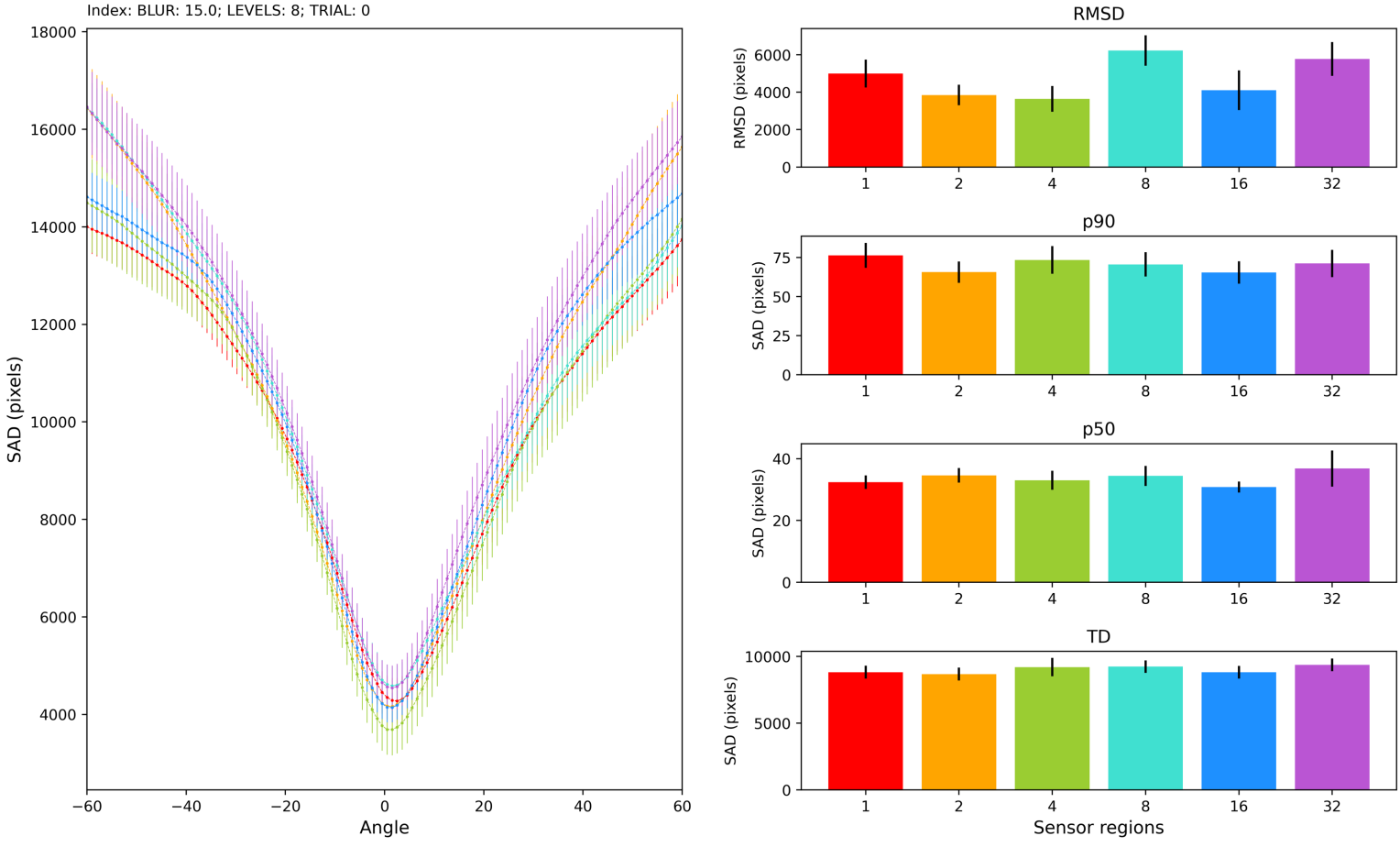
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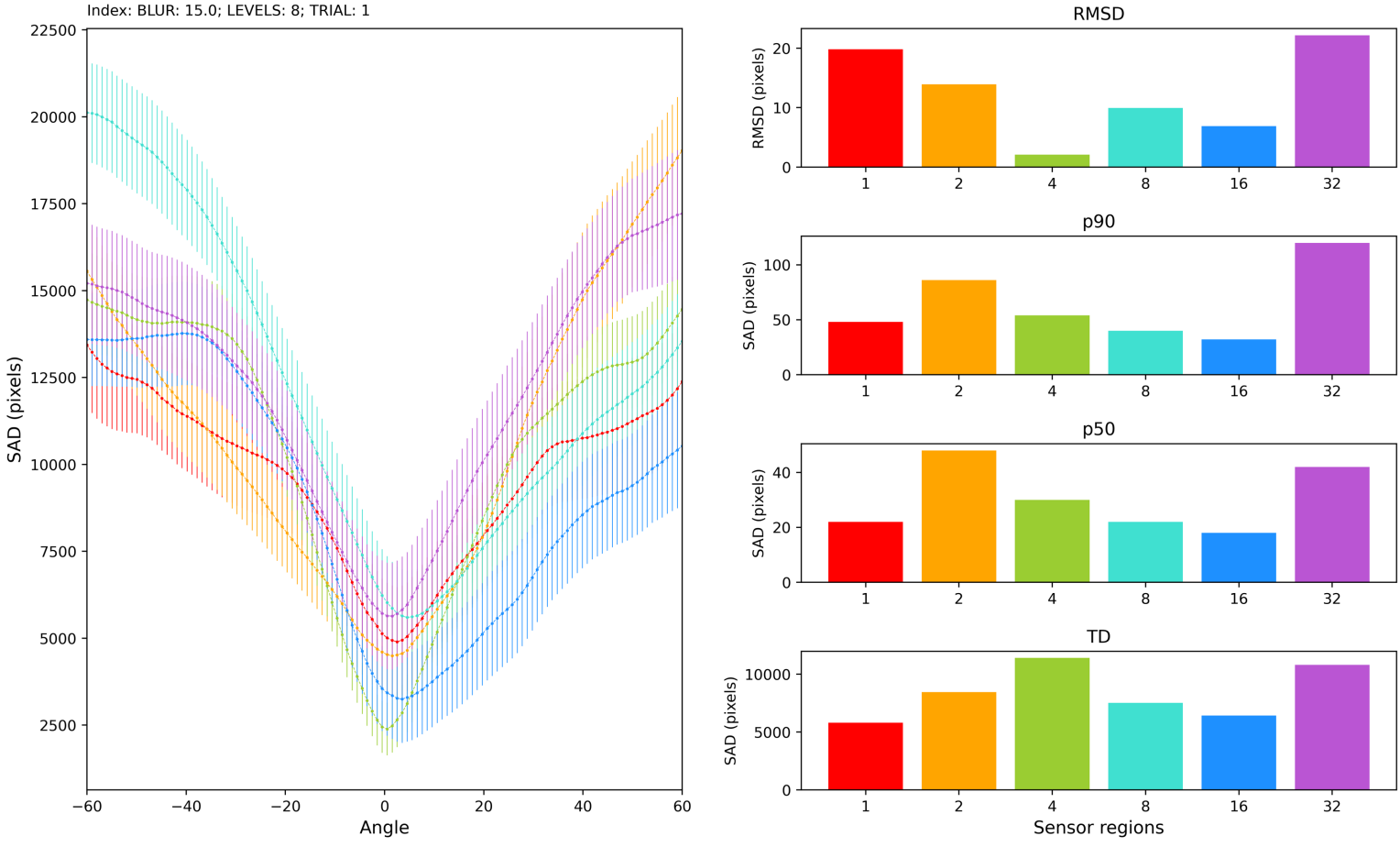
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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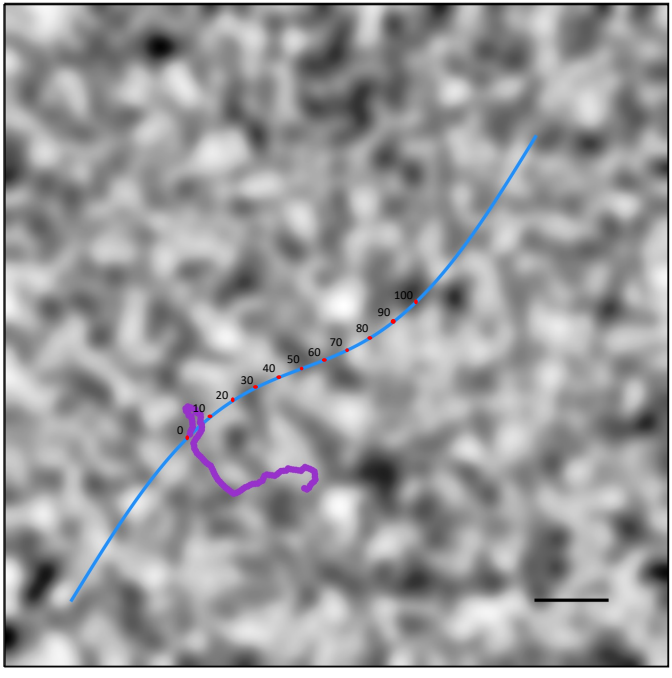
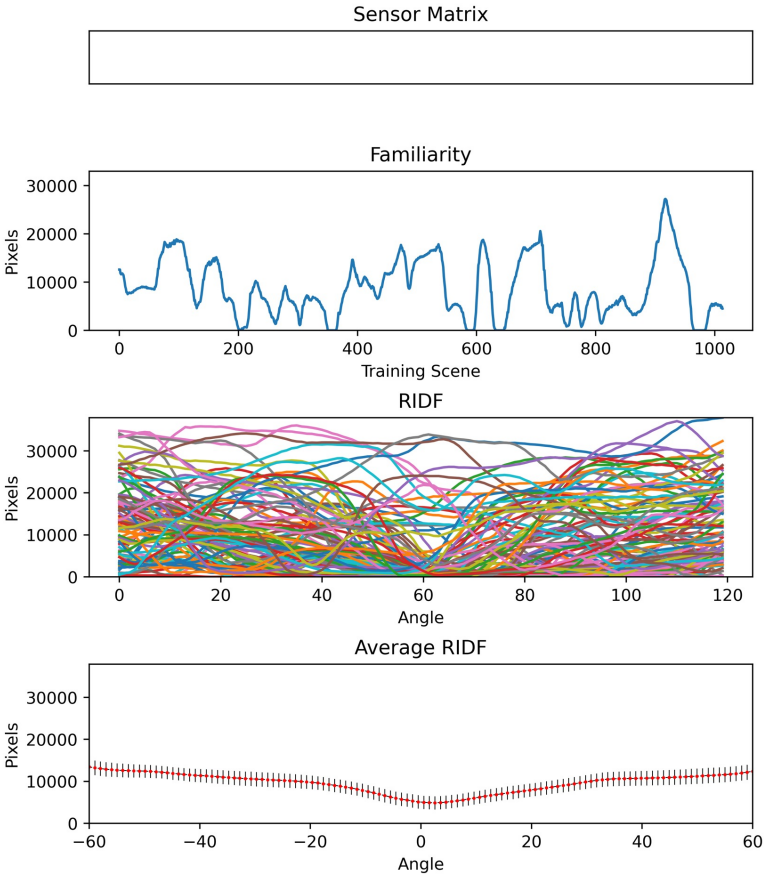
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

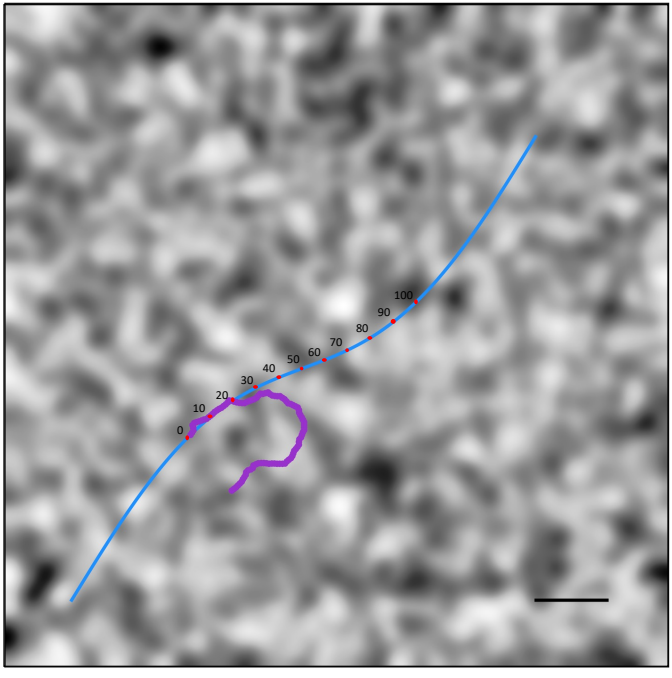


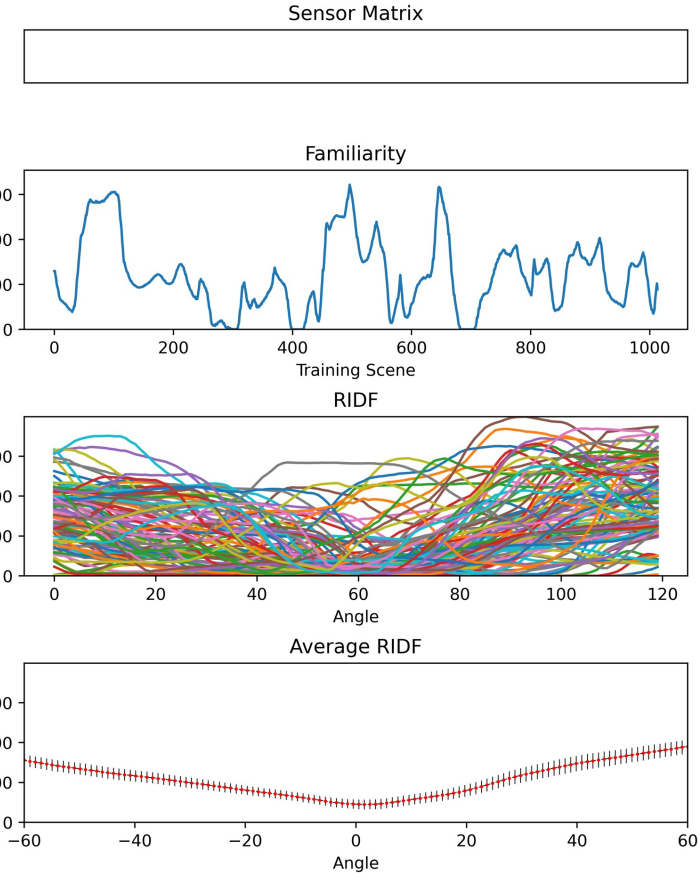


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 7933.79; RMSD/dist: 19.834; TD: 5810; p90: 48; p50: 22; complete: 0

10%

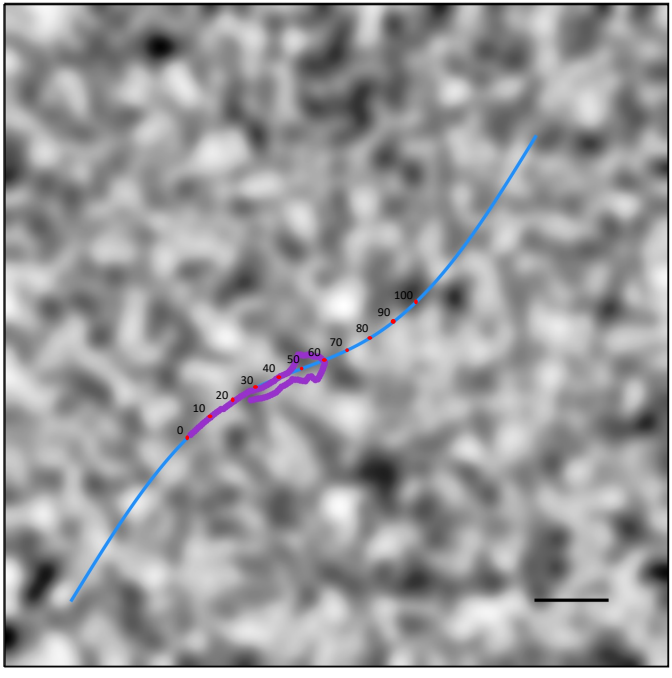


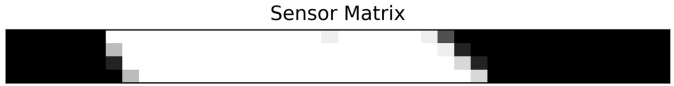


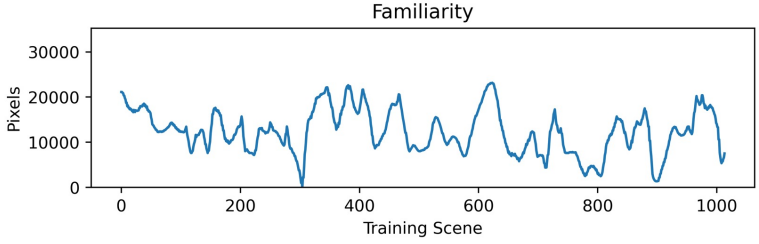
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

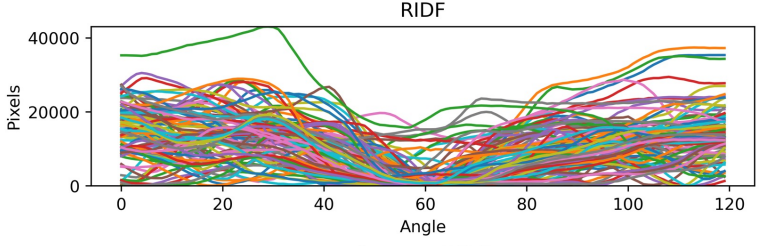
Navigation stats: RMSD error: 5564.75; RMSD/dist: 13.912; TD: 8460; p90: 86; p50: 48; complete: 0

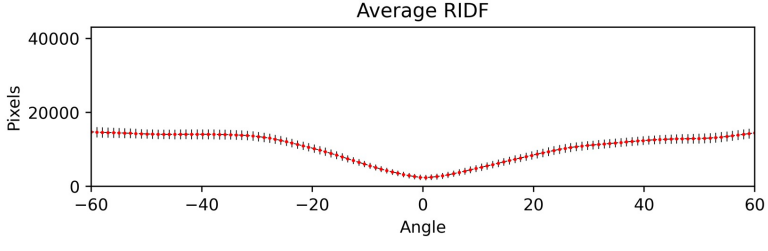
40%











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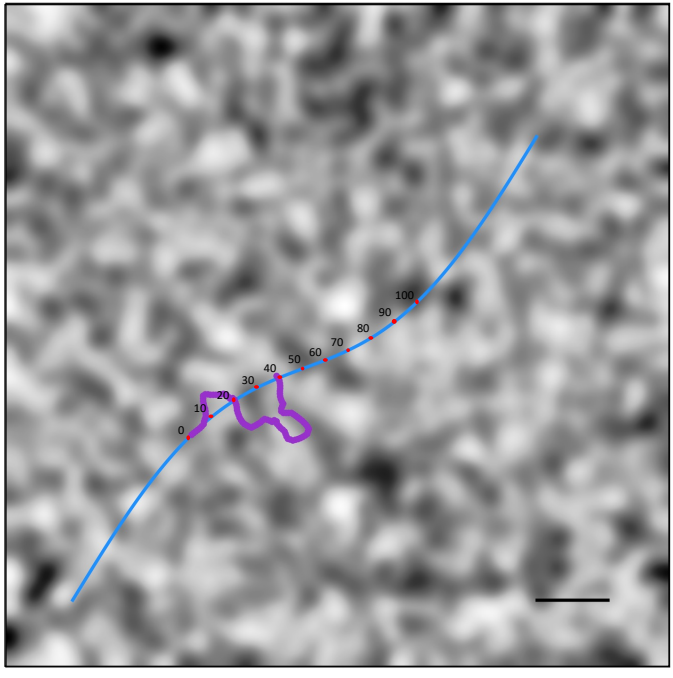
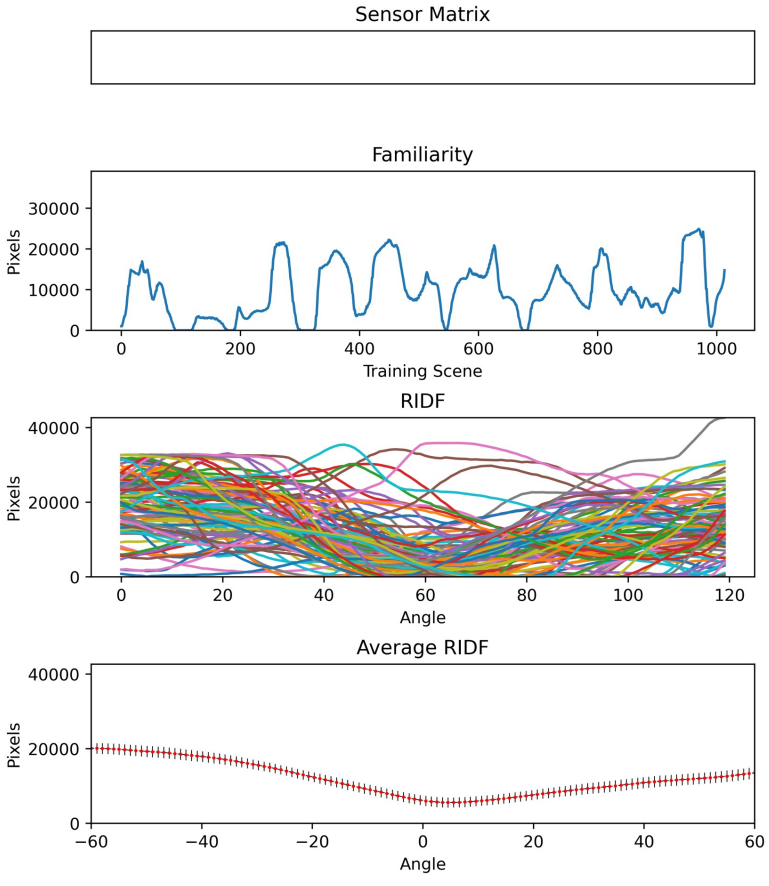
Navigation stats: RMSD error: 838.30; RMSD/dist: 2.096; TD: 11404; p90: 54; p50: 30; complete: 0

0%

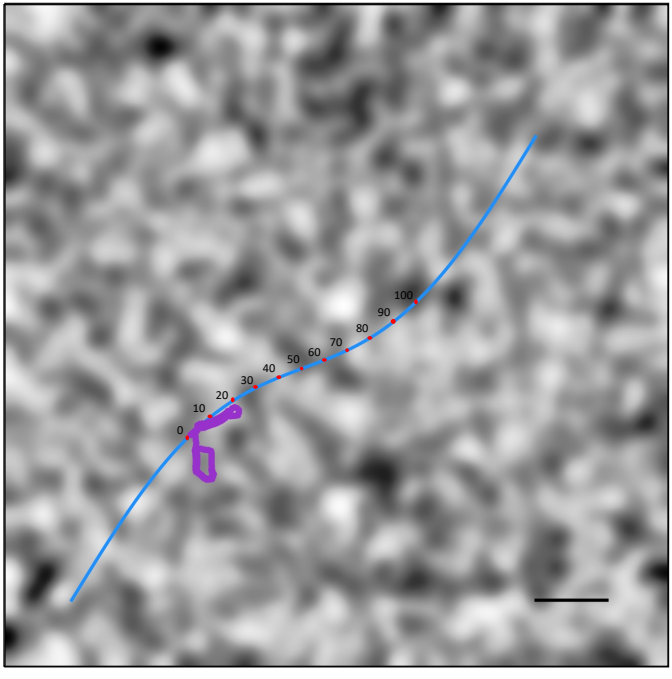


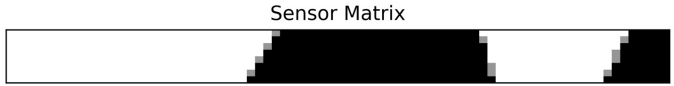


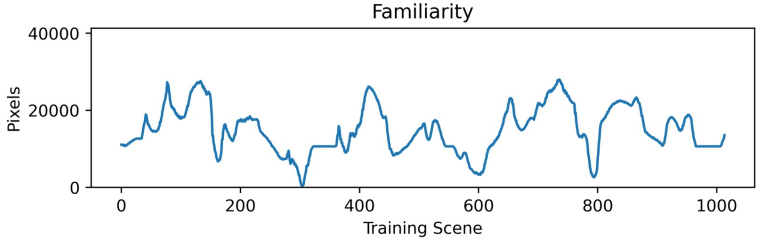
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

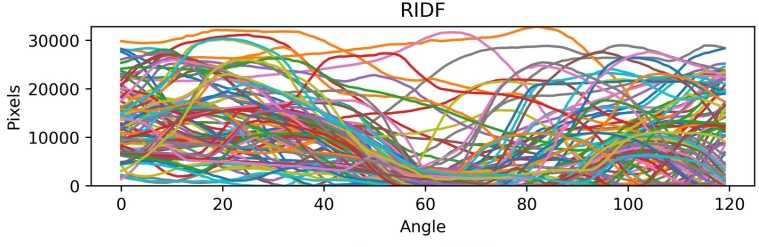
Navigation stats: RMSD error: 3982.83; RMSD/dist: 9.957; TD: 7520; p90: 40; p50: 22; complete: 0

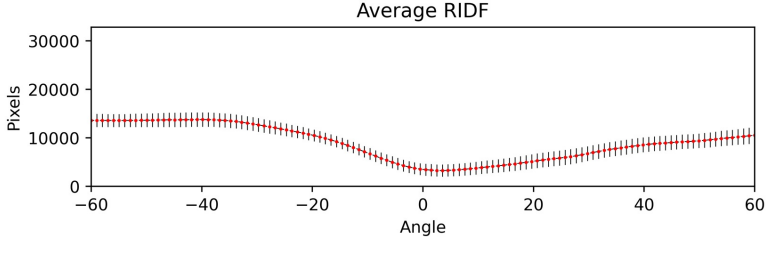
0%







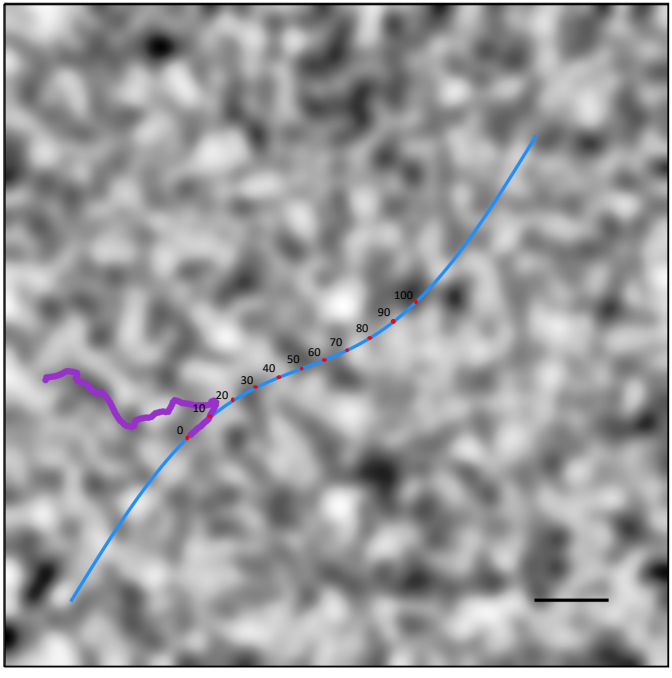


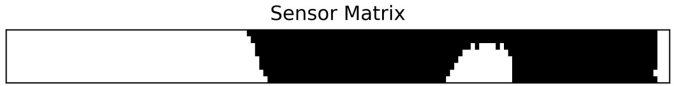


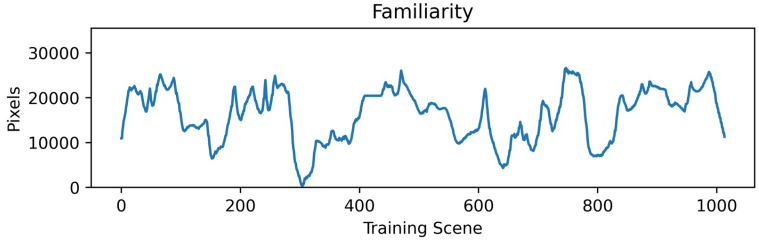
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

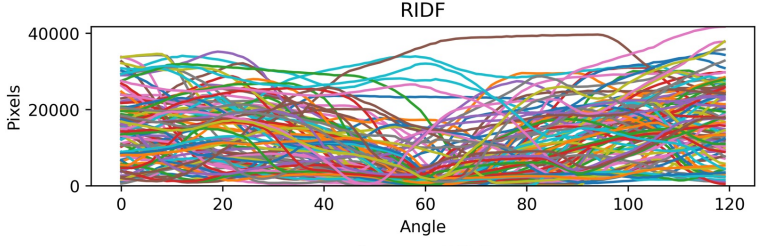
Navigation stats: RMSD error: 2757.25; RMSD/dist: 6.893; TD: 6424; p90: 32; p50: 18; complete: 0

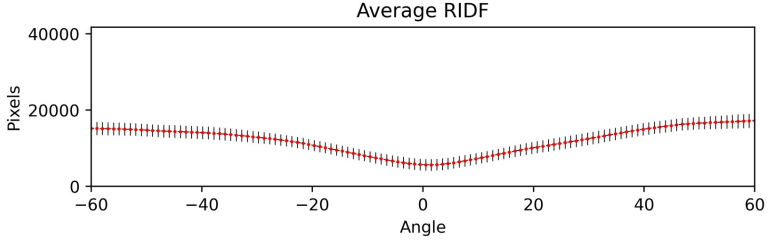
10%





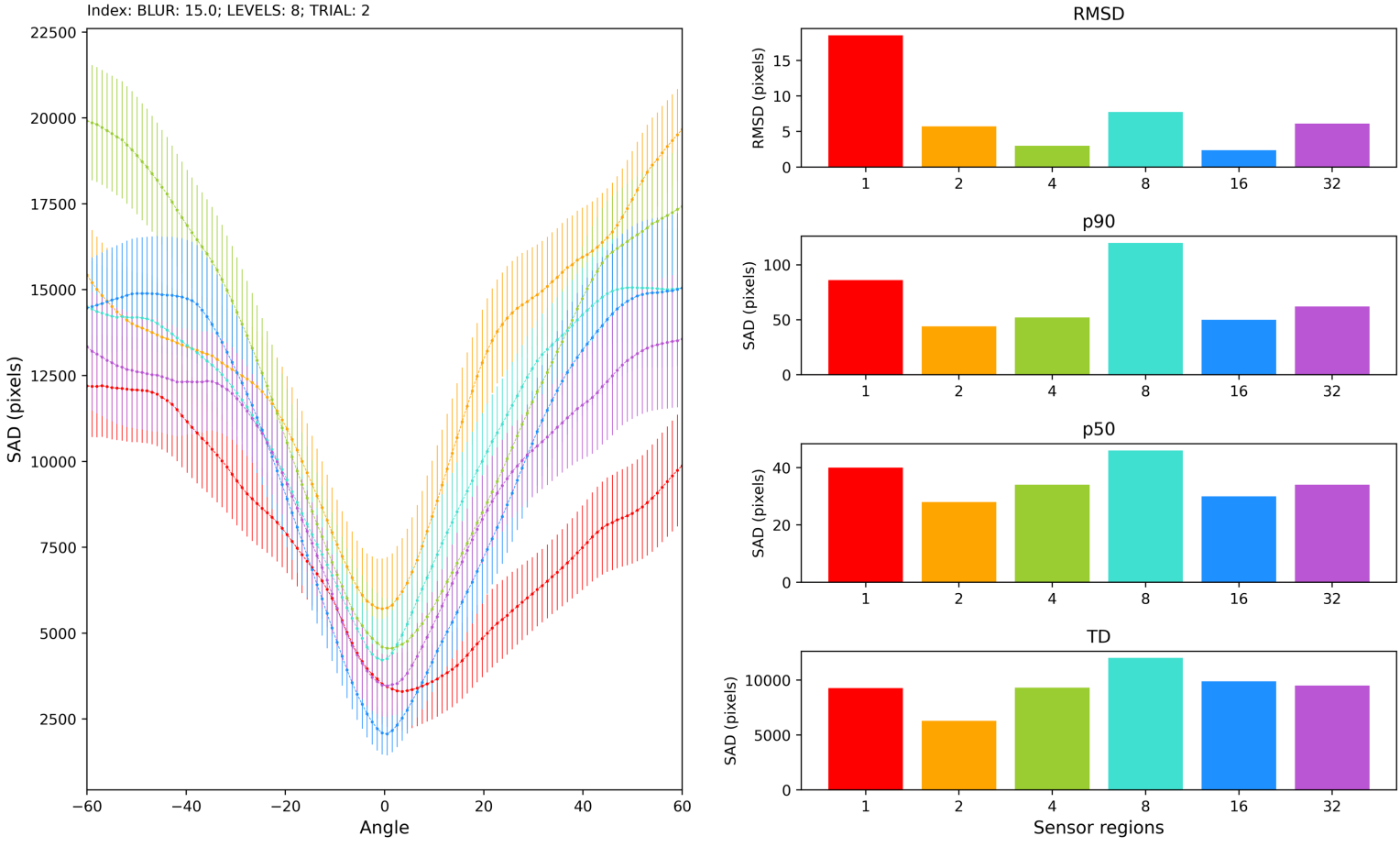




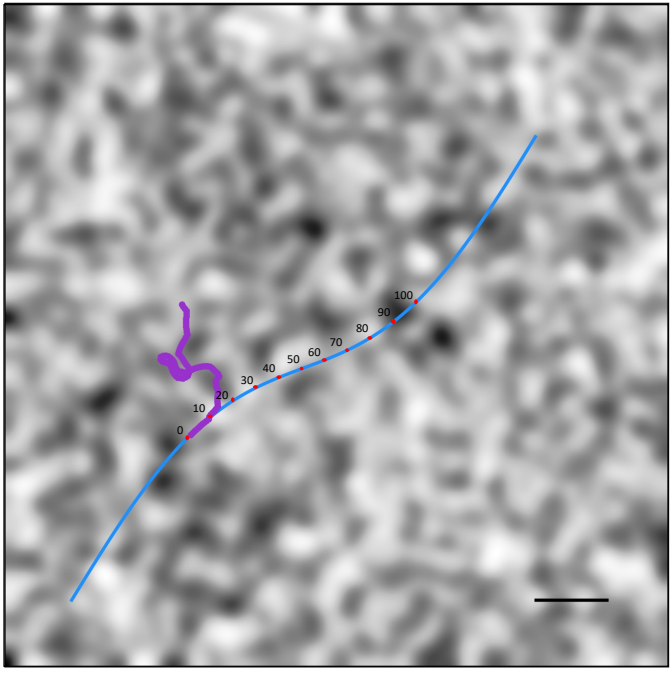


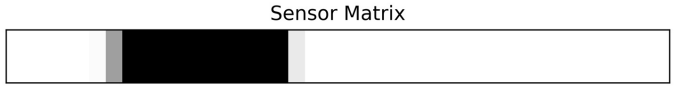
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

