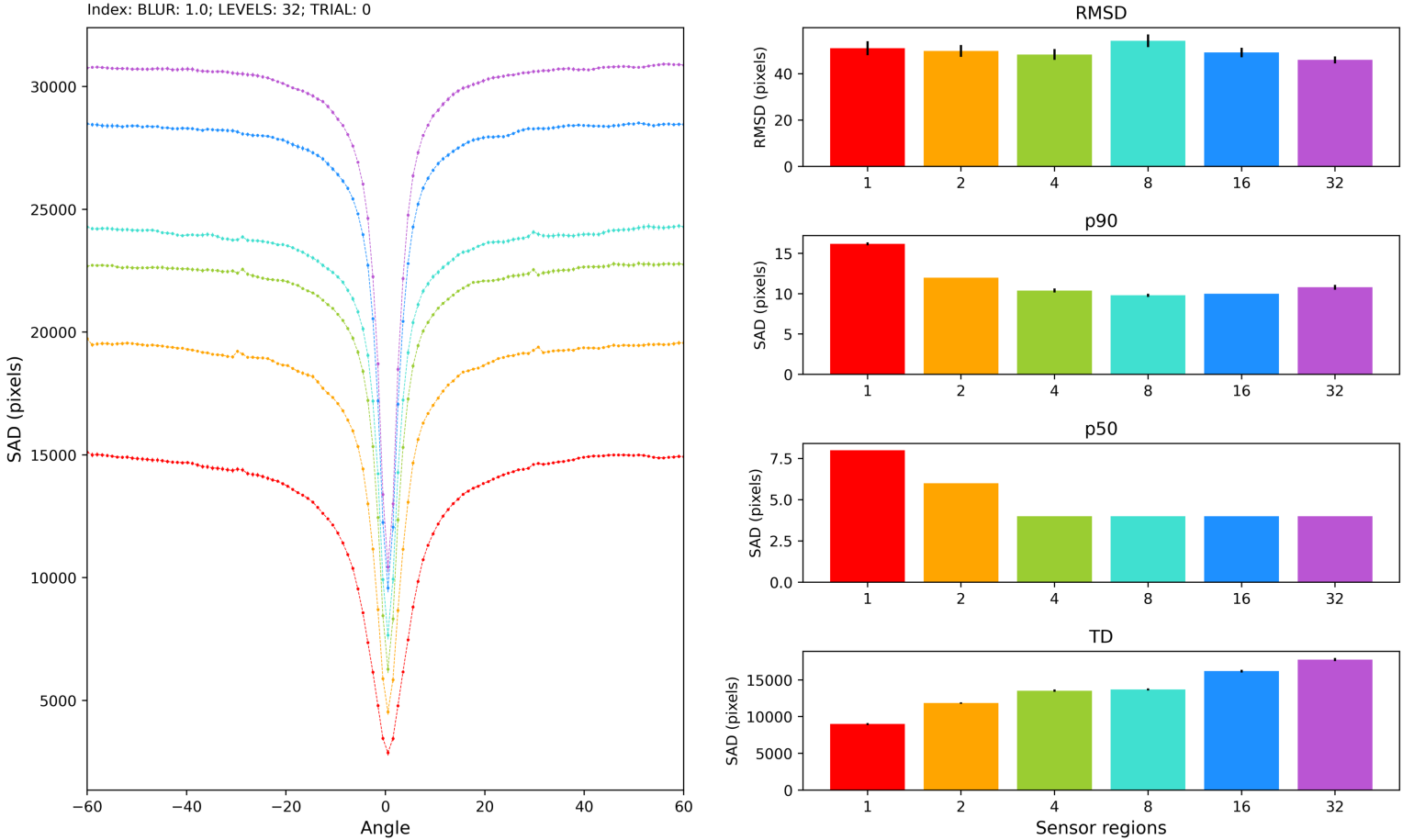
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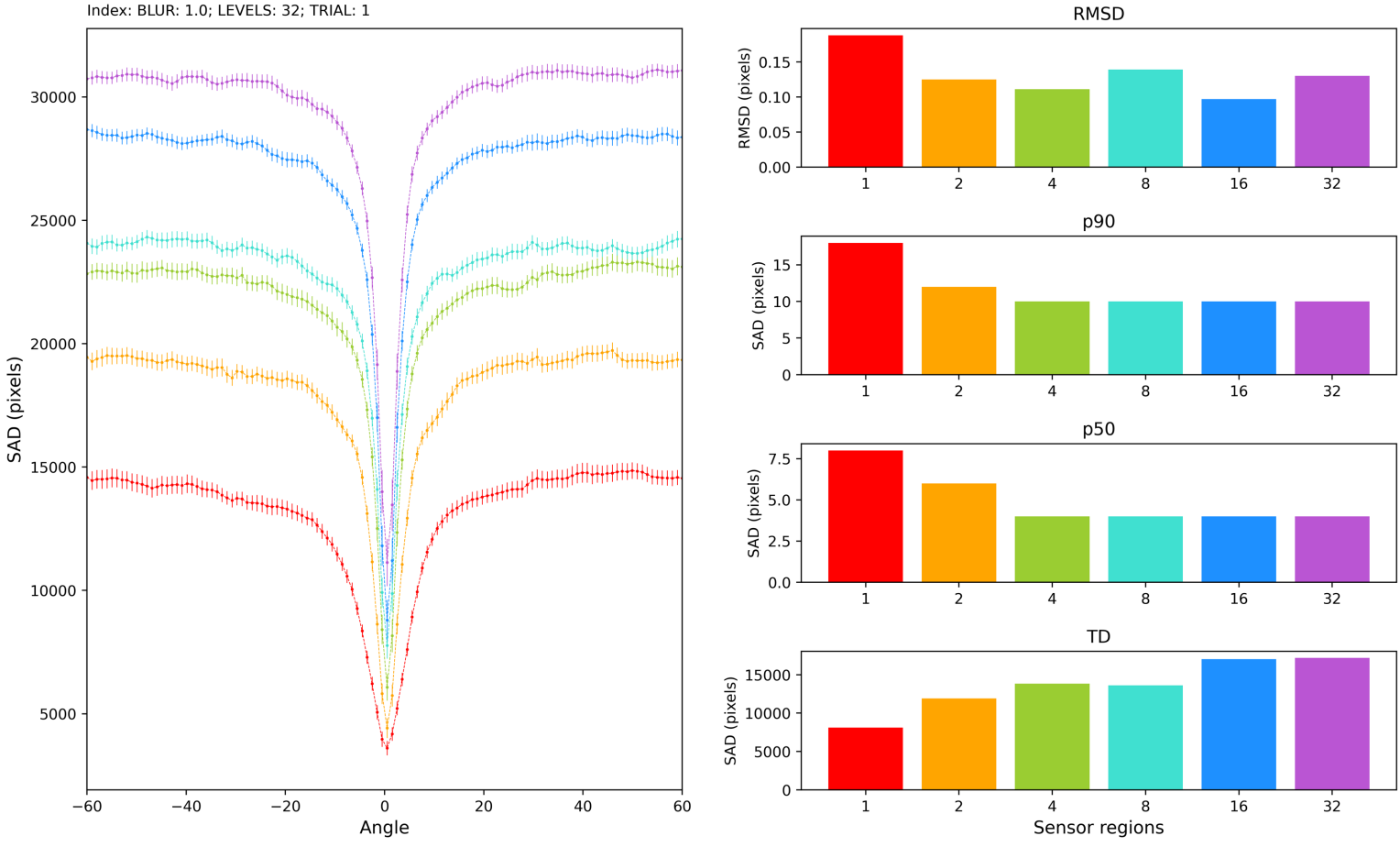
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0
20
40
1
2
4
8
16
32
p90
SAD (pixels)
0
5
10
15
p50
SAD (pixels)
0.0
2.5
5.0
7.5
TD
SAD (pixels)
0
5000
10000
15000
Sensor regions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SAD (pixels)
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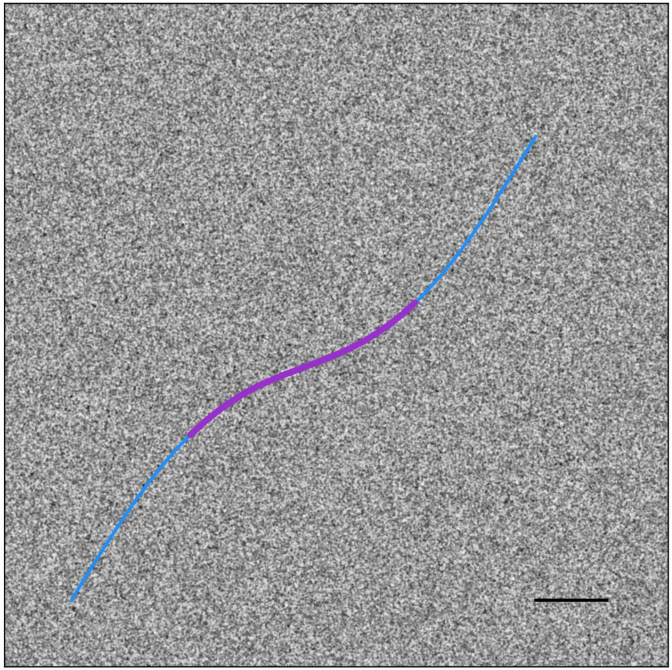
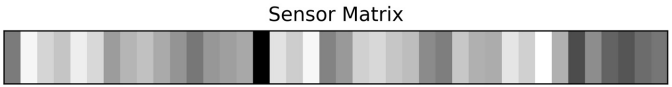
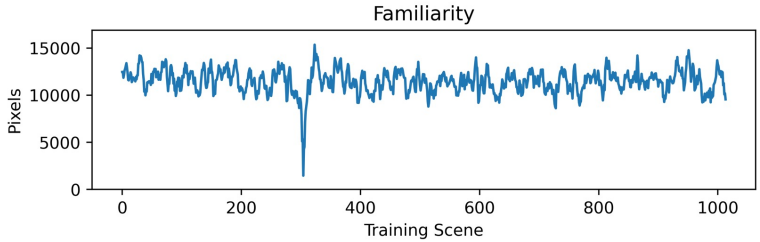
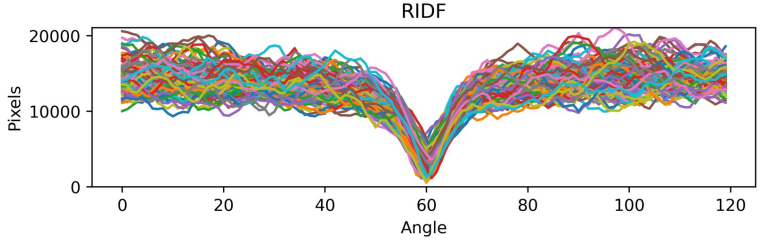
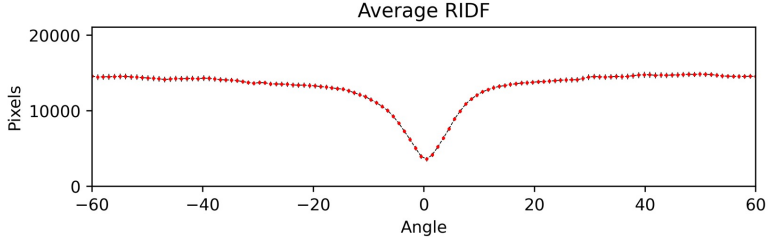
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions





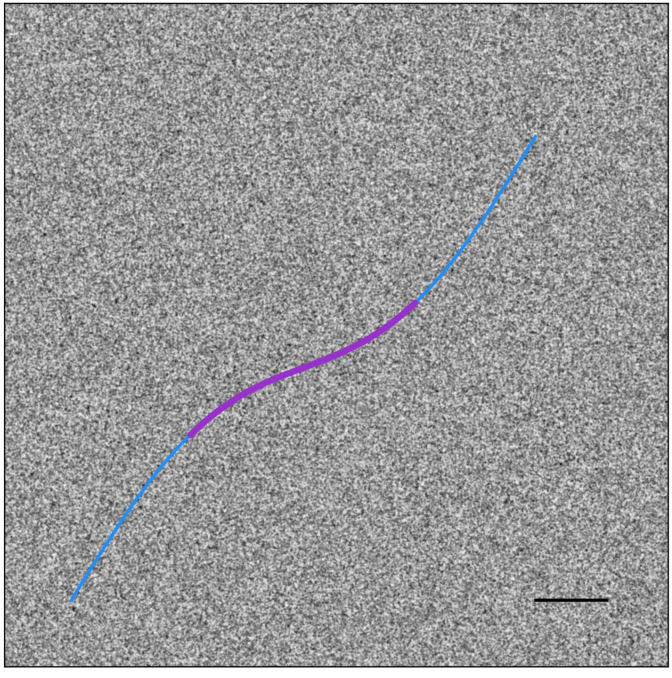


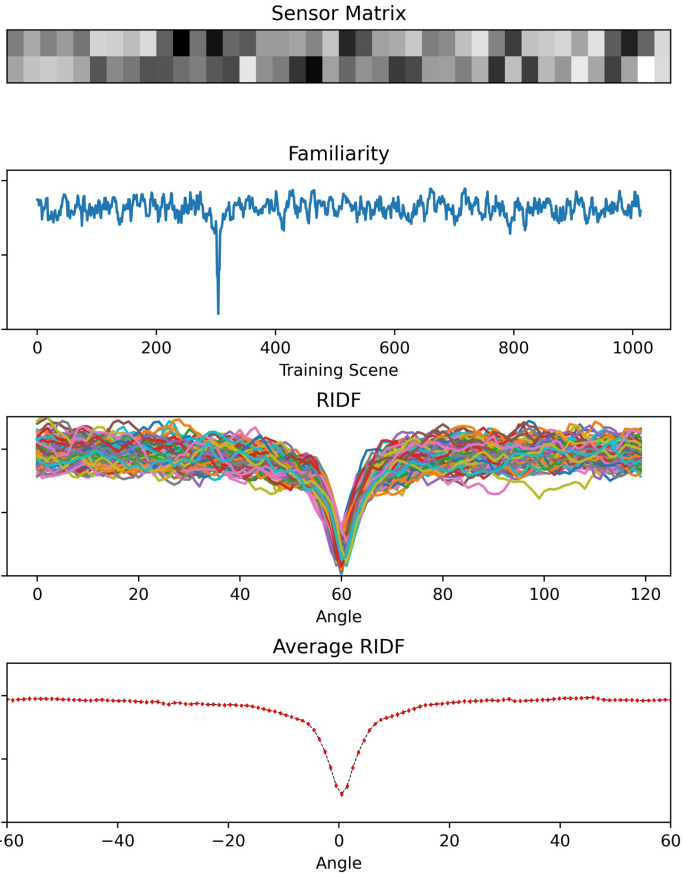




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

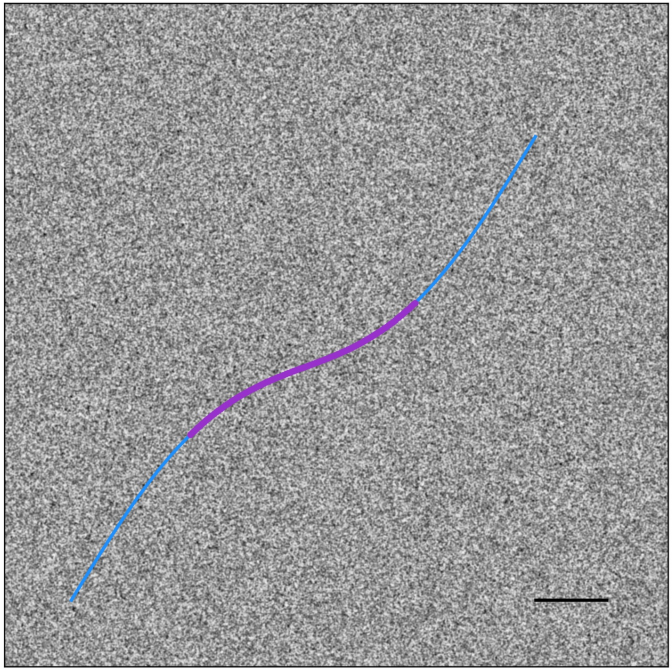
Navigation stats: RMSD error: 75.20; RMSD/dist: 0.188; TD: 8105; p90: 18; p50: 8; complete: 0

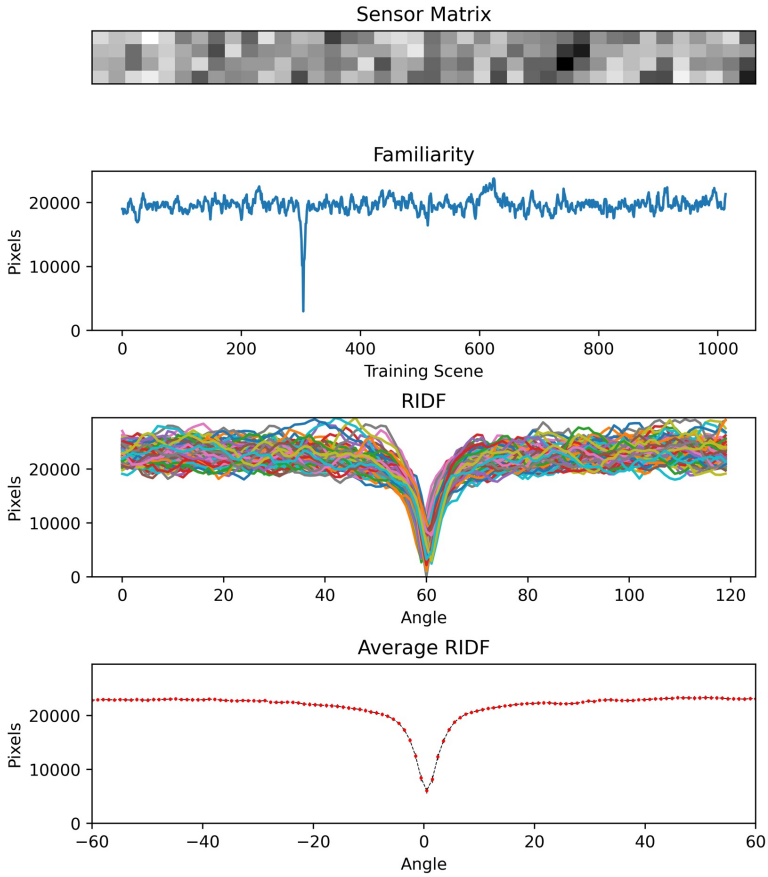




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

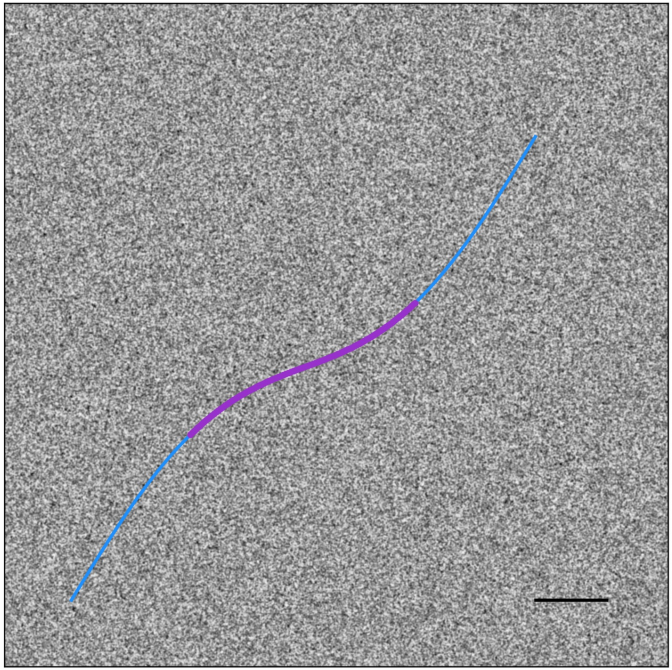
Navigation stats: RMSD error: 50.00; RMSD/dist: 0.125; TD: 11900; p90: 12; p50: 6; complete: 0

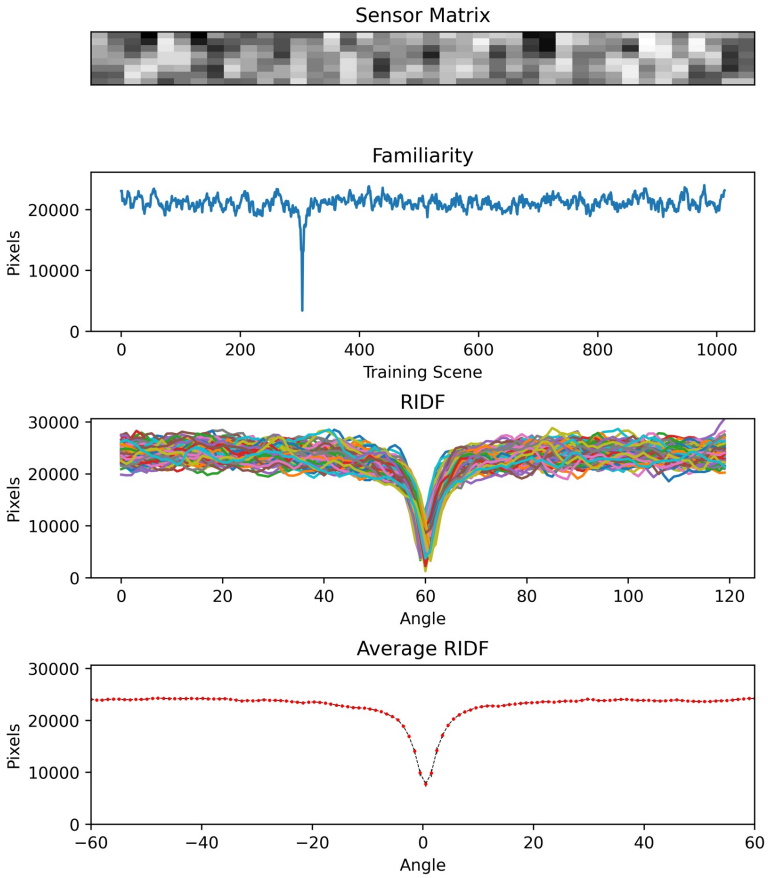




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

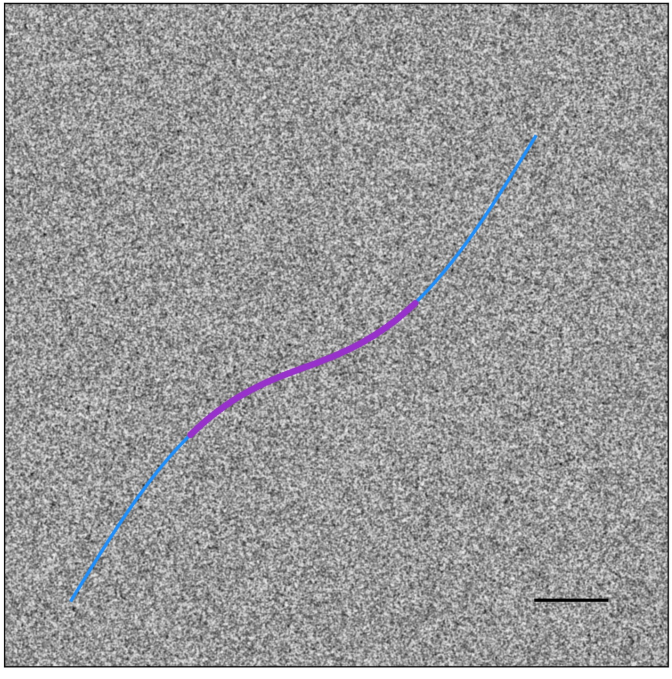
Navigation stats: RMSD error: 44.51; RMSD/dist: 0.111; TD: 13827; p90: 10; p50: 4; complete: 0

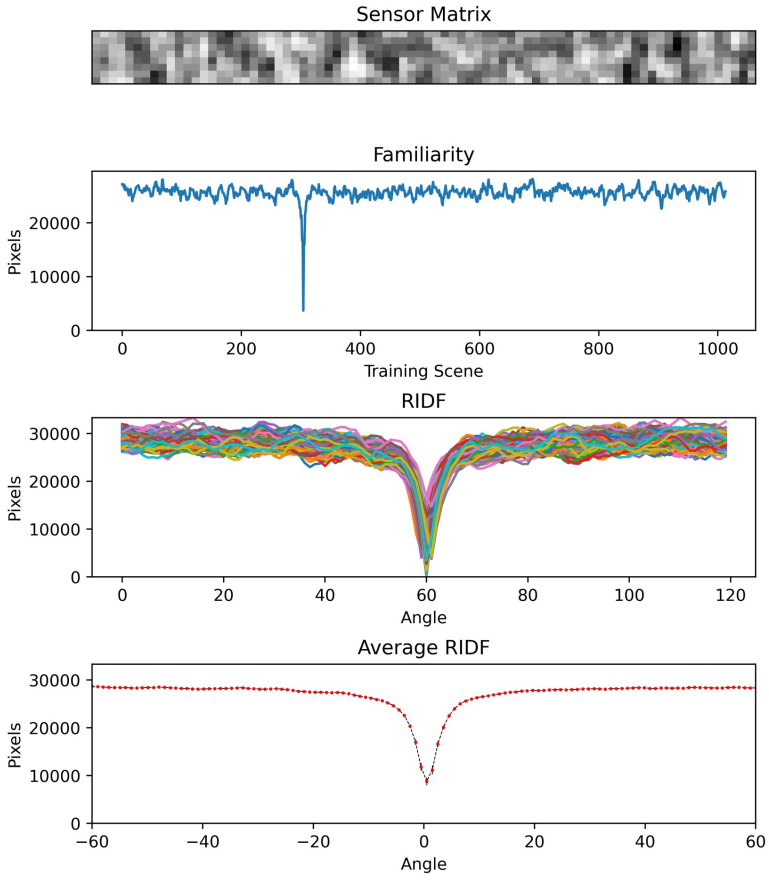




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

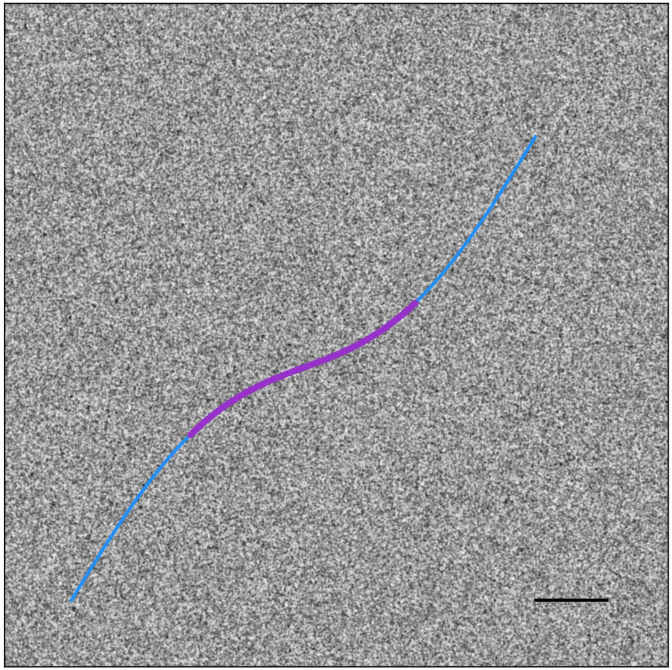
Navigation stats: RMSD error: 55.40; RMSD/dist: 0.139; TD: 13608; p90: 10; p50: 4; complete: 0

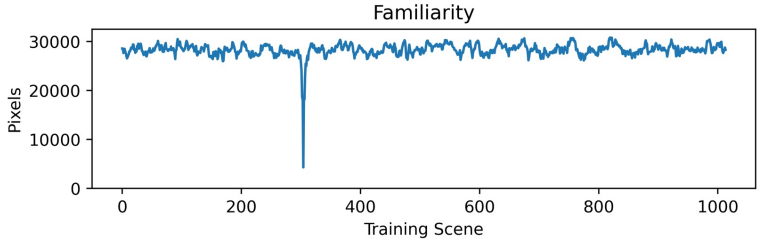


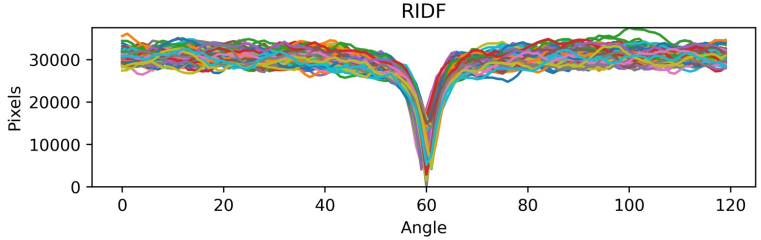


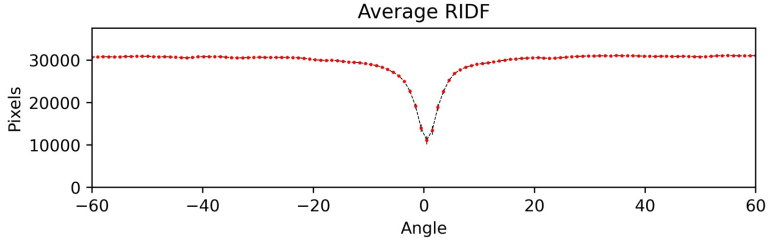
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 38.74; RMSD/dist: 0.097; TD: 17020; p90: 10; p50: 4; complete: 0



