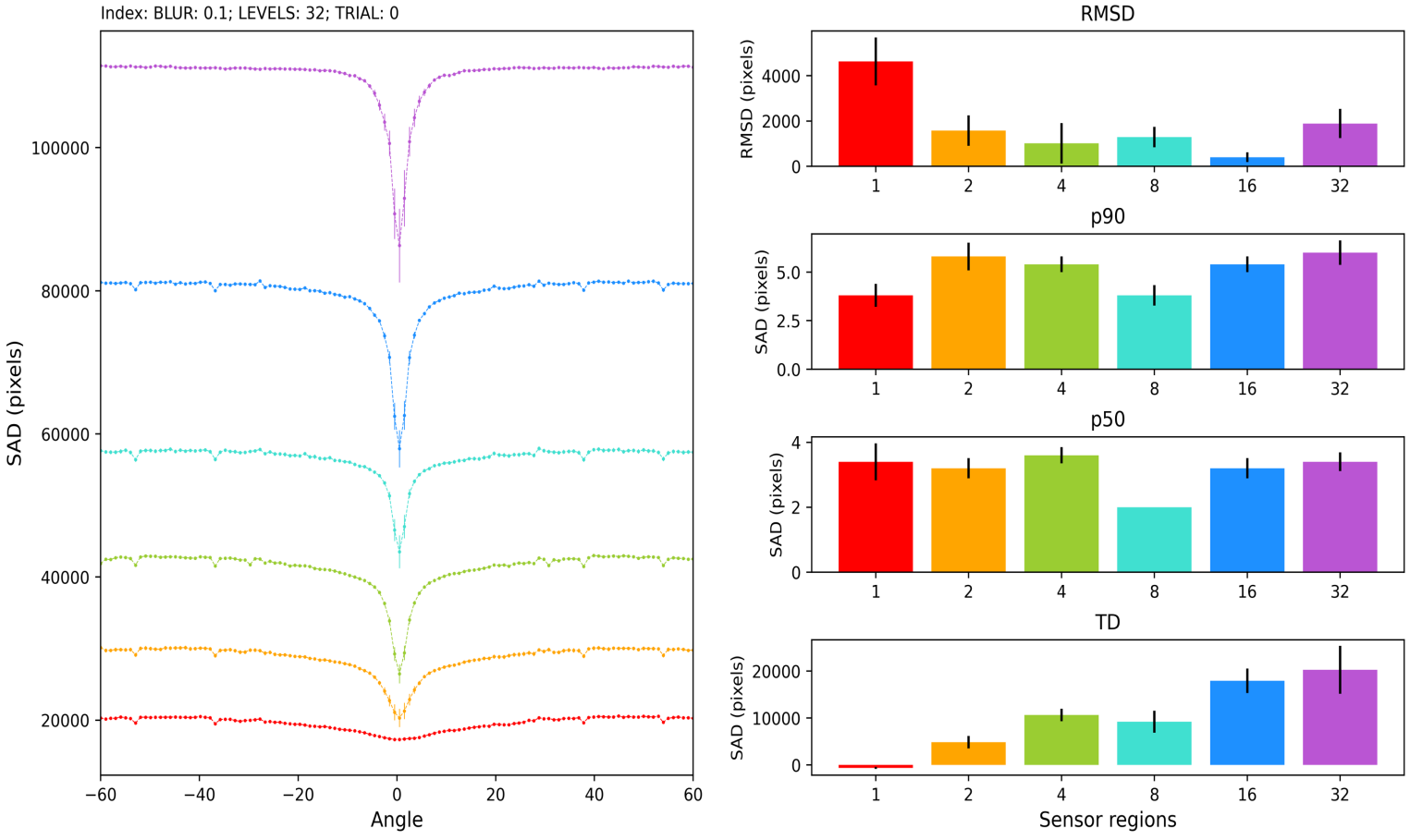
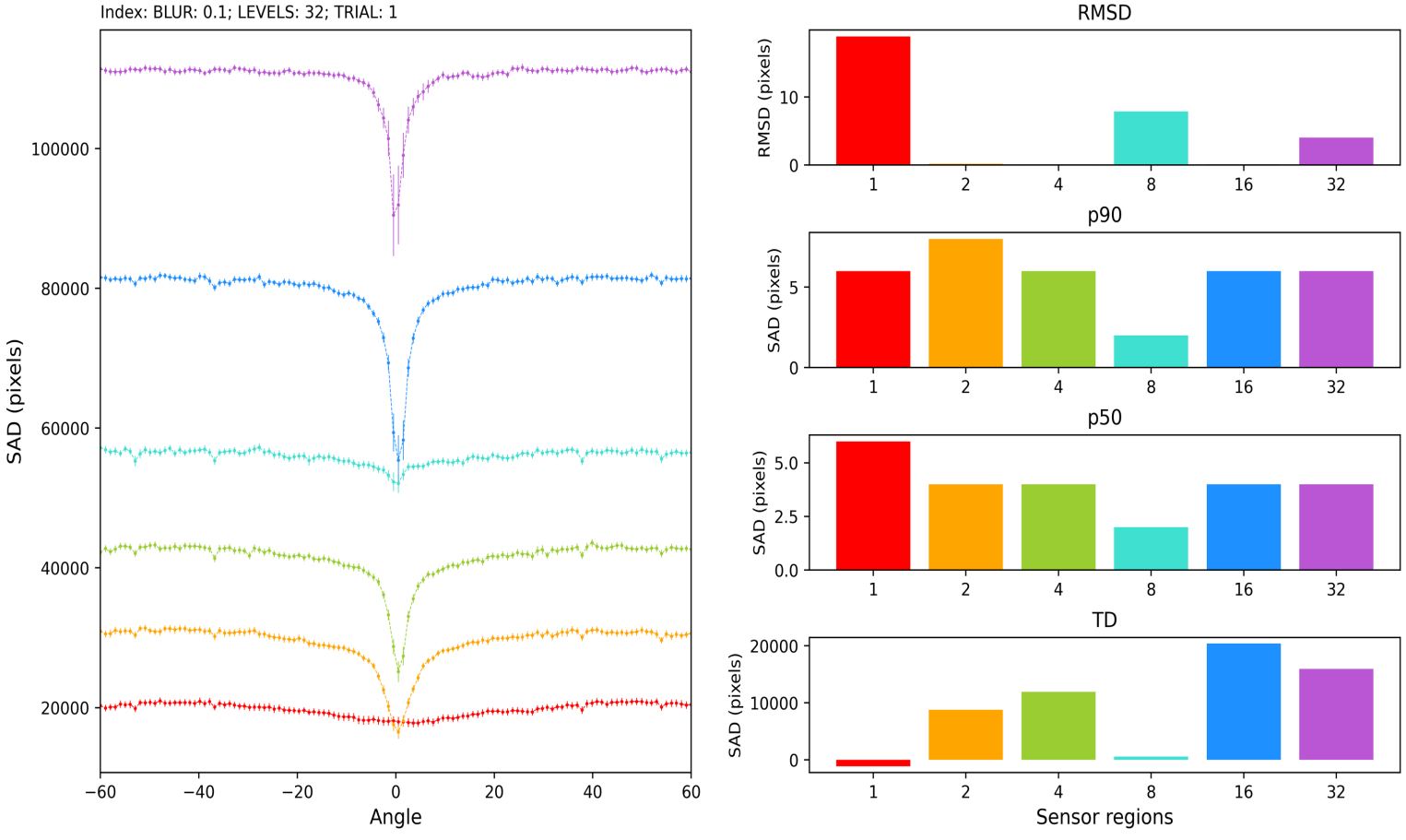
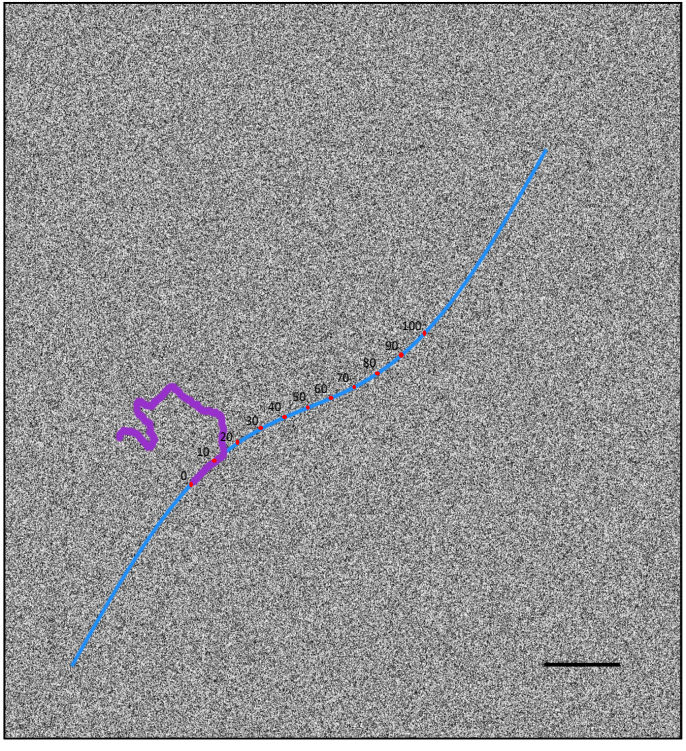
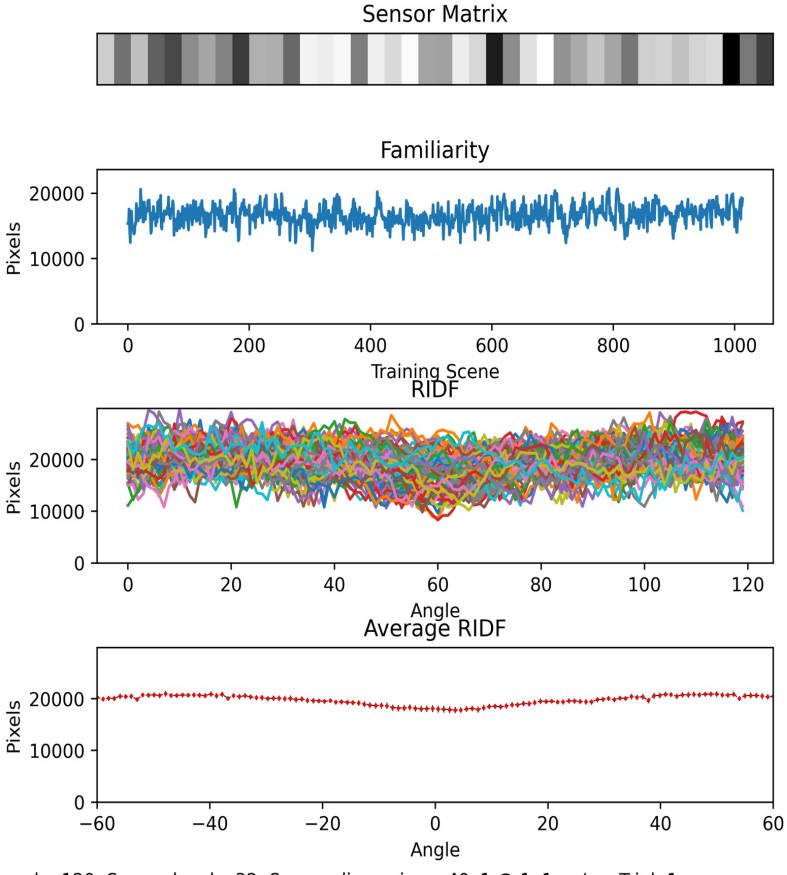

Index: BLUR: 0.1; LEVELS: 32; TRIAL: 0
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4000
2000
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
4
2
TD
20000
10000
Sensor regions


Index: BLUR: 0.1; LEVELS: 32; TRIAL: 1
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

10%

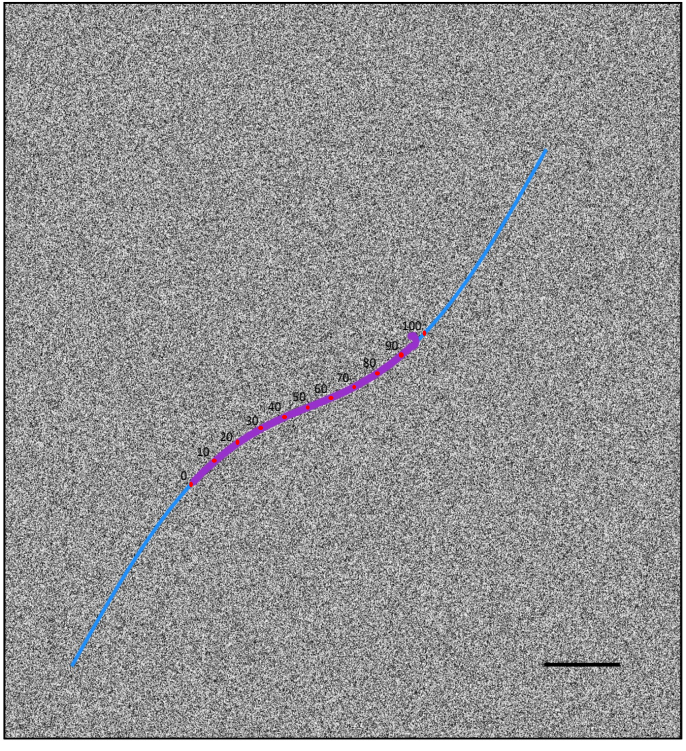


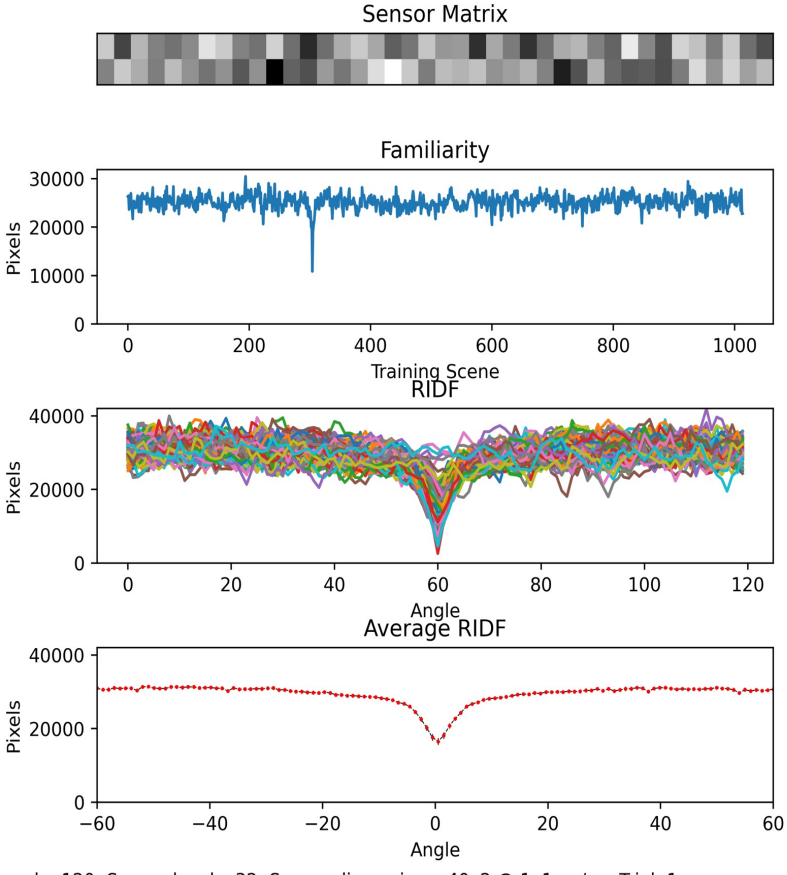


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 7565.09; RMSD/dist: 18.913; TD: -1147; p90: 6; p50: 6; complete: 0

90%

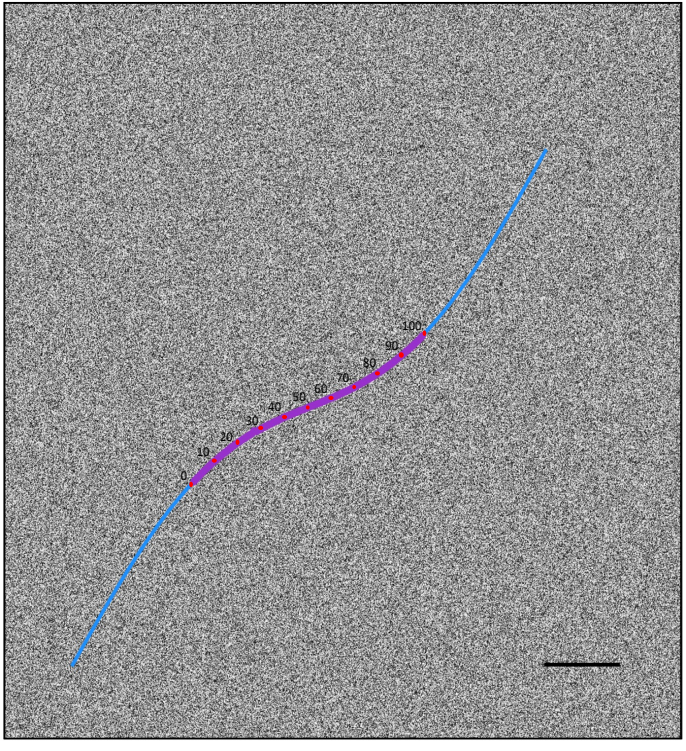


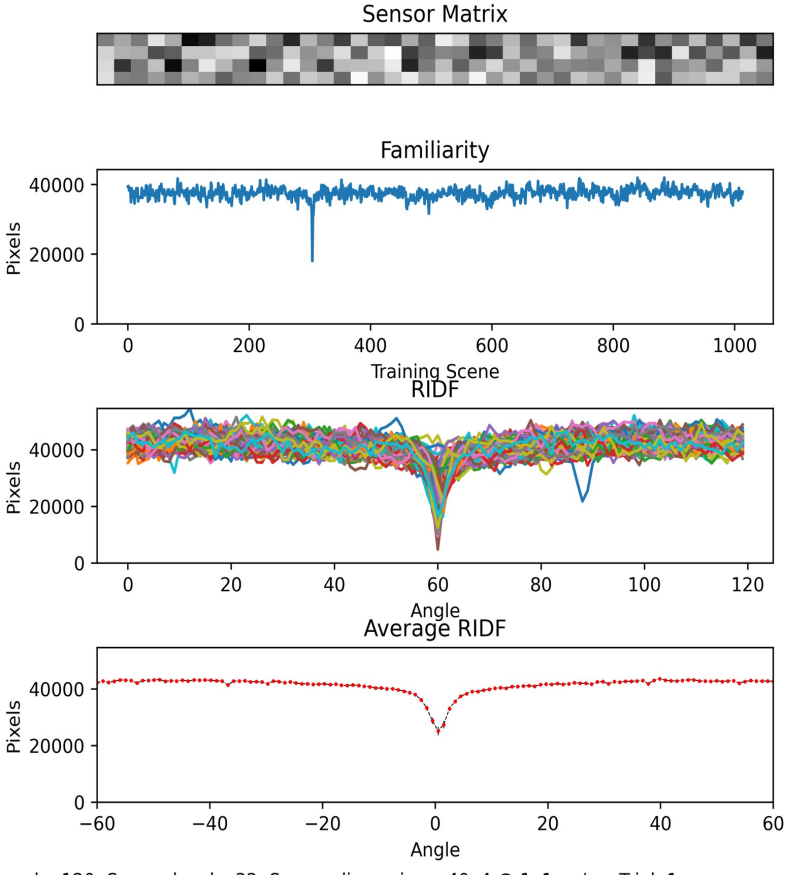


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 71.41; RMSD/dist: 0.179; TD: 8771; p90: 8; p50: 4; complete: 0

100%

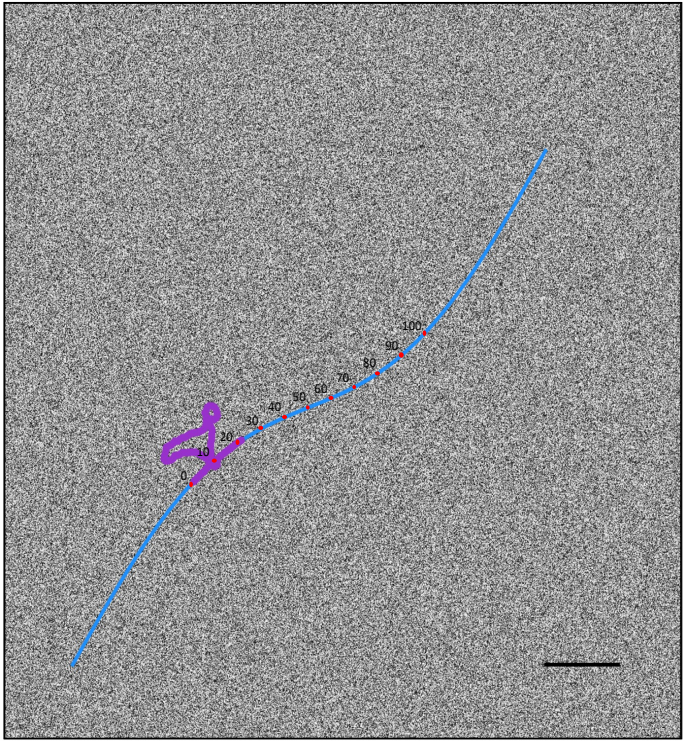


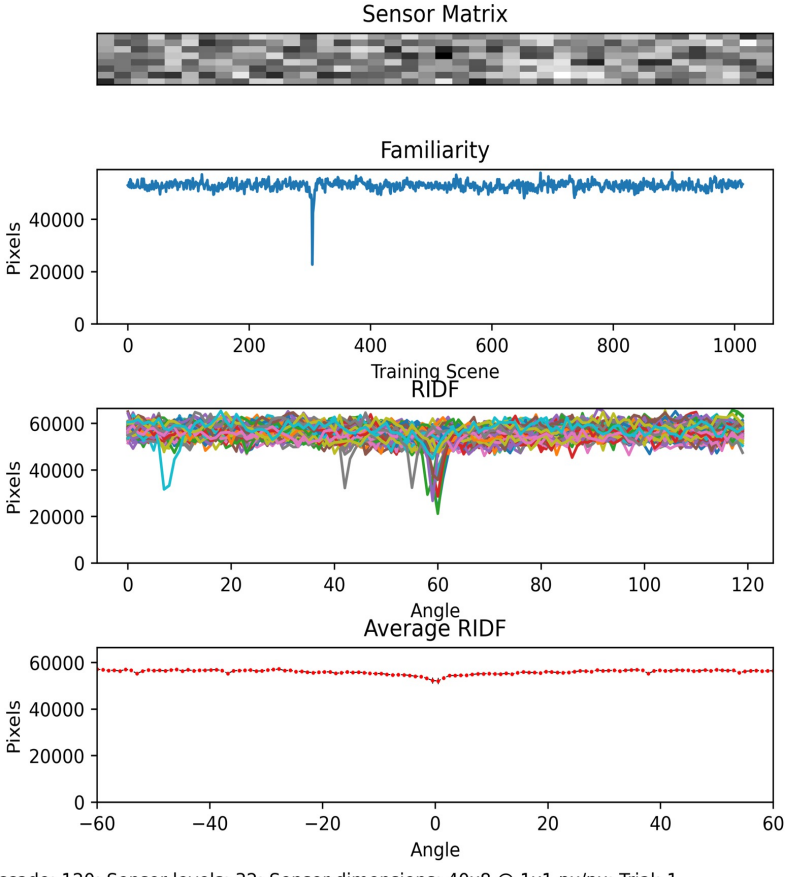


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 37.19; RMSD/dist: 0.093; TD: 11920; p90: 6; p50: 4; complete: 0

20%

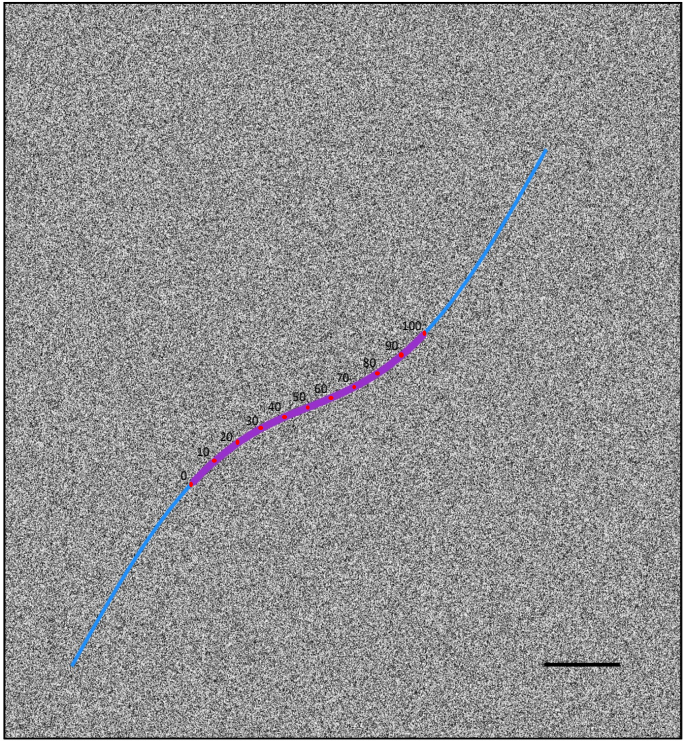


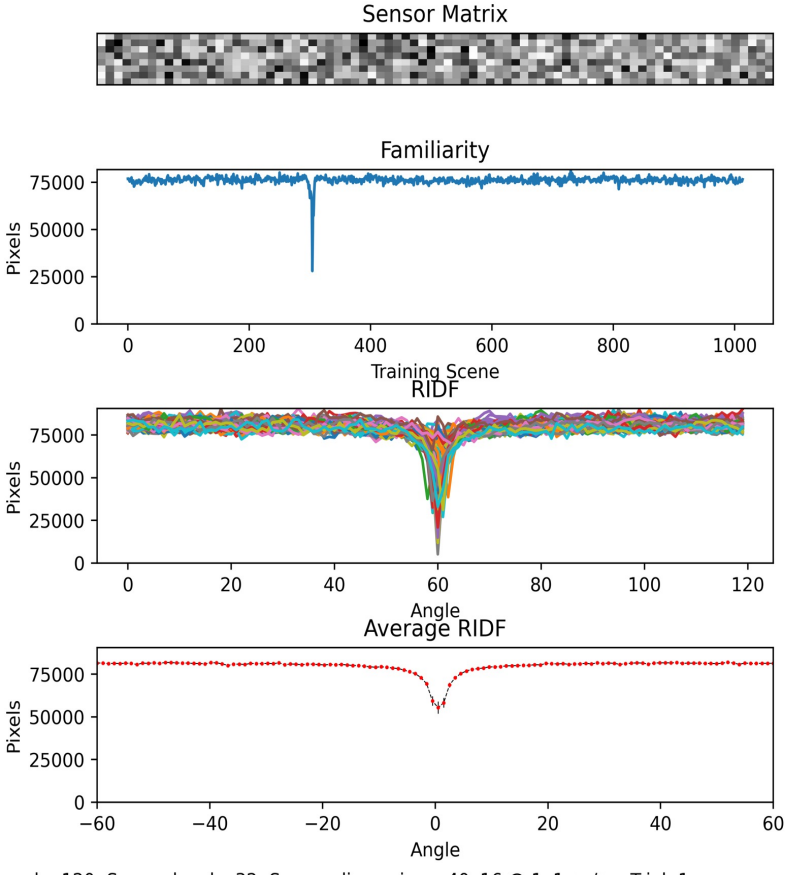


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3151.82; RMSD/dist: 7.880; TD: 558; p90: 2; p50: 2; complete: 0

100%

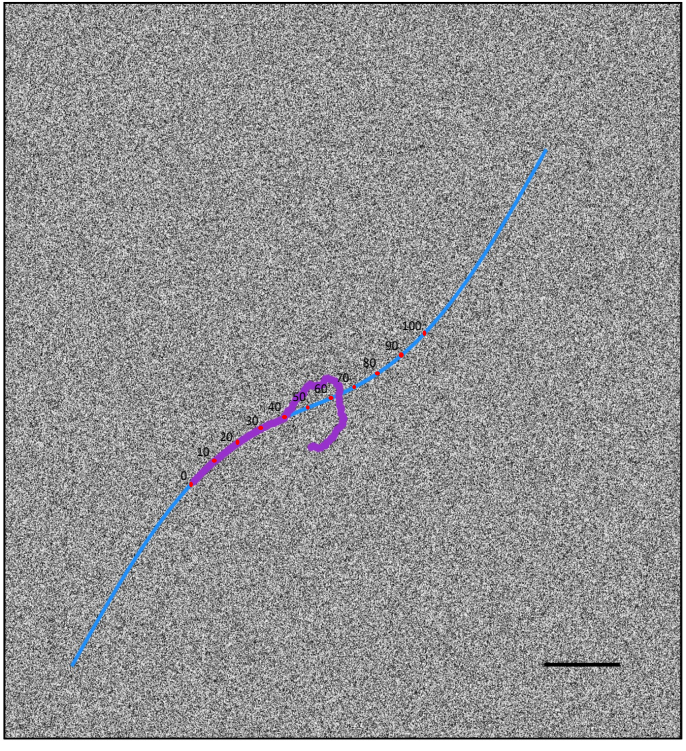


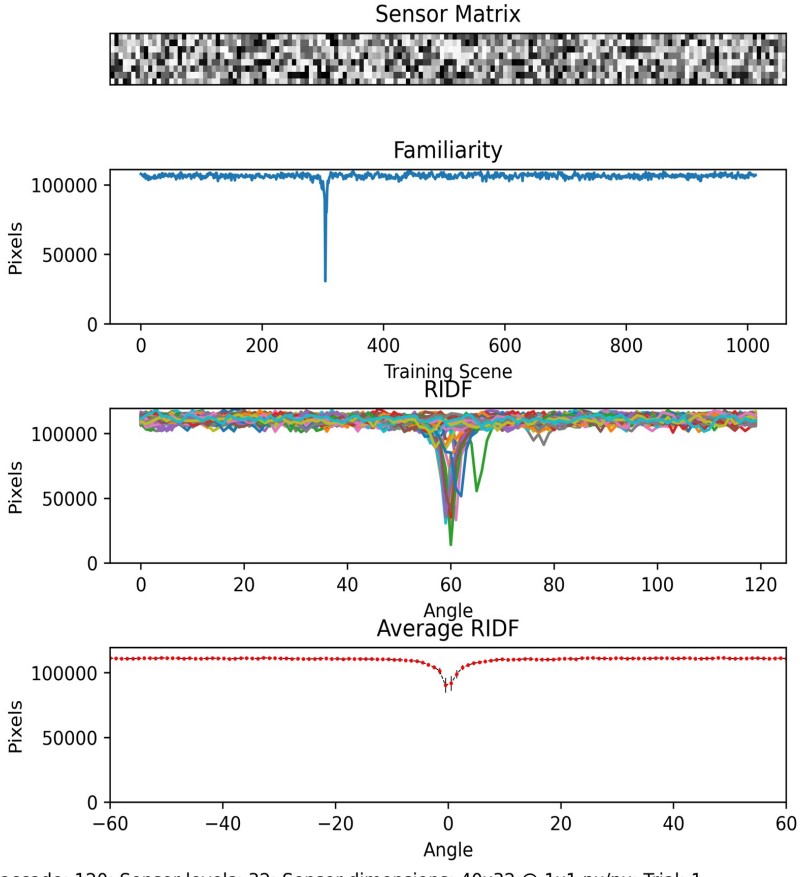


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 44.47; RMSD/dist: 0.111; TD: 20382; p90: 6; p50: 4; complete: 0

