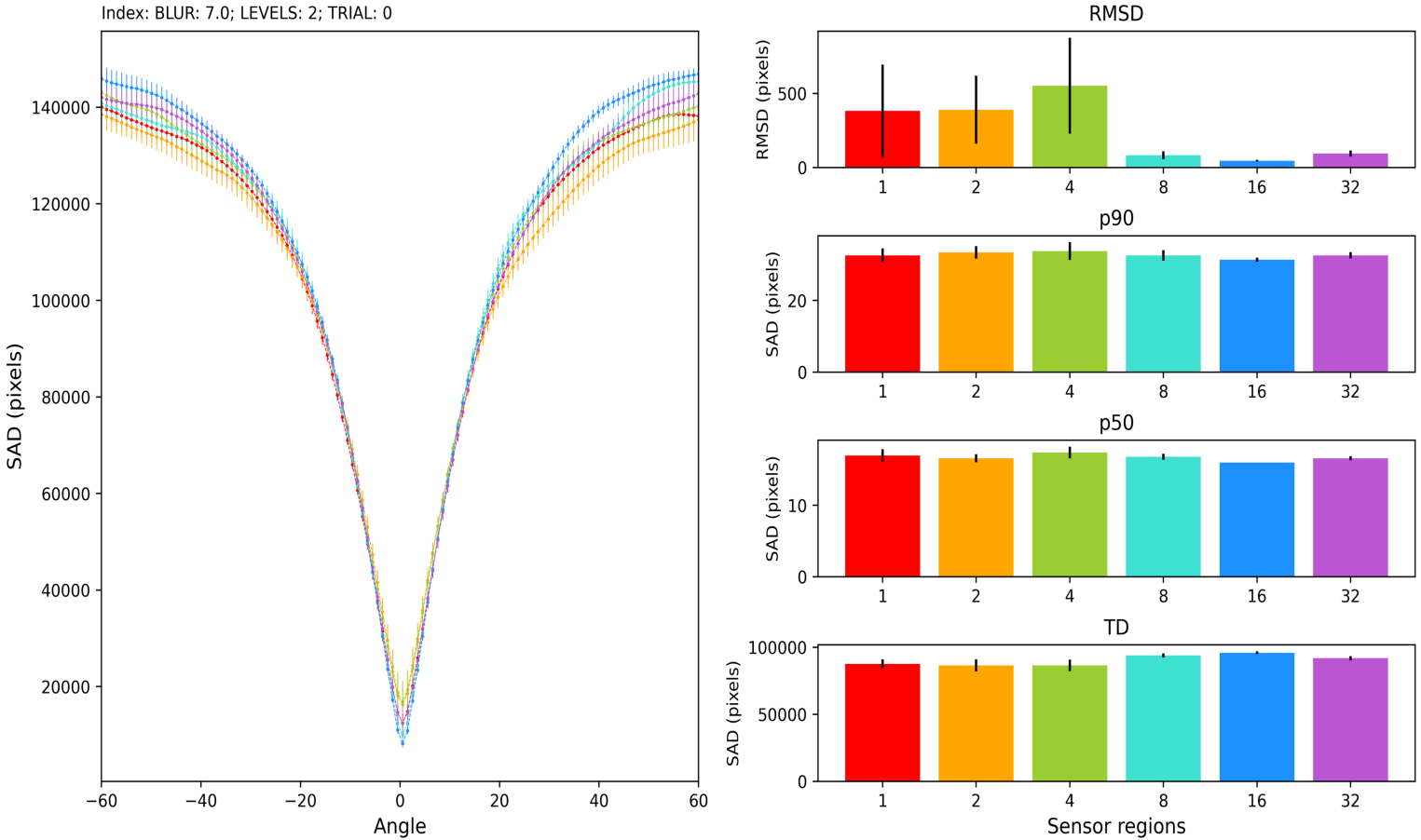
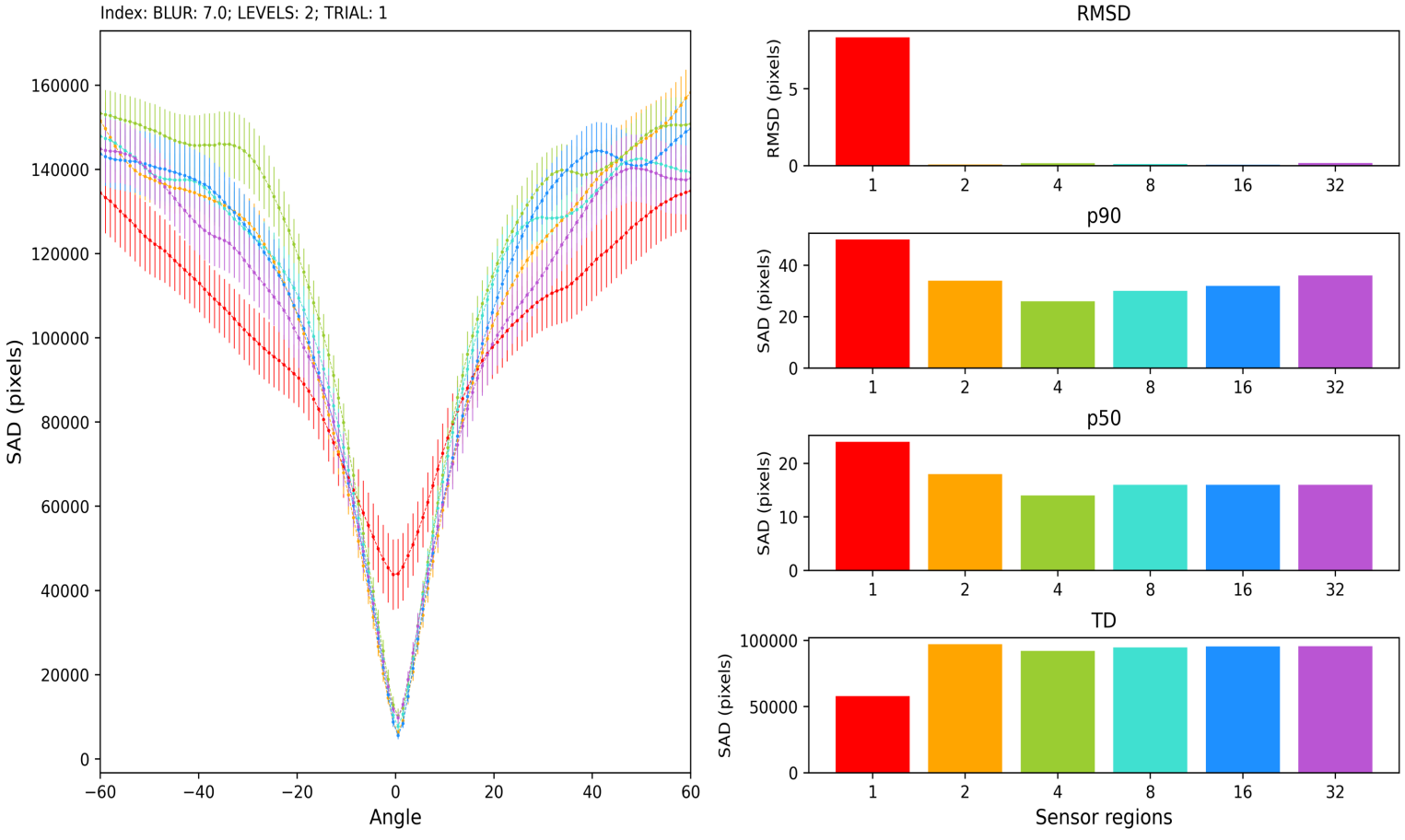
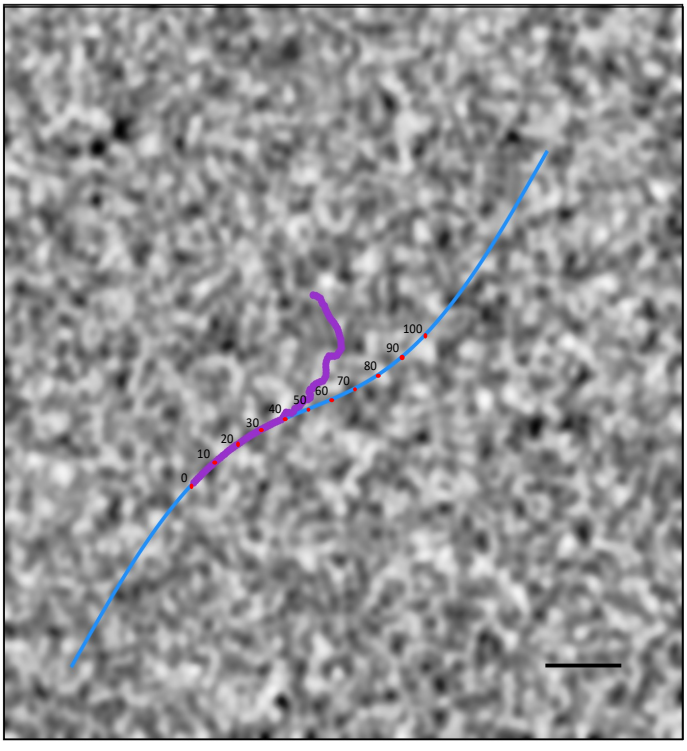
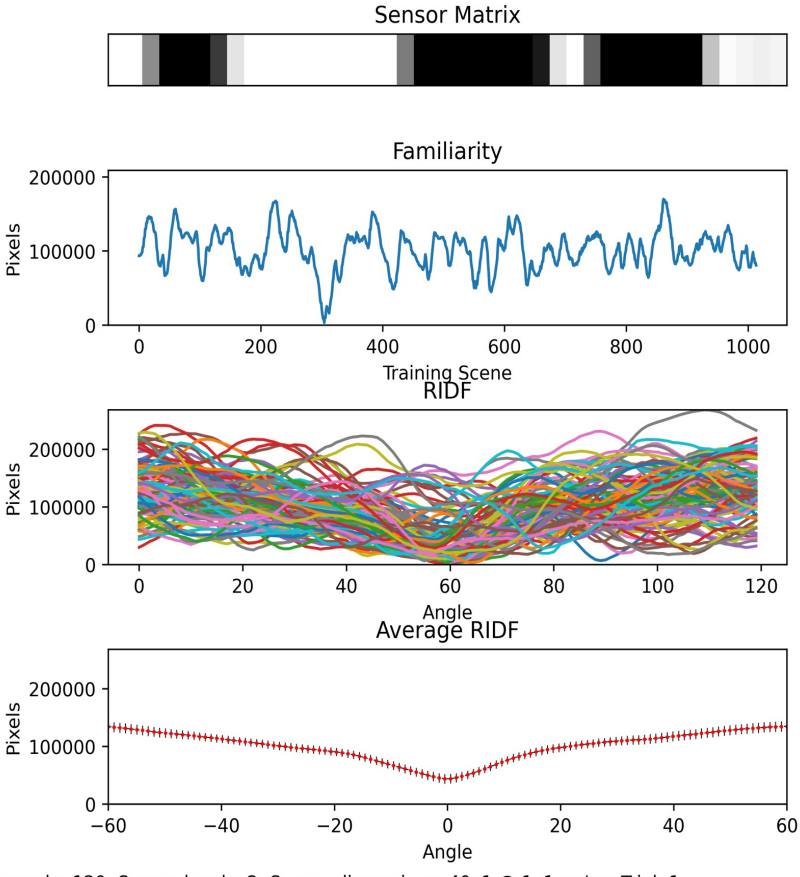

Index: BLUR: 7.0; LEVELS: 2; TRIAL: 0
SAD (pixels)
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
500
0
1
2
4
8
16
32
p90
SAD (pixels)
20
0
p50
SAD (pixels)
10
0
TD
SAD (pixels)
100000
50000
0
Sensor regions


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

40%

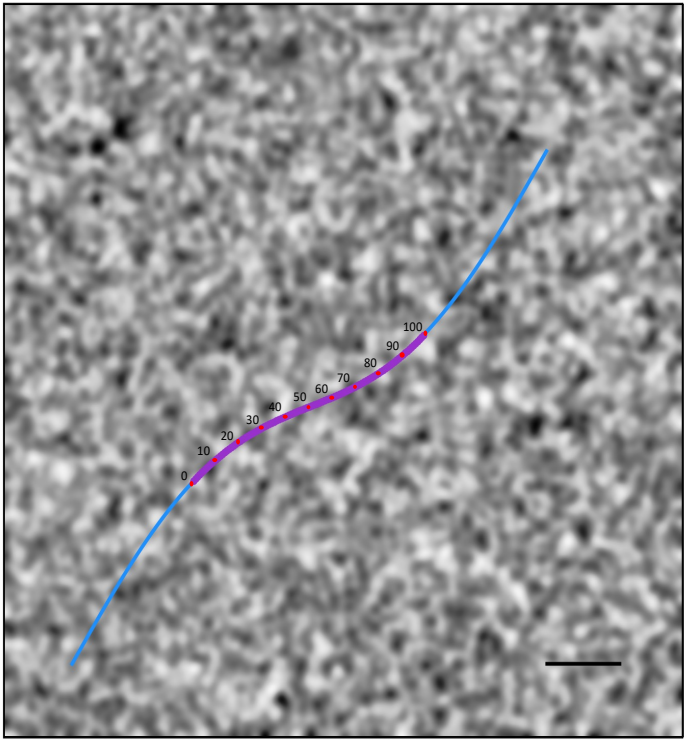


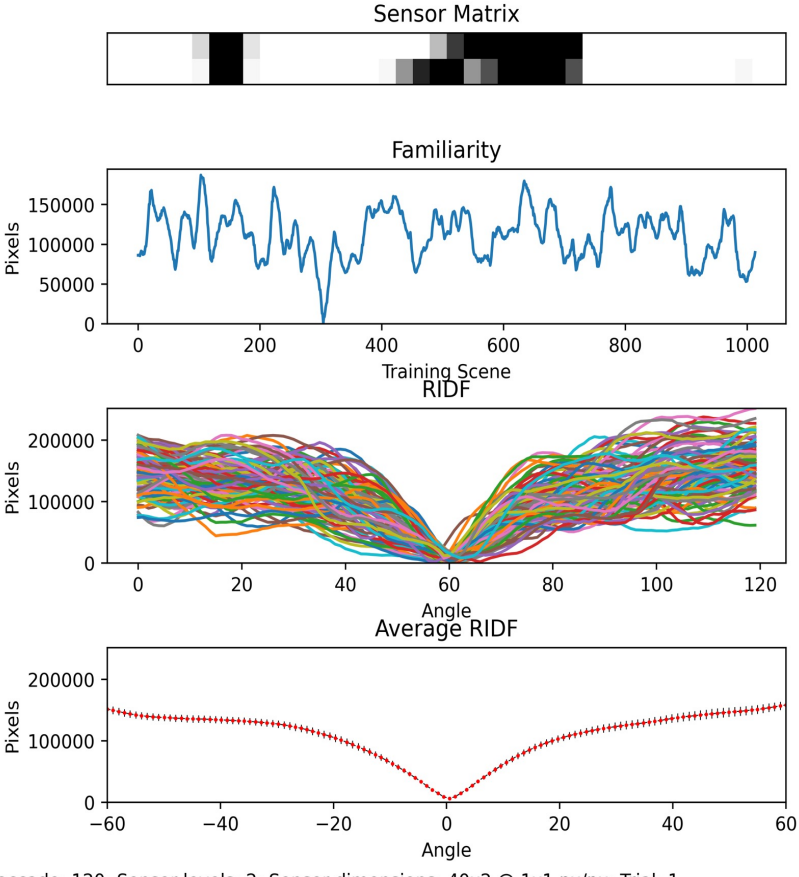


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3343.24; RMSD/dist: 8.358; TD: 57897; p90: 50; p50: 24; complete: 0

100%

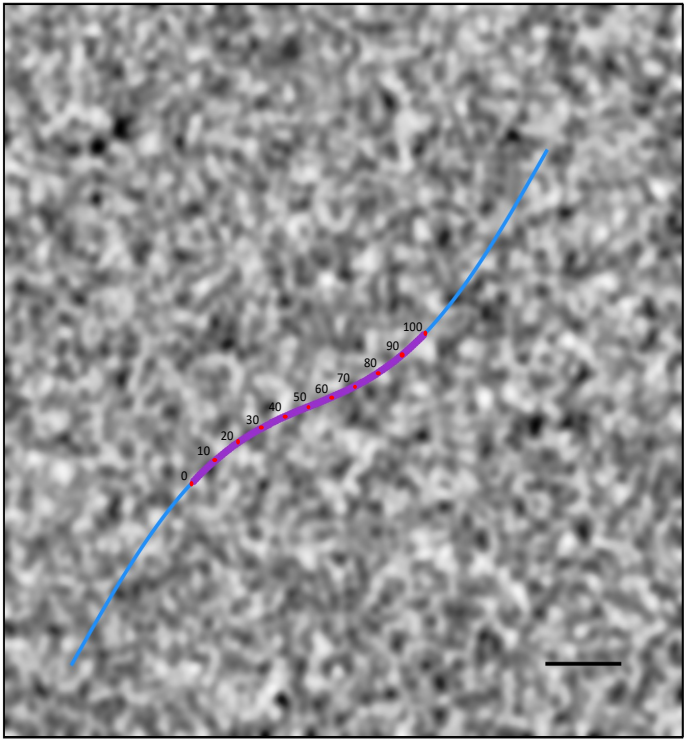


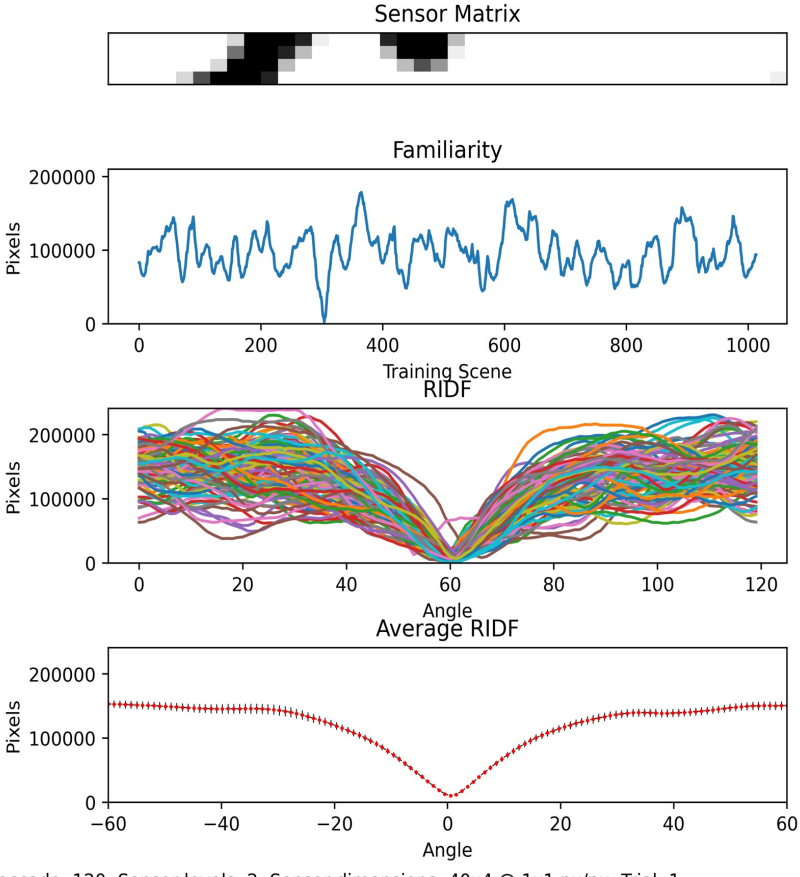


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 31.41; RMSD/dist: 0.079; TD: 97100; p90: 34; p50: 18; complete: 0

100%

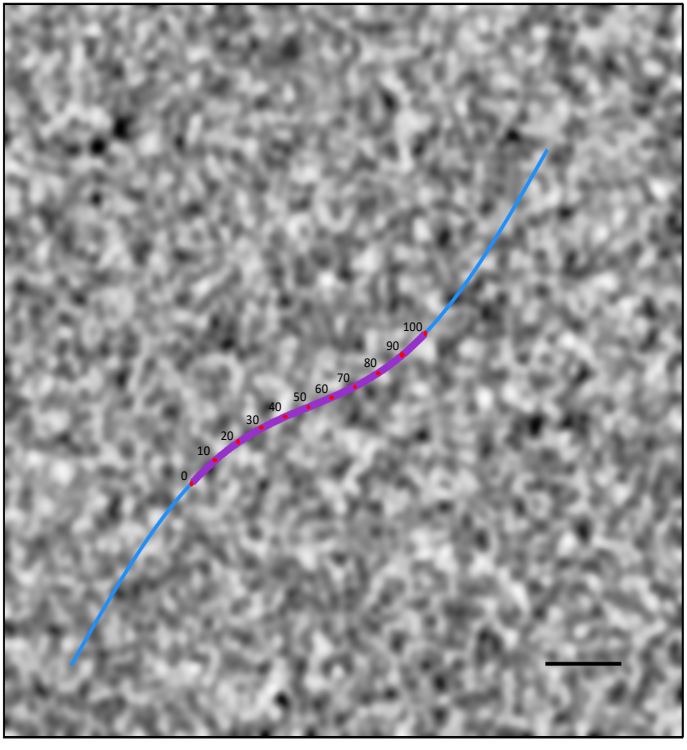


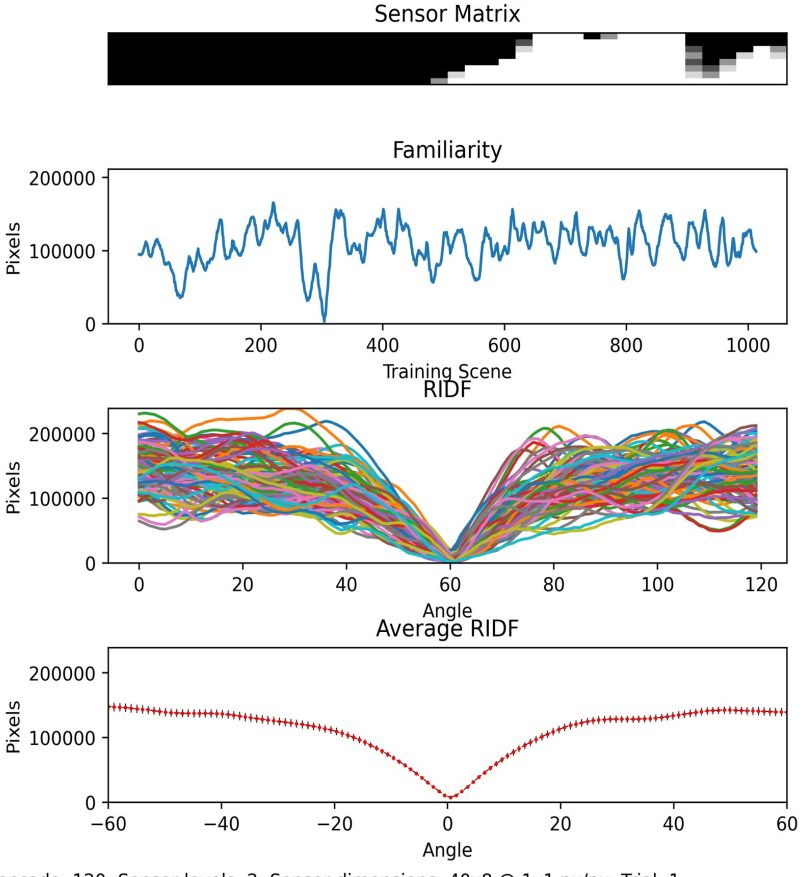


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 64.38; RMSD/dist: 0.161; TD: 92044; p90: 26; p50: 14; complete: 0

100%

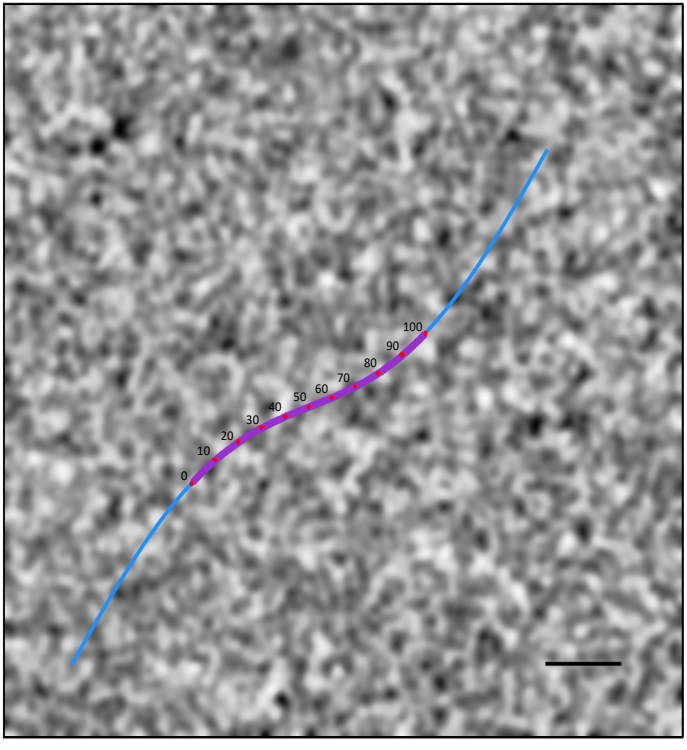


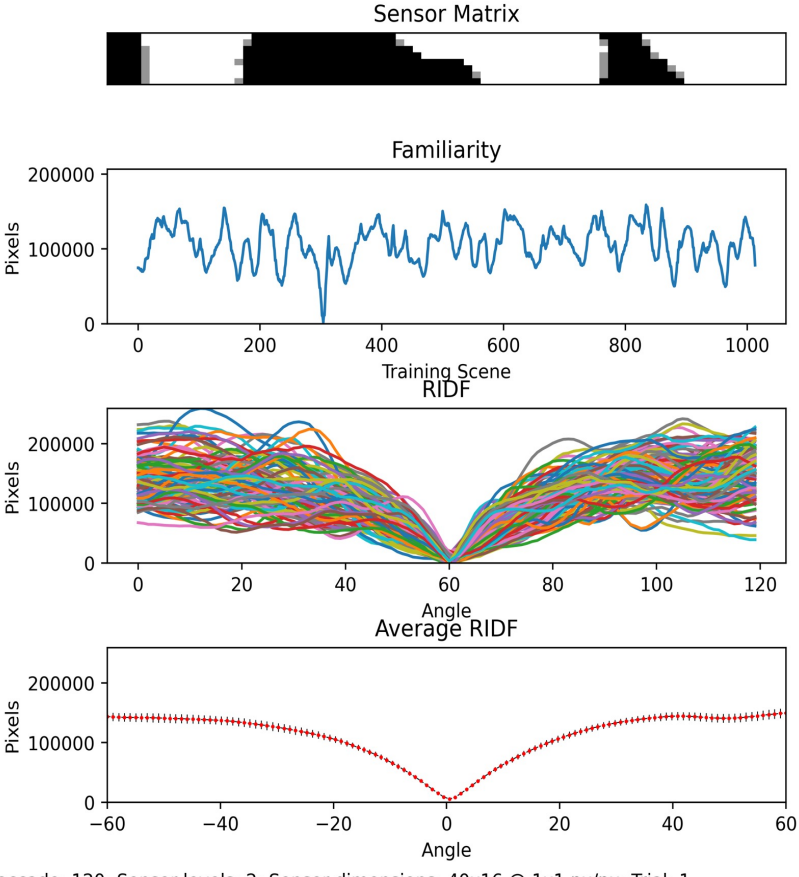


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 43.91; RMSD/dist: 0.110; TD: 94764; p90: 30; p50: 16; complete: 0

100%

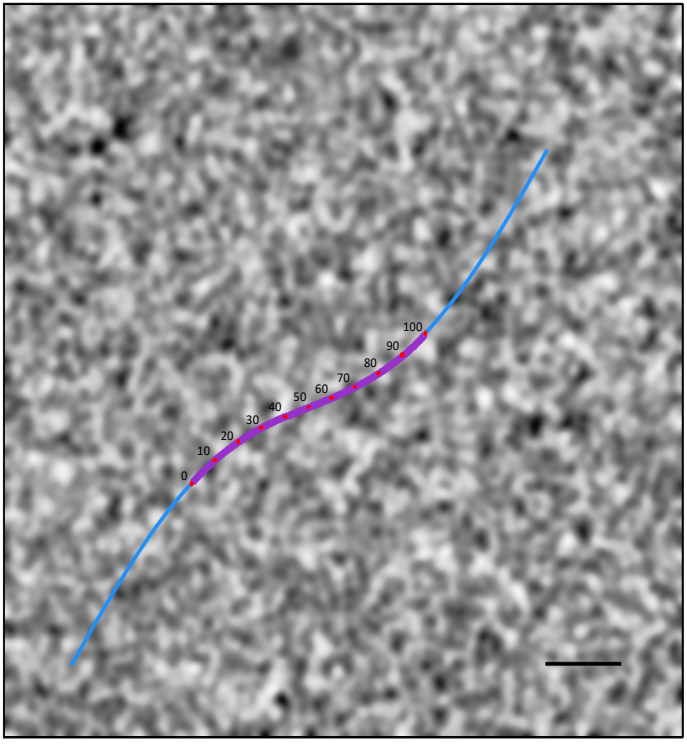


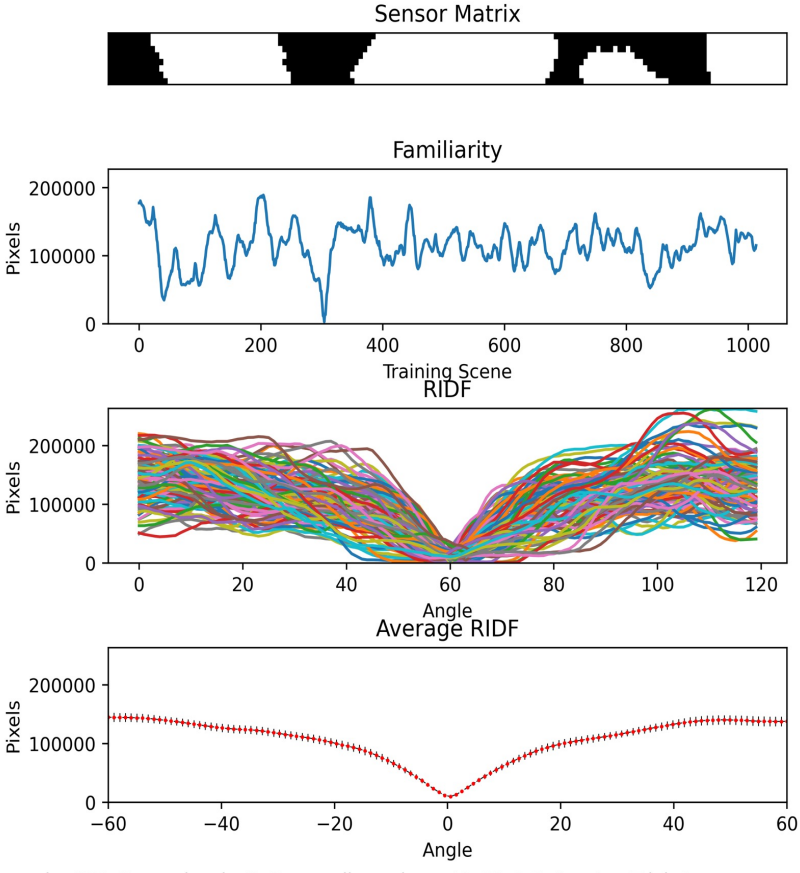


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 28.11; RMSD/dist: 0.070; TD: 95391; p90: 32; p50: 16; complete: 0

