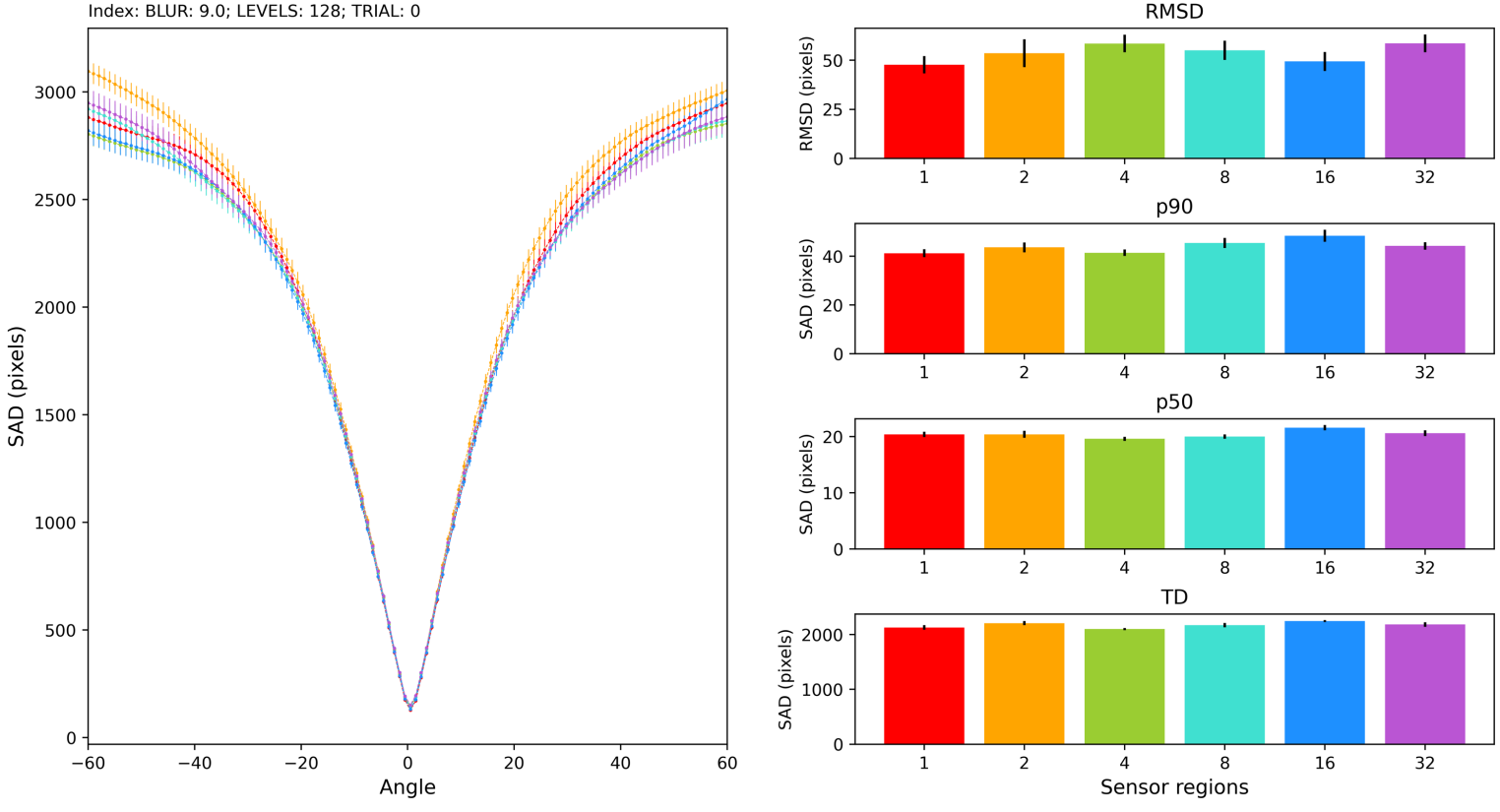
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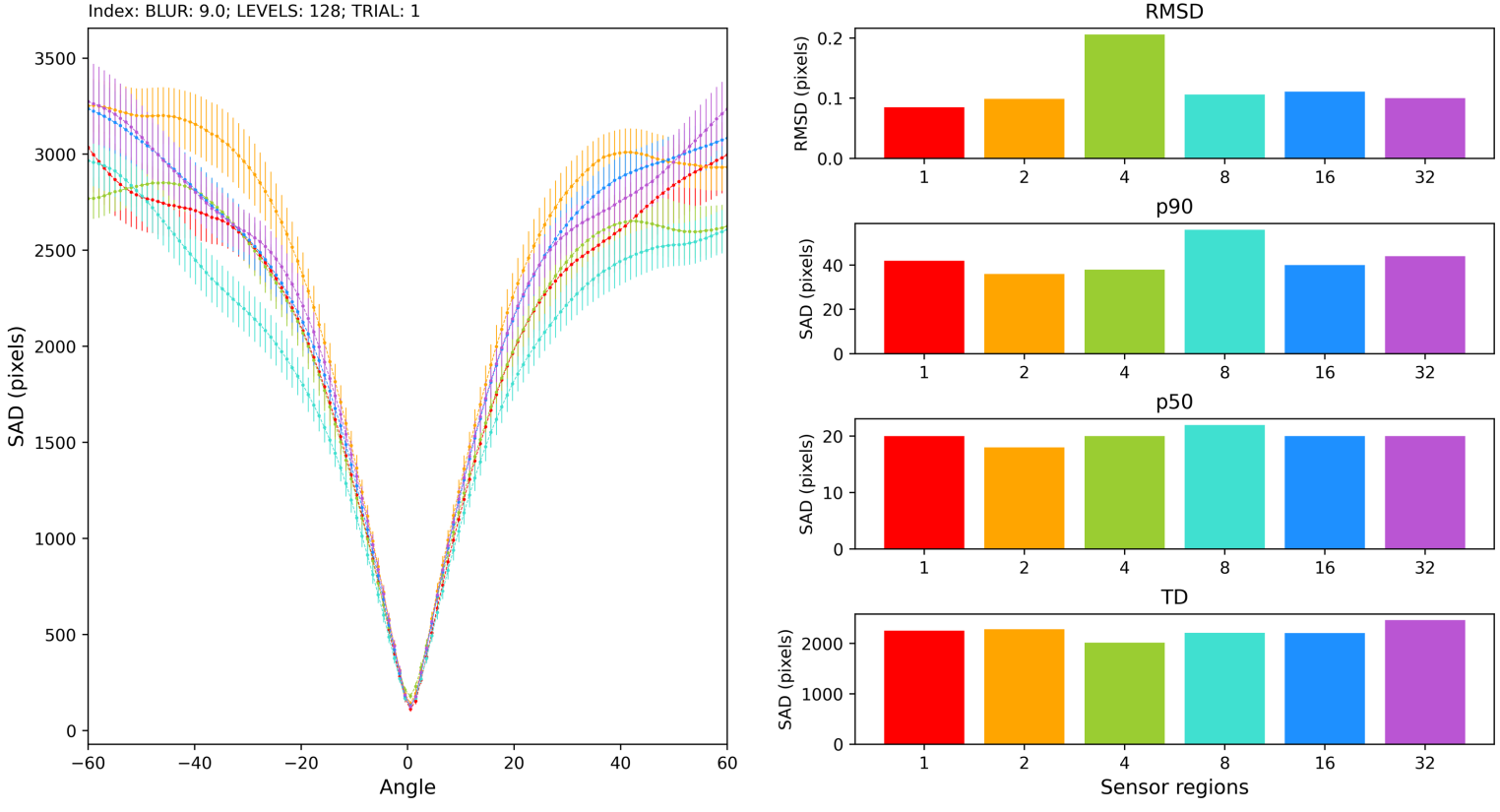
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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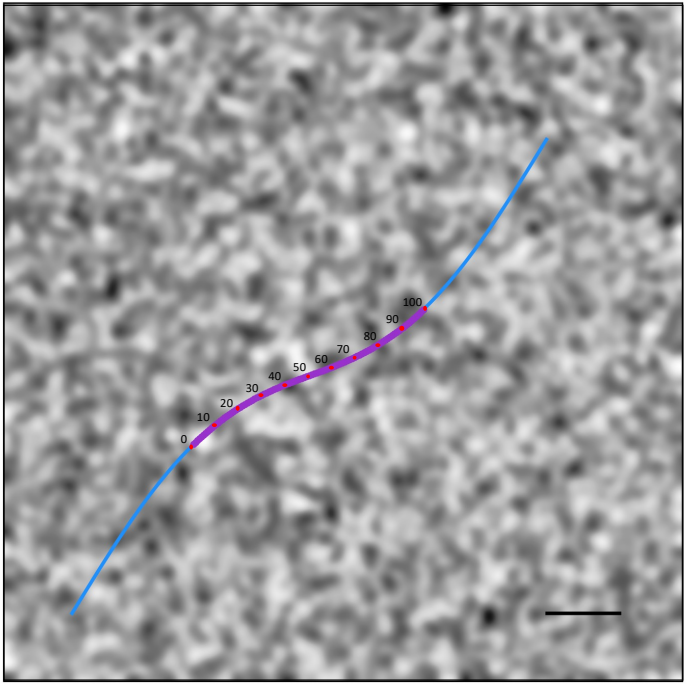
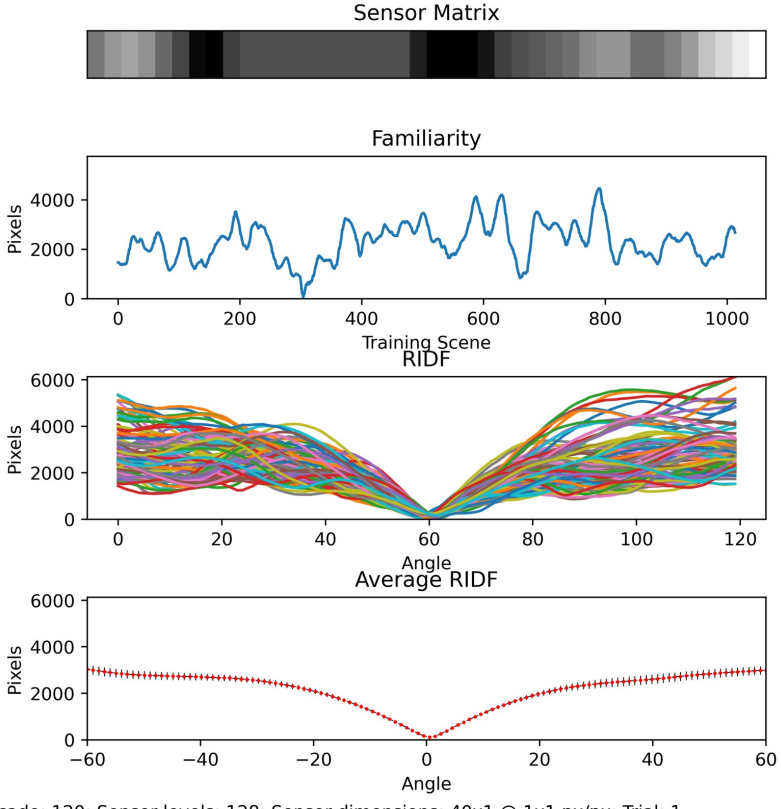
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

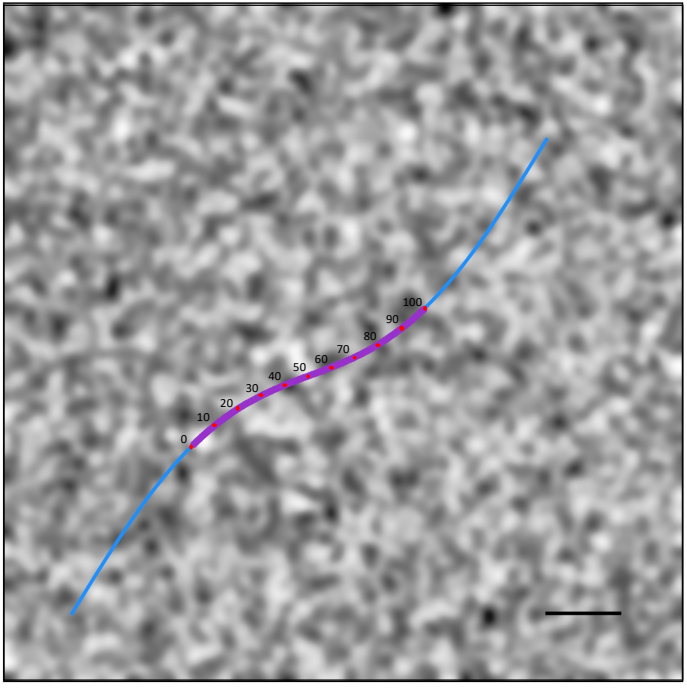
100%

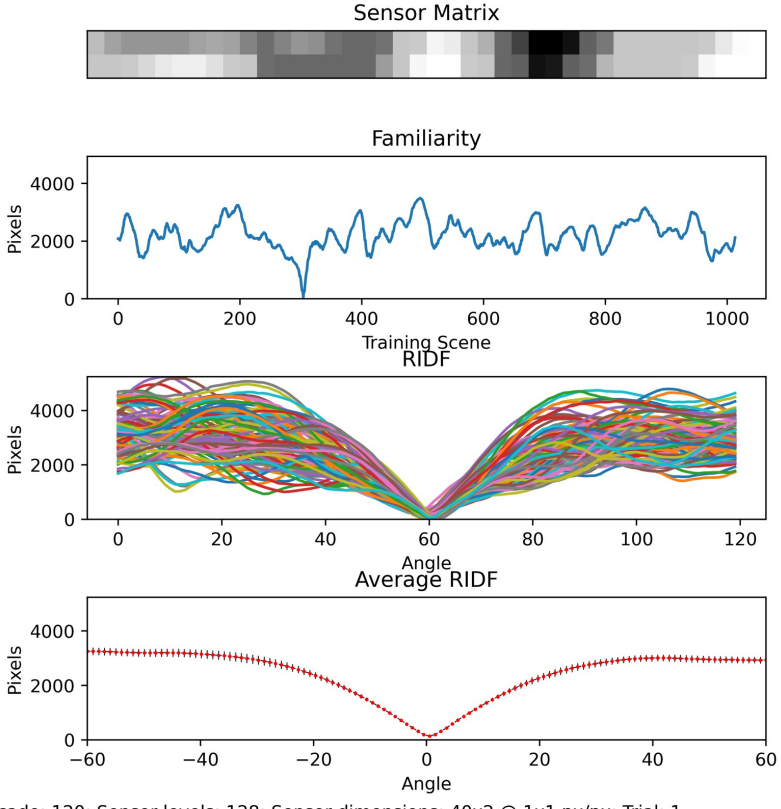



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 33.91; RMSD/dist: 0.085; TD: 2252; p90: 42; p50: 20; complete: 0

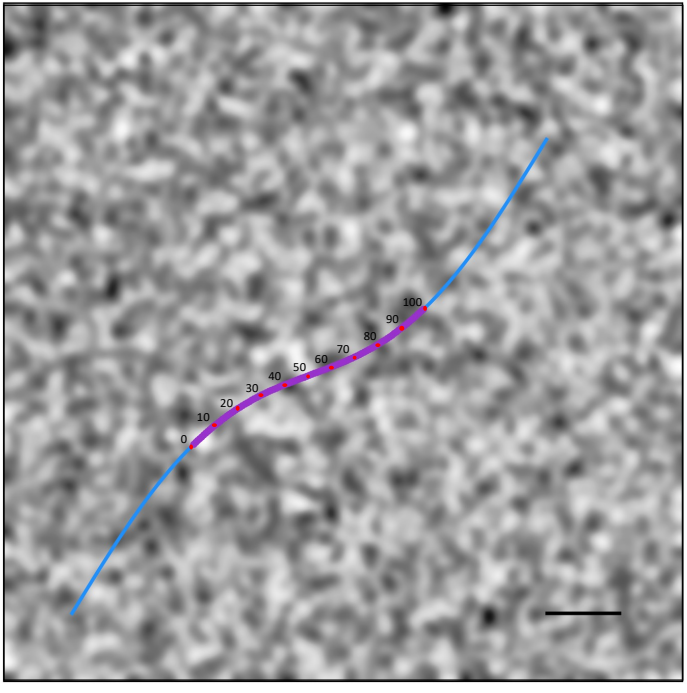
100%

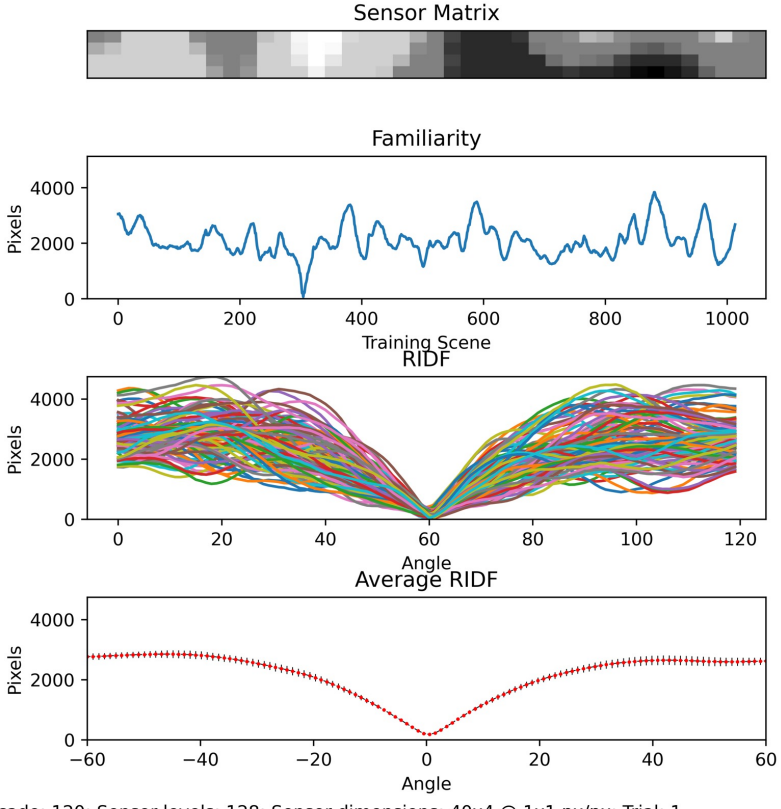



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 39.62; RMSD/dist: 0.099; TD: 2285; p90: 36; p50: 18; complete: 0

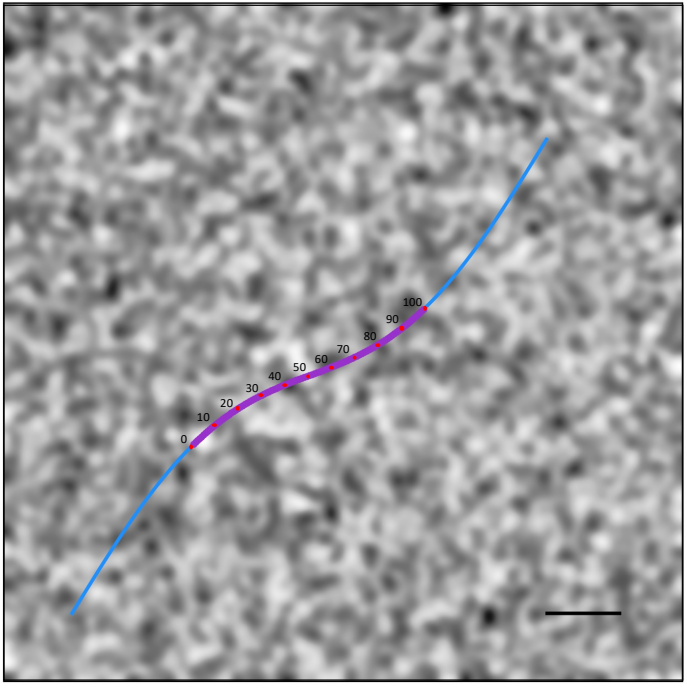
100%

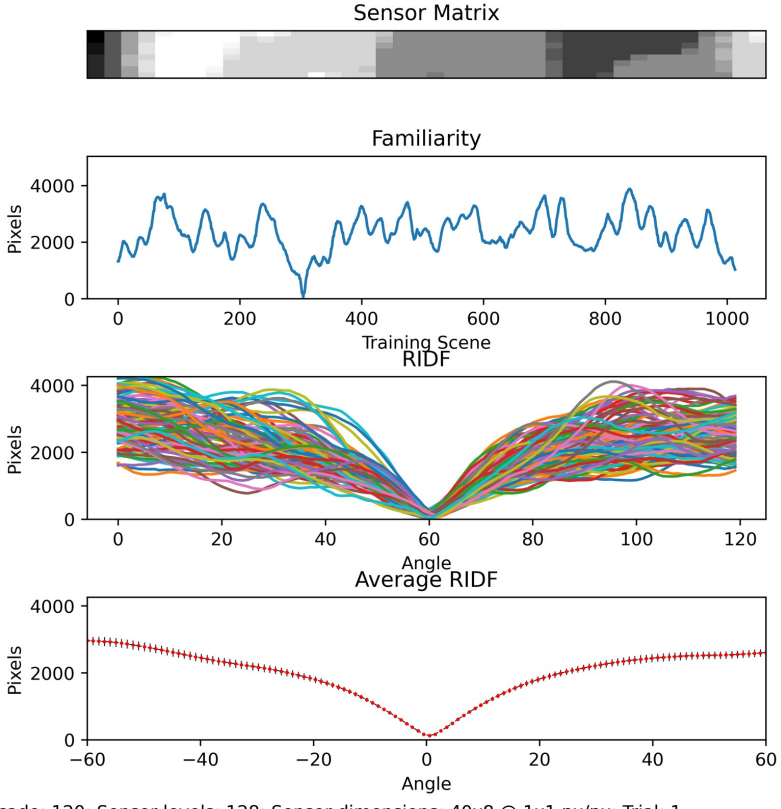



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 82.35; RMSD/dist: 0.206; TD: 2018; p90: 38; p50: 20; complete: 0

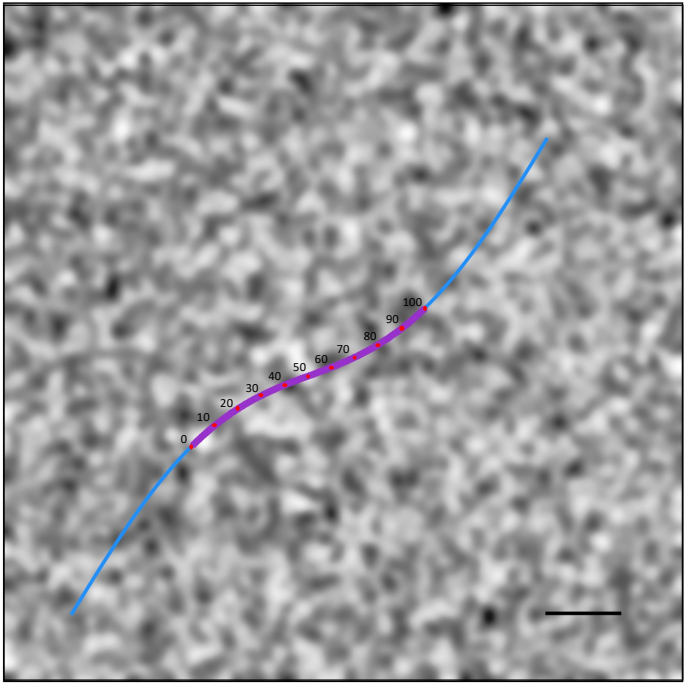
100%

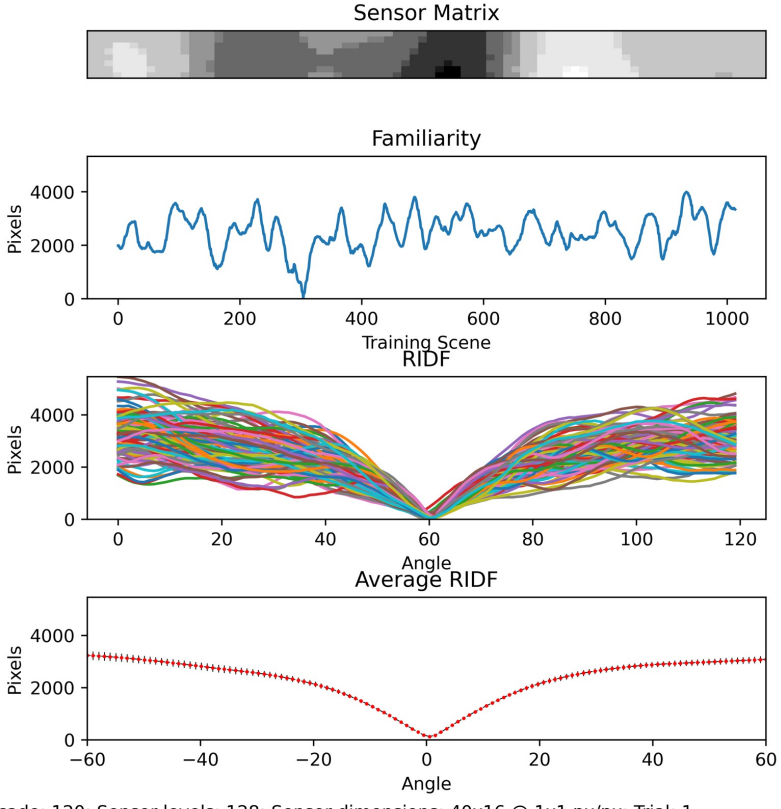



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 42.49; RMSD/dist: 0.106; TD: 2213; p90: 56; p50: 22; complete: 0

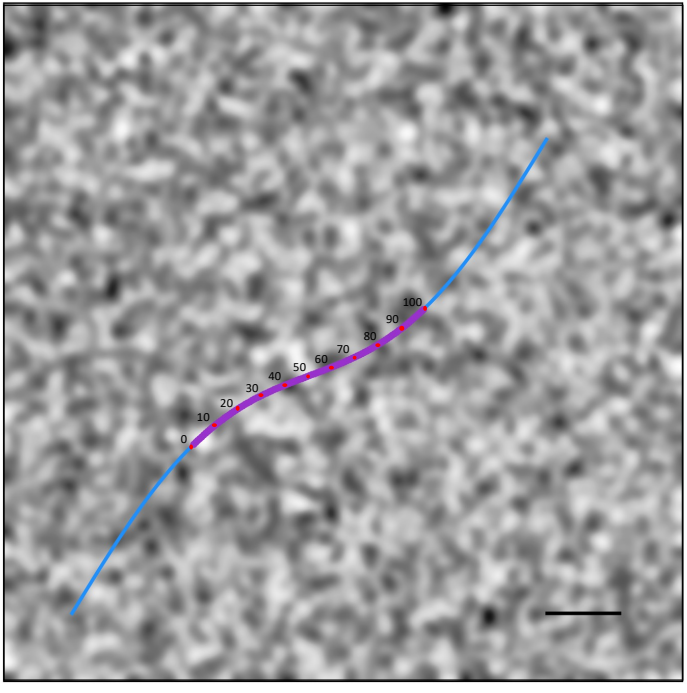
100%

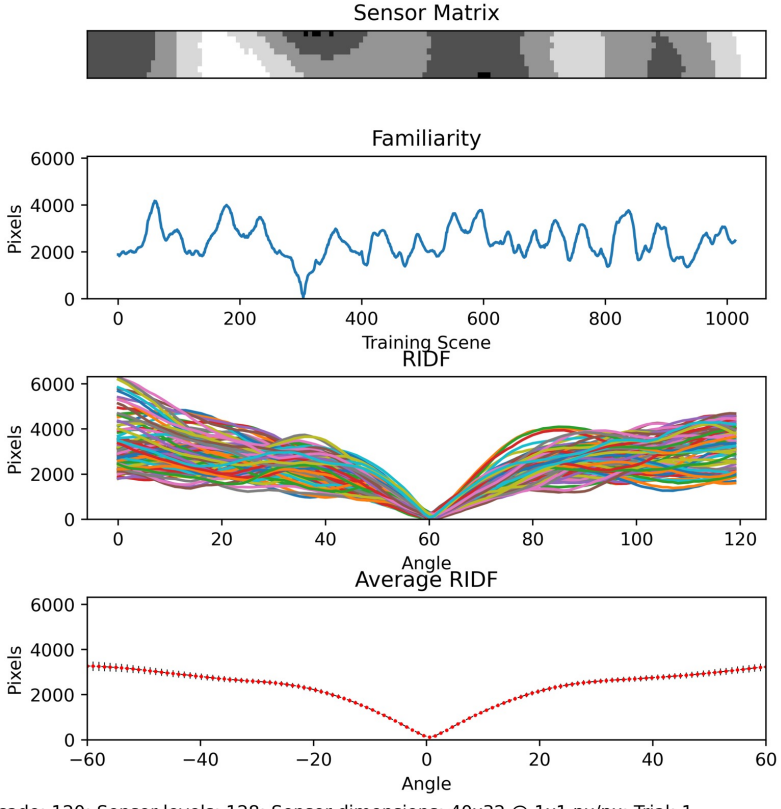


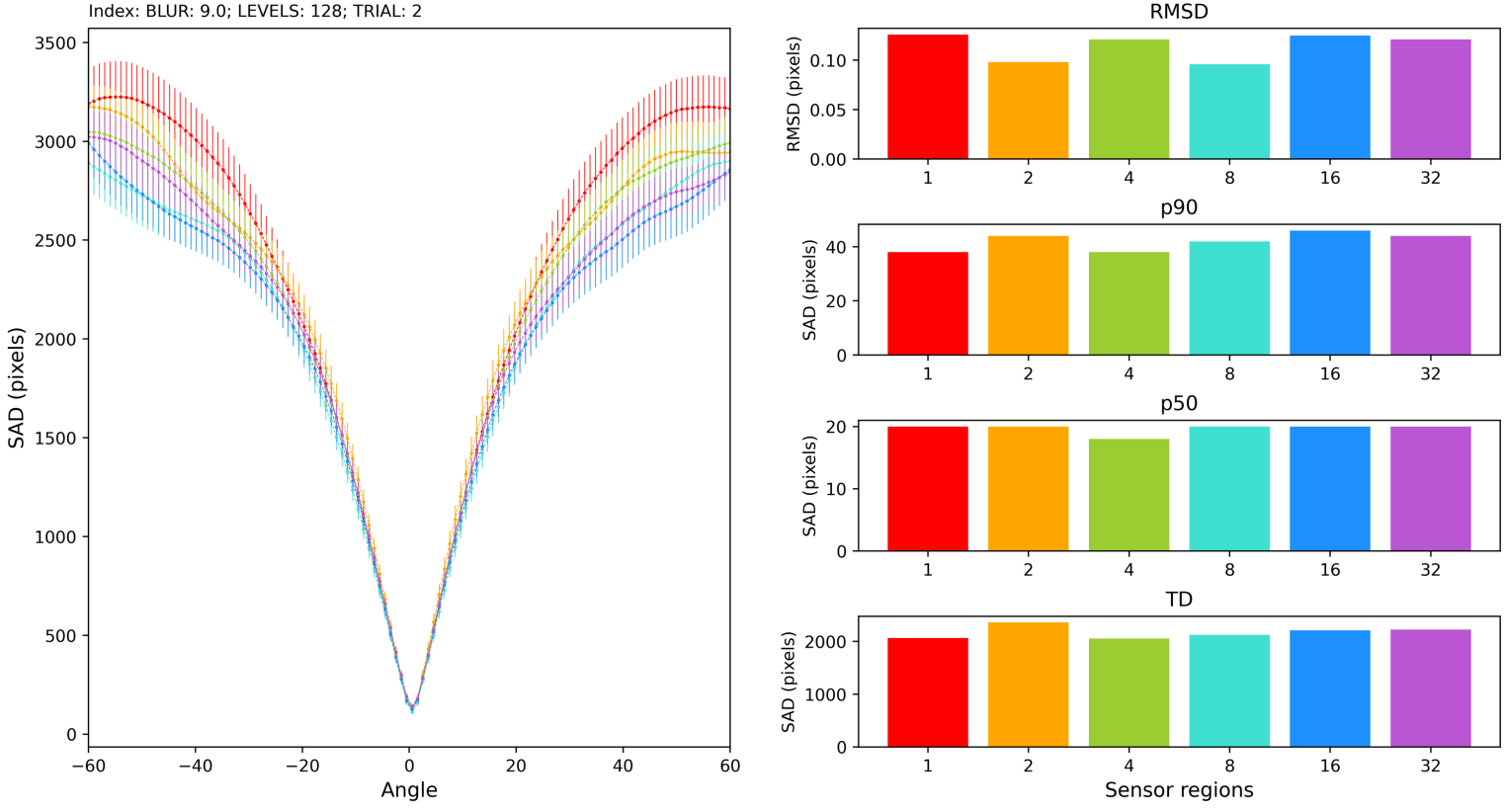

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 44.21; RMSD/dist: 0.111; TD: 2206; p90: 40; p50: 20; complete: 0

