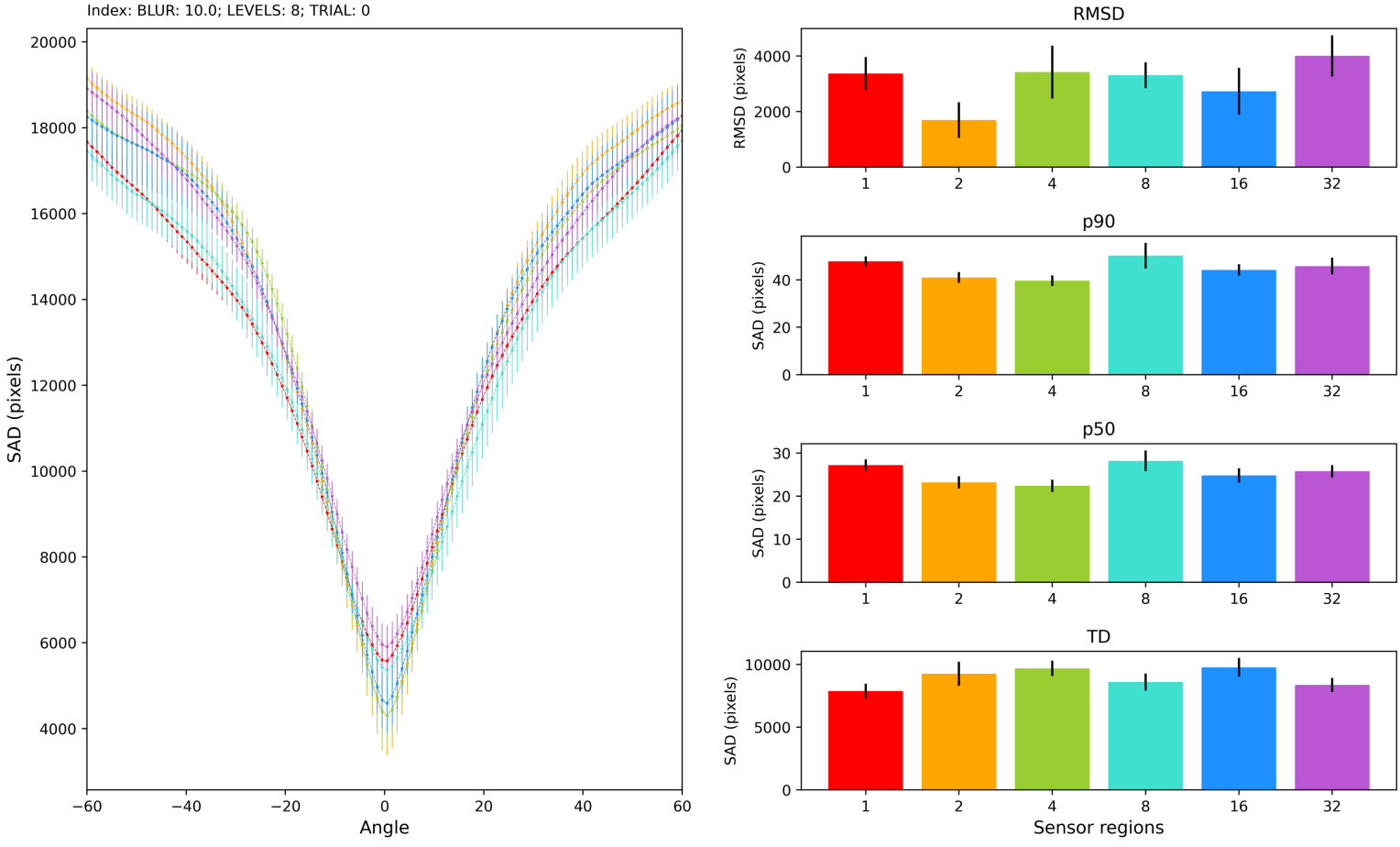
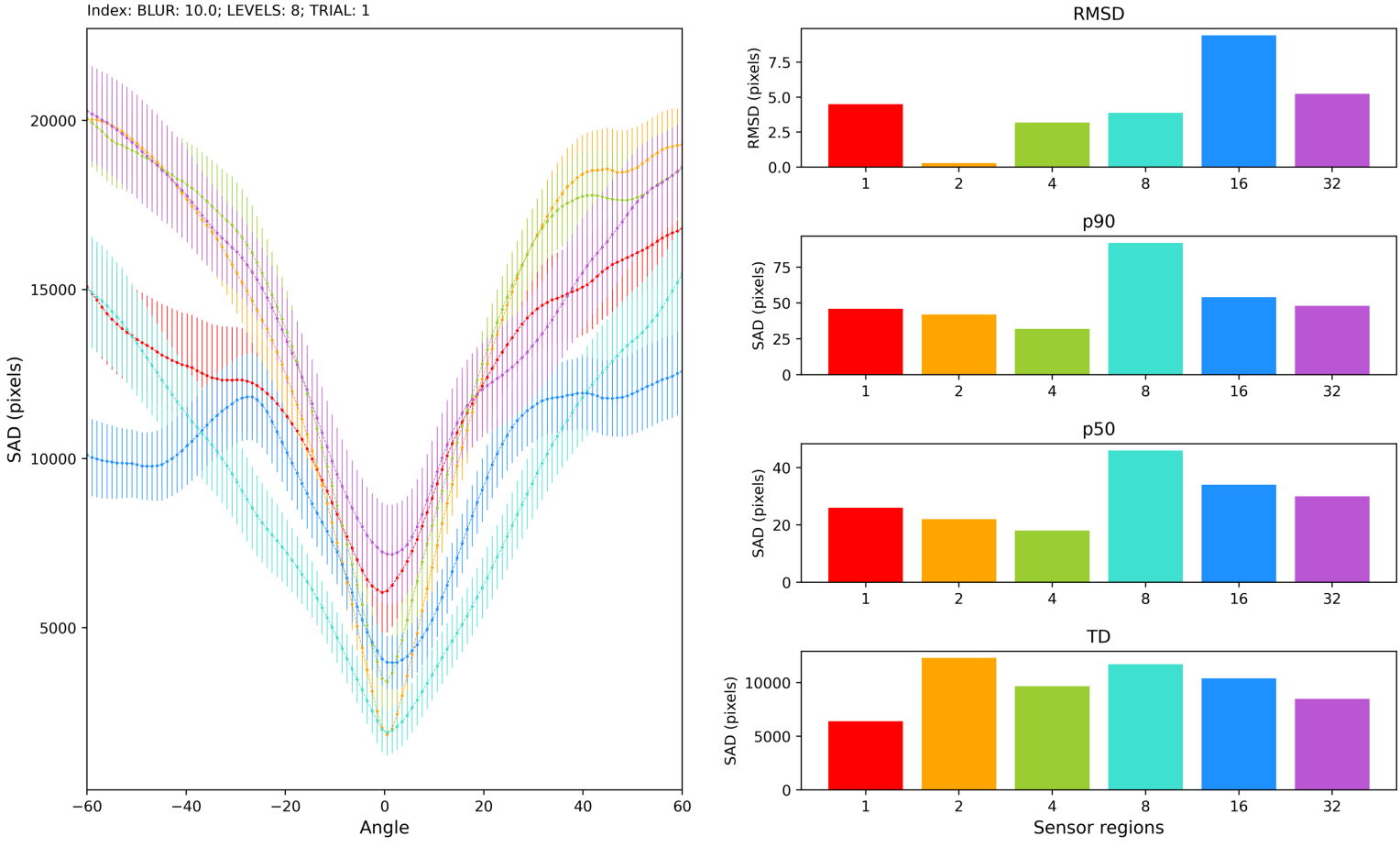
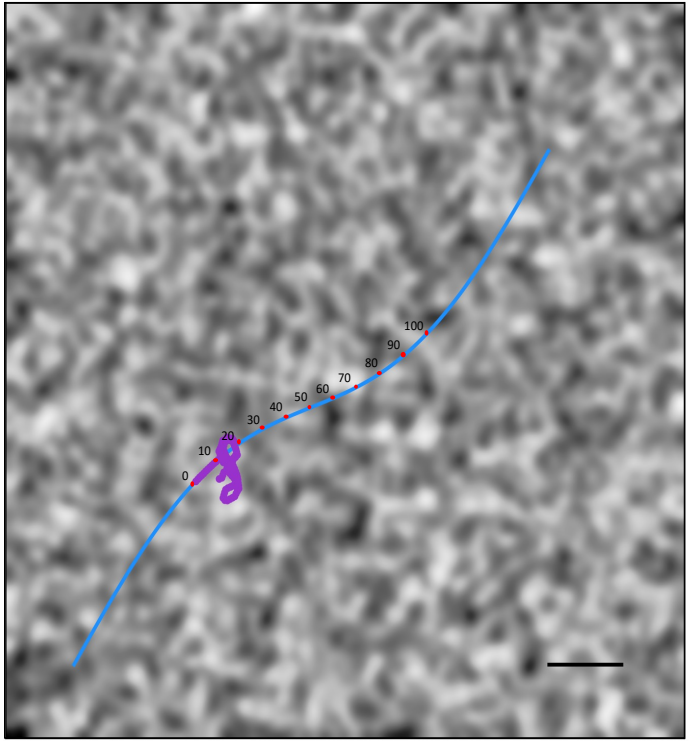
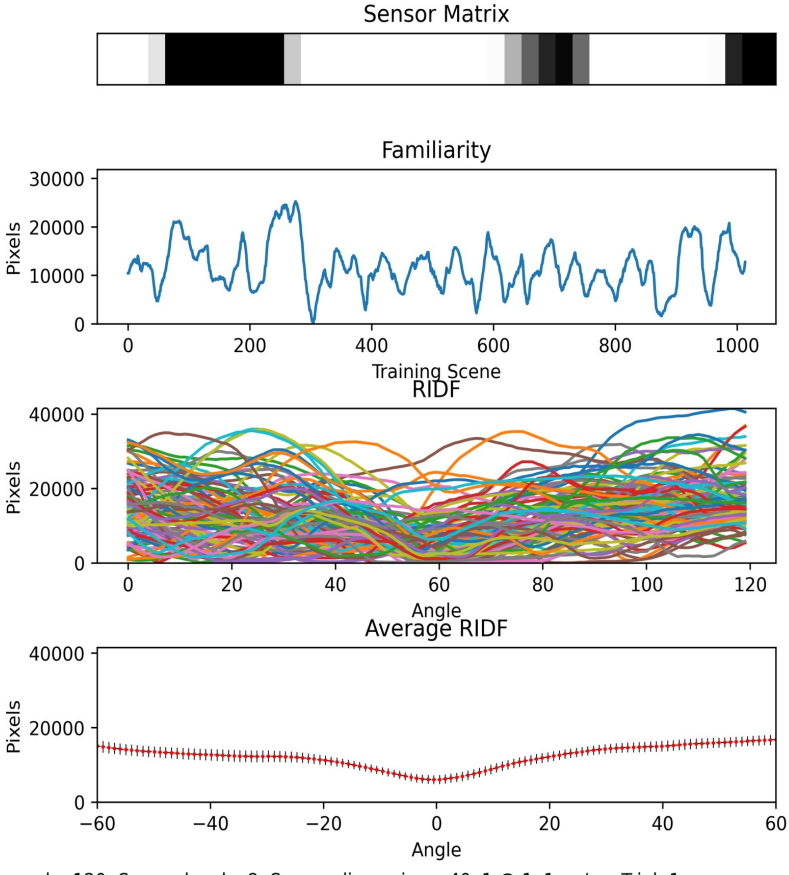

Index: BLUR: 10.0; LEVELS: 8; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 1
SAD (pixels)
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
7.5
5.0
2.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
75
50
25
0
p50
40
20
TD
10000
5000
Sensor regions

10%

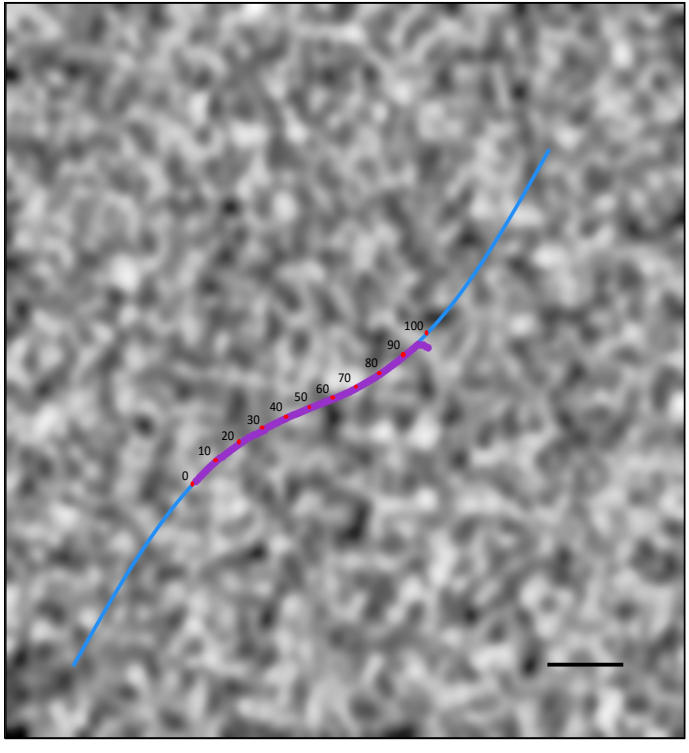


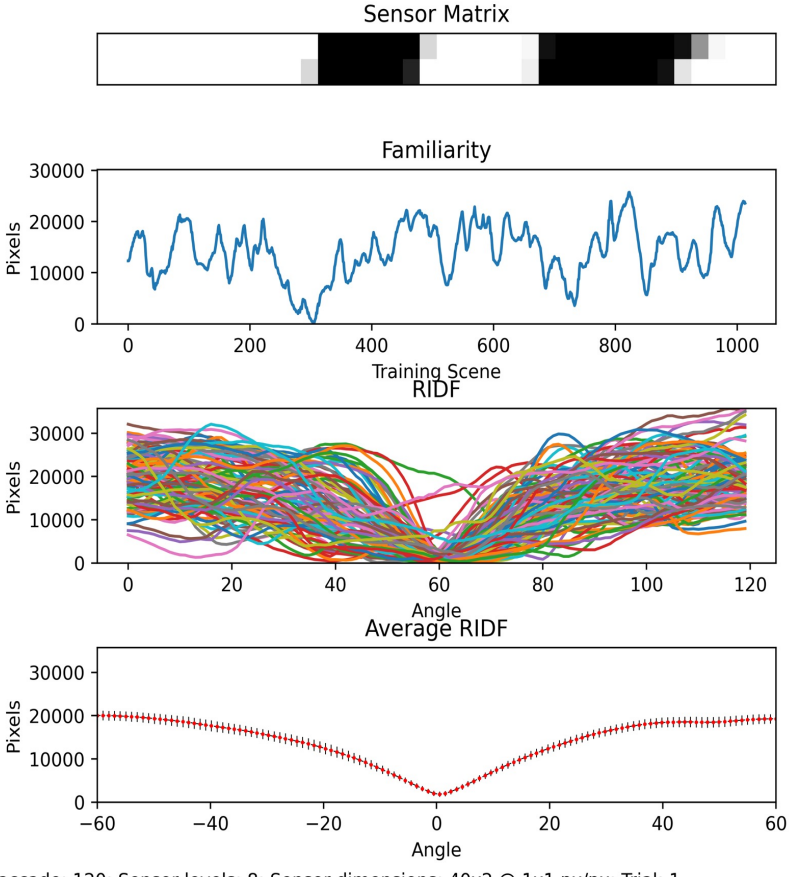


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1800.58; RMSD/dist: 4.501; TD: 6394; p90: 46; p50: 26; complete: 0

