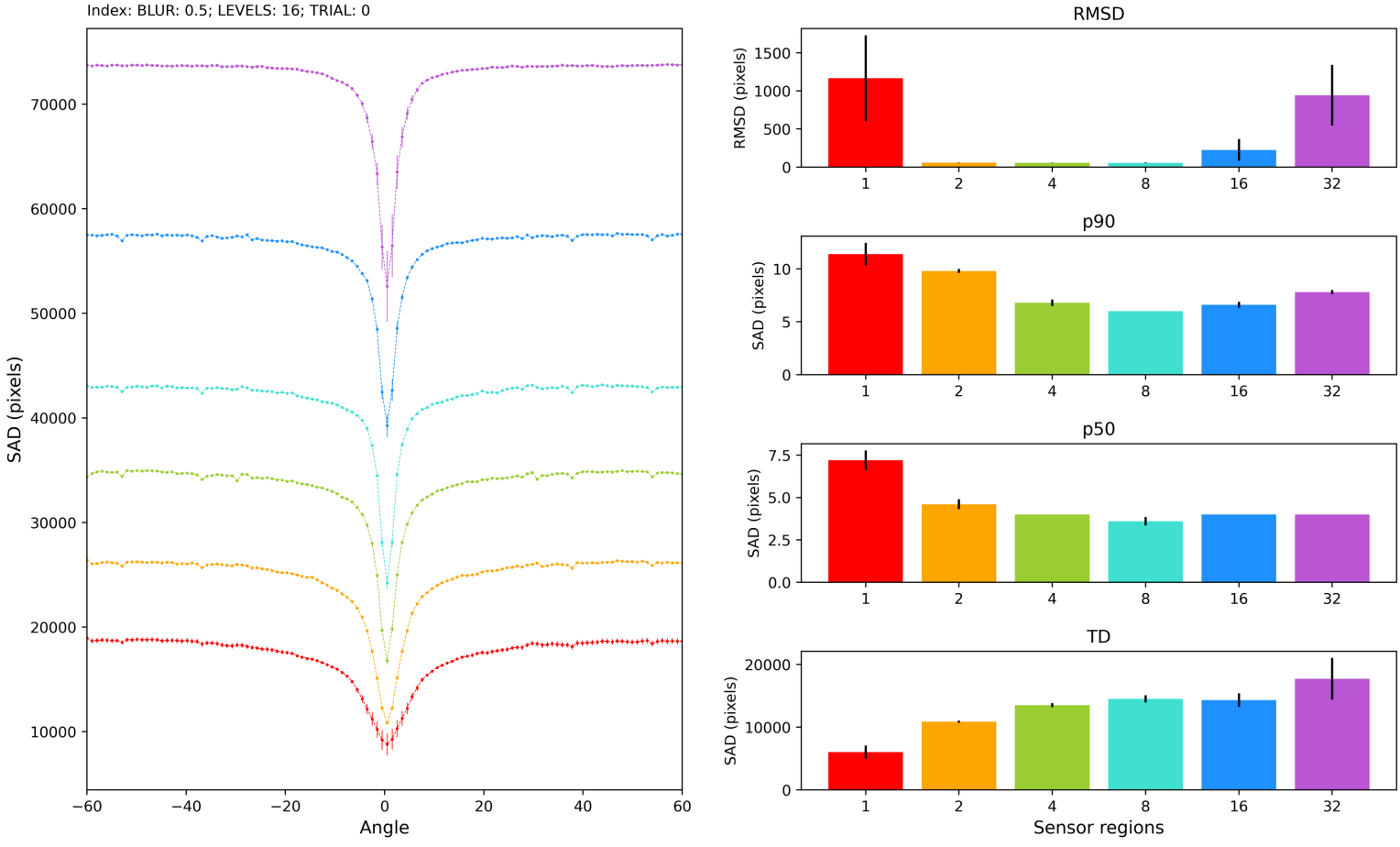
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SAD (pixels)
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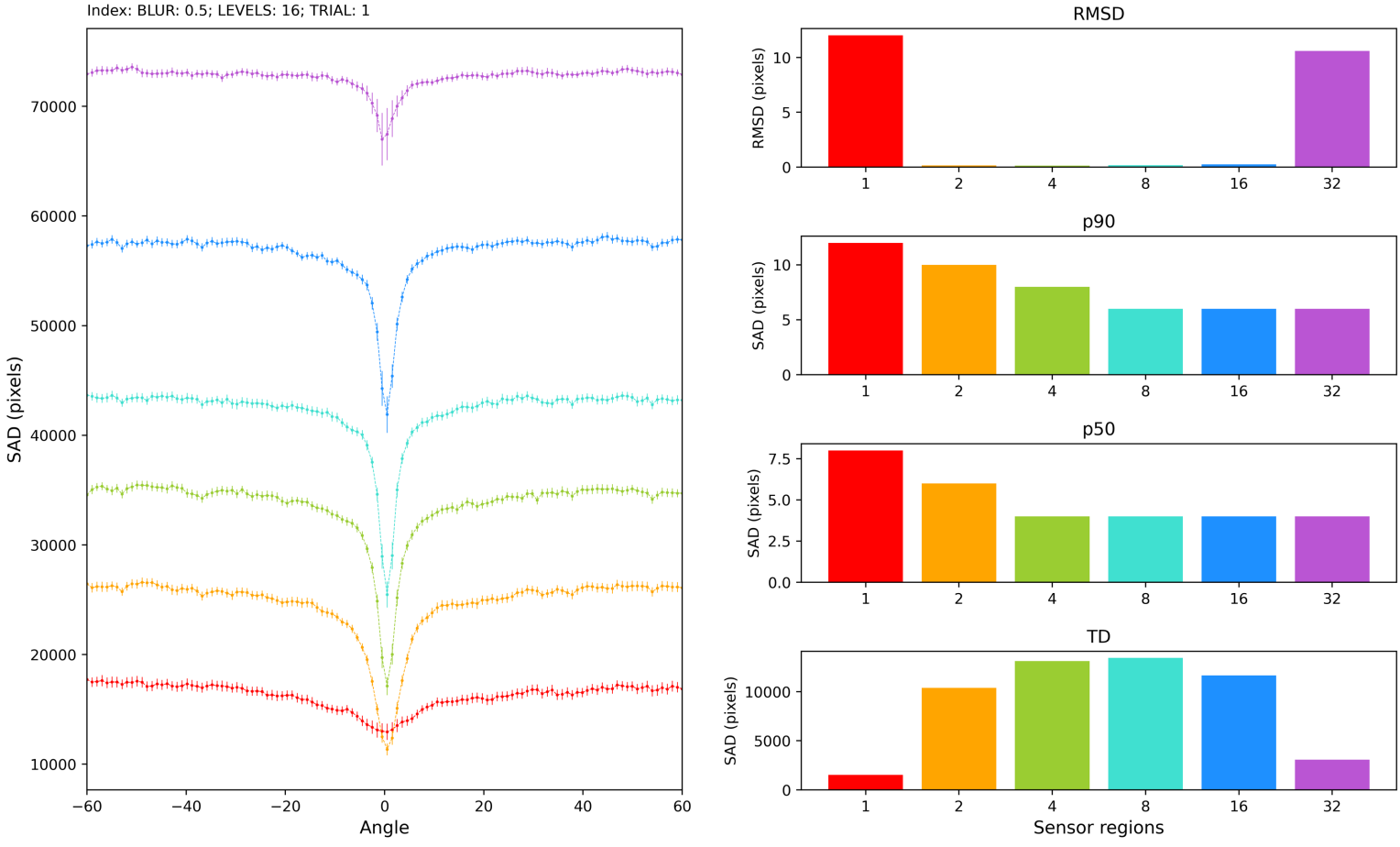
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
1500
1000
500
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions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SAD (pixels)
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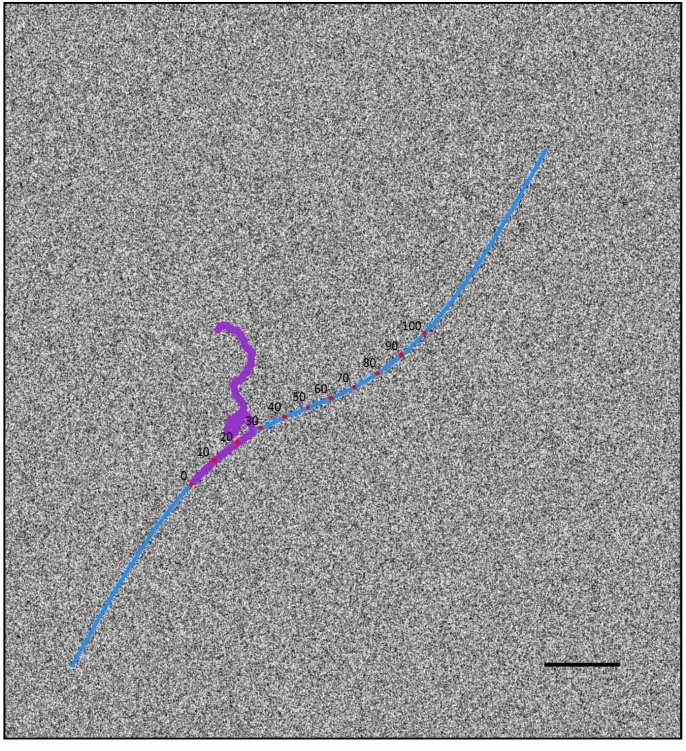
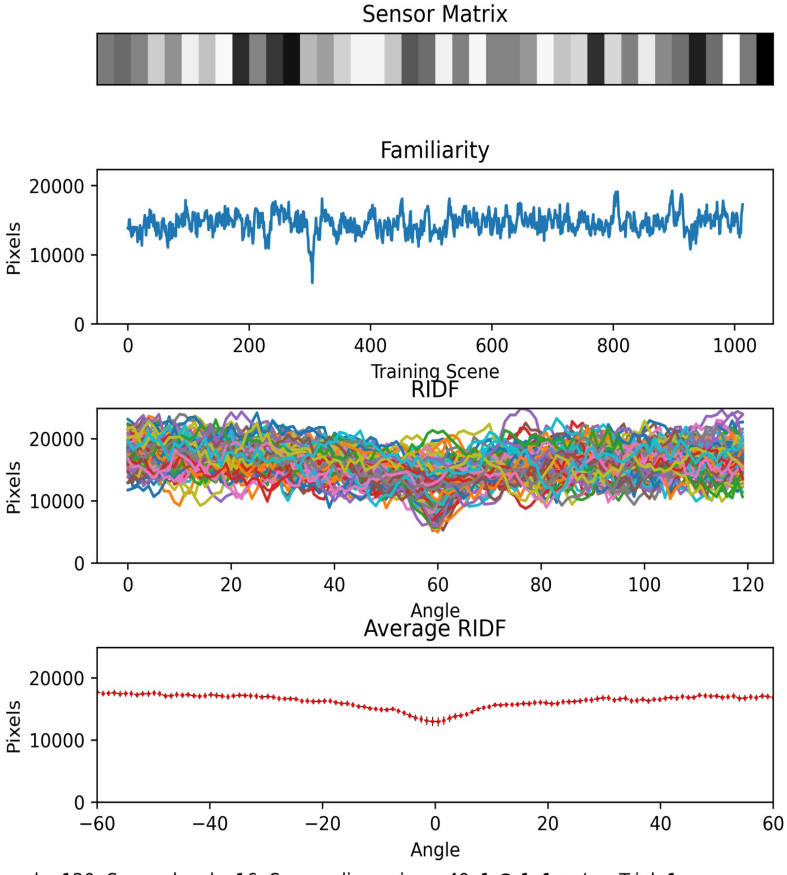
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
1
2
4
8
16
32
p50
SAD (pixels)
7.5
5.0
2.5
0.0
1
2
4
8
16
32
TD
SAD (pixels)
10000
5000
0
1
2
4
8
16
32
Sensor regions

20%

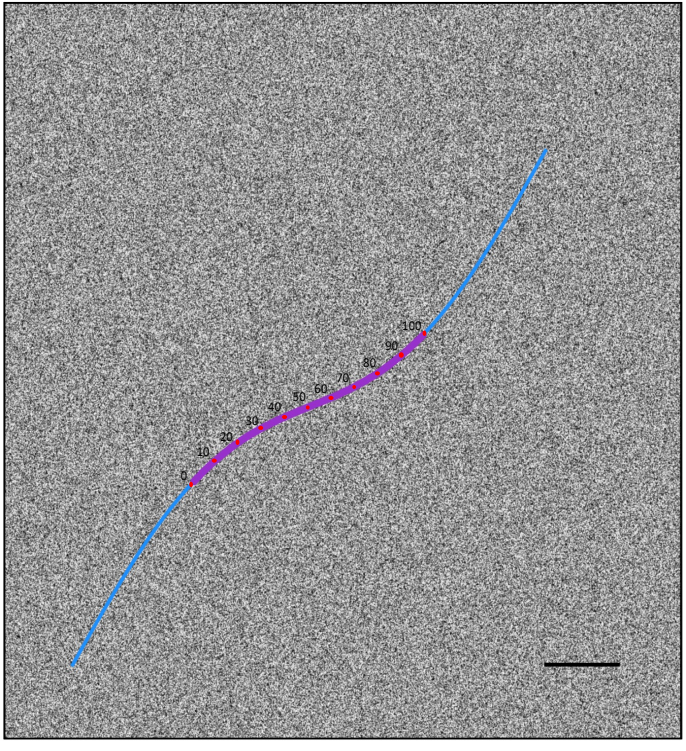


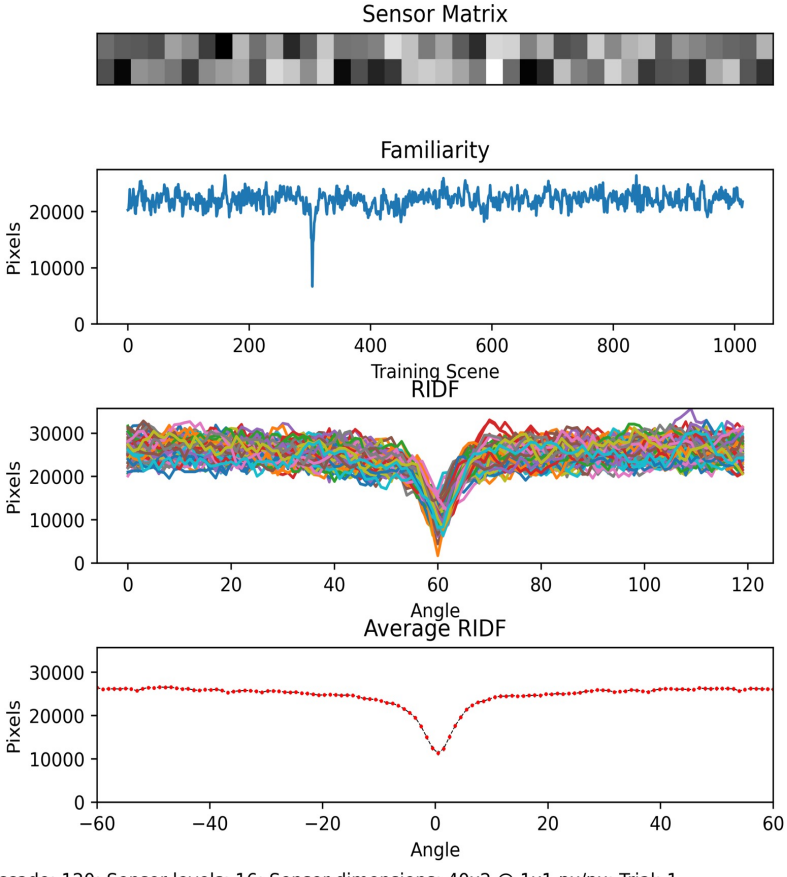


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4813.83; RMSD/dist: 12.035; TD: 1518; p90: 12; p50: 8; complete: 0

100%

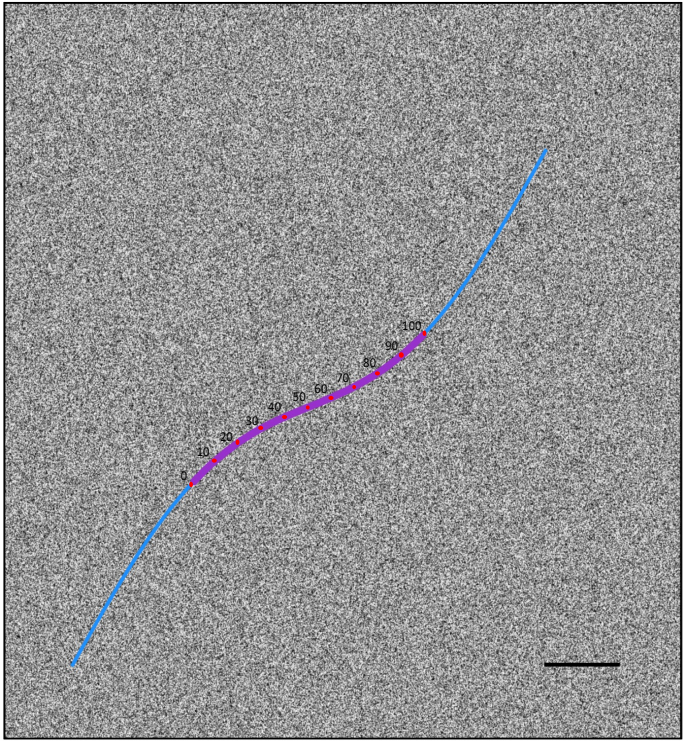


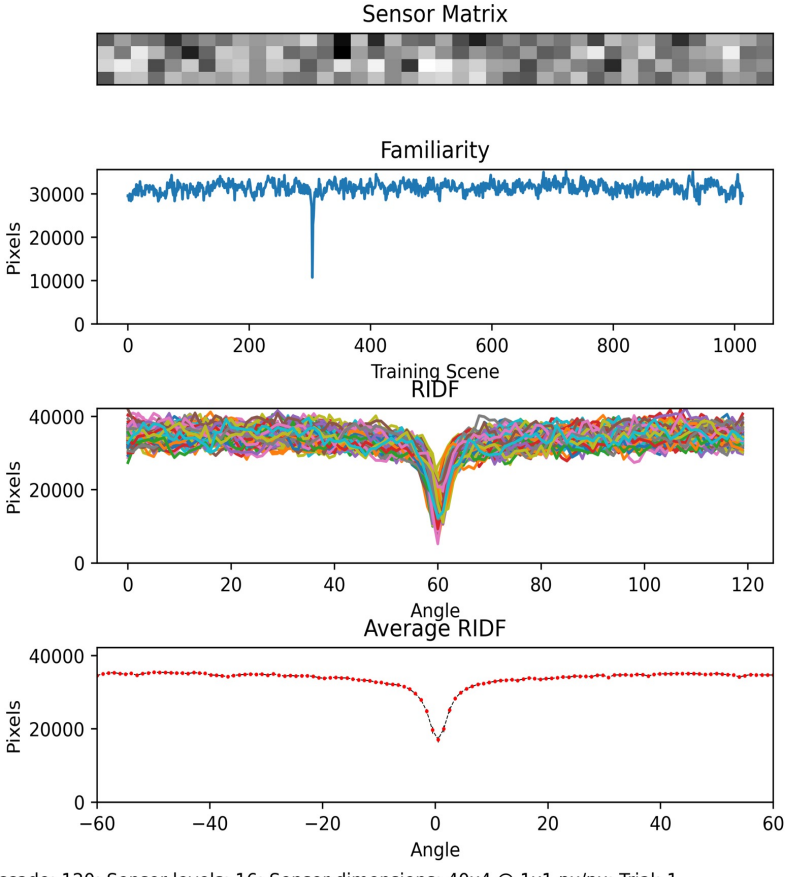


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 60.28; RMSD/dist: 0.151; TD: 10397; p90: 10; p50: 6; complete: 0

100%

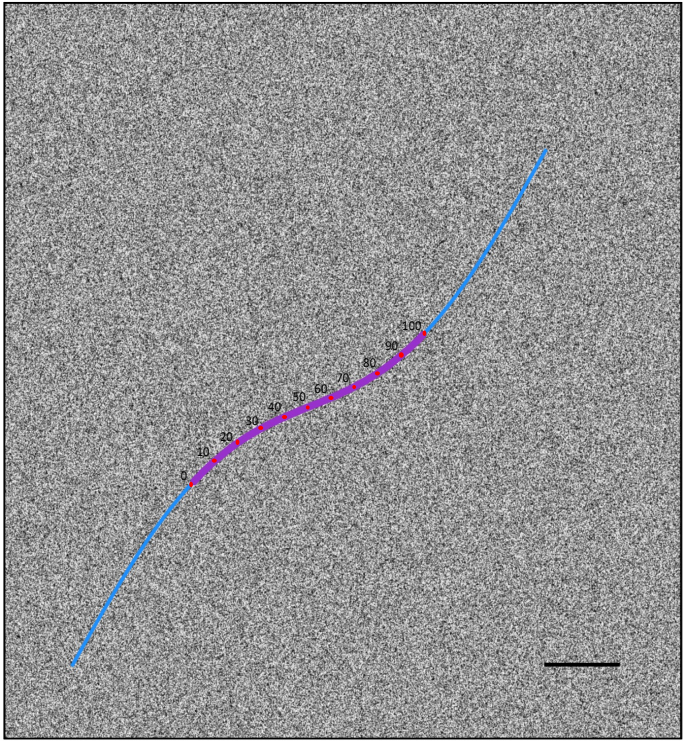


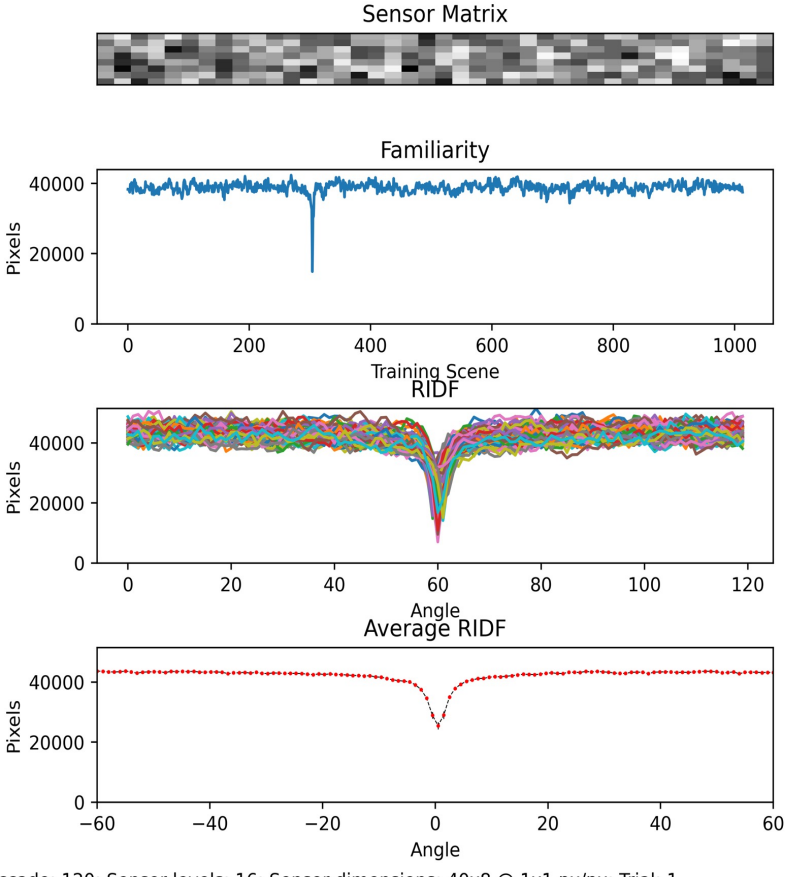


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 54.22; RMSD/dist: 0.136; TD: 13117; p90: 8; p50: 4; complete: 0

100%

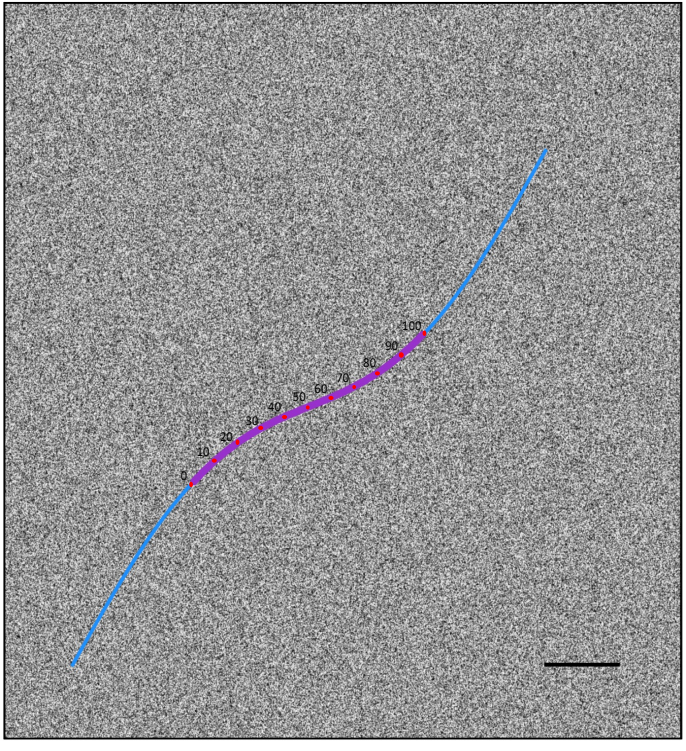


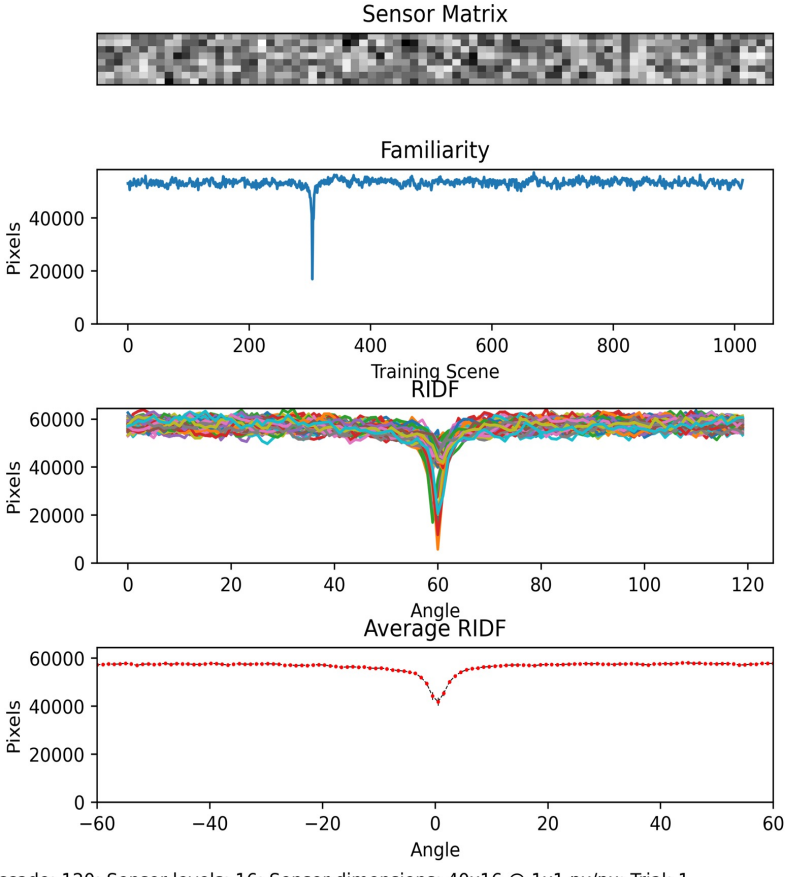


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 63.86; RMSD/dist: 0.160; TD: 13436; p90: 6; p50: 4; complete: 0

100%

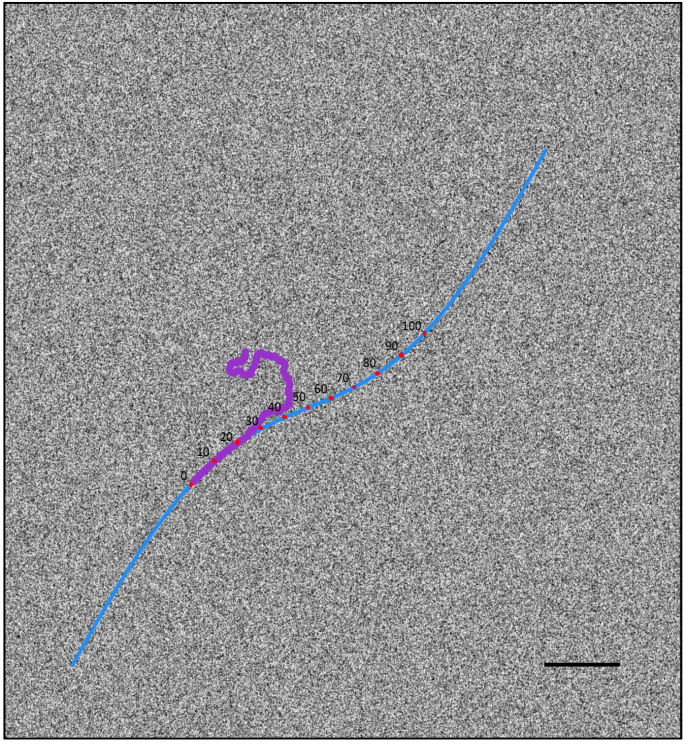


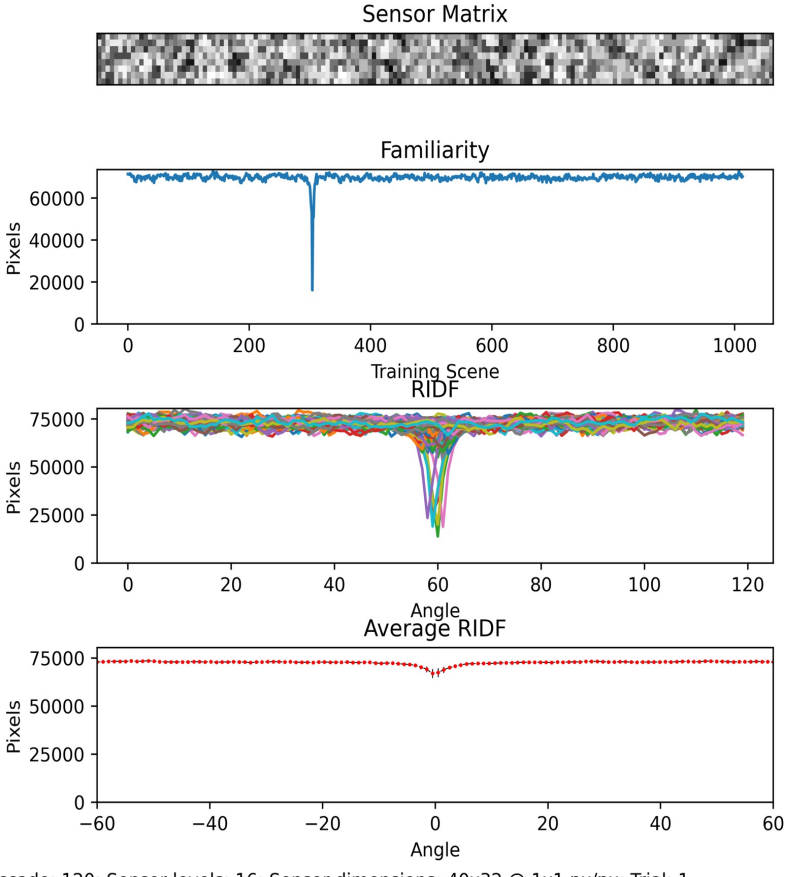


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 95.73; RMSD/dist: 0.239; TD: 11654; p90: 6; p50: 4; complete: 0

