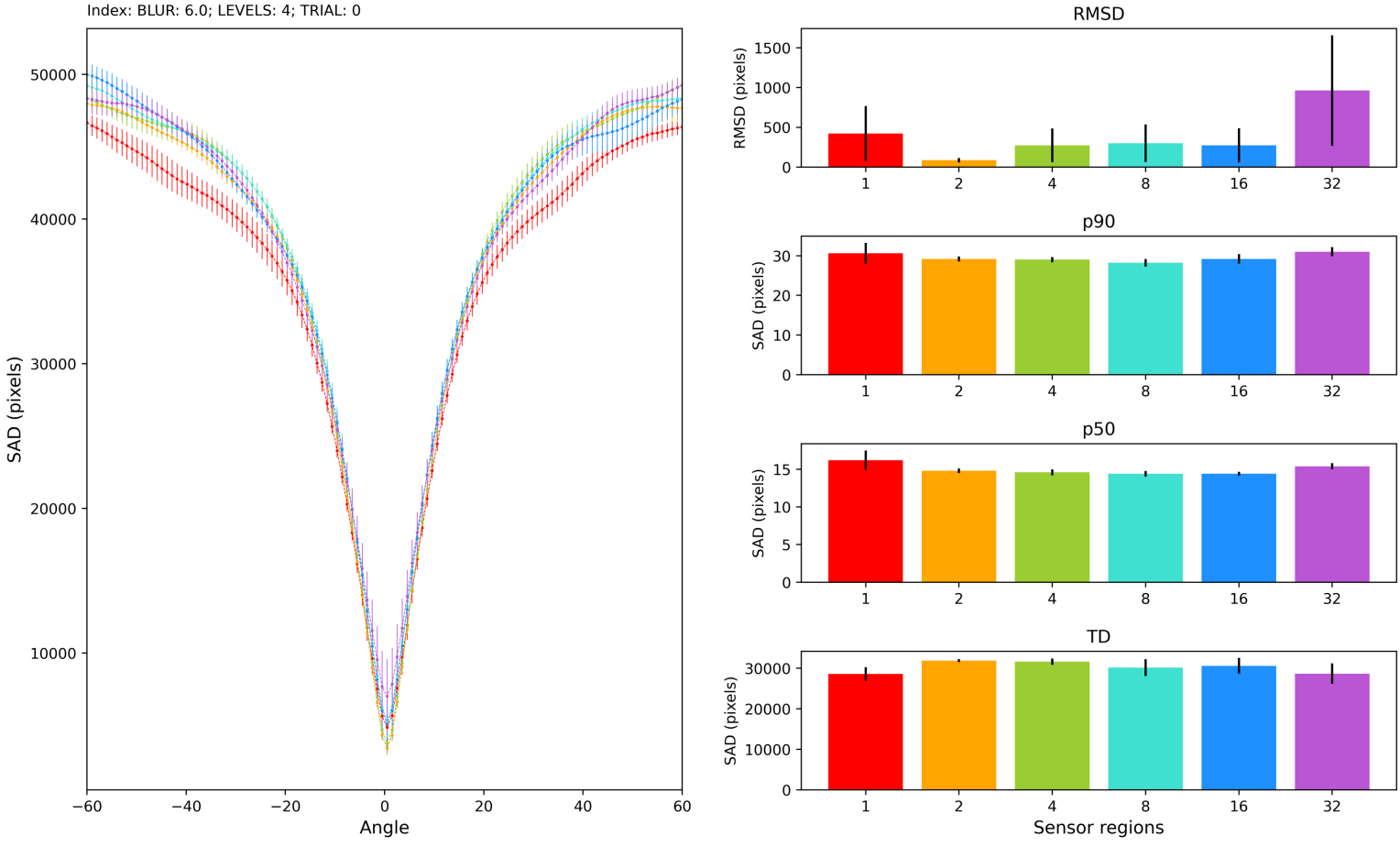
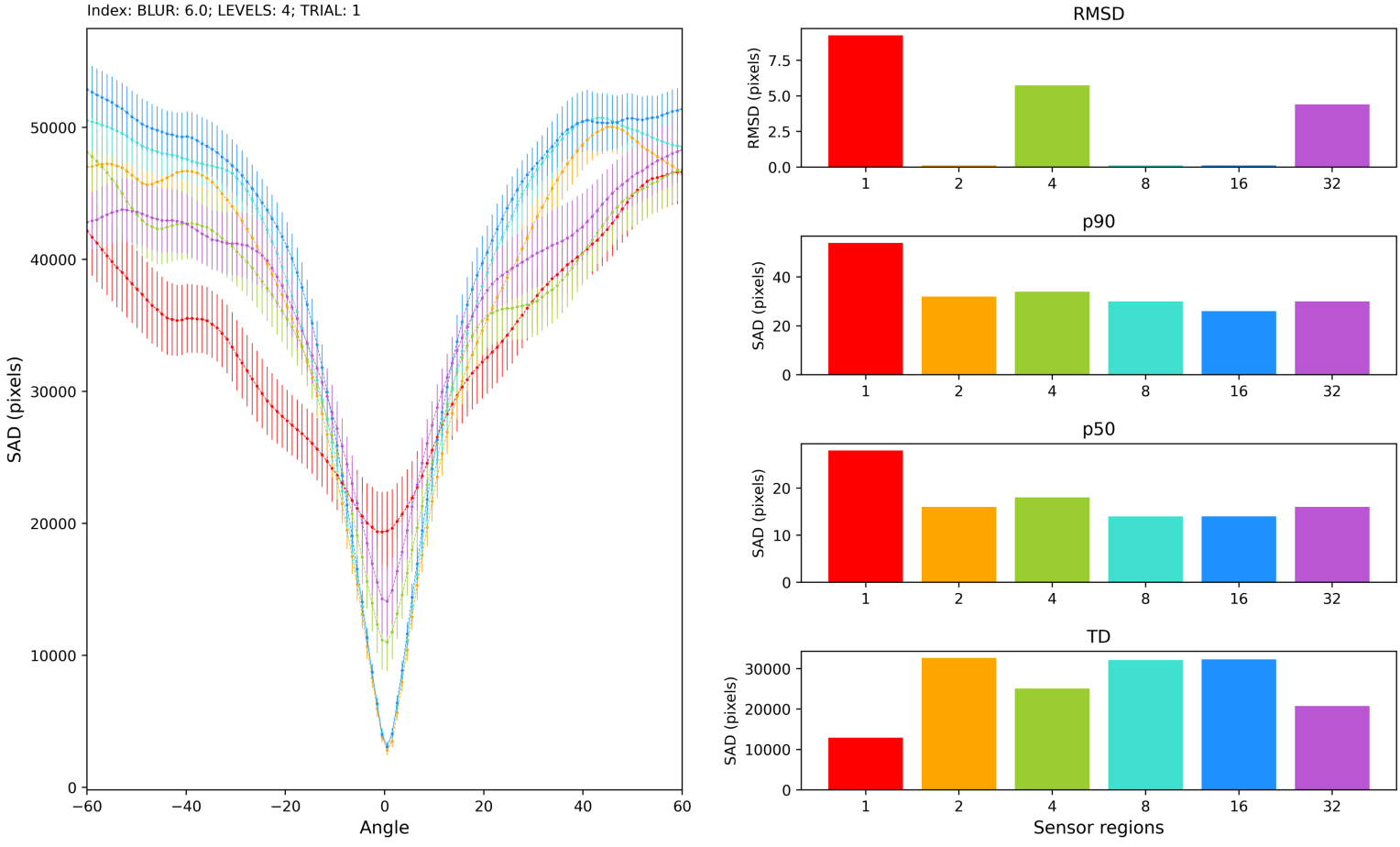
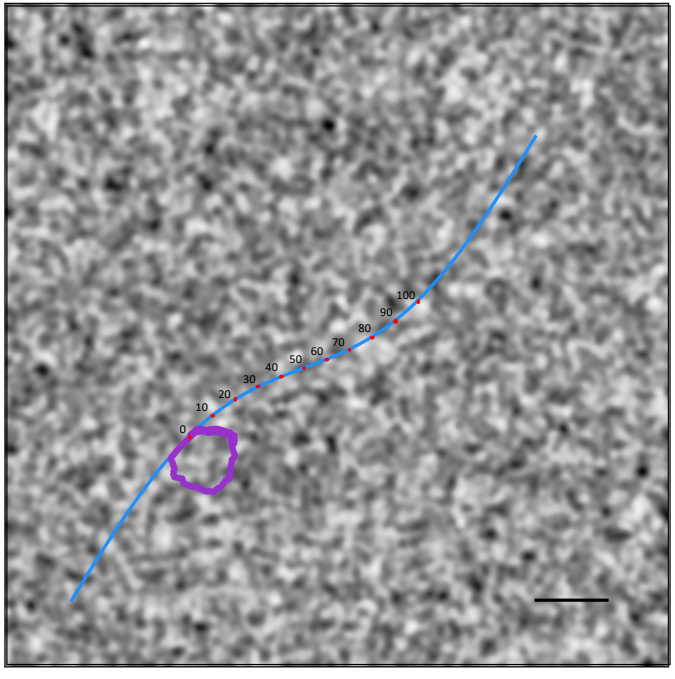
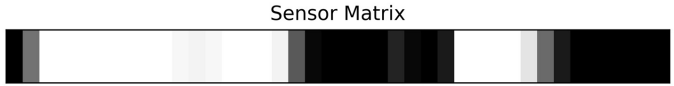
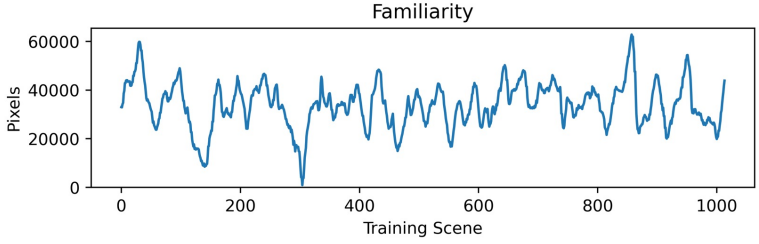

Index: BLUR: 6.0; LEVELS: 4; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

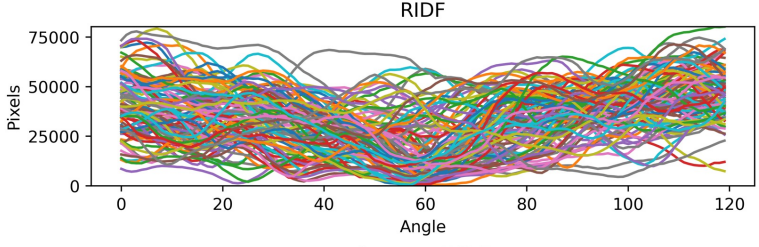

Index: BLUR: 6.0; LEVELS: 4; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

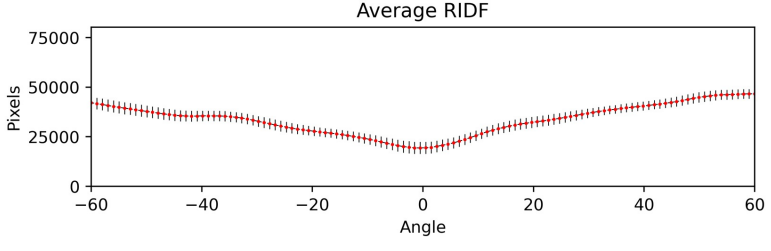
0%







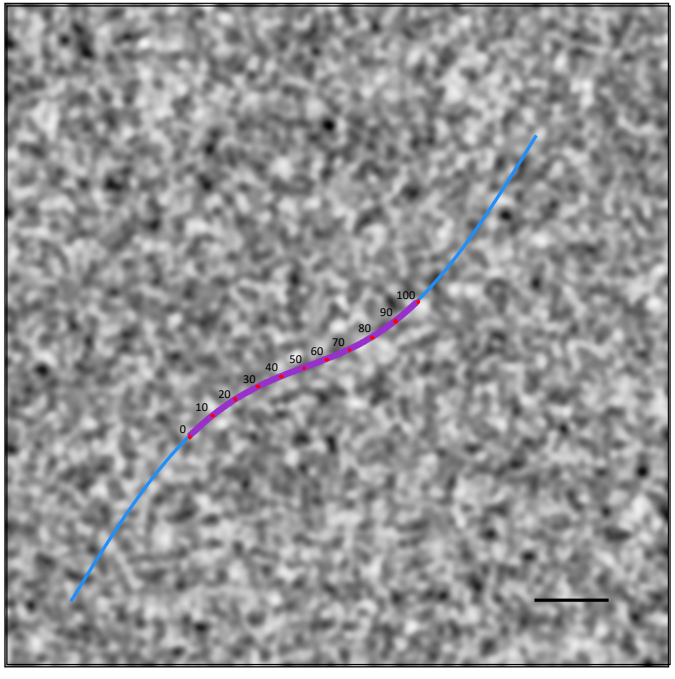


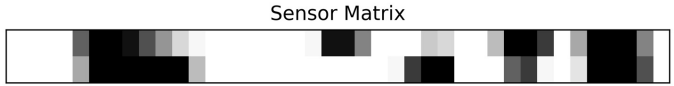


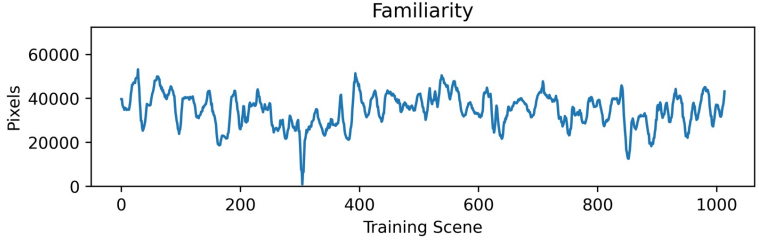
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

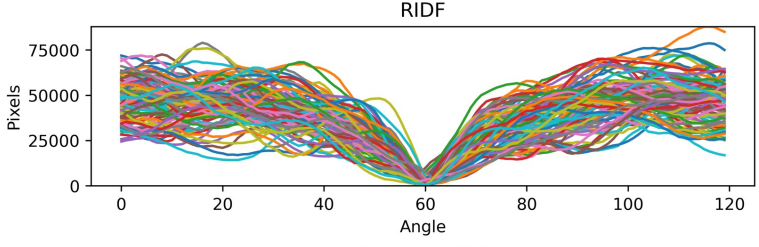
Navigation stats: RMSD error: 3702.83; RMSD/dist: 9.257; TD: 12916; p90: 54; p50: 28; complete: 0

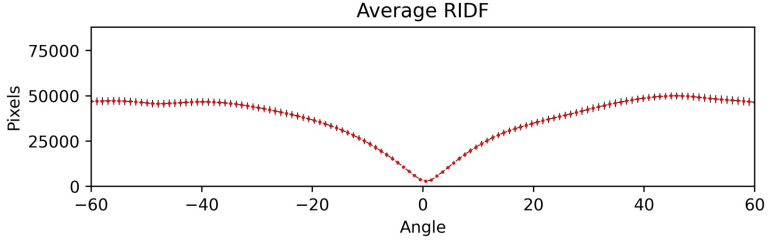
100%







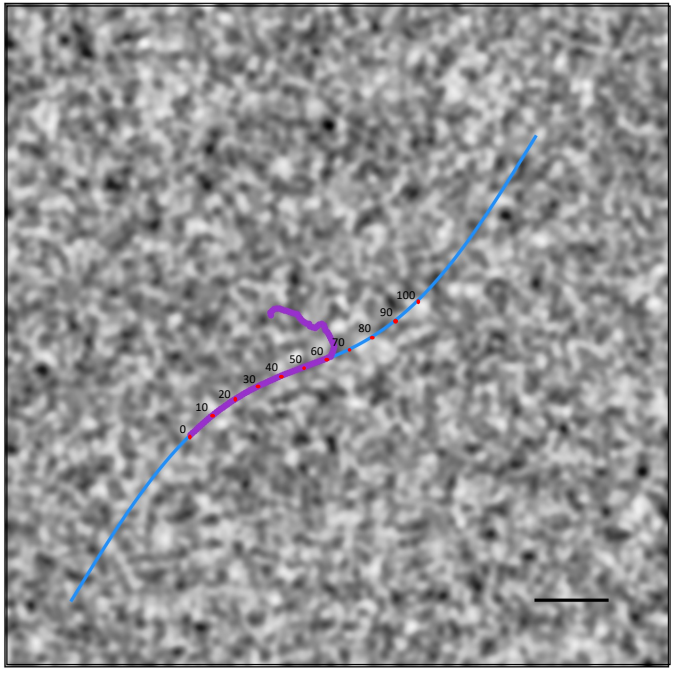


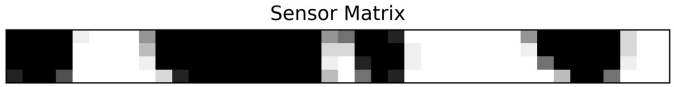


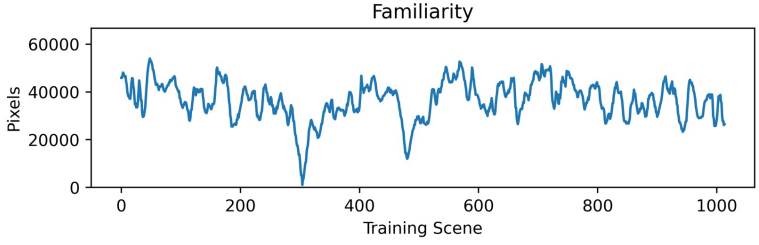
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

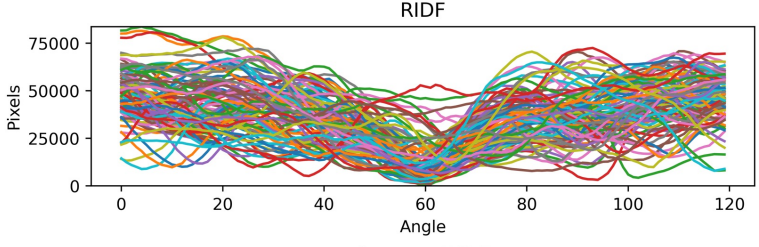
Navigation stats: RMSD error: 45.00; RMSD/dist: 0.112; TD: 32666; p90: 32; p50: 16; complete: 0

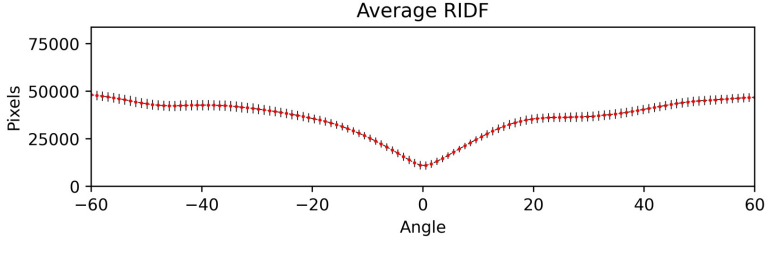
60%







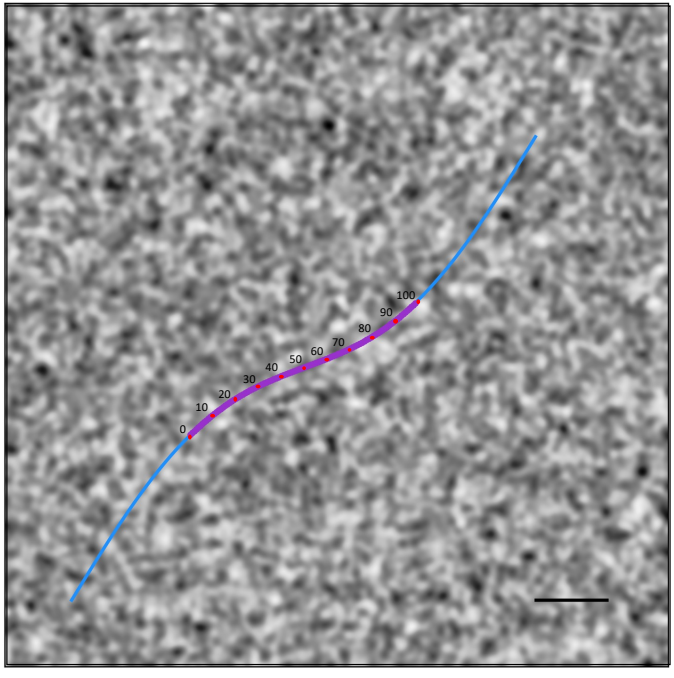


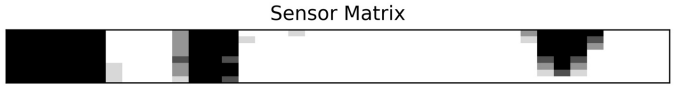


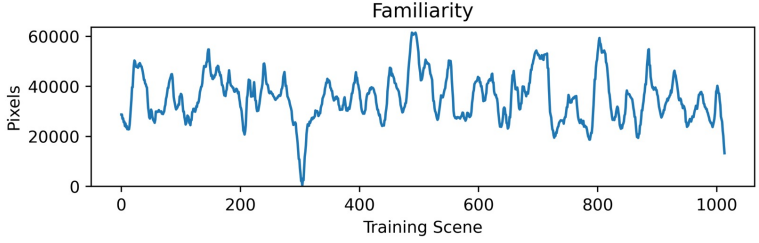
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

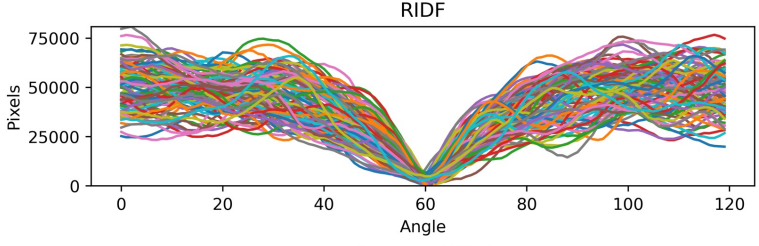
Navigation stats: RMSD error: 2292.75; RMSD/dist: 5.732; TD: 25127; p90: 34; p50: 18; complete: 0

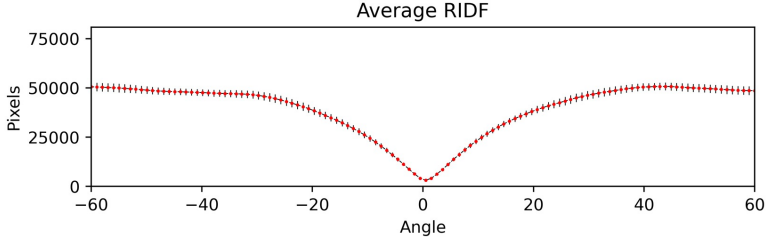
100%







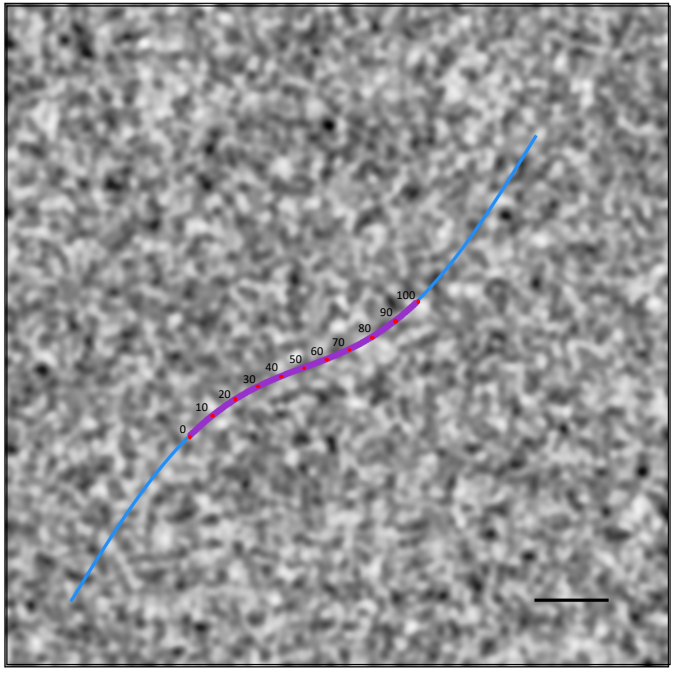


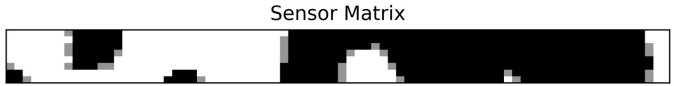


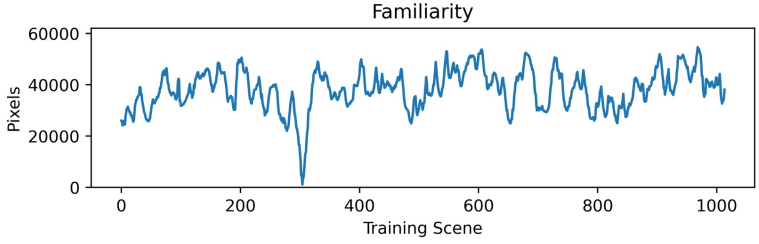
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

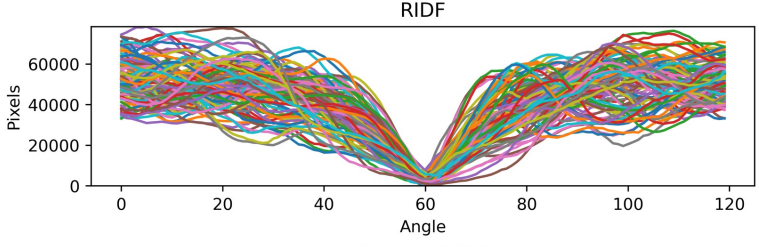
Navigation stats: RMSD error: 45.43; RMSD/dist: 0.114; TD: 32179; p90: 30; p50: 14; complete: 0

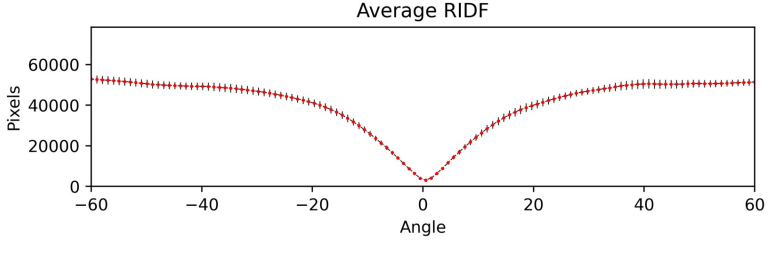
100%







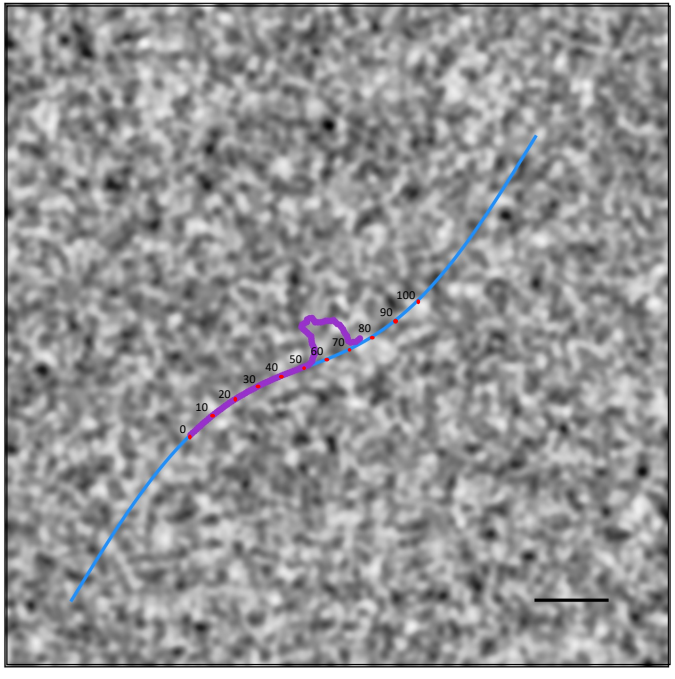


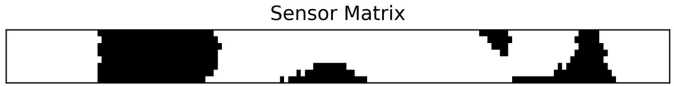


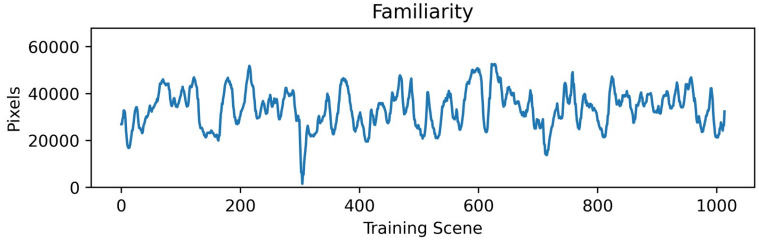
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

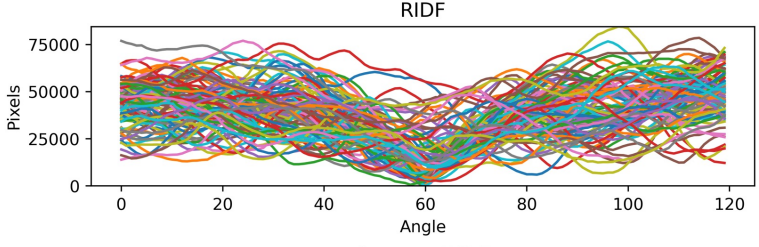
Navigation stats: RMSD error: 45.74; RMSD/dist: 0.114; TD: 32332; p90: 26; p50: 14; complete: 0

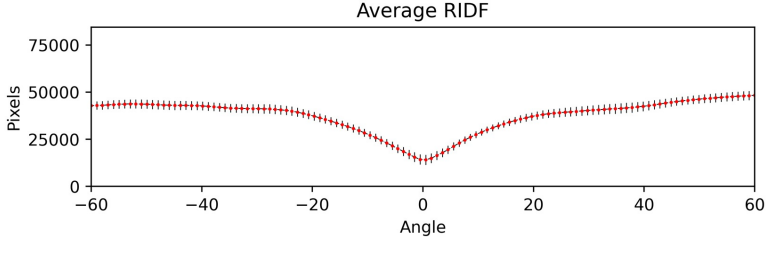
50%





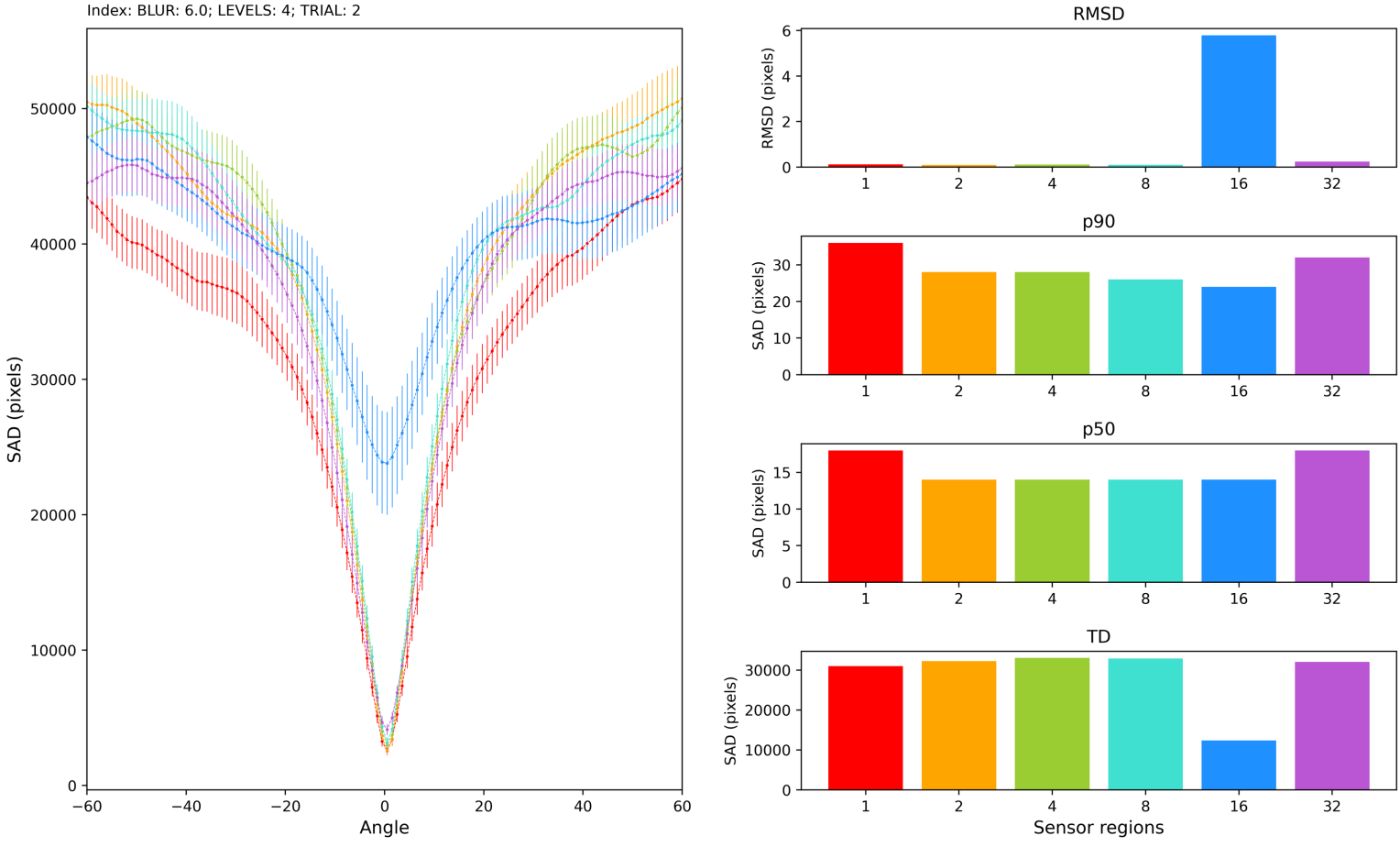




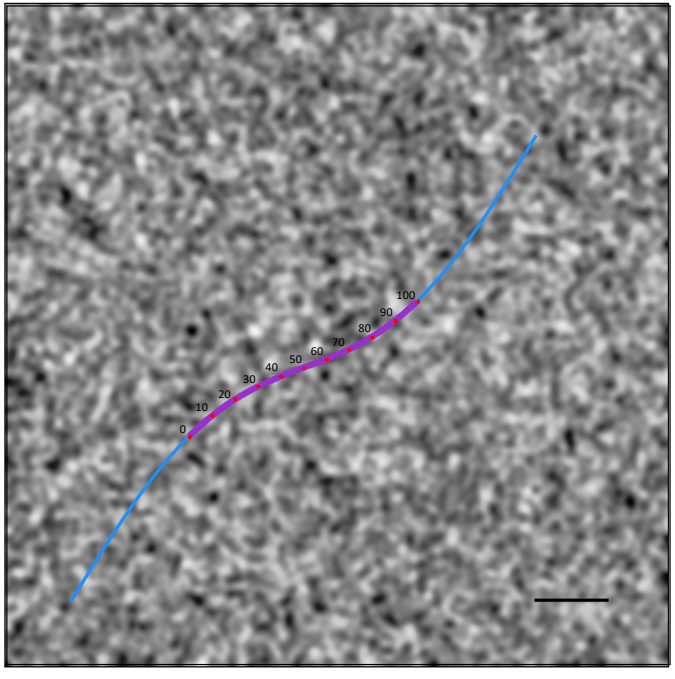


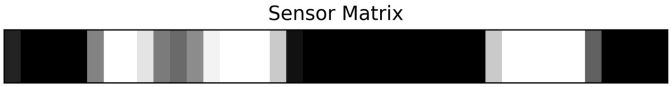
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

