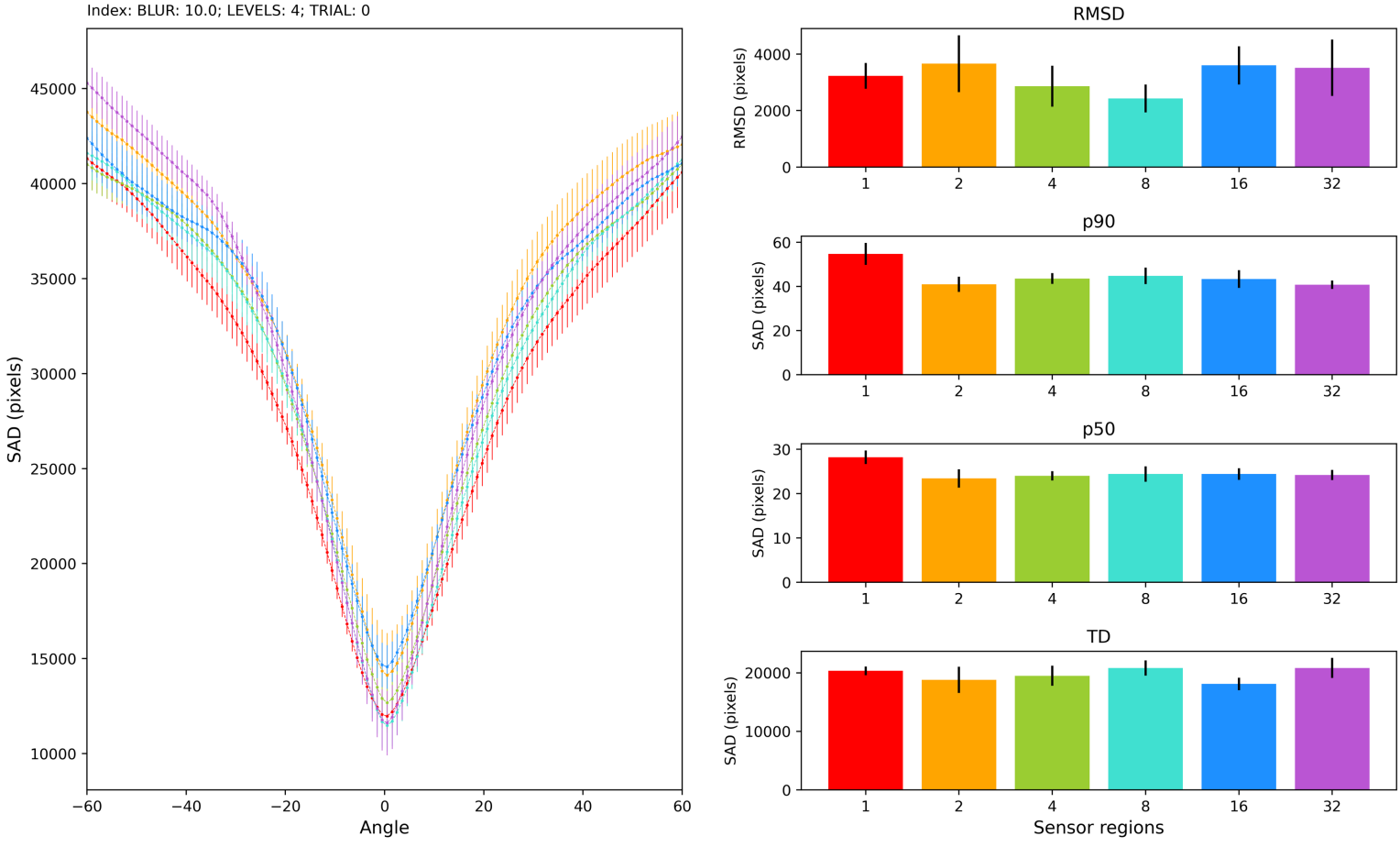
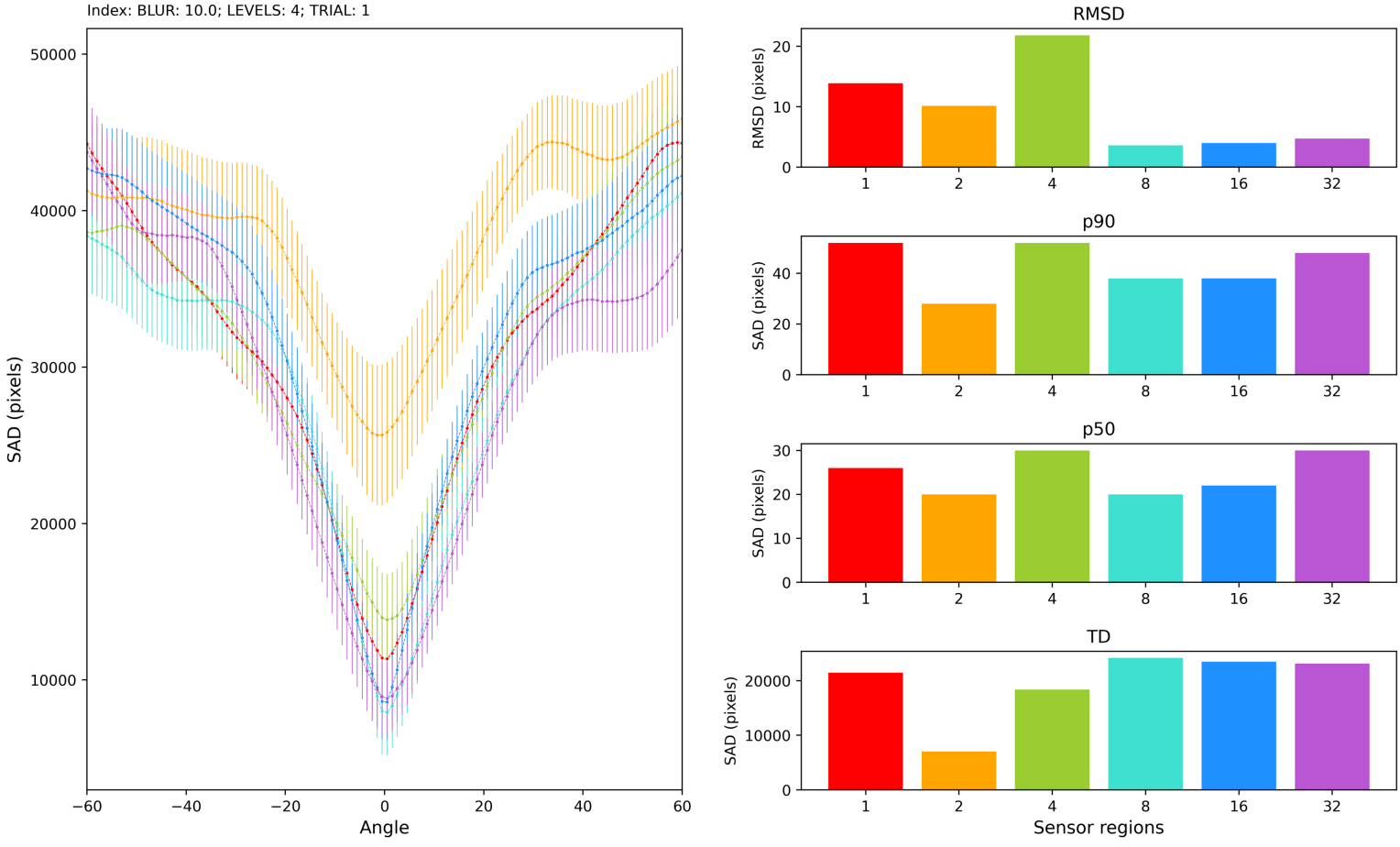
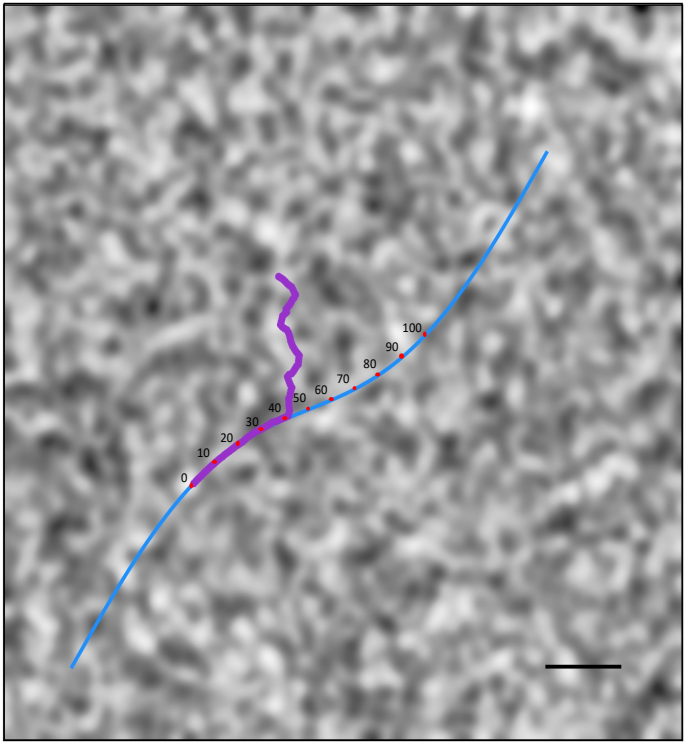
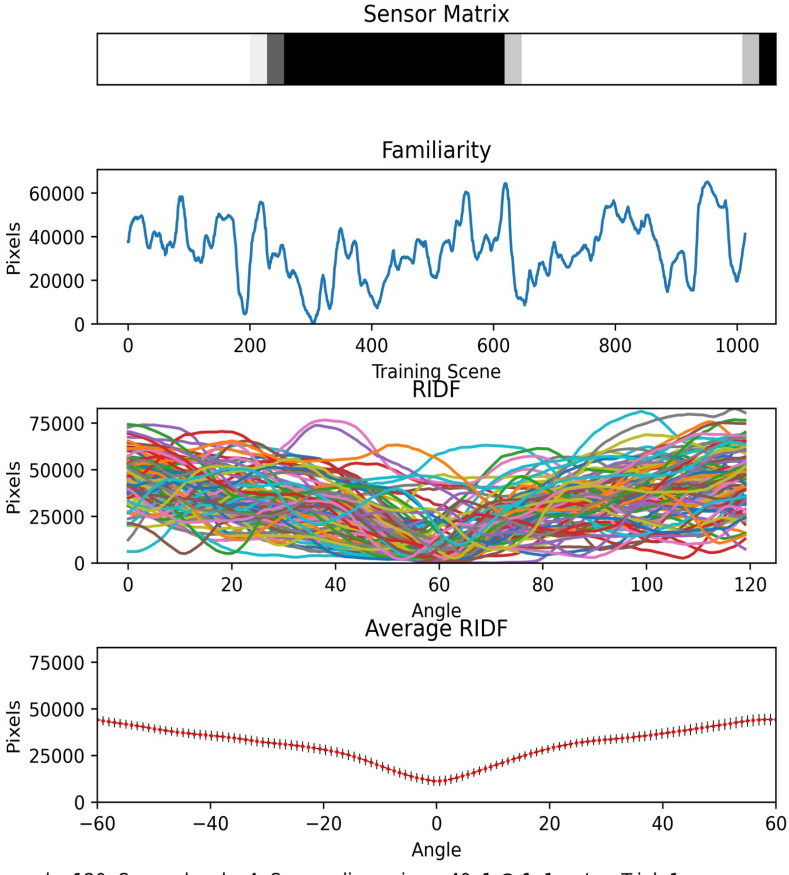

Index: BLUR: 10.0; LEVELS: 4; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

40%

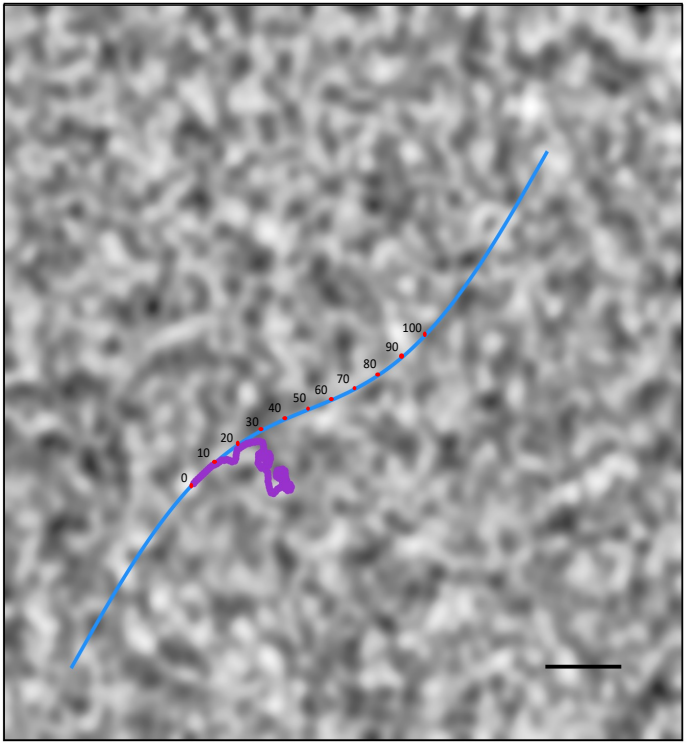


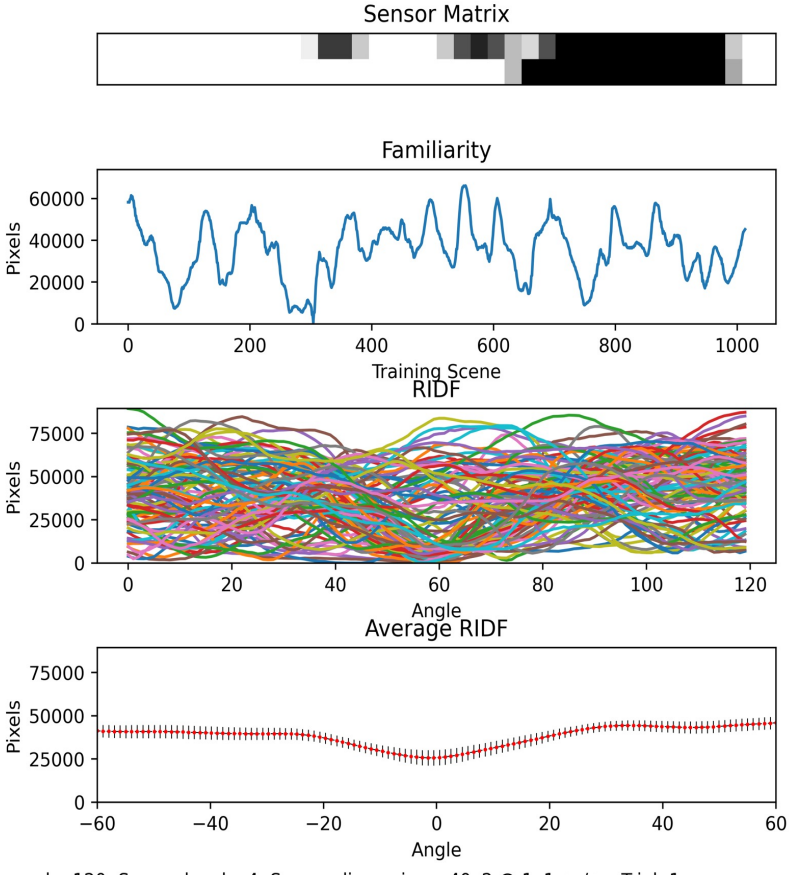


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 5549.07; RMSD/dist: 13.873; TD: 21459; p90: 52; p50: 26; complete: 0

10%

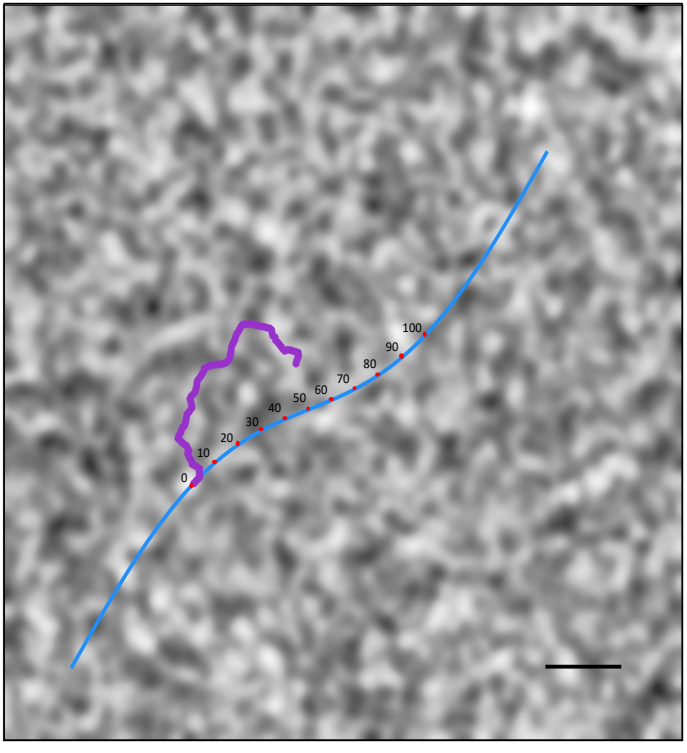


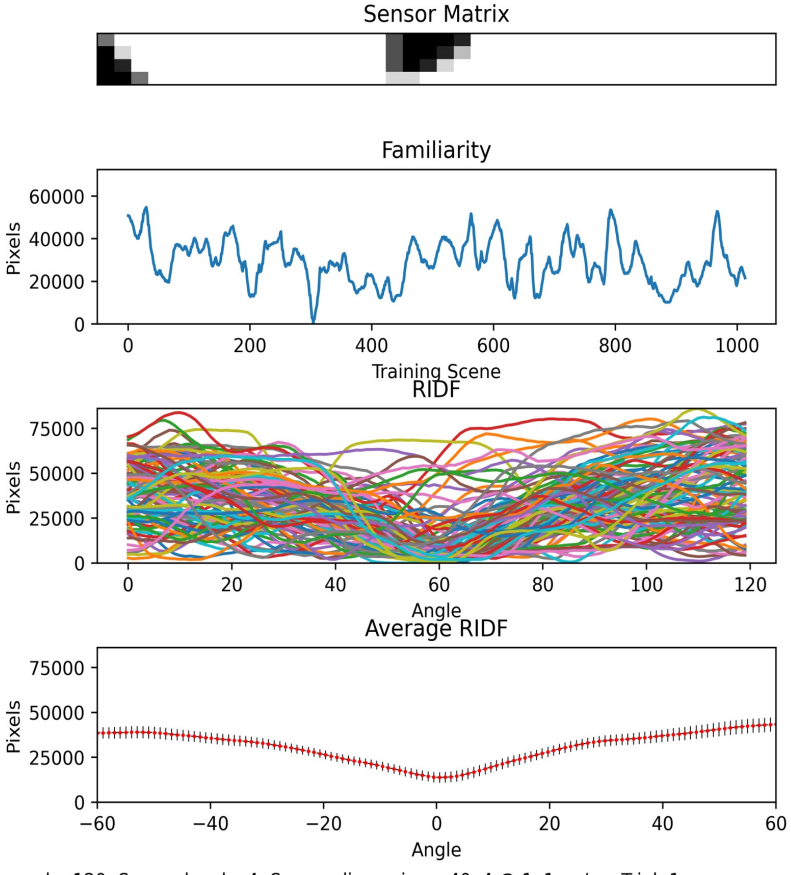


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4057.44; RMSD/dist: 10.144; TD: 7043; p90: 28; p50: 20; complete: 0

0%

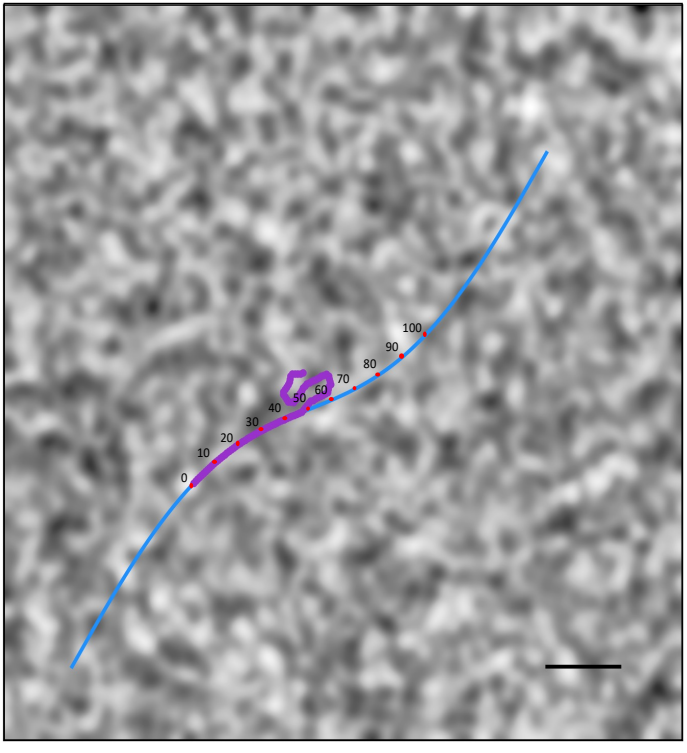


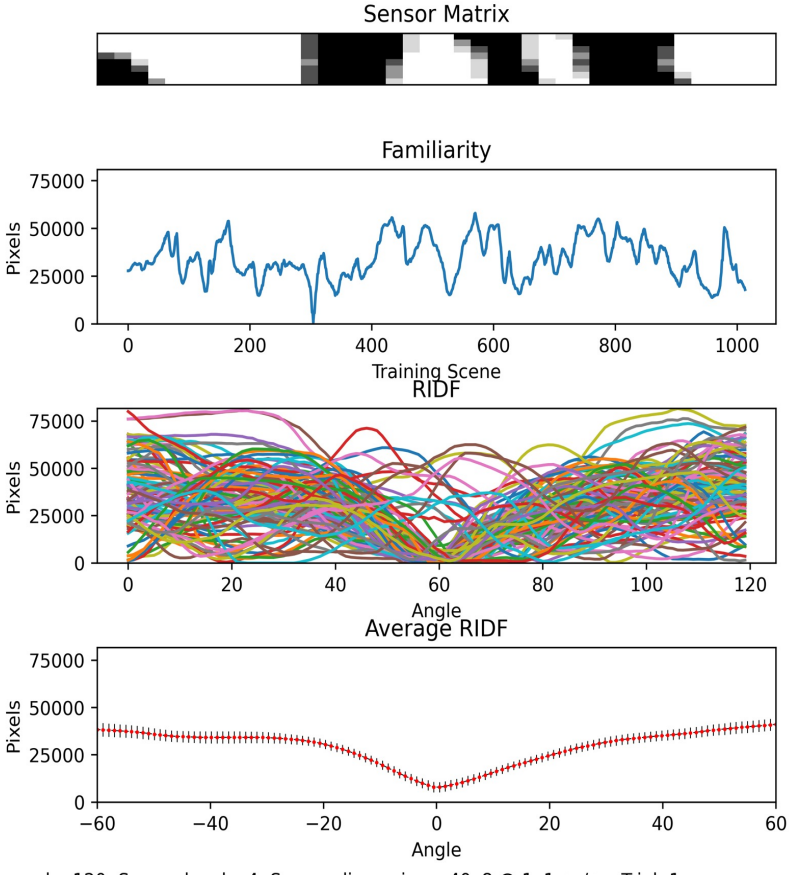


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 8740.08; RMSD/dist: 21.850; TD: 18377; p90: 52; p50: 30; complete: 0

50%

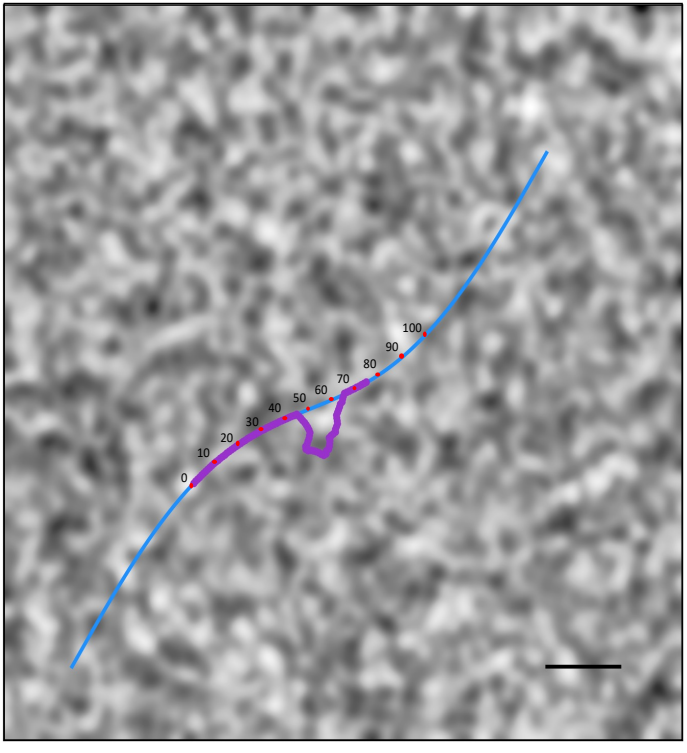


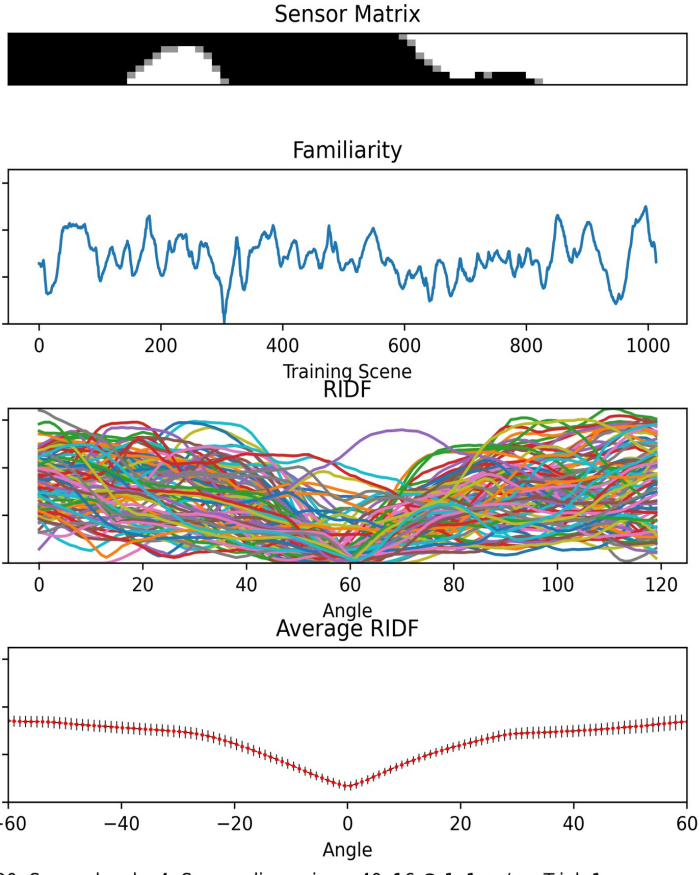


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1435.80; RMSD/dist: 3.589; TD: 24169; p90: 38; p50: 20; complete: 0

40%

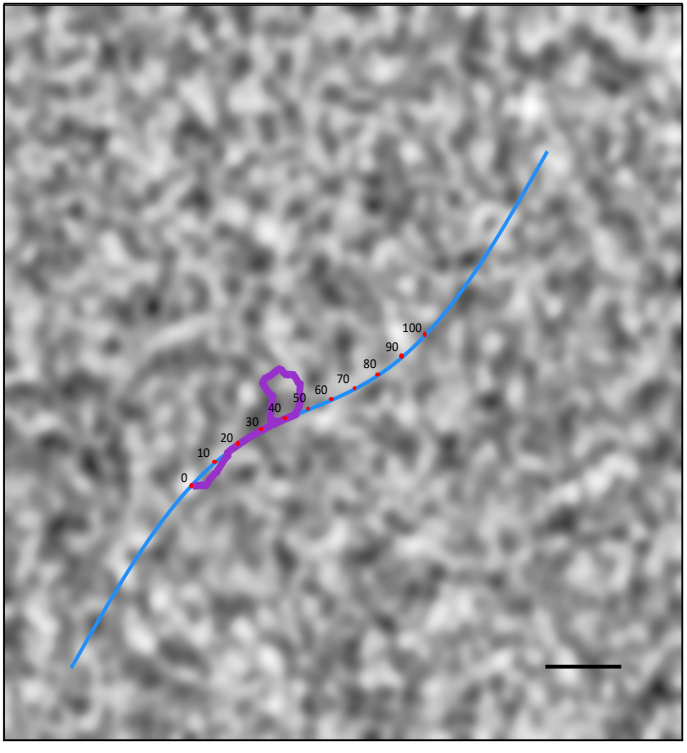


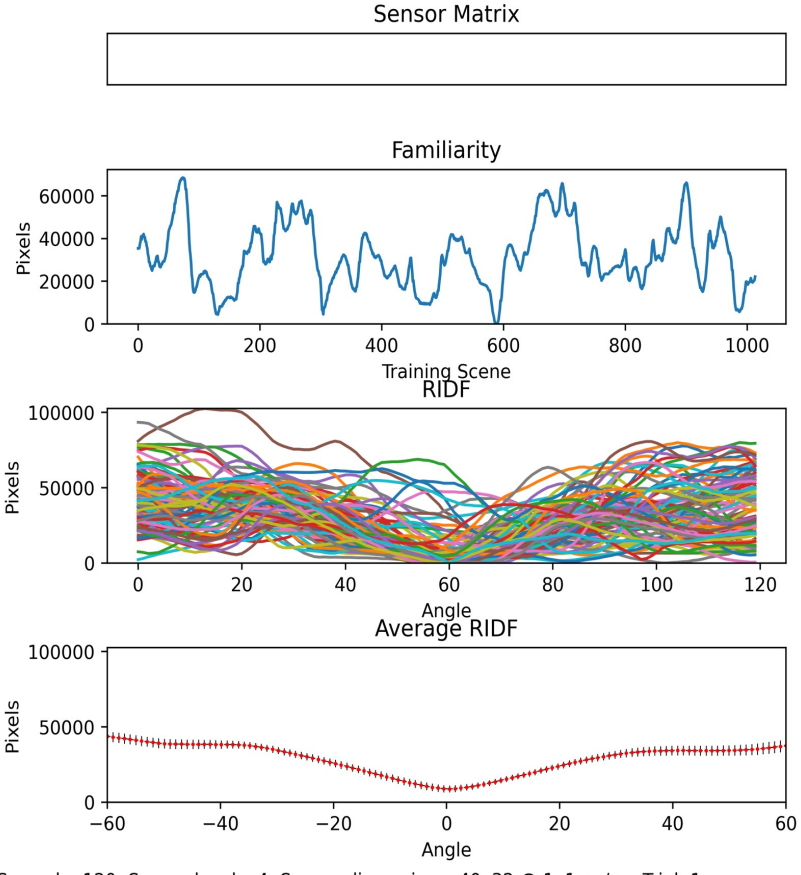


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1588.96; RMSD/dist: 3.972; TD: 23494; p90: 38; p50: 22; complete: 0

