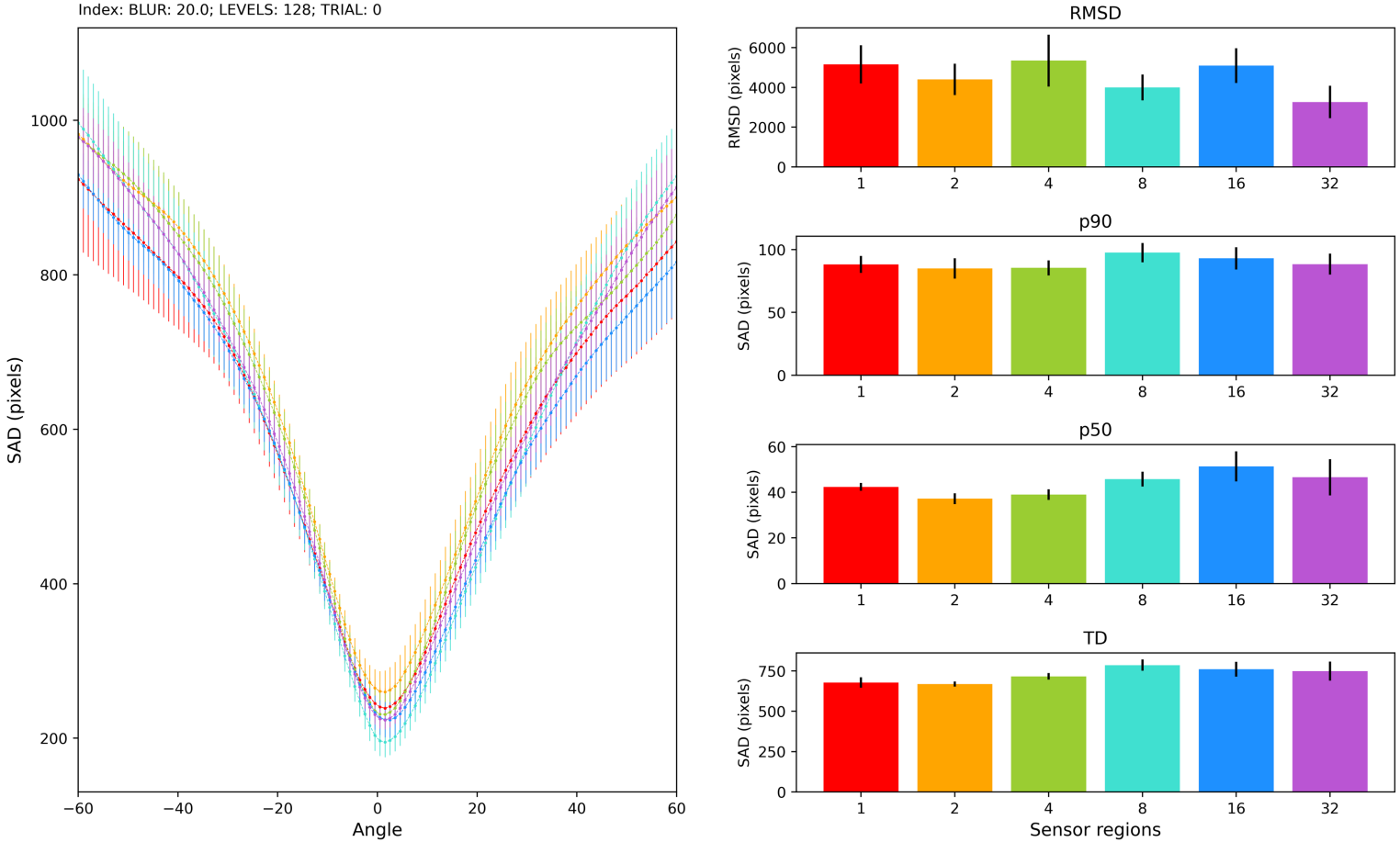
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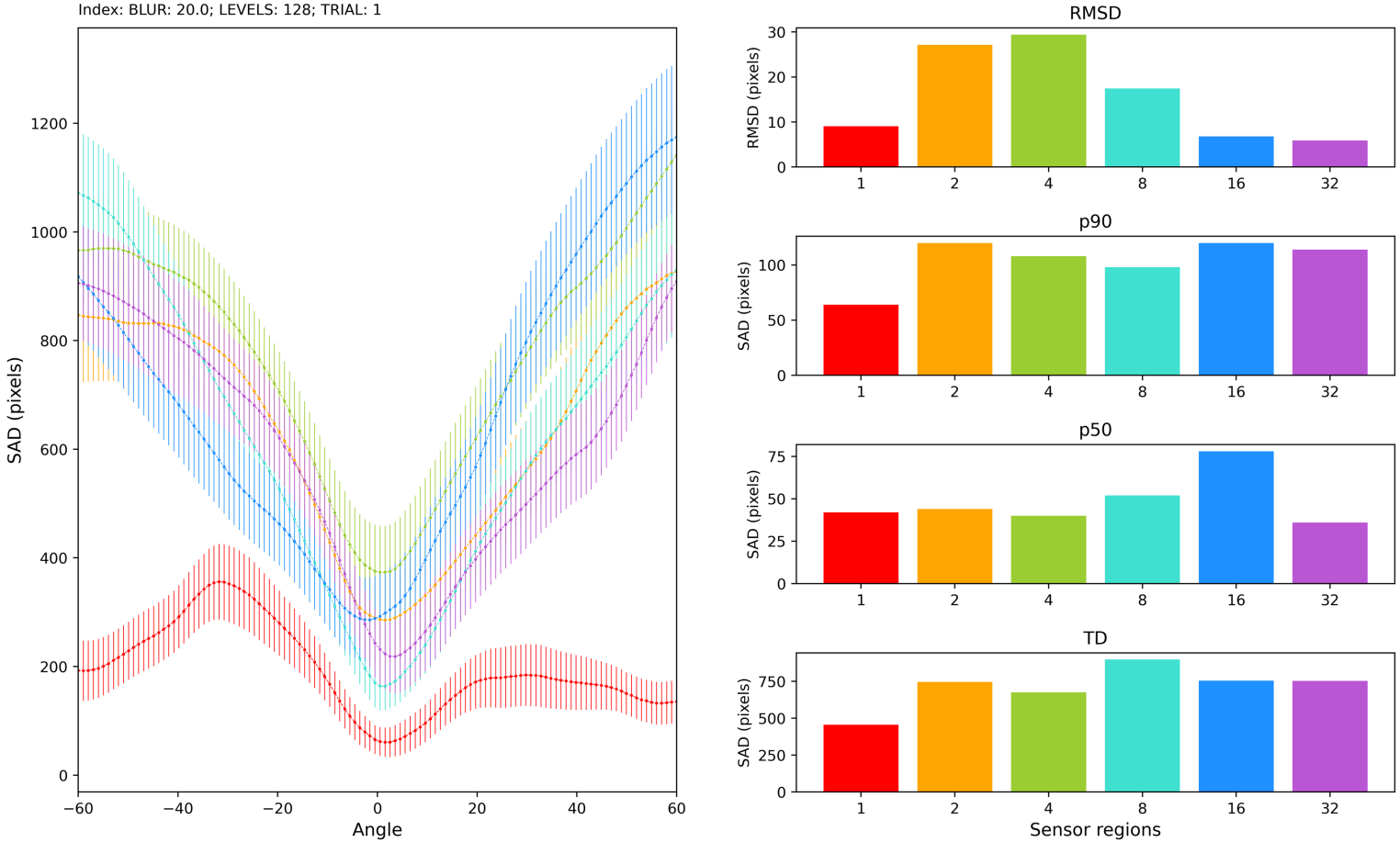
1000
800
600
400
200
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
6000
4000
2000
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
60
40
20
TD
750
500
250
Sensor regions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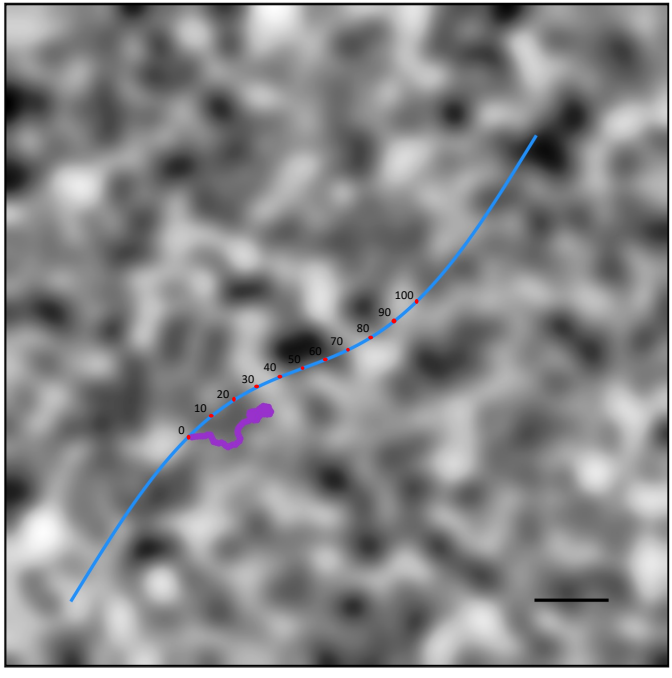
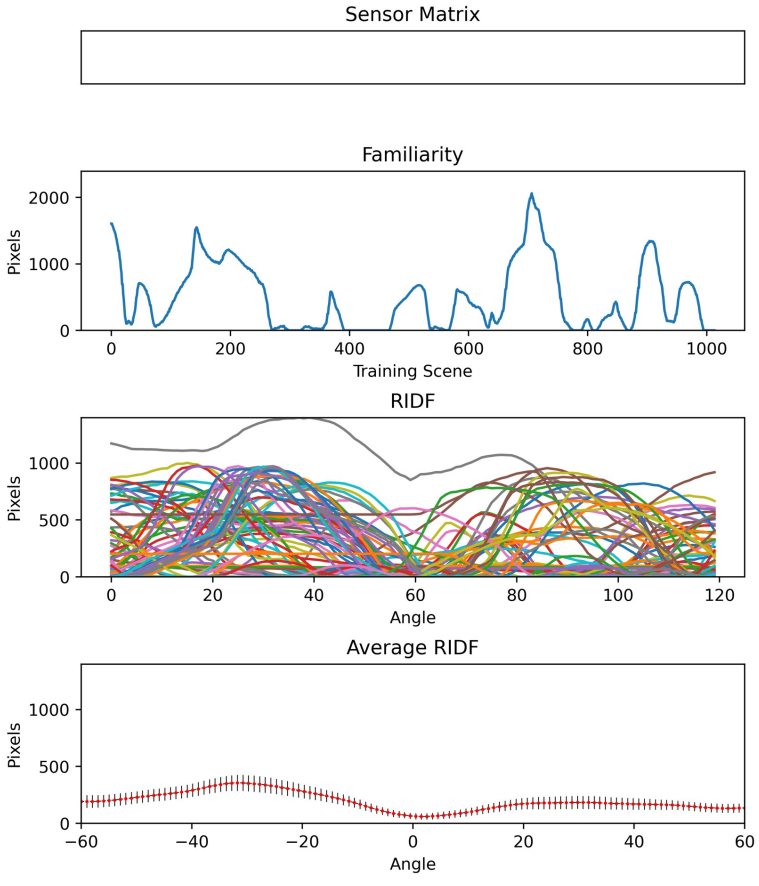
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

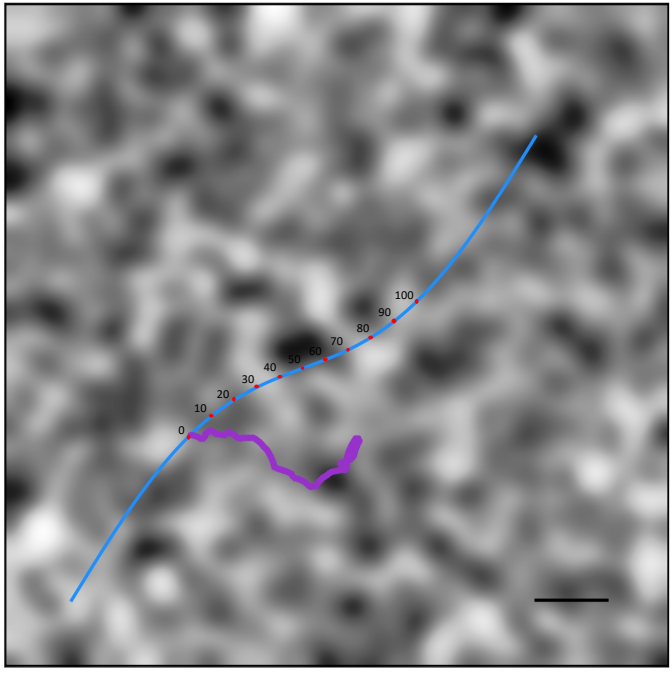


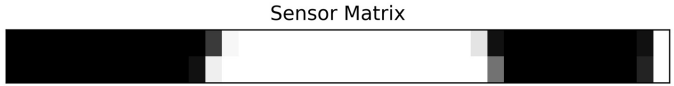


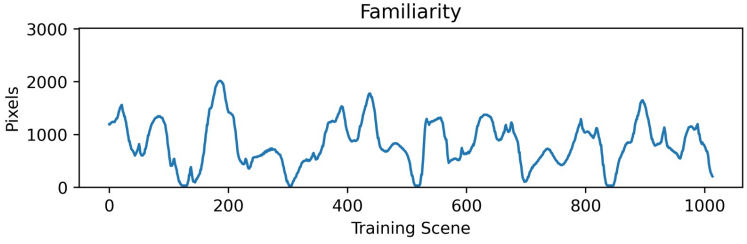
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

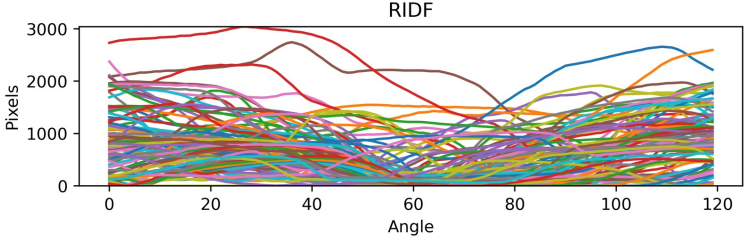
Navigation stats: RMSD error: 3623.82; RMSD/dist: 9.060; TD: 456; p90: 64; p50: 42; complete: 0

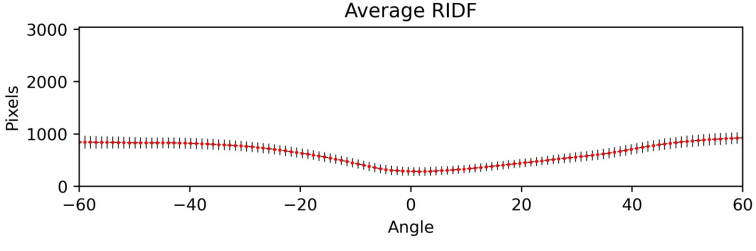
0%







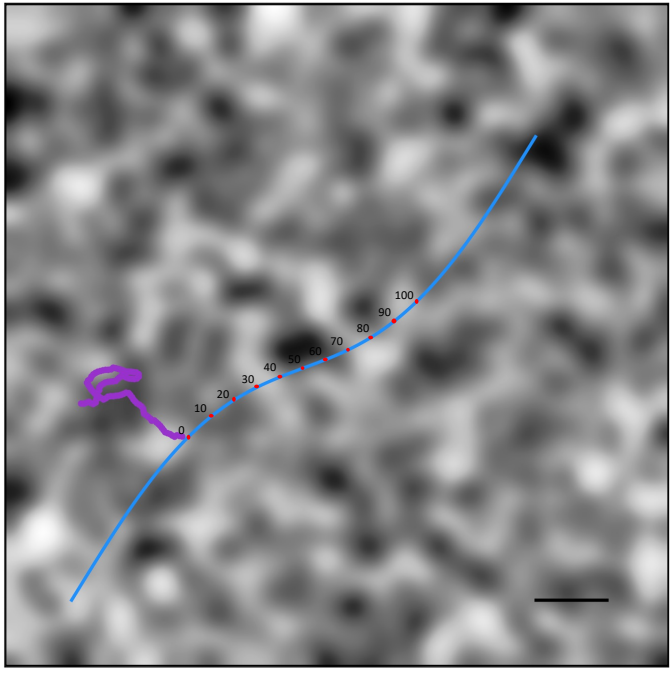


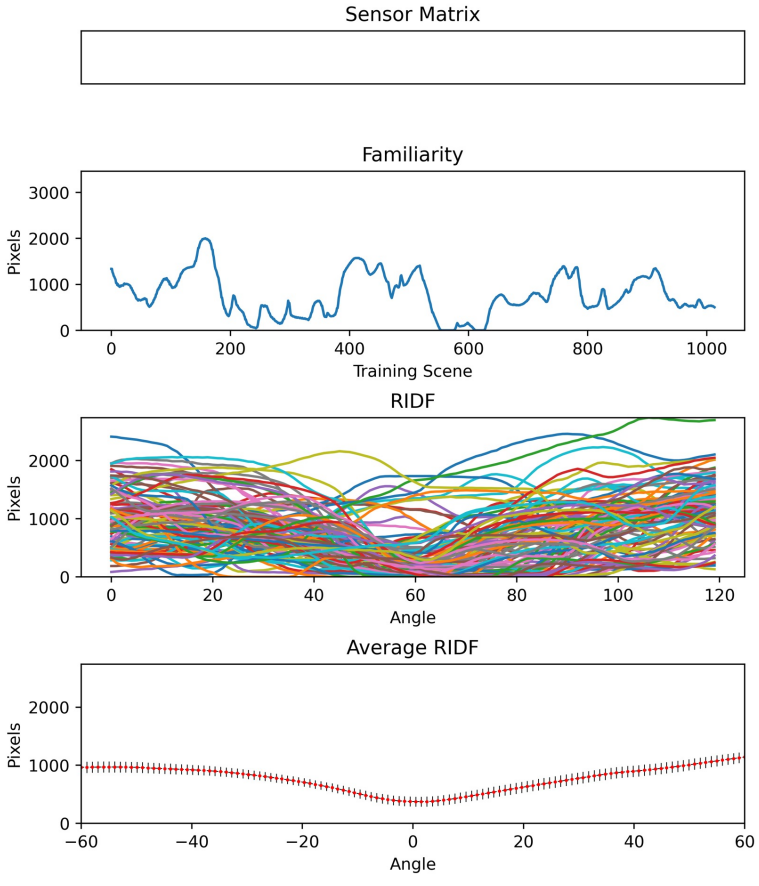


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 10864.82; RMSD/dist: 27.162; TD: 746; p90: 120; p50: 44; complete: 0

0%

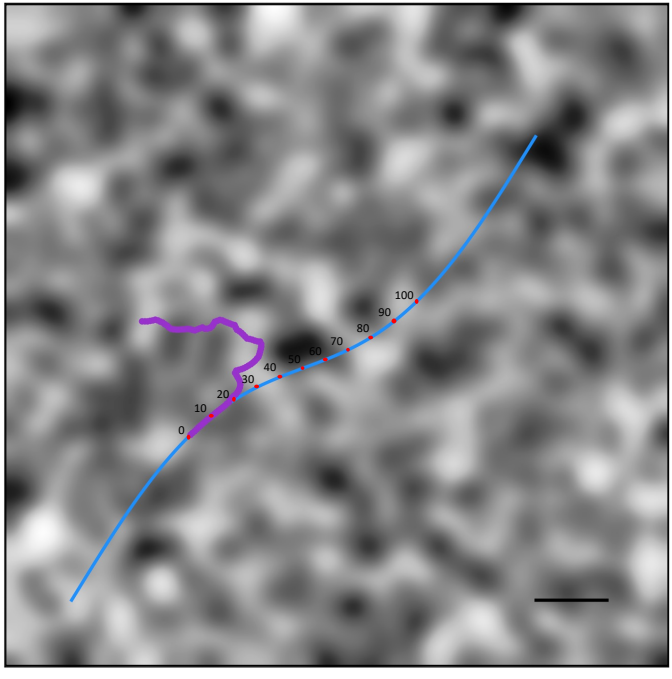


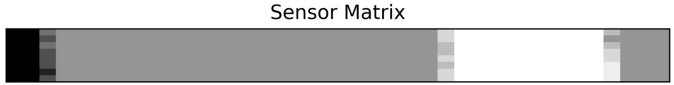


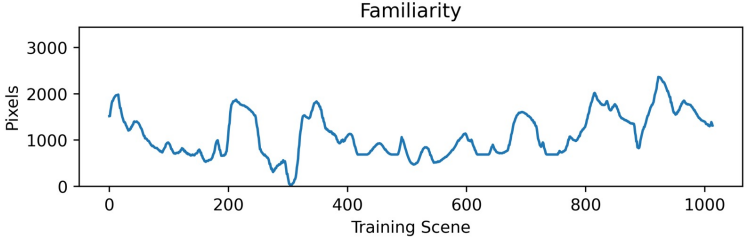
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

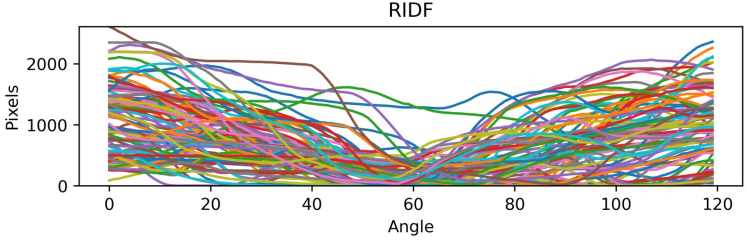
Navigation stats: RMSD error: 11772.41; RMSD/dist: 29.431; TD: 675; p90: 108; p50: 40; complete: 0

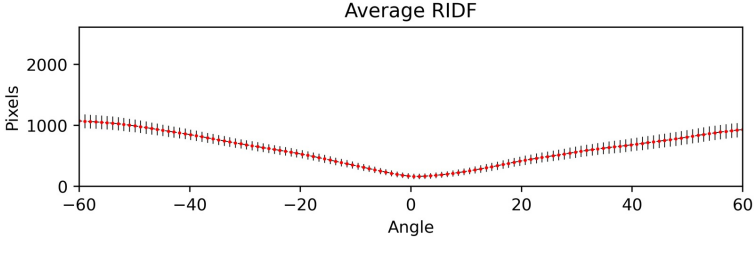
20%







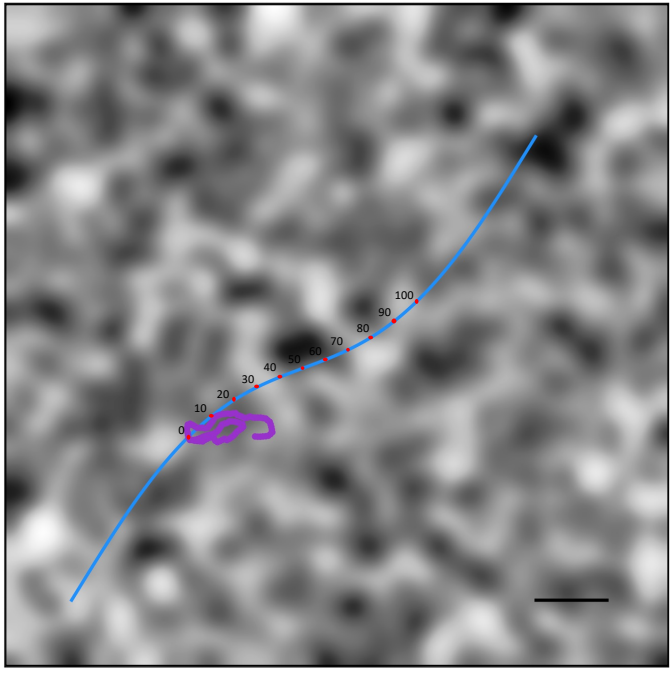


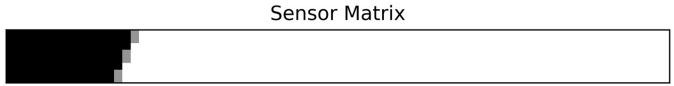


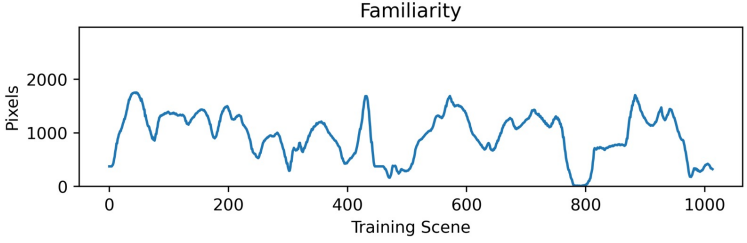
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

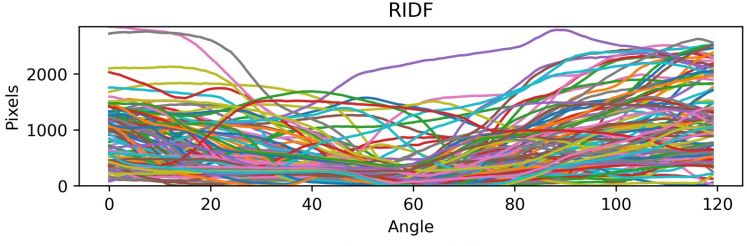
Navigation stats: RMSD error: 6972.66; RMSD/dist: 17.432; TD: 898; p90: 98; p50: 52; complete: 0

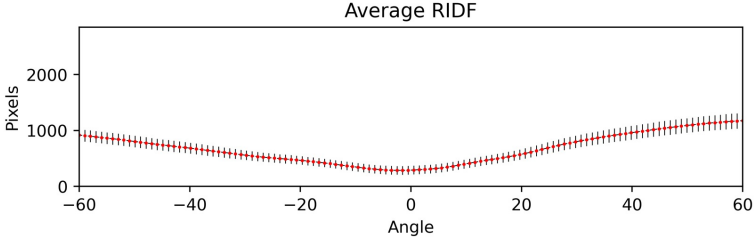
0%







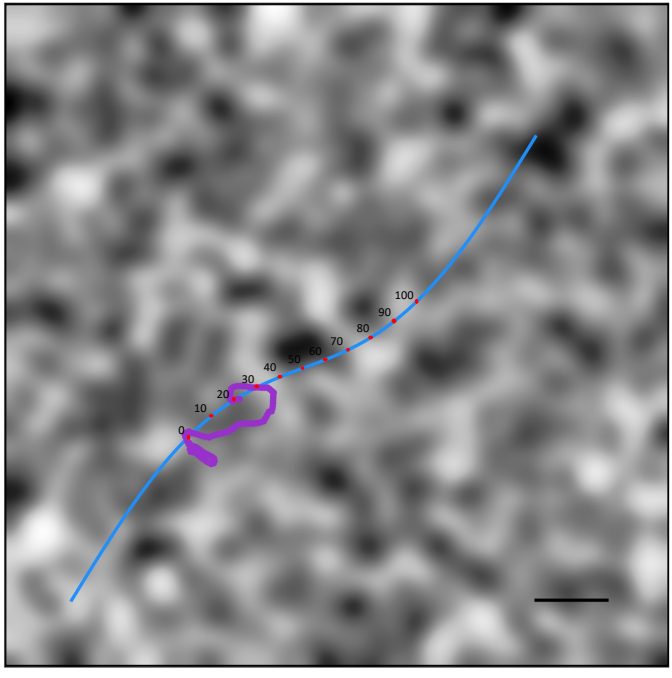


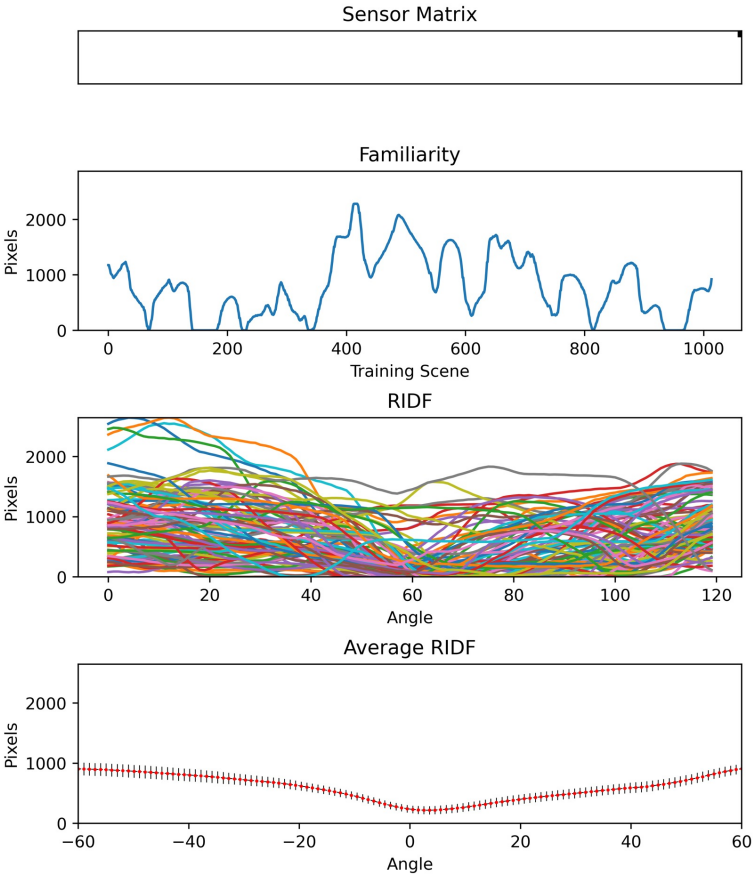


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2710.67; RMSD/dist: 6.777; TD: 755; p90: 120; p50: 78; complete: 0

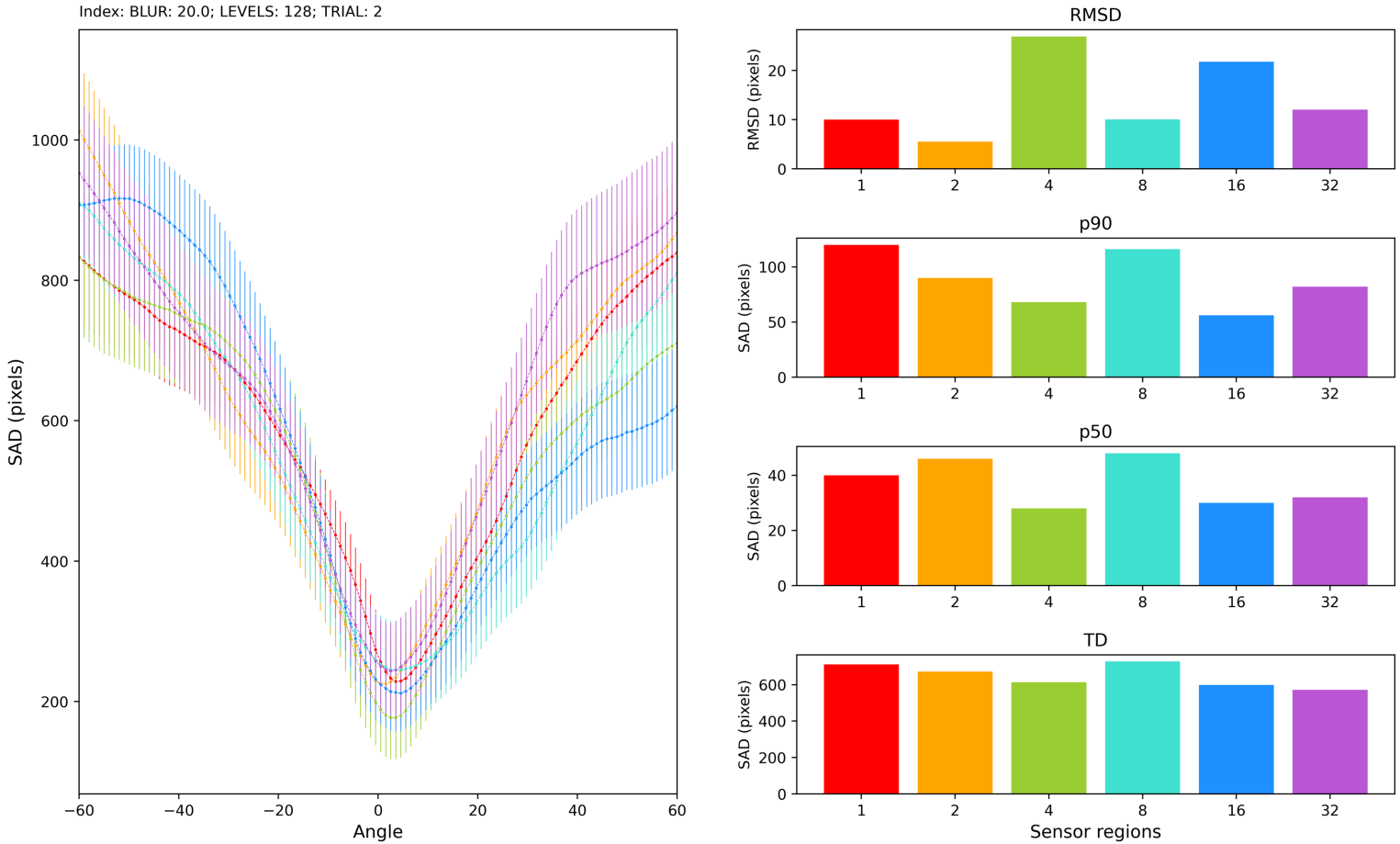
0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2360.37; RMSD/dist: 5.901; TD: 754; p90: 114; p50: 36; complete: 0