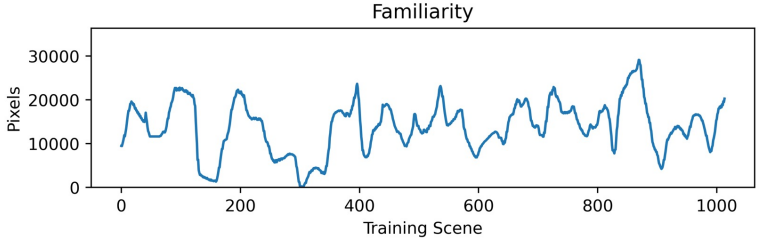
Navigation stats: RMSD error: 8872.71; RMSD/dist: 22.182; TD: 10814; p90: 120; p50: 42; complete: 0

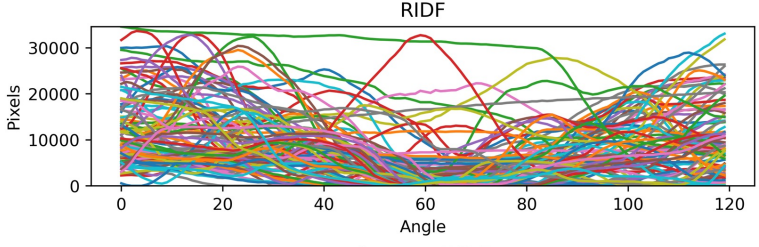

Index: BLUR: 15.0; LEVELS: 8; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

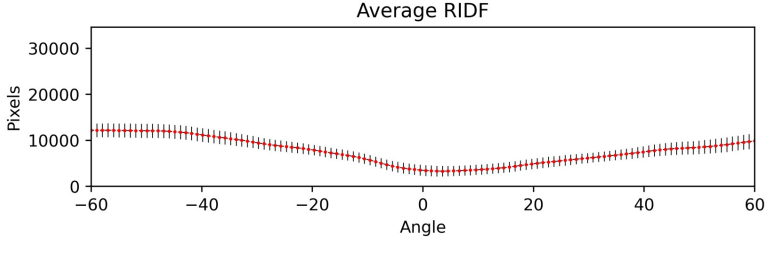
10%







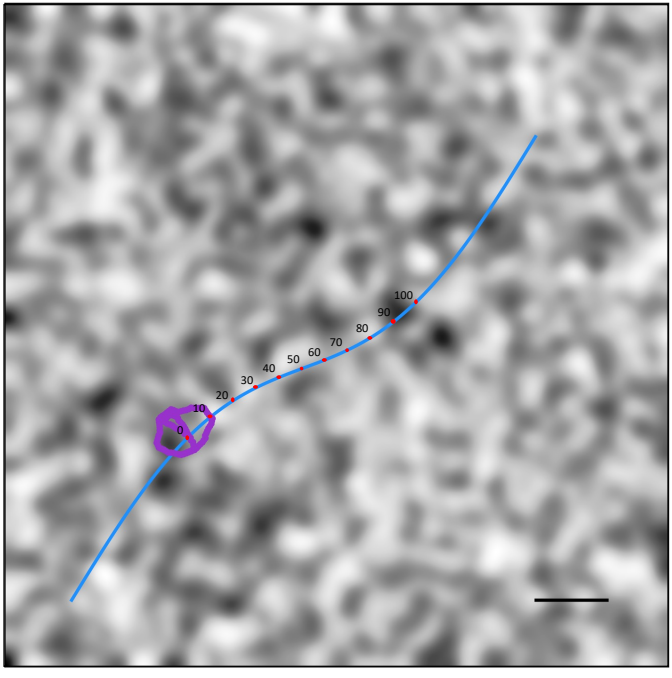


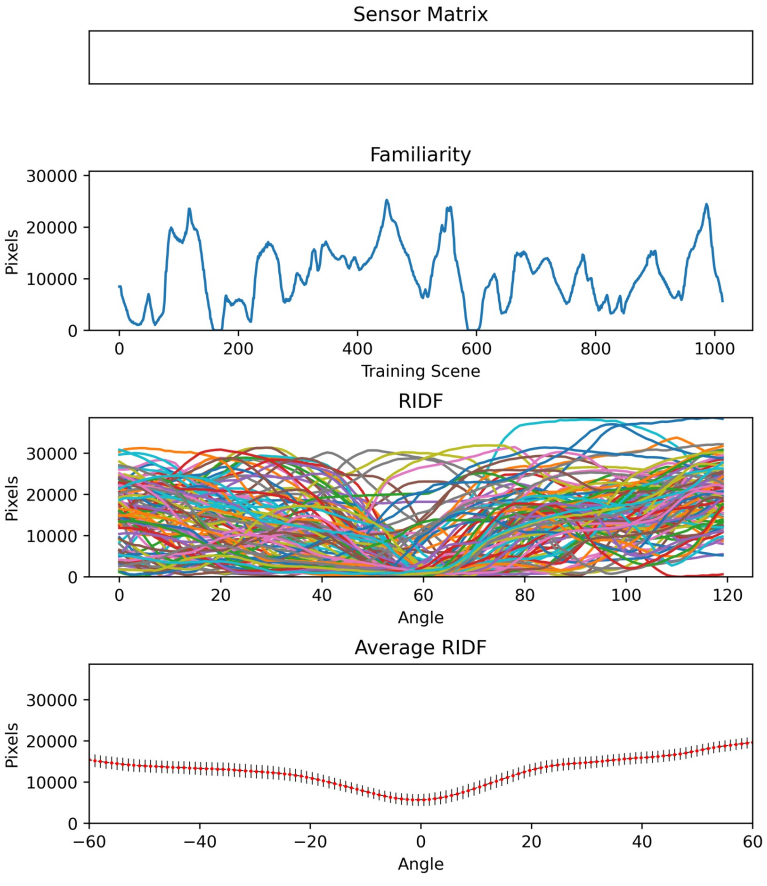


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 7415.31; RMSD/dist: 18.538; TD: 9271; p90: 86; p50: 40; complete: 0

0%

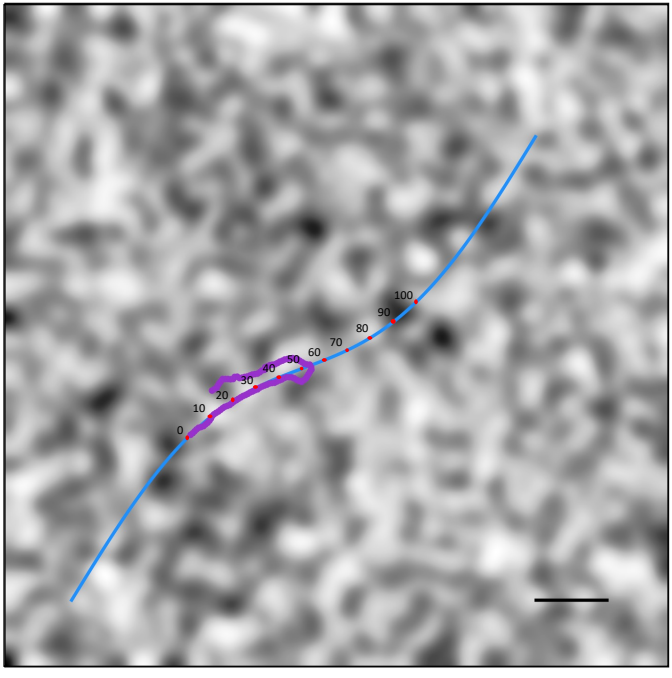


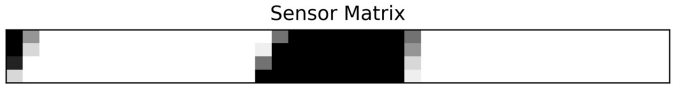


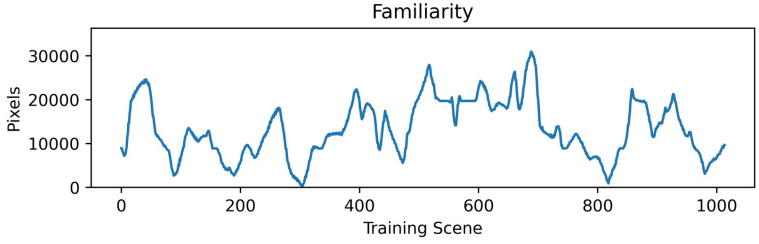
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

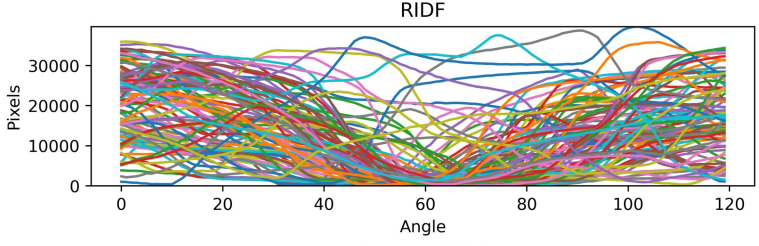
Navigation stats: RMSD error: 2292.31; RMSD/dist: 5.731; TD: 6289; p90: 44; p50: 28; complete: 0

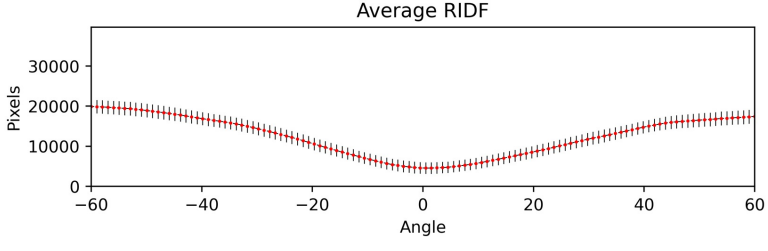
30%







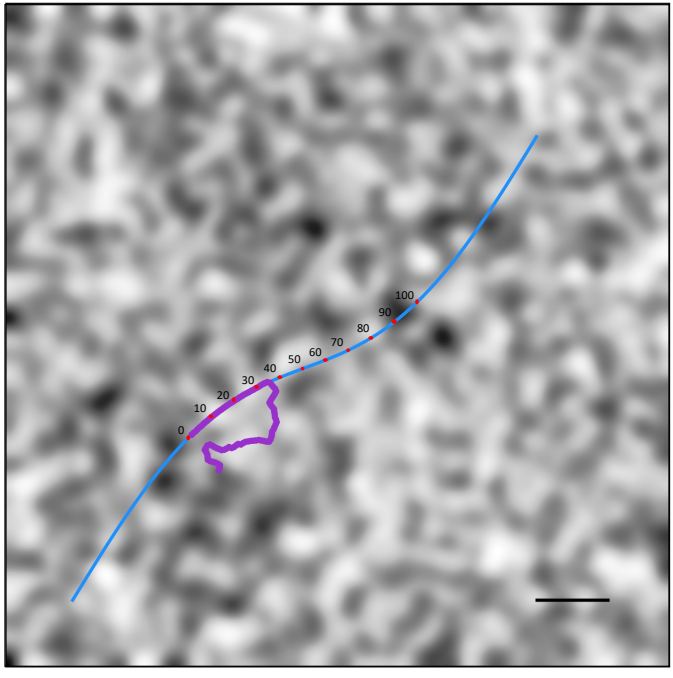


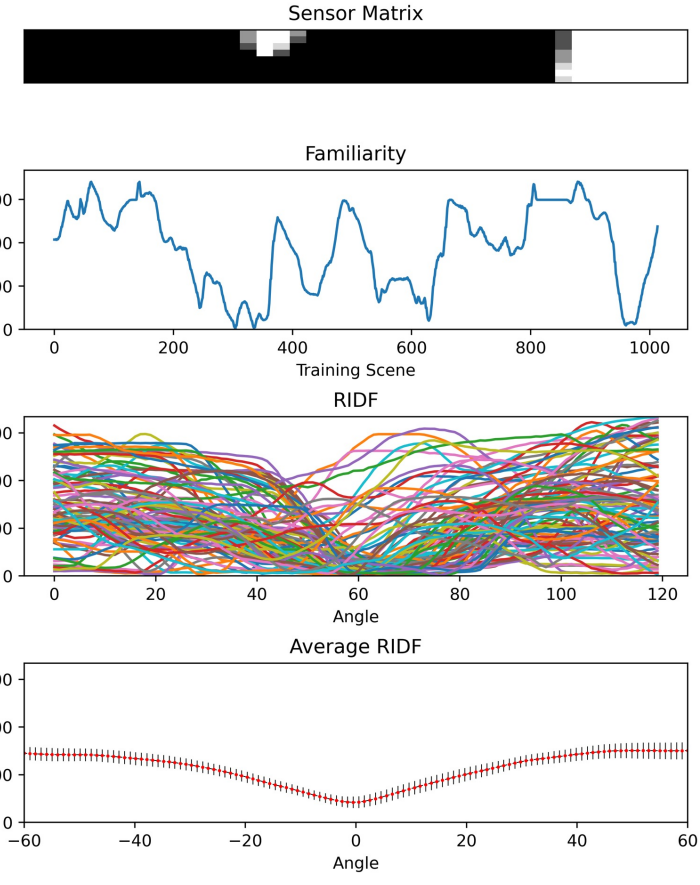


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1195.41; RMSD/dist: 2.989; TD: 9293; p90: 52; p50: 34; complete: 0

30%

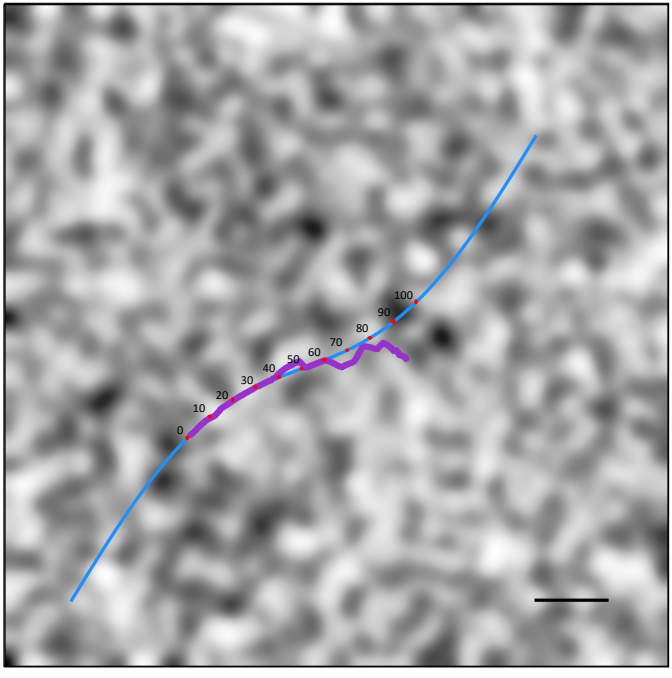


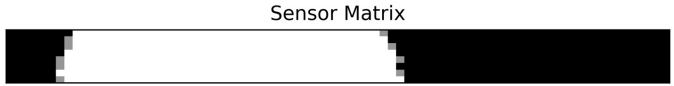


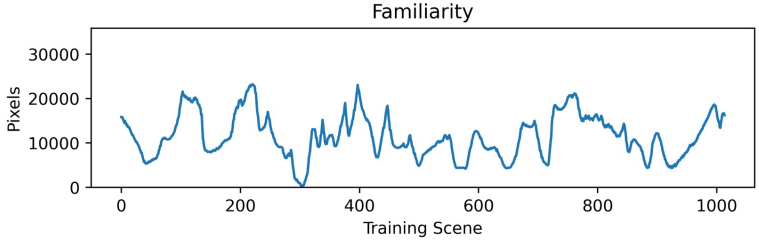
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

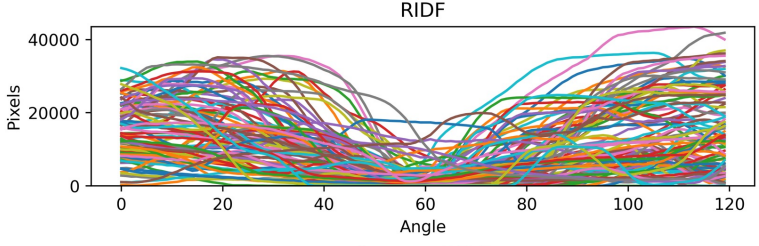
Navigation stats: RMSD error: 3102.21; RMSD/dist: 7.756; TD: 12005; p90: 120; p50: 46; complete: 0

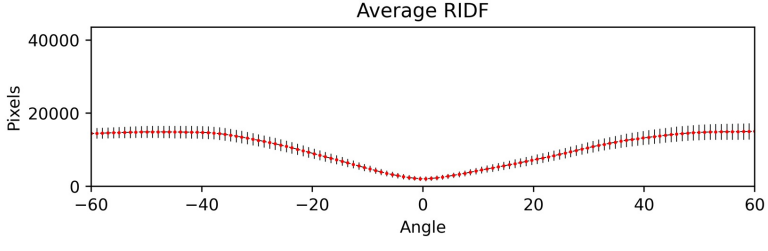
40%







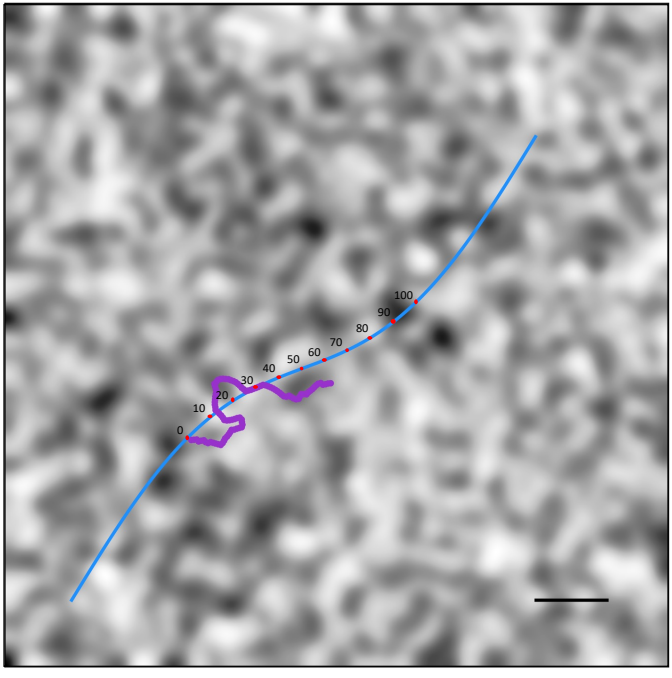


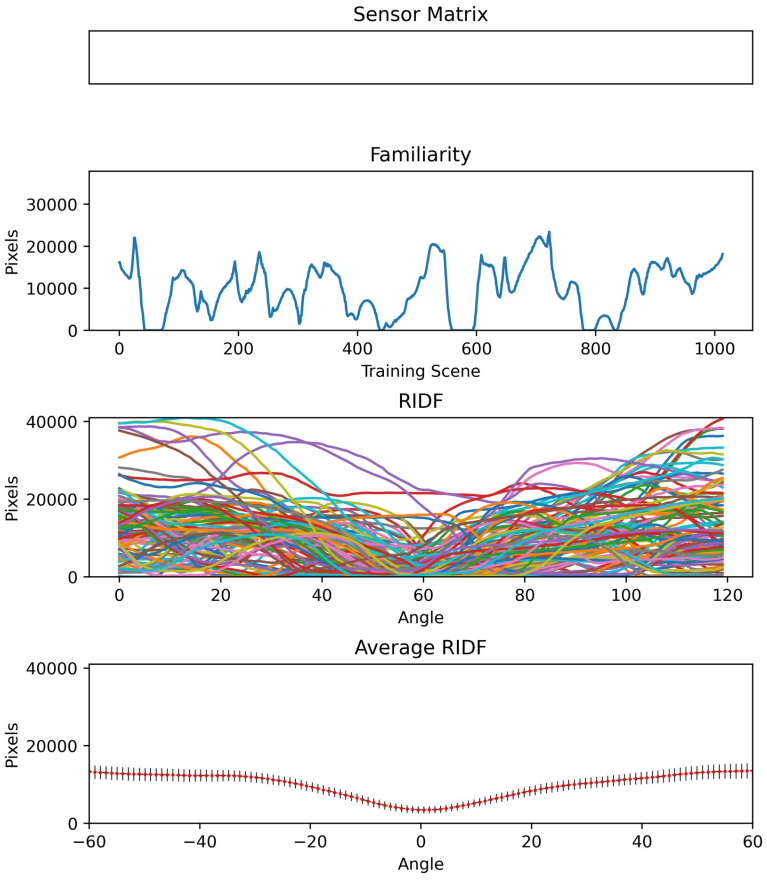


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 944.58; RMSD/dist: 2.361; TD: 9884; p90: 50; p50: 30; complete: 0

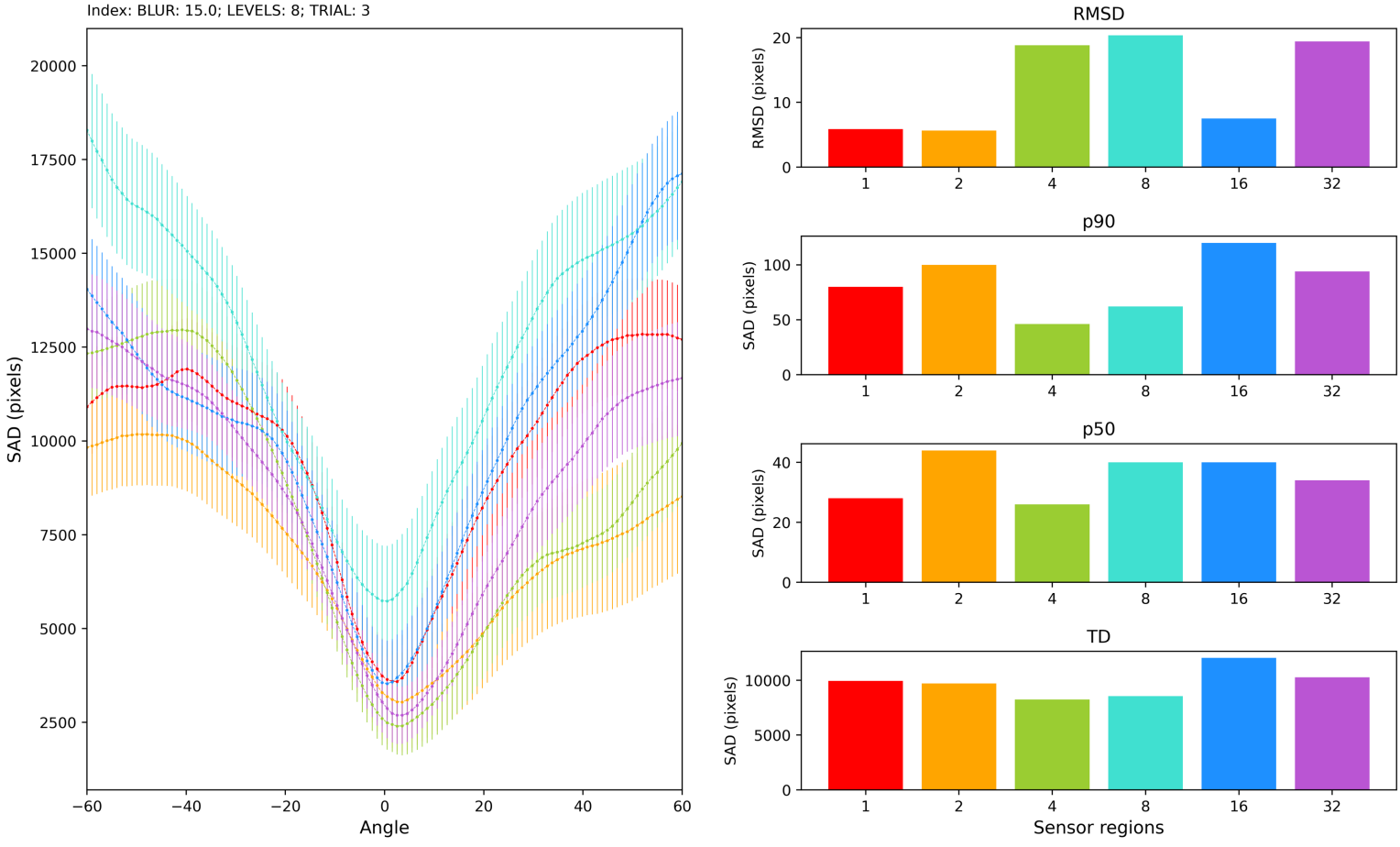
0%



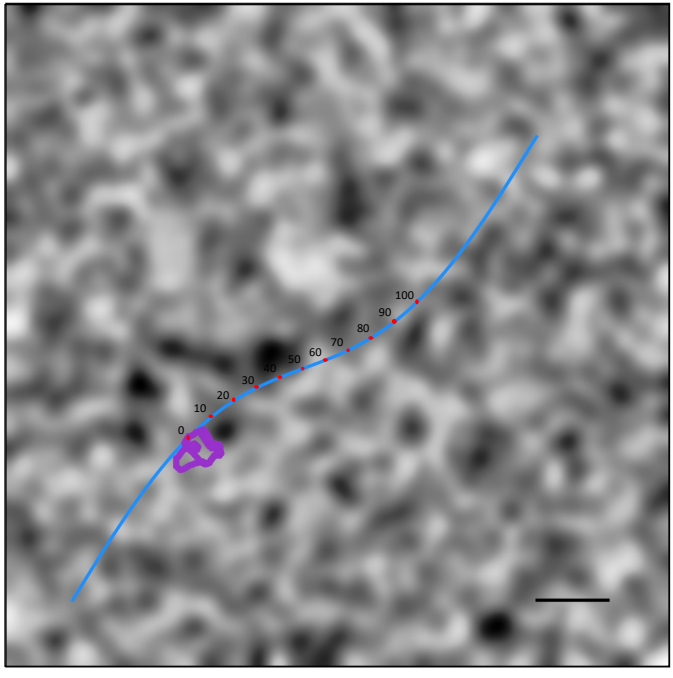


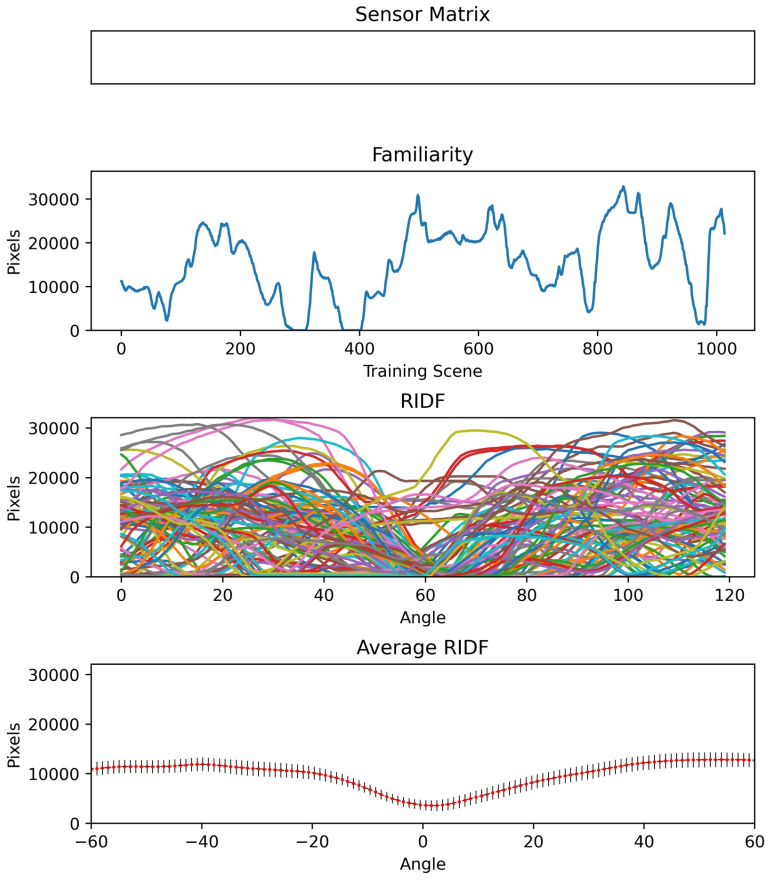
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2441.50; RMSD/dist: 6.104; TD: 9489; p90: 62; p50: 34; complete: 0


Index: BLUR: 15.0; LEVELS: 8; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

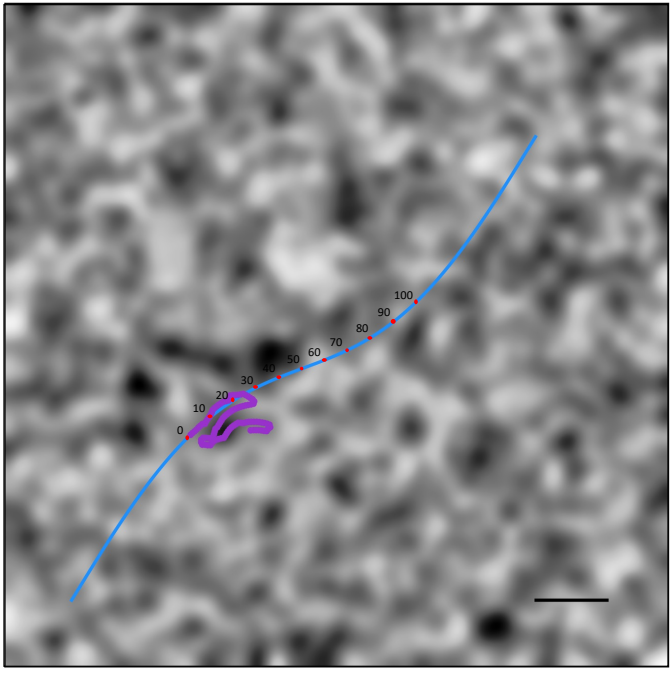


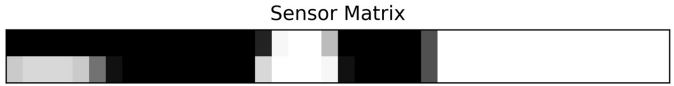


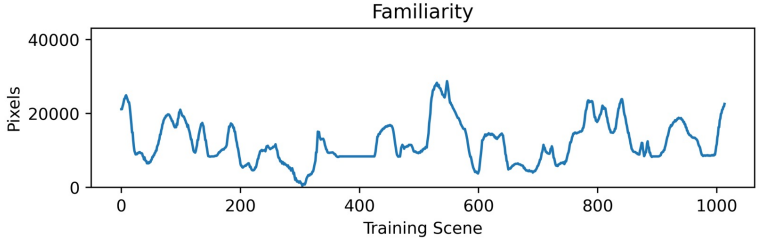
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

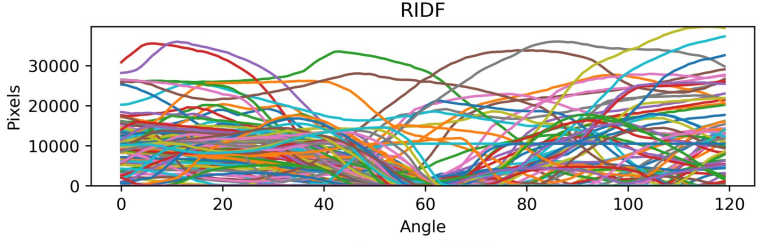
Navigation stats: RMSD error: 2342.77; RMSD/dist: 5.857; TD: 9943; p90: 80; p50: 28; complete: 0