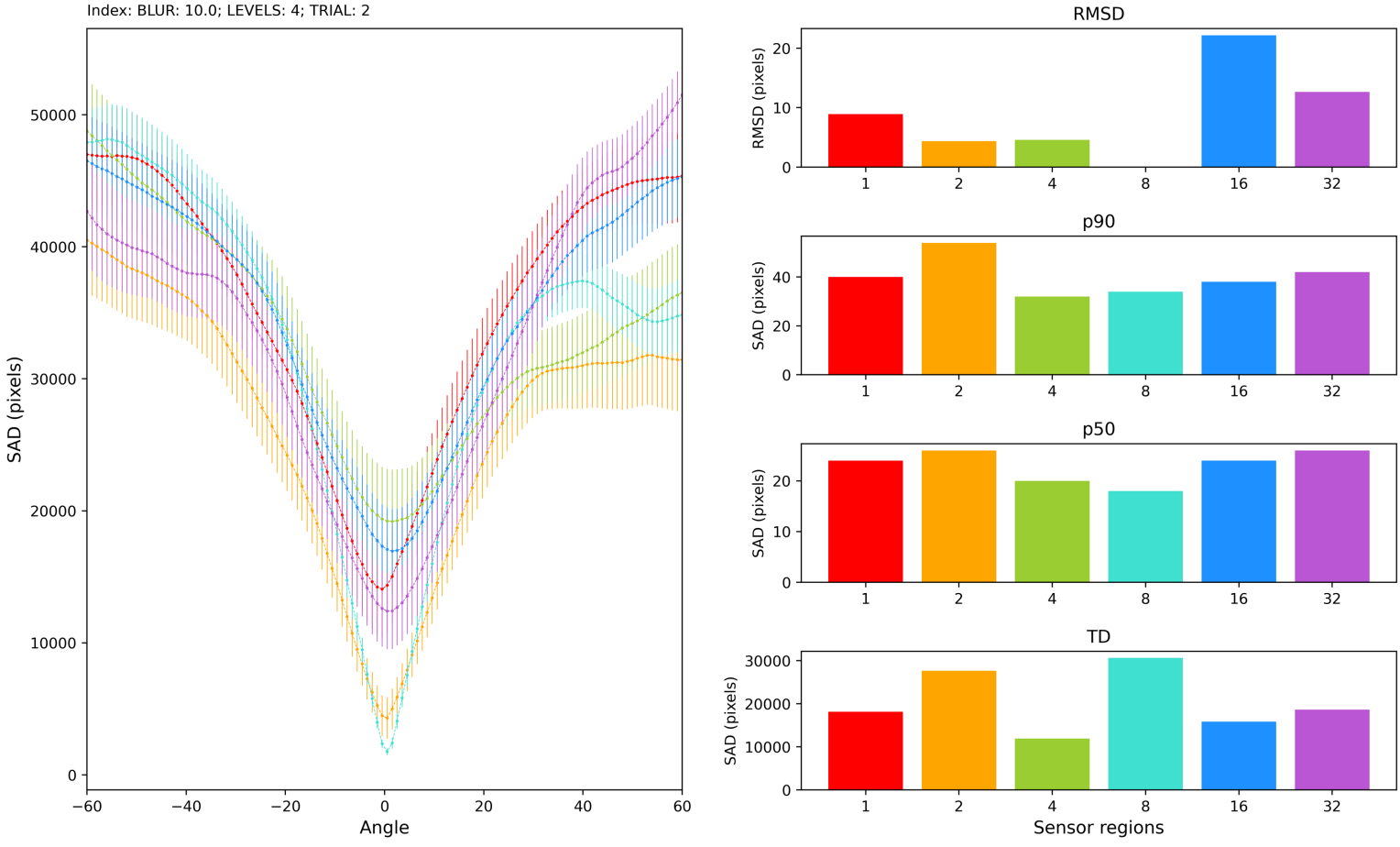
20%



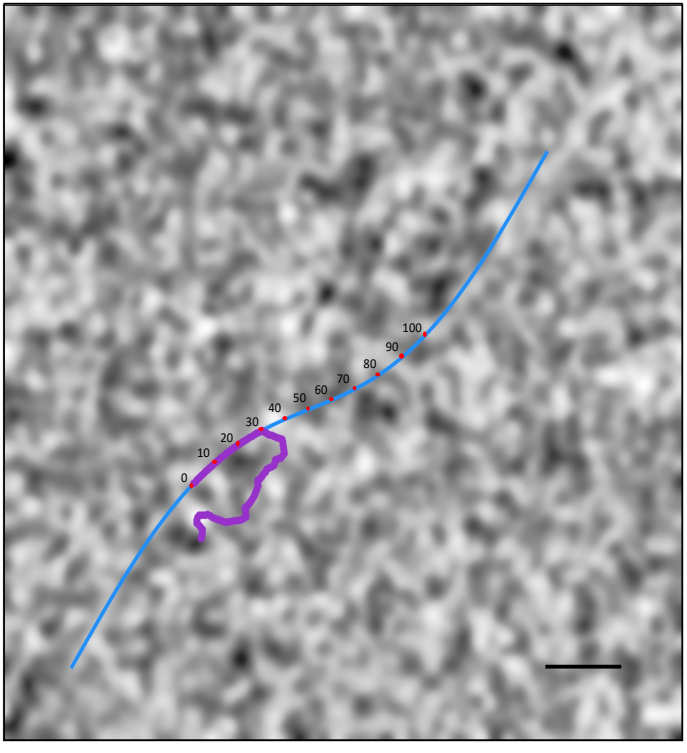


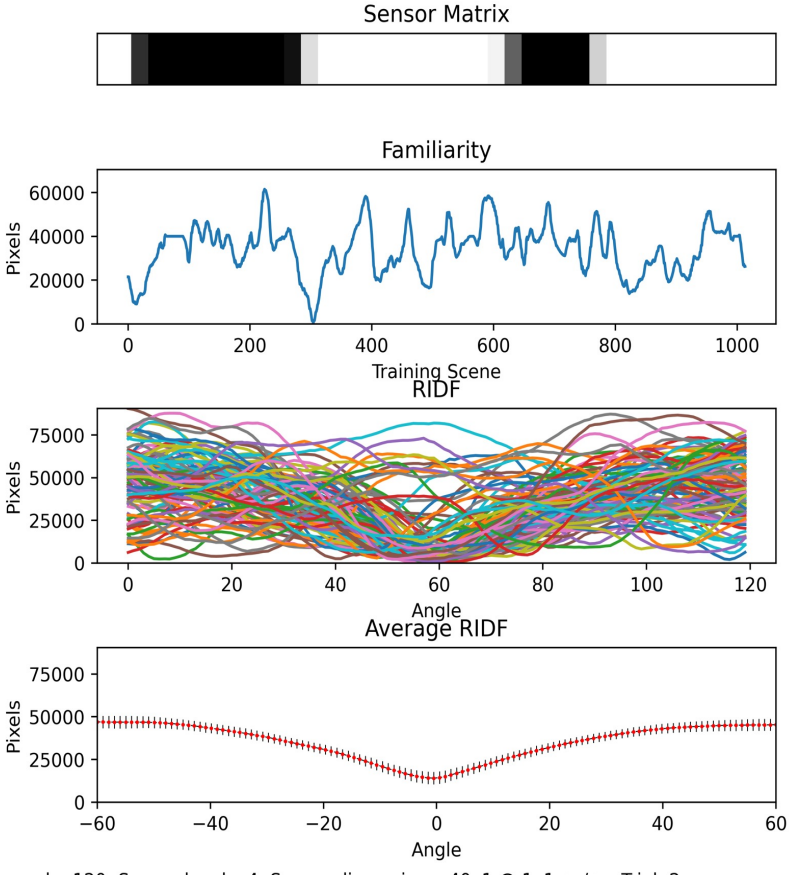
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1887.28; RMSD/dist: 4.718; TD: 23132; p90: 48; p50: 30; complete: 0


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

30%

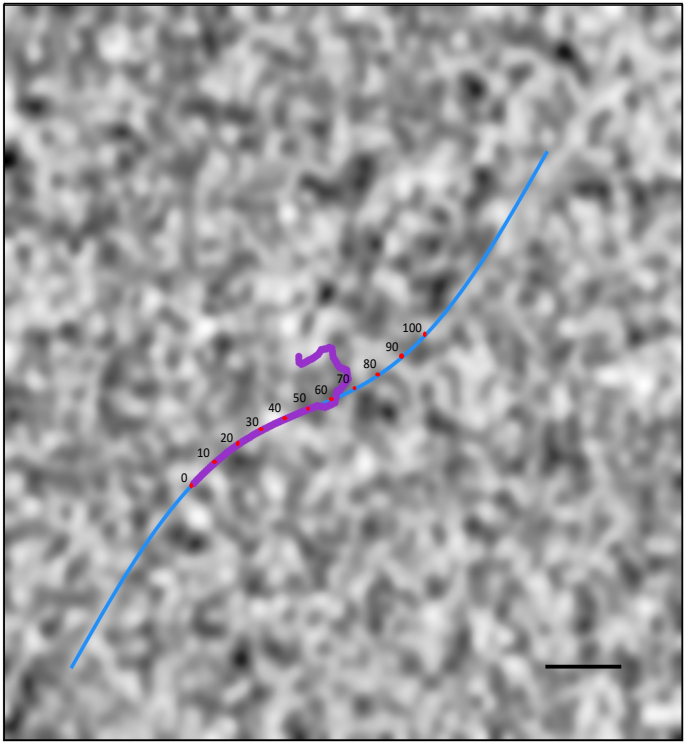


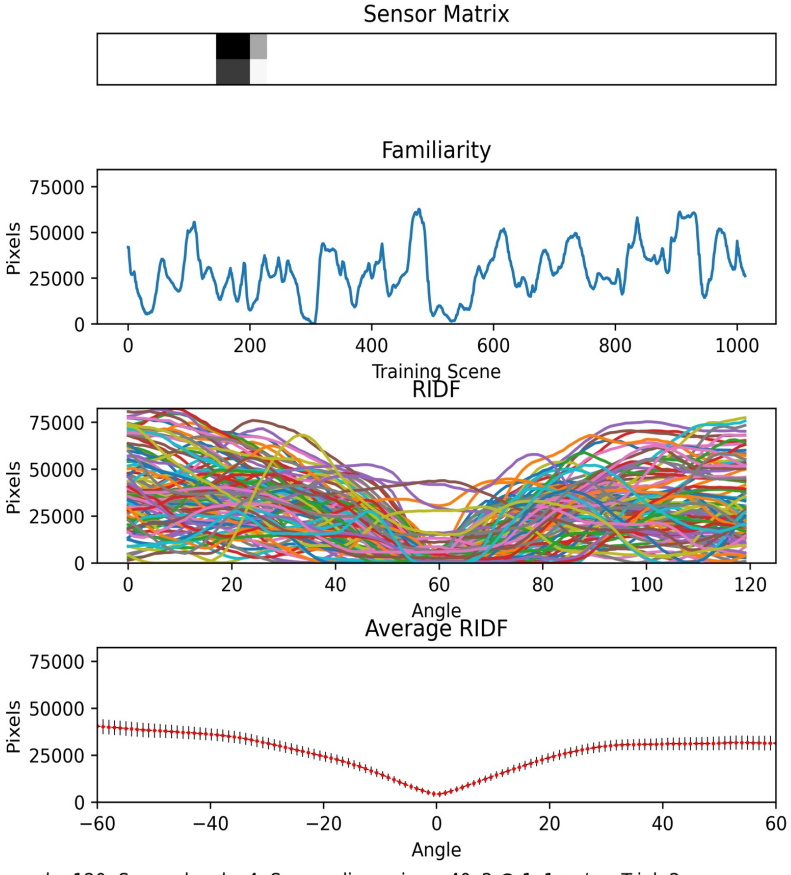


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 3561.70; RMSD/dist: 8.904; TD: 18144; p90: 40; p50: 24; complete: 0

50%

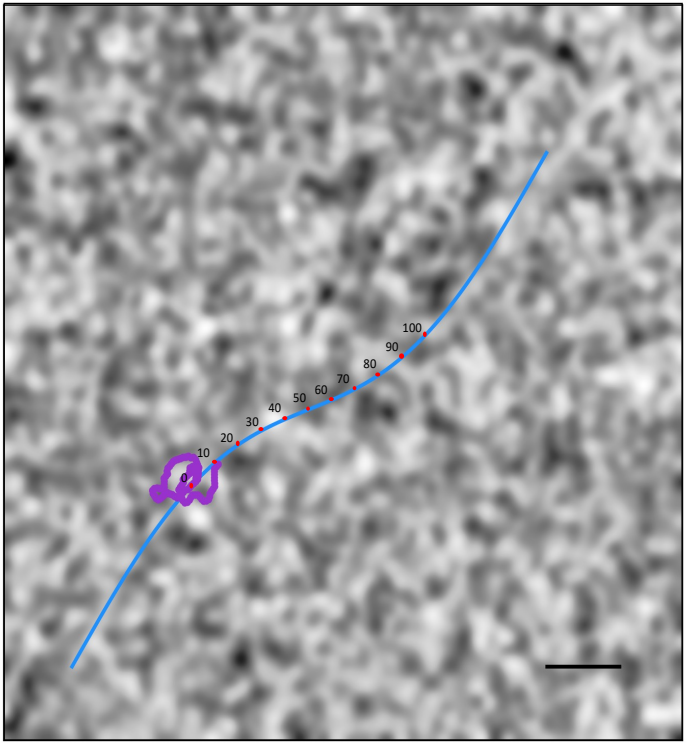


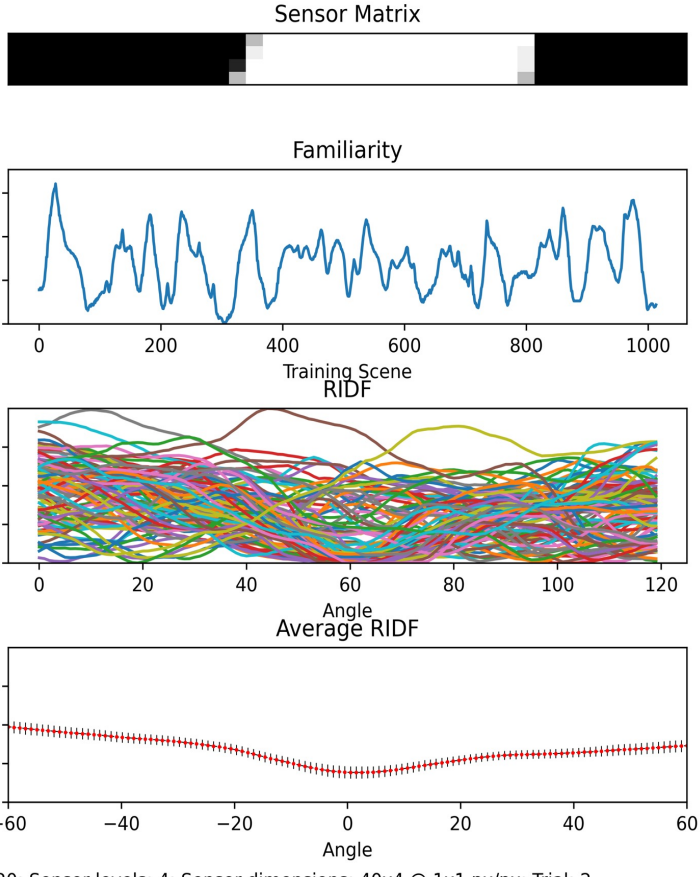


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1745.37; RMSD/dist: 4.363; TD: 27624; p90: 54; p50: 26; complete: 0

0%

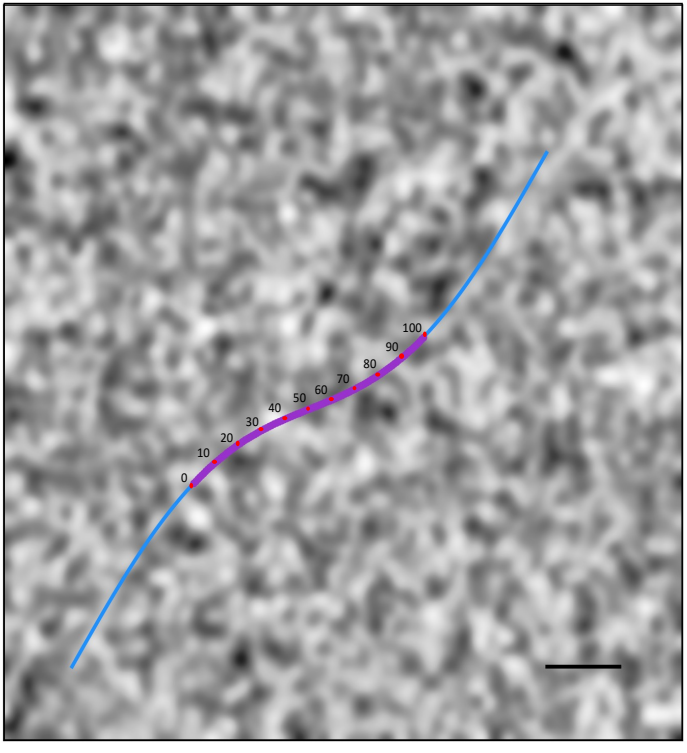


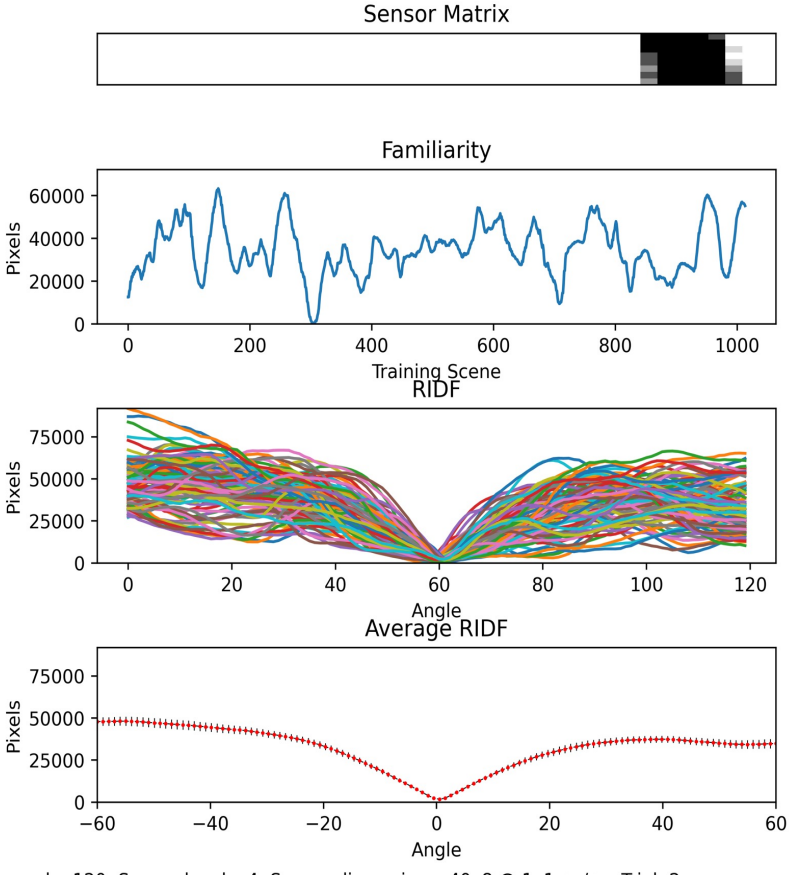


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1822.26; RMSD/dist: 4.556; TD: 11891; p90: 32; p50: 20; complete: 0

100%

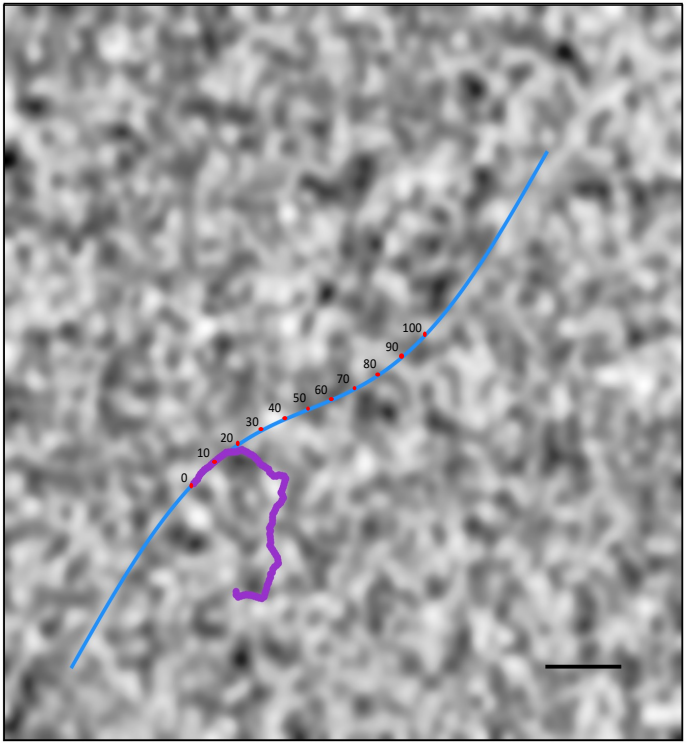


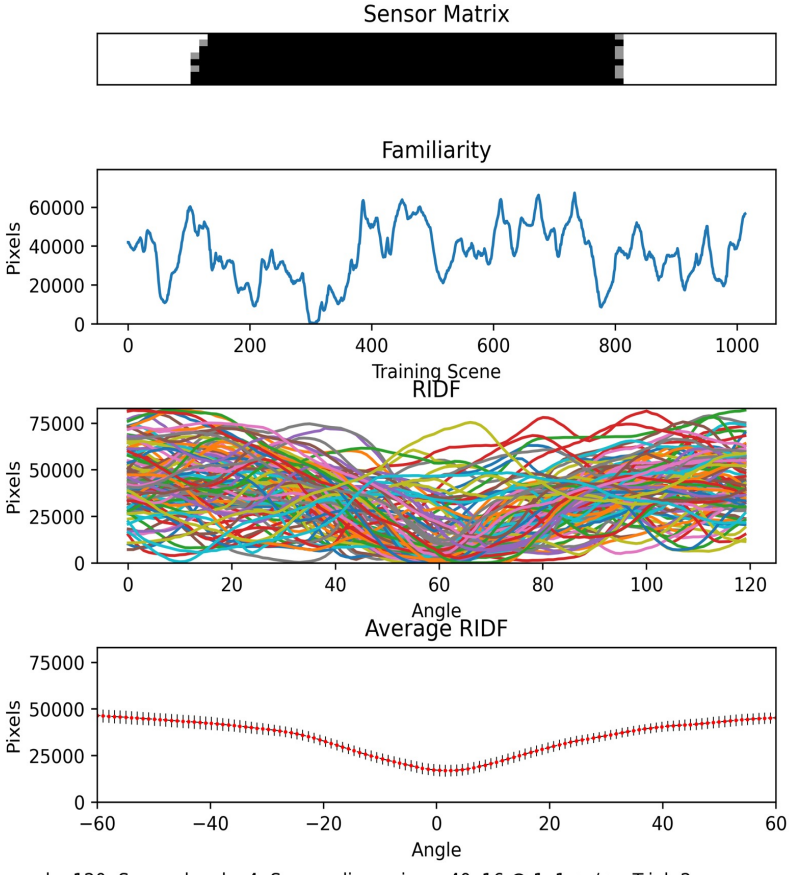


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 30.65; RMSD/dist: 0.077; TD: 30601; p90: 34; p50: 18; complete: 0

10%

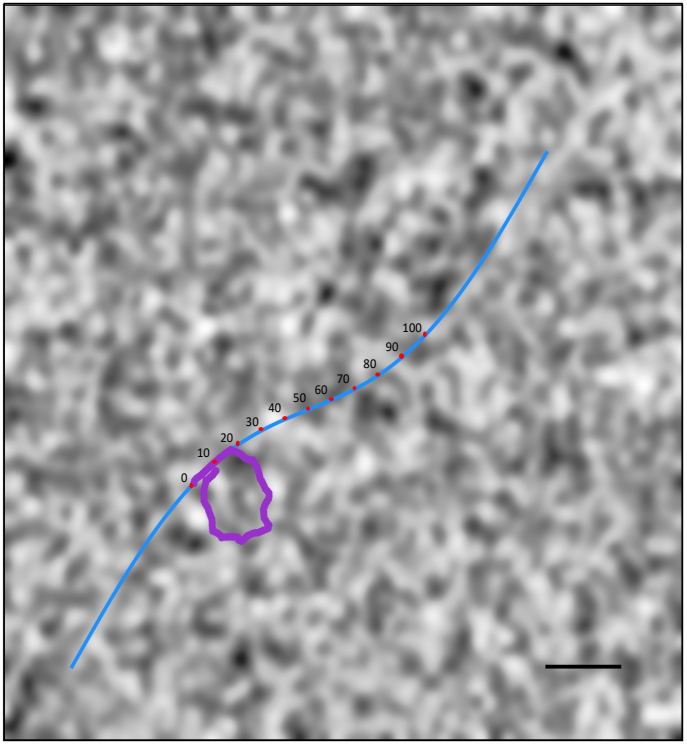


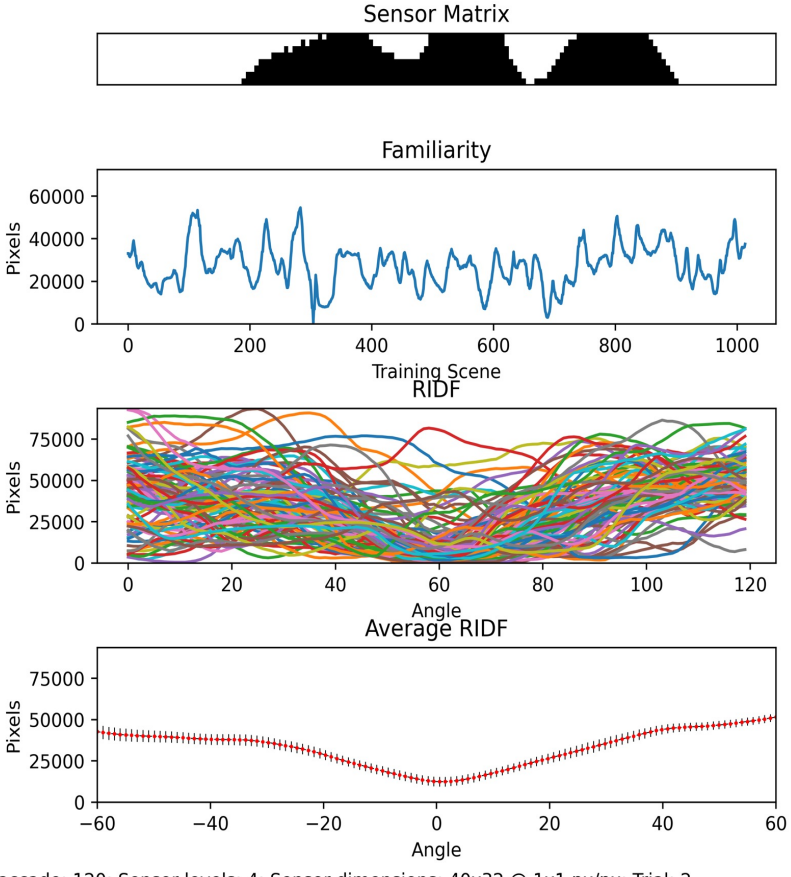


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 8873.23; RMSD/dist: 22.183; TD: 15800; p90: 38; p50: 24; complete: 0

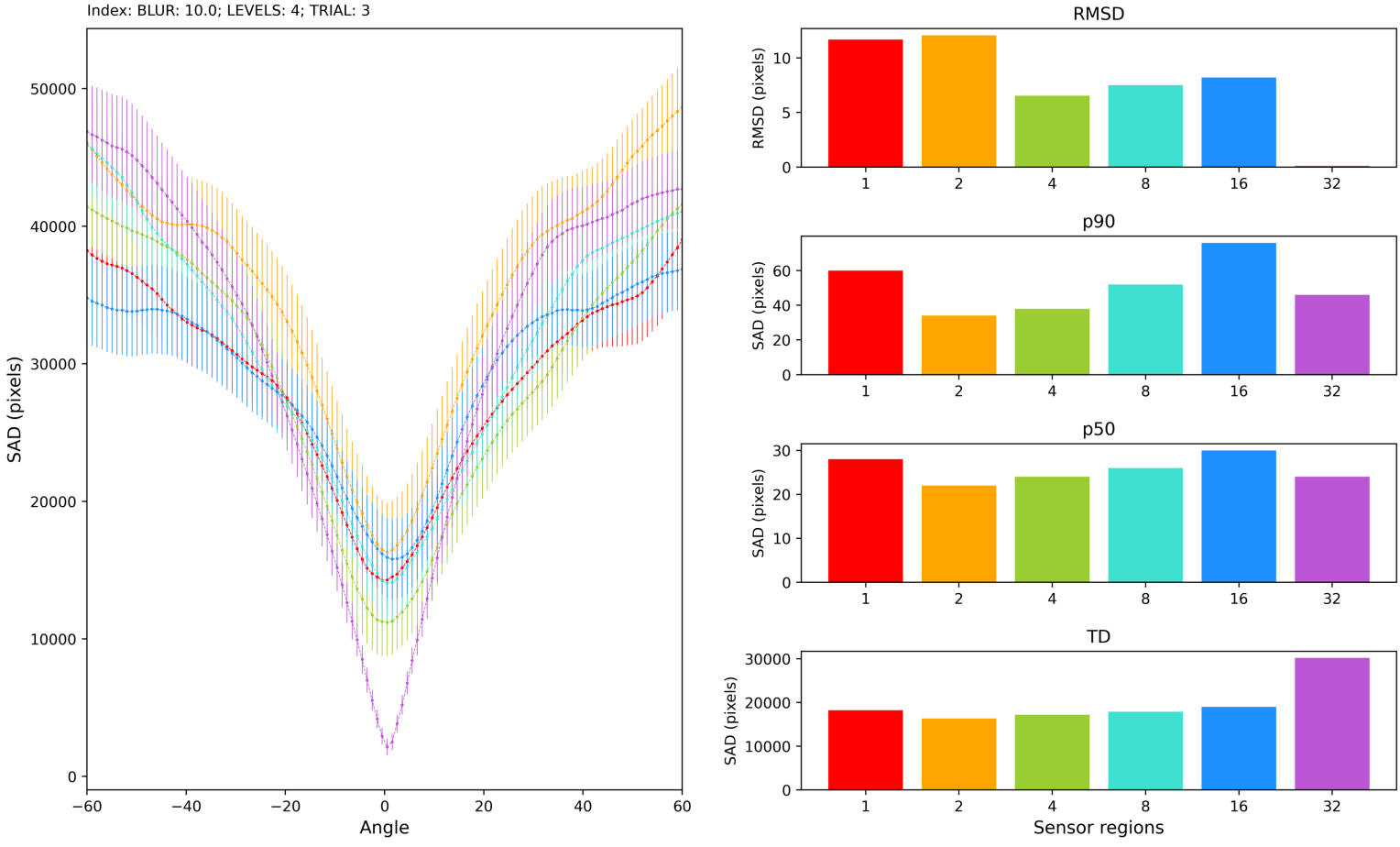
10%



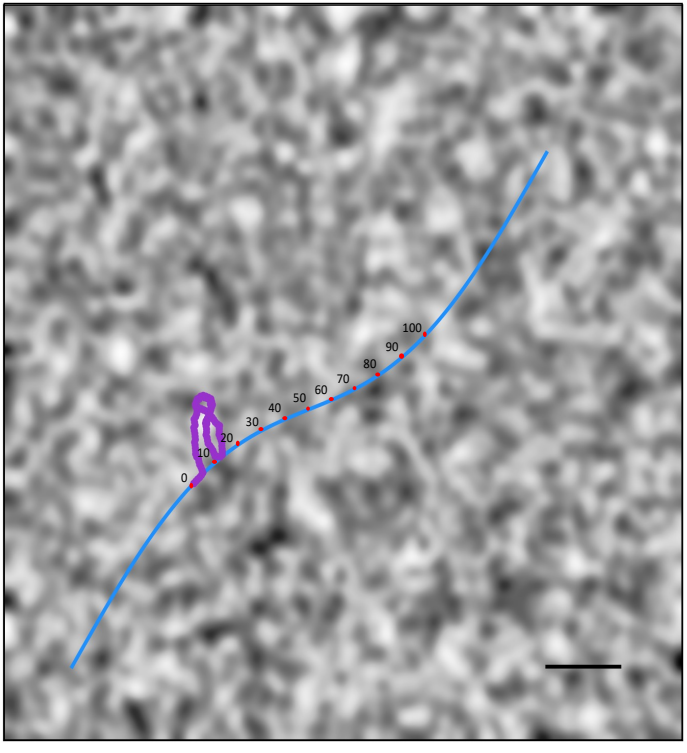


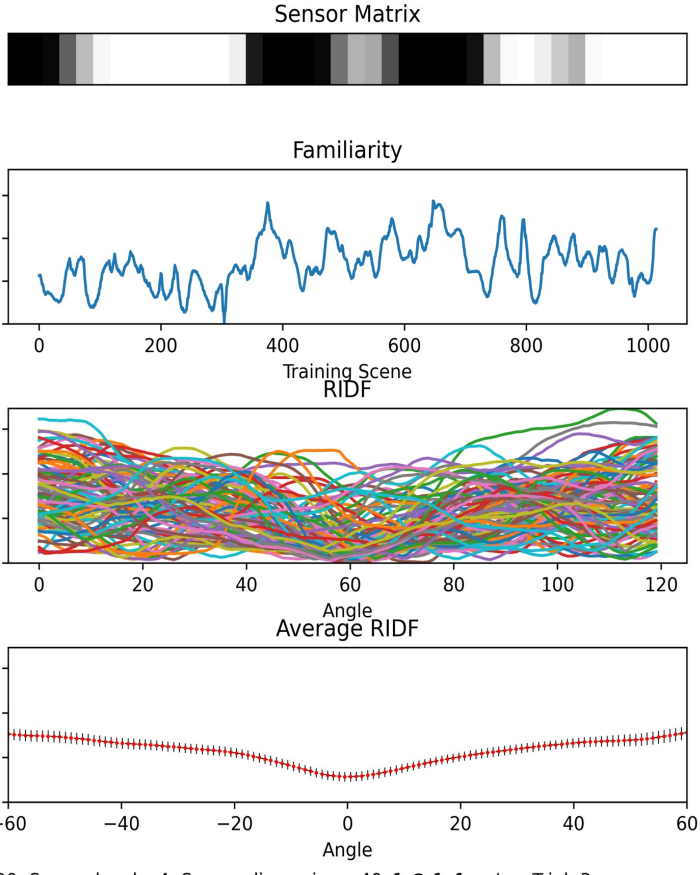
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 5062.82; RMSD/dist: 12.657; TD: 18593; p90: 42; p50: 26; complete: 0


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

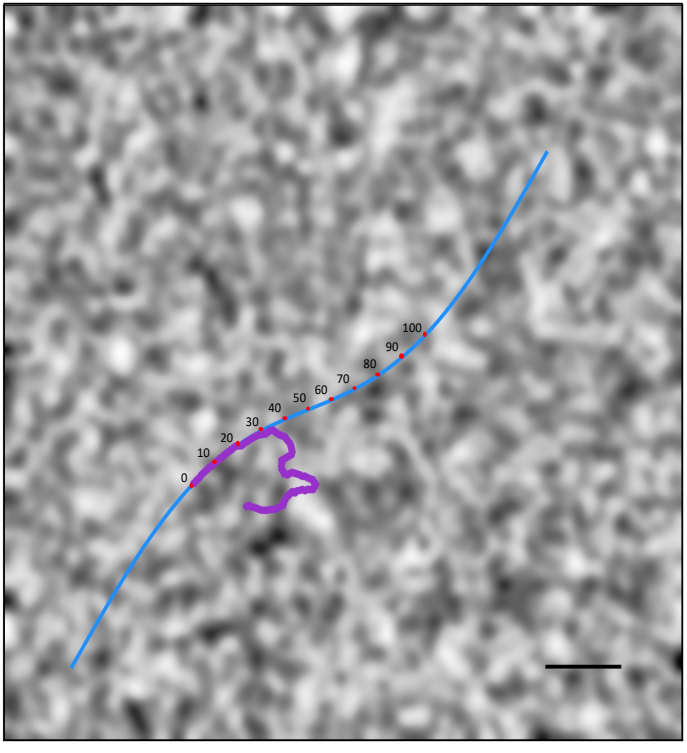


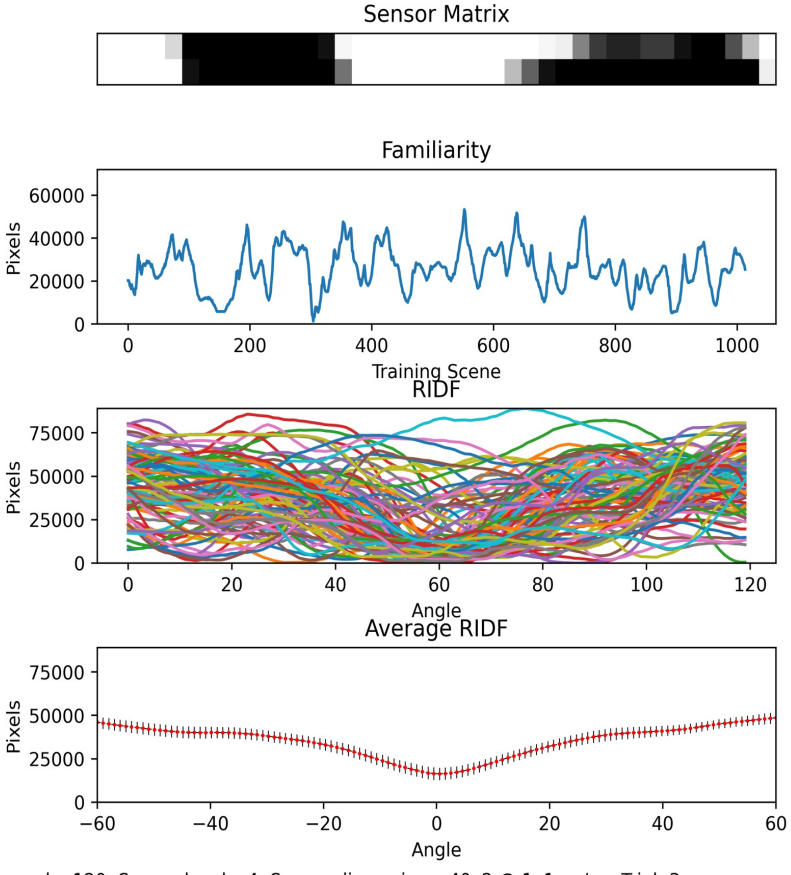


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4666.97; RMSD/dist: 11.667; TD: 18200; p90: 60; p50: 28; complete: 0