90%

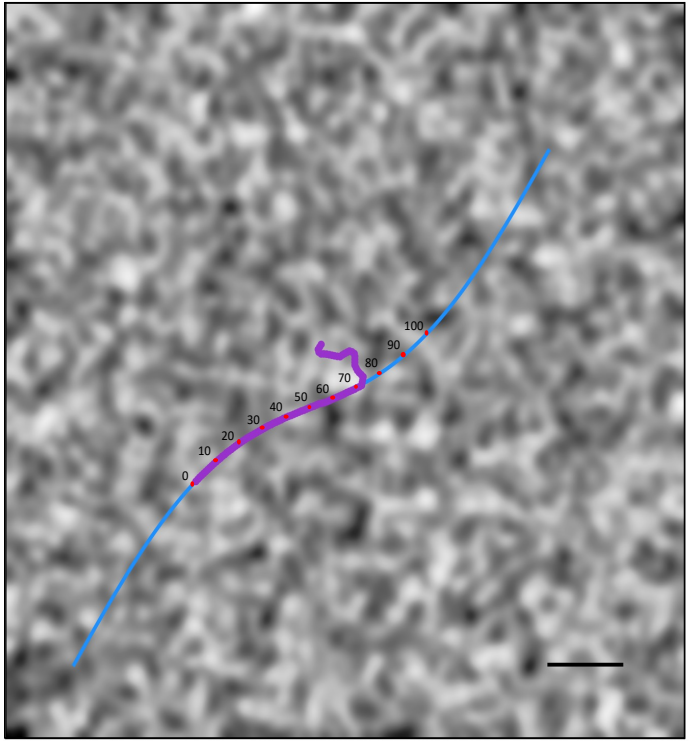


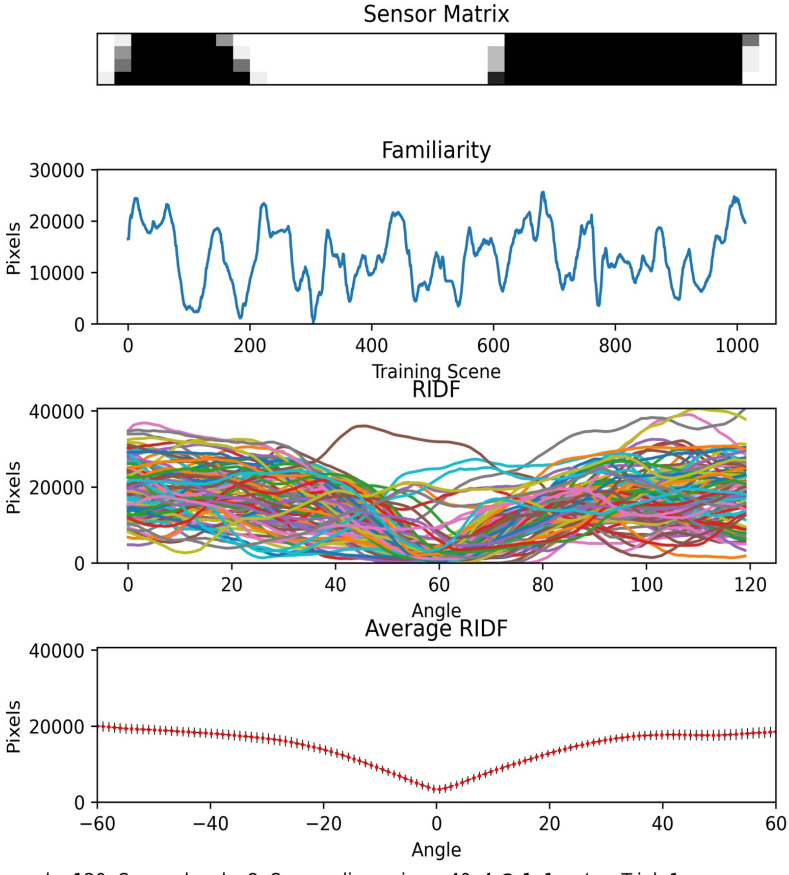


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 112.22; RMSD/dist: 0.281; TD: 12302; p90: 42; p50: 22; complete: 0

70%

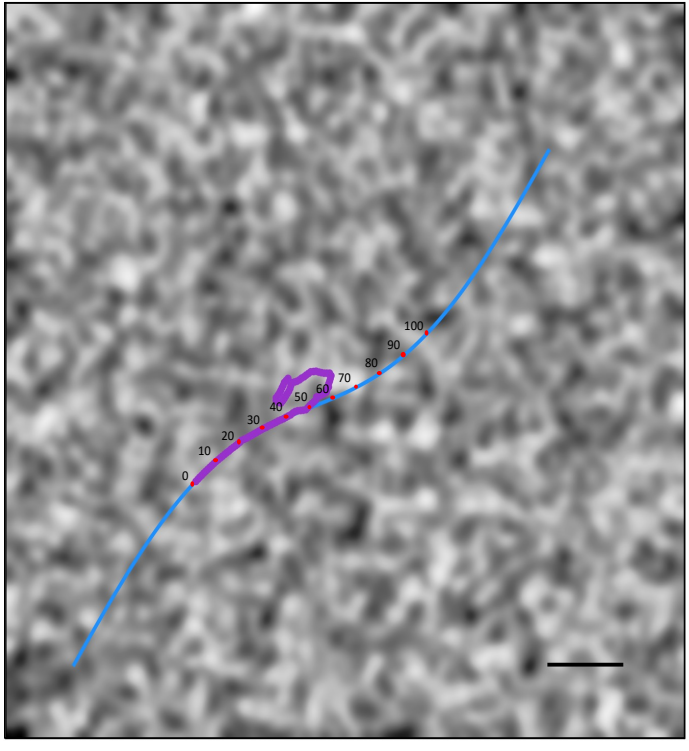


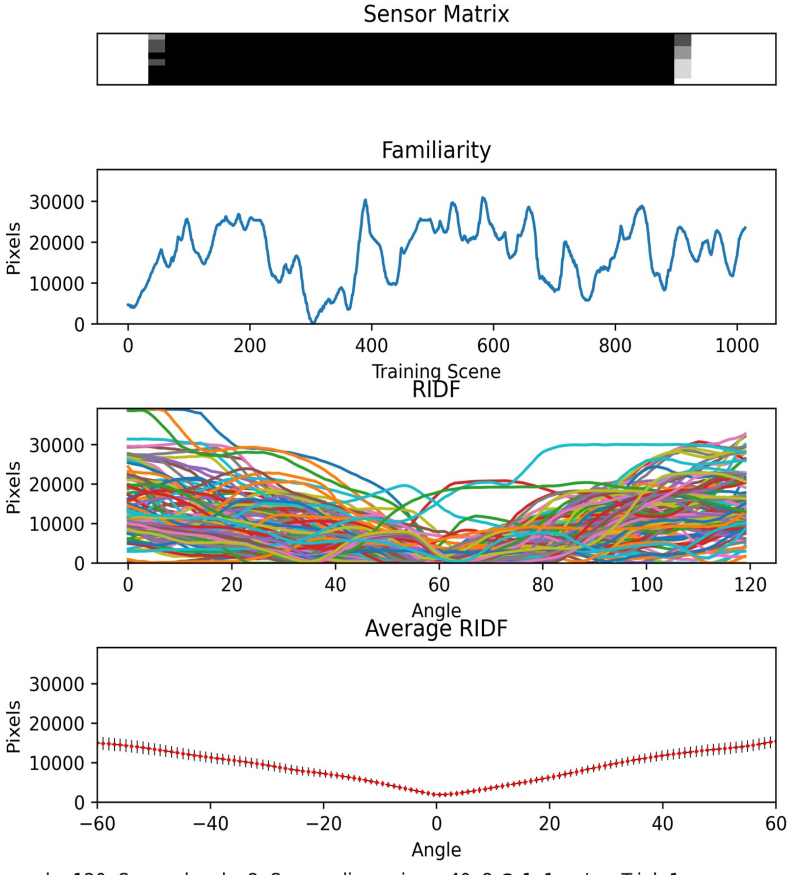


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1271.63; RMSD/dist: 3.179; TD: 9676; p90: 32; p50: 18; complete: 0

40%

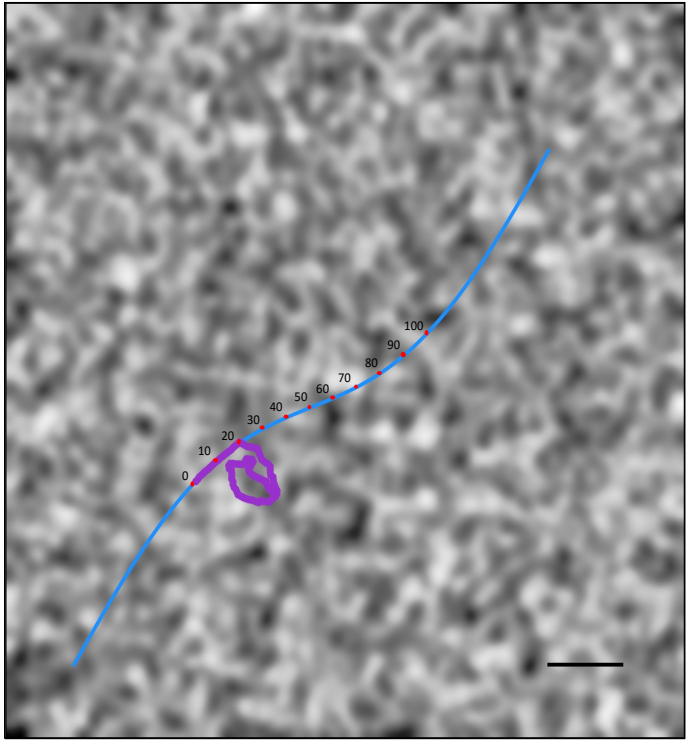


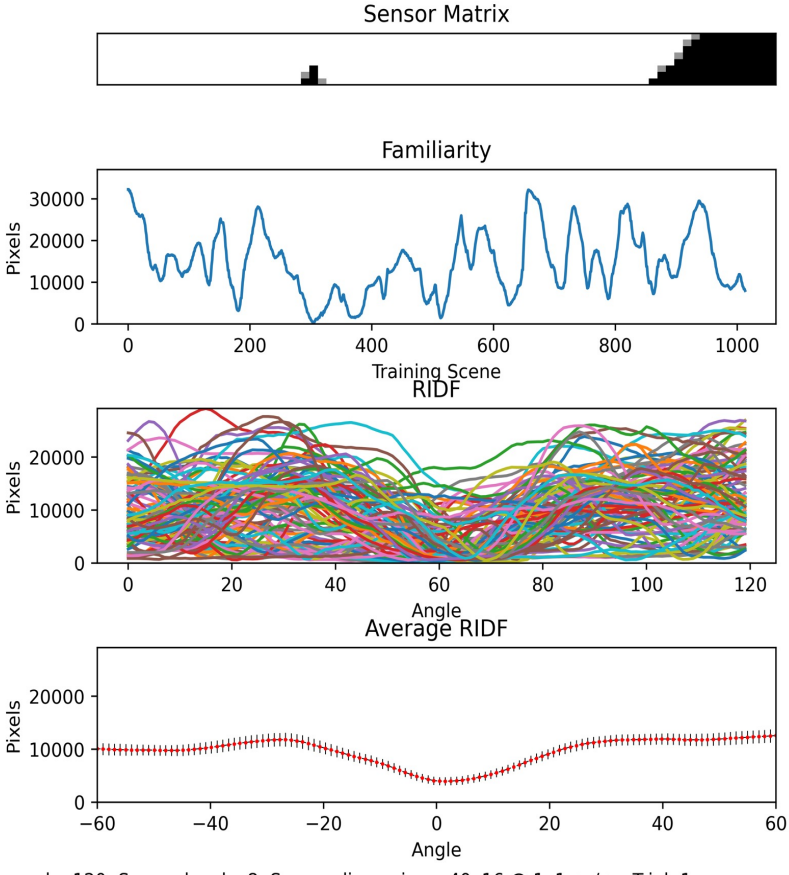


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1549.72; RMSD/dist: 3.874; TD: 11724; p90: 92; p50: 46; complete: 0

