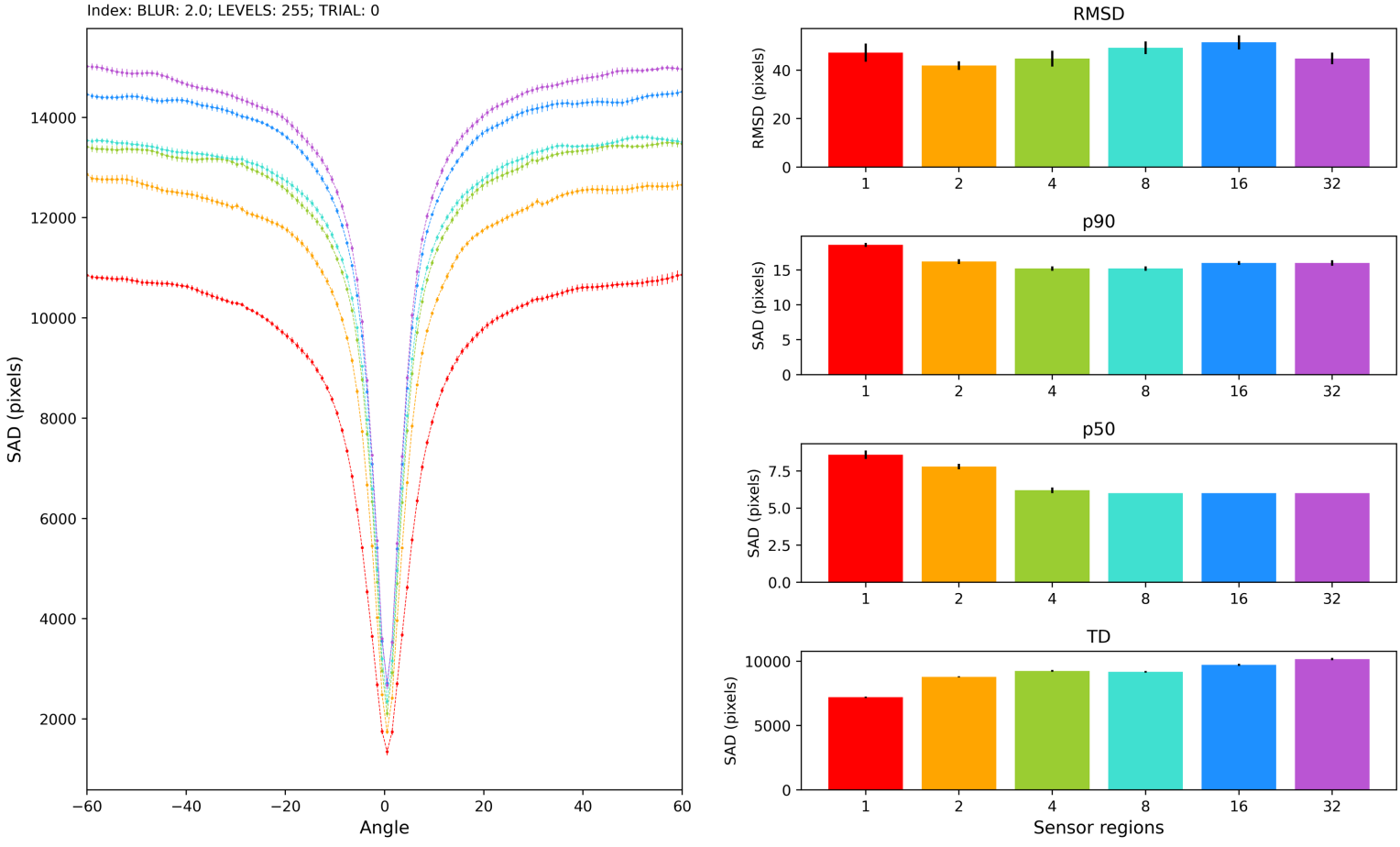
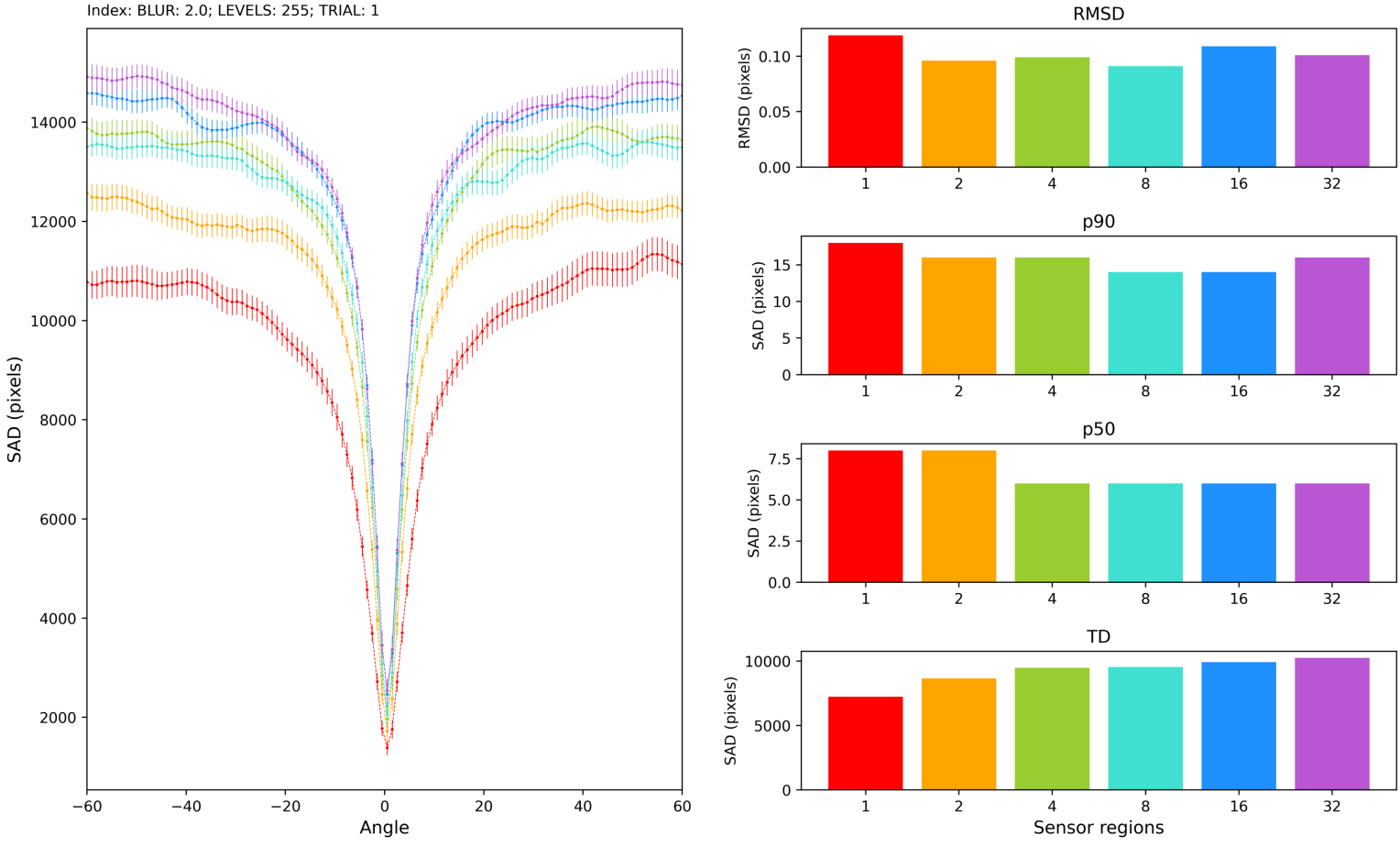

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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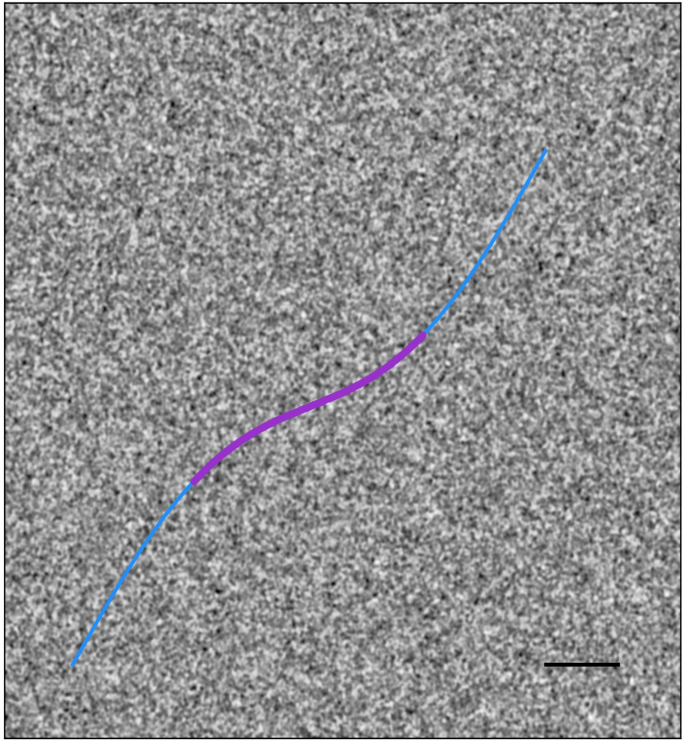
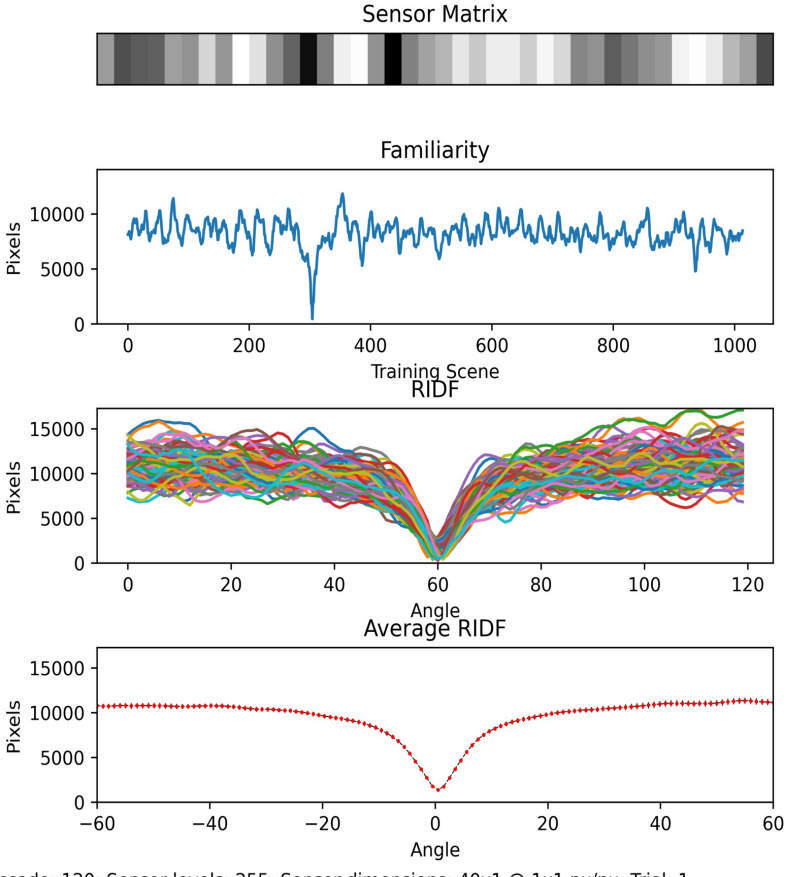
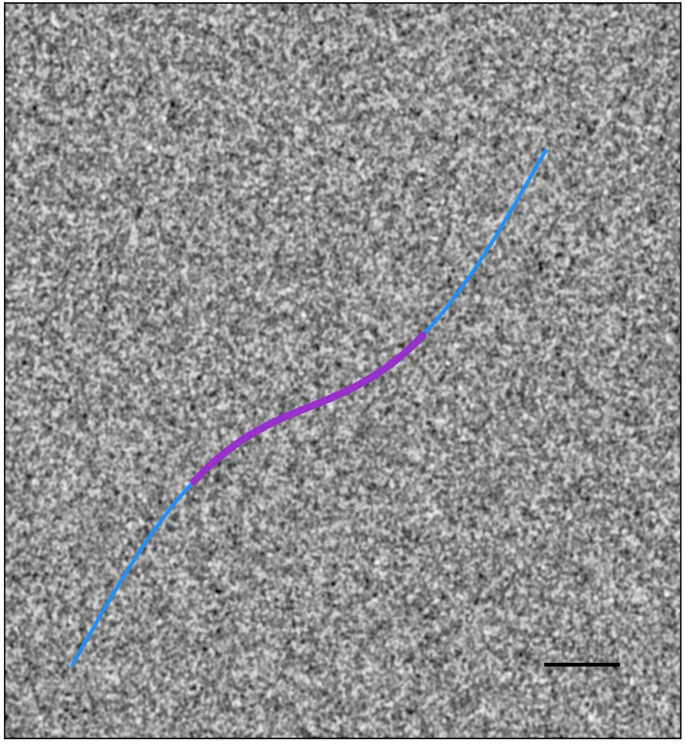
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

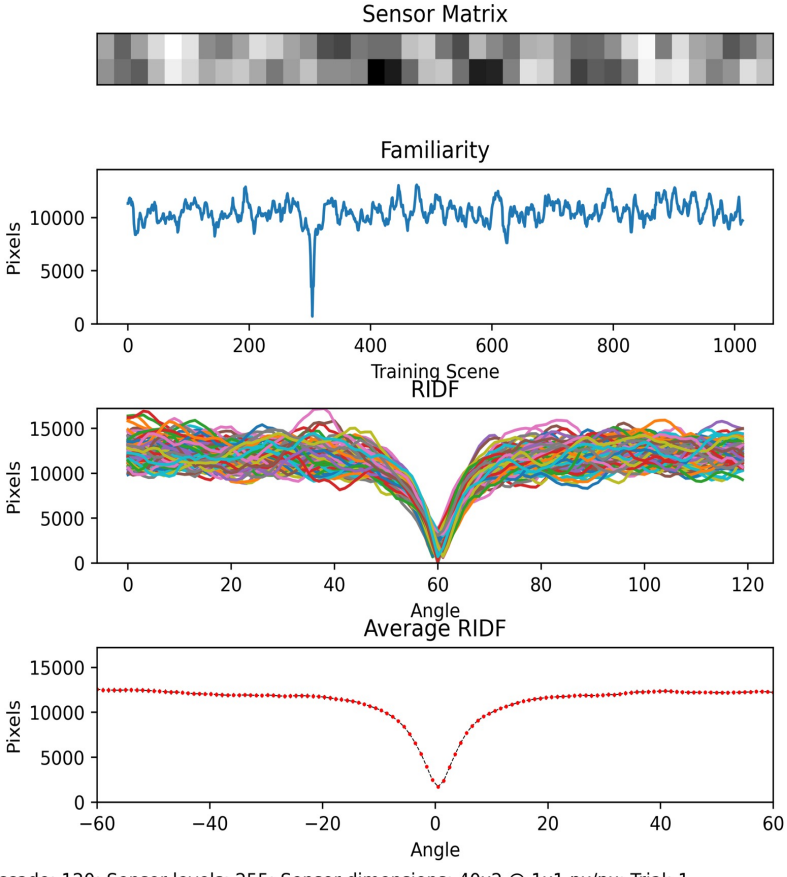





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

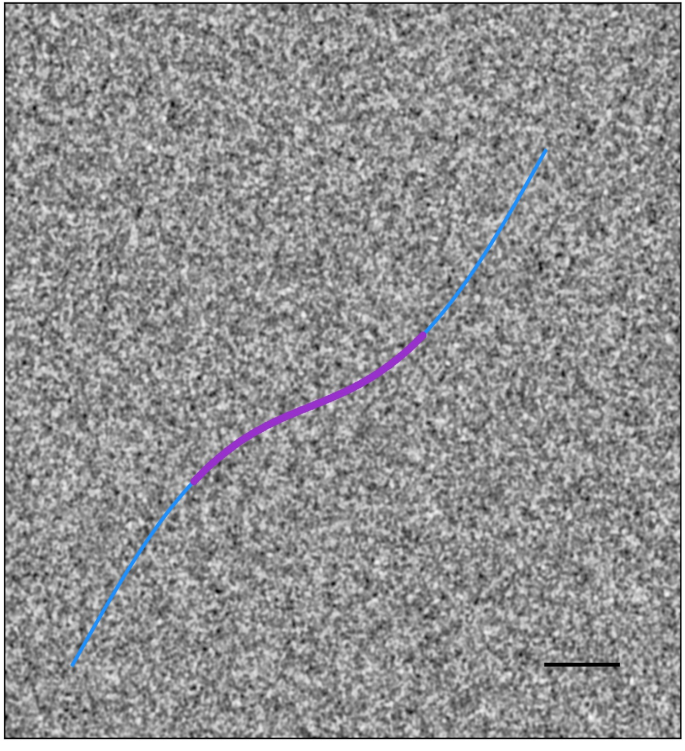
Navigation stats: RMSD error: 47.61; RMSD/dist: 0.119; TD: 7219; p90: 18; p50: 8; complete: 0

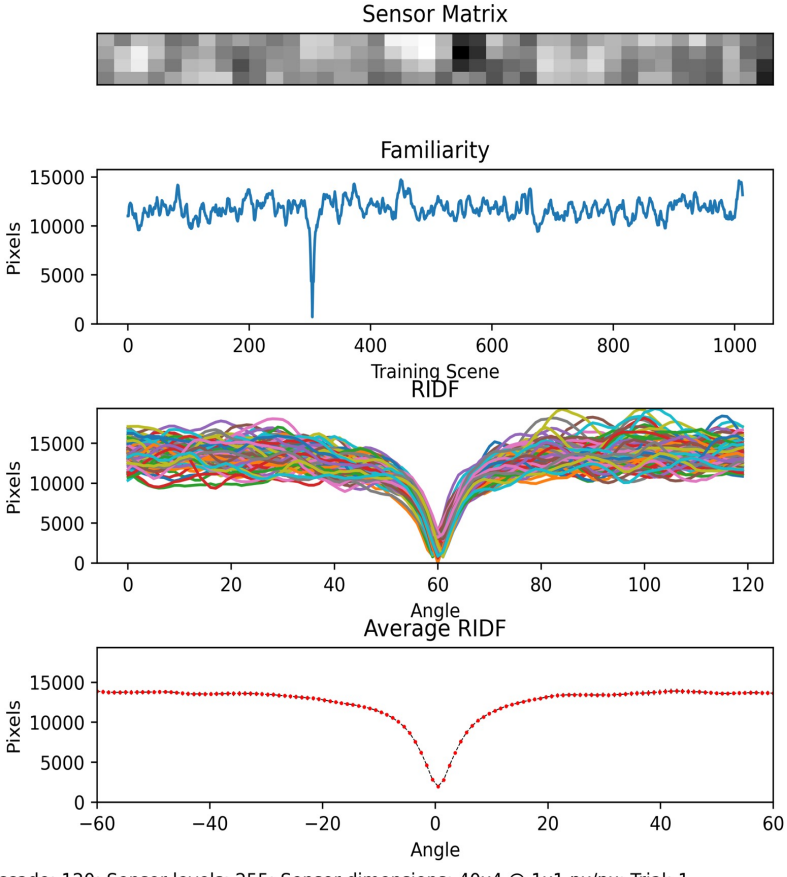





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

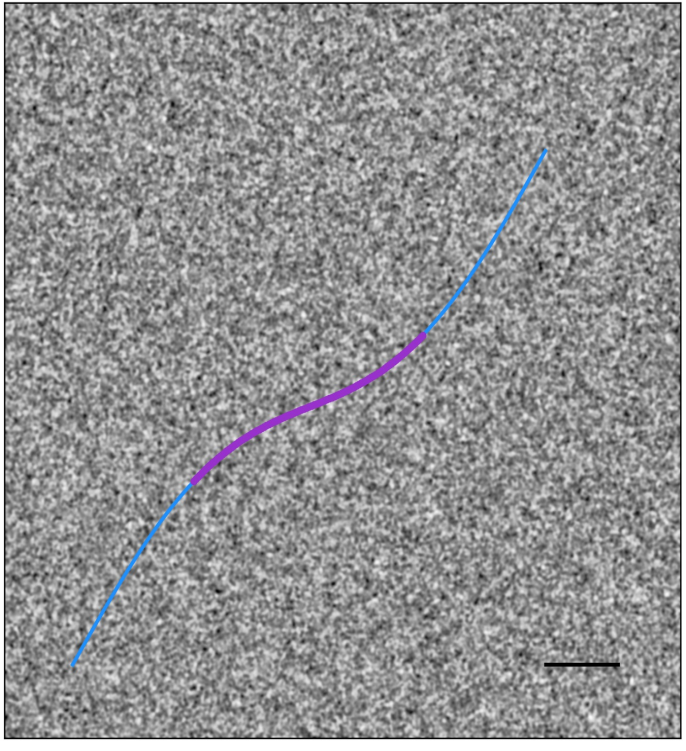
Navigation stats: RMSD error: 38.38; RMSD/dist: 0.096; TD: 8654; p90: 16; p50: 8; complete: 0

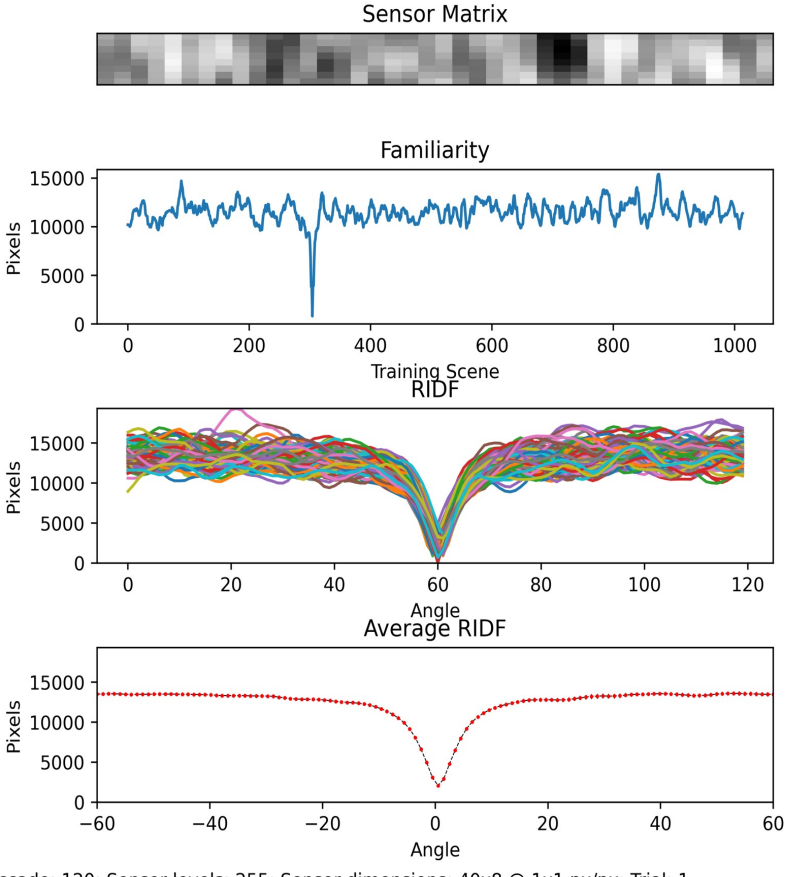





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

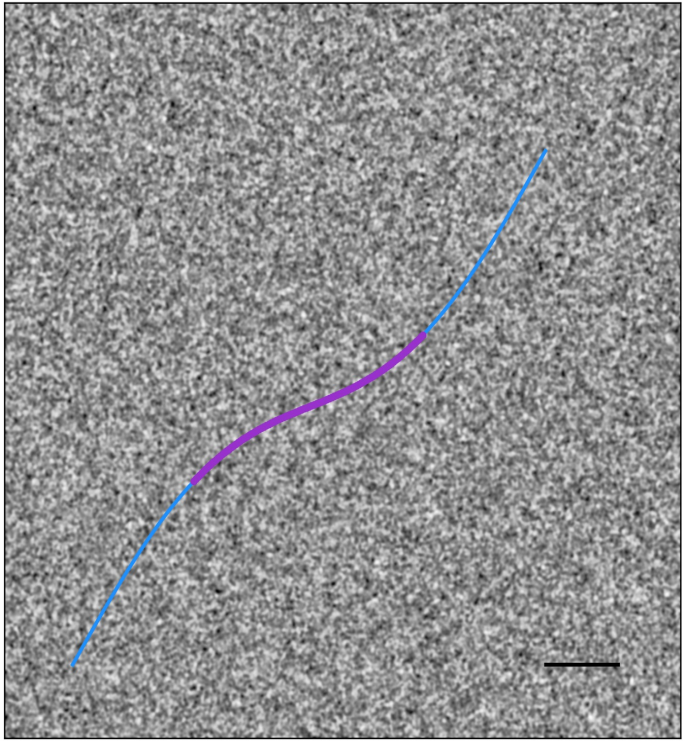
Navigation stats: RMSD error: 39.57; RMSD/dist: 0.099; TD: 9471; p90: 16; p50: 6; complete: 0

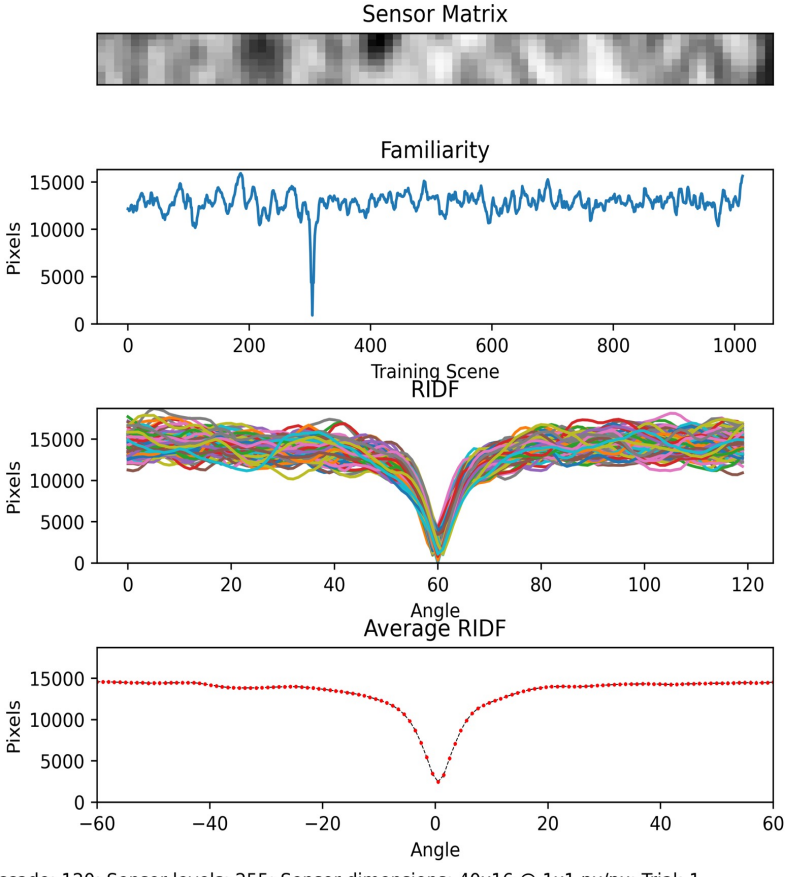





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

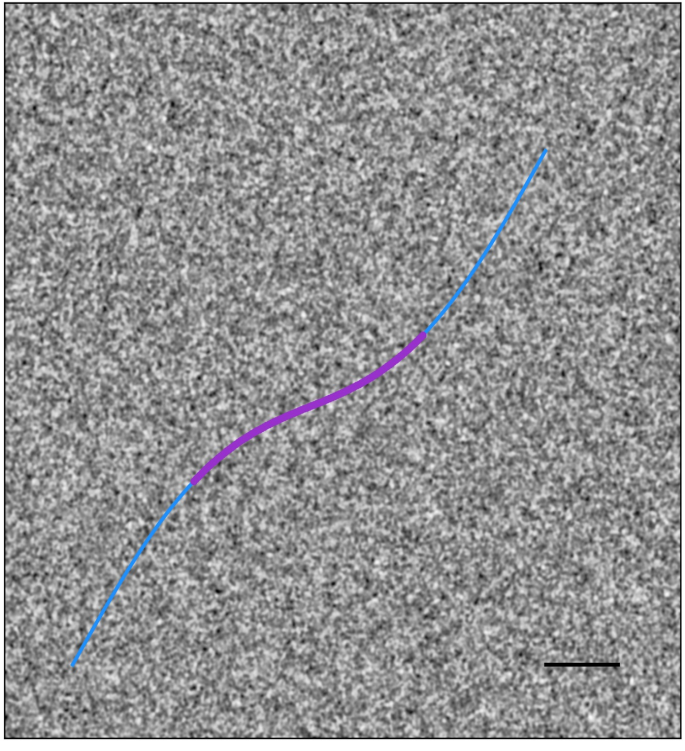
Navigation stats: RMSD error: 36.31; RMSD/dist: 0.091; TD: 9532; p90: 14; p50: 6; complete: 0

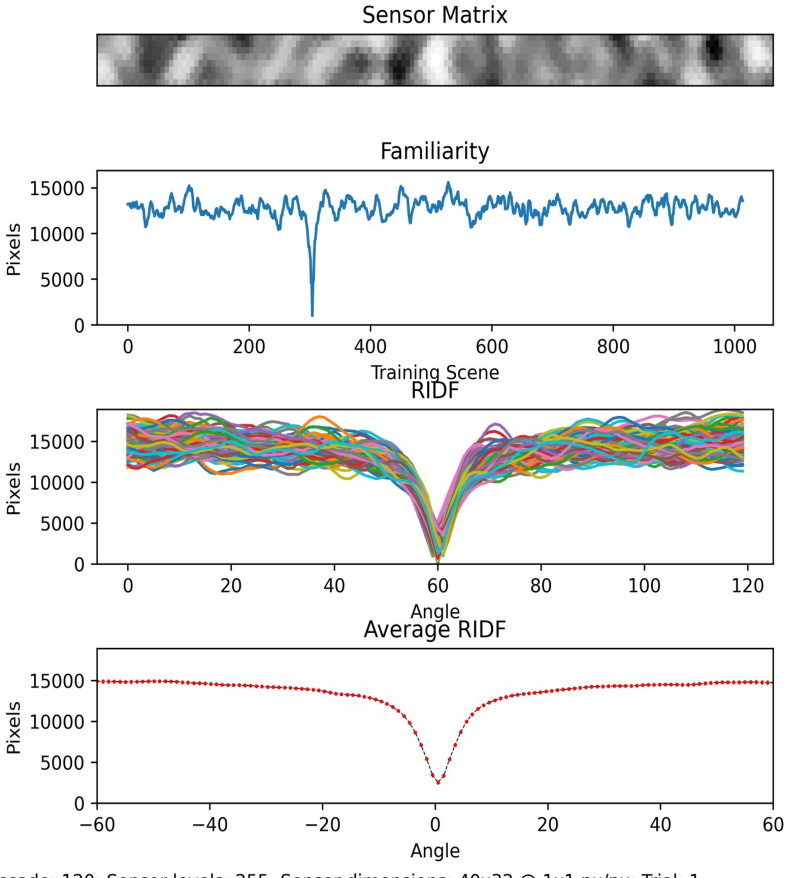





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

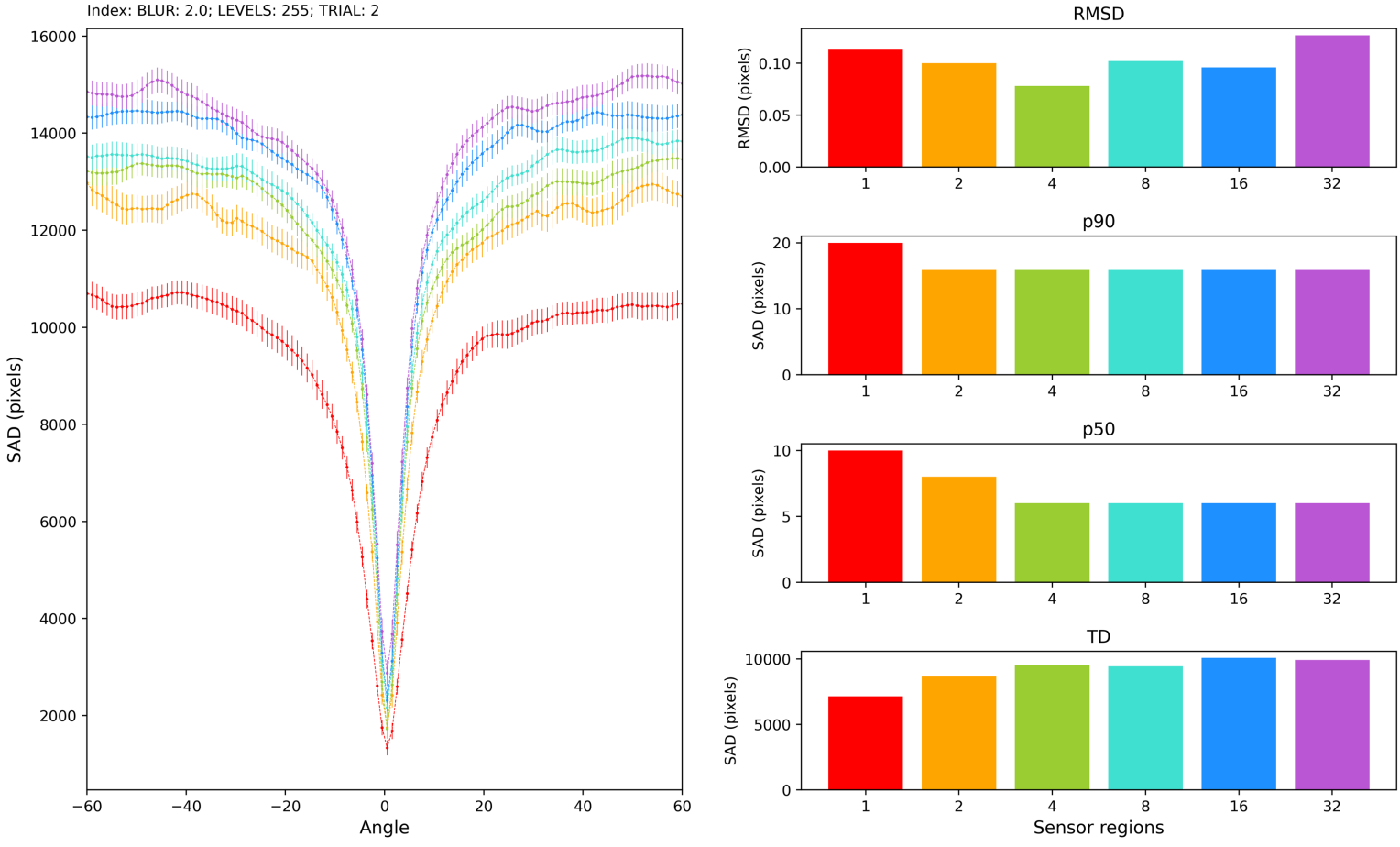
Navigation stats: RMSD error: 43.55; RMSD/dist: 0.109; TD: 9914; p90: 14; p50: 6; complete: 0

