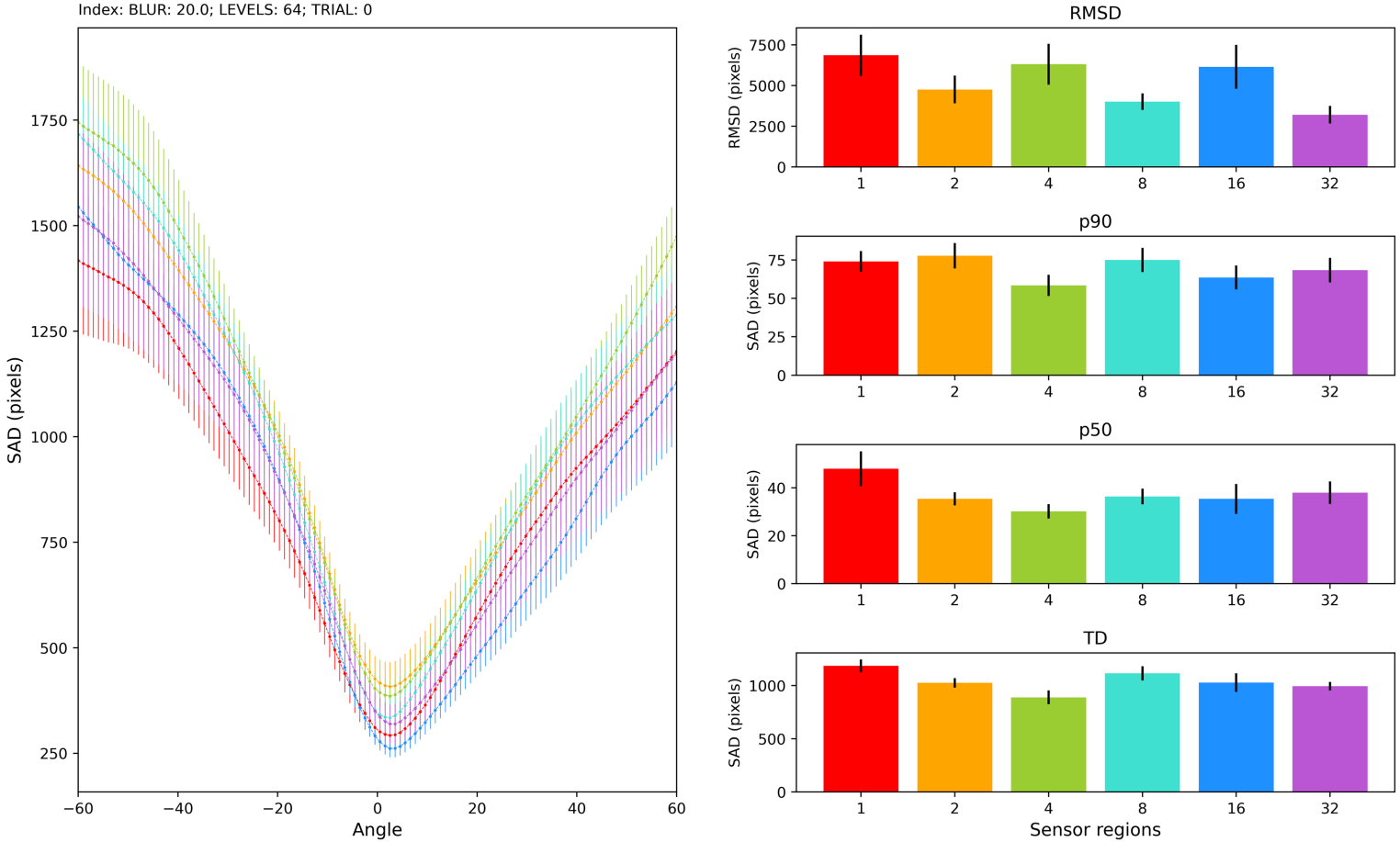
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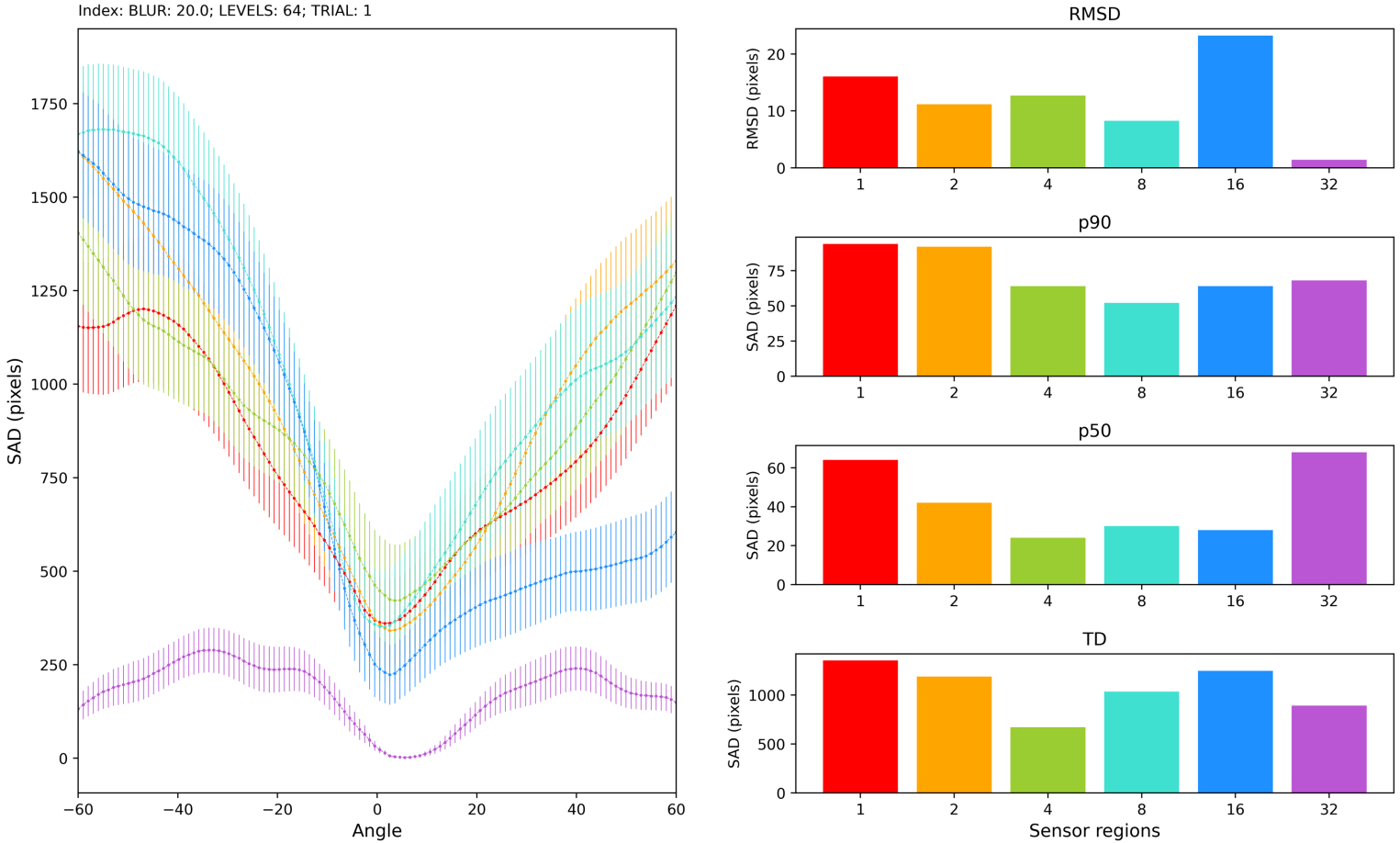
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

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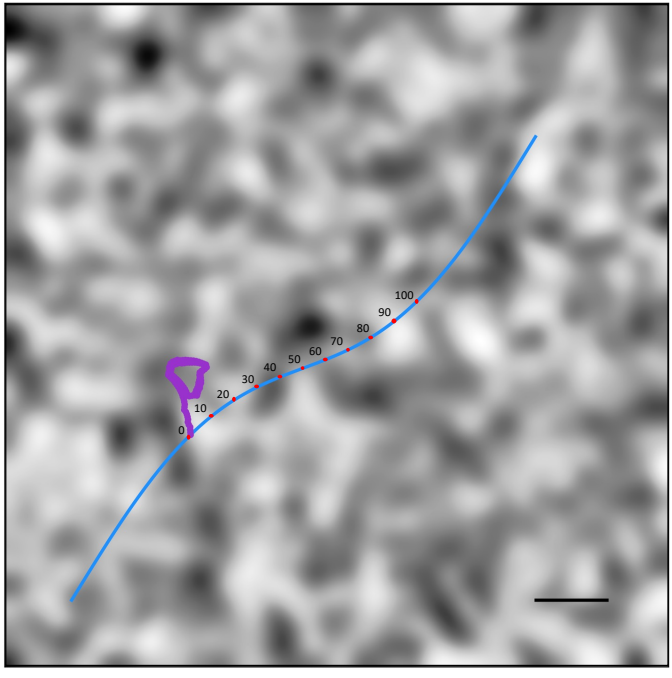
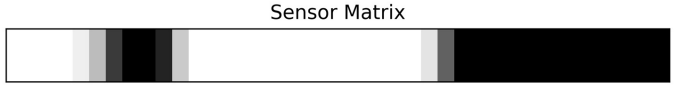
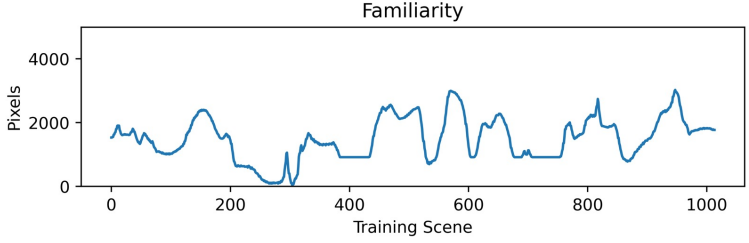
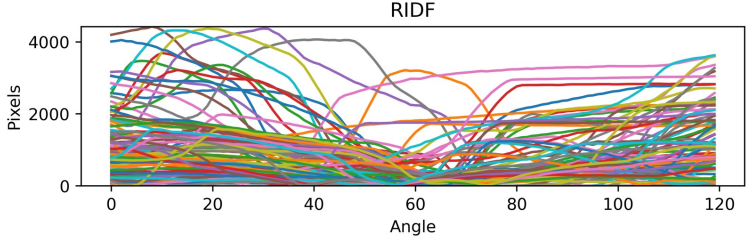
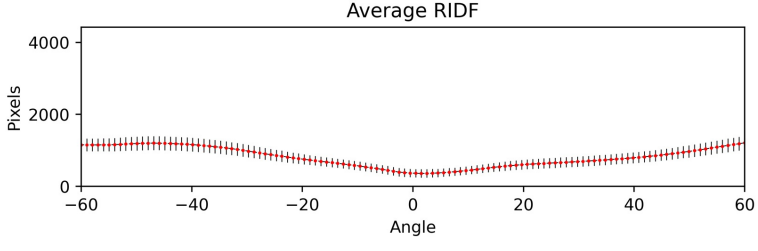






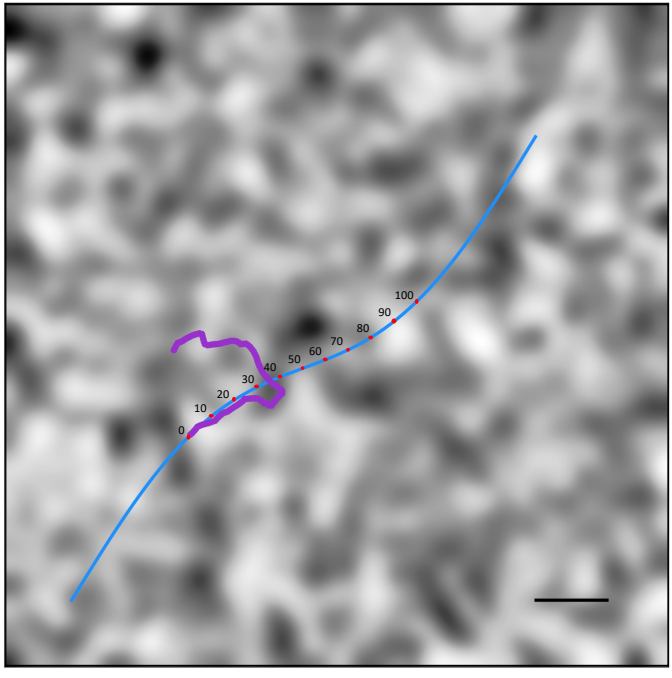


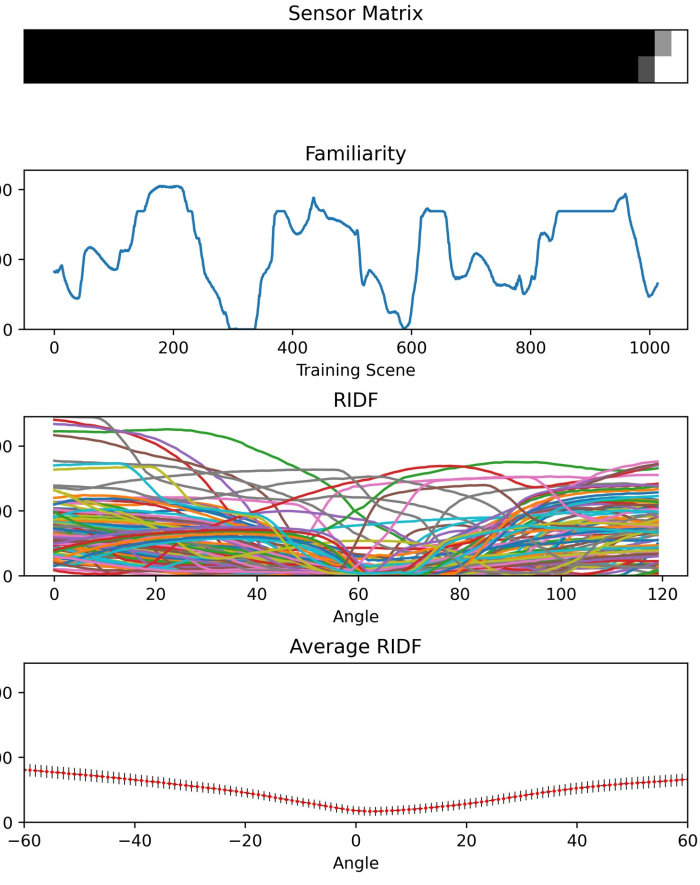


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 6420.52; RMSD/dist: 16.051; TD: 1351; p90: 94; p50: 64; complete: 0

0%

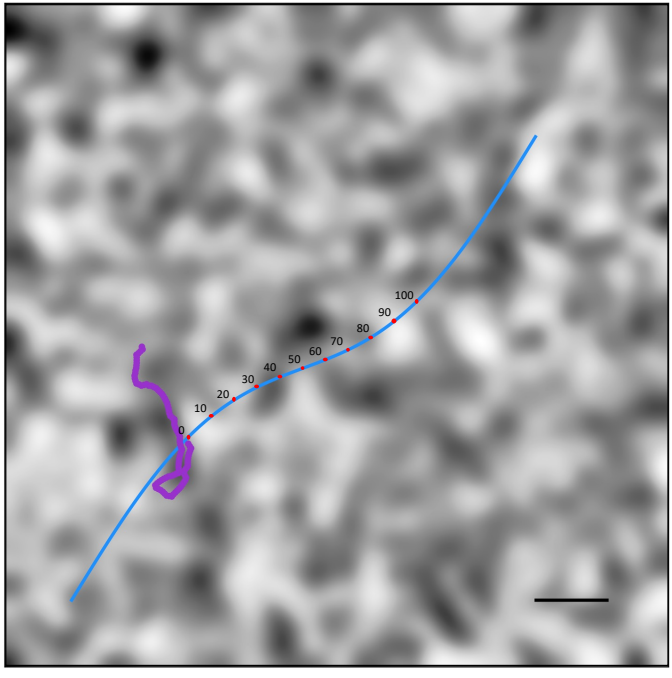


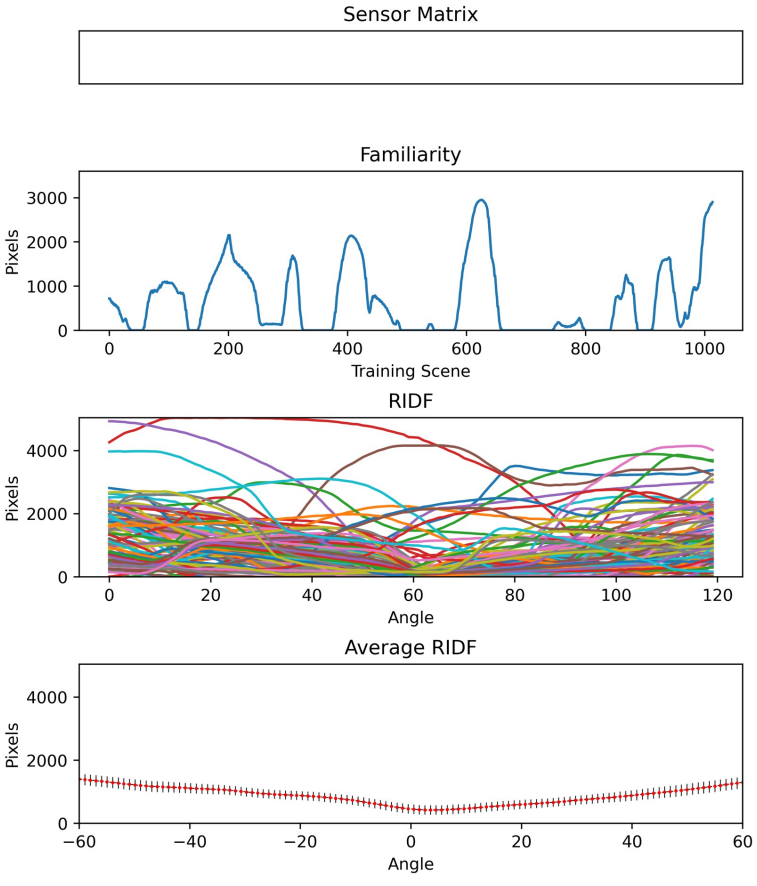


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4459.30; RMSD/dist: 11.148; TD: 1187; p90: 92; p50: 42; complete: 0

0%

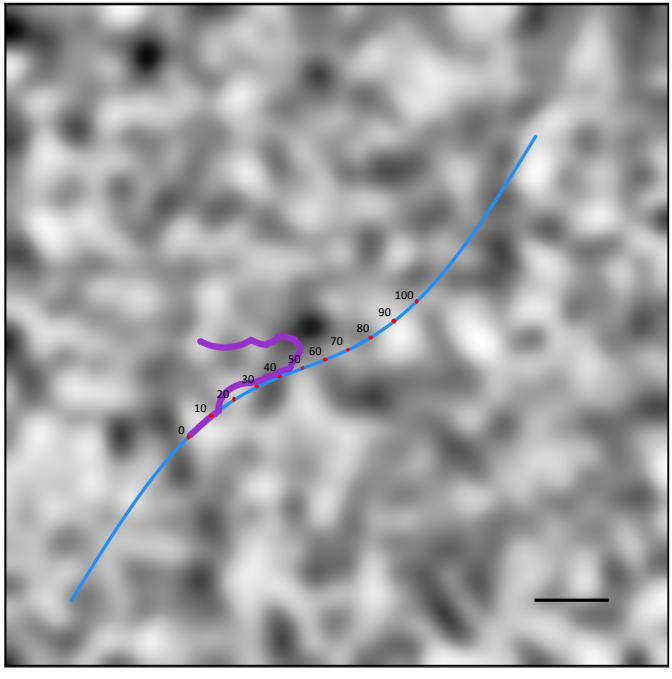


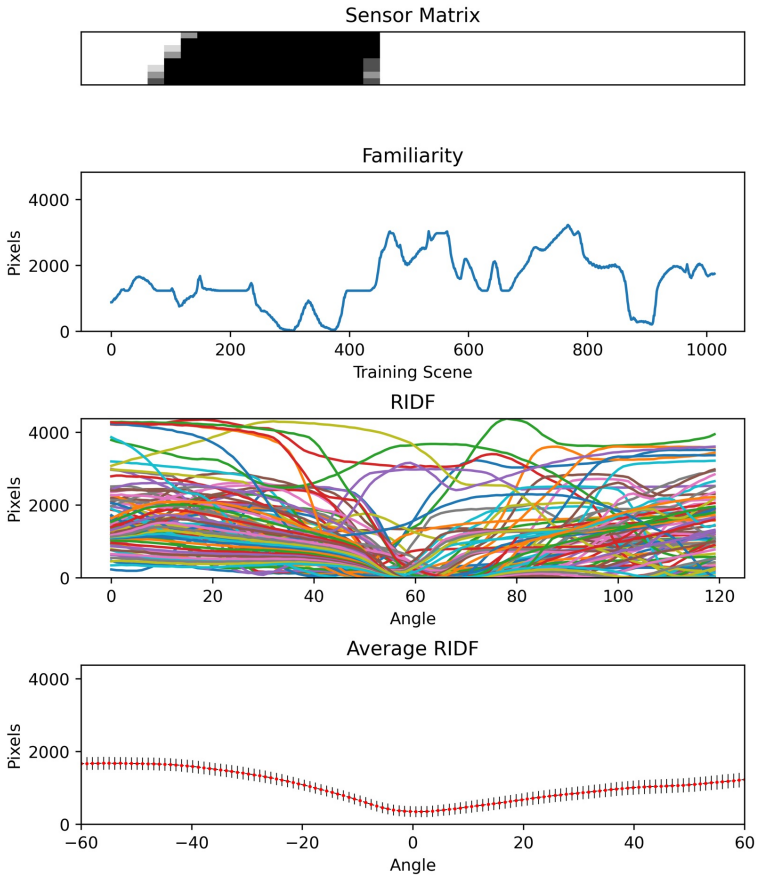


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 5079.68; RMSD/dist: 12.699; TD: 670; p90: 64; p50: 24; complete: 0

10%

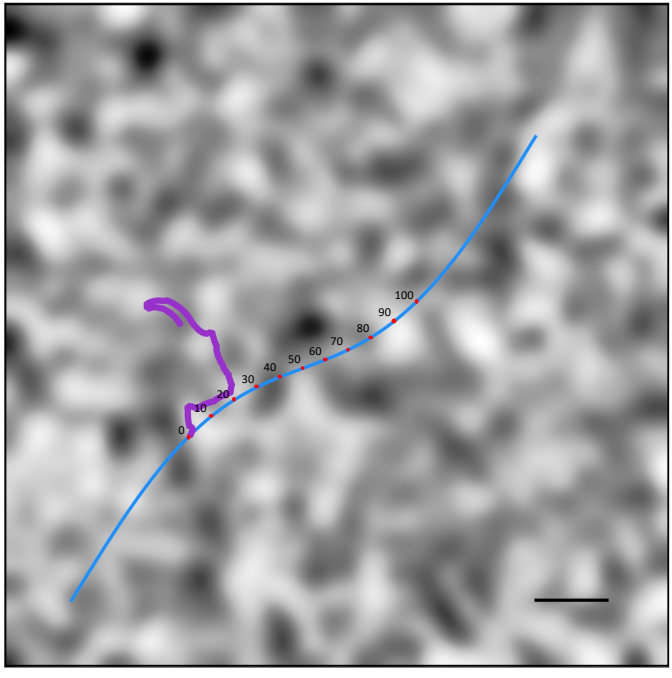


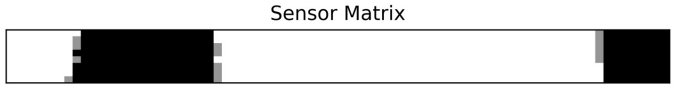


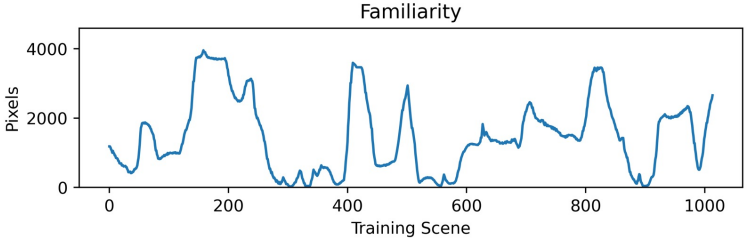
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

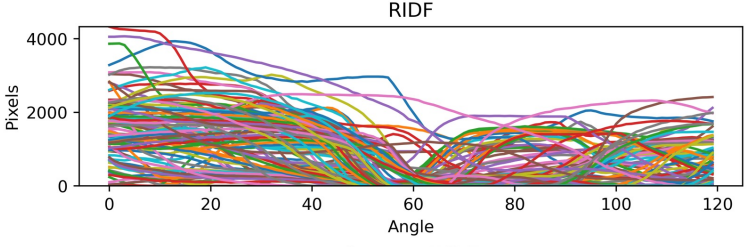
Navigation stats: RMSD error: 3304.53; RMSD/dist: 8.261; TD: 1034; p90: 52; p50: 30; complete: 0

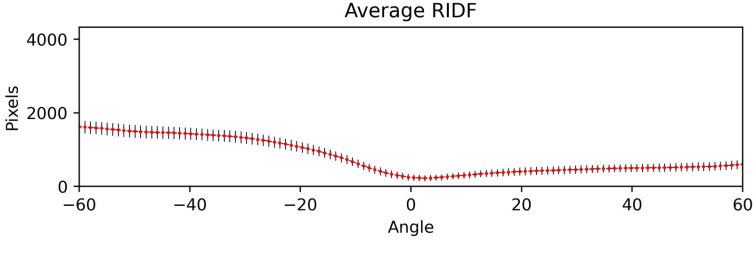
0%







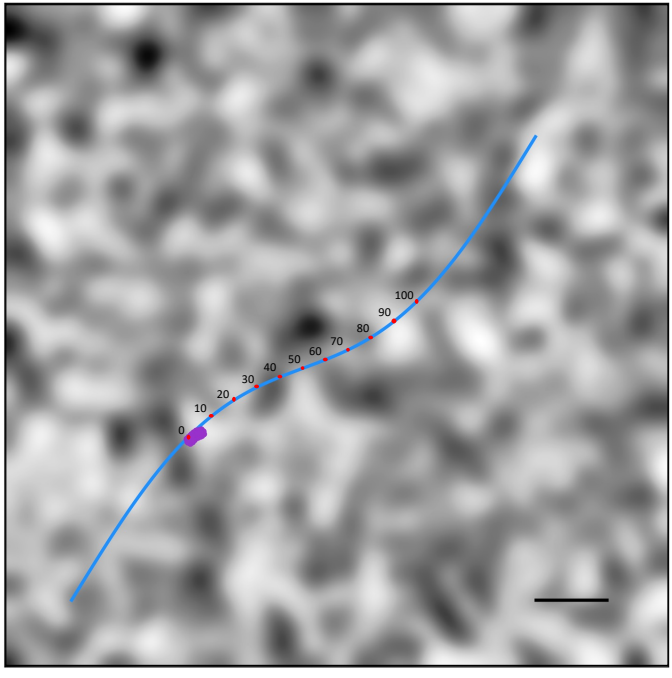


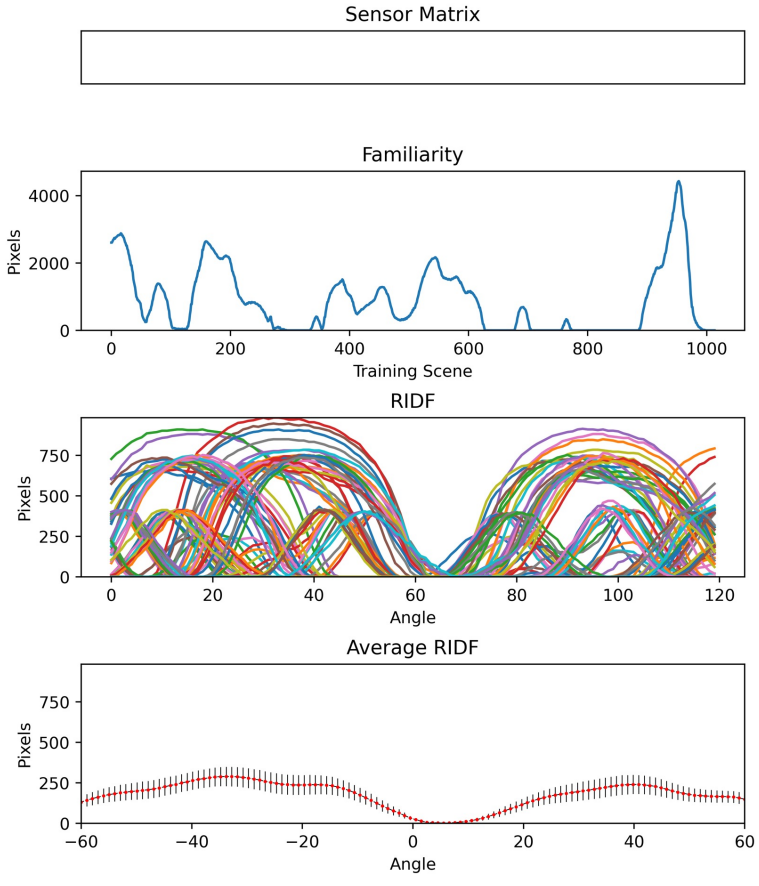


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 9296.98; RMSD/dist: 23.242; TD: 1247; p90: 64; p50: 28; complete: 0

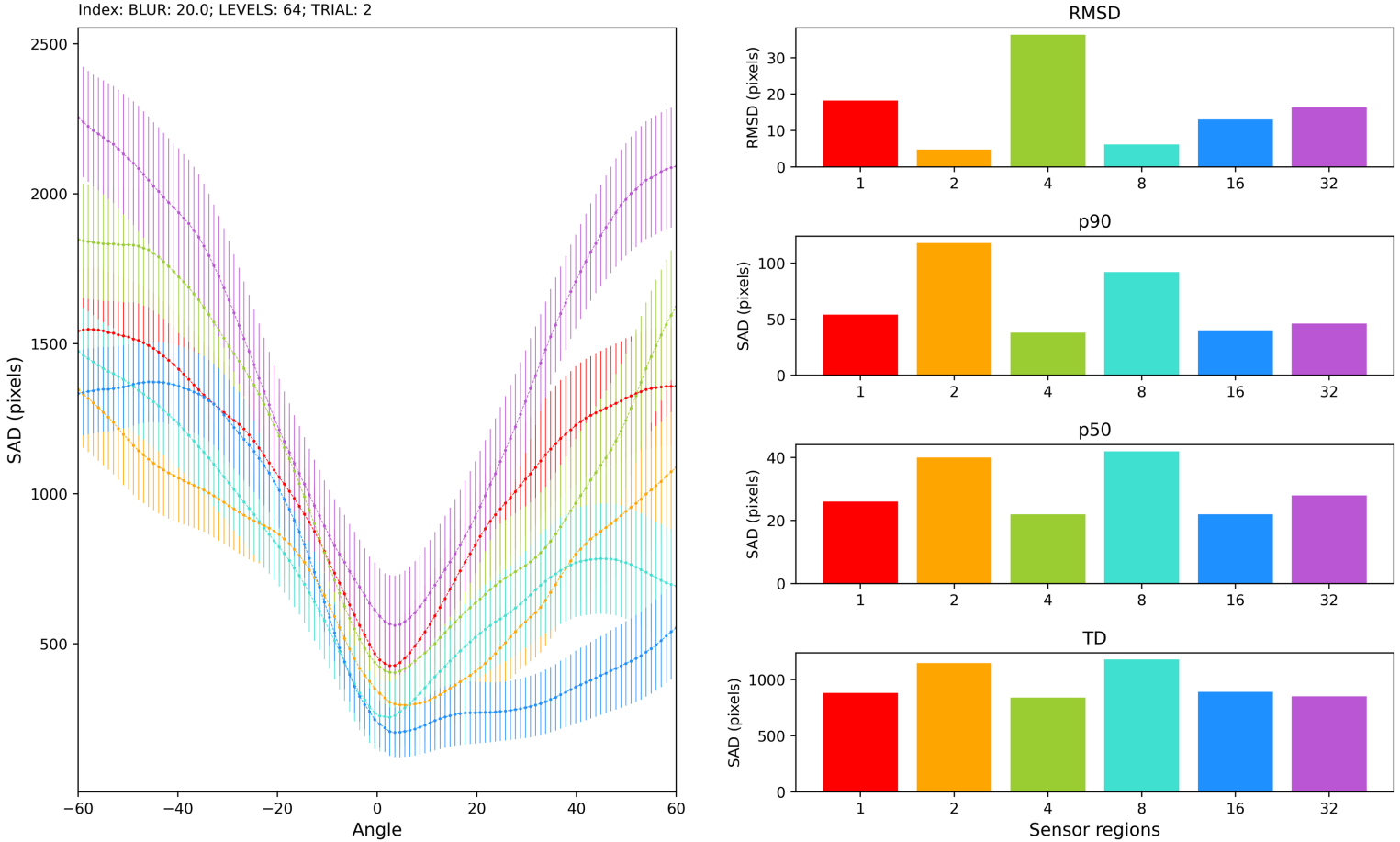
0%



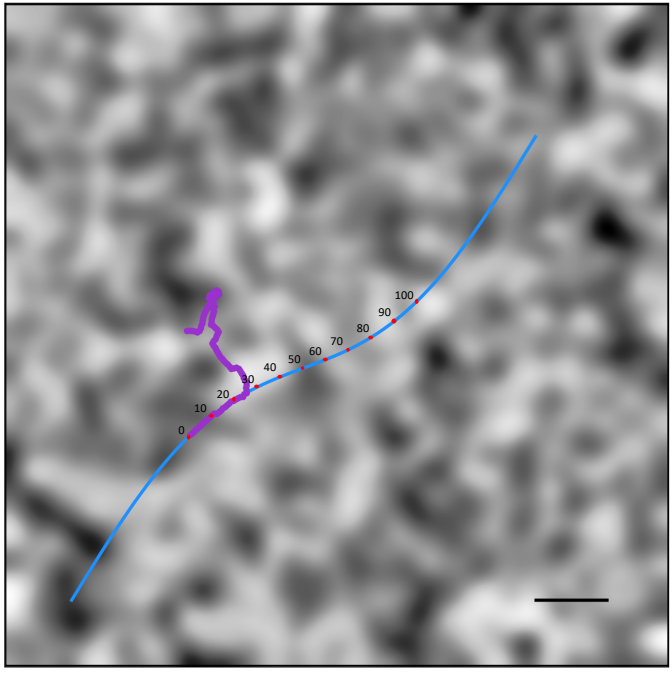


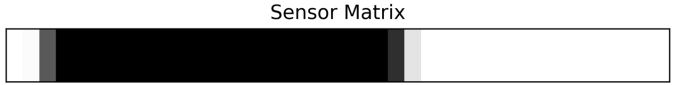
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