Index: BLUR: 20.0; LEVELS: 128; TRIAL: 2
SAD (pixels)
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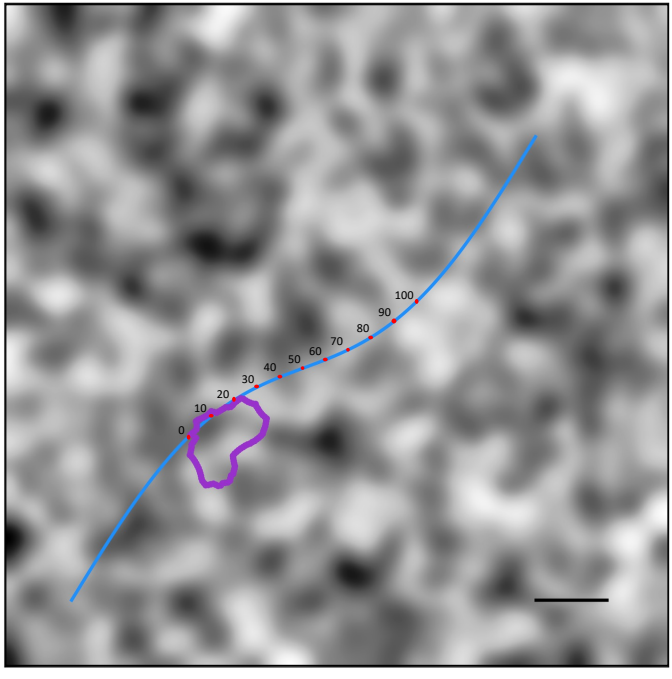
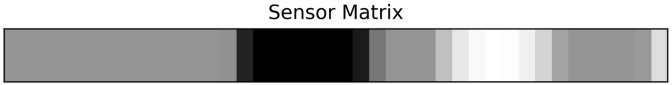
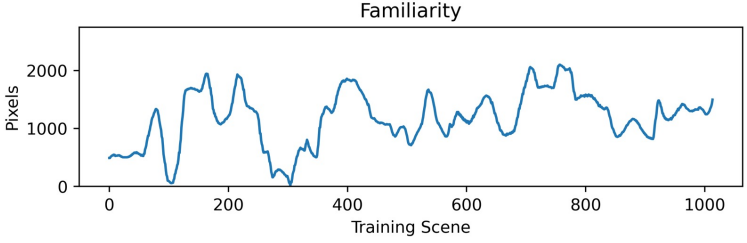
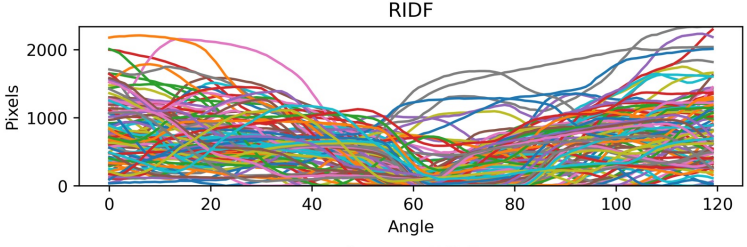
800
600
400
200
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
40
20
TD
600
400
200
Sensor regions

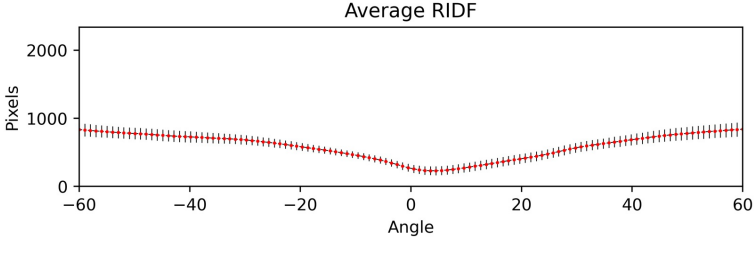
0%







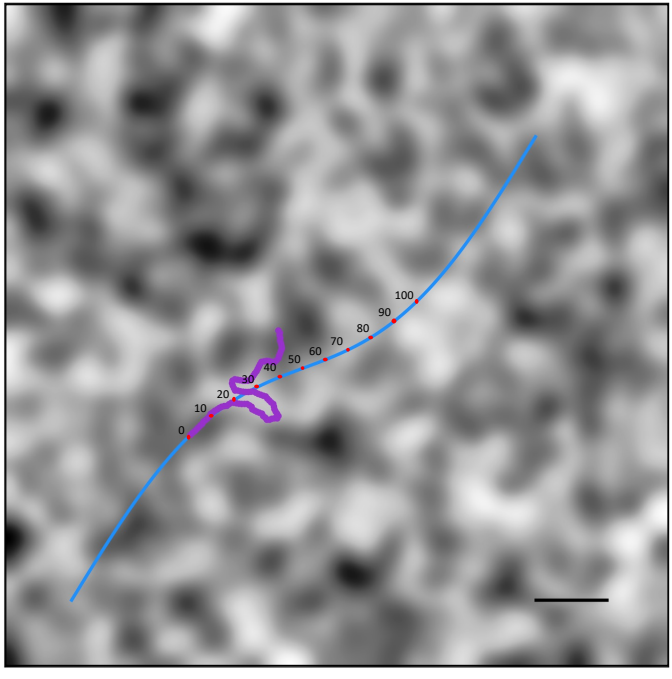


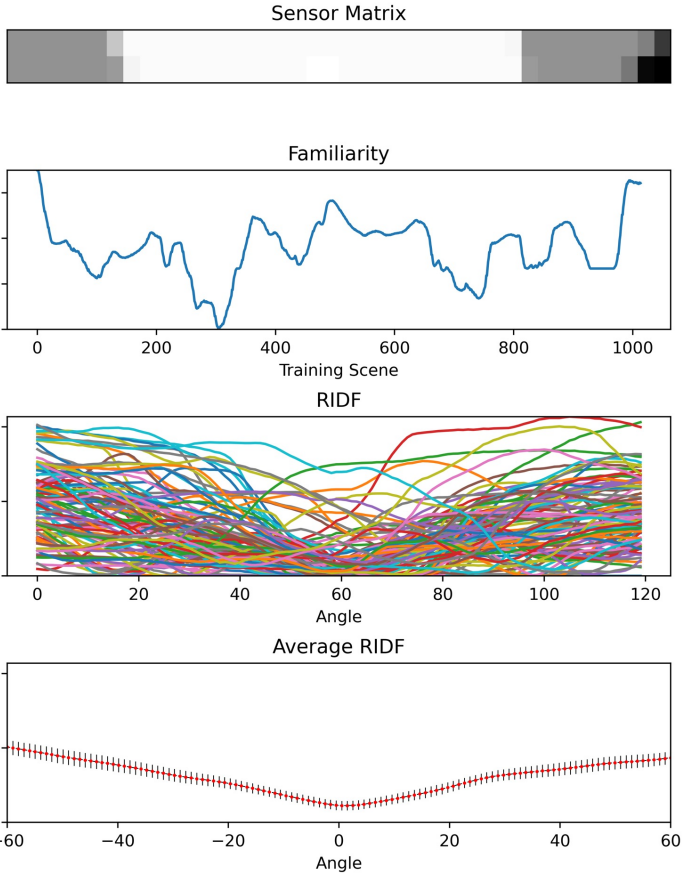


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 3997.81; RMSD/dist: 9.995; TD: 711; p90: 120; p50: 40; complete: 0

10%

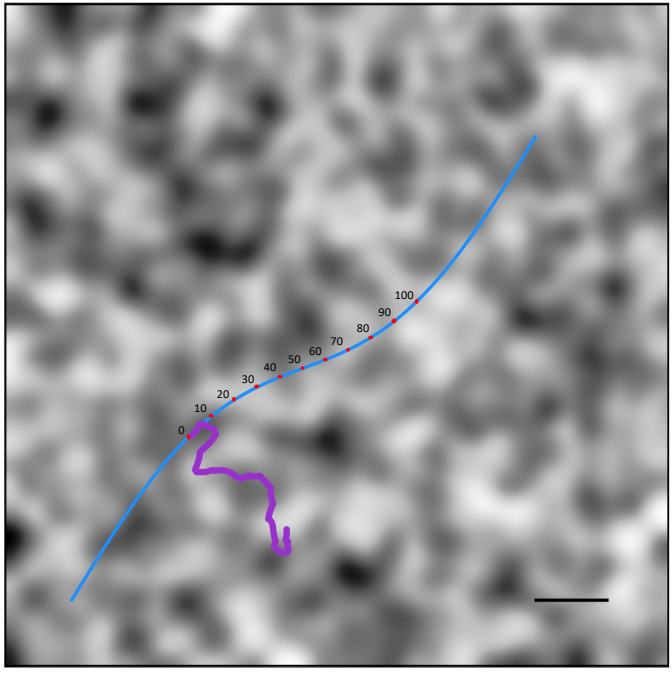


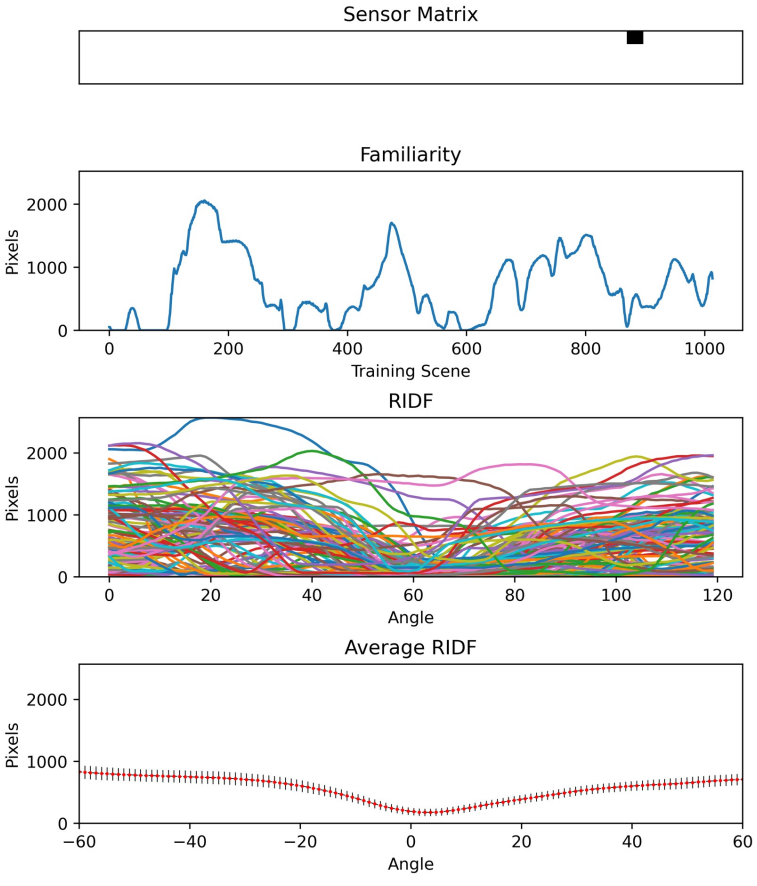


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2208.40; RMSD/dist: 5.521; TD: 672; p90: 90; p50: 46; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 10774.09; RMSD/dist: 26.935; TD: 614; p90: 68; p50: 28; complete: 0

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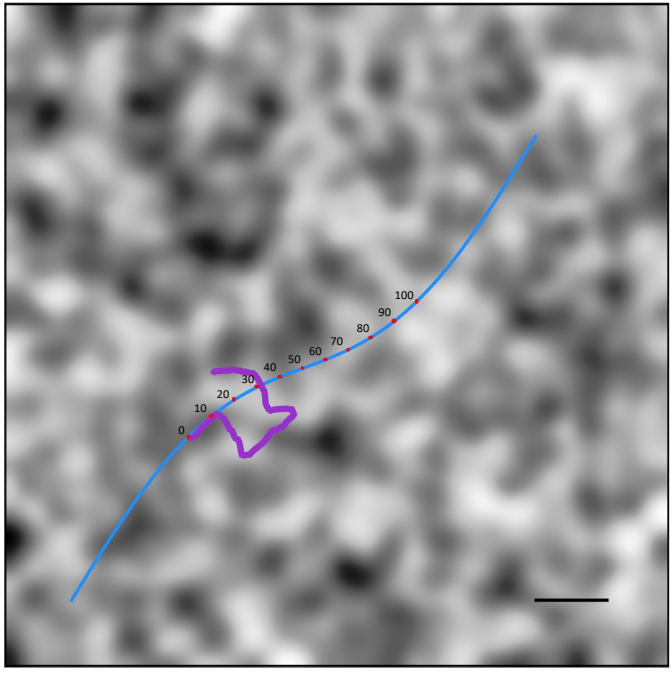
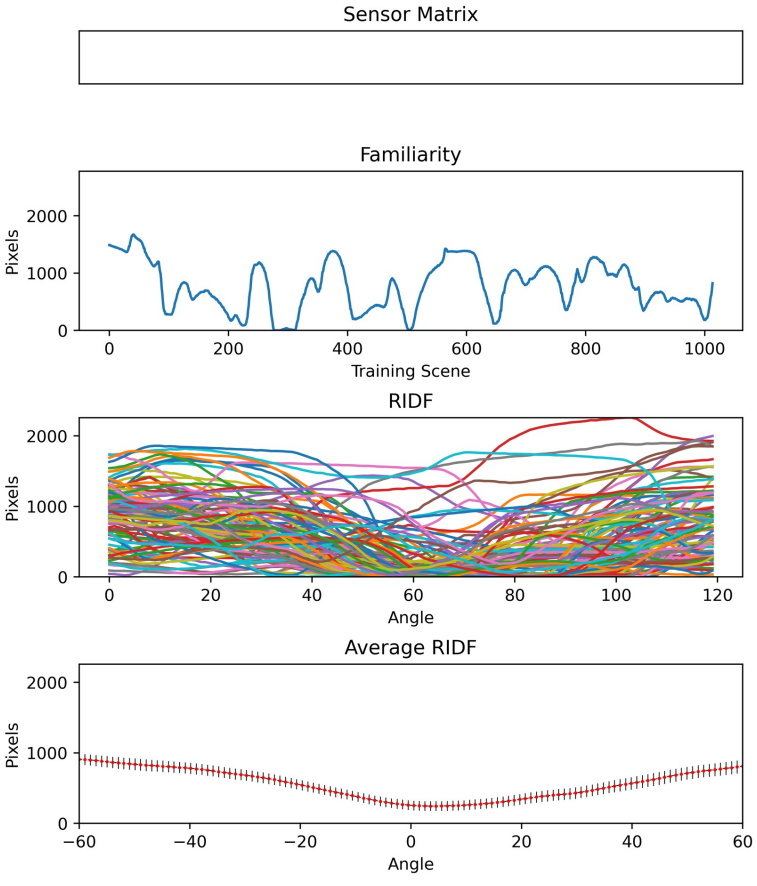
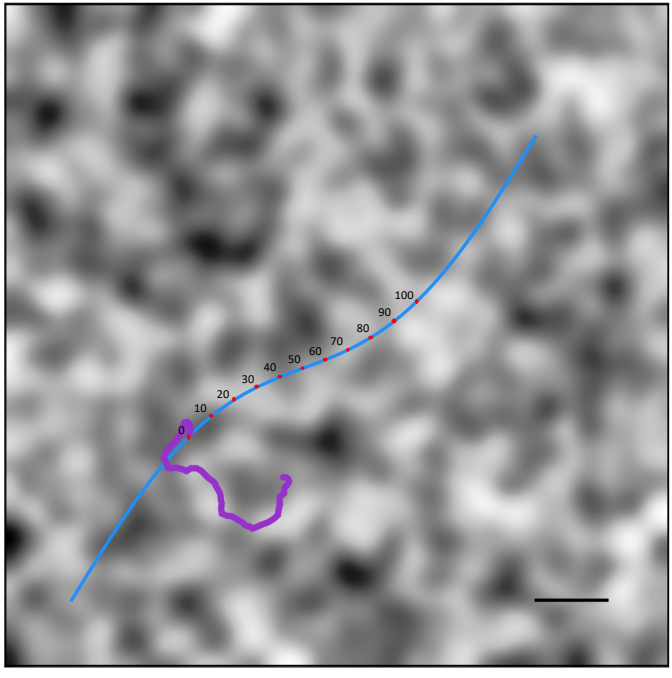


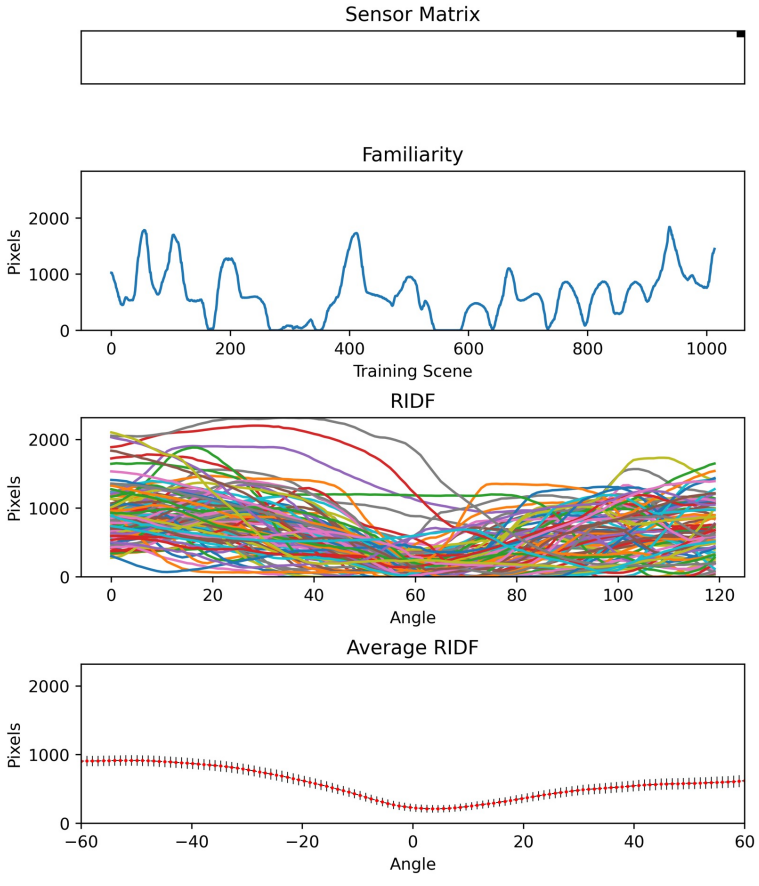


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 4016.84; RMSD/dist: 10.042; TD: 727; p90: 116; p50: 48; complete: 0

0%

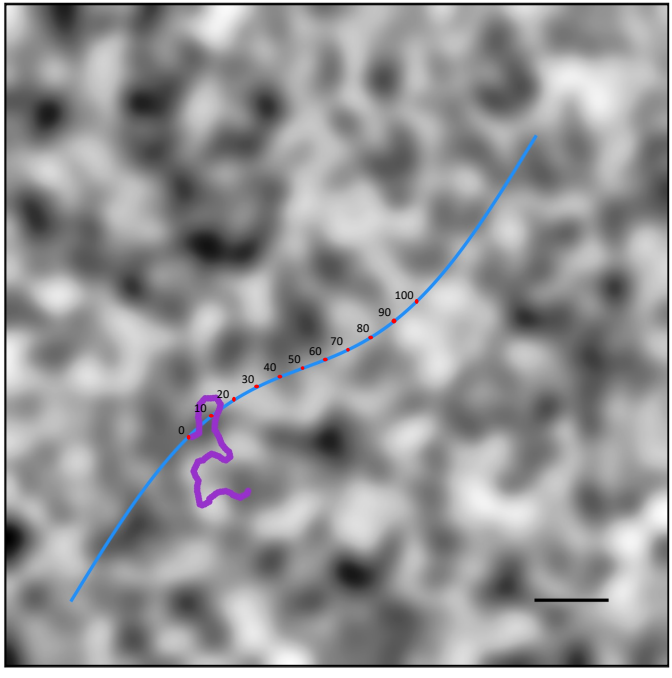


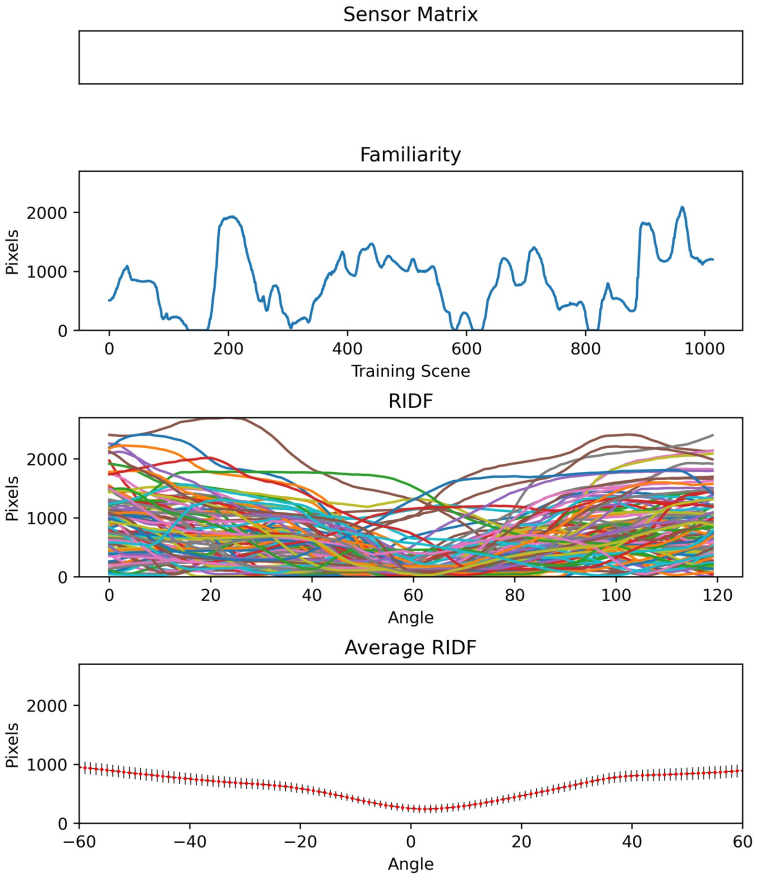


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 8720.43; RMSD/dist: 21.801; TD: 598; p90: 56; p50: 30; complete: 0

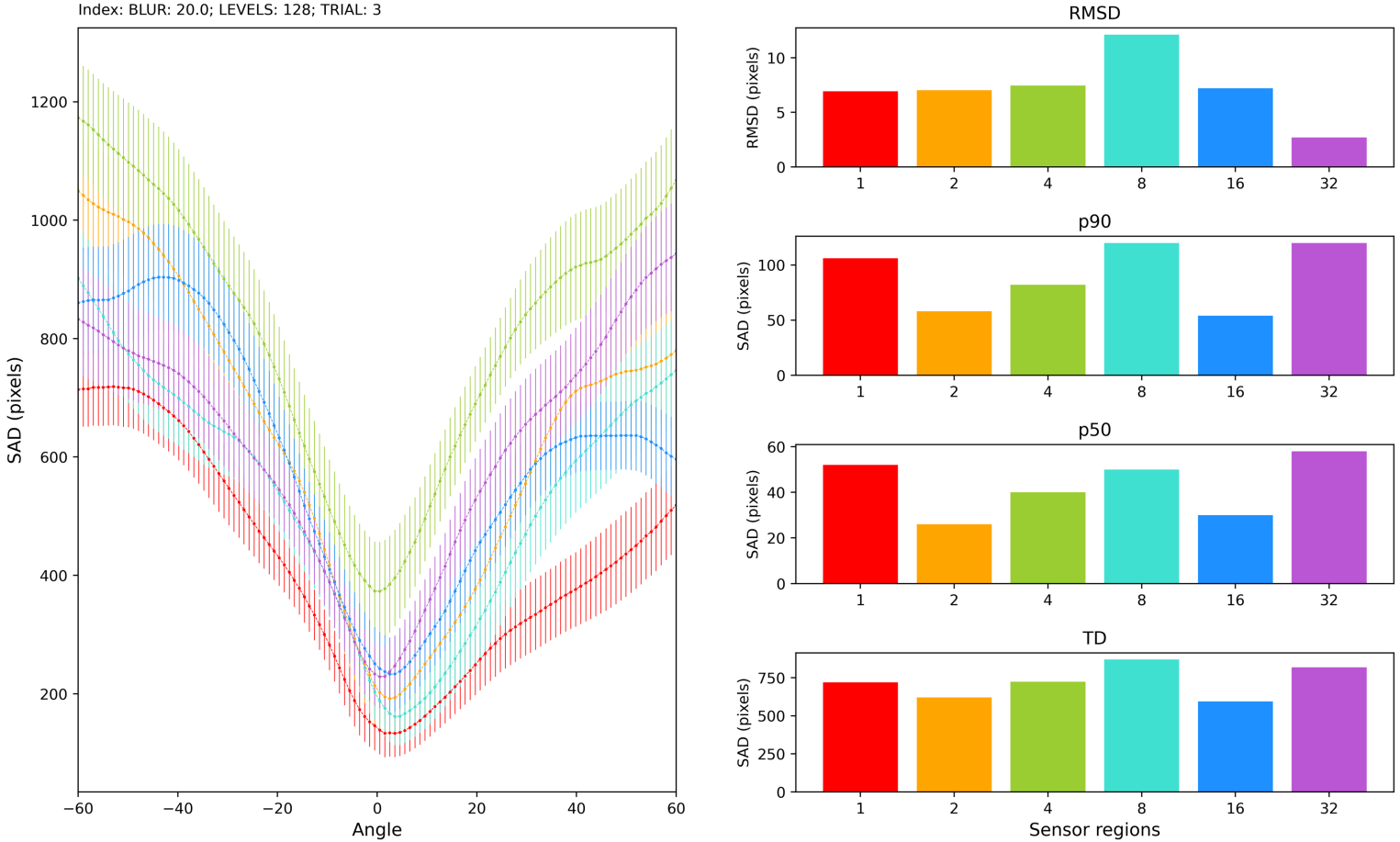
0%



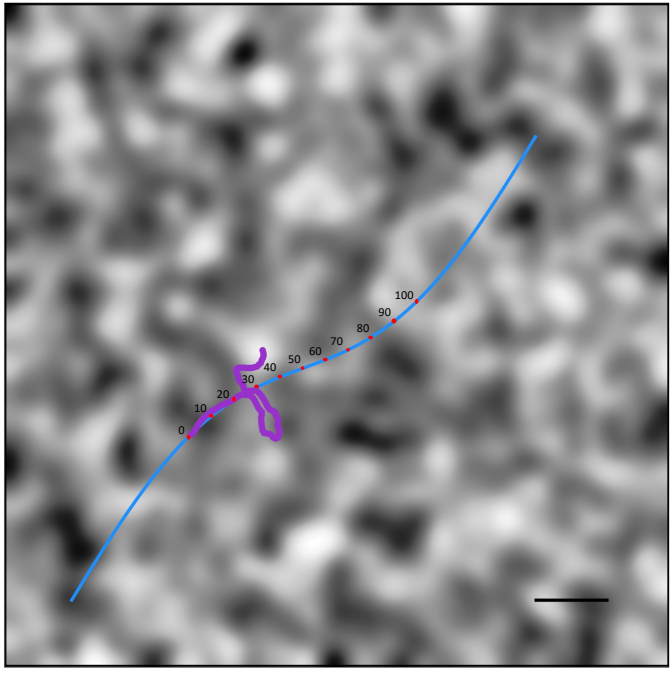


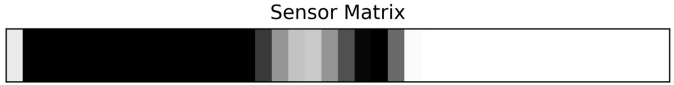
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

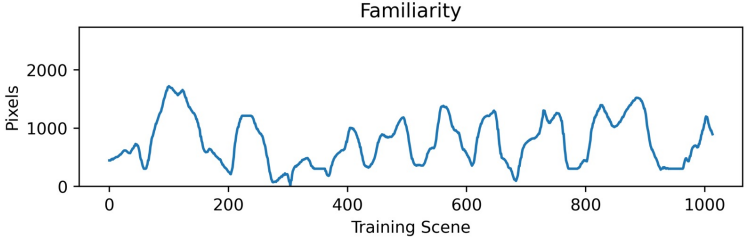
Navigation stats: RMSD error: 4818.06; RMSD/dist: 12.045; TD: 572; p90: 82; p50: 32; complete: 0

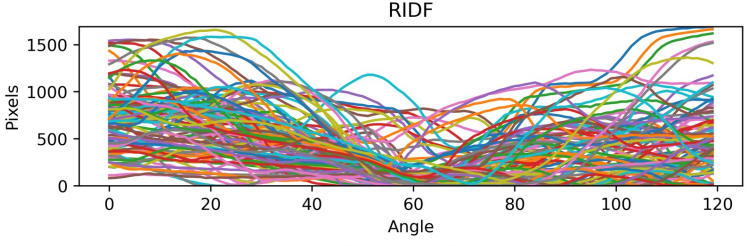

Index: BLUR: 20.0; LEVELS: 128; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

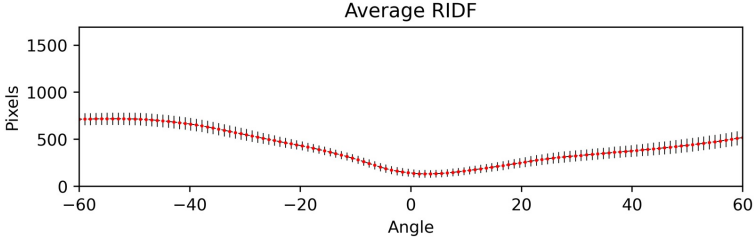
0%







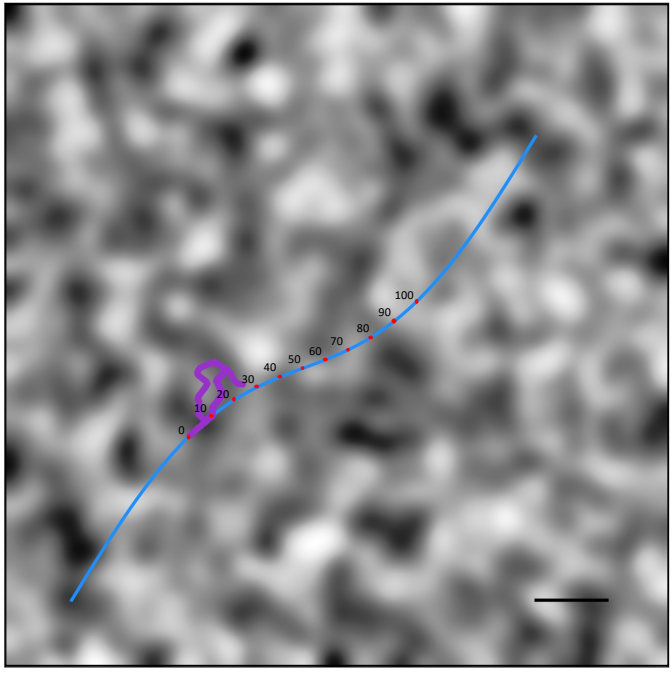


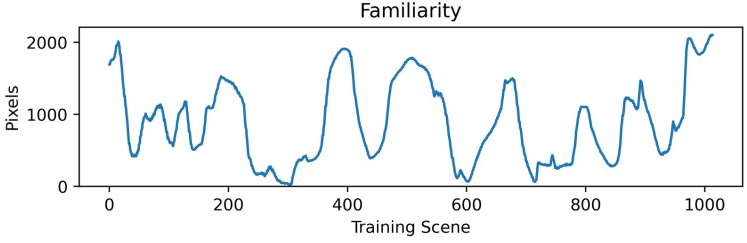


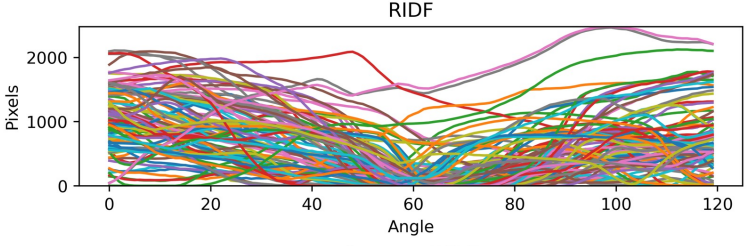
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