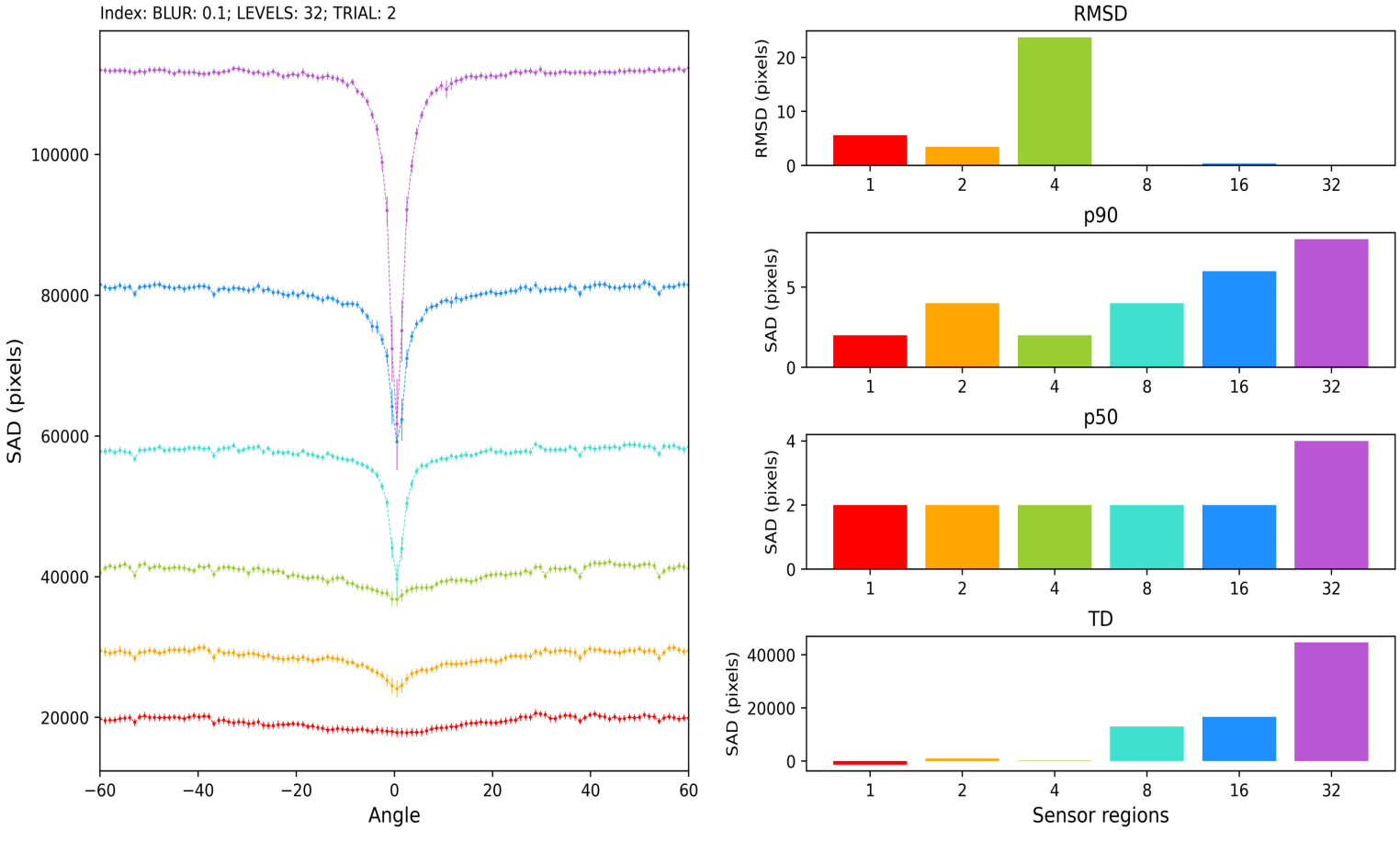
40%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1608.96; RMSD/dist: 4.022; TD: 15948; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 32; TRIAL: 2
SAD (pixels)
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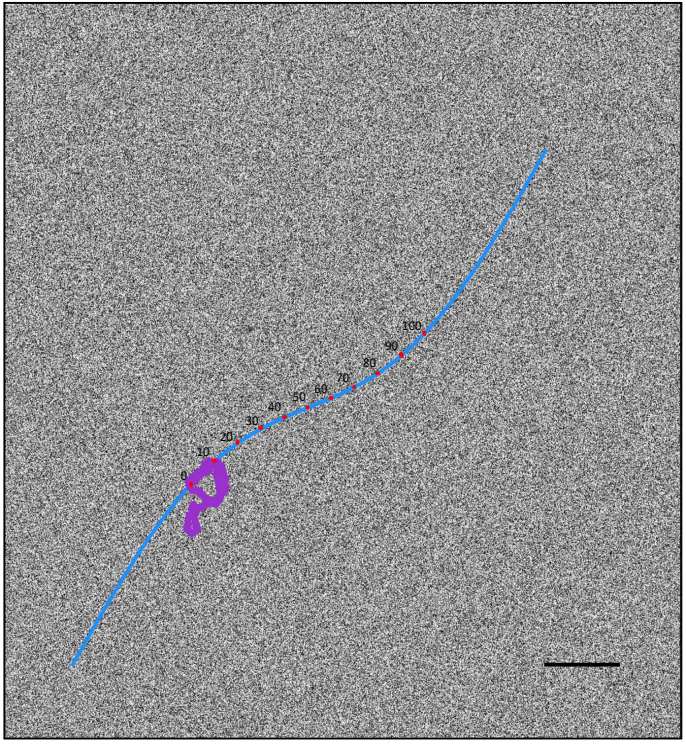
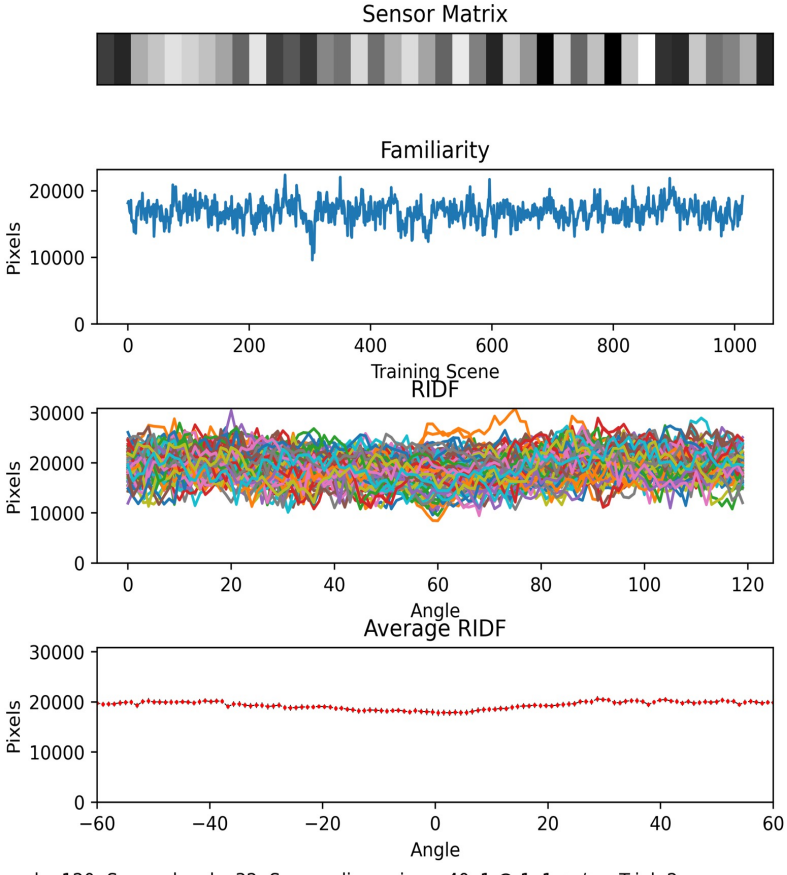
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
4
2
0
TD
SAD (pixels)
40000
20000
0
Sensor regions

10%

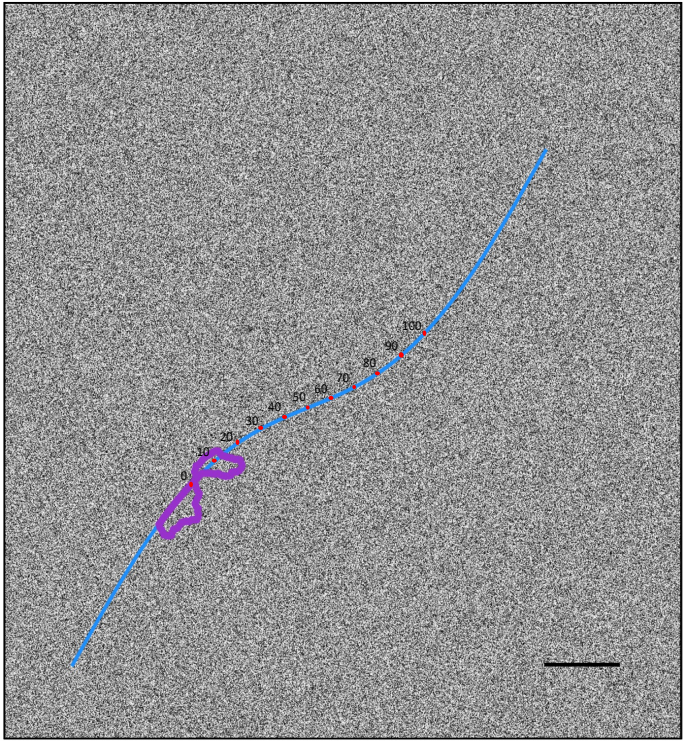


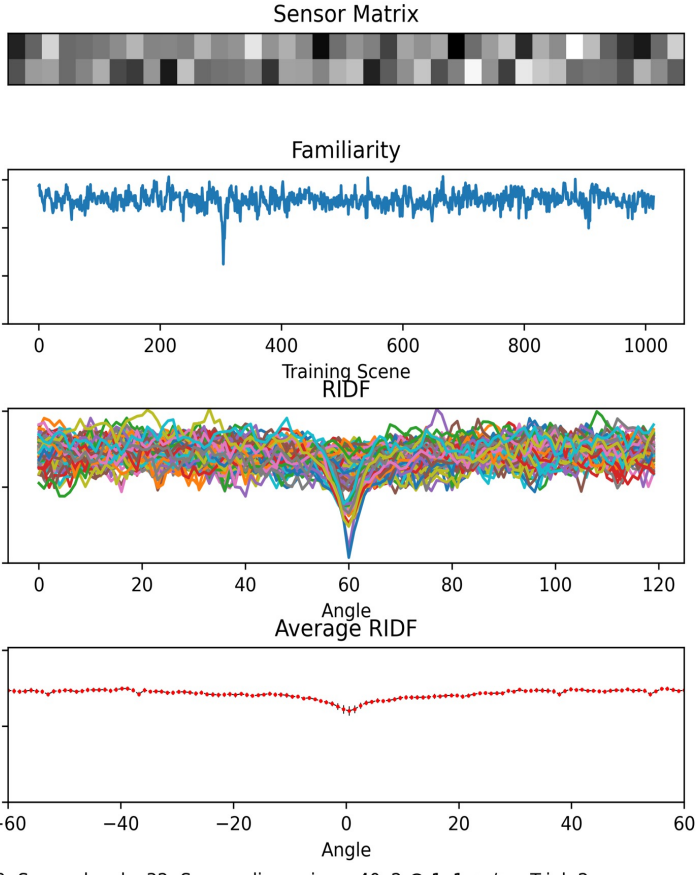


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2248.61; RMSD/dist: 5.622; TD: -1418; p90: 2; p50: 2; complete: 0

0%

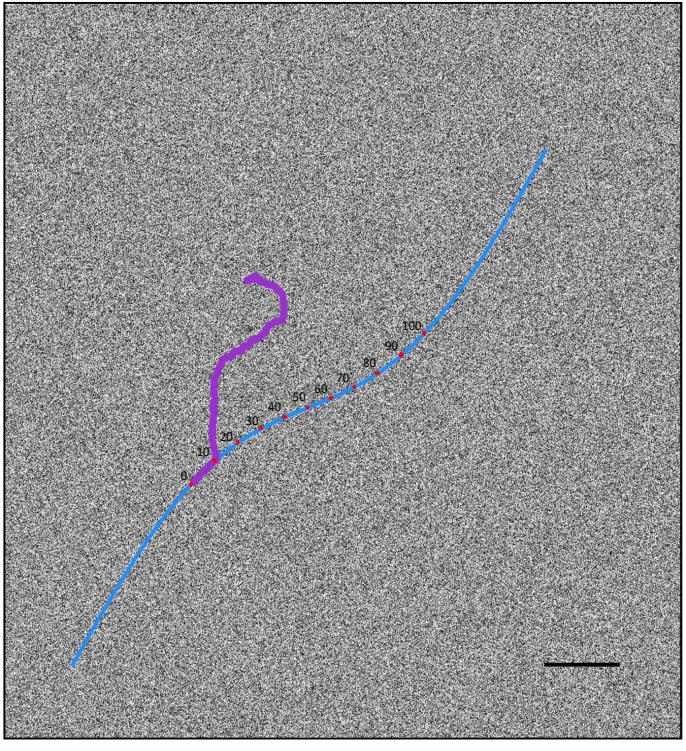


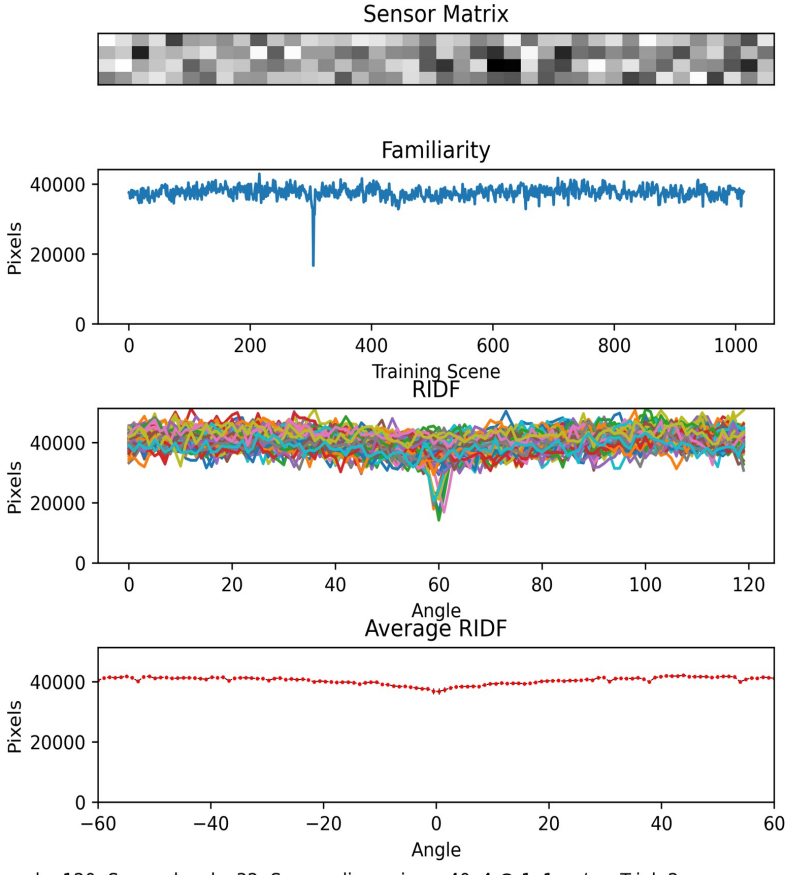


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1368.15; RMSD/dist: 3.420; TD: 950; p90: 4; p50: 2; complete: 0

10%

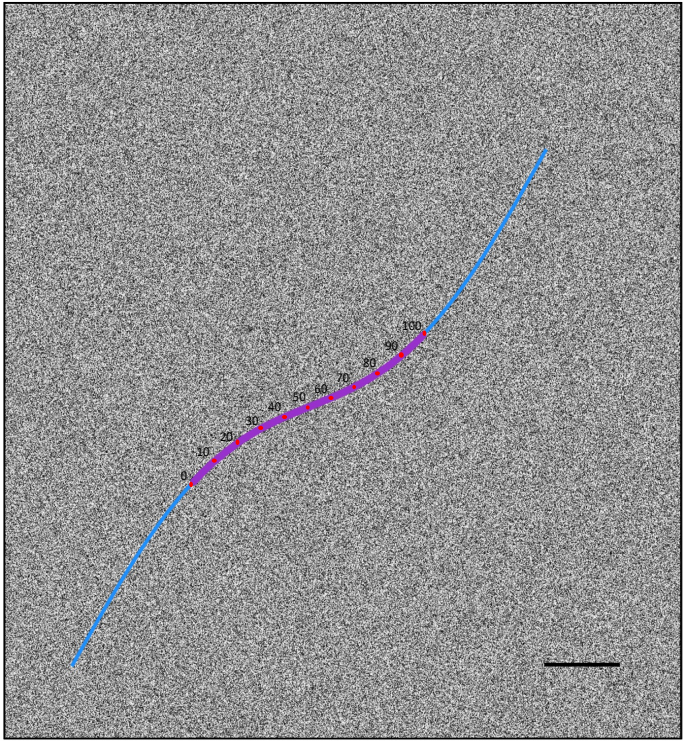


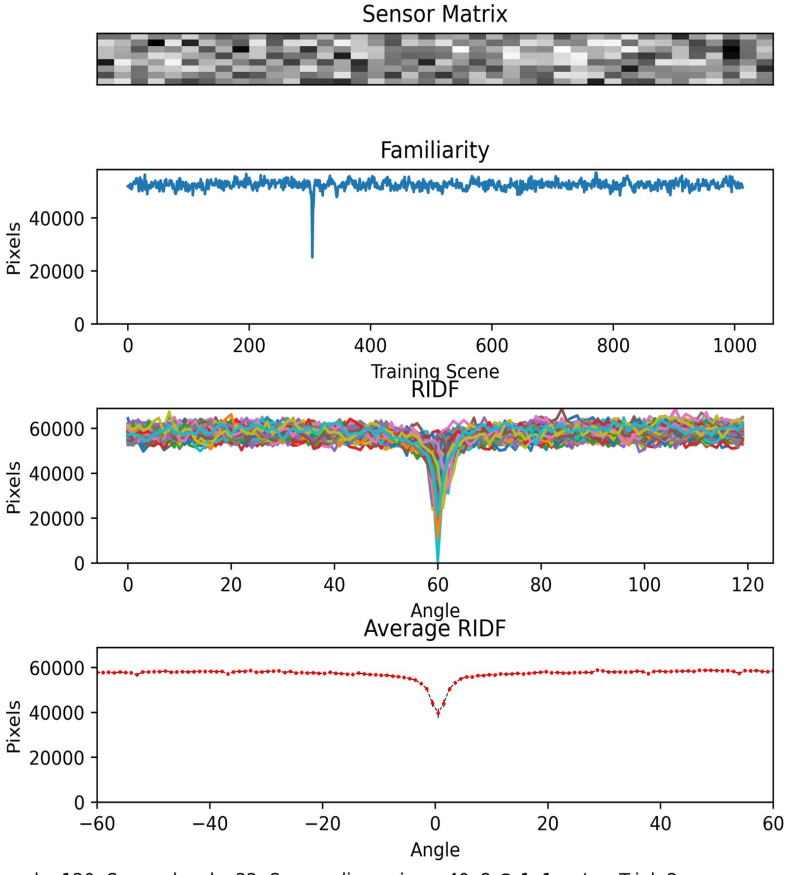


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 9490.70; RMSD/dist: 23.727; TD: 168; p90: 2; p50: 2; complete: 0

100%

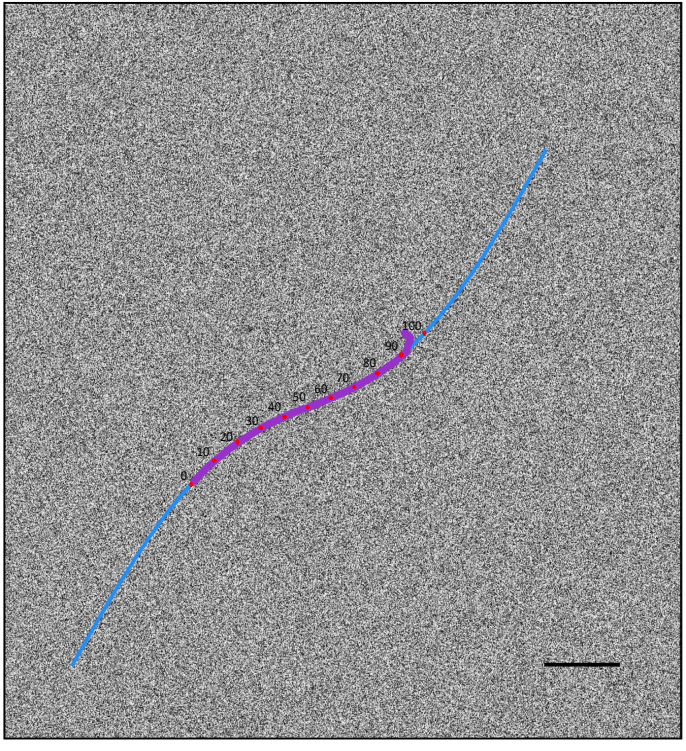


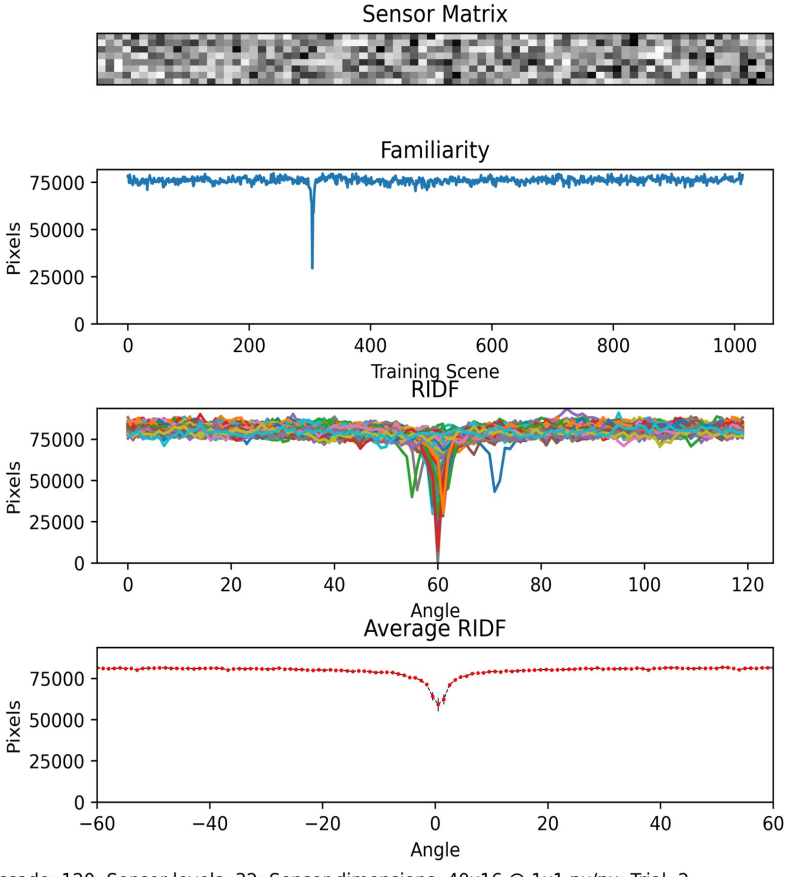


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 50.66; RMSD/dist: 0.127; TD: 13018; p90: 4; p50: 2; complete: 0

90%

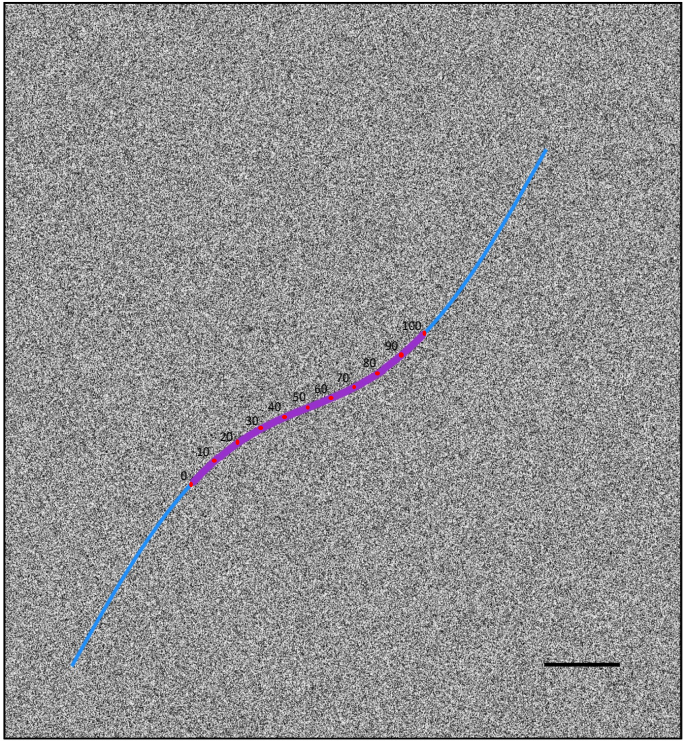


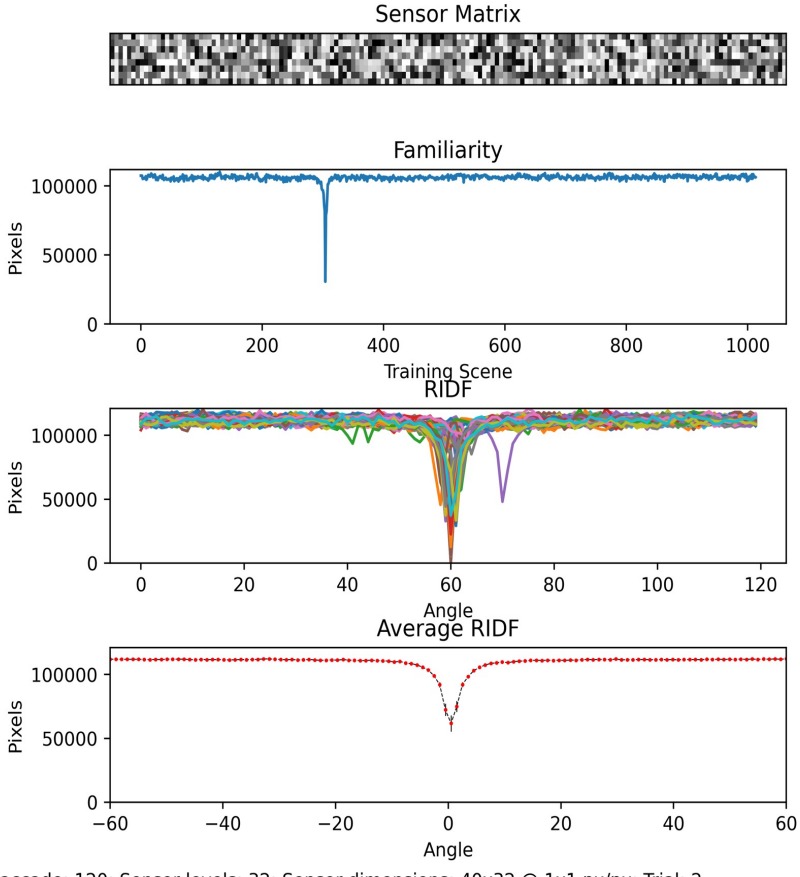


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 139.29; RMSD/dist: 0.348; TD: 16617; p90: 6; p50: 2; complete: 0

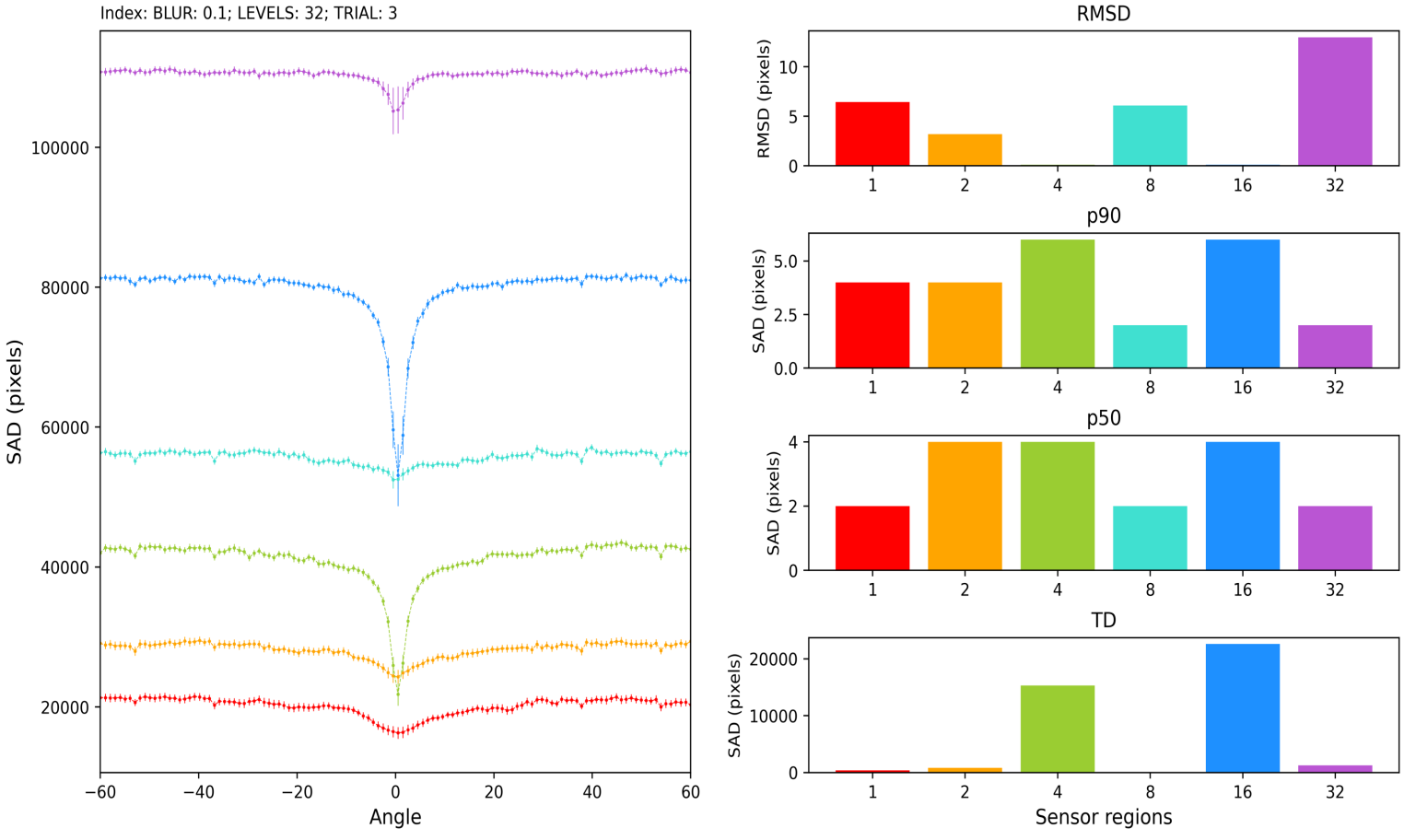
100%



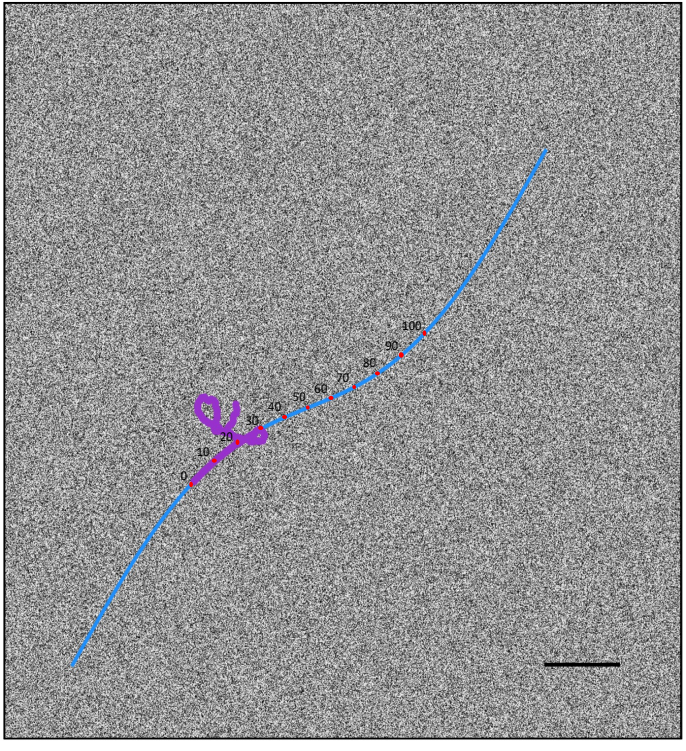


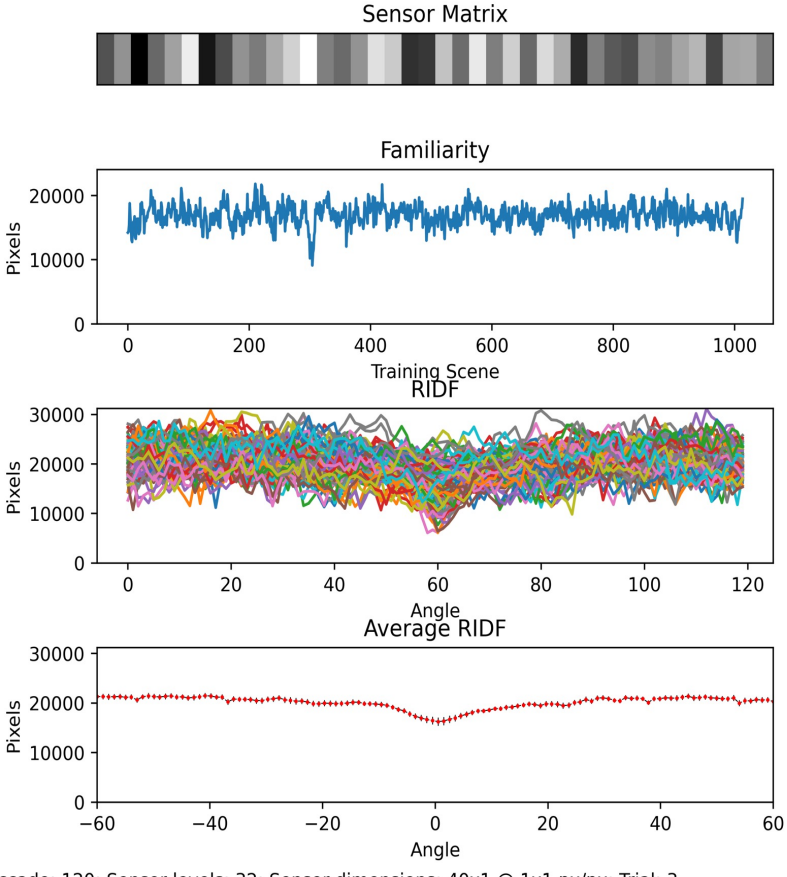
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 41.34; RMSD/dist: 0.103; TD: 44677; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 32; TRIAL: 3
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
4
2
TD
20000
10000
Sensor regions

30%

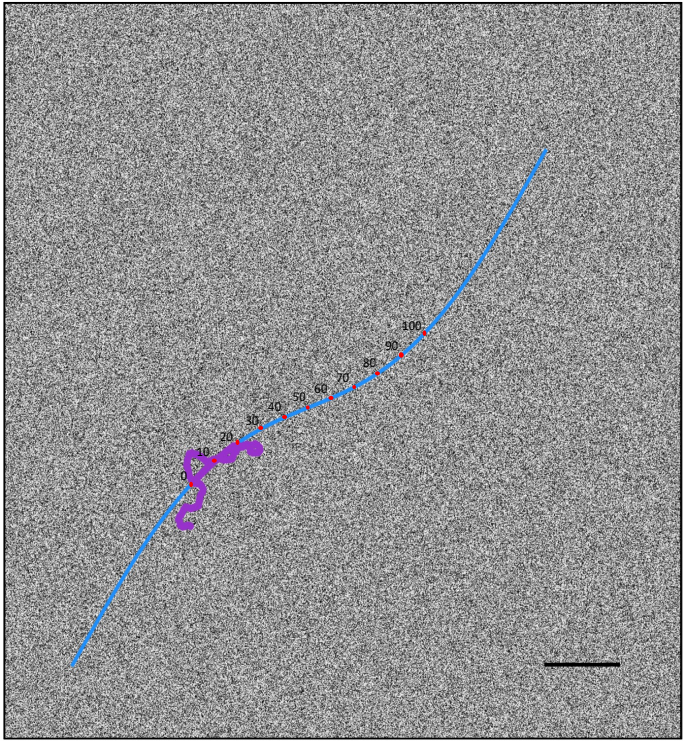


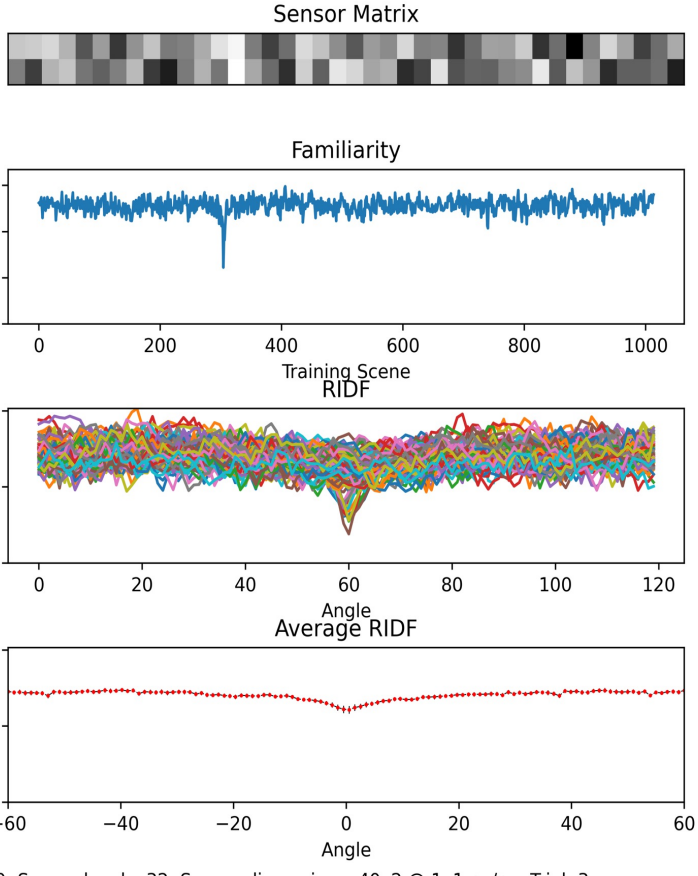


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2570.58; RMSD/dist: 6.426; TD: 393; p90: 4; p50: 2; complete: 0