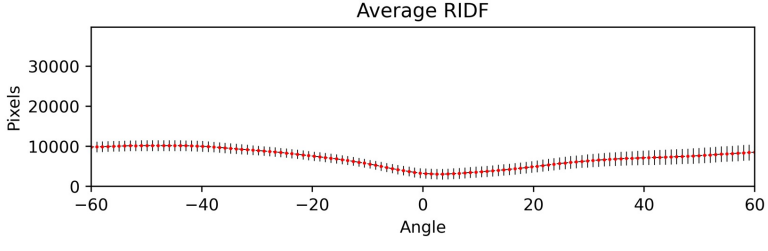
10%







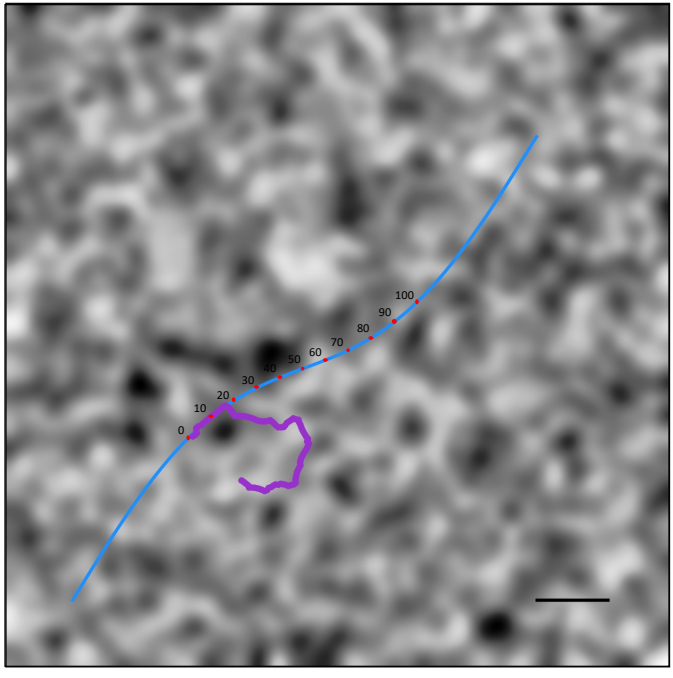


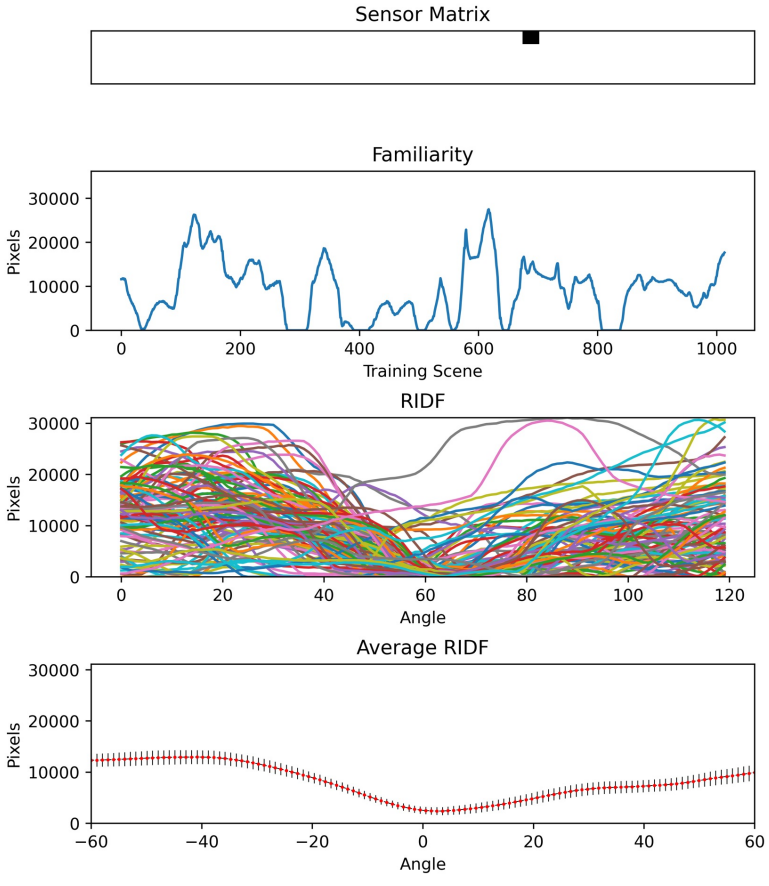


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2256.12; RMSD/dist: 5.640; TD: 9714; p90: 100; p50: 44; complete: 0

10%

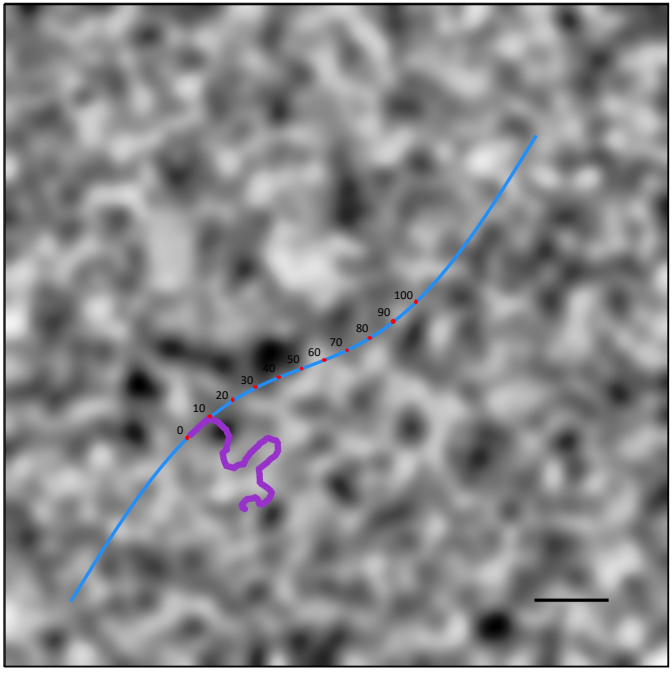


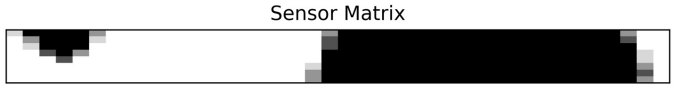


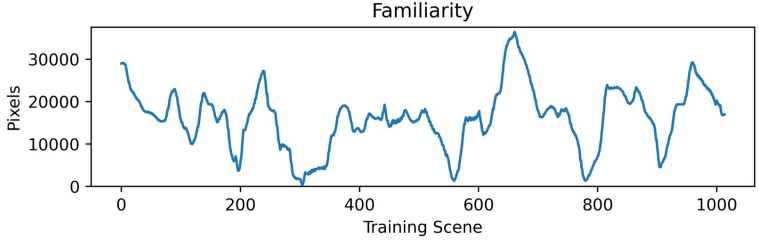
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

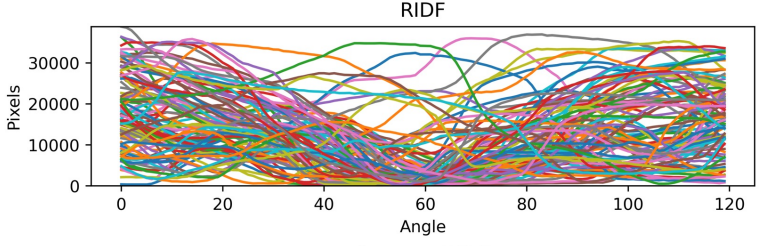
Navigation stats: RMSD error: 7529.82; RMSD/dist: 18.825; TD: 8254; p90: 46; p50: 26; complete: 0

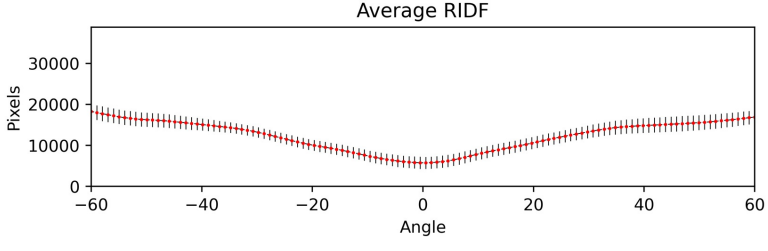
10%







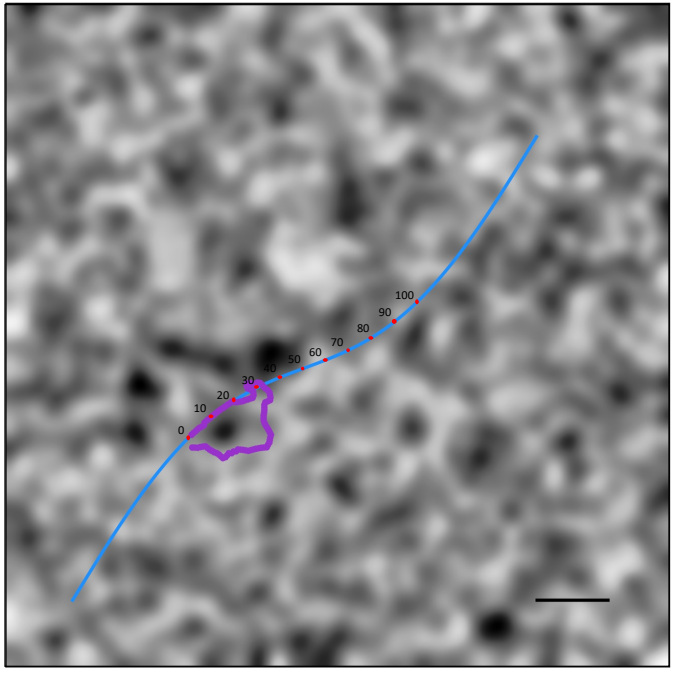


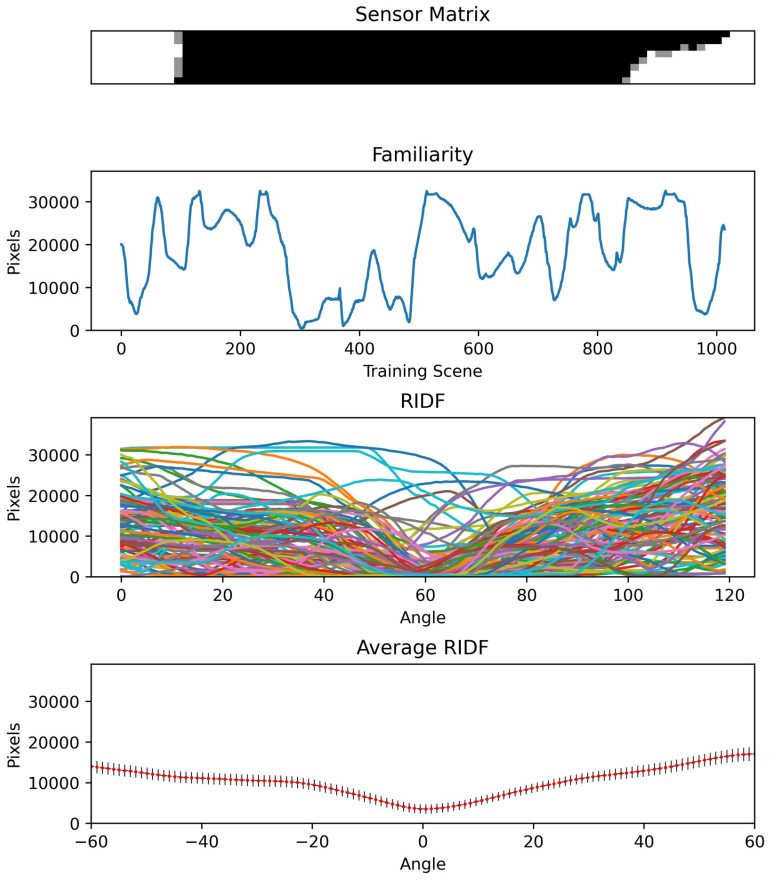


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 8151.77; RMSD/dist: 20.379; TD: 8556; p90: 62; p50: 40; complete: 0

20%

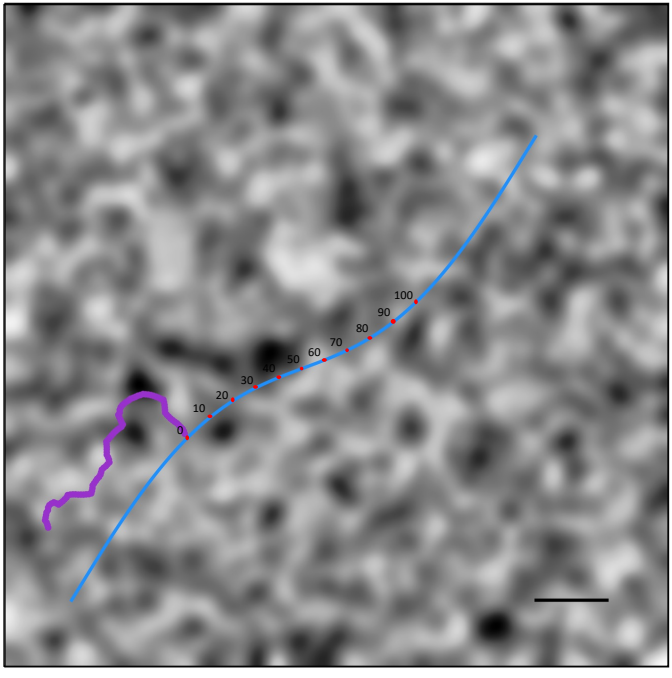


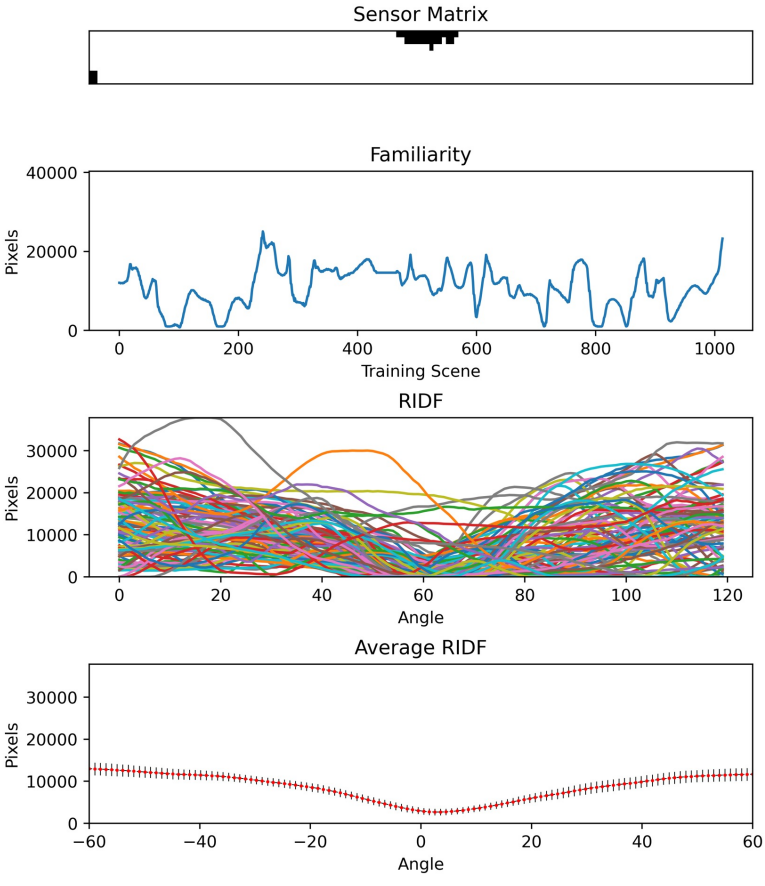


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 3004.95; RMSD/dist: 7.512; TD: 12041; p90: 120; p50: 40; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

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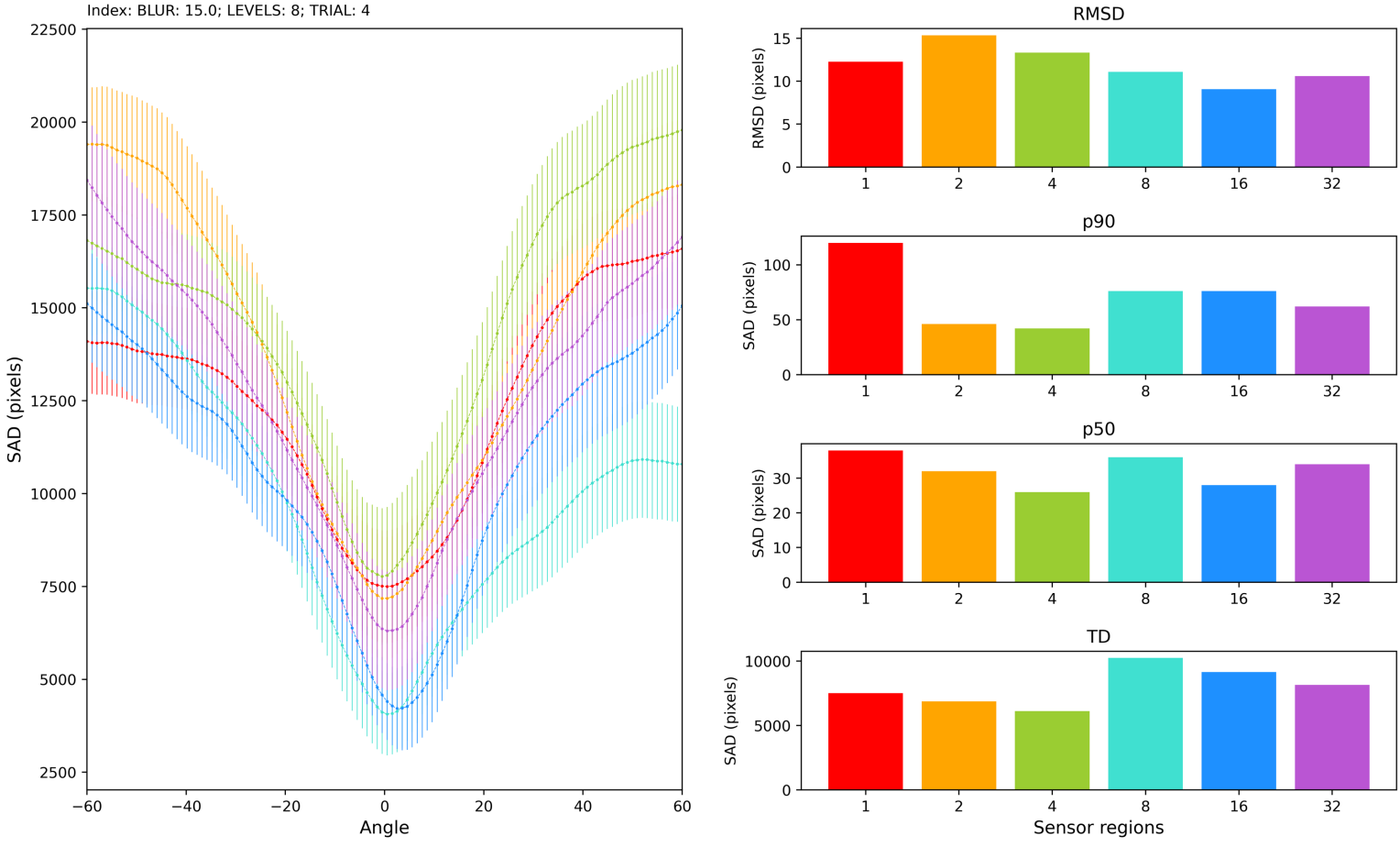
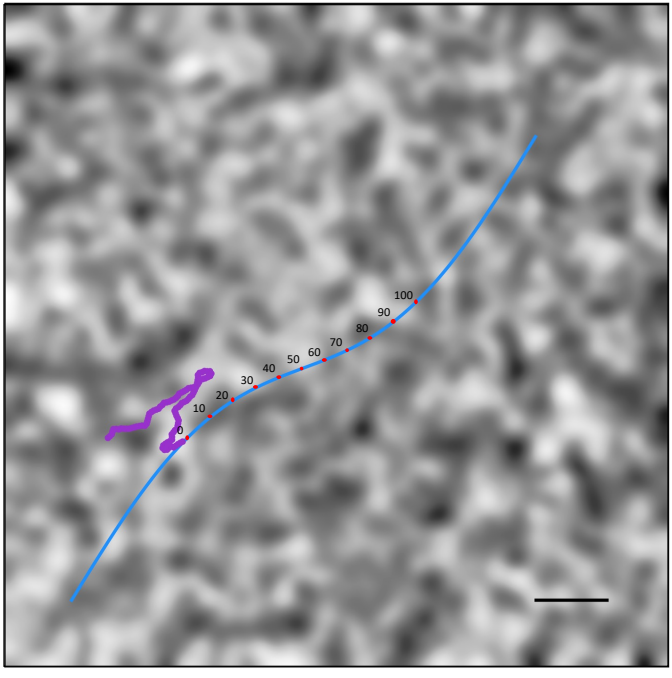
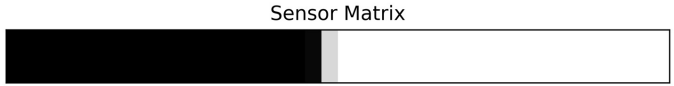
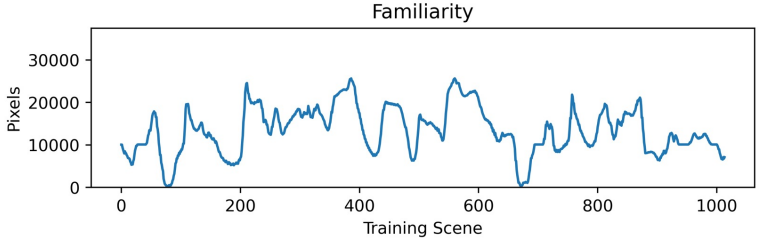
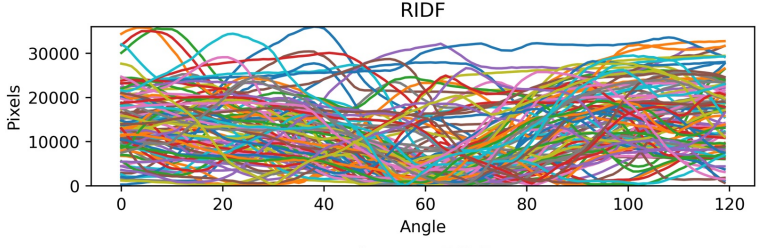

Index: BLUR: 15.0; LEVELS: 8; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

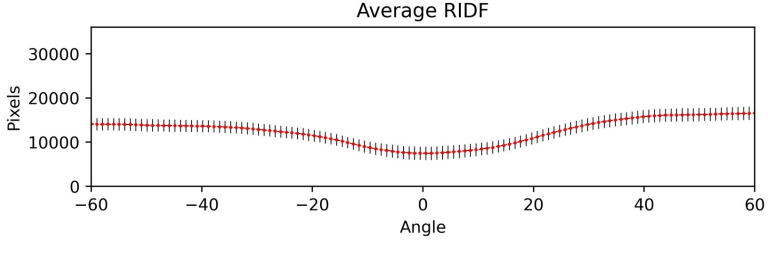
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4905.14; RMSD/dist: 12.263; TD: 7510; p90: 120; p50: 38; complete: 0

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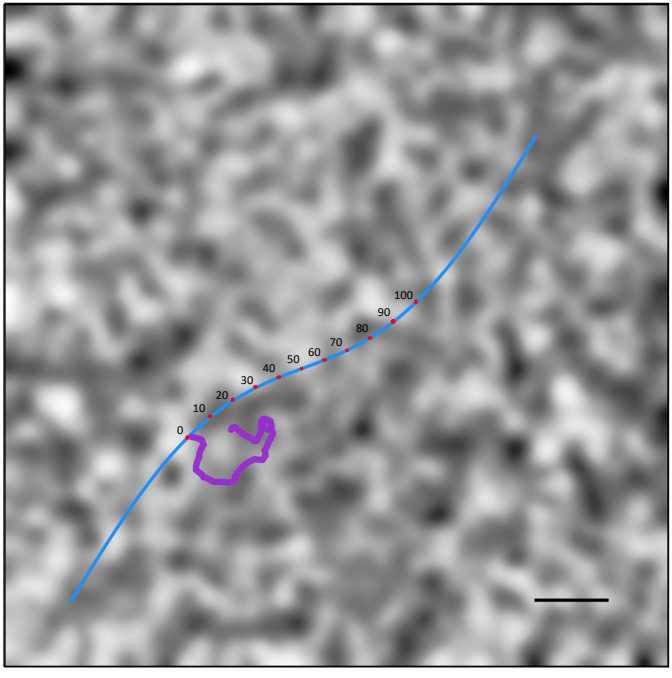
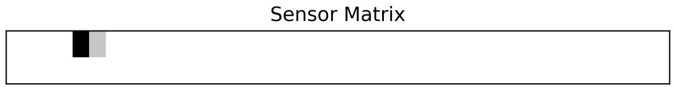
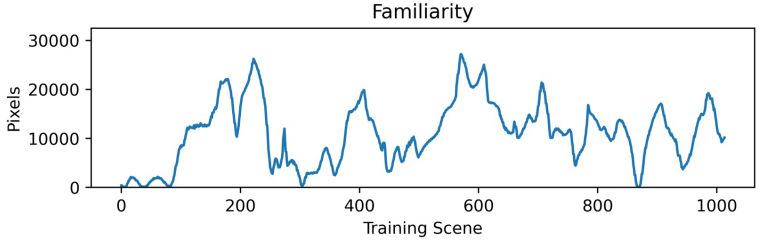
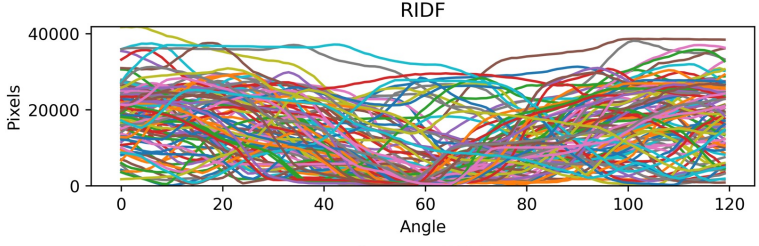
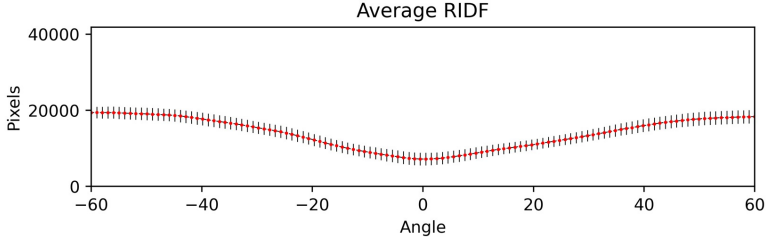






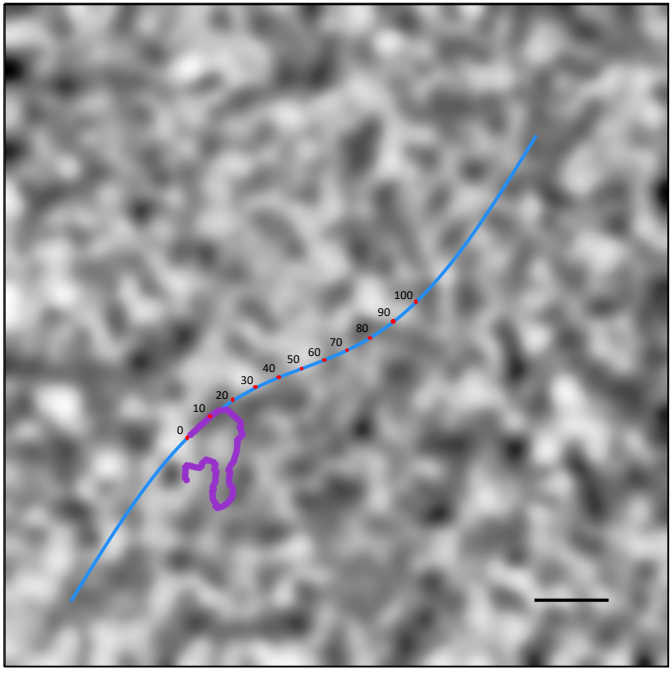


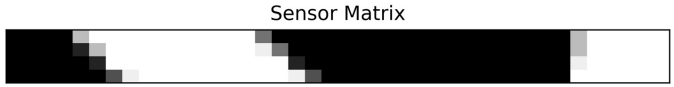


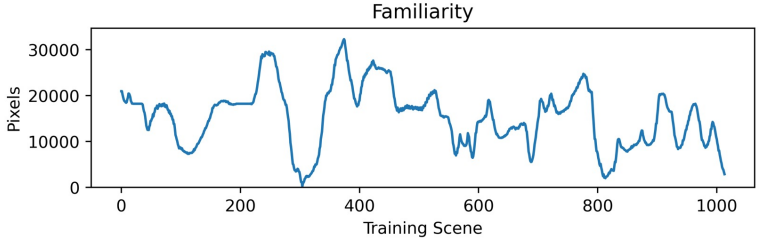
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

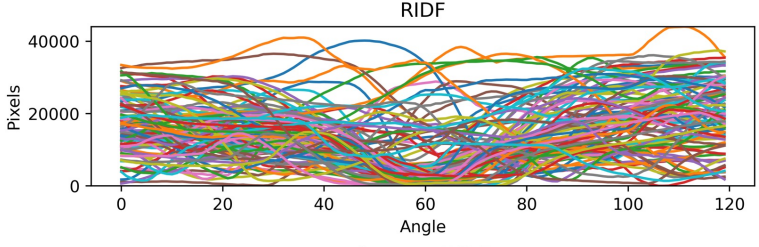
Navigation stats: RMSD error: 6141.83; RMSD/dist: 15.355; TD: 6874; p90: 46; p50: 32; complete: 0

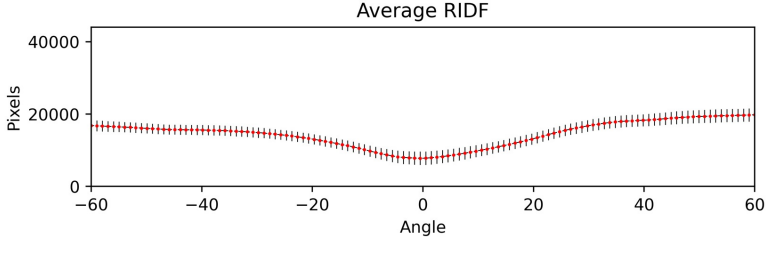
10%







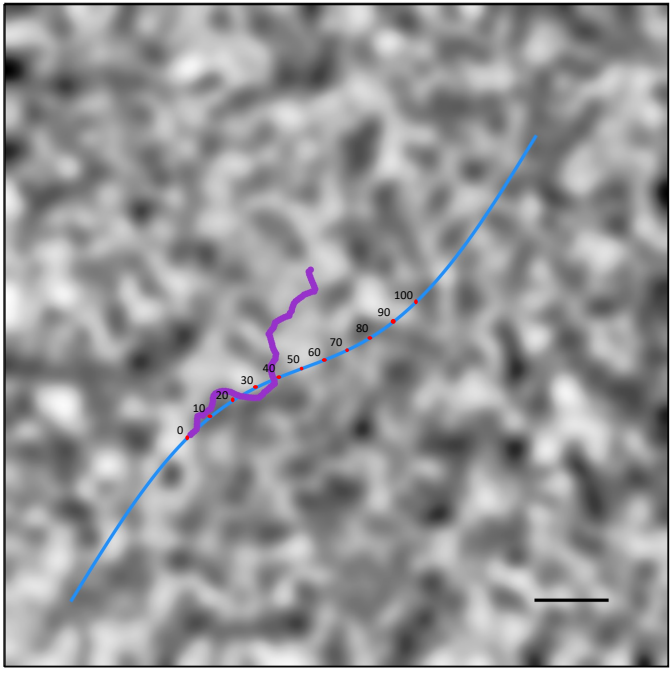


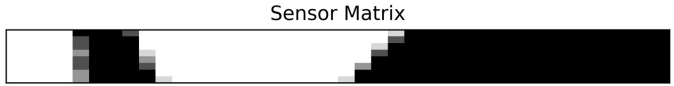


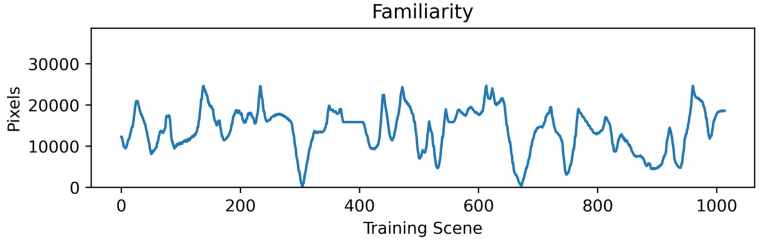
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