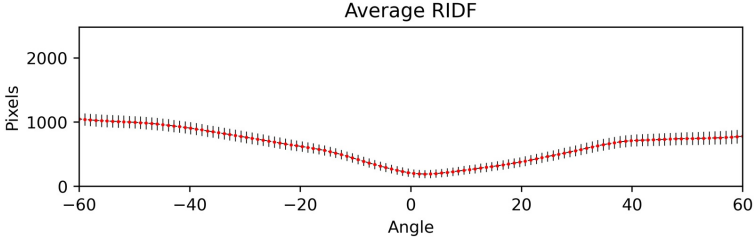
Navigation stats: RMSD error: 2768.88; RMSD/dist: 6.922; TD: 720; p90: 106; p50: 52; complete: 0

10%





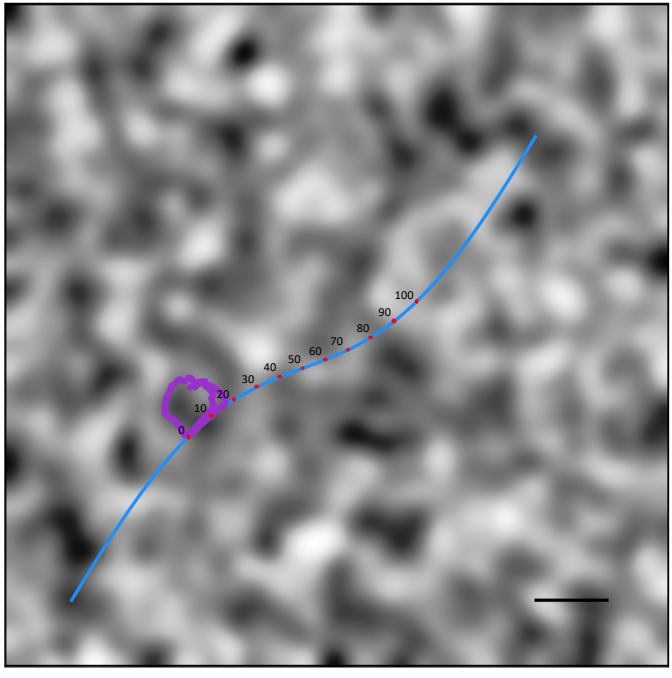


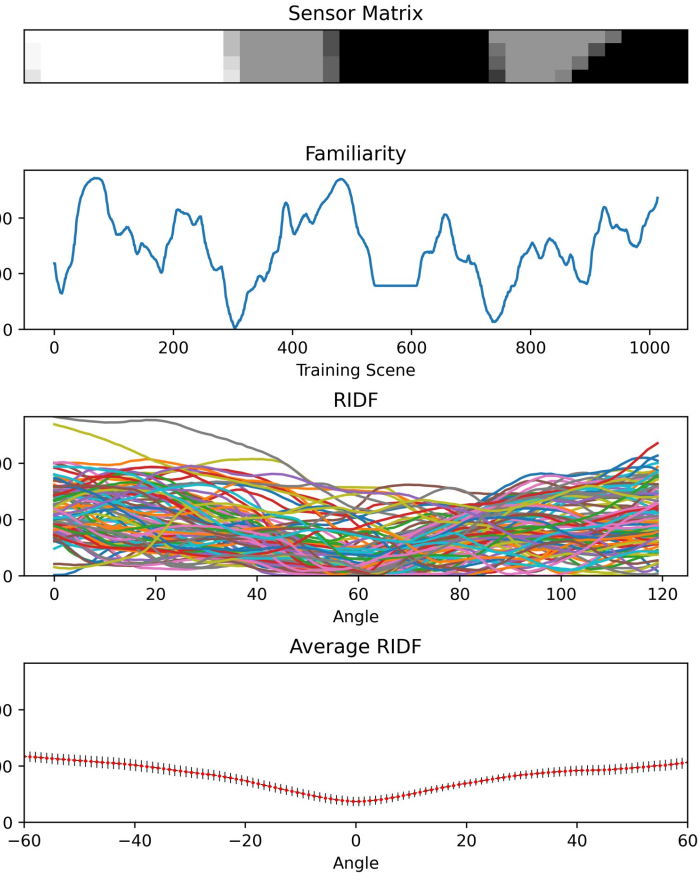


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2814.23; RMSD/dist: 7.036; TD: 621; p90: 58; p50: 26; complete: 0

10%

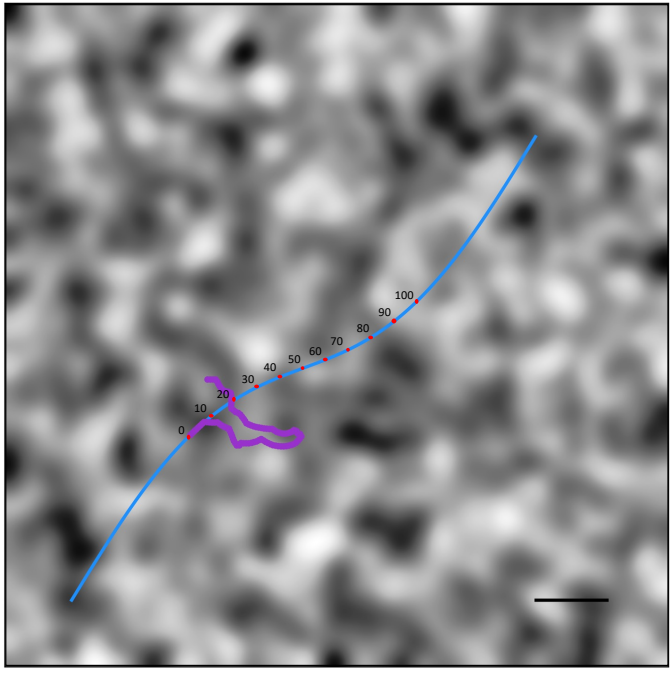


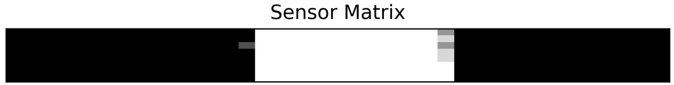


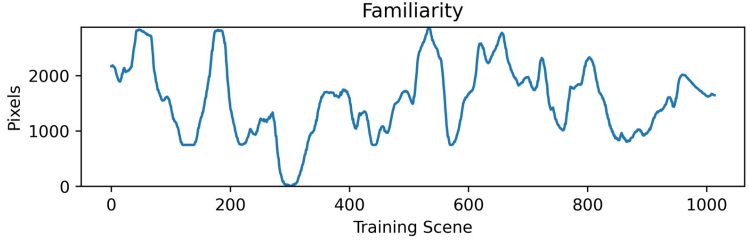
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

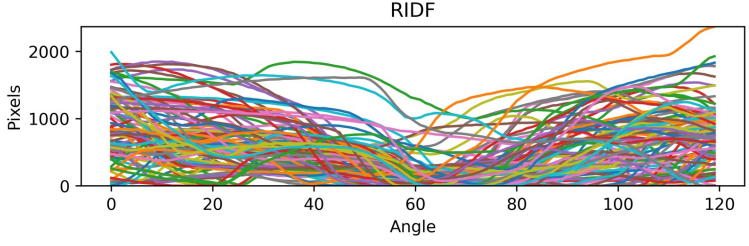
Navigation stats: RMSD error: 2982.15; RMSD/dist: 7.455; TD: 723; p90: 82; p50: 40; complete: 0

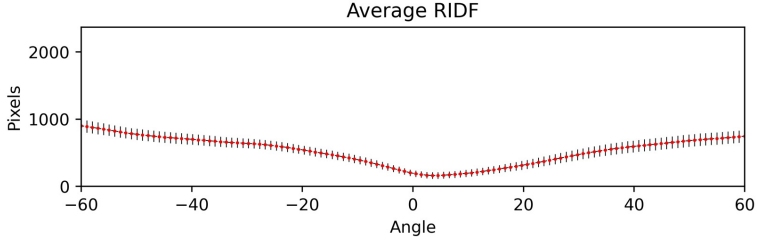
0%







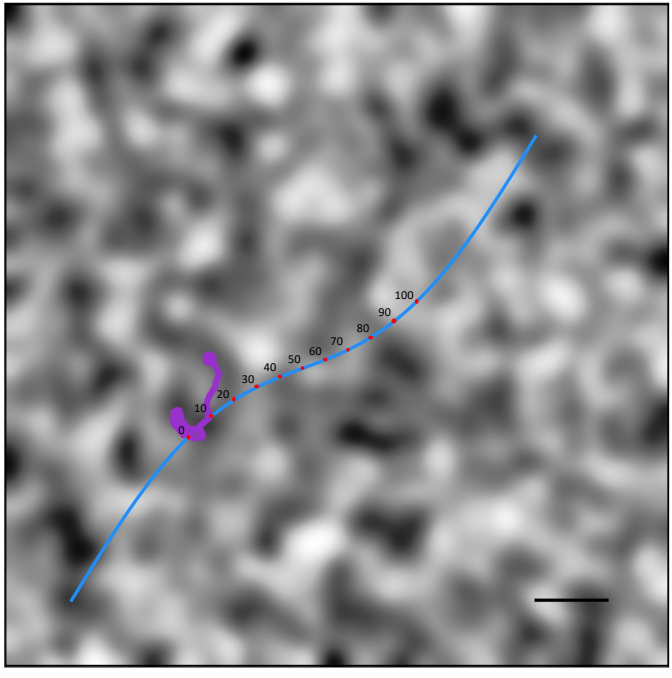


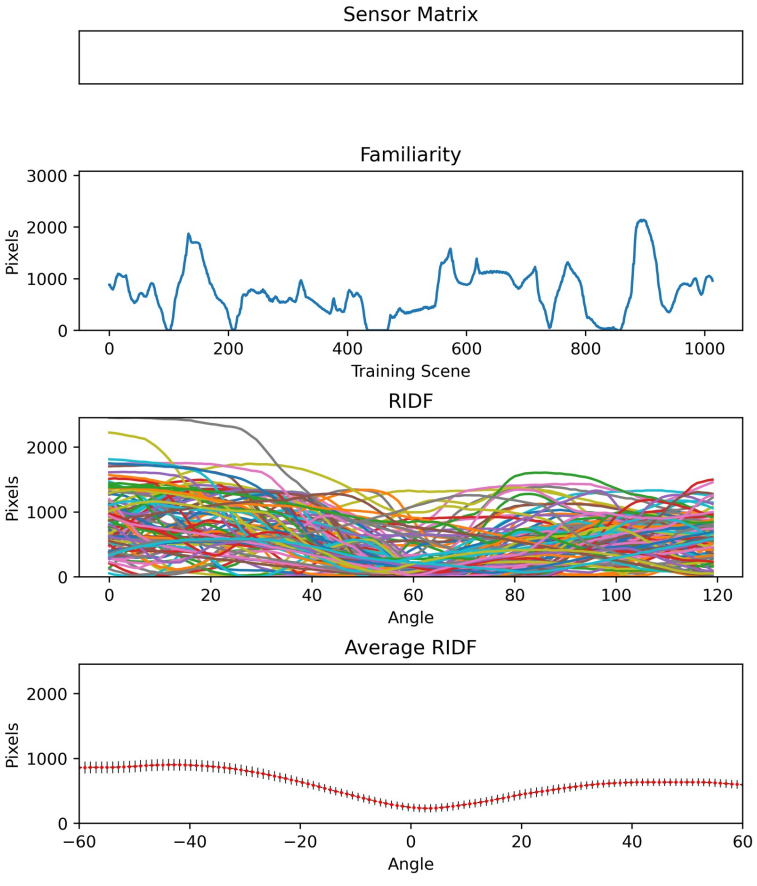


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4851.05; RMSD/dist: 12.128; TD: 869; p90: 120; p50: 50; complete: 0

10%

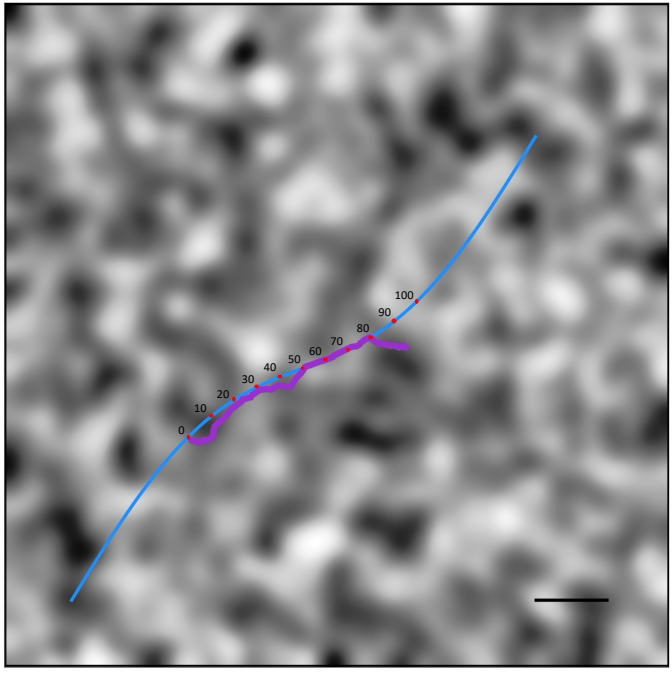


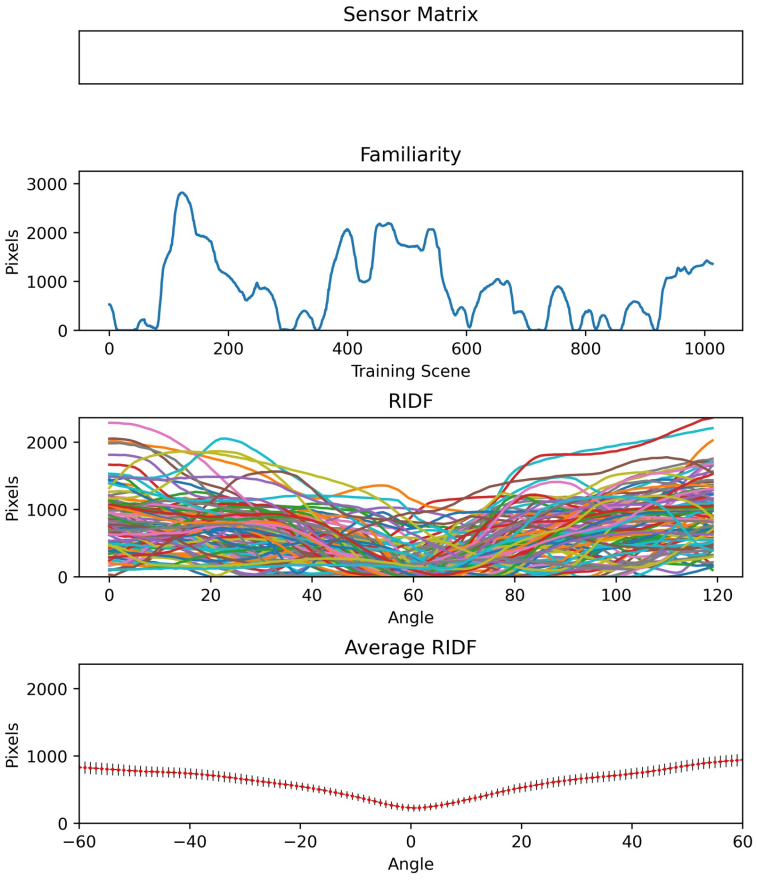


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2878.69; RMSD/dist: 7.197; TD: 594; p90: 54; p50: 30; complete: 0

20%





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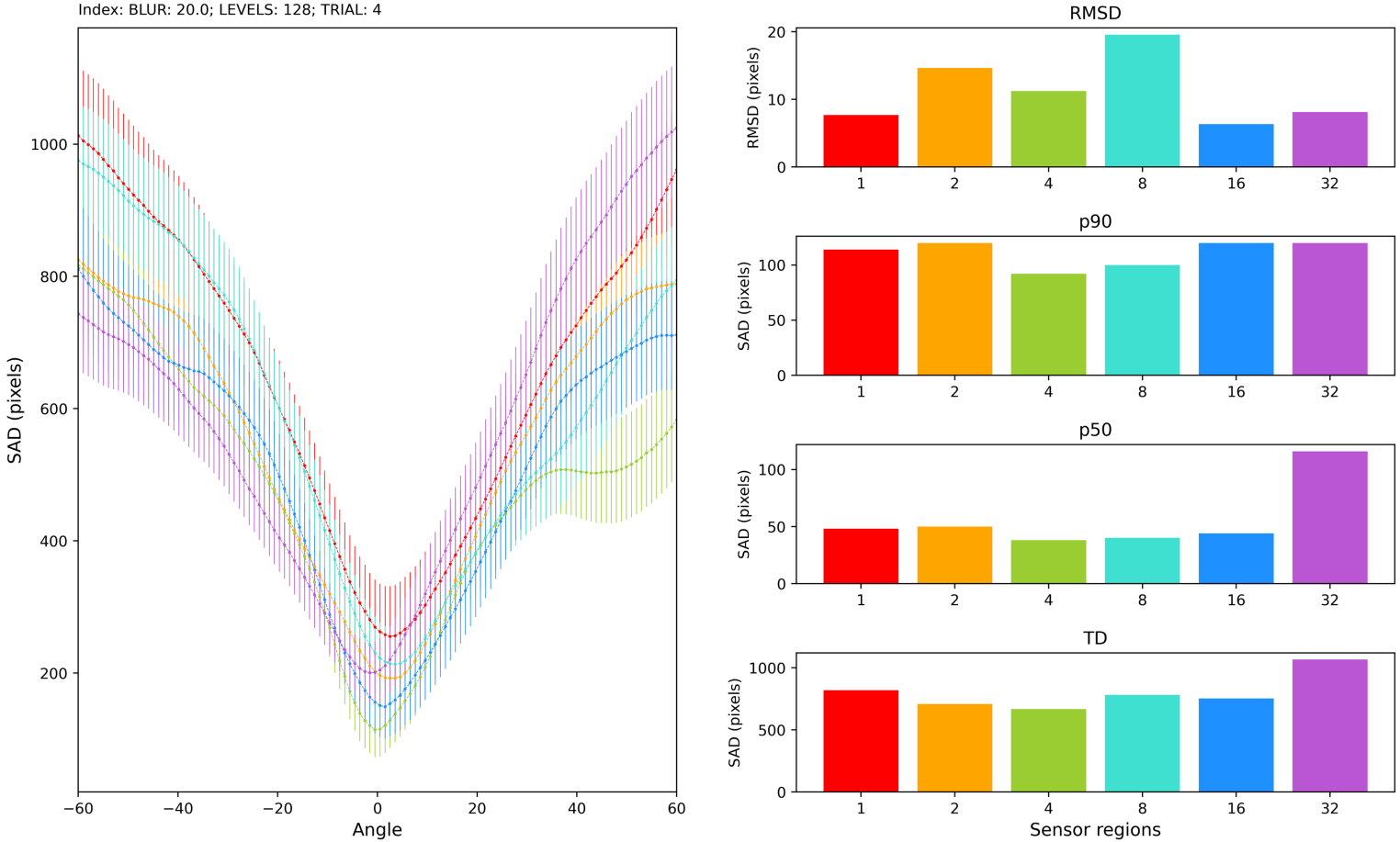
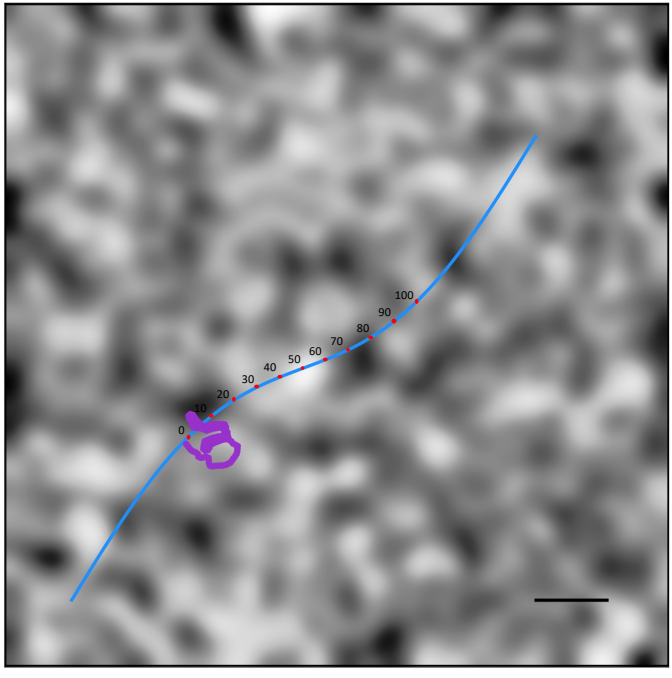
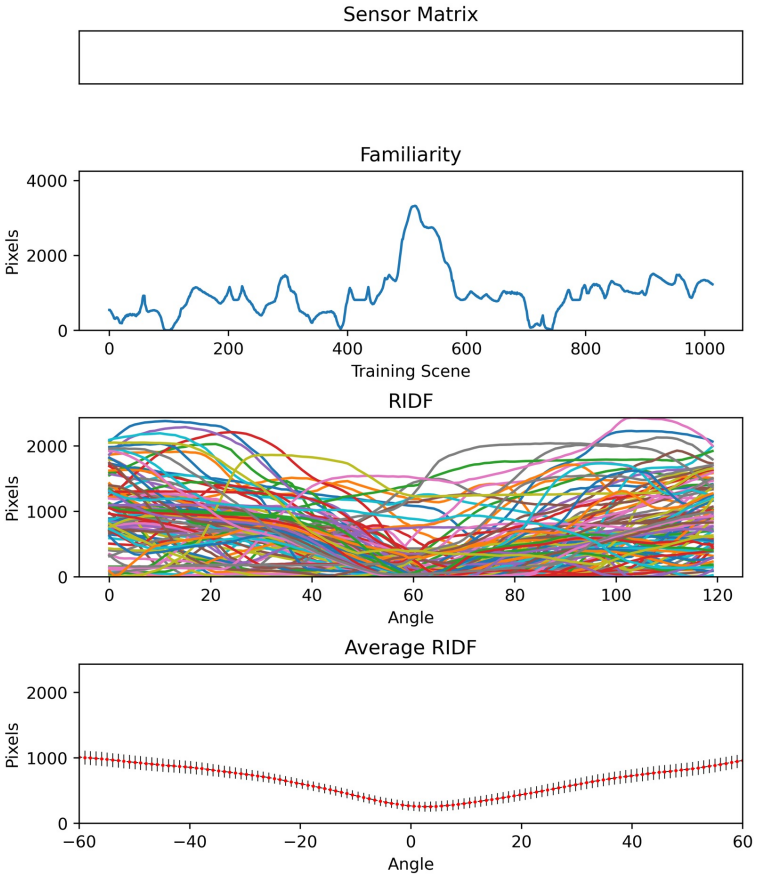
Navigation stats: RMSD error: 1078.82; RMSD/dist: 2.697; TD: 818; p90: 120; p50: 58; complete: 0


Index: BLUR: 20.0; LEVELS: 128; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

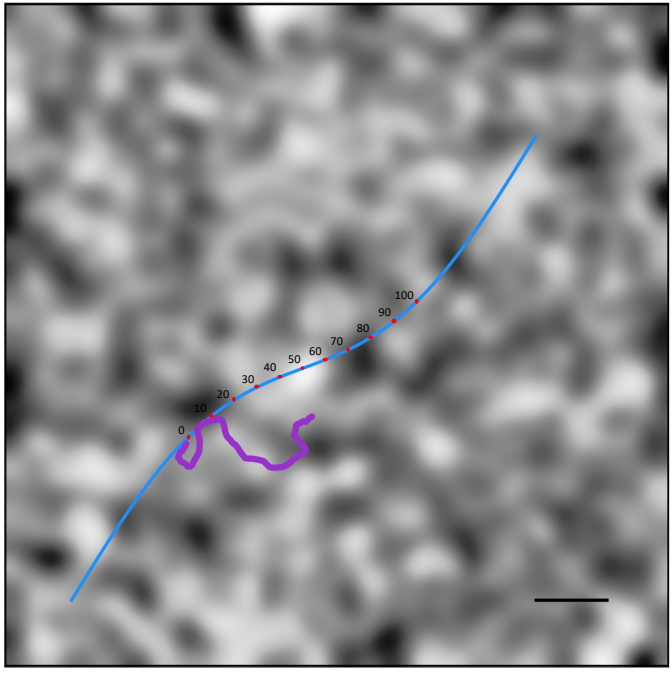


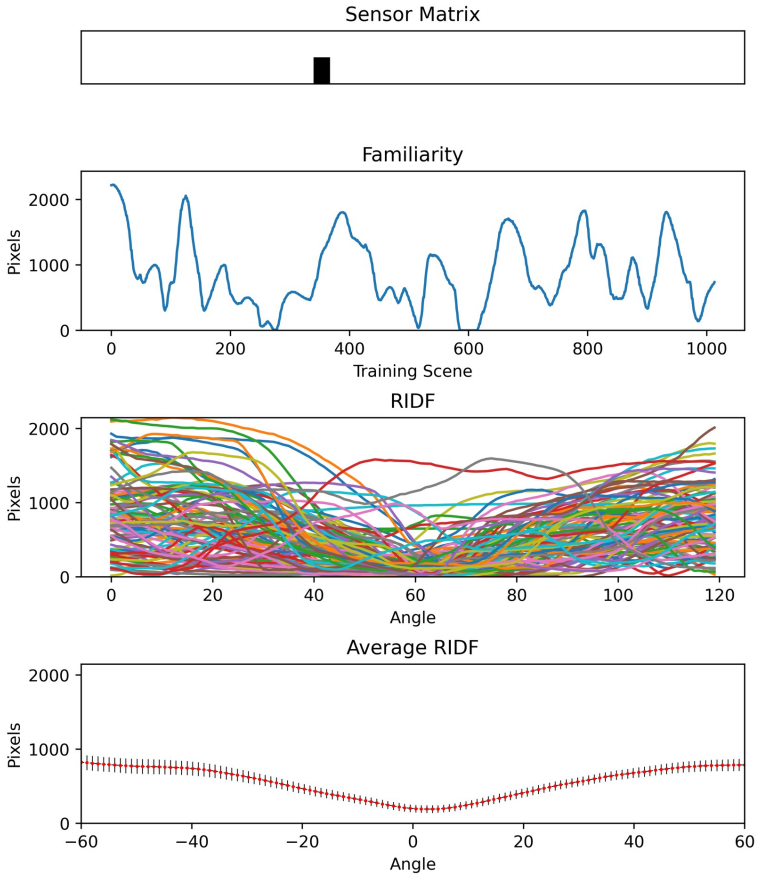


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3072.03; RMSD/dist: 7.680; TD: 819; p90: 114; p50: 48; complete: 0

0%





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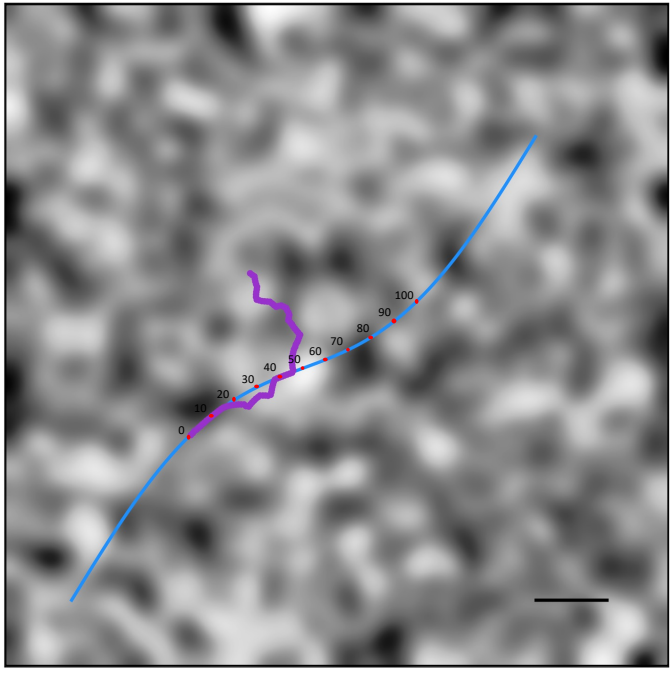
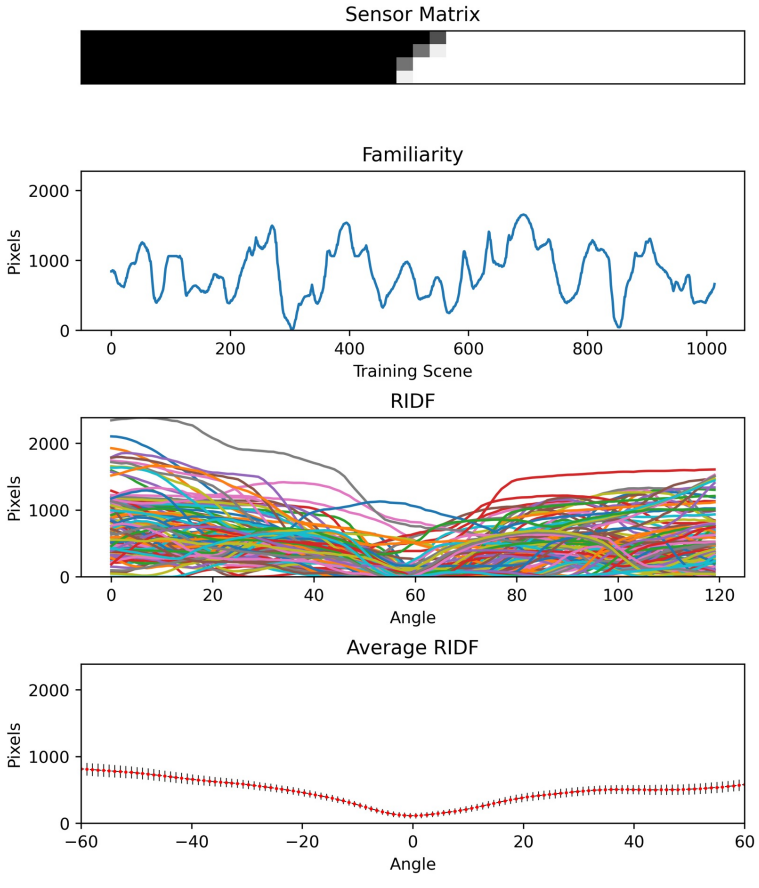
Navigation stats: RMSD error: 5846.36; RMSD/dist: 14.616; TD: 708; p90: 120; p50: 50; complete: 0

20%

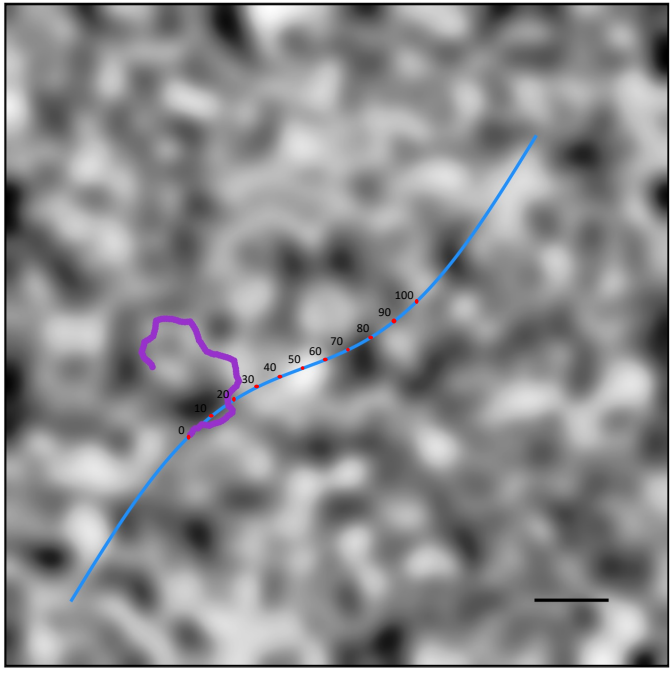


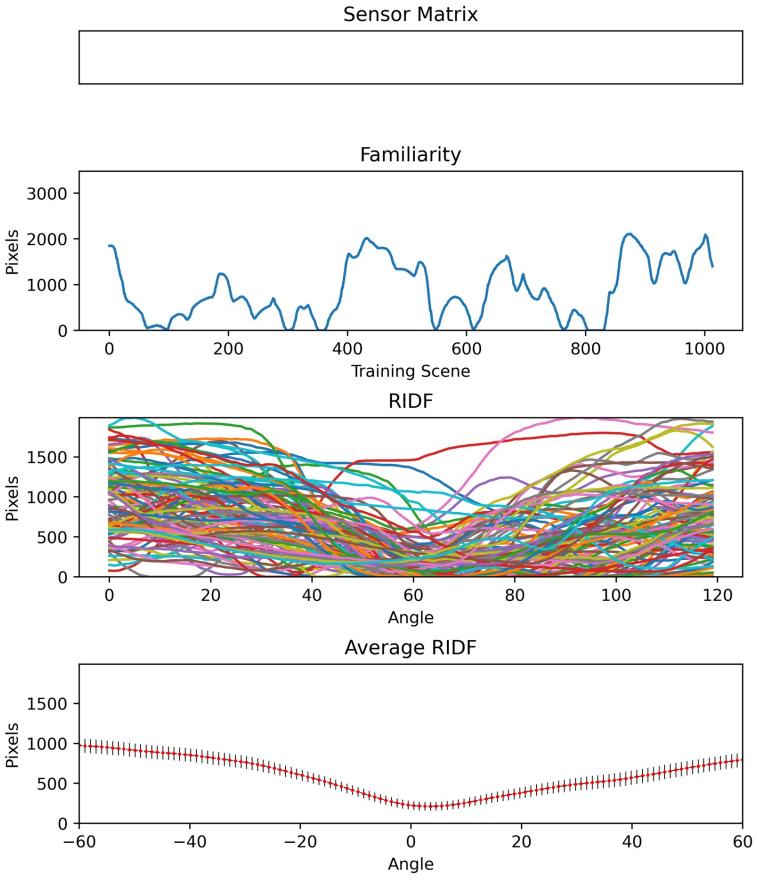


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4487.01; RMSD/dist: 11.218; TD: 667; p90: 92; p50: 38; complete: 0