10%

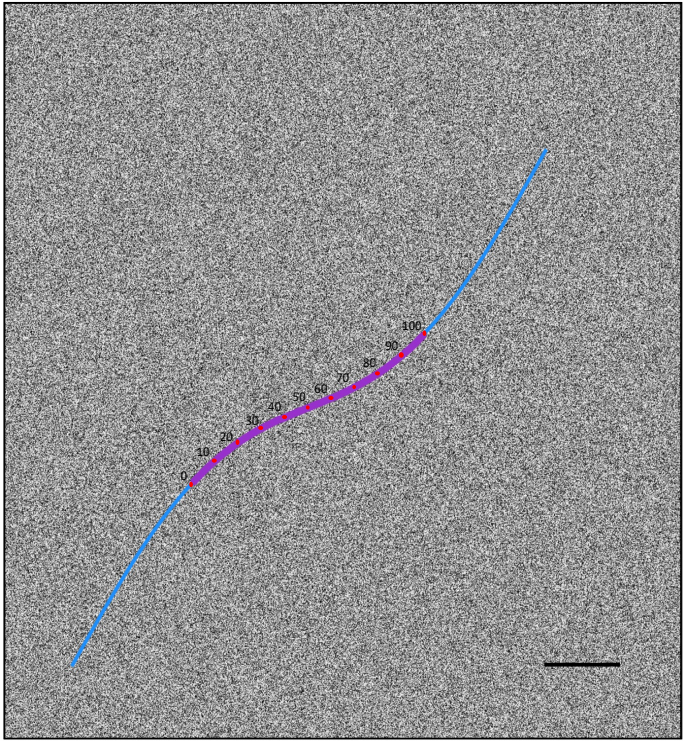


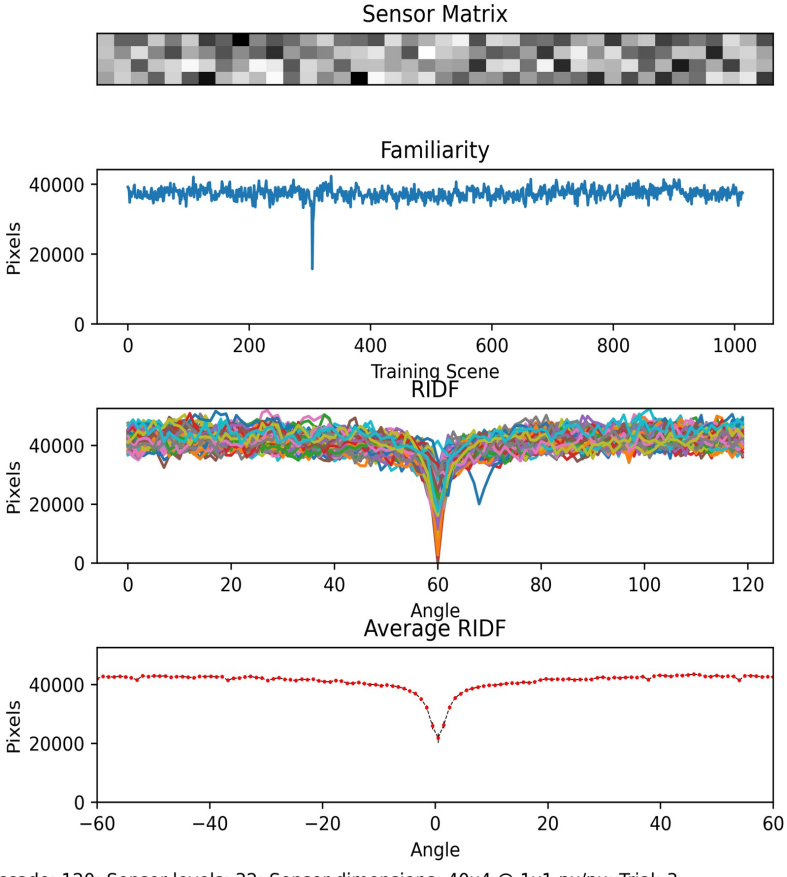


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1271.57; RMSD/dist: 3.179; TD: 827; p90: 4; p50: 4; complete: 0

100%

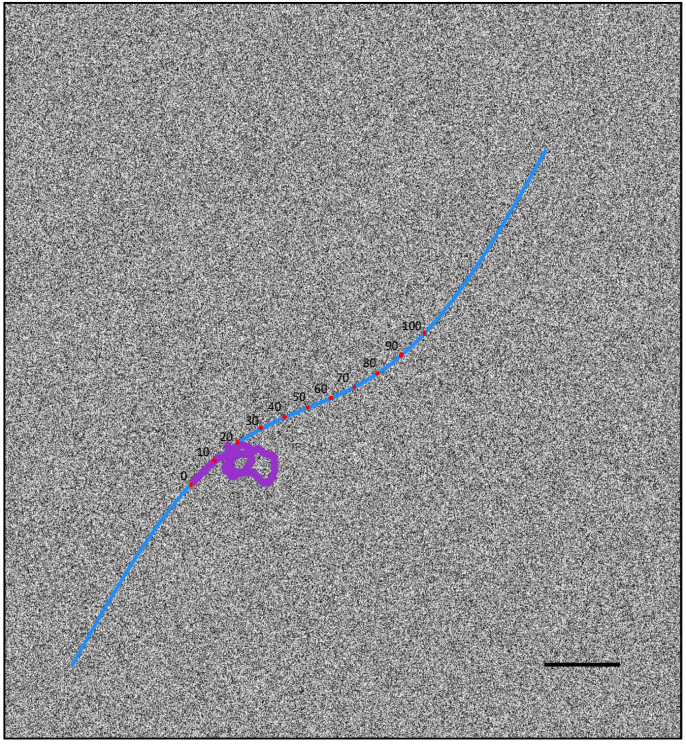


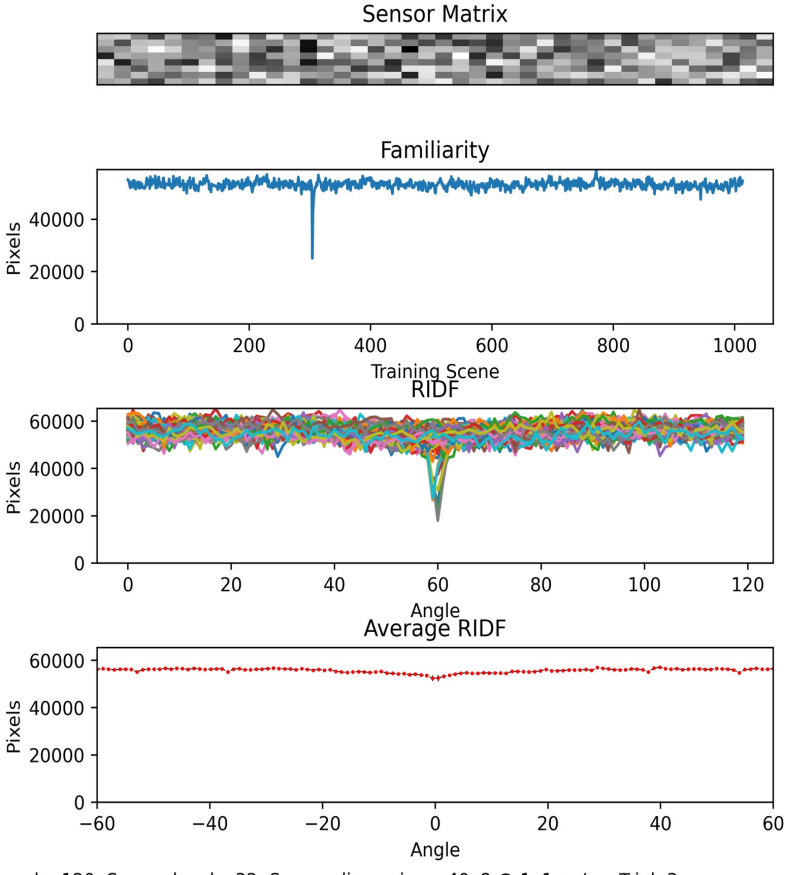


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 36.95; RMSD/dist: 0.092; TD: 15291; p90: 6; p50: 4; complete: 0

10%

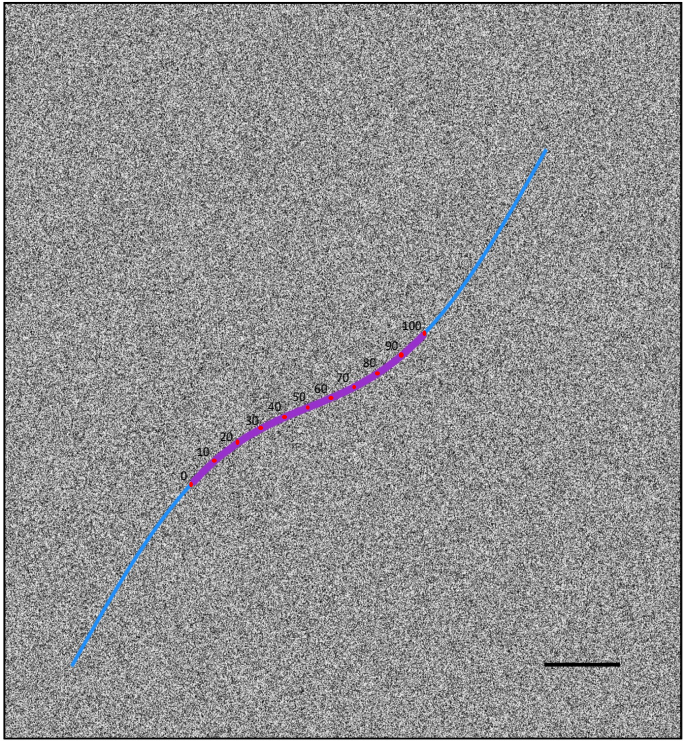


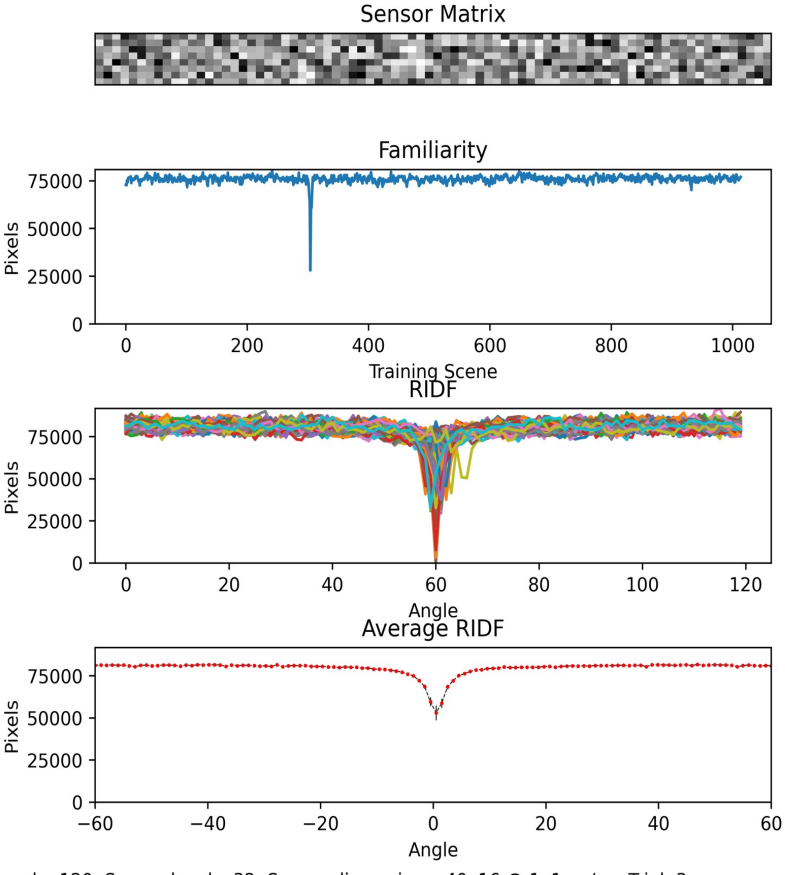


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2427.04; RMSD/dist: 6.068; TD: 2; p90: 2; p50: 2; complete: 0

100%

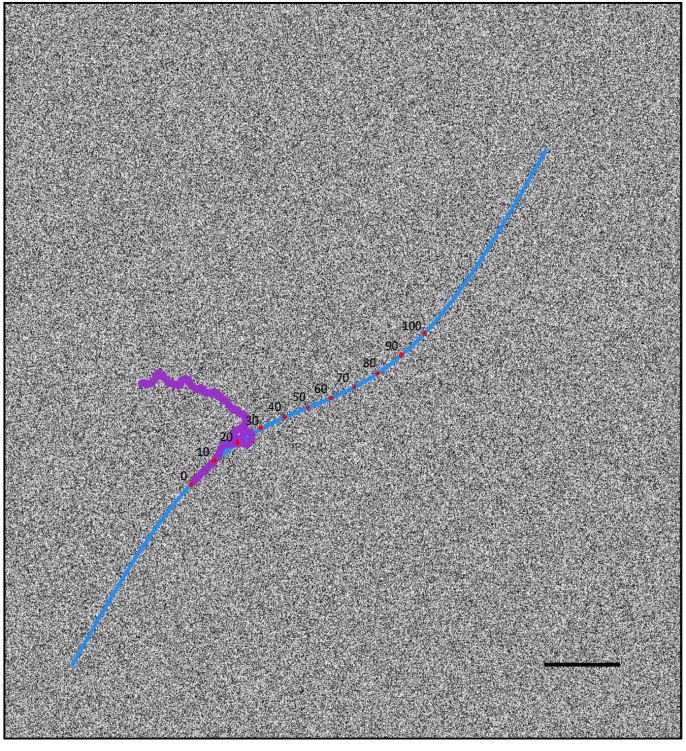


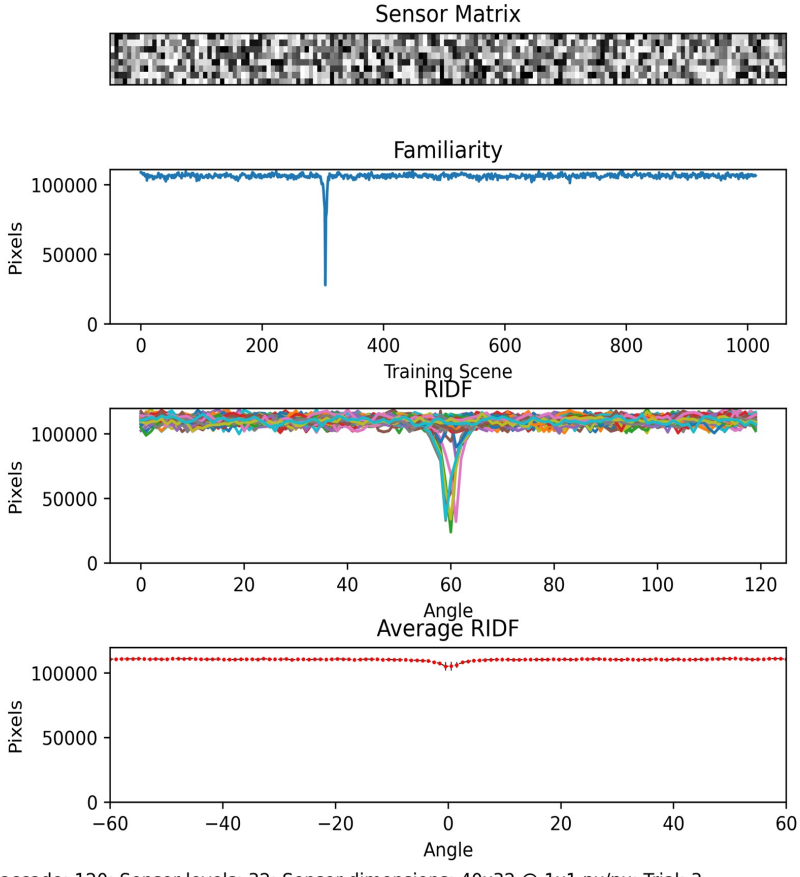


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 43.17; RMSD/dist: 0.108; TD: 22590; p90: 6; p50: 4; complete: 0

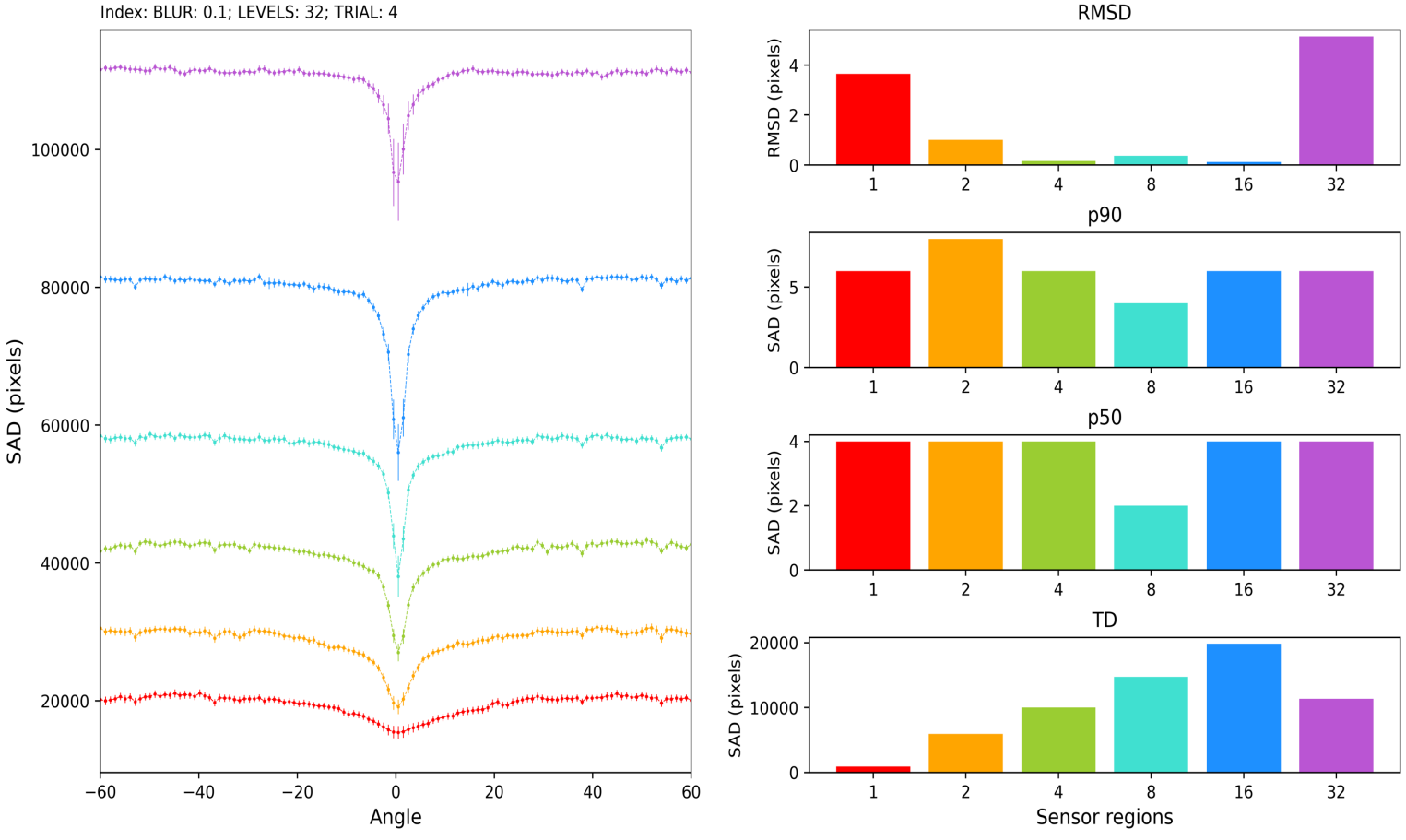
10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 5186.42; RMSD/dist: 12.966; TD: 1254; p90: 2; p50: 2; complete: 0


Index: BLUR: 0.1; LEVELS: 32; TRIAL: 4
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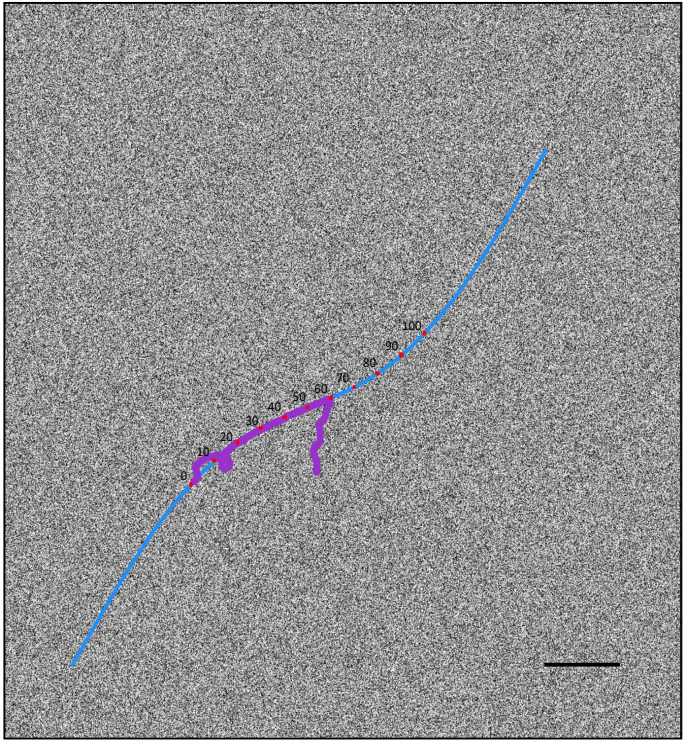
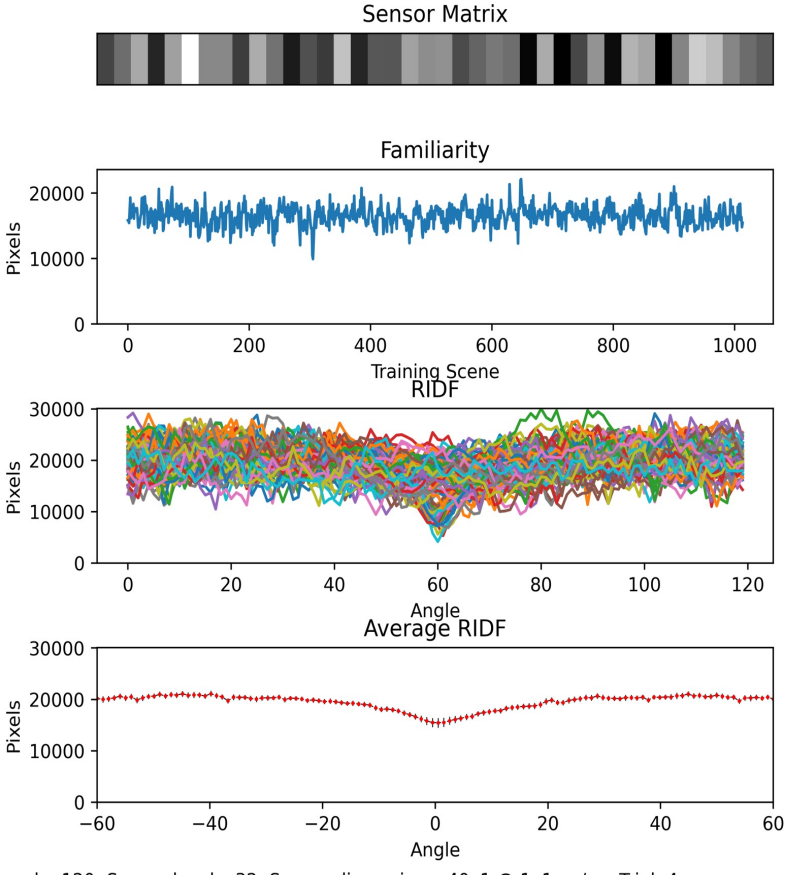
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0
2
4
1
2
4
8
16
32
p90
SAD (pixels)
0
5
1
2
4
8
16
32
p50
SAD (pixels)
0
2
4
1
2
4
8
16
32
TD
SAD (pixels)
0
10000
20000
1
2
4
8
16
32
Sensor regions

40%

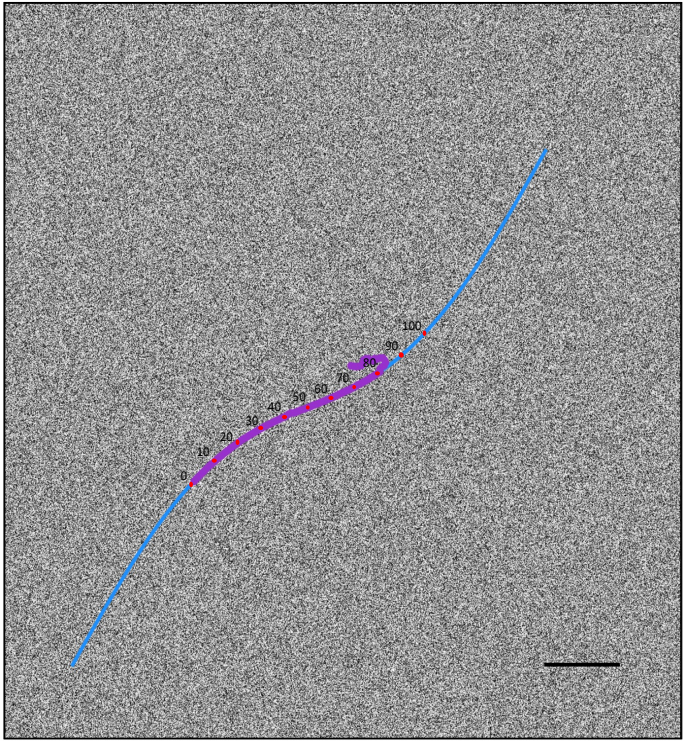


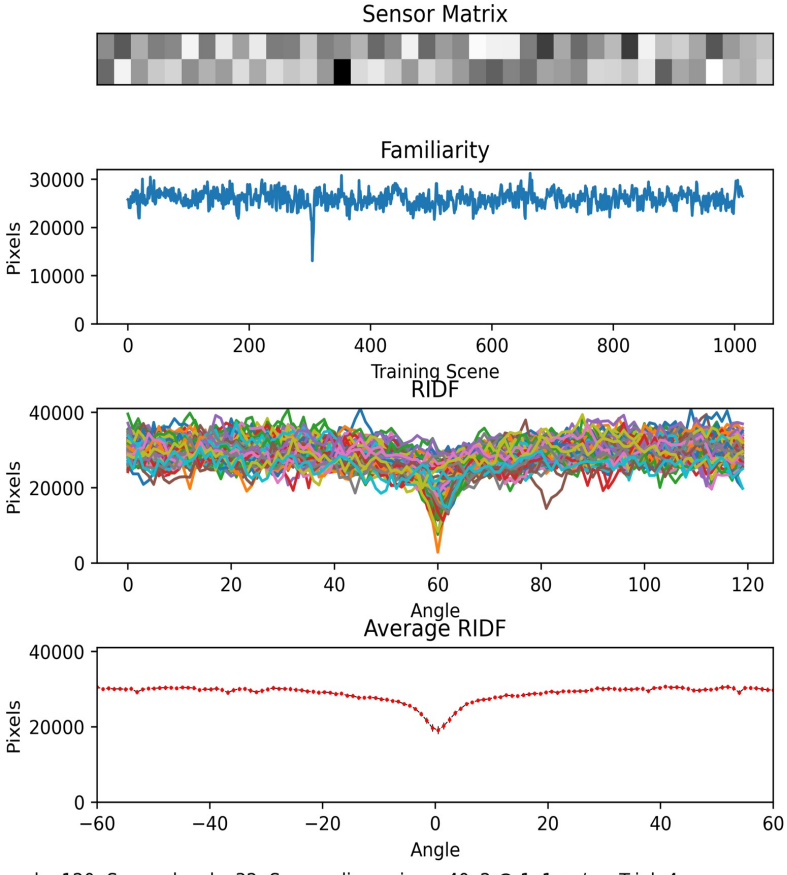


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1460.71; RMSD/dist: 3.652; TD: 923; p90: 6; p50: 4; complete: 0

80%

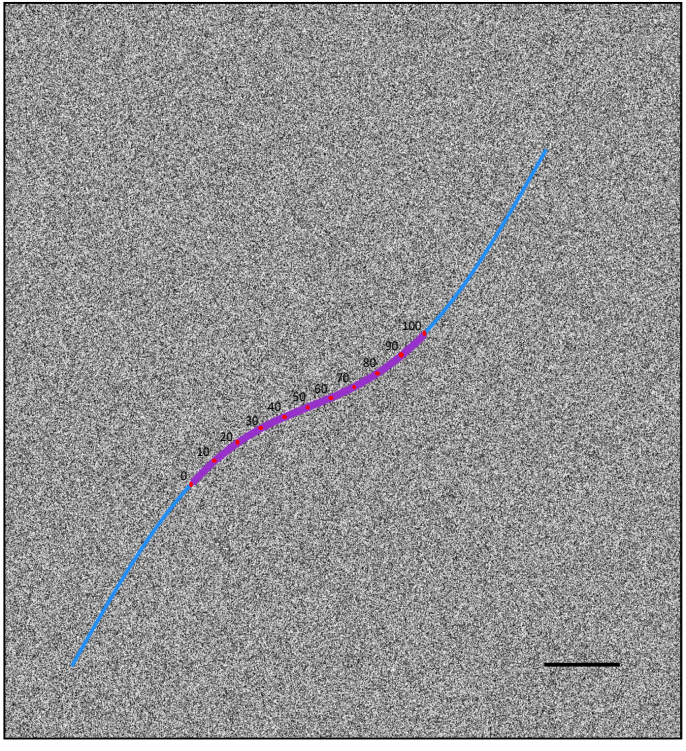


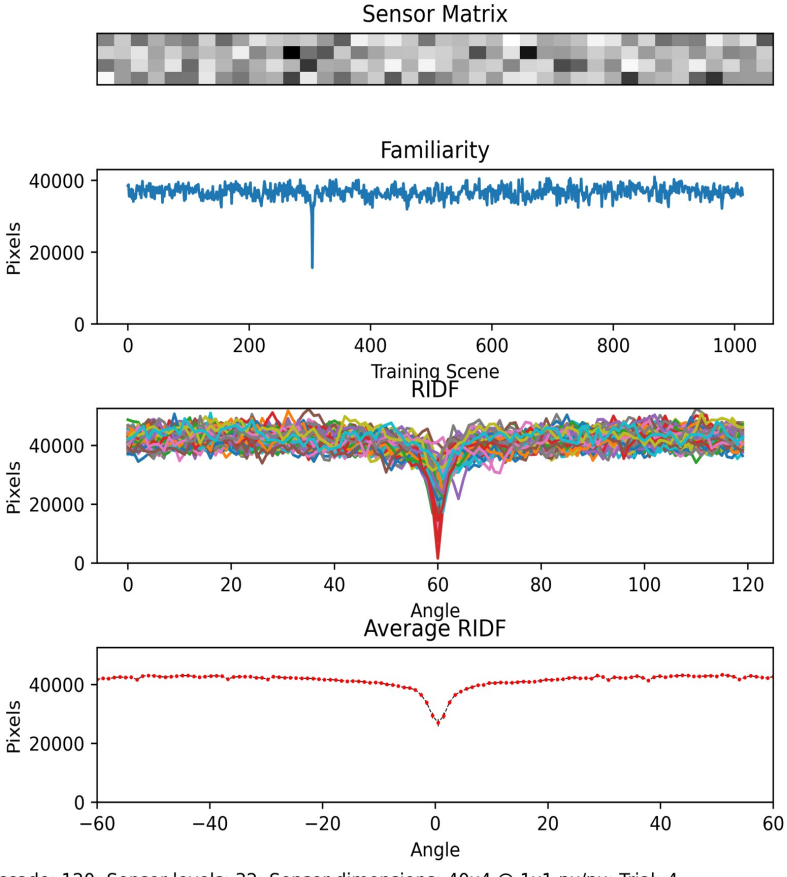


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 403.06; RMSD/dist: 1.008; TD: 5920; p90: 8; p50: 4; complete: 0

100%

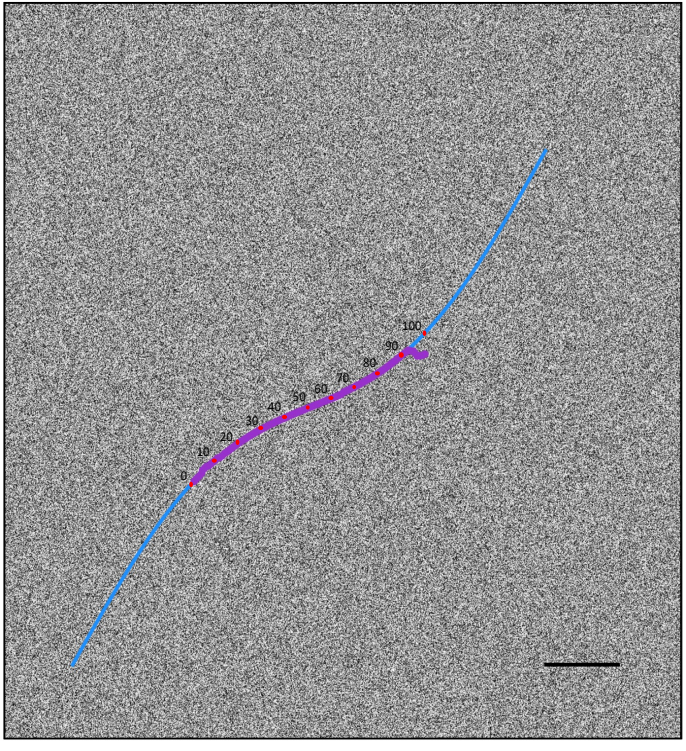


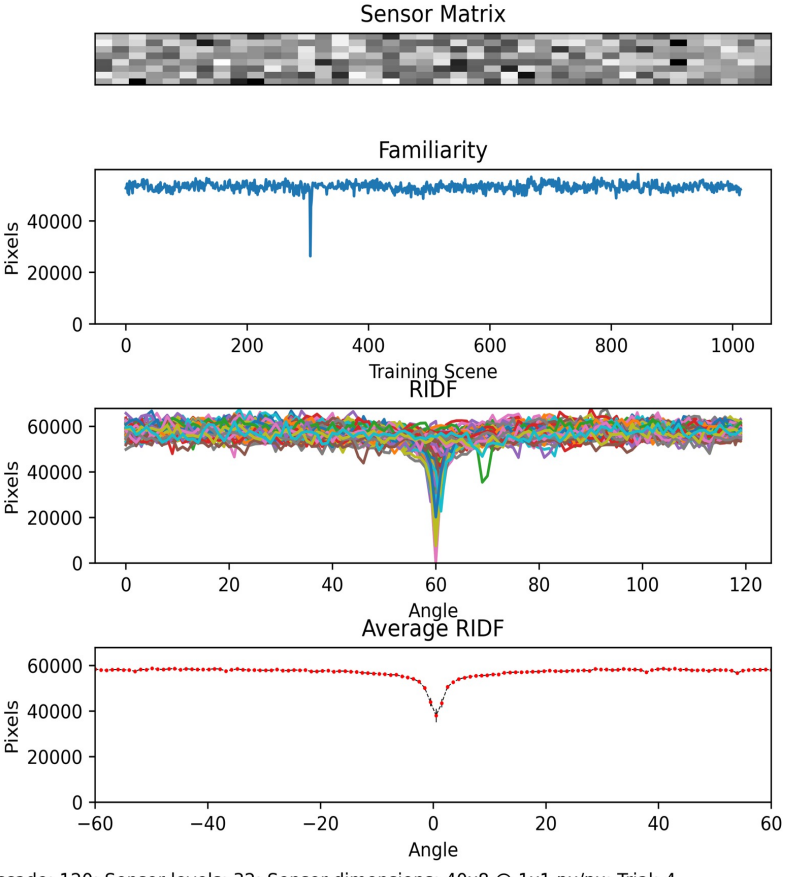


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 65.32; RMSD/dist: 0.163; TD: 10023; p90: 6; p50: 4; complete: 0