100%

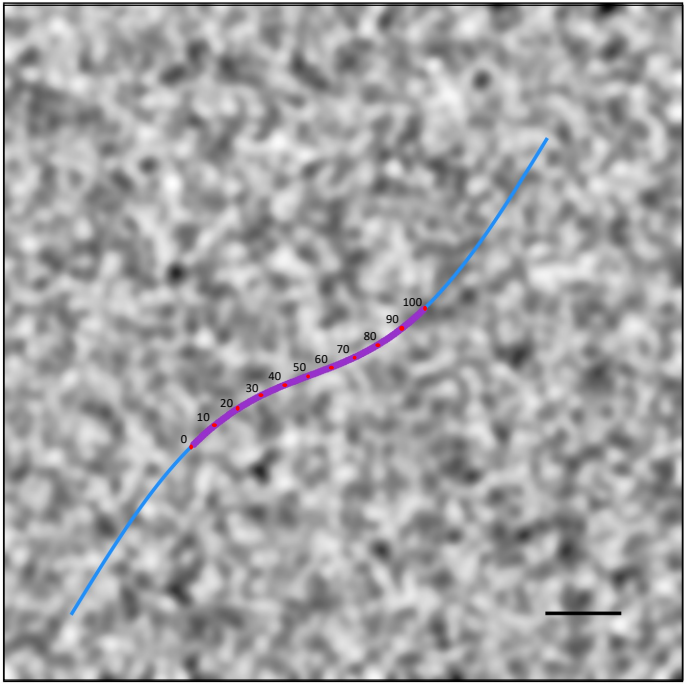


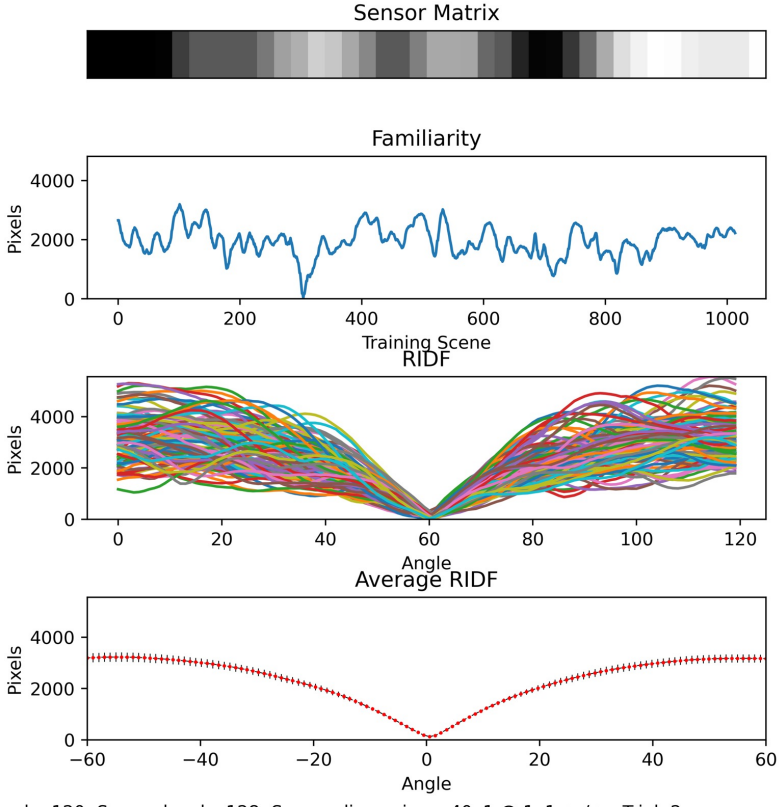




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 39.96; RMSD/dist: 0.100; TD: 2462; p90: 44; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 128; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

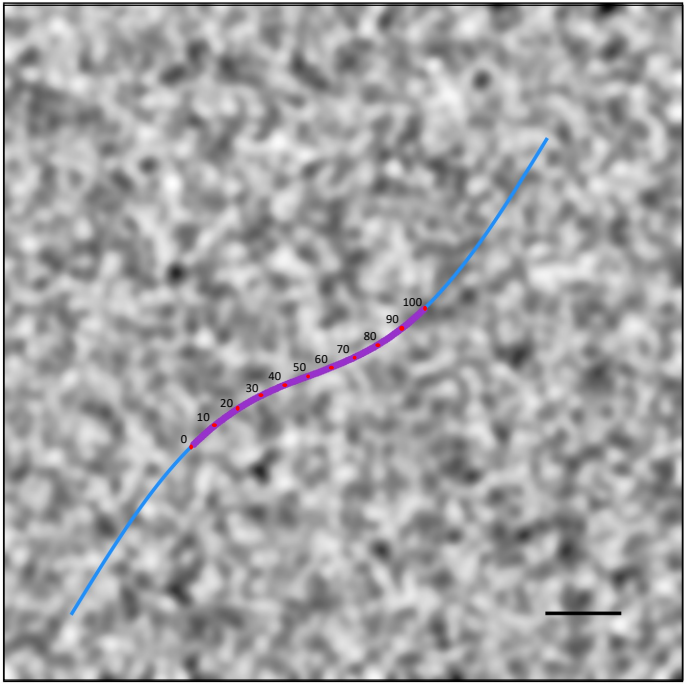
100%

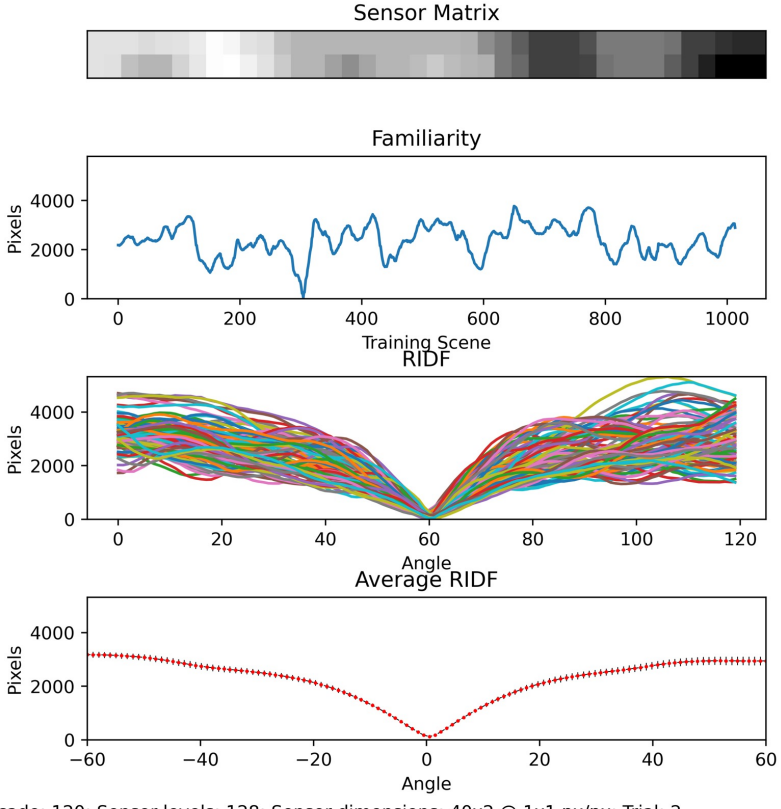



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 50.43; RMSD/dist: 0.126; TD: 2062; p90: 38; p50: 20; complete: 0

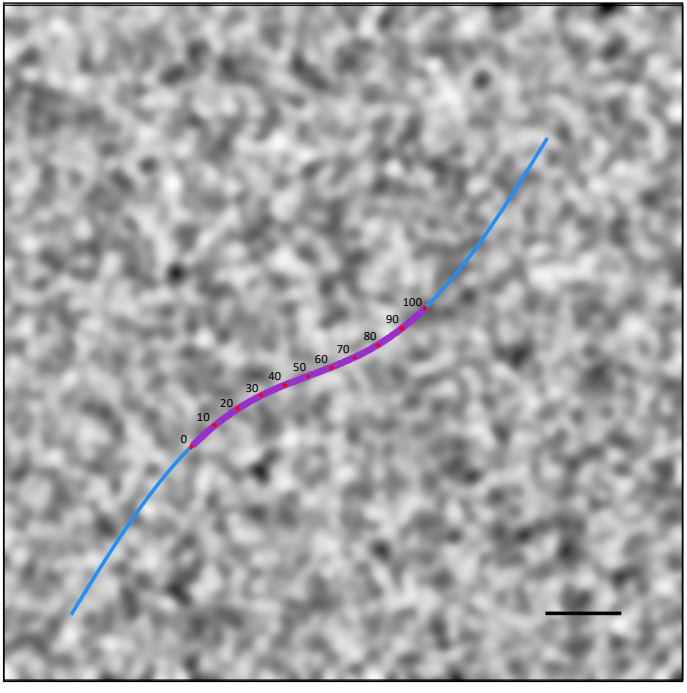
100%

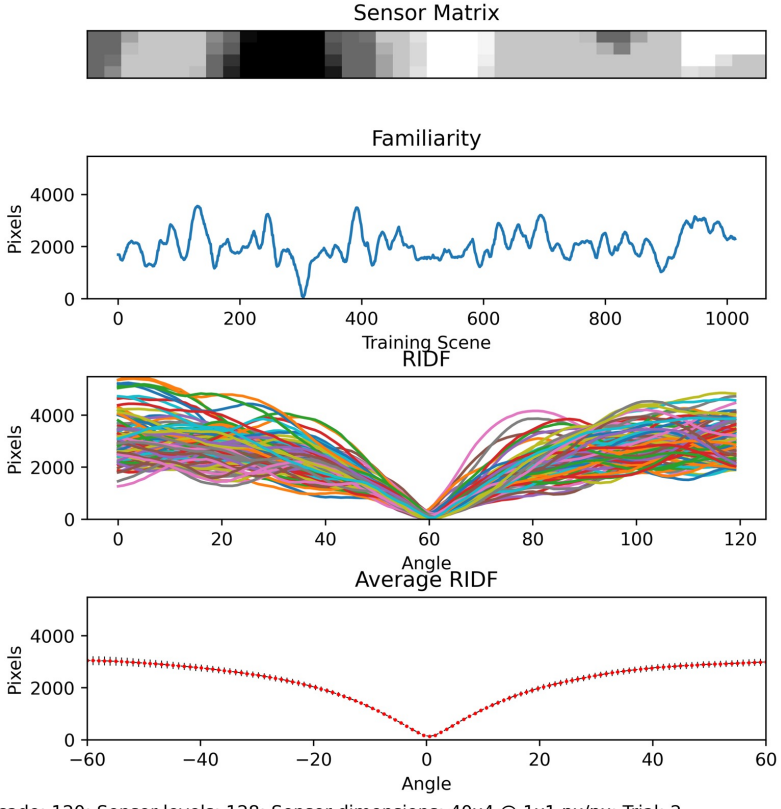



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 39.05; RMSD/dist: 0.098; TD: 2358; p90: 44; p50: 20; complete: 0

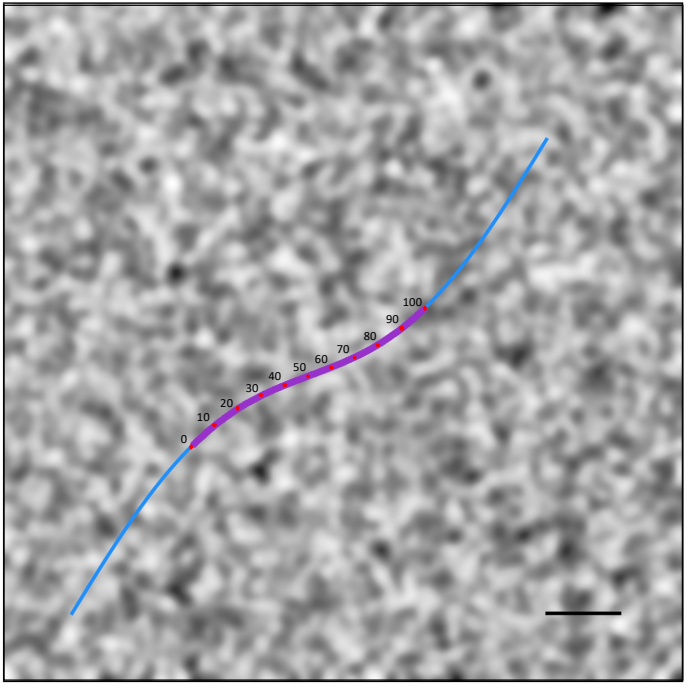
100%

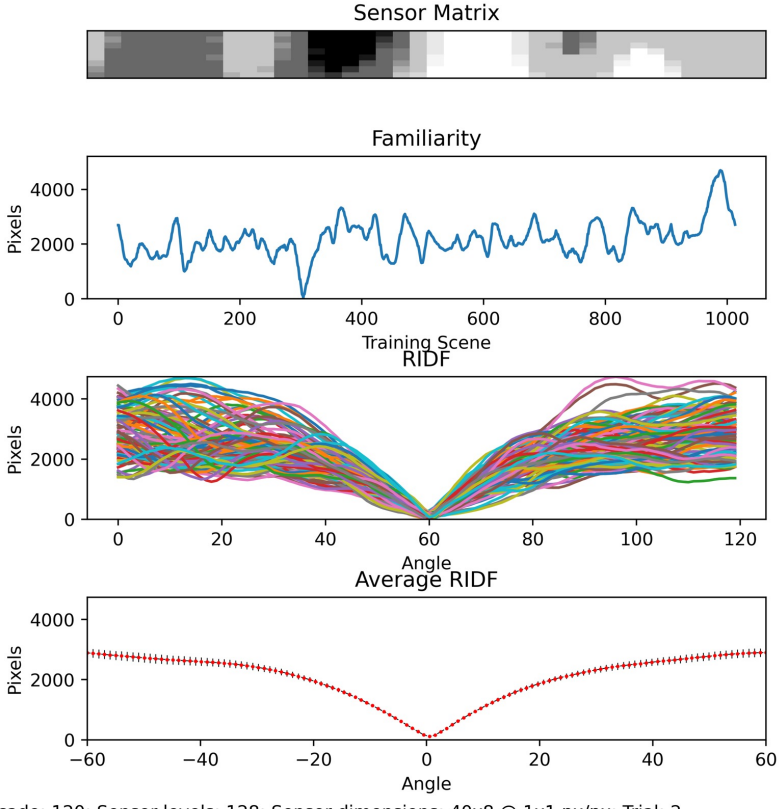



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 48.28; RMSD/dist: 0.121; TD: 2052; p90: 38; p50: 18; complete: 0

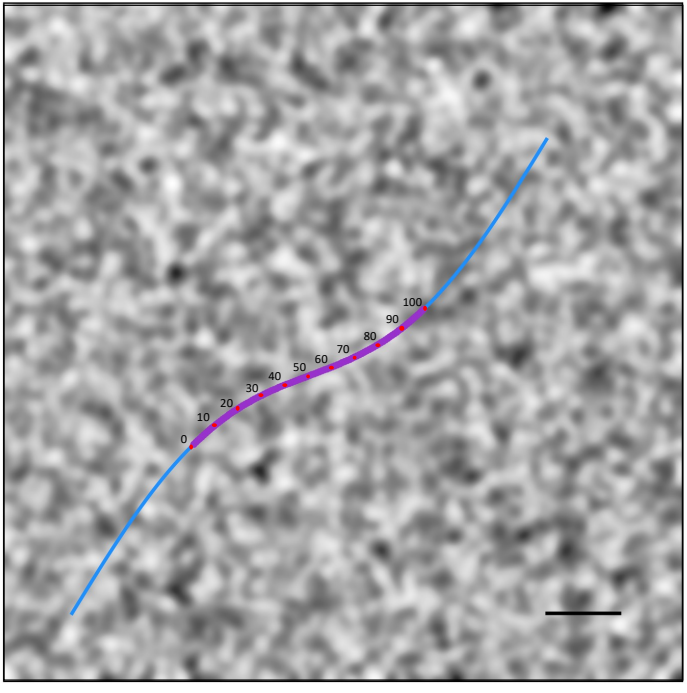
100%

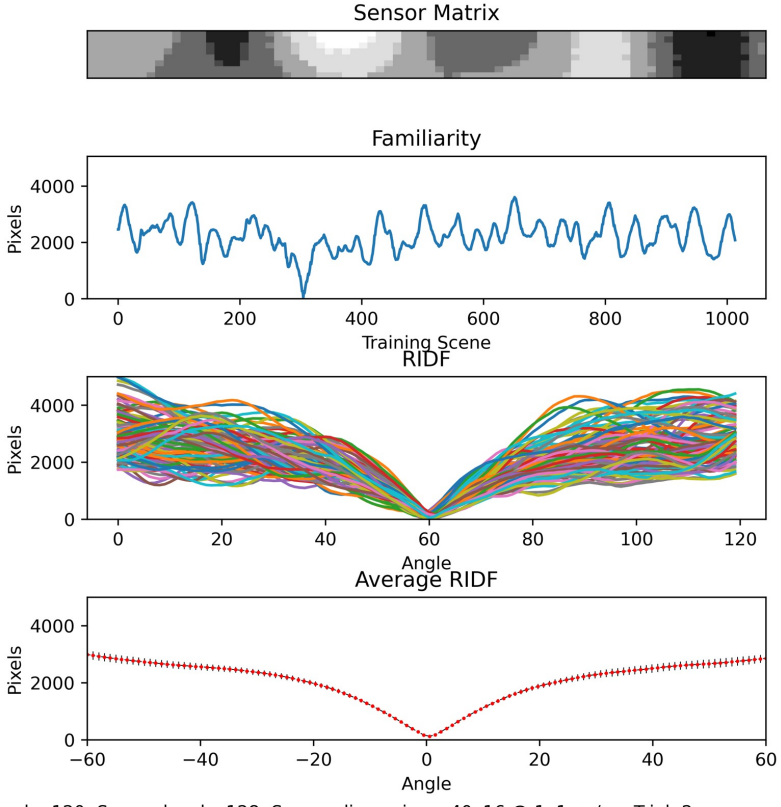



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 38.35; RMSD/dist: 0.096; TD: 2124; p90: 42; p50: 20; complete: 0

100%

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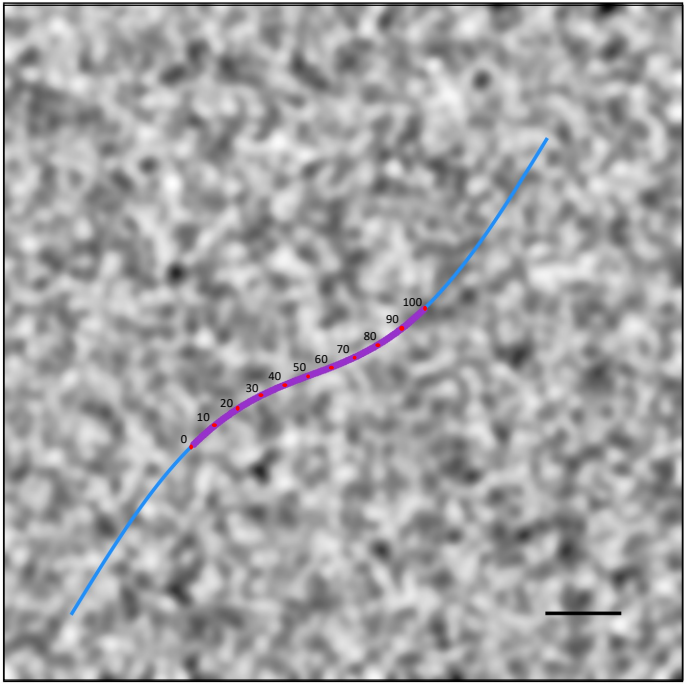
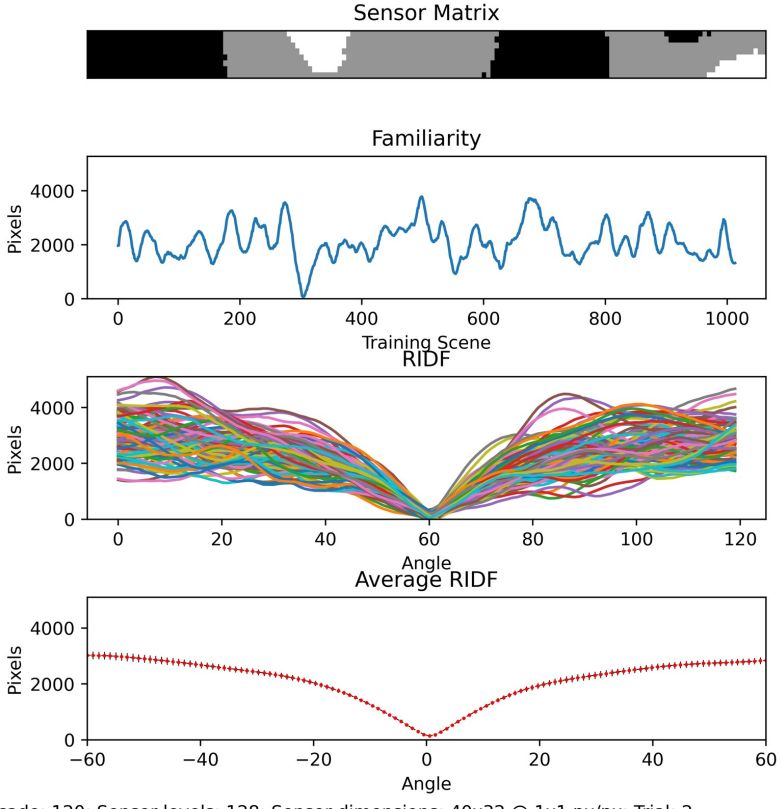
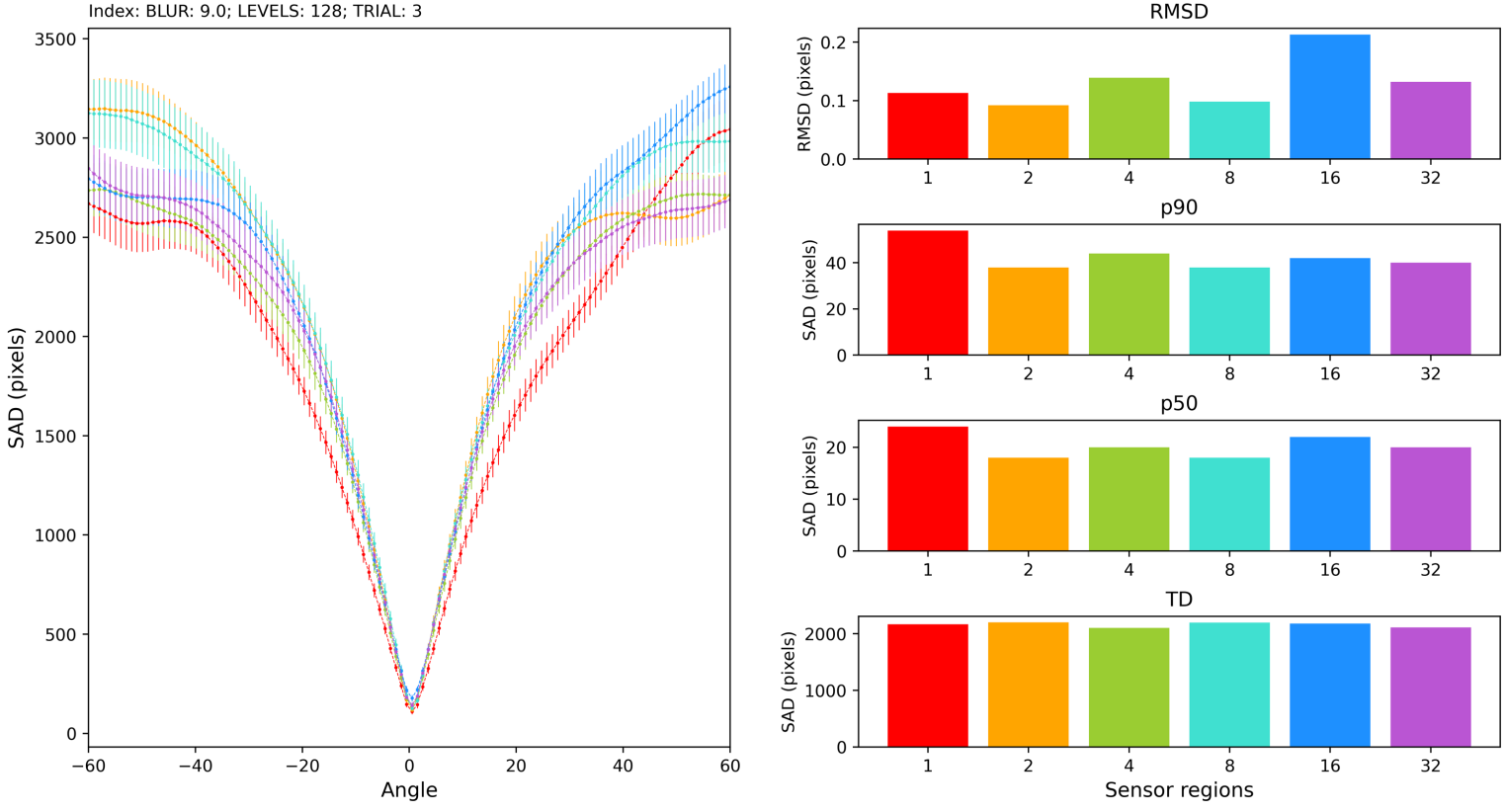
Navigation stats: RMSD error: 50.03; RMSD/dist: 0.125; TD: 2211; p90: 46; p50: 20; complete: 0

100%

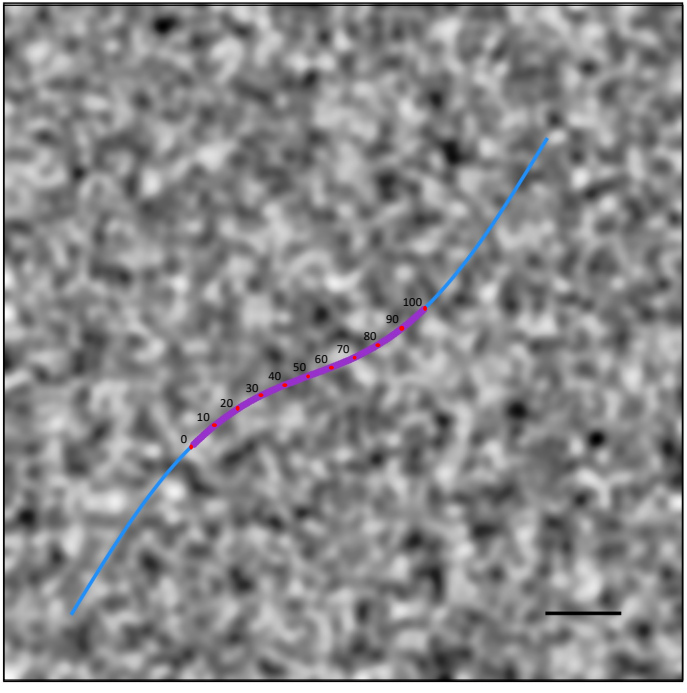


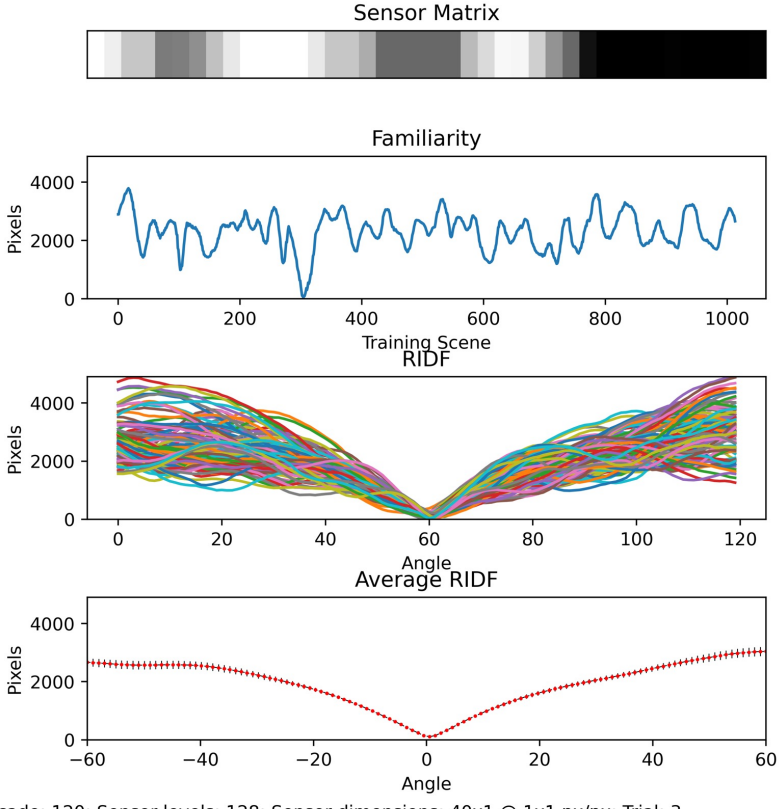




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 48.56; RMSD/dist: 0.121; TD: 2222; p90: 44; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 128; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

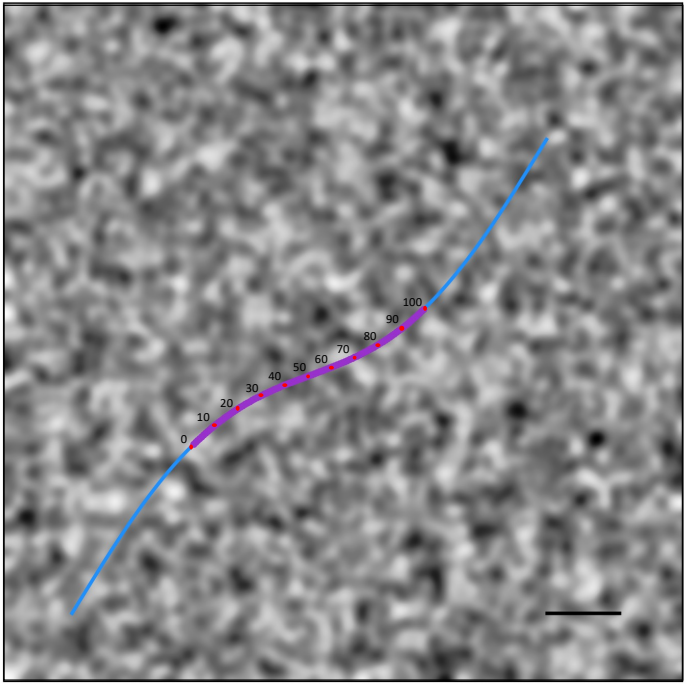
100%

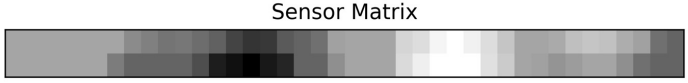


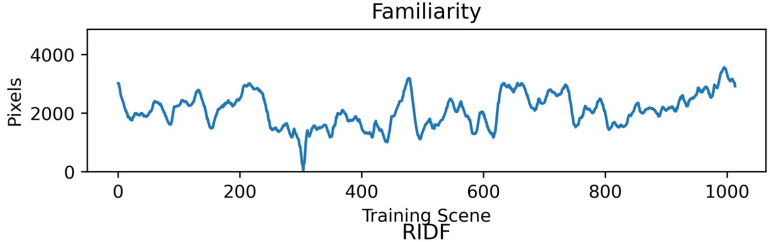



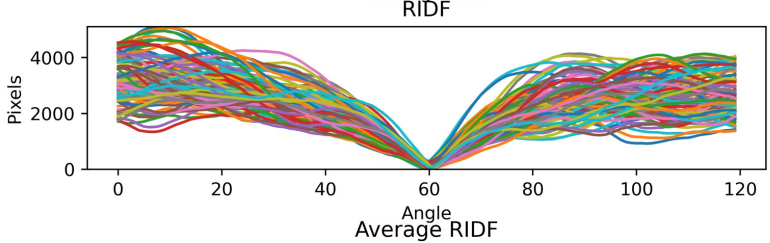

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 45.08; RMSD/dist: 0.113; TD: 2167; p90: 54; p50: 24; complete: 0