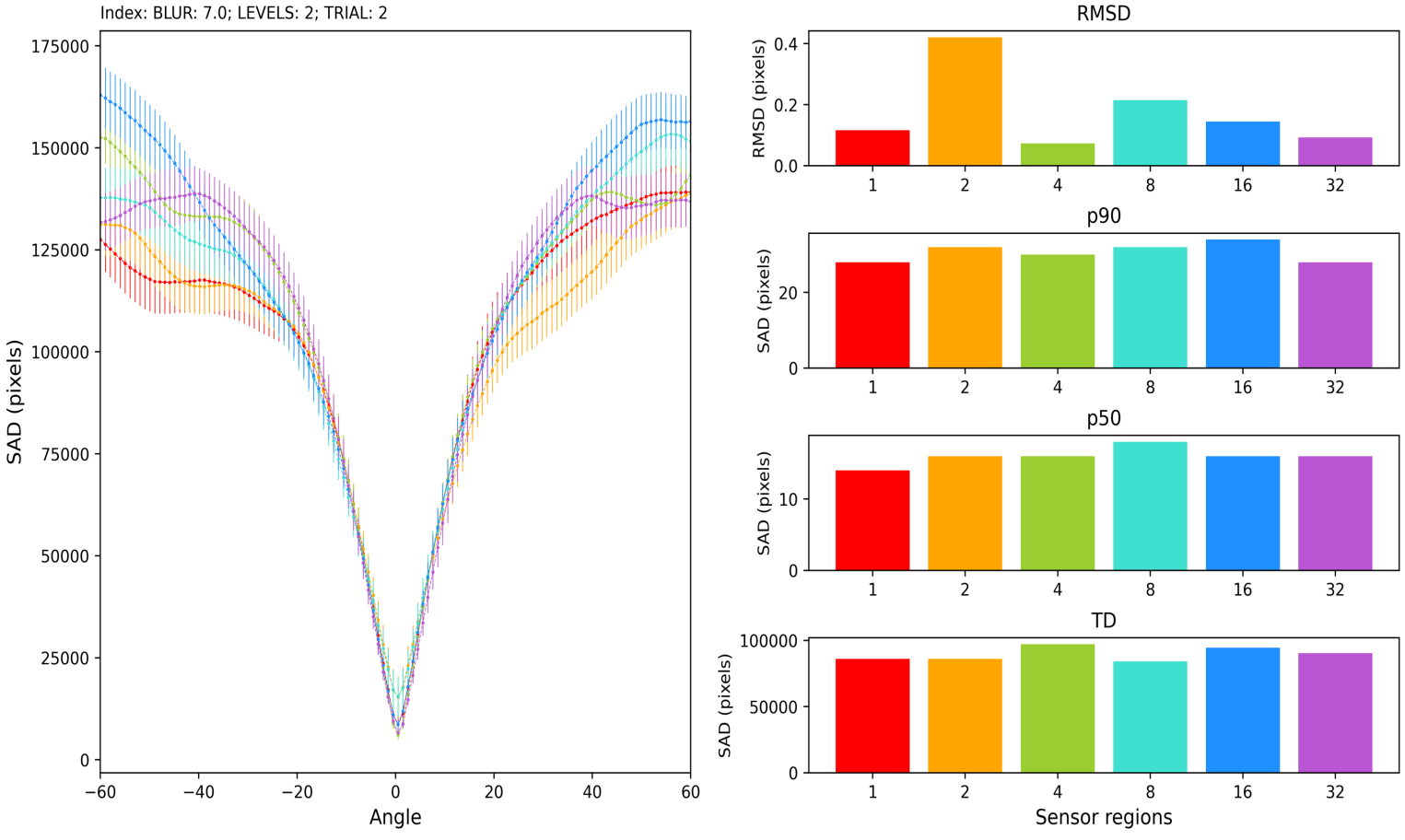
100%



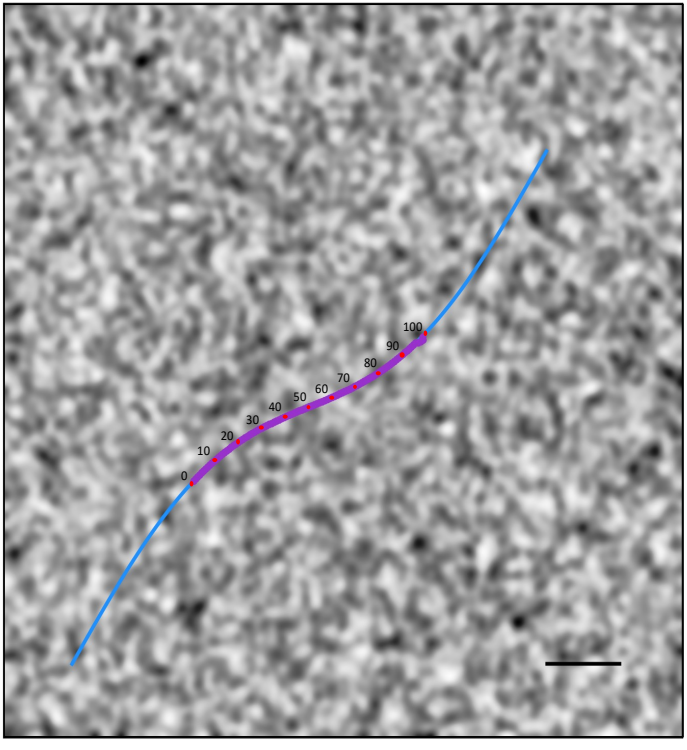


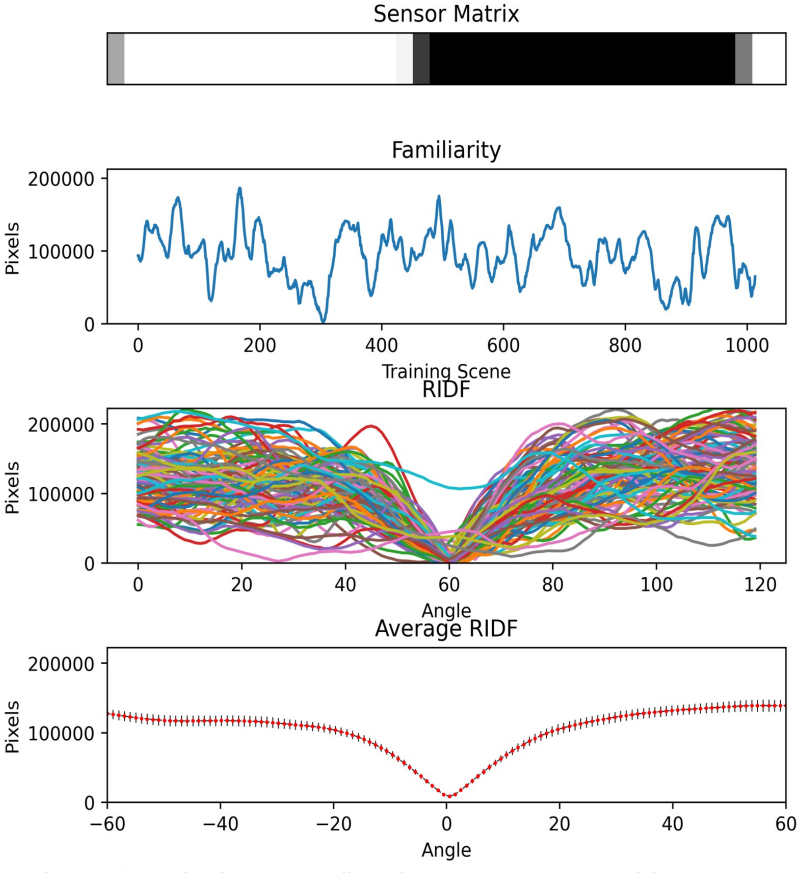
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 67.87; RMSD/dist: 0.170; TD: 95725; p90: 36; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 2
SAD (pixels)
175000
150000
125000
100000
75000
50000
25000
0
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.4
0.2
0.0
1
2
4
8
16
32
p90
SAD (pixels)
20
0
p50
SAD (pixels)
10
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

90%

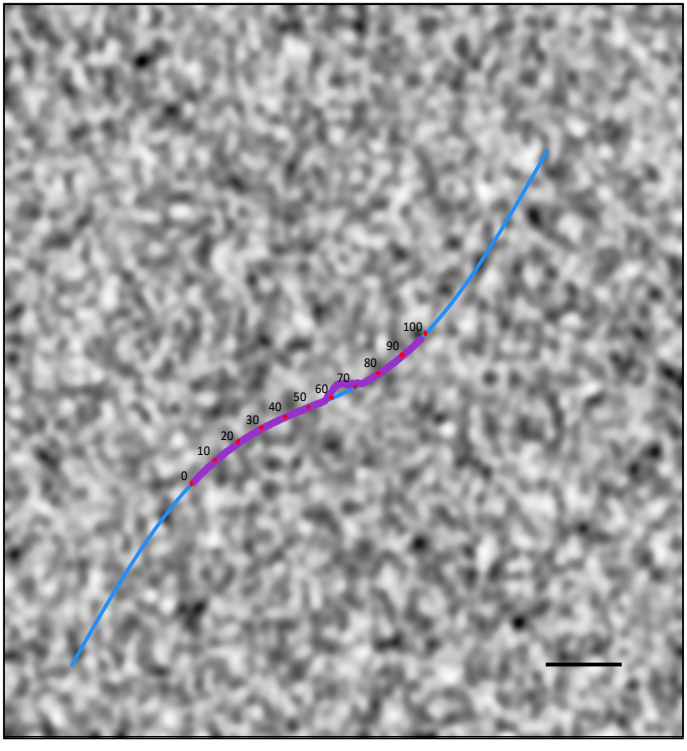


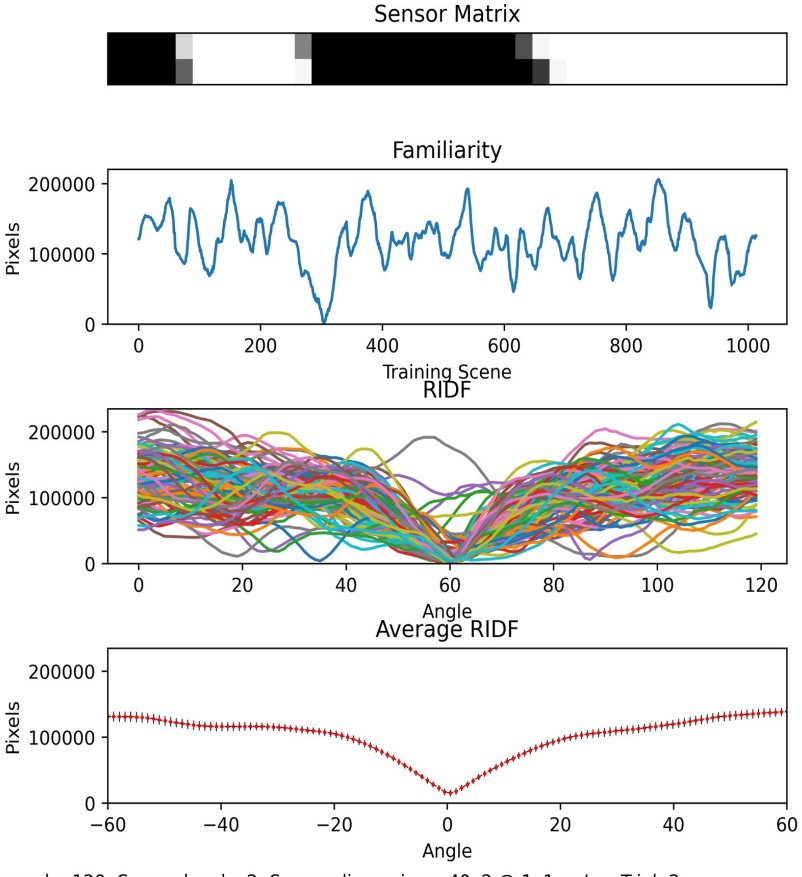


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 46.32; RMSD/dist: 0.116; TD: 86029; p90: 28; p50: 14; complete: 0

80%

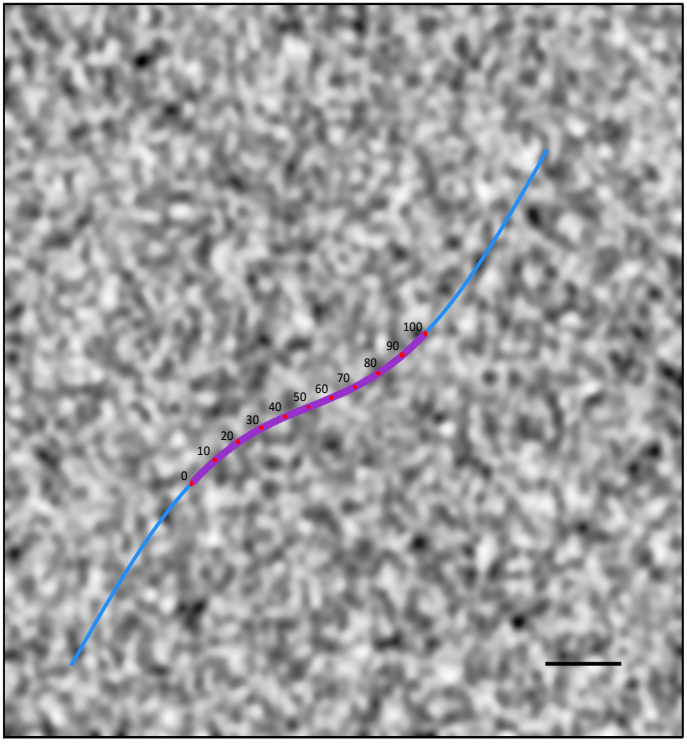


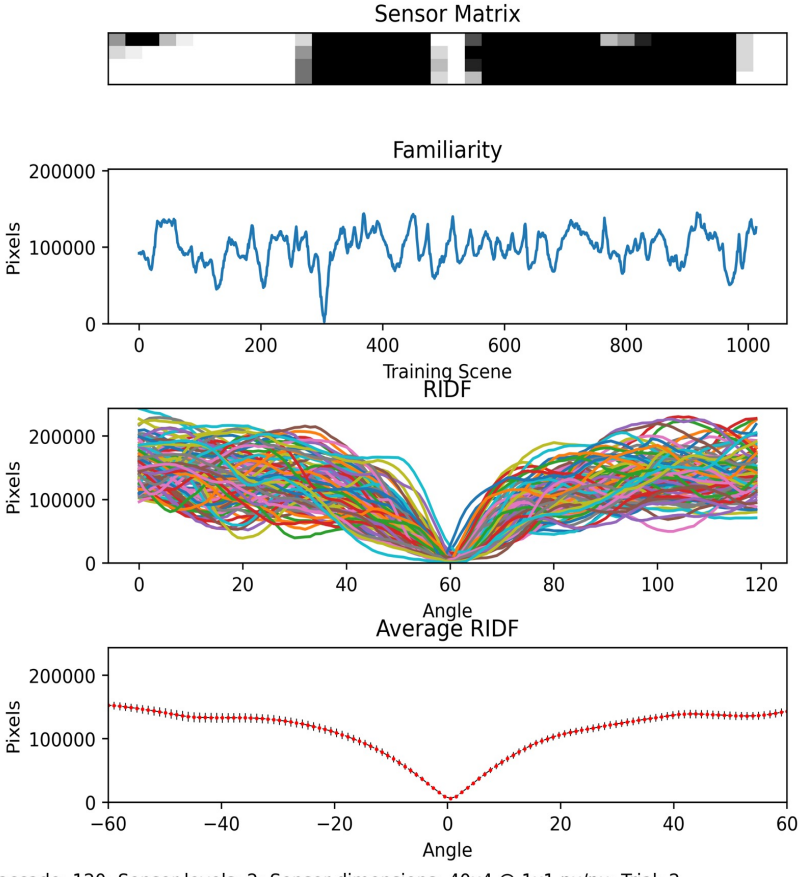


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 168.26; RMSD/dist: 0.421; TD: 86027; p90: 32; p50: 16; complete: 0

100%

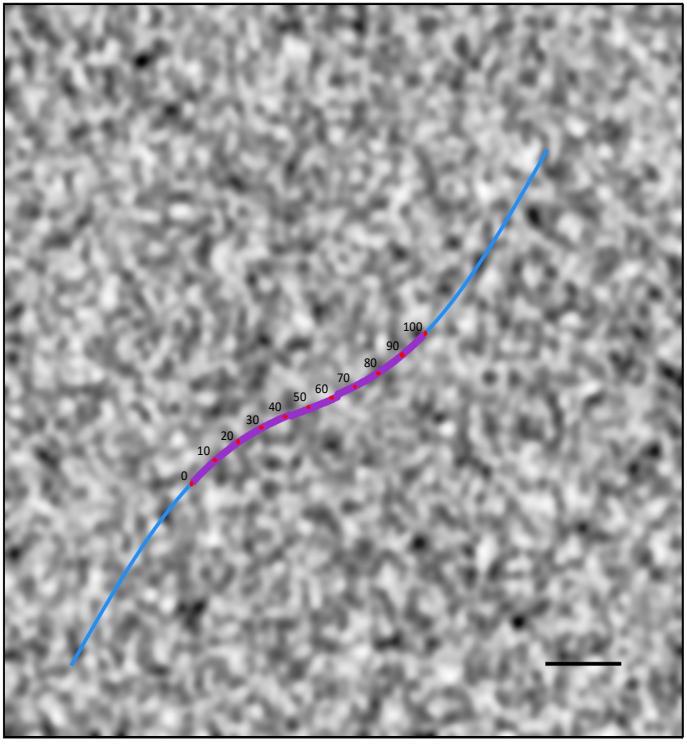


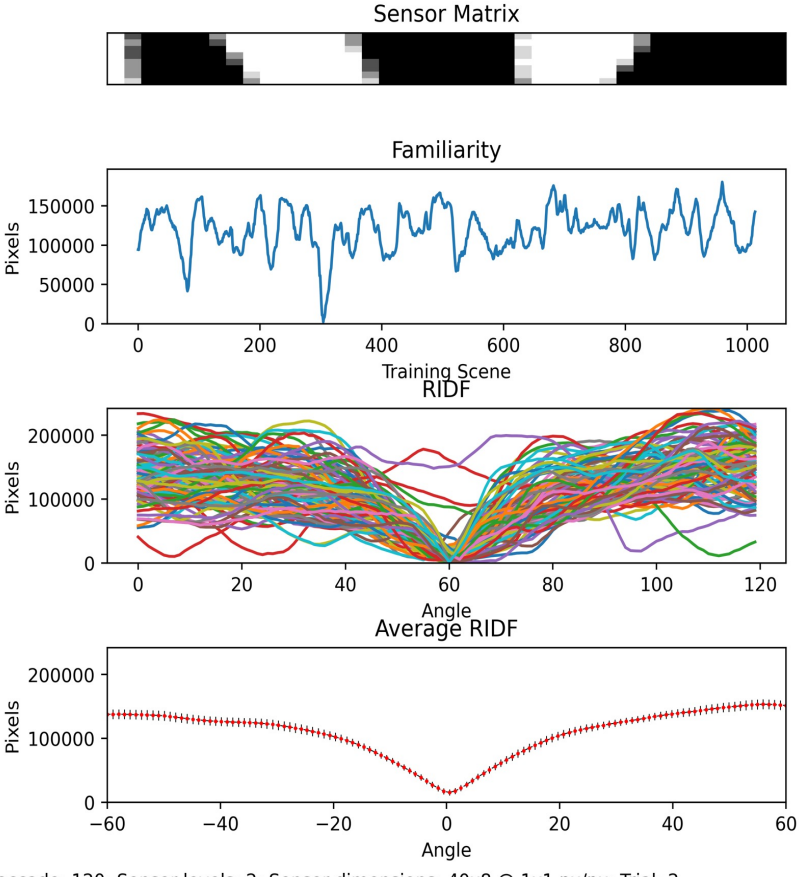


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 29.28; RMSD/dist: 0.073; TD: 97078; p90: 30; p50: 16; complete: 0

90%

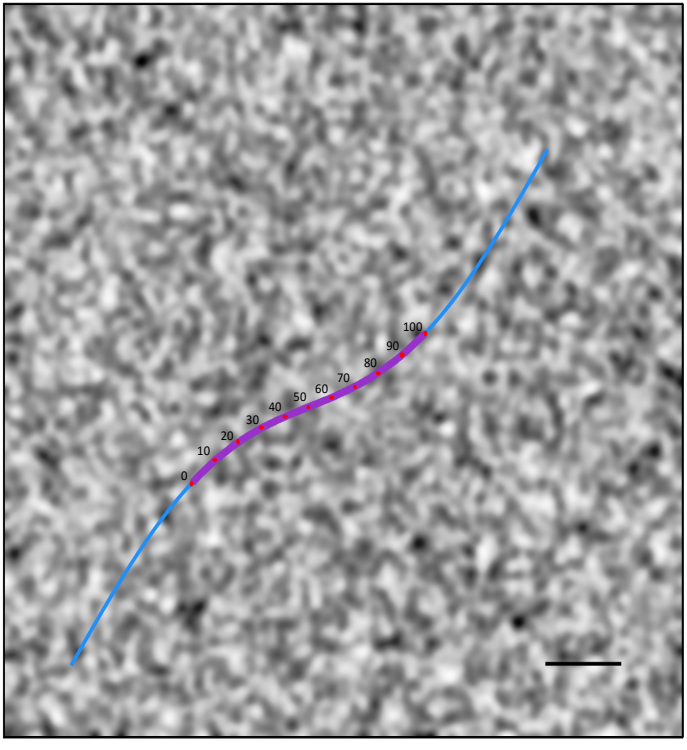


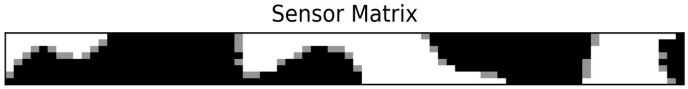


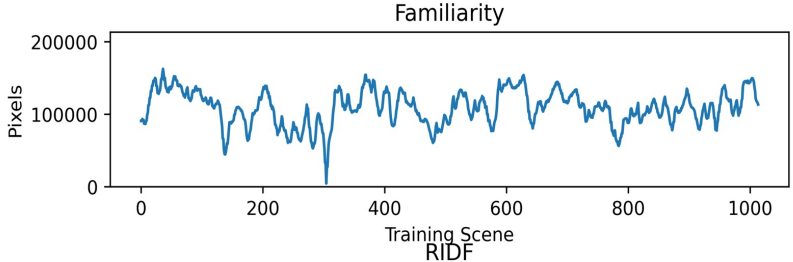
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

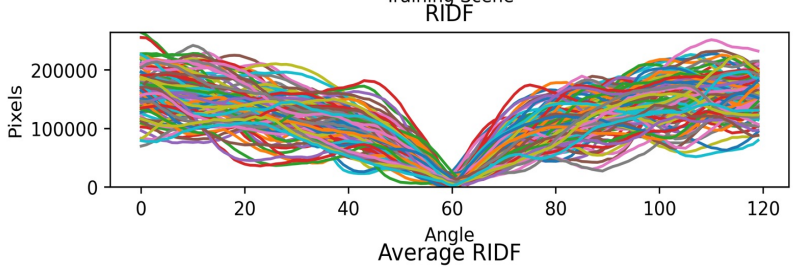
Navigation stats: RMSD error: 85.96; RMSD/dist: 0.215; TD: 84097; p90: 32; p50: 18; complete: 0

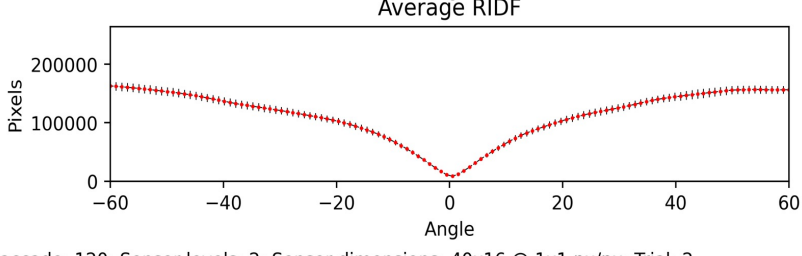
100%







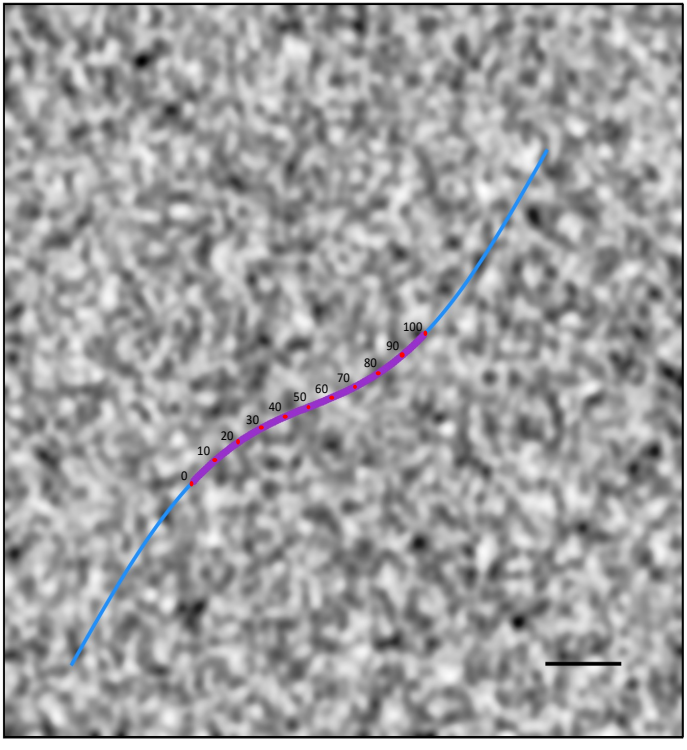


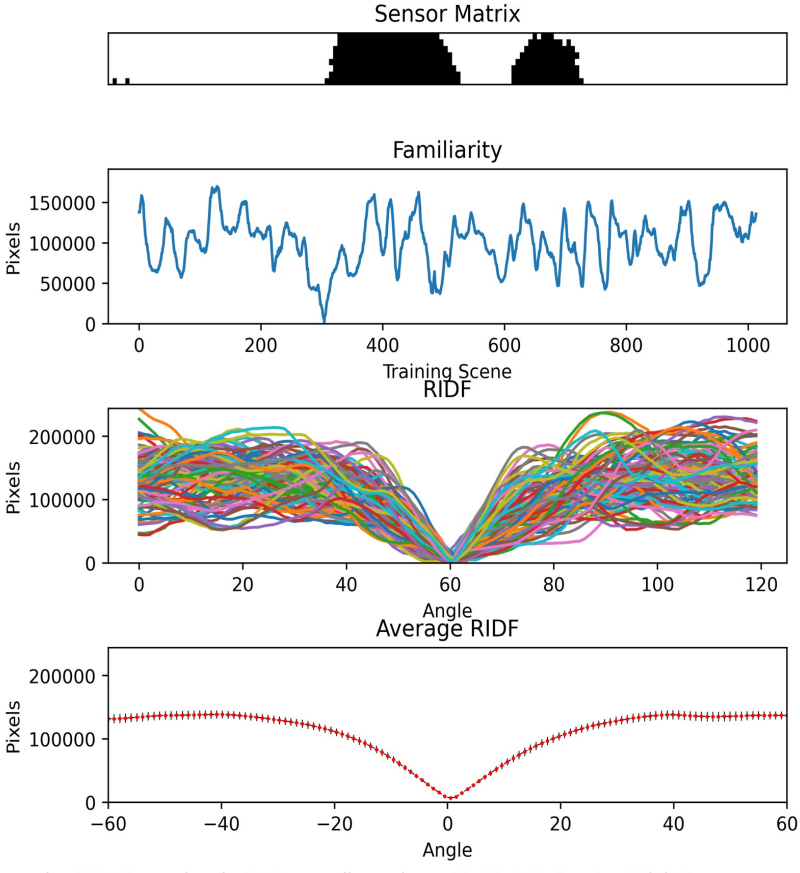


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 58.09; RMSD/dist: 0.145; TD: 94539; p90: 34; p50: 16; complete: 0

100%





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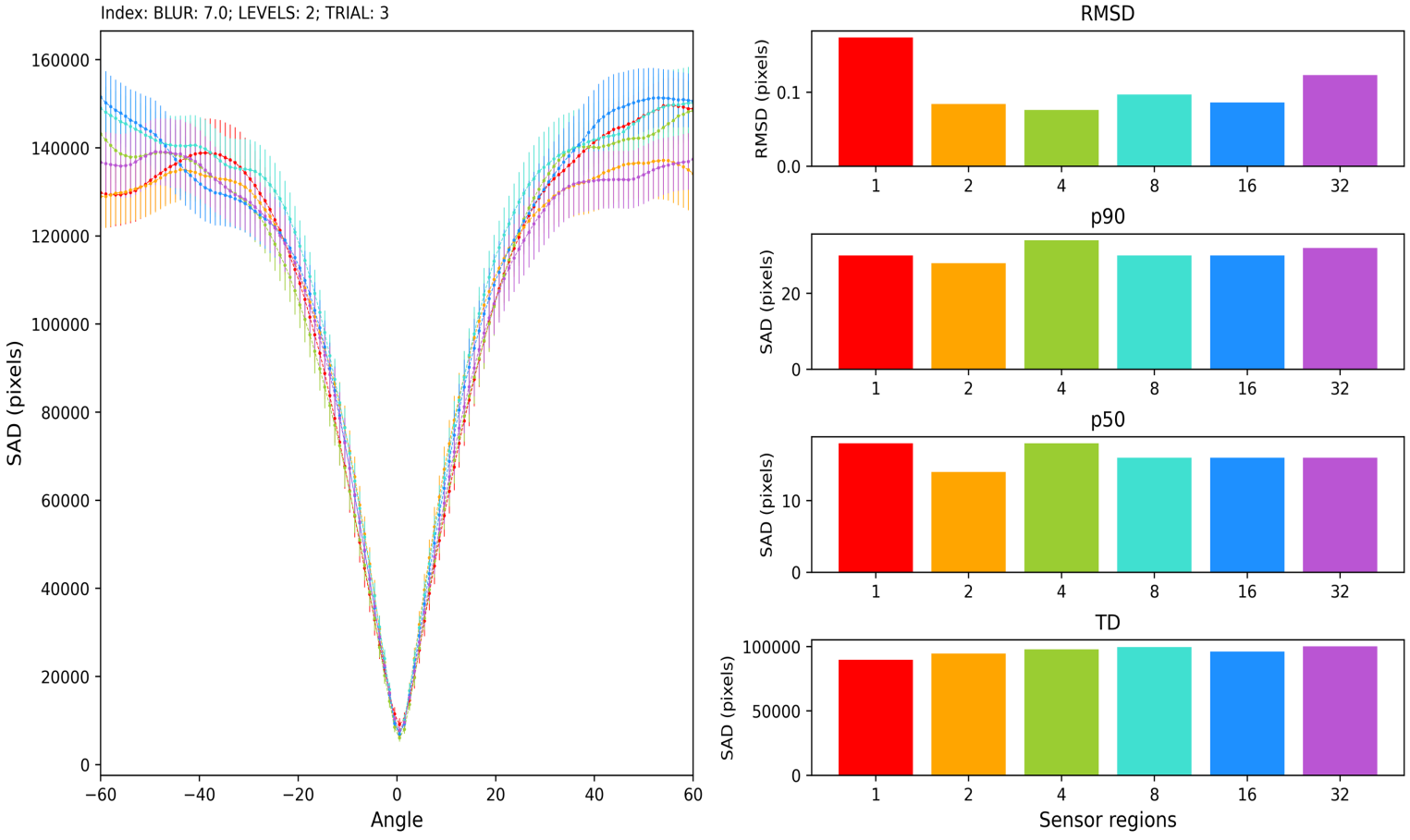
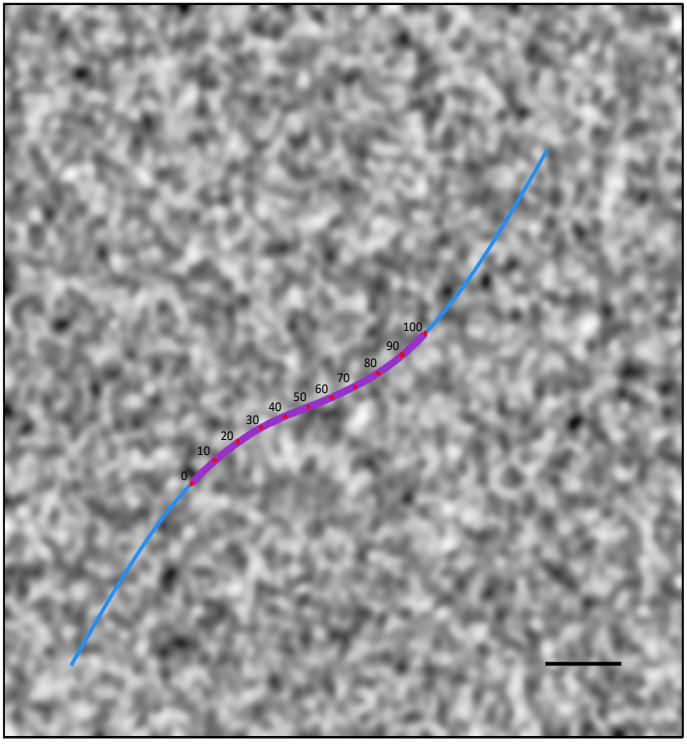
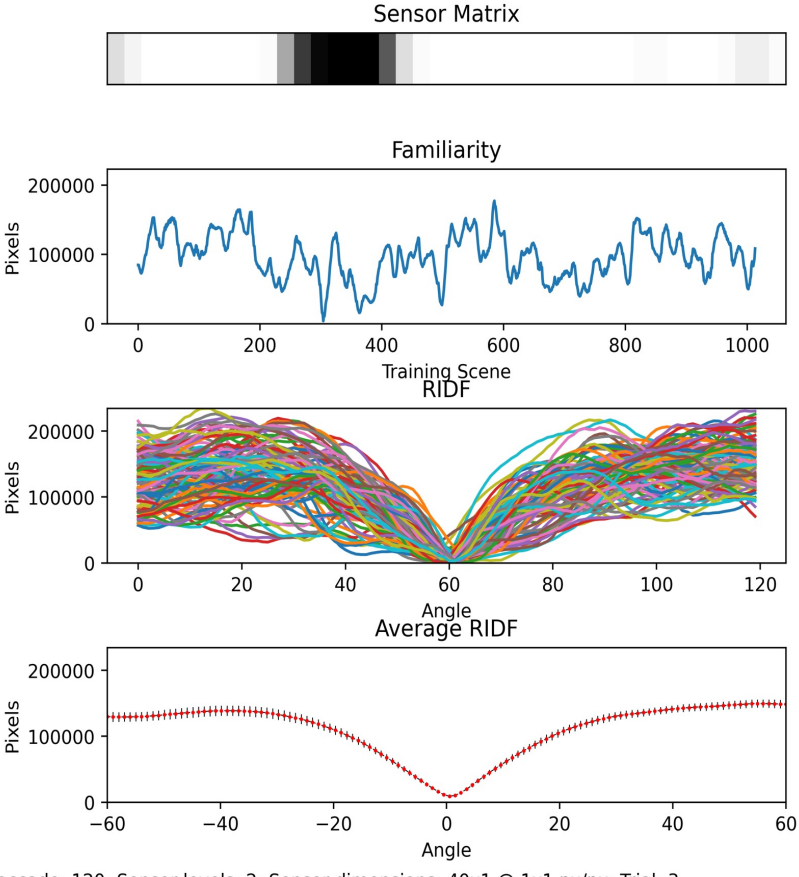
Navigation stats: RMSD error: 37.19; RMSD/dist: 0.093; TD: 90347; p90: 28; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

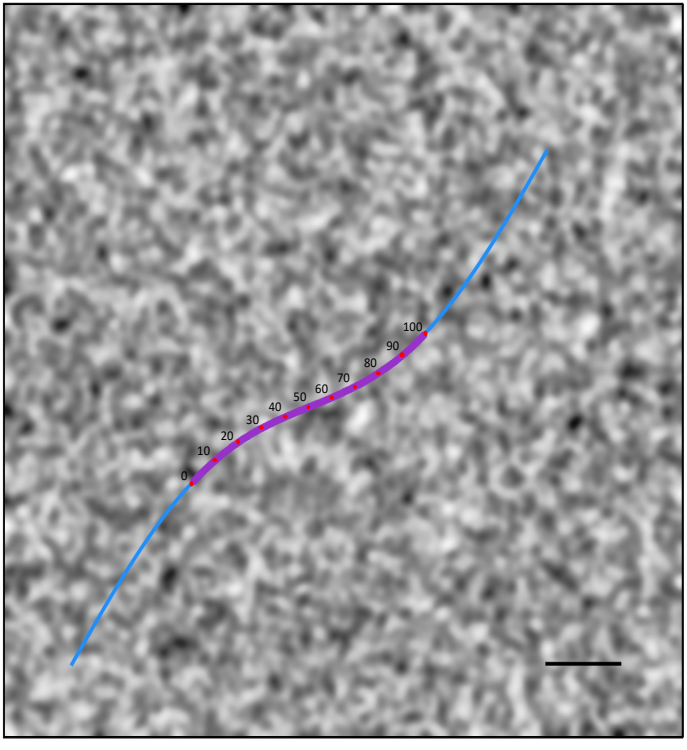


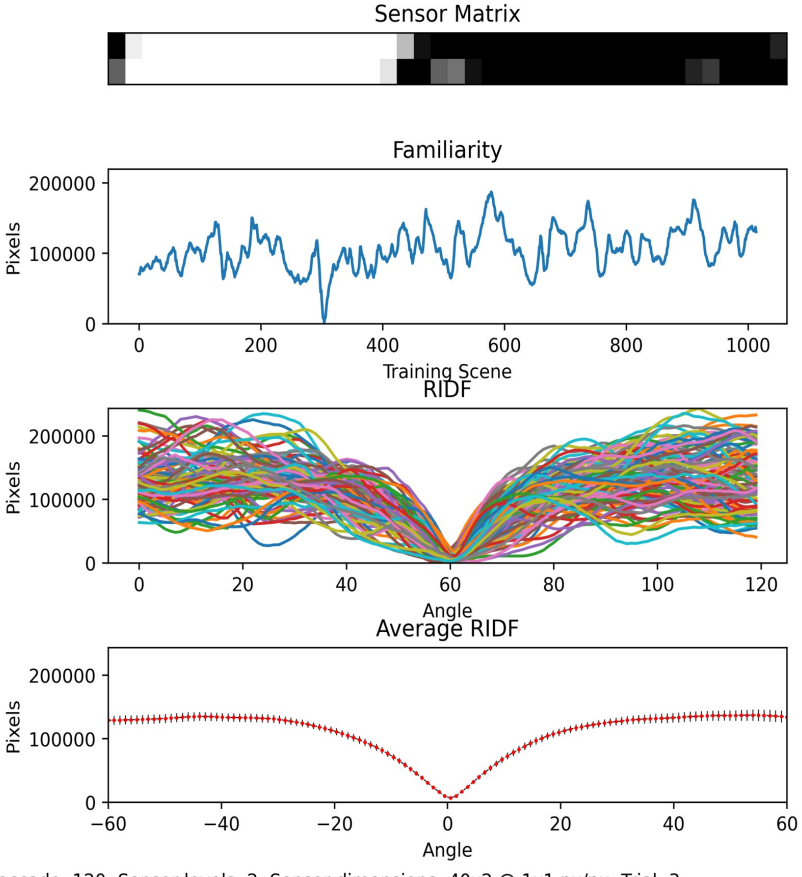


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 69.52; RMSD/dist: 0.174; TD: 89706; p90: 30; p50: 18; complete: 0