20%

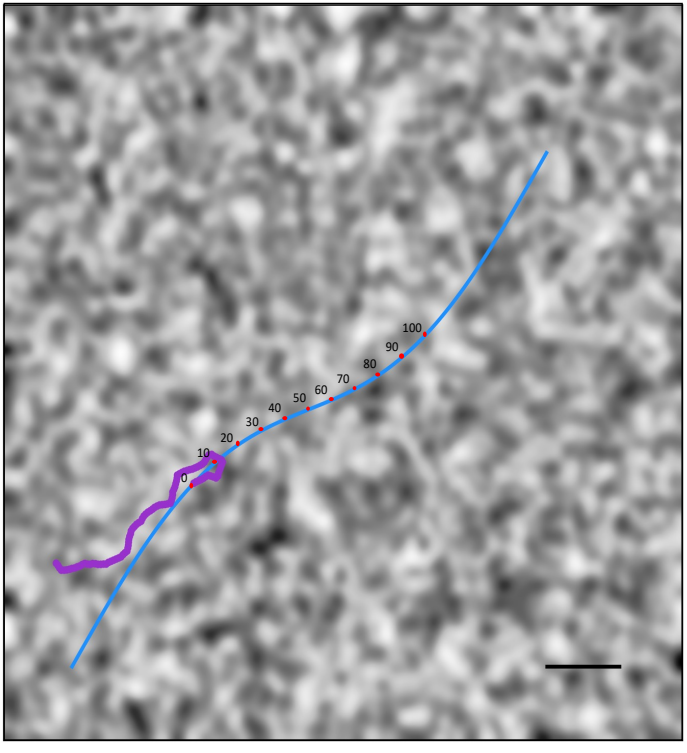


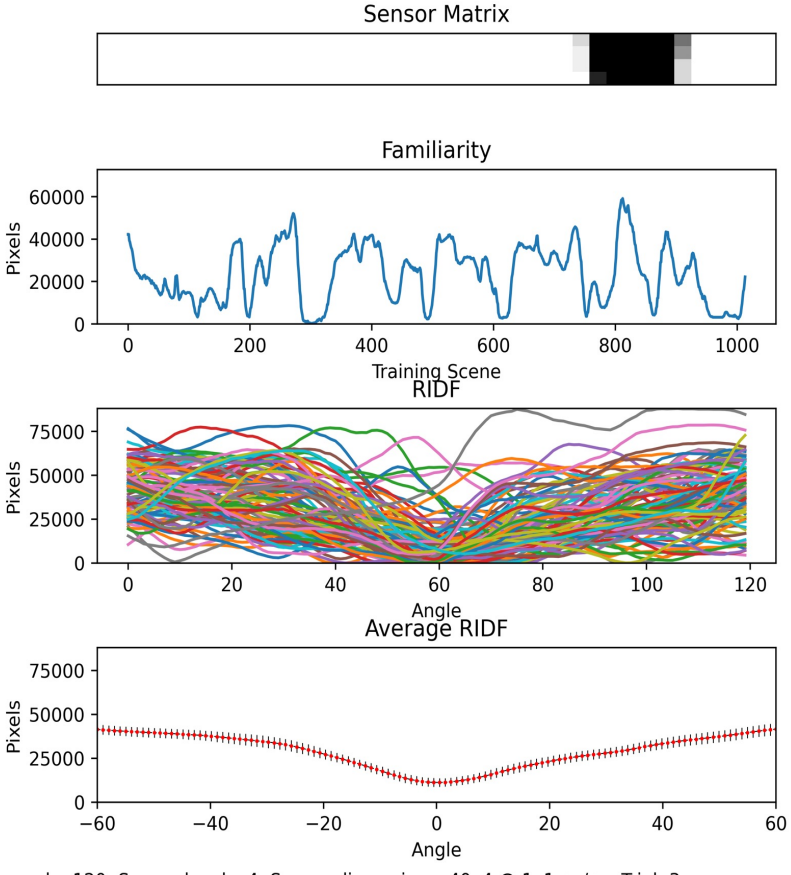


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4828.74; RMSD/dist: 12.072; TD: 16327; p90: 34; p50: 22; complete: 0

0%

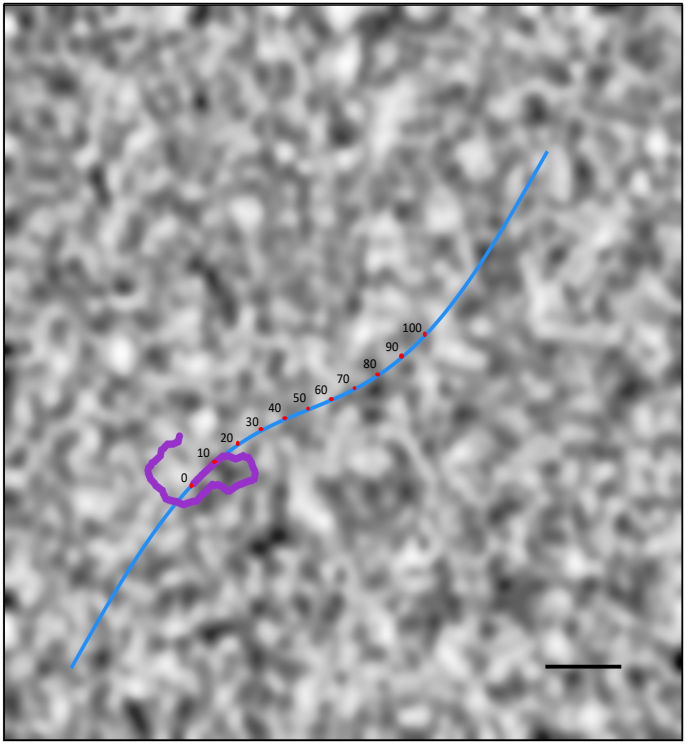


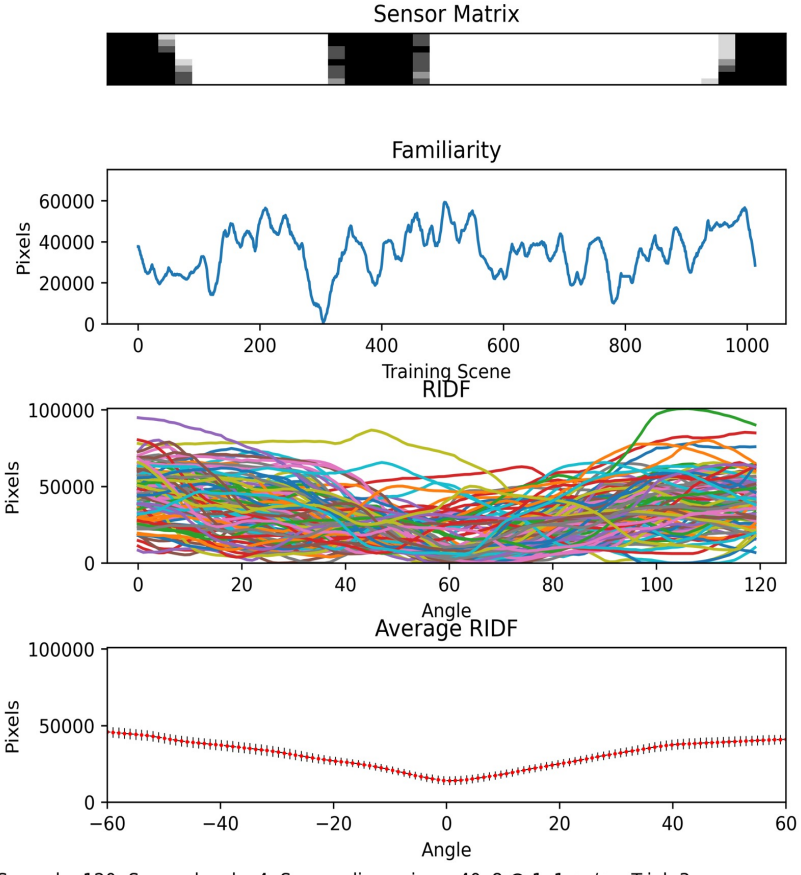


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2611.33; RMSD/dist: 6.528; TD: 17172; p90: 38; p50: 24; complete: 0

10%

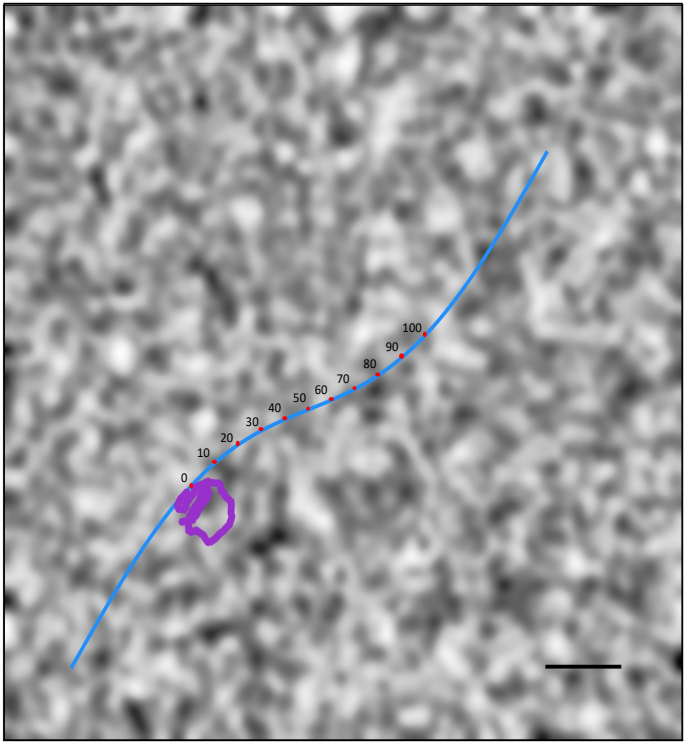


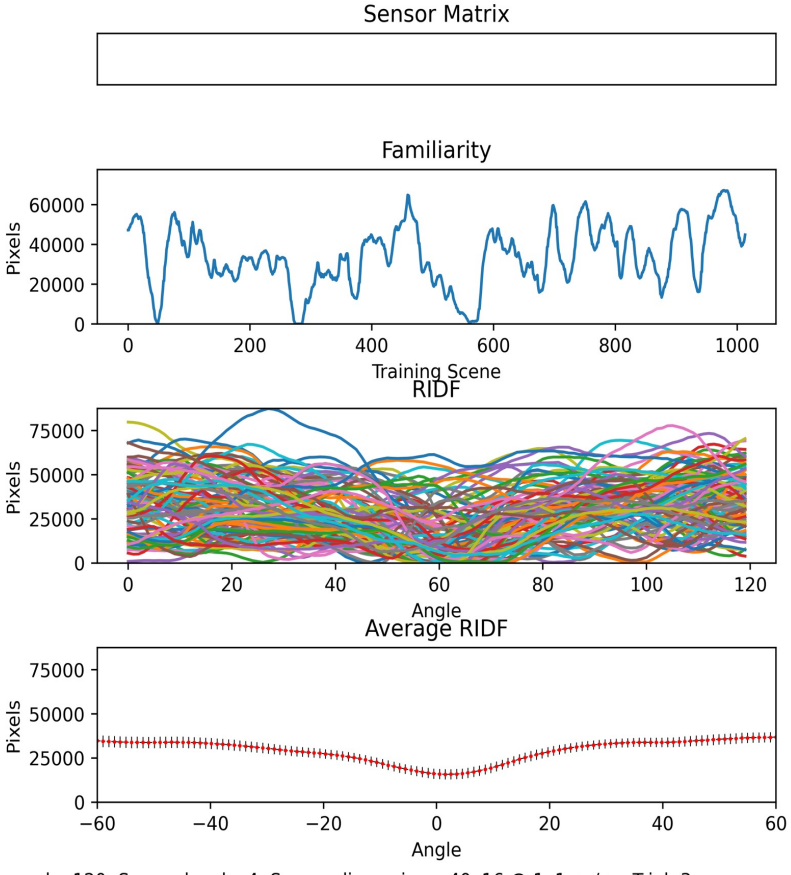


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2997.16; RMSD/dist: 7.493; TD: 17873; p90: 52; p50: 26; complete: 0

0%

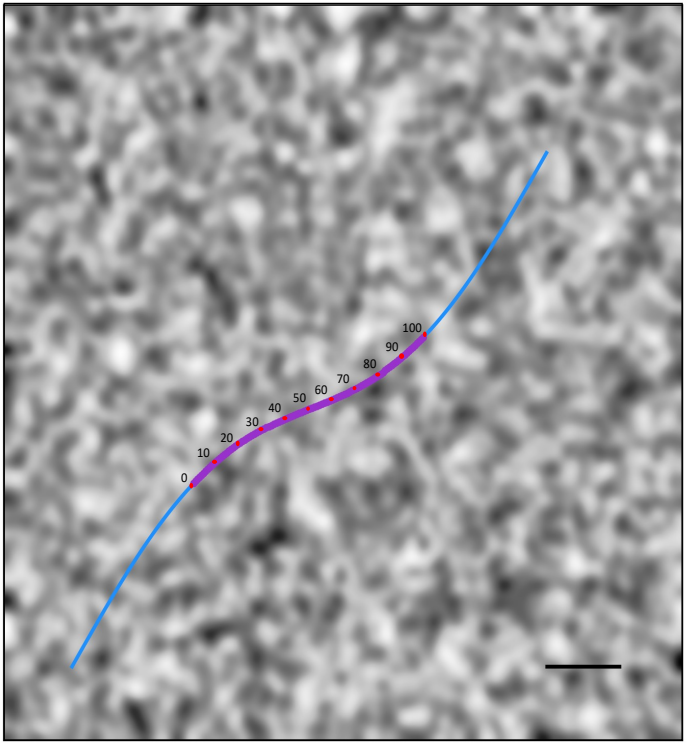


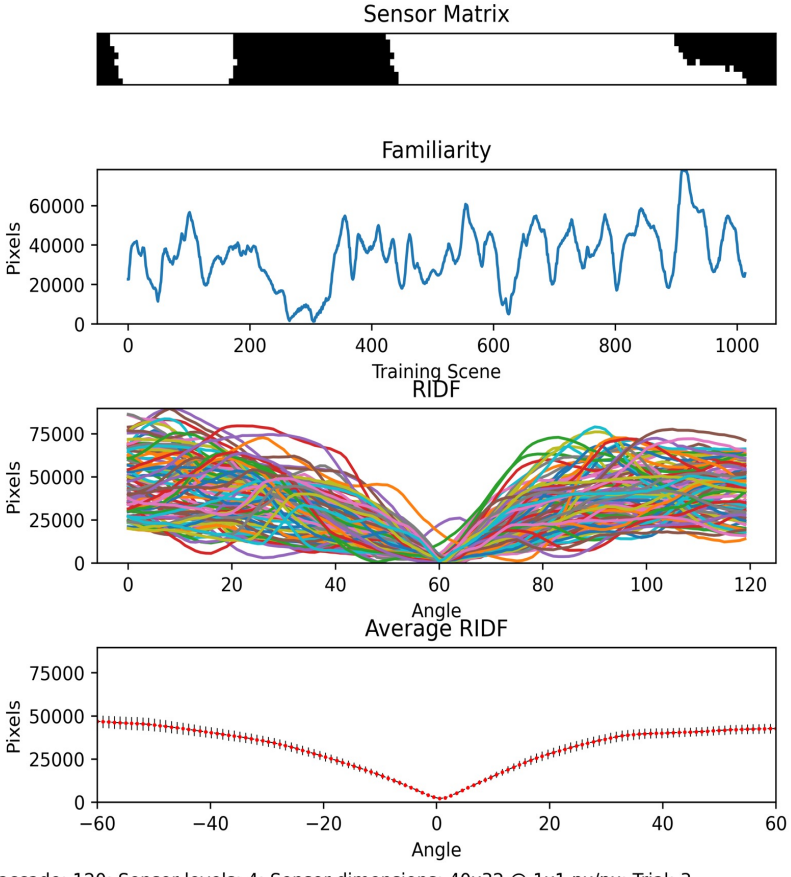


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 3279.76; RMSD/dist: 8.199; TD: 18979; p90: 76; p50: 30; complete: 0

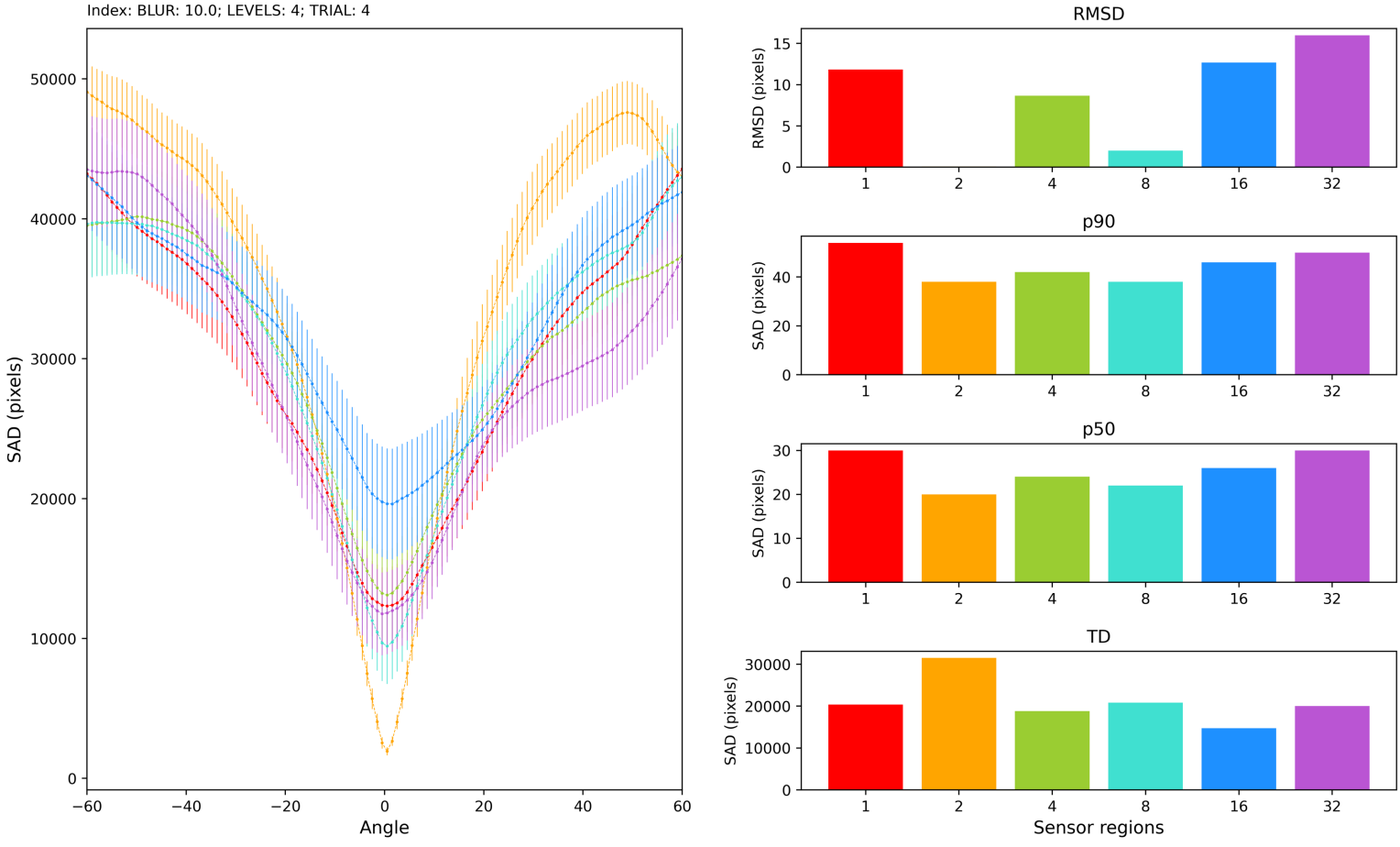
100%



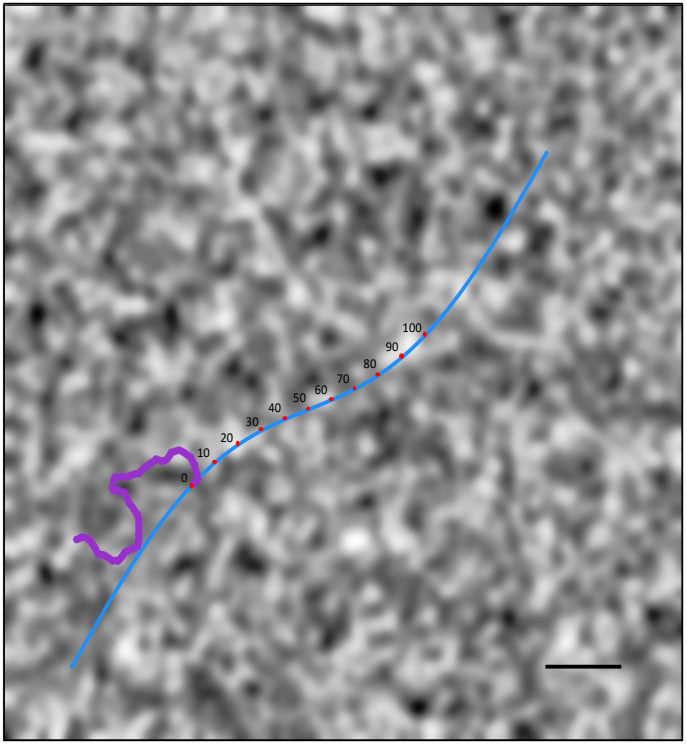


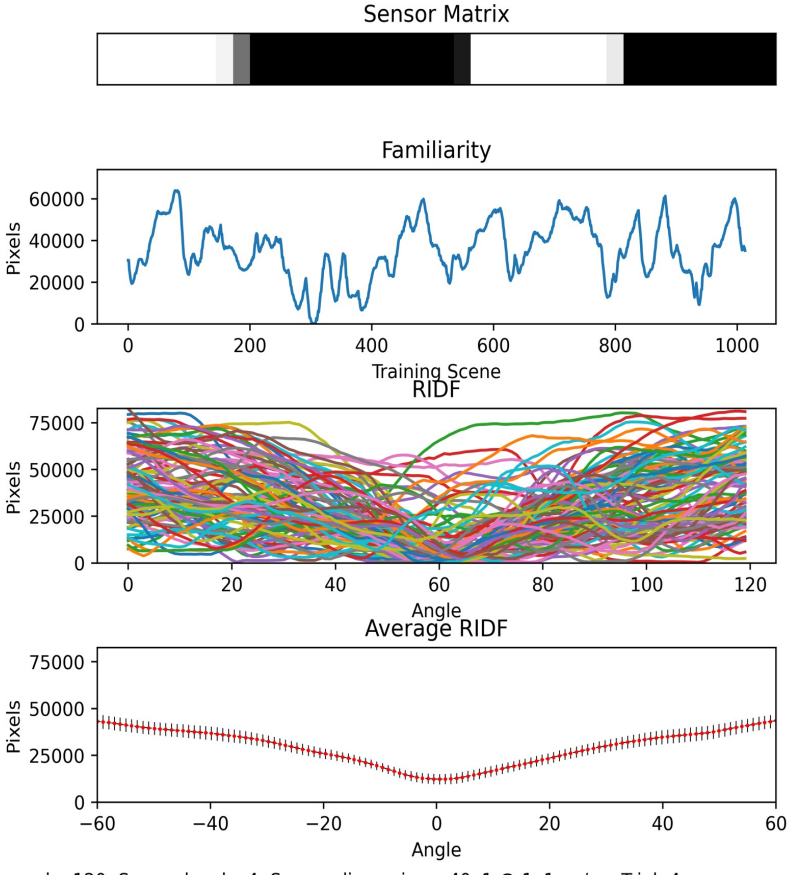
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 45.71; RMSD/dist: 0.114; TD: 30176; p90: 46; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

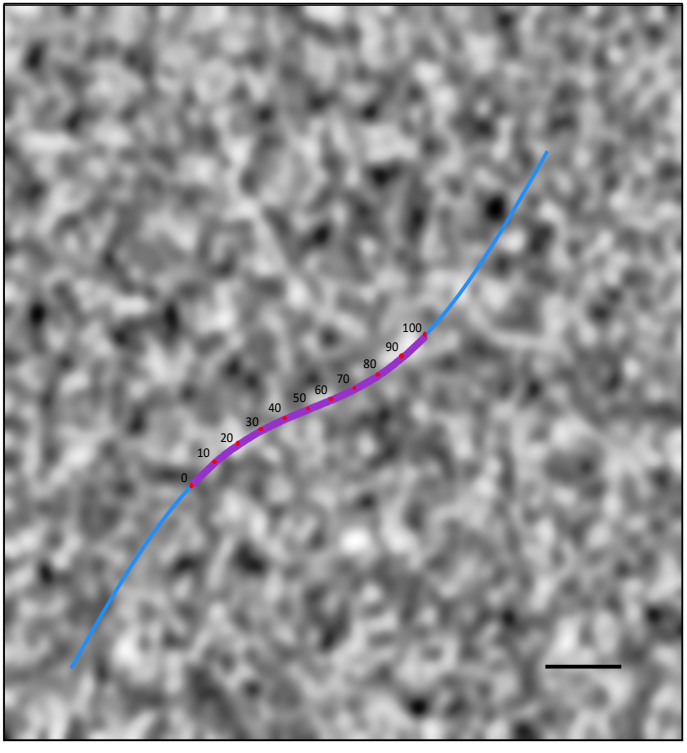


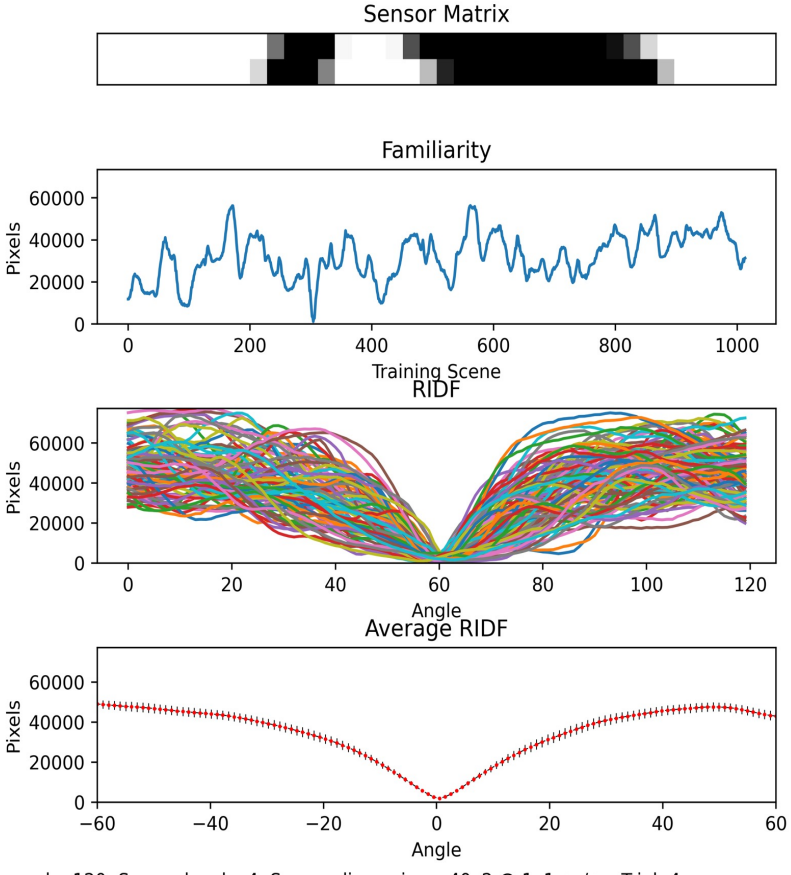


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4731.79; RMSD/dist: 11.829; TD: 20396; p90: 54; p50: 30; complete: 0

100%

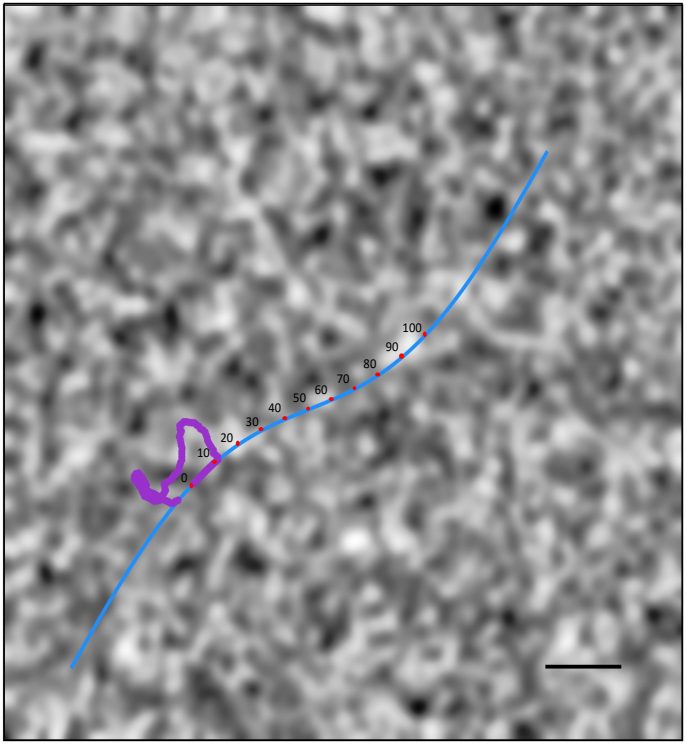


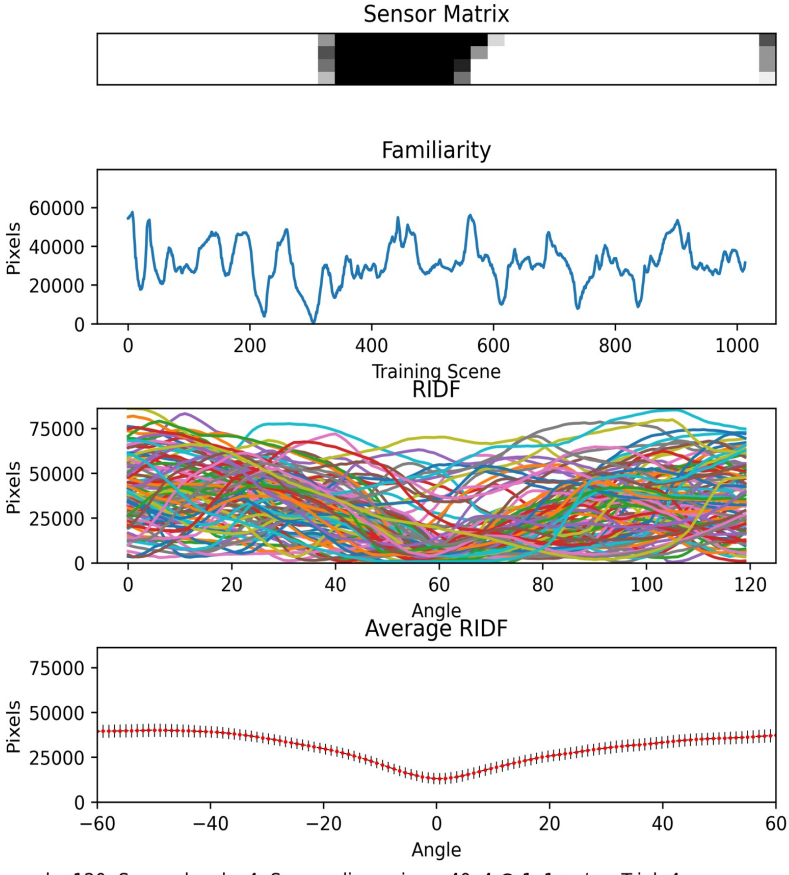


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 32.05; RMSD/dist: 0.080; TD: 31507; p90: 38; p50: 20; complete: 0

10%

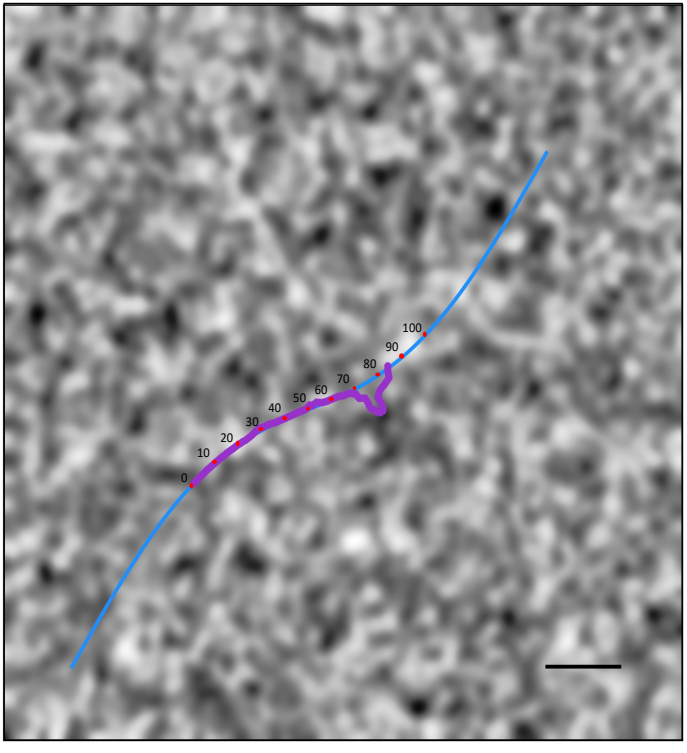


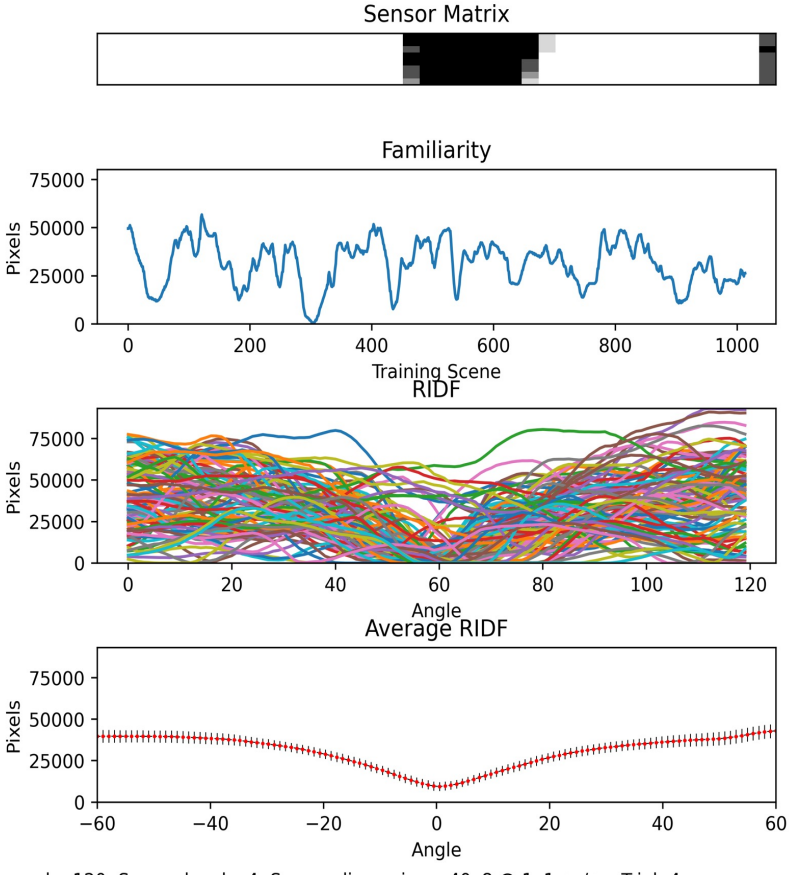


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3460.34; RMSD/dist: 8.651; TD: 18790; p90: 42; p50: 24; complete: 0