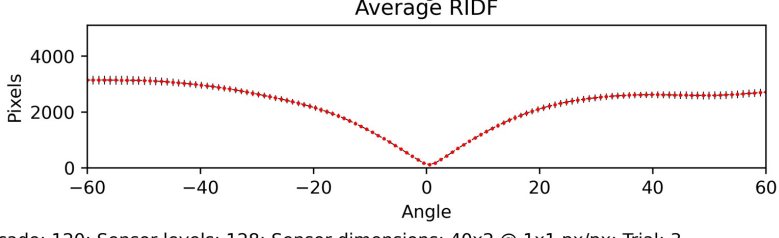
100%



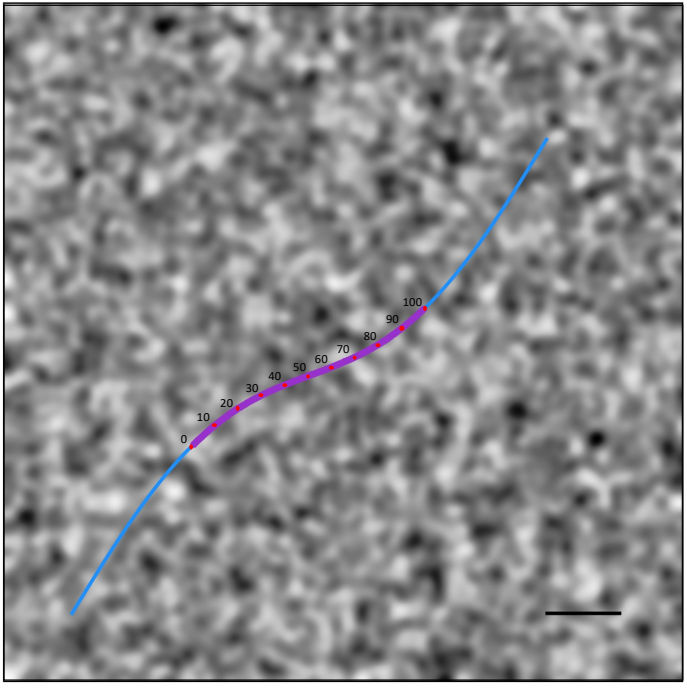



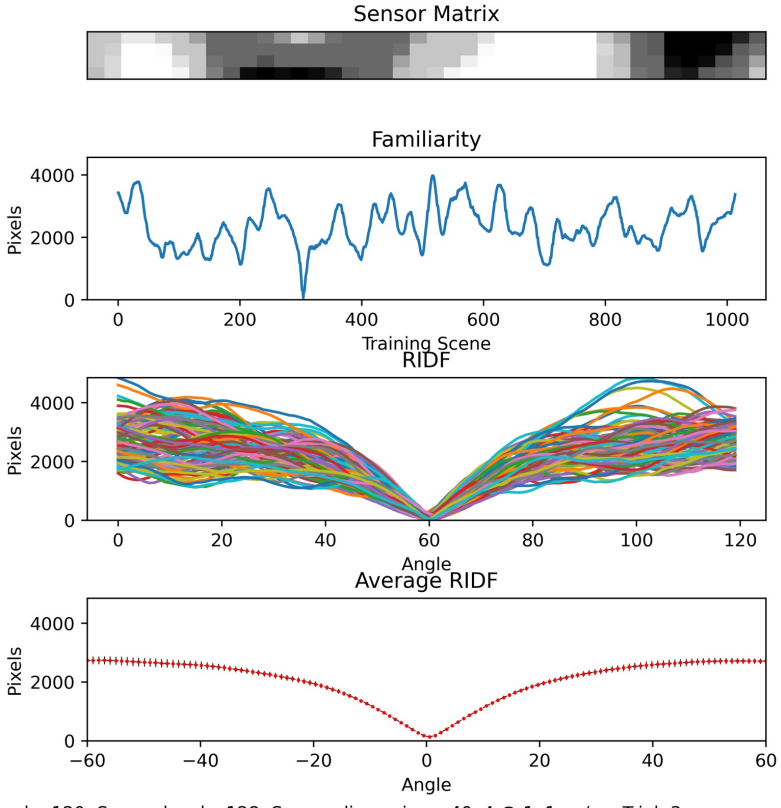




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 36.87; RMSD/dist: 0.092; TD: 2197; p90: 38; p50: 18; complete: 0

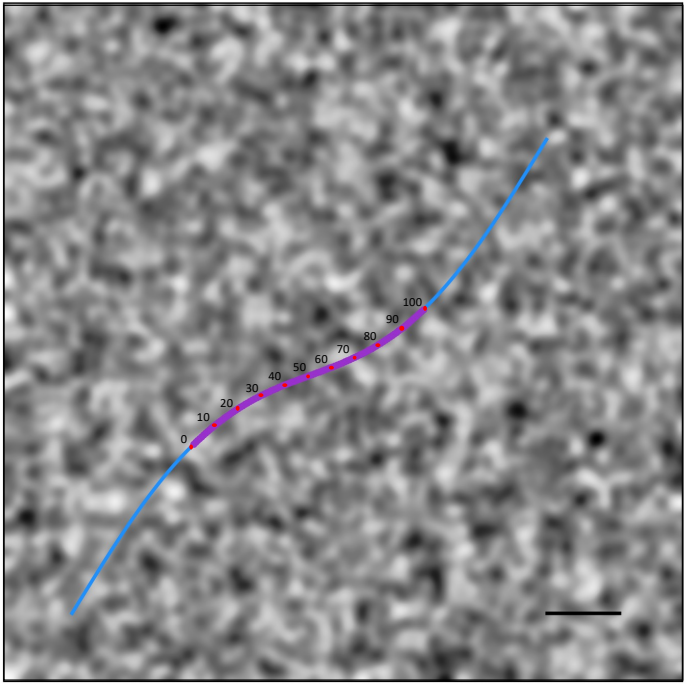
100%

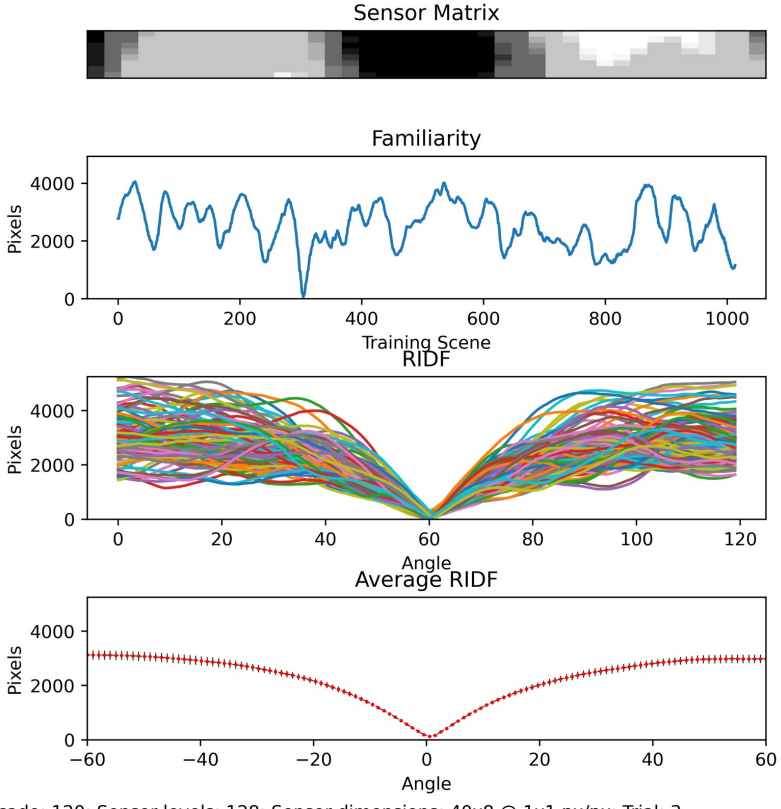



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 55.66; RMSD/dist: 0.139; TD: 2102; p90: 44; p50: 20; complete: 0

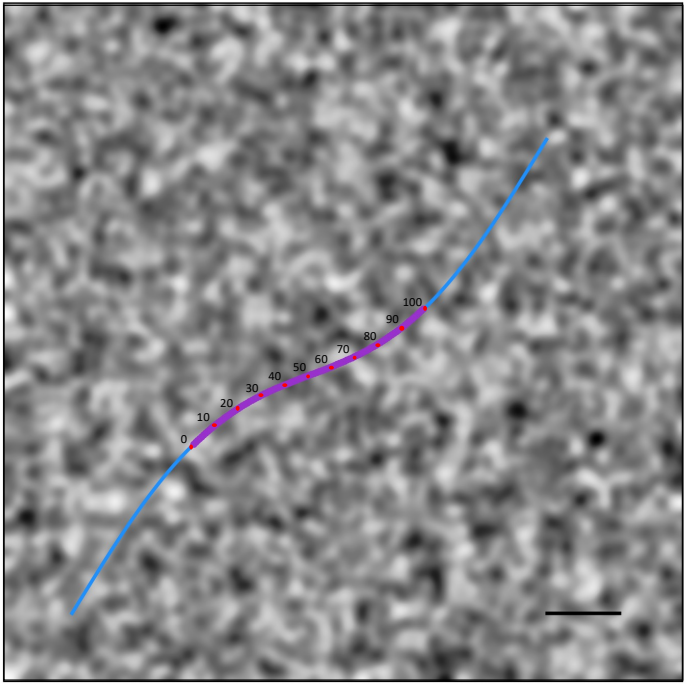
100%

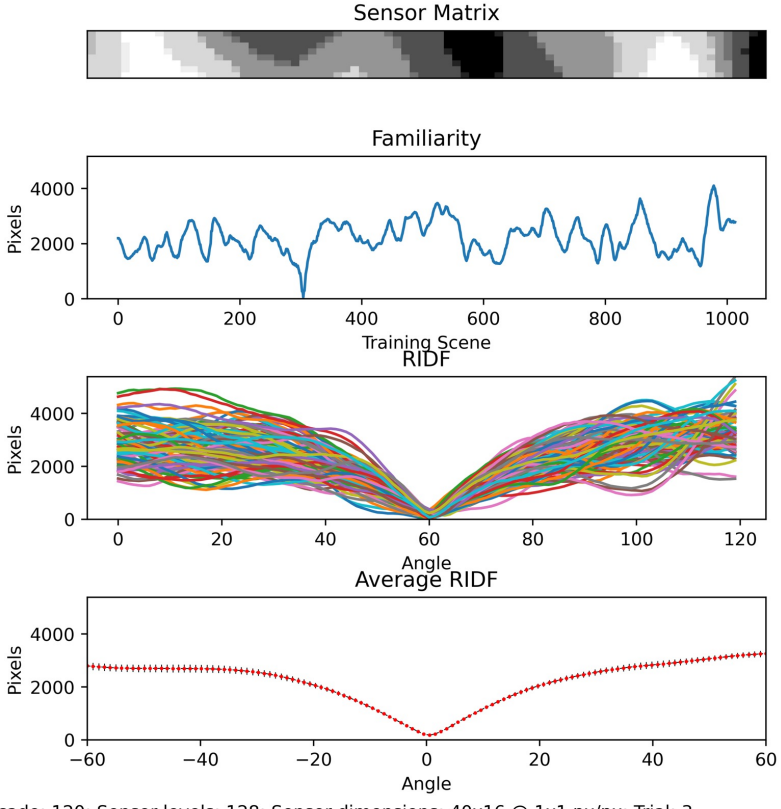



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 39.22; RMSD/dist: 0.098; TD: 2196; p90: 38; p50: 18; complete: 0

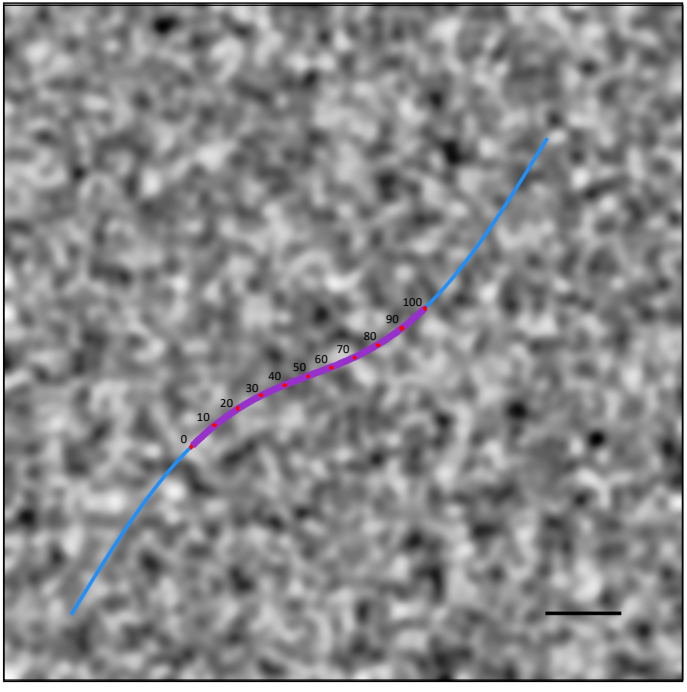
100%

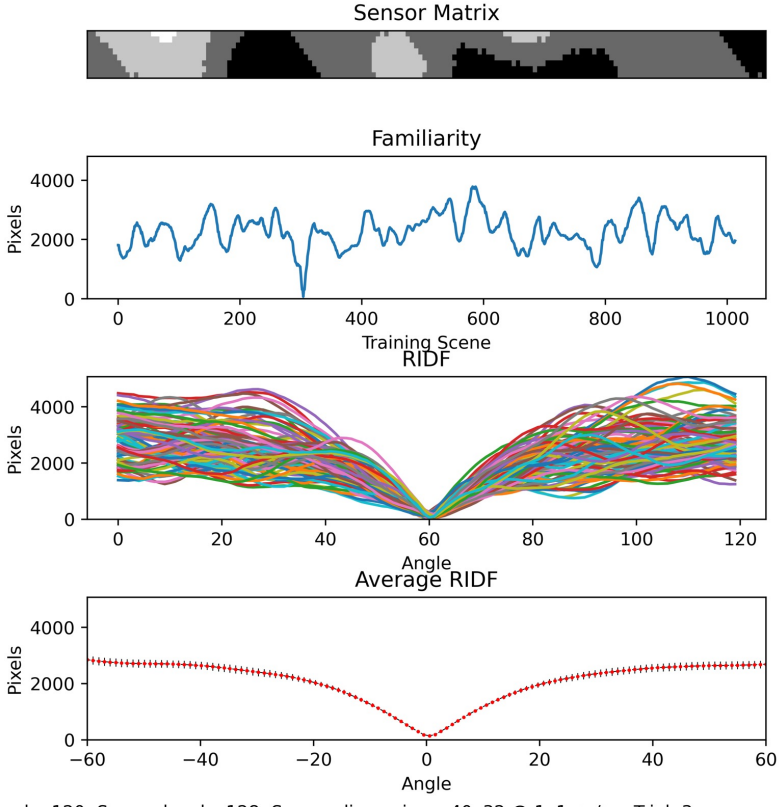


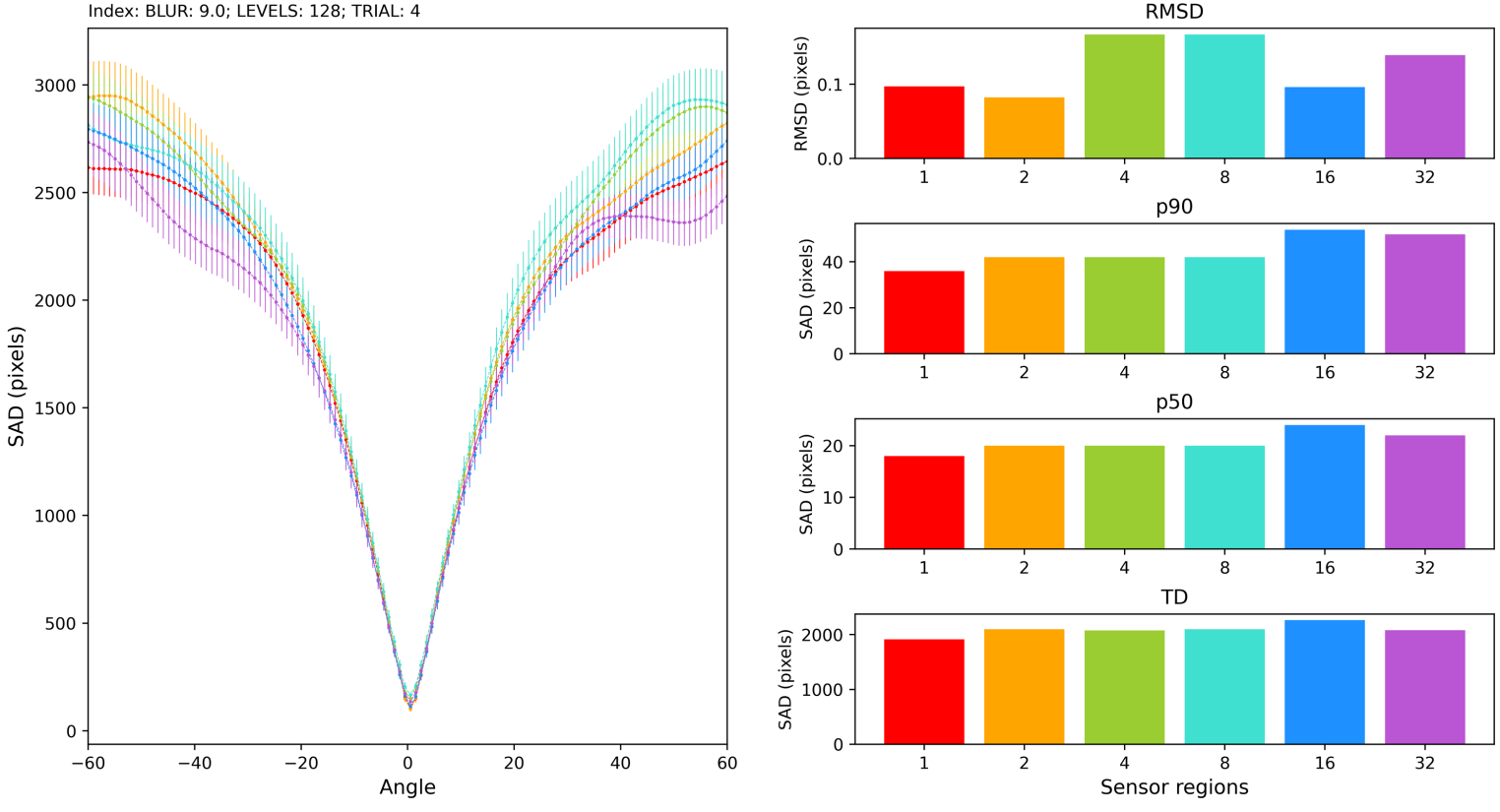

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 85.06; RMSD/dist: 0.213; TD: 2177; p90: 42; p50: 22; complete: 0

100%

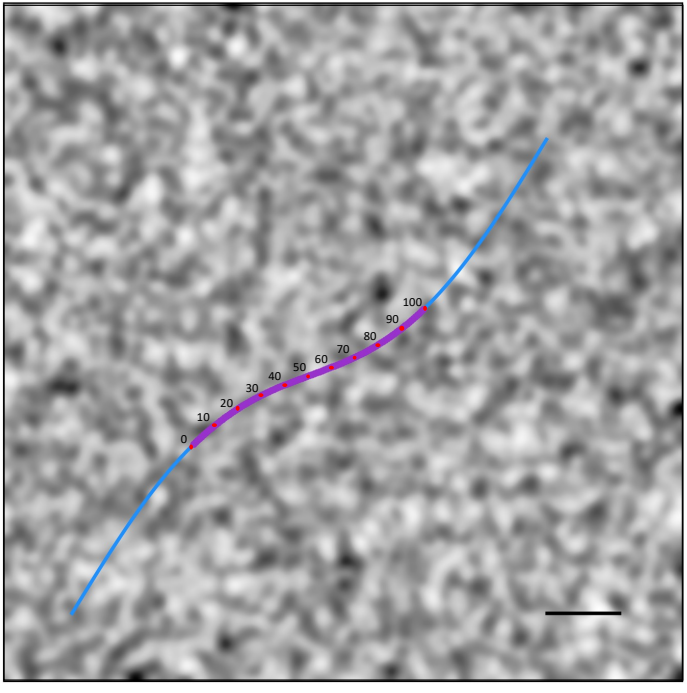


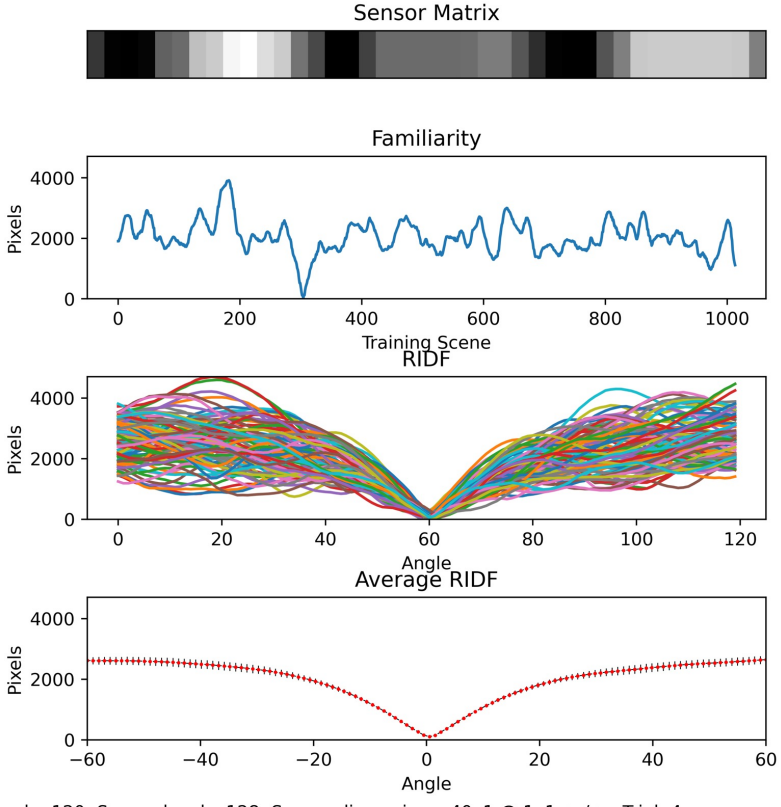




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 52.86; RMSD/dist: 0.132; TD: 2109; p90: 40; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 128; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

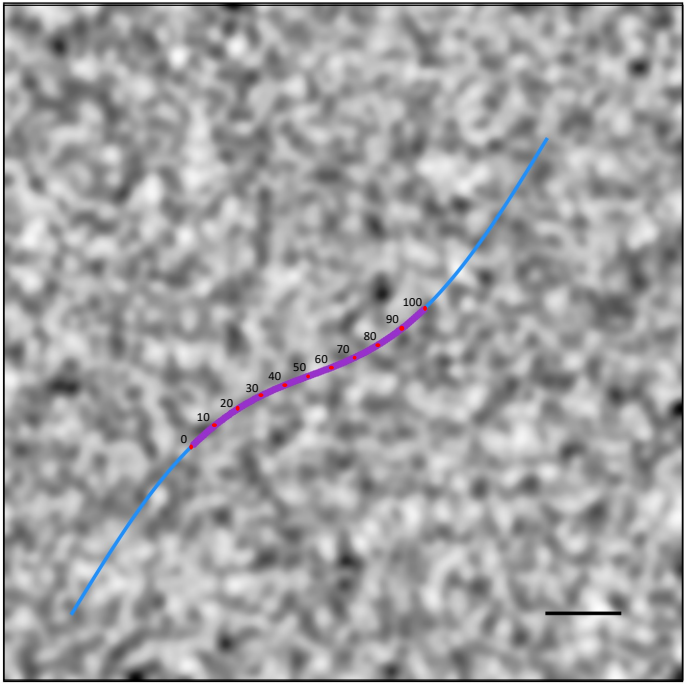
100%

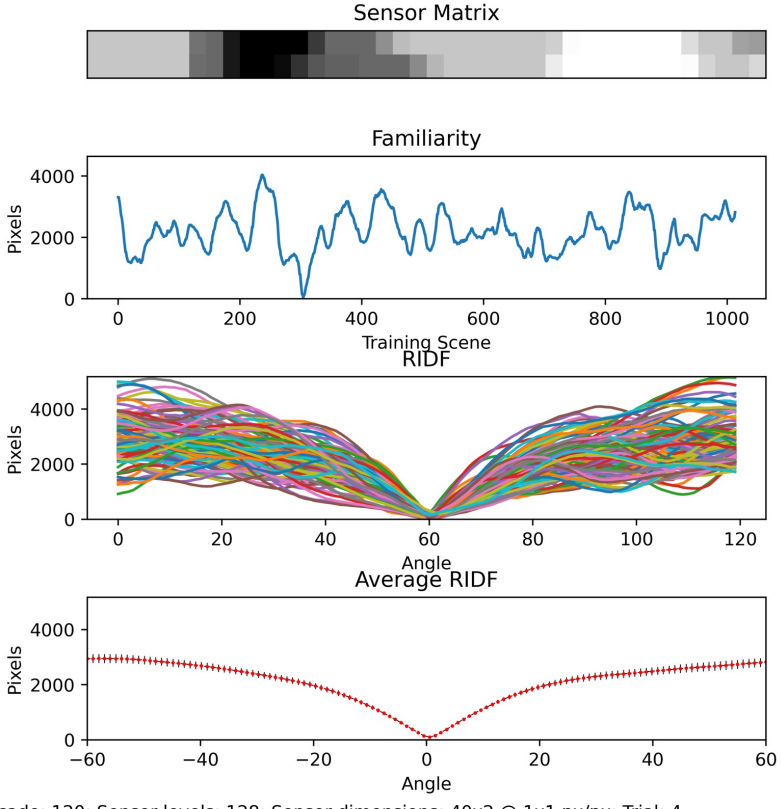



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 38.91; RMSD/dist: 0.097; TD: 1916; p90: 36; p50: 18; complete: 0

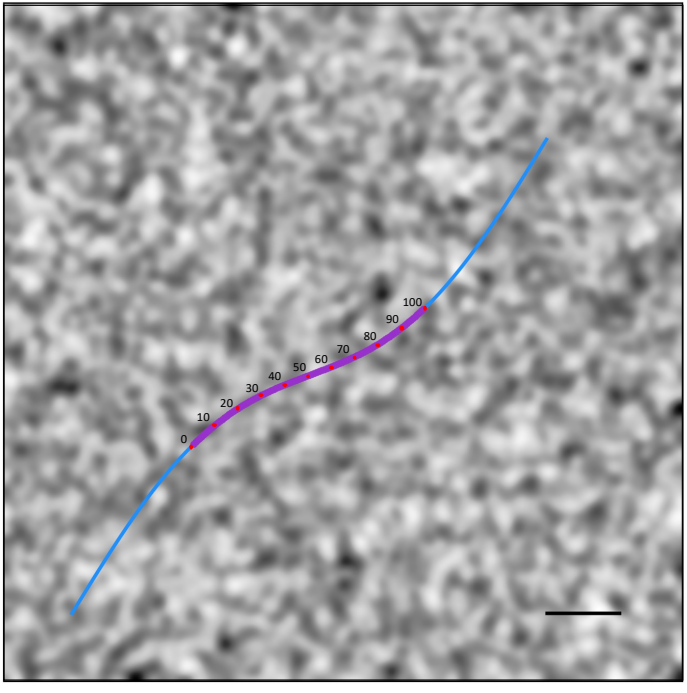
100%

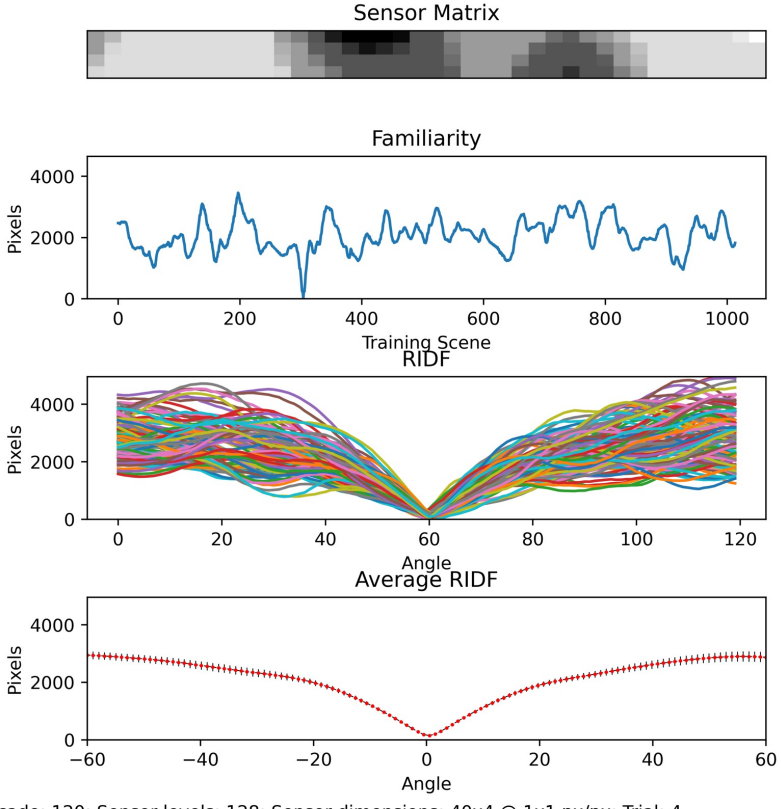



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 32.69; RMSD/dist: 0.082; TD: 2097; p90: 42; p50: 20; complete: 0

100%

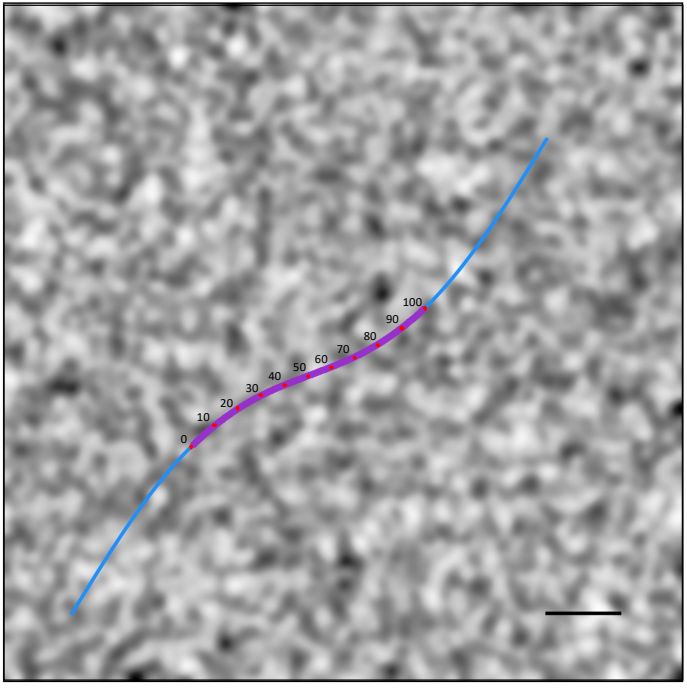


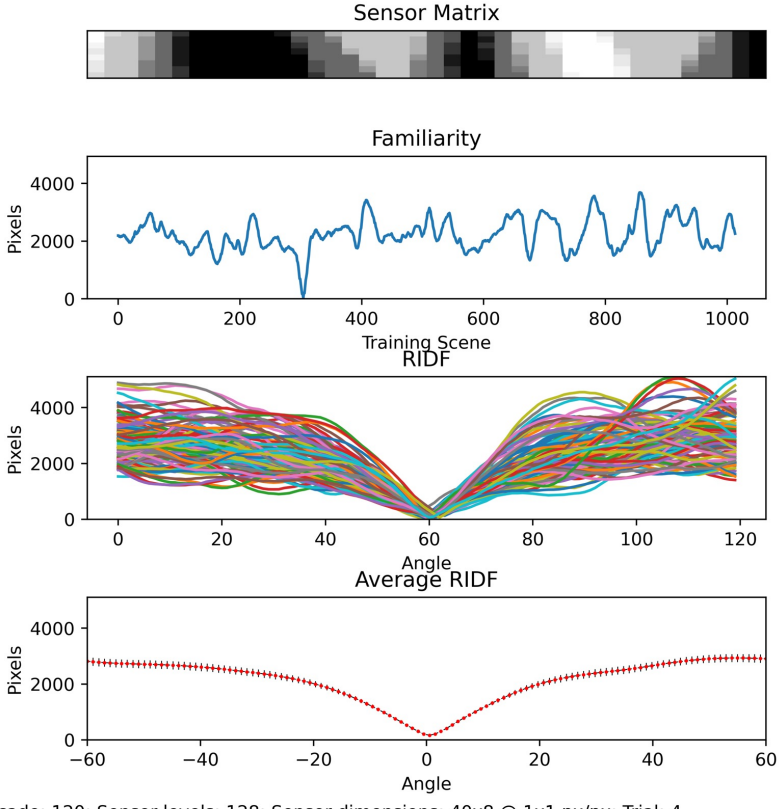




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 66.66; RMSD/dist: 0.167; TD: 2078; p90: 42; p50: 20; complete: 0

