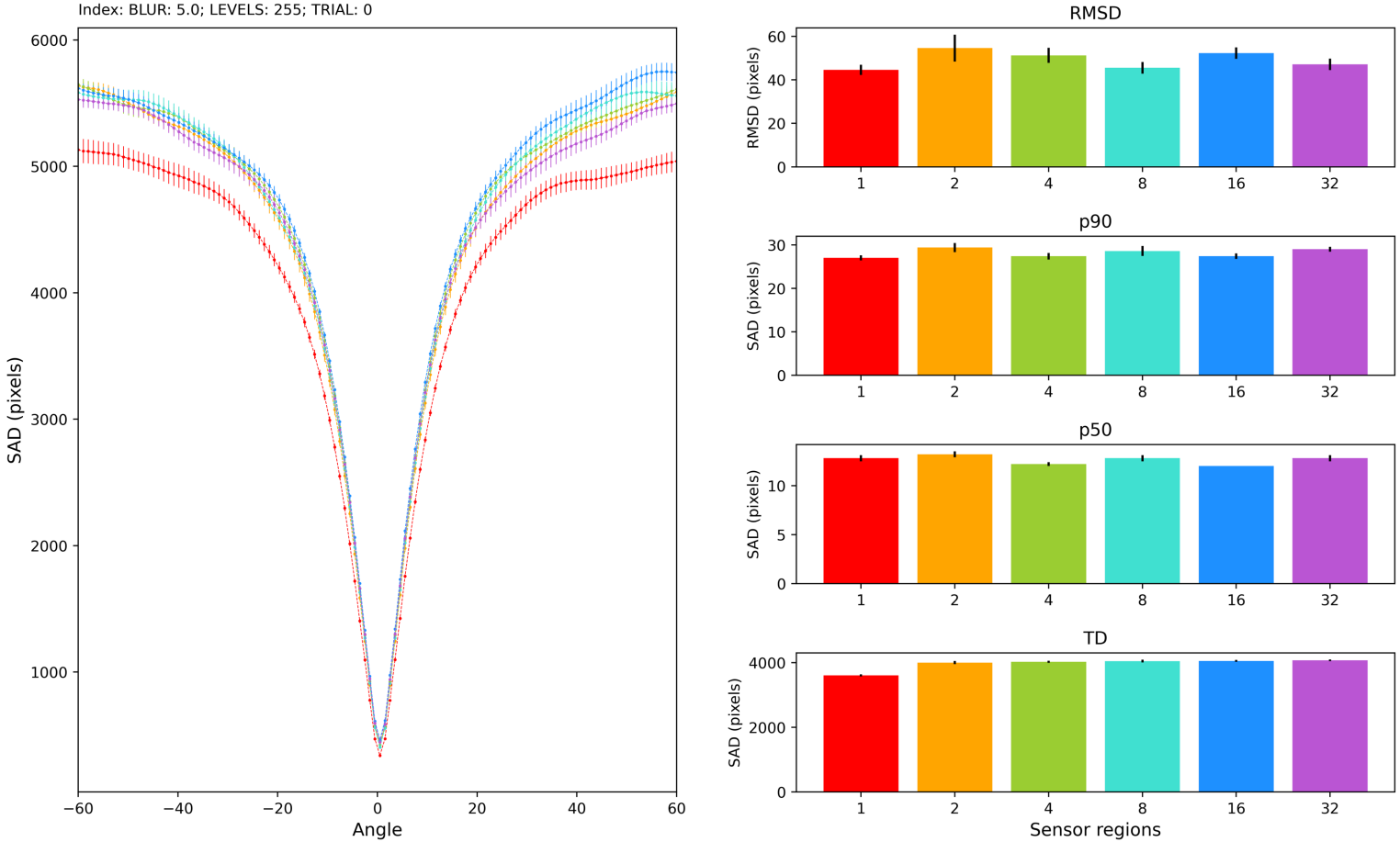
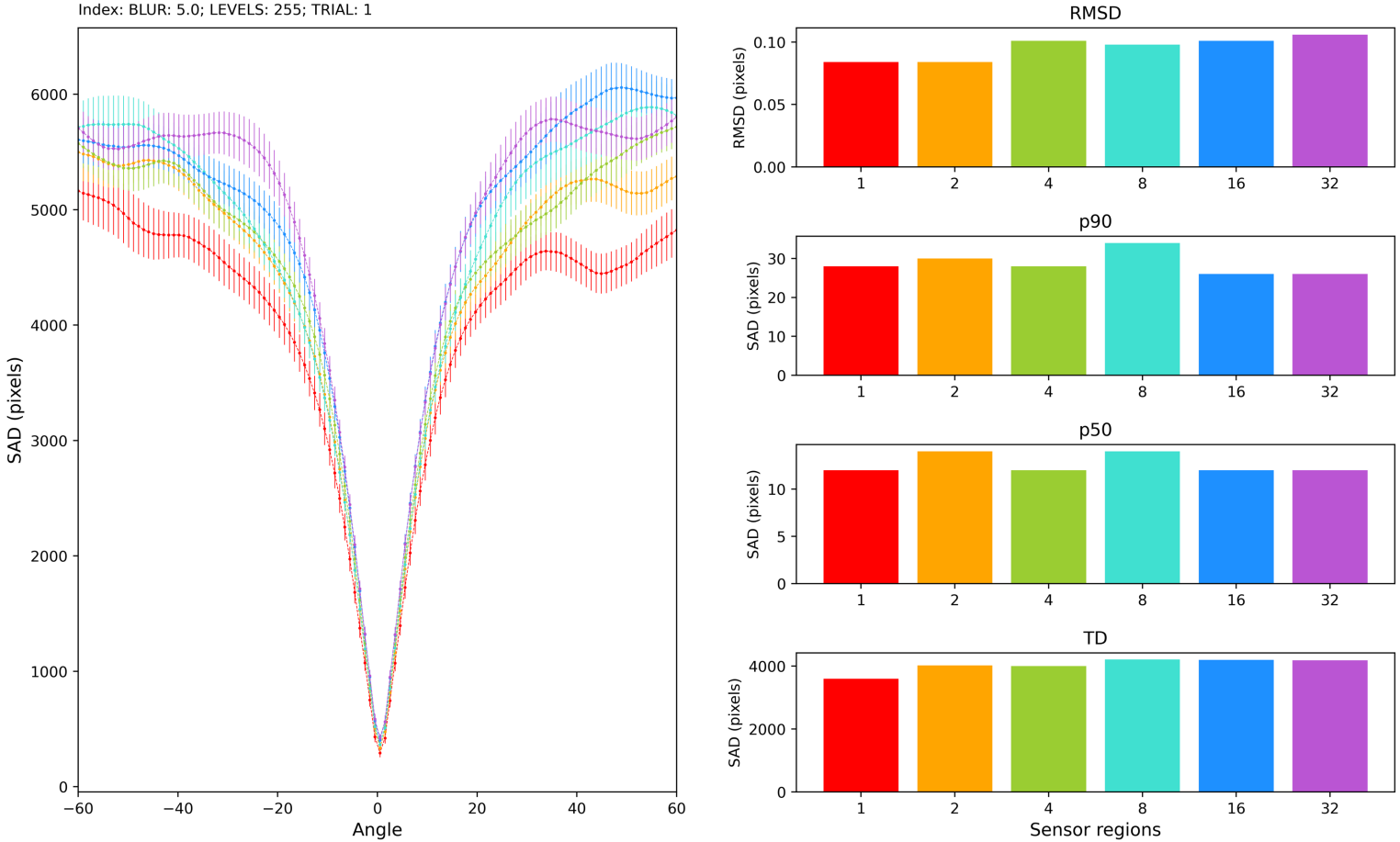

Index: BLUR: 5.0; LEVELS: 255; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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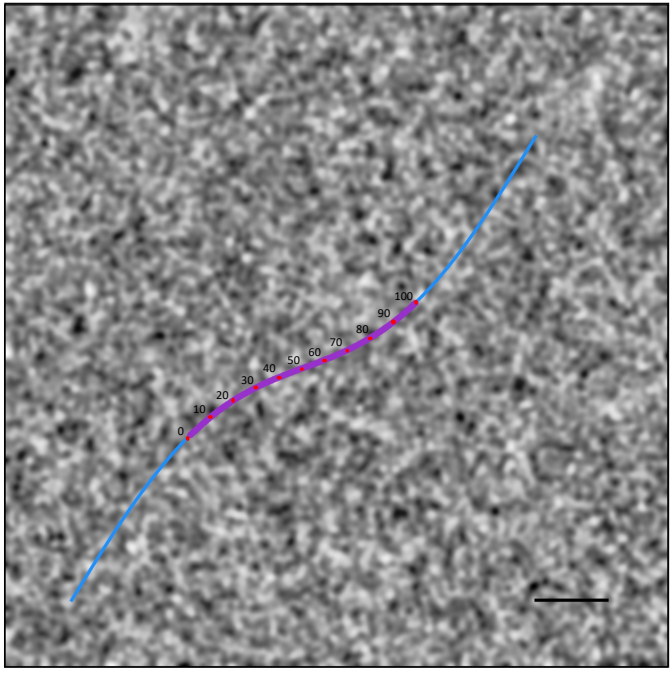
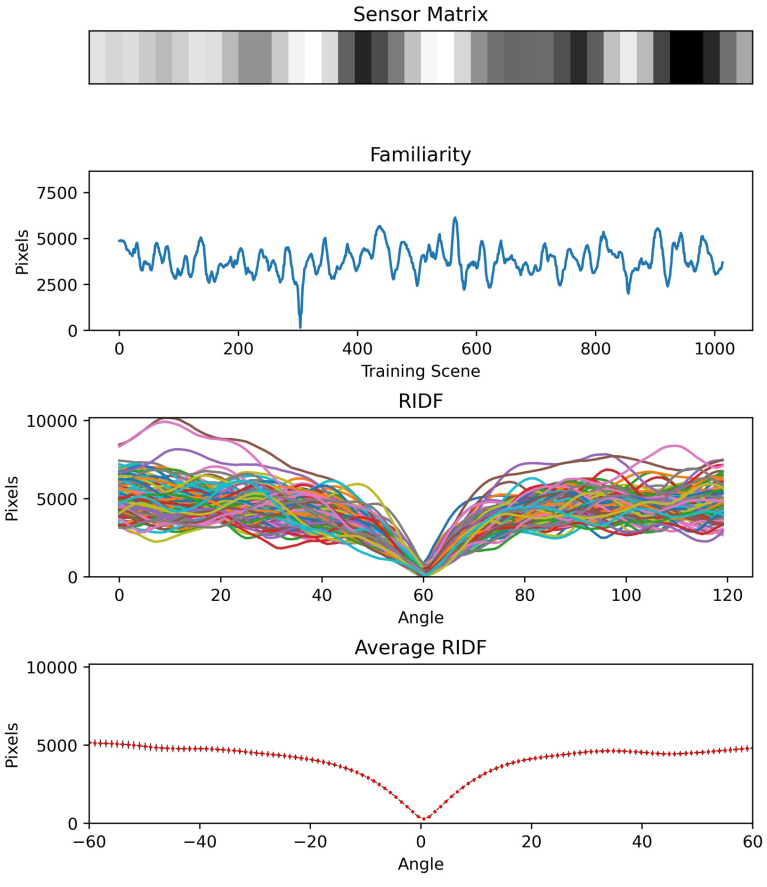
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

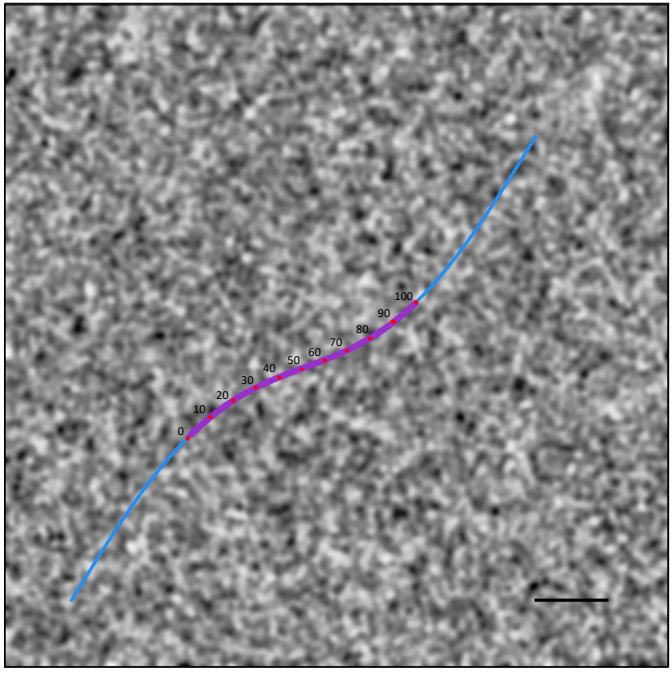


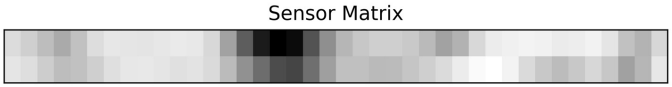


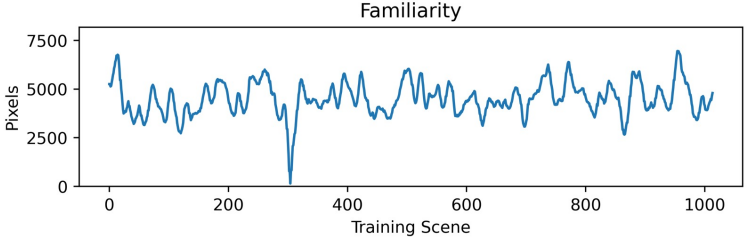
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

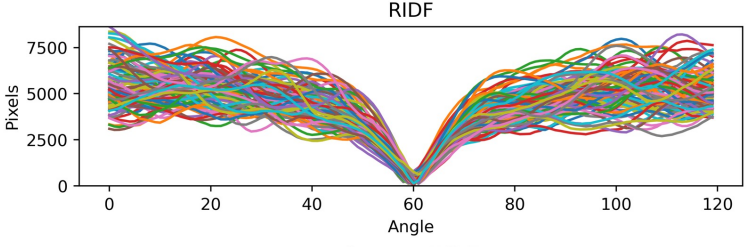
Navigation stats: RMSD error: 33.48; RMSD/dist: 0.084; TD: 3599; p90: 28; p50: 12; complete: 0

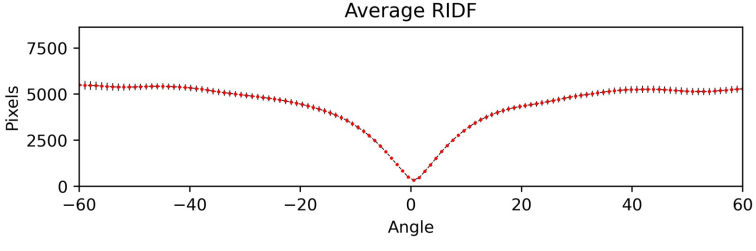
100%







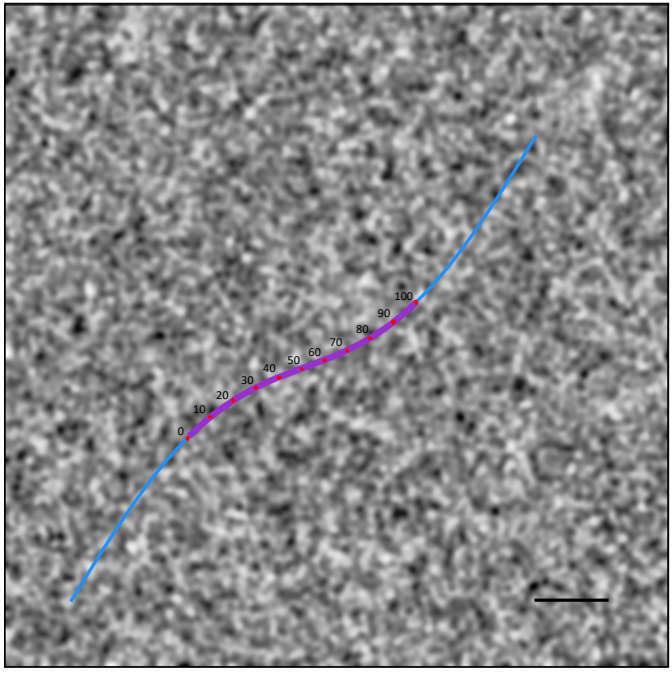


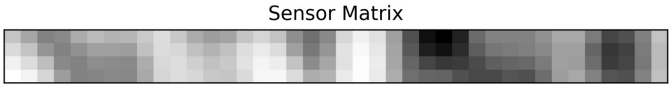


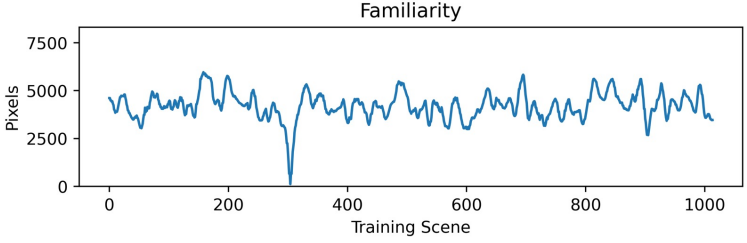
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

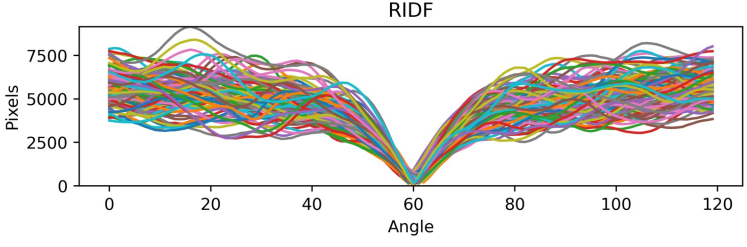
Navigation stats: RMSD error: 33.64; RMSD/dist: 0.084; TD: 4026; p90: 30; p50: 14; complete: 0

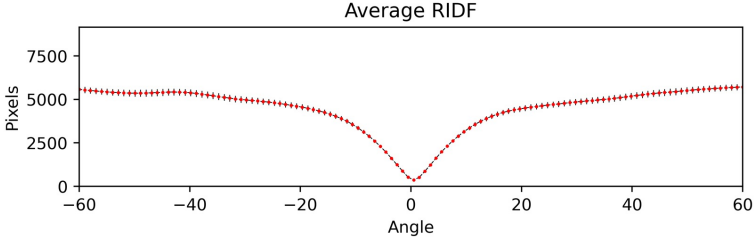
100%







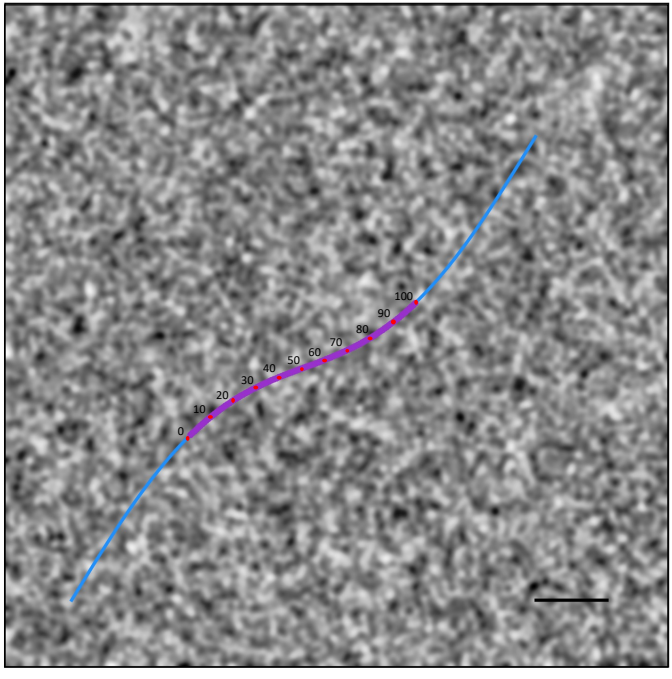


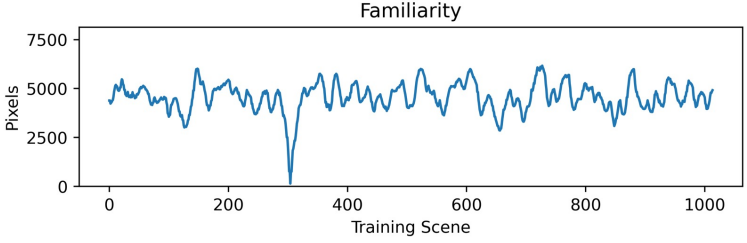


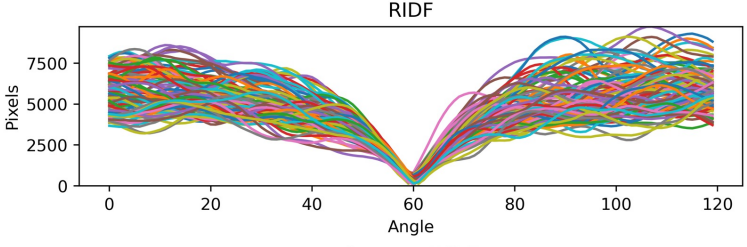
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

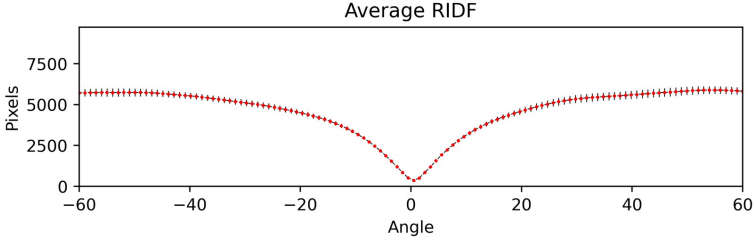
Navigation stats: RMSD error: 40.29; RMSD/dist: 0.101; TD: 4006; p90: 28; p50: 12; complete: 0

100%





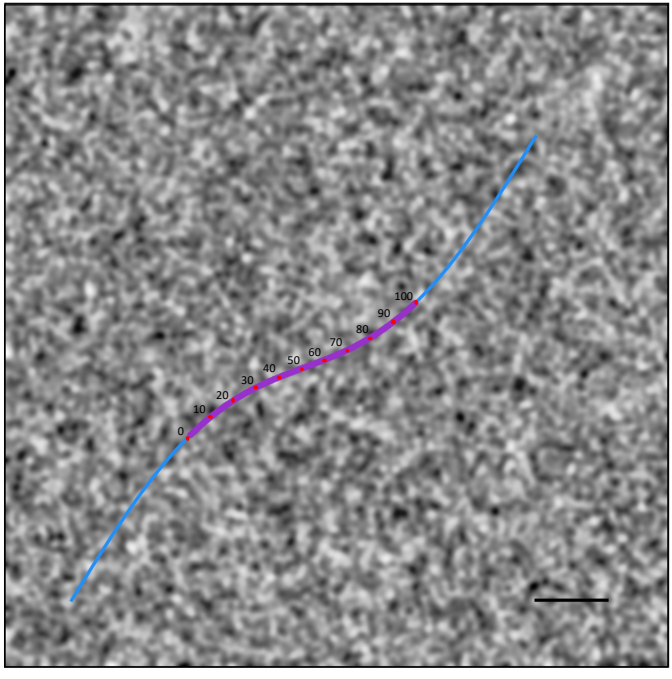


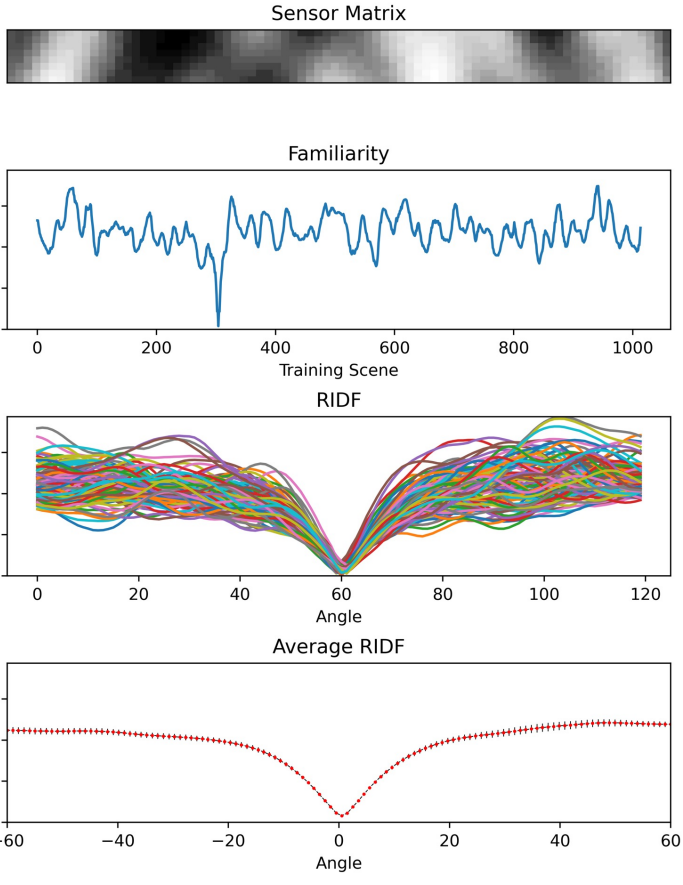


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 39.38; RMSD/dist: 0.098; TD: 4209; p90: 34; p50: 14; complete: 0

100%

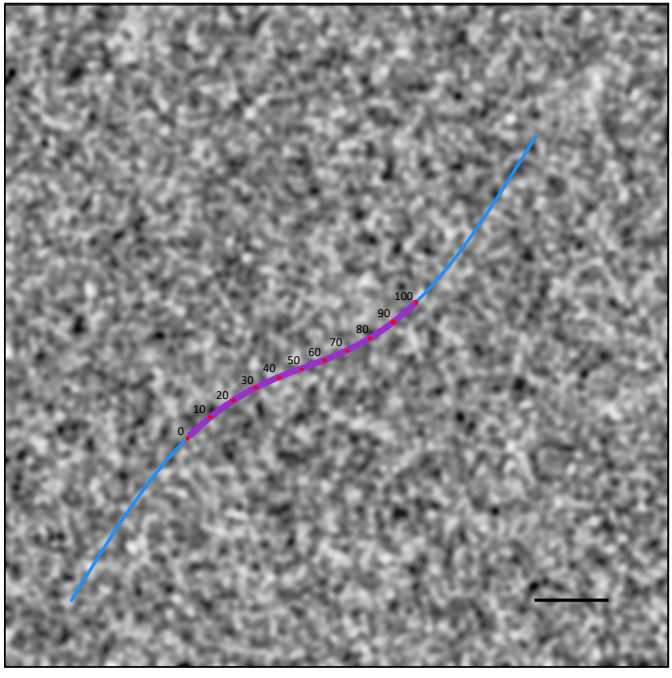


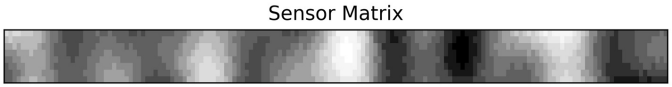


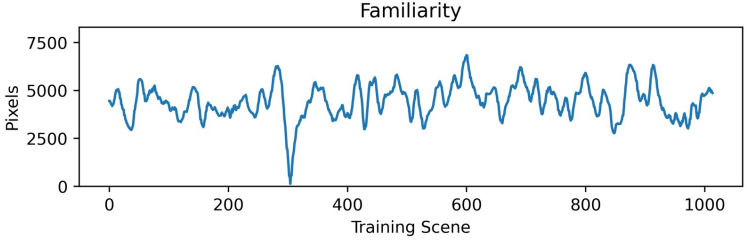
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

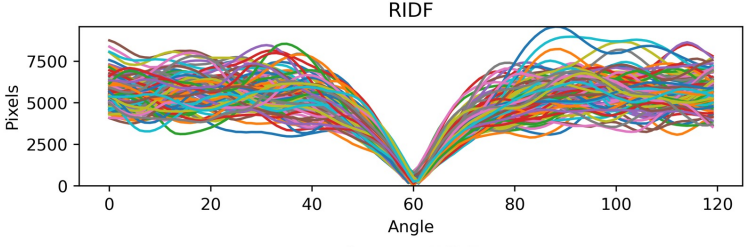
Navigation stats: RMSD error: 40.37; RMSD/dist: 0.101; TD: 4197; p90: 26; p50: 12; complete: 0

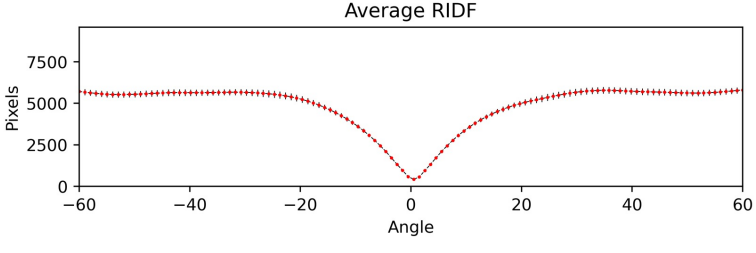
100%





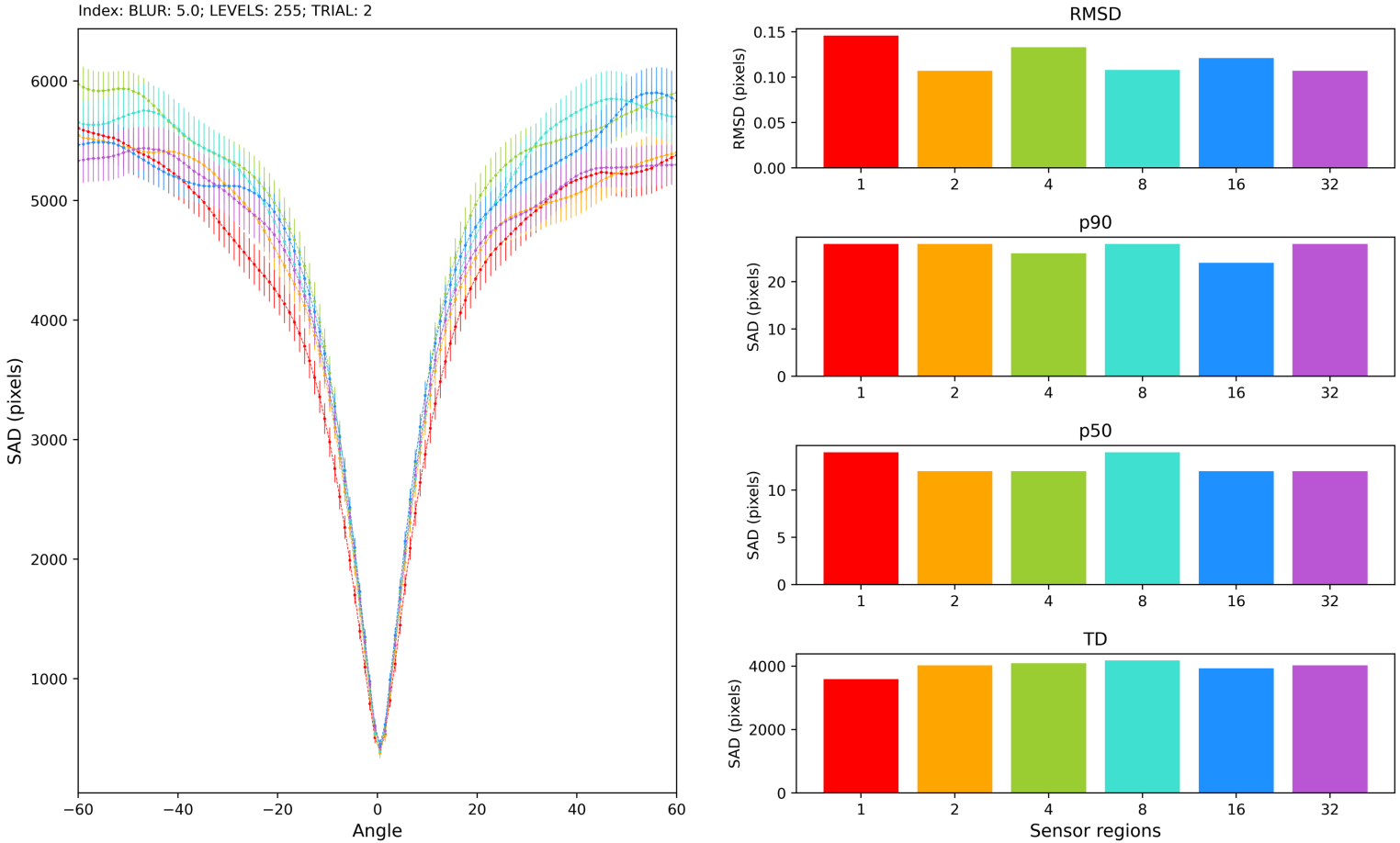




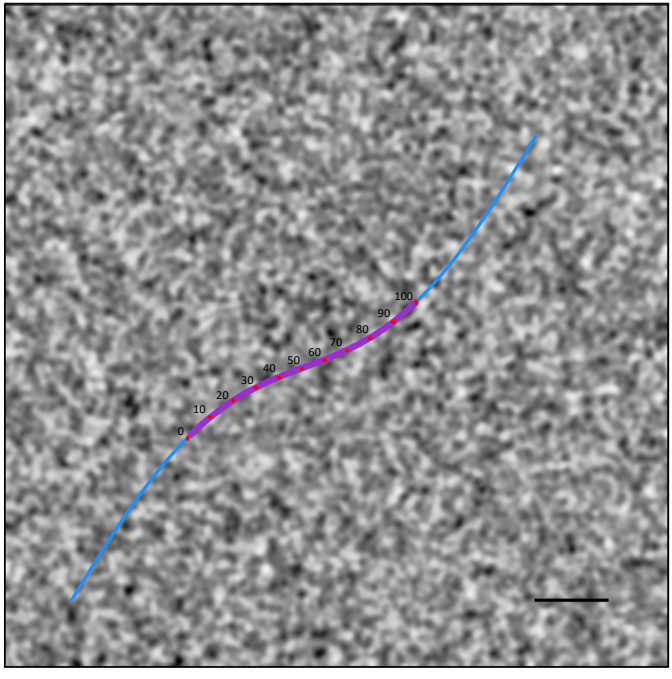


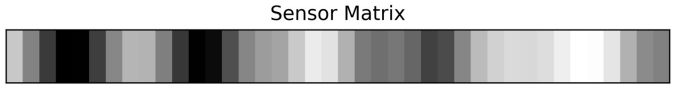
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