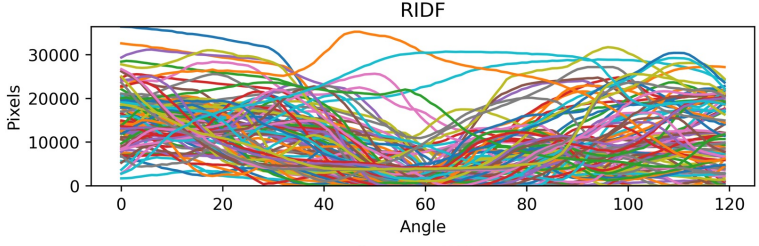
Navigation stats: RMSD error: 5329.63; RMSD/dist: 13.324; TD: 6114; p90: 42; p50: 26; complete: 0

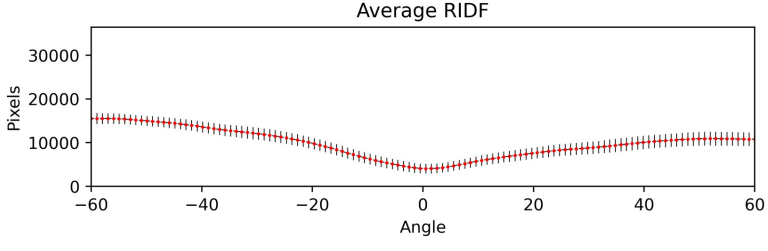
0%







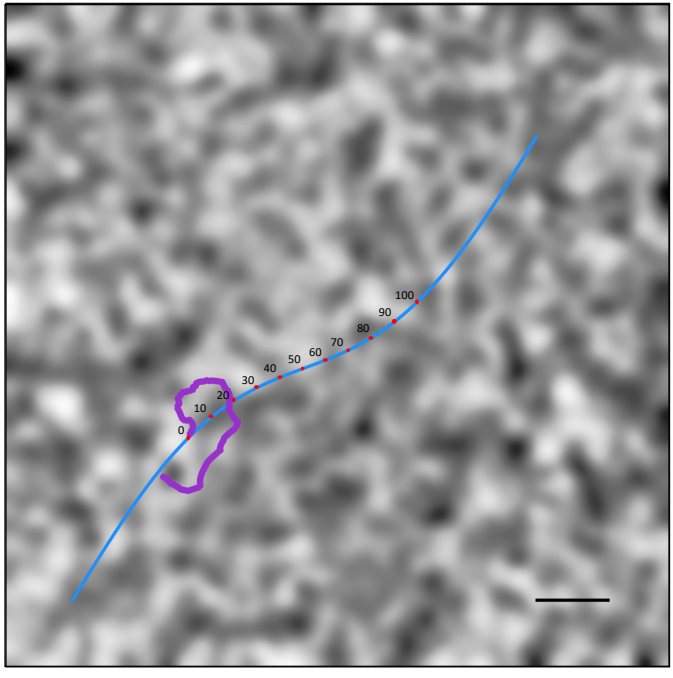


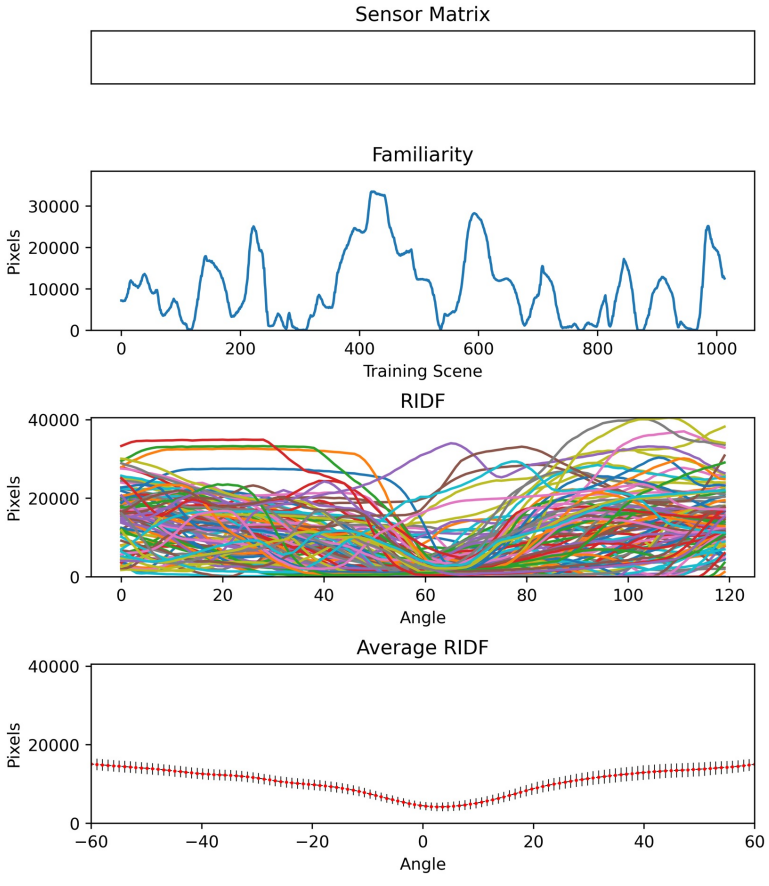


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4434.28; RMSD/dist: 11.086; TD: 10238; p90: 76; p50: 36; complete: 0

0%

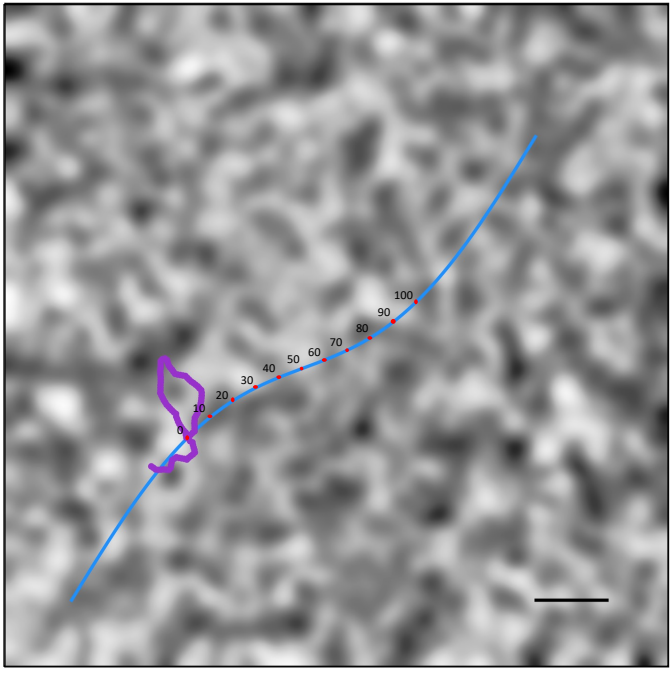


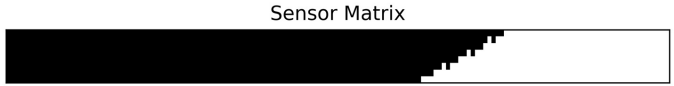


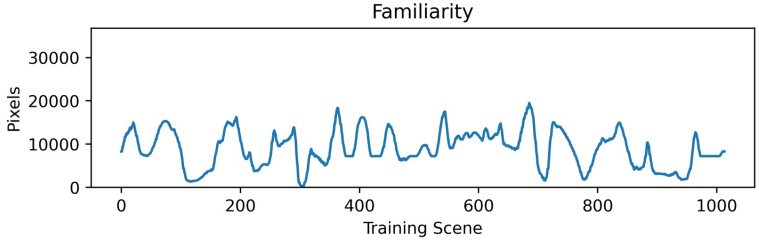
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

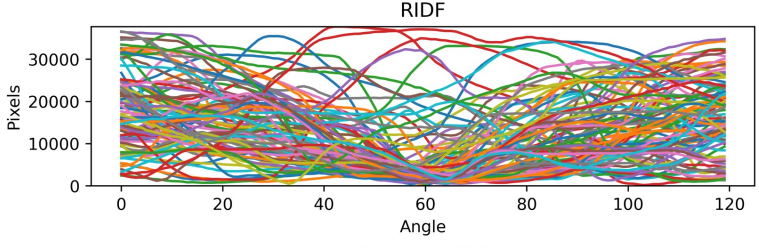
Navigation stats: RMSD error: 3630.09; RMSD/dist: 9.075; TD: 9154; p90: 76; p50: 28; complete: 0

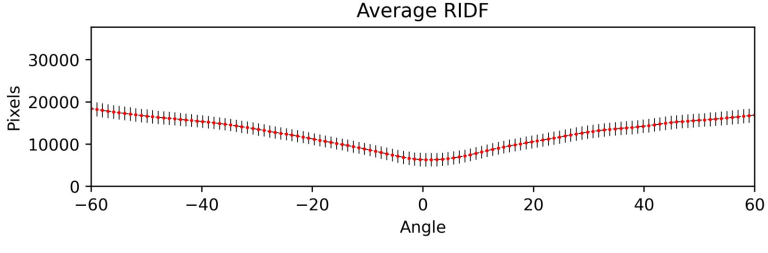
0%





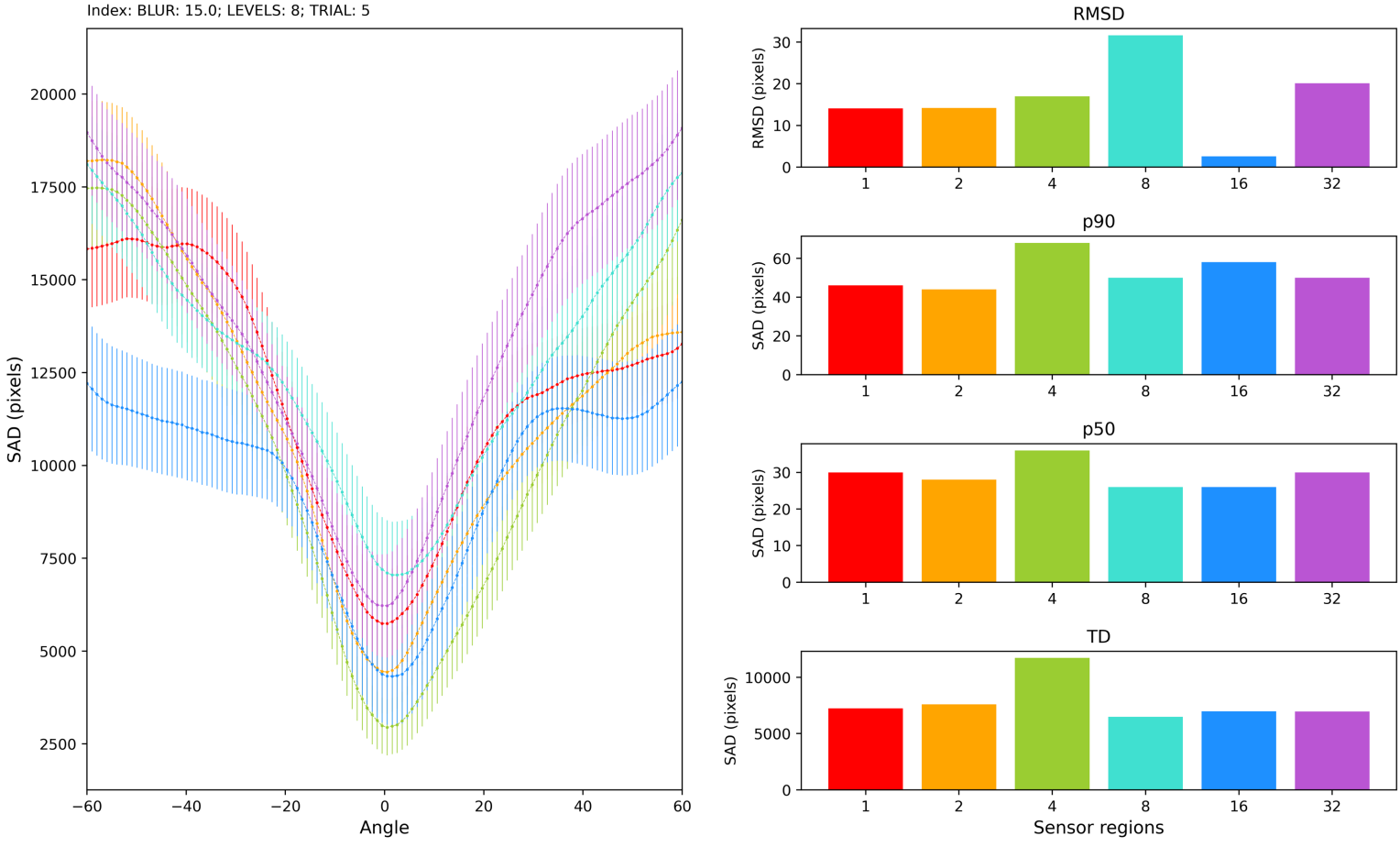




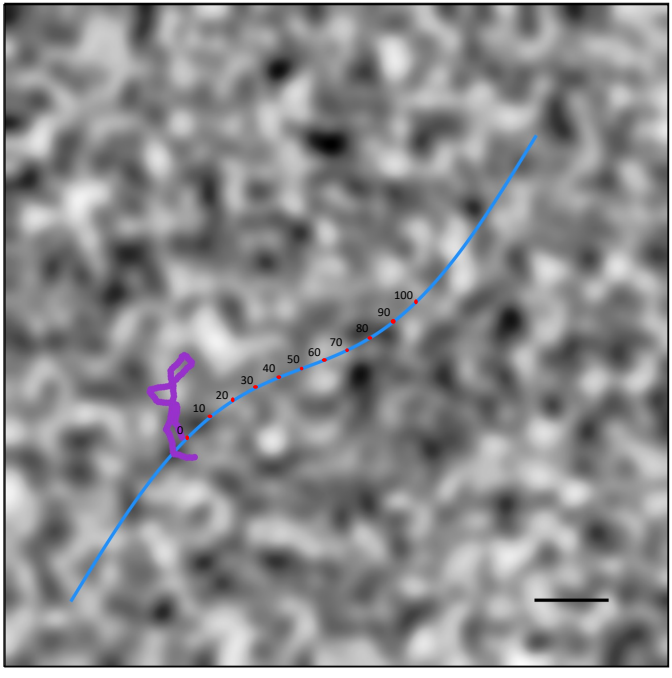


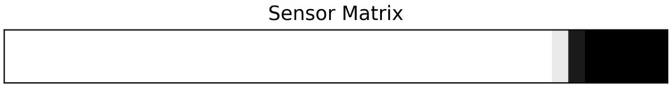
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

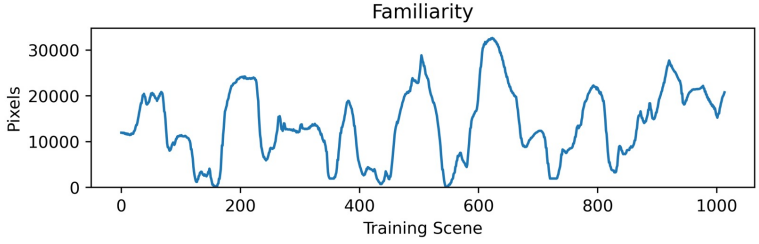
Navigation stats: RMSD error: 4234.71; RMSD/dist: 10.587; TD: 8141; p90: 62; p50: 34; complete: 0

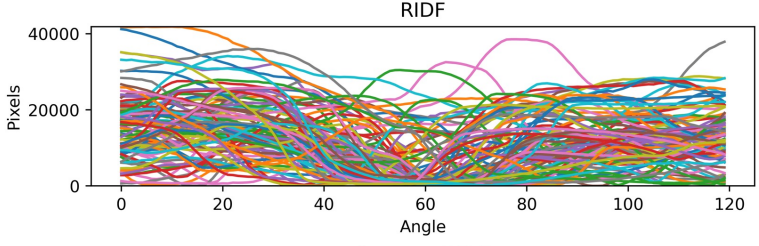

Index: BLUR: 15.0; LEVELS: 8; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

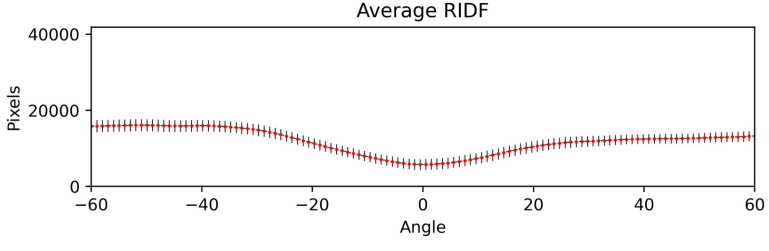
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5632.38; RMSD/dist: 14.081; TD: 7238; p90: 46; p50: 30; complete: 0

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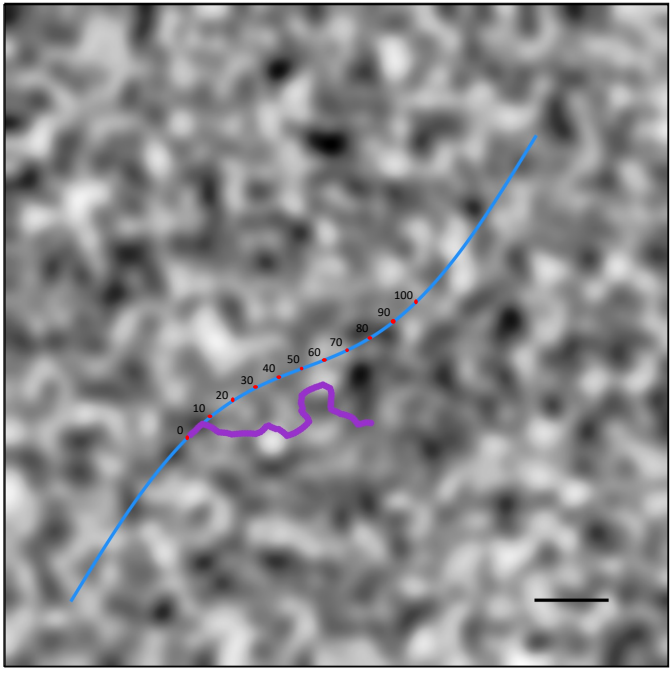
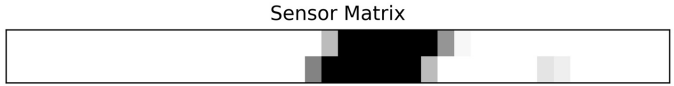
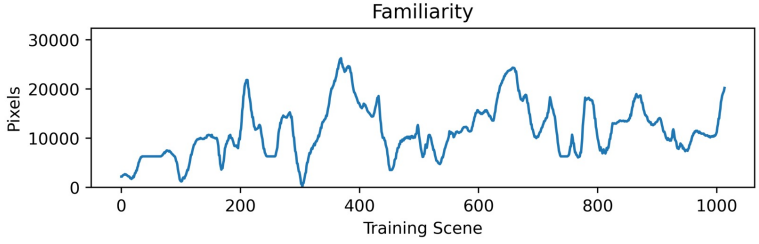
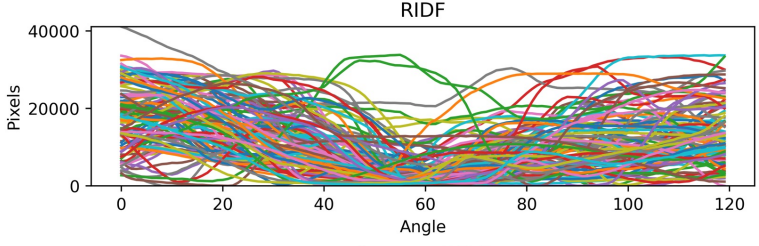
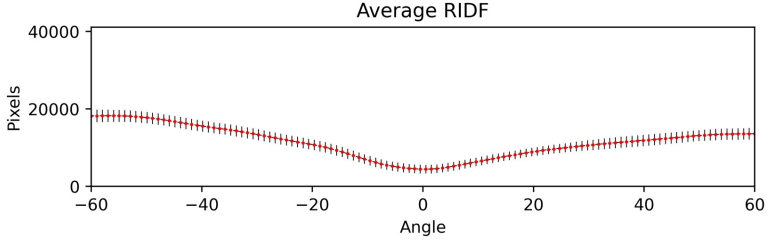






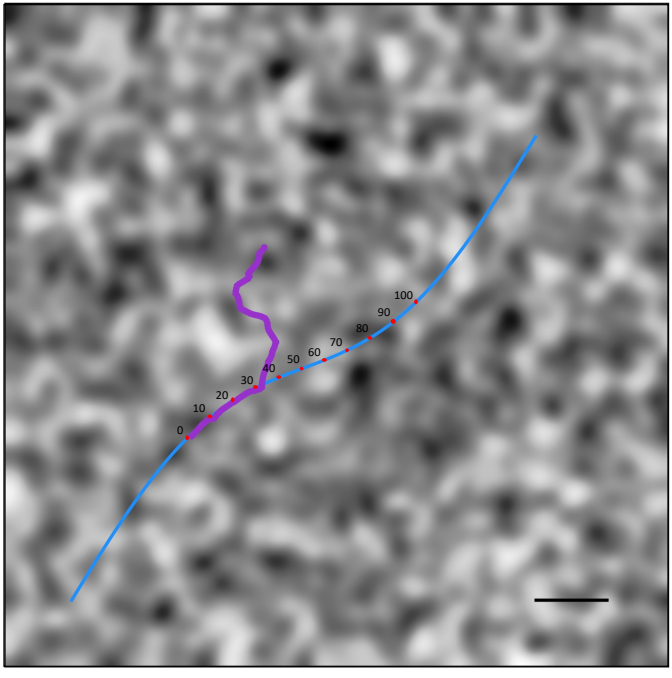


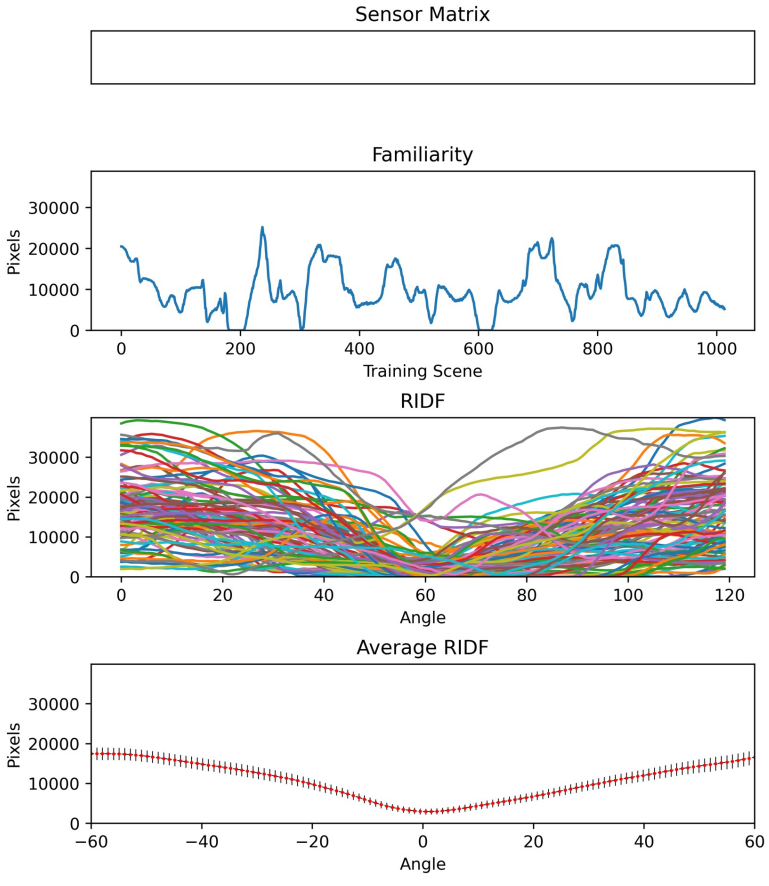


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5674.77; RMSD/dist: 14.187; TD: 7601; p90: 44; p50: 28; complete: 0

20%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 6790.93; RMSD/dist: 16.977; TD: 11712; p90: 68; p50: 36; complete: 0

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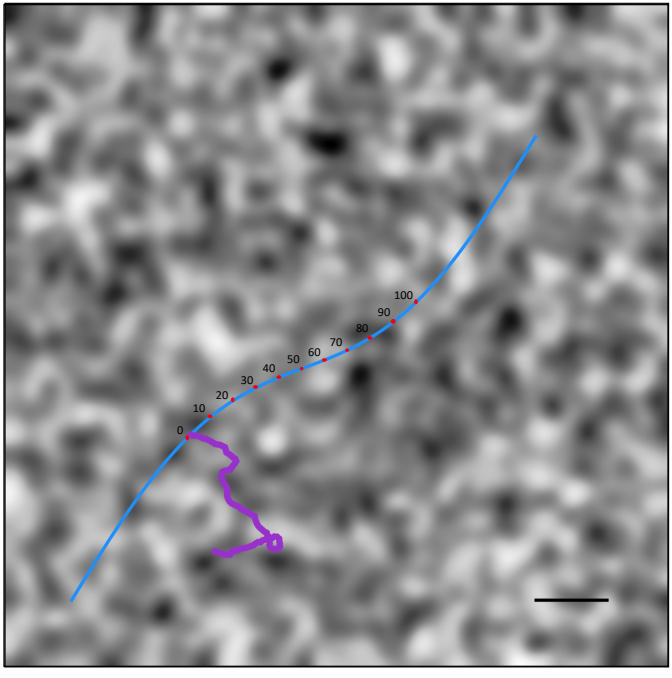
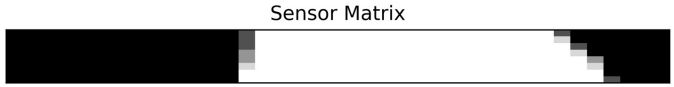
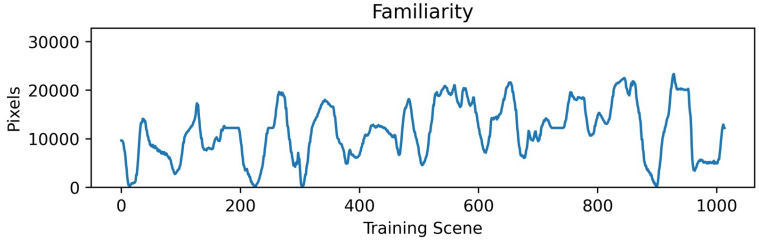
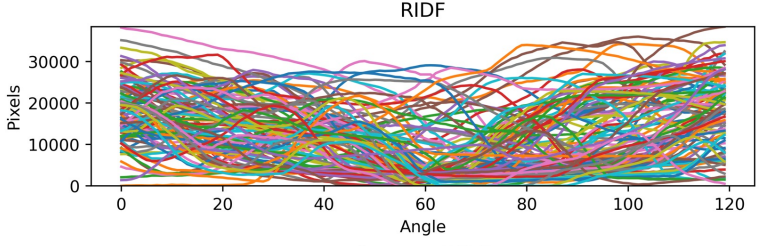
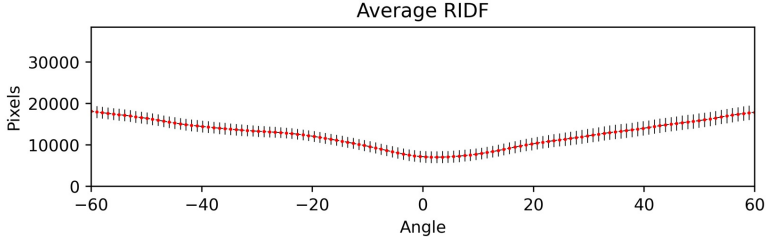






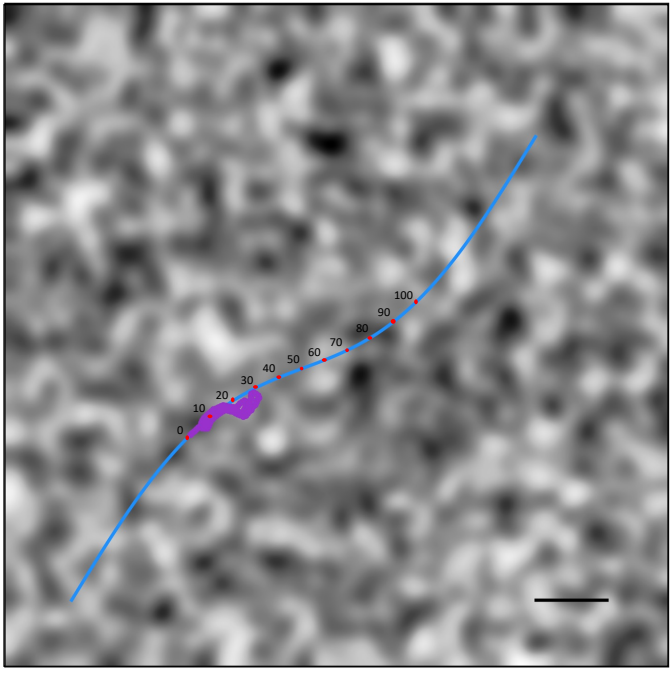


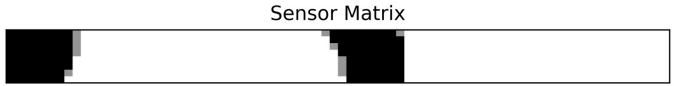


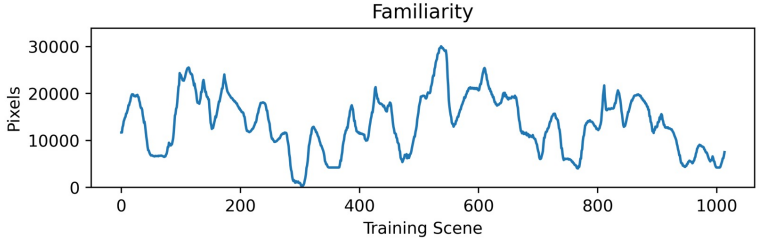
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

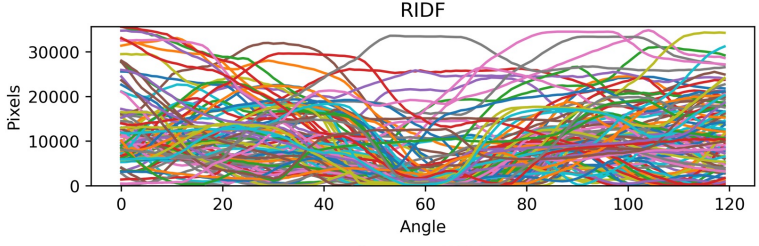
Navigation stats: RMSD error: 12663.29; RMSD/dist: 31.658; TD: 6491; p90: 50; p50: 26; complete: 0

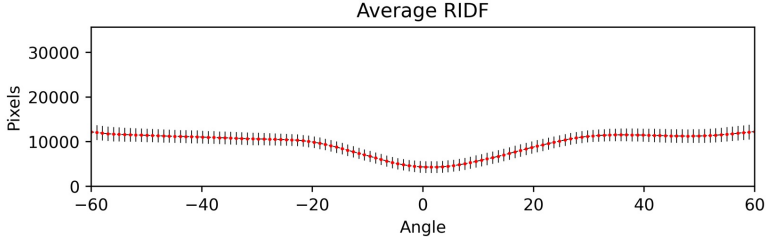
10%







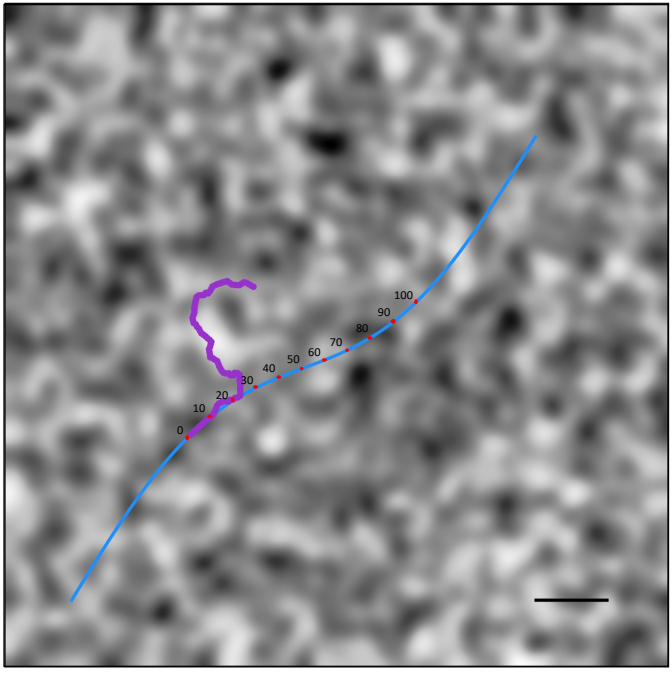


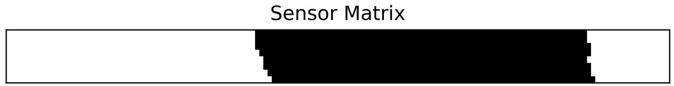


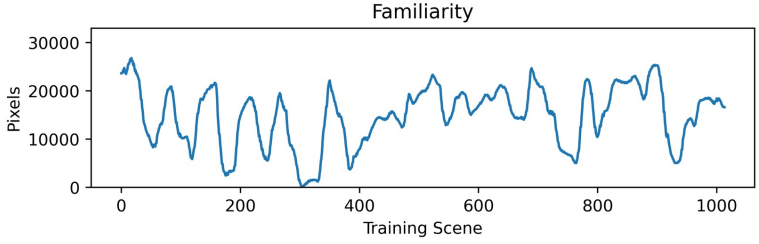
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