100%

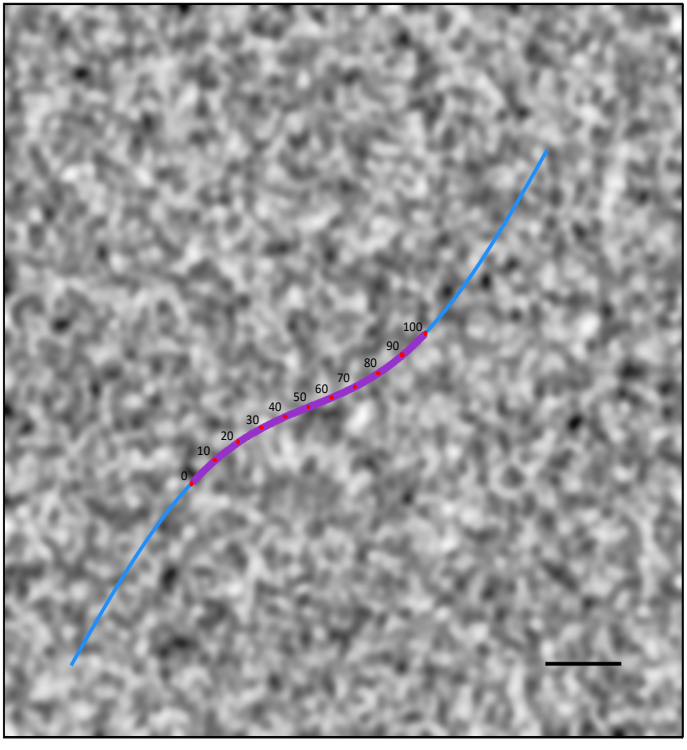


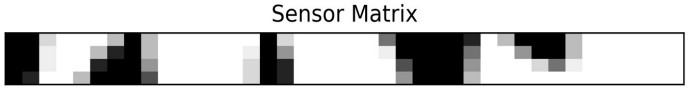


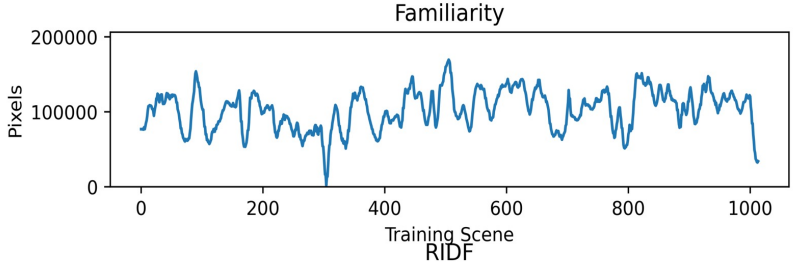
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

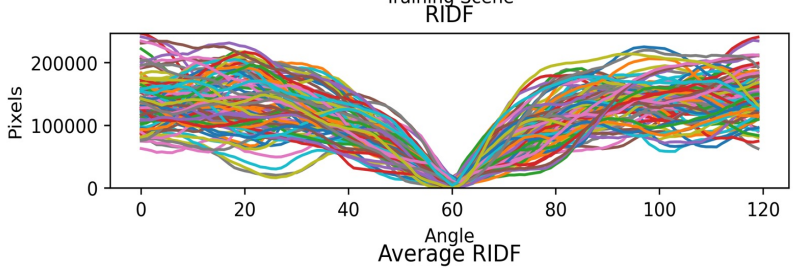
Navigation stats: RMSD error: 33.57; RMSD/dist: 0.084; TD: 94538; p90: 28; p50: 14; complete: 0

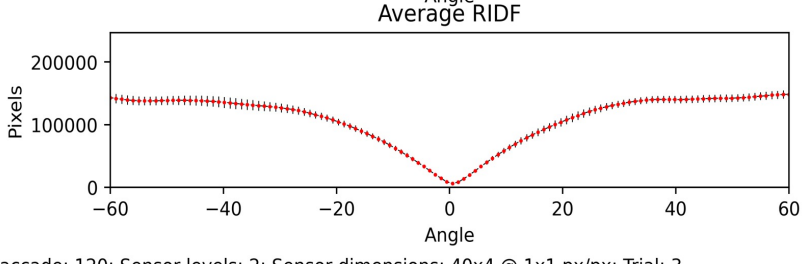
100%







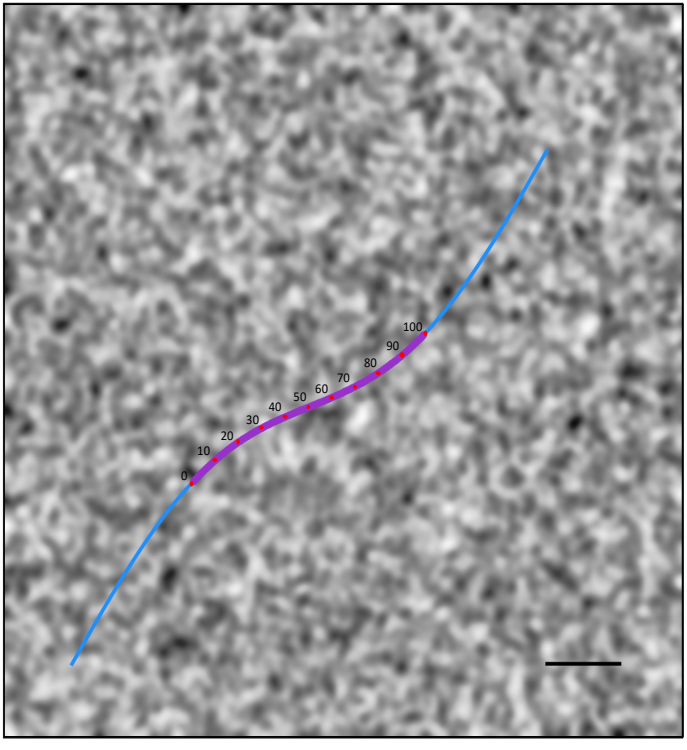


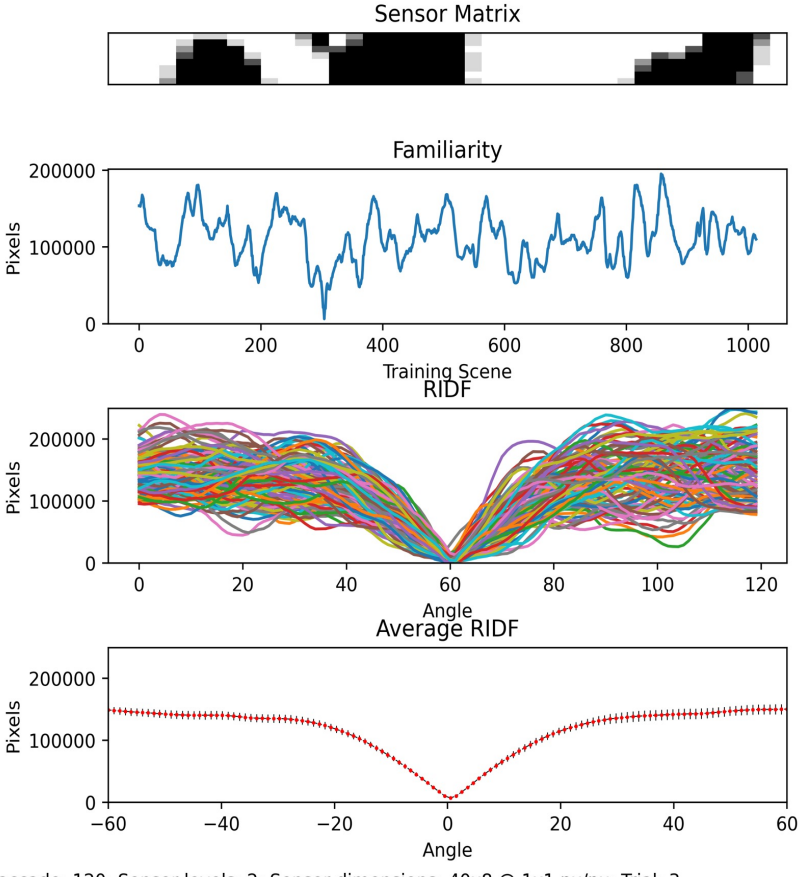


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 30.47; RMSD/dist: 0.076; TD: 97914; p90: 34; p50: 18; complete: 0

100%

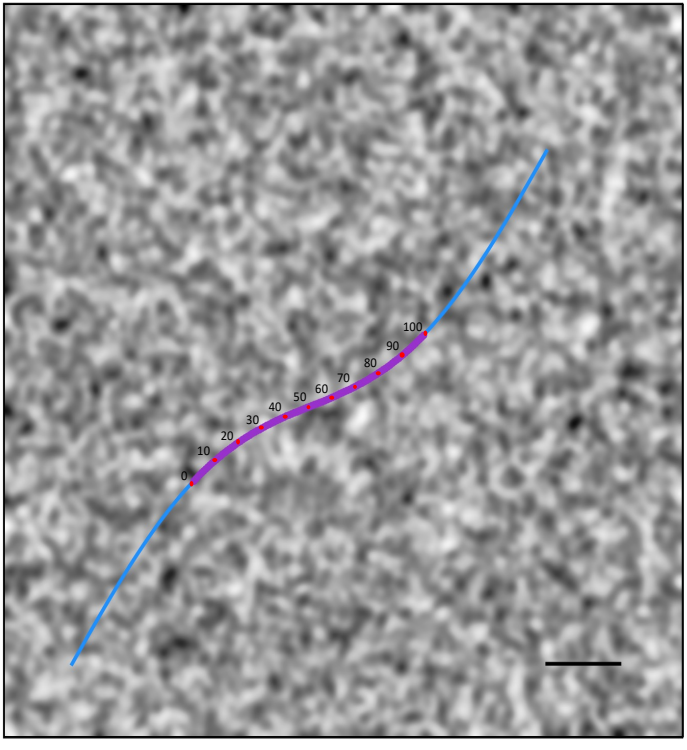


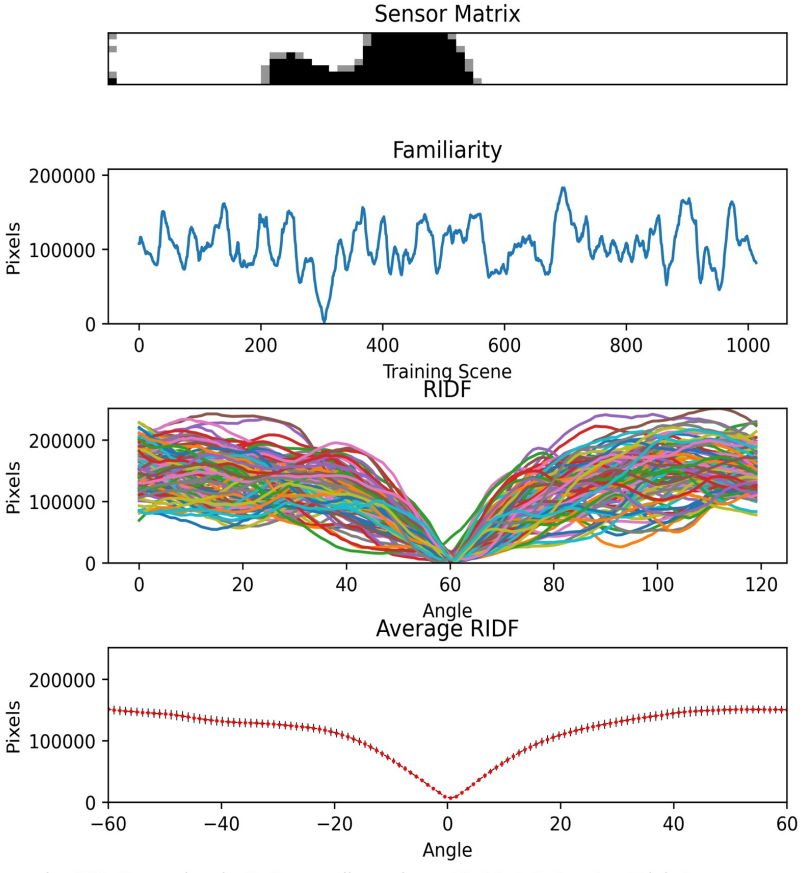


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 38.80; RMSD/dist: 0.097; TD: 99587; p90: 30; p50: 16; complete: 0

100%

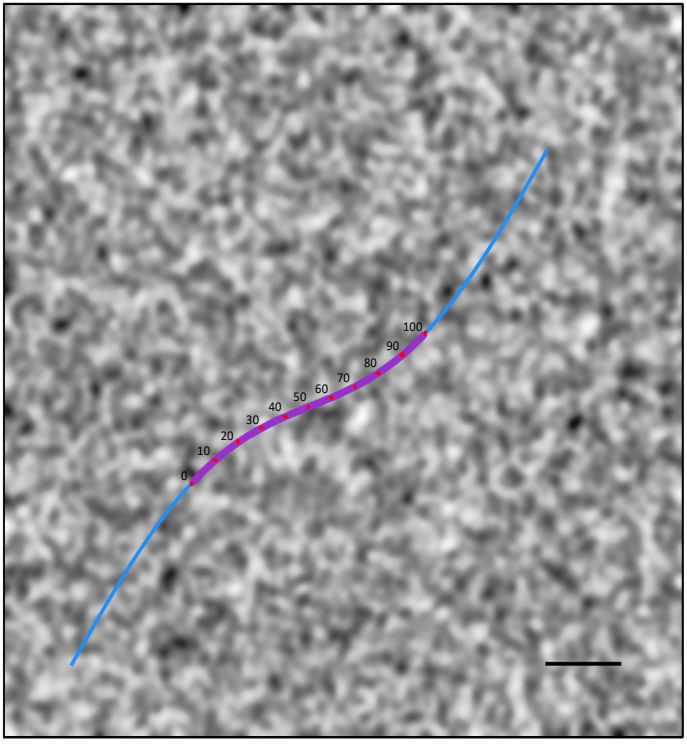


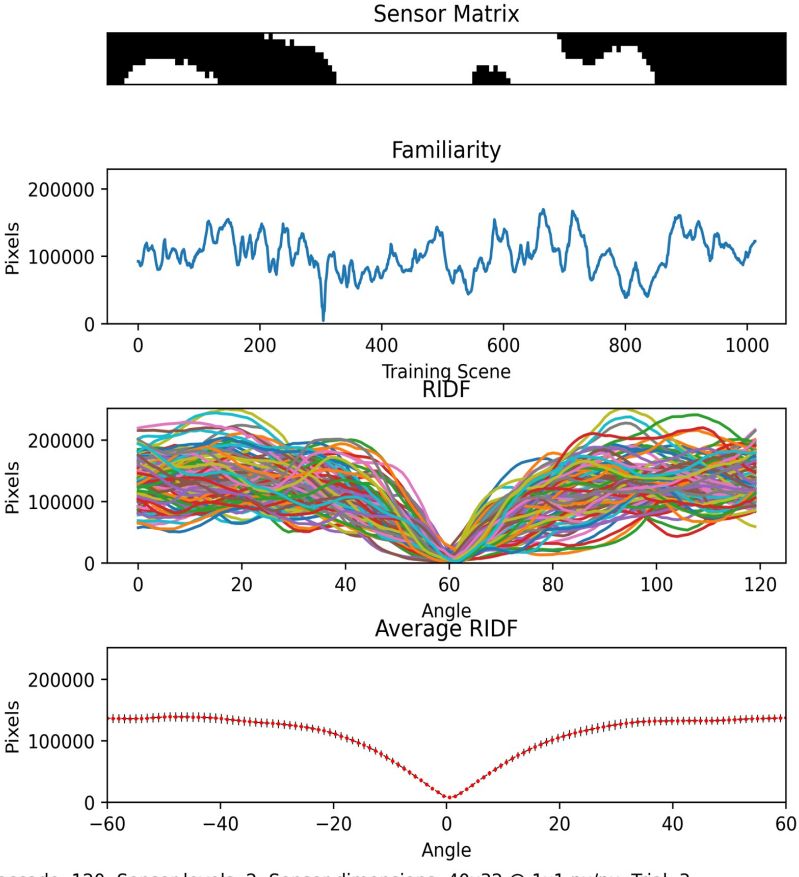


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 34.48; RMSD/dist: 0.086; TD: 96161; p90: 30; p50: 16; complete: 0

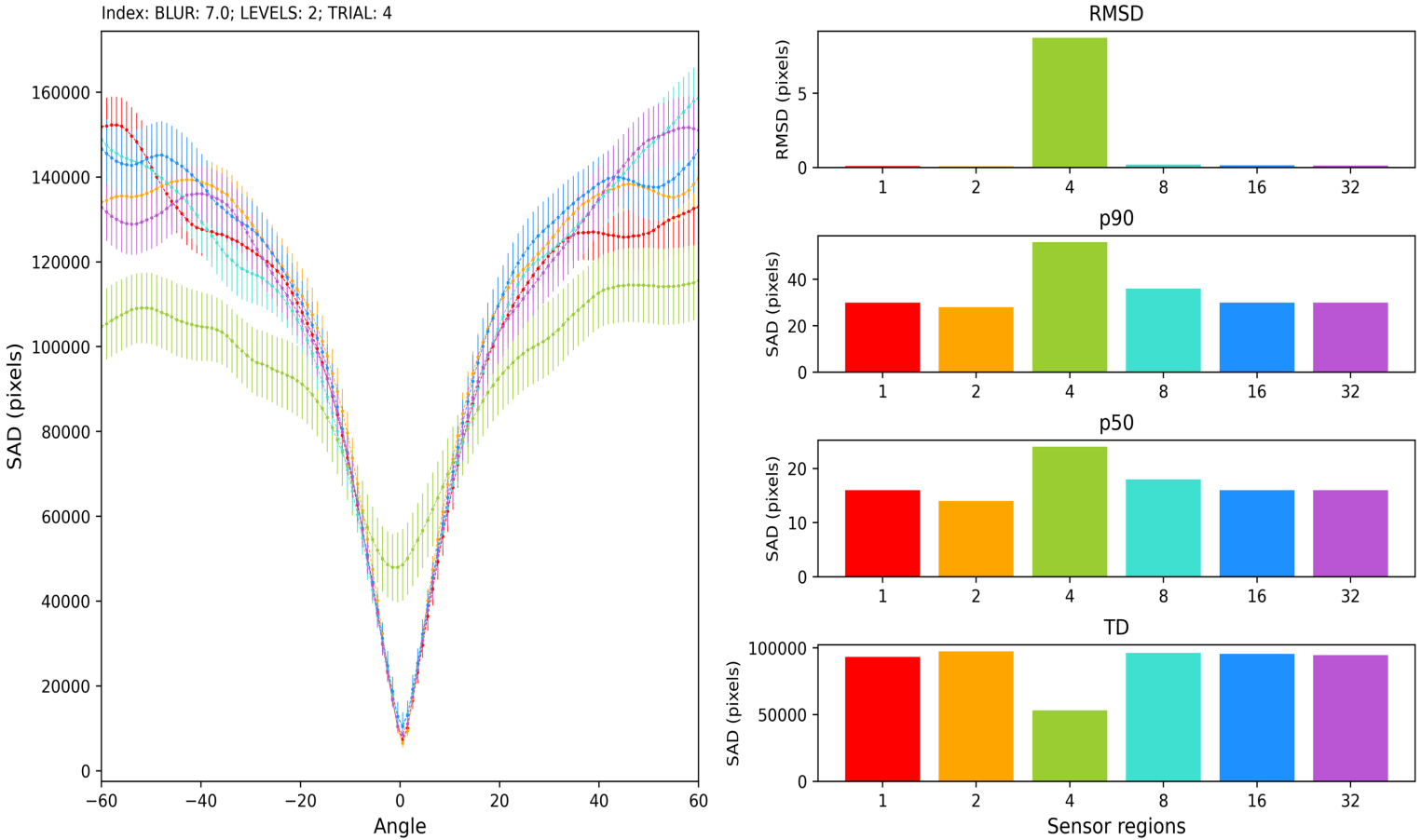
100%



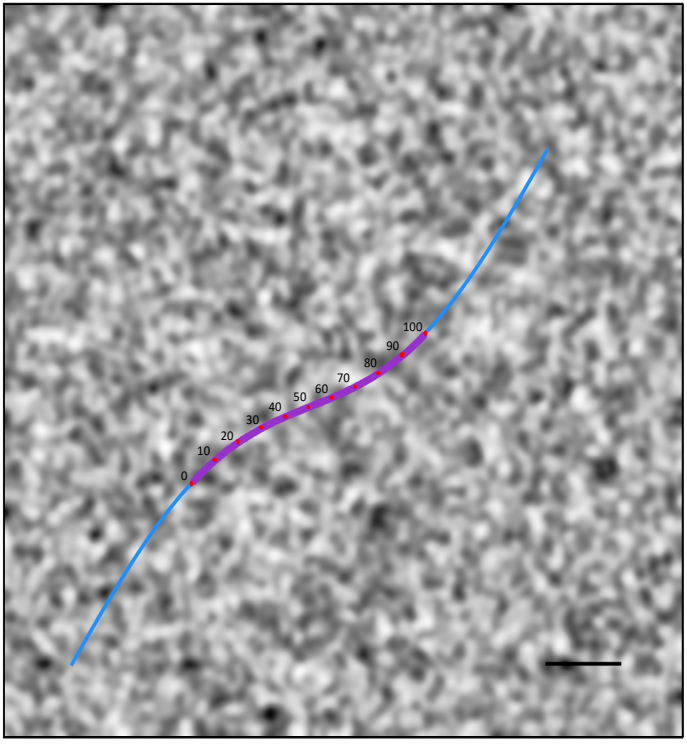


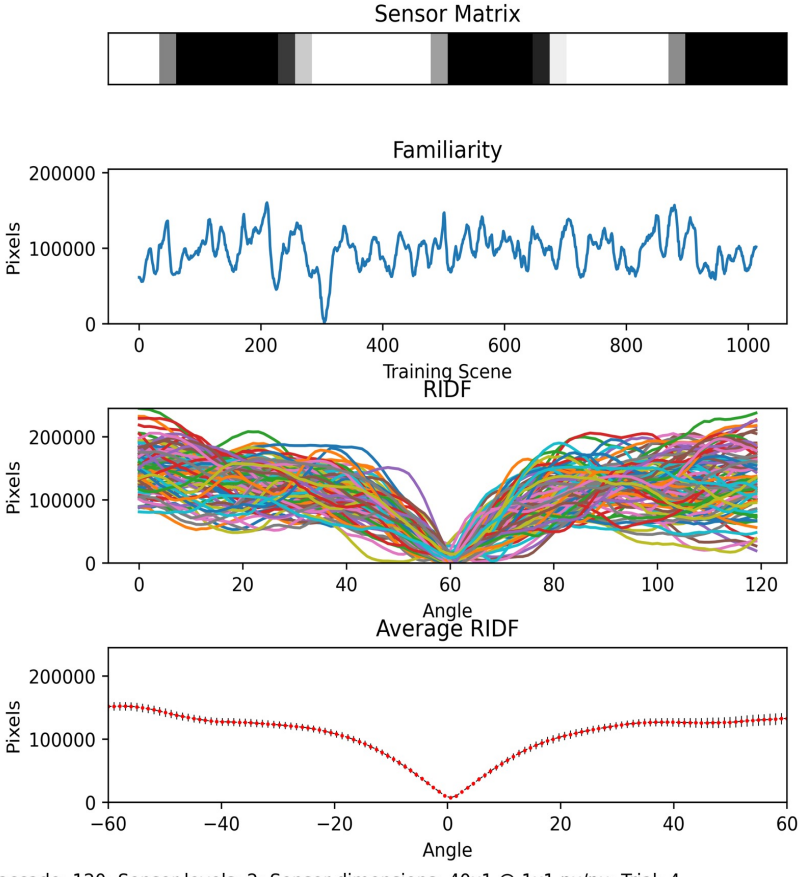
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 49.39; RMSD/dist: 0.123; TD: 100185; p90: 32; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

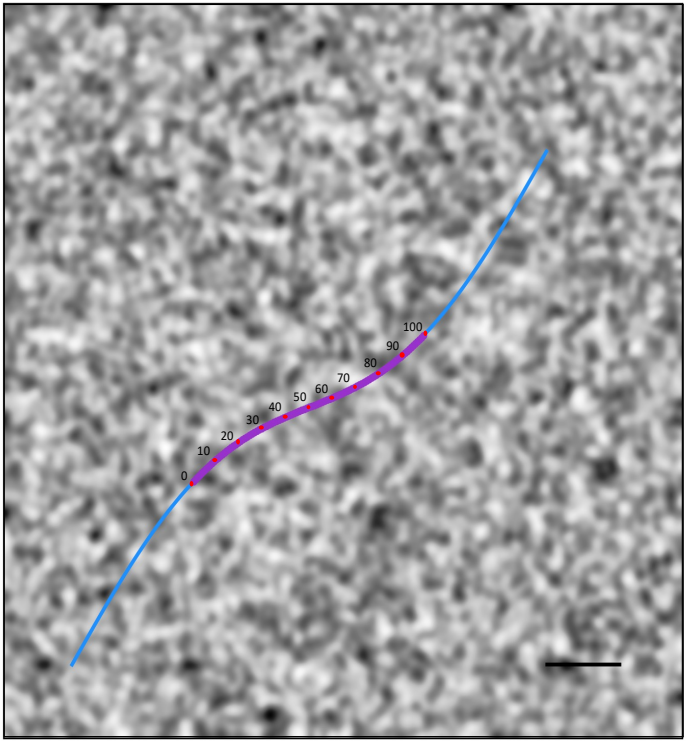


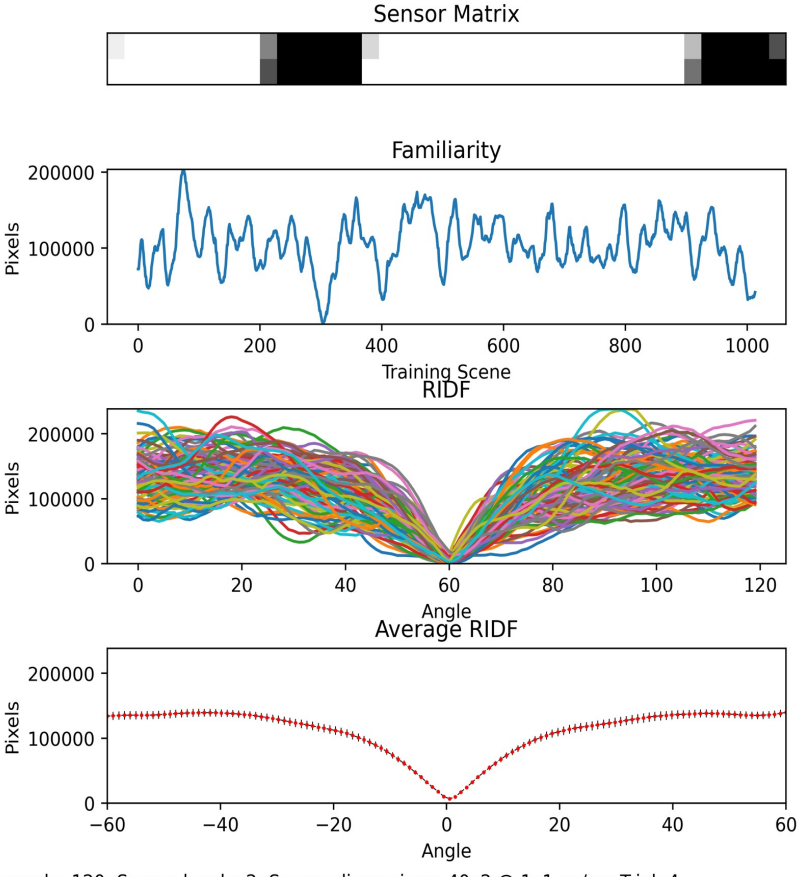


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 37.55; RMSD/dist: 0.094; TD: 93255; p90: 30; p50: 16; complete: 0

100%

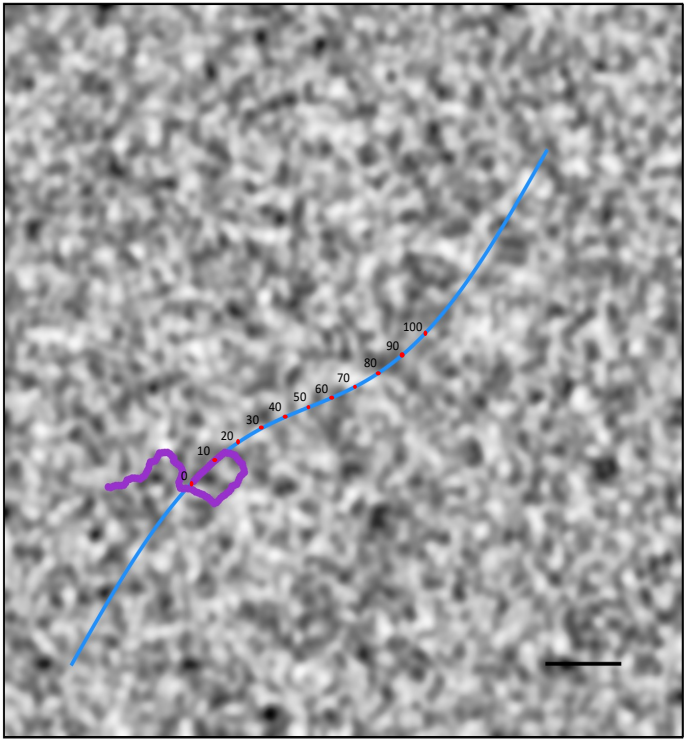


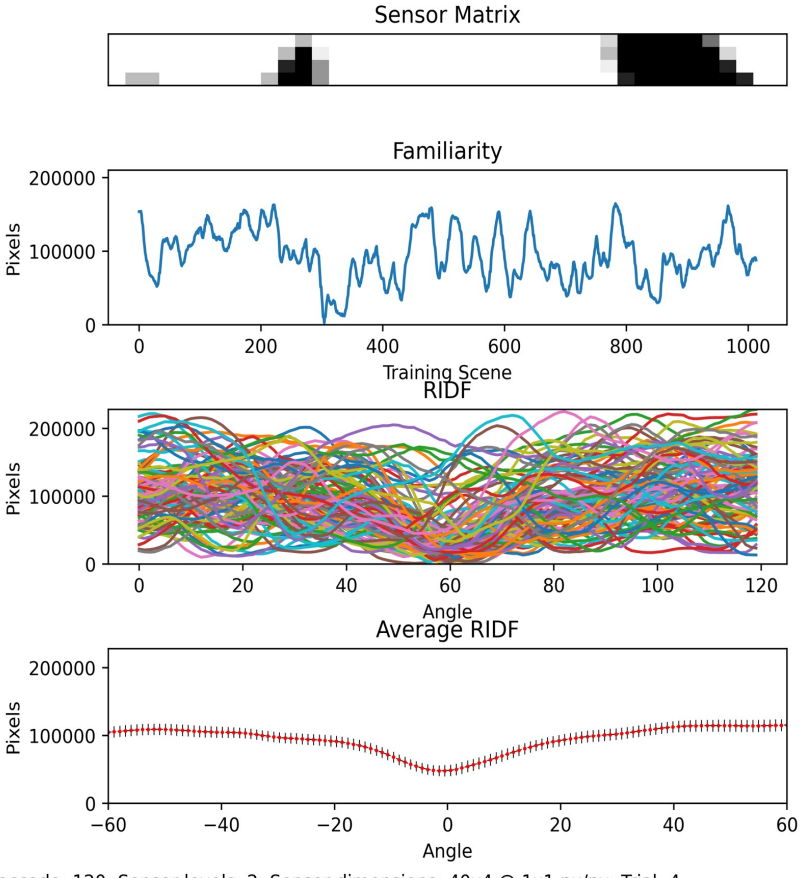


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 31.81; RMSD/dist: 0.080; TD: 97319; p90: 28; p50: 14; complete: 0

10%

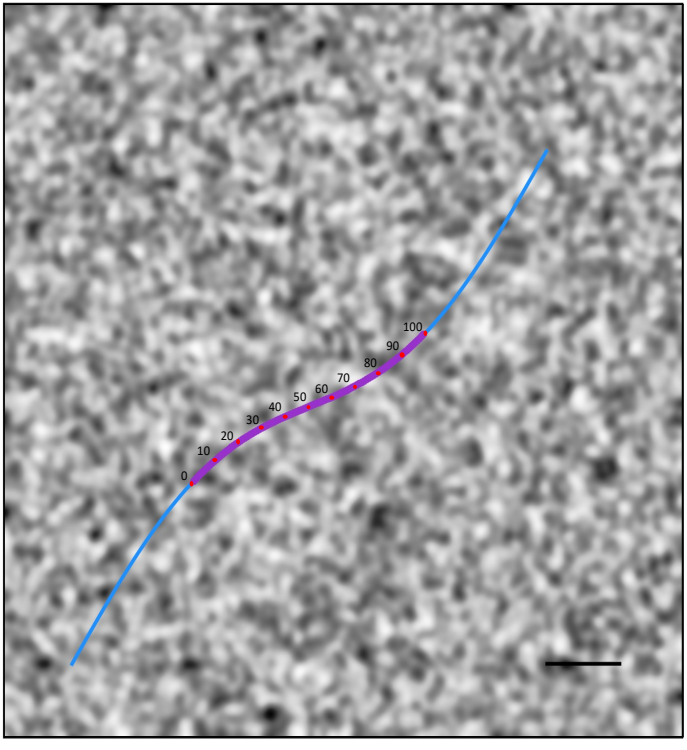


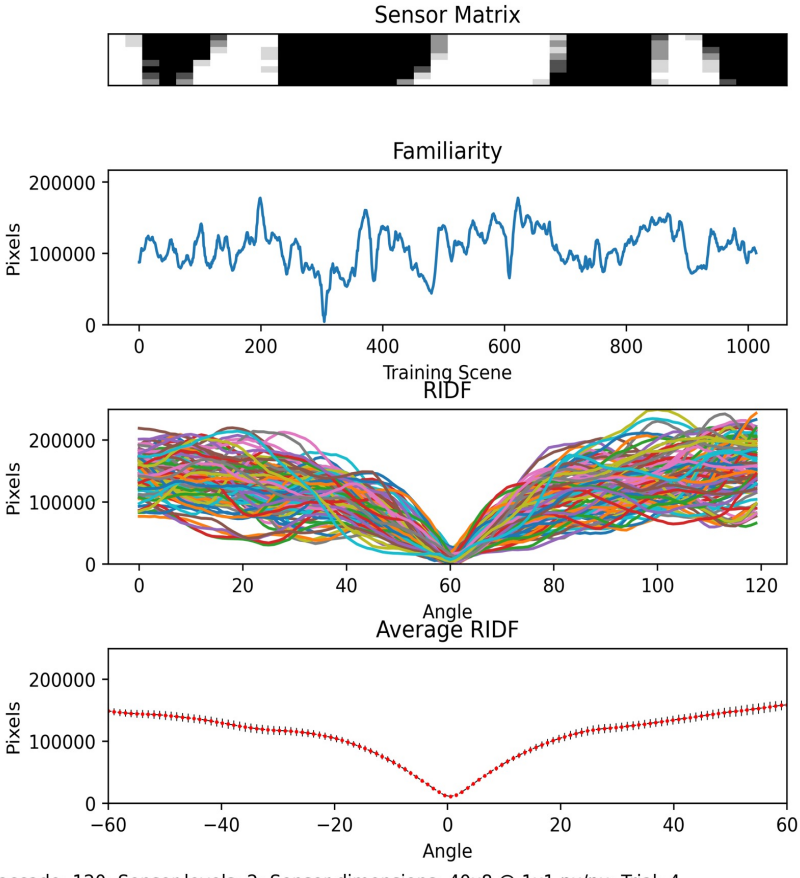


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3498.82; RMSD/dist: 8.747; TD: 53216; p90: 56; p50: 24; complete: 0