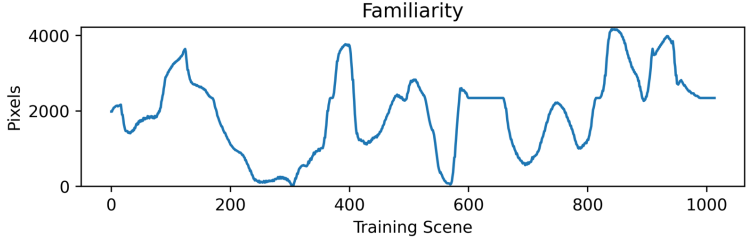
Navigation stats: RMSD error: 563.85; RMSD/dist: 1.410; TD: 892; p90: 68; p50: 68; complete: 0

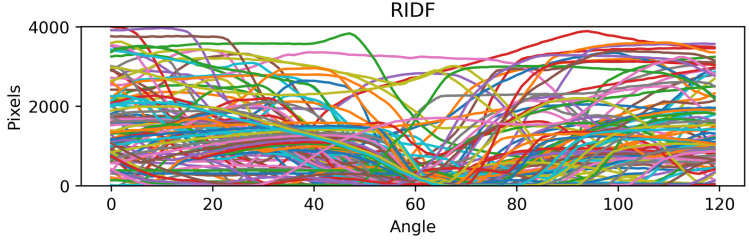

Index: BLUR: 20.0; LEVELS: 64; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

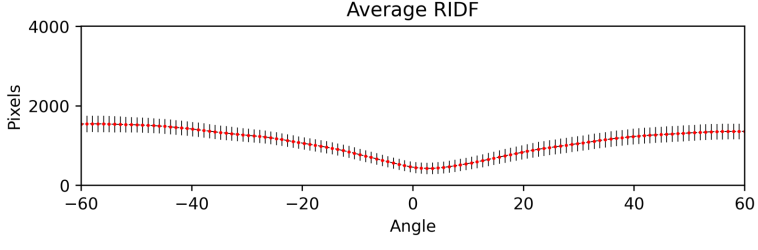
20%







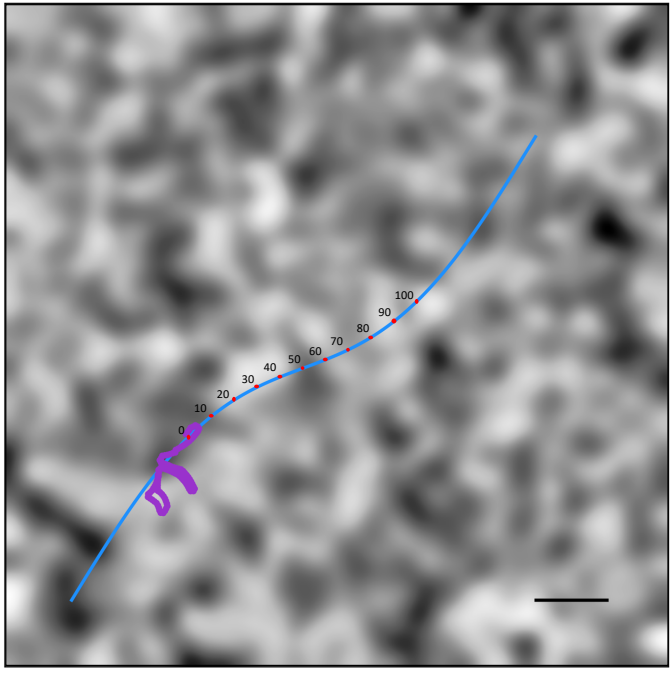


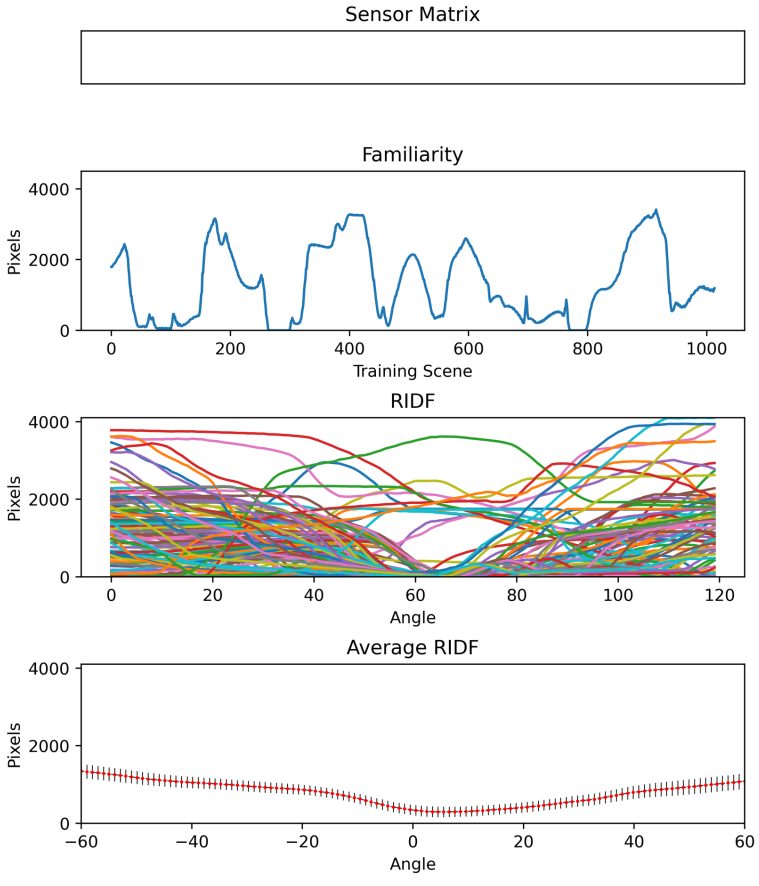


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 7280.33; RMSD/dist: 18.201; TD: 881; p90: 54; p50: 26; complete: 0

0%

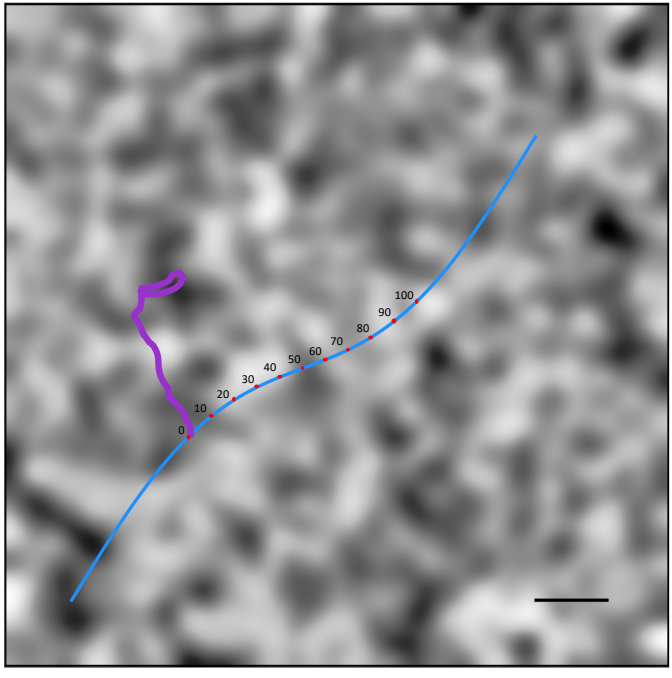


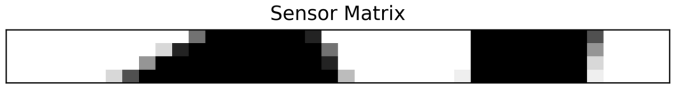


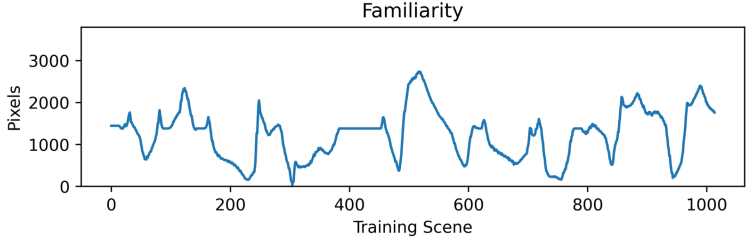
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

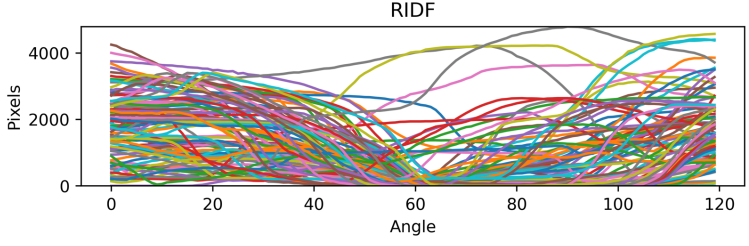
Navigation stats: RMSD error: 1907.27; RMSD/dist: 4.768; TD: 1147; p90: 118; p50: 40; complete: 0

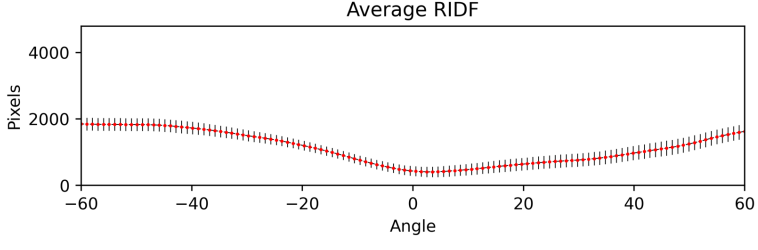
0%







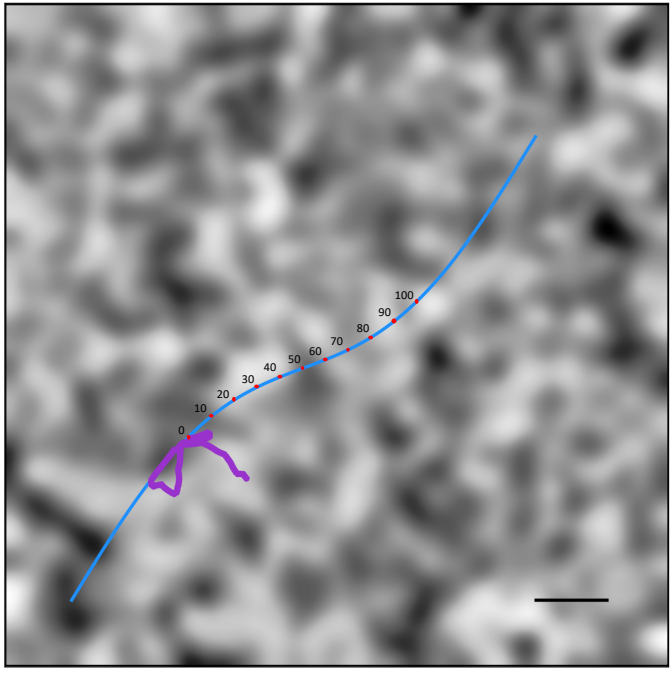


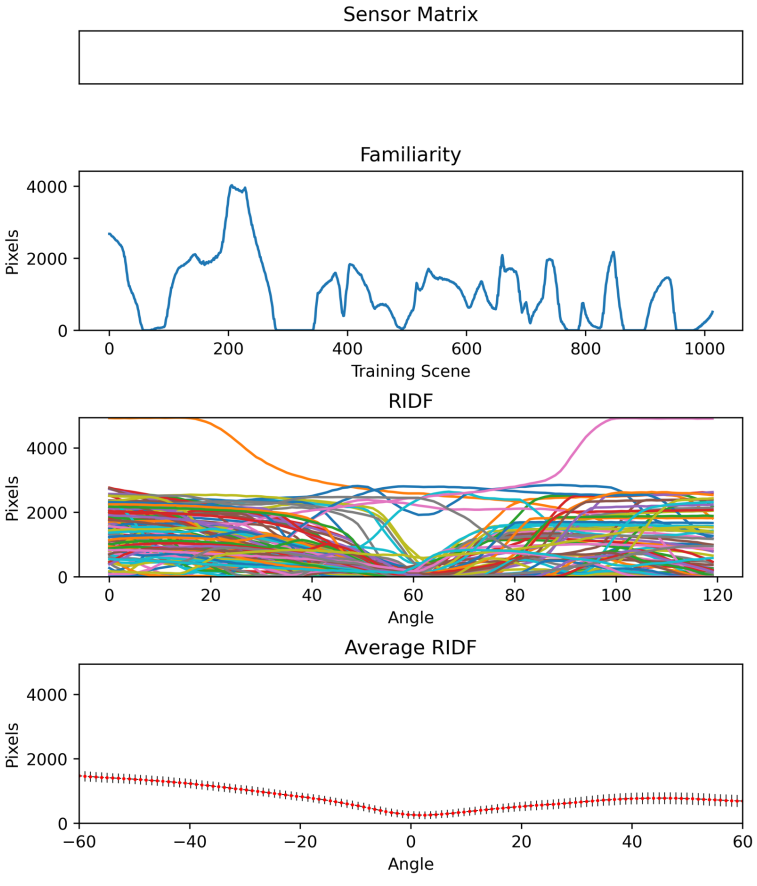


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 14543.61; RMSD/dist: 36.359; TD: 840; p90: 38; p50: 22; complete: 0

0%

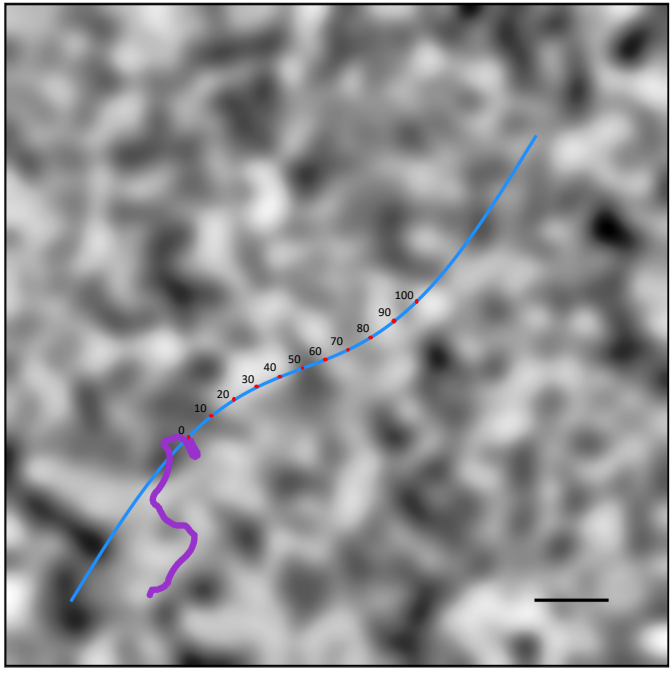


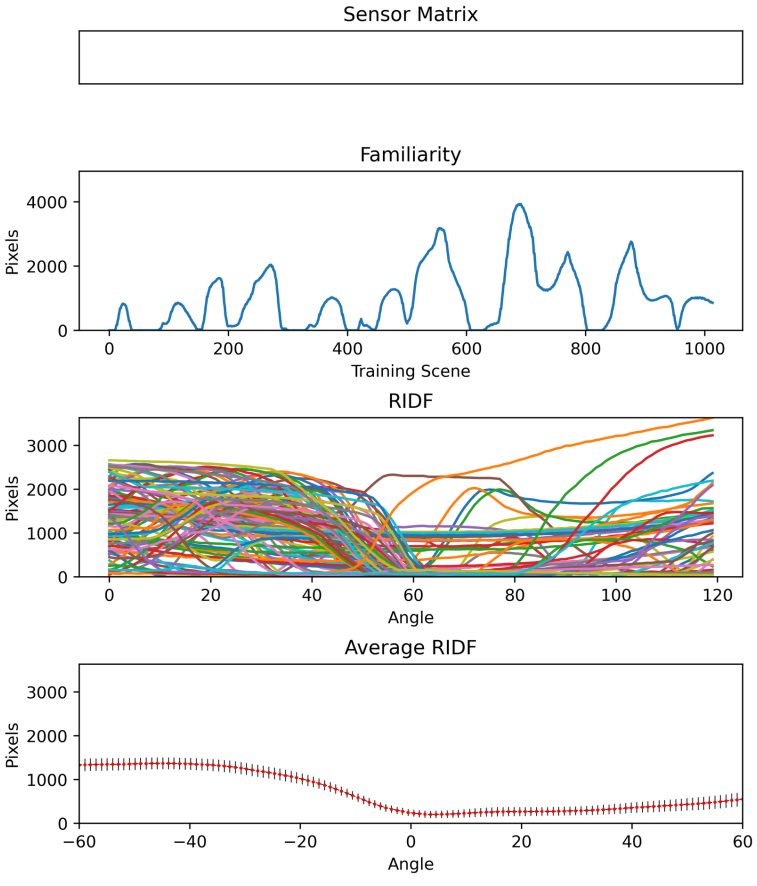


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2462.31; RMSD/dist: 6.156; TD: 1178; p90: 92; p50: 42; complete: 0

0%

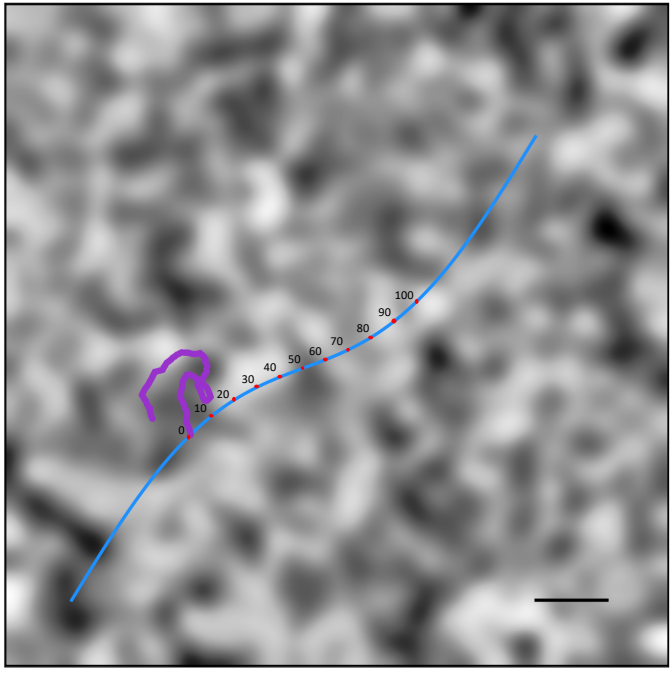


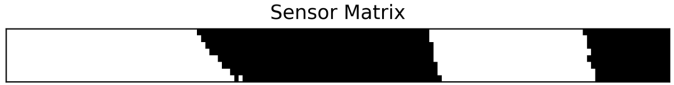


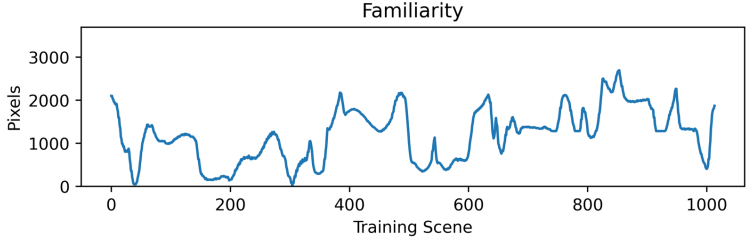
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

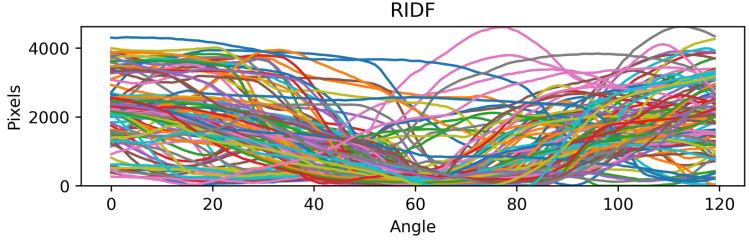
Navigation stats: RMSD error: 5207.43; RMSD/dist: 13.019; TD: 890; p90: 40; p50: 22; complete: 0

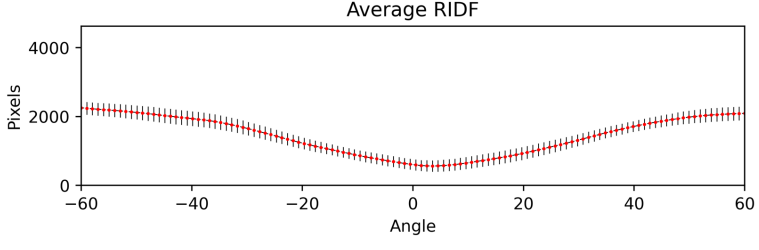
0%





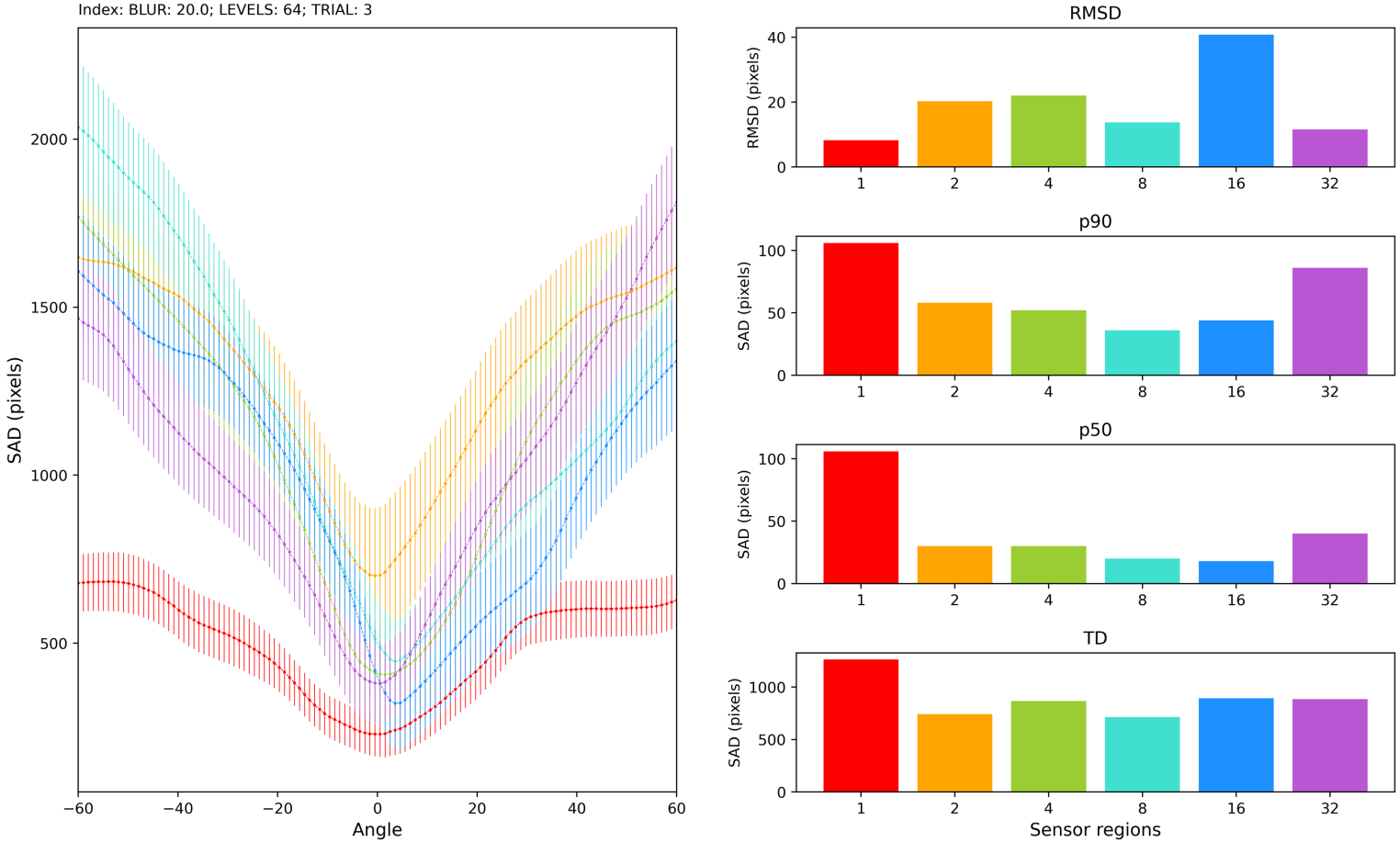




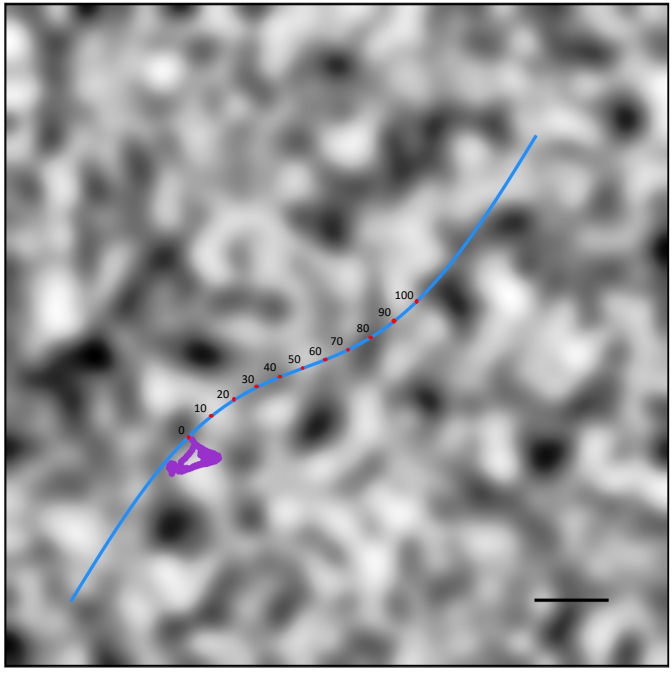


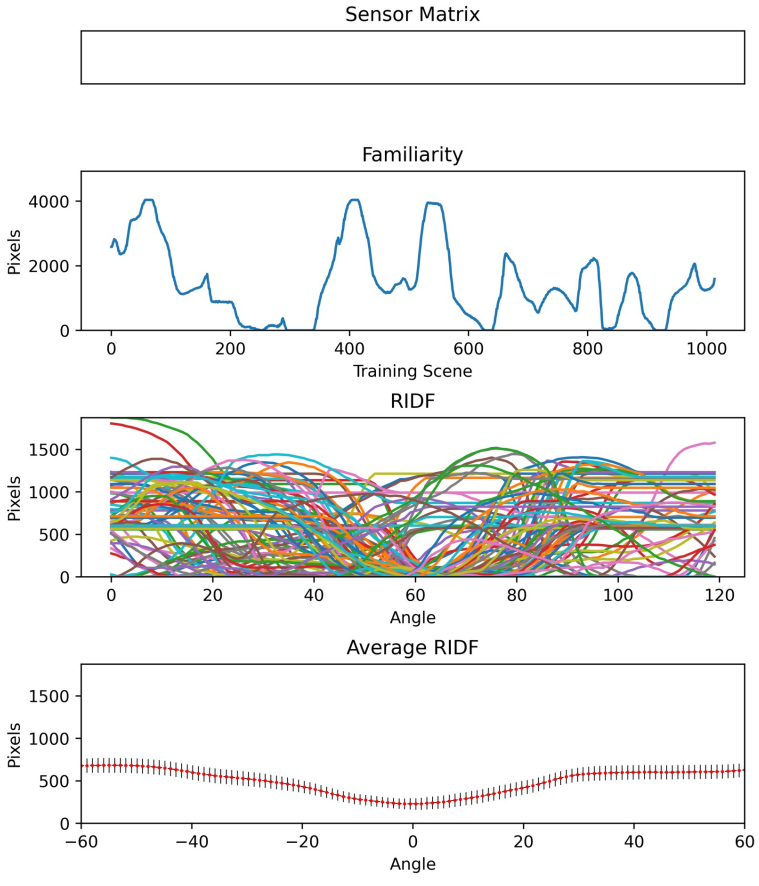
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 6550.93; RMSD/dist: 16.377; TD: 851; p90: 46; p50: 28; complete: 0


Index: BLUR: 20.0; LEVELS: 64; TRIAL: 3
SAD (pixels)
2000
1500
1000
500
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
40
20
0
p90
SAD (pixels)
100
50
0
p50
SAD (pixels)
100
50
0
TD
SAD (pixels)
1000
500
0
1
2
4
8
16
32
Sensor regions

0%

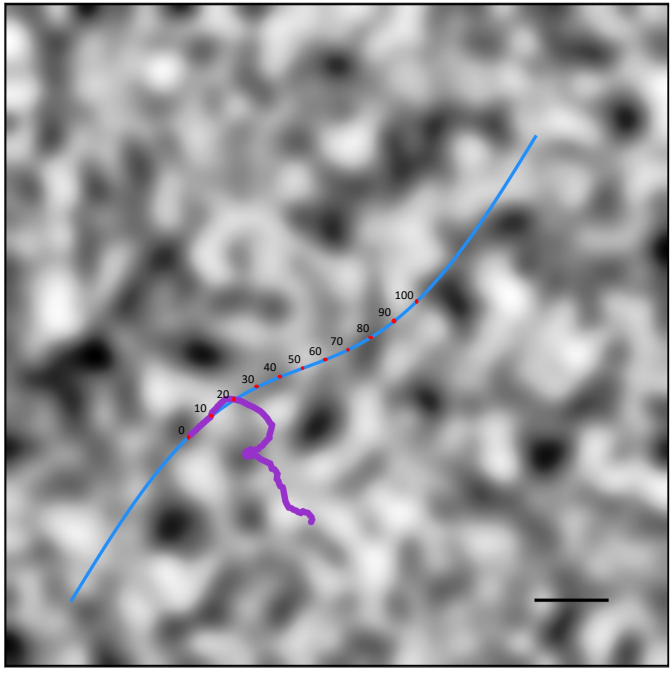


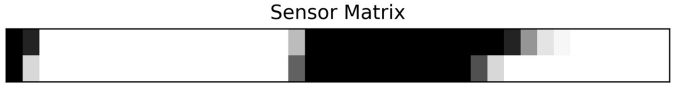


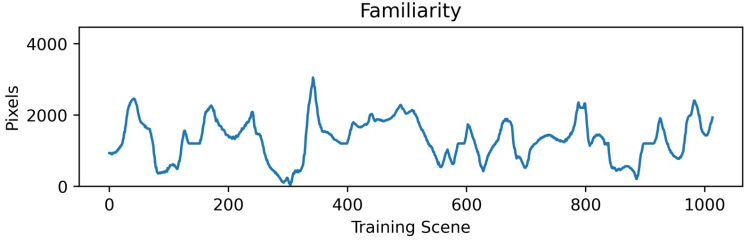
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