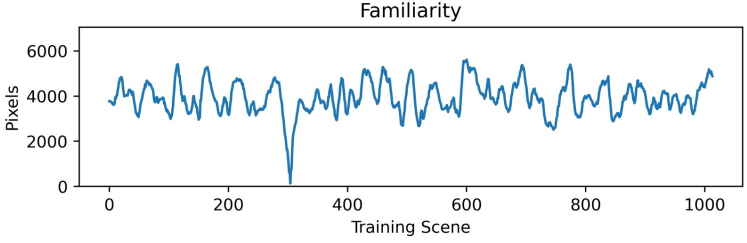
Navigation stats: RMSD error: 42.30; RMSD/dist: 0.106; TD: 4184; p90: 26; p50: 12; complete: 0

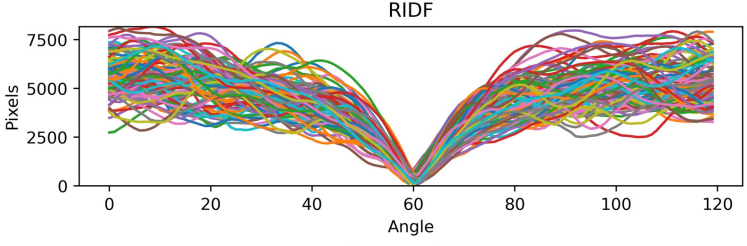

Index: BLUR: 5.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

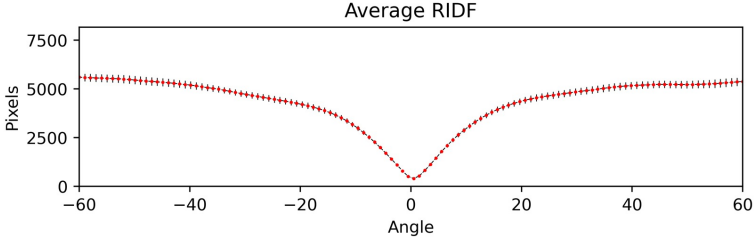
100%







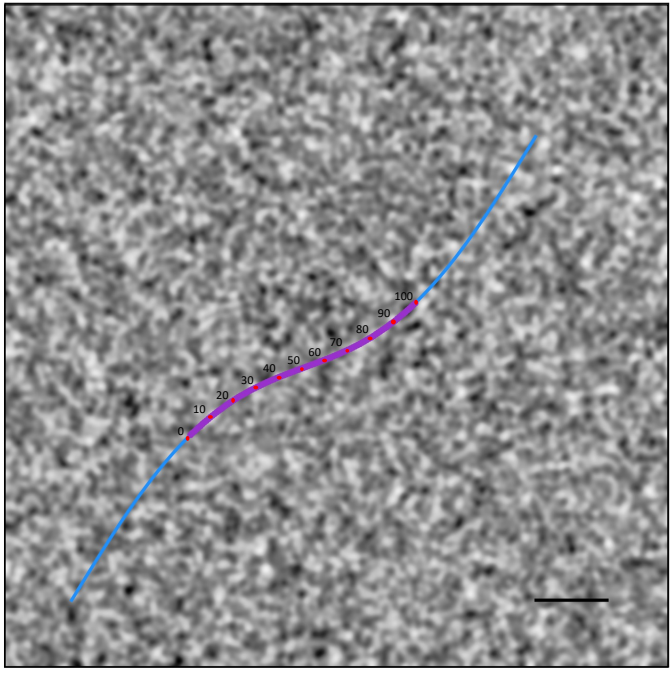


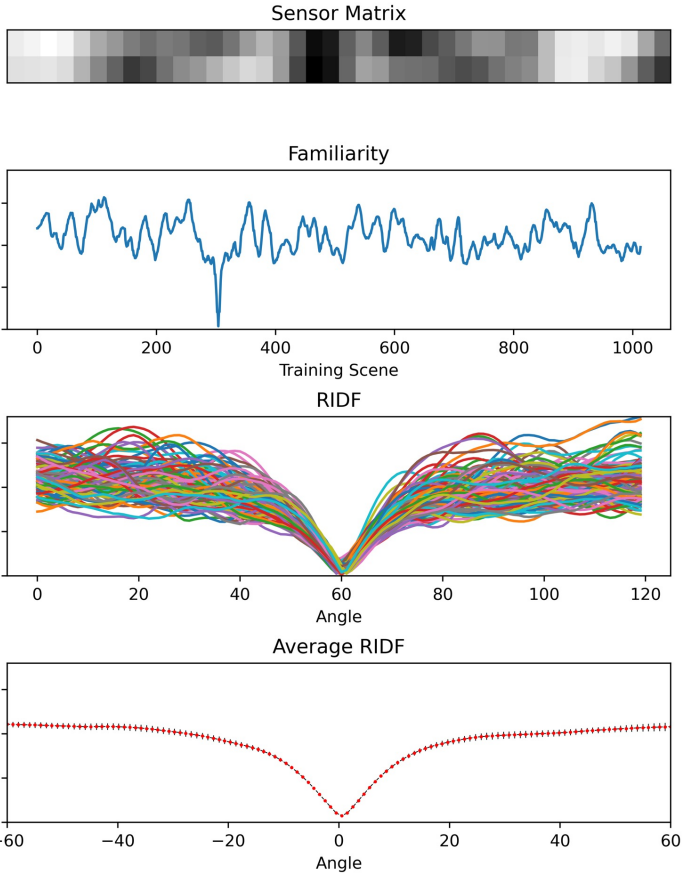


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 58.57; RMSD/dist: 0.146; TD: 3591; p90: 28; p50: 14; complete: 0

100%

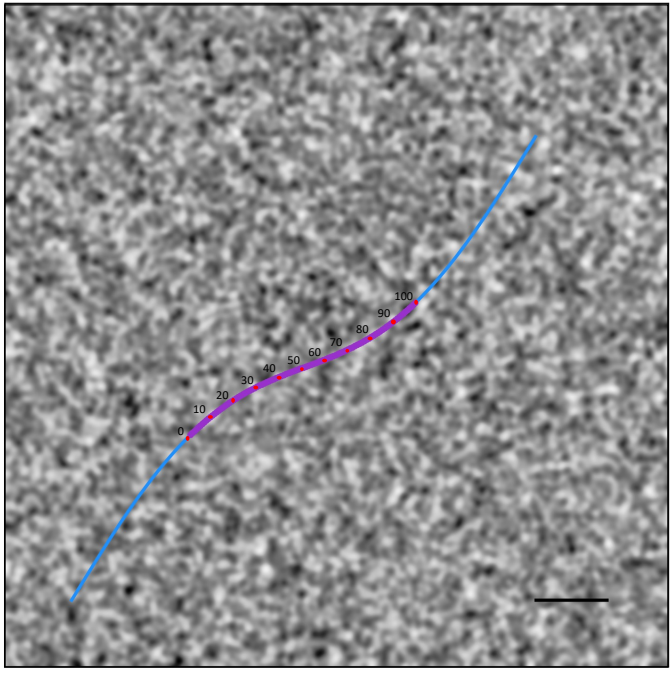


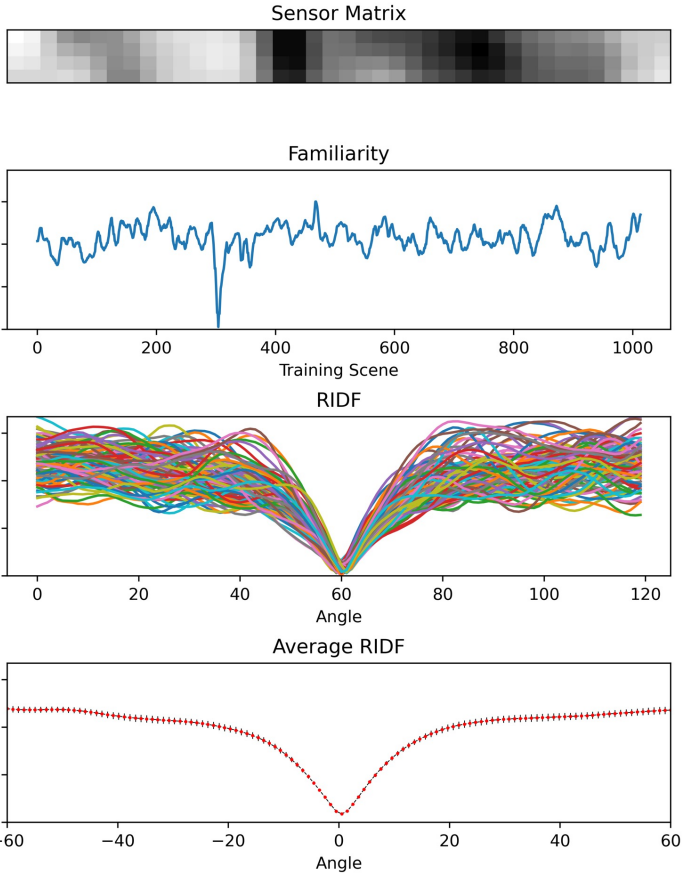


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 42.70; RMSD/dist: 0.107; TD: 4026; p90: 28; p50: 12; complete: 0

100%

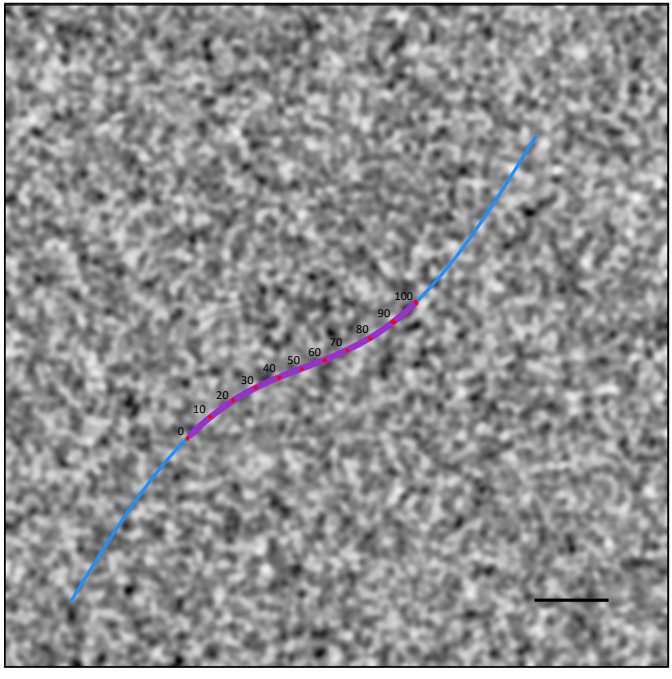


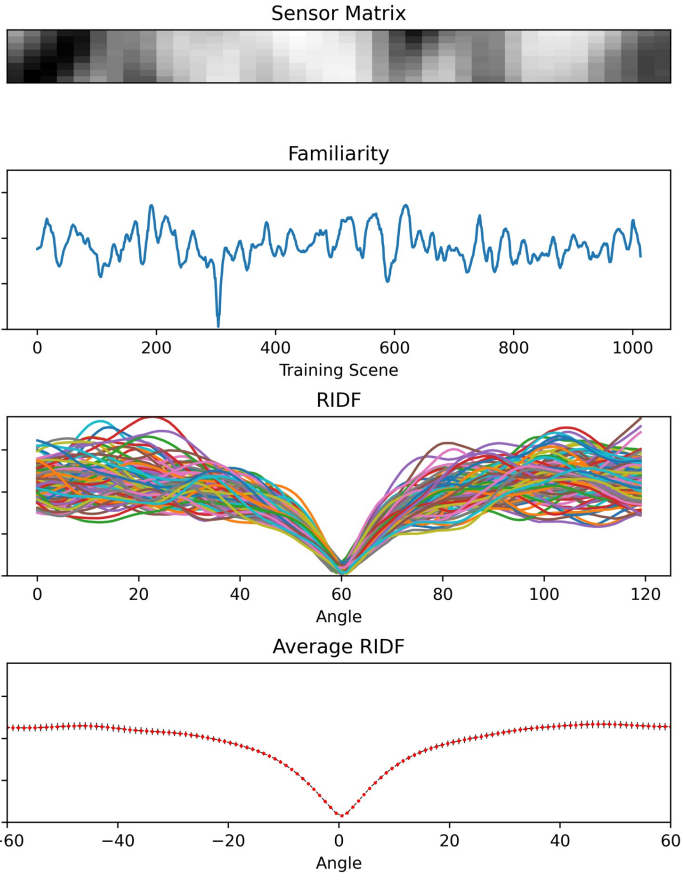


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 53.34; RMSD/dist: 0.133; TD: 4093; p90: 26; p50: 12; complete: 0

100%

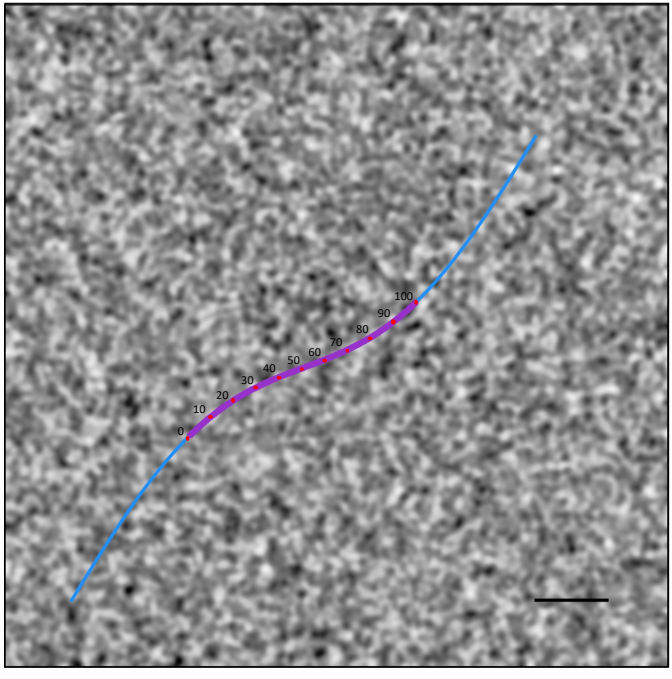


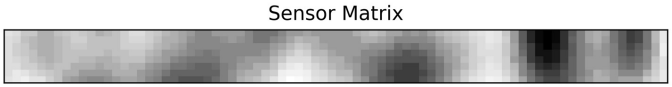


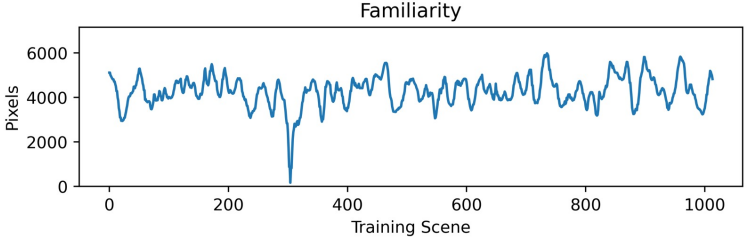
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

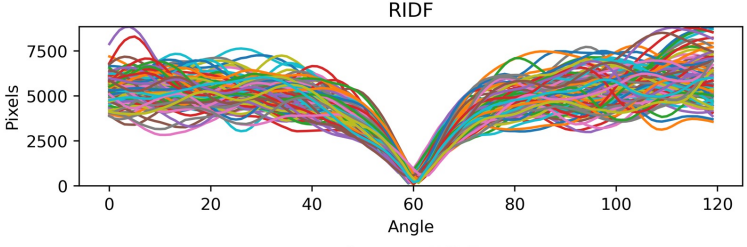
Navigation stats: RMSD error: 43.14; RMSD/dist: 0.108; TD: 4174; p90: 28; p50: 14; complete: 0

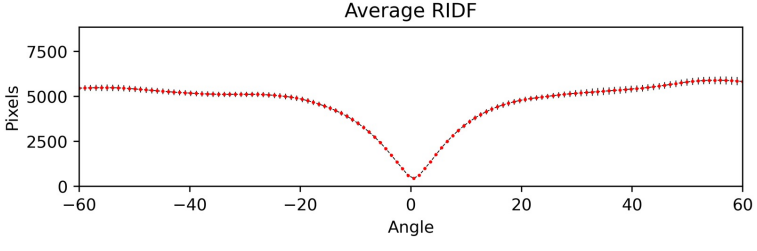
100%







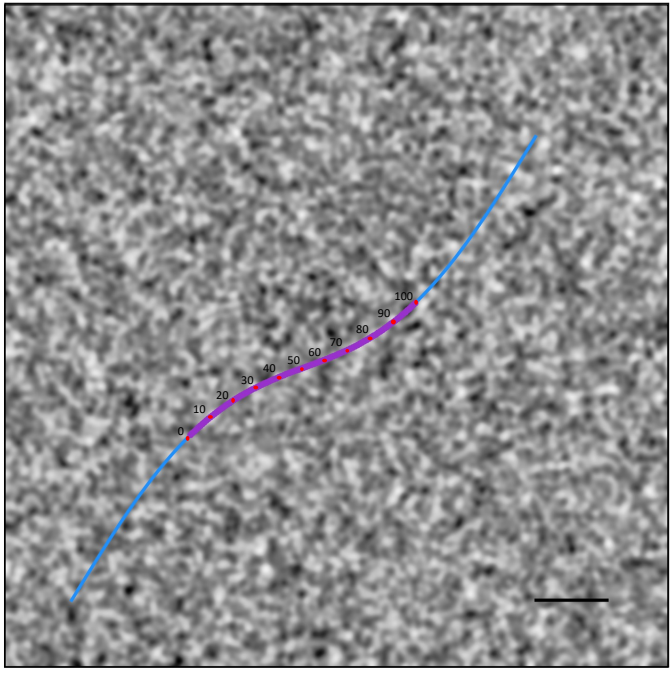


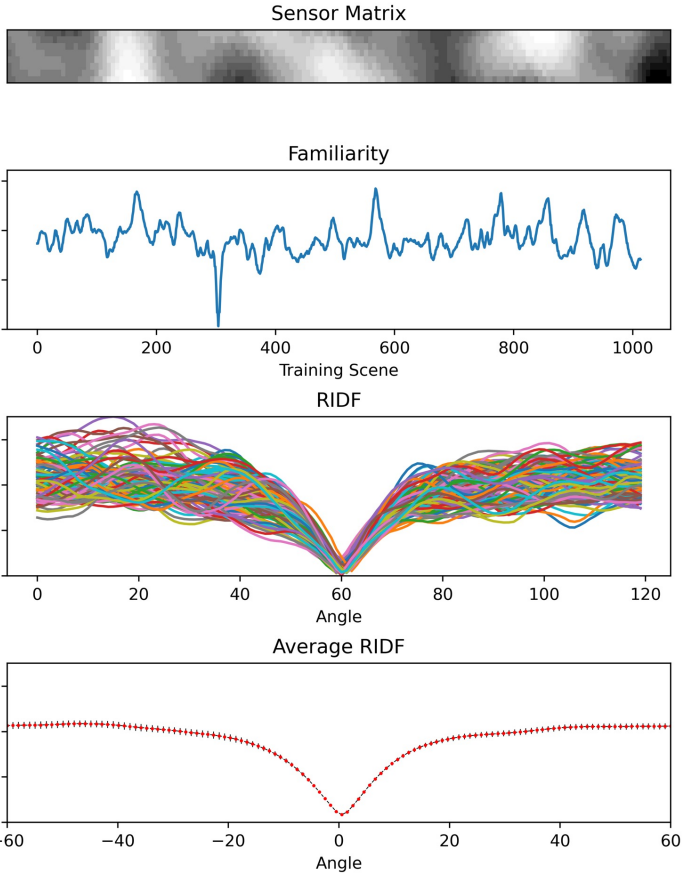


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 48.48; RMSD/dist: 0.121; TD: 3929; p90: 24; p50: 12; complete: 0

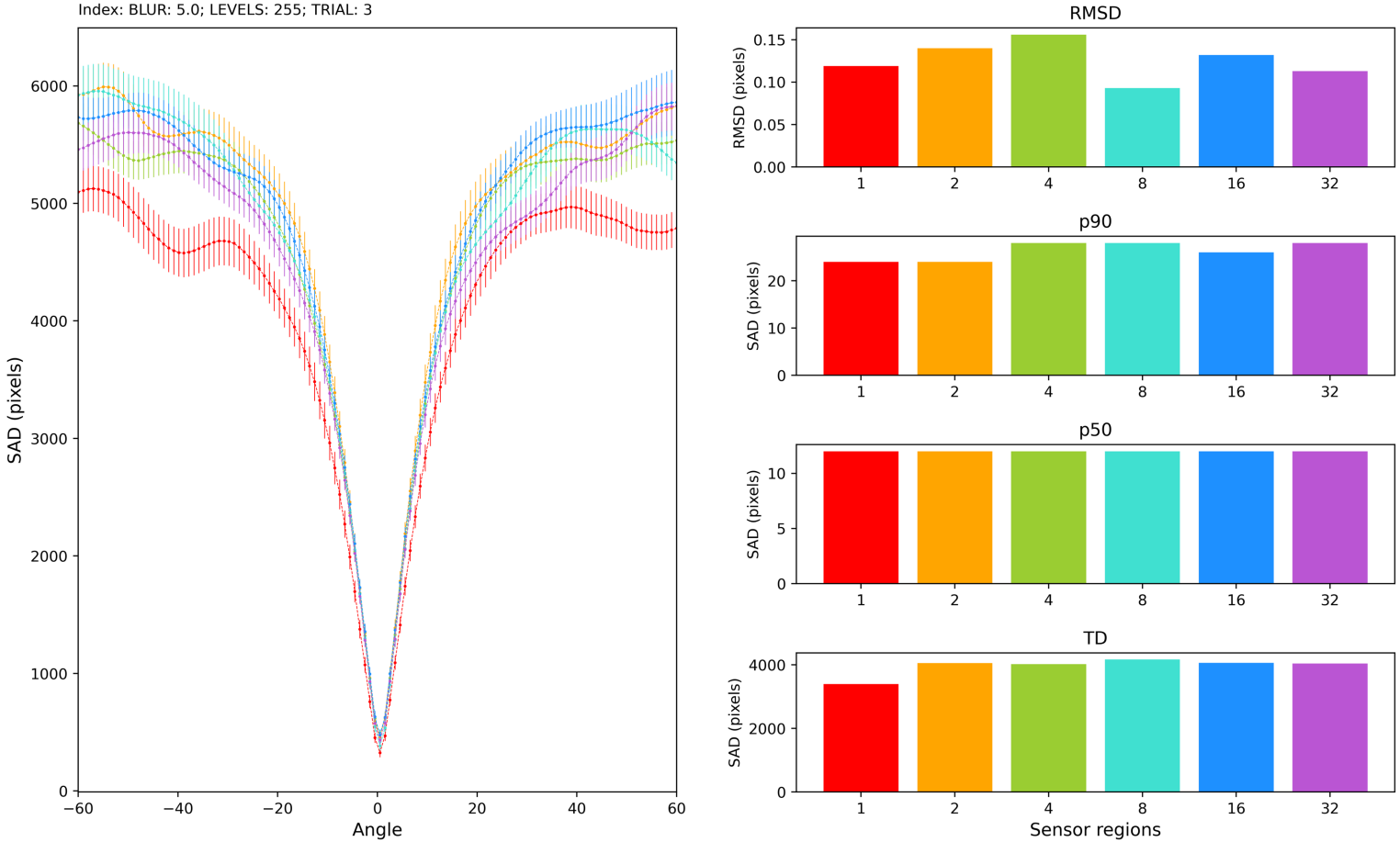
100%



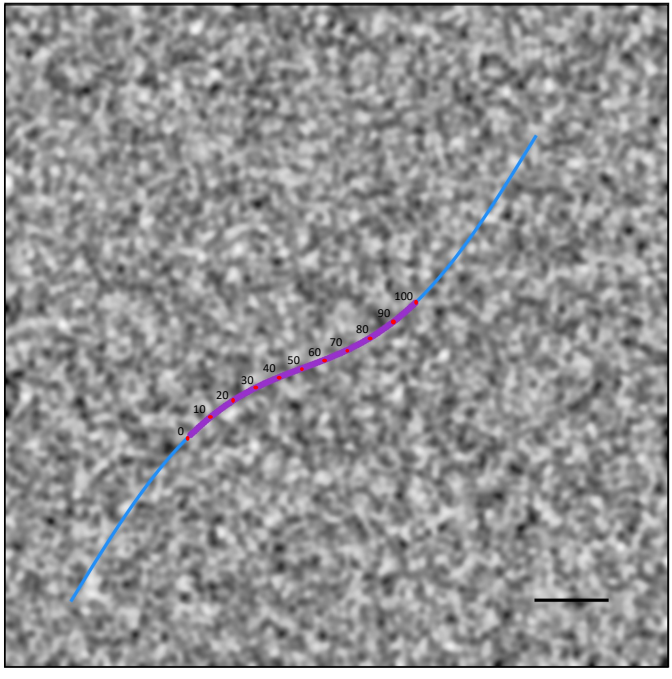


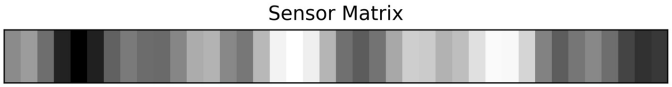
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

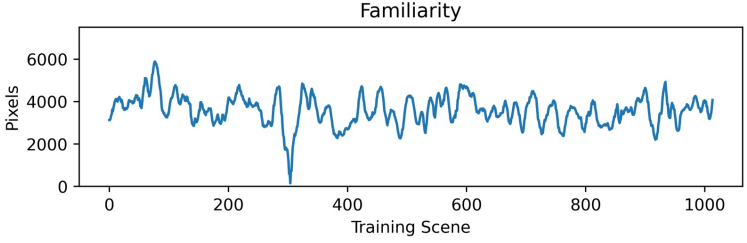
Navigation stats: RMSD error: 42.96; RMSD/dist: 0.107; TD: 4025; p90: 28; p50: 12; complete: 0

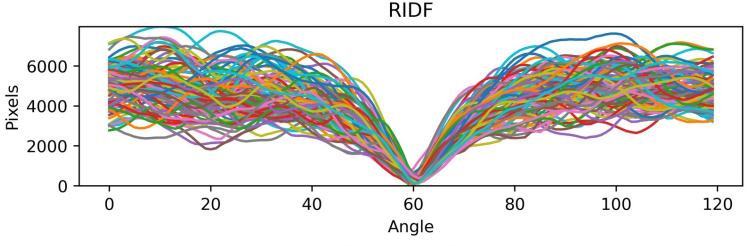

Index: BLUR: 5.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

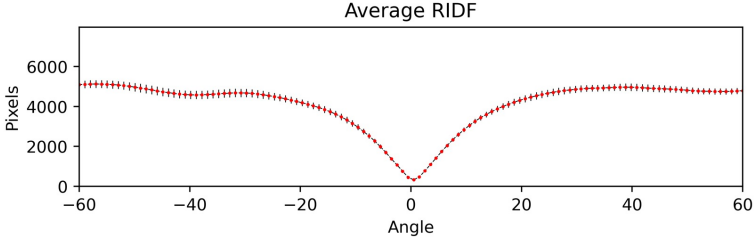
100%







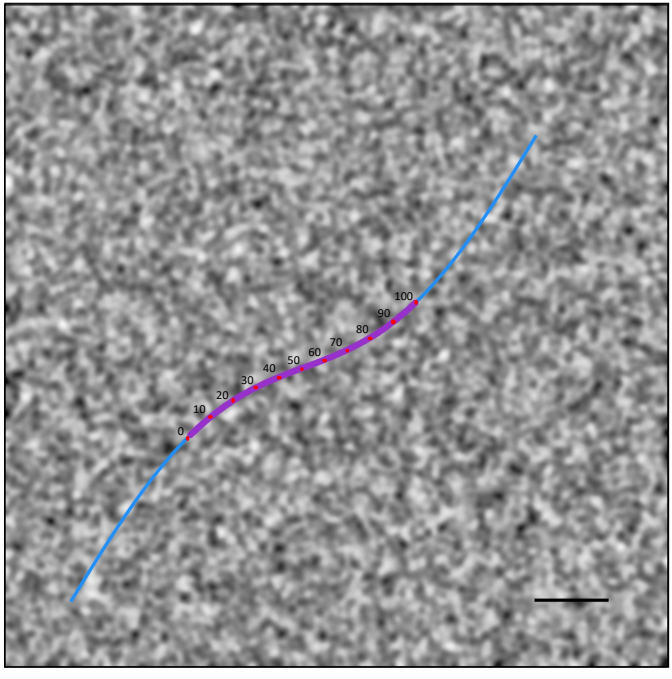


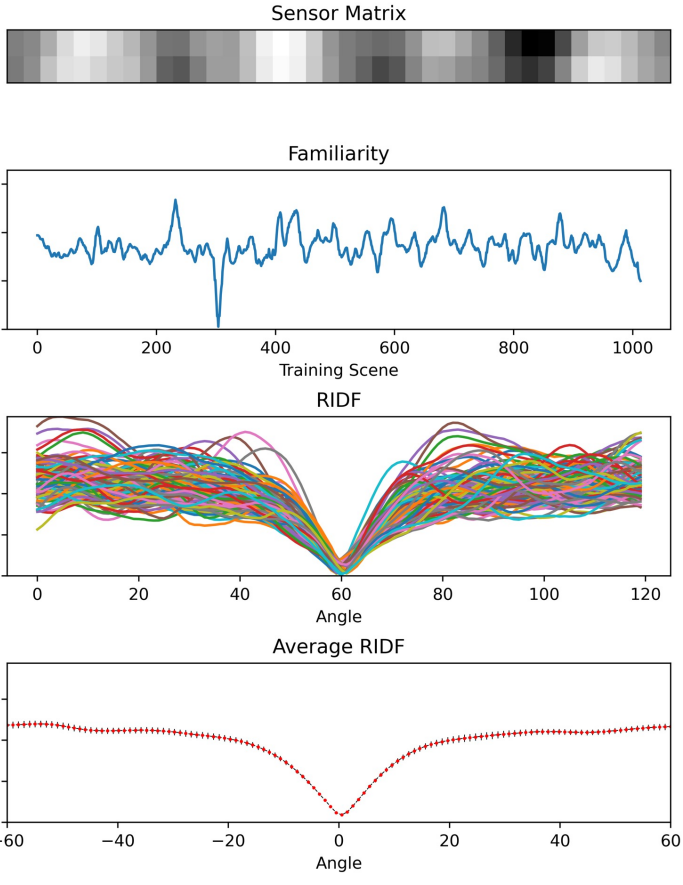


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 47.50; RMSD/dist: 0.119; TD: 3395; p90: 24; p50: 12; complete: 0