50%

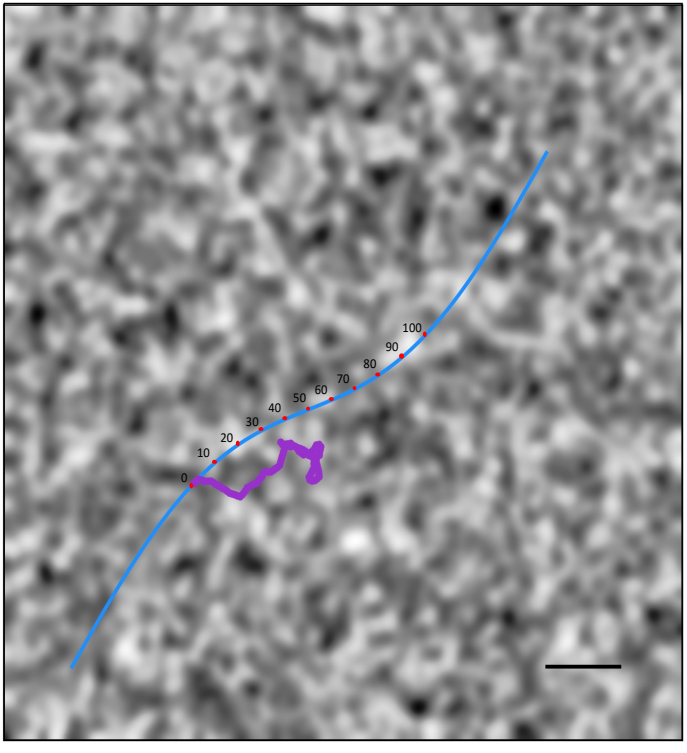


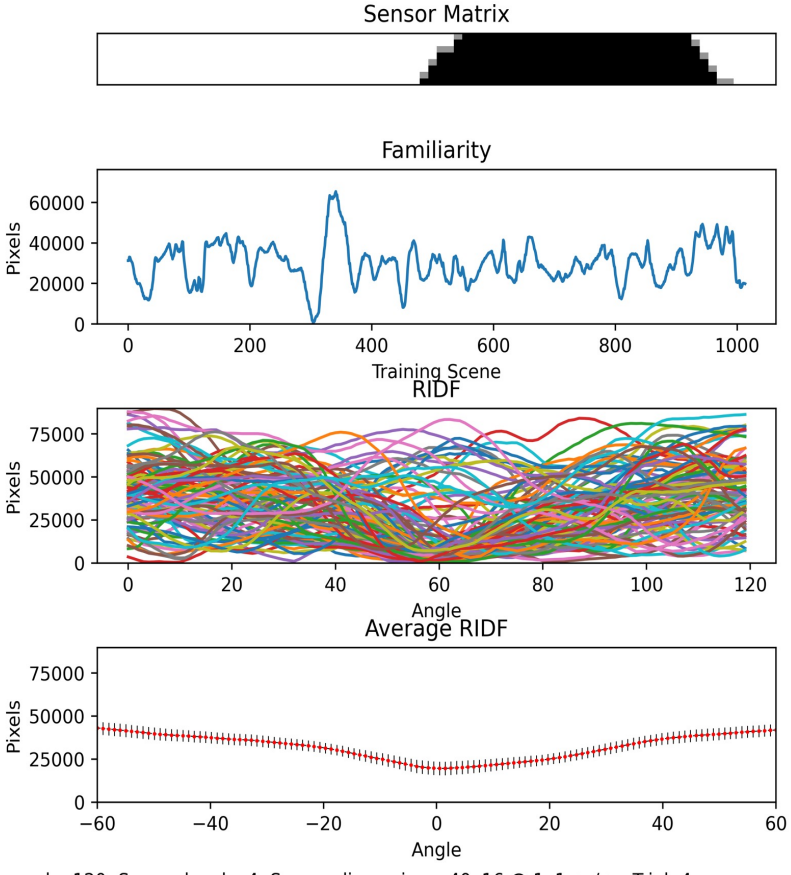


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 798.07; RMSD/dist: 1.995; TD: 20827; p90: 38; p50: 22; complete: 0

0%

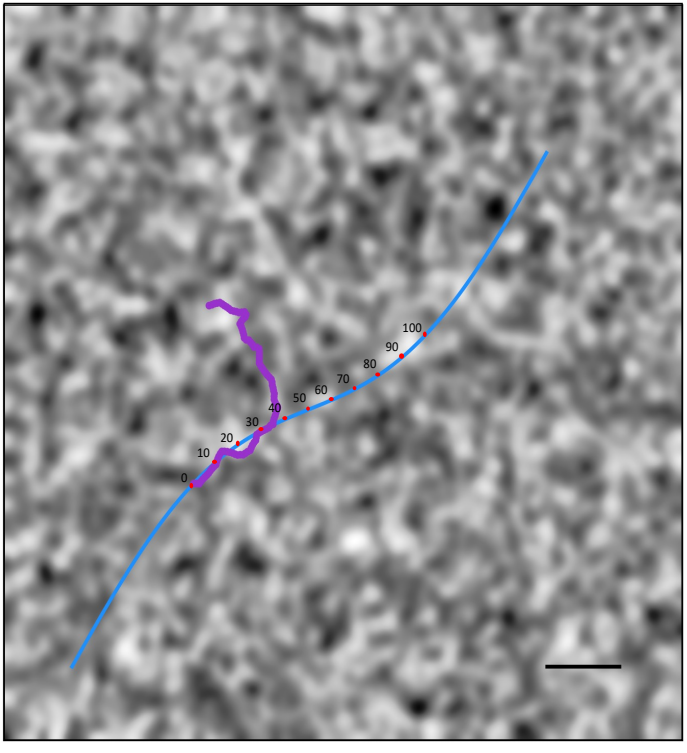


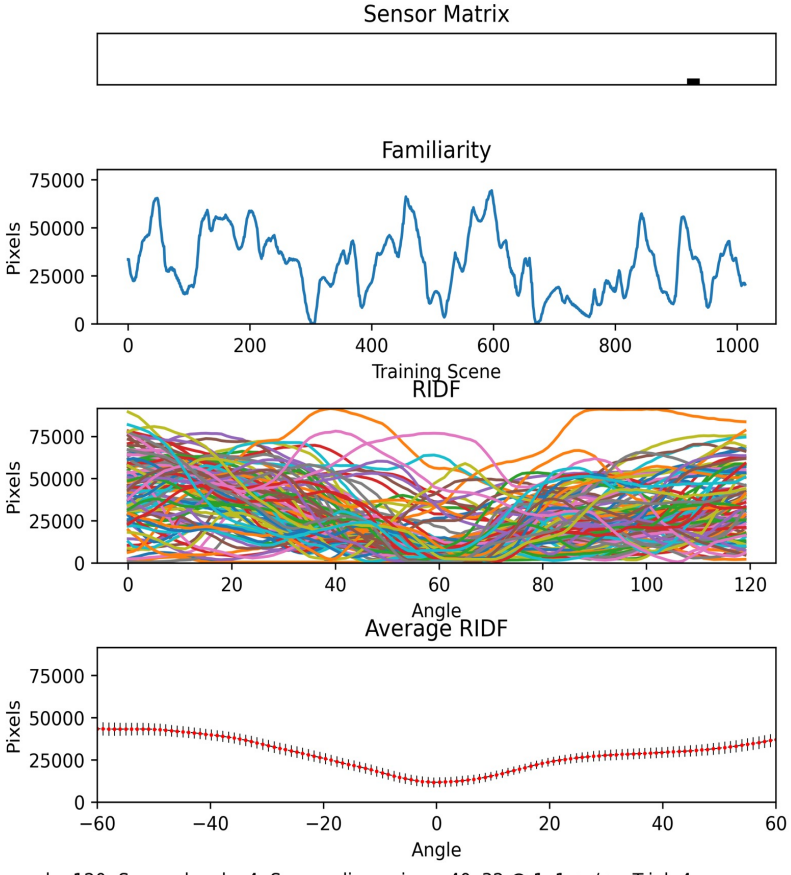


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 5073.31; RMSD/dist: 12.683; TD: 14730; p90: 46; p50: 26; complete: 0

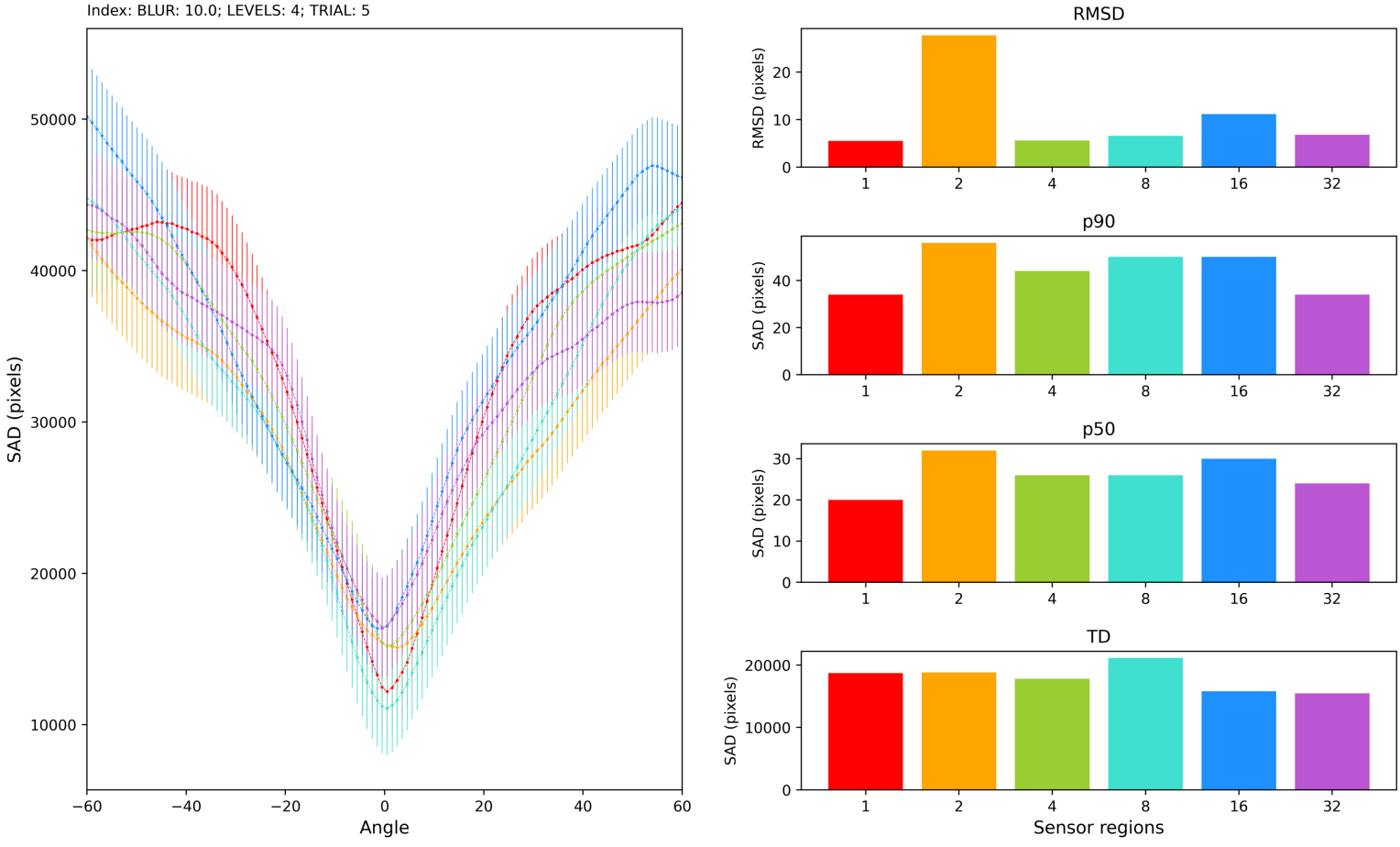
0%



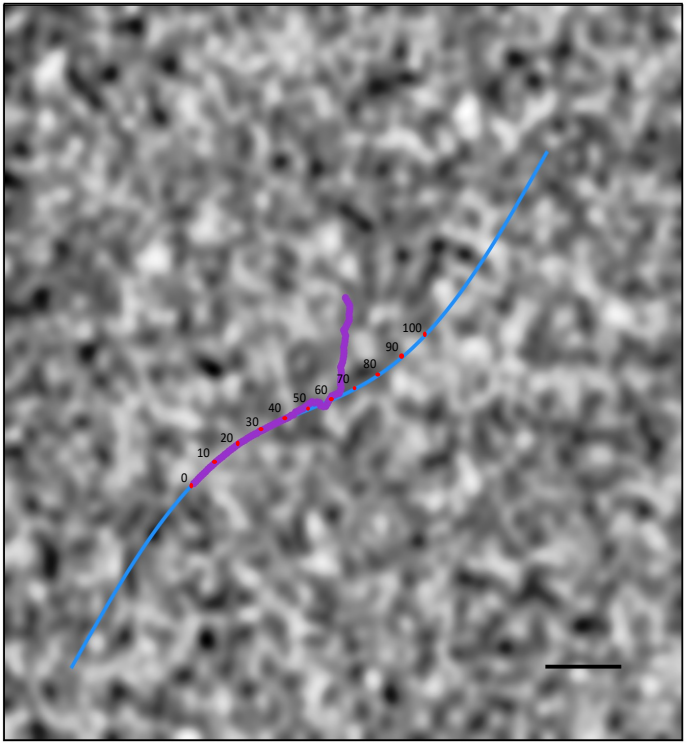


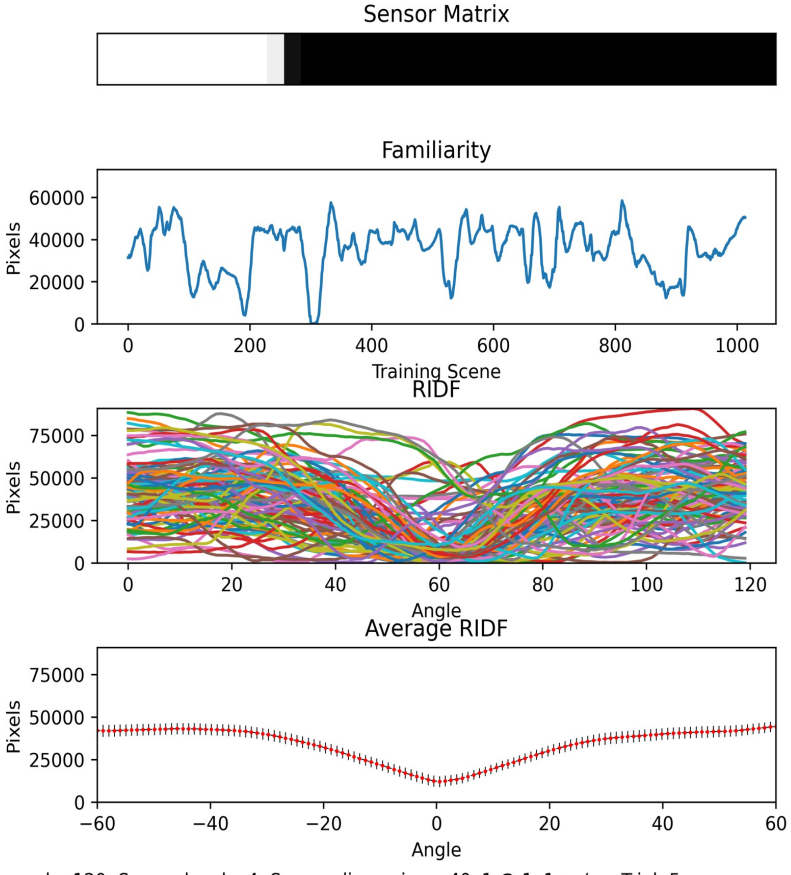
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 6399.12; RMSD/dist: 15.998; TD: 20002; p90: 50; p50: 30; complete: 0


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

40%

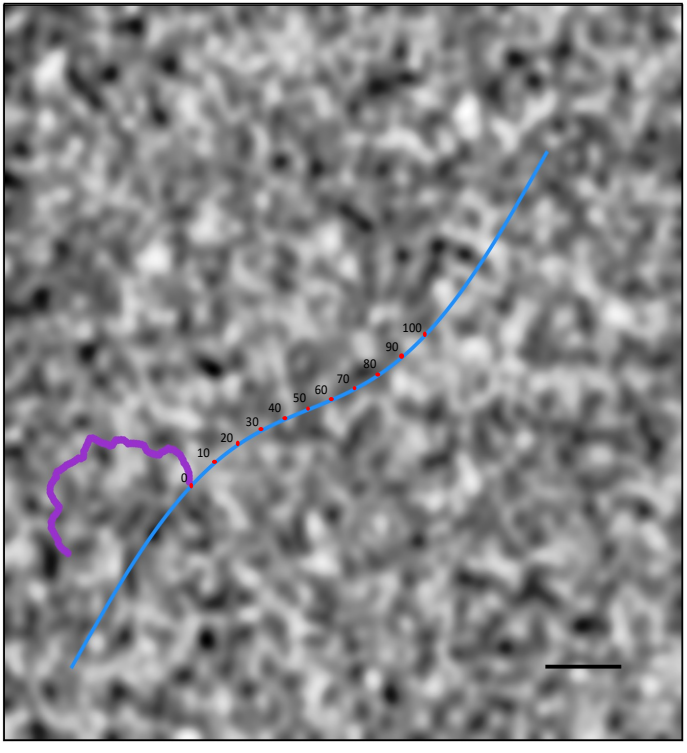


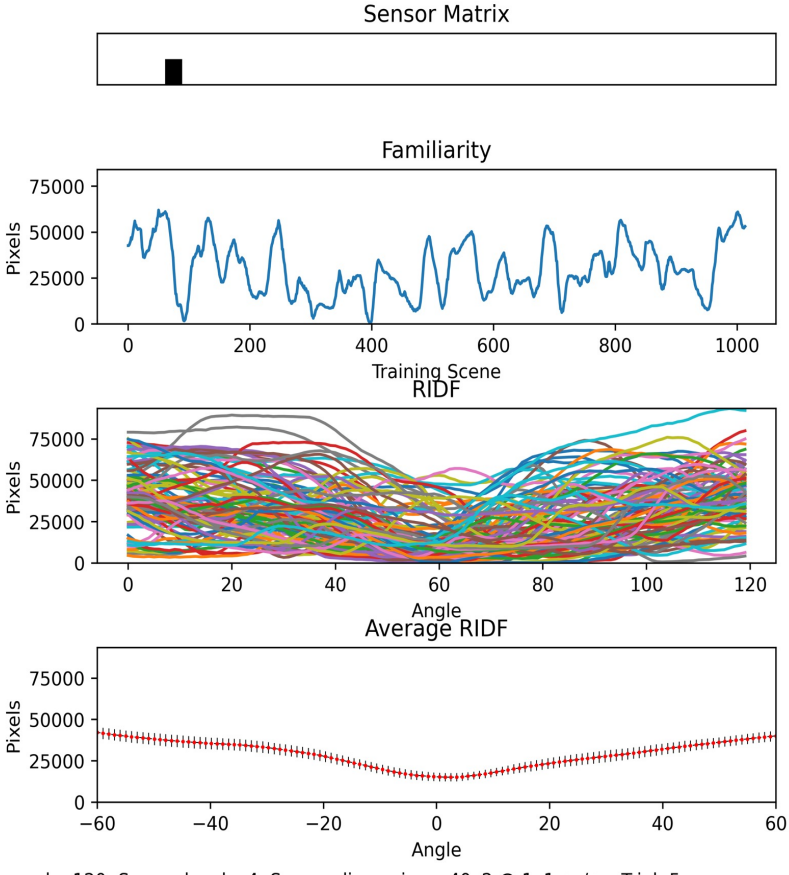


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2209.30; RMSD/dist: 5.523; TD: 18694; p90: 34; p50: 20; complete: 0

0%

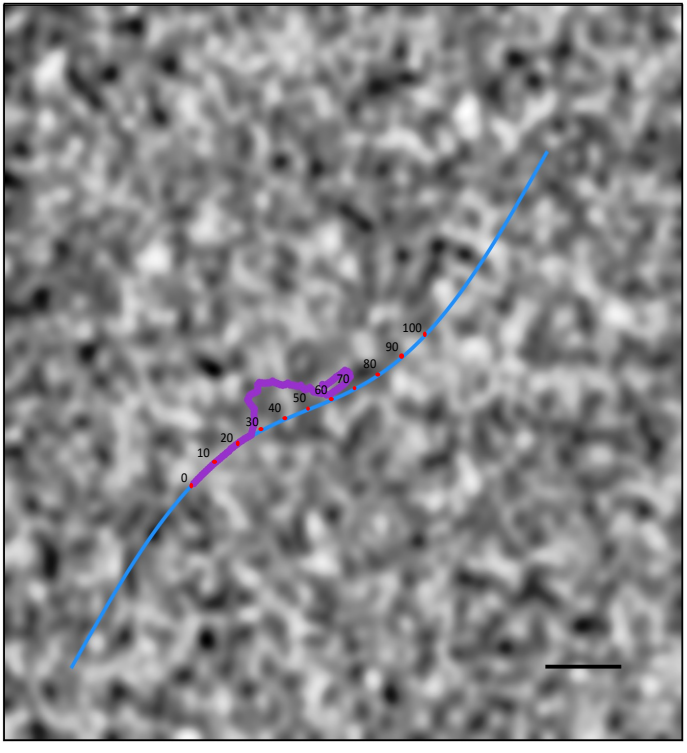


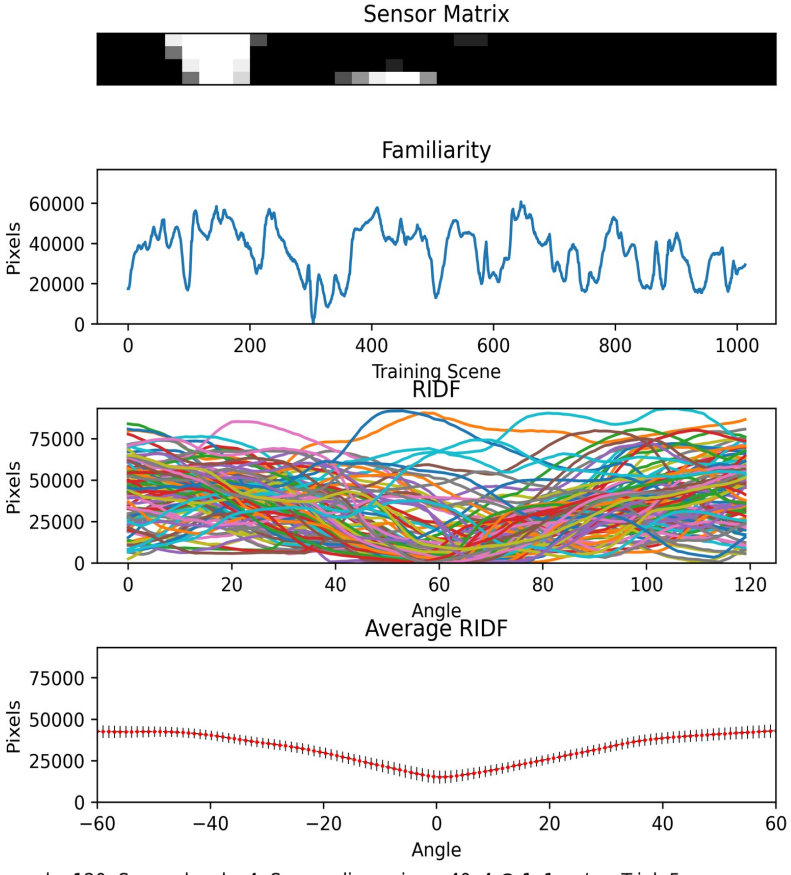


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 11113.95; RMSD/dist: 27.785; TD: 18818; p90: 56; p50: 32; complete: 0

20%

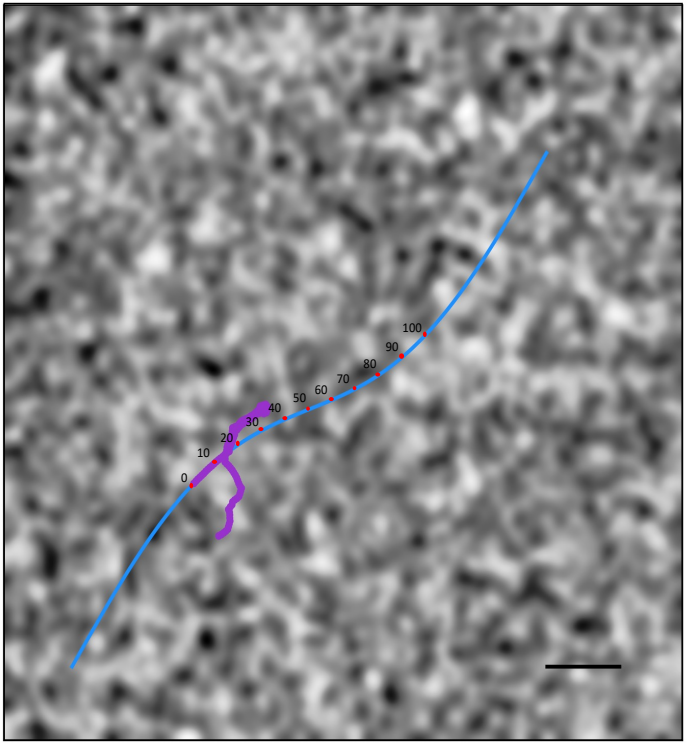


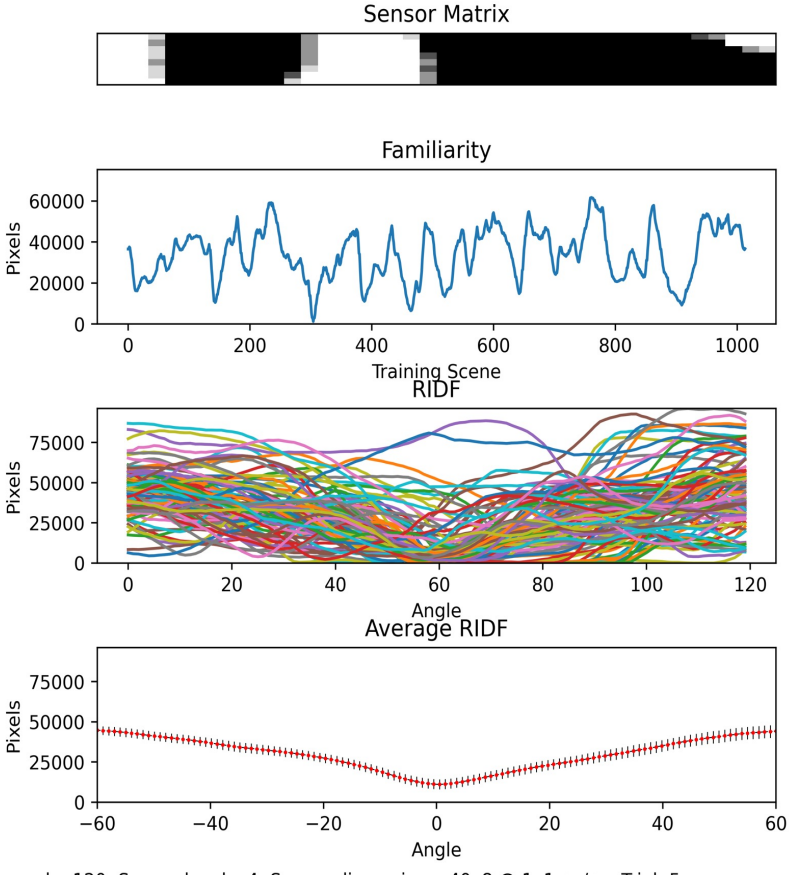


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2230.30; RMSD/dist: 5.576; TD: 17803; p90: 44; p50: 26; complete: 0

10%

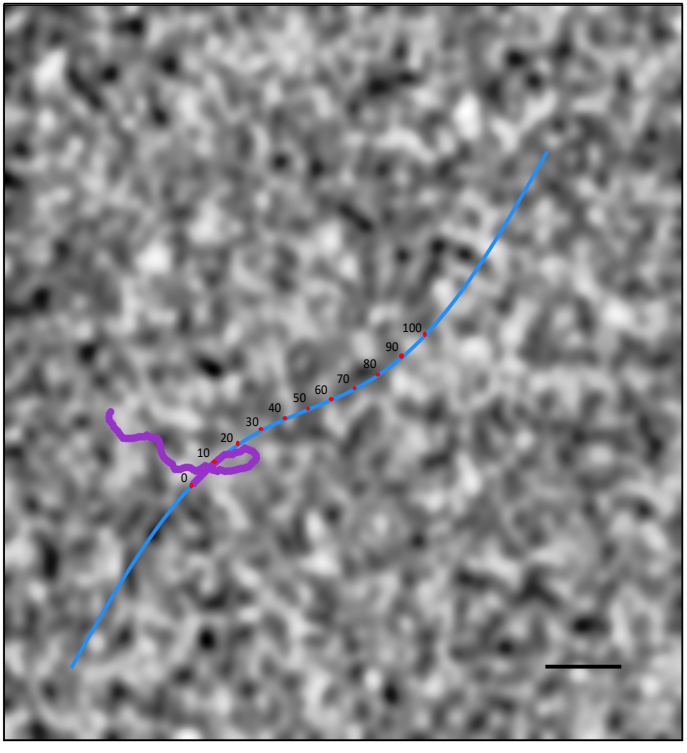


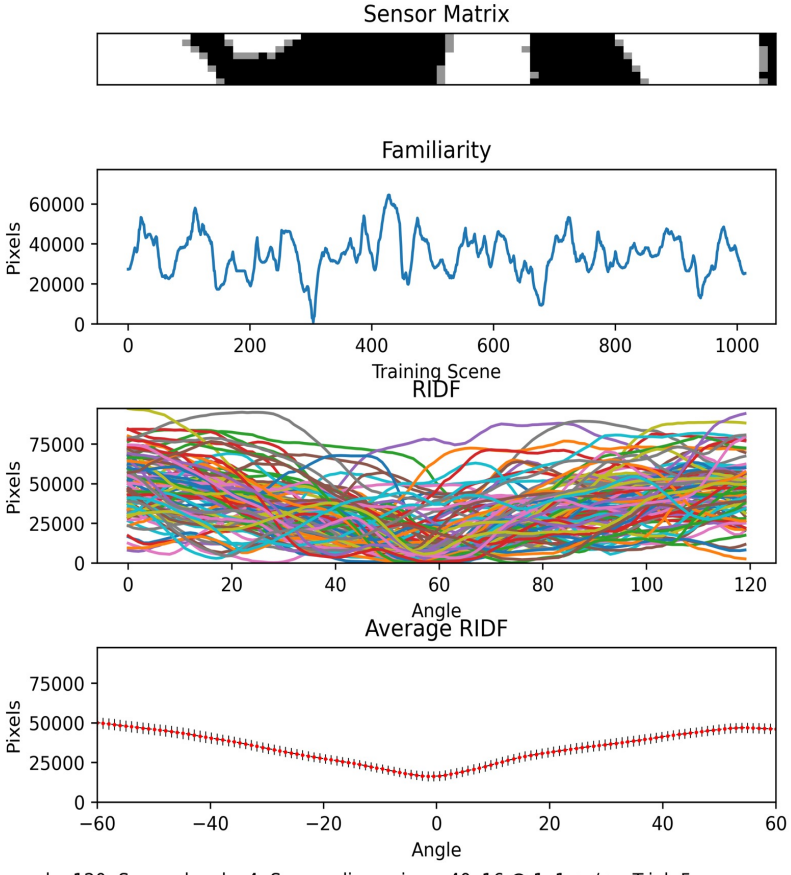


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2635.04; RMSD/dist: 6.588; TD: 21122; p90: 50; p50: 26; complete: 0

10%

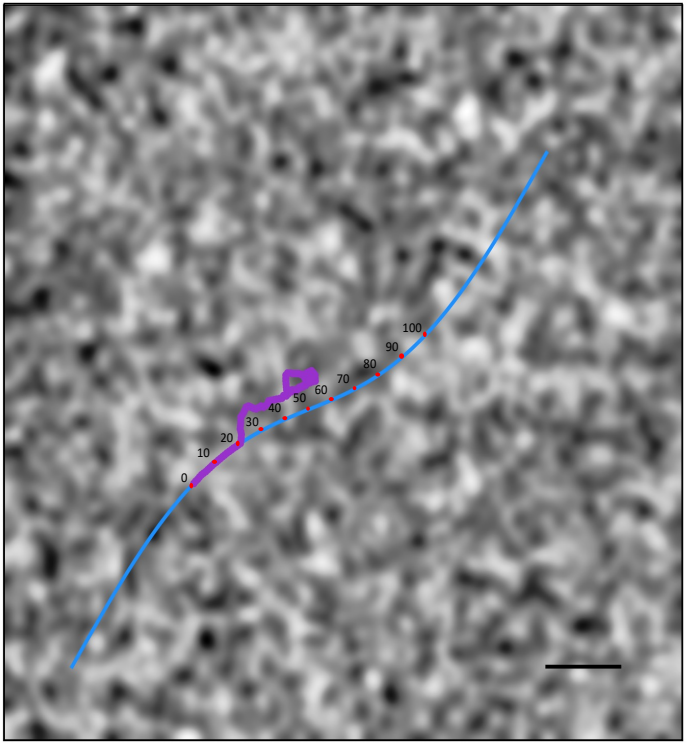


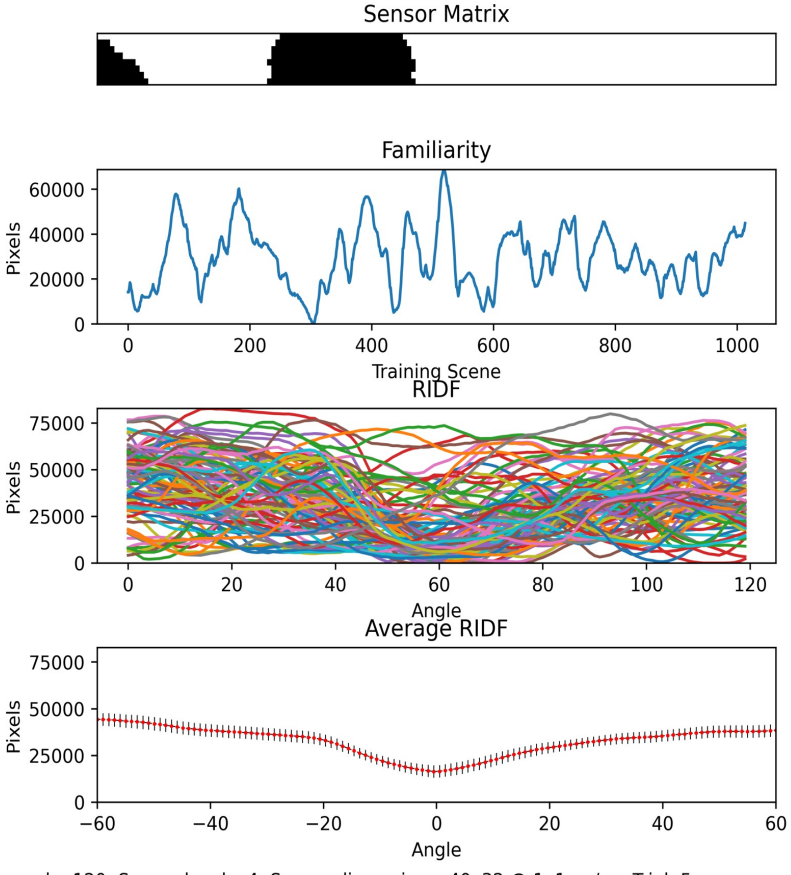


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 4468.78; RMSD/dist: 11.172; TD: 15785; p90: 50; p50: 30; complete: 0

