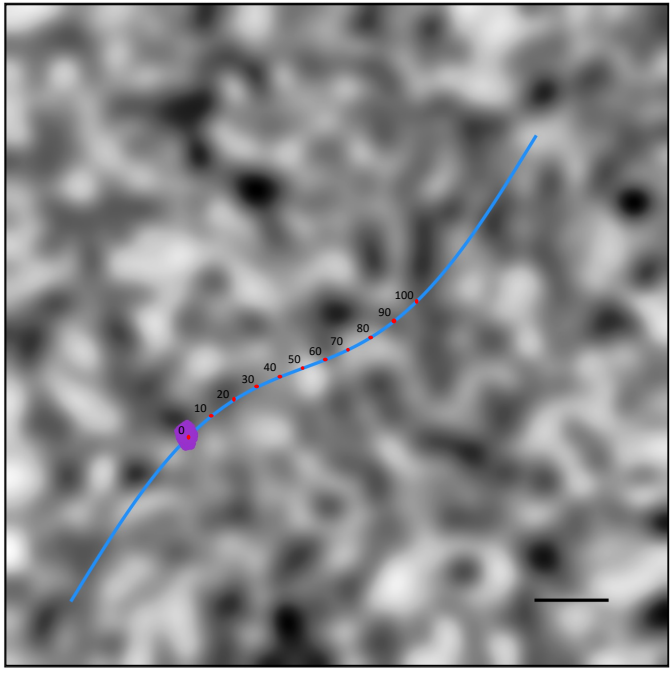


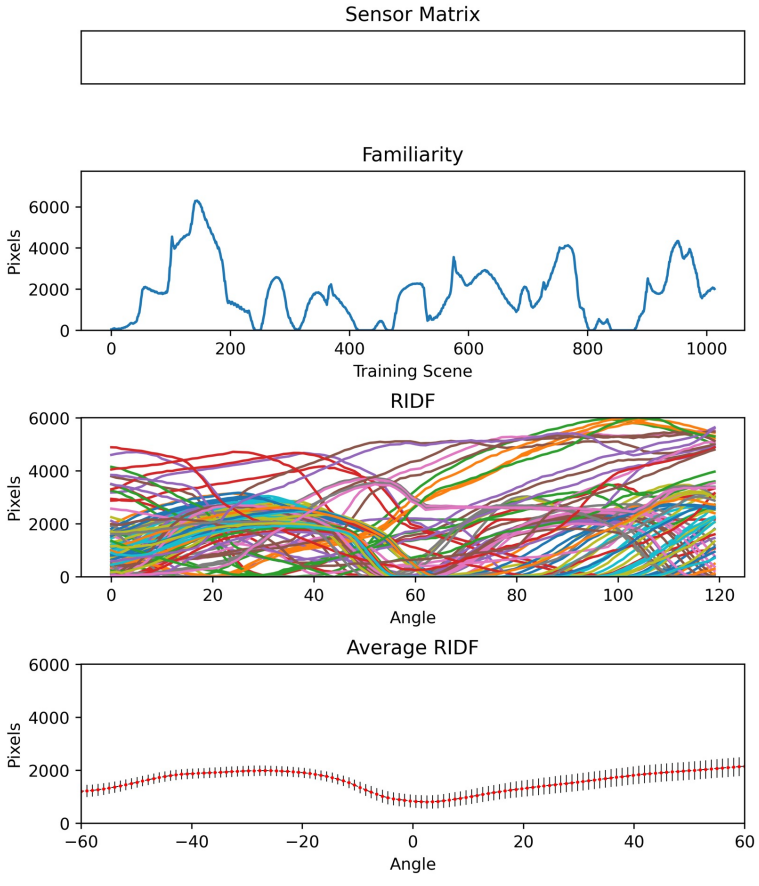


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4236.38; RMSD/dist: 10.591; TD: 1895; p90: 52; p50: 16; complete: 0

0%

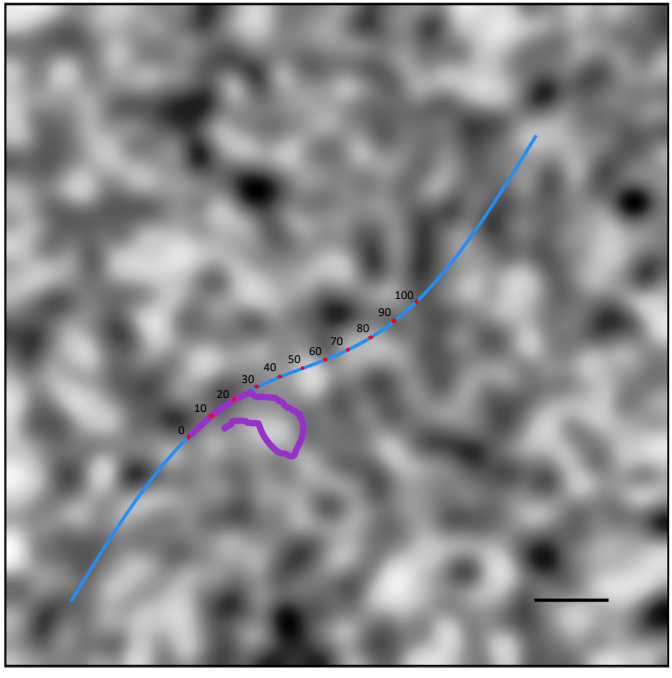


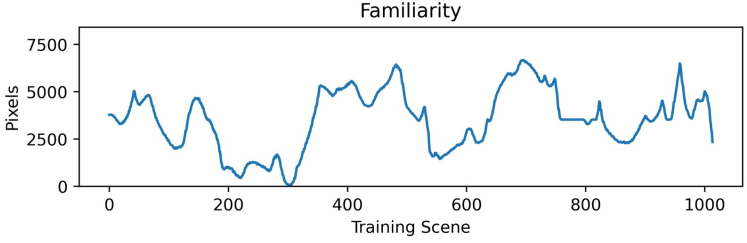


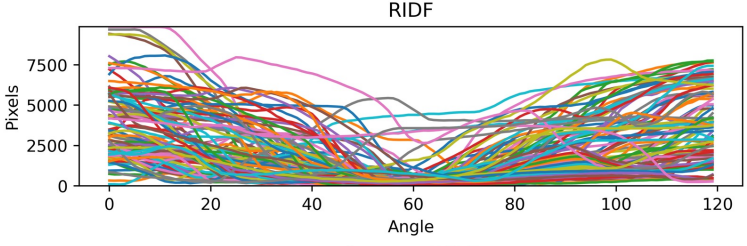
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

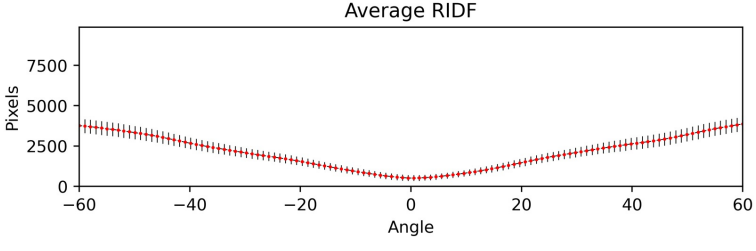
Navigation stats: RMSD error: 863.90; RMSD/dist: 2.160; TD: 1109; p90: 88; p50: 108; complete: 0

20%



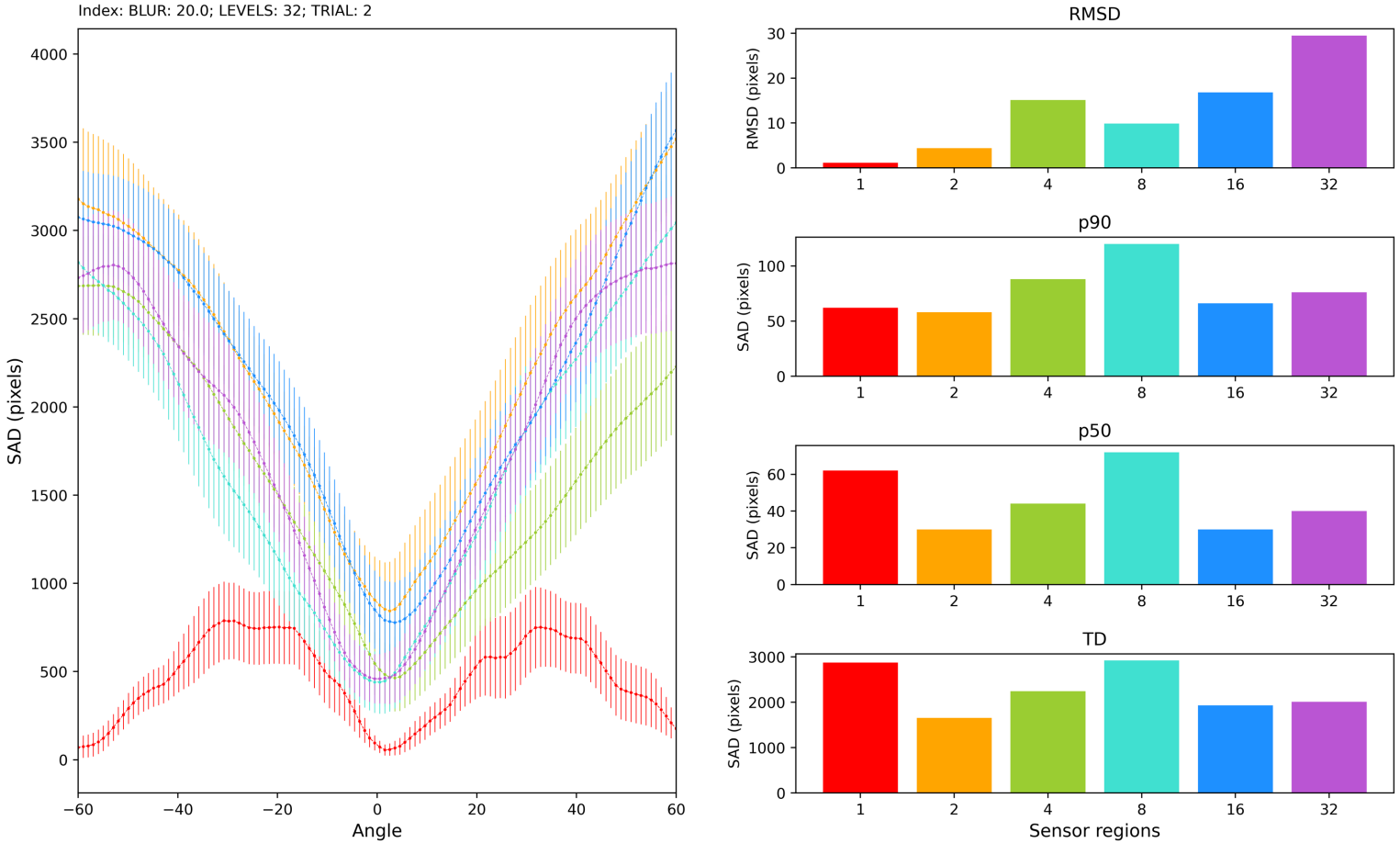




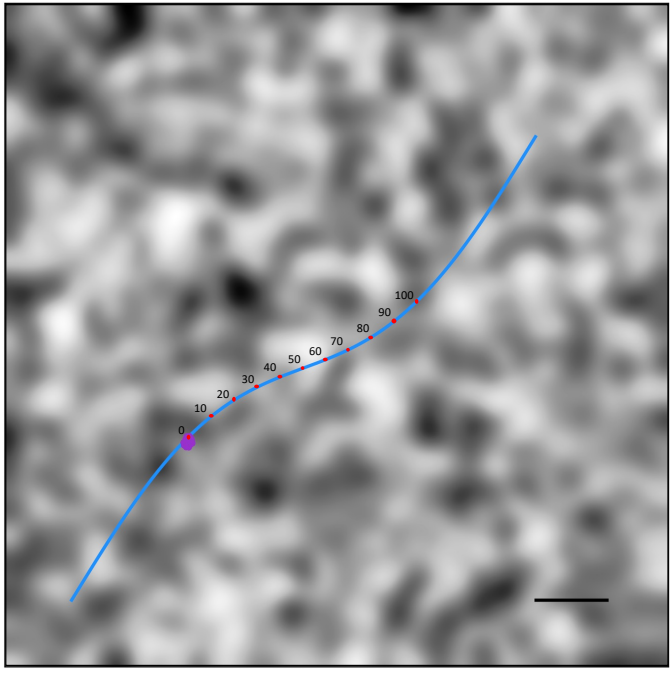


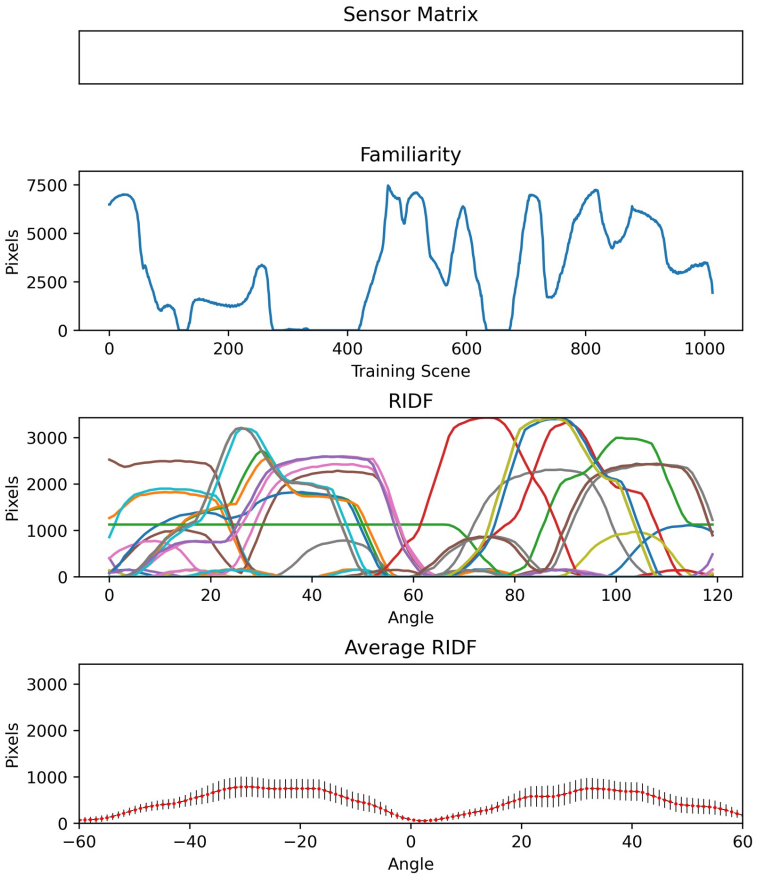
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4366.86; RMSD/dist: 10.917; TD: 2489; p90: 82; p50: 48; complete: 0


Index: BLUR: 20.0; LEVELS: 32; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

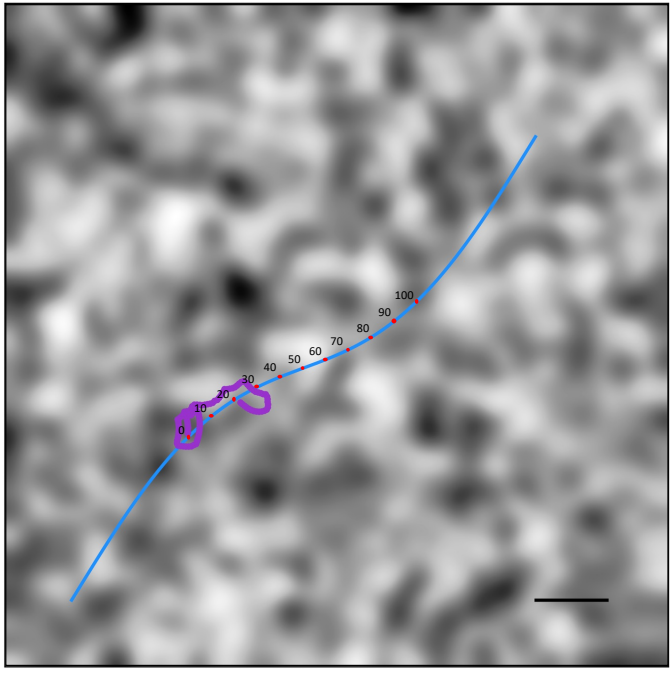


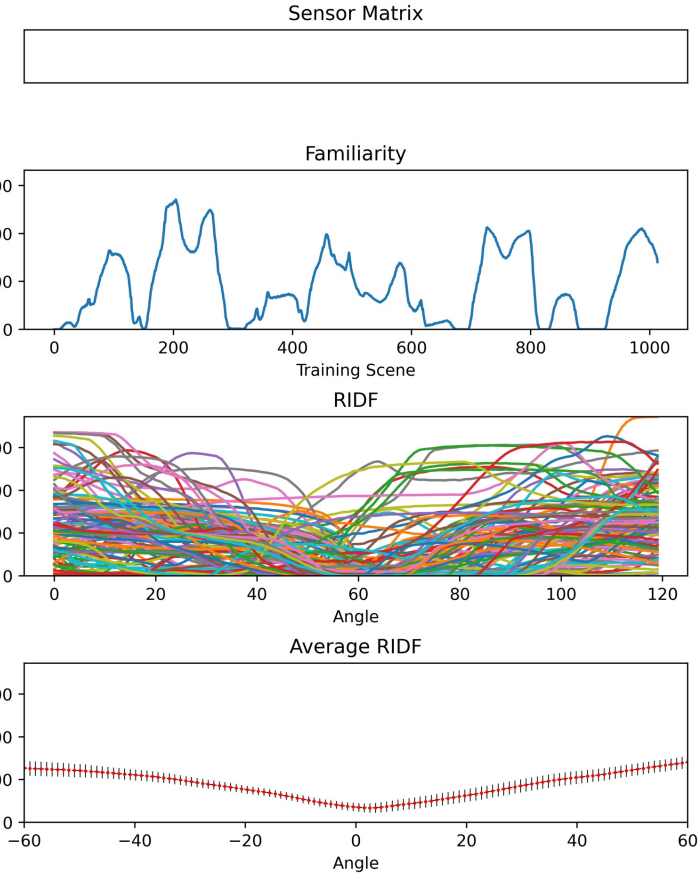


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 440.42; RMSD/dist: 1.101; TD: 2872; p90: 62; p50: 62; complete: 0

0%

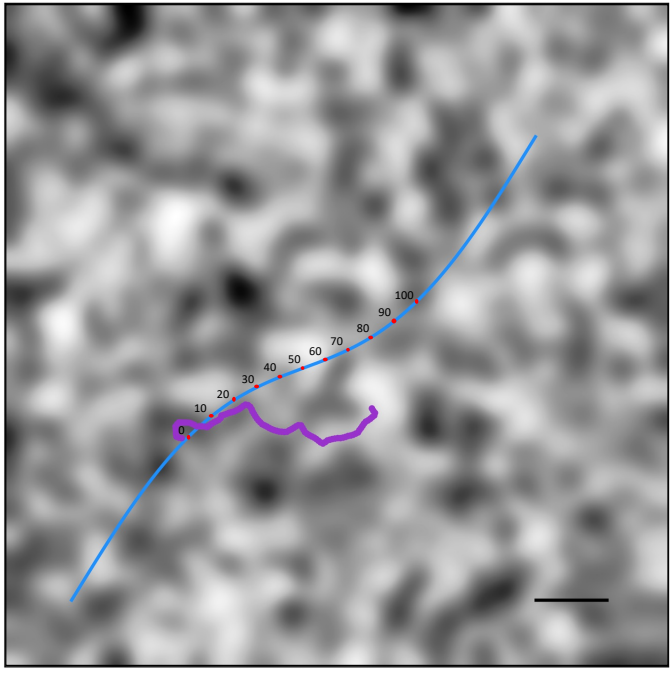


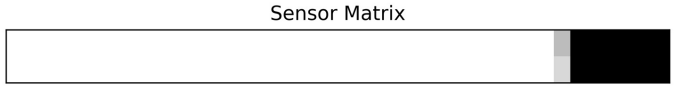


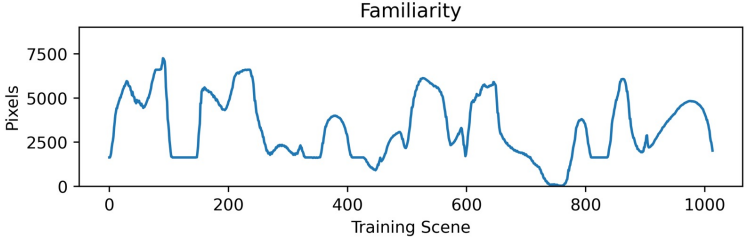
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

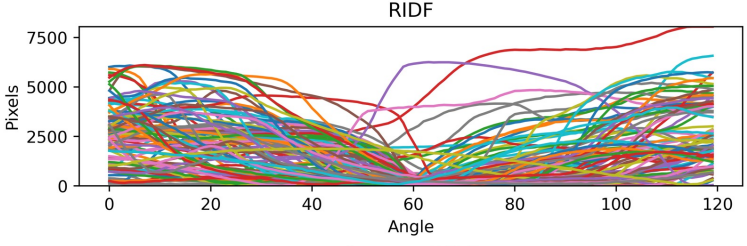
Navigation stats: RMSD error: 1743.96; RMSD/dist: 4.360; TD: 1655; p90: 58; p50: 30; complete: 0

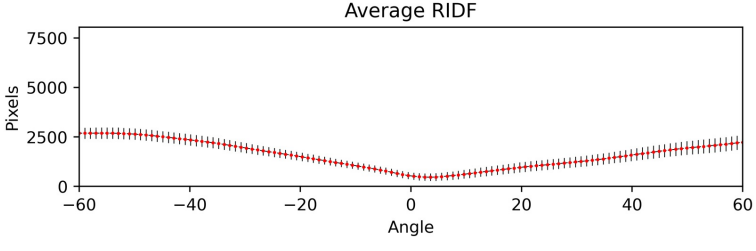
0%







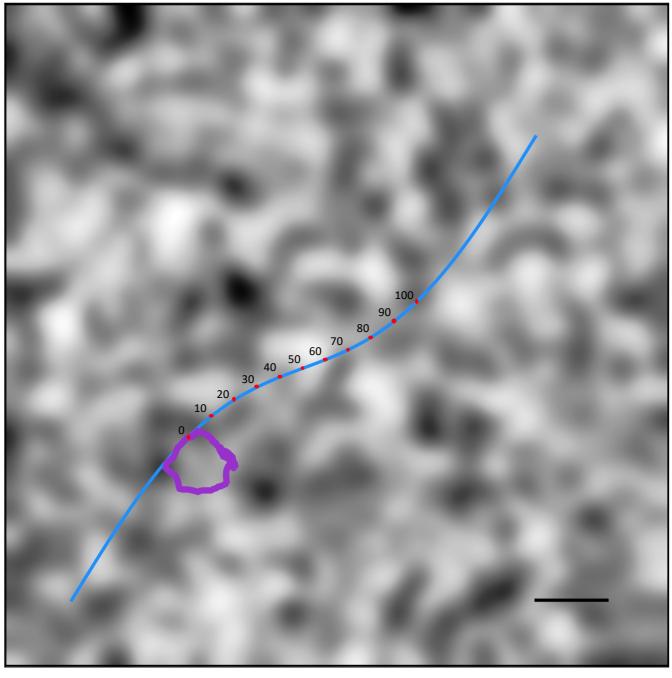


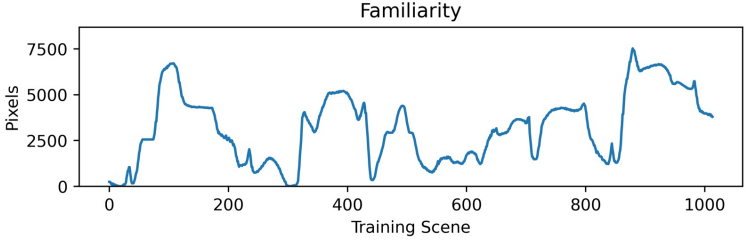


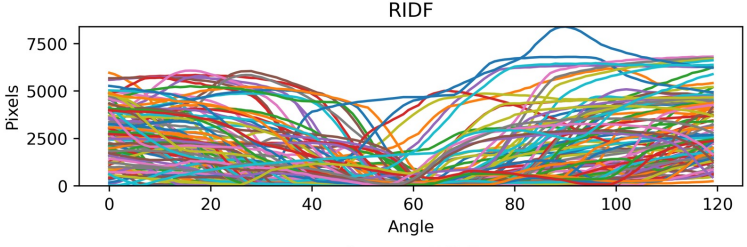
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

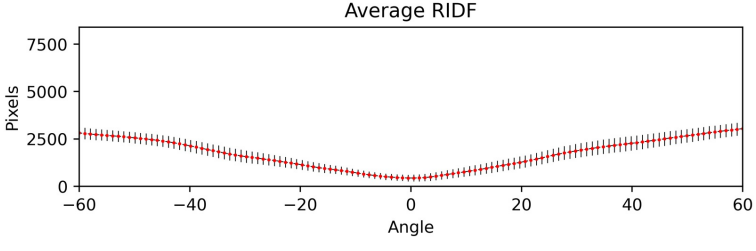
Navigation stats: RMSD error: 6036.16; RMSD/dist: 15.090; TD: 2242; p90: 88; p50: 44; complete: 0

0%





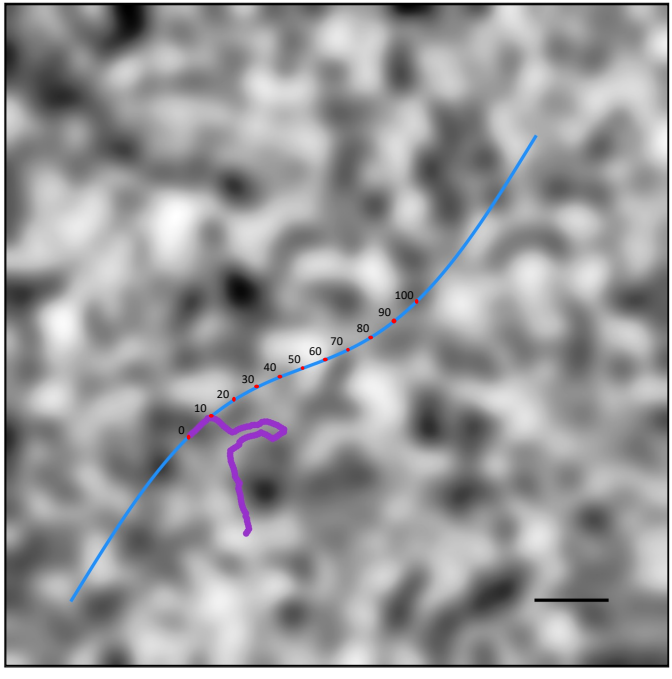


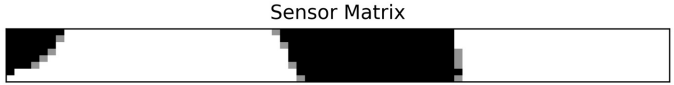


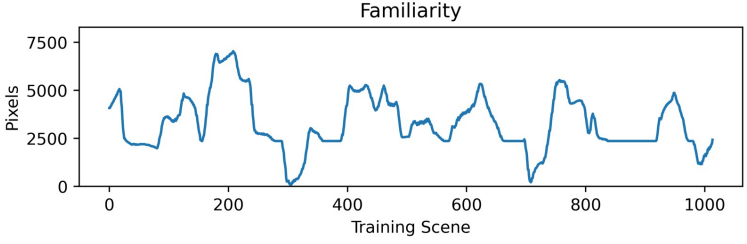
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

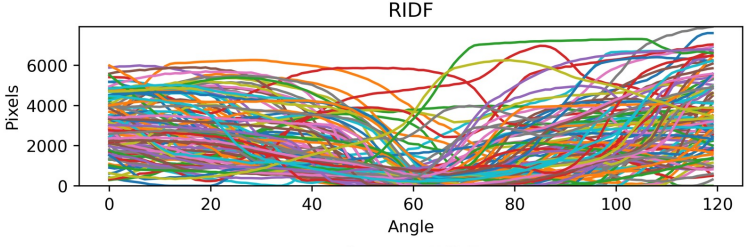
Navigation stats: RMSD error: 3941.33; RMSD/dist: 9.853; TD: 2918; p90: 120; p50: 72; complete: 0