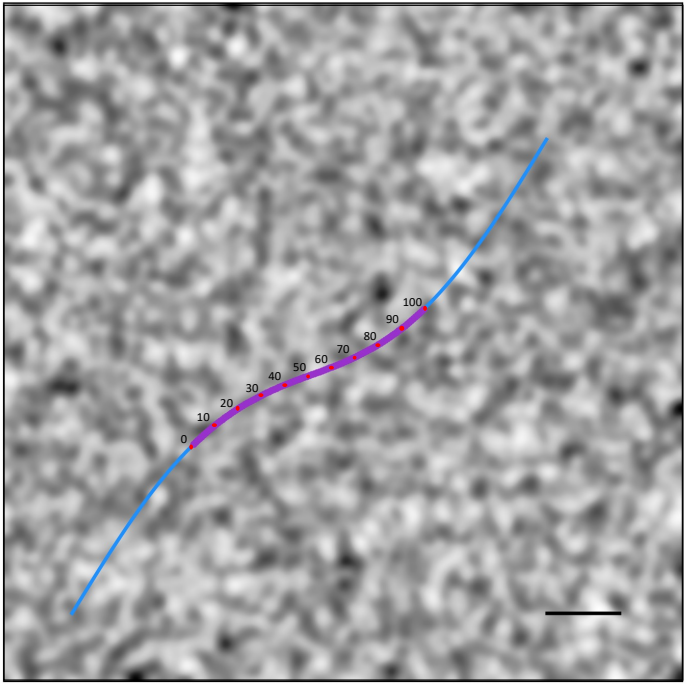
100%

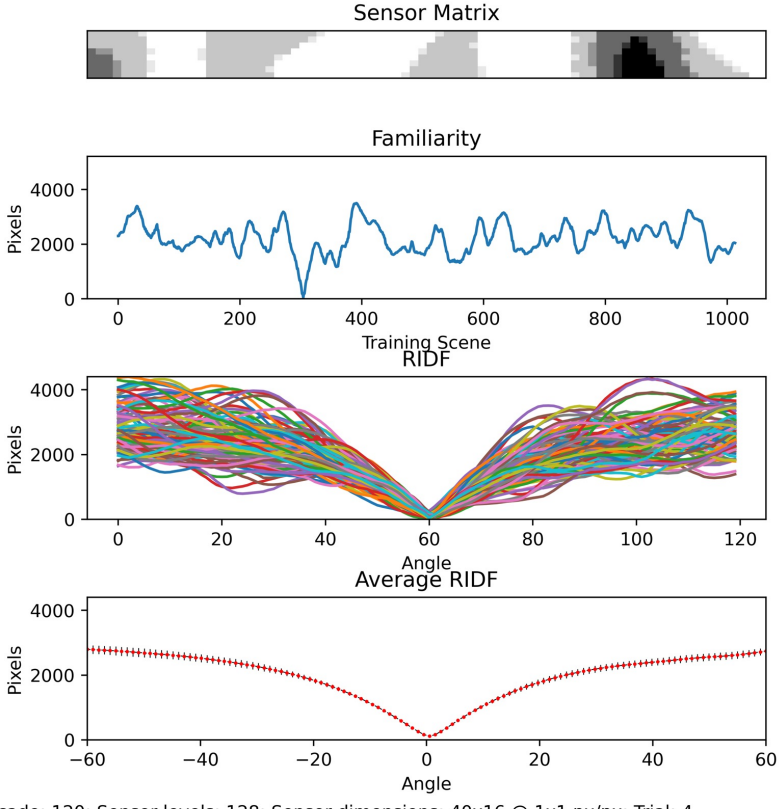



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 66.99; RMSD/dist: 0.167; TD: 2098; p90: 42; p50: 20; complete: 0

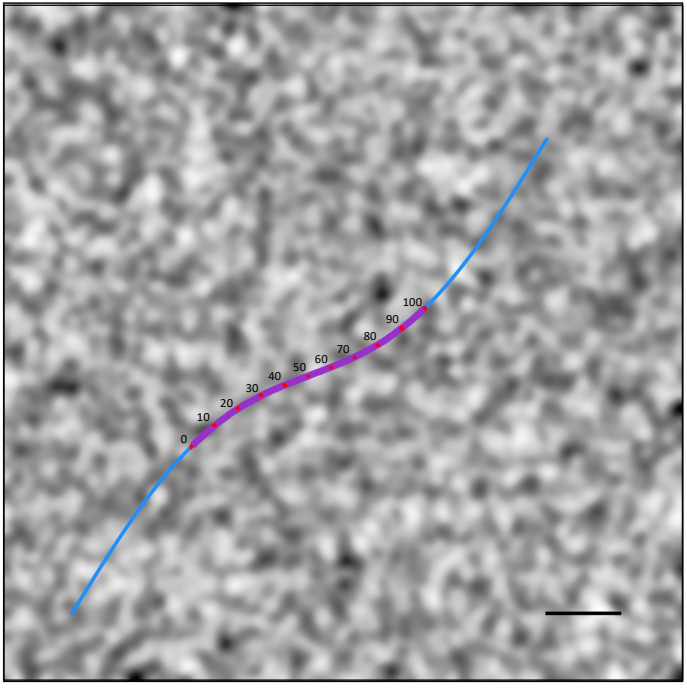
100%

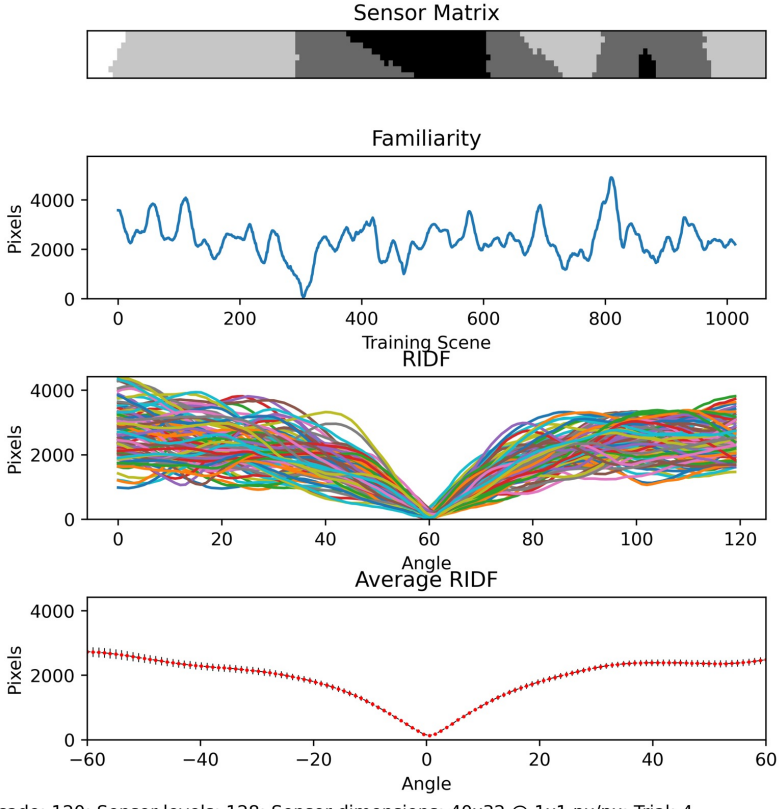


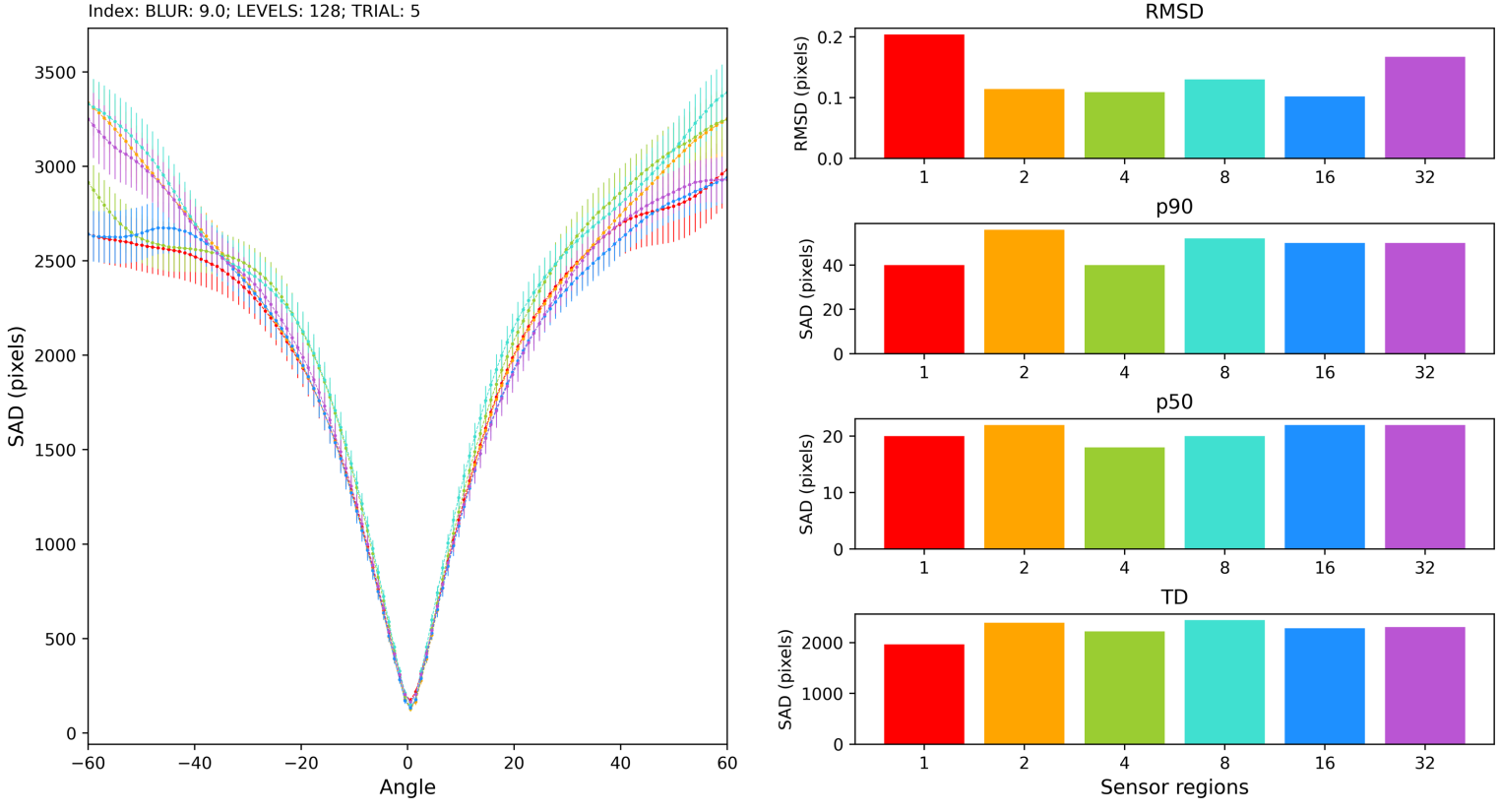

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 38.21; RMSD/dist: 0.096; TD: 2263; p90: 54; p50: 24; complete: 0

100%

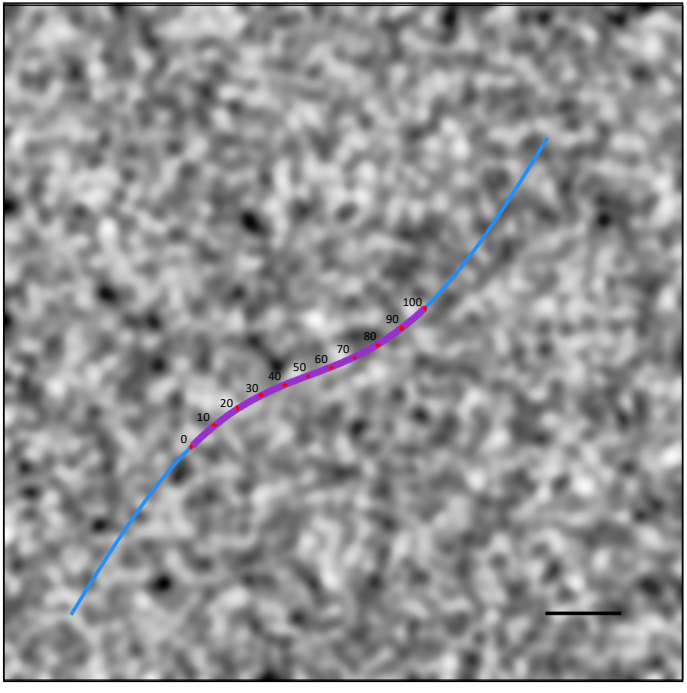


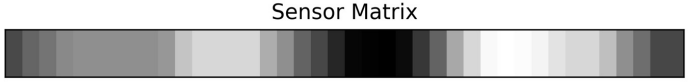



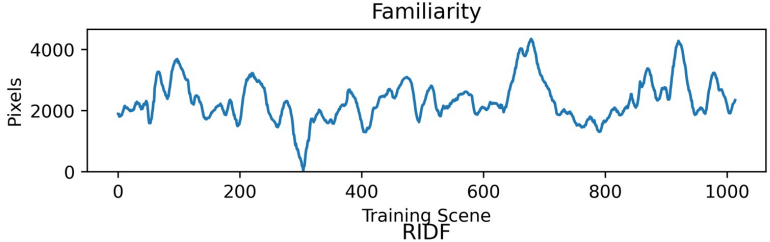

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 55.63; RMSD/dist: 0.139; TD: 2081; p90: 52; p50: 22; complete: 0

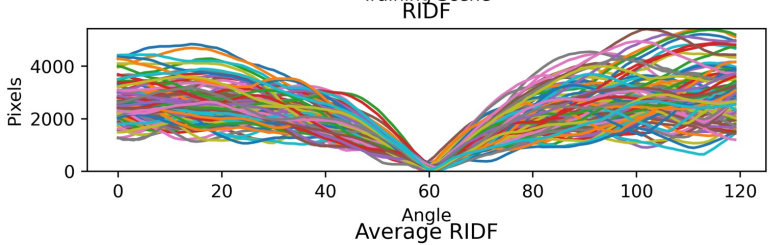

Index: BLUR: 9.0; LEVELS: 128; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

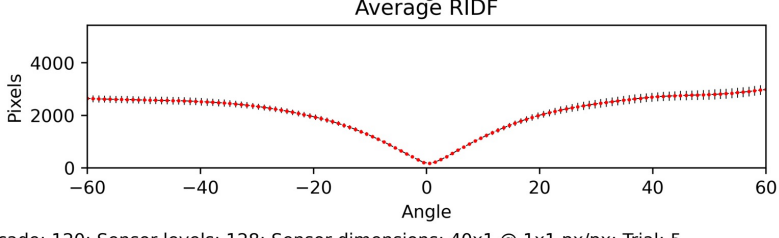
100%



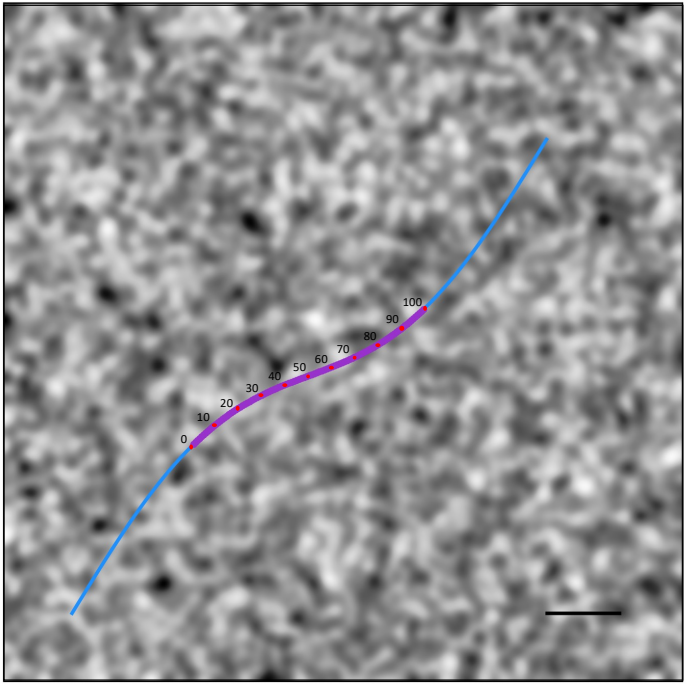



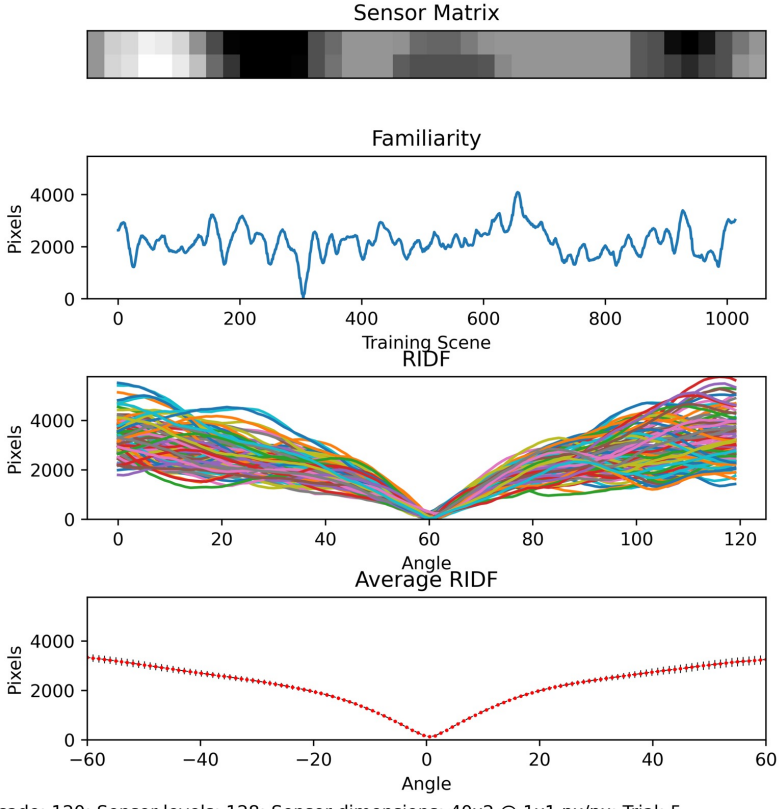




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 81.45; RMSD/dist: 0.204; TD: 1967; p90: 40; p50: 20; complete: 0

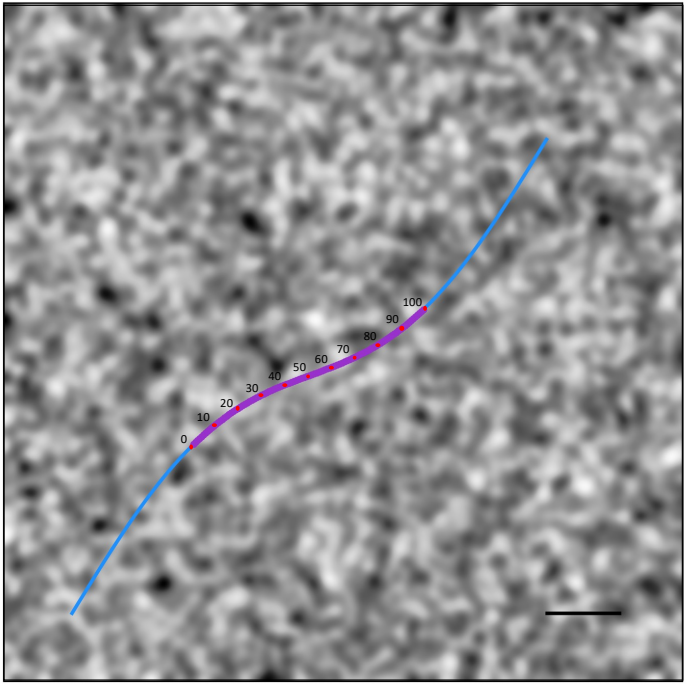
100%

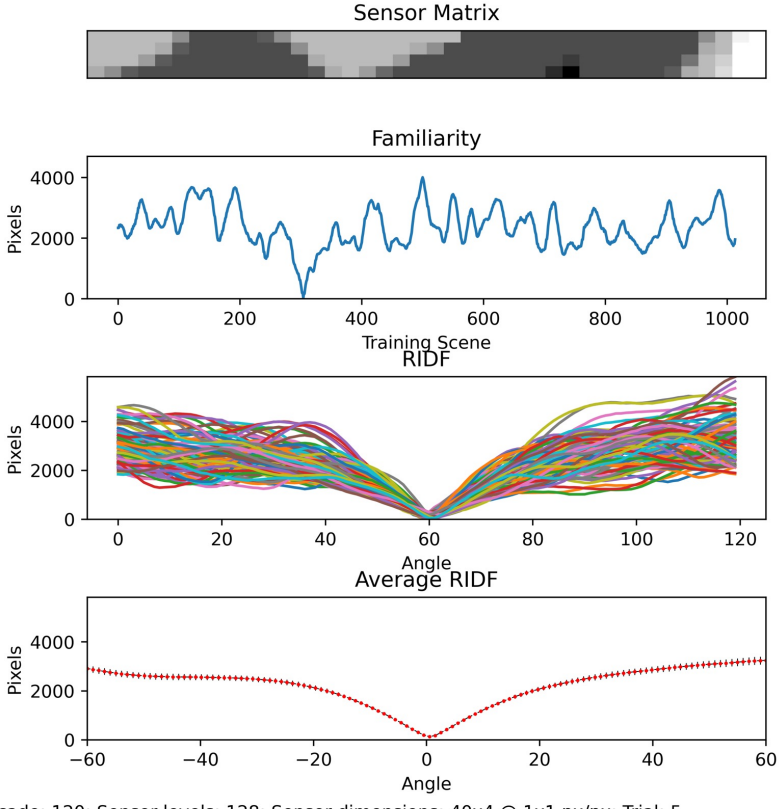



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 45.46; RMSD/dist: 0.114; TD: 2391; p90: 56; p50: 22; complete: 0

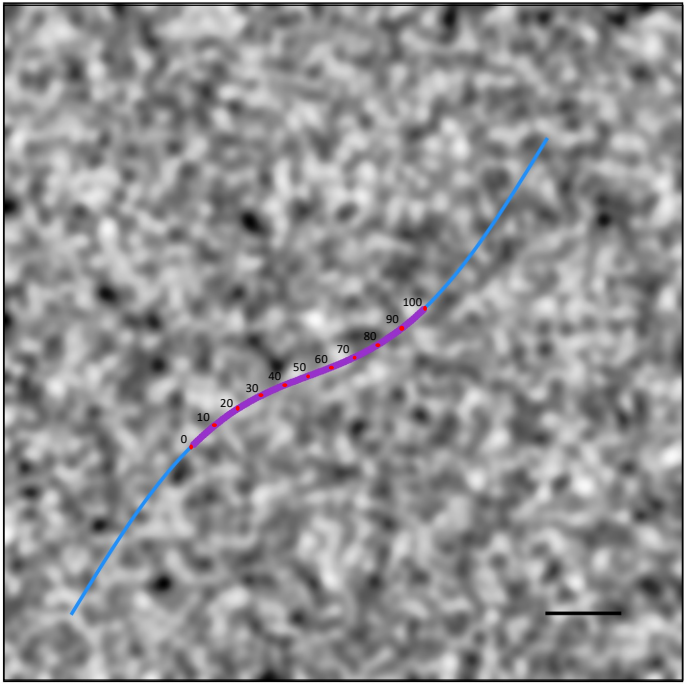
100%

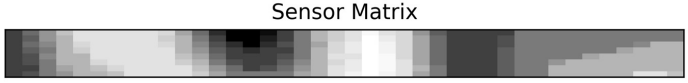


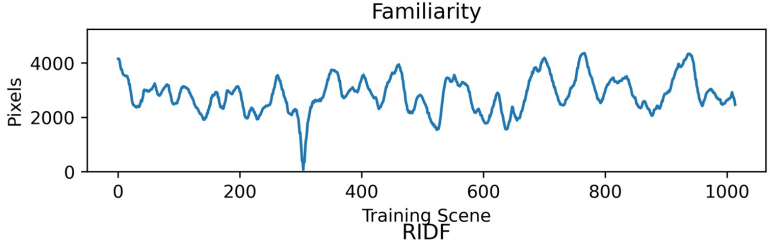



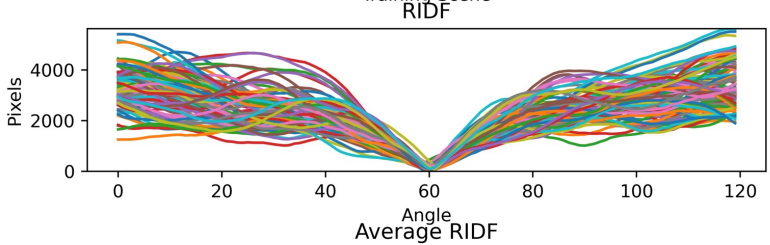

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 43.48; RMSD/dist: 0.109; TD: 2219; p90: 40; p50: 18; complete: 0

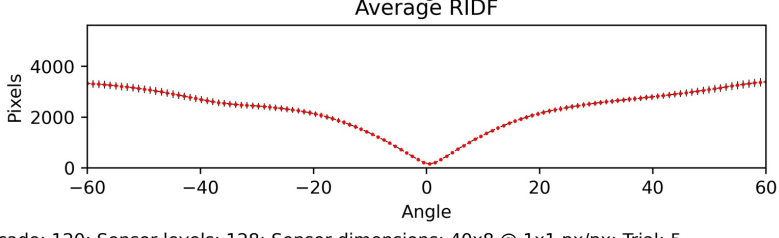
100%



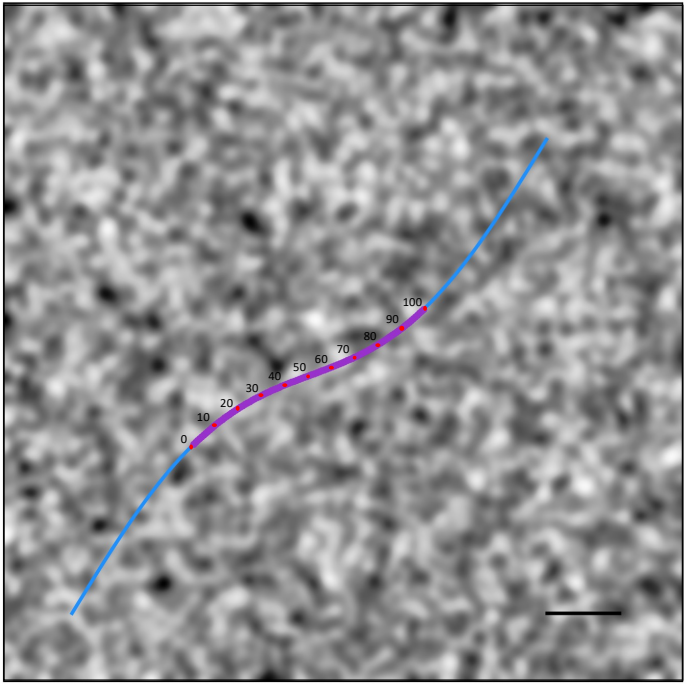



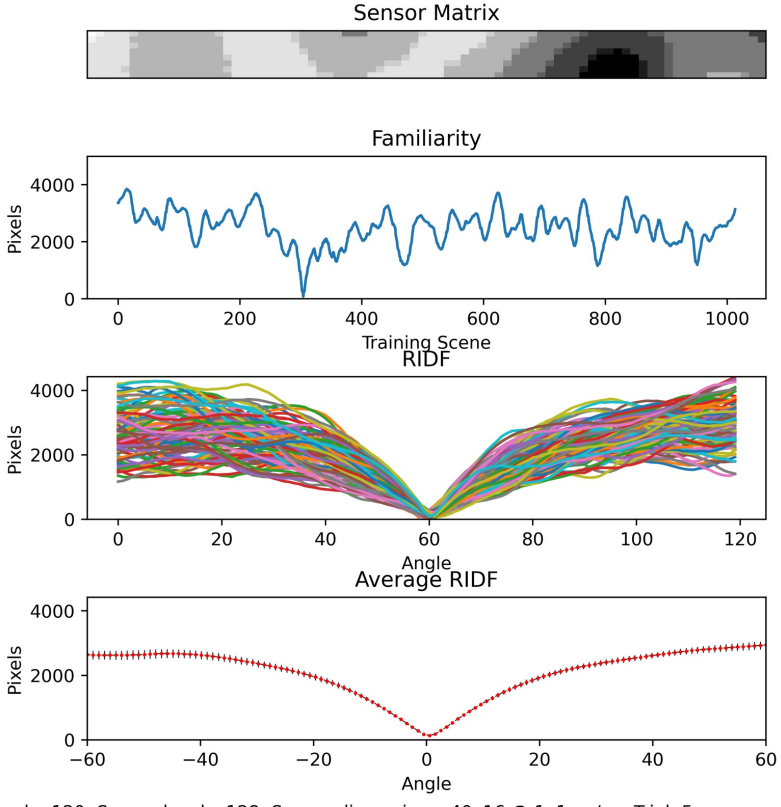




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 51.97; RMSD/dist: 0.130; TD: 2440; p90: 52; p50: 20; complete: 0

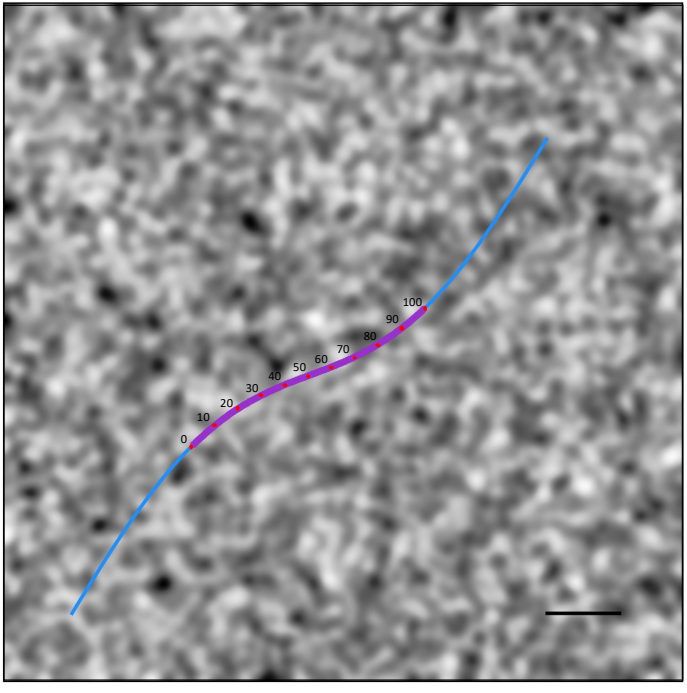
100%

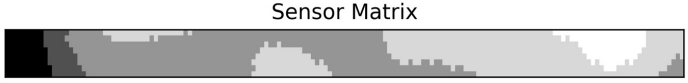


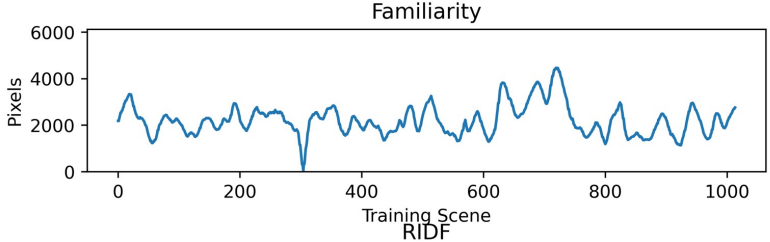



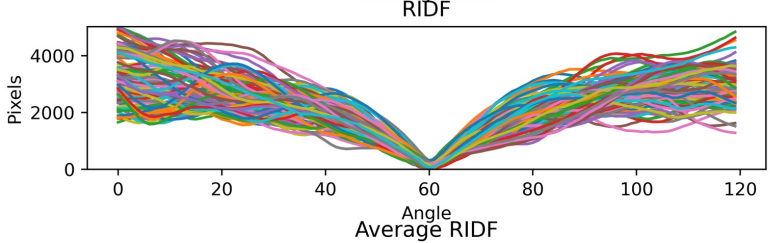

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 40.91; RMSD/dist: 0.102; TD: 2282; p90: 50; p50: 22; complete: 0