20%

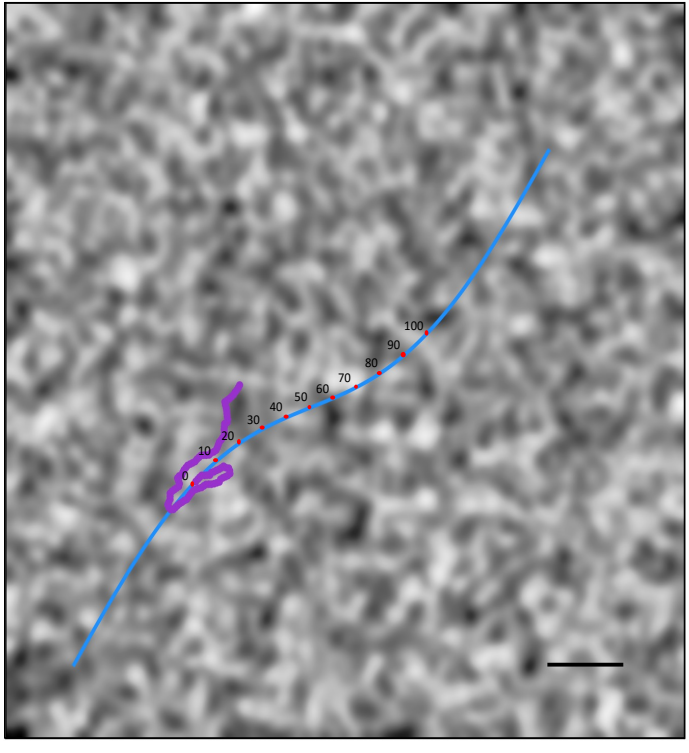


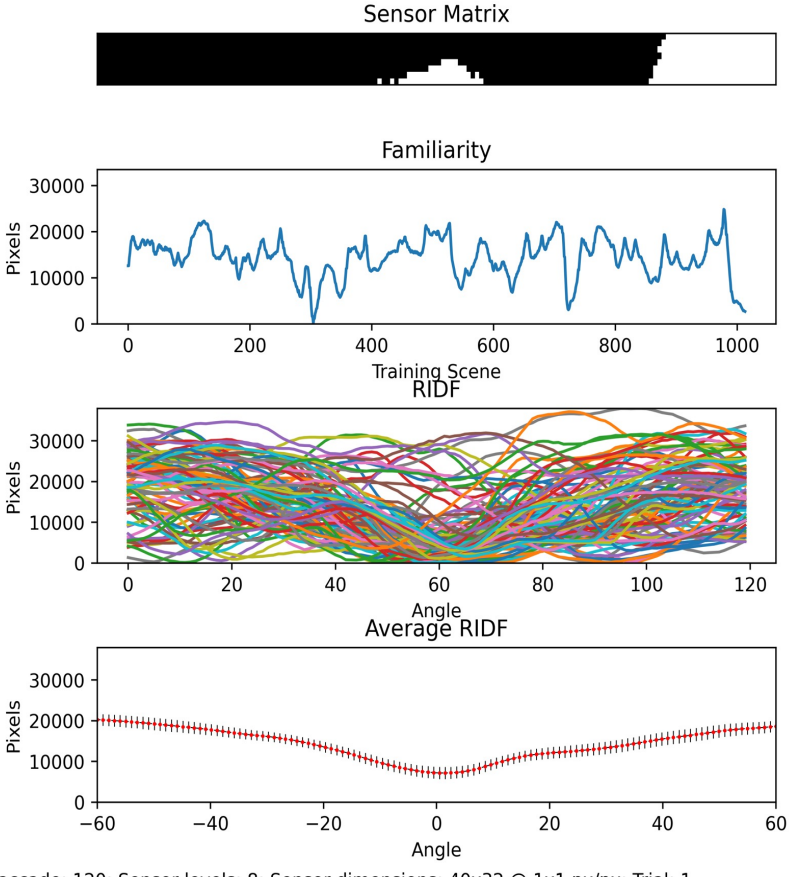


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3771.56; RMSD/dist: 9.429; TD: 10407; p90: 54; p50: 34; complete: 0

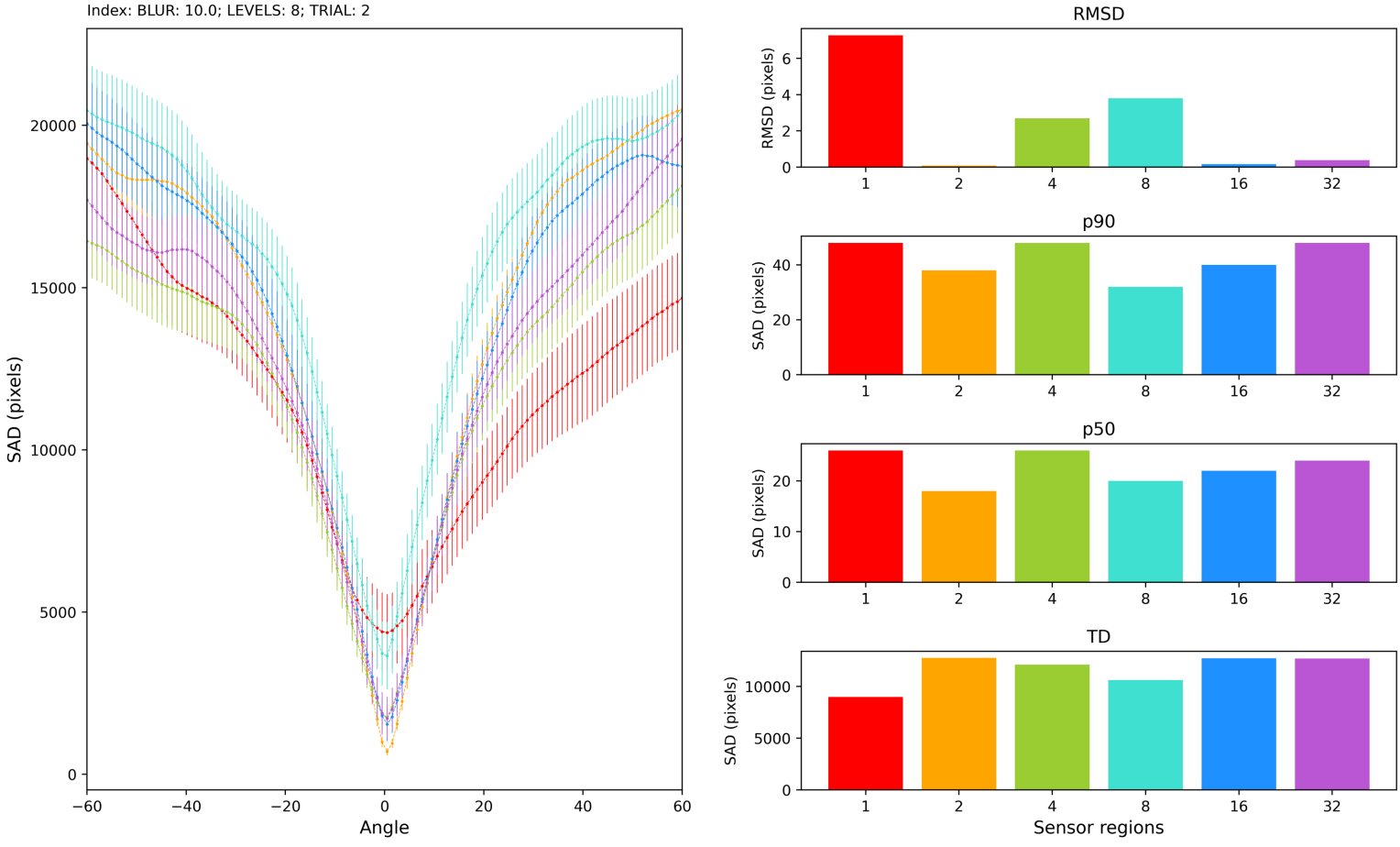
0%



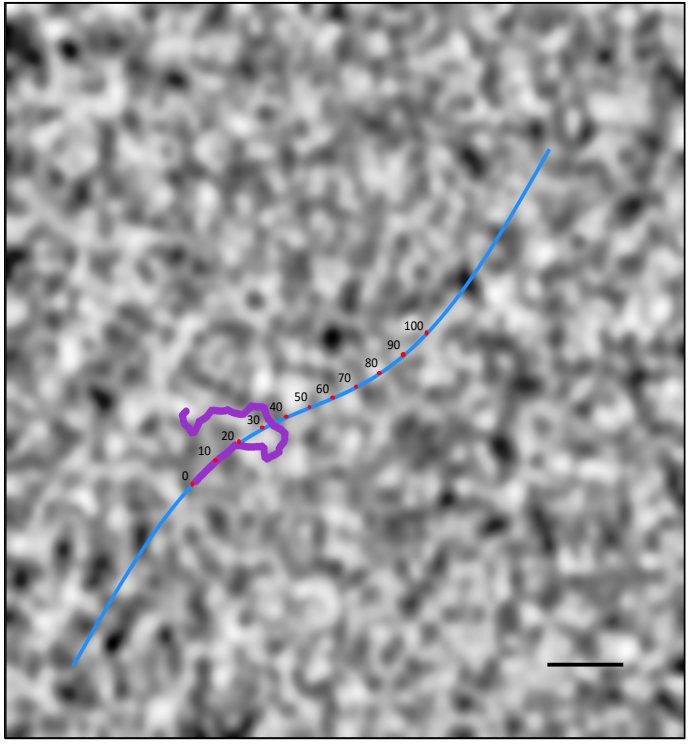


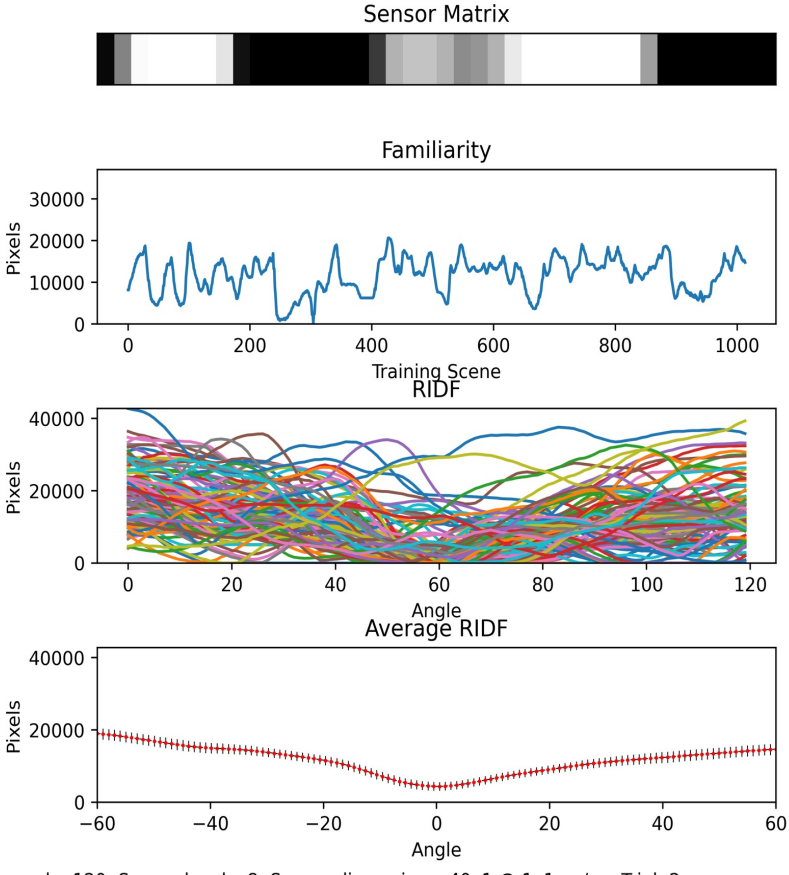
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2097.36; RMSD/dist: 5.243; TD: 8482; p90: 48; p50: 30; complete: 0


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

20%

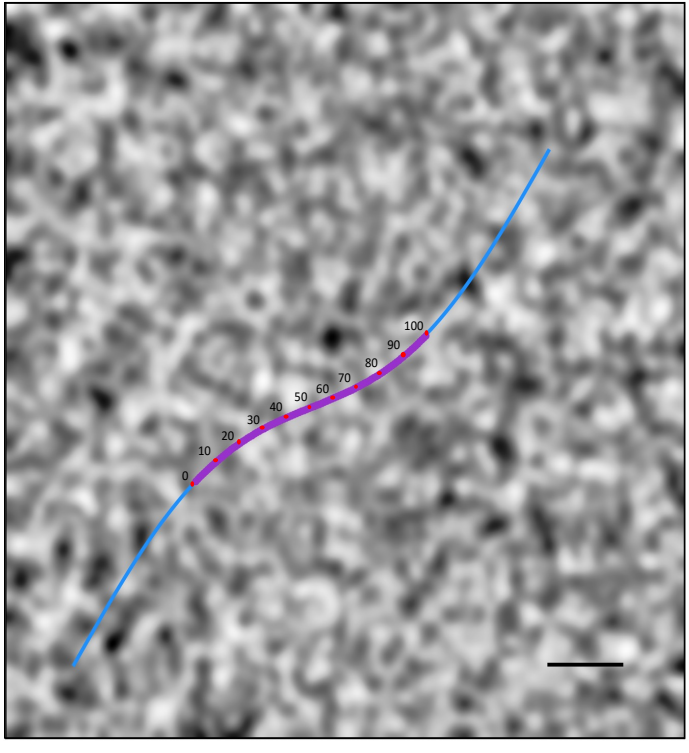


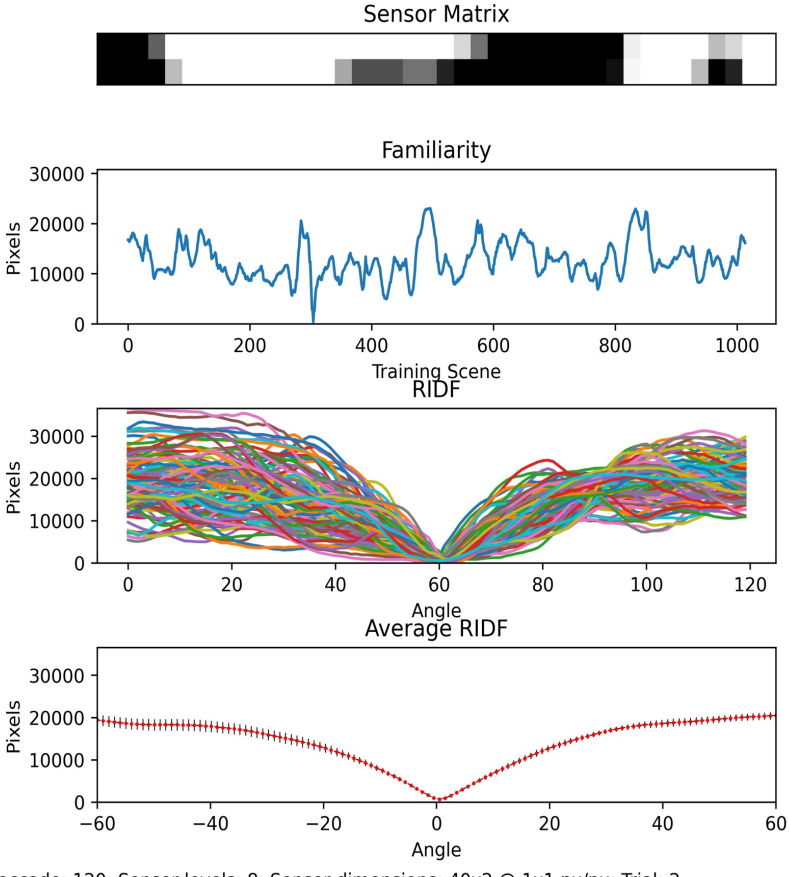


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2912.79; RMSD/dist: 7.282; TD: 8980; p90: 48; p50: 26; complete: 0