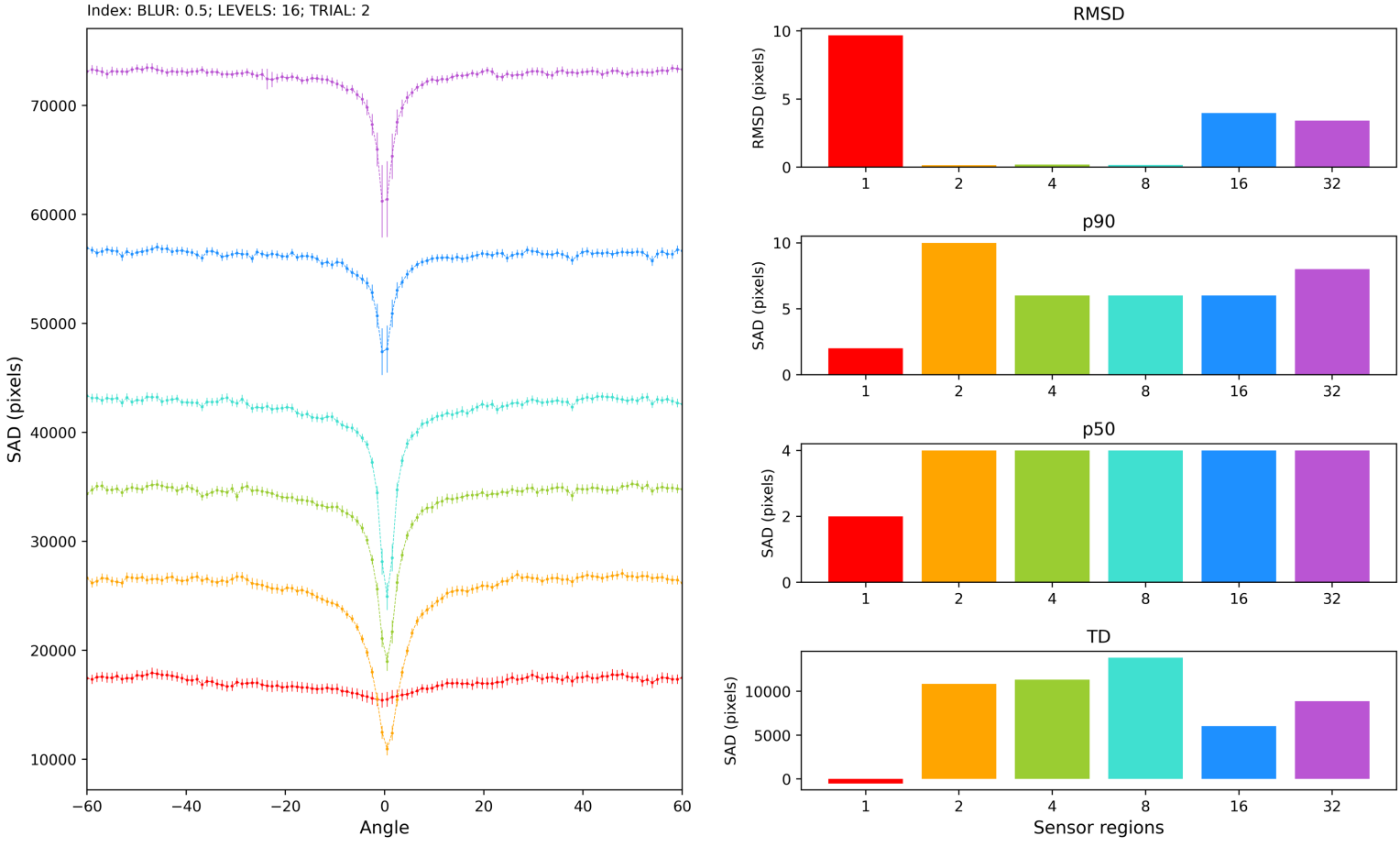
20%



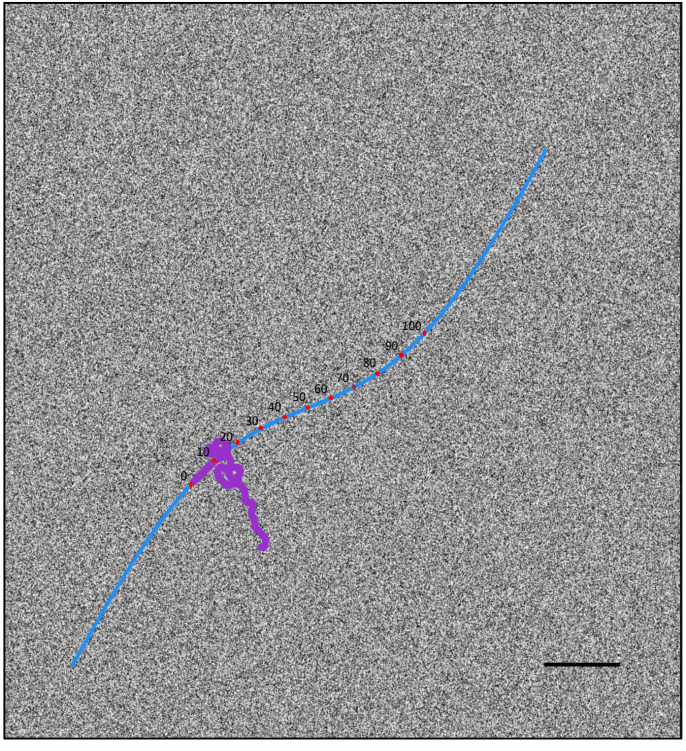


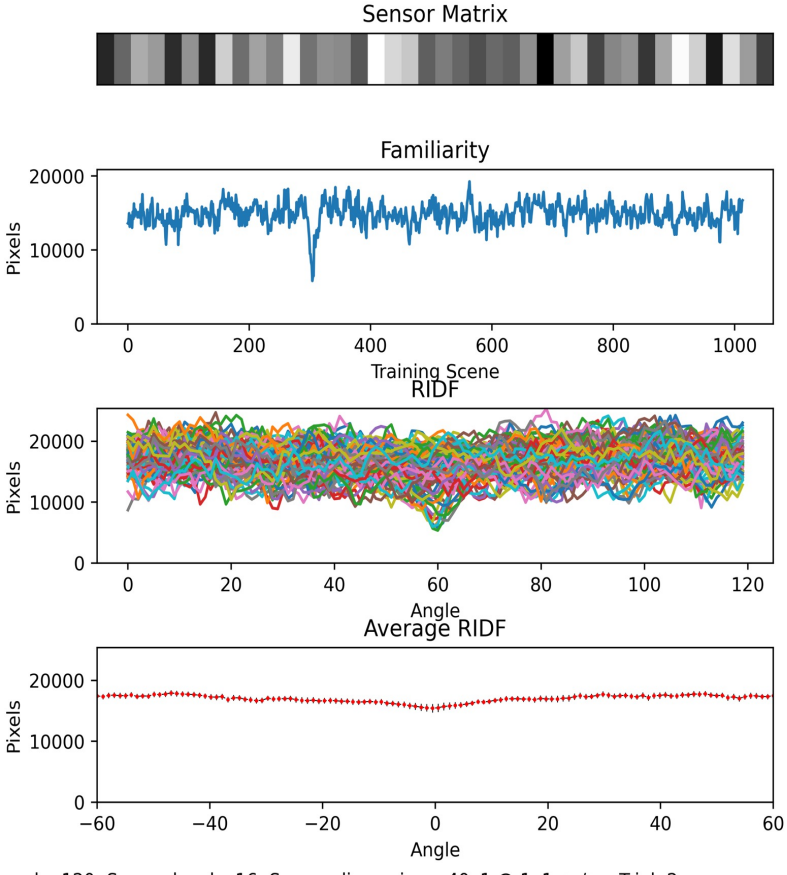
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4237.06; RMSD/dist: 10.593; TD: 3066; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 16; TRIAL: 2
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
1
2
4
8
16
32
p50
SAD (pixels)
4
2
0
1
2
4
8
16
32
TD
SAD (pixels)
10000
5000
0
1
2
4
8
16
32
Sensor regions

10%

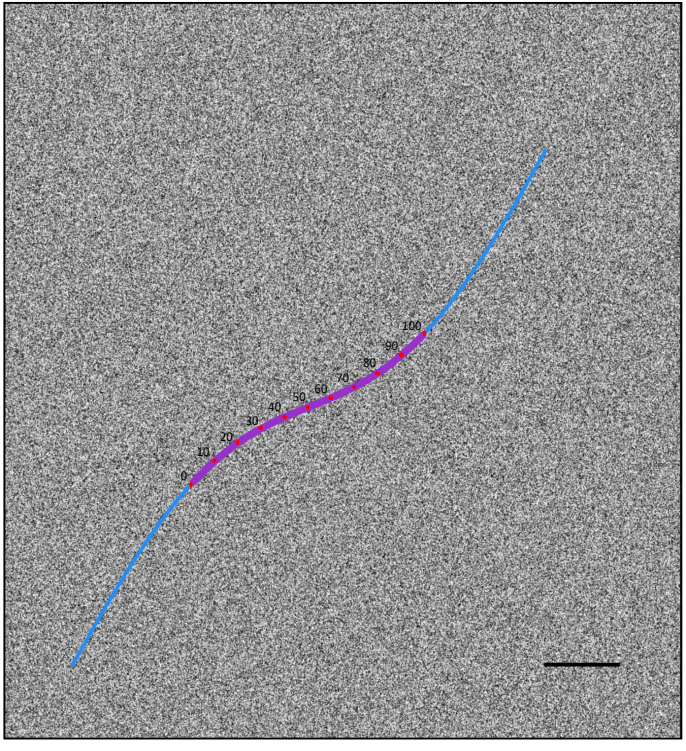


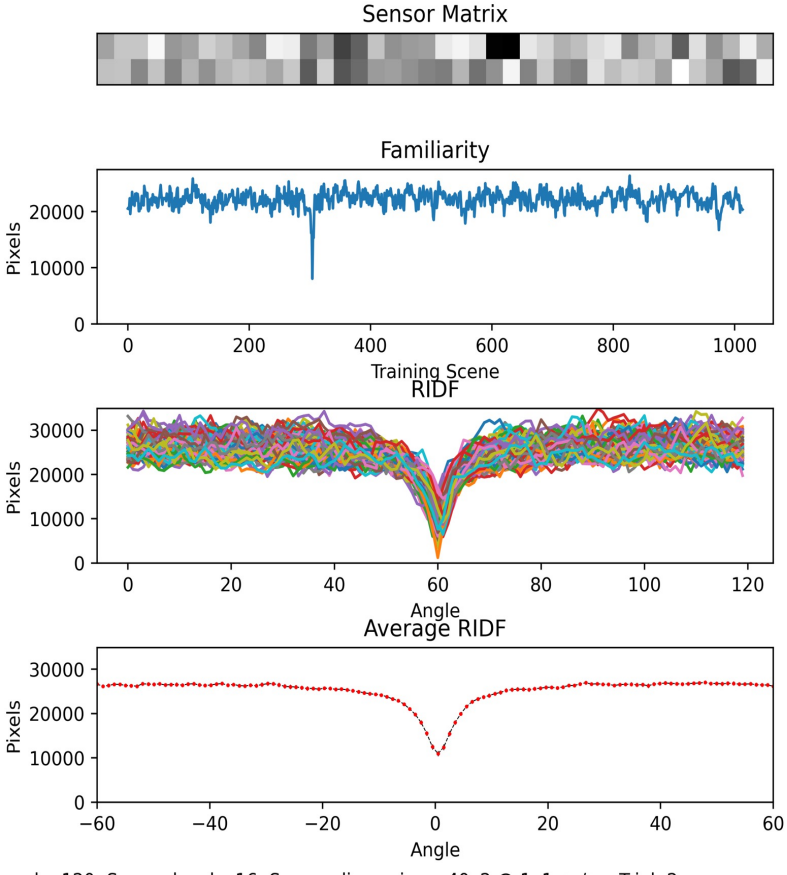


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 3875.26; RMSD/dist: 9.688; TD: -517; p90: 2; p50: 2; complete: 0

100%

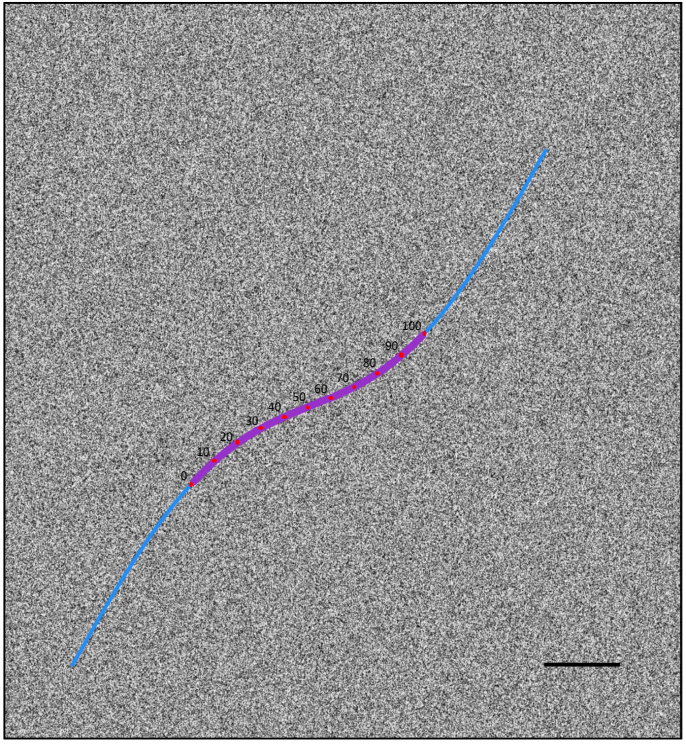


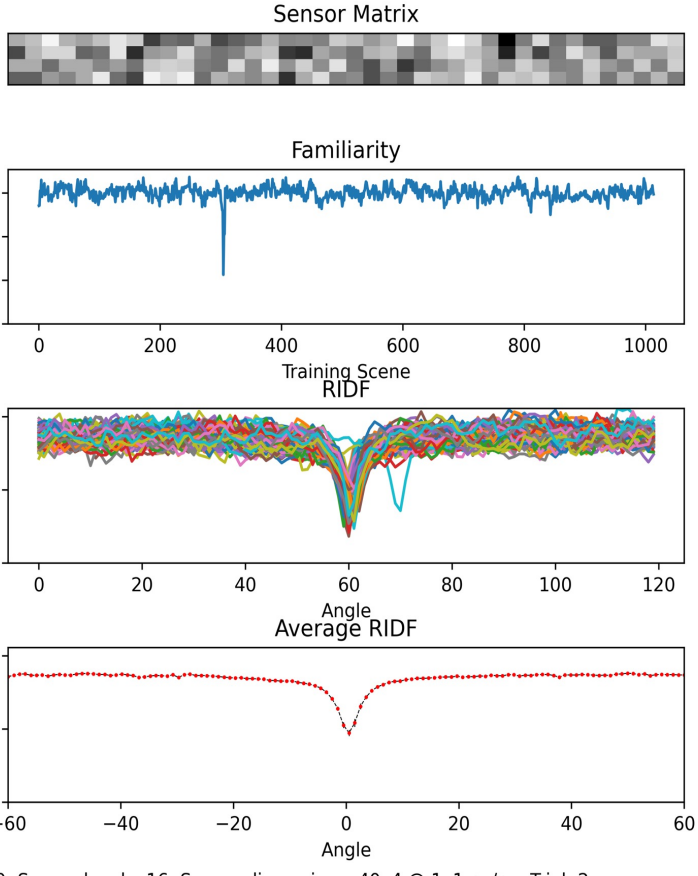


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 53.86; RMSD/dist: 0.135; TD: 10854; p90: 10; p50: 4; complete: 0

100%

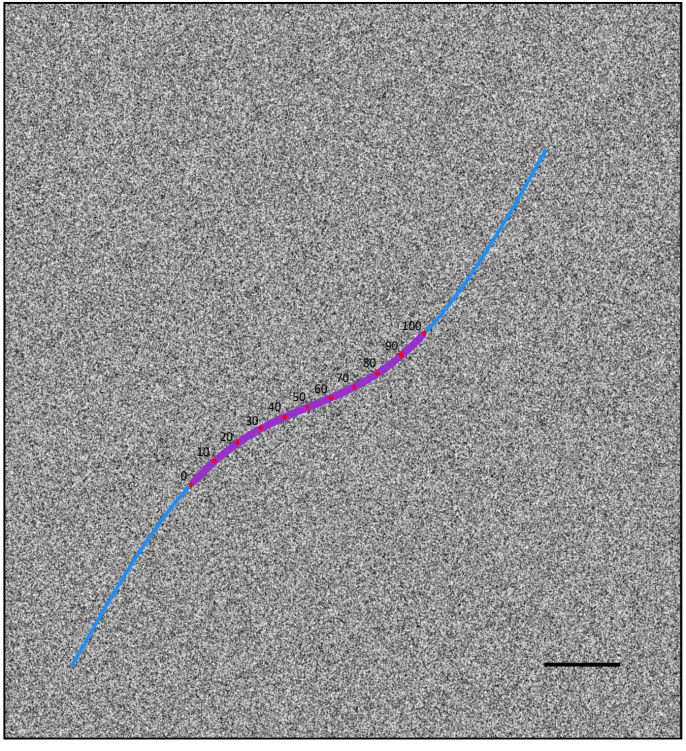


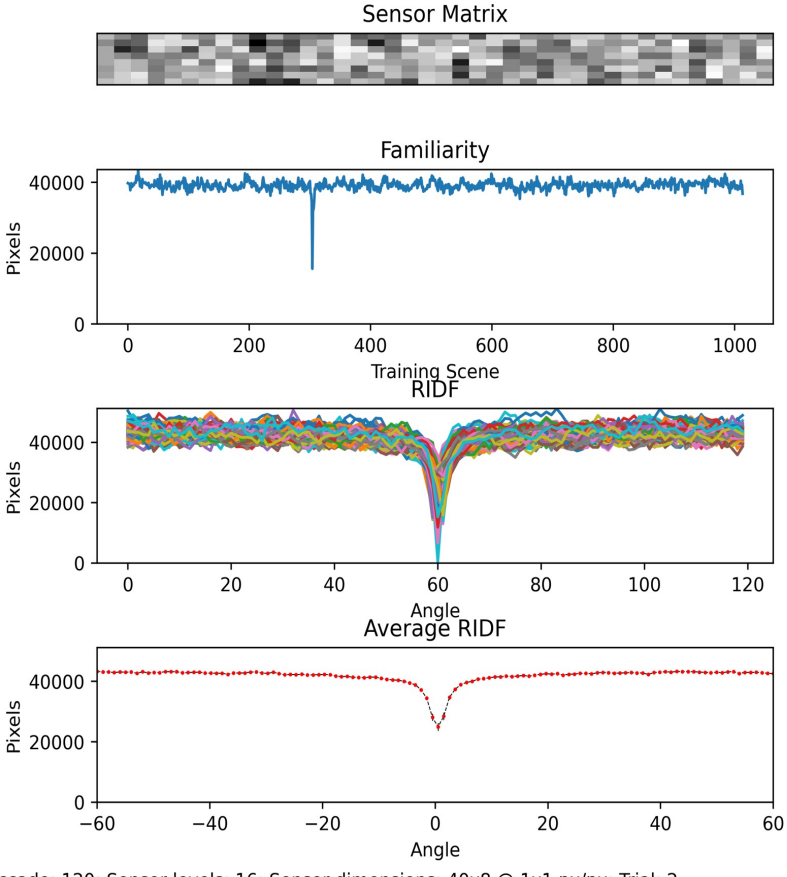


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 74.48; RMSD/dist: 0.186; TD: 11341; p90: 6; p50: 4; complete: 0

100%

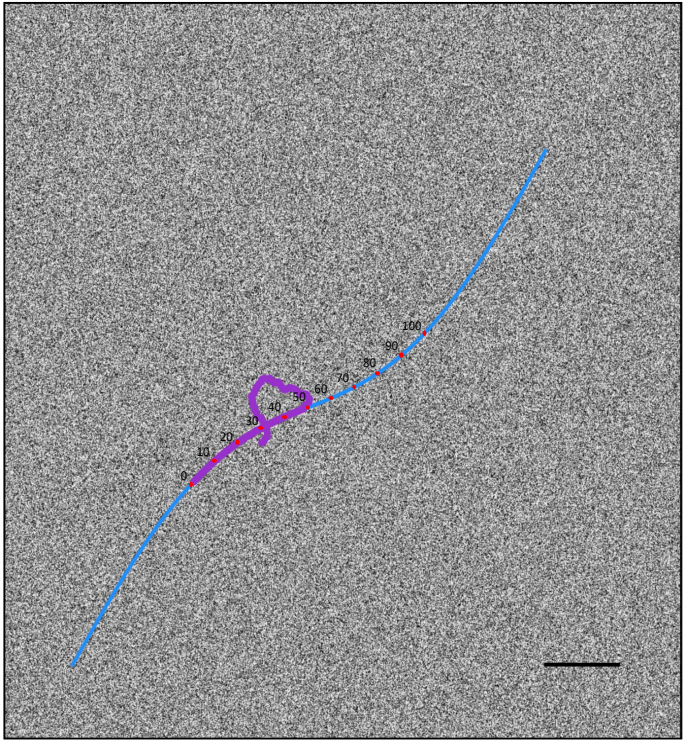


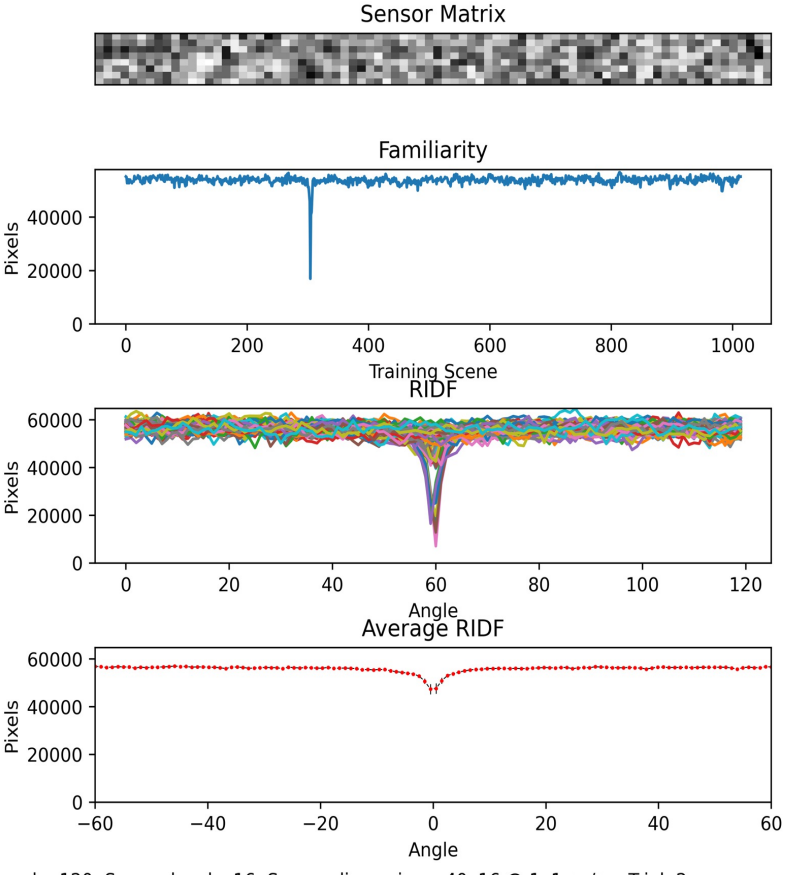


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 58.88; RMSD/dist: 0.147; TD: 13837; p90: 6; p50: 4; complete: 0

50%

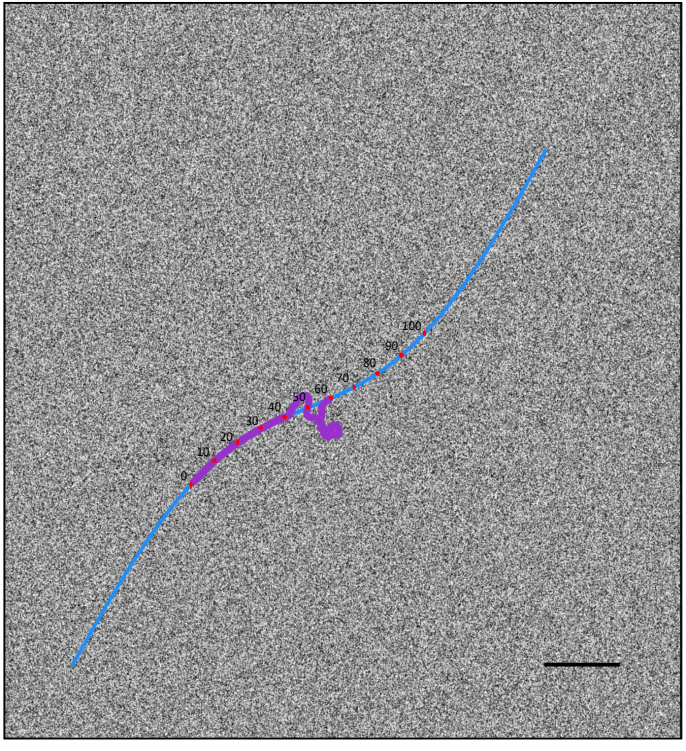


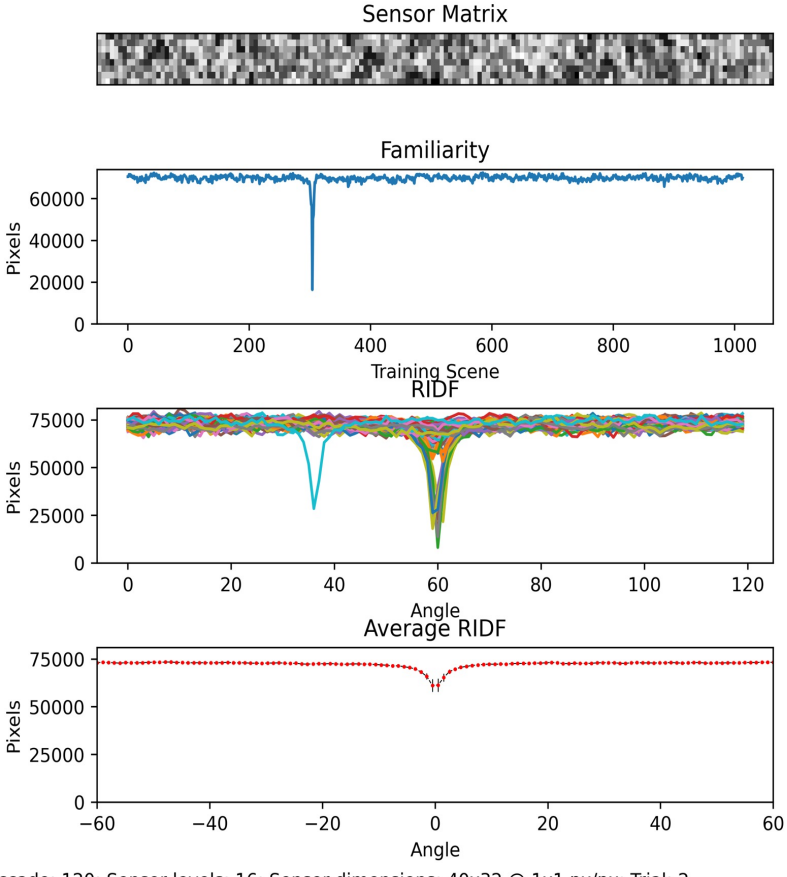


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1585.51; RMSD/dist: 3.964; TD: 6037; p90: 6; p50: 4; complete: 0

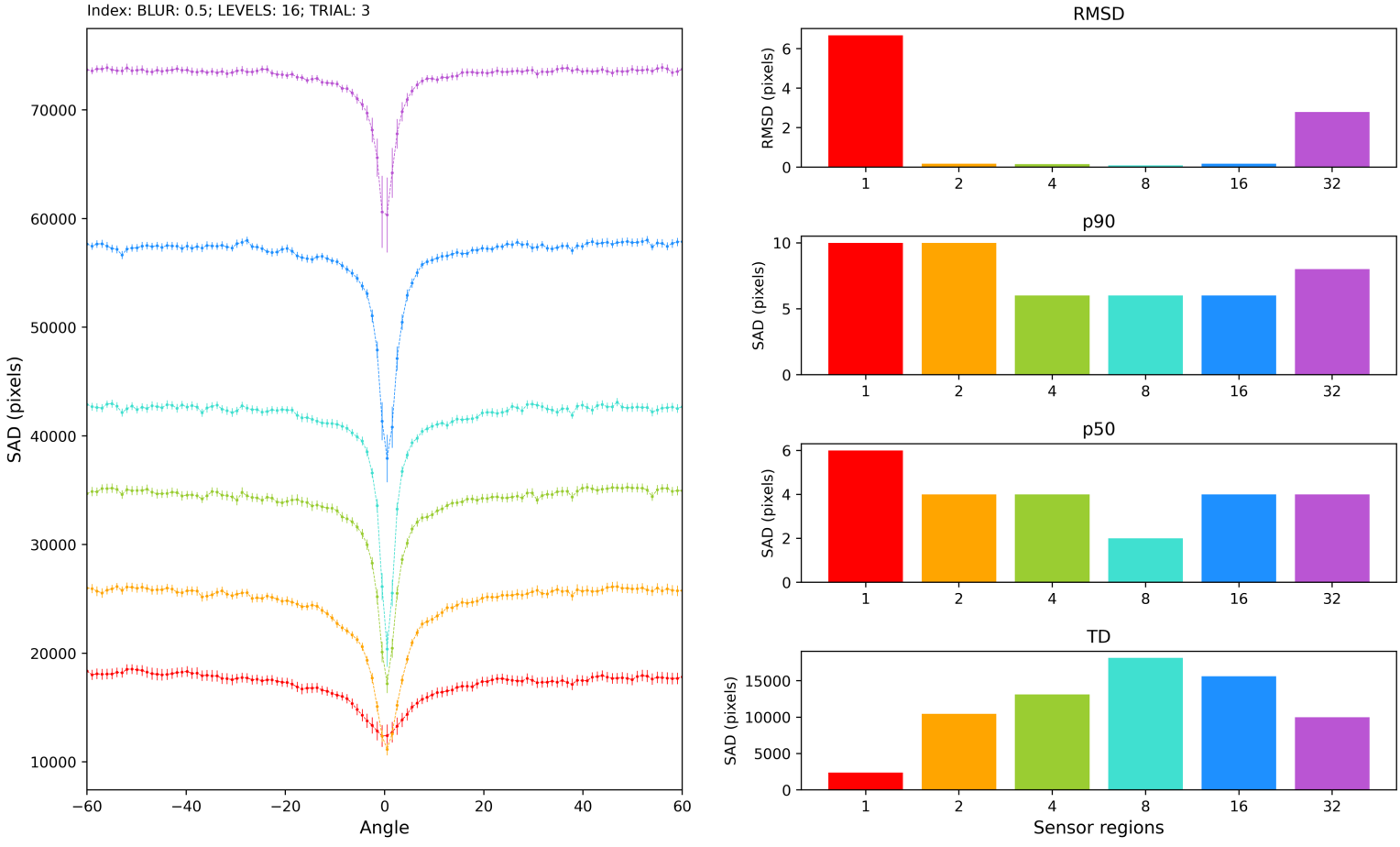
40%



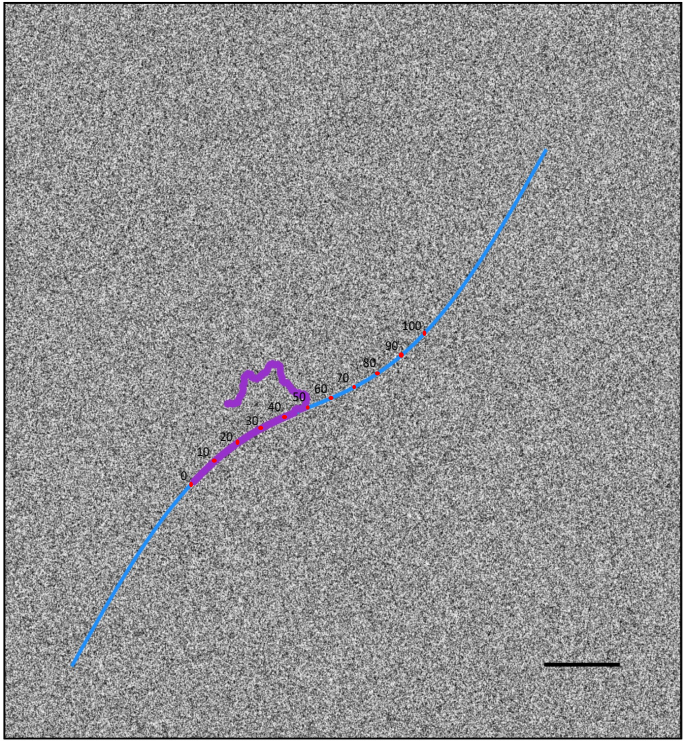


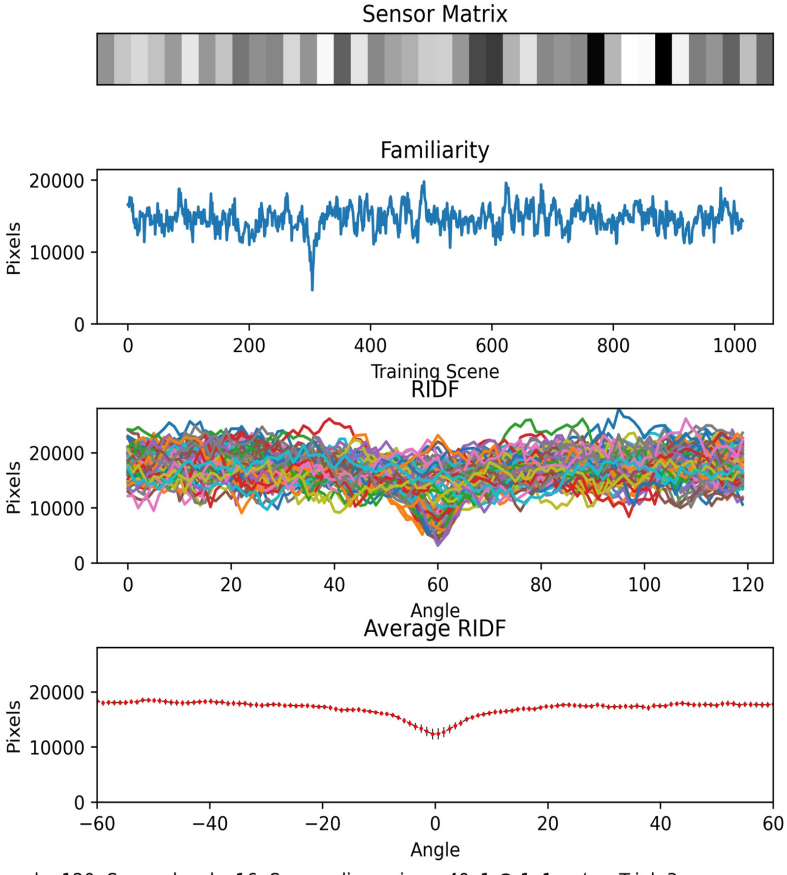
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1362.54; RMSD/dist: 3.406; TD: 8880; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 16; TRIAL: 3
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
6
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
6
4
2
0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

40%

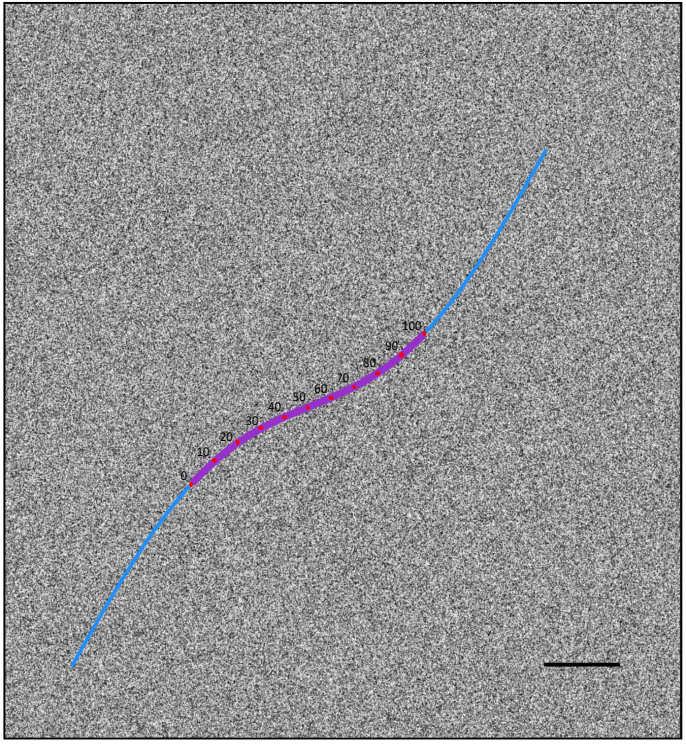


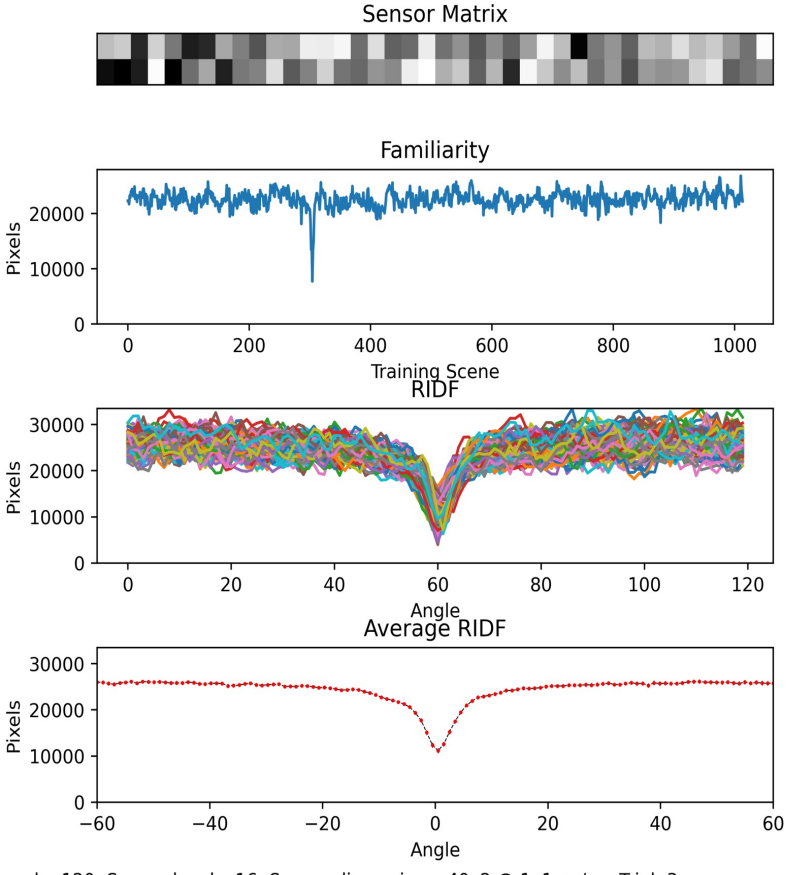


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2670.37; RMSD/dist: 6.676; TD: 2366; p90: 10; p50: 6; complete: 0