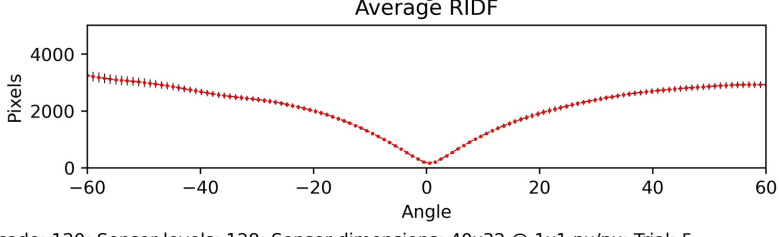
100%



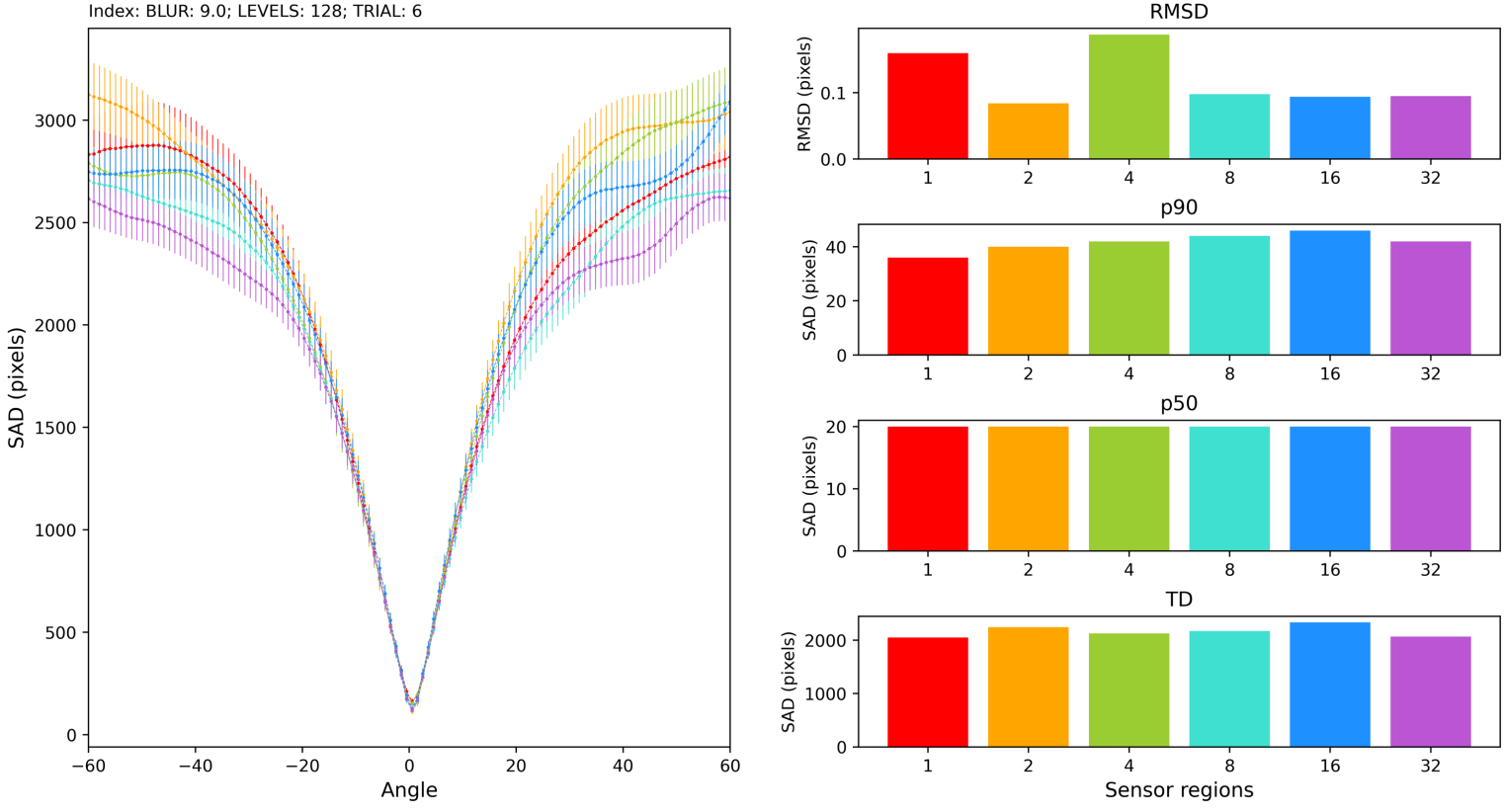



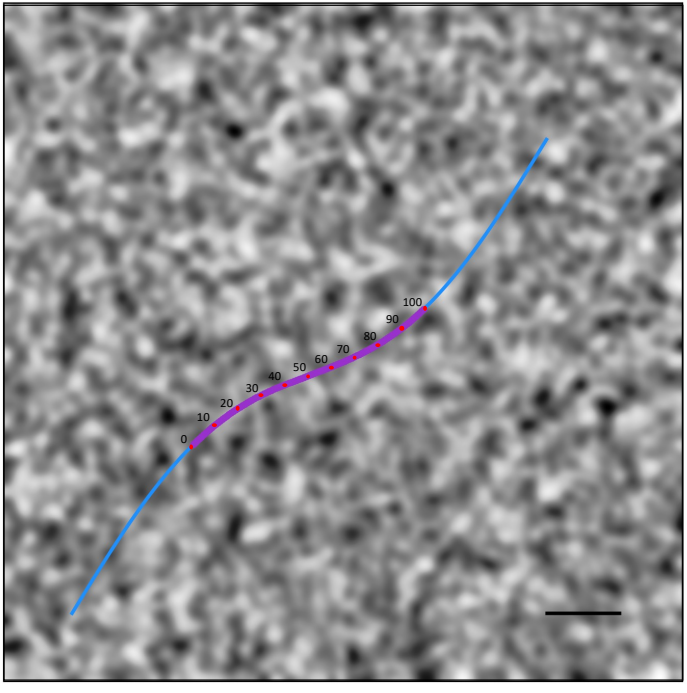



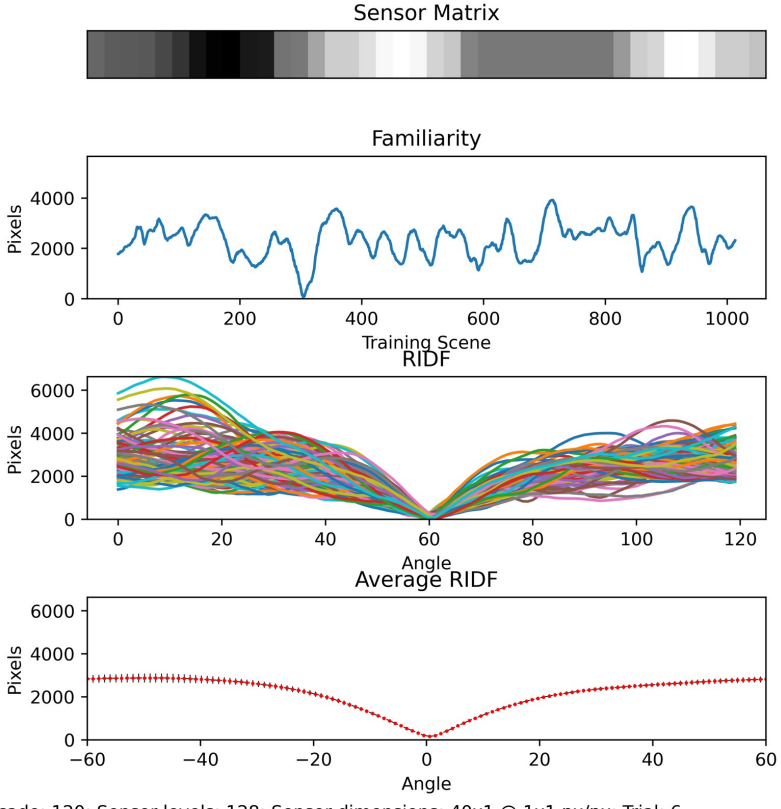




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 66.83; RMSD/dist: 0.167; TD: 2303; p90: 50; p50: 22; complete: 0


Index: BLUR: 9.0; LEVELS: 128; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

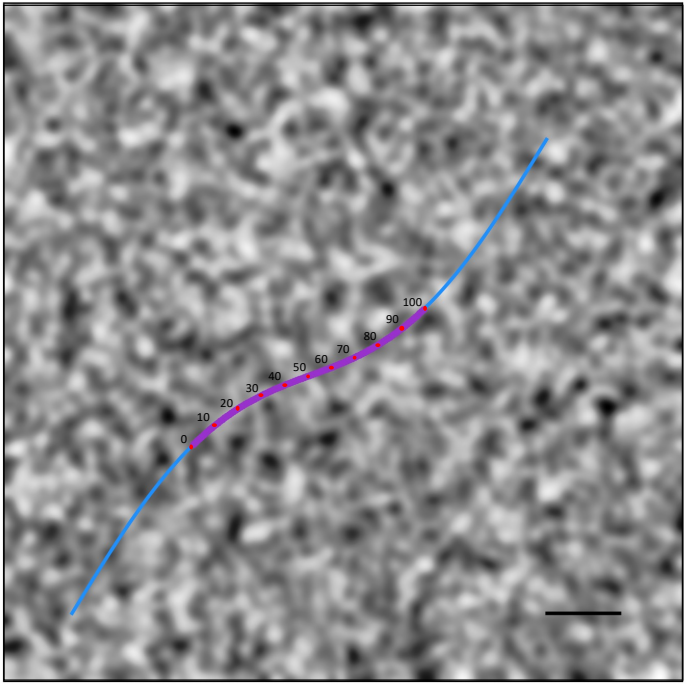
100%

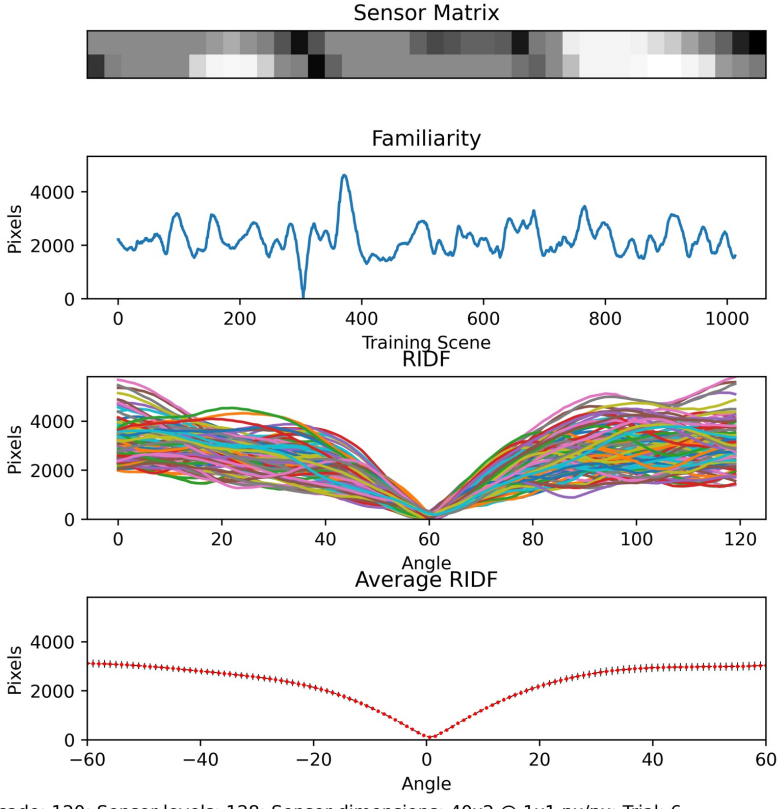



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 63.93; RMSD/dist: 0.160; TD: 2051; p90: 36; p50: 20; complete: 0

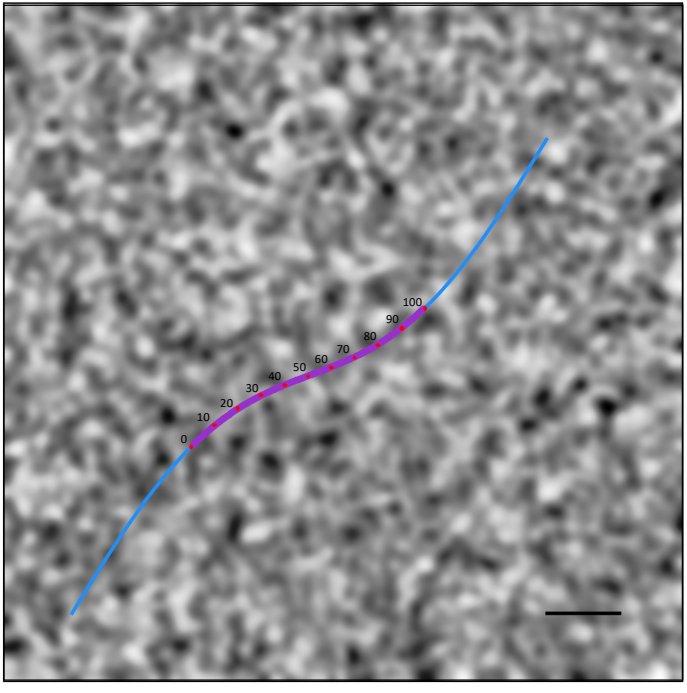
100%

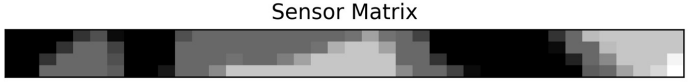


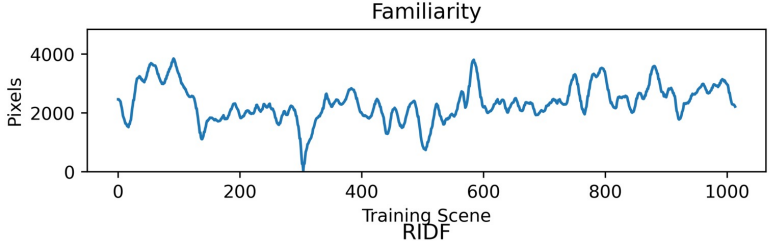



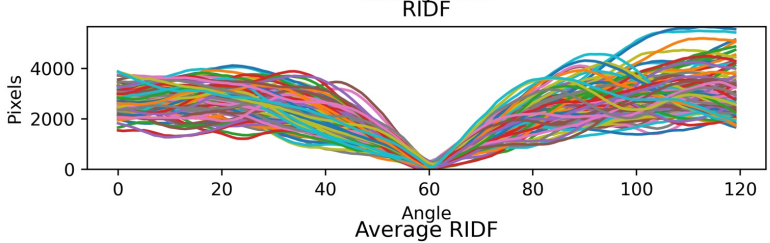

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 33.67; RMSD/dist: 0.084; TD: 2246; p90: 40; p50: 20; complete: 0

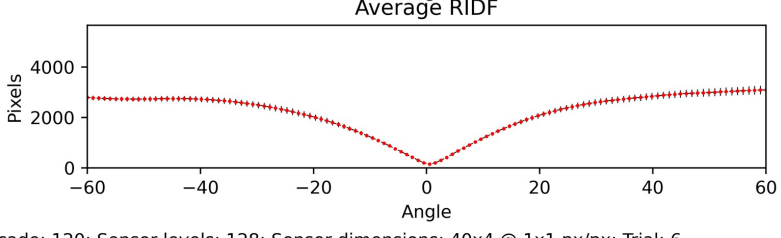
100%



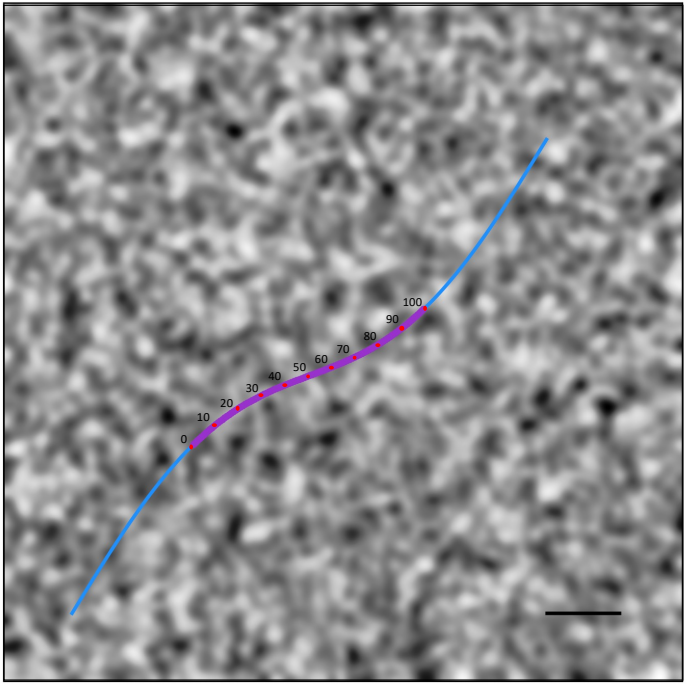



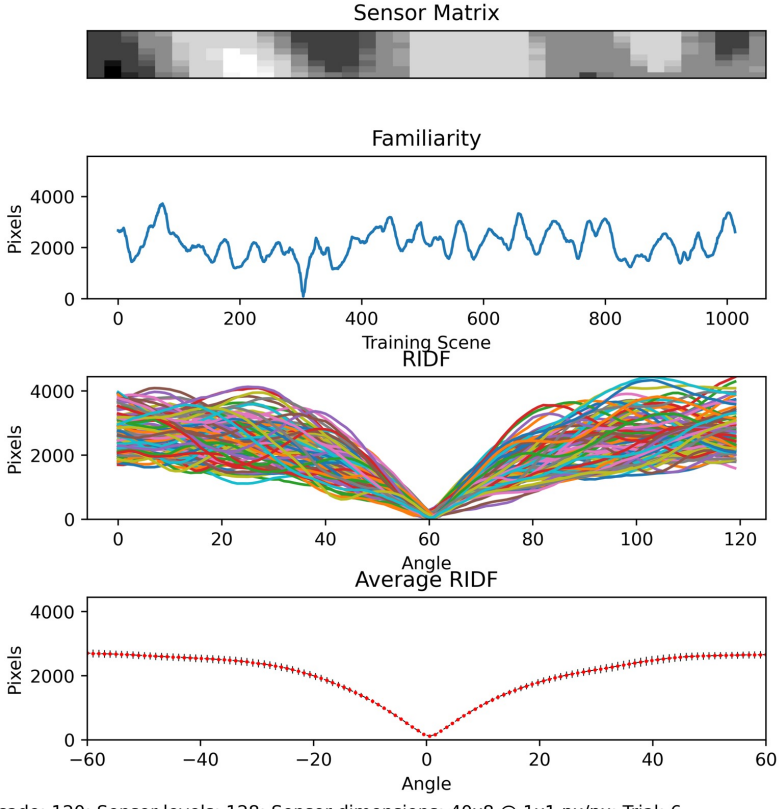




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 75.27; RMSD/dist: 0.188; TD: 2130; p90: 42; p50: 20; complete: 0

100%

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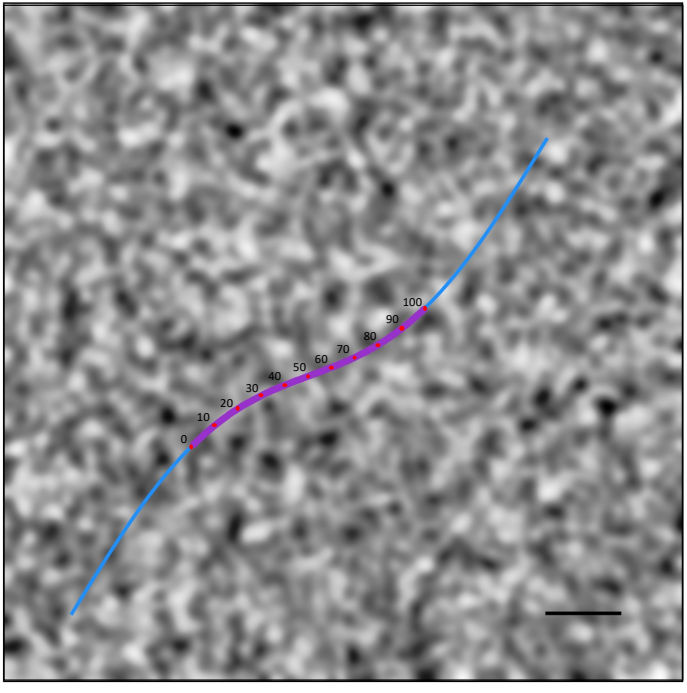
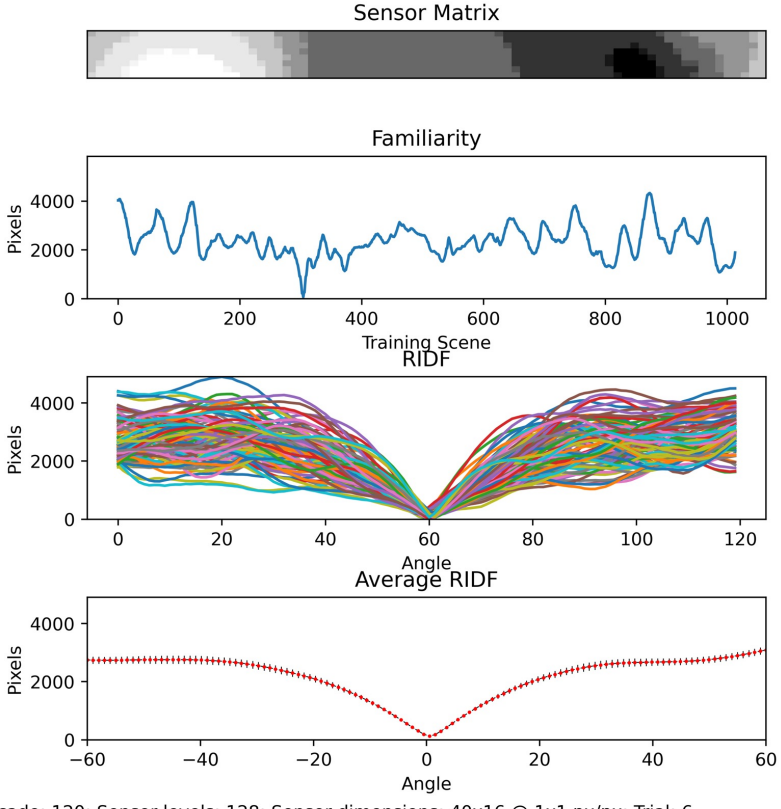
Navigation stats: RMSD error: 39.25; RMSD/dist: 0.098; TD: 2173; p90: 44; p50: 20; complete: 0

100%

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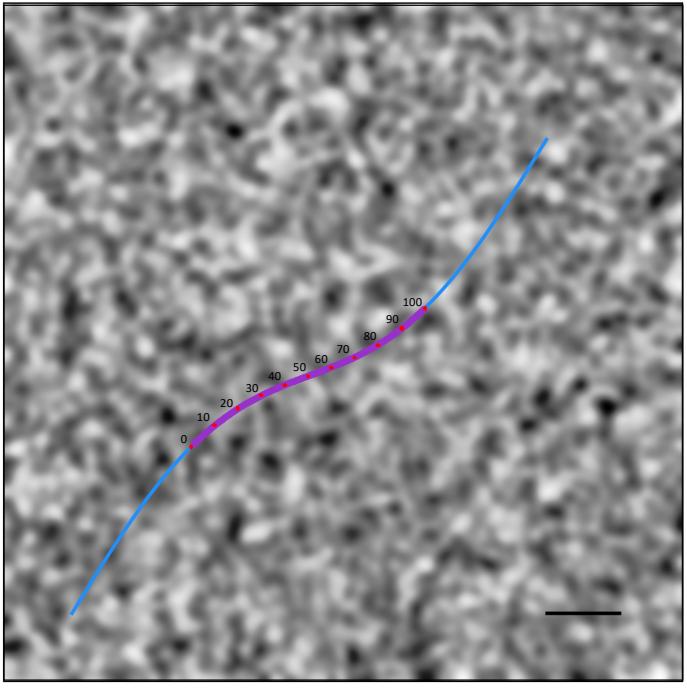
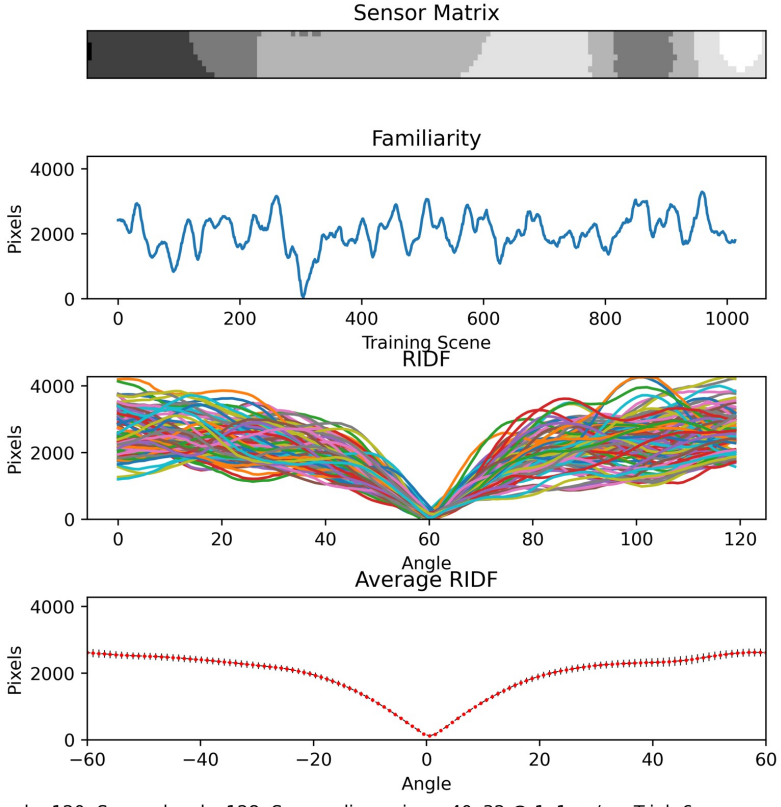
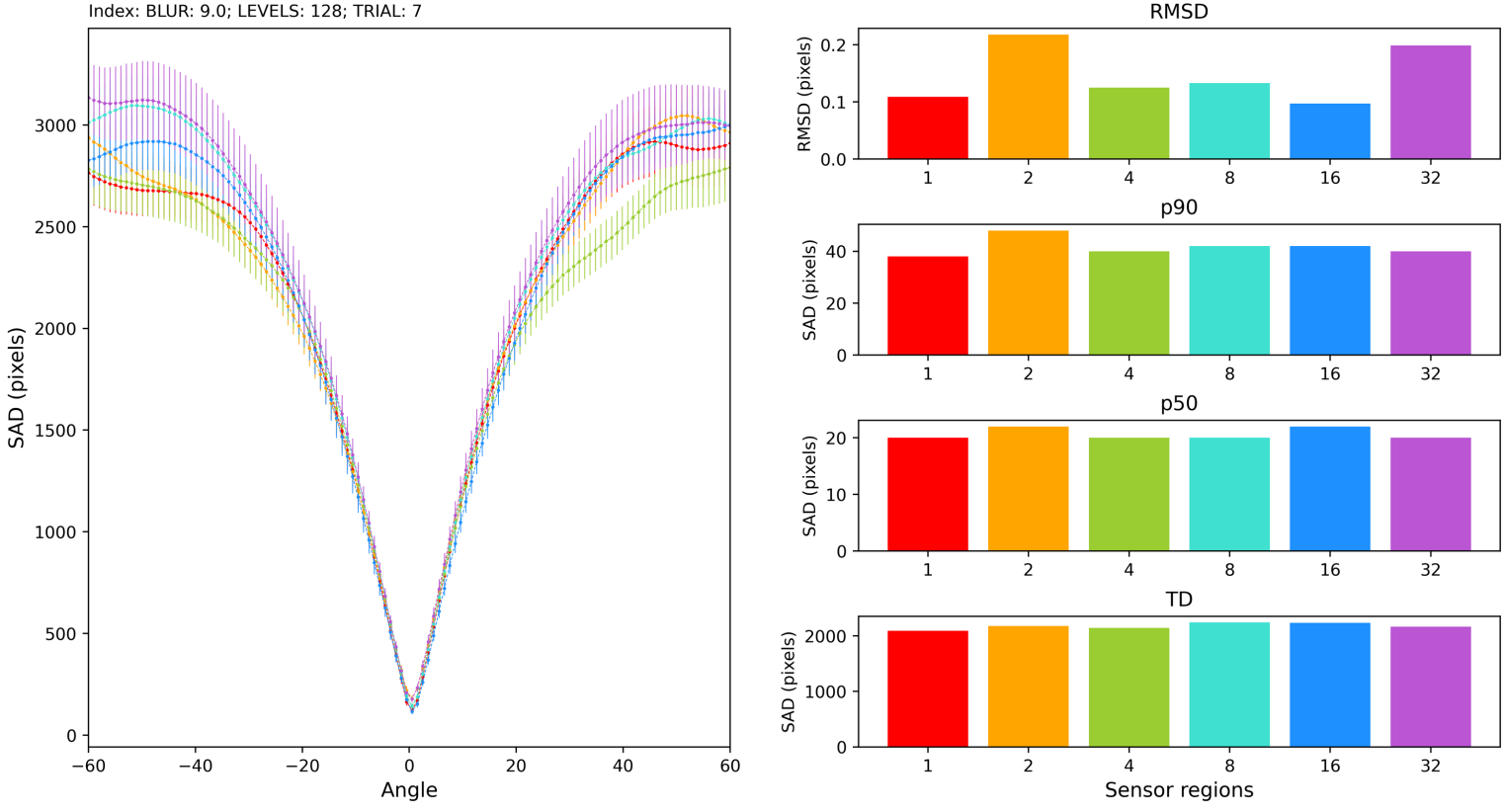
Navigation stats: RMSD error: 37.63; RMSD/dist: 0.094; TD: 2334; p90: 46; p50: 20; complete: 0