0%

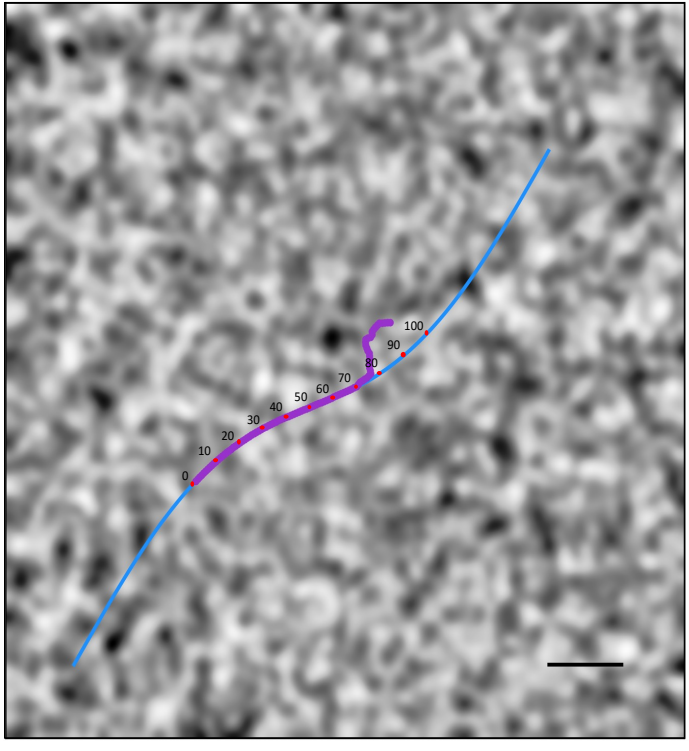


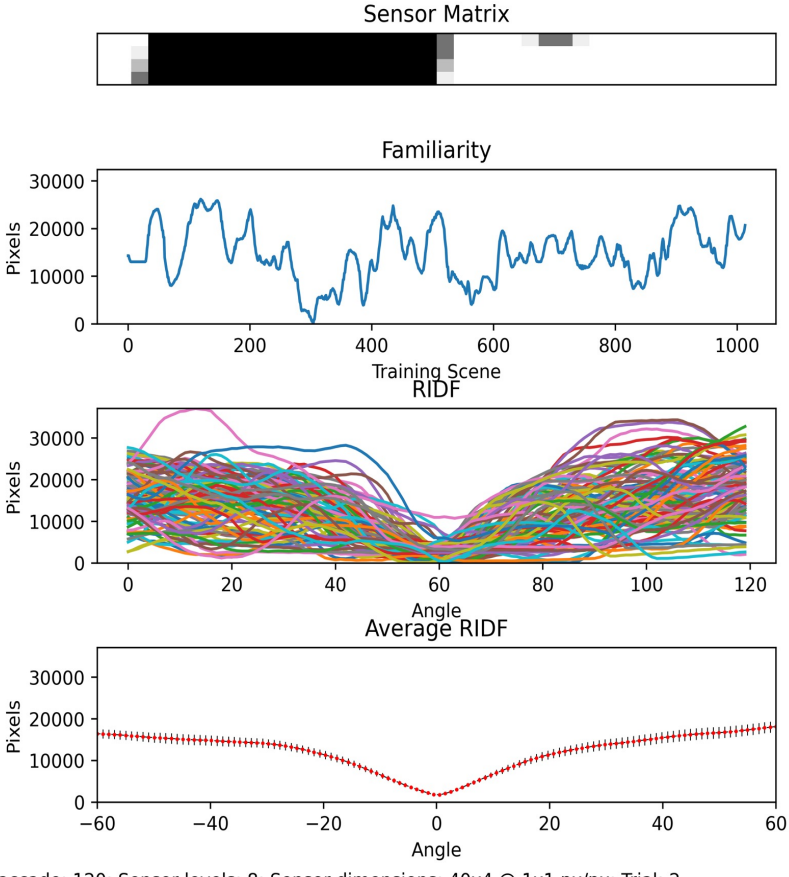


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 30.22; RMSD/dist: 0.076; TD: 12742; p90: 38; p50: 18; complete: 0

70%

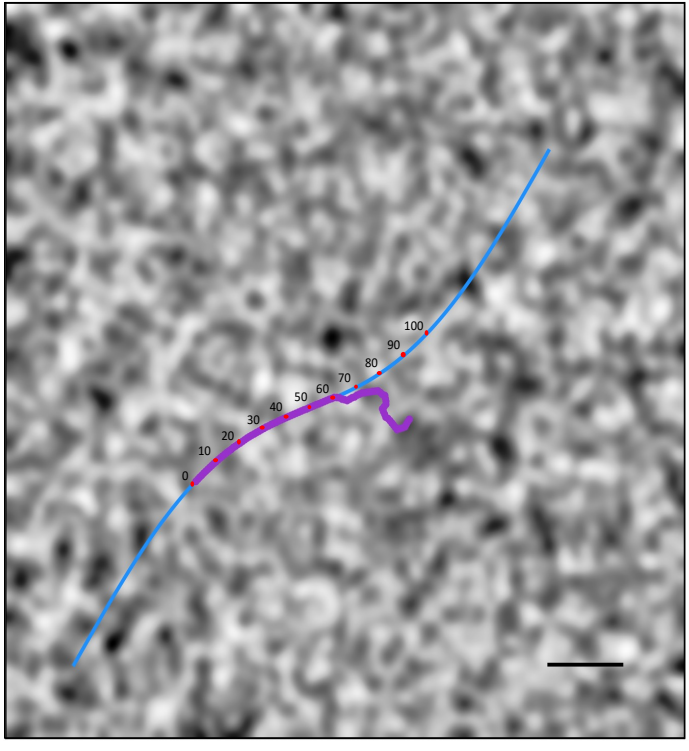


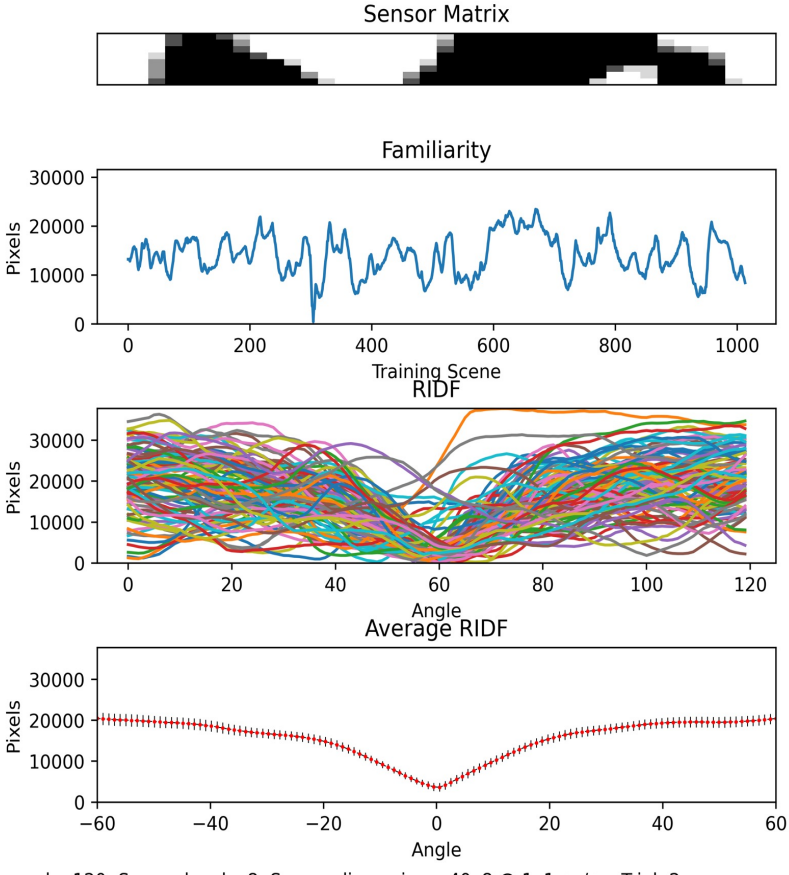


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1076.09; RMSD/dist: 2.690; TD: 12104; p90: 48; p50: 26; complete: 0

60%

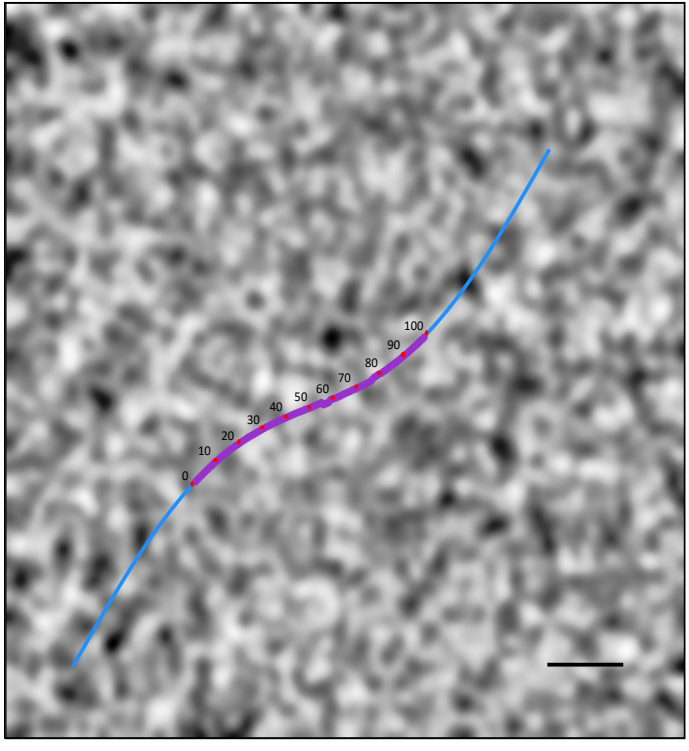


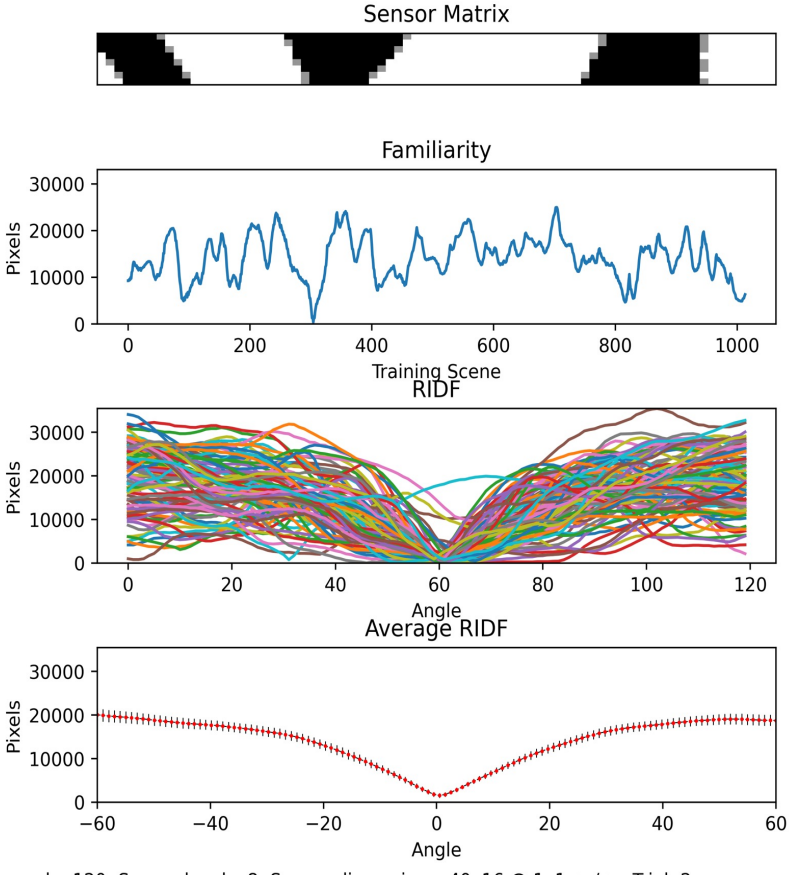


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1519.16; RMSD/dist: 3.798; TD: 10613; p90: 32; p50: 20; complete: 0