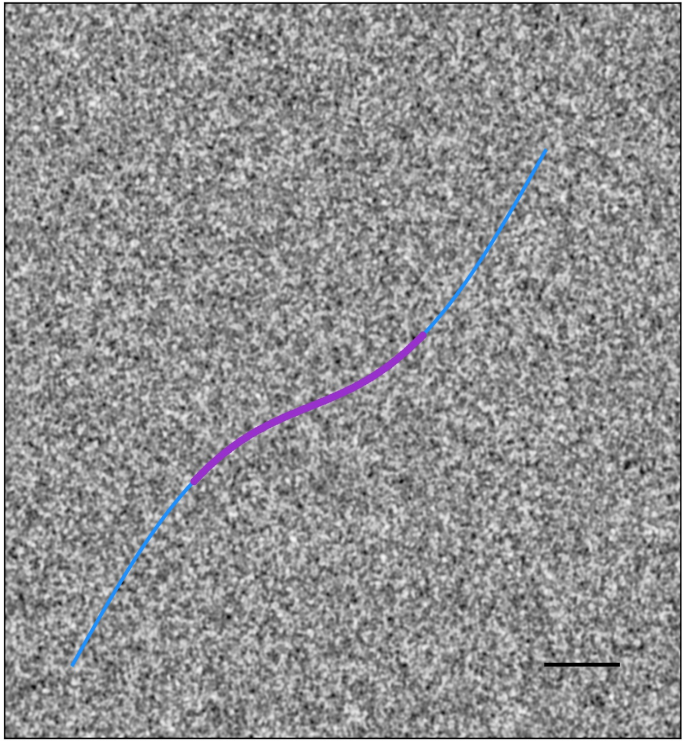


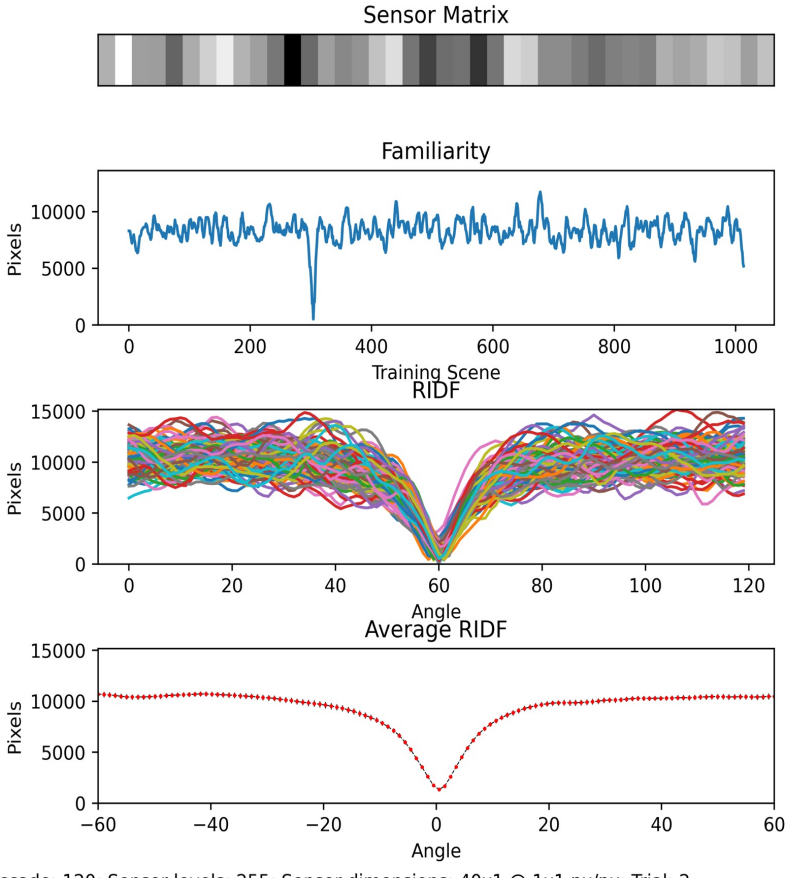



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 40.51; RMSD/dist: 0.101; TD: 10232; p90: 16; p50: 6; complete: 0

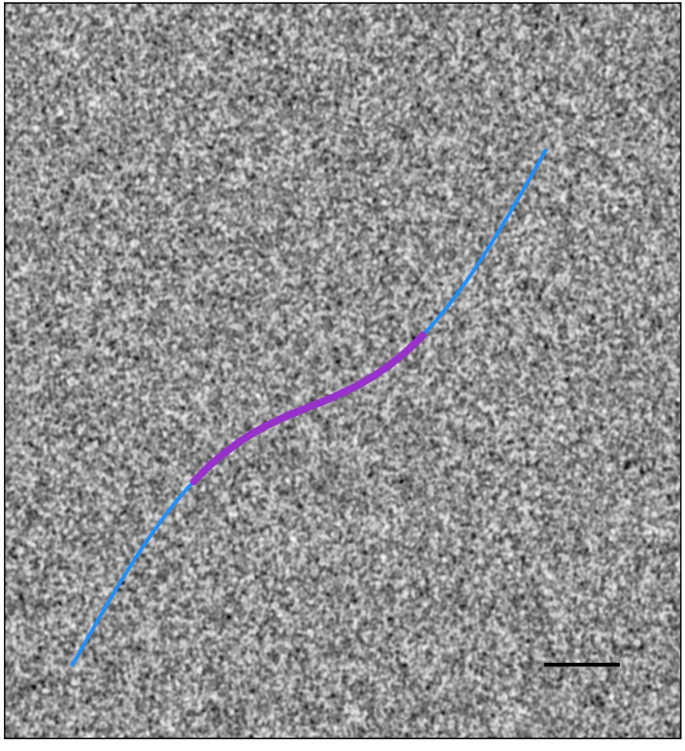

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

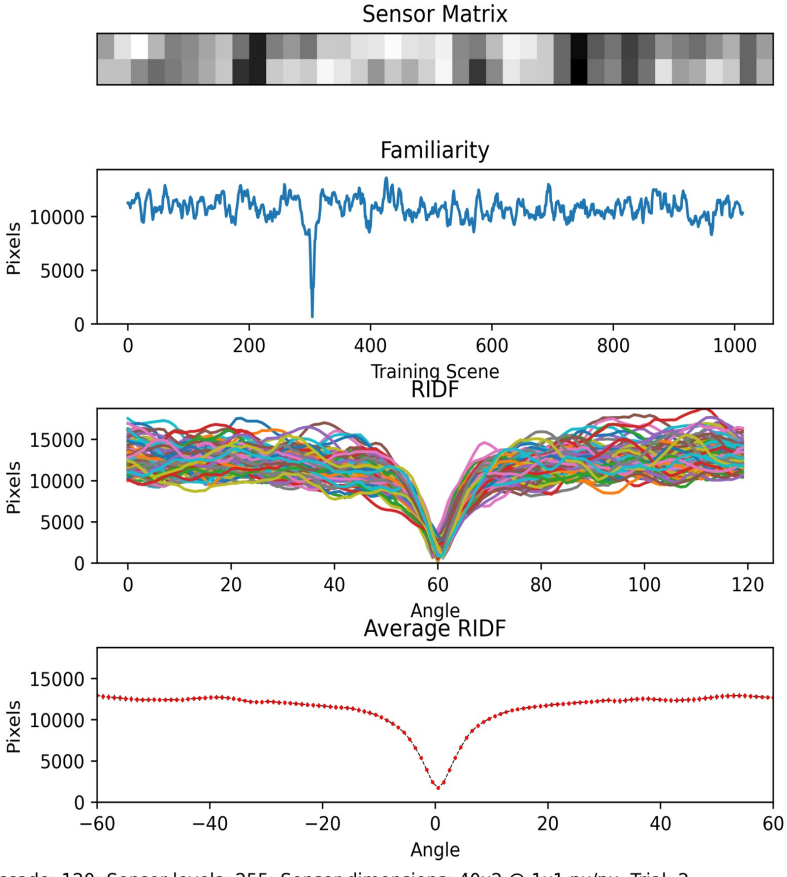





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

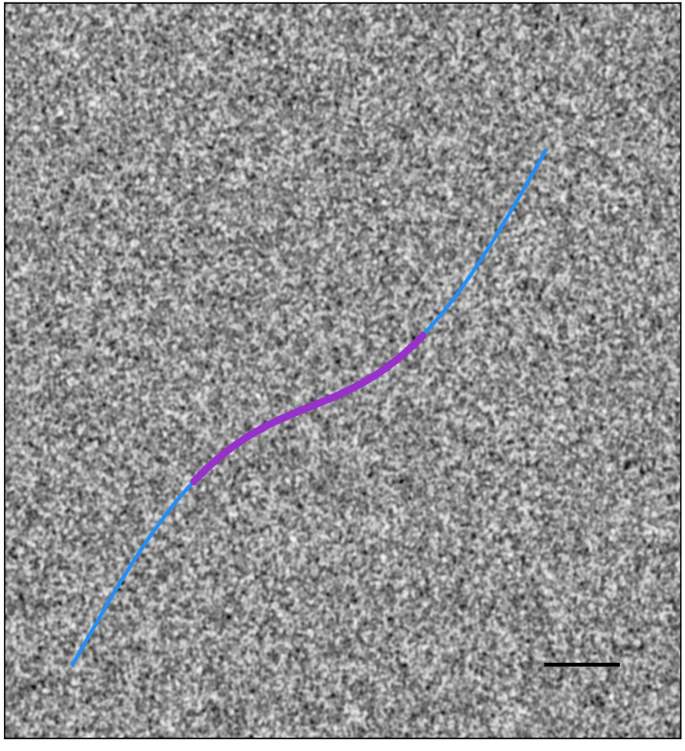
Navigation stats: RMSD error: 45.19; RMSD/dist: 0.113; TD: 7134; p90: 20; p50: 10; complete: 0

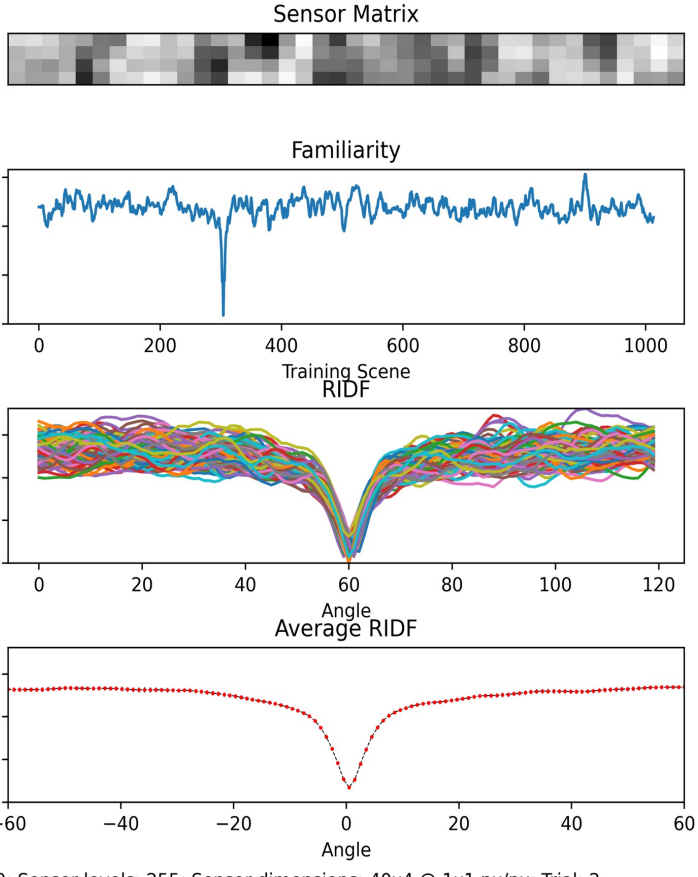





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

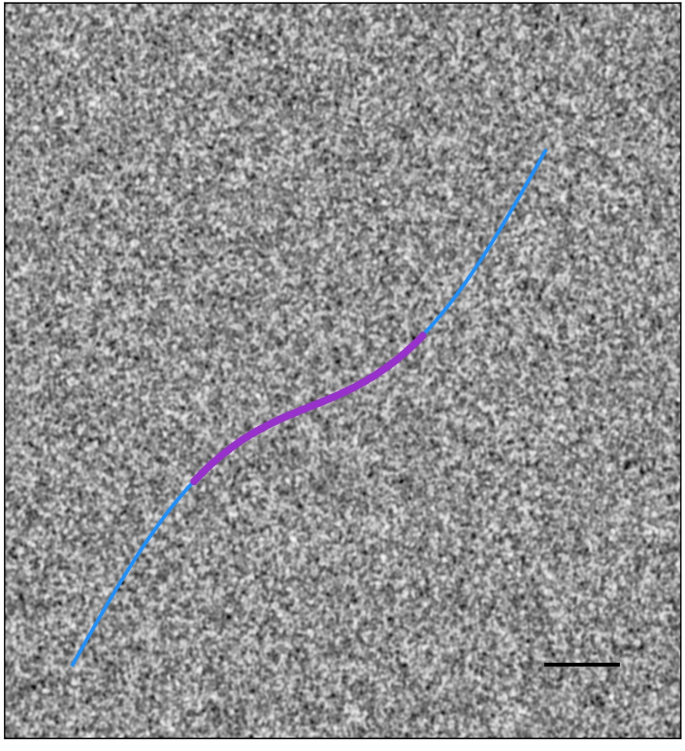
Navigation stats: RMSD error: 39.94; RMSD/dist: 0.100; TD: 8653; p90: 16; p50: 8; complete: 0

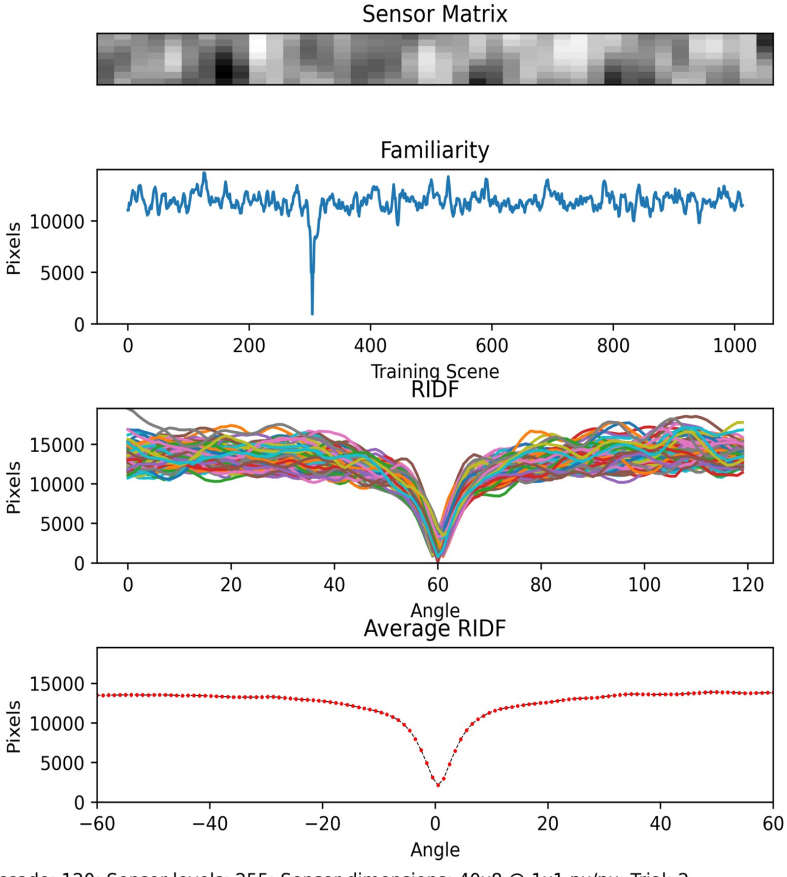





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

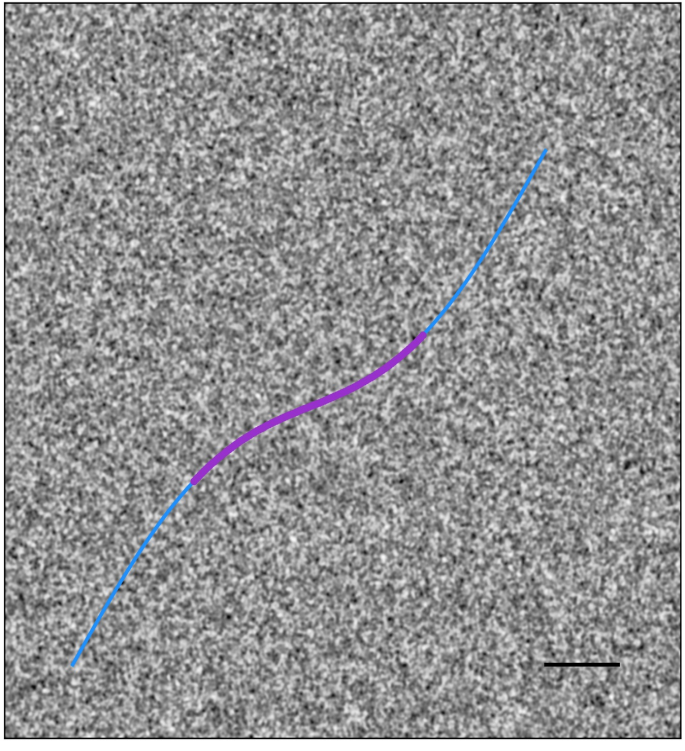
Navigation stats: RMSD error: 31.16; RMSD/dist: 0.078; TD: 9509; p90: 16; p50: 6; complete: 0

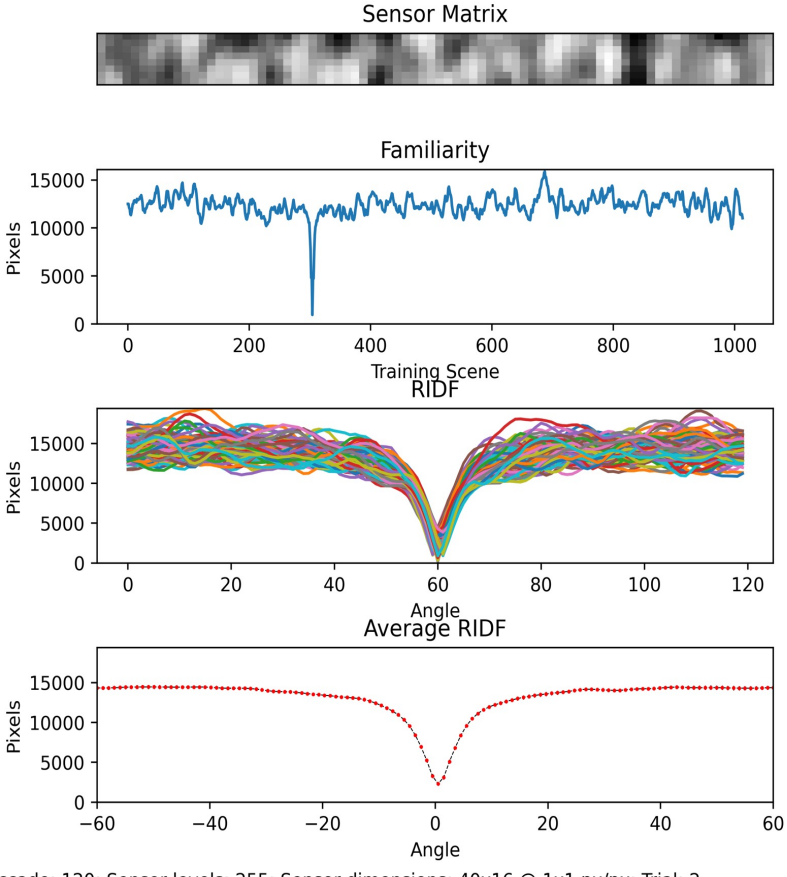





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

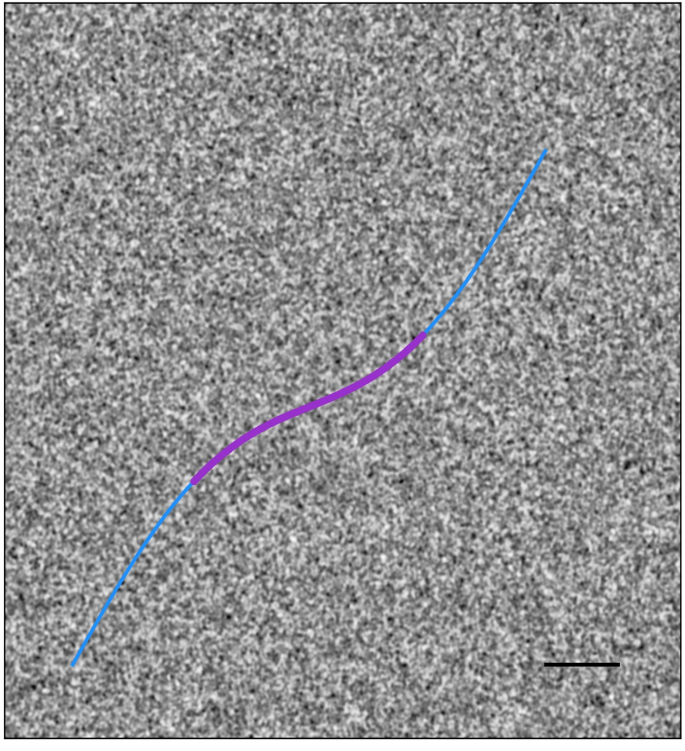
Navigation stats: RMSD error: 40.77; RMSD/dist: 0.102; TD: 9440; p90: 16; p50: 6; complete: 0

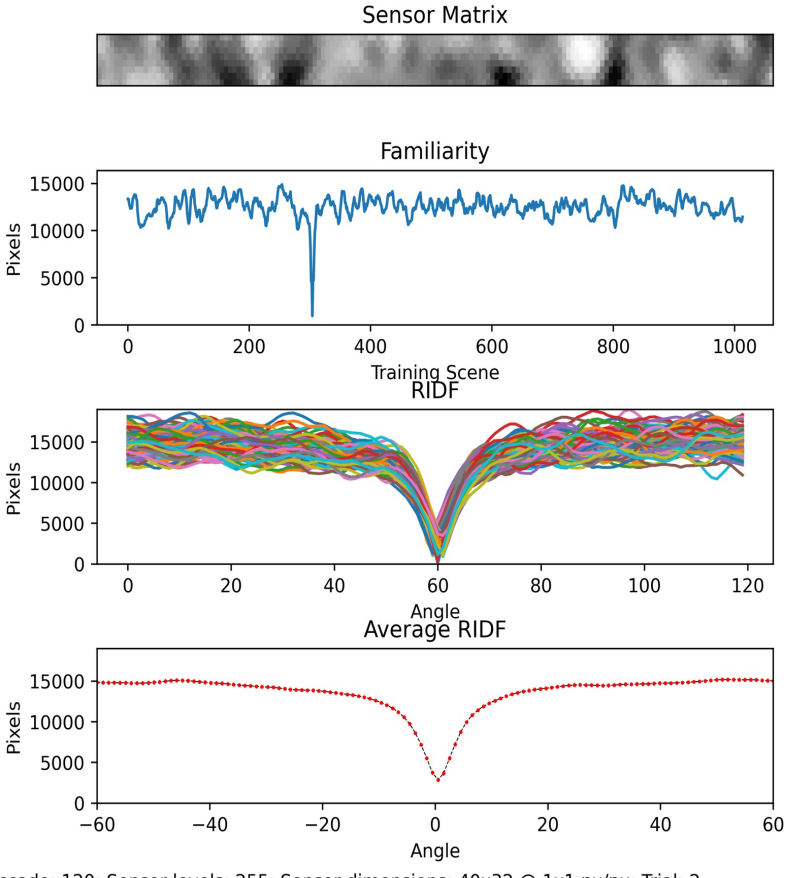





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

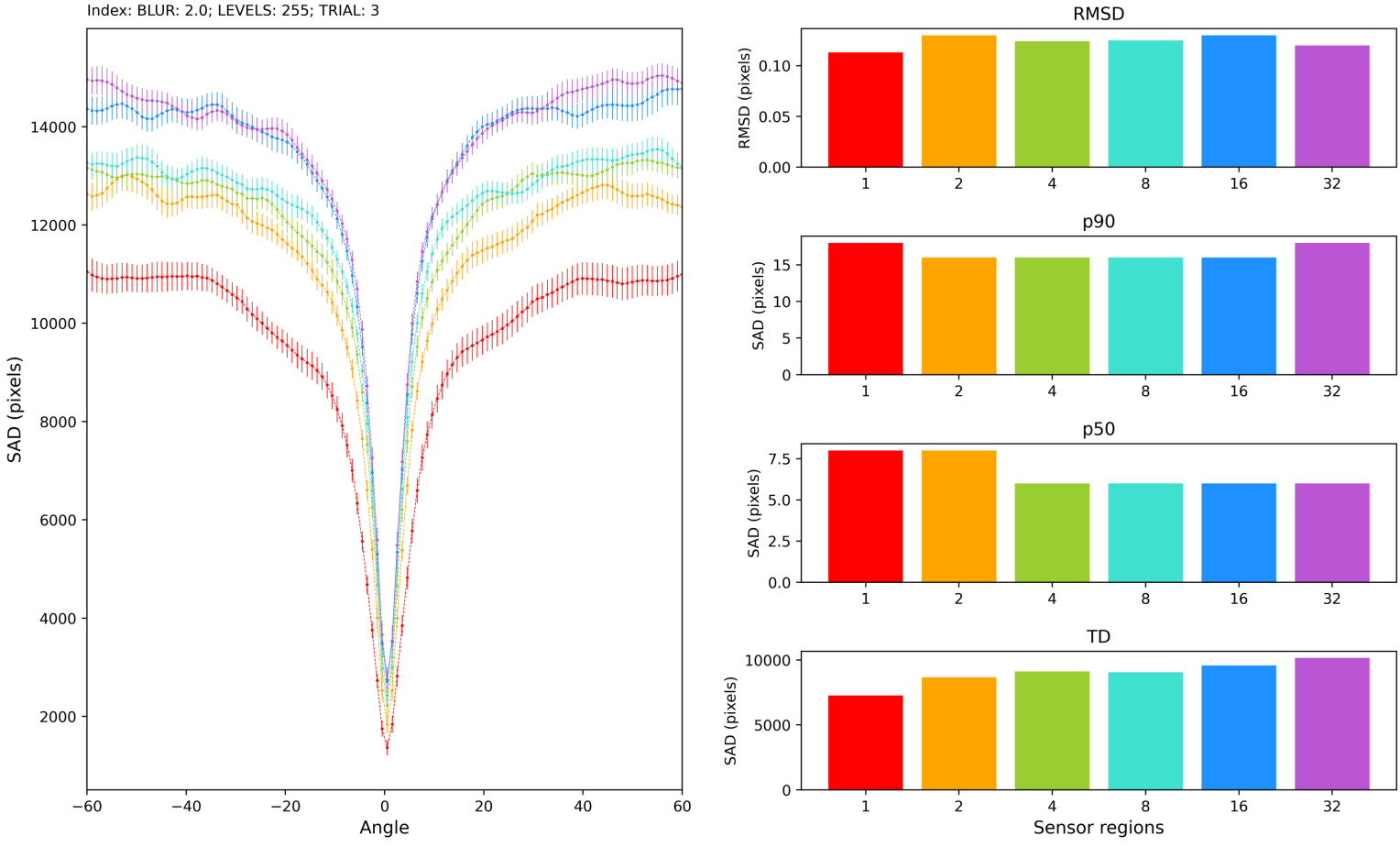
Navigation stats: RMSD error: 38.29; RMSD/dist: 0.096; TD: 10070; p90: 16; p50: 6; complete: 0

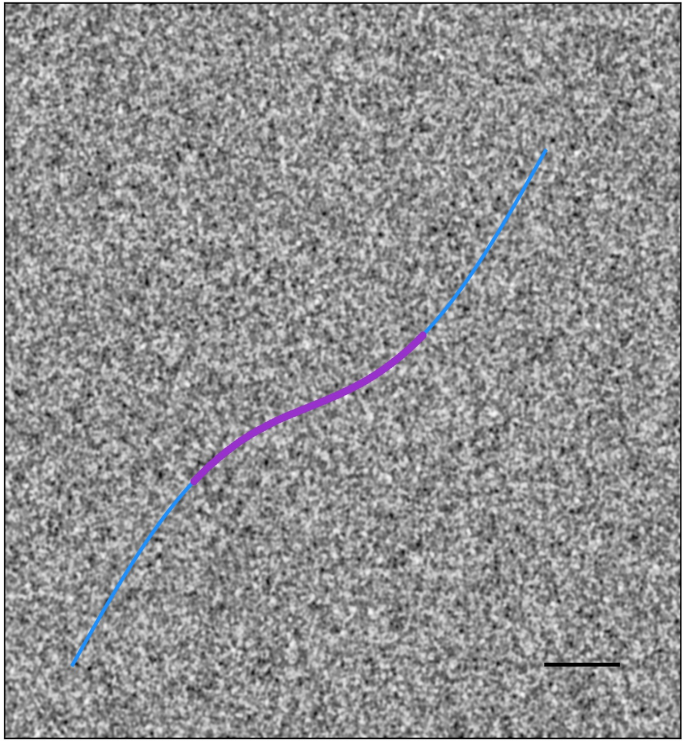


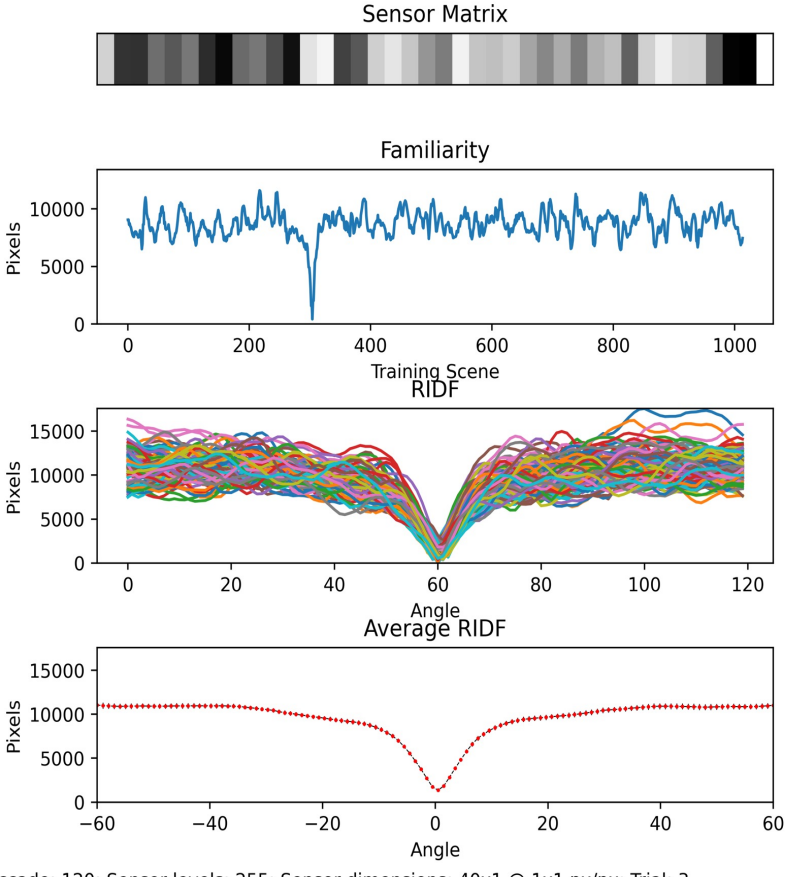



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 50.84; RMSD/dist: 0.127; TD: 9921; p90: 16; p50: 6; complete: 0

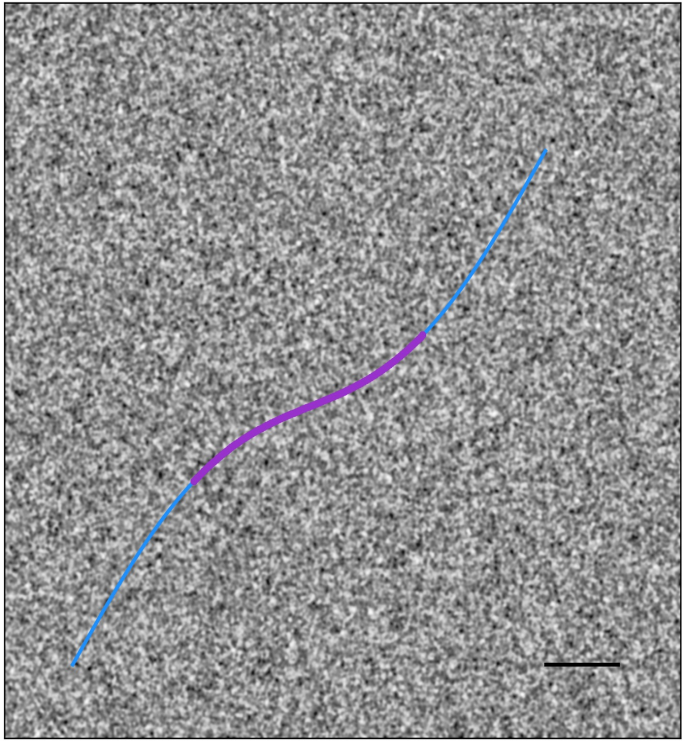

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

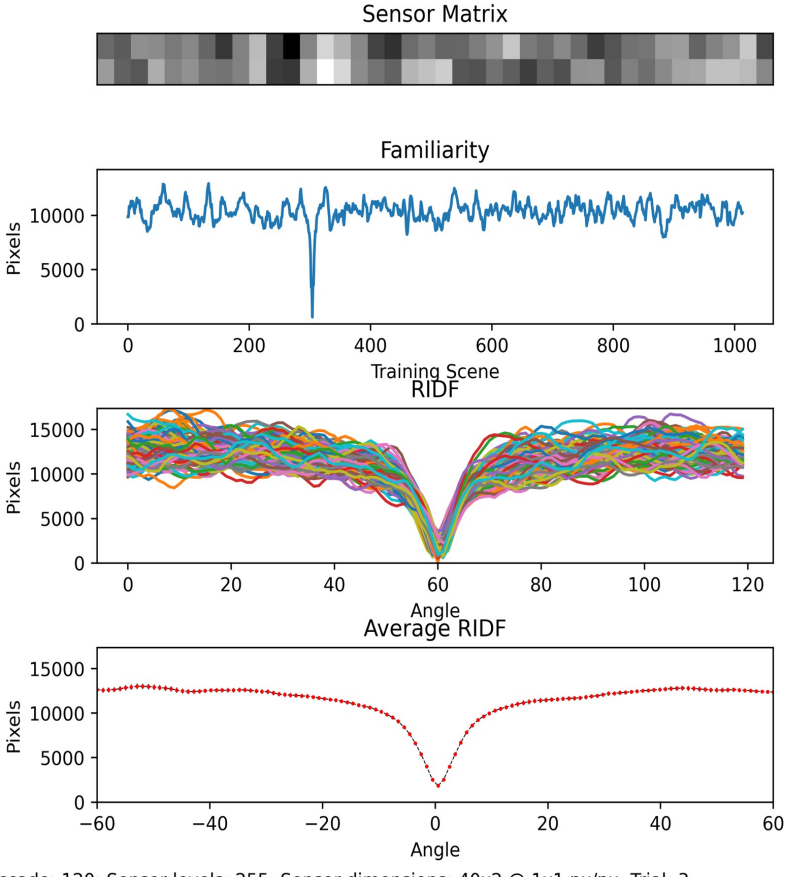





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

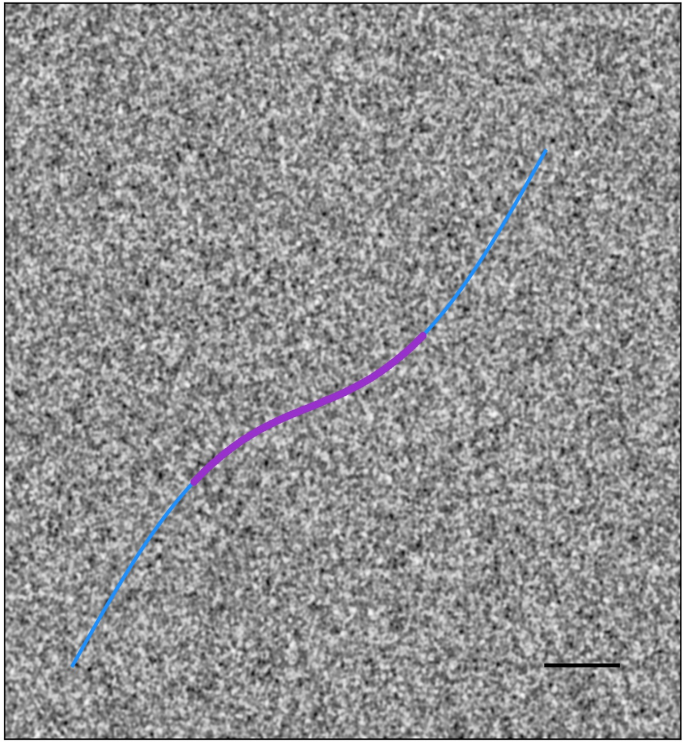
Navigation stats: RMSD error: 45.33; RMSD/dist: 0.113; TD: 7268; p90: 18; p50: 8; complete: 0