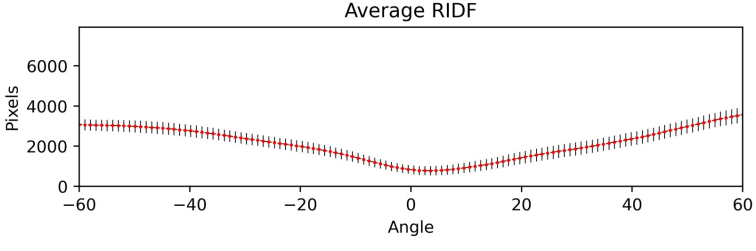
10%







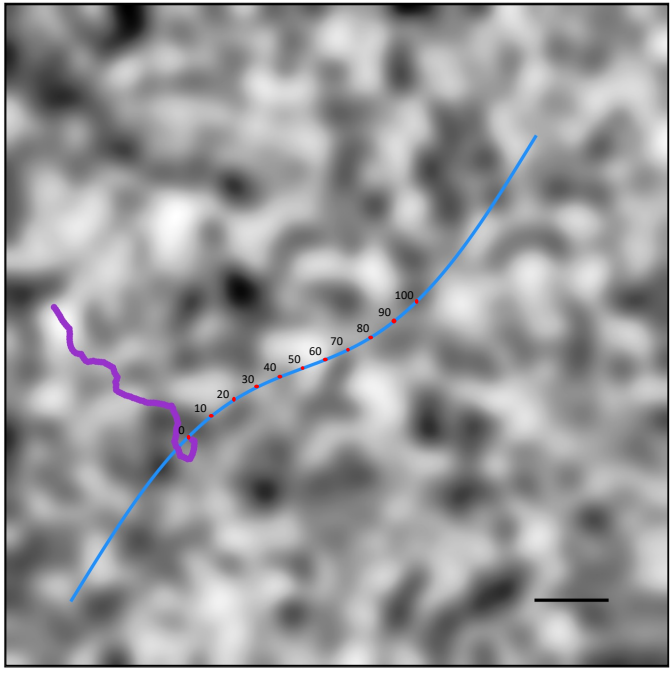


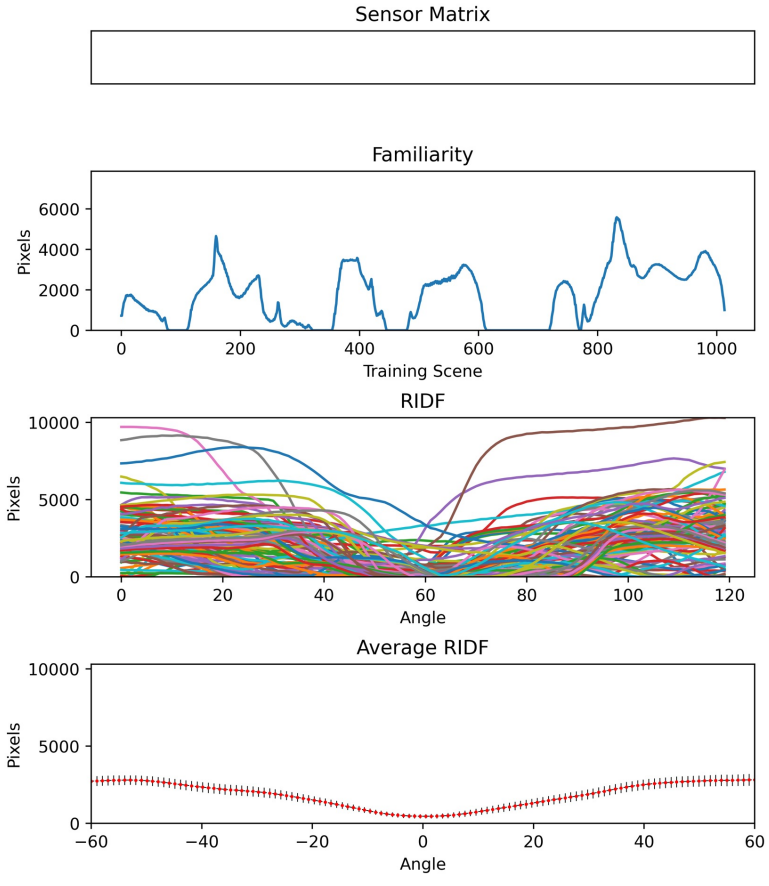


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 6730.57; RMSD/dist: 16.826; TD: 1931; p90: 66; p50: 30; complete: 0

0%





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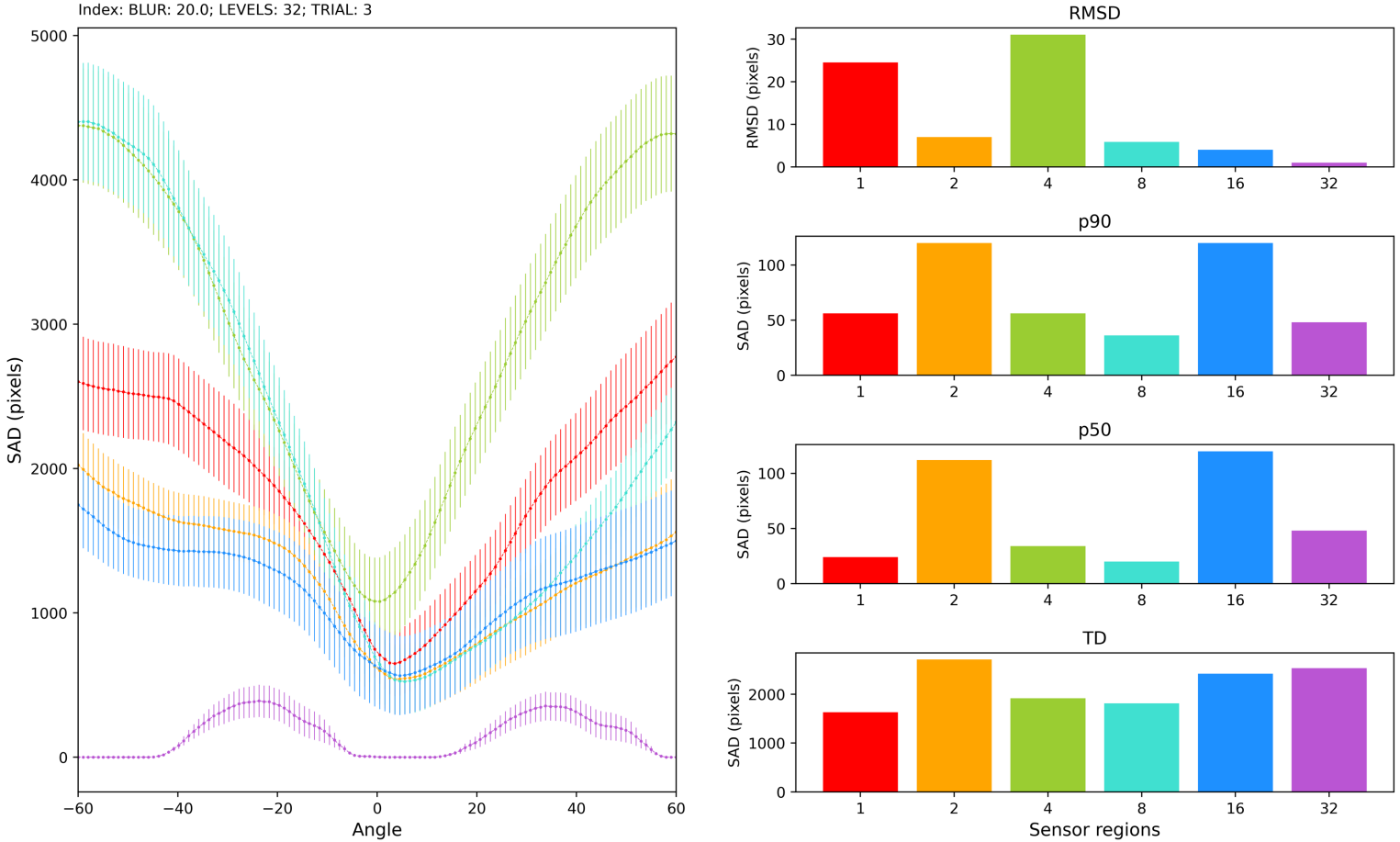
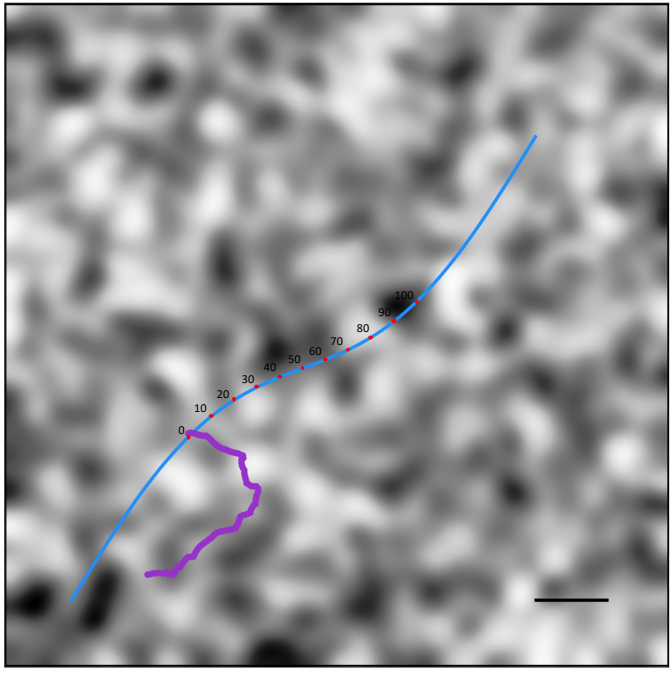
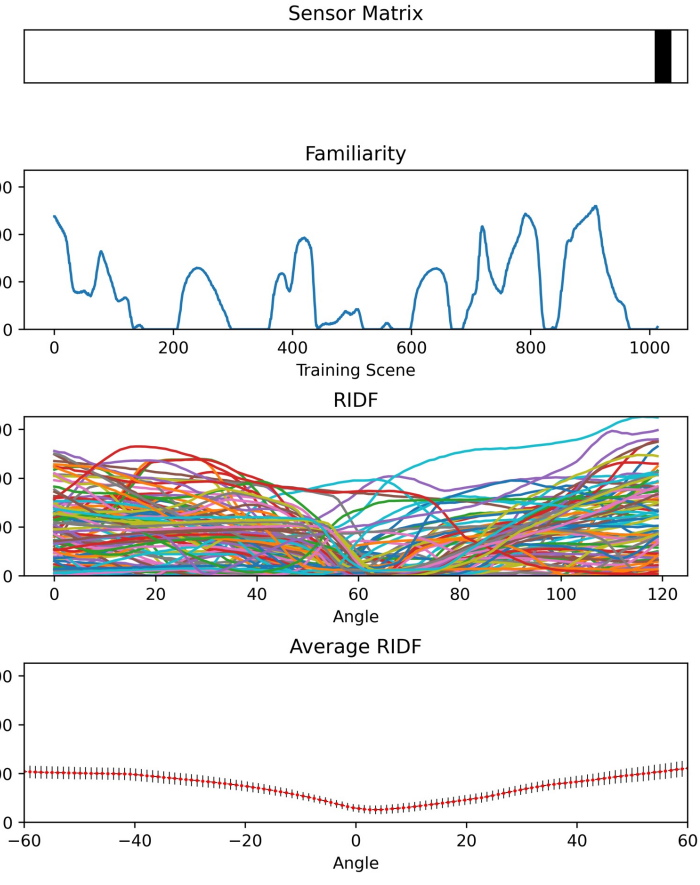
Navigation stats: RMSD error: 11798.77; RMSD/dist: 29.497; TD: 2008; p90: 76; p50: 40; complete: 0


Index: BLUR: 20.0; LEVELS: 32; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

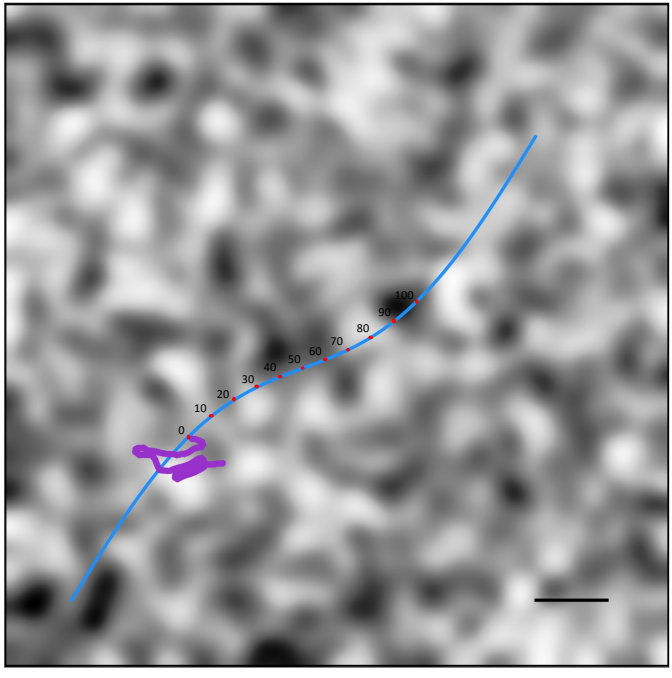


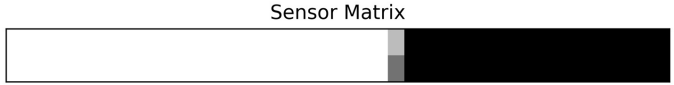


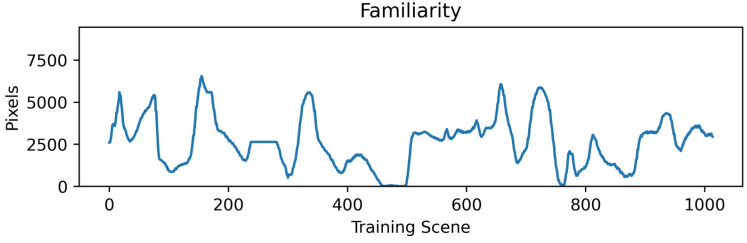
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

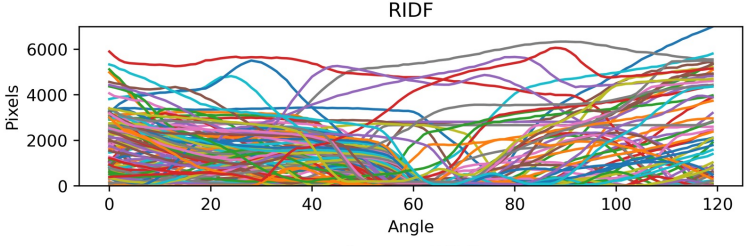
Navigation stats: RMSD error: 9810.74; RMSD/dist: 24.527; TD: 1632; p90: 56; p50: 24; complete: 0

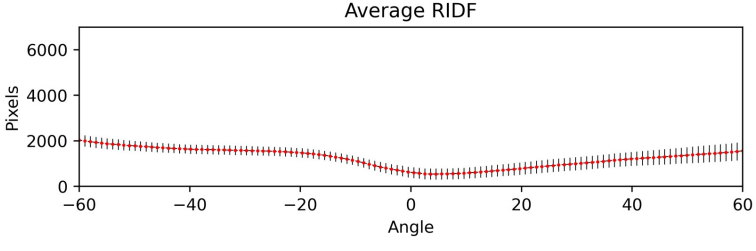
0%







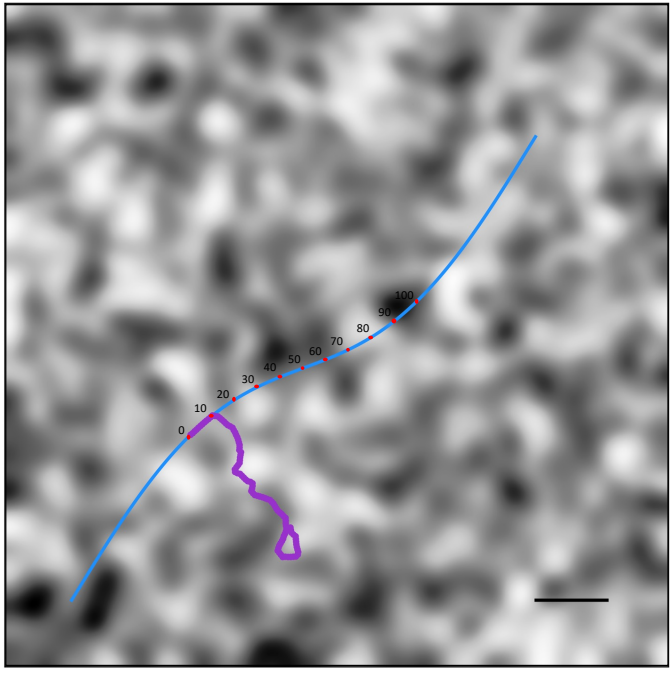


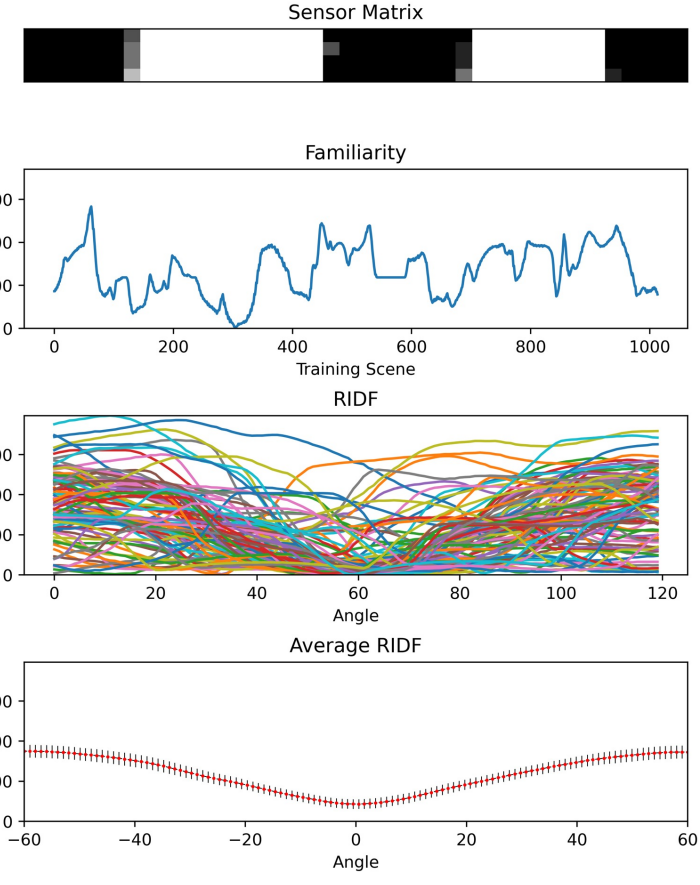


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2803.96; RMSD/dist: 7.010; TD: 2710; p90: 120; p50: 112; complete: 0

10%

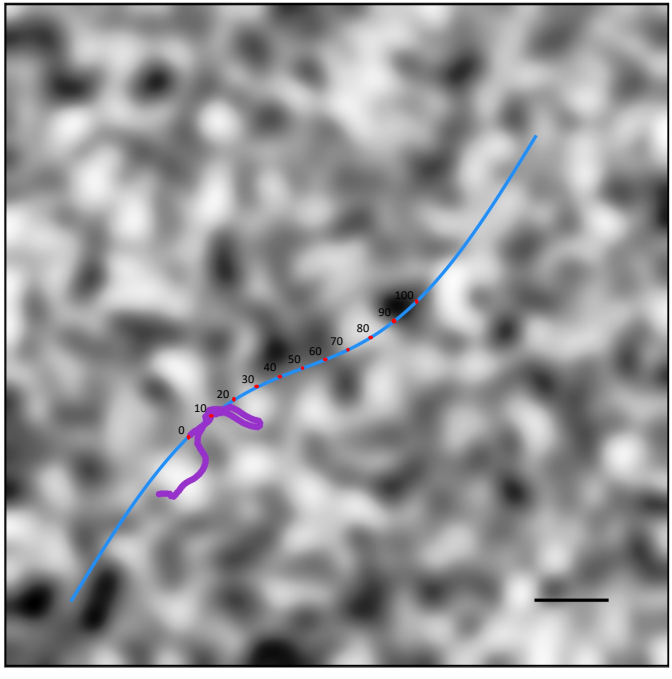


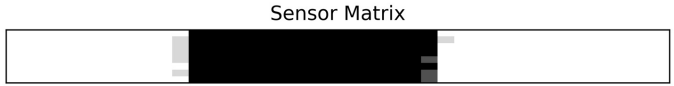


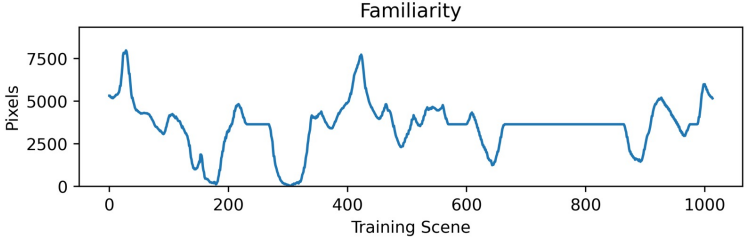
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

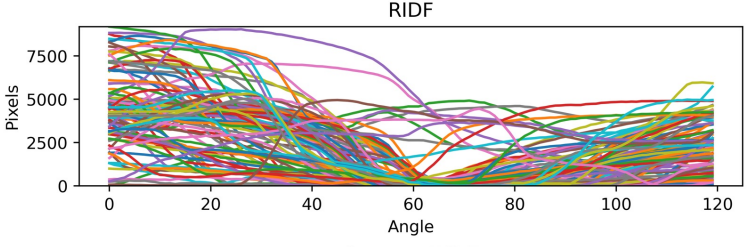
Navigation stats: RMSD error: 12435.89; RMSD/dist: 31.090; TD: 1917; p90: 56; p50: 34; complete: 0

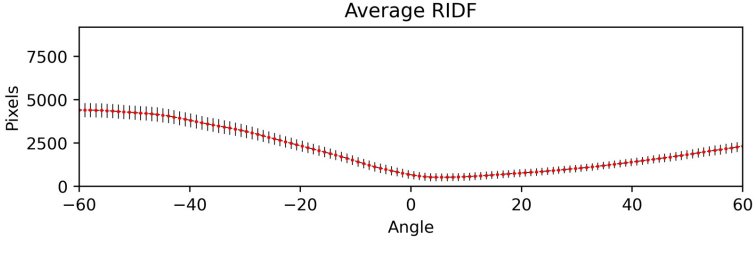
10%







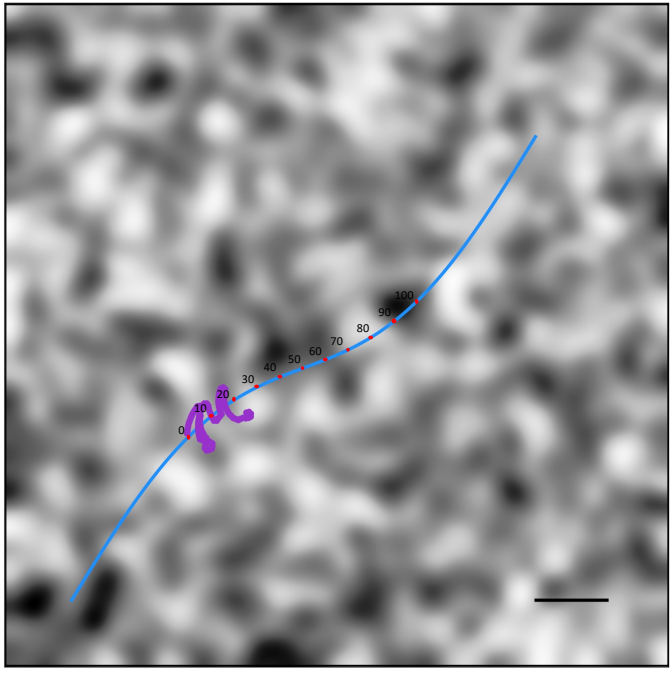


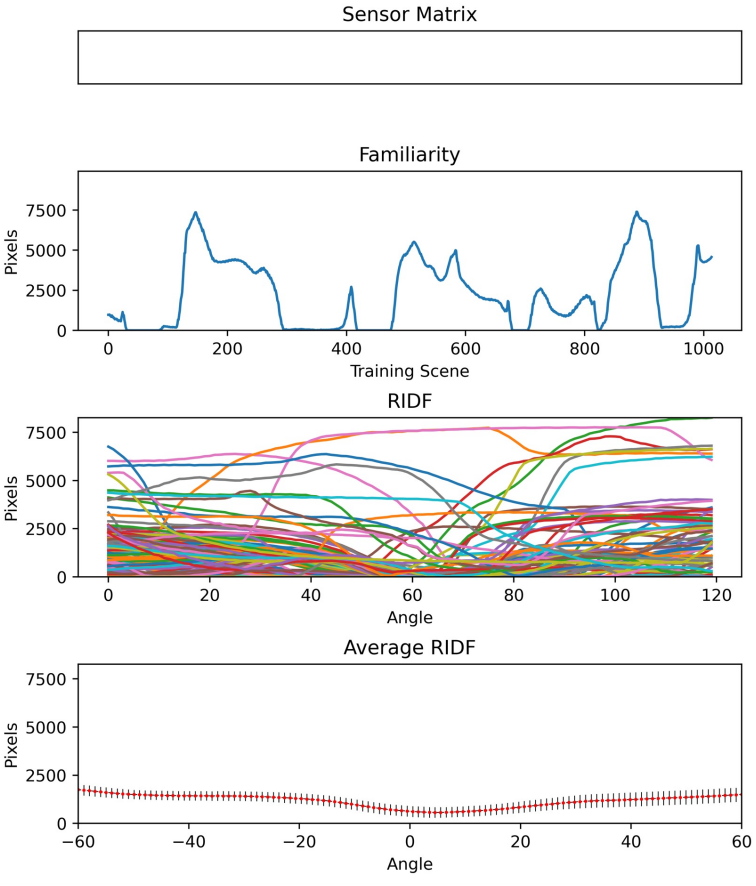


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2338.24; RMSD/dist: 5.846; TD: 1814; p90: 36; p50: 20; complete: 0

0%

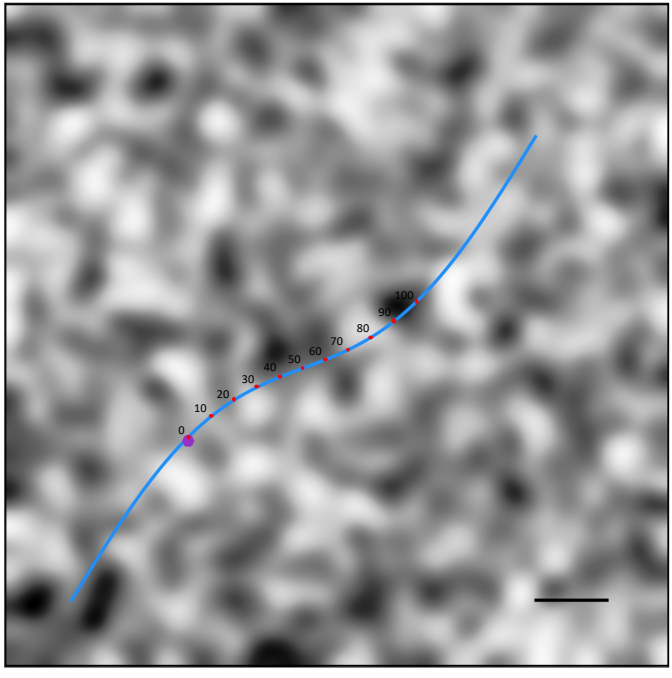


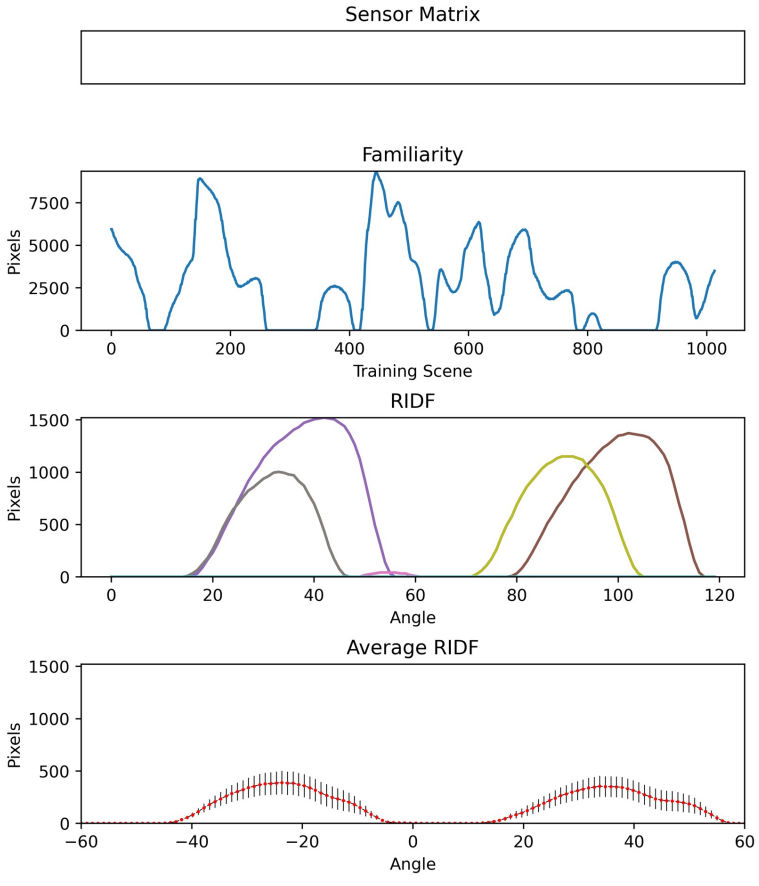


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1609.40; RMSD/dist: 4.024; TD: 2421; p90: 120; p50: 120; complete: 0