100%

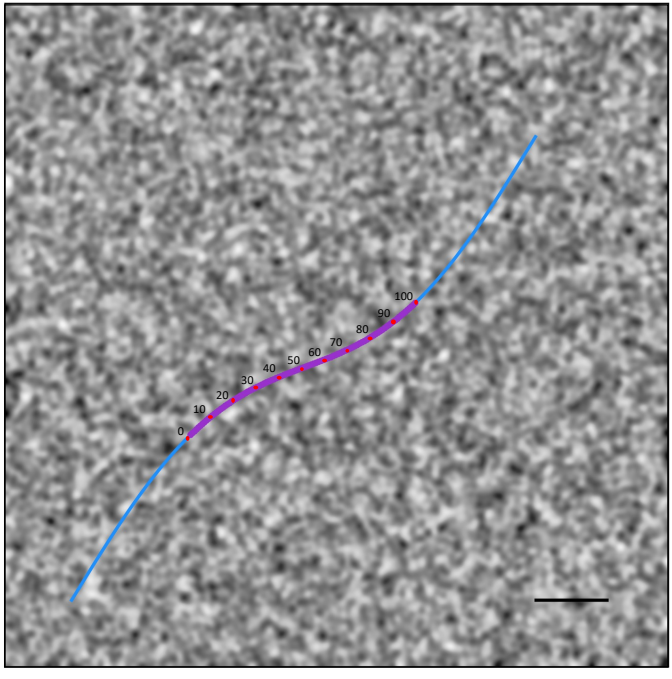


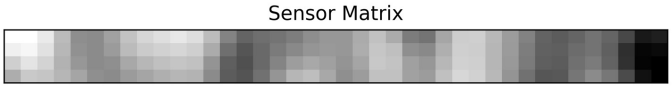


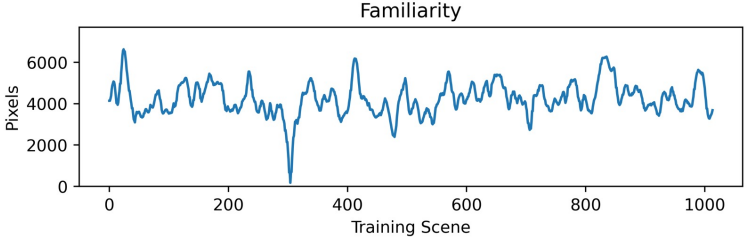
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

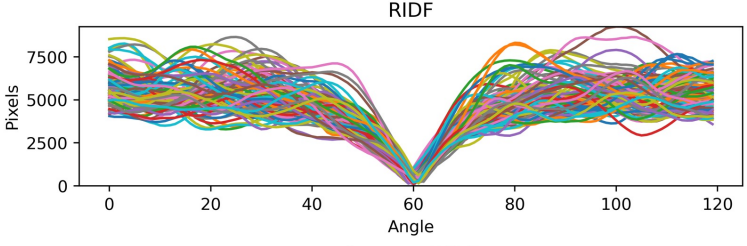
Navigation stats: RMSD error: 55.83; RMSD/dist: 0.140; TD: 4056; p90: 24; p50: 12; complete: 0

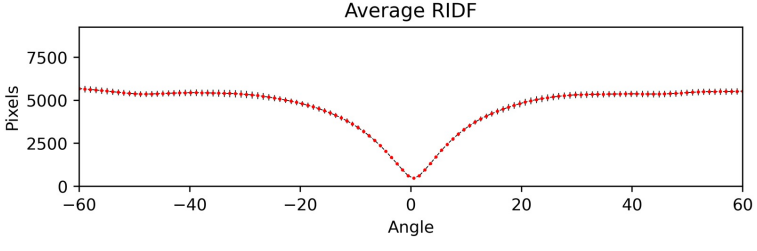
100%







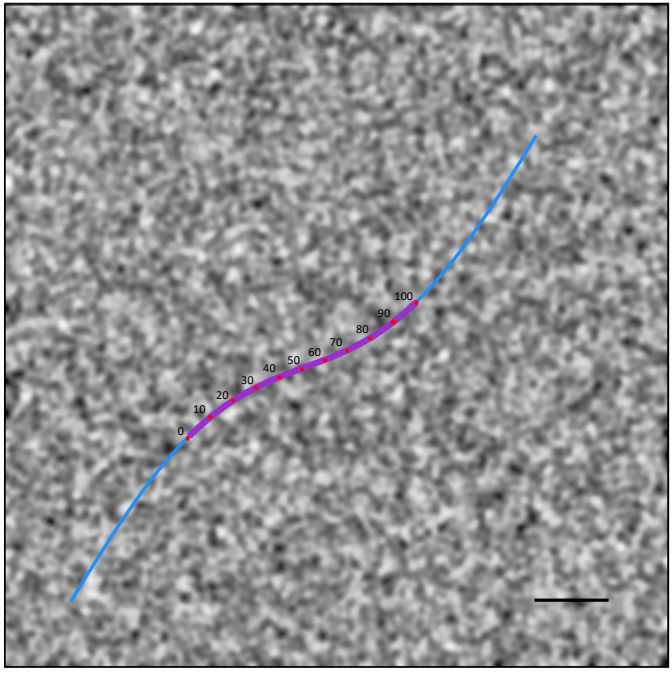


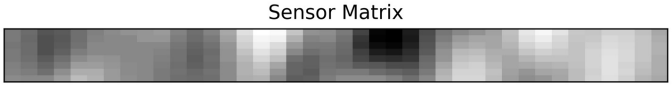


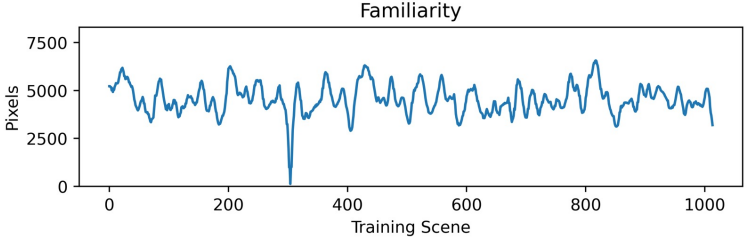
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

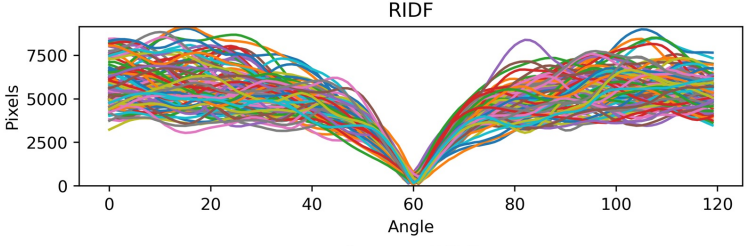
Navigation stats: RMSD error: 62.27; RMSD/dist: 0.156; TD: 4020; p90: 28; p50: 12; complete: 0

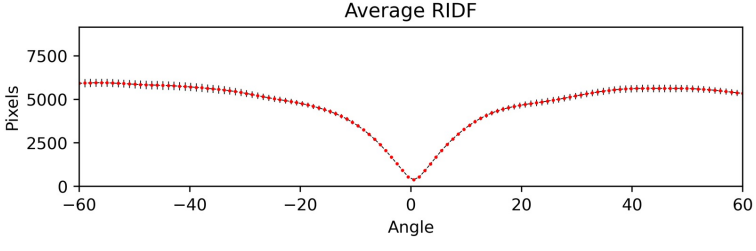
100%







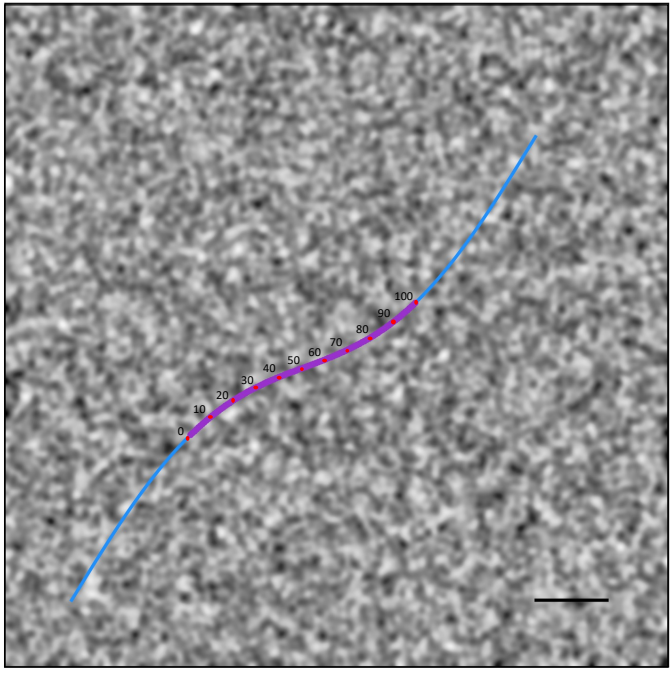


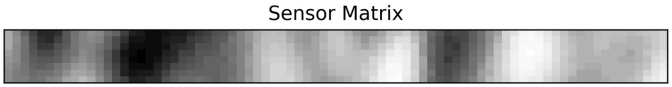


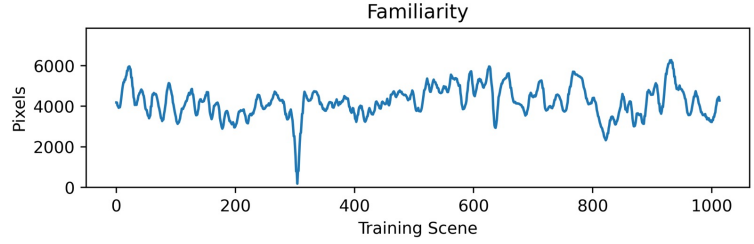
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

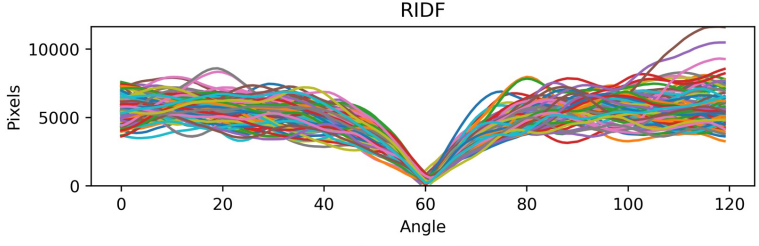
Navigation stats: RMSD error: 37.27; RMSD/dist: 0.093; TD: 4166; p90: 28; p50: 12; complete: 0

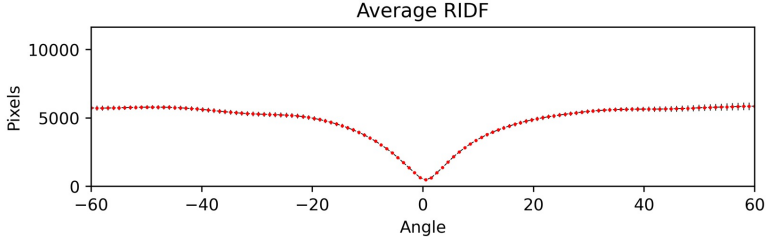
100%











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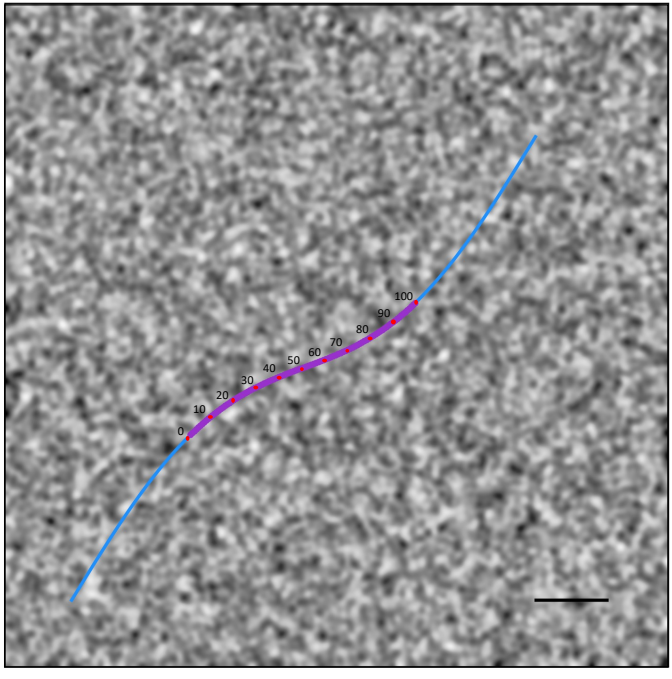
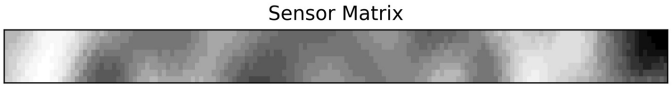
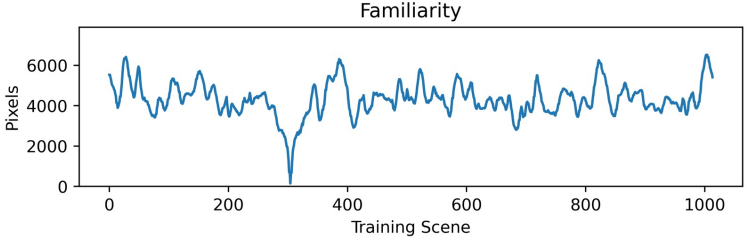
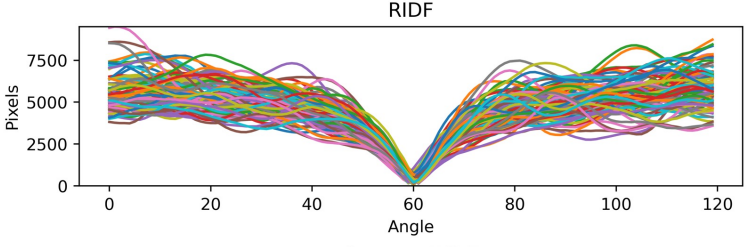
Navigation stats: RMSD error: 52.91; RMSD/dist: 0.132; TD: 4062; p90: 26; p50: 12; complete: 0

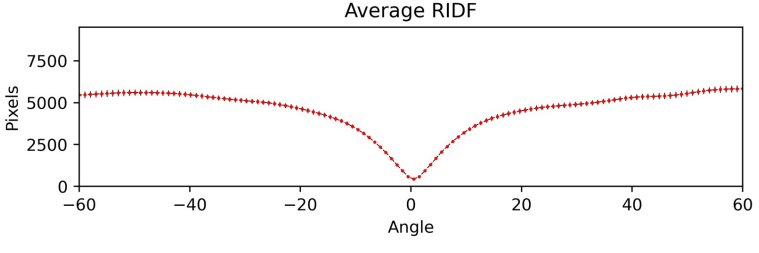
100%





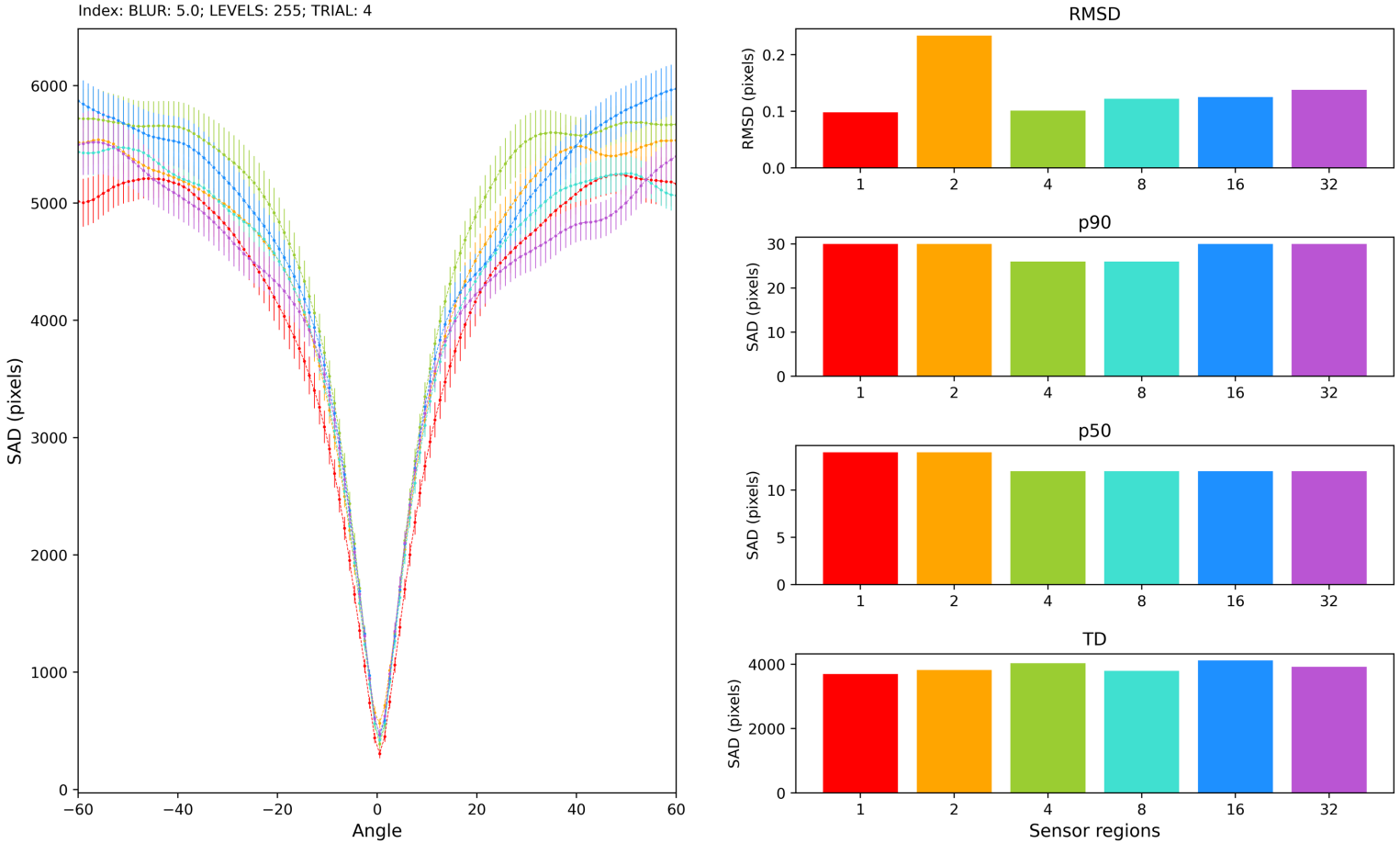




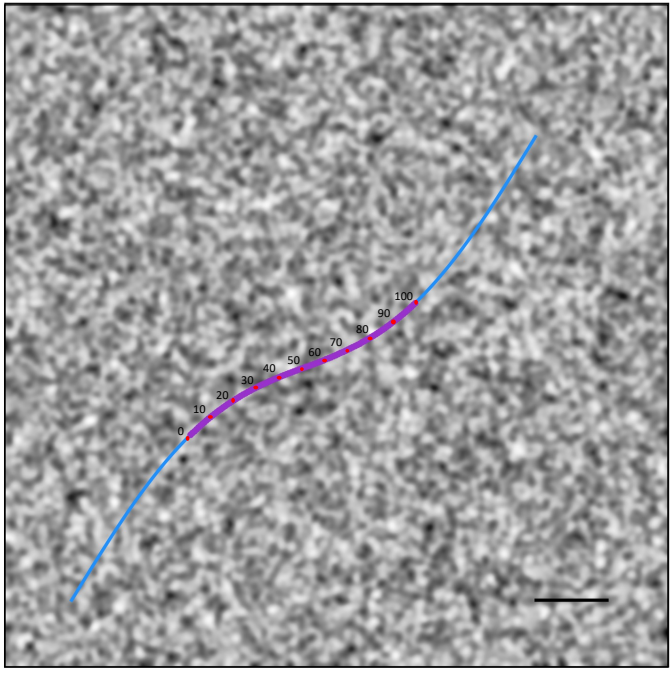


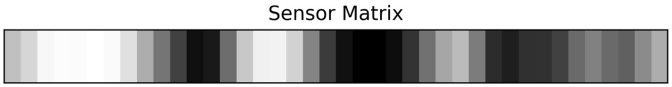
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

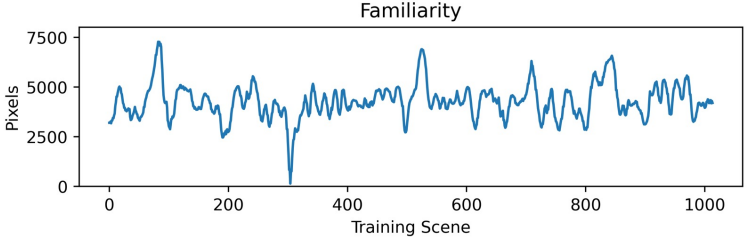
Navigation stats: RMSD error: 45.17; RMSD/dist: 0.113; TD: 4045; p90: 28; p50: 12; complete: 0

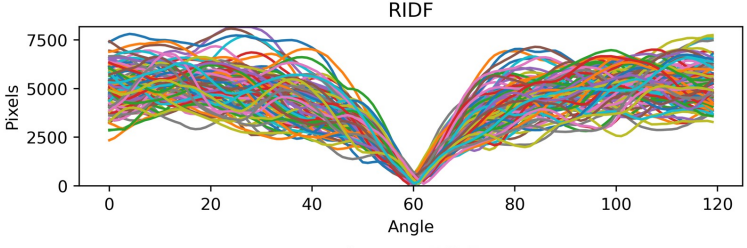

Index: BLUR: 5.0; LEVELS: 255; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

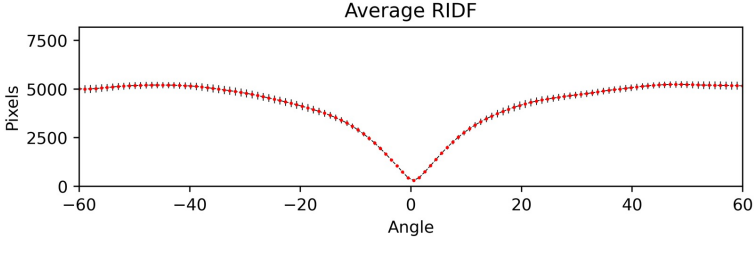
100%







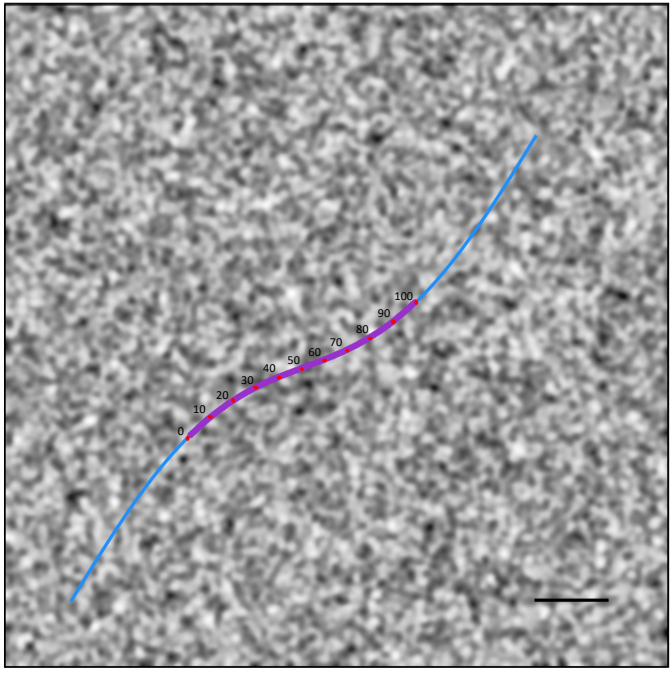


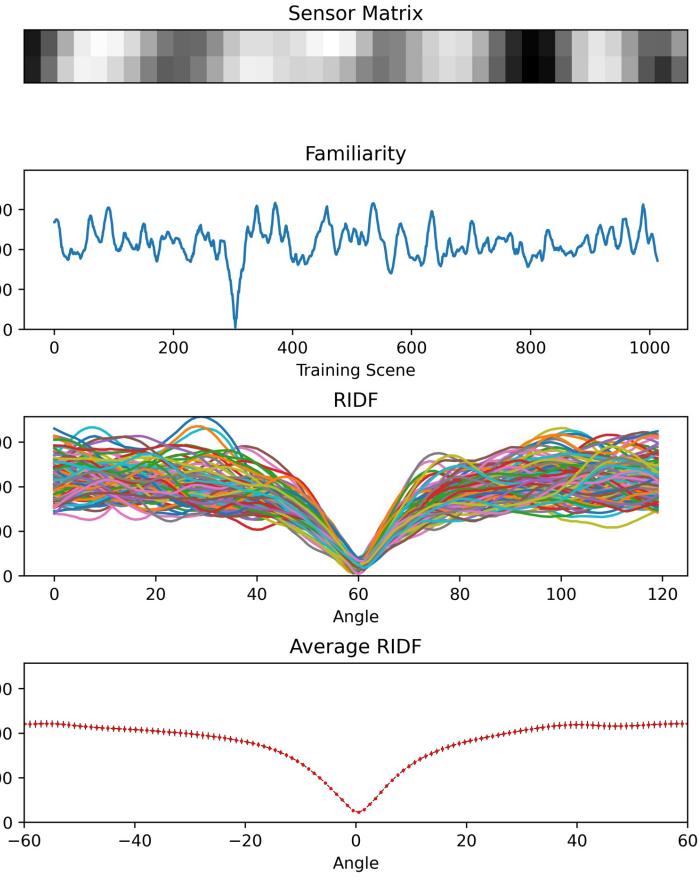


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 39.09; RMSD/dist: 0.098; TD: 3699; p90: 30; p50: 14; complete: 0

100%

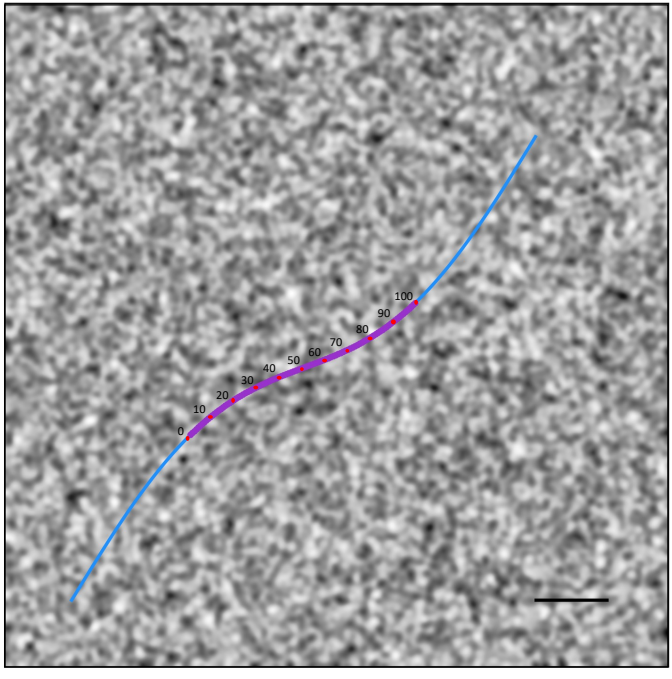


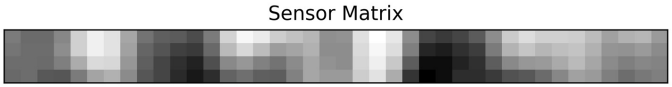


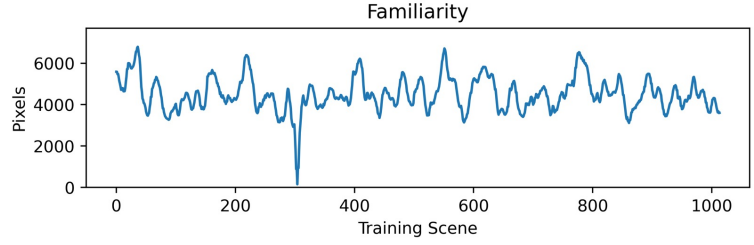
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

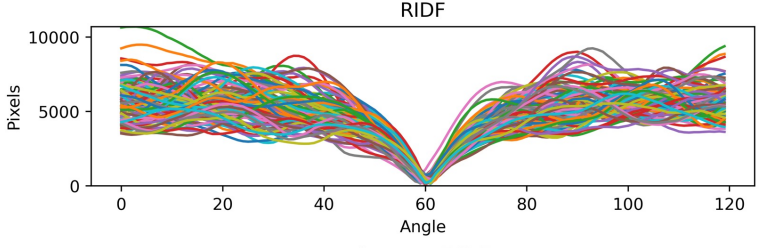
Navigation stats: RMSD error: 93.47; RMSD/dist: 0.234; TD: 3822; p90: 30; p50: 14; complete: 0

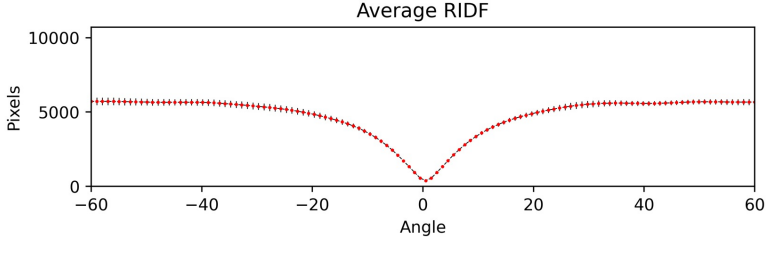
100%







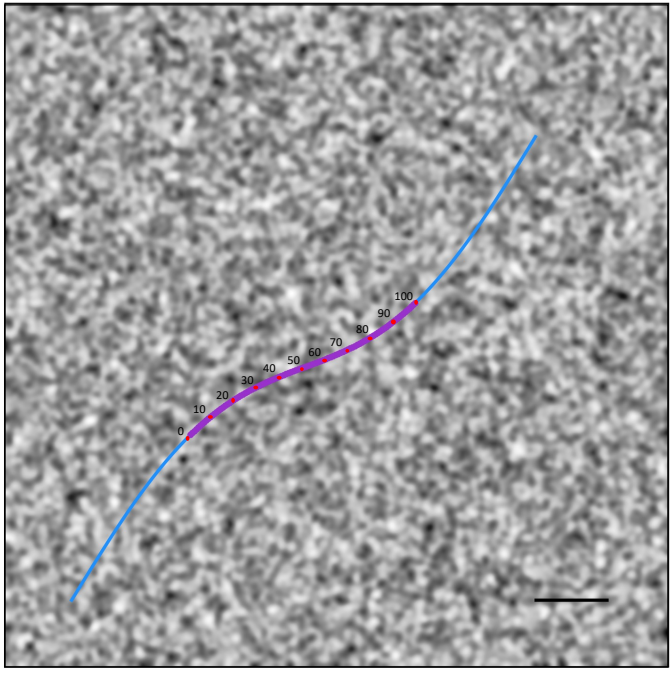


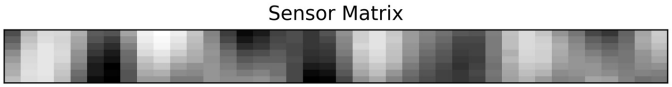


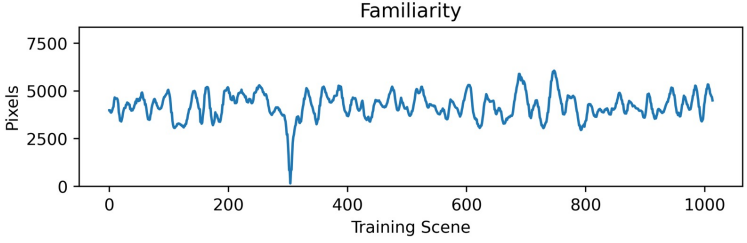
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