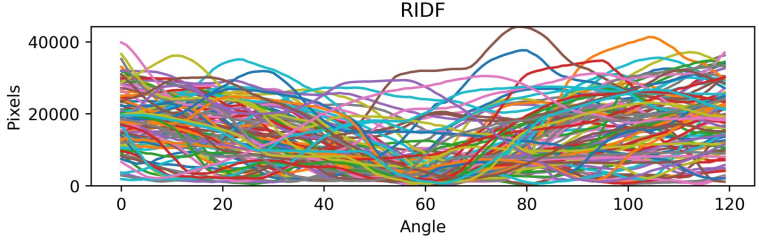
Navigation stats: RMSD error: 1037.84; RMSD/dist: 2.595; TD: 6972; p90: 58; p50: 26; complete: 0

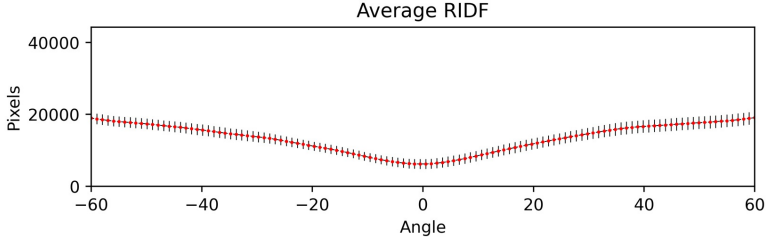
10%





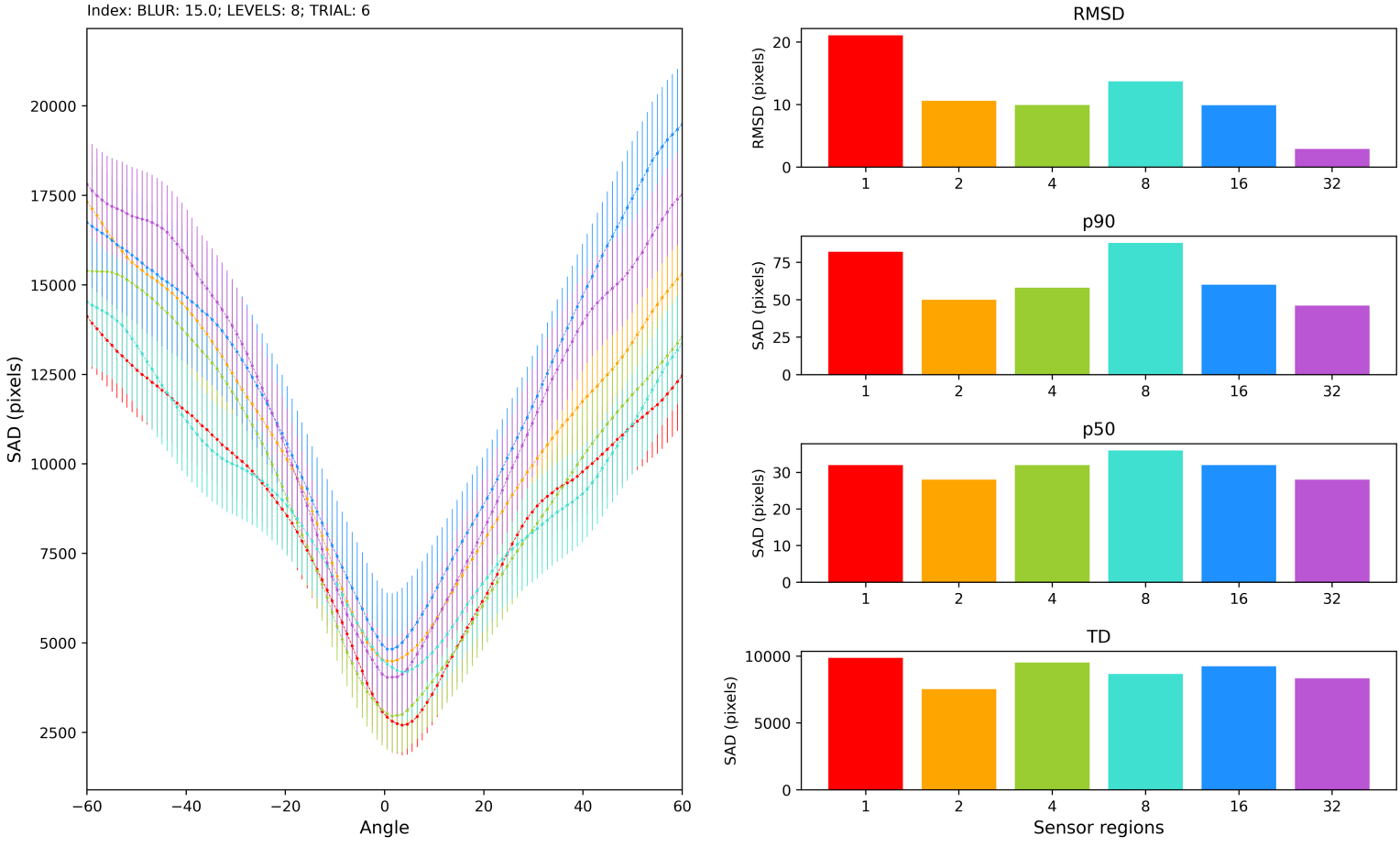




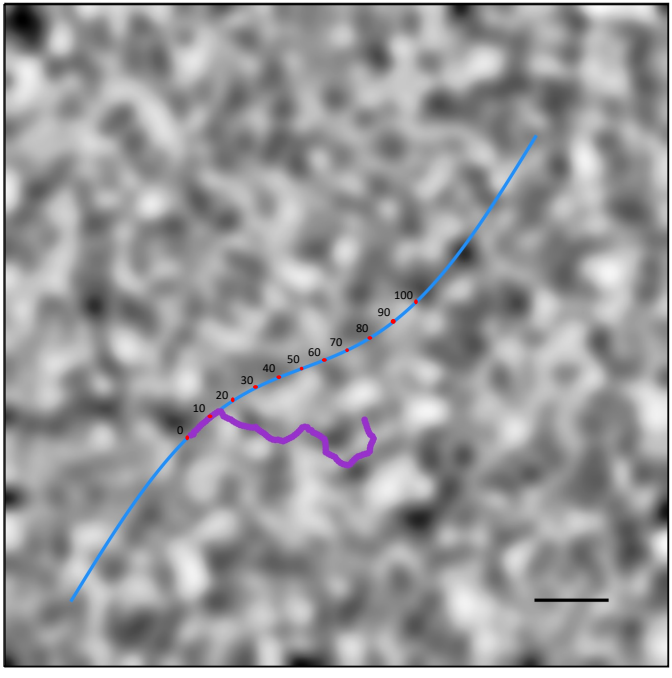


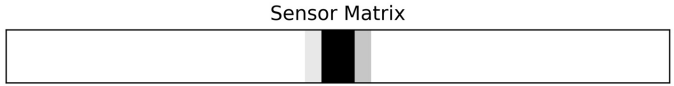
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

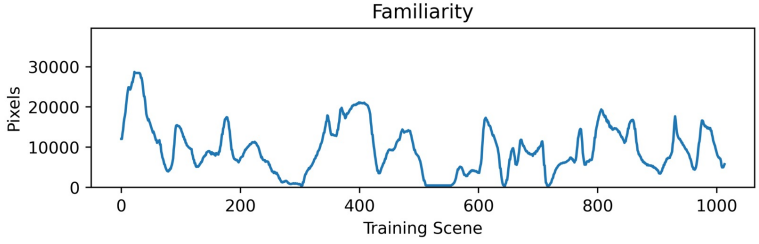
Navigation stats: RMSD error: 8051.08; RMSD/dist: 20.128; TD: 6956; p90: 50; p50: 30; complete: 0

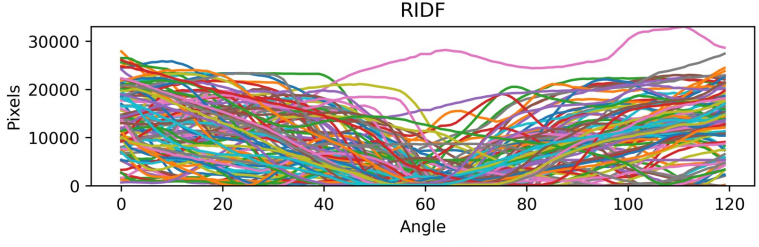

Index: BLUR: 15.0; LEVELS: 8; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

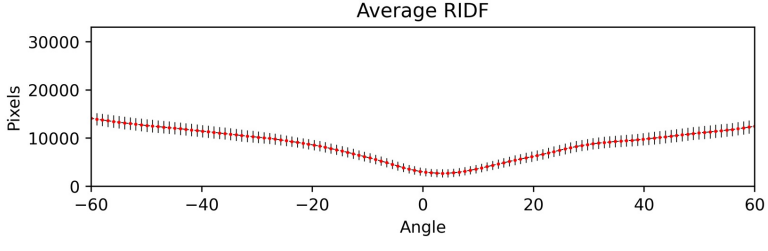
10%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 8443.40; RMSD/dist: 21.108; TD: 9859; p90: 82; p50: 32; complete: 0

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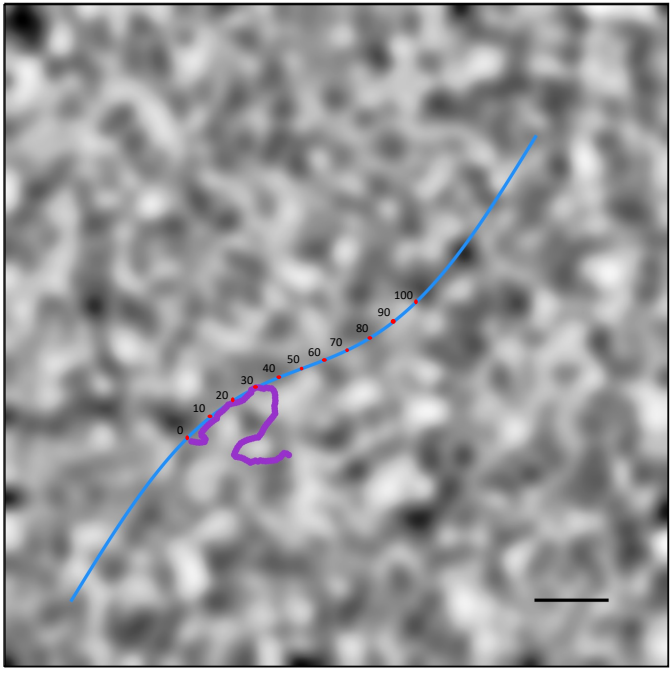
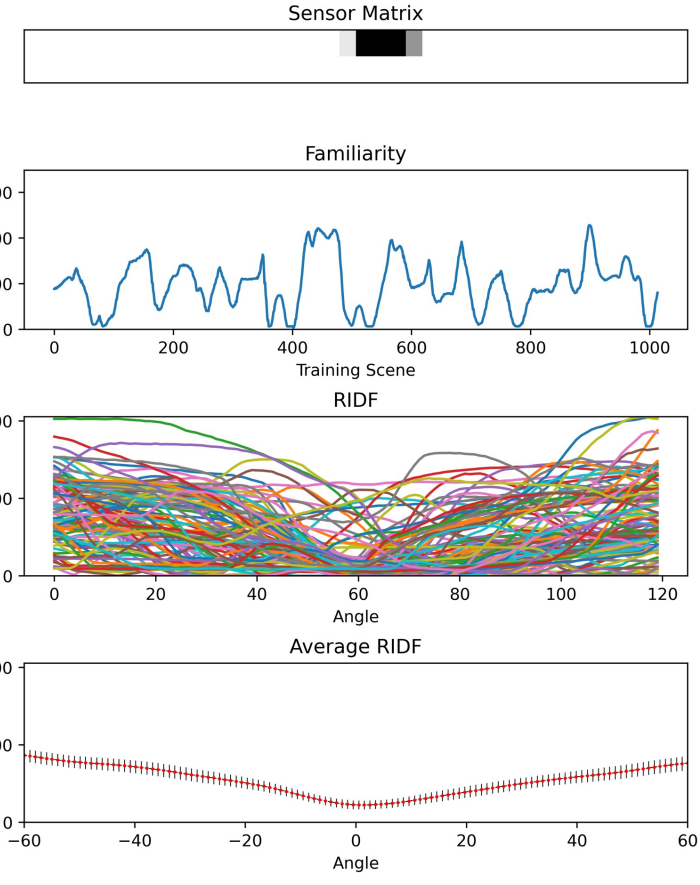
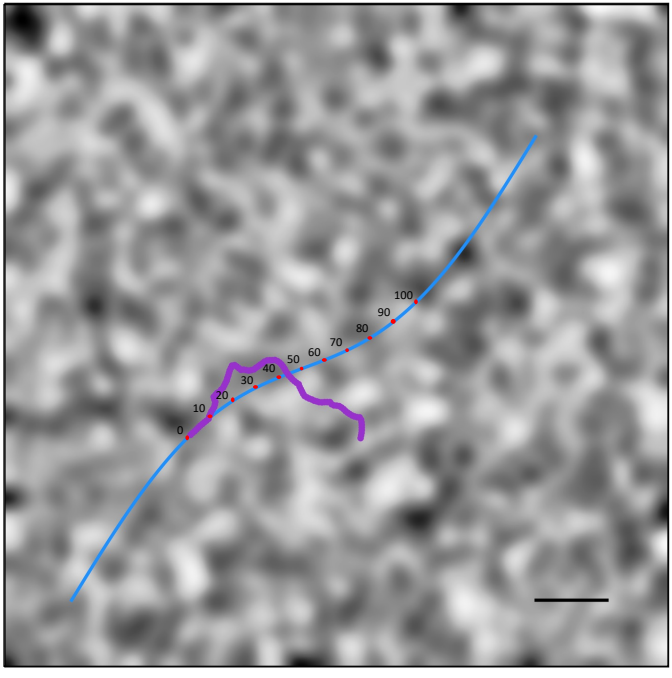


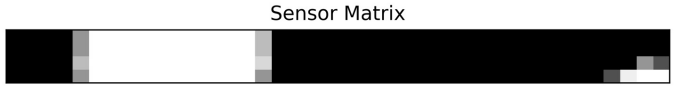


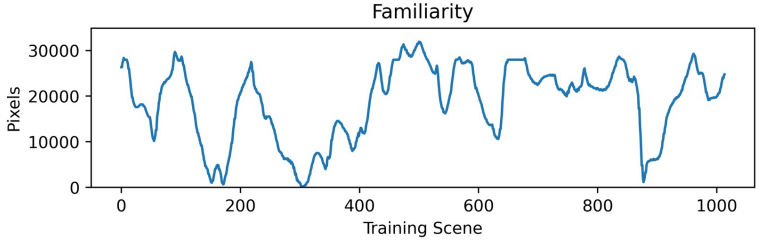
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

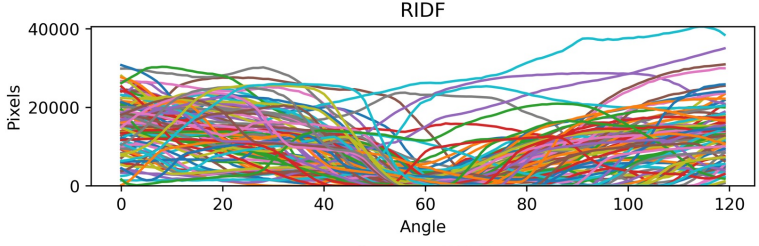
Navigation stats: RMSD error: 4237.79; RMSD/dist: 10.594; TD: 7527; p90: 50; p50: 28; complete: 0

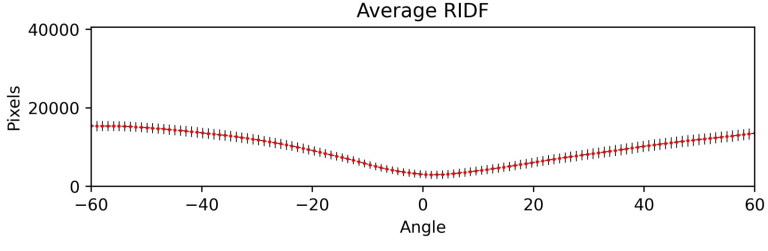
10%







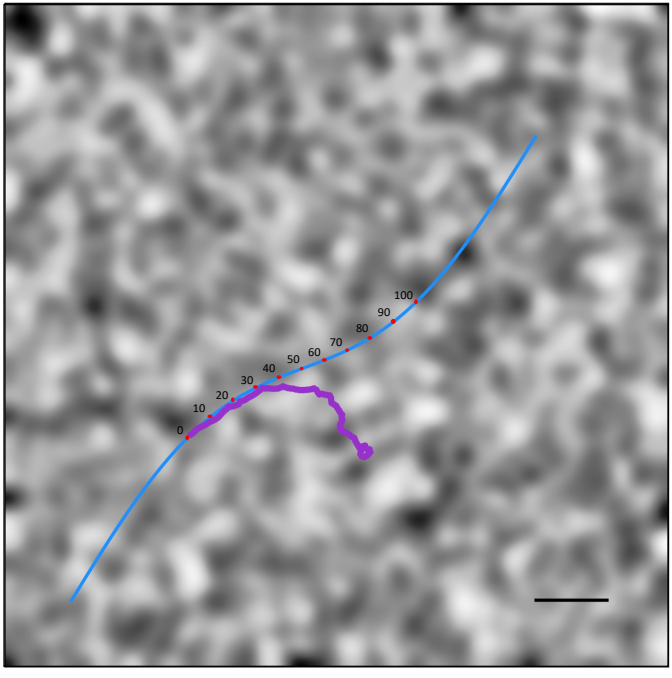


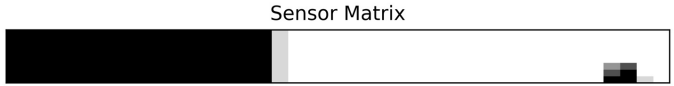


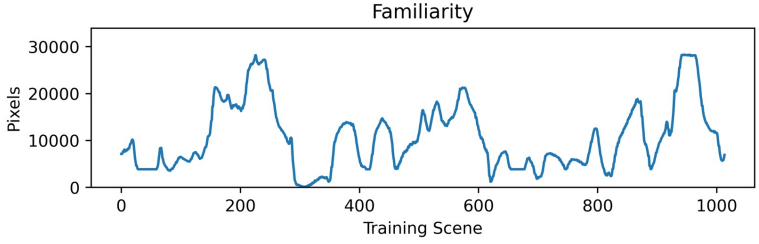
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

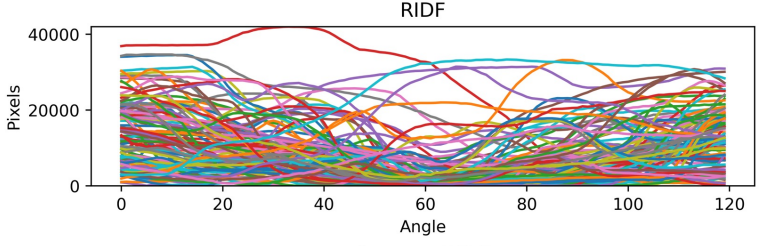
Navigation stats: RMSD error: 3975.31; RMSD/dist: 9.938; TD: 9515; p90: 58; p50: 32; complete: 0

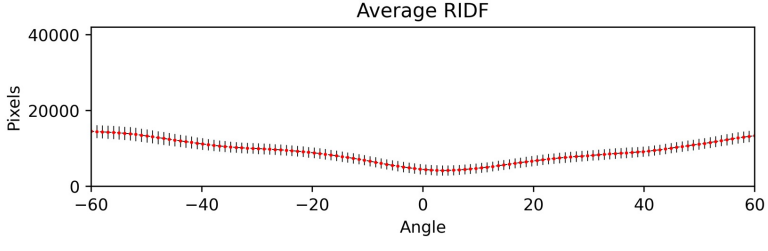
0%







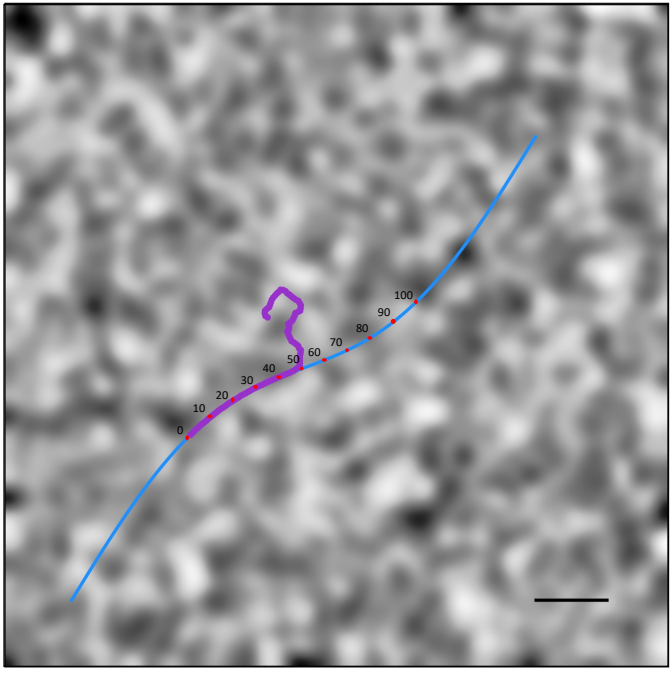


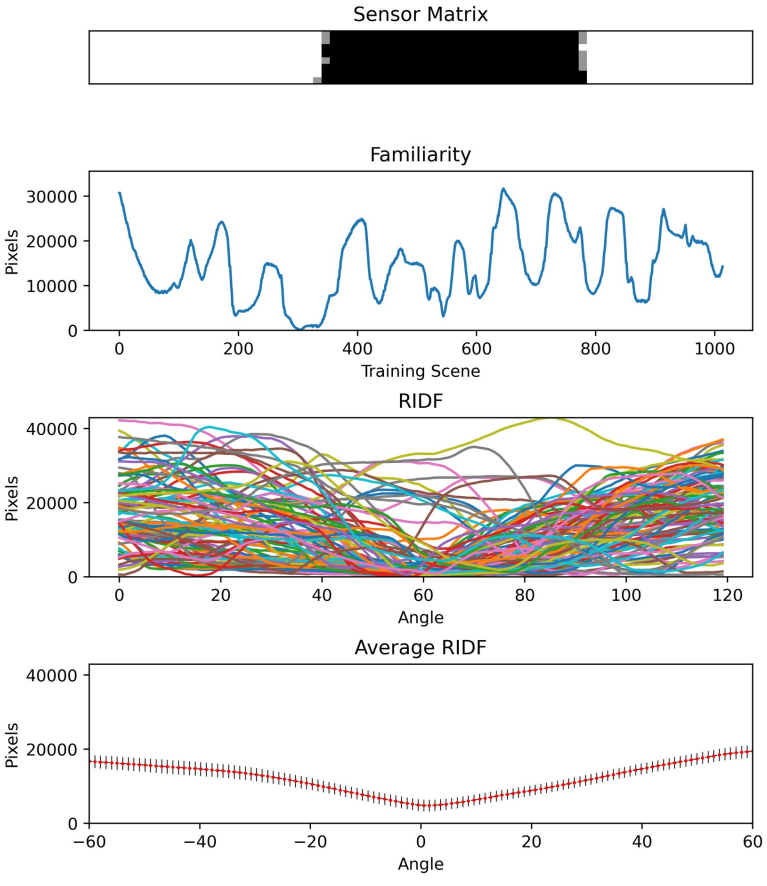


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 5486.59; RMSD/dist: 13.716; TD: 8663; p90: 88; p50: 36; complete: 0

50%

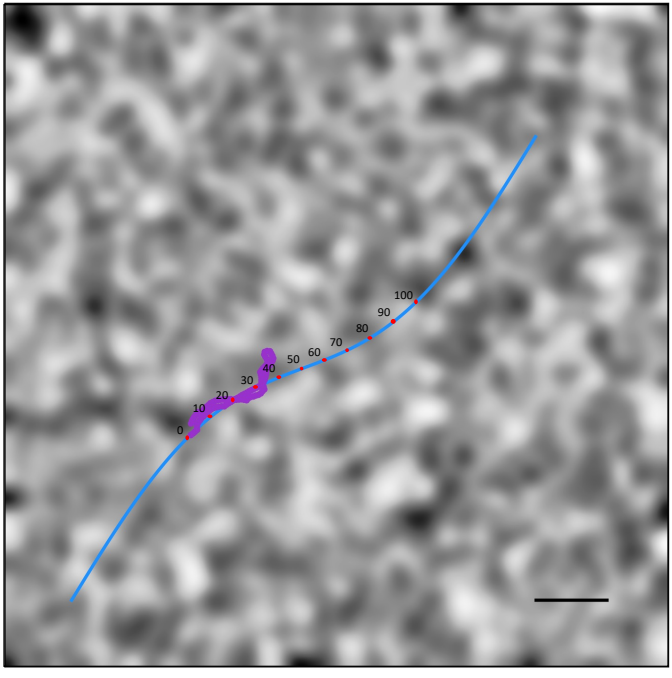


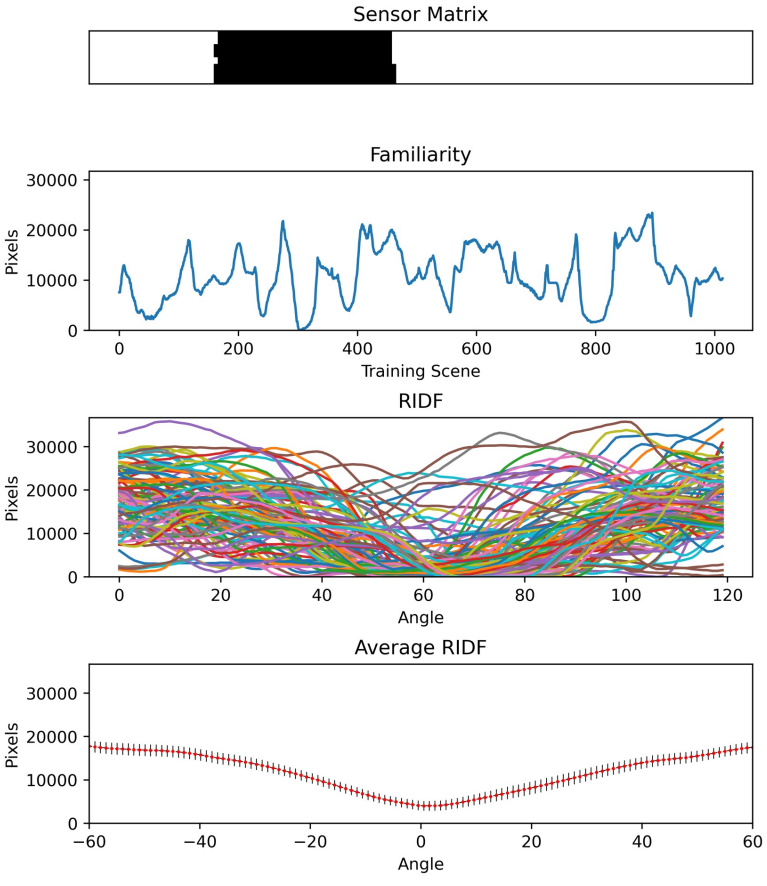


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3961.78; RMSD/dist: 9.904; TD: 9229; p90: 60; p50: 32; complete: 0

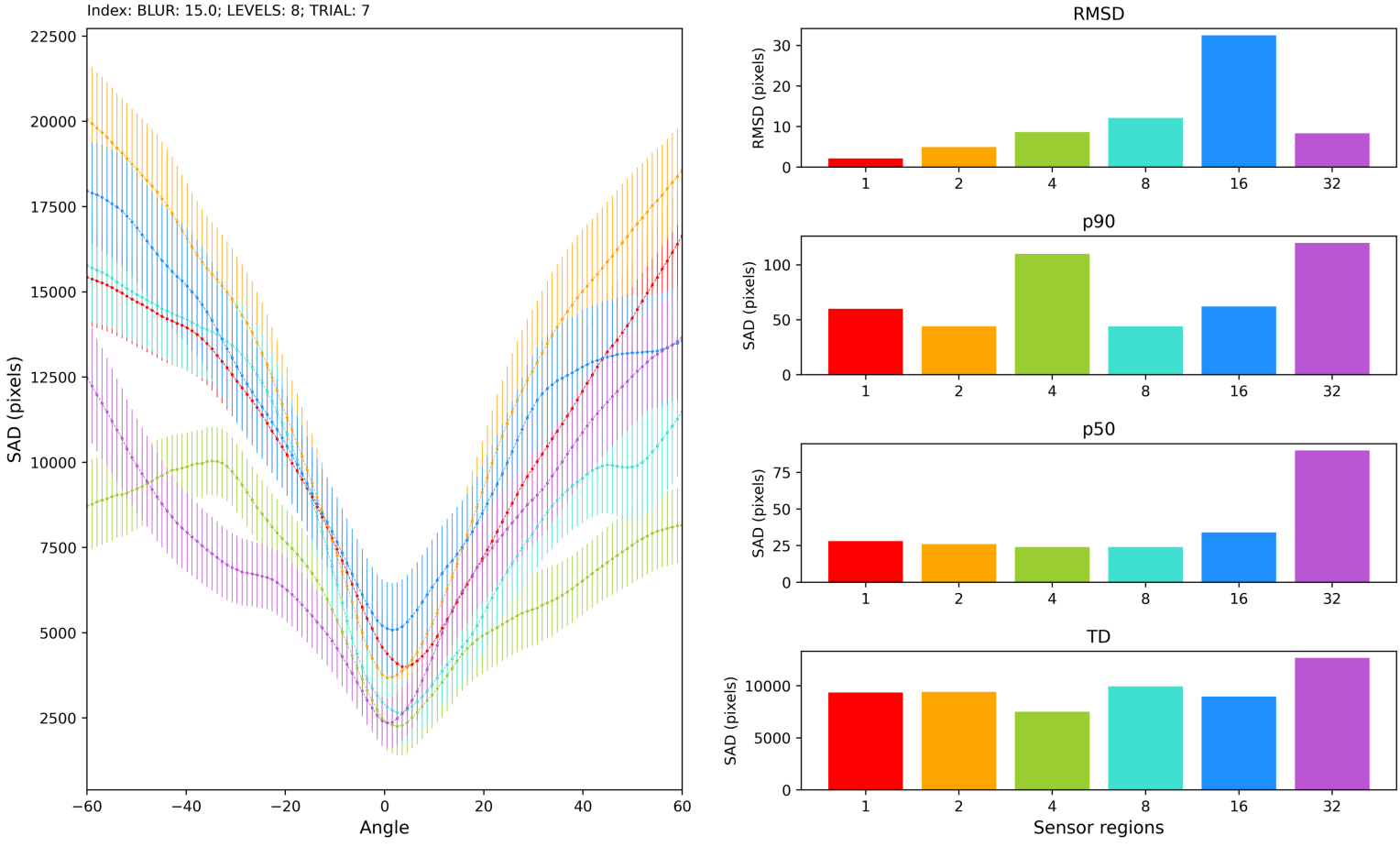
10%



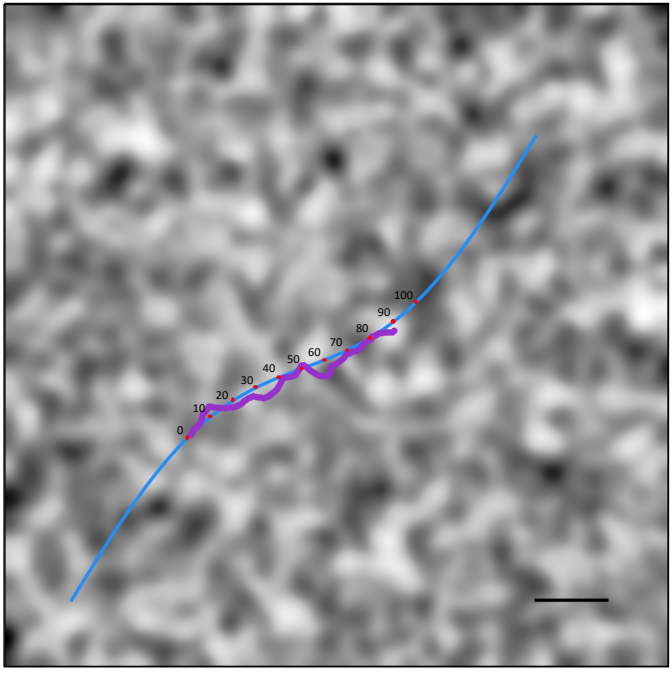


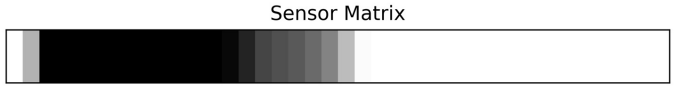
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