100%

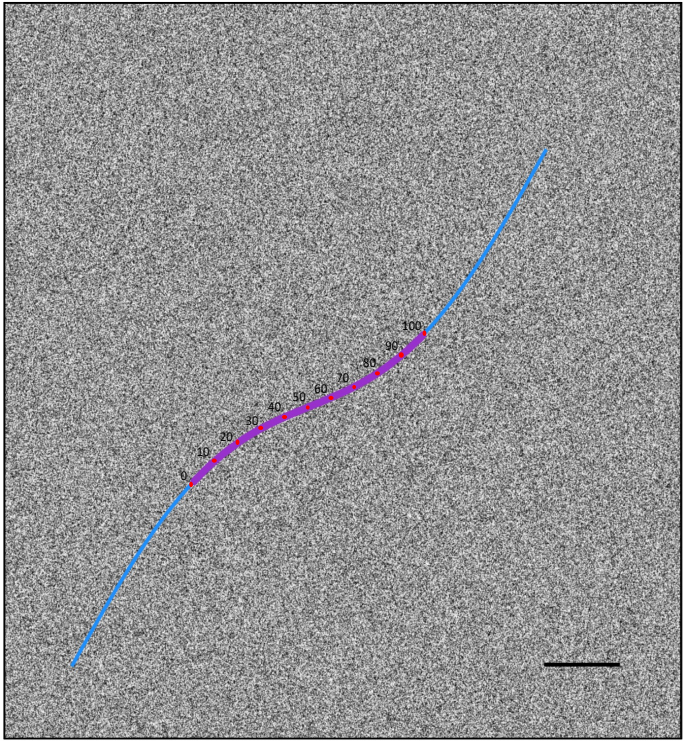


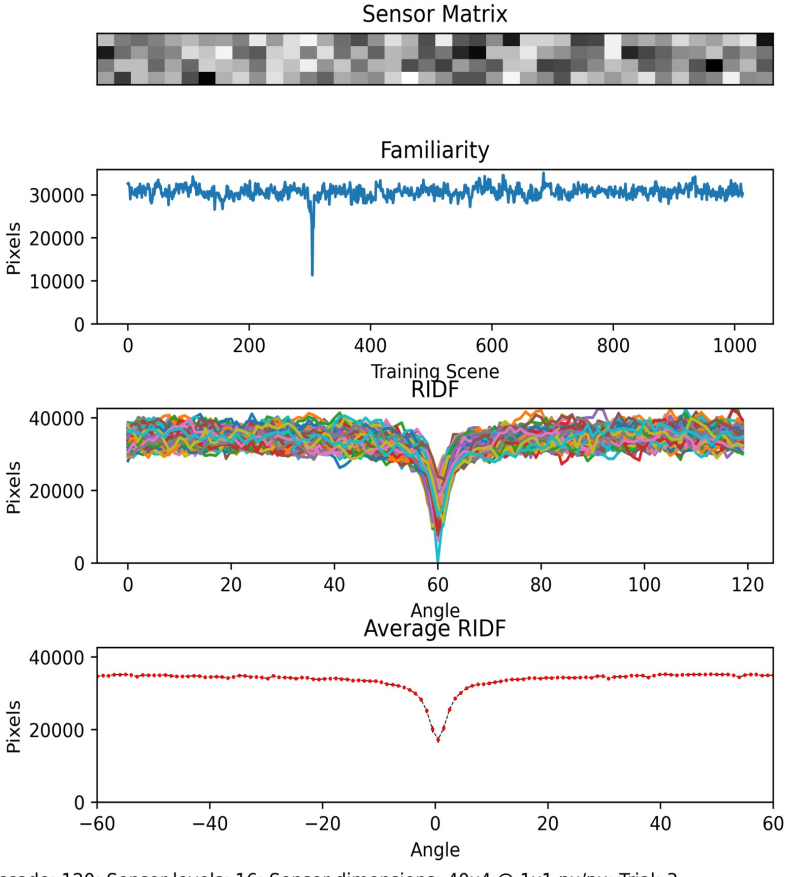


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 65.71; RMSD/dist: 0.164; TD: 10440; p90: 10; p50: 4; complete: 0

100%

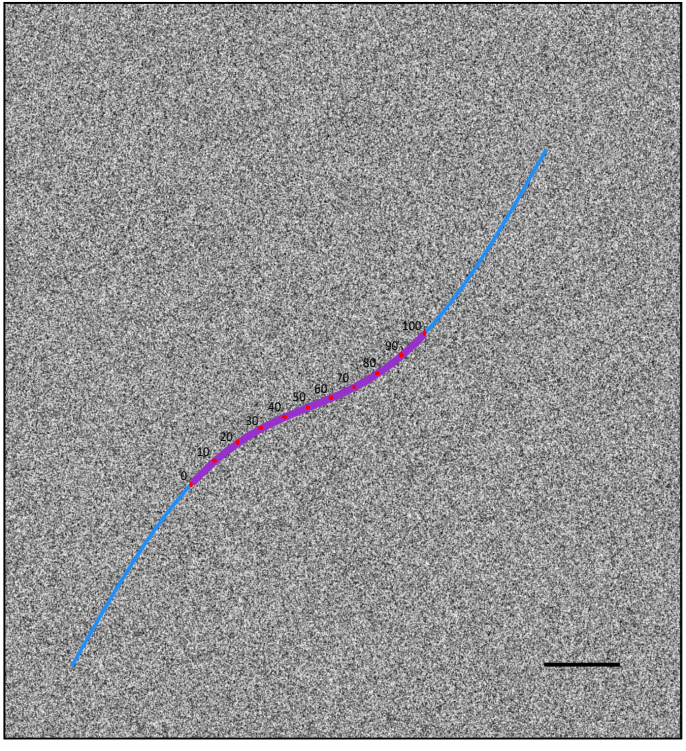


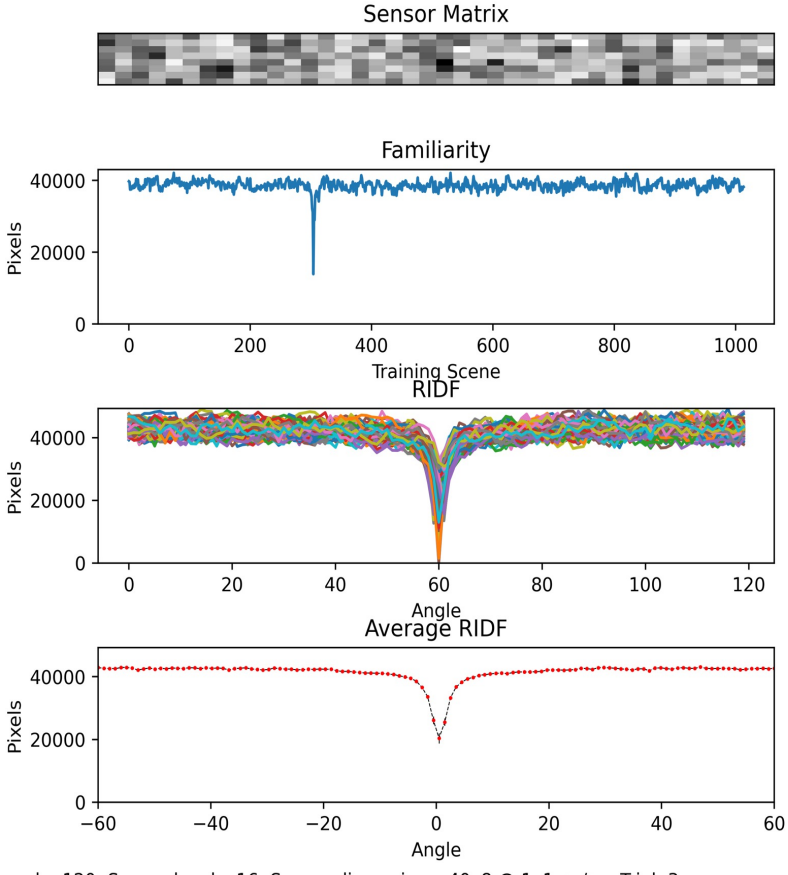


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 60.43; RMSD/dist: 0.151; TD: 13136; p90: 6; p50: 4; complete: 0

100%

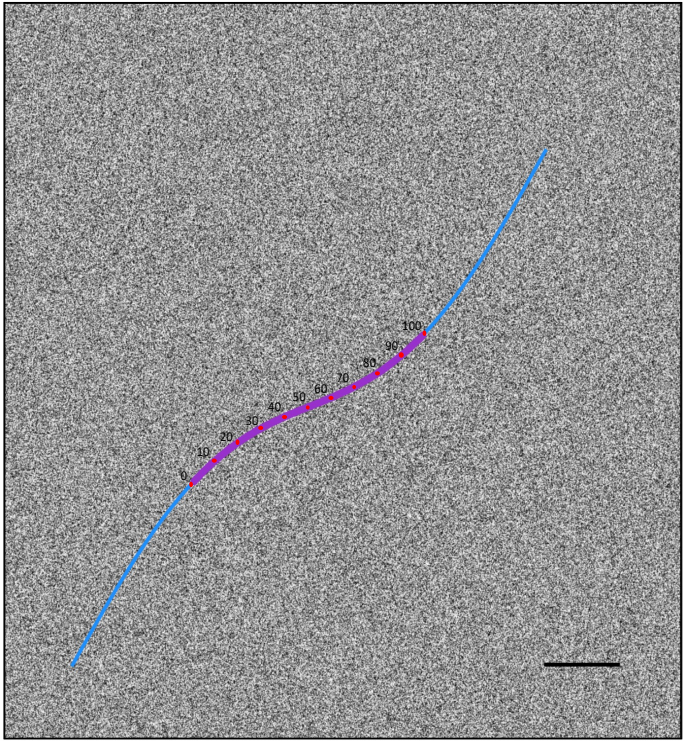


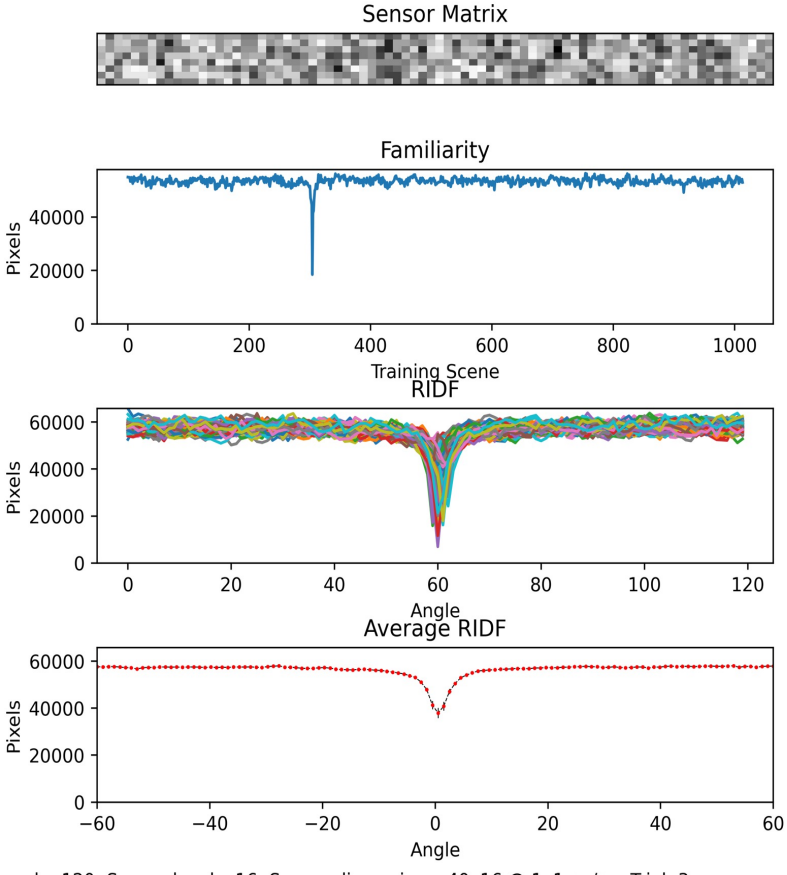


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 31.31; RMSD/dist: 0.078; TD: 18137; p90: 6; p50: 2; complete: 0

100%

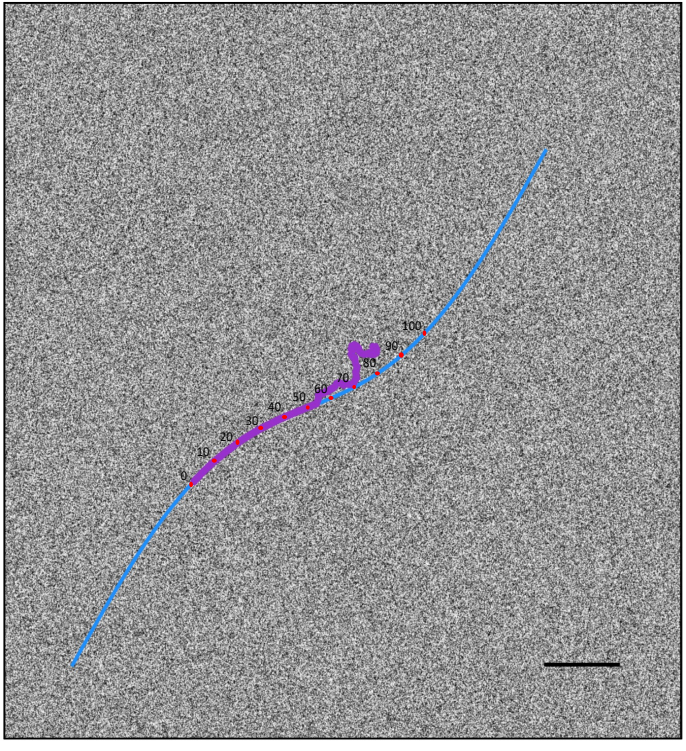


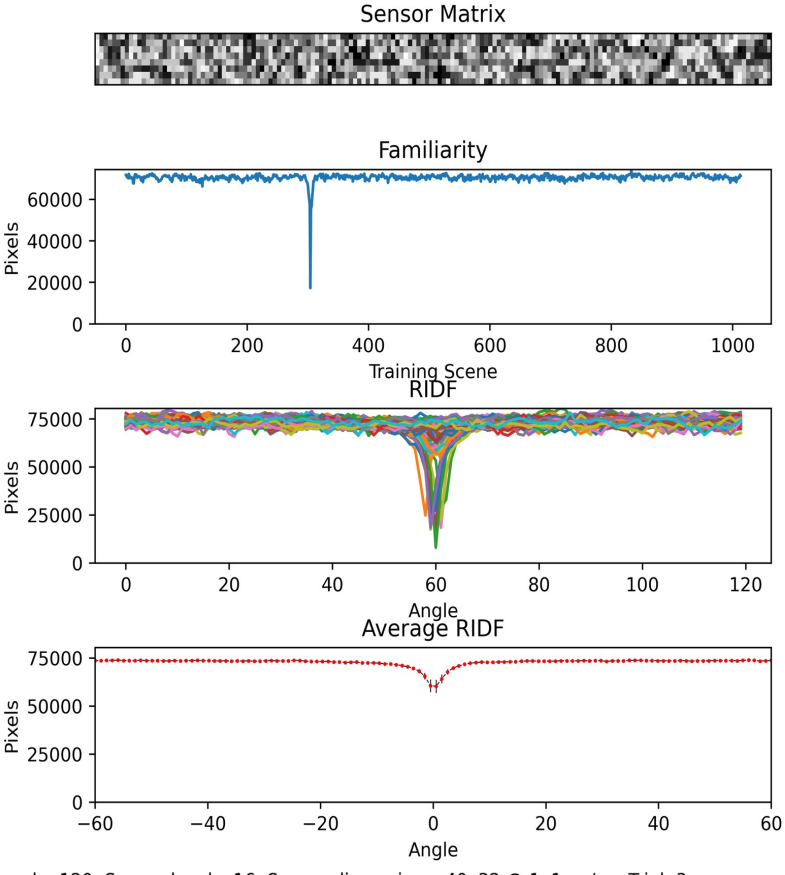


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 69.08; RMSD/dist: 0.173; TD: 15620; p90: 6; p50: 4; complete: 0

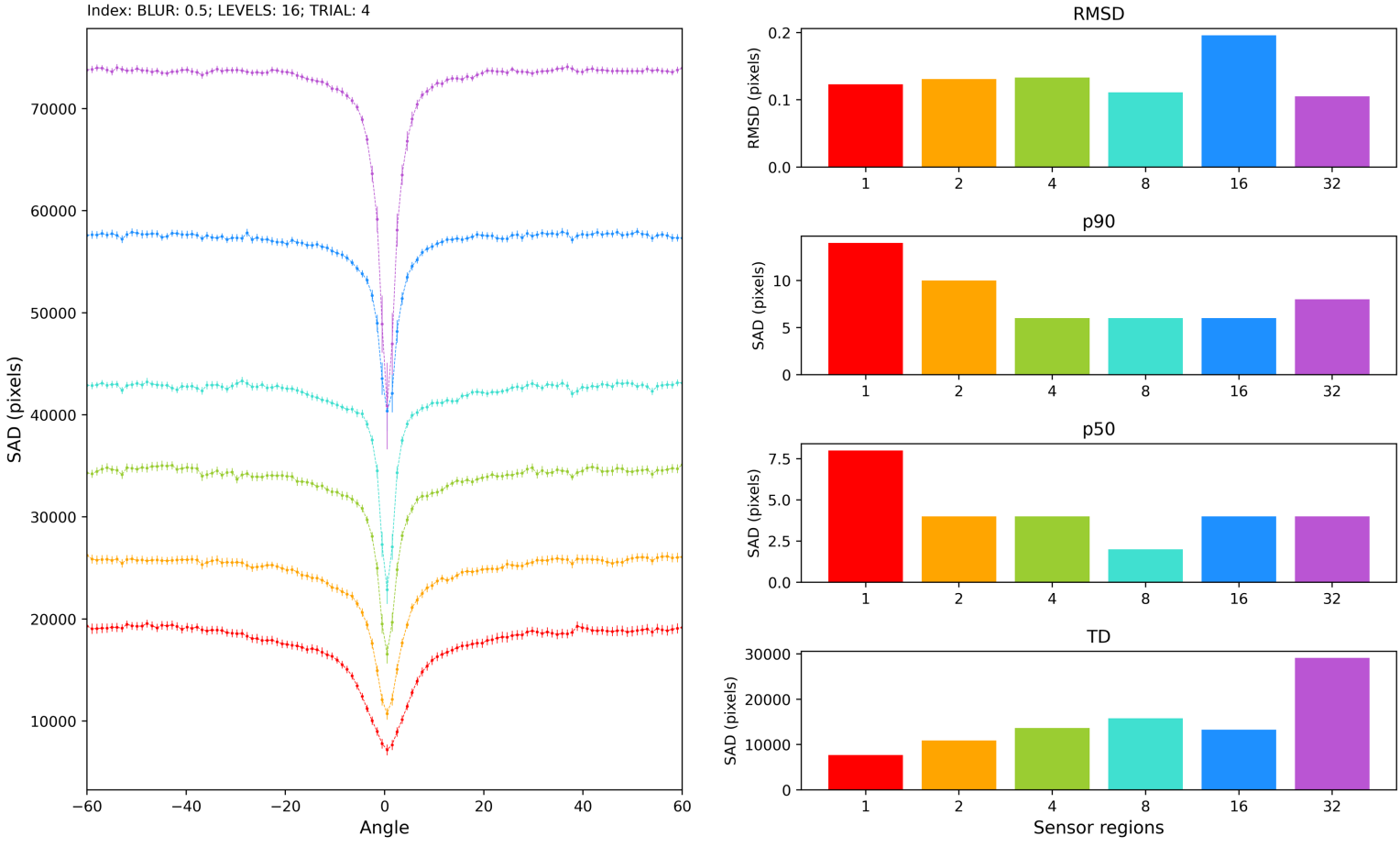
50%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1114.71; RMSD/dist: 2.787; TD: 9983; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 16; TRIAL: 4
SAD (pixels)
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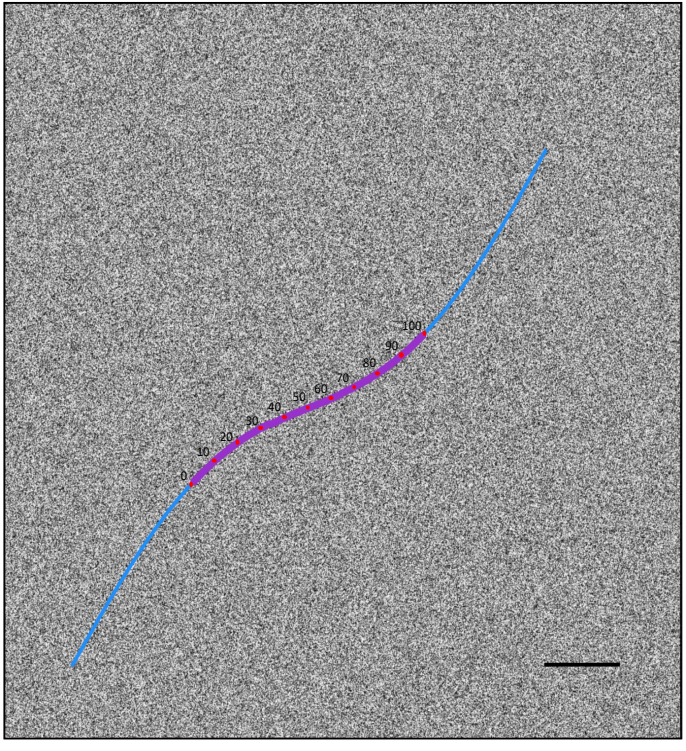
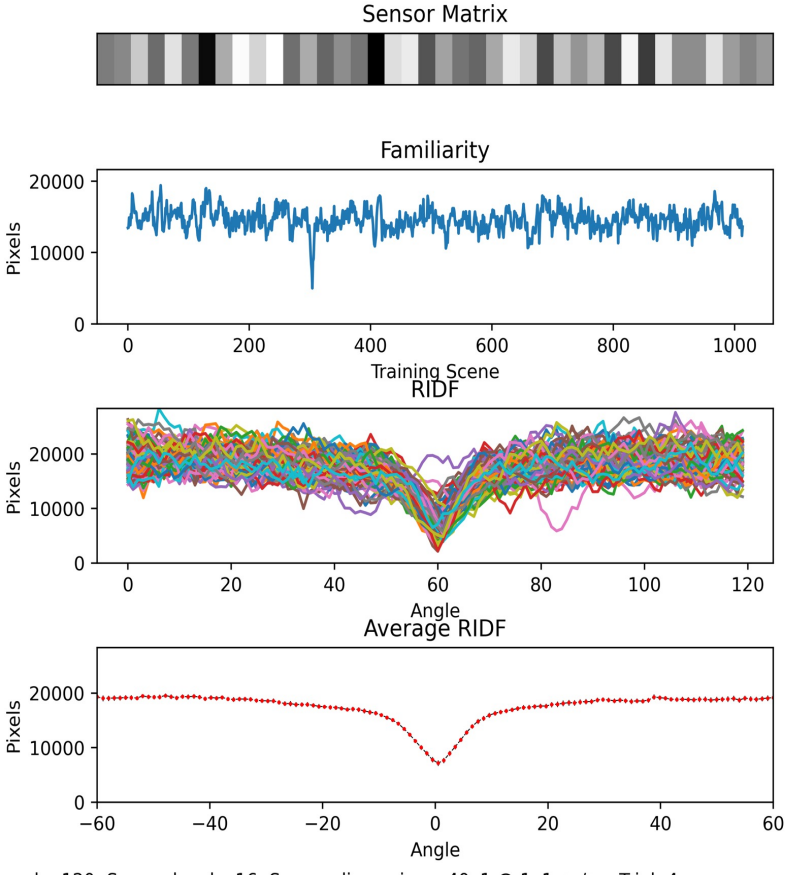
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
30000
20000
10000
0
Sensor regions

100%

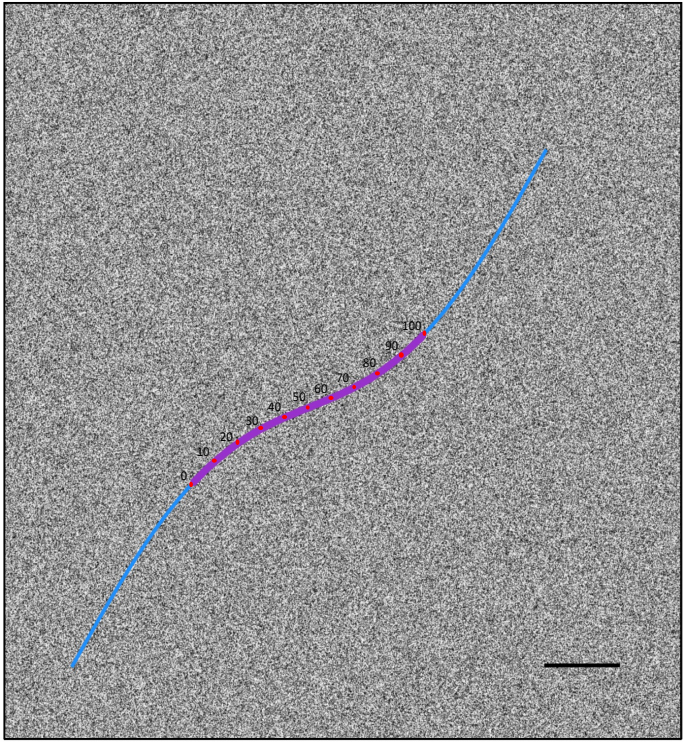


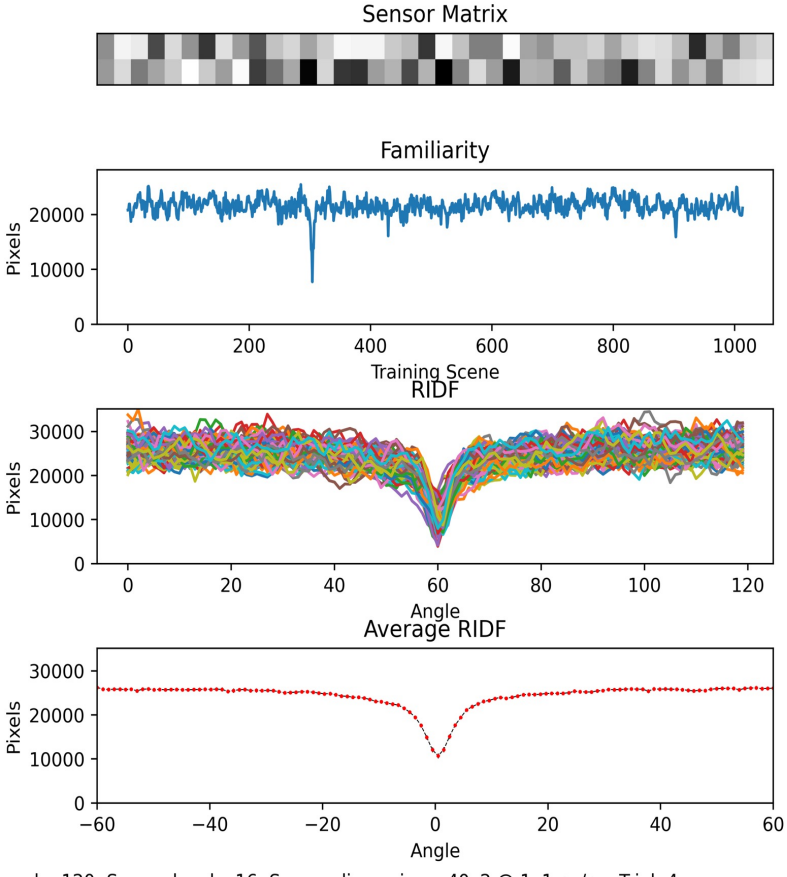


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 49.33; RMSD/dist: 0.123; TD: 7684; p90: 14; p50: 8; complete: 0

100%

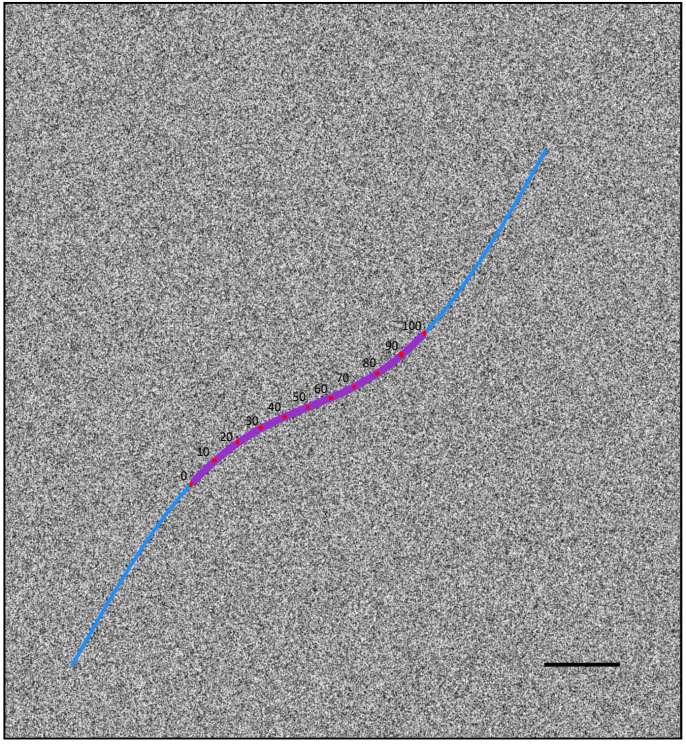


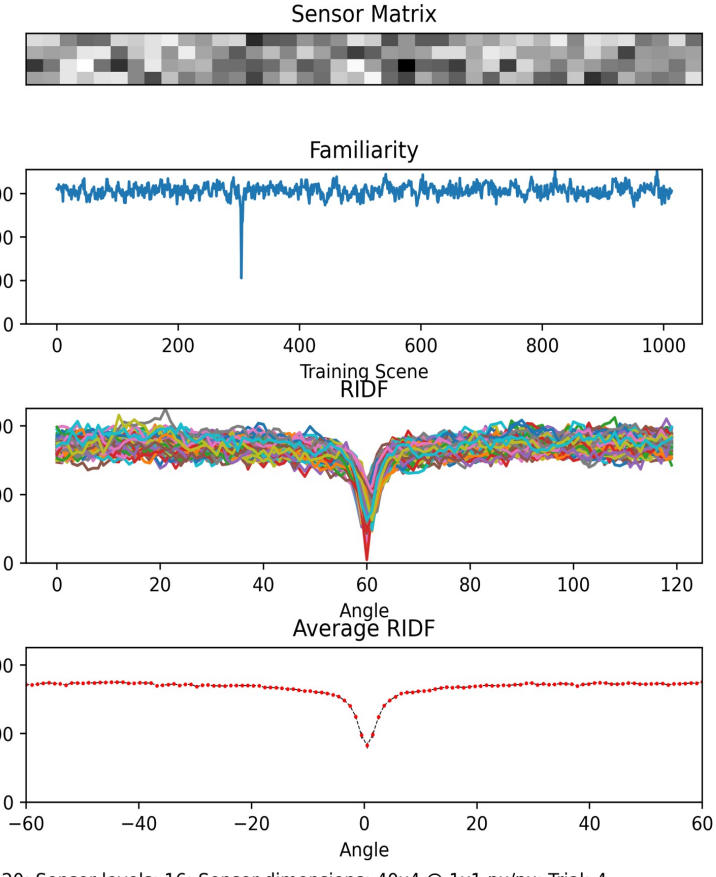


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 52.46; RMSD/dist: 0.131; TD: 10888; p90: 10; p50: 4; complete: 0

100%





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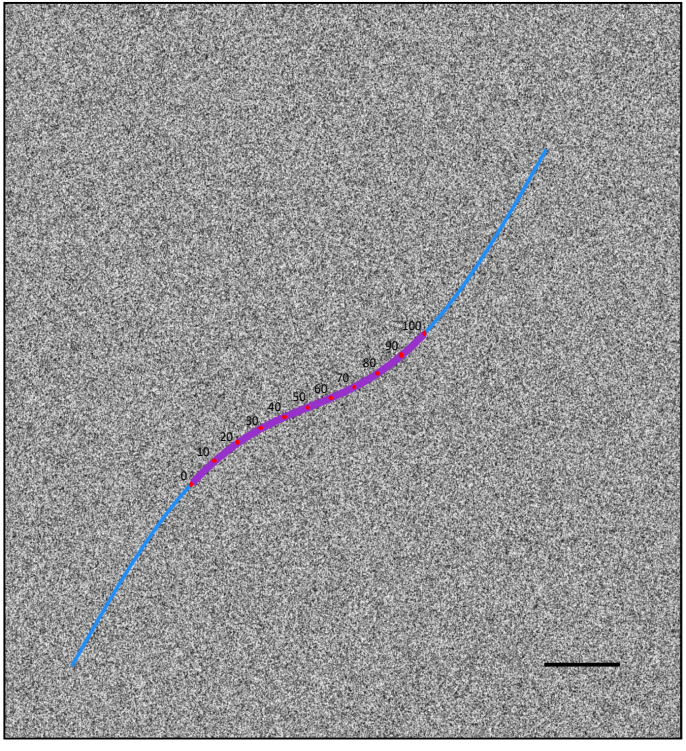
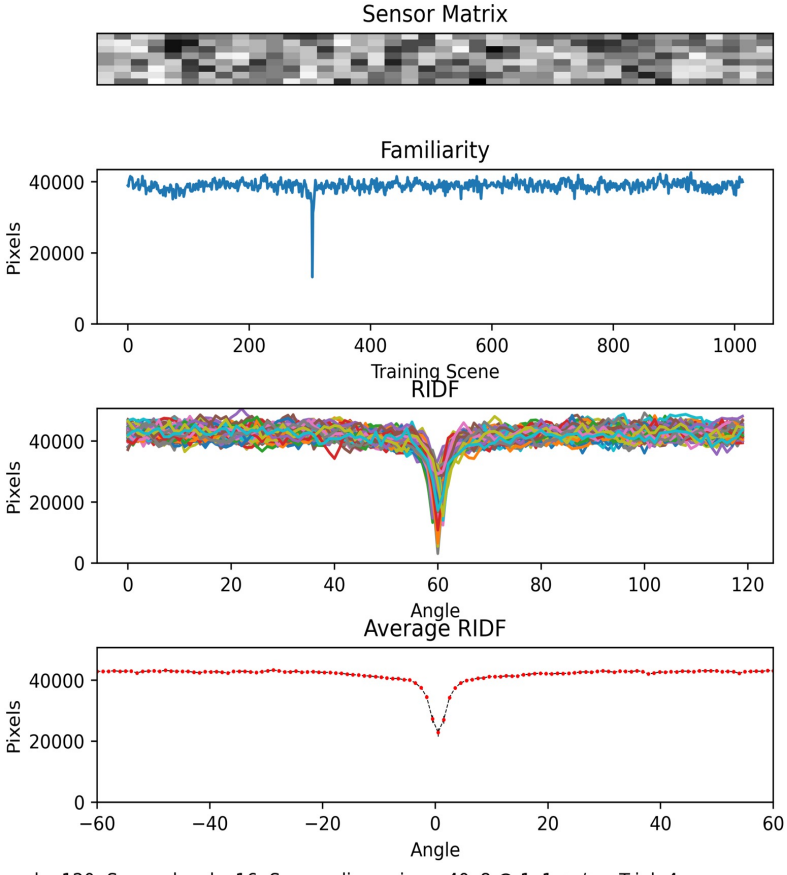
Navigation stats: RMSD error: 53.10; RMSD/dist: 0.133; TD: 13642; p90: 6; p50: 4; complete: 0