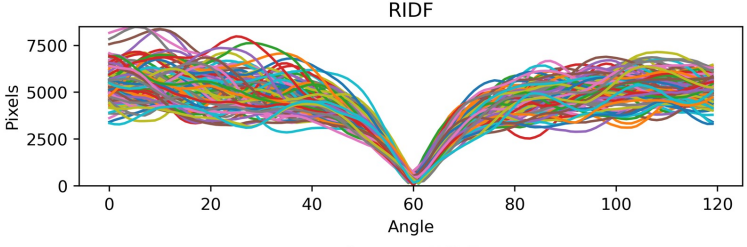
Navigation stats: RMSD error: 40.29; RMSD/dist: 0.101; TD: 4033; p90: 26; p50: 12; complete: 0

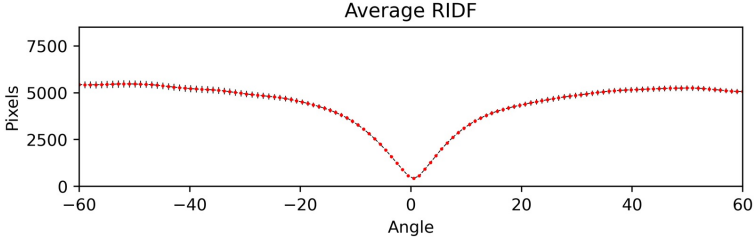
100%







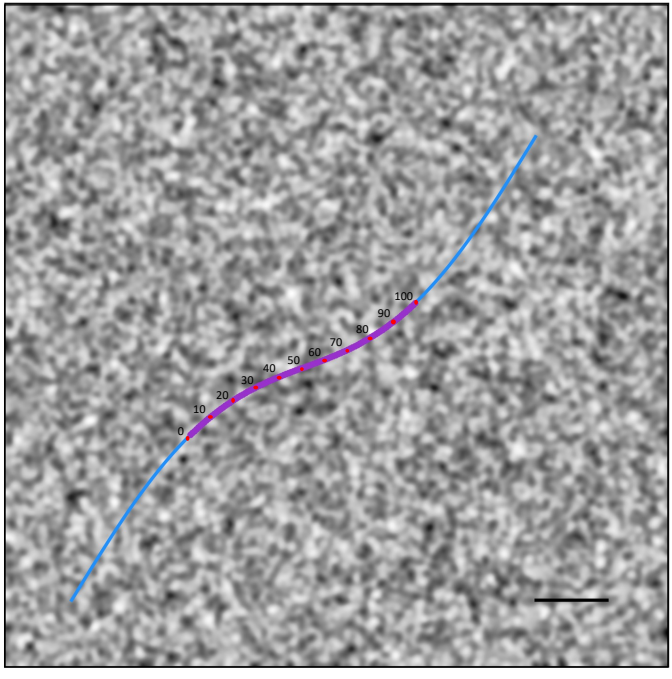


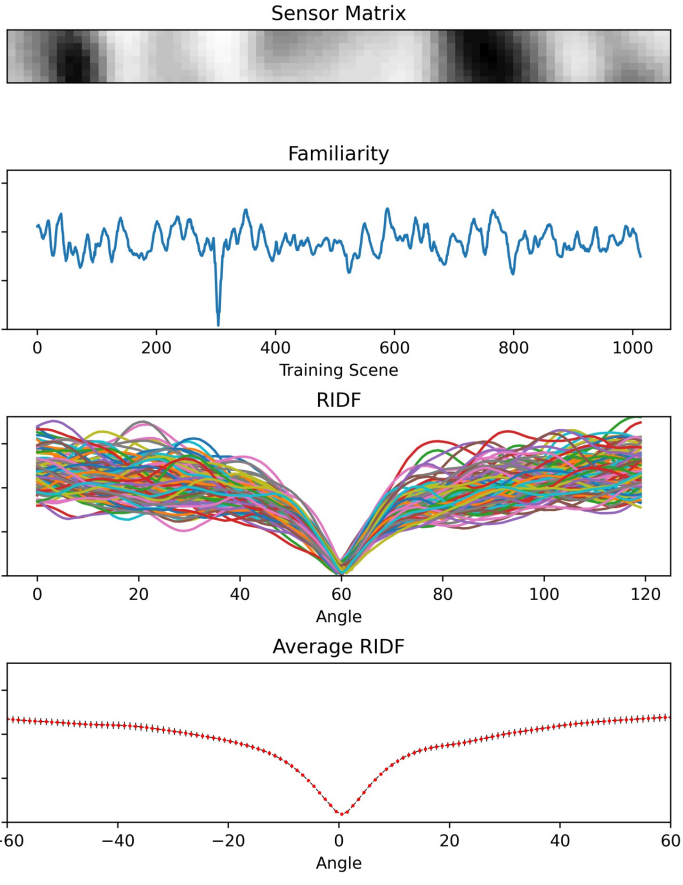


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 48.80; RMSD/dist: 0.122; TD: 3792; p90: 26; p50: 12; complete: 0

100%

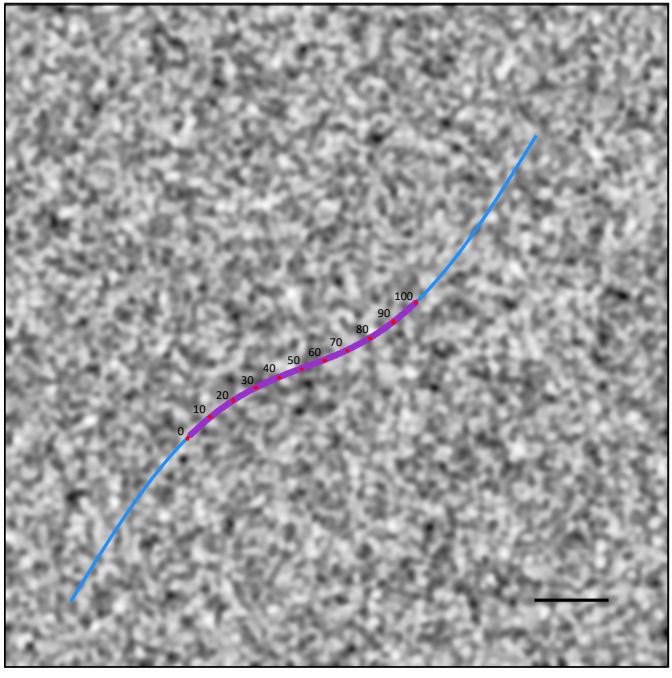


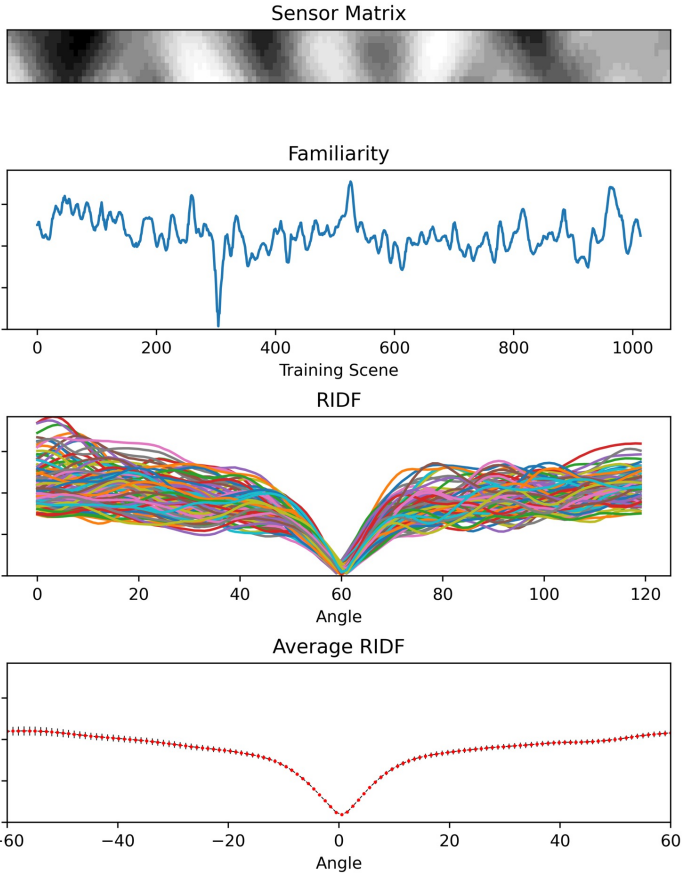


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 49.83; RMSD/dist: 0.125; TD: 4115; p90: 30; p50: 12; complete: 0

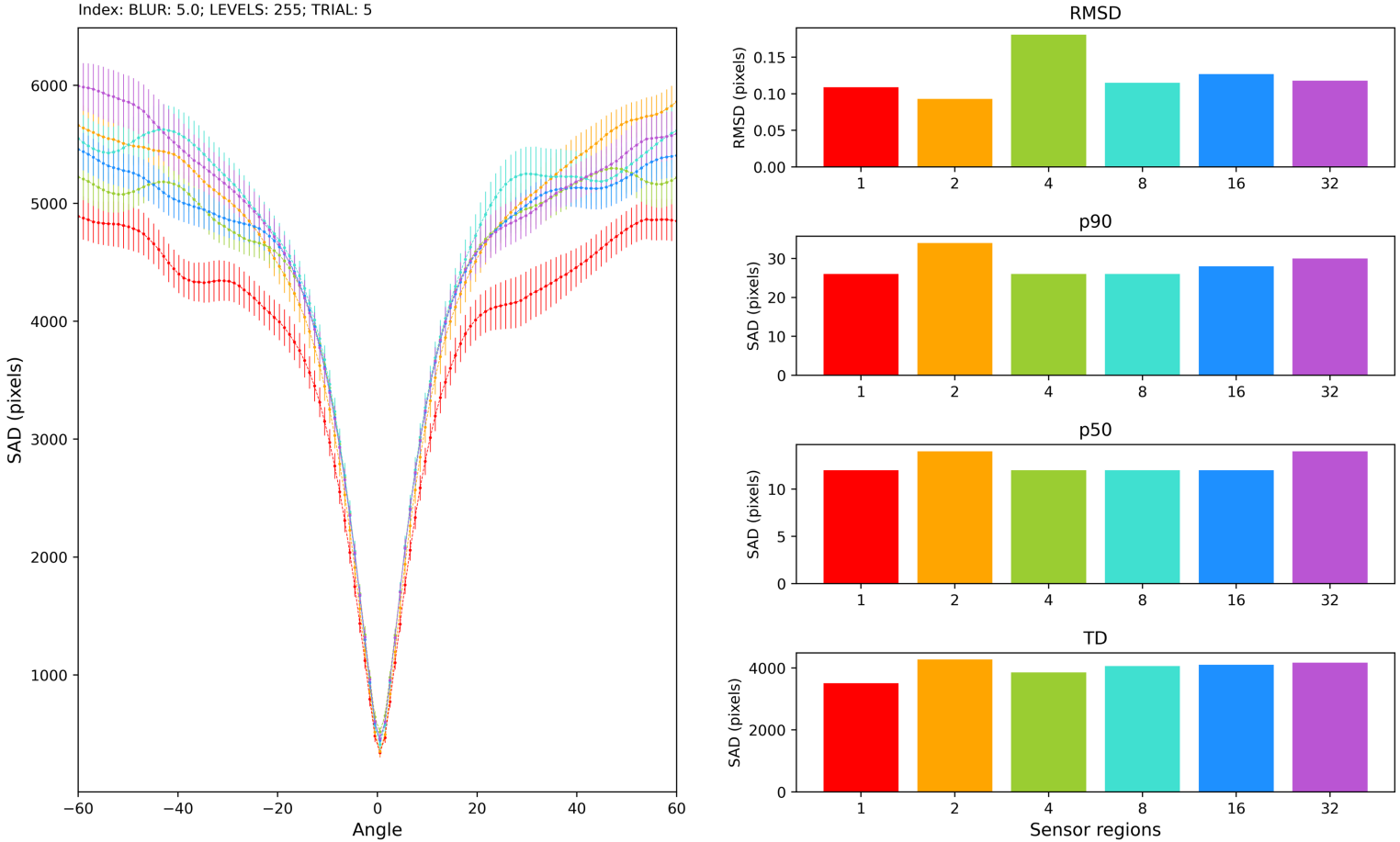
100%



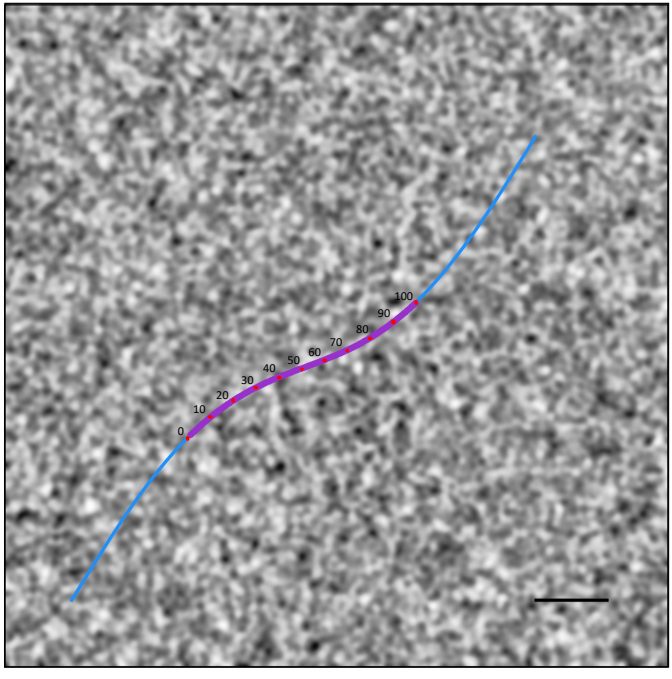


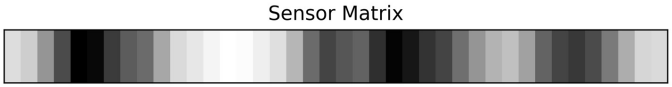
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

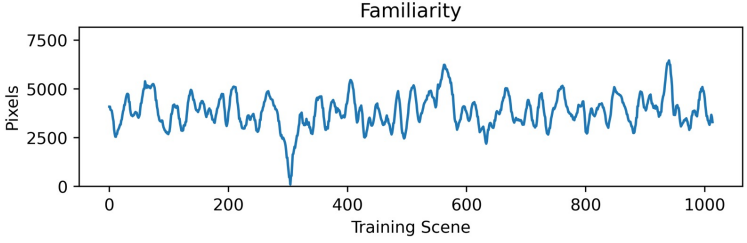
Navigation stats: RMSD error: 55.17; RMSD/dist: 0.138; TD: 3921; p90: 30; p50: 12; complete: 0

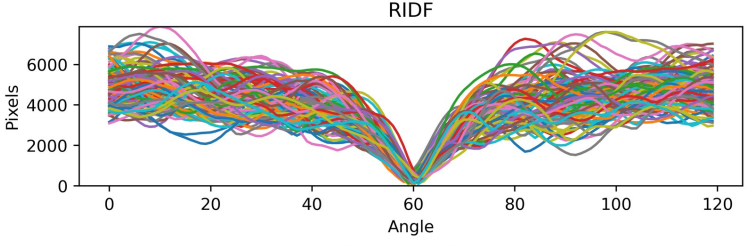

Index: BLUR: 5.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

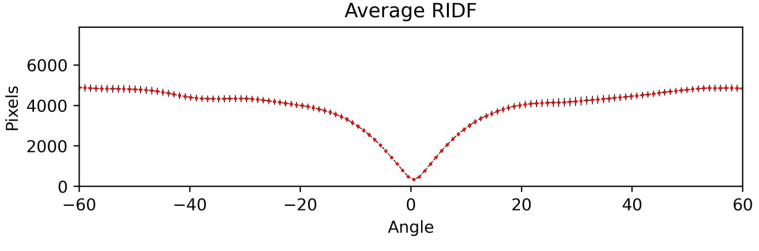
100%







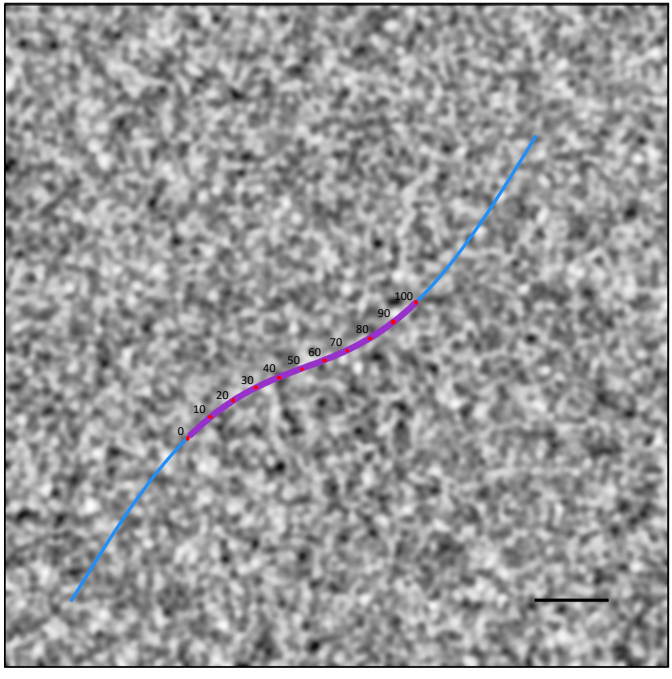


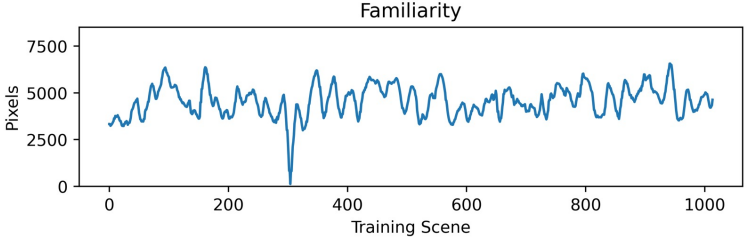


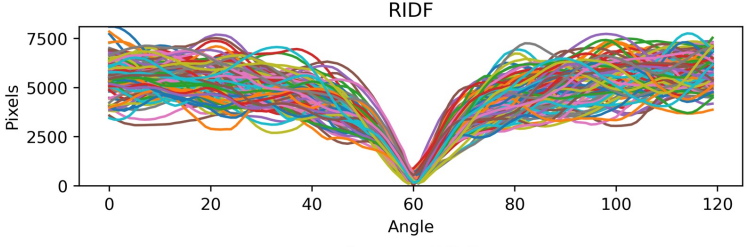
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

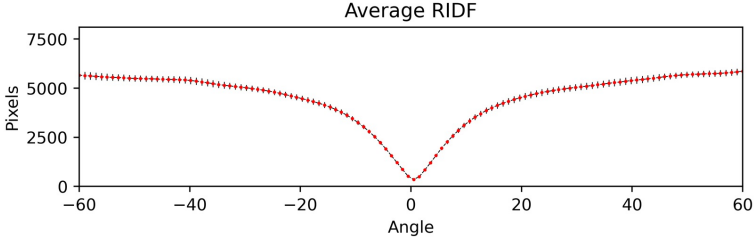
Navigation stats: RMSD error: 43.47; RMSD/dist: 0.109; TD: 3508; p90: 26; p50: 12; complete: 0

100%





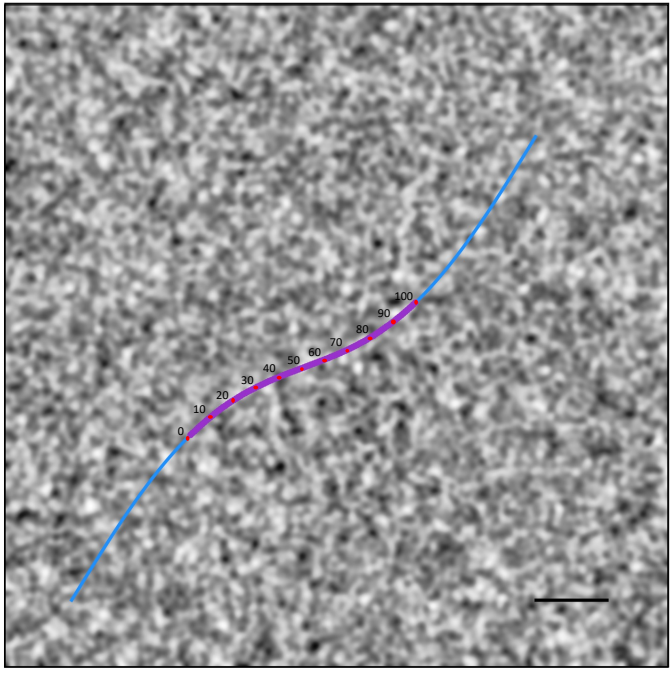


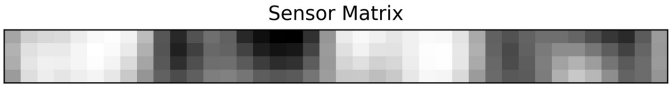


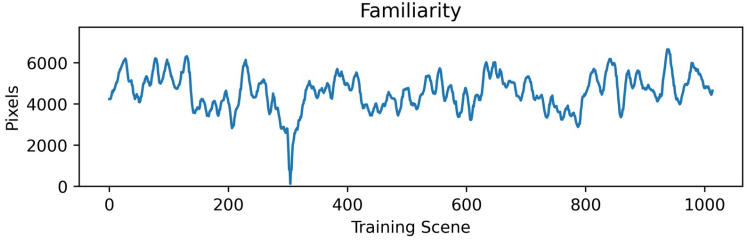
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

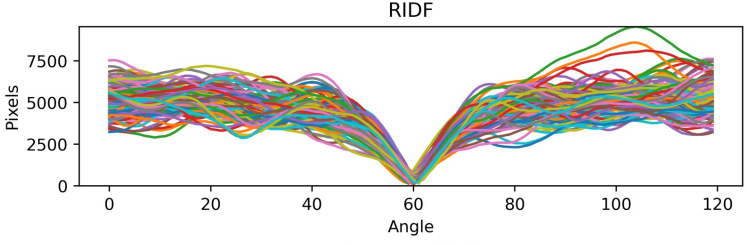
Navigation stats: RMSD error: 37.34; RMSD/dist: 0.093; TD: 4268; p90: 34; p50: 14; complete: 0

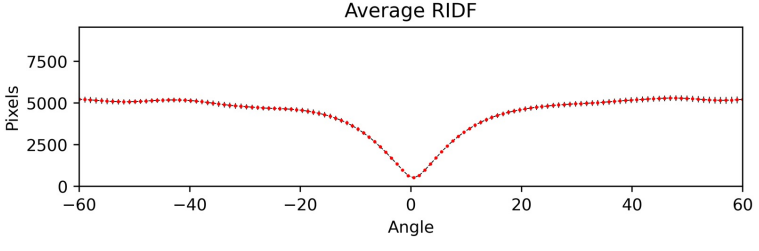
100%







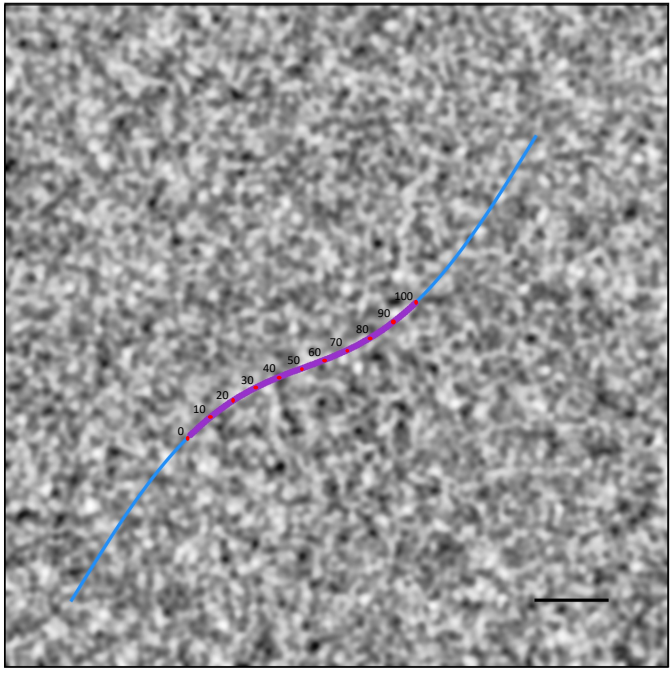


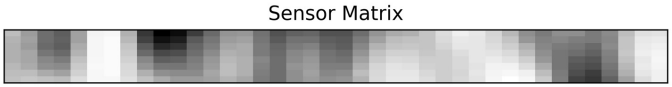


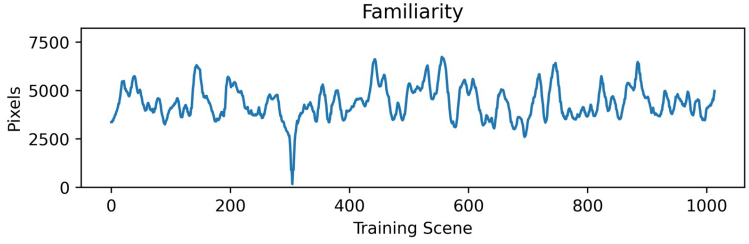
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

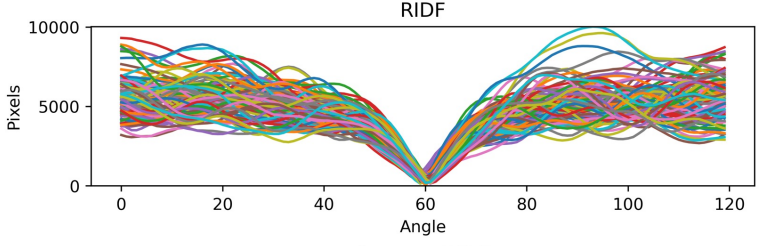
Navigation stats: RMSD error: 72.27; RMSD/dist: 0.181; TD: 3852; p90: 26; p50: 12; complete: 0

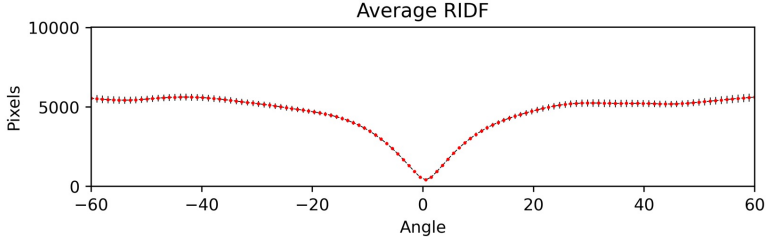
100%







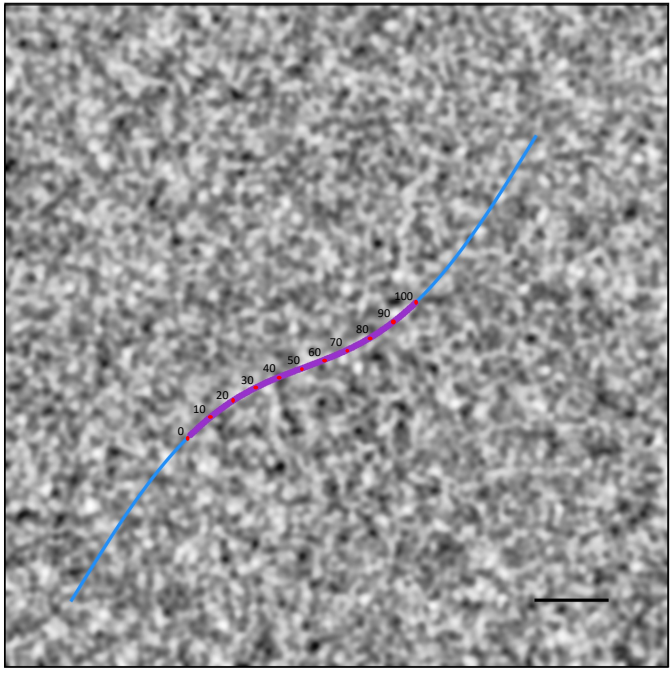


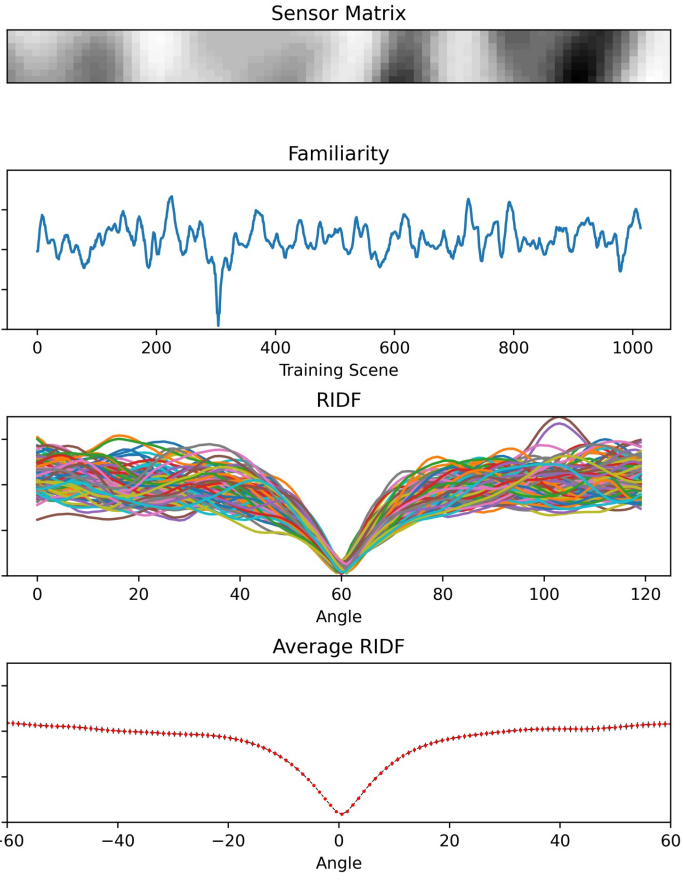


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 46.13; RMSD/dist: 0.115; TD: 4062; p90: 26; p50: 12; complete: 0

100%

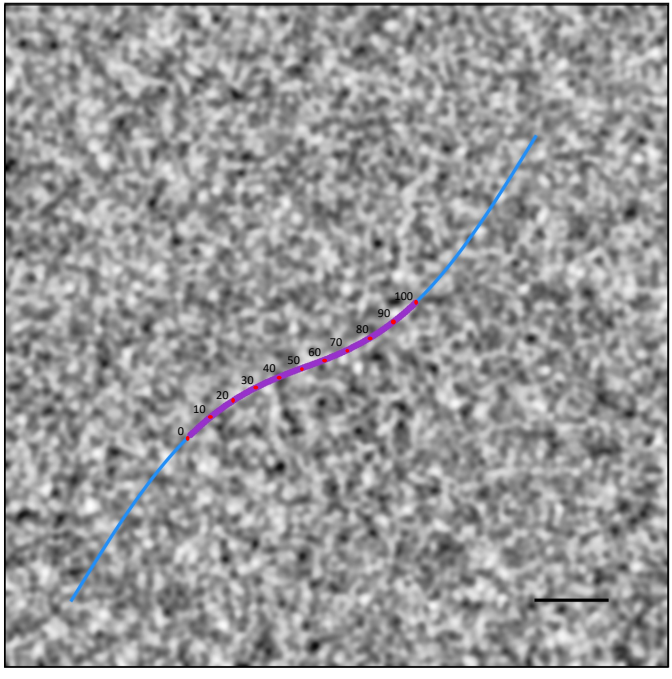


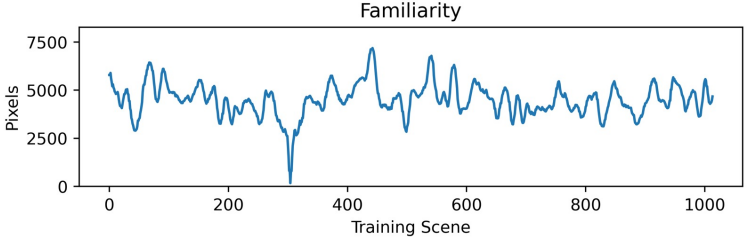


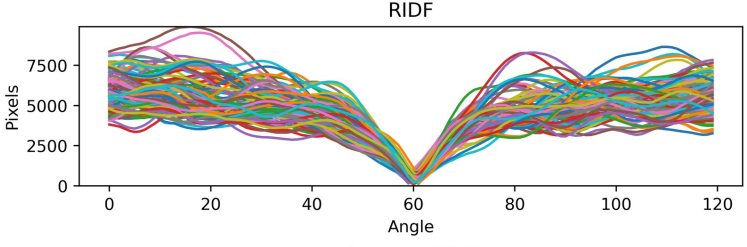
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