0%

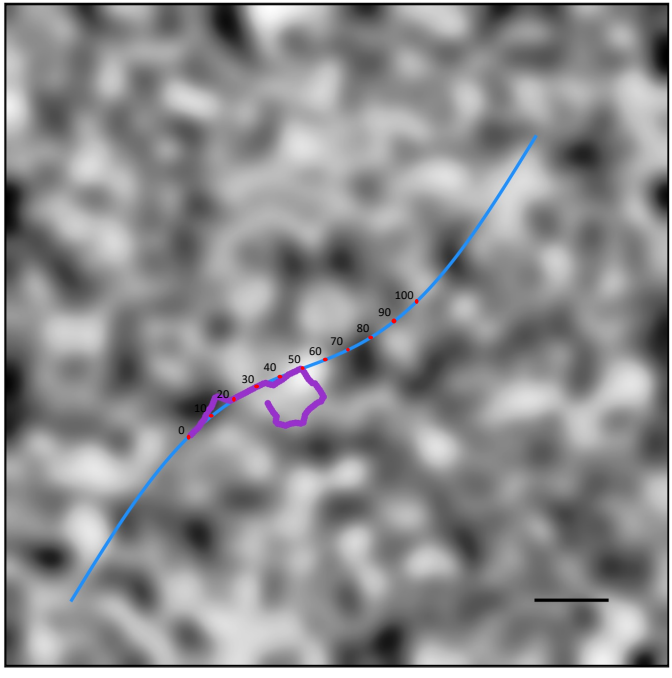


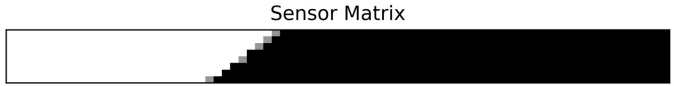


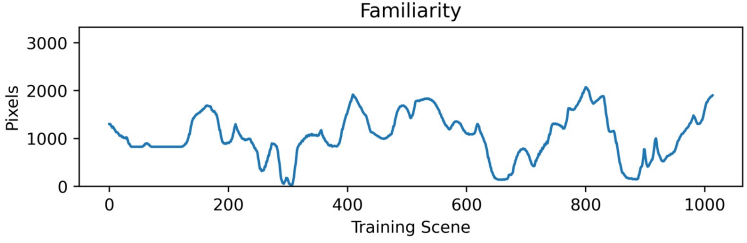
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

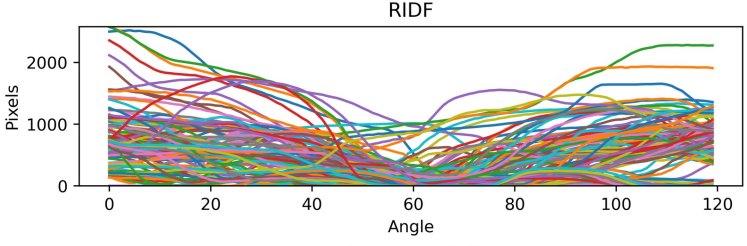
Navigation stats: RMSD error: 7825.56; RMSD/dist: 19.564; TD: 782; p90: 100; p50: 40; complete: 0

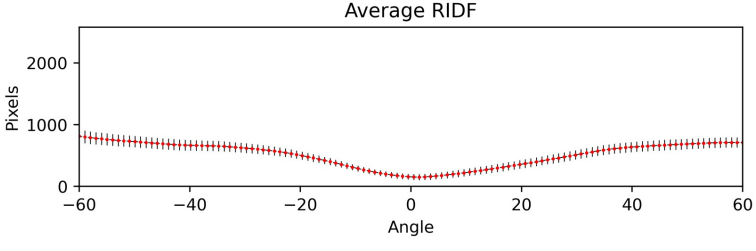
10%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2533.61; RMSD/dist: 6.334; TD: 753; p90: 120; p50: 44; complete: 0

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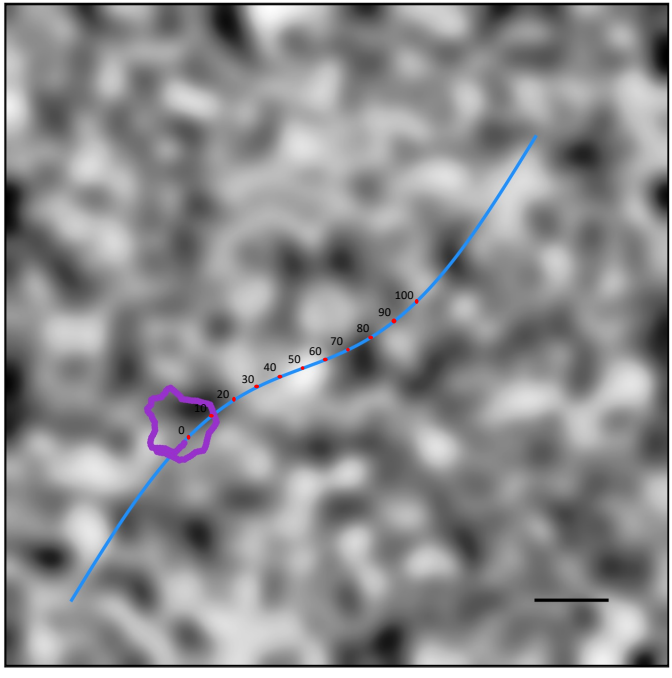

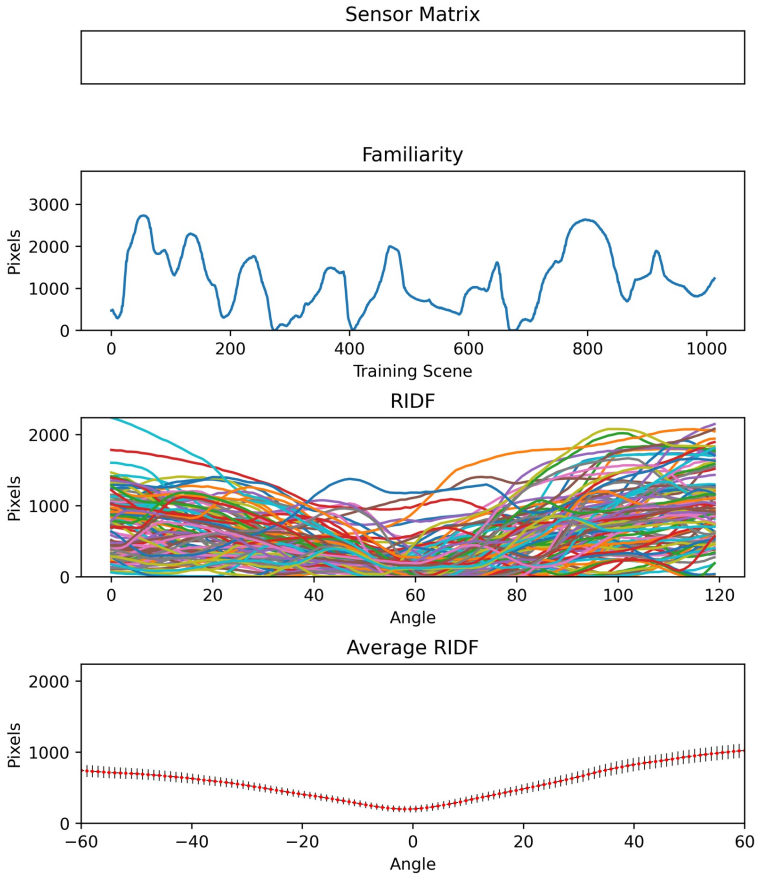

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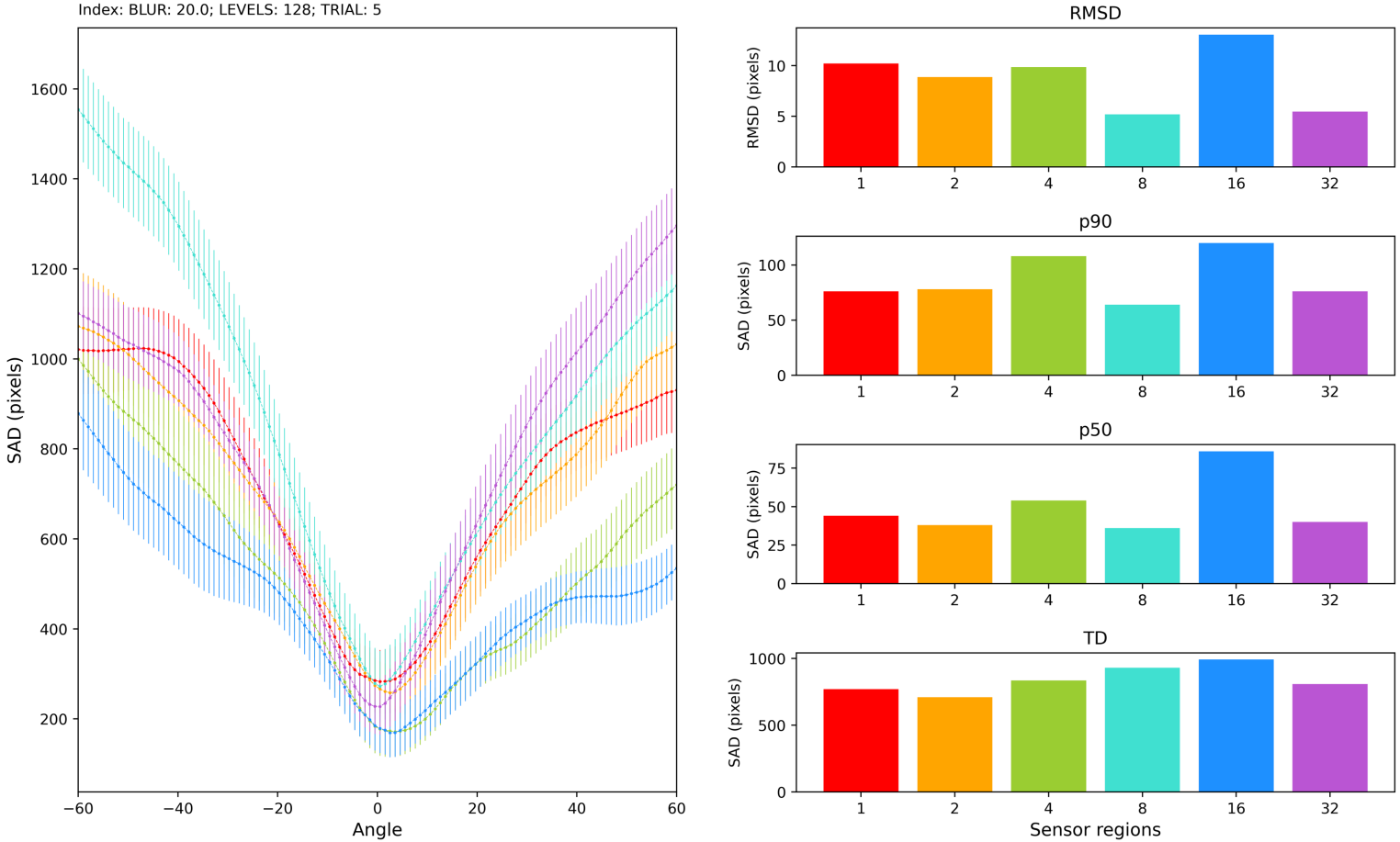
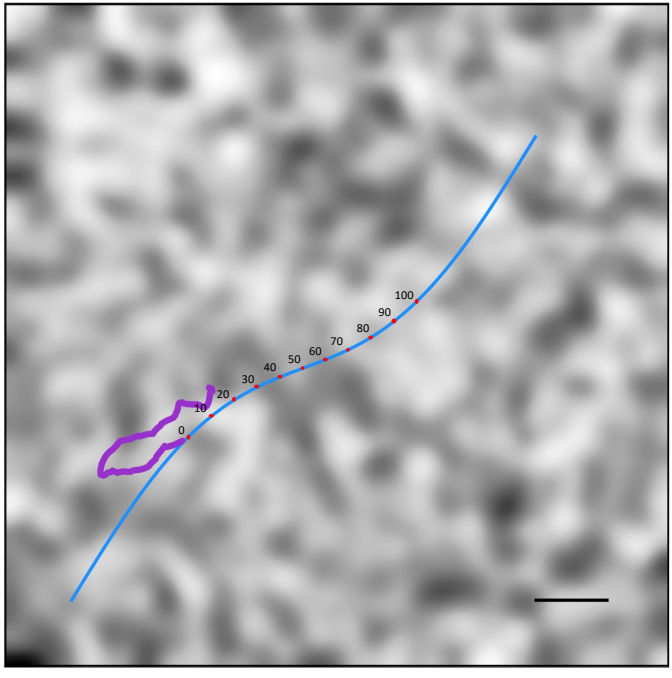
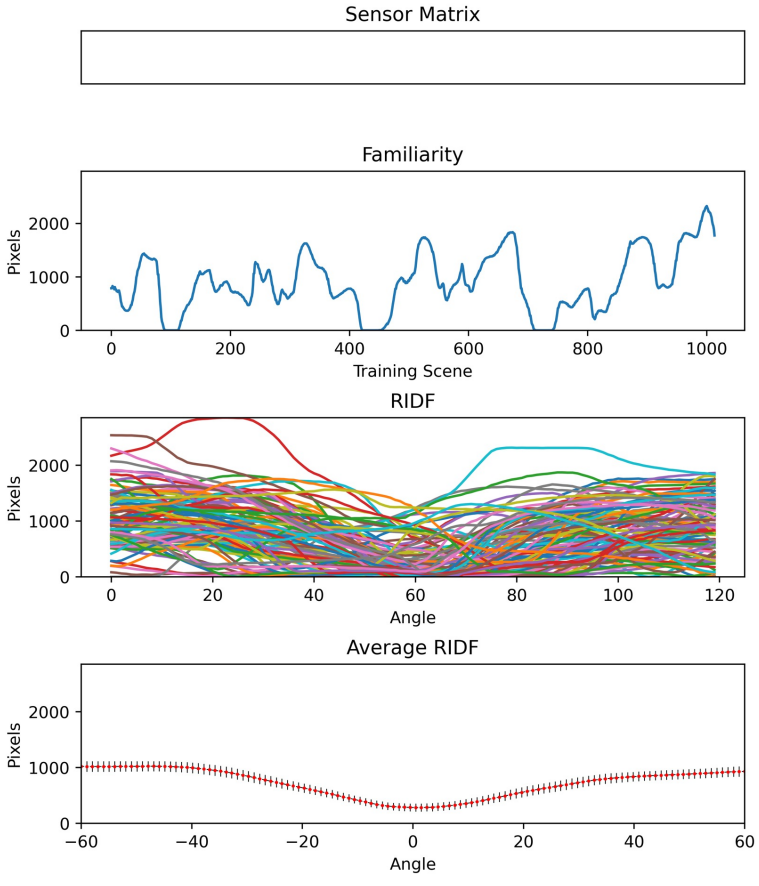
Navigation stats: RMSD error: 3249.07; RMSD/dist: 8.123; TD: 1066; p90: 120; p50: 116; complete: 0


Index: BLUR: 20.0; LEVELS: 128; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 4079.58; RMSD/dist: 10.199; TD: 769; p90: 76; p50: 44; complete: 0

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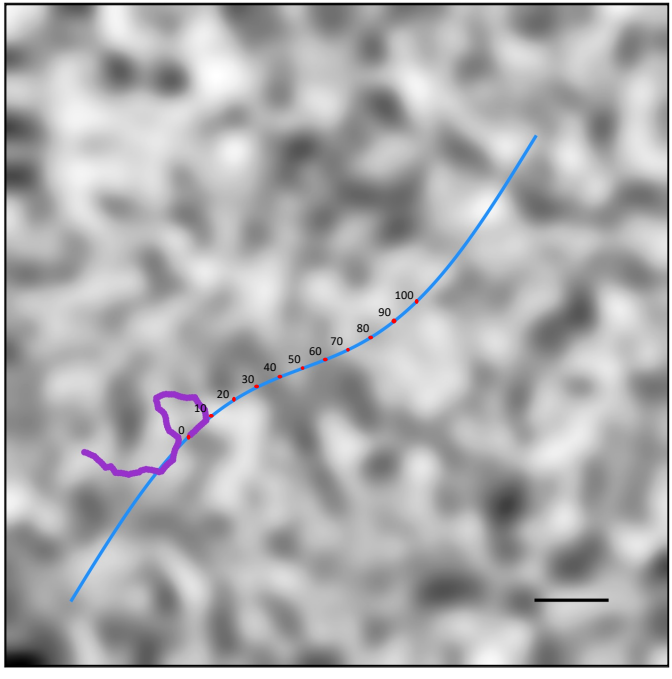
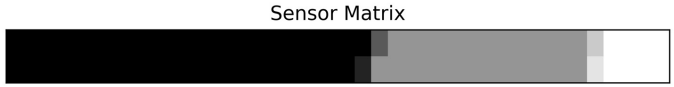
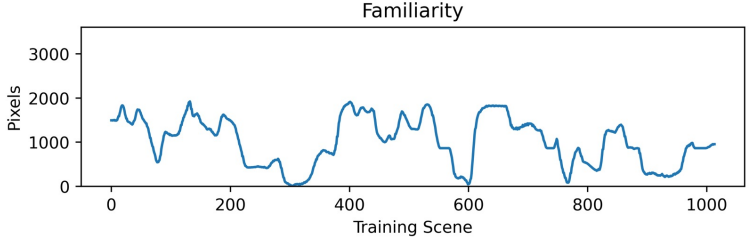
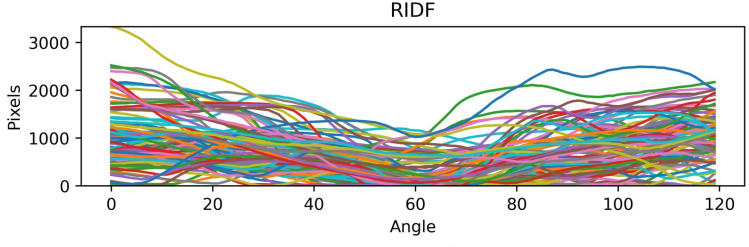
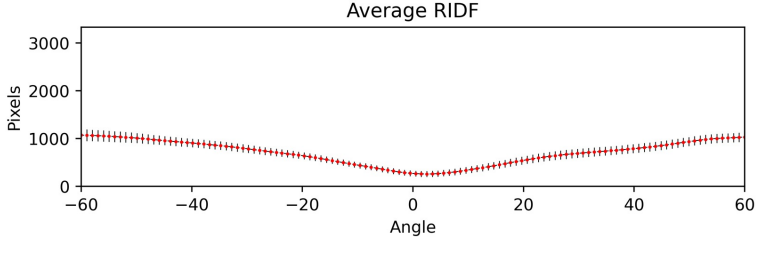






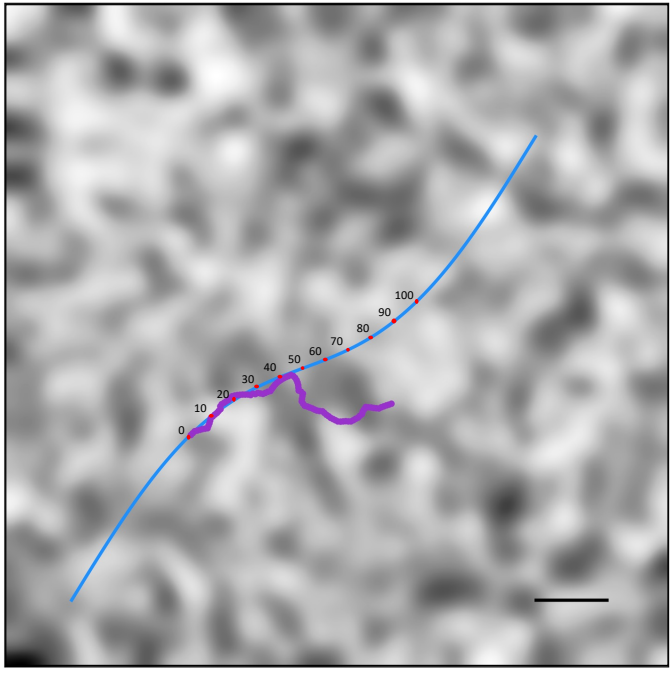


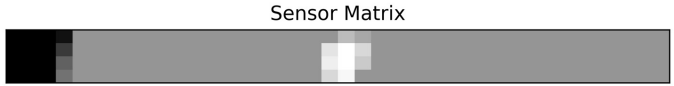


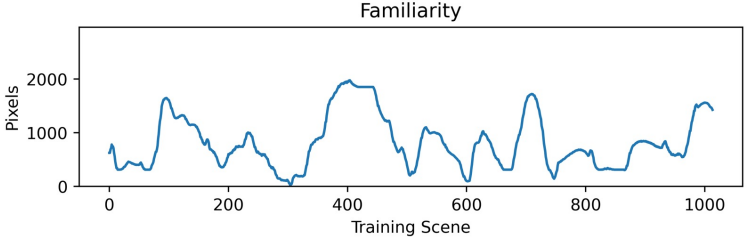
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

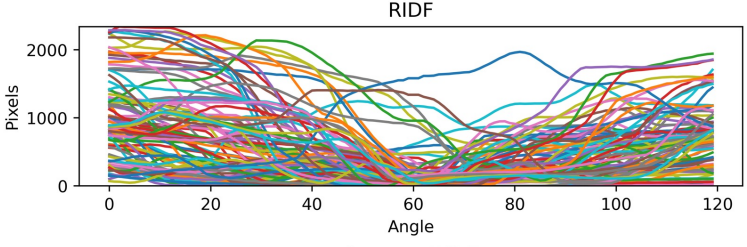
Navigation stats: RMSD error: 3549.30; RMSD/dist: 8.873; TD: 709; p90: 78; p50: 38; complete: 0

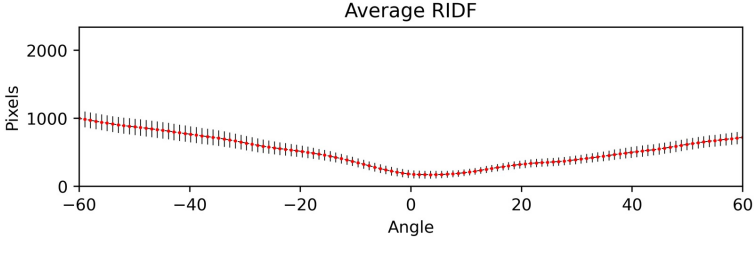
0%







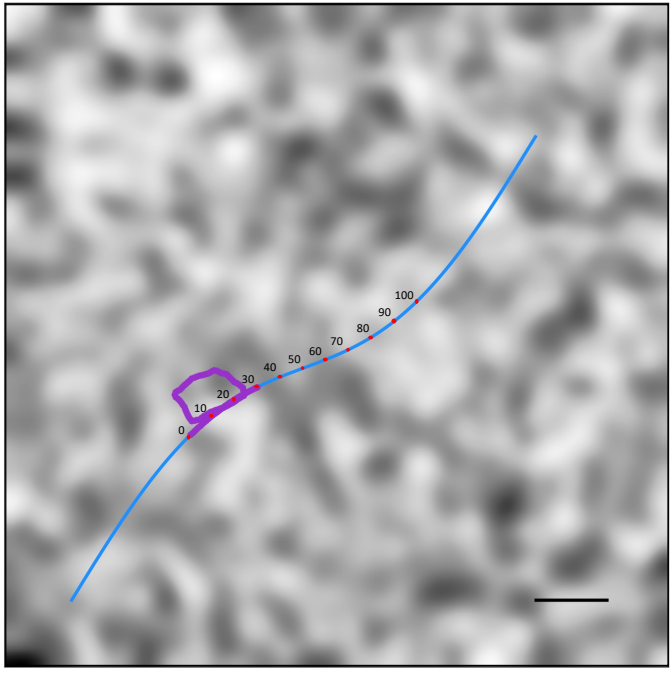


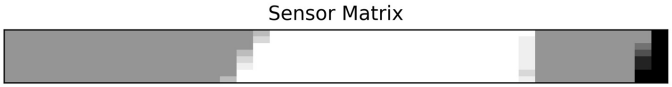


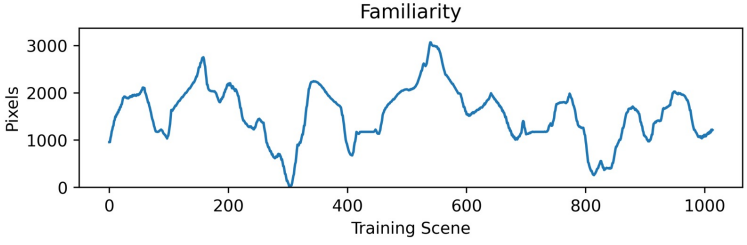
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

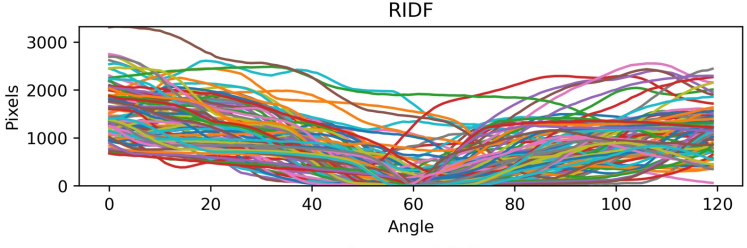
Navigation stats: RMSD error: 3941.80; RMSD/dist: 9.855; TD: 834; p90: 108; p50: 54; complete: 0

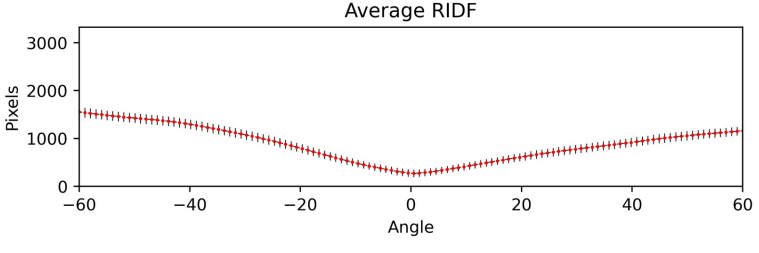
30%







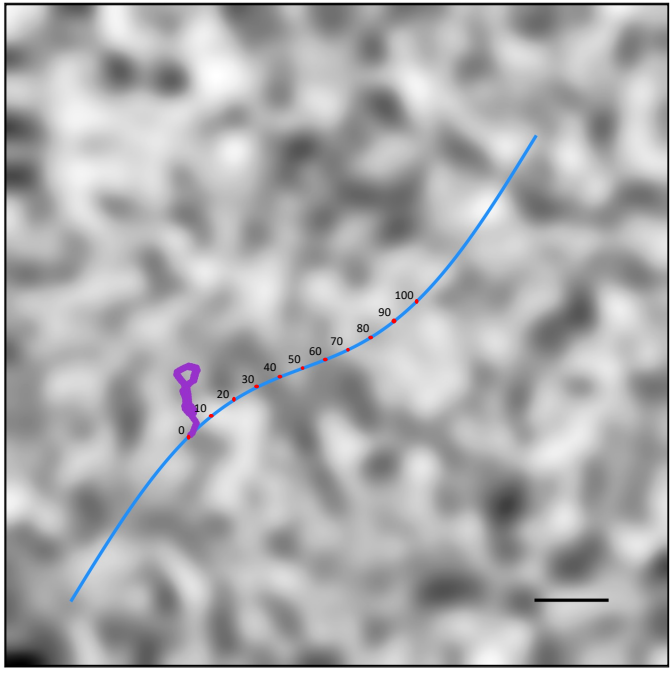


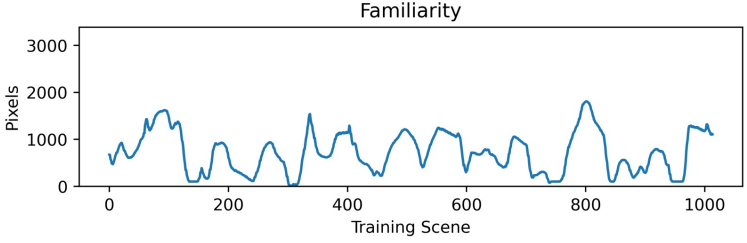


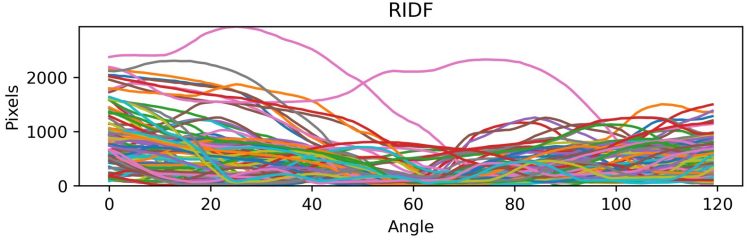
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

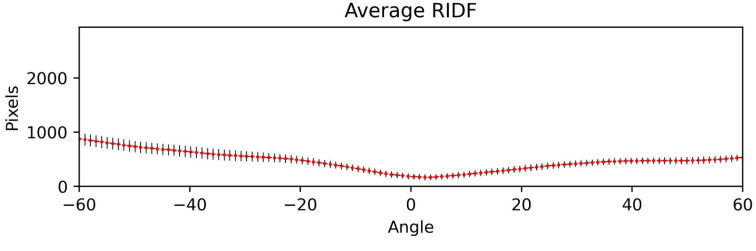
Navigation stats: RMSD error: 2073.41; RMSD/dist: 5.184; TD: 930; p90: 64; p50: 36; complete: 0