100%

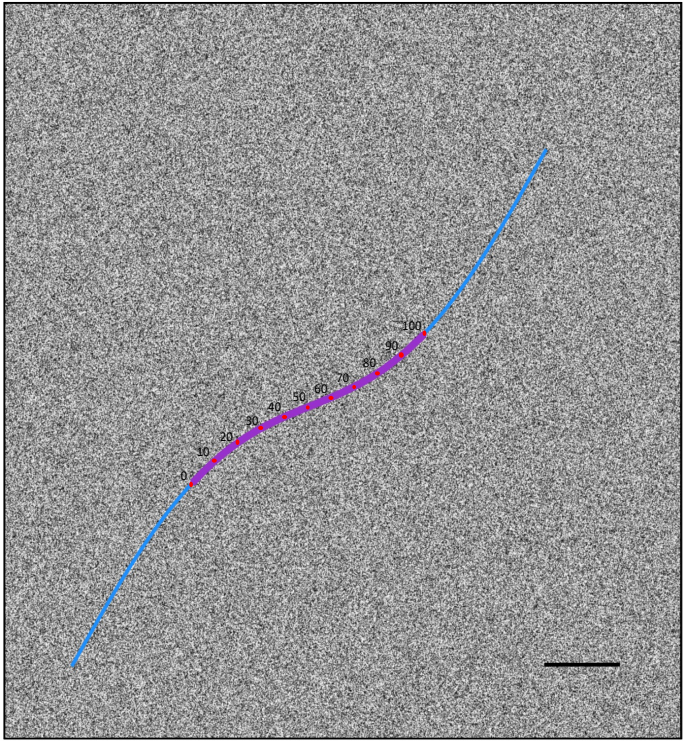


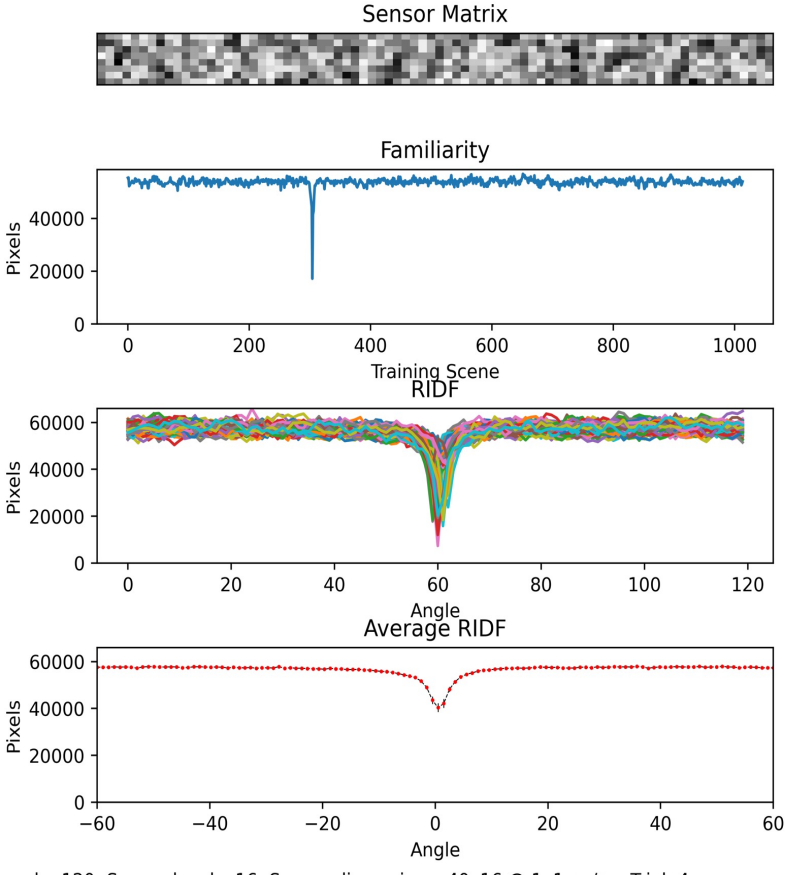


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 44.20; RMSD/dist: 0.111; TD: 15811; p90: 6; p50: 2; complete: 0

100%

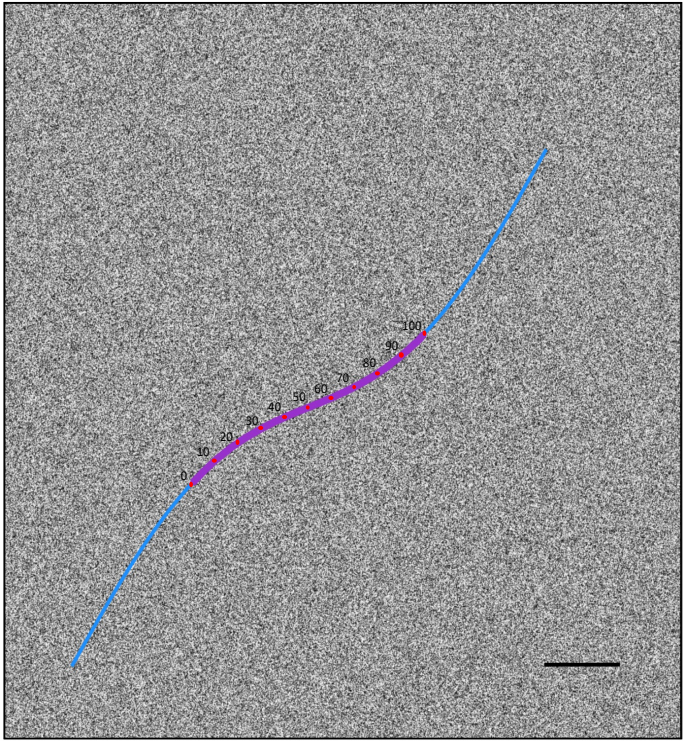


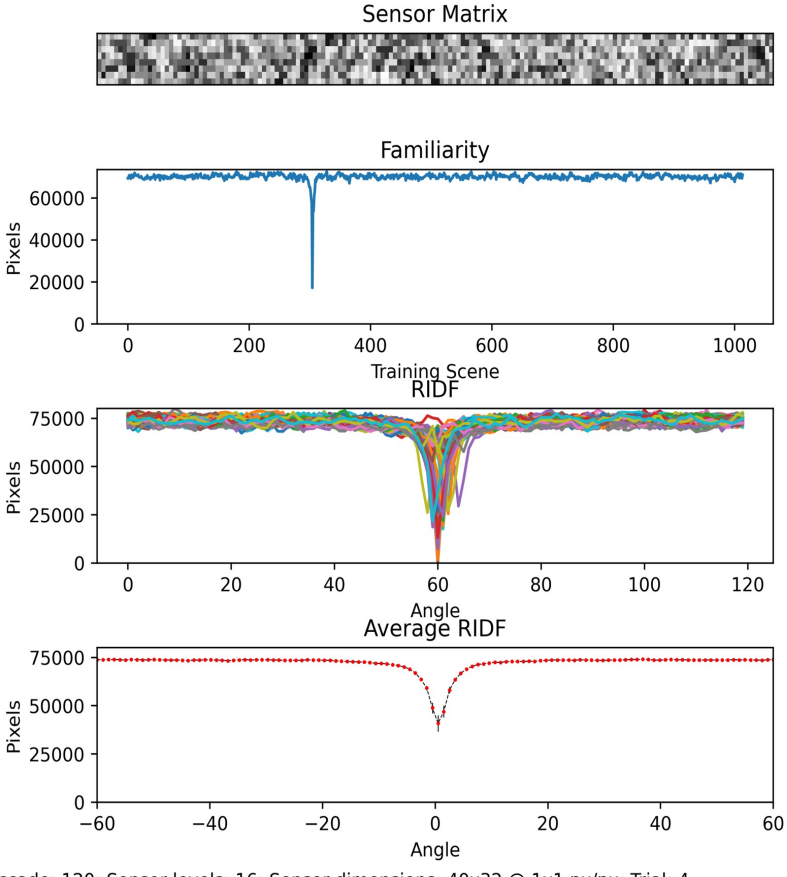


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 78.47; RMSD/dist: 0.196; TD: 13289; p90: 6; p50: 4; complete: 0

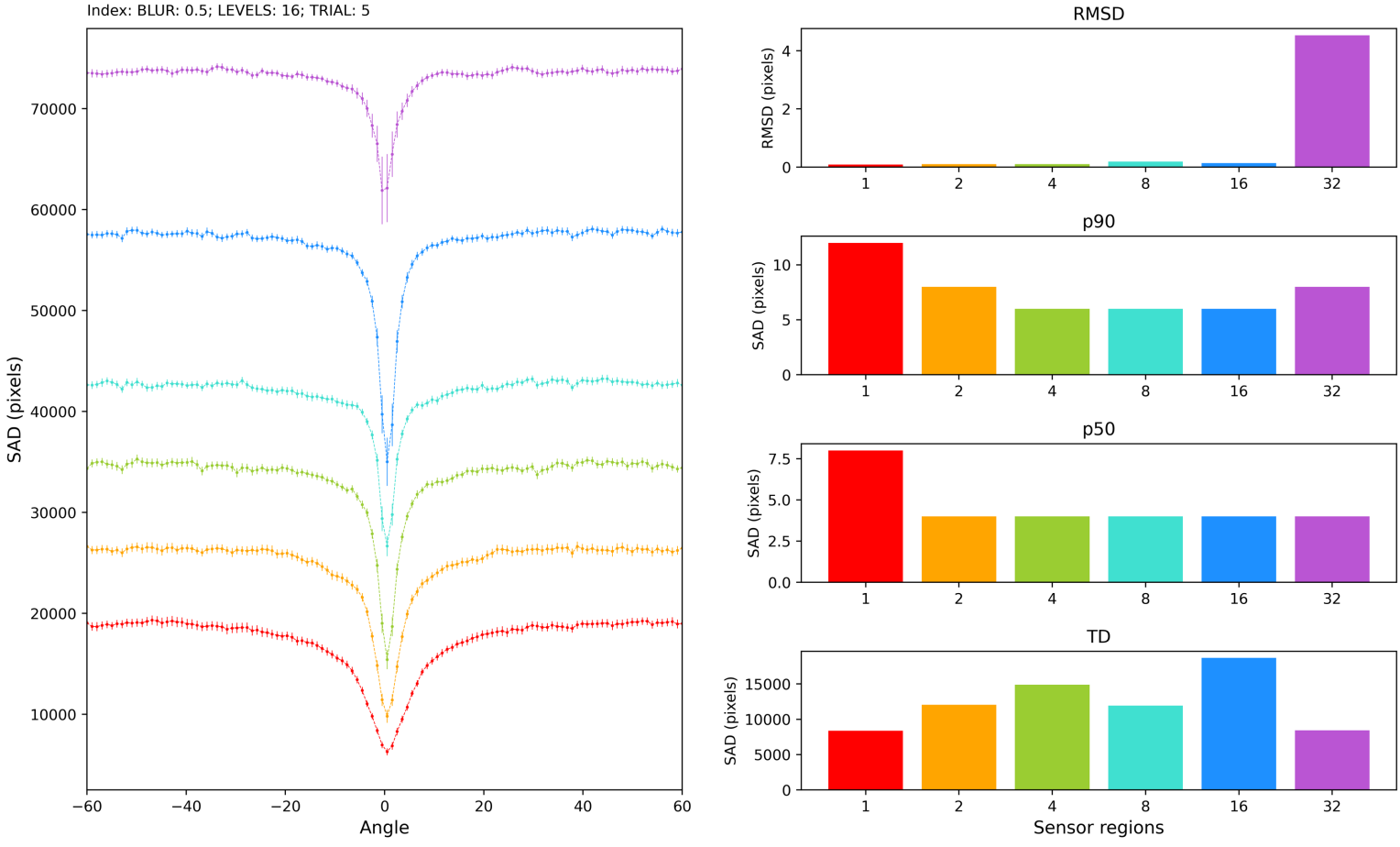
100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 41.95; RMSD/dist: 0.105; TD: 29106; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 16; TRIAL: 5
SAD (pixels)
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40000
30000
20000
10000
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−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
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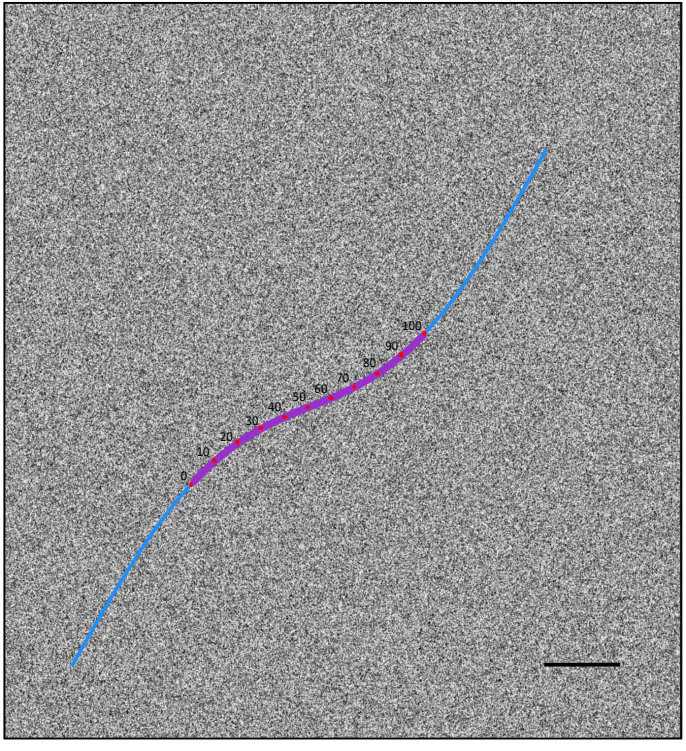
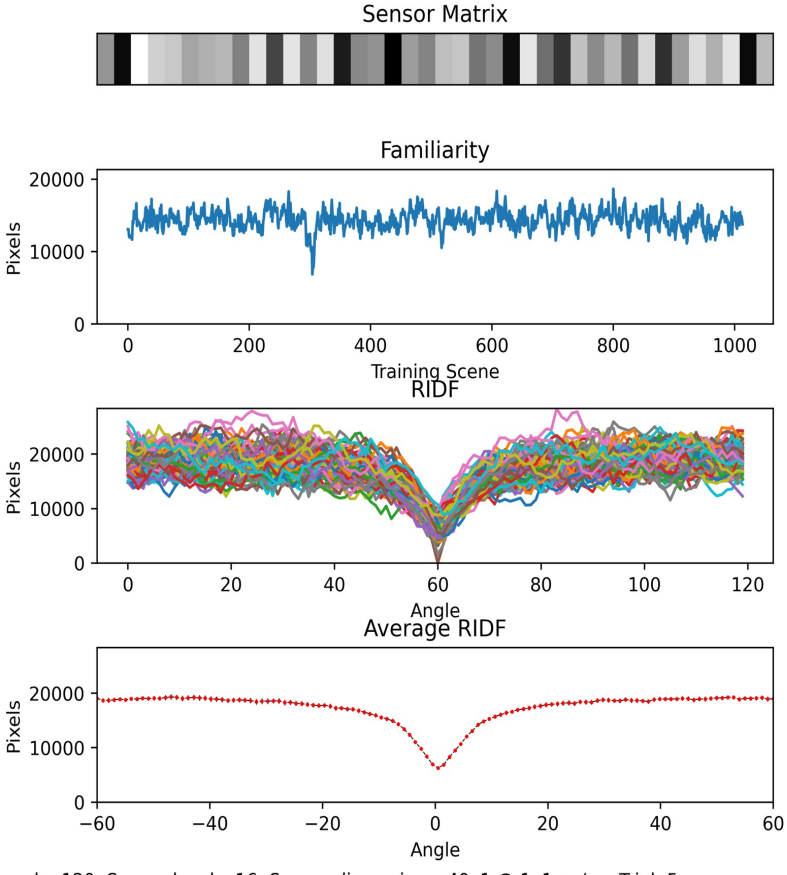
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

100%

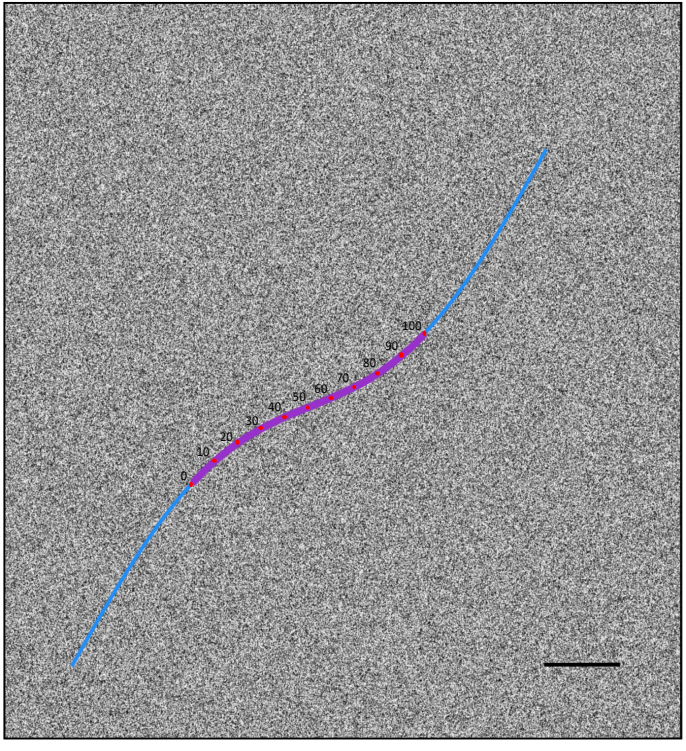


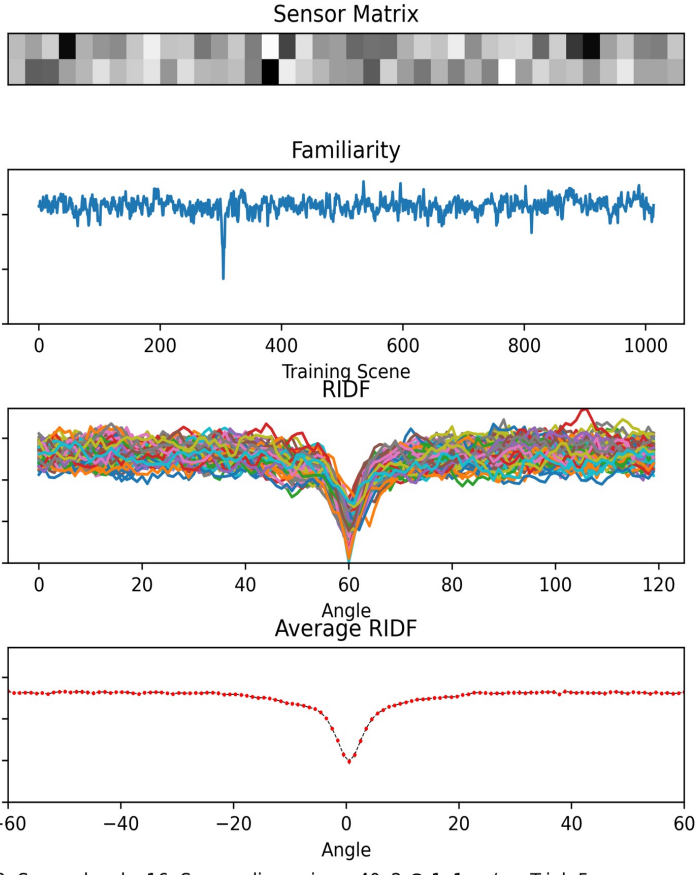


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 34.81; RMSD/dist: 0.087; TD: 8364; p90: 12; p50: 8; complete: 0

100%

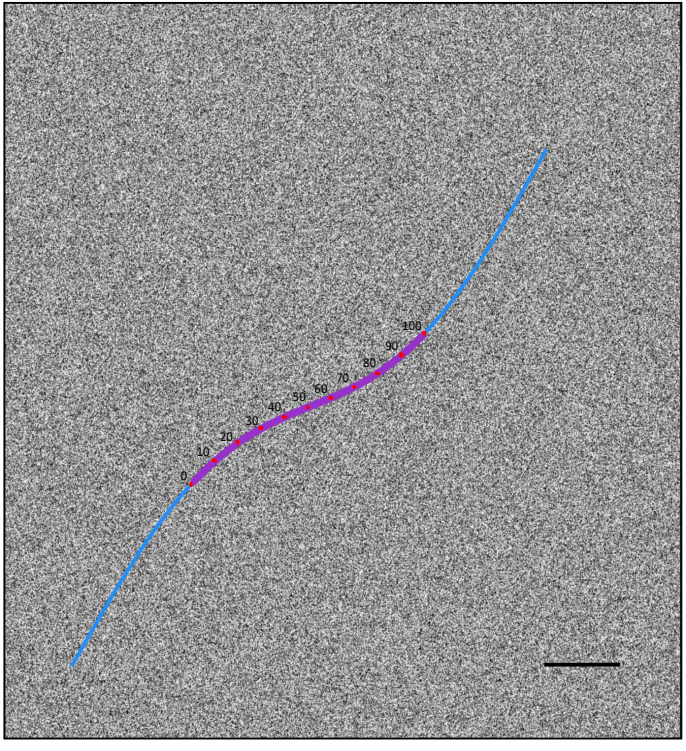


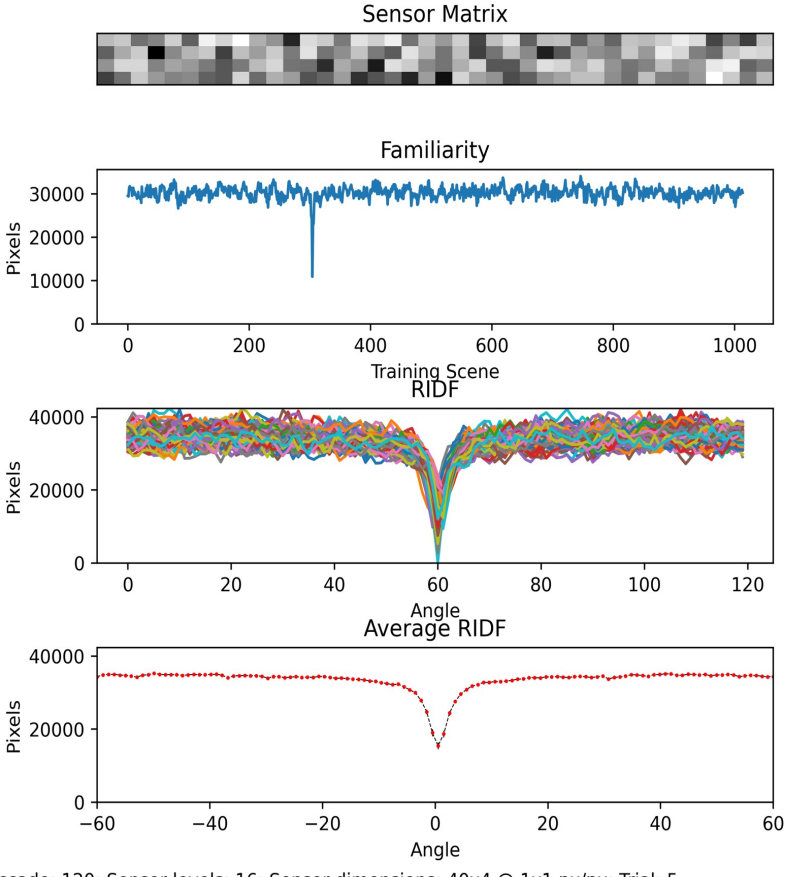


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 38.53; RMSD/dist: 0.096; TD: 12052; p90: 8; p50: 4; complete: 0

100%

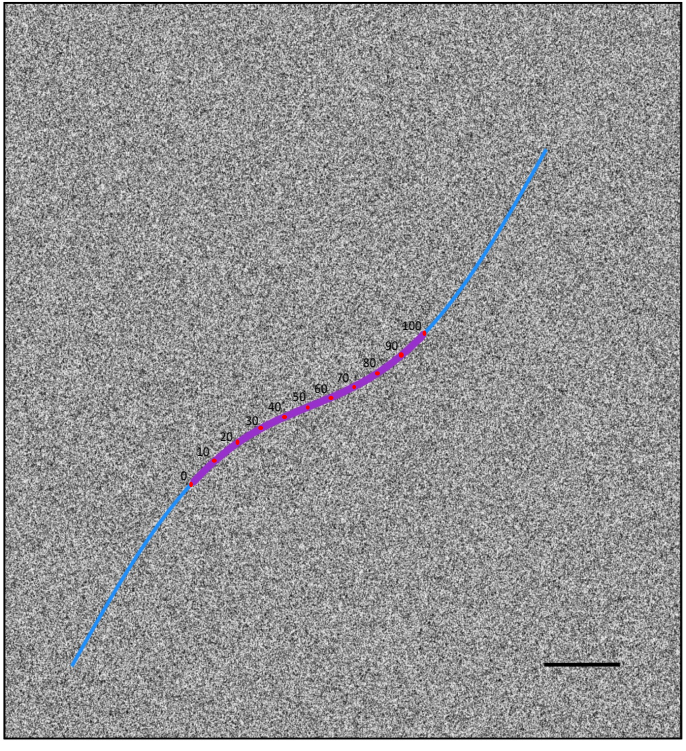


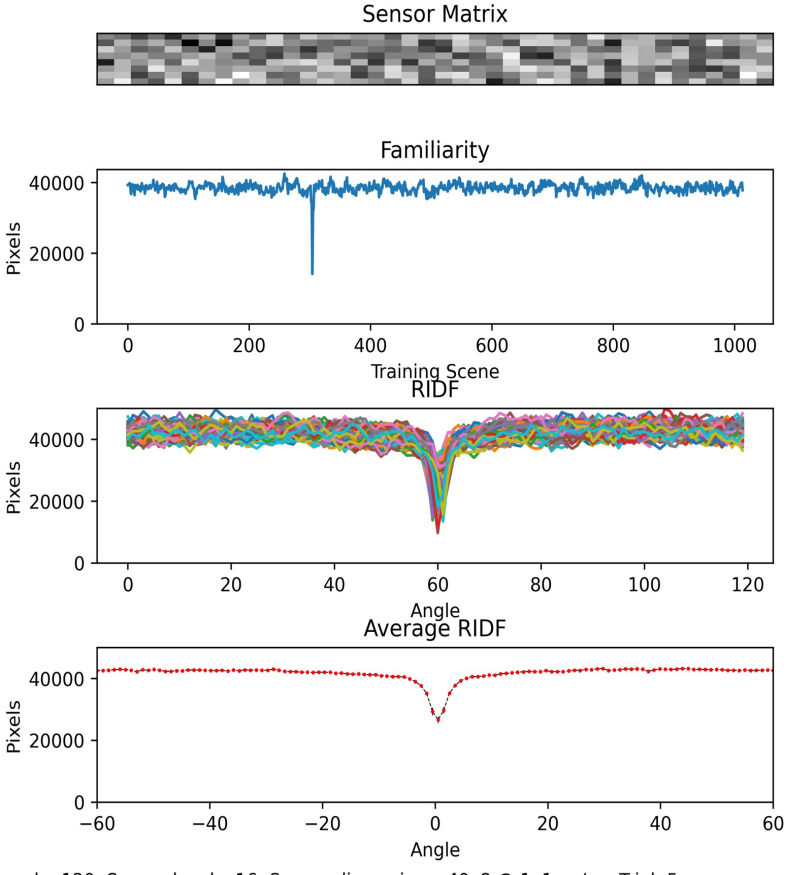


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 40.55; RMSD/dist: 0.101; TD: 14885; p90: 6; p50: 4; complete: 0

100%

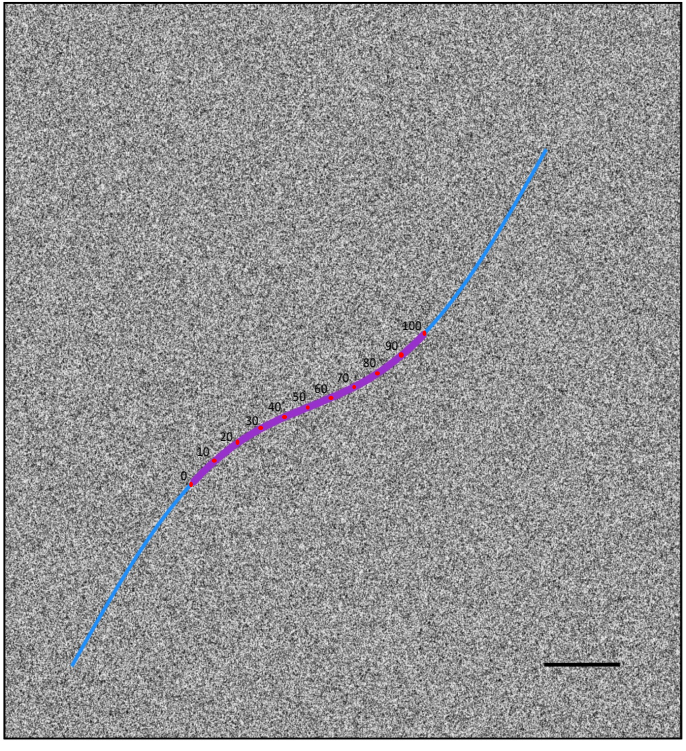


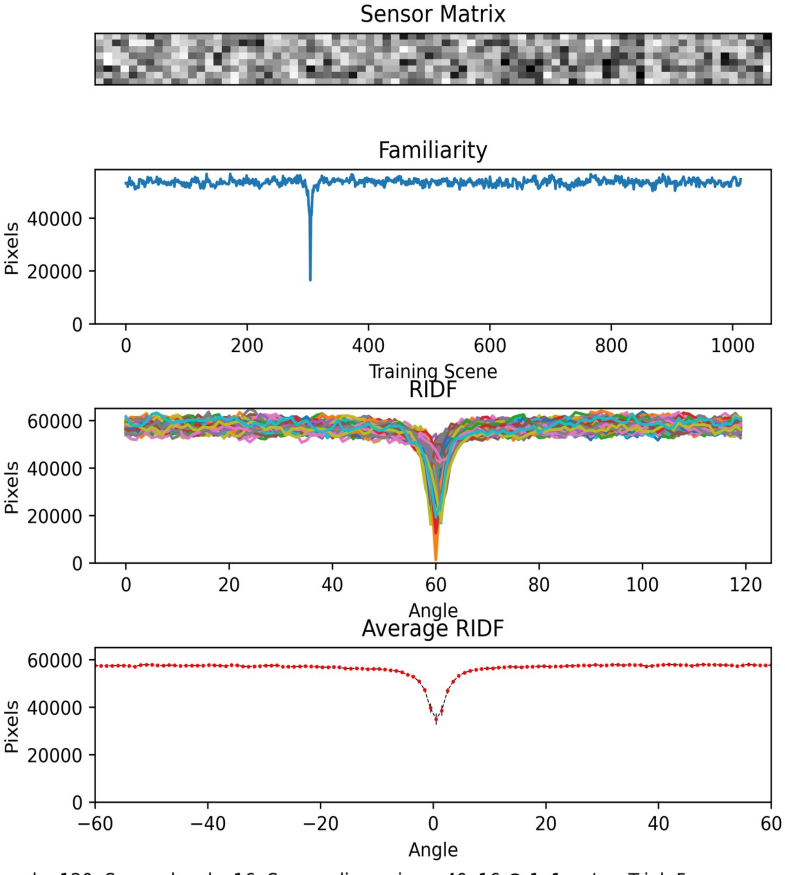


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 73.96; RMSD/dist: 0.185; TD: 11929; p90: 6; p50: 4; complete: 0

100%

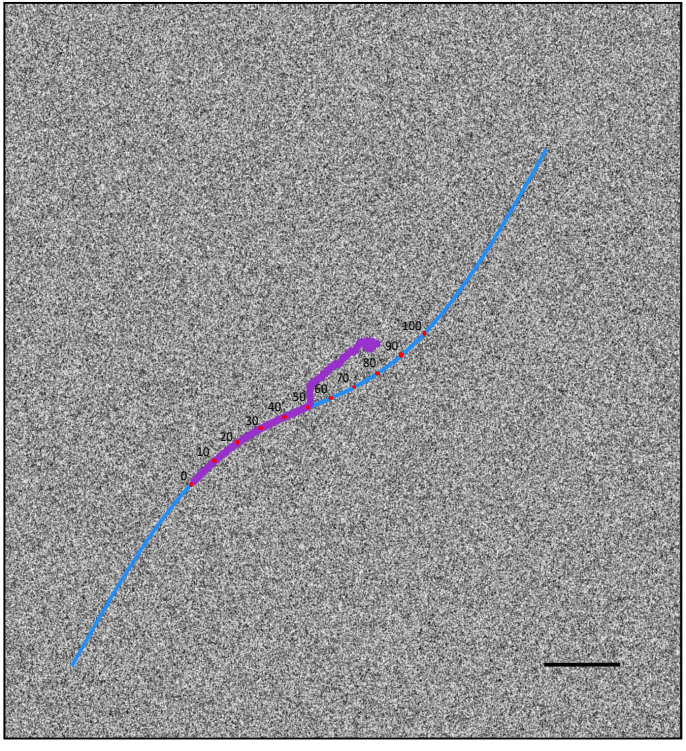


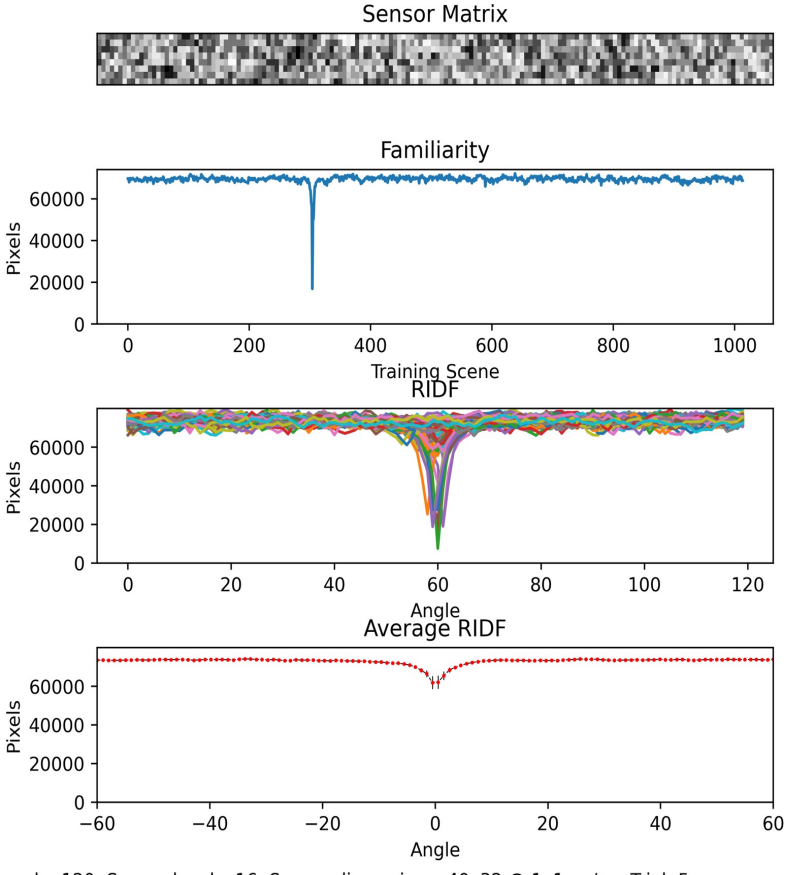


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 53.82; RMSD/dist: 0.135; TD: 18680; p90: 6; p50: 4; complete: 0