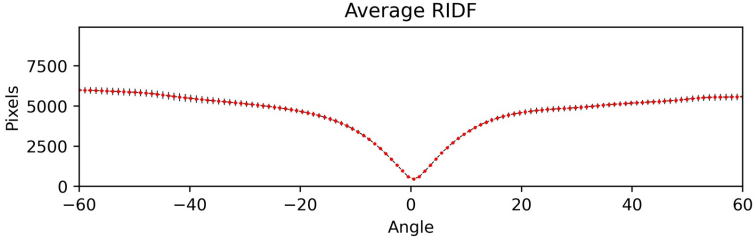
Navigation stats: RMSD error: 50.79; RMSD/dist: 0.127; TD: 4099; p90: 28; p50: 12; complete: 0

100%



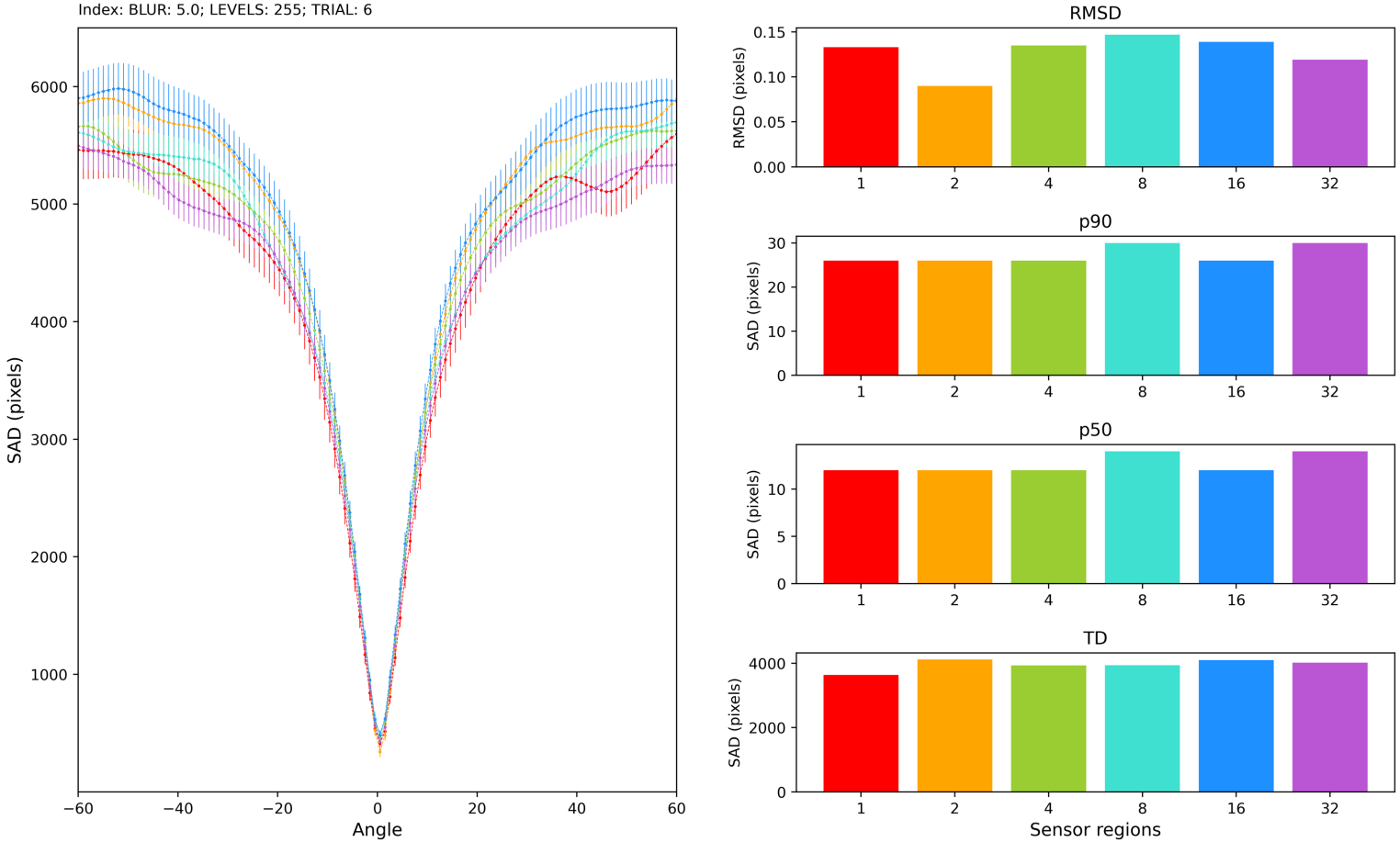




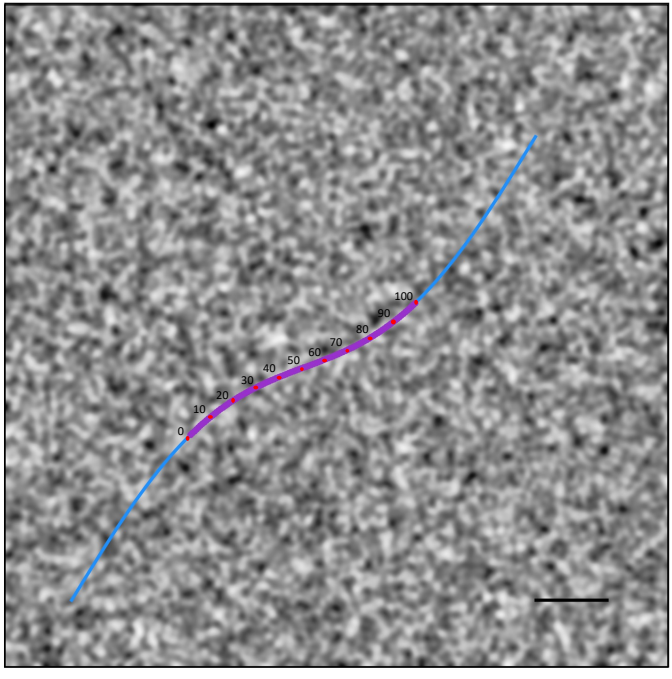


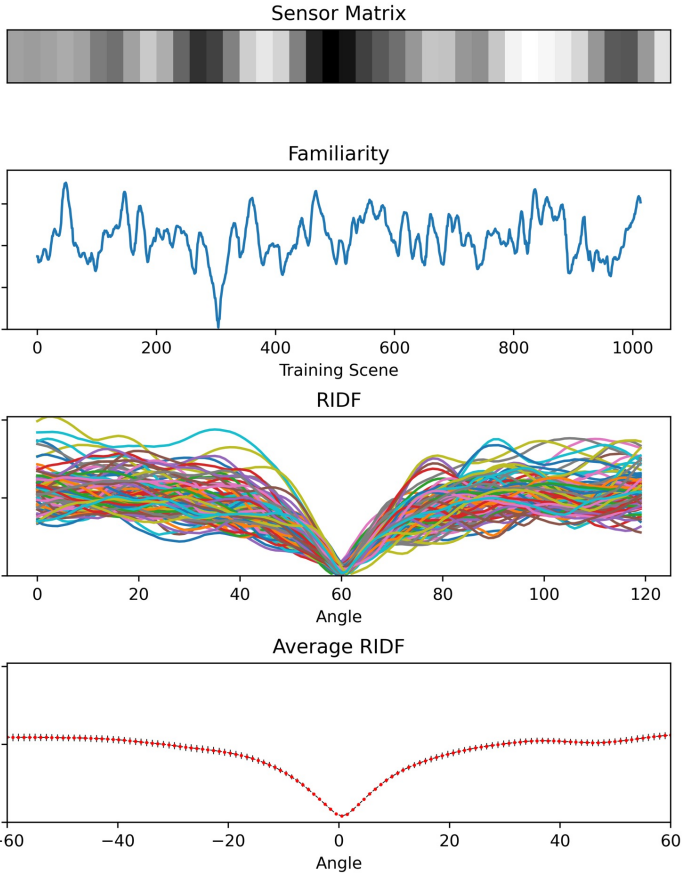
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 47.36; RMSD/dist: 0.118; TD: 4170; p90: 30; p50: 14; complete: 0


Index: BLUR: 5.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

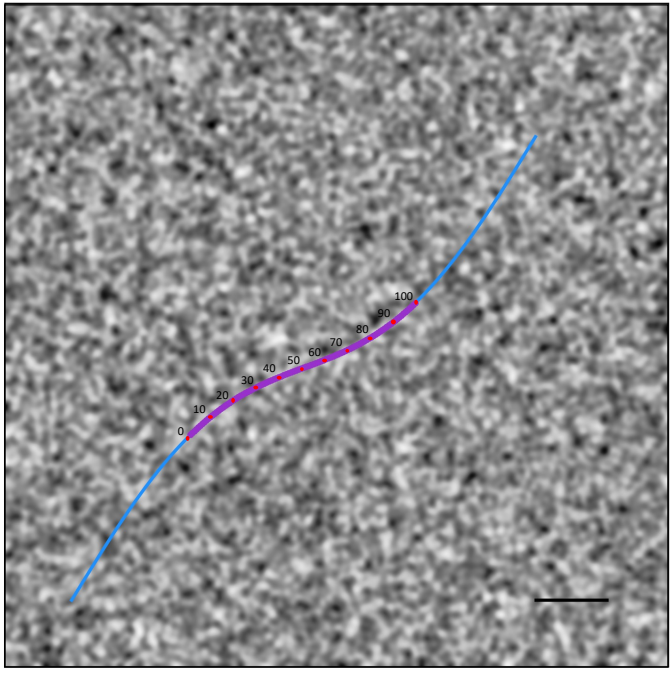


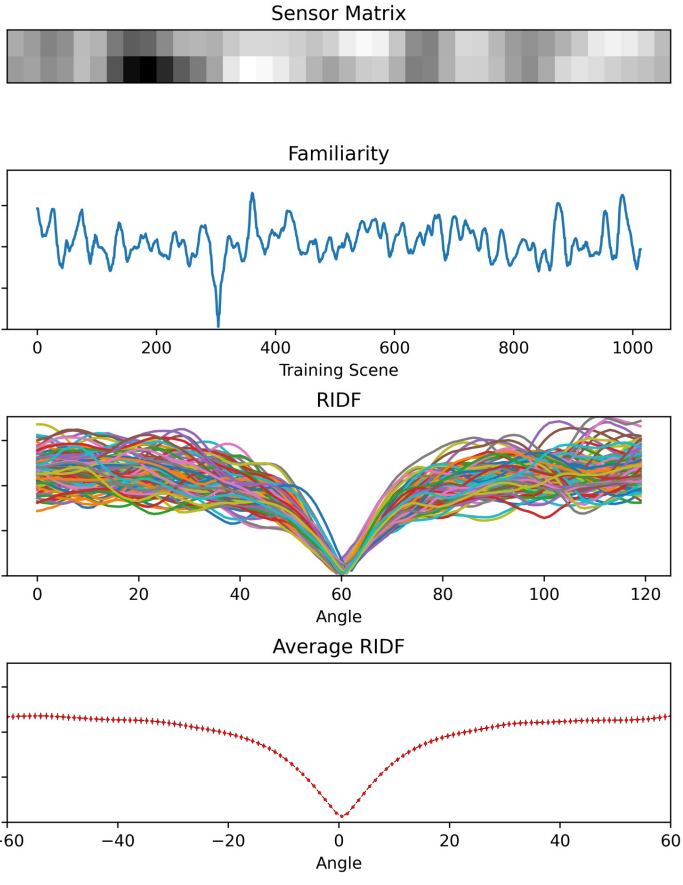


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 53.09; RMSD/dist: 0.133; TD: 3642; p90: 26; p50: 12; complete: 0

100%

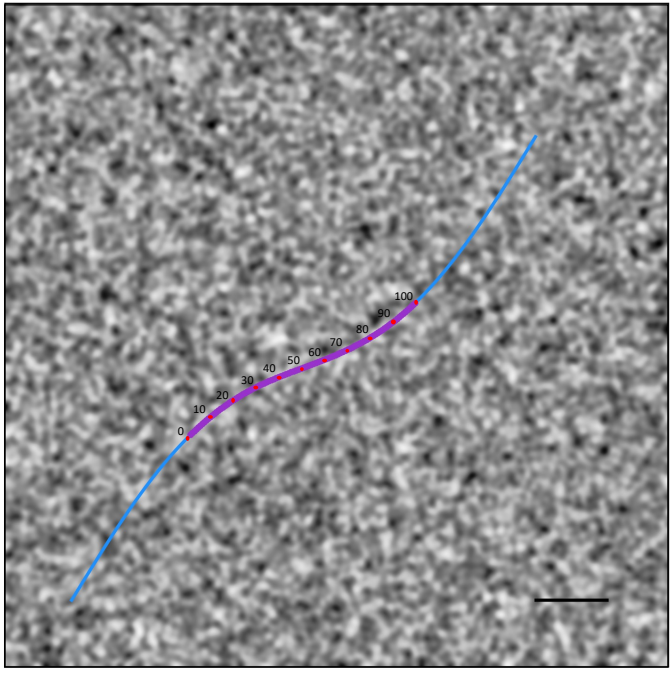


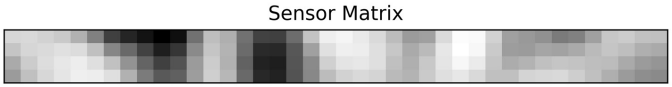


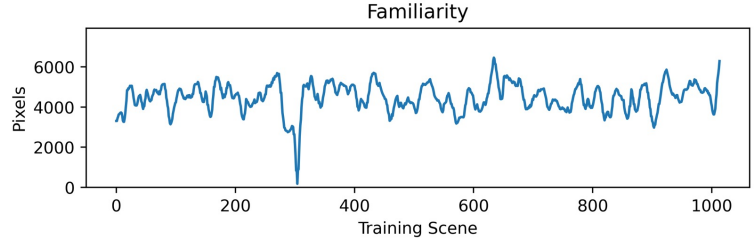
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

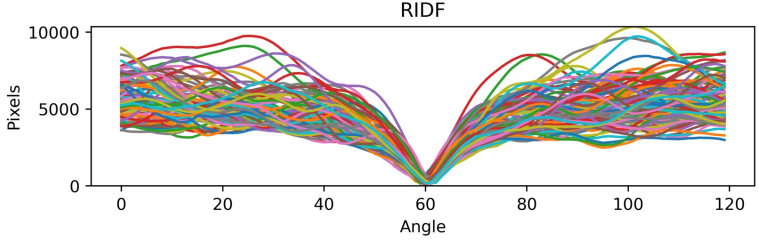
Navigation stats: RMSD error: 35.88; RMSD/dist: 0.090; TD: 4118; p90: 26; p50: 12; complete: 0

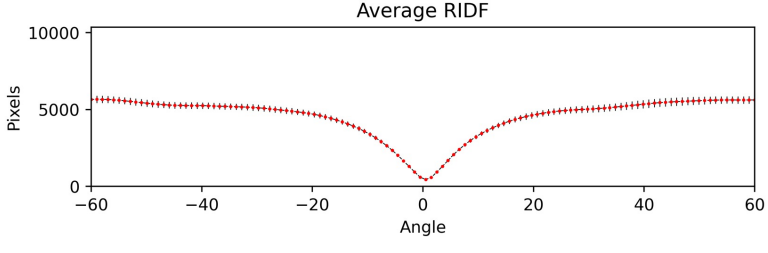
100%







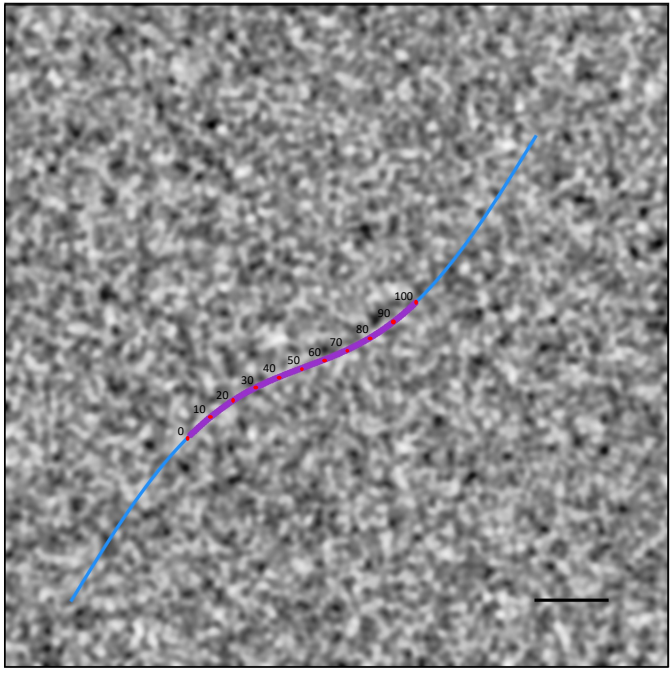


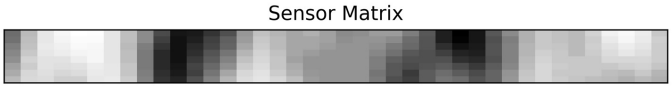


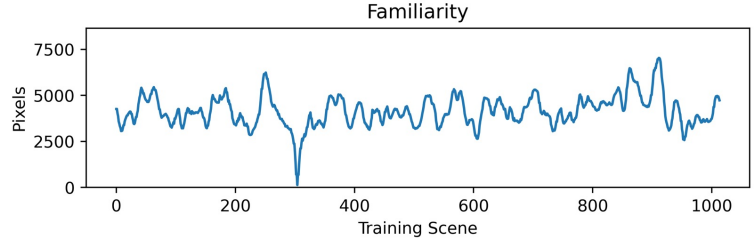
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

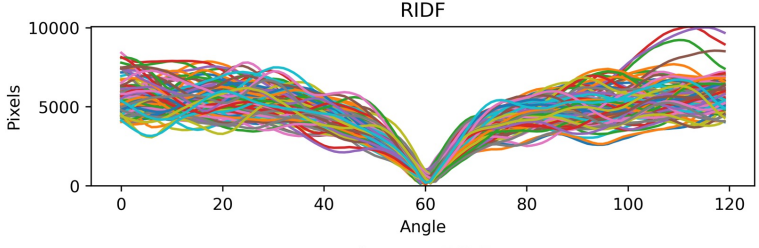
Navigation stats: RMSD error: 53.99; RMSD/dist: 0.135; TD: 3934; p90: 26; p50: 12; complete: 0

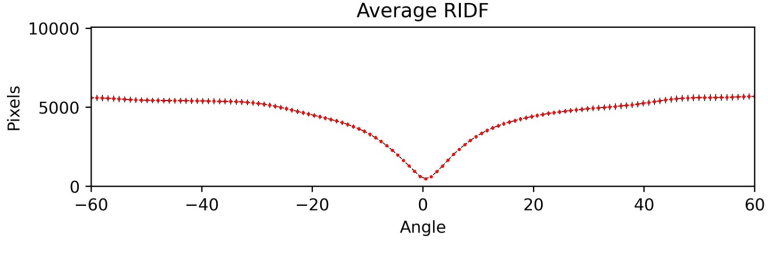
100%







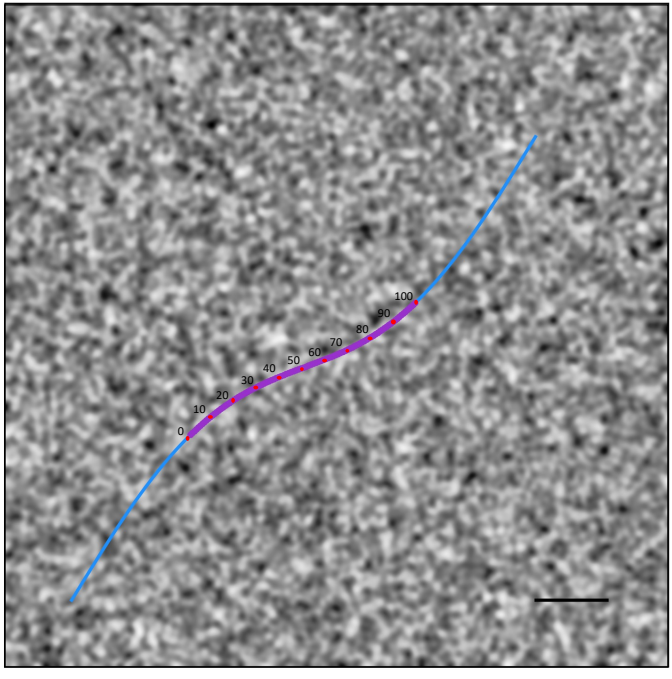


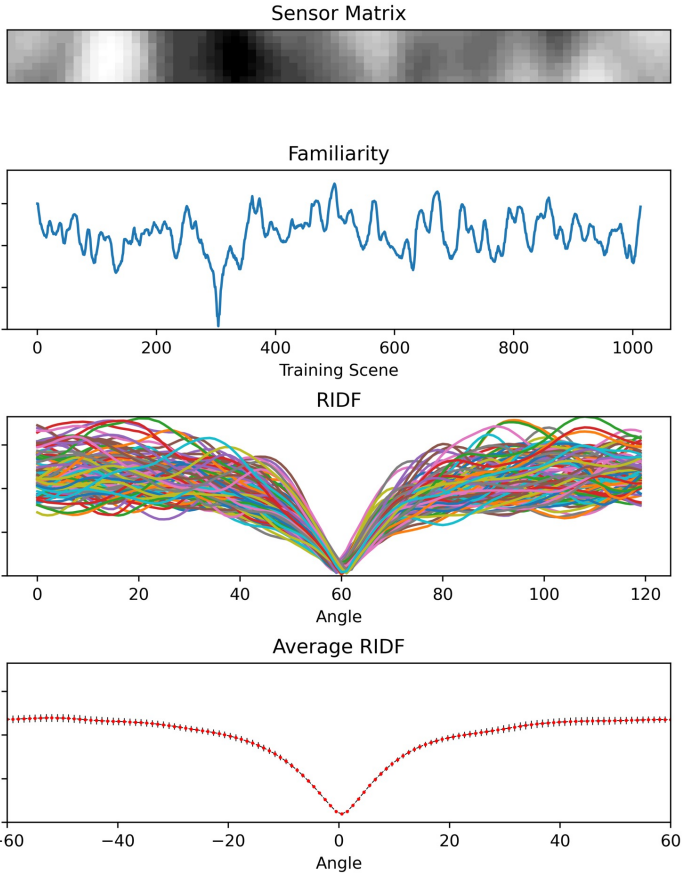


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 58.78; RMSD/dist: 0.147; TD: 3945; p90: 30; p50: 14; complete: 0

100%

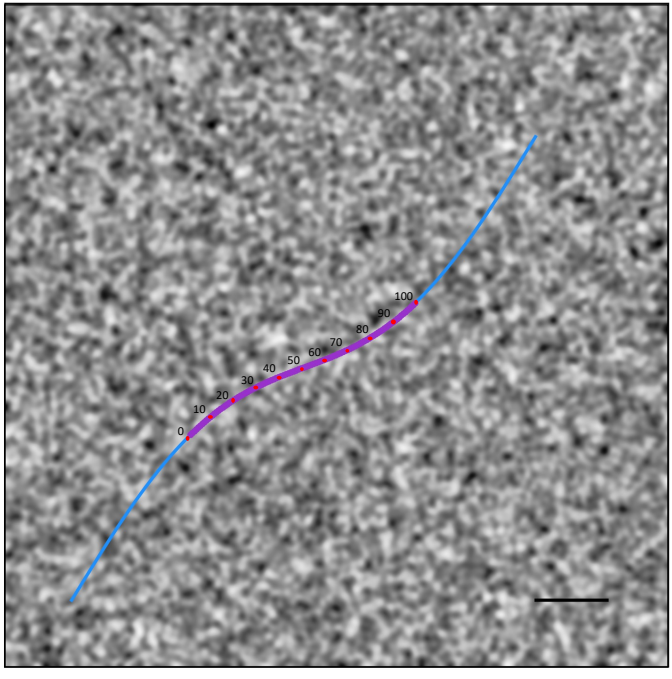


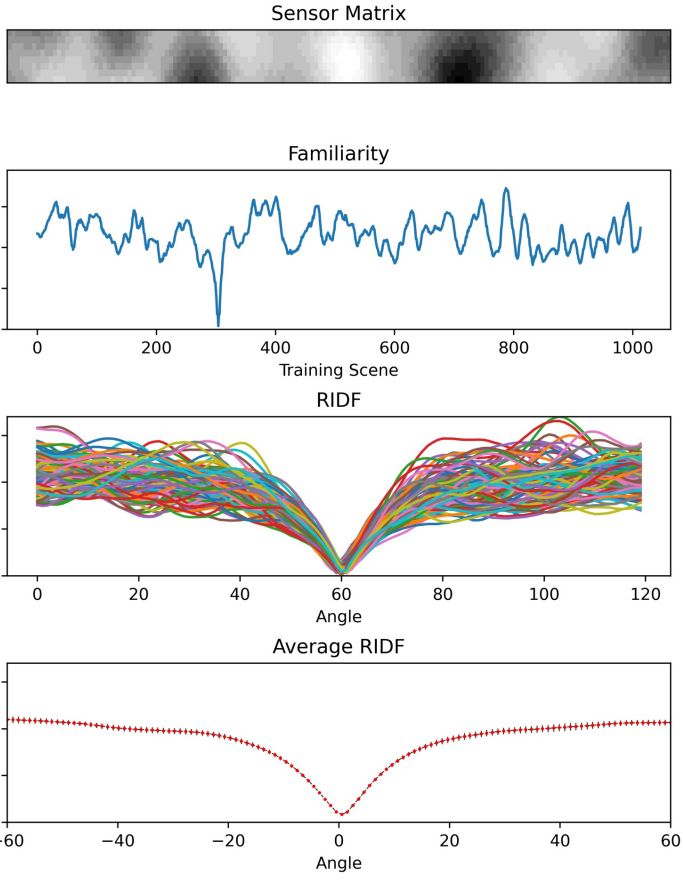


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 55.58; RMSD/dist: 0.139; TD: 4104; p90: 26; p50: 12; complete: 0

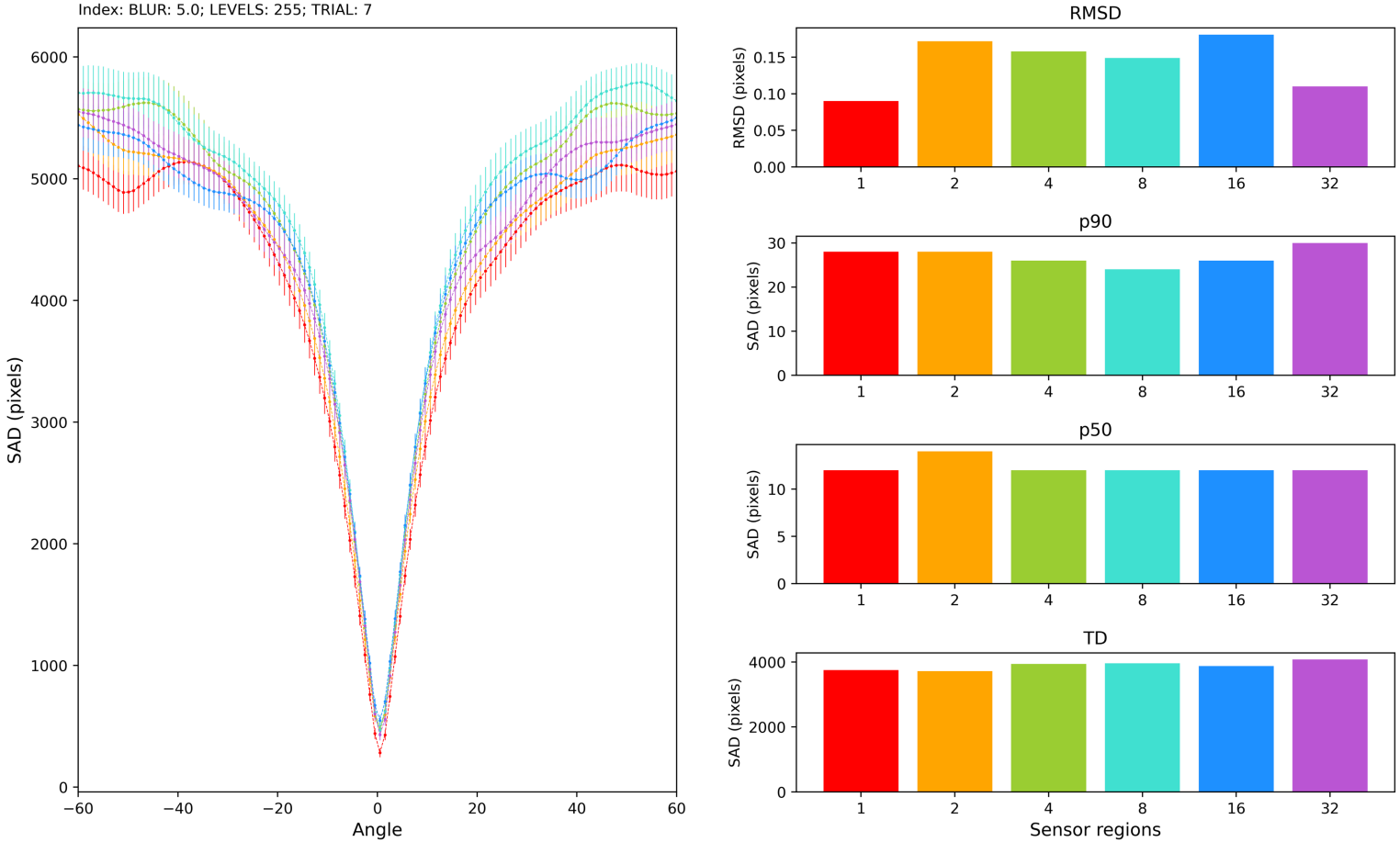
100%



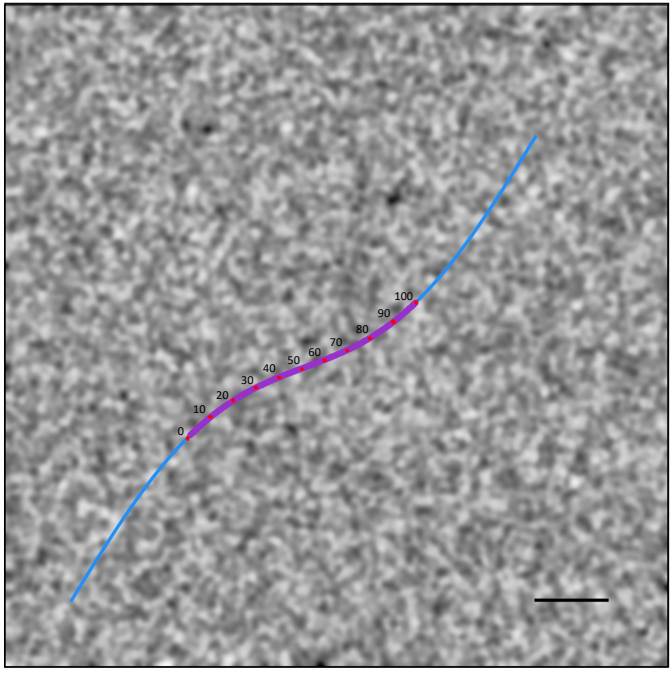


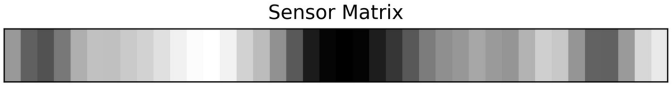
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