100%

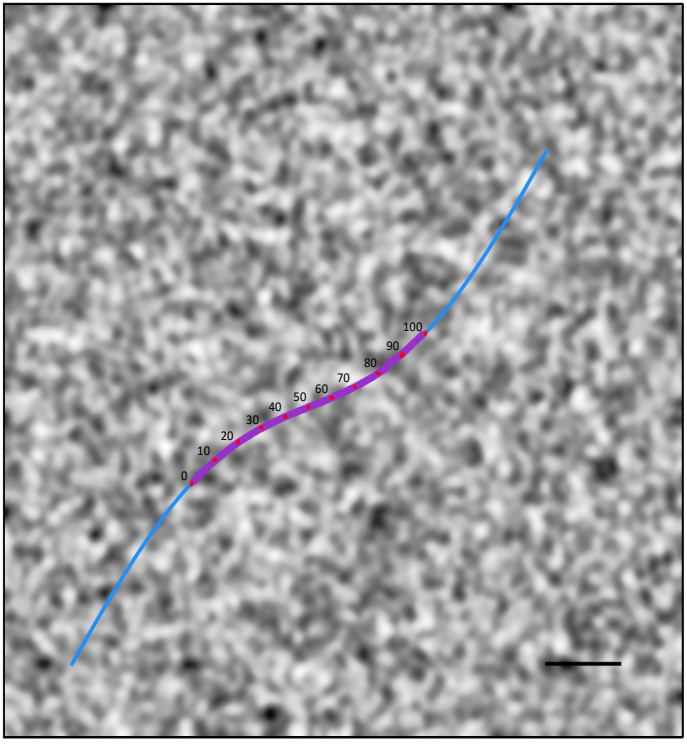


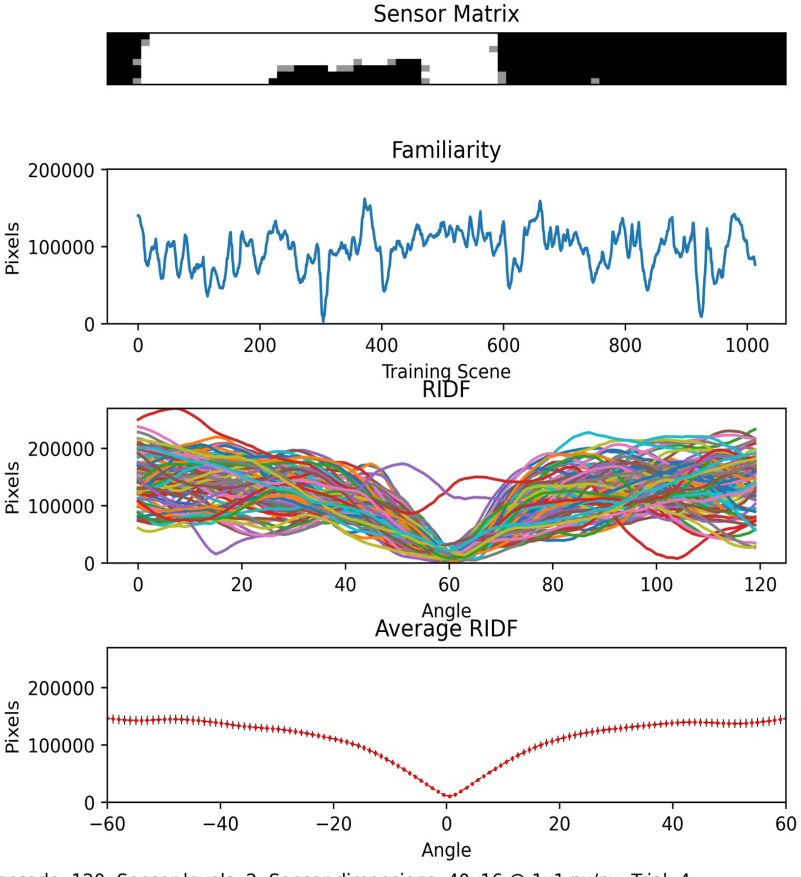


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 78.51; RMSD/dist: 0.196; TD: 96180; p90: 36; p50: 18; complete: 0

100%

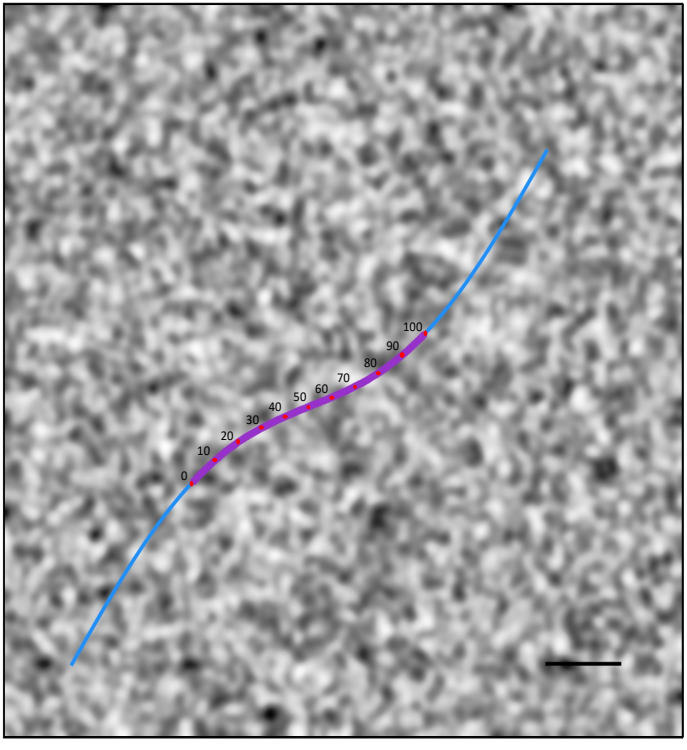


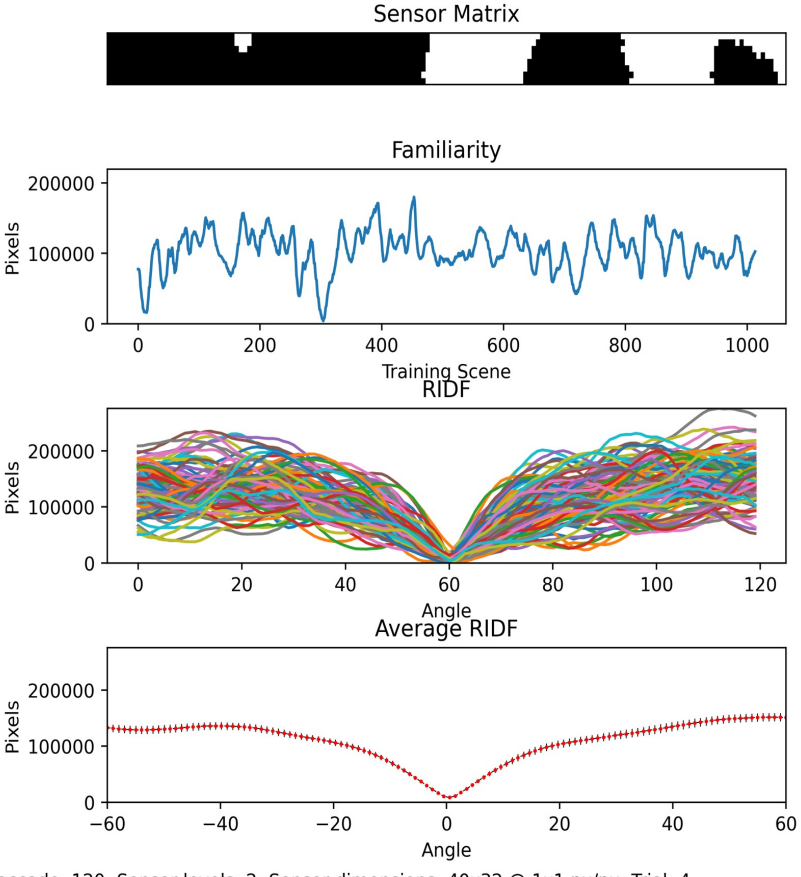


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 59.52; RMSD/dist: 0.149; TD: 95448; p90: 30; p50: 16; complete: 0

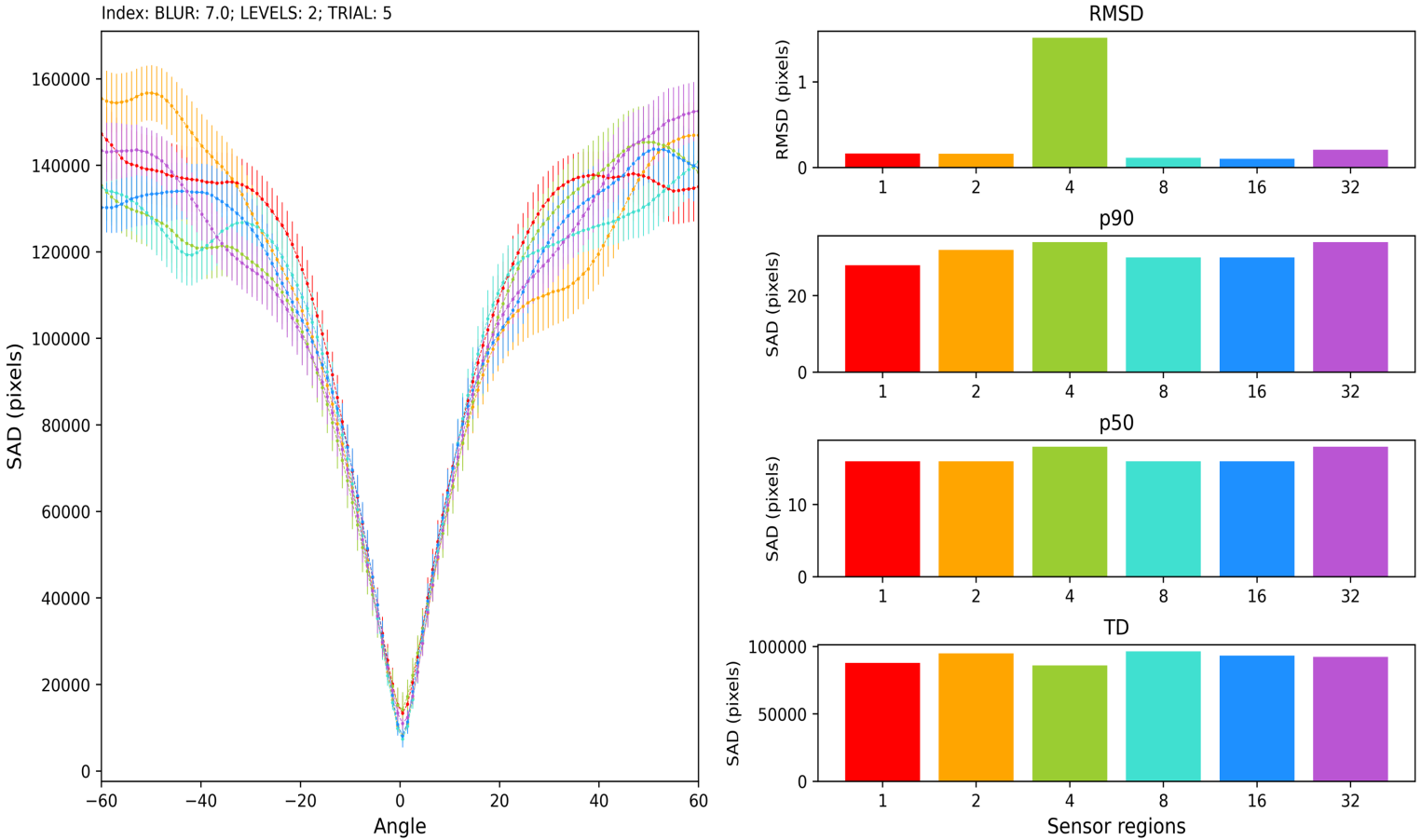
100%



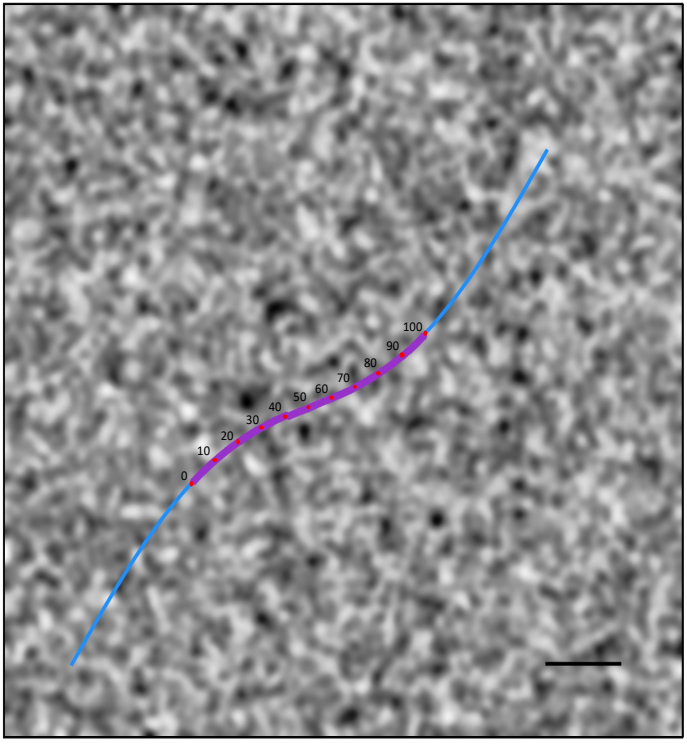


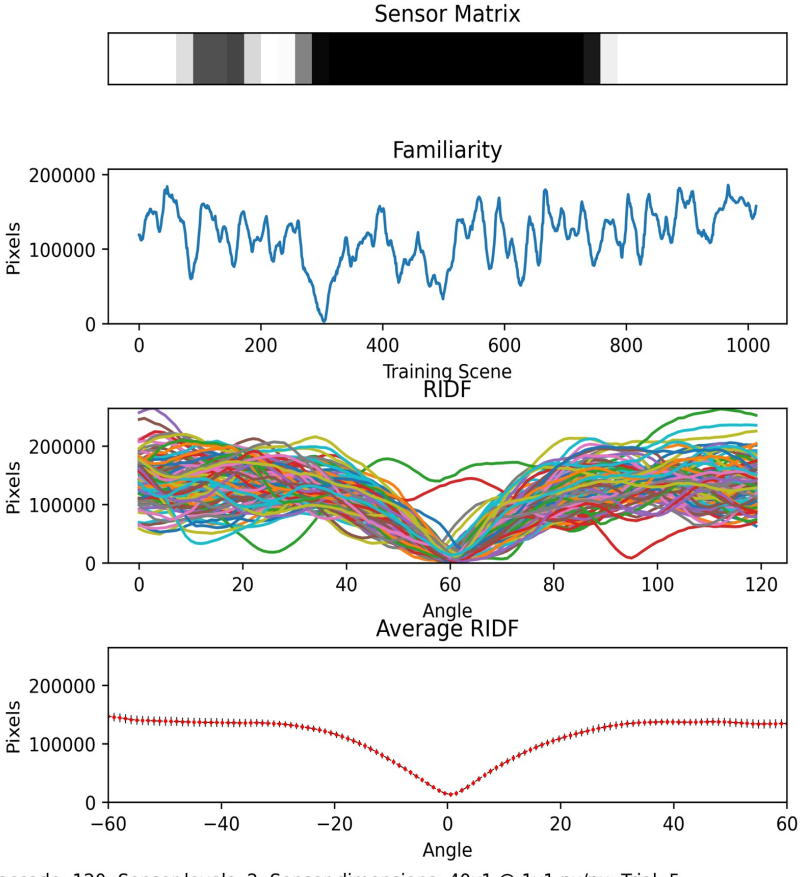
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 55.71; RMSD/dist: 0.139; TD: 94630; p90: 30; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

90%

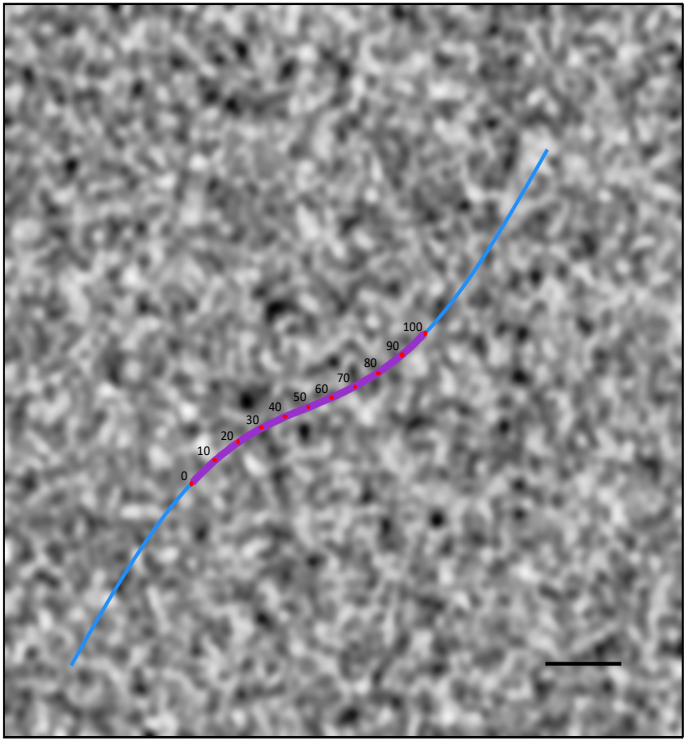


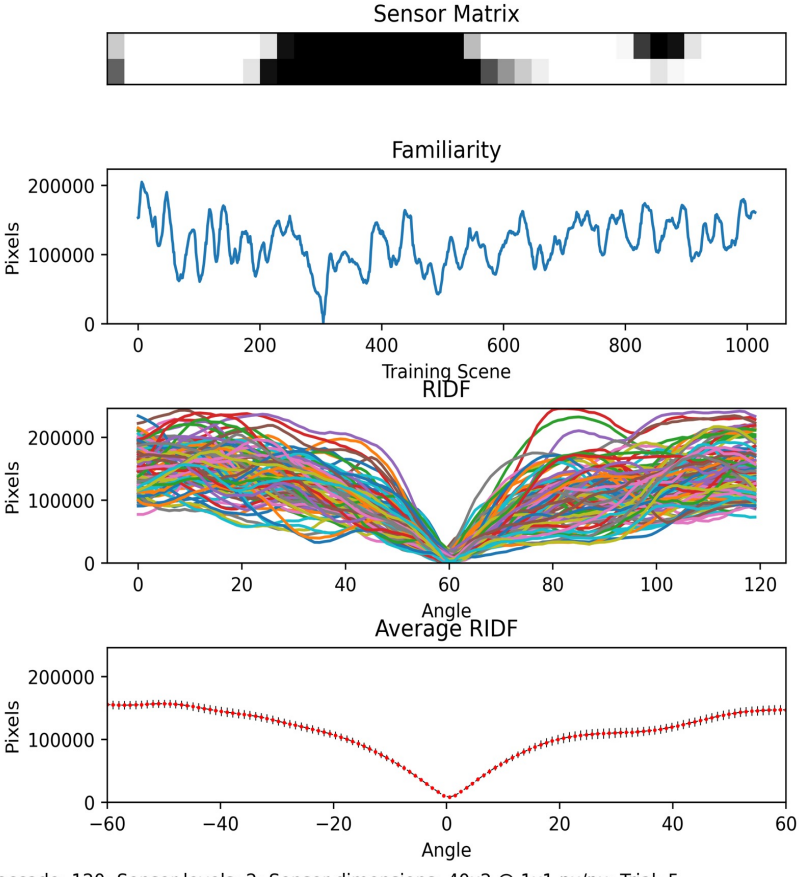


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 66.16; RMSD/dist: 0.165; TD: 87885; p90: 28; p50: 16; complete: 0

100%

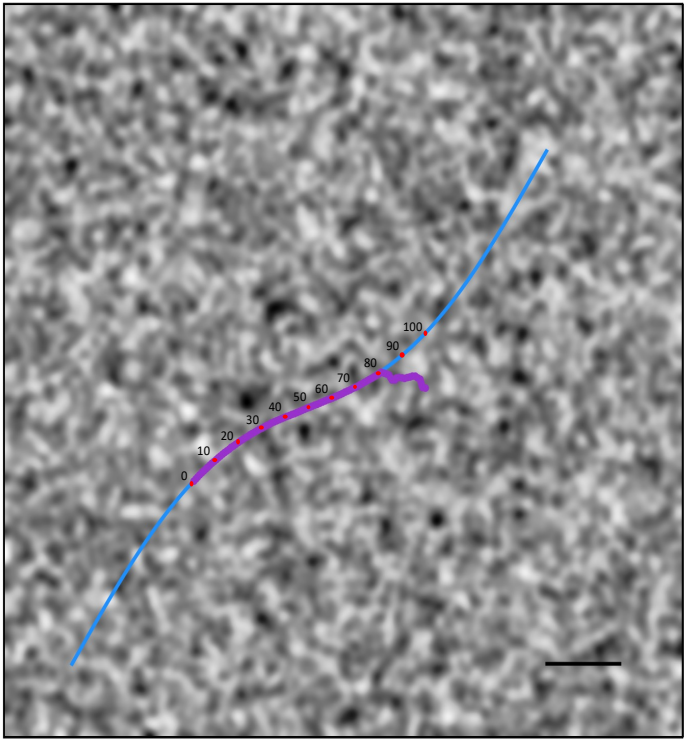


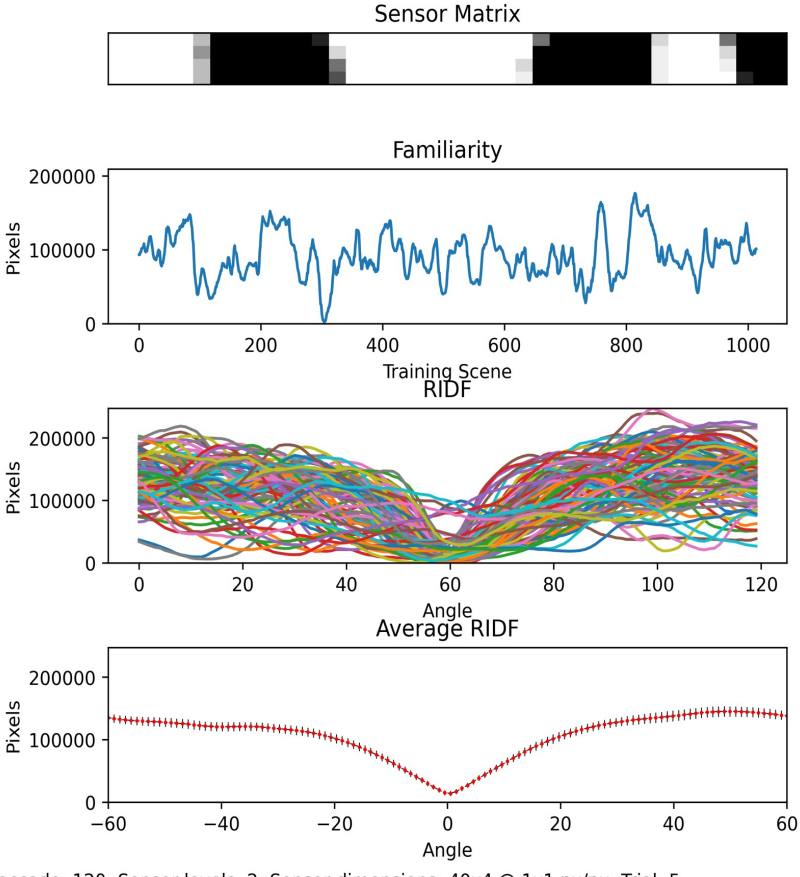


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 64.30; RMSD/dist: 0.161; TD: 94918; p90: 32; p50: 16; complete: 0

80%

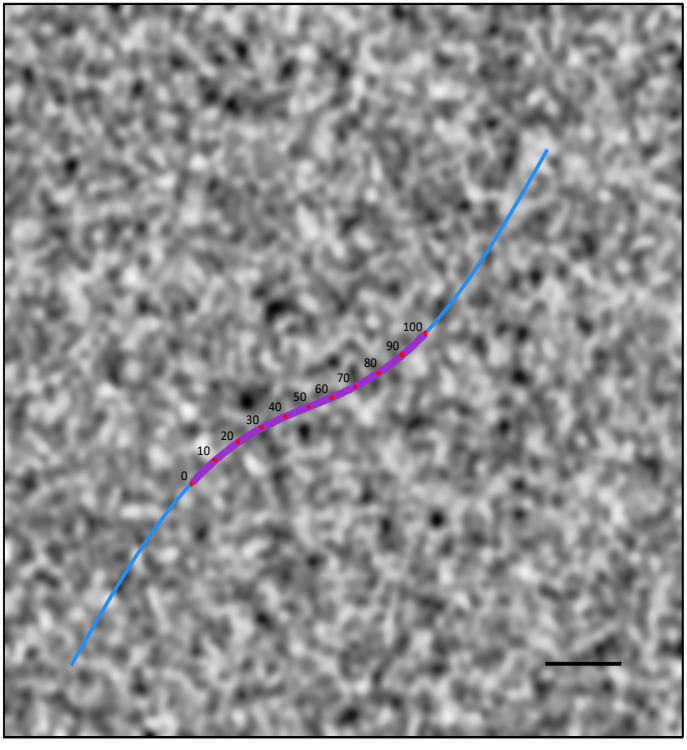


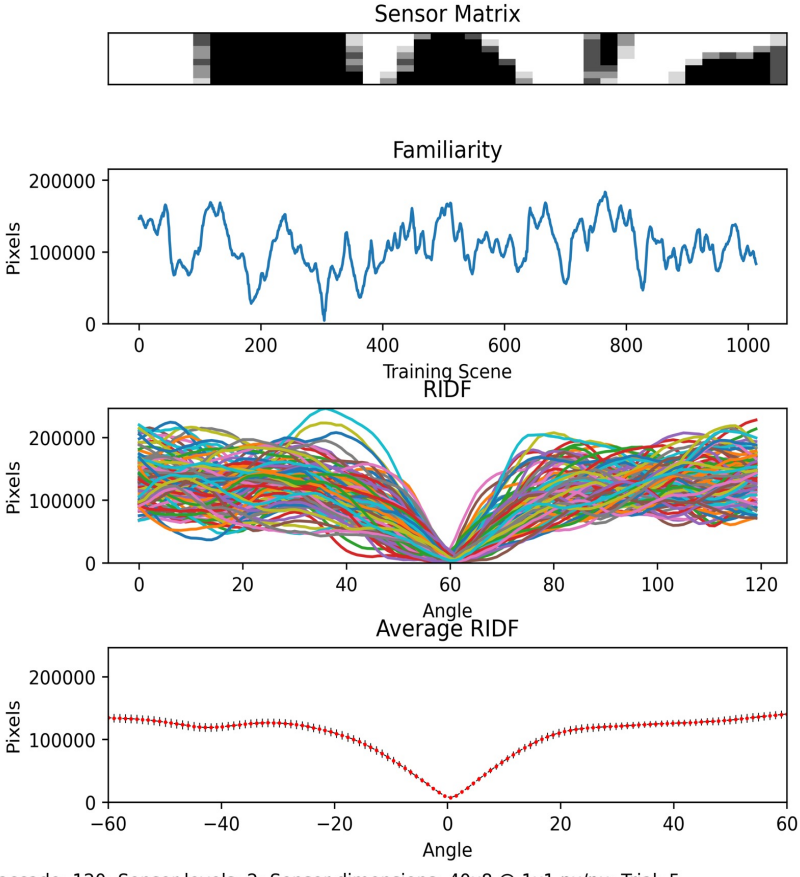


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 606.50; RMSD/dist: 1.516; TD: 85943; p90: 34; p50: 18; complete: 0

100%

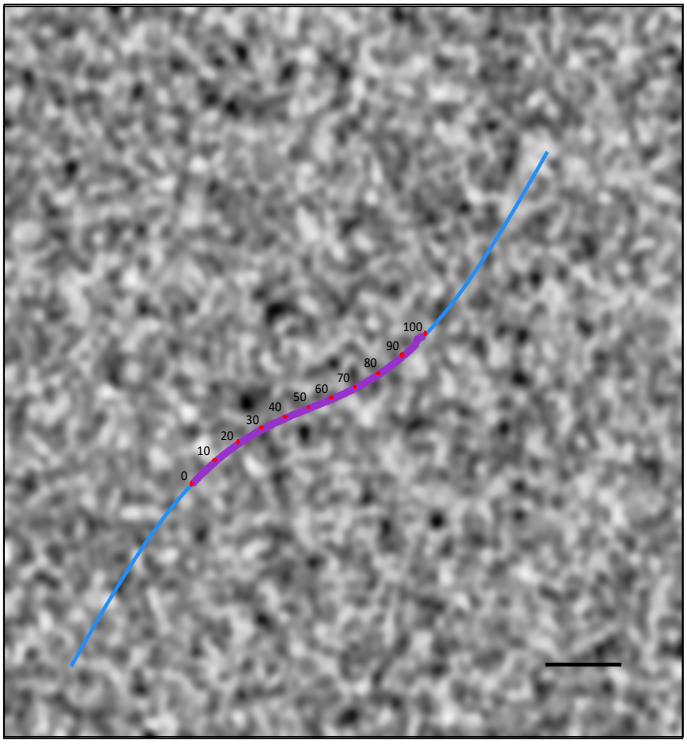


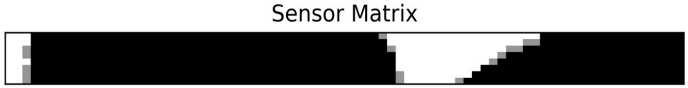


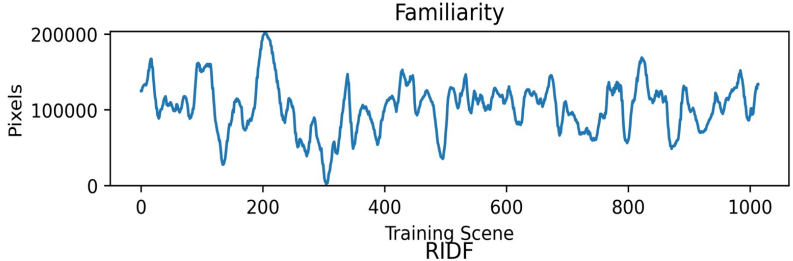
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

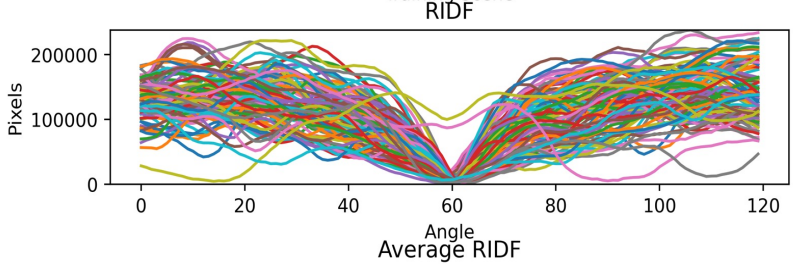
Navigation stats: RMSD error: 45.41; RMSD/dist: 0.114; TD: 96373; p90: 30; p50: 16; complete: 0

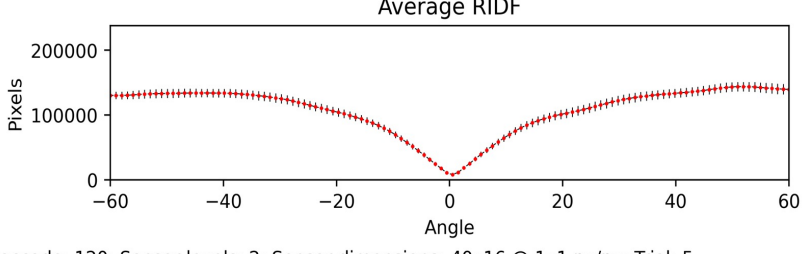
90%







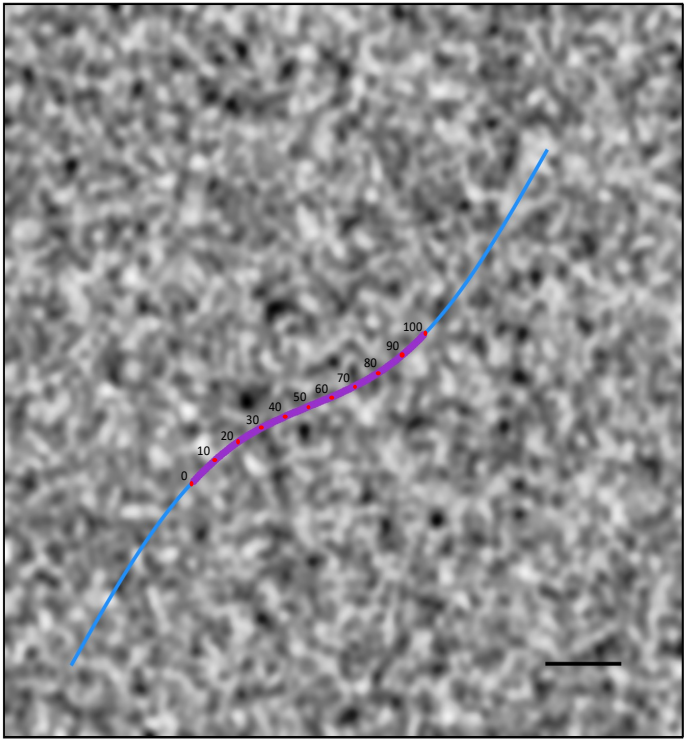


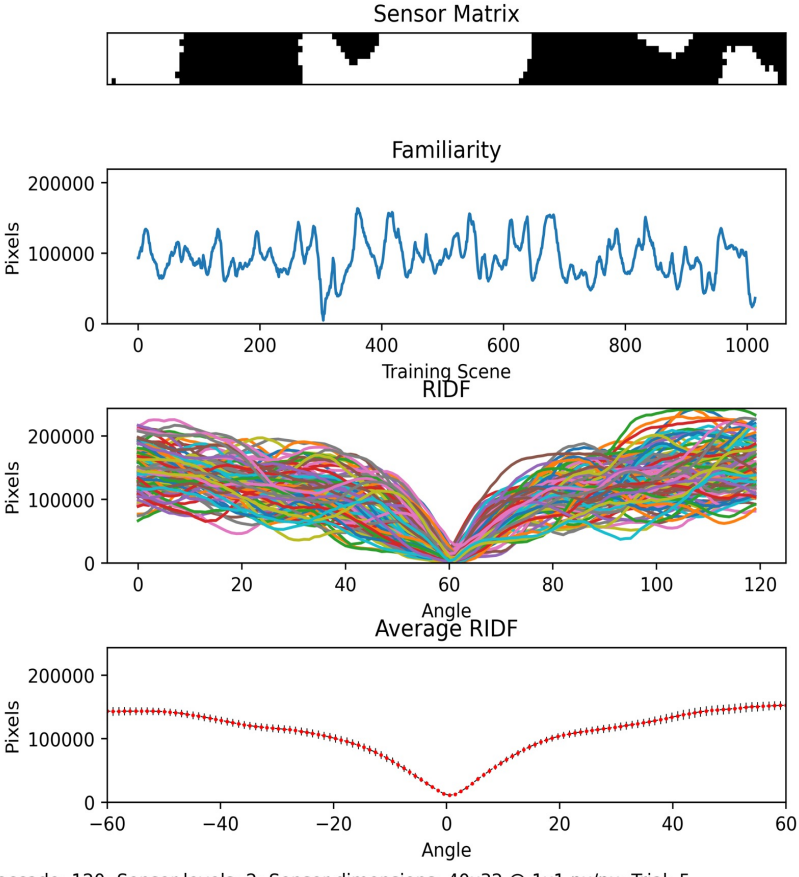


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 41.20; RMSD/dist: 0.103; TD: 93234; p90: 30; p50: 16; complete: 0