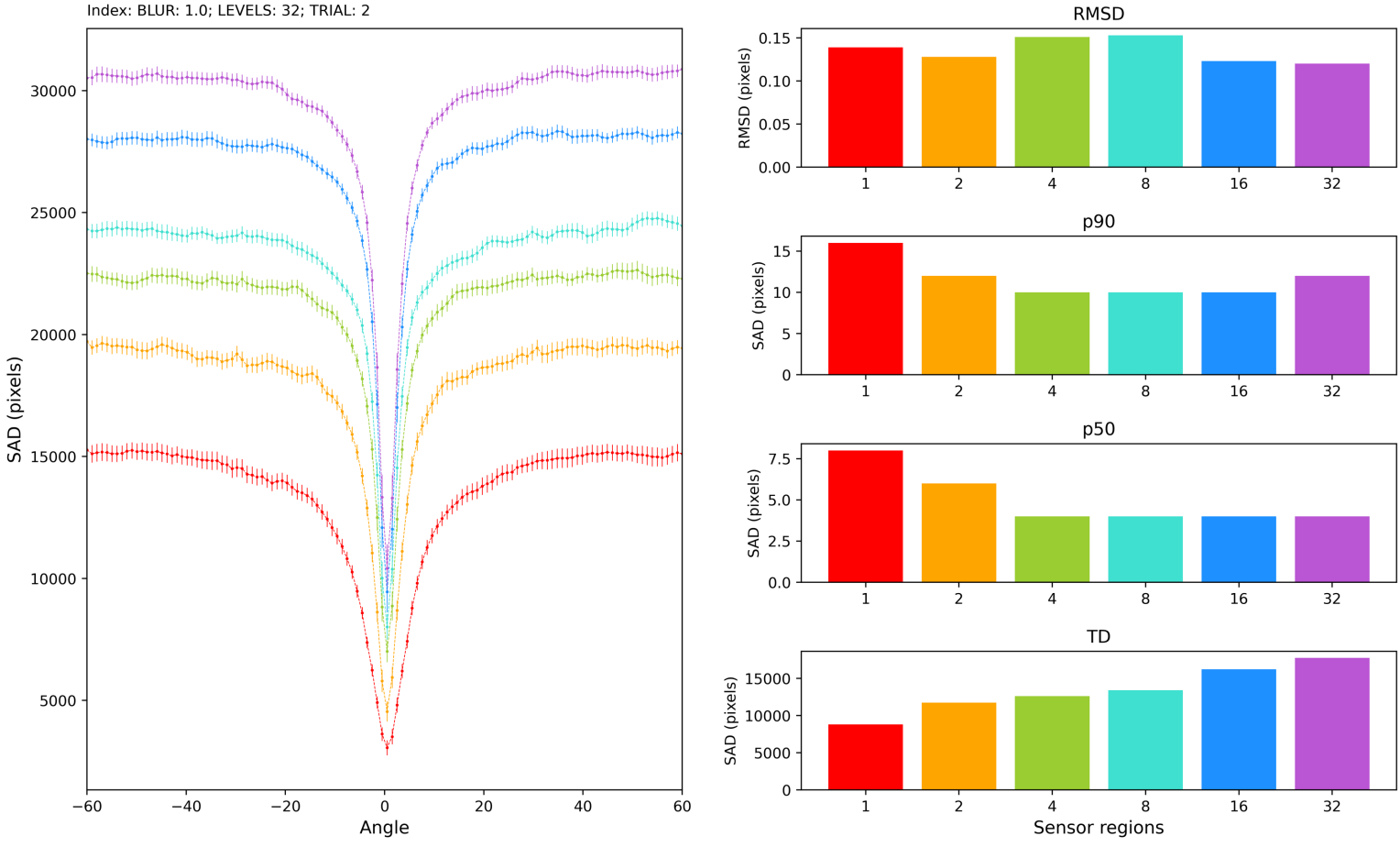






Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 52.15; RMSD/dist: 0.130; TD: 17185; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 32; TRIAL: 2
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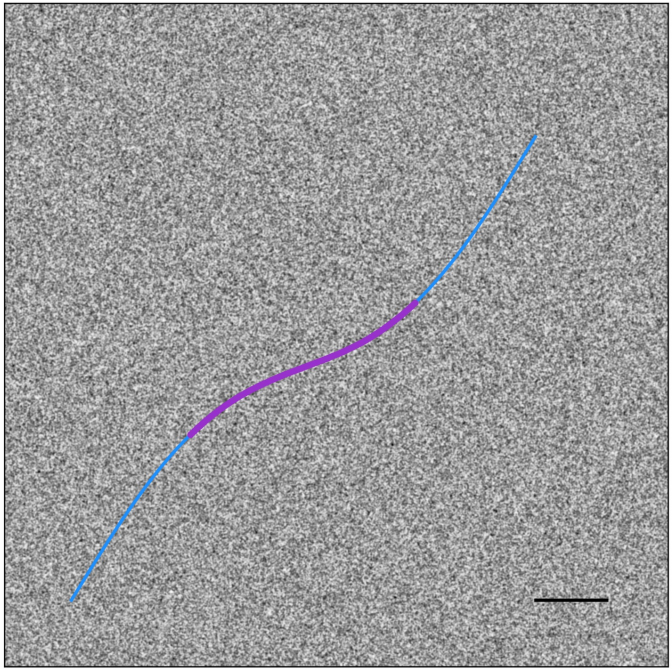
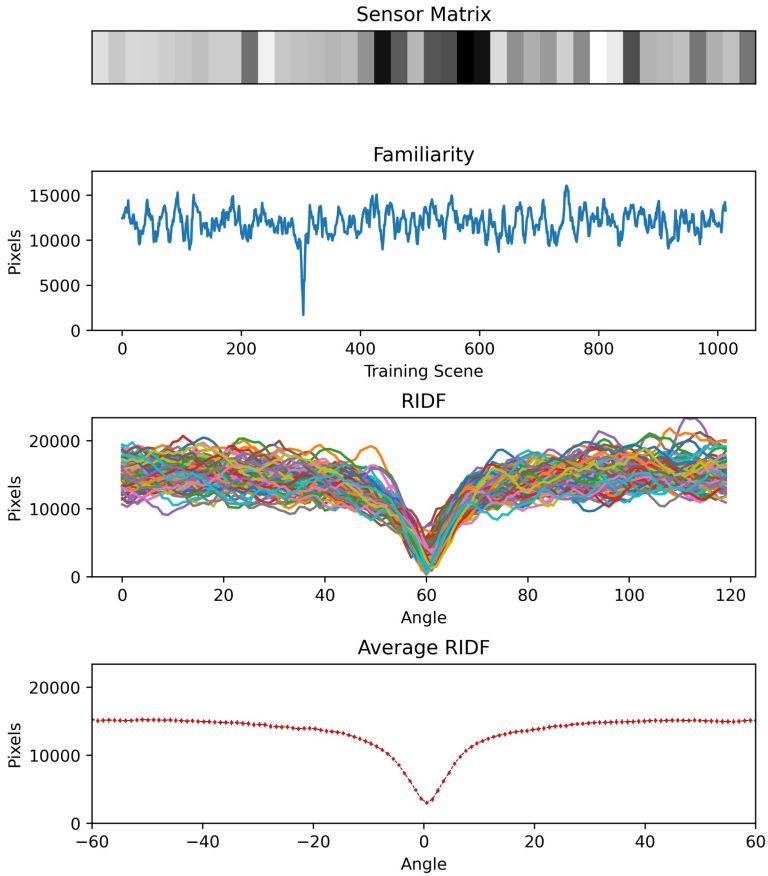
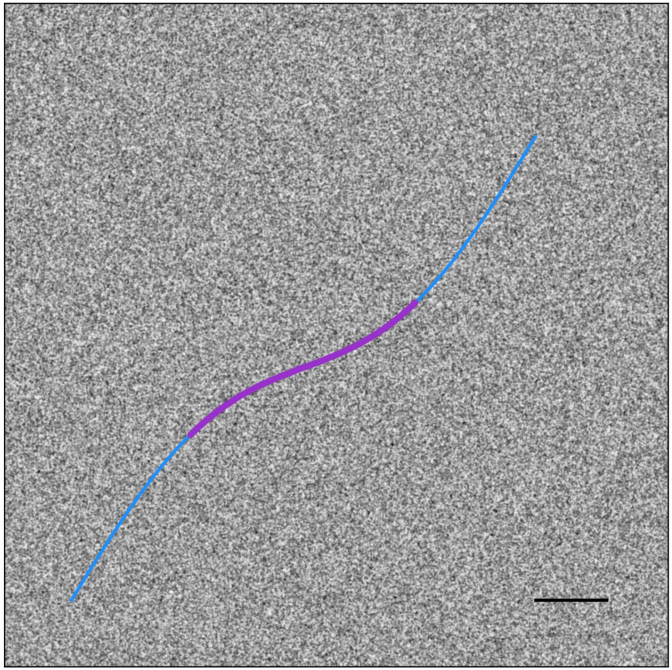
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

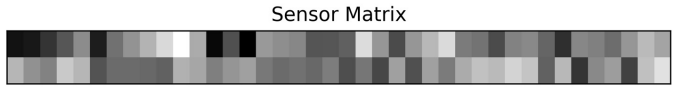


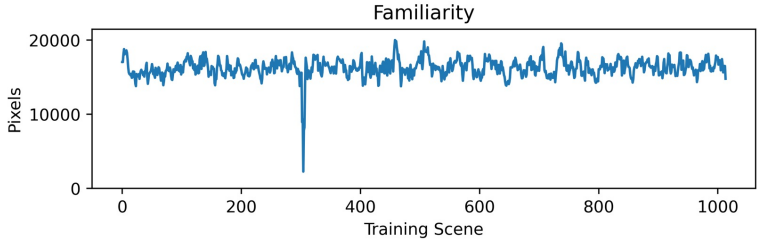


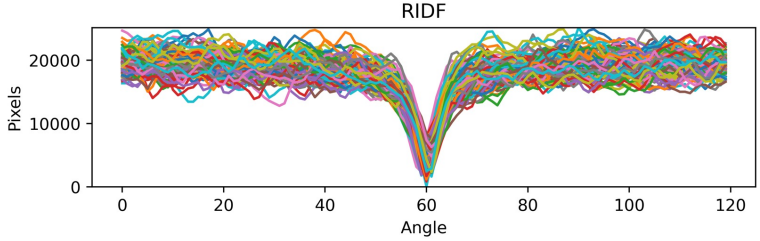
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

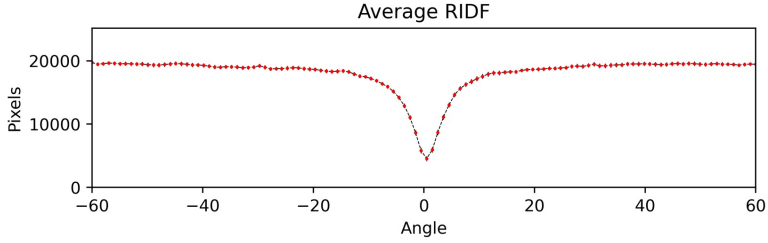
Navigation stats: RMSD error: 55.42; RMSD/dist: 0.139; TD: 8801; p90: 16; p50: 8; complete: 0





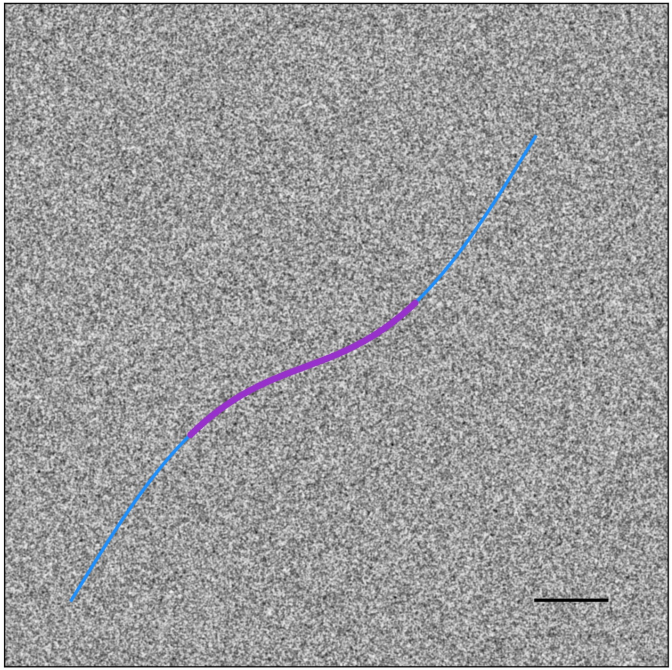


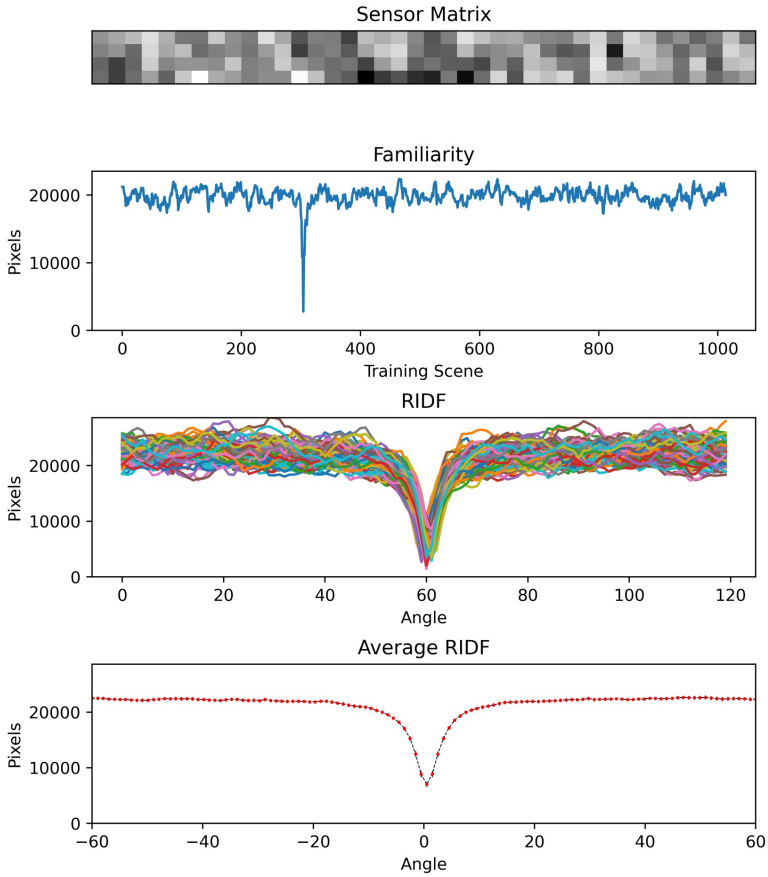




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

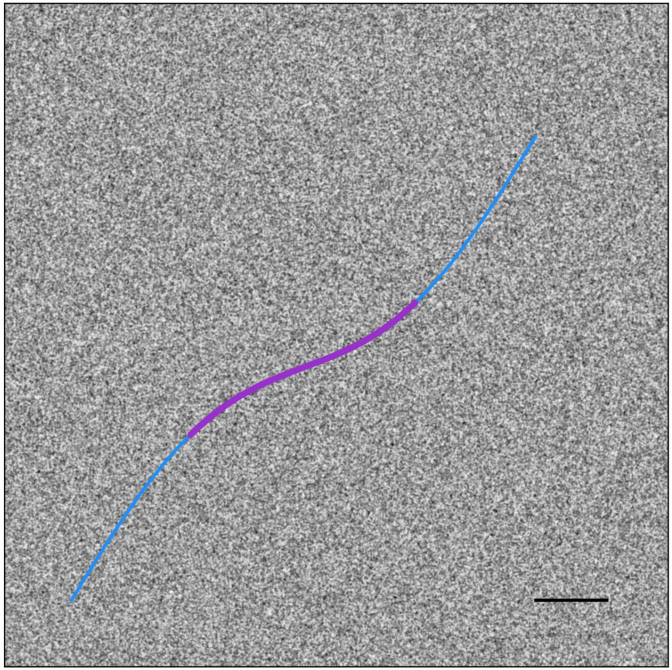
Navigation stats: RMSD error: 51.27; RMSD/dist: 0.128; TD: 11745; p90: 12; p50: 6; complete: 0

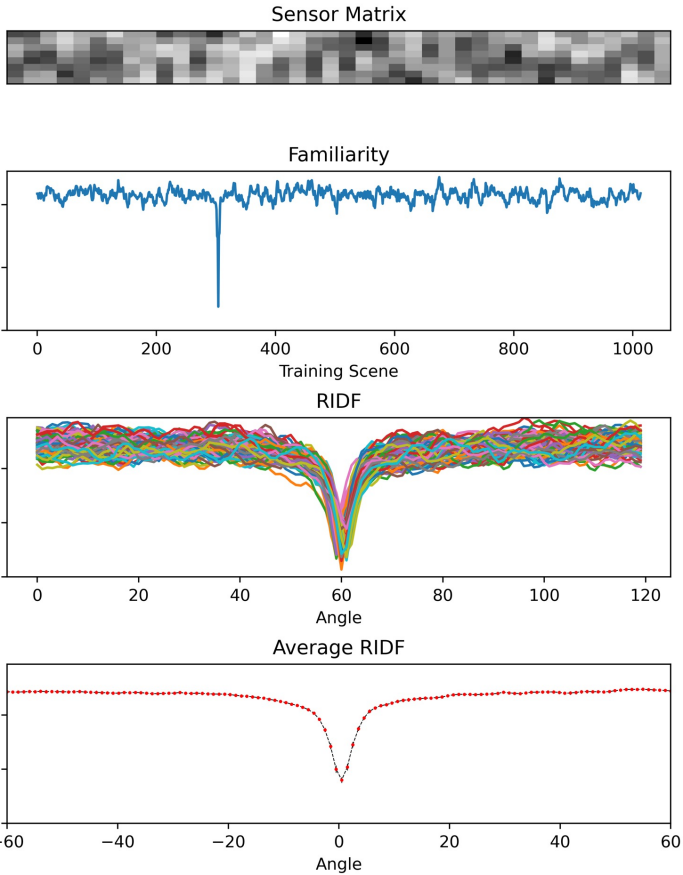




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

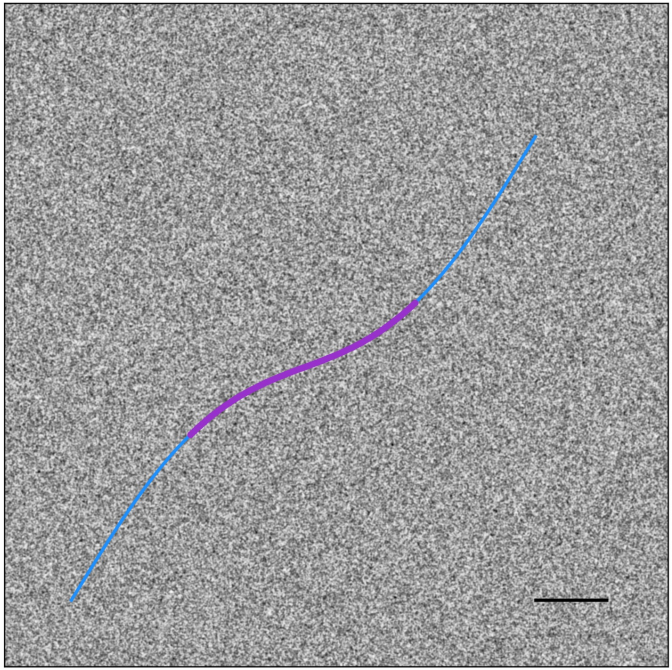
Navigation stats: RMSD error: 60.52; RMSD/dist: 0.151; TD: 12622; p90: 10; p50: 4; complete: 0

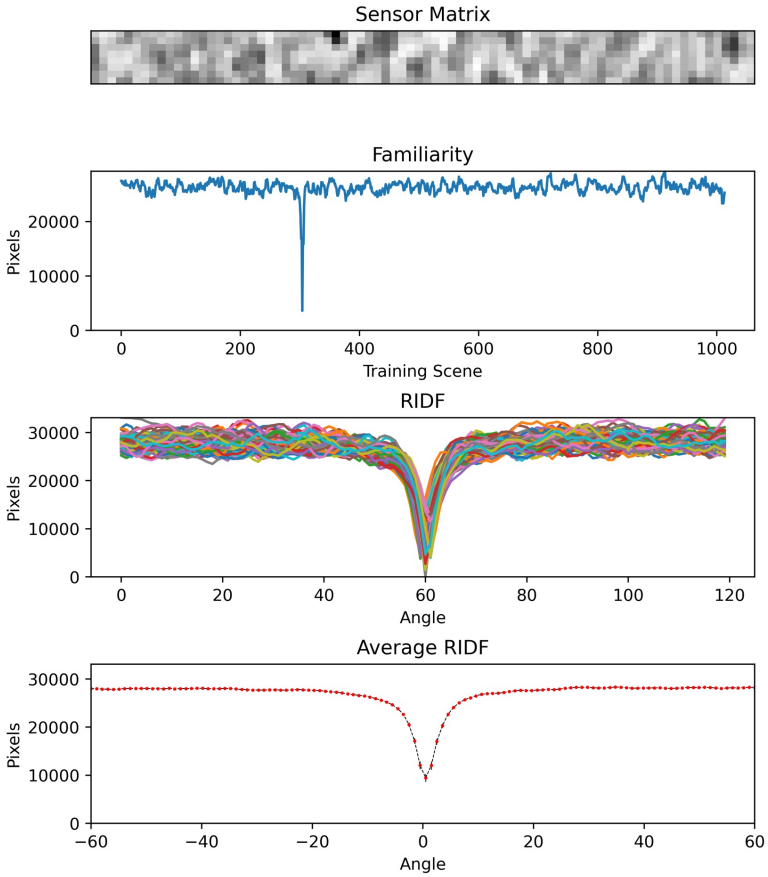




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

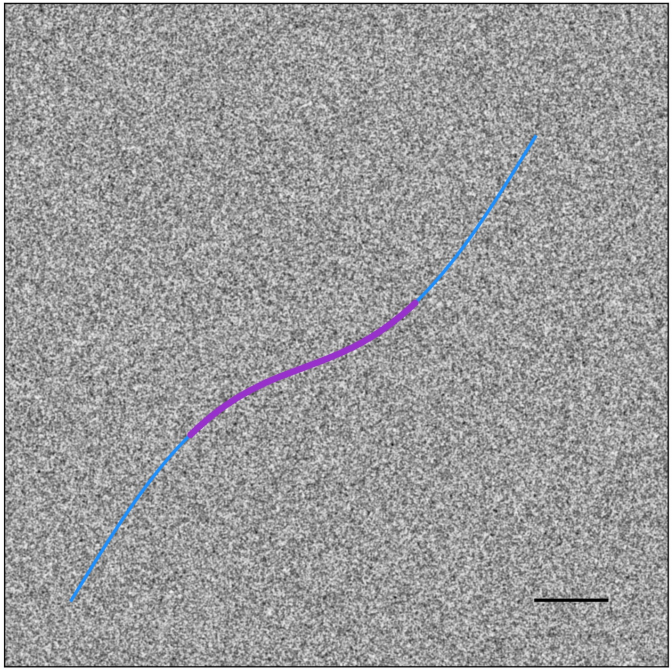
Navigation stats: RMSD error: 61.25; RMSD/dist: 0.153; TD: 13433; p90: 10; p50: 4; complete: 0

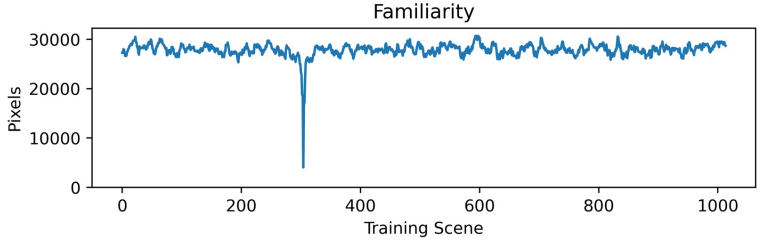


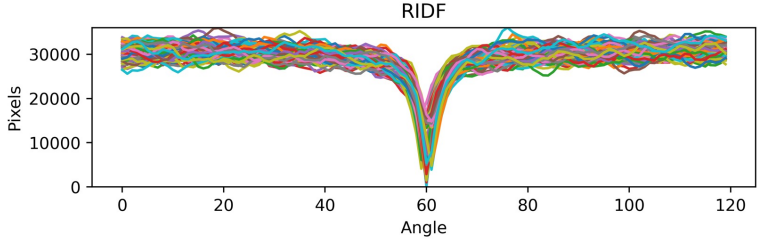


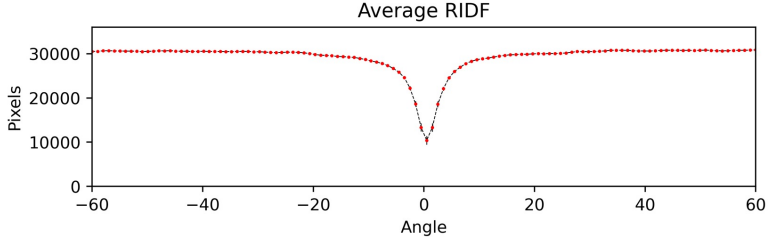
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 49.16; RMSD/dist: 0.123; TD: 16222; p90: 10; p50: 4; complete: 0



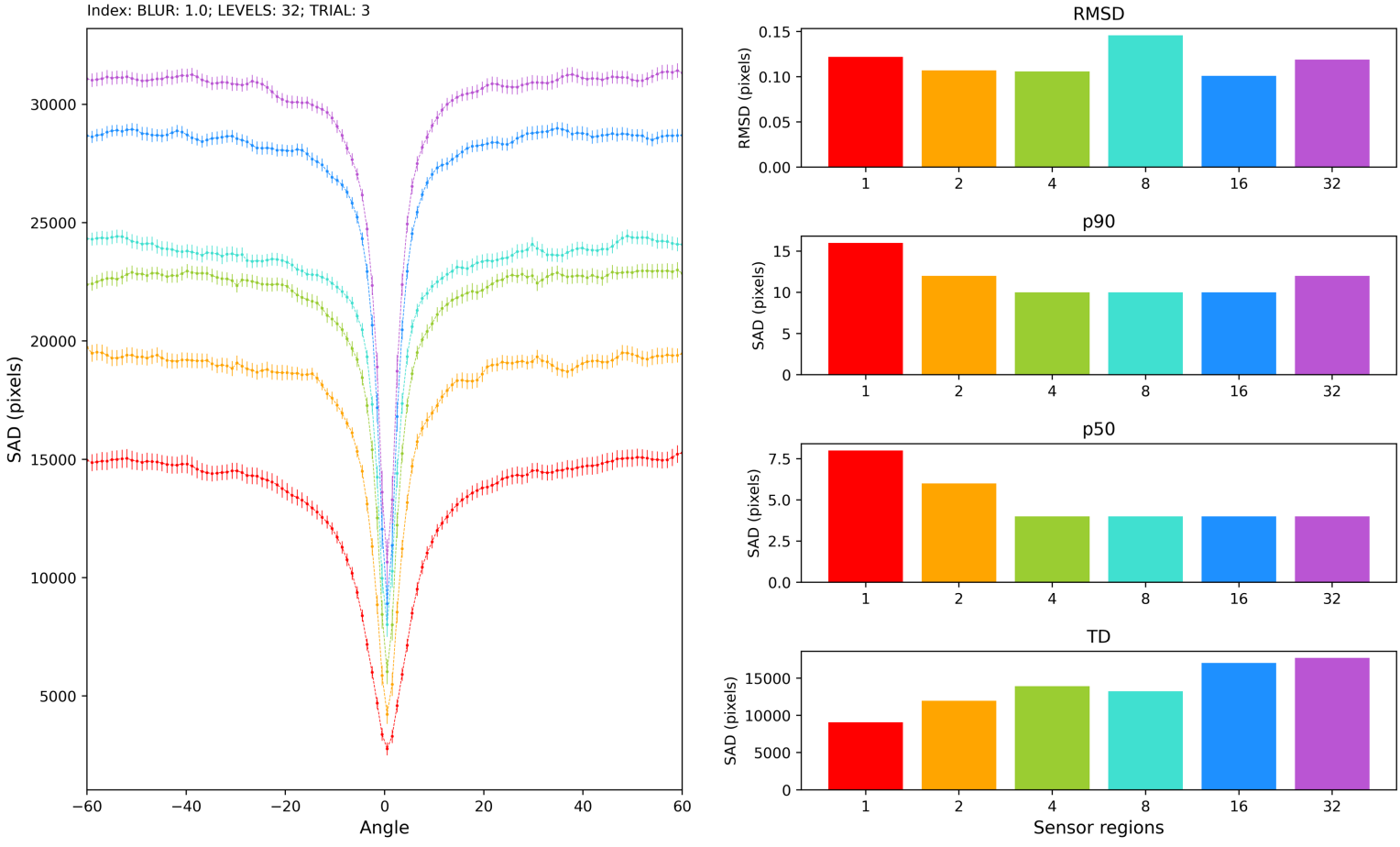






Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 47.96; RMSD/dist: 0.120; TD: 17758; p90: 12; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 32; TRIAL: 3
SAD (pixels)
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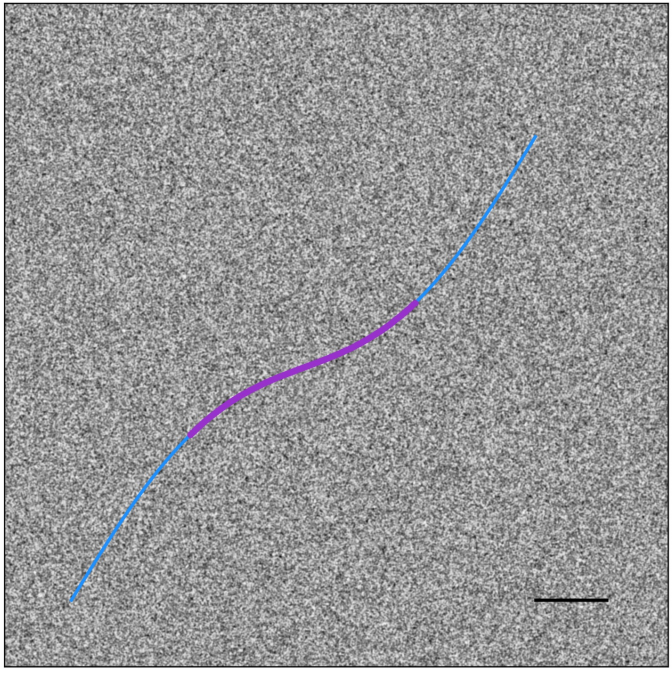
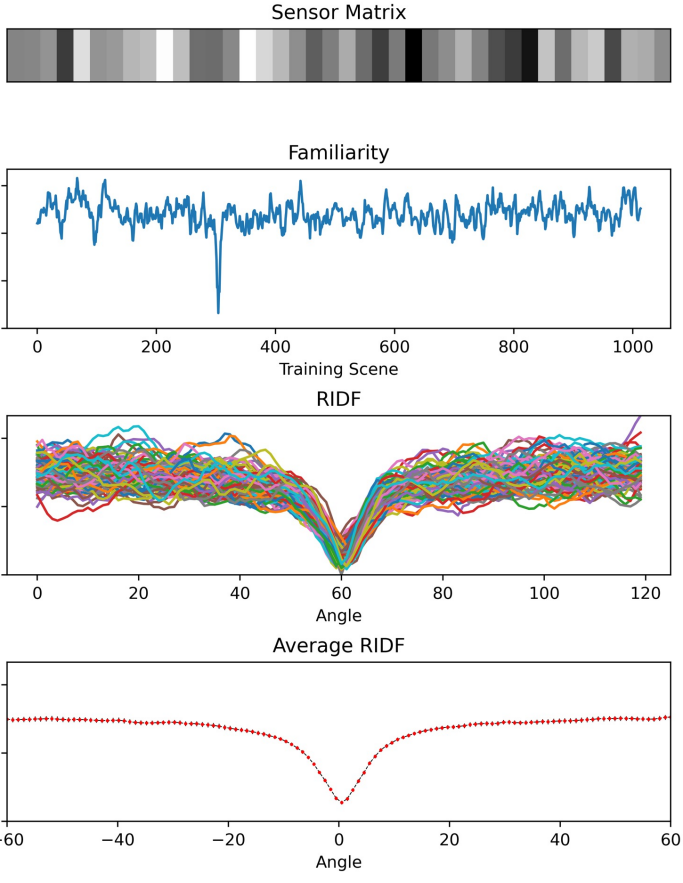
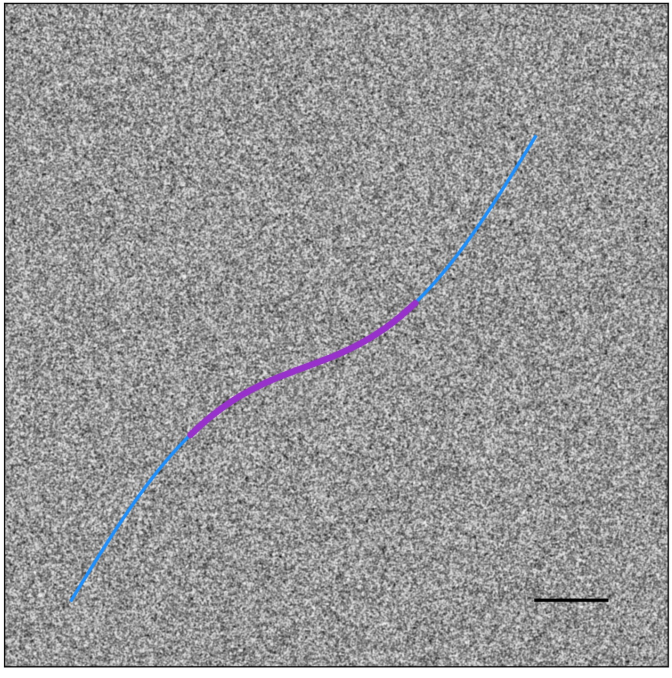
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

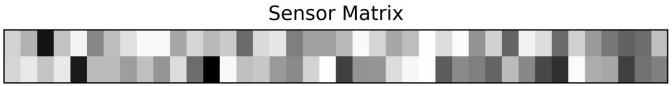


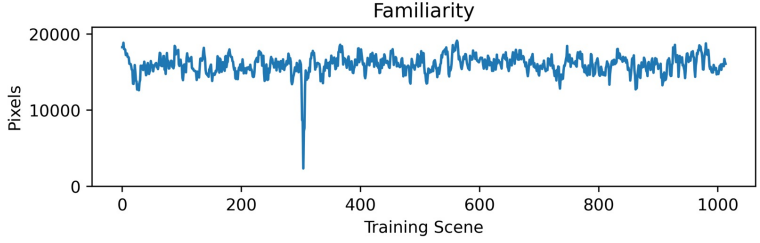


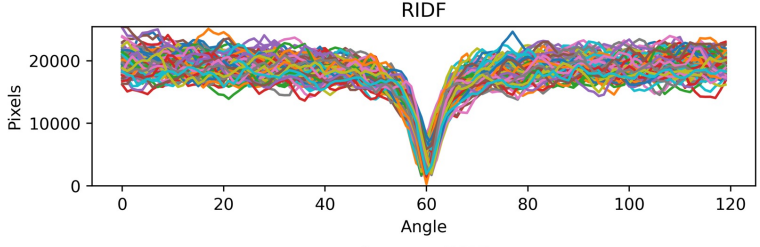
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