90%

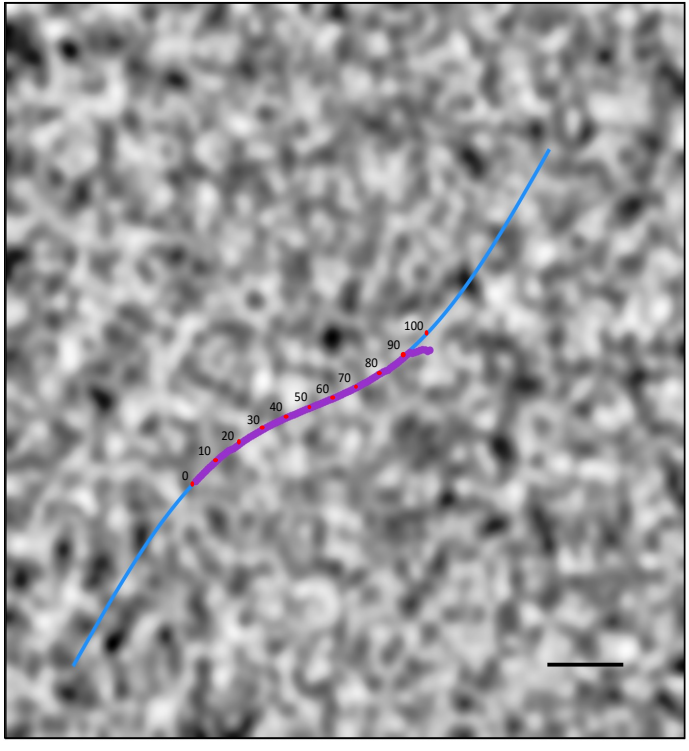


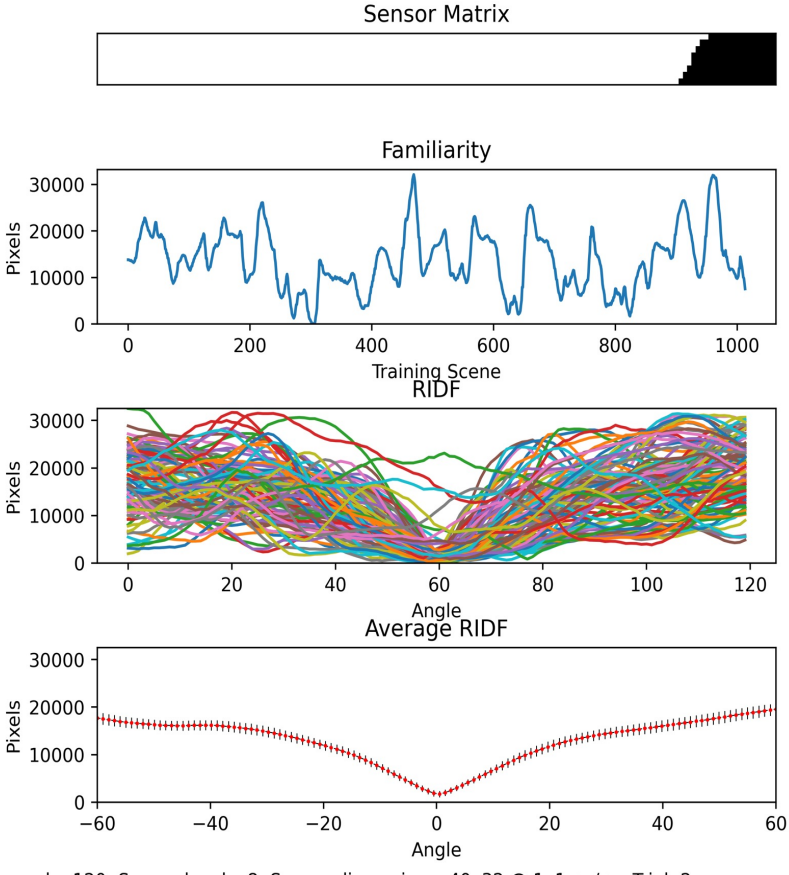


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 62.80; RMSD/dist: 0.157; TD: 12708; p90: 40; p50: 22; complete: 0

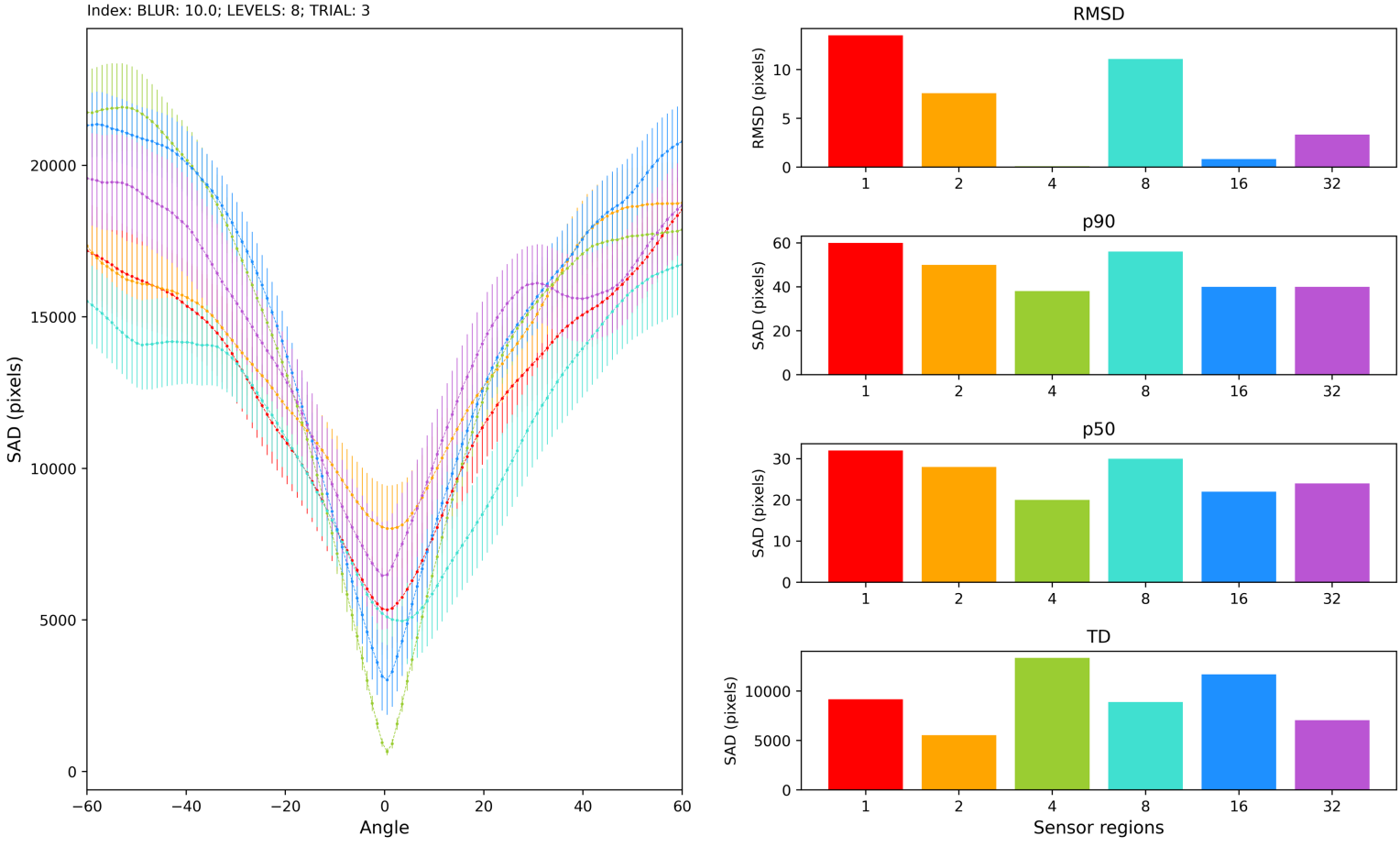
90%



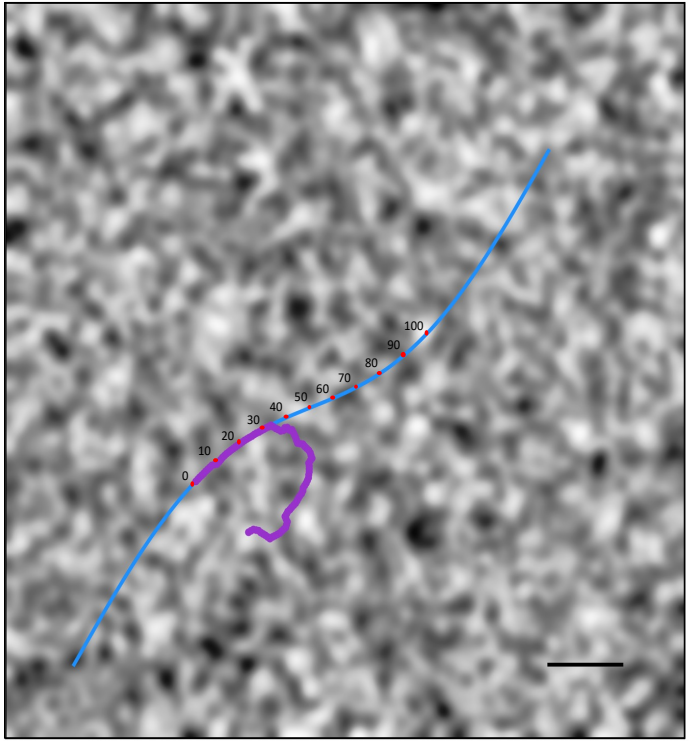


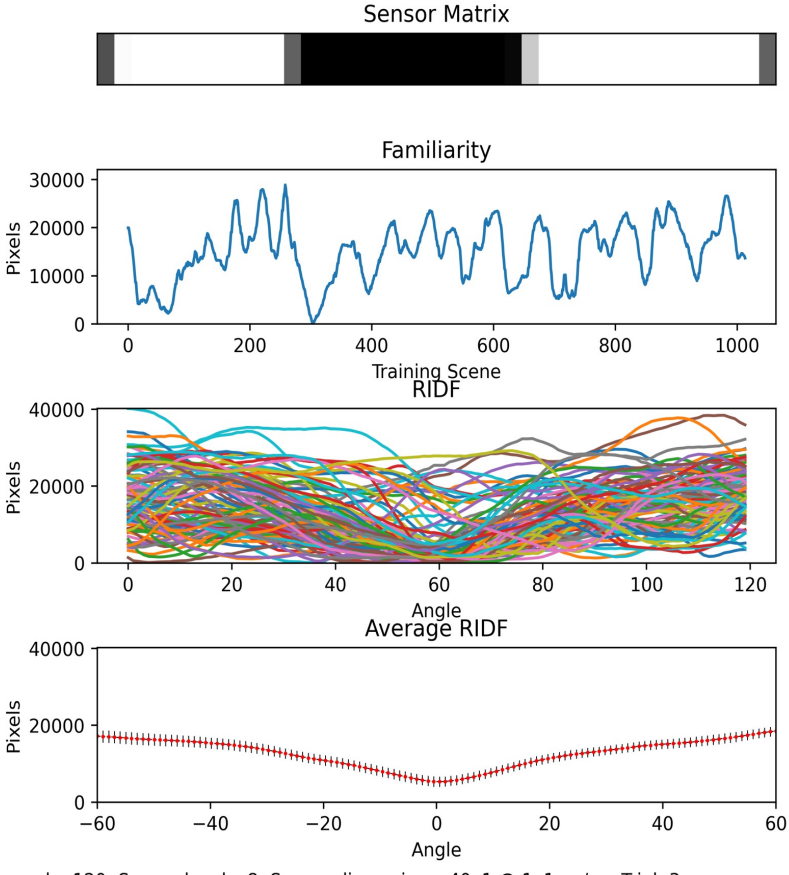
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 152.81; RMSD/dist: 0.382; TD: 12682; p90: 48; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

30%

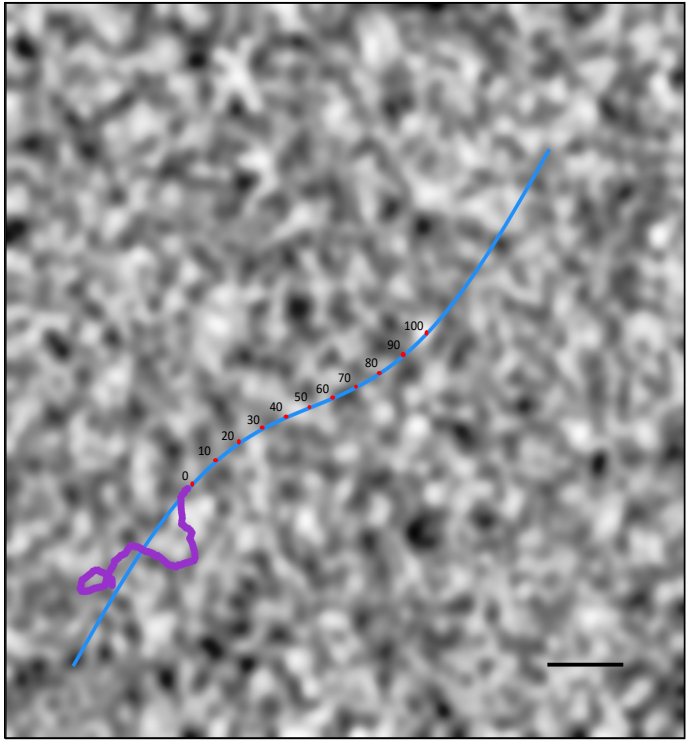


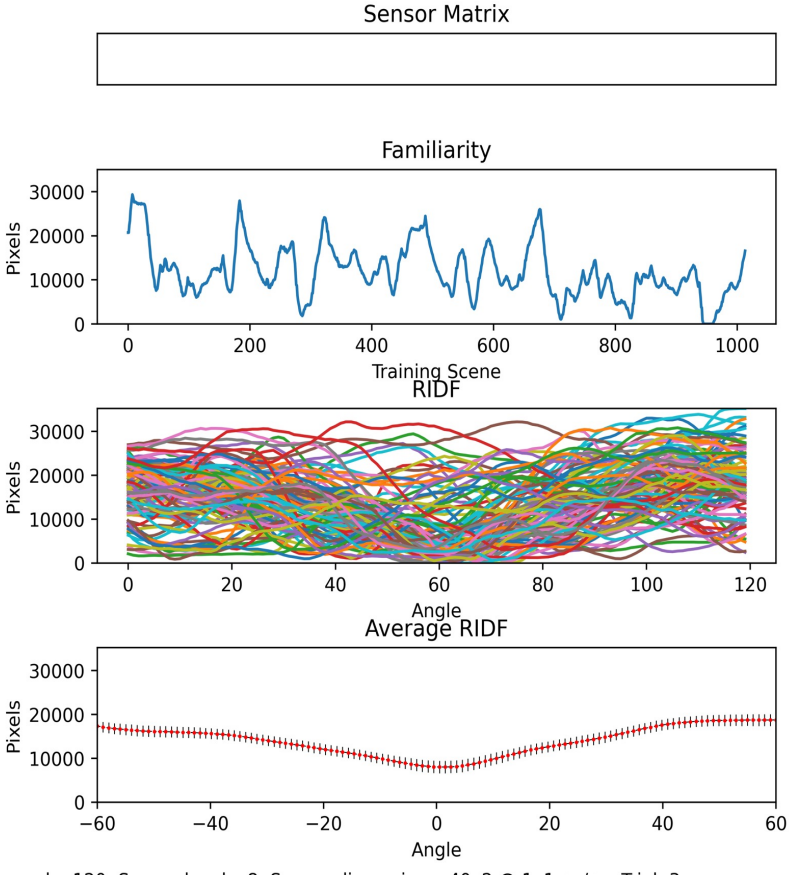


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 5411.10; RMSD/dist: 13.528; TD: 9167; p90: 60; p50: 32; complete: 0