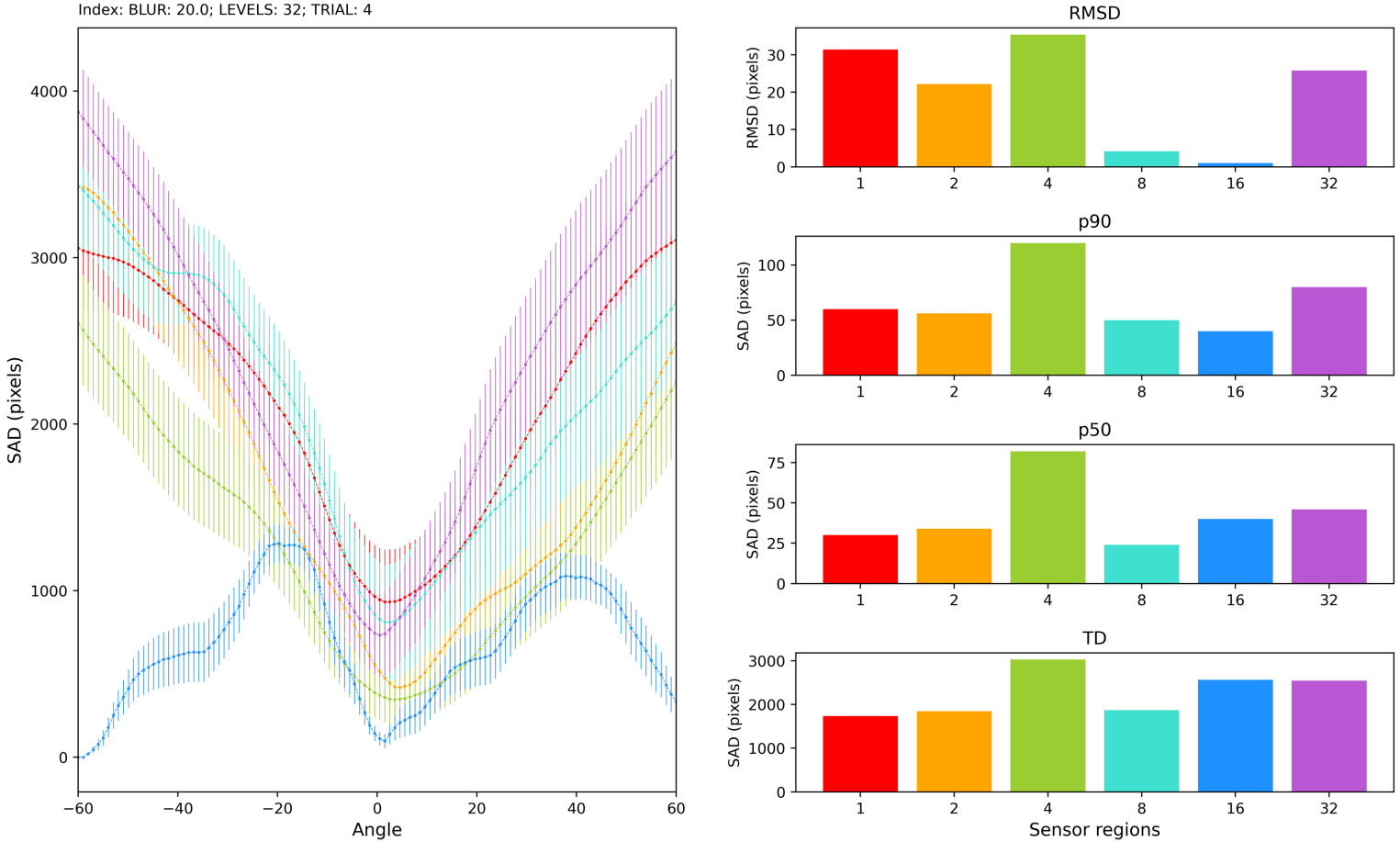
0%



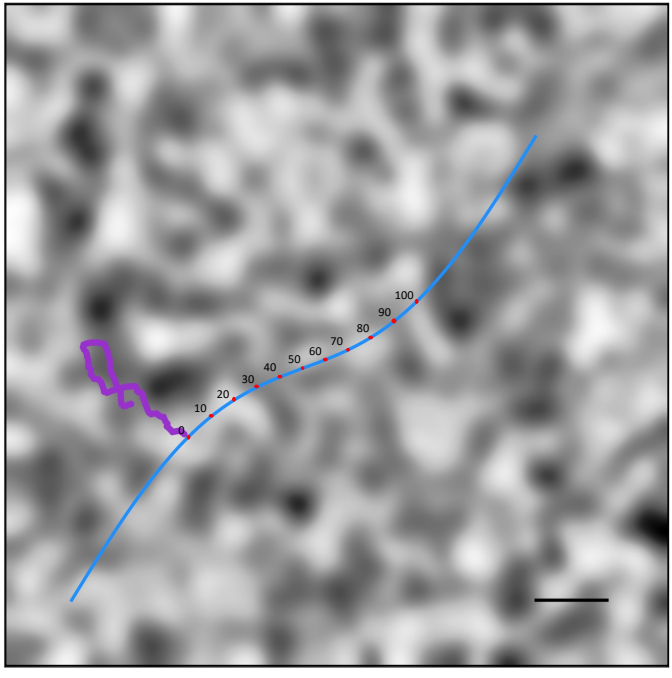


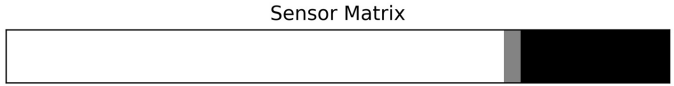
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

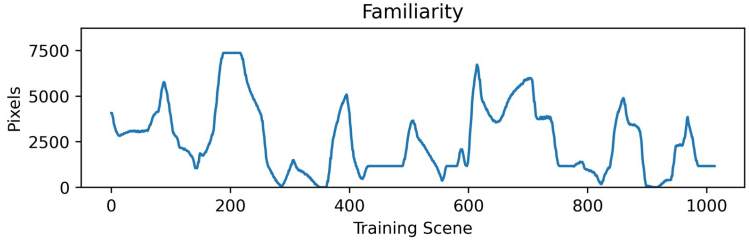
Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 2536; p90: 48; p50: 48; complete: 0

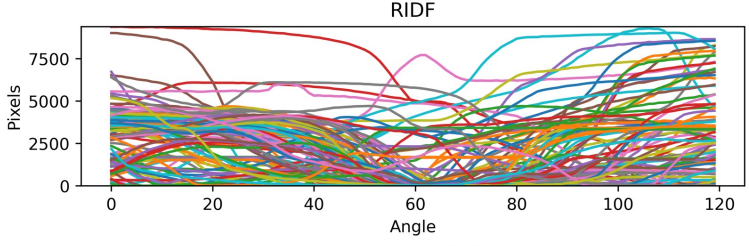

Index: BLUR: 20.0; LEVELS: 32; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

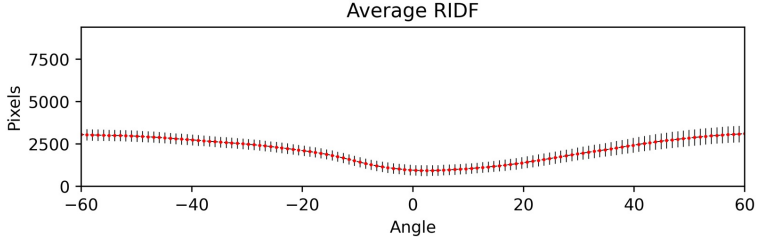
0%







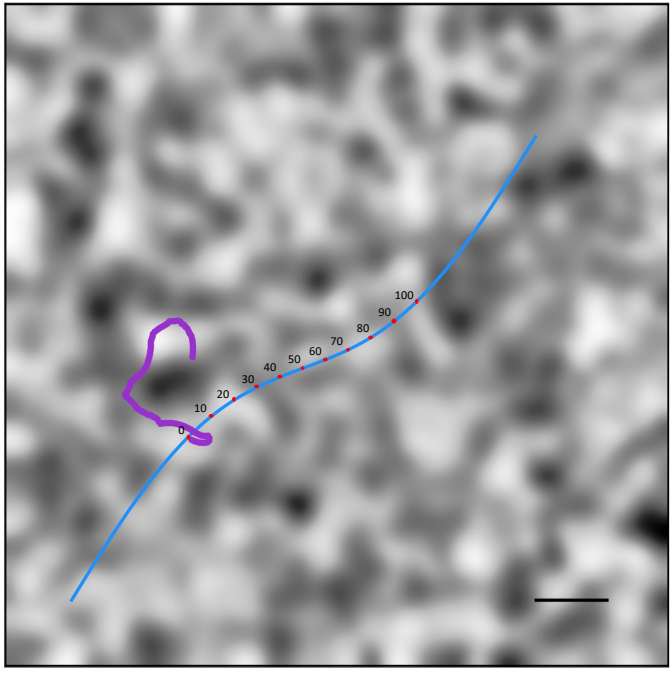


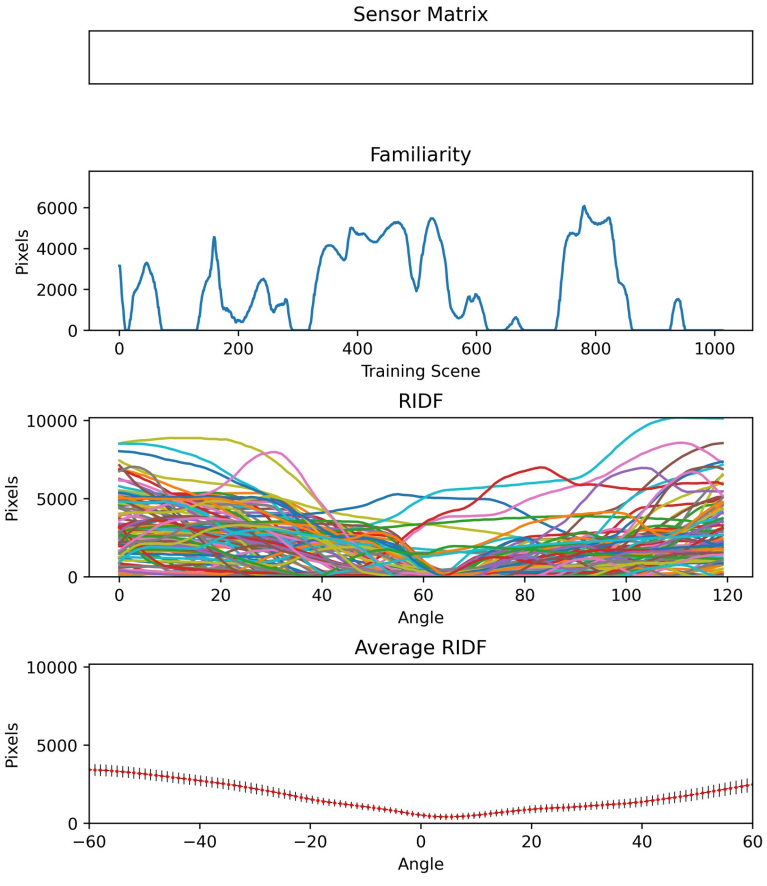


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 12557.48; RMSD/dist: 31.394; TD: 1736; p90: 60; p50: 30; complete: 0

0%

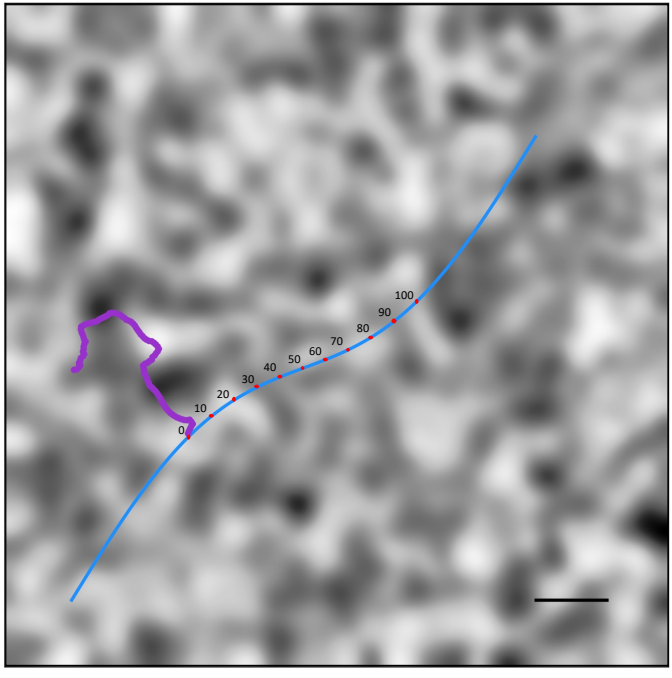


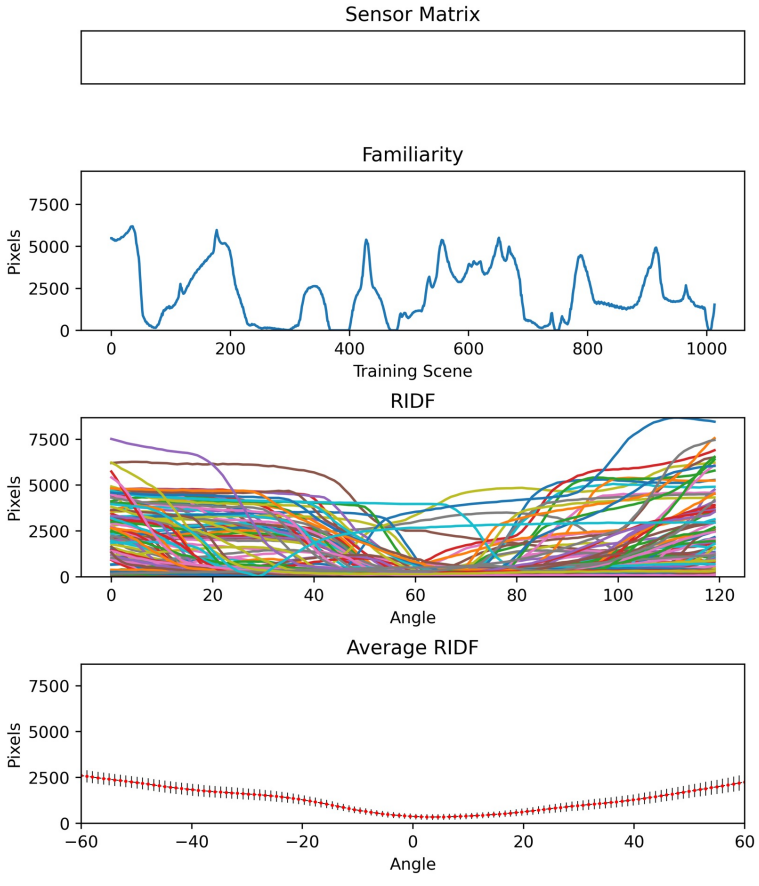


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 8859.90; RMSD/dist: 22.150; TD: 1844; p90: 56; p50: 34; complete: 0

0%

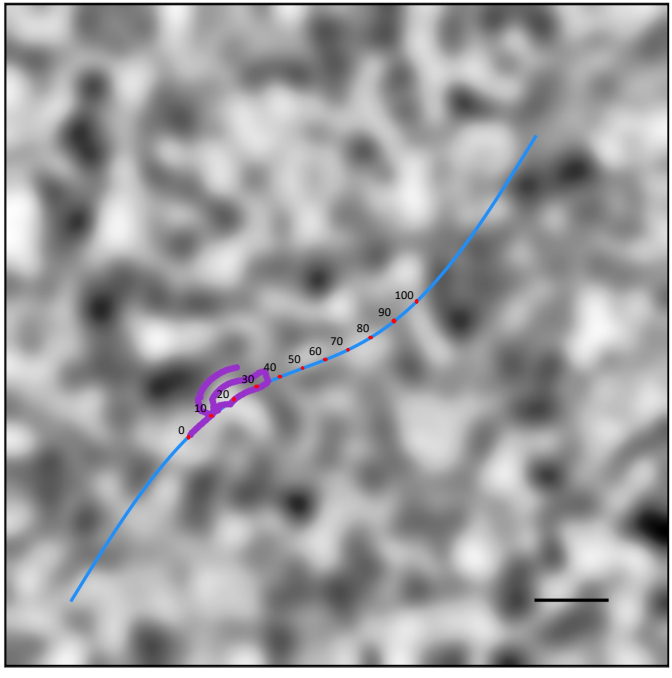


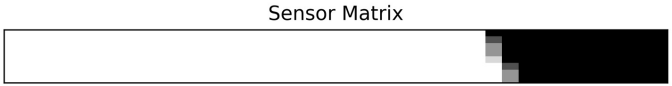


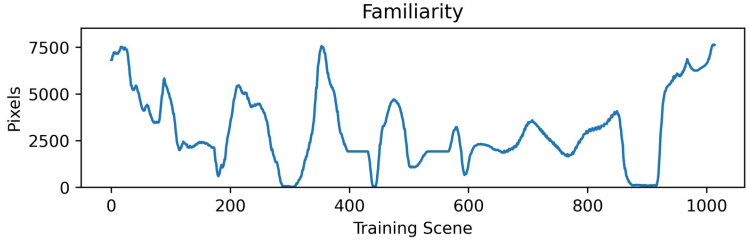
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

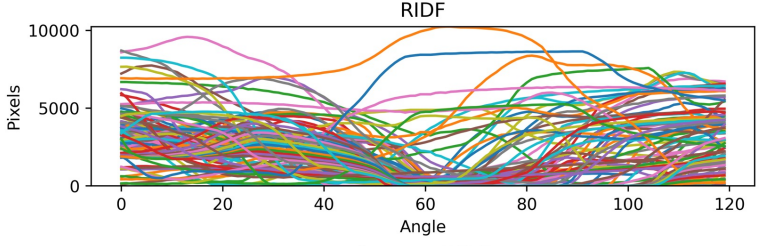
Navigation stats: RMSD error: 14156.18; RMSD/dist: 35.390; TD: 3026; p90: 120; p50: 82; complete: 0

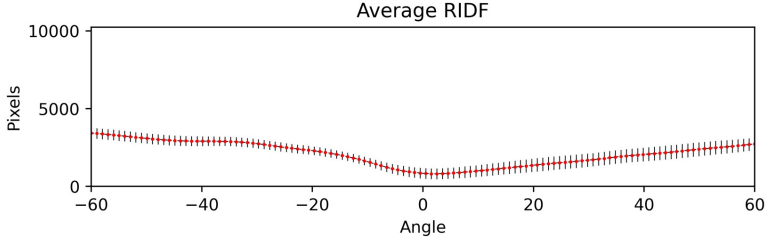
20%







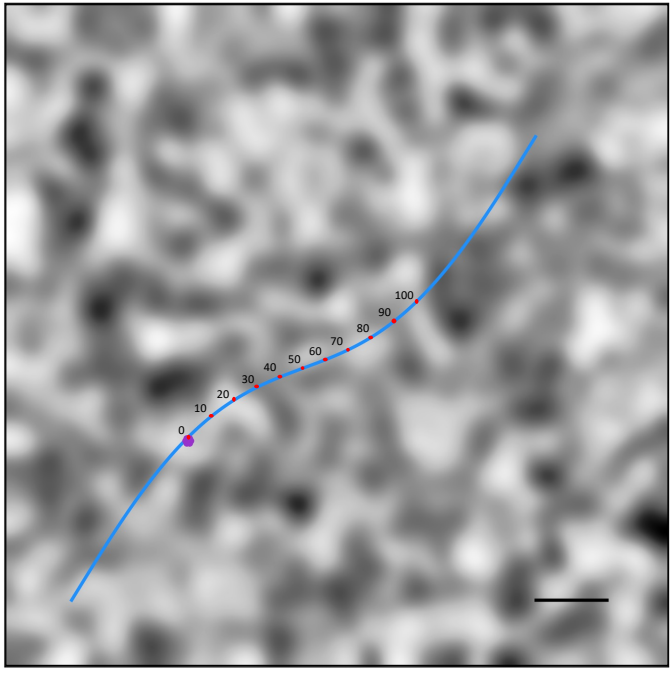


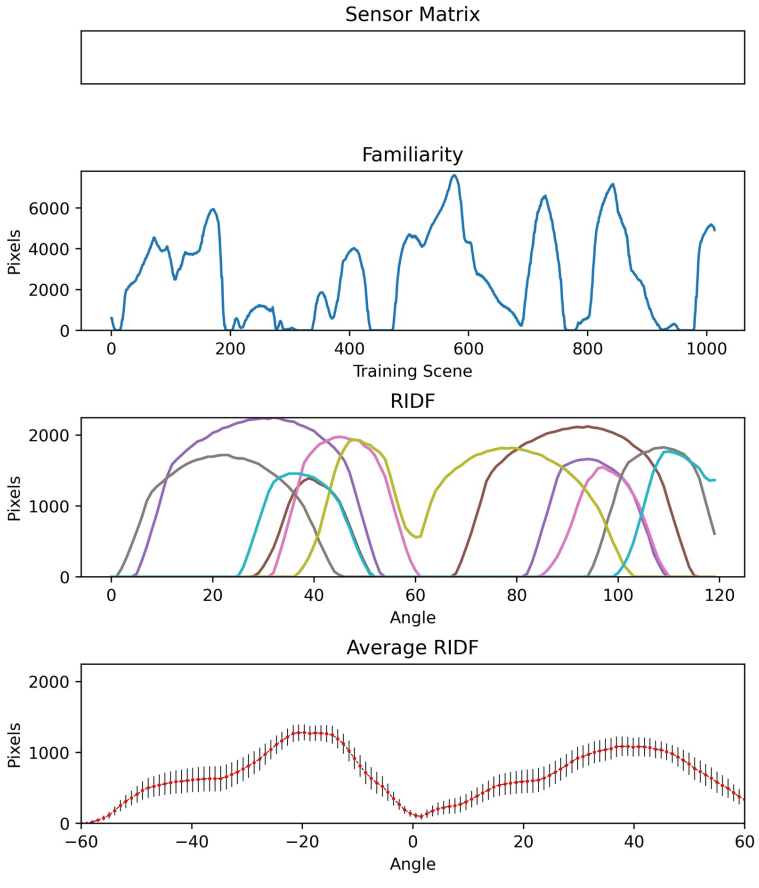


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1669.39; RMSD/dist: 4.173; TD: 1872; p90: 50; p50: 24; complete: 0

0%

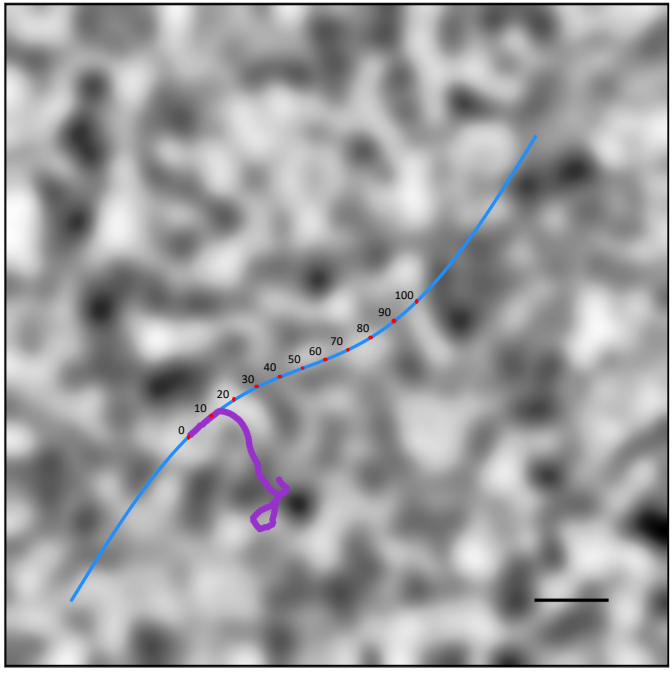


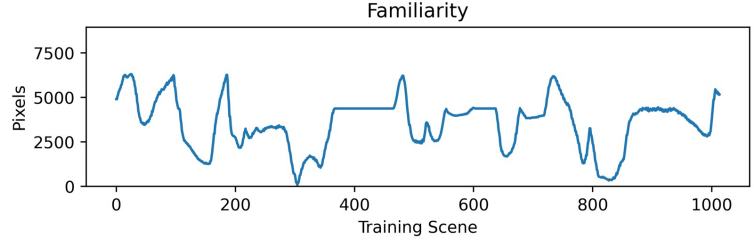


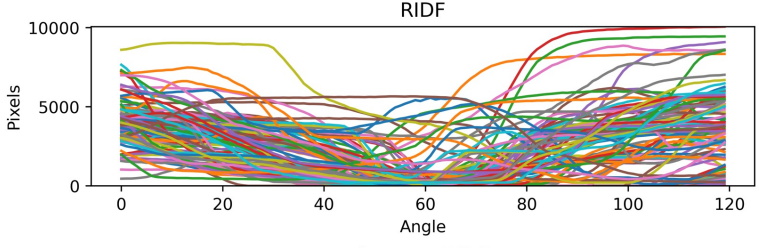
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

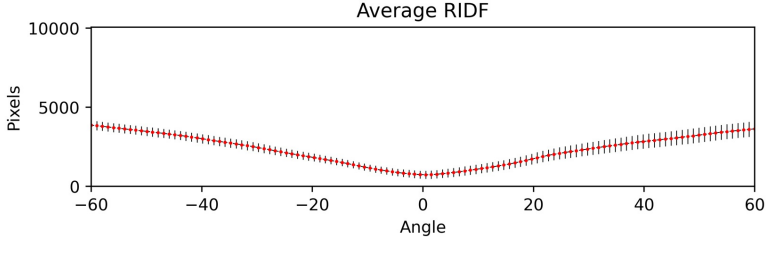
Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 2564; p90: 40; p50: 40; complete: 0

10%



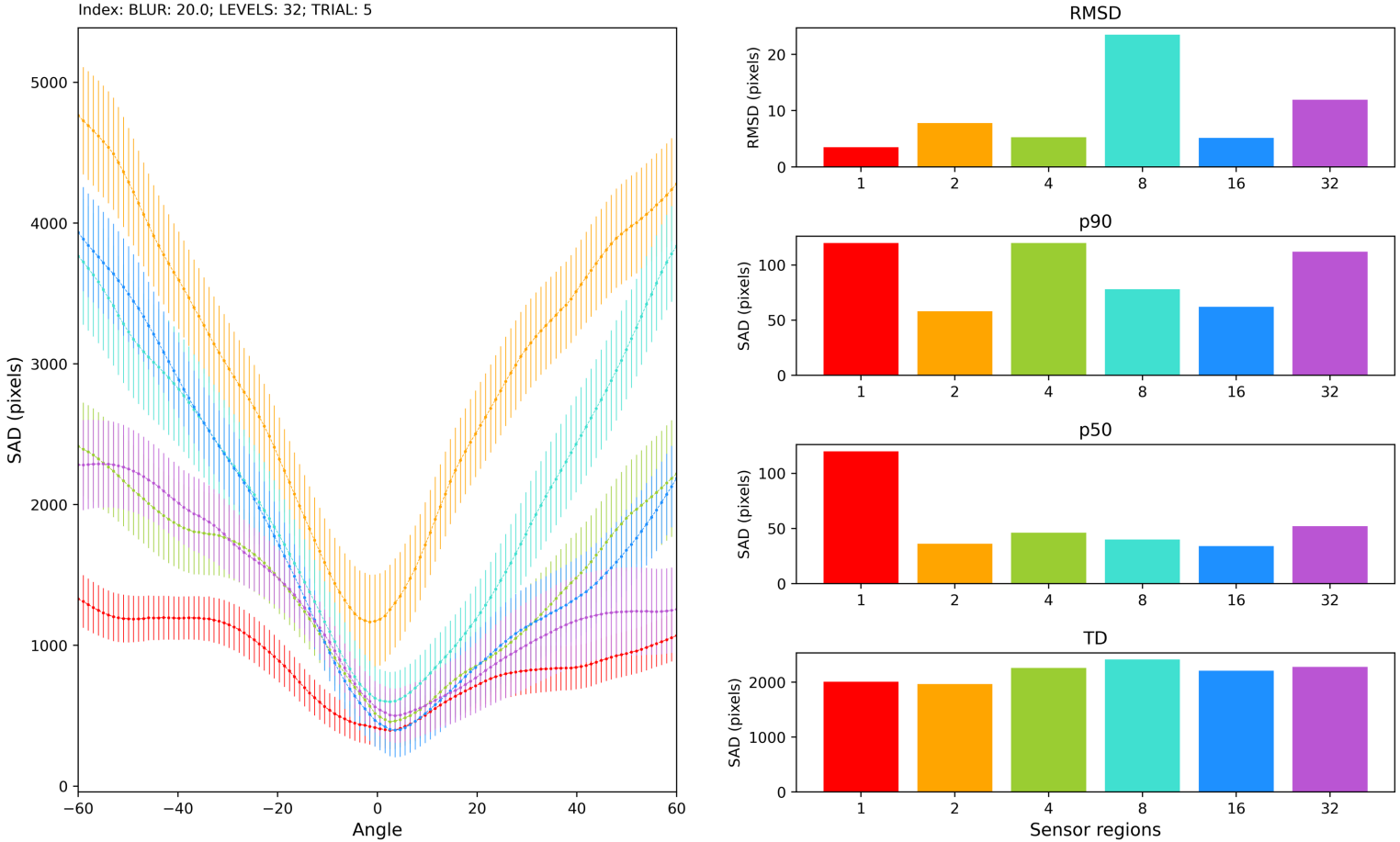




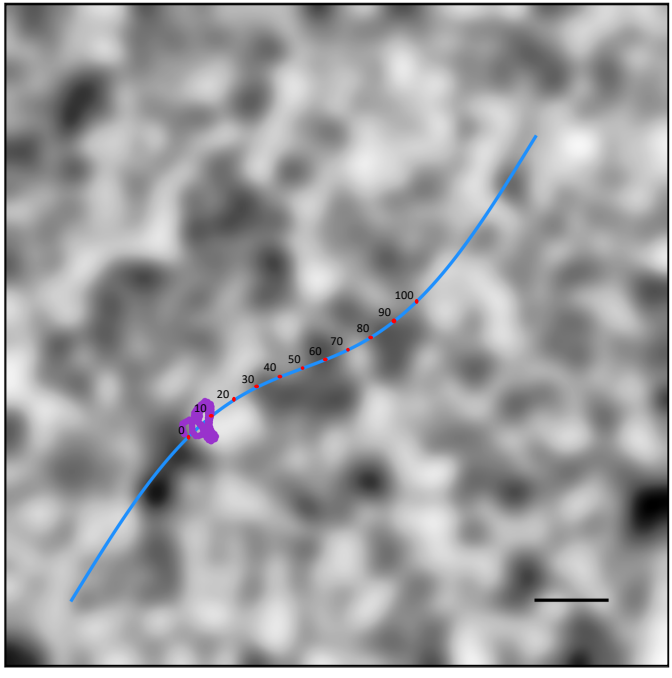


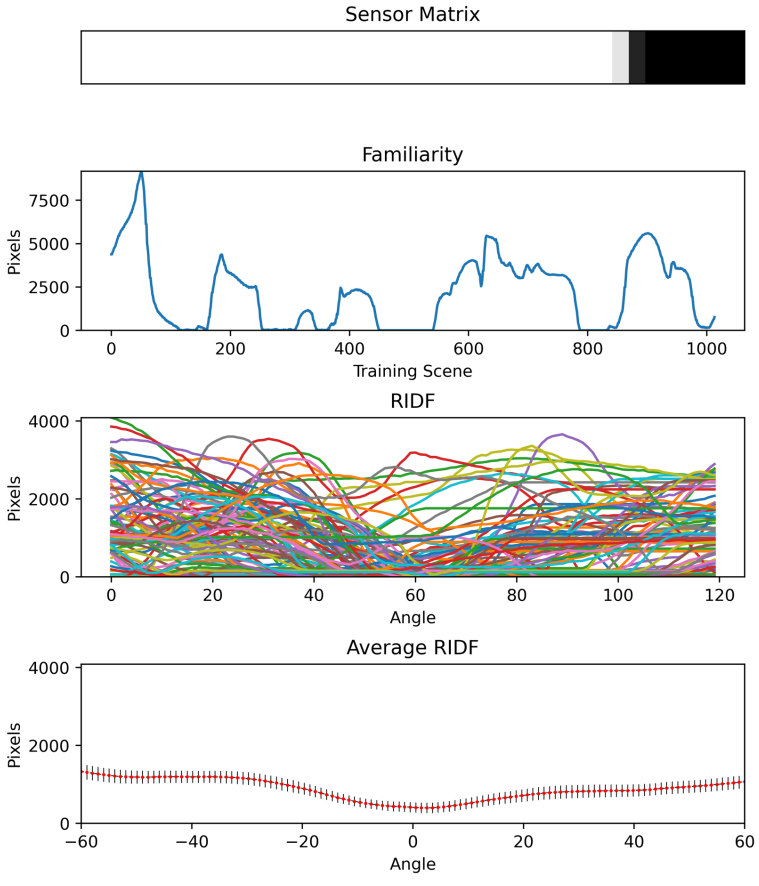
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 10311.85; RMSD/dist: 25.780; TD: 2543; p90: 80; p50: 46; complete: 0