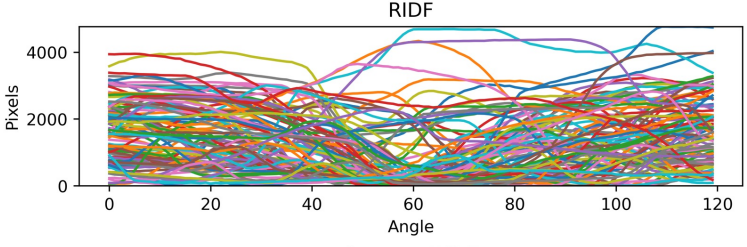
Navigation stats: RMSD error: 3297.47; RMSD/dist: 8.244; TD: 1263; p90: 106; p50: 106; complete: 0

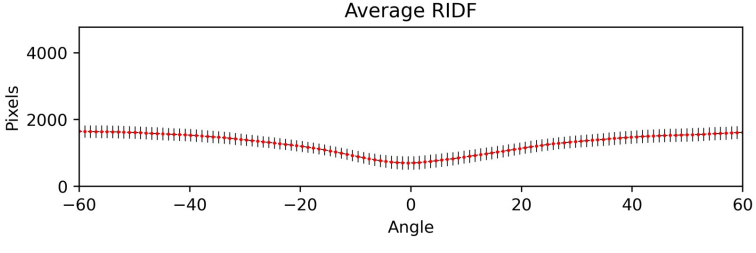
10%







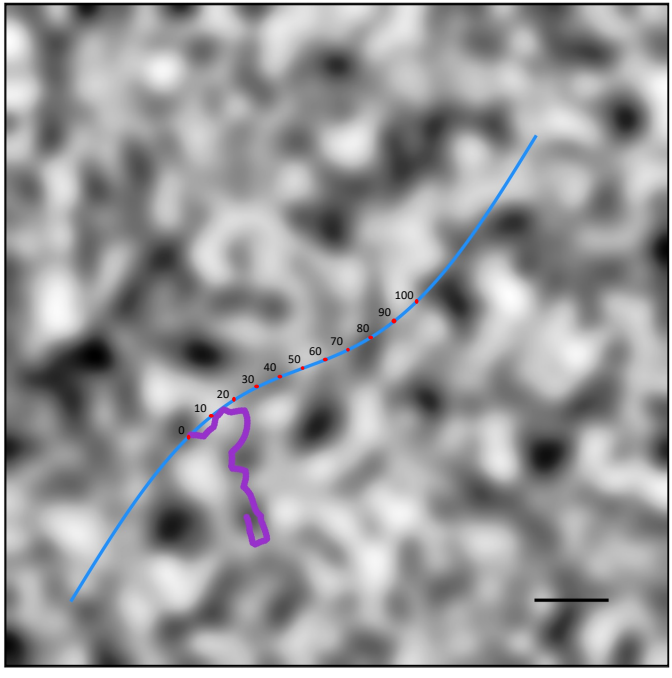


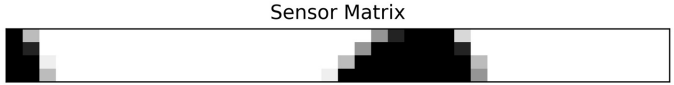


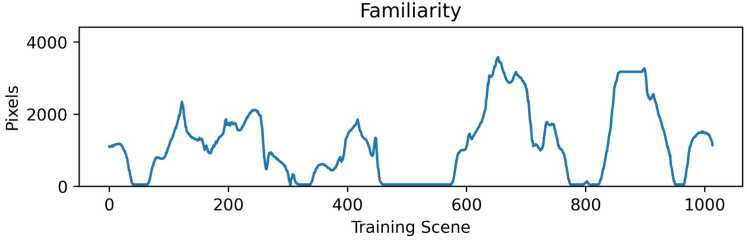
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

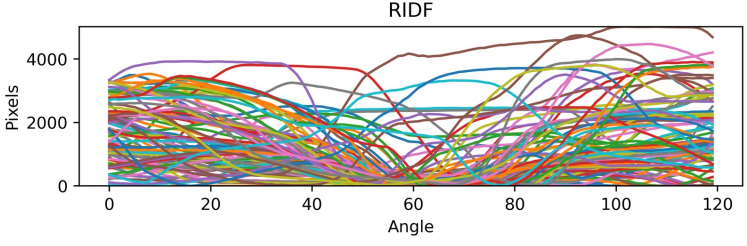
Navigation stats: RMSD error: 8088.83; RMSD/dist: 20.222; TD: 741; p90: 58; p50: 30; complete: 0

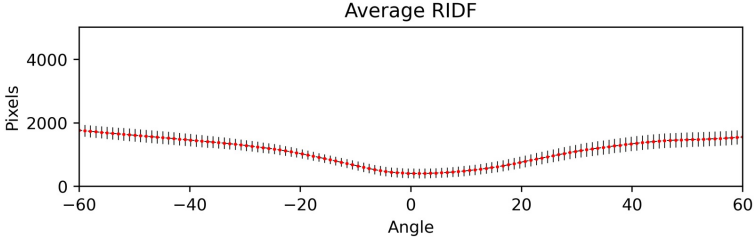
0%







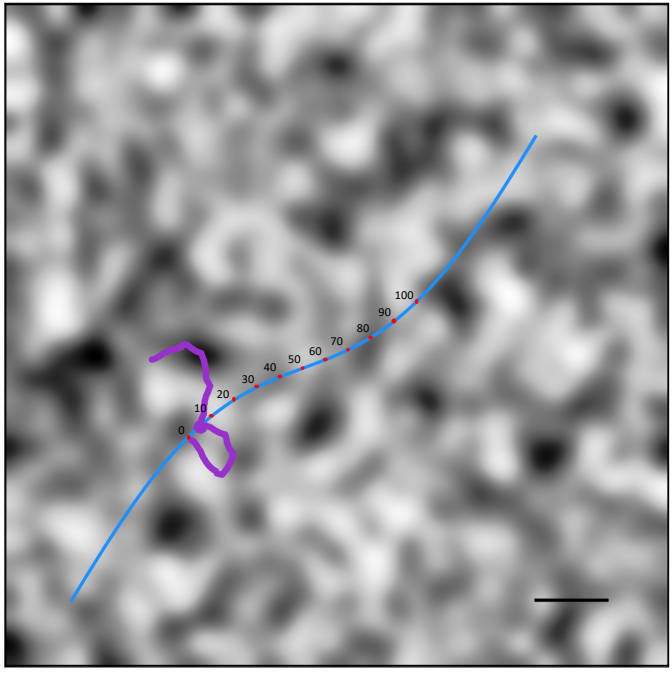


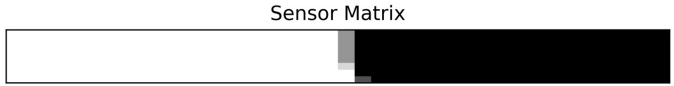


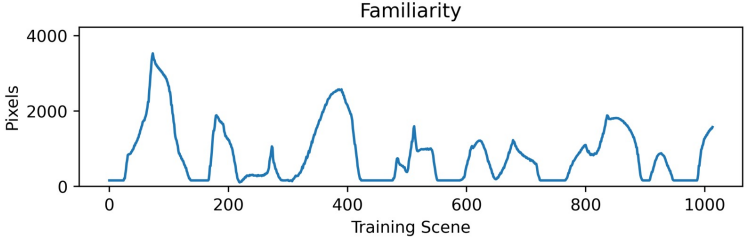
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

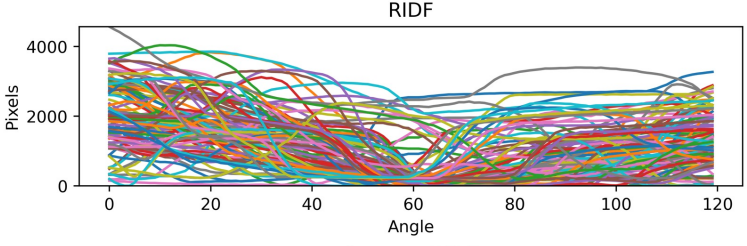
Navigation stats: RMSD error: 8806.78; RMSD/dist: 22.017; TD: 868; p90: 52; p50: 30; complete: 0

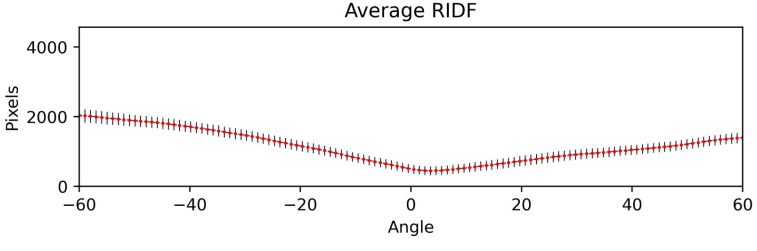
0%







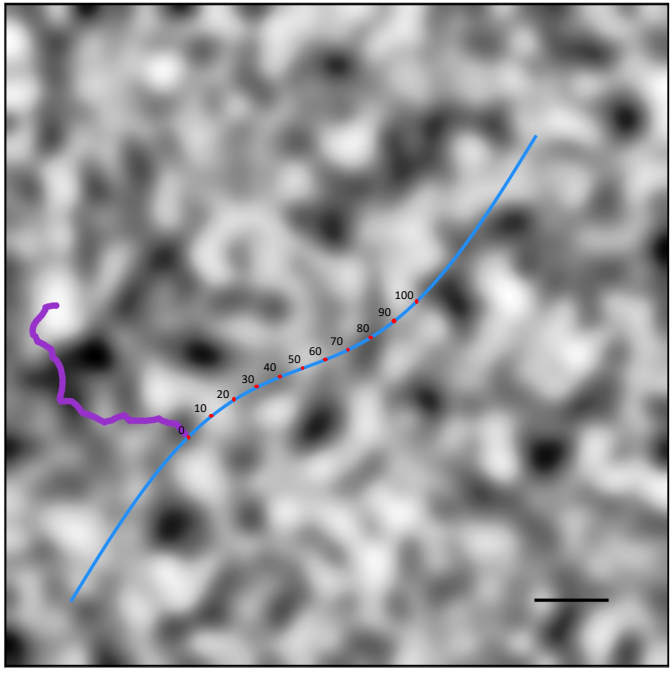


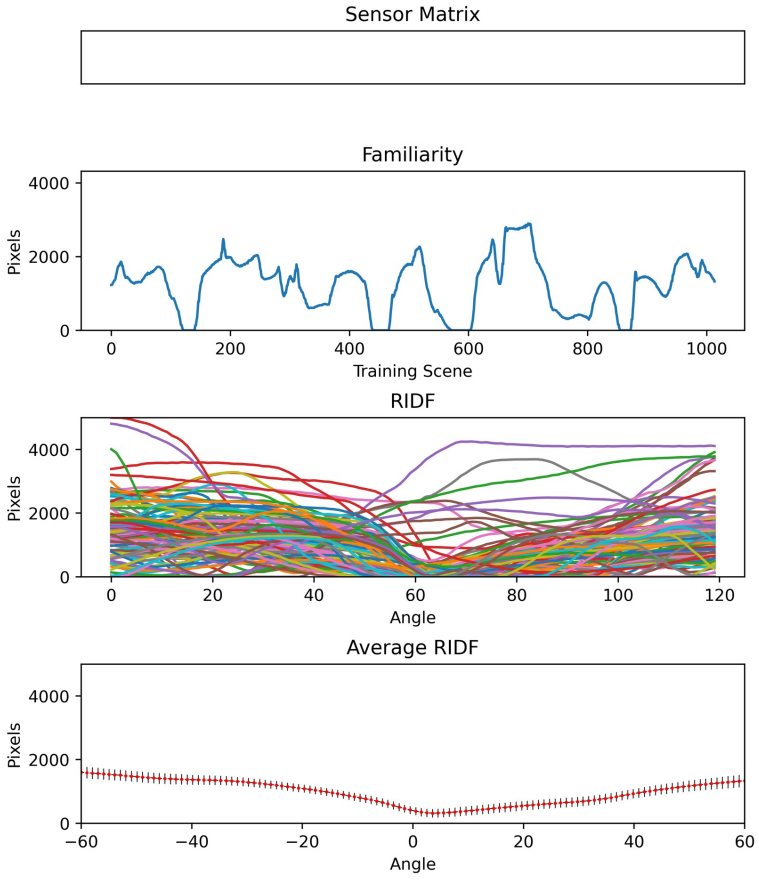


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 5476.25; RMSD/dist: 13.691; TD: 713; p90: 36; p50: 20; complete: 0

0%

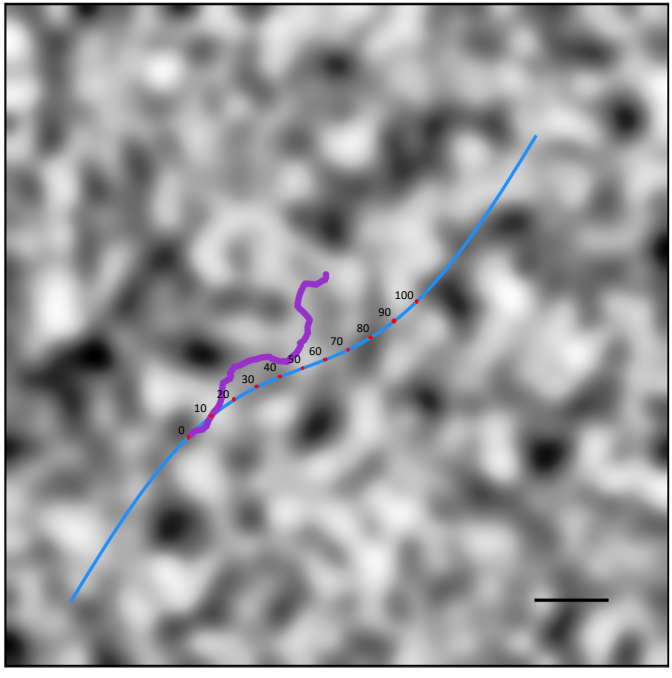


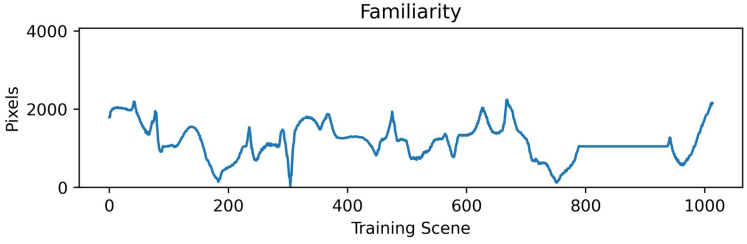


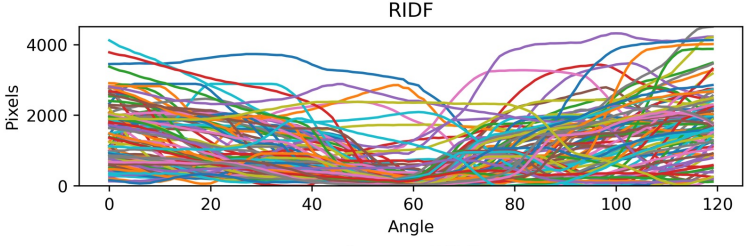
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

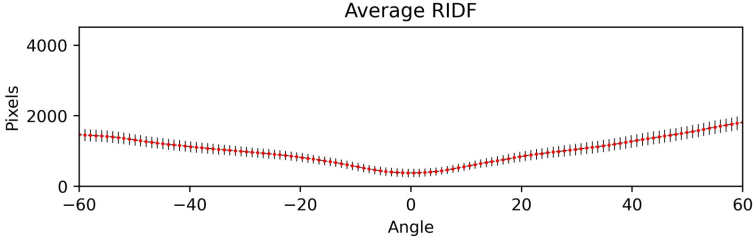
Navigation stats: RMSD error: 16319.10; RMSD/dist: 40.798; TD: 894; p90: 44; p50: 18; complete: 0

0%



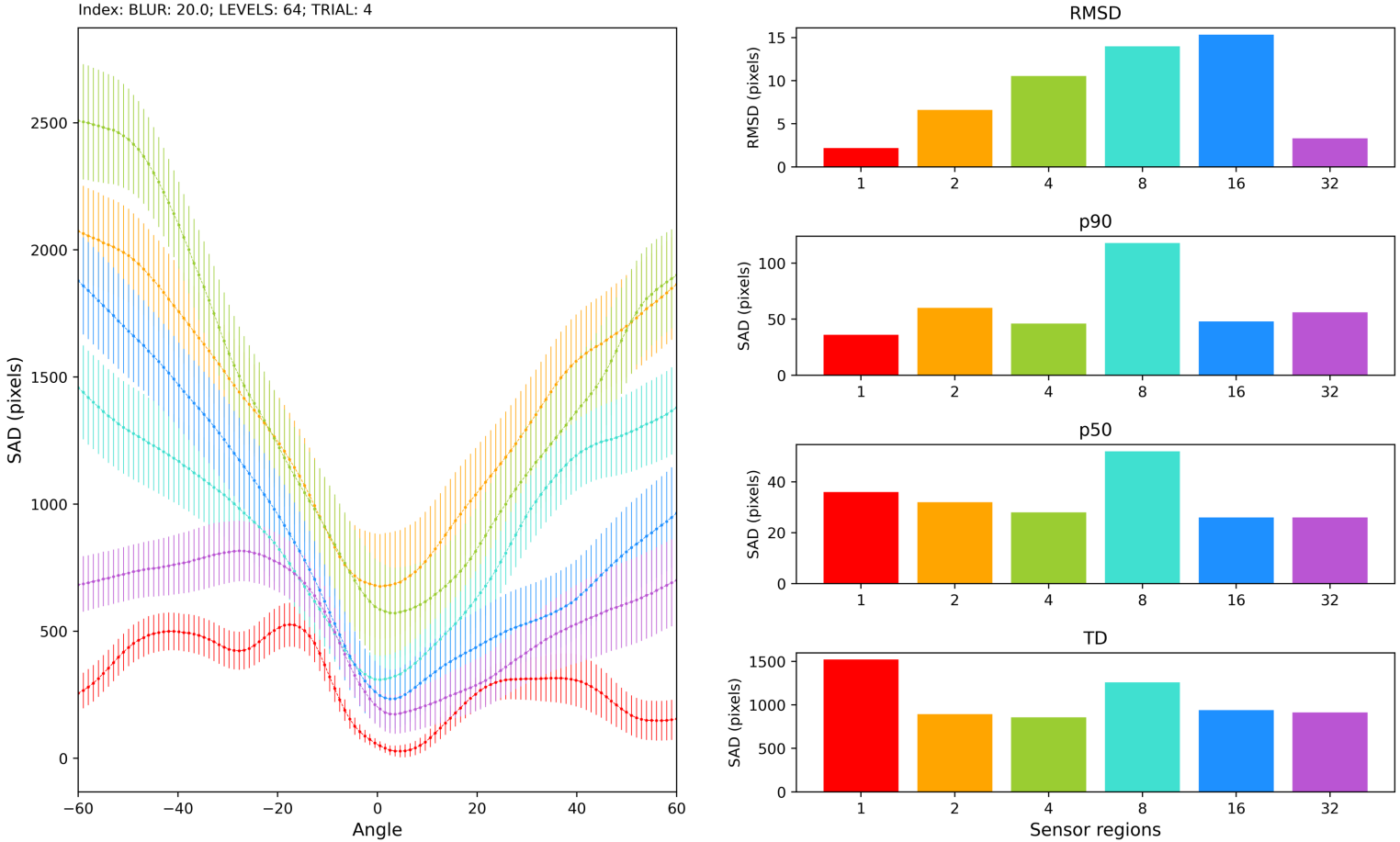




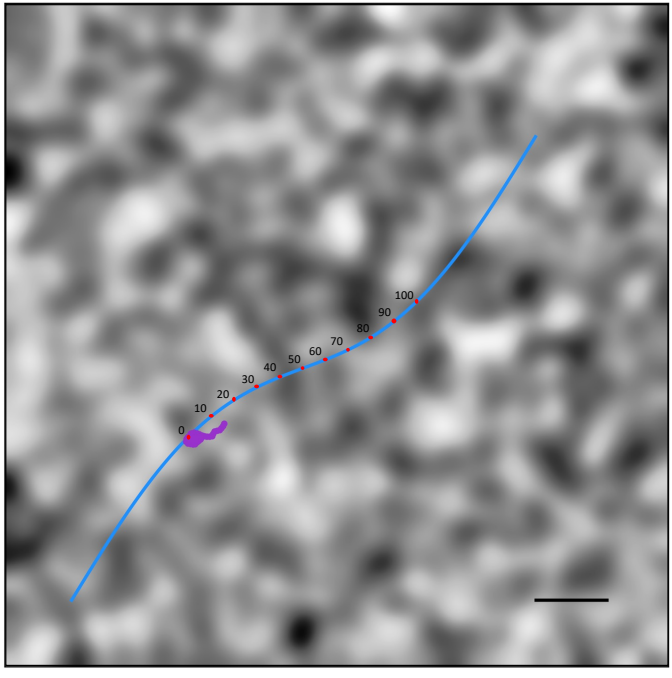


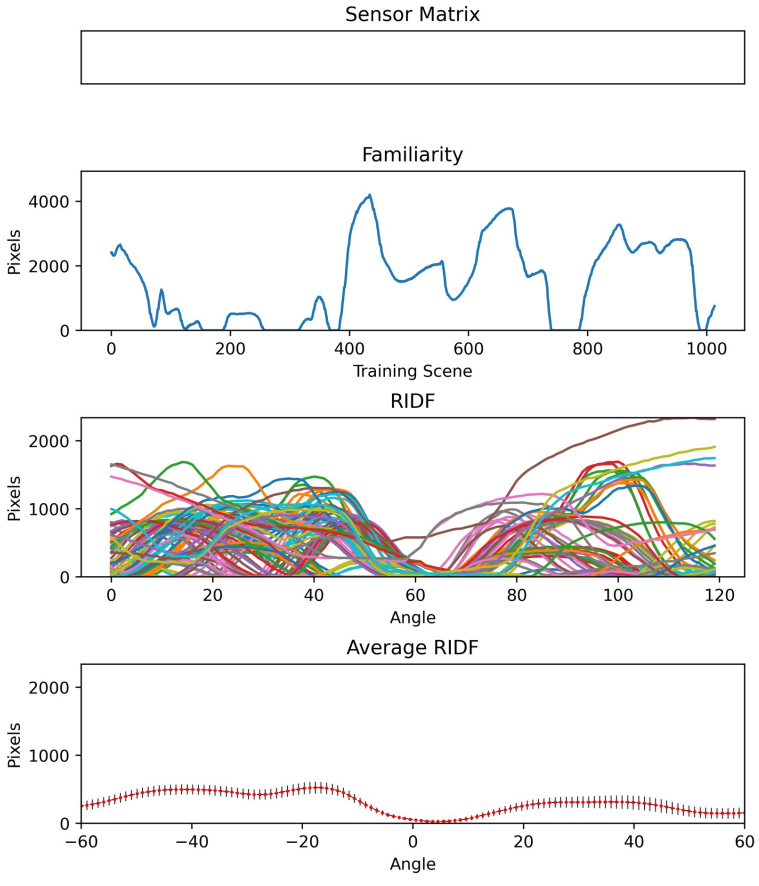
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4620.79; RMSD/dist: 11.552; TD: 886; p90: 86; p50: 40; complete: 0


Index: BLUR: 20.0; LEVELS: 64; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

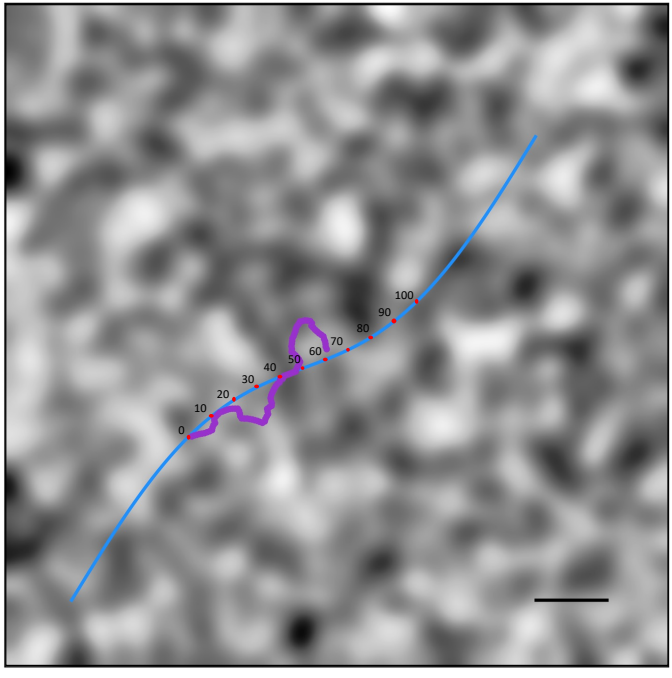


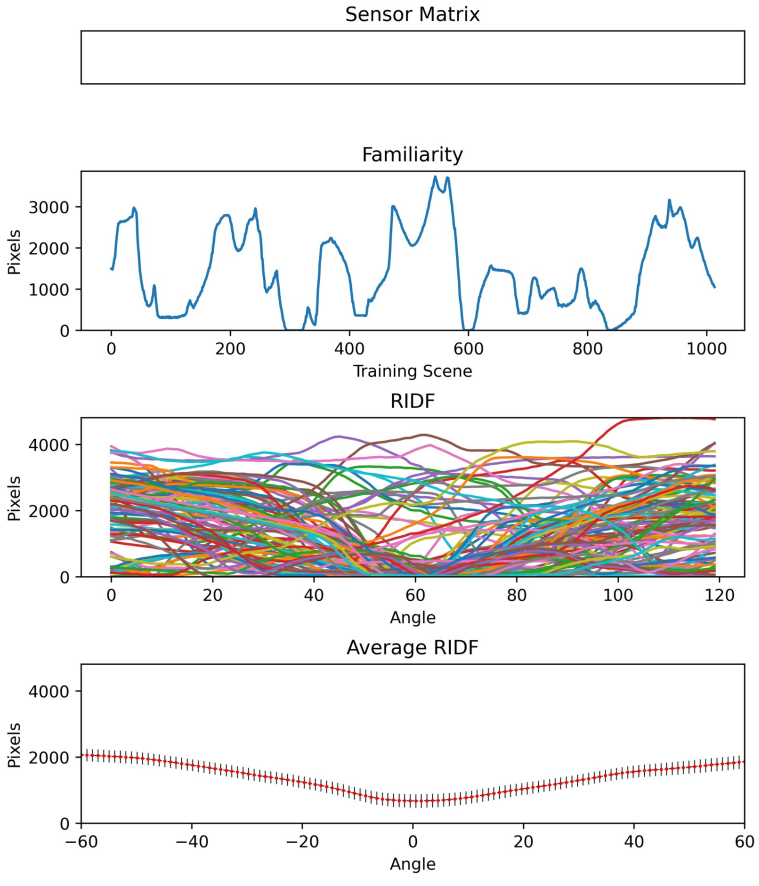


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 874.80; RMSD/dist: 2.187; TD: 1521; p90: 36; p50: 36; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 2643.76; RMSD/dist: 6.609; TD: 894; p90: 60; p50: 32; complete: 0

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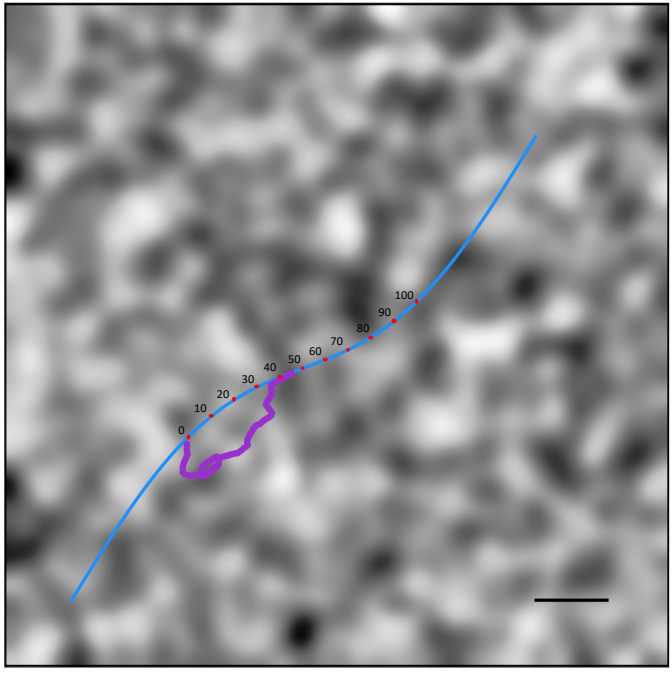
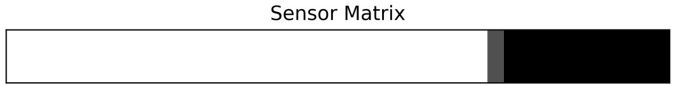
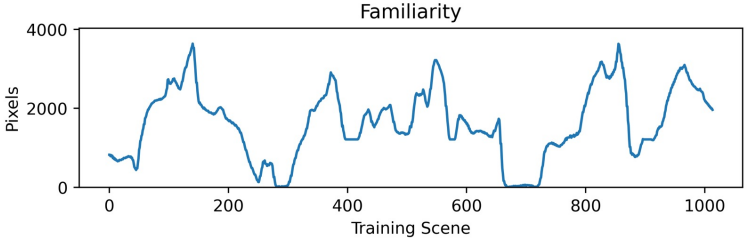
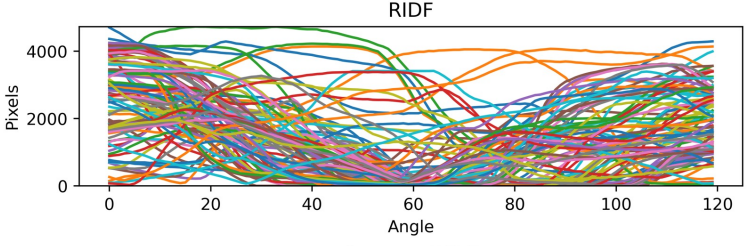
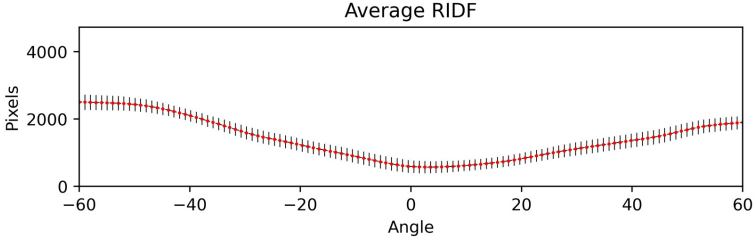






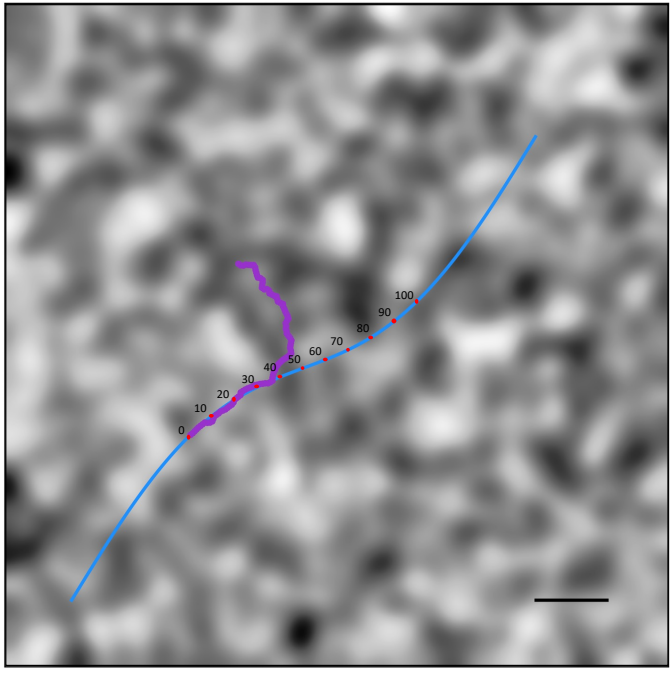


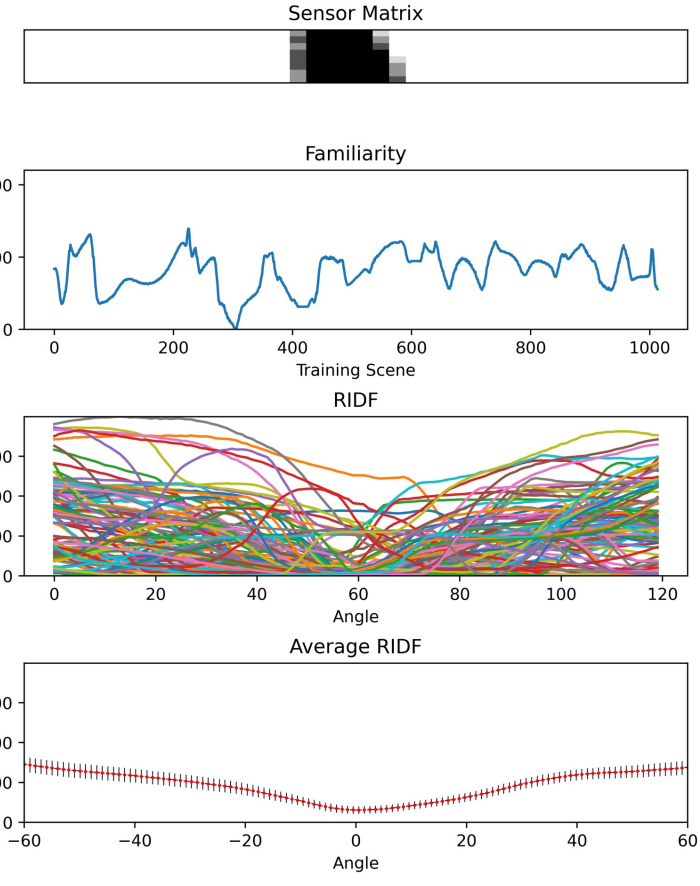


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4211.89; RMSD/dist: 10.530; TD: 856; p90: 46; p50: 28; complete: 0