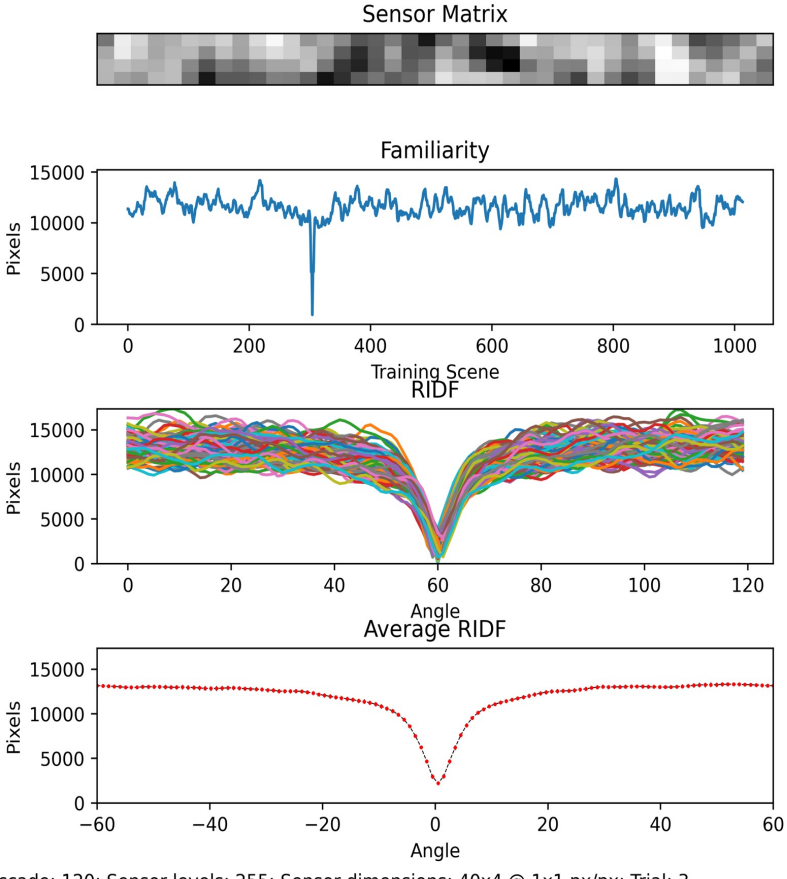





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

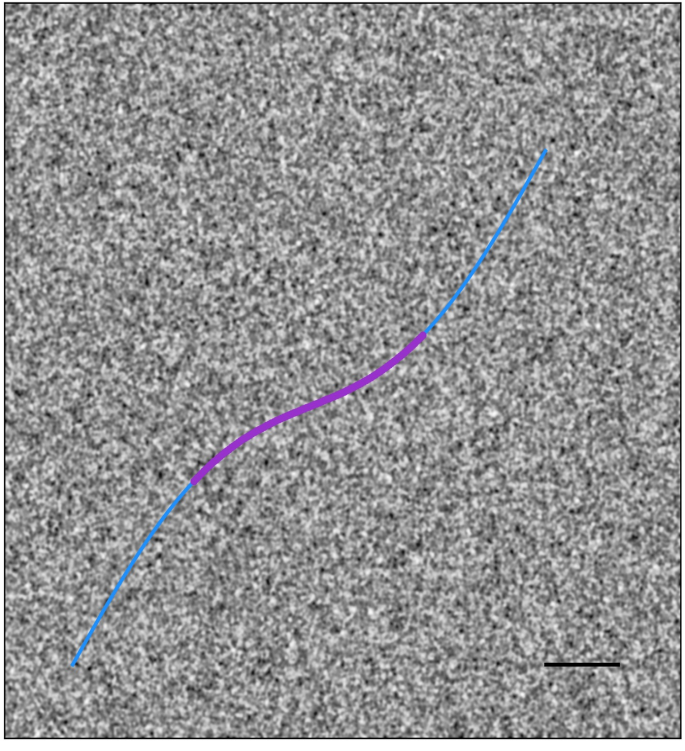
Navigation stats: RMSD error: 51.94; RMSD/dist: 0.130; TD: 8666; p90: 16; p50: 8; complete: 0

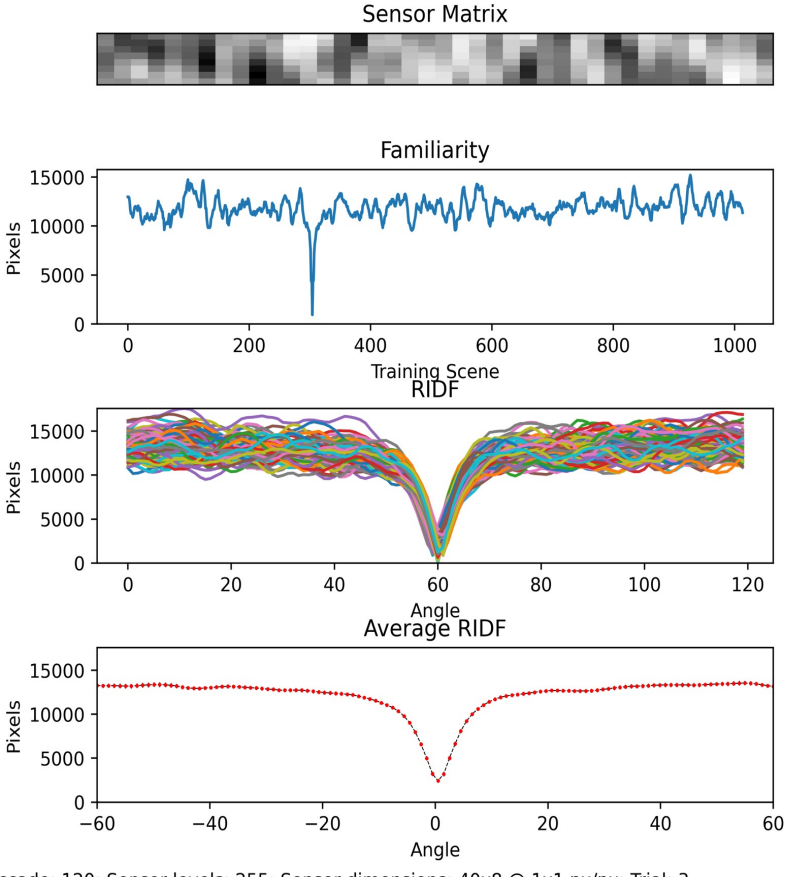





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

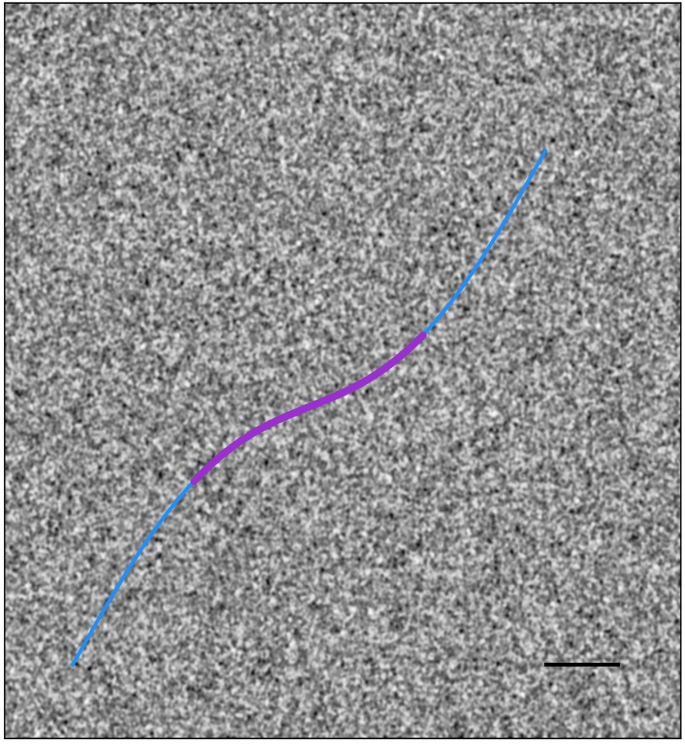
Navigation stats: RMSD error: 49.60; RMSD/dist: 0.124; TD: 9120; p90: 16; p50: 6; complete: 0

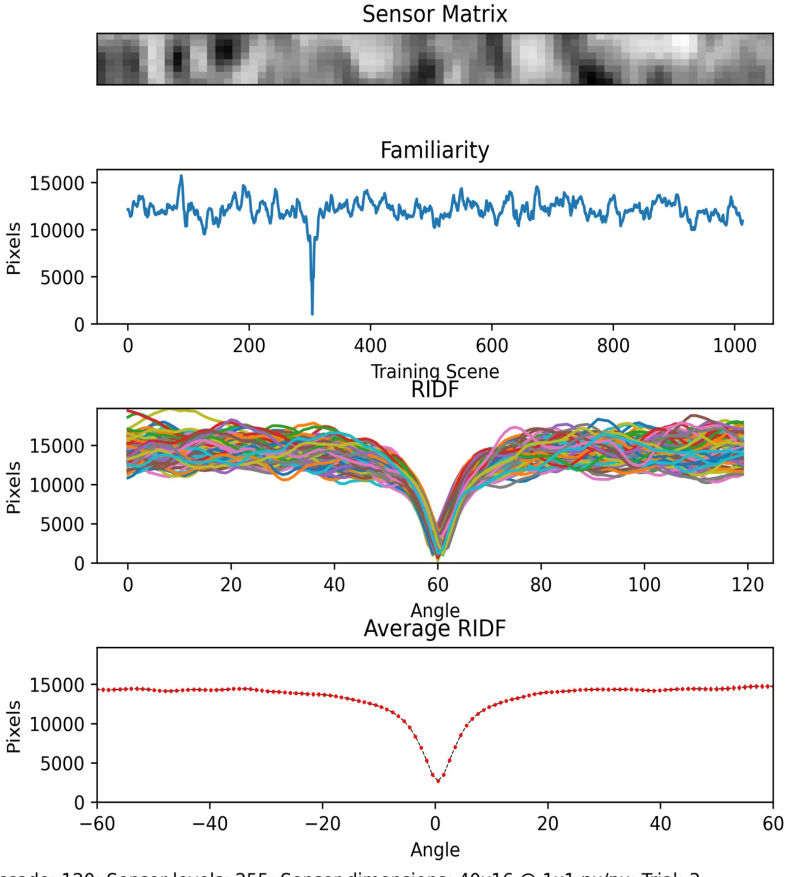





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

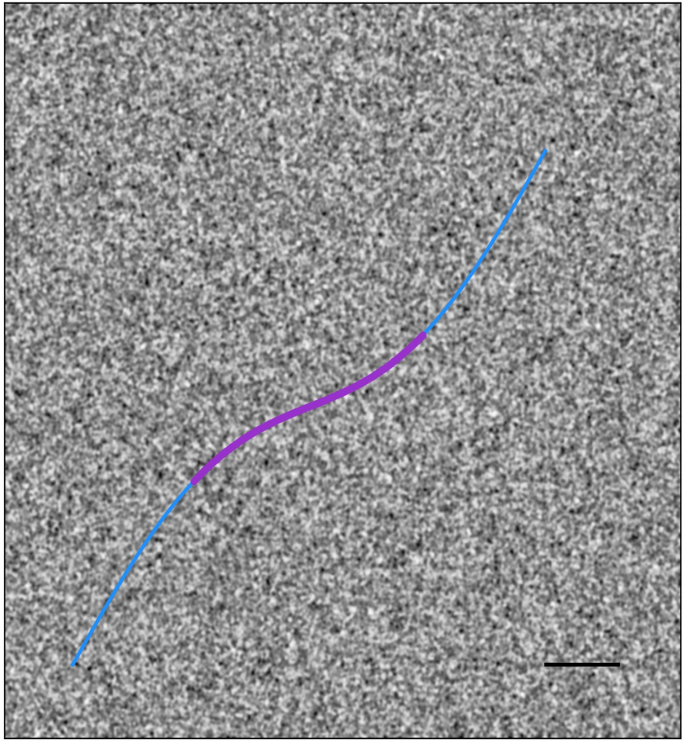
Navigation stats: RMSD error: 49.89; RMSD/dist: 0.125; TD: 9055; p90: 16; p50: 6; complete: 0

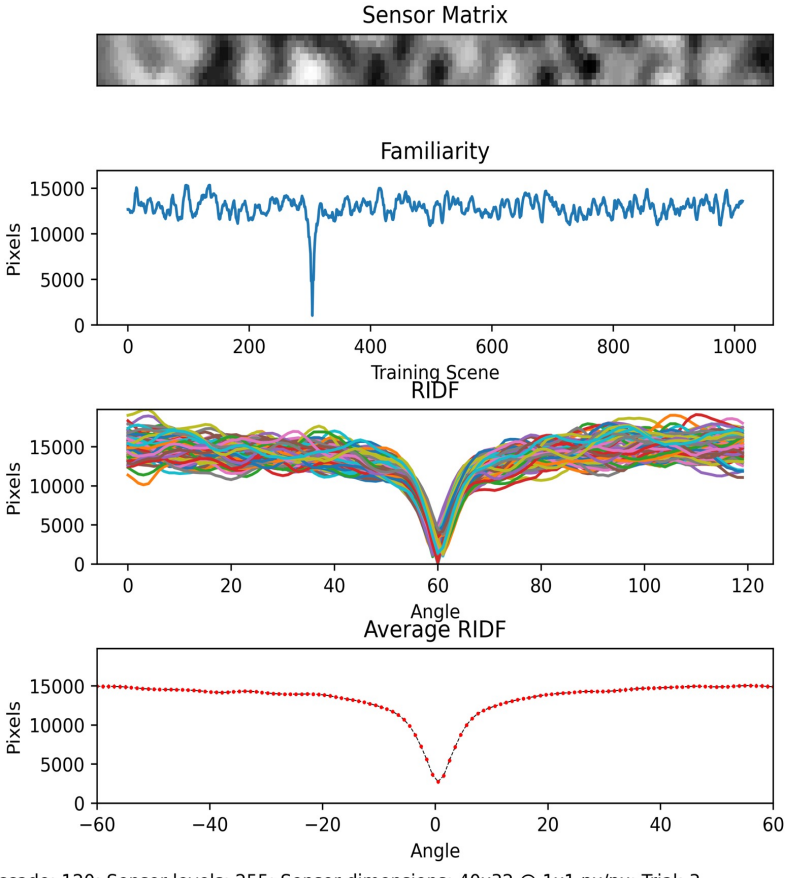





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

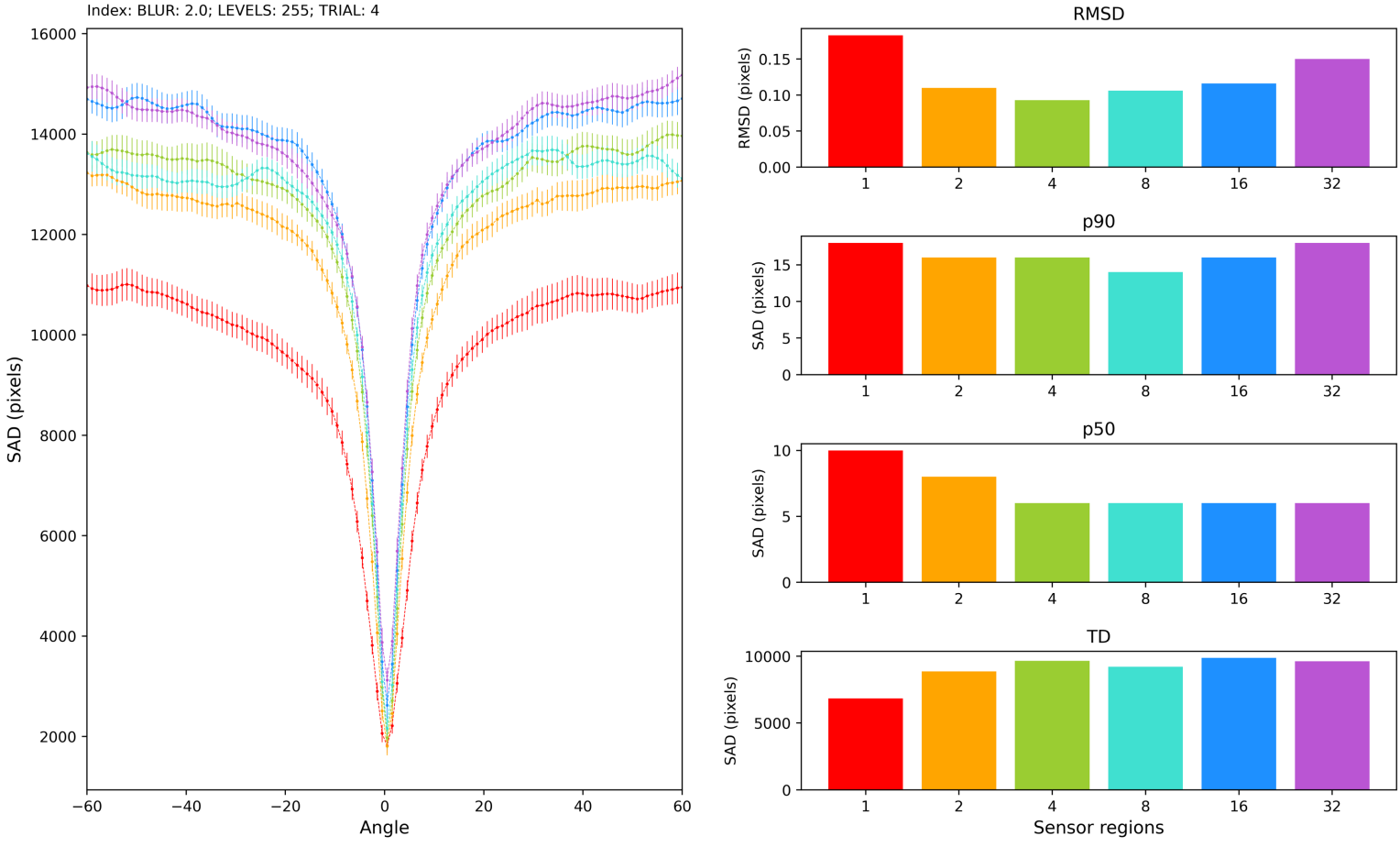
Navigation stats: RMSD error: 51.87; RMSD/dist: 0.130; TD: 9586; p90: 16; p50: 6; complete: 0

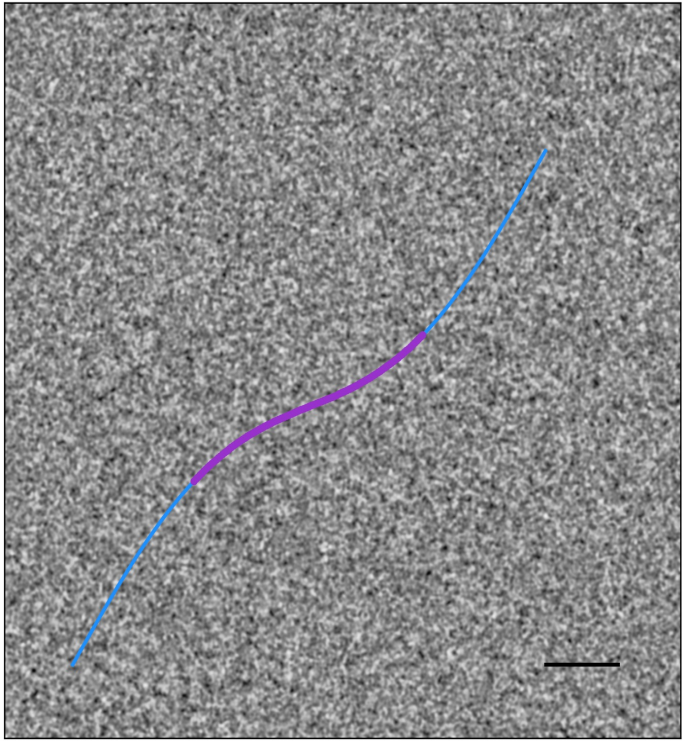


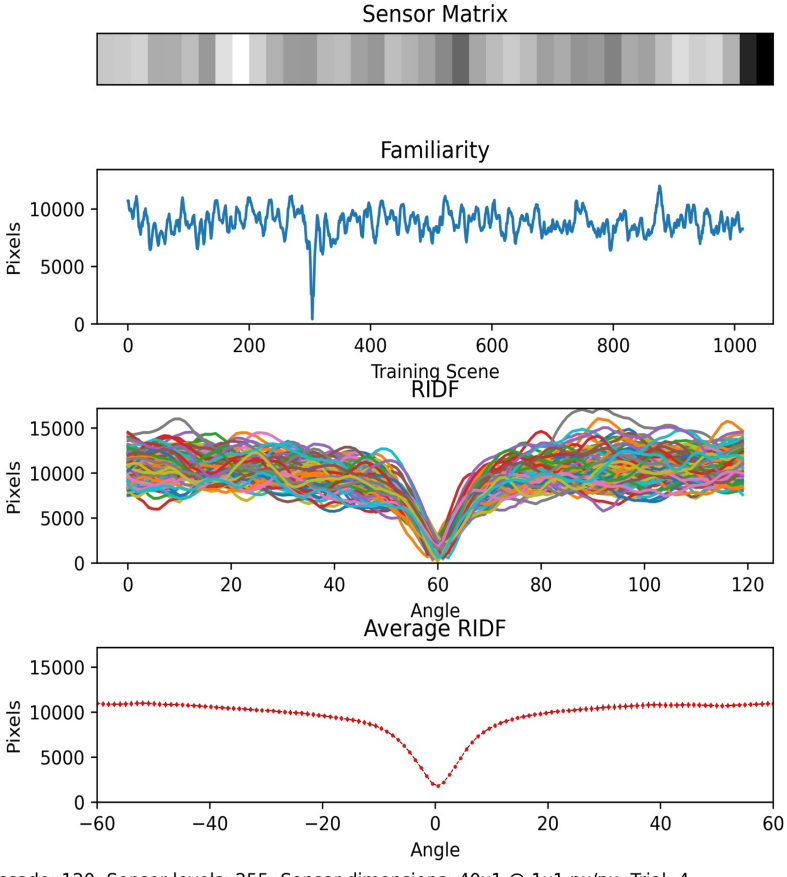



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 47.83; RMSD/dist: 0.120; TD: 10158; p90: 18; p50: 6; complete: 0

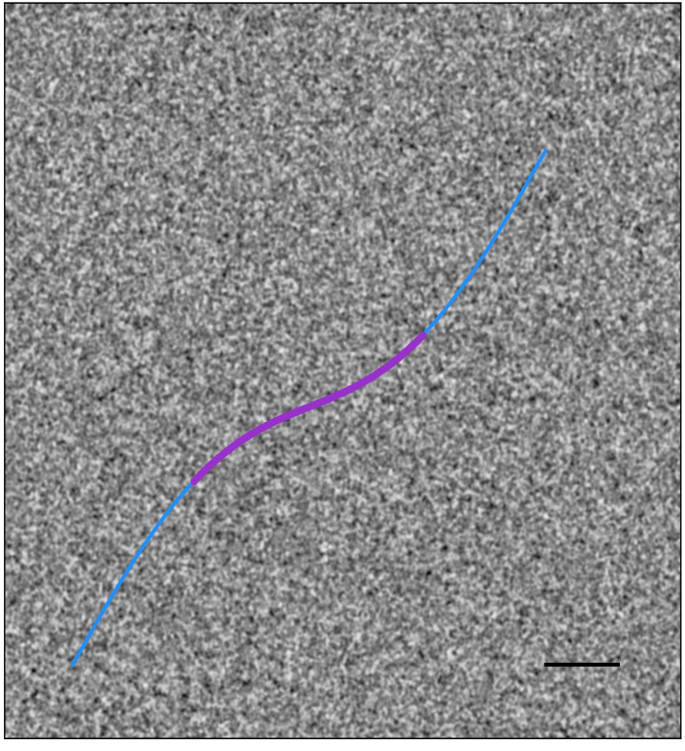

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

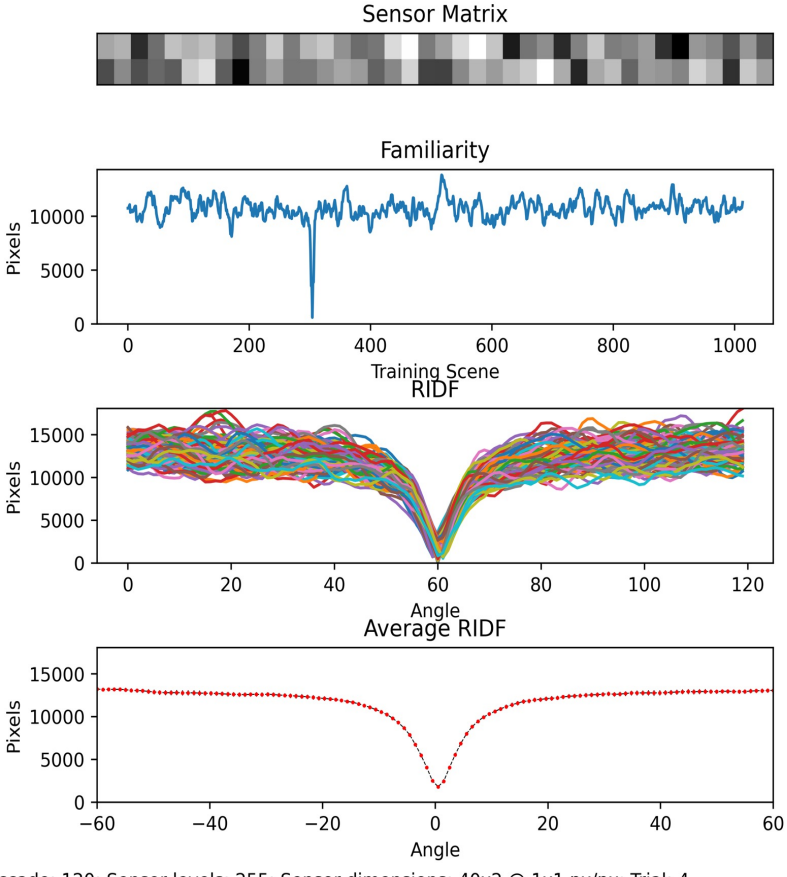





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

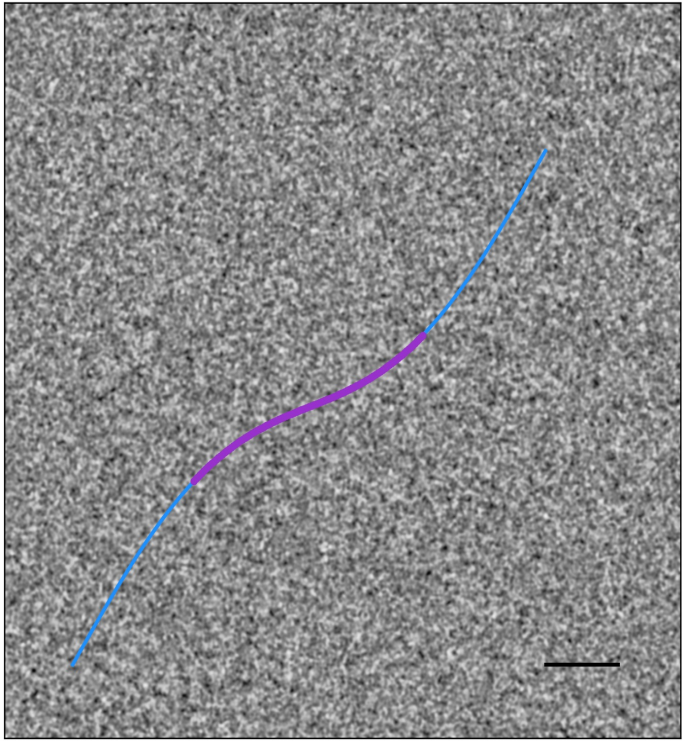
Navigation stats: RMSD error: 73.13; RMSD/dist: 0.183; TD: 6840; p90: 18; p50: 10; complete: 0

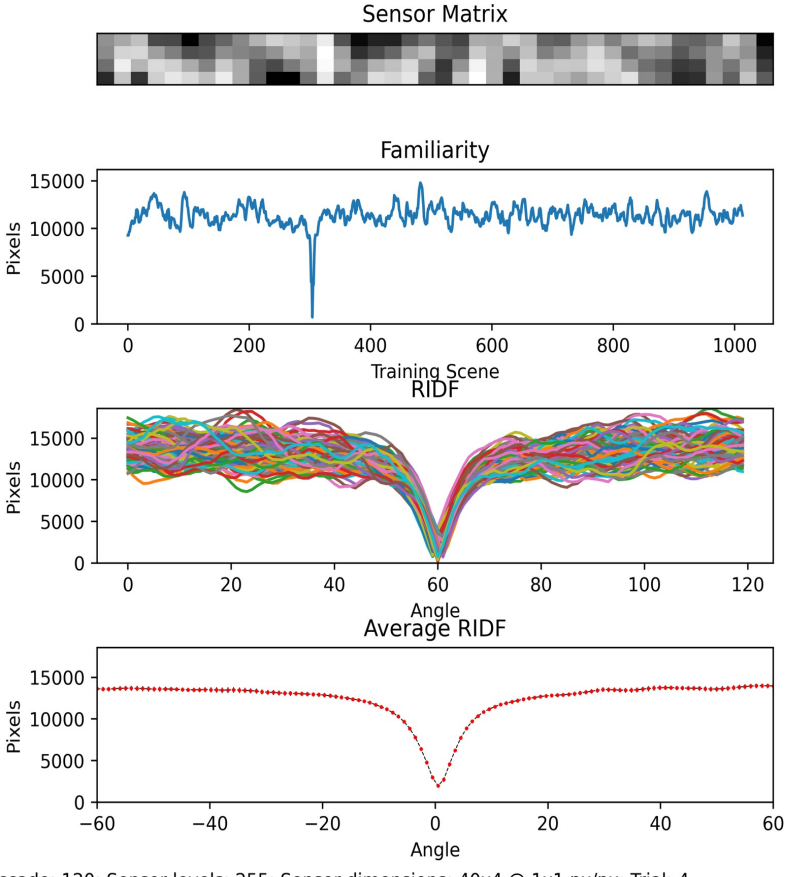





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

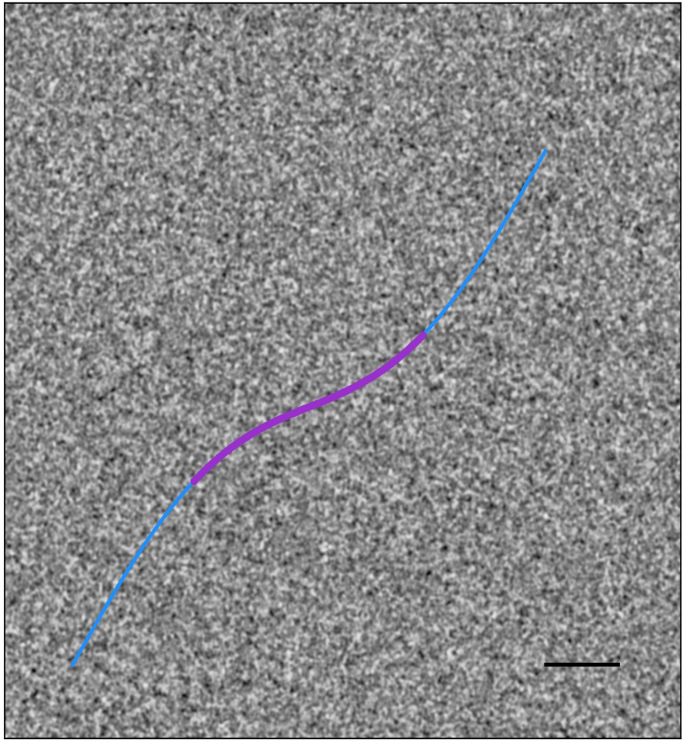
Navigation stats: RMSD error: 43.92; RMSD/dist: 0.110; TD: 8860; p90: 16; p50: 8; complete: 0