0%





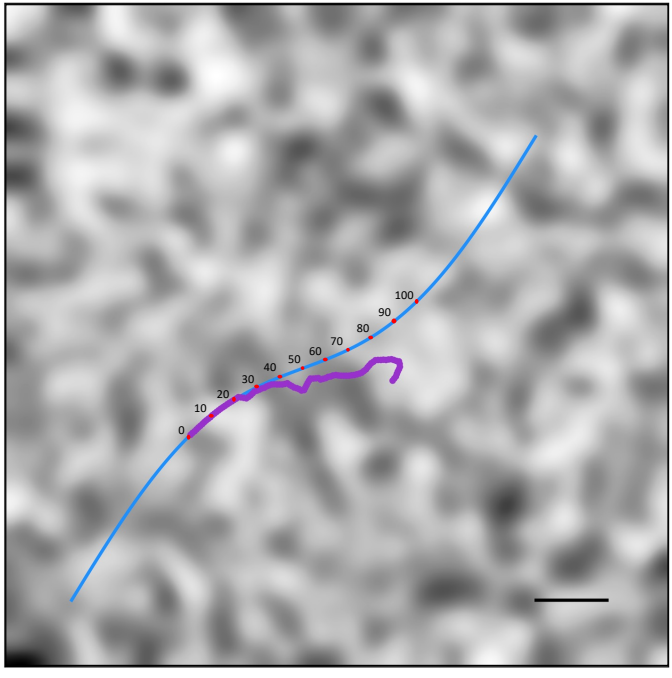


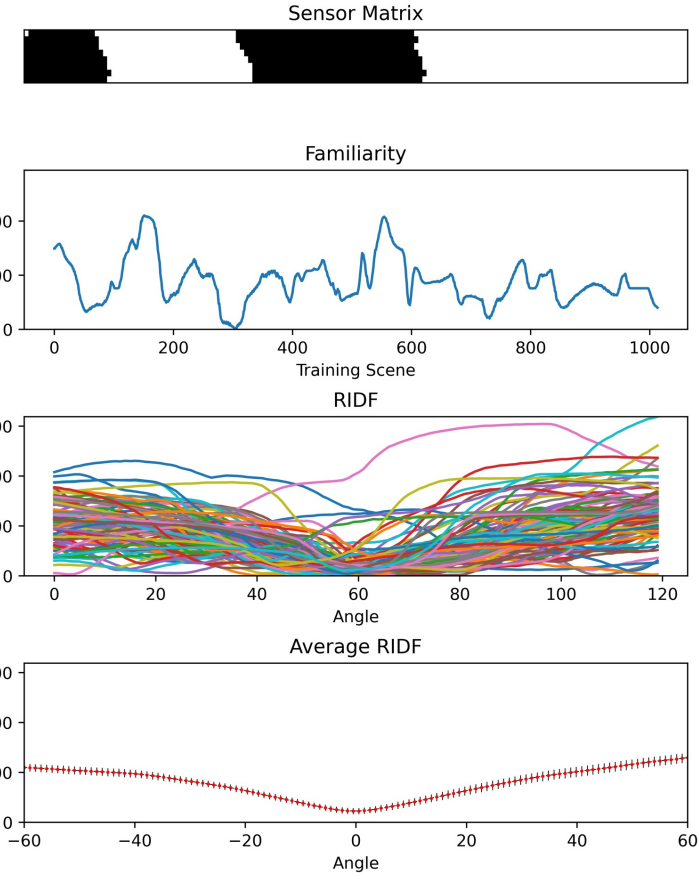


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5224.74; RMSD/dist: 13.062; TD: 991; p90: 120; p50: 86; complete: 0

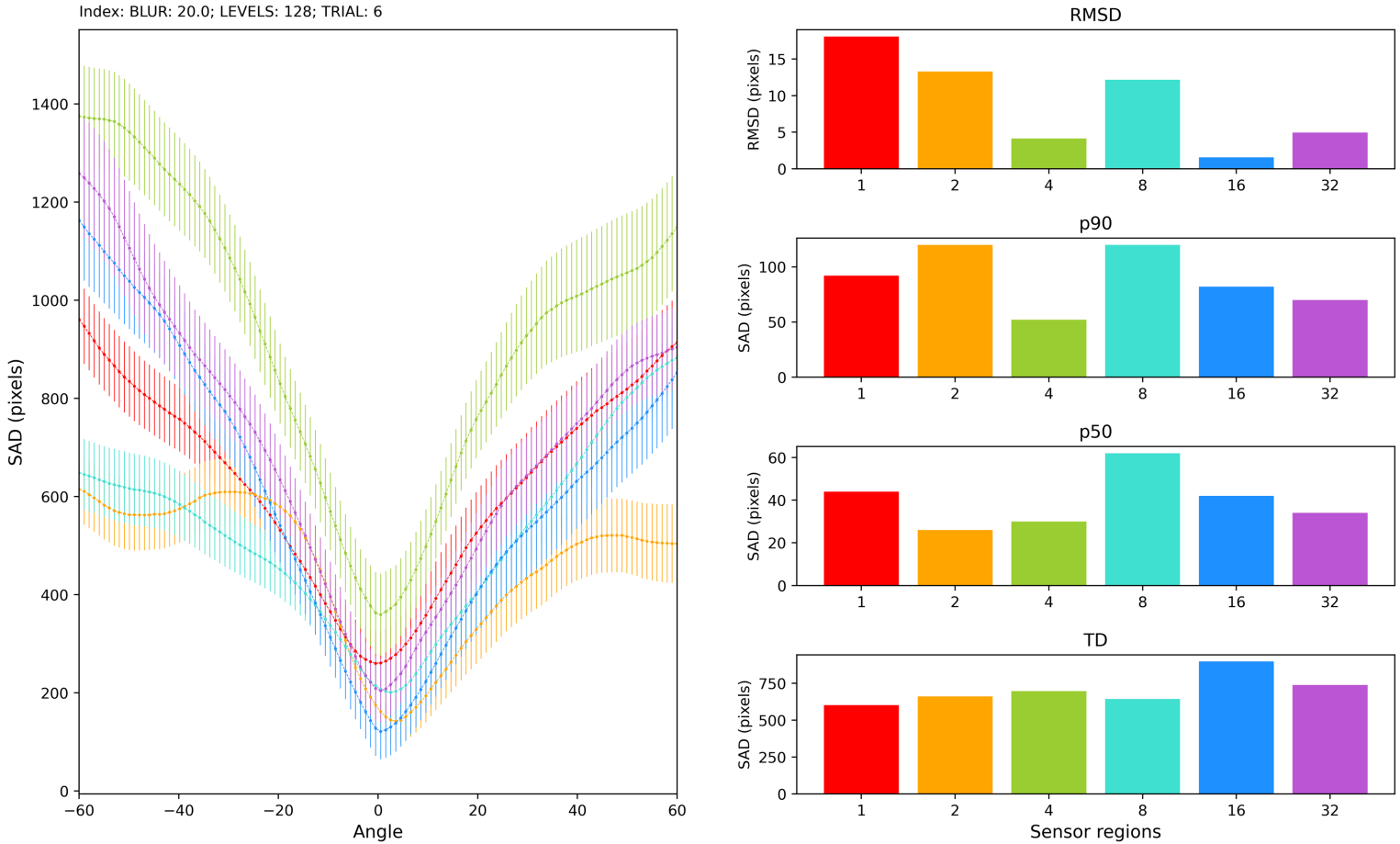
20%



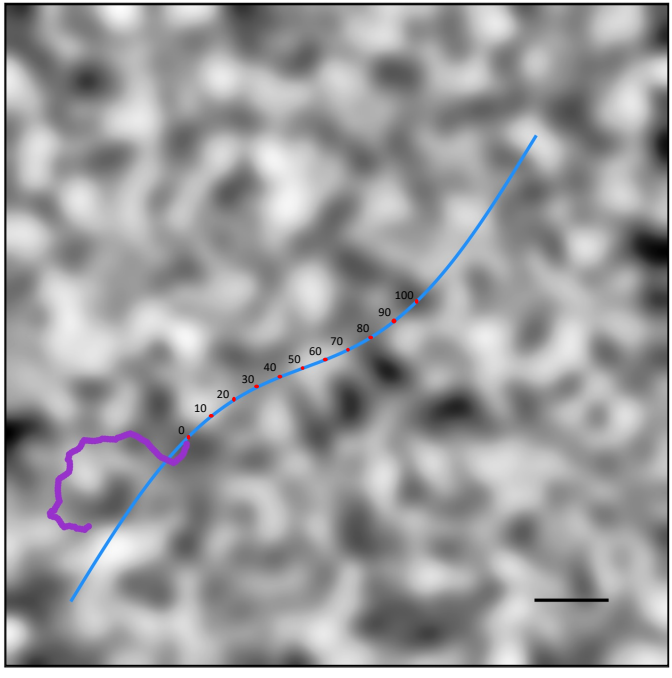


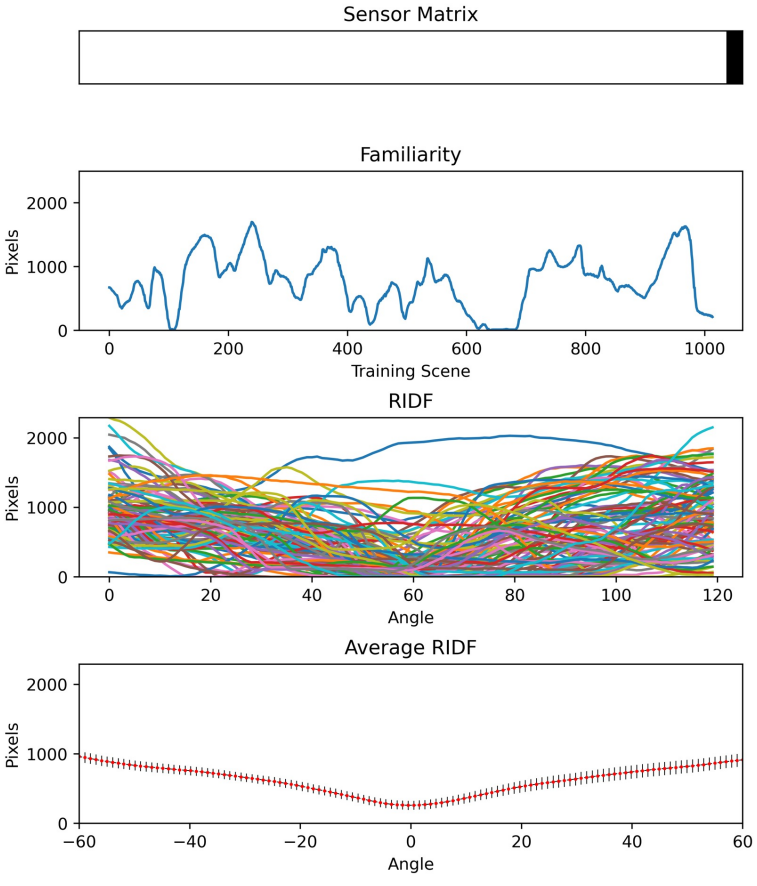
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2182.53; RMSD/dist: 5.456; TD: 808; p90: 76; p50: 40; complete: 0


Index: BLUR: 20.0; LEVELS: 128; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

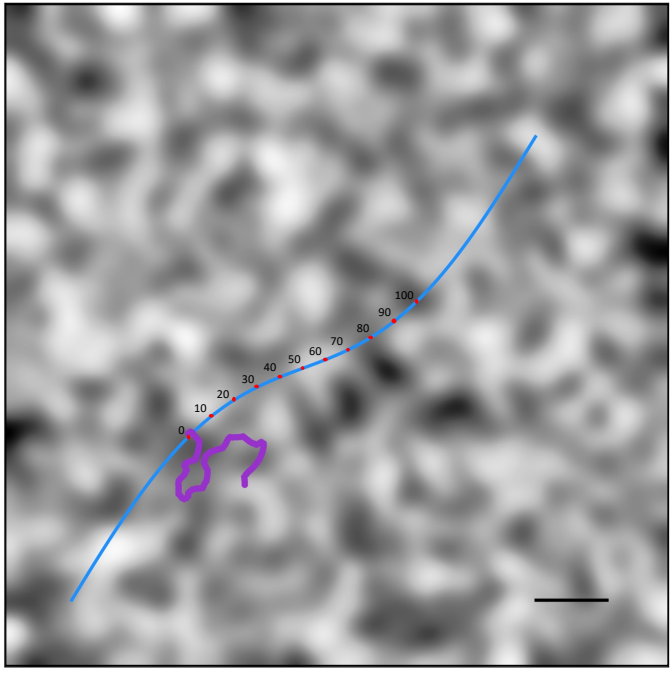


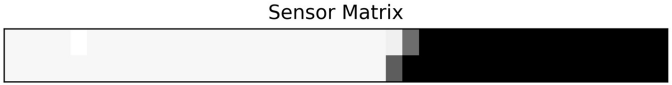


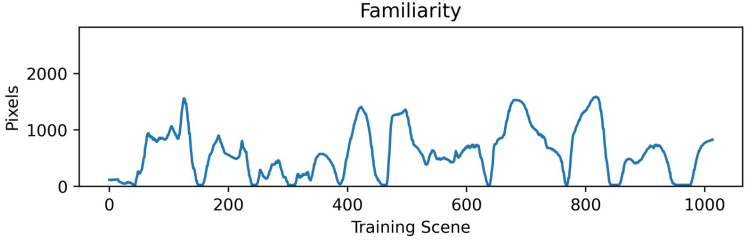
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

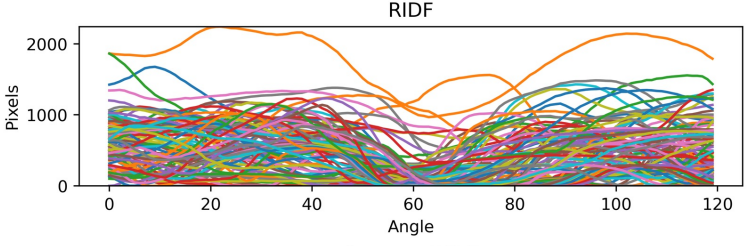
Navigation stats: RMSD error: 7237.86; RMSD/dist: 18.095; TD: 602; p90: 92; p50: 44; complete: 0

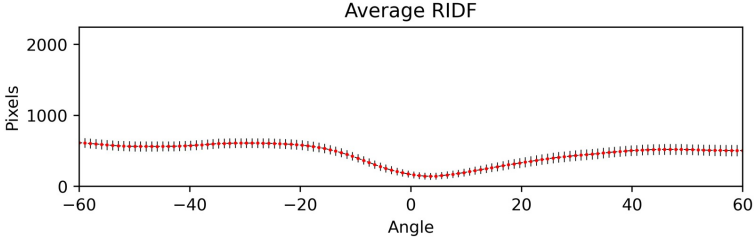
0%







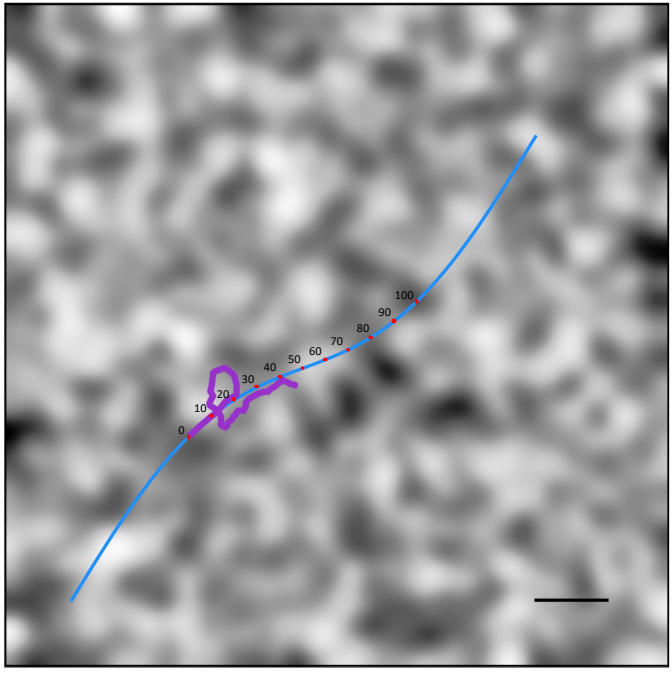


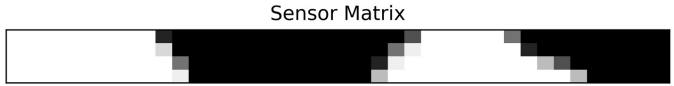


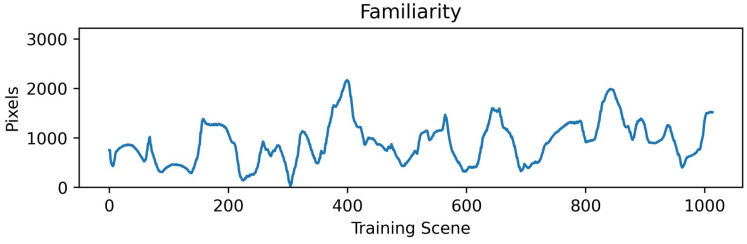
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

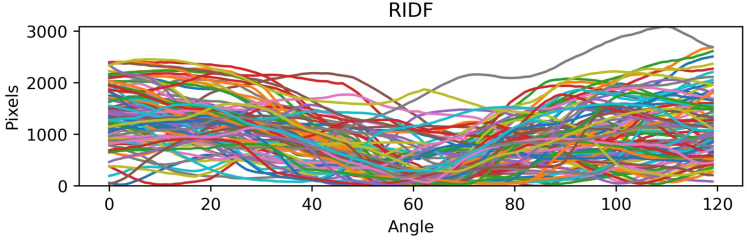
Navigation stats: RMSD error: 5322.77; RMSD/dist: 13.307; TD: 660; p90: 120; p50: 26; complete: 0

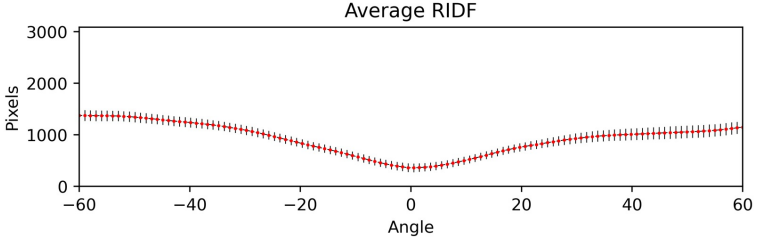
10%







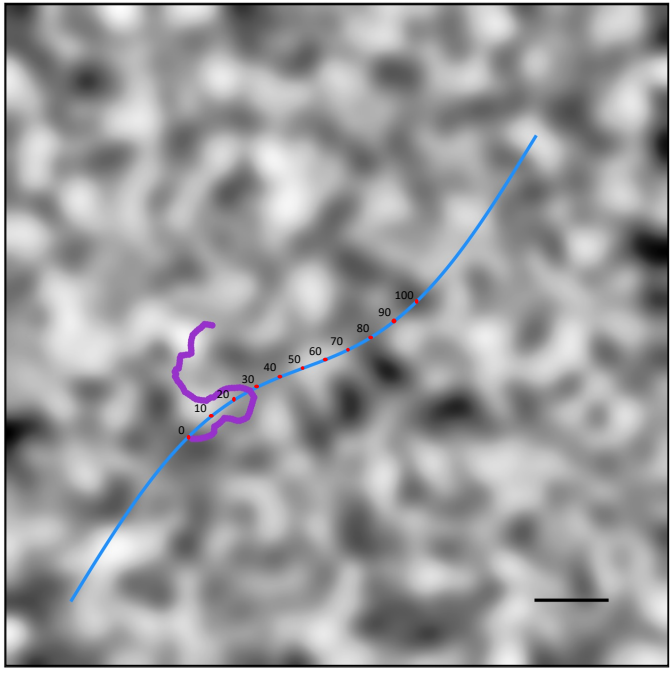


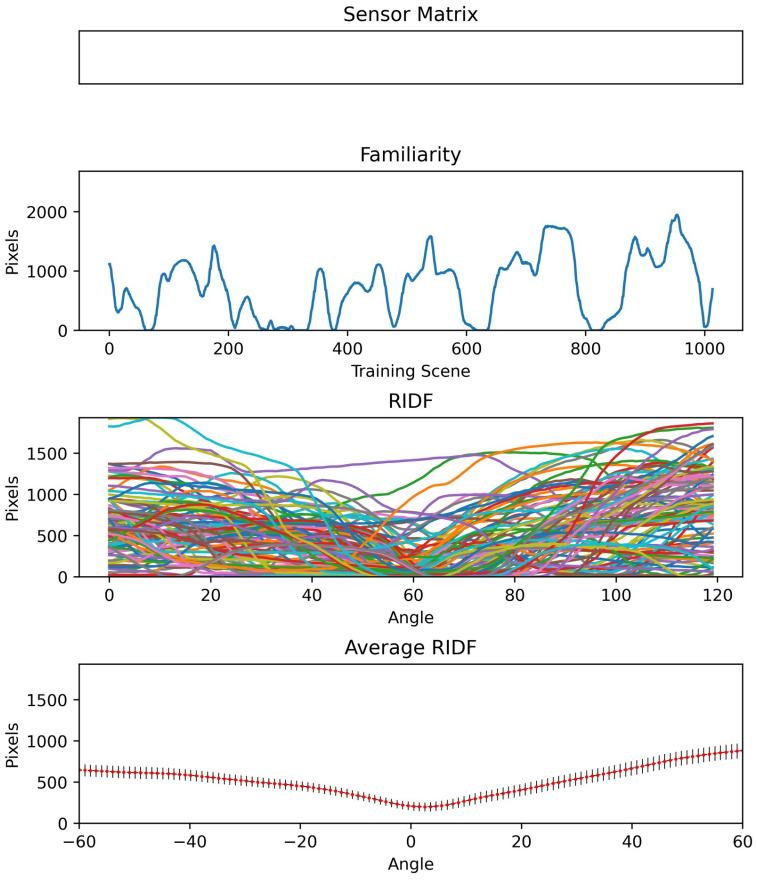


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1652.41; RMSD/dist: 4.131; TD: 697; p90: 52; p50: 30; complete: 0

0%

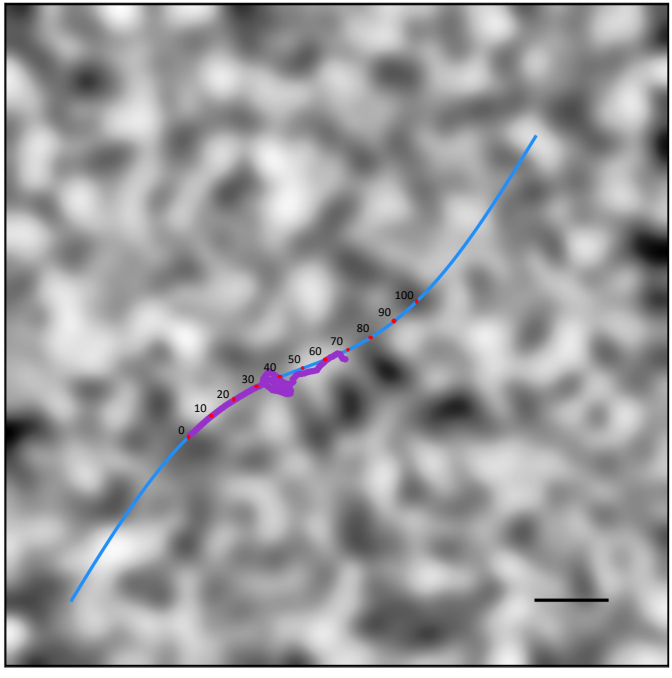


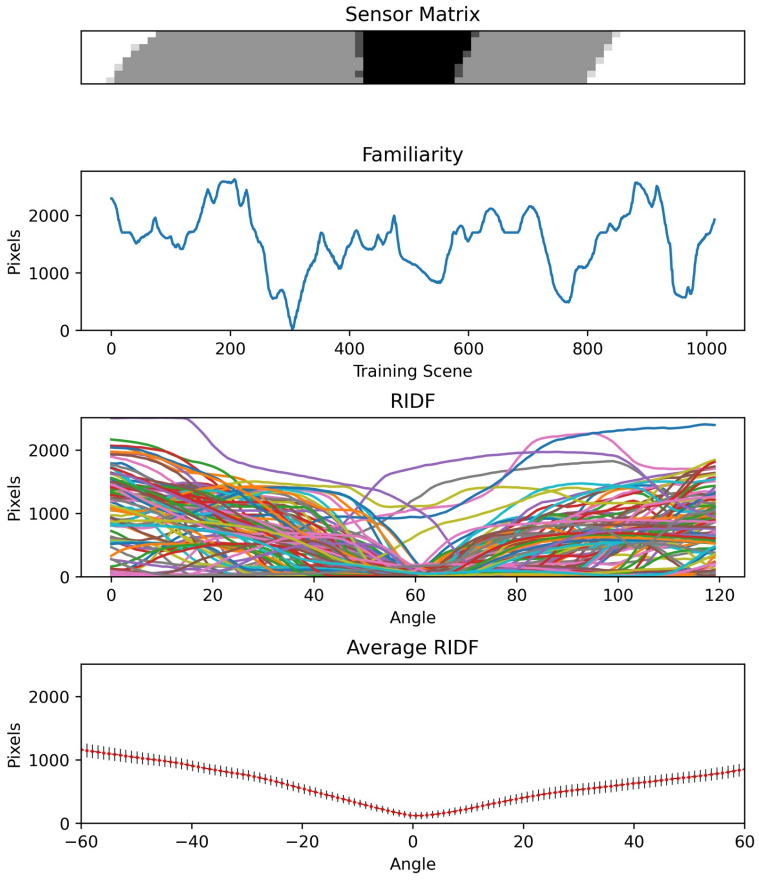


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4868.40; RMSD/dist: 12.171; TD: 644; p90: 120; p50: 62; complete: 0

40%

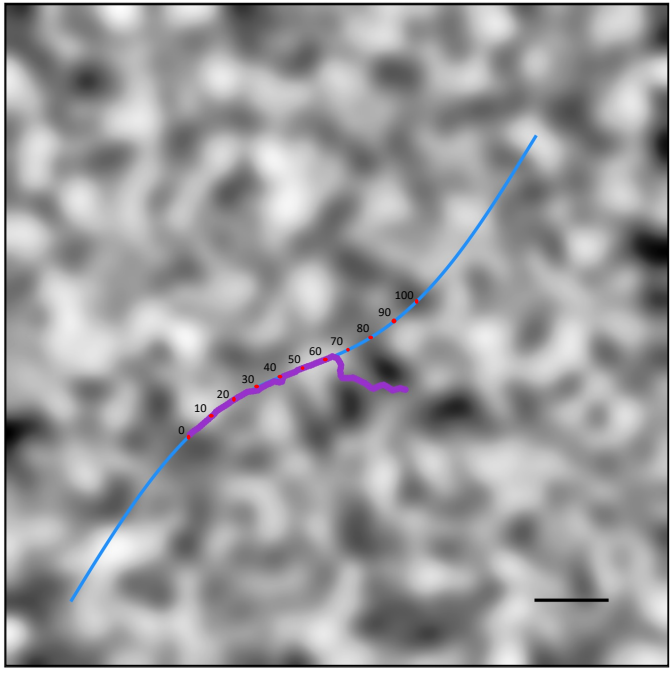


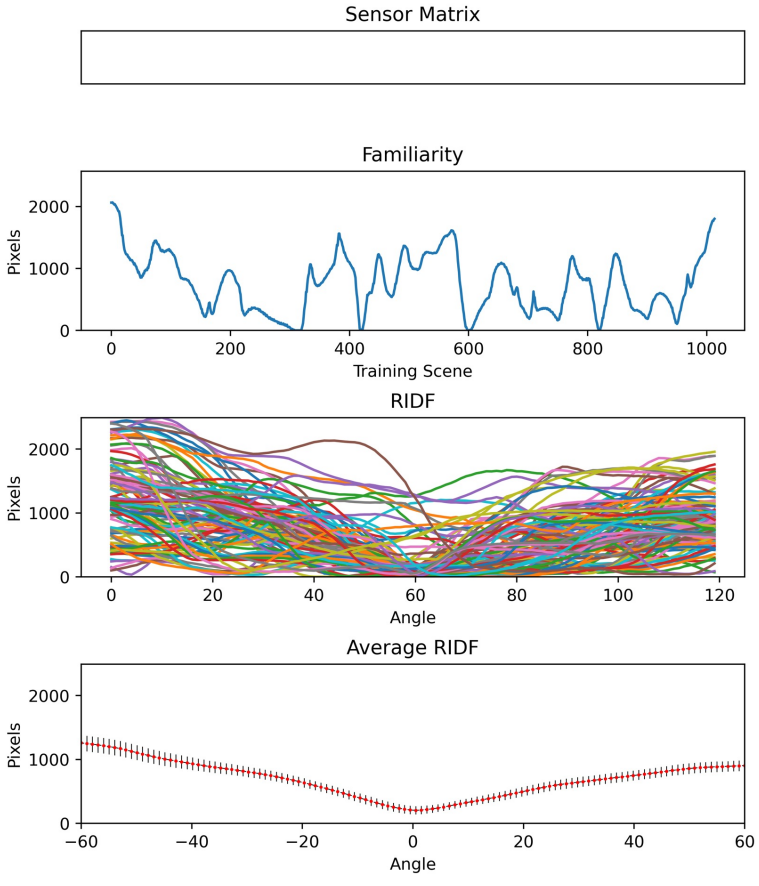


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 624.31; RMSD/dist: 1.561; TD: 897; p90: 82; p50: 42; complete: 0

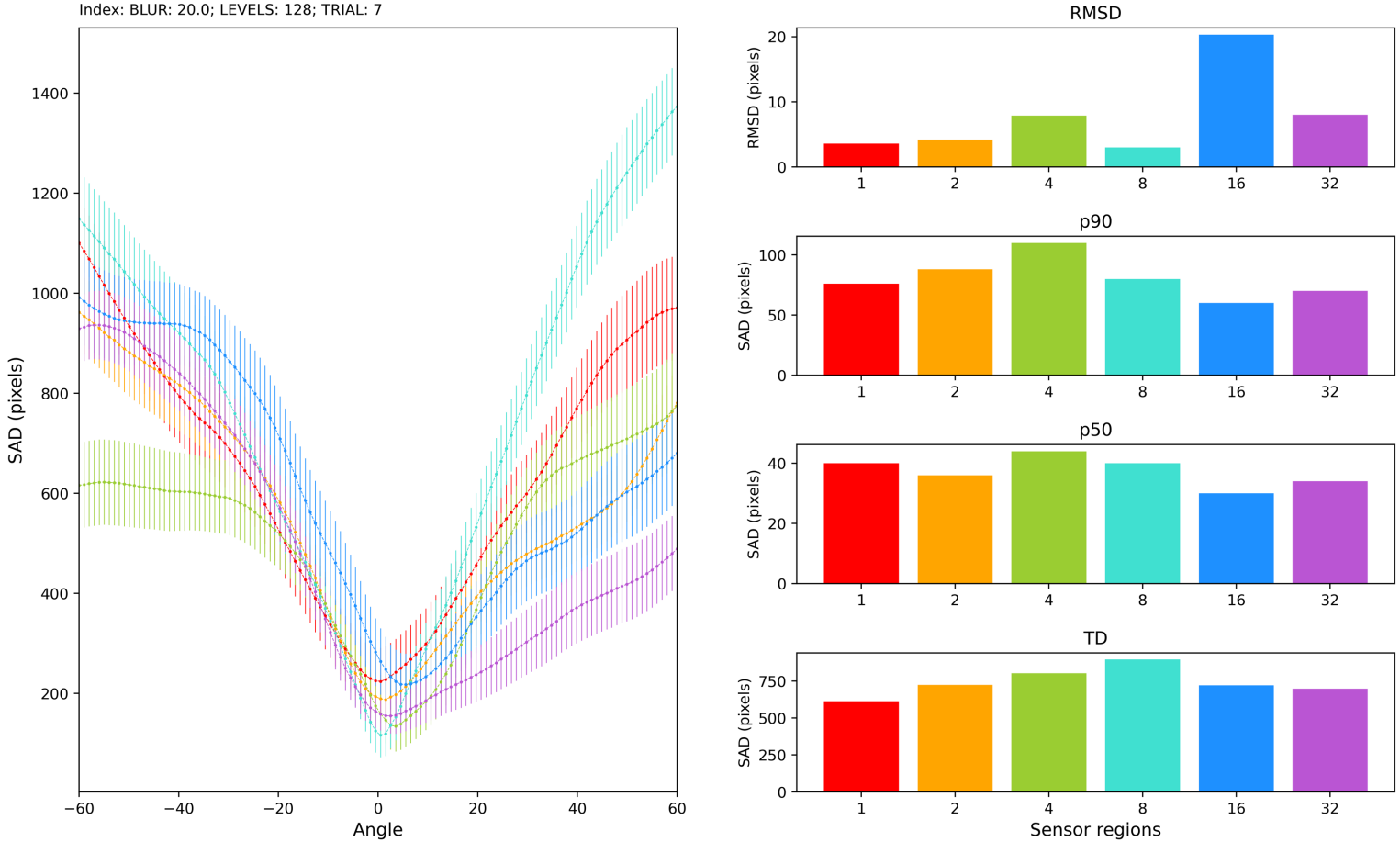
40%



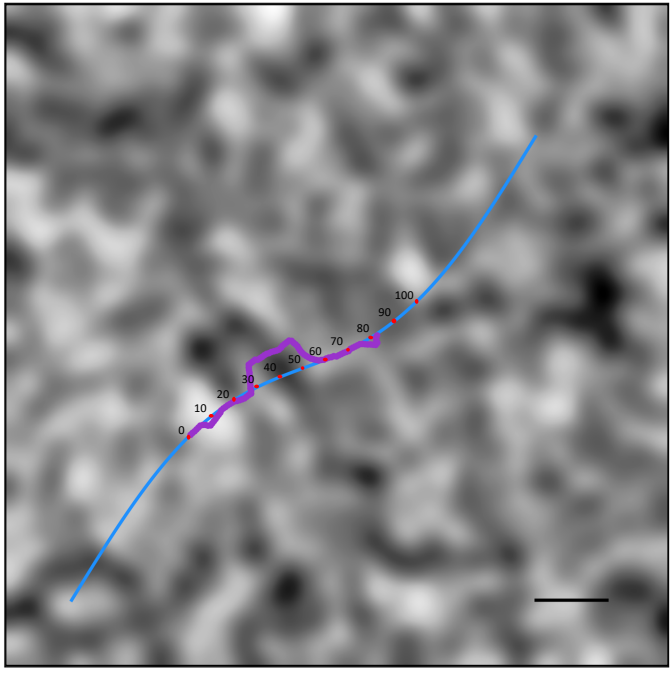


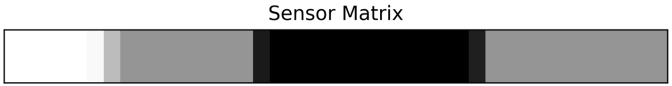
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