90%

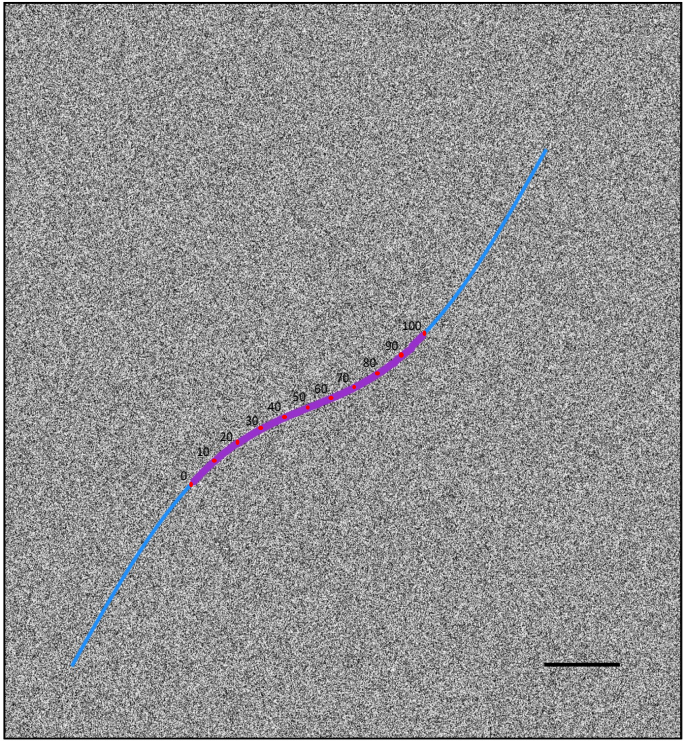


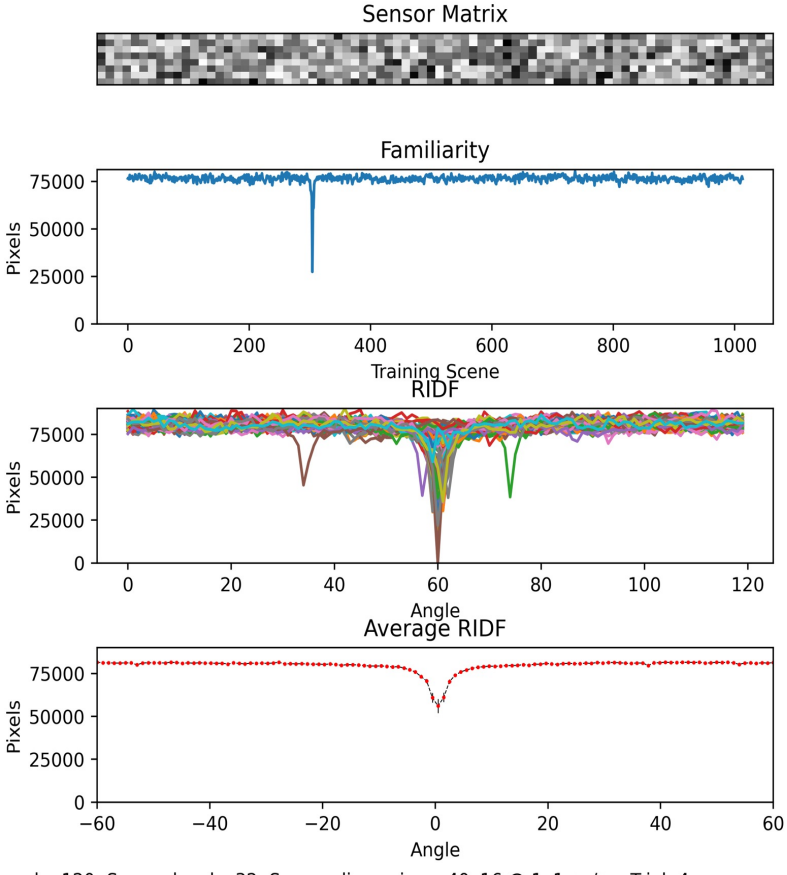


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 145.95; RMSD/dist: 0.365; TD: 14712; p90: 4; p50: 2; complete: 0

100%

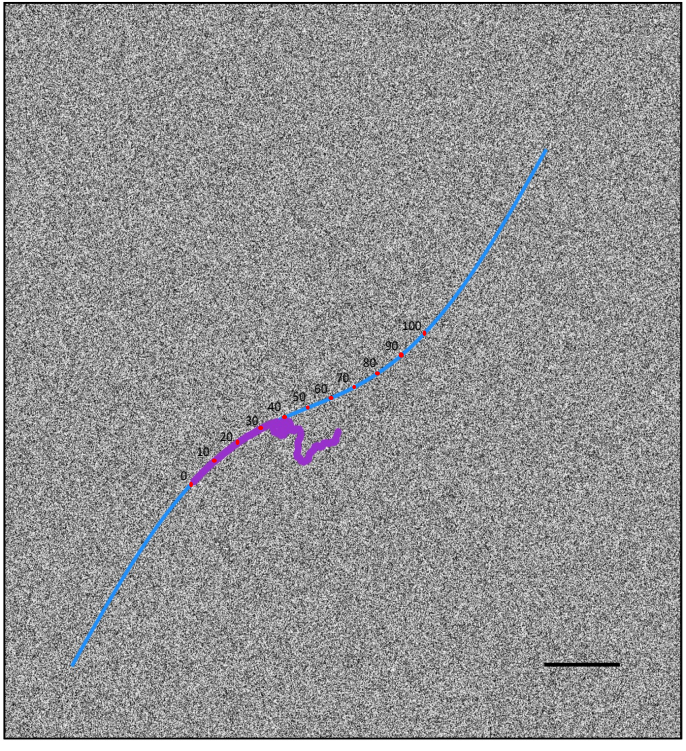


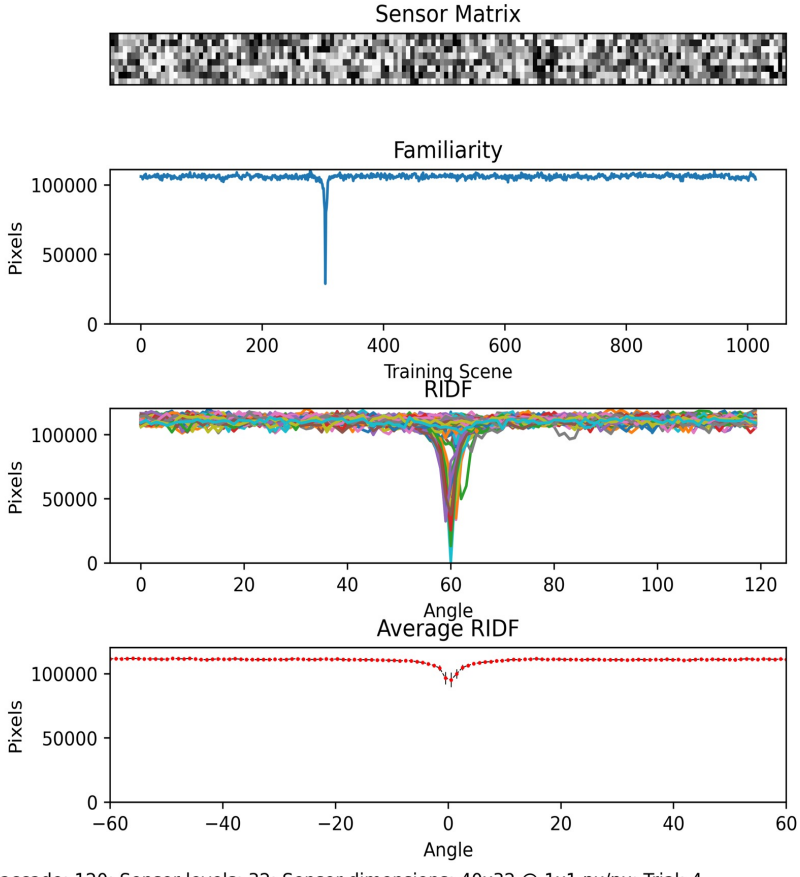


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 47.92; RMSD/dist: 0.120; TD: 19813; p90: 6; p50: 4; complete: 0

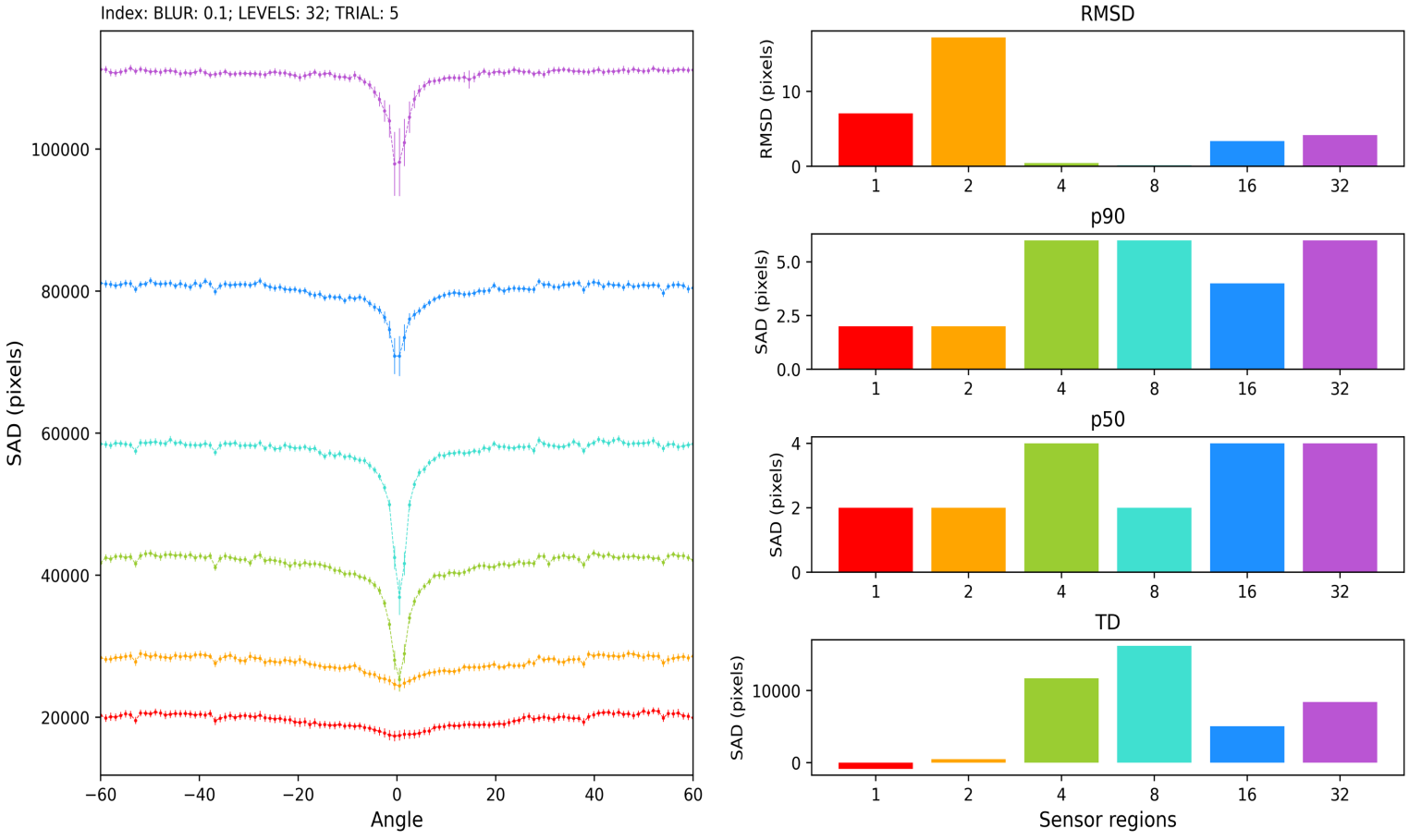
30%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2060.53; RMSD/dist: 5.151; TD: 11339; p90: 6; p50: 4; complete: 0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40000
20000
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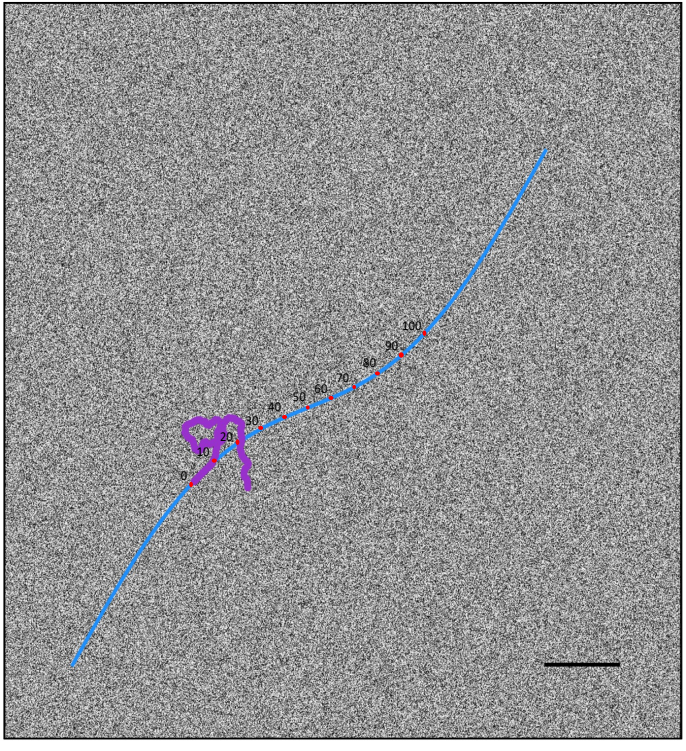
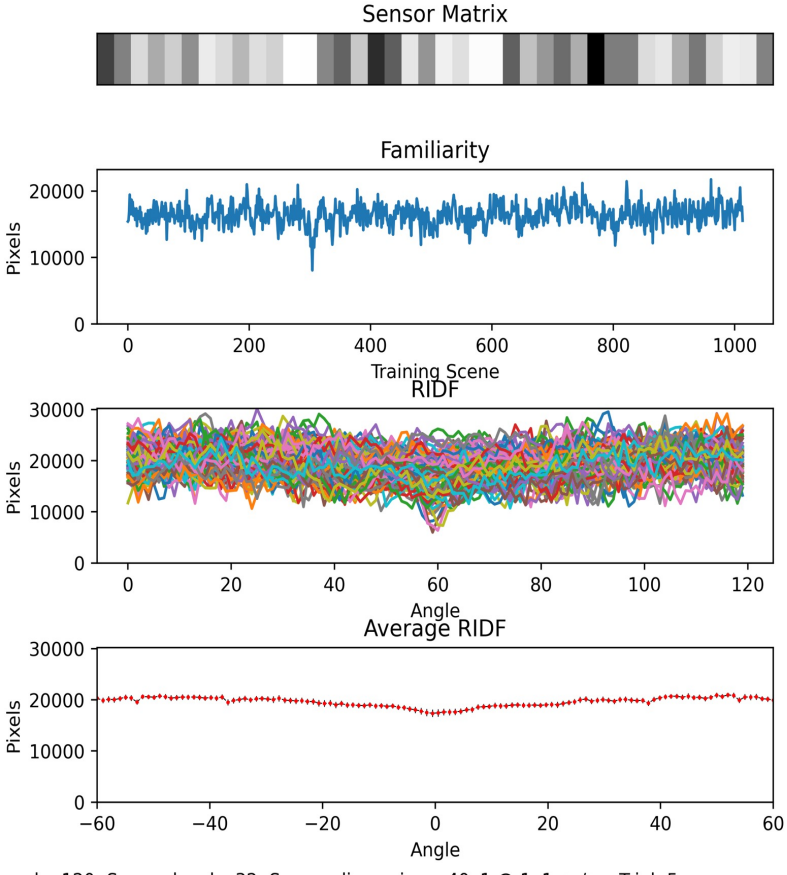
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
4
2
0
TD
10000
0
Sensor regions

10%

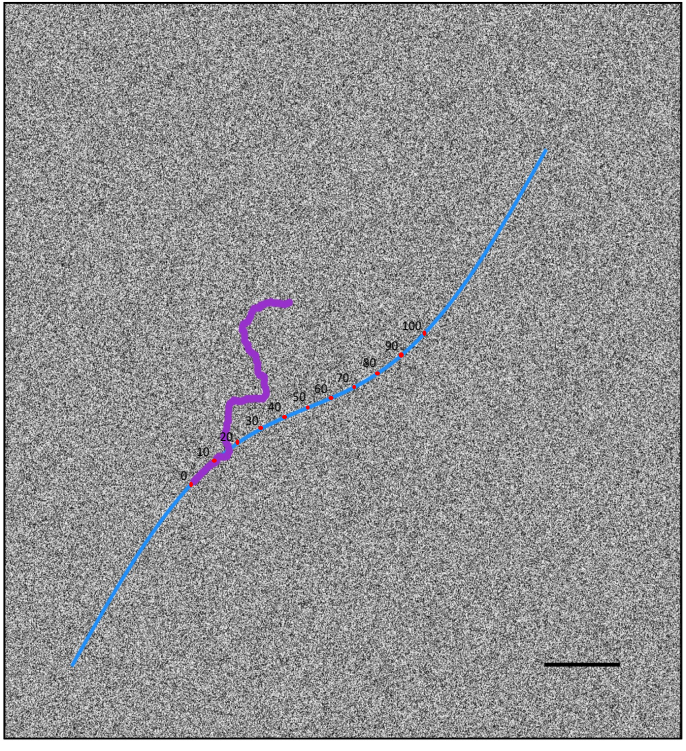


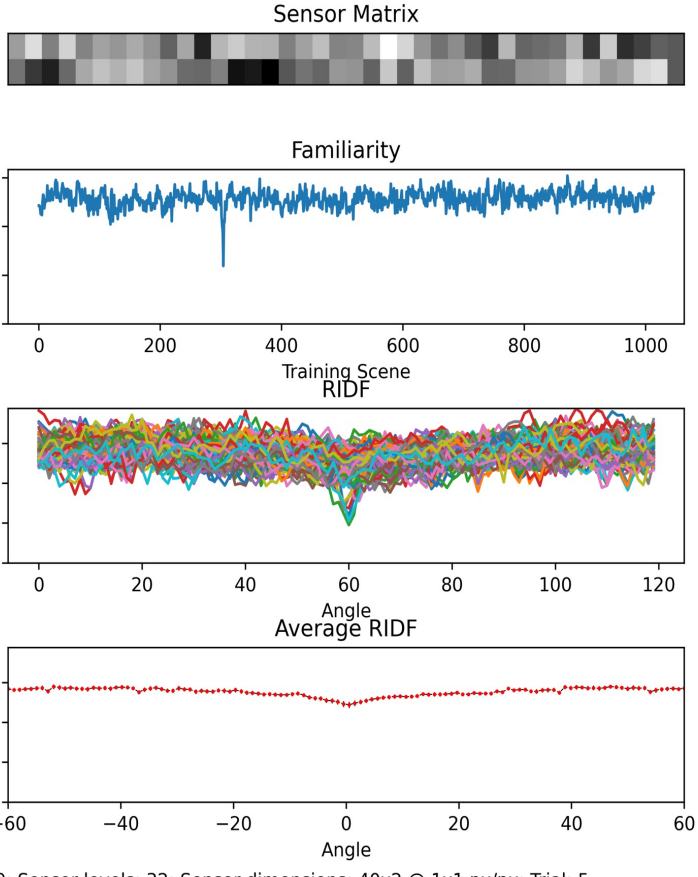


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2833.62; RMSD/dist: 7.084; TD: -854; p90: 2; p50: 2; complete: 0

10%

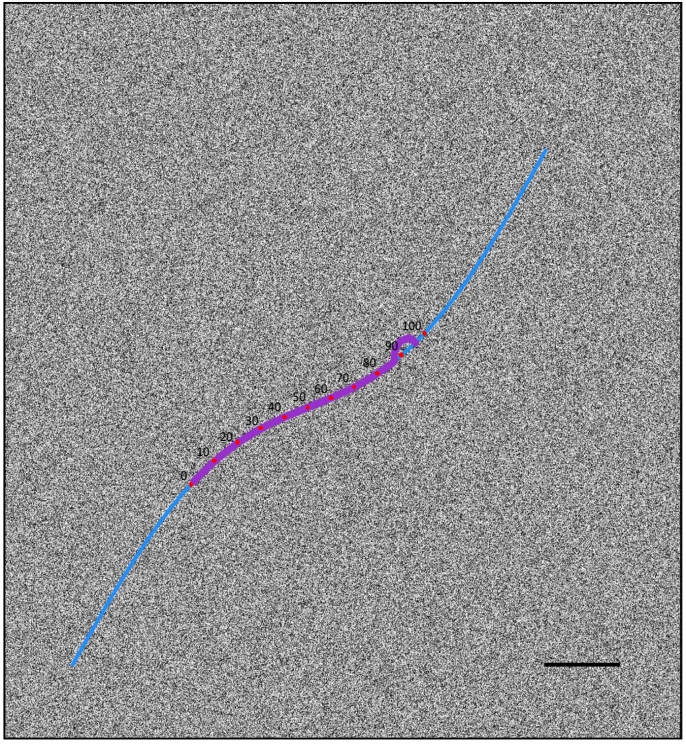


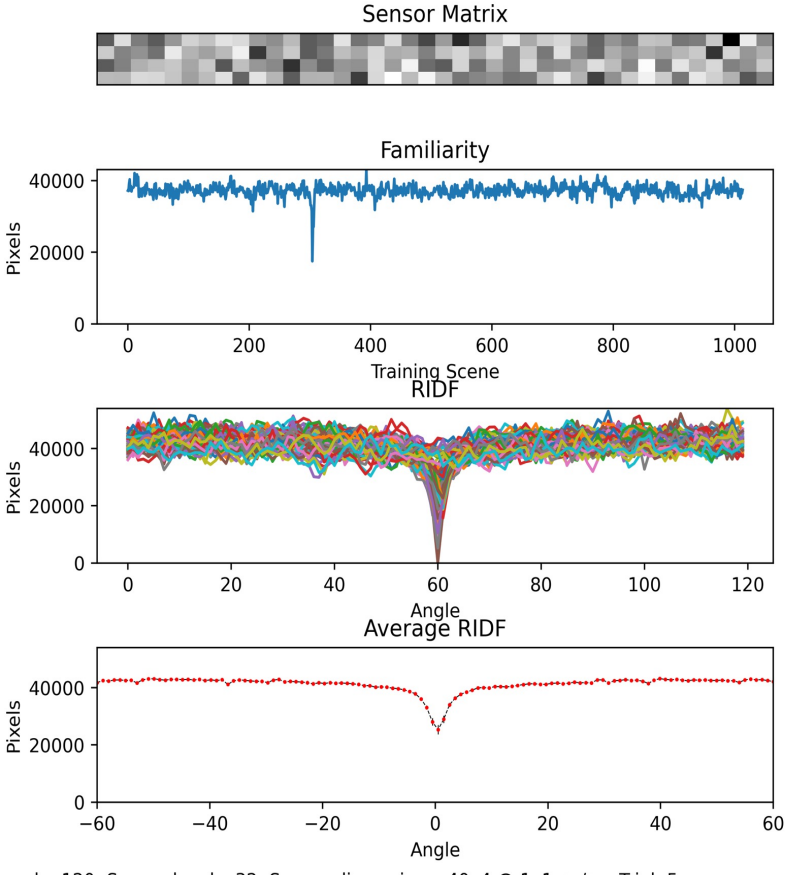


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 6889.08; RMSD/dist: 17.223; TD: 479; p90: 2; p50: 2; complete: 0

80%

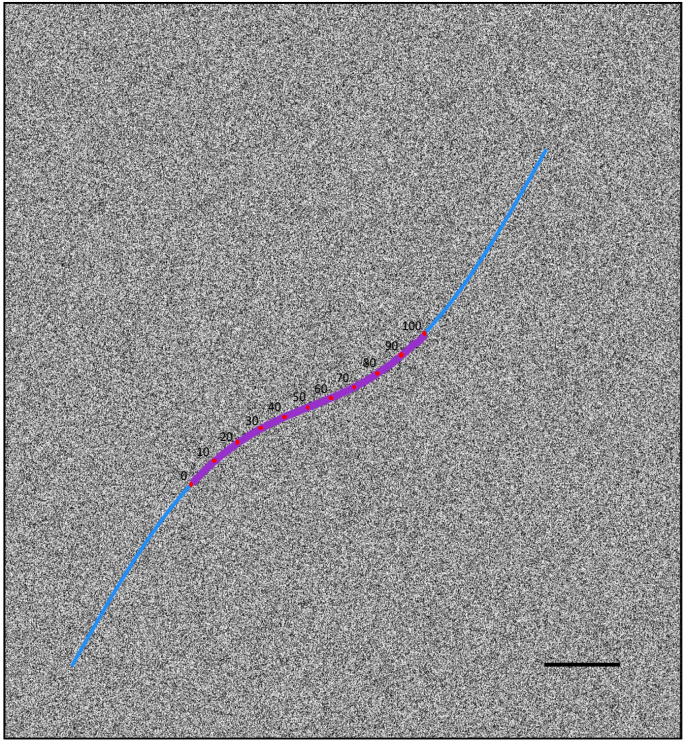


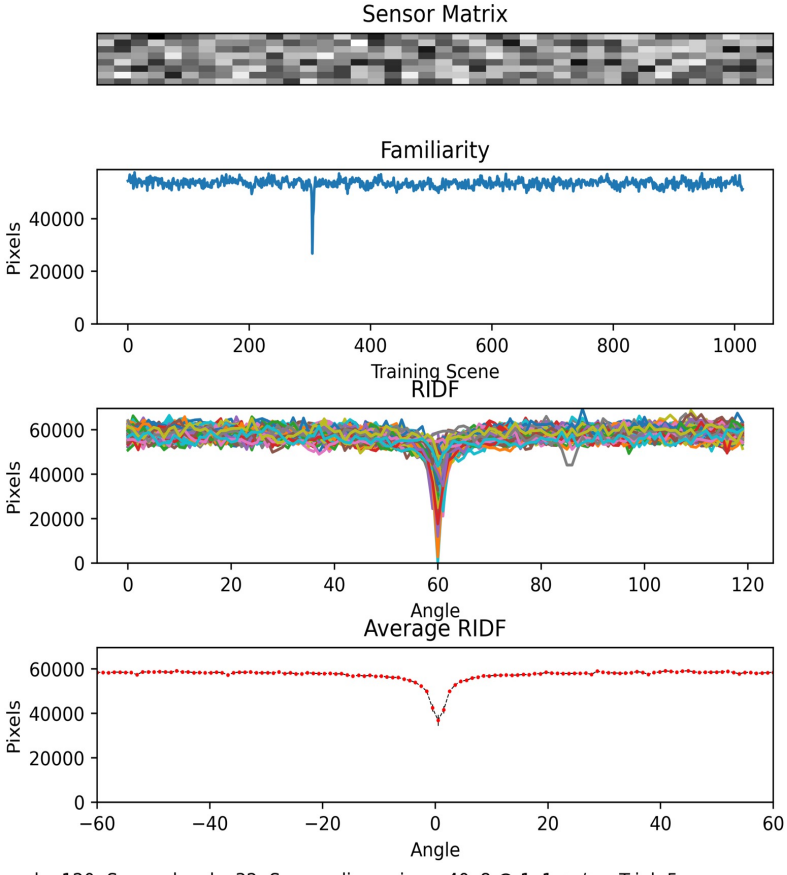


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 172.26; RMSD/dist: 0.431; TD: 11706; p90: 6; p50: 4; complete: 0

100%

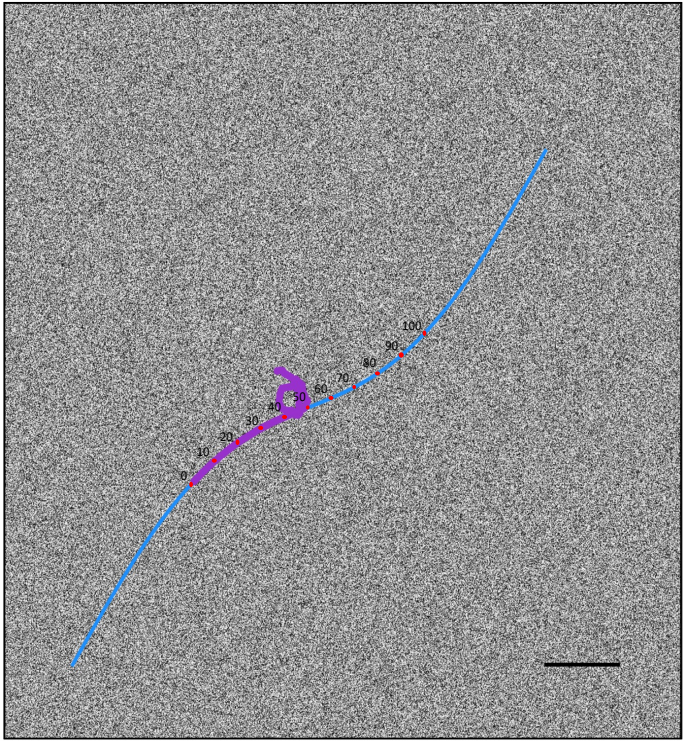


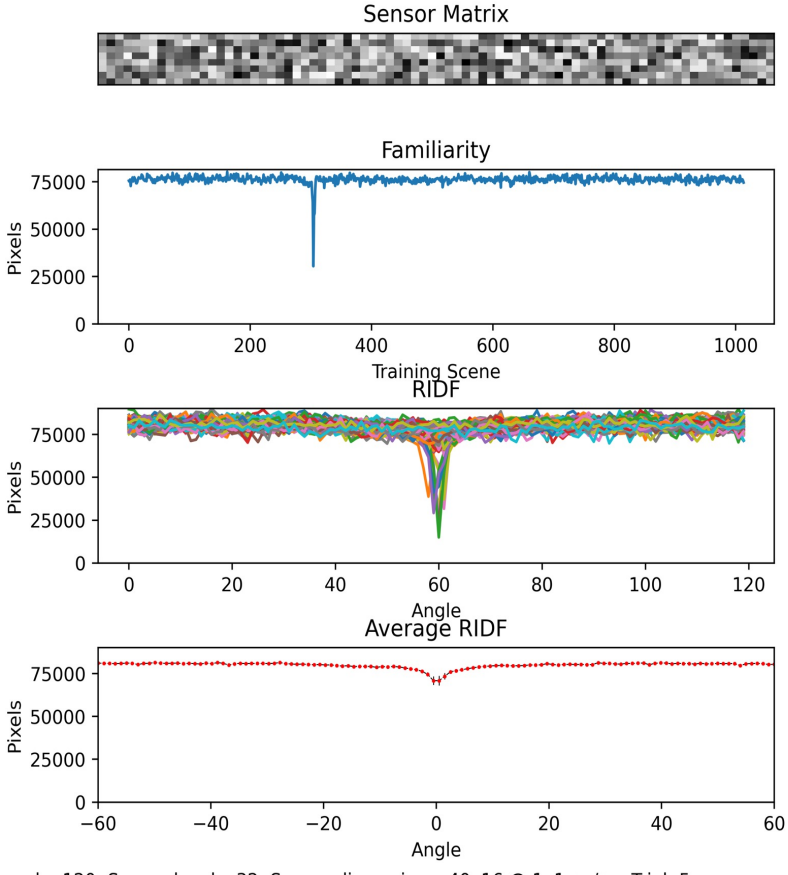


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 47.05; RMSD/dist: 0.118; TD: 16188; p90: 6; p50: 2; complete: 0

40%

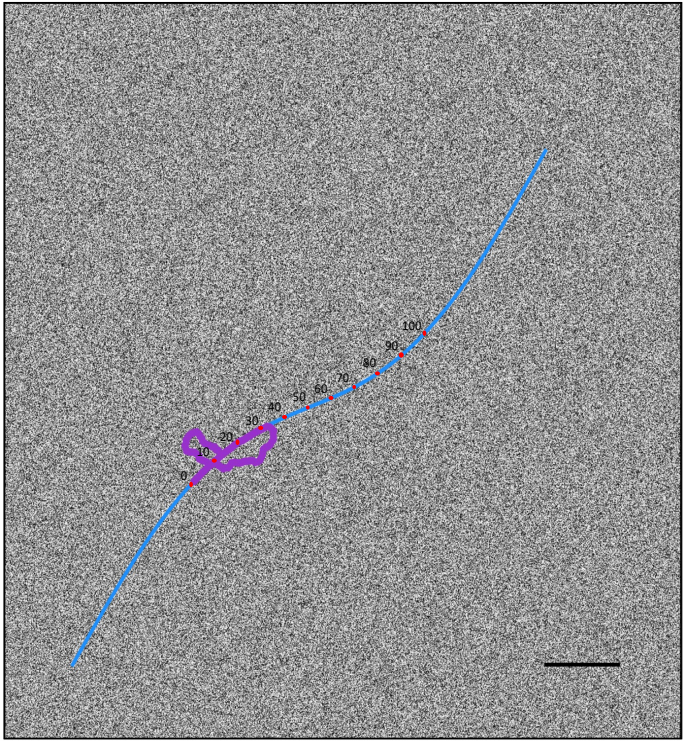


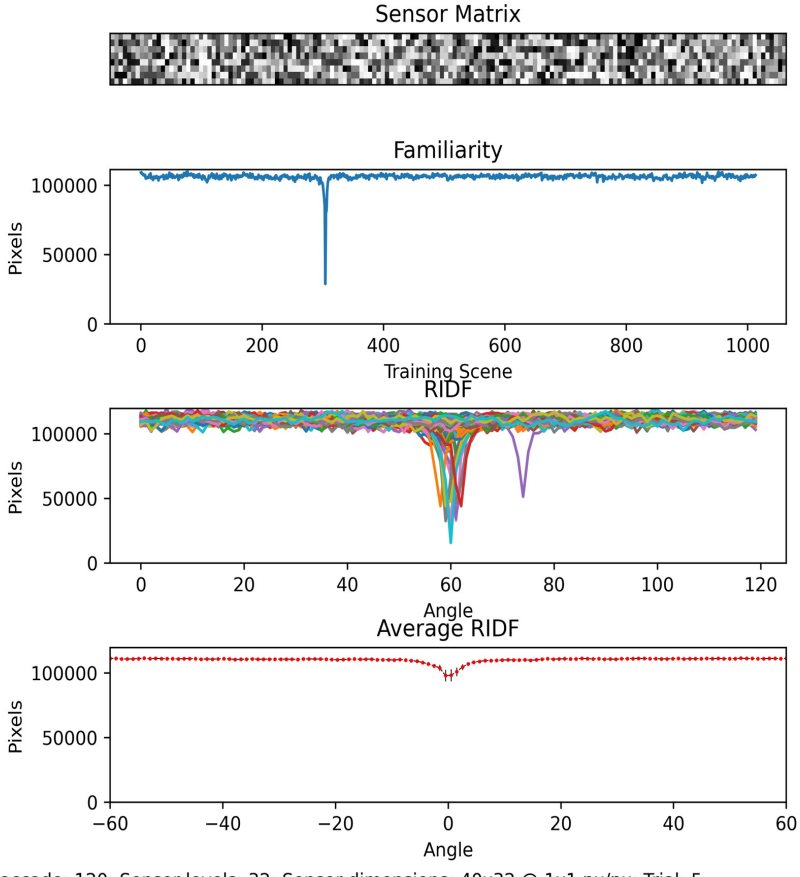


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1350.49; RMSD/dist: 3.376; TD: 5063; p90: 4; p50: 4; complete: 0