Index: BLUR: 20.0; LEVELS: 32; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

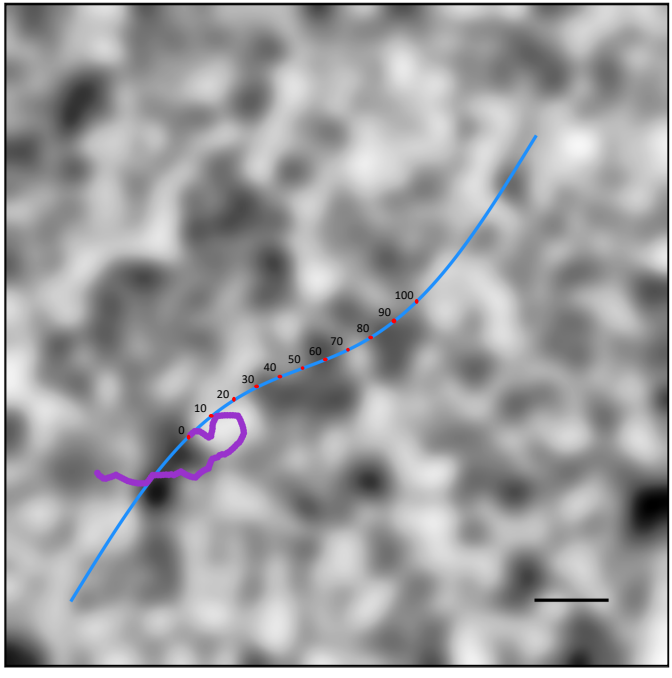


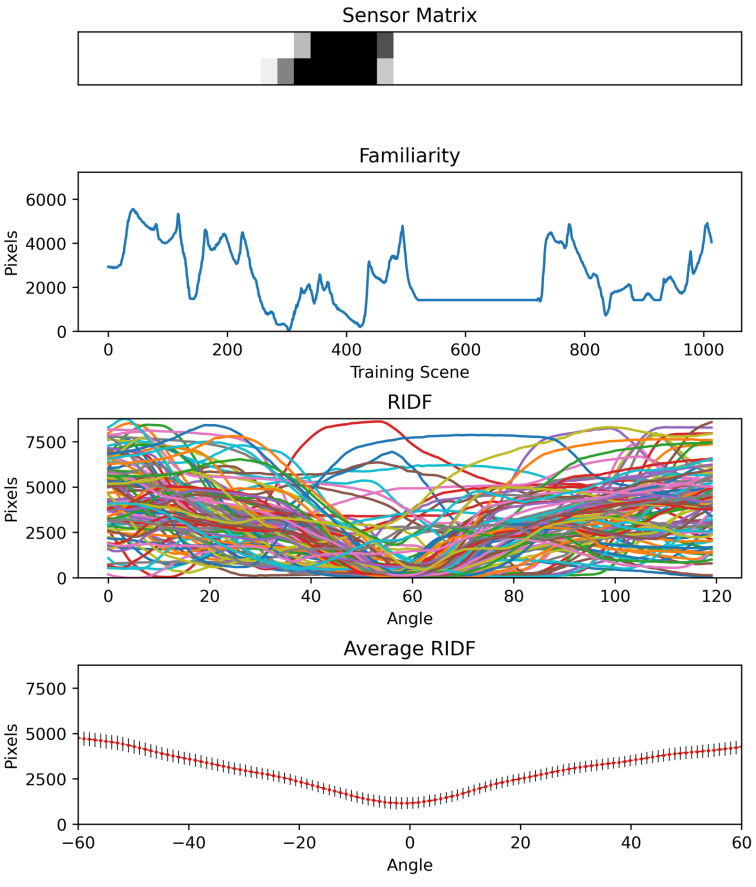


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1400.88; RMSD/dist: 3.502; TD: 2010; p90: 120; p50: 120; complete: 0

0%

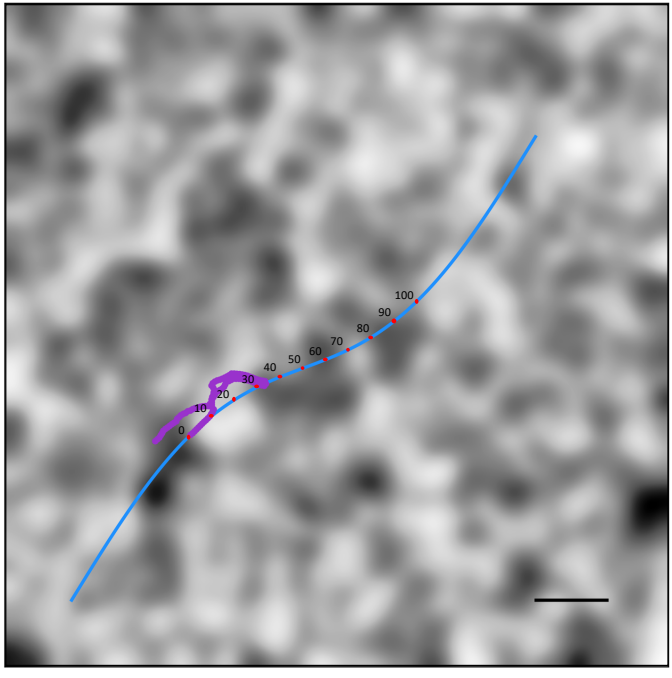


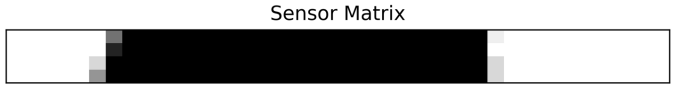


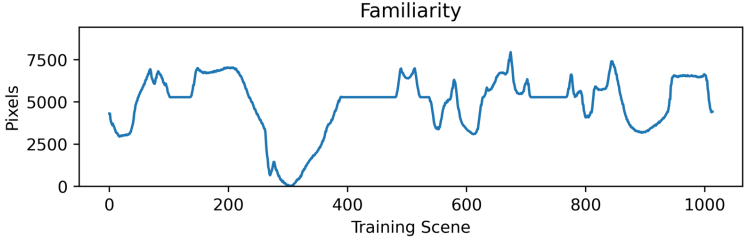
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

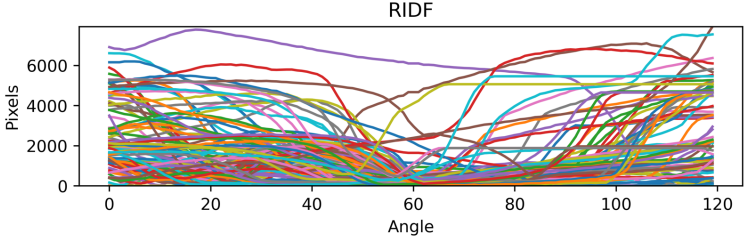
Navigation stats: RMSD error: 3114.51; RMSD/dist: 7.786; TD: 1965; p90: 58; p50: 36; complete: 0

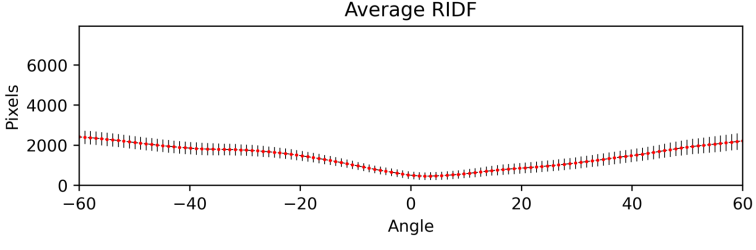
10%







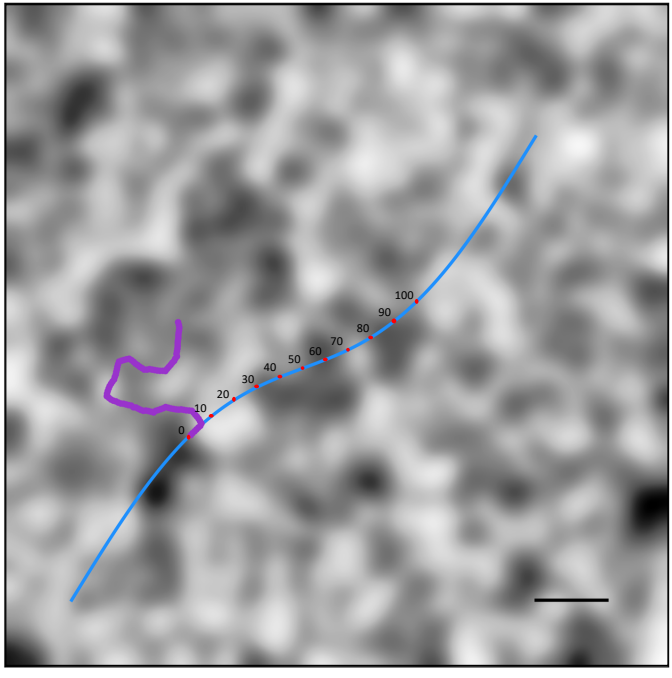


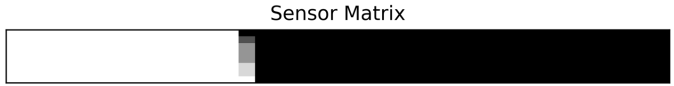


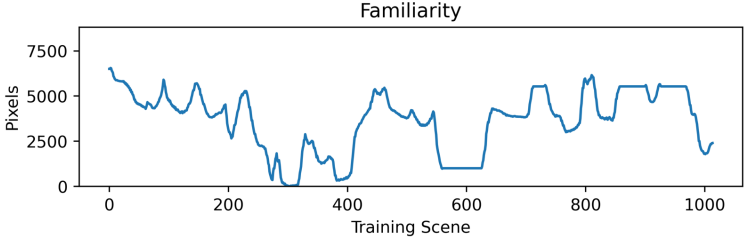
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

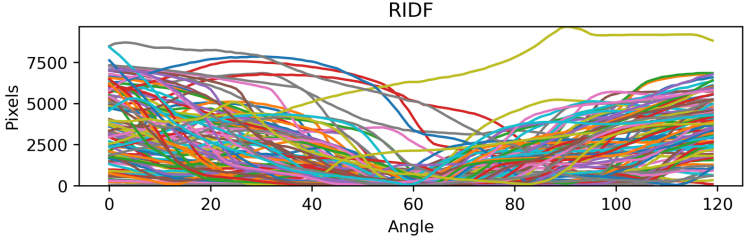
Navigation stats: RMSD error: 2103.10; RMSD/dist: 5.258; TD: 2261; p90: 120; p50: 46; complete: 0

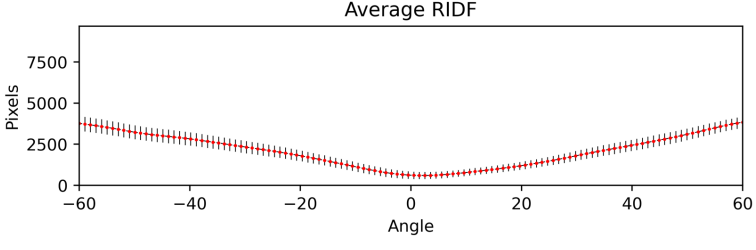
0%







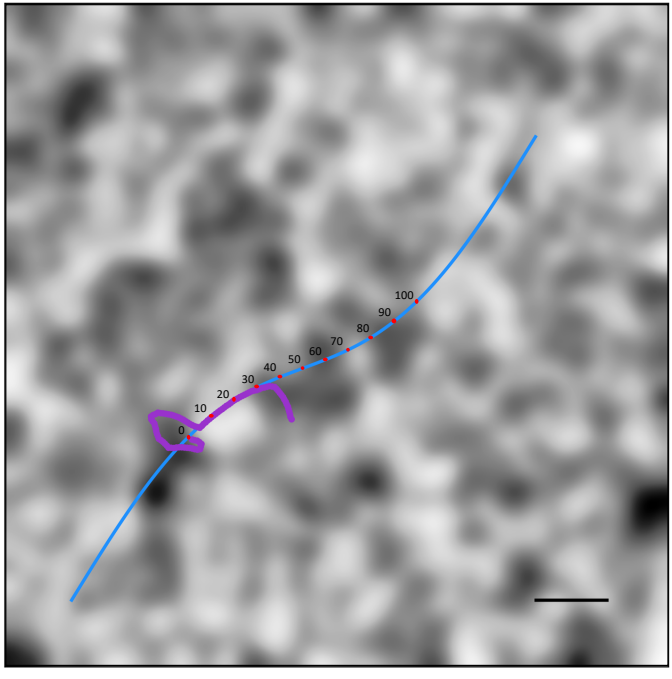


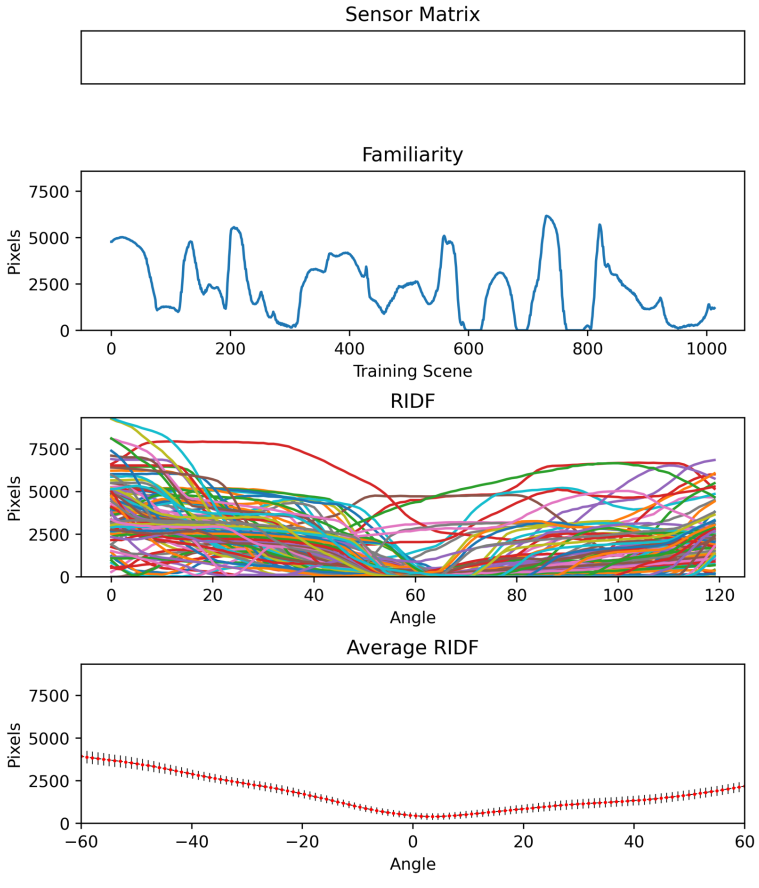


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 9403.29; RMSD/dist: 23.508; TD: 2412; p90: 78; p50: 40; complete: 0

20%

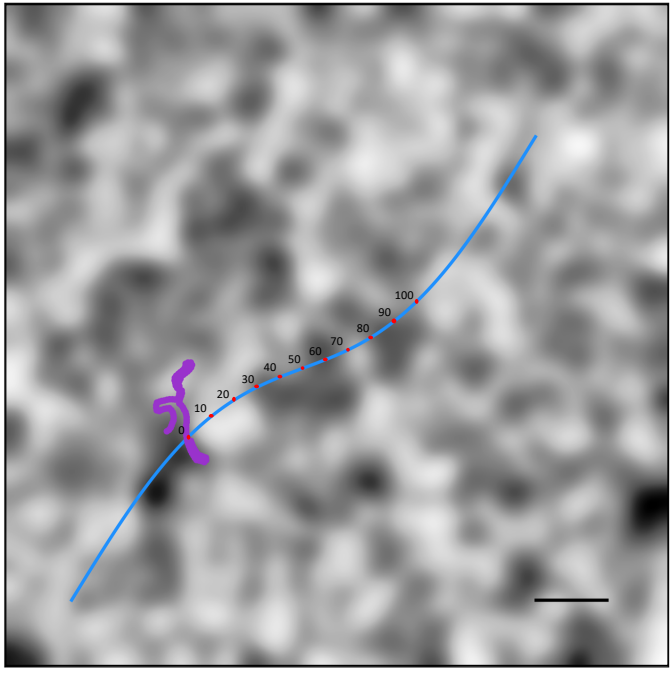


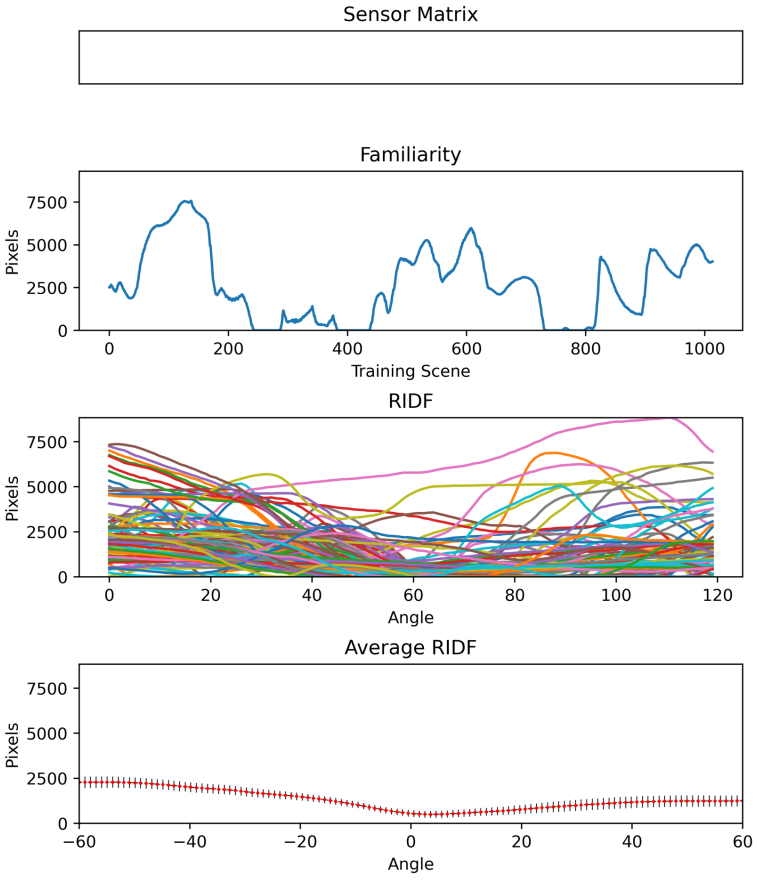


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2057.38; RMSD/dist: 5.143; TD: 2211; p90: 62; p50: 34; complete: 0

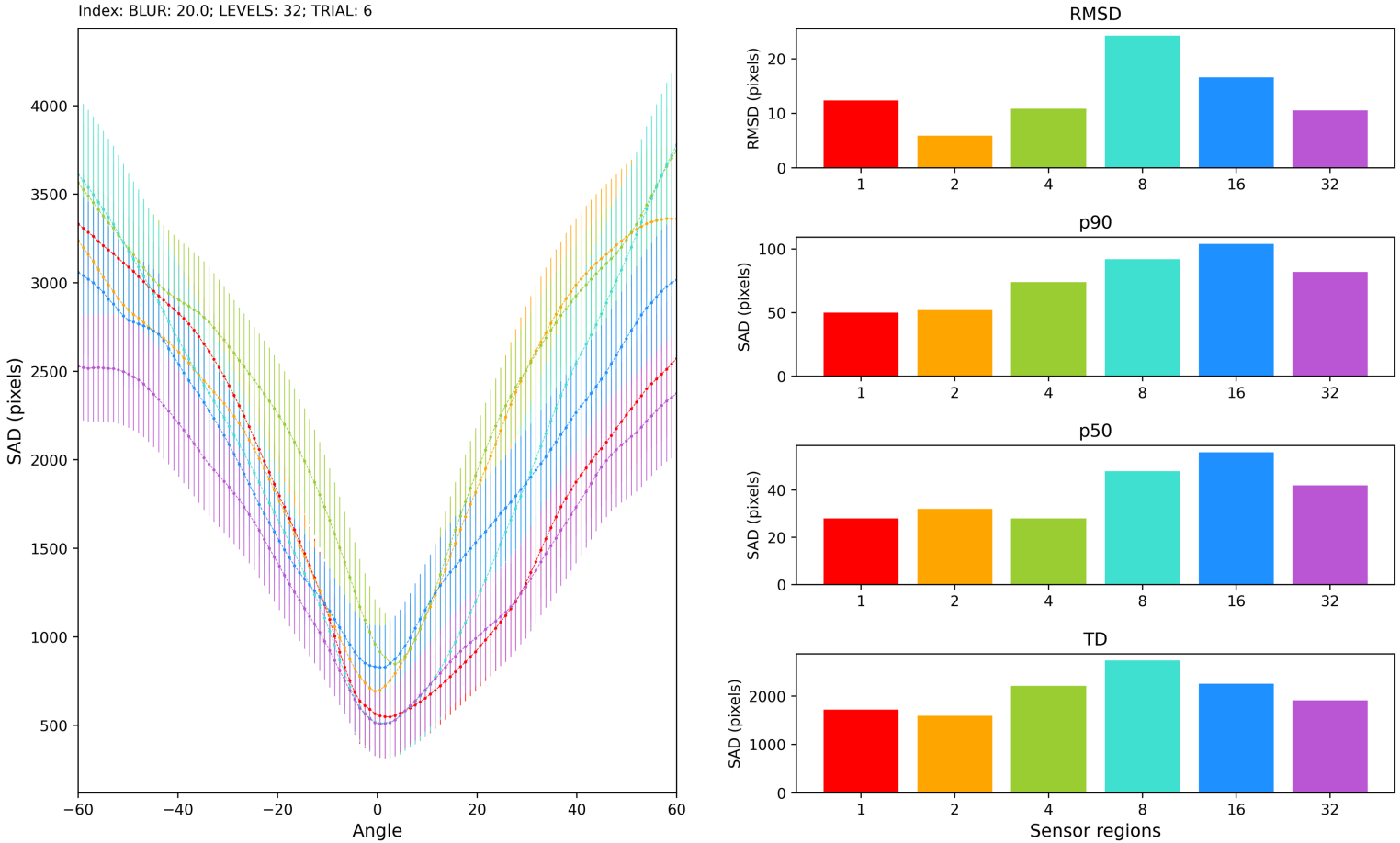
0%



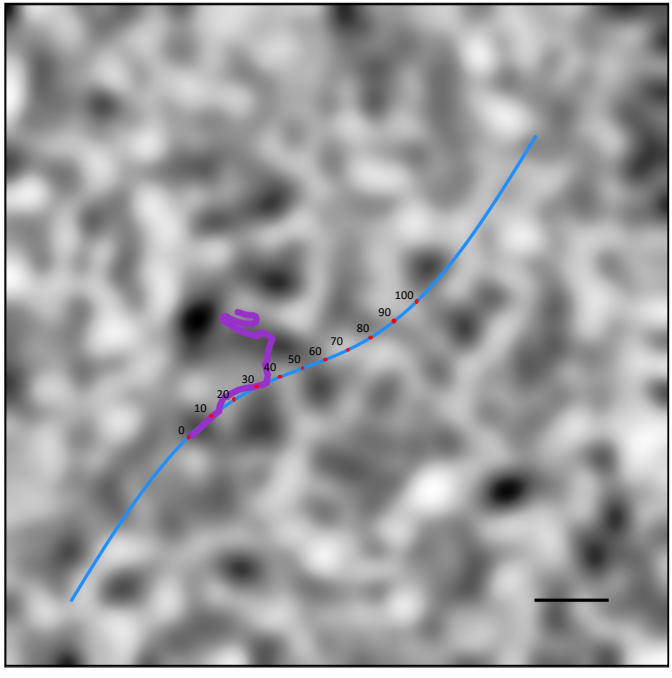


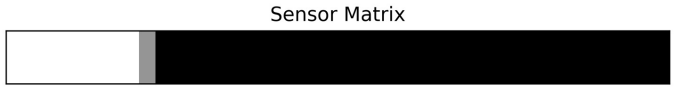
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

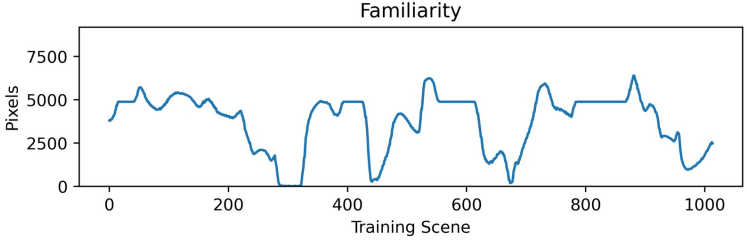
Navigation stats: RMSD error: 4764.89; RMSD/dist: 11.912; TD: 2280; p90: 112; p50: 52; complete: 0

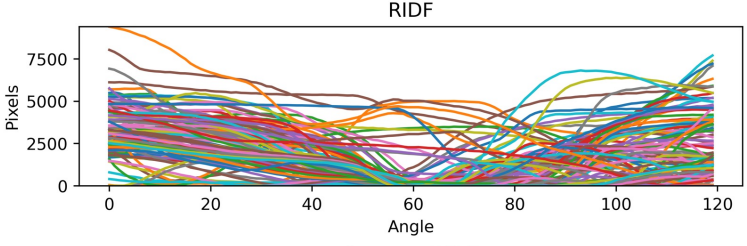

Index: BLUR: 20.0; LEVELS: 32; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

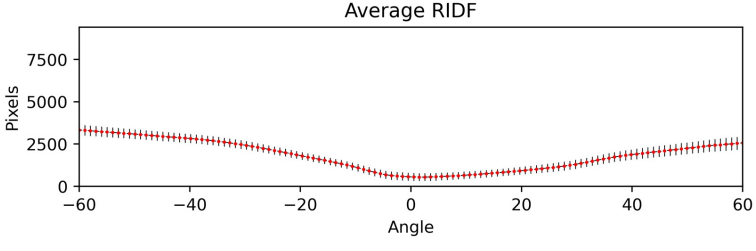
10%







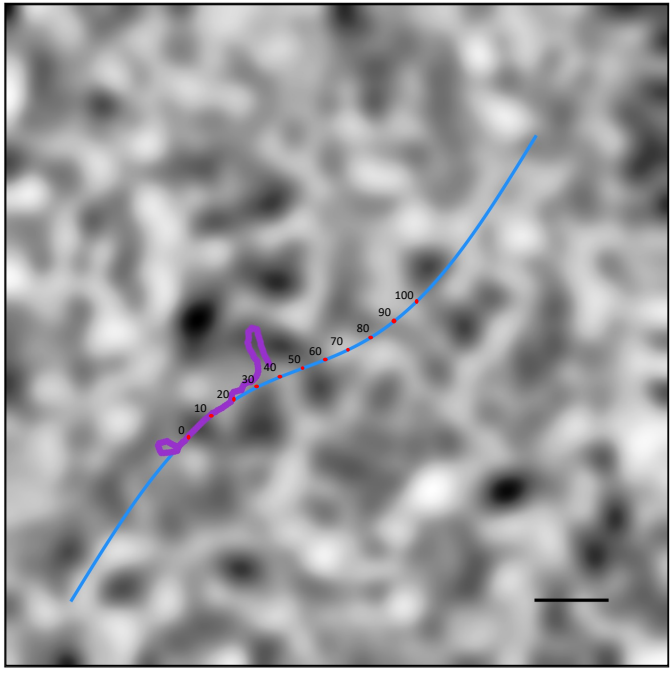


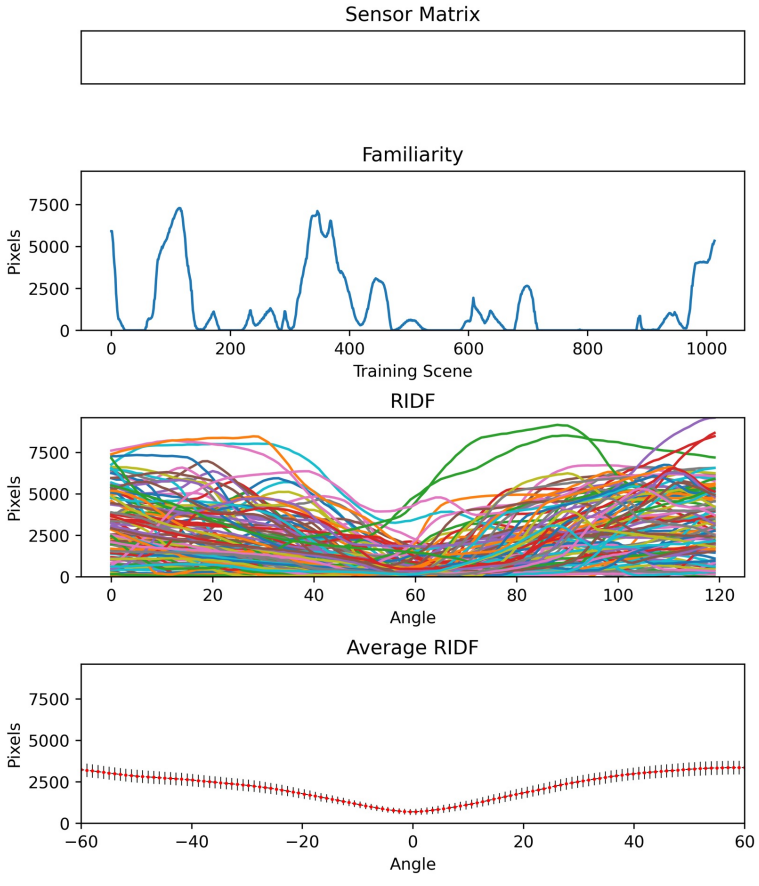


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4944.60; RMSD/dist: 12.361; TD: 1722; p90: 50; p50: 28; complete: 0