0%

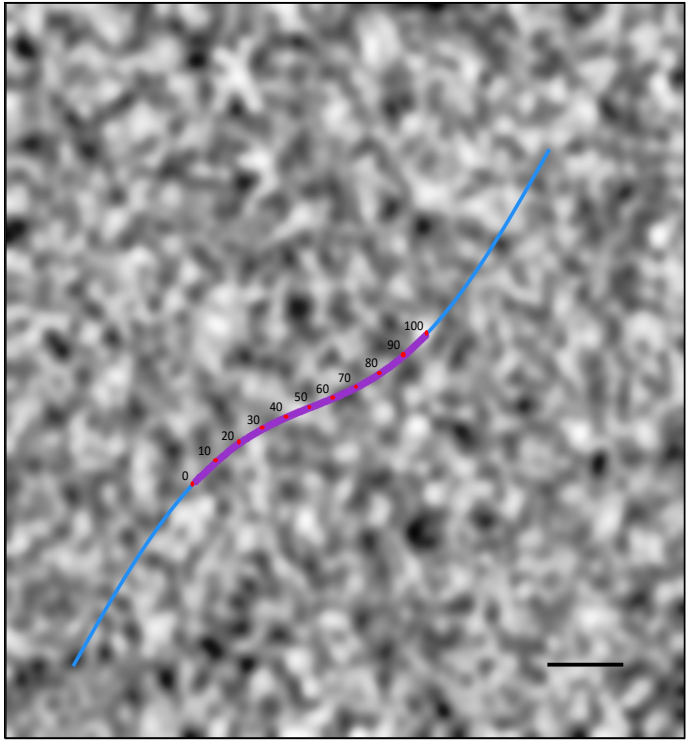


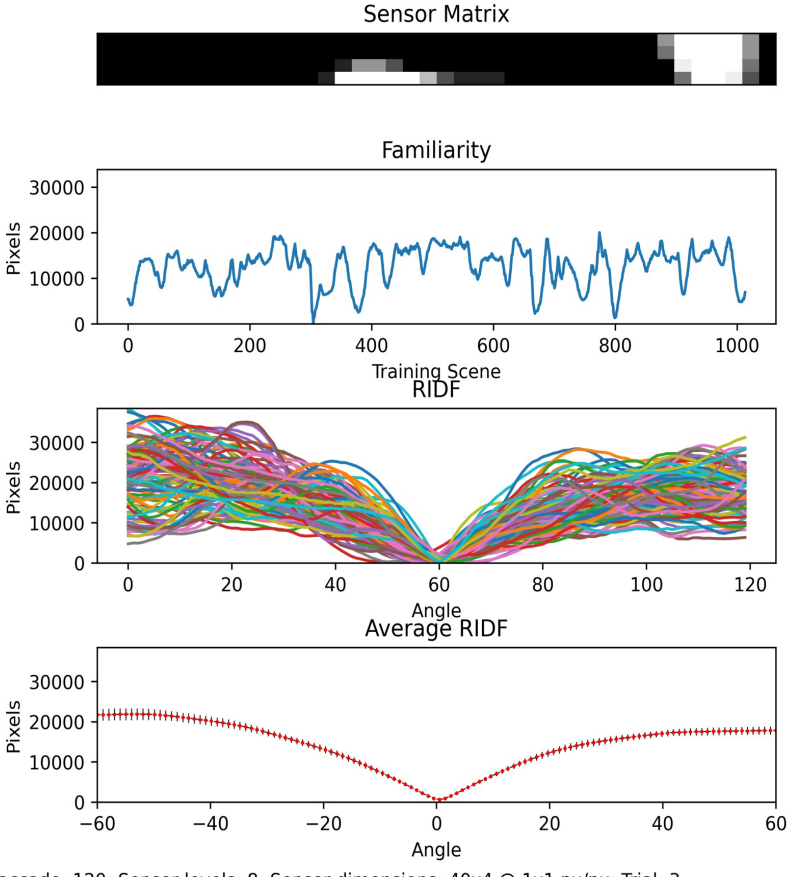


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 3033.89; RMSD/dist: 7.585; TD: 5518; p90: 50; p50: 28; complete: 0

100%

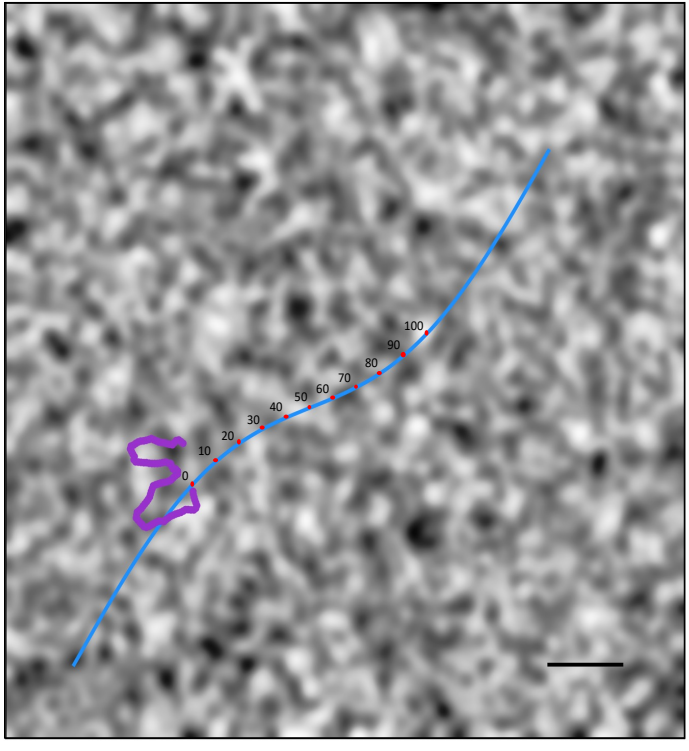


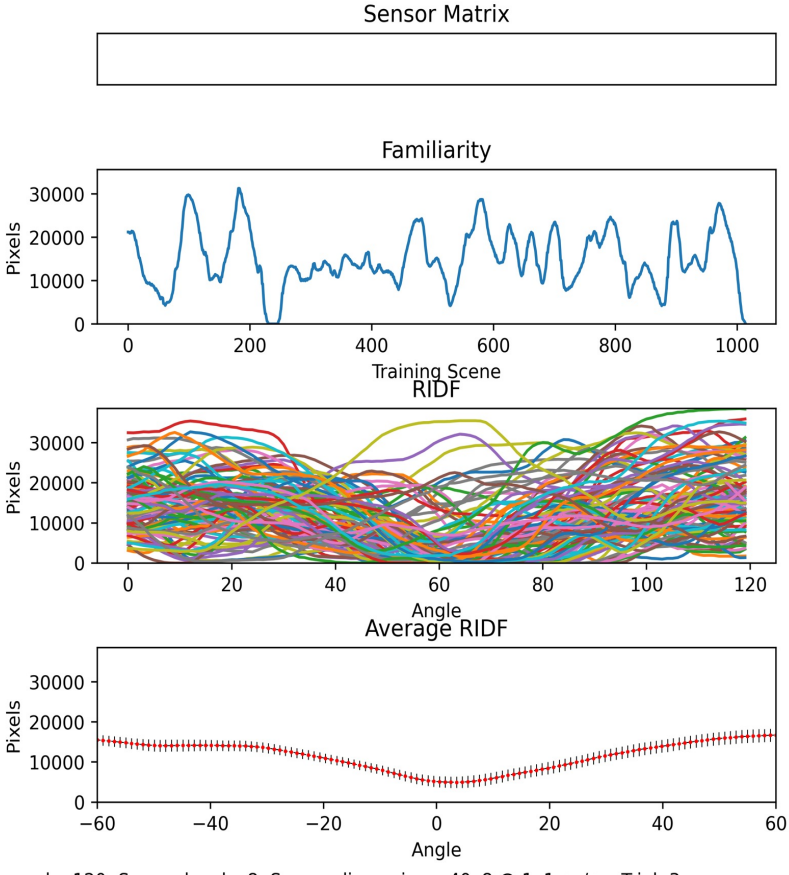


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 32.29; RMSD/dist: 0.081; TD: 13337; p90: 38; p50: 20; complete: 0

0%

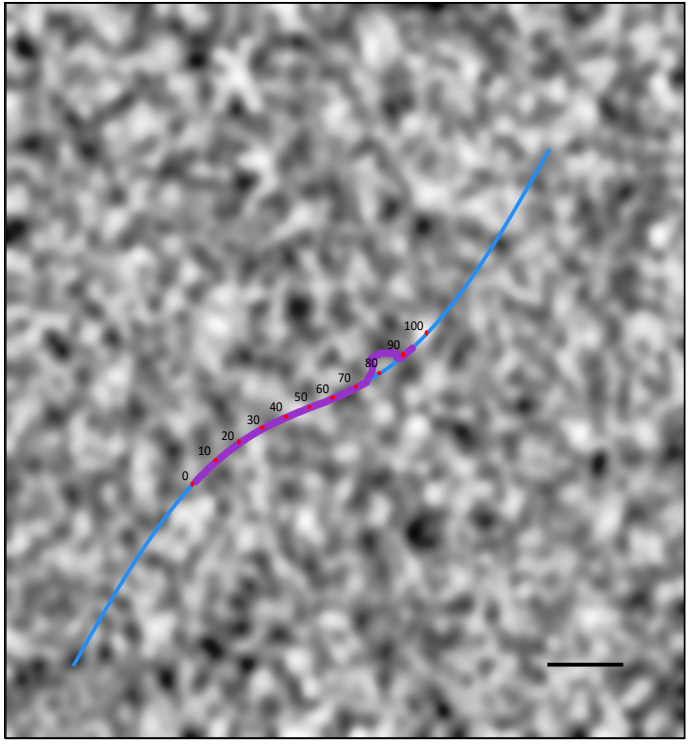


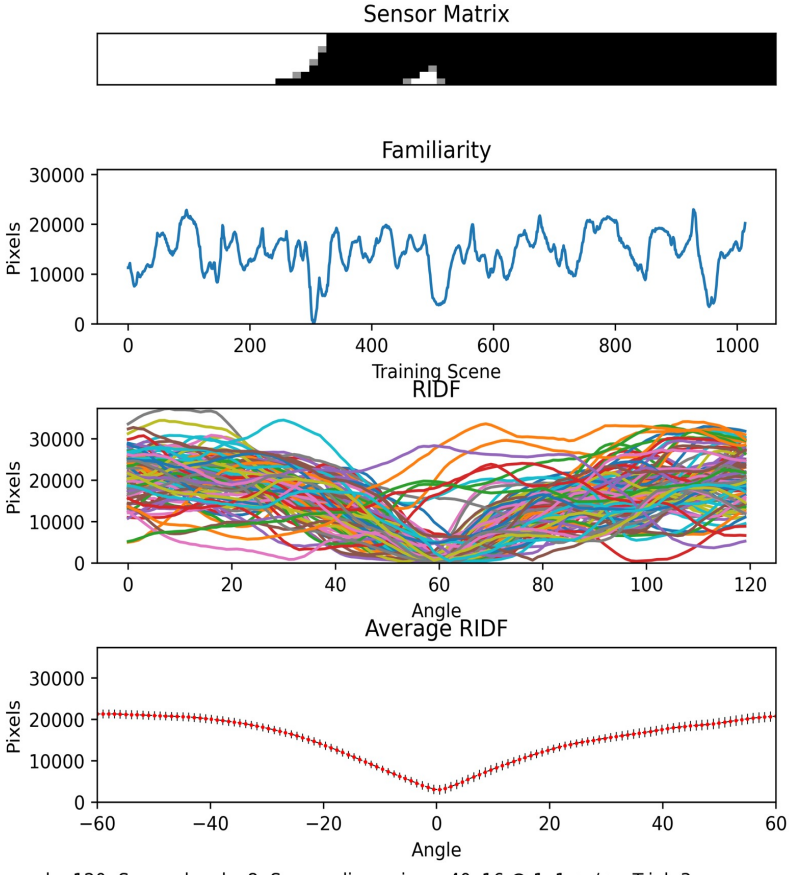


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4432.11; RMSD/dist: 11.080; TD: 8877; p90: 56; p50: 30; complete: 0

70%

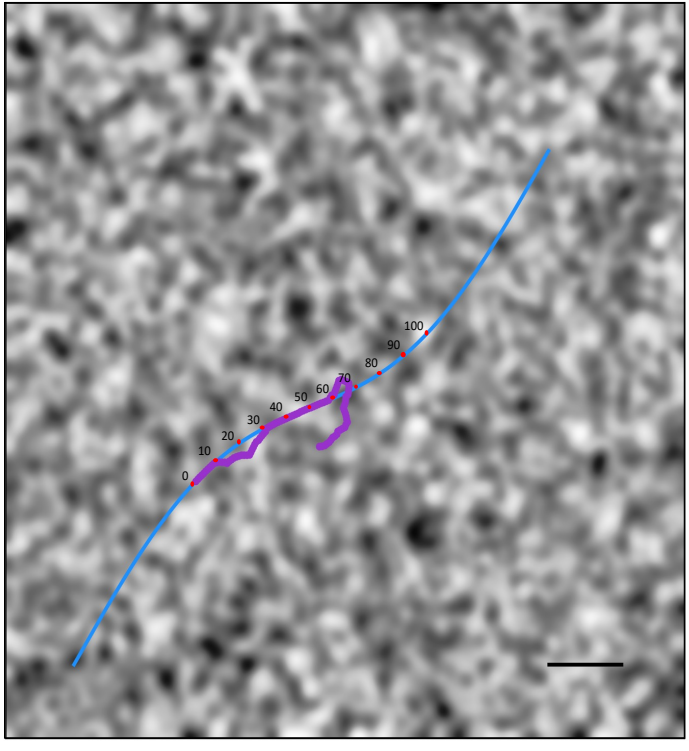


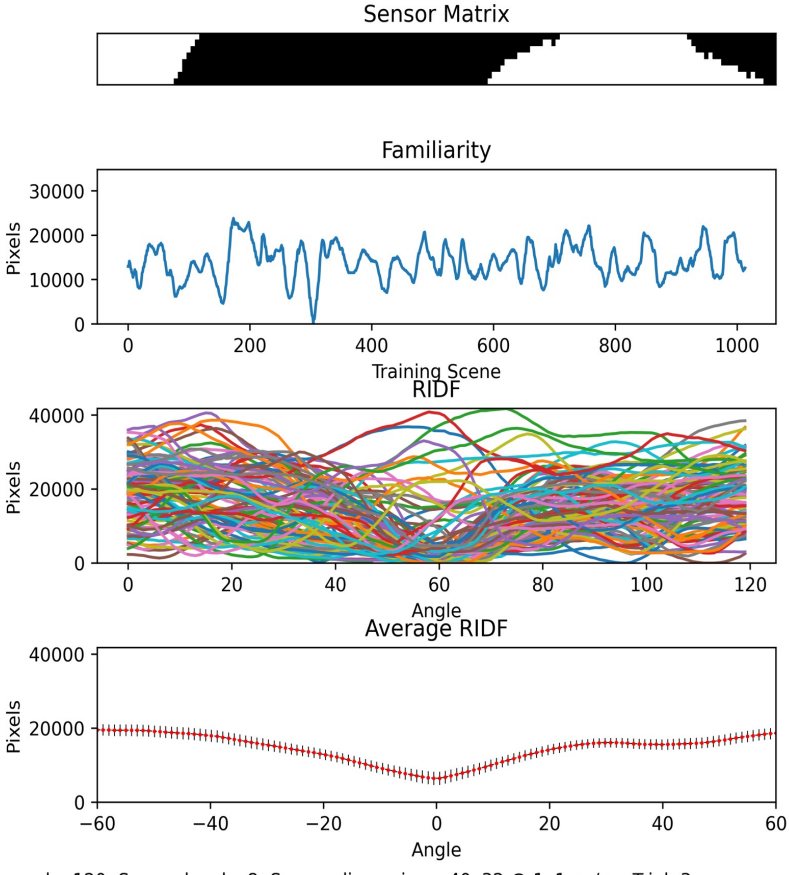


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 329.31; RMSD/dist: 0.823; TD: 11690; p90: 40; p50: 22; complete: 0