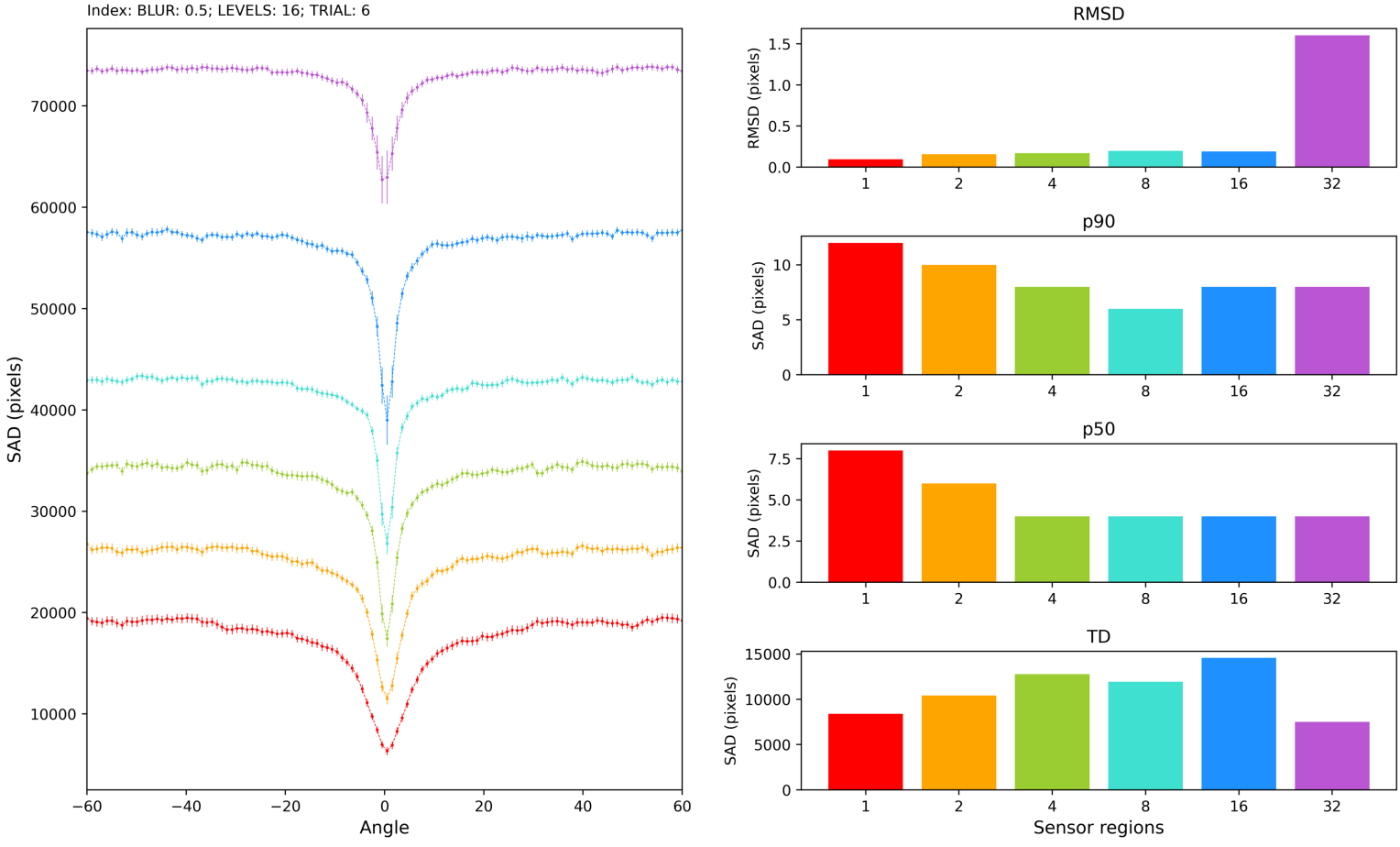
50%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1812.80; RMSD/dist: 4.532; TD: 8433; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 16; TRIAL: 6
SAD (pixels)
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60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
1.5
1.0
0.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
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0.0
TD
SAD (pixels)
15000
10000
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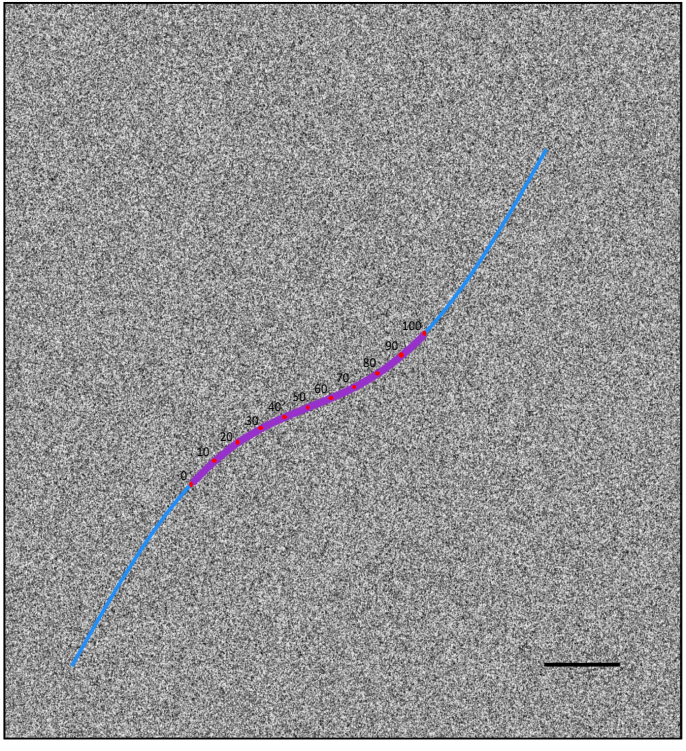
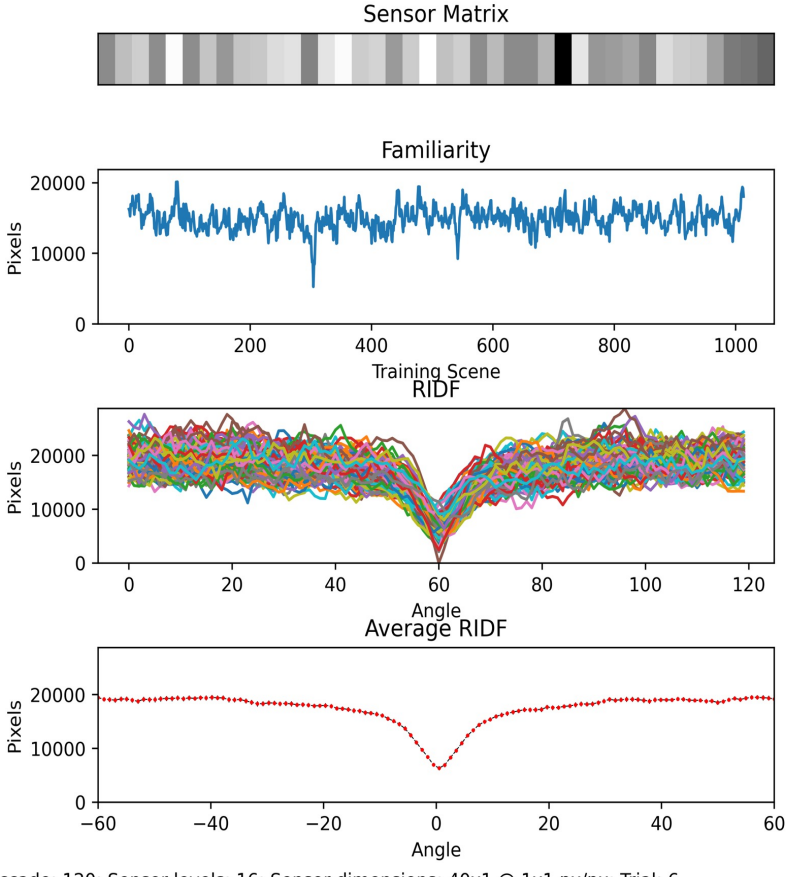
0
Sensor regions

100%

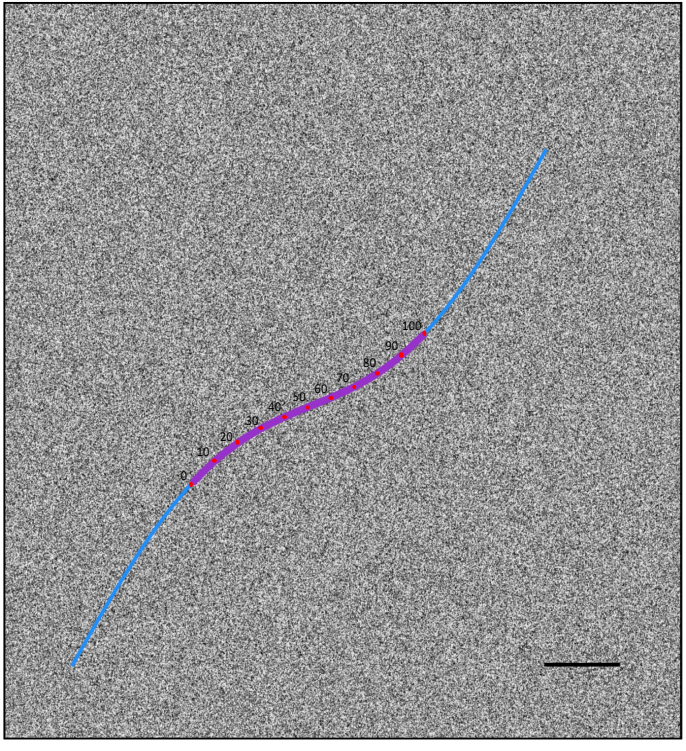


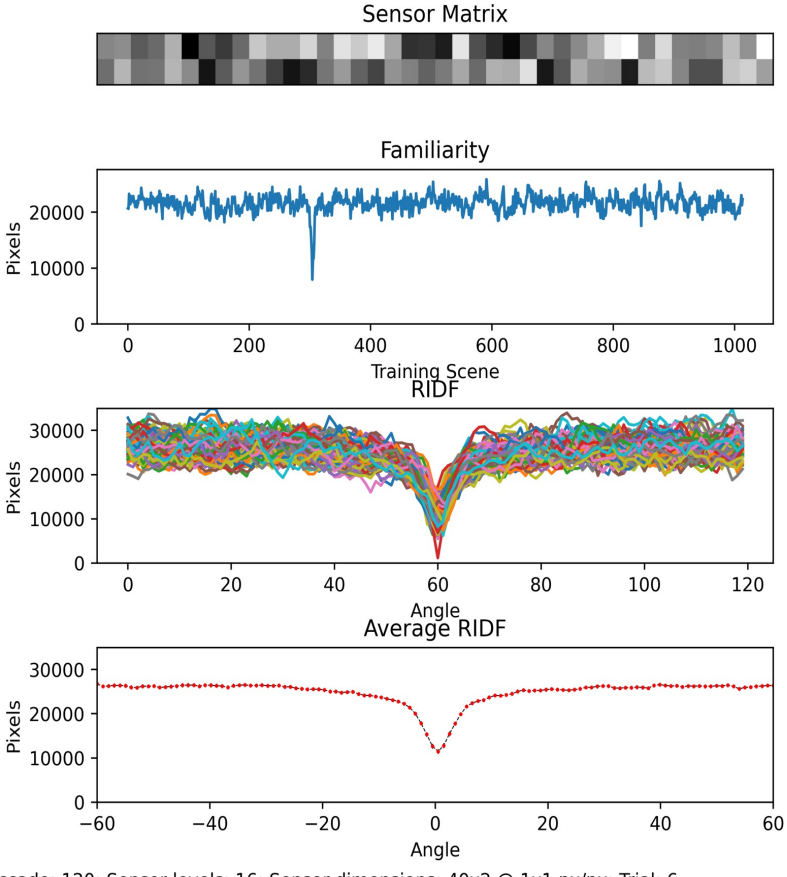


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 37.55; RMSD/dist: 0.094; TD: 8379; p90: 12; p50: 8; complete: 0

100%

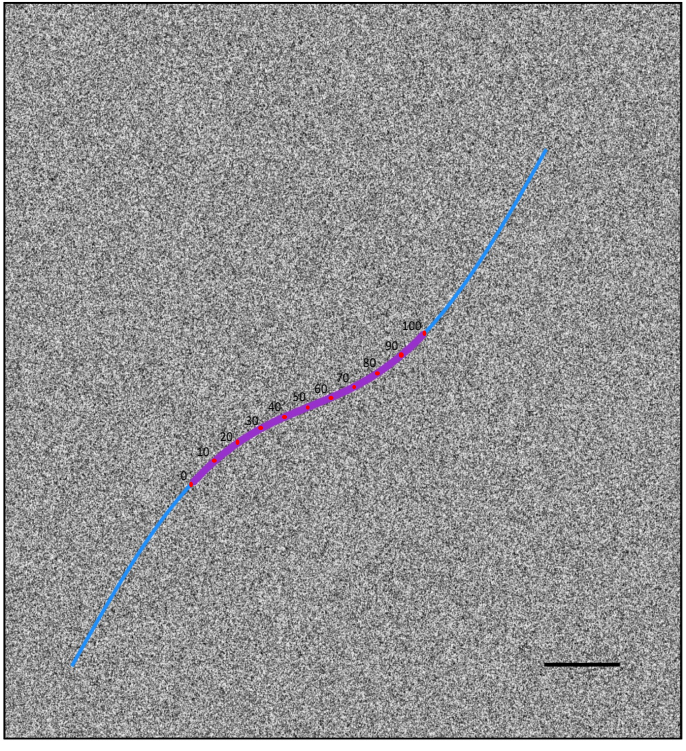


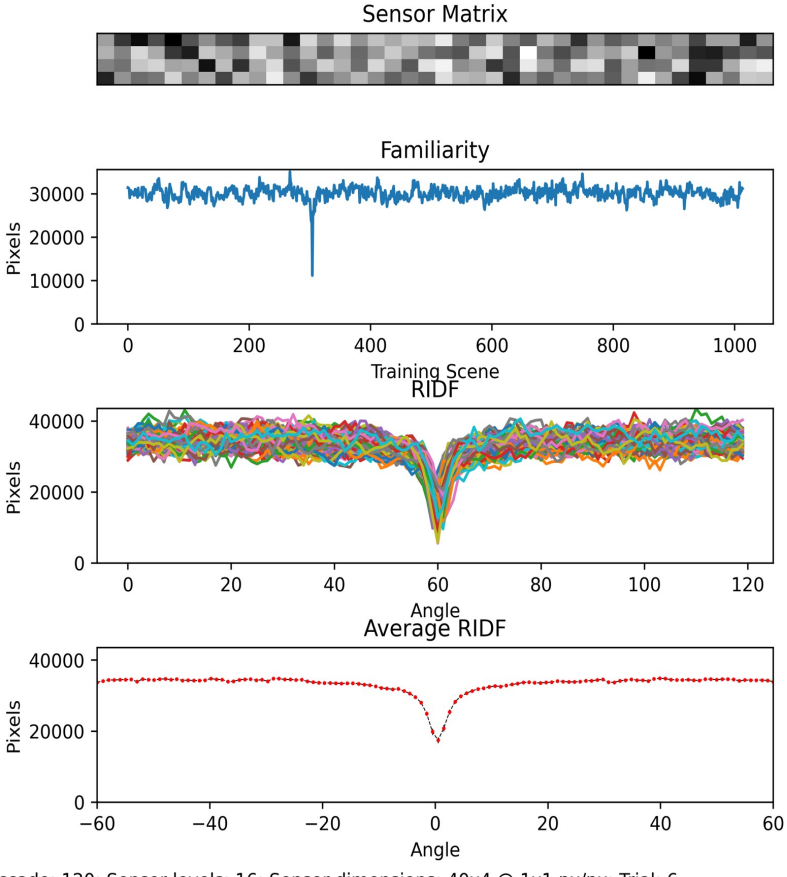


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 62.52; RMSD/dist: 0.156; TD: 10422; p90: 10; p50: 6; complete: 0

100%

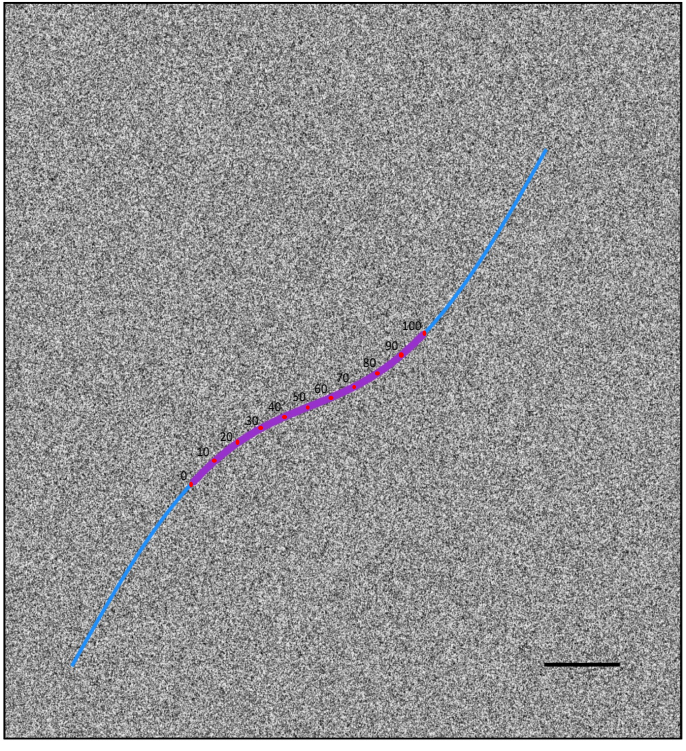


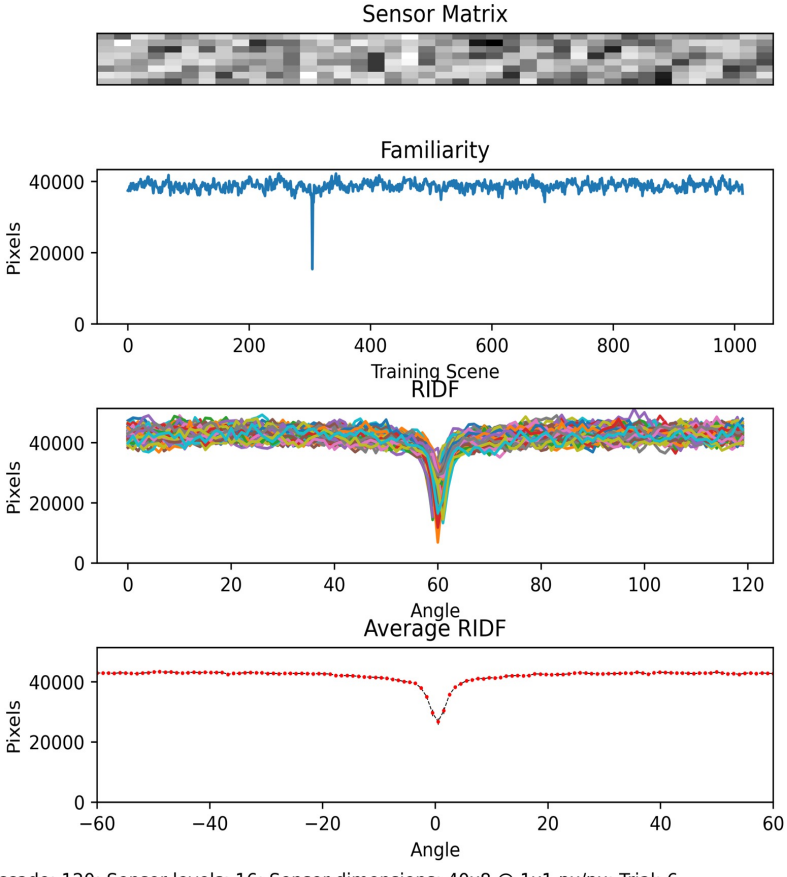


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 67.66; RMSD/dist: 0.169; TD: 12771; p90: 8; p50: 4; complete: 0

100%

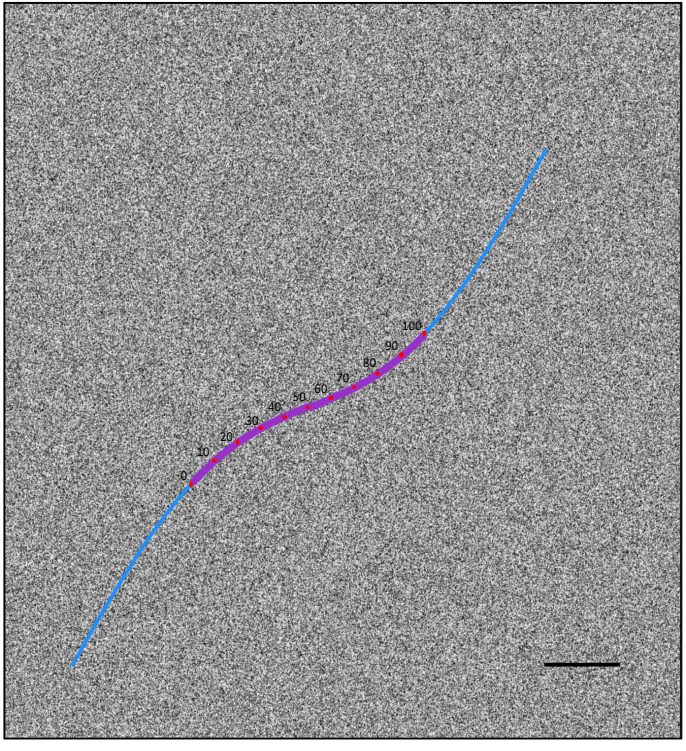


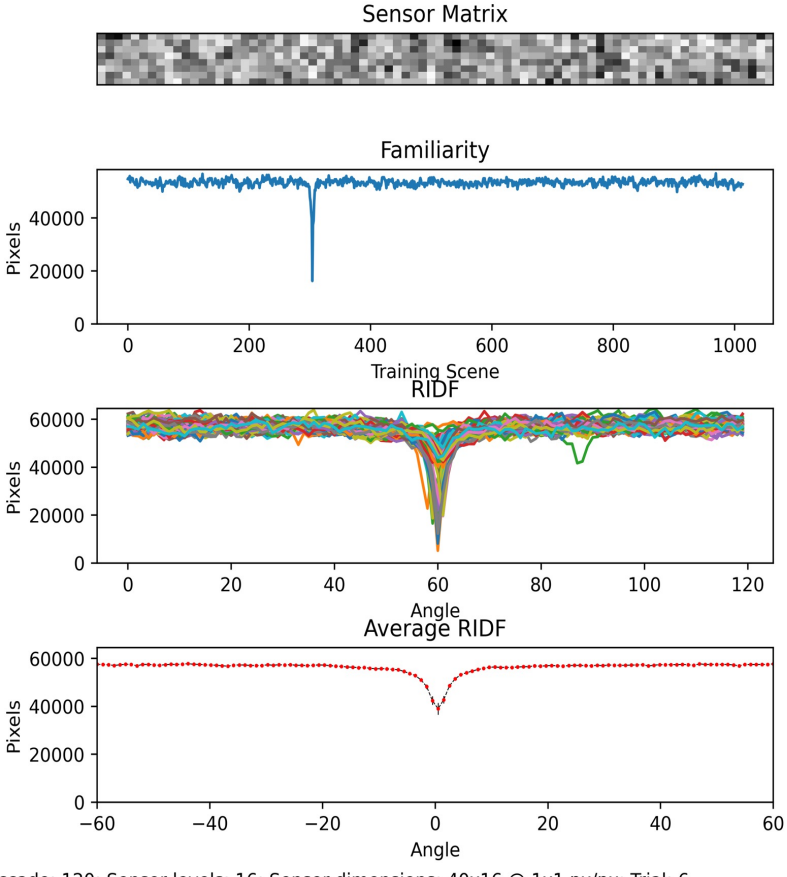


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 78.88; RMSD/dist: 0.197; TD: 11938; p90: 6; p50: 4; complete: 0

100%

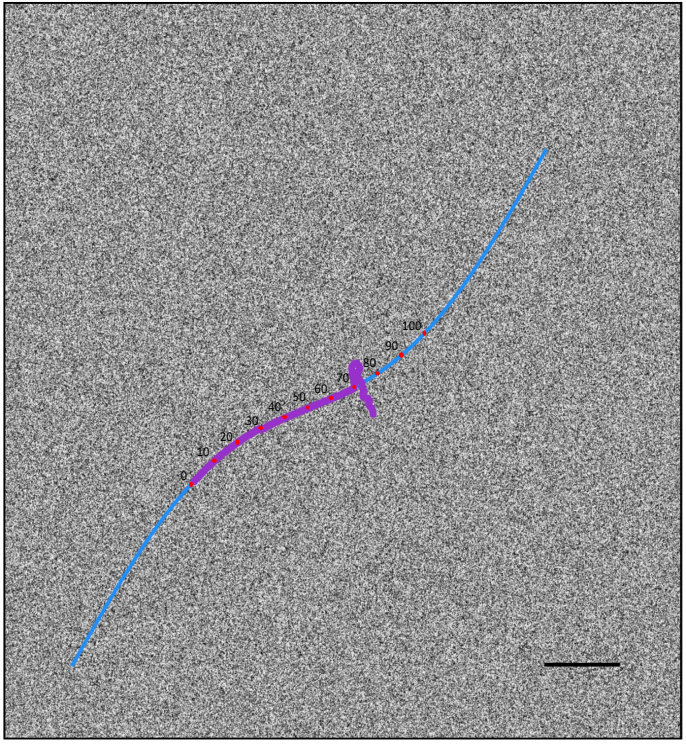


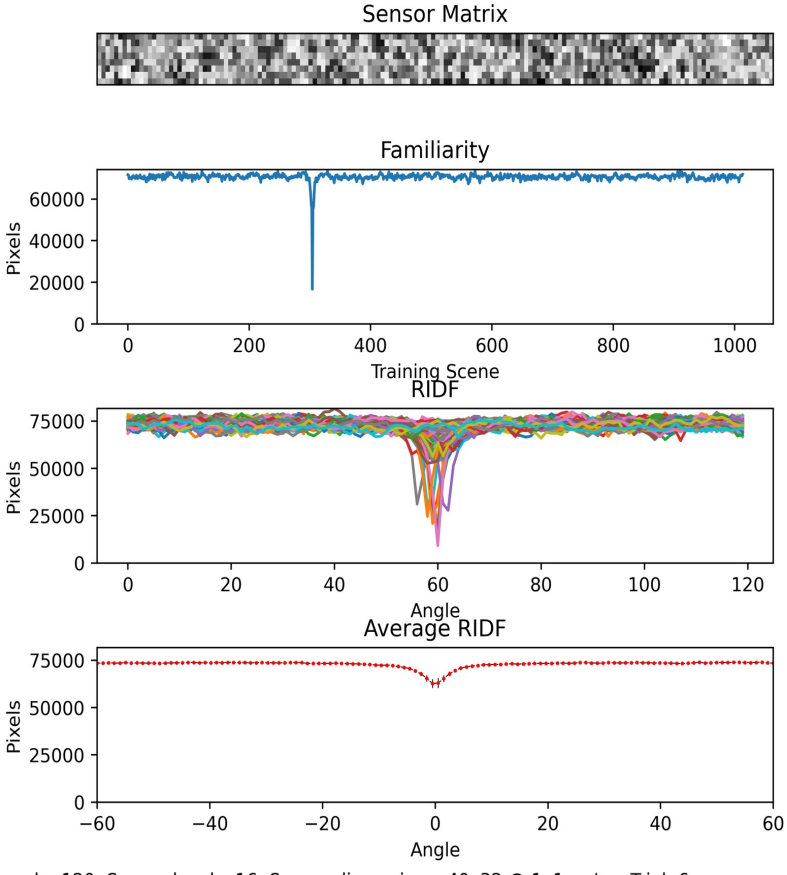


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 75.94; RMSD/dist: 0.190; TD: 14558; p90: 8; p50: 4; complete: 0

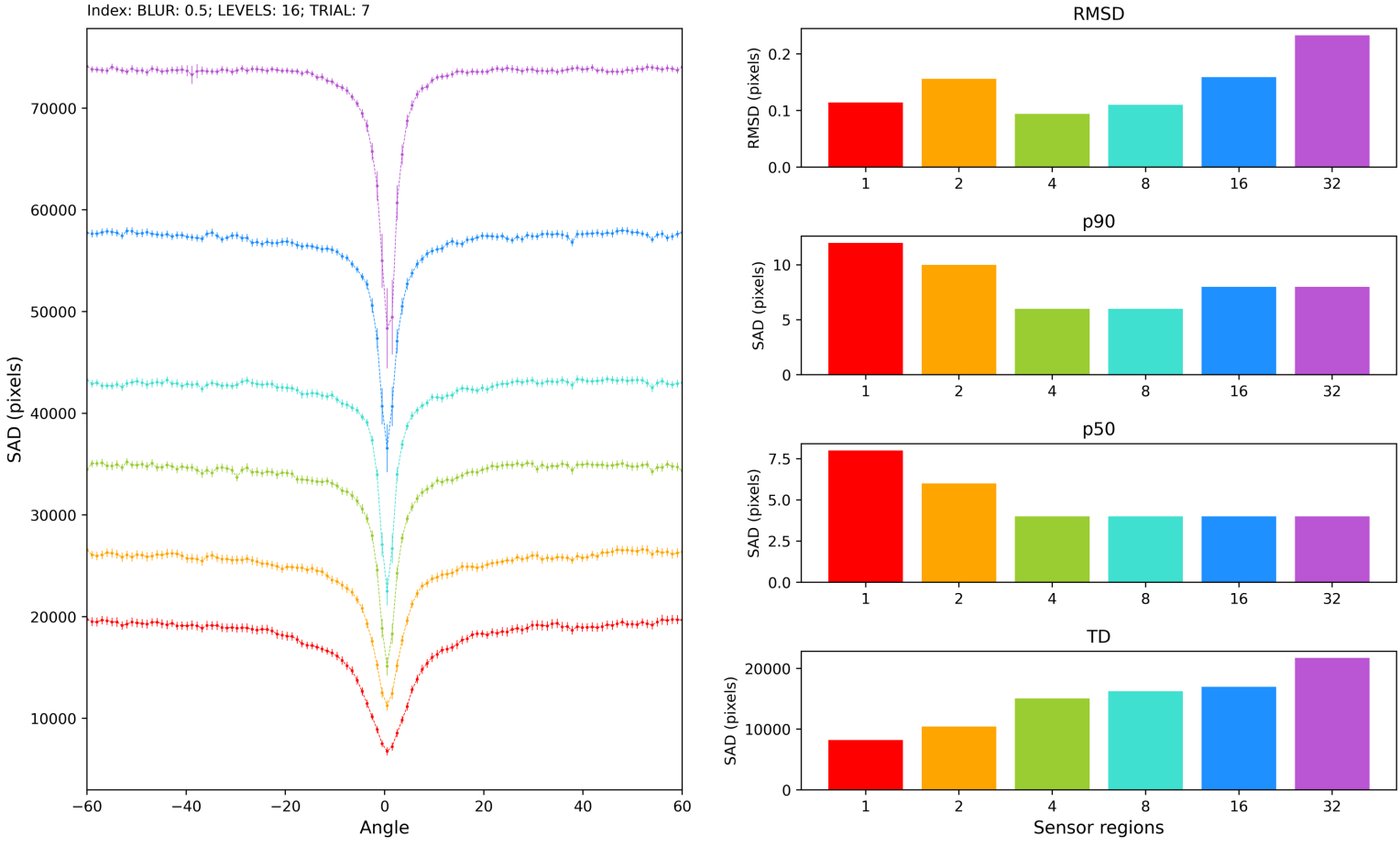
70%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 642.16; RMSD/dist: 1.605; TD: 7495; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 16; TRIAL: 7
SAD (pixels)
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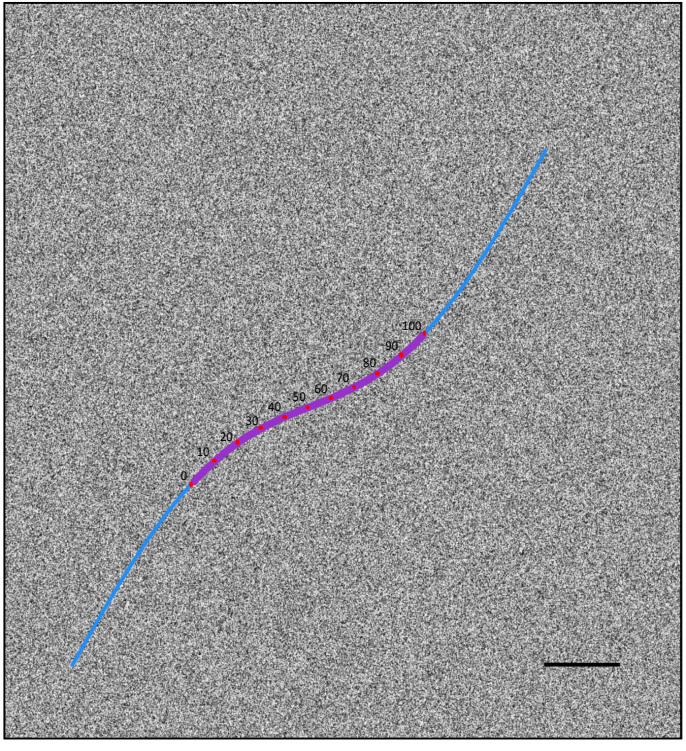
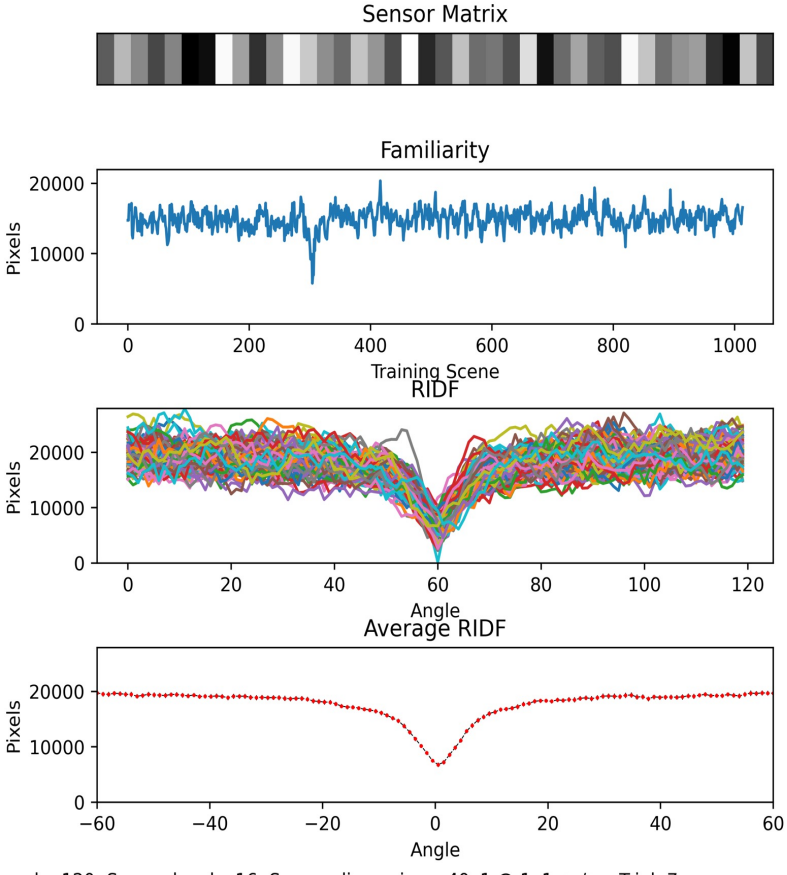
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