10%

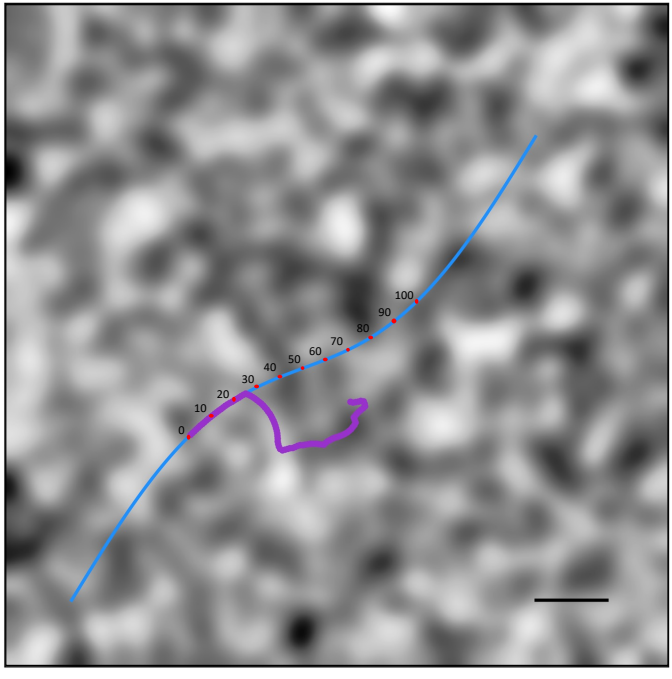


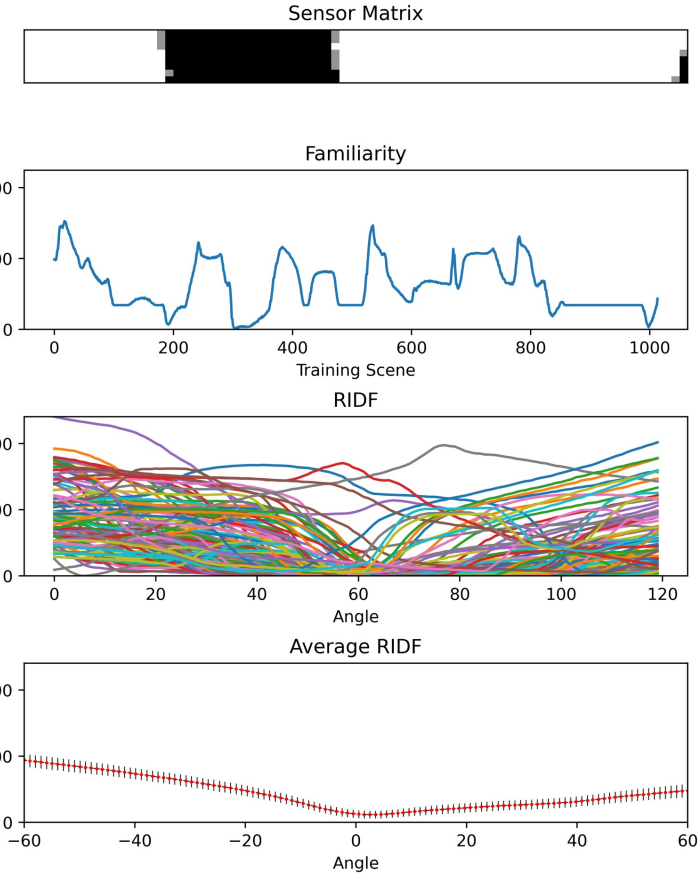


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 5597.49; RMSD/dist: 13.994; TD: 1258; p90: 118; p50: 52; complete: 0

20%

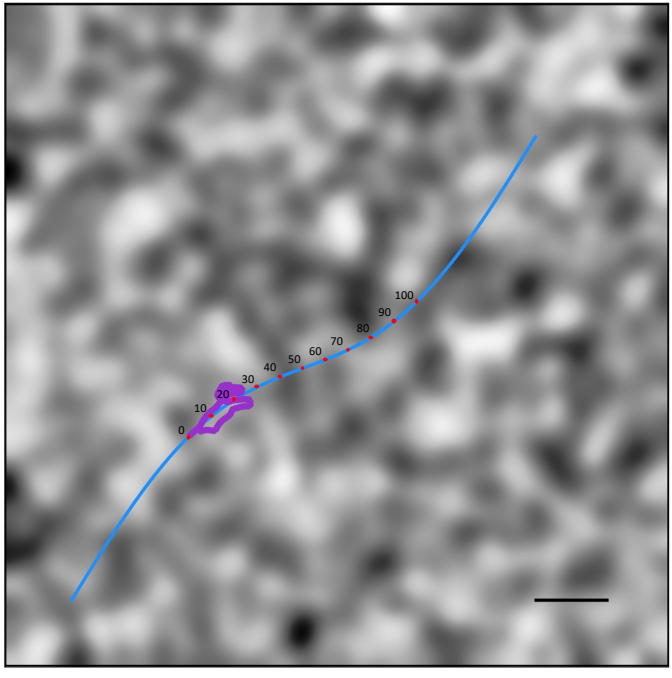


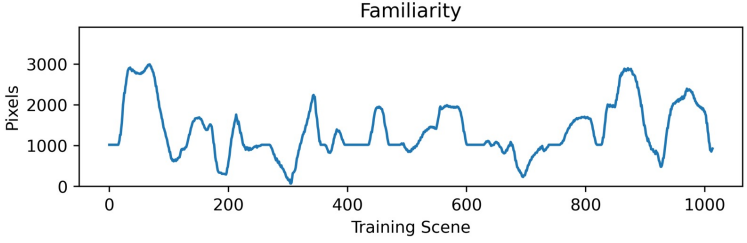


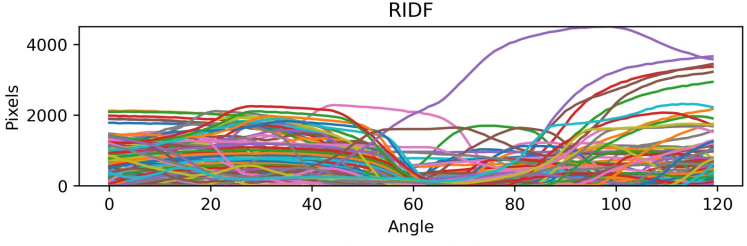
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

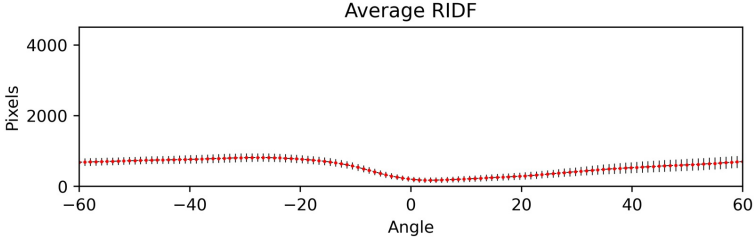
Navigation stats: RMSD error: 6138.17; RMSD/dist: 15.345; TD: 940; p90: 48; p50: 26; complete: 0

0%



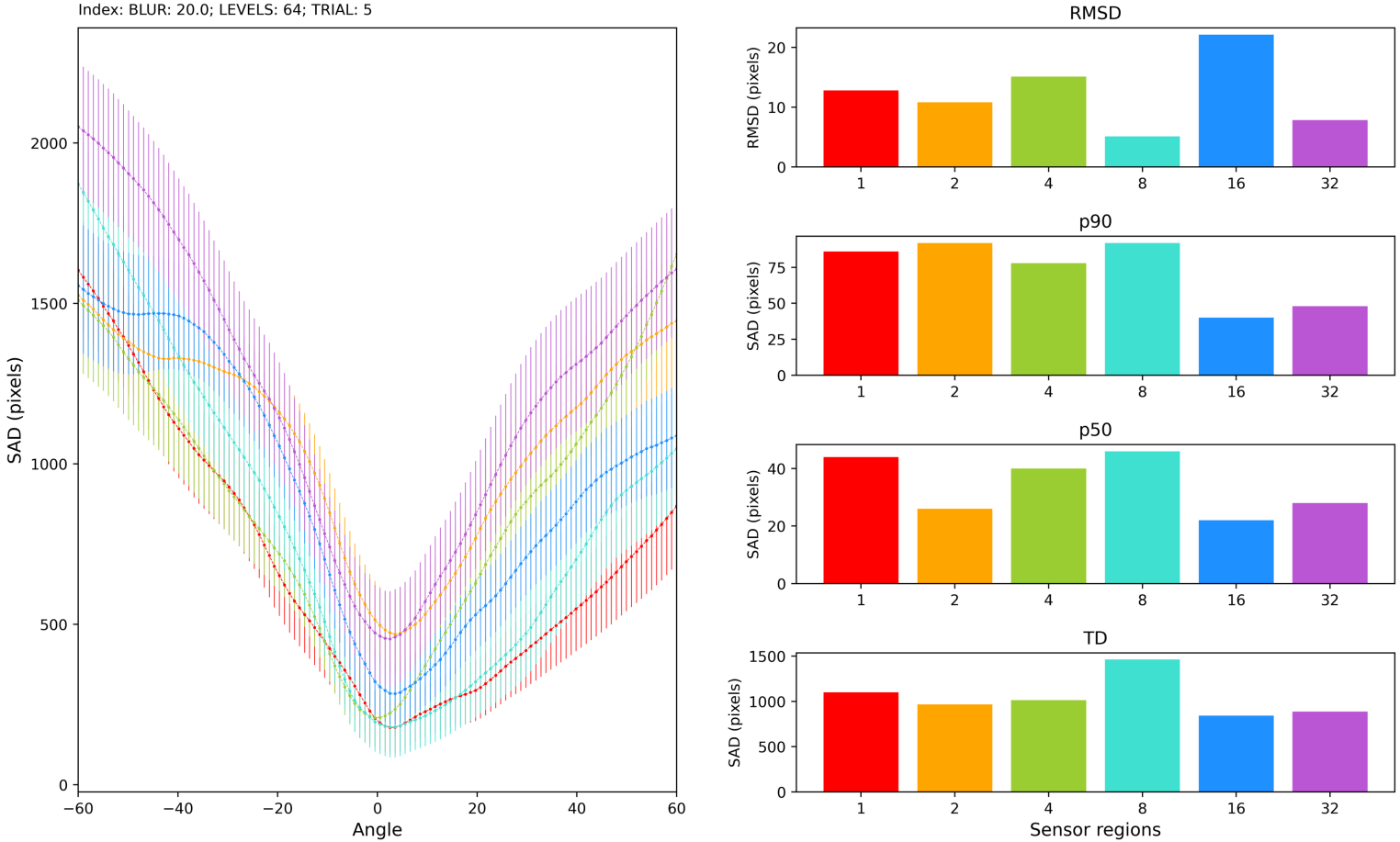




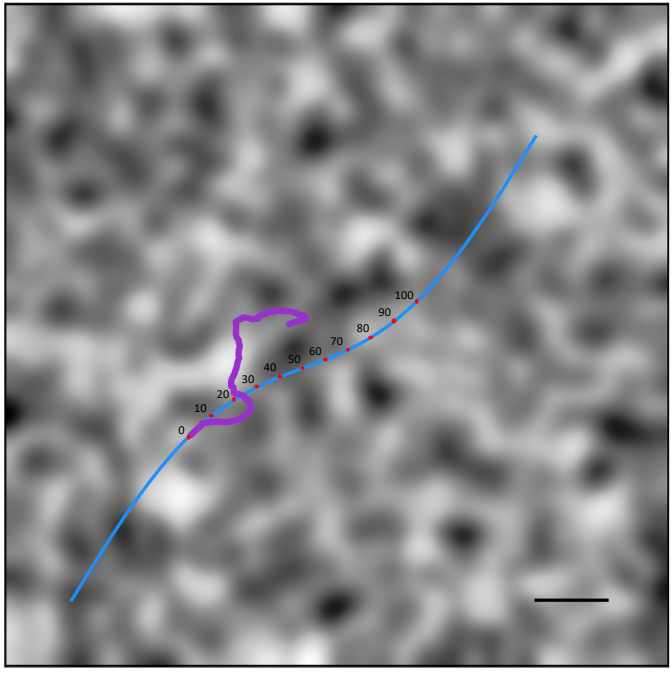


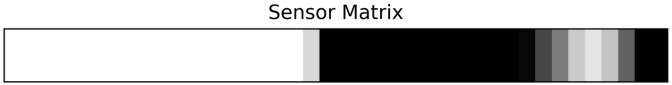
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

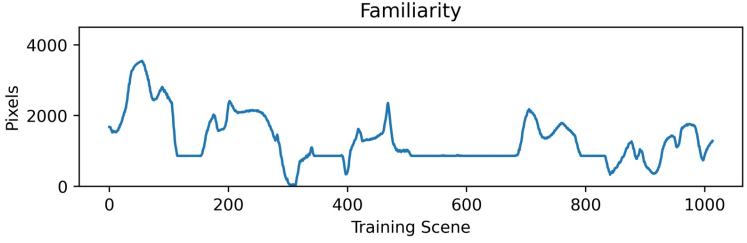
Navigation stats: RMSD error: 1327.86; RMSD/dist: 3.320; TD: 914; p90: 56; p50: 26; complete: 0

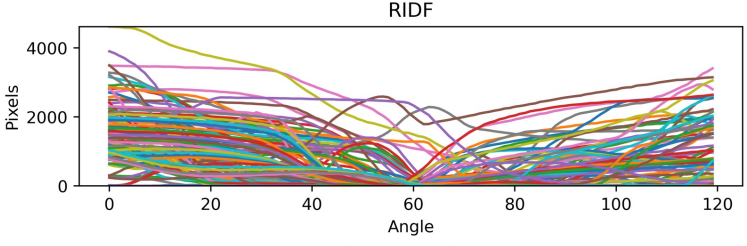

Index: BLUR: 20.0; LEVELS: 64; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

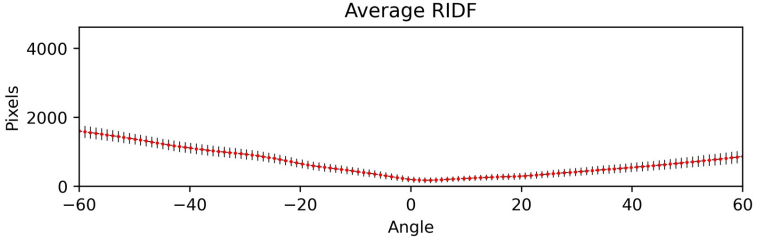
0%







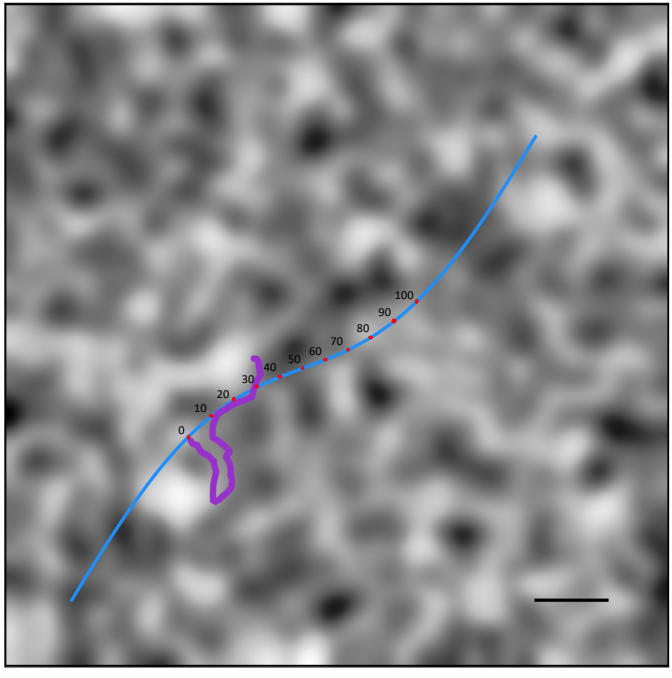


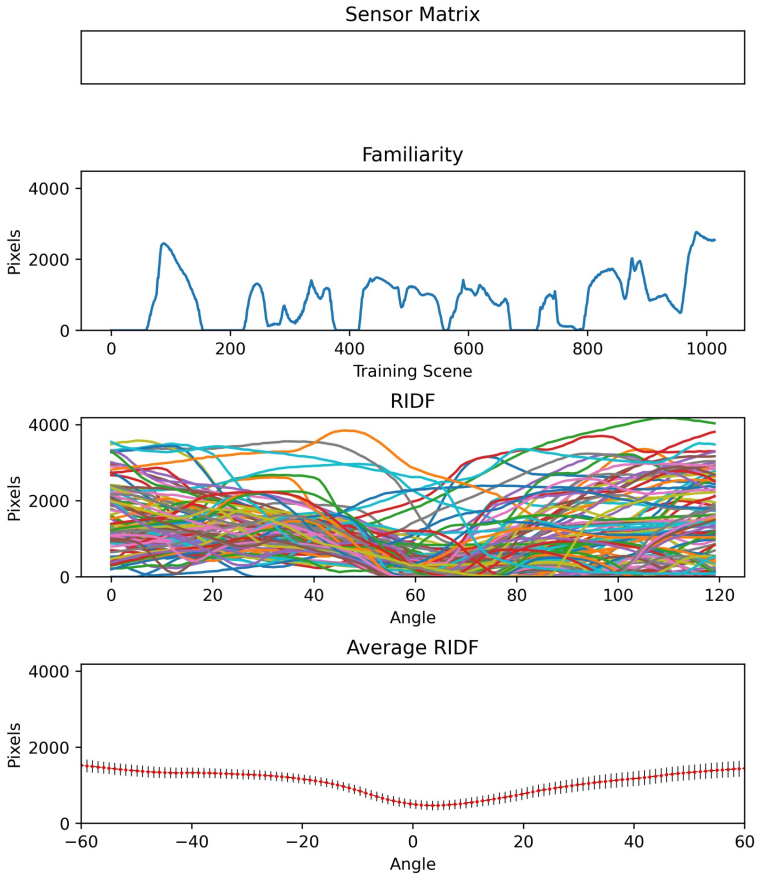


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5123.96; RMSD/dist: 12.810; TD: 1100; p90: 86; p50: 44; complete: 0

0%

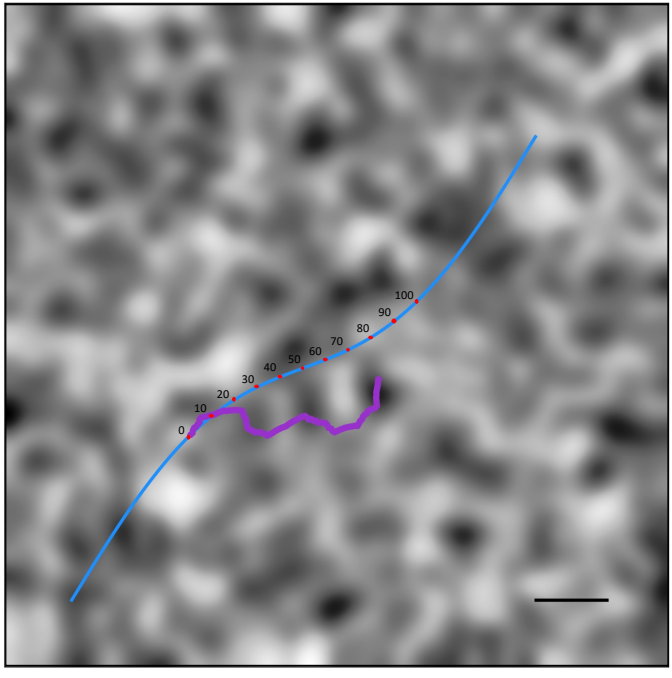


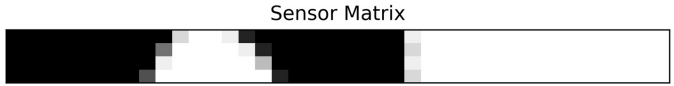


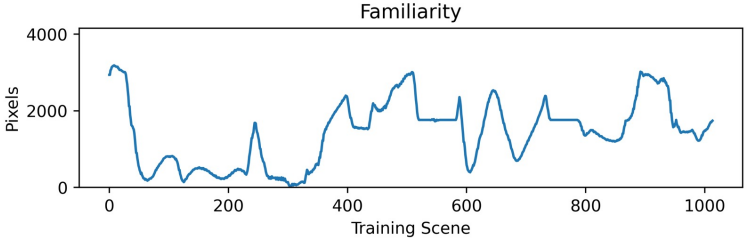
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

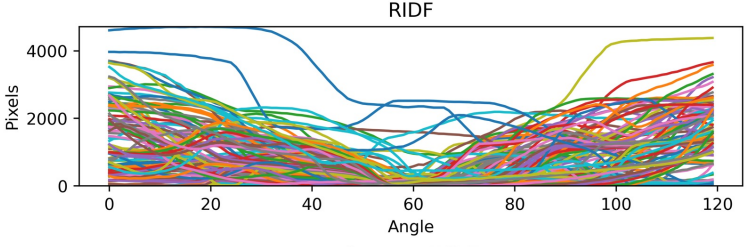
Navigation stats: RMSD error: 4321.79; RMSD/dist: 10.804; TD: 967; p90: 92; p50: 26; complete: 0

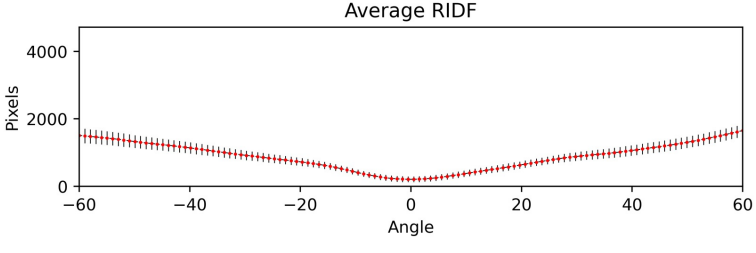
0%







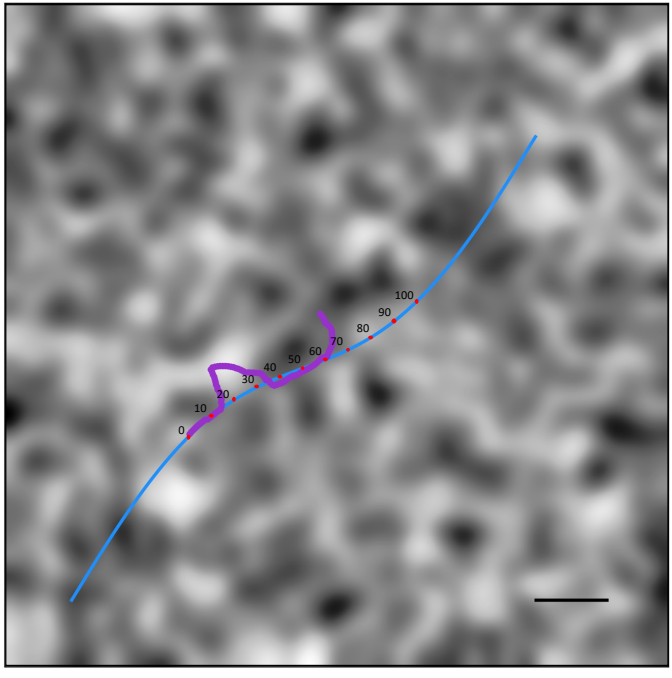


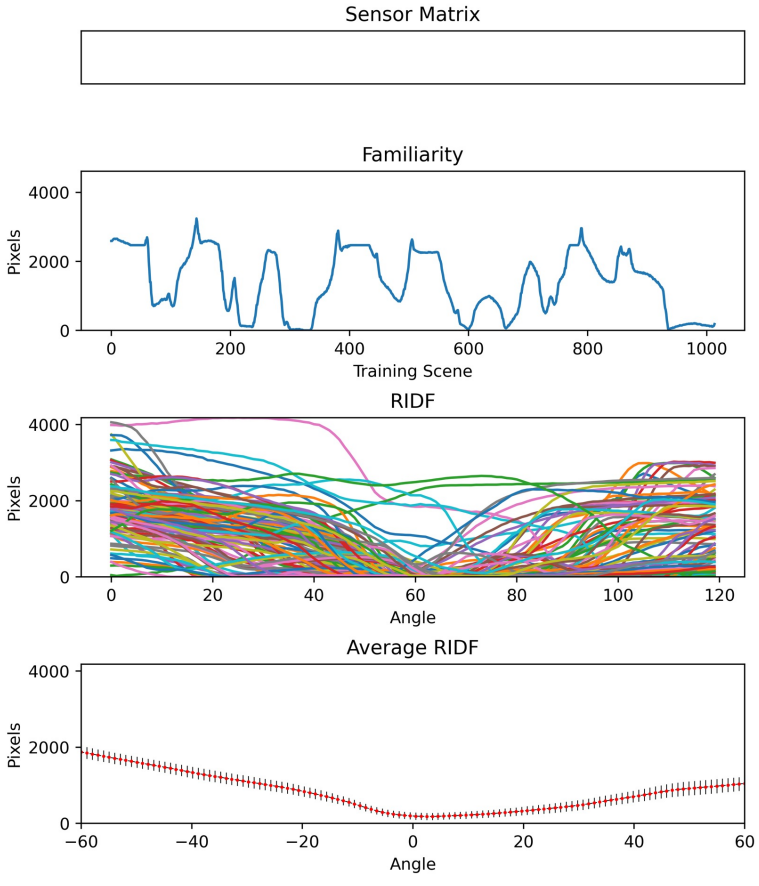


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 6051.43; RMSD/dist: 15.129; TD: 1014; p90: 78; p50: 40; complete: 0

10%

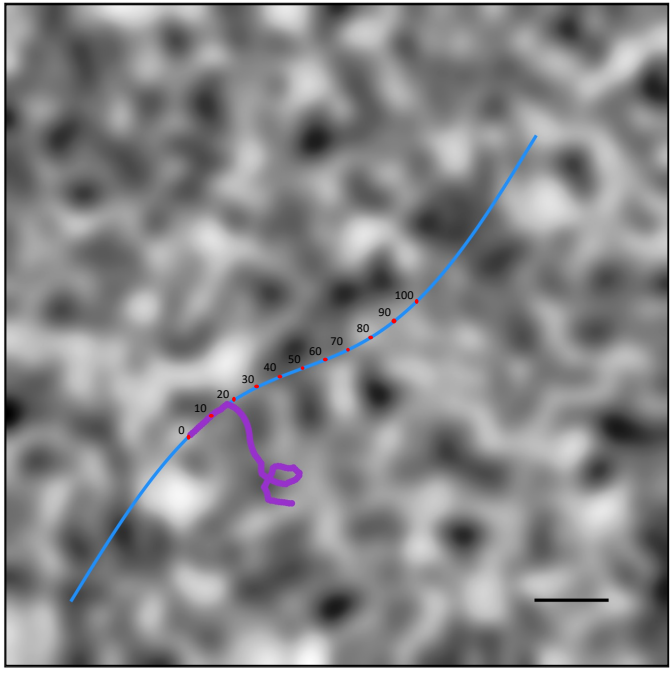


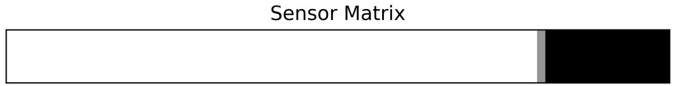


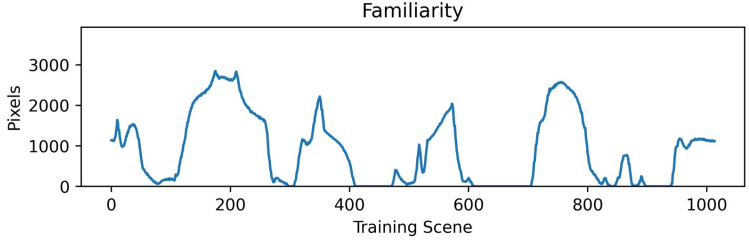
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

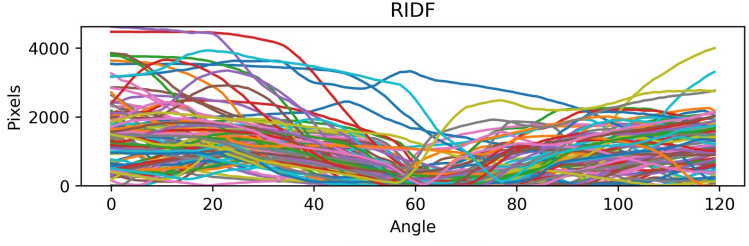
Navigation stats: RMSD error: 2046.55; RMSD/dist: 5.116; TD: 1462; p90: 92; p50: 46; complete: 0

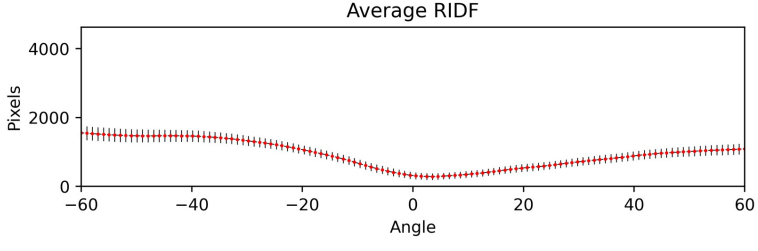
10%











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Navigation stats: RMSD error: 8864.65; RMSD/dist: 22.162; TD: 842; p90: 40; p50: 22; complete: 0

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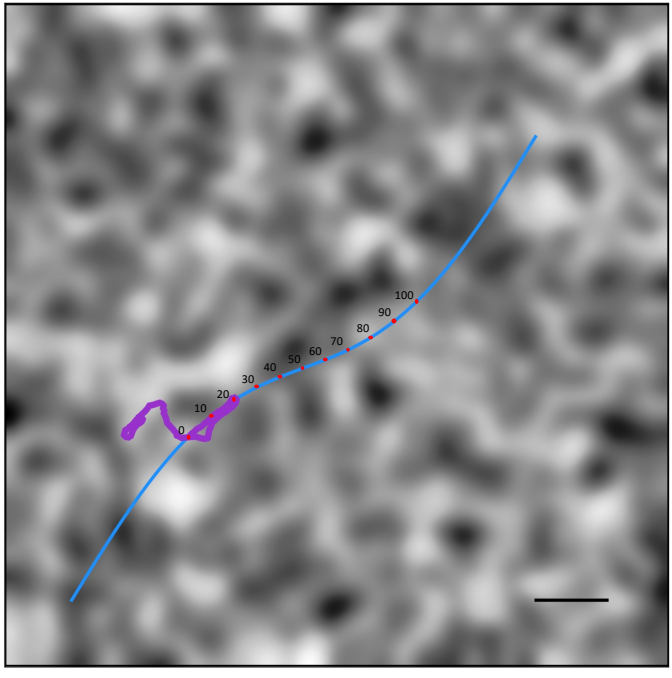