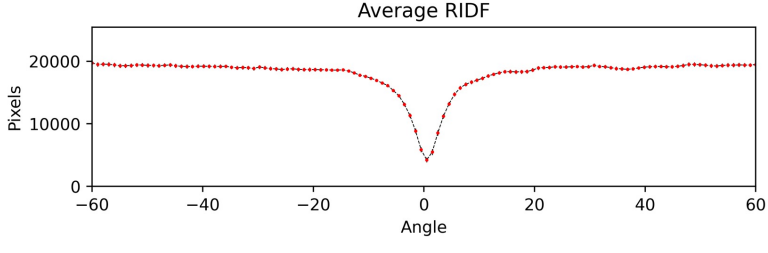
Navigation stats: RMSD error: 48.77; RMSD/dist: 0.122; TD: 9074; p90: 16; p50: 8; complete: 0





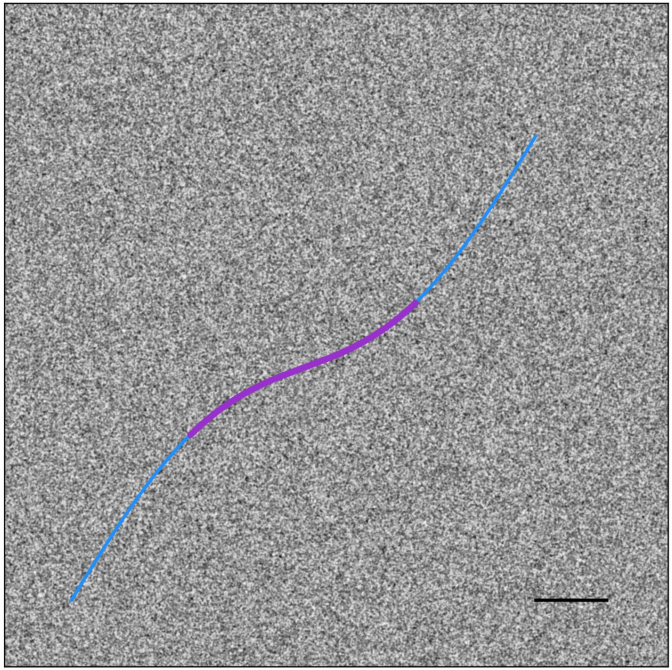


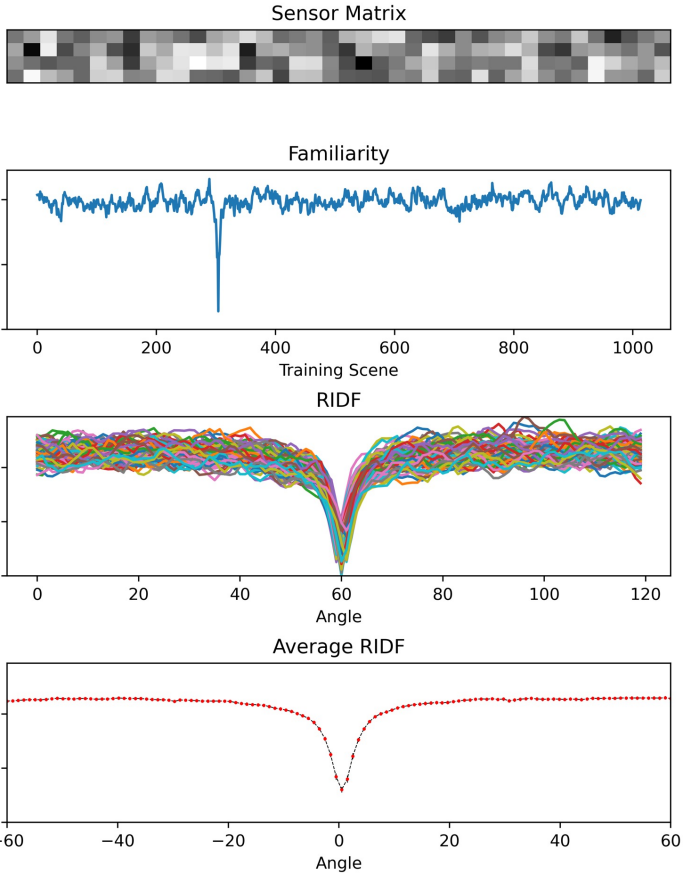




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

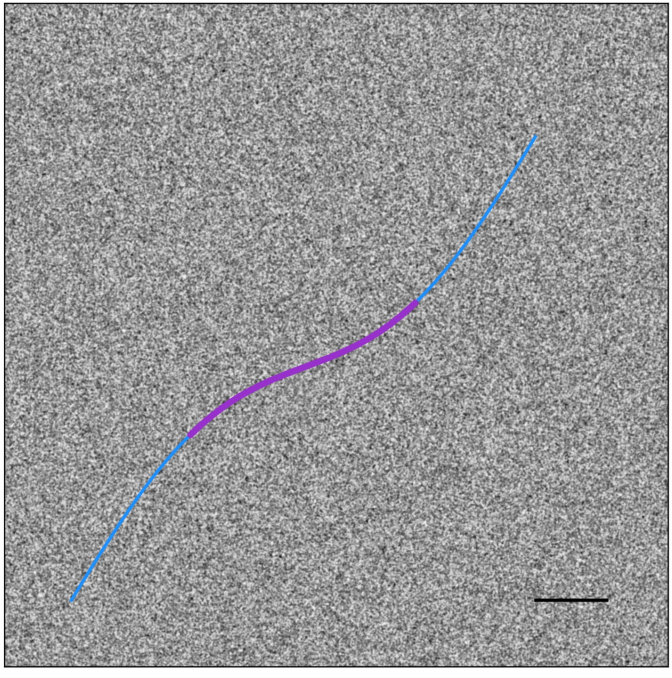
Navigation stats: RMSD error: 42.90; RMSD/dist: 0.107; TD: 11972; p90: 12; p50: 6; complete: 0

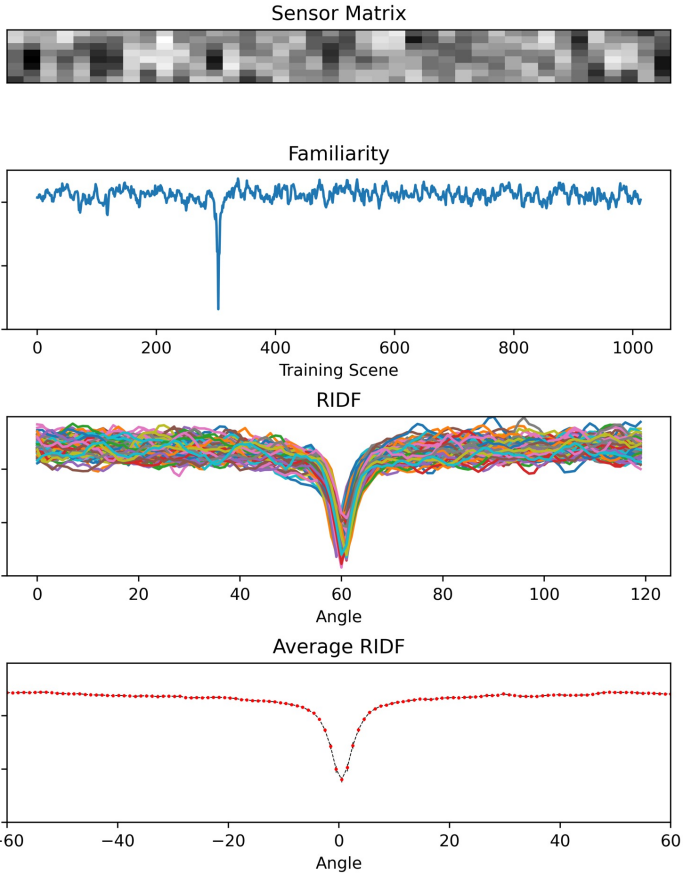




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

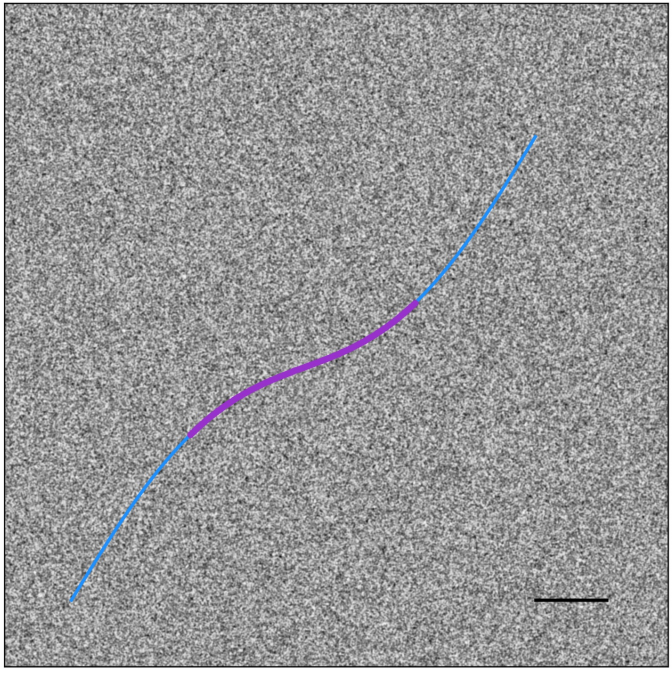
Navigation stats: RMSD error: 42.54; RMSD/dist: 0.106; TD: 13914; p90: 10; p50: 4; complete: 0

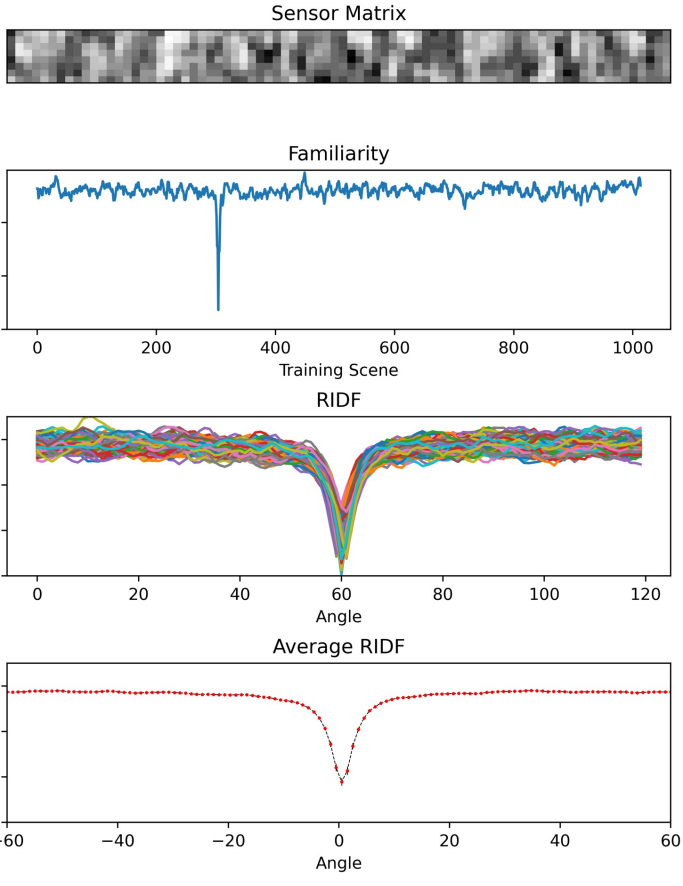




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

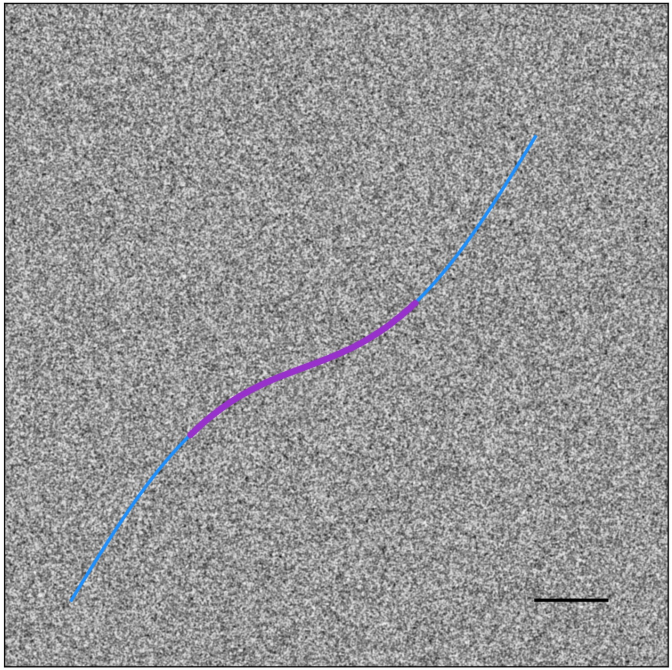
Navigation stats: RMSD error: 58.60; RMSD/dist: 0.146; TD: 13236; p90: 10; p50: 4; complete: 0

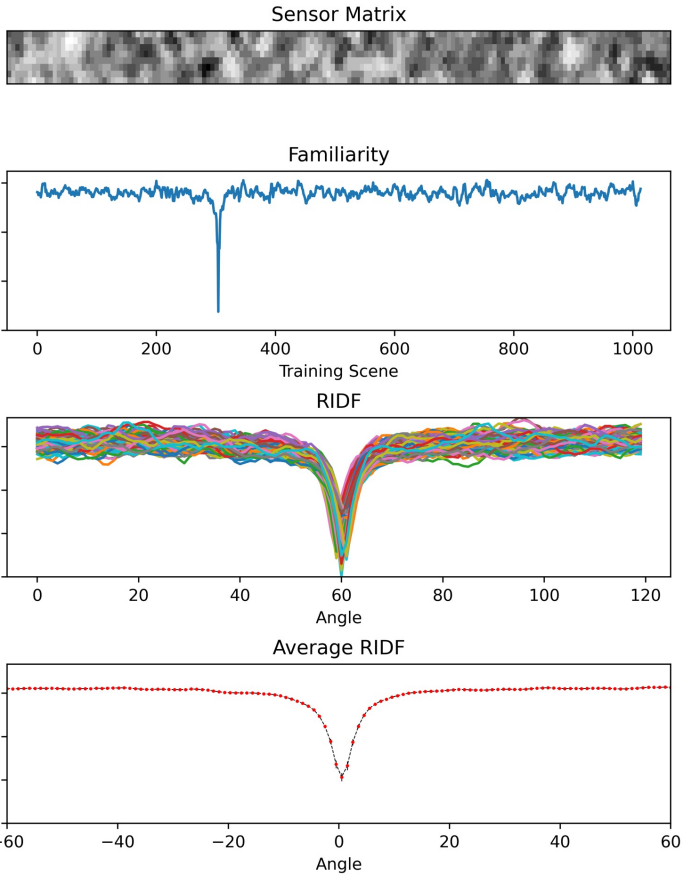




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

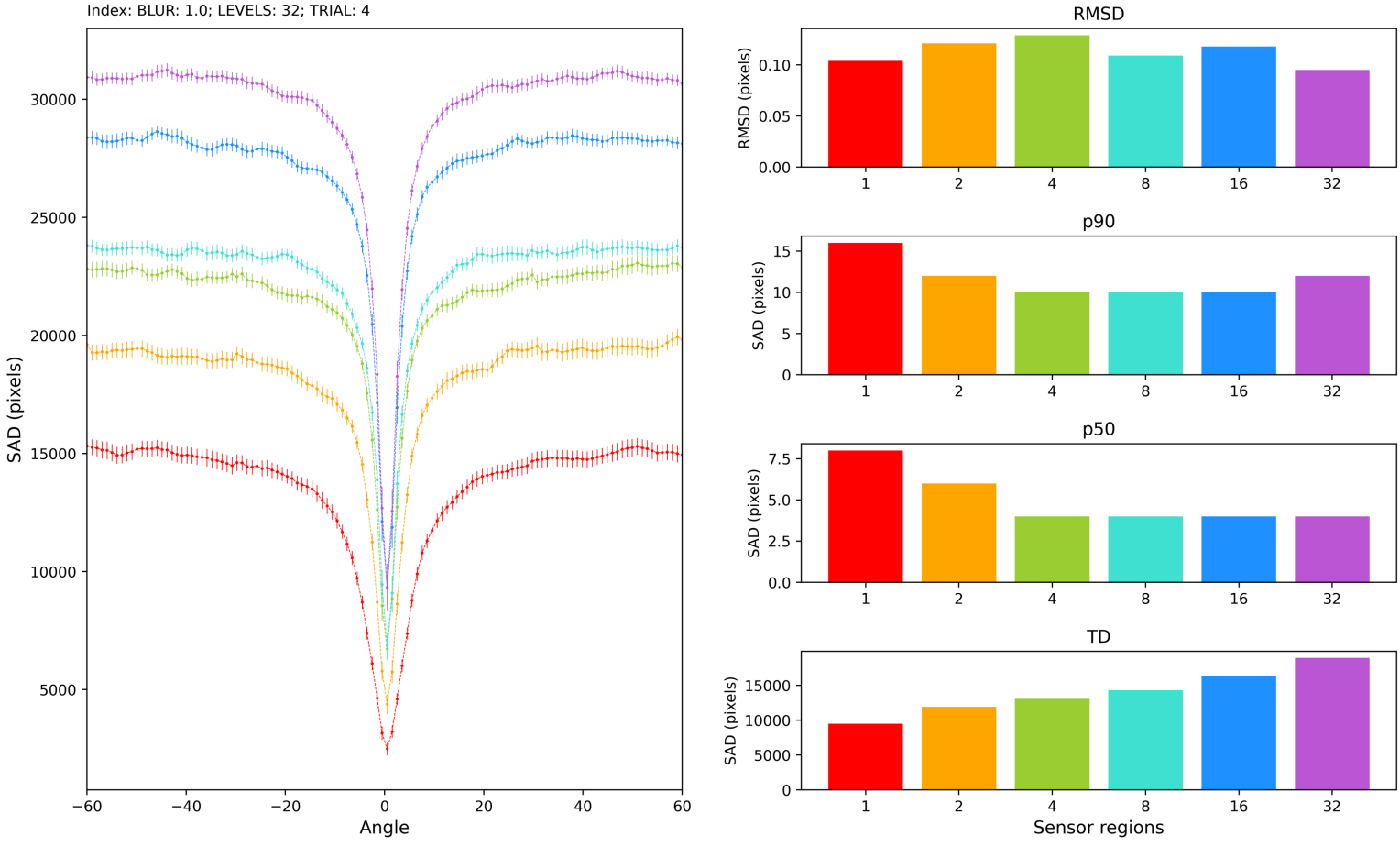
Navigation stats: RMSD error: 40.41; RMSD/dist: 0.101; TD: 17052; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 47.57; RMSD/dist: 0.119; TD: 17718; p90: 12; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 32; TRIAL: 4
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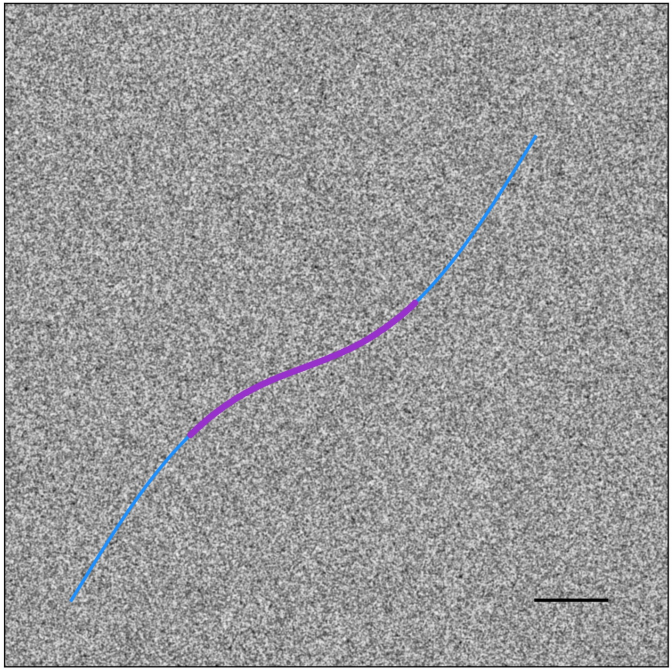
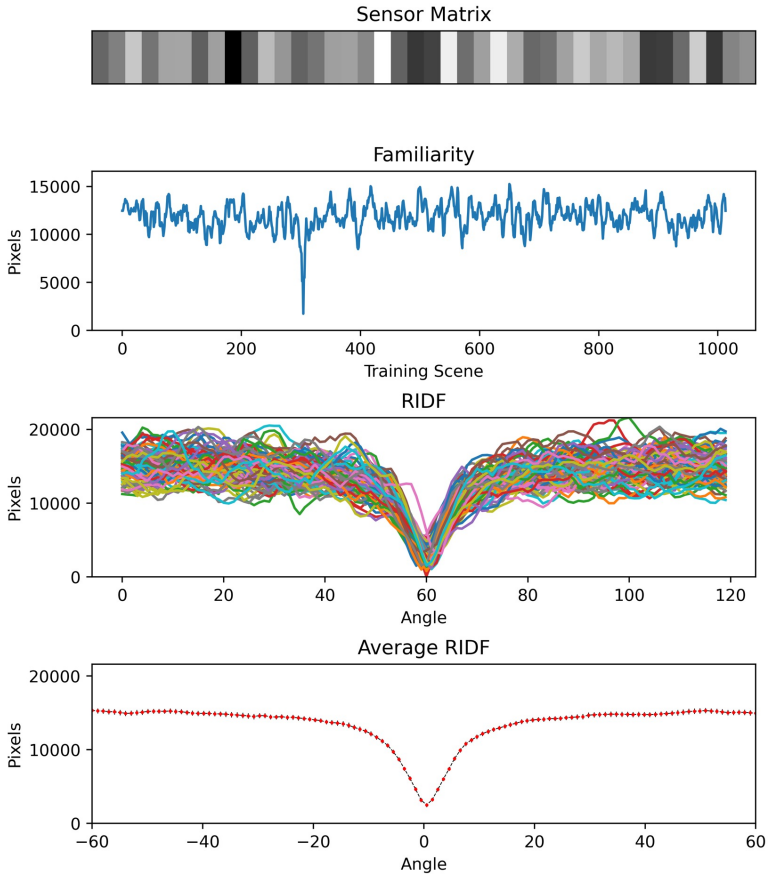
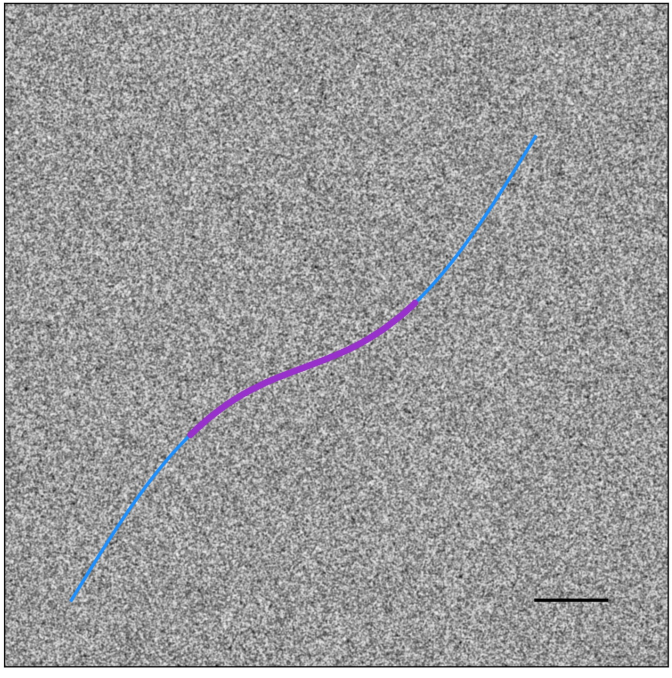
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

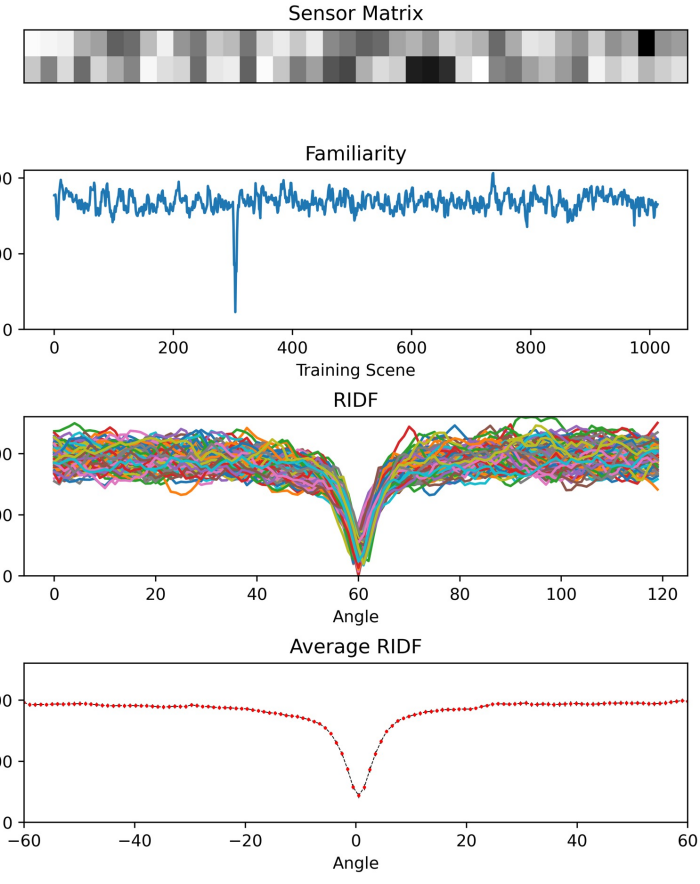




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

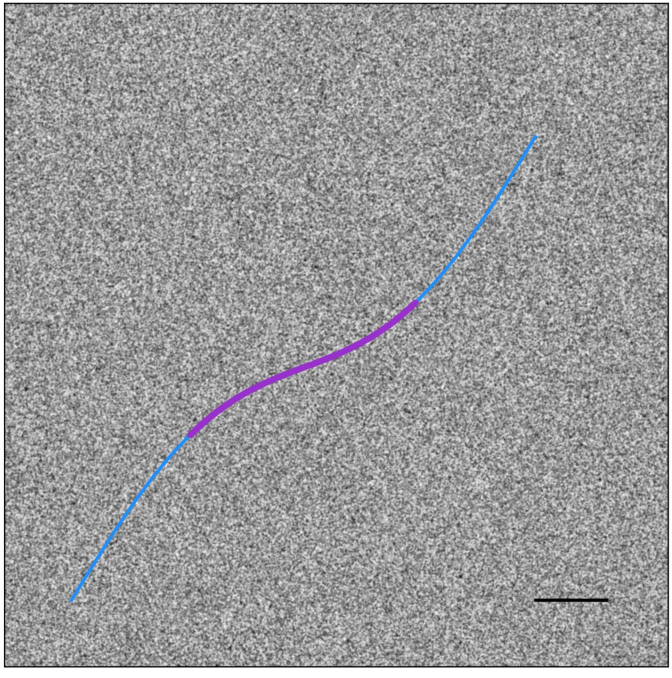
Navigation stats: RMSD error: 41.64; RMSD/dist: 0.104; TD: 9475; p90: 16; p50: 8; complete: 0

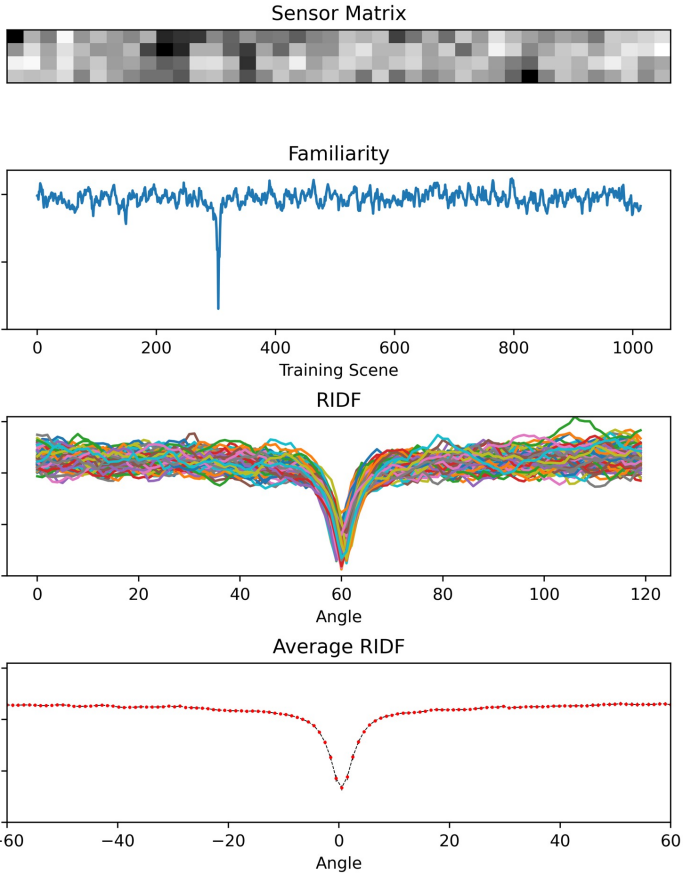




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

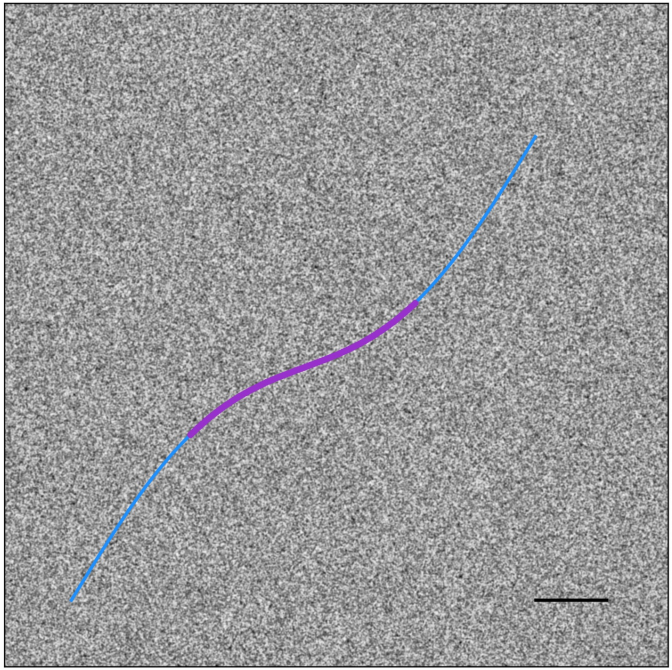
Navigation stats: RMSD error: 48.47; RMSD/dist: 0.121; TD: 11914; p90: 12; p50: 6; complete: 0