20%

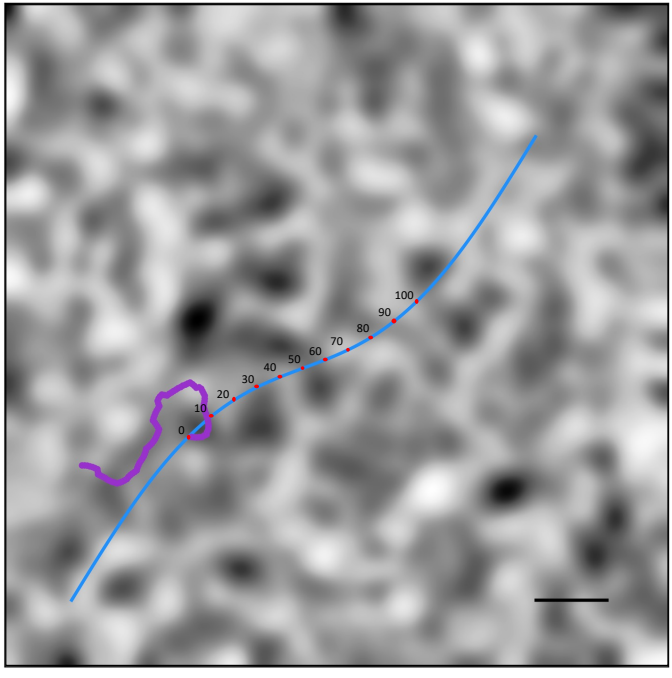


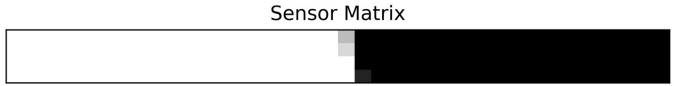


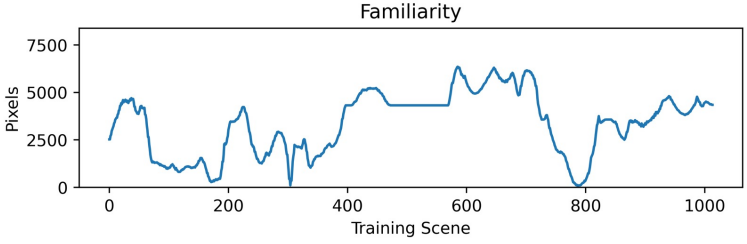
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

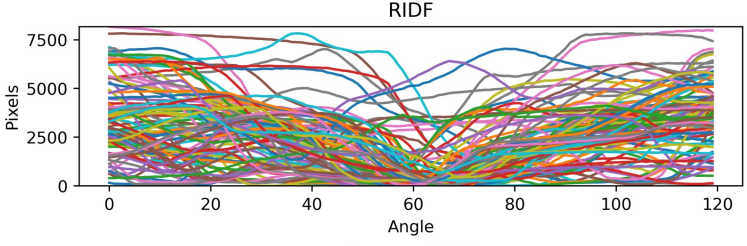
Navigation stats: RMSD error: 2357.74; RMSD/dist: 5.894; TD: 1594; p90: 52; p50: 32; complete: 0

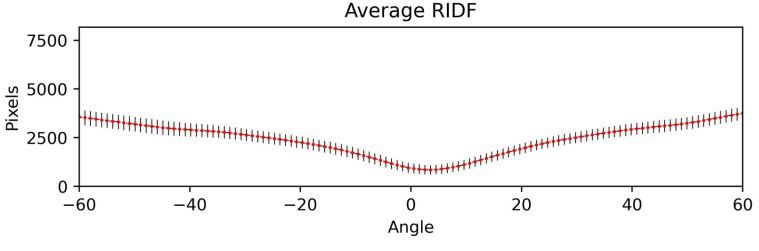
0%







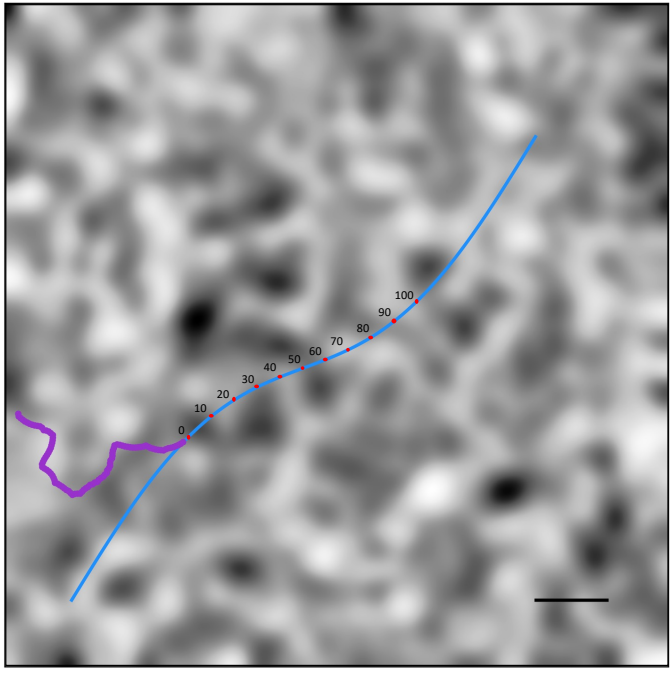


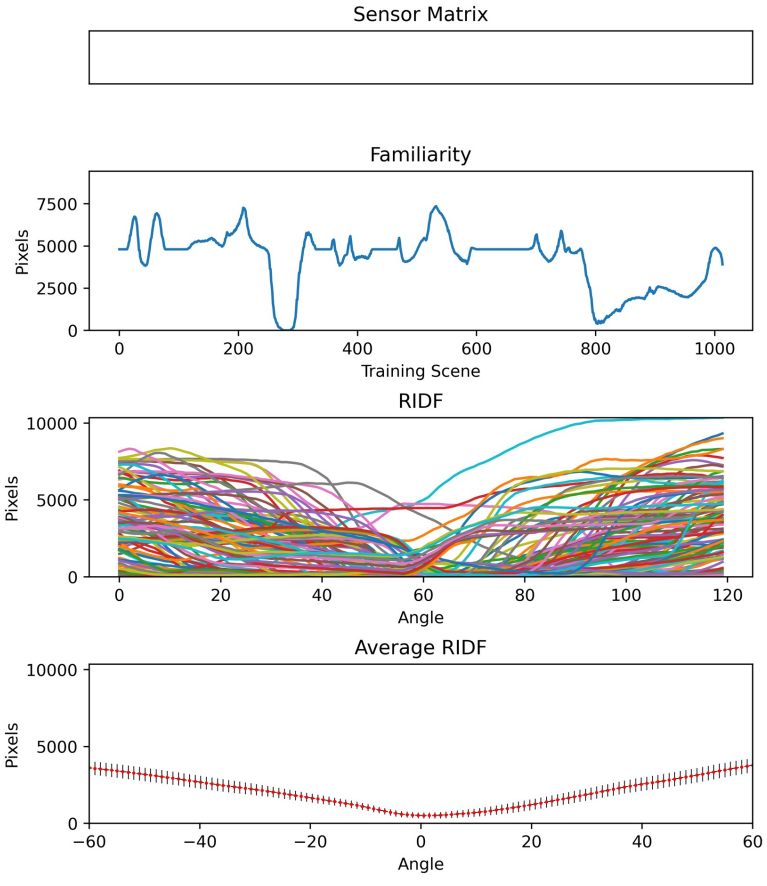


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4340.23; RMSD/dist: 10.851; TD: 2214; p90: 74; p50: 28; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 9711.03; RMSD/dist: 24.278; TD: 2736; p90: 92; p50: 48; complete: 0

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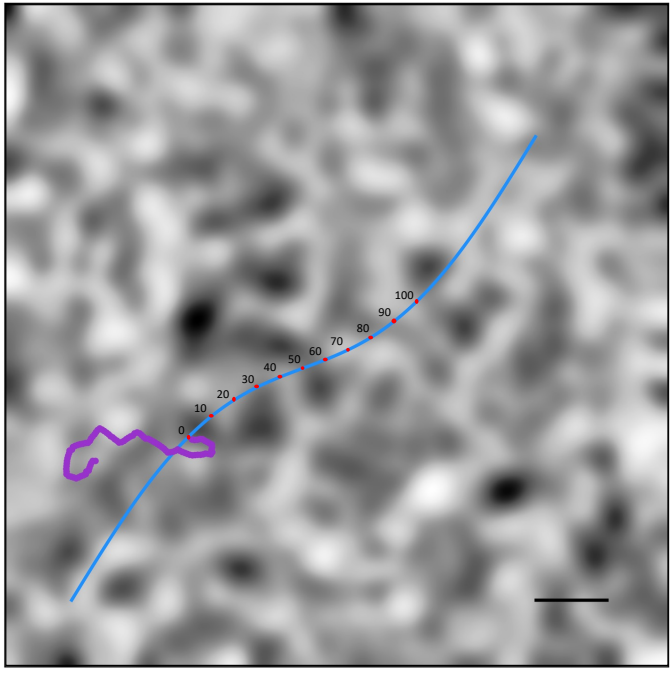

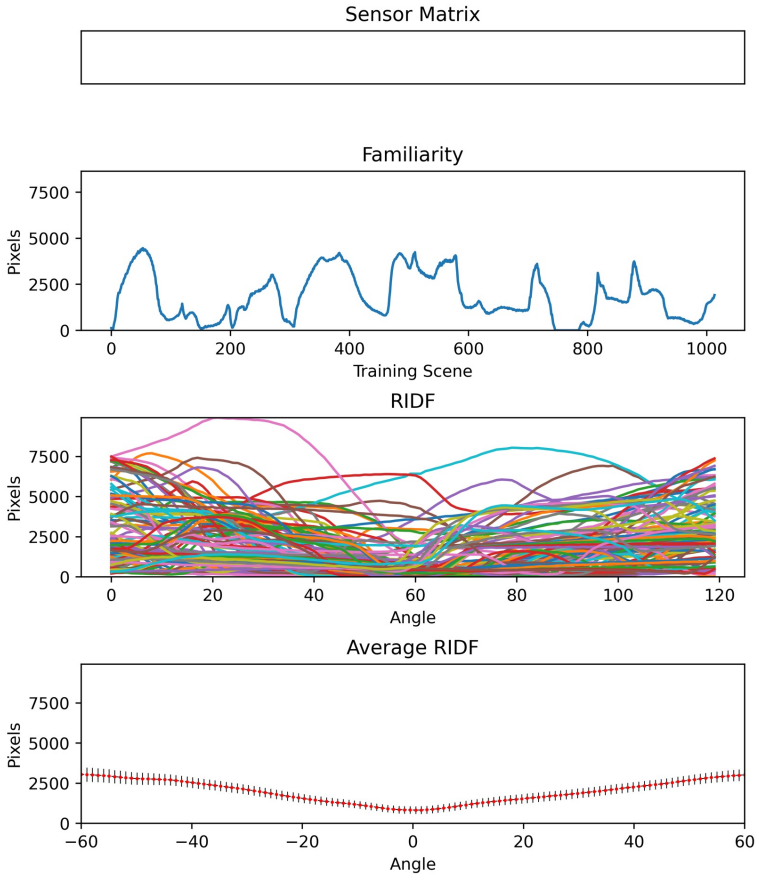

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 6637.72; RMSD/dist: 16.594; TD: 2256; p90: 104; p50: 56; complete: 0

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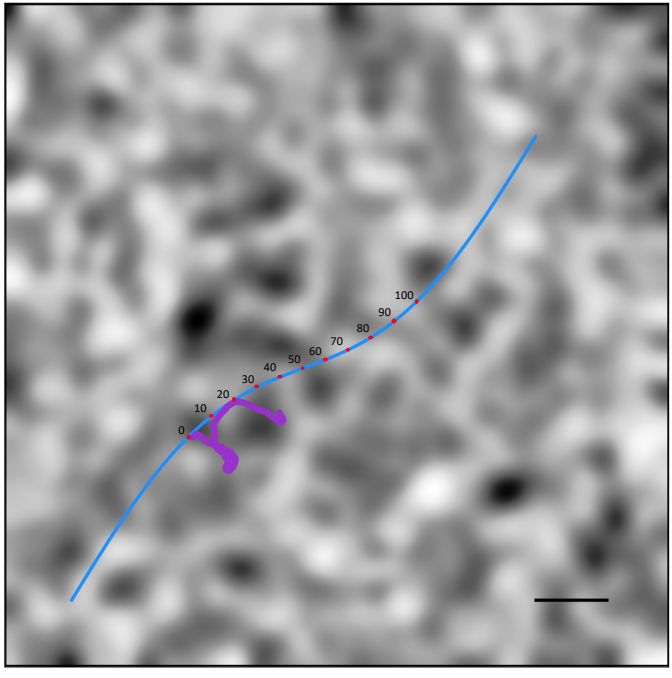
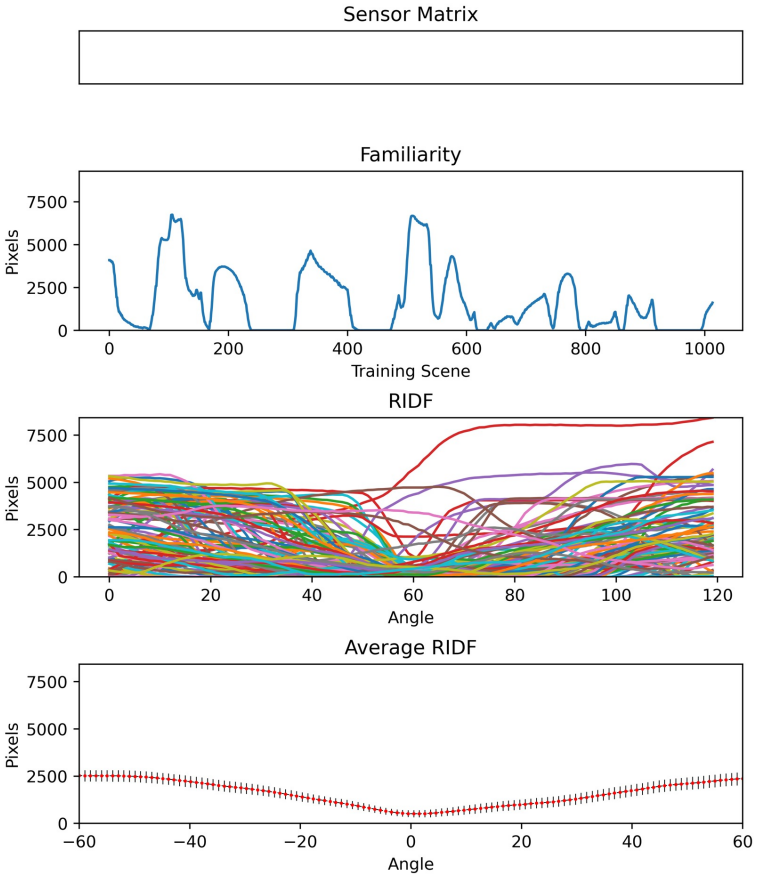
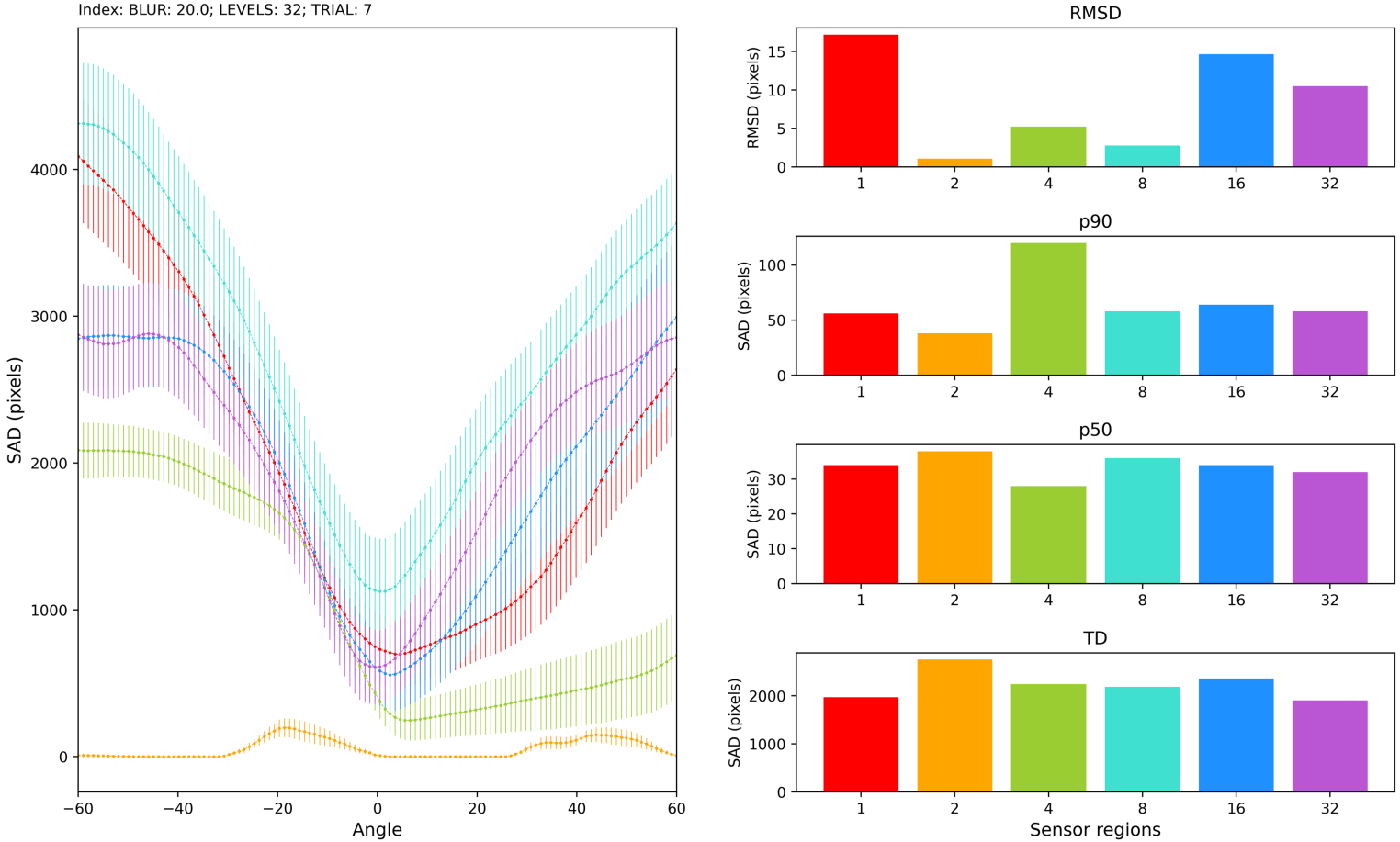


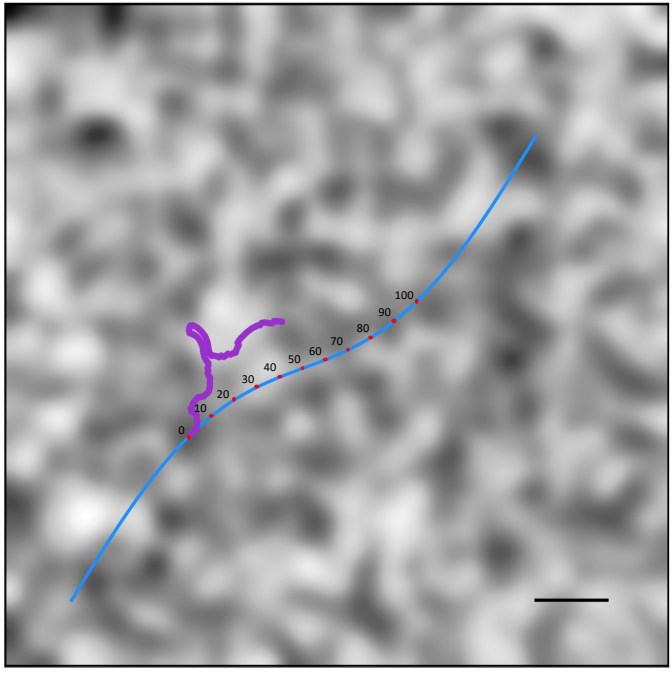


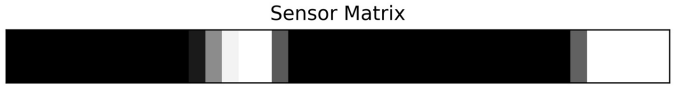
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

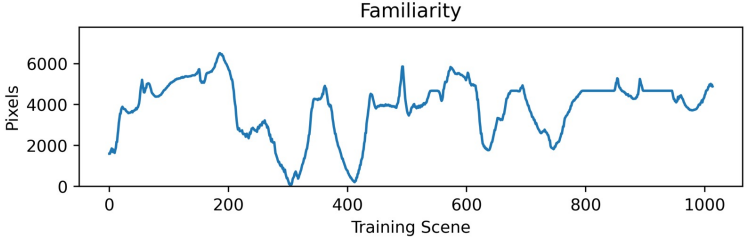
Navigation stats: RMSD error: 4206.39; RMSD/dist: 10.516; TD: 1915; p90: 82; p50: 42; complete: 0

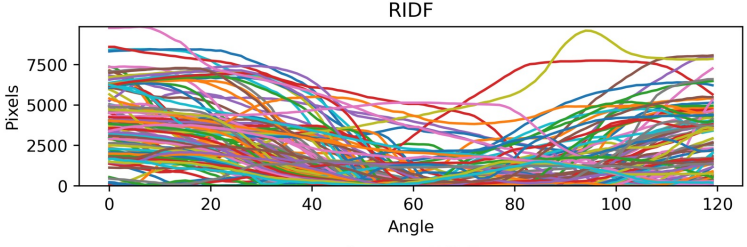

Index: BLUR: 20.0; LEVELS: 32; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

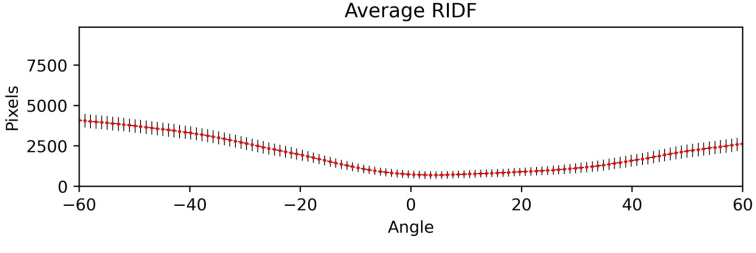
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 6881.15; RMSD/dist: 17.203; TD: 1968; p90: 56; p50: 34; complete: 0

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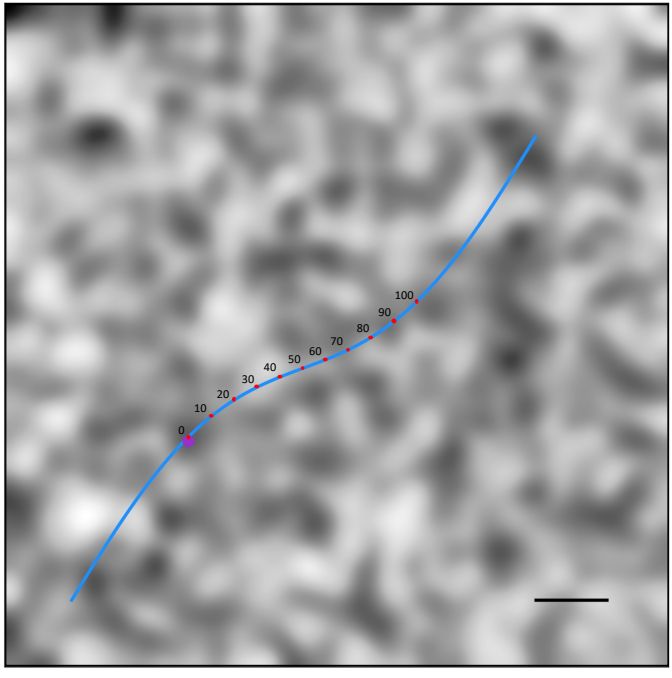

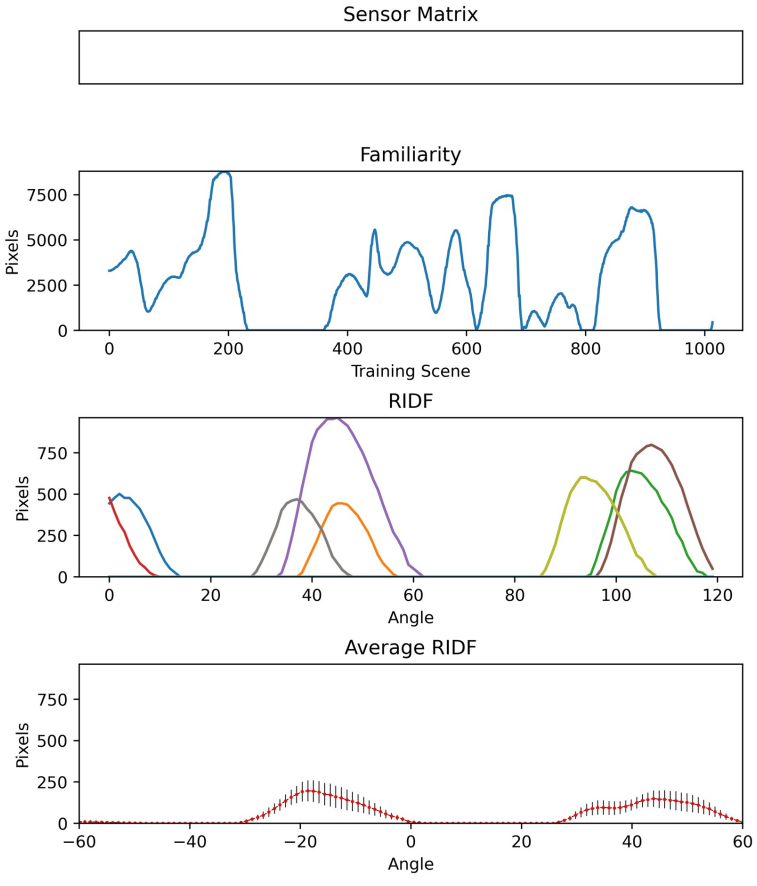

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 427.02; RMSD/dist: 1.068; TD: 2751; p90: 38; p50: 38; complete: 0

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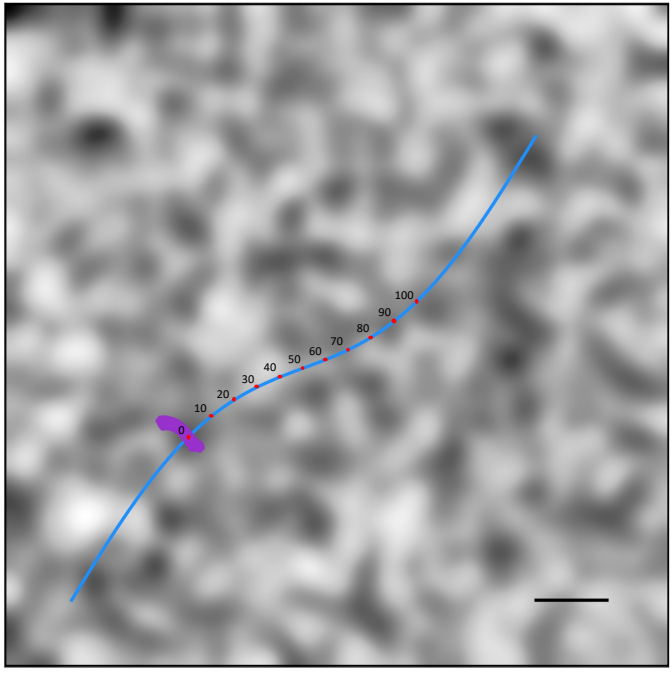