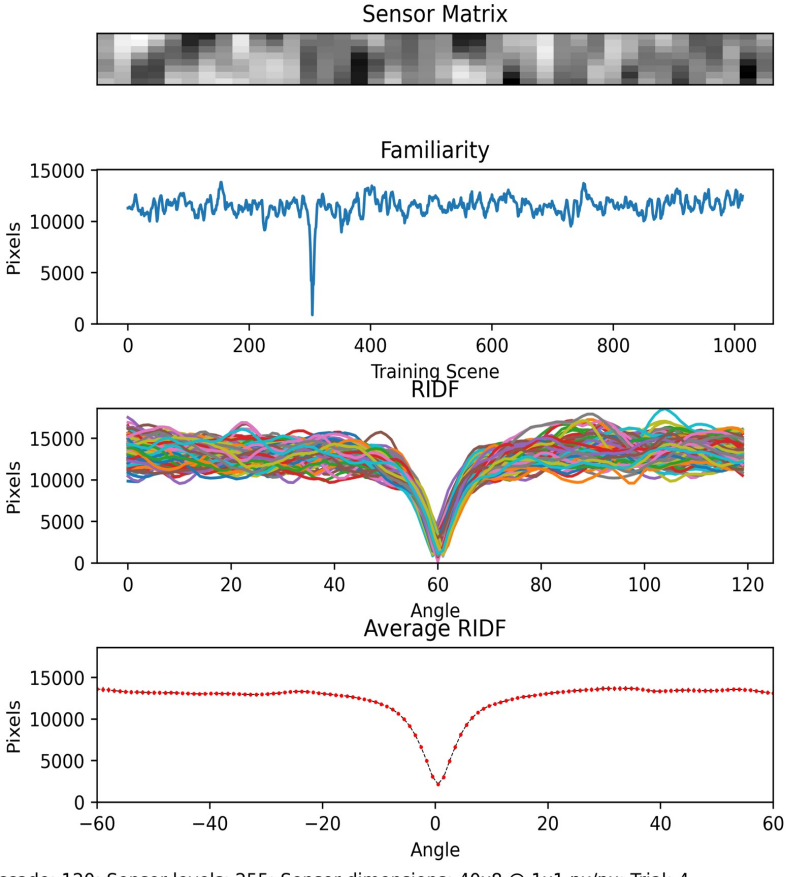





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

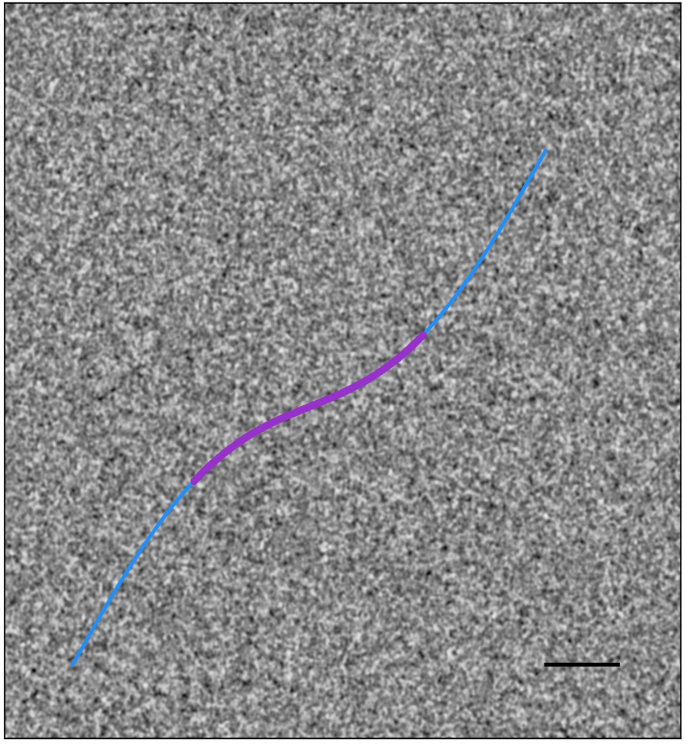
Navigation stats: RMSD error: 37.37; RMSD/dist: 0.093; TD: 9655; p90: 16; p50: 6; complete: 0

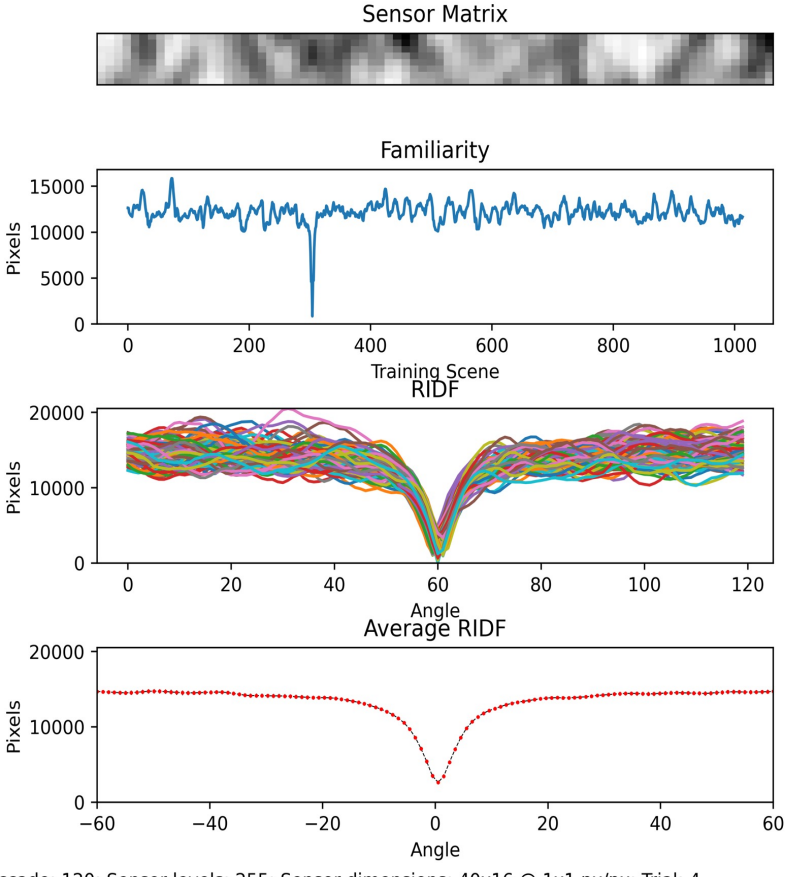





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

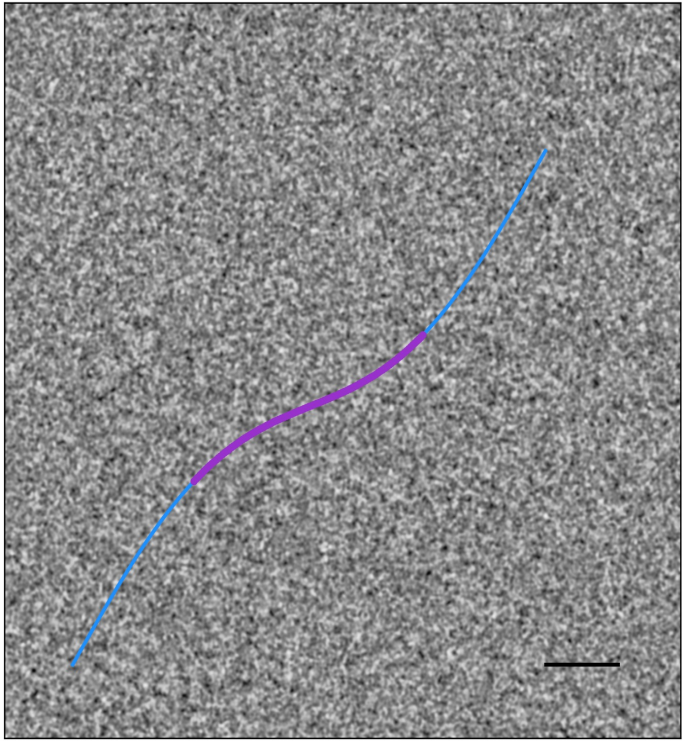
Navigation stats: RMSD error: 42.37; RMSD/dist: 0.106; TD: 9222; p90: 14; p50: 6; complete: 0

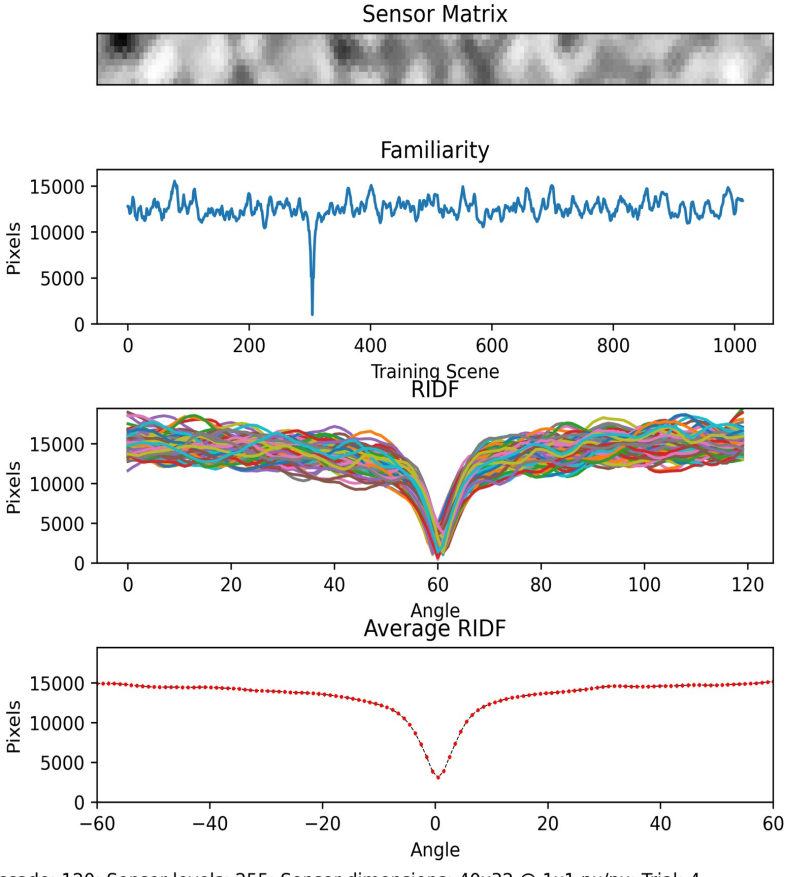





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

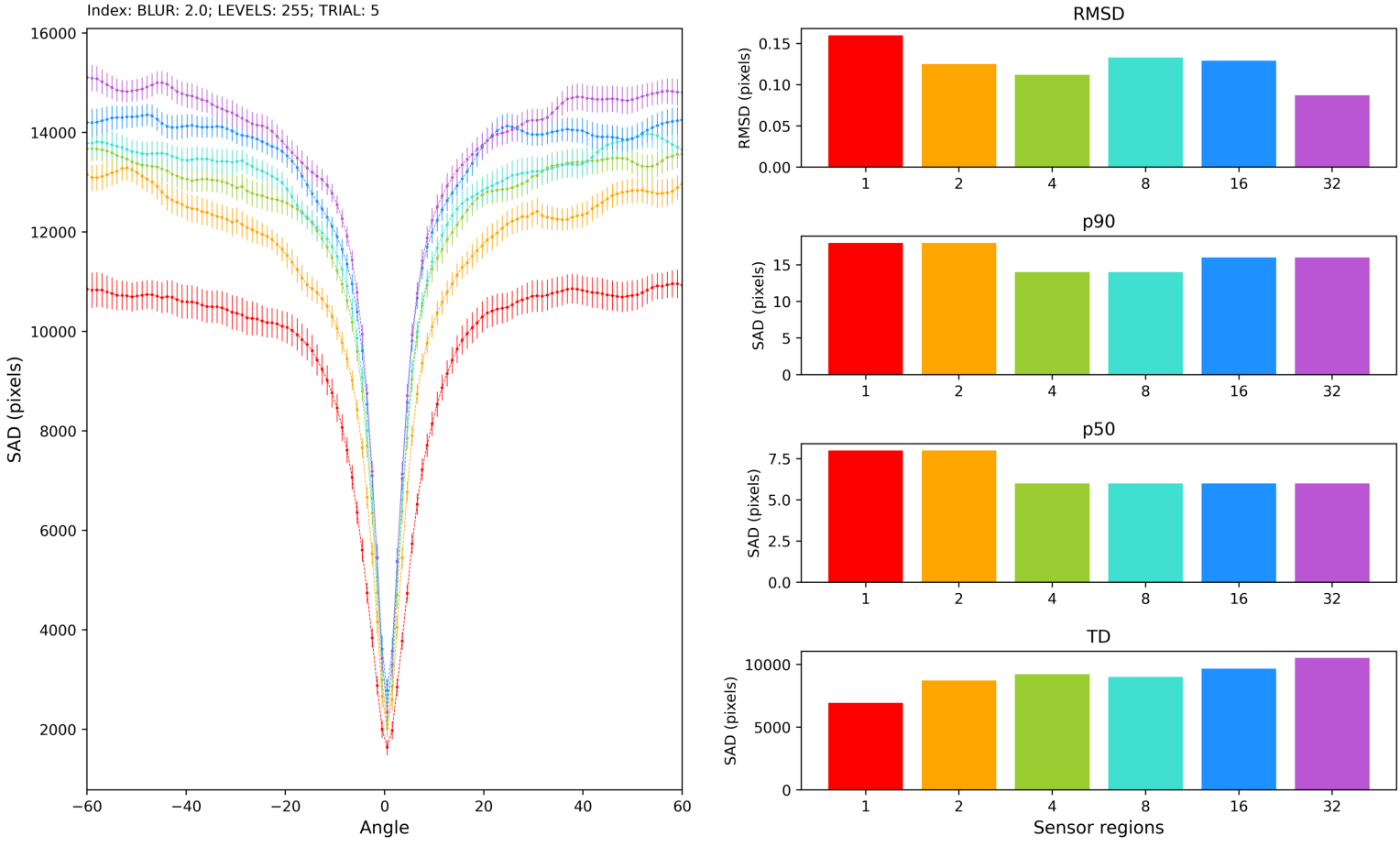
Navigation stats: RMSD error: 46.28; RMSD/dist: 0.116; TD: 9871; p90: 16; p50: 6; complete: 0

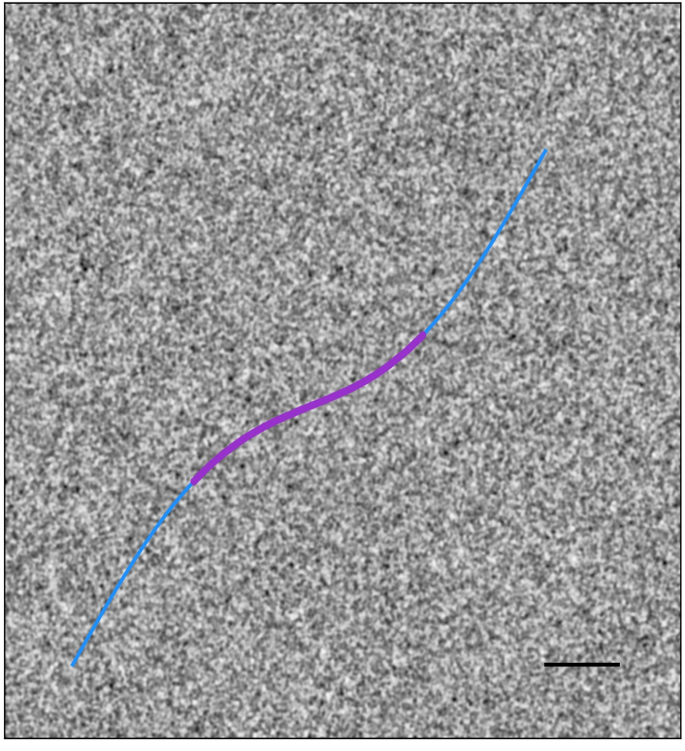


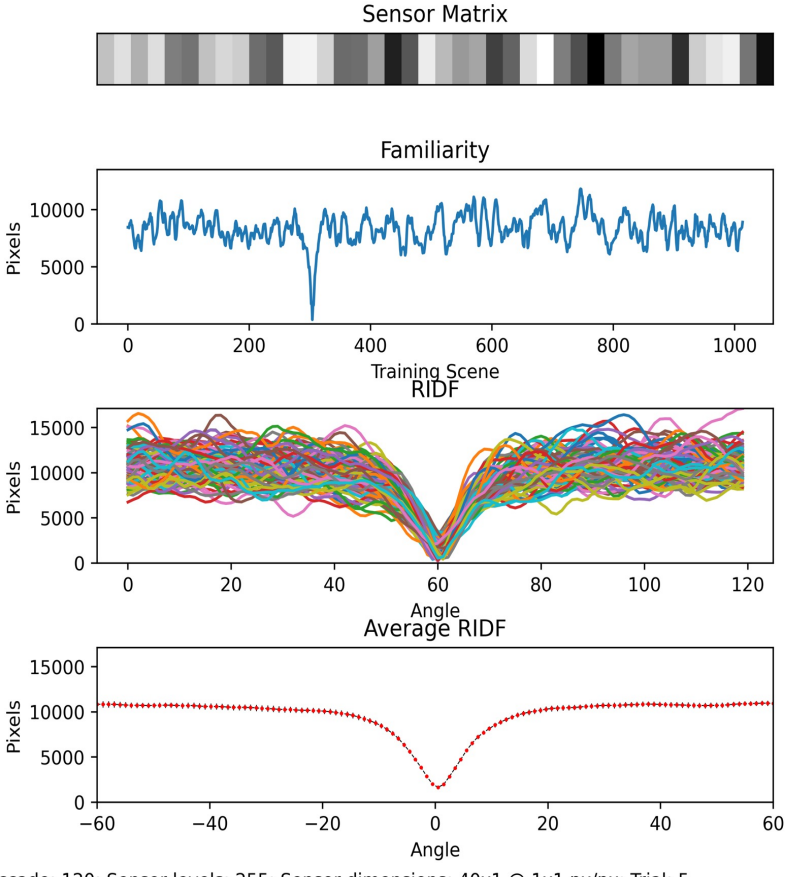



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 60.15; RMSD/dist: 0.150; TD: 9624; p90: 18; p50: 6; complete: 0

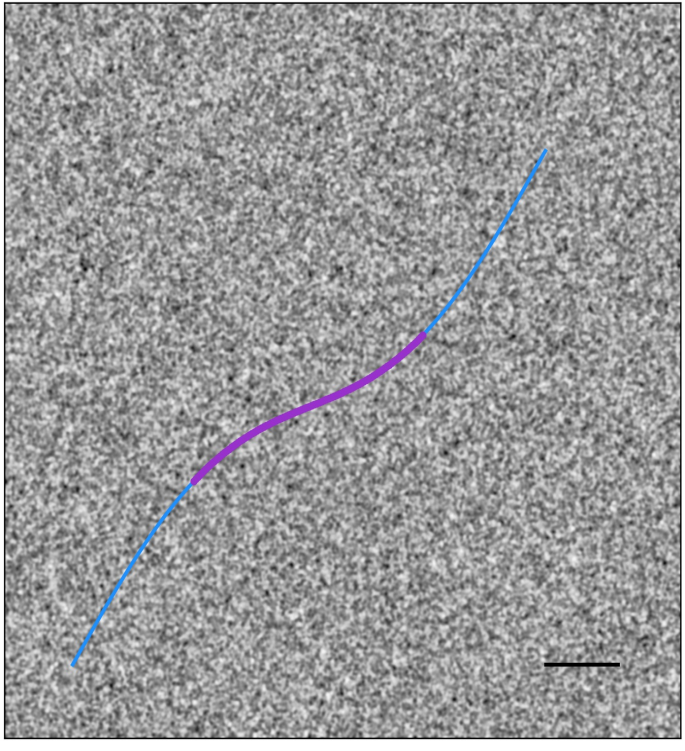

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

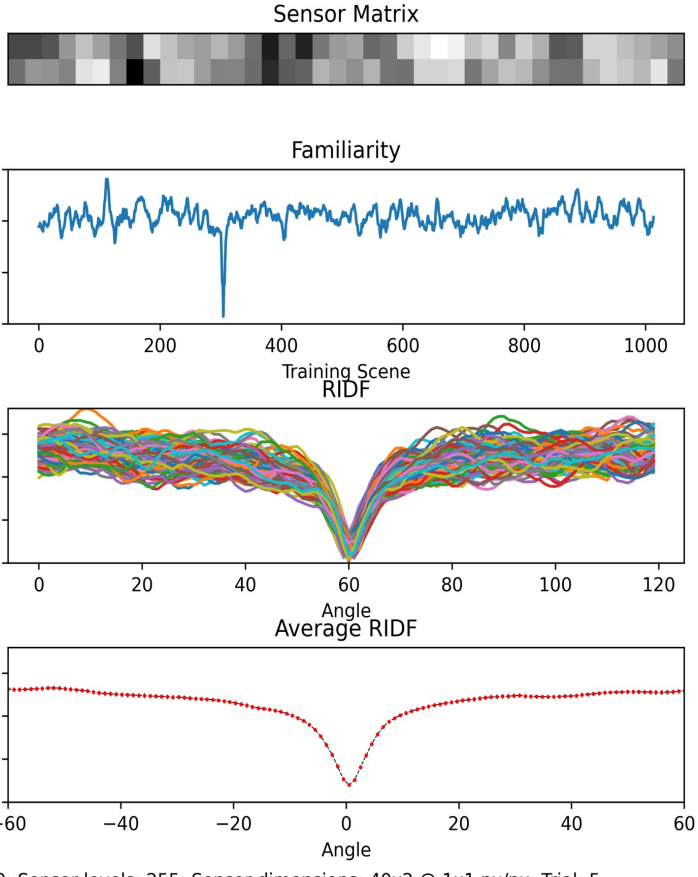





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

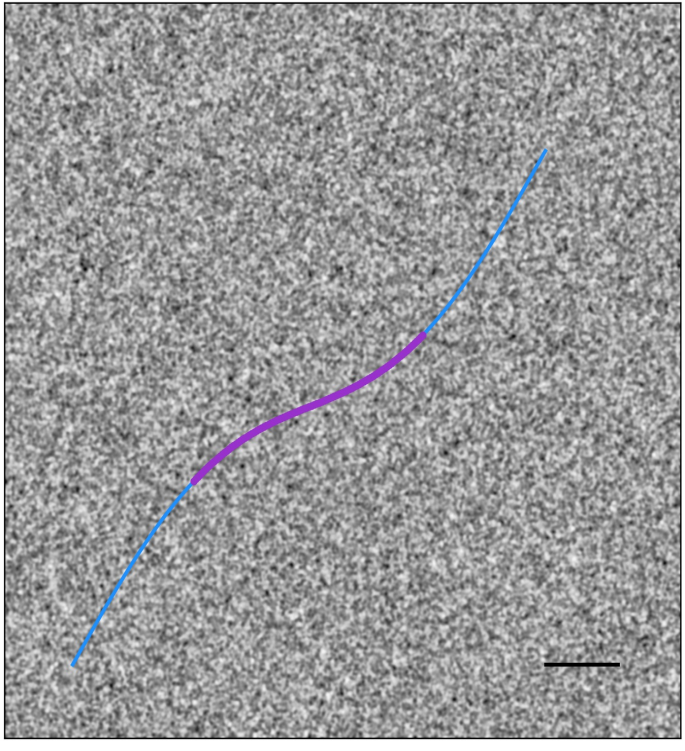
Navigation stats: RMSD error: 64.09; RMSD/dist: 0.160; TD: 6939; p90: 18; p50: 8; complete: 0

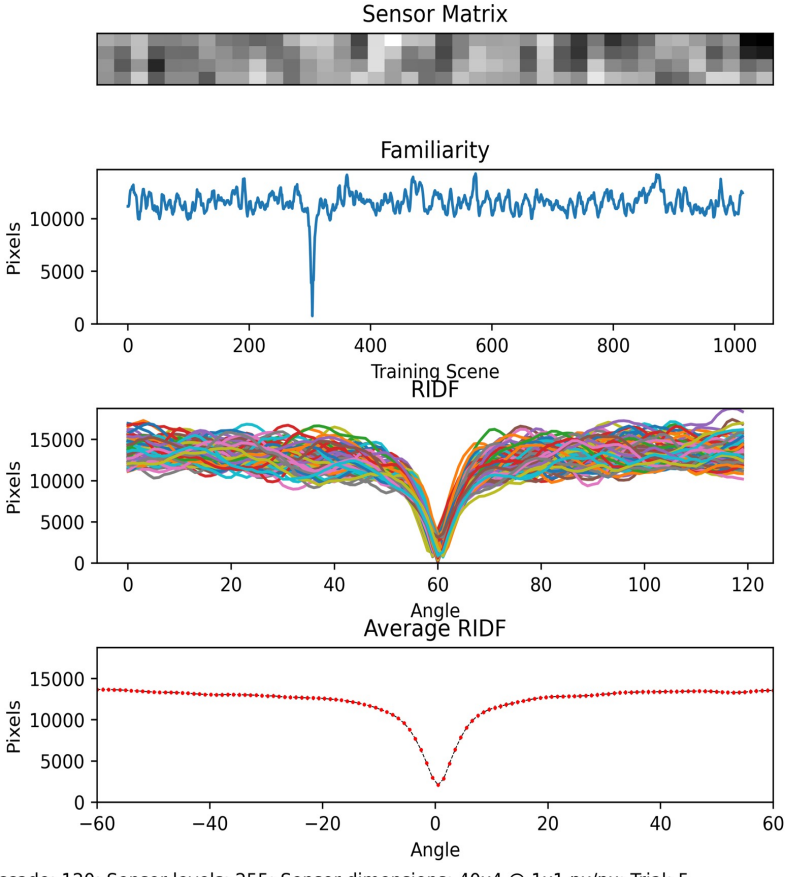





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

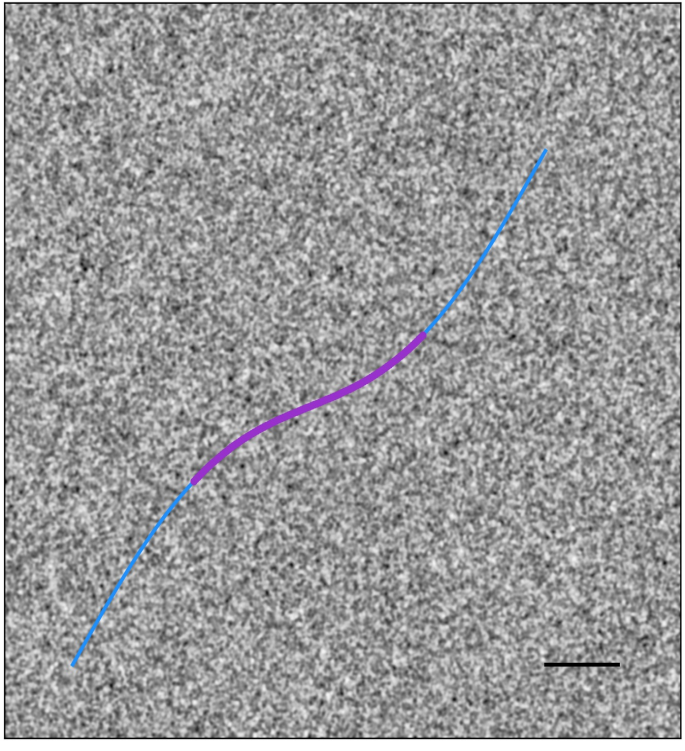
Navigation stats: RMSD error: 50.05; RMSD/dist: 0.125; TD: 8710; p90: 18; p50: 8; complete: 0

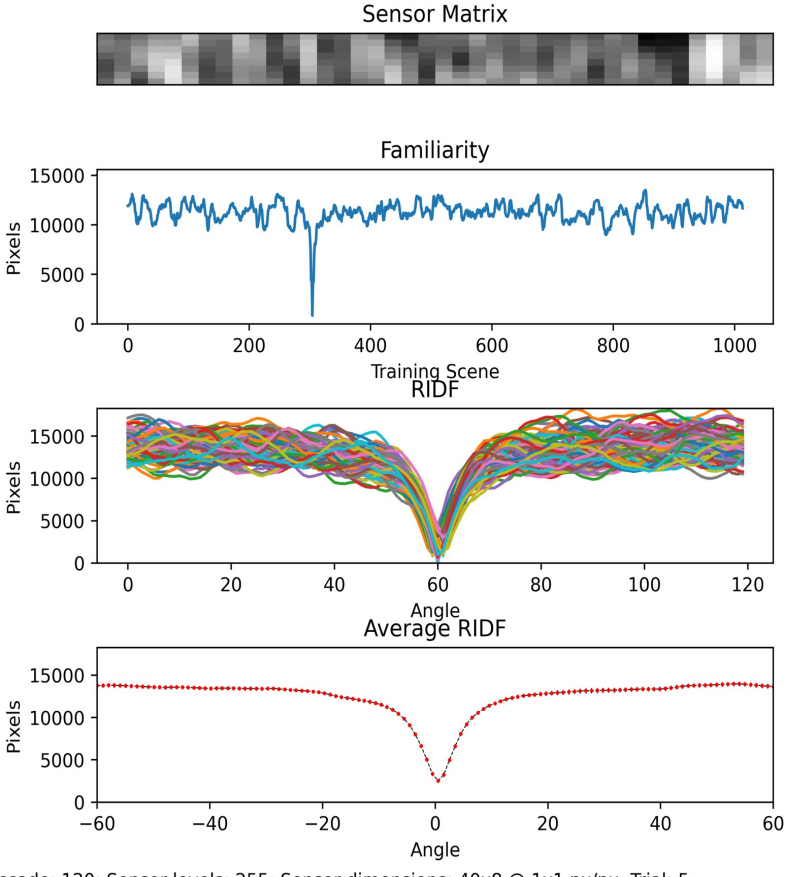





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

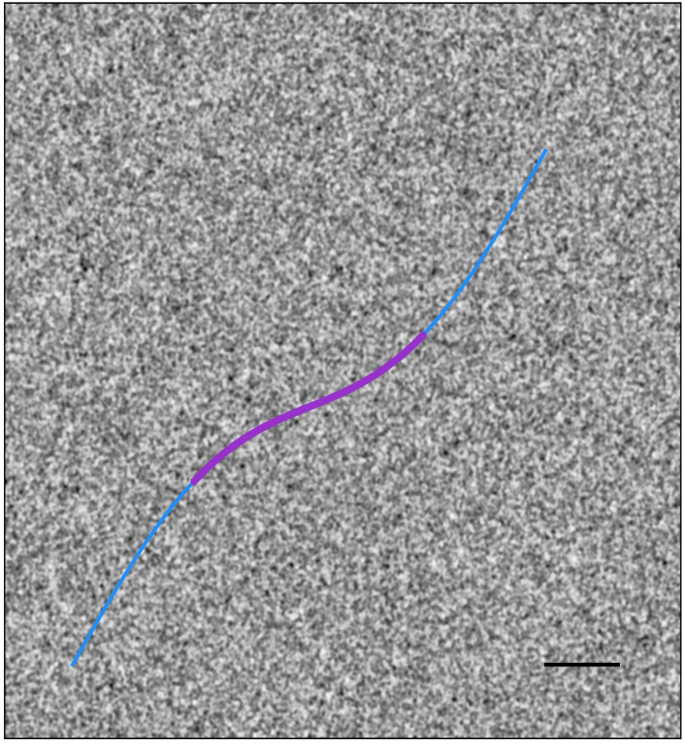
Navigation stats: RMSD error: 44.79; RMSD/dist: 0.112; TD: 9230; p90: 14; p50: 6; complete: 0

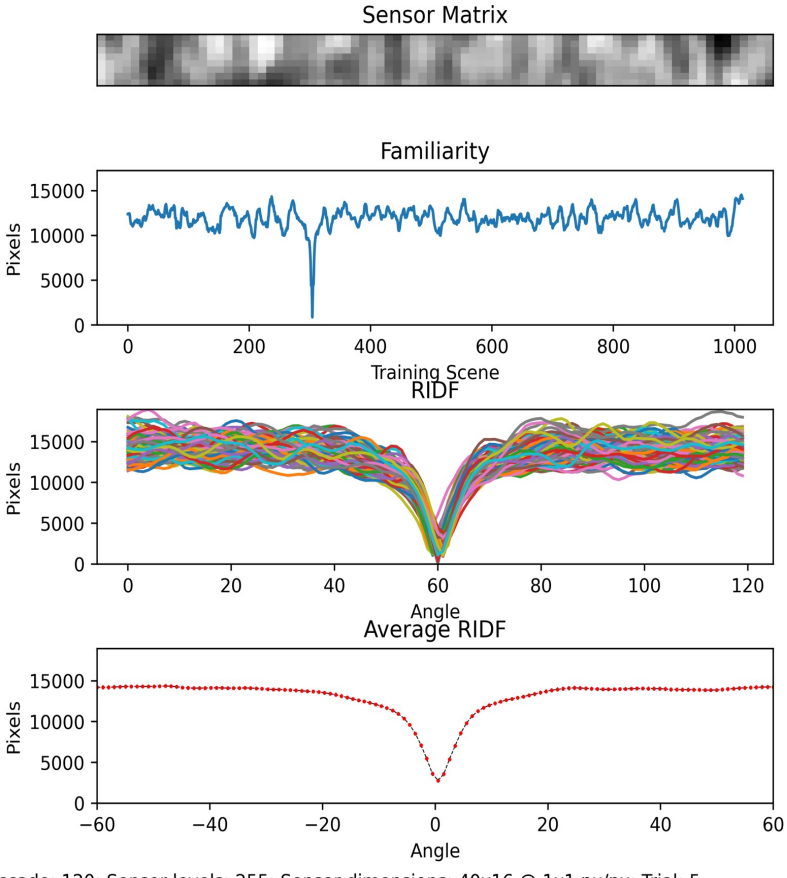





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

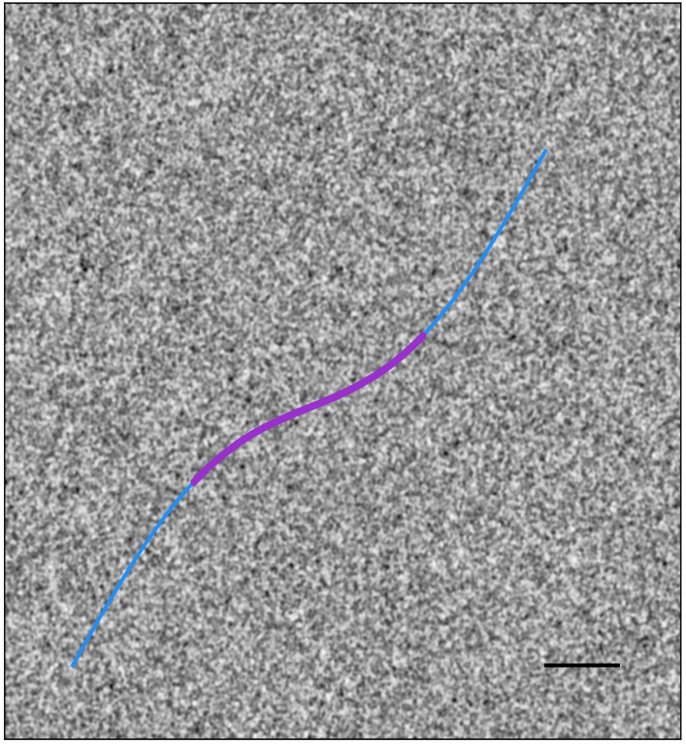
Navigation stats: RMSD error: 53.33; RMSD/dist: 0.133; TD: 9008; p90: 14; p50: 6; complete: 0