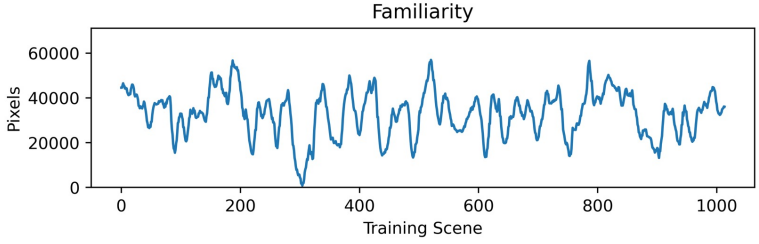
Navigation stats: RMSD error: 1762.08; RMSD/dist: 4.405; TD: 20763; p90: 30; p50: 16; complete: 0

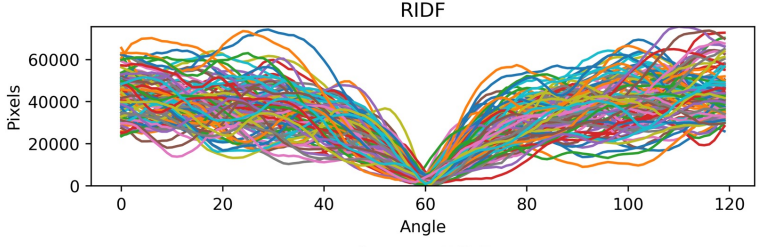

Index: BLUR: 6.0; LEVELS: 4; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

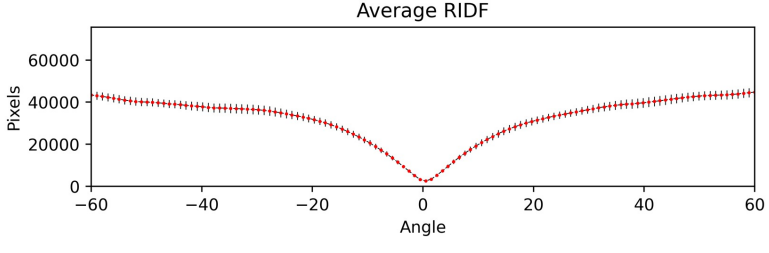
100%







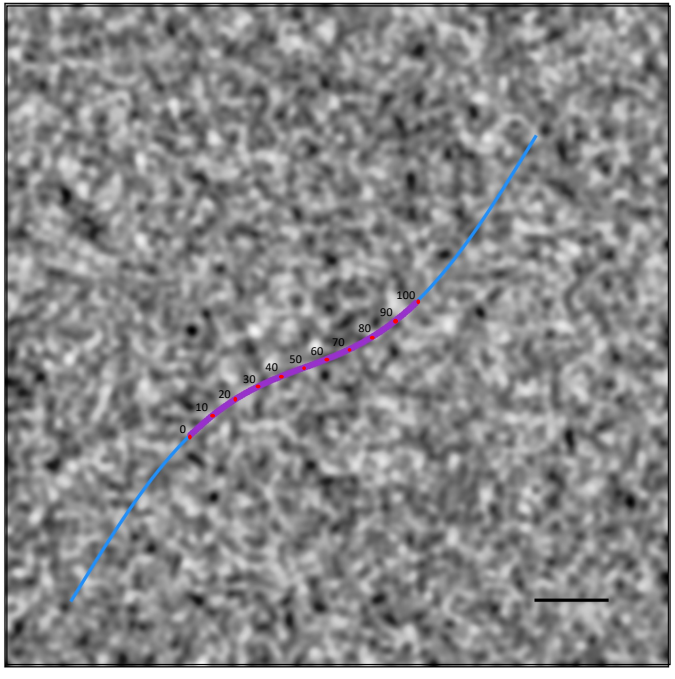


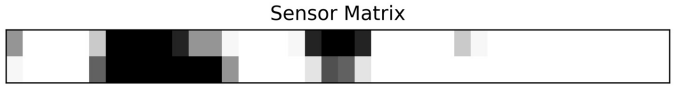


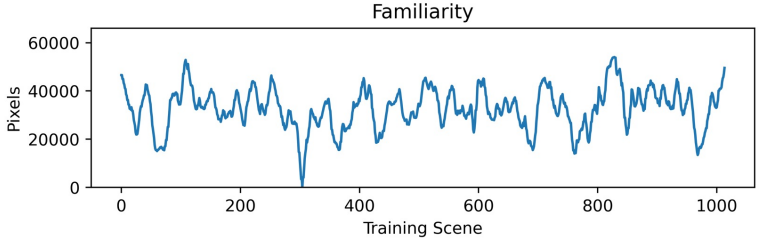
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

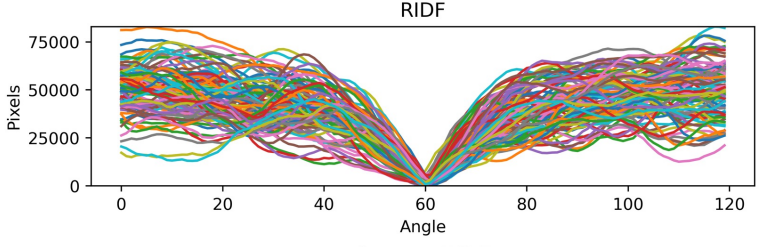
Navigation stats: RMSD error: 48.73; RMSD/dist: 0.122; TD: 30988; p90: 36; p50: 18; complete: 0

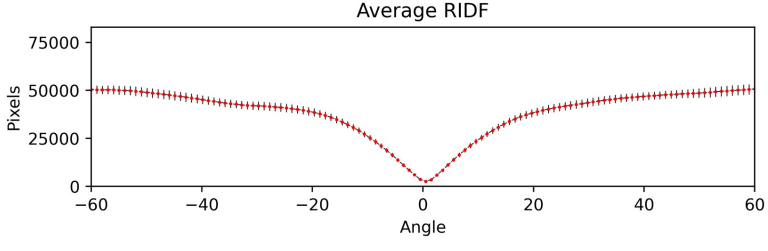
100%







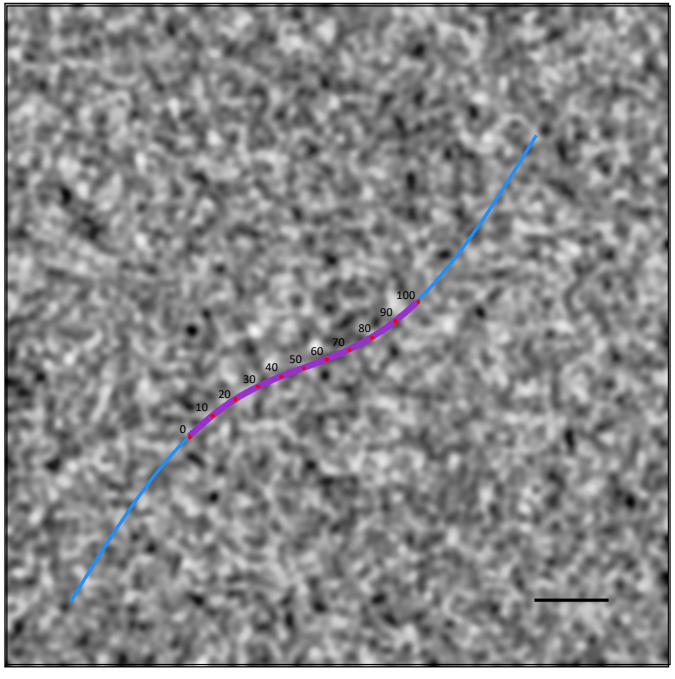


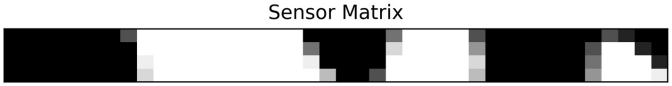


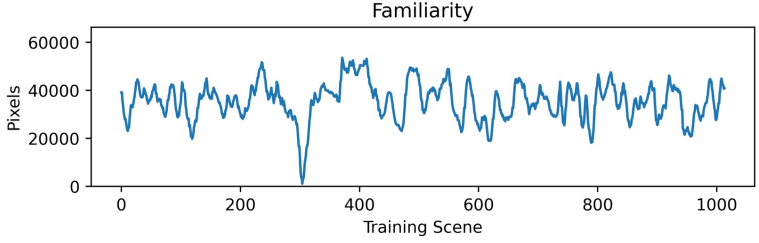
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

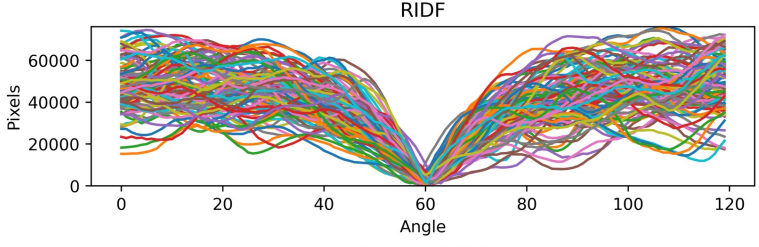
Navigation stats: RMSD error: 34.99; RMSD/dist: 0.087; TD: 32230; p90: 28; p50: 14; complete: 0

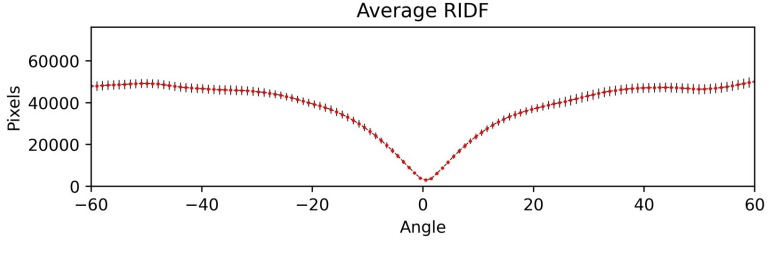
100%







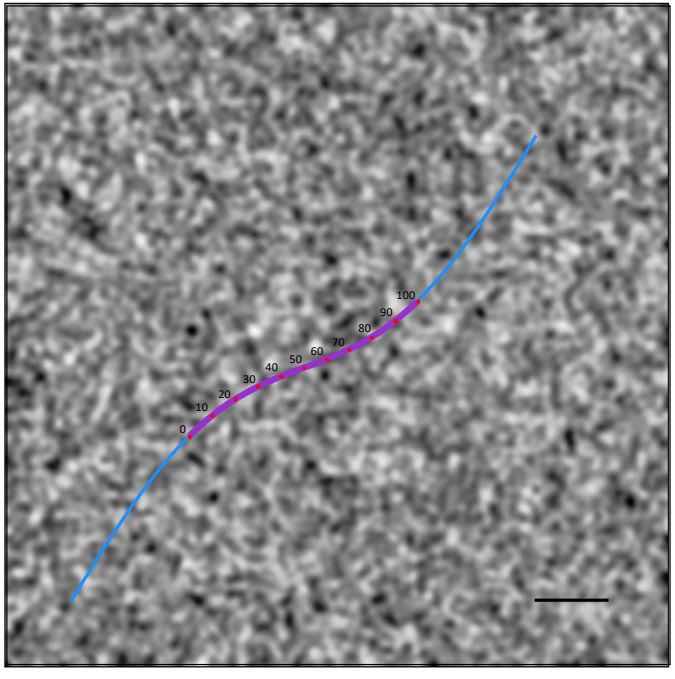


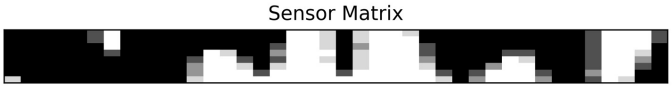


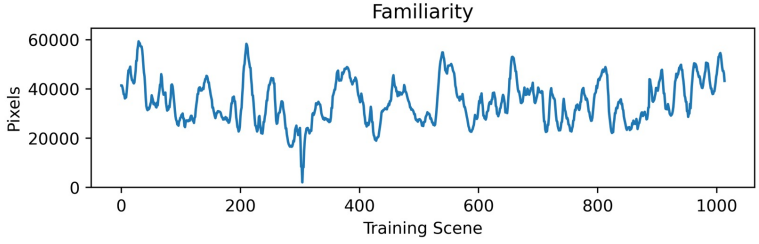
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

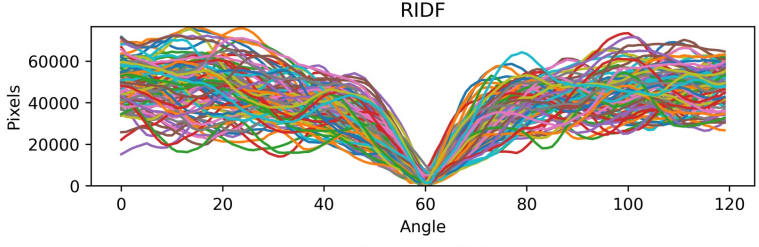
Navigation stats: RMSD error: 42.59; RMSD/dist: 0.106; TD: 33016; p90: 28; p50: 14; complete: 0

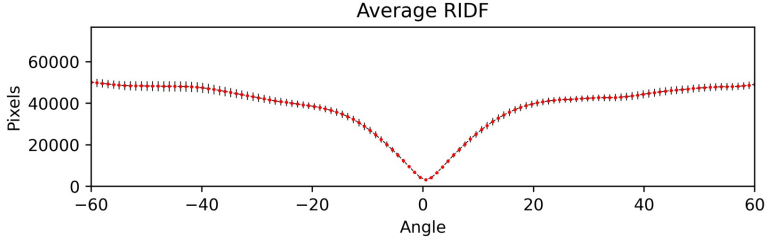
100%











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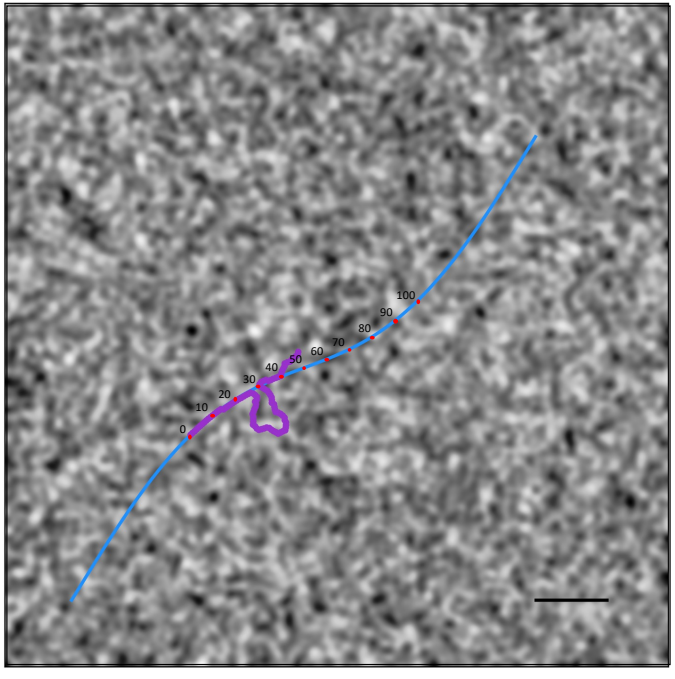
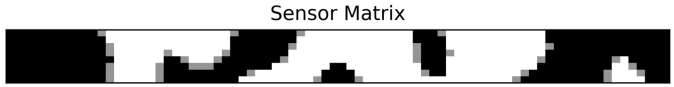
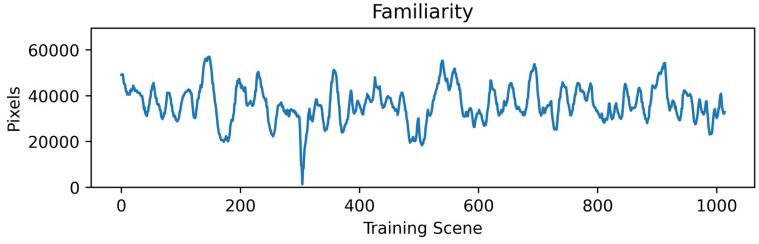
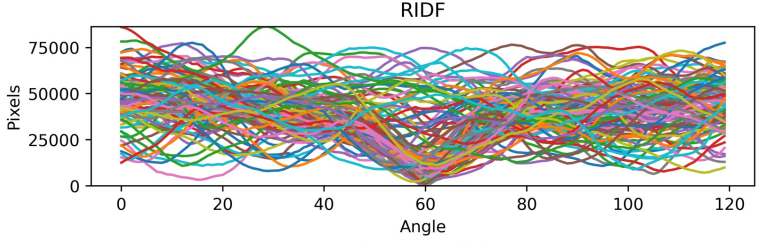
Navigation stats: RMSD error: 40.35; RMSD/dist: 0.101; TD: 32875; p90: 26; p50: 14; complete: 0

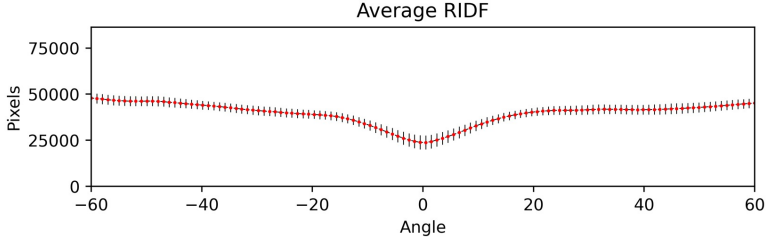
30%











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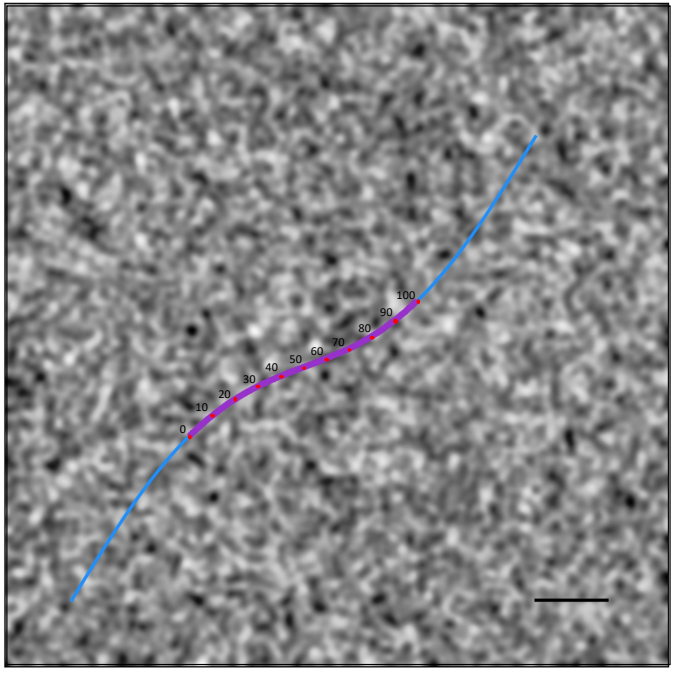
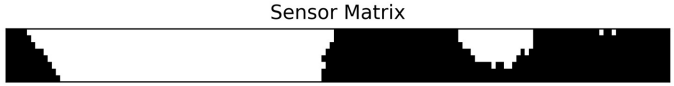
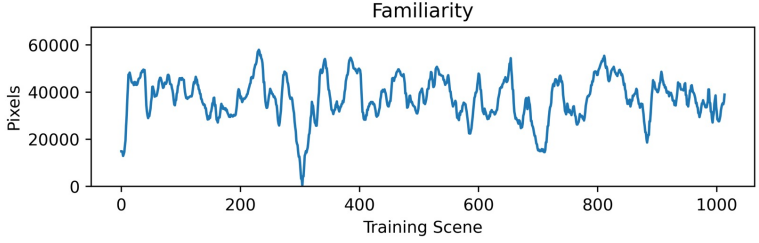
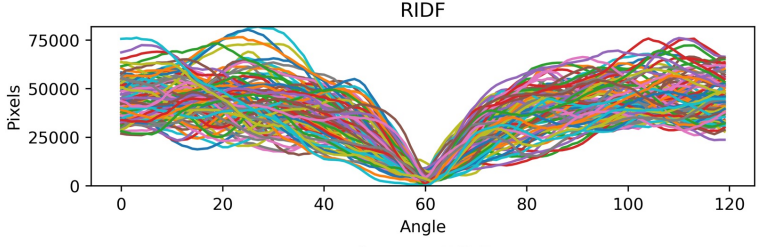
Navigation stats: RMSD error: 2317.87; RMSD/dist: 5.795; TD: 12337; p90: 24; p50: 14; complete: 0

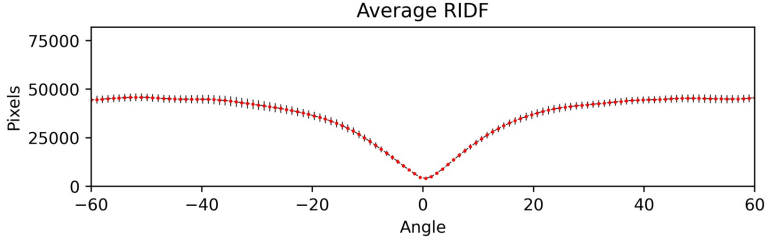
100%





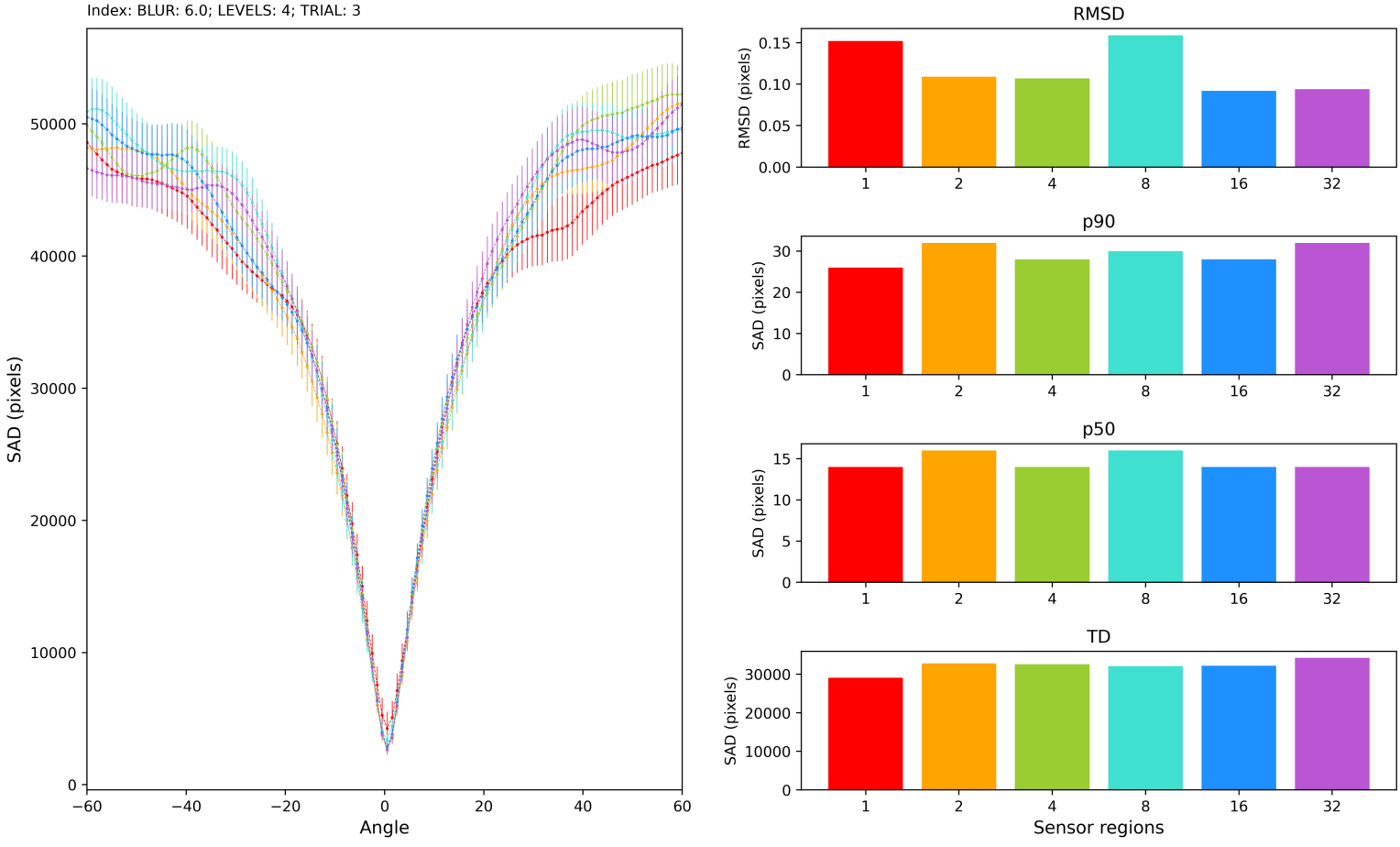




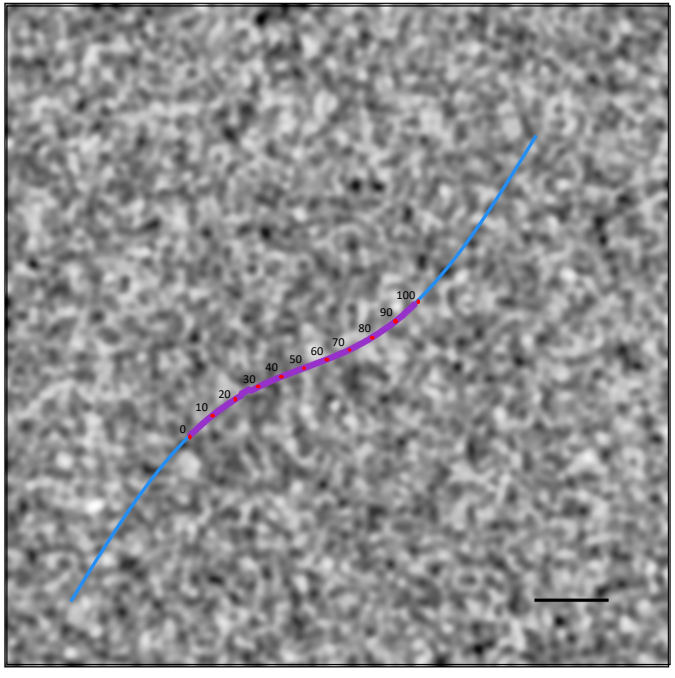


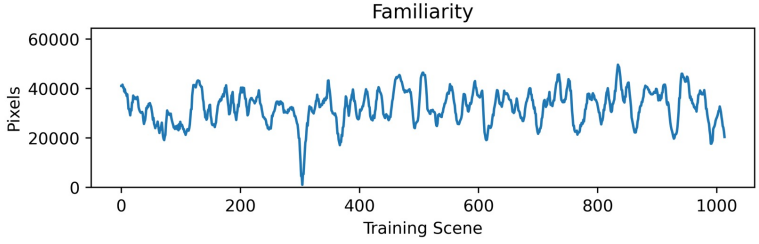
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

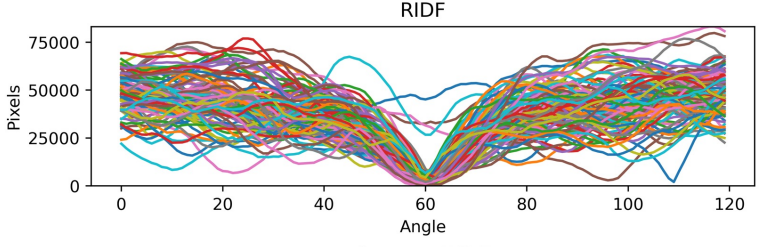
Navigation stats: RMSD error: 94.50; RMSD/dist: 0.236; TD: 32058; p90: 32; p50: 18; complete: 0

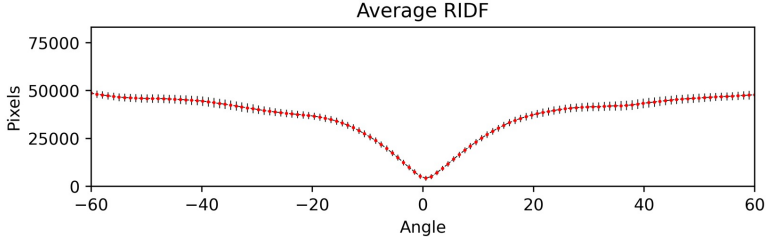

Index: BLUR: 6.0; LEVELS: 4; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

100%





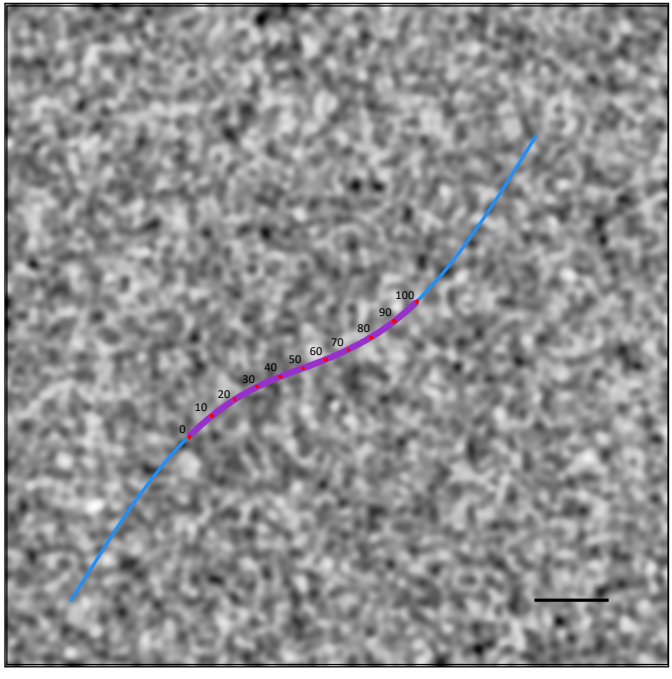


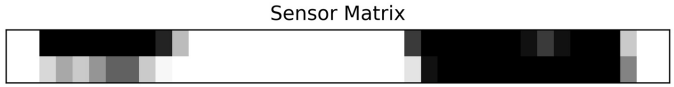


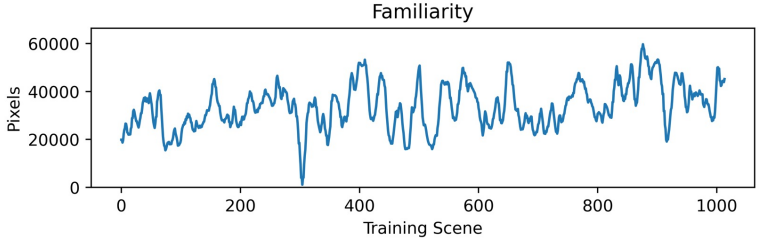
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