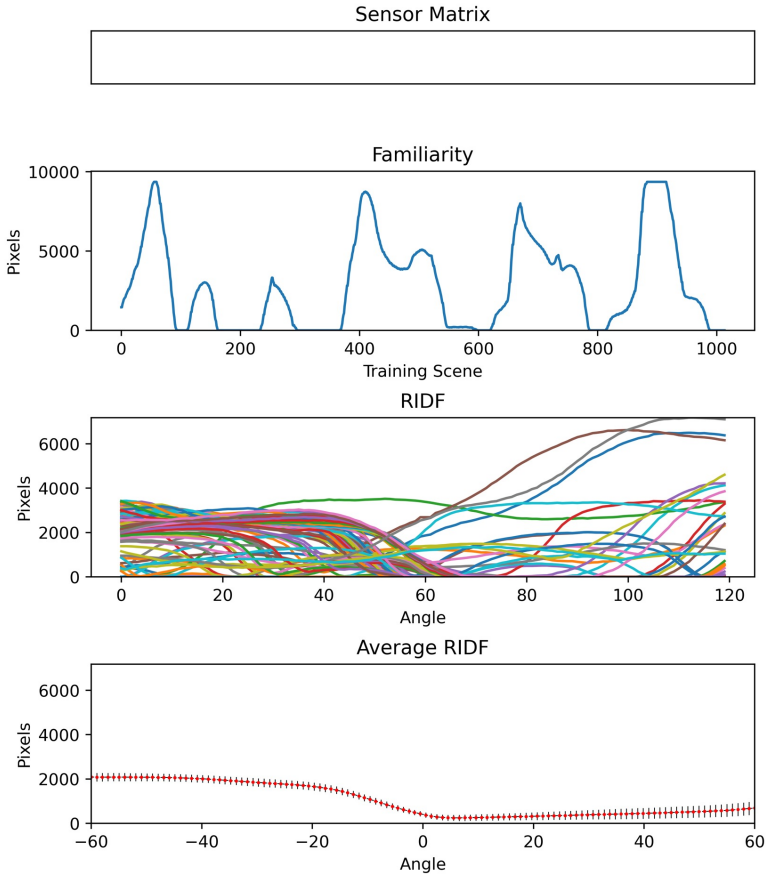

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2096.49; RMSD/dist: 5.241; TD: 2241; p90: 120; p50: 28; complete: 0

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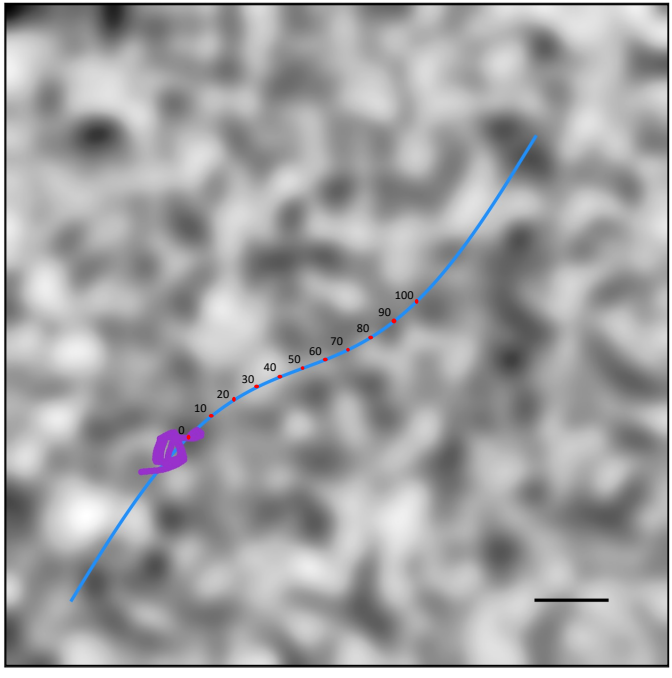

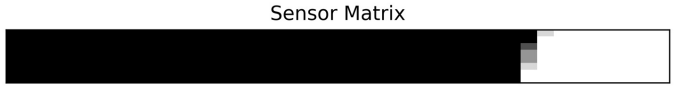

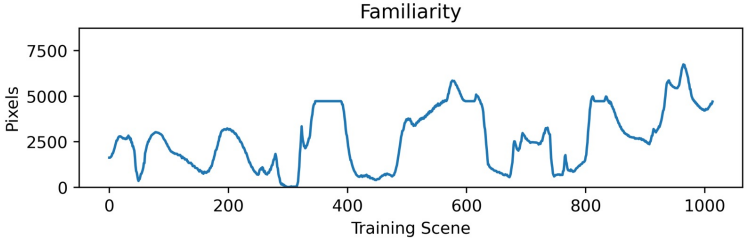

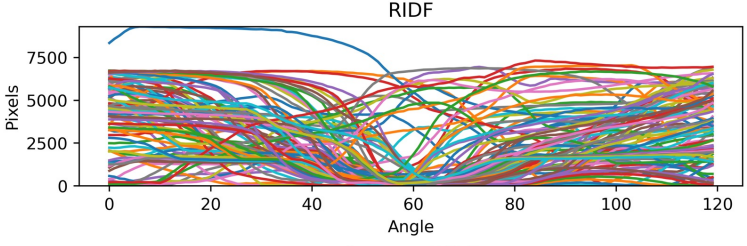

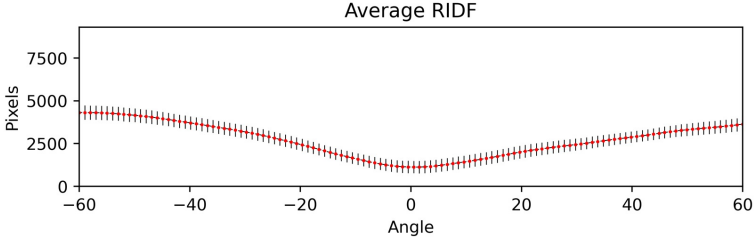

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1109.13; RMSD/dist: 2.773; TD: 2186; p90: 58; p50: 36; complete: 0

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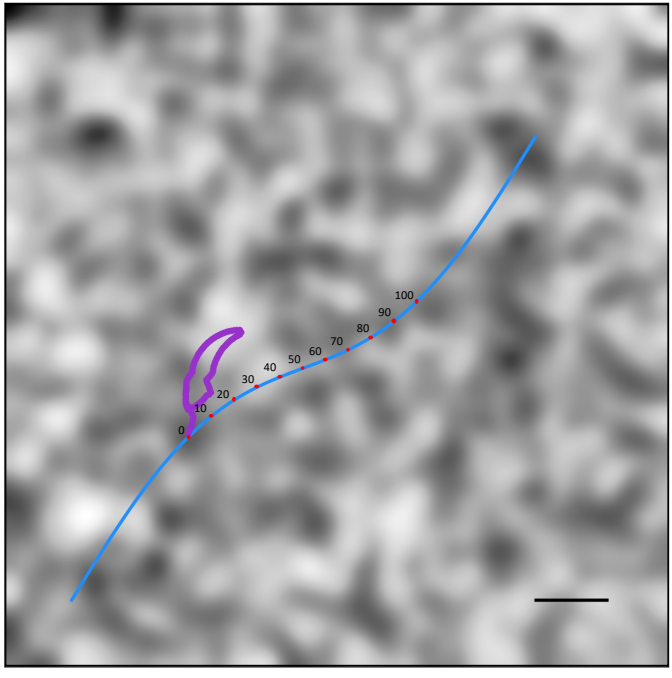

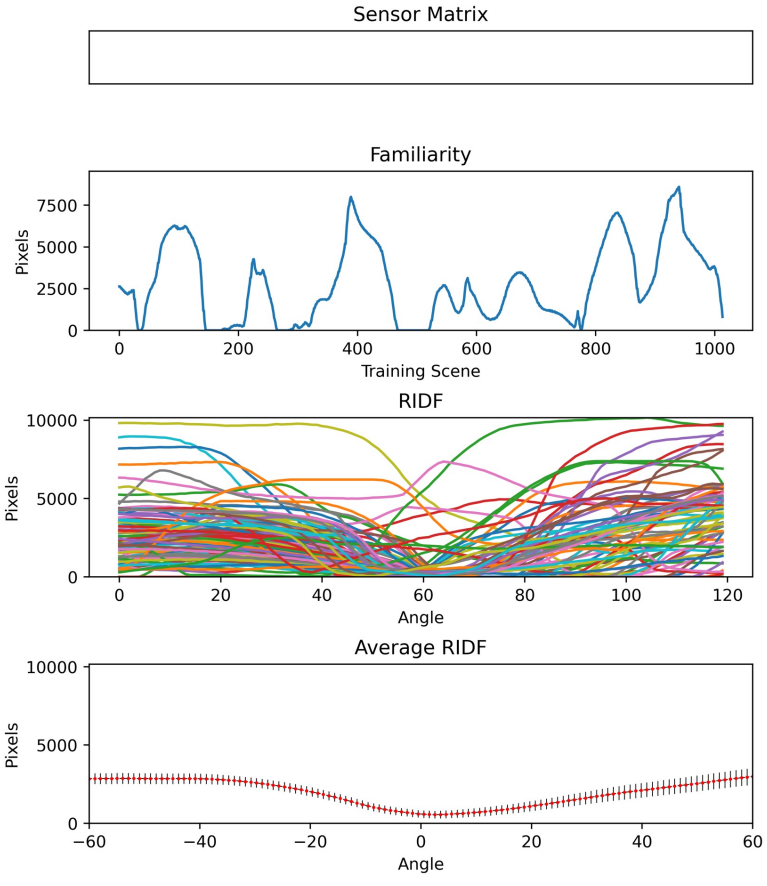

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 5861.58; RMSD/dist: 14.654; TD: 2357; p90: 64; p50: 34; complete: 0

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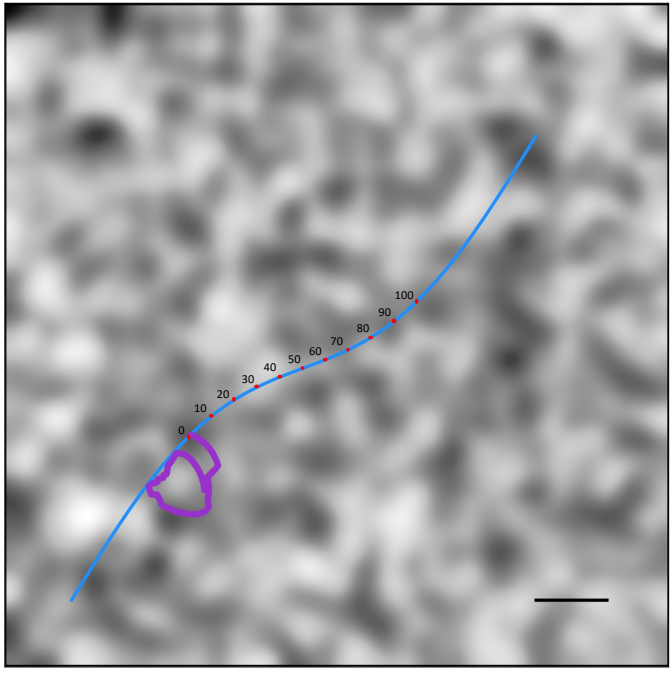
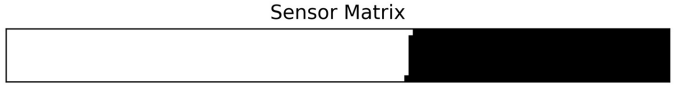
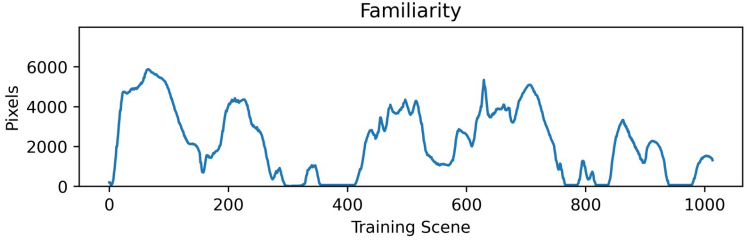
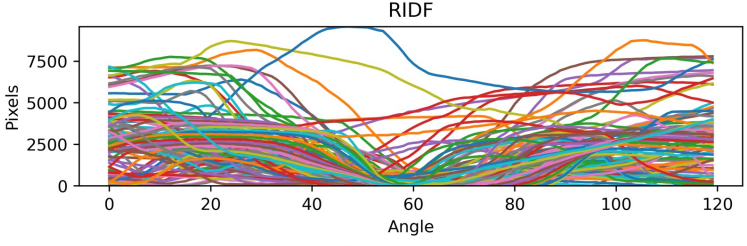
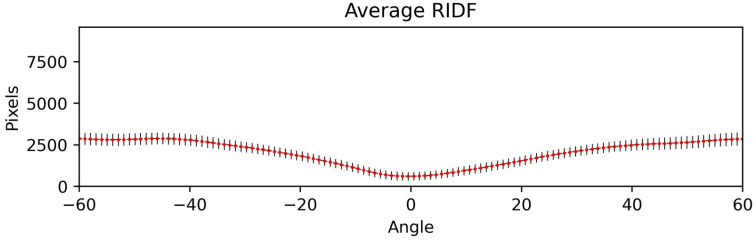




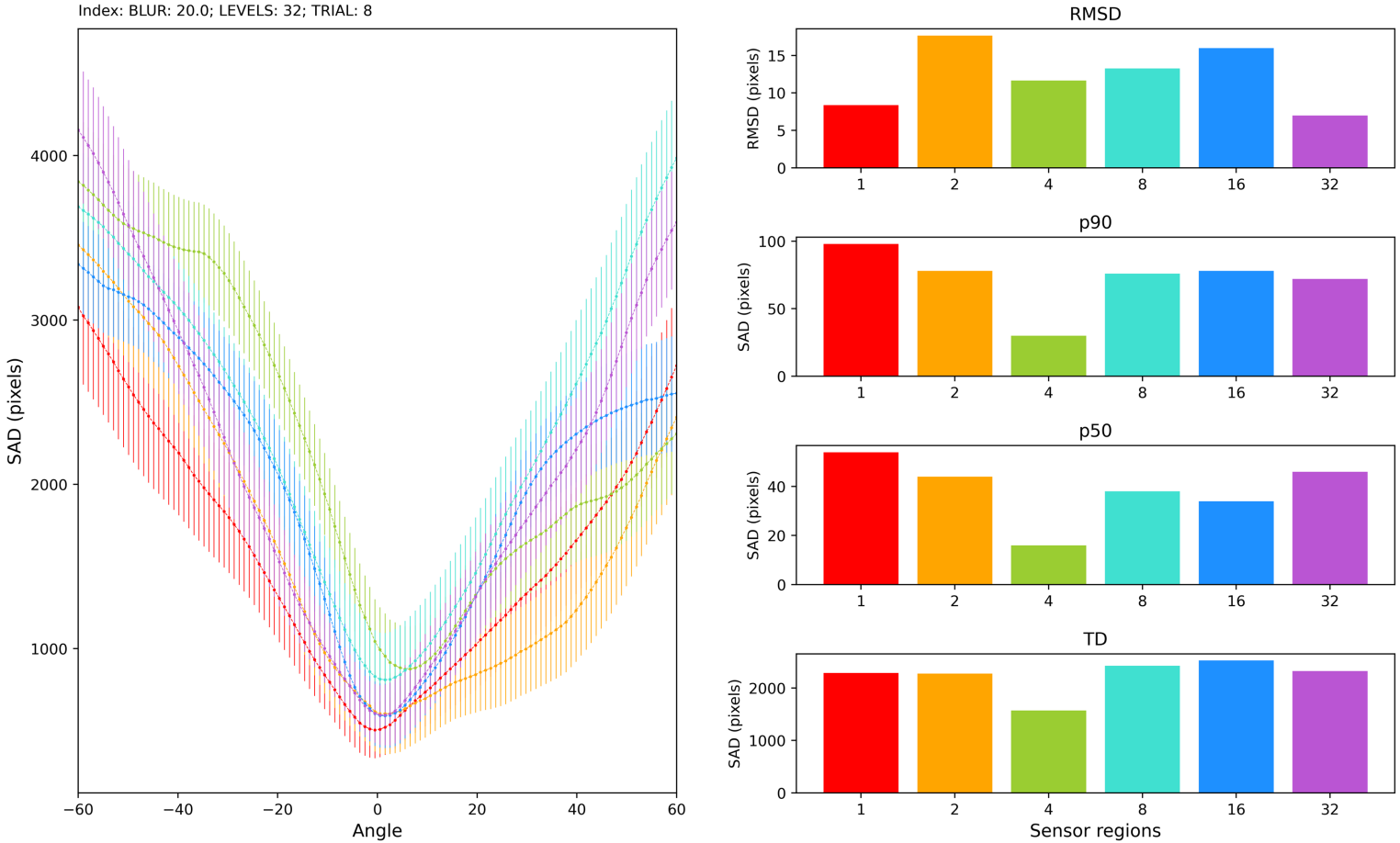






Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 4193.75; RMSD/dist: 10.484; TD: 1902; p90: 58; p50: 32; complete: 0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2000
1000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
15
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
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p50
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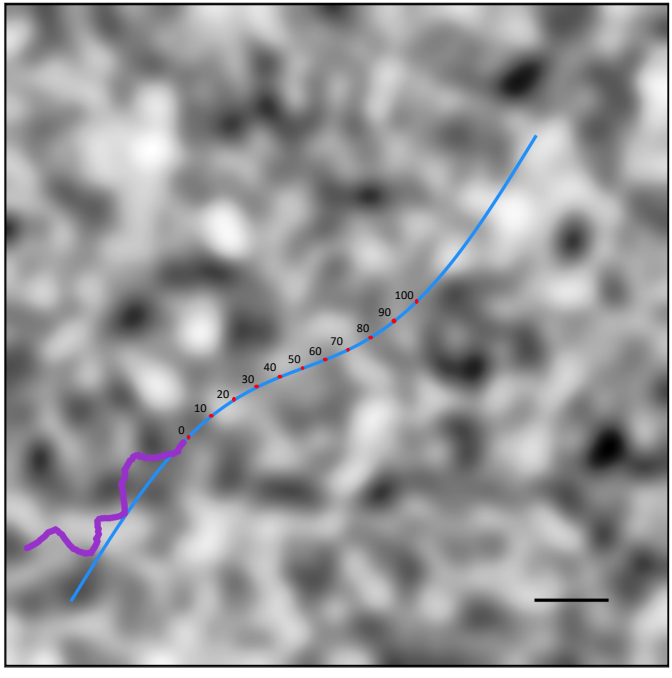
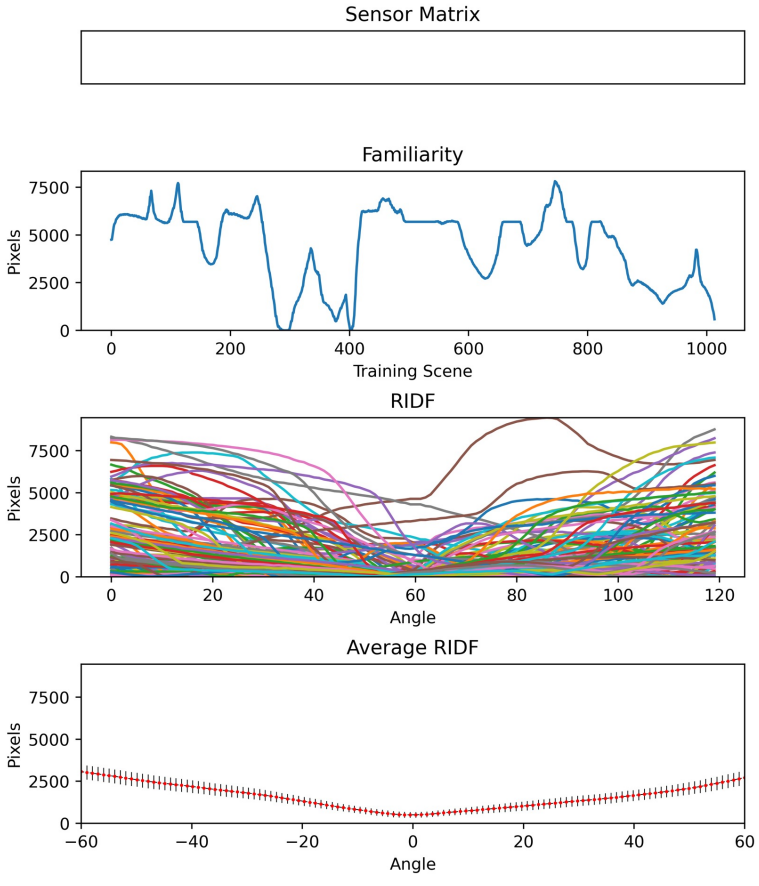
TD
2000
1000
Sensor regions

0%

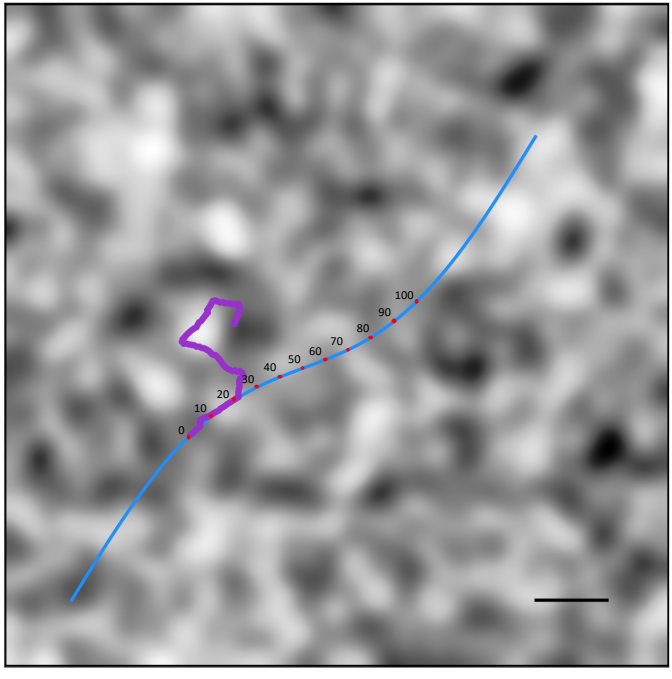


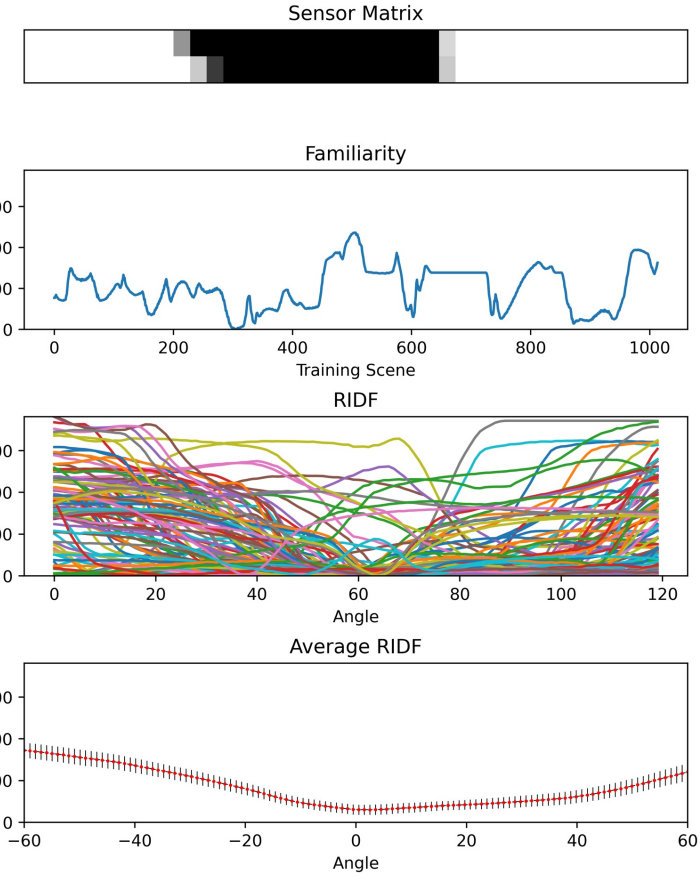


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3353.34; RMSD/dist: 8.383; TD: 2288; p90: 98; p50: 54; complete: 0

10%

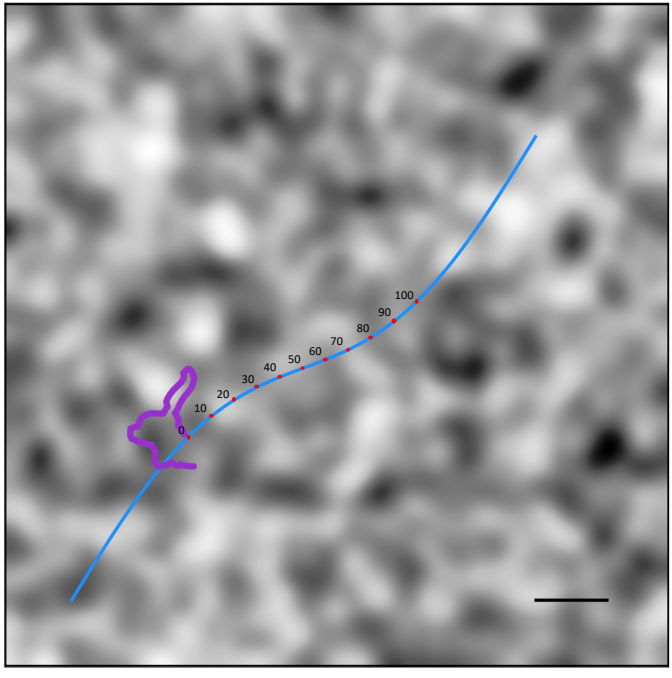


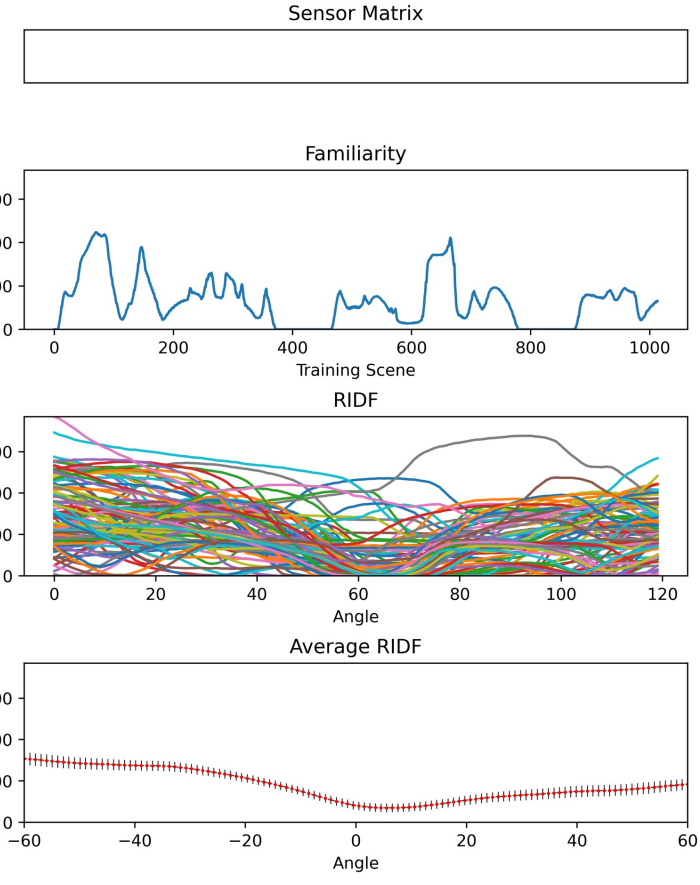


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 7067.02; RMSD/dist: 17.668; TD: 2276; p90: 78; p50: 44; complete: 0

0%

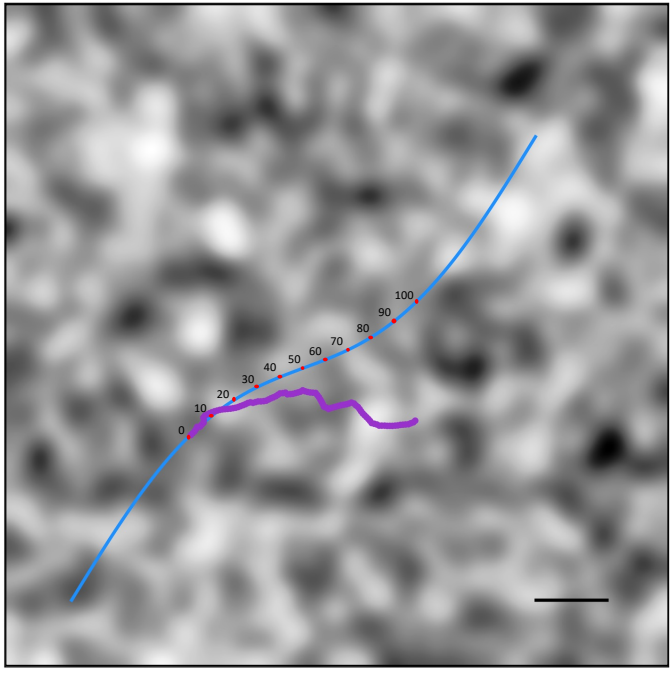


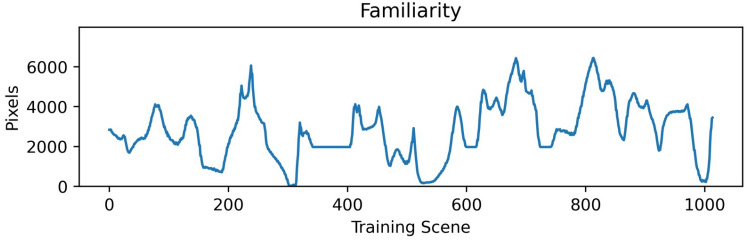


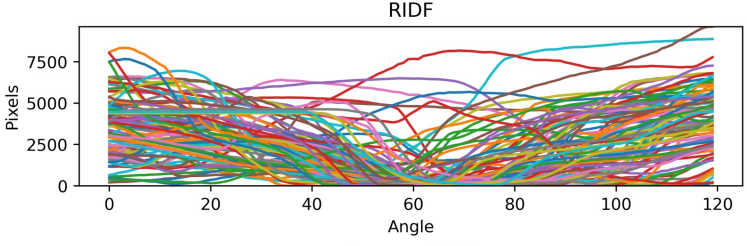
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