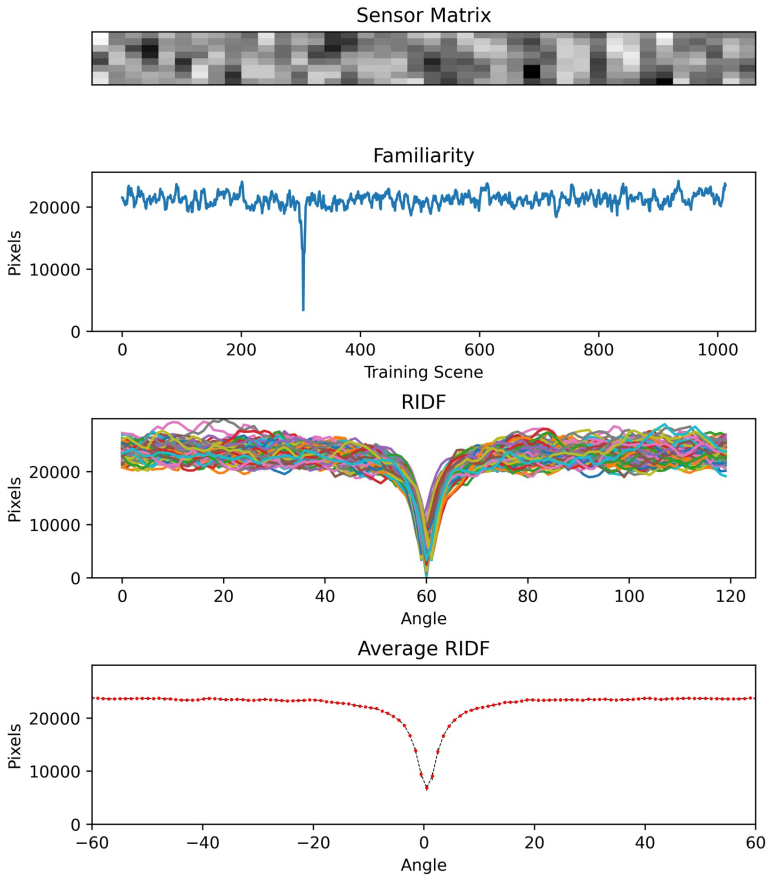




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

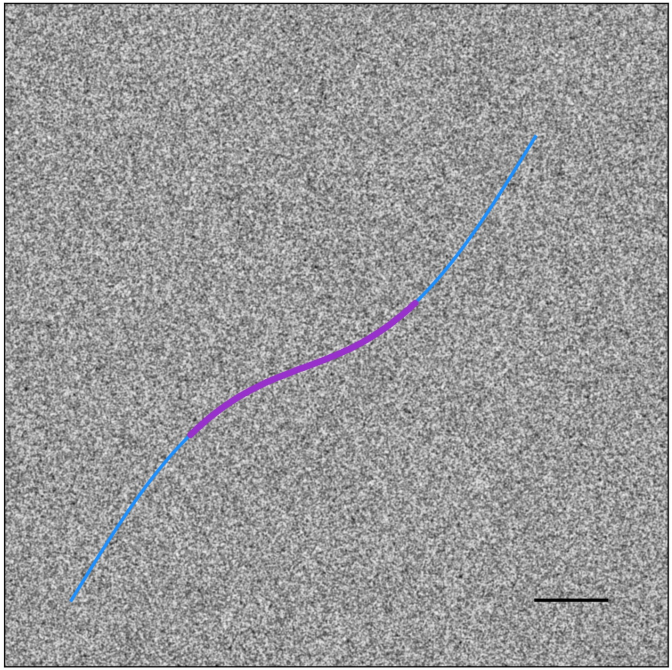
Navigation stats: RMSD error: 51.76; RMSD/dist: 0.129; TD: 13052; p90: 10; p50: 4; complete: 0

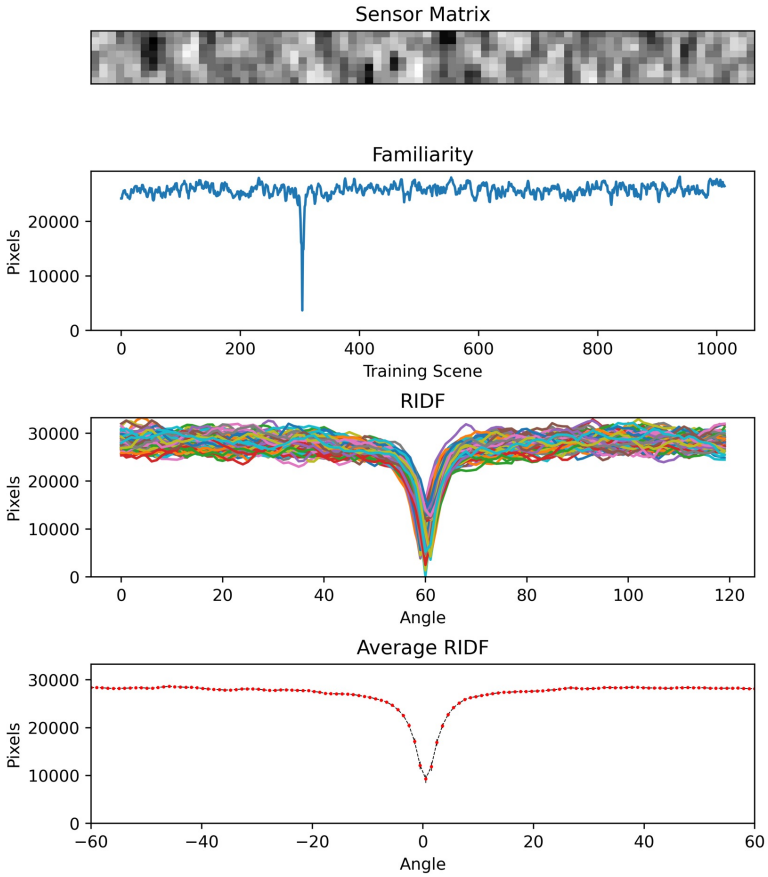




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

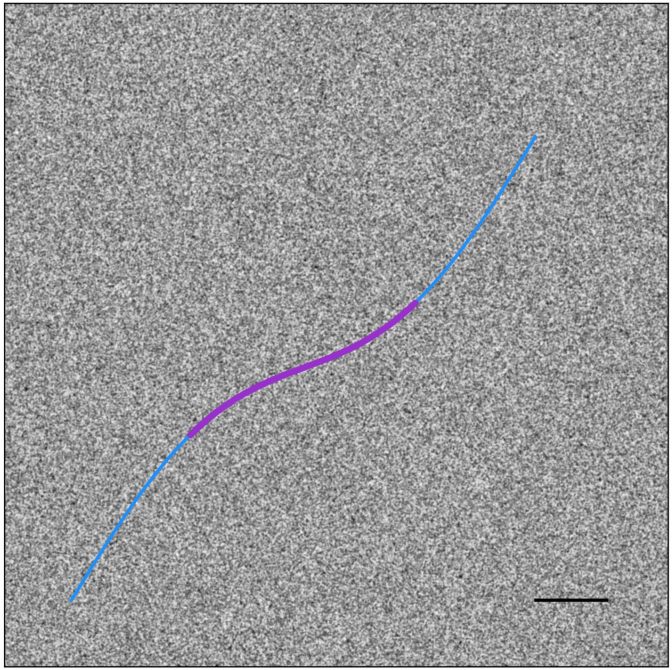
Navigation stats: RMSD error: 43.46; RMSD/dist: 0.109; TD: 14306; p90: 10; p50: 4; complete: 0

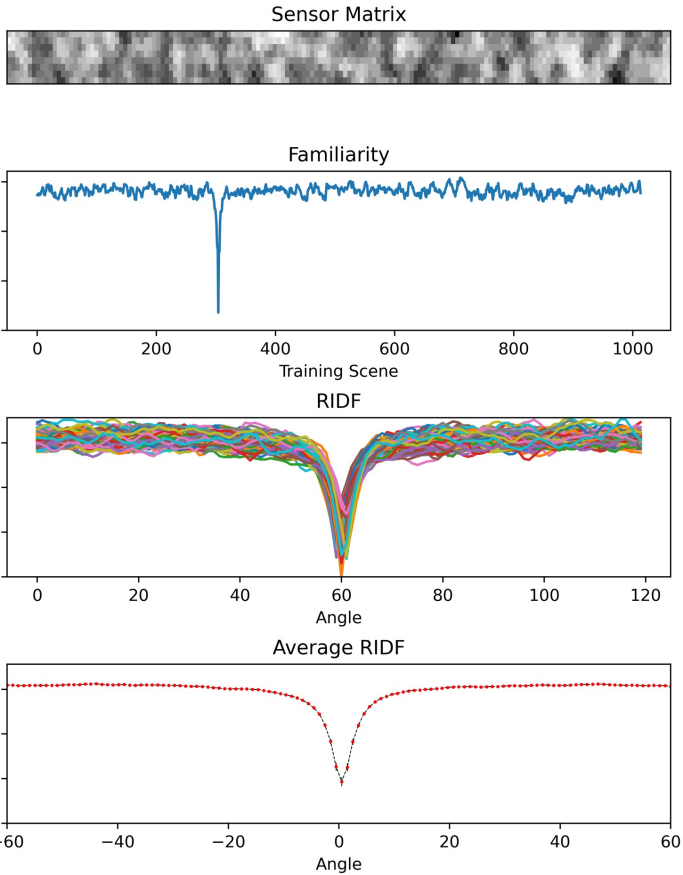




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 47.14; RMSD/dist: 0.118; TD: 16308; p90: 10; p50: 4; complete: 0





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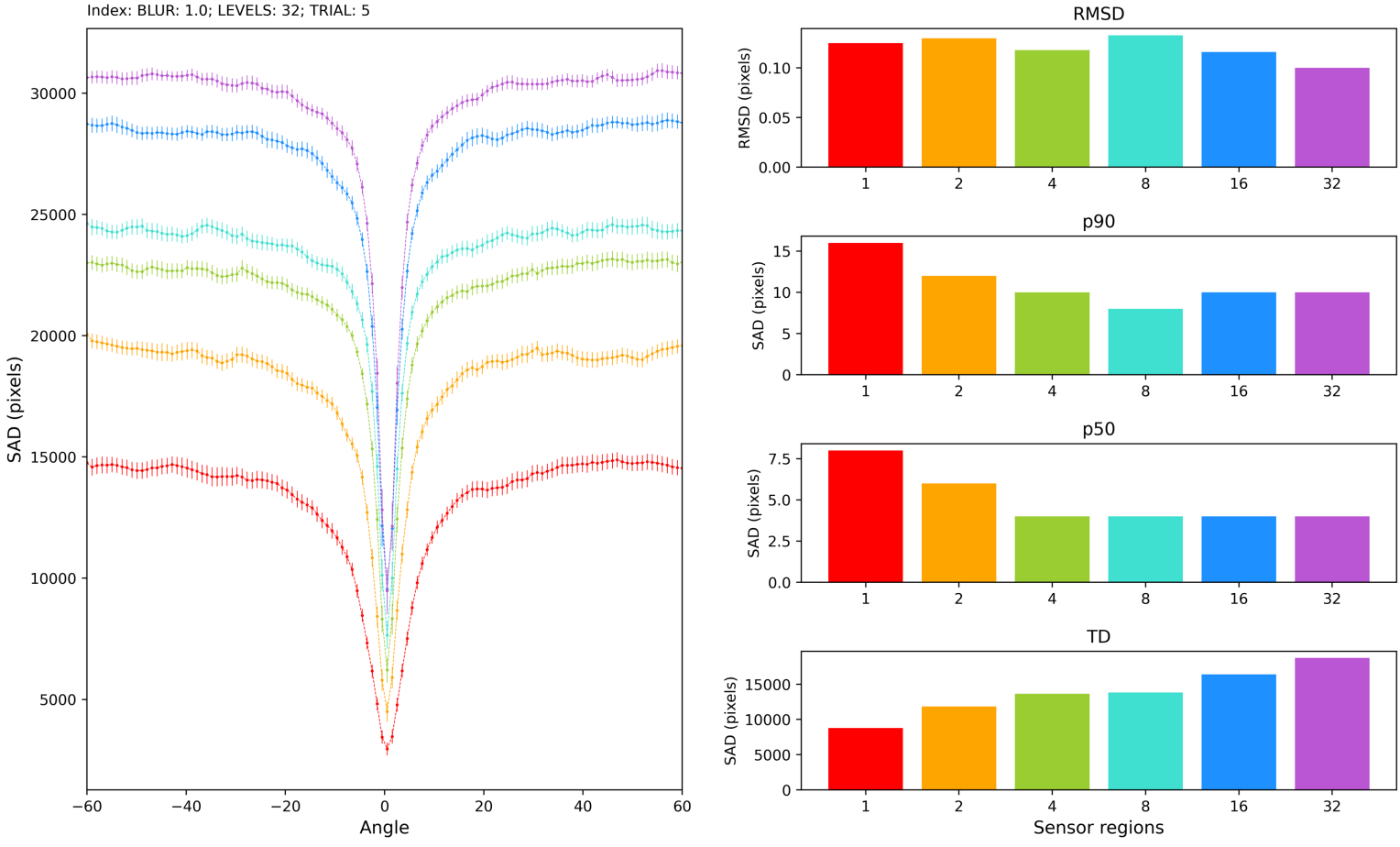
Navigation stats: RMSD error: 38.20; RMSD/dist: 0.095; TD: 18931; p90: 12; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 32; TRIAL: 5
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25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
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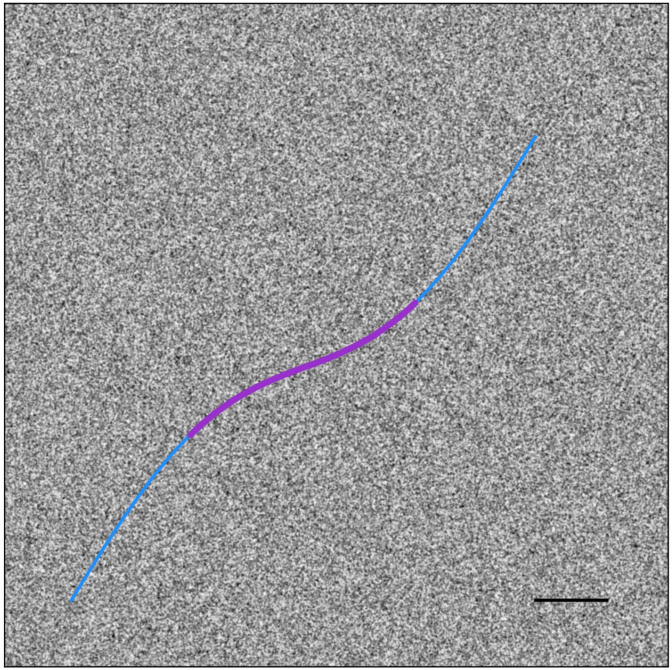
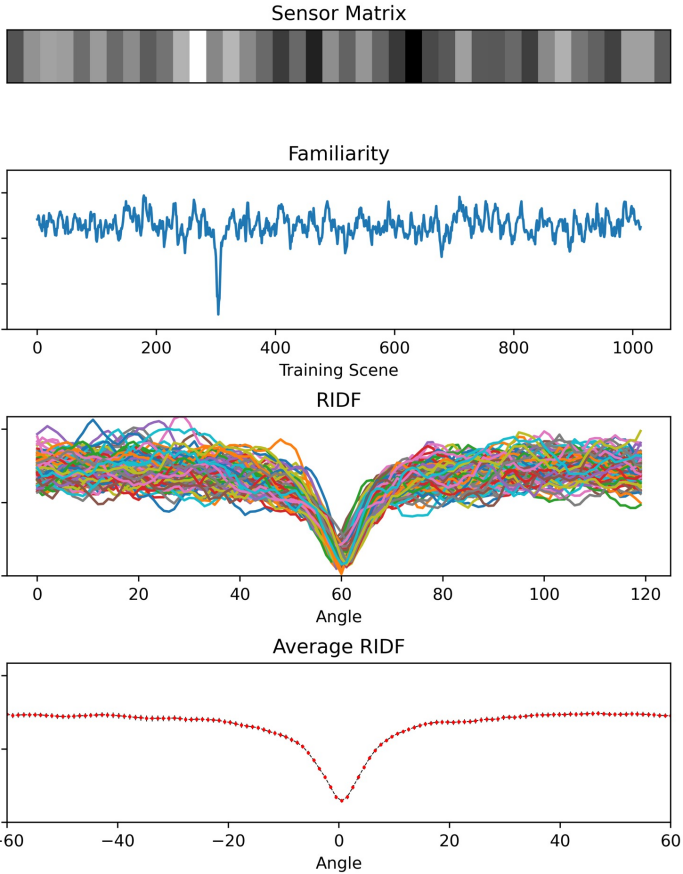
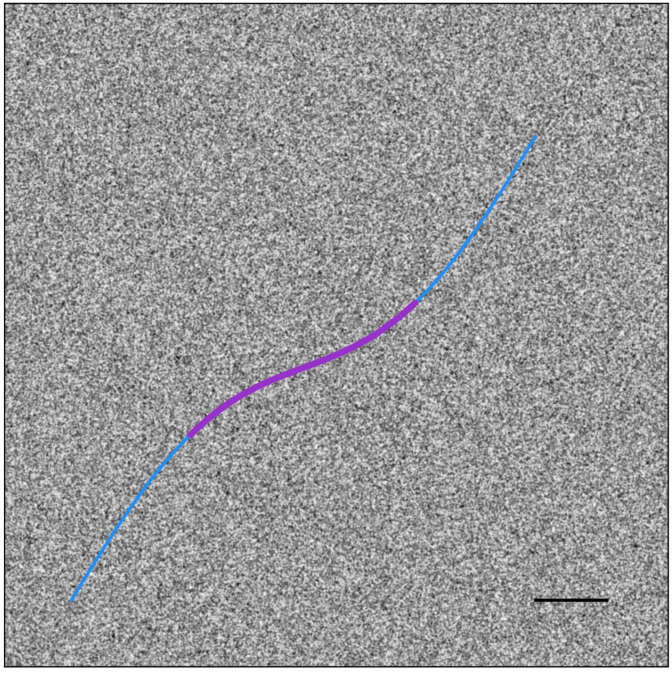
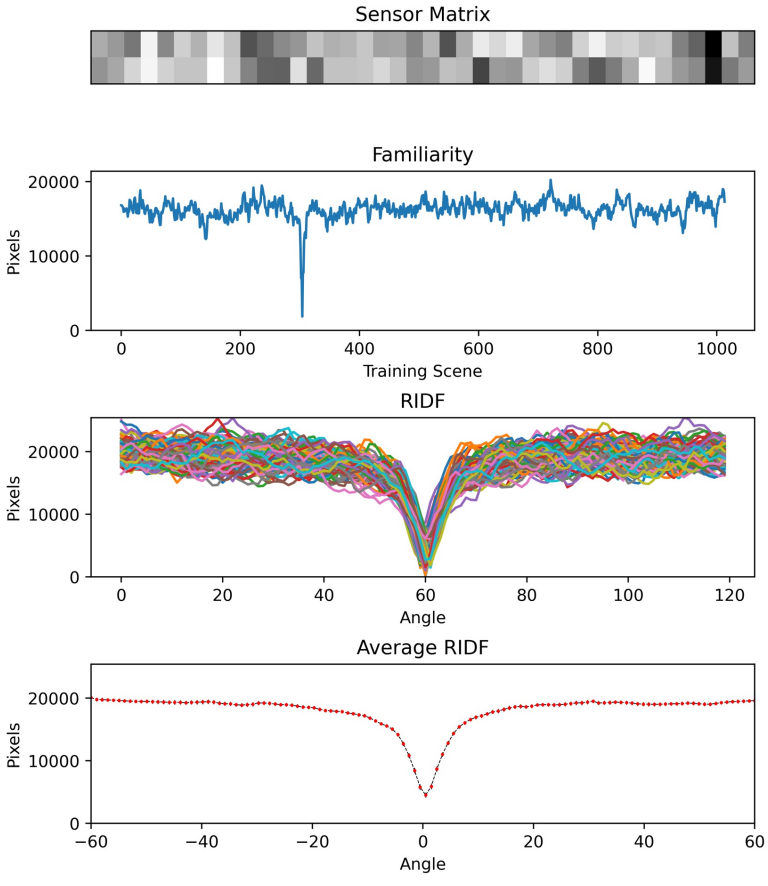




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

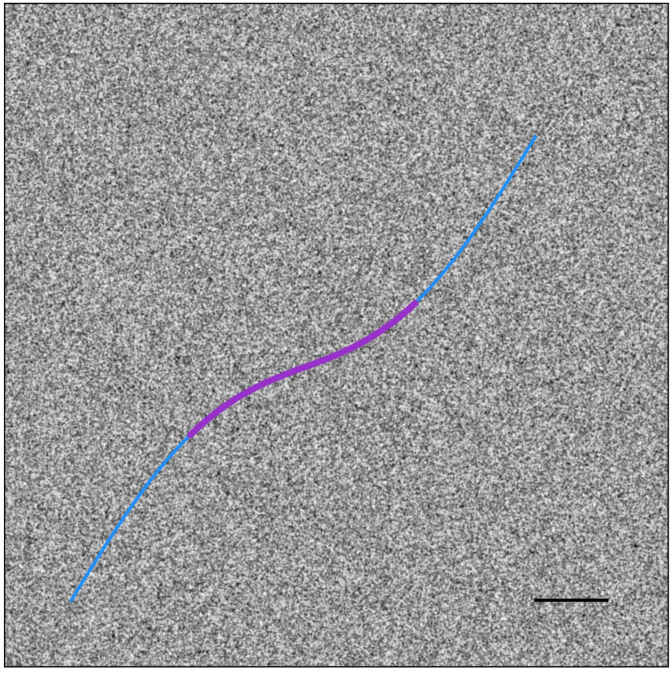
Navigation stats: RMSD error: 50.09; RMSD/dist: 0.125; TD: 8775; p90: 16; p50: 8; complete: 0

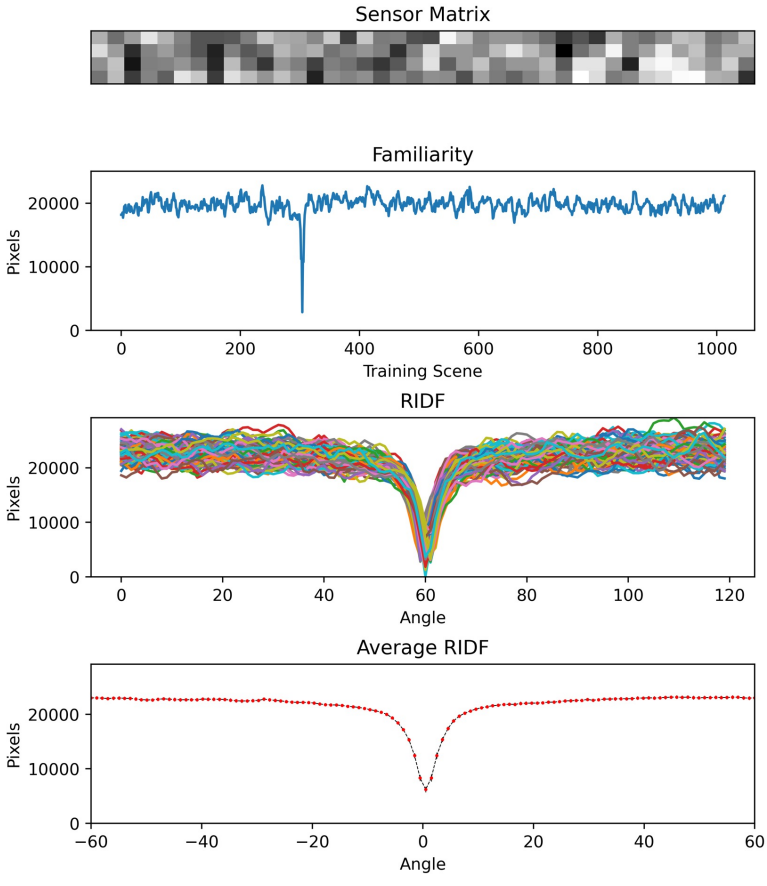




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

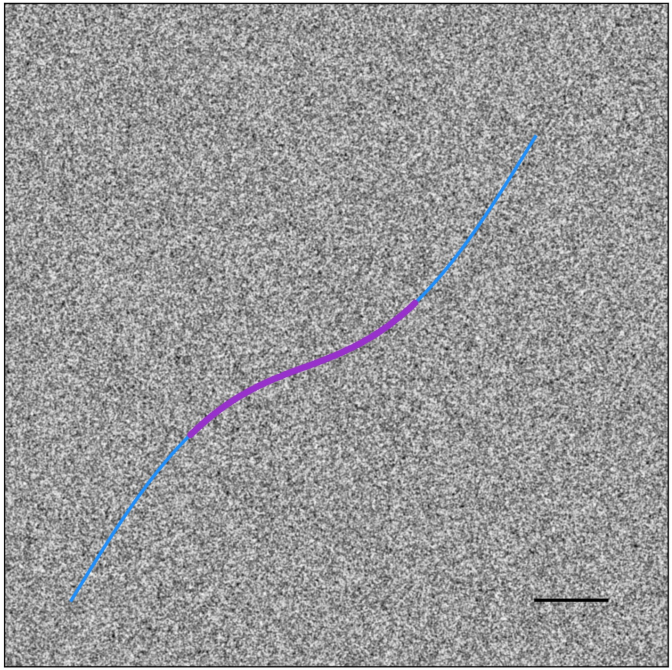
Navigation stats: RMSD error: 51.83; RMSD/dist: 0.130; TD: 11836; p90: 12; p50: 6; complete: 0

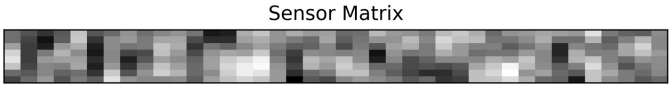


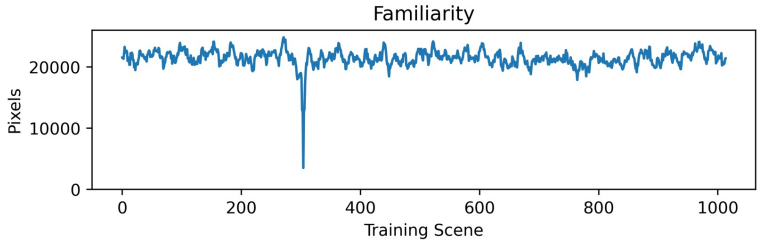


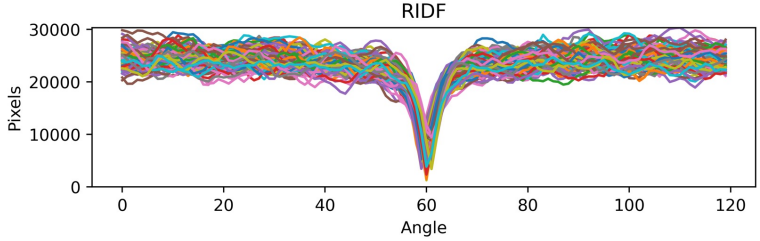
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

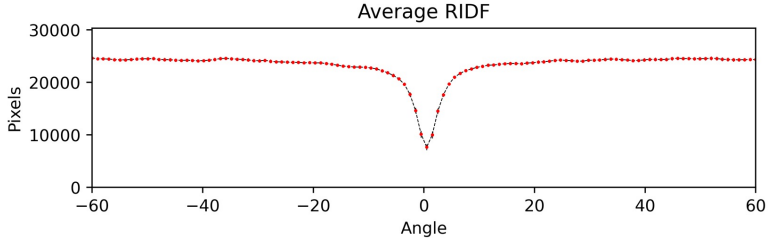
Navigation stats: RMSD error: 47.26; RMSD/dist: 0.118; TD: 13657; p90: 10; p50: 4; complete: 0





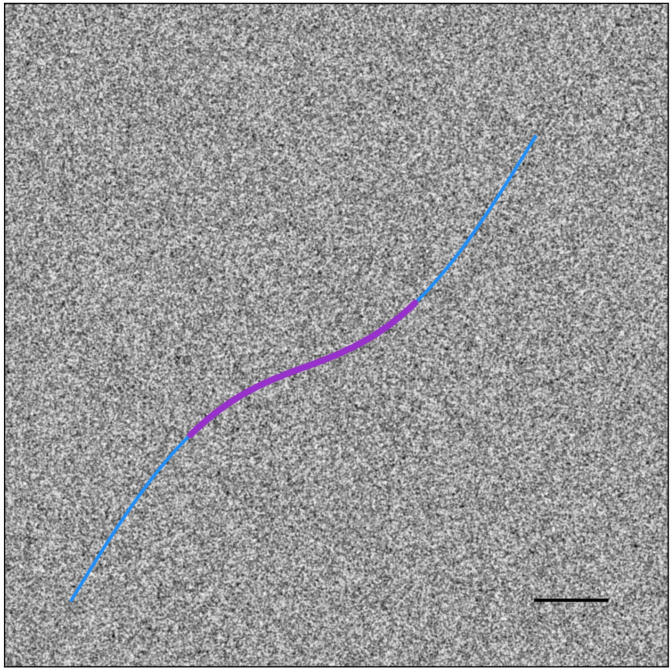


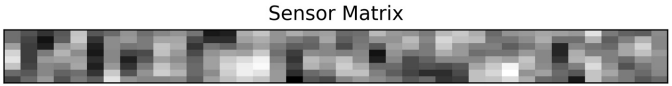


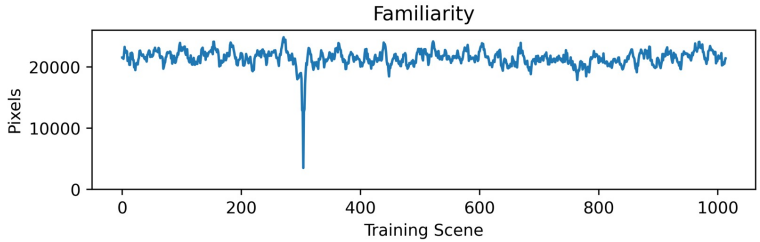


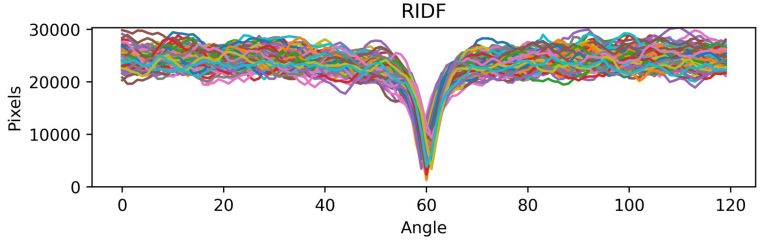
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

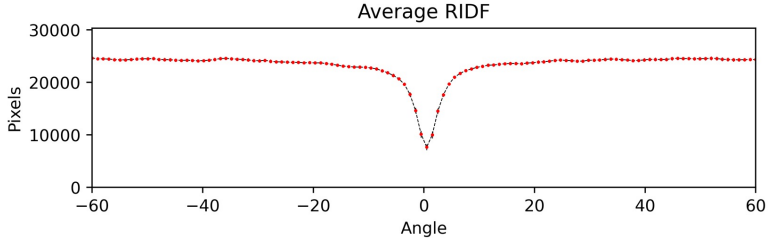
Navigation stats: RMSD error: 53.13; RMSD/dist: 0.133; TD: 13829; p90: 8; p50: 4; complete: 0