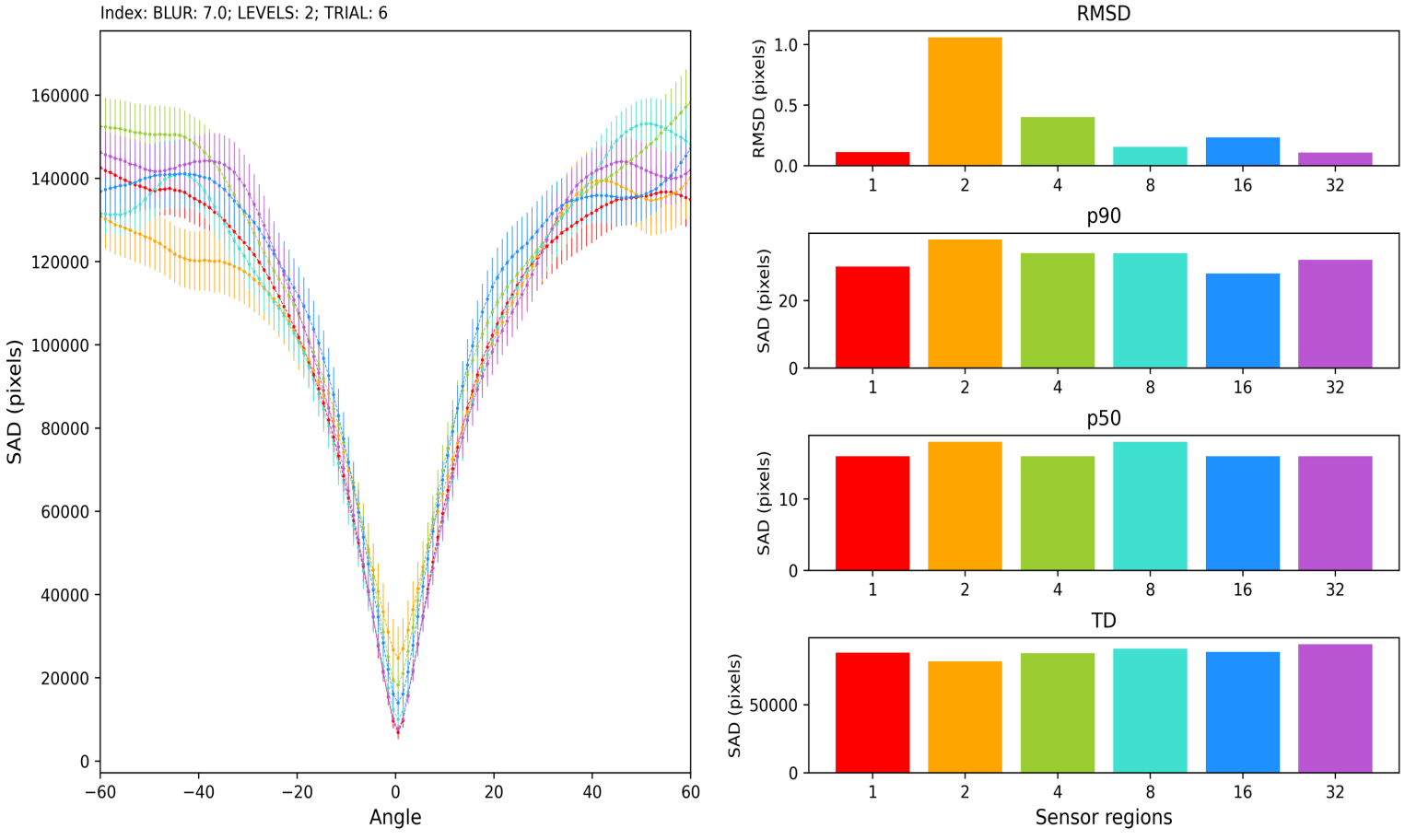
100%



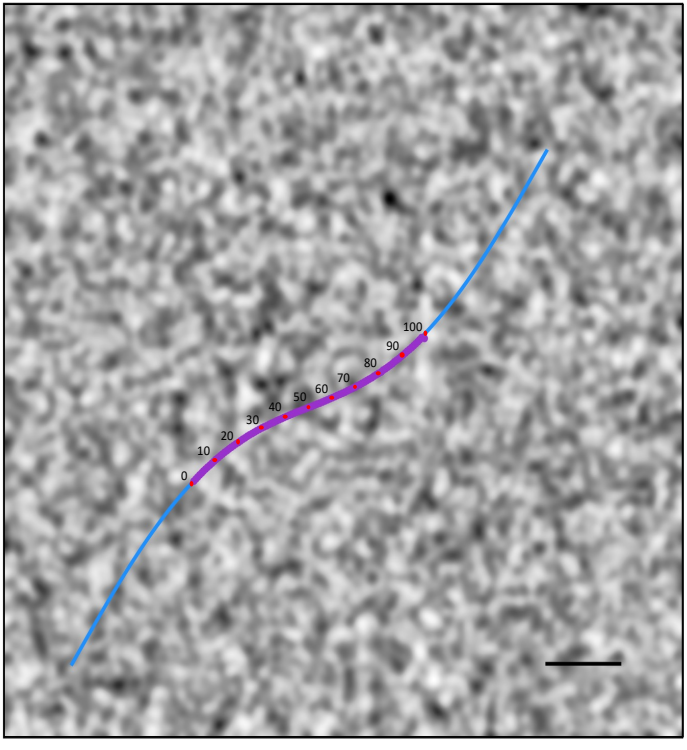


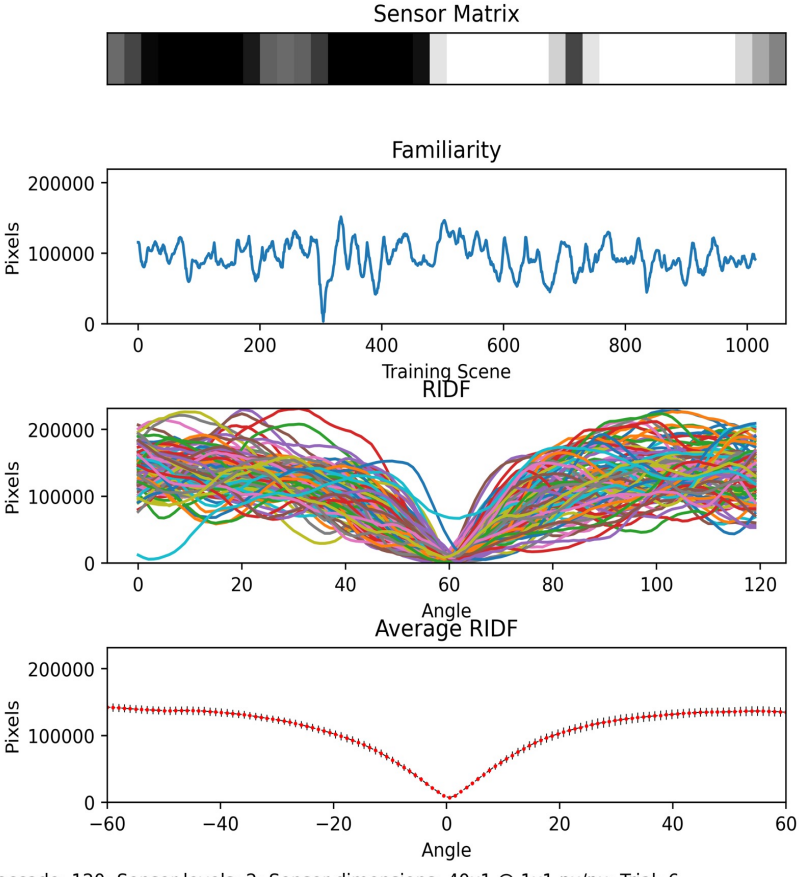
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 82.62; RMSD/dist: 0.207; TD: 92396; p90: 34; p50: 18; complete: 0


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

90%

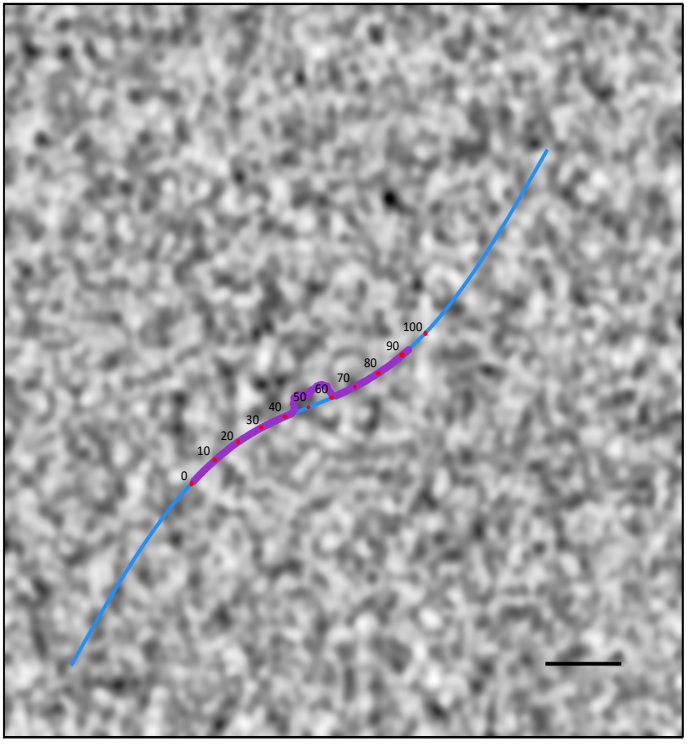


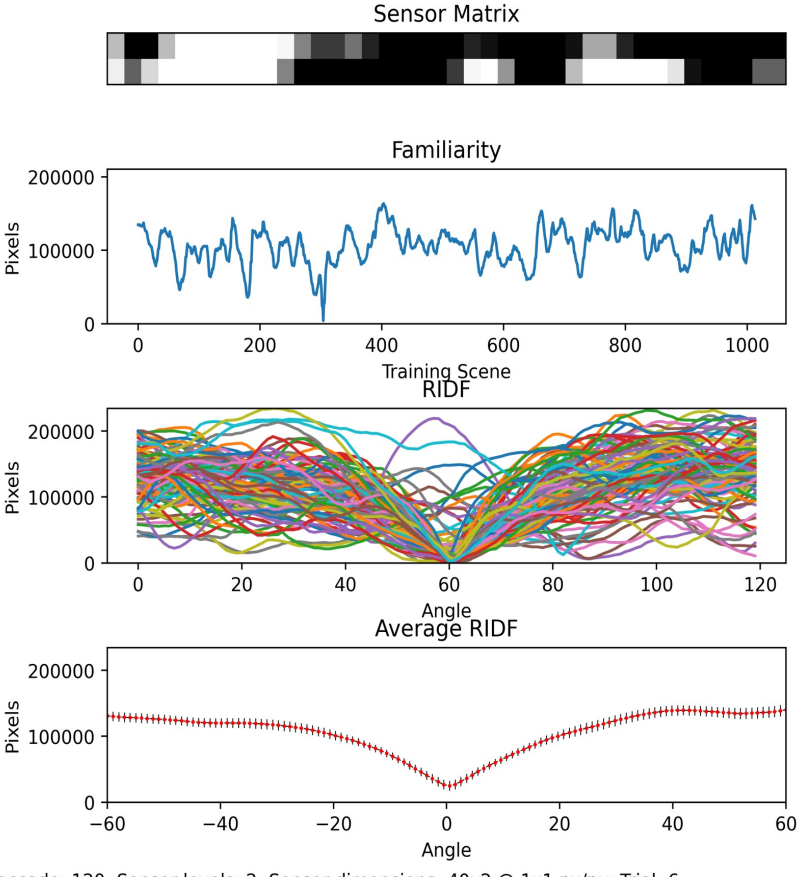


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 44.61; RMSD/dist: 0.112; TD: 88417; p90: 30; p50: 16; complete: 0

80%

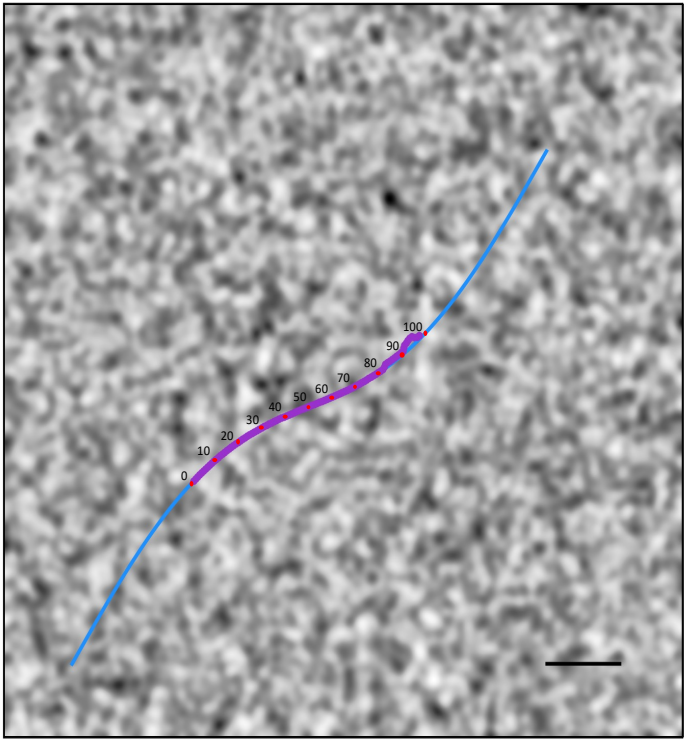


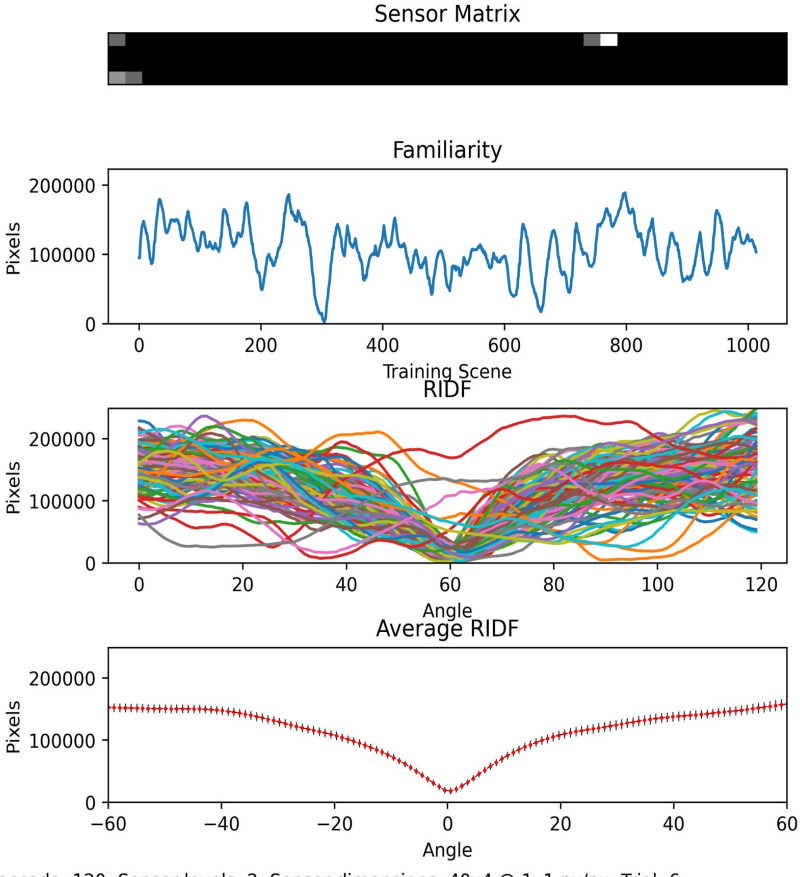


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 423.83; RMSD/dist: 1.060; TD: 81874; p90: 38; p50: 18; complete: 0

80%

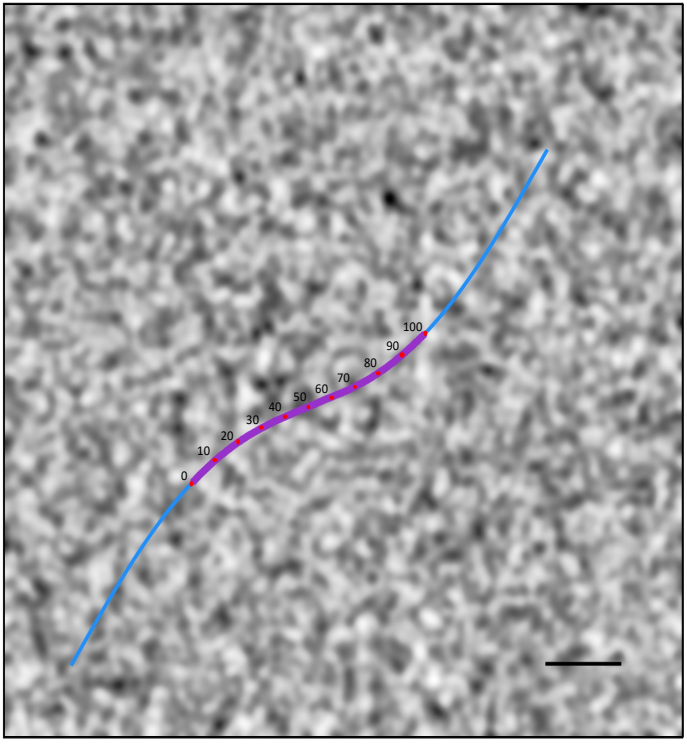


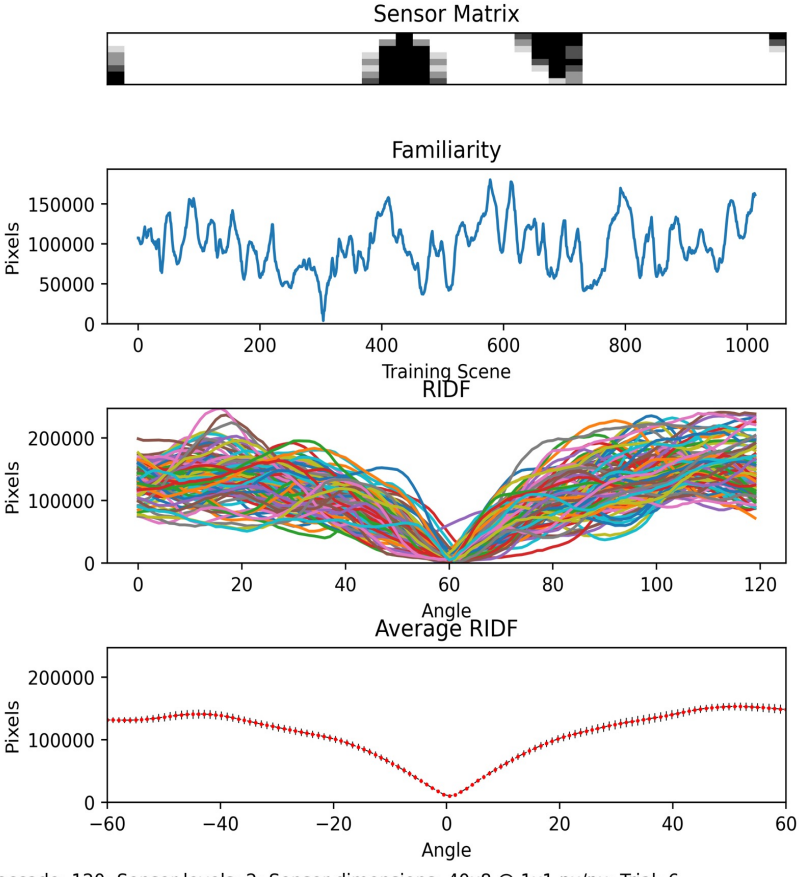


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 160.84; RMSD/dist: 0.402; TD: 88001; p90: 34; p50: 16; complete: 0

100%

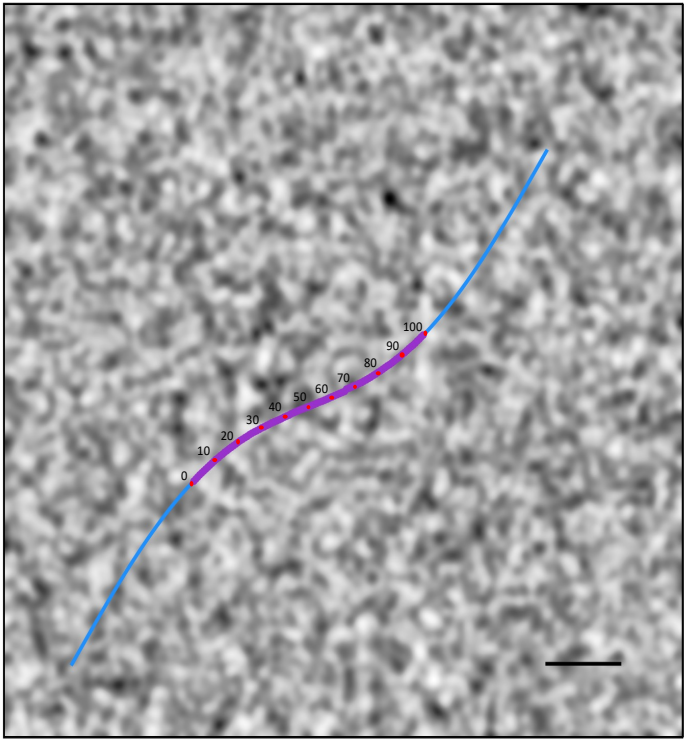


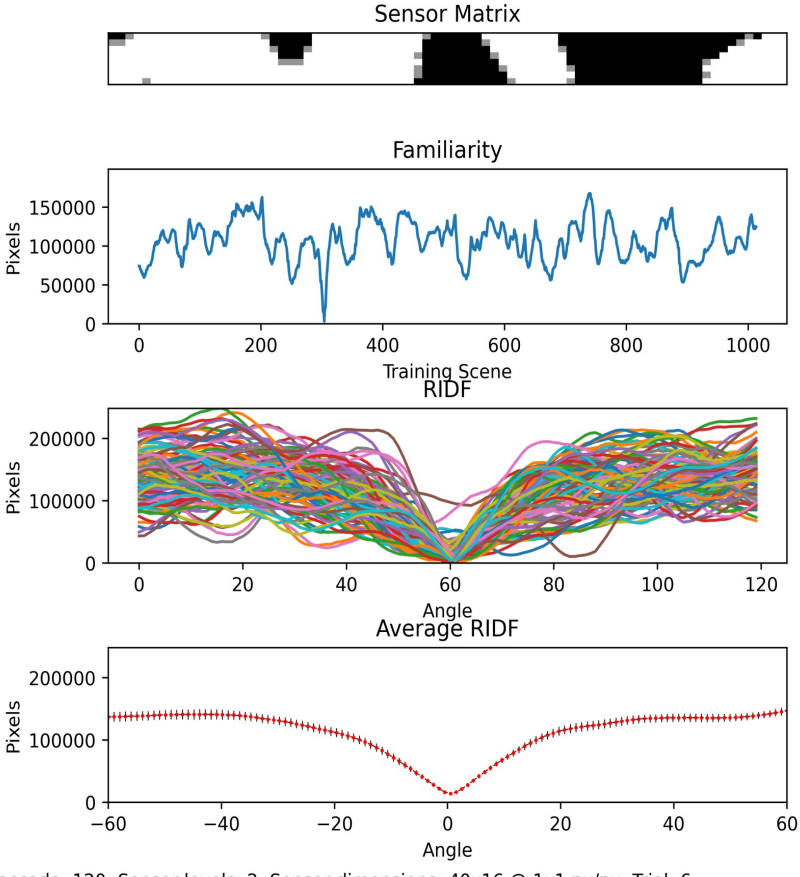


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 62.31; RMSD/dist: 0.156; TD: 91249; p90: 34; p50: 18; complete: 0

100%

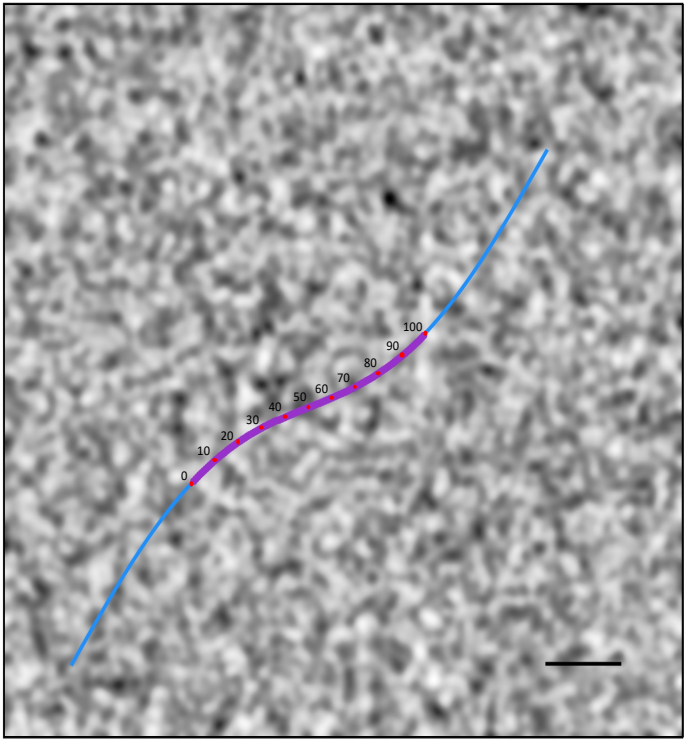


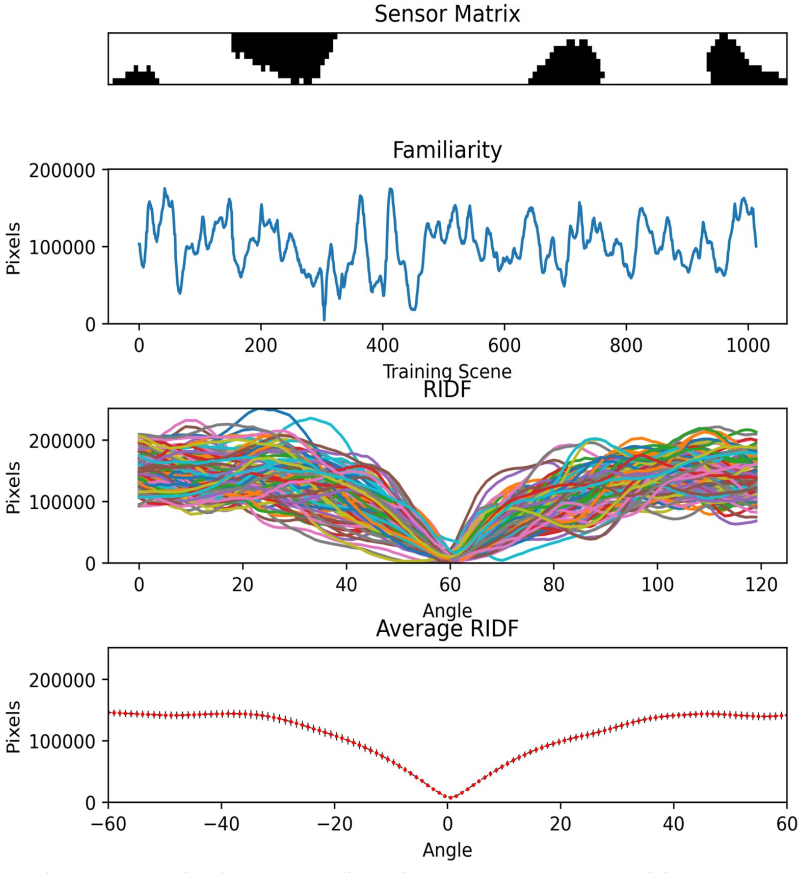


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 93.09; RMSD/dist: 0.233; TD: 88814; p90: 28; p50: 16; complete: 0

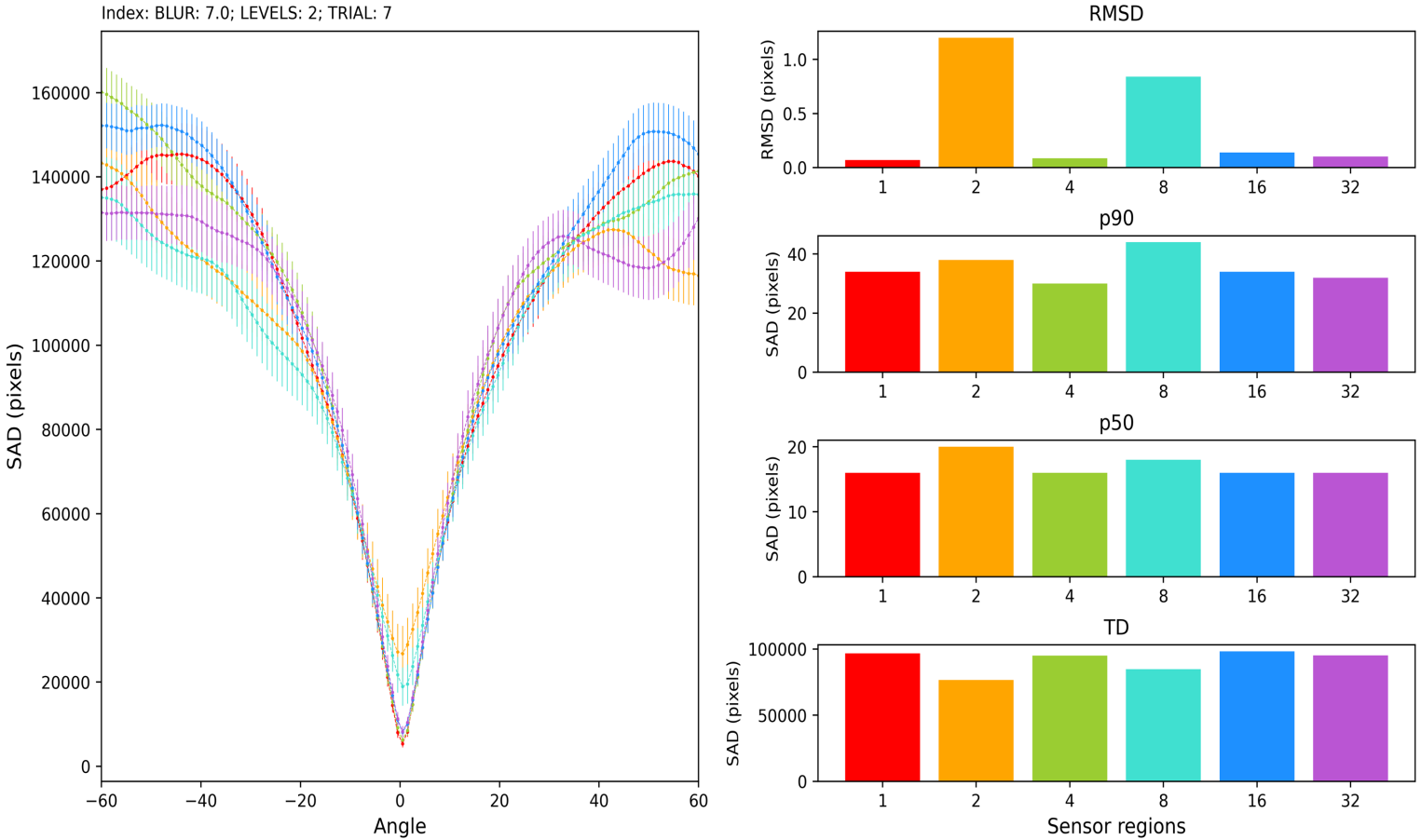
100%



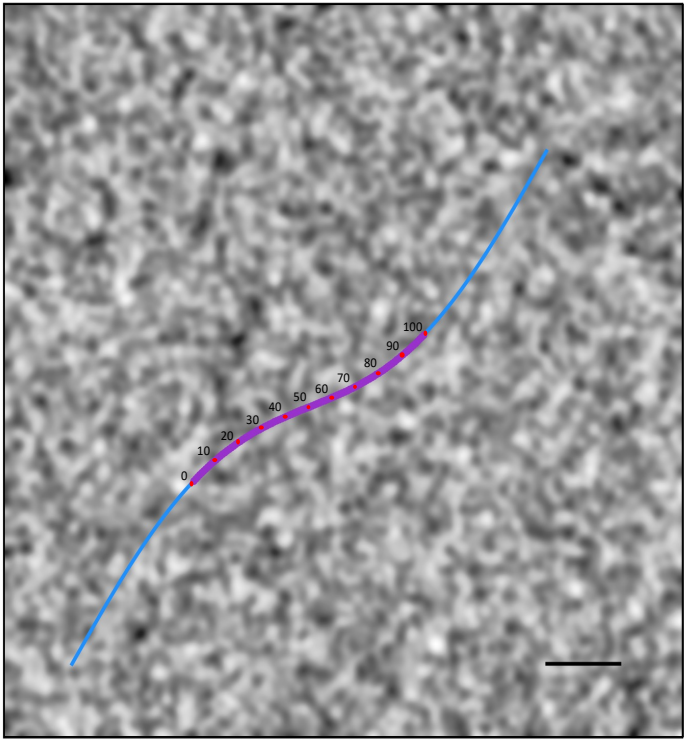


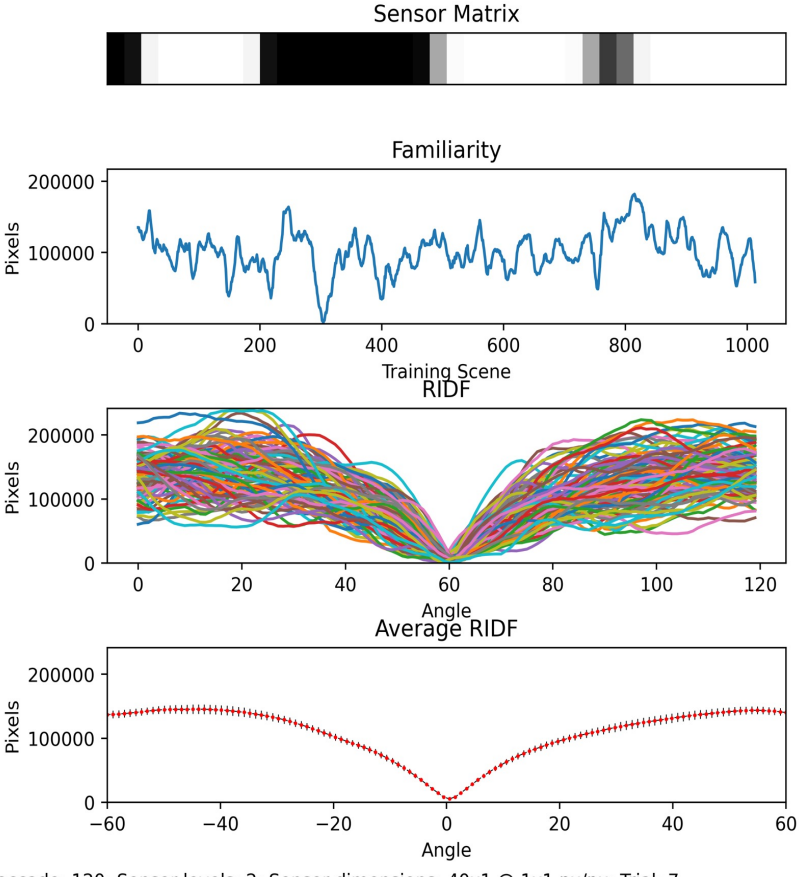
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 43.45; RMSD/dist: 0.109; TD: 94498; p90: 32; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