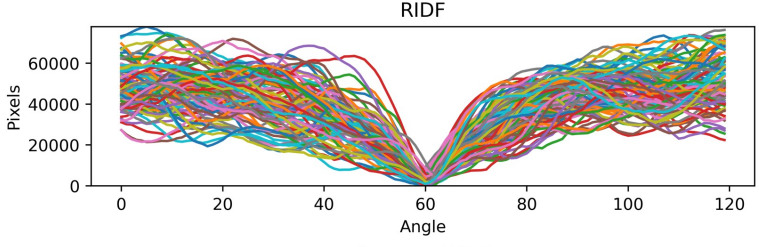
Navigation stats: RMSD error: 60.63; RMSD/dist: 0.152; TD: 29072; p90: 26; p50: 14; complete: 0

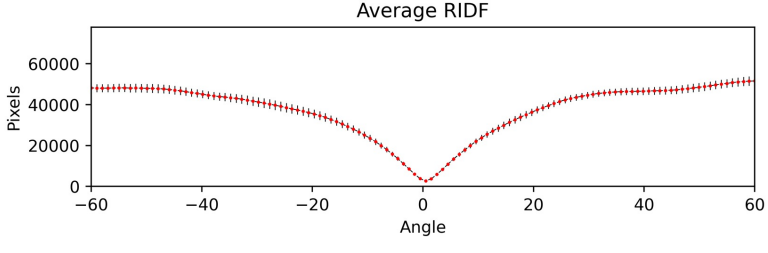
100%







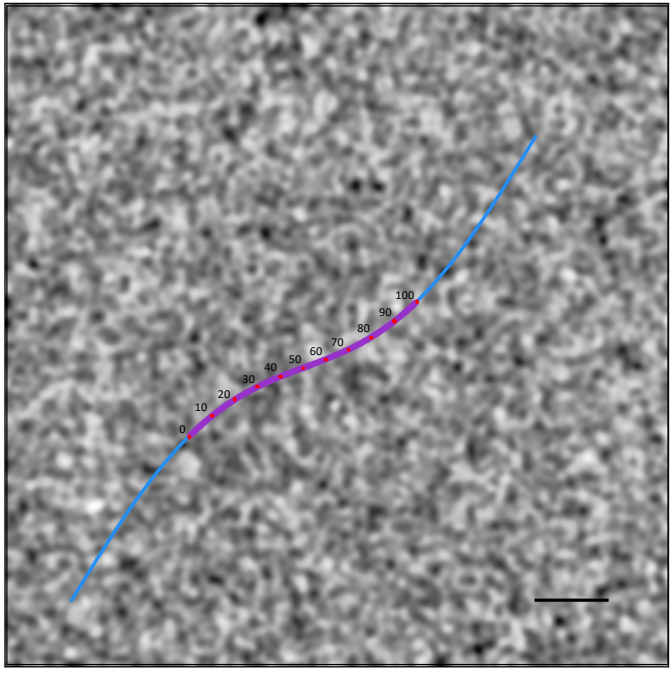


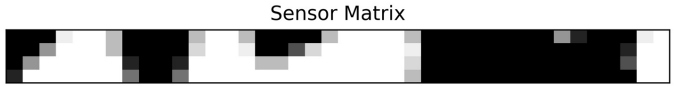


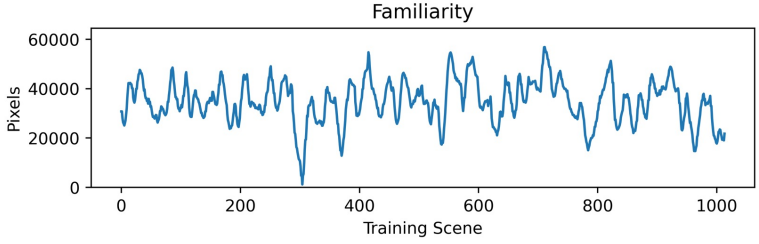
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

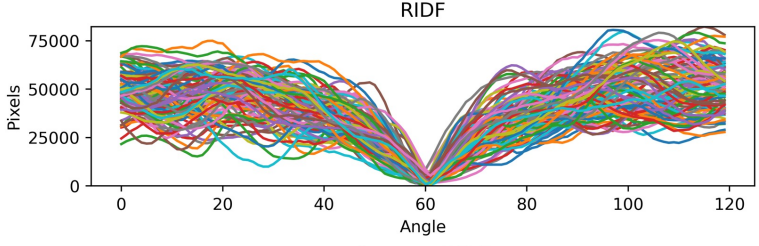
Navigation stats: RMSD error: 43.73; RMSD/dist: 0.109; TD: 32803; p90: 32; p50: 16; complete: 0

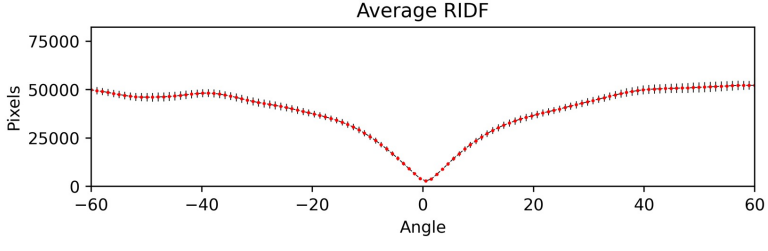
100%







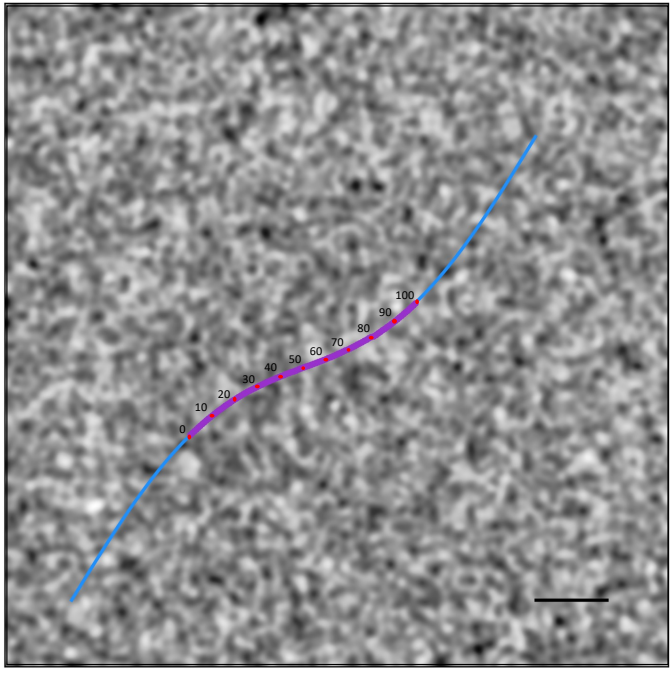


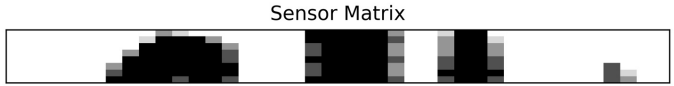


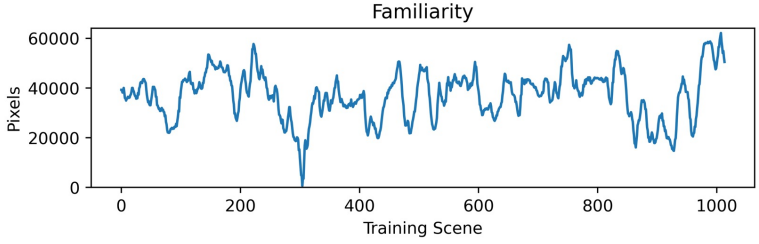
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

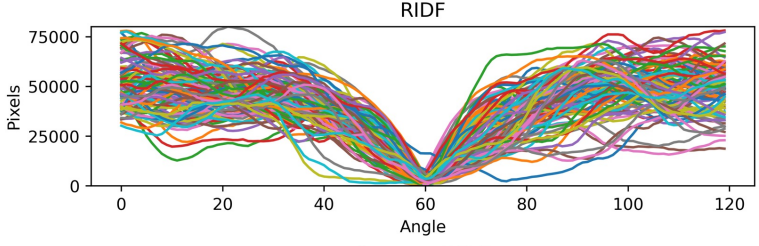
Navigation stats: RMSD error: 42.67; RMSD/dist: 0.107; TD: 32571; p90: 28; p50: 14; complete: 0

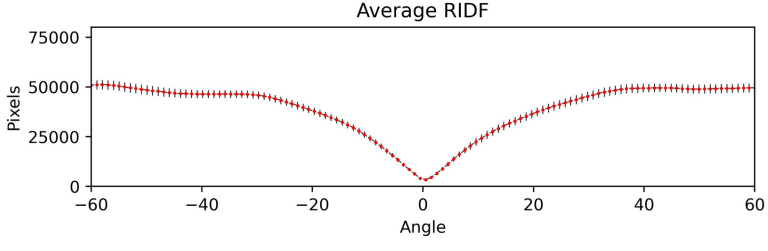
100%







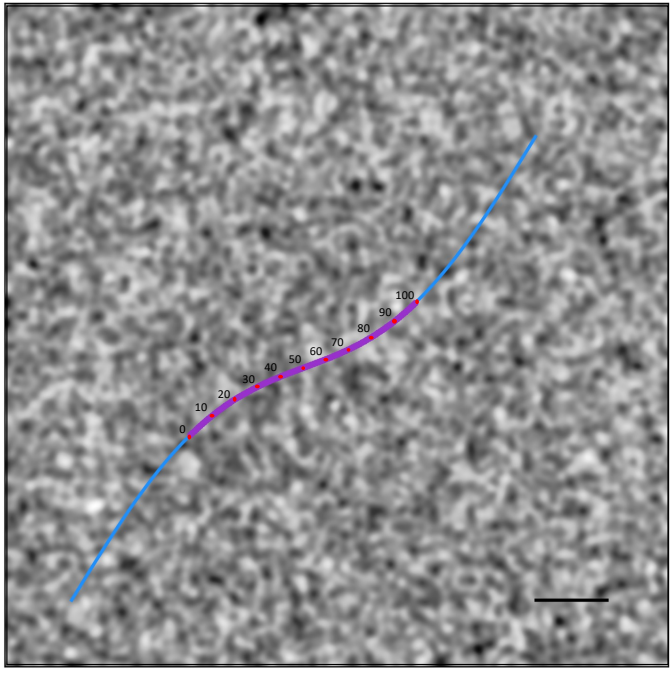


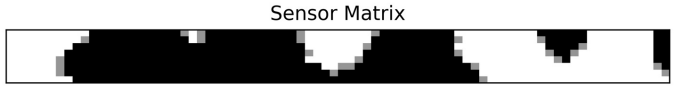


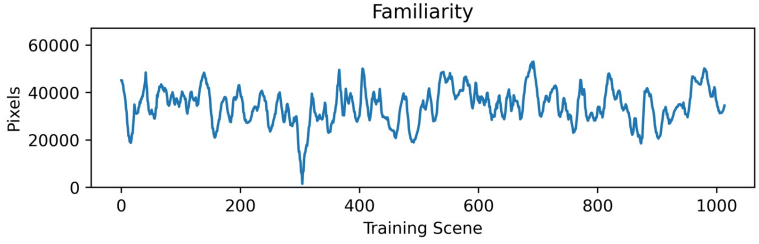
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

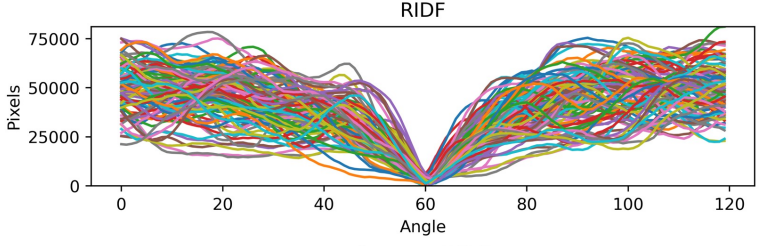
Navigation stats: RMSD error: 63.47; RMSD/dist: 0.159; TD: 32084; p90: 30; p50: 16; complete: 0

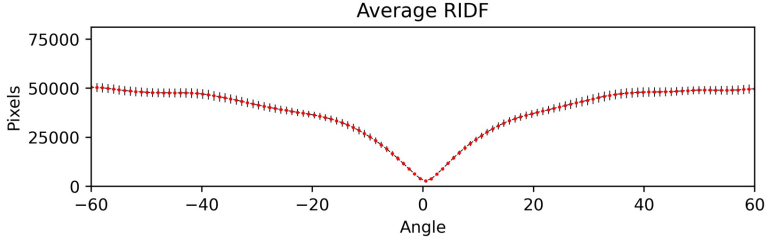
100%







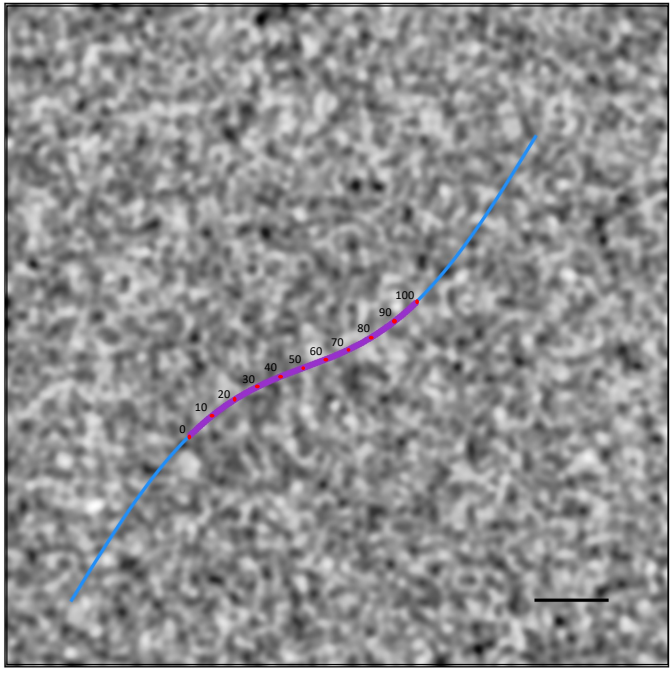


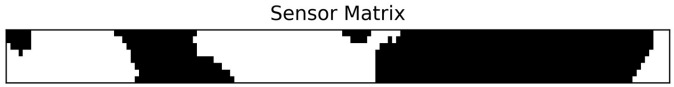


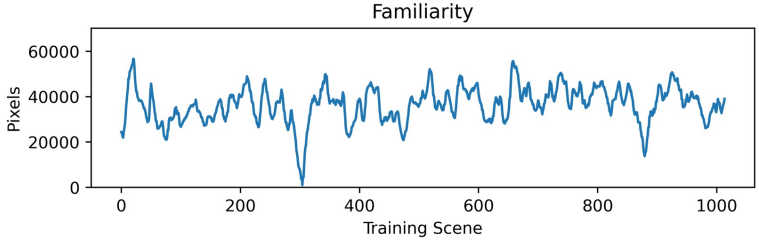
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

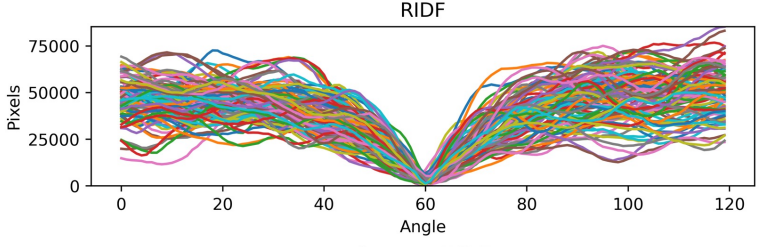
Navigation stats: RMSD error: 36.78; RMSD/dist: 0.092; TD: 32221; p90: 28; p50: 14; complete: 0

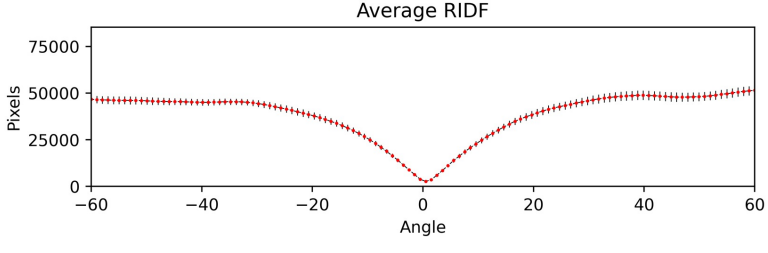
100%





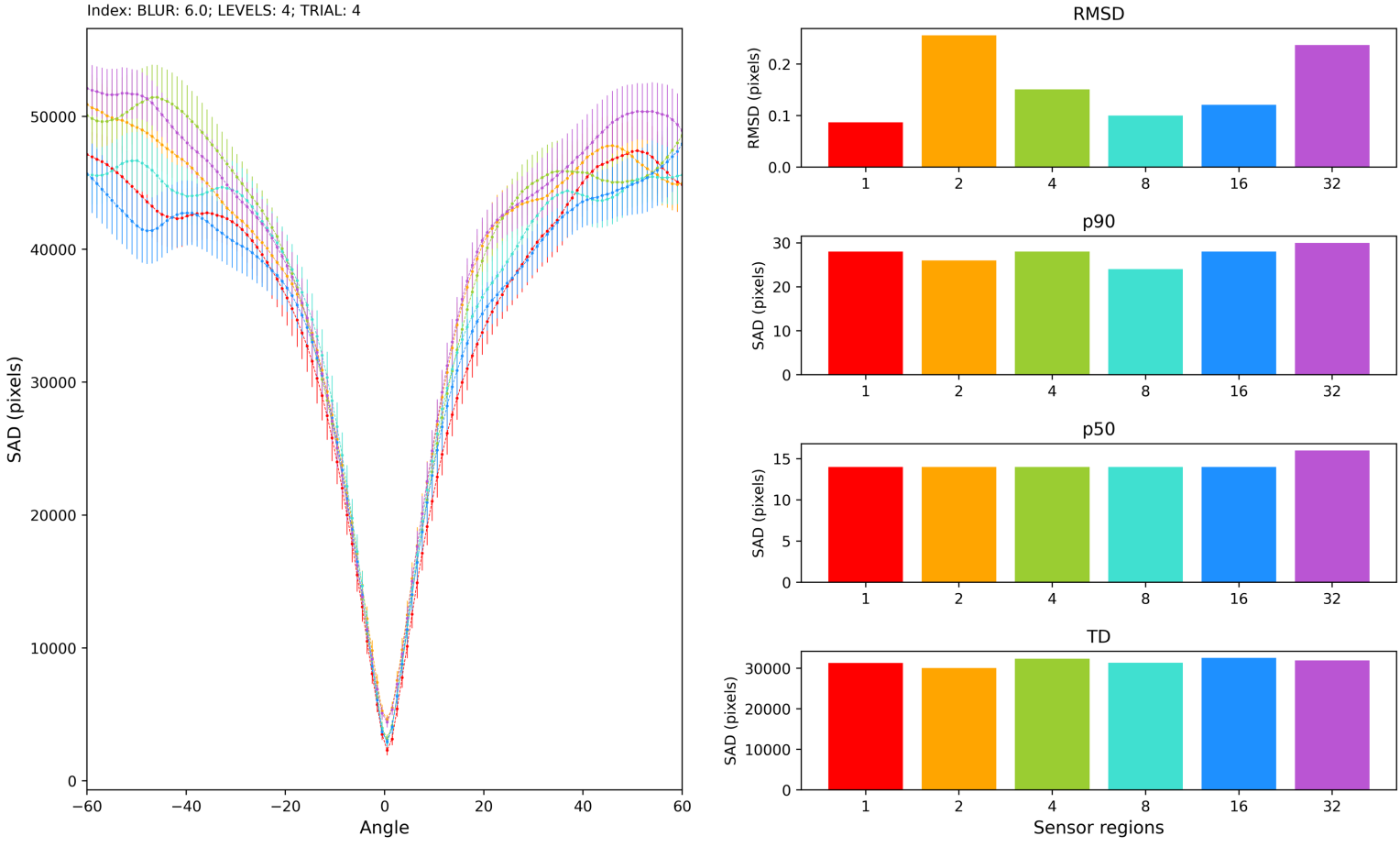




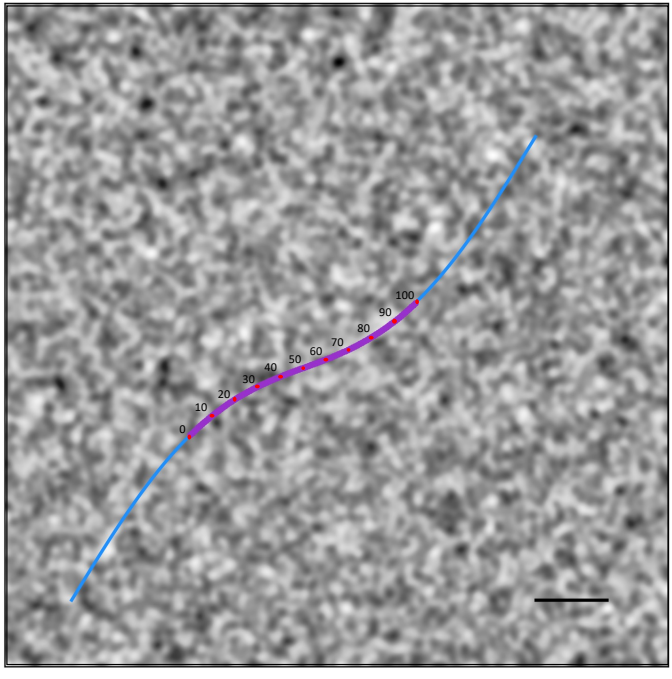


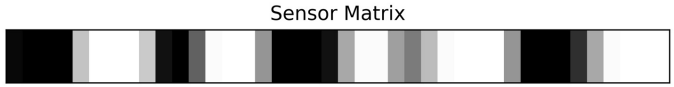
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

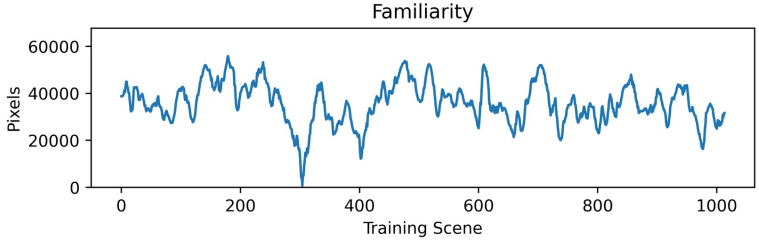
Navigation stats: RMSD error: 37.61; RMSD/dist: 0.094; TD: 34211; p90: 32; p50: 14; complete: 0

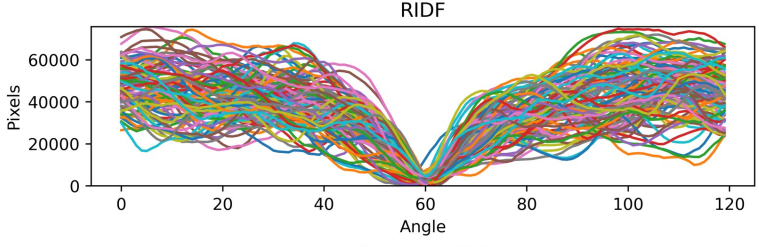

Index: BLUR: 6.0; LEVELS: 4; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

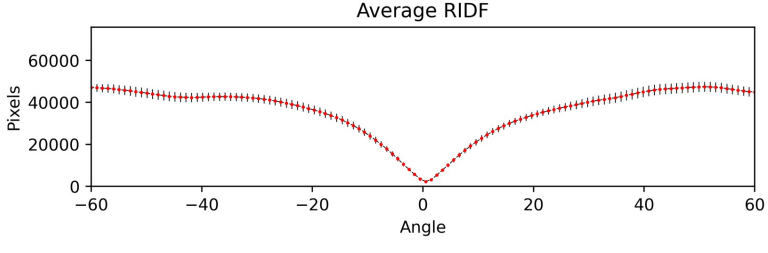
100%







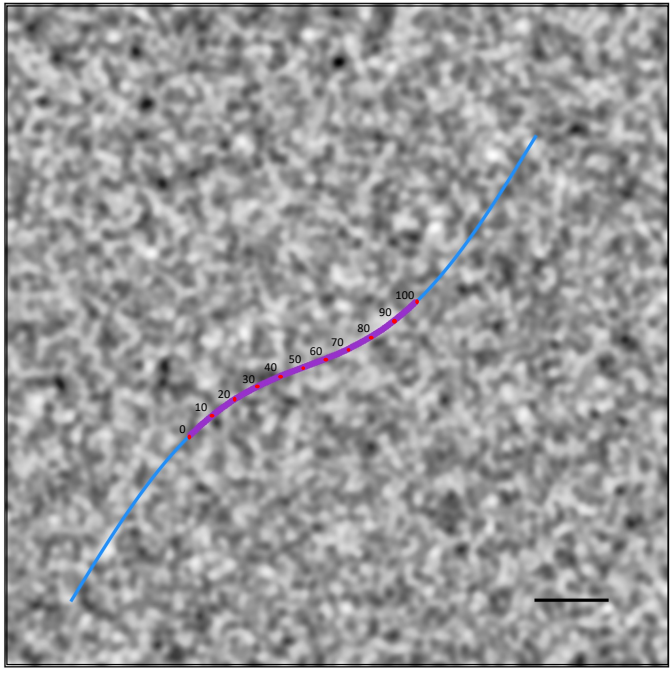


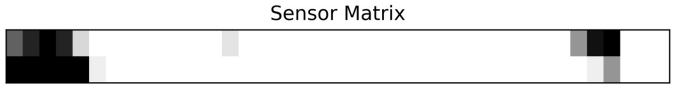


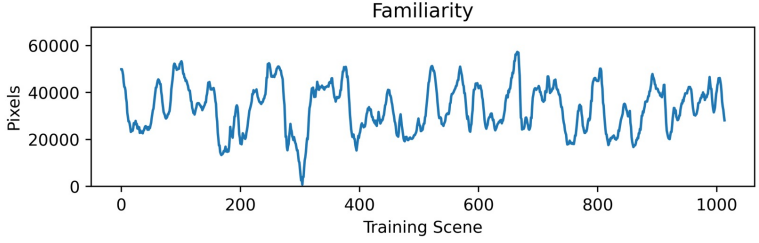
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

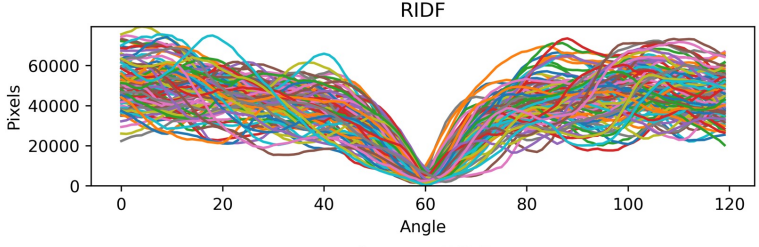
Navigation stats: RMSD error: 34.82; RMSD/dist: 0.087; TD: 31310; p90: 28; p50: 14; complete: 0

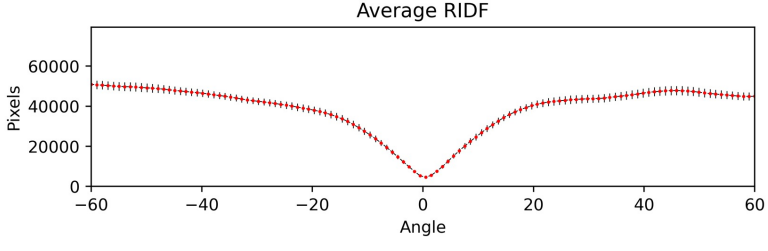
100%







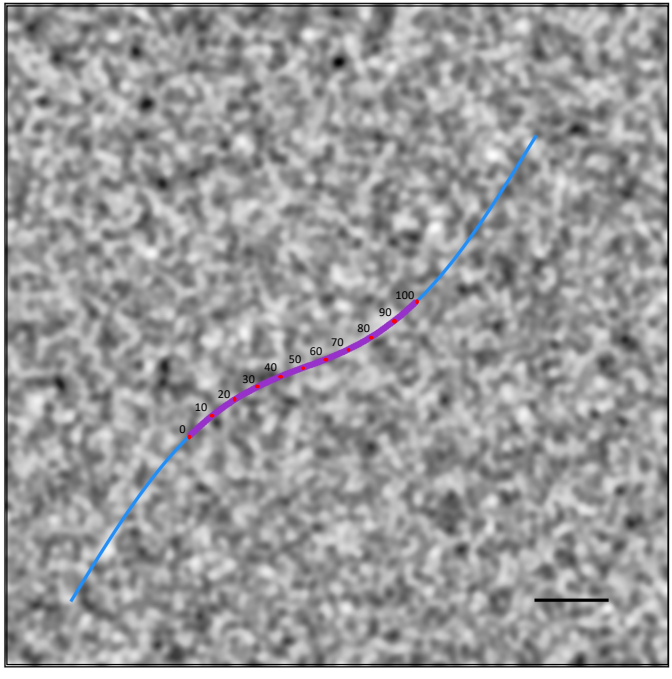


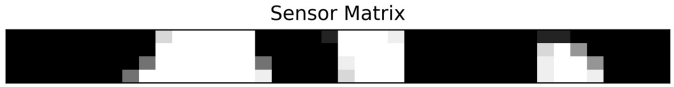


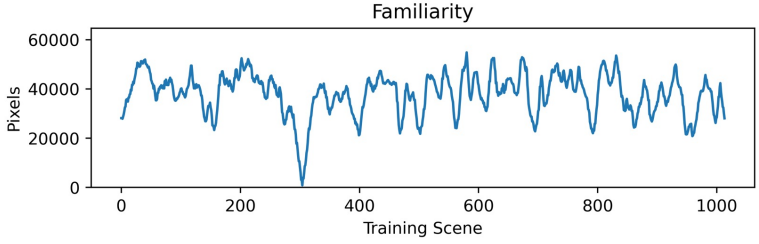
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

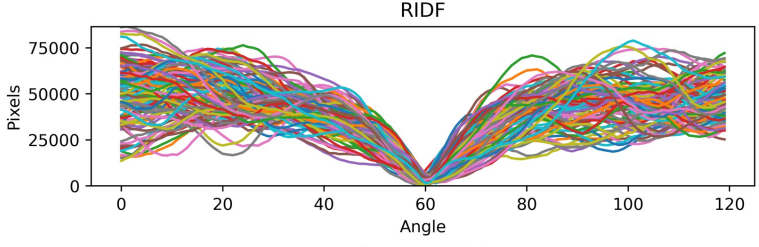
Navigation stats: RMSD error: 102.58; RMSD/dist: 0.256; TD: 30041; p90: 26; p50: 14; complete: 0

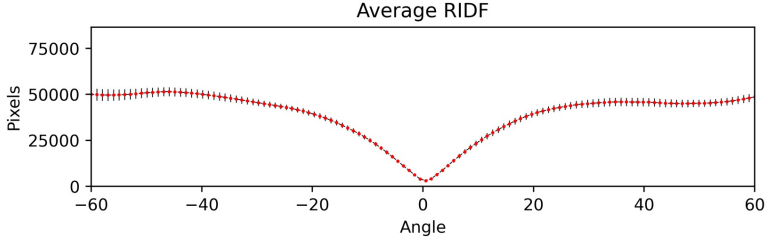
100%







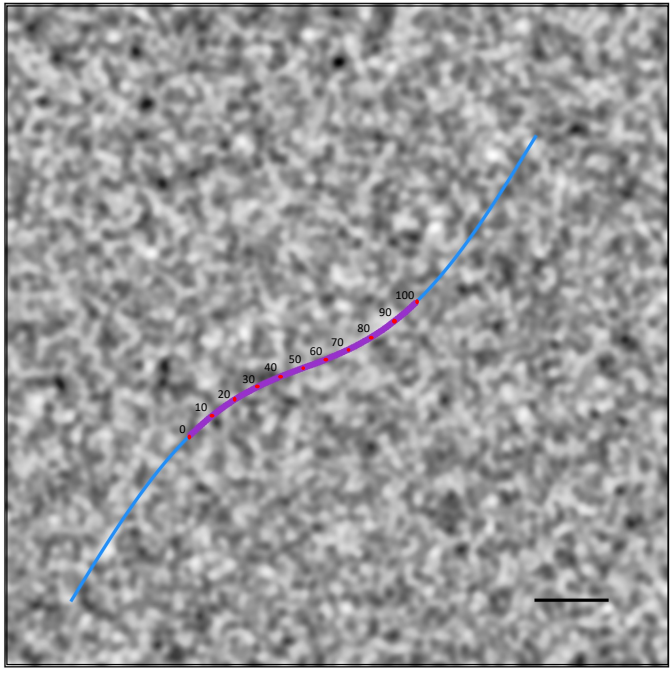


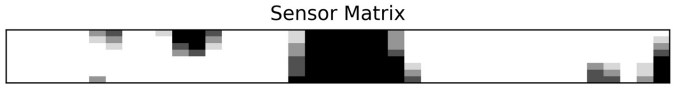


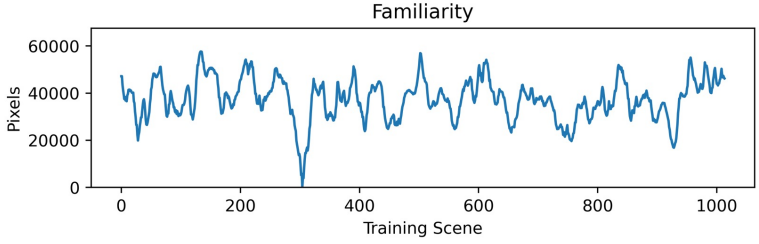
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