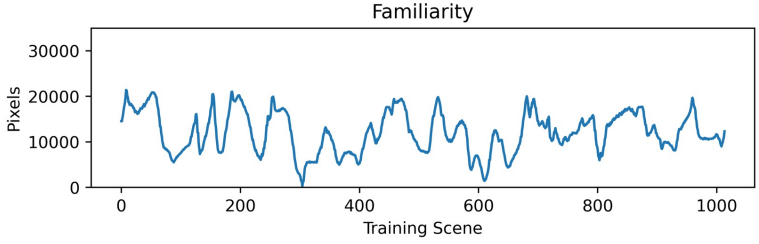
Navigation stats: RMSD error: 1159.94; RMSD/dist: 2.900; TD: 8329; p90: 46; p50: 28; complete: 0

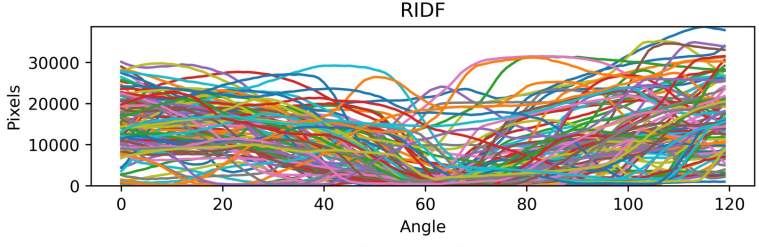

Index: BLUR: 15.0; LEVELS: 8; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

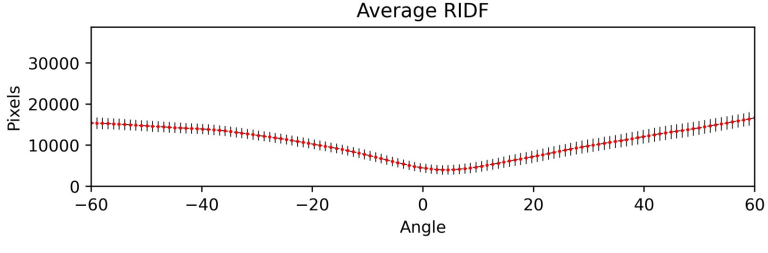
0%







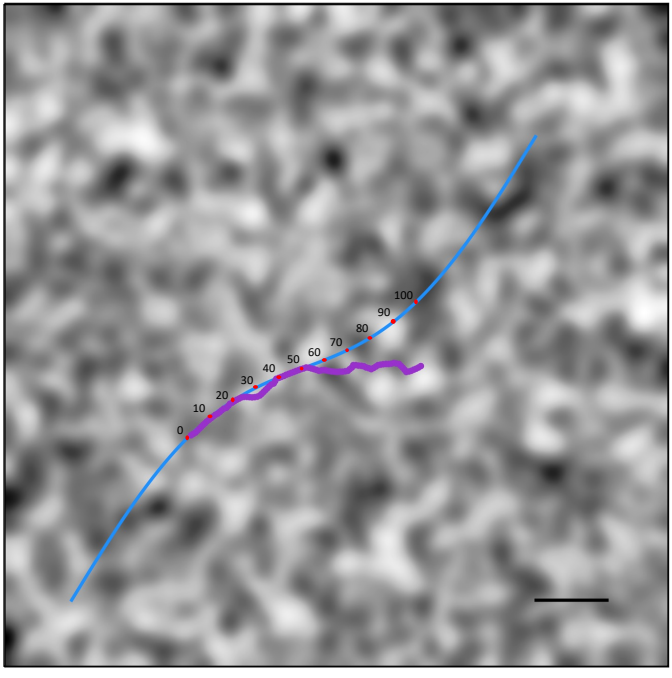


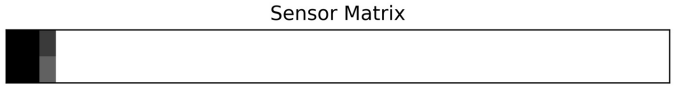


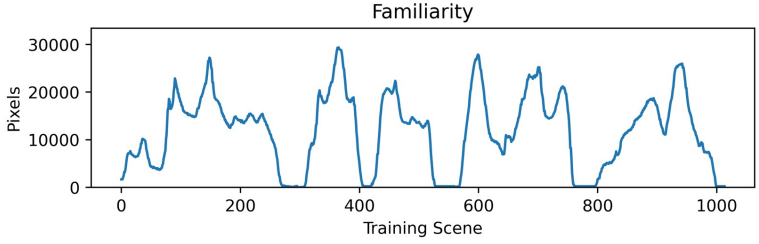
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

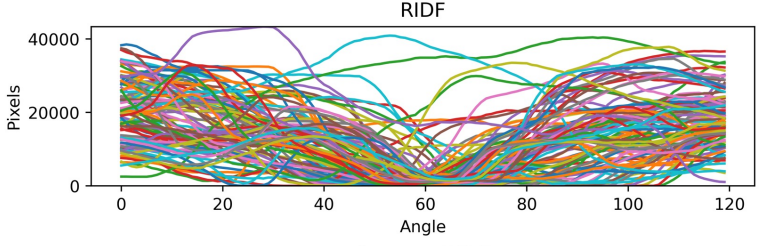
Navigation stats: RMSD error: 846.36; RMSD/dist: 2.116; TD: 9364; p90: 60; p50: 28; complete: 0

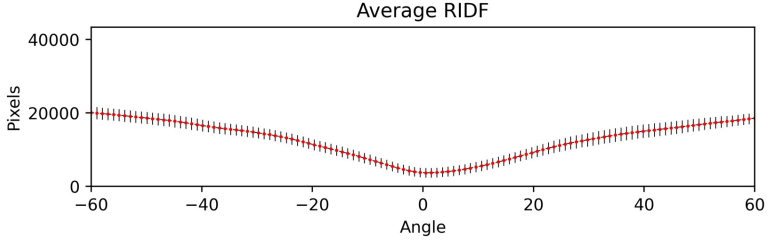
30%







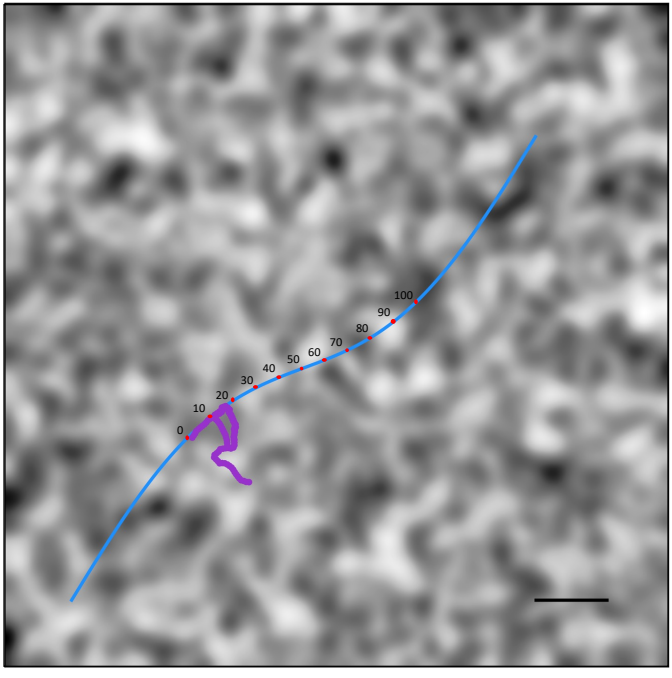


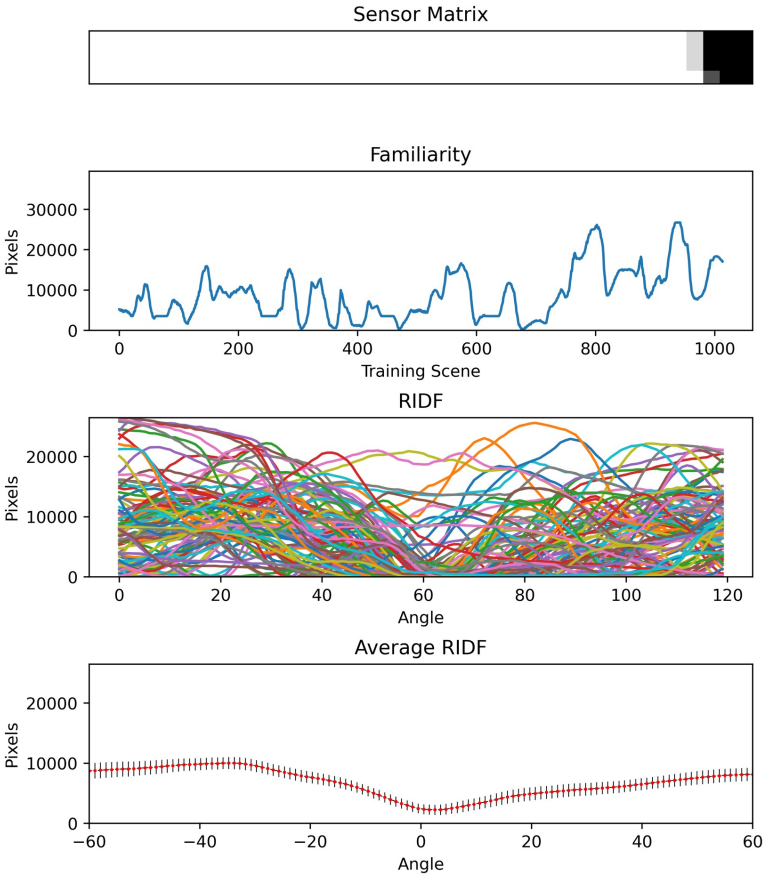


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1982.28; RMSD/dist: 4.956; TD: 9425; p90: 44; p50: 26; complete: 0

10%

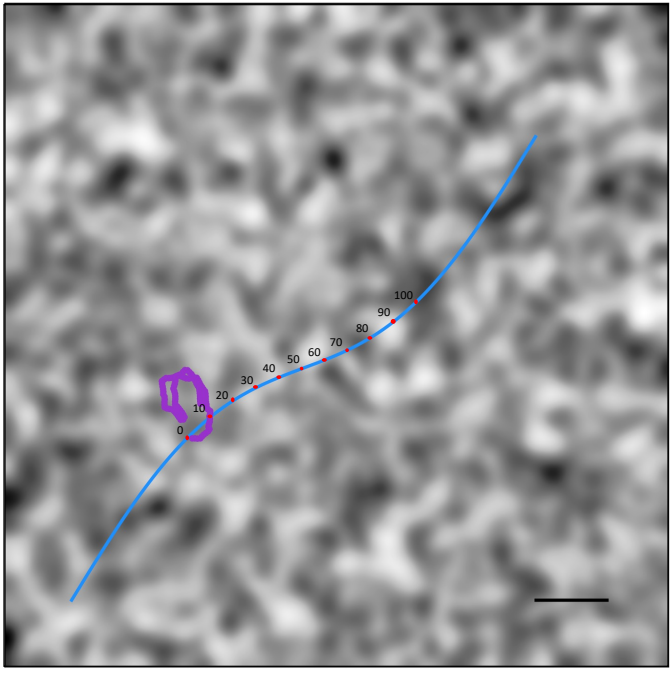


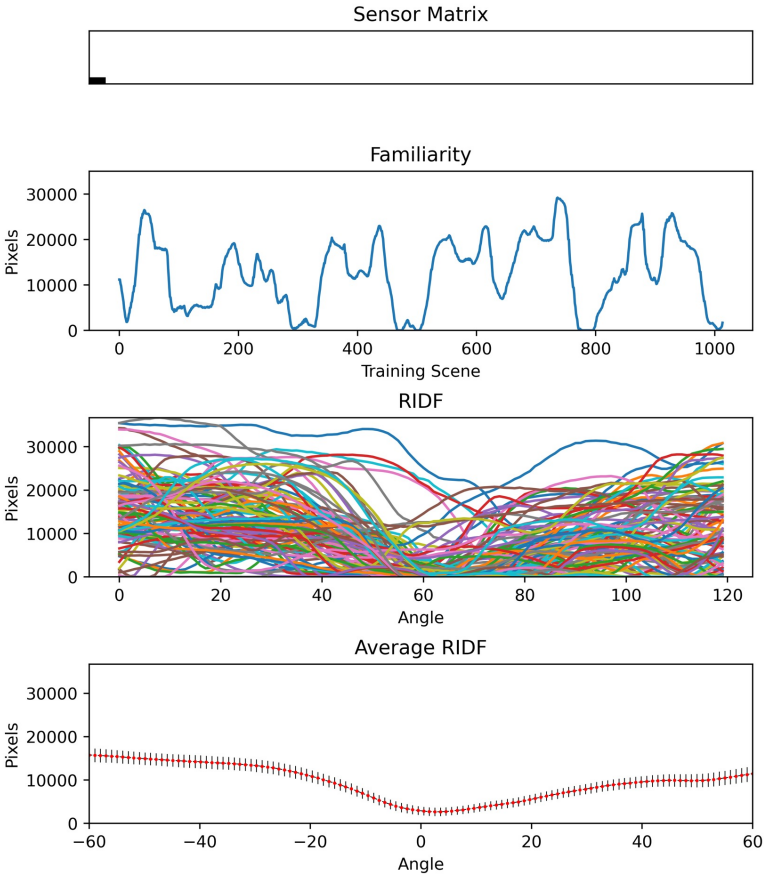


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3454.57; RMSD/dist: 8.636; TD: 7509; p90: 110; p50: 24; complete: 0

0%

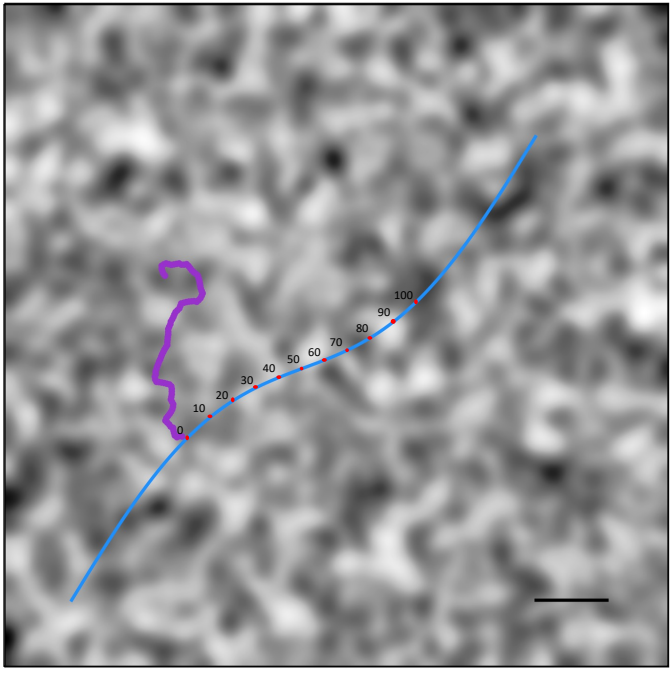


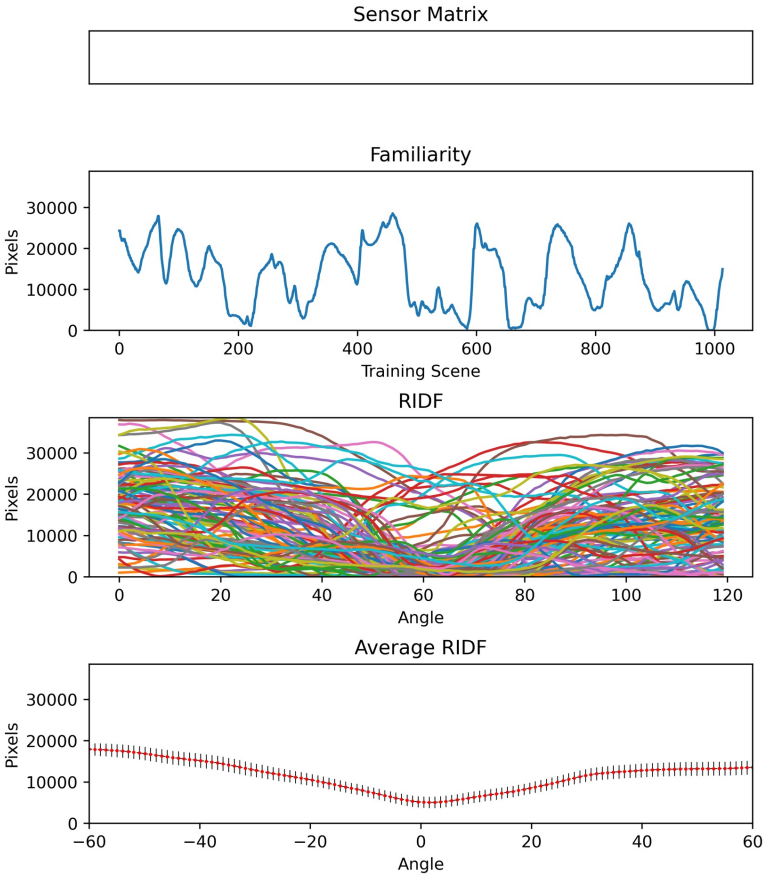


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 4847.65; RMSD/dist: 12.119; TD: 9939; p90: 44; p50: 24; complete: 0

0%





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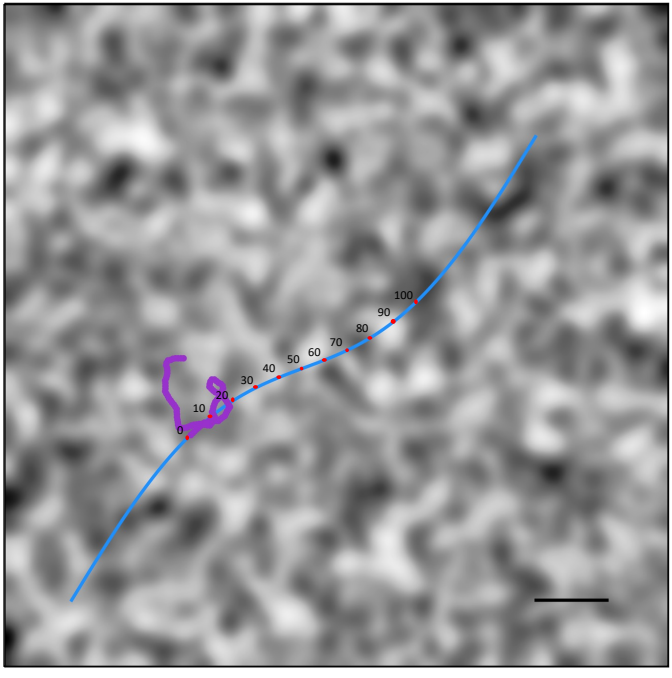
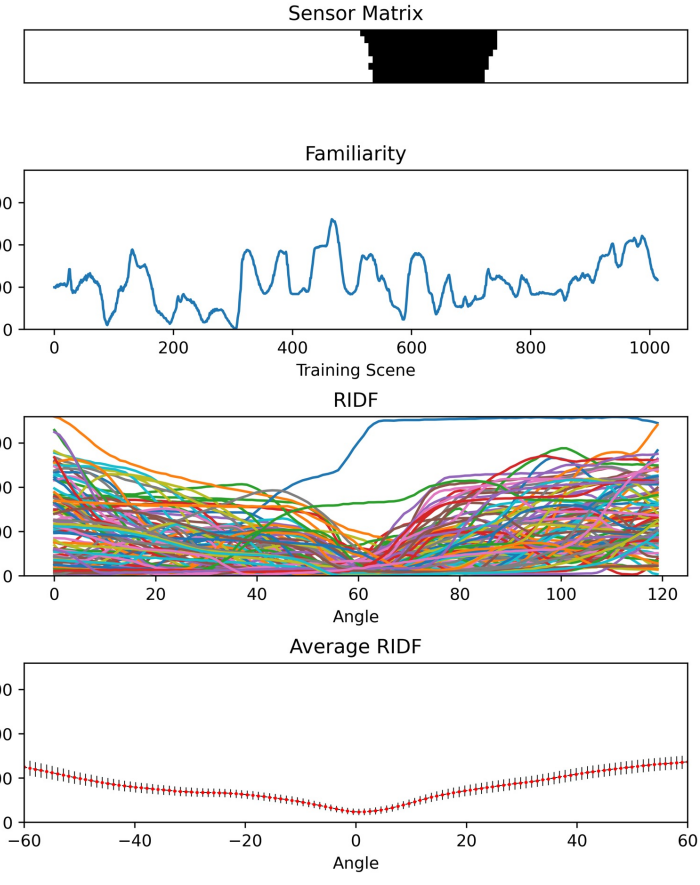
Navigation stats: RMSD error: 13000.35; RMSD/dist: 32.501; TD: 8972; p90: 62; p50: 34; complete: 0

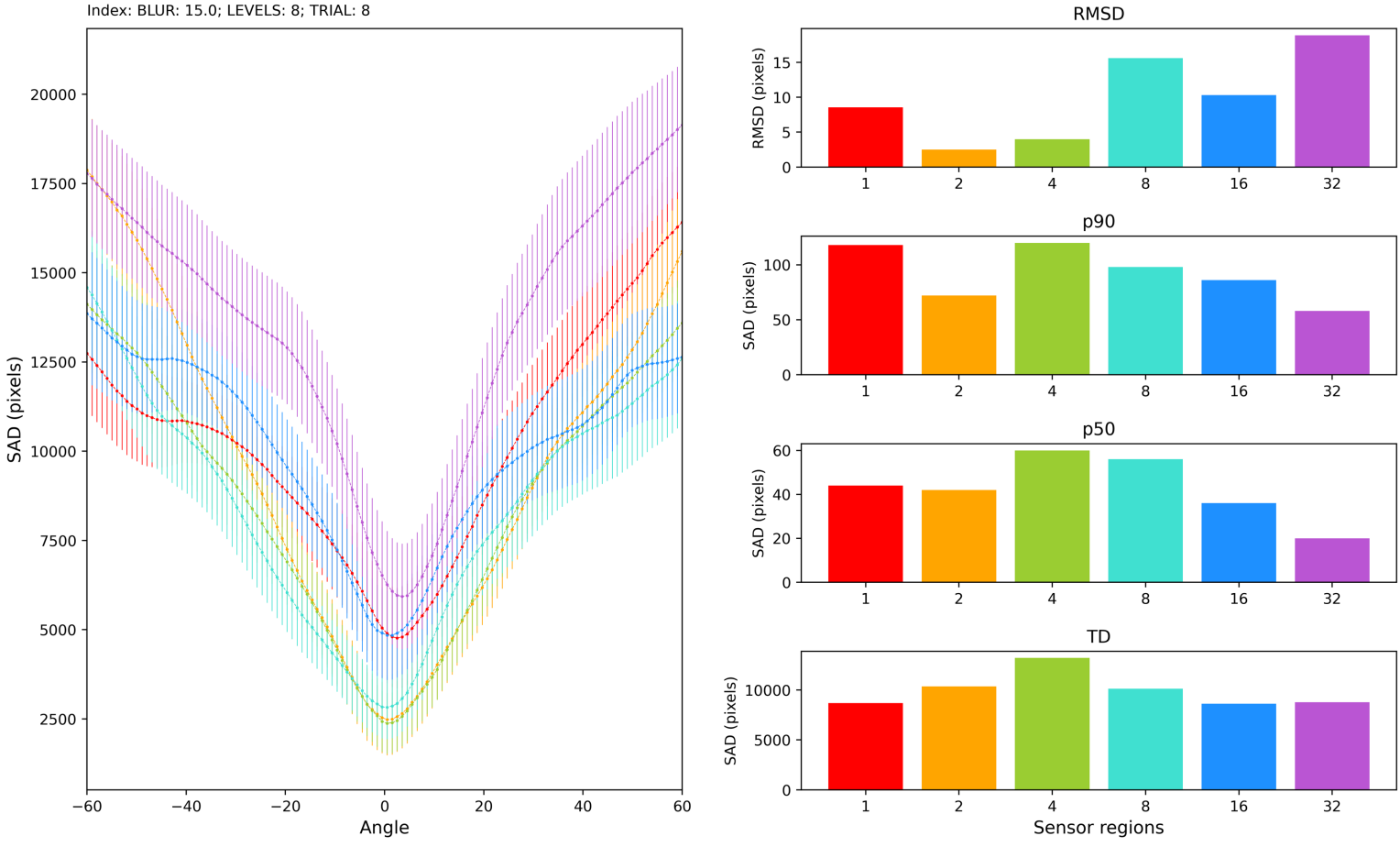
10%



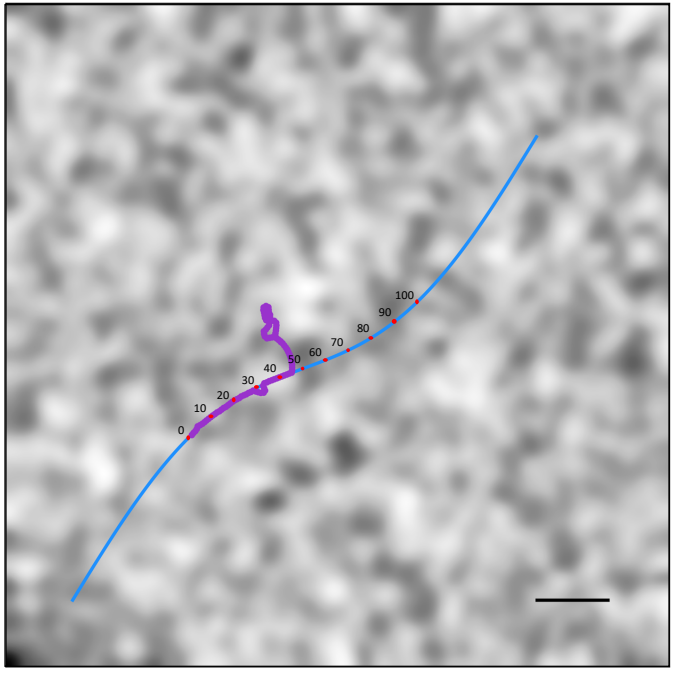


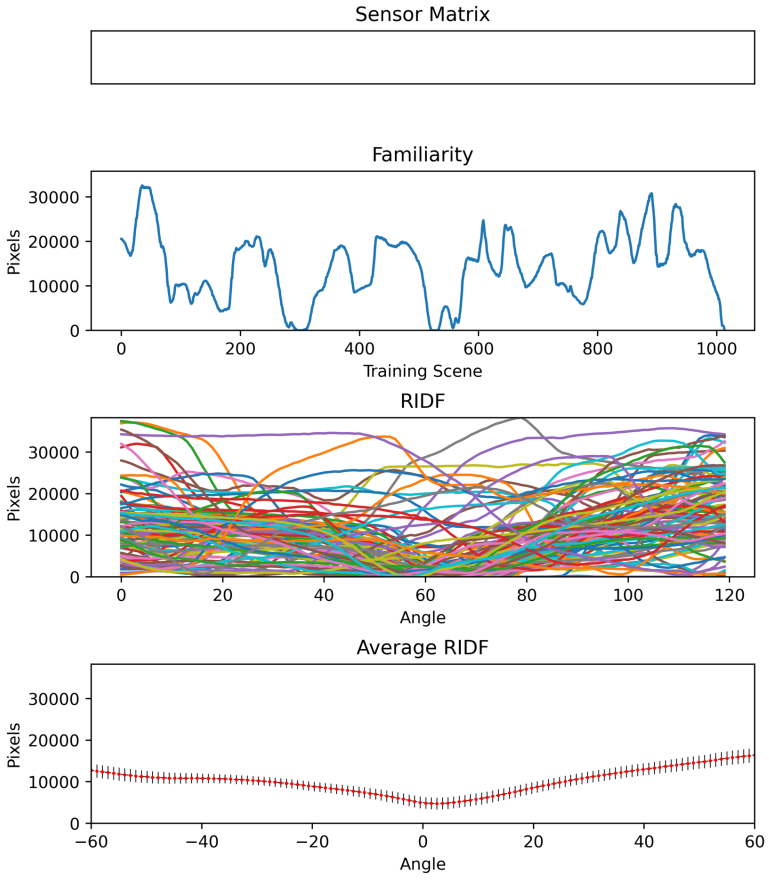
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3317.92; RMSD/dist: 8.295; TD: 12682; p90: 120; p50: 90; complete: 0


Index: BLUR: 15.0; LEVELS: 8; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

30%

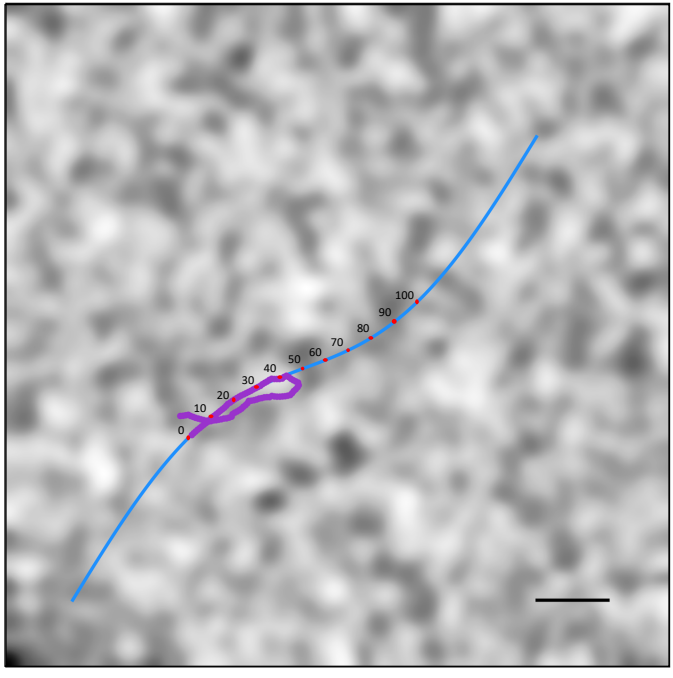


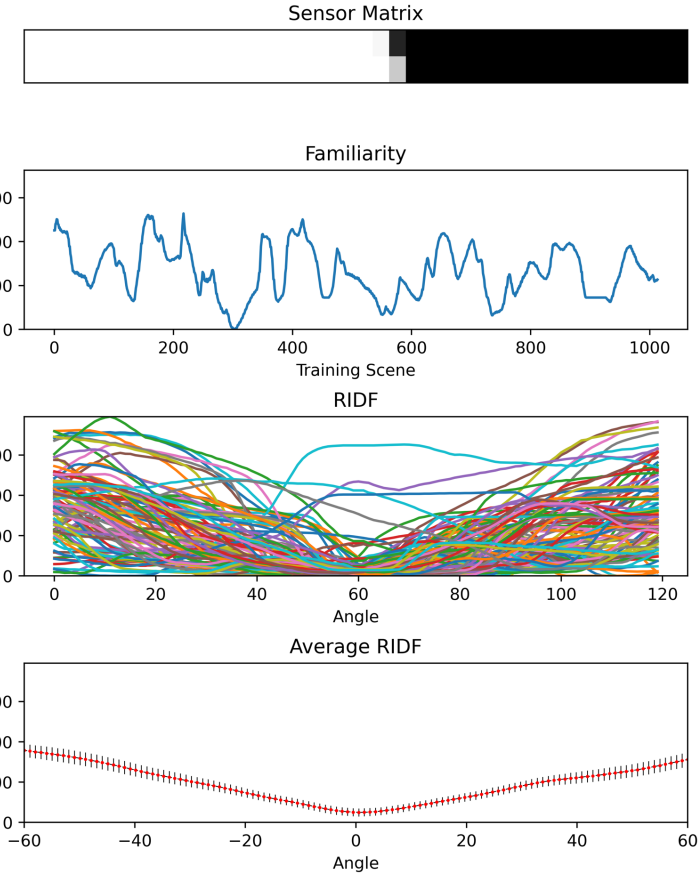


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3417.07; RMSD/dist: 8.543; TD: 8687; p90: 118; p50: 44; complete: 0