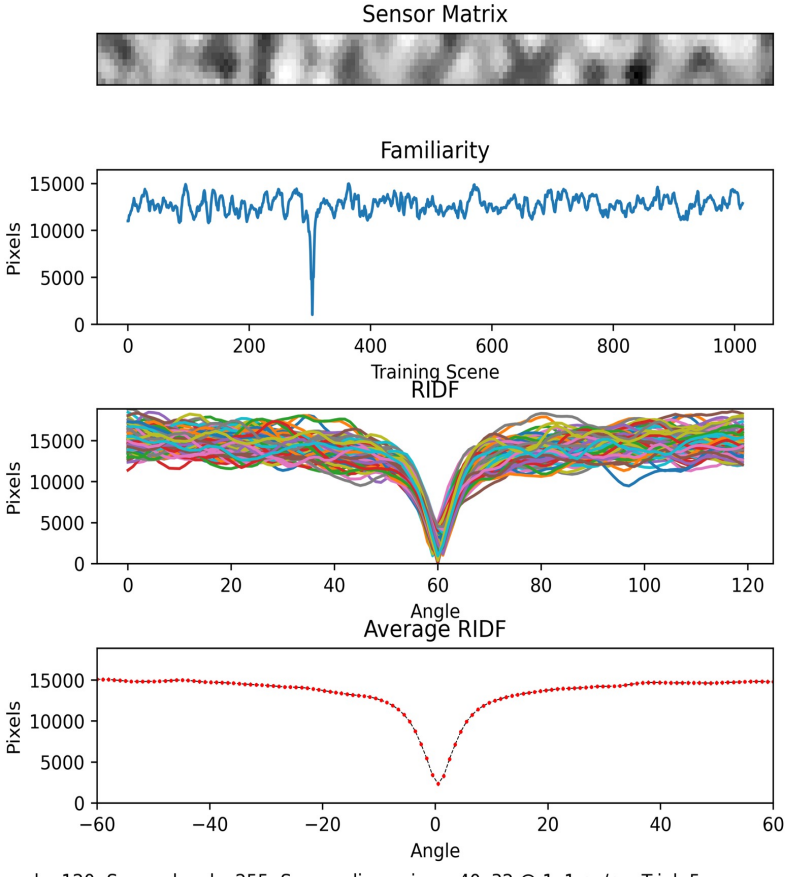





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

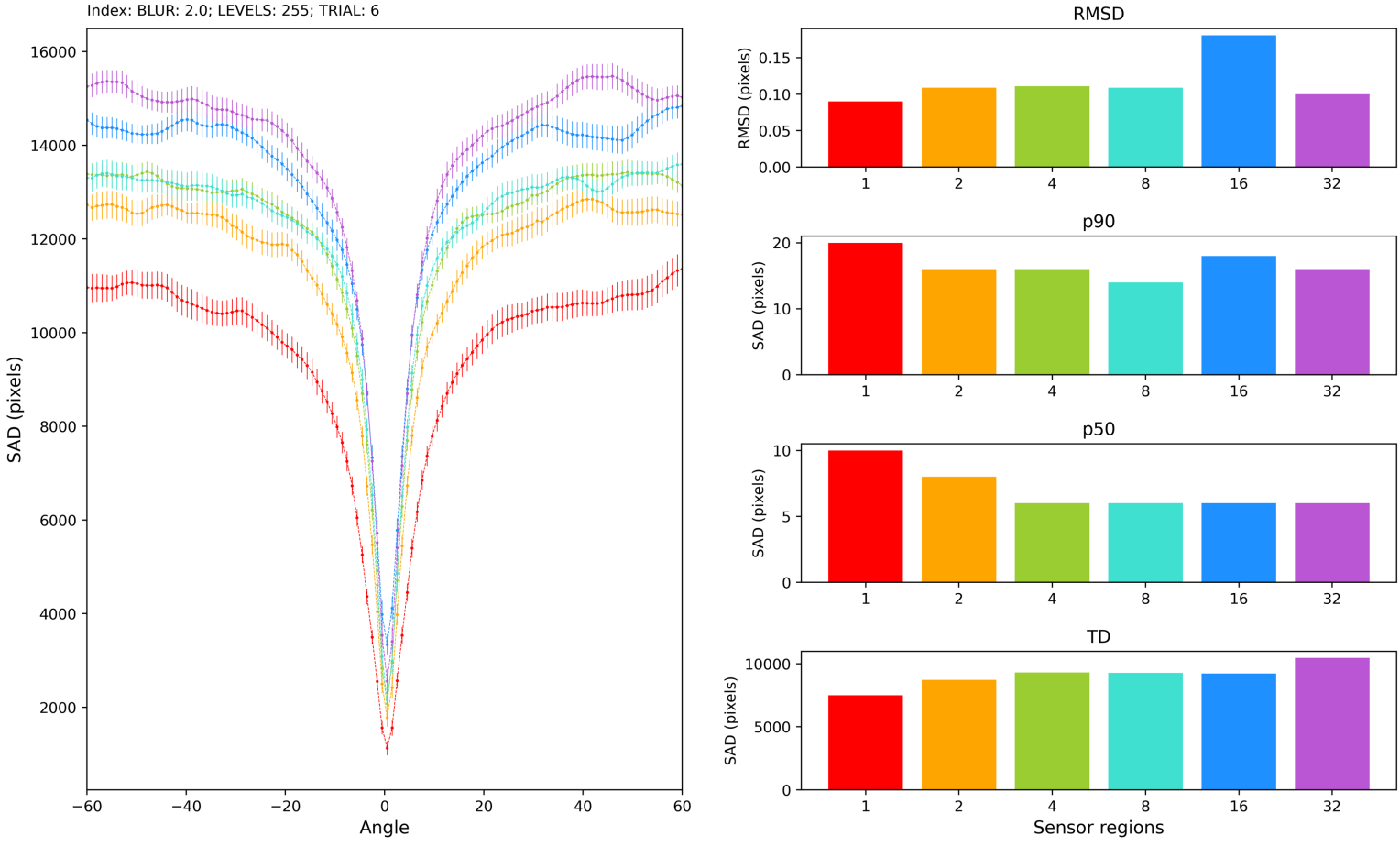
Navigation stats: RMSD error: 51.73; RMSD/dist: 0.129; TD: 9652; p90: 16; p50: 6; complete: 0

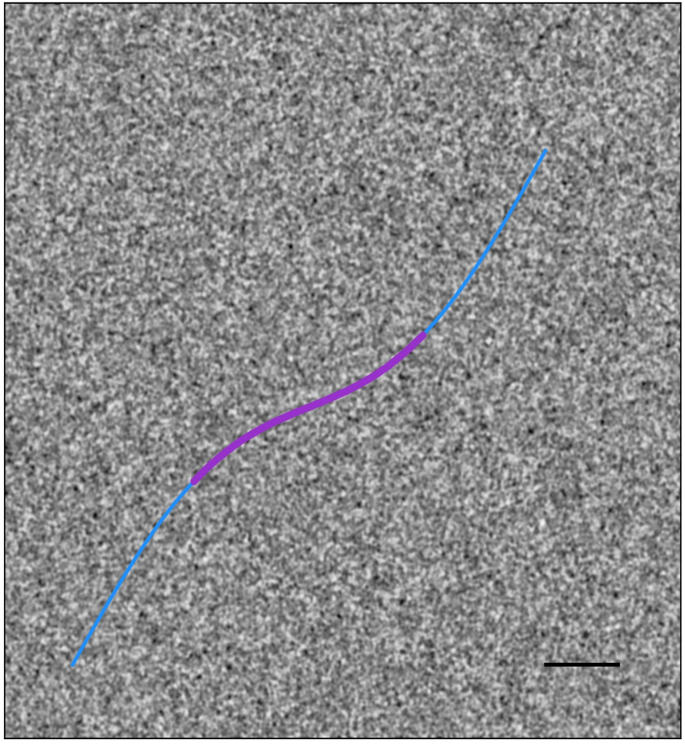


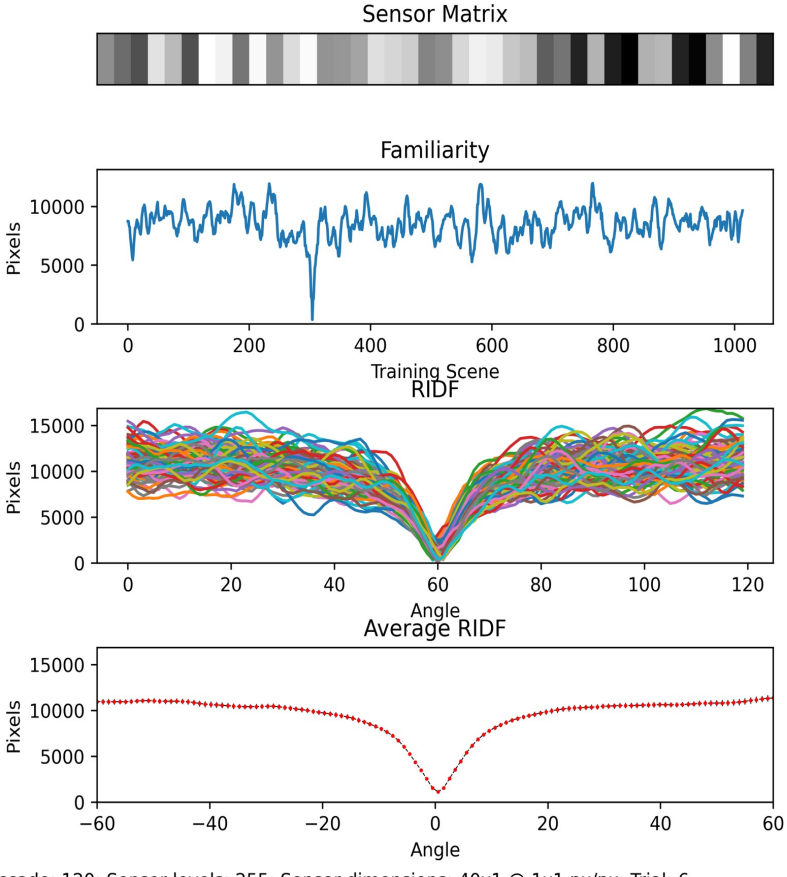



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 34.89; RMSD/dist: 0.087; TD: 10510; p90: 16; p50: 6; complete: 0

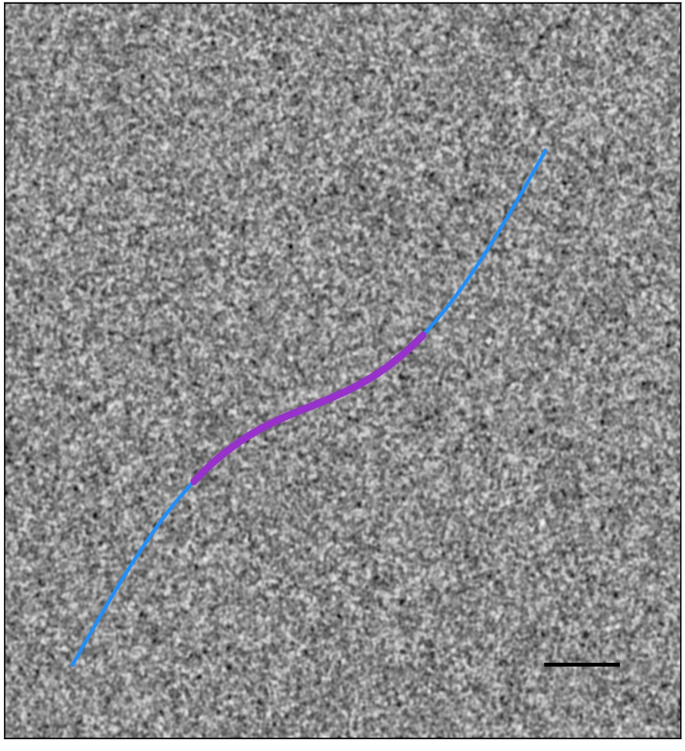

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

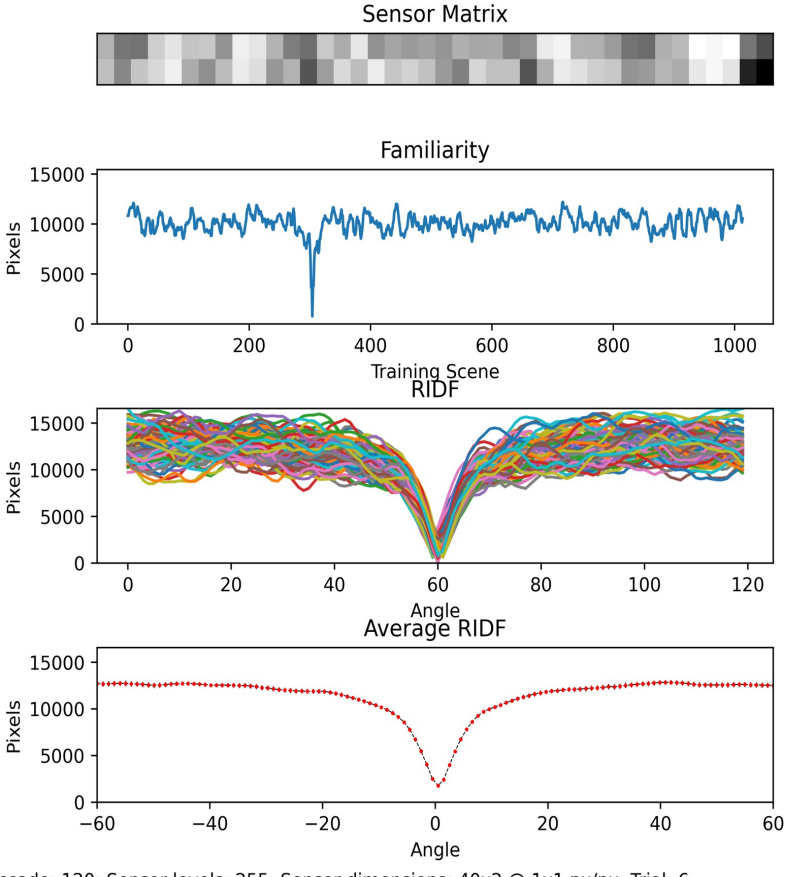





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

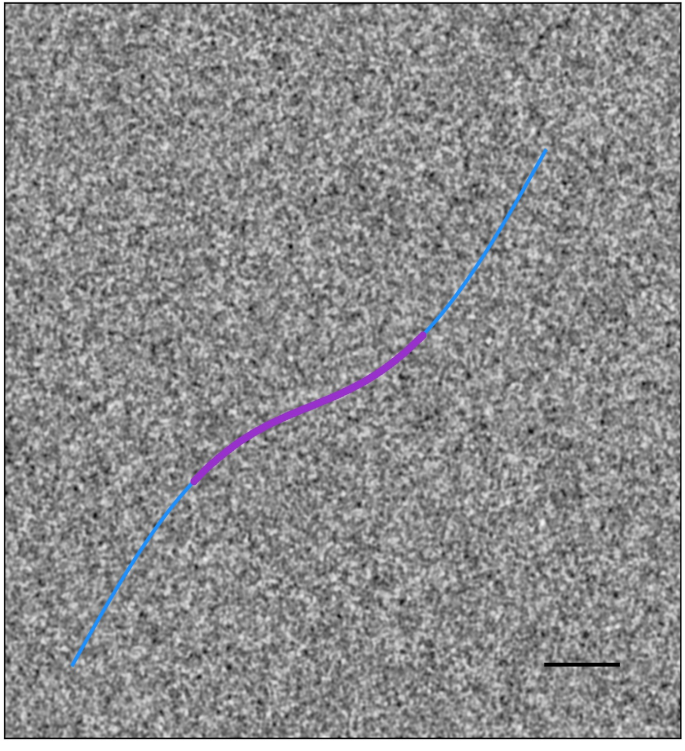
Navigation stats: RMSD error: 36.06; RMSD/dist: 0.090; TD: 7507; p90: 20; p50: 10; complete: 0

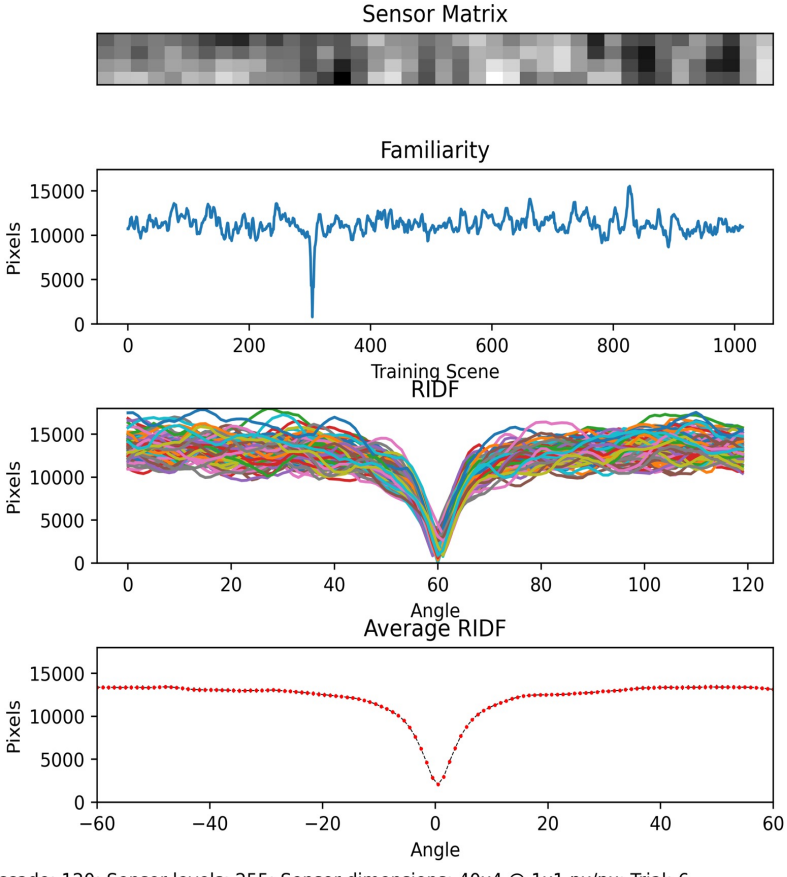





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

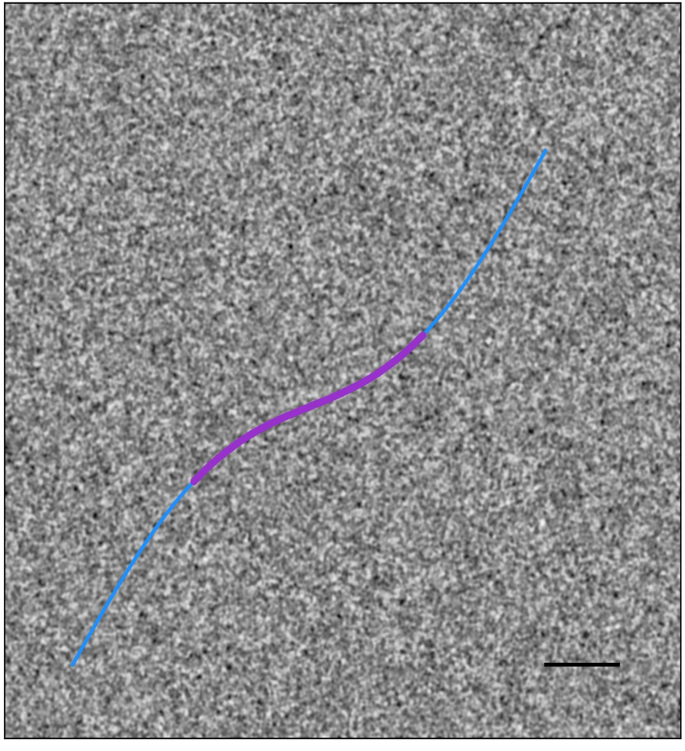
Navigation stats: RMSD error: 43.77; RMSD/dist: 0.109; TD: 8726; p90: 16; p50: 8; complete: 0

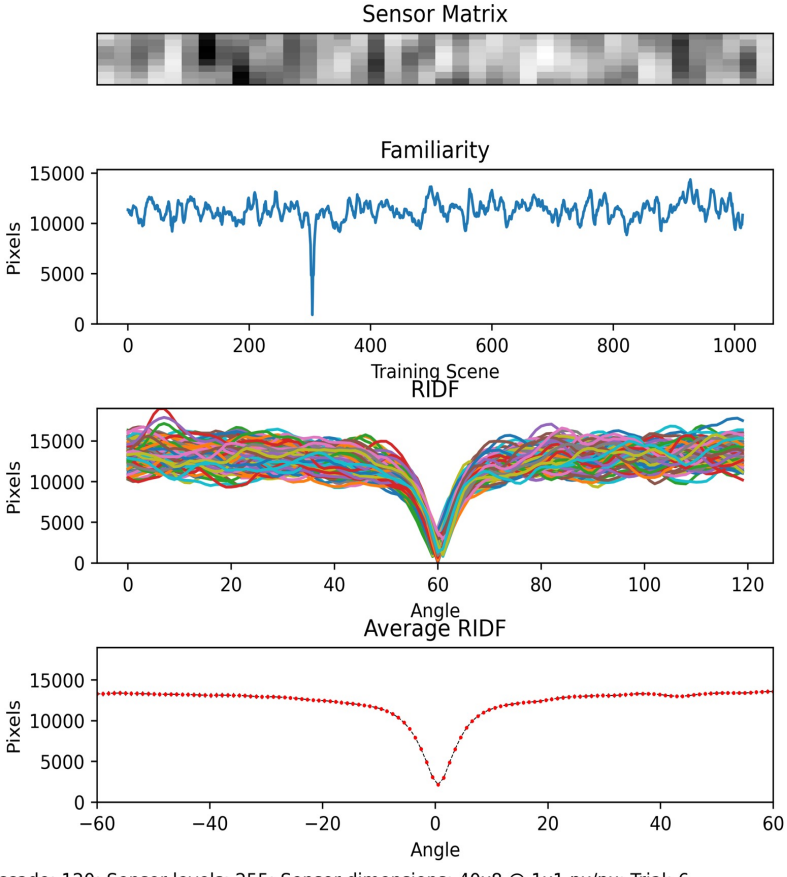





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

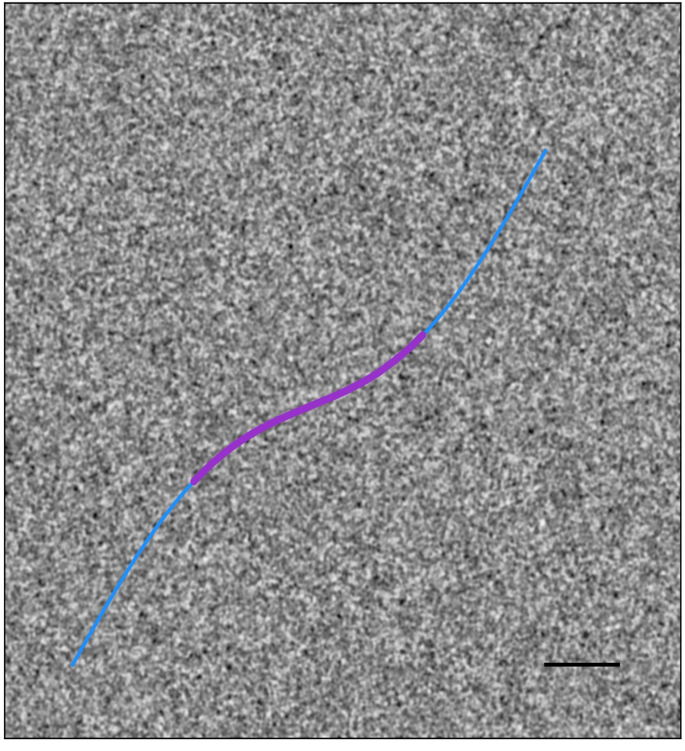
Navigation stats: RMSD error: 44.21; RMSD/dist: 0.111; TD: 9318; p90: 16; p50: 6; complete: 0

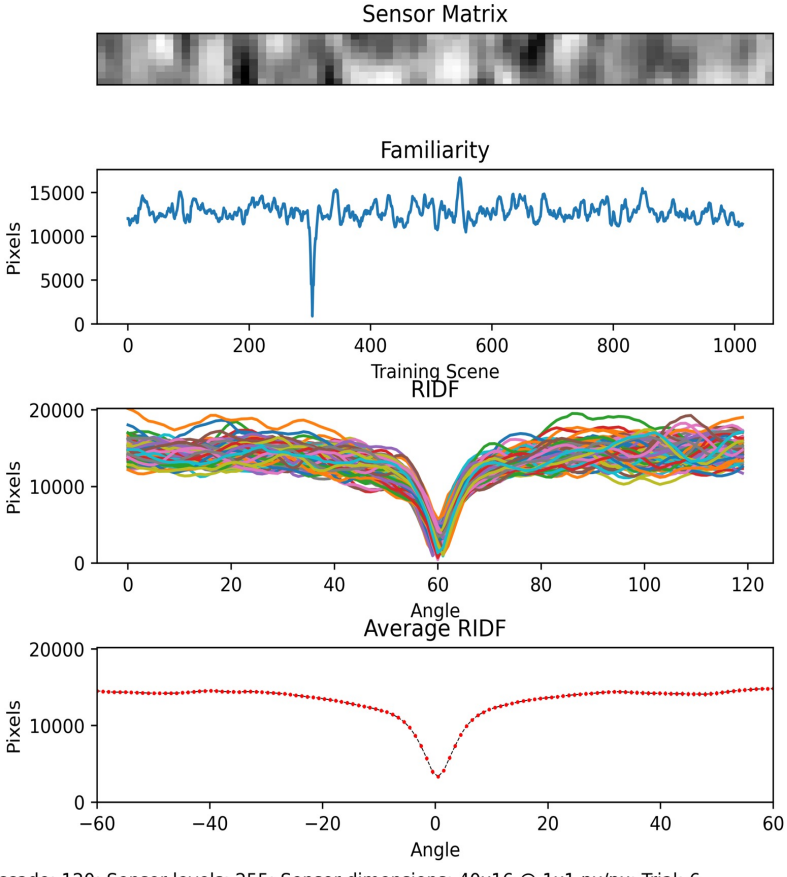





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

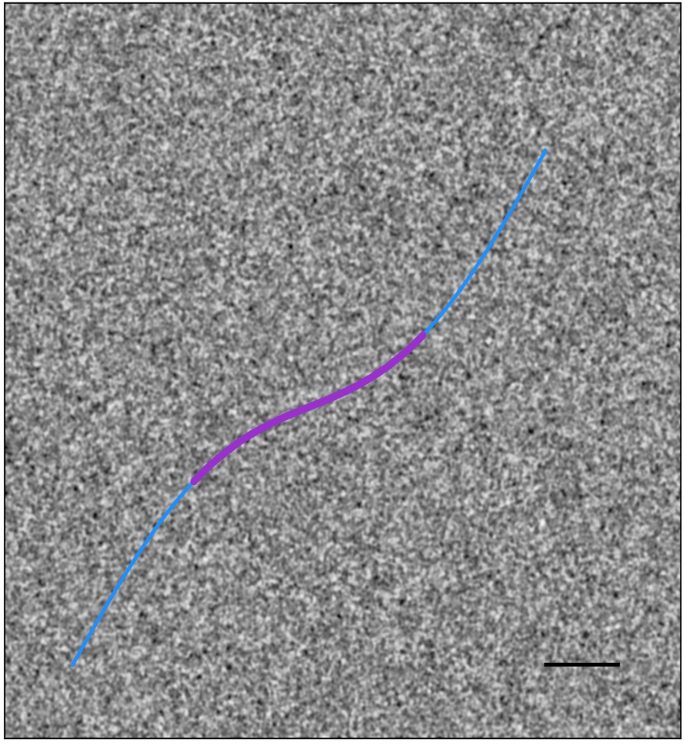
Navigation stats: RMSD error: 43.76; RMSD/dist: 0.109; TD: 9277; p90: 14; p50: 6; complete: 0

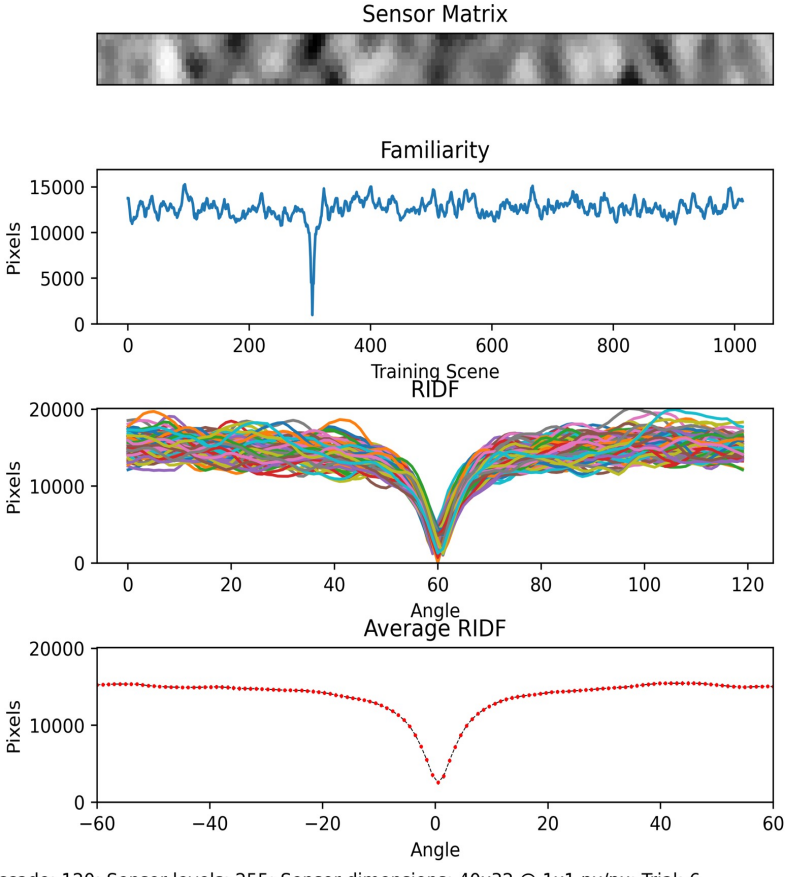





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

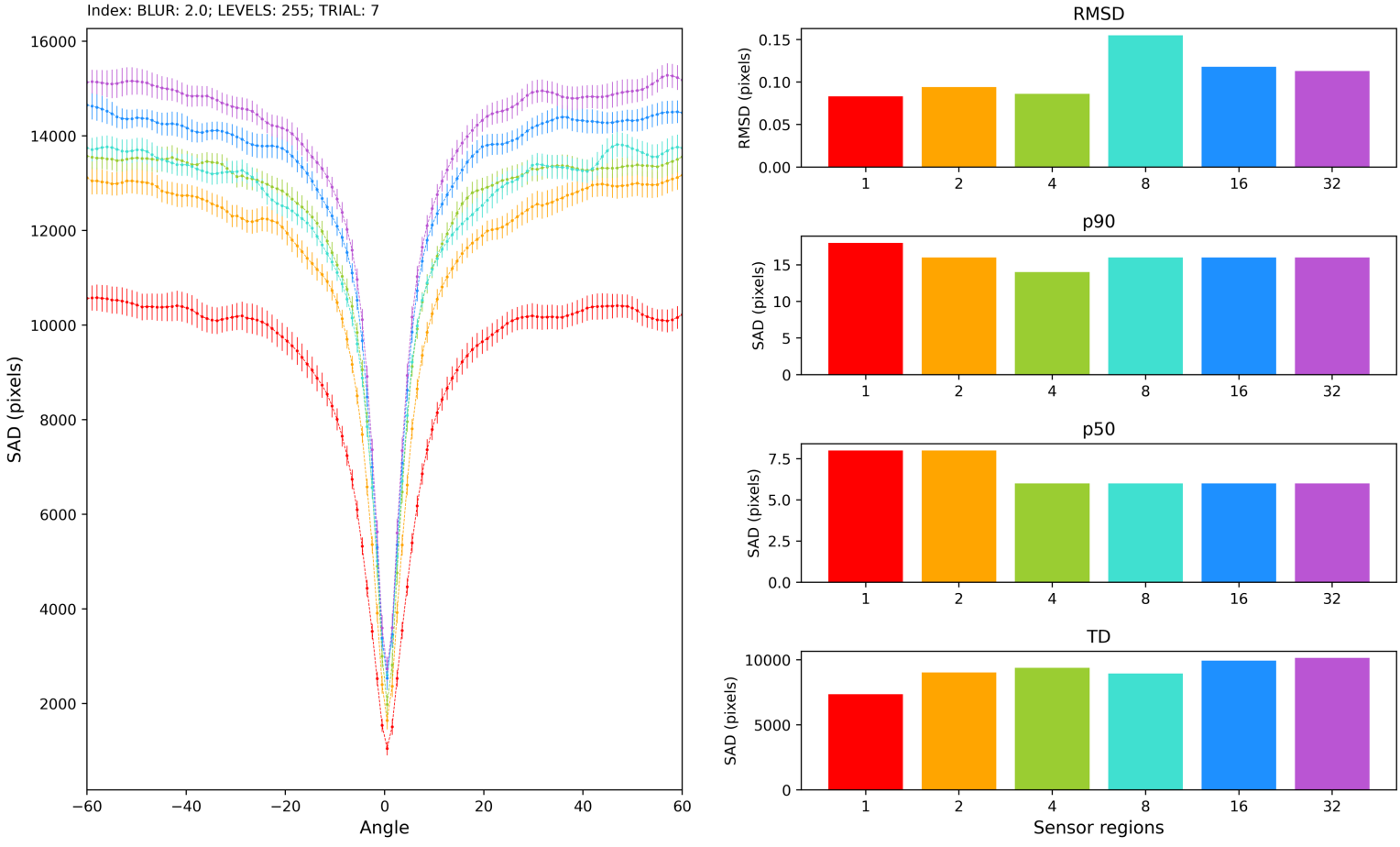
Navigation stats: RMSD error: 72.32; RMSD/dist: 0.181; TD: 9225; p90: 18; p50: 6; complete: 0