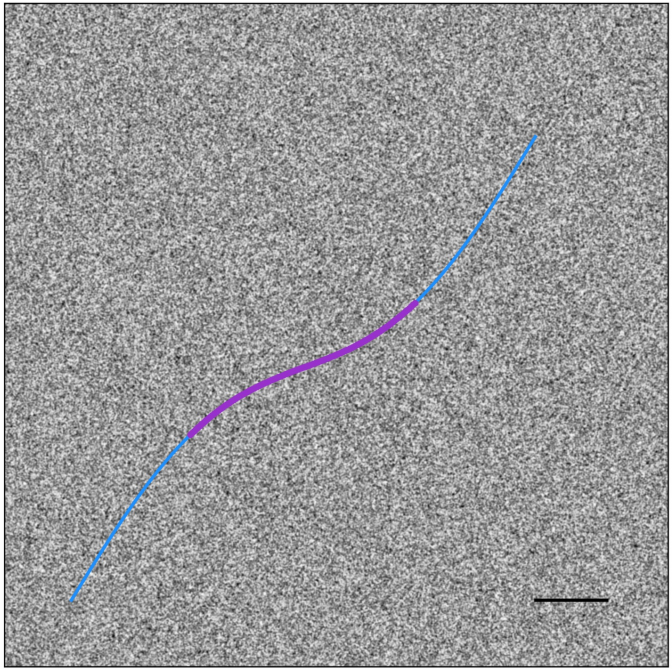


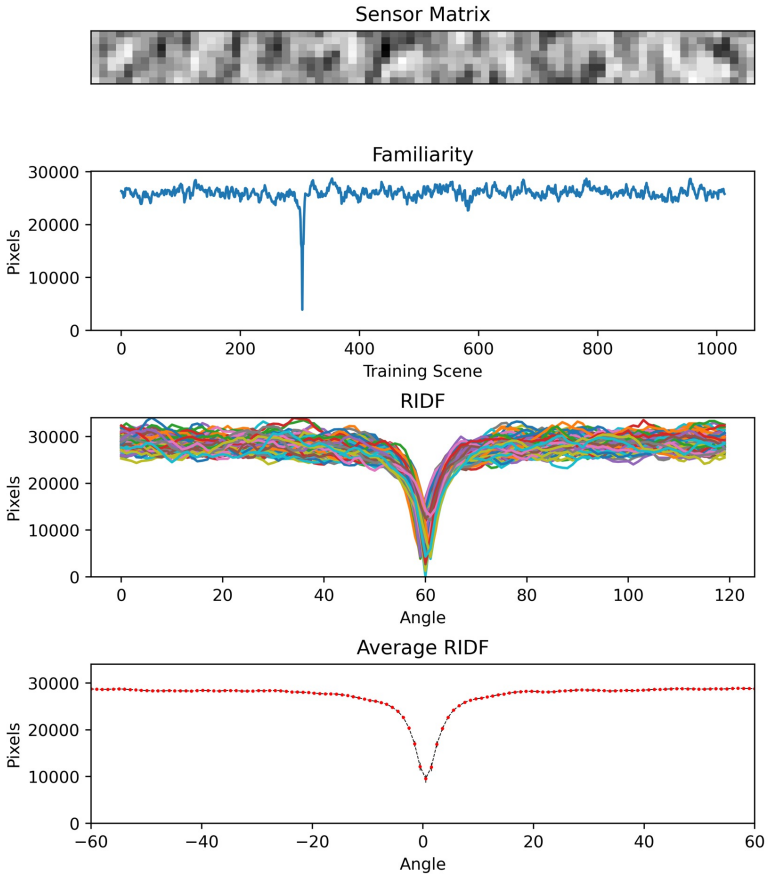




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

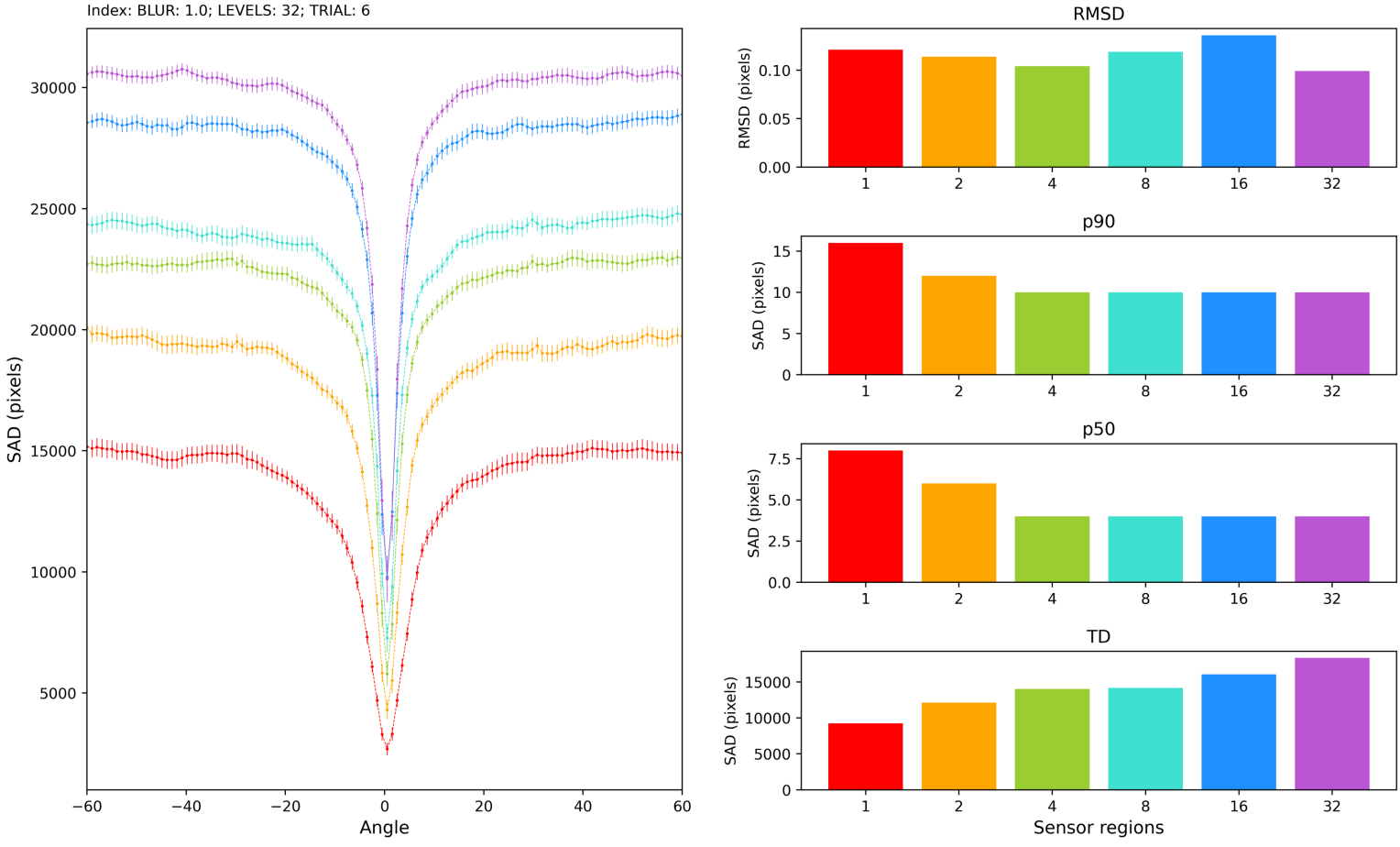
Navigation stats: RMSD error: 53.13; RMSD/dist: 0.133; TD: 13829; p90: 8; p50: 4; complete: 0

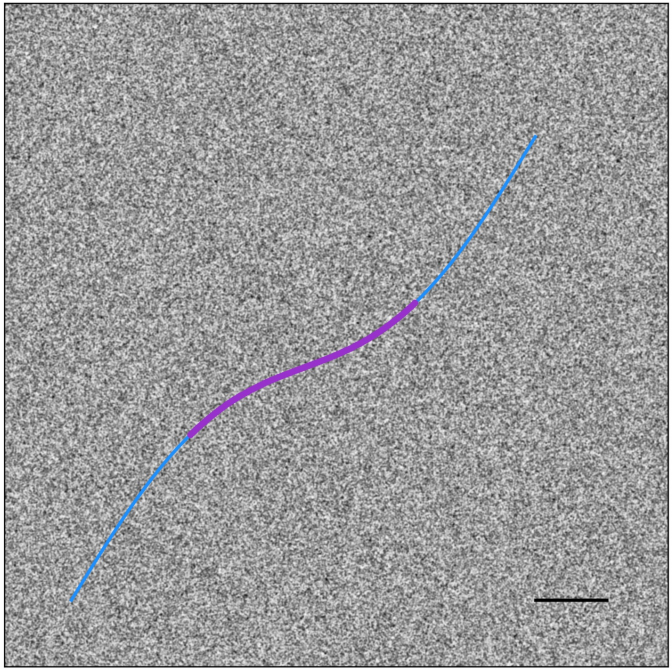


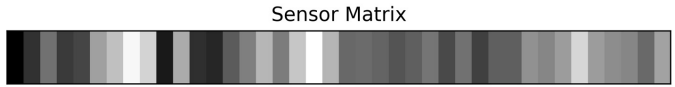


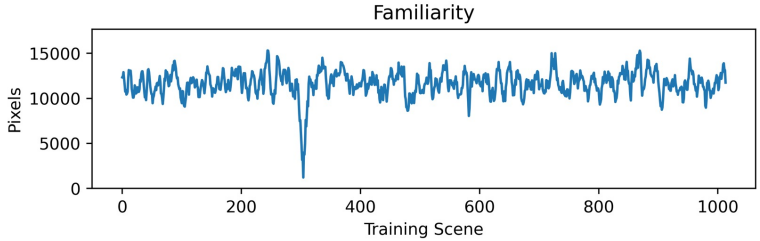
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

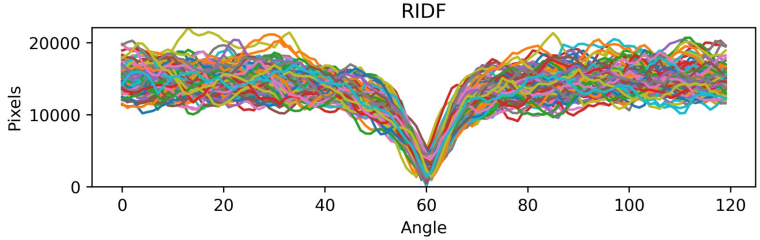
Navigation stats: RMSD error: 46.46; RMSD/dist: 0.116; TD: 16400; p90: 10; p50: 4; complete: 0

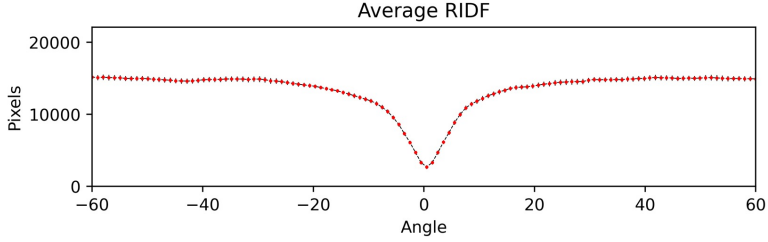

Index: BLUR: 1.0; LEVELS: 32; TRIAL: 6
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
7.5
5.0
2.5
0.0
TD
15000
10000
5000
Sensor regions





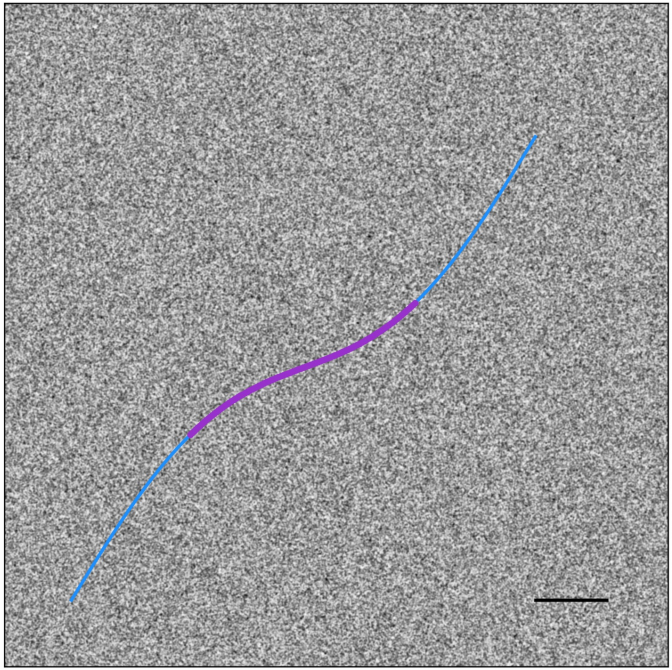


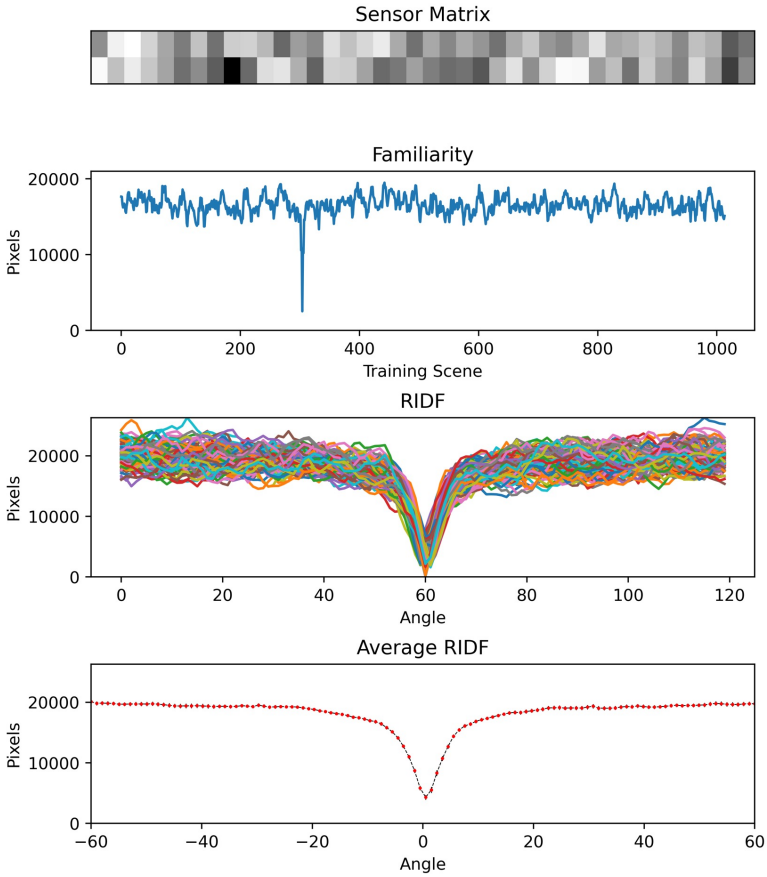




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

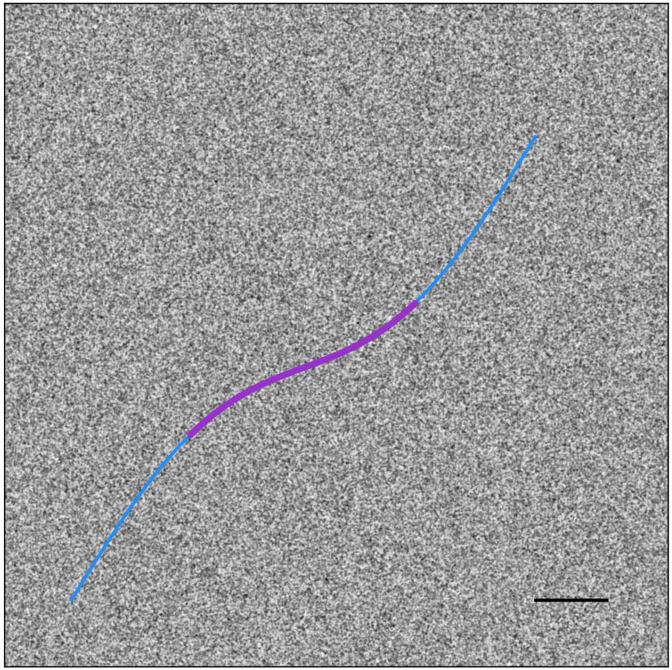
Navigation stats: RMSD error: 48.39; RMSD/dist: 0.121; TD: 9226; p90: 16; p50: 8; complete: 0

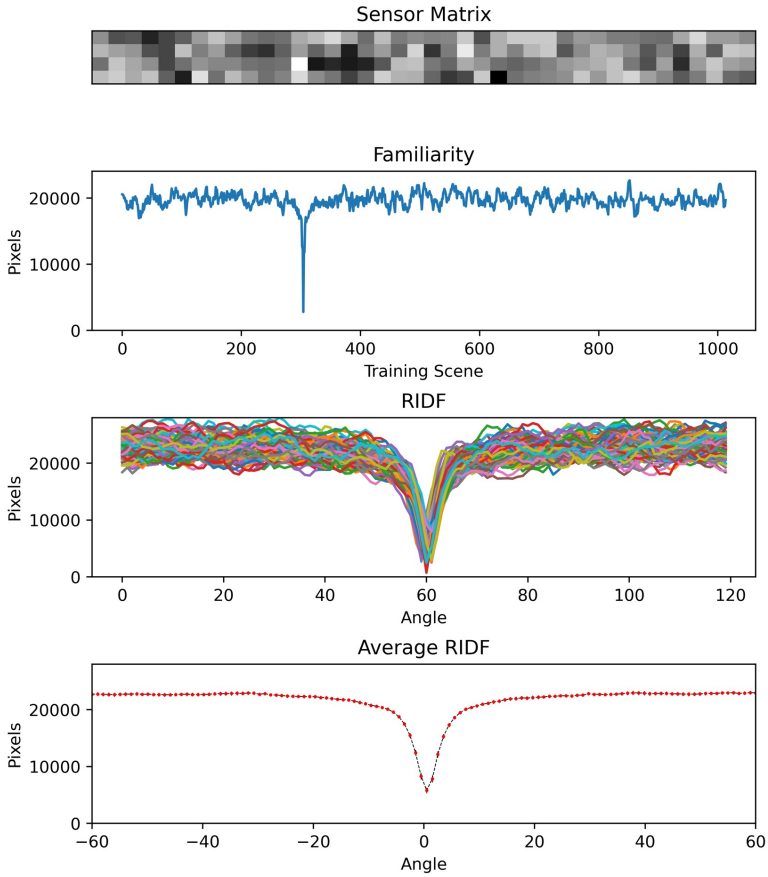




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

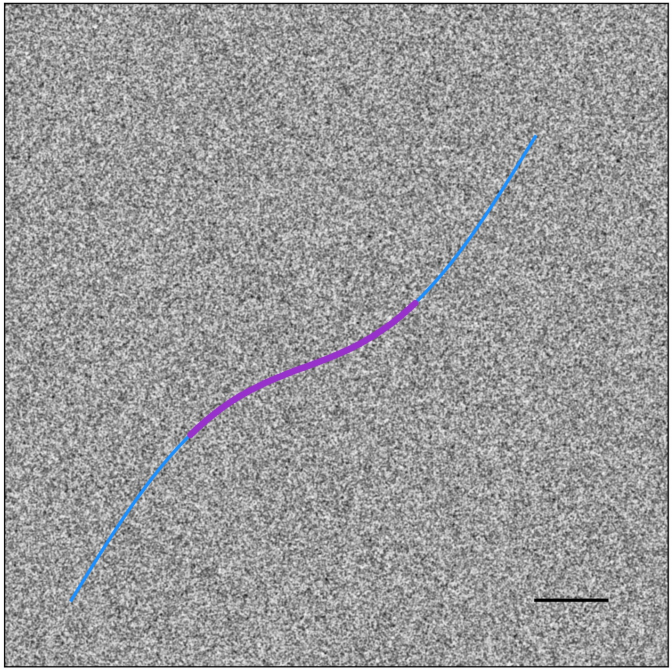
Navigation stats: RMSD error: 45.60; RMSD/dist: 0.114; TD: 12132; p90: 12; p50: 6; complete: 0

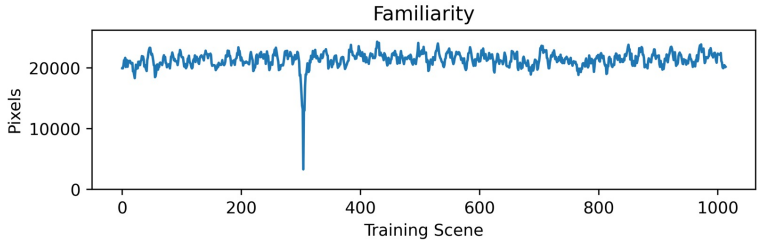


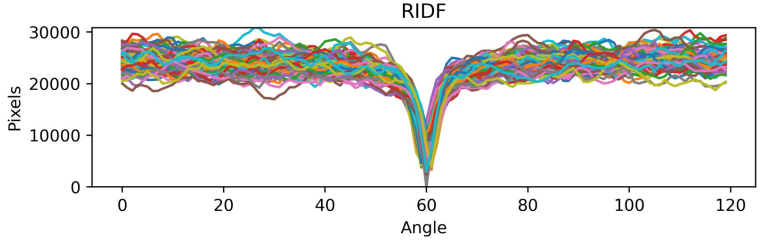


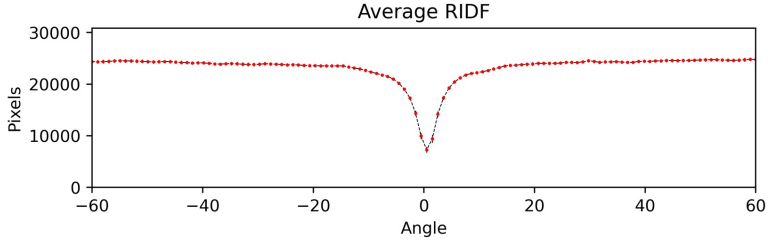
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 41.46; RMSD/dist: 0.104; TD: 14019; p90: 10; p50: 4; complete: 0



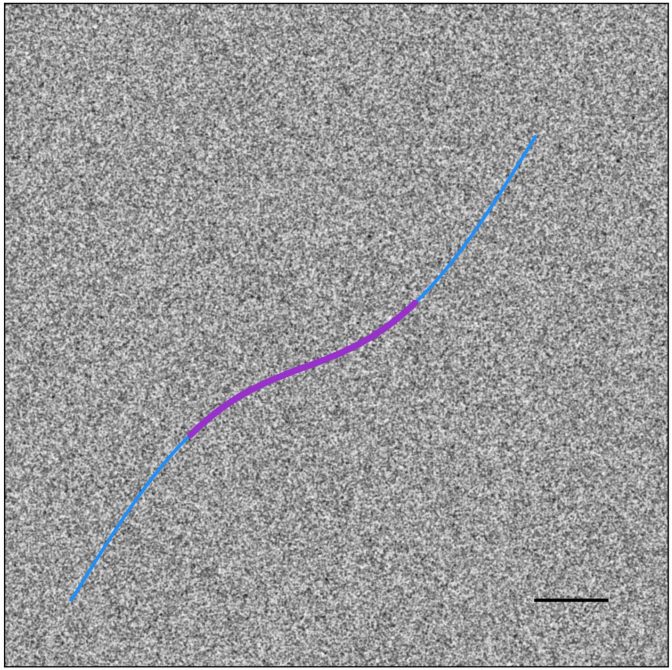


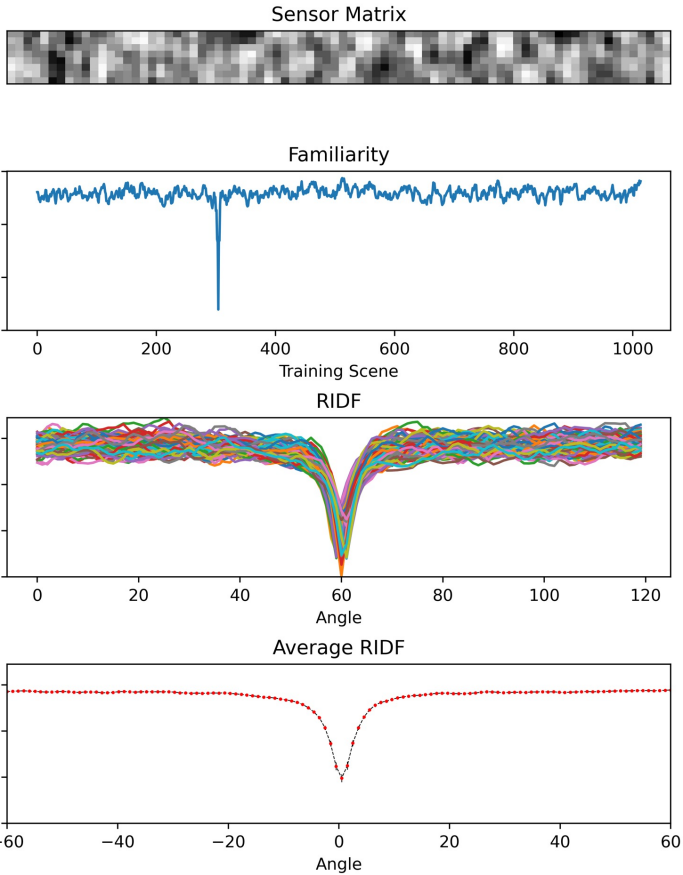




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

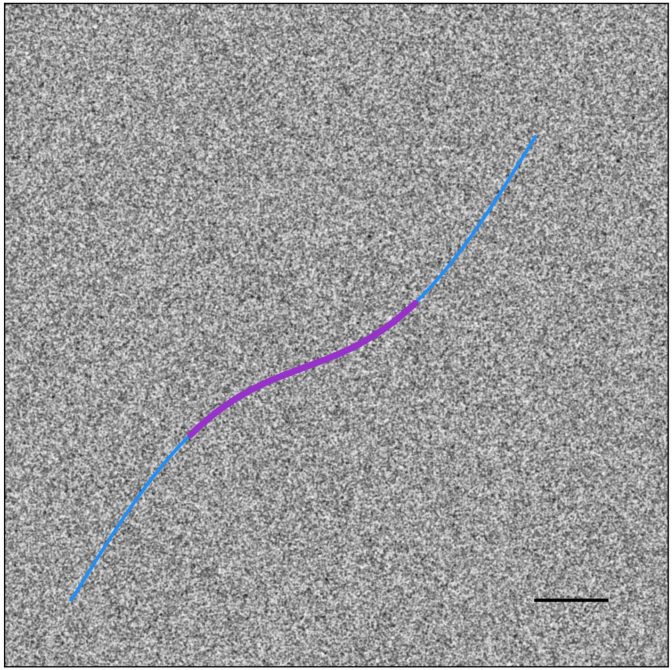
Navigation stats: RMSD error: 47.48; RMSD/dist: 0.119; TD: 14186; p90: 10; p50: 4; complete: 0

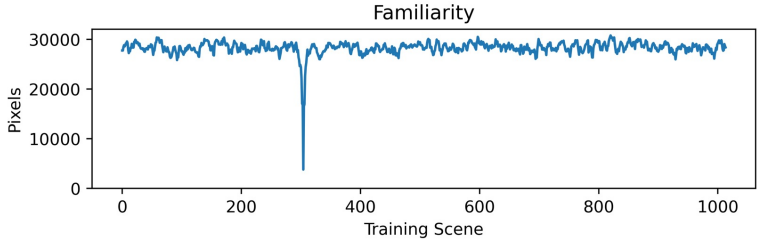


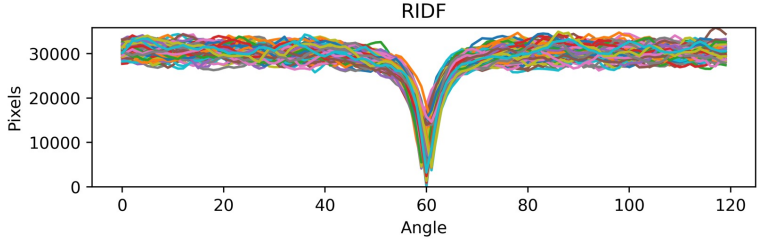


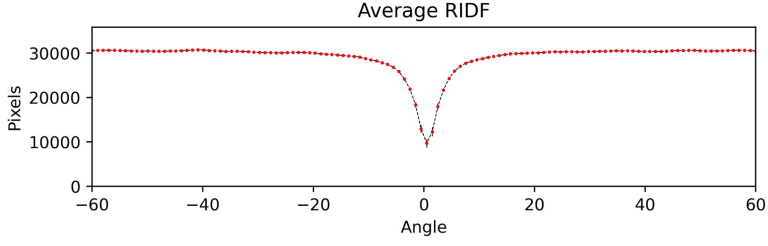
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 54.36; RMSD/dist: 0.136; TD: 16051; p90: 10; p50: 4; complete: 0



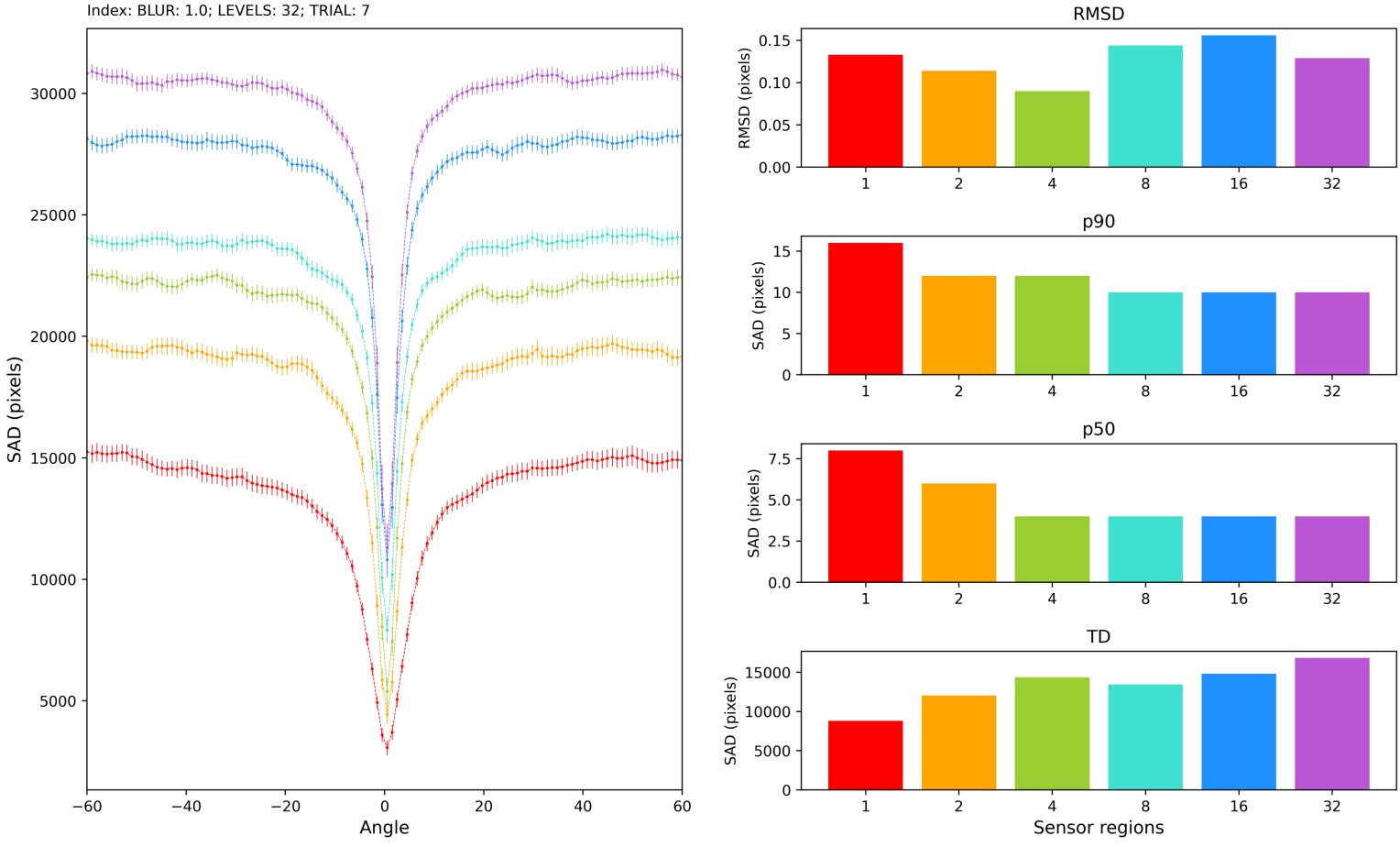


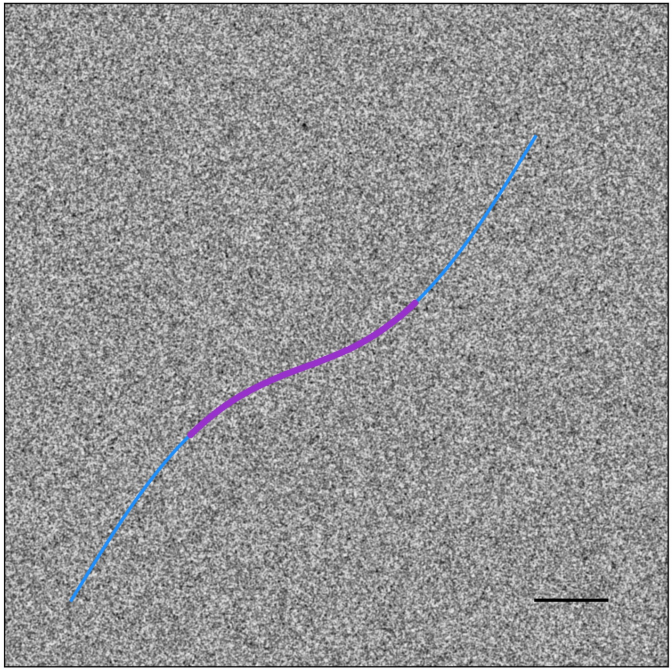


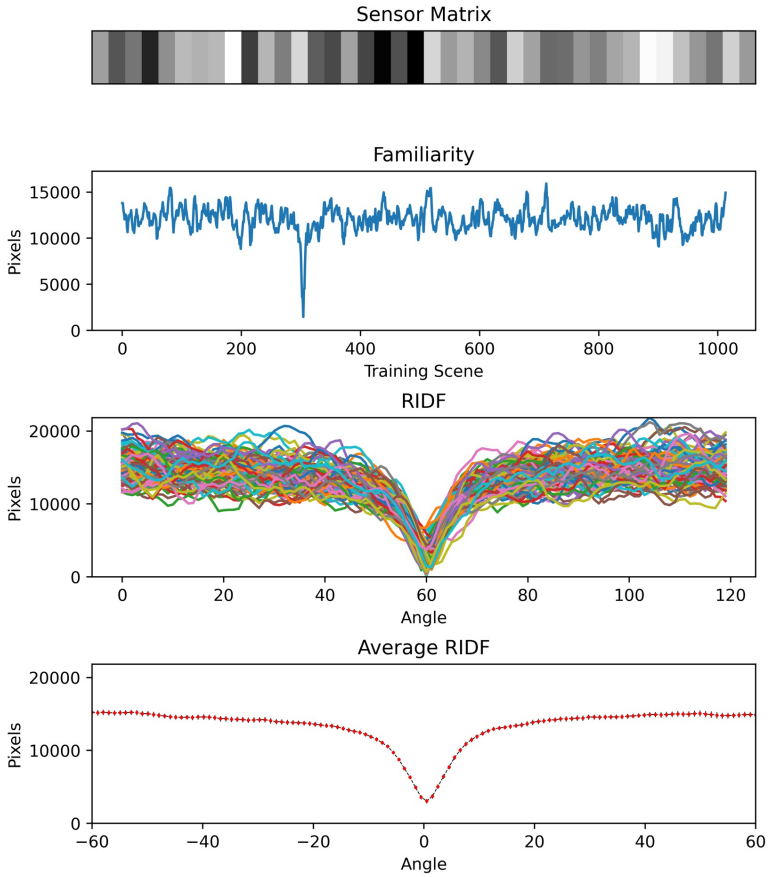


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 39.70; RMSD/dist: 0.099; TD: 18331; p90: 10; p50: 4; complete: 0