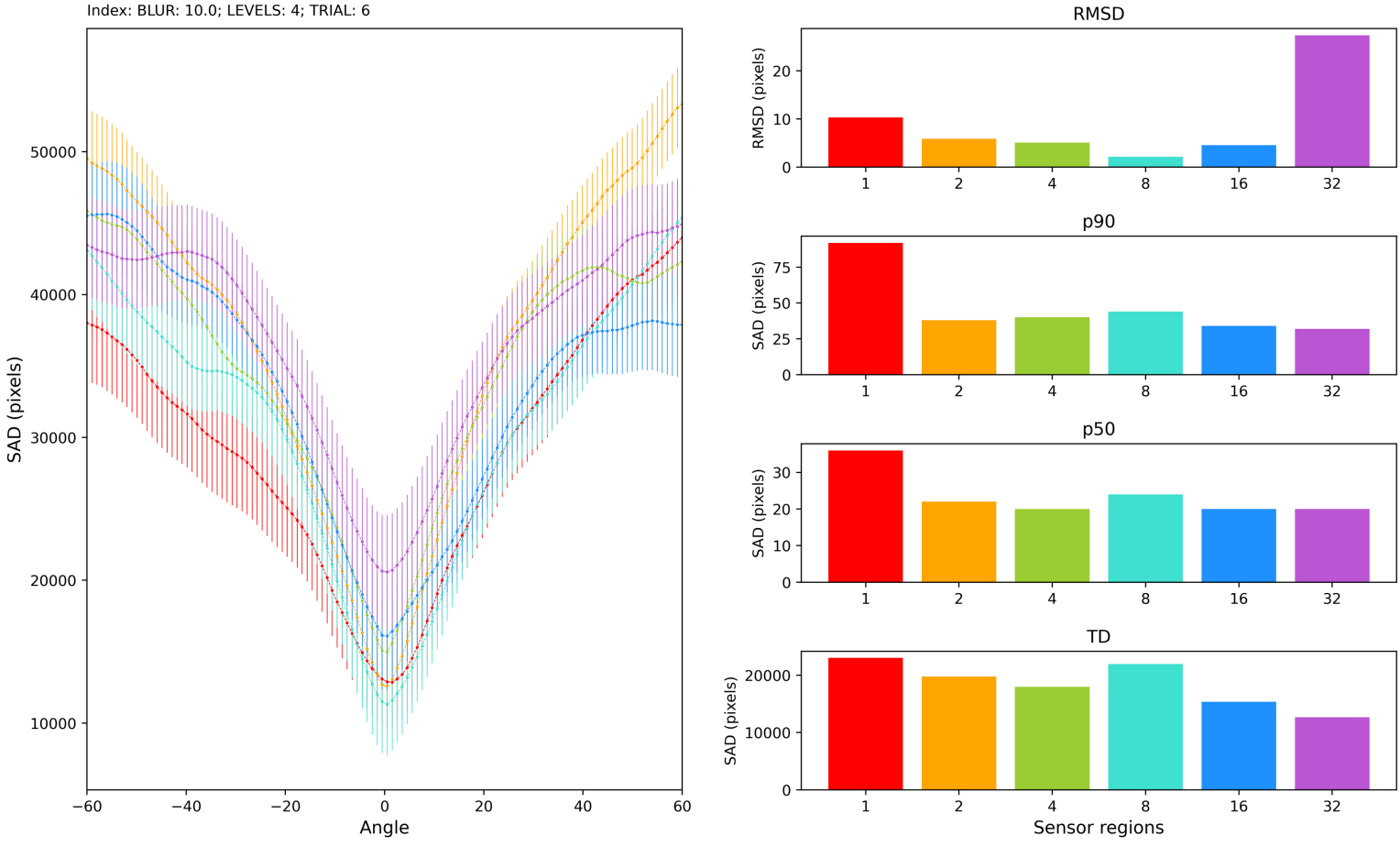
20%



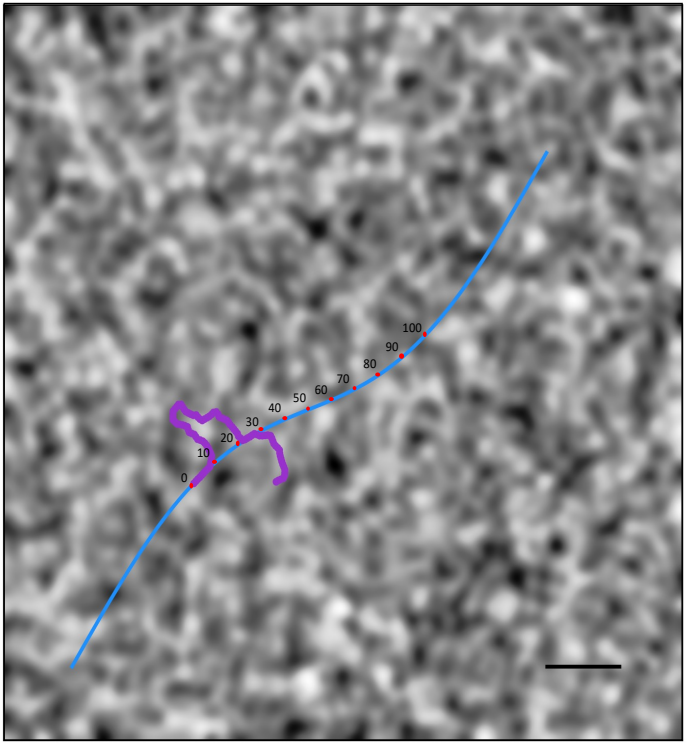


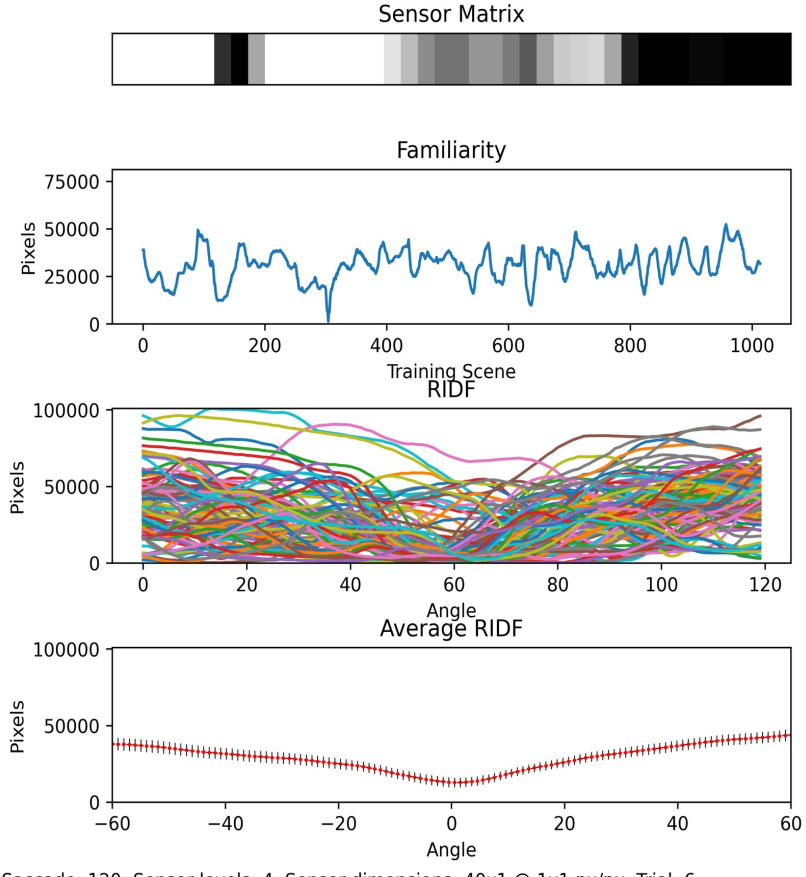
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2716.27; RMSD/dist: 6.791; TD: 15458; p90: 34; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 6
SAD (pixels)
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0
10
20
1
2
4
8
16
32
p90
SAD (pixels)
0
25
50
75
p50
0
10
20
30
TD
0
10000
20000
Sensor regions

10%

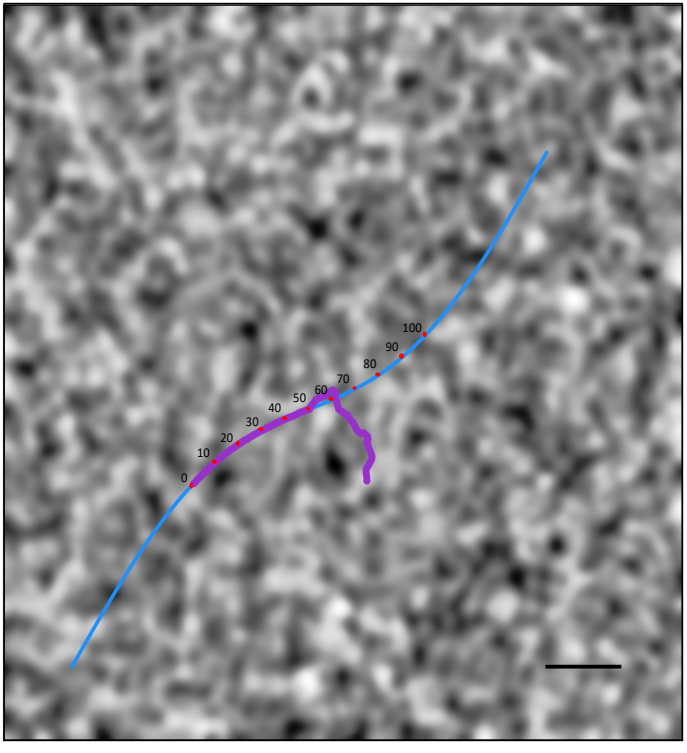


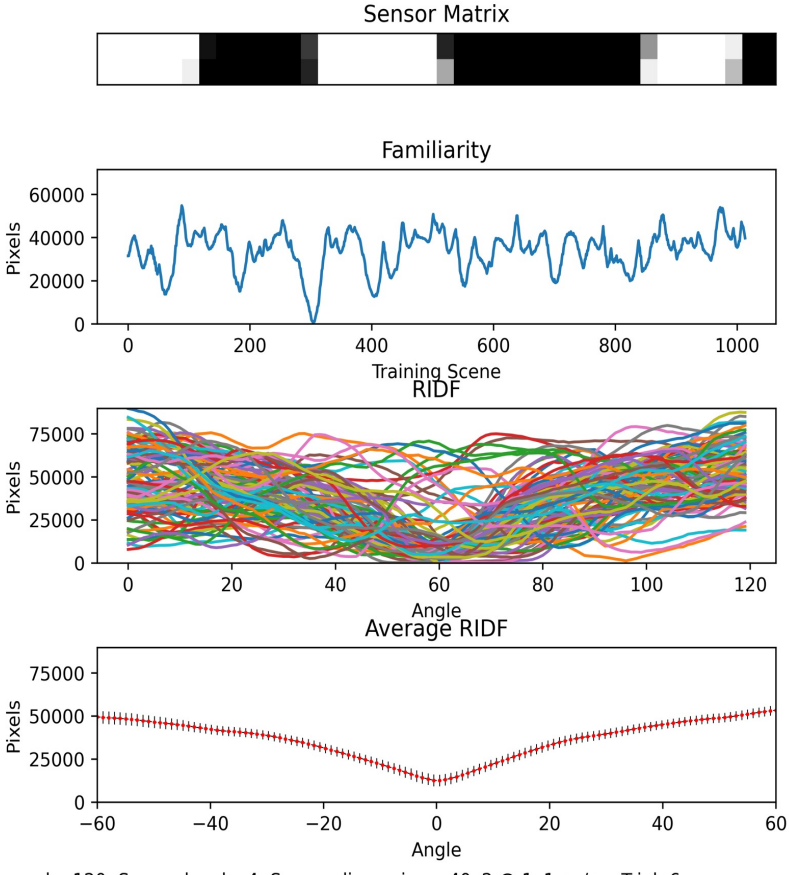


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4116.60; RMSD/dist: 10.291; TD: 23015; p90: 92; p50: 36; complete: 0

50%

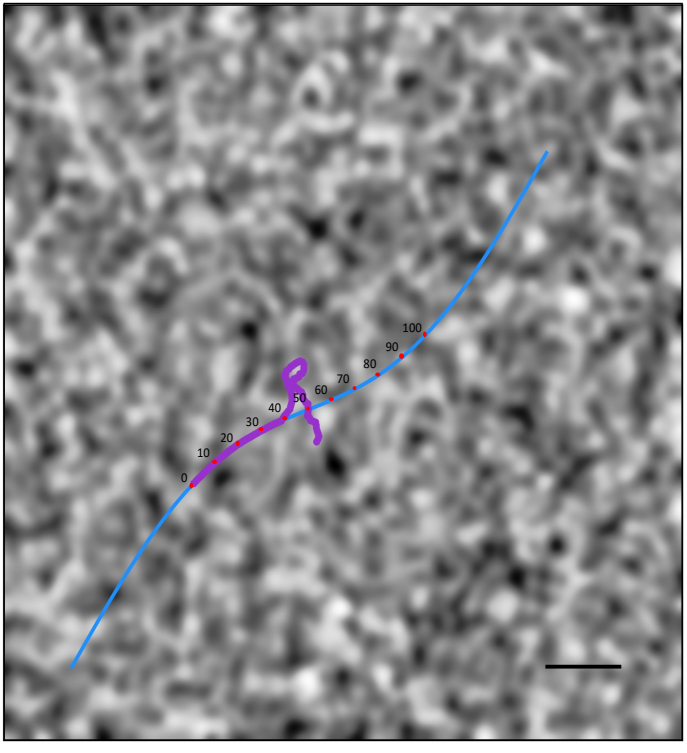


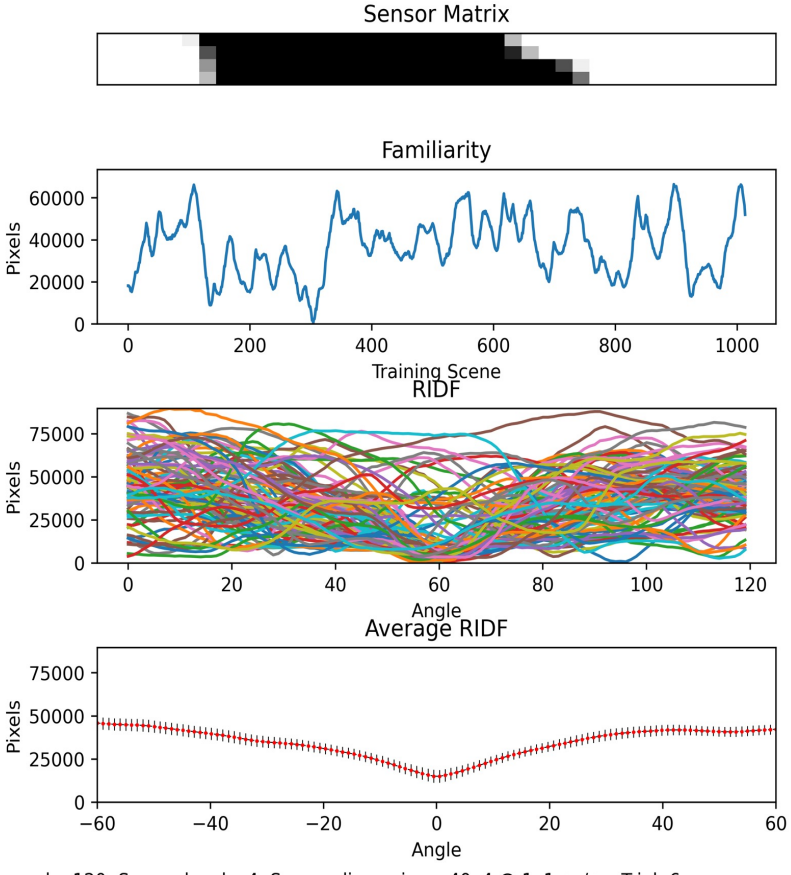


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2343.25; RMSD/dist: 5.858; TD: 19789; p90: 38; p50: 22; complete: 0

40%

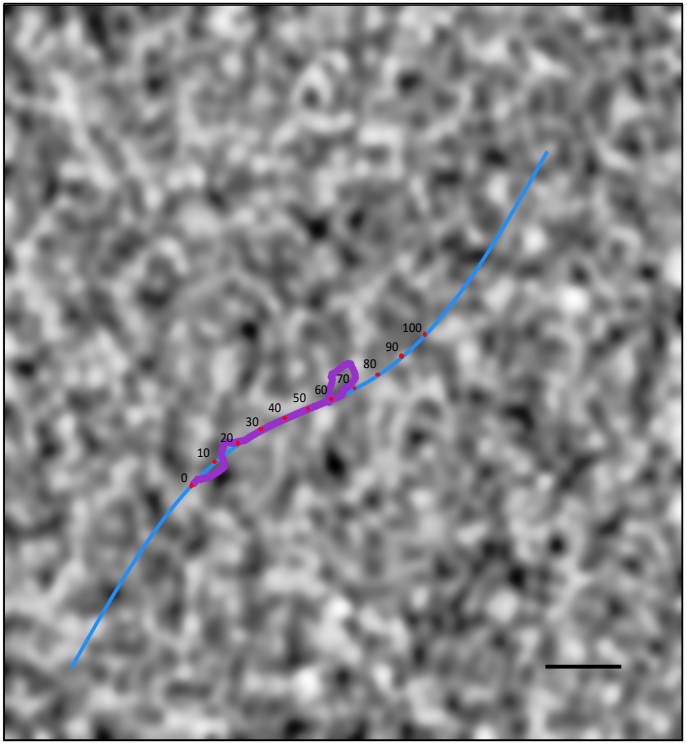


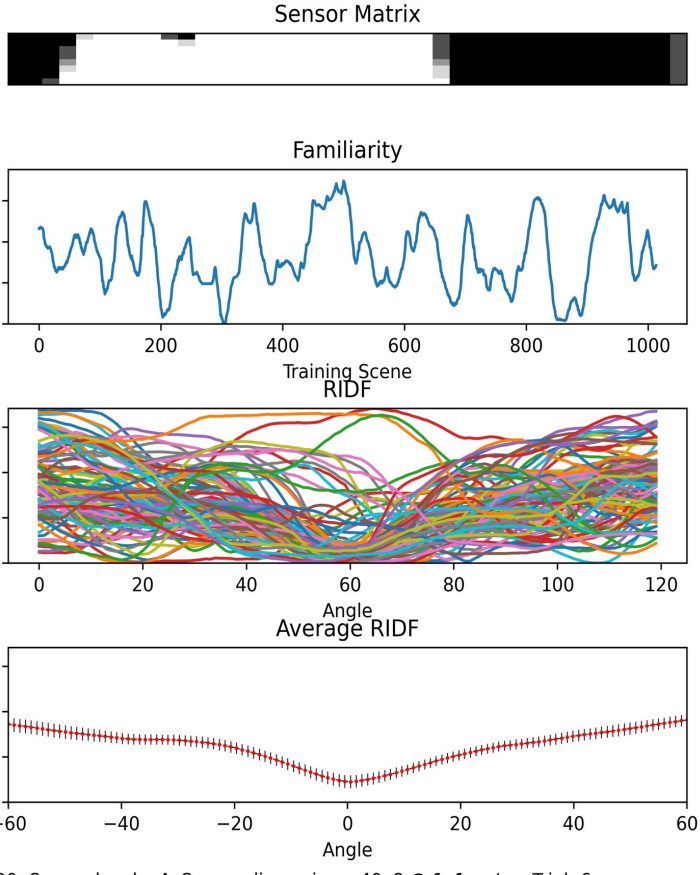


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2031.52; RMSD/dist: 5.079; TD: 17973; p90: 40; p50: 20; complete: 0

40%

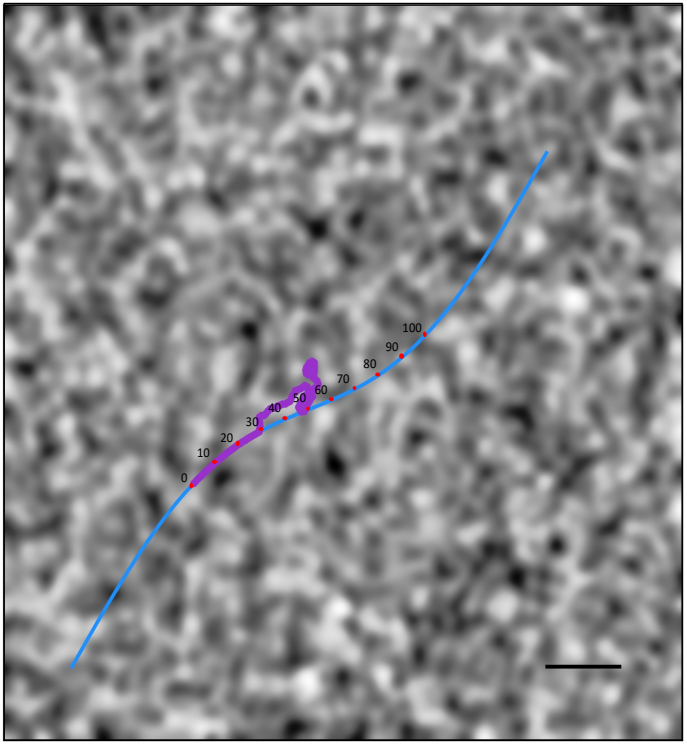


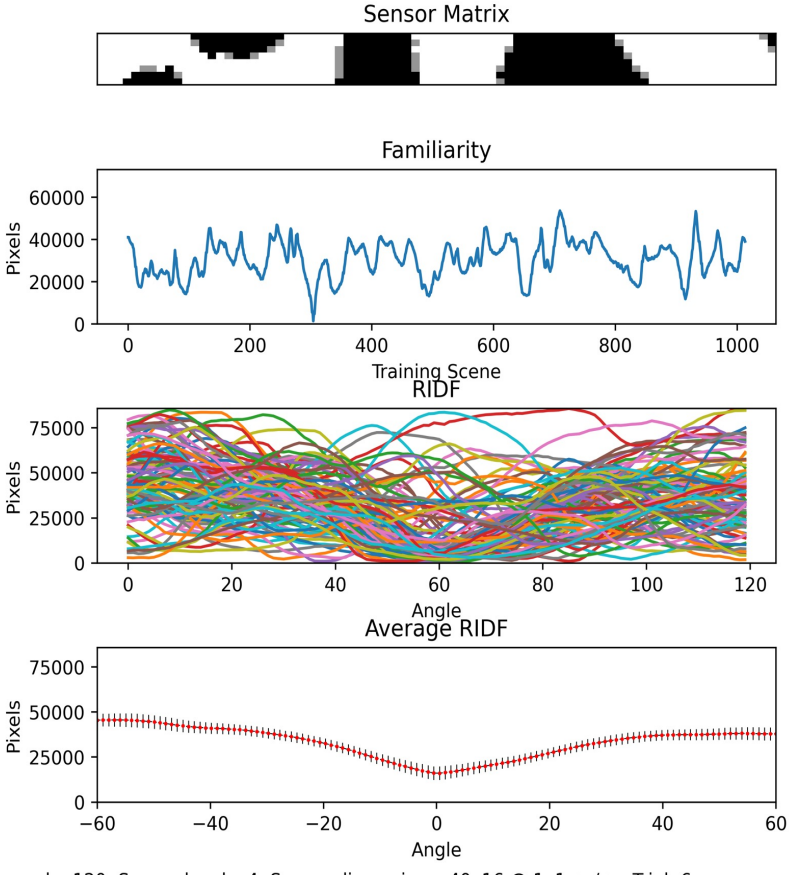


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 854.31; RMSD/dist: 2.136; TD: 21968; p90: 44; p50: 24; complete: 0

30%

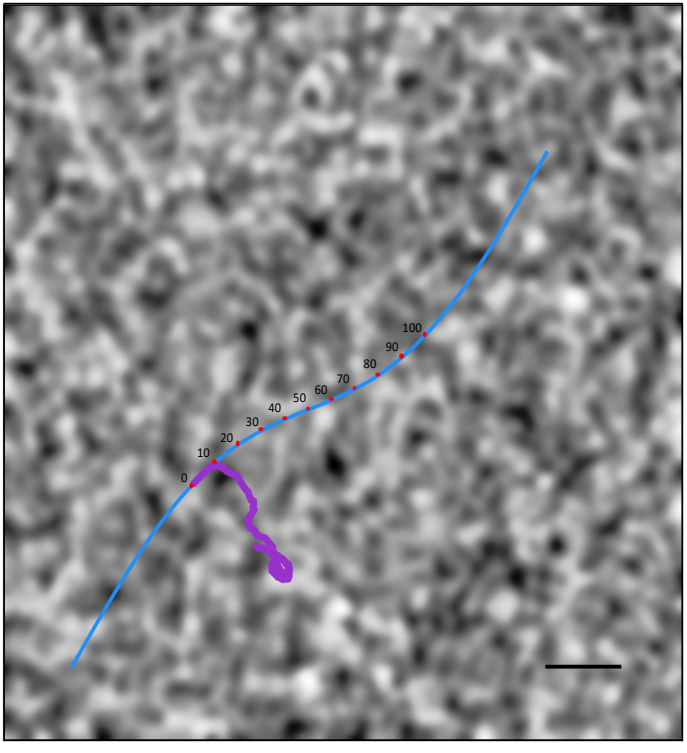


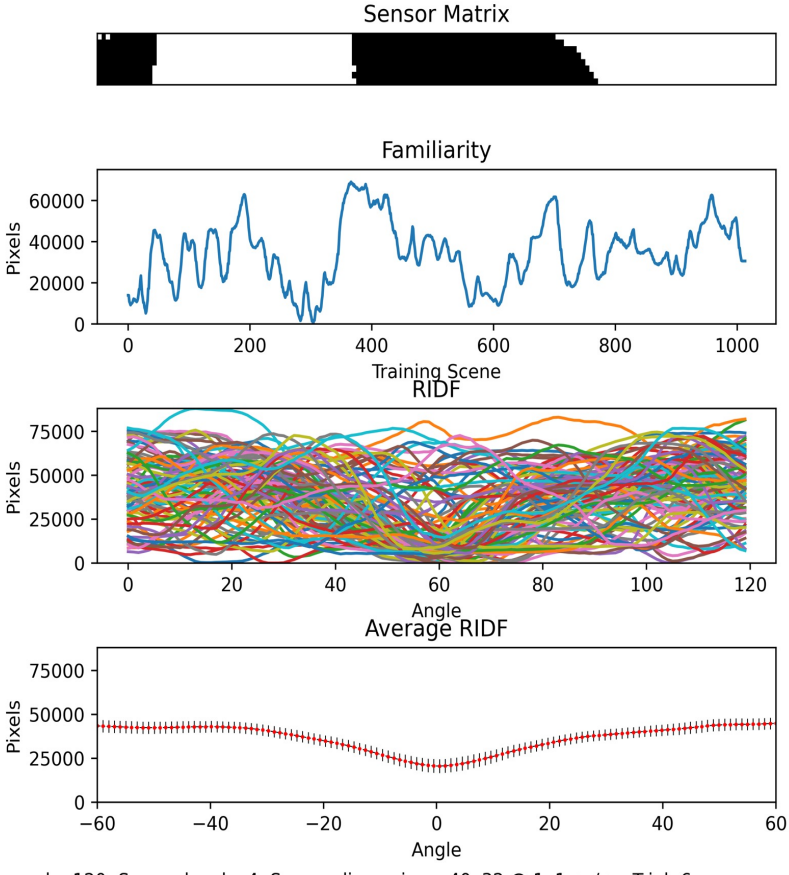


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1813.77; RMSD/dist: 4.534; TD: 15346; p90: 34; p50: 20; complete: 0

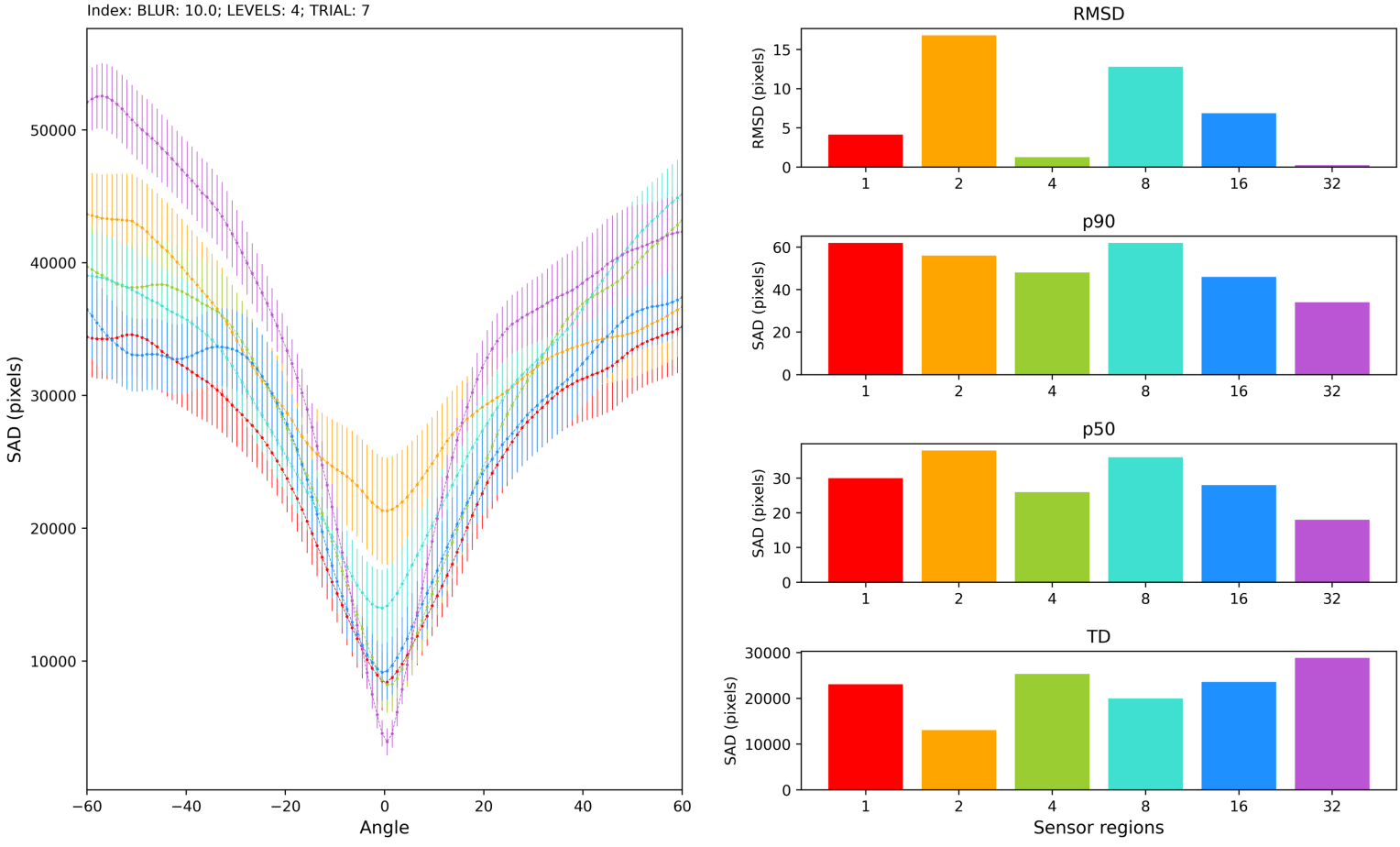
10%



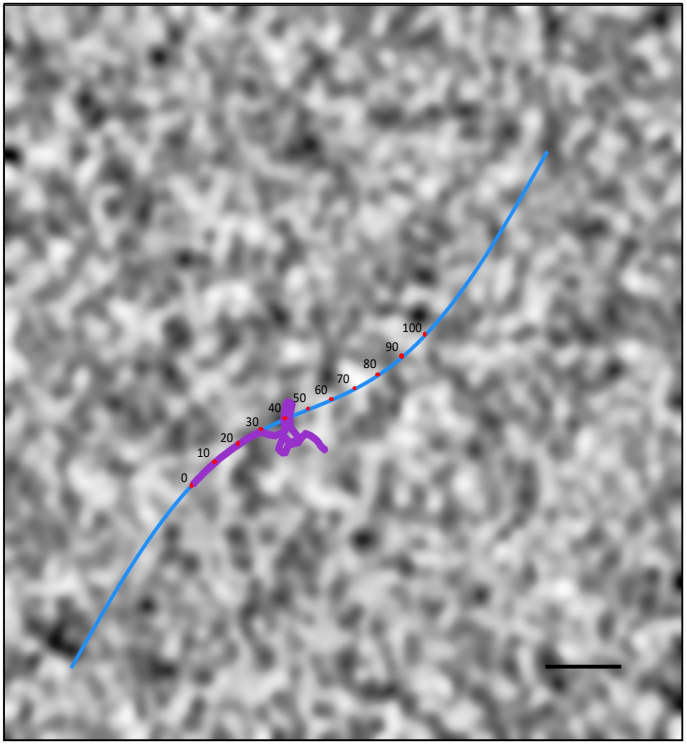


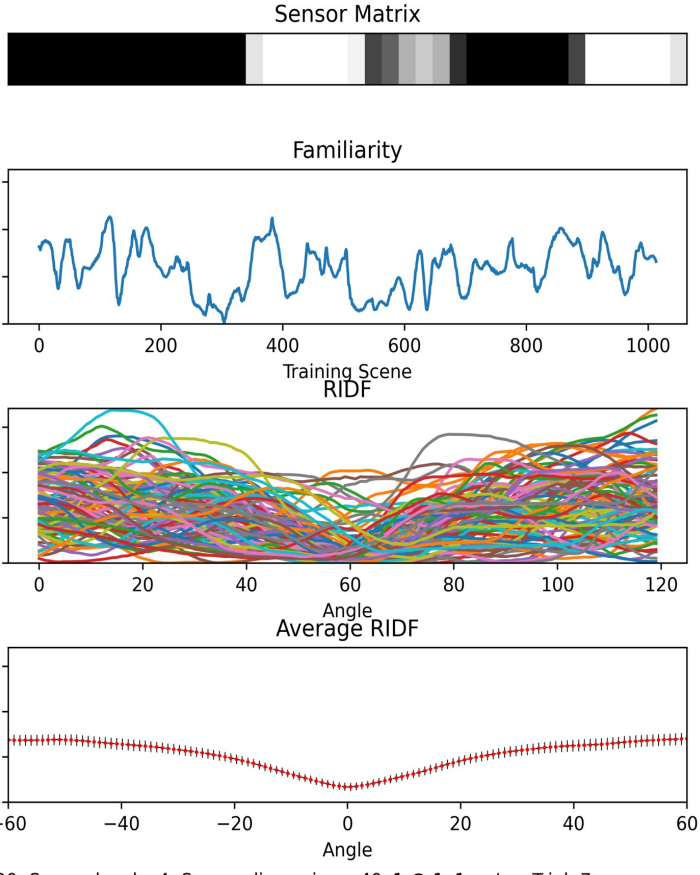
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 10956.98; RMSD/dist: 27.392; TD: 12654; p90: 32; p50: 20; complete: 0