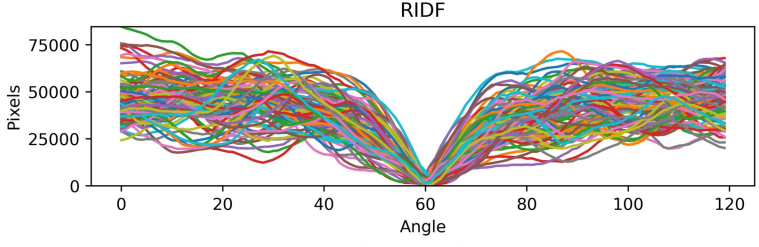
Navigation stats: RMSD error: 60.25; RMSD/dist: 0.151; TD: 32314; p90: 28; p50: 14; complete: 0

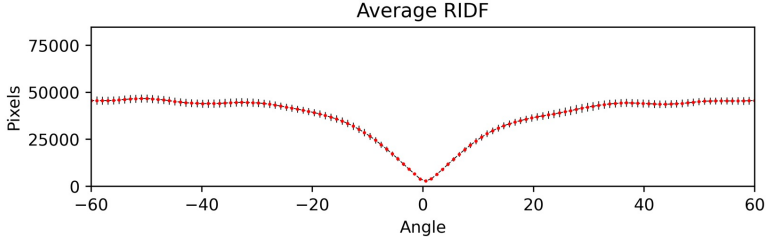
100%







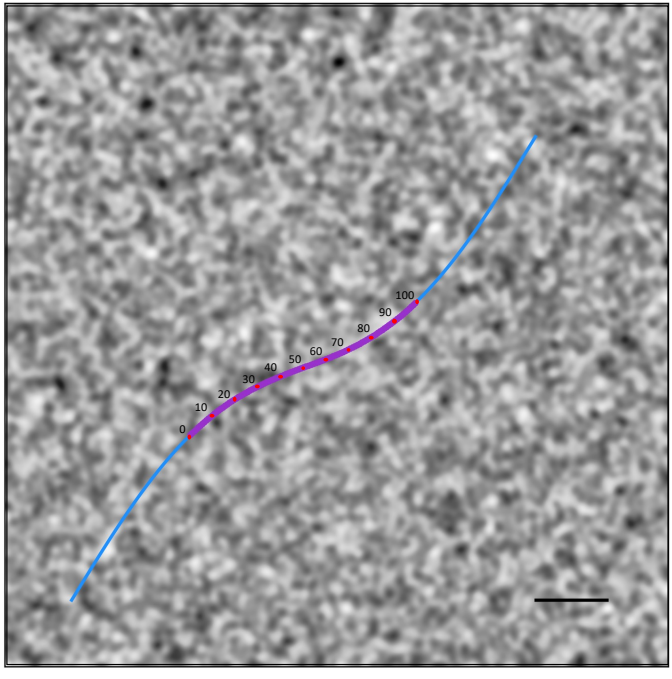


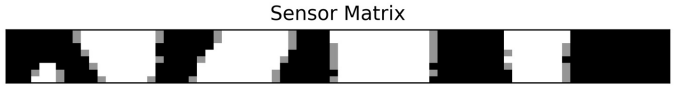


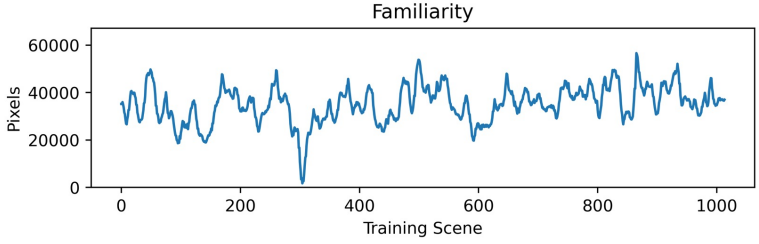
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

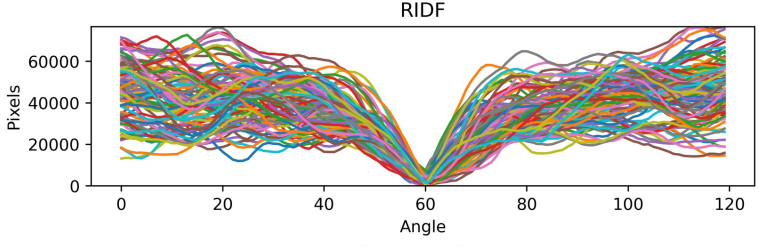
Navigation stats: RMSD error: 39.91; RMSD/dist: 0.100; TD: 31356; p90: 24; p50: 14; complete: 0

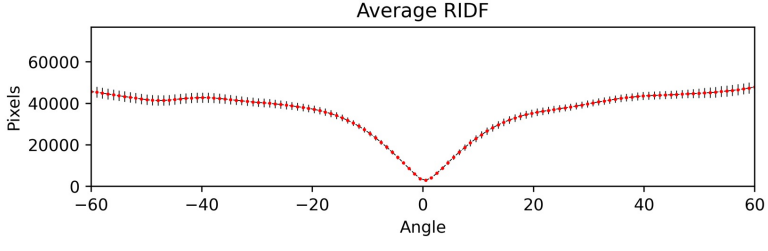
100%







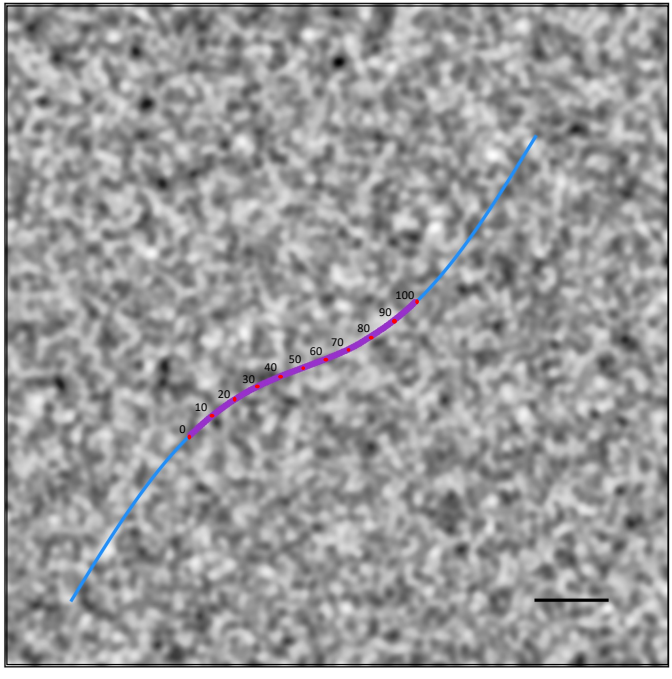


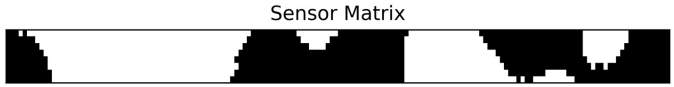


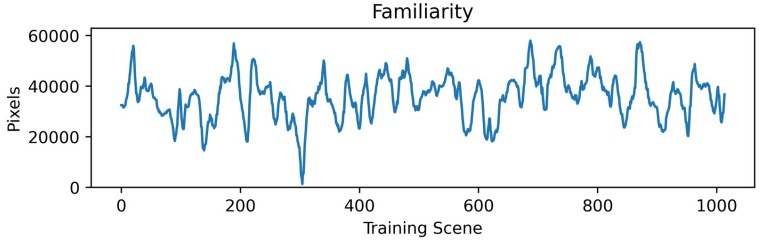
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

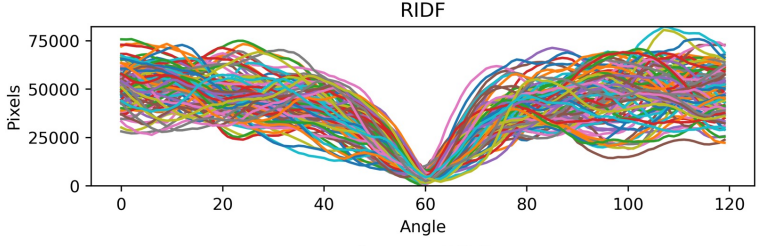
Navigation stats: RMSD error: 48.51; RMSD/dist: 0.121; TD: 32514; p90: 28; p50: 14; complete: 0

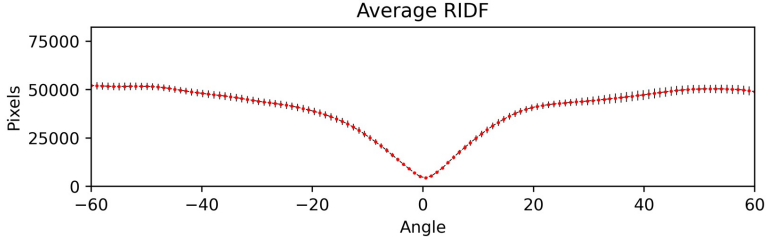
100%





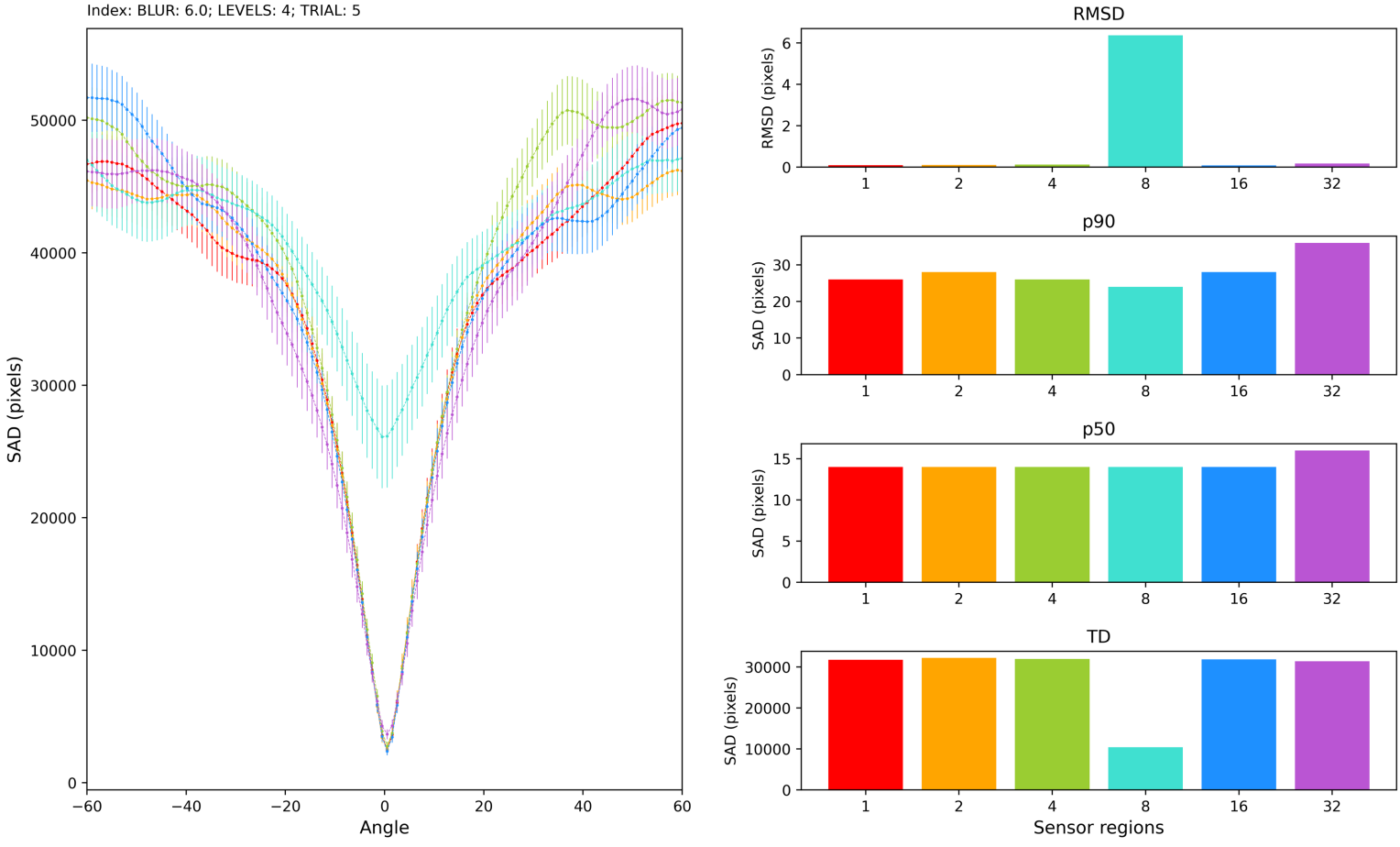




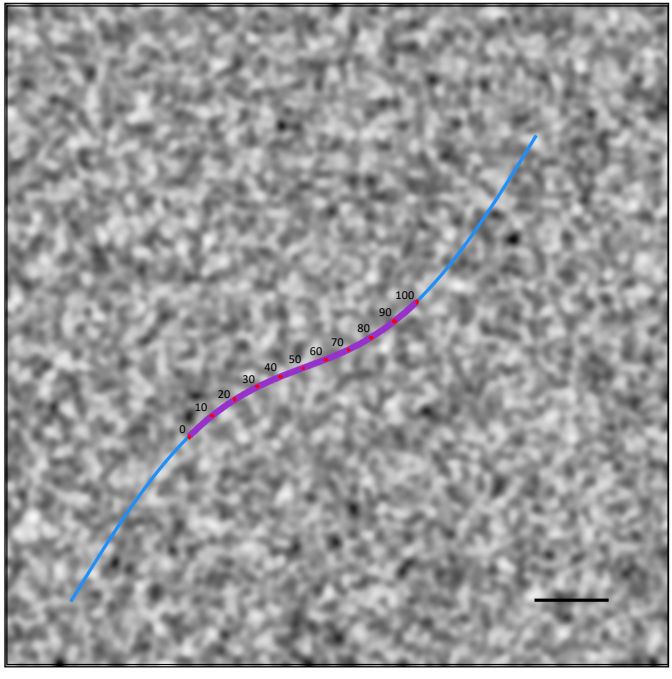


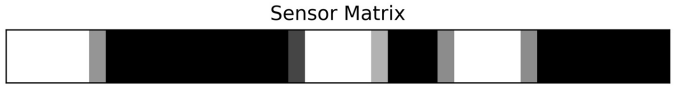
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

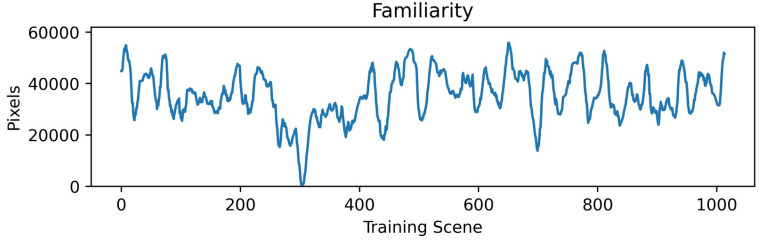
Navigation stats: RMSD error: 94.96; RMSD/dist: 0.237; TD: 31892; p90: 30; p50: 16; complete: 0

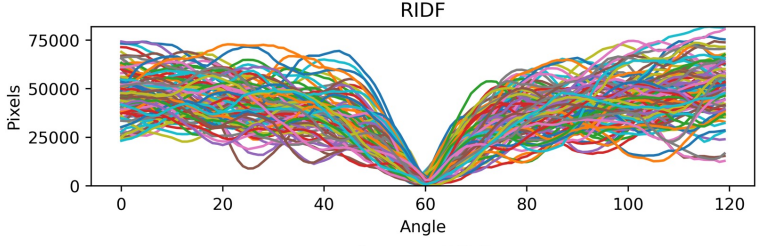

Index: BLUR: 6.0; LEVELS: 4; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

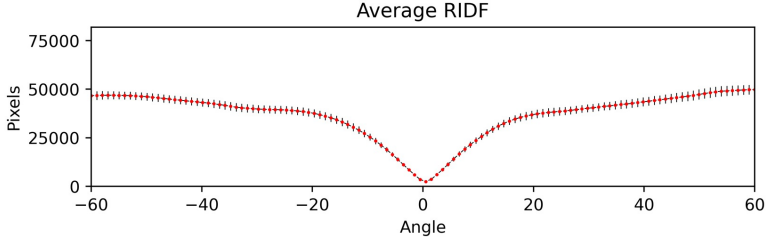
100%







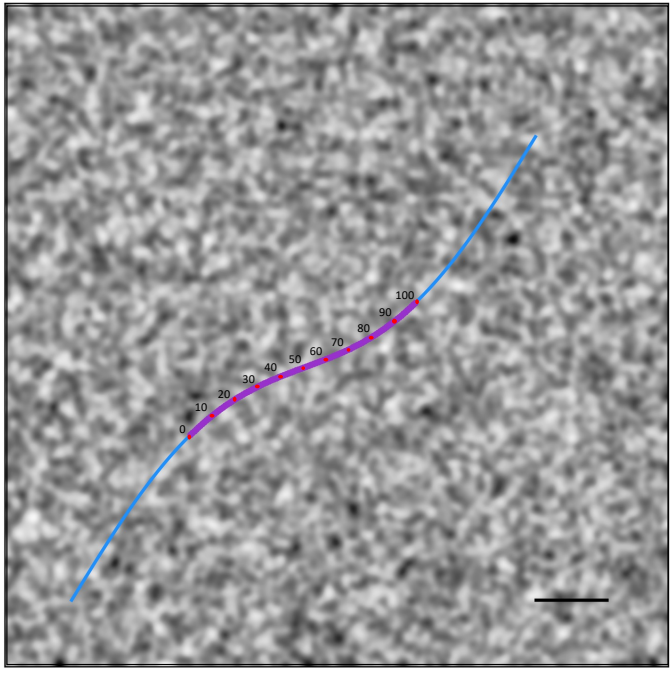


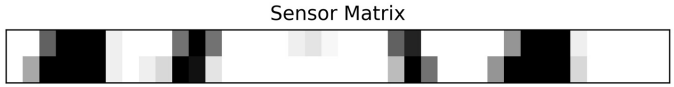


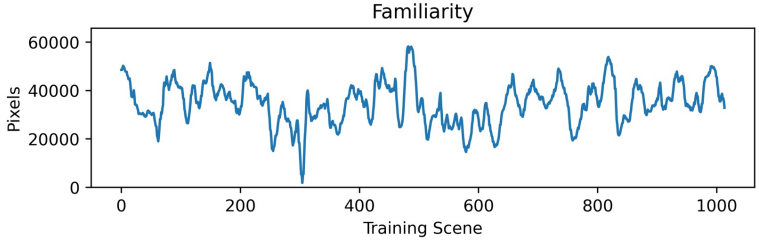
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

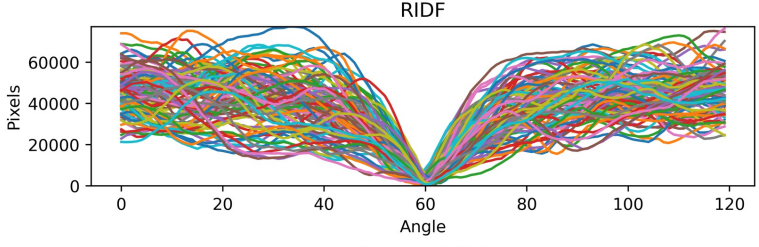
Navigation stats: RMSD error: 34.04; RMSD/dist: 0.085; TD: 31761; p90: 26; p50: 14; complete: 0

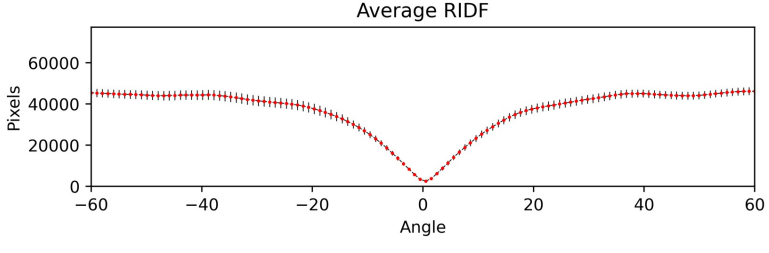
100%







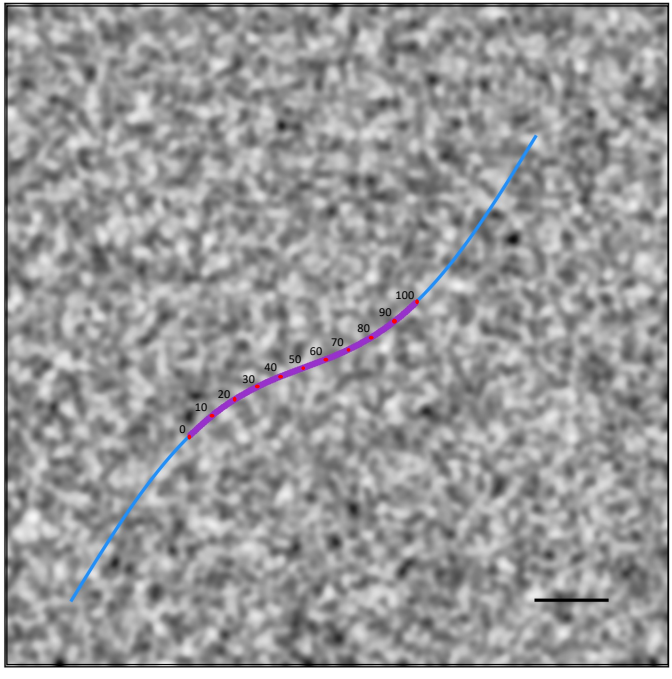


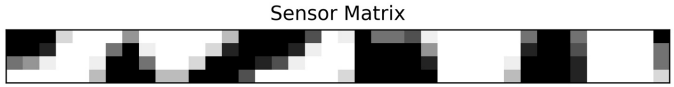


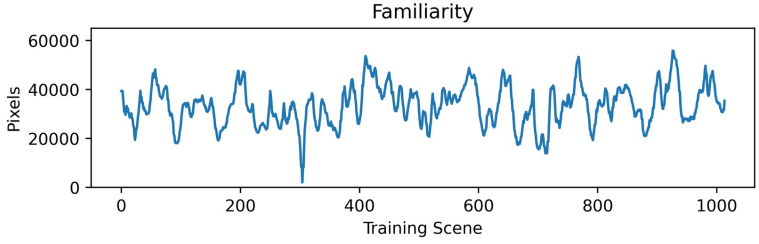
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

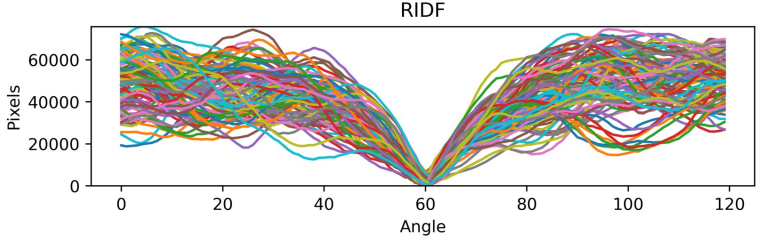
Navigation stats: RMSD error: 38.60; RMSD/dist: 0.097; TD: 32196; p90: 28; p50: 14; complete: 0

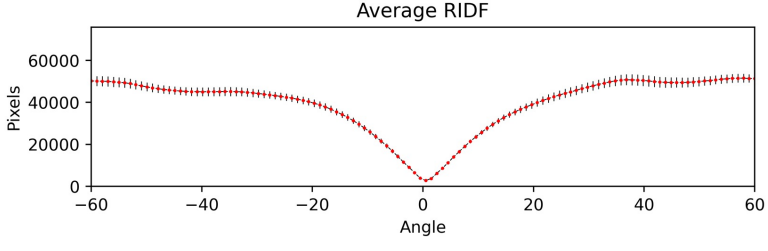
100%







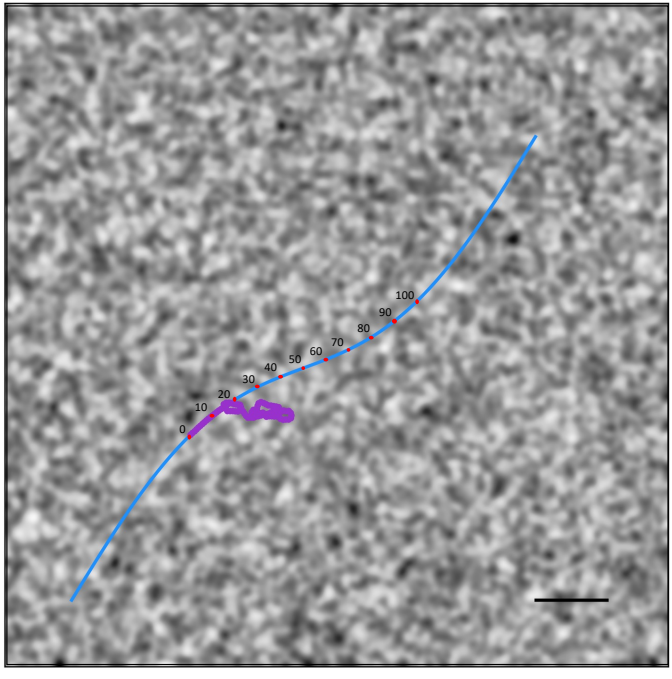


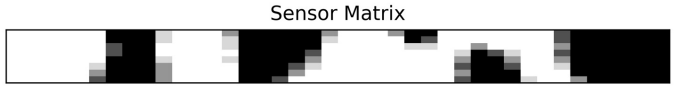


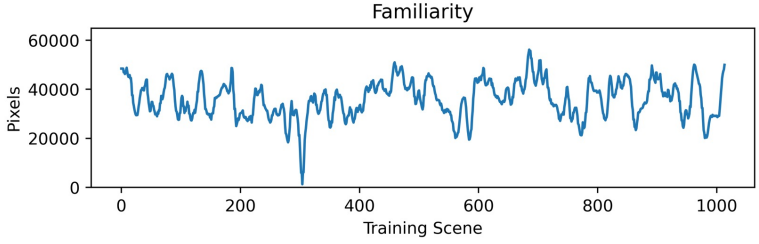
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

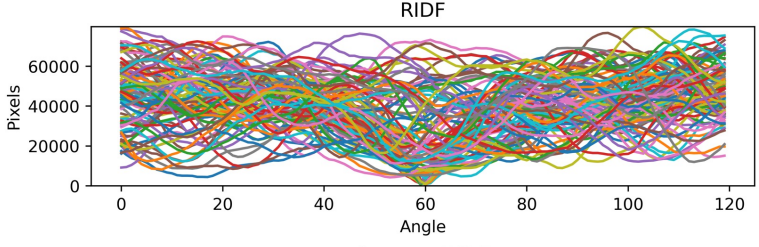
Navigation stats: RMSD error: 45.88; RMSD/dist: 0.115; TD: 31976; p90: 26; p50: 14; complete: 0

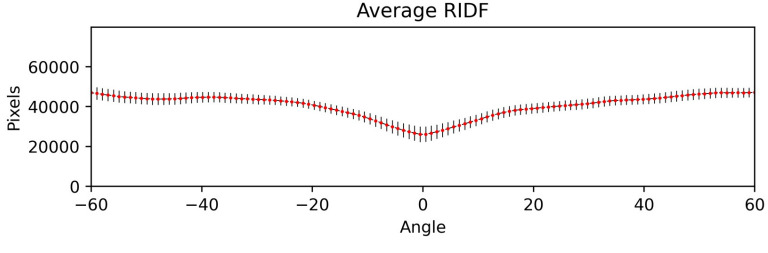
10%







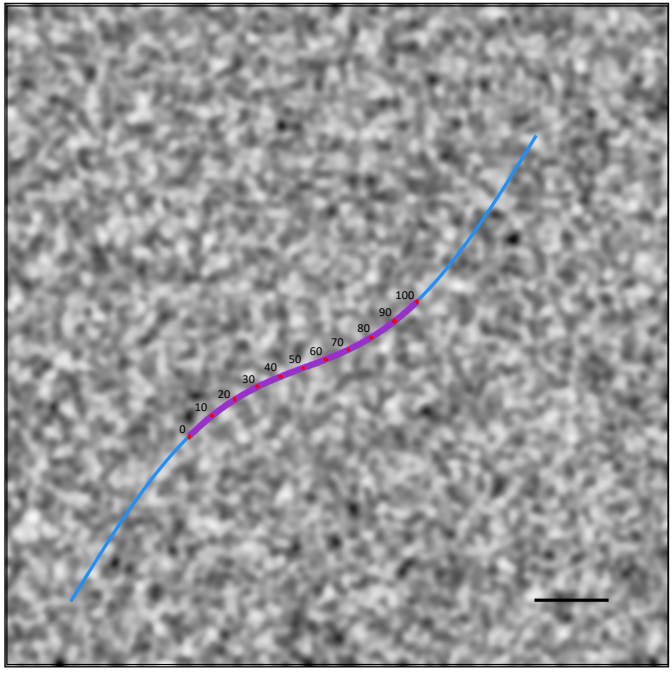


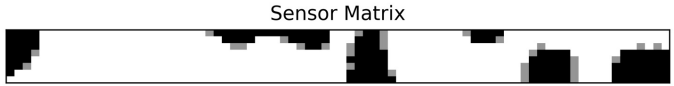


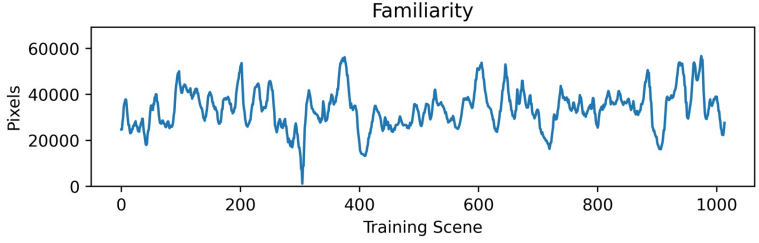
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

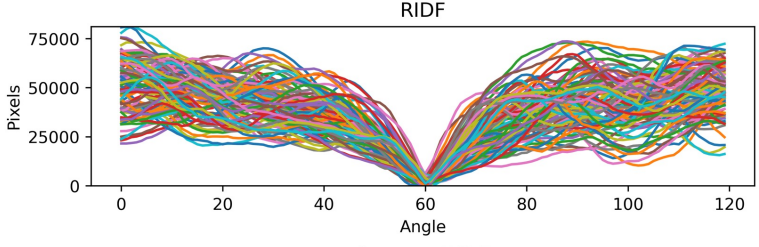
Navigation stats: RMSD error: 2548.88; RMSD/dist: 6.372; TD: 10408; p90: 24; p50: 14; complete: 0

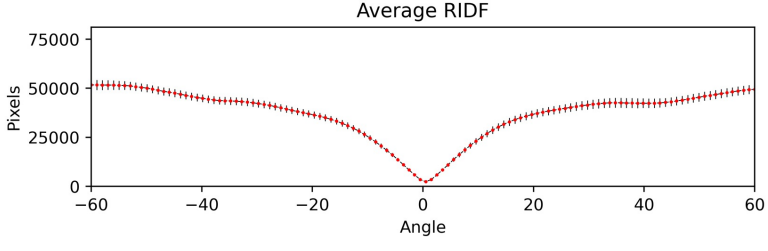
100%







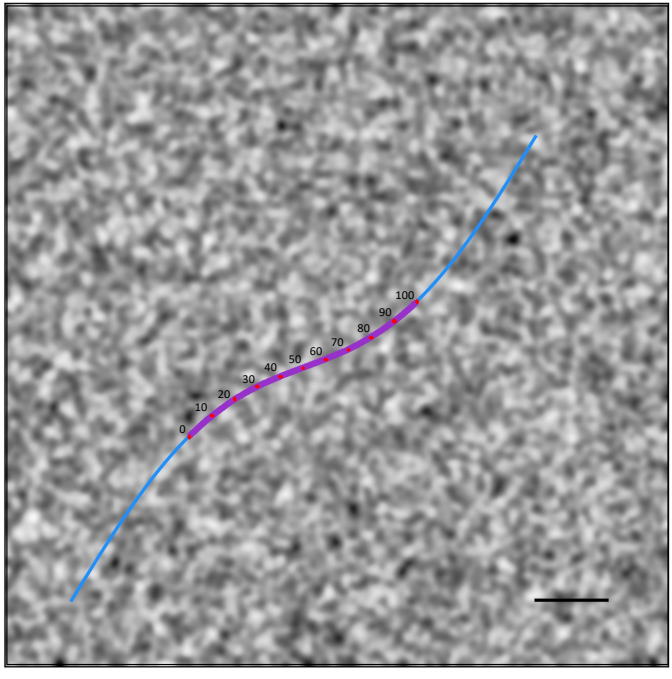


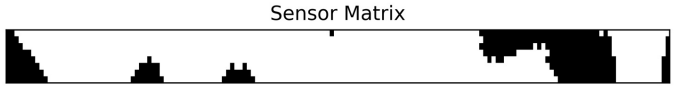


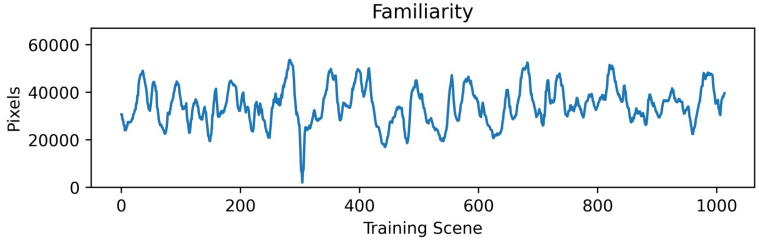
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