100%

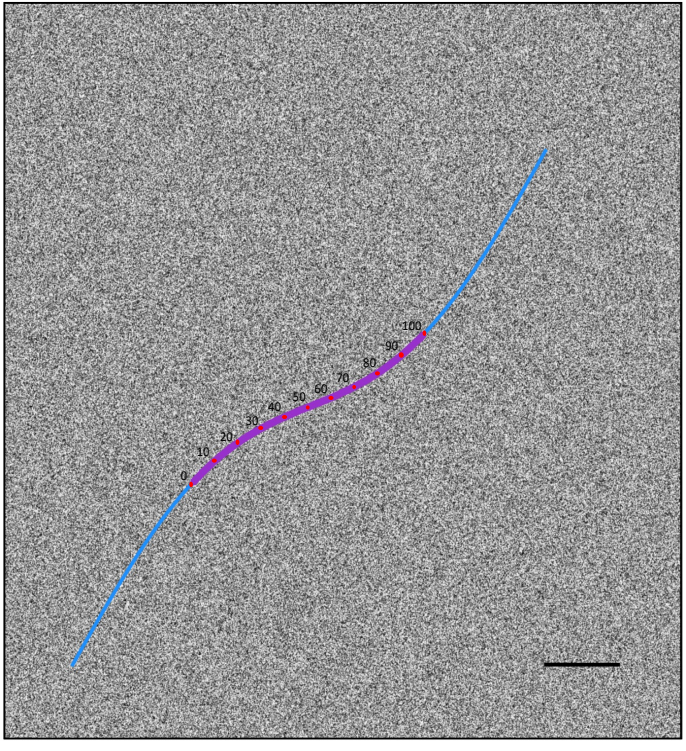


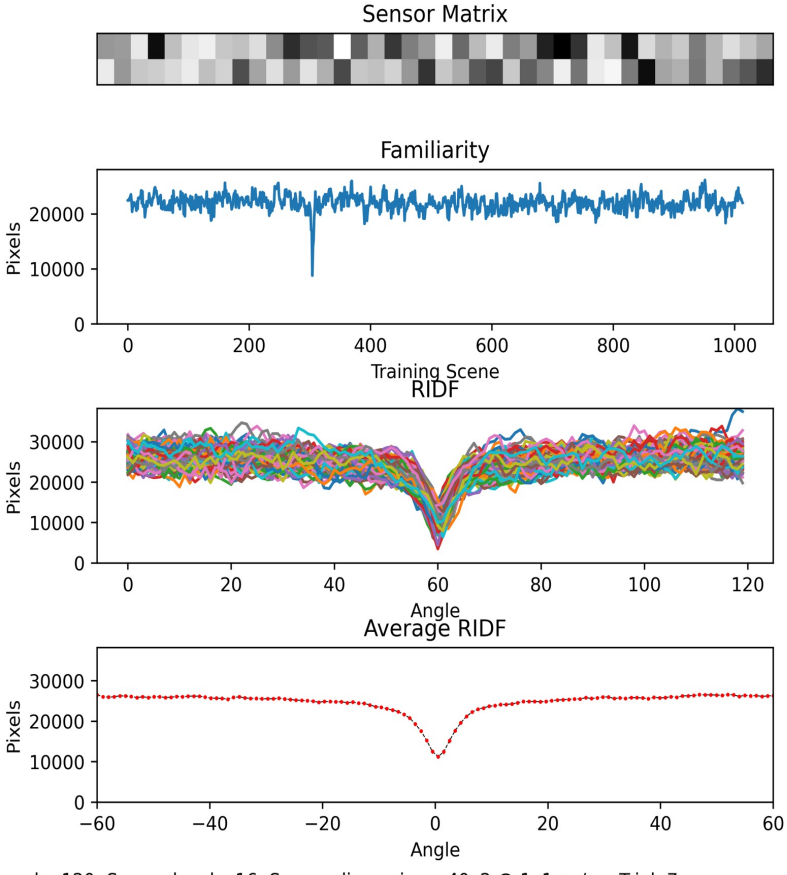


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 45.77; RMSD/dist: 0.114; TD: 8221; p90: 12; p50: 8; complete: 0

100%

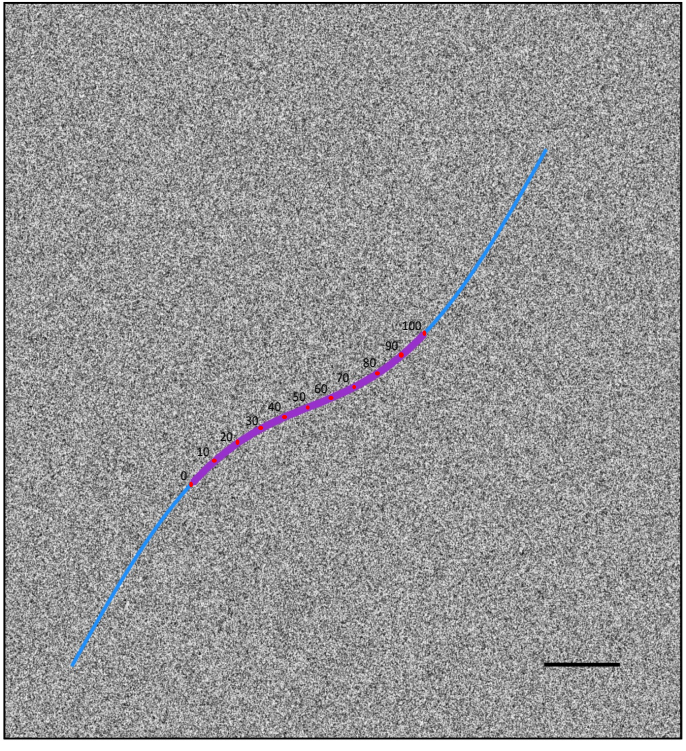


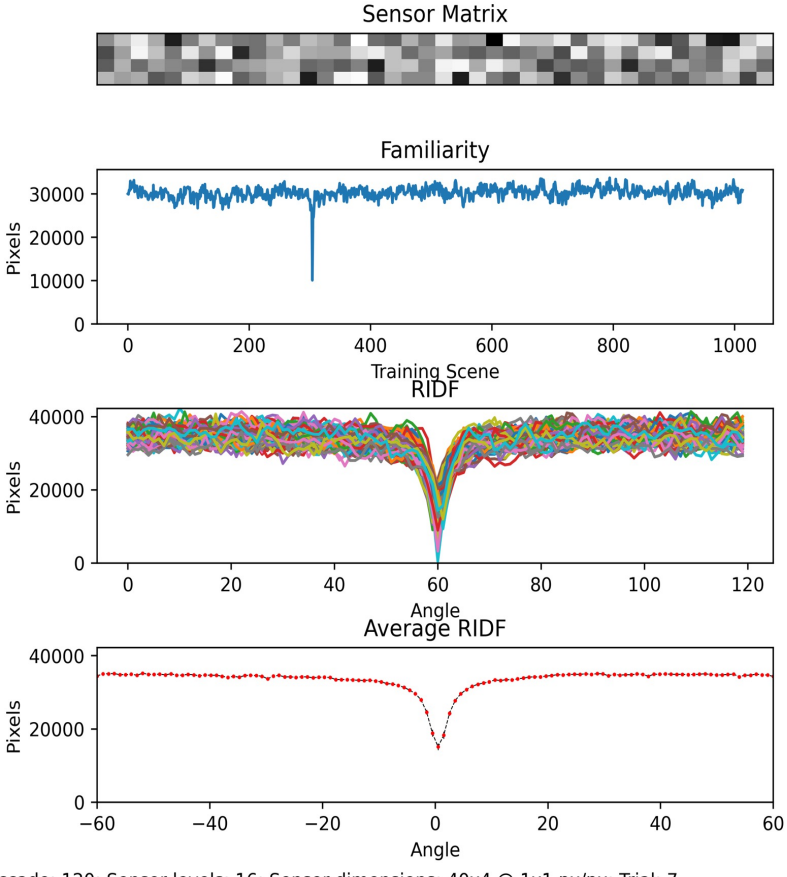


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 62.24; RMSD/dist: 0.156; TD: 10425; p90: 10; p50: 6; complete: 0

100%

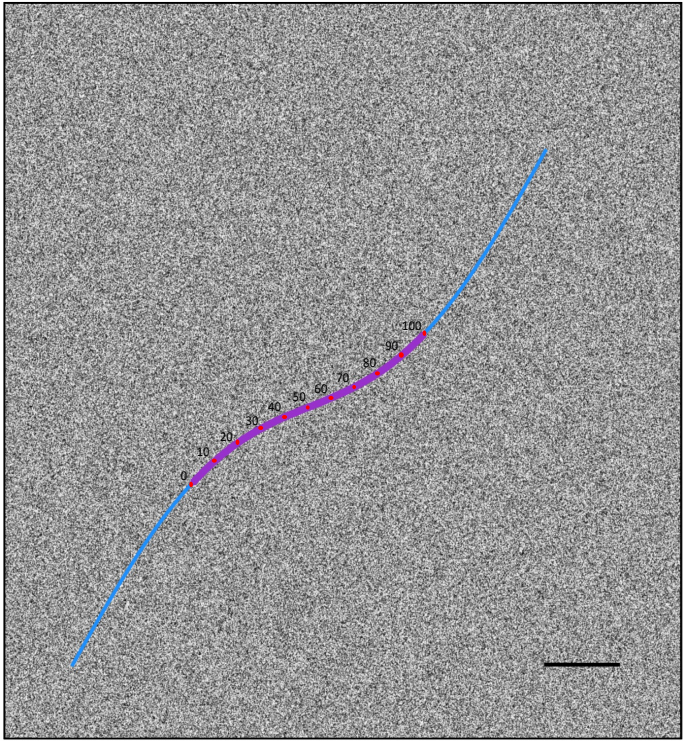


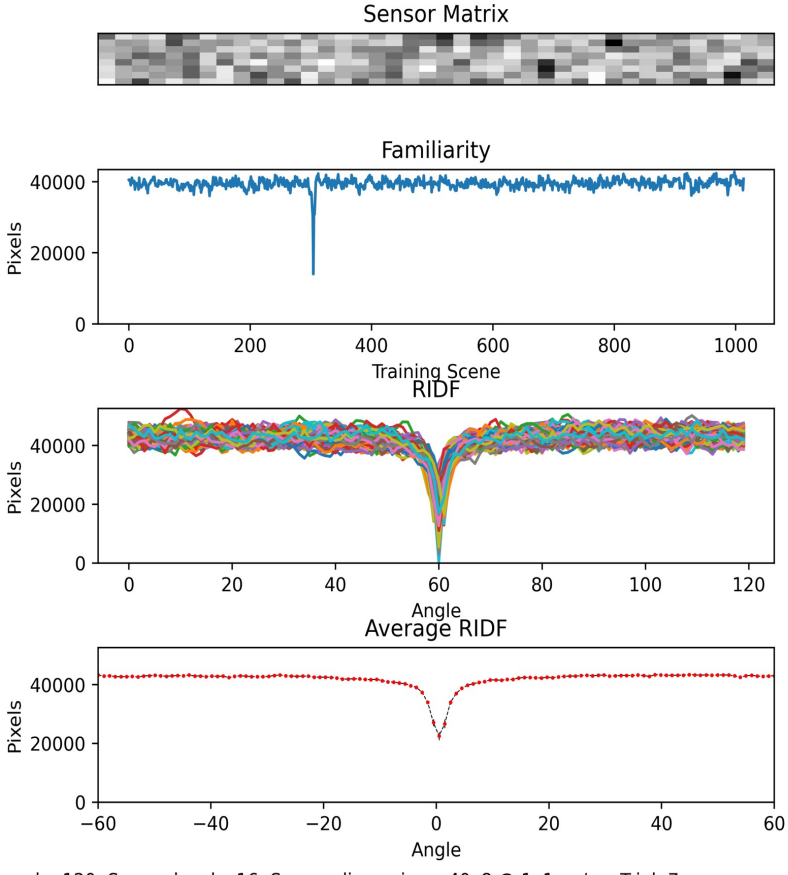


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 37.71; RMSD/dist: 0.094; TD: 15069; p90: 6; p50: 4; complete: 0

100%

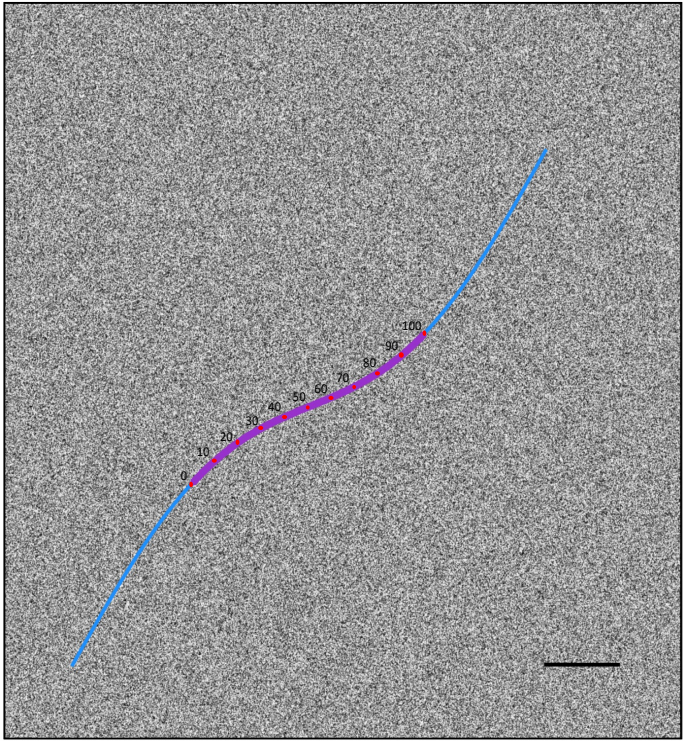


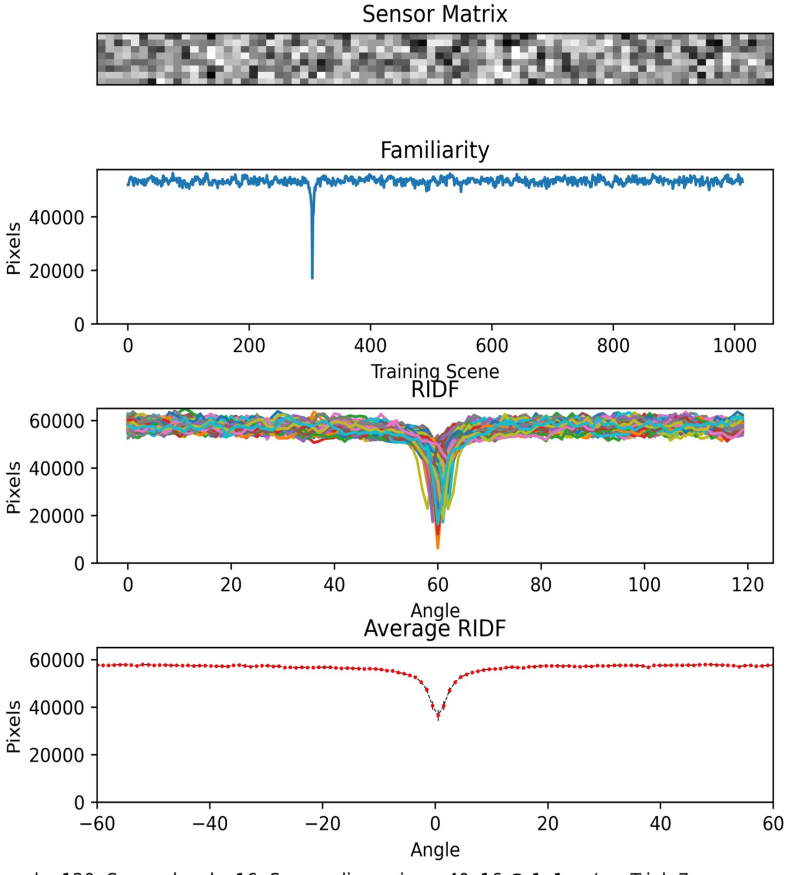


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 43.84; RMSD/dist: 0.110; TD: 16235; p90: 6; p50: 4; complete: 0

100%

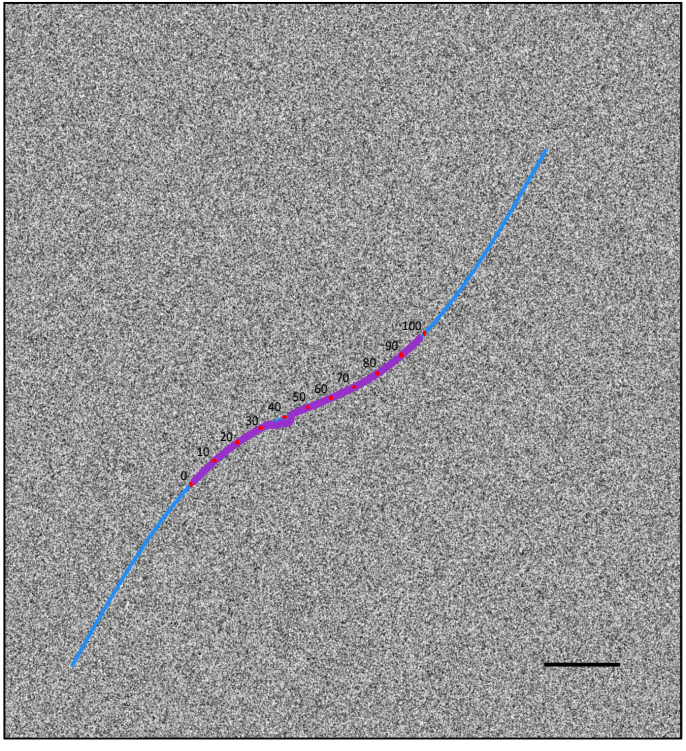


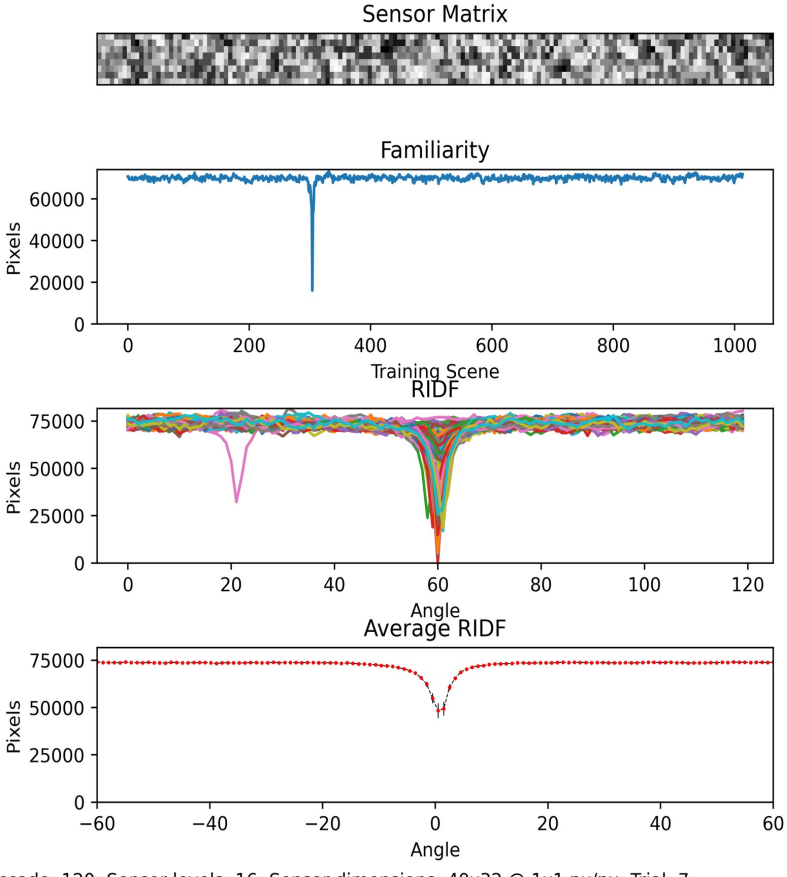


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 63.70; RMSD/dist: 0.159; TD: 16972; p90: 8; p50: 4; complete: 0

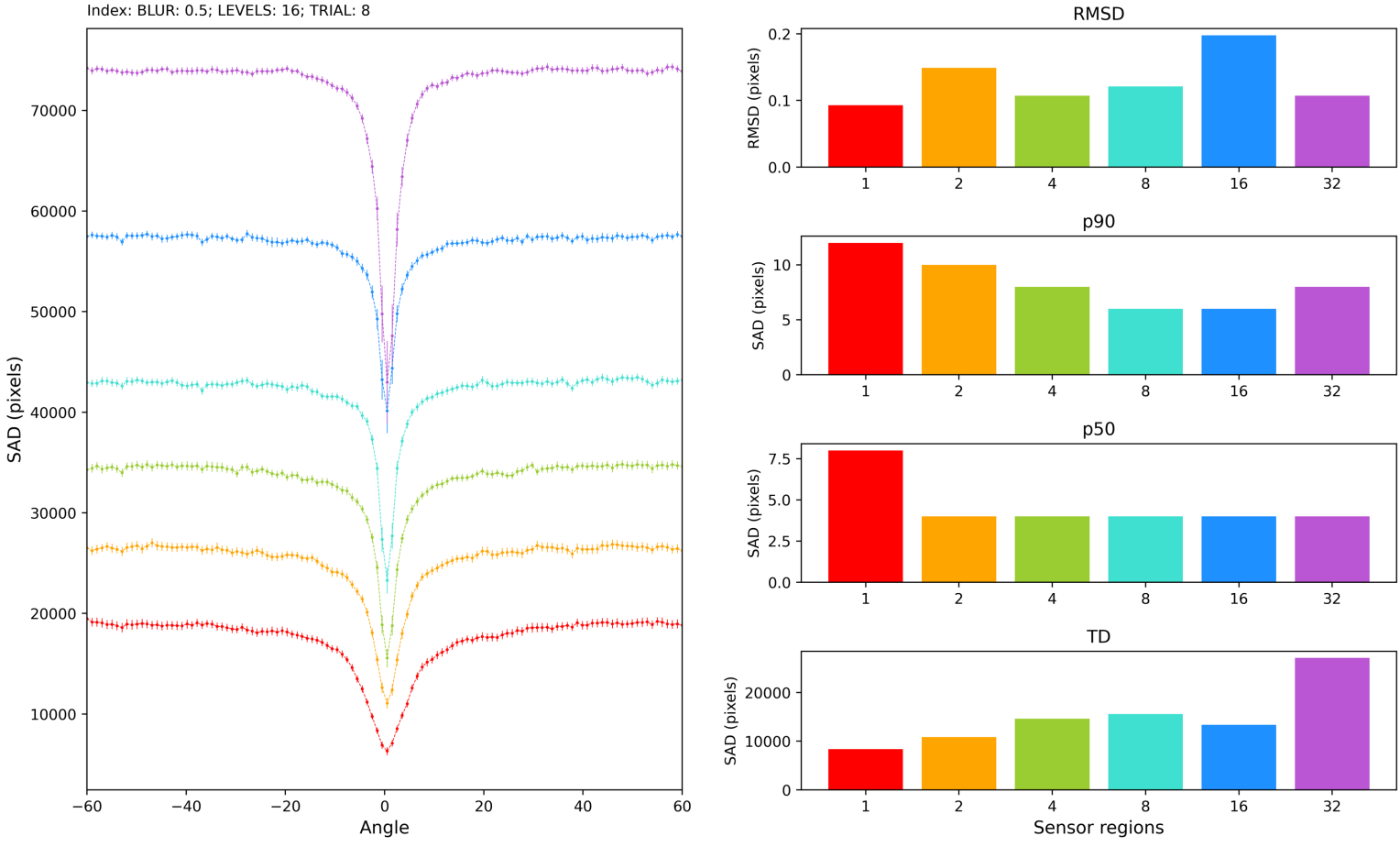
90%



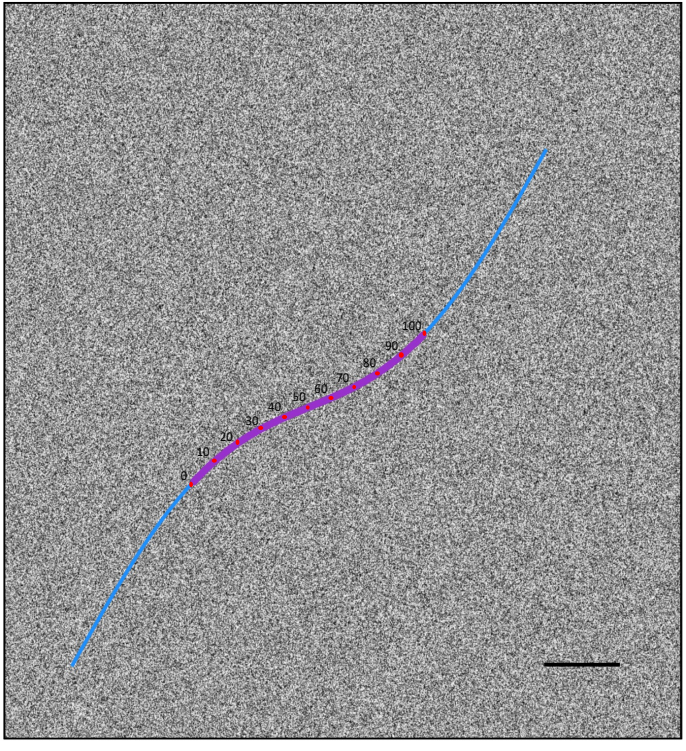


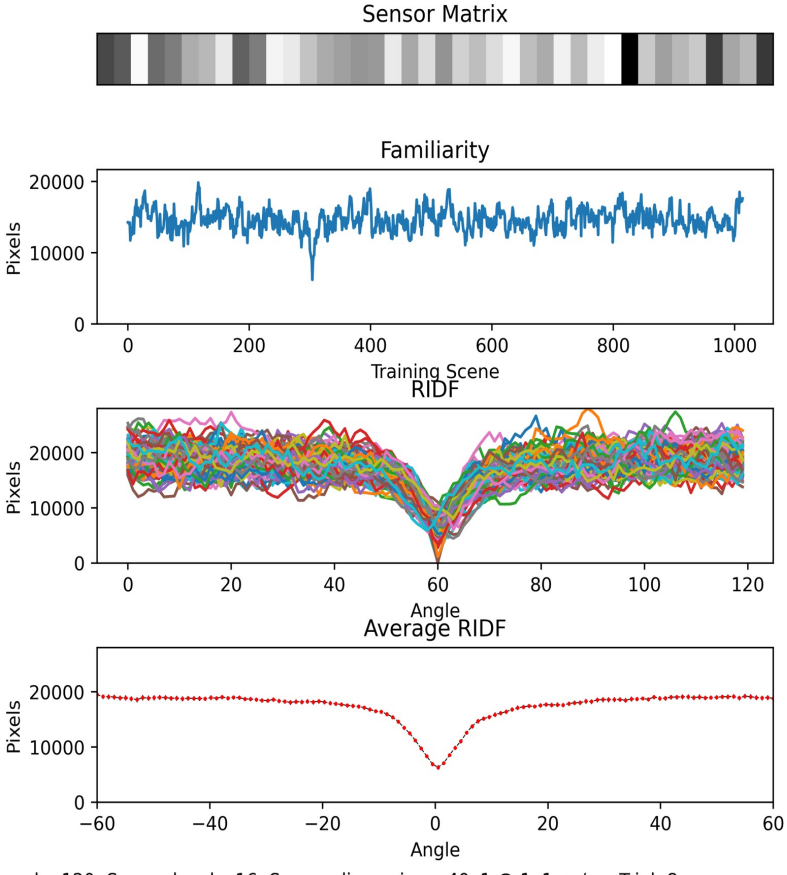
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 93.12; RMSD/dist: 0.233; TD: 21732; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 16; TRIAL: 8
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

100%

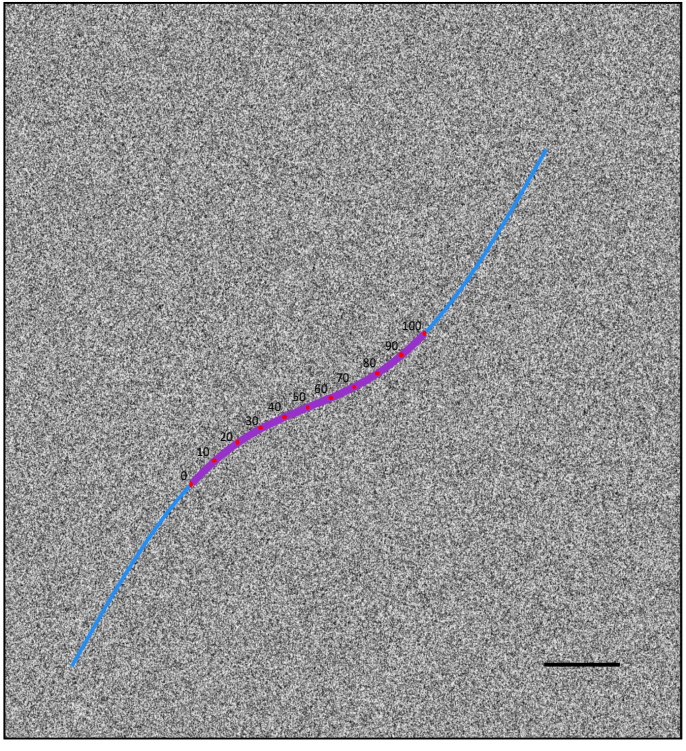


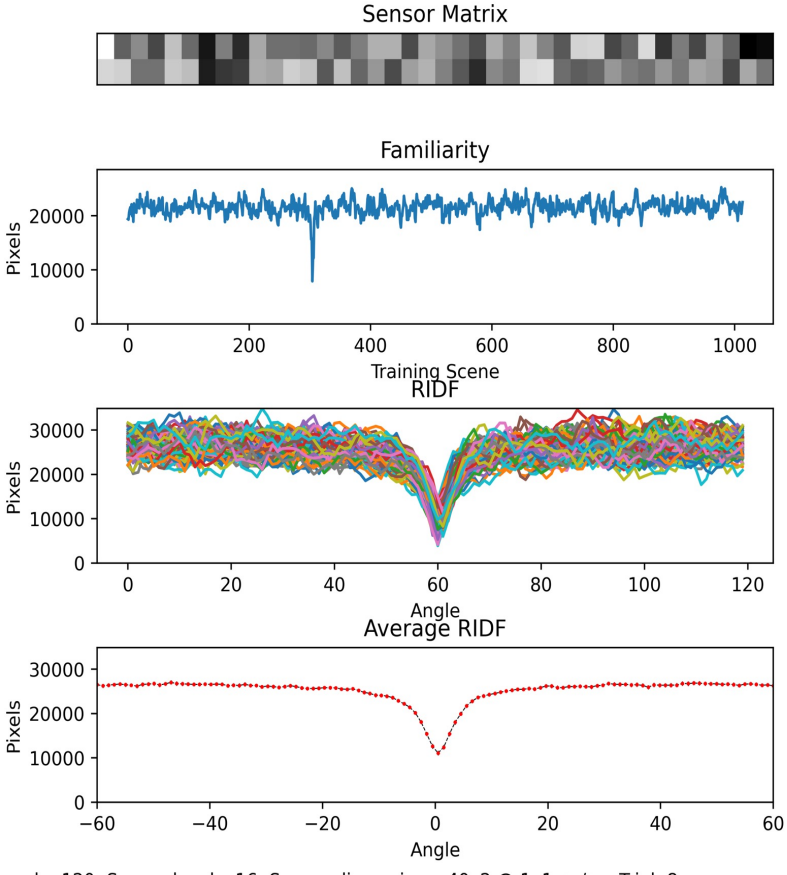


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 37.12; RMSD/dist: 0.093; TD: 8383; p90: 12; p50: 8; complete: 0