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 7
SAD (pixels)
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
15
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
60
40
20
0
p50
30
20
10
TD
30000
20000
10000
Sensor regions

20%

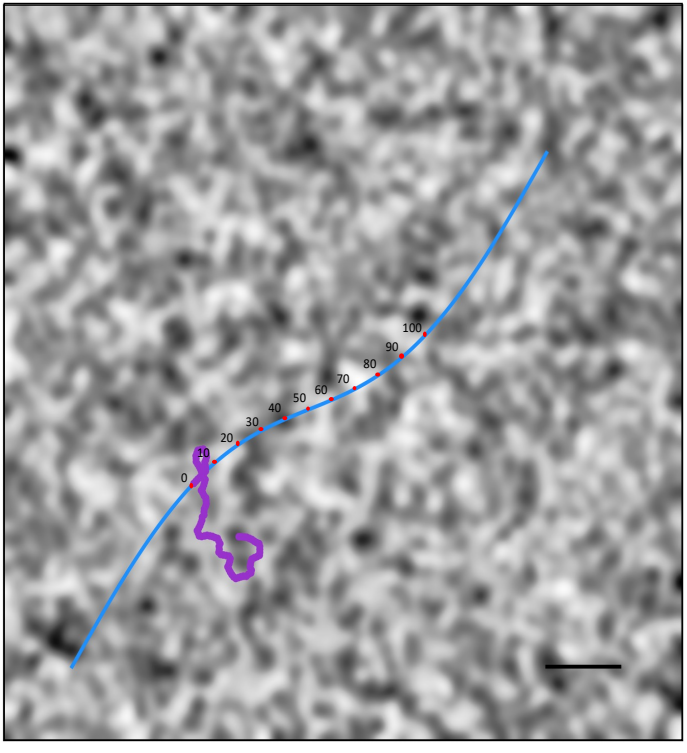


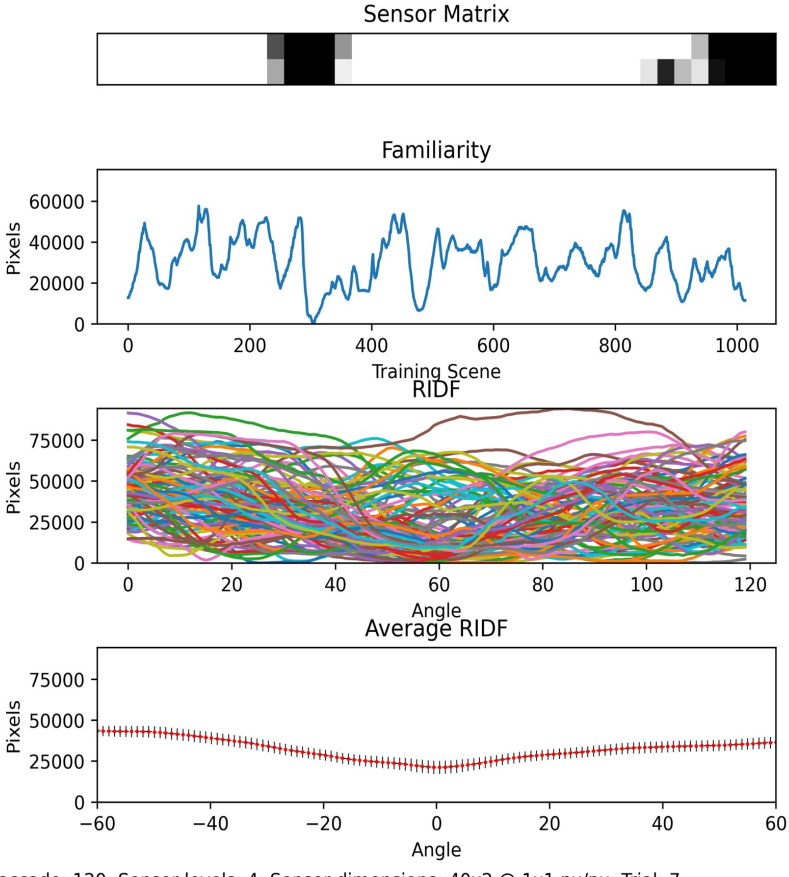


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1653.88; RMSD/dist: 4.135; TD: 23051; p90: 62; p50: 30; complete: 0

0%

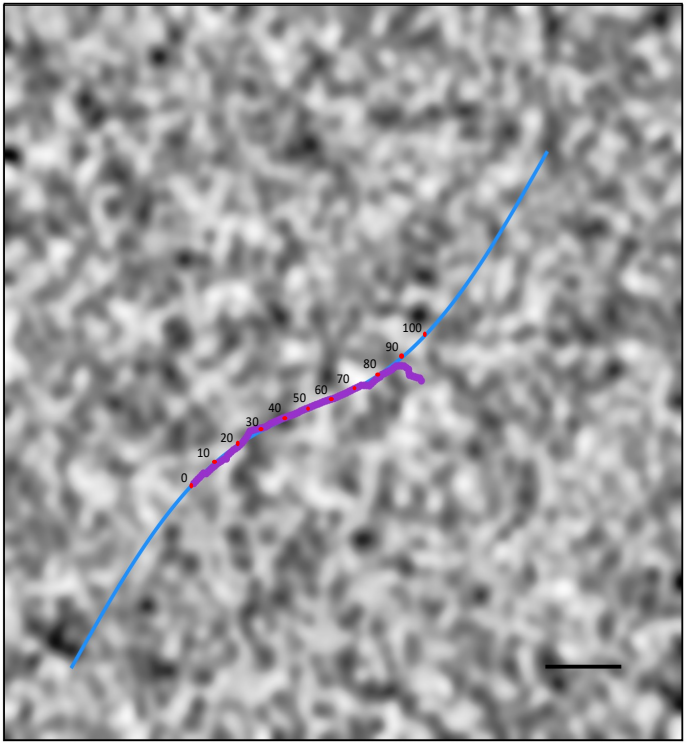


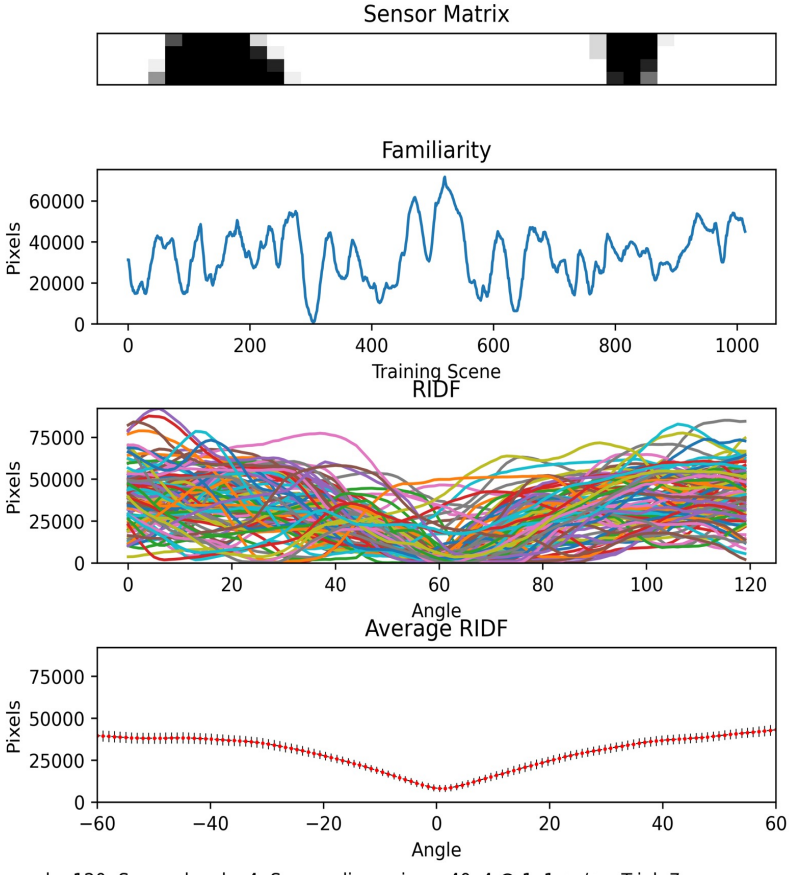


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 6726.07; RMSD/dist: 16.815; TD: 13051; p90: 56; p50: 38; complete: 0

40%

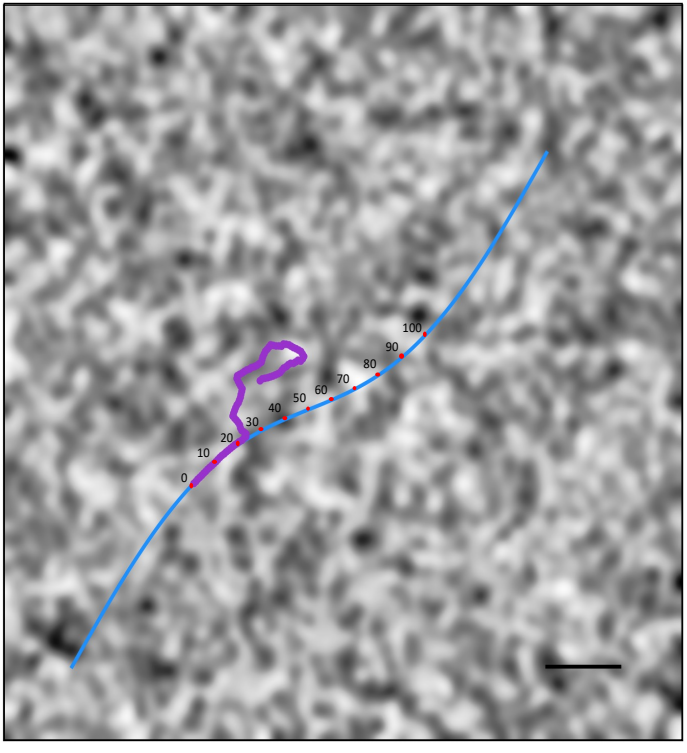


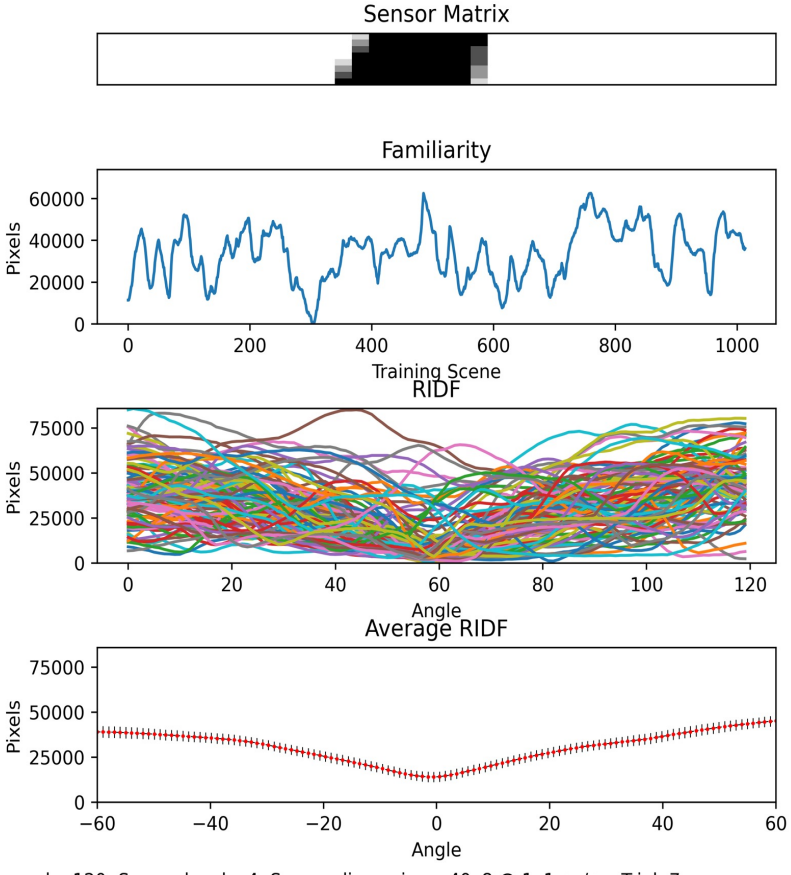


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 505.18; RMSD/dist: 1.263; TD: 25344; p90: 48; p50: 26; complete: 0

20%

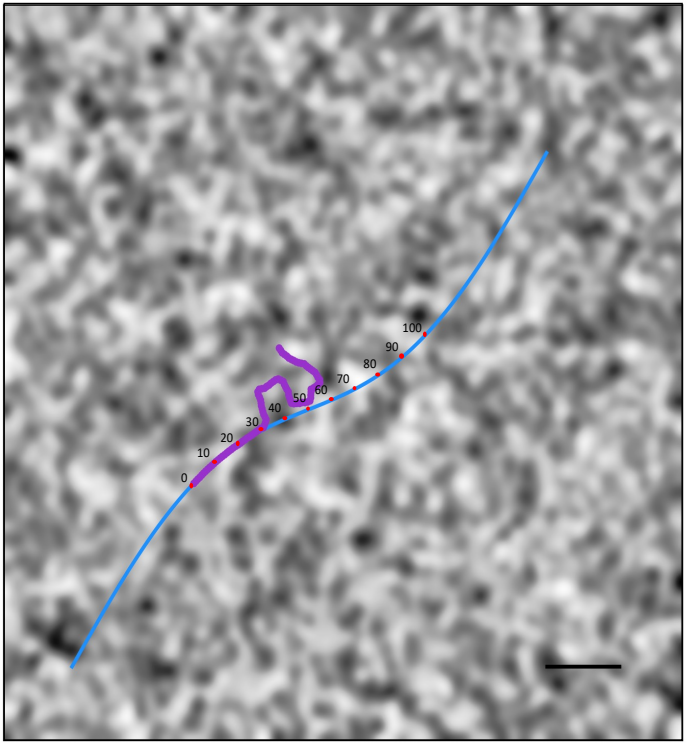


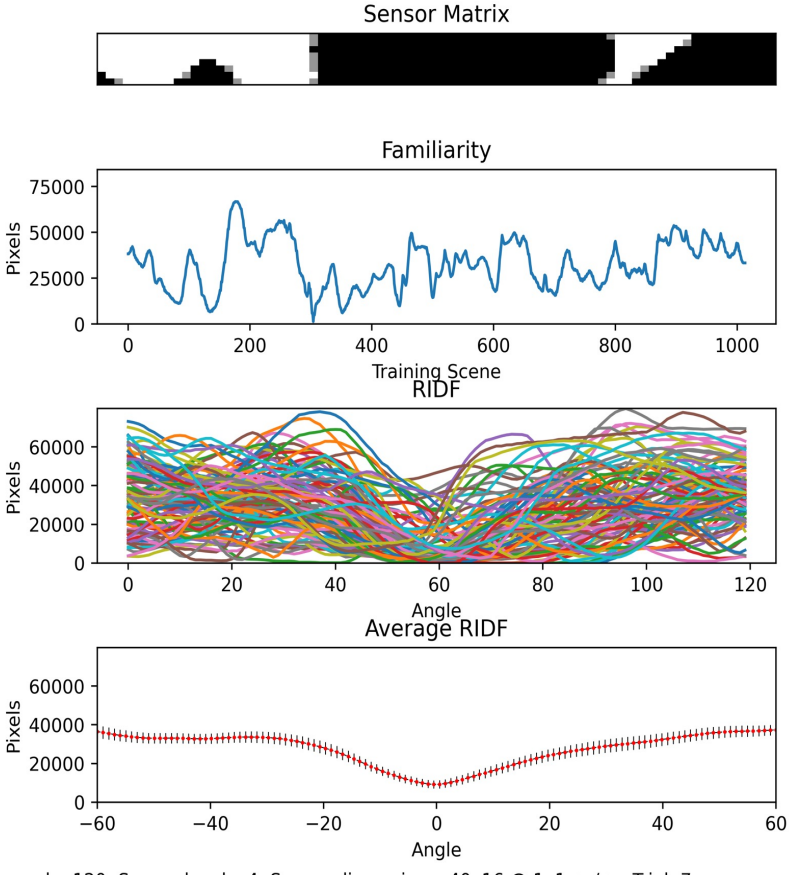


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 5115.98; RMSD/dist: 12.790; TD: 19965; p90: 62; p50: 36; complete: 0

30%

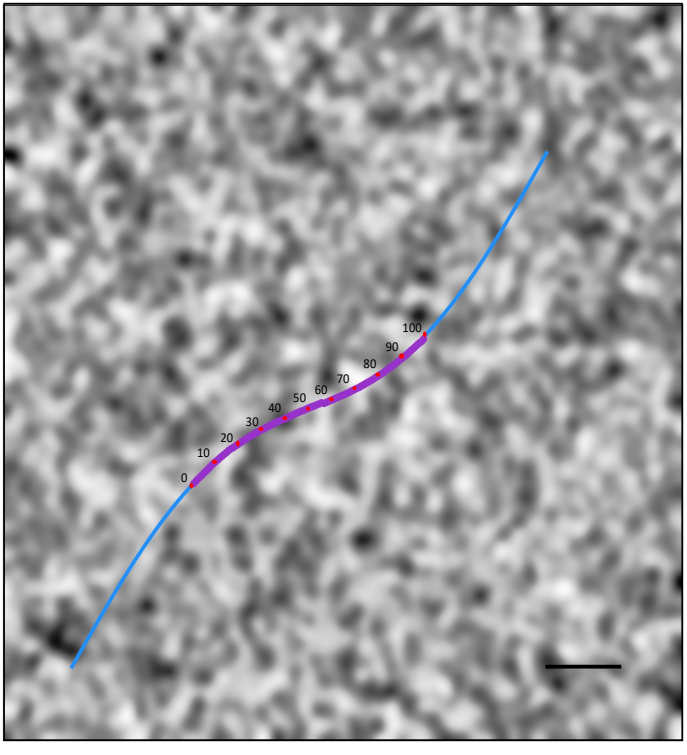


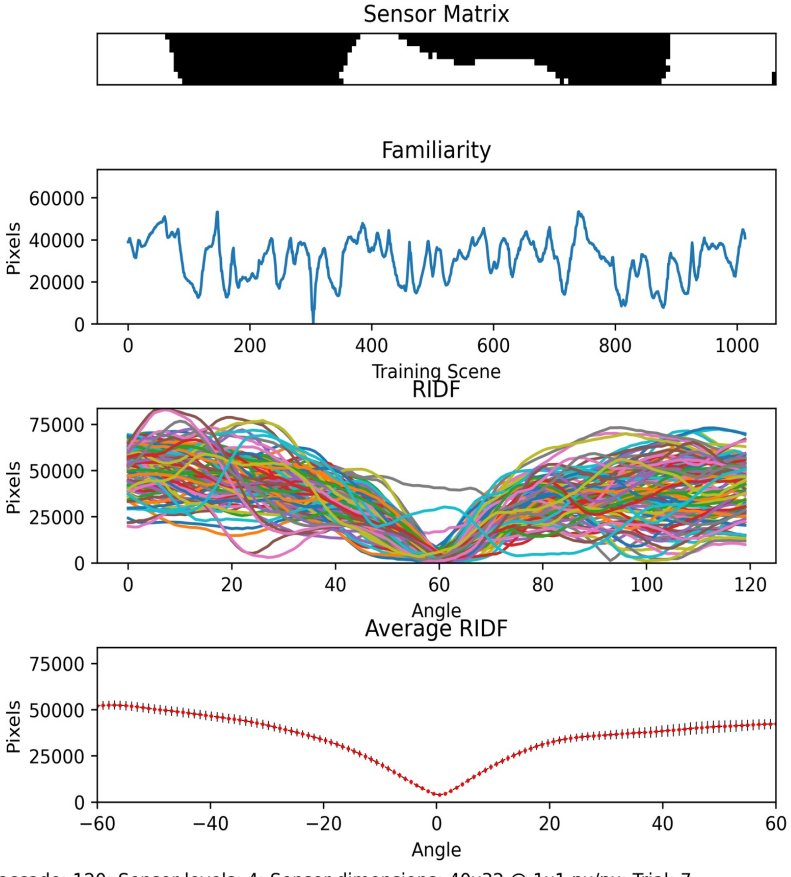


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2749.04; RMSD/dist: 6.873; TD: 23573; p90: 46; p50: 28; complete: 0

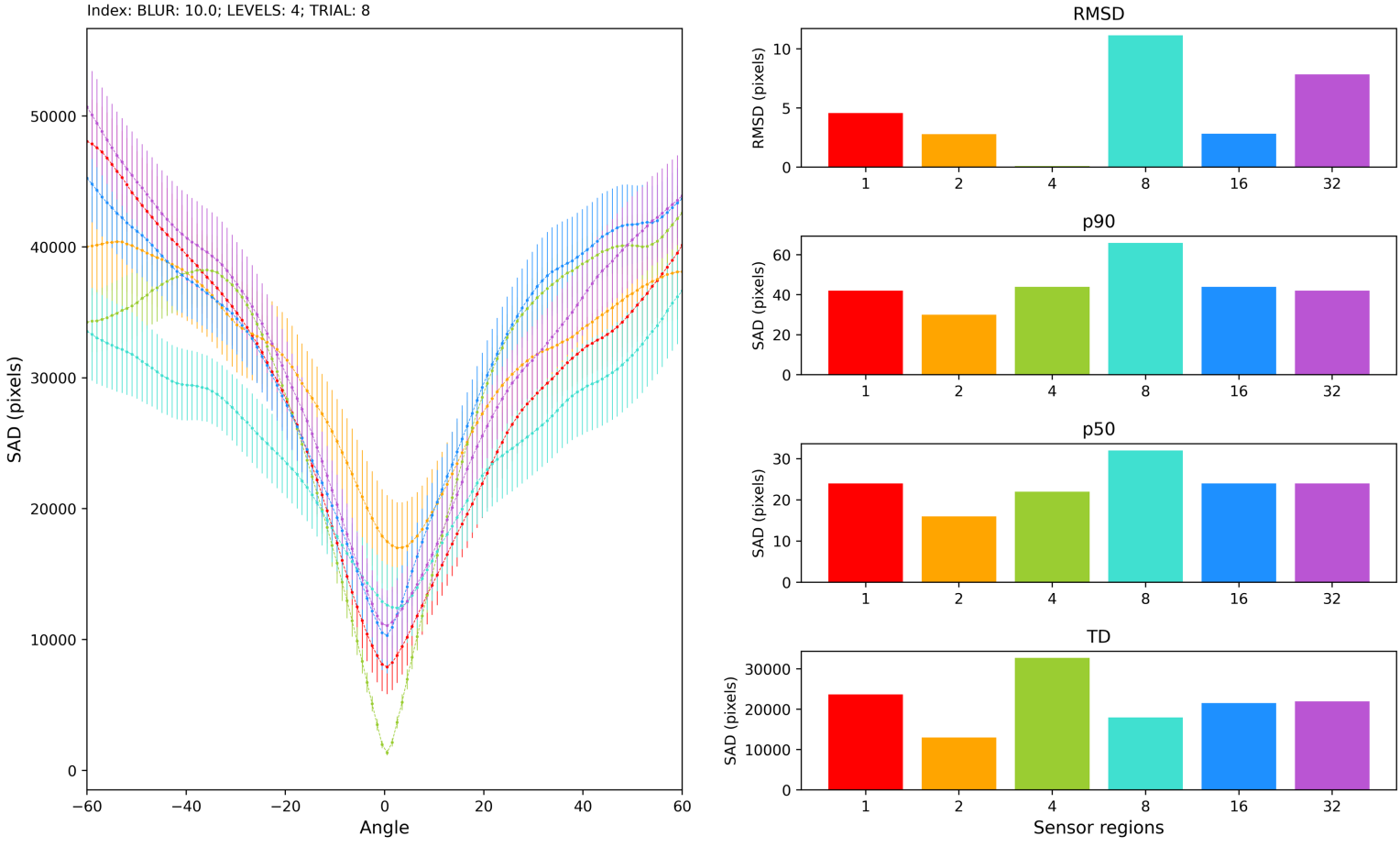
90%



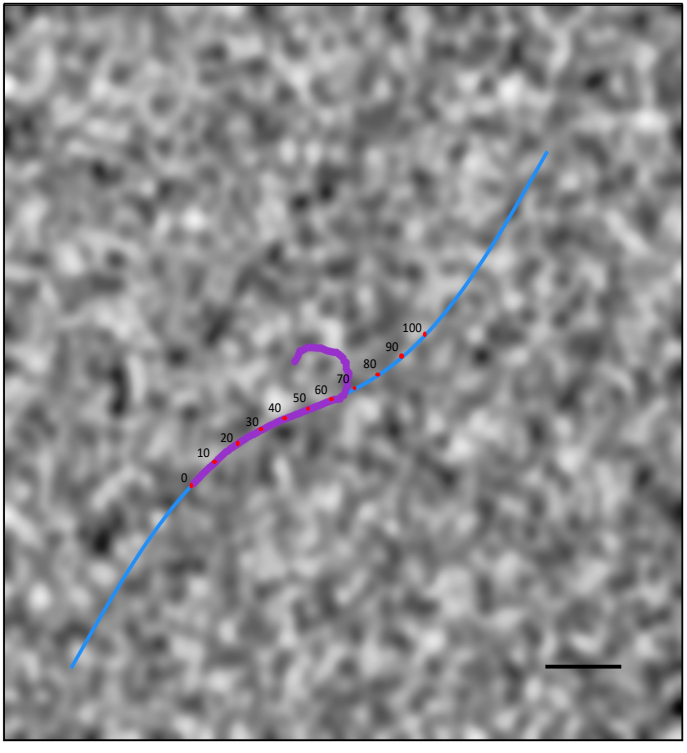


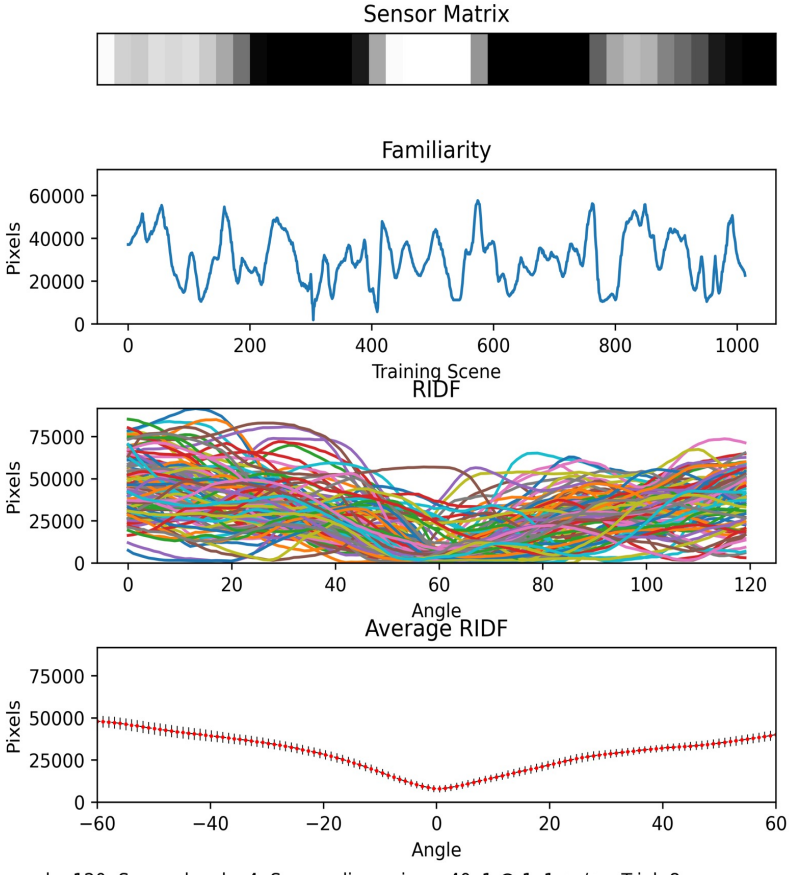
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 97.03; RMSD/dist: 0.243; TD: 28824; p90: 34; p50: 18; complete: 0


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

60%

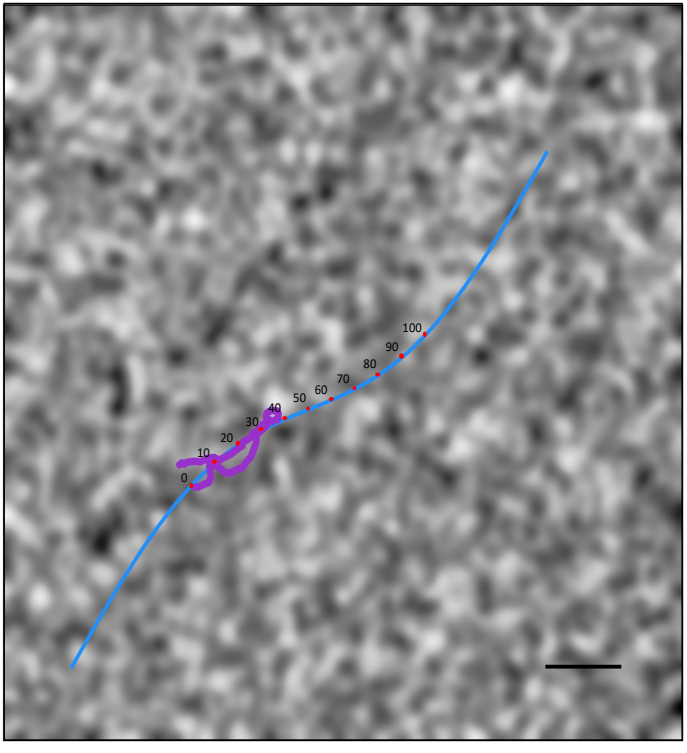


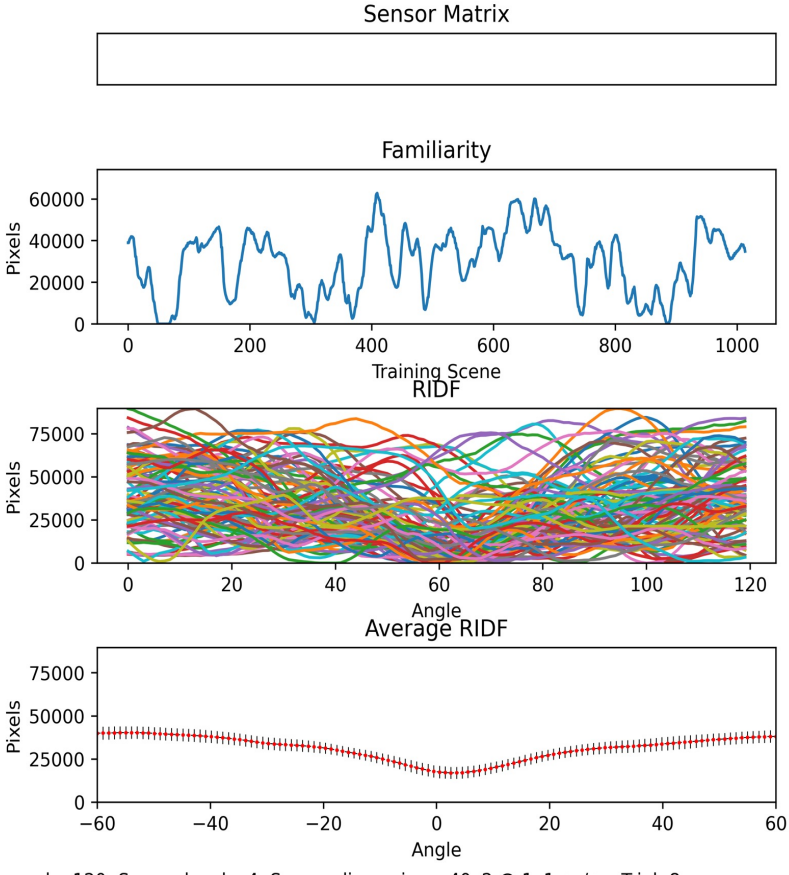


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1831.27; RMSD/dist: 4.578; TD: 23687; p90: 42; p50: 24; complete: 0