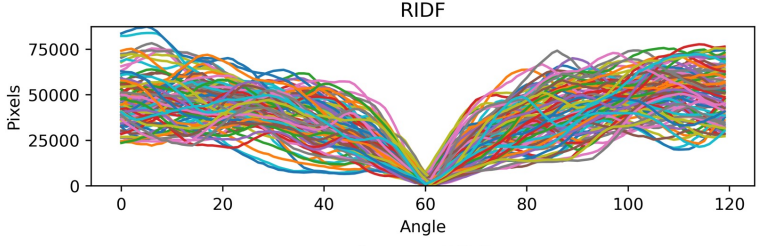
Navigation stats: RMSD error: 32.89; RMSD/dist: 0.082; TD: 31886; p90: 28; p50: 14; complete: 0

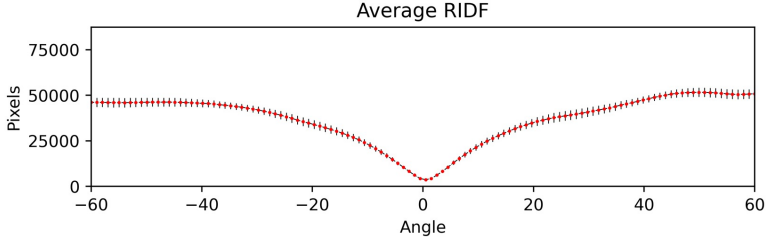
100%





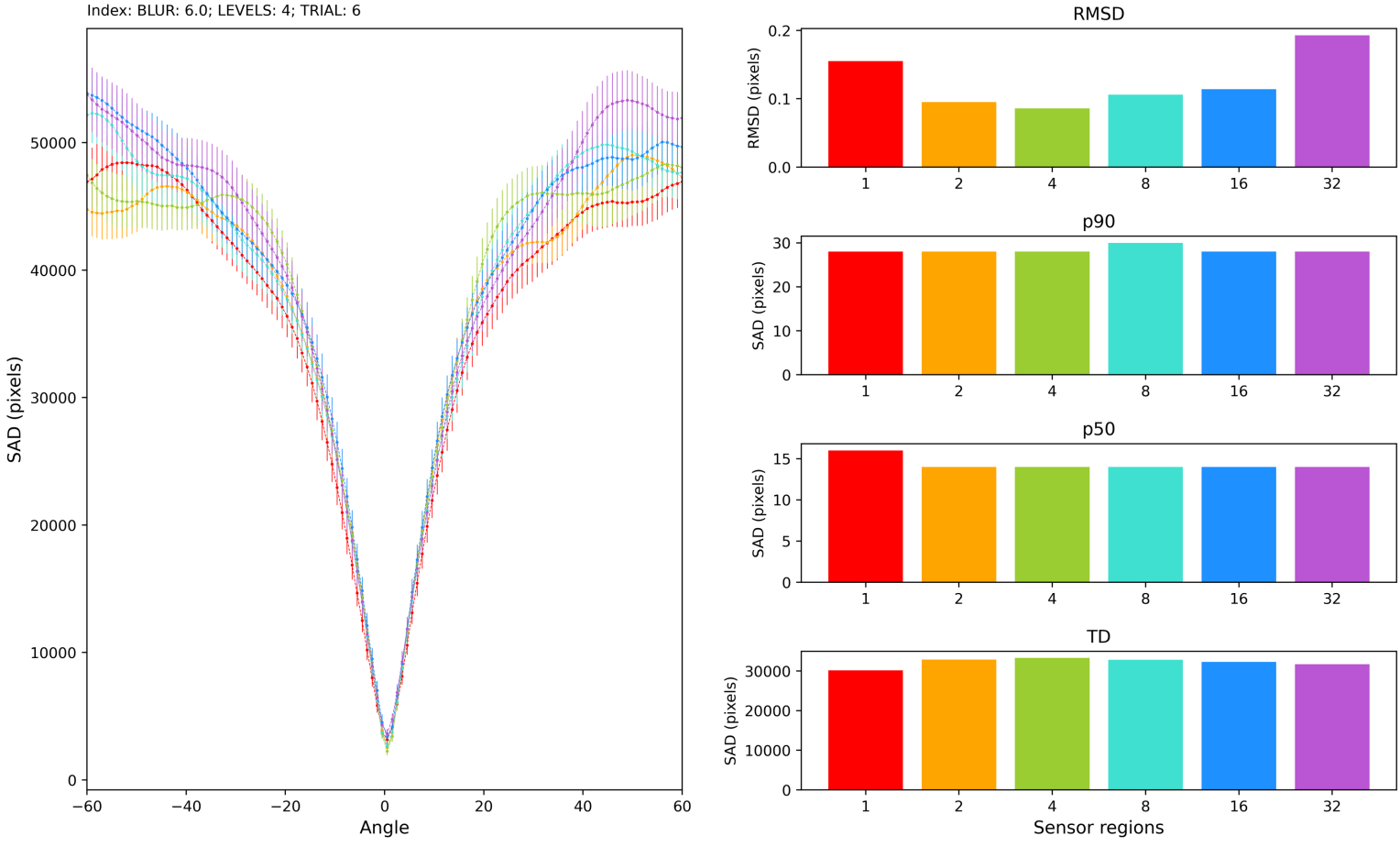




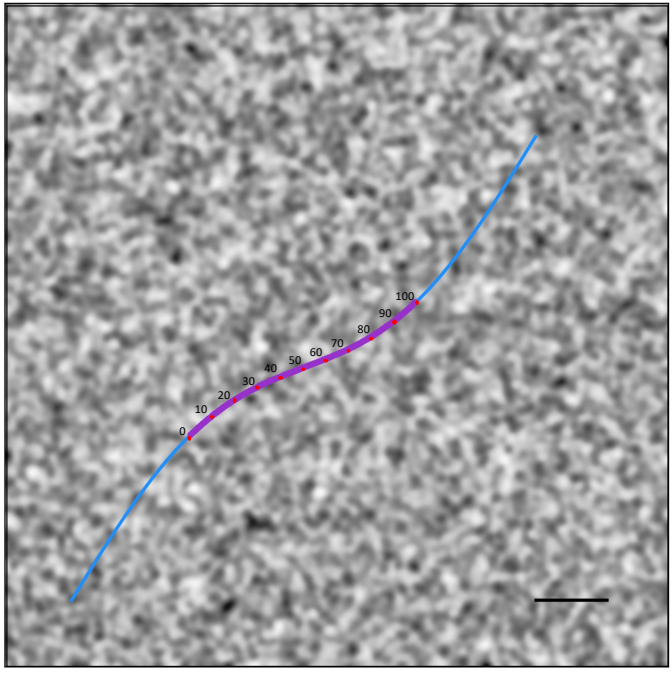


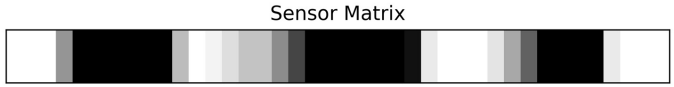
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

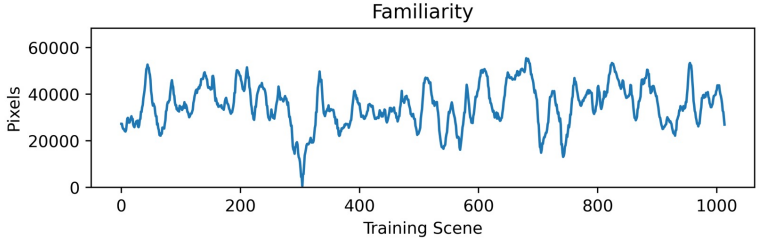
Navigation stats: RMSD error: 69.58; RMSD/dist: 0.174; TD: 31381; p90: 36; p50: 16; complete: 0

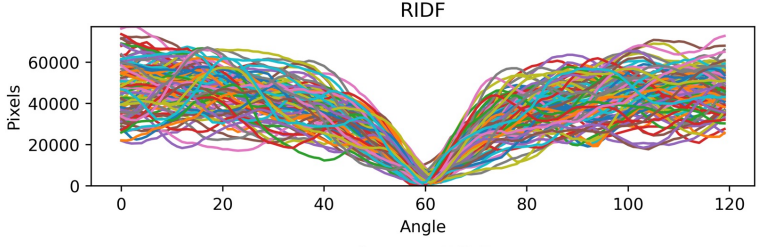

Index: BLUR: 6.0; LEVELS: 4; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

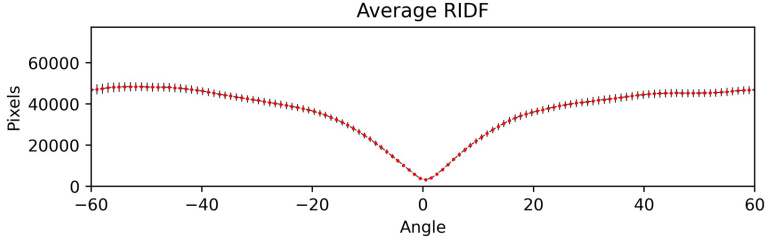
100%







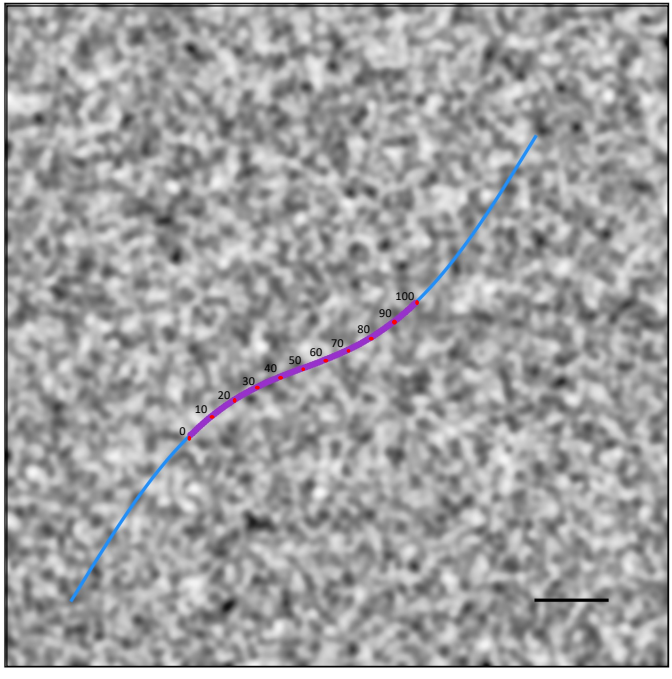


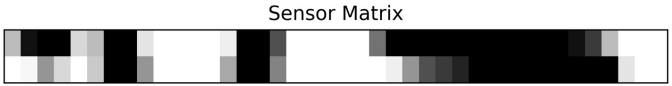


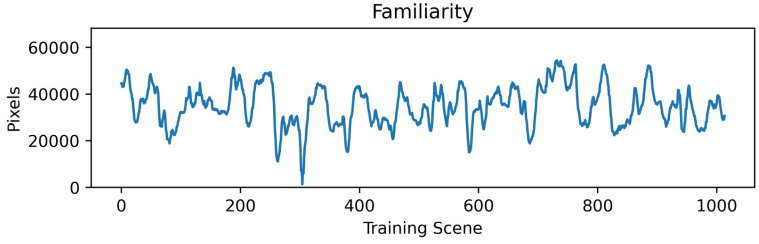
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

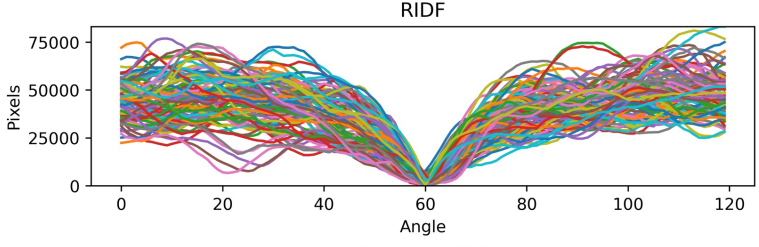
Navigation stats: RMSD error: 61.86; RMSD/dist: 0.155; TD: 30168; p90: 28; p50: 16; complete: 0

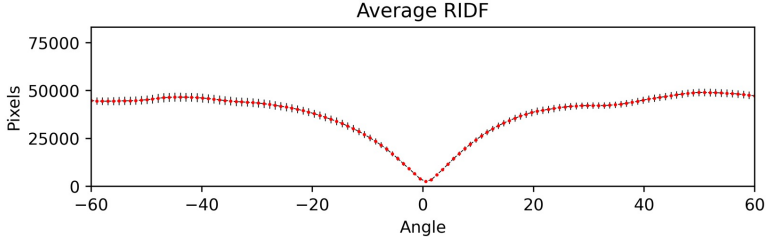
100%







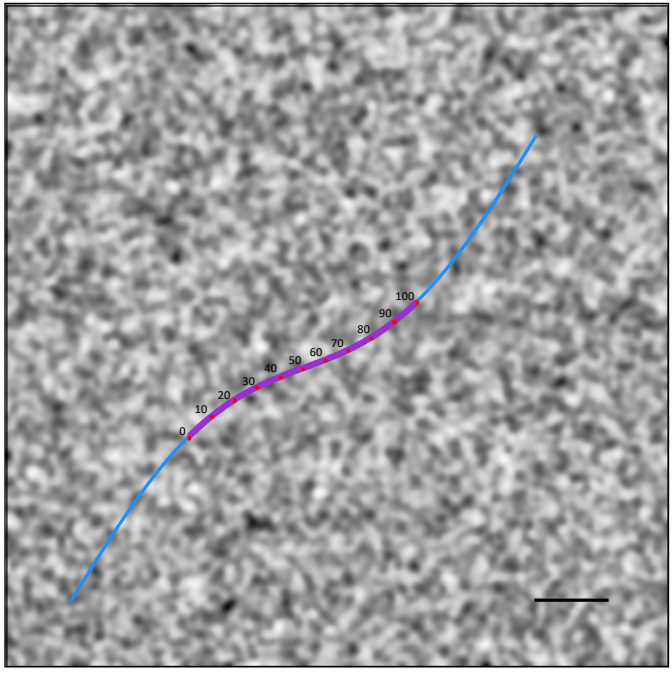


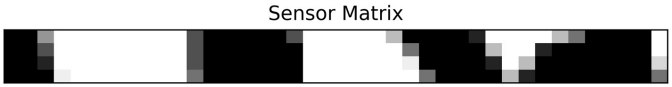


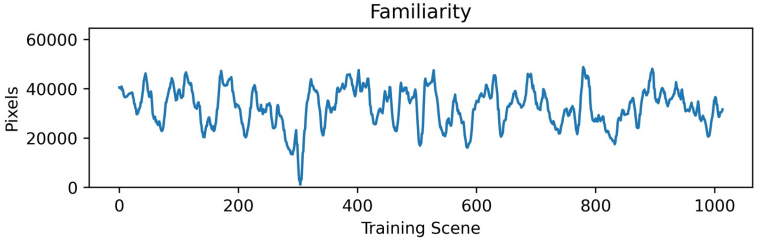
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

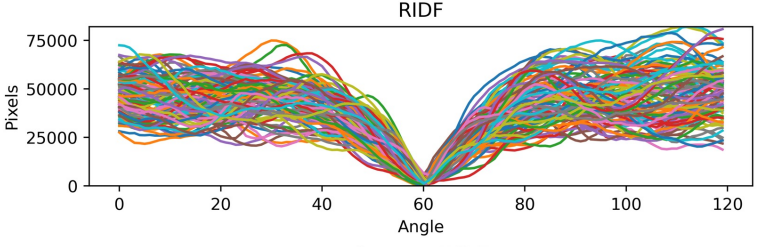
Navigation stats: RMSD error: 38.02; RMSD/dist: 0.095; TD: 32891; p90: 28; p50: 14; complete: 0

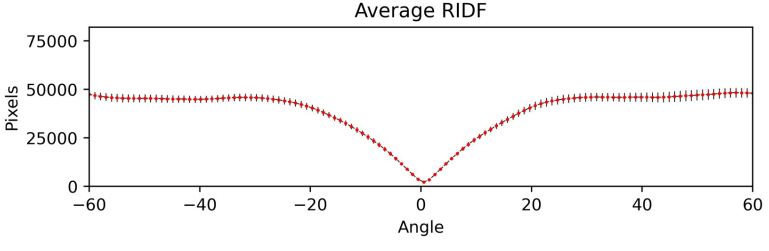
100%







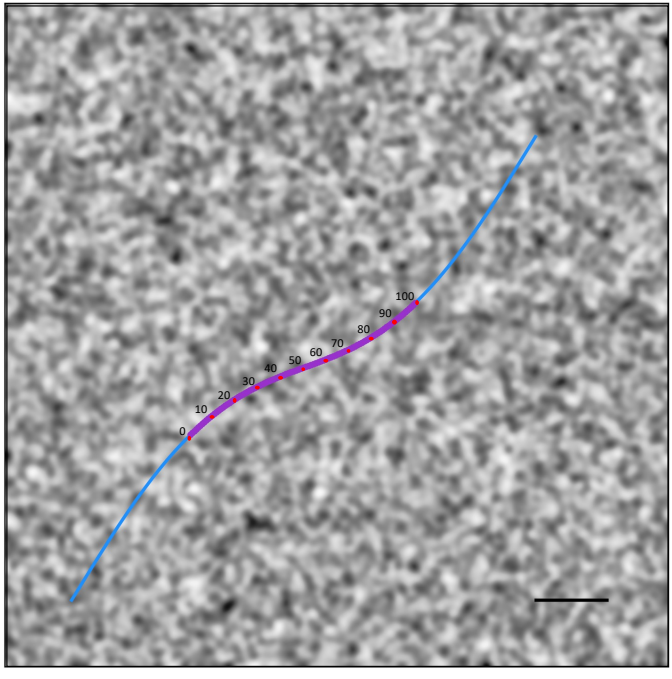


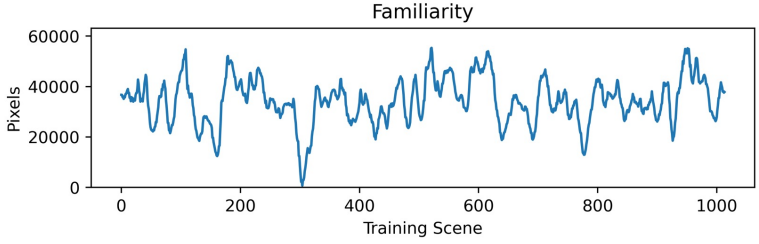


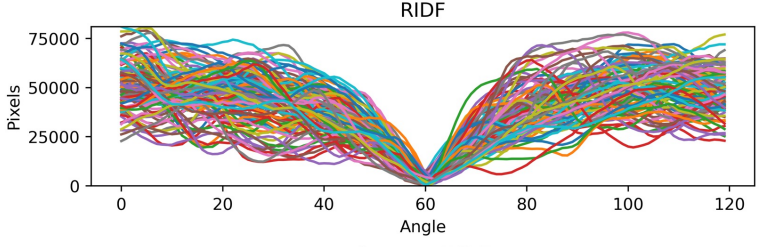
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

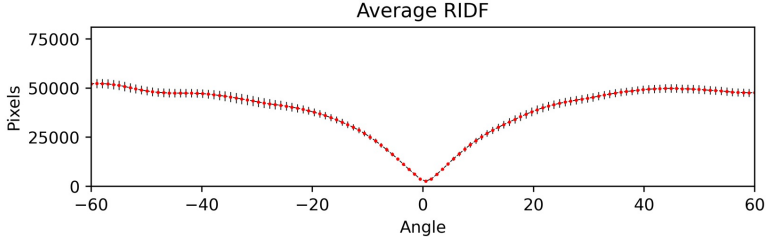
Navigation stats: RMSD error: 34.56; RMSD/dist: 0.086; TD: 33280; p90: 28; p50: 14; complete: 0

100%





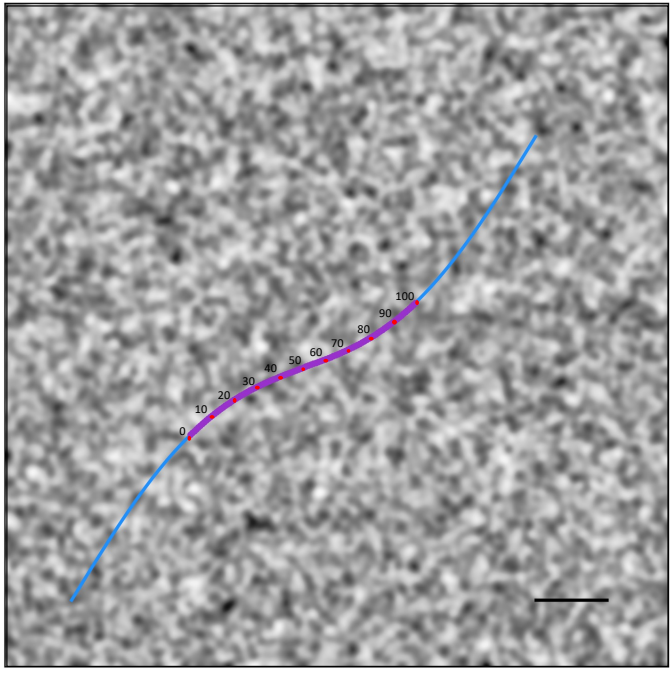


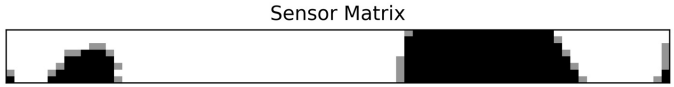


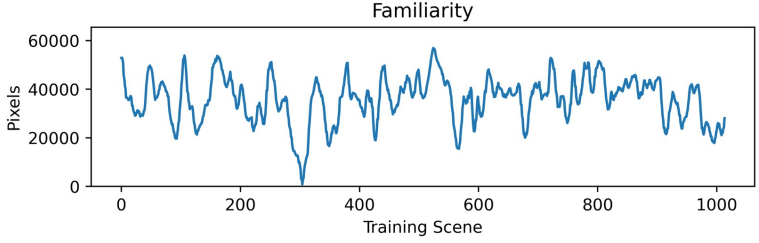
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

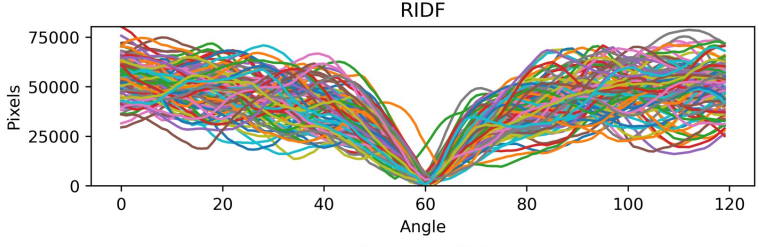
Navigation stats: RMSD error: 42.45; RMSD/dist: 0.106; TD: 32811; p90: 30; p50: 14; complete: 0

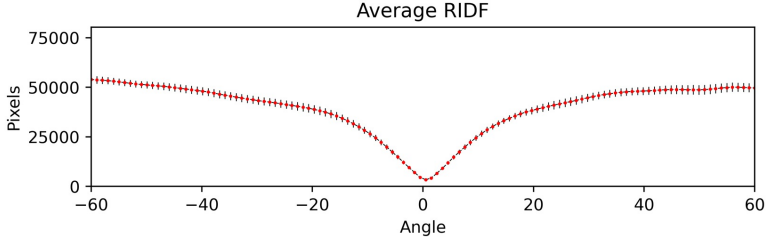
100%







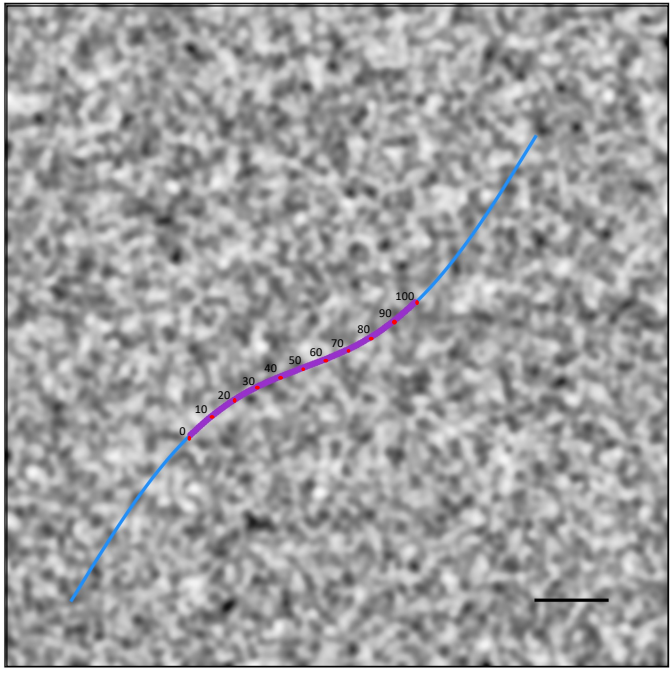


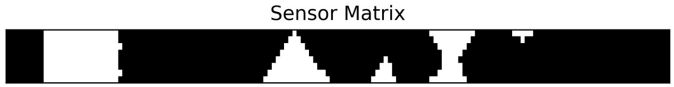


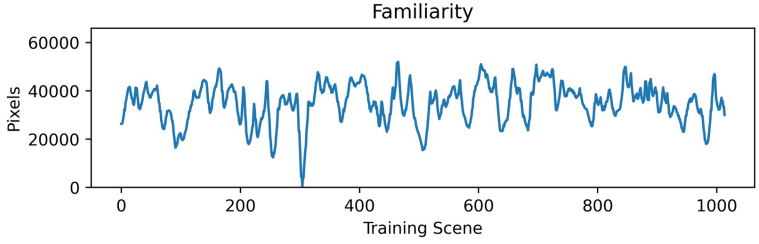
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

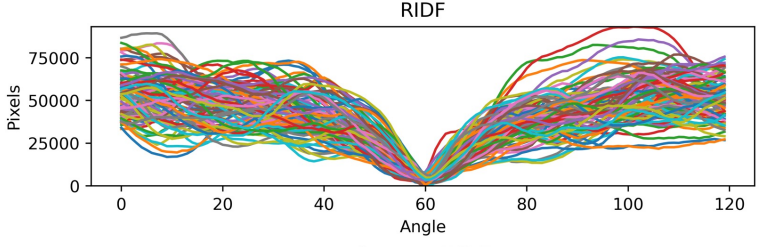
Navigation stats: RMSD error: 45.73; RMSD/dist: 0.114; TD: 32270; p90: 28; p50: 14; complete: 0

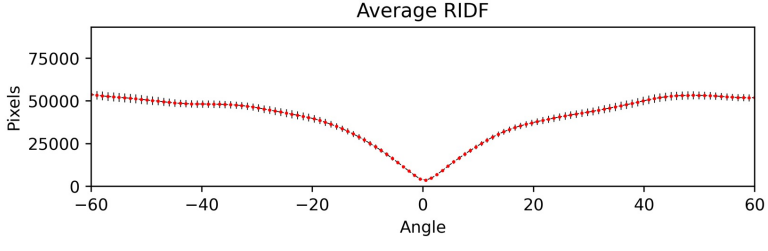
100%





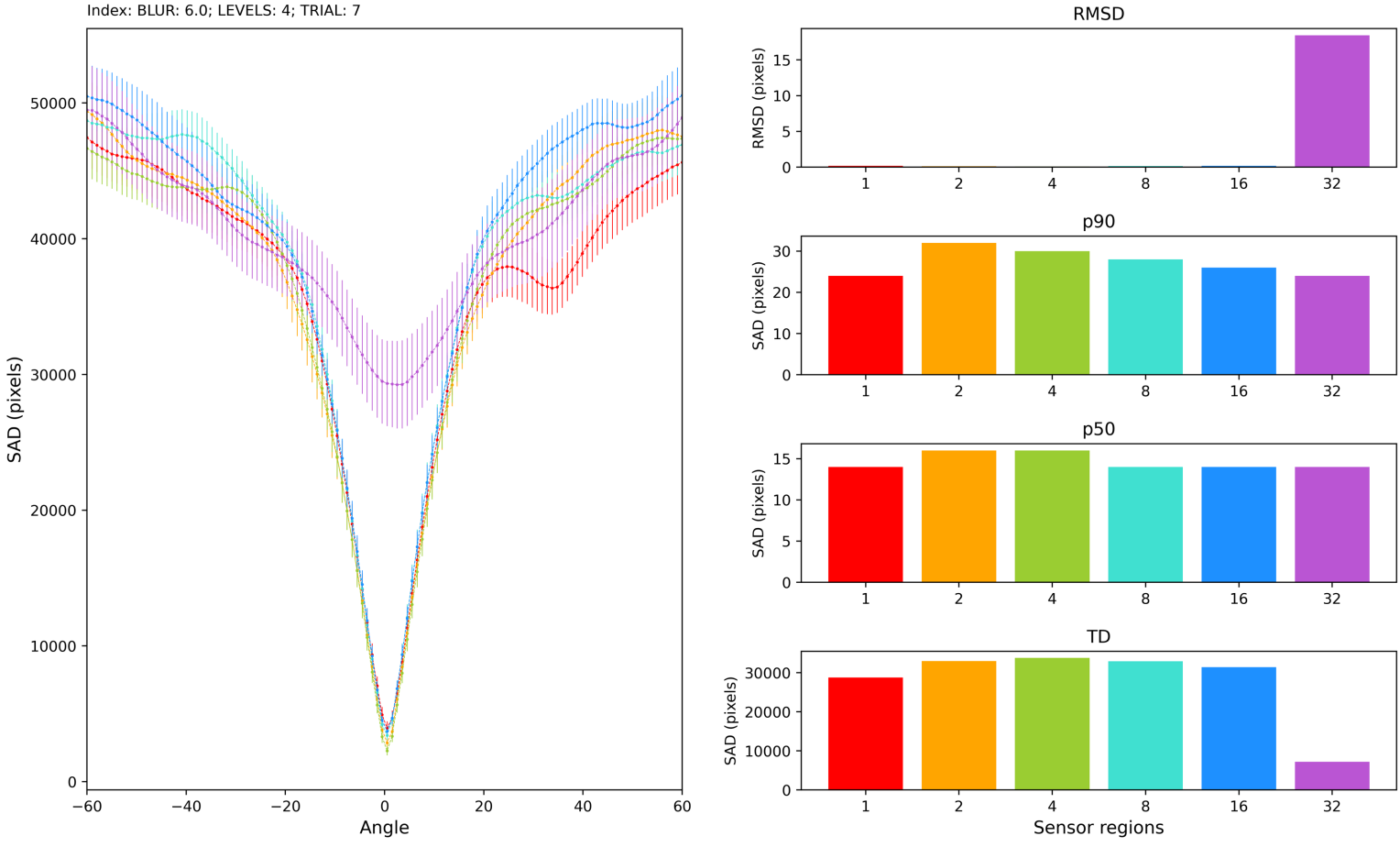




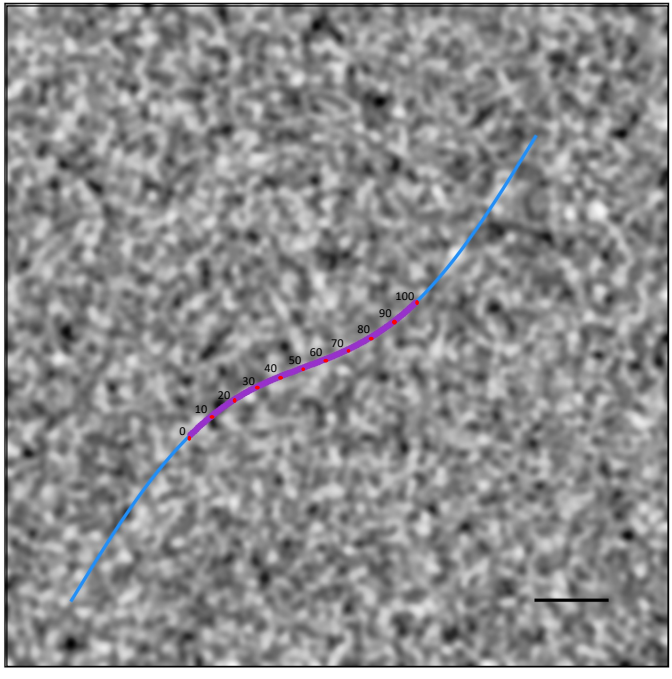


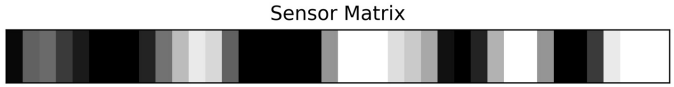
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