100%

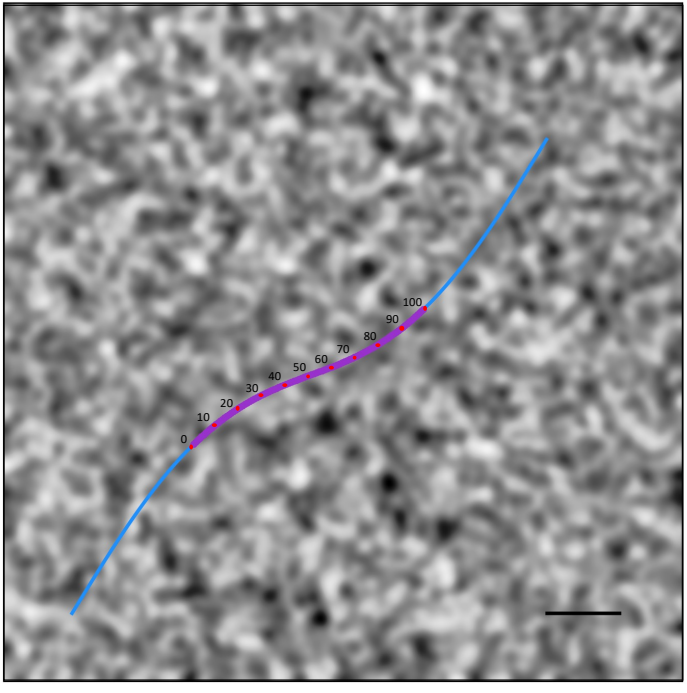


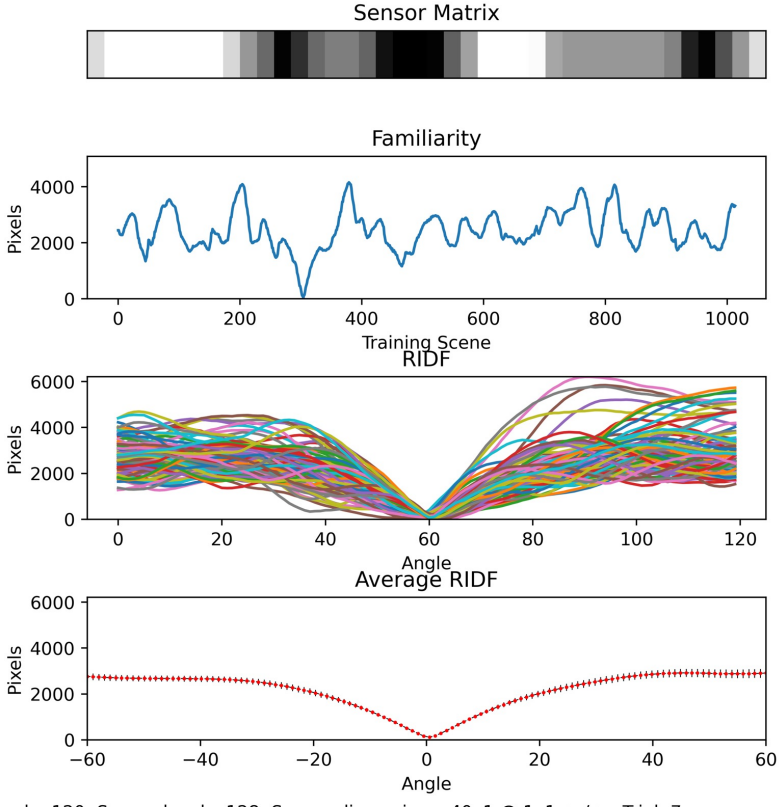




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 38.08; RMSD/dist: 0.095; TD: 2069; p90: 42; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 128; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

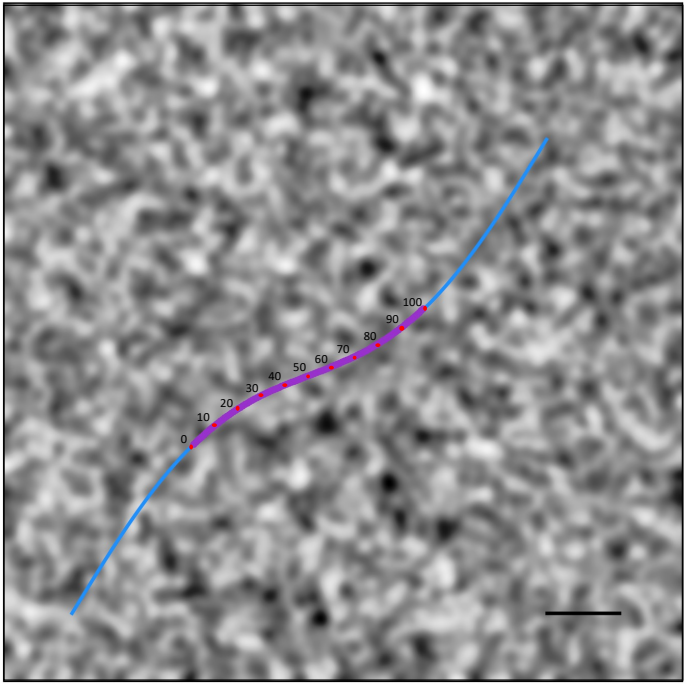
100%

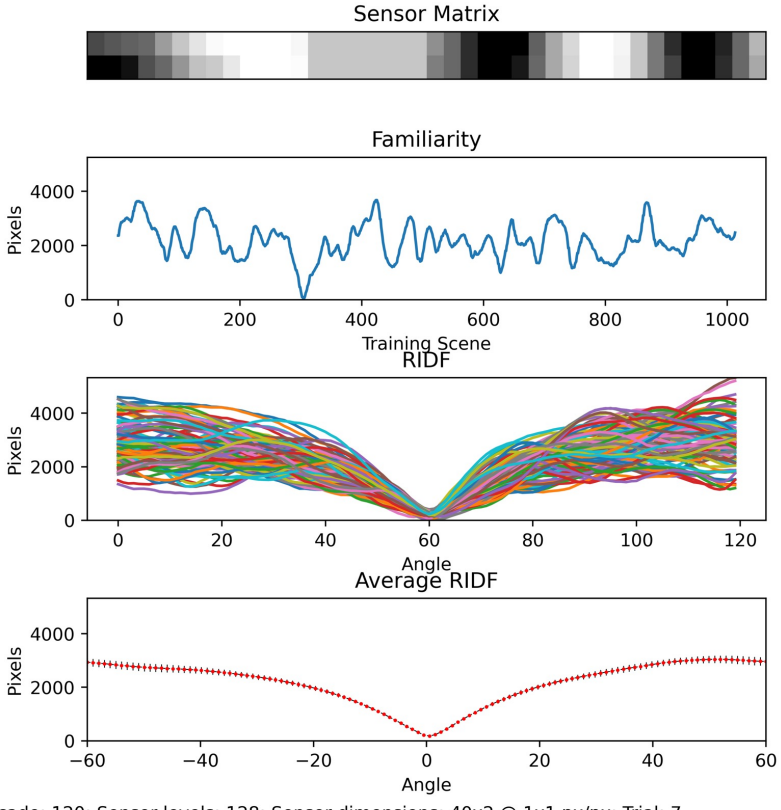



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 43.52; RMSD/dist: 0.109; TD: 2093; p90: 38; p50: 20; complete: 0

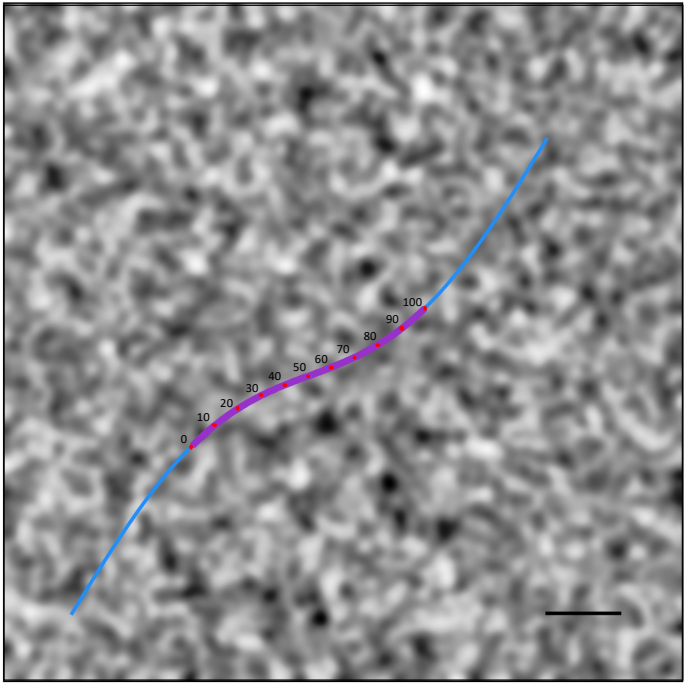
100%

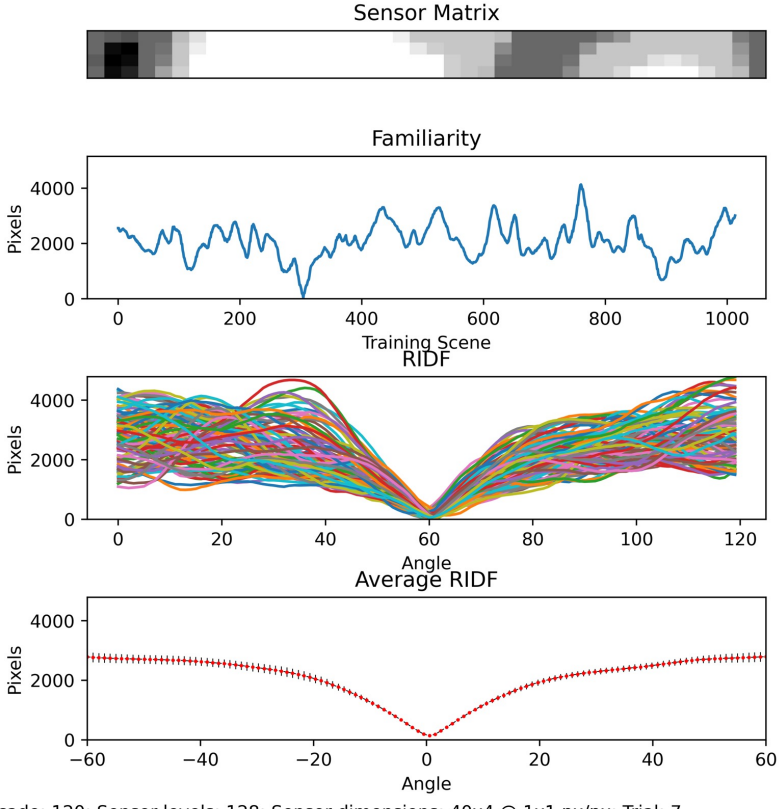



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 87.38; RMSD/dist: 0.218; TD: 2178; p90: 48; p50: 22; complete: 0

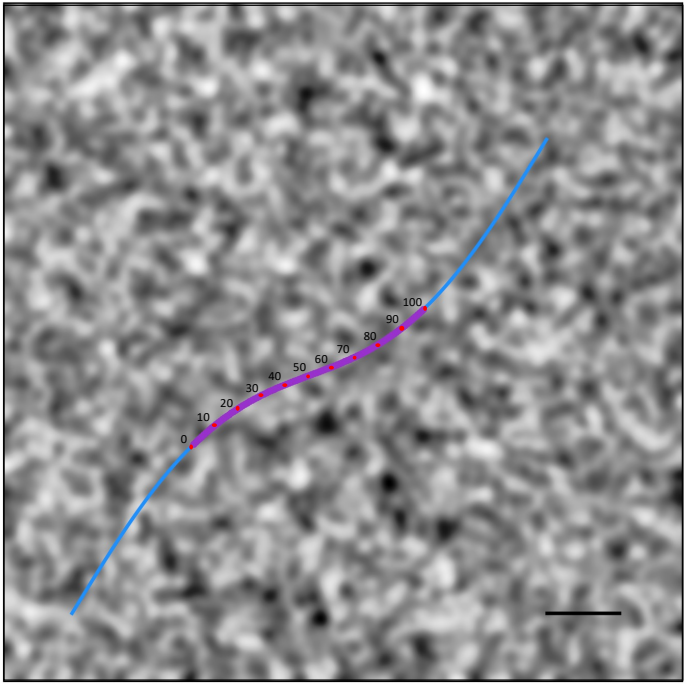
100%

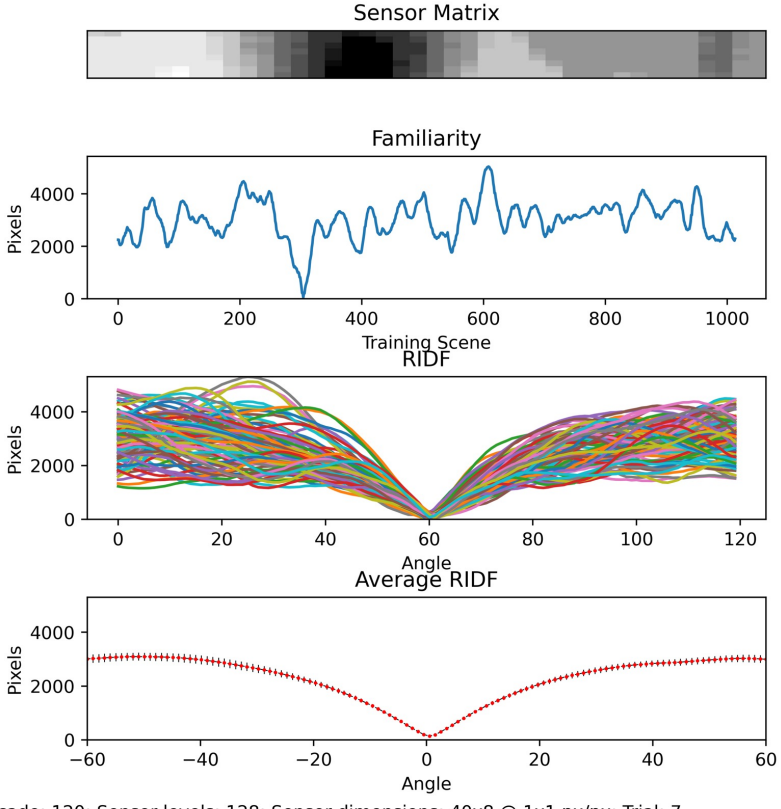



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 50.05; RMSD/dist: 0.125; TD: 2143; p90: 40; p50: 20; complete: 0

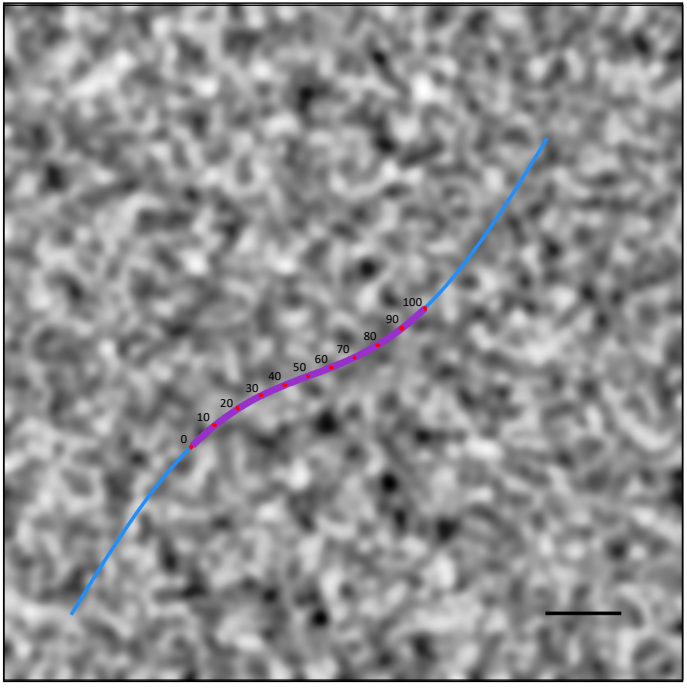
100%

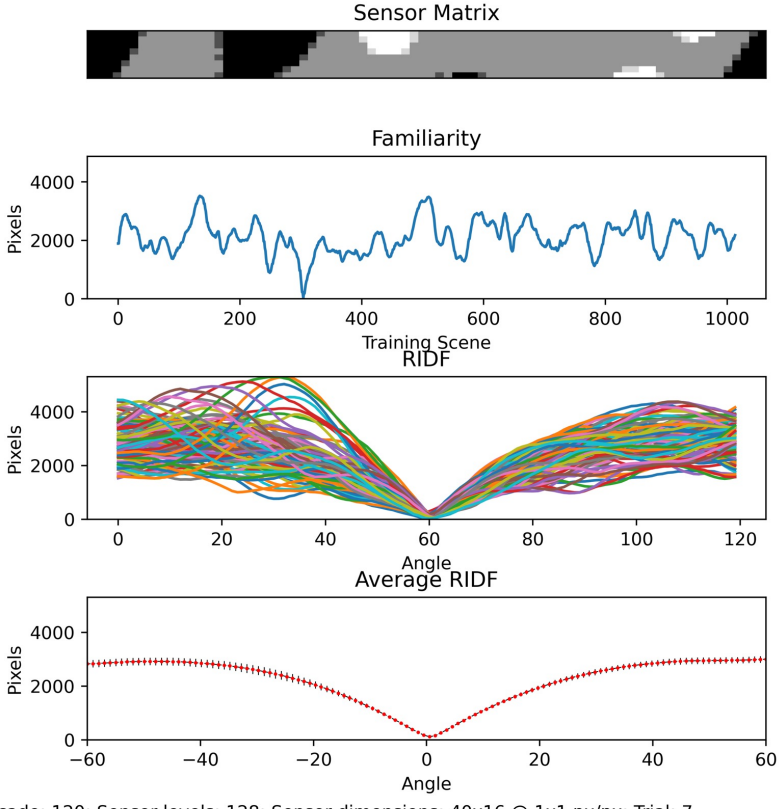



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 53.14; RMSD/dist: 0.133; TD: 2241; p90: 42; p50: 20; complete: 0

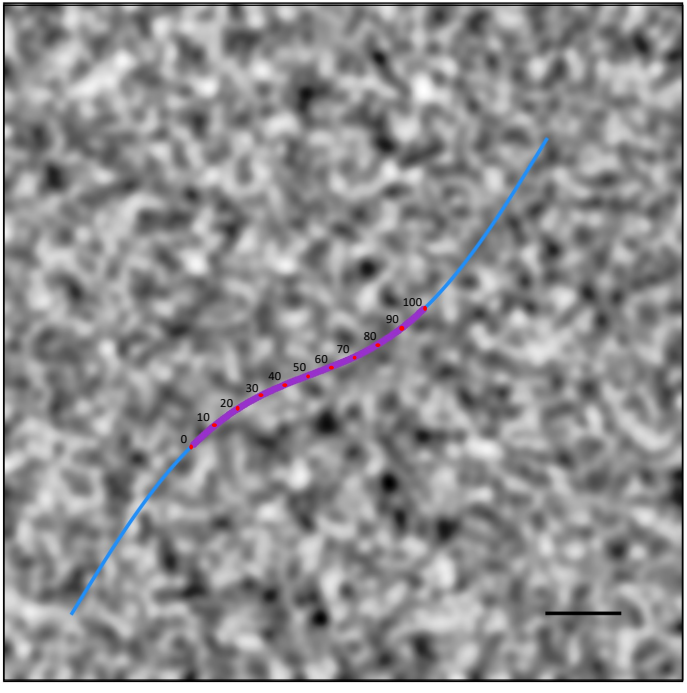
100%

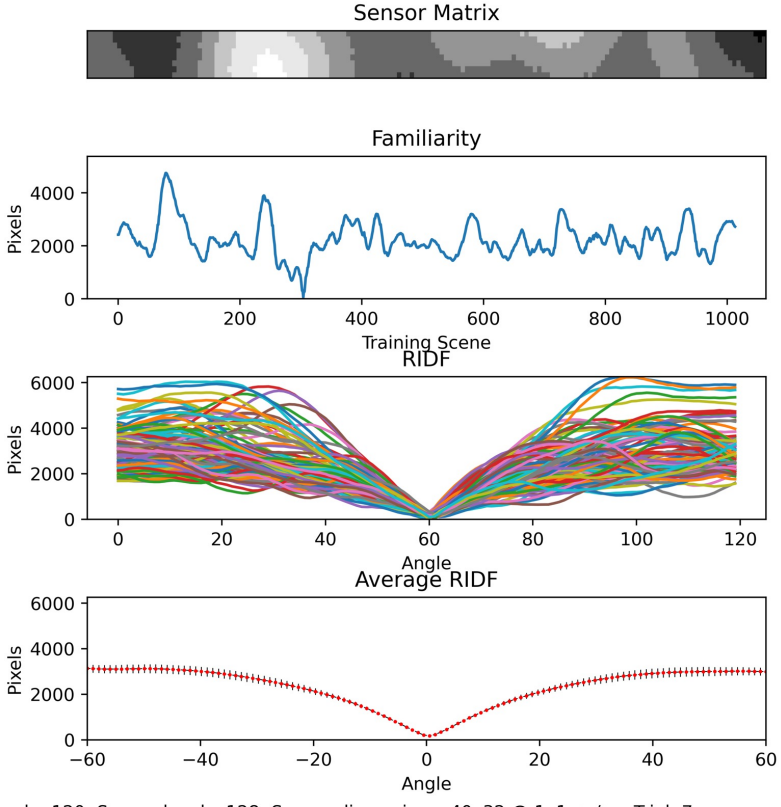



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 38.78; RMSD/dist: 0.097; TD: 2235; p90: 42; p50: 22; complete: 0

100%

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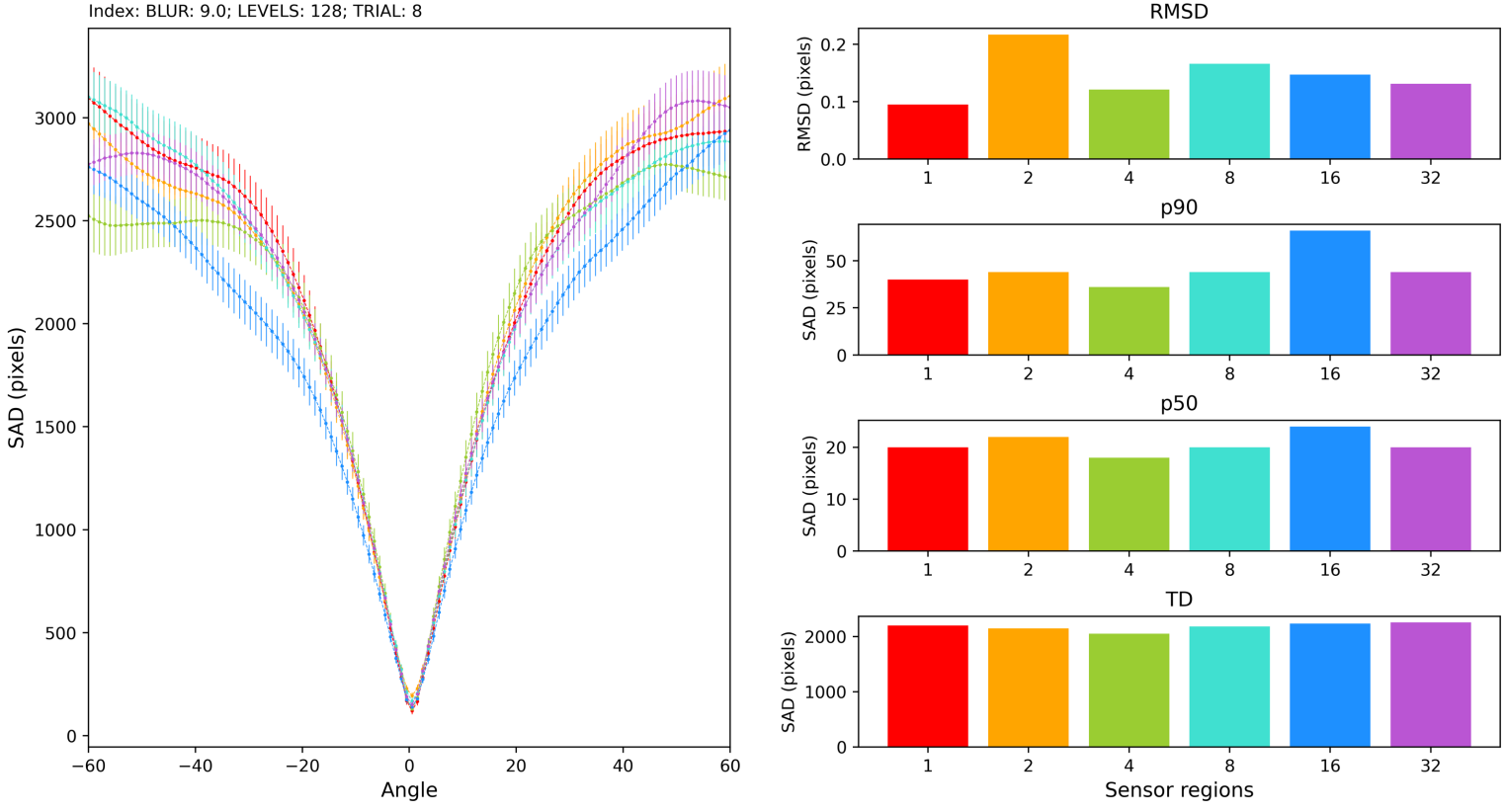
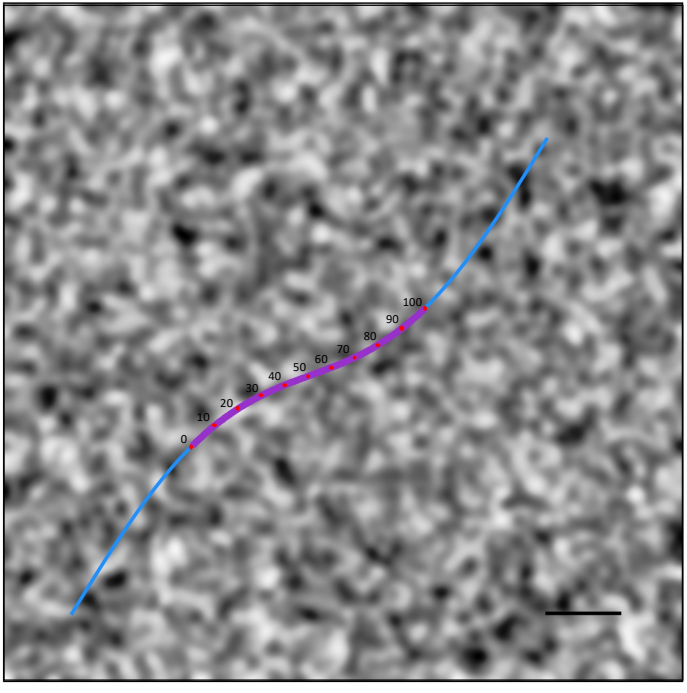
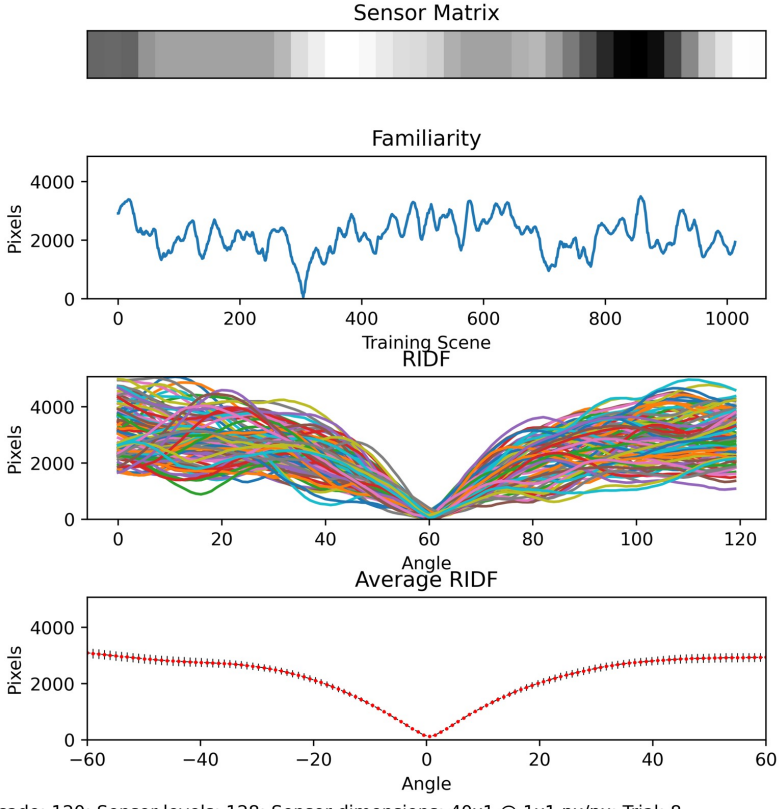
Navigation stats: RMSD error: 79.66; RMSD/dist: 0.199; TD: 2163; p90: 40; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 128; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

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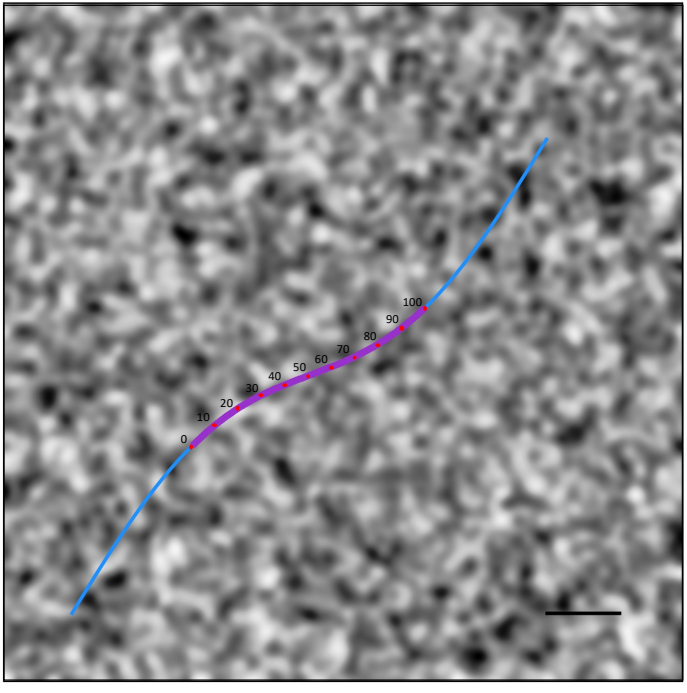
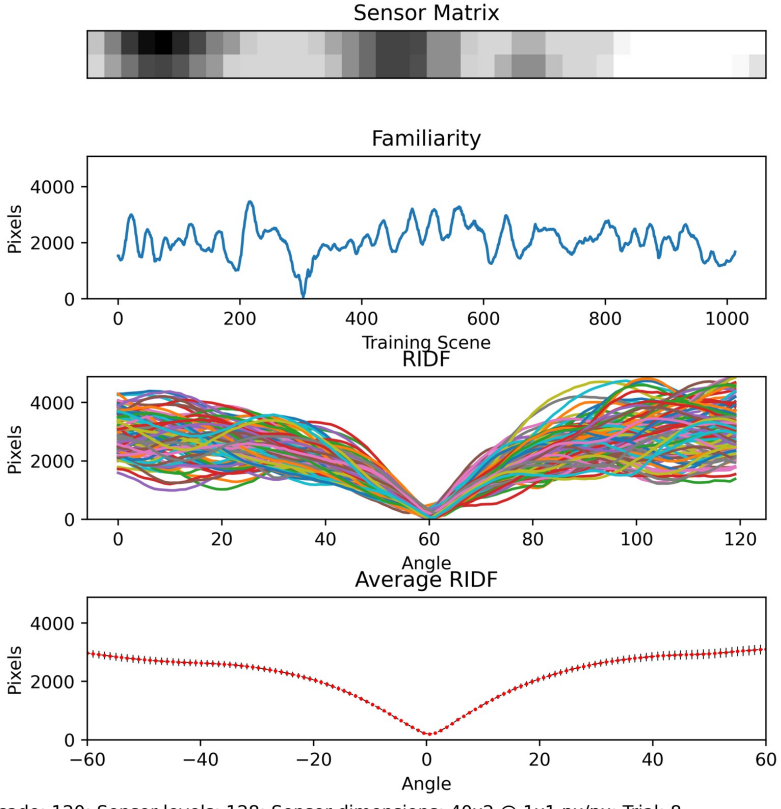
Navigation stats: RMSD error: 38.16; RMSD/dist: 0.095; TD: 2198; p90: 40; p50: 20; complete: 0