10%

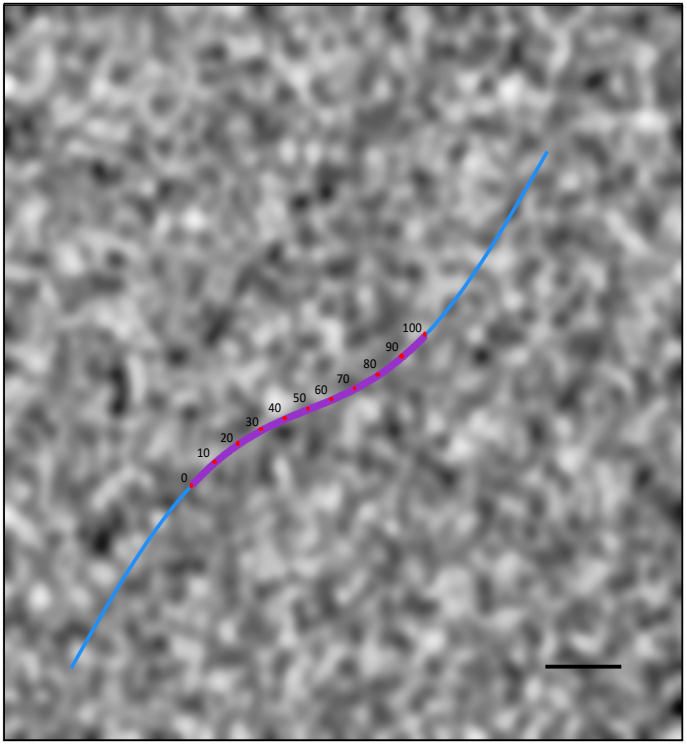


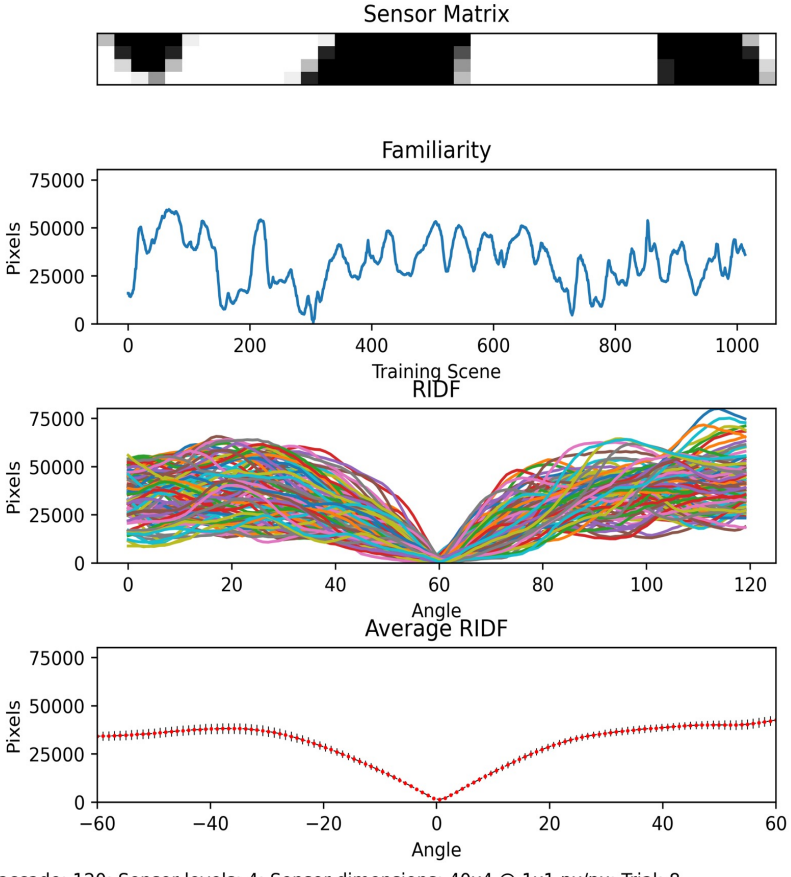


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1114.07; RMSD/dist: 2.785; TD: 12990; p90: 30; p50: 16; complete: 0

100%

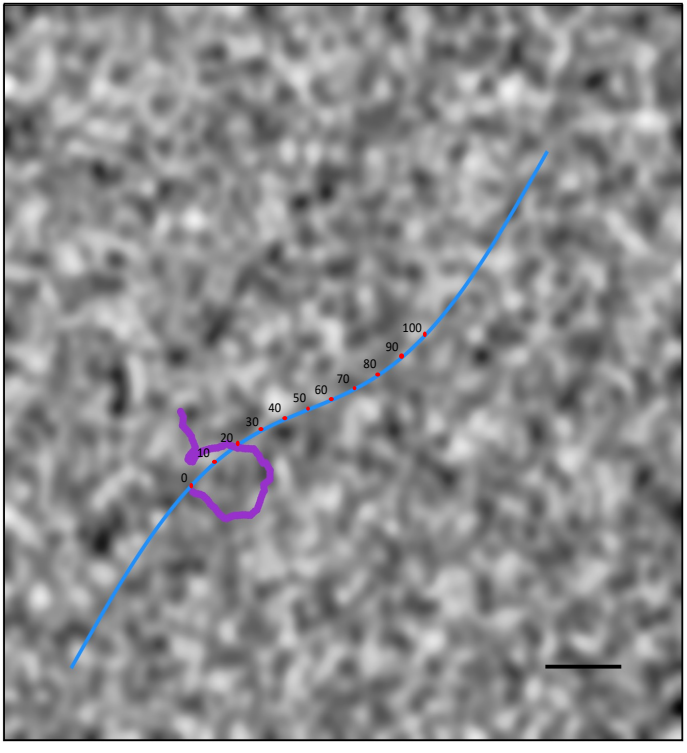


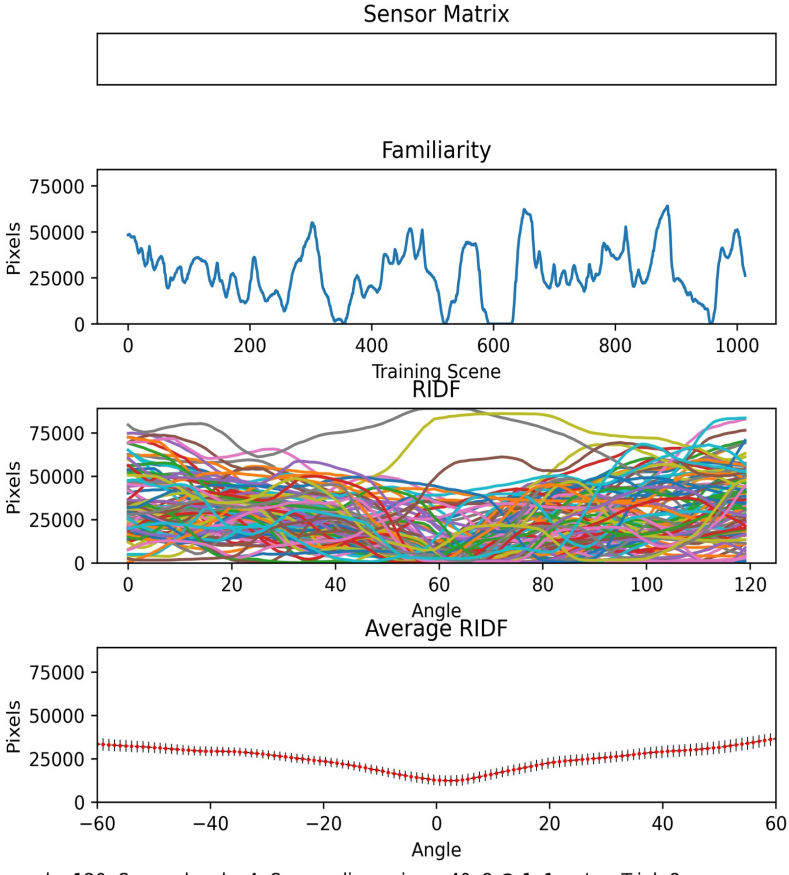


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 32.11; RMSD/dist: 0.080; TD: 32725; p90: 44; p50: 22; complete: 0

0%

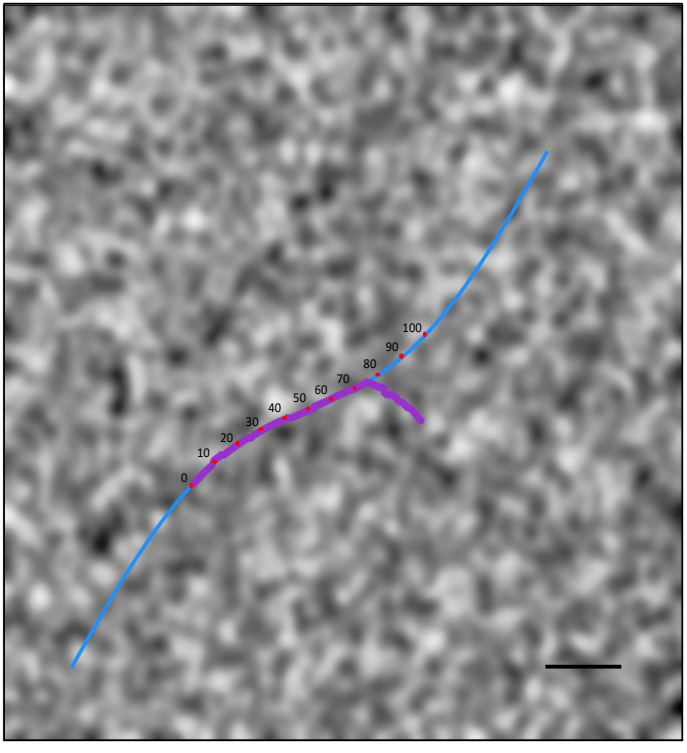


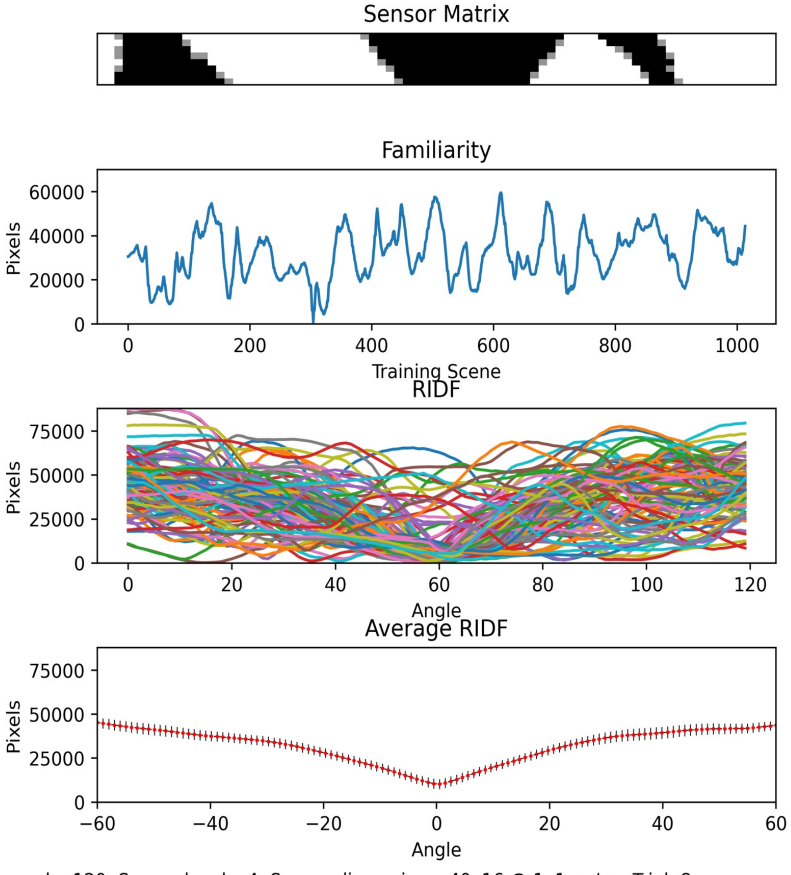


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 4461.64; RMSD/dist: 11.154; TD: 17956; p90: 66; p50: 32; complete: 0

70%

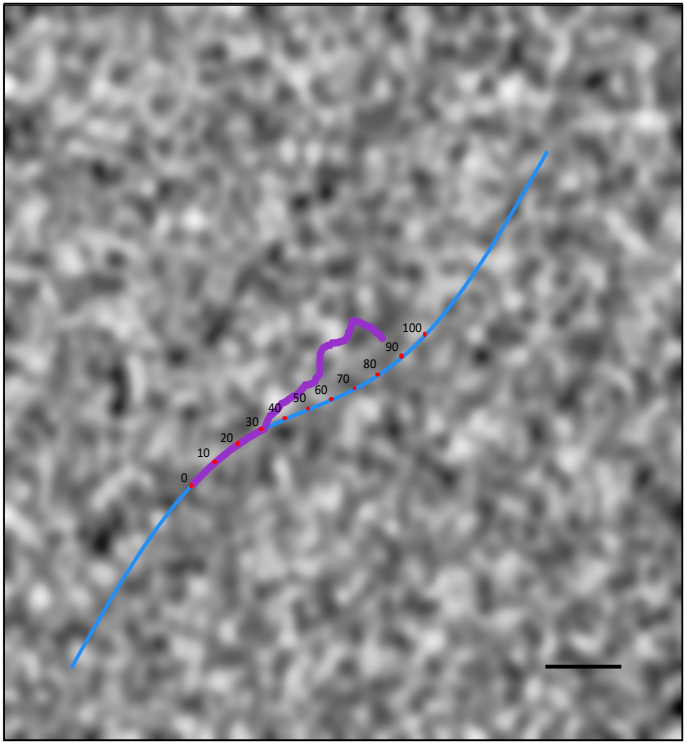


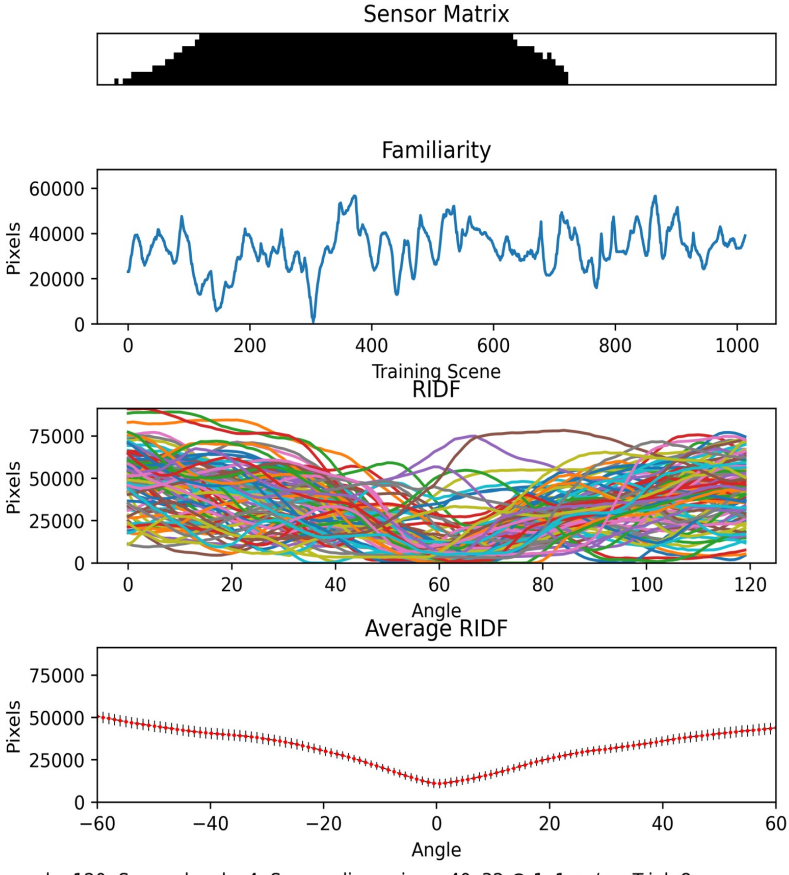


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1127.04; RMSD/dist: 2.818; TD: 21527; p90: 44; p50: 24; complete: 0

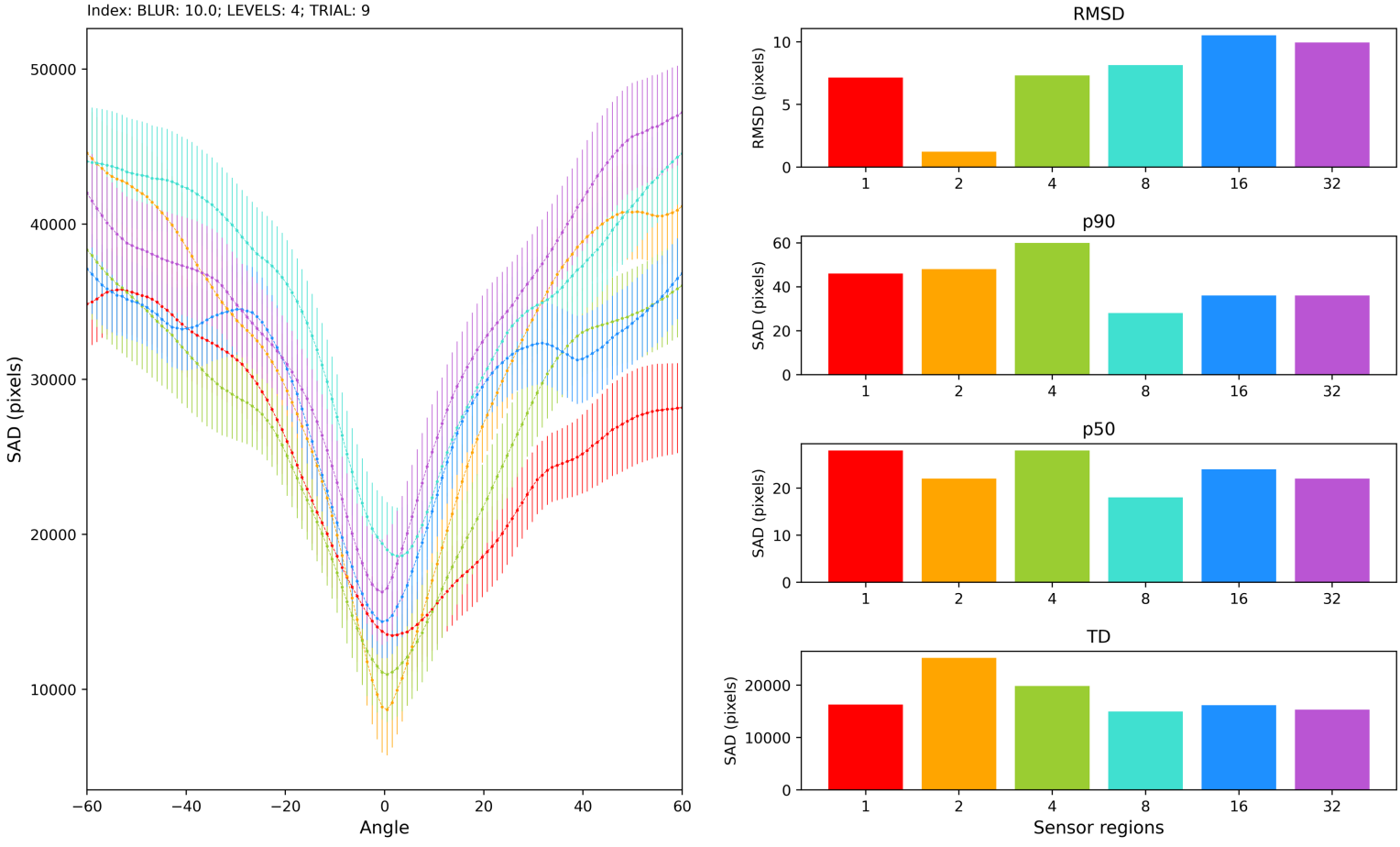
30%



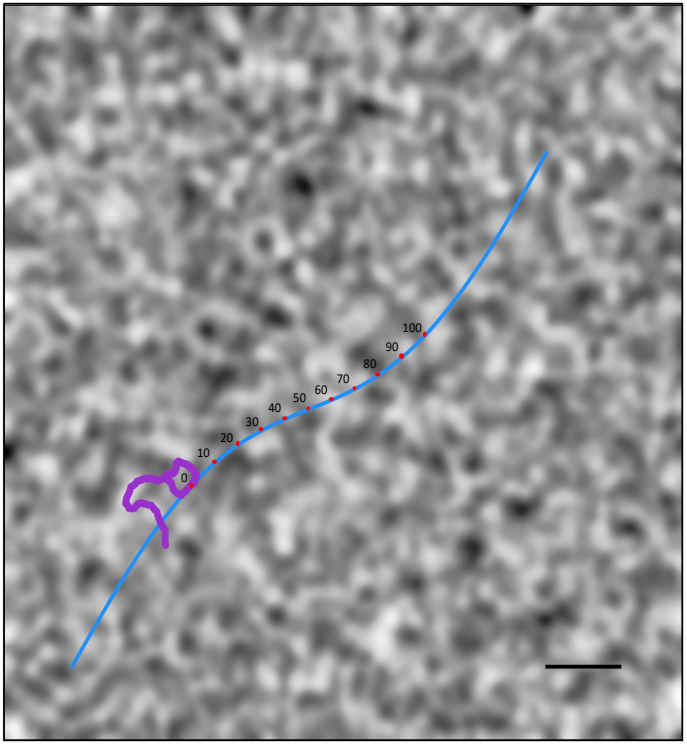


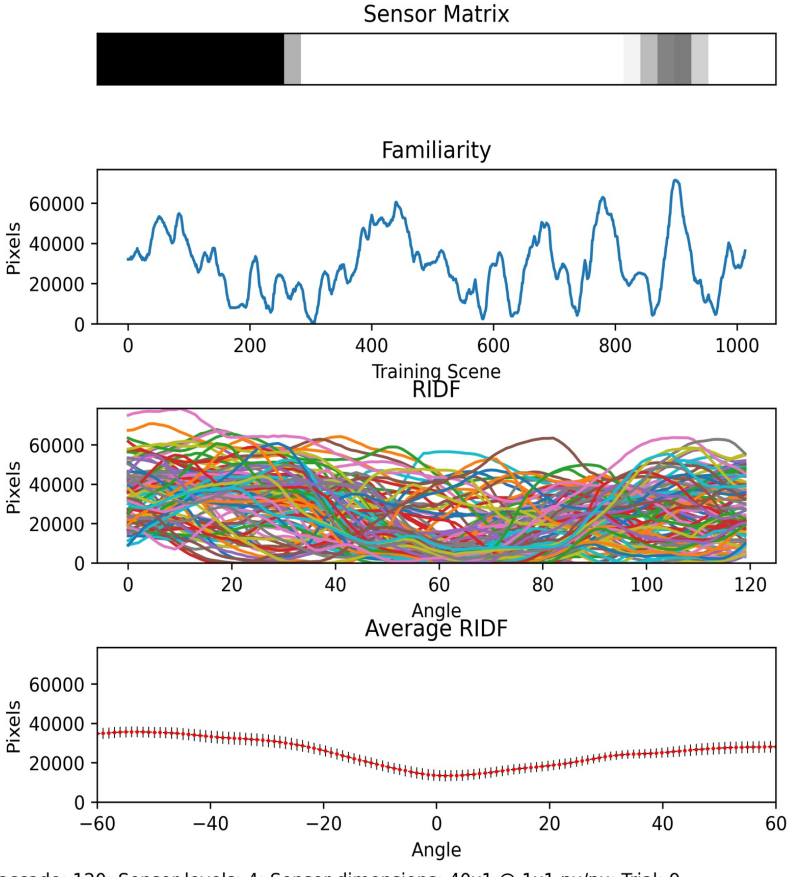
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3138.45; RMSD/dist: 7.846; TD: 21955; p90: 42; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

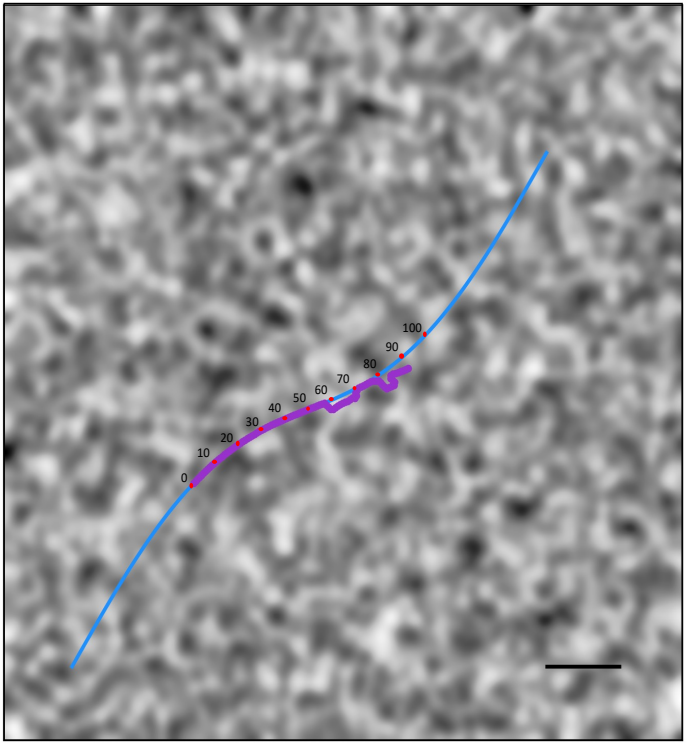


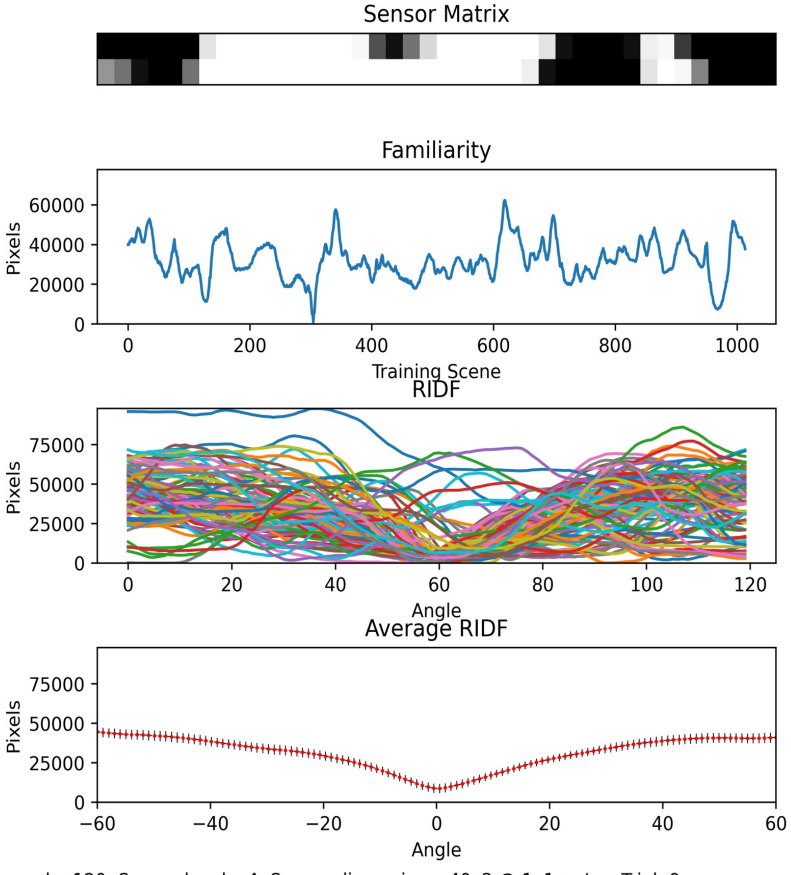


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2859.39; RMSD/dist: 7.148; TD: 16319; p90: 46; p50: 28; complete: 0

60%

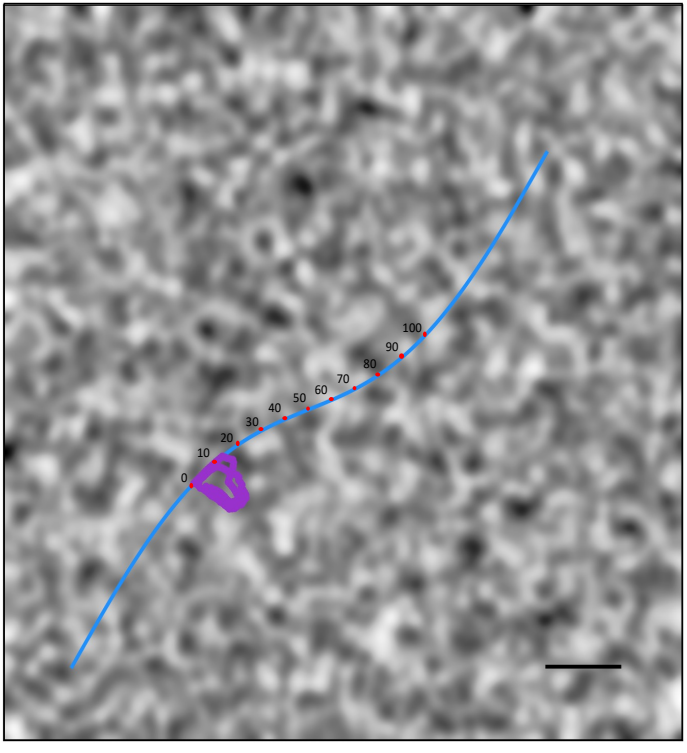


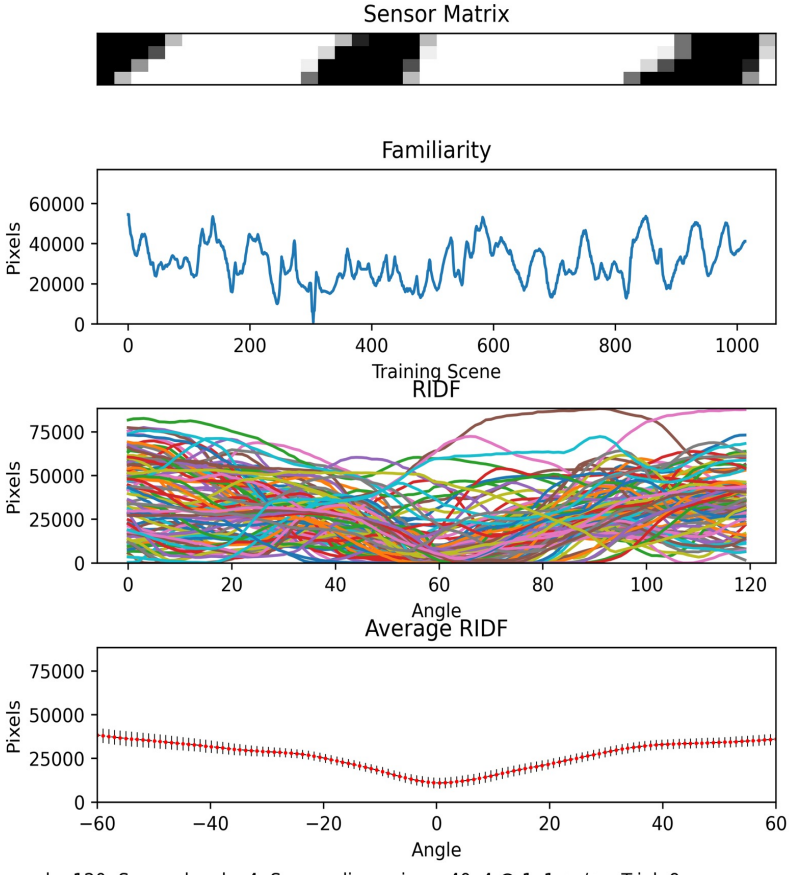


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 489.99; RMSD/dist: 1.225; TD: 25209; p90: 48; p50: 22; complete: 0

10%

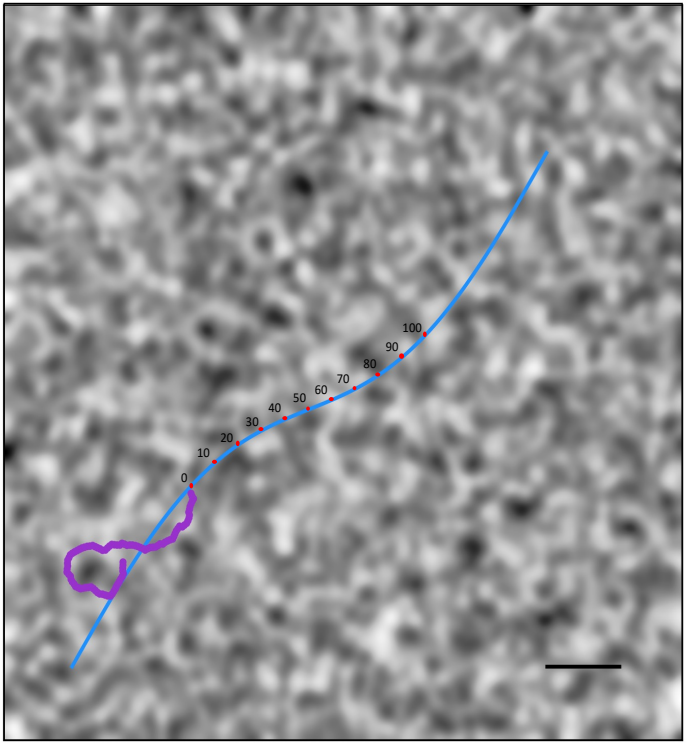


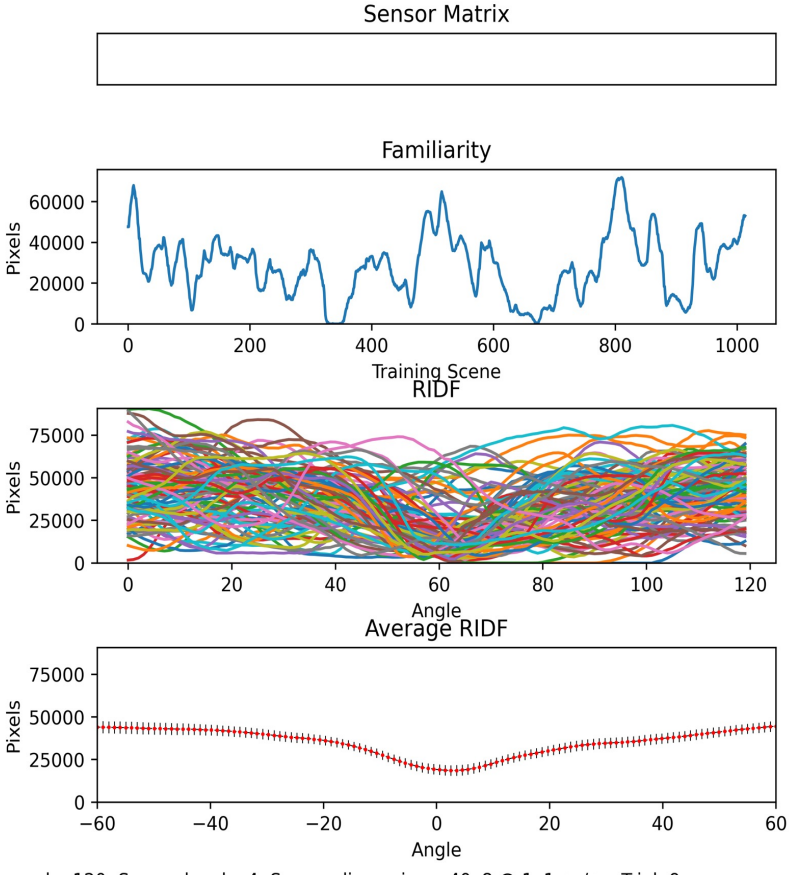


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2927.37; RMSD/dist: 7.318; TD: 19871; p90: 60; p50: 28; complete: 0