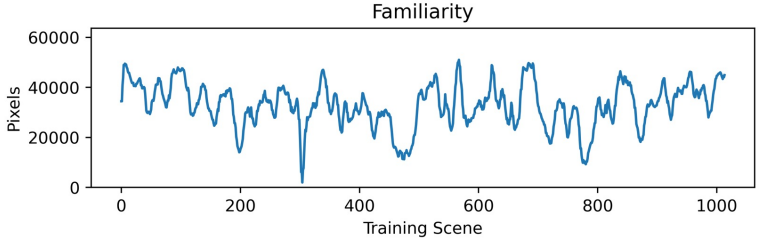
Navigation stats: RMSD error: 77.15; RMSD/dist: 0.193; TD: 31689; p90: 28; p50: 14; complete: 0

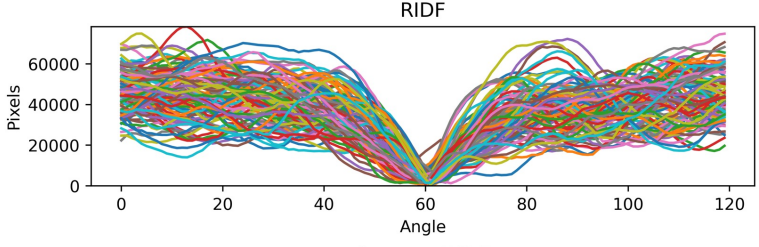

Index: BLUR: 6.0; LEVELS: 4; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

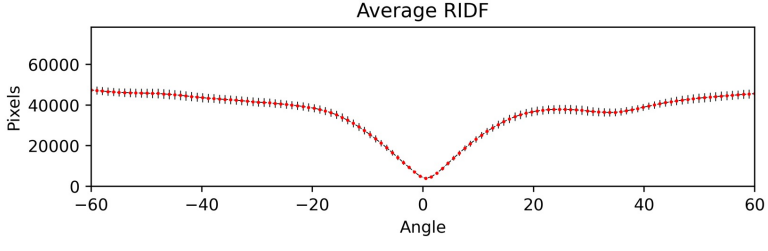
100%







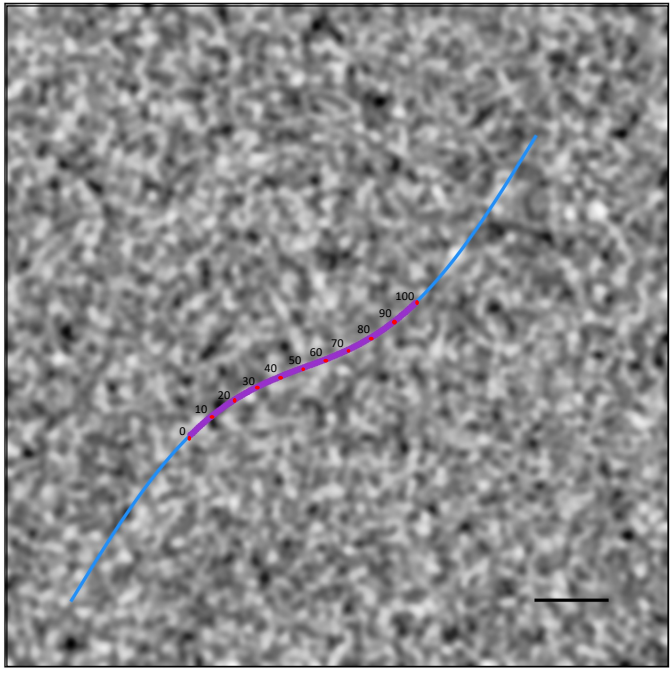


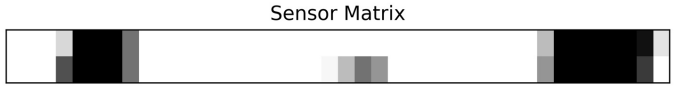


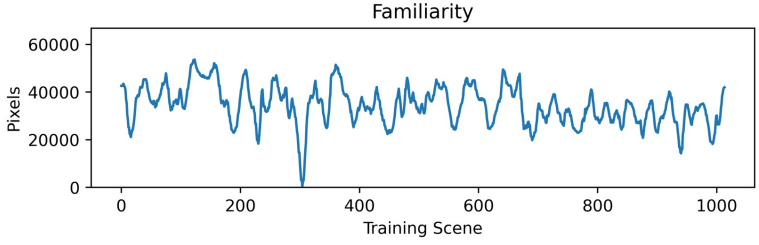
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

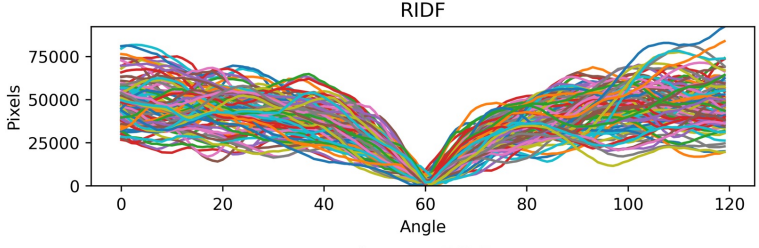
Navigation stats: RMSD error: 70.46; RMSD/dist: 0.176; TD: 28757; p90: 24; p50: 14; complete: 0

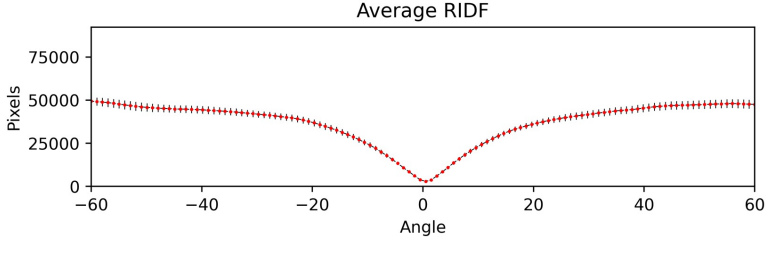
100%







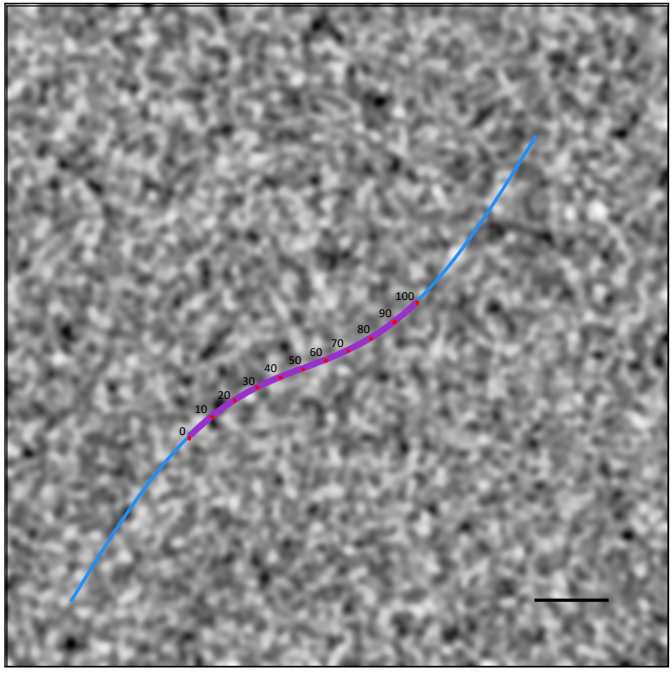


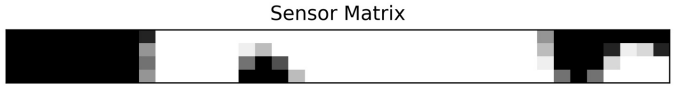


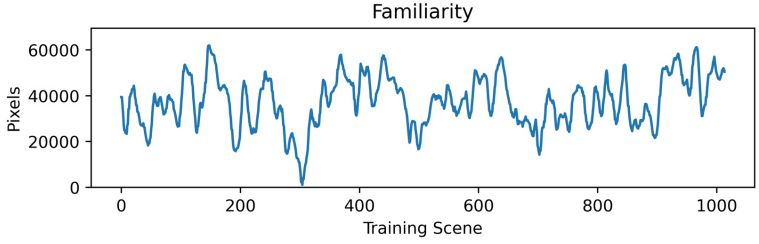
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

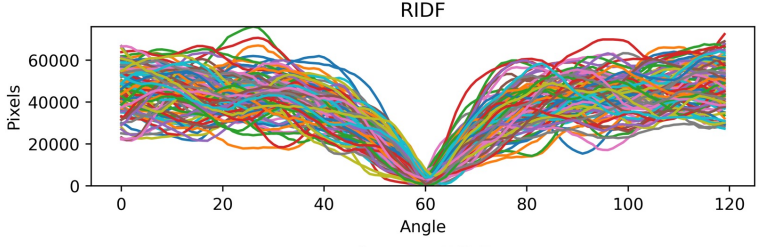
Navigation stats: RMSD error: 43.12; RMSD/dist: 0.108; TD: 32973; p90: 32; p50: 16; complete: 0

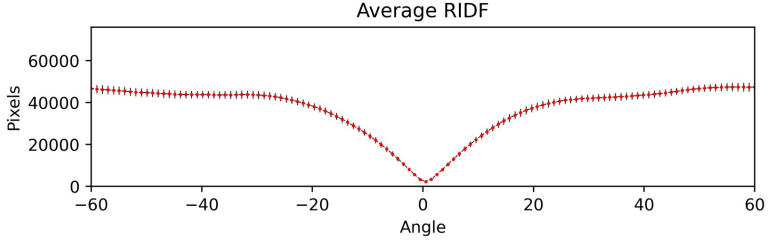
100%







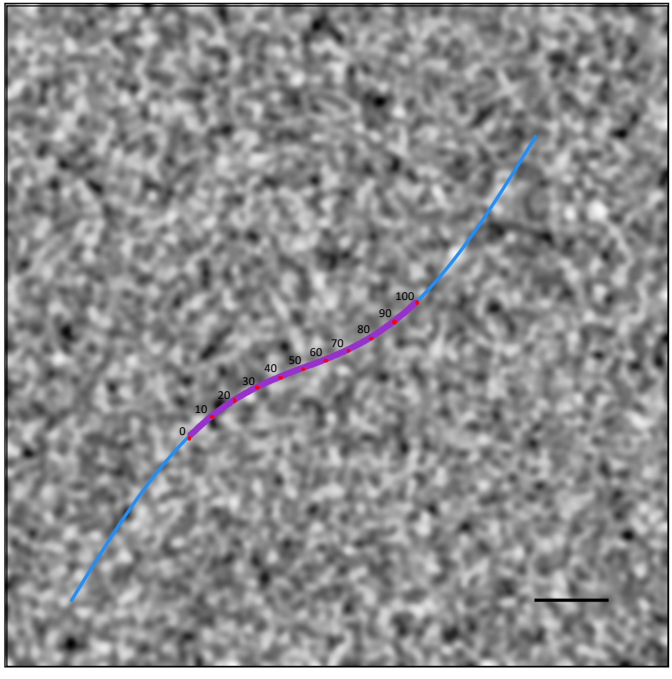


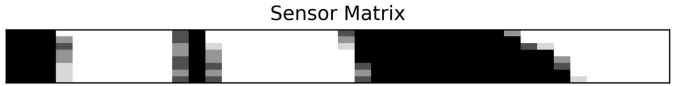


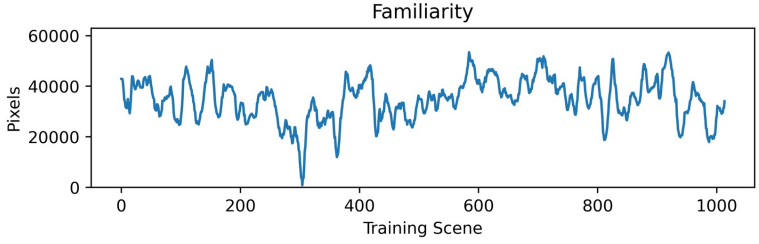
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

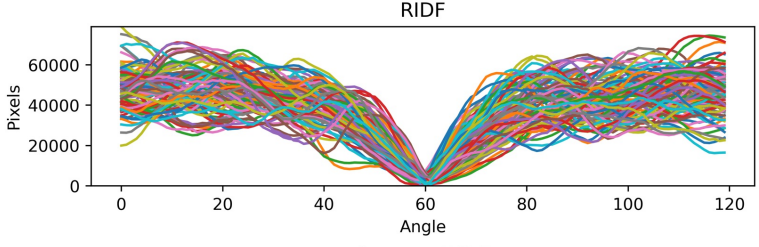
Navigation stats: RMSD error: 27.72; RMSD/dist: 0.069; TD: 33740; p90: 30; p50: 16; complete: 0

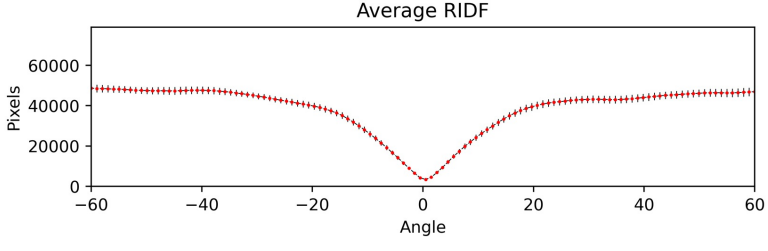
100%







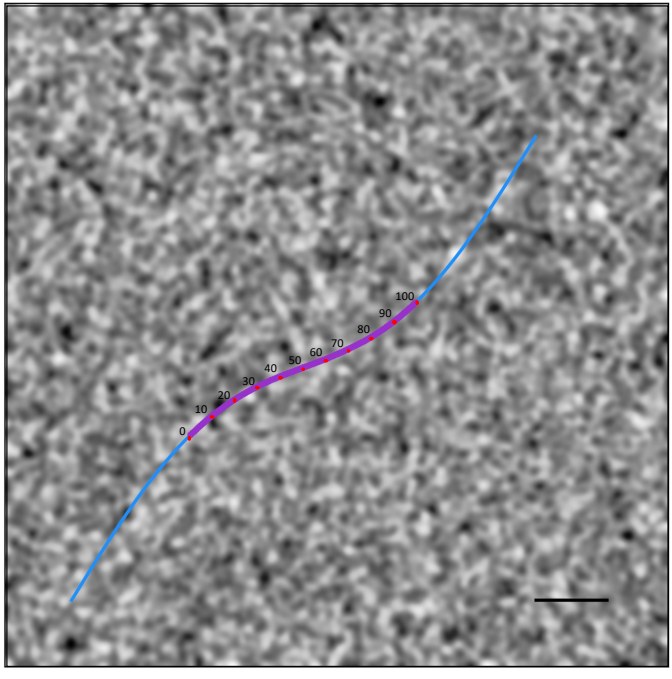


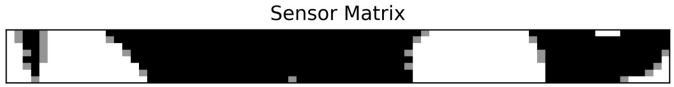


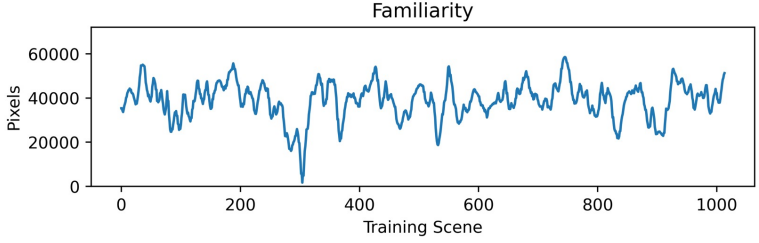
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

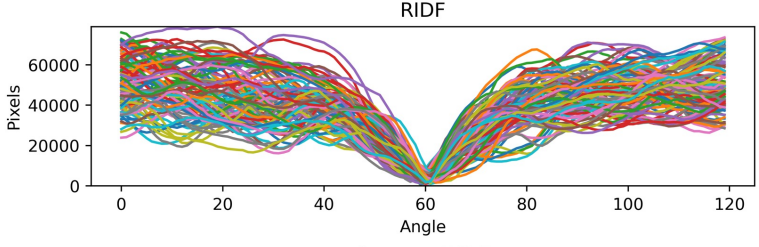
Navigation stats: RMSD error: 58.15; RMSD/dist: 0.145; TD: 32912; p90: 28; p50: 14; complete: 0

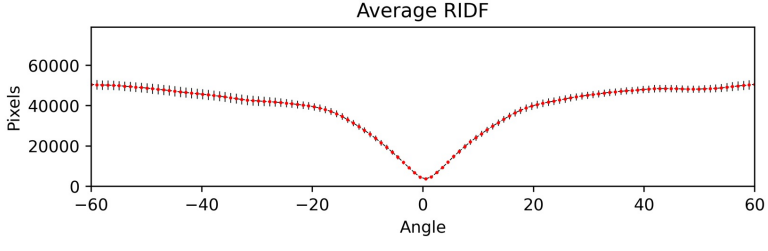
100%







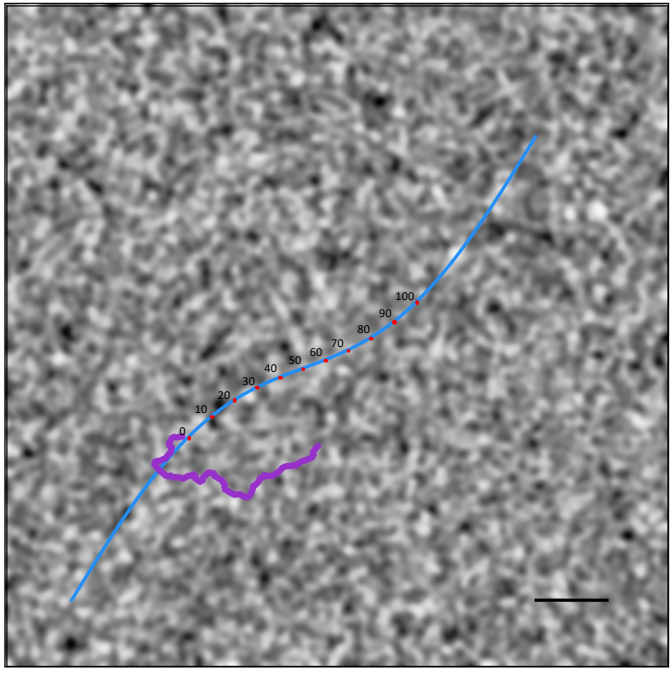


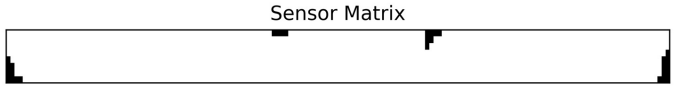


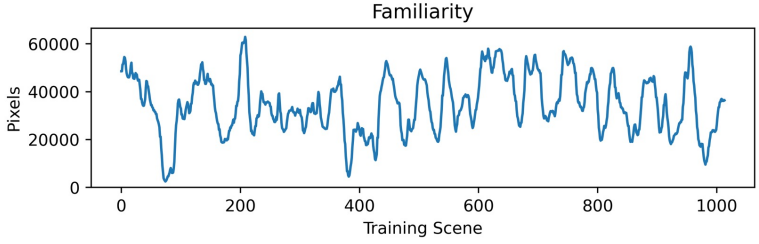
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

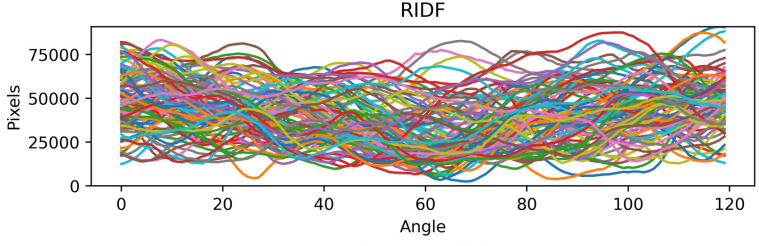
Navigation stats: RMSD error: 65.39; RMSD/dist: 0.163; TD: 31403; p90: 26; p50: 14; complete: 0

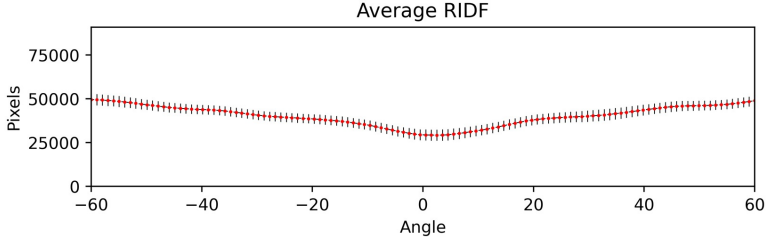
0%





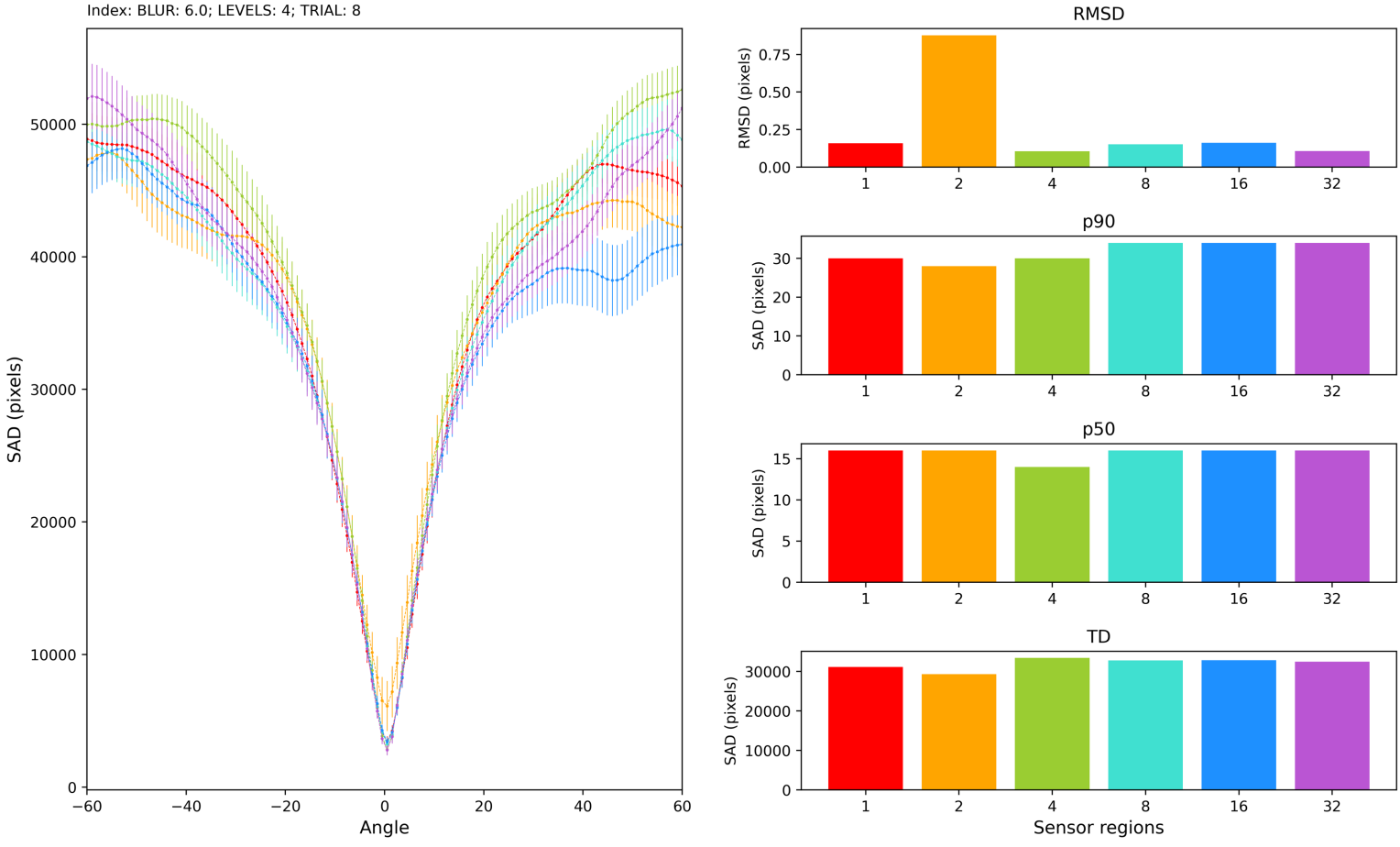




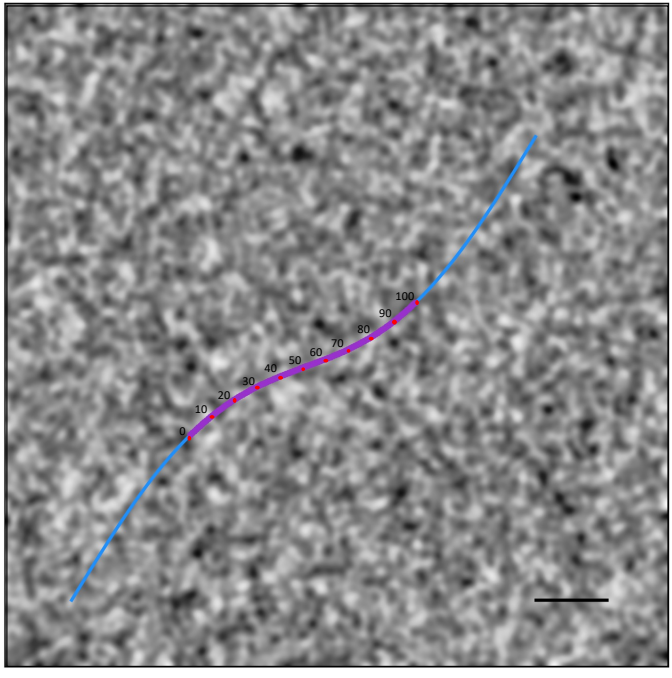


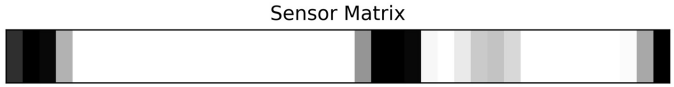
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

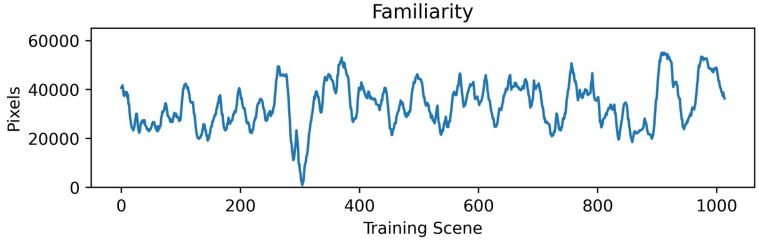
Navigation stats: RMSD error: 7382.36; RMSD/dist: 18.456; TD: 7150; p90: 24; p50: 14; complete: 0

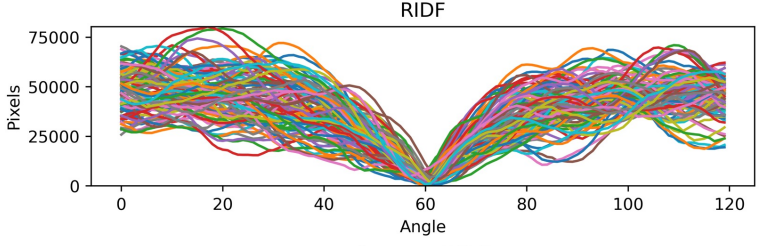

Index: BLUR: 6.0; LEVELS: 4; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

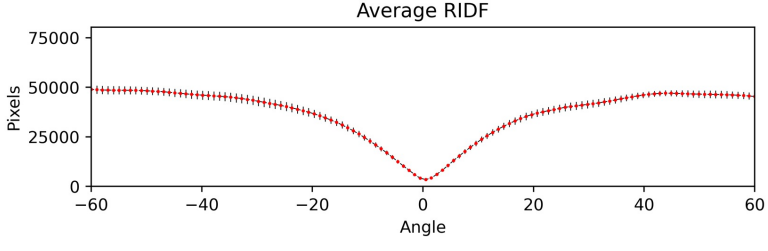
100%







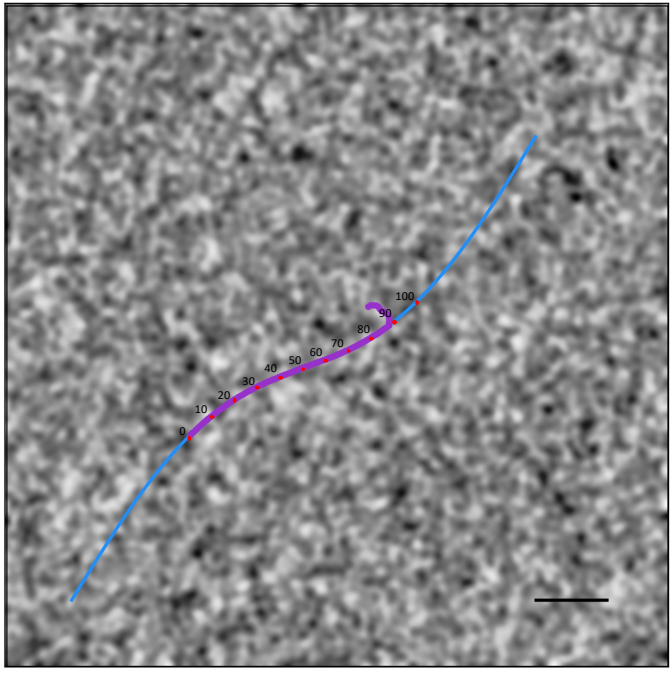


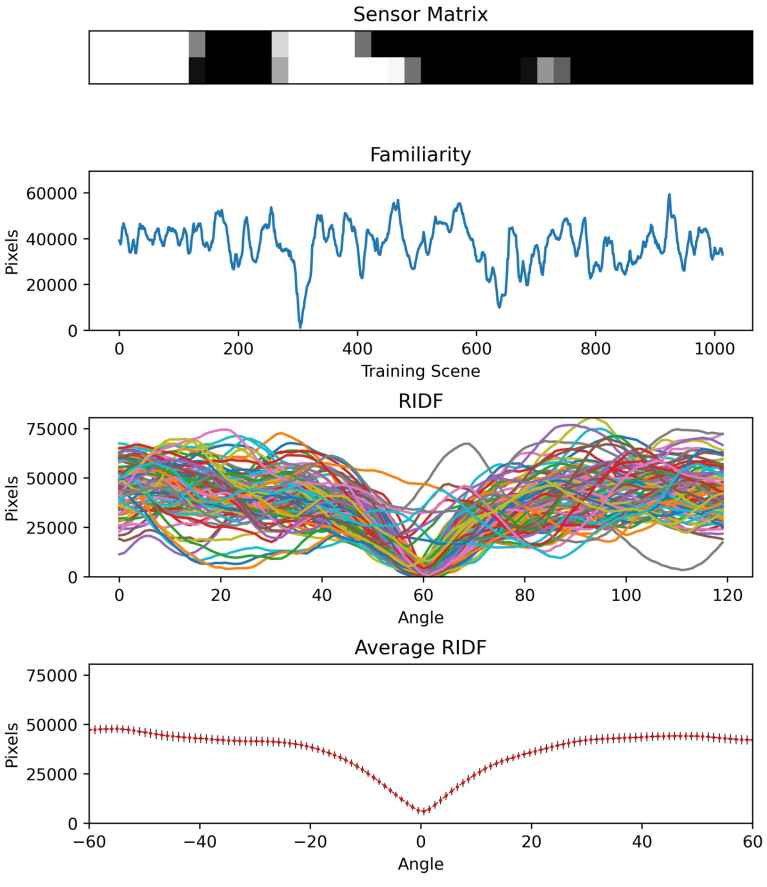


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 63.53; RMSD/dist: 0.159; TD: 31113; p90: 30; p50: 16; complete: 0