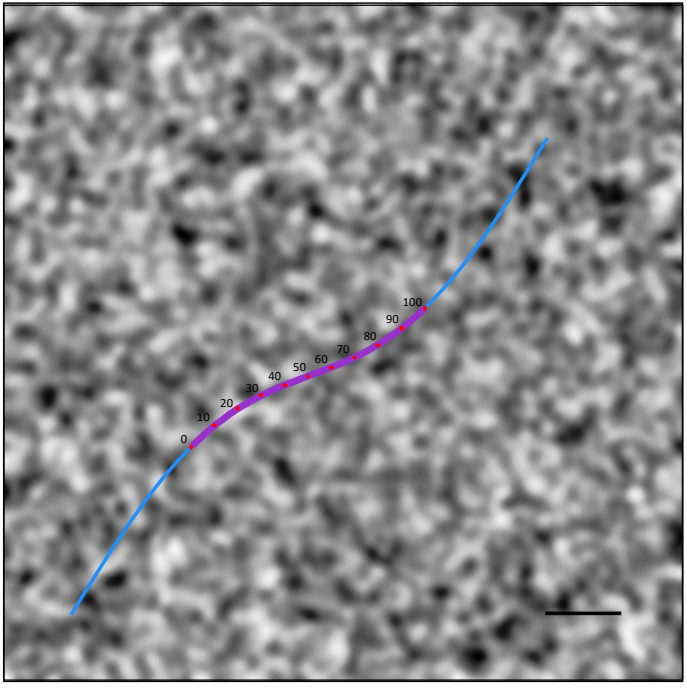
100%

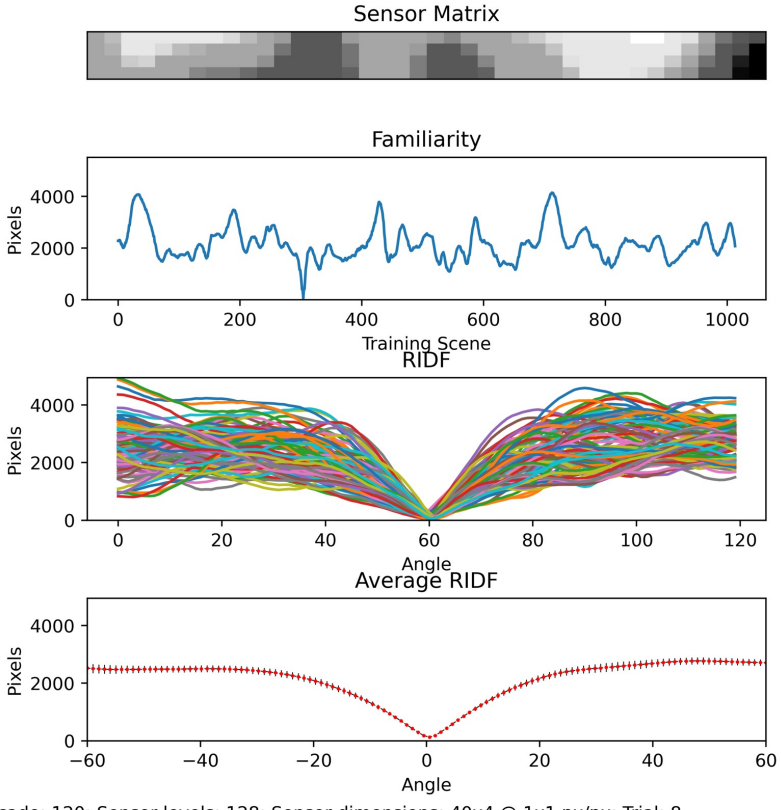



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 86.89; RMSD/dist: 0.217; TD: 2148; p90: 44; p50: 22; complete: 0

100%

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Navigation stats: RMSD error: 48.24; RMSD/dist: 0.121; TD: 2051; p90: 36; p50: 18; complete: 0

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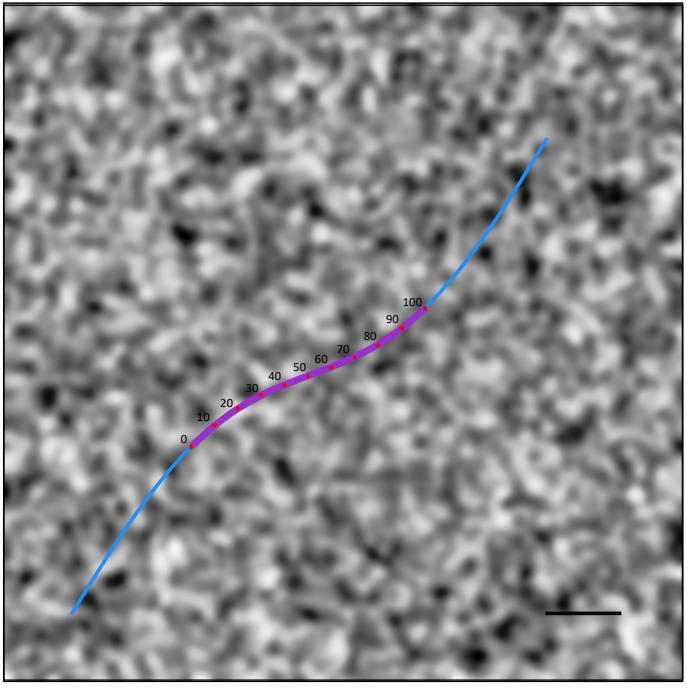


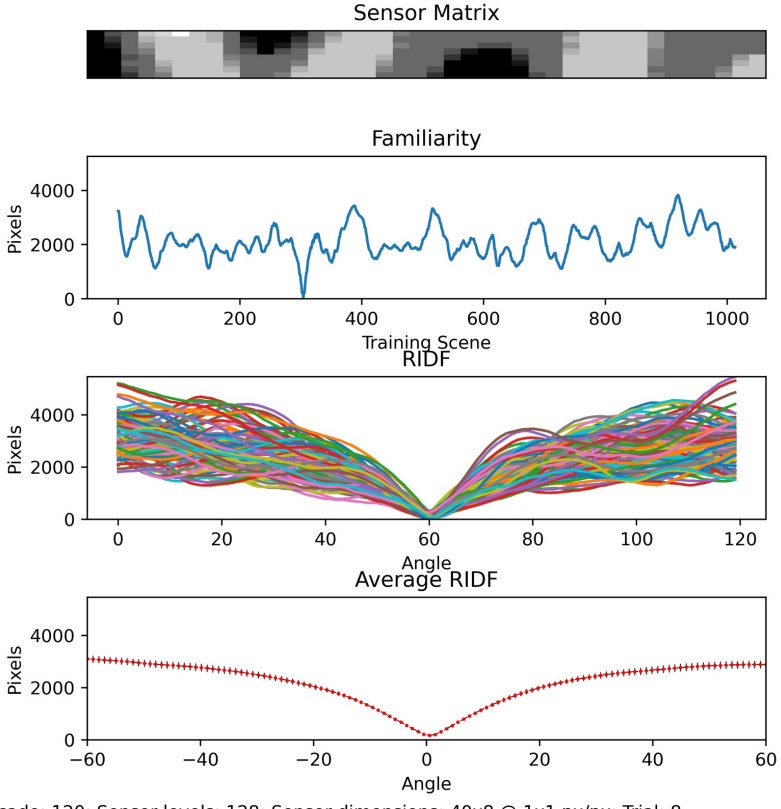


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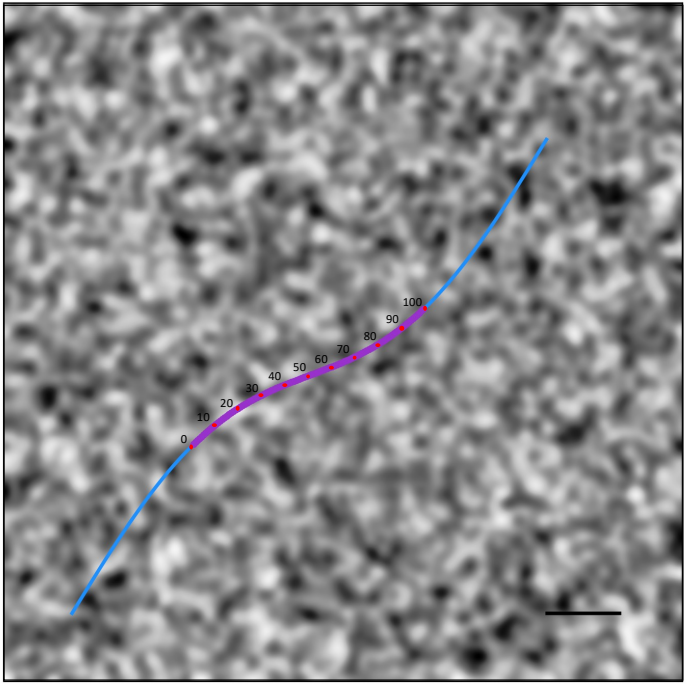
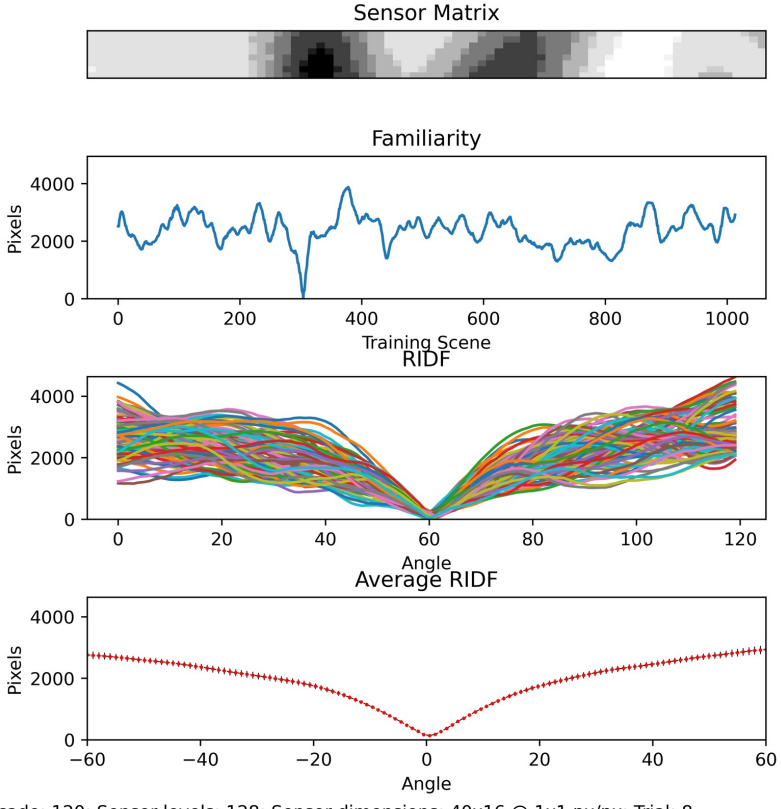
Navigation stats: RMSD error: 66.21; RMSD/dist: 0.166; TD: 2183; p90: 44; p50: 20; complete: 0

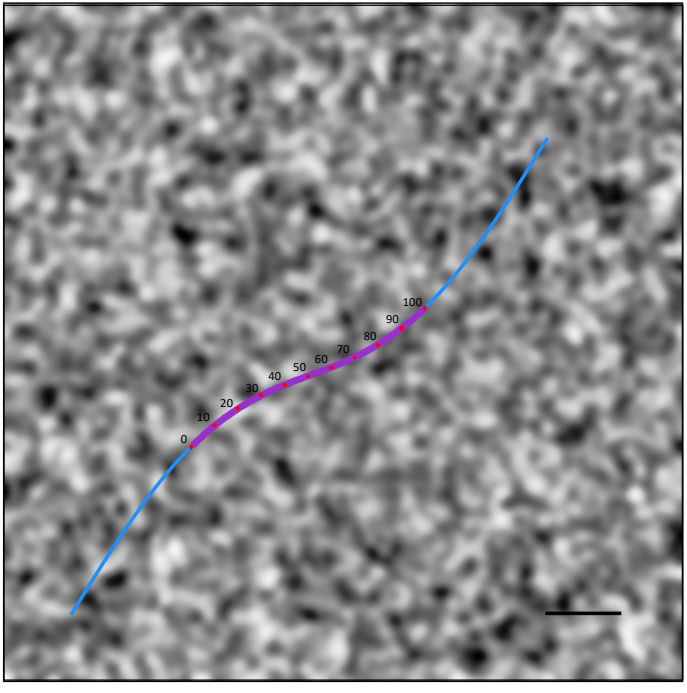
100%

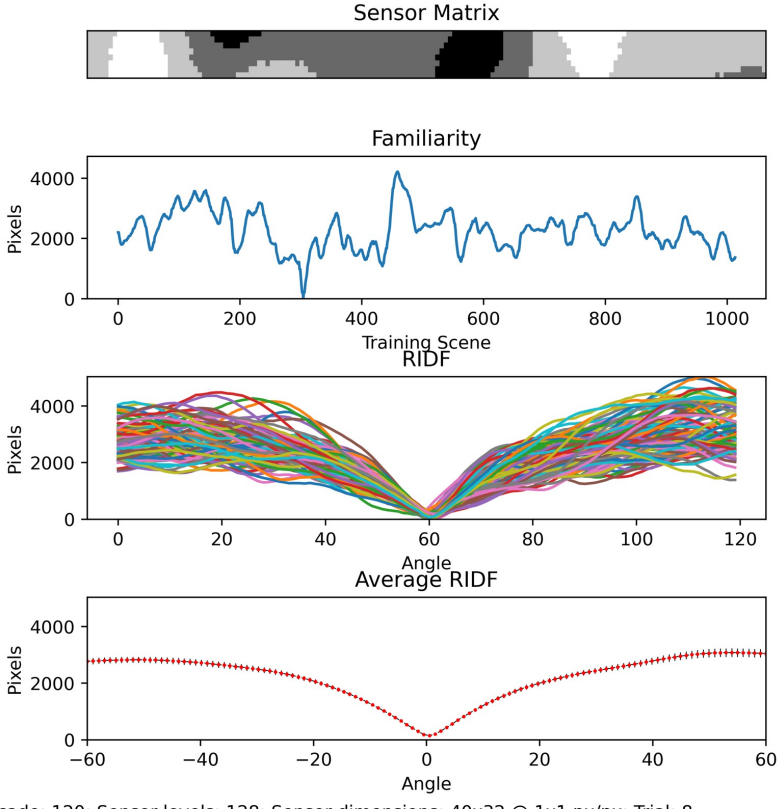



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 58.96; RMSD/dist: 0.147; TD: 2234; p90: 66; p50: 24; complete: 0

100%

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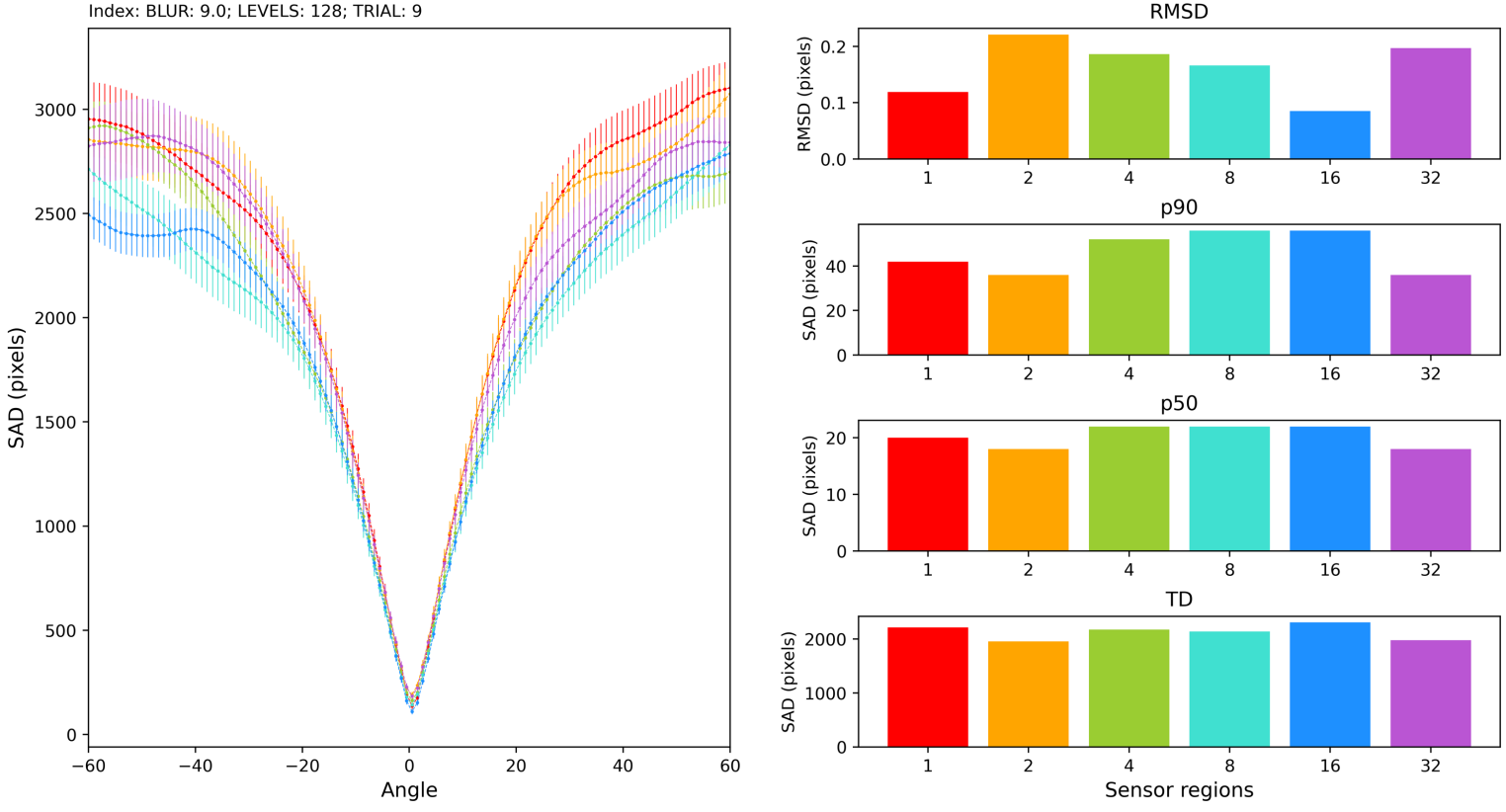
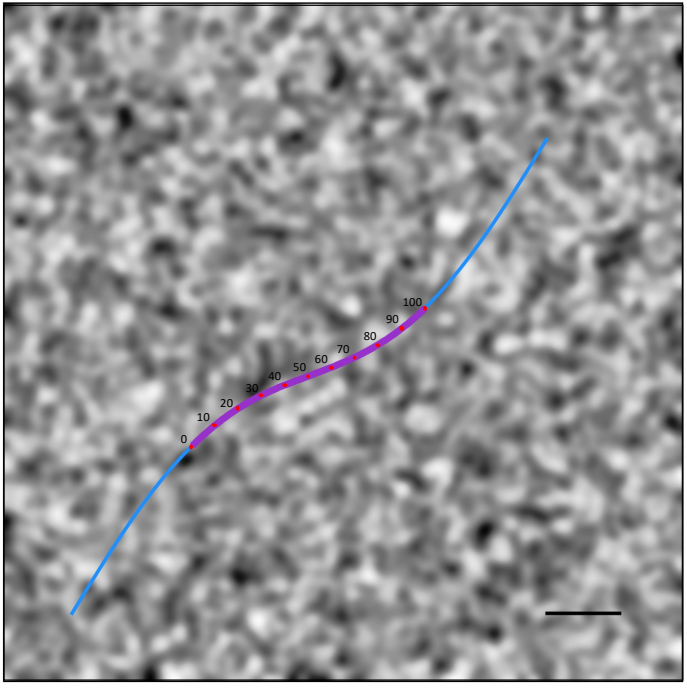
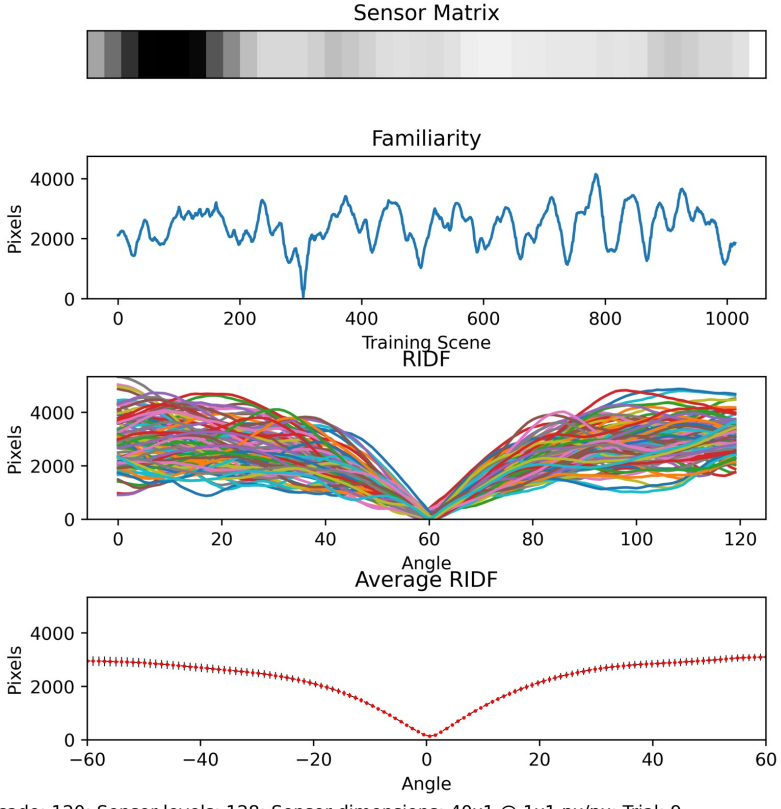

Index: BLUR: 9.0; LEVELS: 128; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

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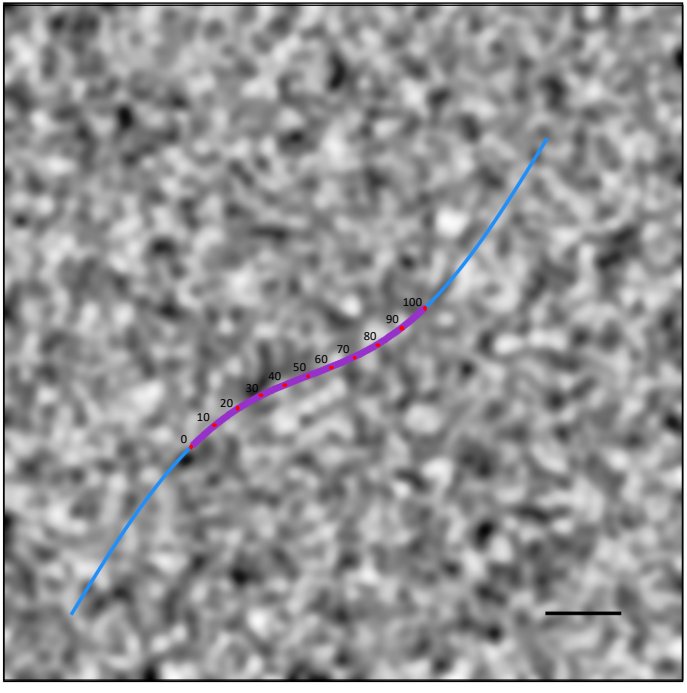
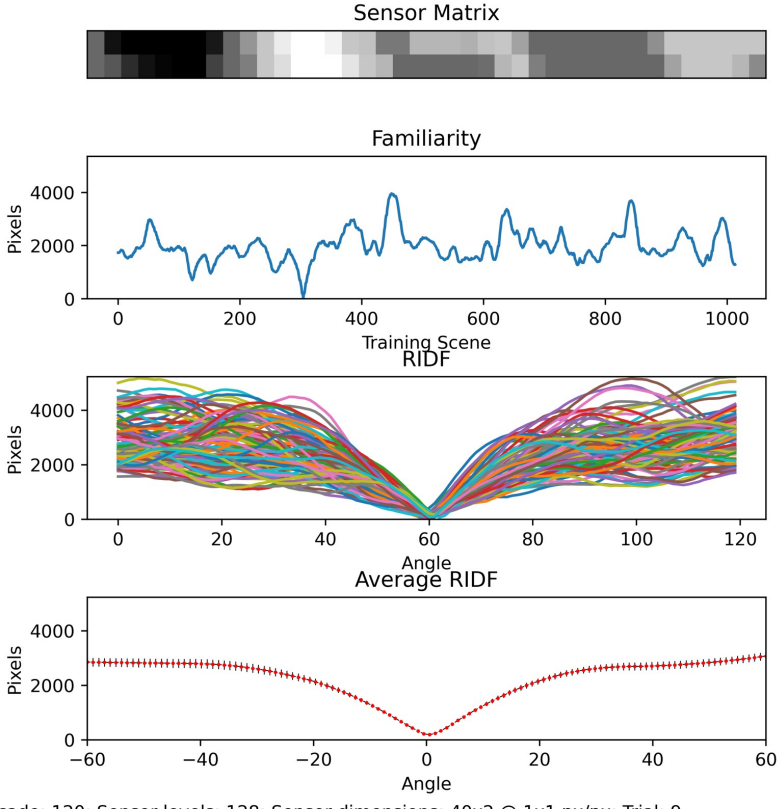
Navigation stats: RMSD error: 47.53; RMSD/dist: 0.119; TD: 2217; p90: 42; p50: 20; complete: 0

100%

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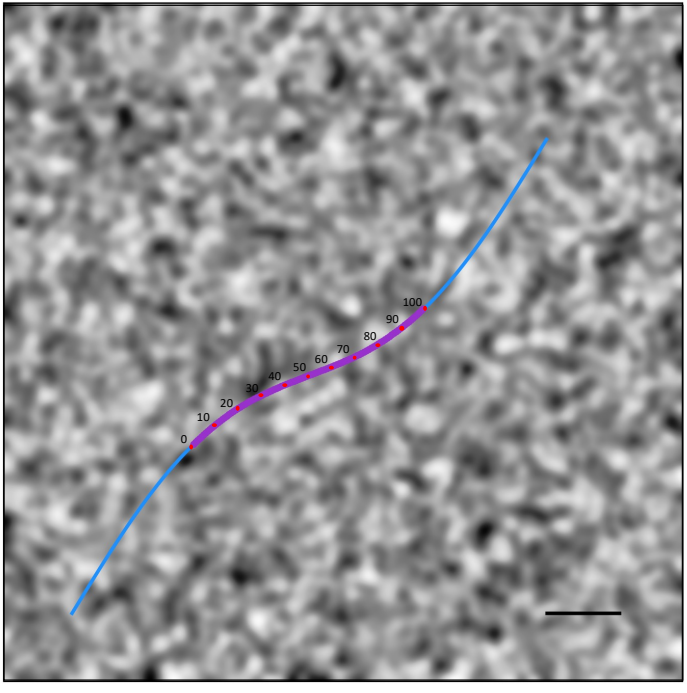
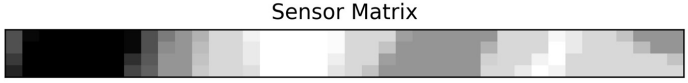
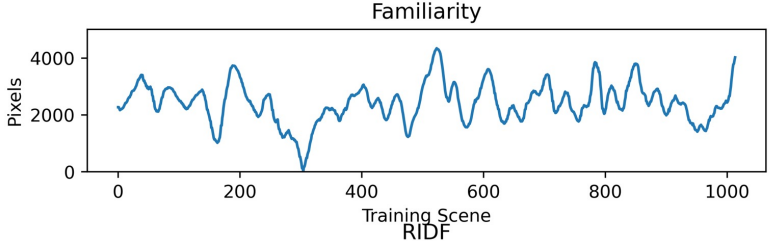
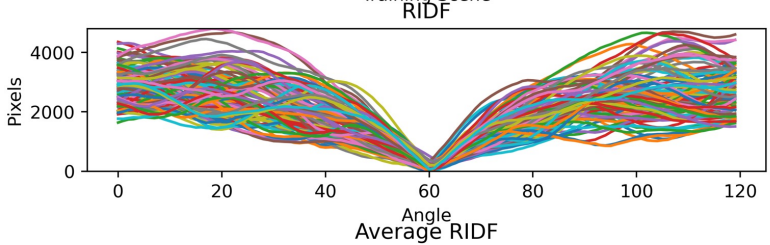
Navigation stats: RMSD error: 88.25; RMSD/dist: 0.221; TD: 1957; p90: 36; p50: 18; complete: 0

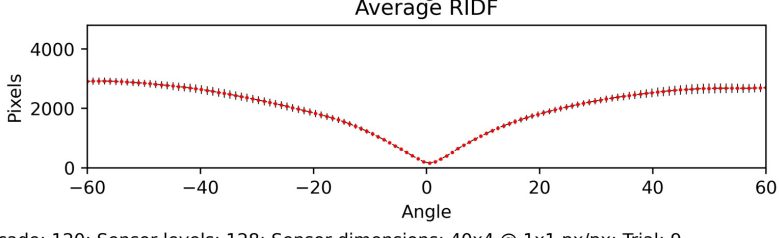
100%



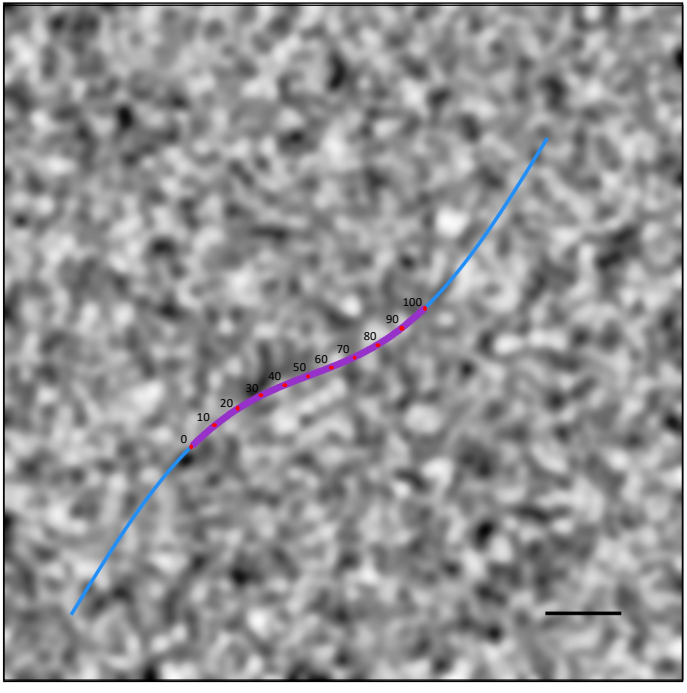



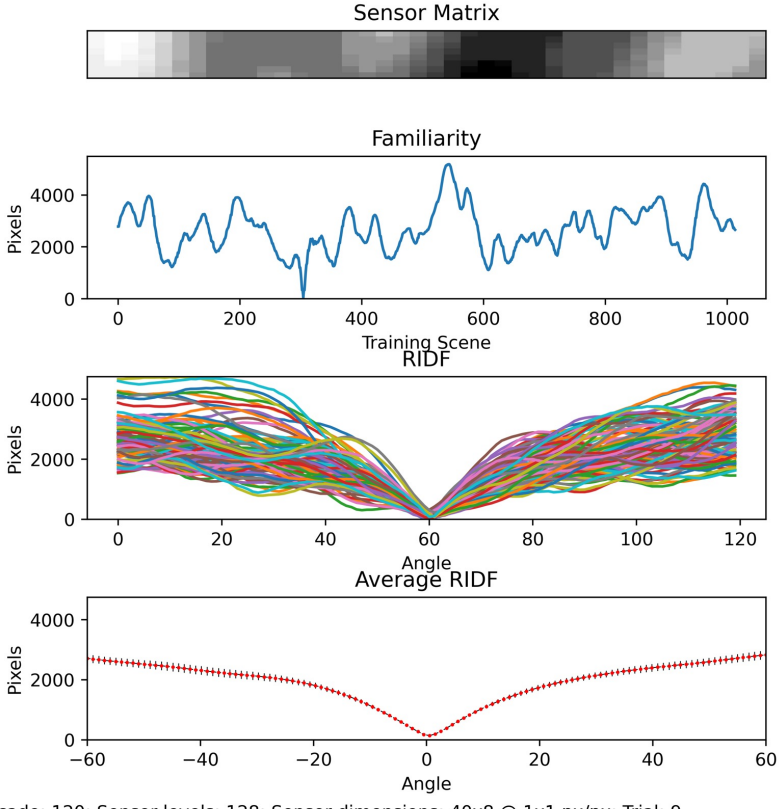




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 74.50; RMSD/dist: 0.186; TD: 2174; p90: 52; p50: 22; complete: 0