100%

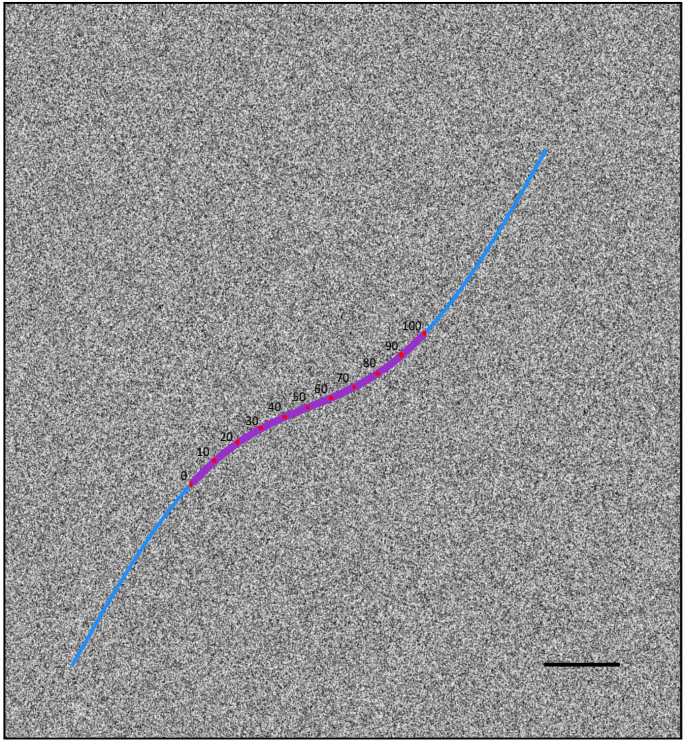


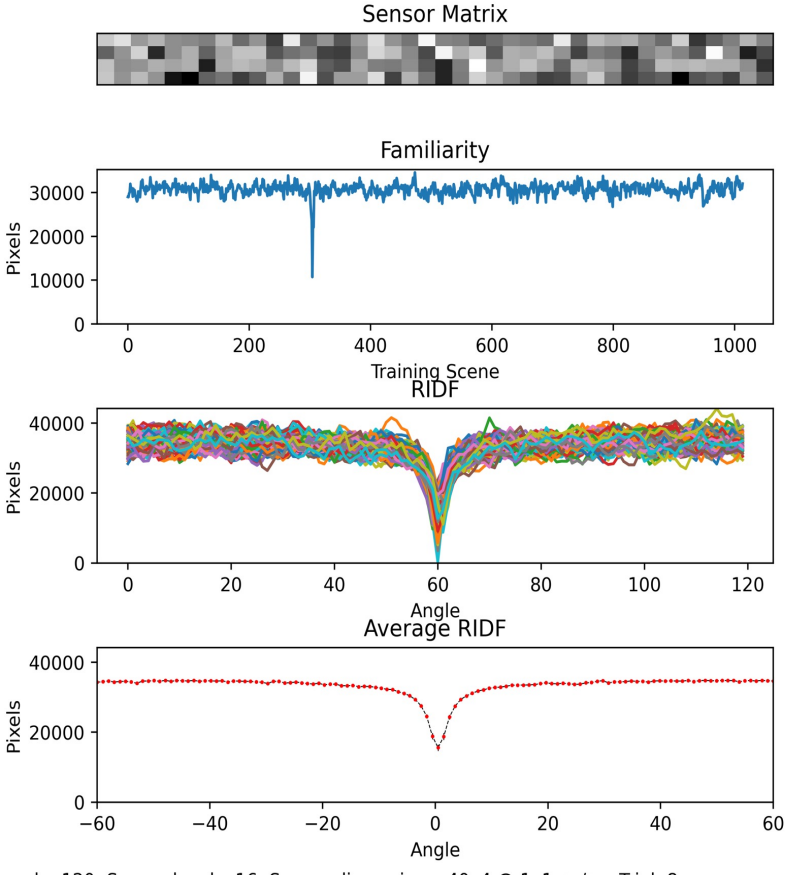


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 59.70; RMSD/dist: 0.149; TD: 10848; p90: 10; p50: 4; complete: 0

100%

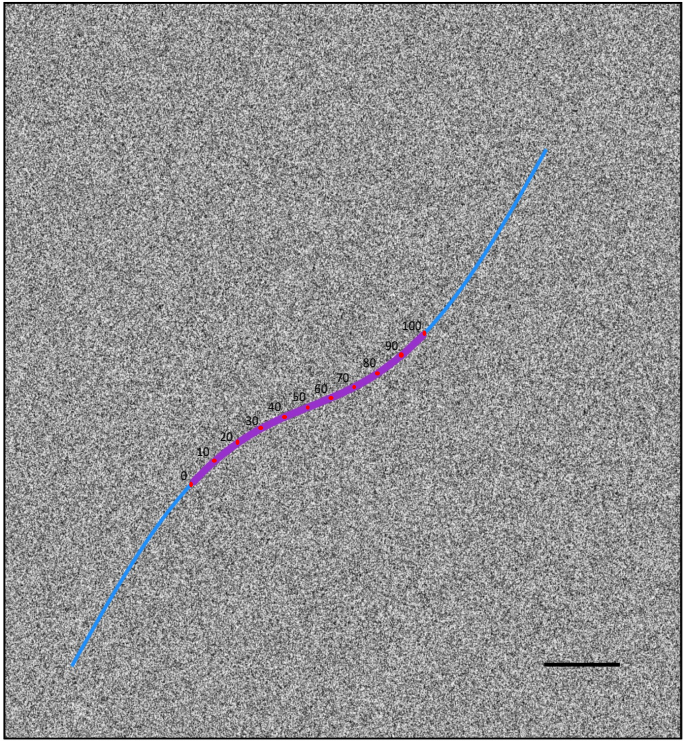


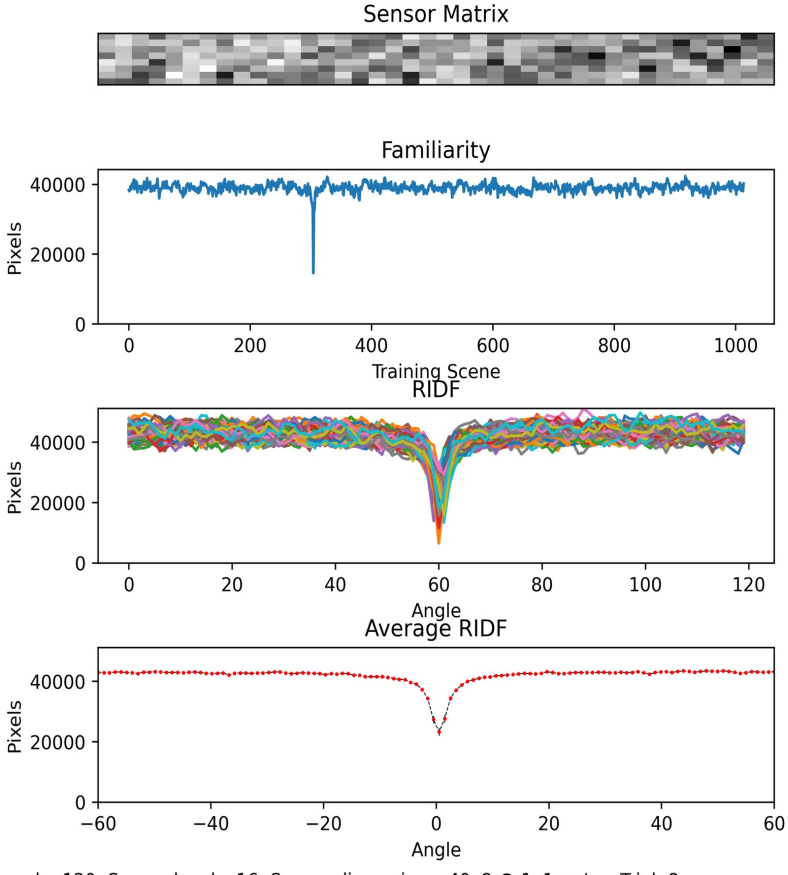


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 42.99; RMSD/dist: 0.107; TD: 14624; p90: 8; p50: 4; complete: 0

100%

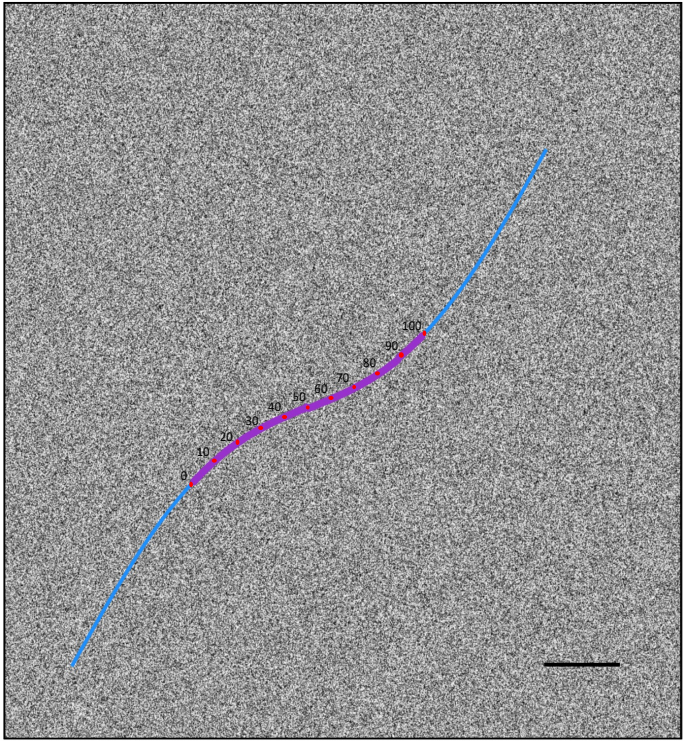


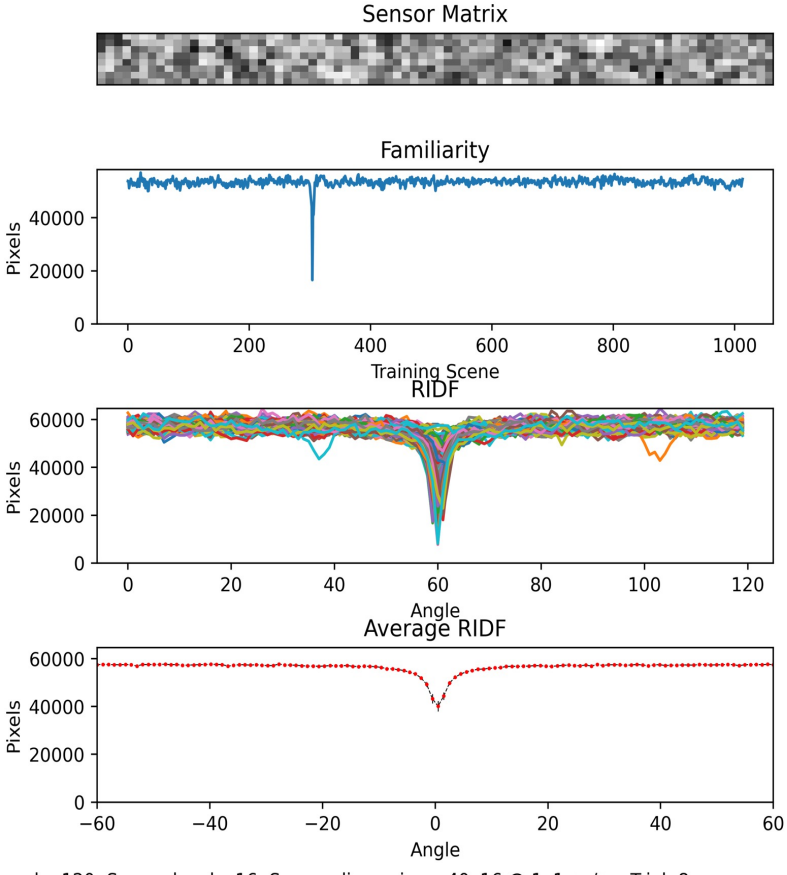


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 48.42; RMSD/dist: 0.121; TD: 15554; p90: 6; p50: 4; complete: 0

100%

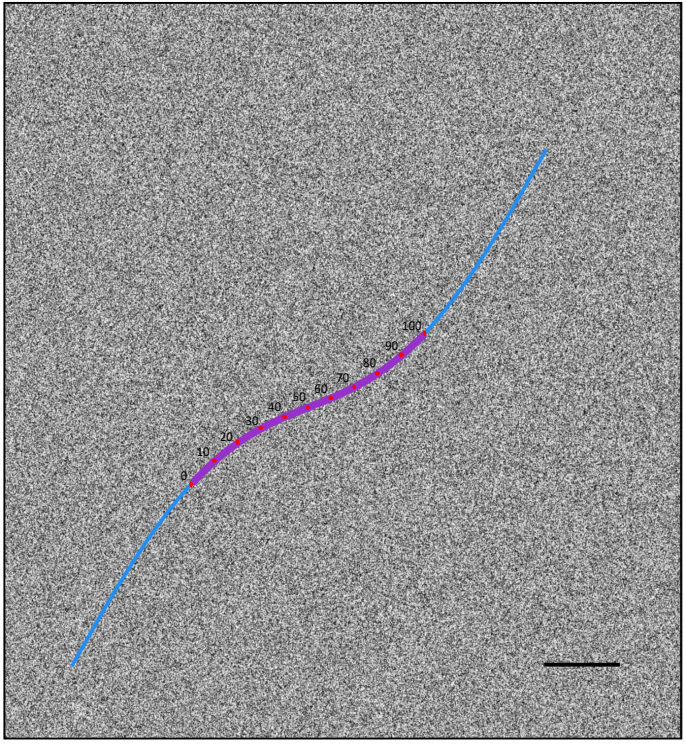


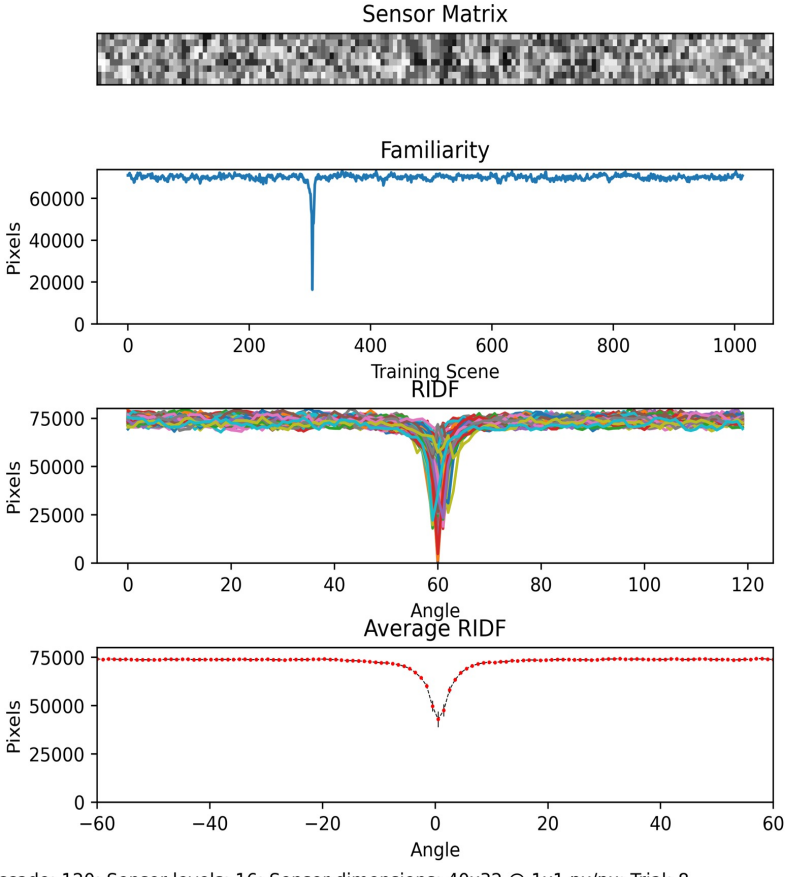


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 79.26; RMSD/dist: 0.198; TD: 13338; p90: 6; p50: 4; complete: 0

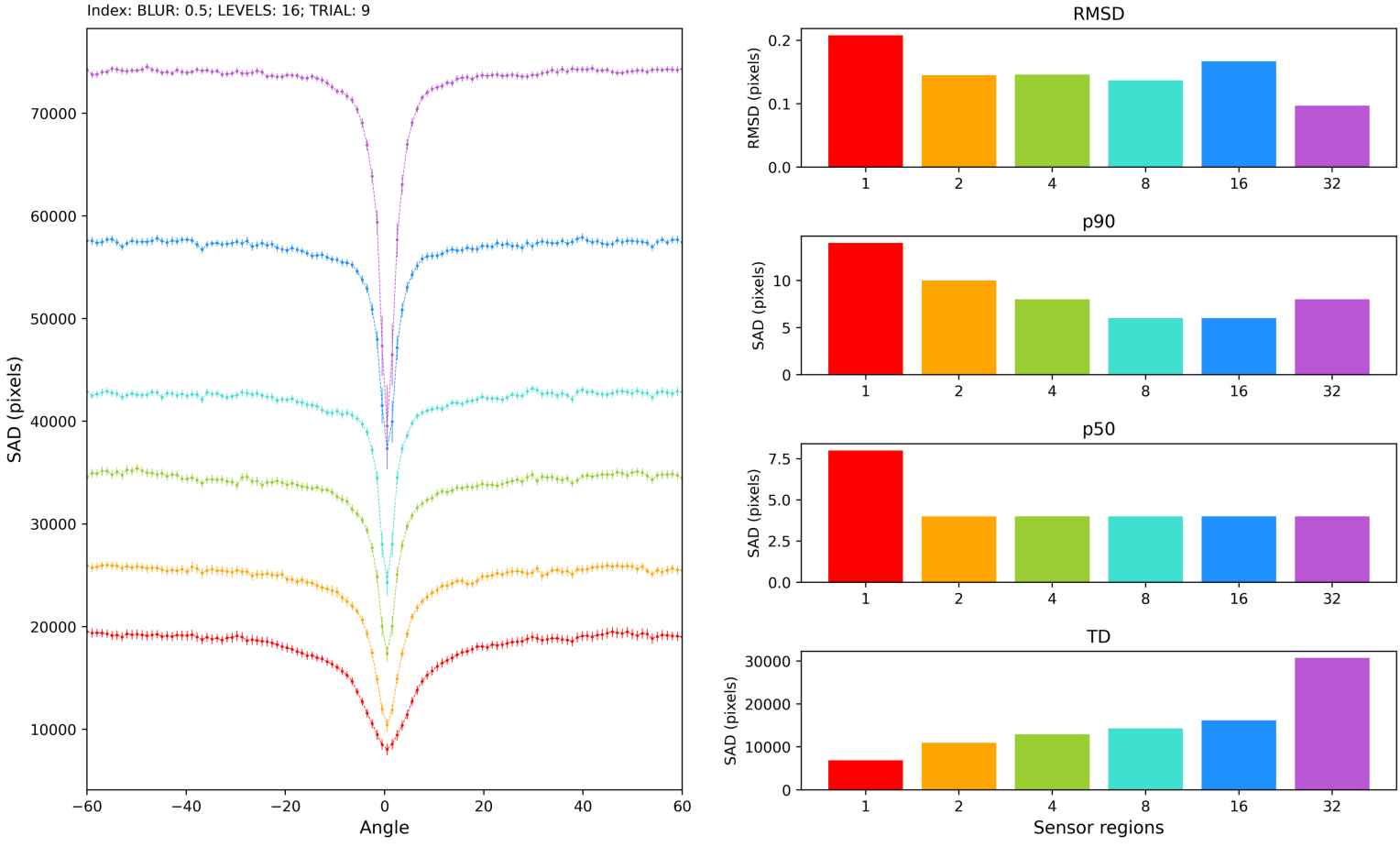
100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 42.95; RMSD/dist: 0.107; TD: 27104; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 16; TRIAL: 9
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
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SAD (pixels)
30000
20000
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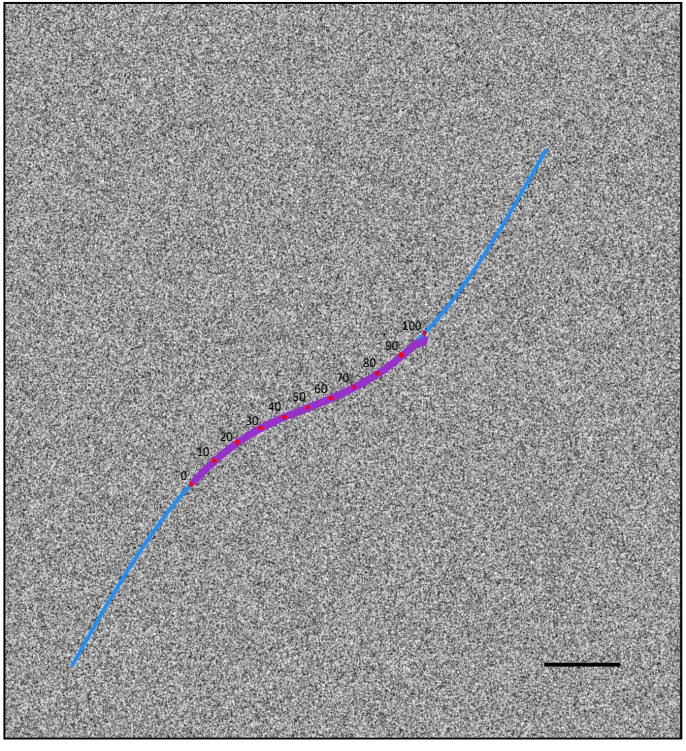
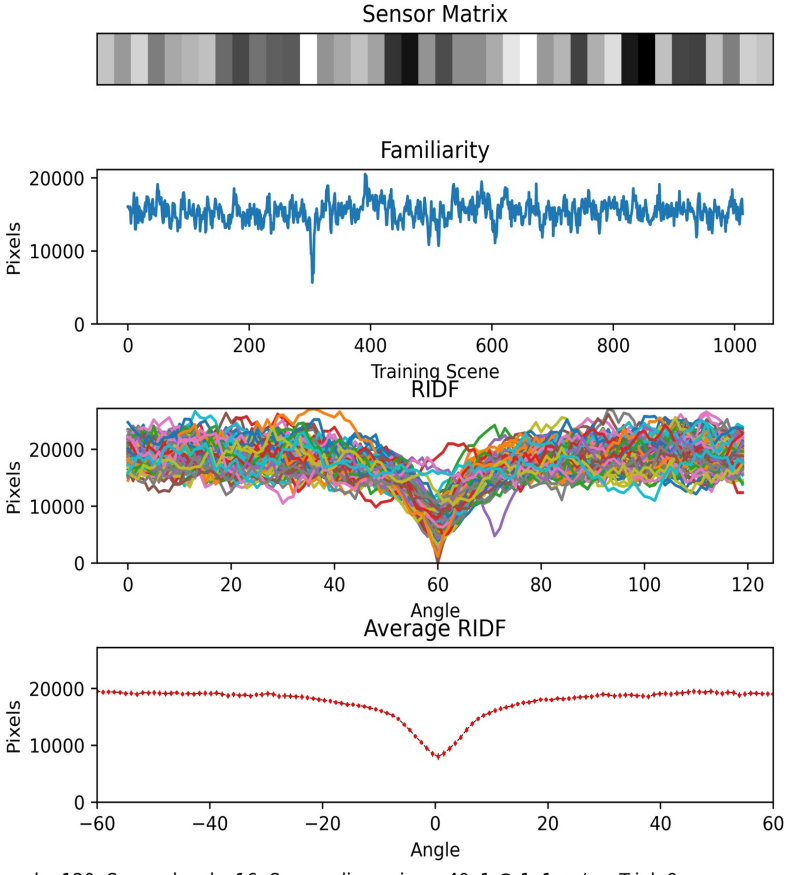
0
Sensor regions

90%

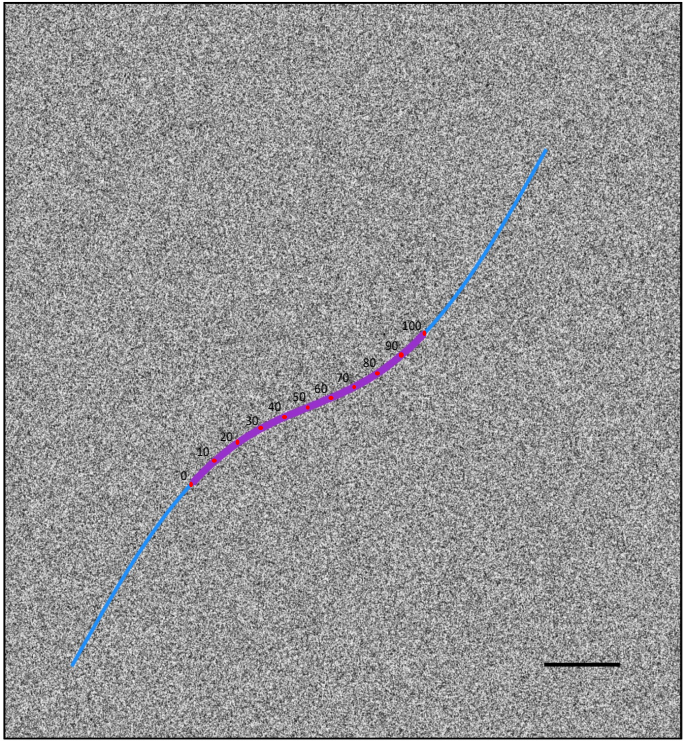


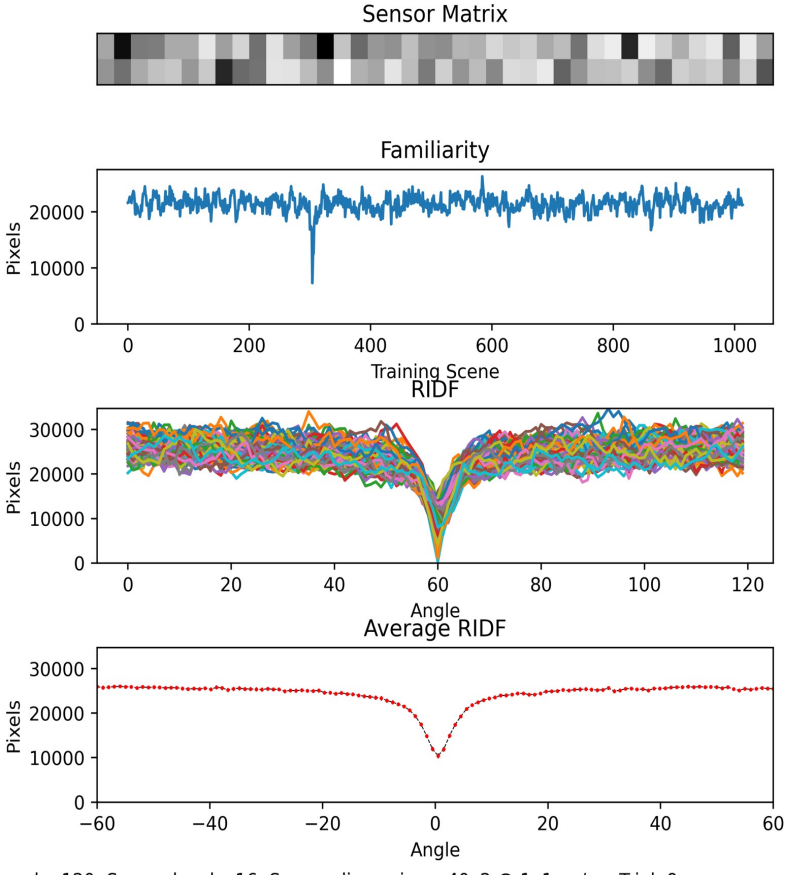


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 83.24; RMSD/dist: 0.208; TD: 6855; p90: 14; p50: 8; complete: 0

100%

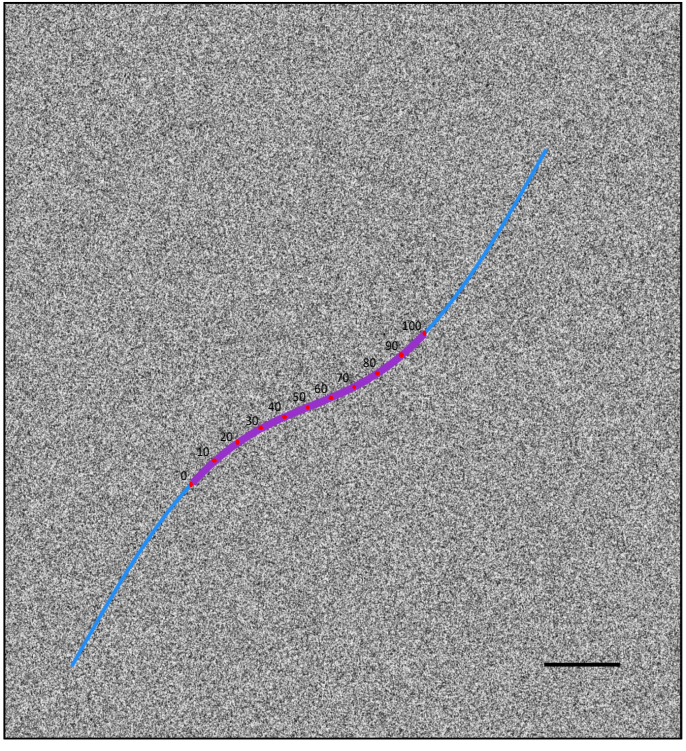


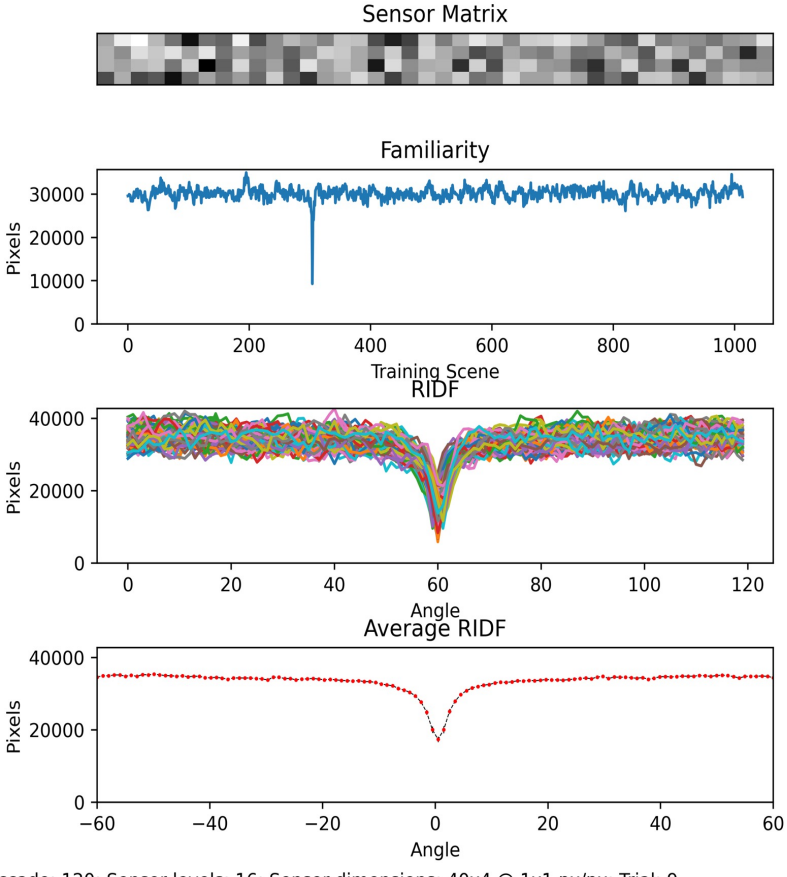


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 57.87; RMSD/dist: 0.145; TD: 10958; p90: 10; p50: 4; complete: 0

100%

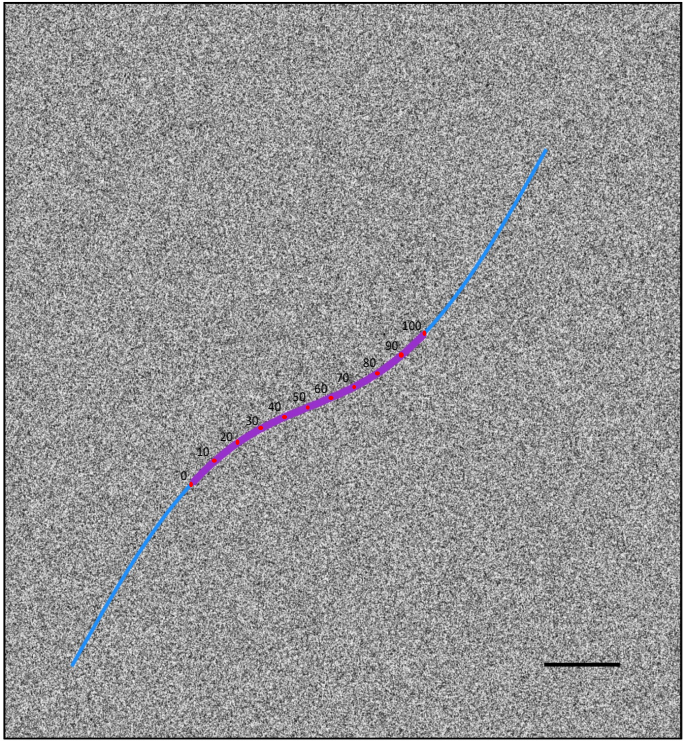


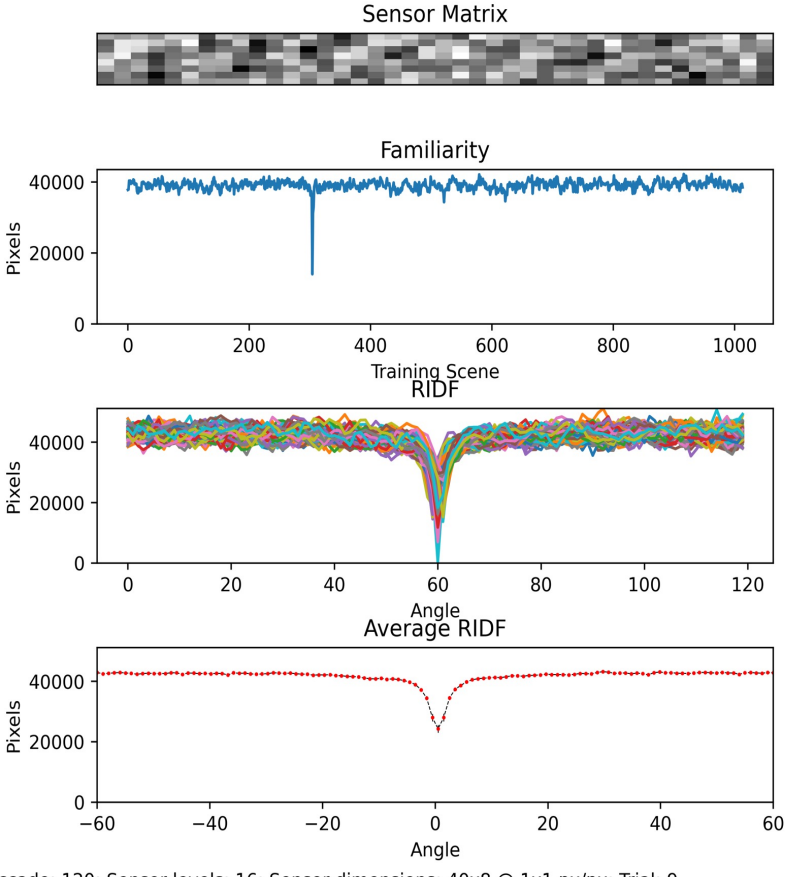


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 58.21; RMSD/dist: 0.146; TD: 12901; p90: 8; p50: 4; complete: 0