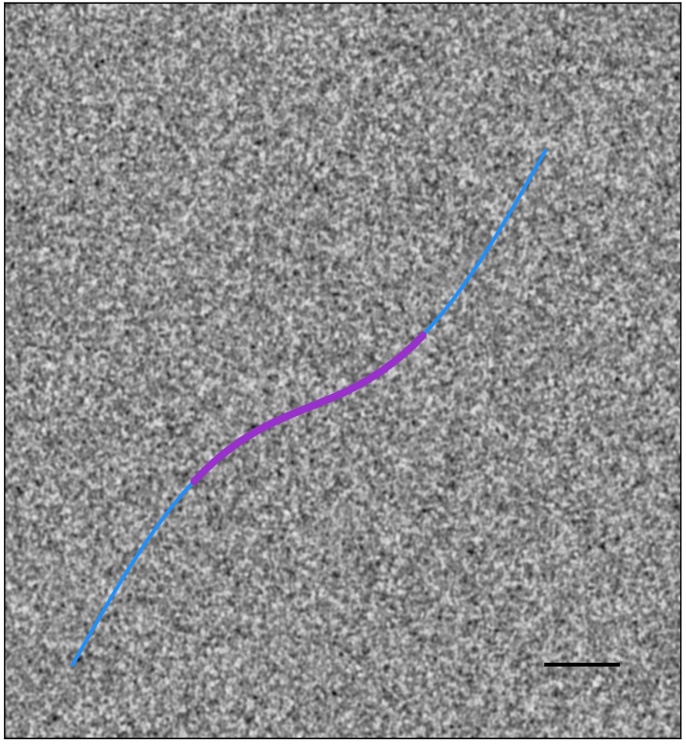


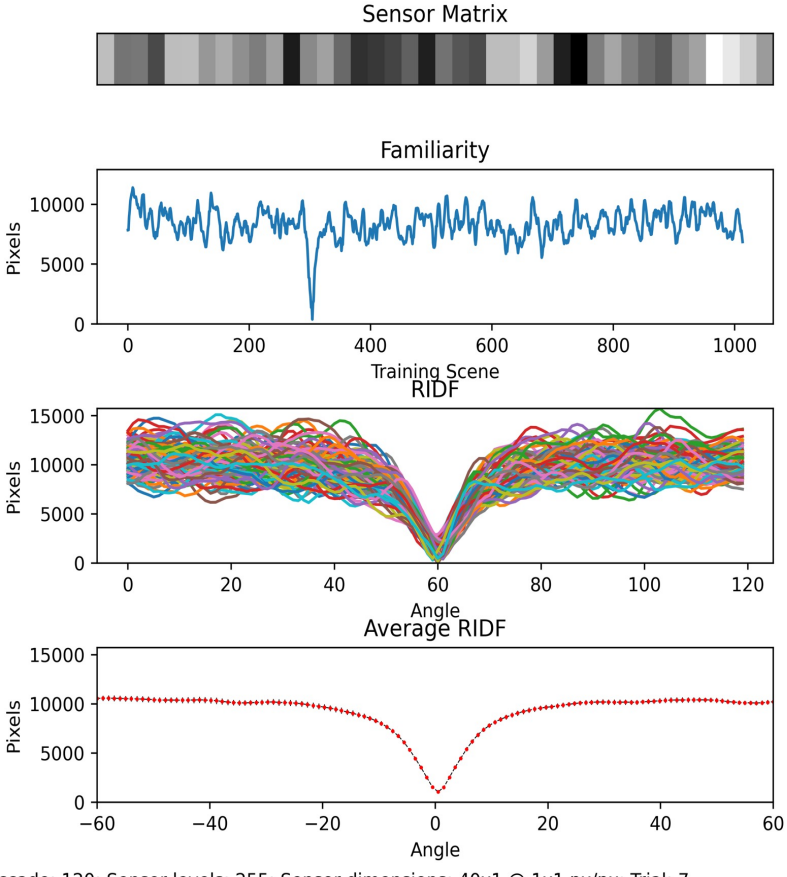



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 40.18; RMSD/dist: 0.100; TD: 10463; p90: 16; p50: 6; complete: 0

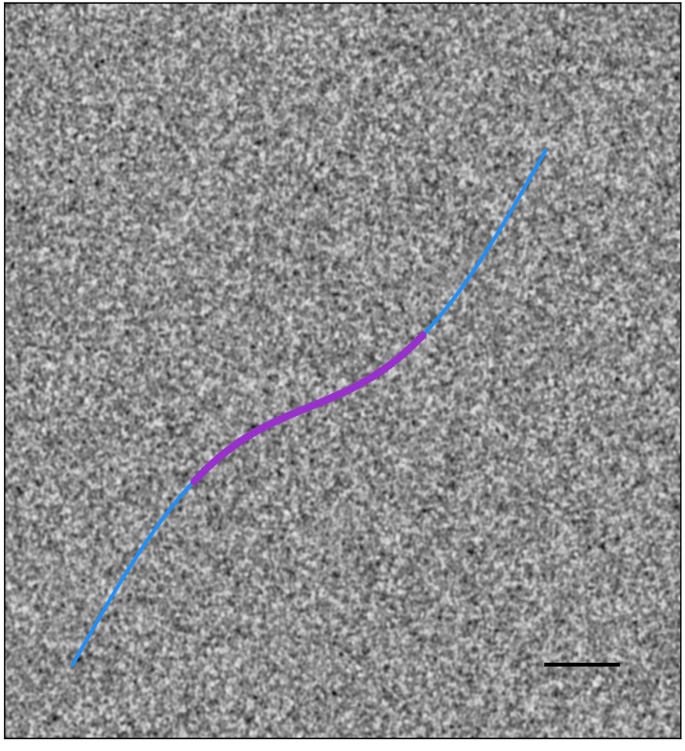

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

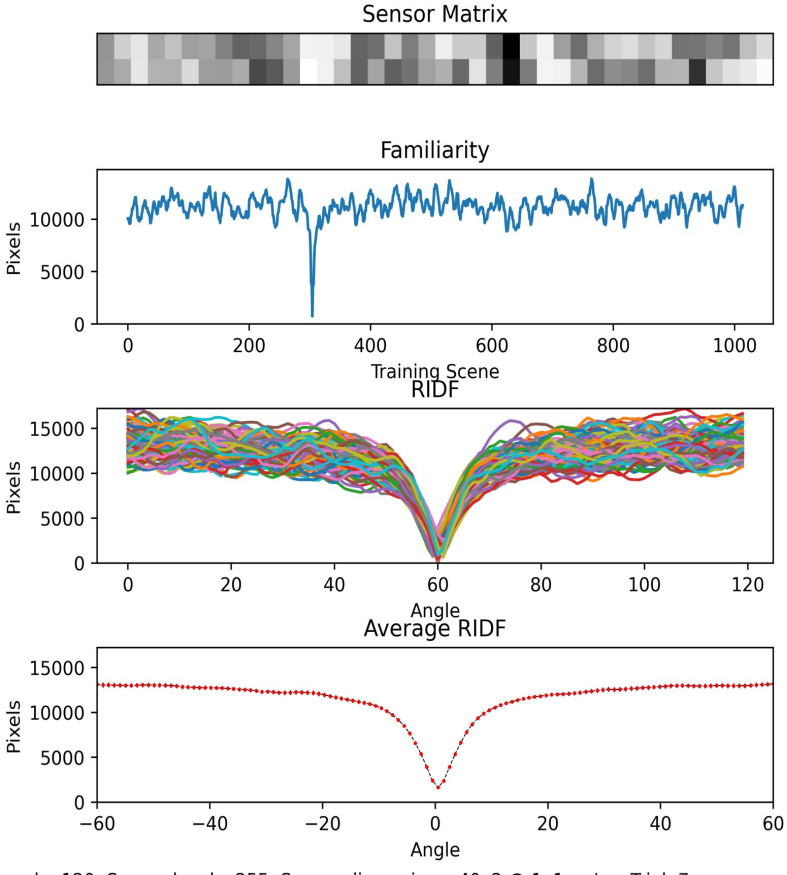





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

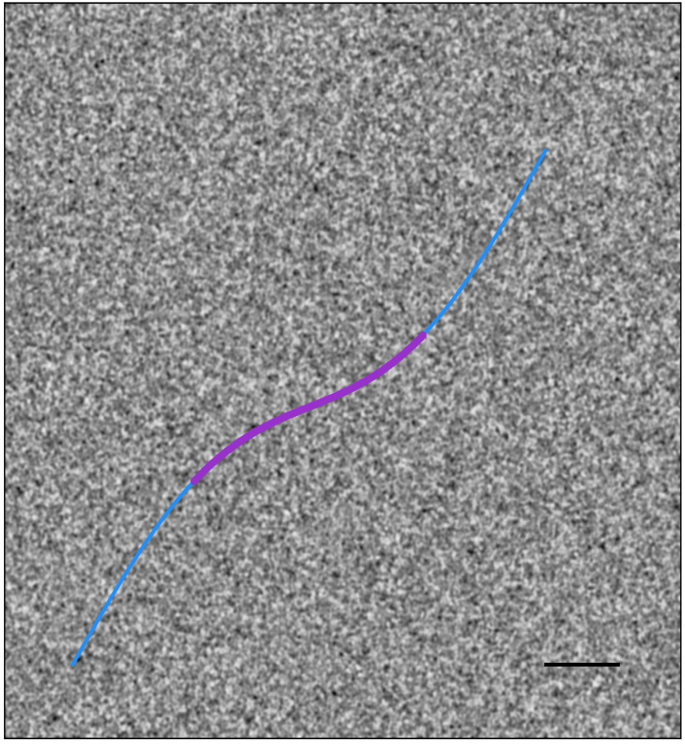
Navigation stats: RMSD error: 33.39; RMSD/dist: 0.083; TD: 7356; p90: 18; p50: 8; complete: 0

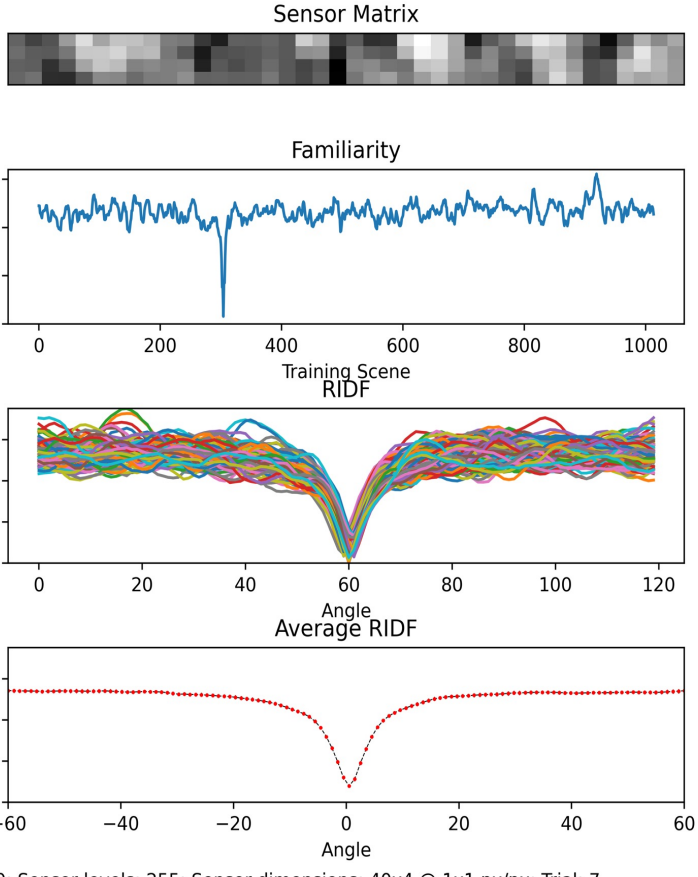





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

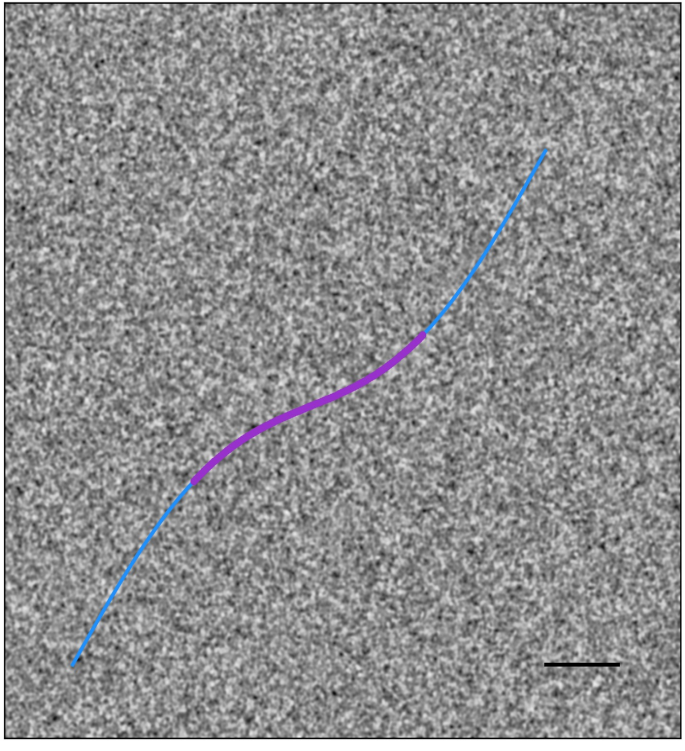
Navigation stats: RMSD error: 37.52; RMSD/dist: 0.094; TD: 9024; p90: 16; p50: 8; complete: 0

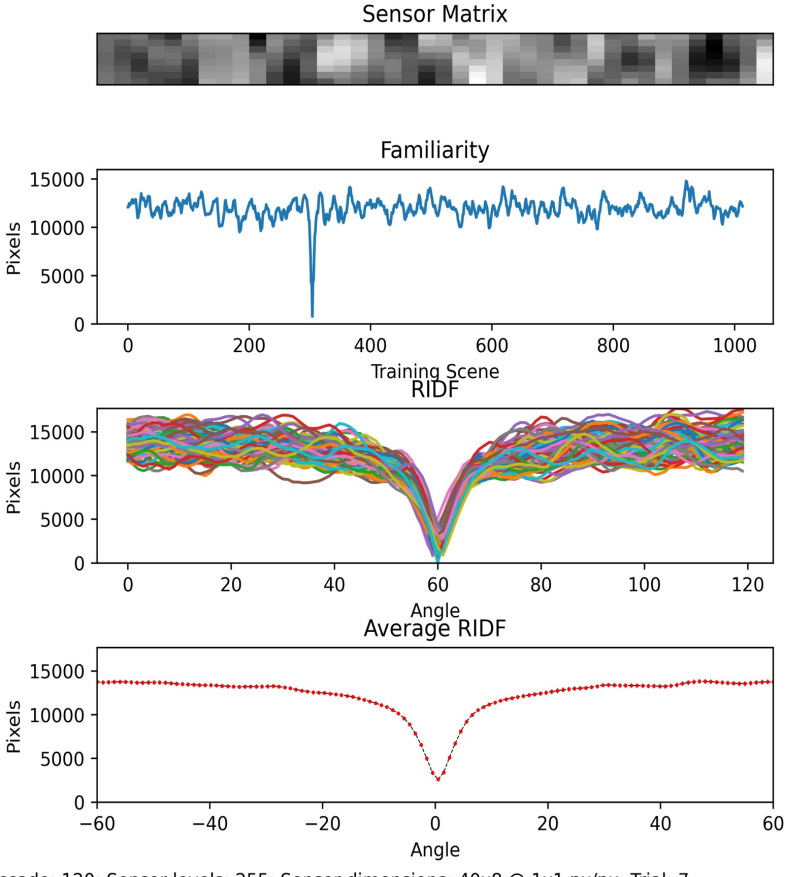





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

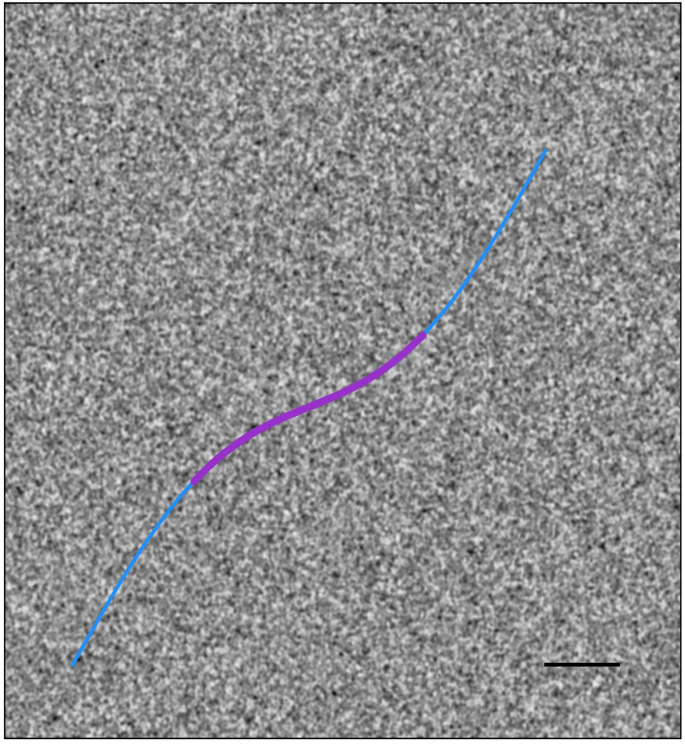
Navigation stats: RMSD error: 34.43; RMSD/dist: 0.086; TD: 9379; p90: 14; p50: 6; complete: 0

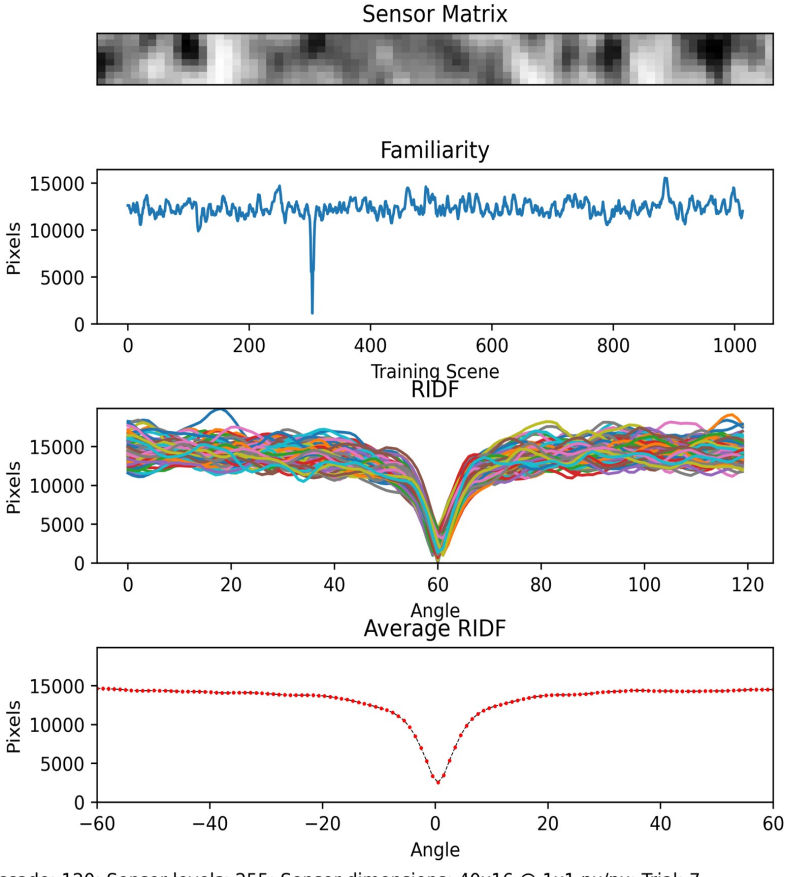





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

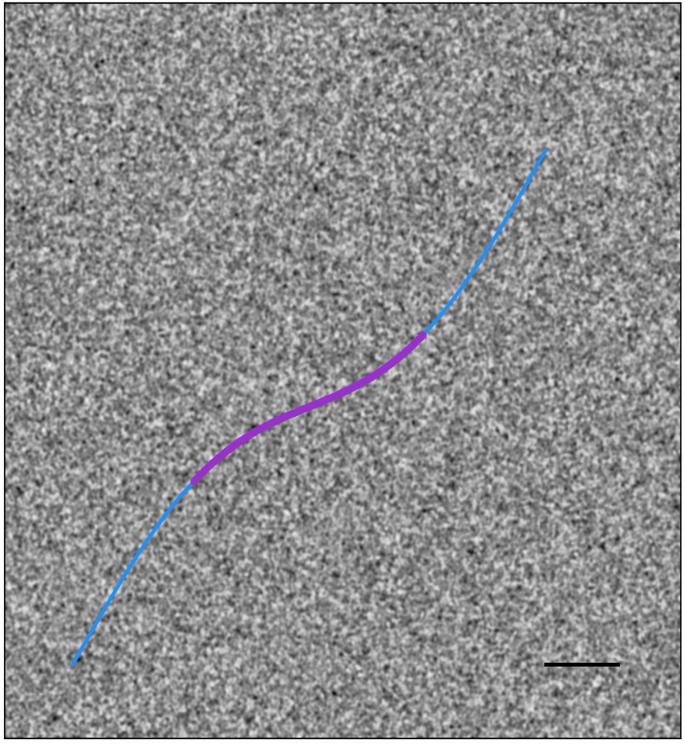
Navigation stats: RMSD error: 61.86; RMSD/dist: 0.155; TD: 8945; p90: 16; p50: 6; complete: 0

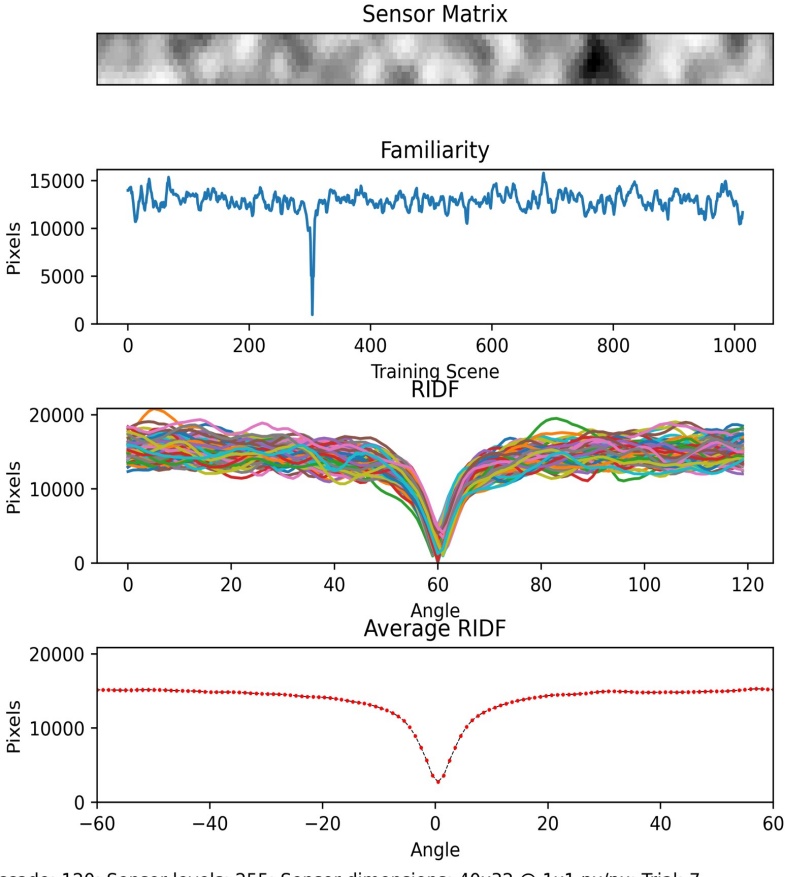





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

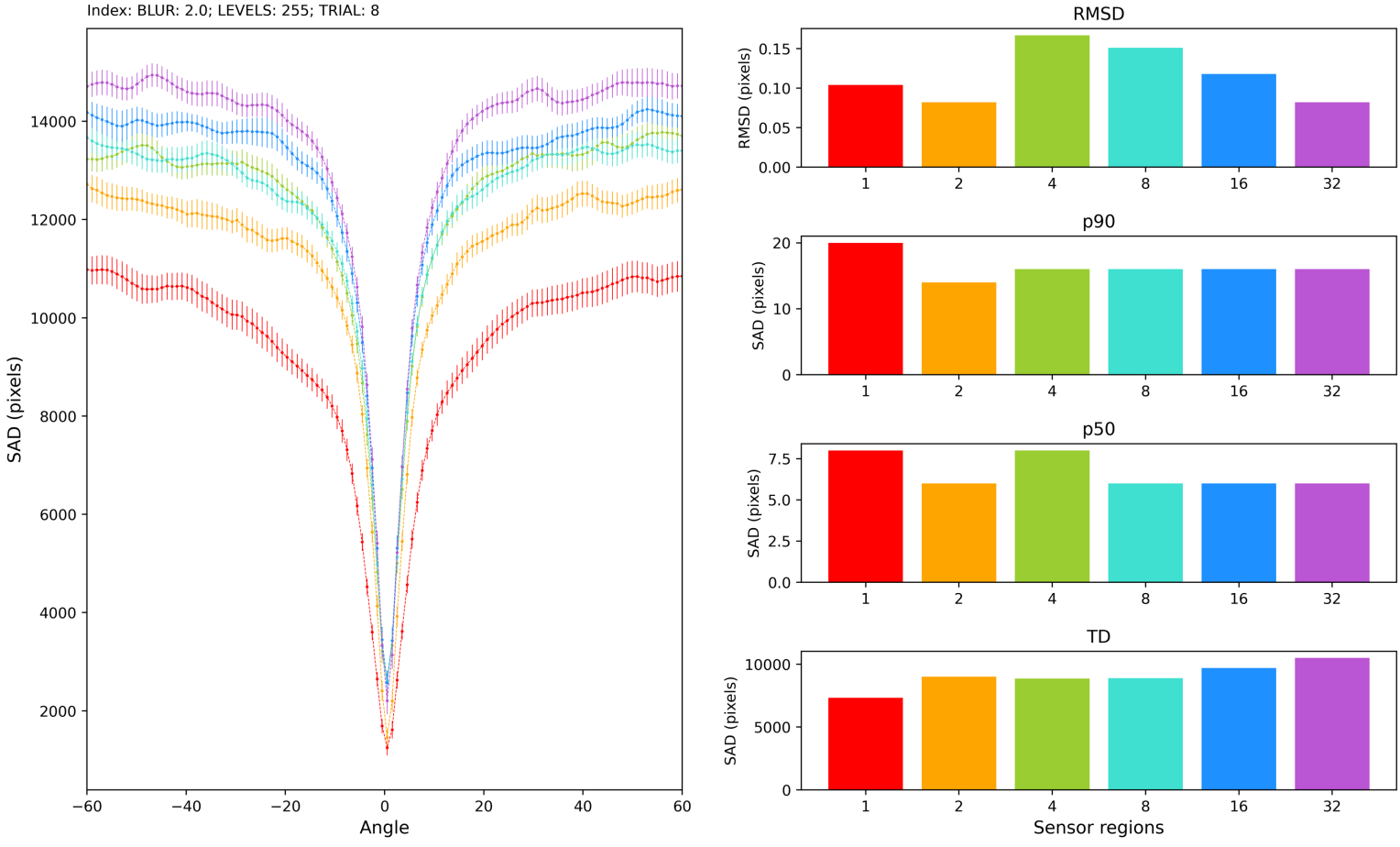
Navigation stats: RMSD error: 47.39; RMSD/dist: 0.118; TD: 9929; p90: 16; p50: 6; complete: 0

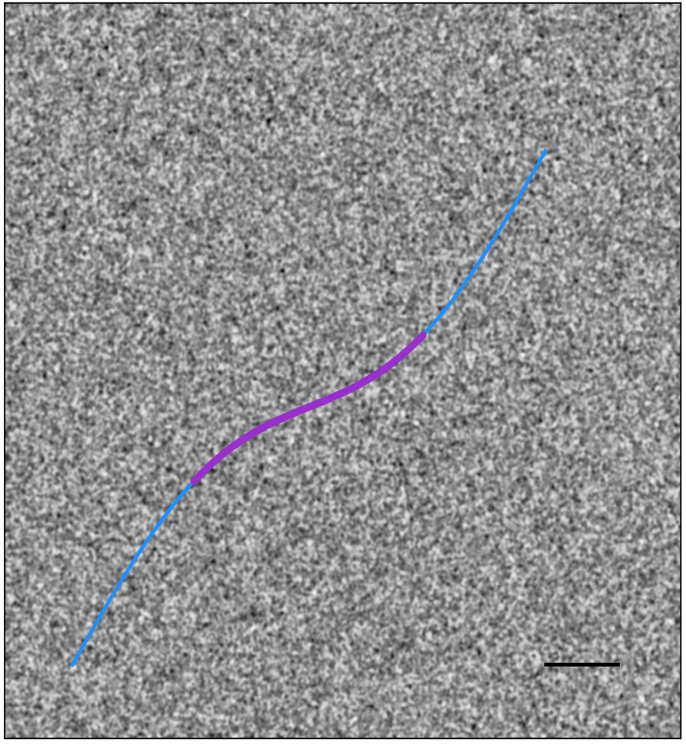


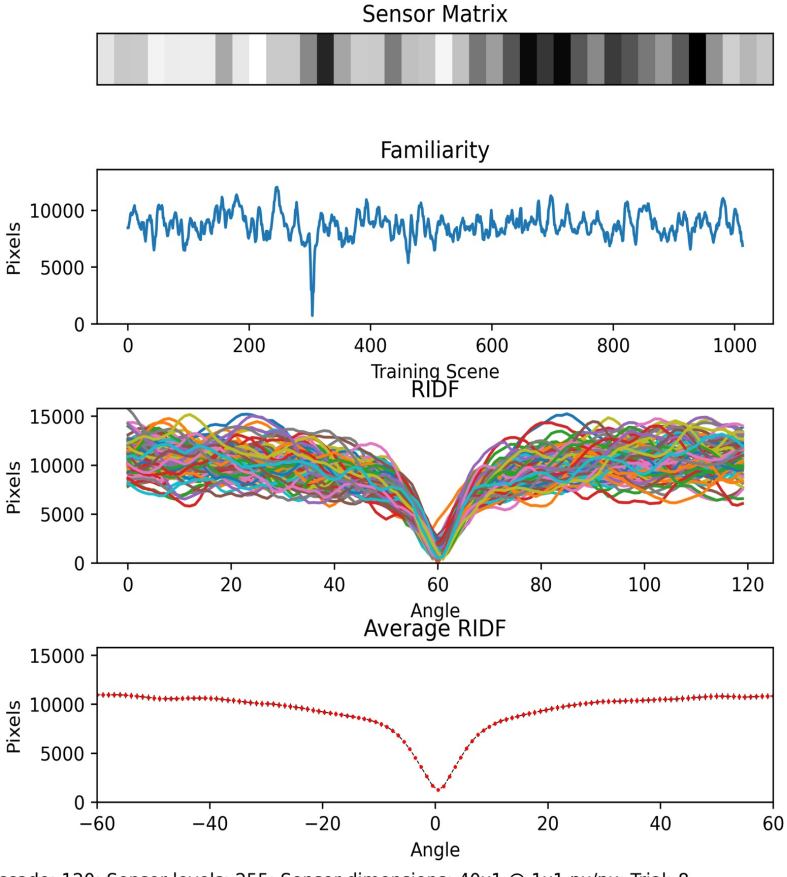



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 45.39; RMSD/dist: 0.113; TD: 10140; p90: 16; p50: 6; complete: 0

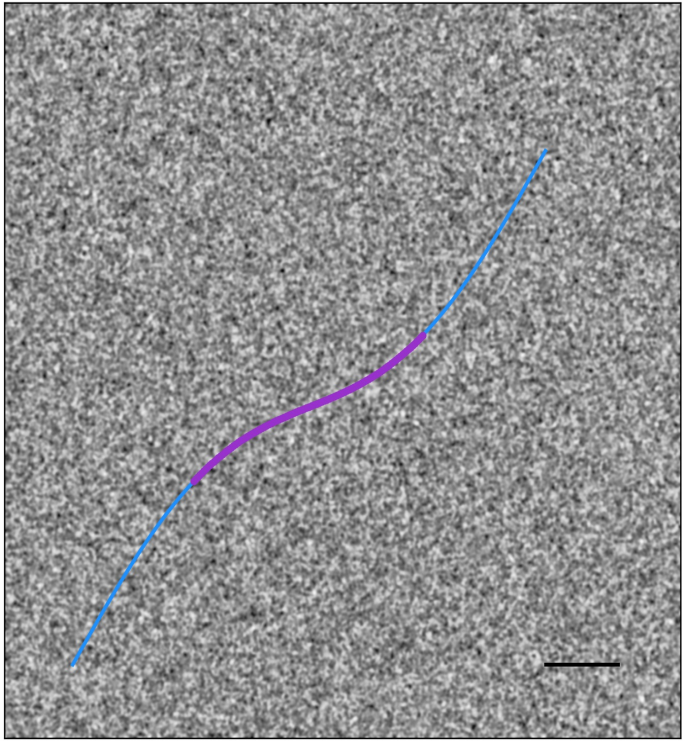

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

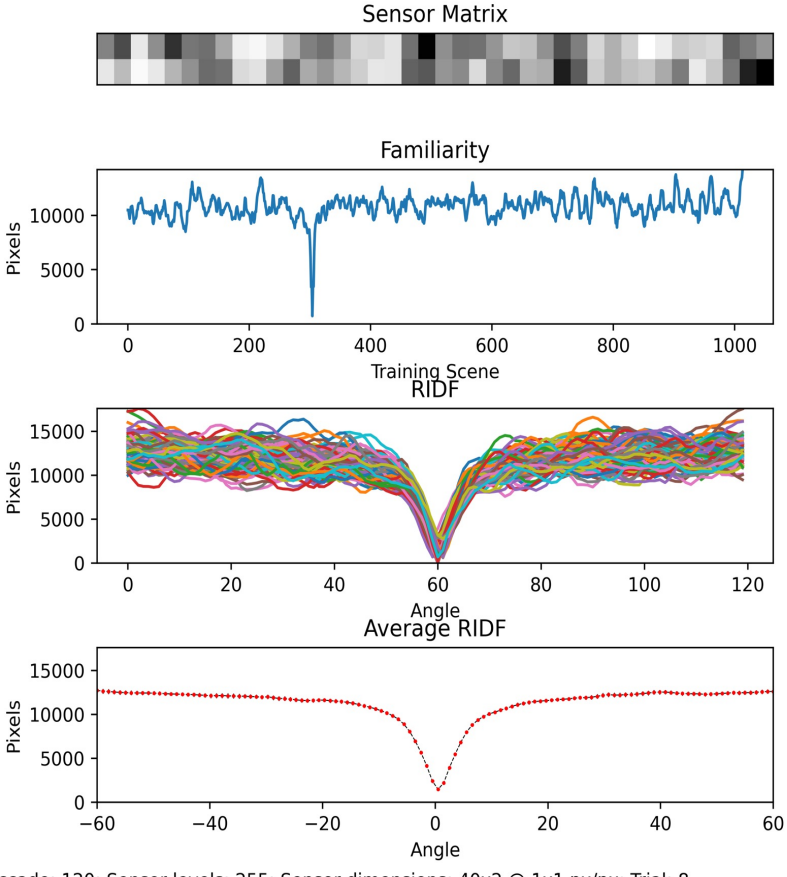





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

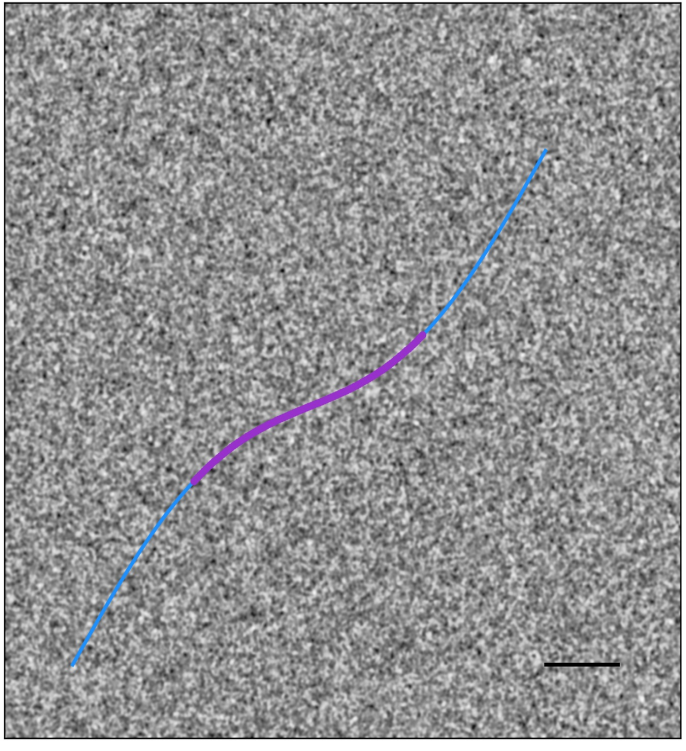
Navigation stats: RMSD error: 41.50; RMSD/dist: 0.104; TD: 7321; p90: 20; p50: 8; complete: 0