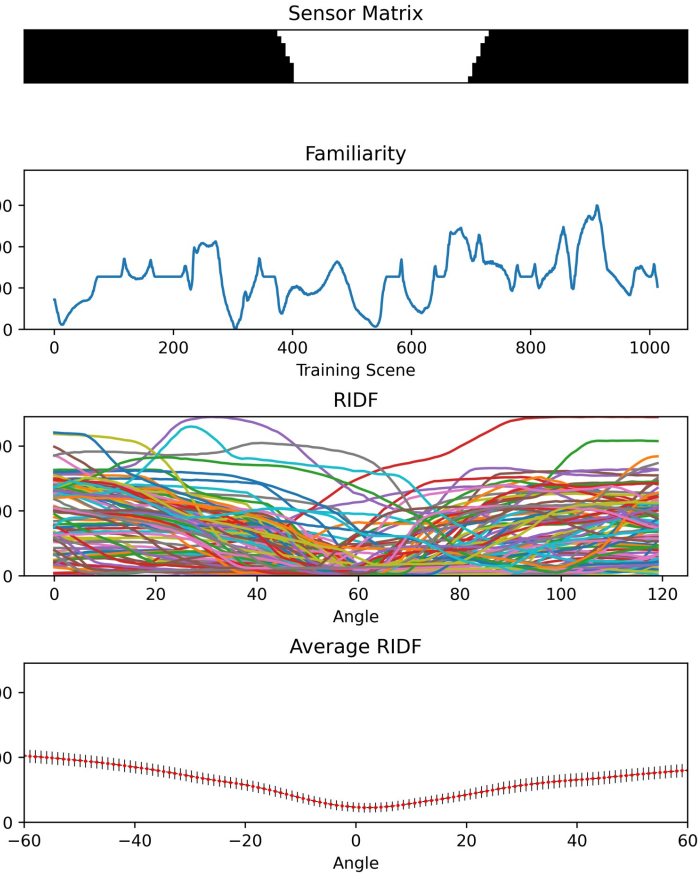

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

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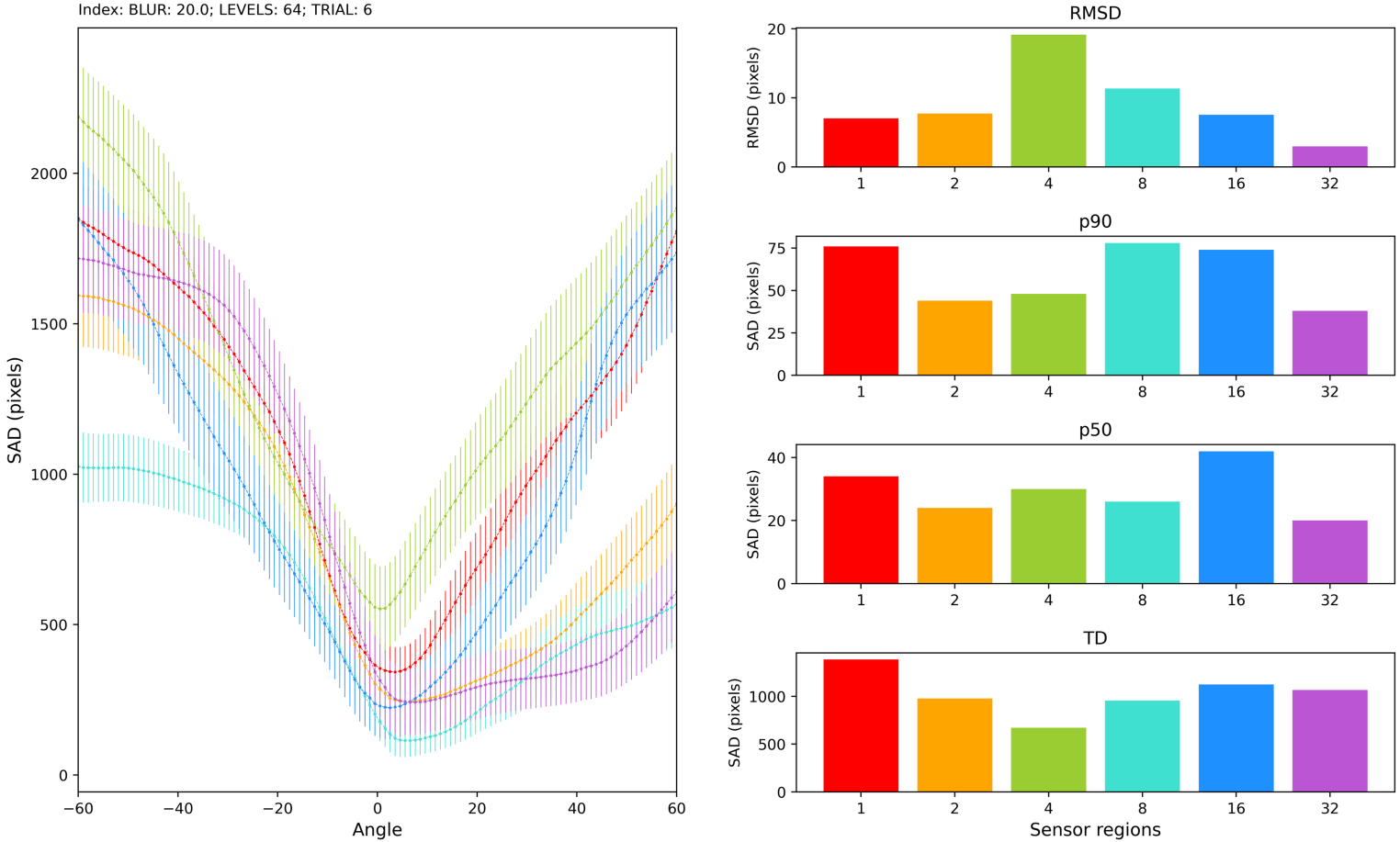
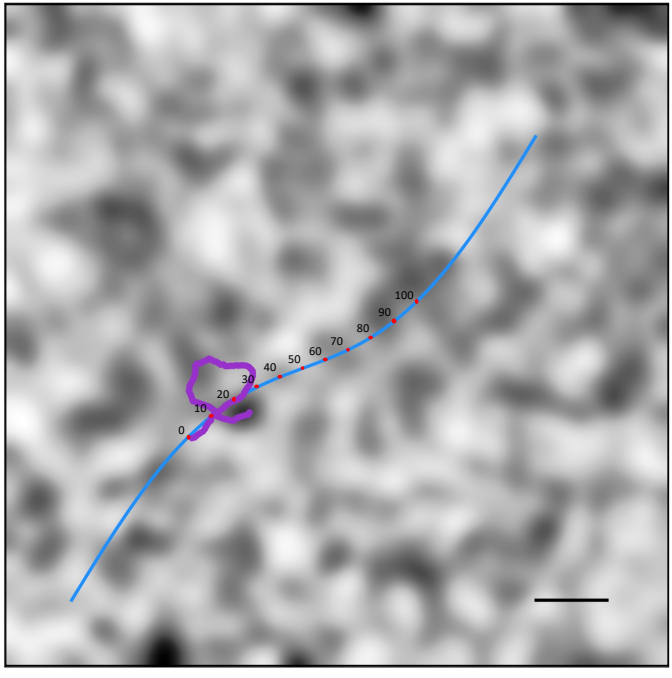
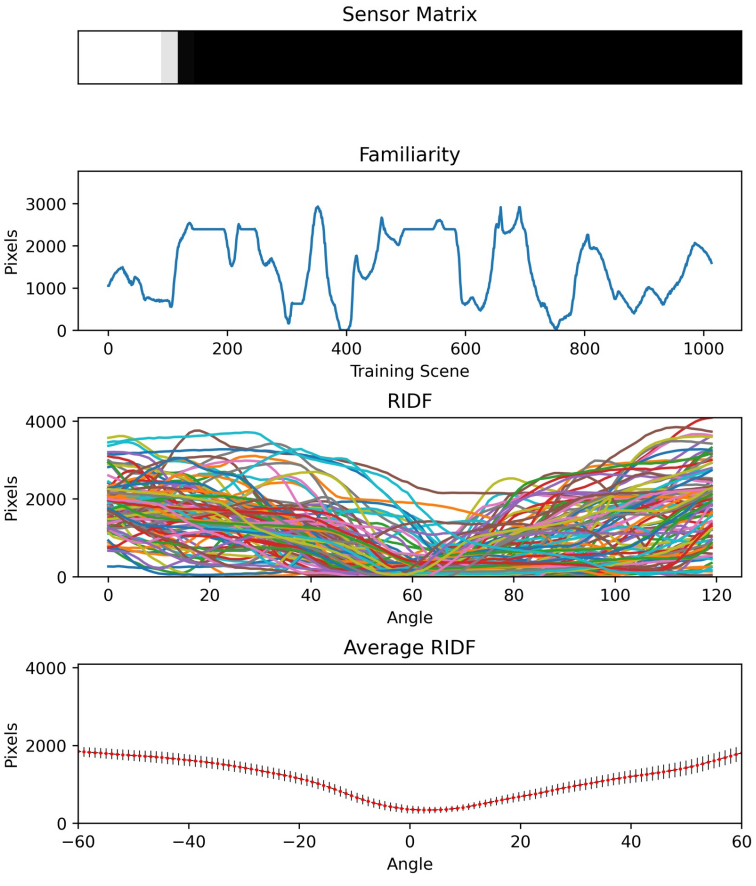

Index: BLUR: 20.0; LEVELS: 64; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2809.71; RMSD/dist: 7.024; TD: 1386; p90: 76; p50: 34; complete: 0

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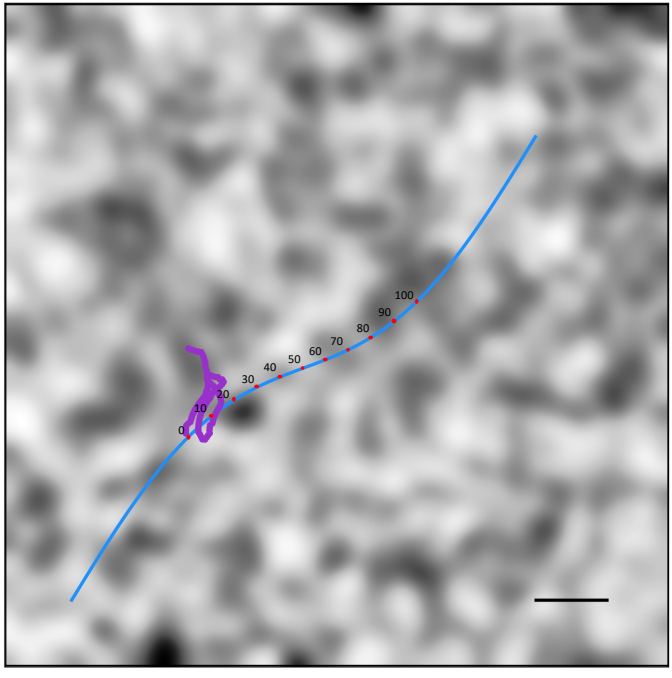
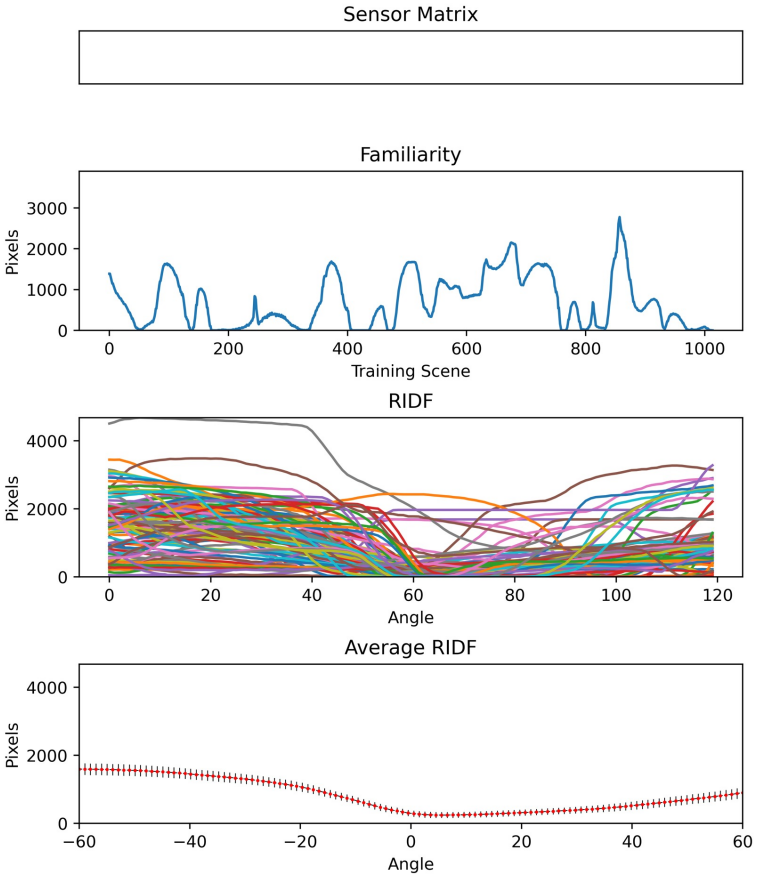
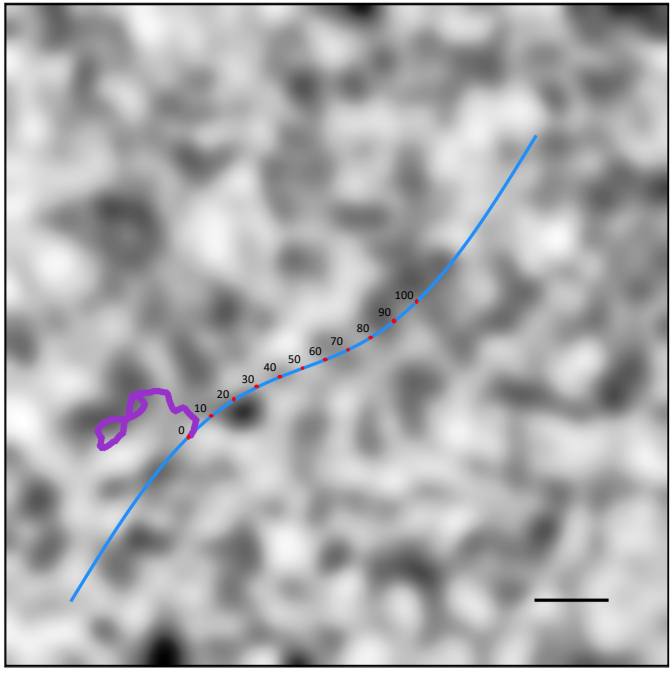


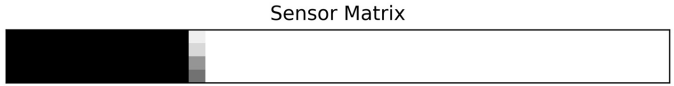


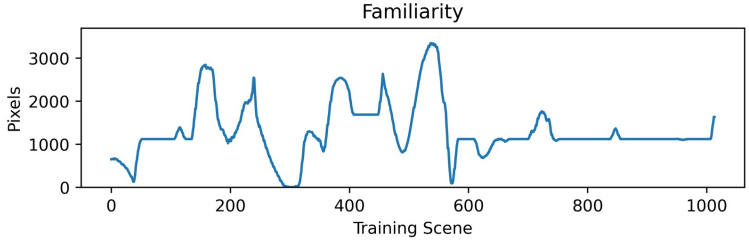
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

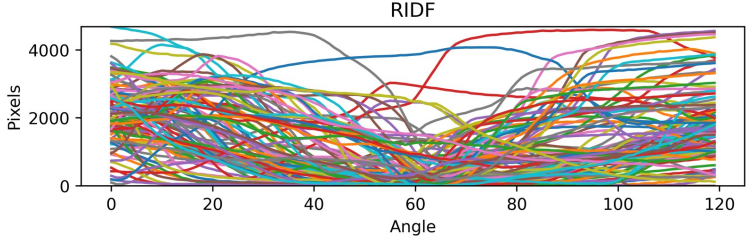
Navigation stats: RMSD error: 3083.05; RMSD/dist: 7.708; TD: 979; p90: 44; p50: 24; complete: 0

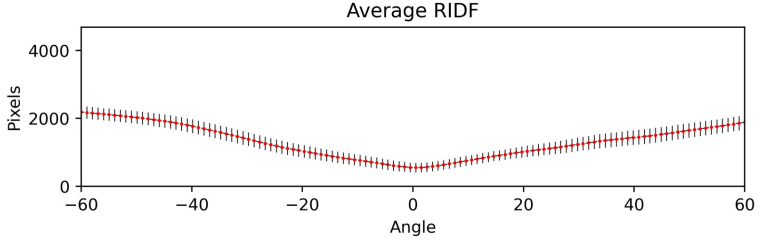
0%







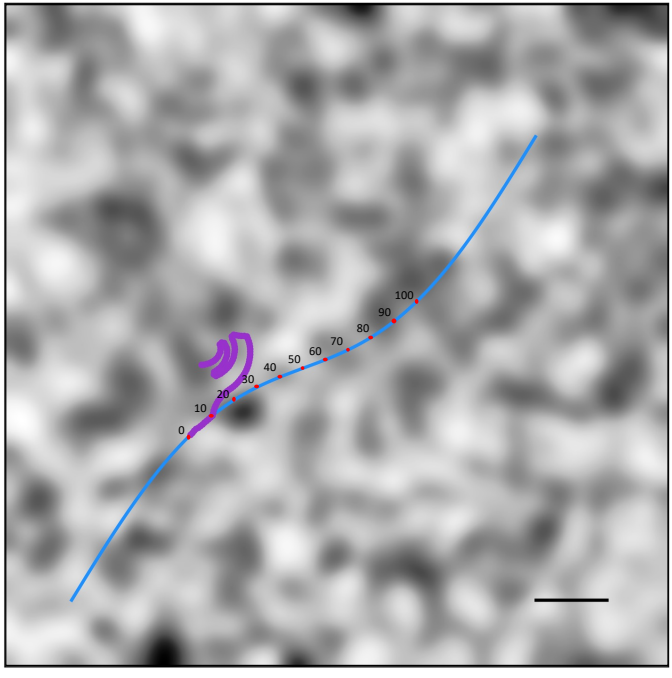


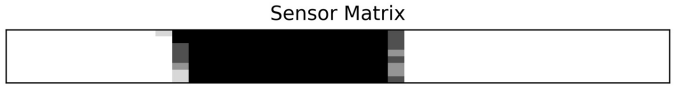


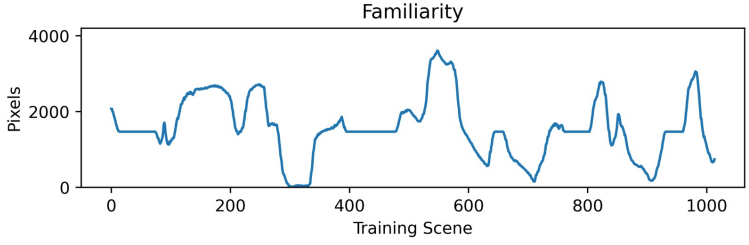
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

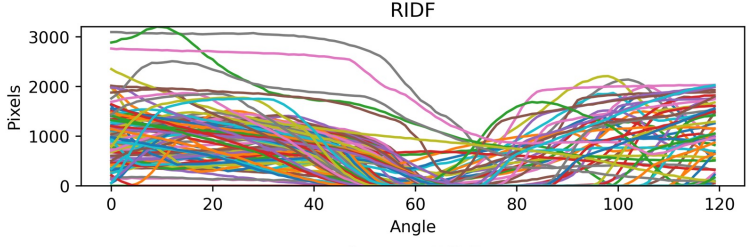
Navigation stats: RMSD error: 7658.89; RMSD/dist: 19.147; TD: 671; p90: 48; p50: 30; complete: 0

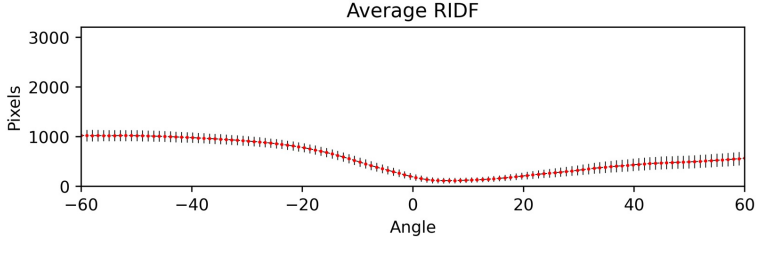
10%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4532.73; RMSD/dist: 11.332; TD: 956; p90: 78; p50: 26; complete: 0

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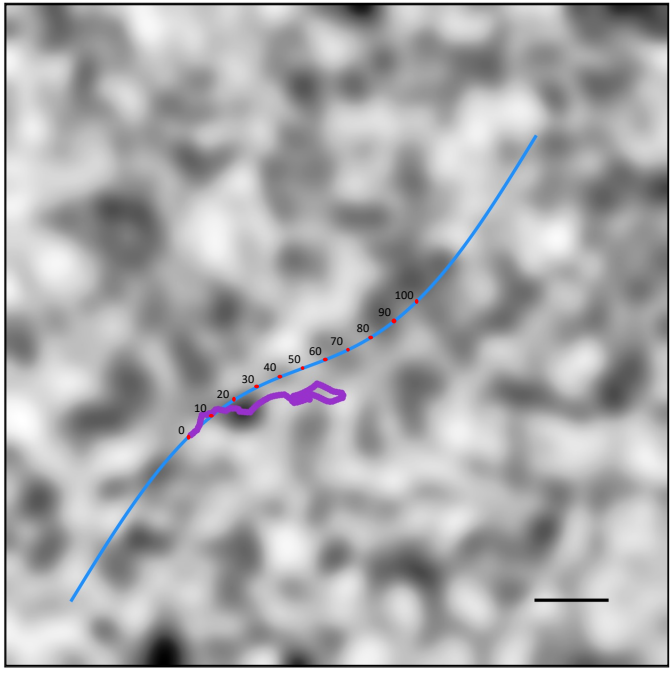

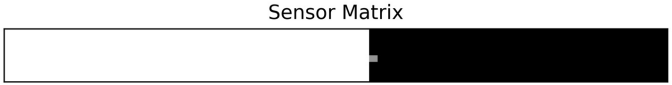

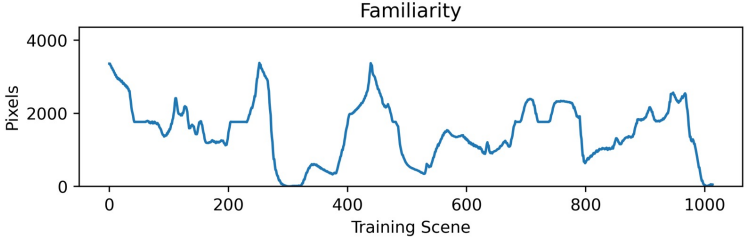

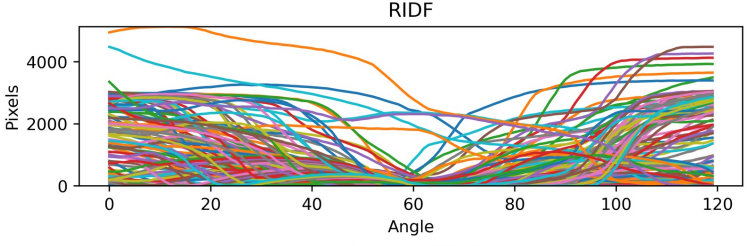

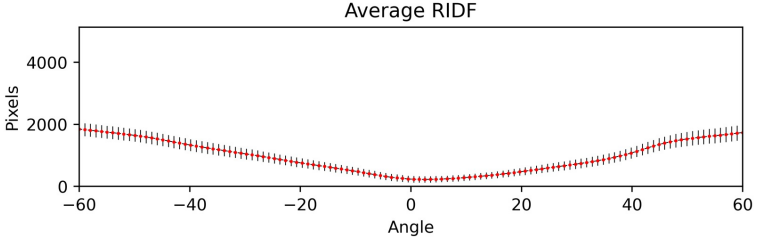

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3015.84; RMSD/dist: 7.540; TD: 1125; p90: 74; p50: 42; complete: 0

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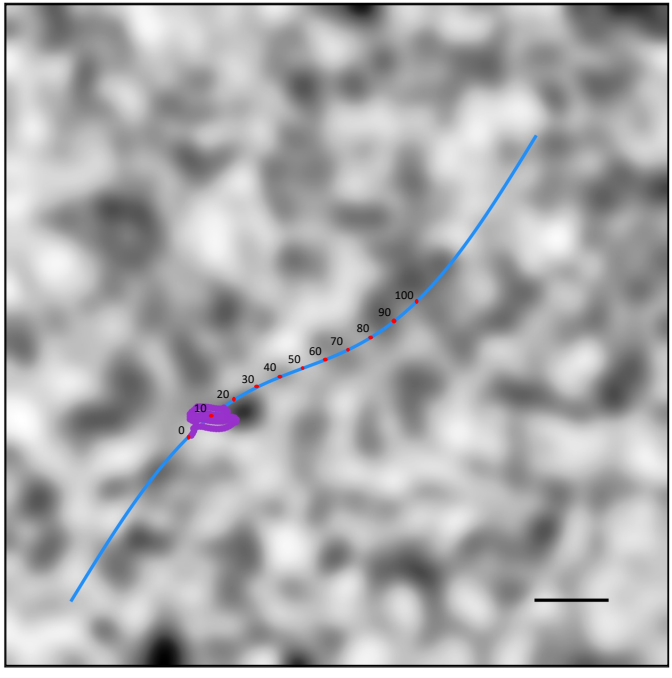

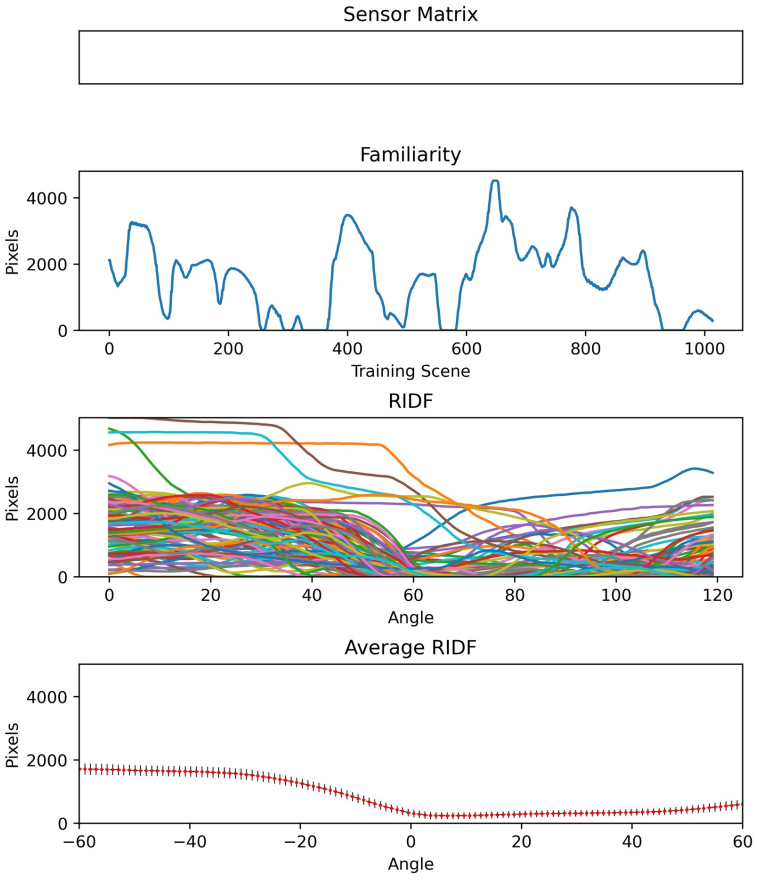

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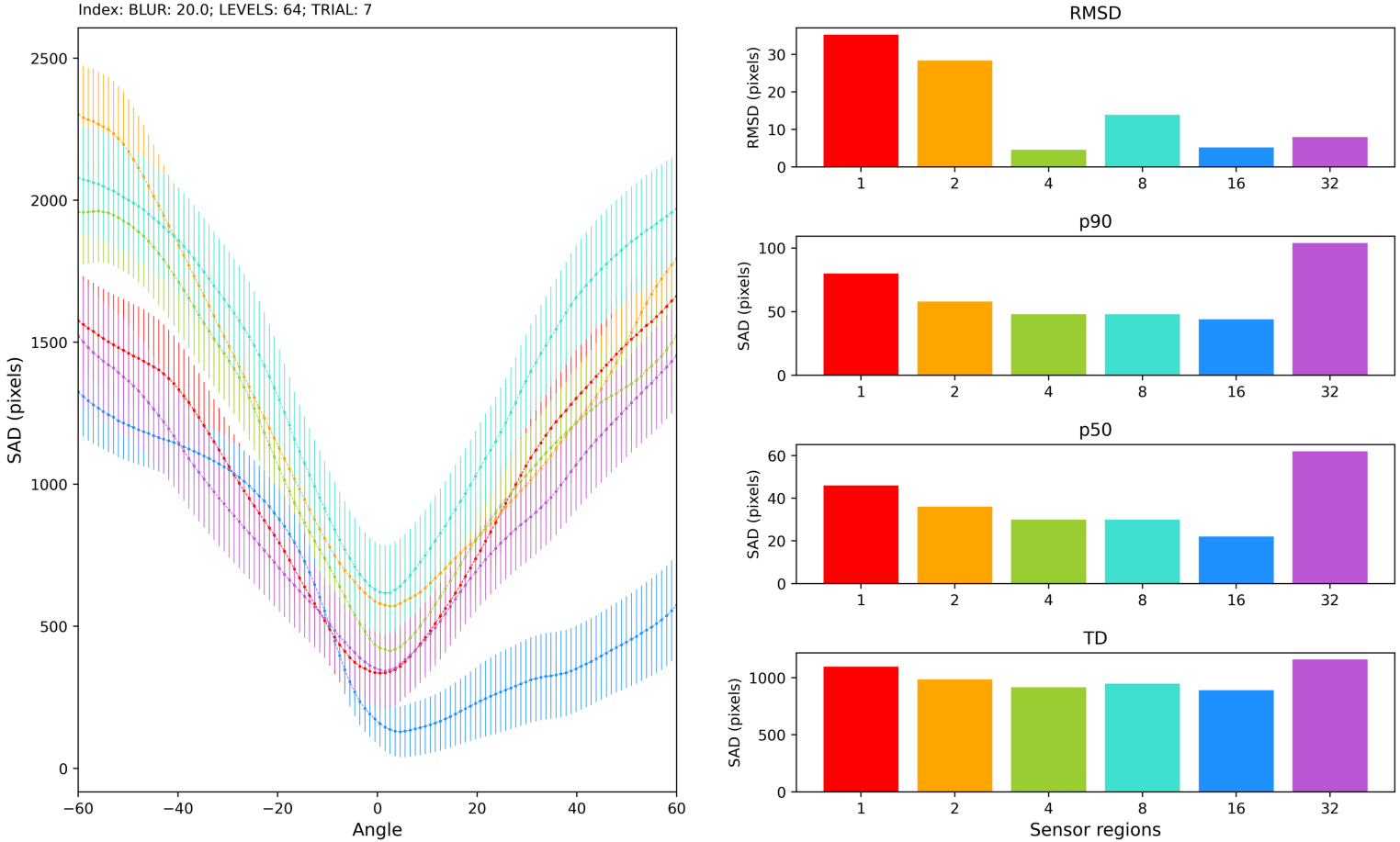
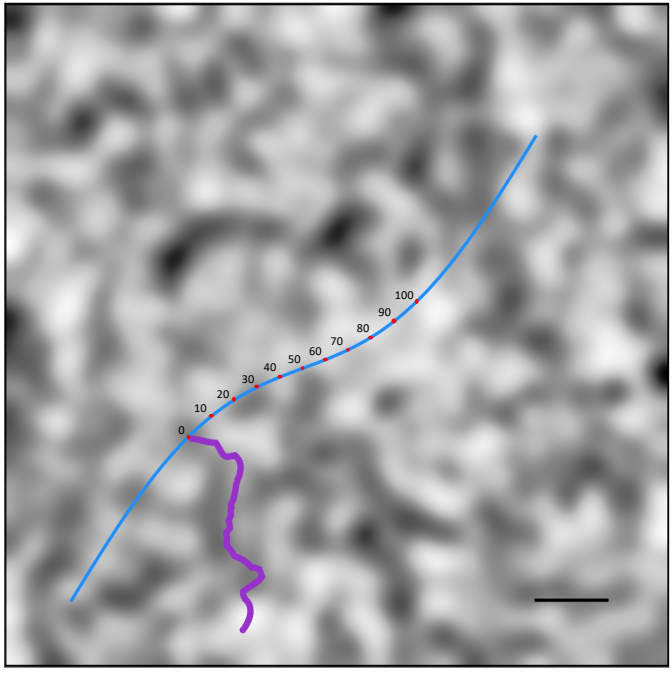
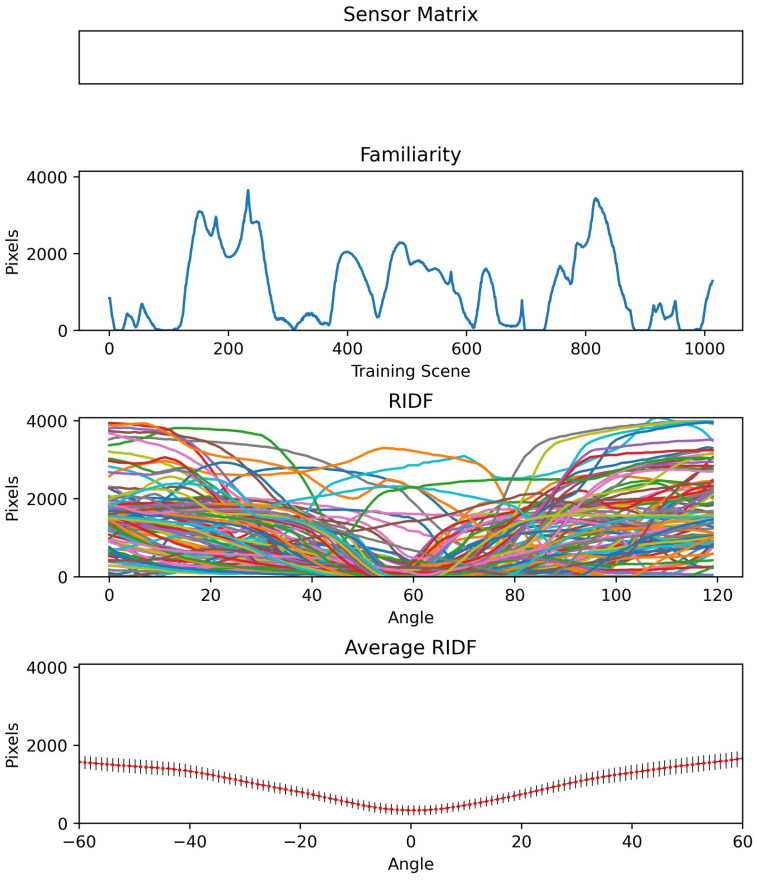
Navigation stats: RMSD error: 1186.66; RMSD/dist: 2.967; TD: 1068; p90: 38; p50: 20; complete: 0