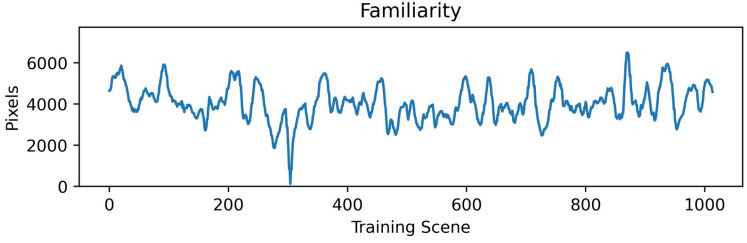
Navigation stats: RMSD error: 47.57; RMSD/dist: 0.119; TD: 4022; p90: 30; p50: 14; complete: 0

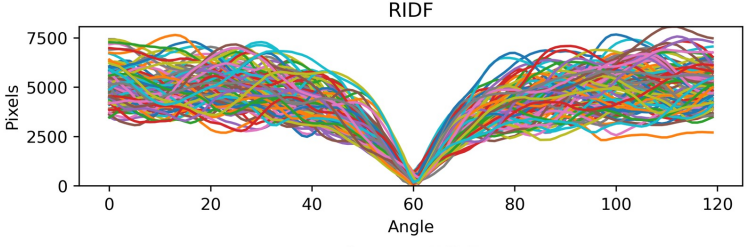

Index: BLUR: 5.0; LEVELS: 255; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

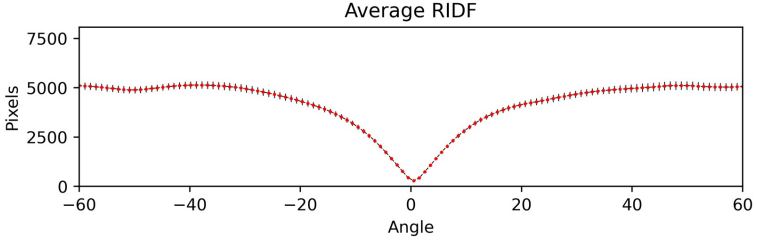
100%







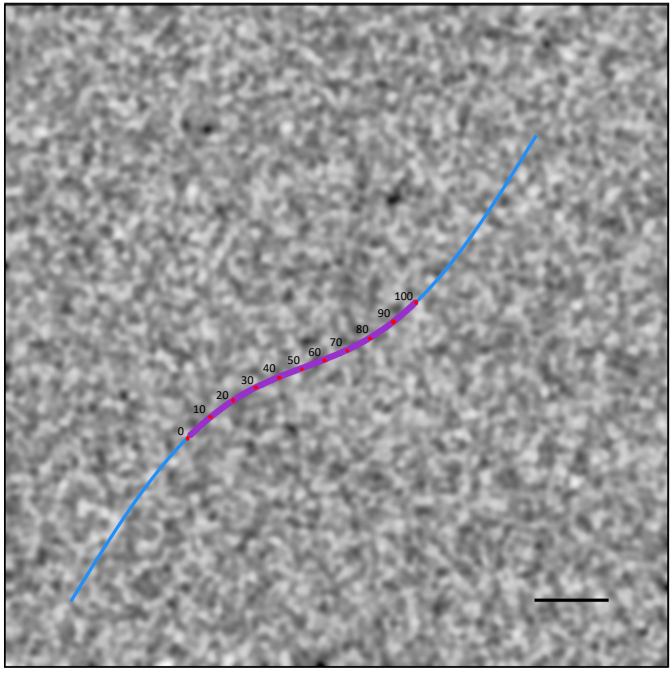


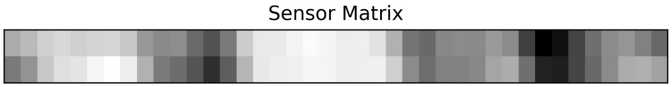


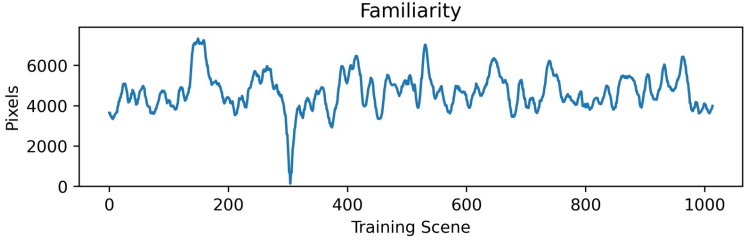
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

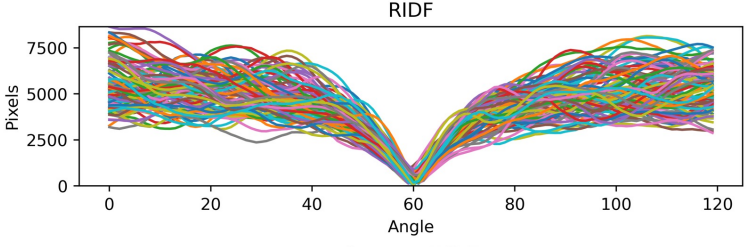
Navigation stats: RMSD error: 35.86; RMSD/dist: 0.090; TD: 3751; p90: 28; p50: 12; complete: 0

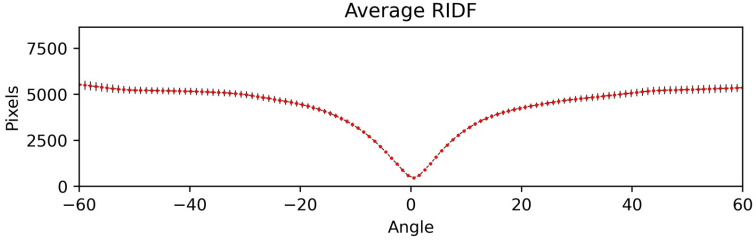
100%







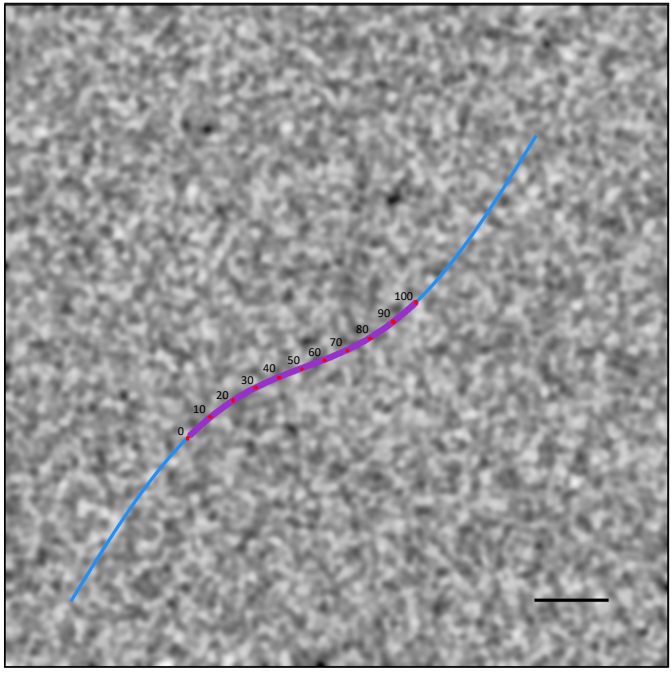


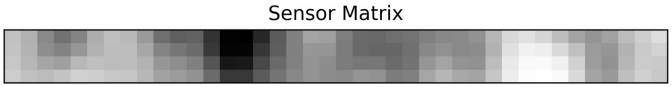


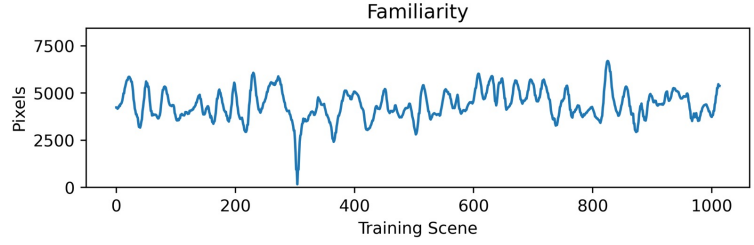
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

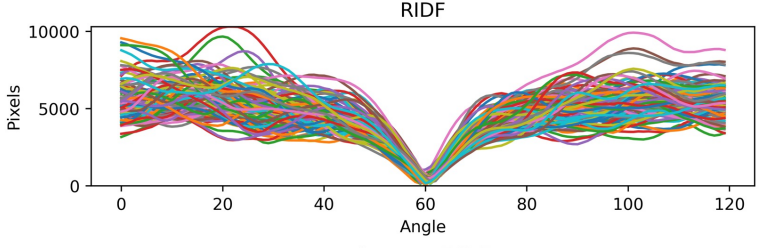
Navigation stats: RMSD error: 68.68; RMSD/dist: 0.172; TD: 3722; p90: 28; p50: 14; complete: 0

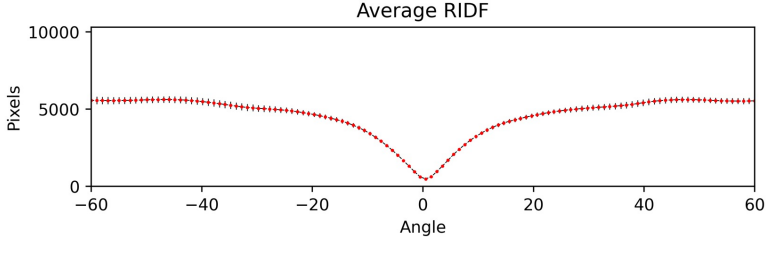
100%







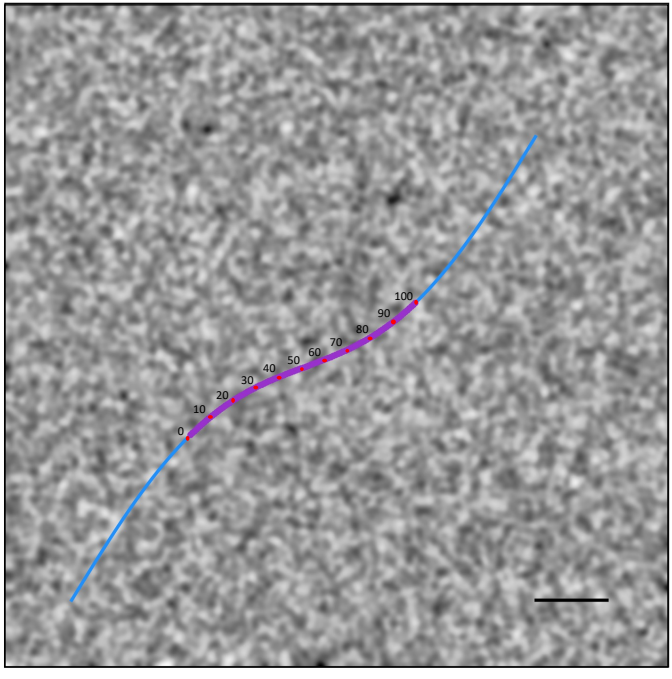


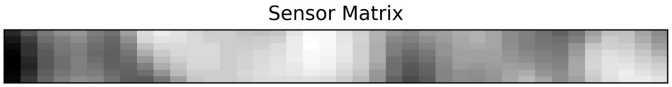


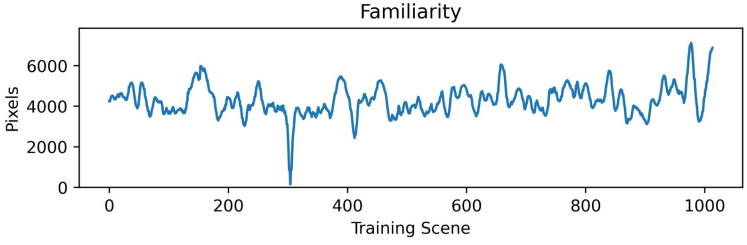
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

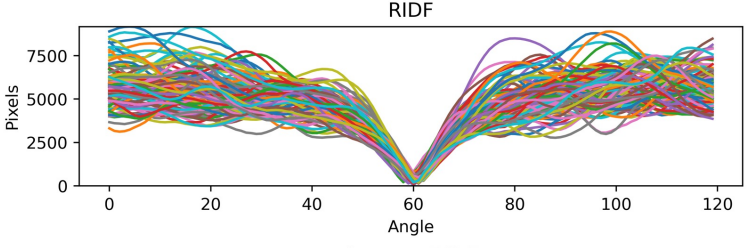
Navigation stats: RMSD error: 63.16; RMSD/dist: 0.158; TD: 3940; p90: 26; p50: 12; complete: 0

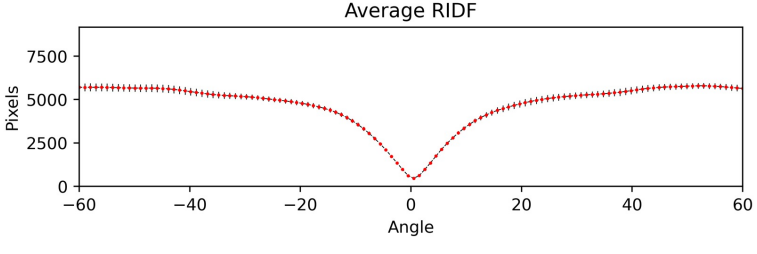
100%







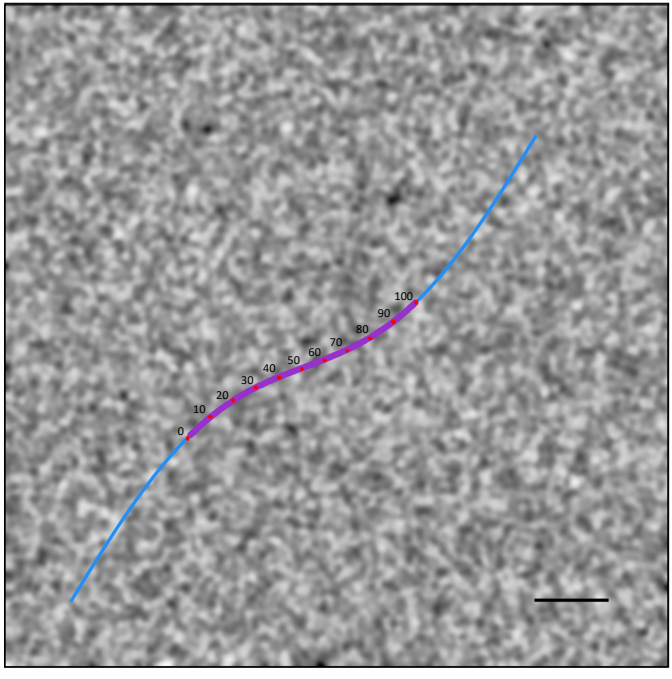


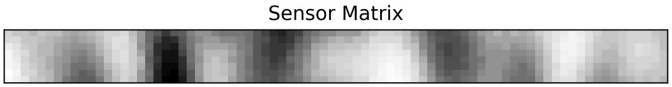


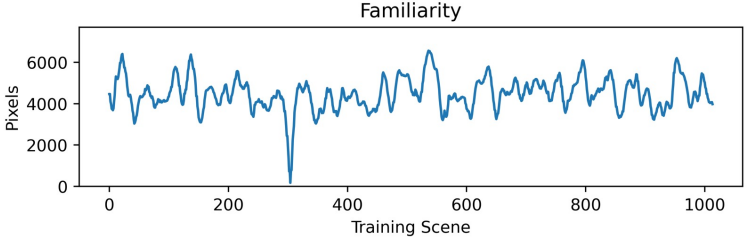
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

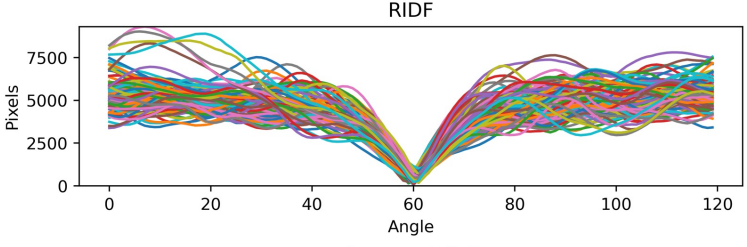
Navigation stats: RMSD error: 59.68; RMSD/dist: 0.149; TD: 3961; p90: 24; p50: 12; complete: 0

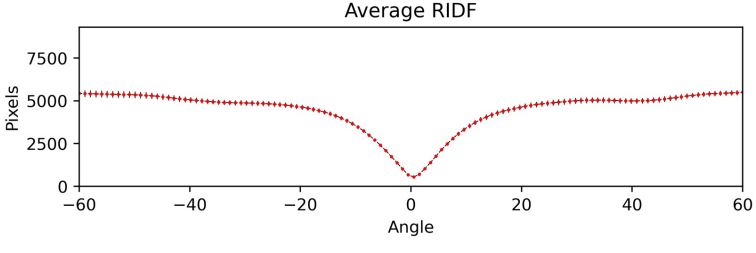
100%







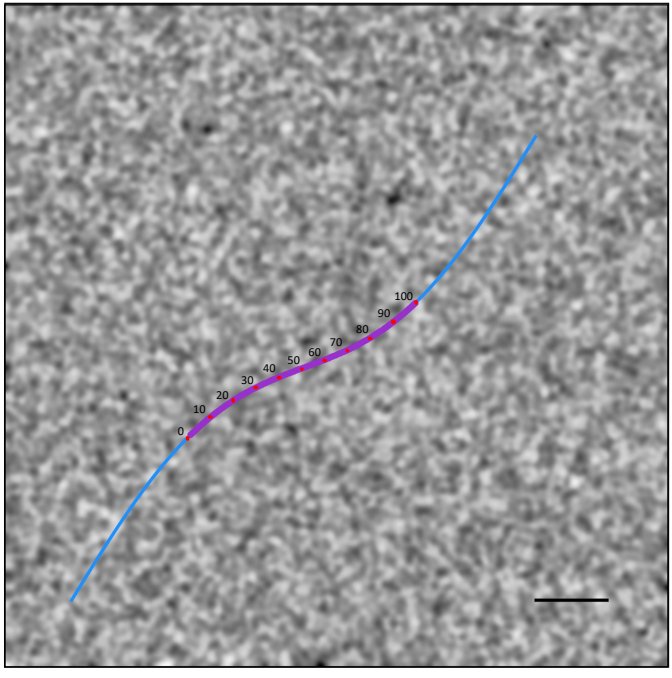


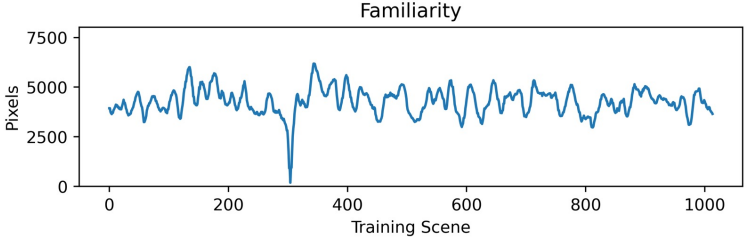


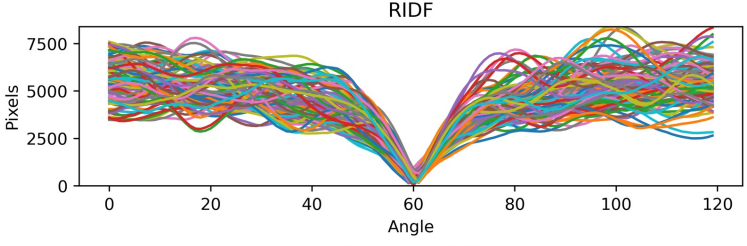
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

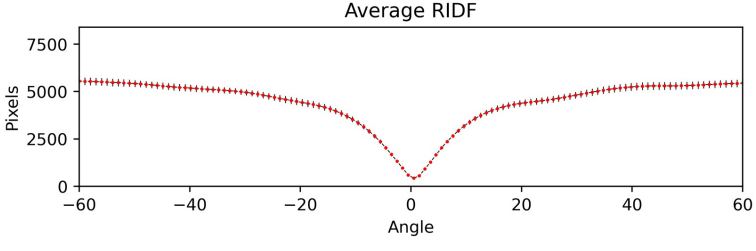
Navigation stats: RMSD error: 72.29; RMSD/dist: 0.181; TD: 3876; p90: 26; p50: 12; complete: 0

100%



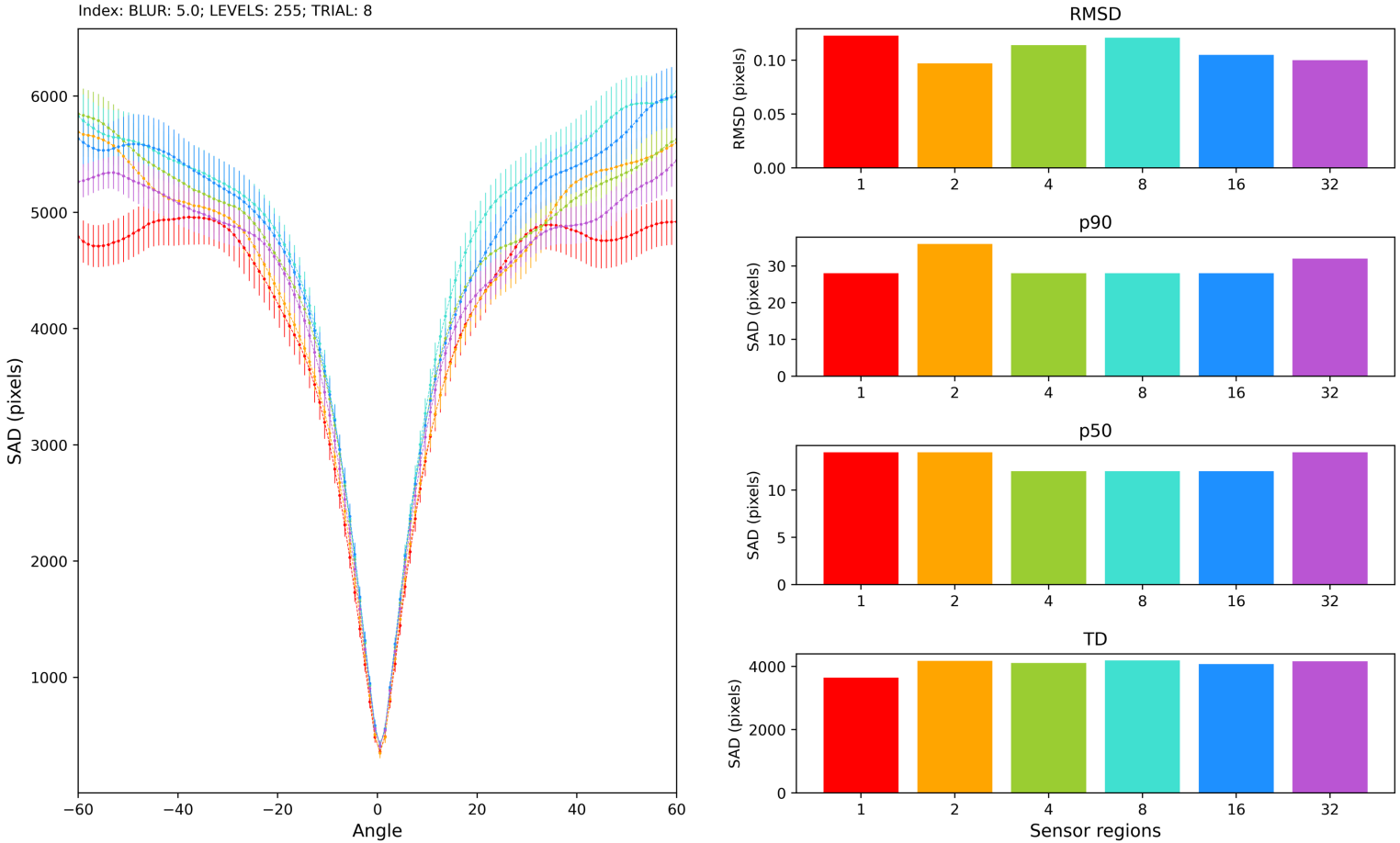




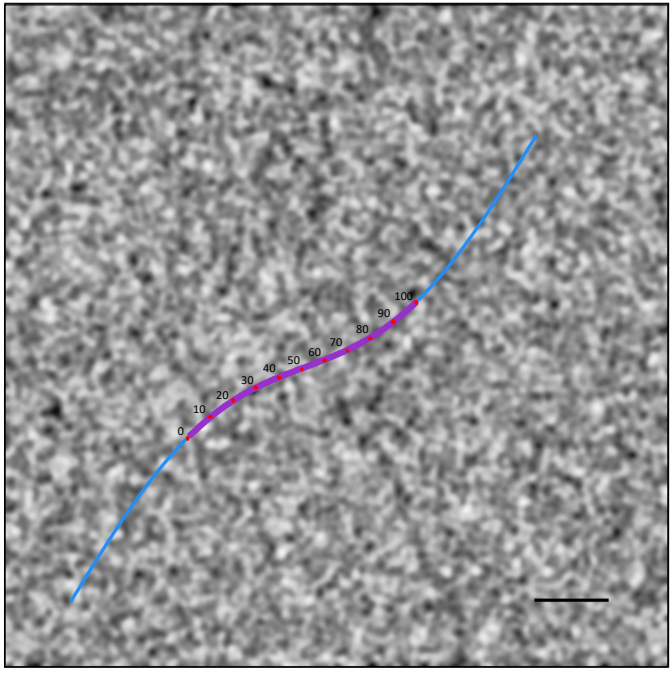


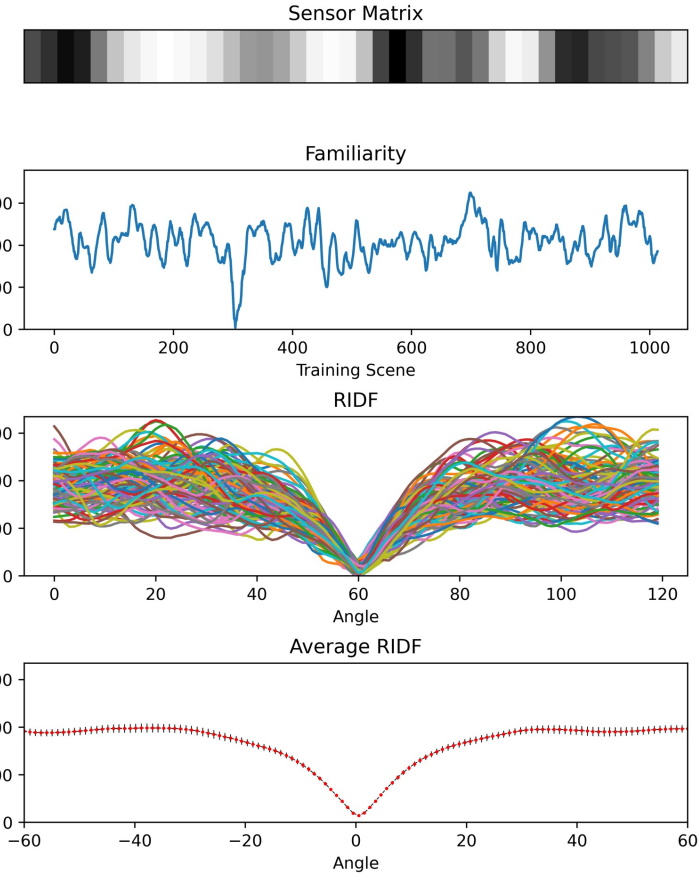
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 43.88; RMSD/dist: 0.110; TD: 4075; p90: 30; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 255; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

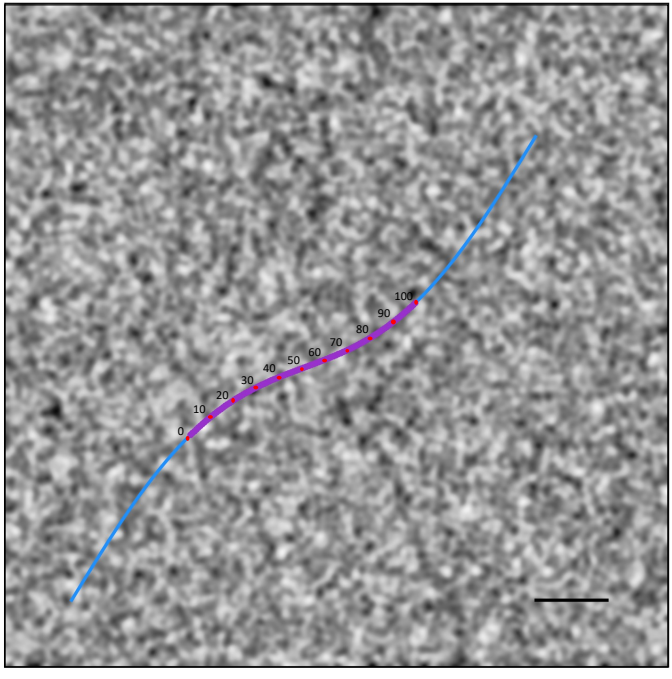


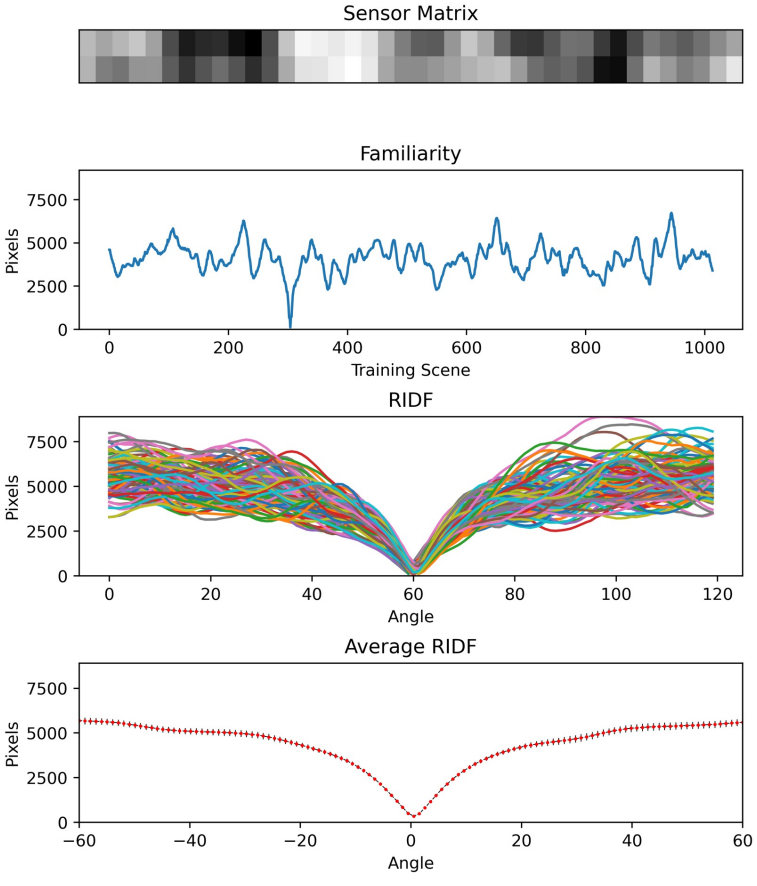


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 49.30; RMSD/dist: 0.123; TD: 3648; p90: 28; p50: 14; complete: 0