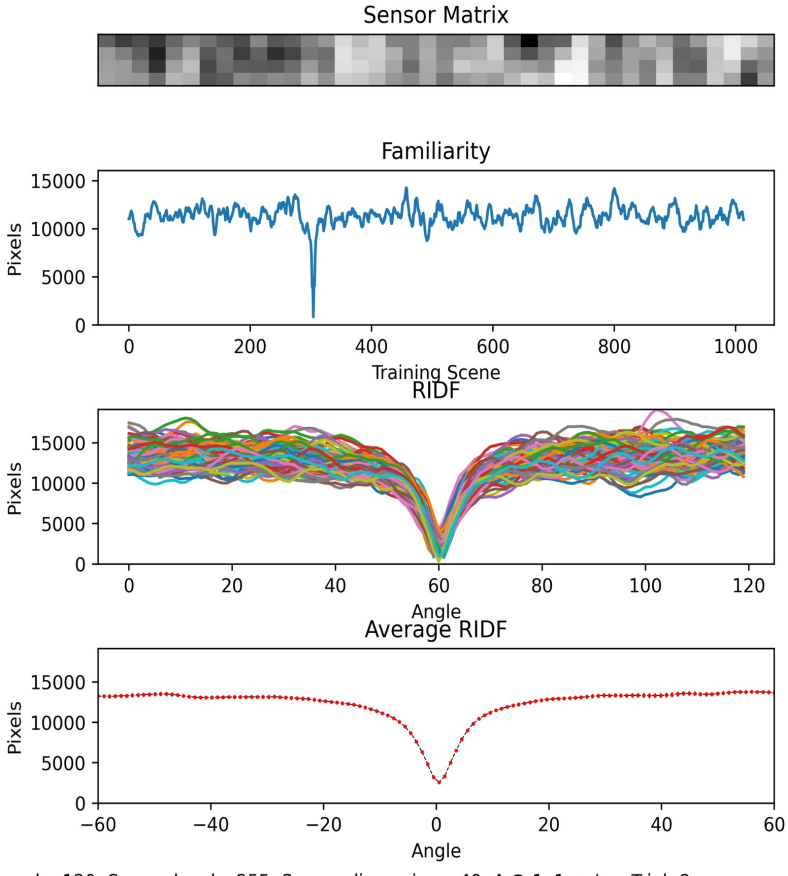





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

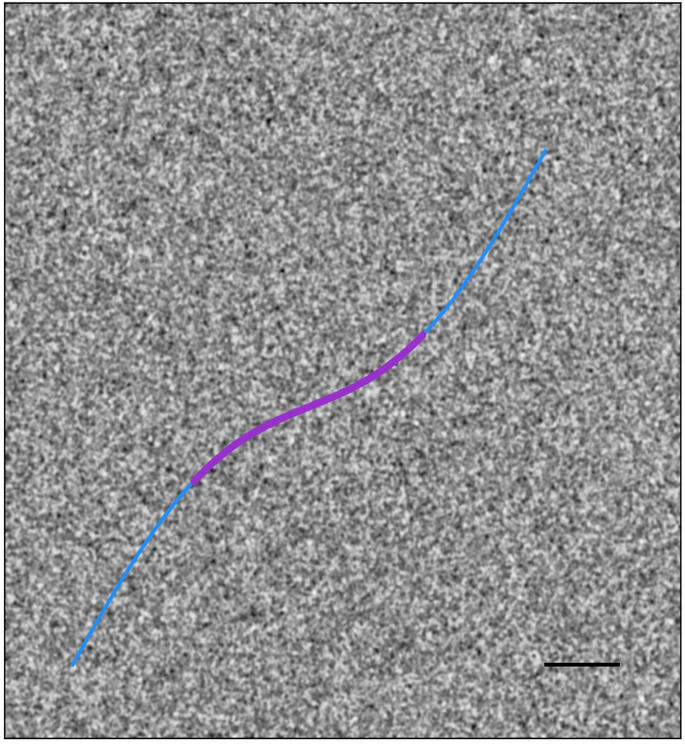
Navigation stats: RMSD error: 32.85; RMSD/dist: 0.082; TD: 9001; p90: 14; p50: 6; complete: 0

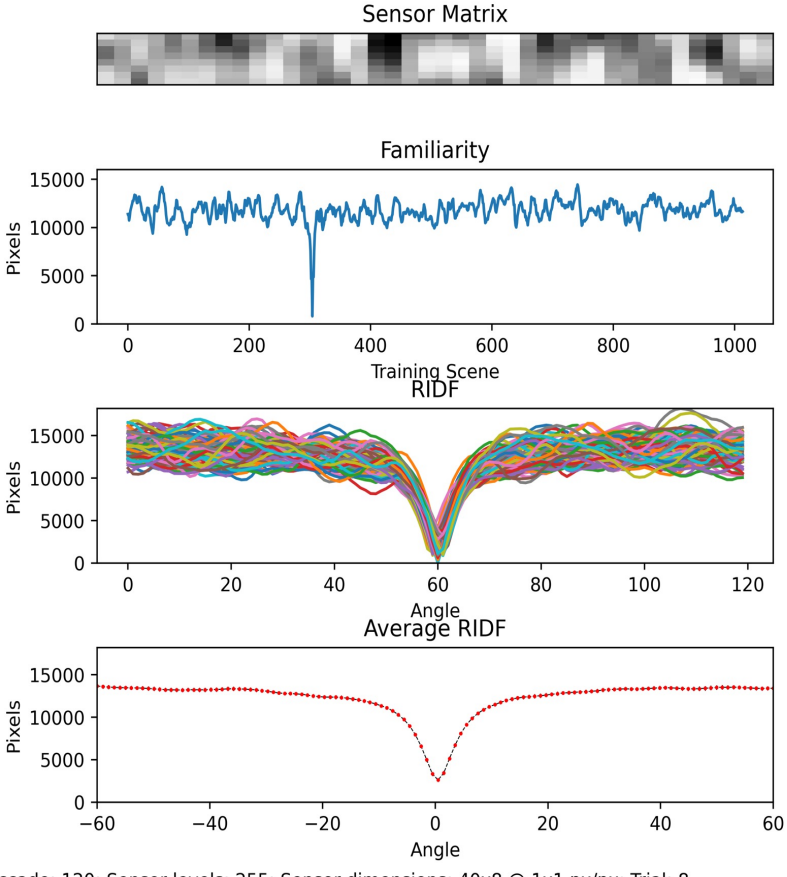





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

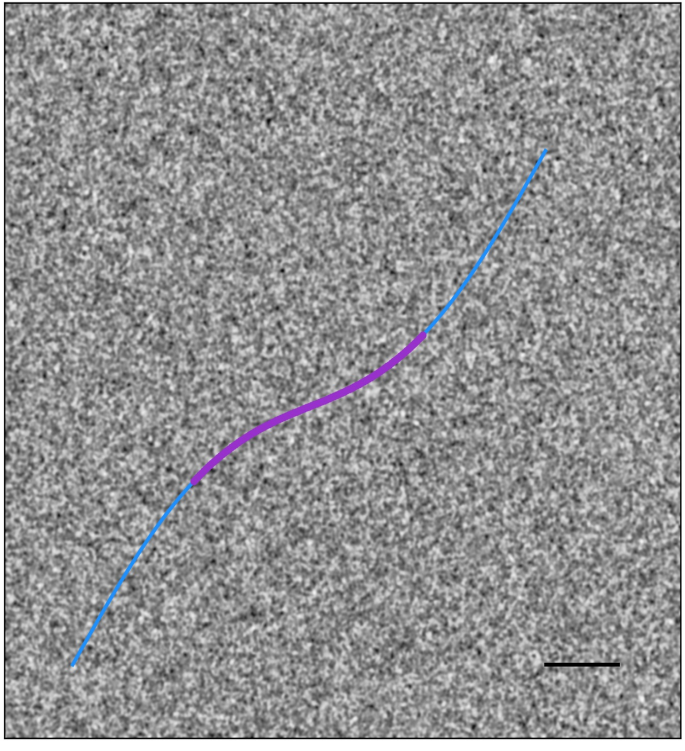
Navigation stats: RMSD error: 66.99; RMSD/dist: 0.167; TD: 8855; p90: 16; p50: 8; complete: 0

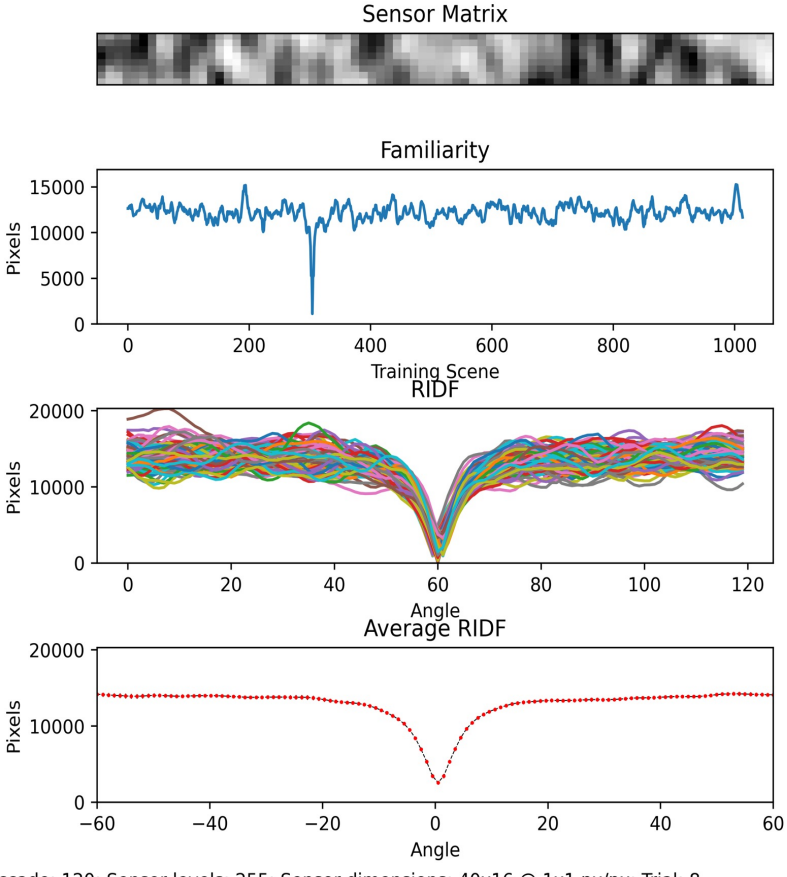





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

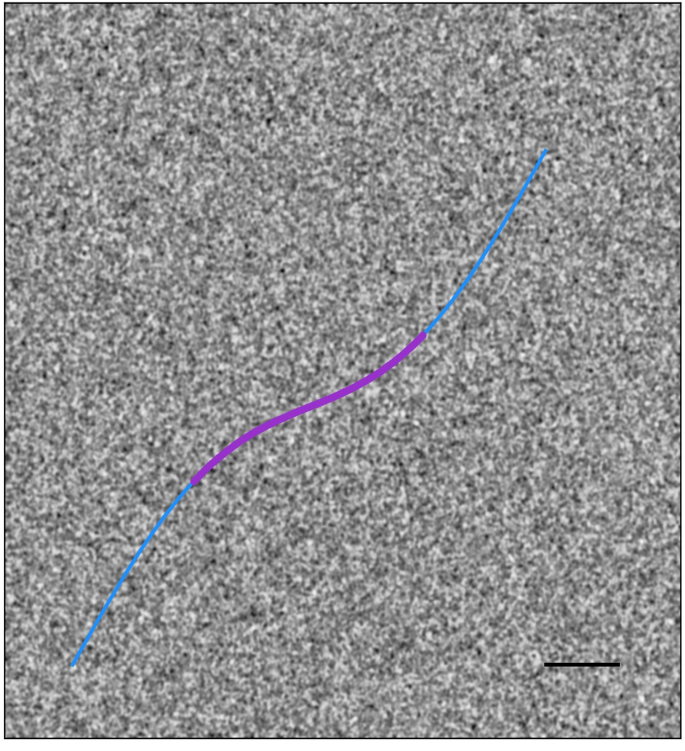
Navigation stats: RMSD error: 60.23; RMSD/dist: 0.151; TD: 8898; p90: 16; p50: 6; complete: 0

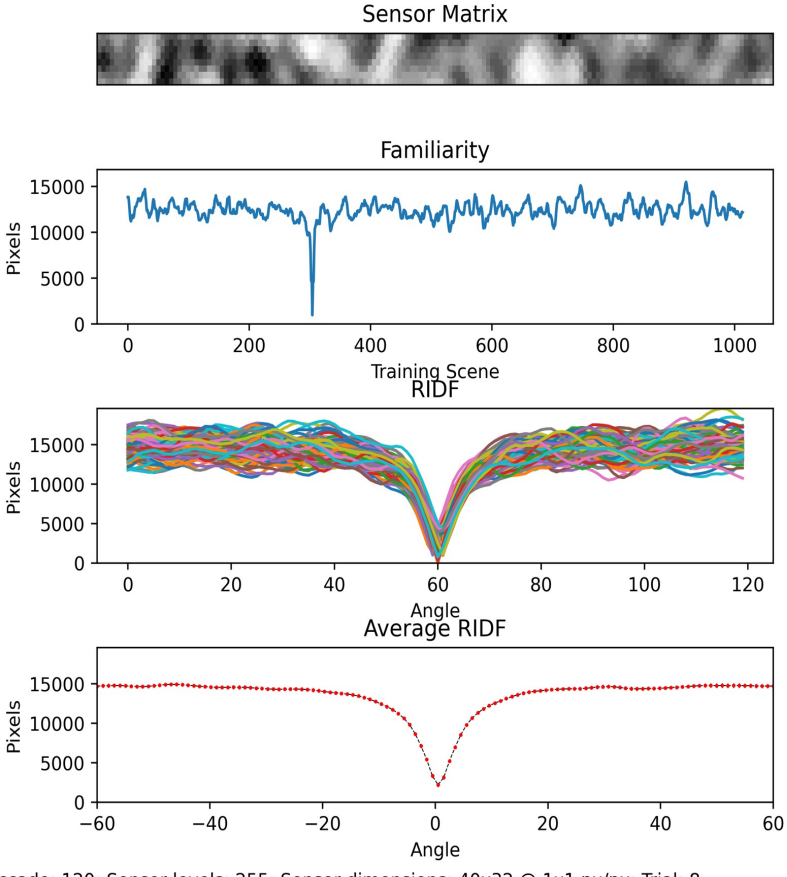





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

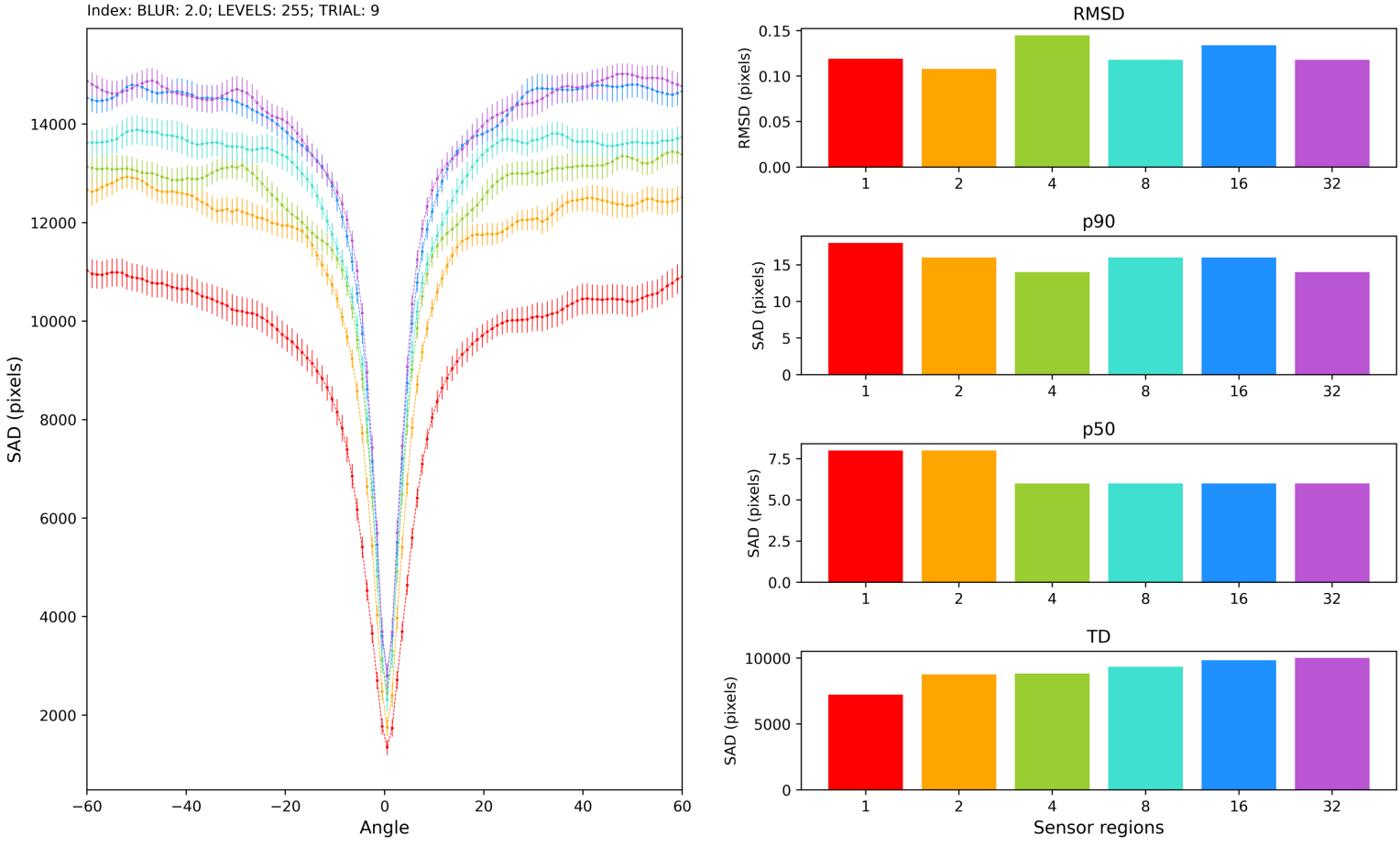
Navigation stats: RMSD error: 47.05; RMSD/dist: 0.118; TD: 9707; p90: 16; p50: 6; complete: 0

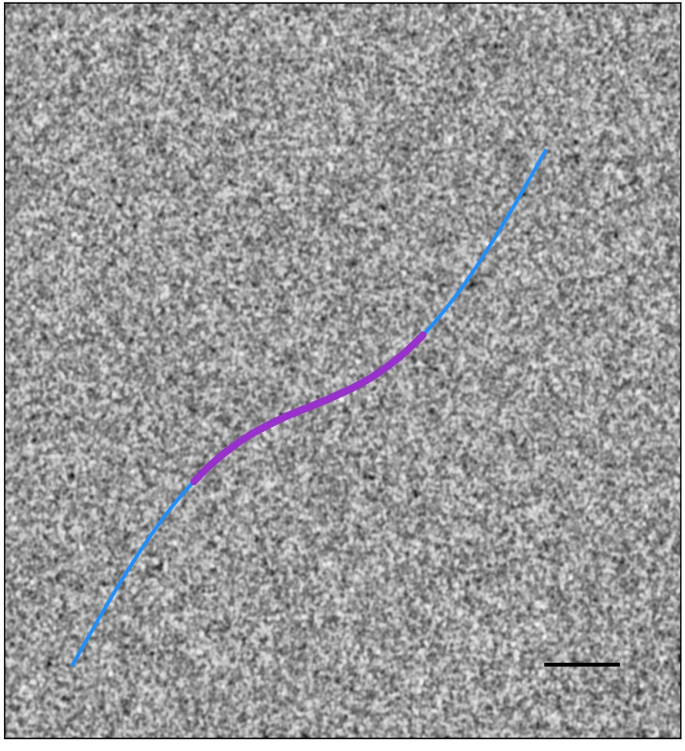


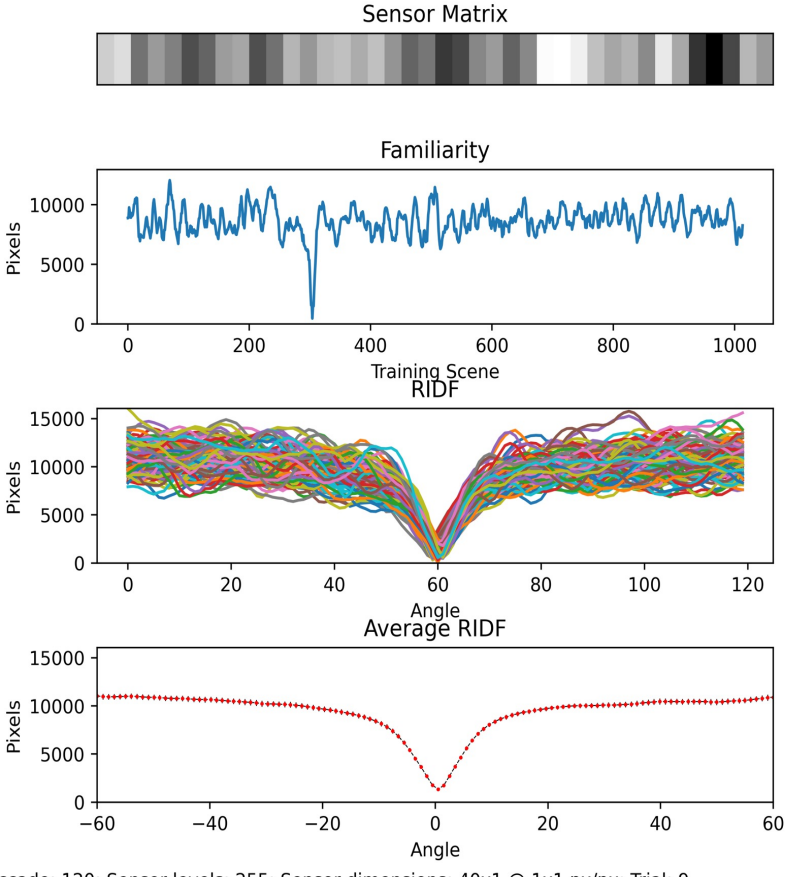



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 32.99; RMSD/dist: 0.082; TD: 10498; p90: 16; p50: 6; complete: 0

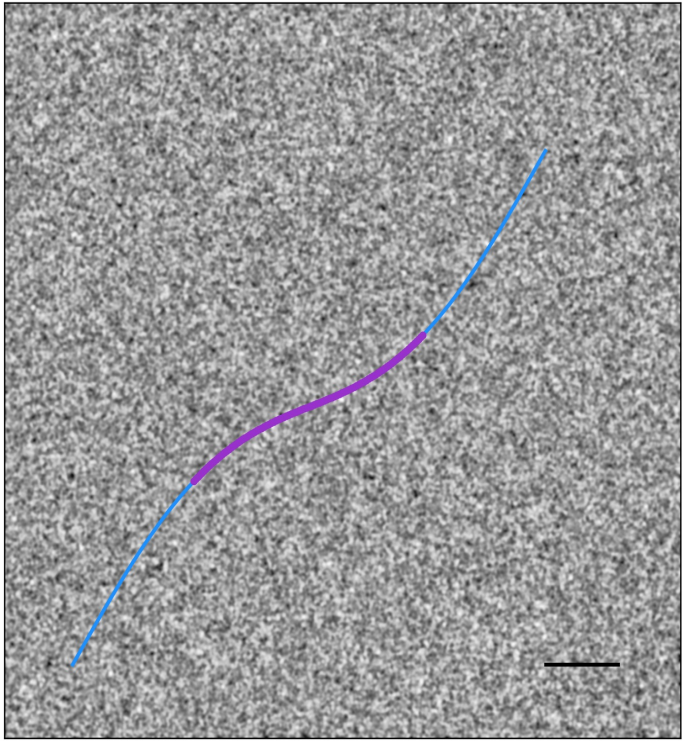

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

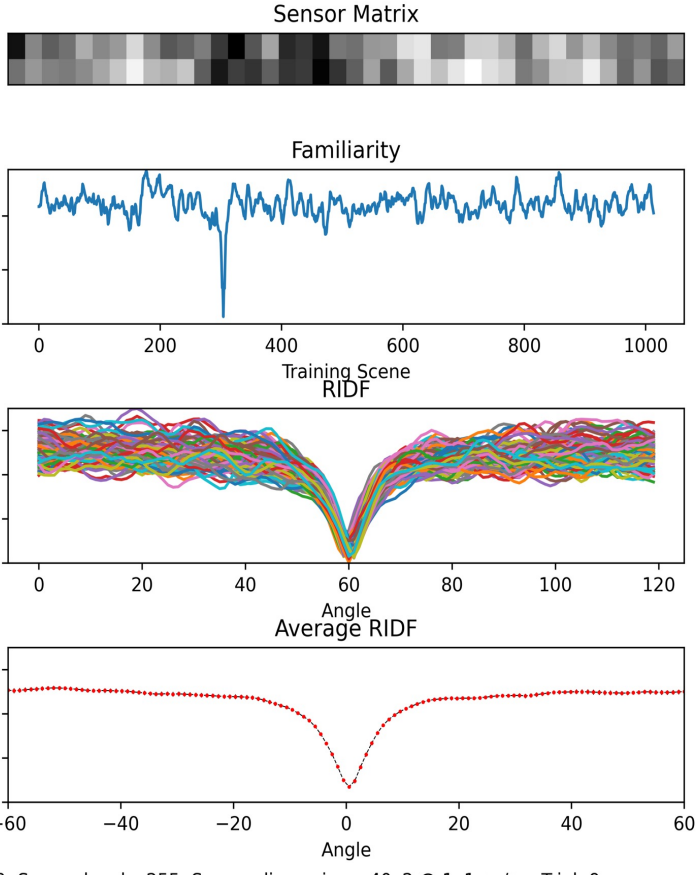





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

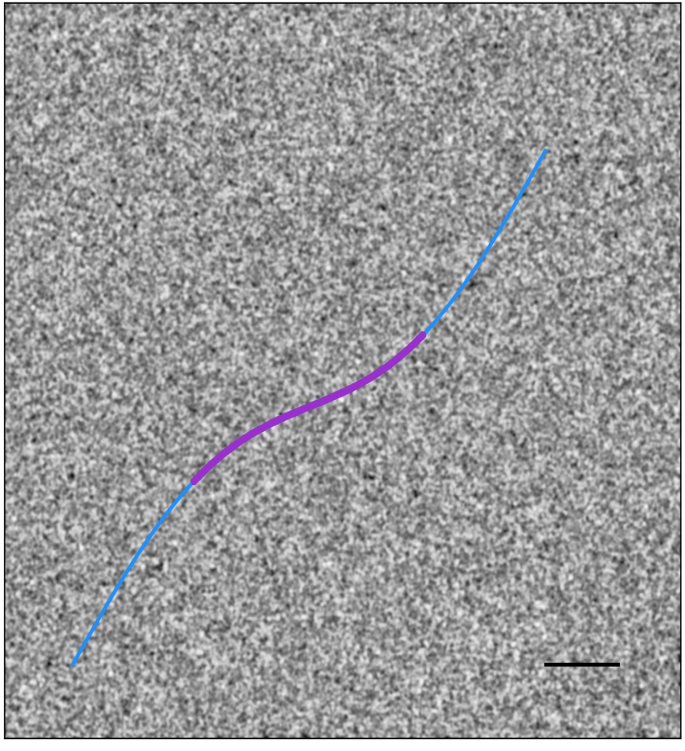
Navigation stats: RMSD error: 47.62; RMSD/dist: 0.119; TD: 7223; p90: 18; p50: 8; complete: 0

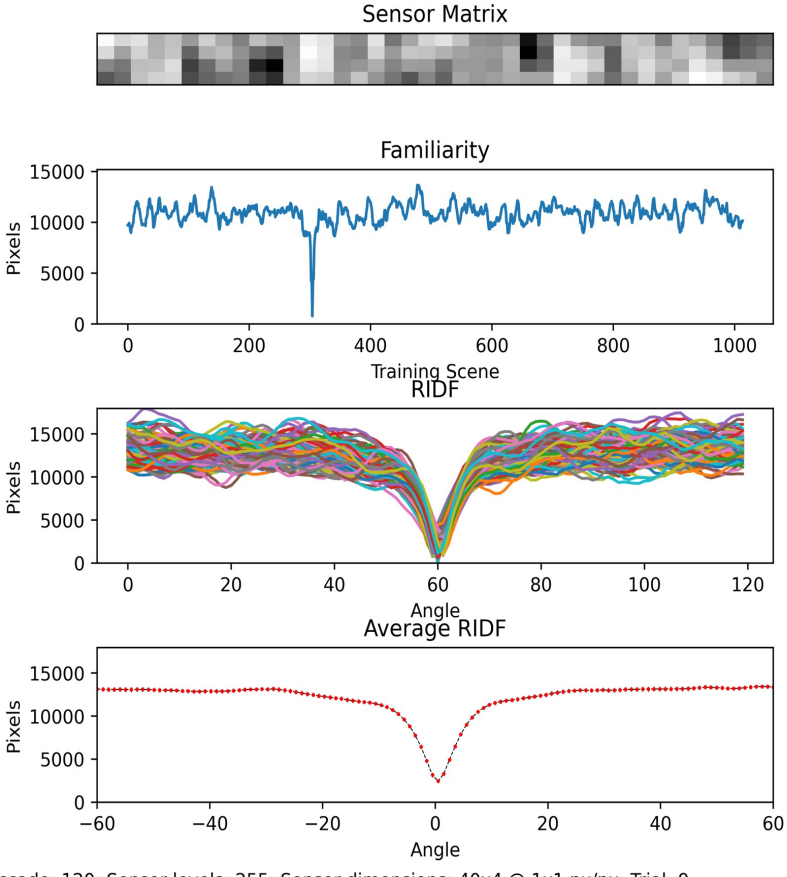





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

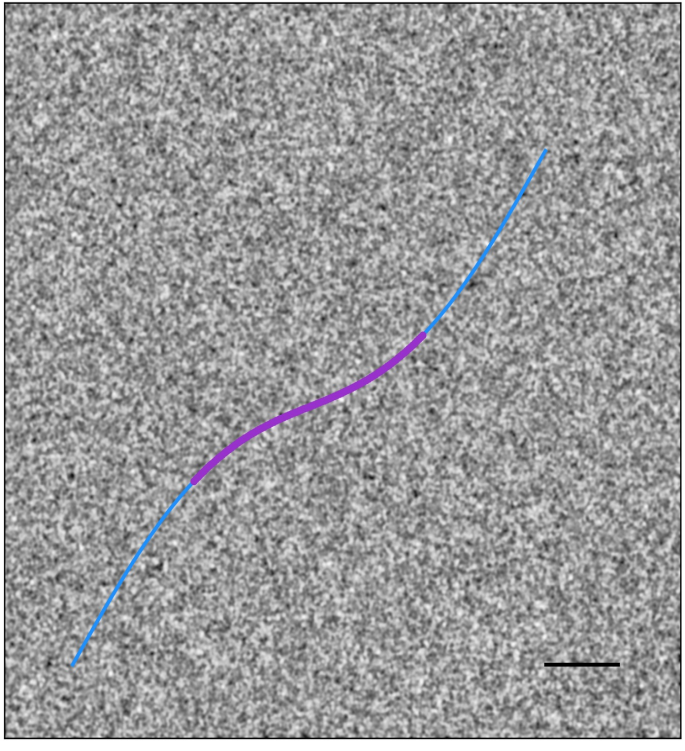
Navigation stats: RMSD error: 43.00; RMSD/dist: 0.108; TD: 8779; p90: 16; p50: 8; complete: 0

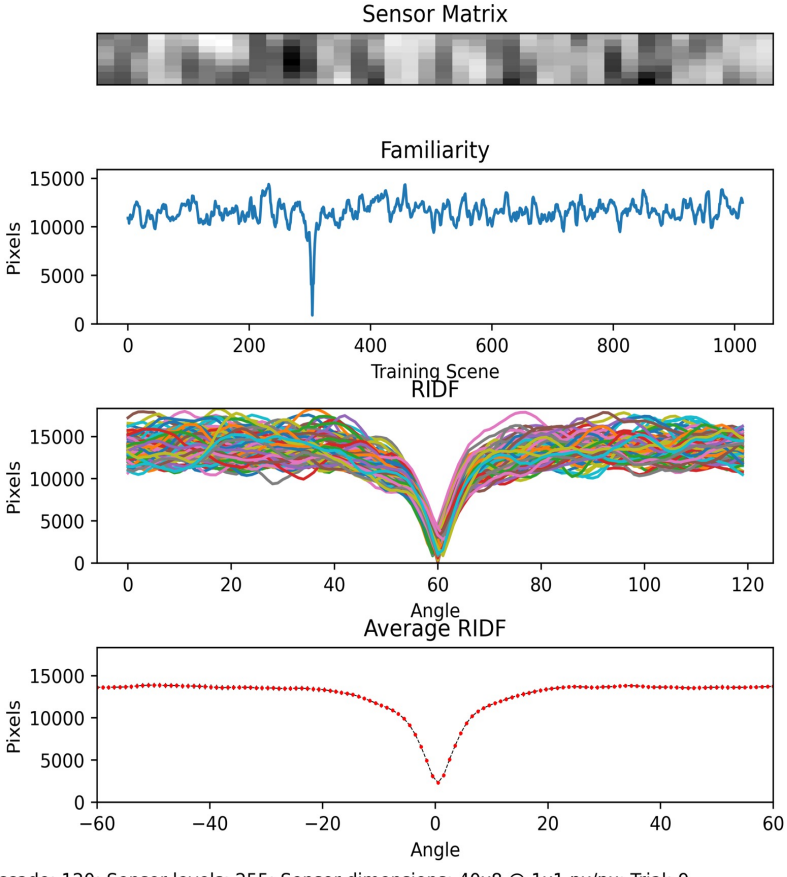





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

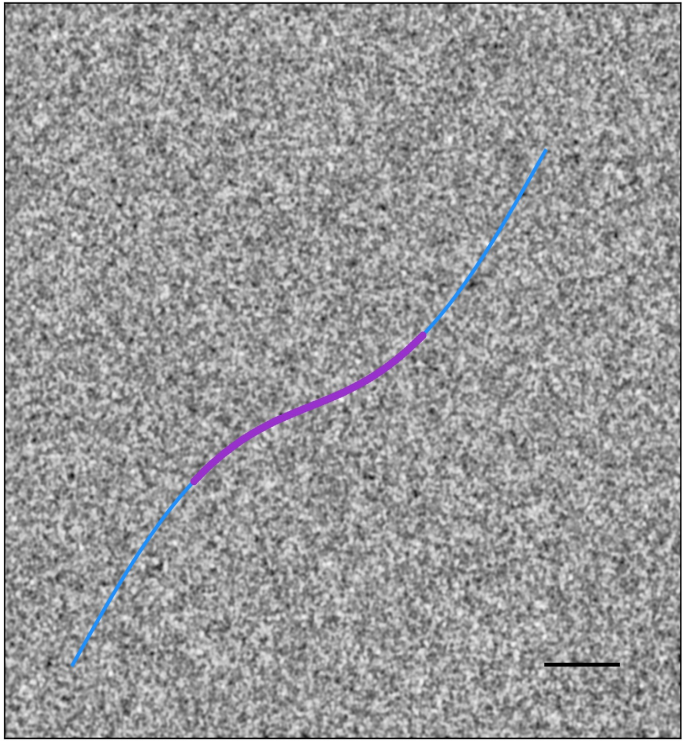
Navigation stats: RMSD error: 58.00; RMSD/dist: 0.145; TD: 8838; p90: 14; p50: 6; complete: 0