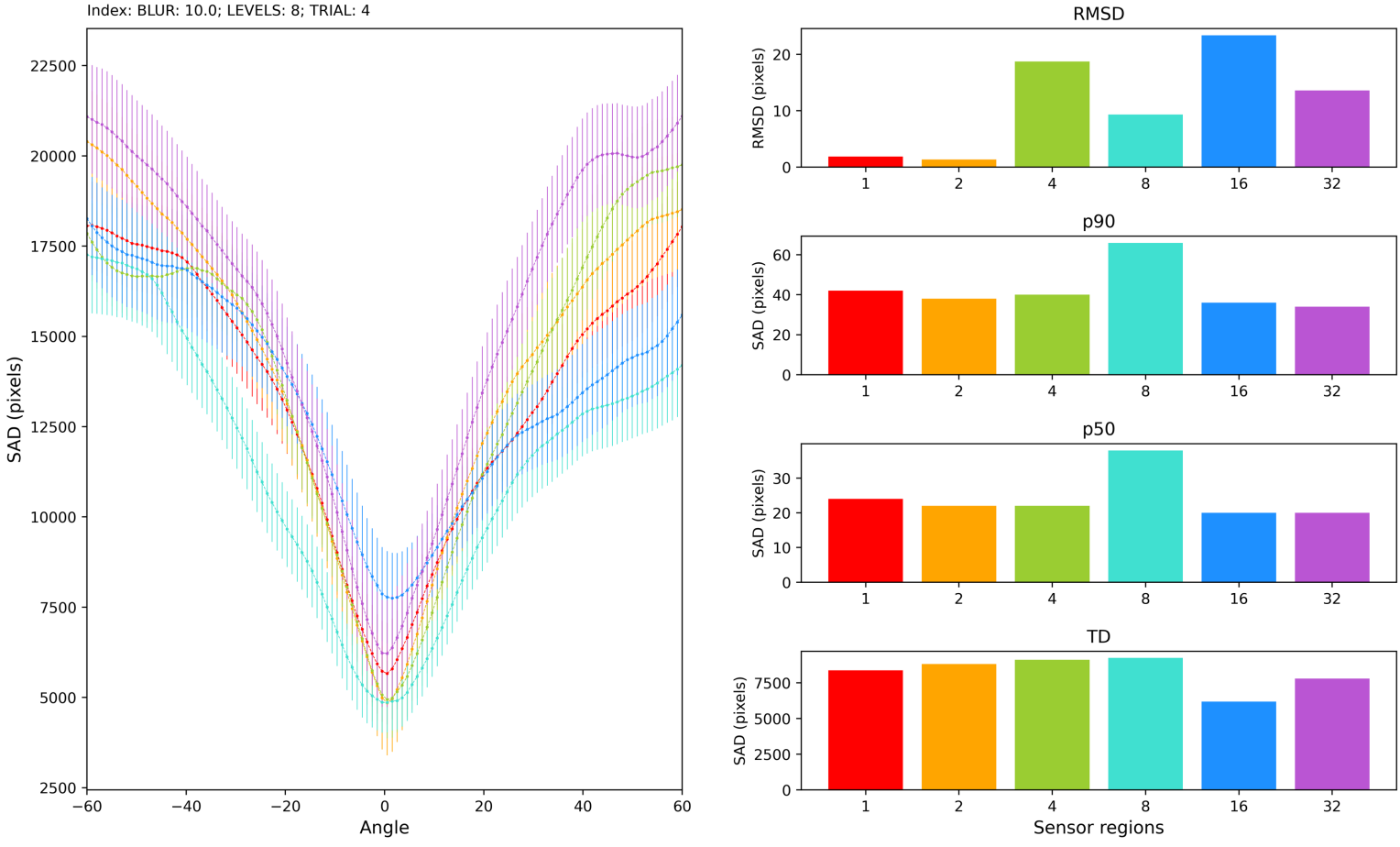
30%



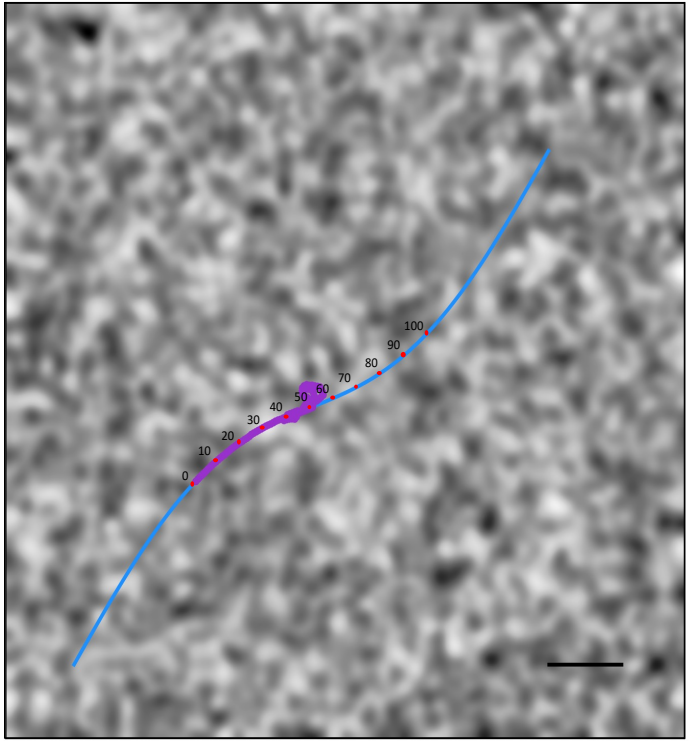


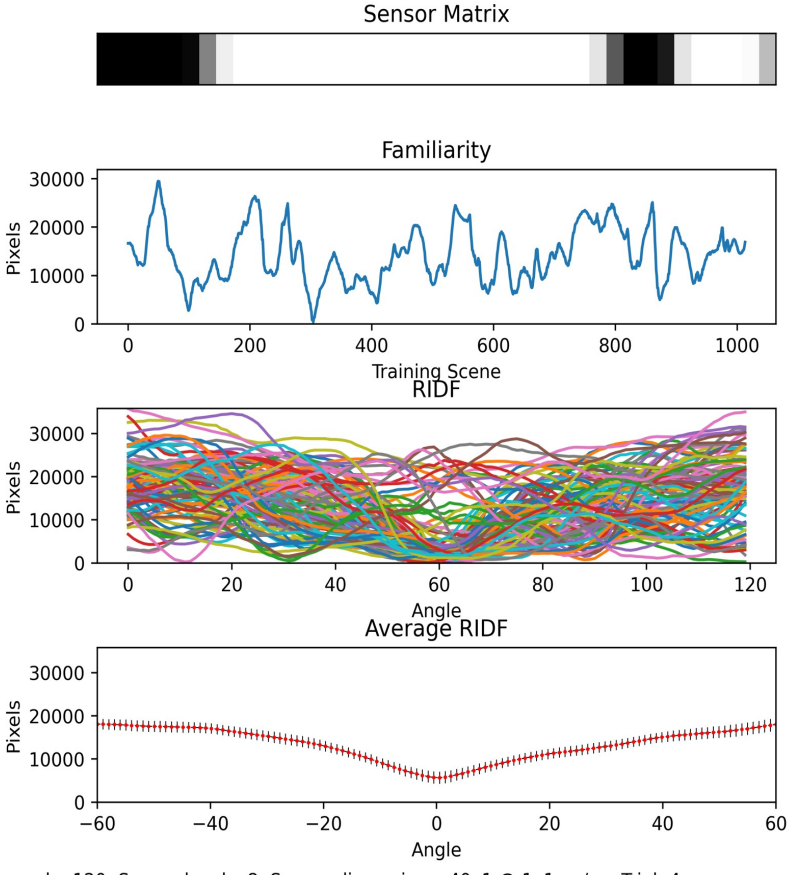
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1335.46; RMSD/dist: 3.339; TD: 7051; p90: 40; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

50%

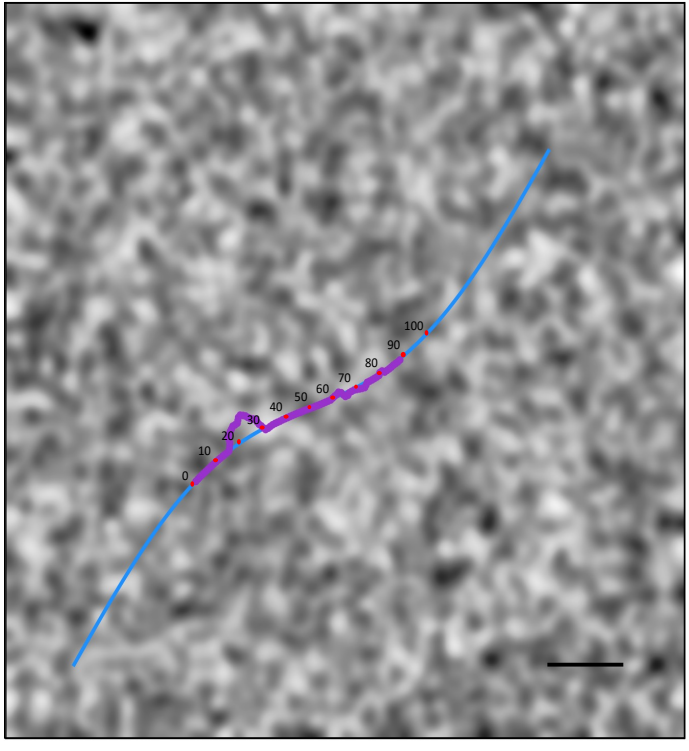


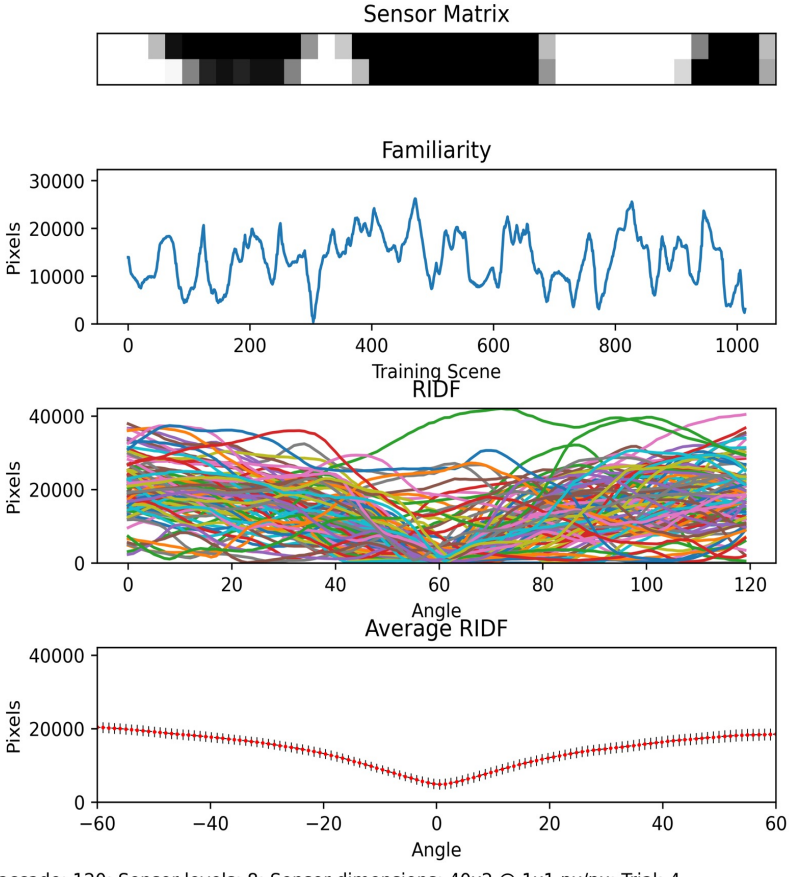


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 744.57; RMSD/dist: 1.861; TD: 8379; p90: 42; p50: 24; complete: 0