100%

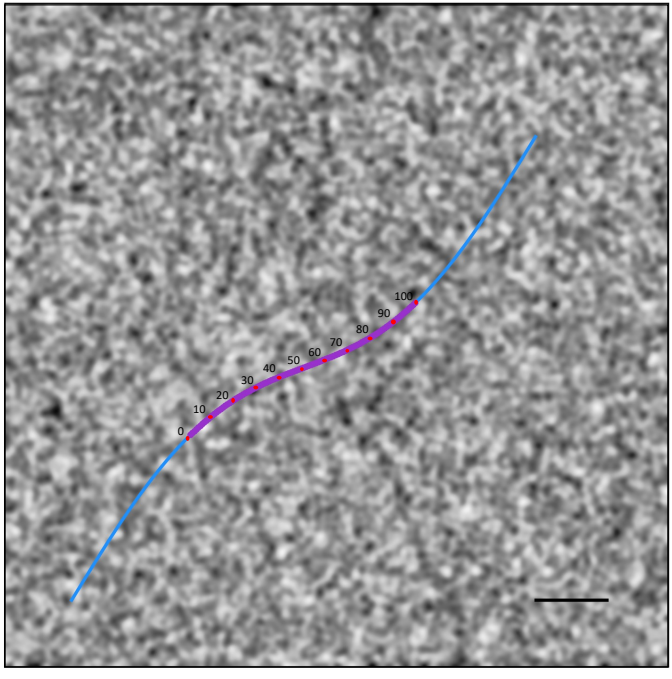


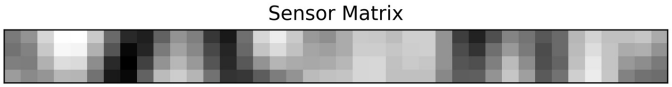


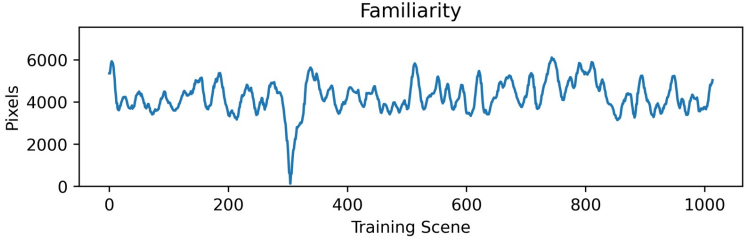
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

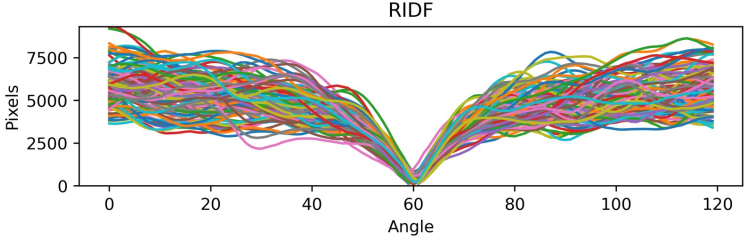
Navigation stats: RMSD error: 38.69; RMSD/dist: 0.097; TD: 4174; p90: 36; p50: 14; complete: 0

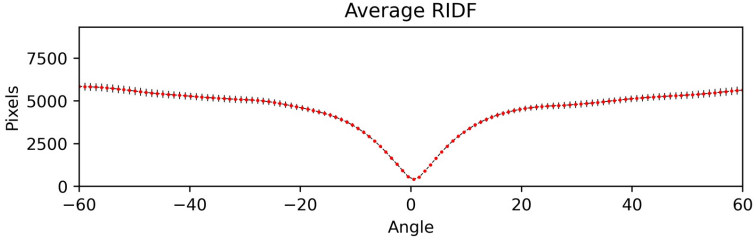
100%







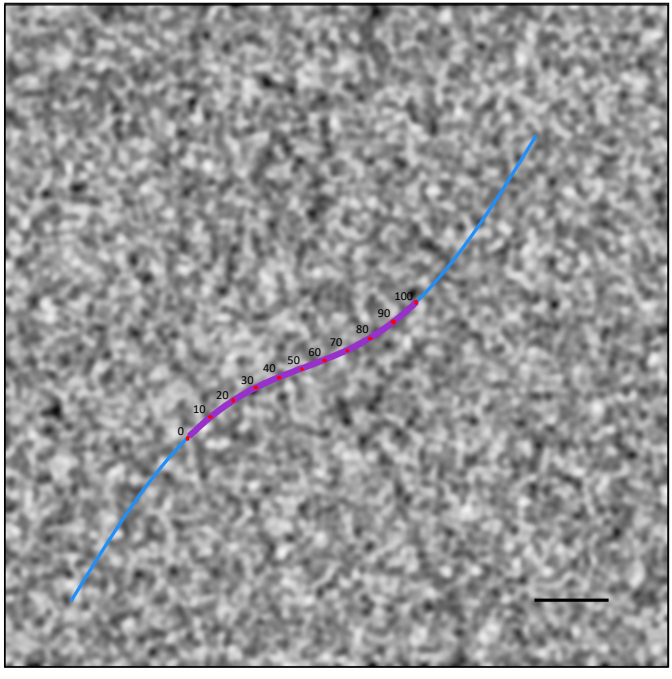


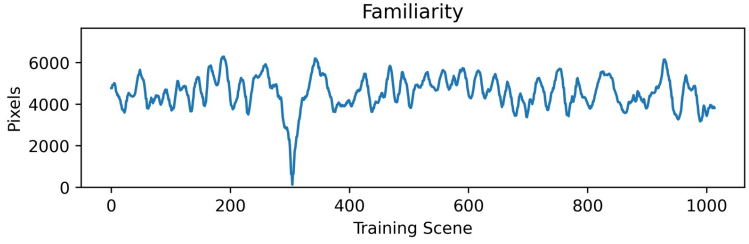


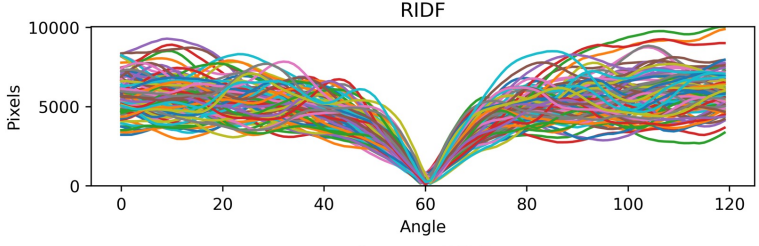
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

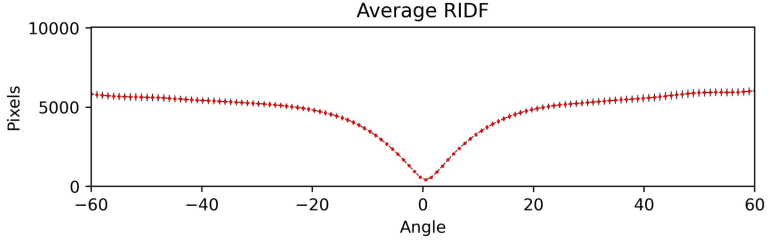
Navigation stats: RMSD error: 45.69; RMSD/dist: 0.114; TD: 4107; p90: 28; p50: 12; complete: 0

100%





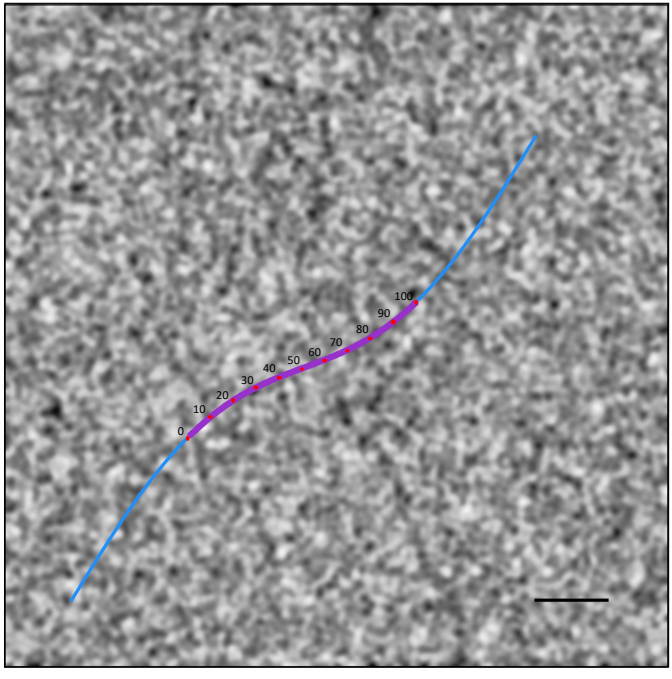


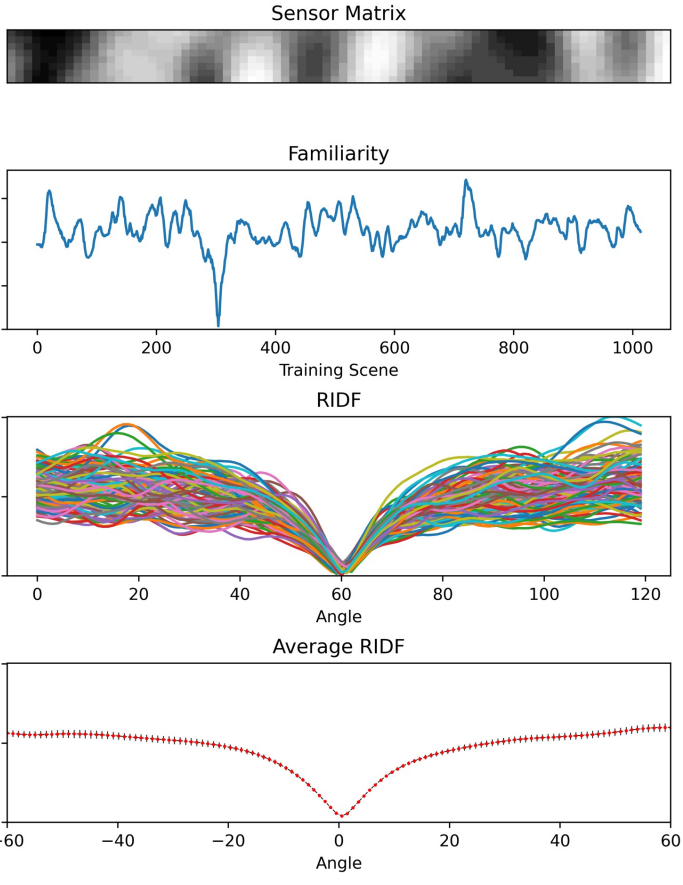


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 48.41; RMSD/dist: 0.121; TD: 4186; p90: 28; p50: 12; complete: 0

100%

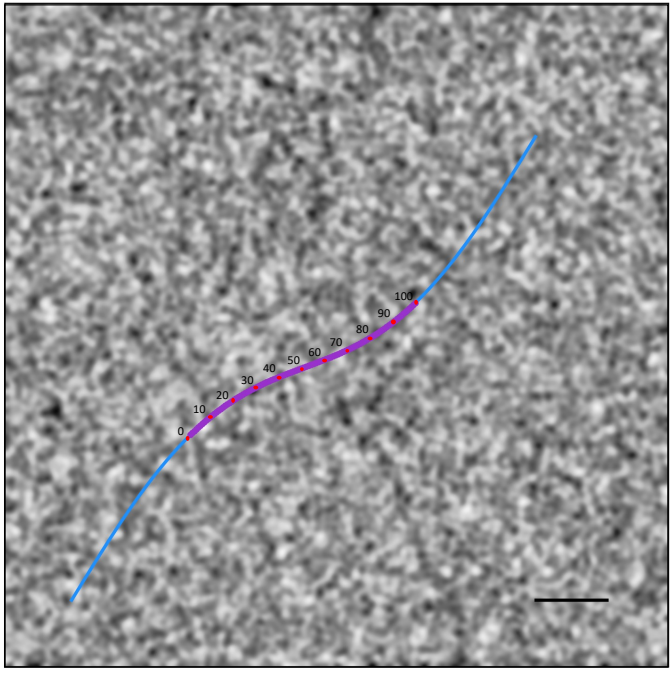


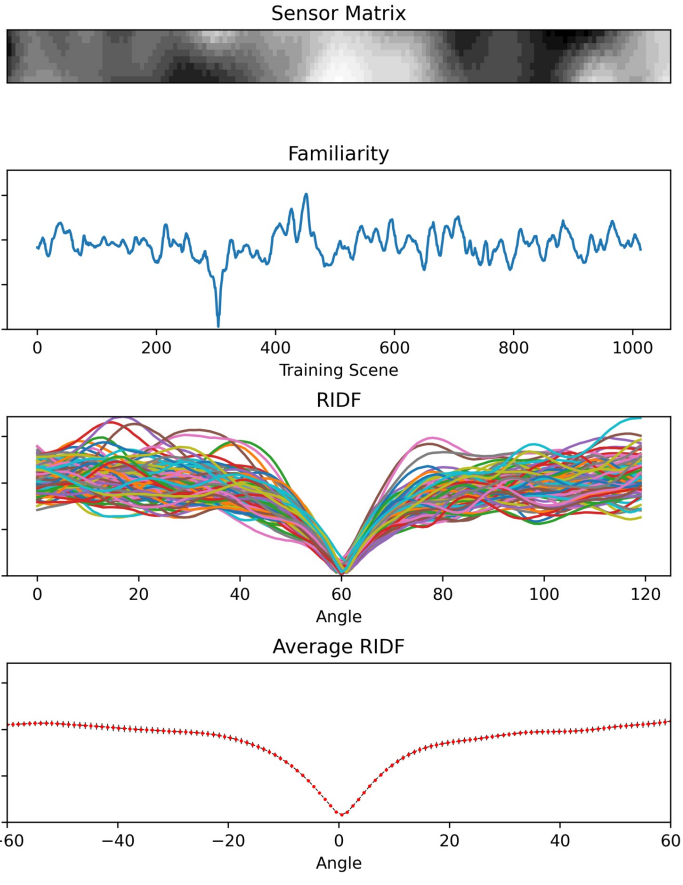


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 41.92; RMSD/dist: 0.105; TD: 4072; p90: 28; p50: 12; complete: 0

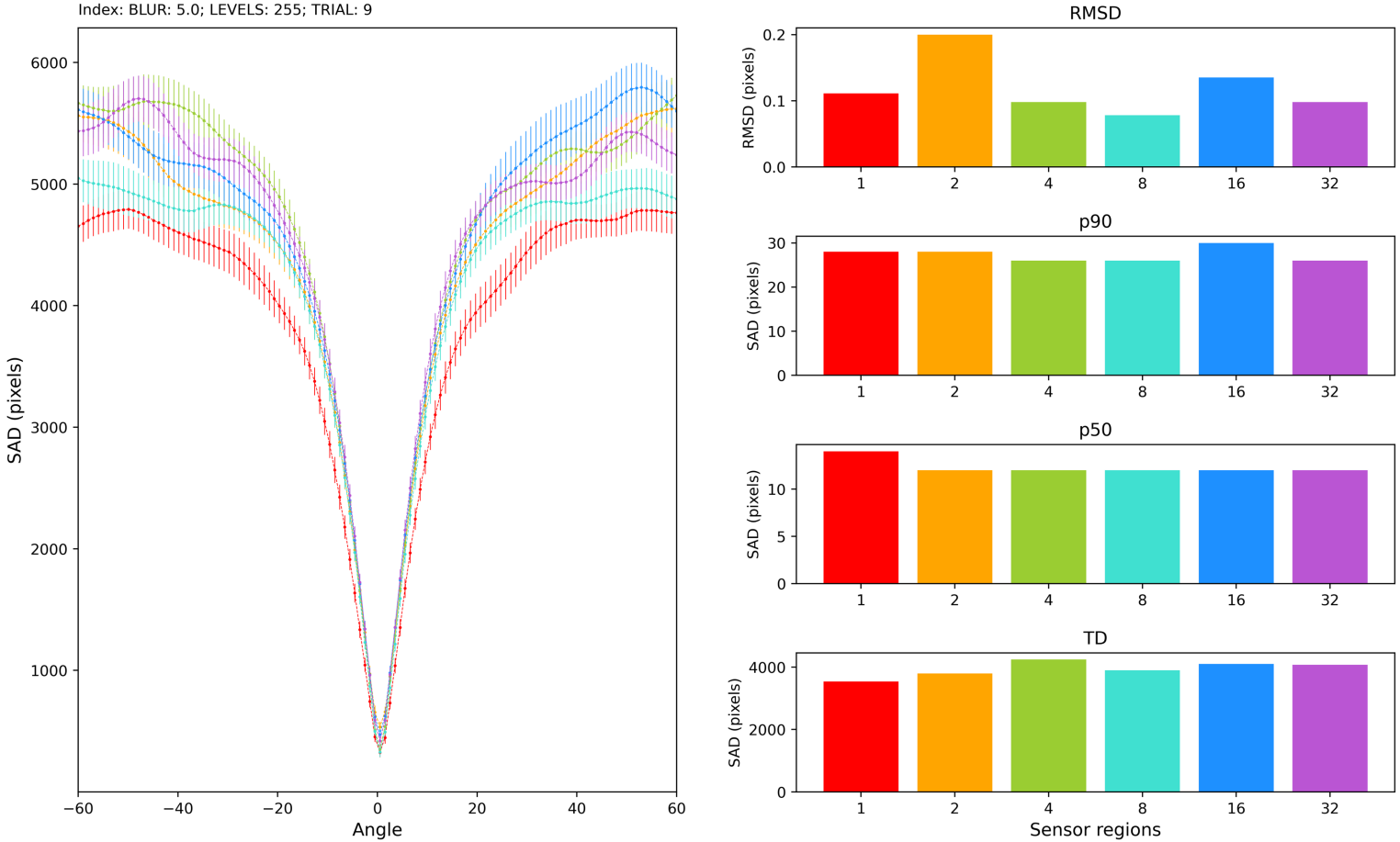
100%



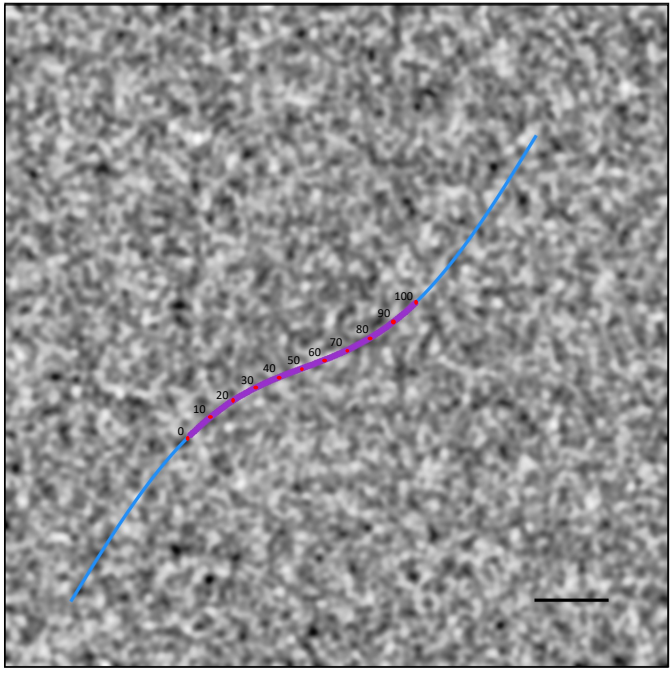


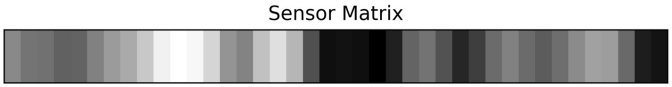
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

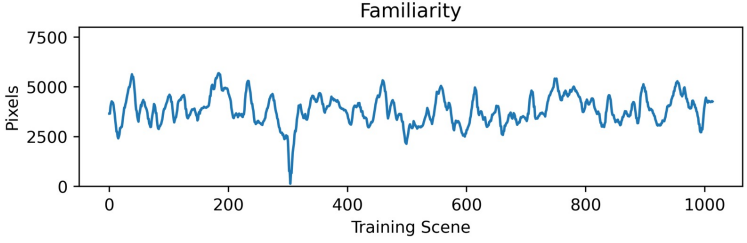
Navigation stats: RMSD error: 39.97; RMSD/dist: 0.100; TD: 4165; p90: 32; p50: 14; complete: 0

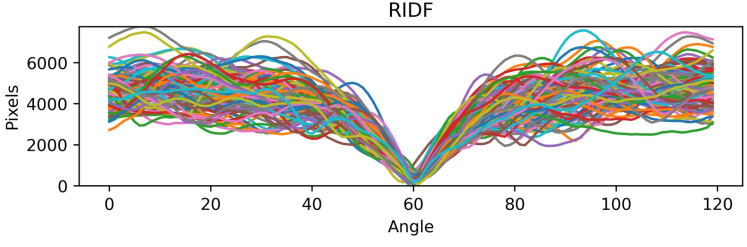

Index: BLUR: 5.0; LEVELS: 255; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

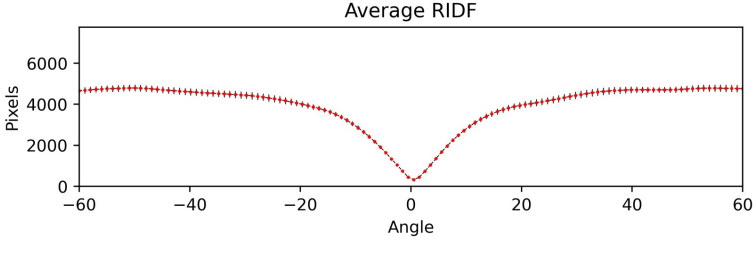
100%







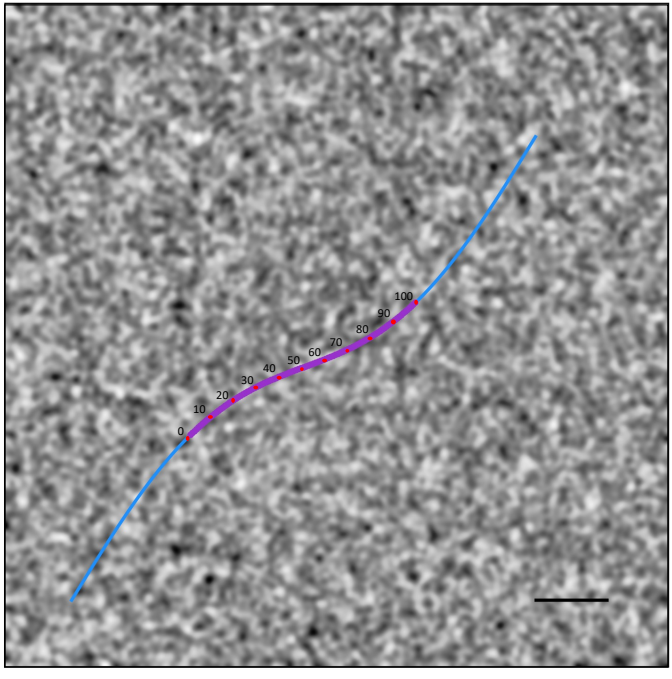


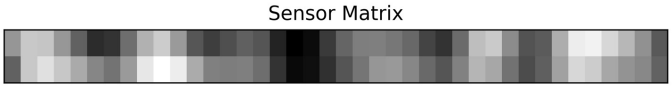


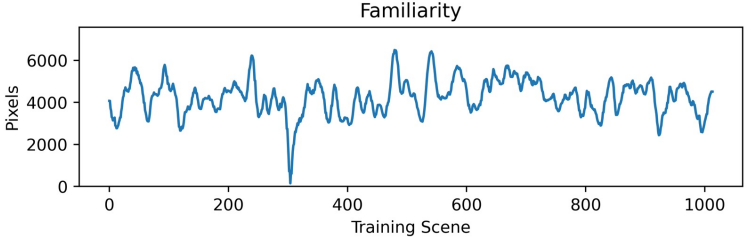
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

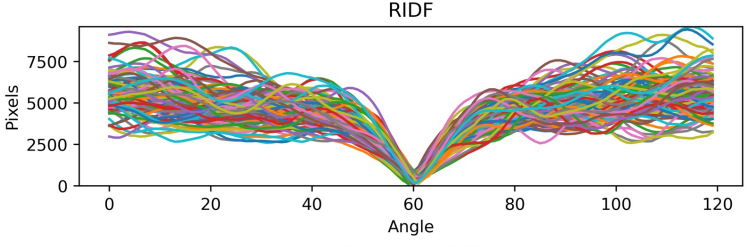
Navigation stats: RMSD error: 44.44; RMSD/dist: 0.111; TD: 3537; p90: 28; p50: 14; complete: 0

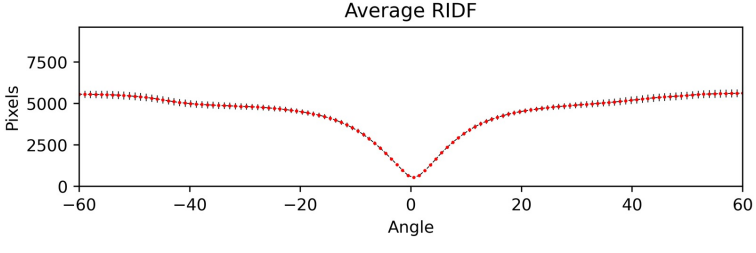
100%







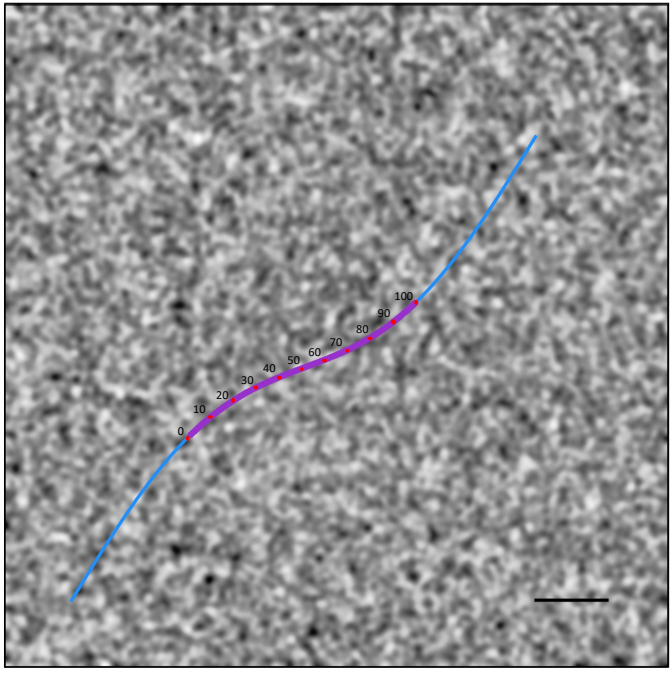


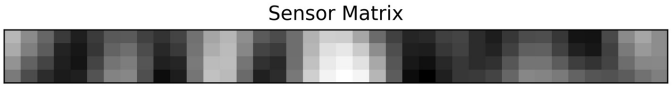


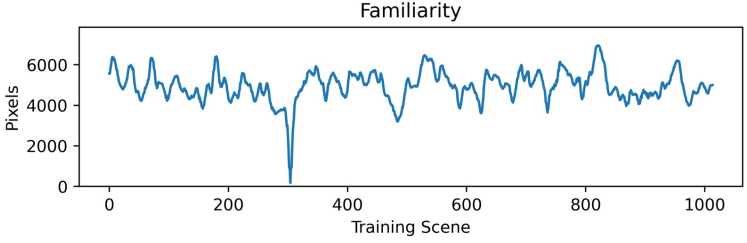
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

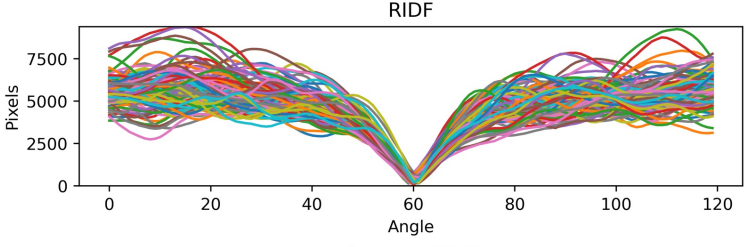
Navigation stats: RMSD error: 79.82; RMSD/dist: 0.200; TD: 3800; p90: 28; p50: 12; complete: 0

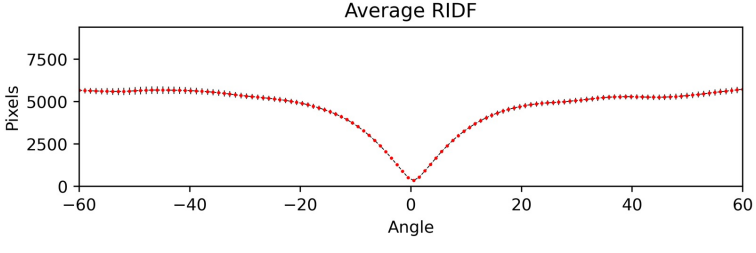
100%







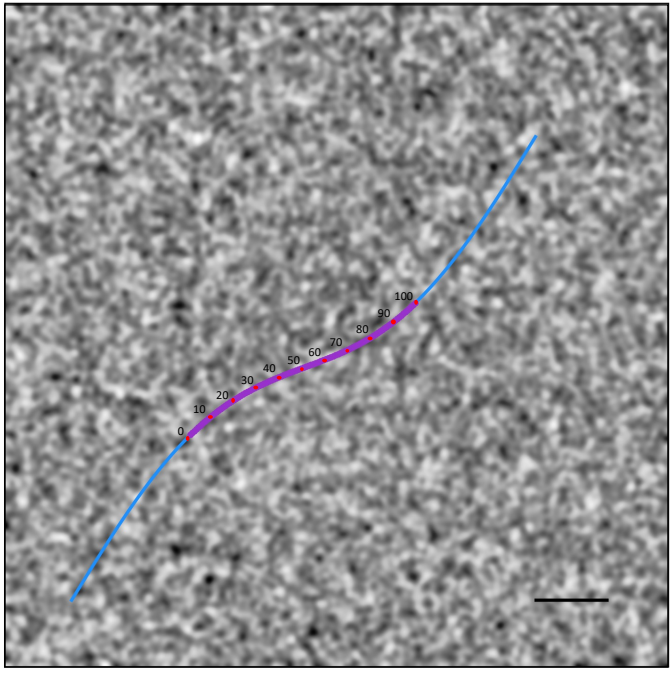


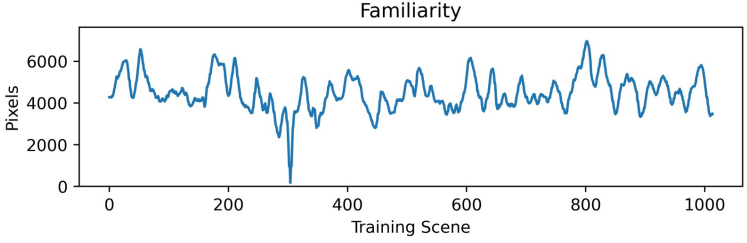


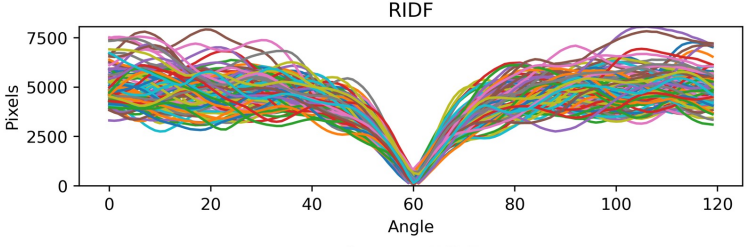
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

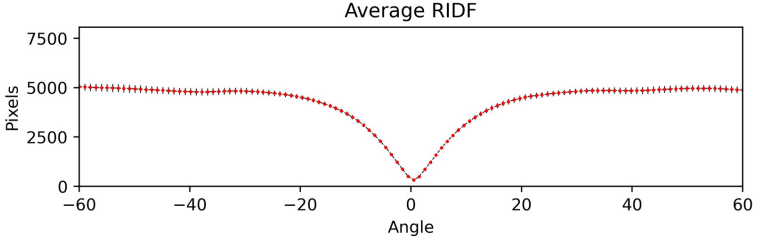
Navigation stats: RMSD error: 39.32; RMSD/dist: 0.098; TD: 4243; p90: 26; p50: 12; complete: 0