100%

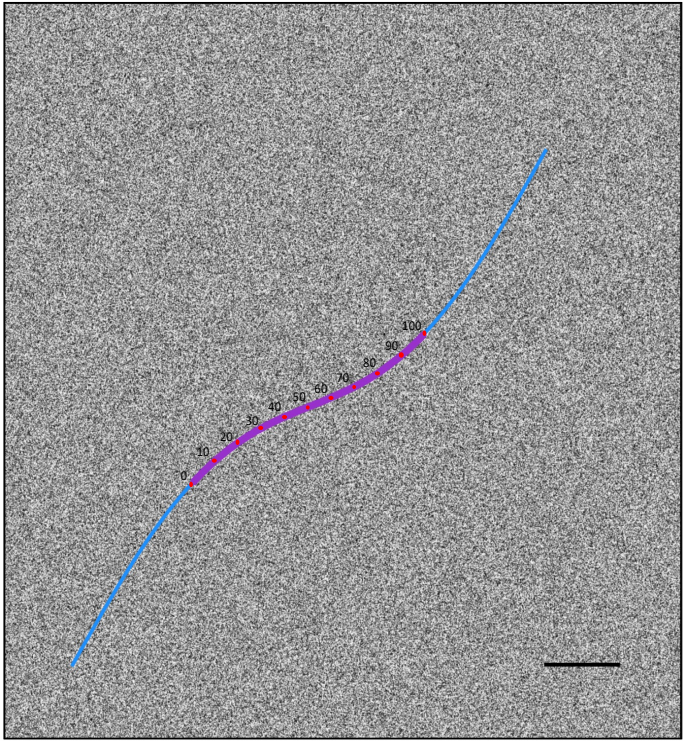


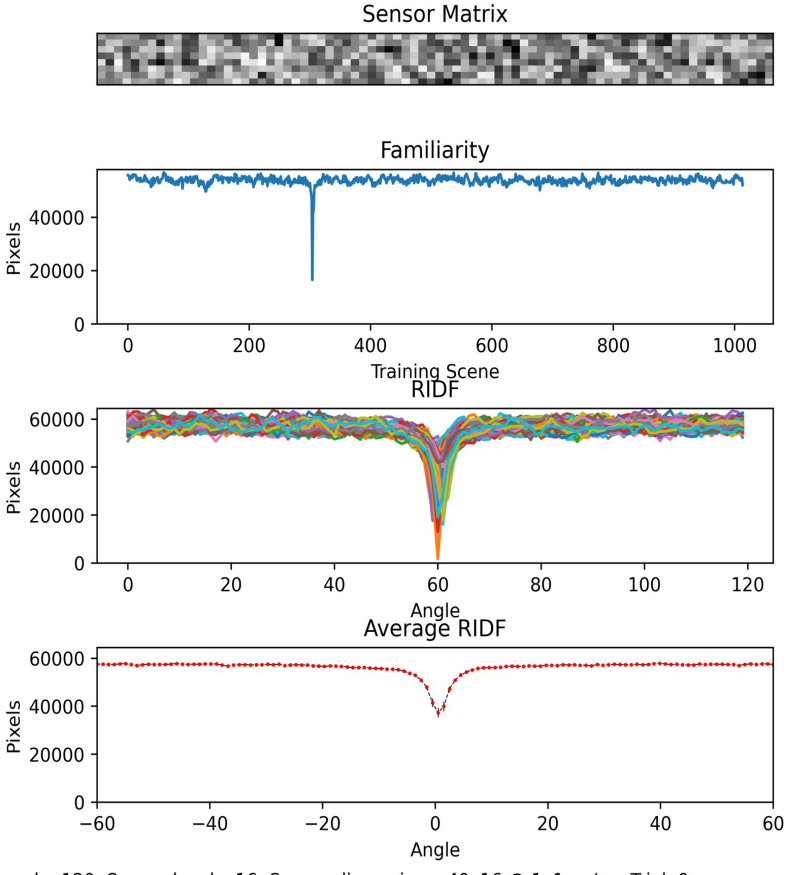


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 54.89; RMSD/dist: 0.137; TD: 14301; p90: 6; p50: 4; complete: 0

100%

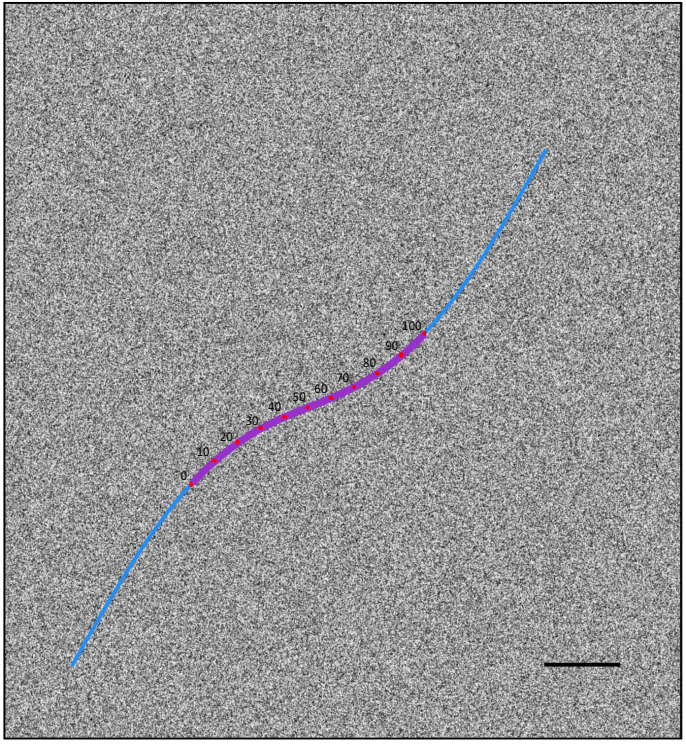


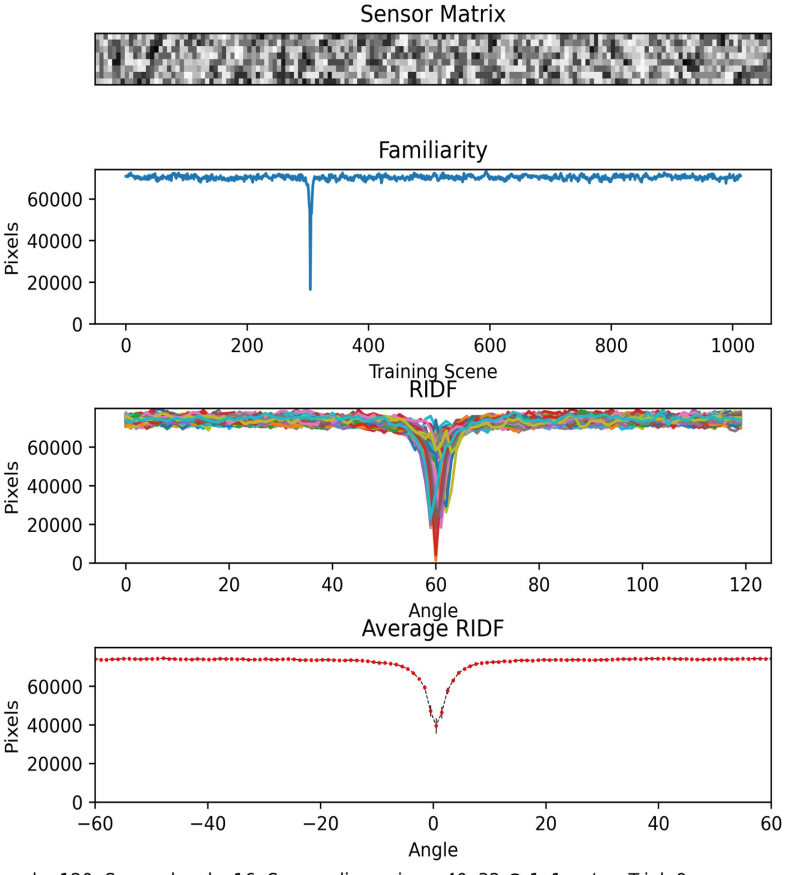


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 66.89; RMSD/dist: 0.167; TD: 16168; p90: 6; p50: 4; complete: 0

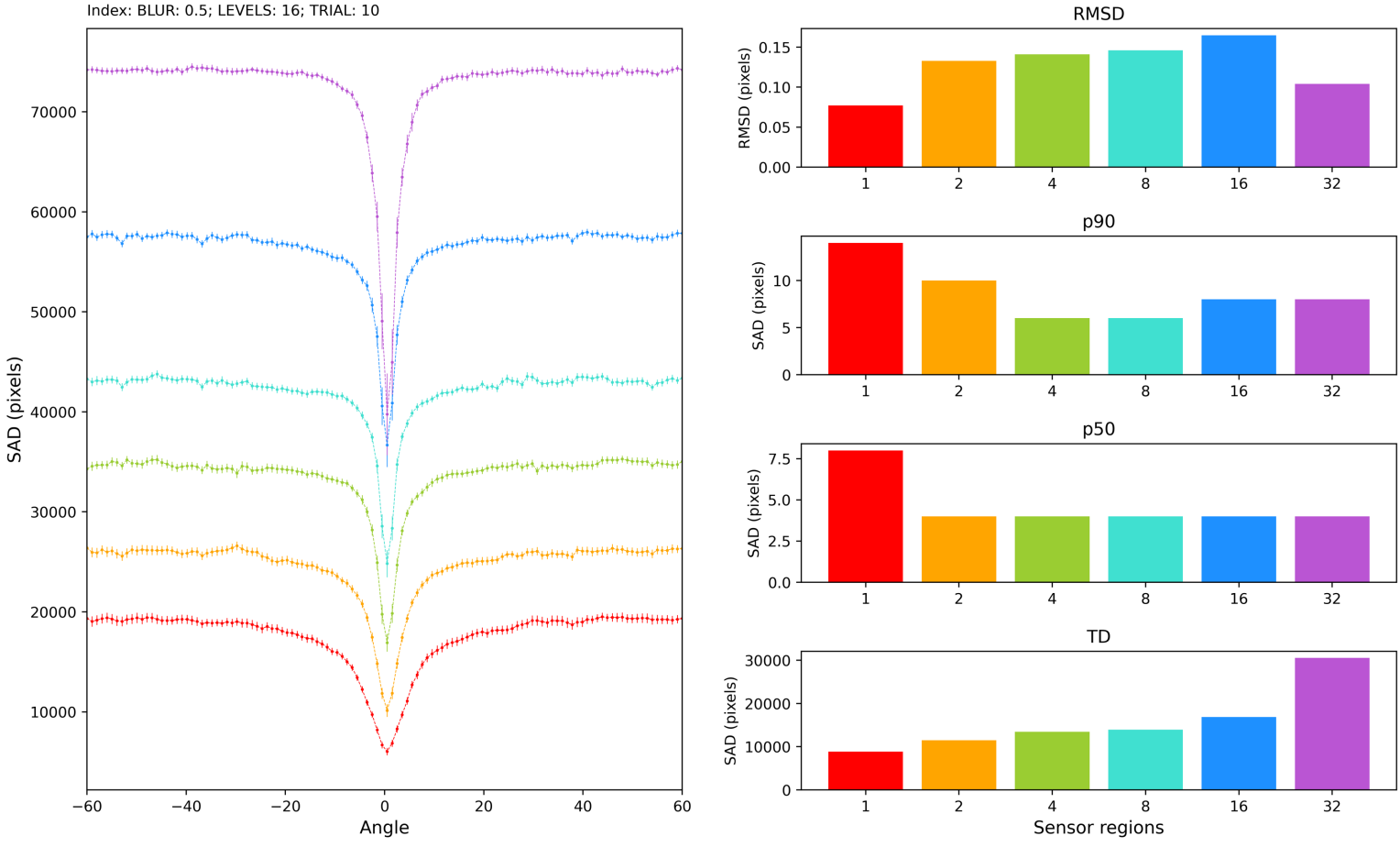
100%



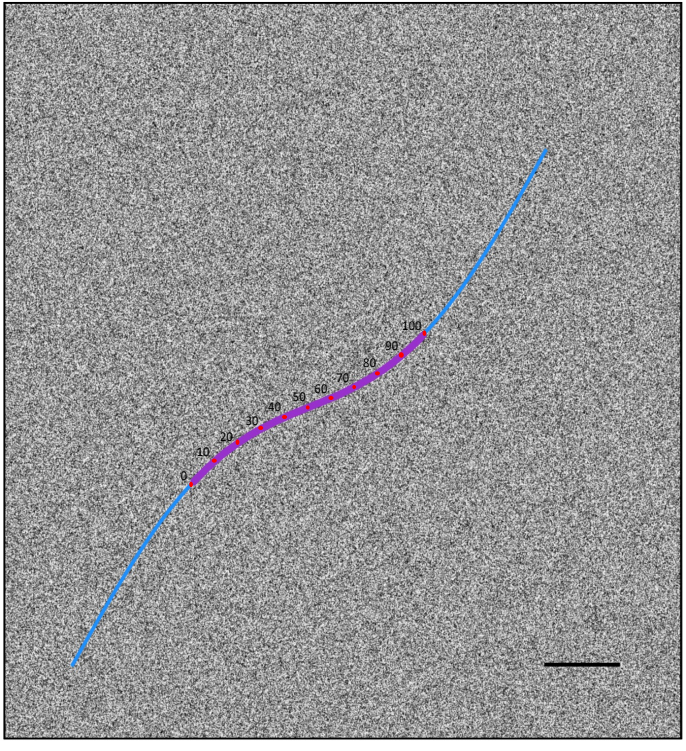


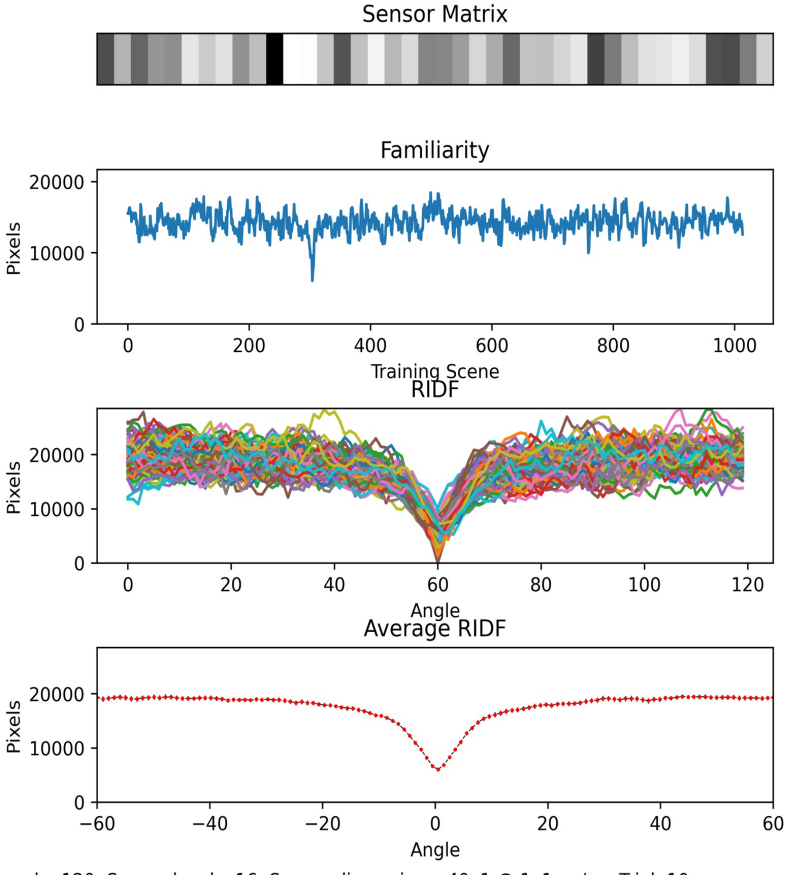
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 38.66; RMSD/dist: 0.097; TD: 30702; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 16; TRIAL: 10
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
30000
20000
10000
0
Sensor regions

100%

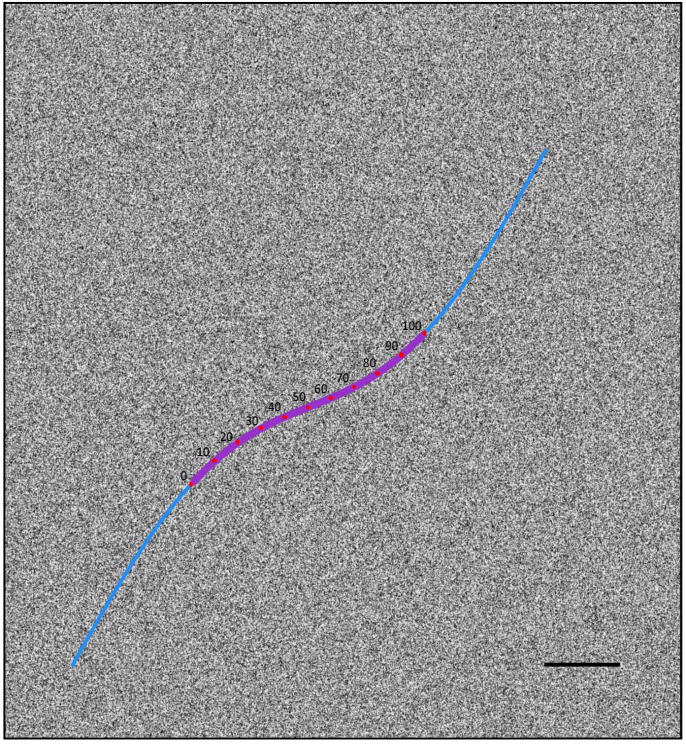


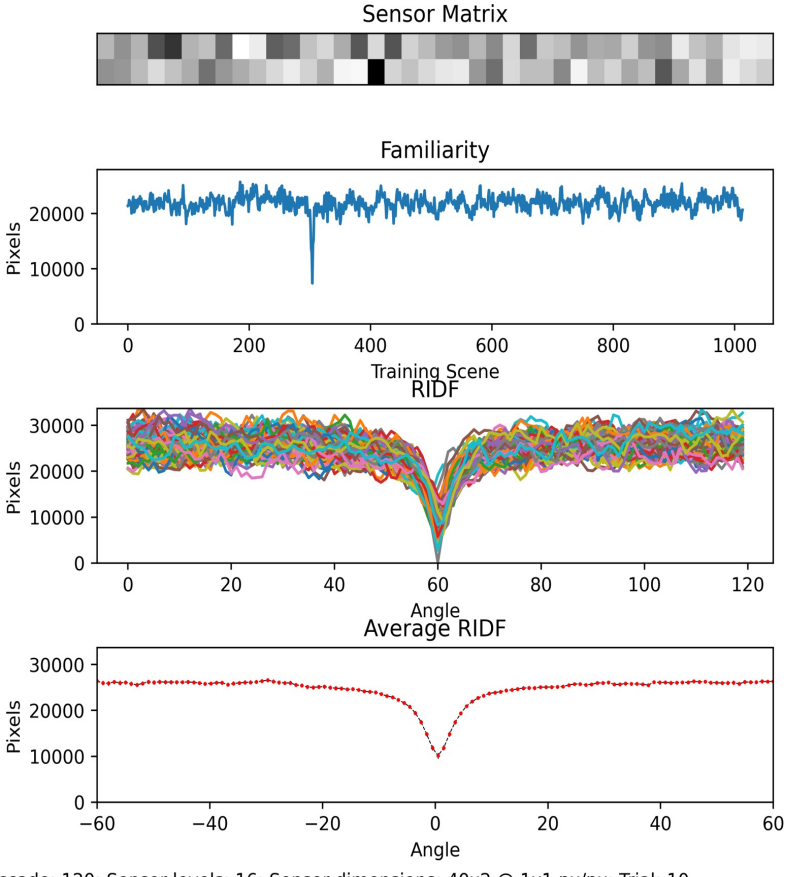


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 30.71; RMSD/dist: 0.077; TD: 8837; p90: 14; p50: 8; complete: 0

100%

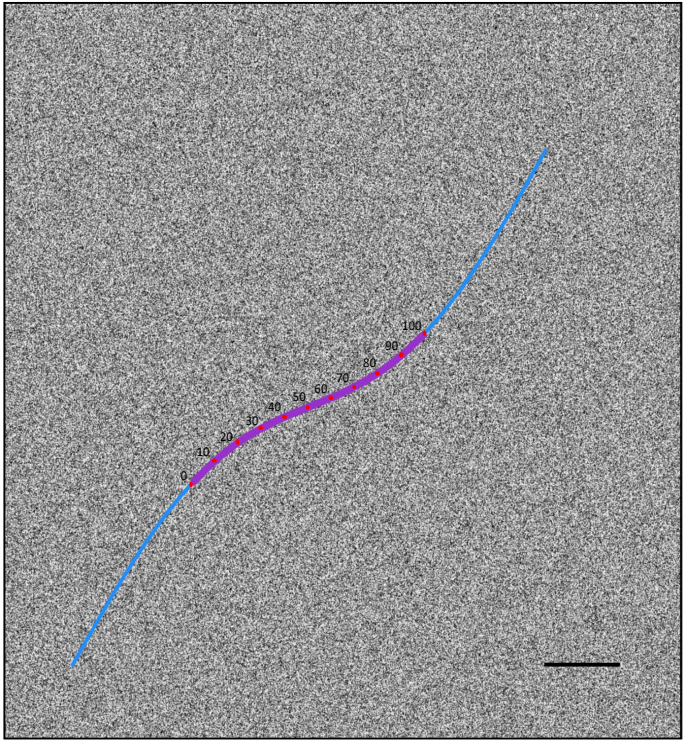


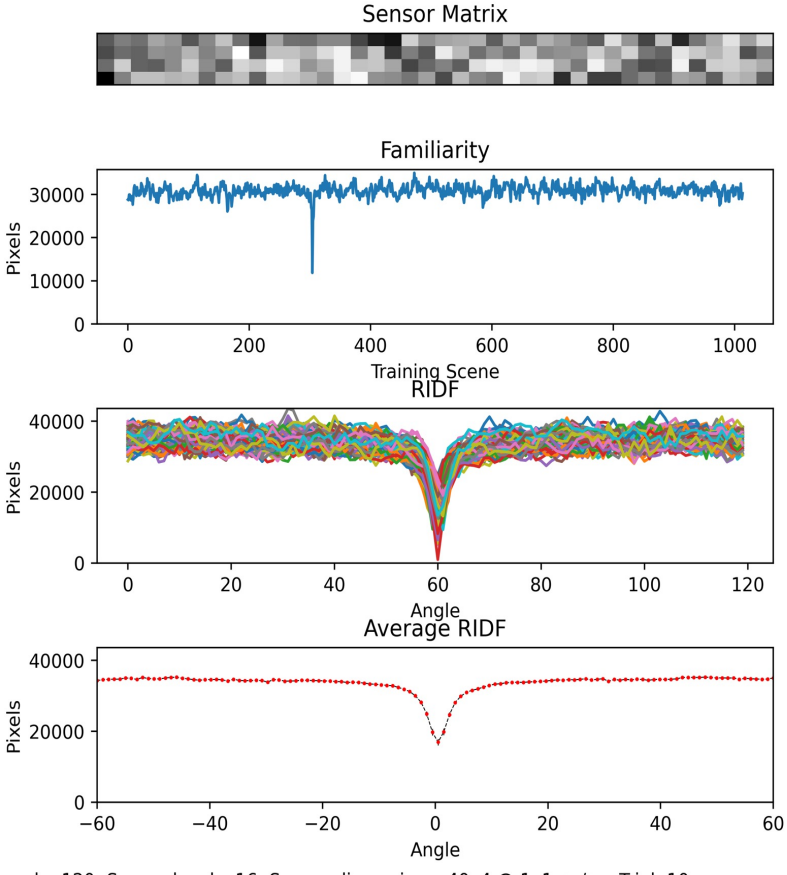


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 53.14; RMSD/dist: 0.133; TD: 11479; p90: 10; p50: 4; complete: 0

100%

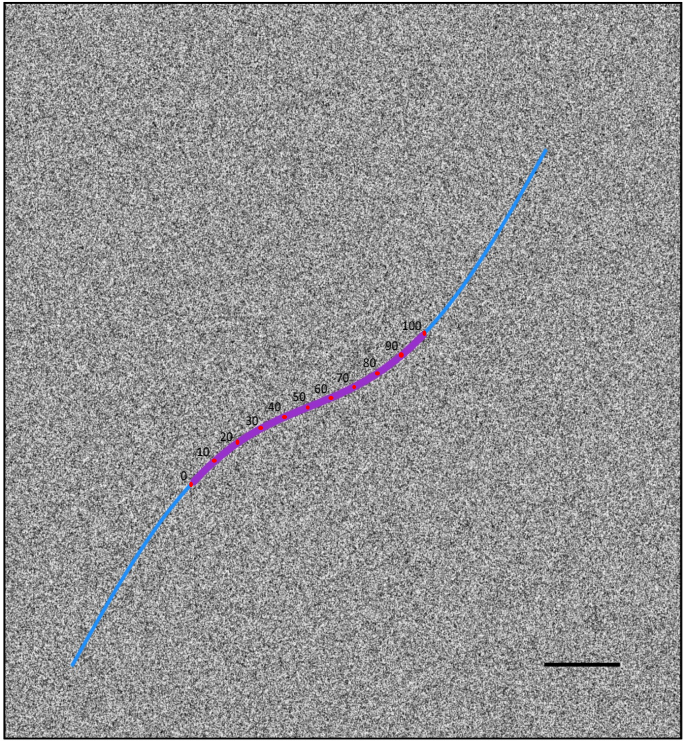


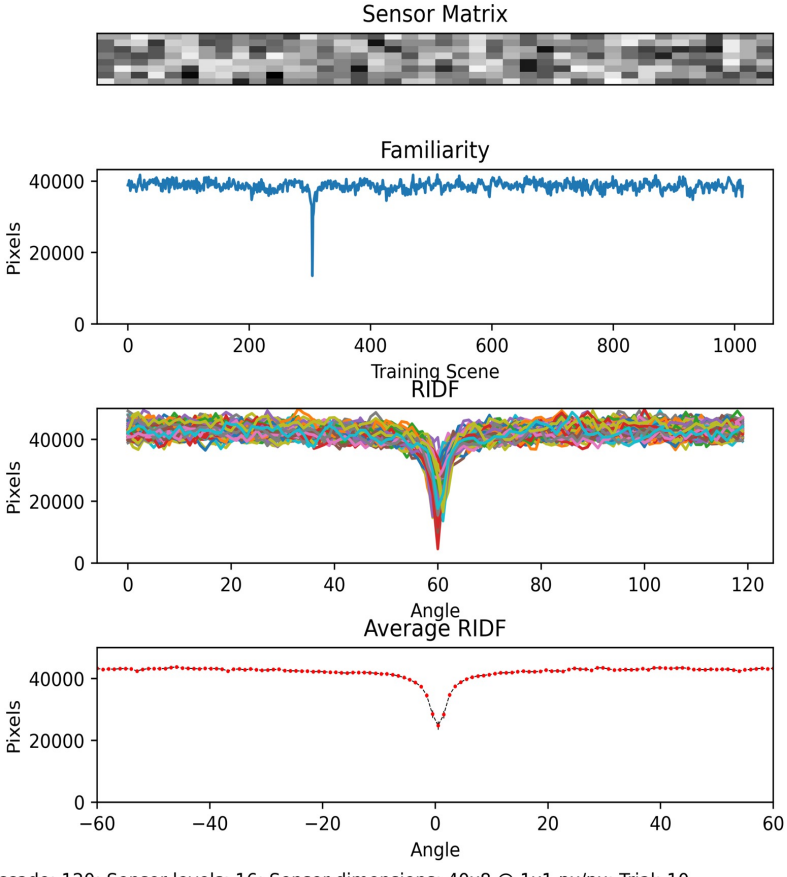


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 56.50; RMSD/dist: 0.141; TD: 13418; p90: 6; p50: 4; complete: 0

100%

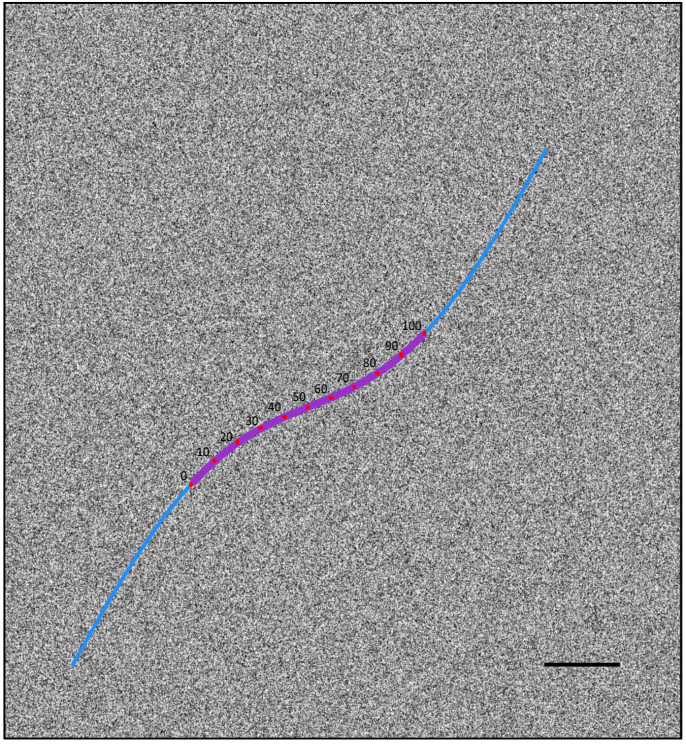


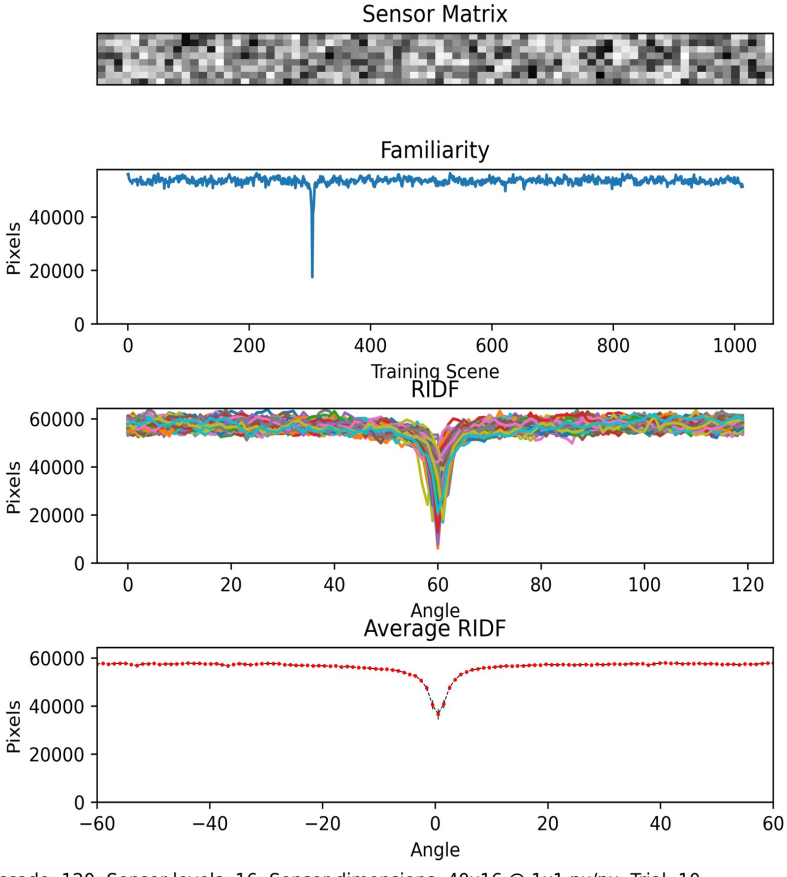


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 58.34; RMSD/dist: 0.146; TD: 13945; p90: 6; p50: 4; complete: 0

100%

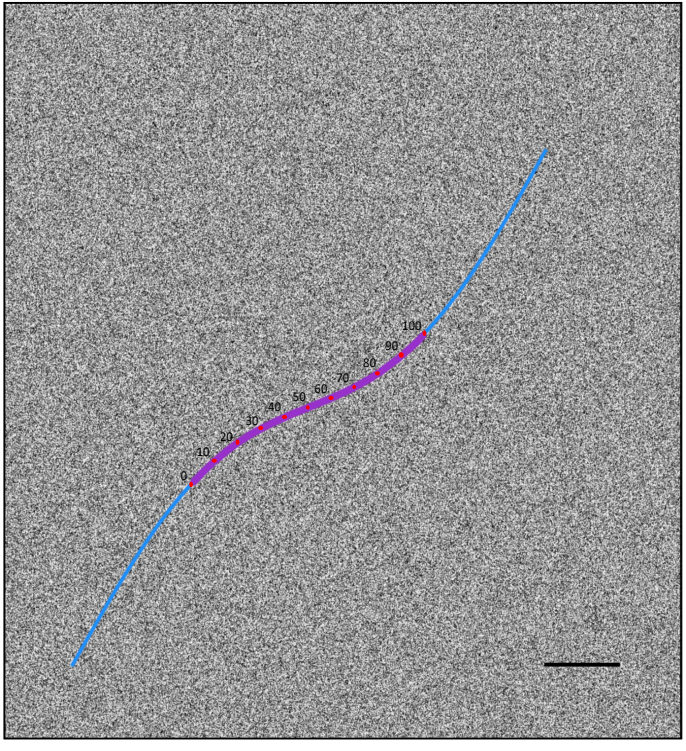


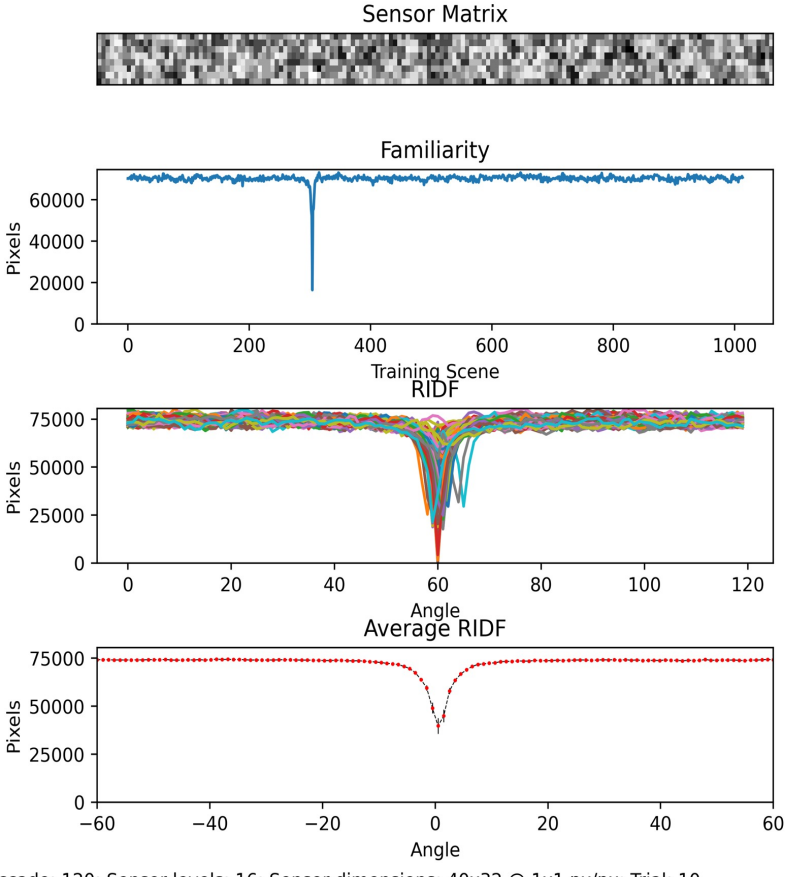


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 65.92; RMSD/dist: 0.165; TD: 16854; p90: 8; p50: 4; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 41.65; RMSD/dist: 0.104; TD: 30531; p90: 8; p50: 4; complete: 0