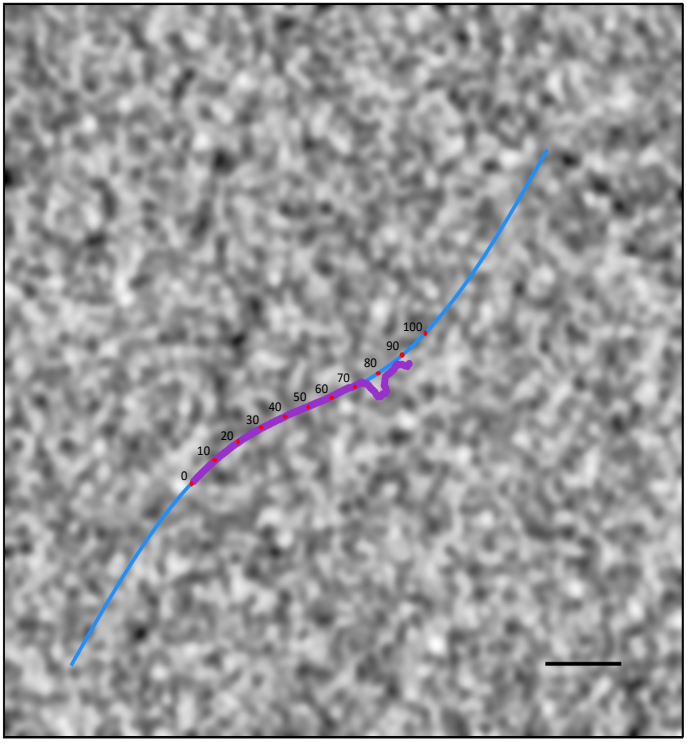


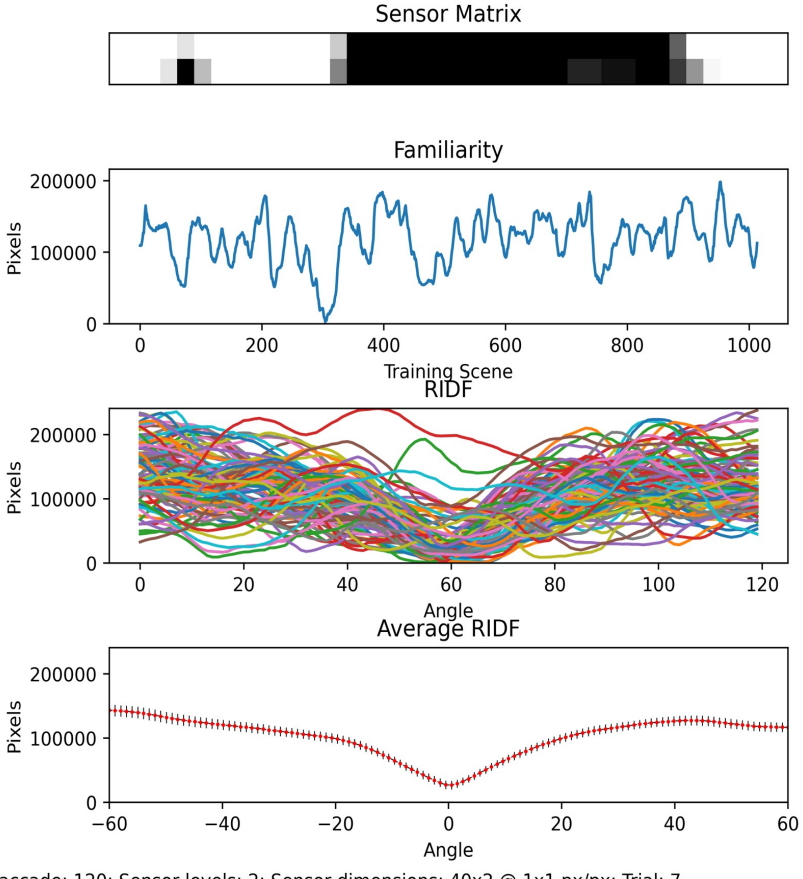


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 28.12; RMSD/dist: 0.070; TD: 96727; p90: 34; p50: 16; complete: 0

70%

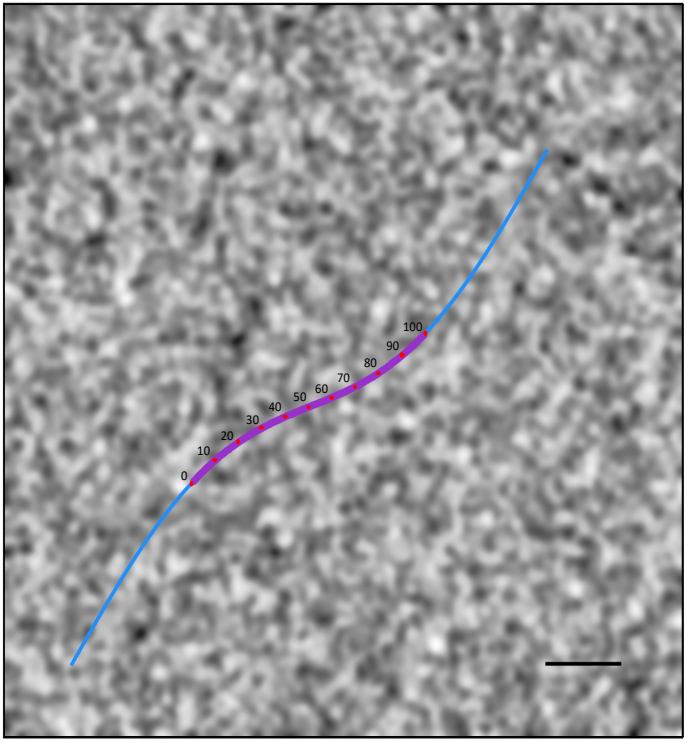


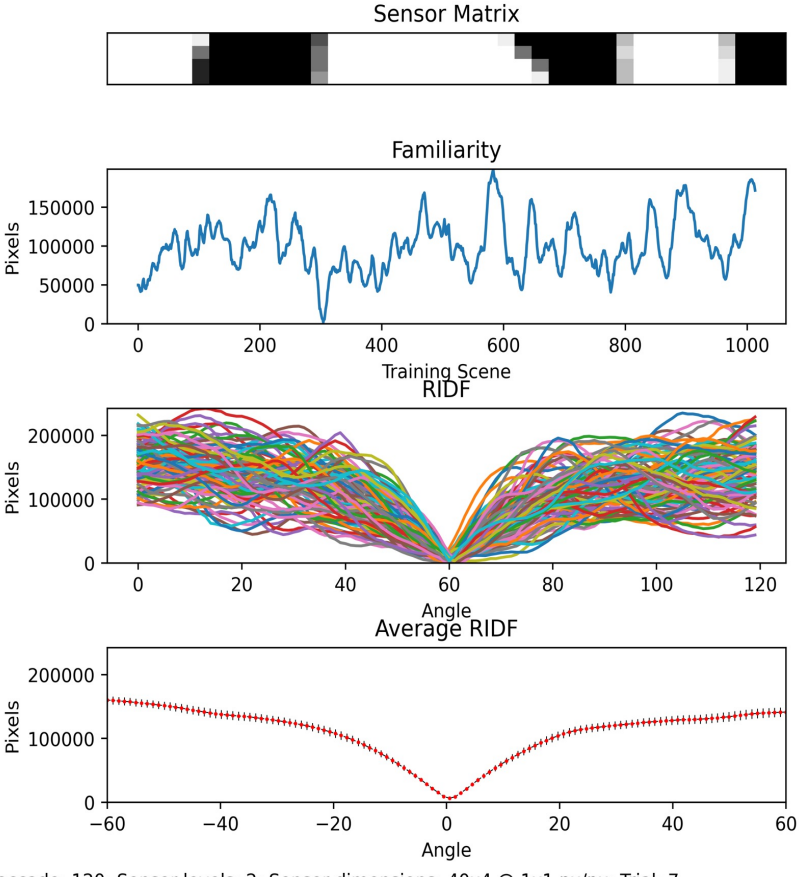


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 480.45; RMSD/dist: 1.201; TD: 76632; p90: 38; p50: 20; complete: 0

100%

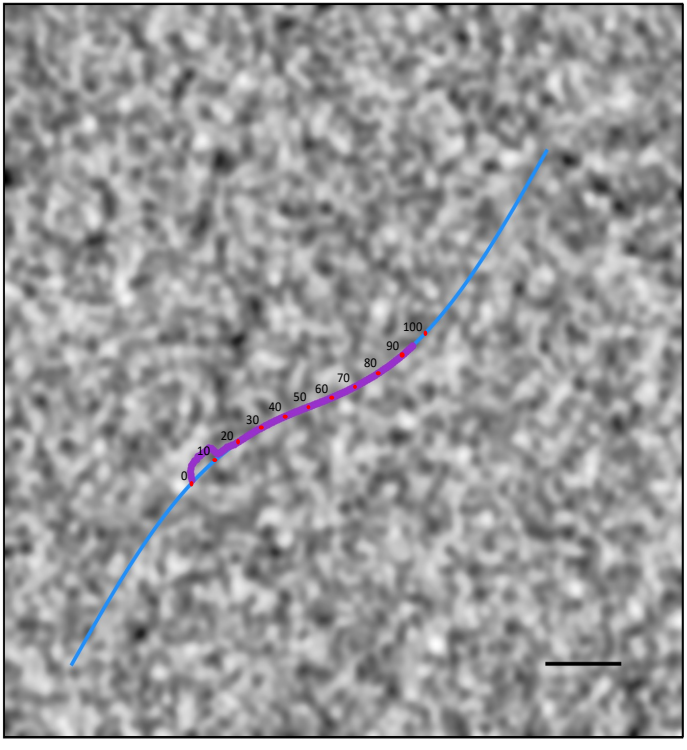


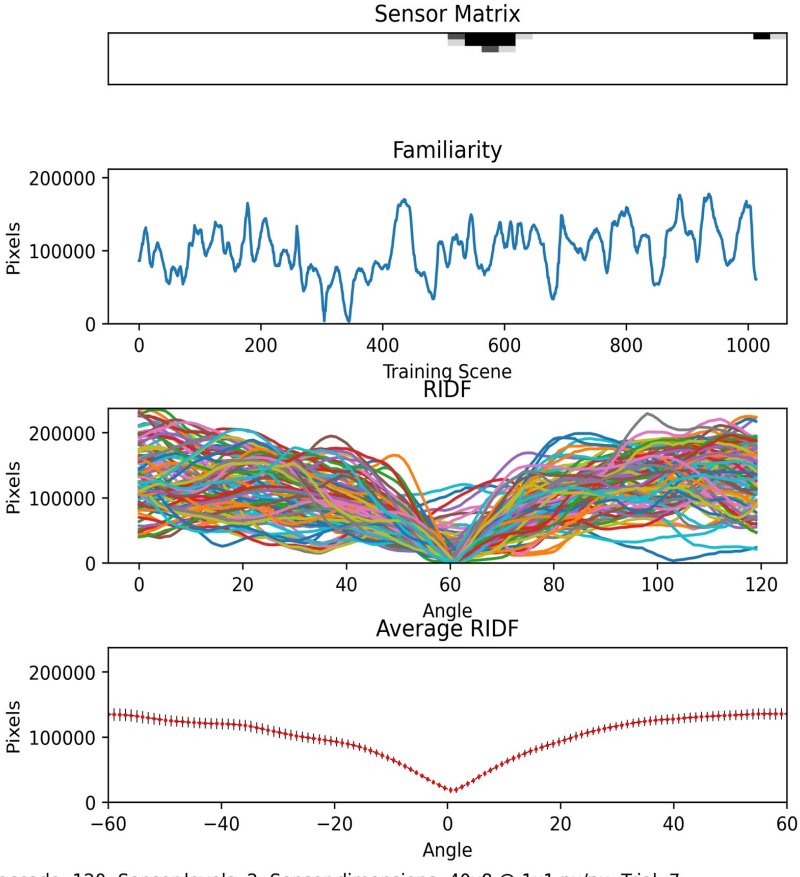


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 34.32; RMSD/dist: 0.086; TD: 94991; p90: 30; p50: 16; complete: 0

80%

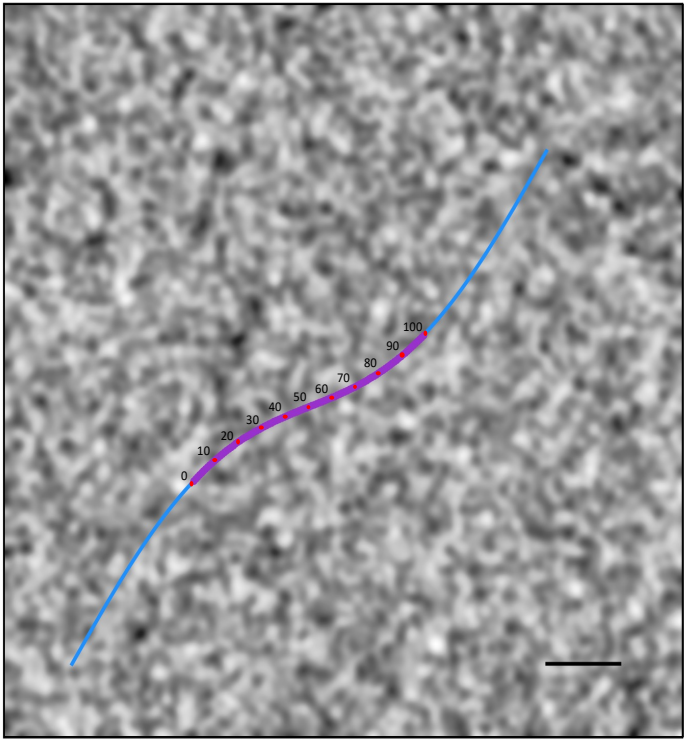


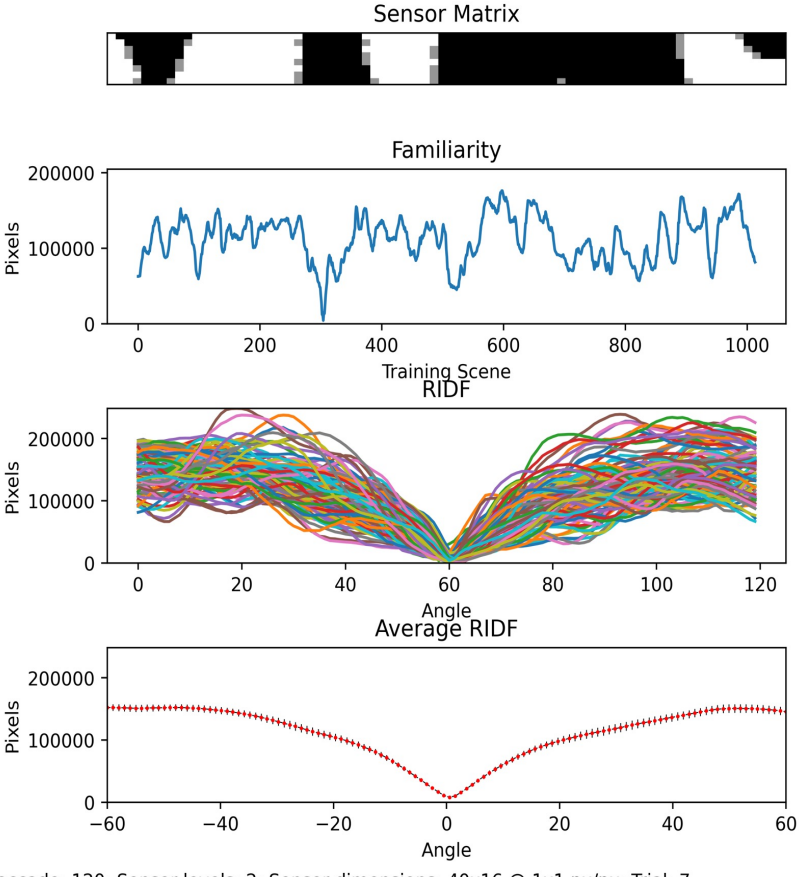


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 336.12; RMSD/dist: 0.840; TD: 84752; p90: 44; p50: 18; complete: 0

100%

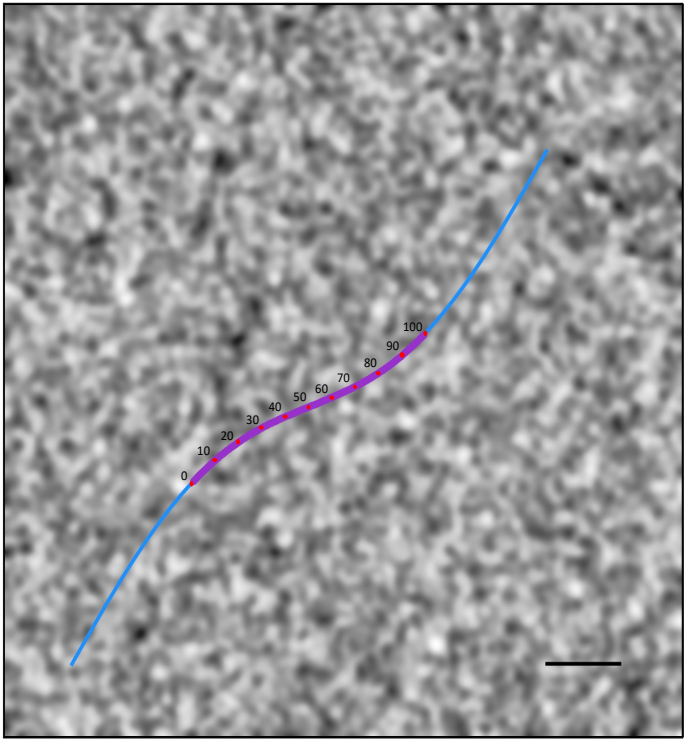


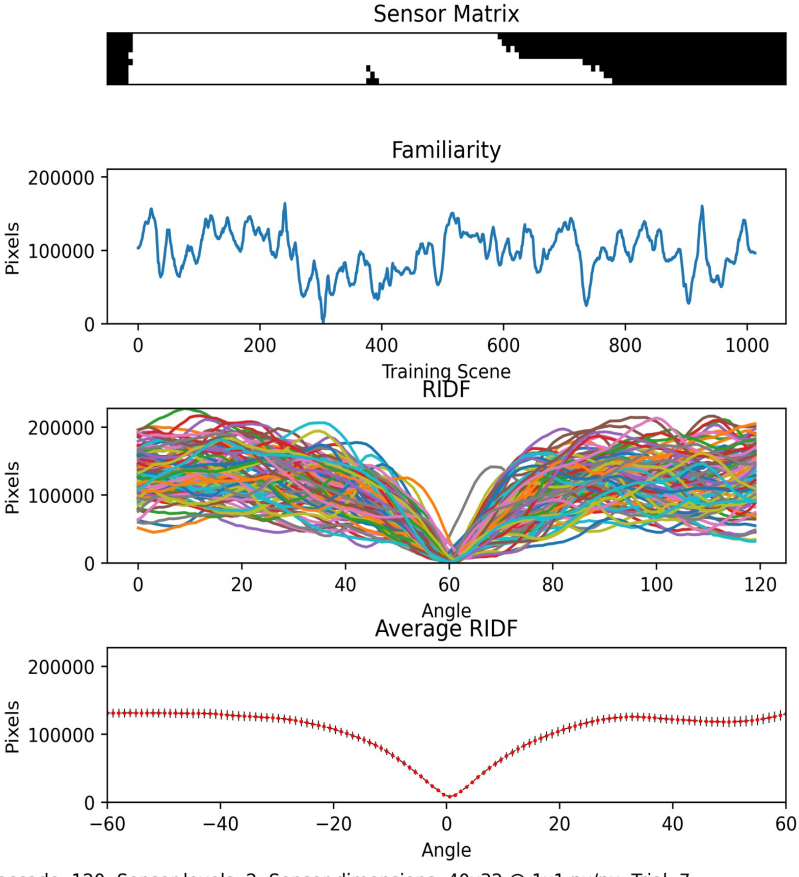


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 55.80; RMSD/dist: 0.139; TD: 98198; p90: 34; p50: 16; complete: 0

100%





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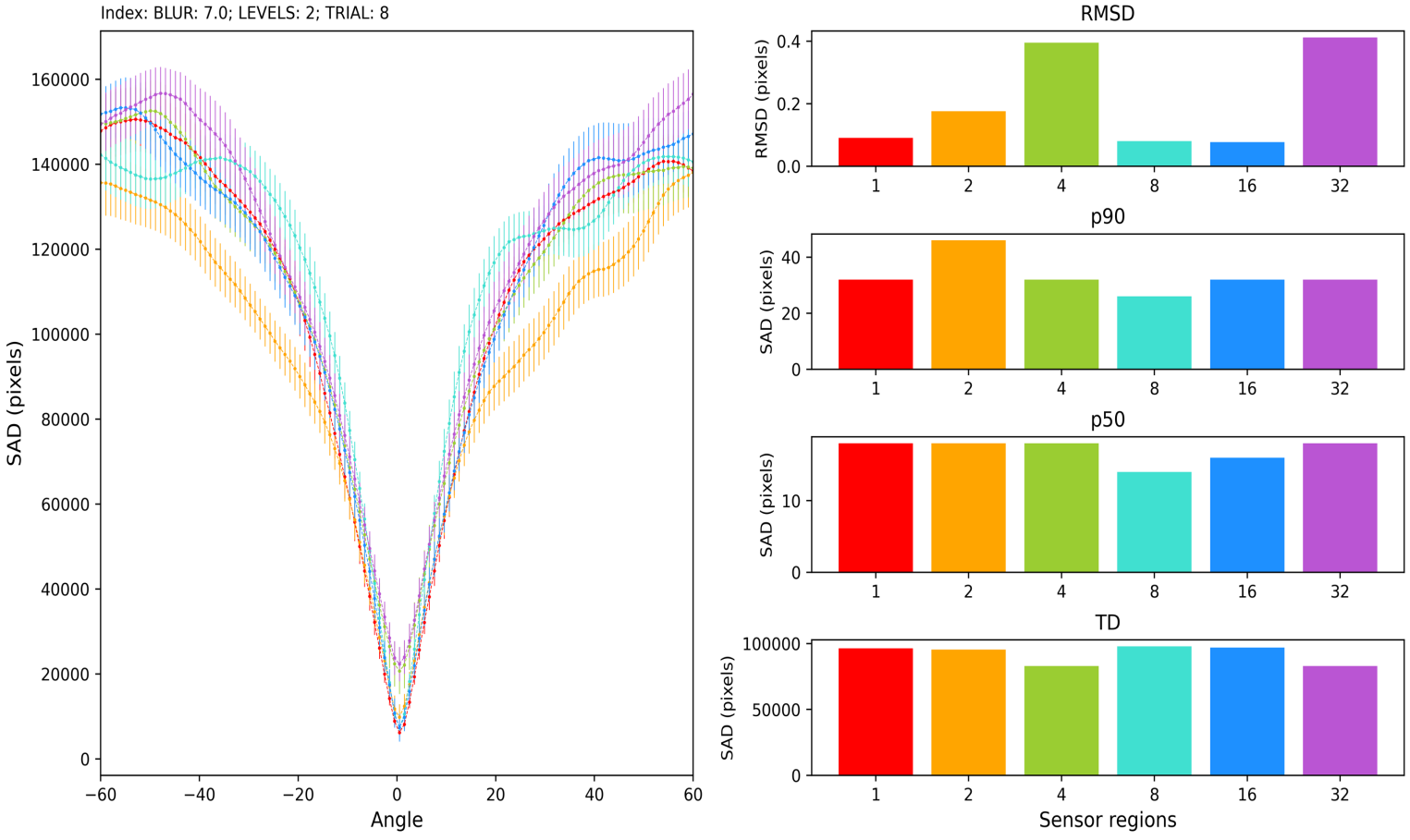
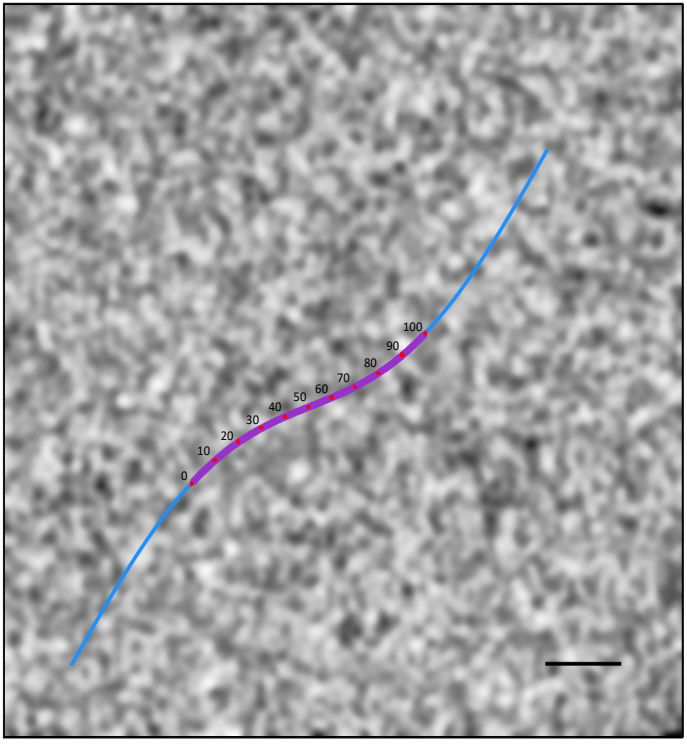
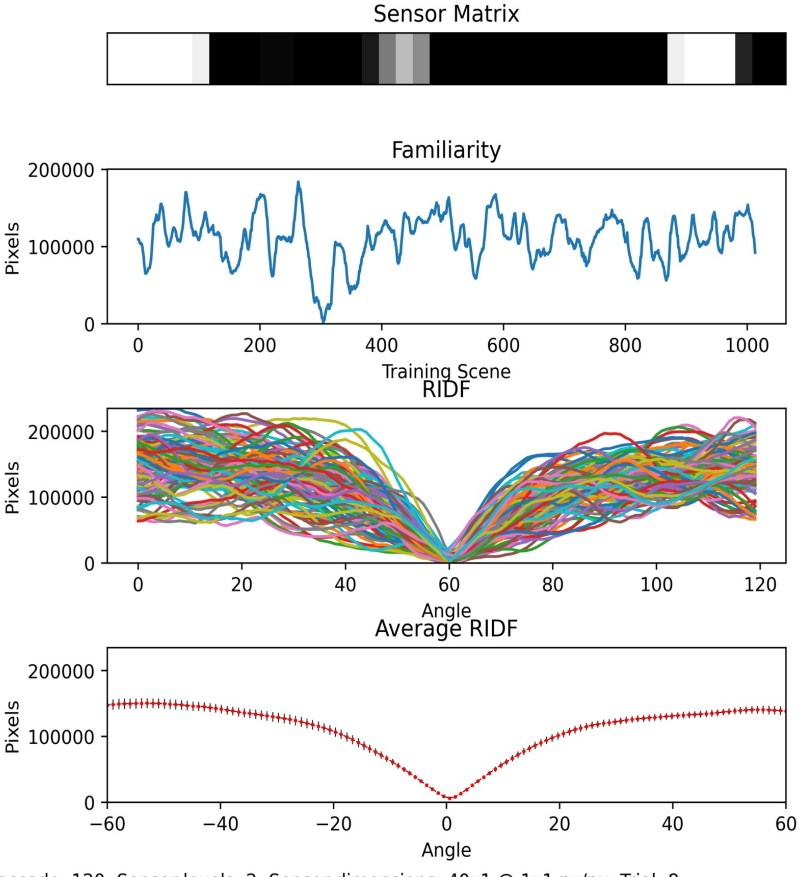
Navigation stats: RMSD error: 41.01; RMSD/dist: 0.103; TD: 95112; p90: 32; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

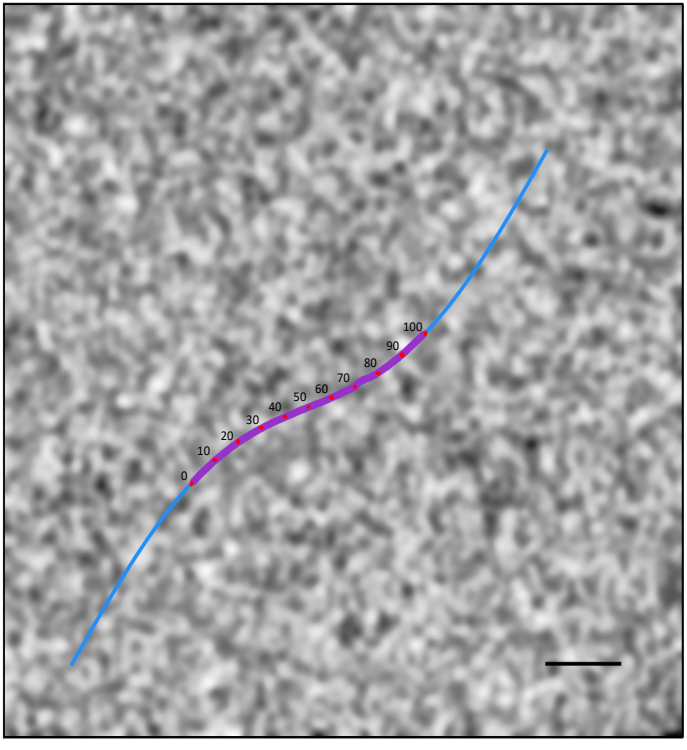


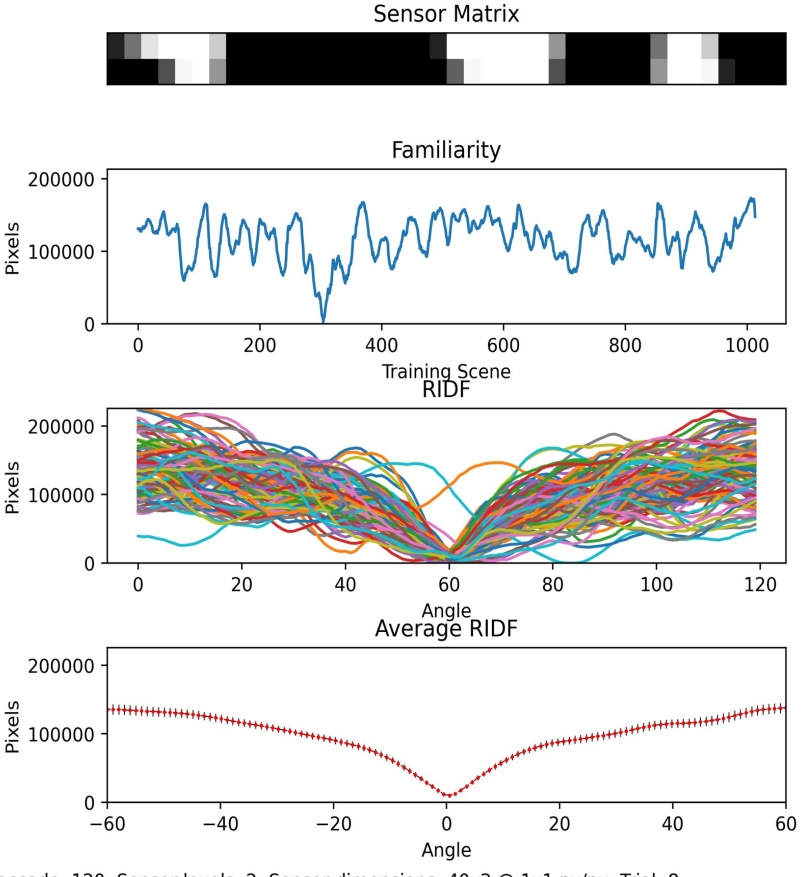


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 36.41; RMSD/dist: 0.091; TD: 96335; p90: 32; p50: 18; complete: 0