100%





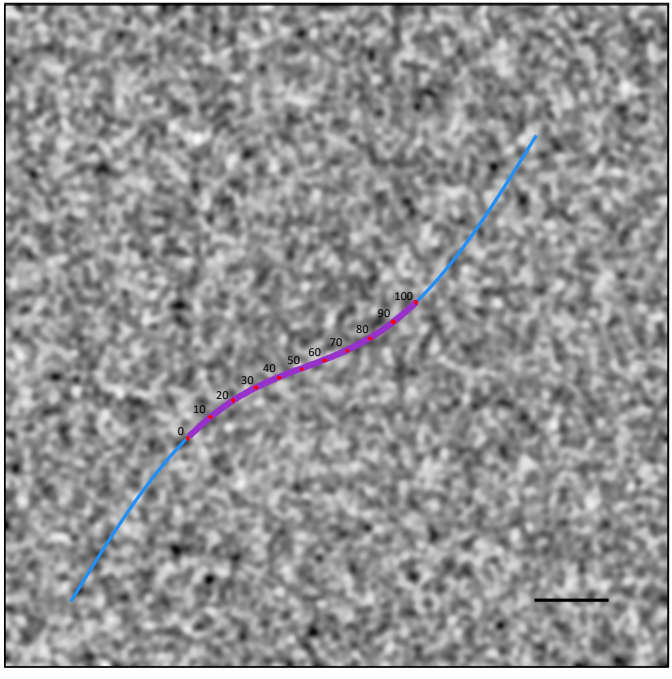


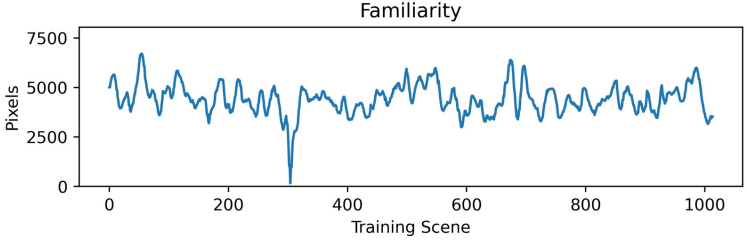


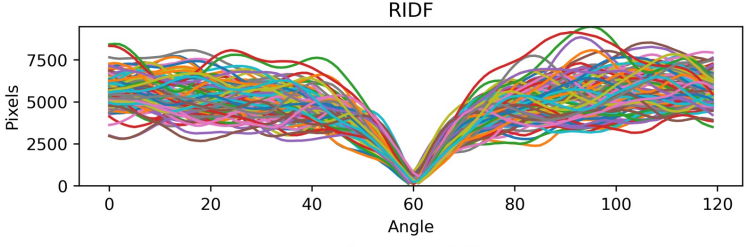
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

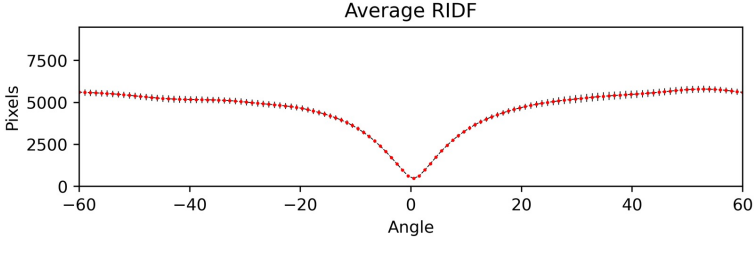
Navigation stats: RMSD error: 31.06; RMSD/dist: 0.078; TD: 3900; p90: 26; p50: 12; complete: 0

100%





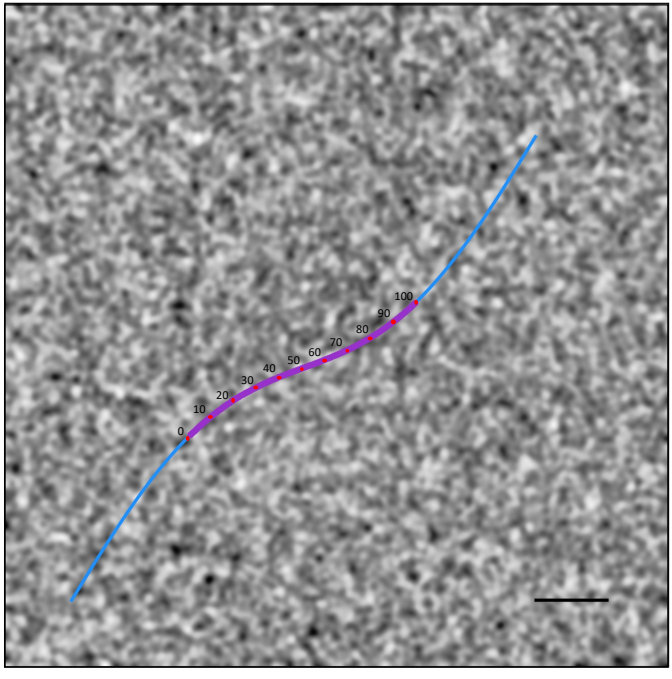


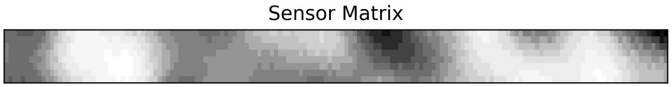


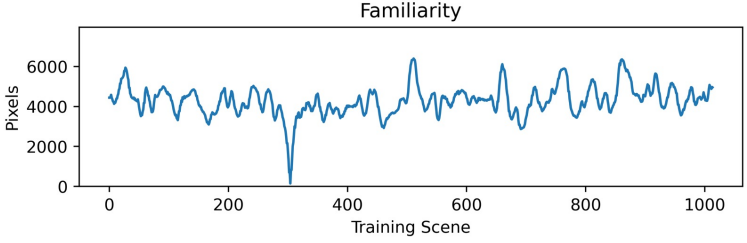
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

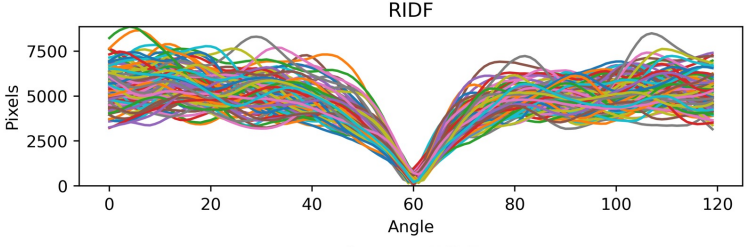
Navigation stats: RMSD error: 54.05; RMSD/dist: 0.135; TD: 4105; p90: 30; p50: 12; complete: 0

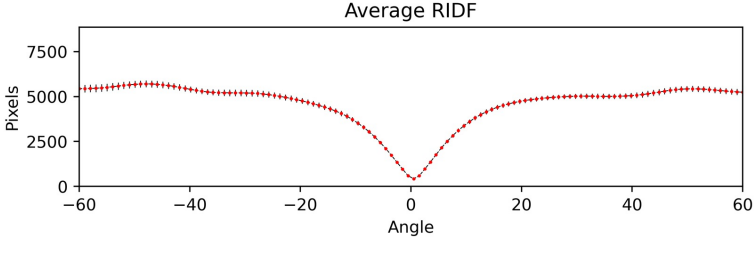
100%





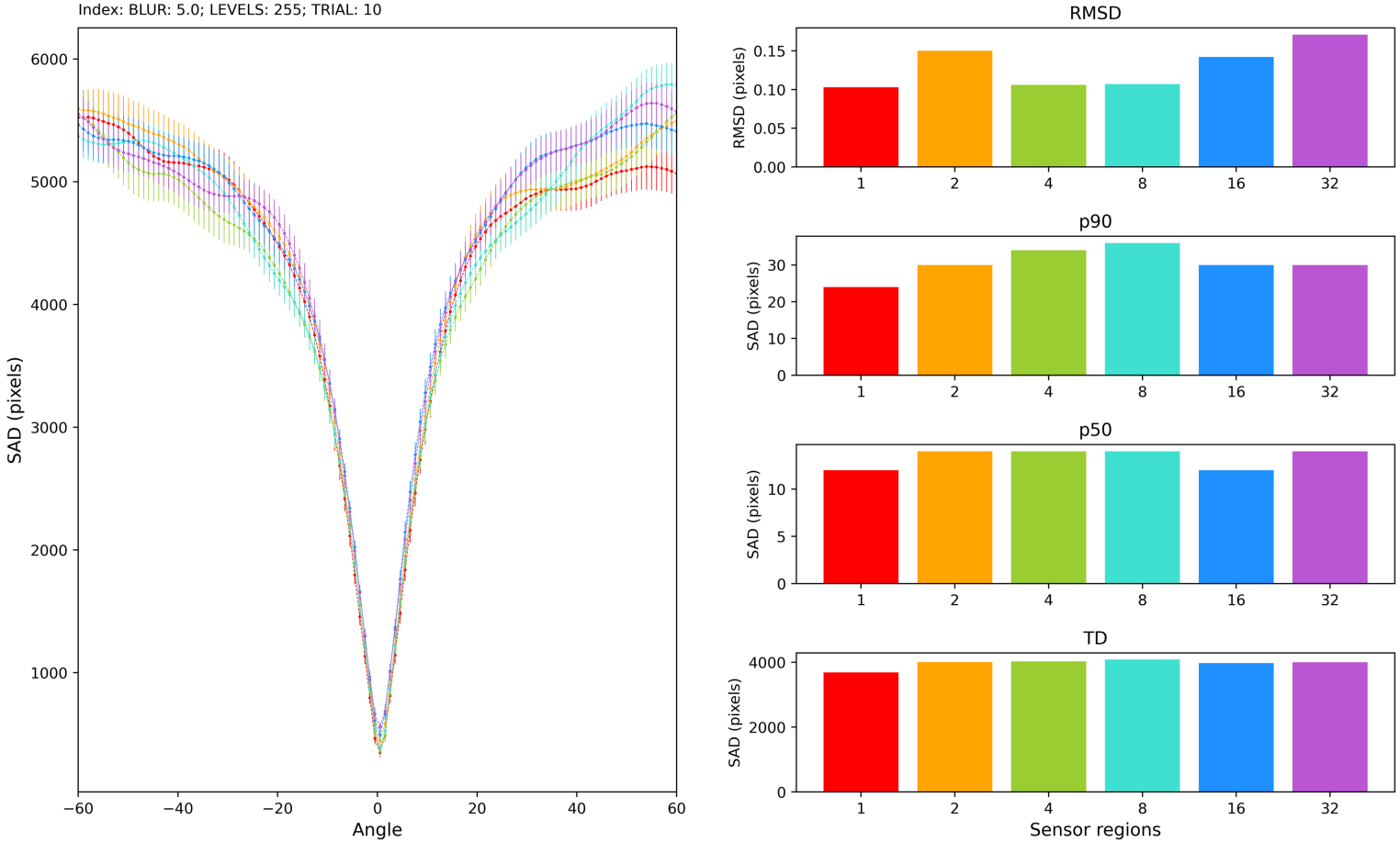




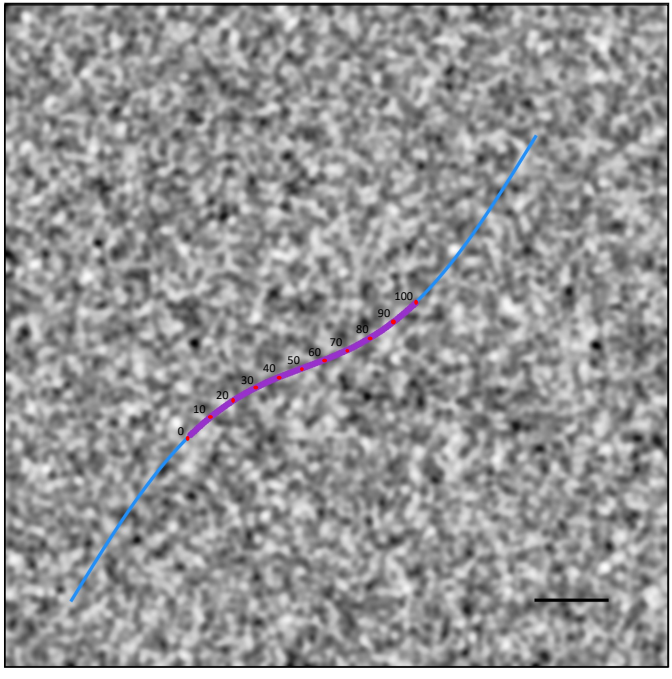


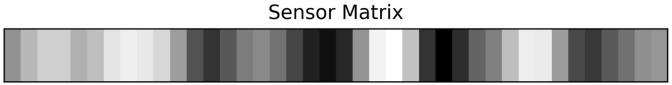
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

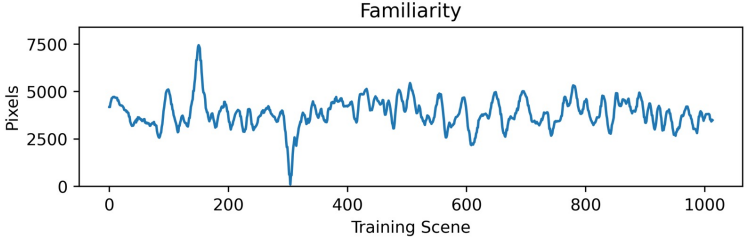
Navigation stats: RMSD error: 39.04; RMSD/dist: 0.098; TD: 4077; p90: 26; p50: 12; complete: 0

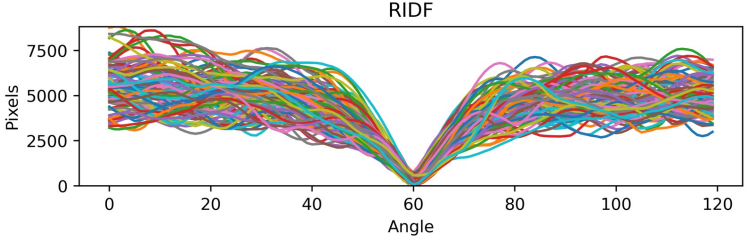

Index: BLUR: 5.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

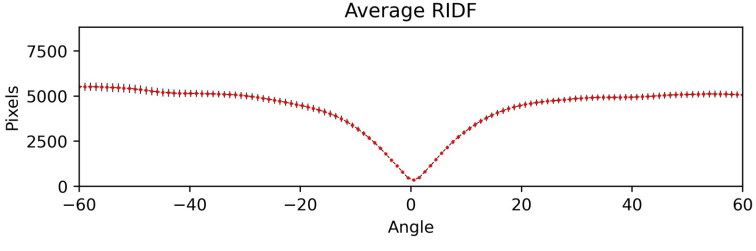
100%







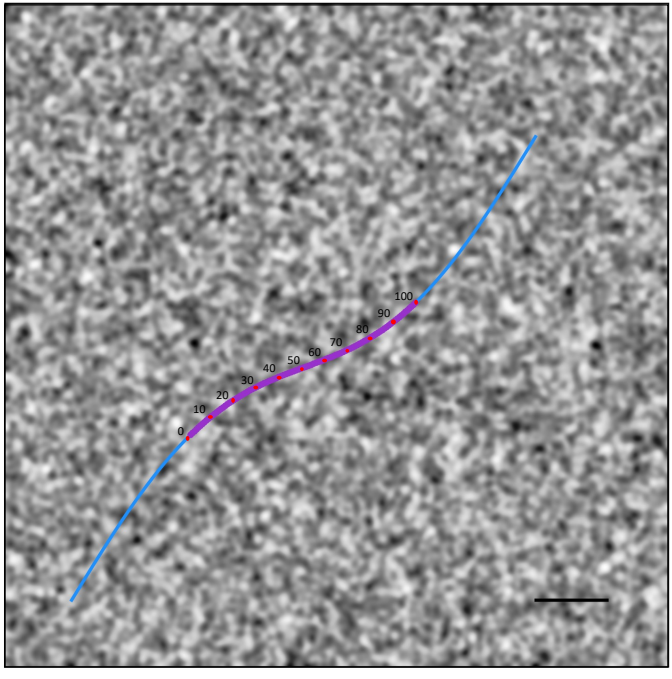


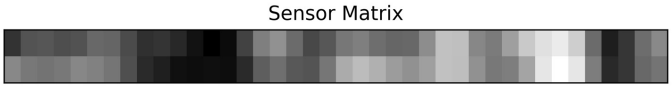


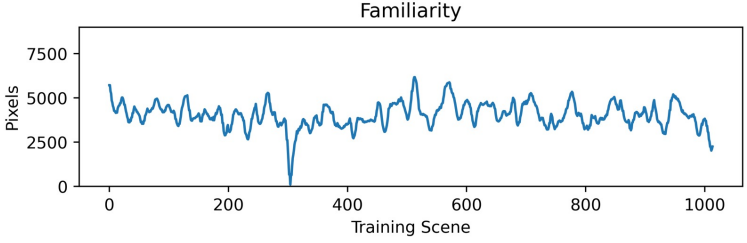
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

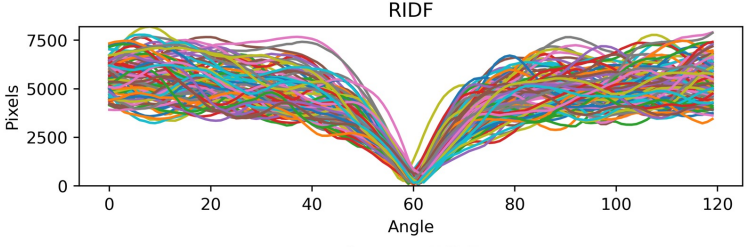
Navigation stats: RMSD error: 41.28; RMSD/dist: 0.103; TD: 3685; p90: 24; p50: 12; complete: 0

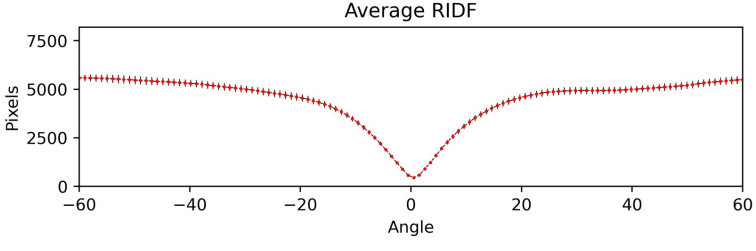
100%







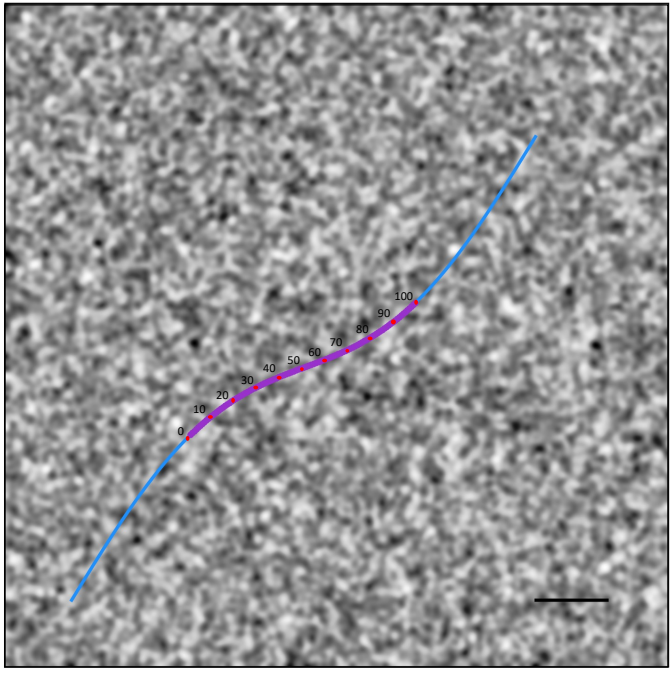


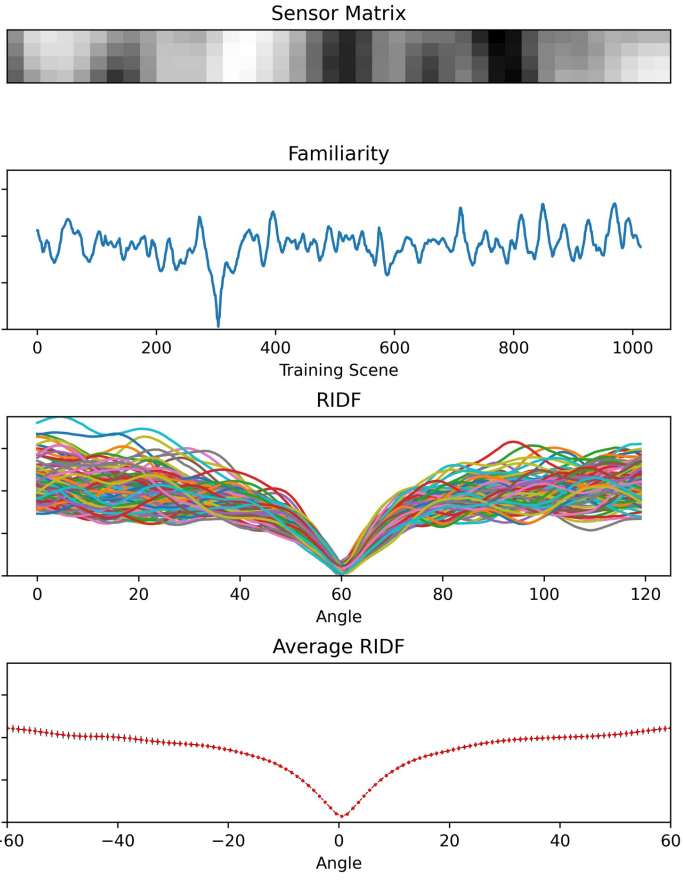


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 60.17; RMSD/dist: 0.150; TD: 4007; p90: 30; p50: 14; complete: 0

100%

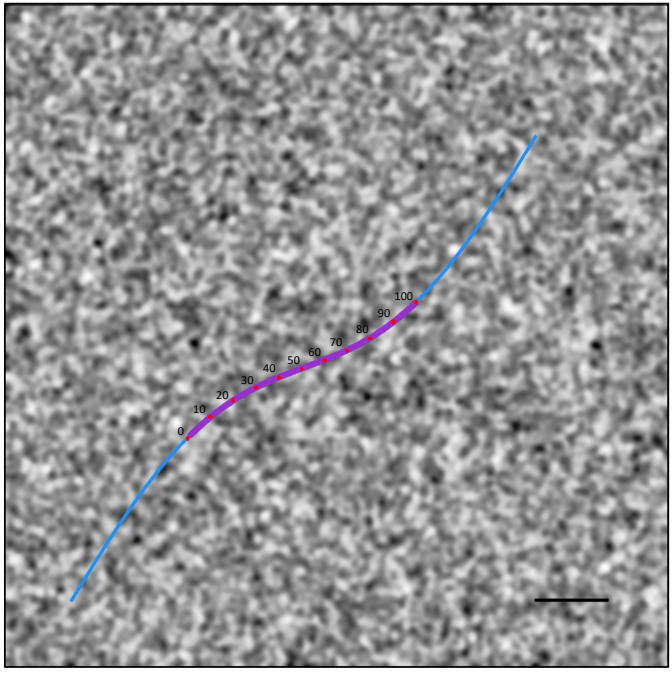


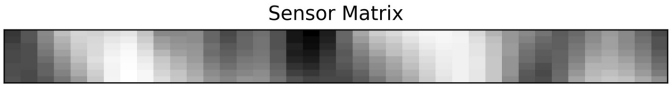


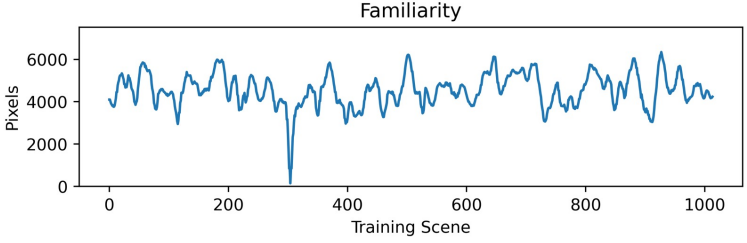
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

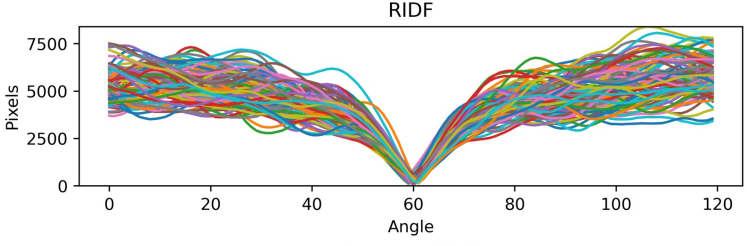
Navigation stats: RMSD error: 42.23; RMSD/dist: 0.106; TD: 4028; p90: 34; p50: 14; complete: 0

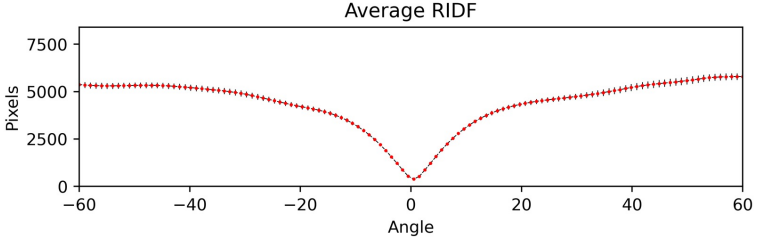
100%







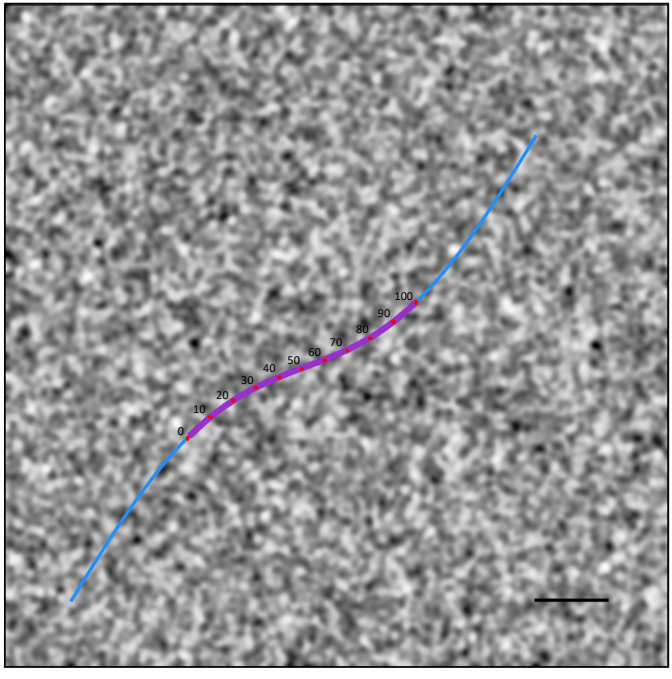


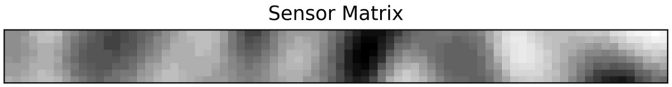


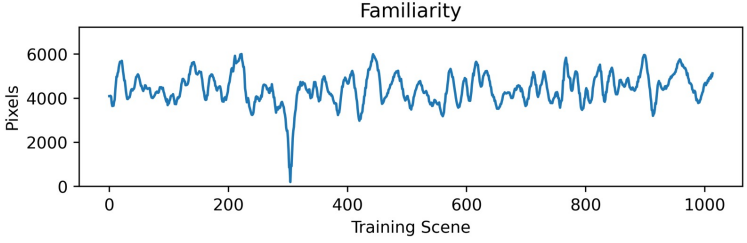
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

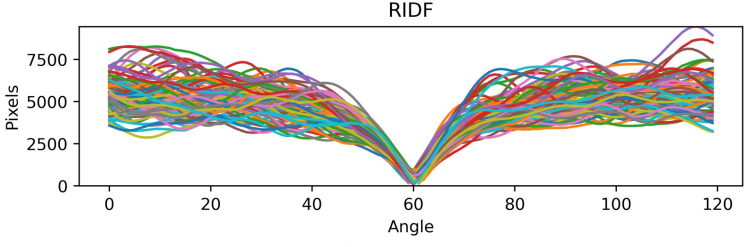
Navigation stats: RMSD error: 42.75; RMSD/dist: 0.107; TD: 4081; p90: 36; p50: 14; complete: 0

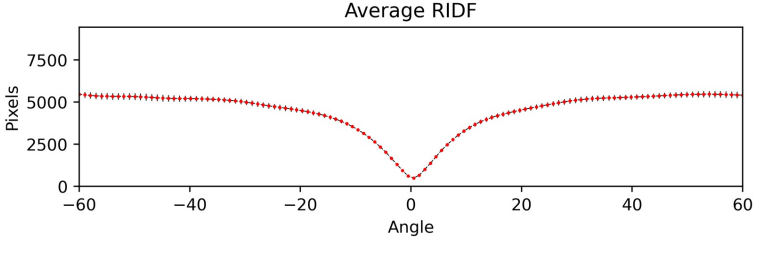
100%







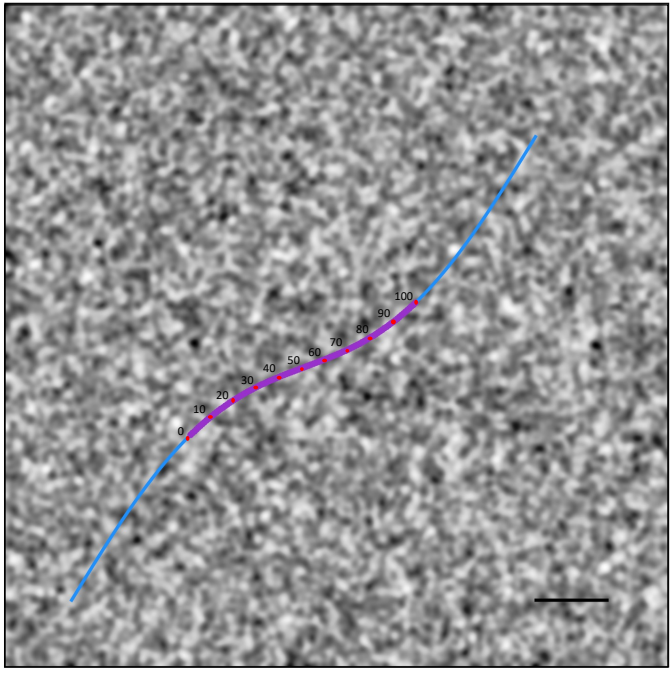


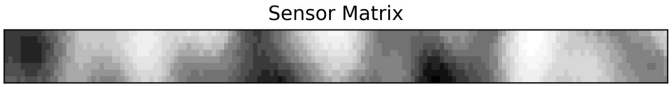


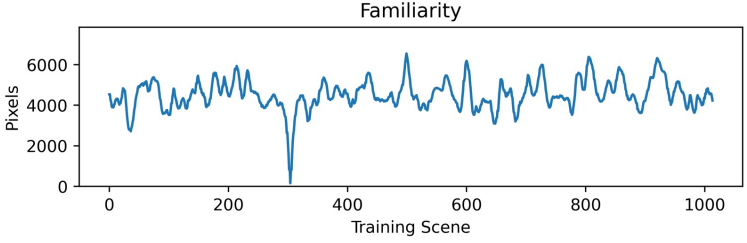
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

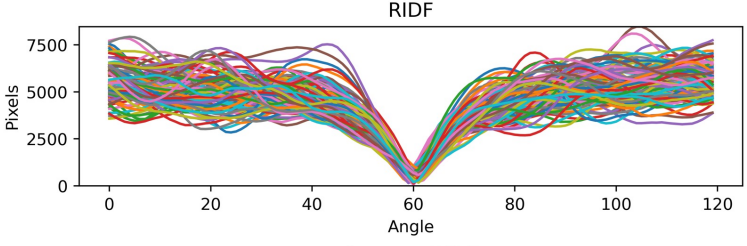
Navigation stats: RMSD error: 56.87; RMSD/dist: 0.142; TD: 3972; p90: 30; p50: 12; complete: 0

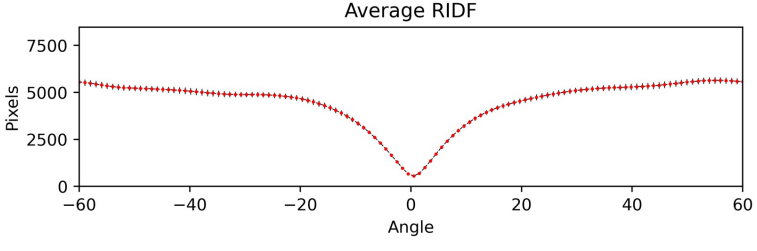
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 68.46; RMSD/dist: 0.171; TD: 4001; p90: 30; p50: 14; complete: 0