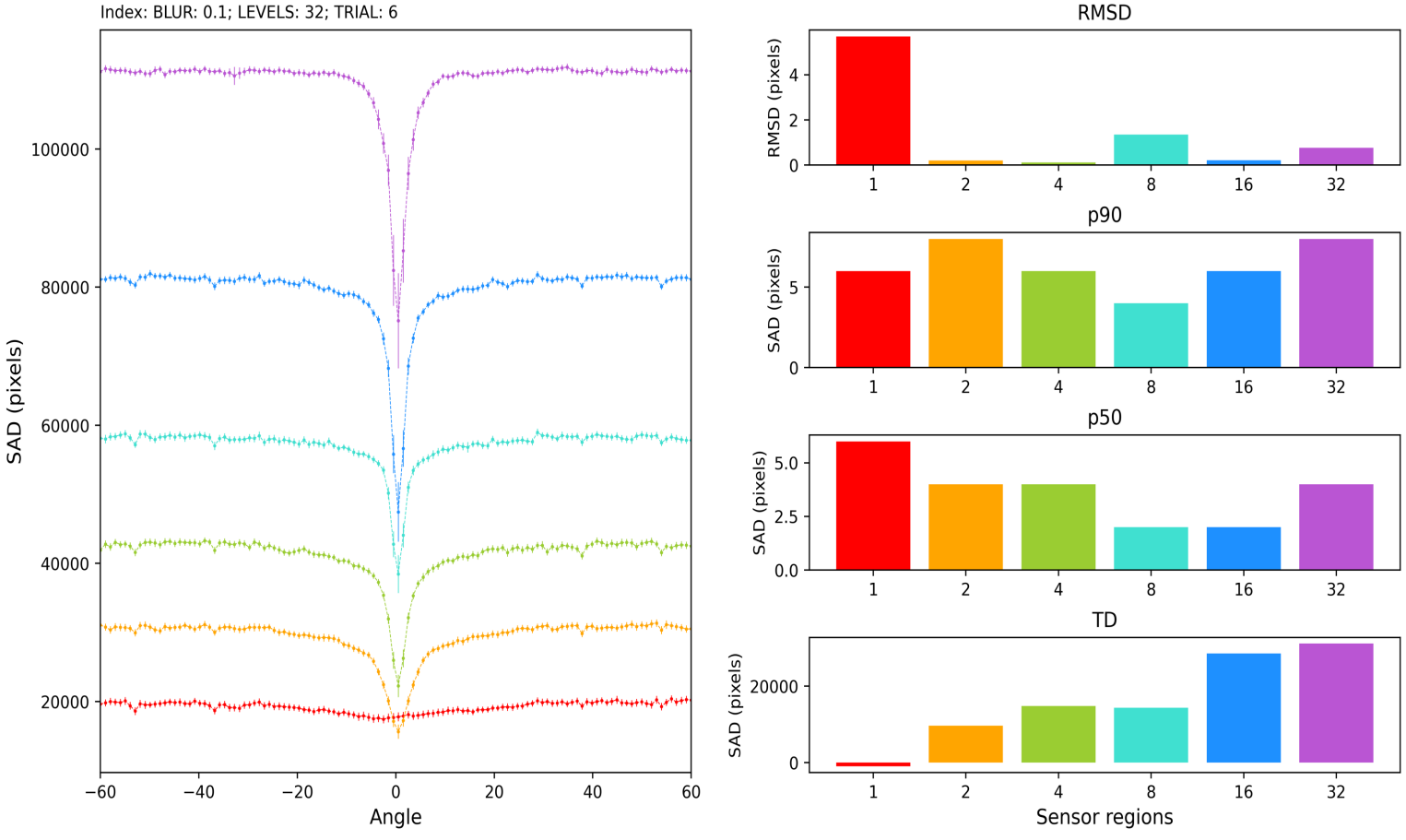
30%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1669.99; RMSD/dist: 4.175; TD: 8424; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 32; TRIAL: 6
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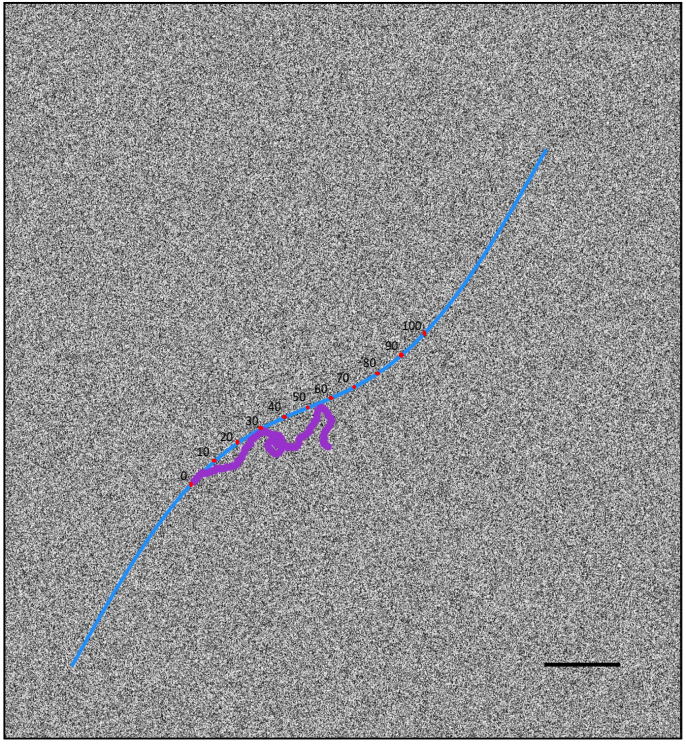
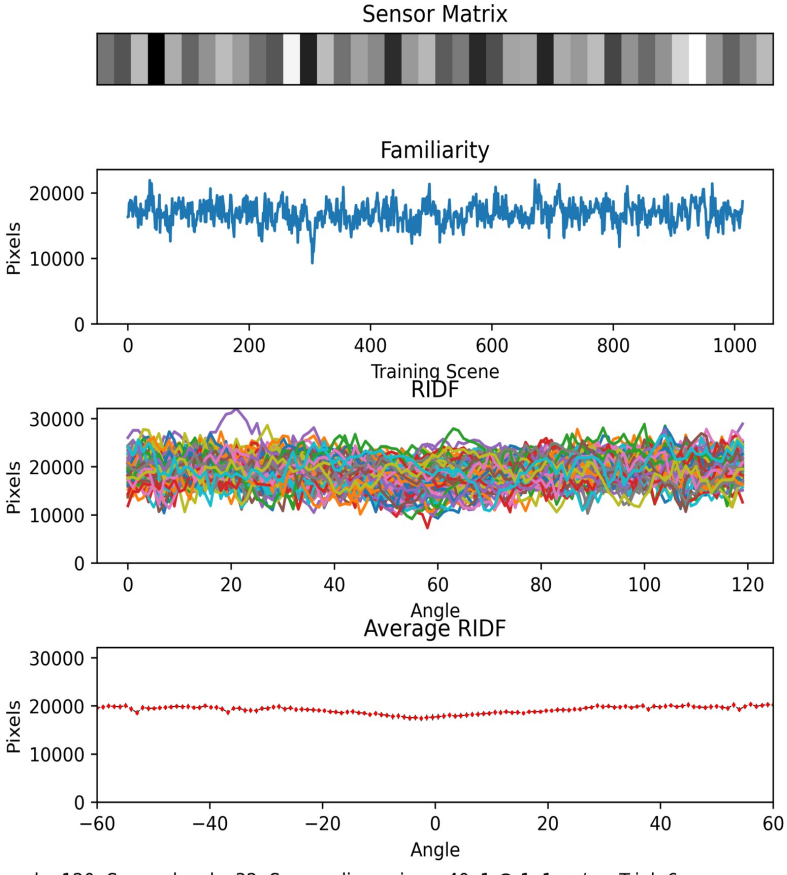
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
5.0
2.5
0.0
TD
SAD (pixels)
20000
0
Sensor regions

0%

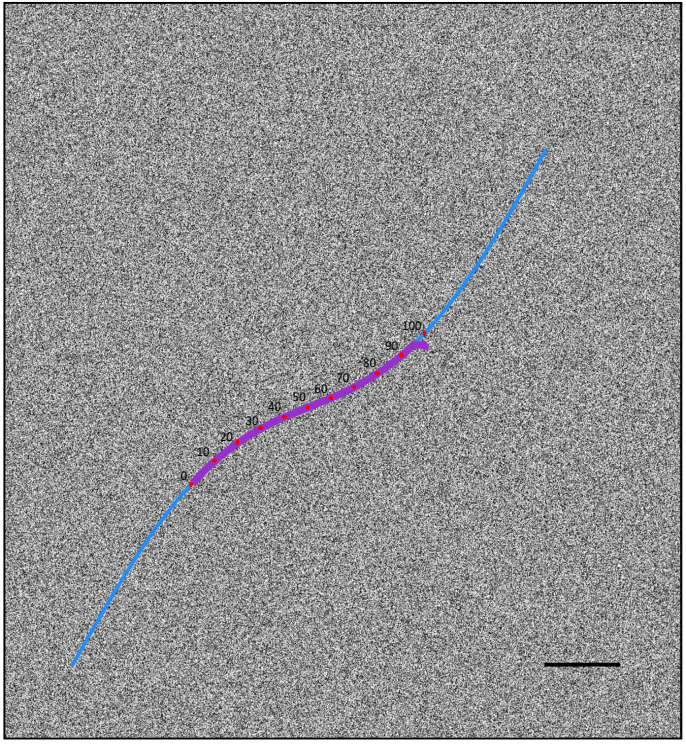


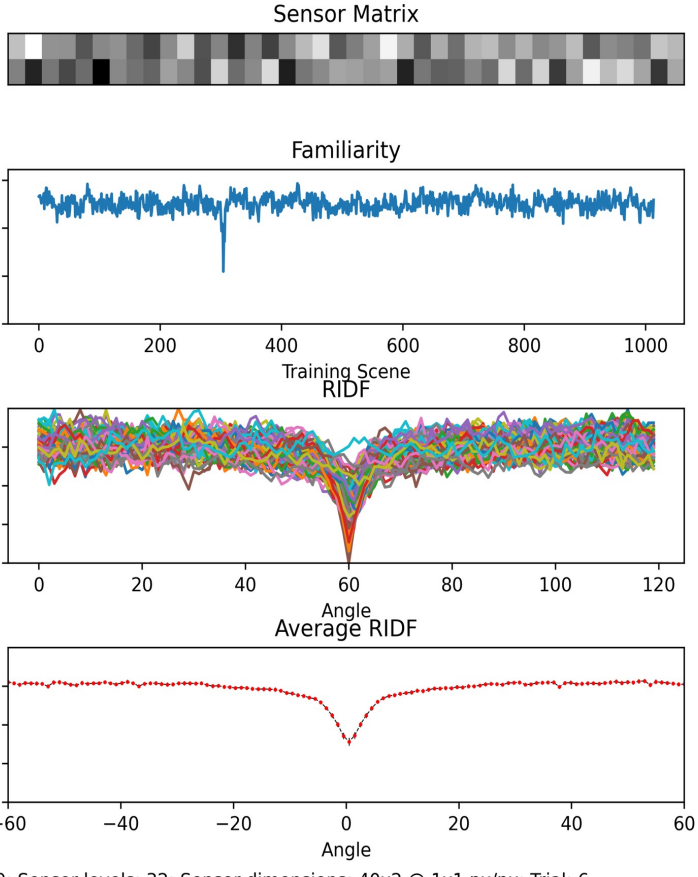


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2279.01; RMSD/dist: 5.698; TD: -976; p90: 6; p50: 6; complete: 0

90%

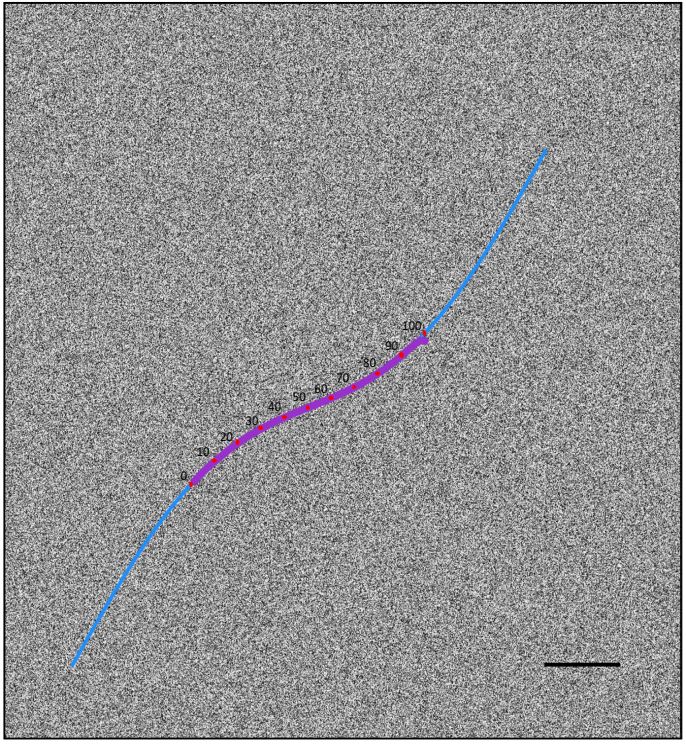


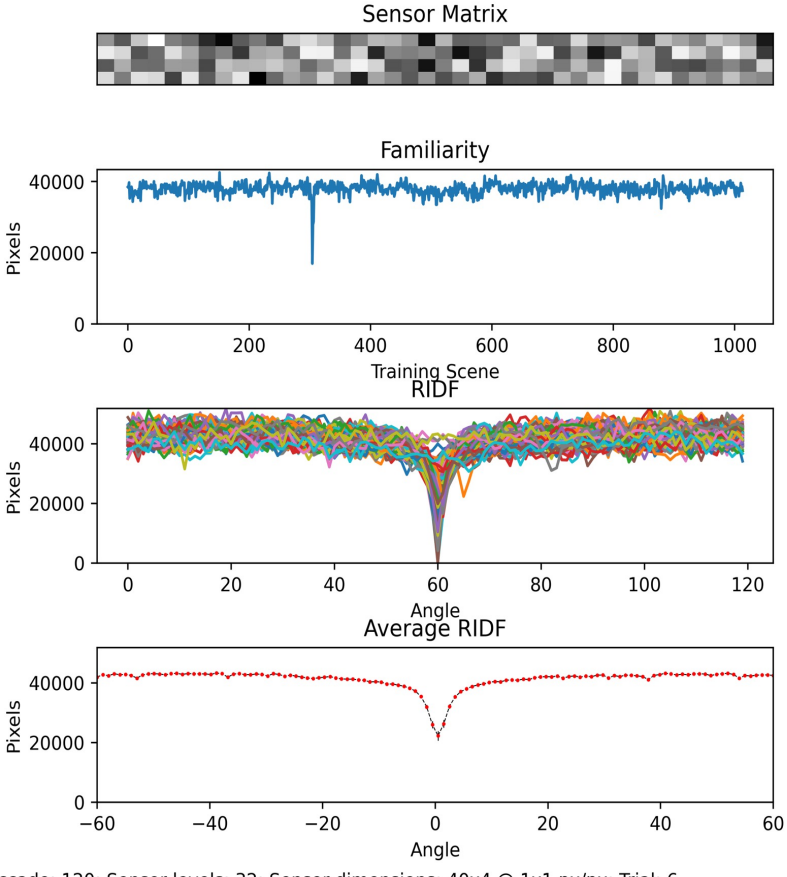


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 79.68; RMSD/dist: 0.199; TD: 9649; p90: 8; p50: 4; complete: 0

90%

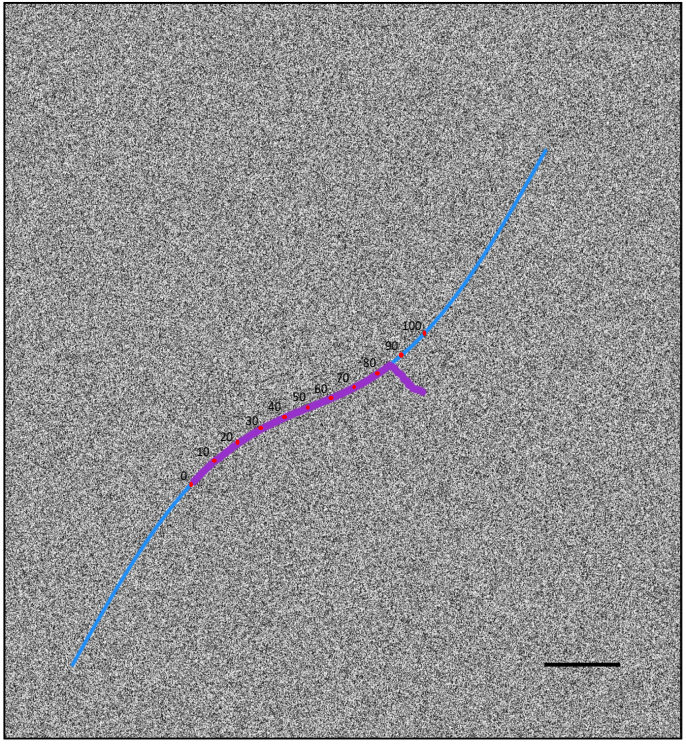


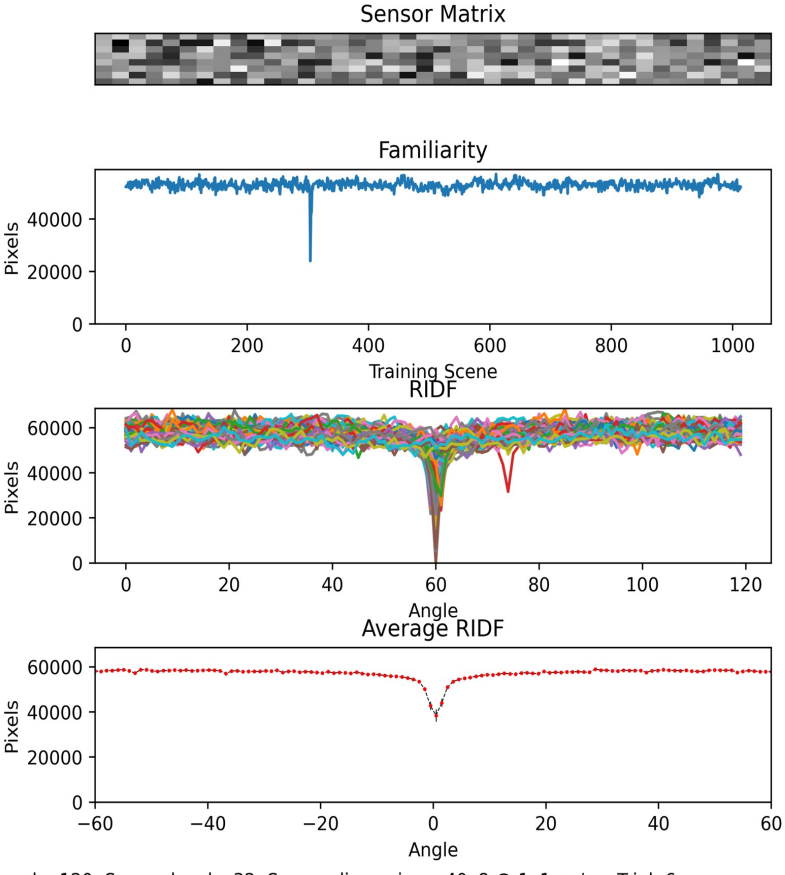


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 42.38; RMSD/dist: 0.106; TD: 14784; p90: 6; p50: 4; complete: 0

80%

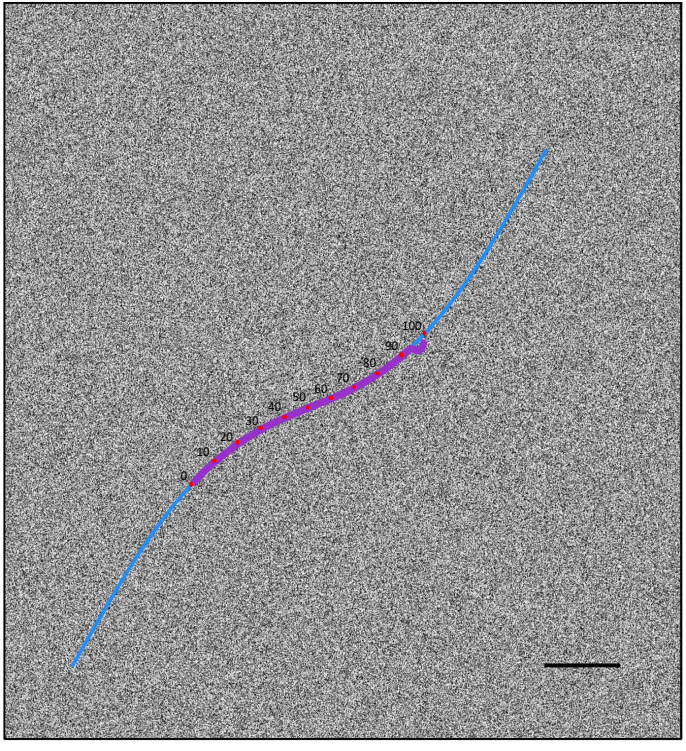


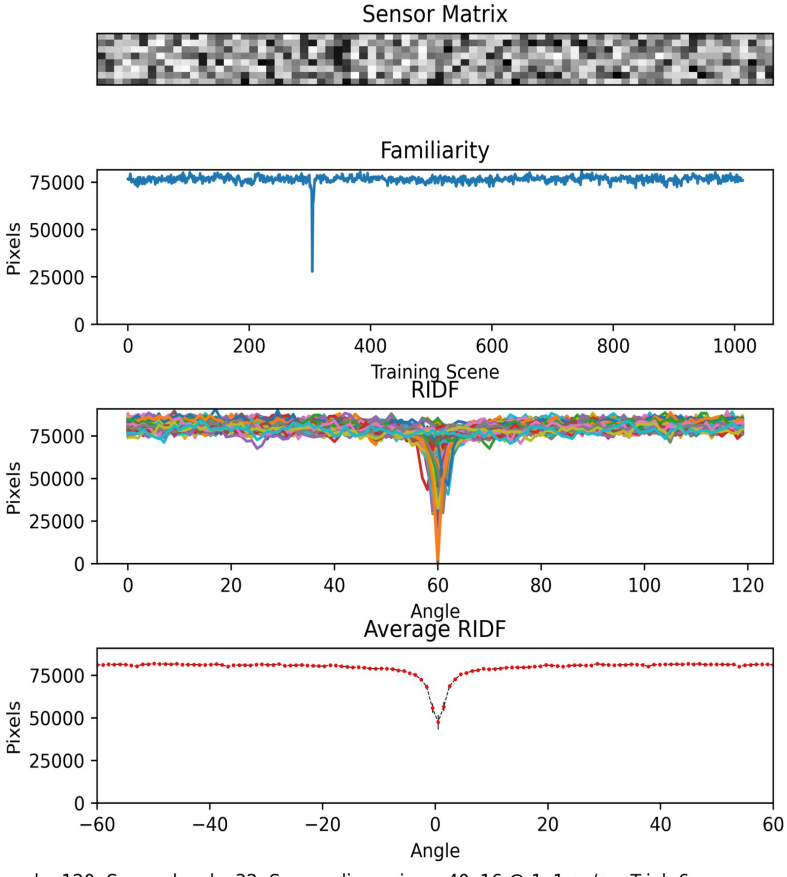


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 539.19; RMSD/dist: 1.348; TD: 14375; p90: 4; p50: 2; complete: 0

90%

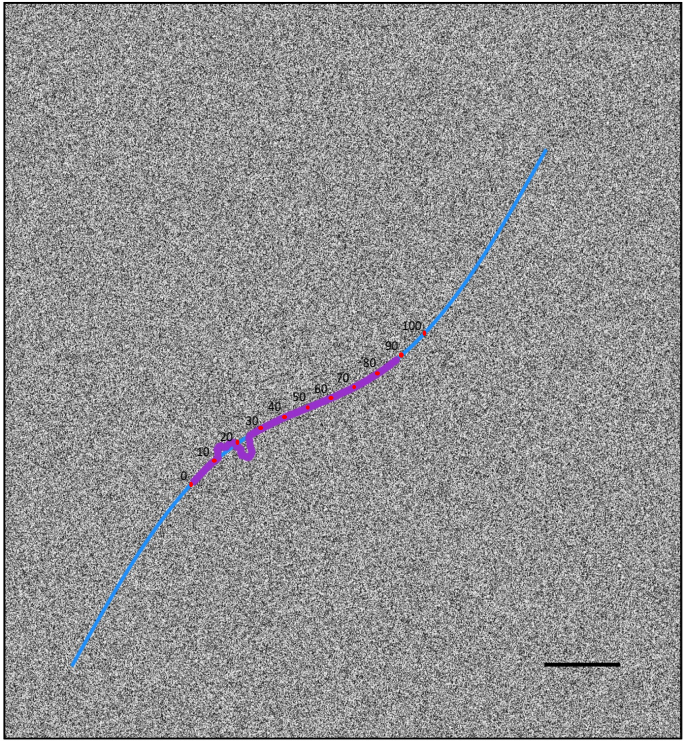


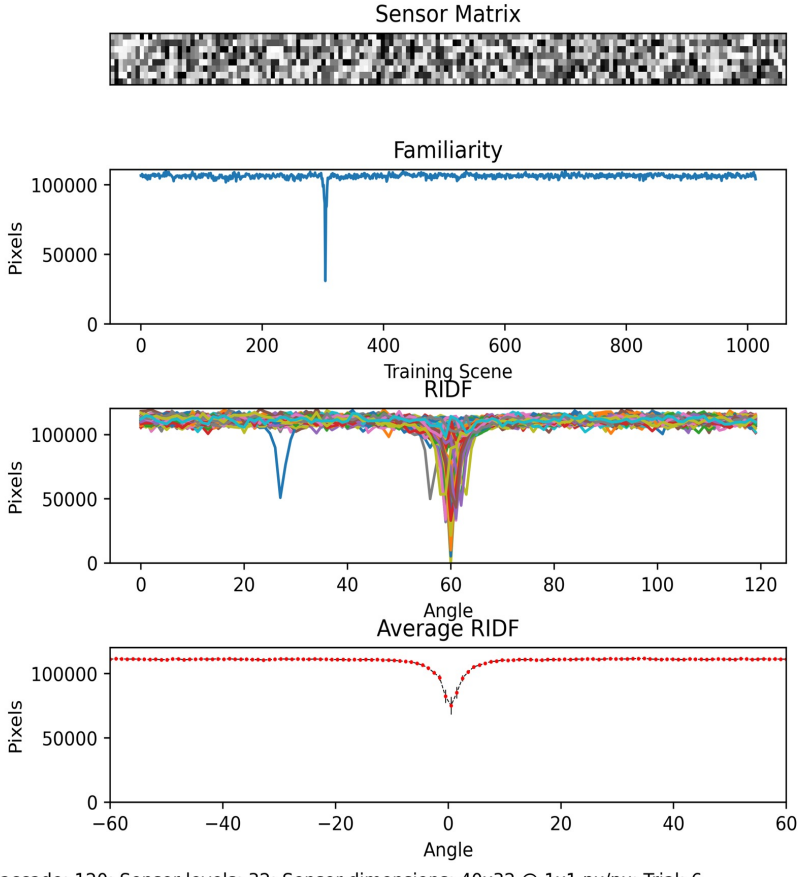


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 81.18; RMSD/dist: 0.203; TD: 28533; p90: 6; p50: 2; complete: 0

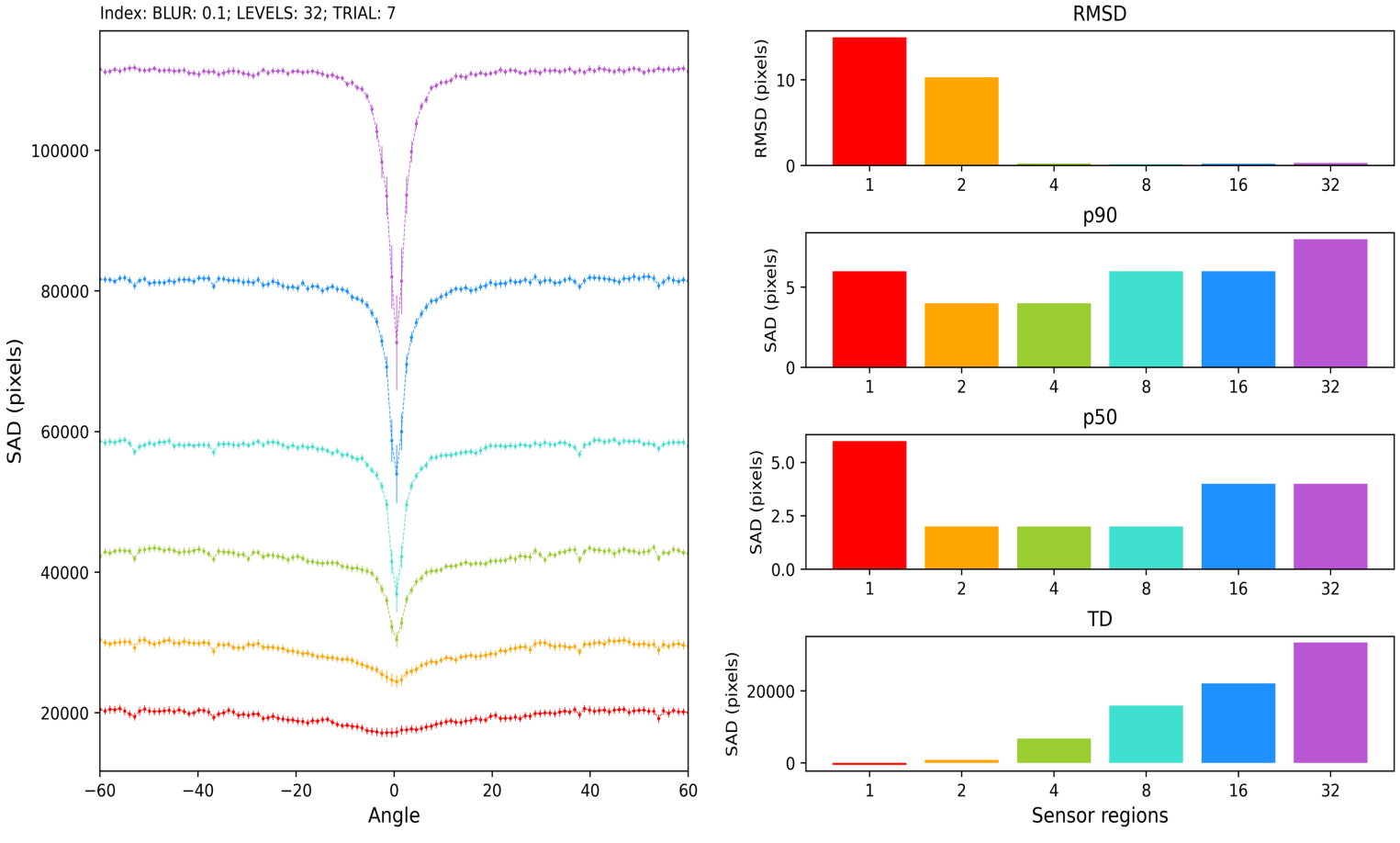
70%



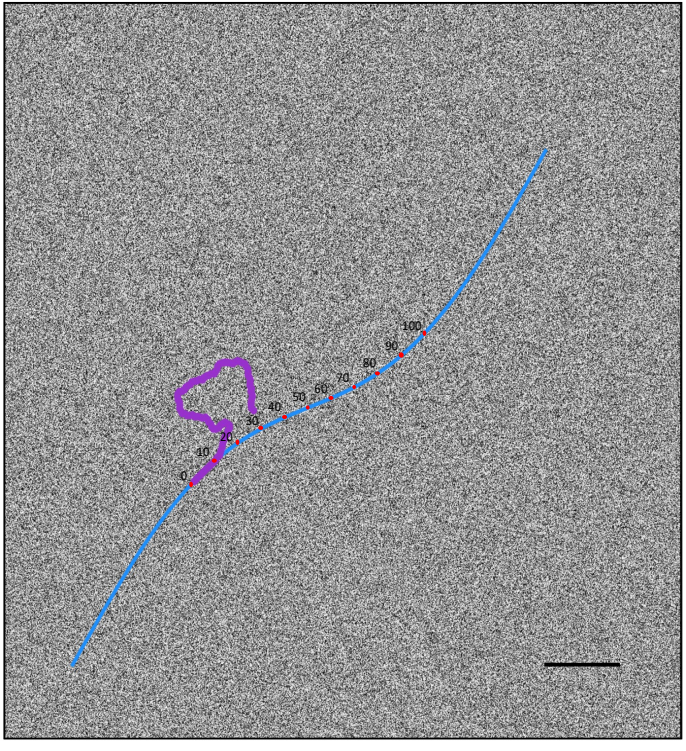


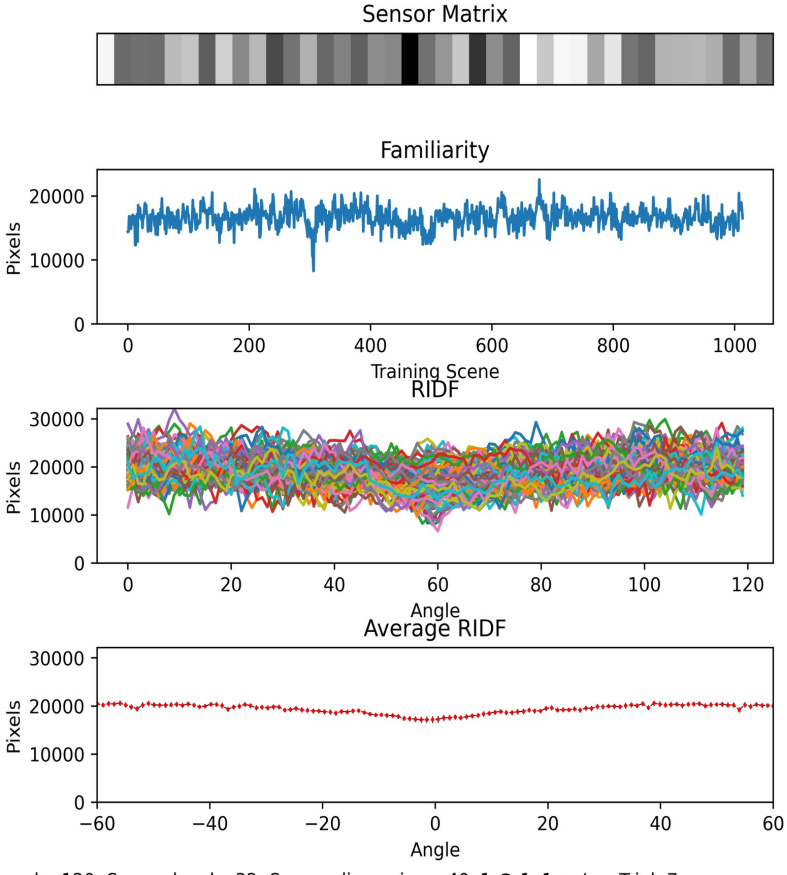
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 303.44; RMSD/dist: 0.759; TD: 31145; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 32; TRIAL: 7
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
5.0
2.5
0.0
TD
SAD (pixels)
20000
0
Sensor regions