40%

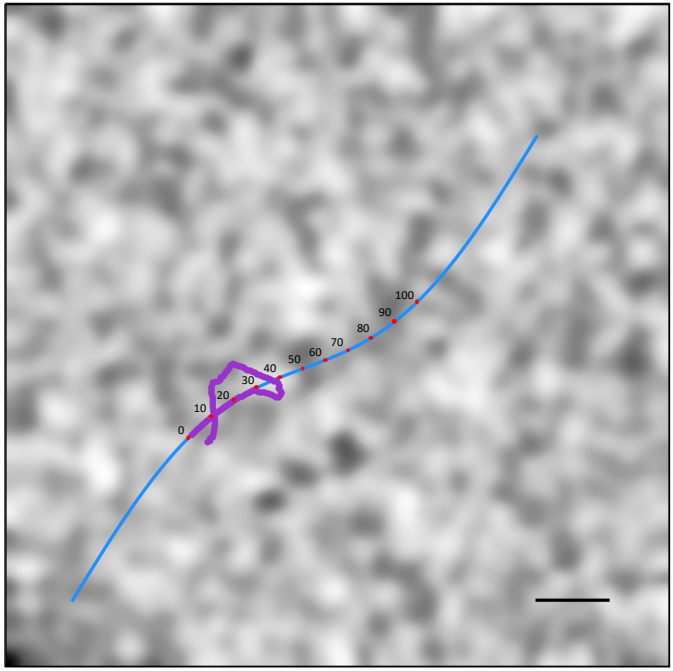


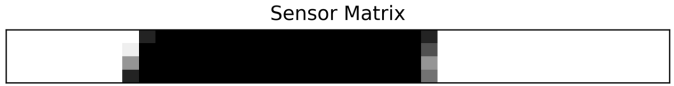


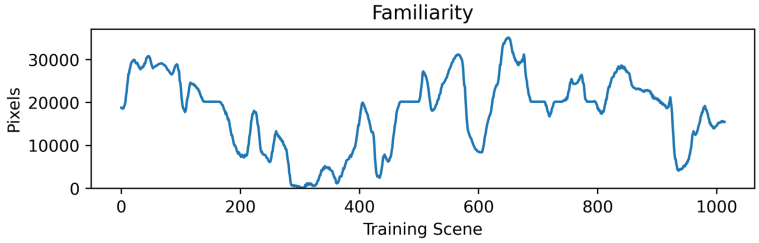
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

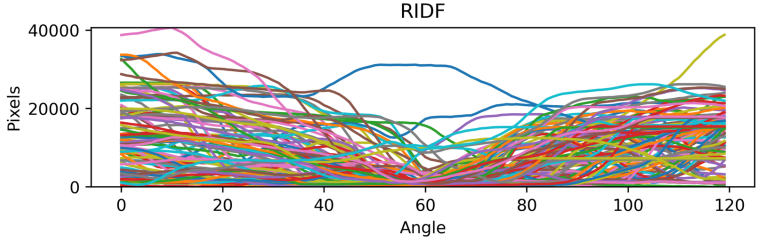
Navigation stats: RMSD error: 1005.48; RMSD/dist: 2.514; TD: 10363; p90: 72; p50: 42; complete: 0

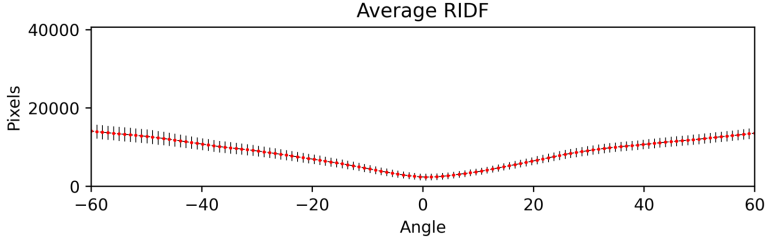
30%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1591.19; RMSD/dist: 3.978; TD: 13214; p90: 120; p50: 60; complete: 0

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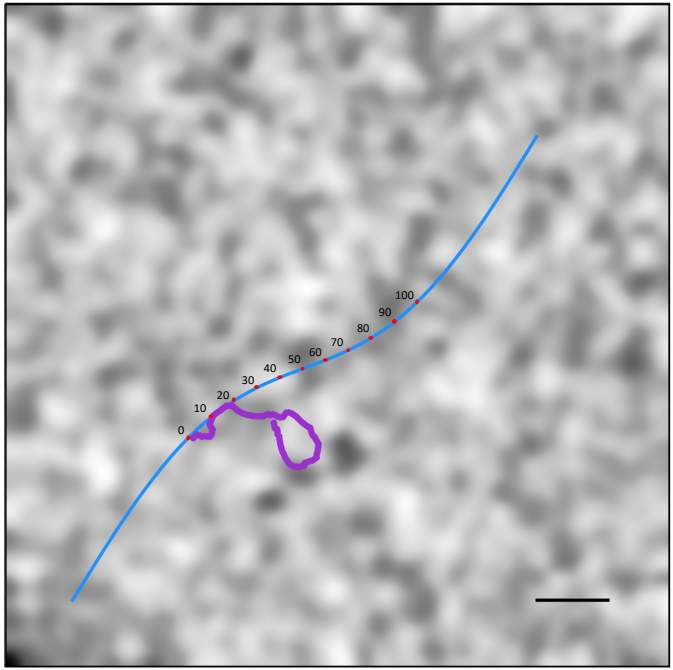

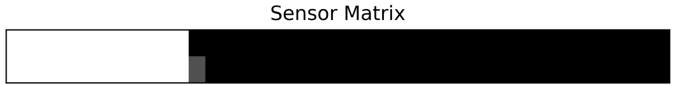

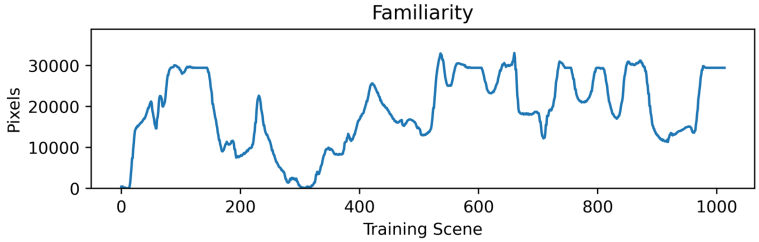

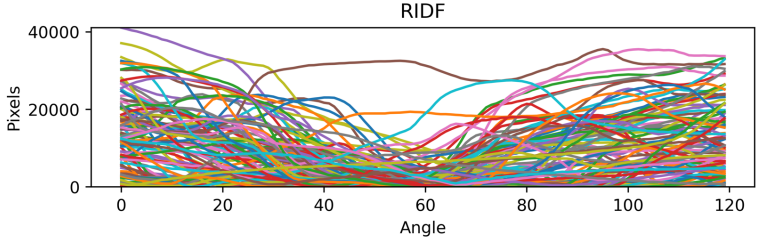

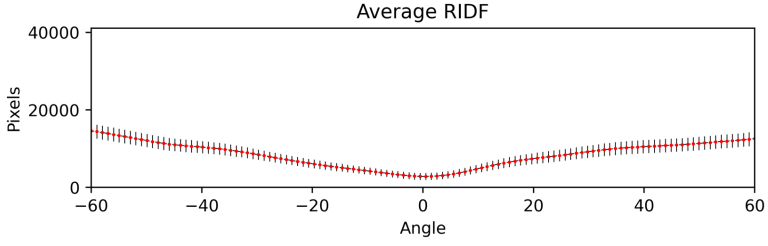

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 6241.36; RMSD/dist: 15.603; TD: 10132; p90: 98; p50: 56; complete: 0

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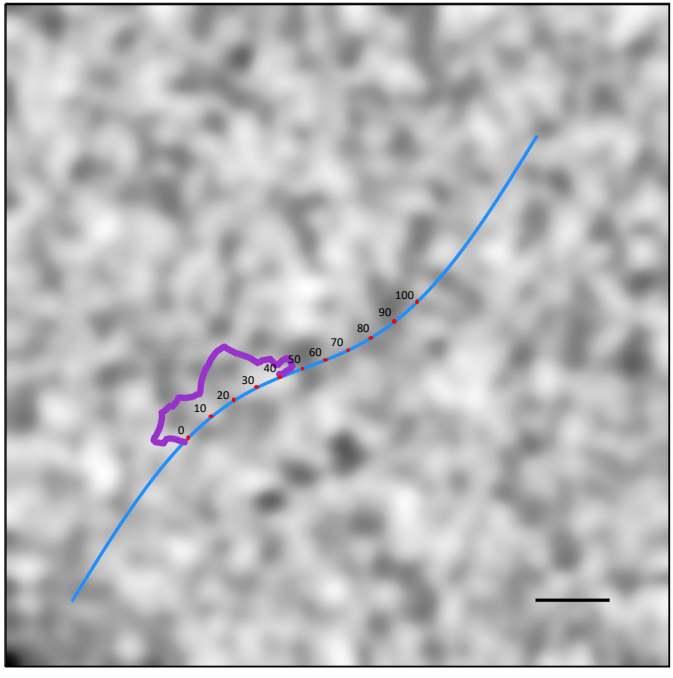

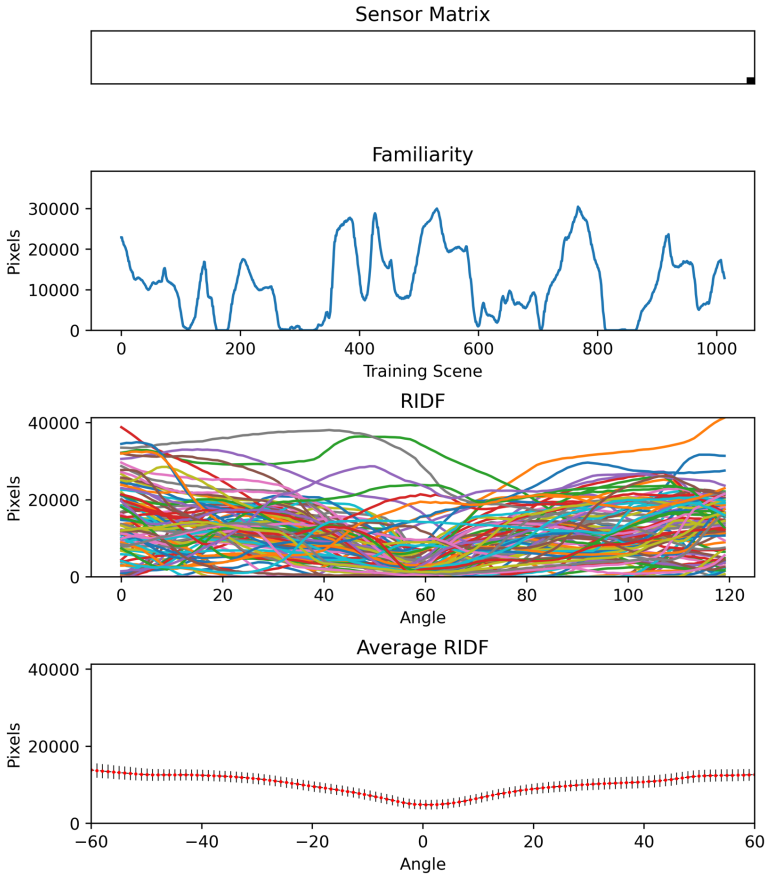

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 4124.95; RMSD/dist: 10.312; TD: 8631; p90: 86; p50: 36; complete: 0

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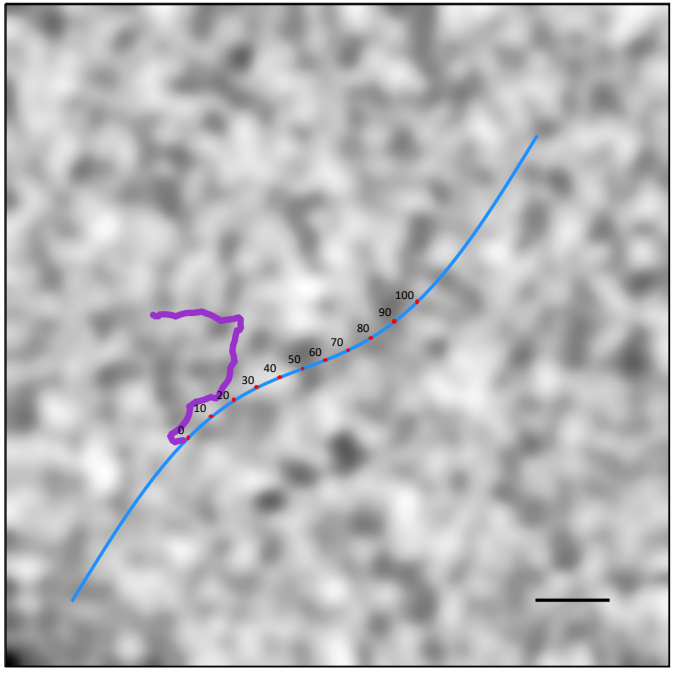
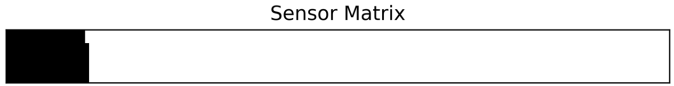
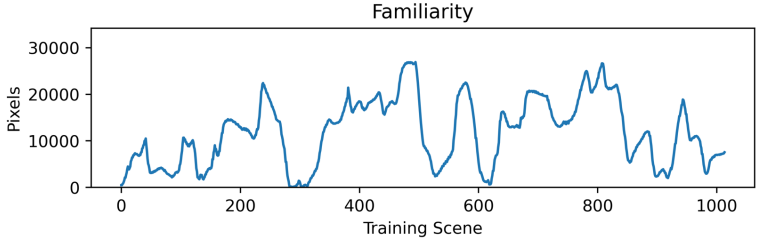
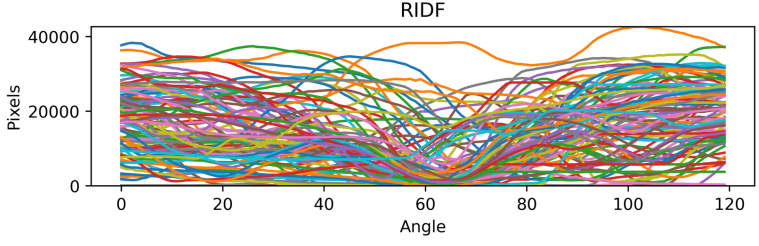
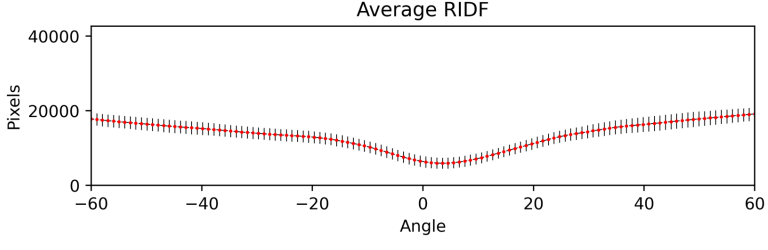




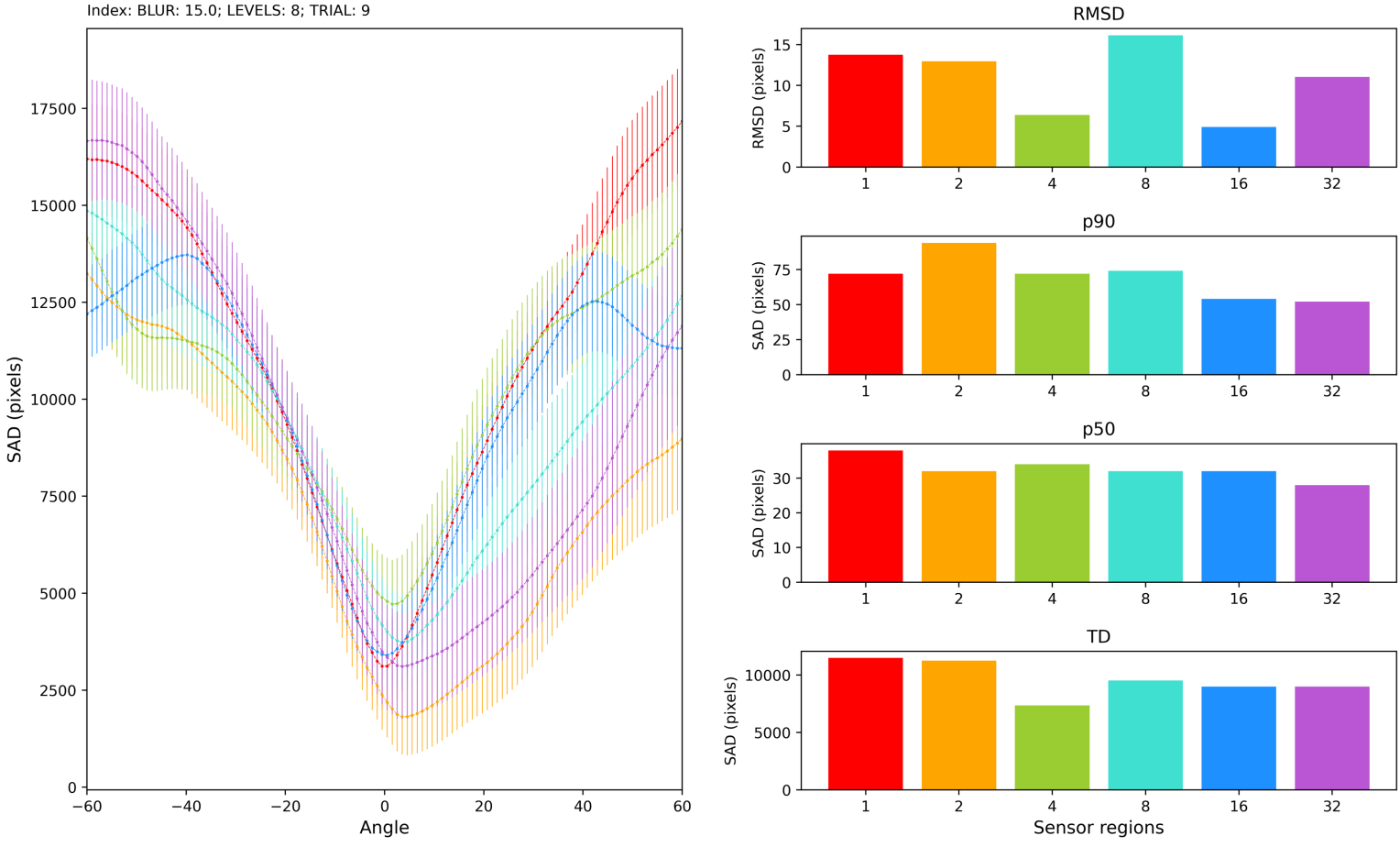




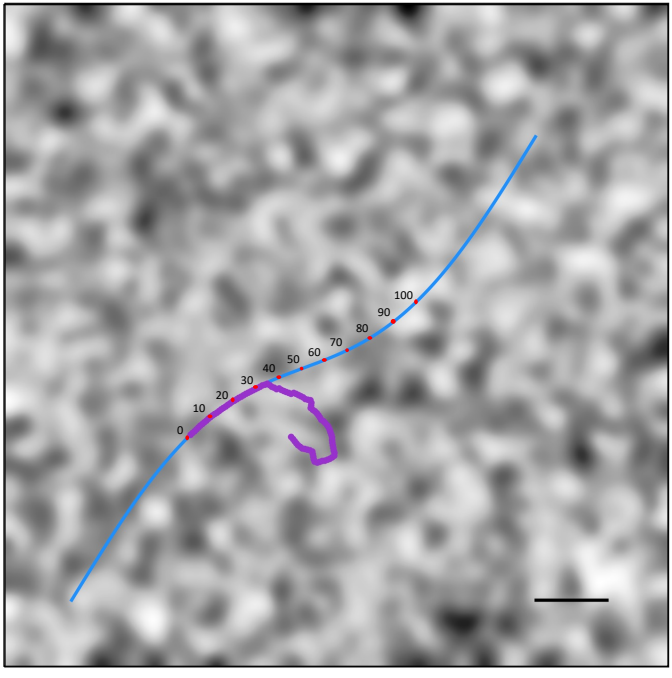


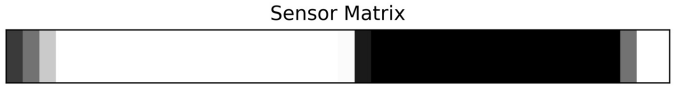
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

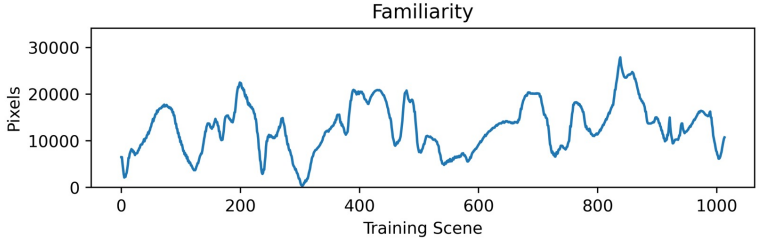
Navigation stats: RMSD error: 7550.29; RMSD/dist: 18.876; TD: 8782; p90: 58; p50: 20; complete: 0

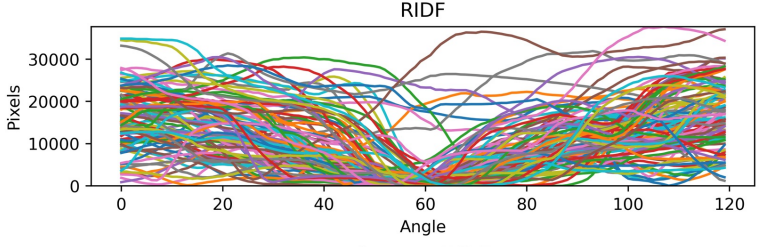

Index: BLUR: 15.0; LEVELS: 8; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

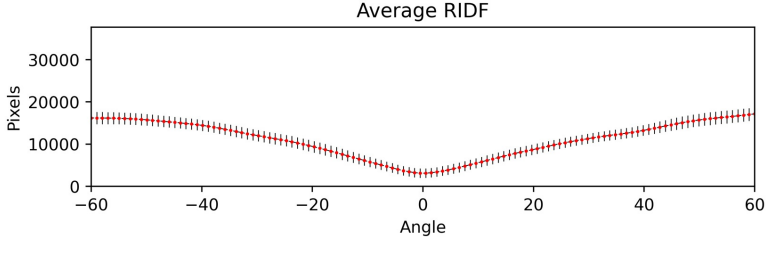
30%







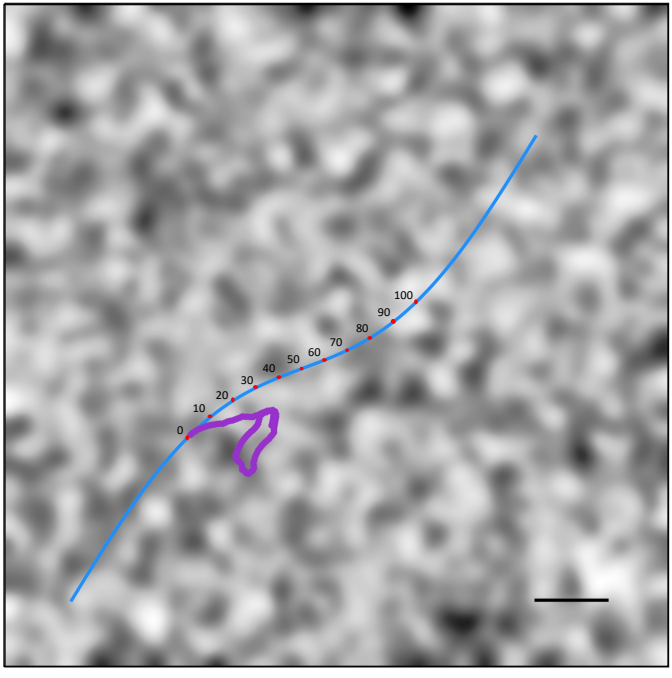


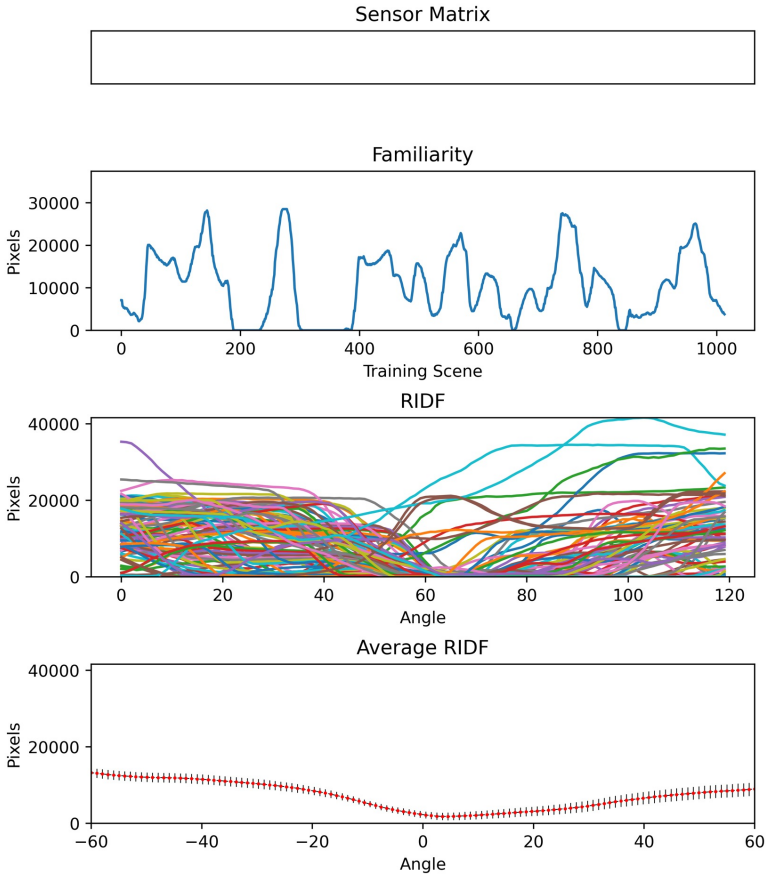


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 5501.42; RMSD/dist: 13.754; TD: 11480; p90: 72; p50: 38; complete: 0

0%

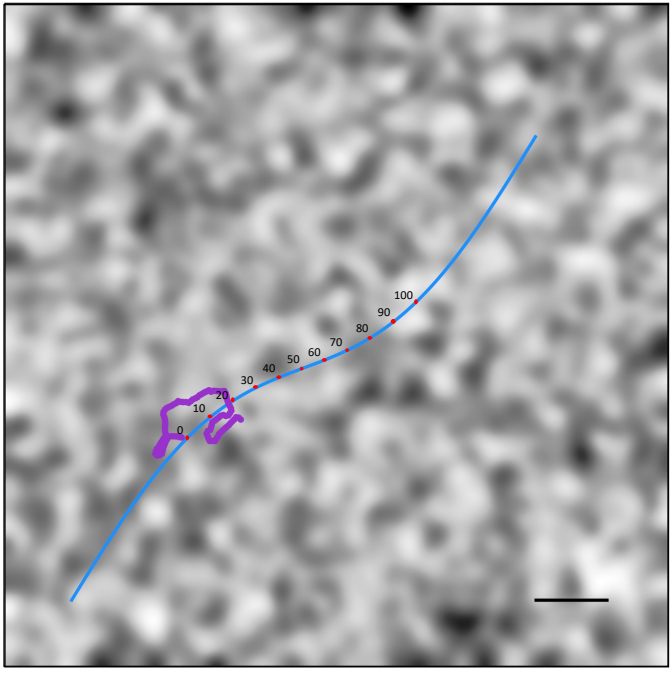


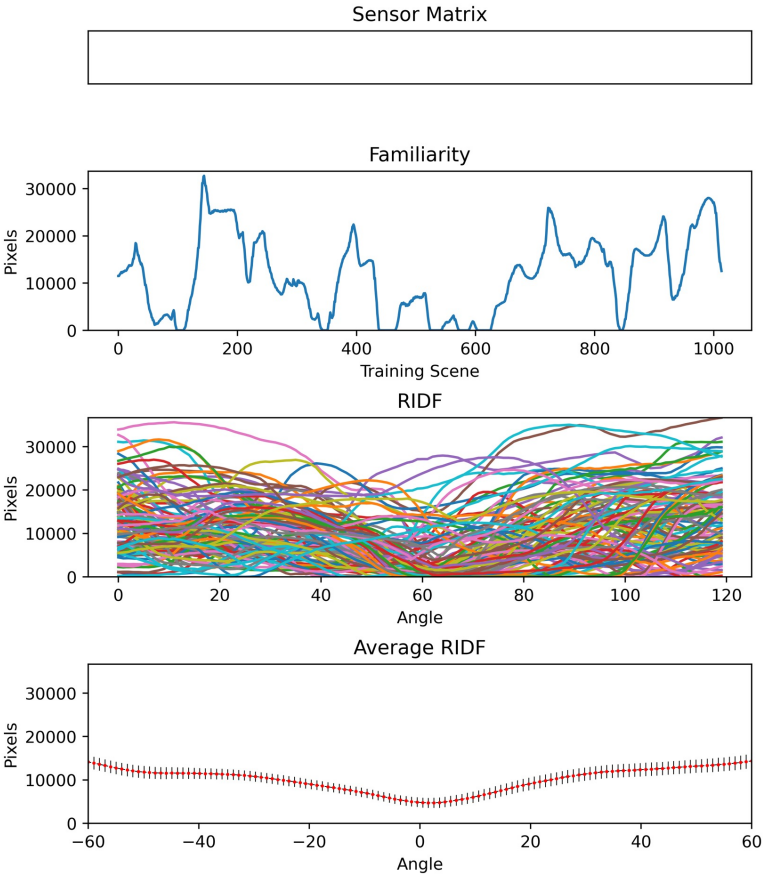


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 5183.89; RMSD/dist: 12.960; TD: 11257; p90: 94; p50: 32; complete: 0

0%

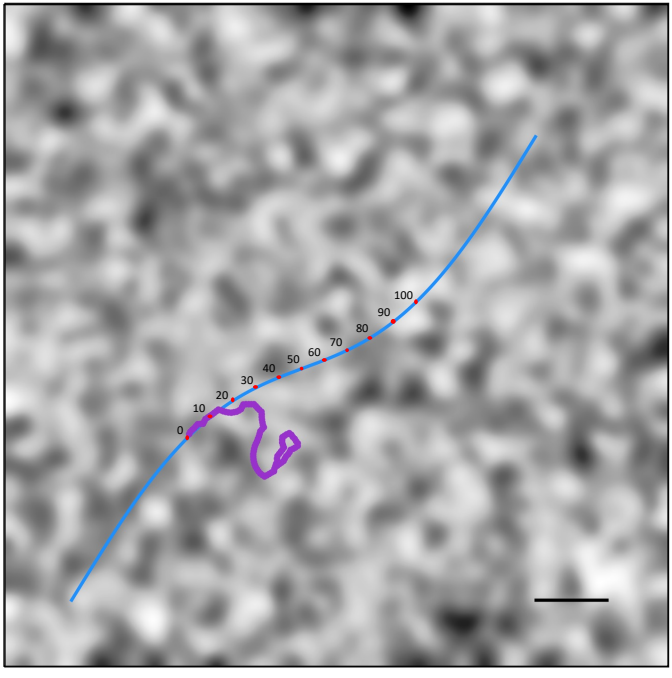


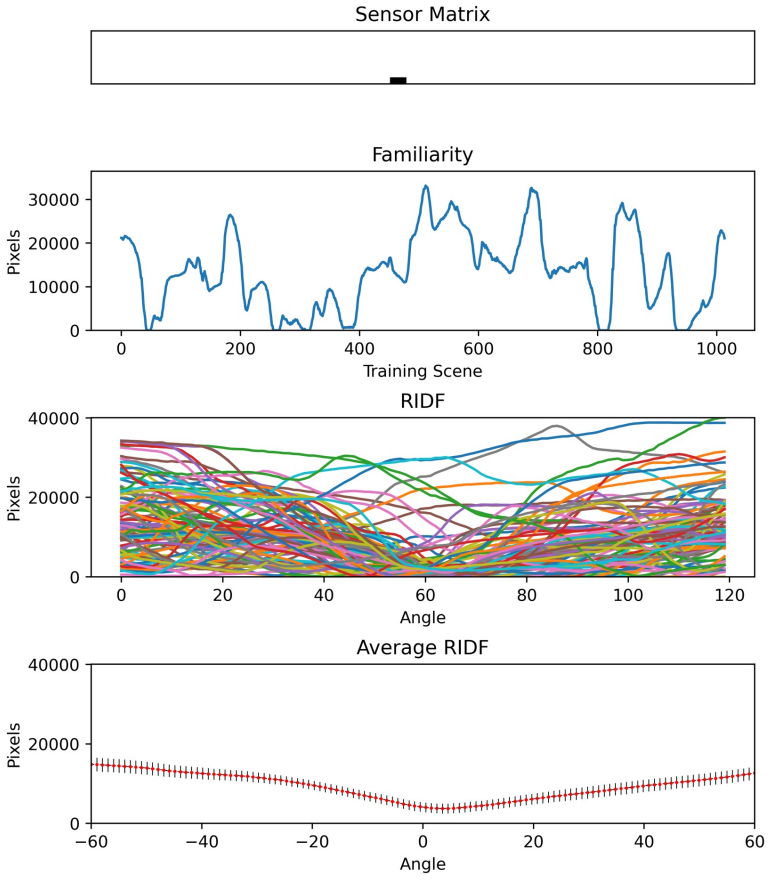


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2548.55; RMSD/dist: 6.371; TD: 7342; p90: 72; p50: 34; complete: 0