Index: BLUR: 20.0; LEVELS: 64; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

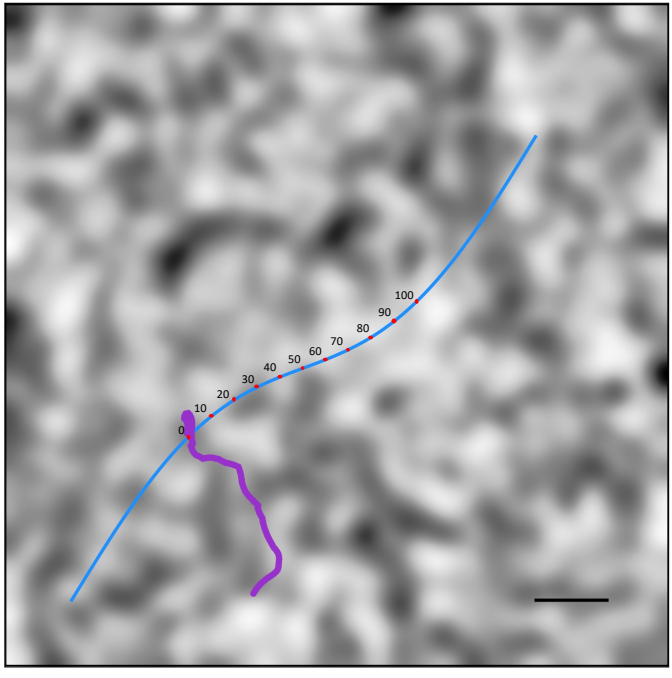


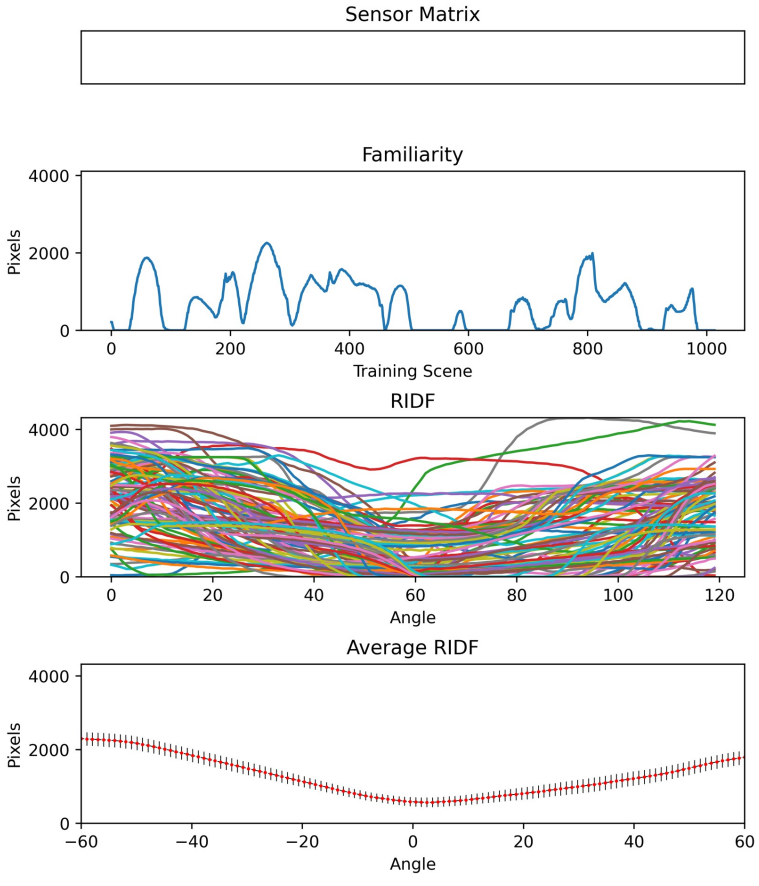


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 14118.33; RMSD/dist: 35.296; TD: 1096; p90: 80; p50: 46; complete: 0

0%

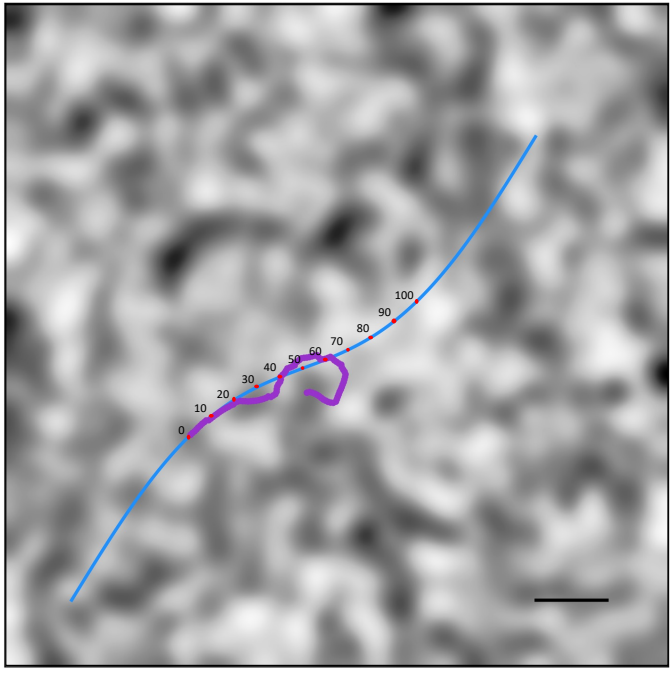


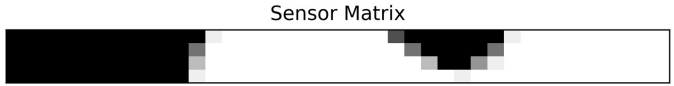


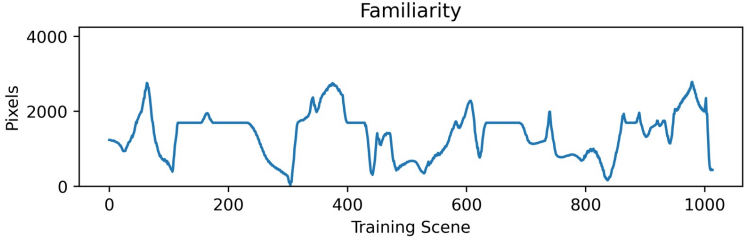
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

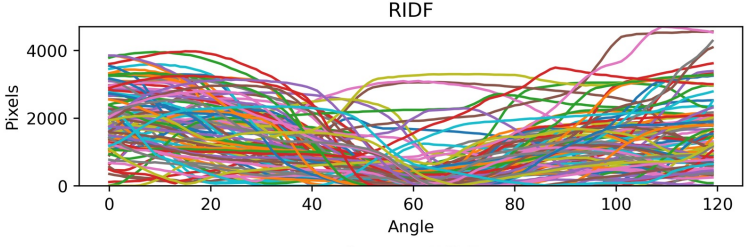
Navigation stats: RMSD error: 11350.68; RMSD/dist: 28.377; TD: 985; p90: 58; p50: 36; complete: 0

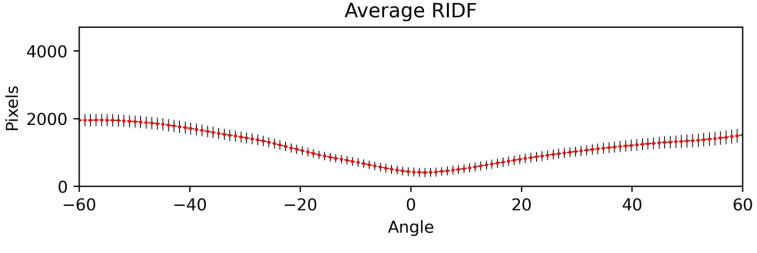
10%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1835.23; RMSD/dist: 4.588; TD: 916; p90: 48; p50: 30; complete: 0

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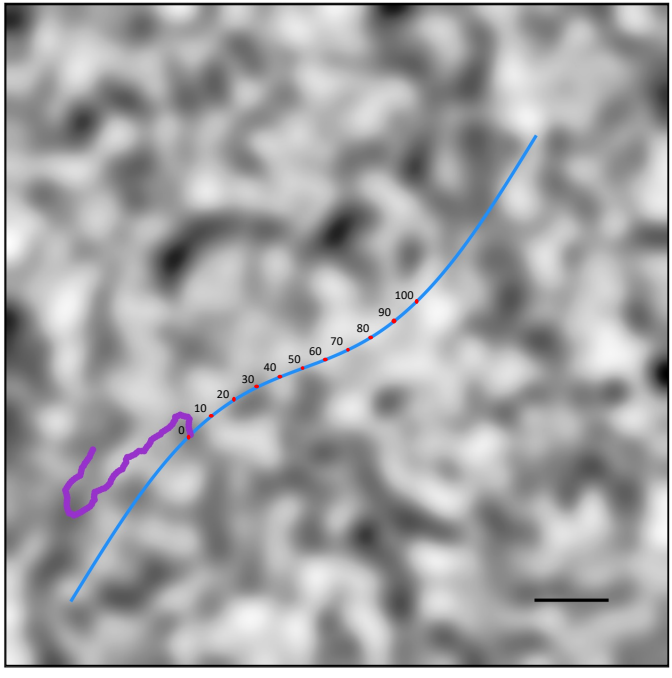
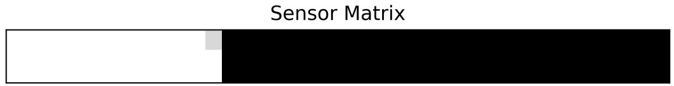
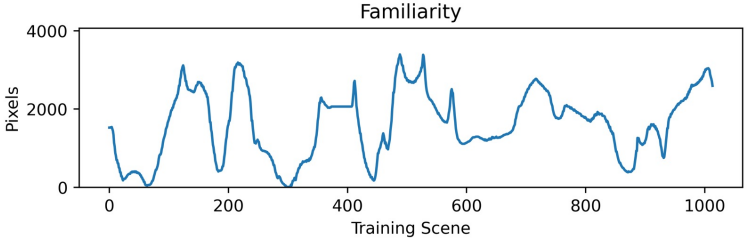
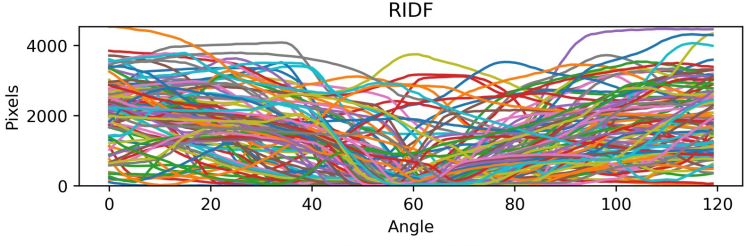
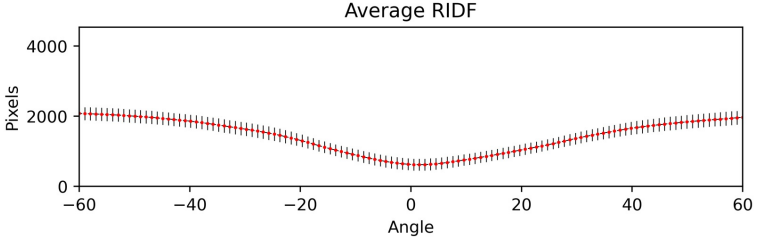






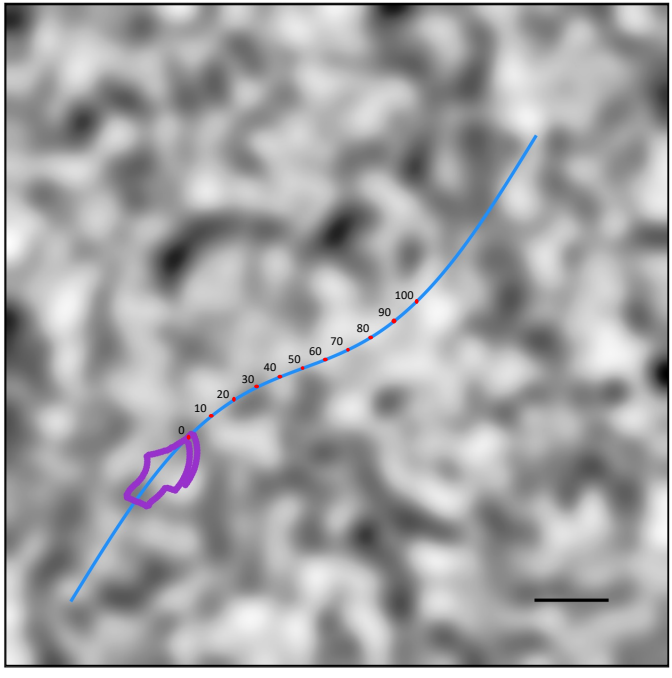


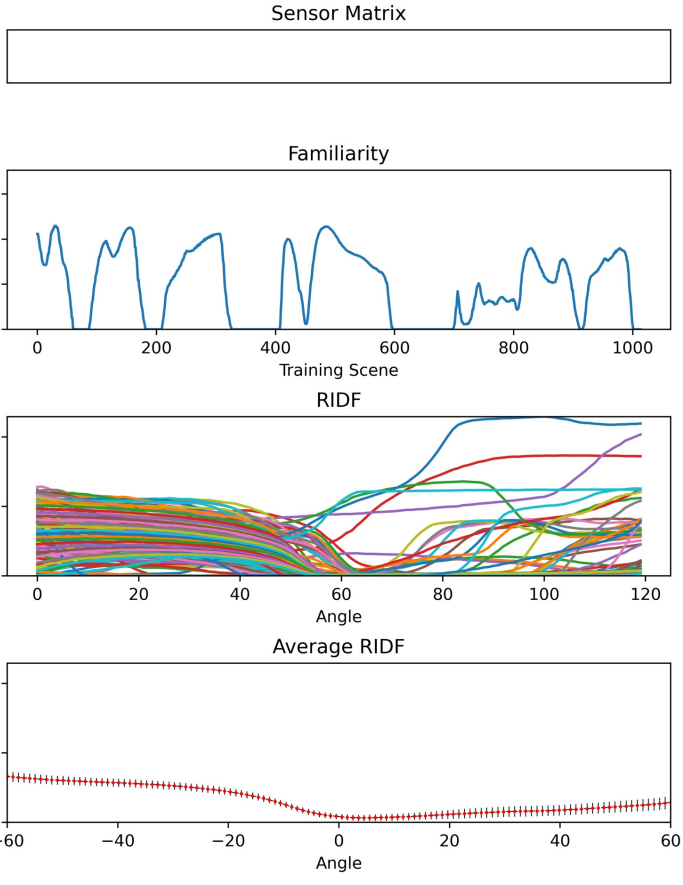


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 5560.66; RMSD/dist: 13.902; TD: 949; p90: 48; p50: 30; complete: 0

0%

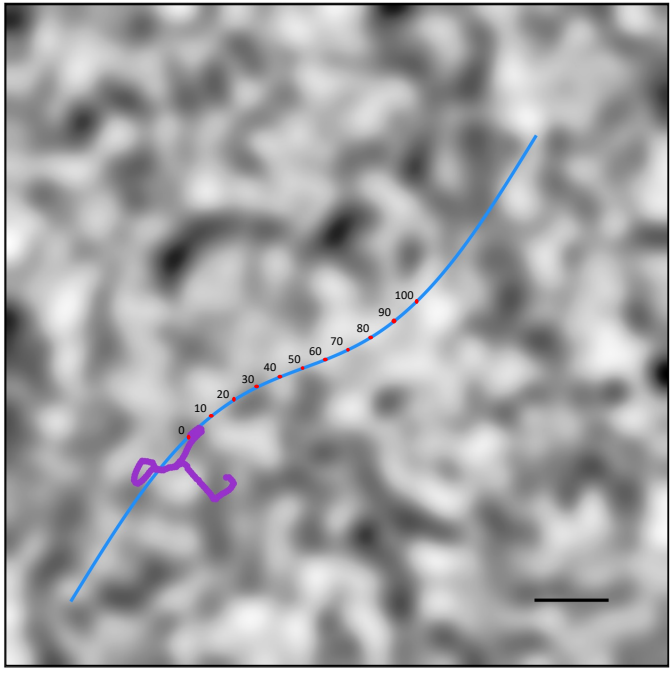


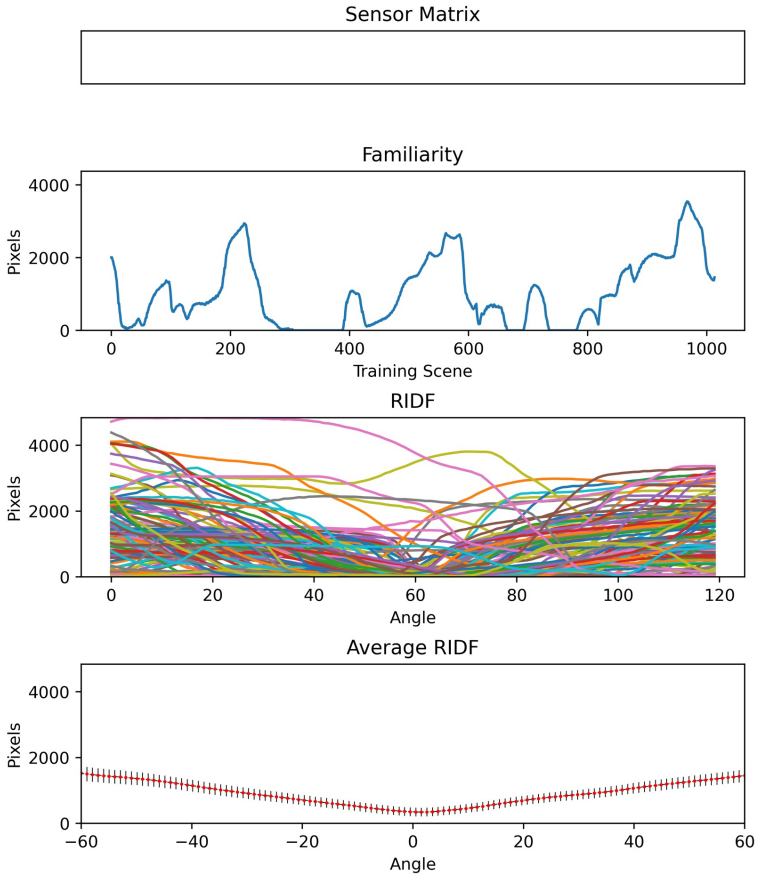


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2077.93; RMSD/dist: 5.195; TD: 890; p90: 44; p50: 22; complete: 0

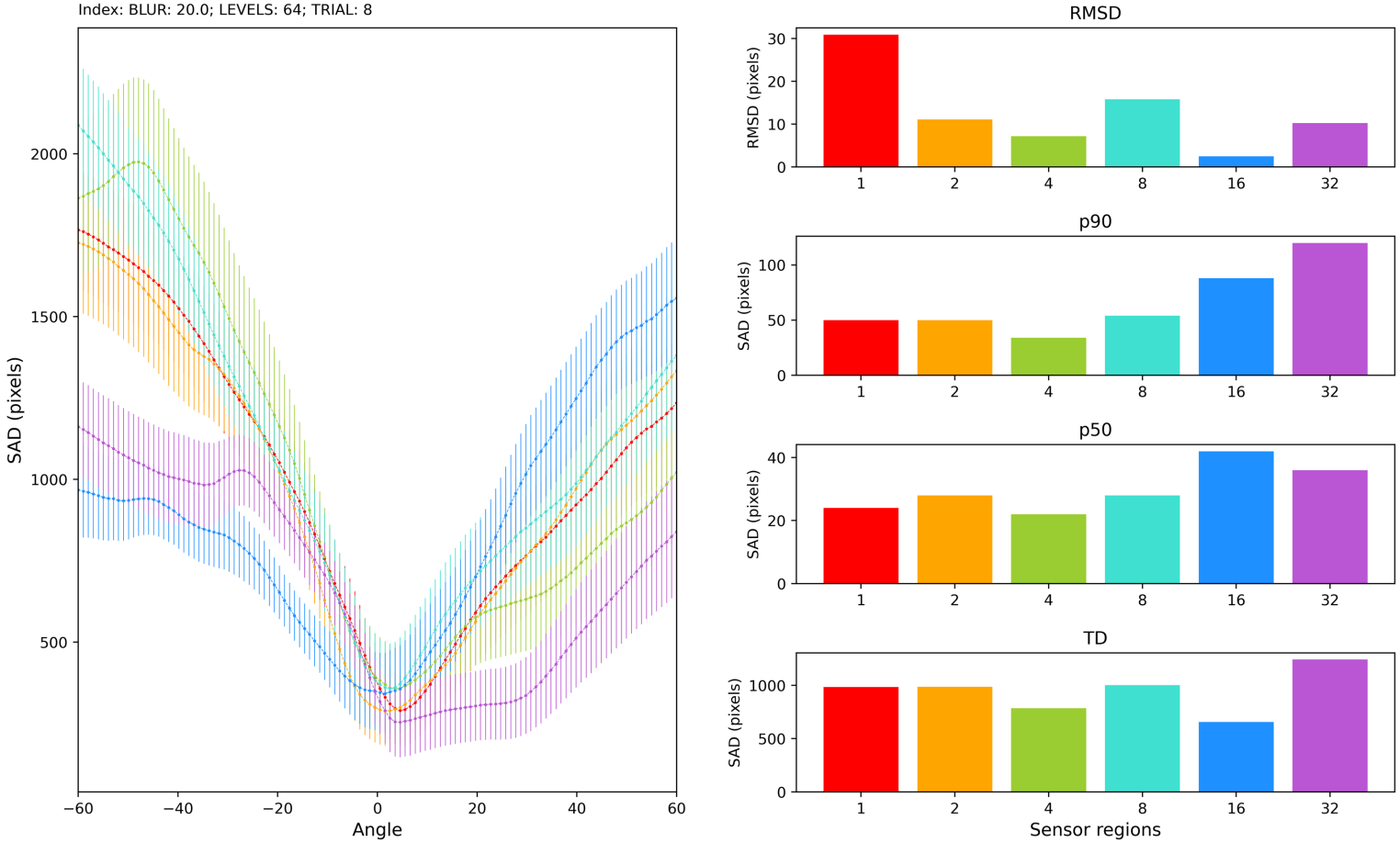
0%



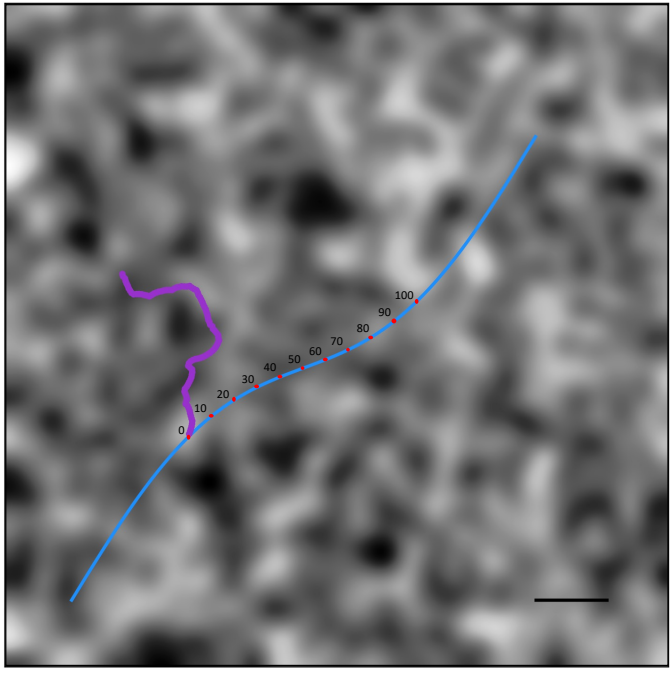


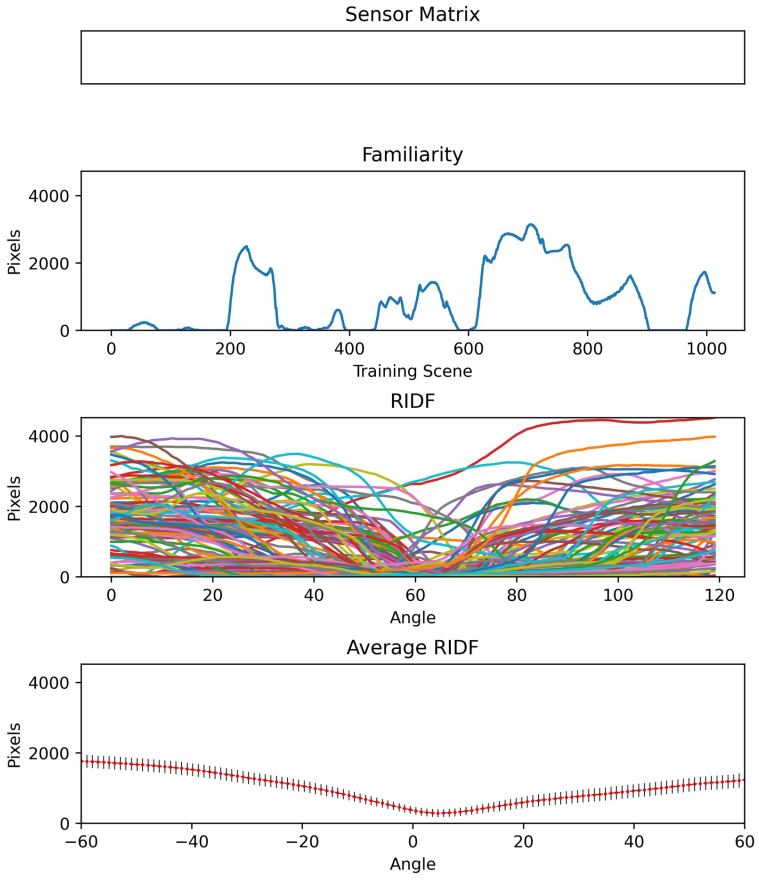
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3177.72; RMSD/dist: 7.944; TD: 1159; p90: 104; p50: 62; complete: 0


Index: BLUR: 20.0; LEVELS: 64; TRIAL: 8
SAD (pixels)
2000
1500
1000
500
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
30
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
40
20
TD
1000
500
Sensor regions

0%

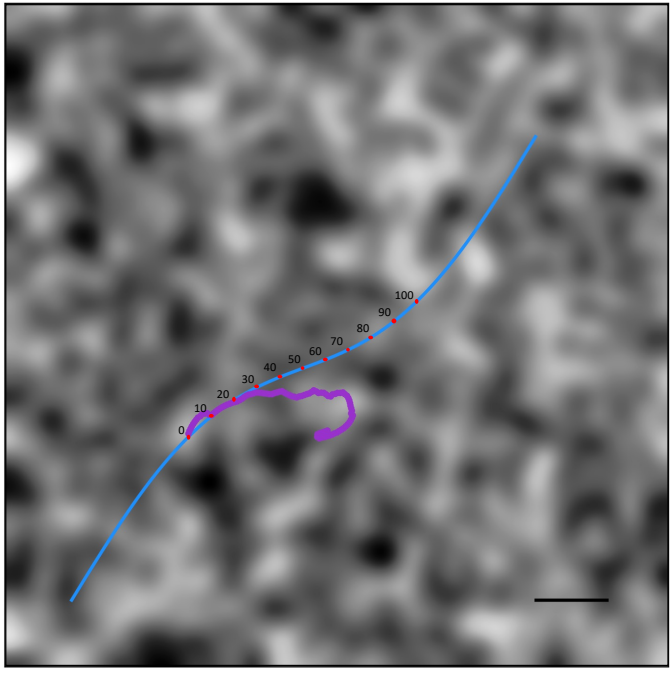


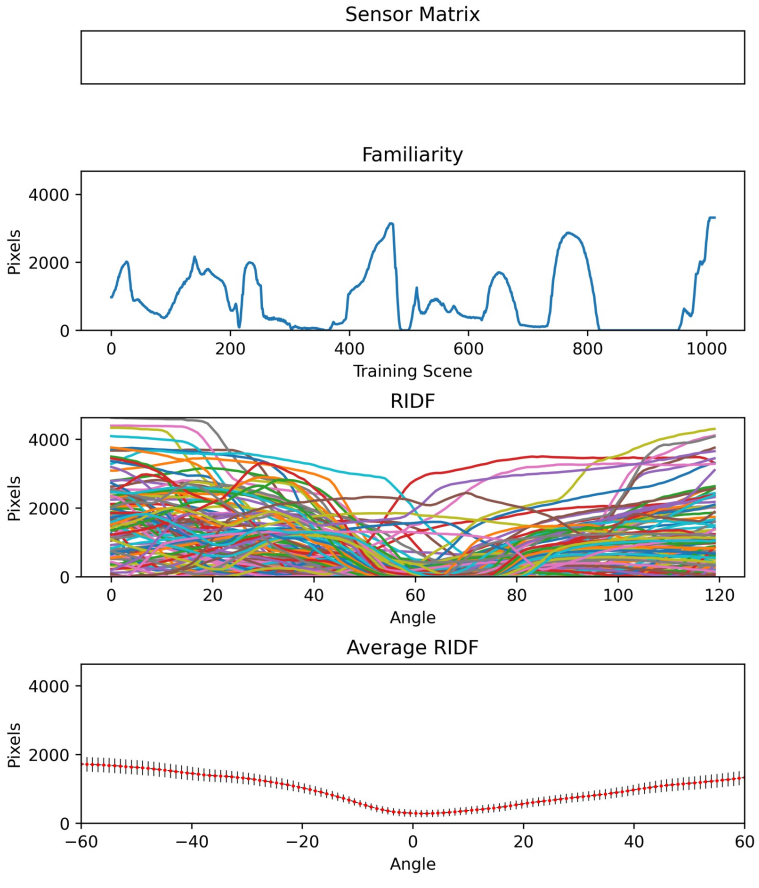


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 12364.95; RMSD/dist: 30.912; TD: 985; p90: 50; p50: 24; complete: 0