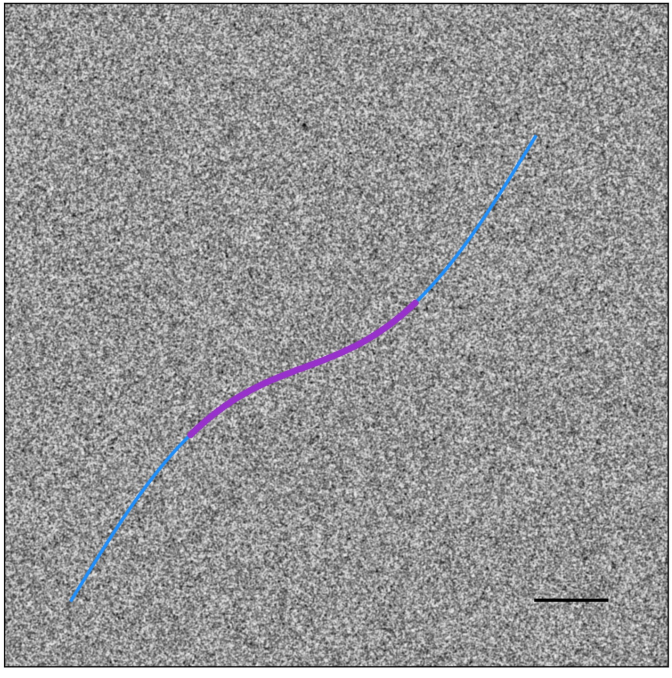

Index: BLUR: 1.0; LEVELS: 32; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

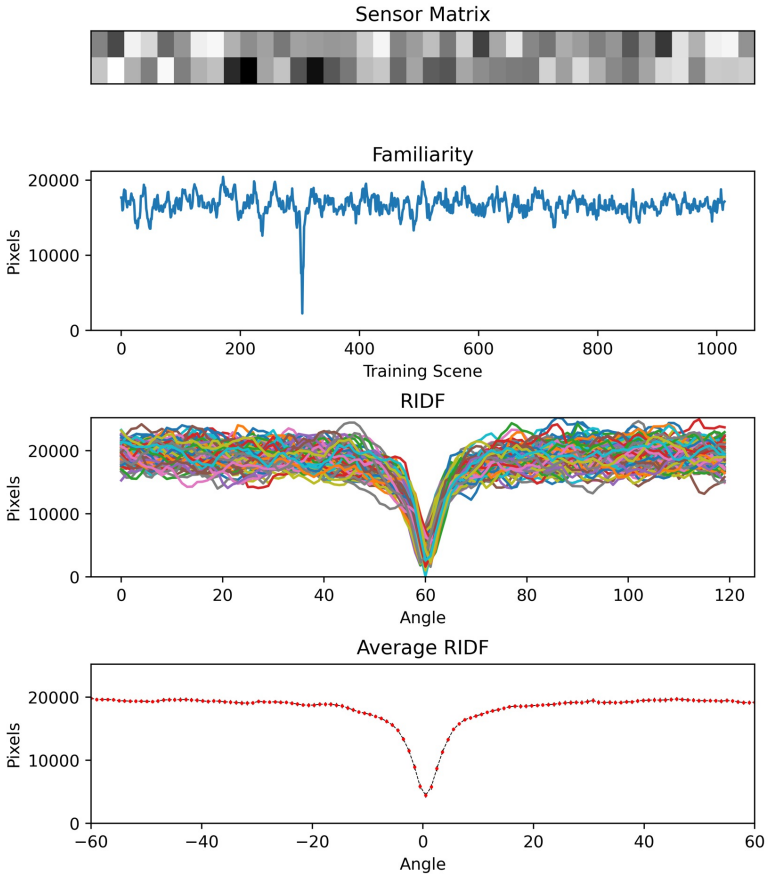




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

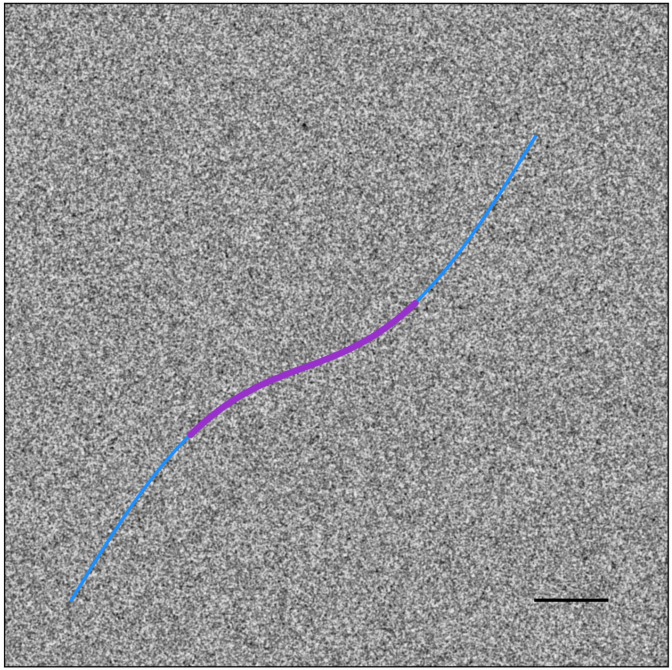
Navigation stats: RMSD error: 53.27; RMSD/dist: 0.133; TD: 8805; p90: 16; p50: 8; complete: 0

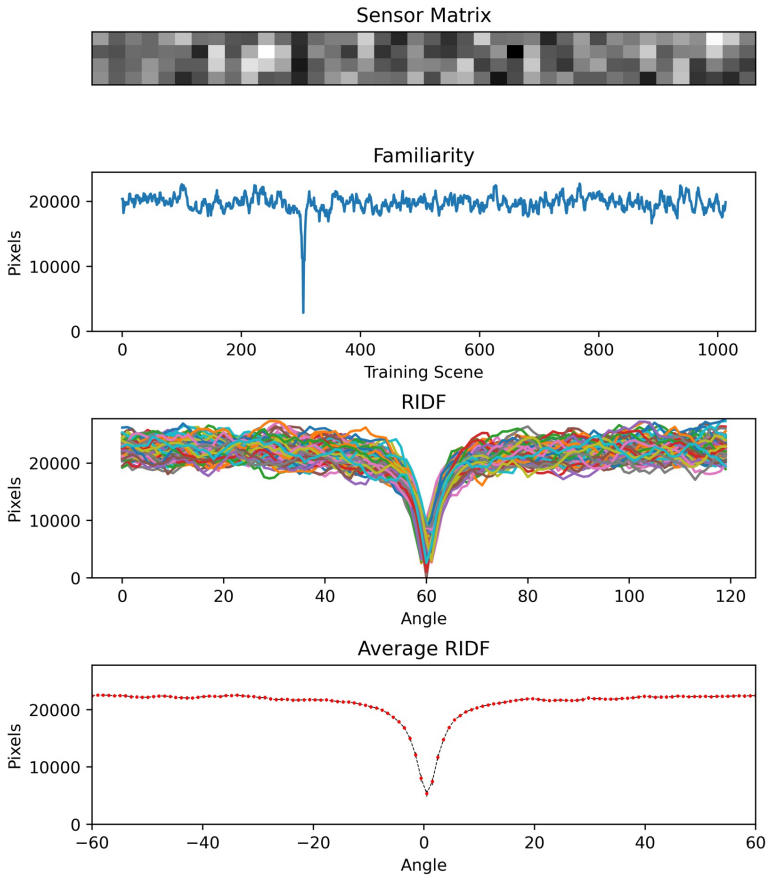




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

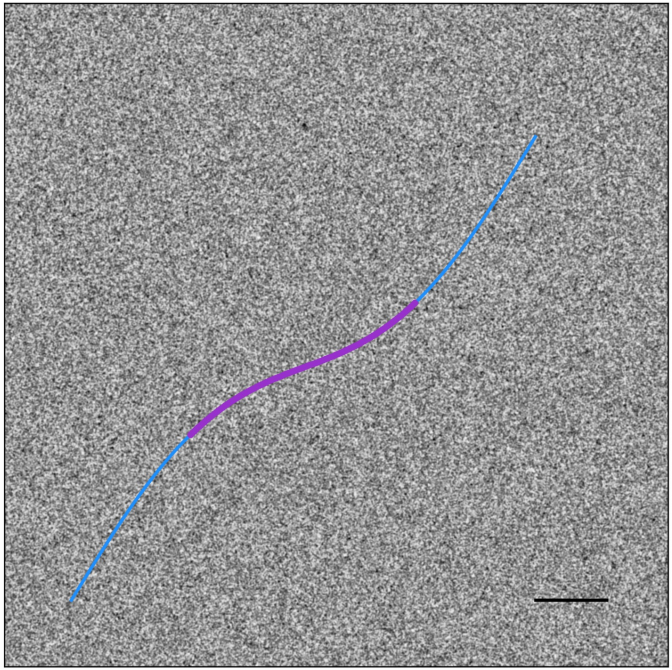
Navigation stats: RMSD error: 45.43; RMSD/dist: 0.114; TD: 12025; p90: 12; p50: 6; complete: 0

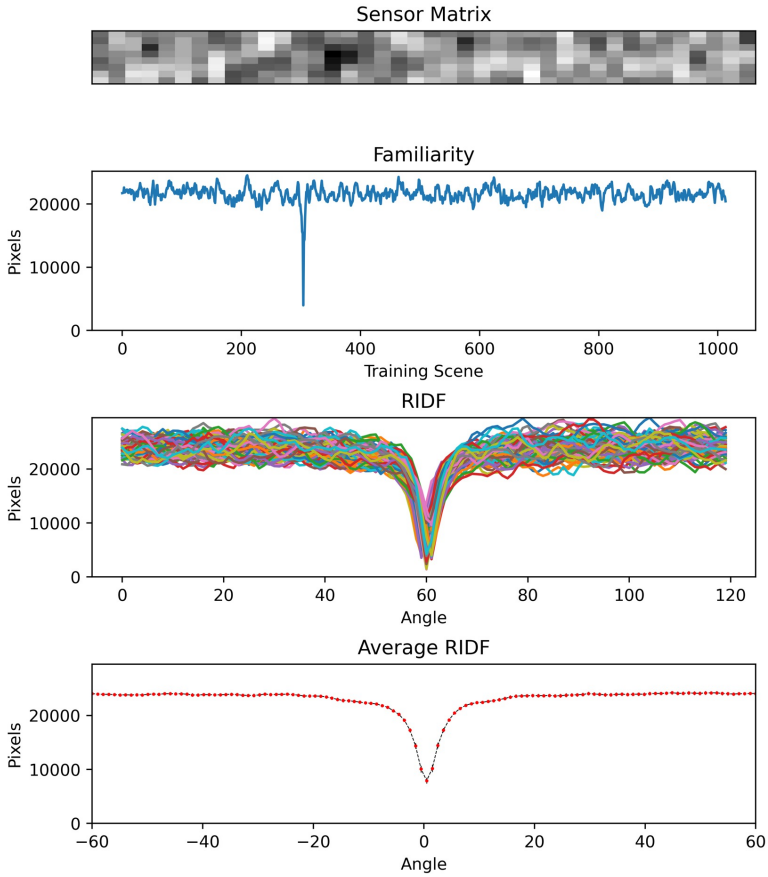




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

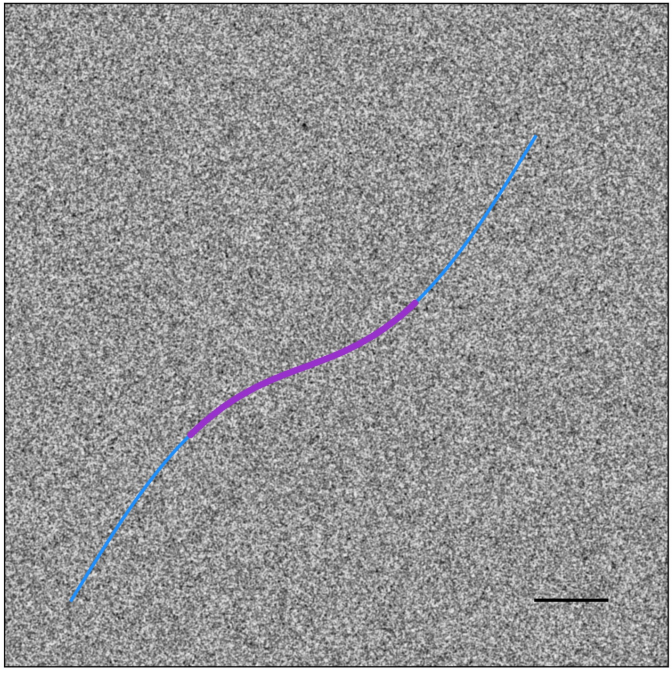
Navigation stats: RMSD error: 36.00; RMSD/dist: 0.090; TD: 14344; p90: 12; p50: 4; complete: 0

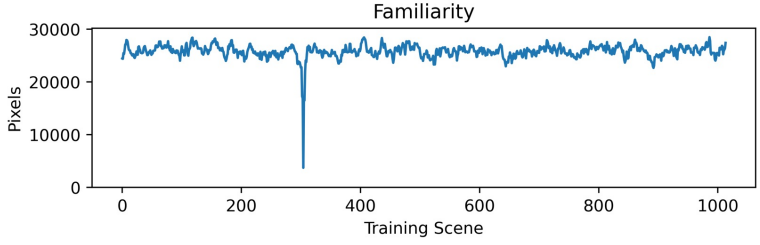


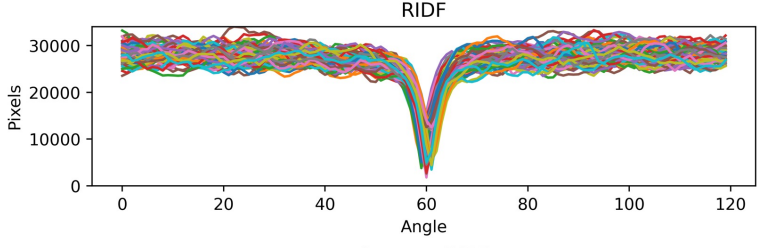


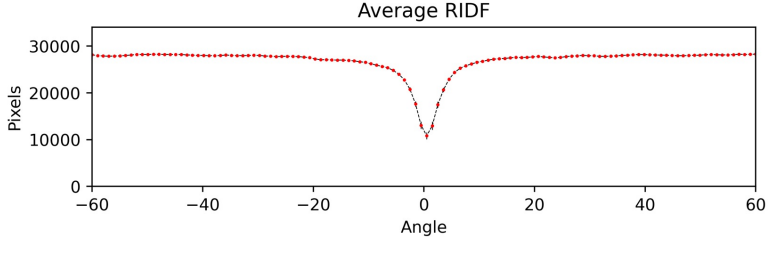
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 57.67; RMSD/dist: 0.144; TD: 13440; p90: 10; p50: 4; complete: 0



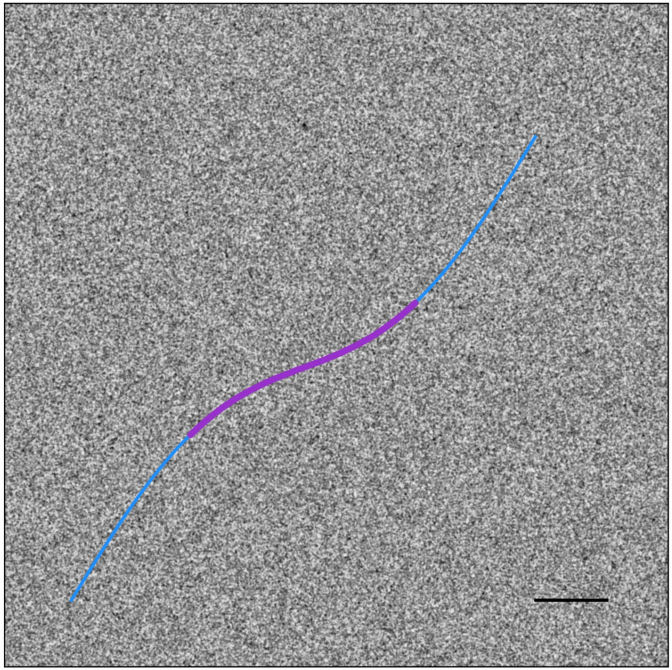


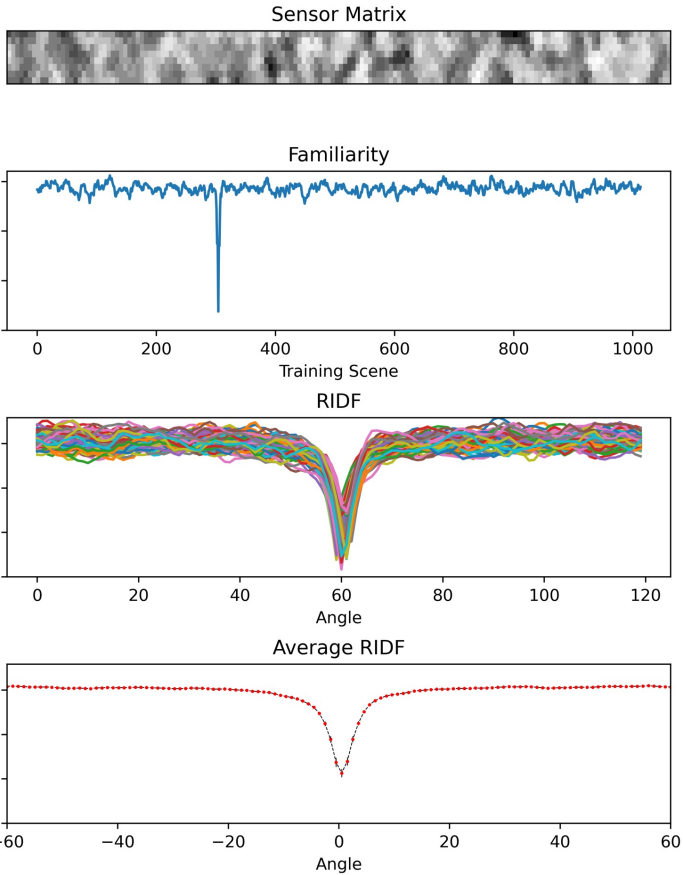




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

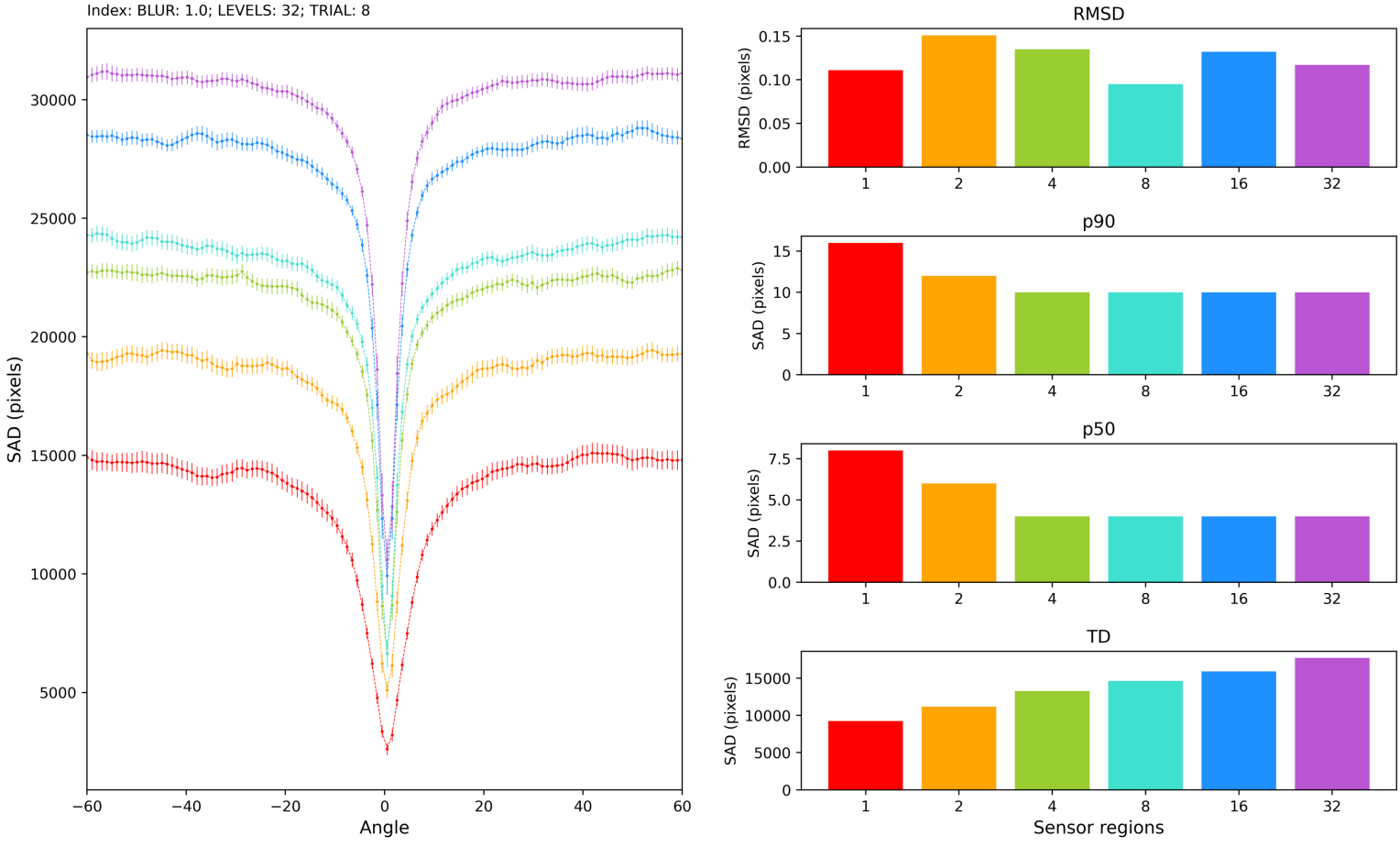
Navigation stats: RMSD error: 62.40; RMSD/dist: 0.156; TD: 14820; p90: 10; p50: 4; complete: 0

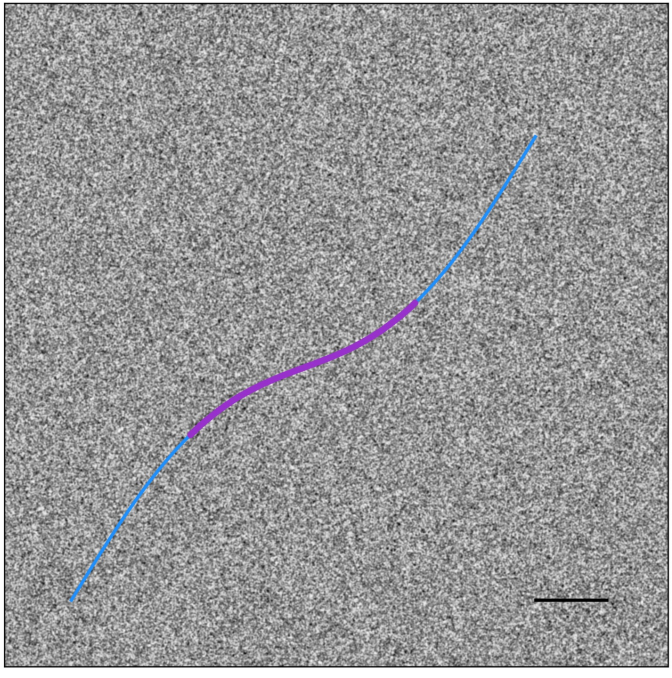


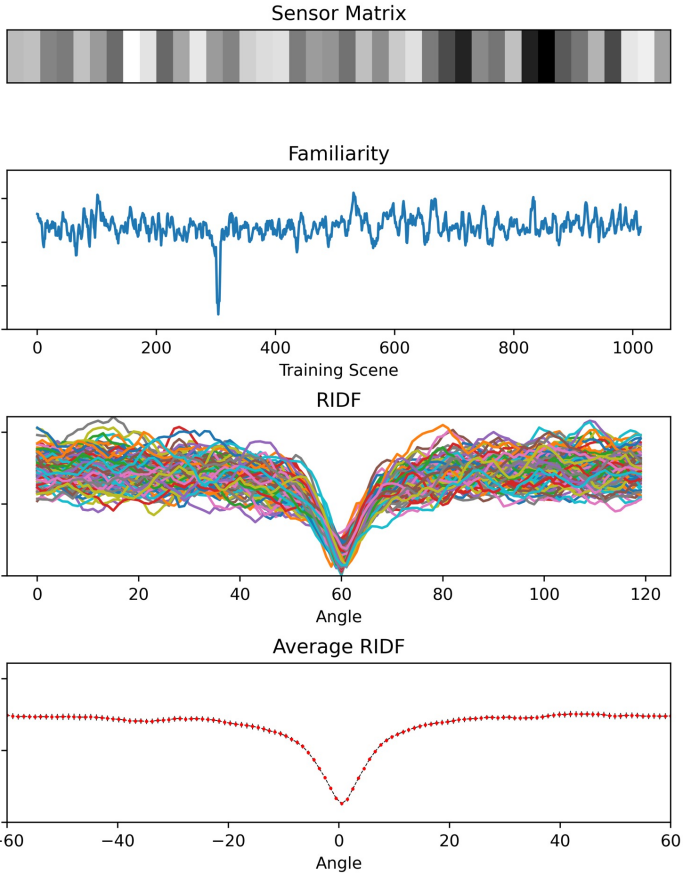


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 51.76; RMSD/dist: 0.129; TD: 16820; p90: 10; p50: 4; complete: 0

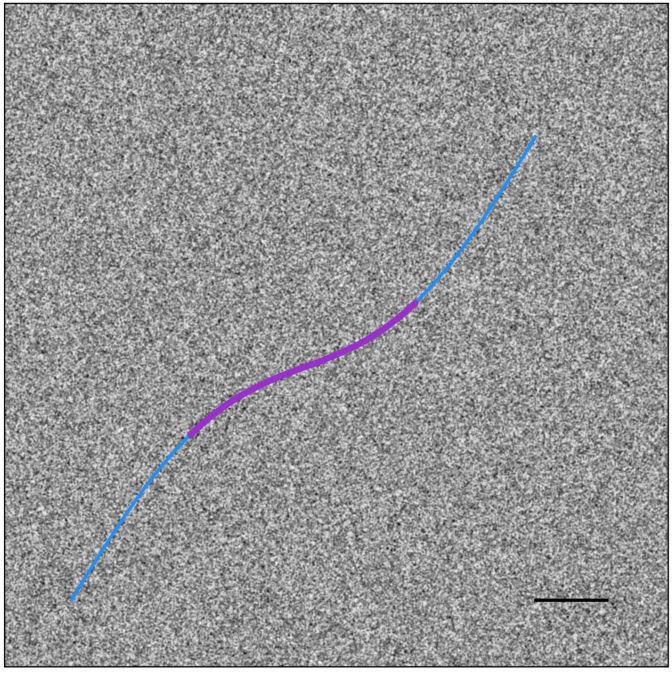

Index: BLUR: 1.0; LEVELS: 32; TRIAL: 8
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

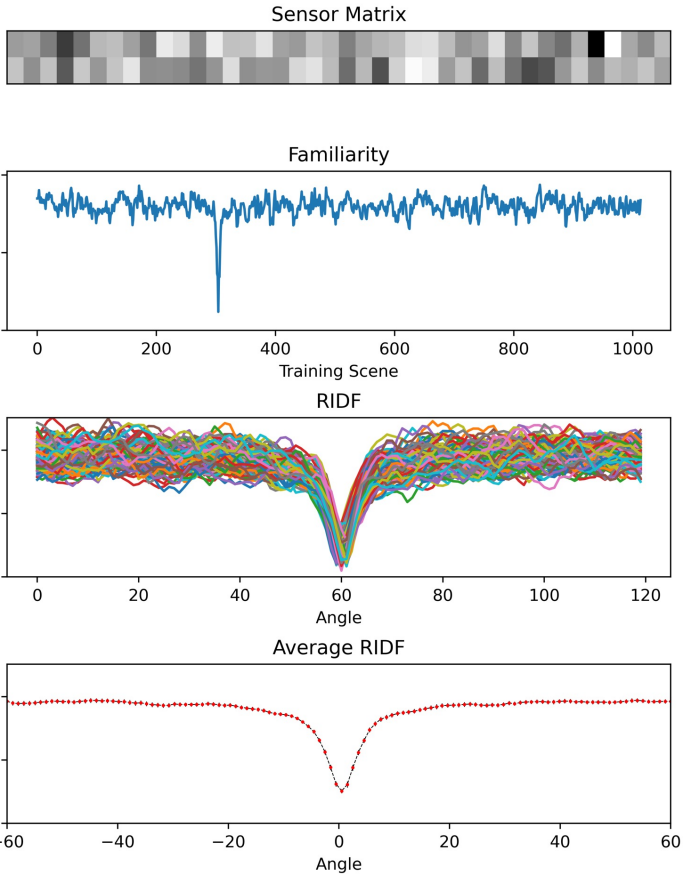




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

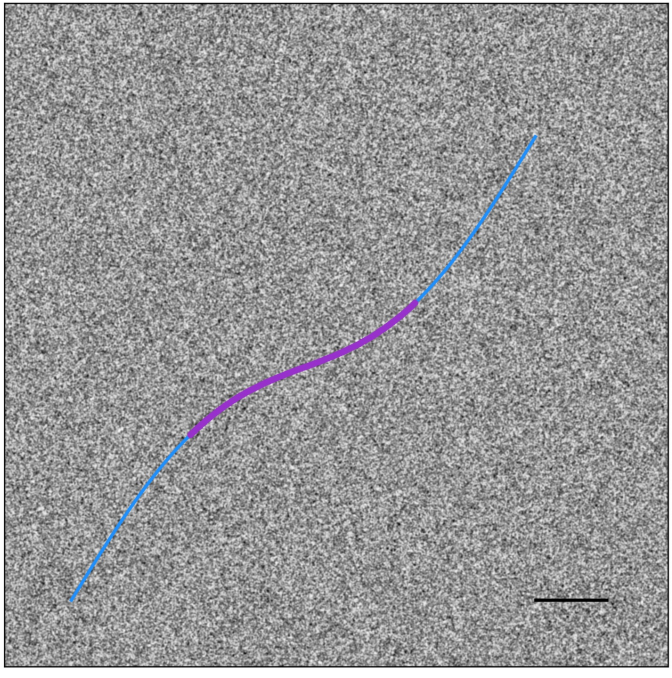
Navigation stats: RMSD error: 44.26; RMSD/dist: 0.111; TD: 9244; p90: 16; p50: 8; complete: 0