100%

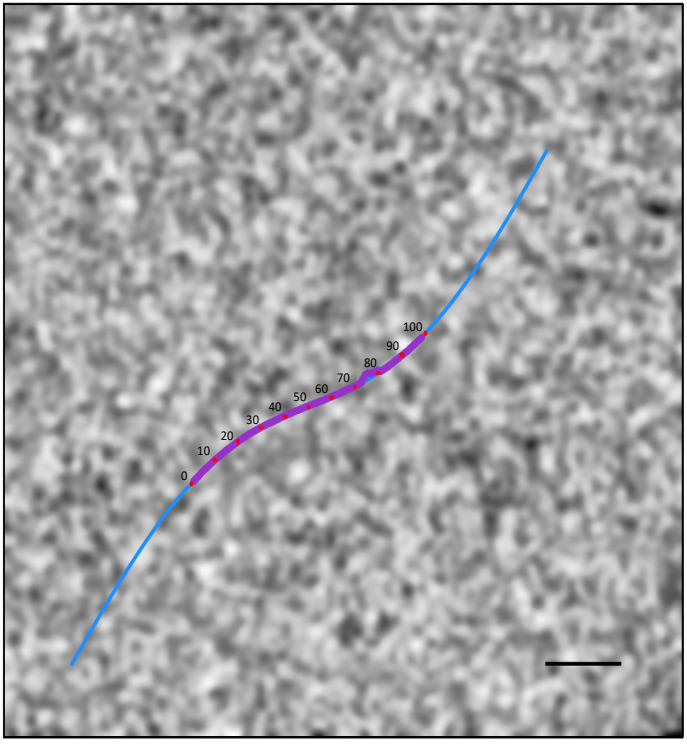


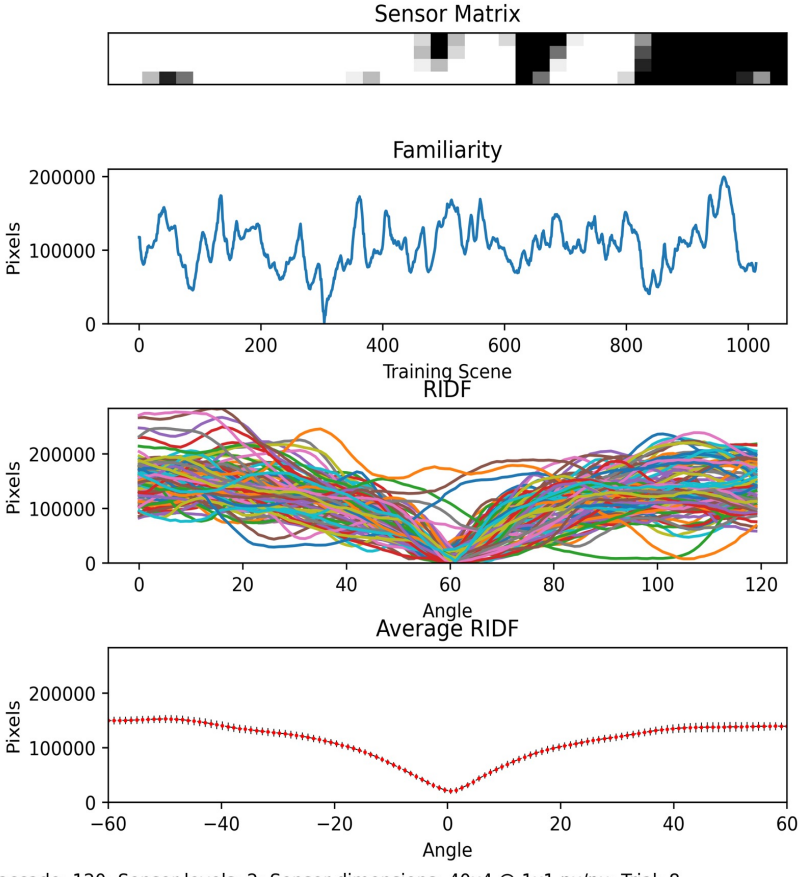


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 70.53; RMSD/dist: 0.176; TD: 95436; p90: 46; p50: 18; complete: 0

90%

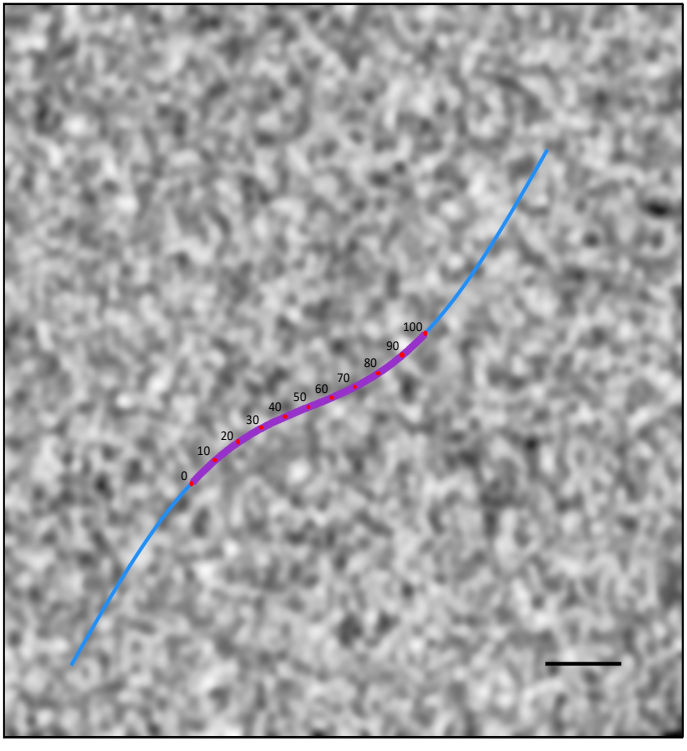


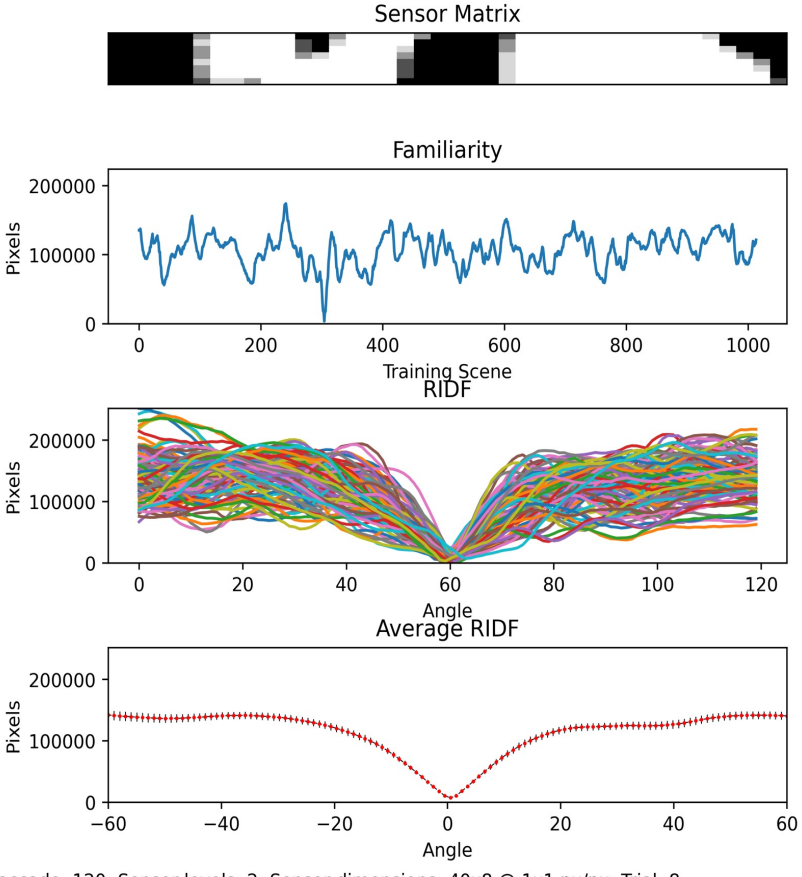


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 157.93; RMSD/dist: 0.395; TD: 83024; p90: 32; p50: 18; complete: 0

100%

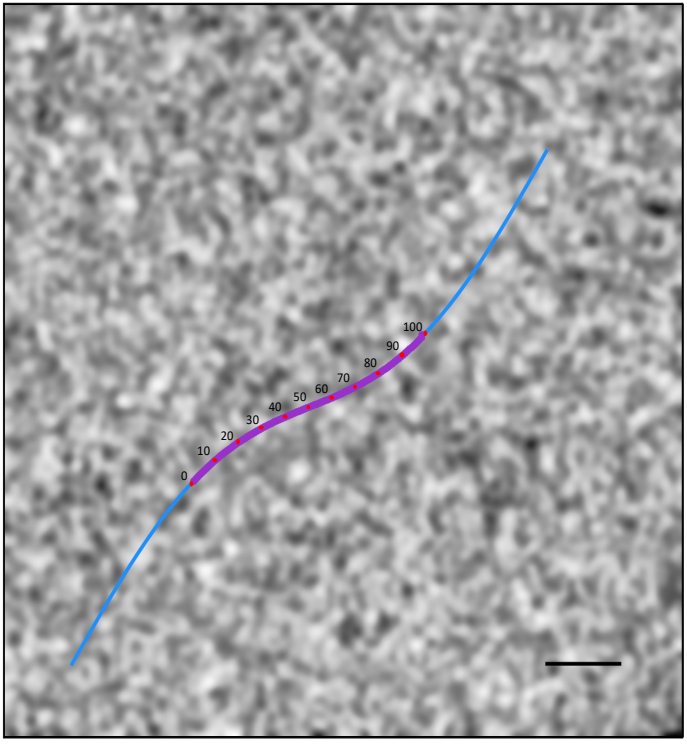


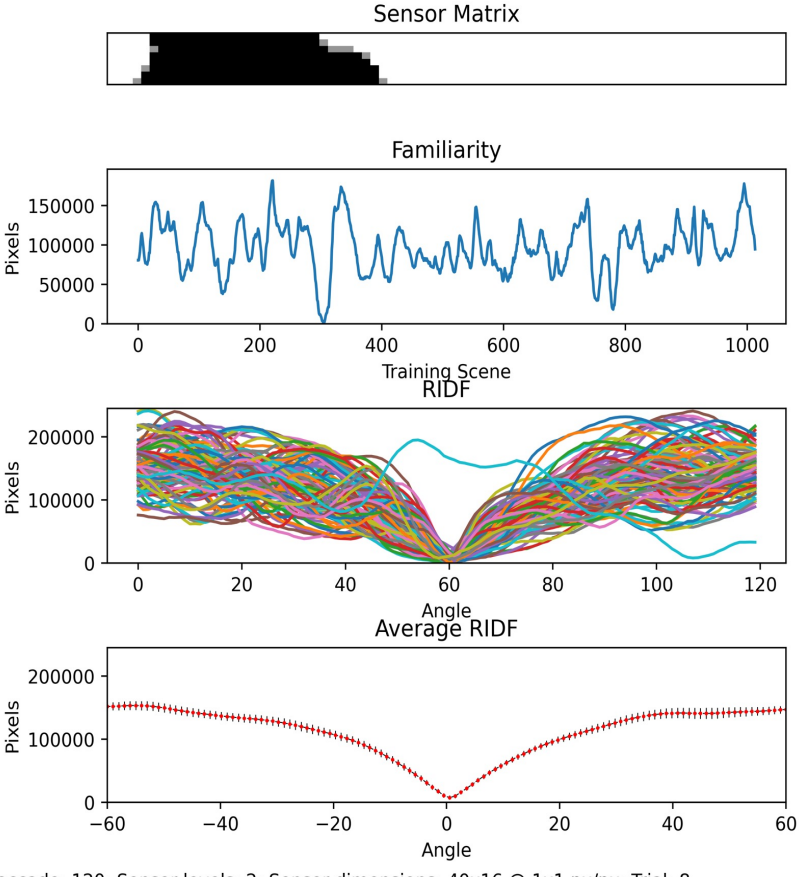


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 32.09; RMSD/dist: 0.080; TD: 97853; p90: 26; p50: 14; complete: 0

100%

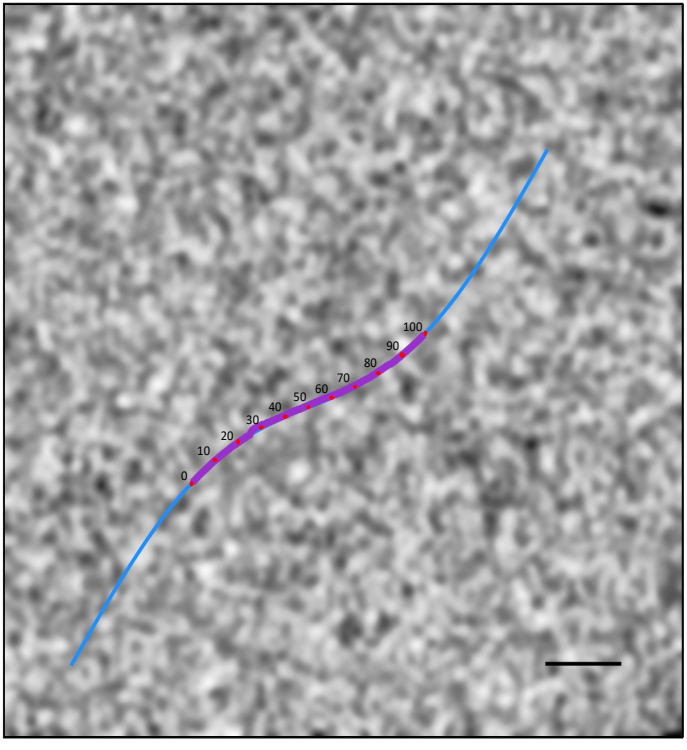


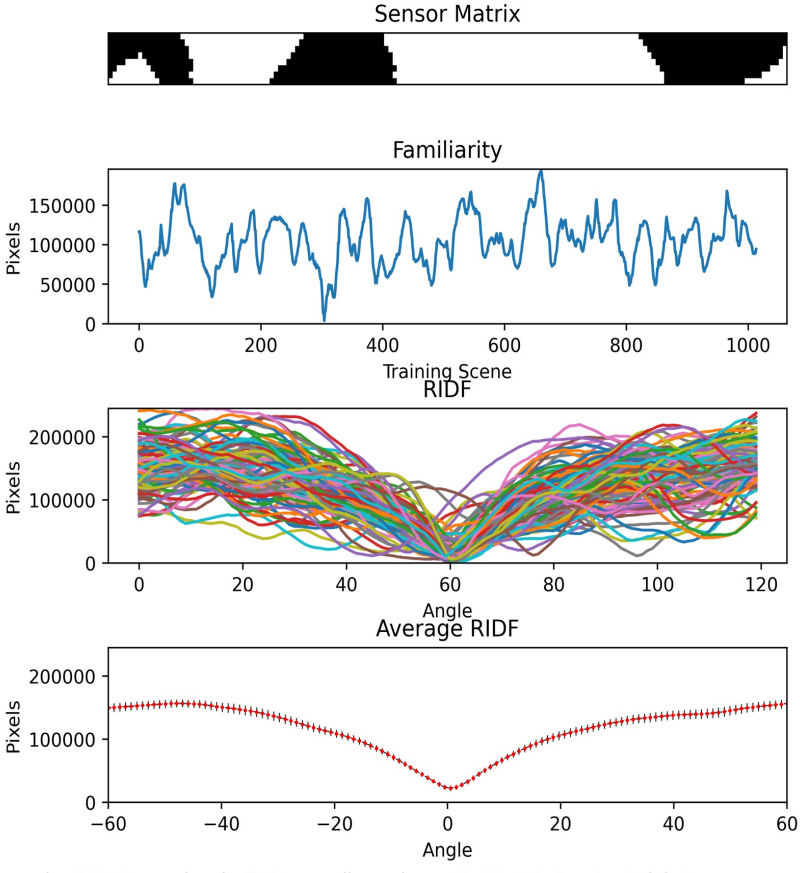


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 30.84; RMSD/dist: 0.077; TD: 96965; p90: 32; p50: 16; complete: 0

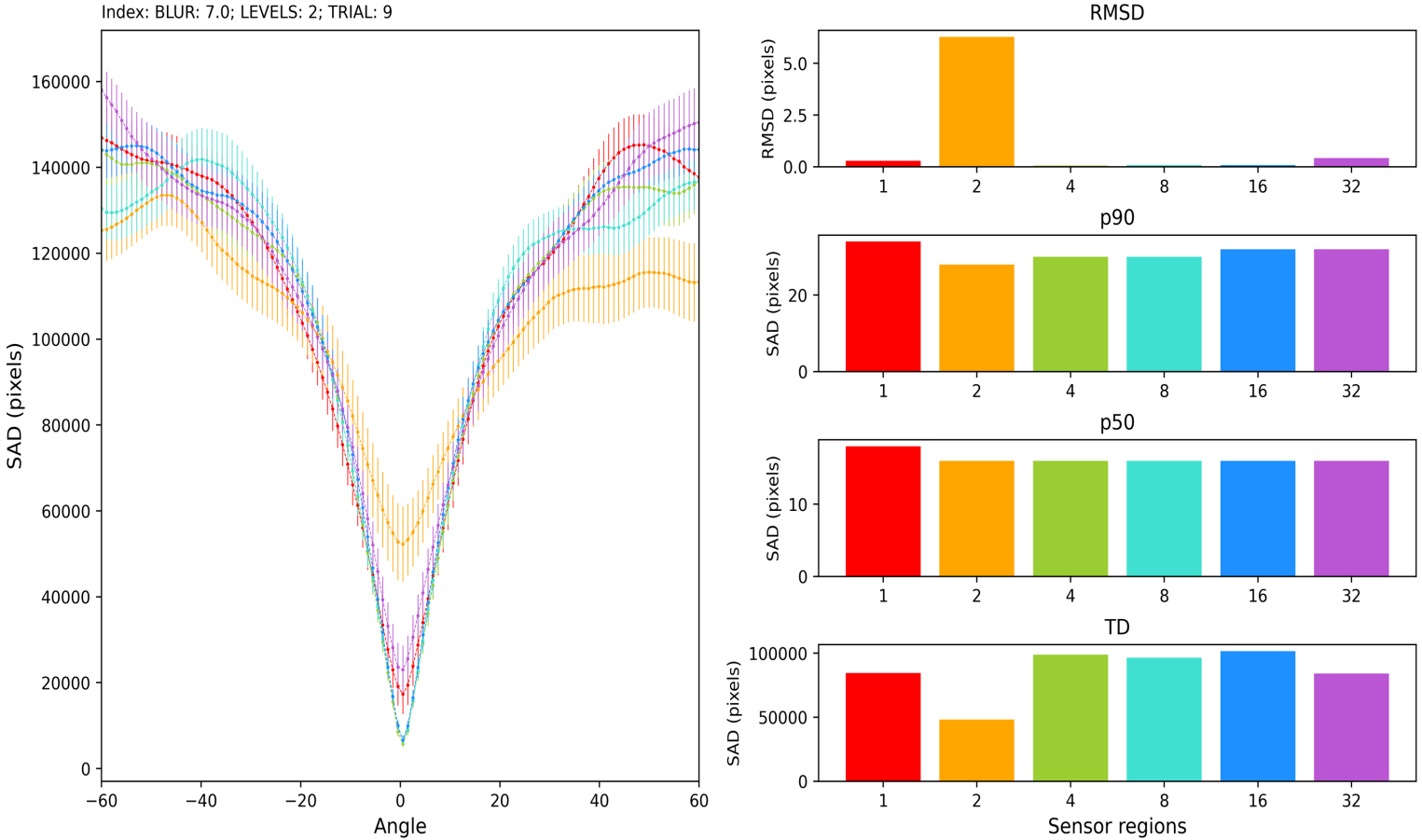
90%



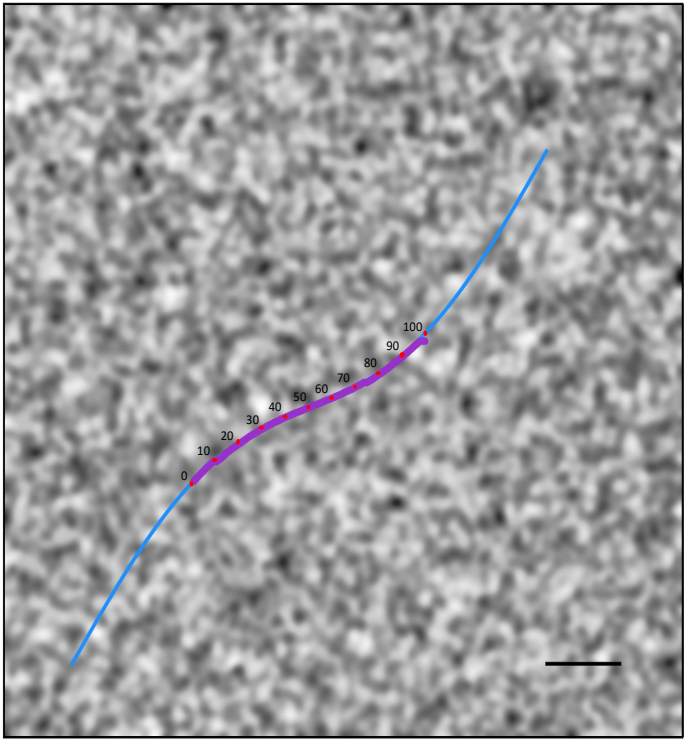


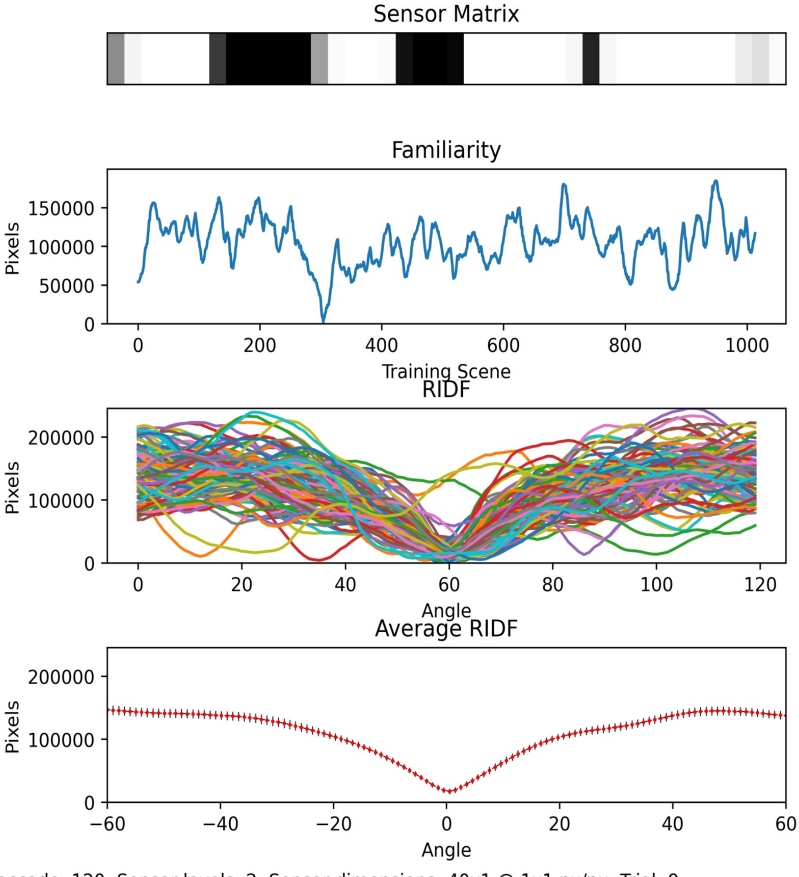
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 164.78; RMSD/dist: 0.412; TD: 82952; p90: 32; p50: 18; complete: 0


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

90%

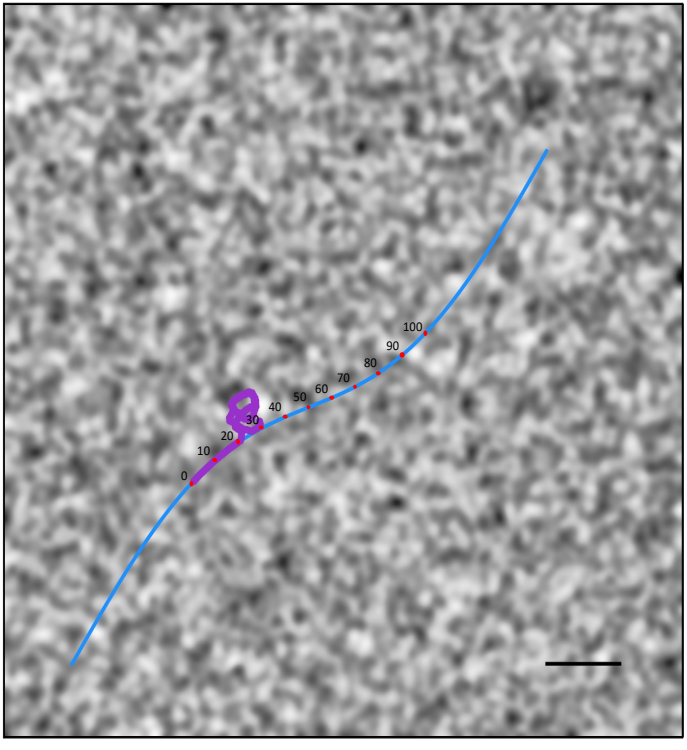


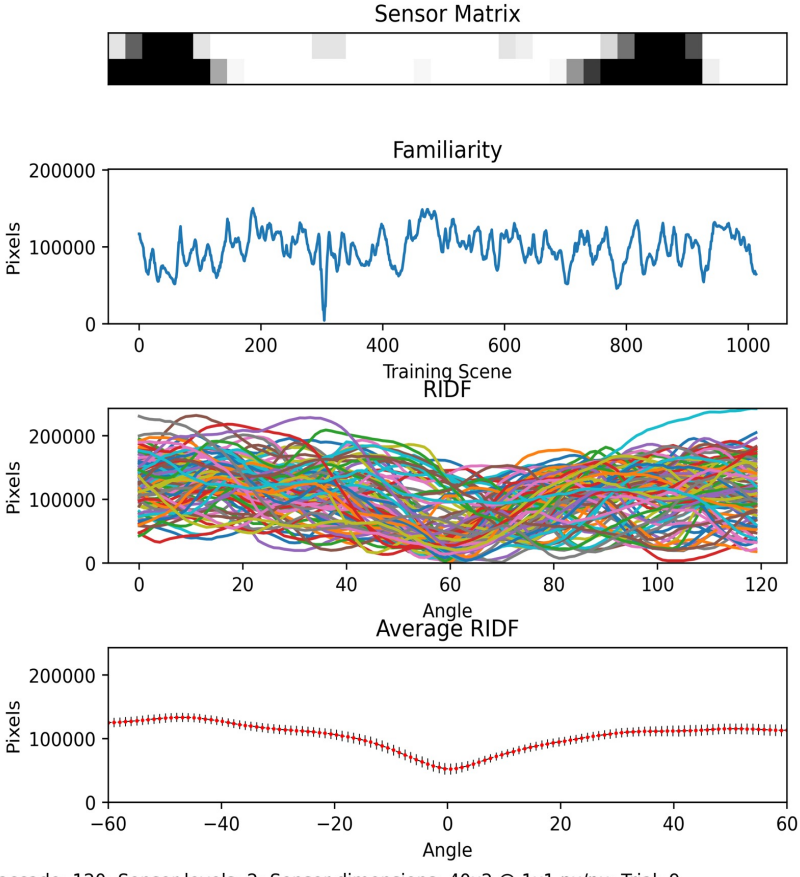


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 116.85; RMSD/dist: 0.292; TD: 84402; p90: 34; p50: 18; complete: 0

20%

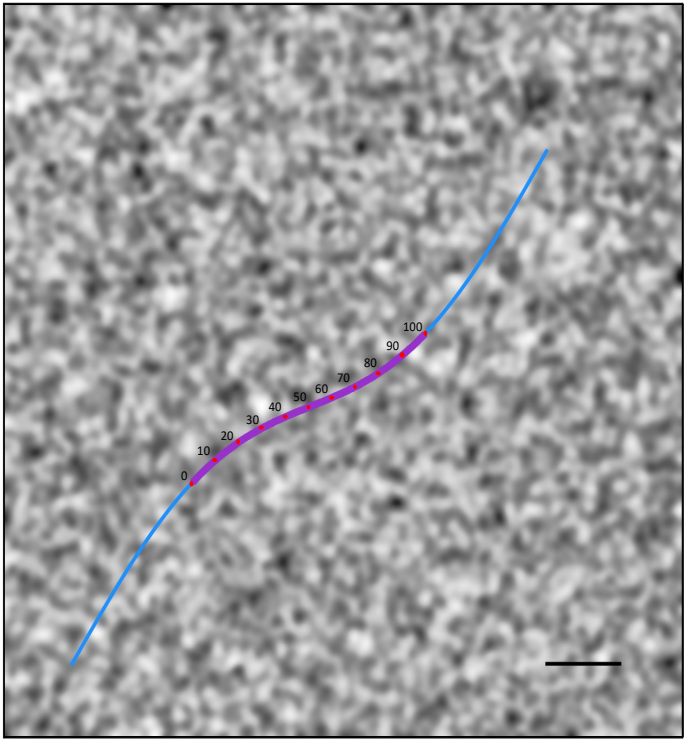


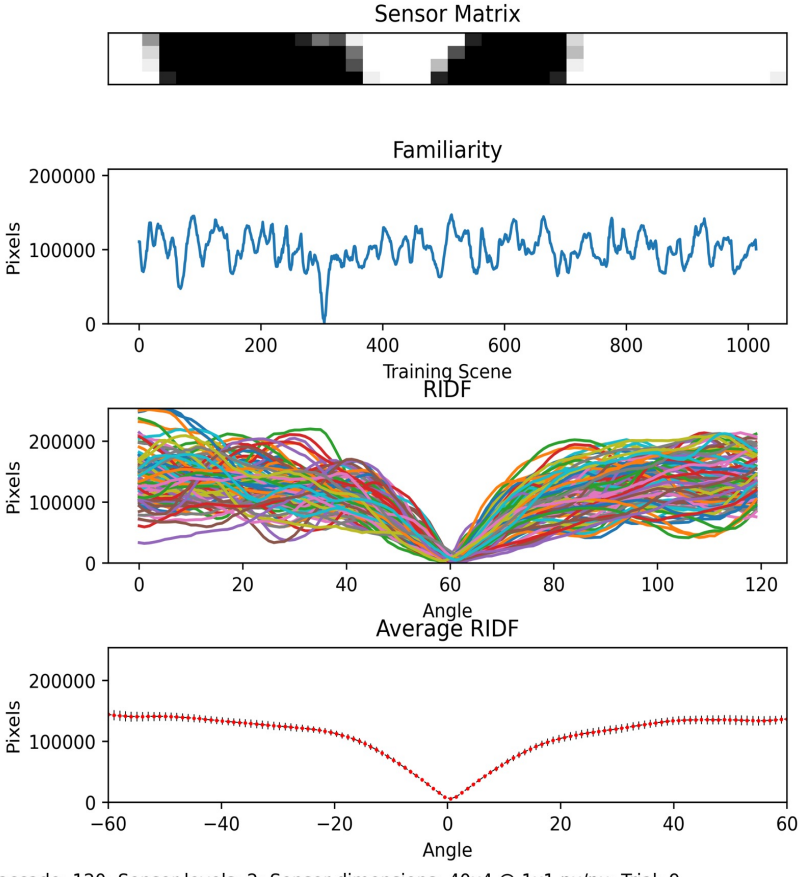


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2514.28; RMSD/dist: 6.286; TD: 48191; p90: 28; p50: 16; complete: 0

100%

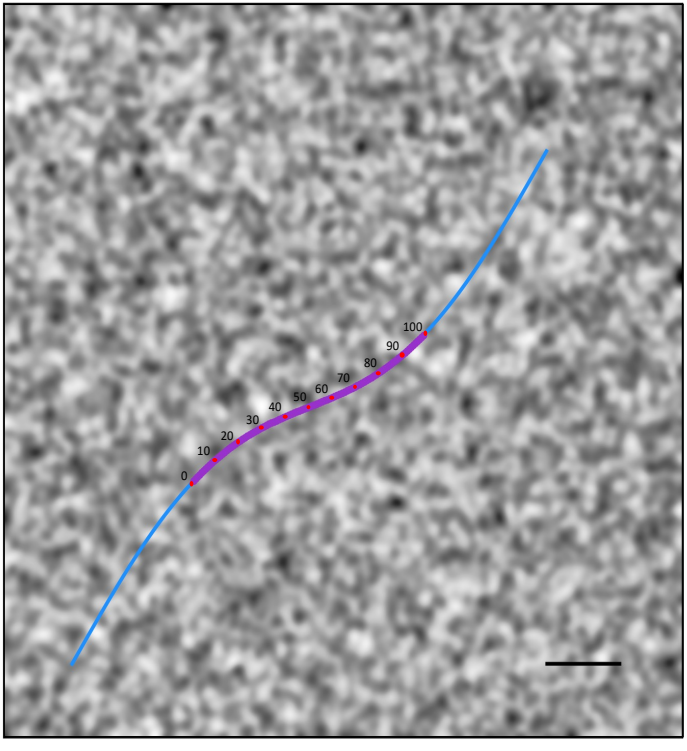


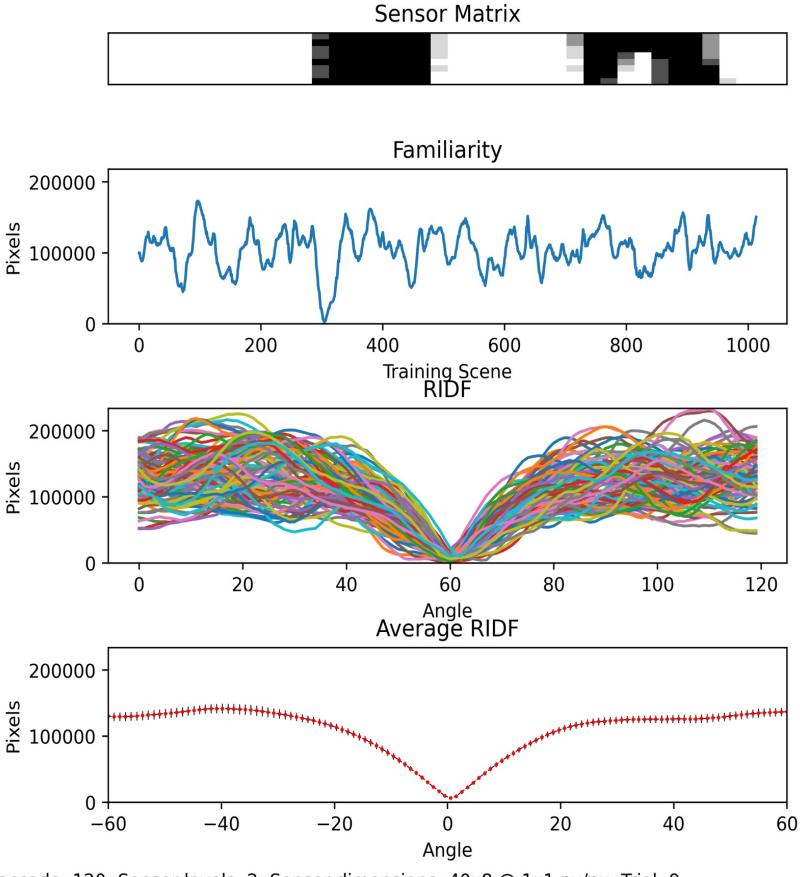


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 24.29; RMSD/dist: 0.061; TD: 98819; p90: 30; p50: 16; complete: 0