10%

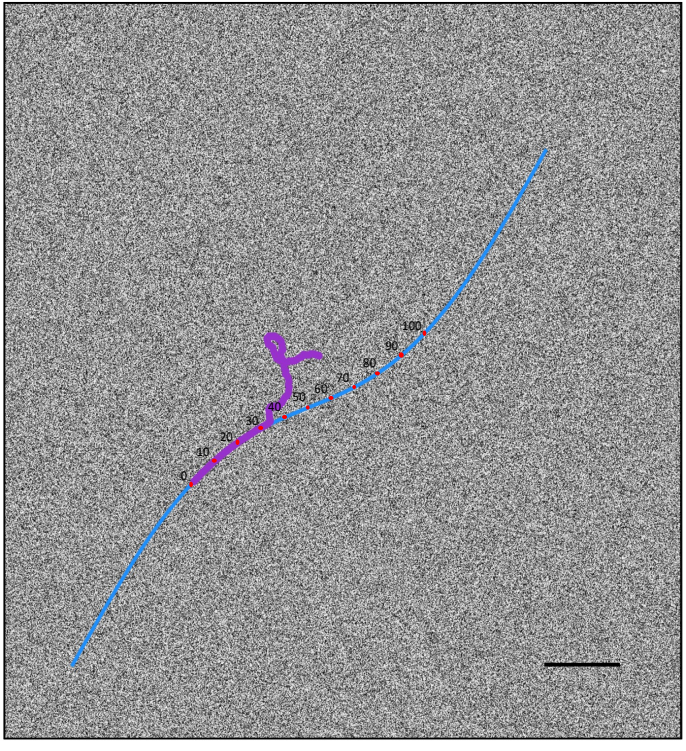


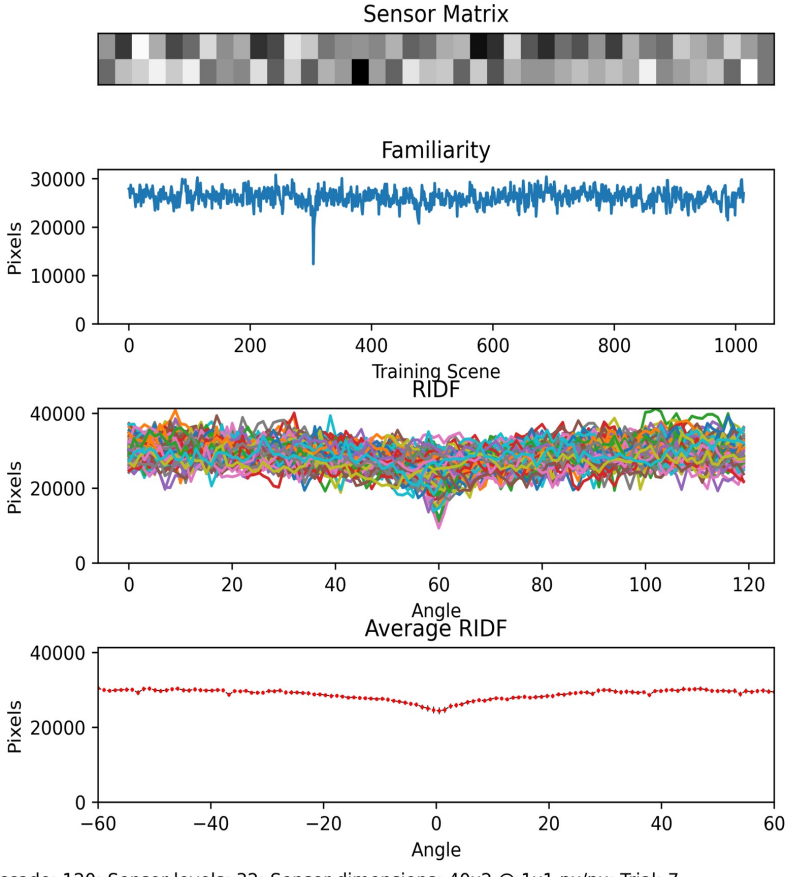


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 5981.16; RMSD/dist: 14.953; TD: -536; p90: 6; p50: 6; complete: 0

30%

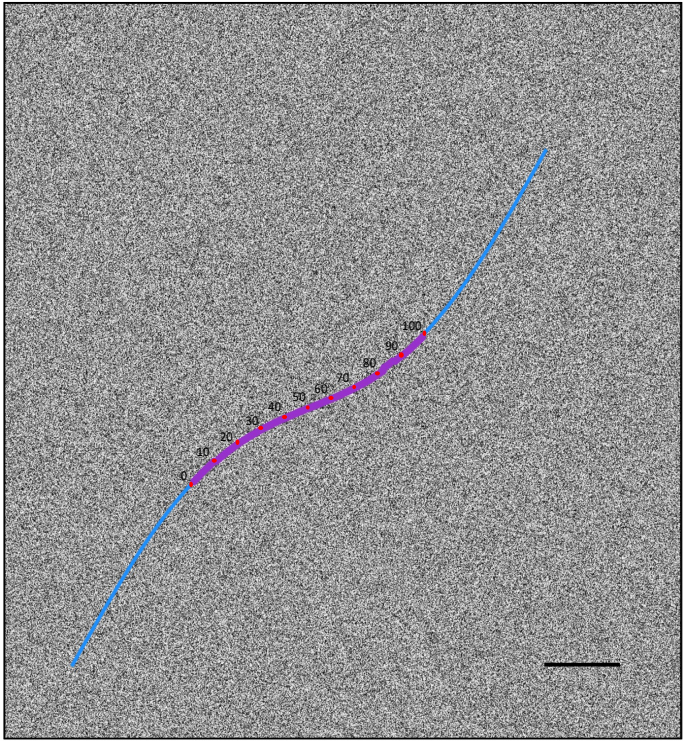


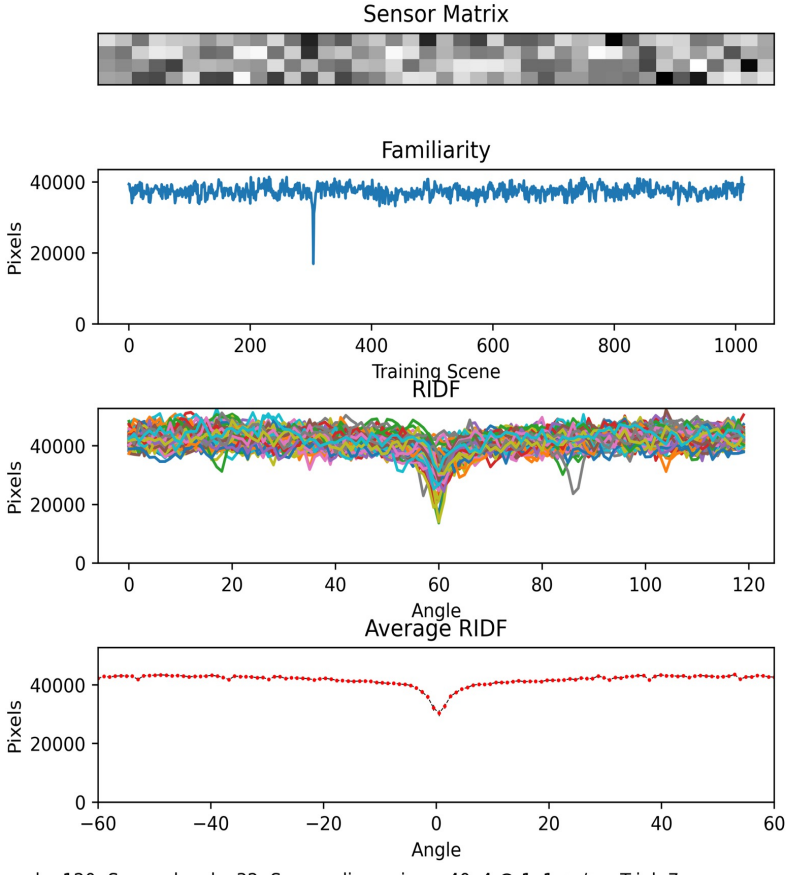


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 4109.91; RMSD/dist: 10.275; TD: 849; p90: 4; p50: 2; complete: 0

100%

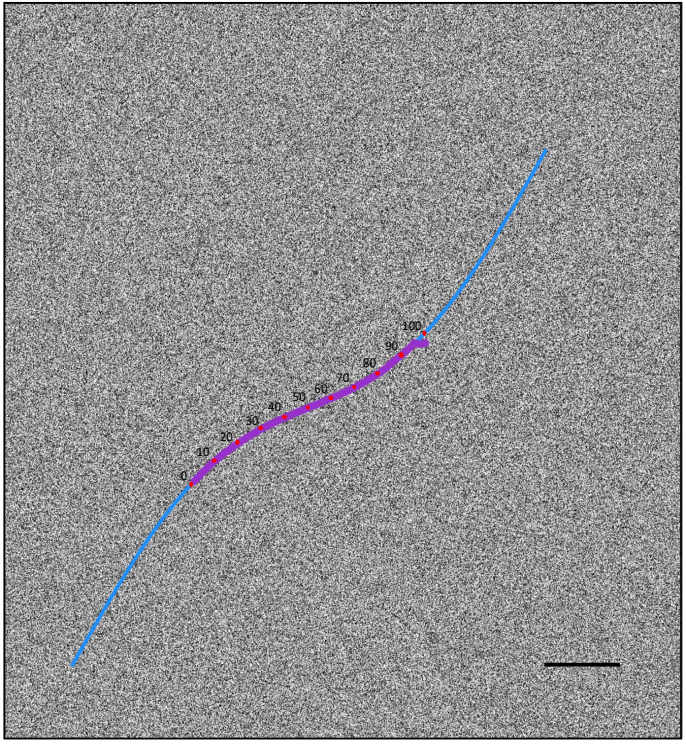


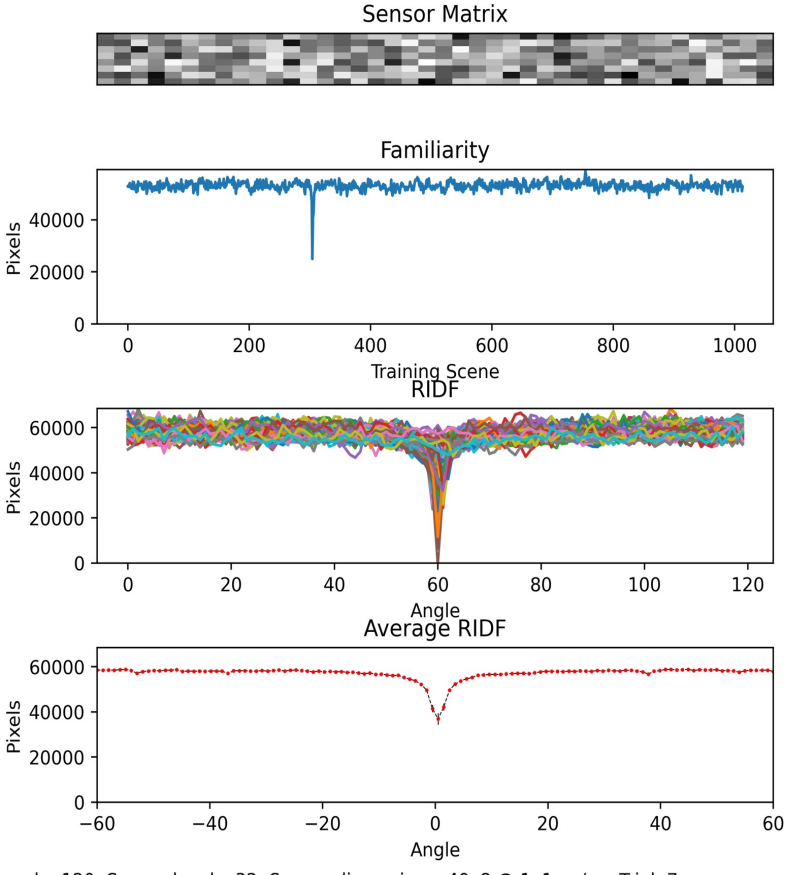


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 94.30; RMSD/dist: 0.236; TD: 6764; p90: 4; p50: 2; complete: 0

90%

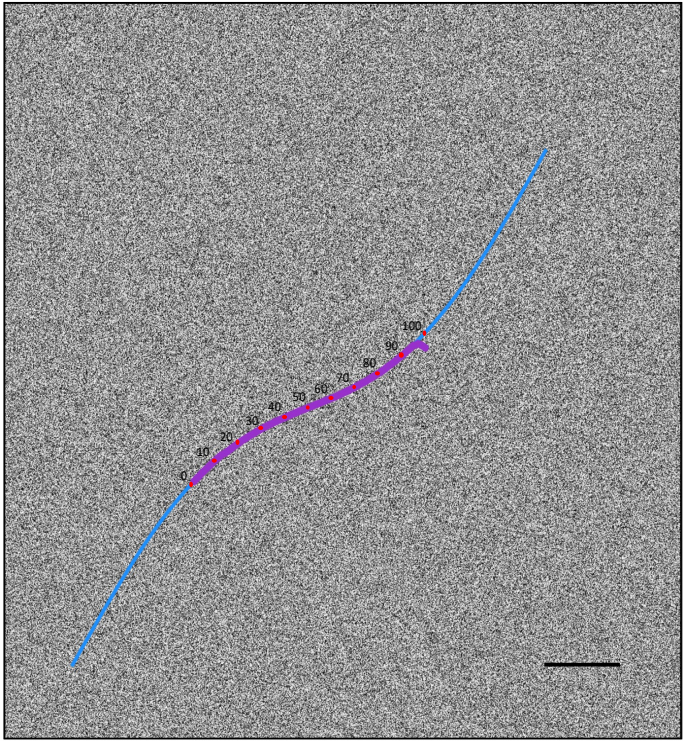


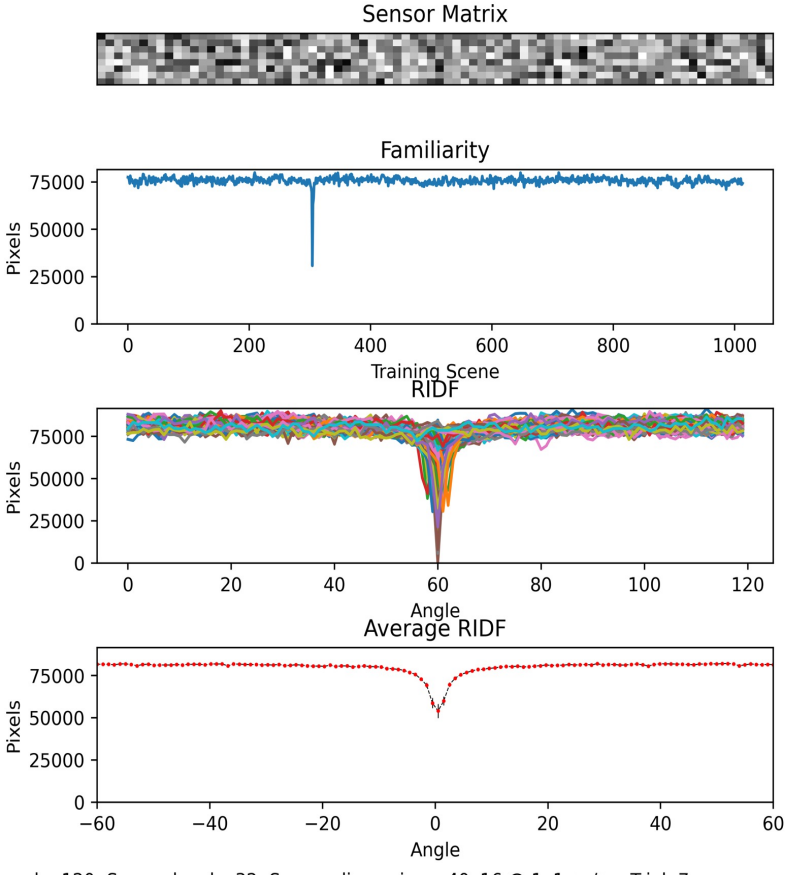


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 59.59; RMSD/dist: 0.149; TD: 15973; p90: 6; p50: 2; complete: 0

90%

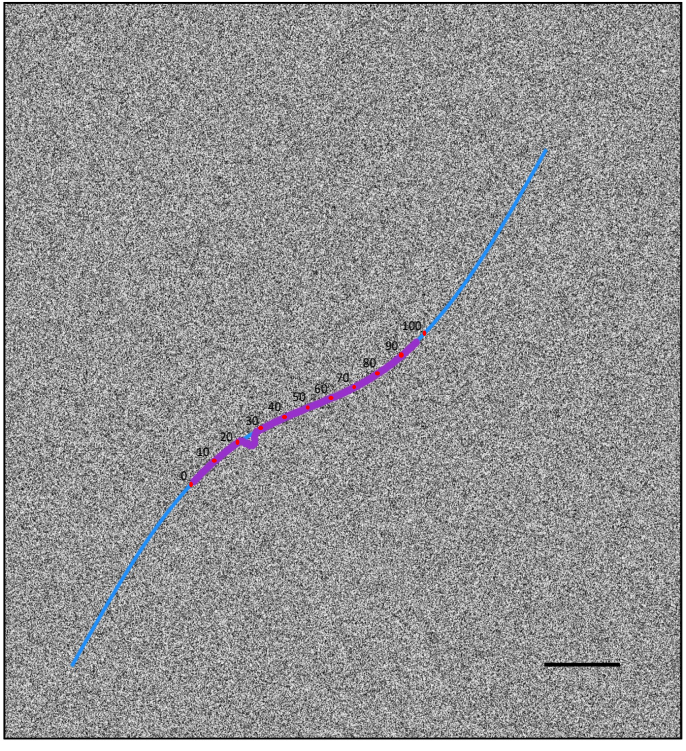


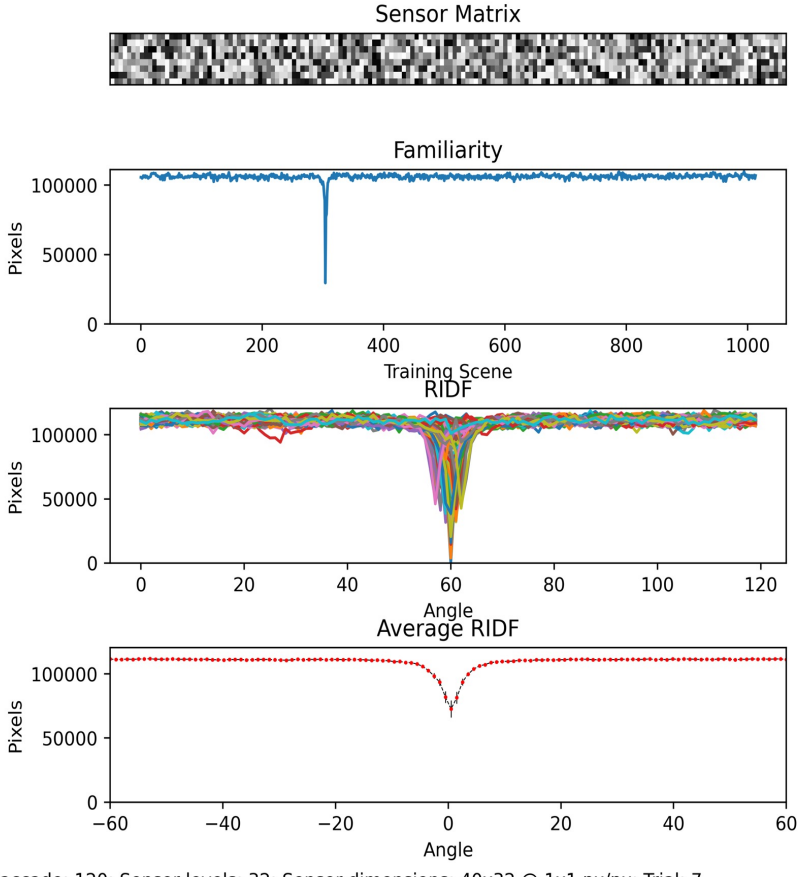


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 82.39; RMSD/dist: 0.206; TD: 22068; p90: 6; p50: 4; complete: 0

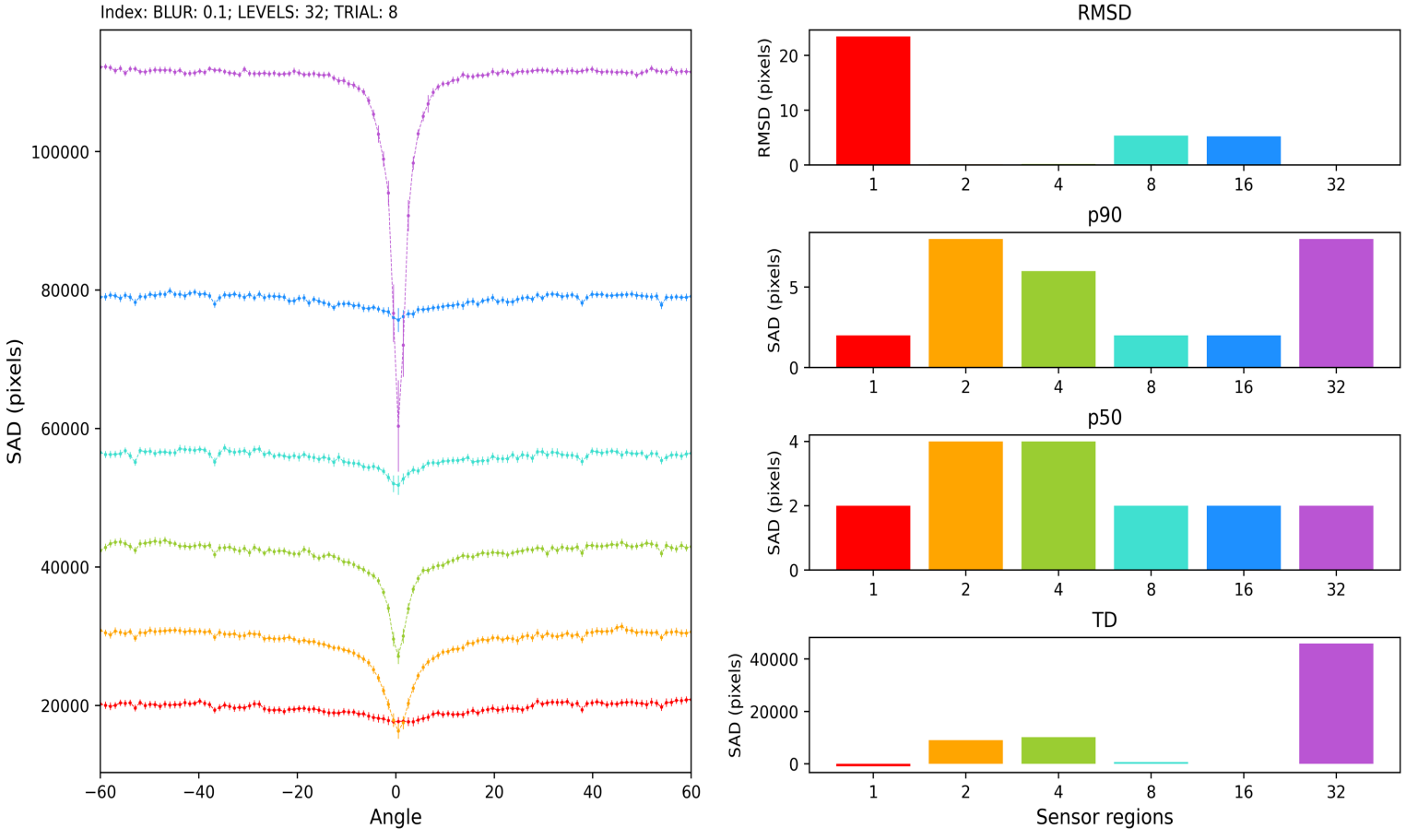
80%



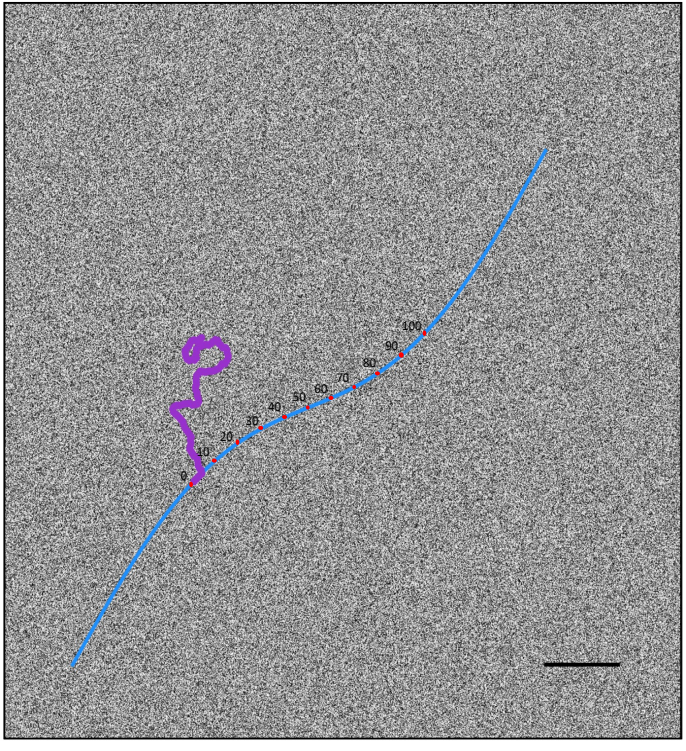


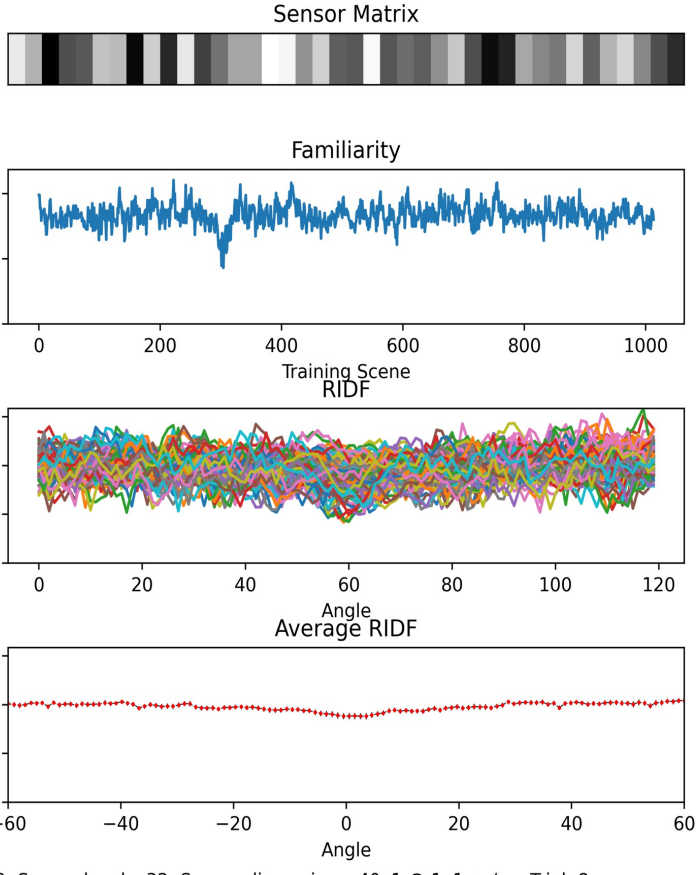
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 112.66; RMSD/dist: 0.282; TD: 33464; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 32; TRIAL: 8
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
4
2
0
TD
SAD (pixels)
40000
20000
0
Sensor regions

0%

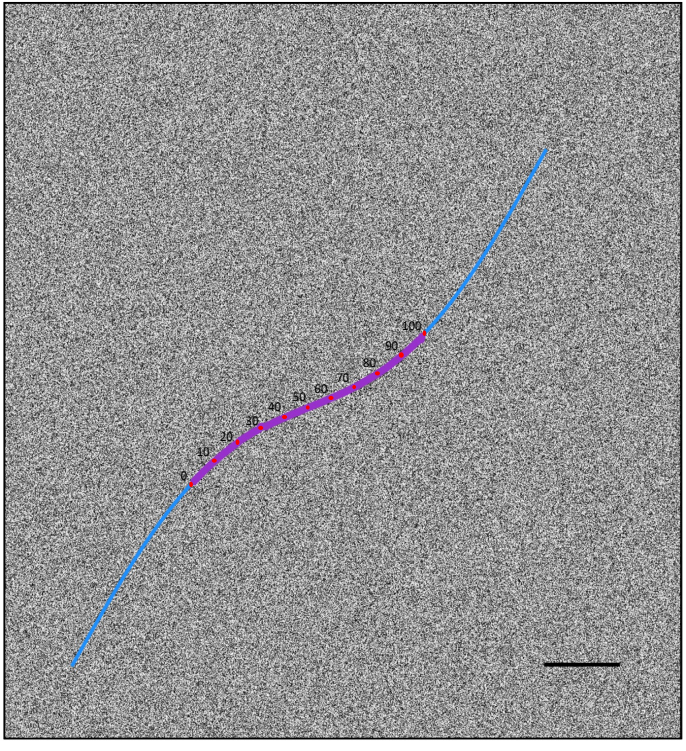


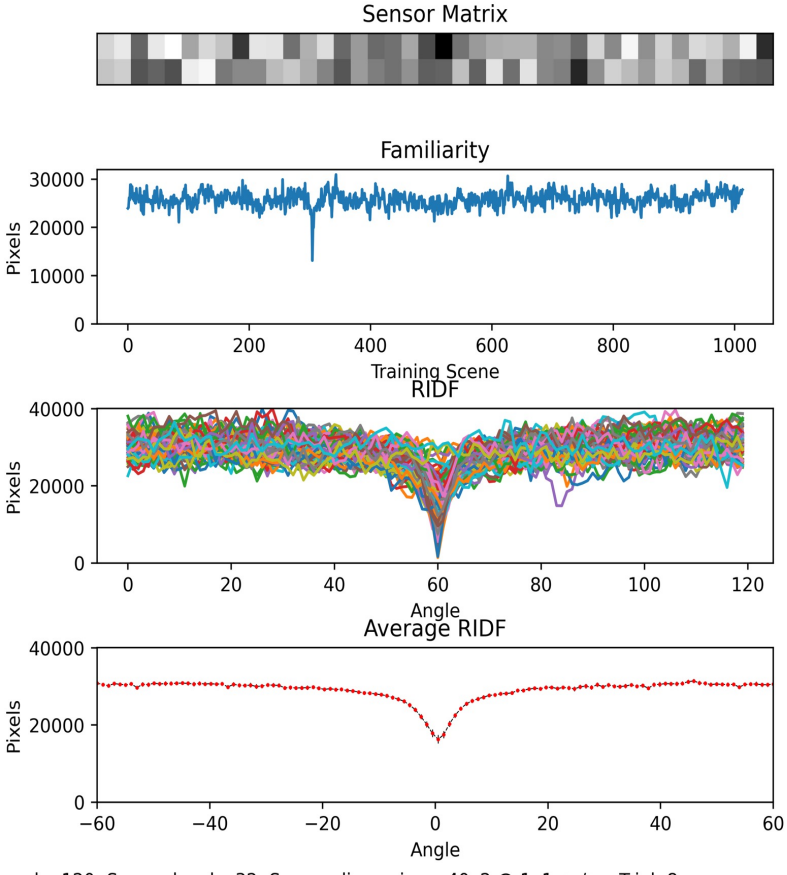


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 9394.28; RMSD/dist: 23.486; TD: -929; p90: 2; p50: 2; complete: 0