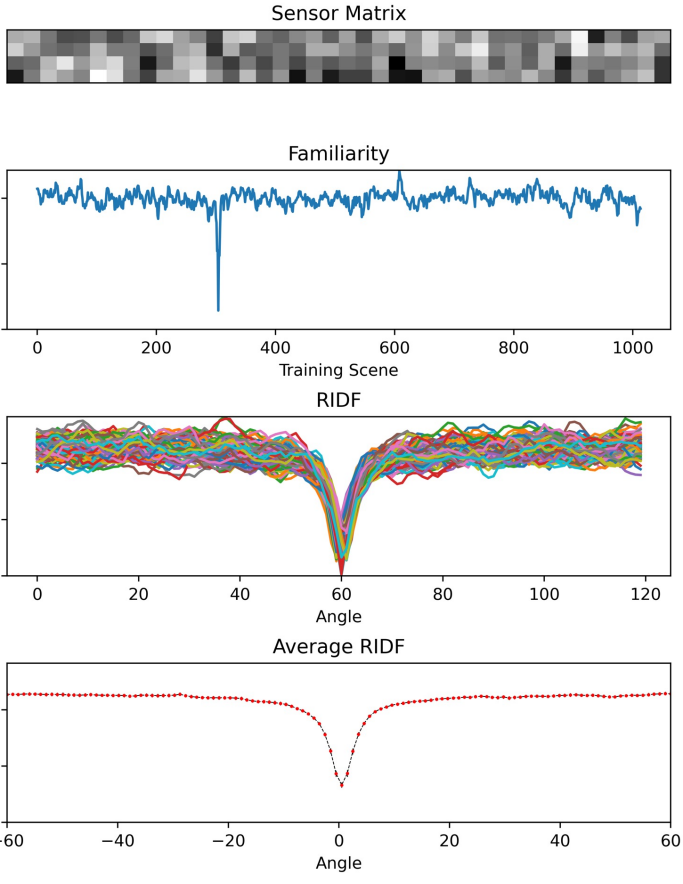




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

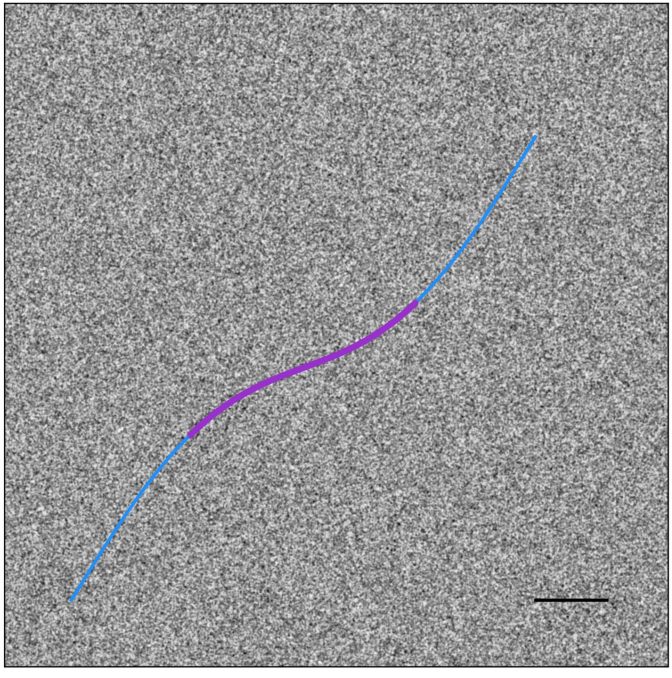
Navigation stats: RMSD error: 60.39; RMSD/dist: 0.151; TD: 11158; p90: 12; p50: 6; complete: 0

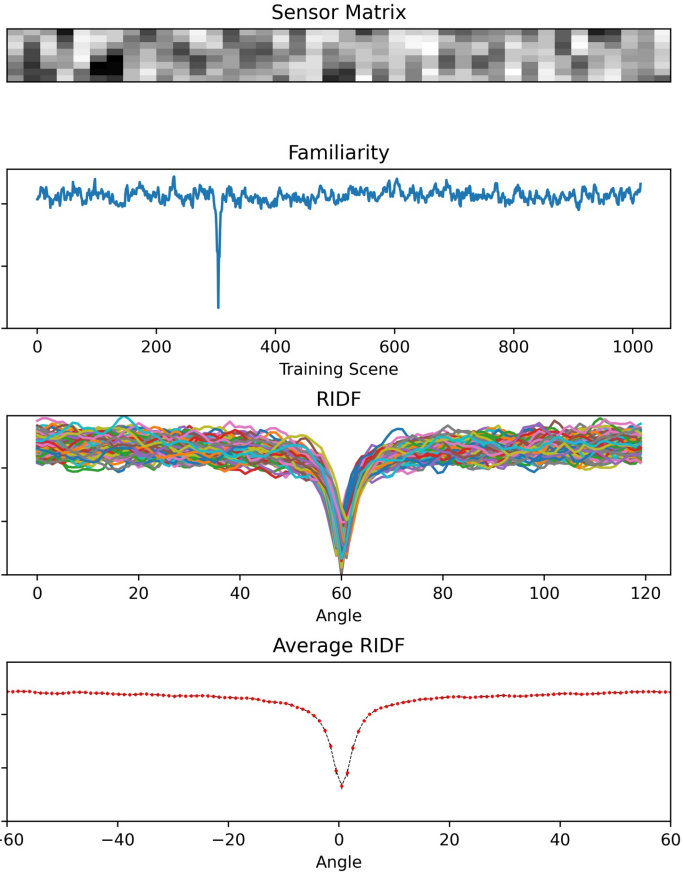




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

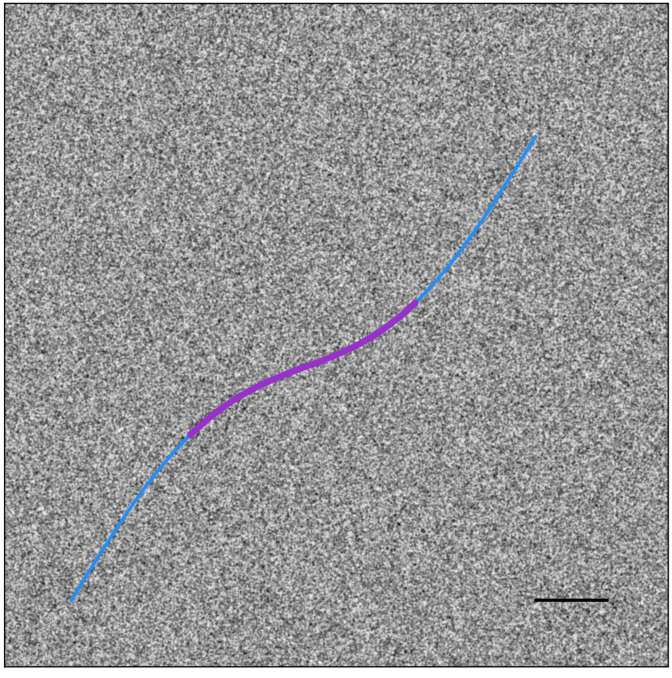
Navigation stats: RMSD error: 53.92; RMSD/dist: 0.135; TD: 13269; p90: 10; p50: 4; complete: 0

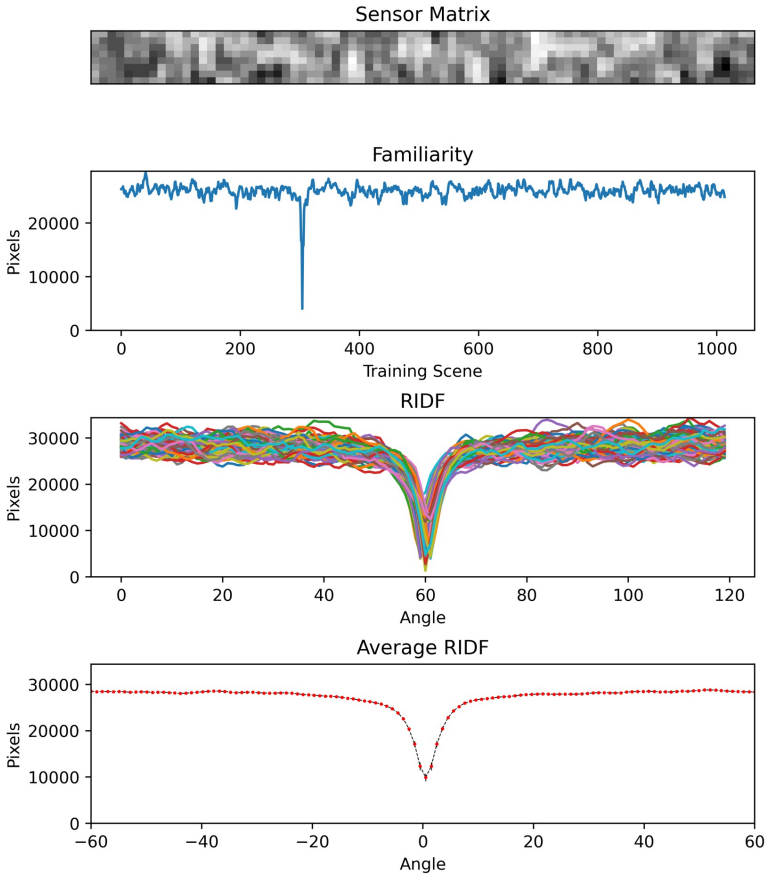




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

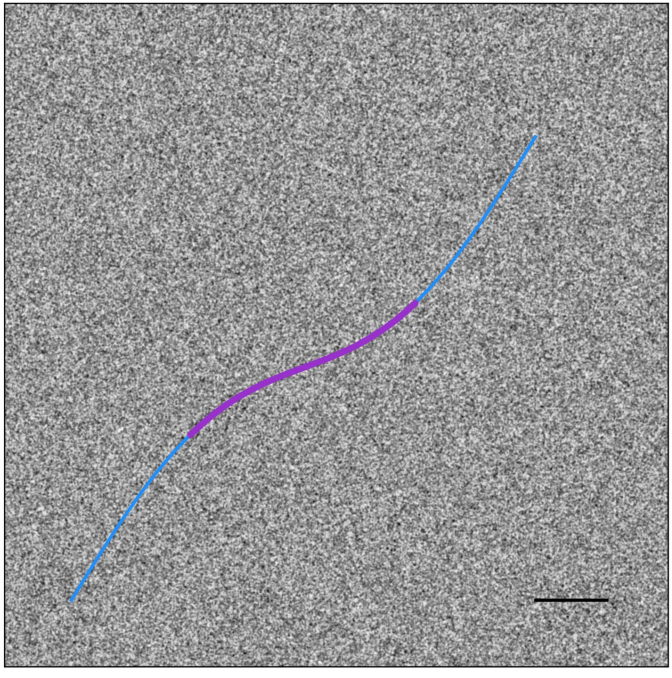
Navigation stats: RMSD error: 37.86; RMSD/dist: 0.095; TD: 14617; p90: 10; p50: 4; complete: 0

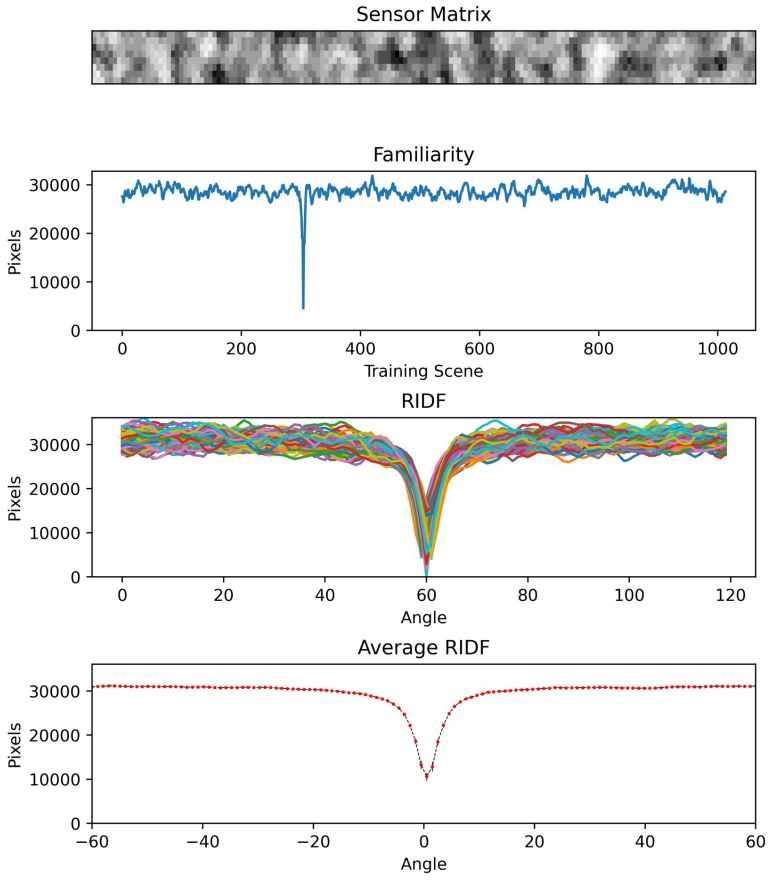




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

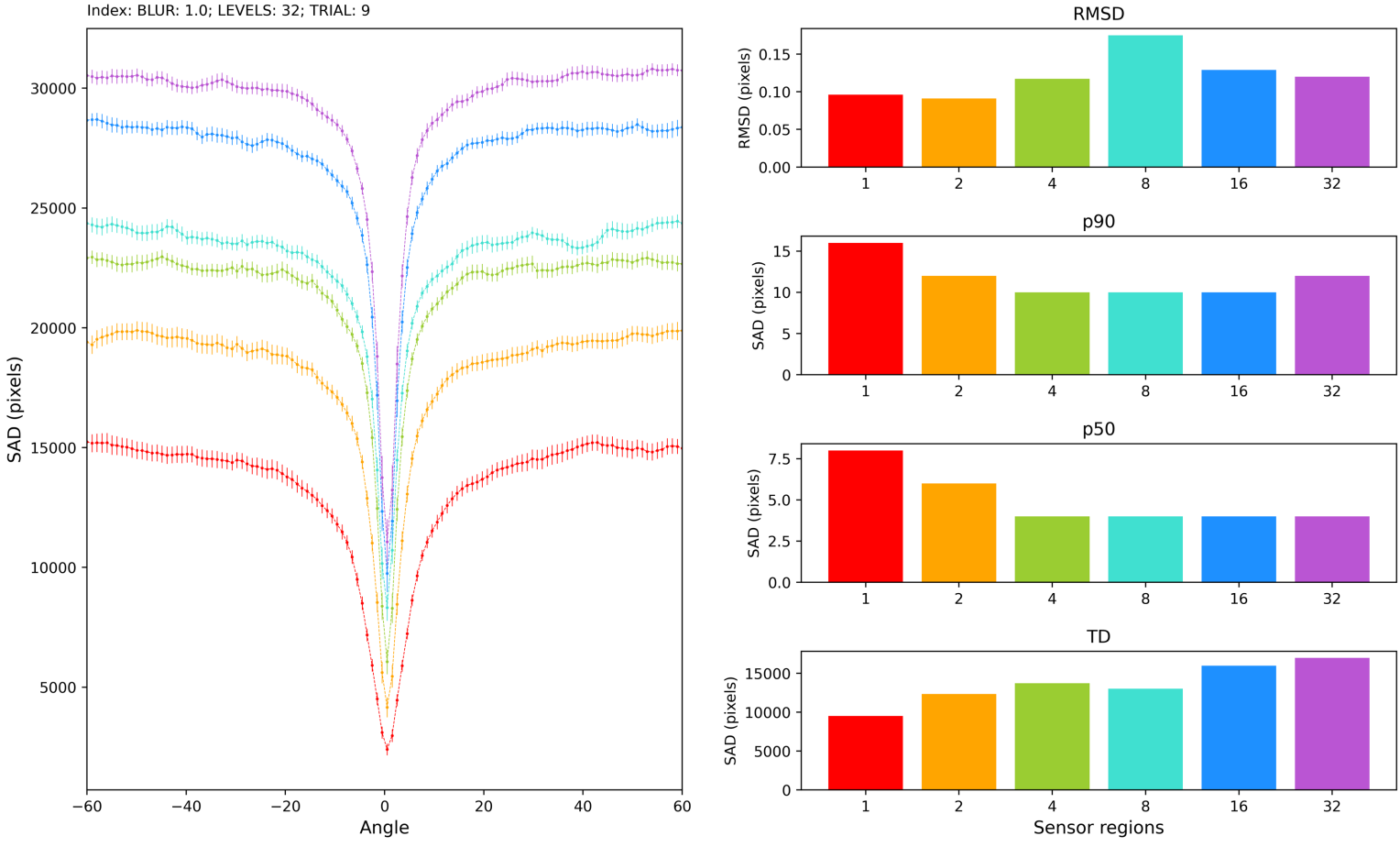
Navigation stats: RMSD error: 52.62; RMSD/dist: 0.132; TD: 15888; p90: 10; p50: 4; complete: 0

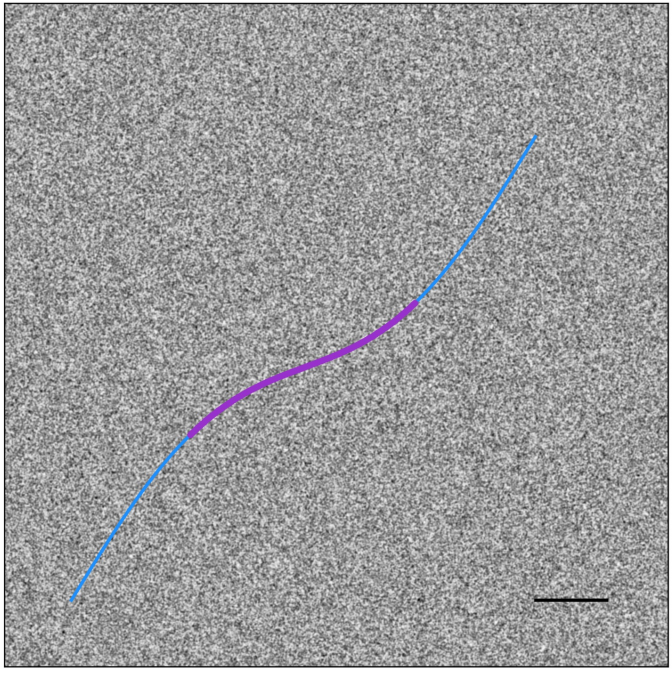


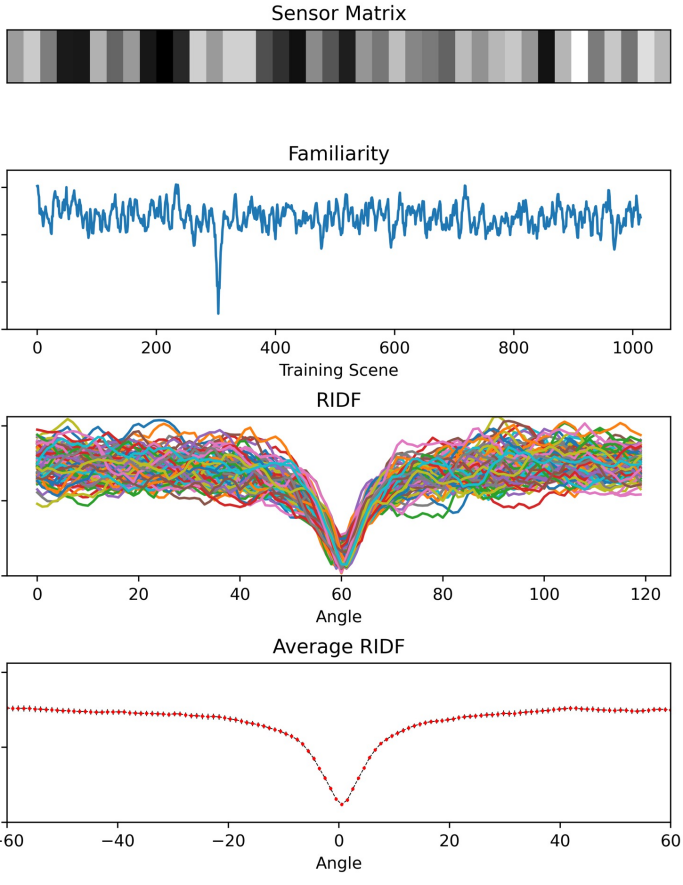


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 46.99; RMSD/dist: 0.117; TD: 17702; p90: 10; p50: 4; complete: 0

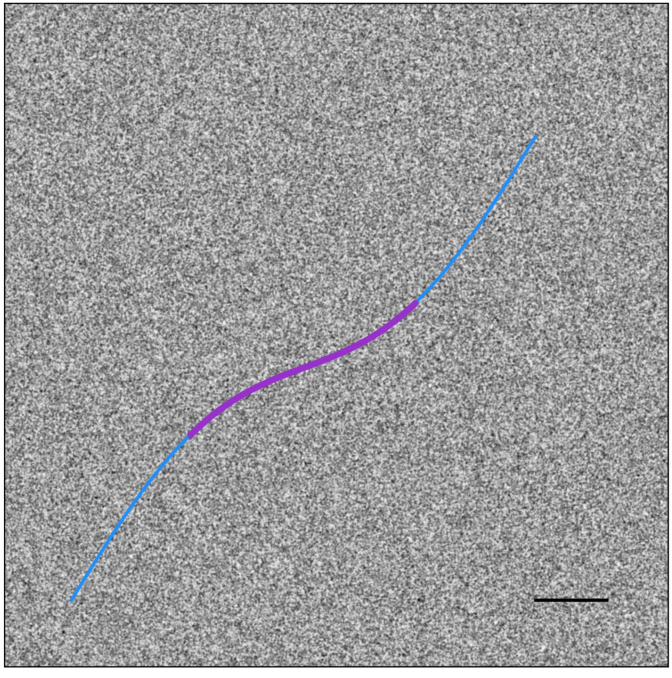

Index: BLUR: 1.0; LEVELS: 32; TRIAL: 9
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

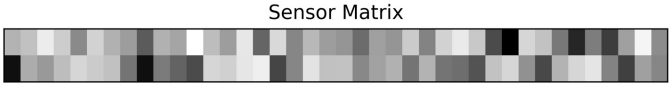


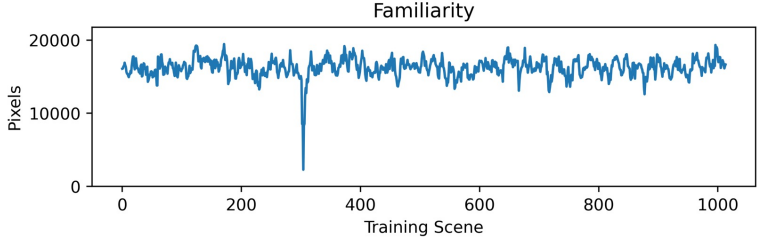


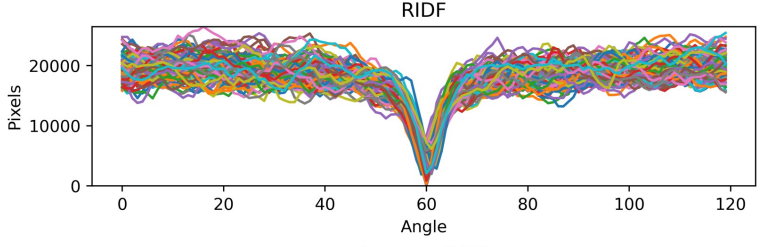
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

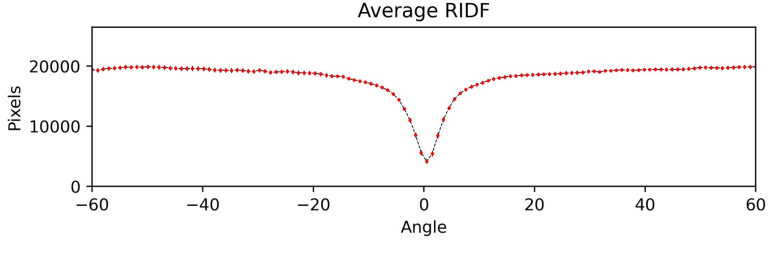
Navigation stats: RMSD error: 38.58; RMSD/dist: 0.096; TD: 9520; p90: 16; p50: 8; complete: 0





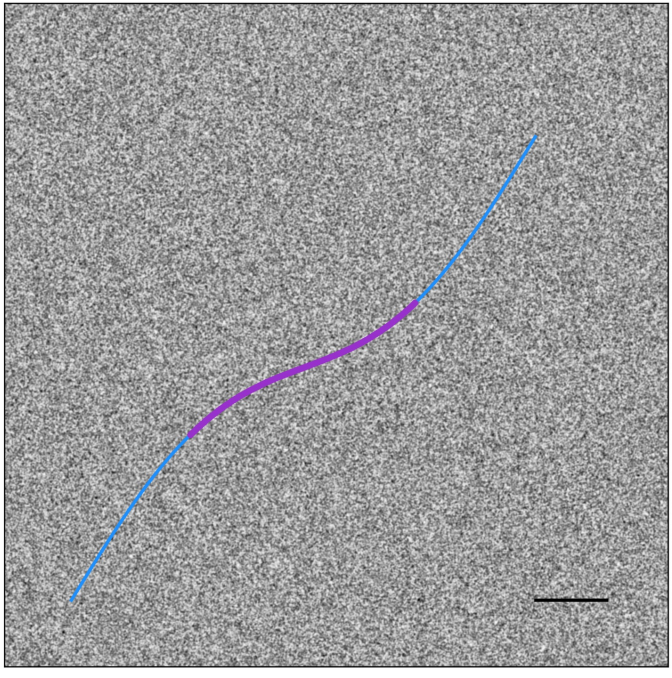


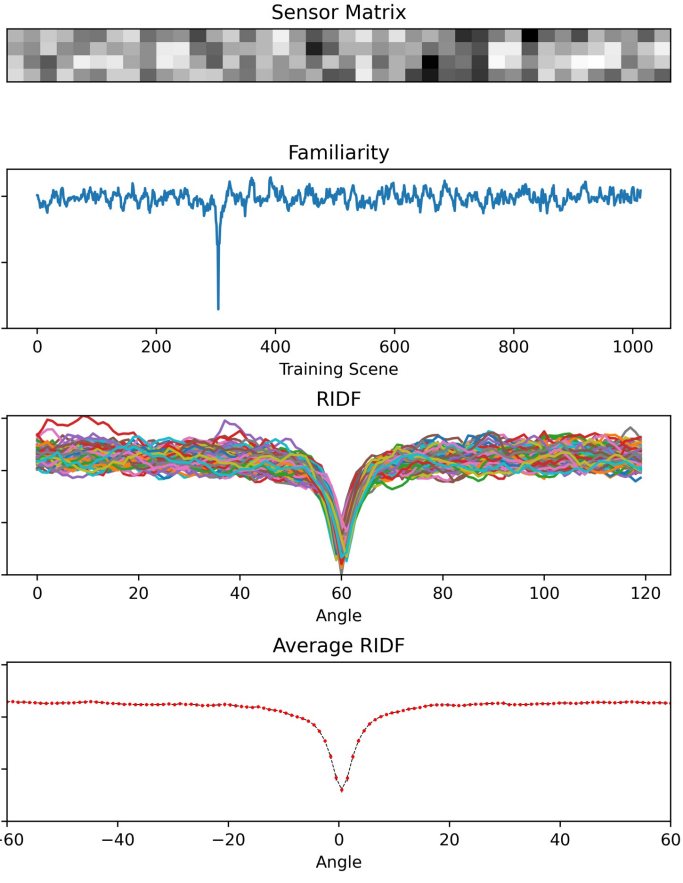




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

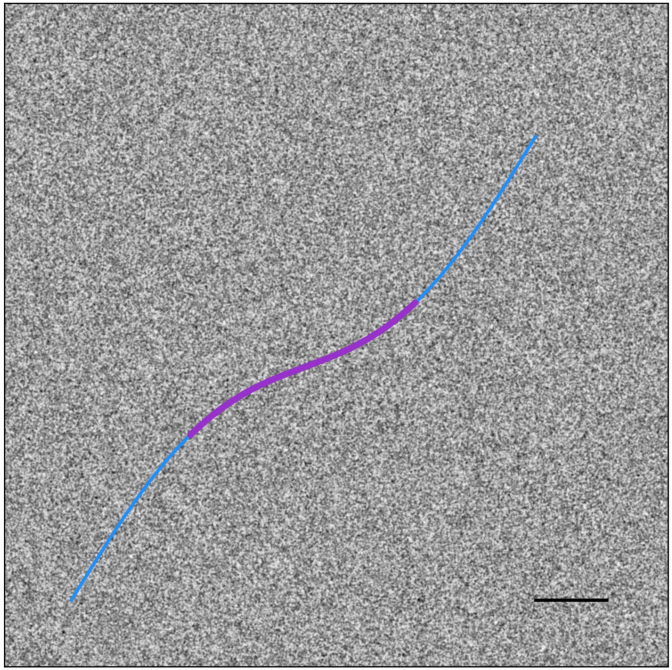
Navigation stats: RMSD error: 36.36; RMSD/dist: 0.091; TD: 12356; p90: 12; p50: 6; complete: 0

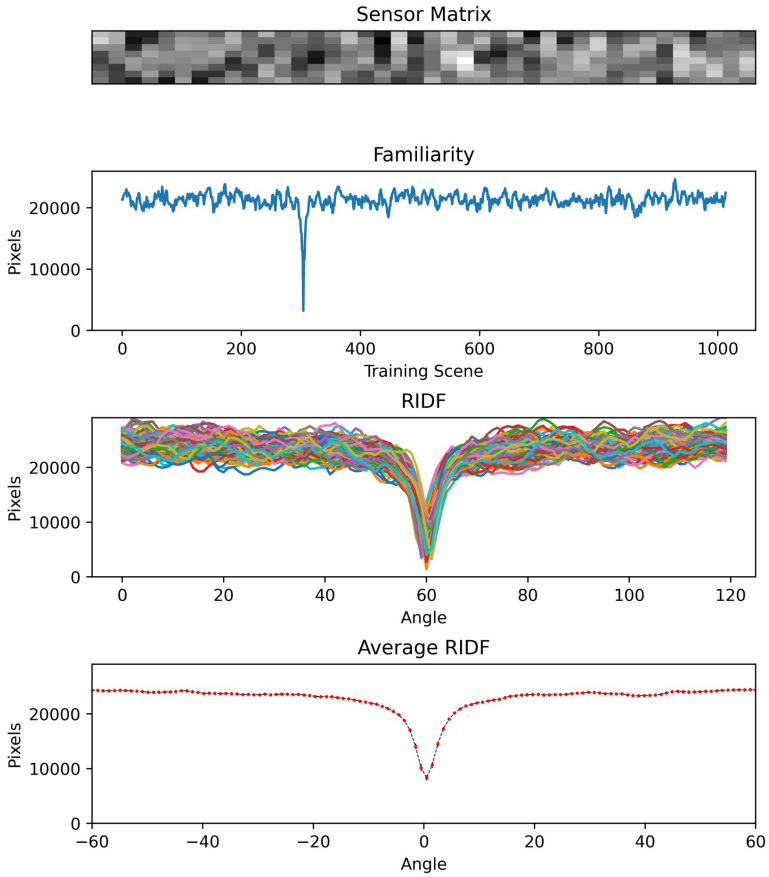




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

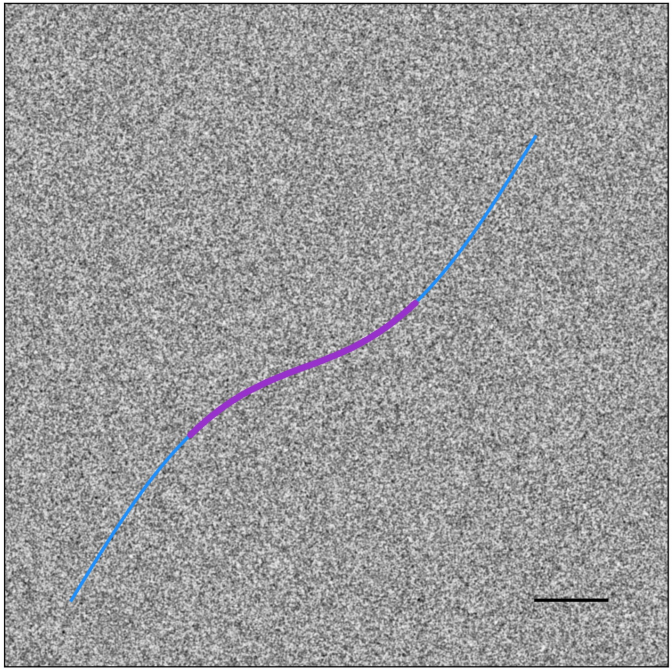
Navigation stats: RMSD error: 46.96; RMSD/dist: 0.117; TD: 13739; p90: 10; p50: 4; complete: 0