0%

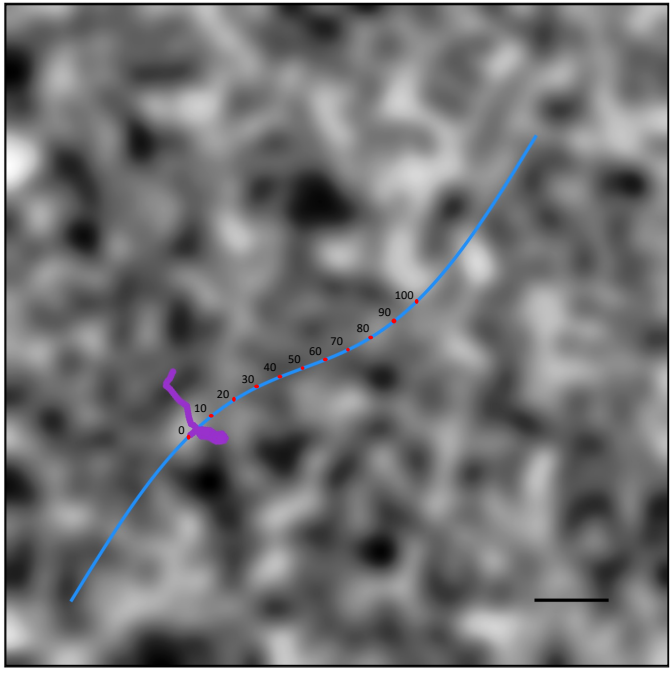


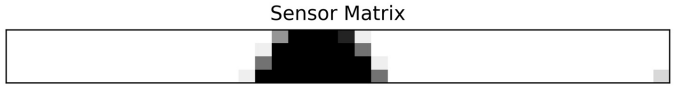


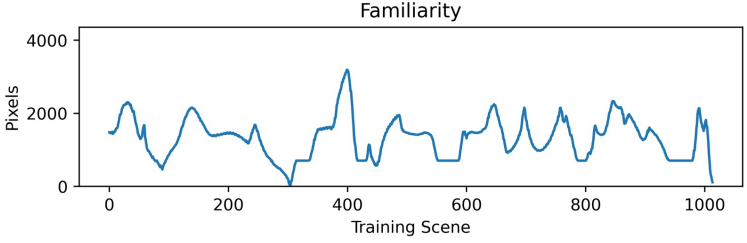
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

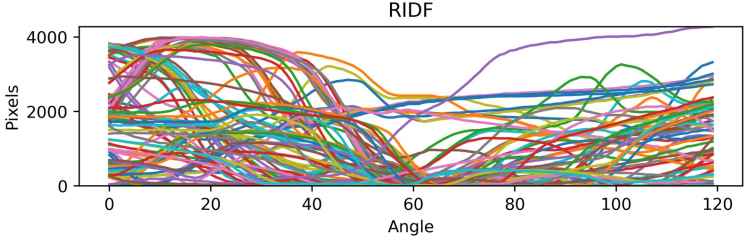
Navigation stats: RMSD error: 4432.54; RMSD/dist: 11.081; TD: 987; p90: 50; p50: 28; complete: 0

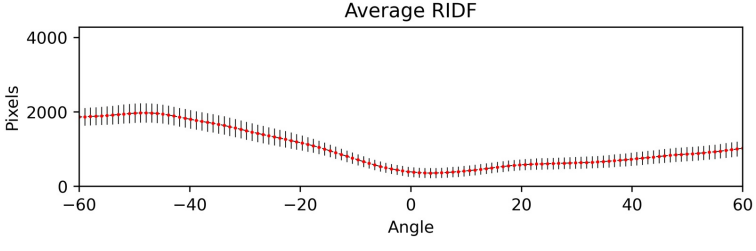
0%







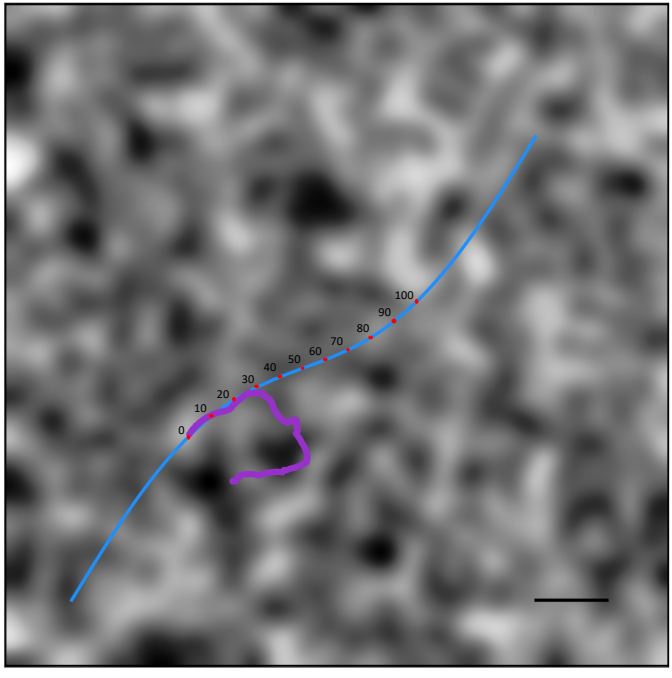


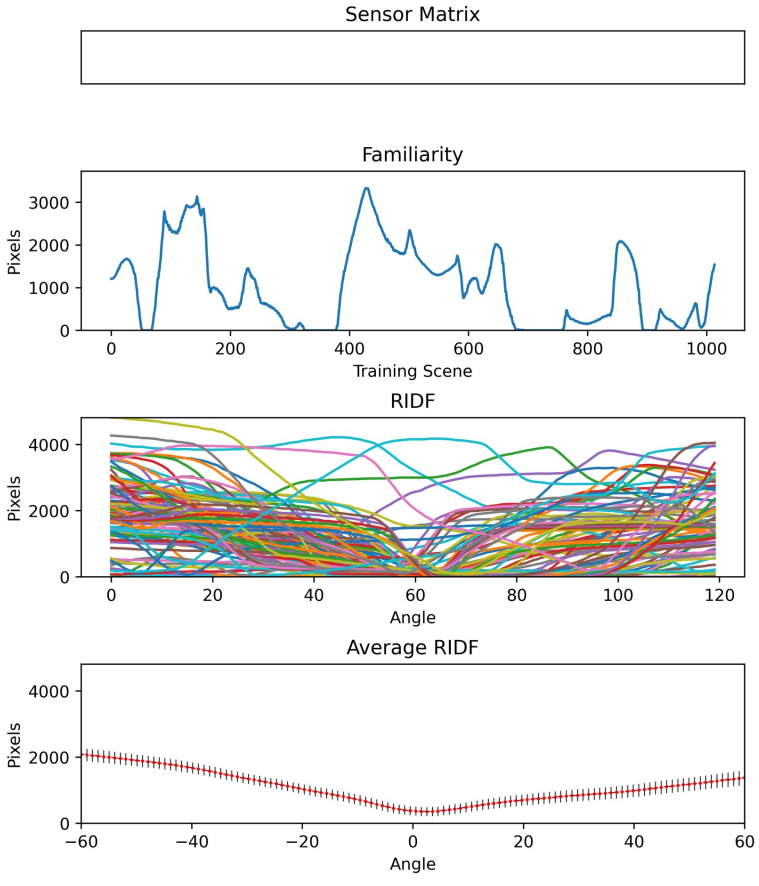


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2869.33; RMSD/dist: 7.173; TD: 786; p90: 34; p50: 22; complete: 0

0%

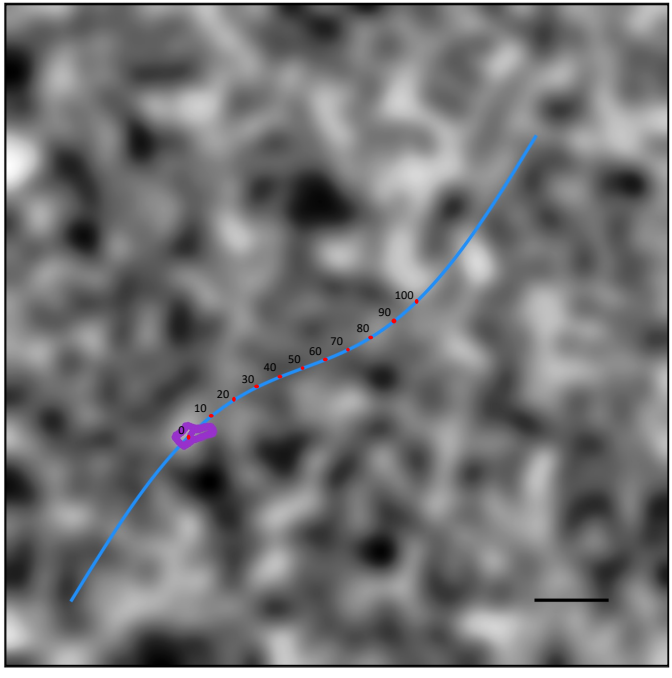


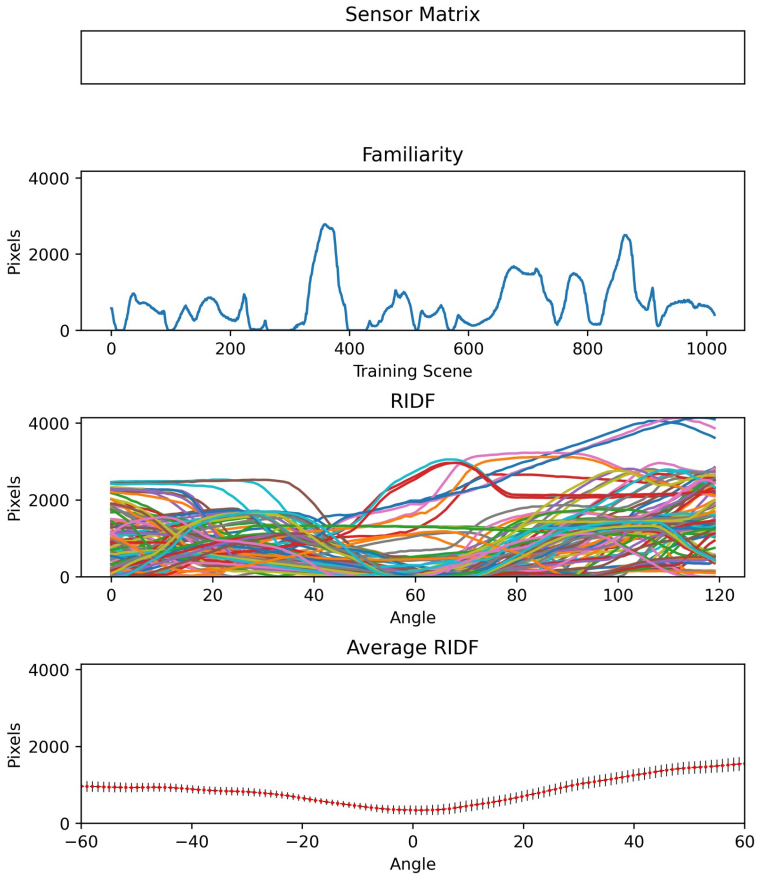


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 6314.87; RMSD/dist: 15.787; TD: 1002; p90: 54; p50: 28; complete: 0

0%

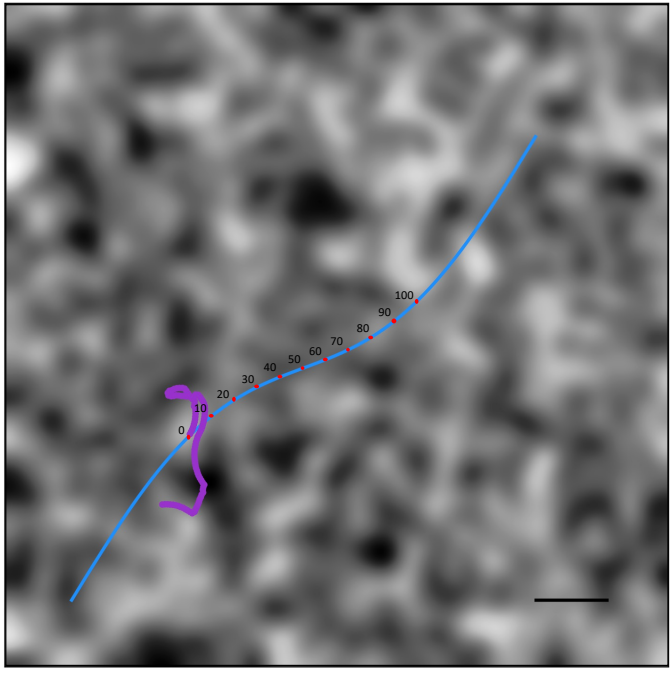


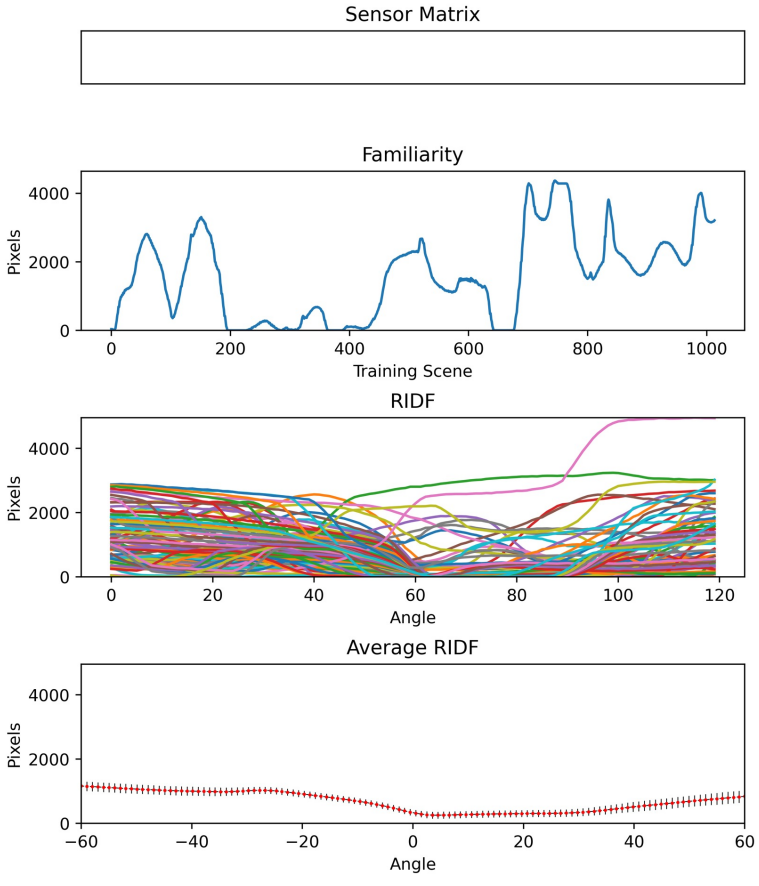


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 977.35; RMSD/dist: 2.443; TD: 655; p90: 88; p50: 42; complete: 0

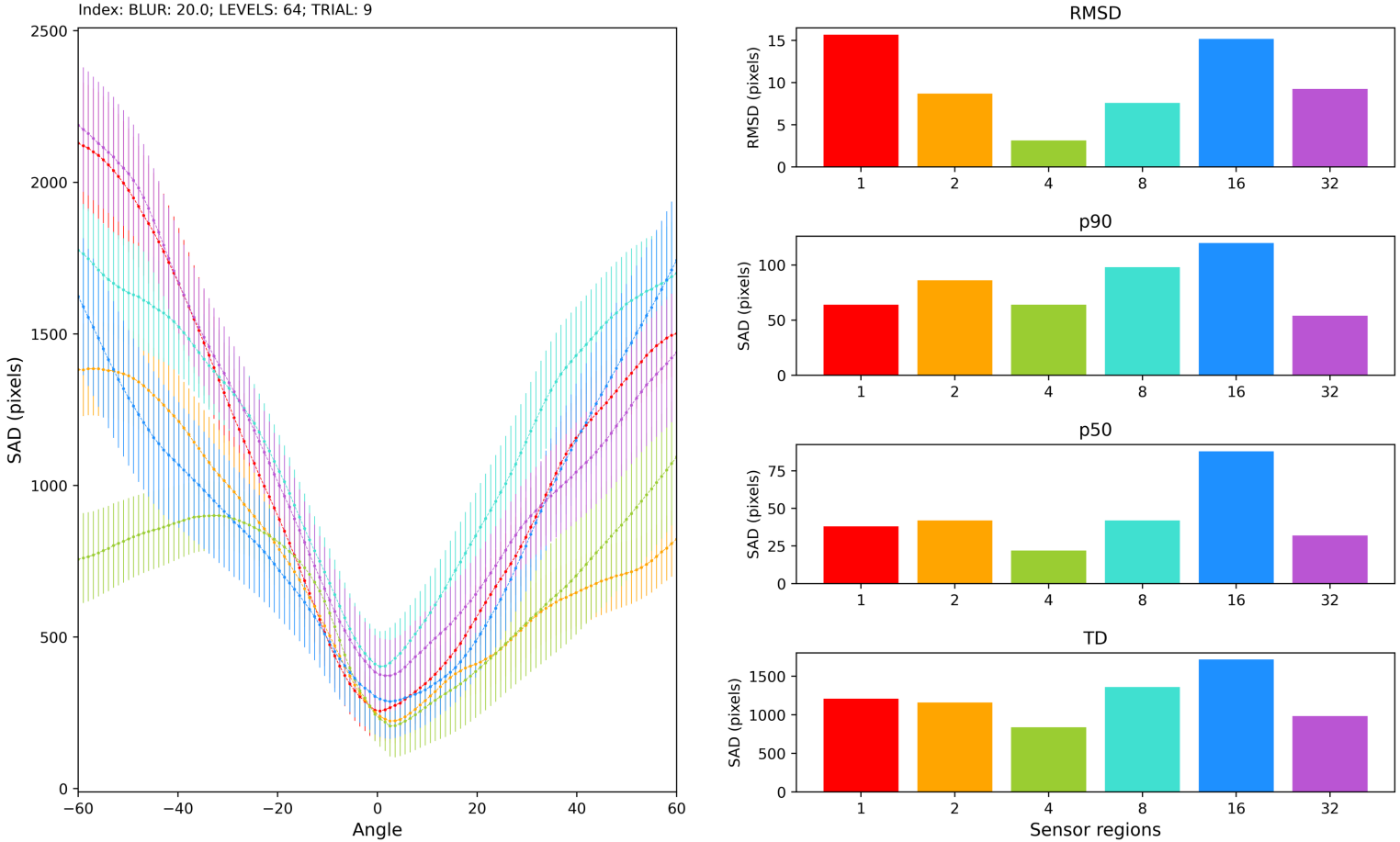
0%



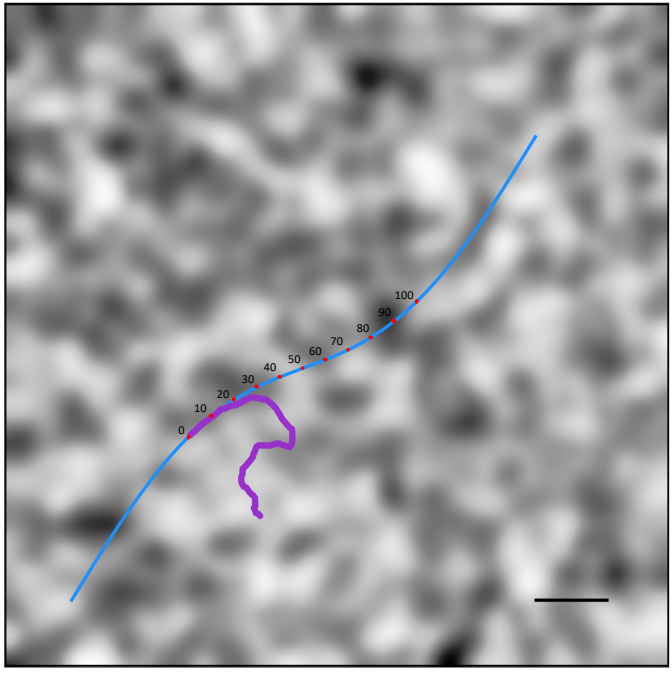


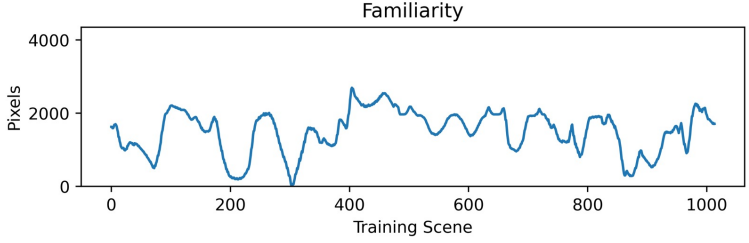
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

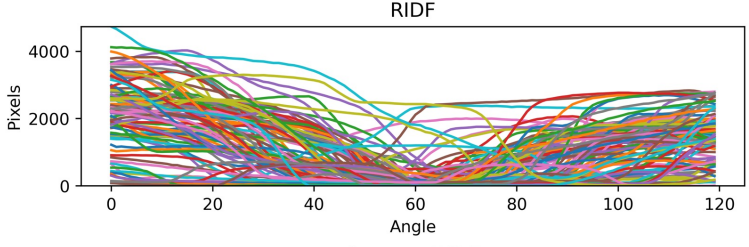
Navigation stats: RMSD error: 4088.74; RMSD/dist: 10.222; TD: 1242; p90: 120; p50: 36; complete: 0

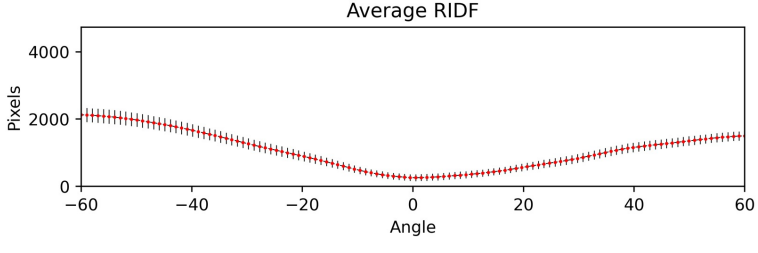

Index: BLUR: 20.0; LEVELS: 64; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%





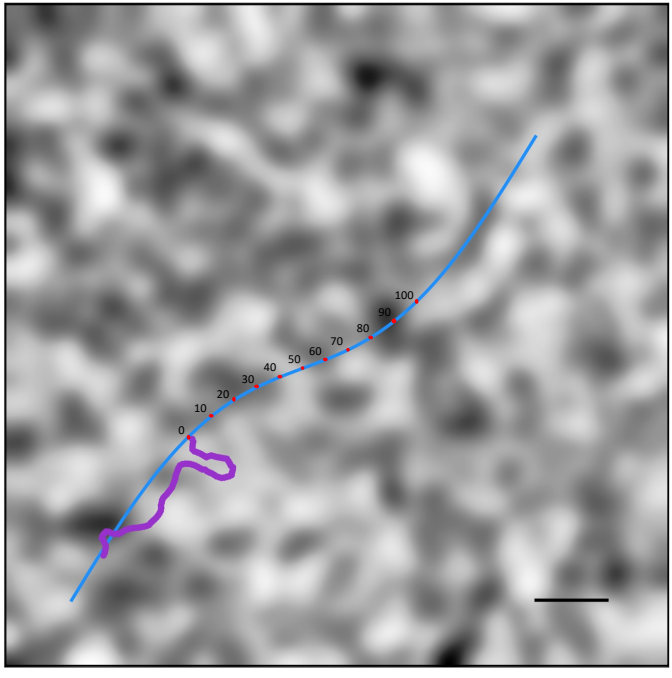


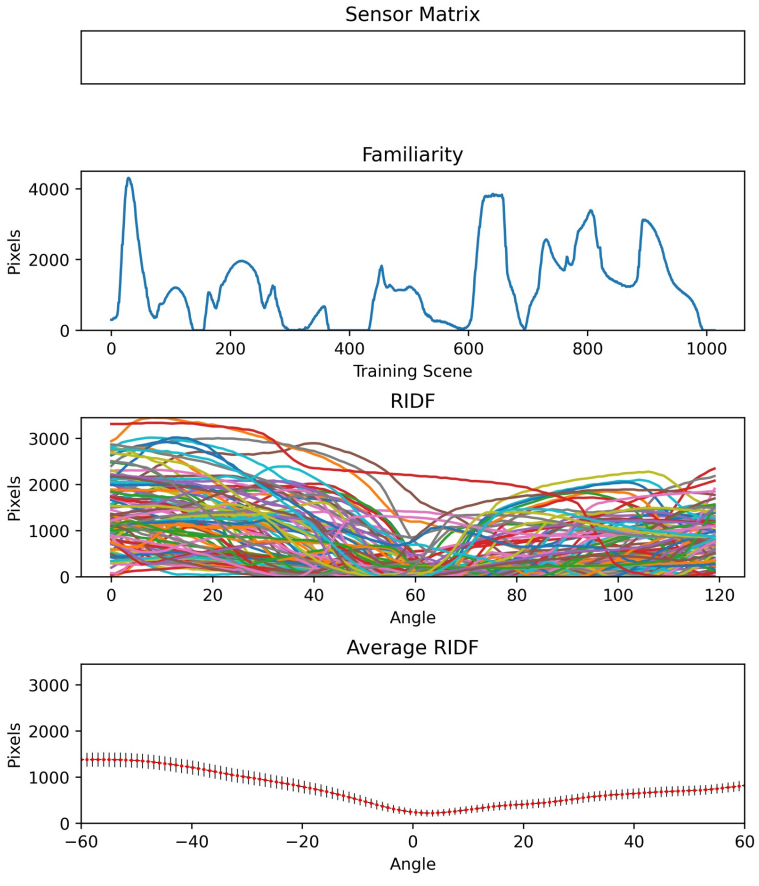


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 6276.92; RMSD/dist: 15.692; TD: 1209; p90: 64; p50: 38; complete: 0

0%

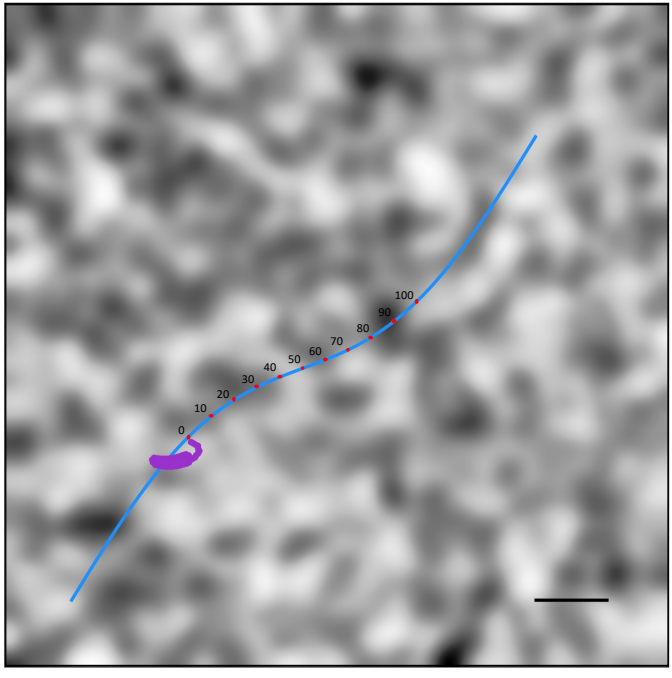


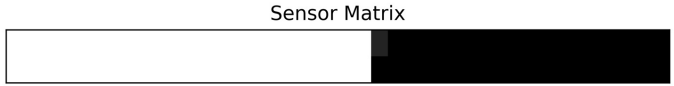


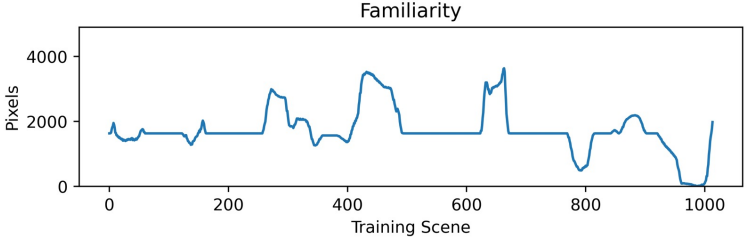
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

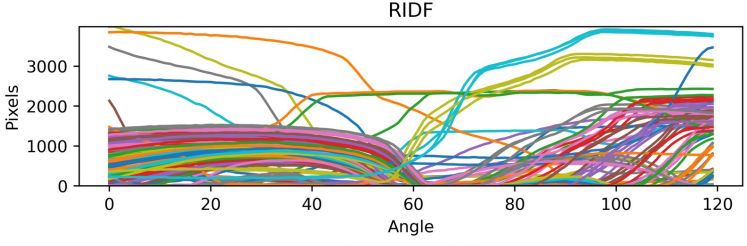
Navigation stats: RMSD error: 3480.66; RMSD/dist: 8.702; TD: 1158; p90: 86; p50: 42; complete: 0

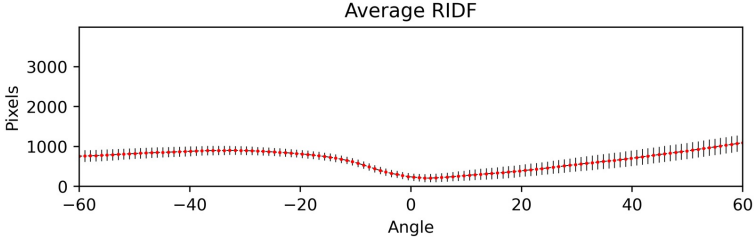
0%







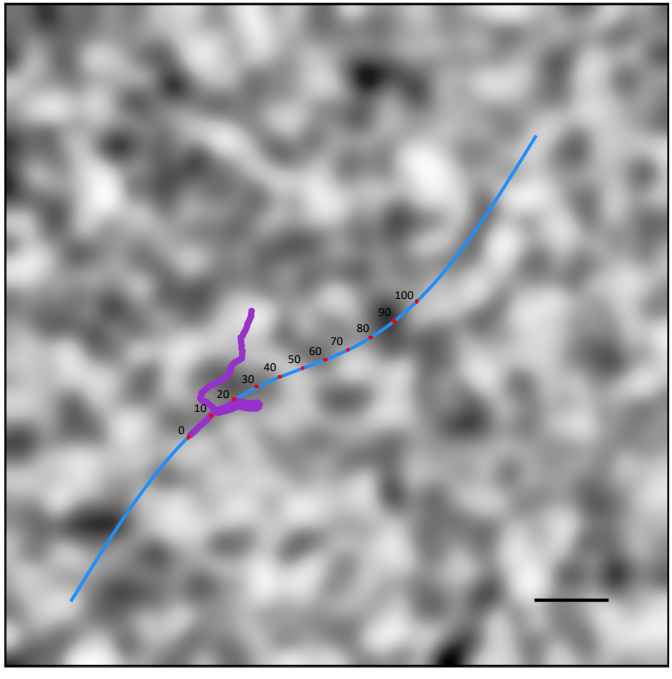


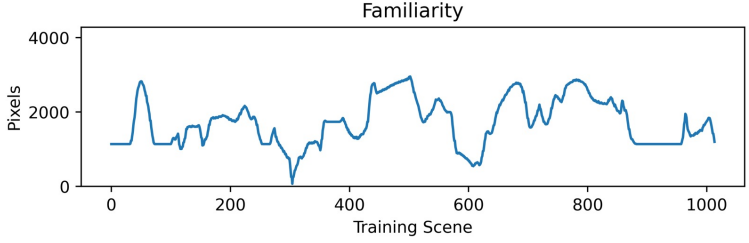


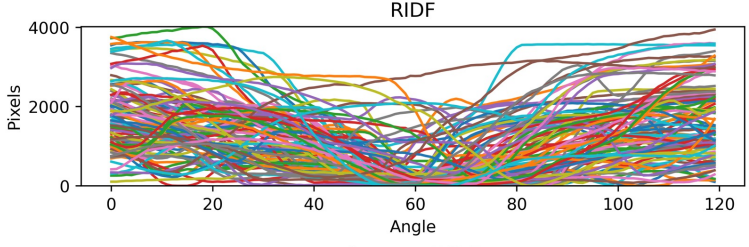
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

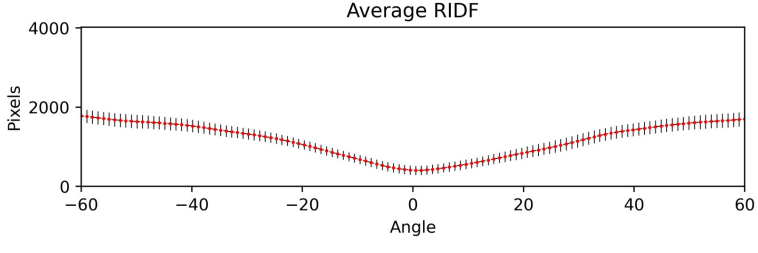
Navigation stats: RMSD error: 1254.50; RMSD/dist: 3.136; TD: 837; p90: 64; p50: 22; complete: 0