100%

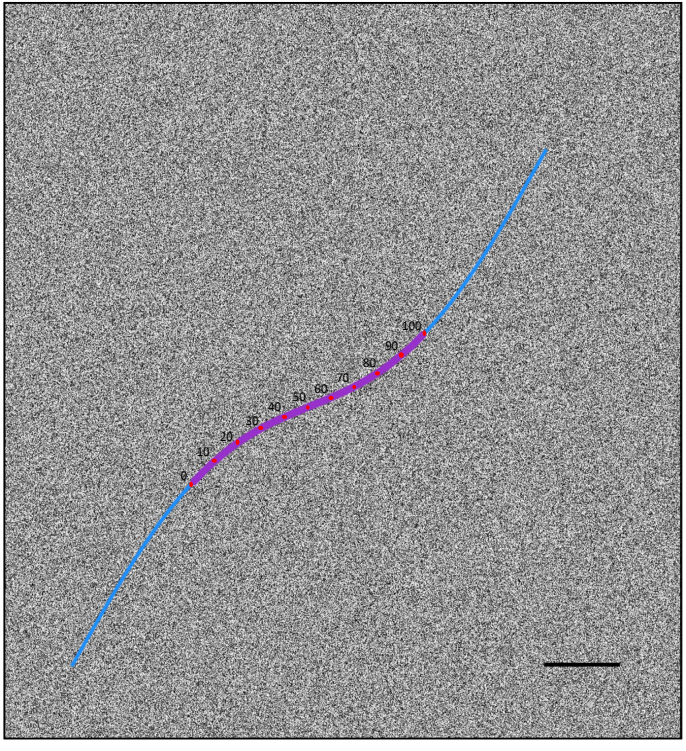


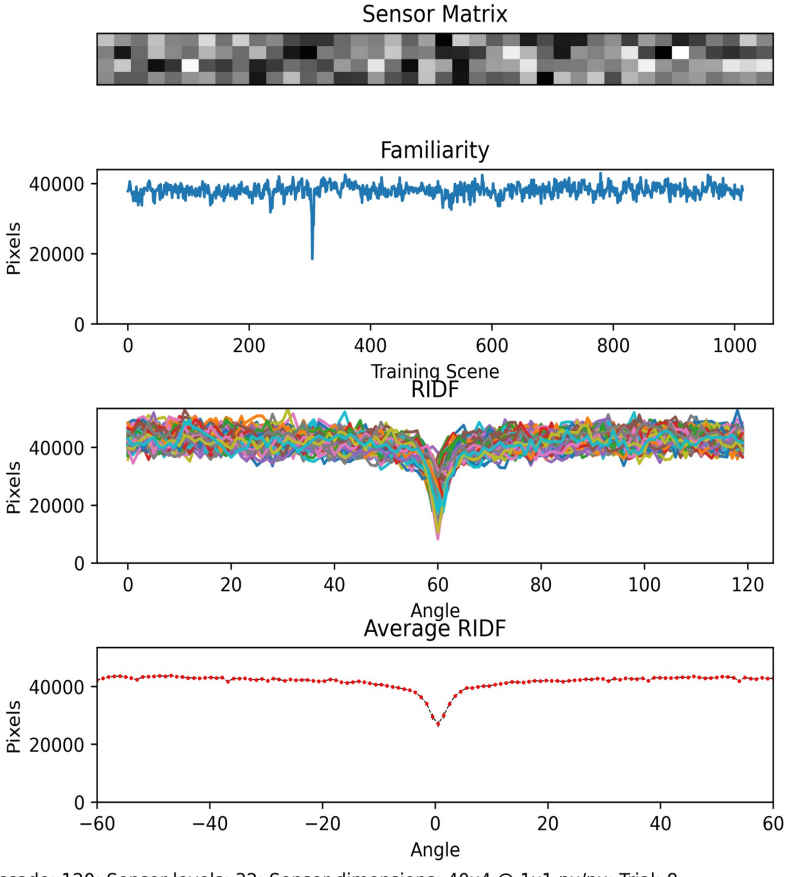


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 59.90; RMSD/dist: 0.150; TD: 9065; p90: 8; p50: 4; complete: 0

100%

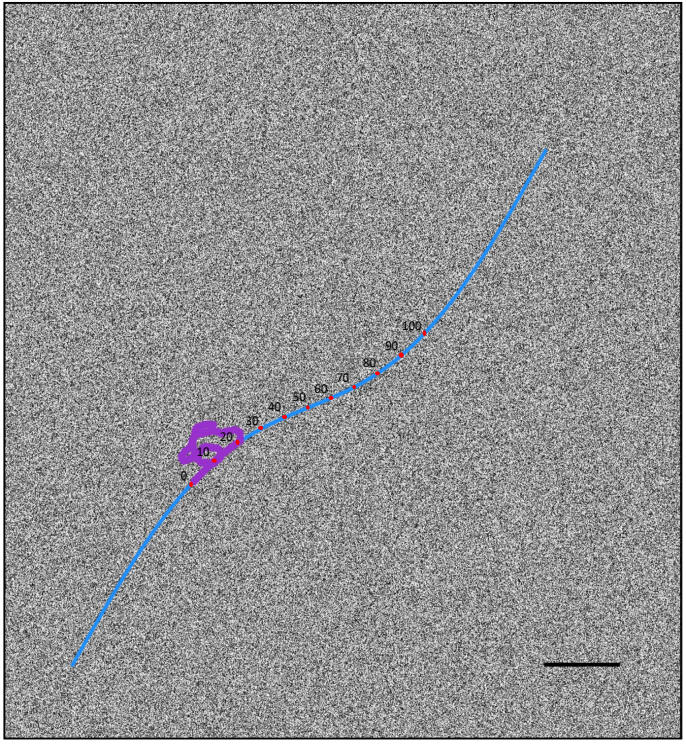


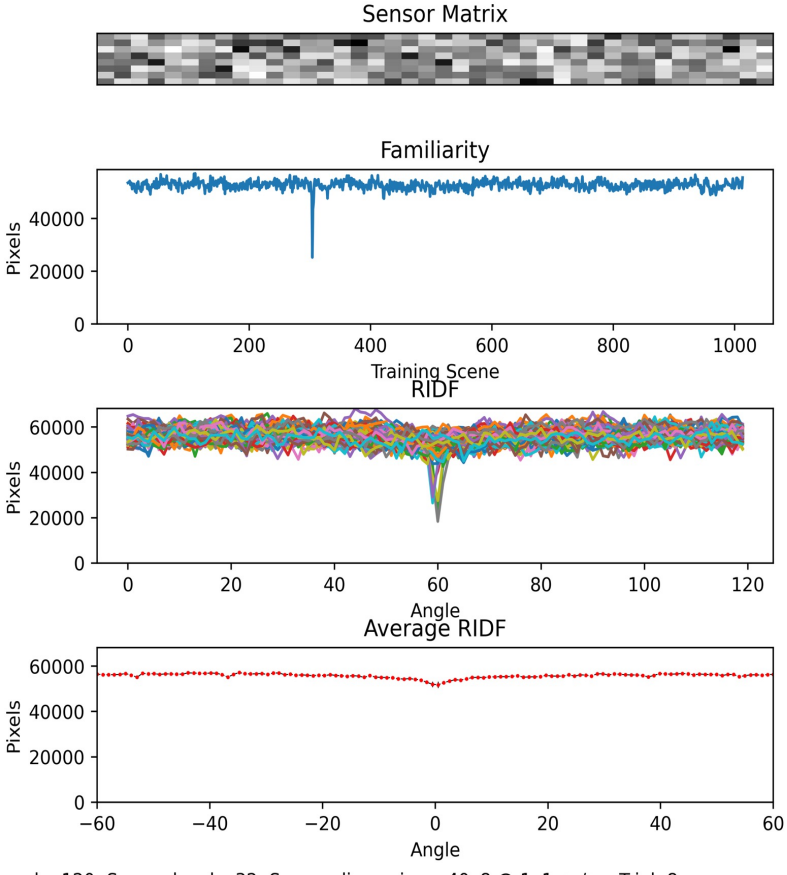


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 72.14; RMSD/dist: 0.180; TD: 10188; p90: 6; p50: 4; complete: 0

0%

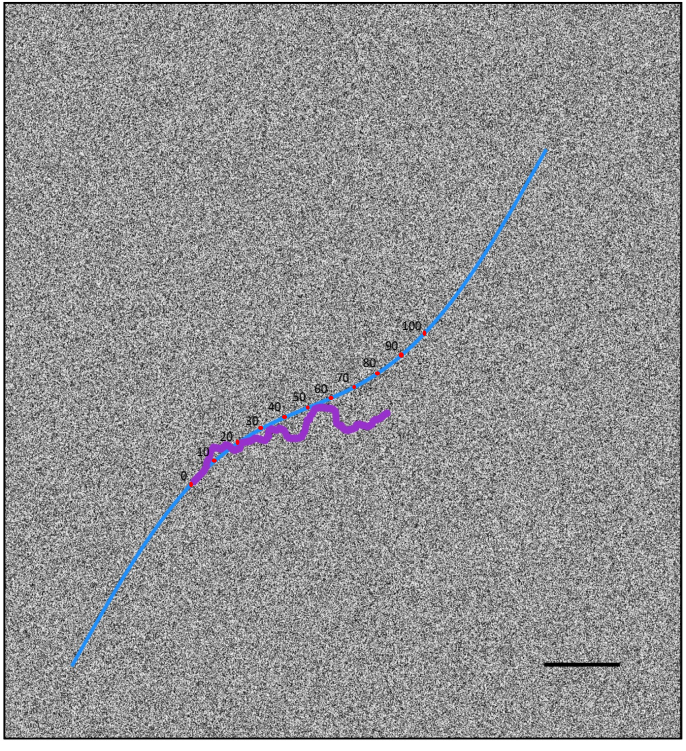


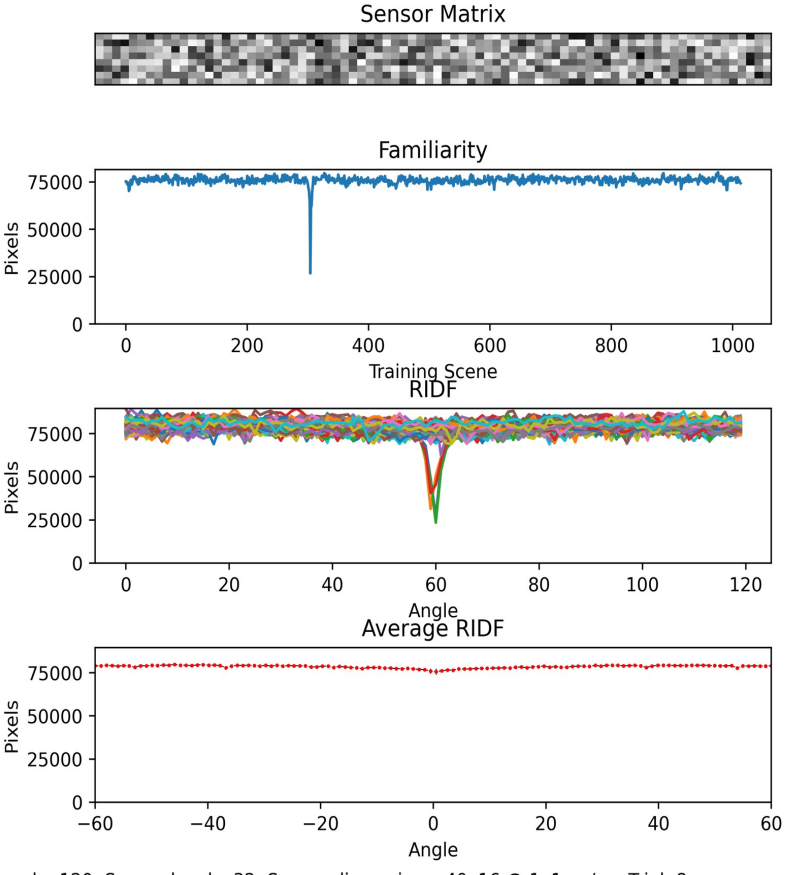


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2142.82; RMSD/dist: 5.357; TD: 694; p90: 2; p50: 2; complete: 0

0%

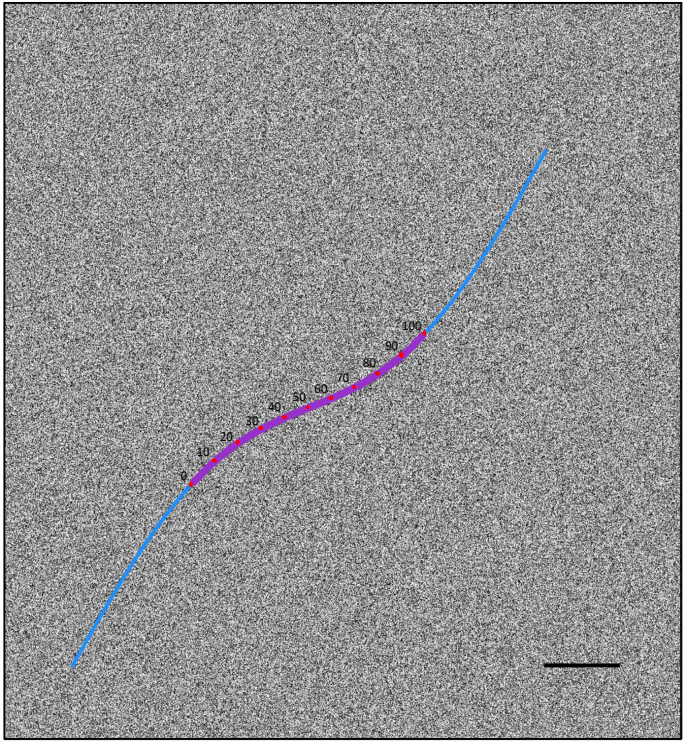


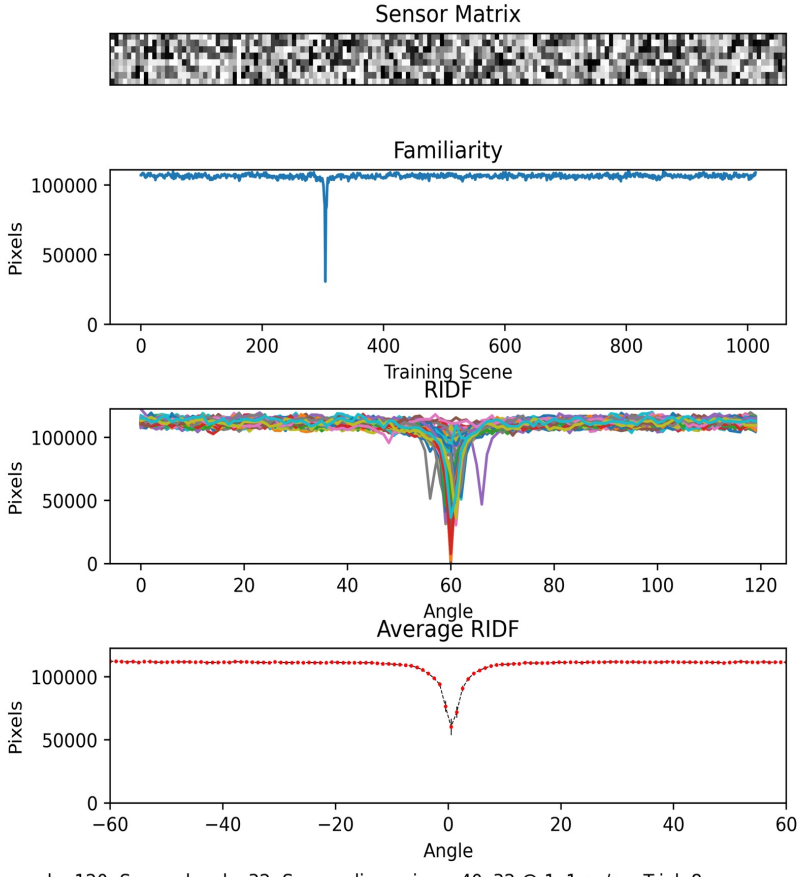


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2096.89; RMSD/dist: 5.242; TD: 53; p90: 2; p50: 2; complete: 0

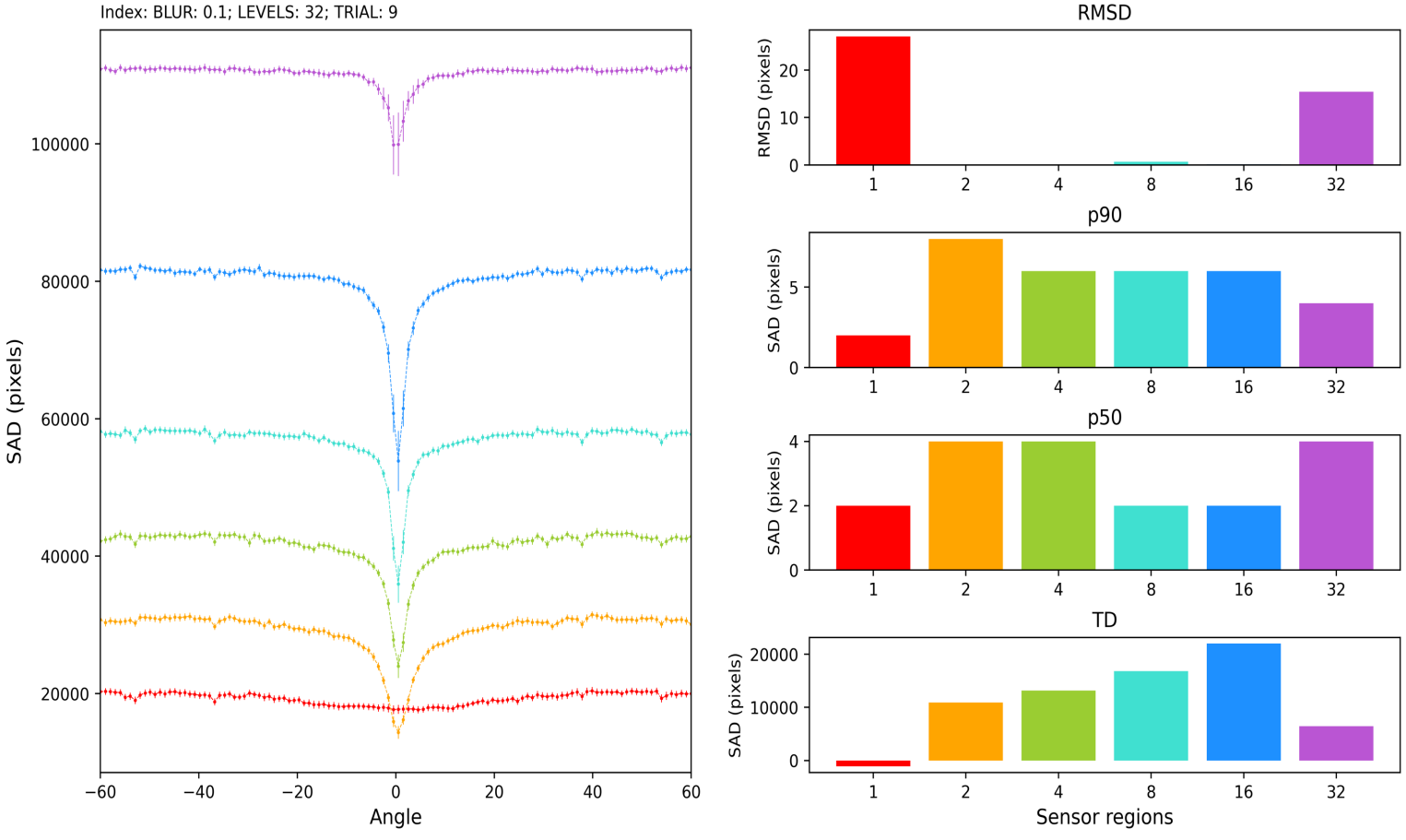
100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 40.51; RMSD/dist: 0.101; TD: 45889; p90: 8; p50: 2; complete: 0


Index: BLUR: 0.1; LEVELS: 32; TRIAL: 9
SAD (pixels)
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60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
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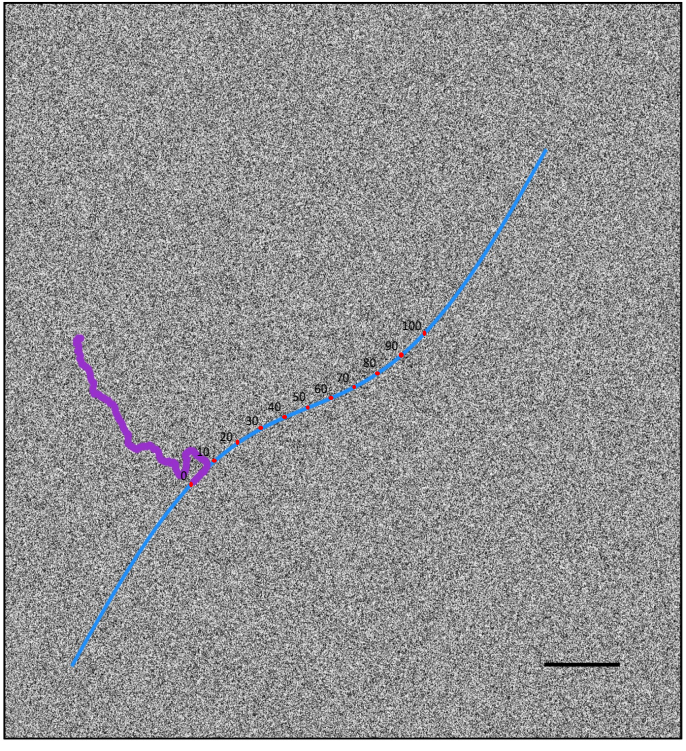
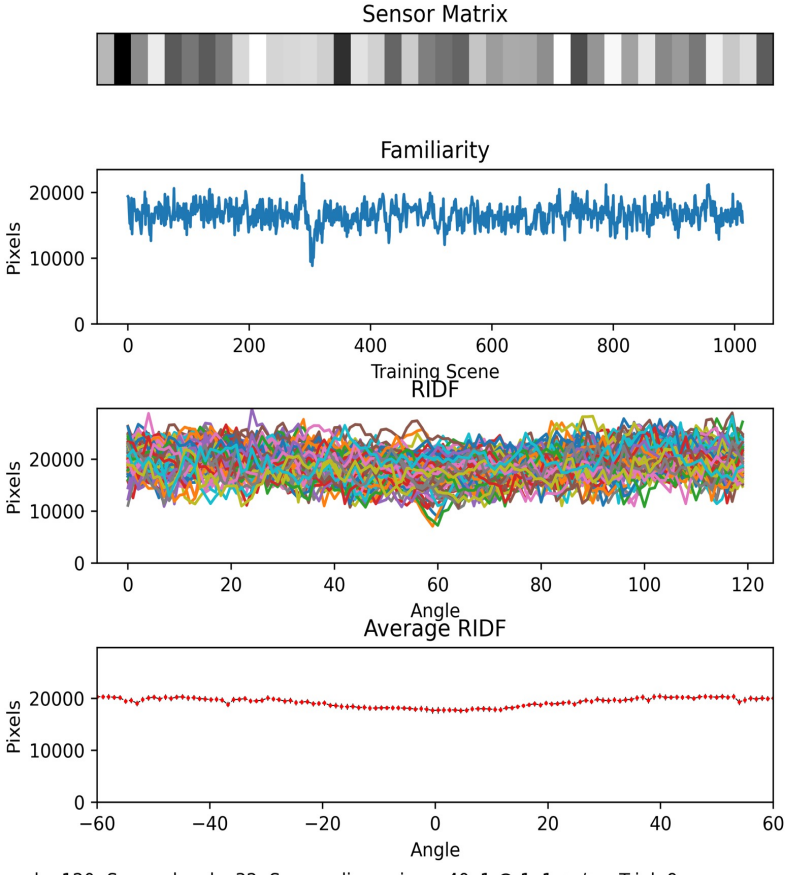
p50
SAD (pixels)
4
2
0
TD
SAD (pixels)
20000
10000
0
Sensor regions

0%

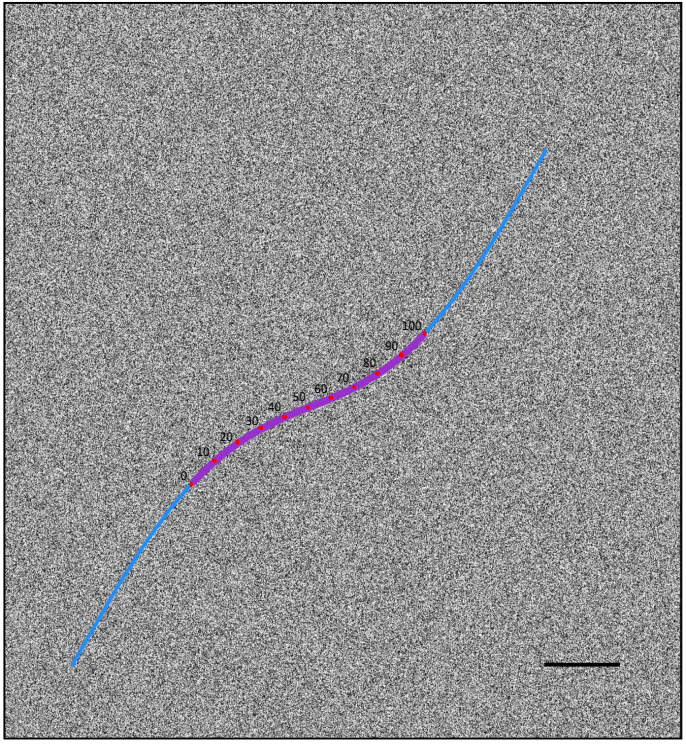


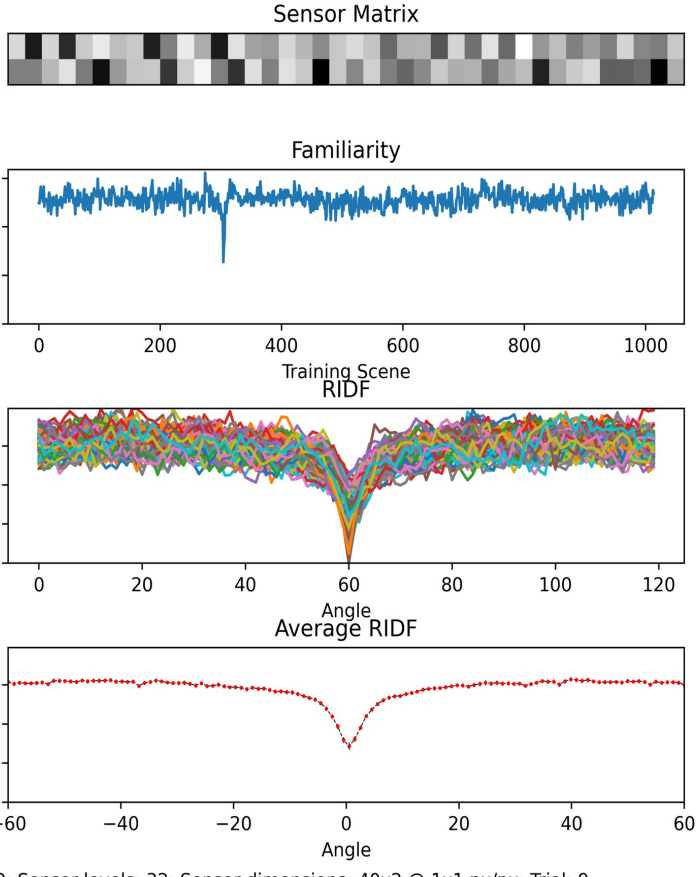


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 10845.55; RMSD/dist: 27.114; TD: -1097; p90: 2; p50: 2; complete: 0

100%

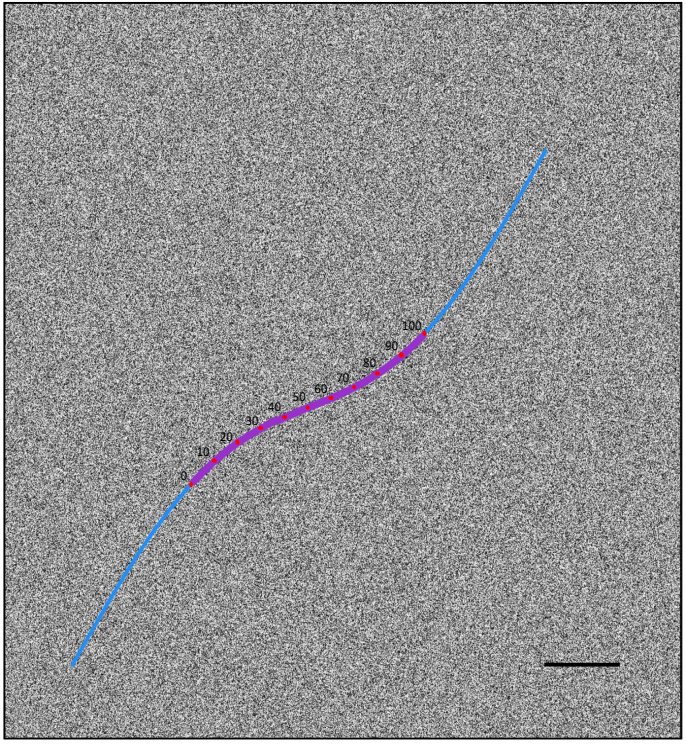


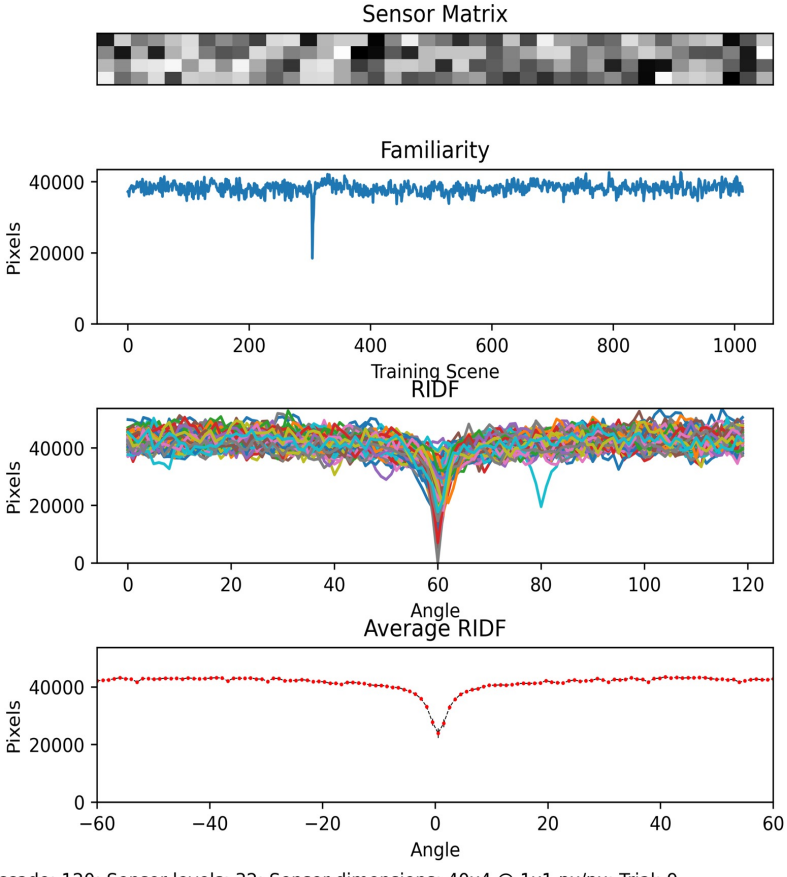


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 31.89; RMSD/dist: 0.080; TD: 10900; p90: 8; p50: 4; complete: 0

100%

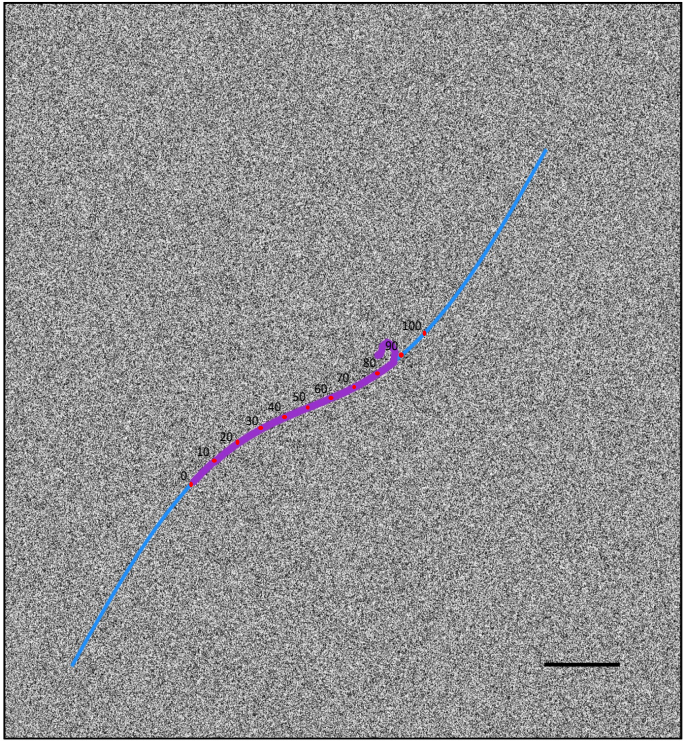


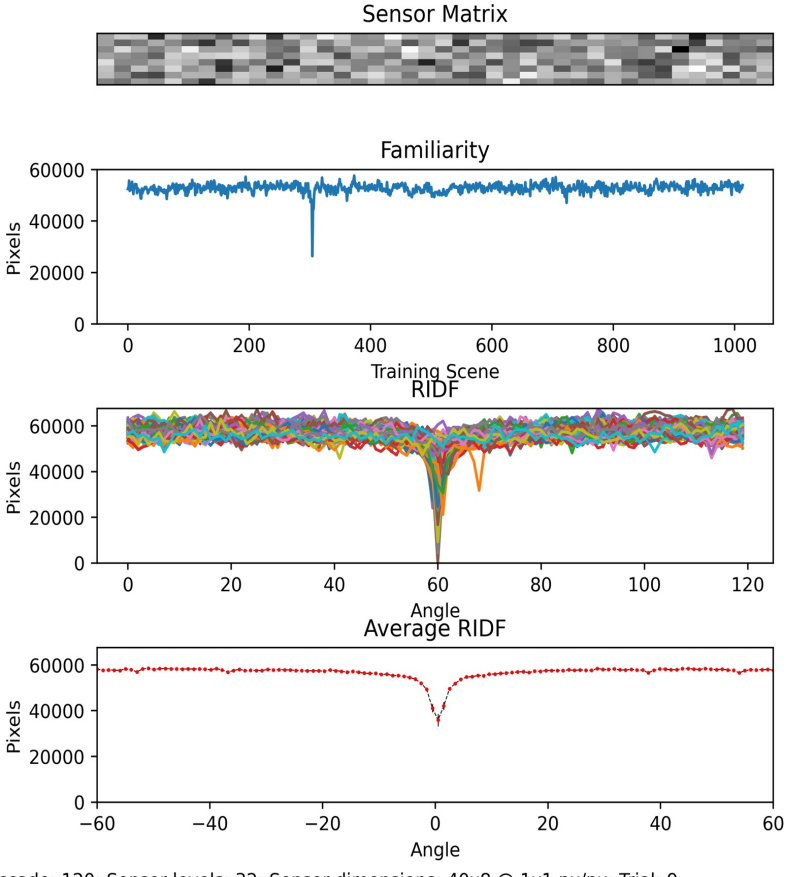


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 47.54; RMSD/dist: 0.119; TD: 13134; p90: 6; p50: 4; complete: 0