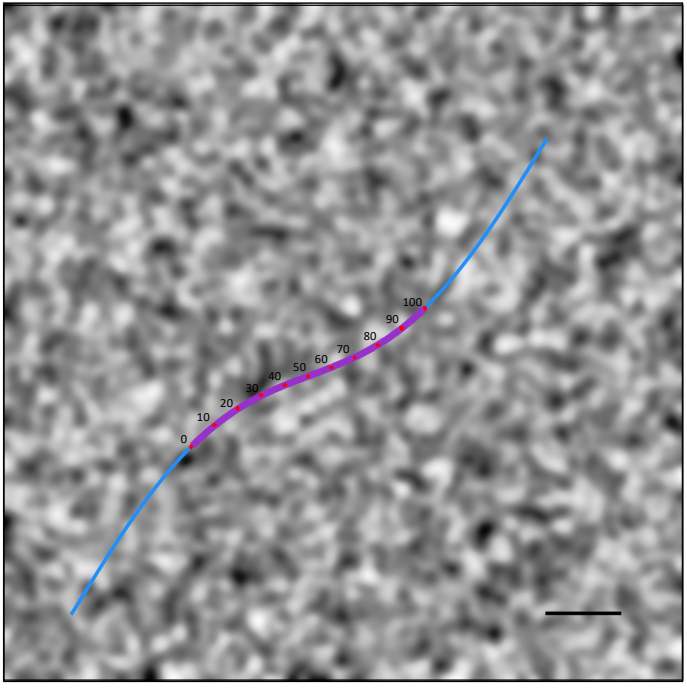
100%

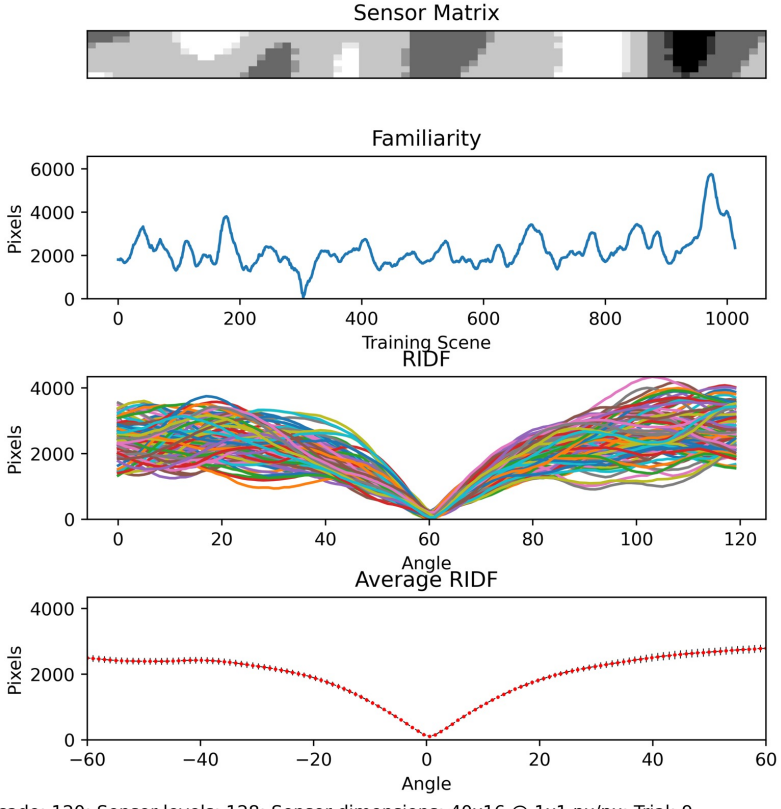



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 66.48; RMSD/dist: 0.166; TD: 2140; p90: 56; p50: 22; complete: 0

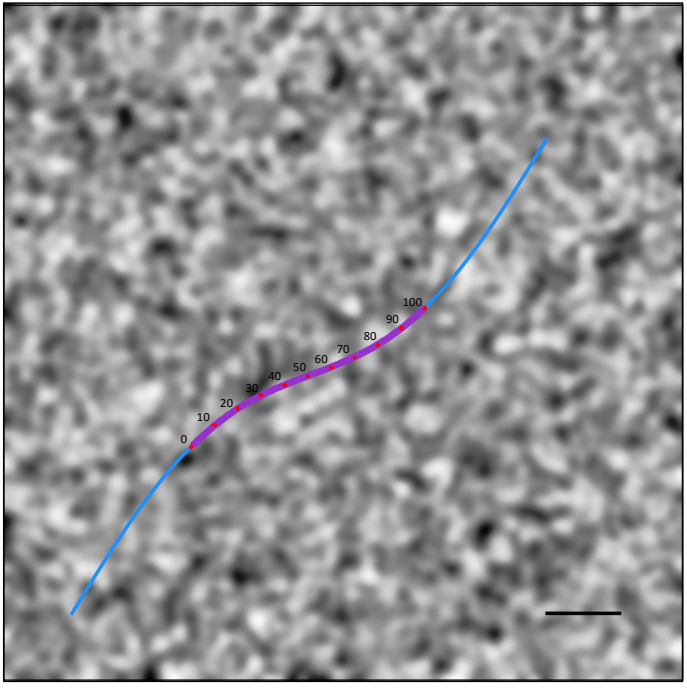
100%

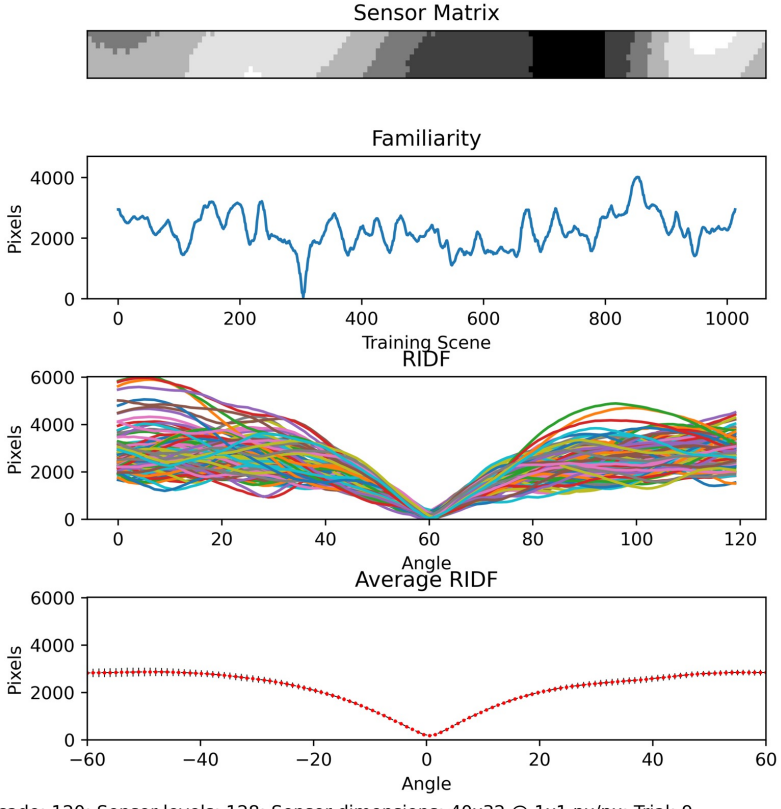


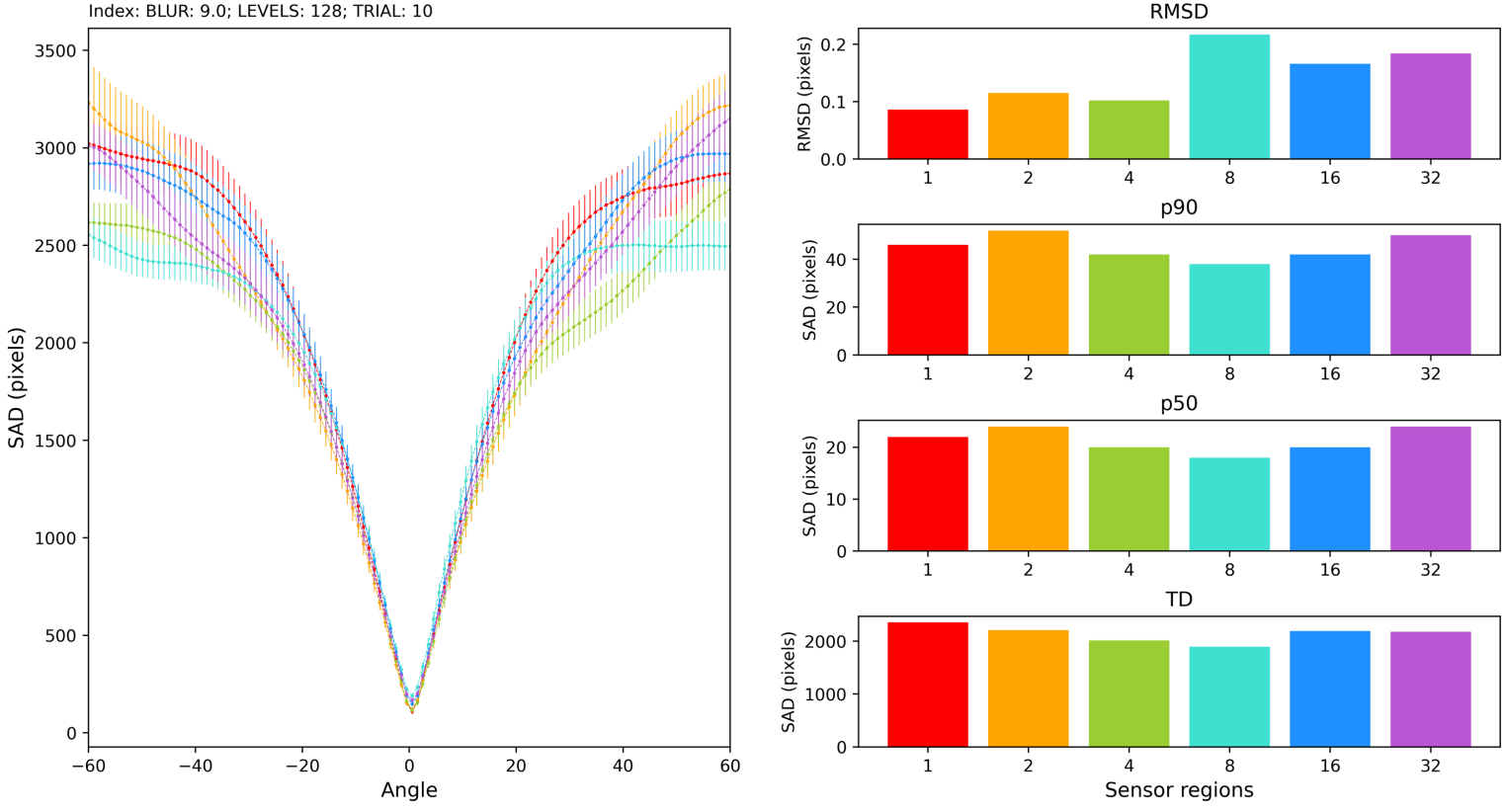

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 33.81; RMSD/dist: 0.085; TD: 2308; p90: 56; p50: 22; complete: 0

100%

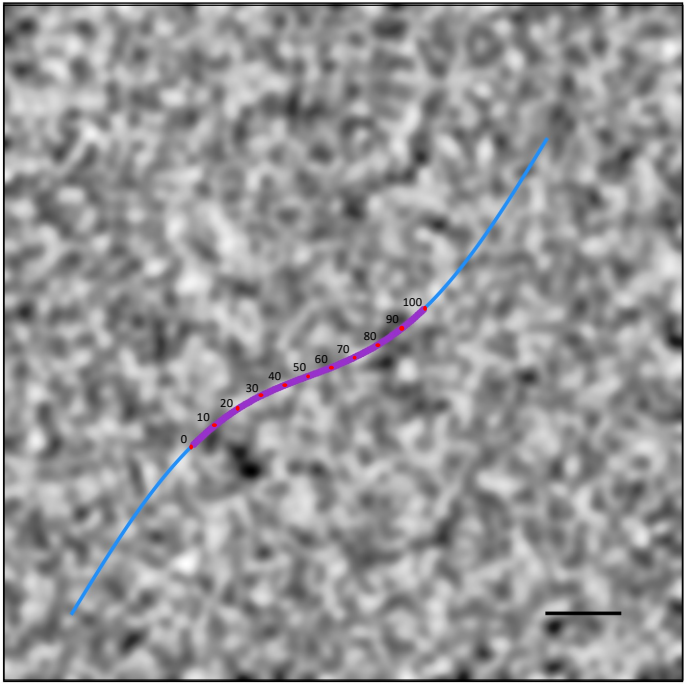


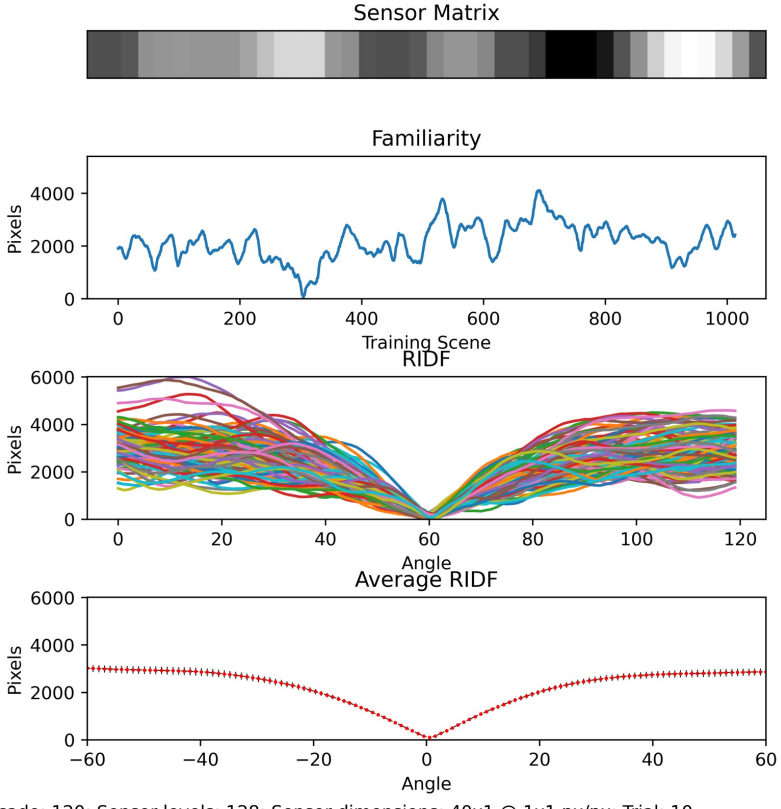




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 78.67; RMSD/dist: 0.197; TD: 1977; p90: 36; p50: 18; complete: 0


Index: BLUR: 9.0; LEVELS: 128; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

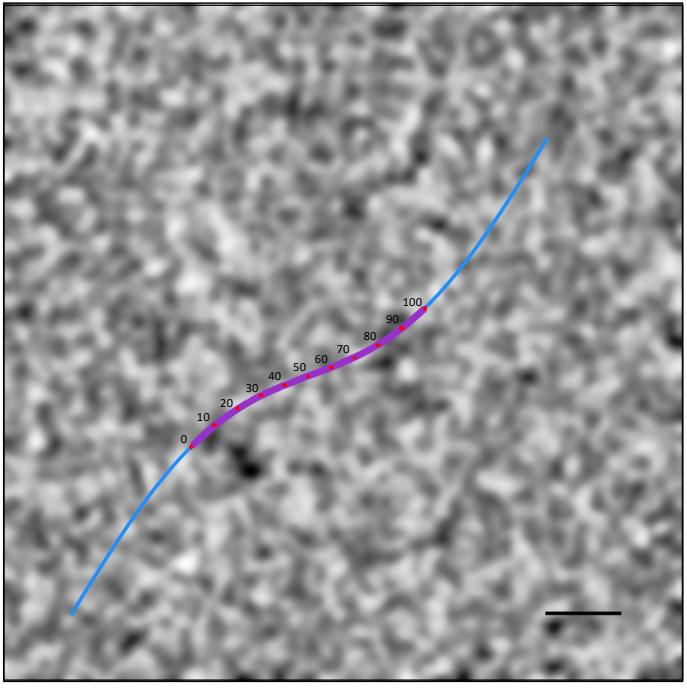
100%

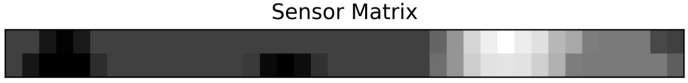


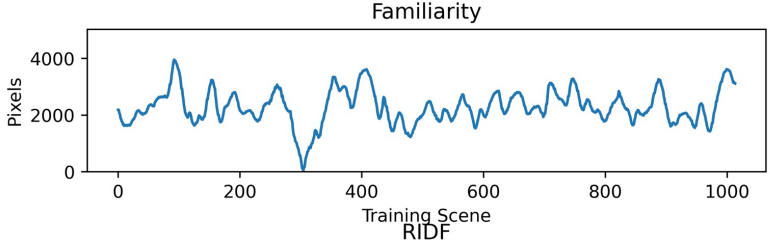



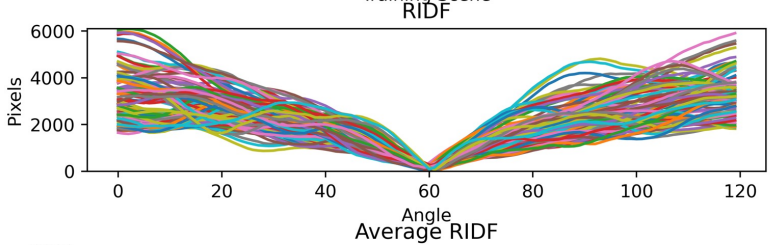

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 34.41; RMSD/dist: 0.086; TD: 2355; p90: 46; p50: 22; complete: 0

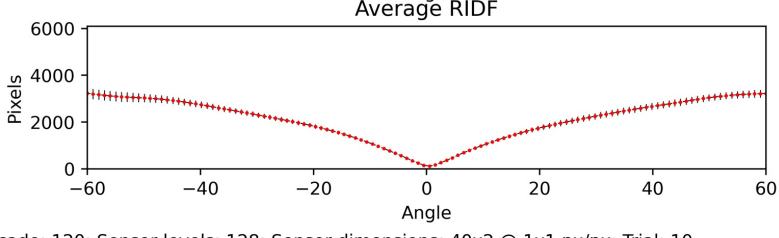
100%



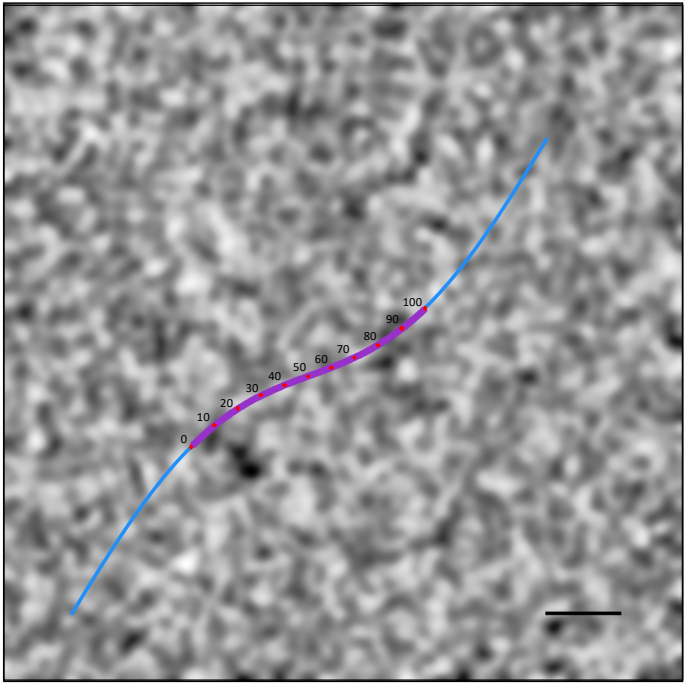



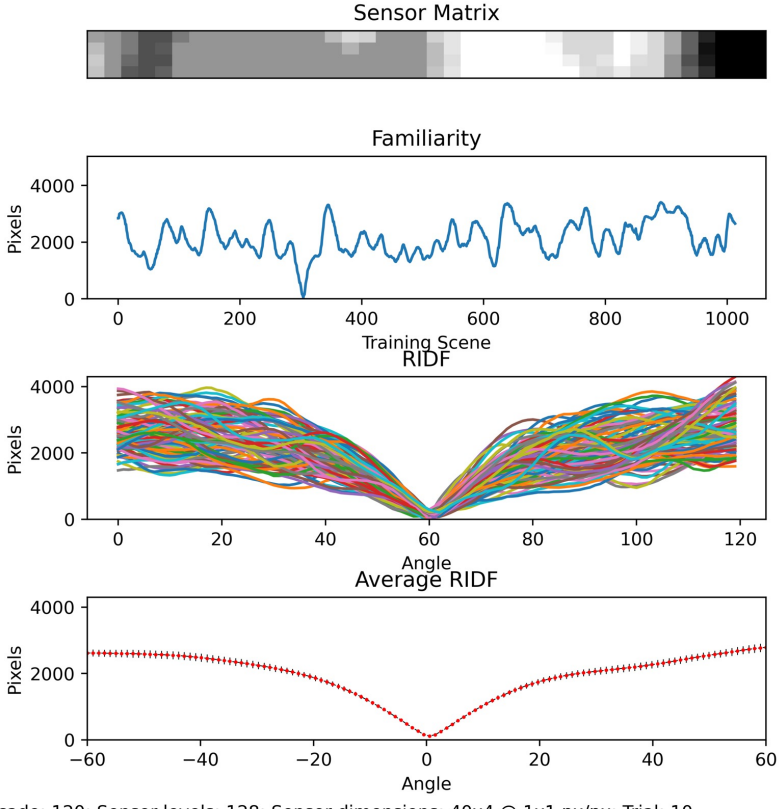




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 46.08; RMSD/dist: 0.115; TD: 2209; p90: 52; p50: 24; complete: 0

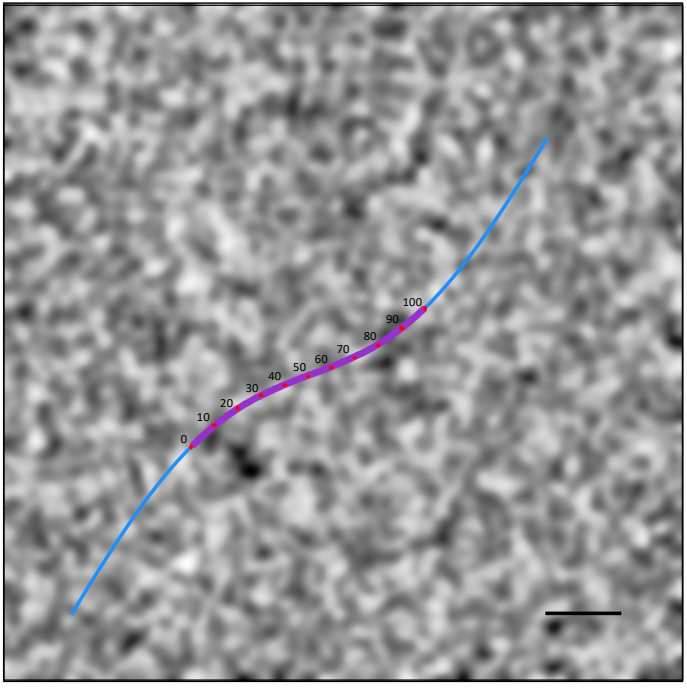
100%

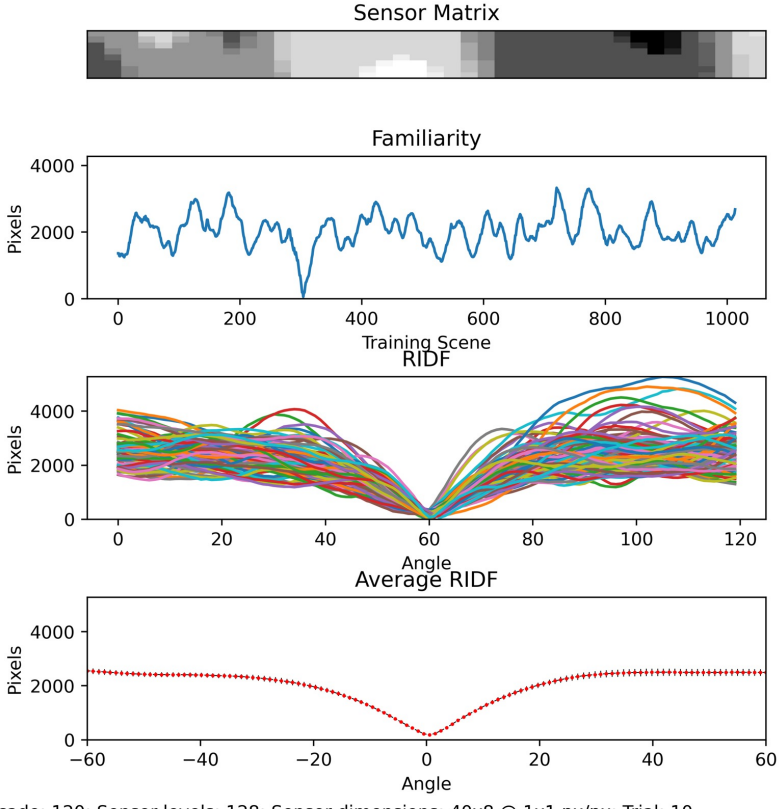



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 40.99; RMSD/dist: 0.102; TD: 2014; p90: 42; p50: 20; complete: 0

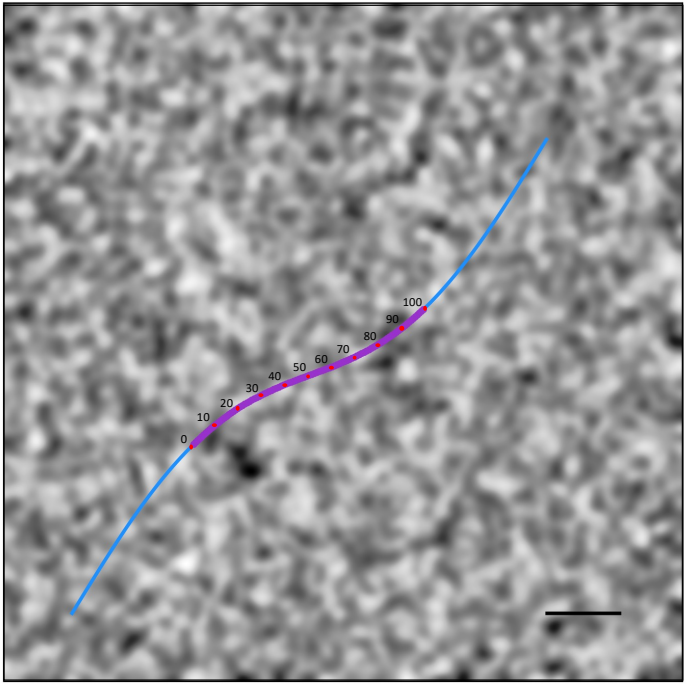
100%

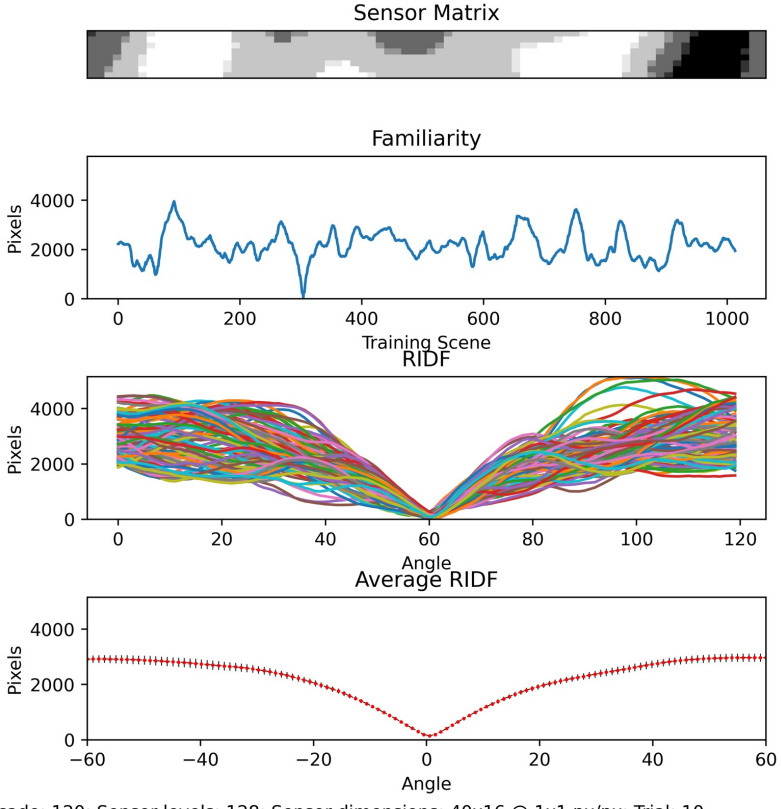



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 86.63; RMSD/dist: 0.217; TD: 1895; p90: 38; p50: 18; complete: 0

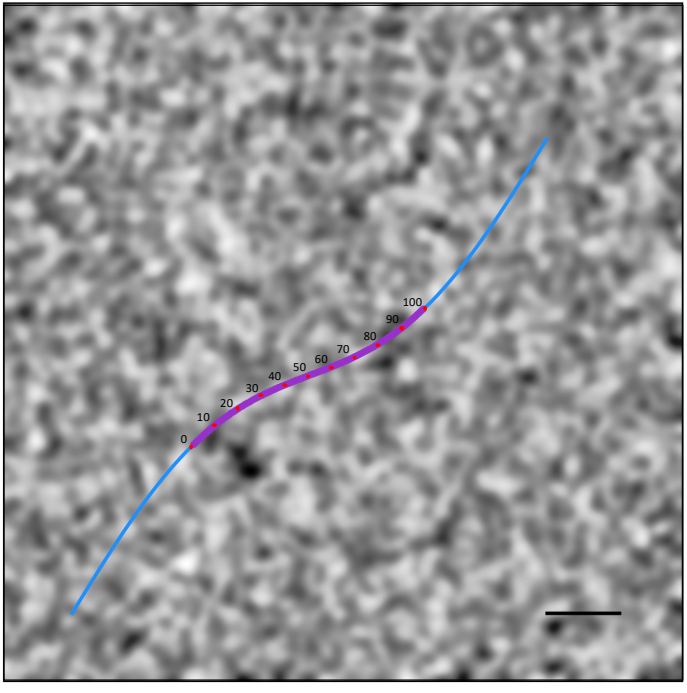
100%

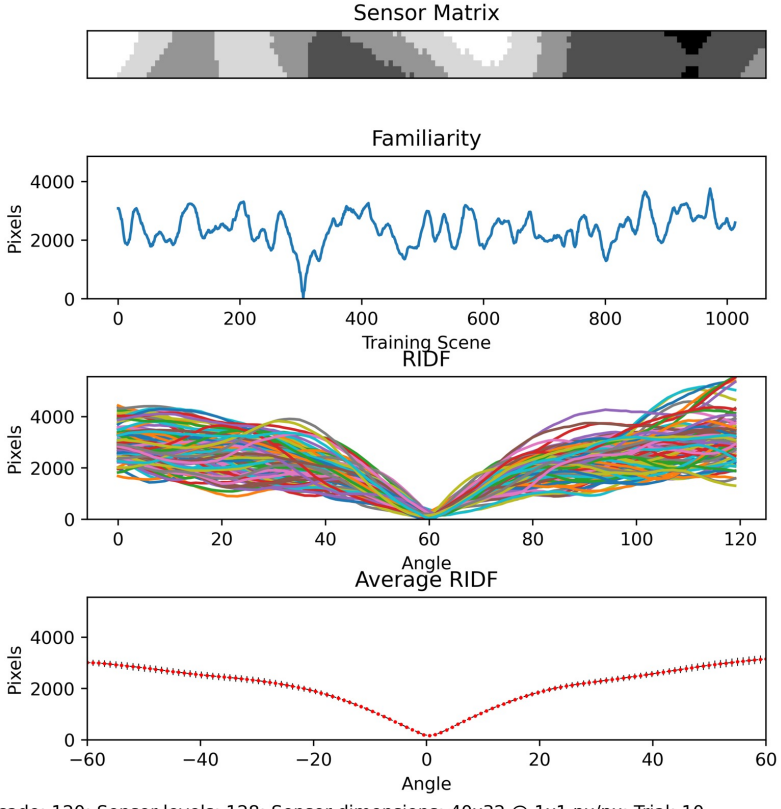



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 66.38; RMSD/dist: 0.166; TD: 2194; p90: 42; p50: 20; complete: 0

100%




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 73.52; RMSD/dist: 0.184; TD: 2181; p90: 50; p50: 24; complete: 0