100%

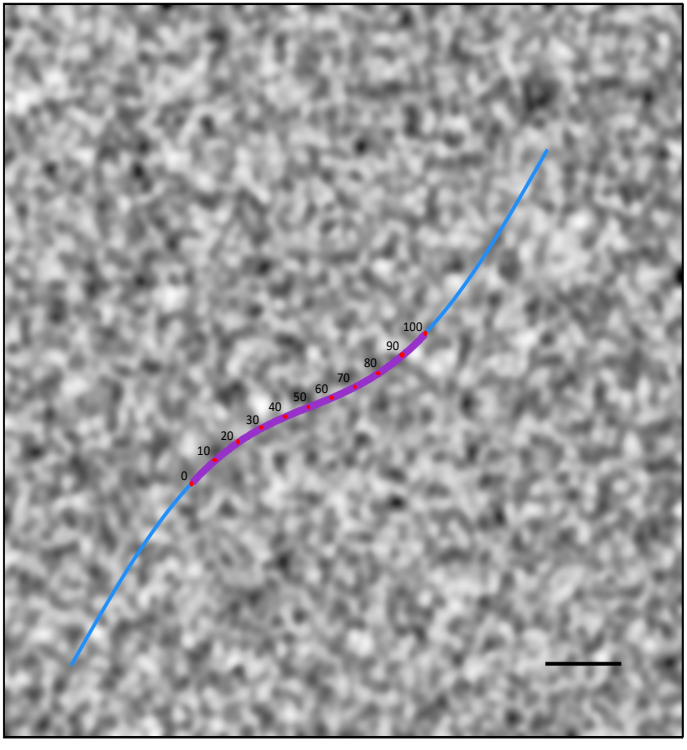


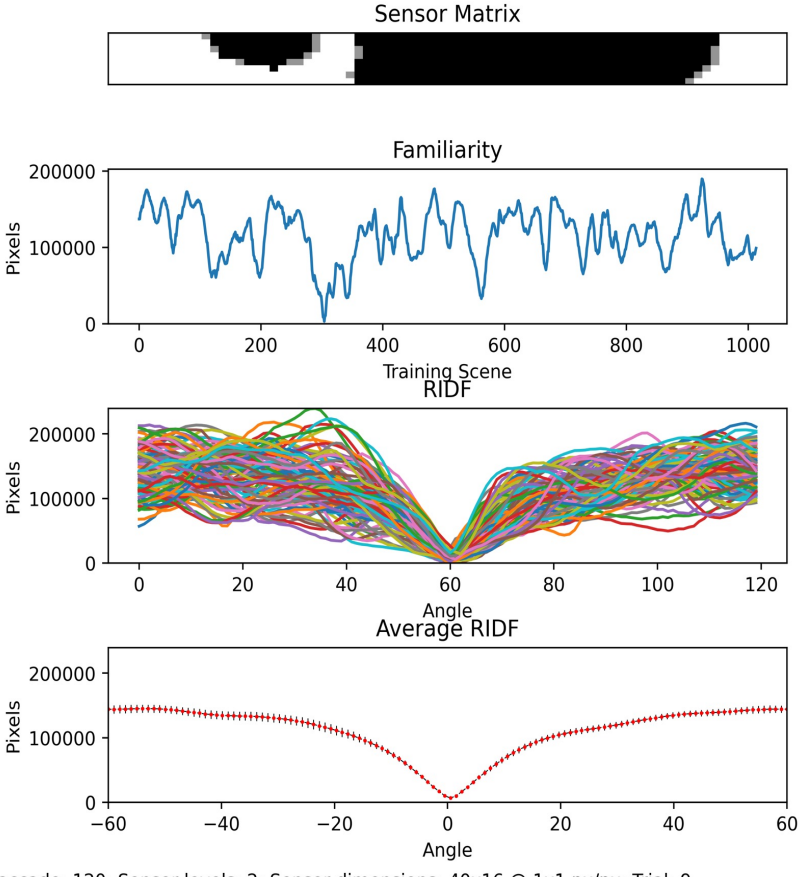


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 35.78; RMSD/dist: 0.089; TD: 96407; p90: 30; p50: 16; complete: 0

100%

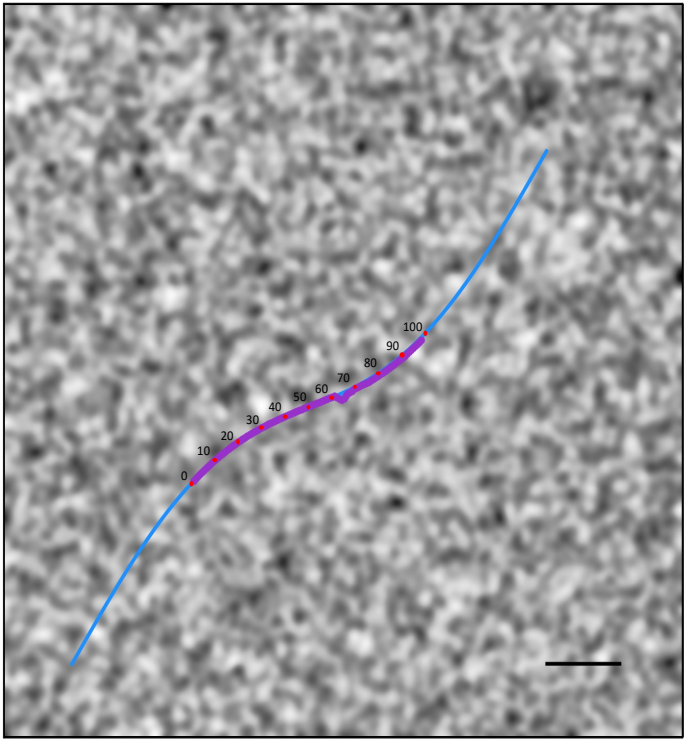


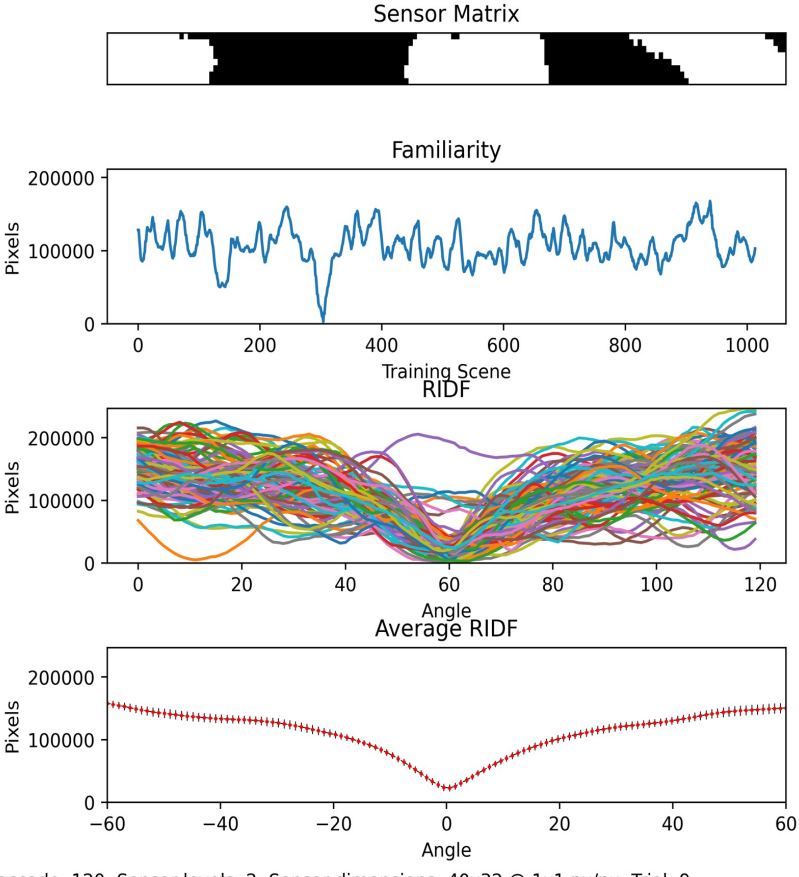


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 33.49; RMSD/dist: 0.084; TD: 101527; p90: 32; p50: 16; complete: 0

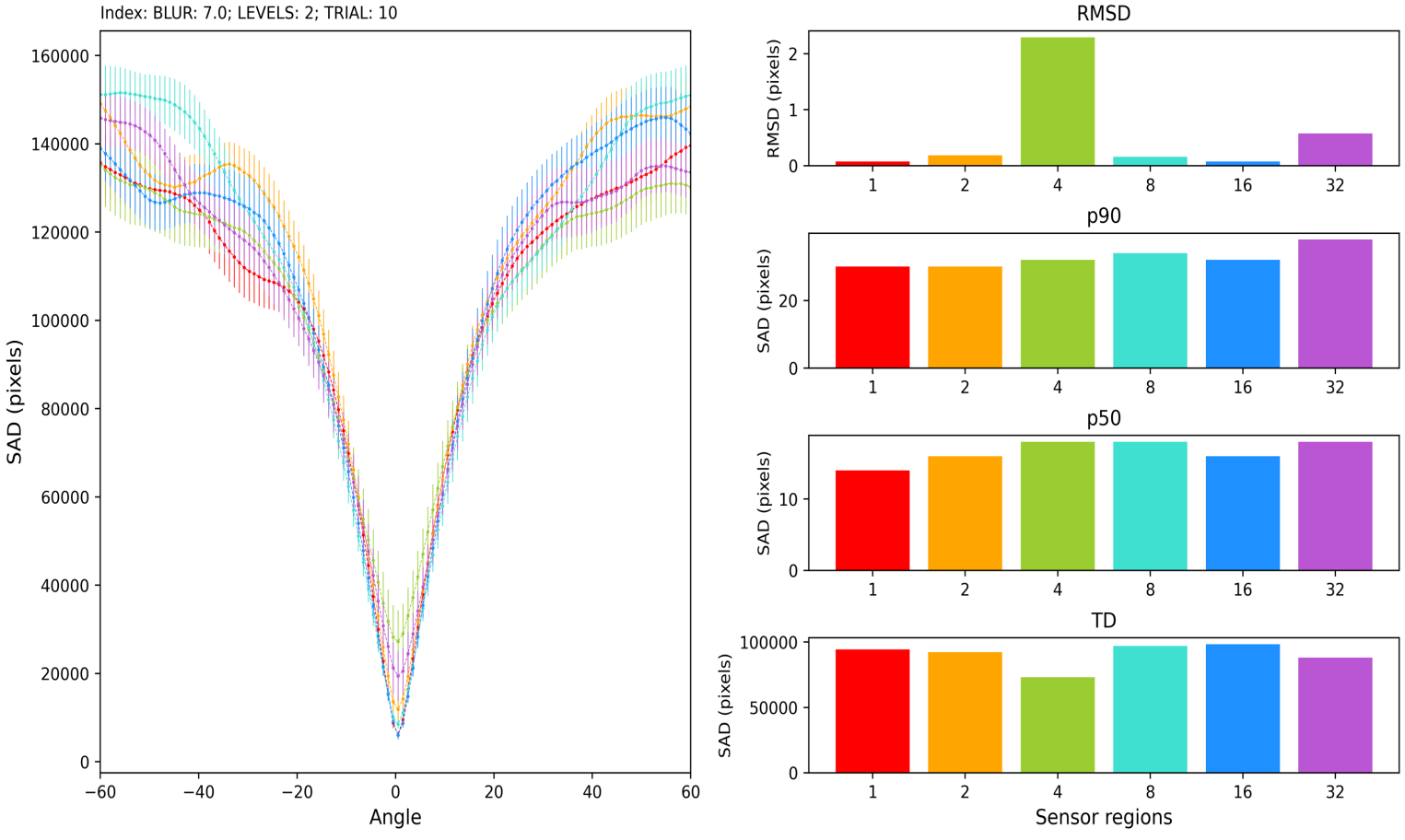
90%



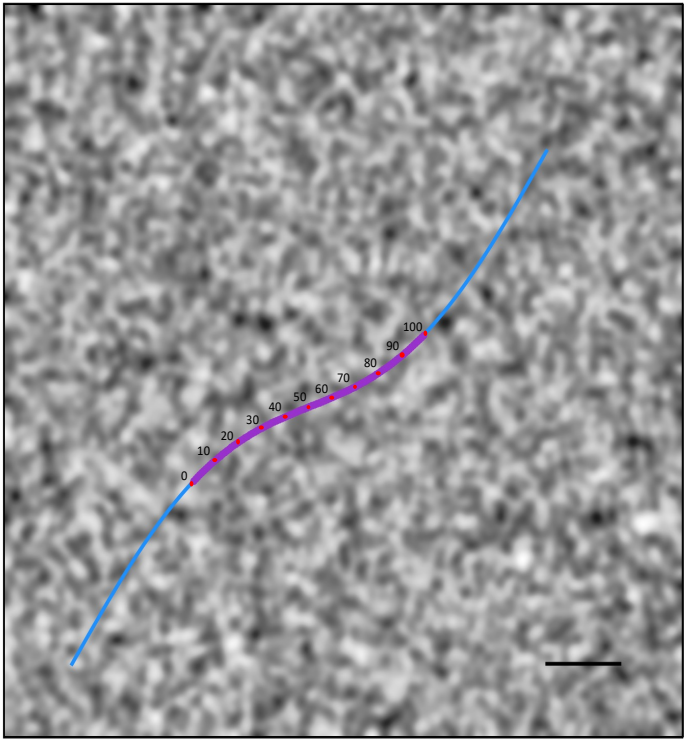


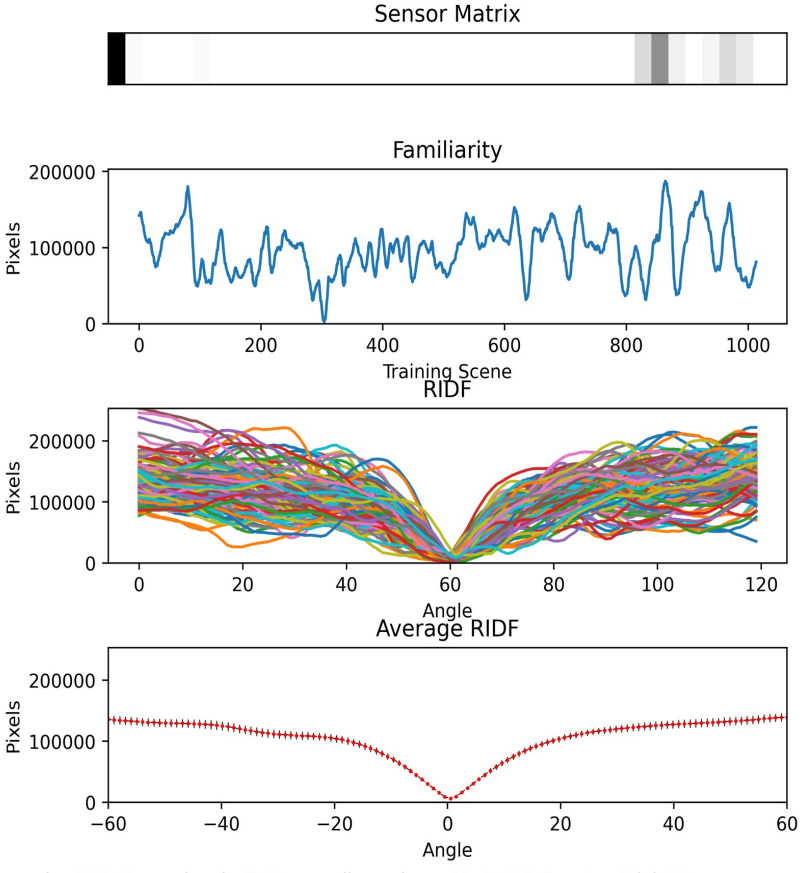
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 170.81; RMSD/dist: 0.427; TD: 84197; p90: 32; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 2; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

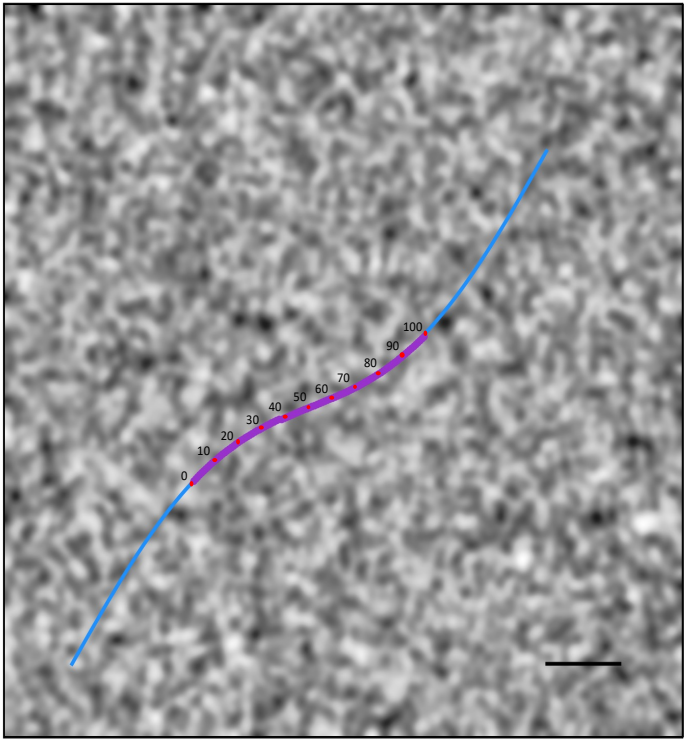


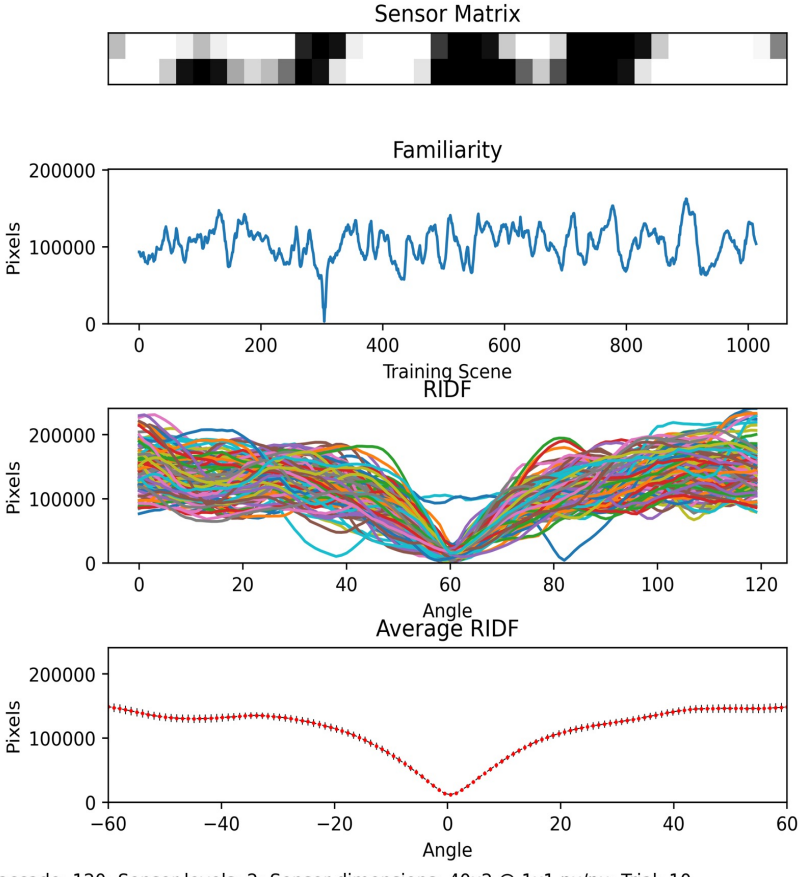


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 29.03; RMSD/dist: 0.073; TD: 94335; p90: 30; p50: 14; complete: 0

90%

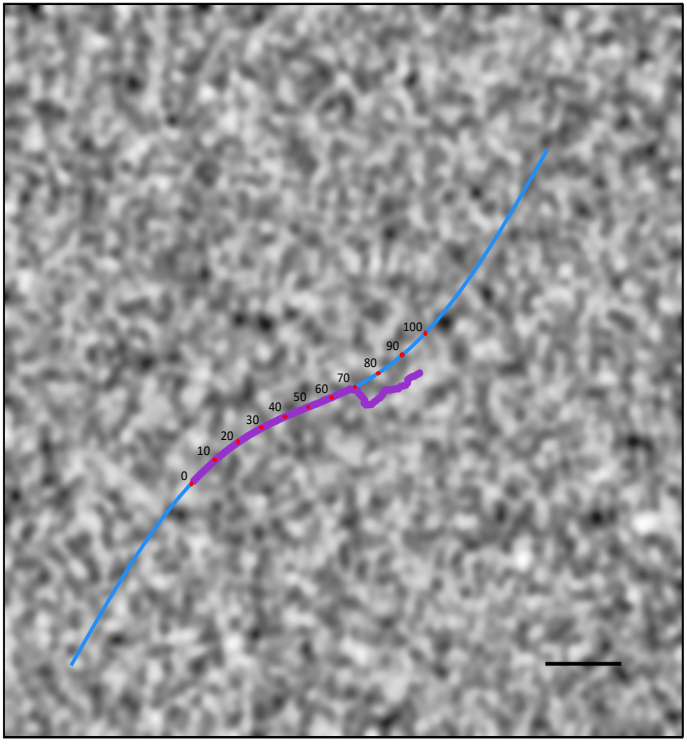


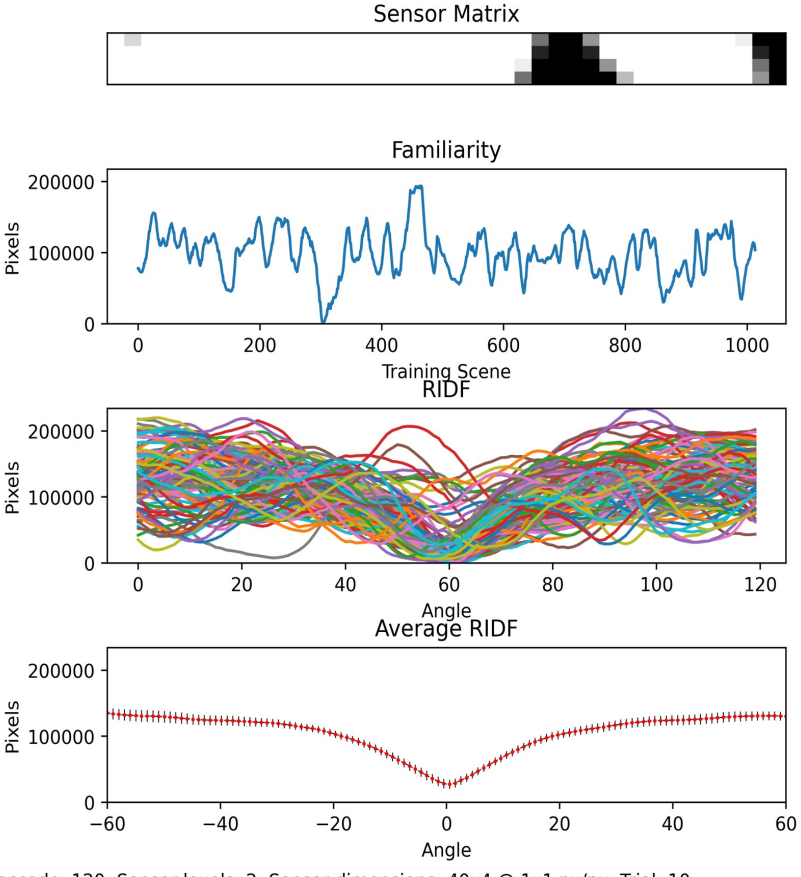


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 75.20; RMSD/dist: 0.188; TD: 92217; p90: 30; p50: 16; complete: 0

70%

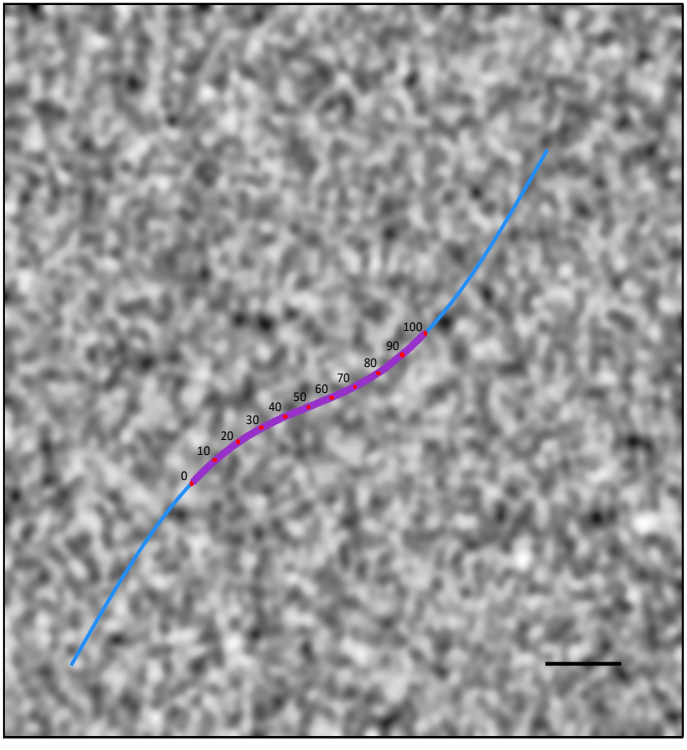


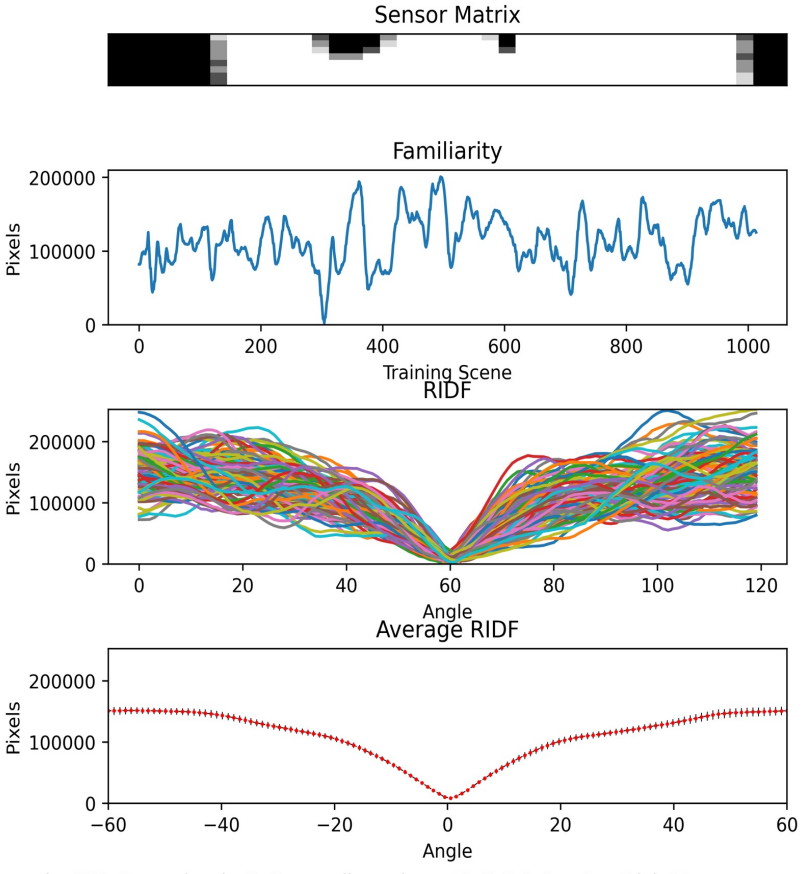


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 917.50; RMSD/dist: 2.294; TD: 73179; p90: 32; p50: 18; complete: 0

100%

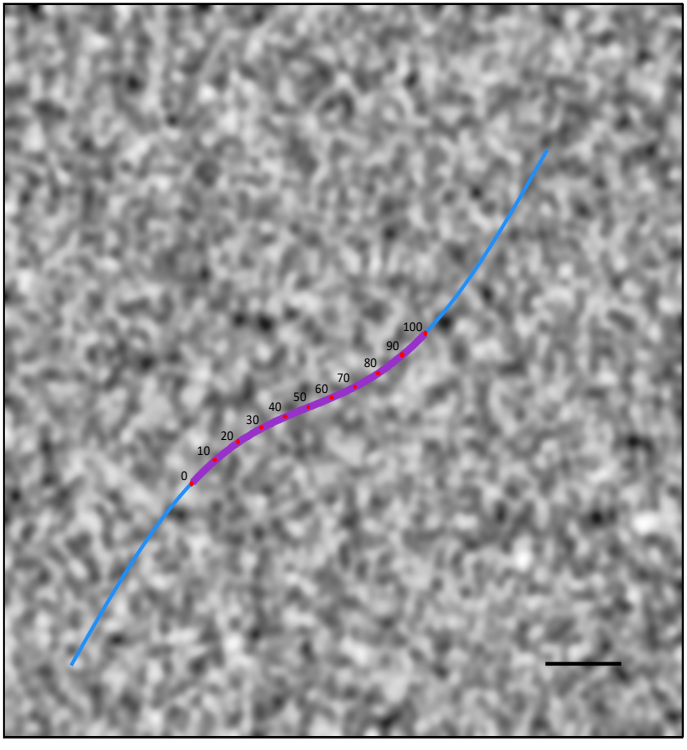


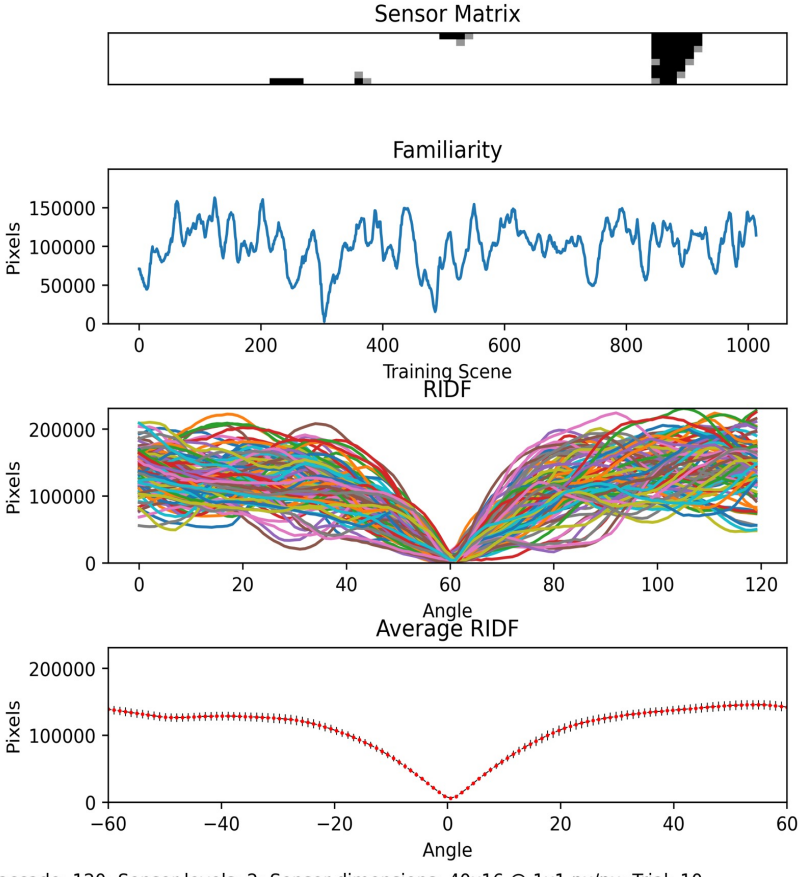


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 64.05; RMSD/dist: 0.160; TD: 97125; p90: 34; p50: 18; complete: 0

100%

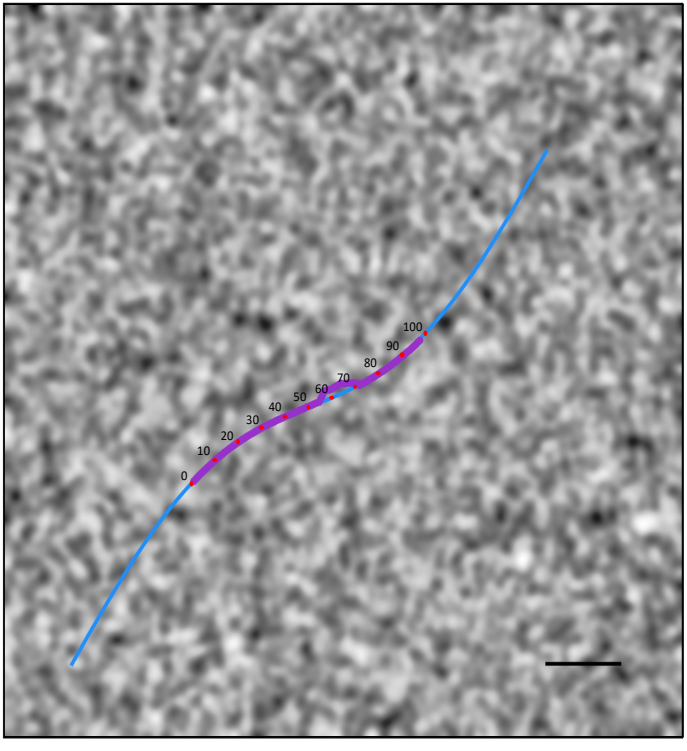


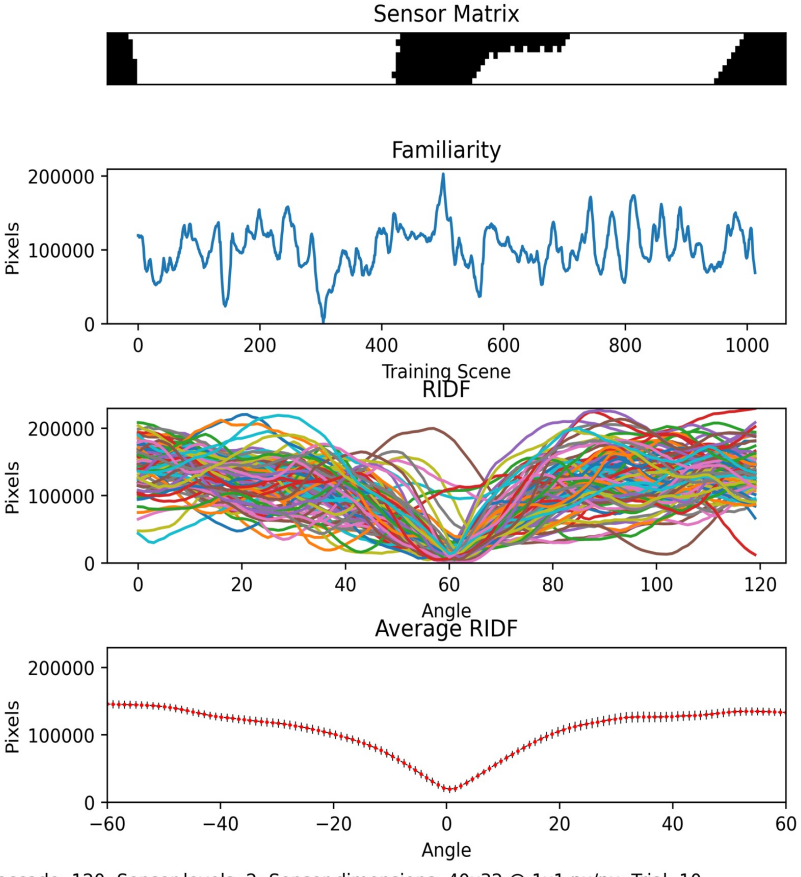


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 29.16; RMSD/dist: 0.073; TD: 98325; p90: 32; p50: 16; complete: 0

80%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 230.80; RMSD/dist: 0.577; TD: 88123; p90: 38; p50: 18; complete: 0