80%

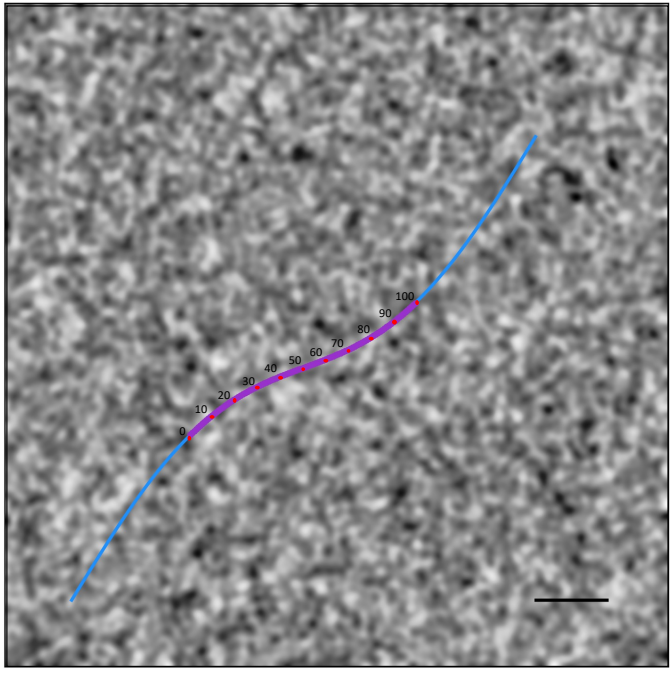


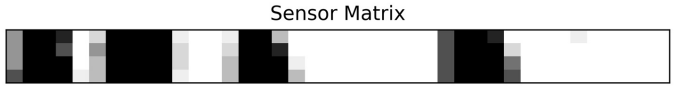


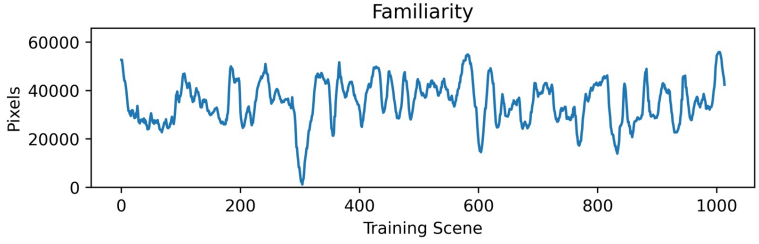
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

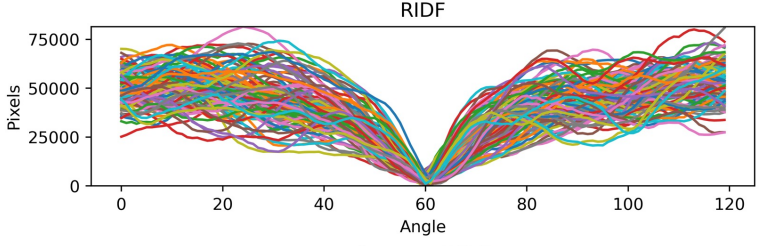
Navigation stats: RMSD error: 351.19; RMSD/dist: 0.878; TD: 29303; p90: 28; p50: 16; complete: 0

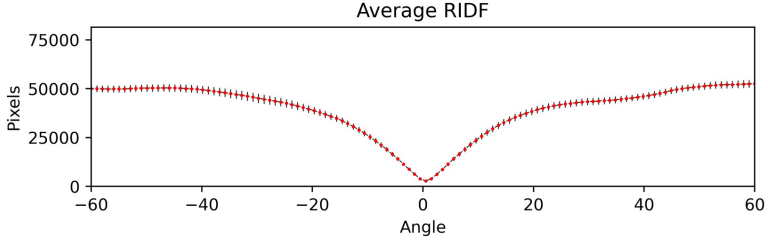
100%







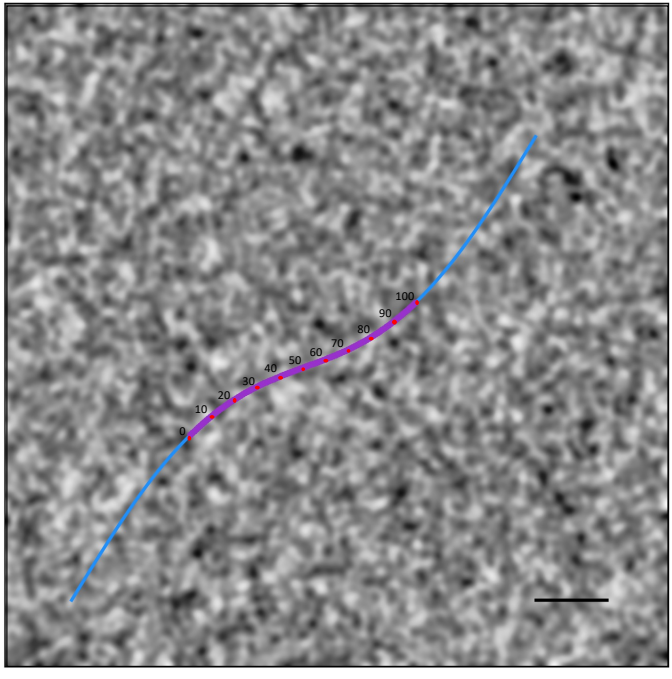


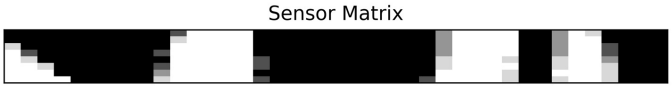


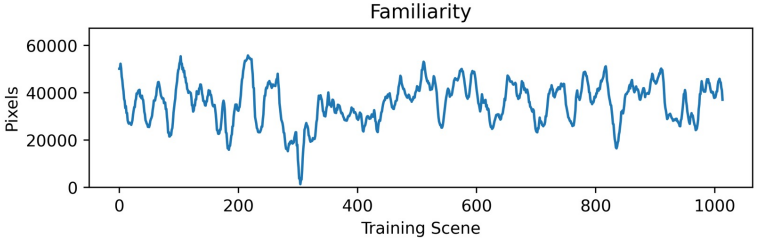
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

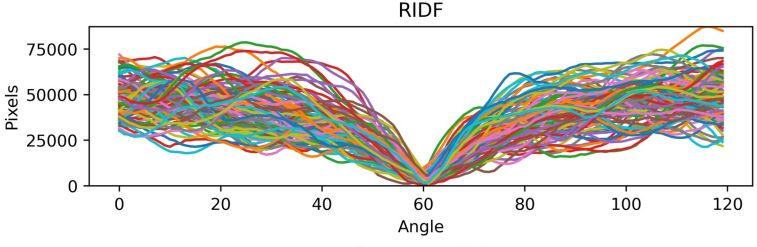
Navigation stats: RMSD error: 42.05; RMSD/dist: 0.105; TD: 33411; p90: 30; p50: 14; complete: 0

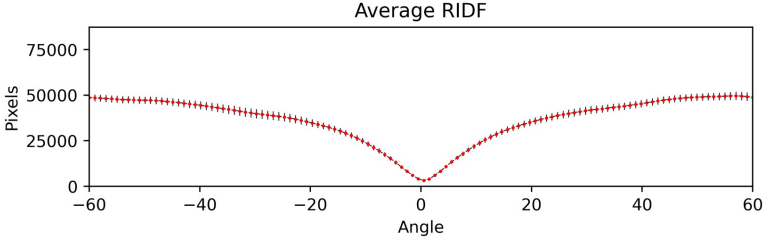
100%







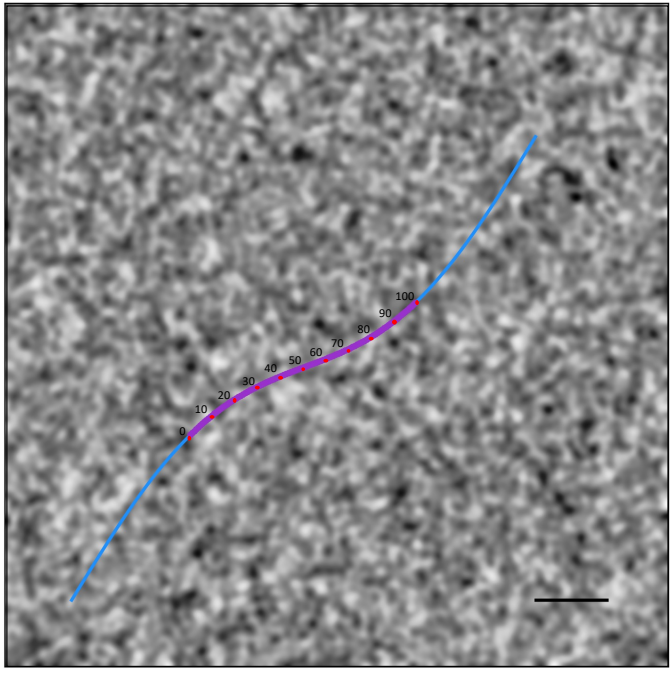


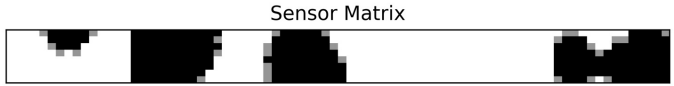


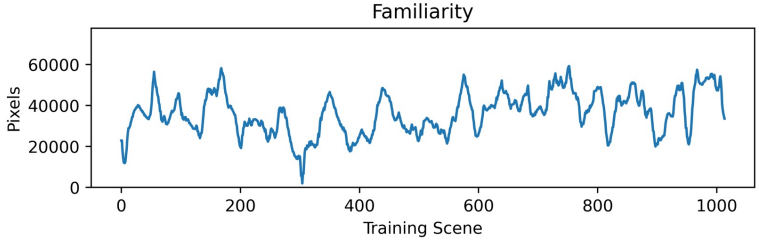
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

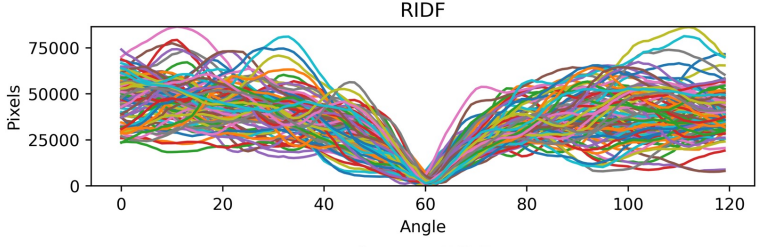
Navigation stats: RMSD error: 61.00; RMSD/dist: 0.152; TD: 32775; p90: 34; p50: 16; complete: 0

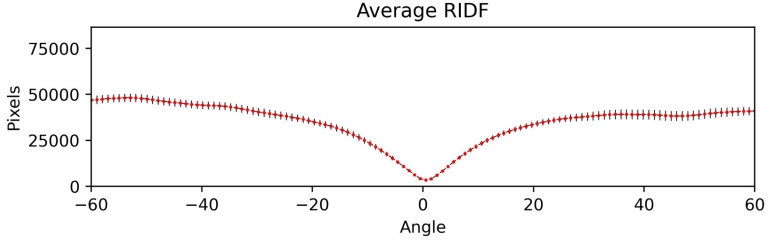
100%







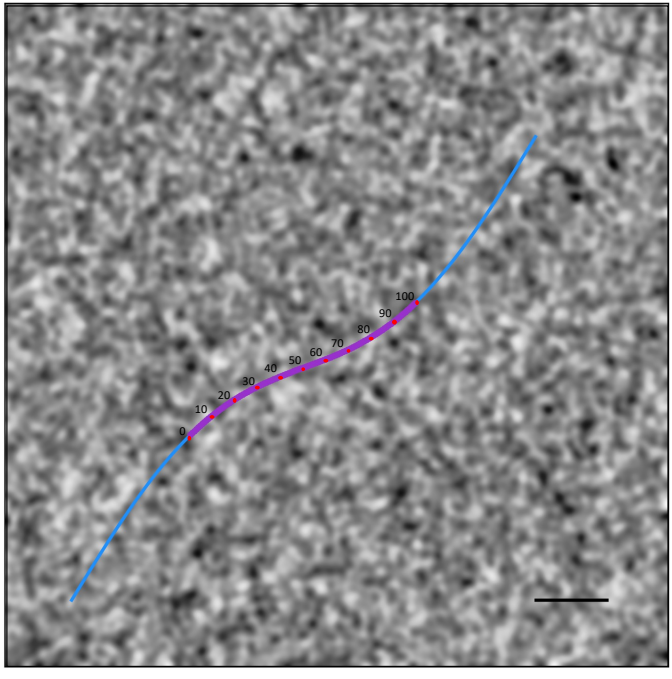


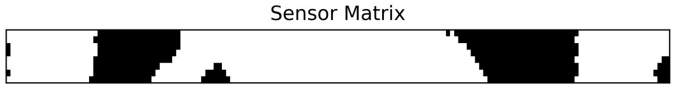


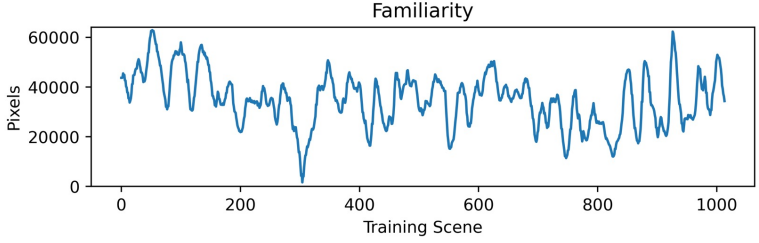
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

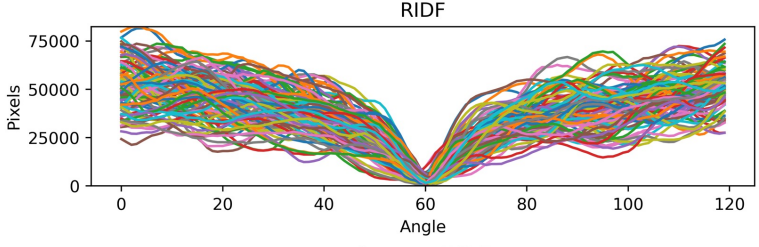
Navigation stats: RMSD error: 64.60; RMSD/dist: 0.162; TD: 32843; p90: 34; p50: 16; complete: 0

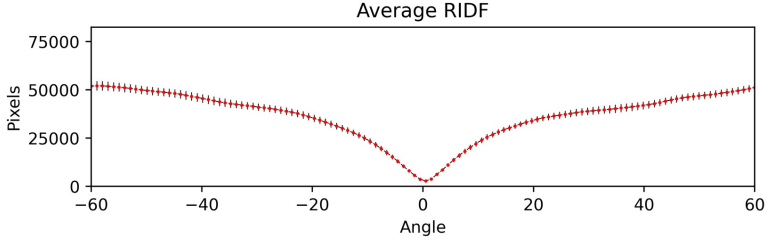
100%





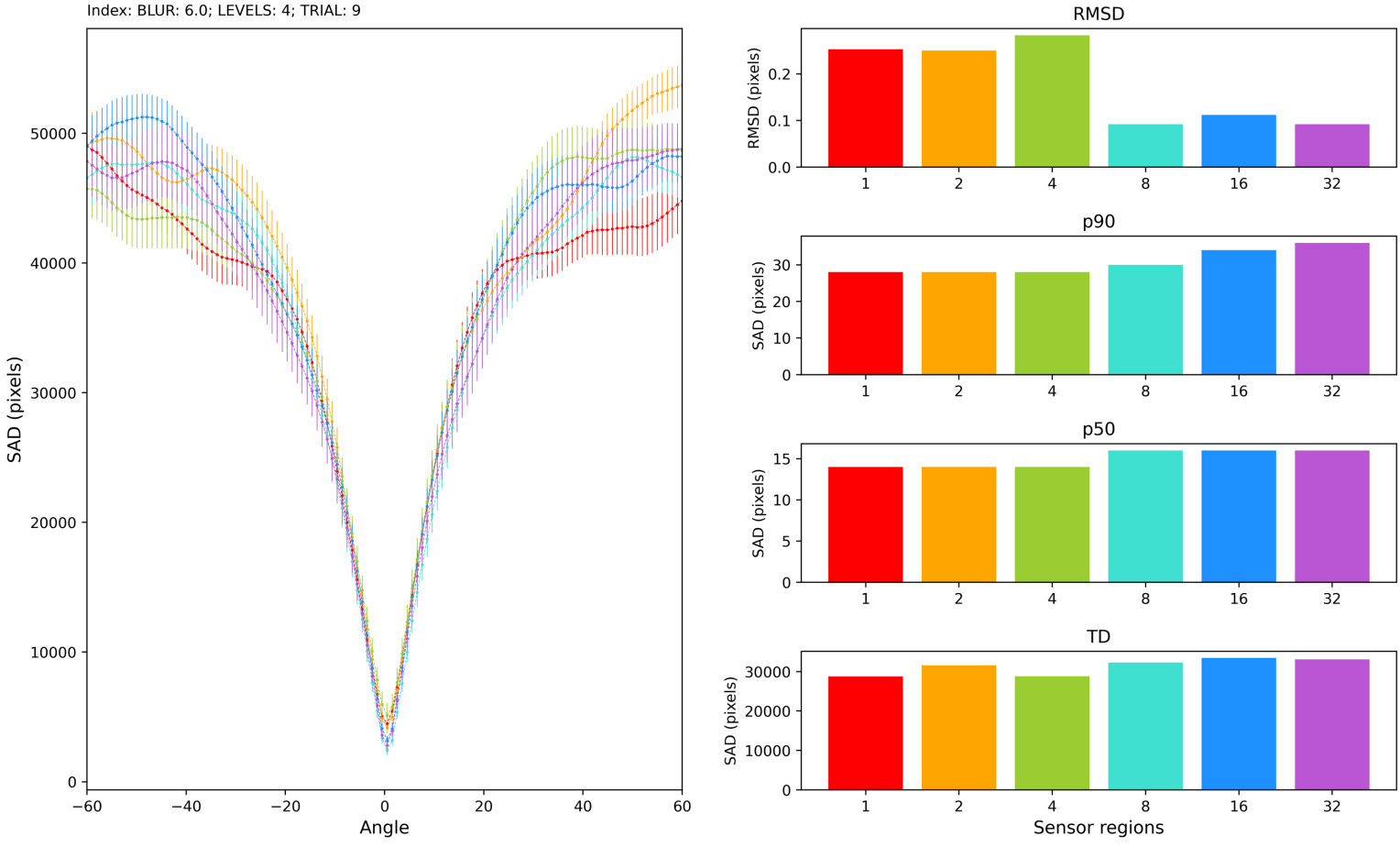




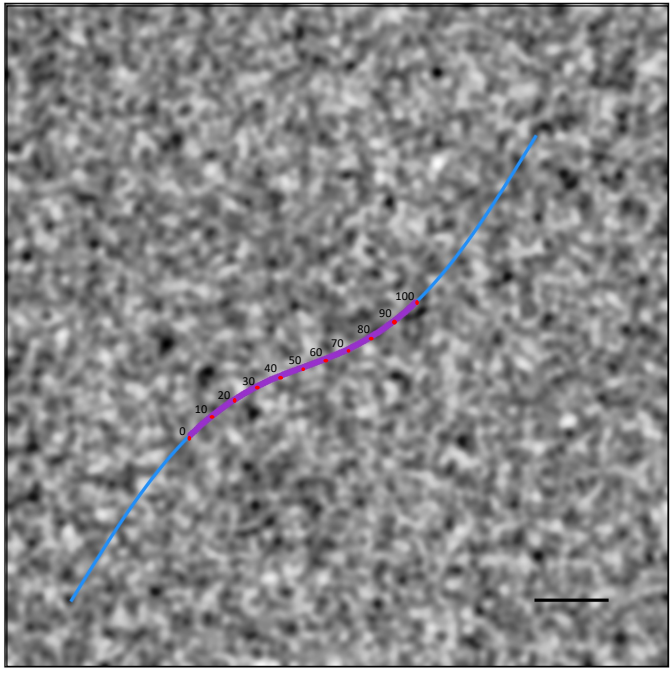


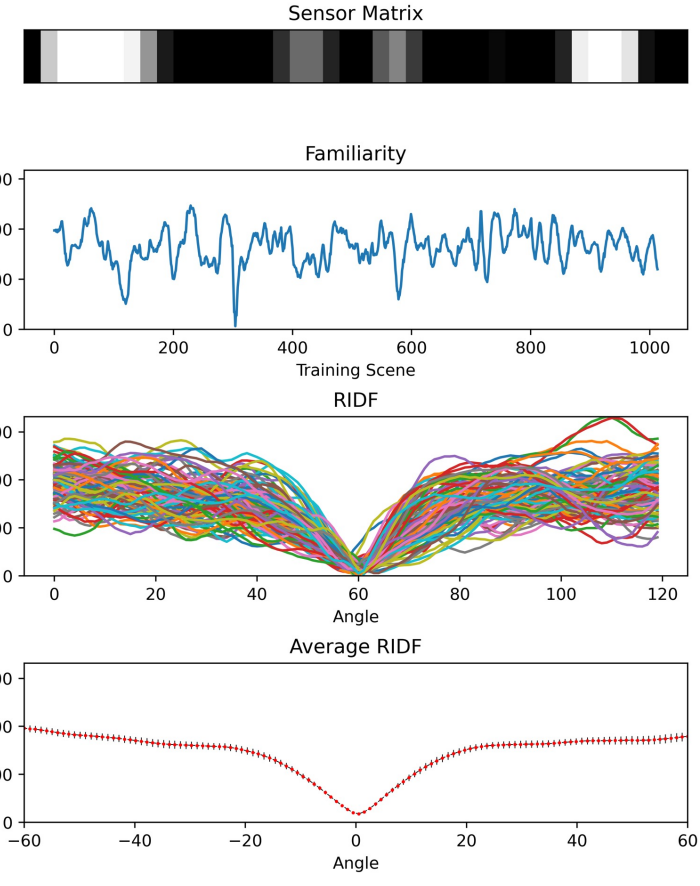
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 42.88; RMSD/dist: 0.107; TD: 32479; p90: 34; p50: 16; complete: 0


Index: BLUR: 6.0; LEVELS: 4; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

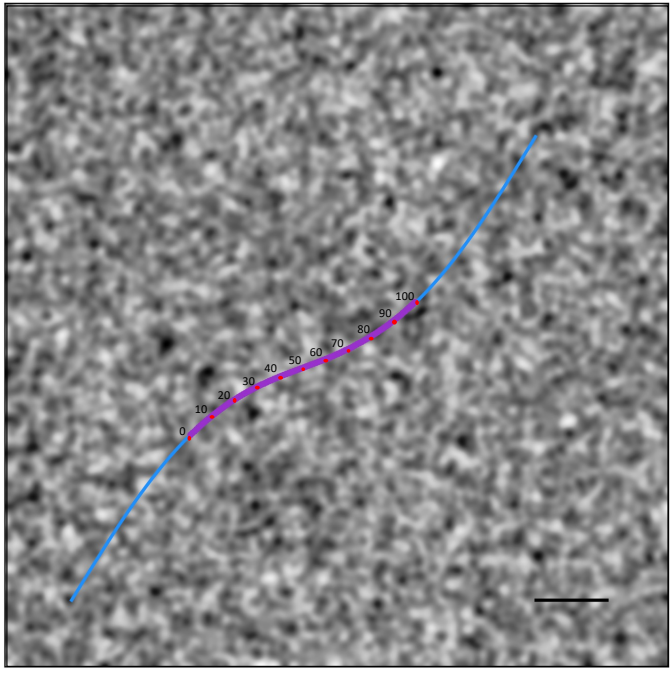


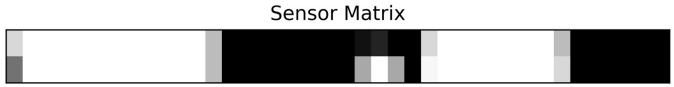


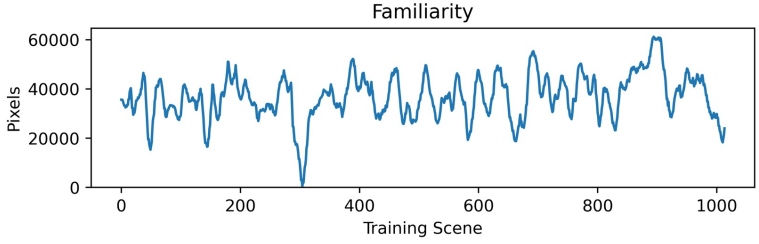
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

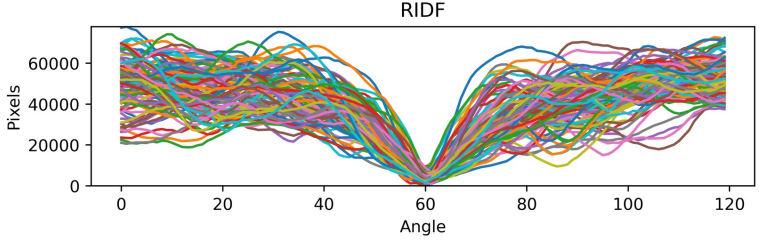
Navigation stats: RMSD error: 101.24; RMSD/dist: 0.253; TD: 28735; p90: 28; p50: 14; complete: 0

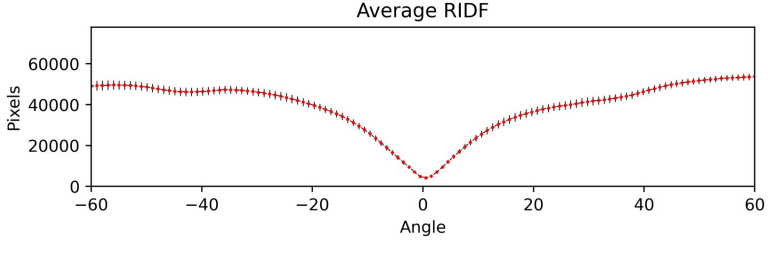
100%







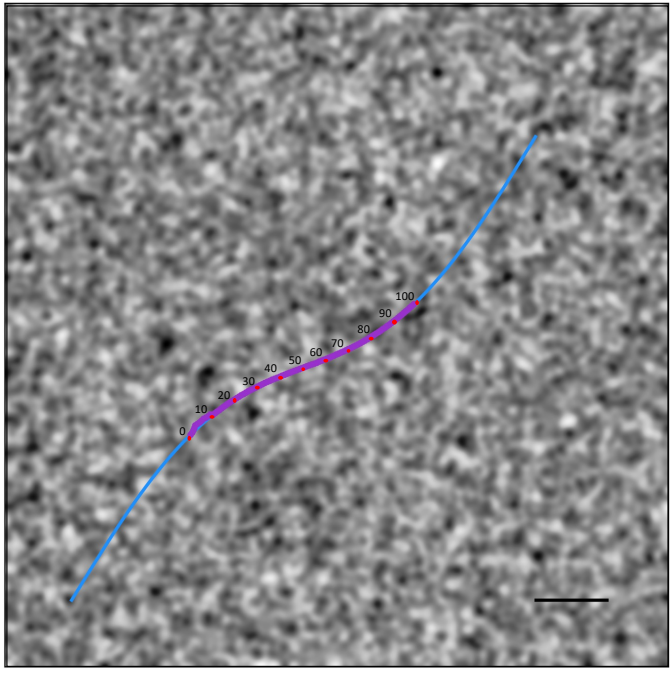


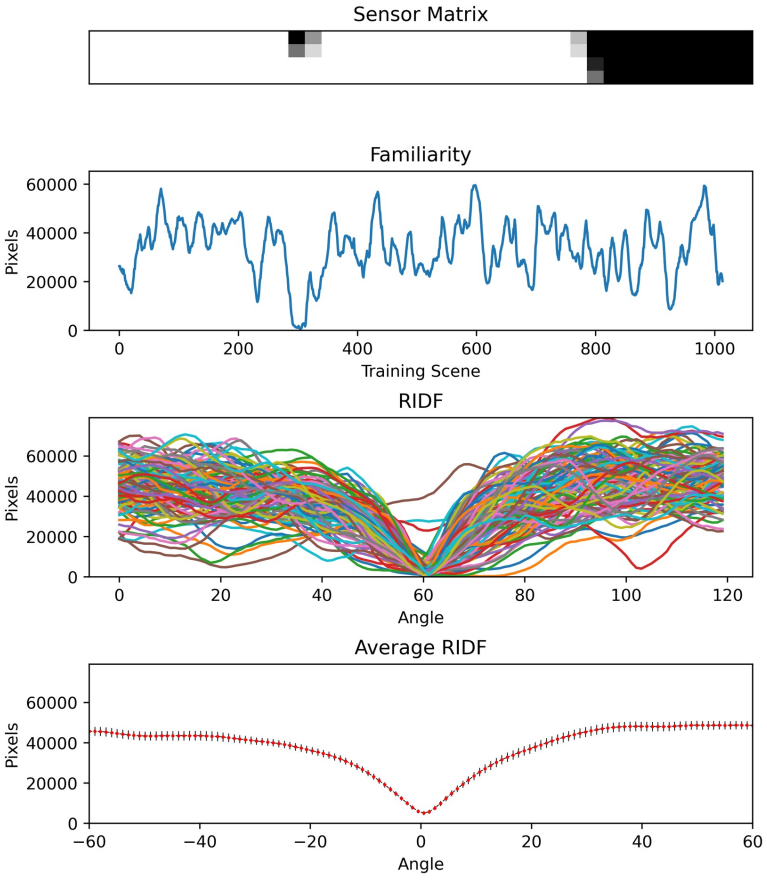


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 99.84; RMSD/dist: 0.250; TD: 31569; p90: 28; p50: 14; complete: 0

90%

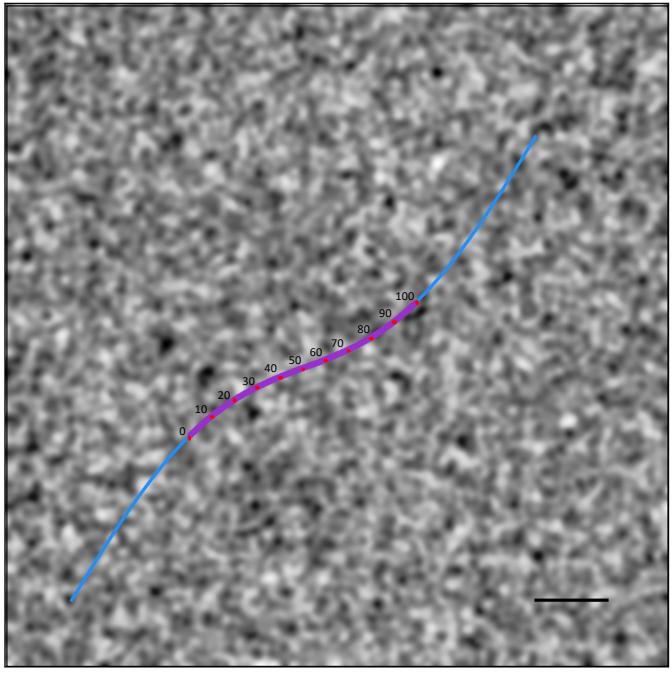


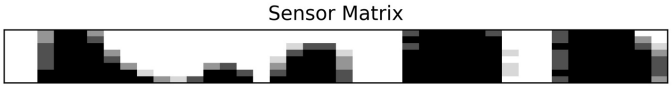


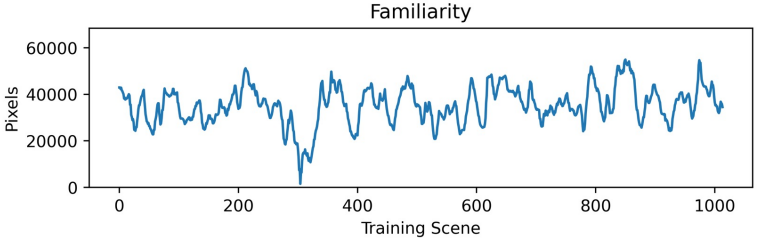
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

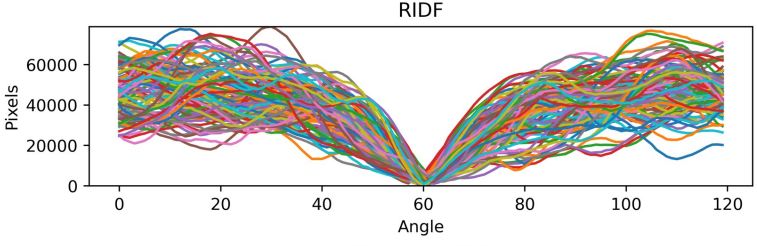
Navigation stats: RMSD error: 113.20; RMSD/dist: 0.283; TD: 28806; p90: 28; p50: 14; complete: 0