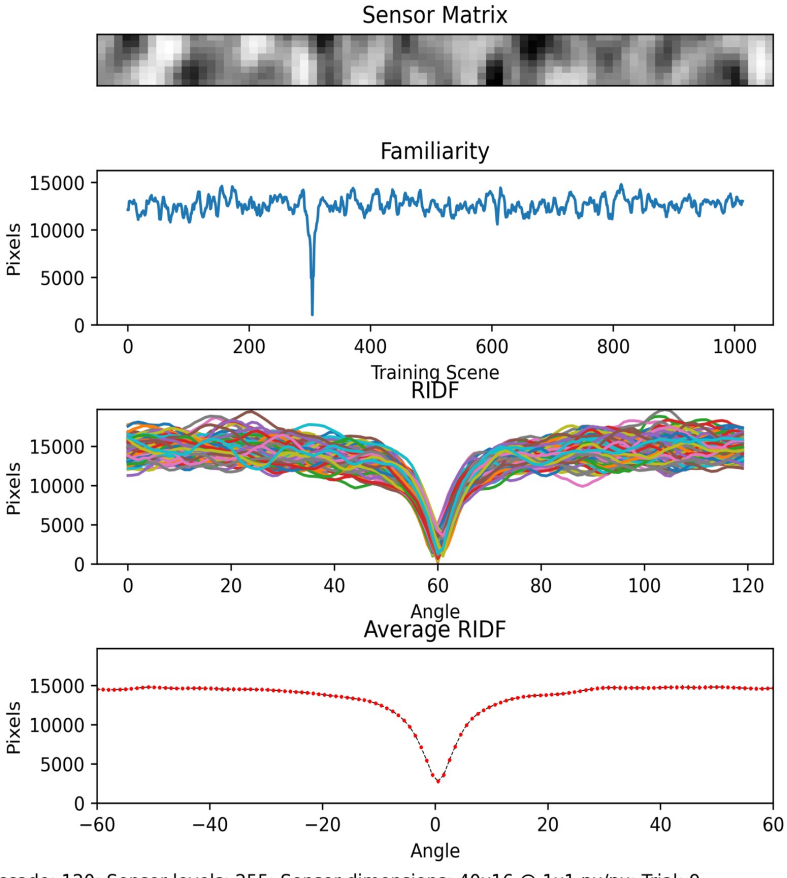





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

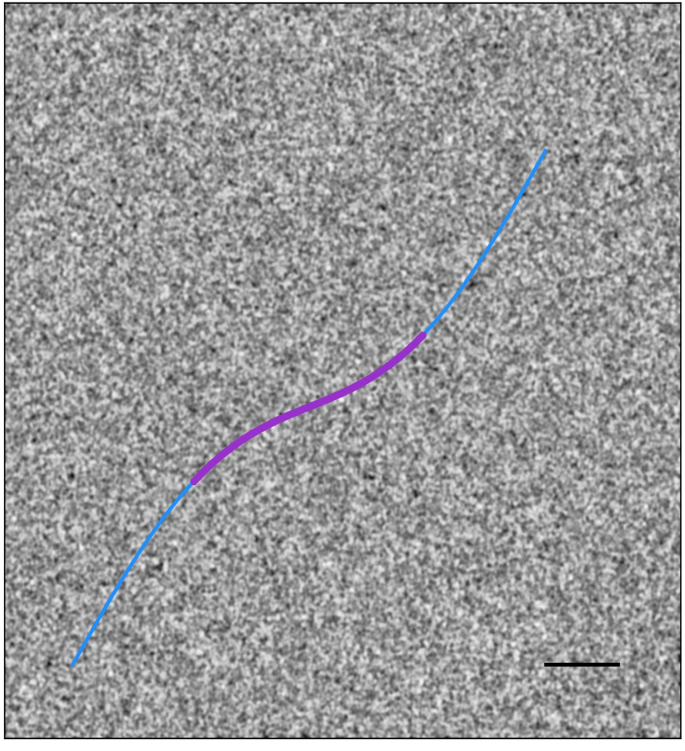
Navigation stats: RMSD error: 47.36; RMSD/dist: 0.118; TD: 9352; p90: 16; p50: 6; complete: 0

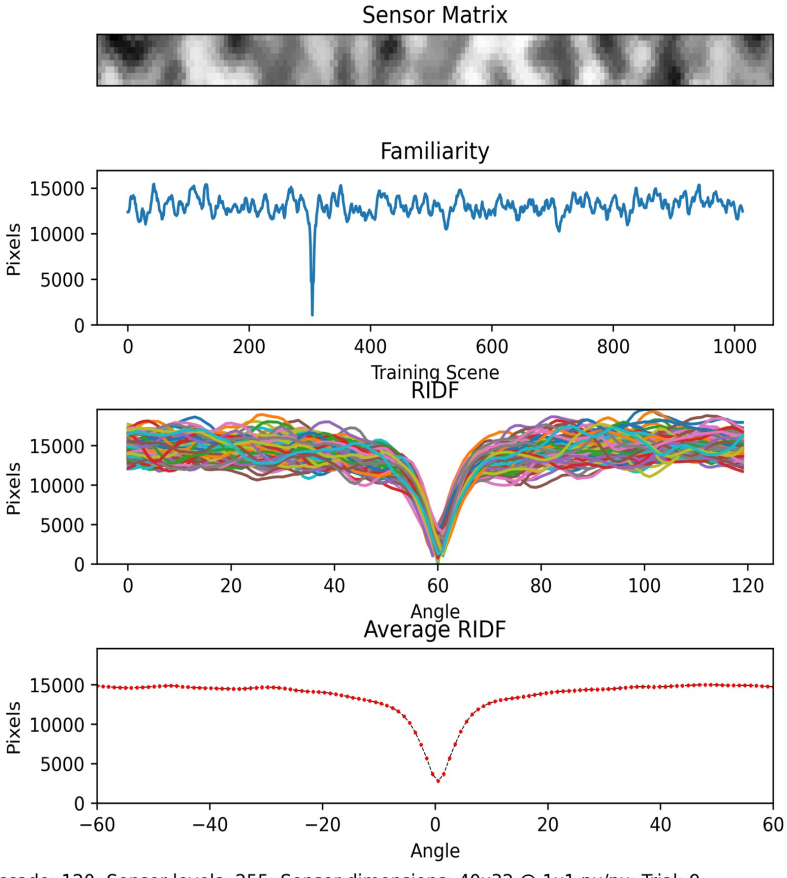





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

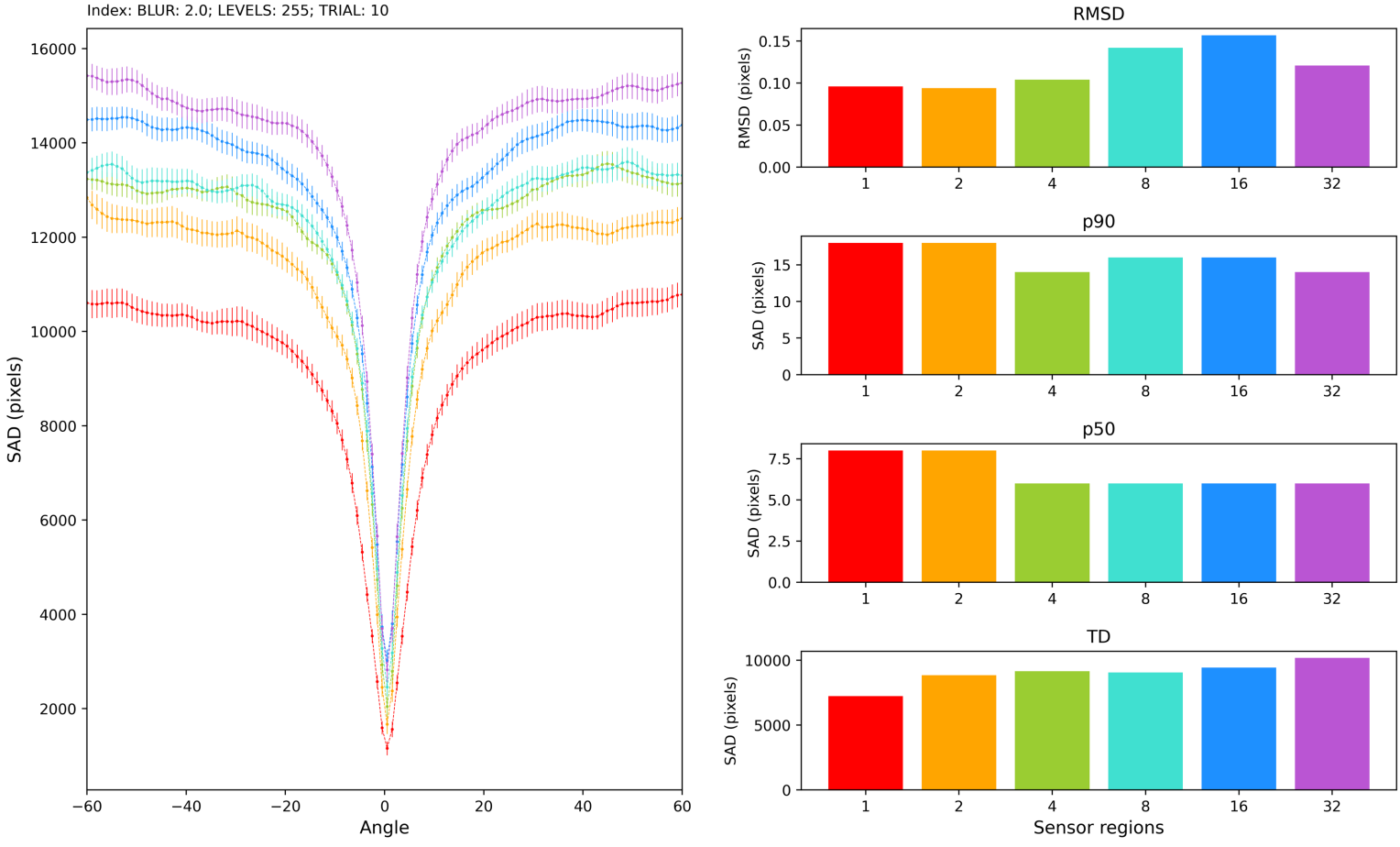
Navigation stats: RMSD error: 53.47; RMSD/dist: 0.134; TD: 9851; p90: 16; p50: 6; complete: 0

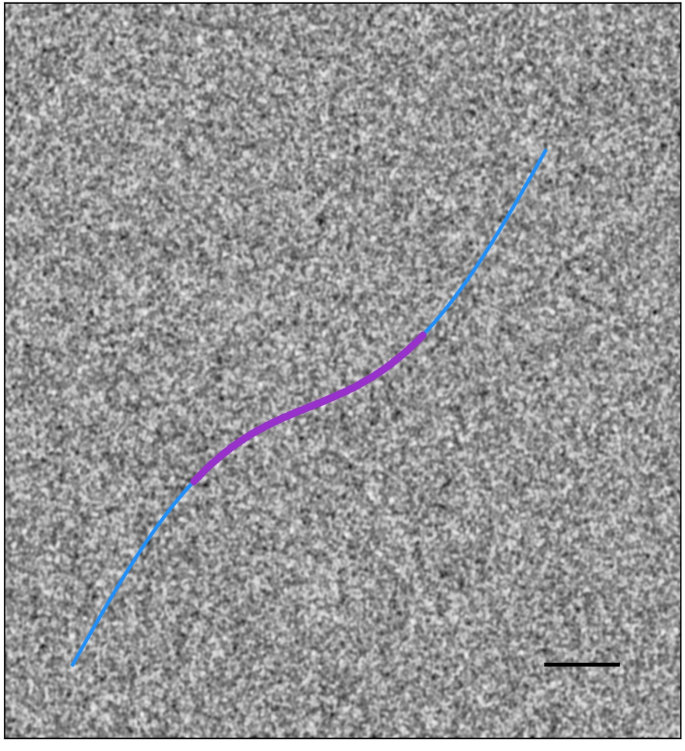


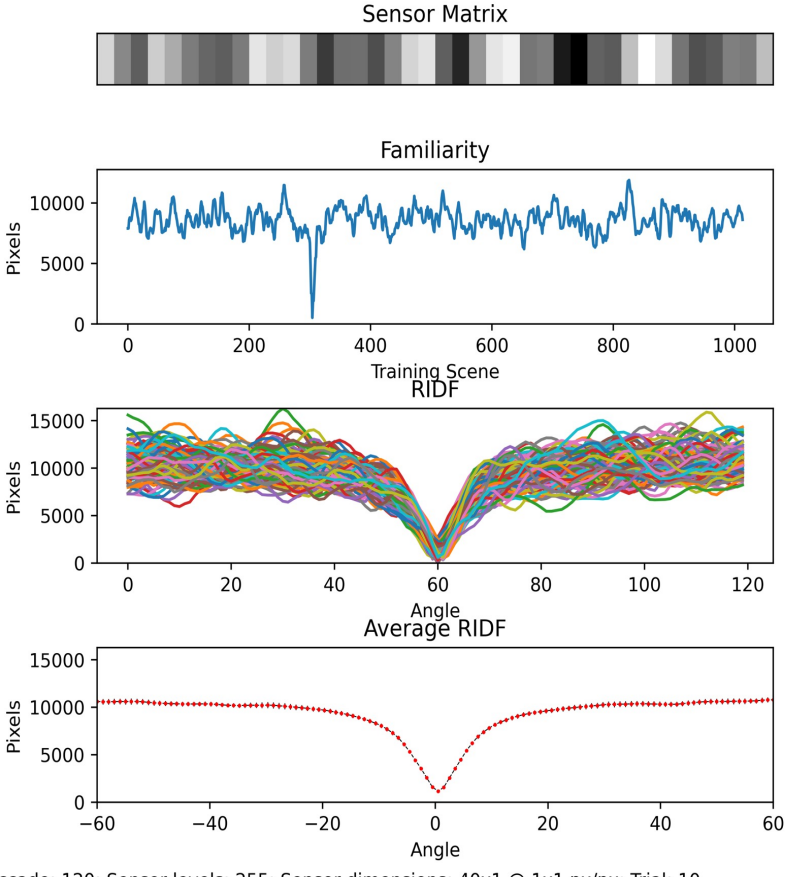



Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 47.35; RMSD/dist: 0.118; TD: 10015; p90: 14; p50: 6; complete: 0

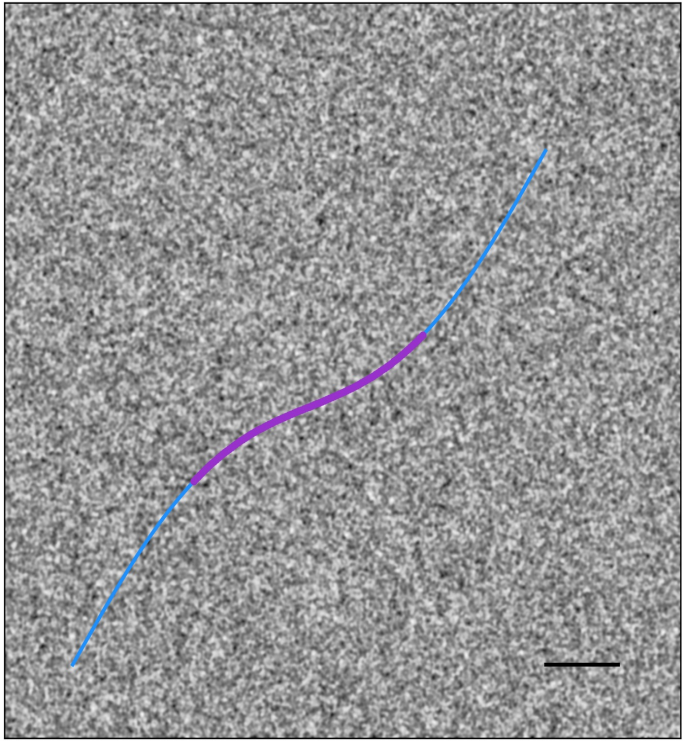

Index: BLUR: 2.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

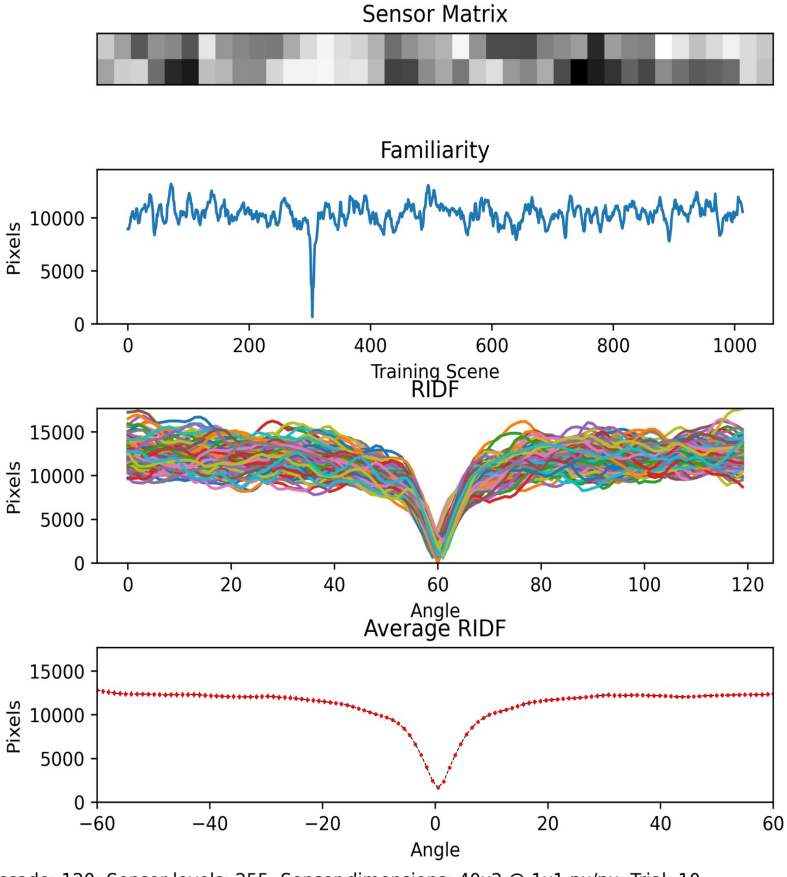





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

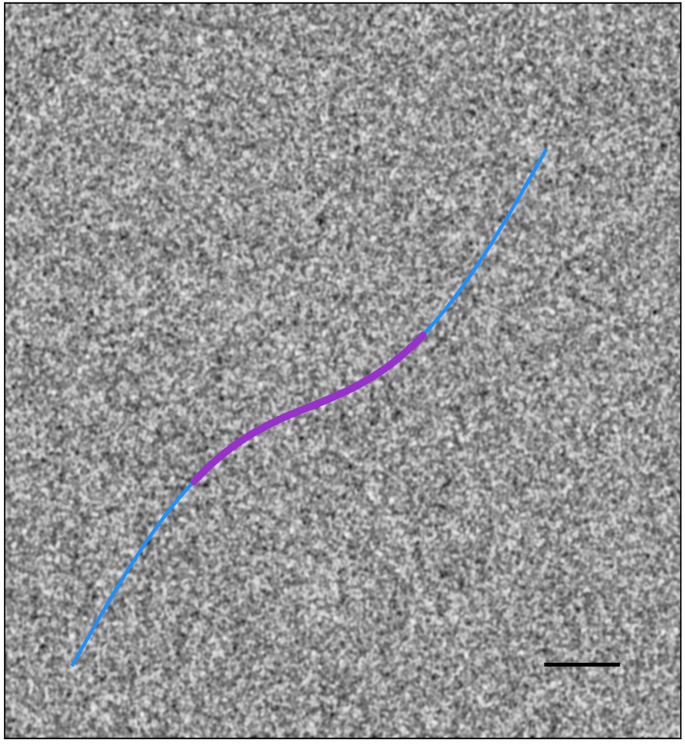
Navigation stats: RMSD error: 38.56; RMSD/dist: 0.096; TD: 7233; p90: 18; p50: 8; complete: 0

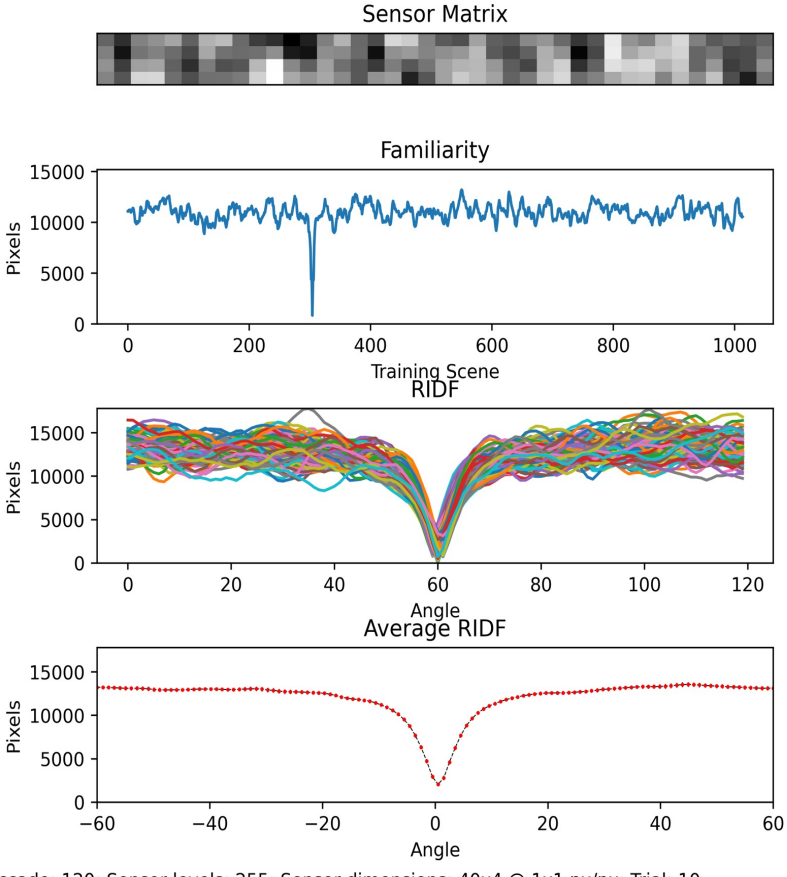





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

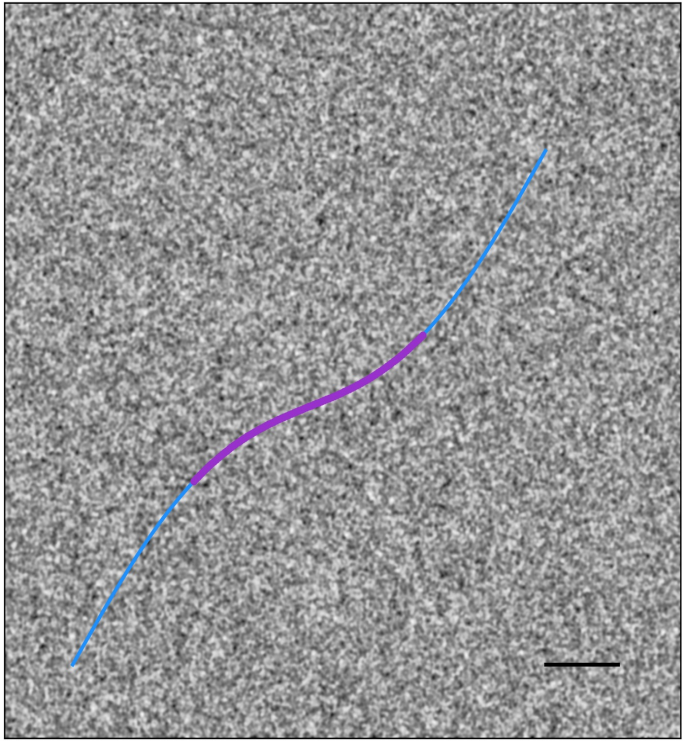
Navigation stats: RMSD error: 37.59; RMSD/dist: 0.094; TD: 8833; p90: 18; p50: 8; complete: 0

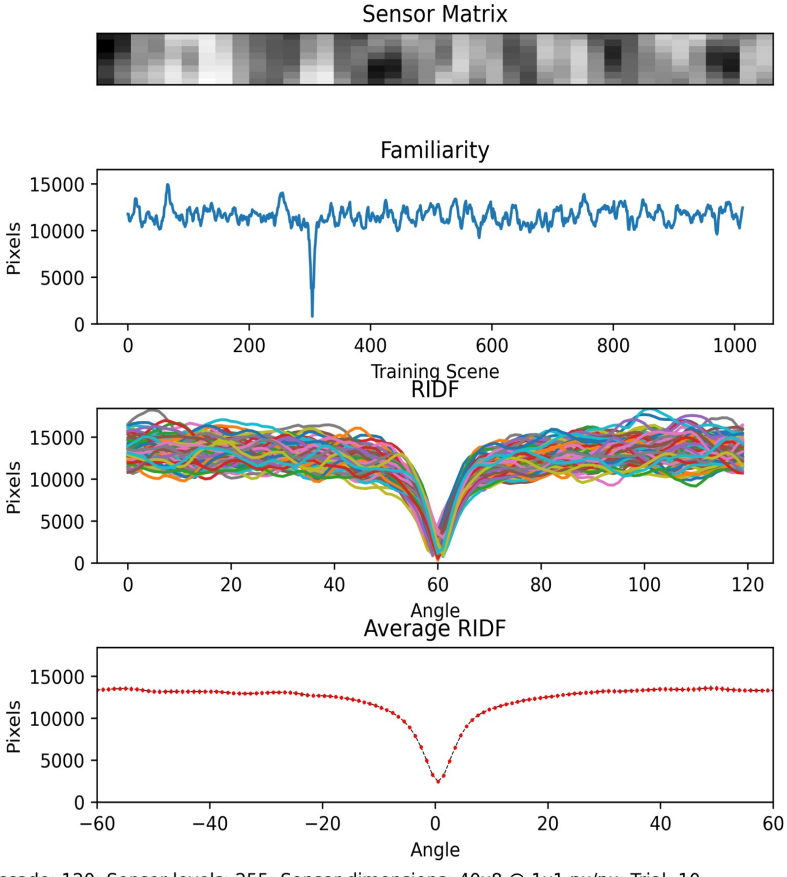





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

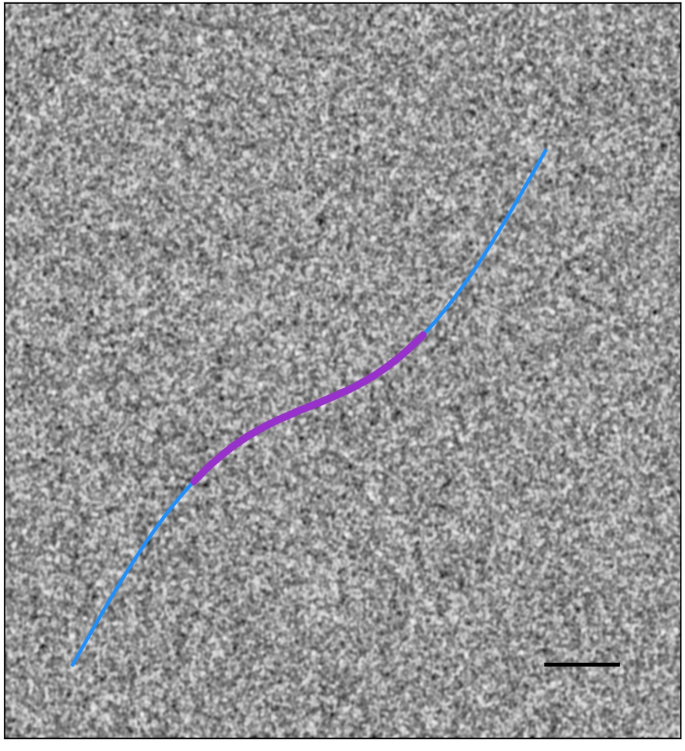
Navigation stats: RMSD error: 41.45; RMSD/dist: 0.104; TD: 9154; p90: 14; p50: 6; complete: 0

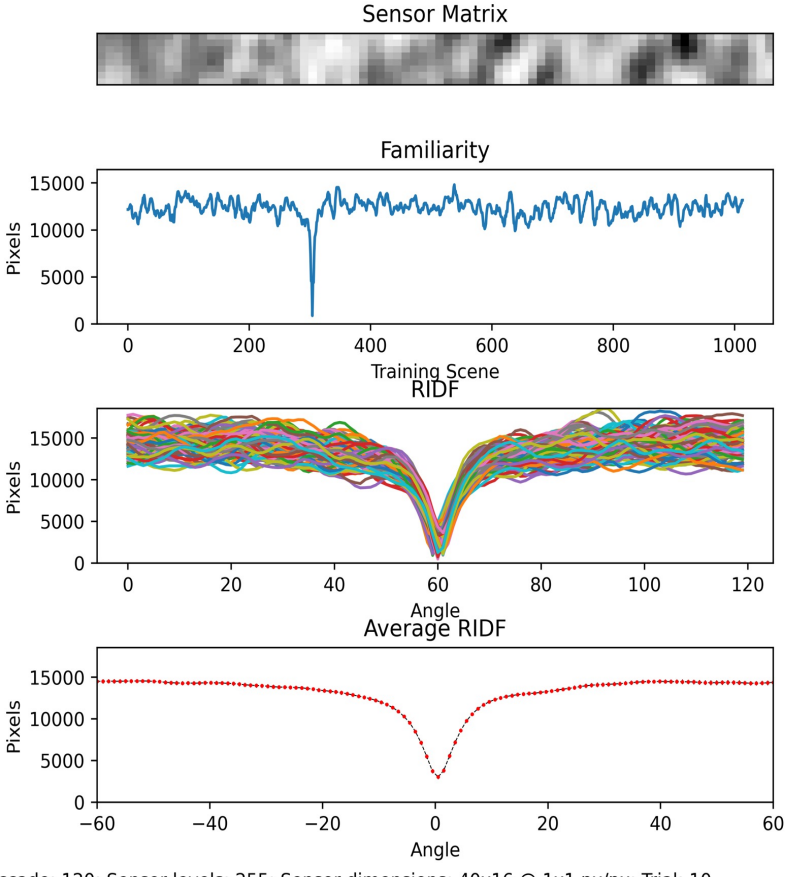





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

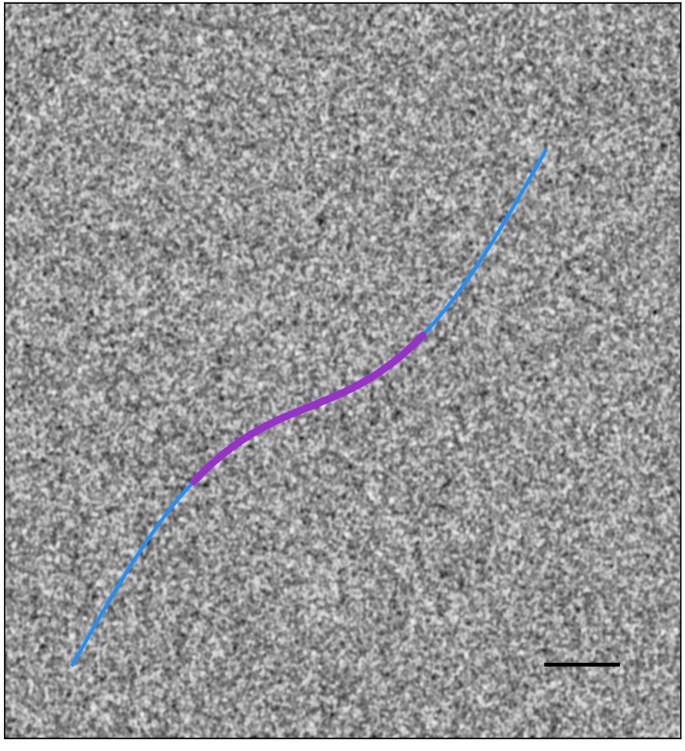
Navigation stats: RMSD error: 56.75; RMSD/dist: 0.142; TD: 9054; p90: 16; p50: 6; complete: 0

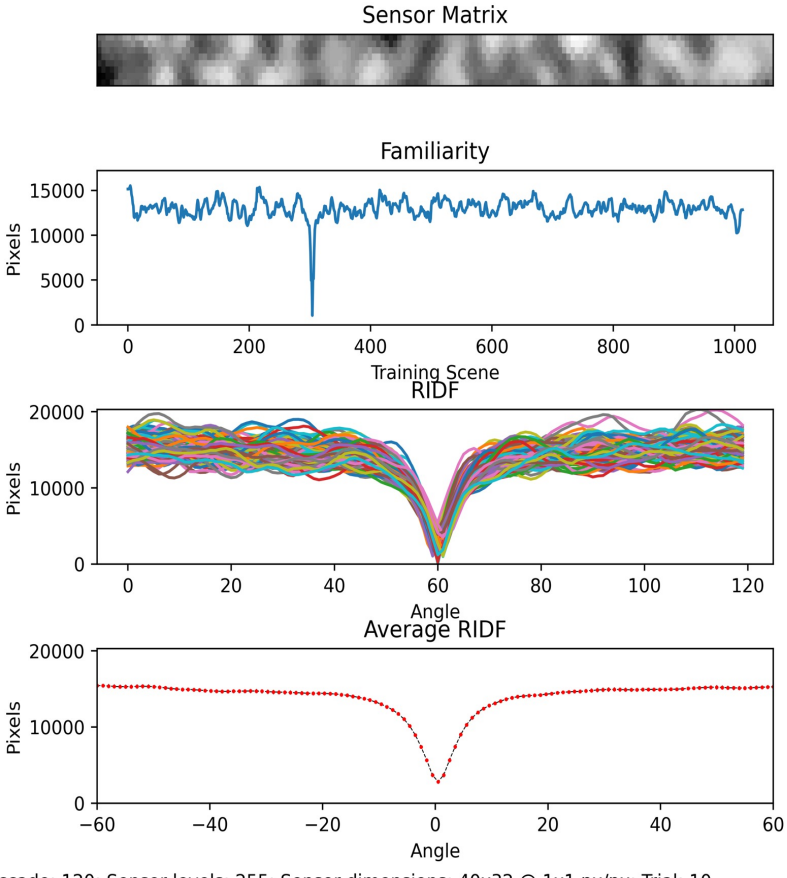





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 62.88; RMSD/dist: 0.157; TD: 9431; p90: 16; p50: 6; complete: 0






Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 48.28; RMSD/dist: 0.121; TD: 10165; p90: 14; p50: 6; complete: 0