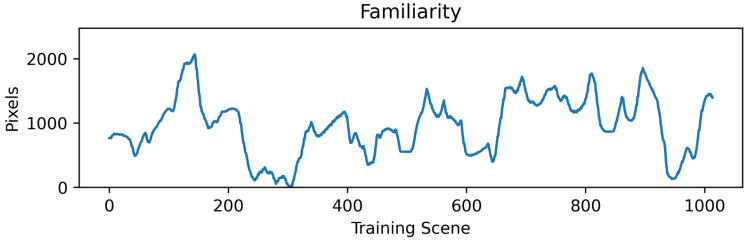
Navigation stats: RMSD error: 1975.33; RMSD/dist: 4.938; TD: 738; p90: 70; p50: 34; complete: 0

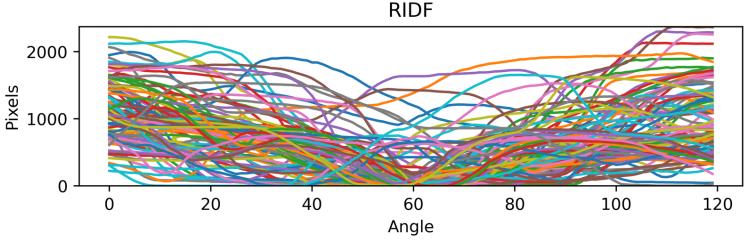

Index: BLUR: 20.0; LEVELS: 128; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

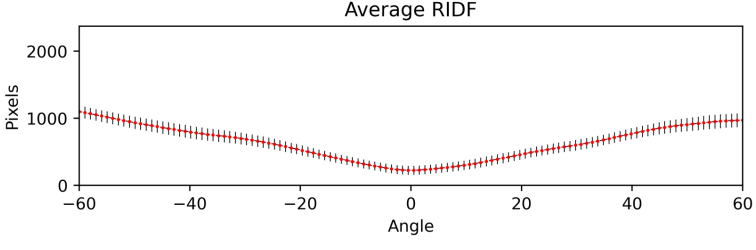
10%







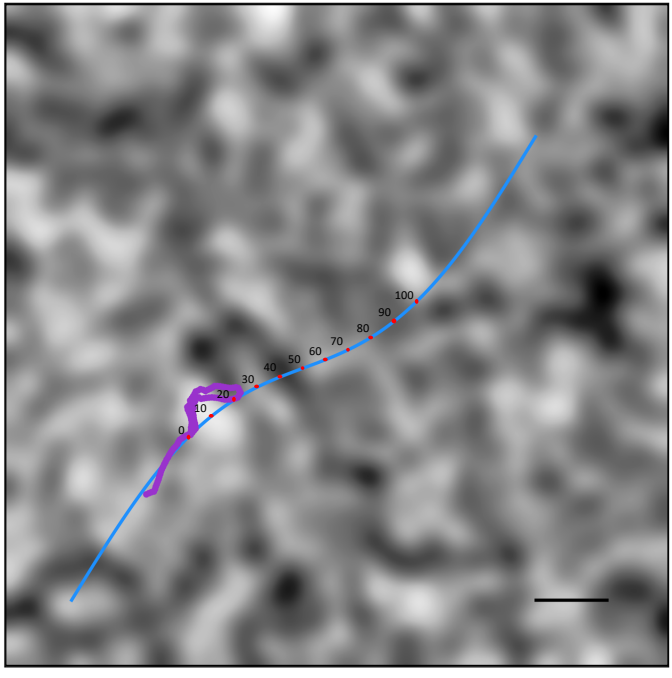


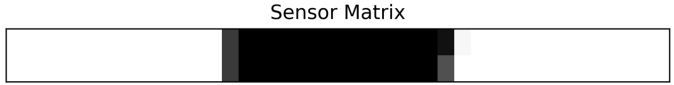


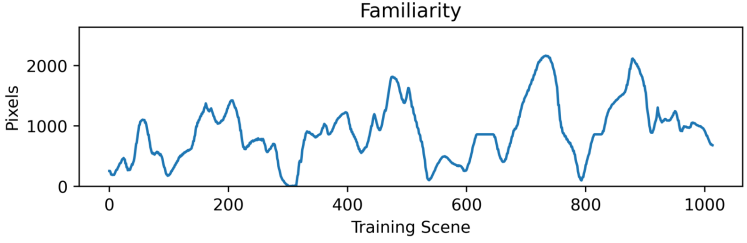
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

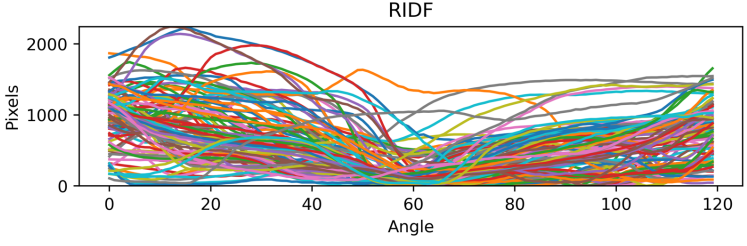
Navigation stats: RMSD error: 1423.48; RMSD/dist: 3.559; TD: 614; p90: 76; p50: 40; complete: 0

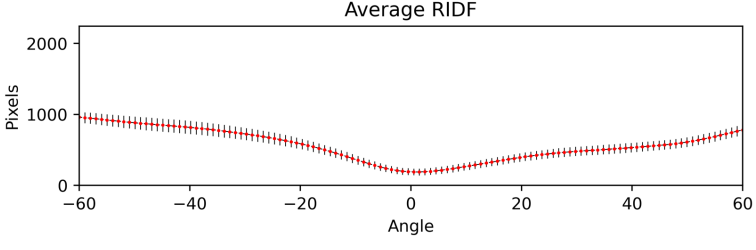
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1670.29; RMSD/dist: 4.176; TD: 724; p90: 88; p50: 36; complete: 0

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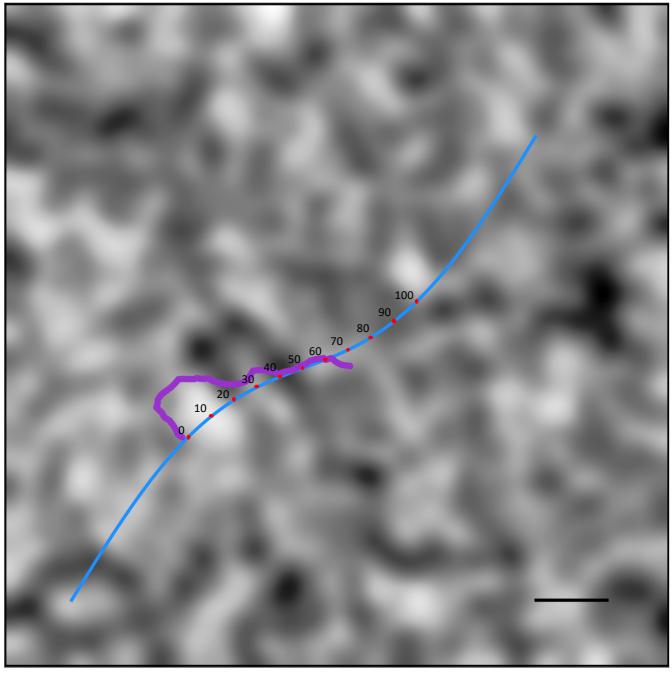
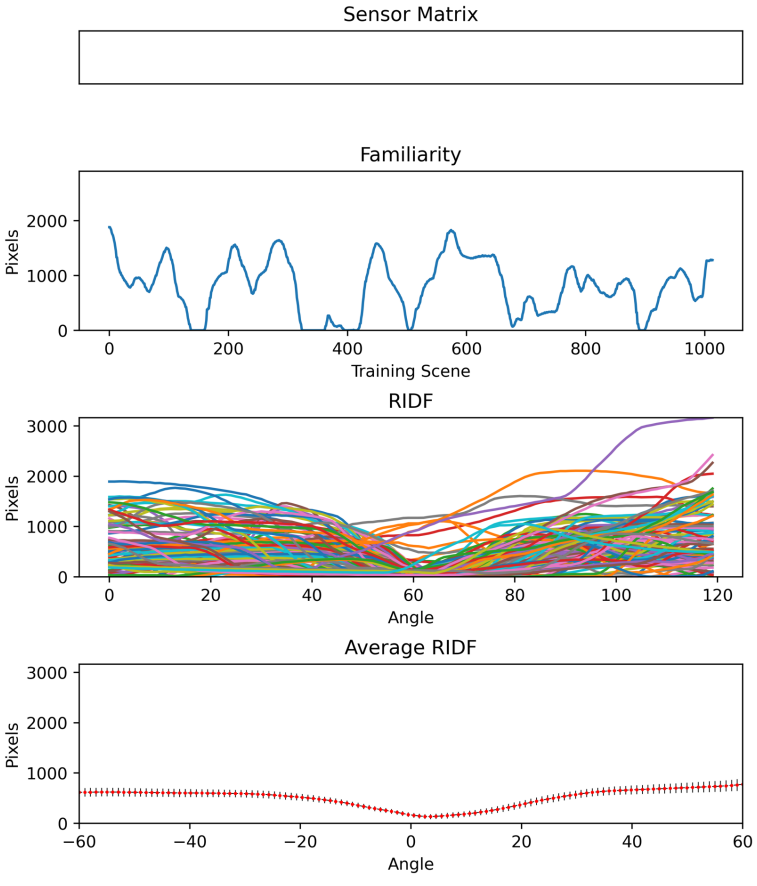
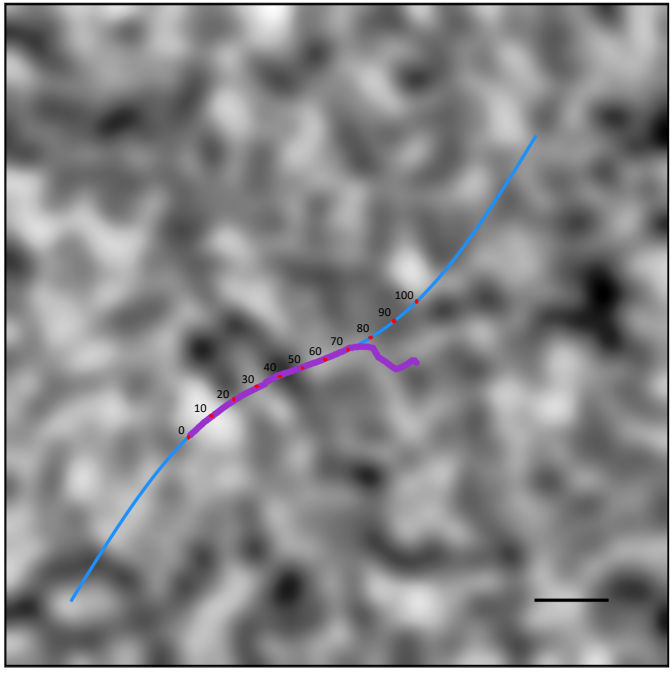


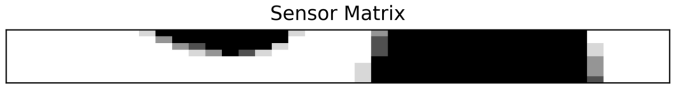


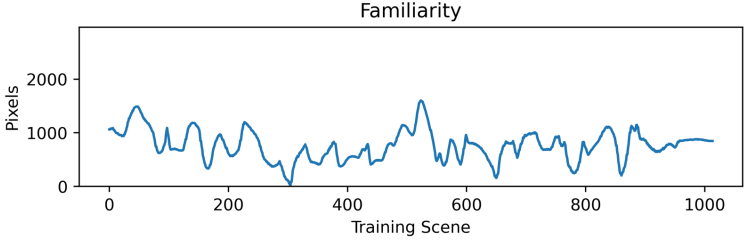
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

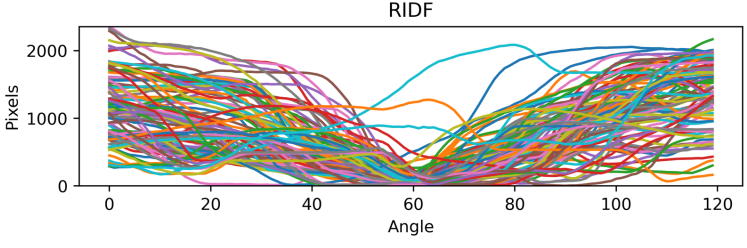
Navigation stats: RMSD error: 3151.70; RMSD/dist: 7.879; TD: 803; p90: 110; p50: 44; complete: 0

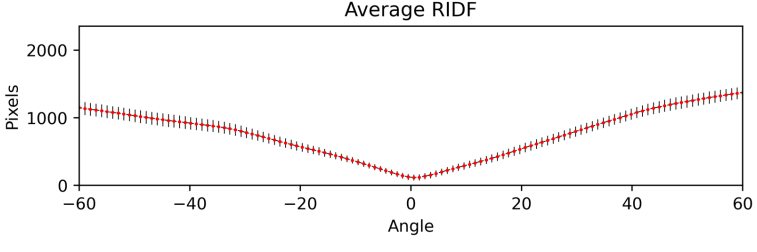
60%







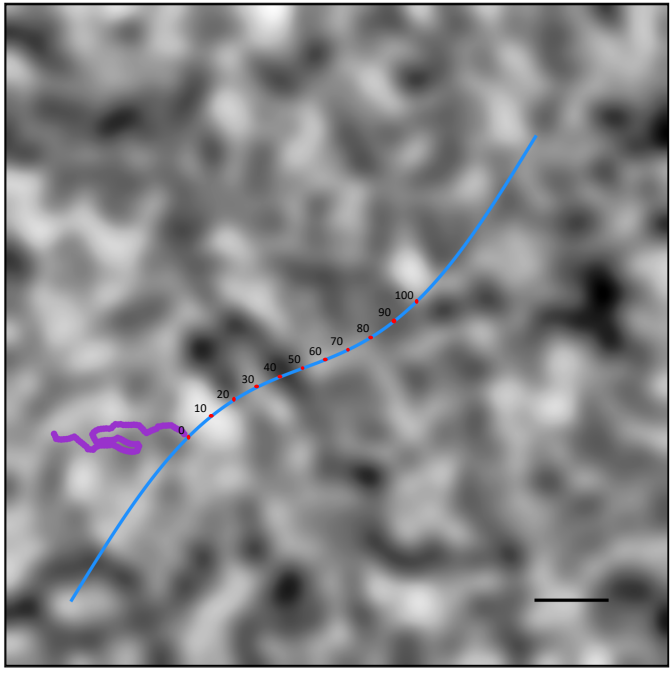


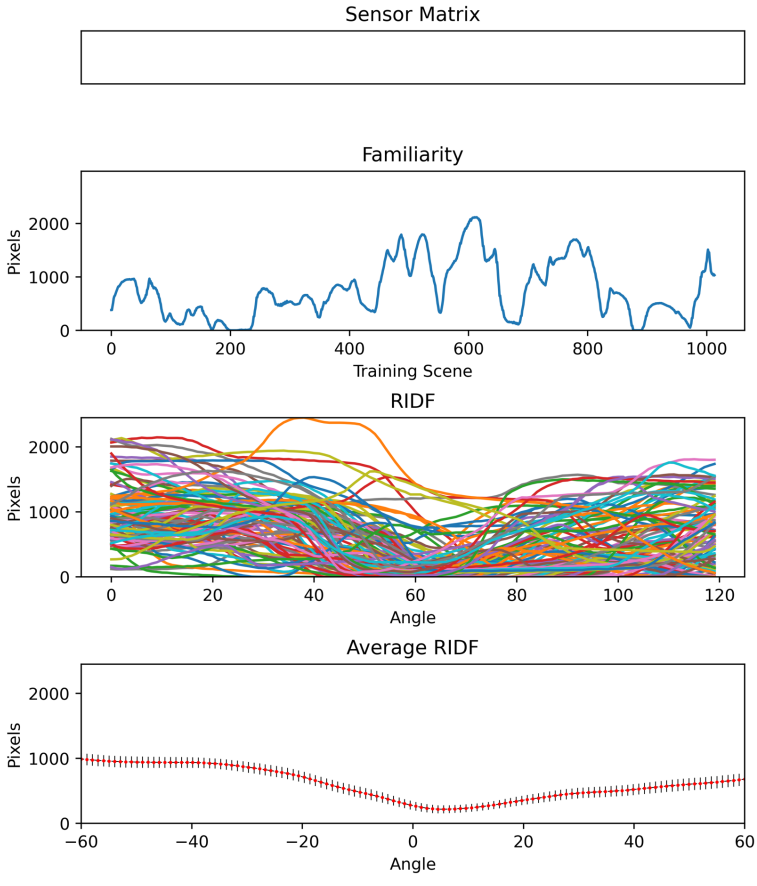


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1196.09; RMSD/dist: 2.990; TD: 896; p90: 80; p50: 40; complete: 0

0%

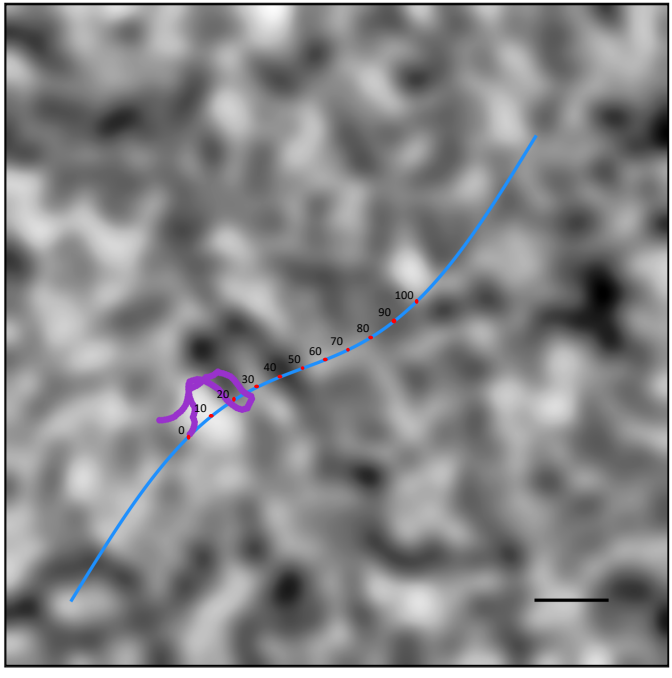


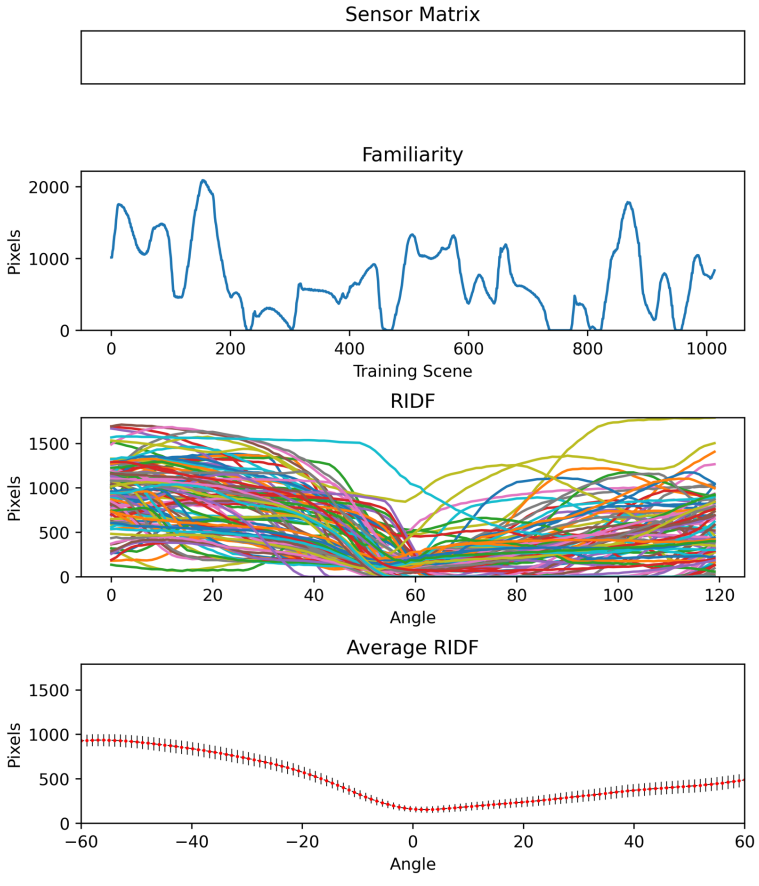


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 8130.61; RMSD/dist: 20.327; TD: 721; p90: 60; p50: 30; complete: 0

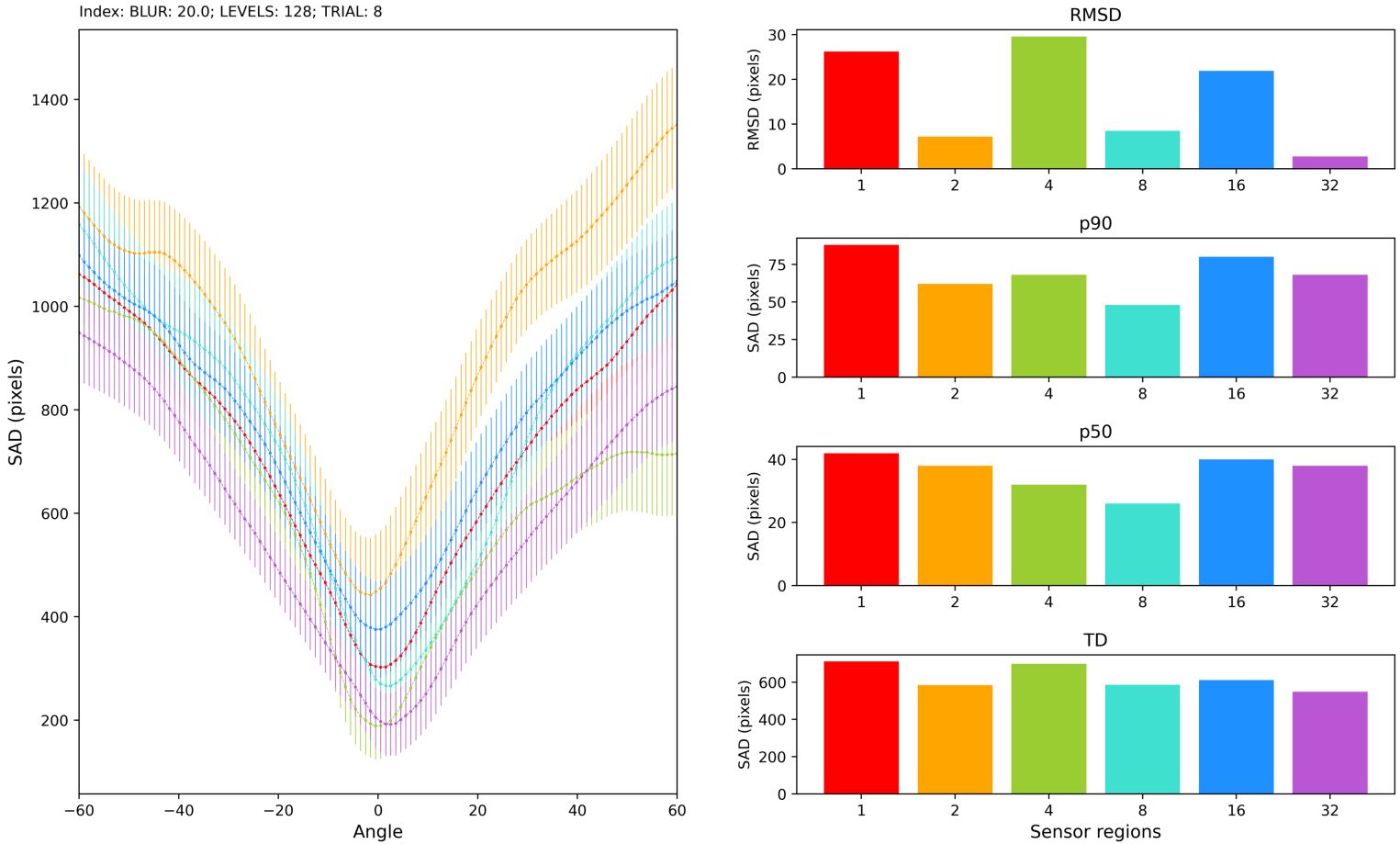
0%



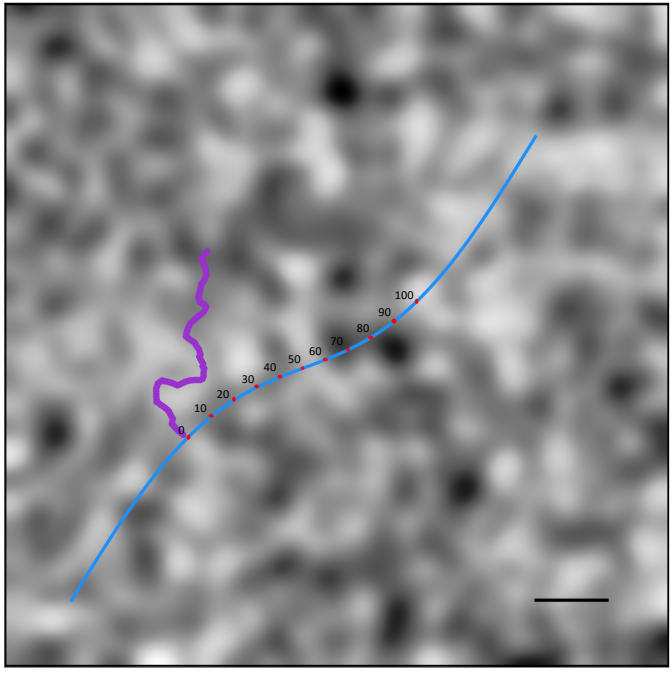


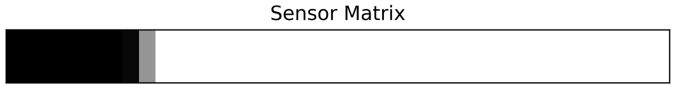
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

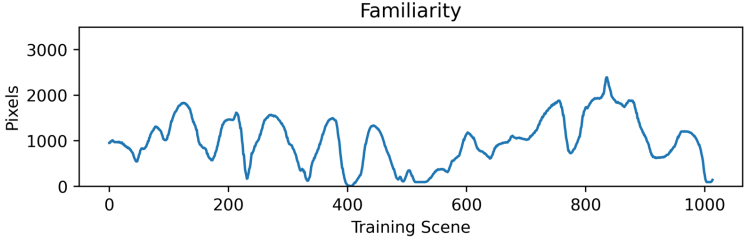
Navigation stats: RMSD error: 3206.46; RMSD/dist: 8.016; TD: 698; p90: 70; p50: 34; complete: 0

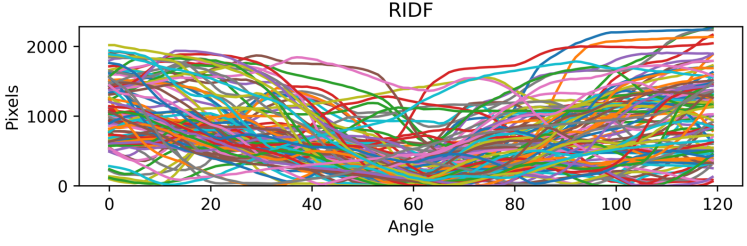

Index: BLUR: 20.0; LEVELS: 128; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

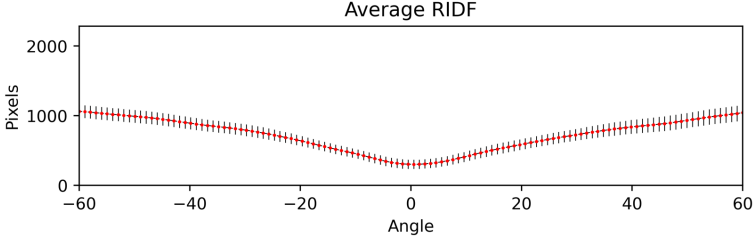
0%







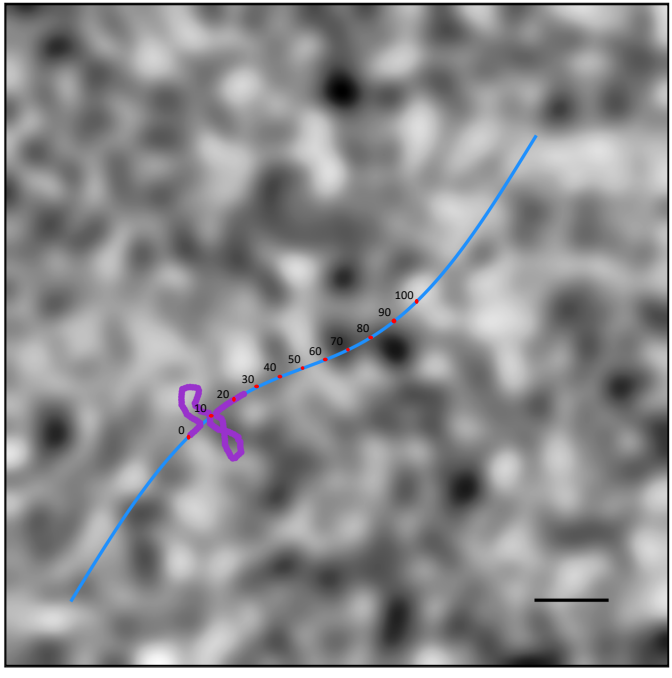


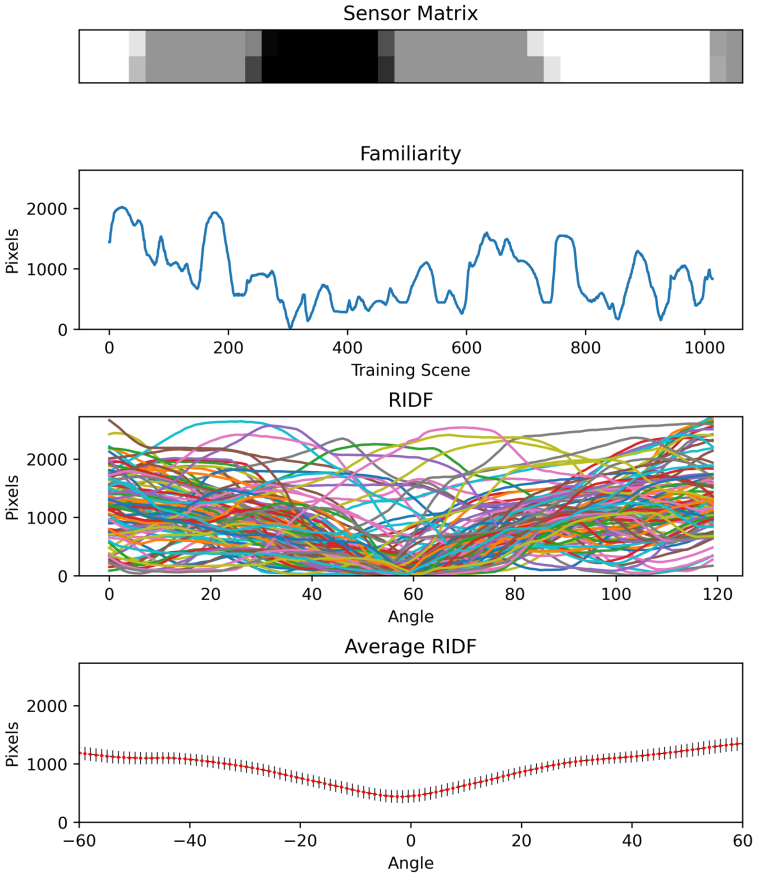


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 10490.44; RMSD/dist: 26.226; TD: 711; p90: 88; p50: 42; complete: 0