80%

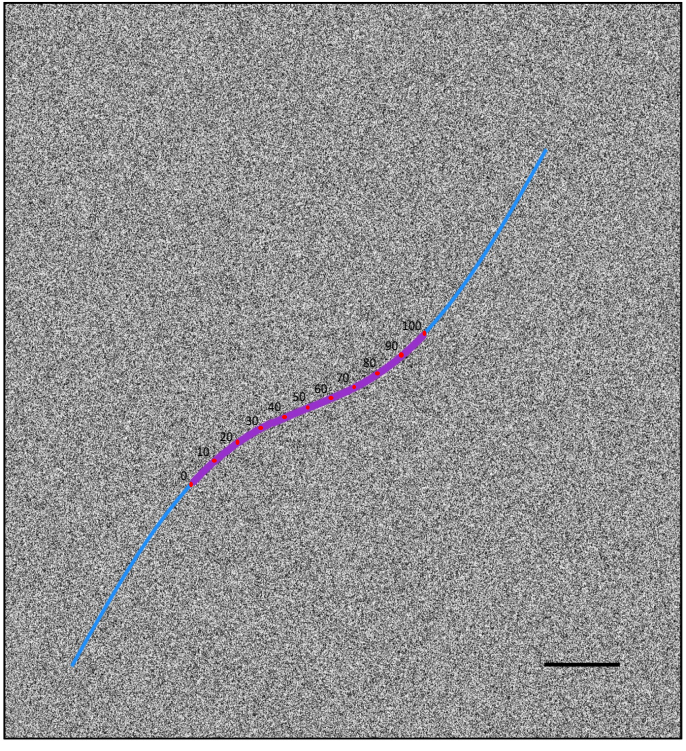


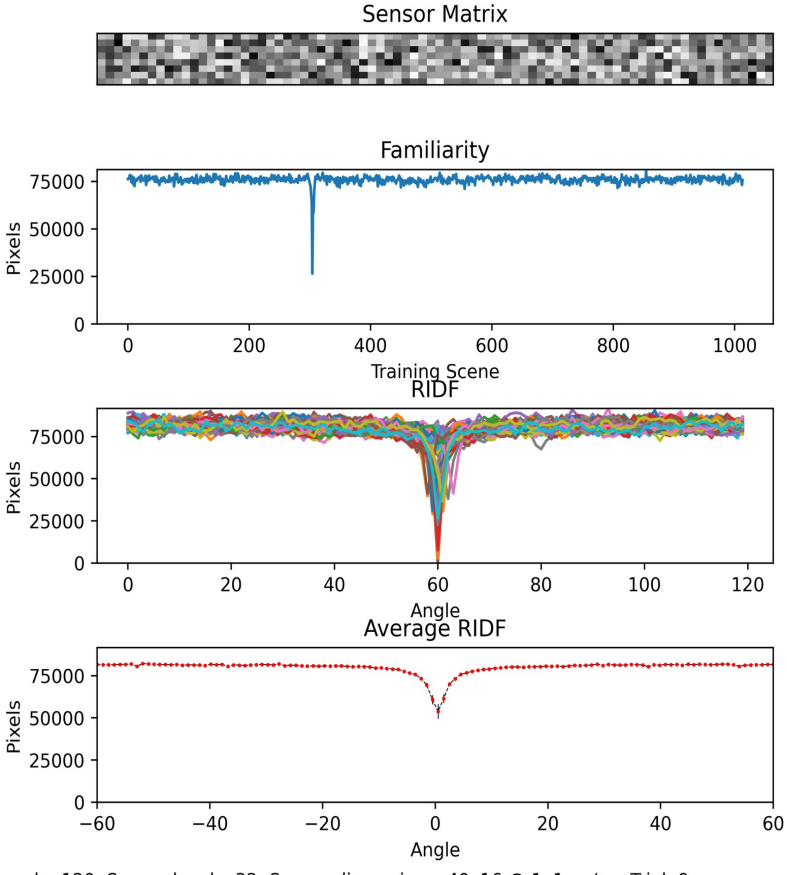


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 276.14; RMSD/dist: 0.690; TD: 16809; p90: 6; p50: 2; complete: 0

0%

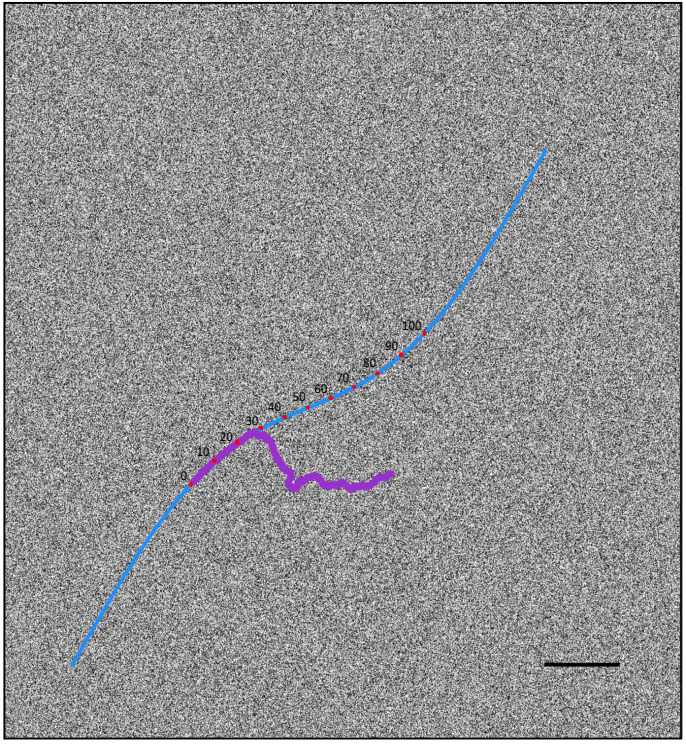


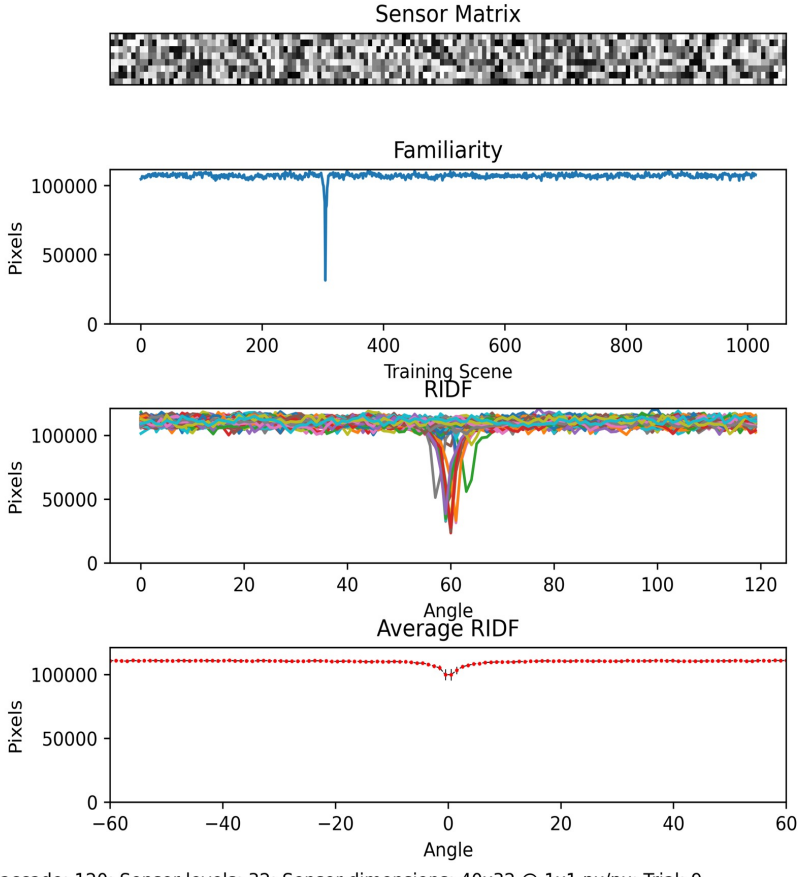


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 55.74; RMSD/dist: 0.139; TD: 21995; p90: 6; p50: 2; complete: 0

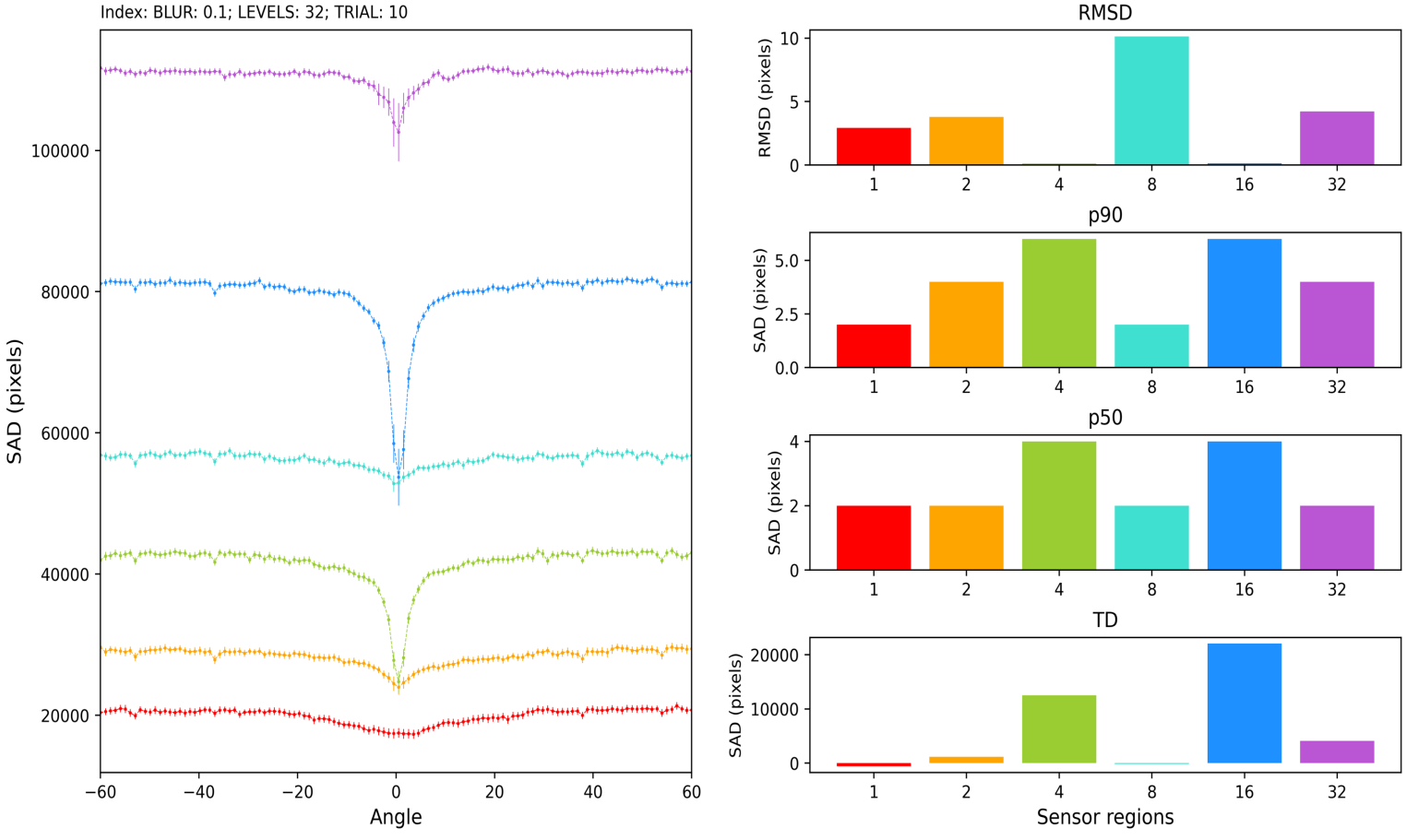
20%



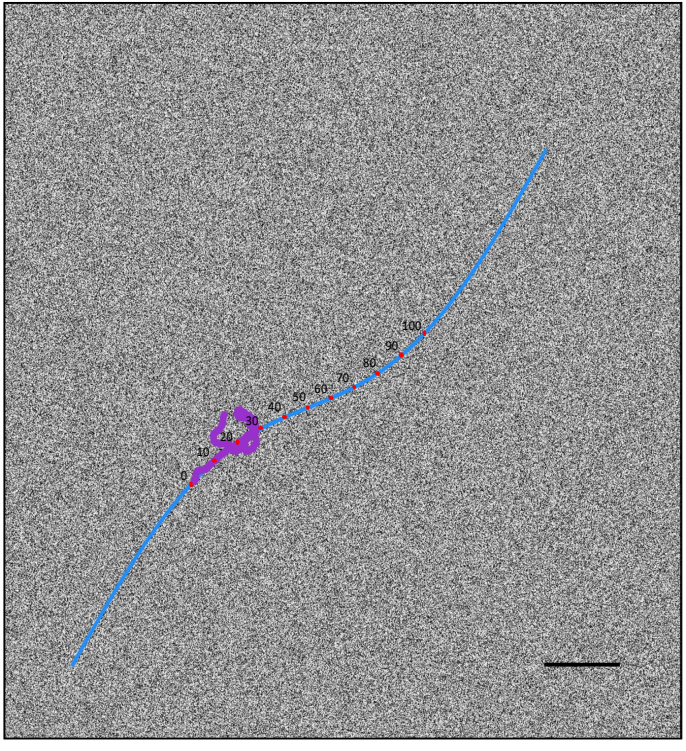


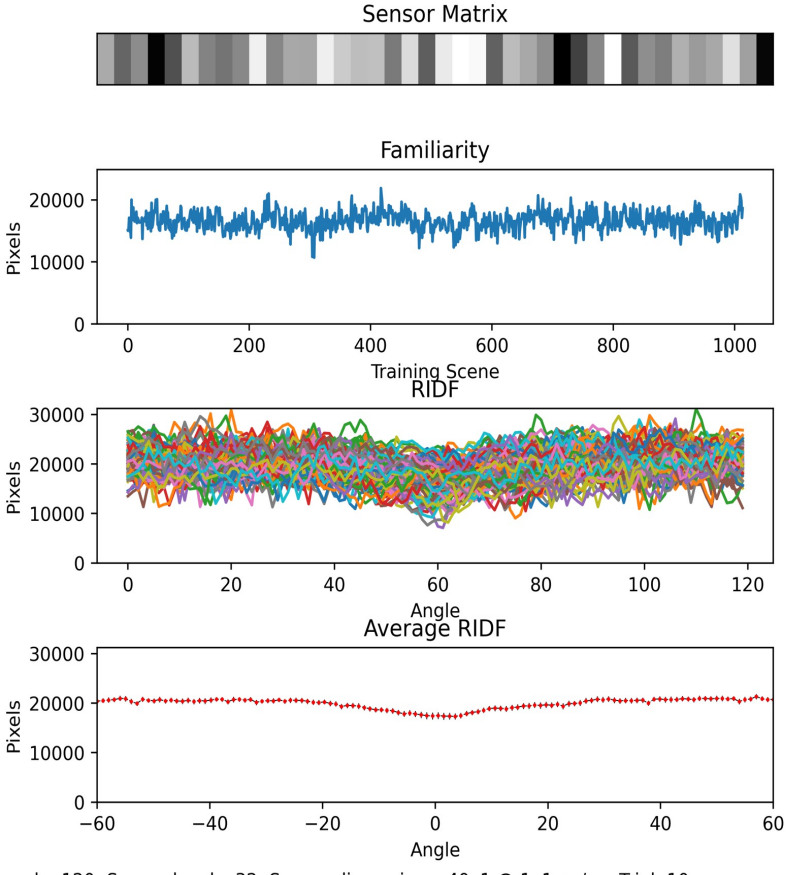
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 6177.45; RMSD/dist: 15.444; TD: 6469; p90: 4; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 32; TRIAL: 10
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
4
2
TD
20000
10000
Sensor regions

20%

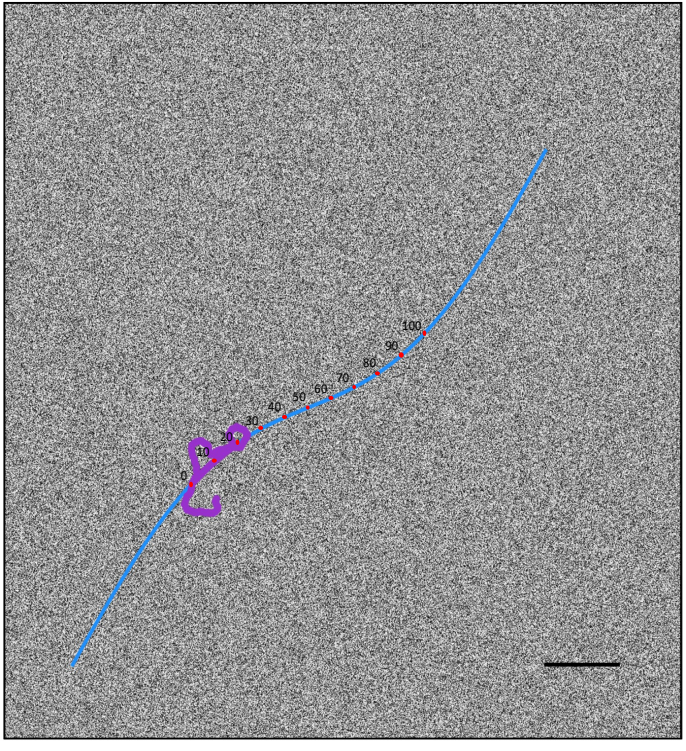


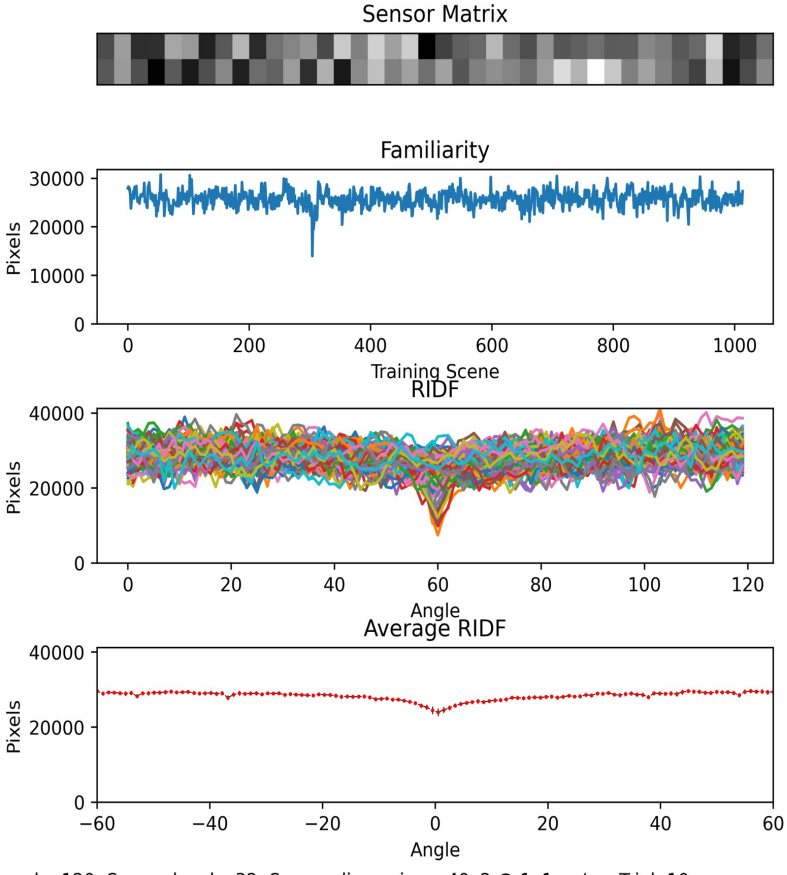


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1168.41; RMSD/dist: 2.921; TD: -591; p90: 2; p50: 2; complete: 0

20%

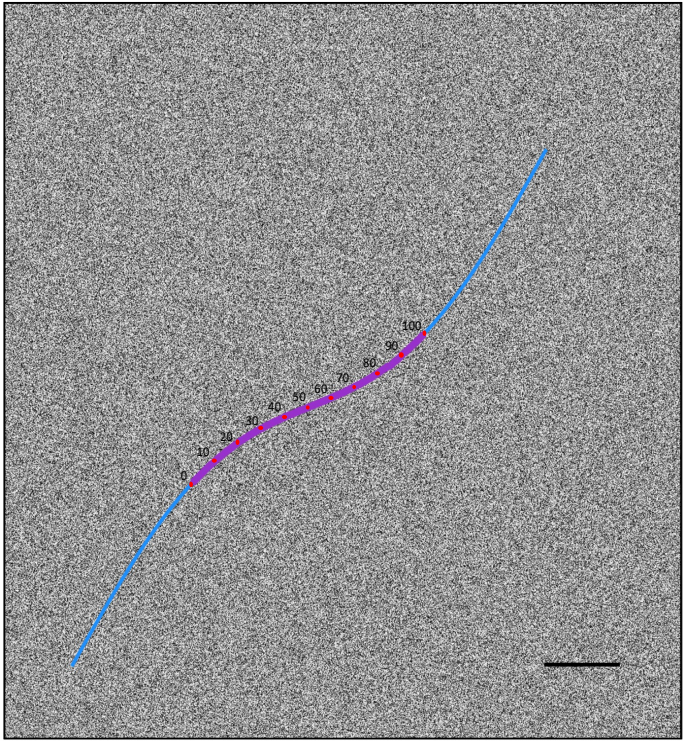


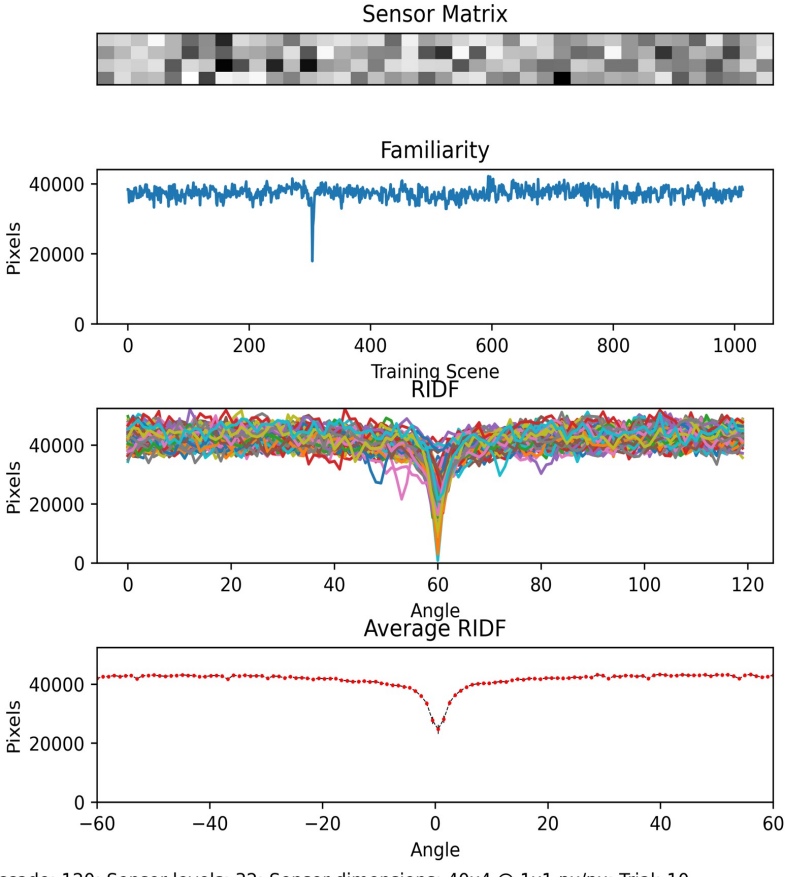


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1512.54; RMSD/dist: 3.781; TD: 1137; p90: 4; p50: 2; complete: 0

100%

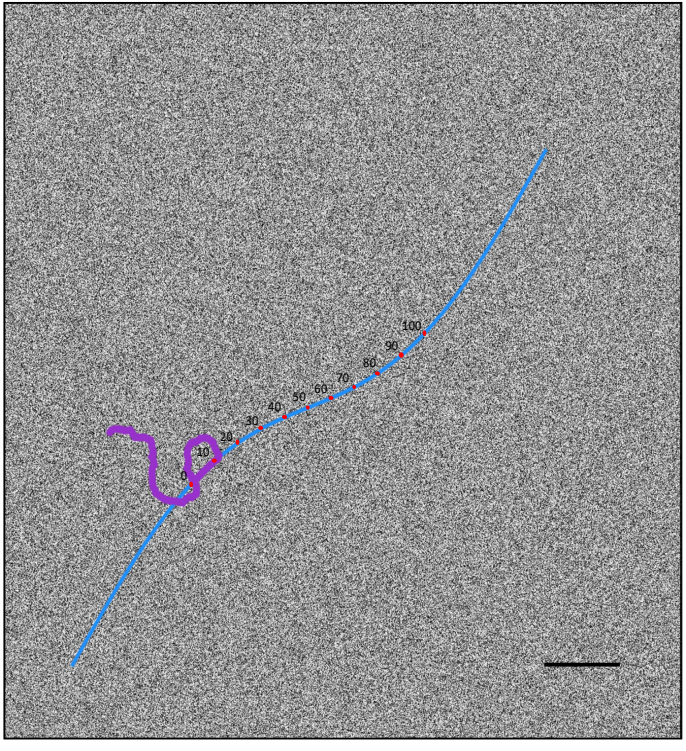


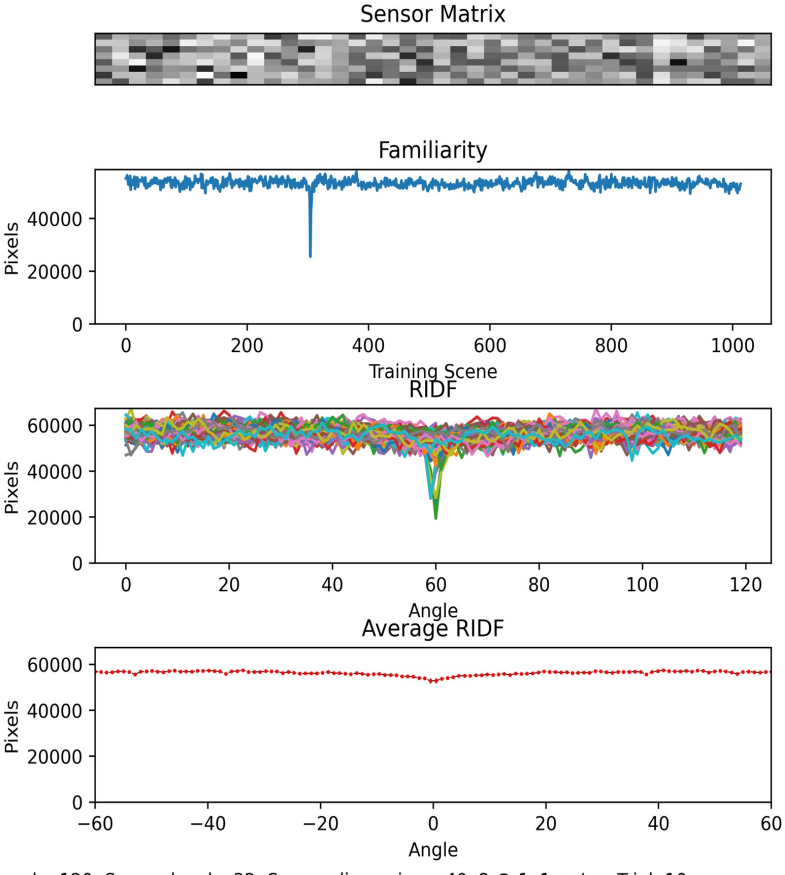


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 48.78; RMSD/dist: 0.122; TD: 12495; p90: 6; p50: 4; complete: 0

10%

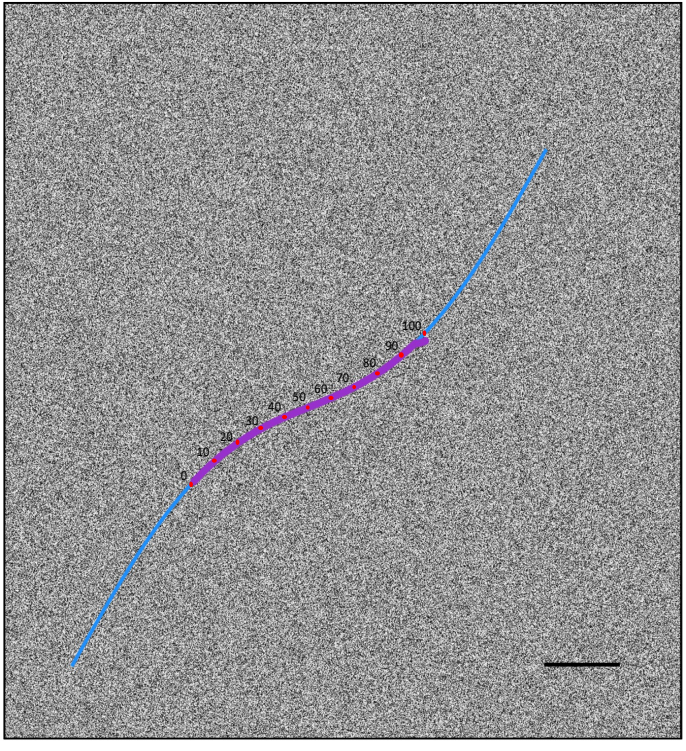


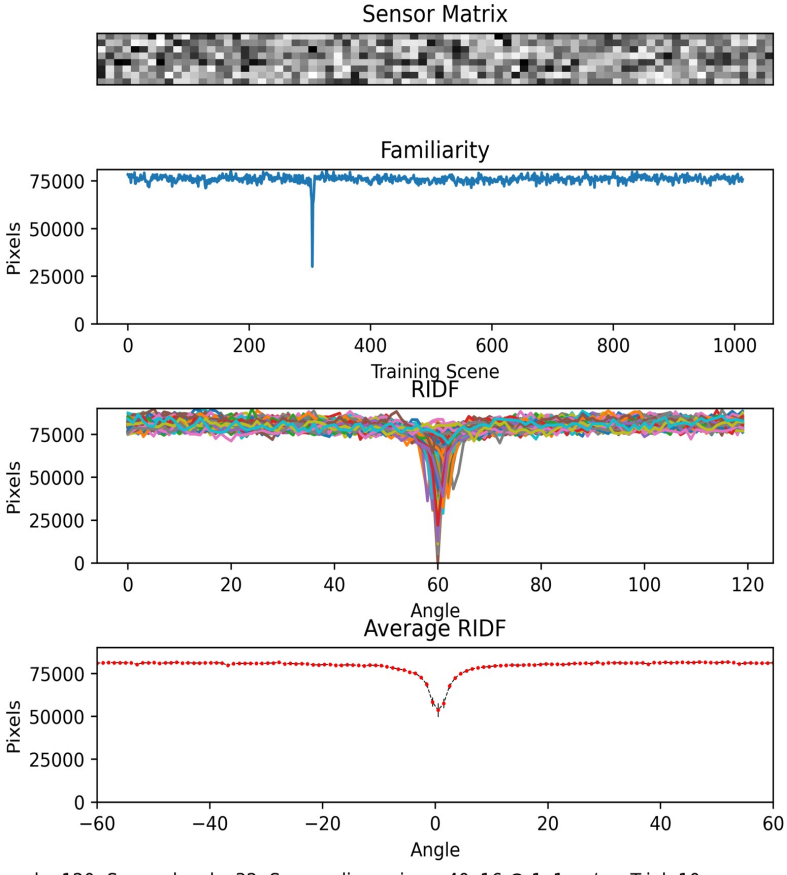


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4053.94; RMSD/dist: 10.135; TD: -161; p90: 2; p50: 2; complete: 0

90%

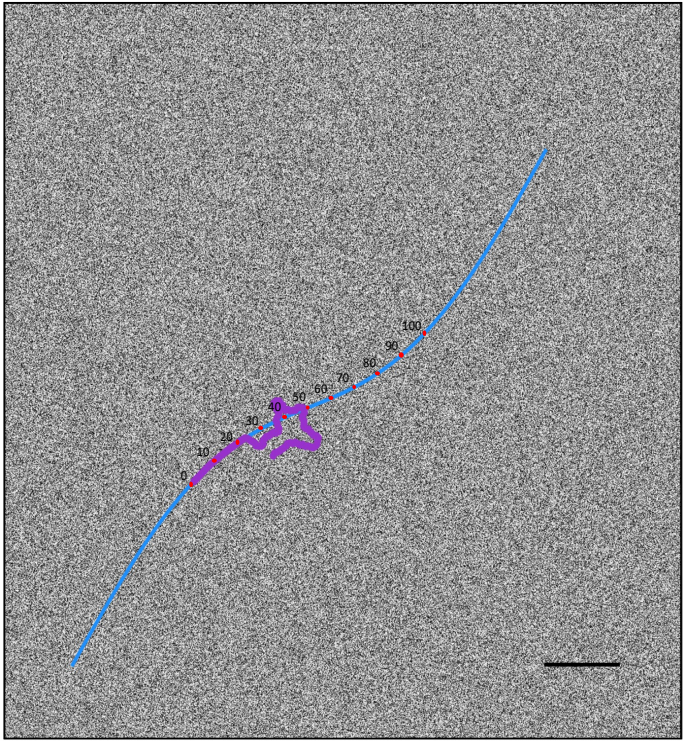


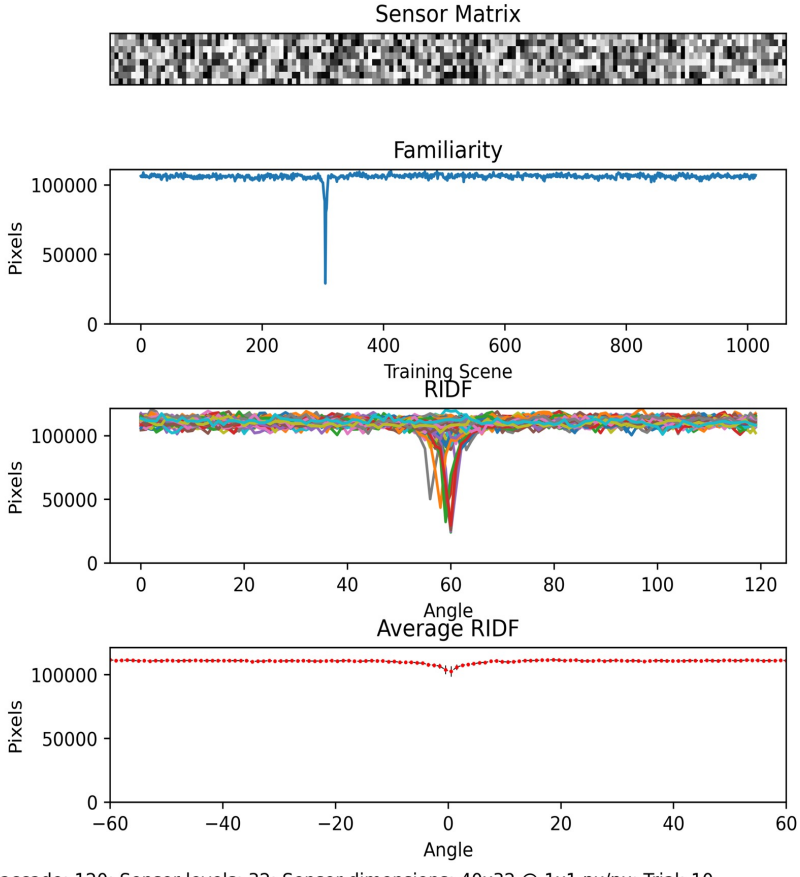


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 57.08; RMSD/dist: 0.143; TD: 22060; p90: 6; p50: 4; complete: 0

20%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1690.06; RMSD/dist: 4.225; TD: 4105; p90: 4; p50: 2; complete: 0