10%





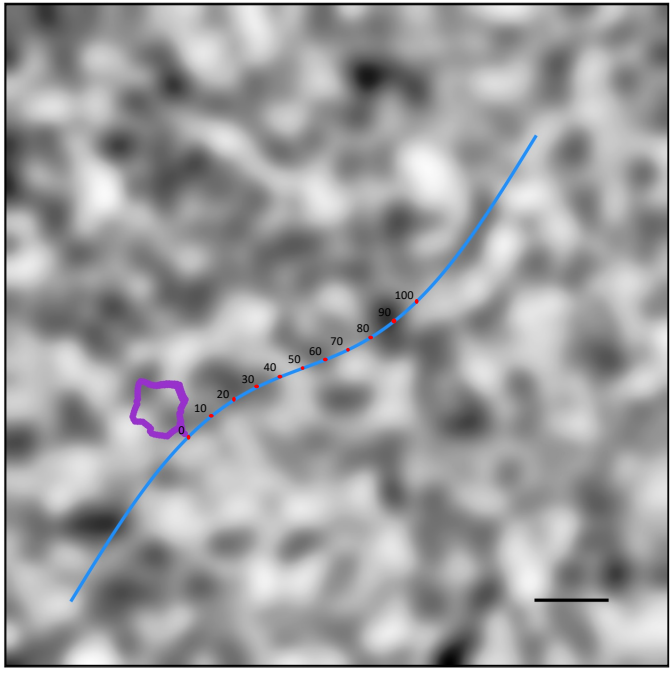


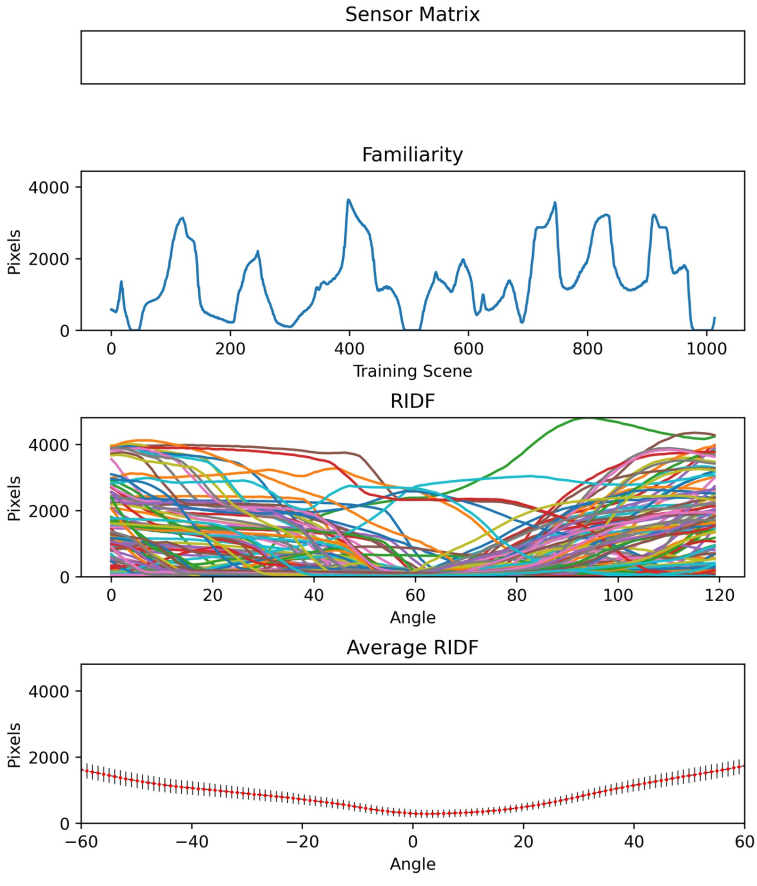


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3038.67; RMSD/dist: 7.597; TD: 1361; p90: 98; p50: 42; complete: 0

0%

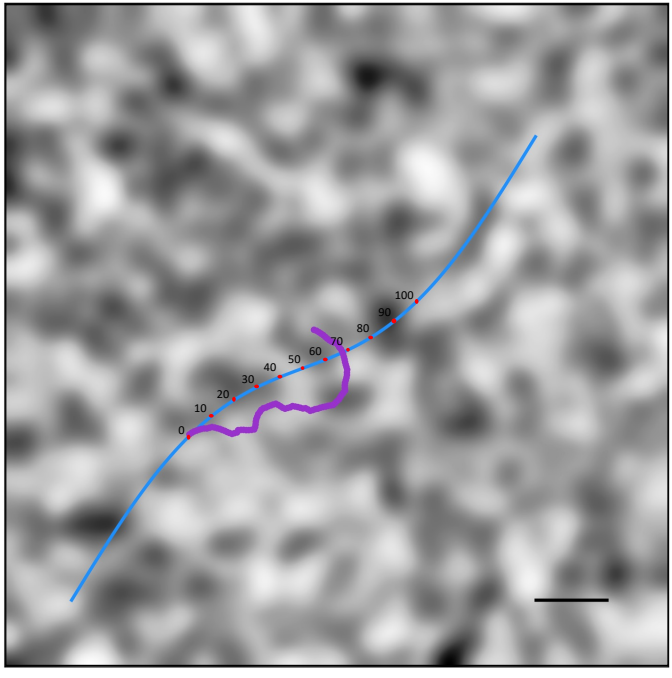


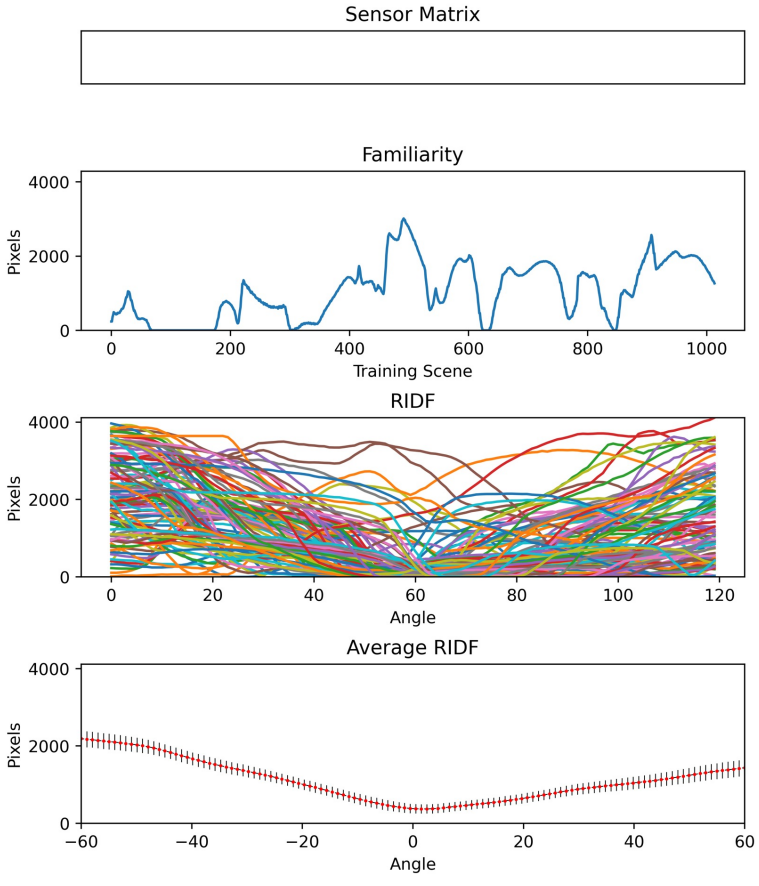


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 6072.96; RMSD/dist: 15.182; TD: 1716; p90: 120; p50: 88; complete: 0

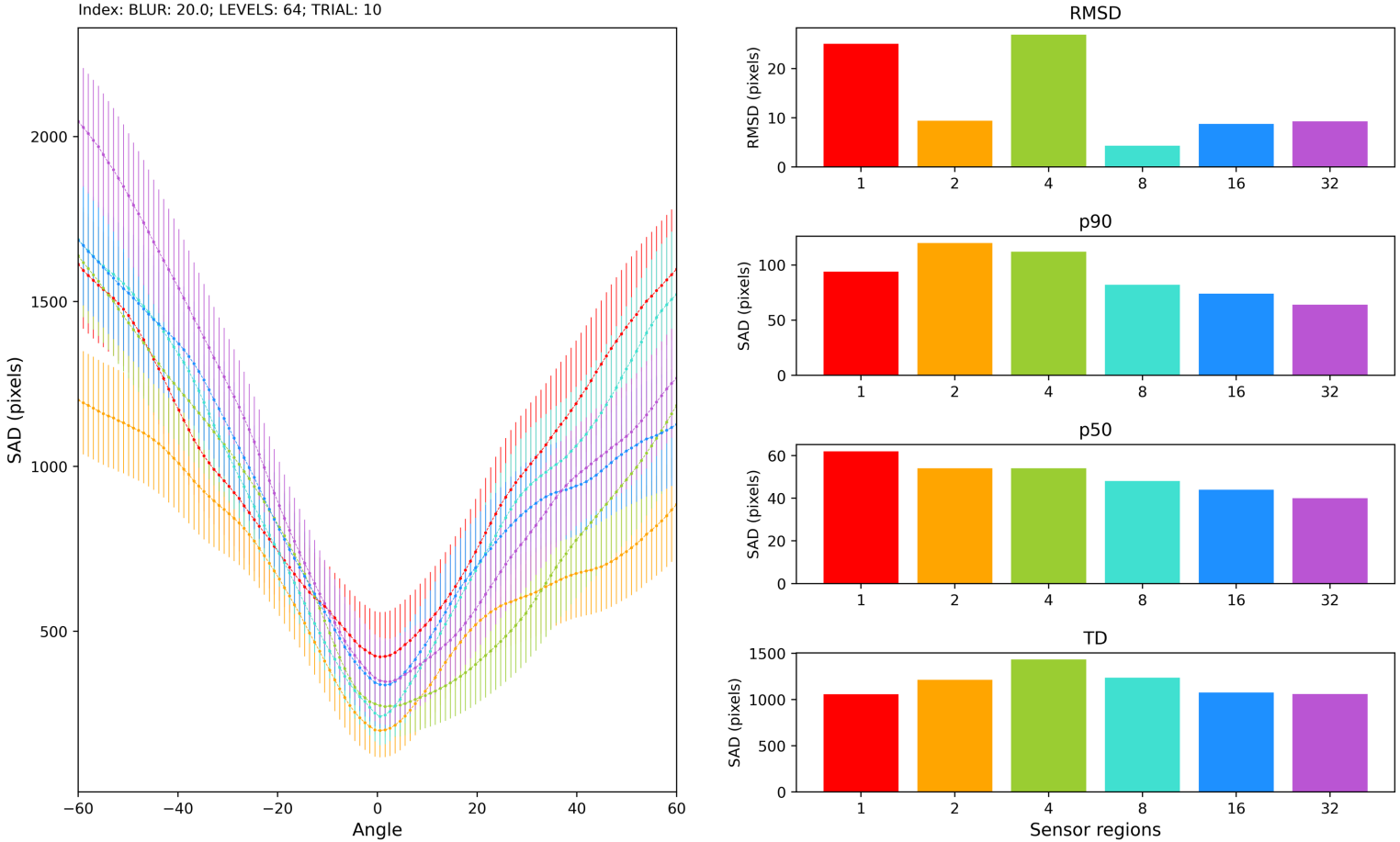
0%



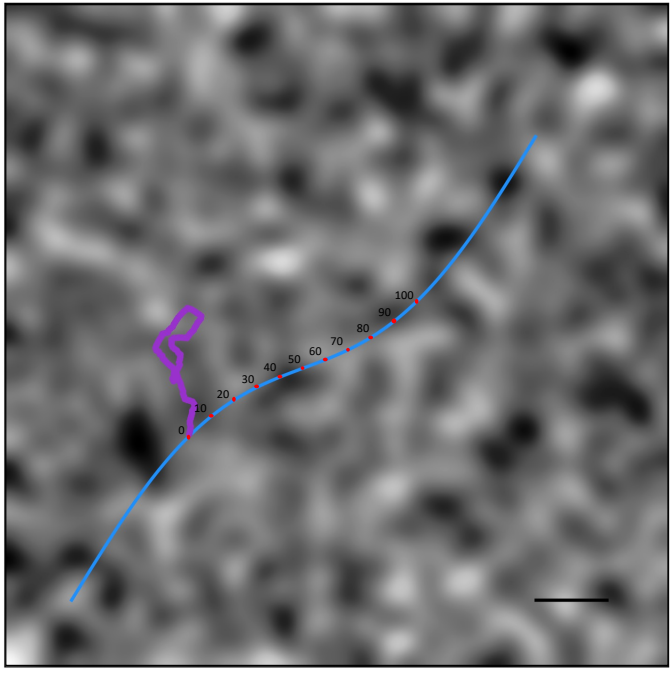


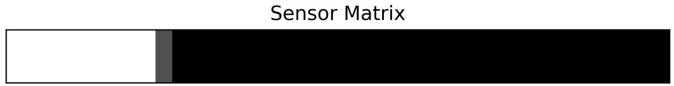
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

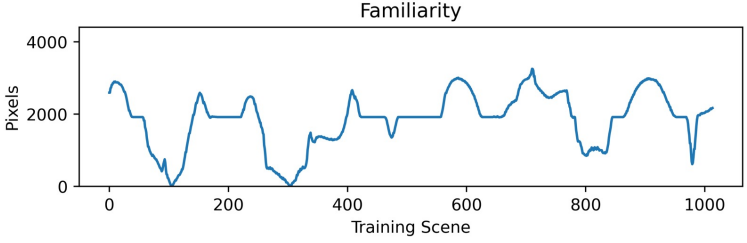
Navigation stats: RMSD error: 3698.80; RMSD/dist: 9.247; TD: 983; p90: 54; p50: 32; complete: 0

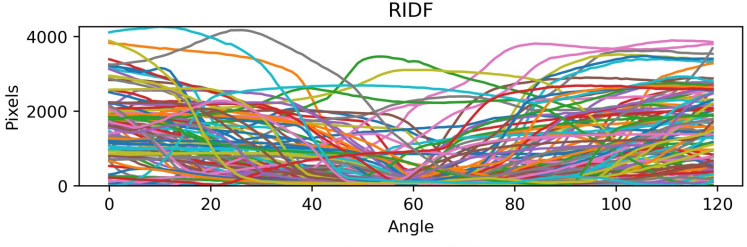

Index: BLUR: 20.0; LEVELS: 64; TRIAL: 10
SAD (pixels)
2000
1500
1000
500
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
60
40
20
TD
1500
1000
500
Sensor regions

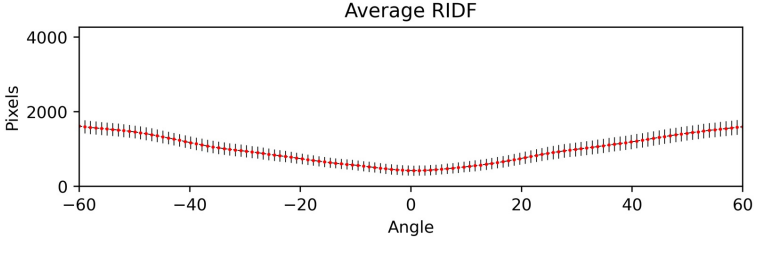
0%







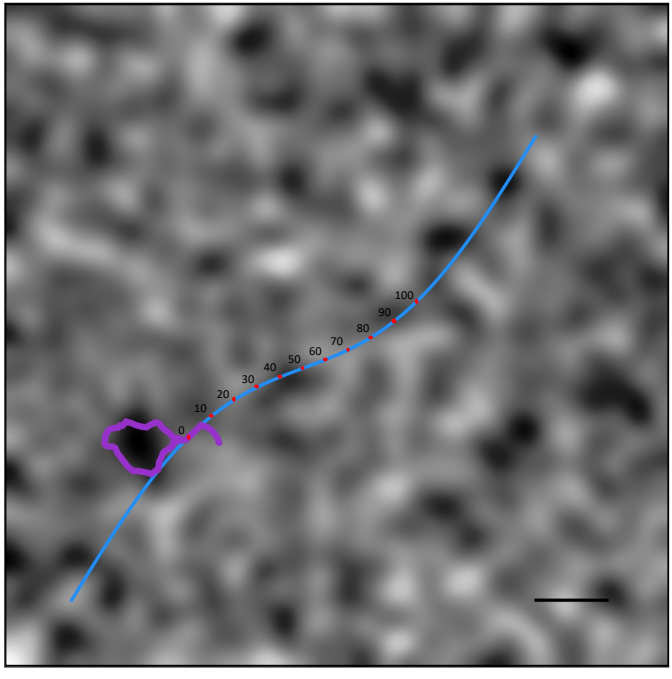


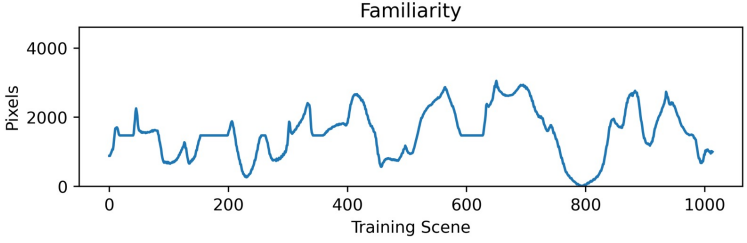


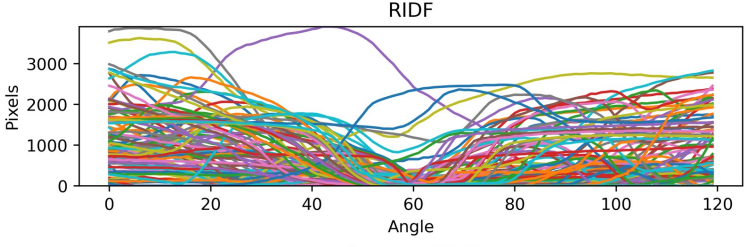
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

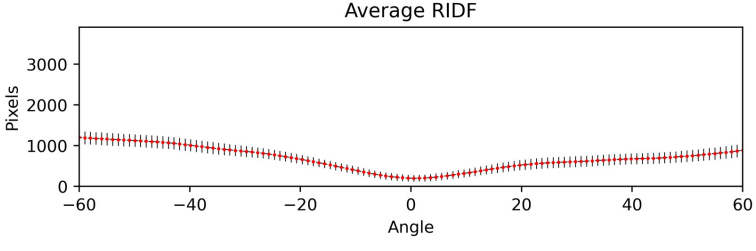
Navigation stats: RMSD error: 10005.91; RMSD/dist: 25.015; TD: 1058; p90: 94; p50: 62; complete: 0

0%





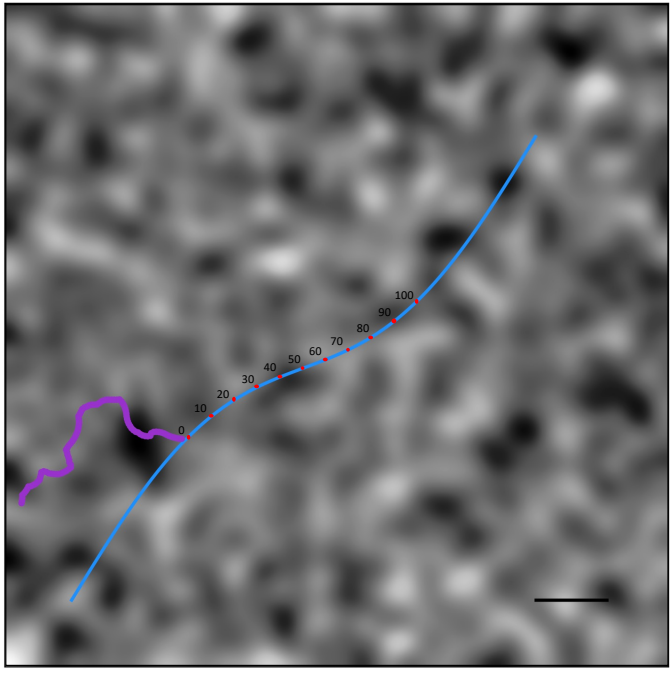


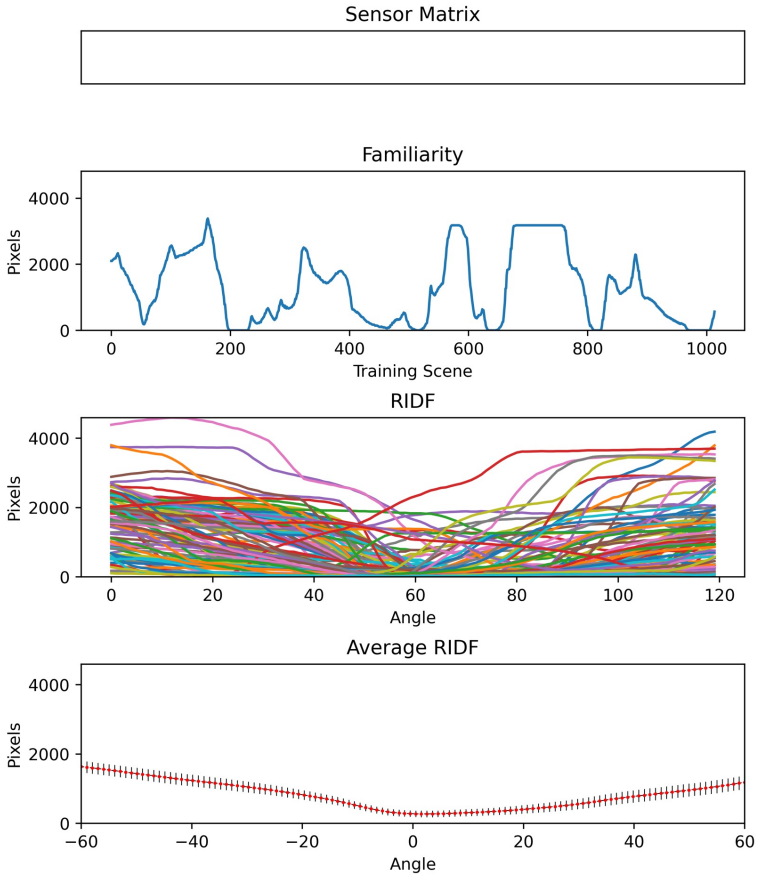


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3750.93; RMSD/dist: 9.377; TD: 1214; p90: 120; p50: 54; complete: 0

0%

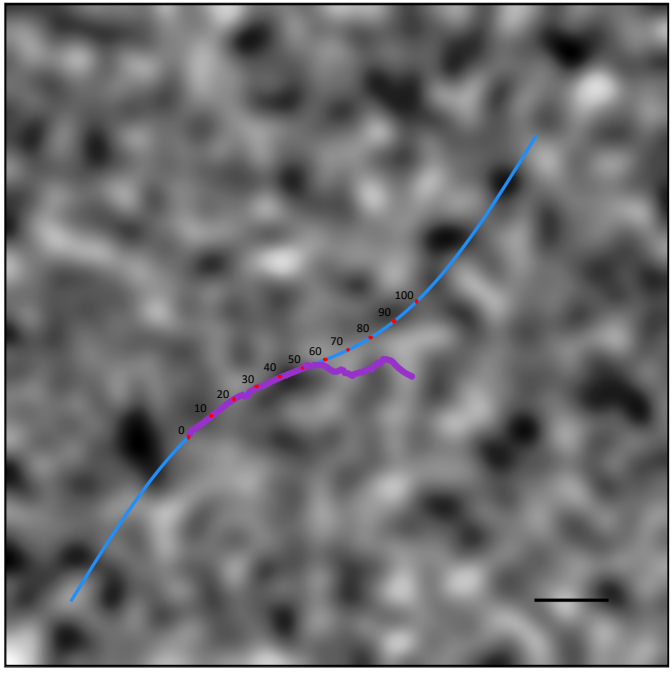


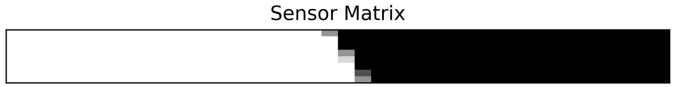


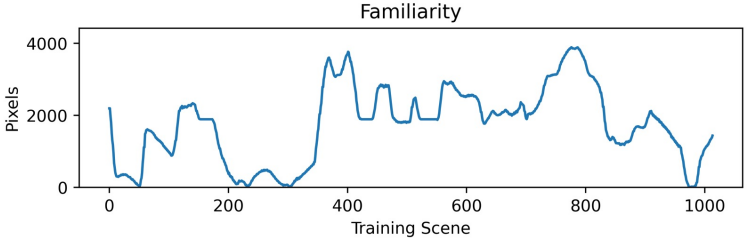
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

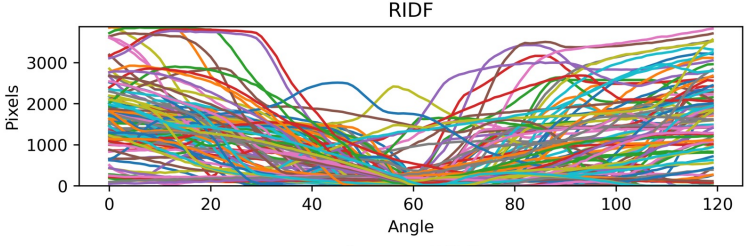
Navigation stats: RMSD error: 10758.92; RMSD/dist: 26.897; TD: 1433; p90: 112; p50: 54; complete: 0

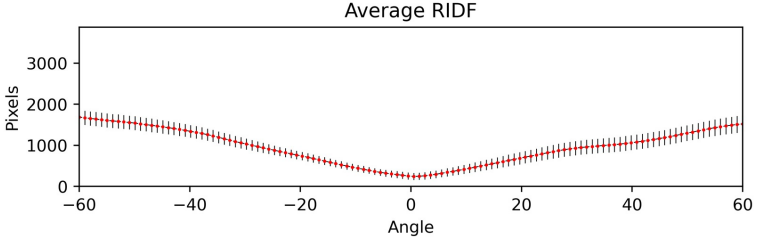
40%







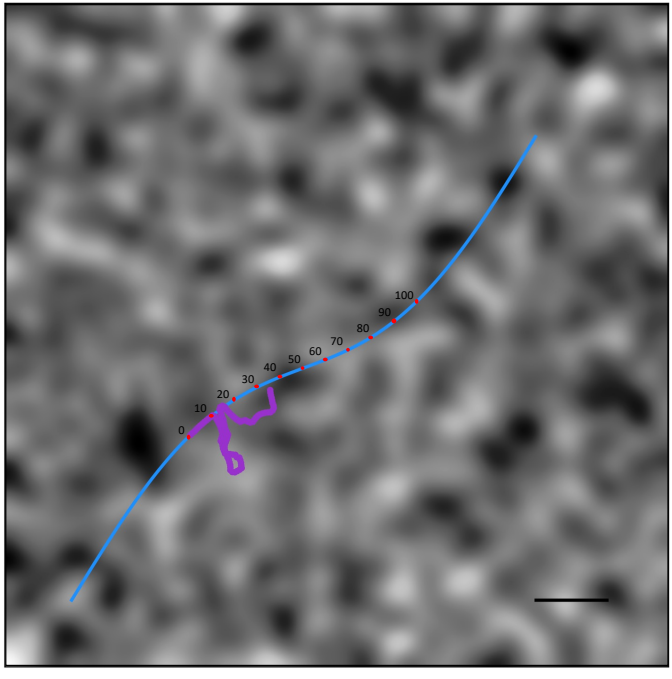


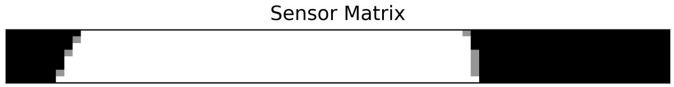


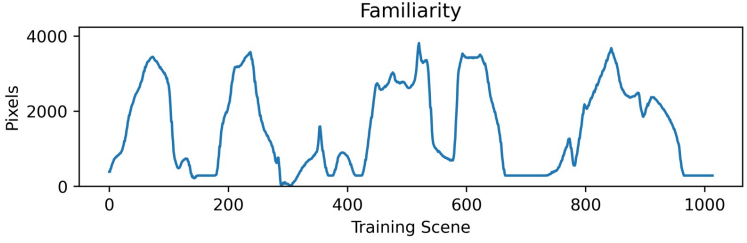
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

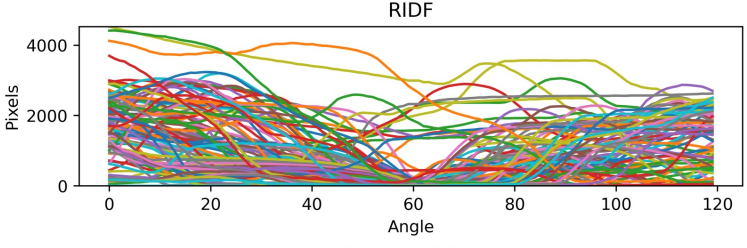
Navigation stats: RMSD error: 1714.20; RMSD/dist: 4.285; TD: 1236; p90: 82; p50: 48; complete: 0

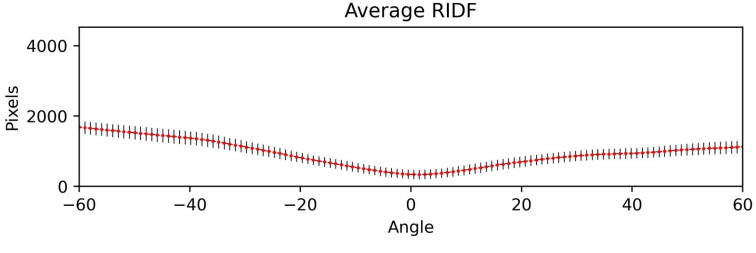
10%







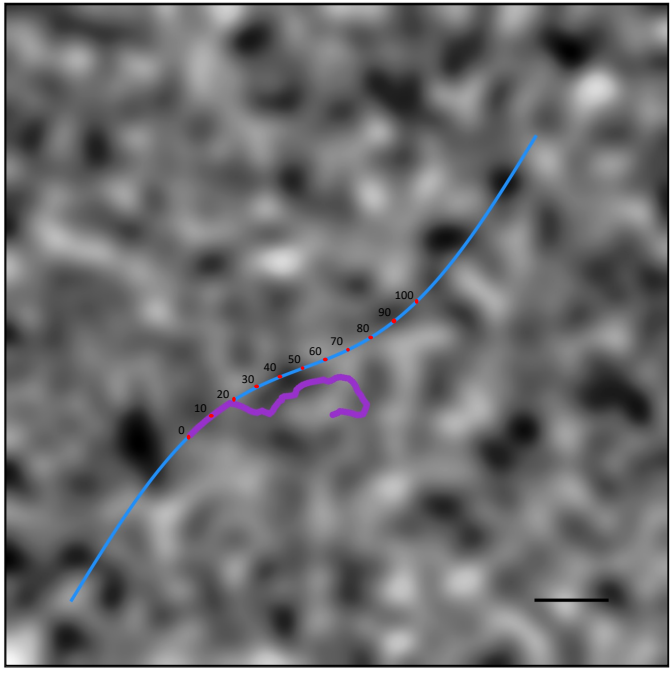


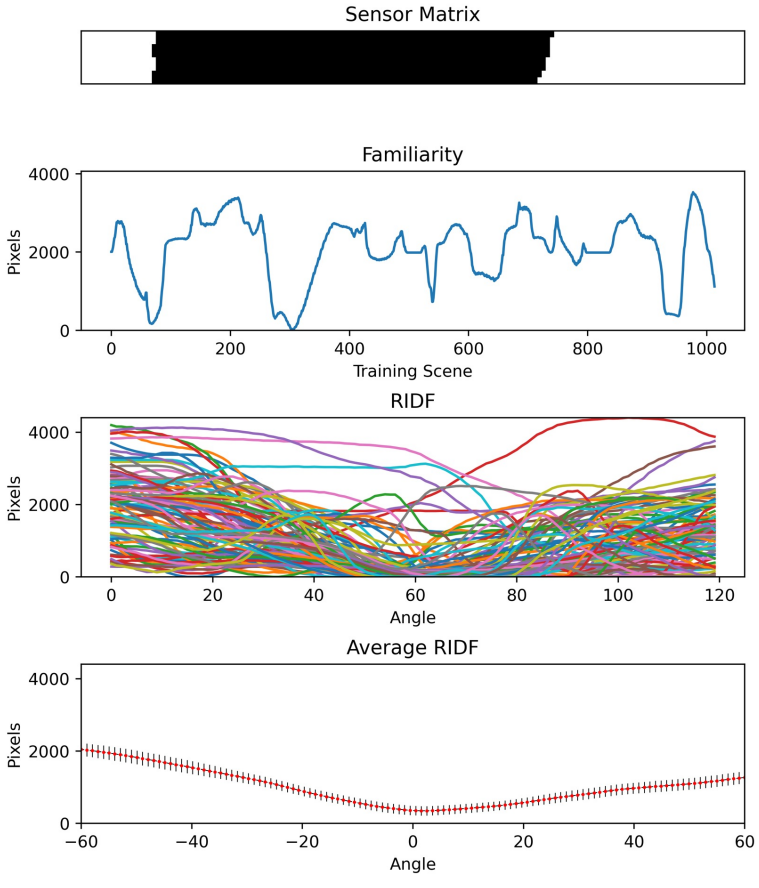


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3491.41; RMSD/dist: 8.729; TD: 1077; p90: 74; p50: 44; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3695.90; RMSD/dist: 9.240; TD: 1060; p90: 64; p50: 40; complete: 0