20%

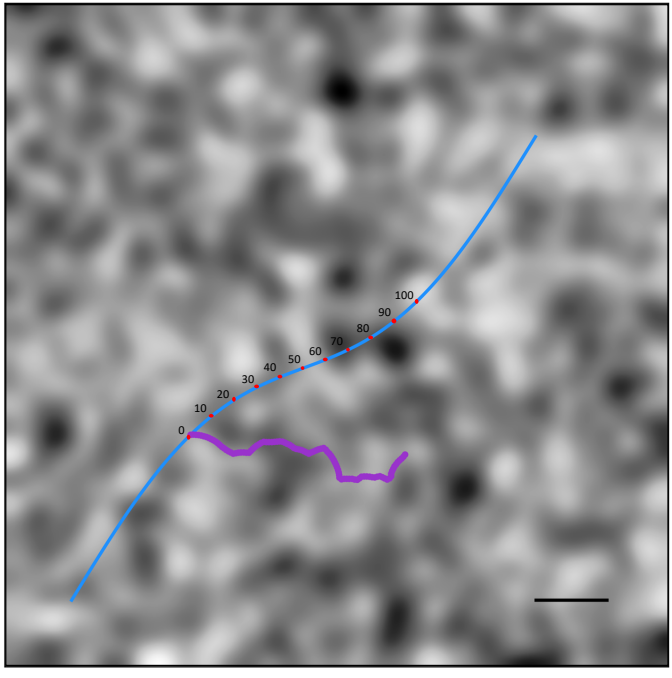


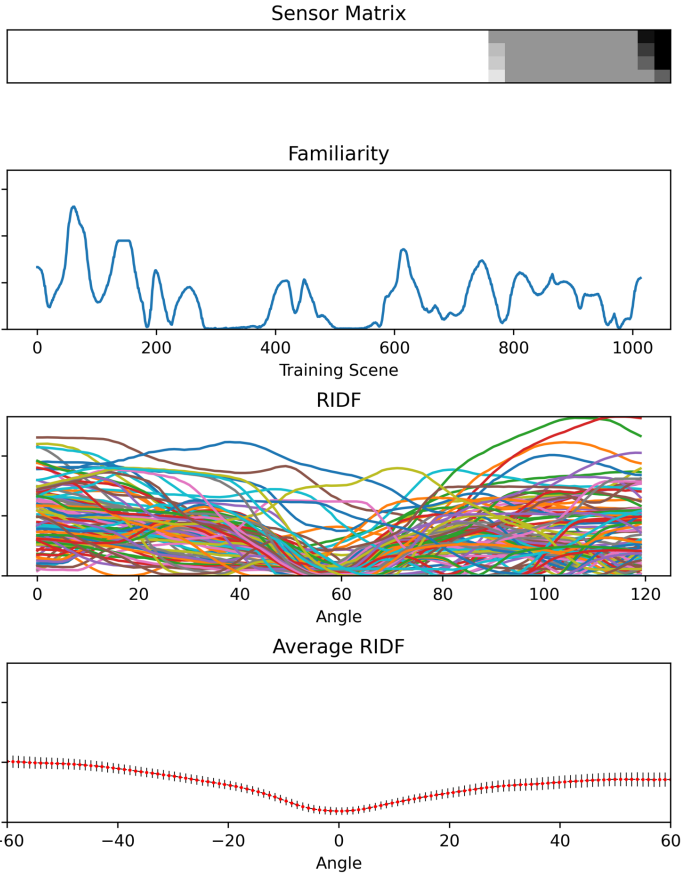


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2883.36; RMSD/dist: 7.208; TD: 584; p90: 62; p50: 38; complete: 0

0%

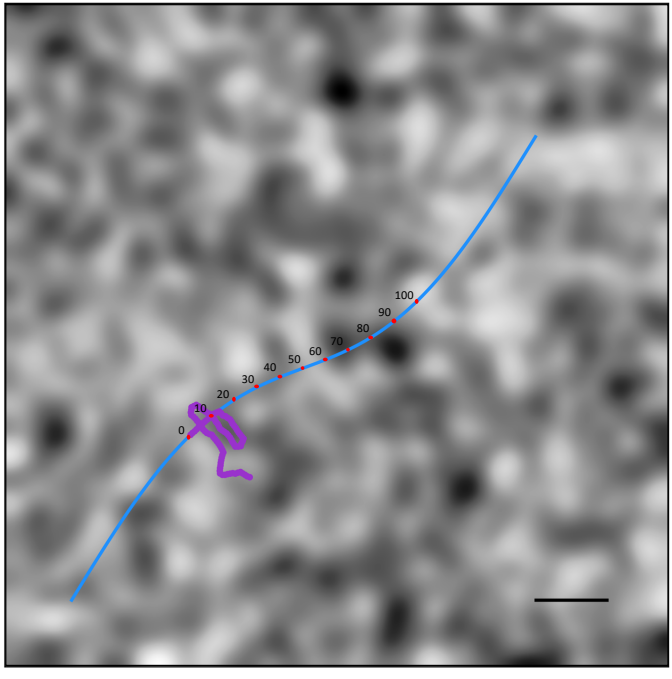


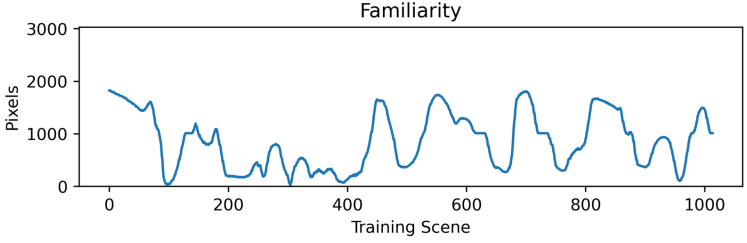


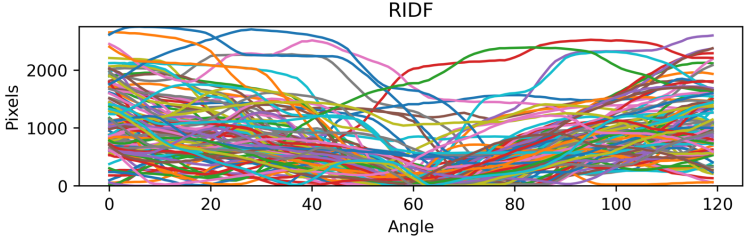
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

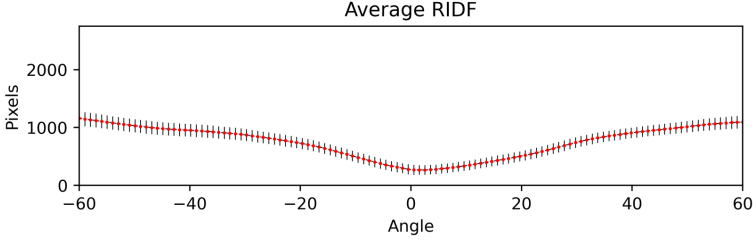
Navigation stats: RMSD error: 11846.68; RMSD/dist: 29.617; TD: 699; p90: 68; p50: 32; complete: 0

10%





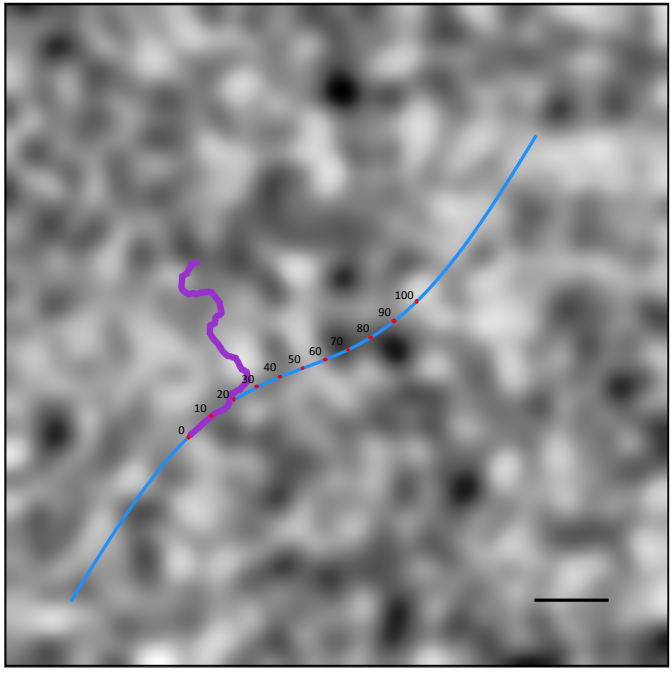


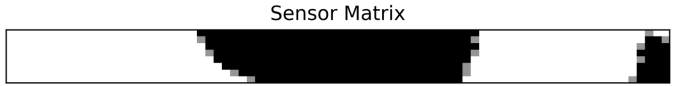


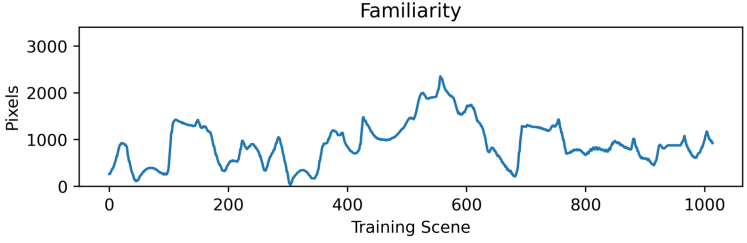
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

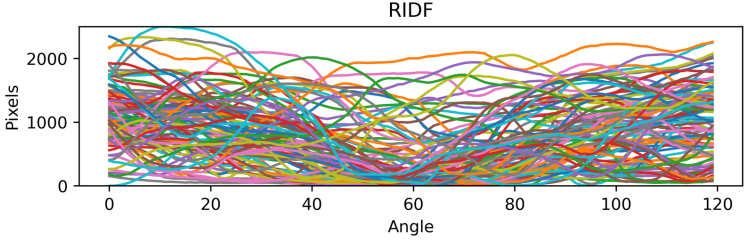
Navigation stats: RMSD error: 3400.61; RMSD/dist: 8.502; TD: 586; p90: 48; p50: 26; complete: 0

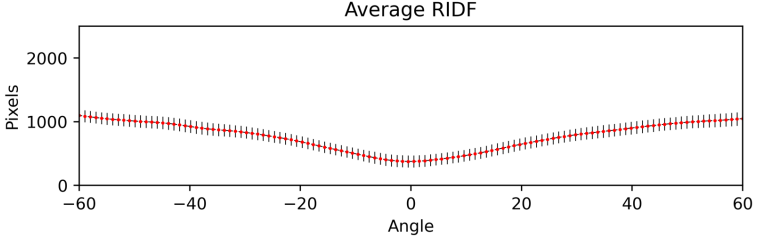
10%







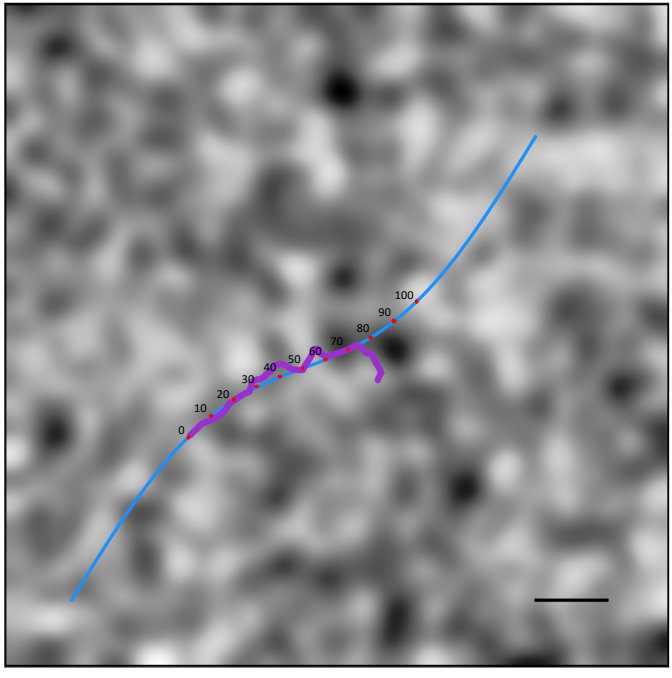


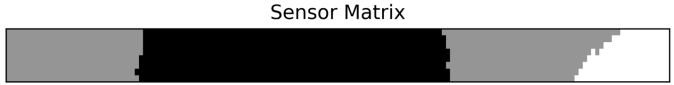


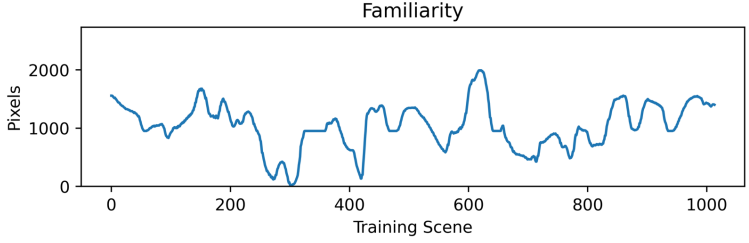
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

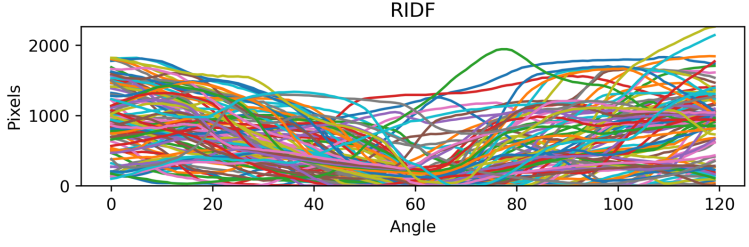
Navigation stats: RMSD error: 8758.42; RMSD/dist: 21.896; TD: 611; p90: 80; p50: 40; complete: 0

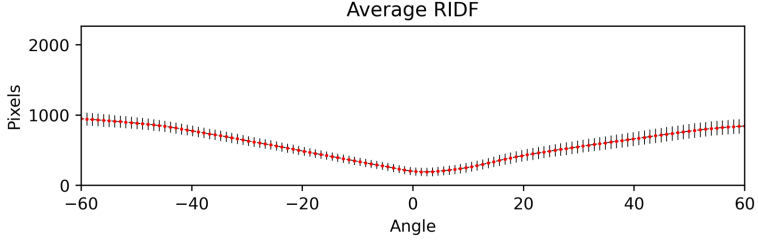
20%





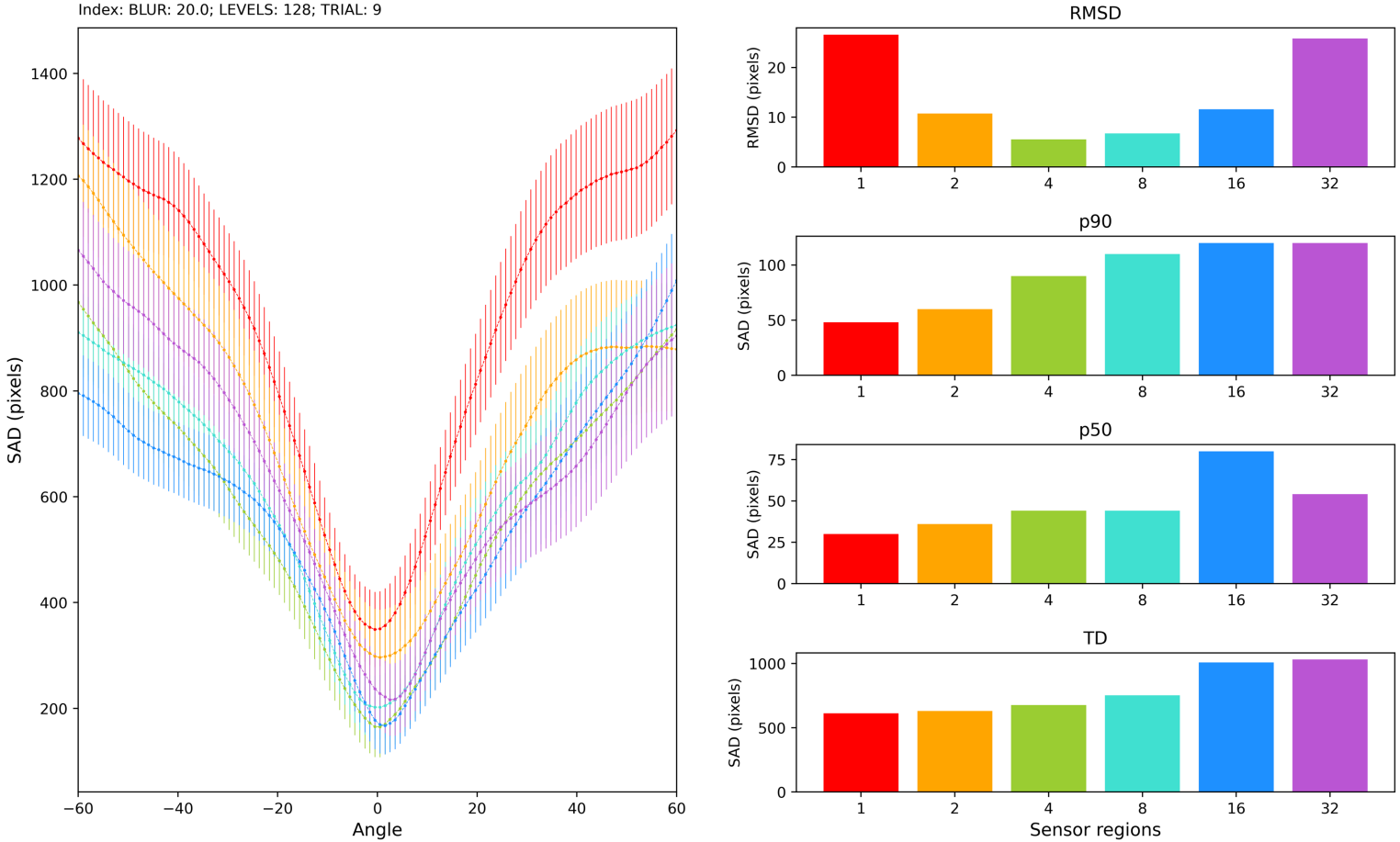




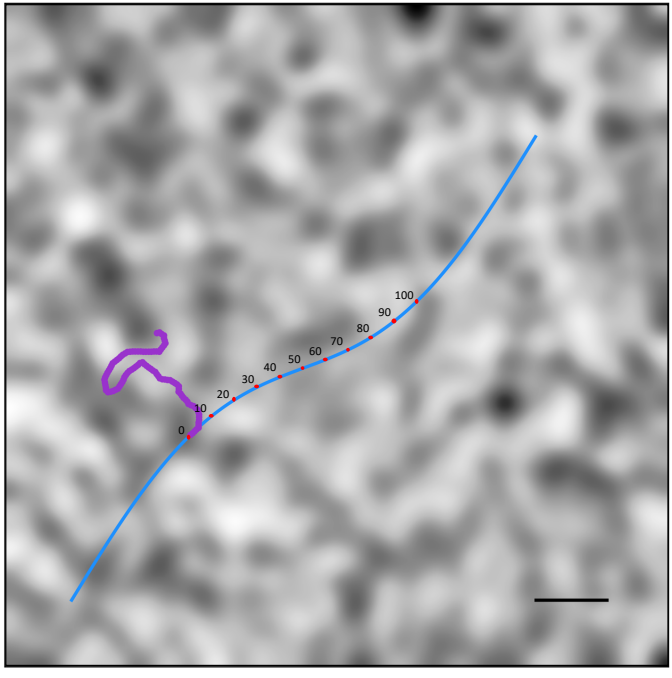


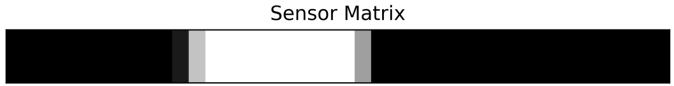
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

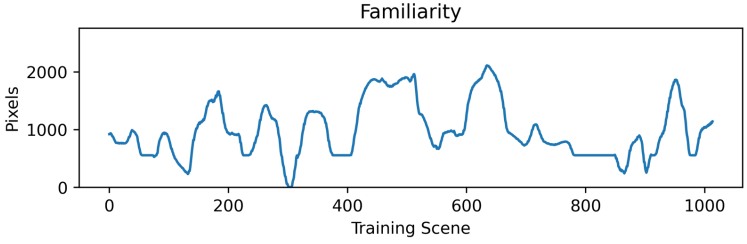
Navigation stats: RMSD error: 1087.84; RMSD/dist: 2.720; TD: 549; p90: 68; p50: 38; complete: 0

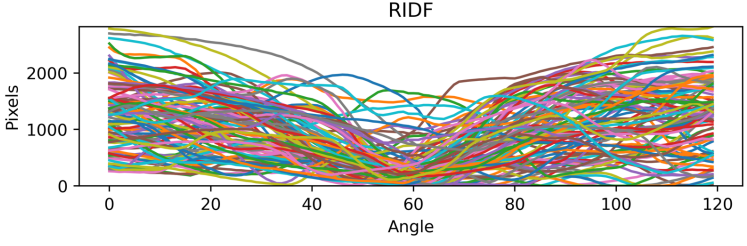

Index: BLUR: 20.0; LEVELS: 128; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

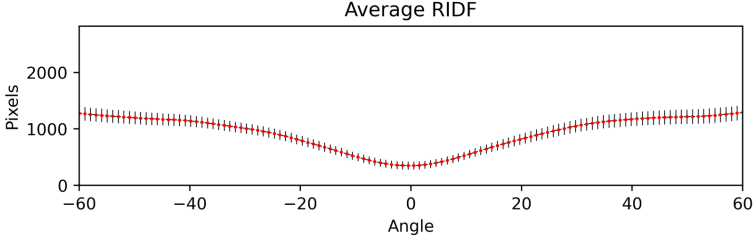
0%







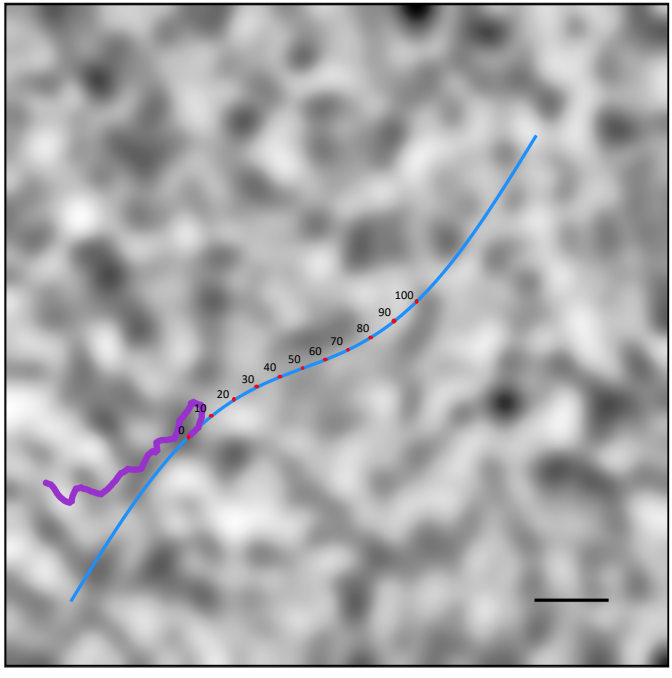


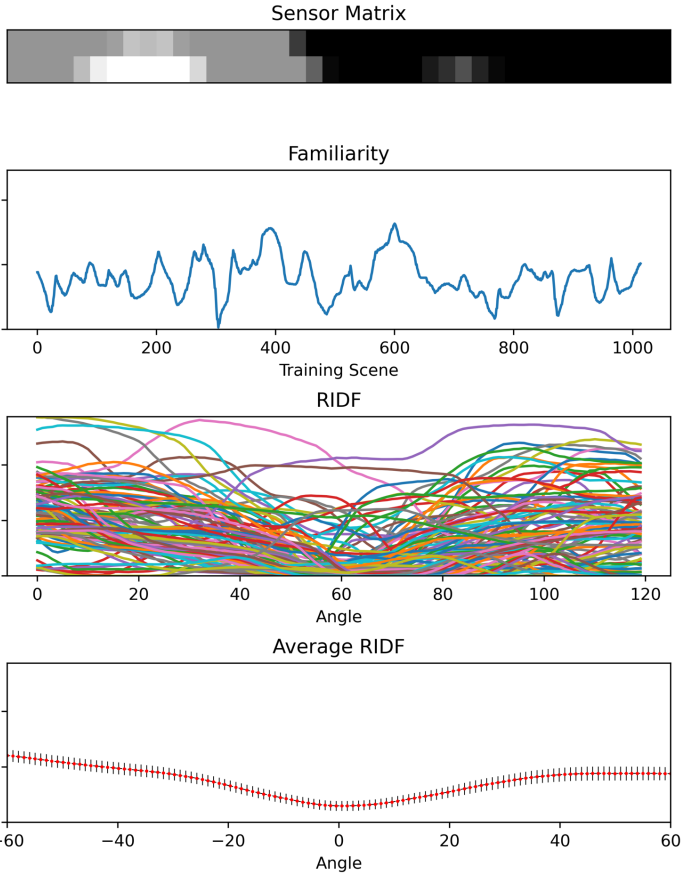


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 10643.32; RMSD/dist: 26.608; TD: 613; p90: 48; p50: 30; complete: 0

0%

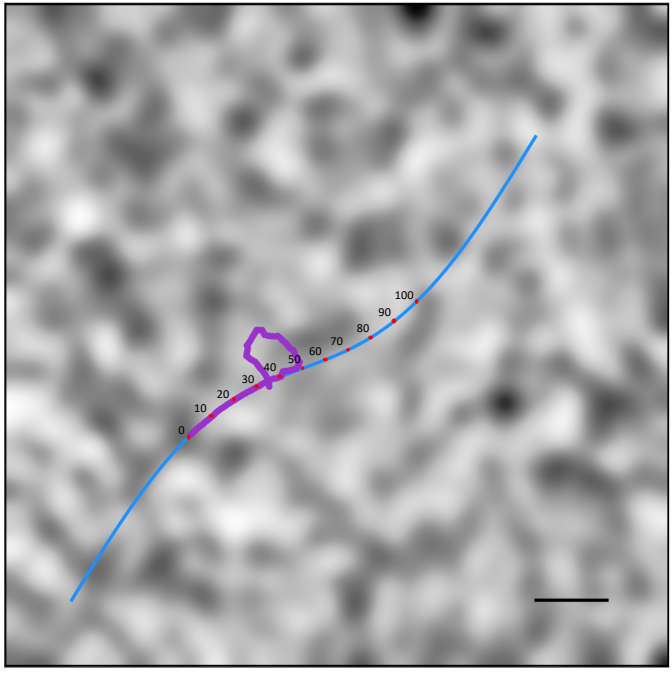


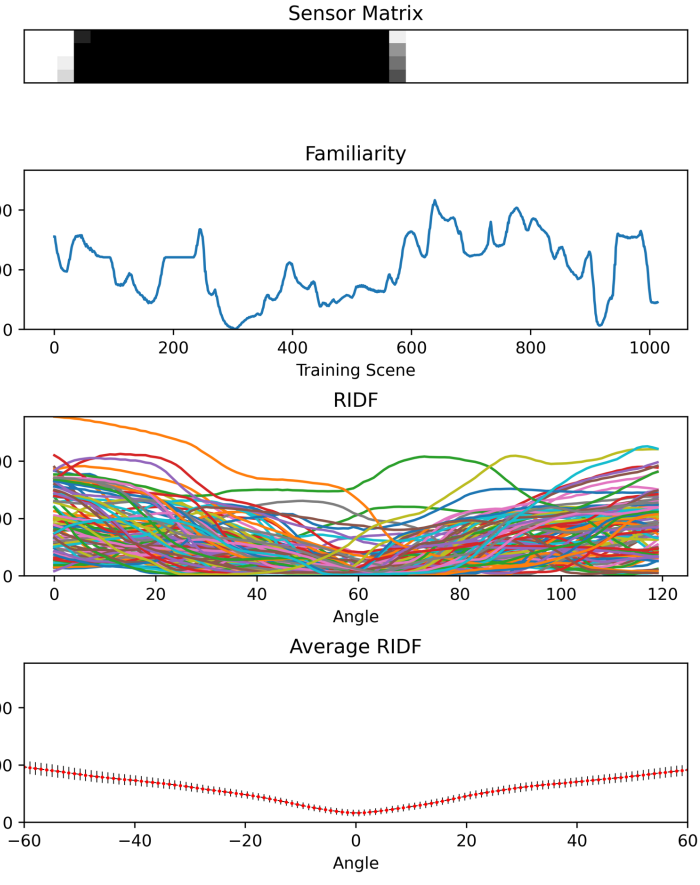


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 4297.19; RMSD/dist: 10.743; TD: 631; p90: 60; p50: 36; complete: 0

40%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2217.53; RMSD/dist: 5.544; TD: 677; p90: 90; p50: 44; complete: 0

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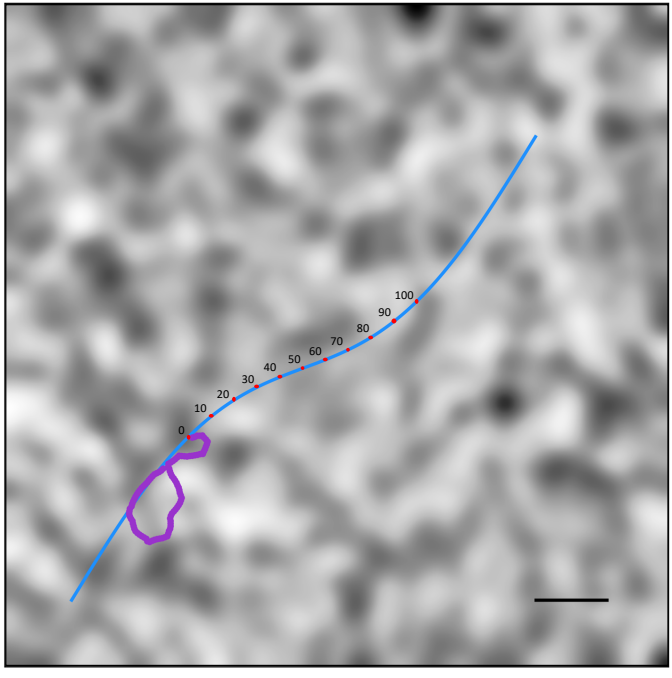
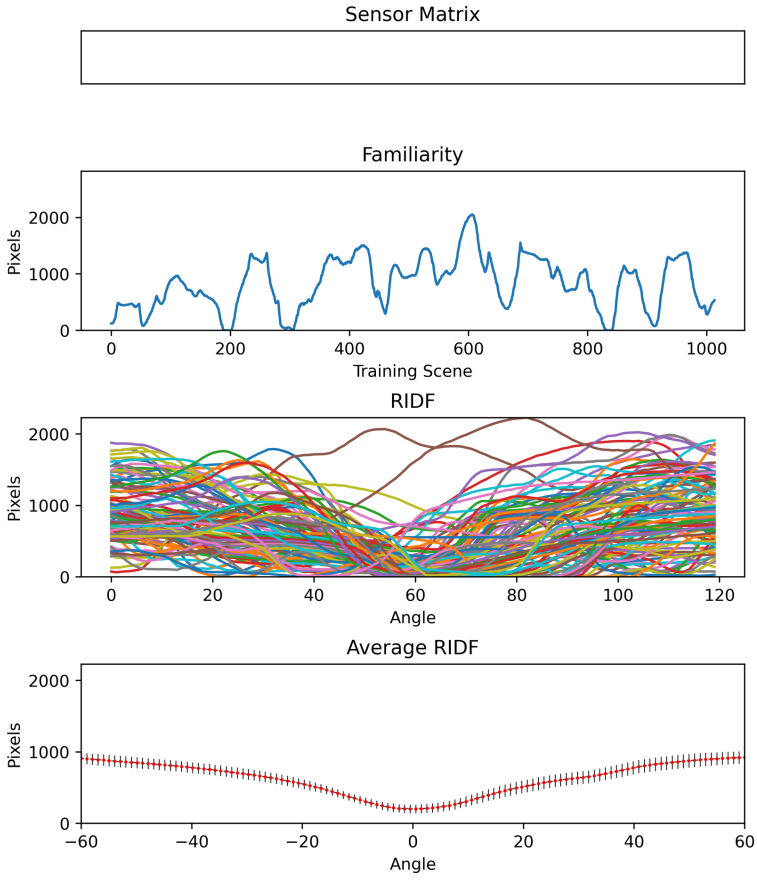
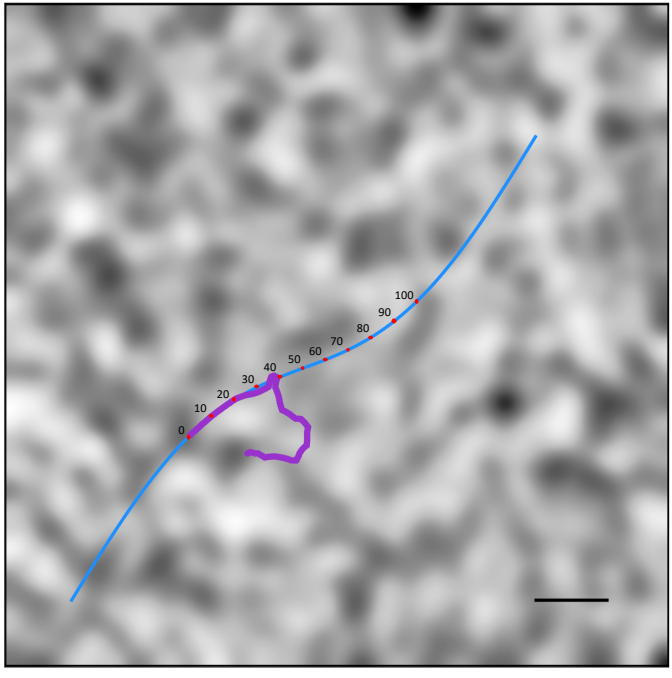