10%





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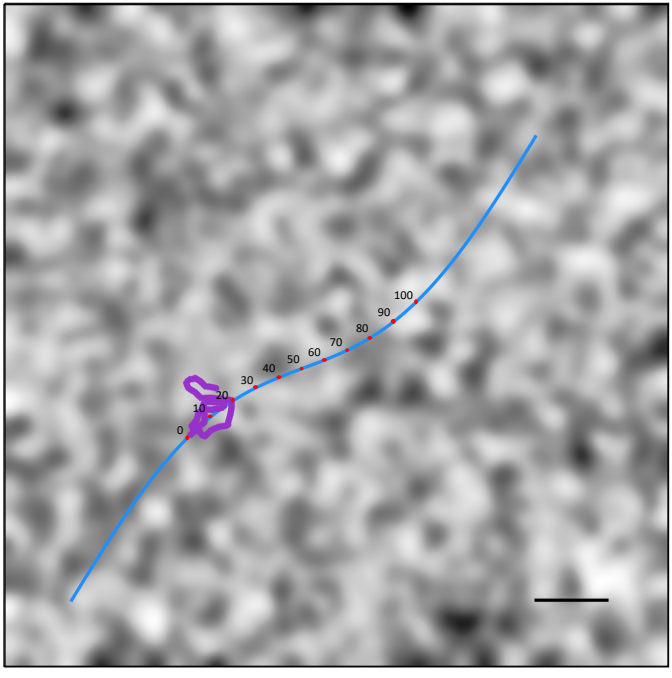
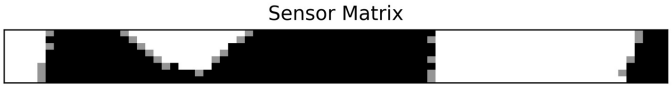
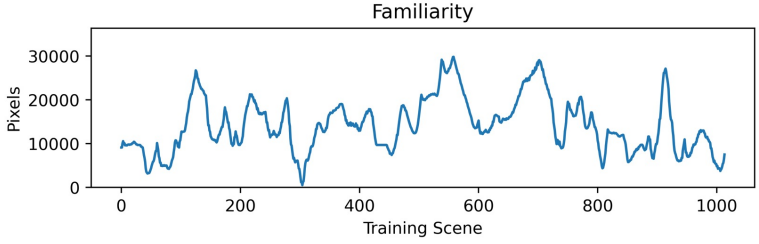
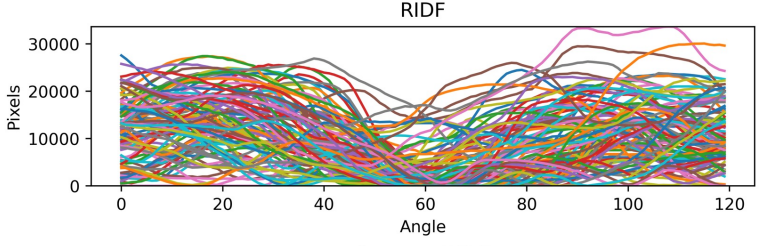
Navigation stats: RMSD error: 6456.56; RMSD/dist: 16.141; TD: 9515; p90: 74; p50: 32; complete: 0

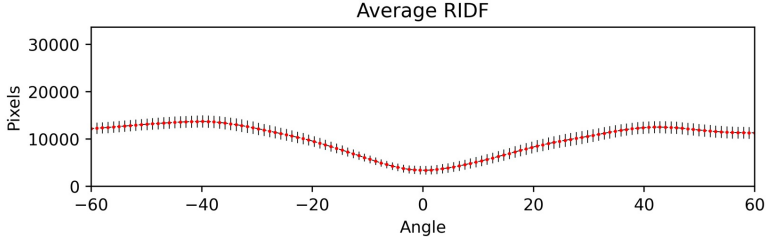
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1967.22; RMSD/dist: 4.918; TD: 8989; p90: 54; p50: 32; complete: 0

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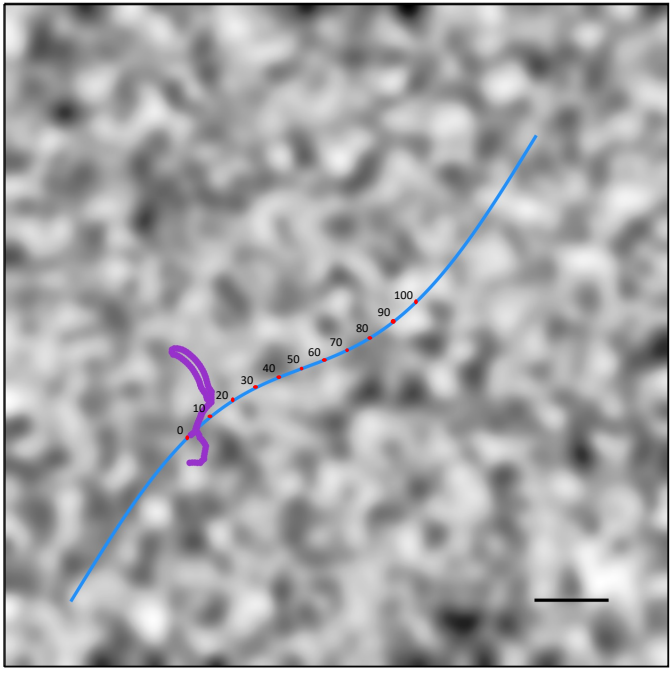
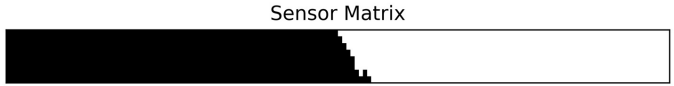
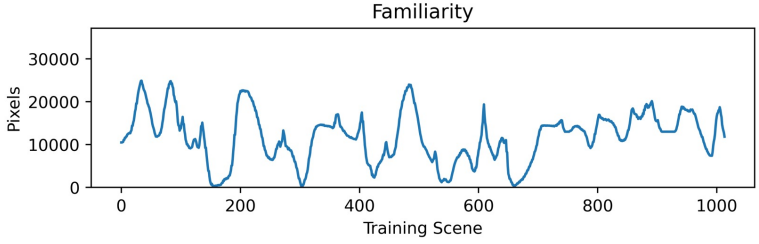
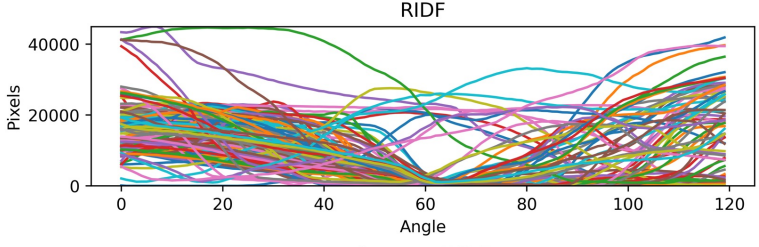
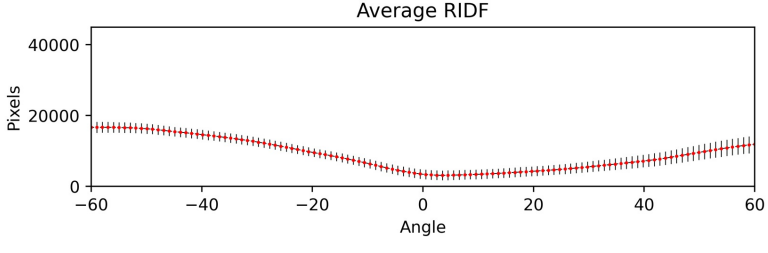




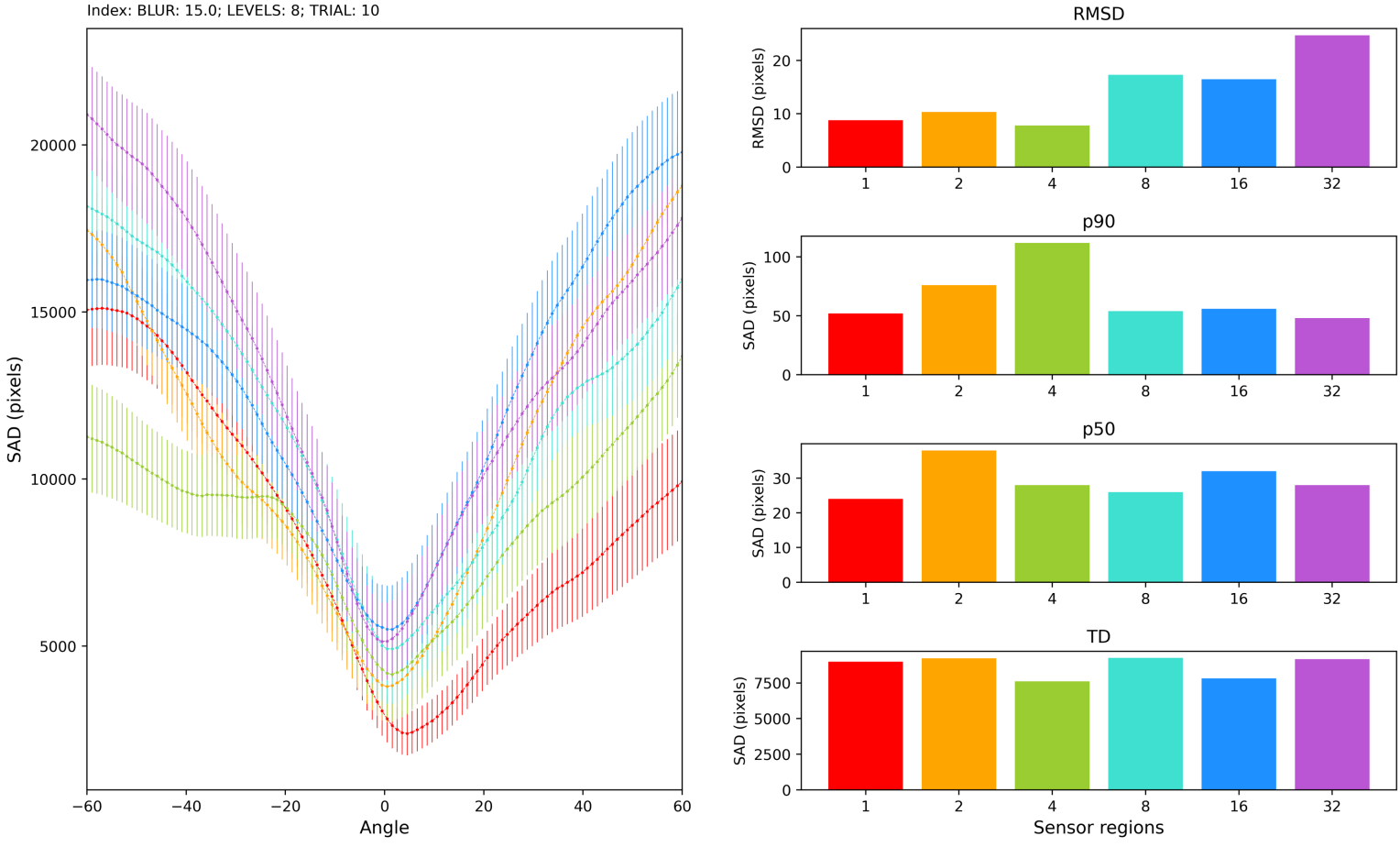




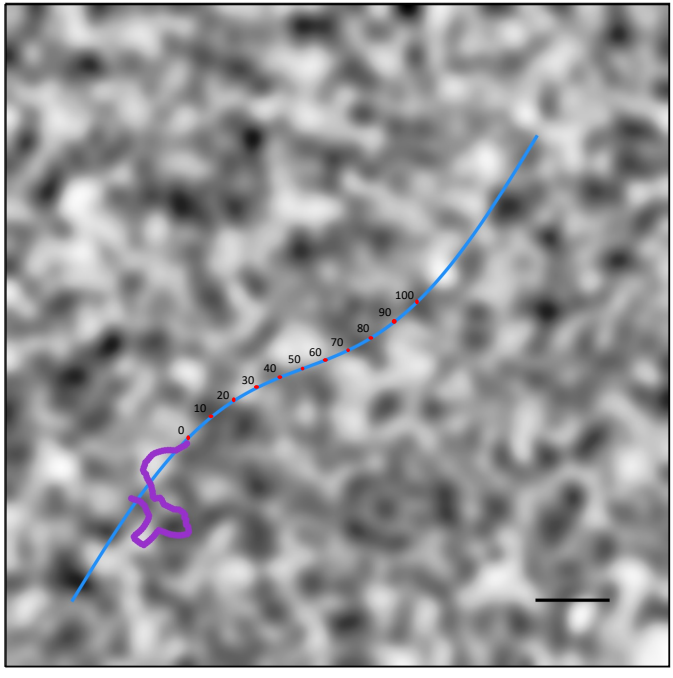


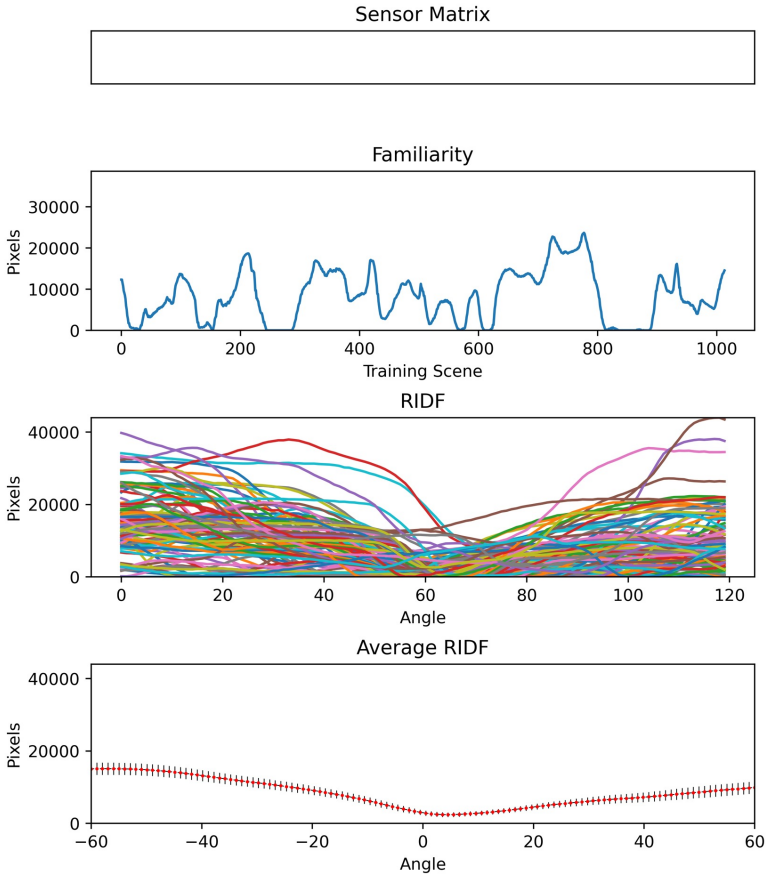
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 4417.20; RMSD/dist: 11.043; TD: 8994; p90: 52; p50: 28; complete: 0


Index: BLUR: 15.0; LEVELS: 8; TRIAL: 10
SAD (pixels)
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
30
20
10
TD
7500
5000
2500
Sensor regions

0%

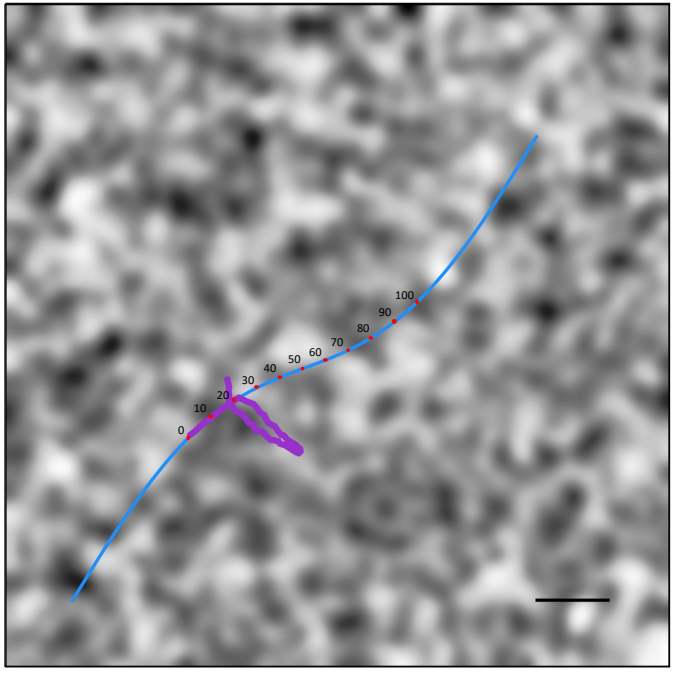


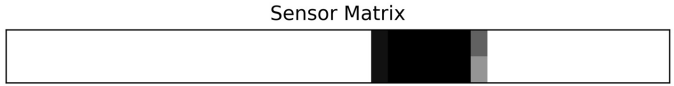


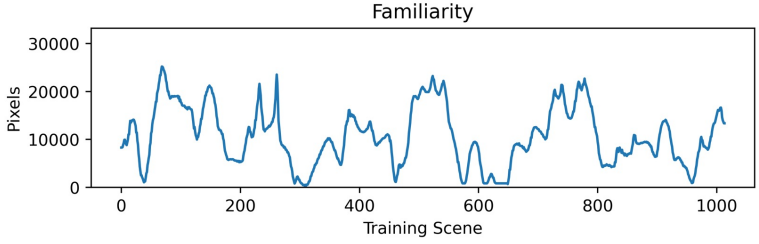
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

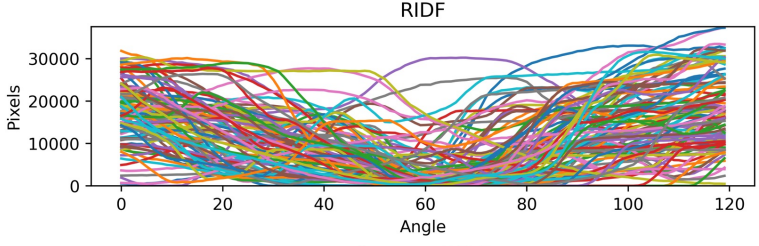
Navigation stats: RMSD error: 3510.86; RMSD/dist: 8.777; TD: 8988; p90: 52; p50: 24; complete: 0

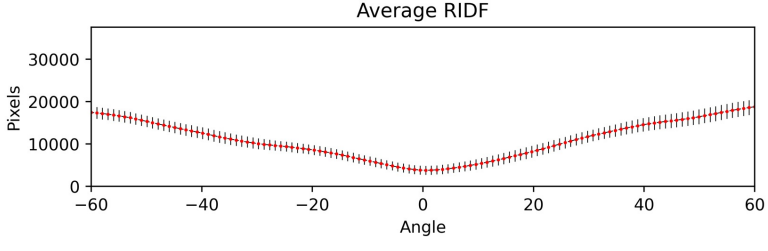
20%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4133.73; RMSD/dist: 10.334; TD: 9233; p90: 76; p50: 38; complete: 0

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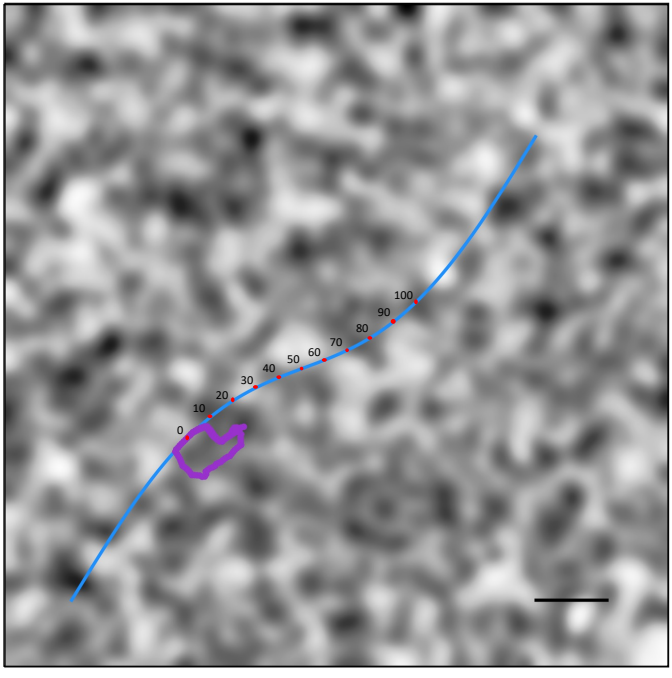
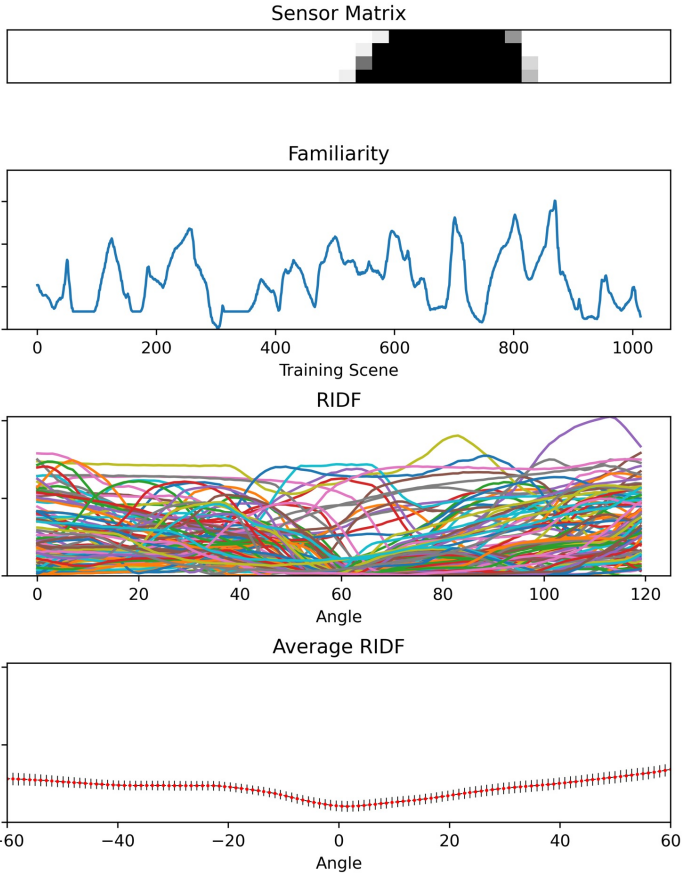
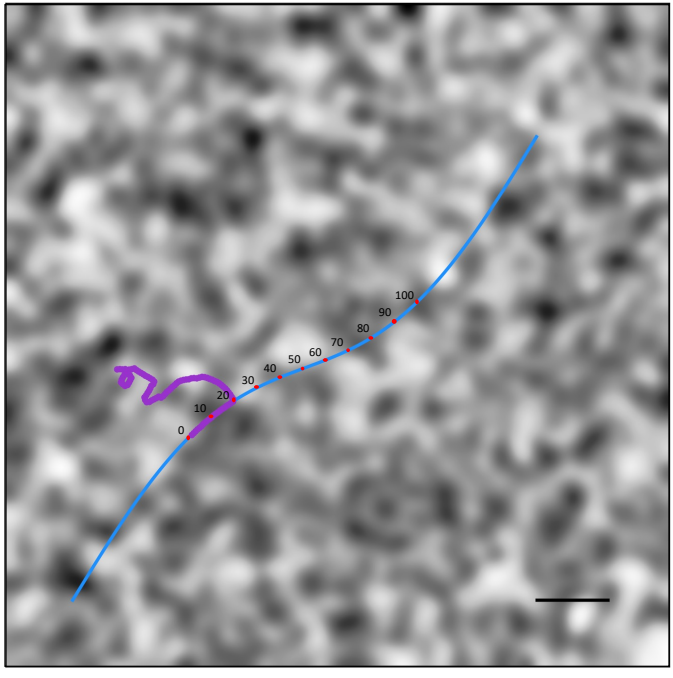


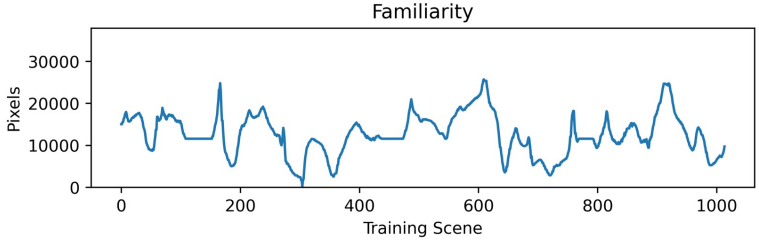


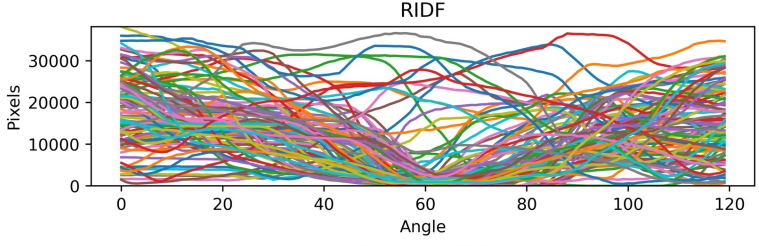
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

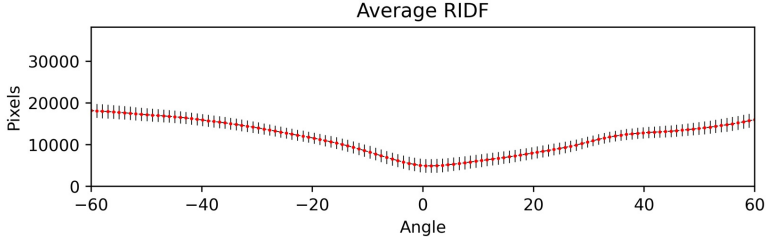
Navigation stats: RMSD error: 3118.58; RMSD/dist: 7.796; TD: 7611; p90: 112; p50: 28; complete: 0

20%









Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 6918.96; RMSD/dist: 17.297; TD: 9250; p90: 54; p50: 26; complete: 0

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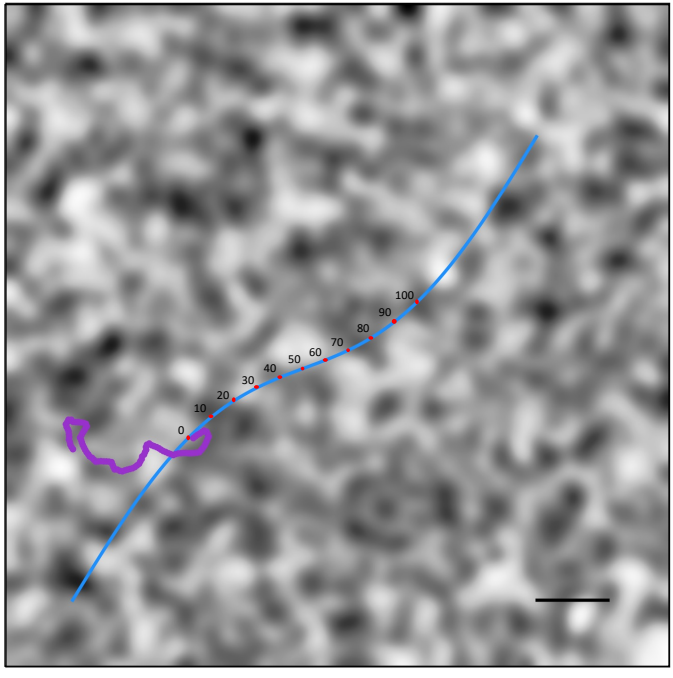

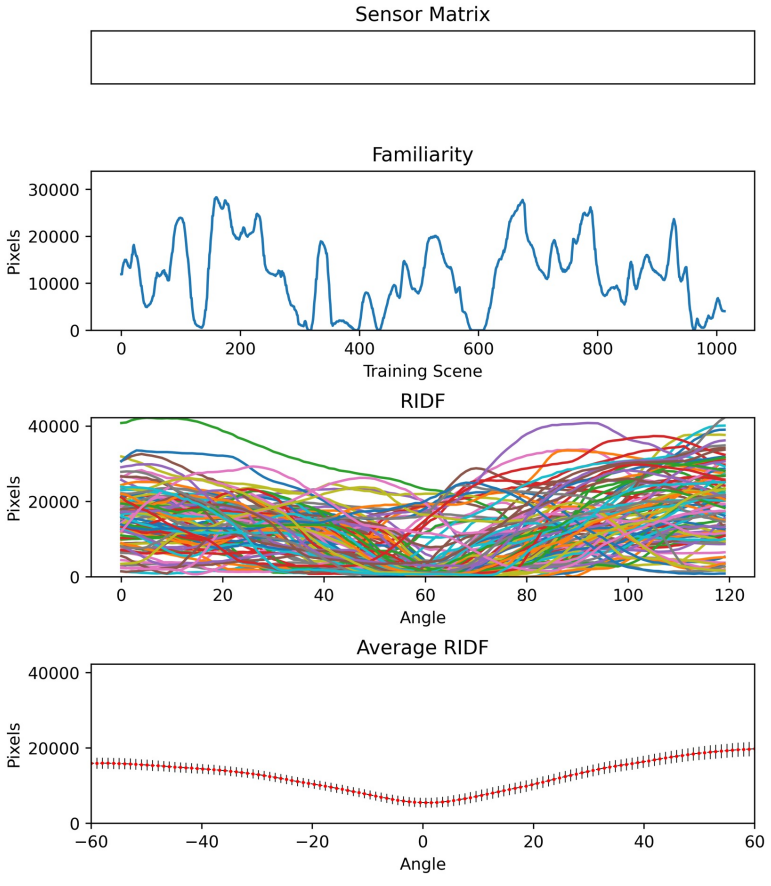

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 6595.18; RMSD/dist: 16.488; TD: 7815; p90: 56; p50: 32; complete: 0

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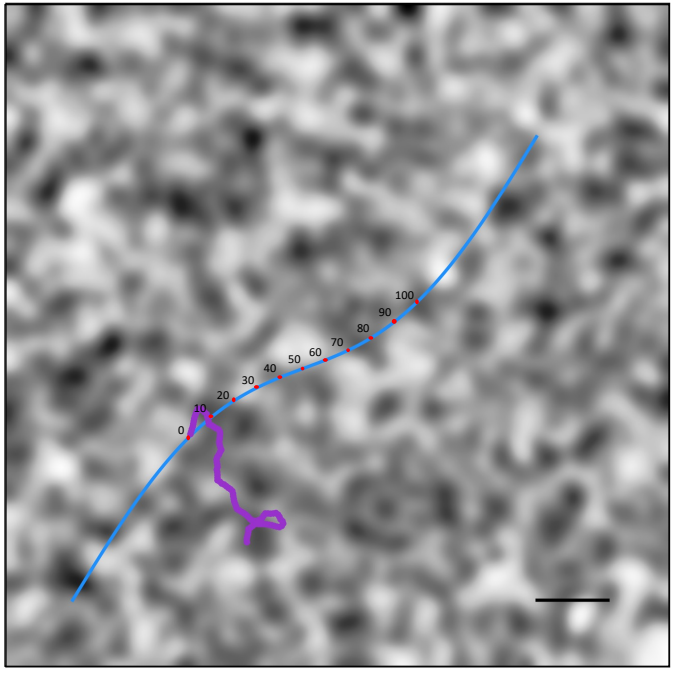

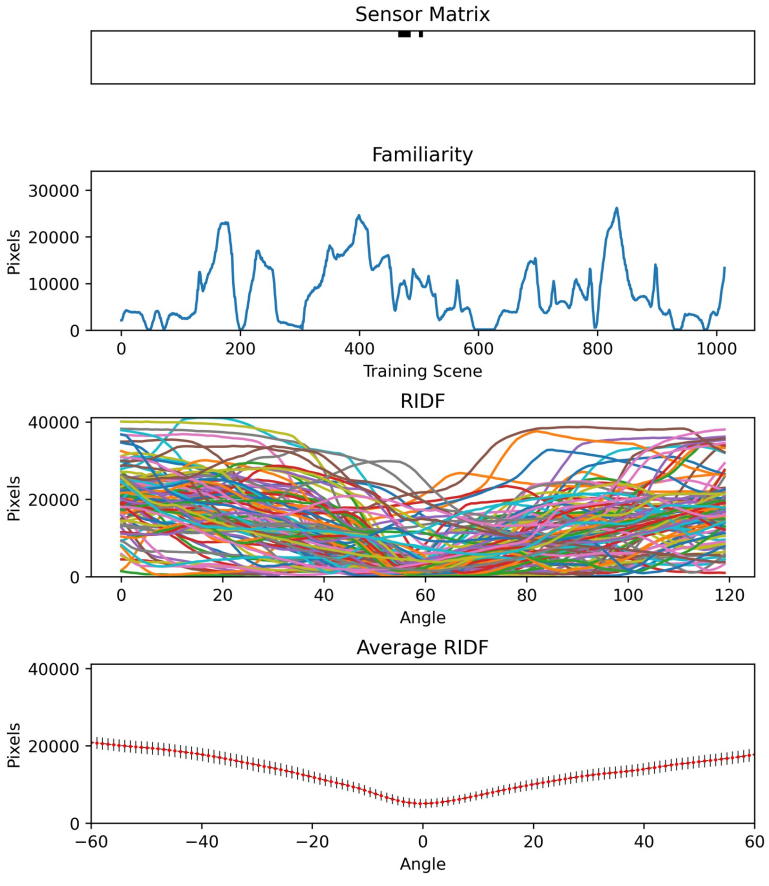

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 9895.19; RMSD/dist: 24.738; TD: 9172; p90: 48; p50: 28; complete: 0