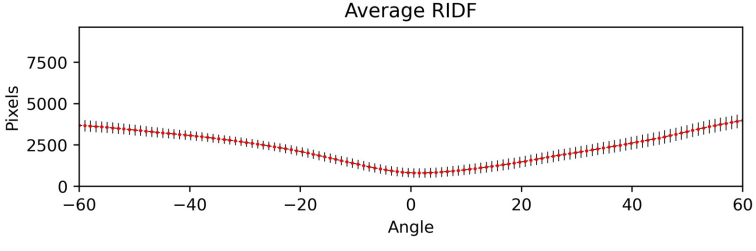
Navigation stats: RMSD error: 4657.54; RMSD/dist: 11.644; TD: 1571; p90: 30; p50: 16; complete: 0

0%





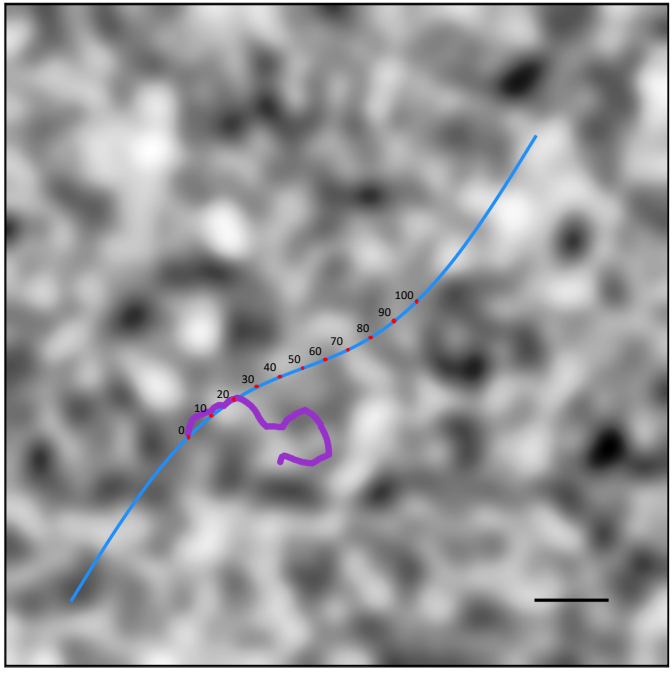


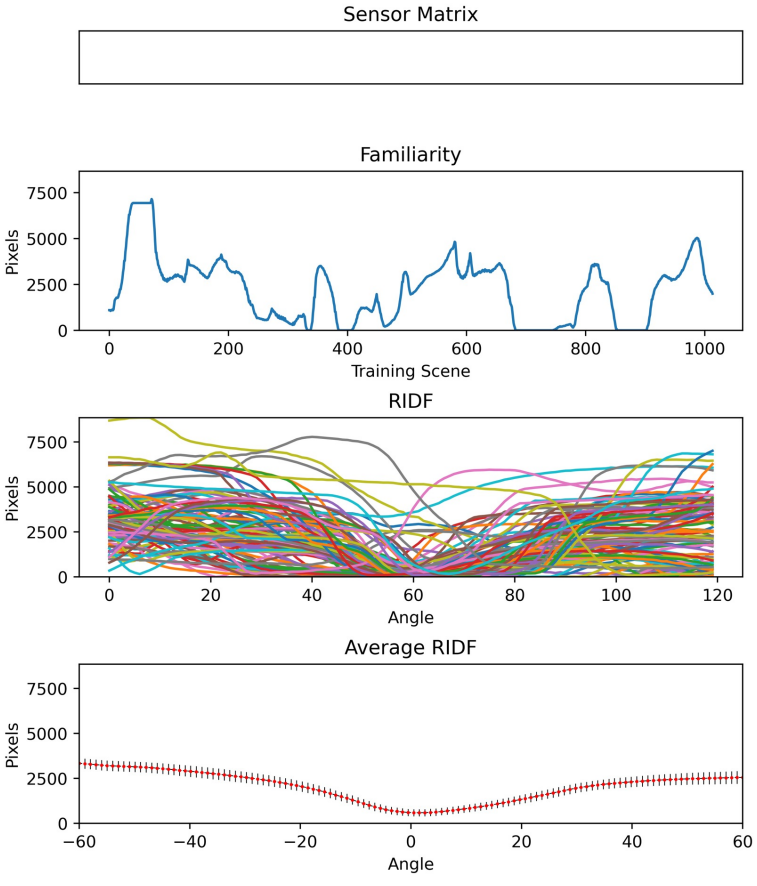


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5305.66; RMSD/dist: 13.264; TD: 2425; p90: 76; p50: 38; complete: 0

0%

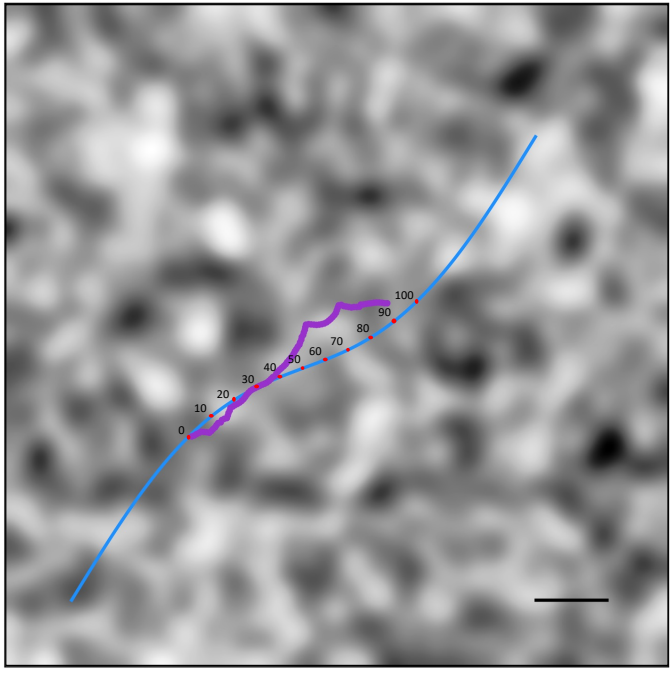


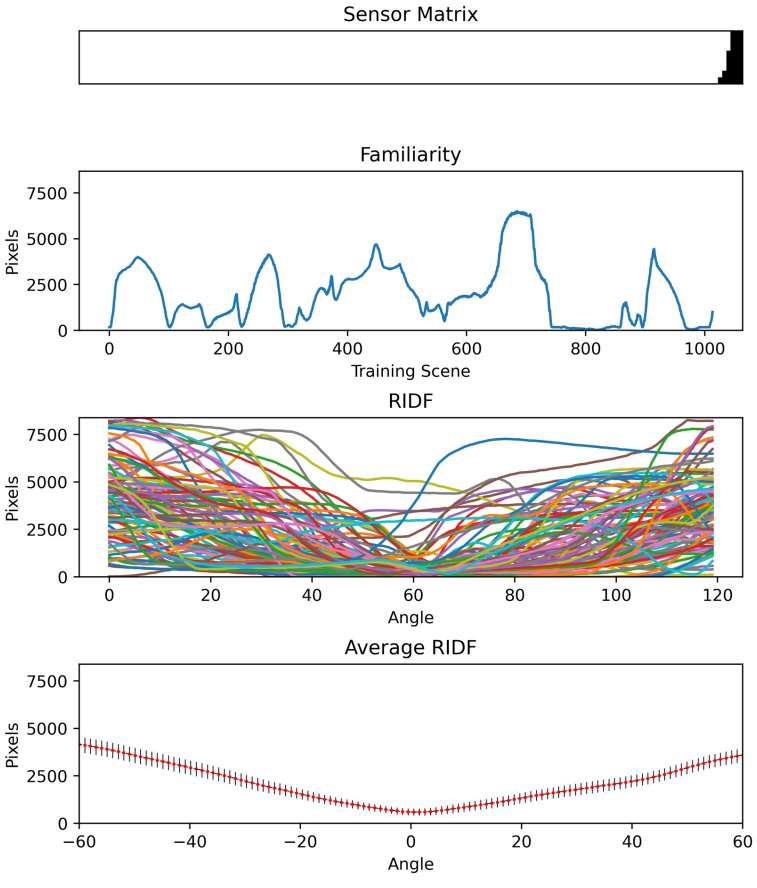


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 6390.88; RMSD/dist: 15.977; TD: 2525; p90: 78; p50: 34; complete: 0

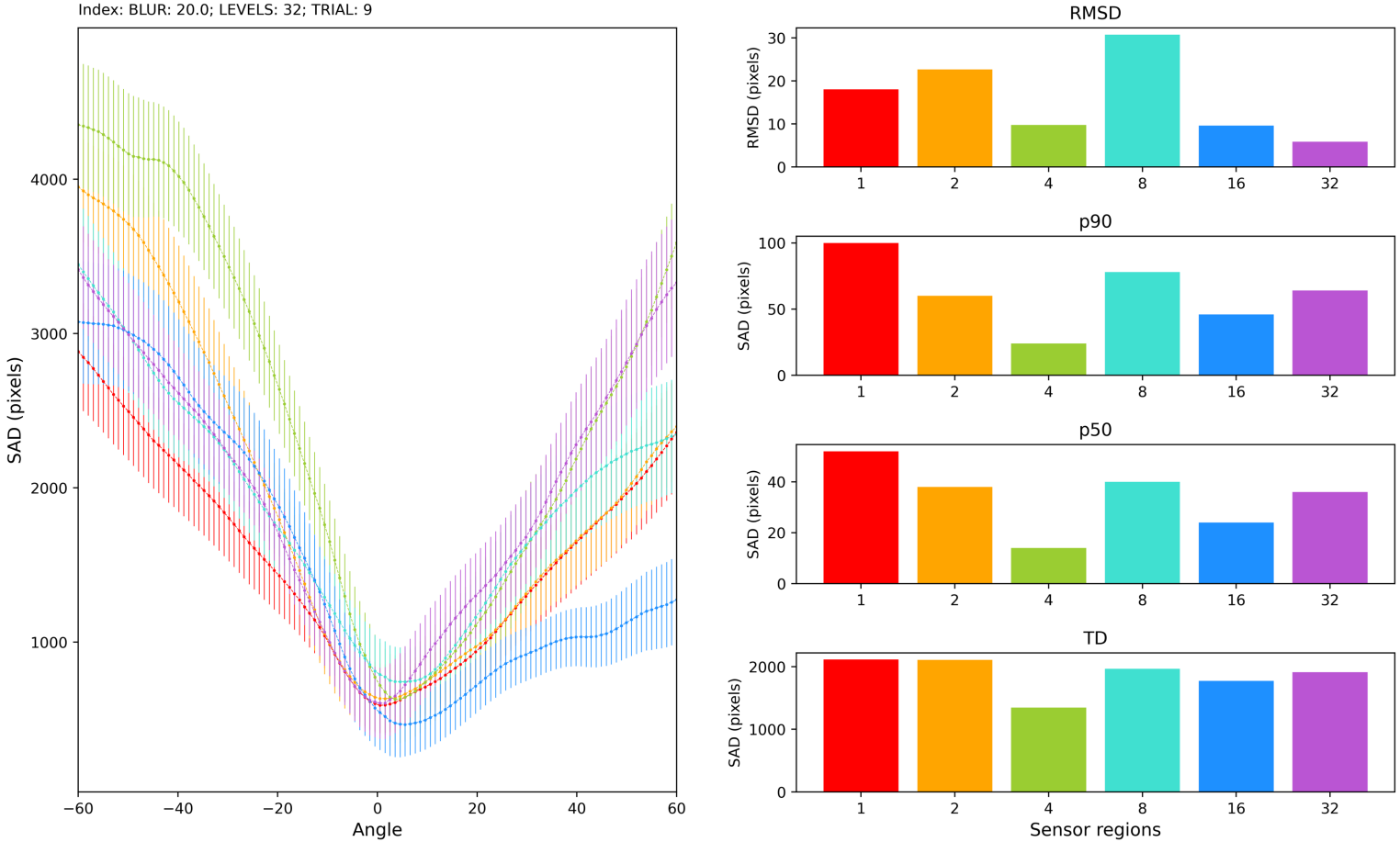
0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2794.98; RMSD/dist: 6.987; TD: 2325; p90: 72; p50: 46; complete: 0


Index: BLUR: 20.0; LEVELS: 32; TRIAL: 9
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−60
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20
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60
Angle
RMSD
RMSD (pixels)
30
20
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p90
SAD (pixels)
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p50
40
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TD
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Sensor regions

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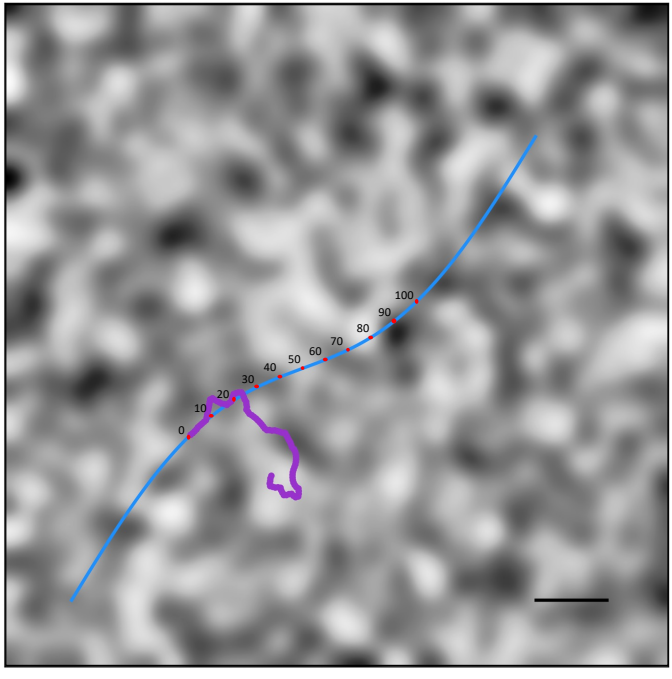

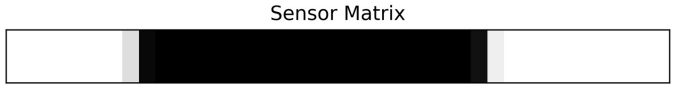

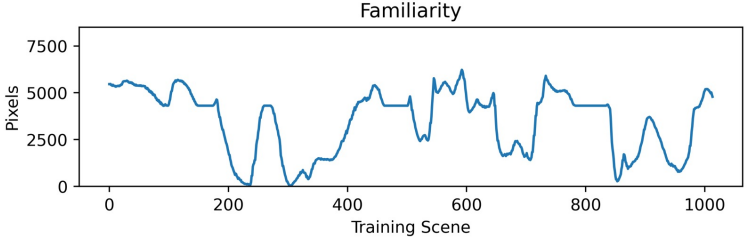

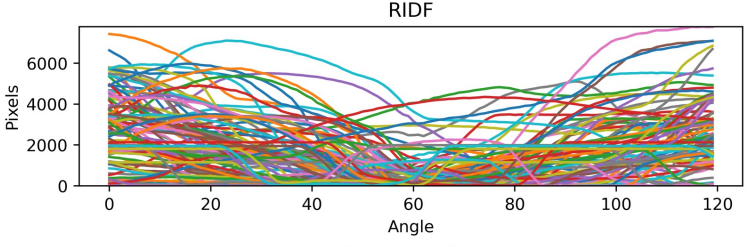

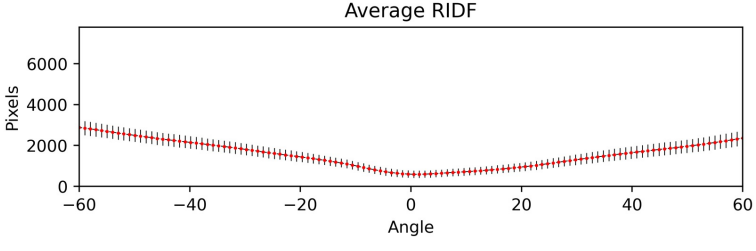

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 7217.78; RMSD/dist: 18.044; TD: 2114; p90: 100; p50: 52; complete: 0

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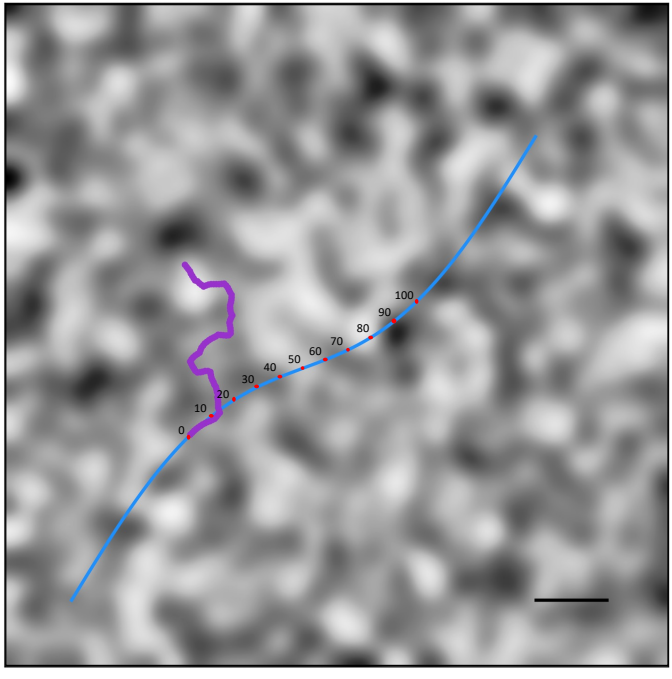
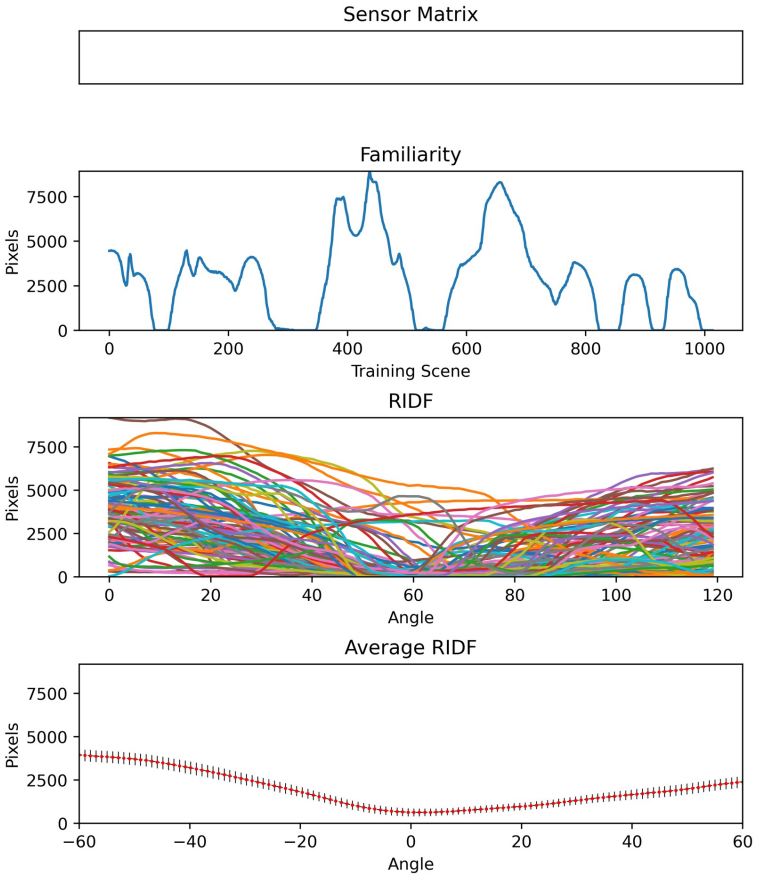
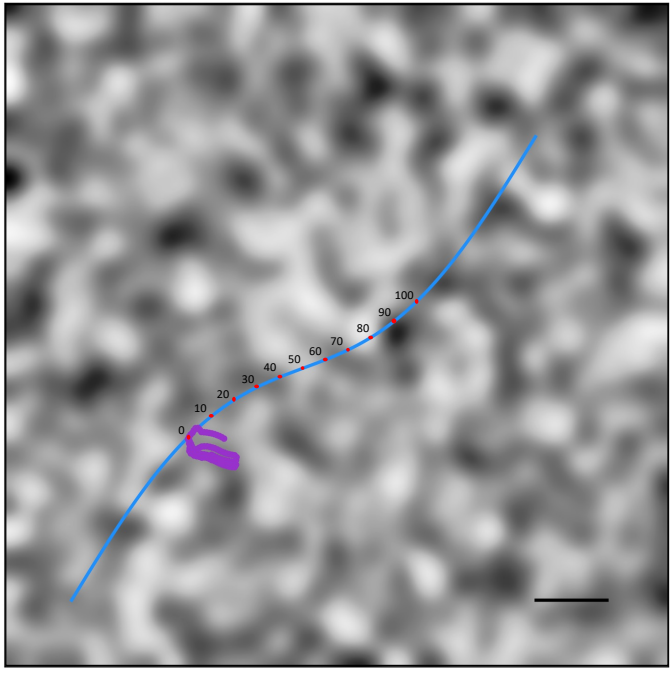


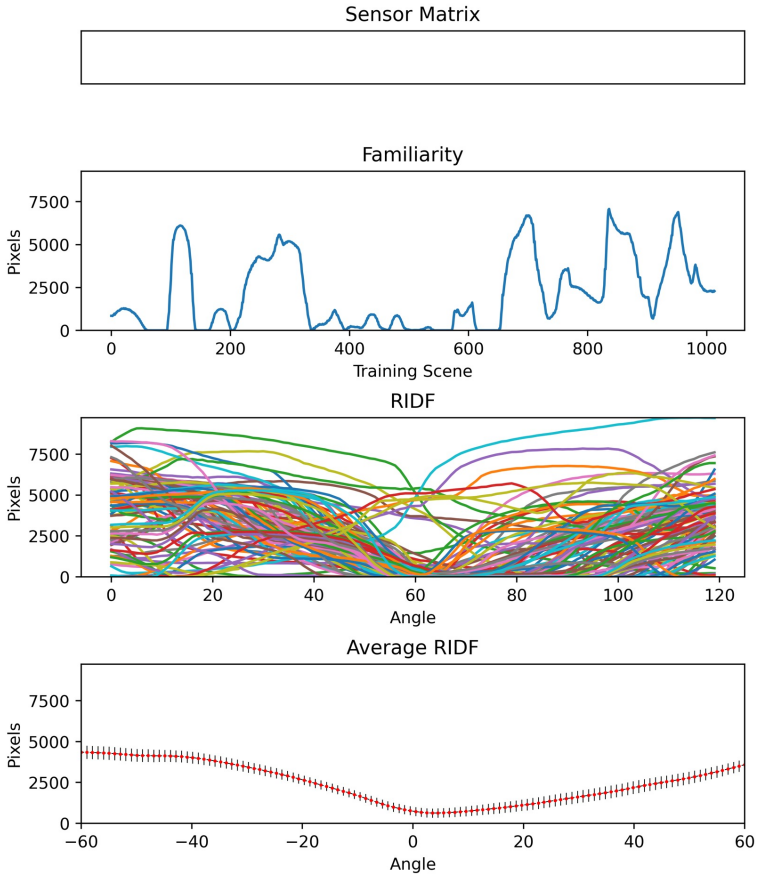


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 9069.39; RMSD/dist: 22.673; TD: 2108; p90: 60; p50: 38; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3905.64; RMSD/dist: 9.764; TD: 1347; p90: 24; p50: 14; complete: 0

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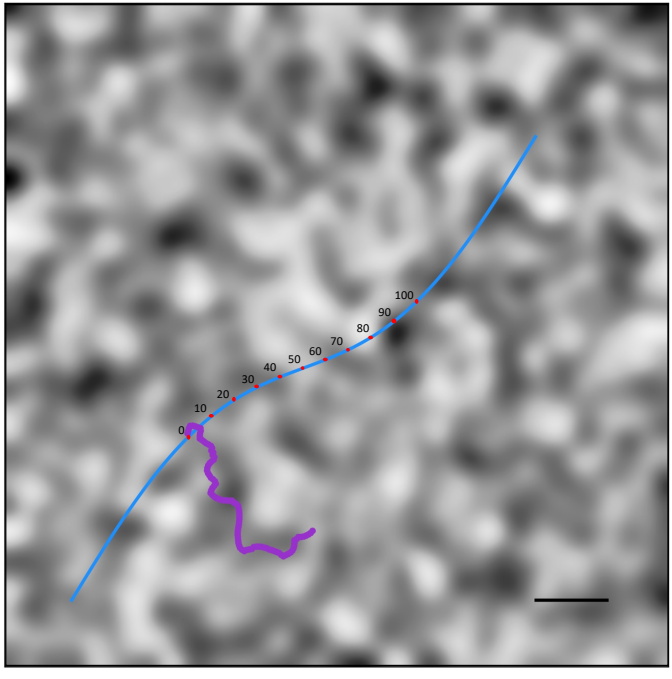

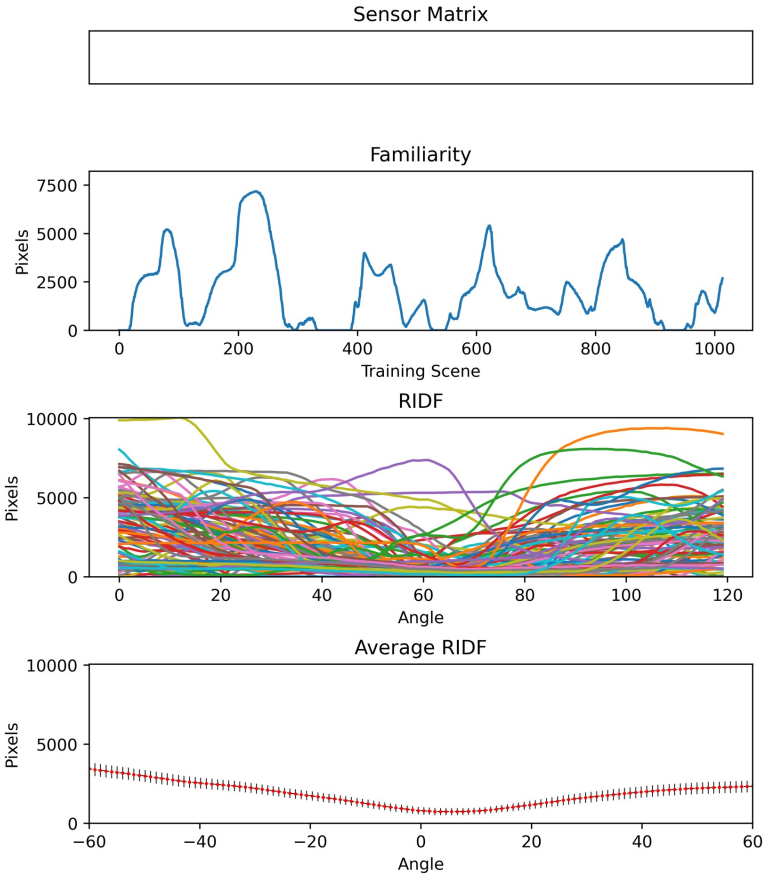

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 12312.83; RMSD/dist: 30.782; TD: 1965; p90: 78; p50: 40; complete: 0

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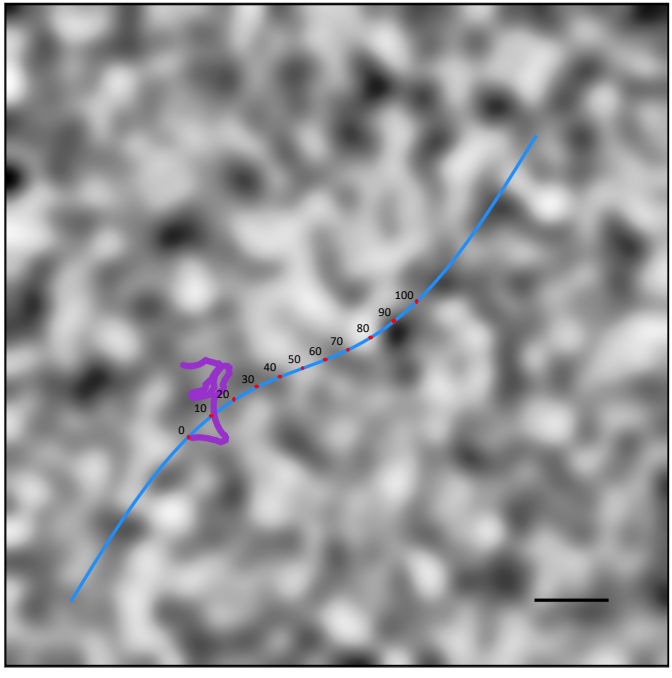
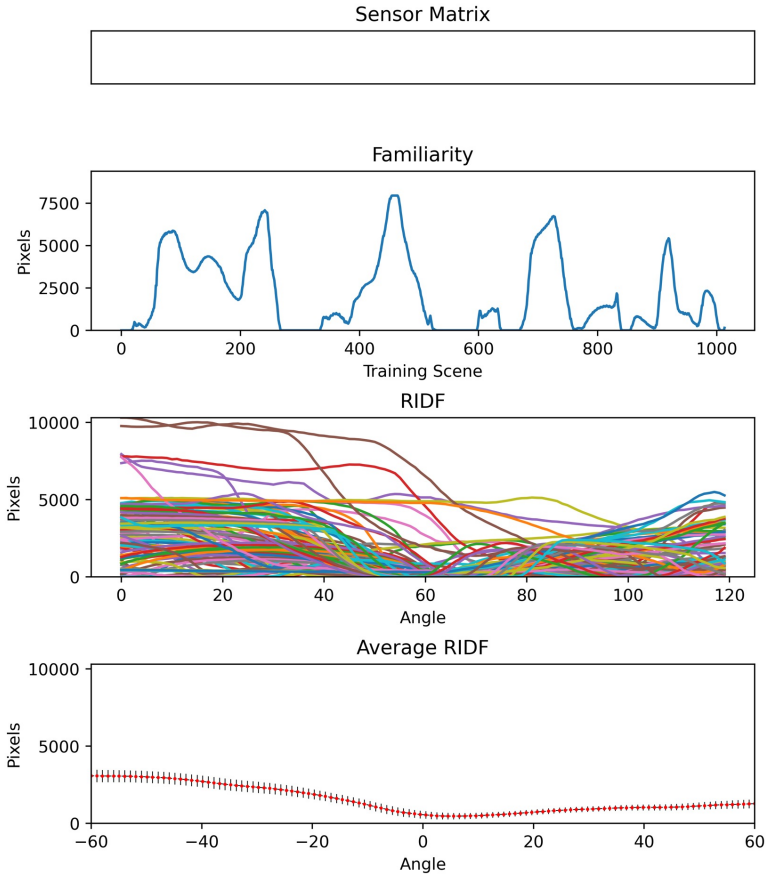
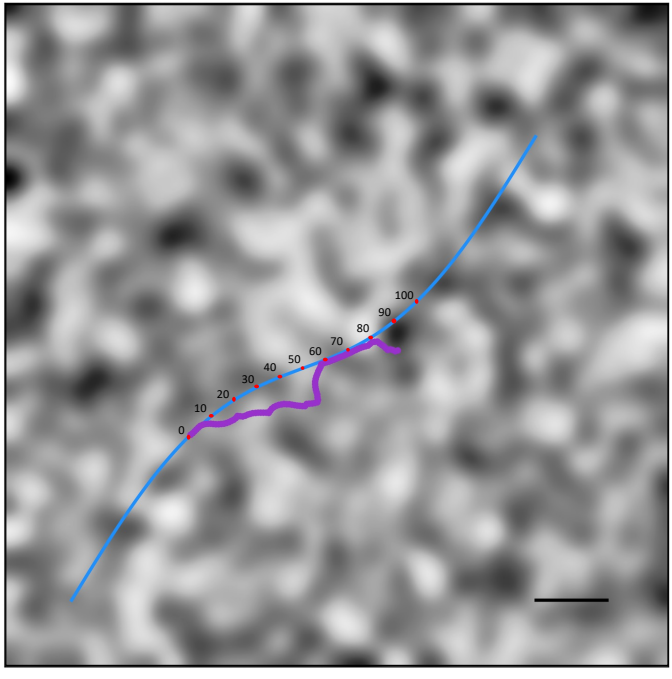