0%

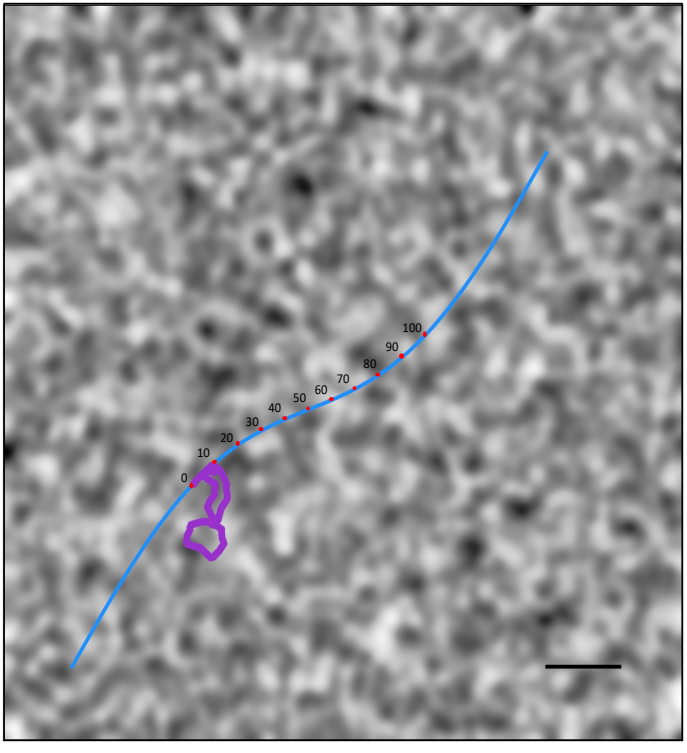


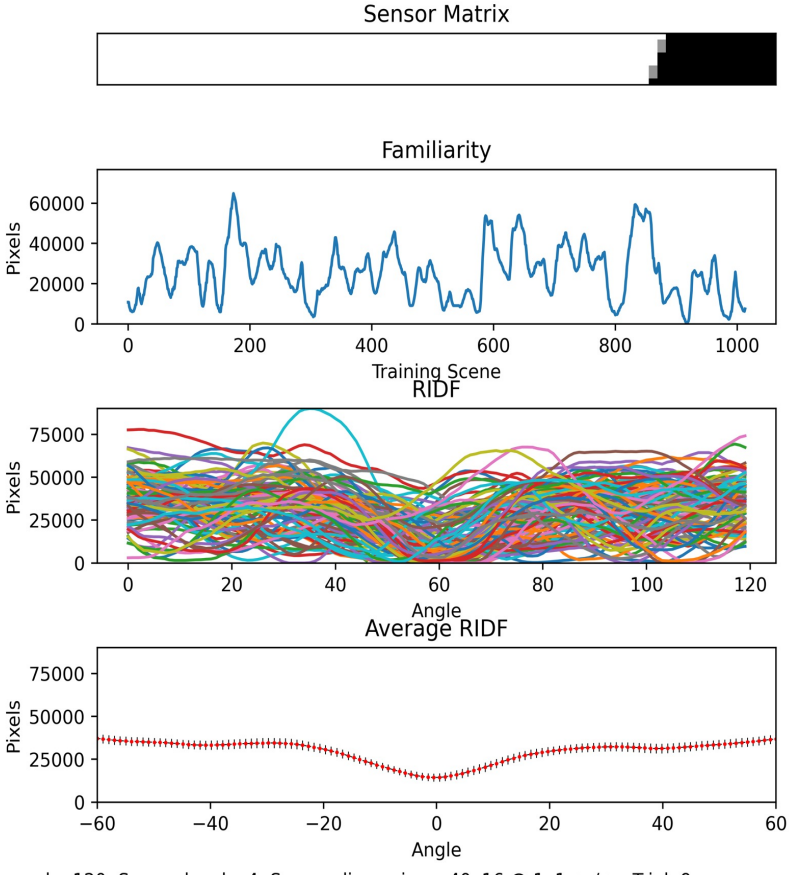


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3257.61; RMSD/dist: 8.144; TD: 14959; p90: 28; p50: 18; complete: 0

10%

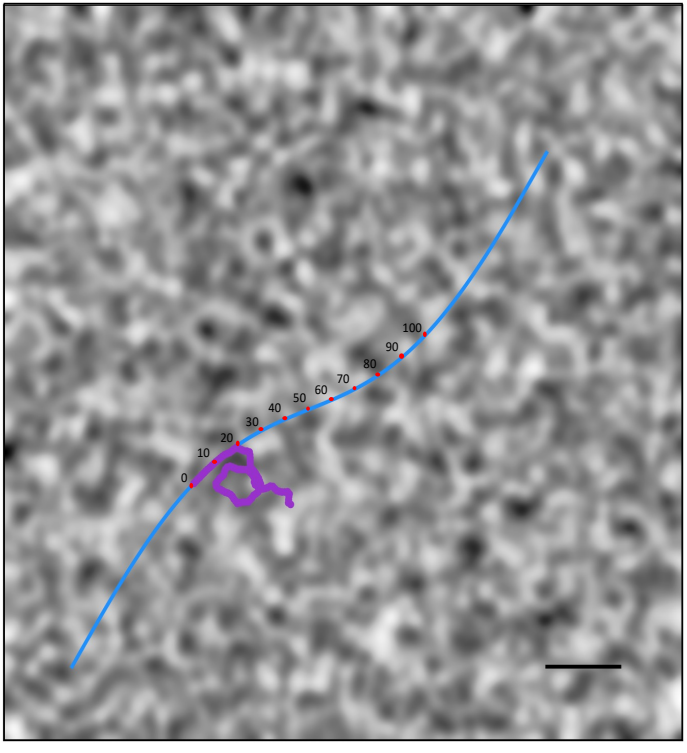


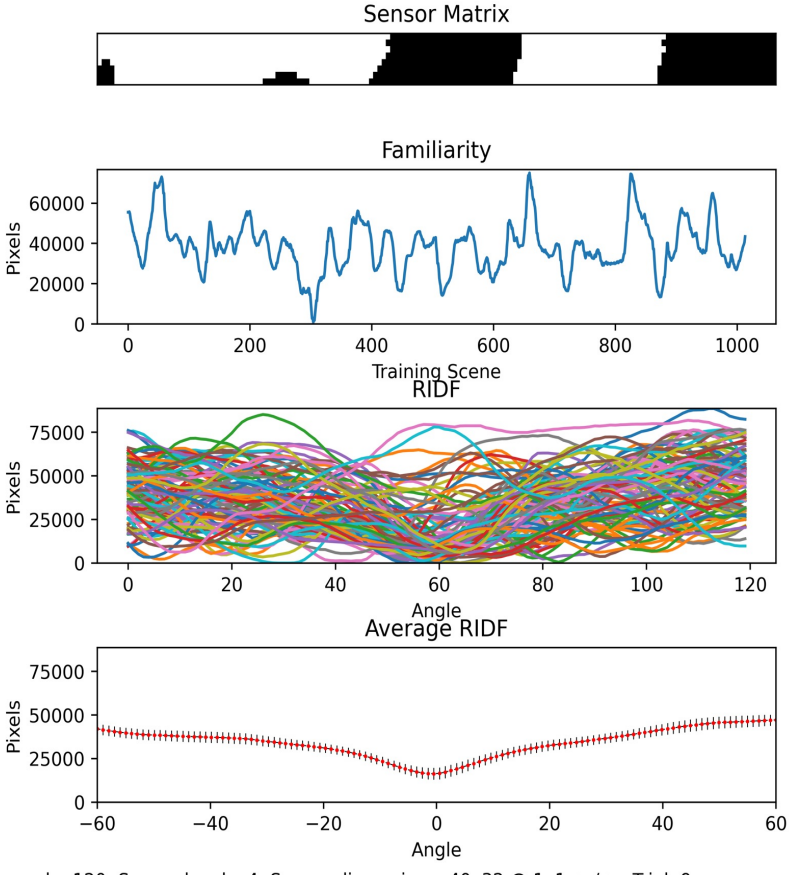


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 4212.29; RMSD/dist: 10.531; TD: 16185; p90: 36; p50: 24; complete: 0

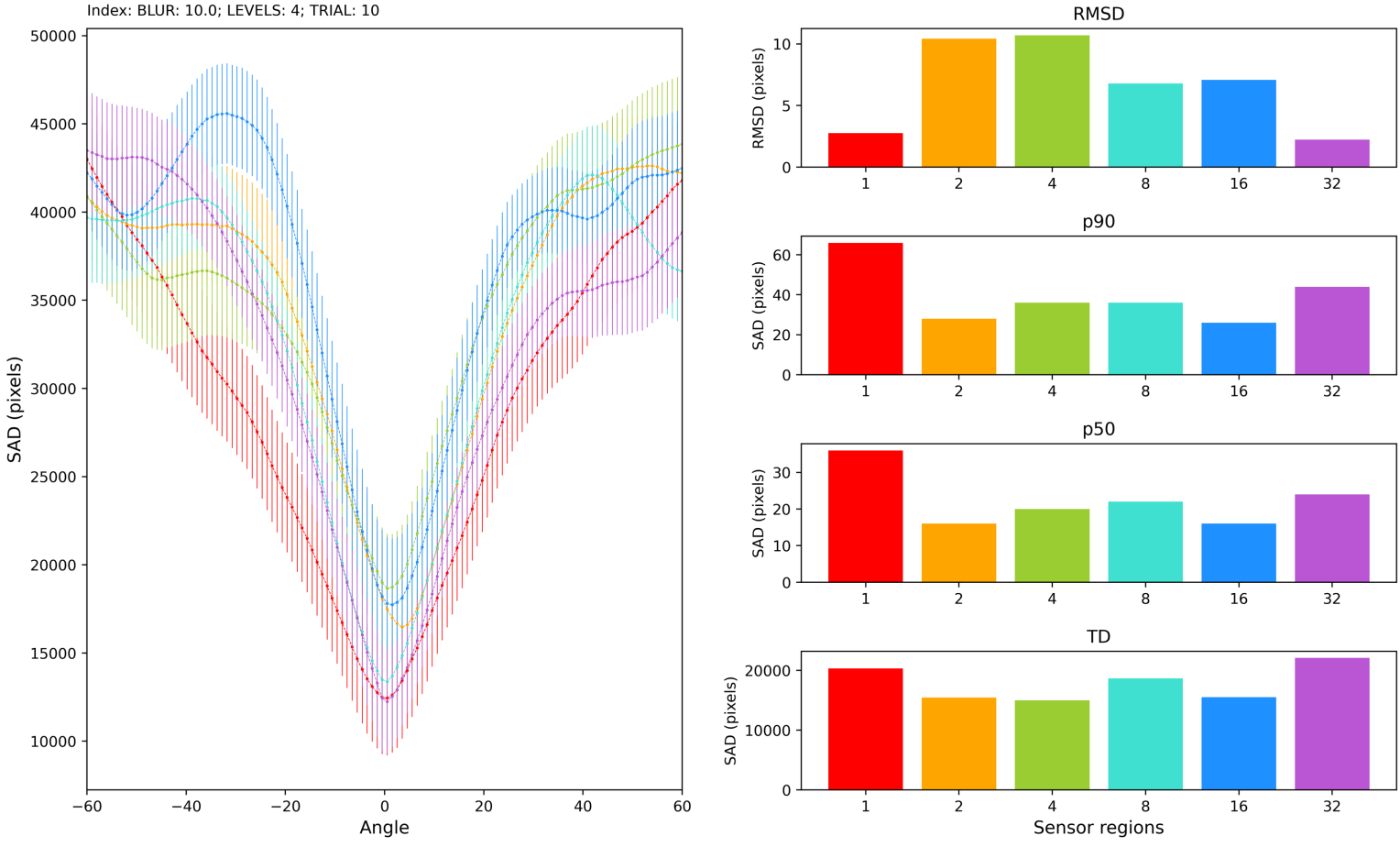
10%



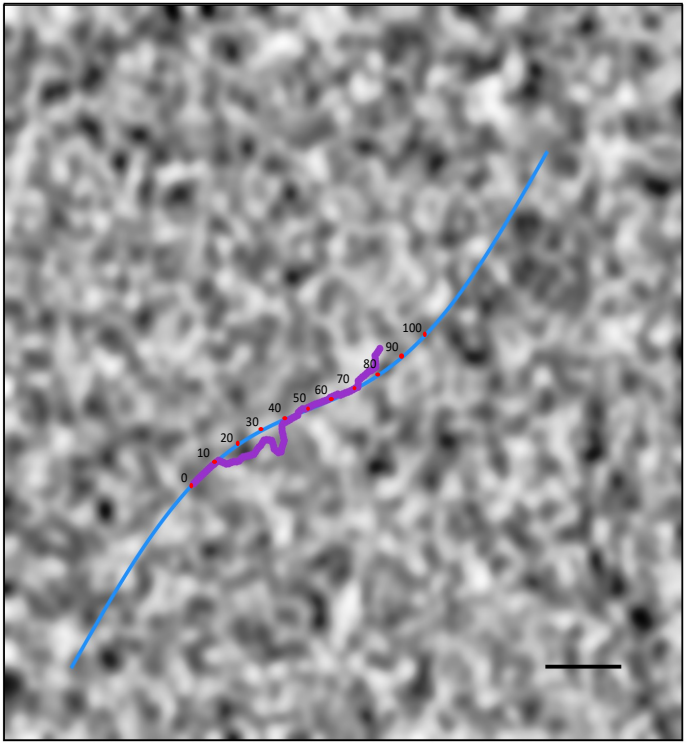


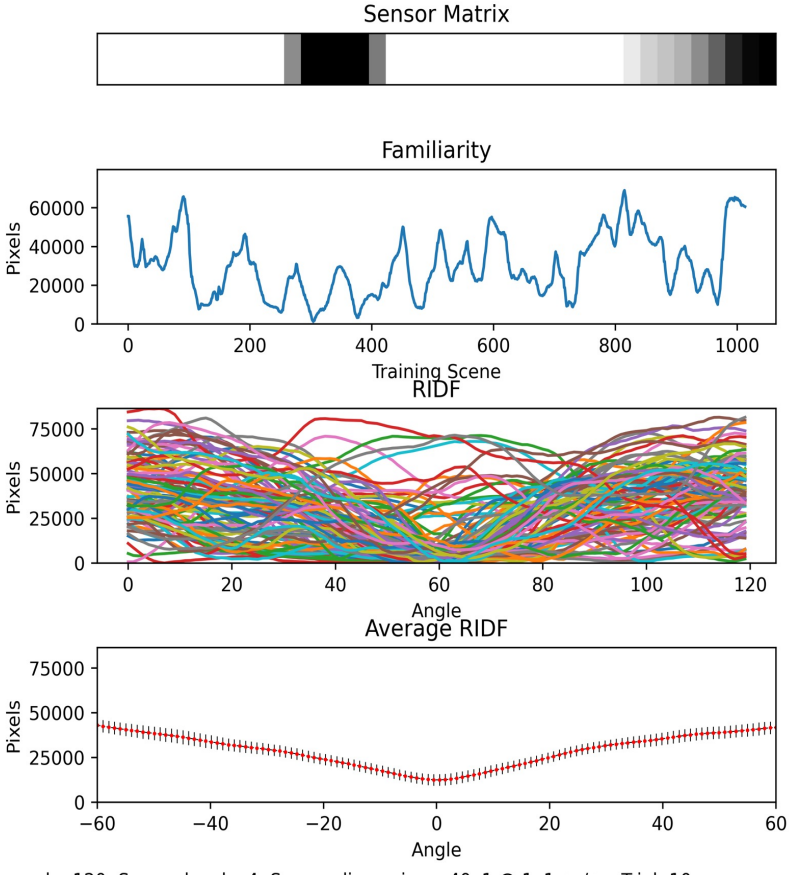
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3983.27; RMSD/dist: 9.958; TD: 15336; p90: 36; p50: 22; complete: 0


Index: BLUR: 10.0; LEVELS: 4; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

20%

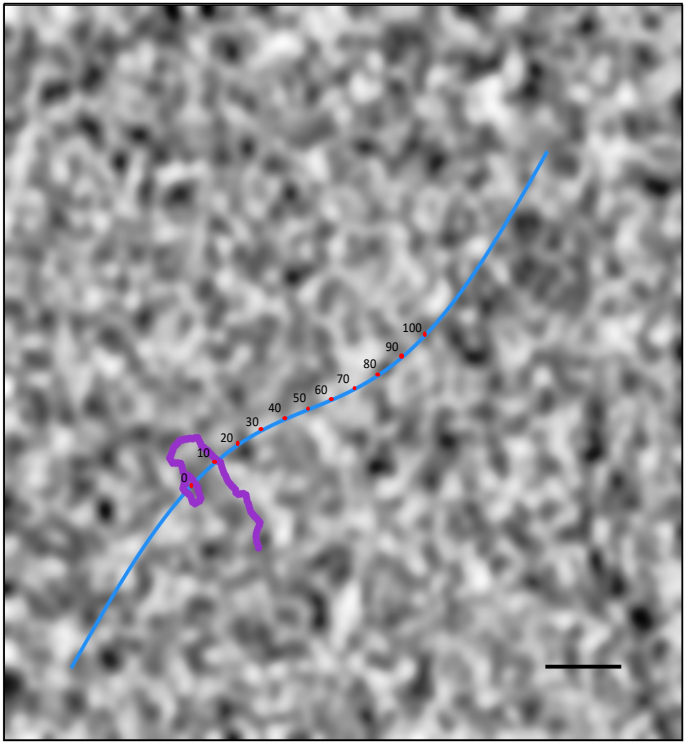


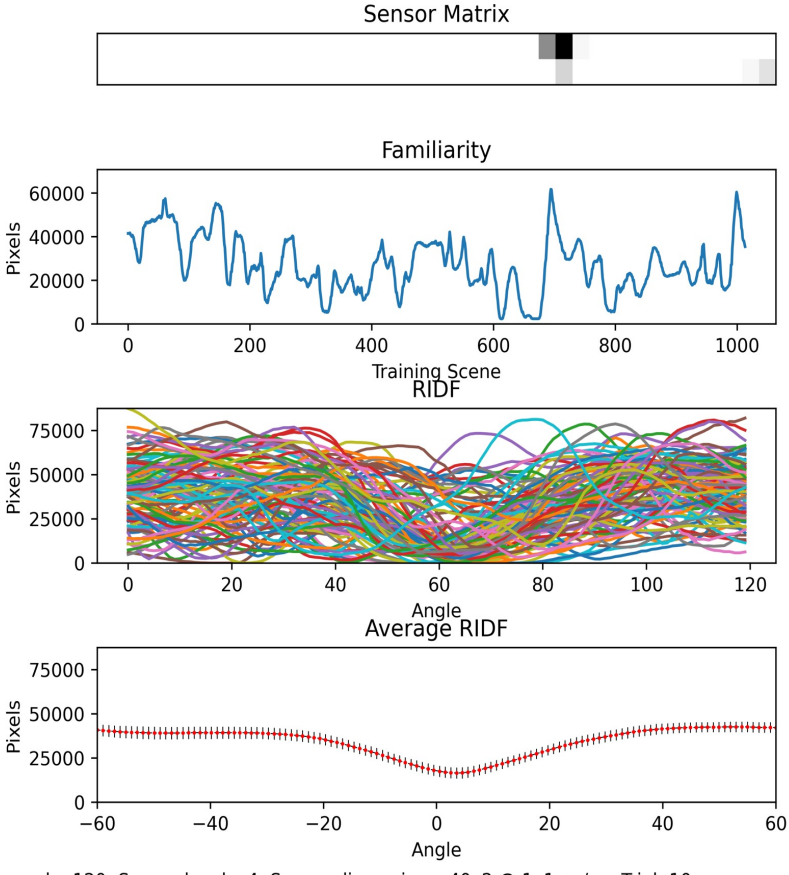


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1104.70; RMSD/dist: 2.762; TD: 20325; p90: 66; p50: 36; complete: 0

0%

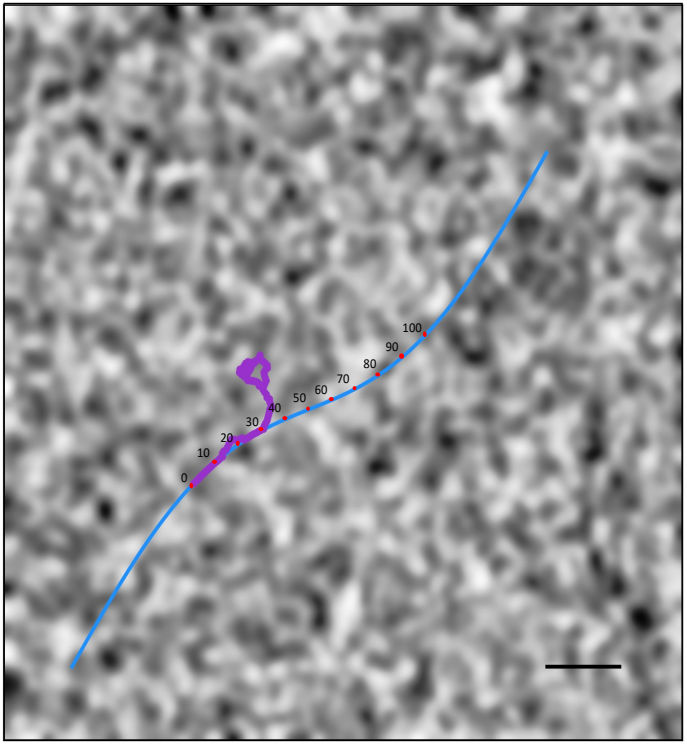


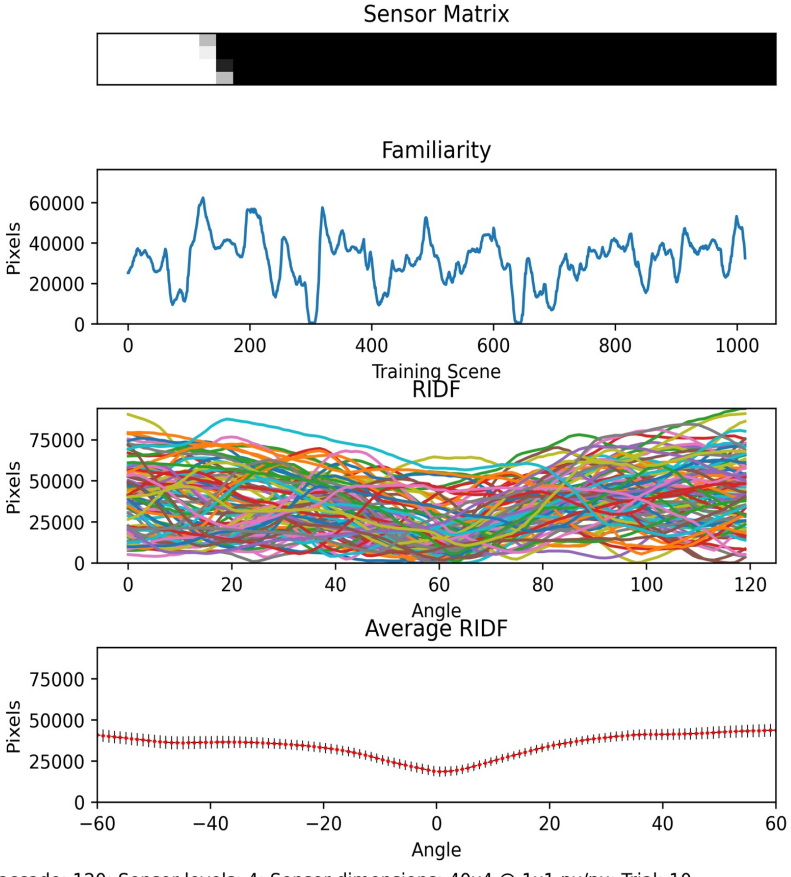


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4166.97; RMSD/dist: 10.417; TD: 15463; p90: 28; p50: 16; complete: 0

20%

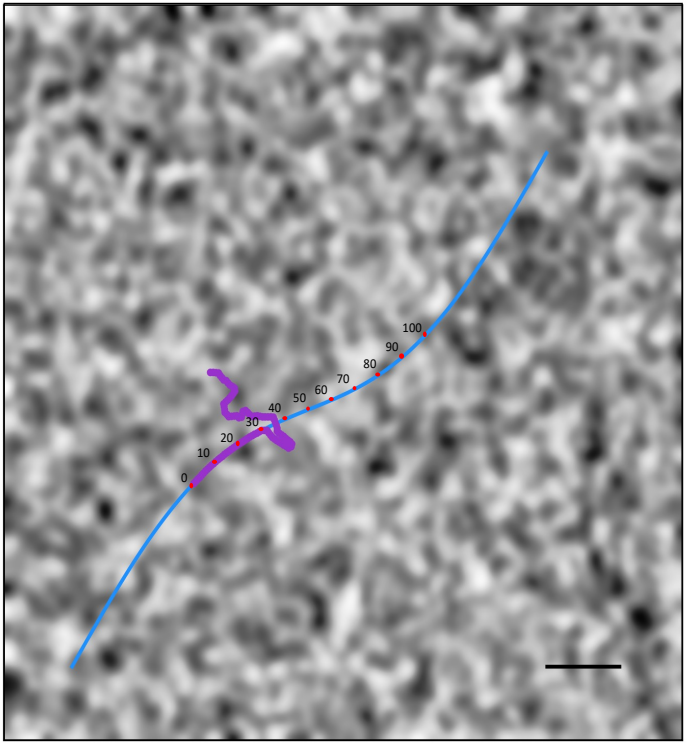


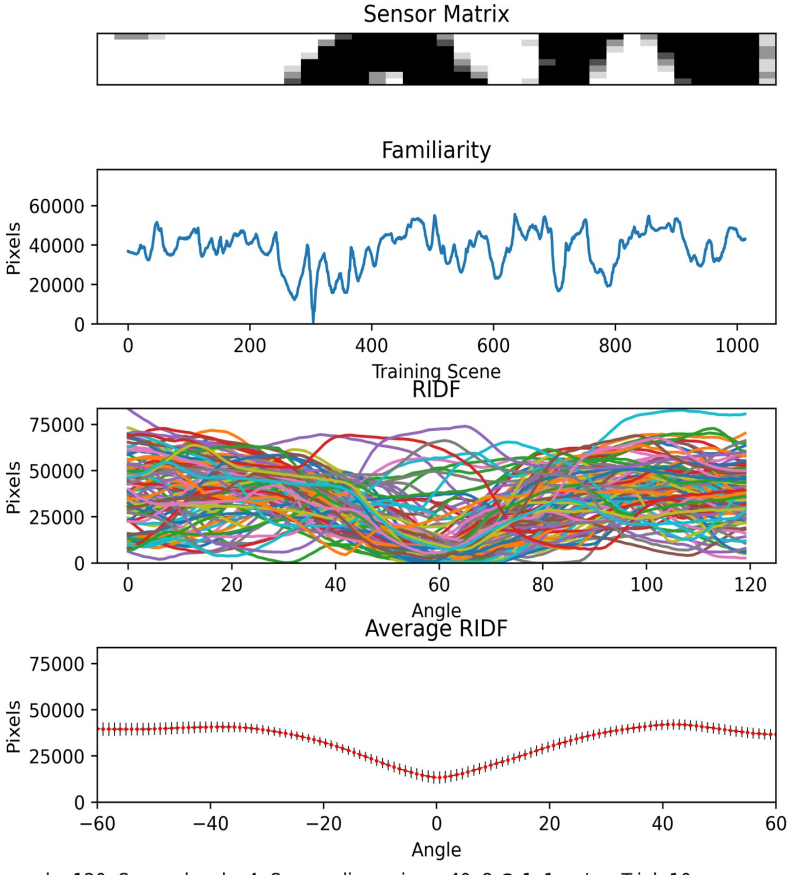


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4281.16; RMSD/dist: 10.703; TD: 14992; p90: 36; p50: 20; complete: 0

30%

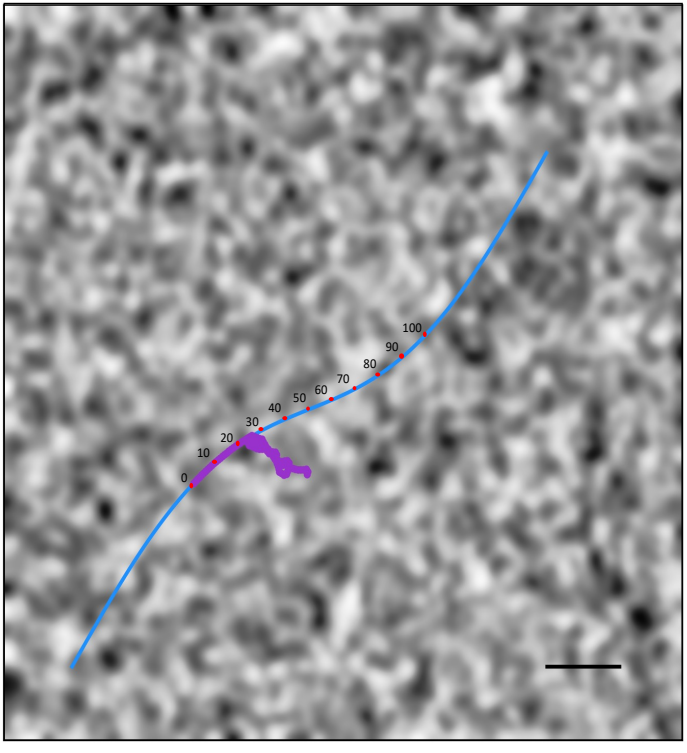


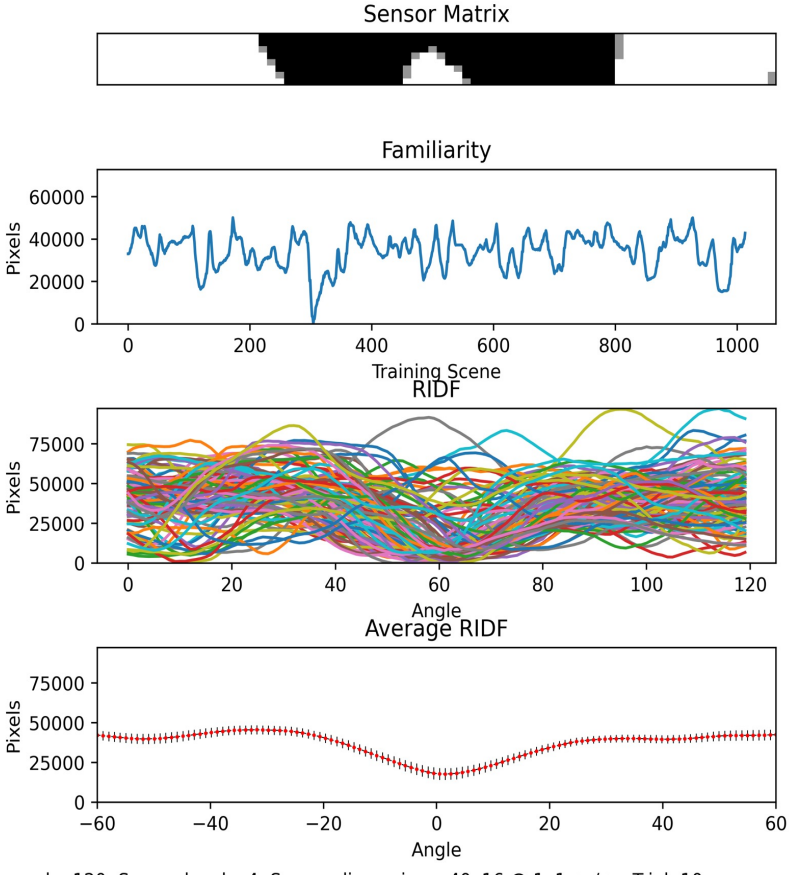


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2711.53; RMSD/dist: 6.779; TD: 18664; p90: 36; p50: 22; complete: 0

20%

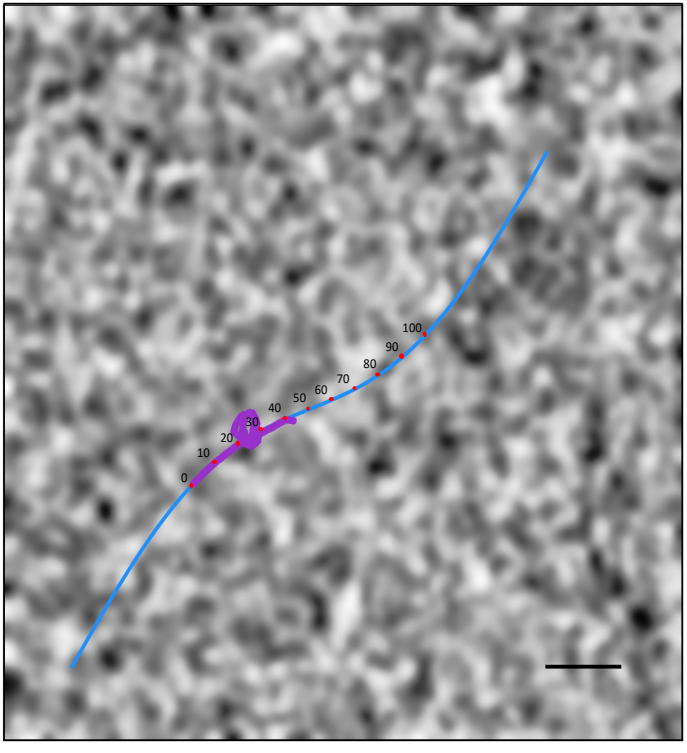


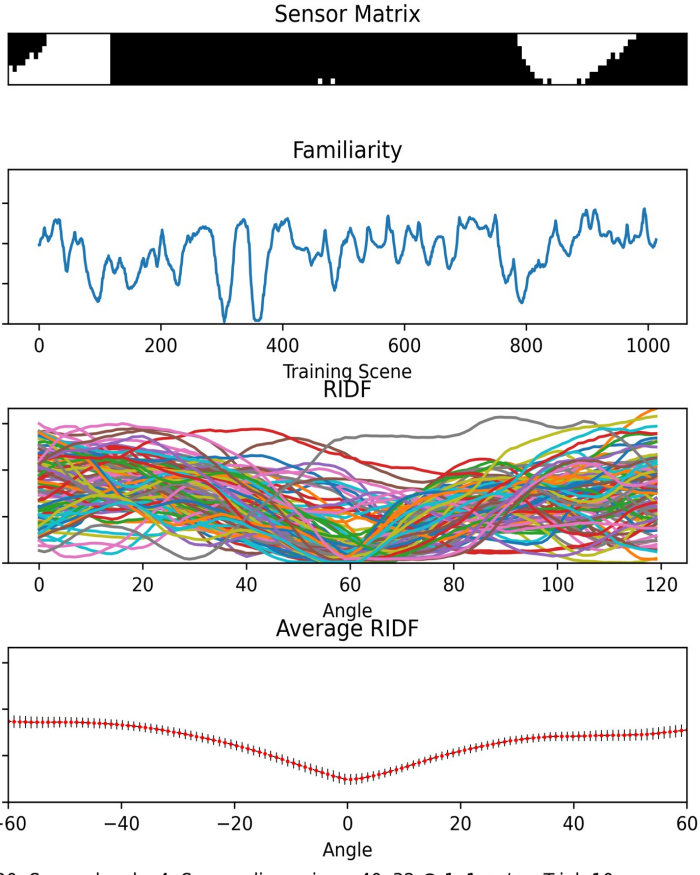


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2830.03; RMSD/dist: 7.075; TD: 15508; p90: 26; p50: 16; complete: 0

40%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 891.65; RMSD/dist: 2.229; TD: 22080; p90: 44; p50: 24; complete: 0