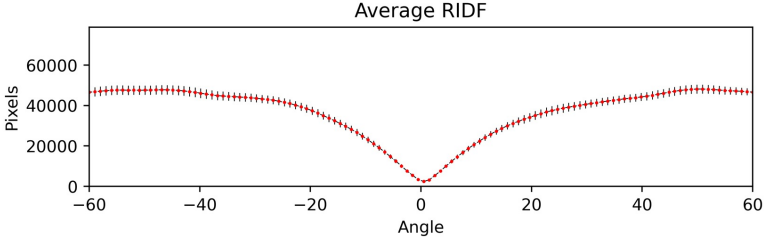
100%







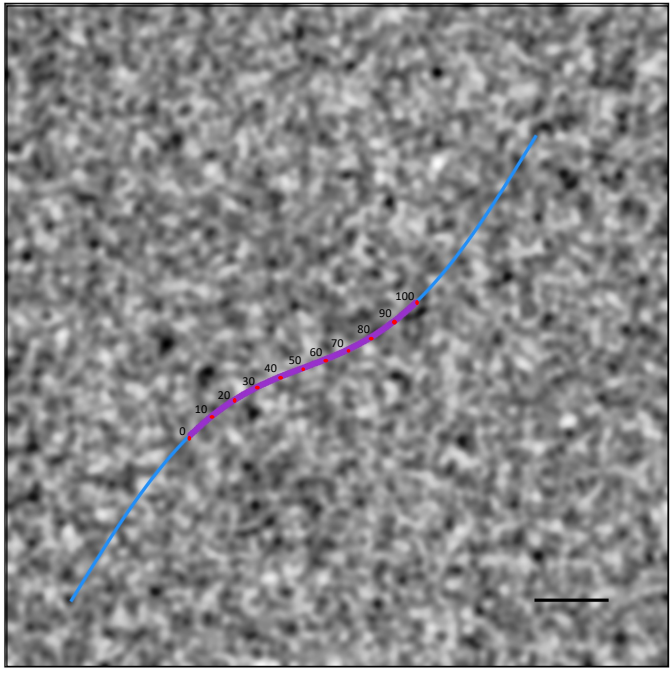


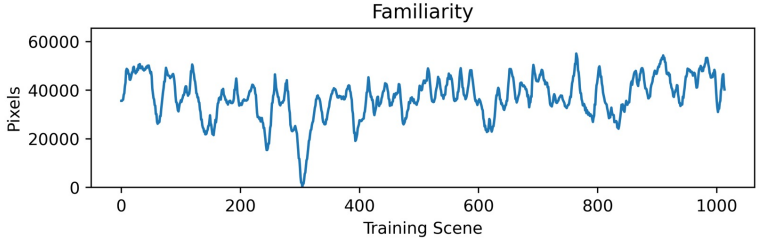


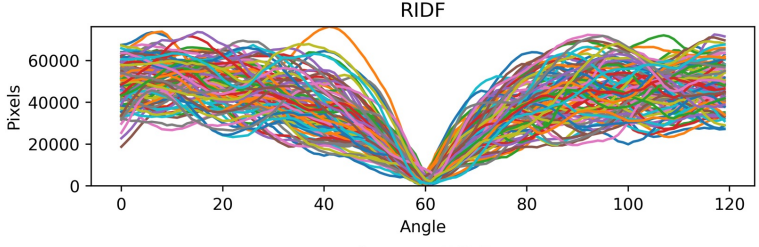
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

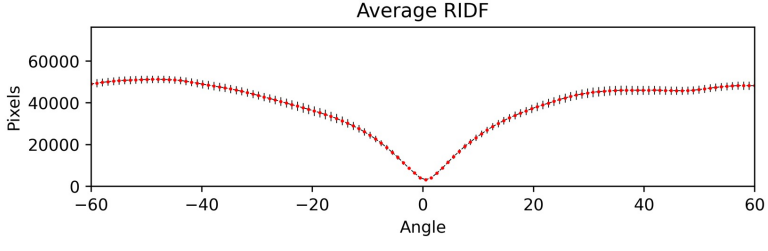
Navigation stats: RMSD error: 36.68; RMSD/dist: 0.092; TD: 32314; p90: 30; p50: 16; complete: 0

100%





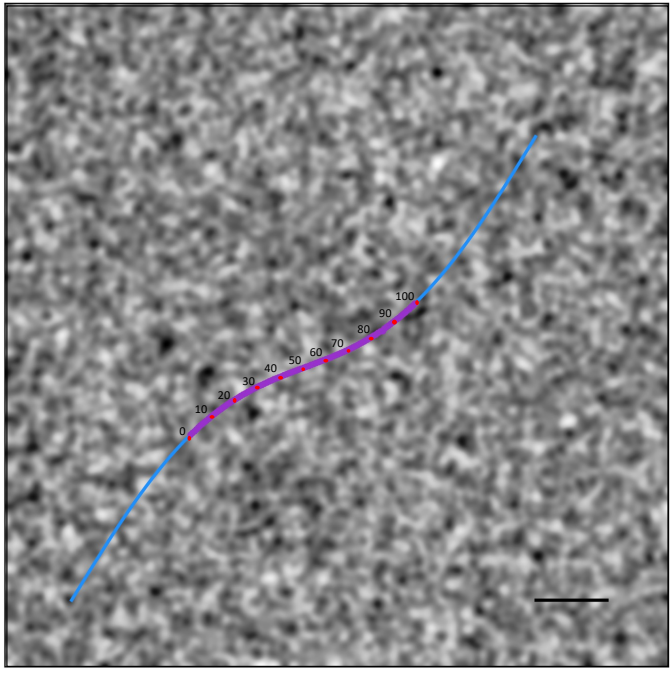


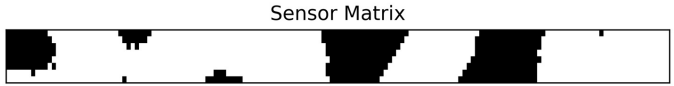


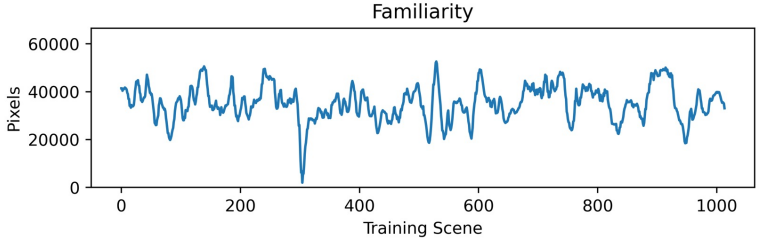
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

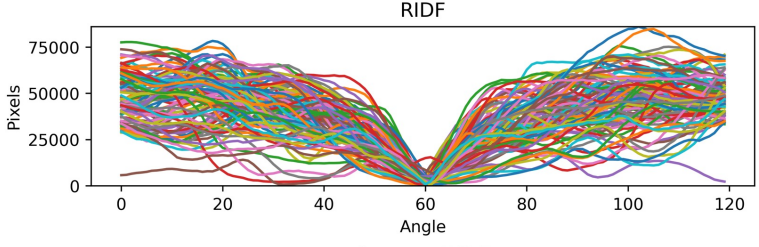
Navigation stats: RMSD error: 44.89; RMSD/dist: 0.112; TD: 33444; p90: 34; p50: 16; complete: 0

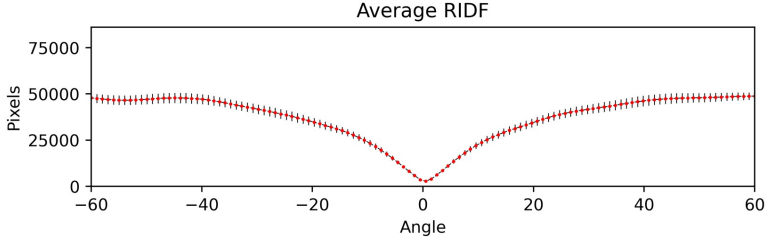
100%





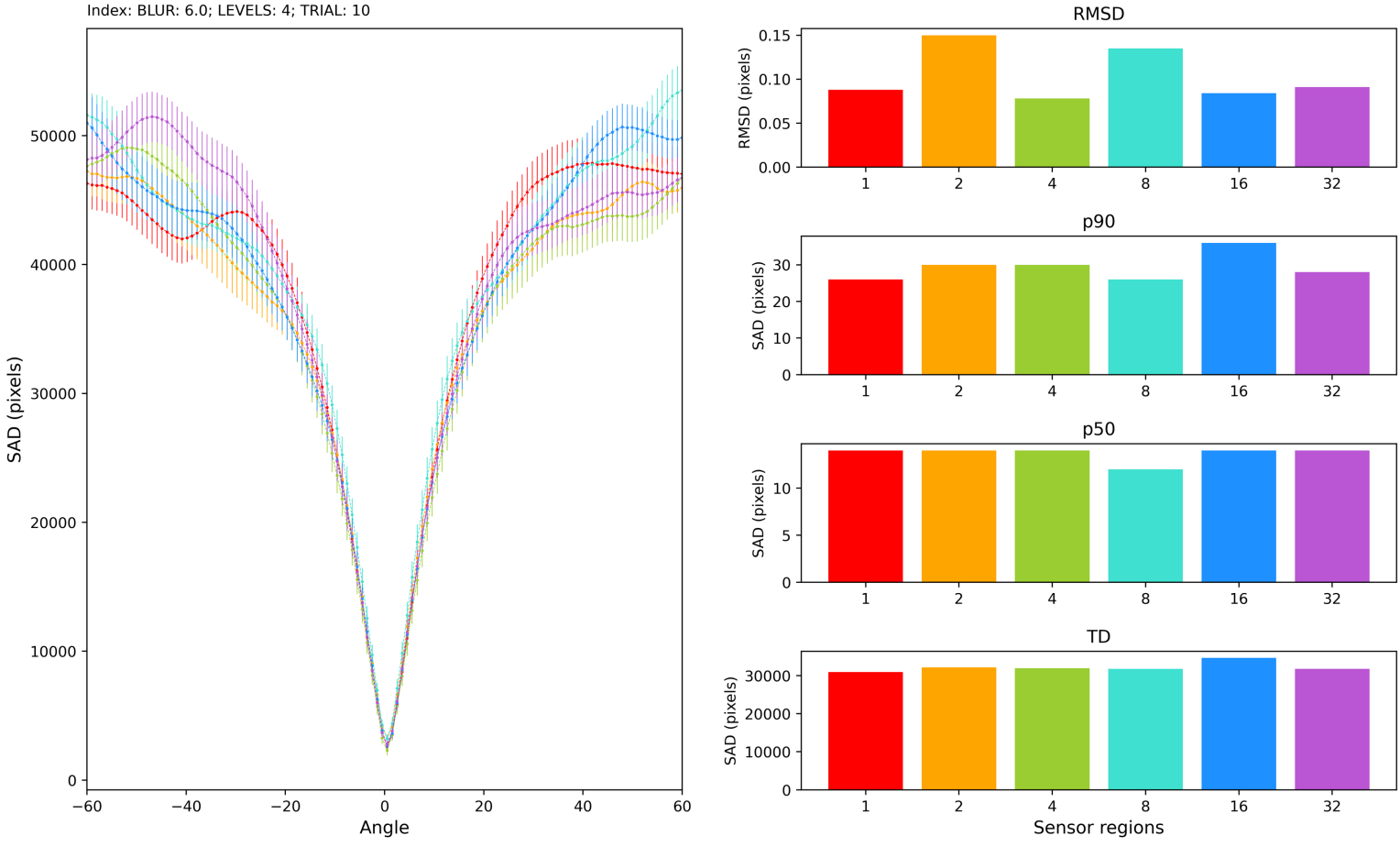




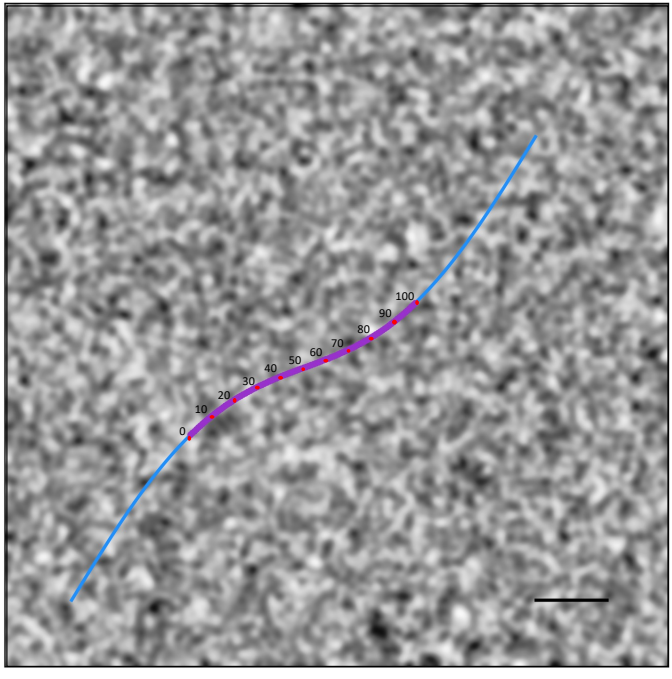


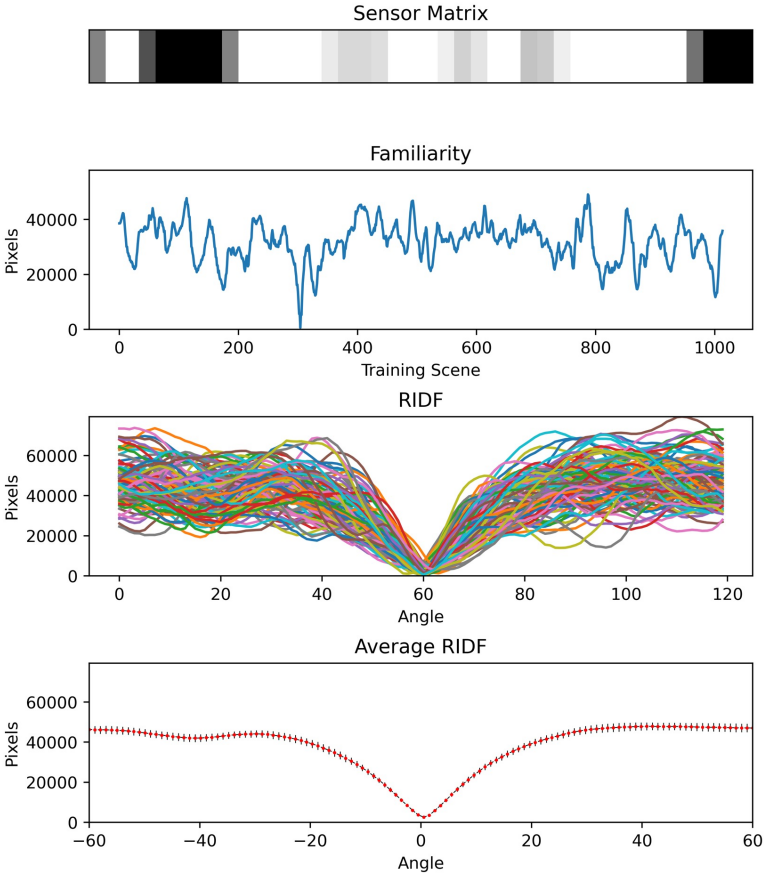
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 36.89; RMSD/dist: 0.092; TD: 33118; p90: 36; p50: 16; complete: 0


Index: BLUR: 6.0; LEVELS: 4; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

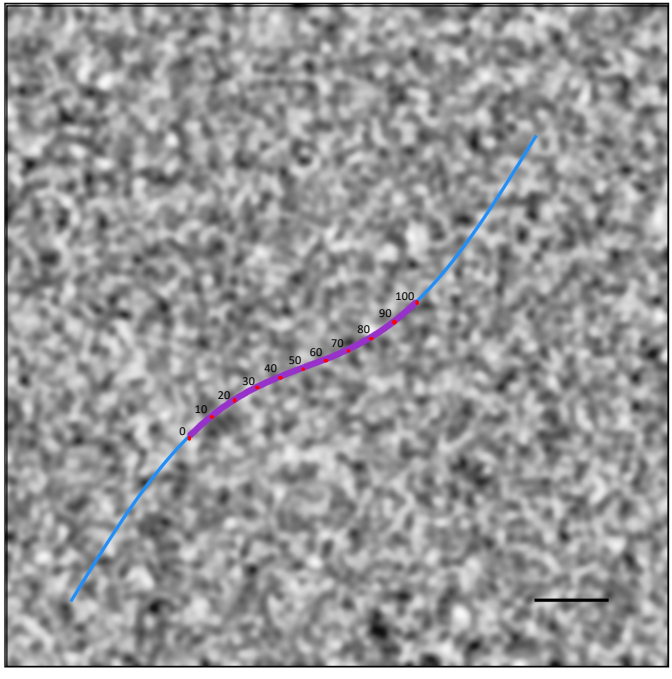


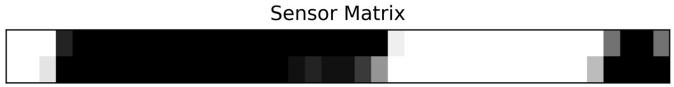


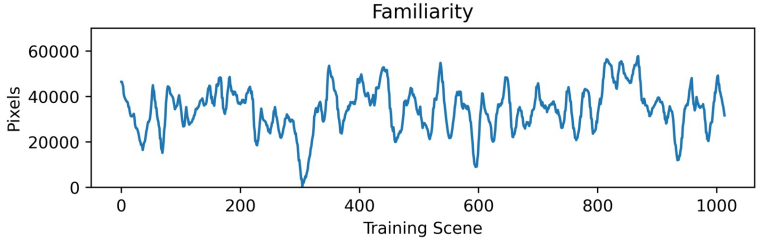
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

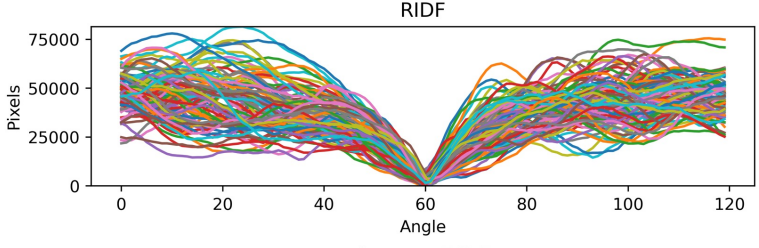
Navigation stats: RMSD error: 35.20; RMSD/dist: 0.088; TD: 30938; p90: 26; p50: 14; complete: 0

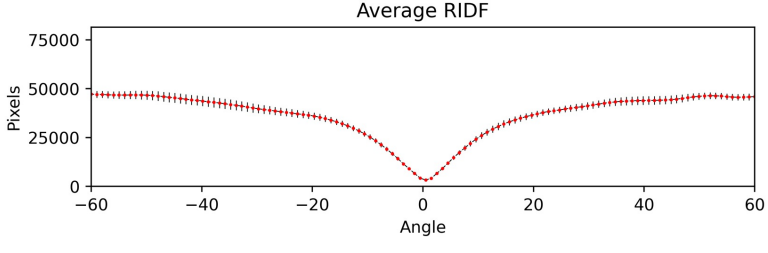
100%







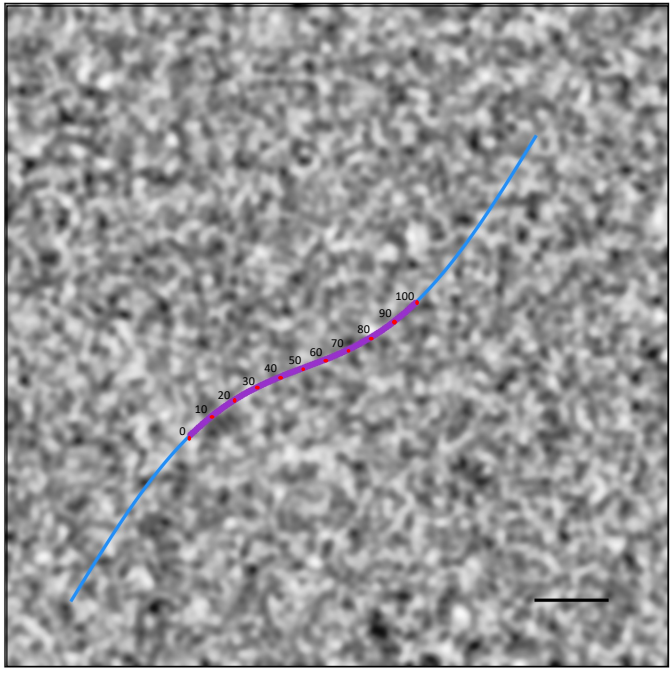


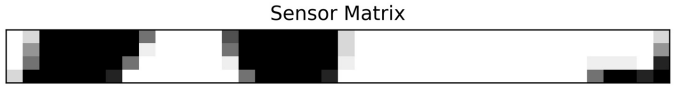


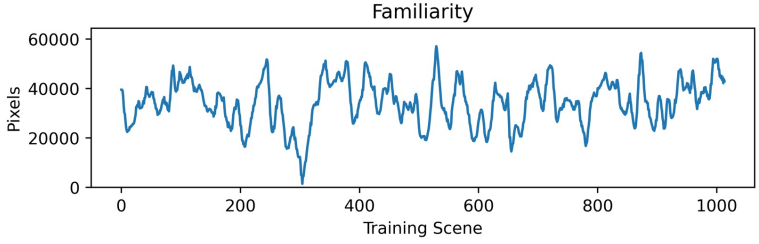
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

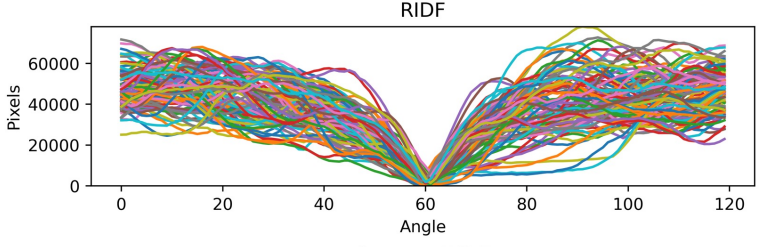
Navigation stats: RMSD error: 60.00; RMSD/dist: 0.150; TD: 32163; p90: 30; p50: 14; complete: 0

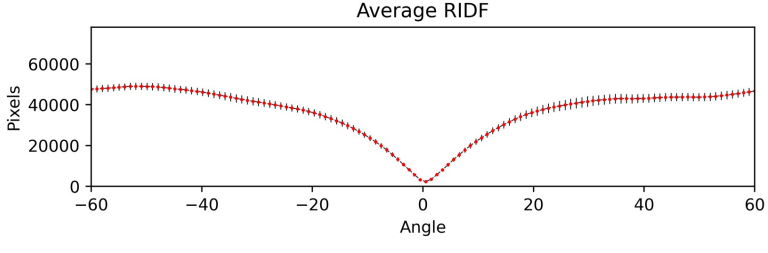
100%







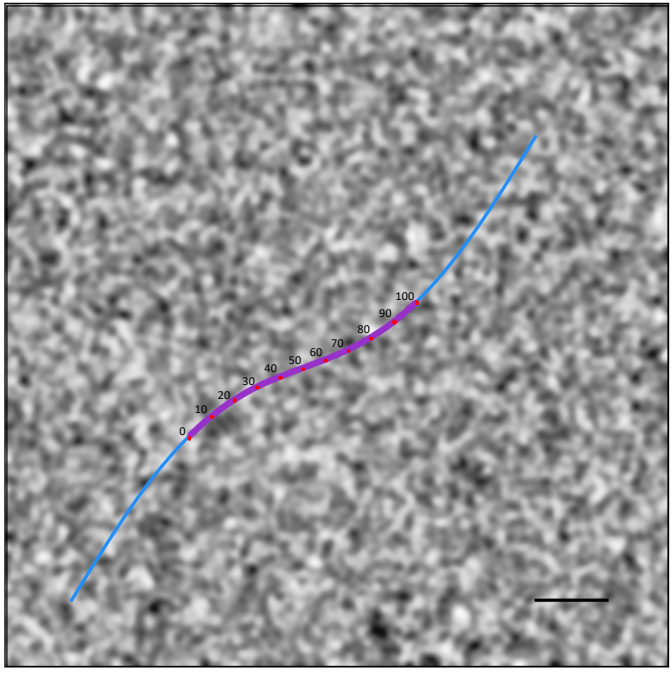


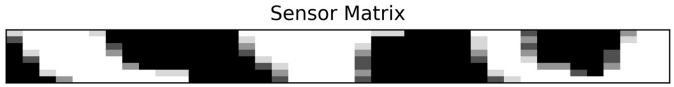


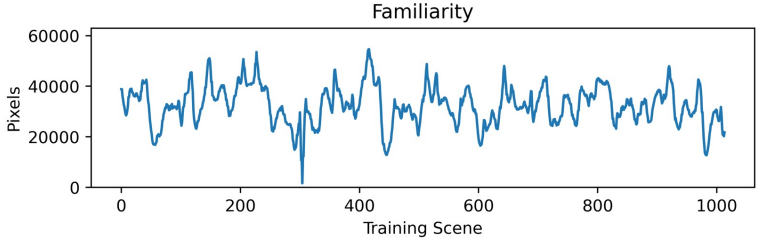
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

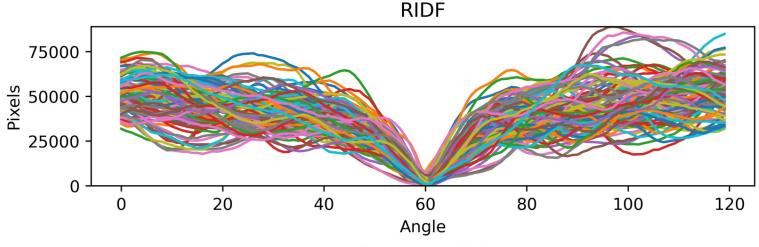
Navigation stats: RMSD error: 31.18; RMSD/dist: 0.078; TD: 31963; p90: 30; p50: 14; complete: 0

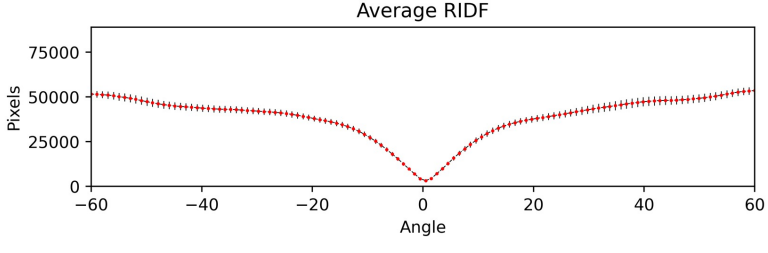
100%







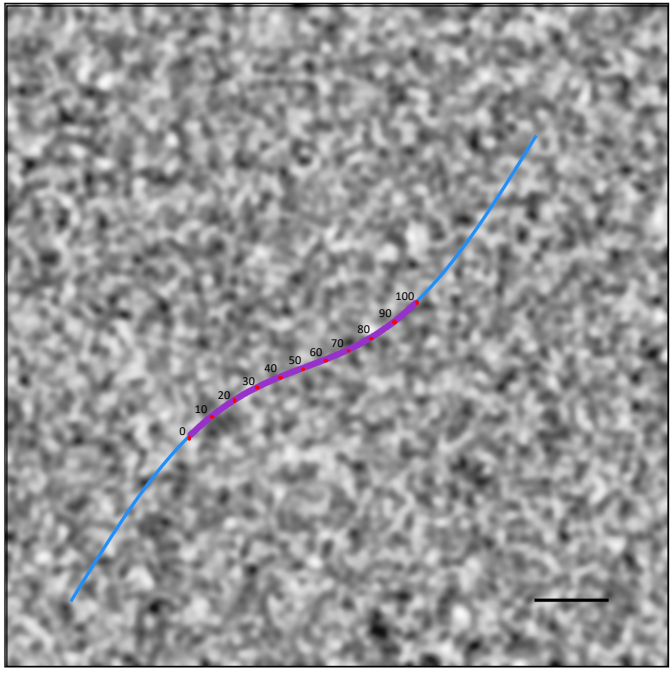


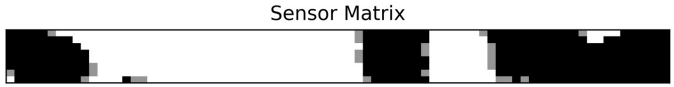


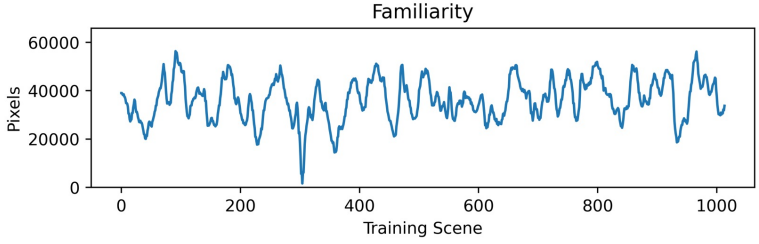
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

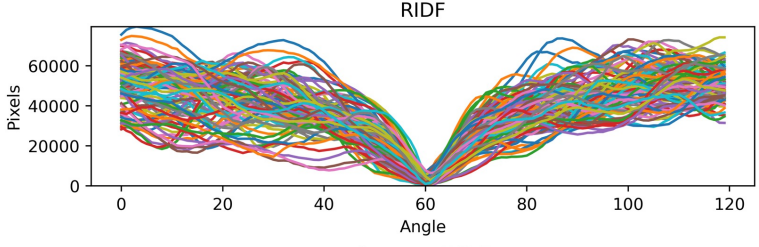
Navigation stats: RMSD error: 53.86; RMSD/dist: 0.135; TD: 31766; p90: 26; p50: 12; complete: 0

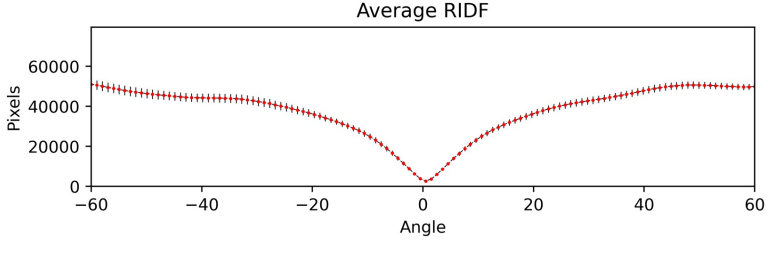
100%







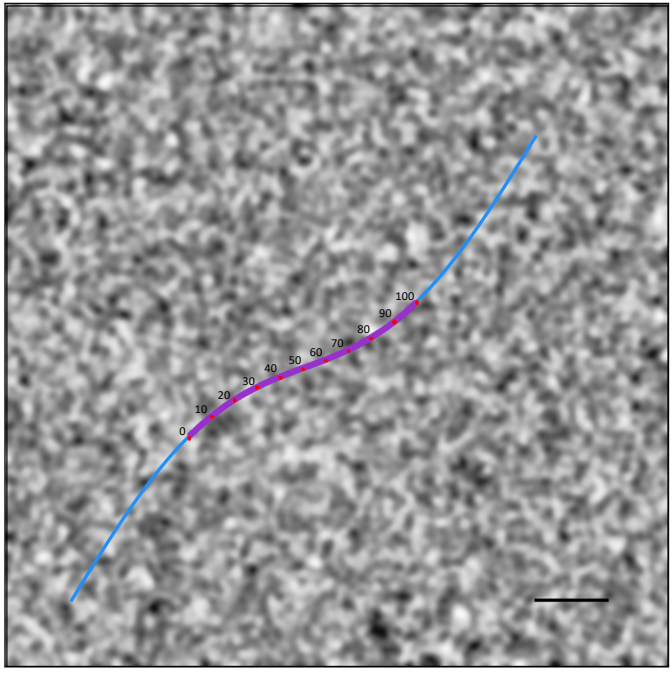


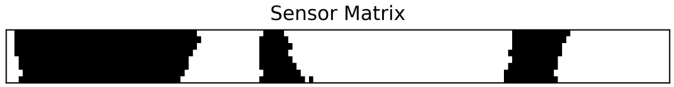


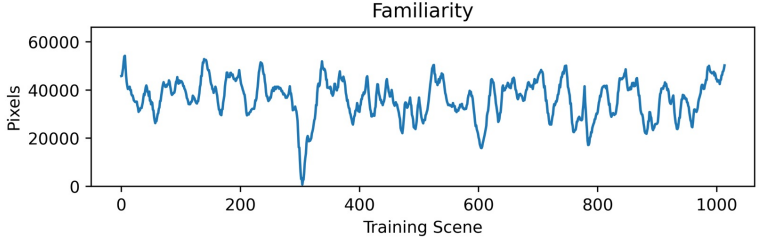
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

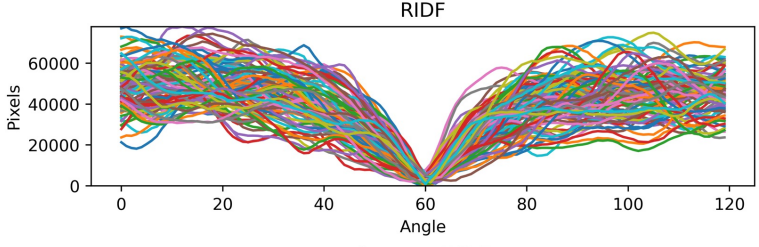
Navigation stats: RMSD error: 33.74; RMSD/dist: 0.084; TD: 34651; p90: 36; p50: 14; complete: 0

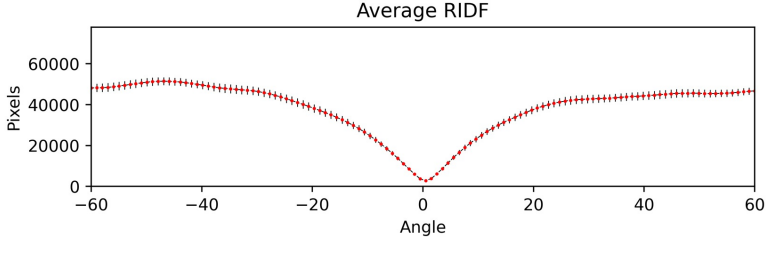
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 6; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 36.58; RMSD/dist: 0.091; TD: 31808; p90: 28; p50: 14; complete: 0