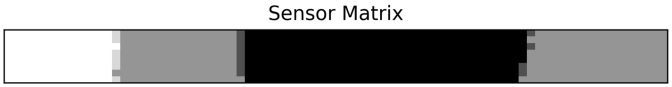


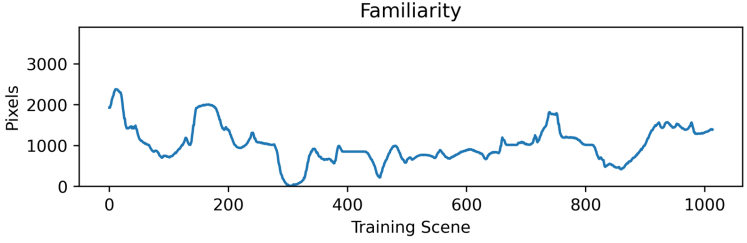
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

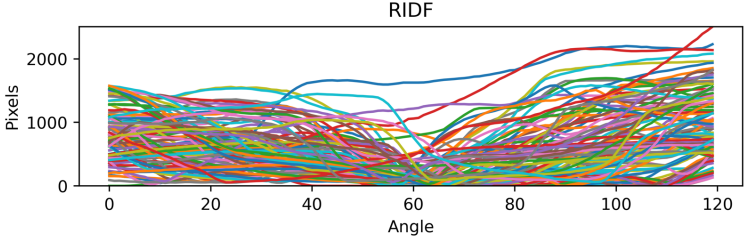
Navigation stats: RMSD error: 2689.46; RMSD/dist: 6.724; TD: 752; p90: 110; p50: 44; complete: 0

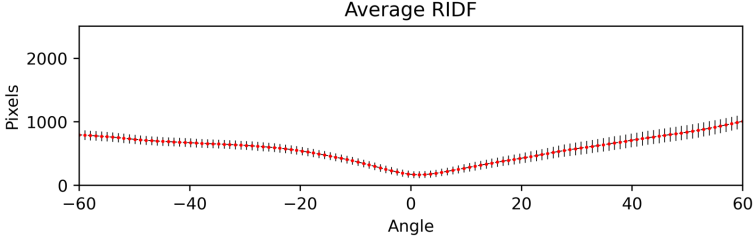
20%







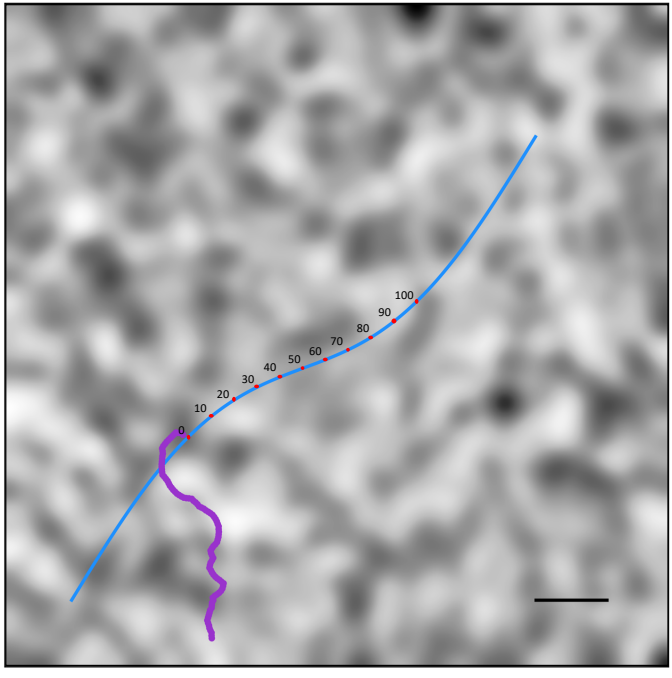


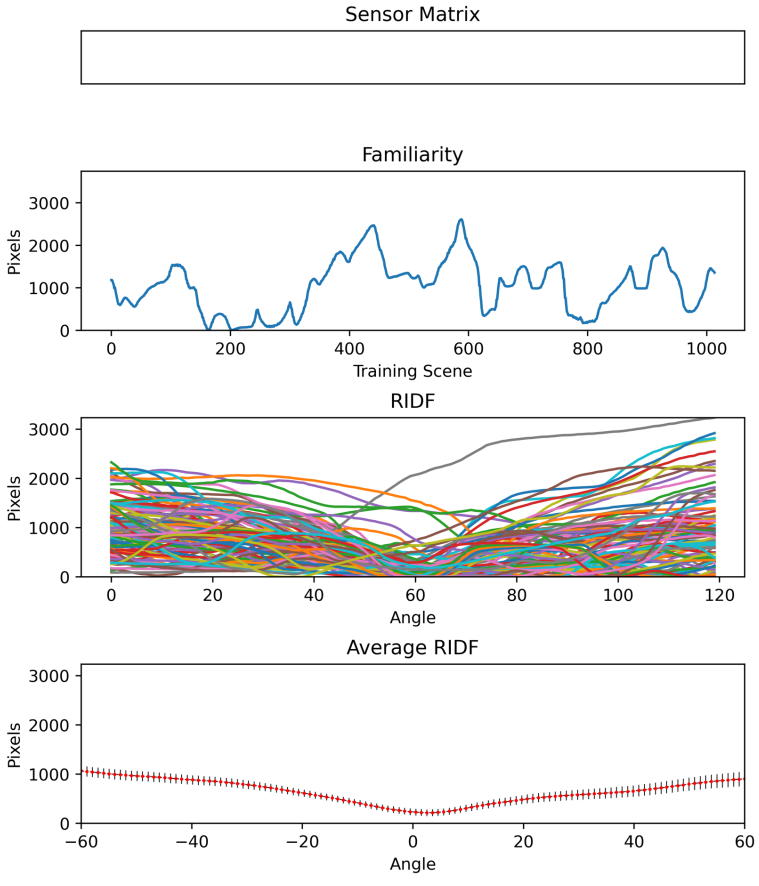


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 4626.11; RMSD/dist: 11.565; TD: 1008; p90: 120; p50: 80; complete: 0

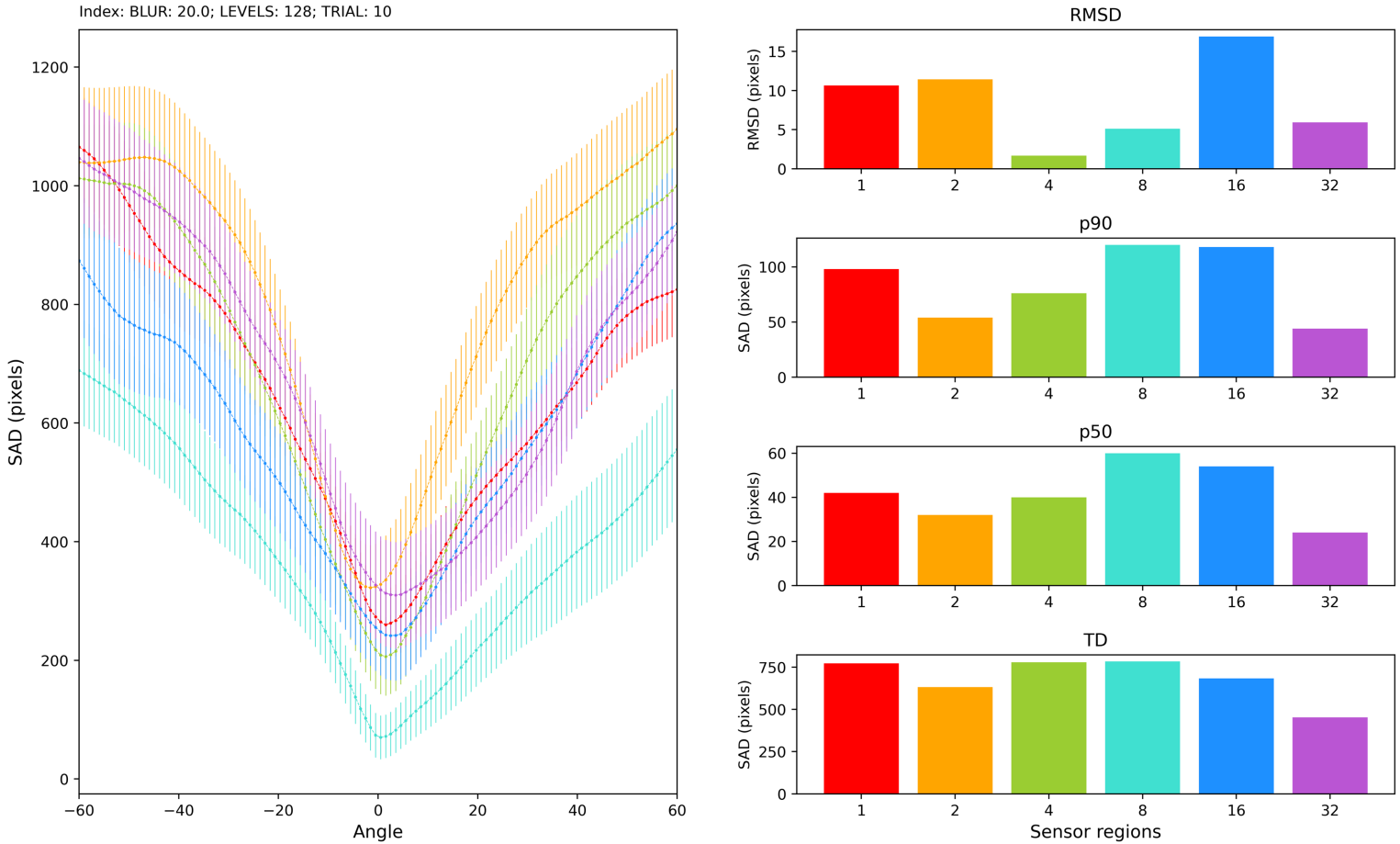
0%



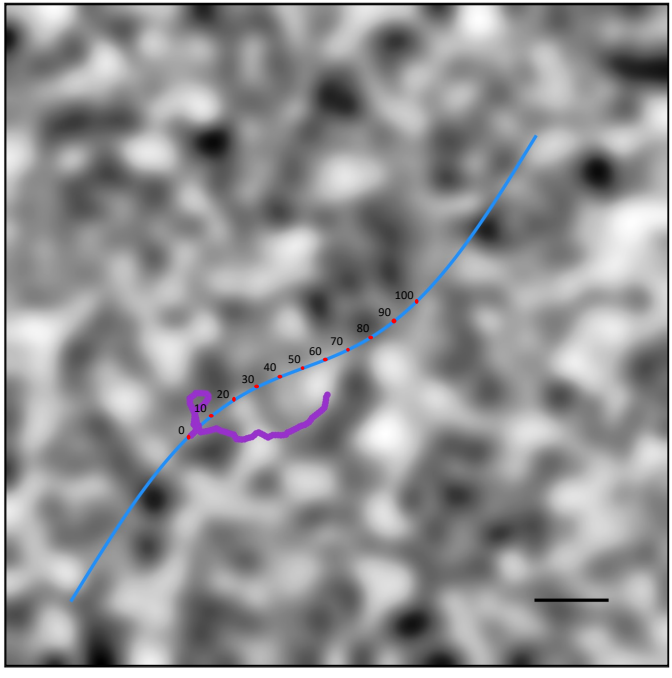


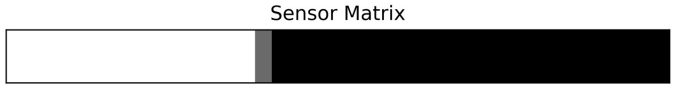
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

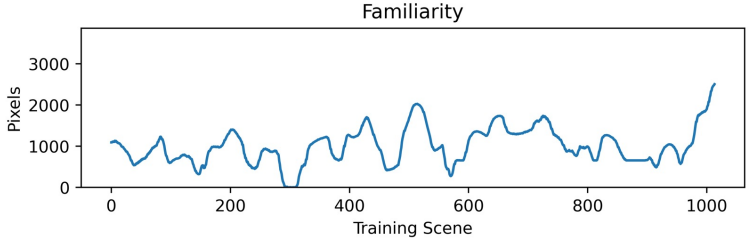
Navigation stats: RMSD error: 10322.26; RMSD/dist: 25.806; TD: 1031; p90: 120; p50: 54; complete: 0

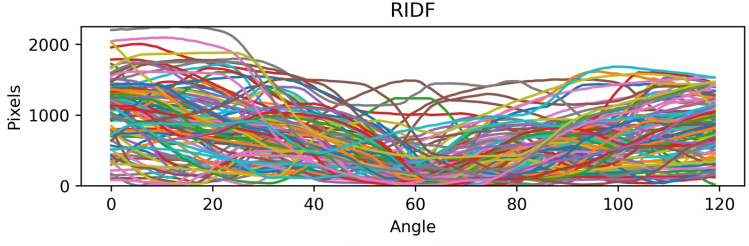

Index: BLUR: 20.0; LEVELS: 128; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

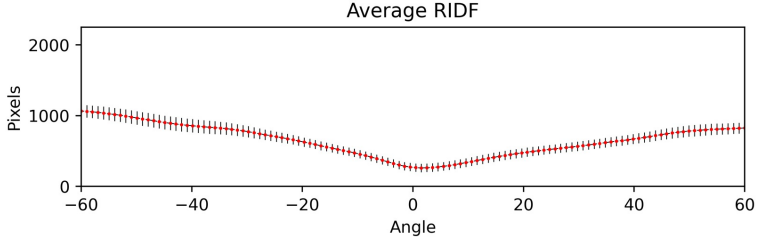
0%







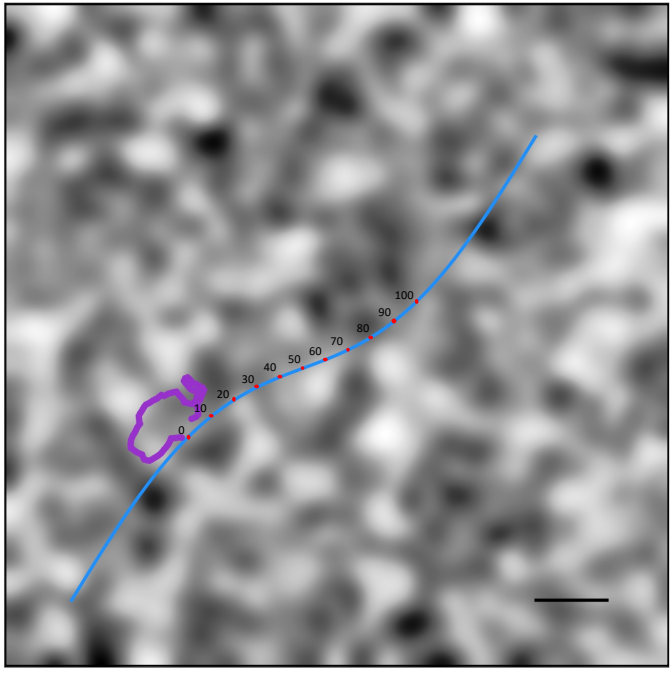


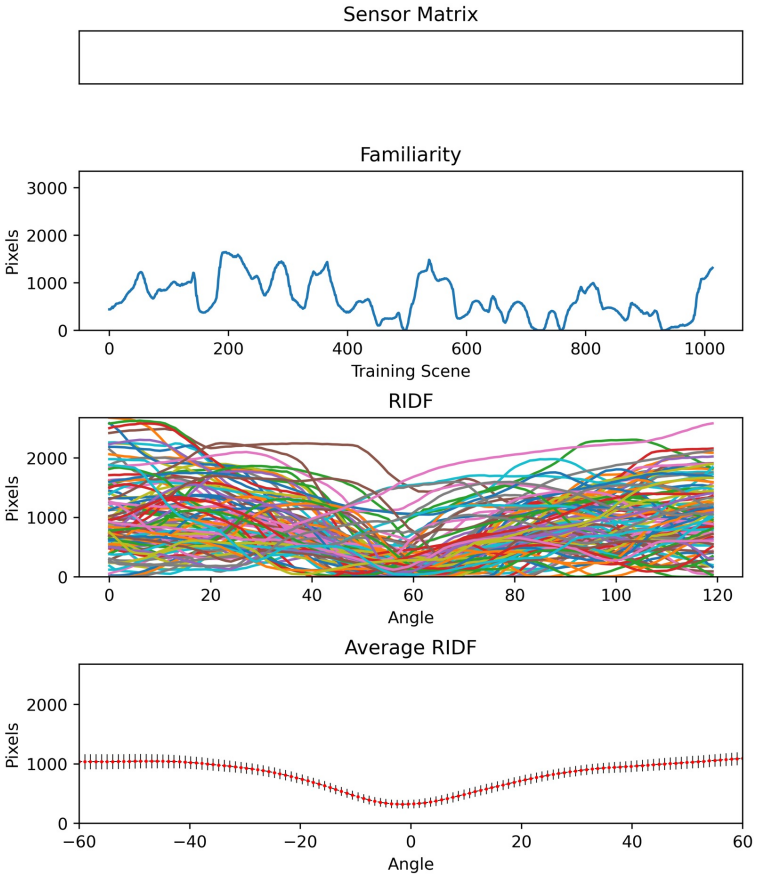


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4255.55; RMSD/dist: 10.639; TD: 772; p90: 98; p50: 42; complete: 0

0%

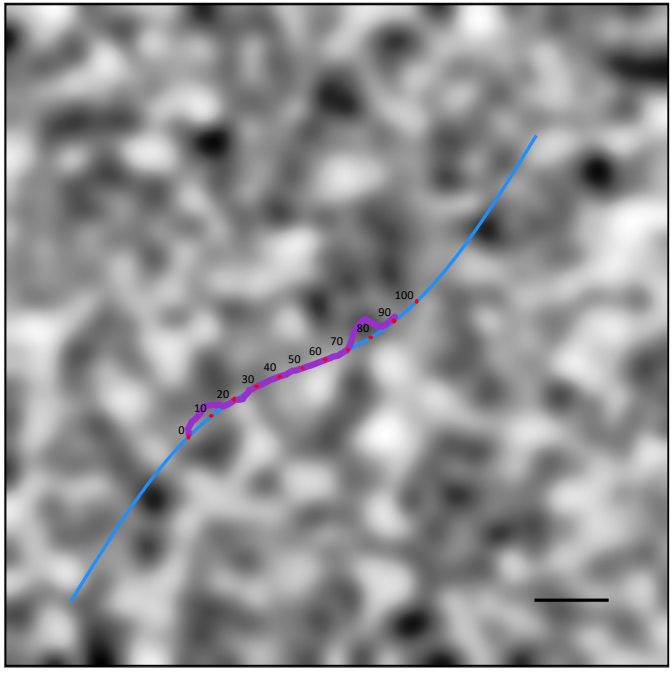


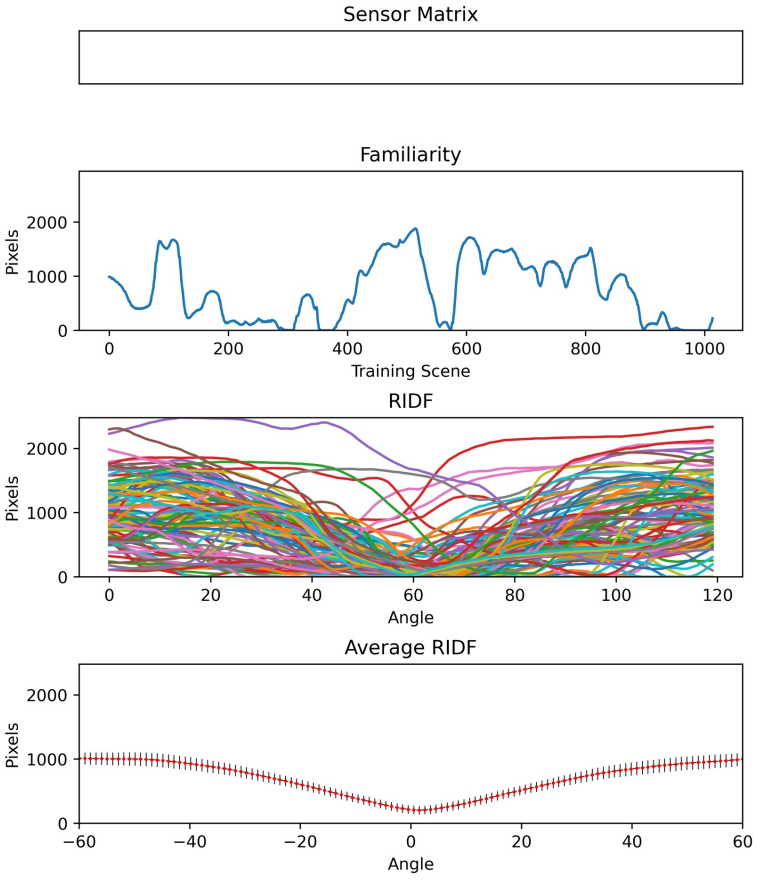


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4571.31; RMSD/dist: 11.428; TD: 632; p90: 54; p50: 32; complete: 0

30%

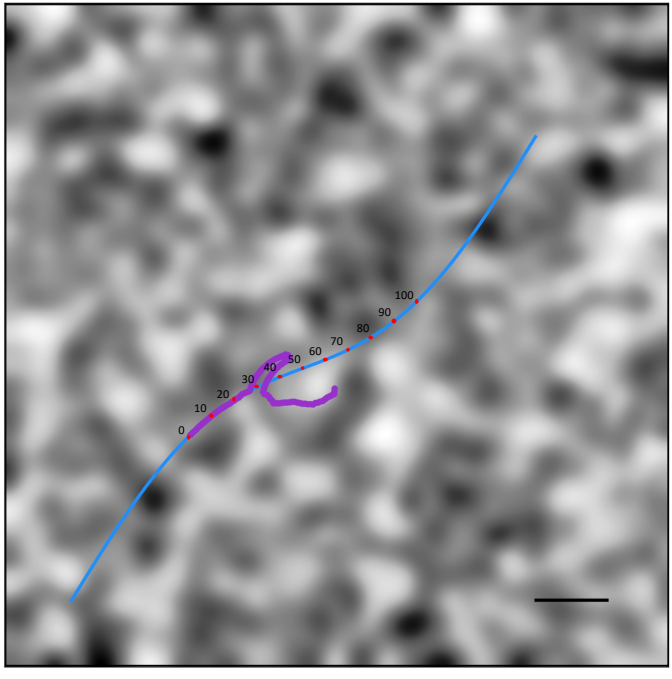


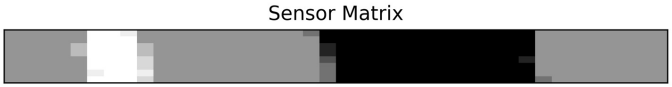


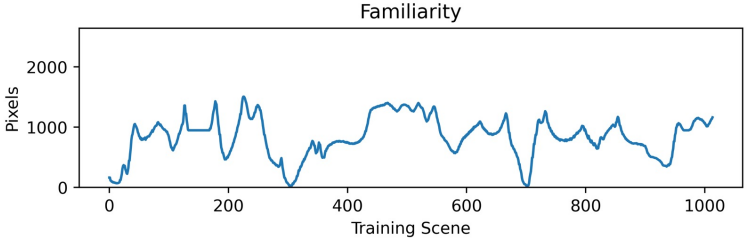
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

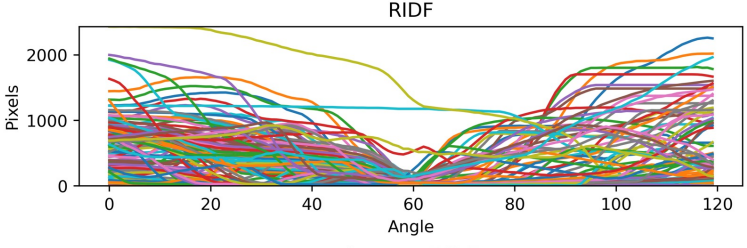
Navigation stats: RMSD error: 668.33; RMSD/dist: 1.671; TD: 778; p90: 76; p50: 40; complete: 0

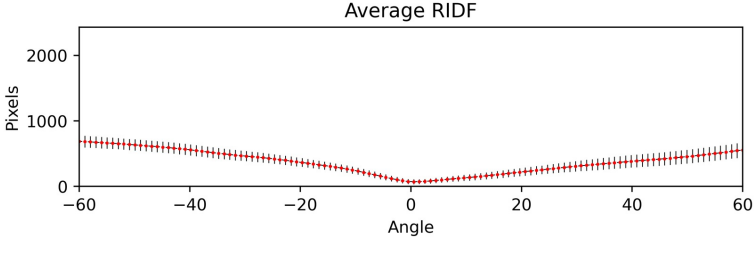
20%







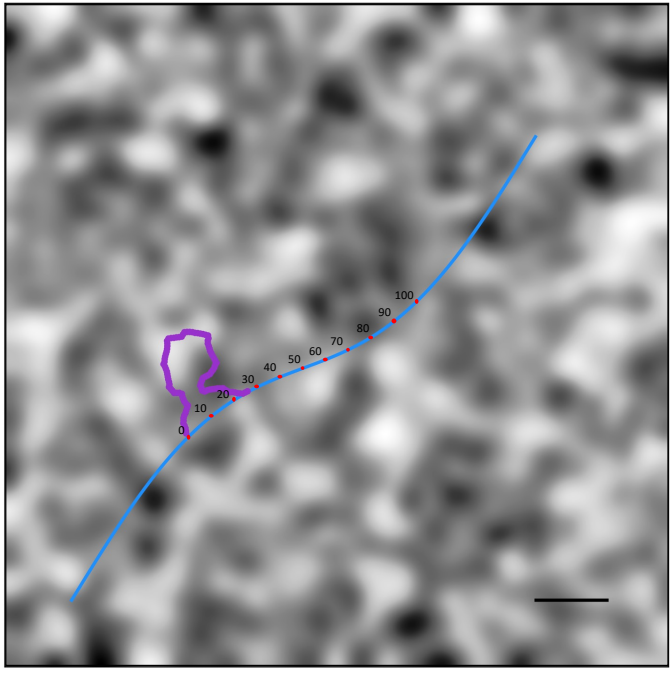


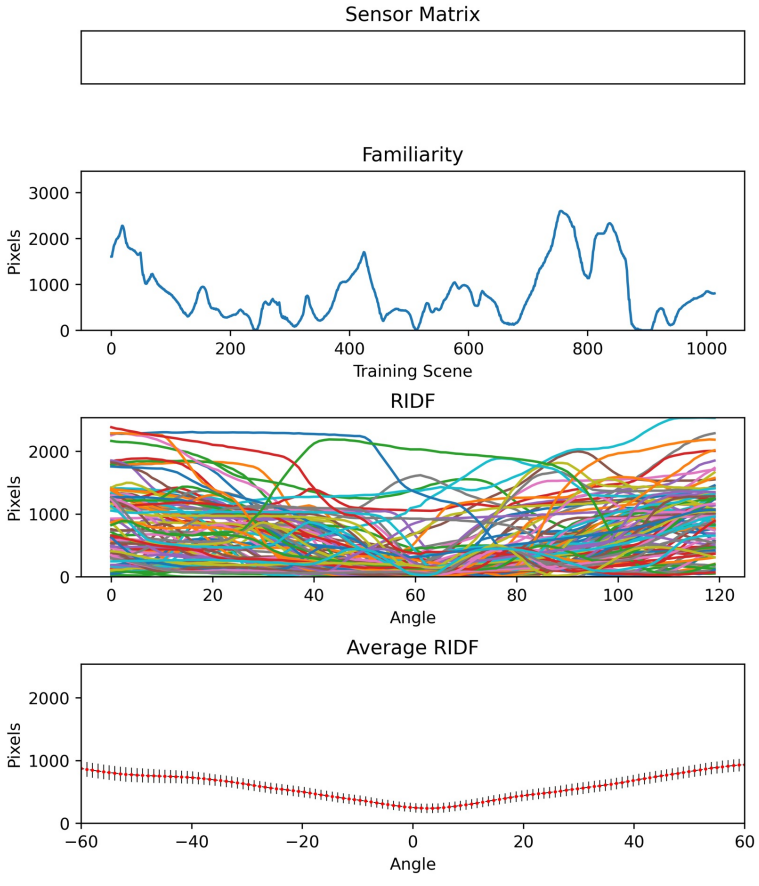


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2043.30; RMSD/dist: 5.108; TD: 783; p90: 120; p50: 60; complete: 0

0%

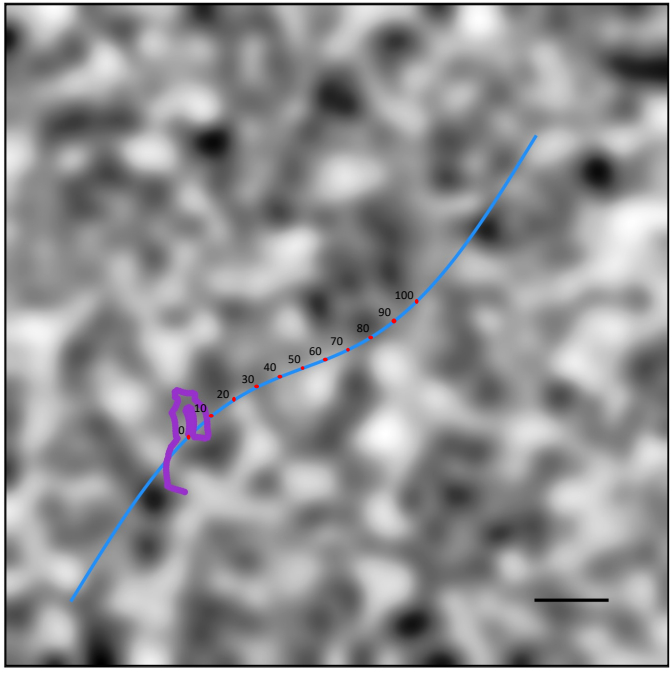


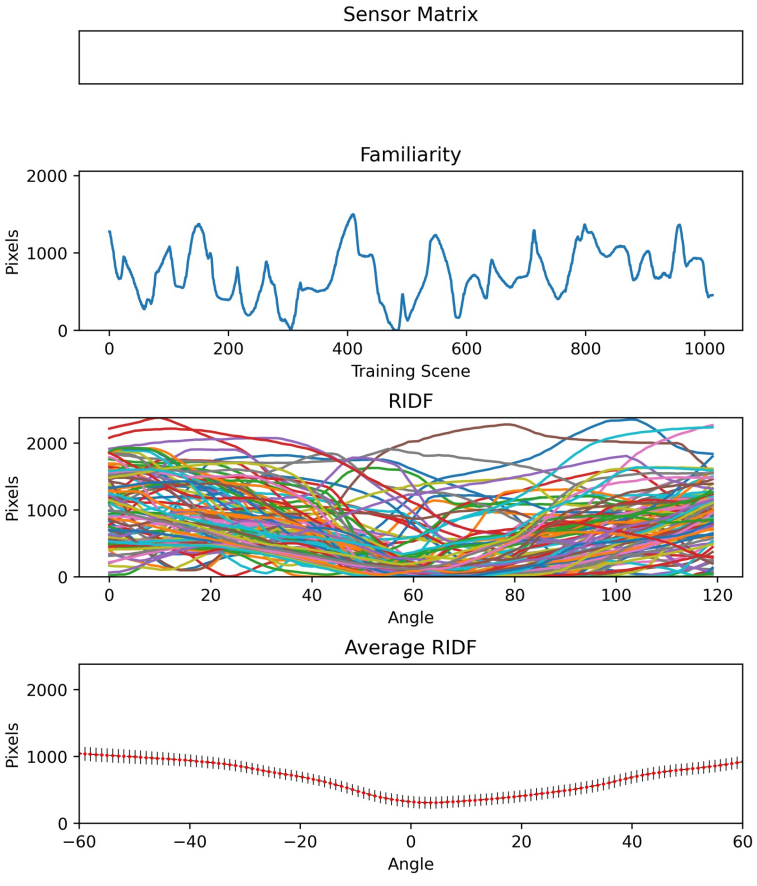


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 6768.09; RMSD/dist: 16.920; TD: 683; p90: 118; p50: 54; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2375.57; RMSD/dist: 5.939; TD: 453; p90: 44; p50: 24; complete: 0