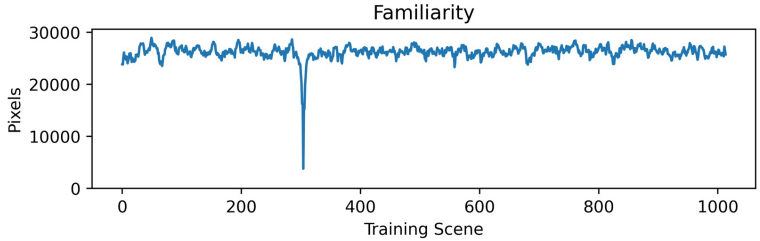


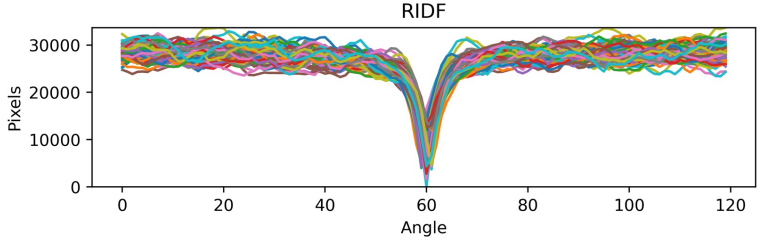


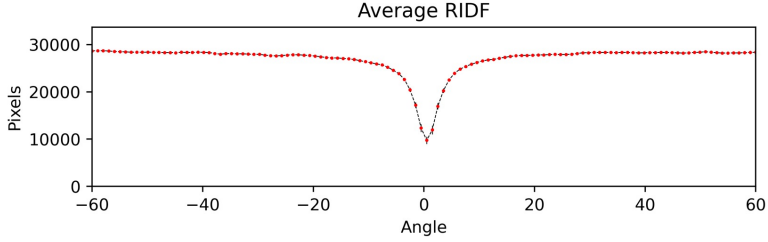
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 69.83; RMSD/dist: 0.175; TD: 13021; p90: 10; p50: 4; complete: 0



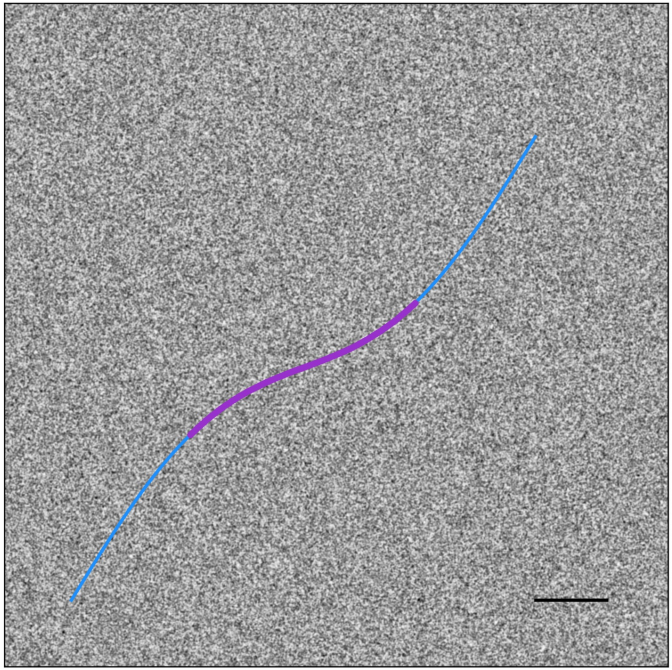


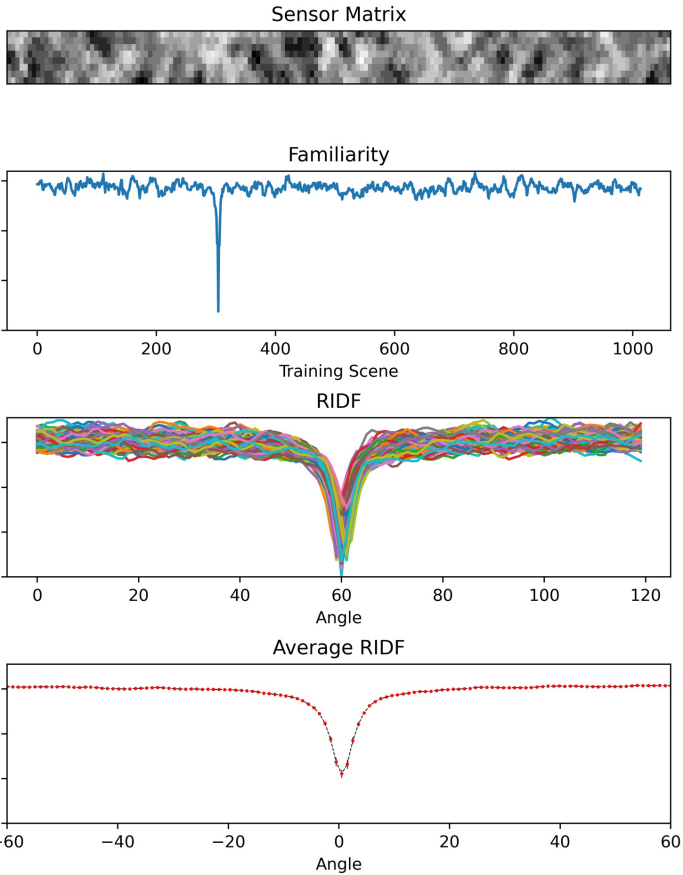




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

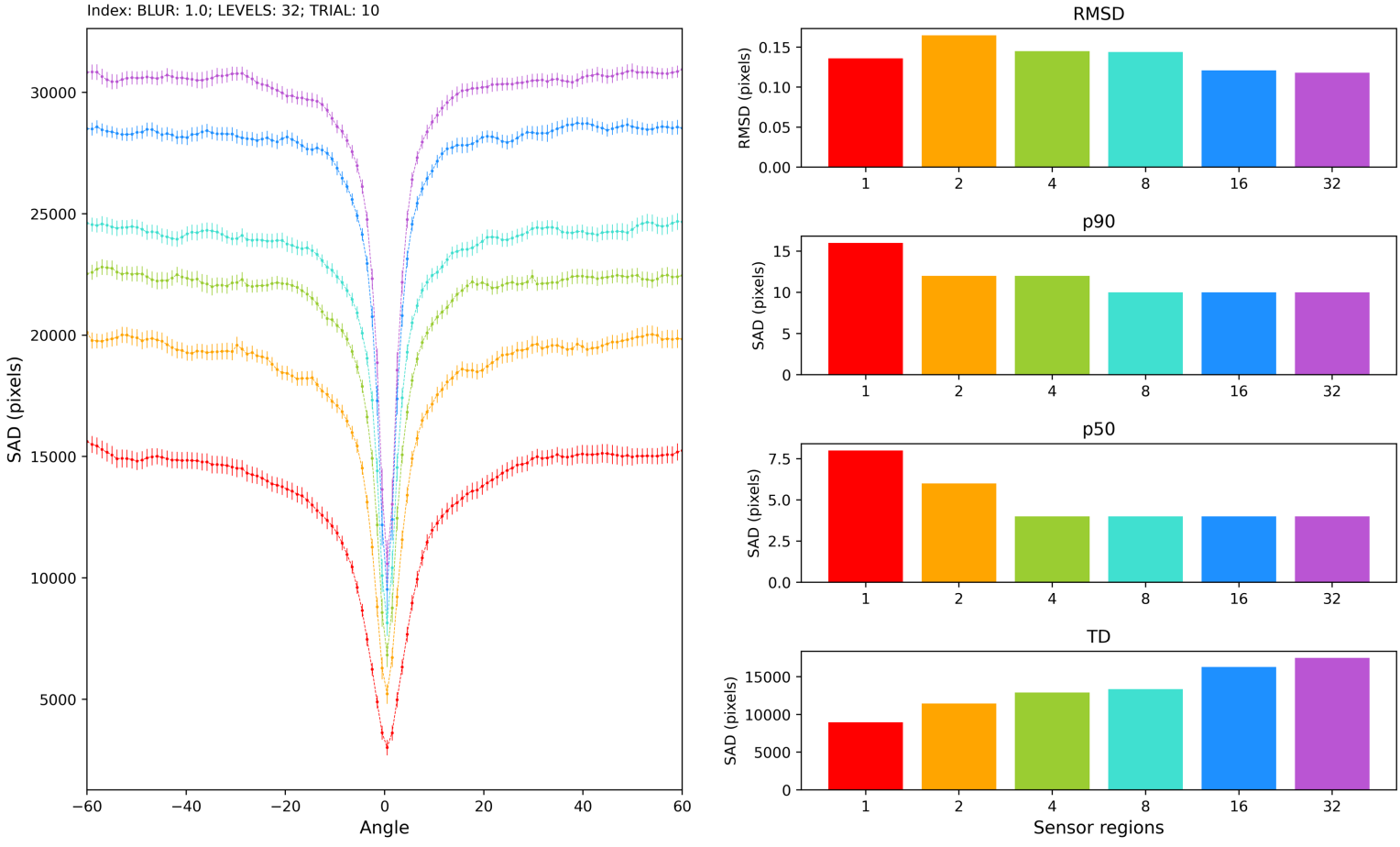
Navigation stats: RMSD error: 51.59; RMSD/dist: 0.129; TD: 16003; p90: 10; p50: 4; complete: 0

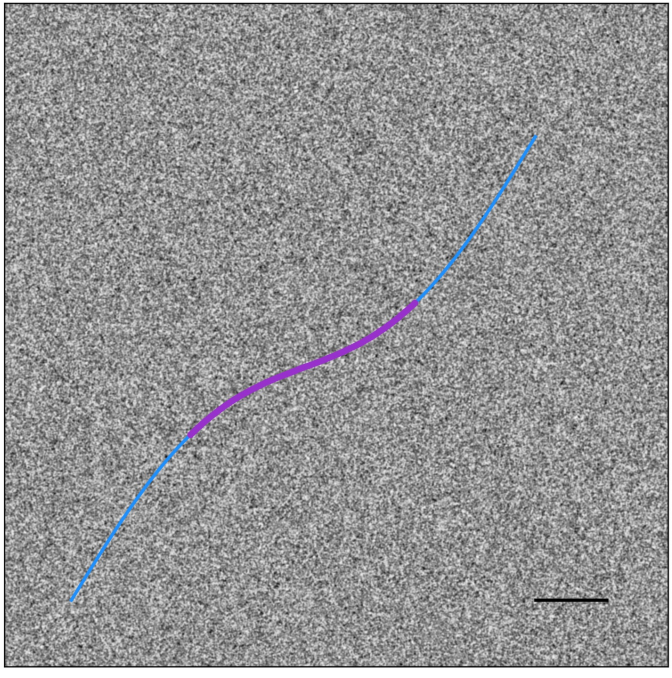


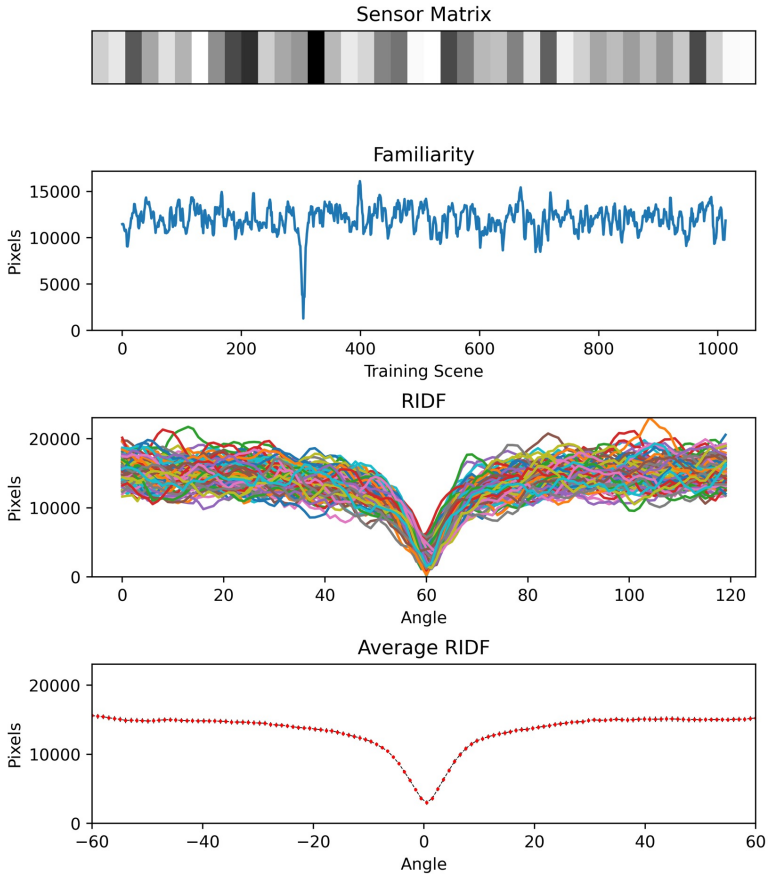


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 48.19; RMSD/dist: 0.120; TD: 16985; p90: 12; p50: 4; complete: 0

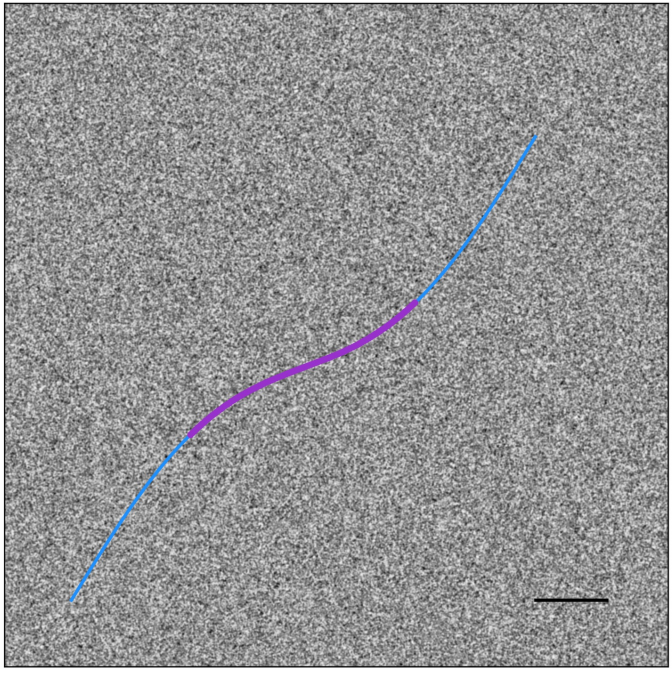

Index: BLUR: 1.0; LEVELS: 32; TRIAL: 10
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
15
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

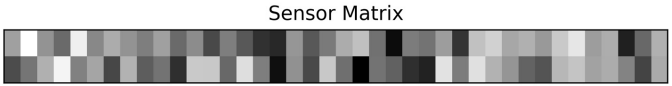


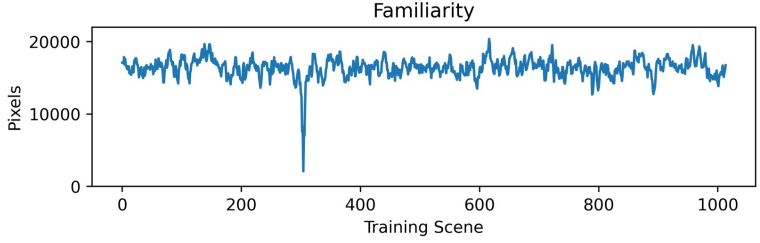


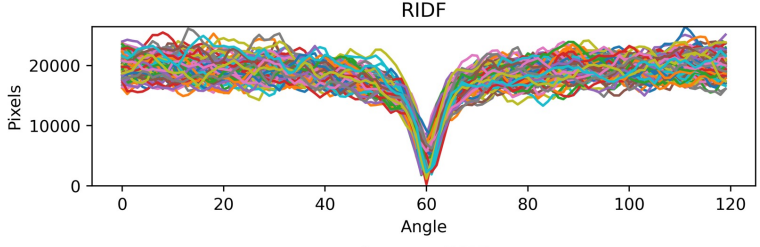
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

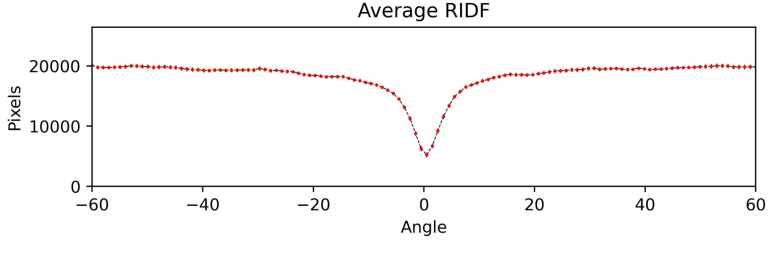
Navigation stats: RMSD error: 54.21; RMSD/dist: 0.136; TD: 8969; p90: 16; p50: 8; complete: 0





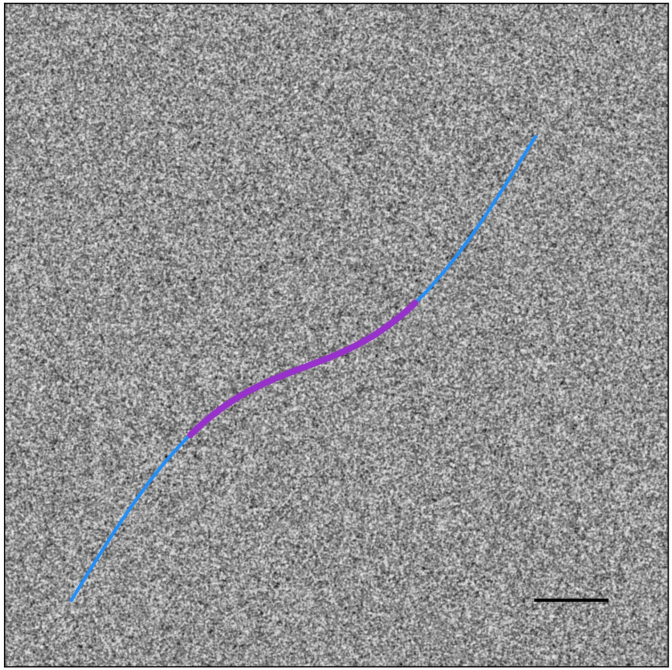


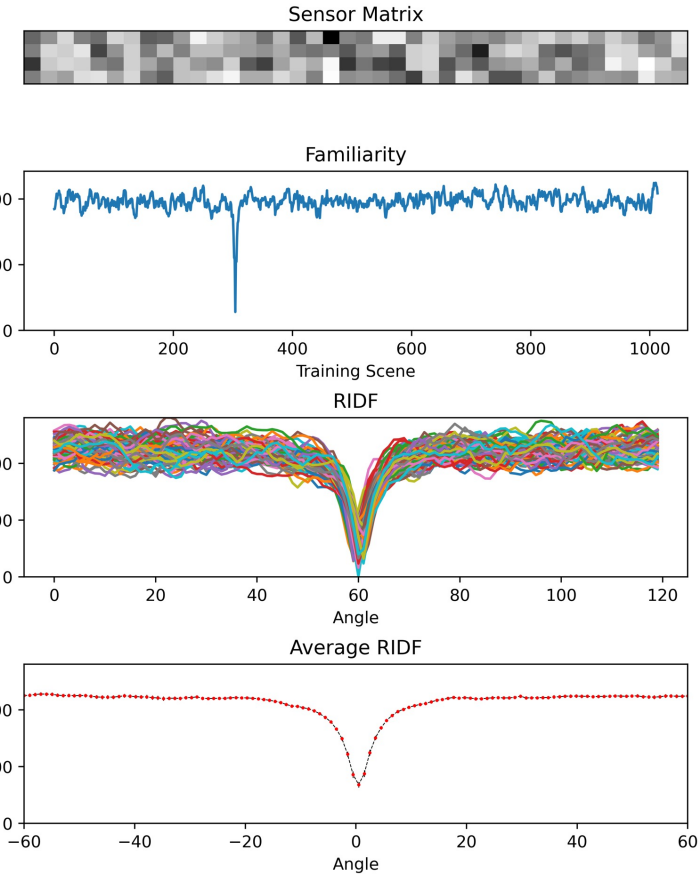




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

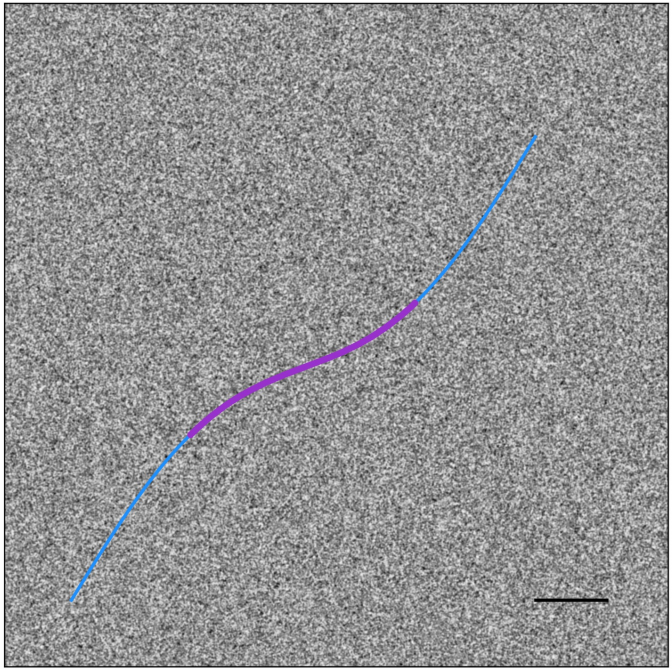
Navigation stats: RMSD error: 65.82; RMSD/dist: 0.165; TD: 11446; p90: 12; p50: 6; complete: 0

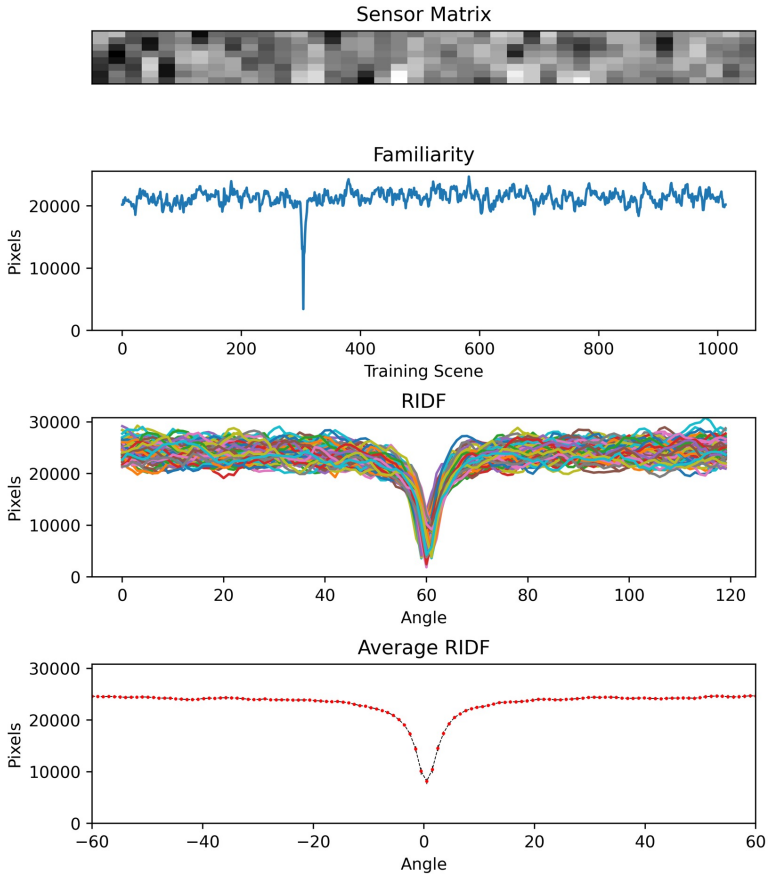




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

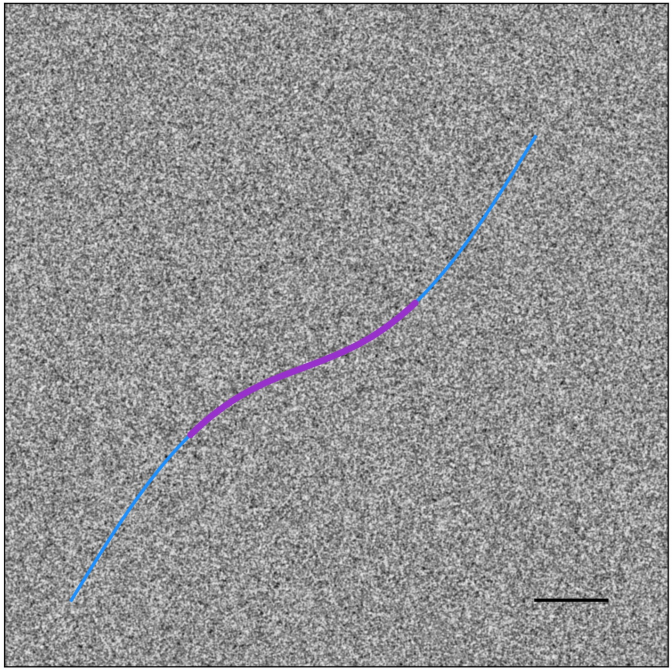
Navigation stats: RMSD error: 58.14; RMSD/dist: 0.145; TD: 12910; p90: 12; p50: 4; complete: 0

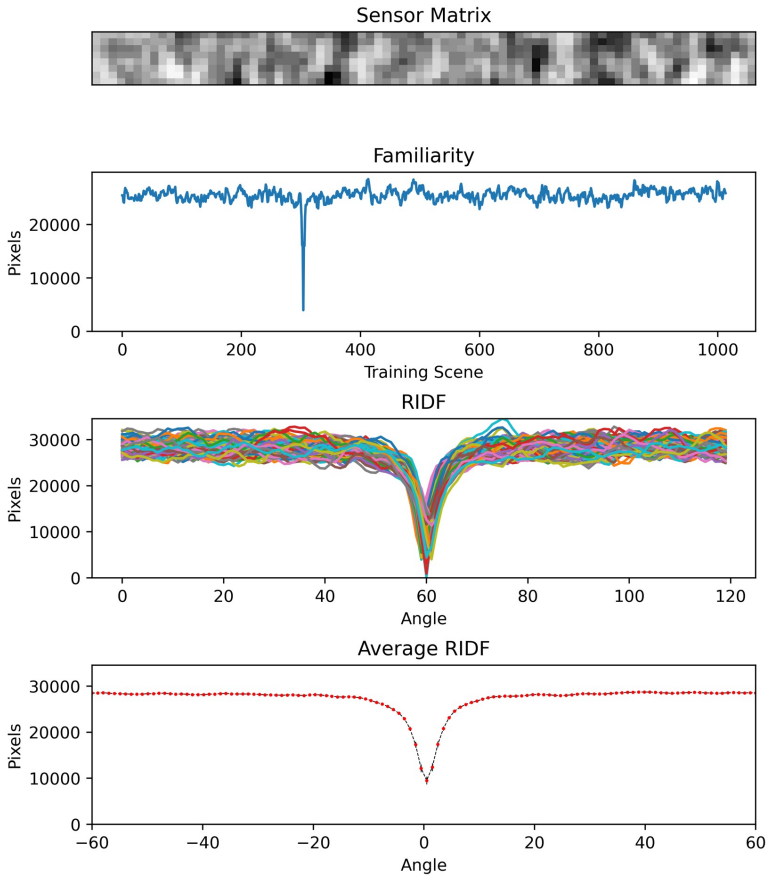




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

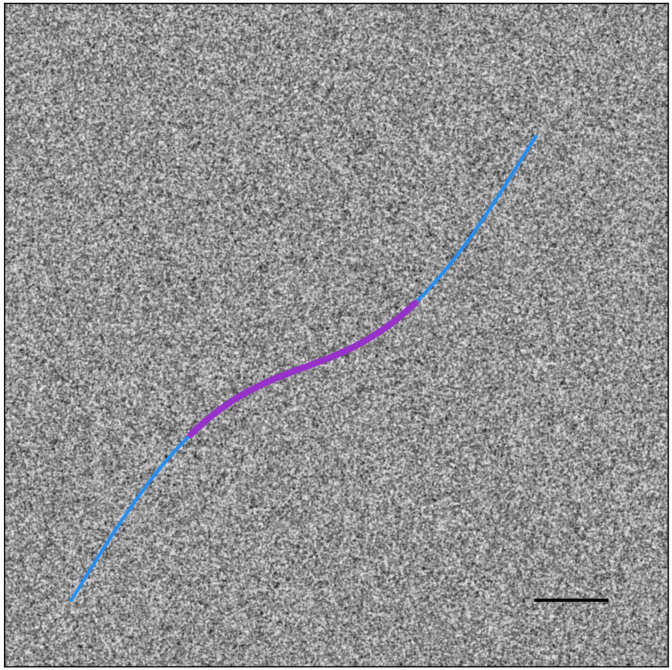
Navigation stats: RMSD error: 57.43; RMSD/dist: 0.144; TD: 13351; p90: 10; p50: 4; complete: 0

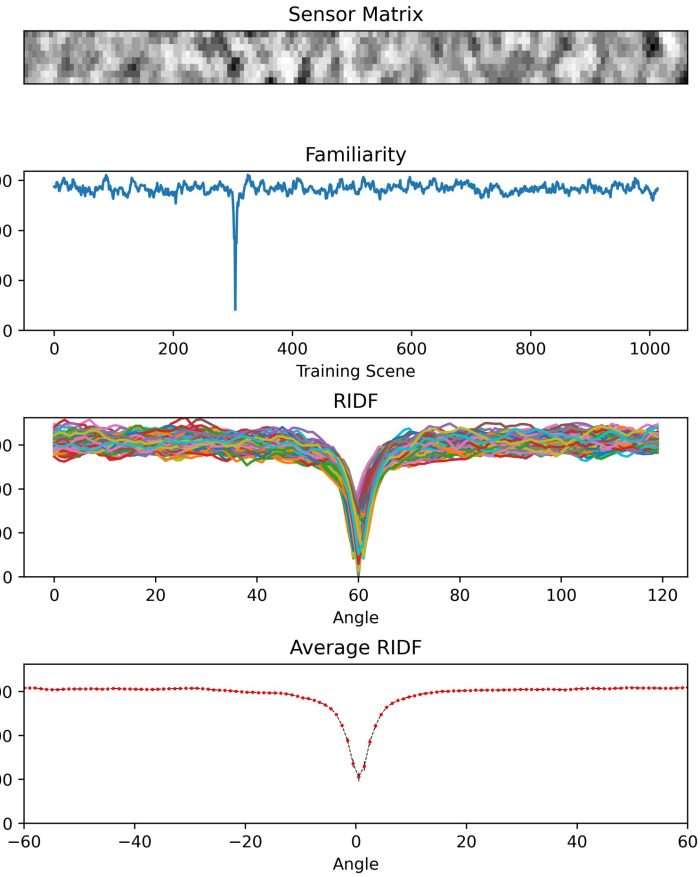




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 48.54; RMSD/dist: 0.121; TD: 16297; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 47.36; RMSD/dist: 0.118; TD: 17493; p90: 10; p50: 4; complete: 0