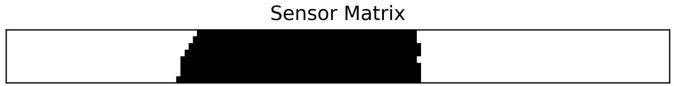


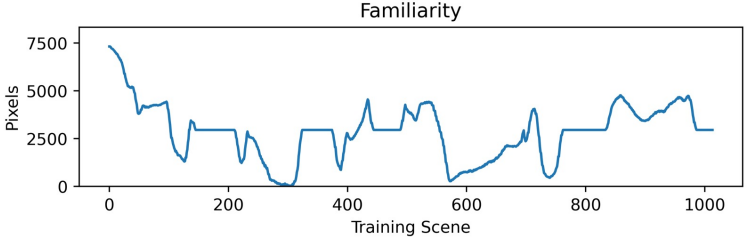
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

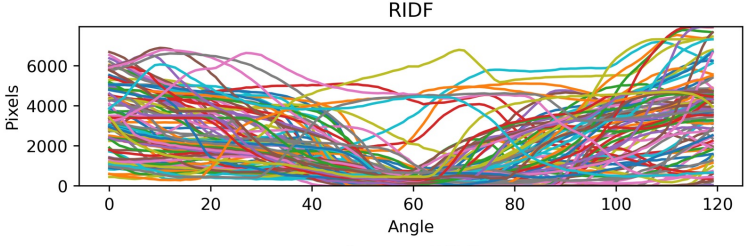
Navigation stats: RMSD error: 3837.33; RMSD/dist: 9.593; TD: 1774; p90: 46; p50: 24; complete: 0

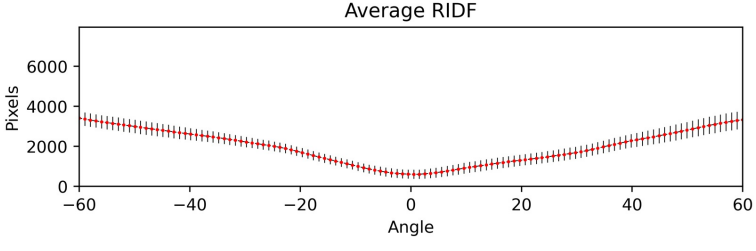
0%





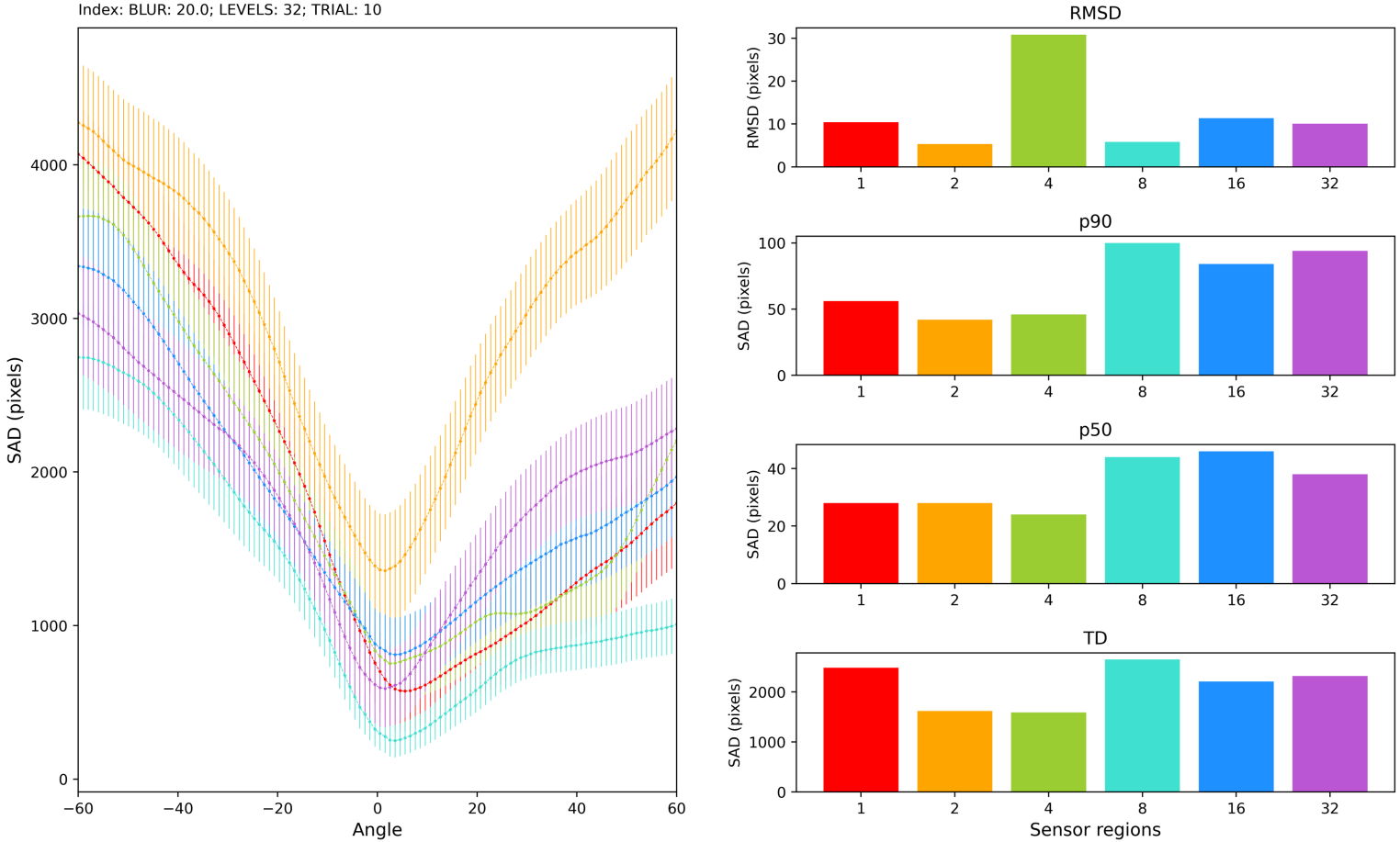




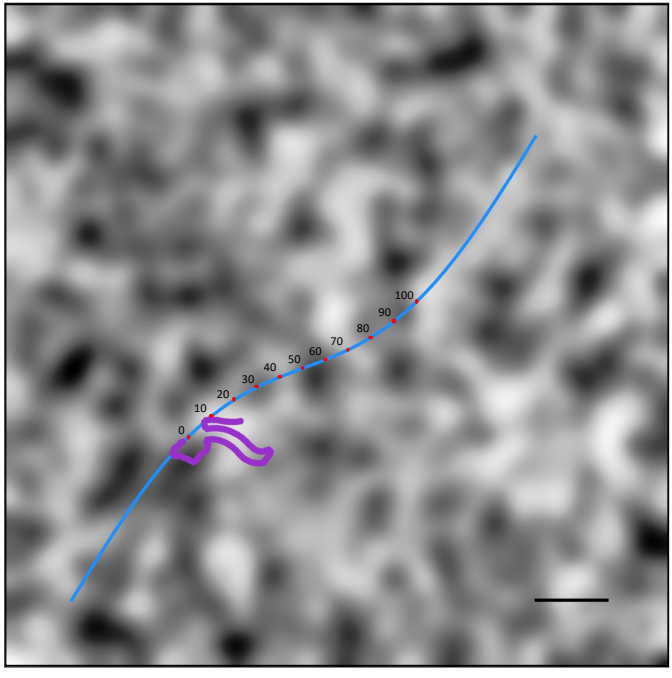


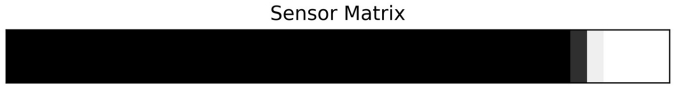
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

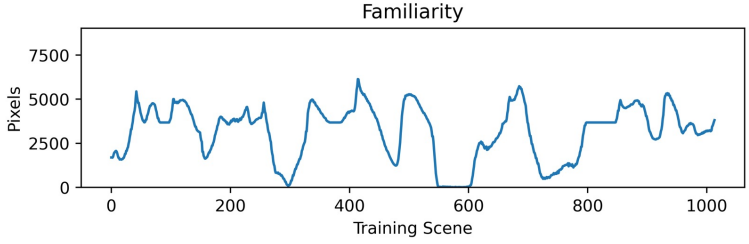
Navigation stats: RMSD error: 2331.65; RMSD/dist: 5.829; TD: 1912; p90: 64; p50: 36; complete: 0

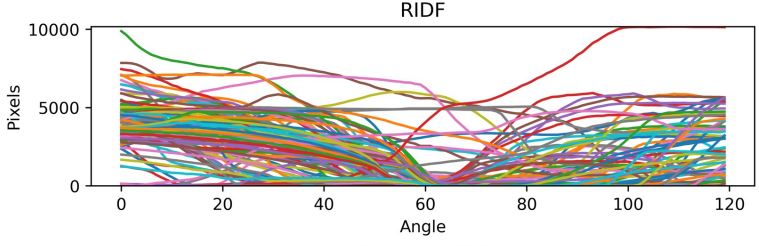

Index: BLUR: 20.0; LEVELS: 32; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

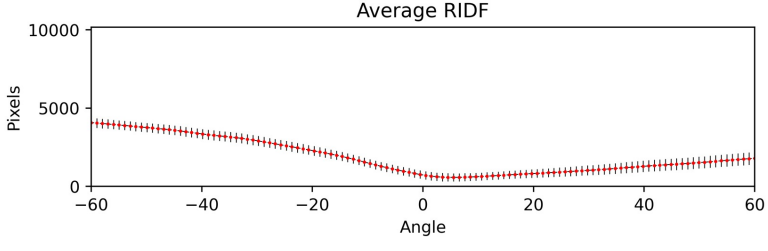
0%







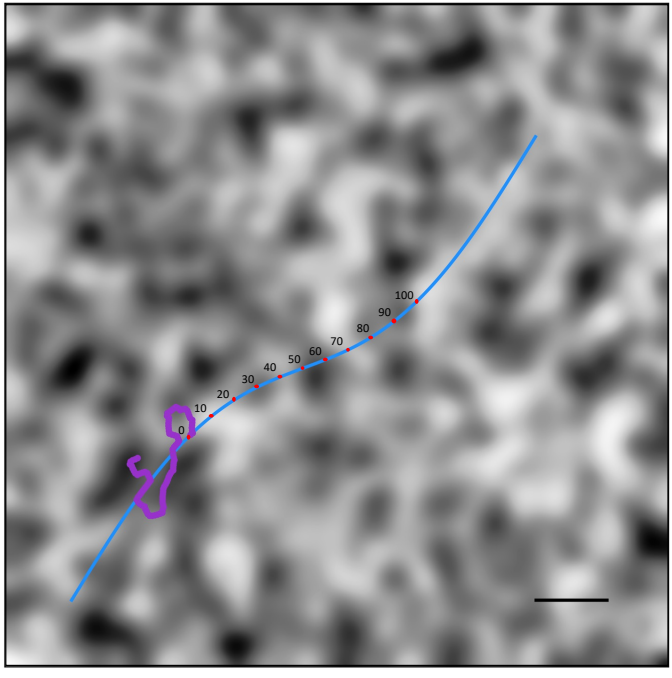


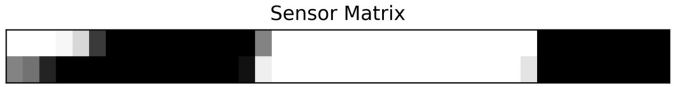


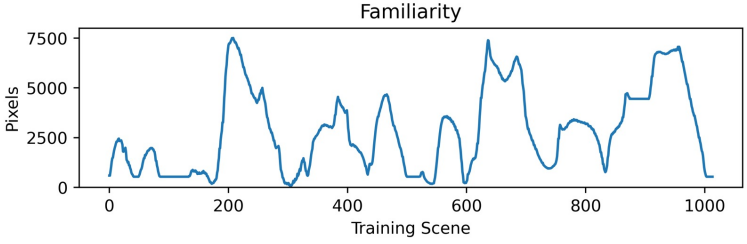
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

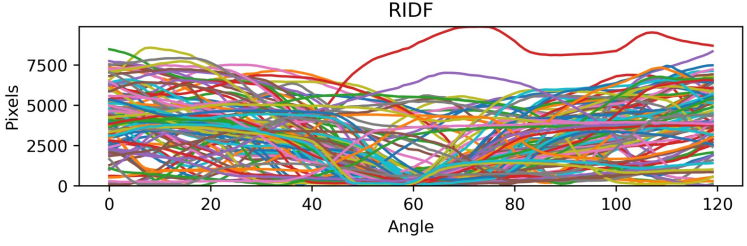
Navigation stats: RMSD error: 4164.78; RMSD/dist: 10.412; TD: 2482; p90: 56; p50: 28; complete: 0

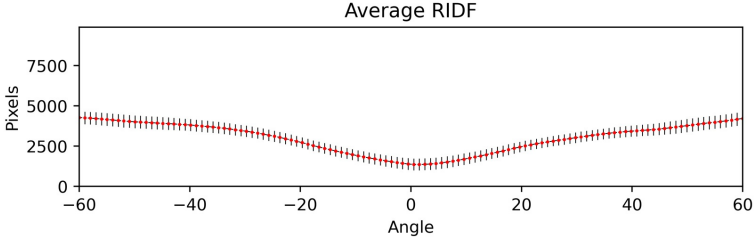
0%











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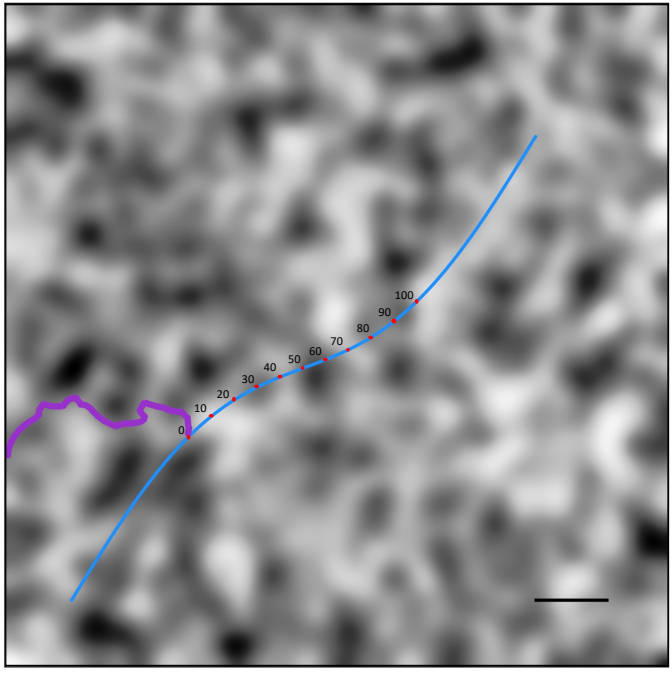
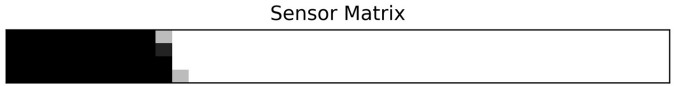
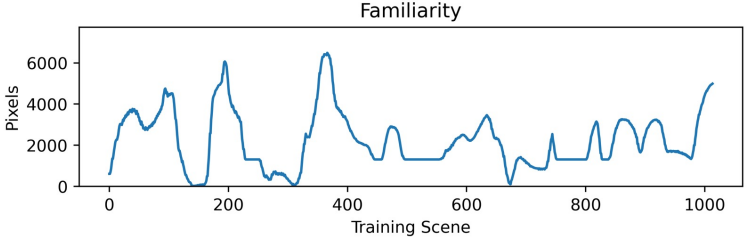
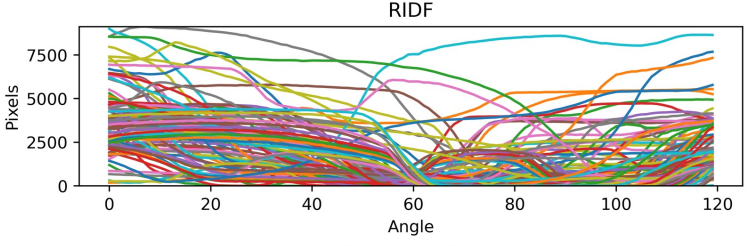
Navigation stats: RMSD error: 2129.51; RMSD/dist: 5.324; TD: 1618; p90: 42; p50: 28; complete: 0

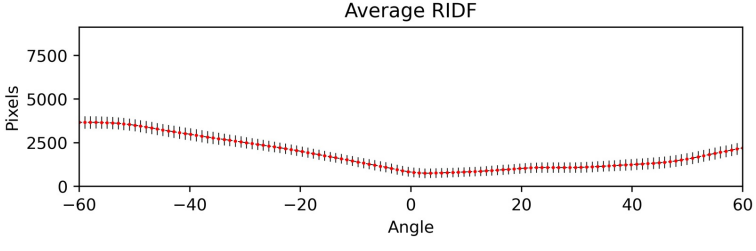
0%







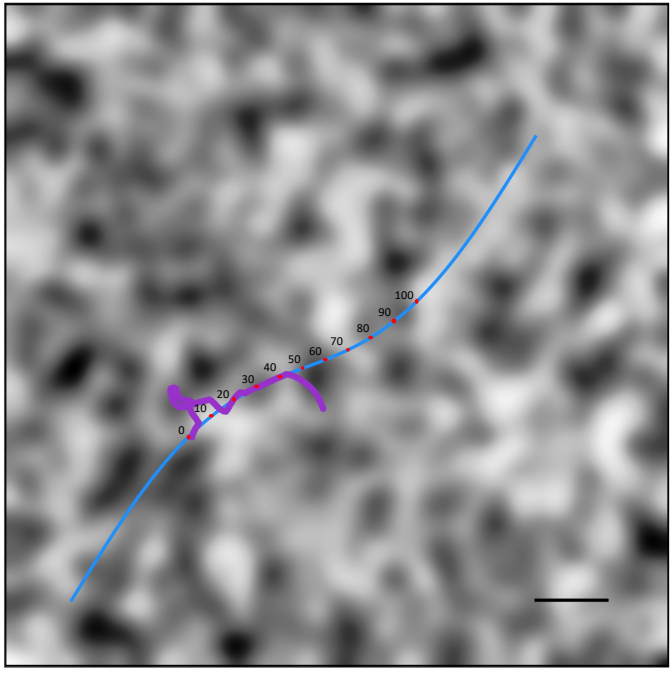


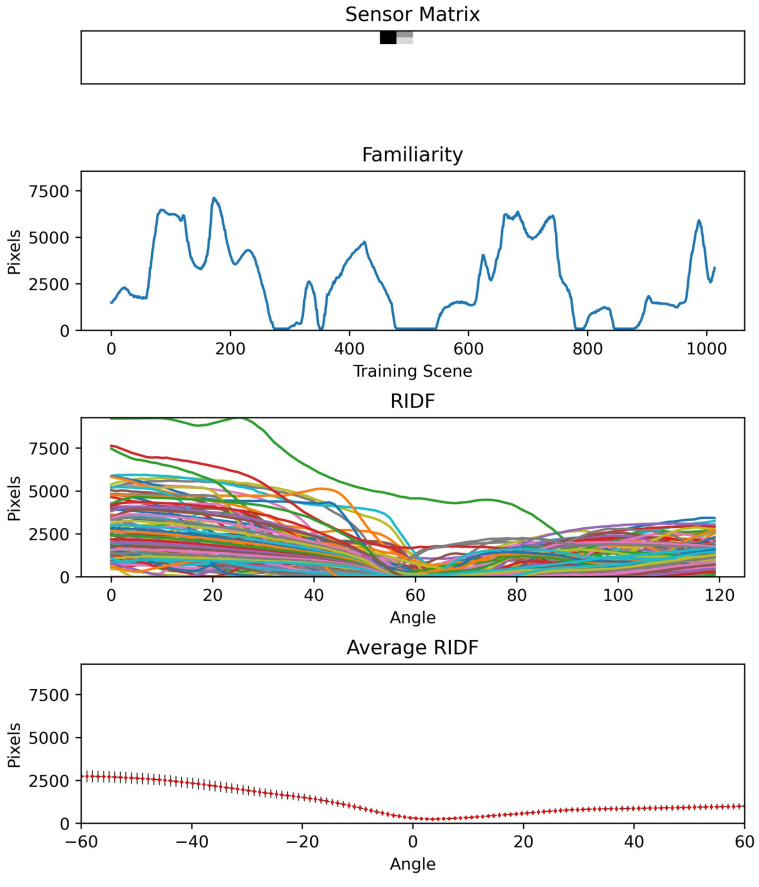


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 12341.30; RMSD/dist: 30.853; TD: 1589; p90: 46; p50: 24; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2317.04; RMSD/dist: 5.793; TD: 2646; p90: 100; p50: 44; complete: 0

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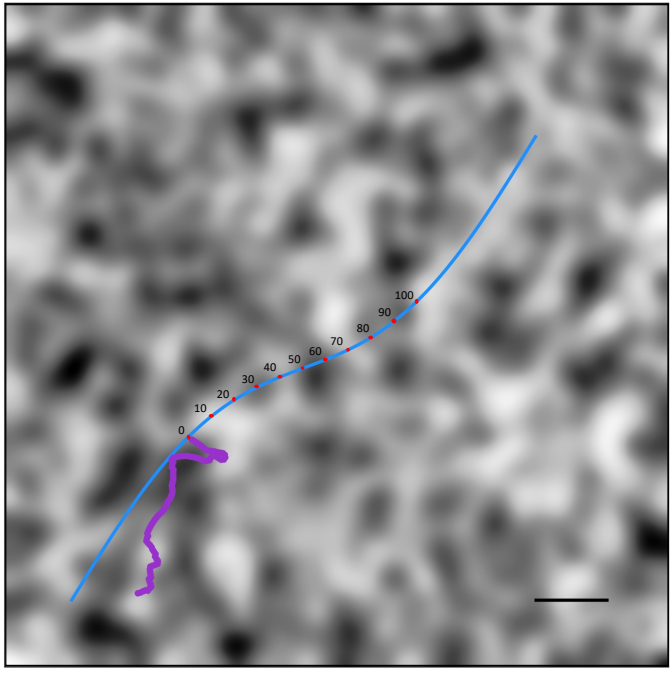
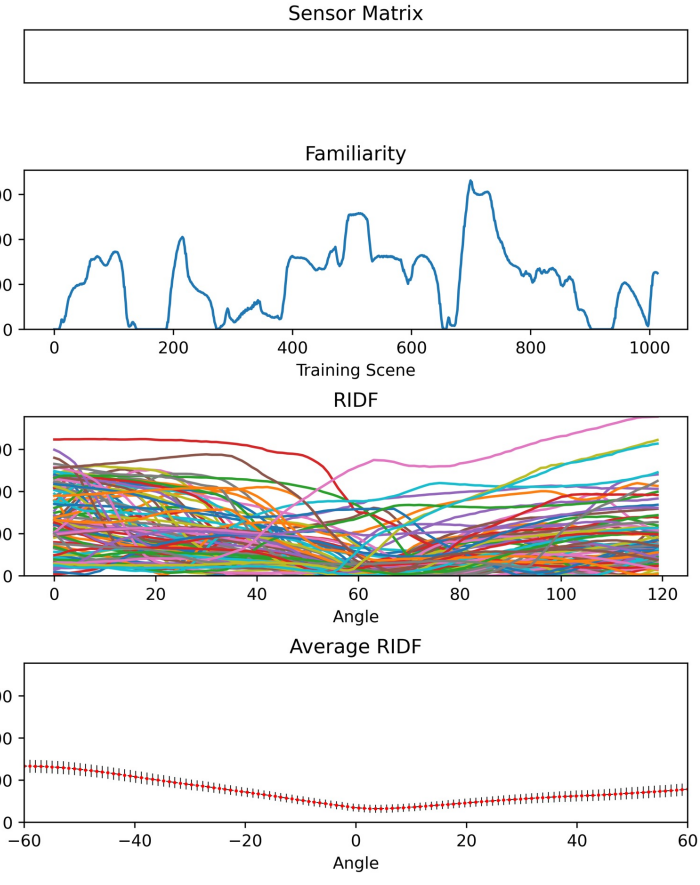
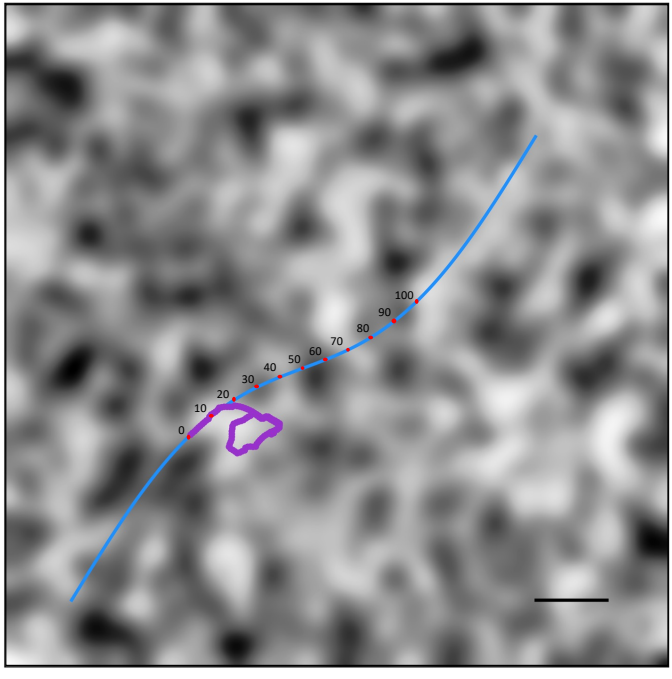


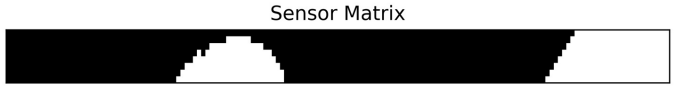


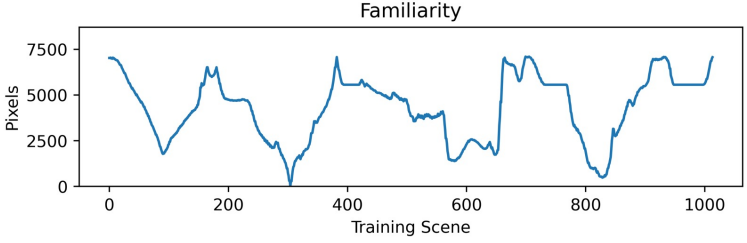
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

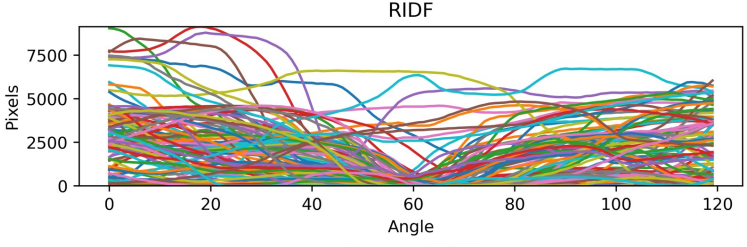
Navigation stats: RMSD error: 4533.25; RMSD/dist: 11.333; TD: 2206; p90: 84; p50: 46; complete: 0

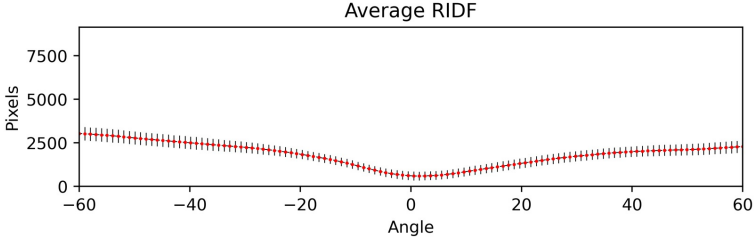
10%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4019.37; RMSD/dist: 10.048; TD: 2317; p90: 94; p50: 38; complete: 0