50%

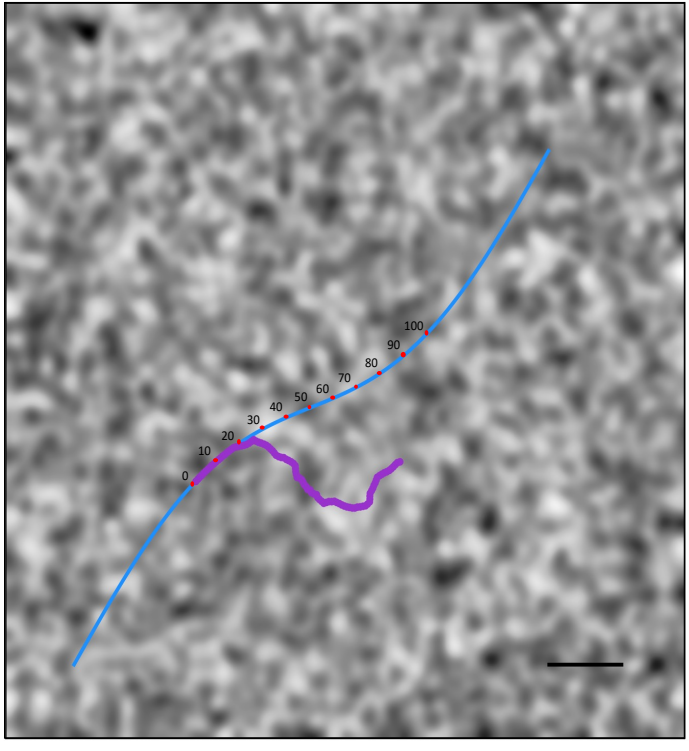


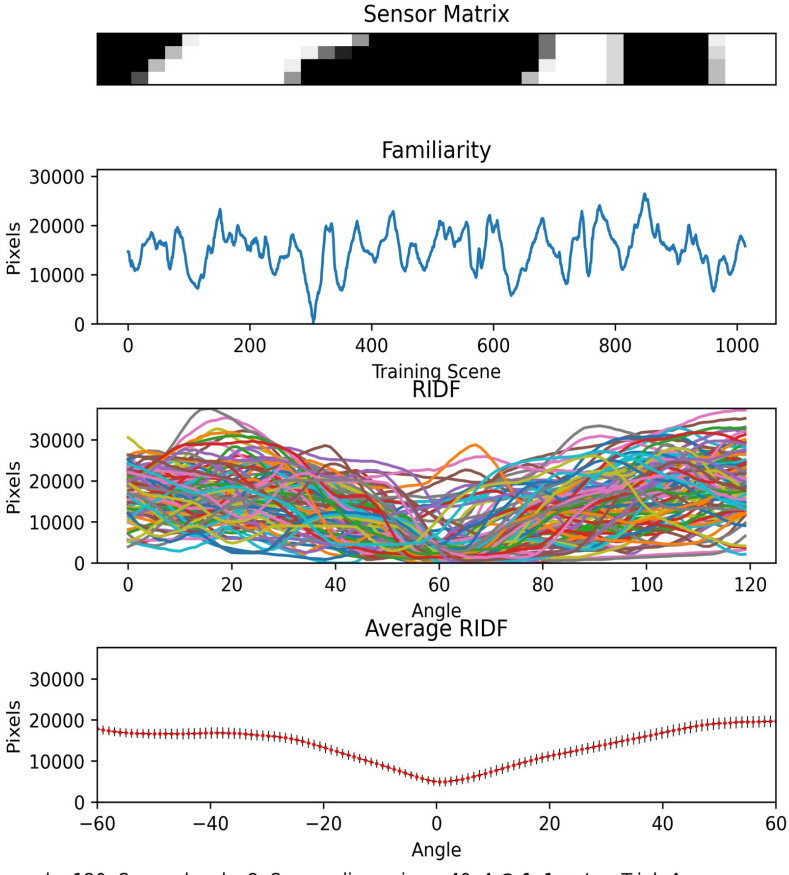


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 542.16; RMSD/dist: 1.355; TD: 8823; p90: 38; p50: 22; complete: 0

10%

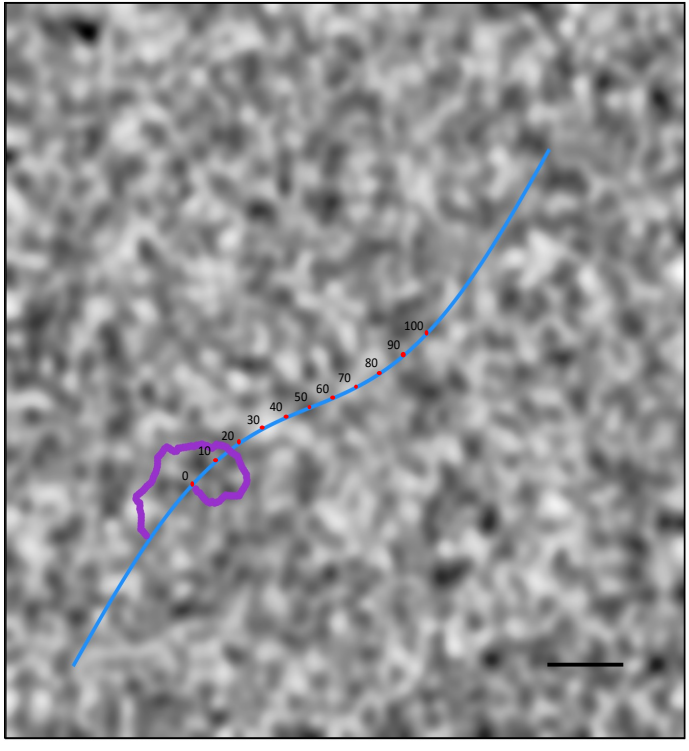


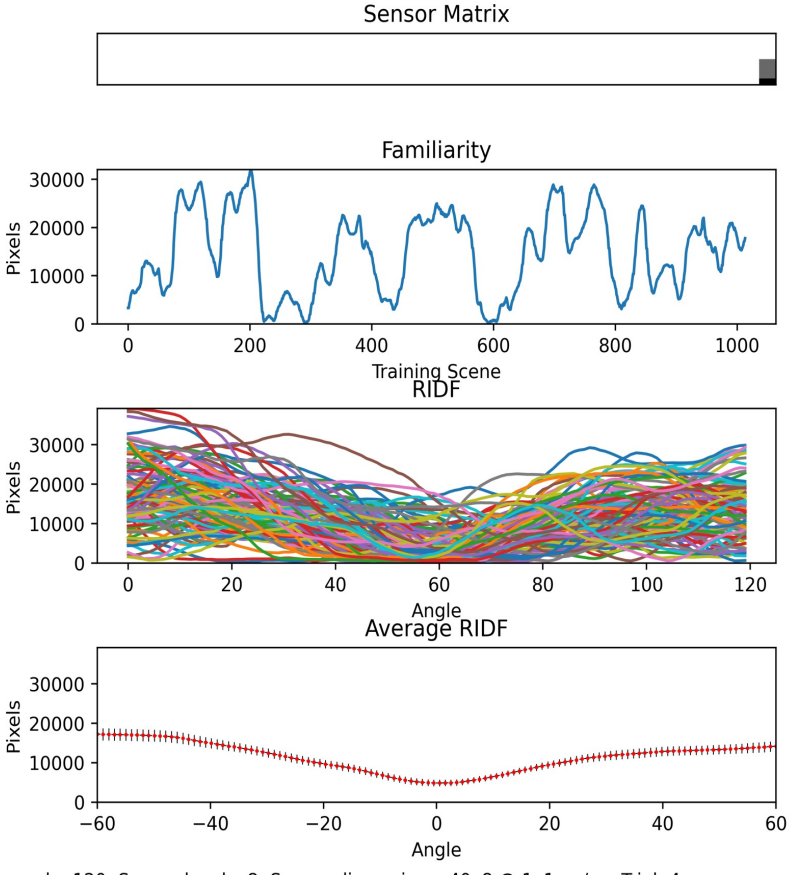


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 7498.31; RMSD/dist: 18.746; TD: 9121; p90: 40; p50: 22; complete: 0

0%

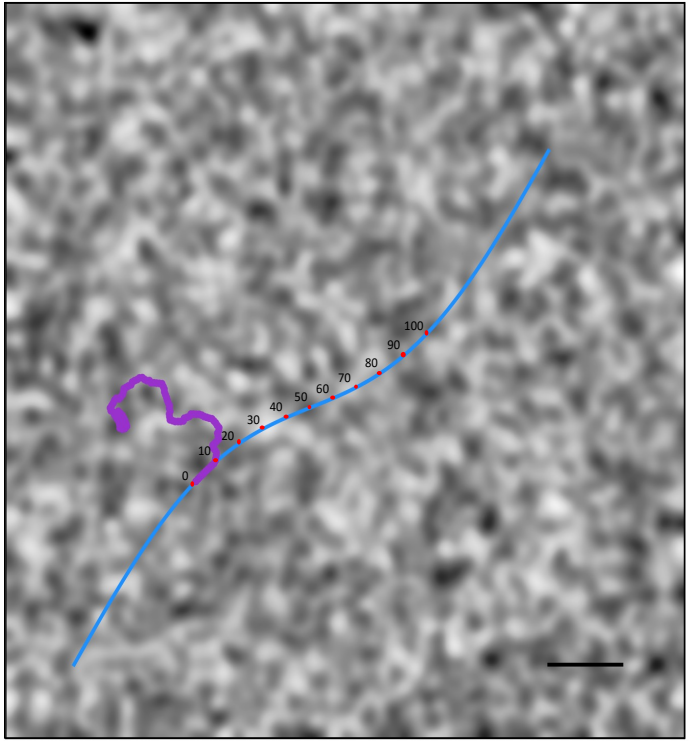


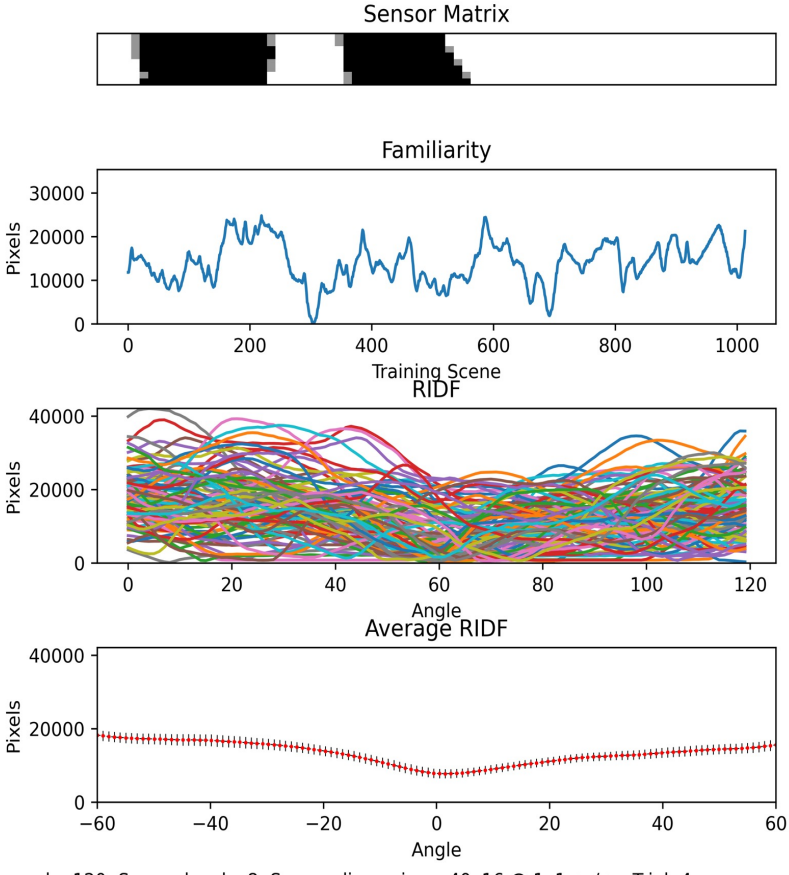


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3734.39; RMSD/dist: 9.336; TD: 9245; p90: 66; p50: 38; complete: 0

10%

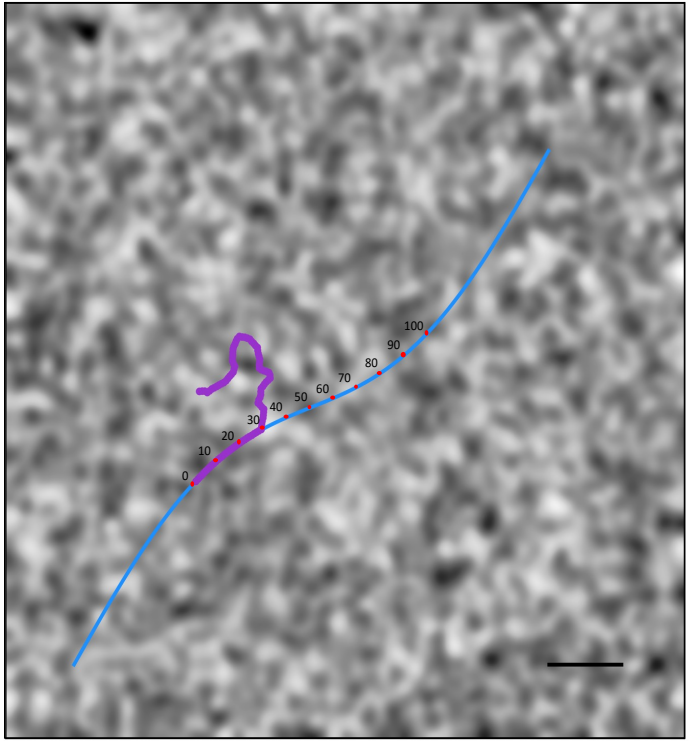


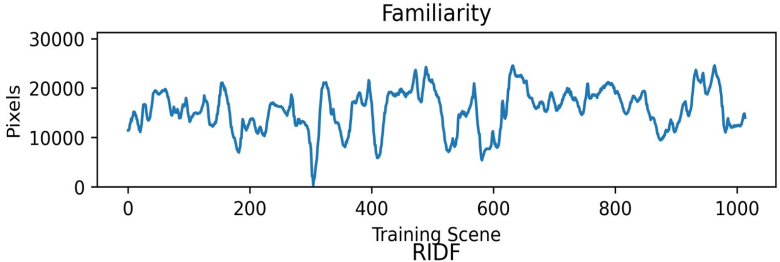


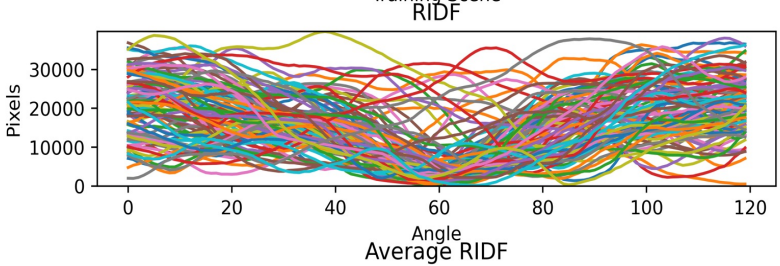
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

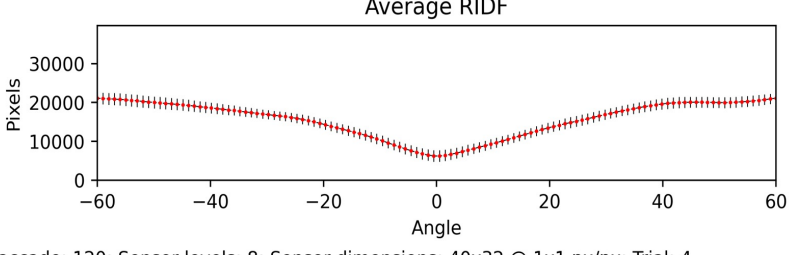
Navigation stats: RMSD error: 9360.65; RMSD/dist: 23.402; TD: 6182; p90: 36; p50: 20; complete: 0

30%



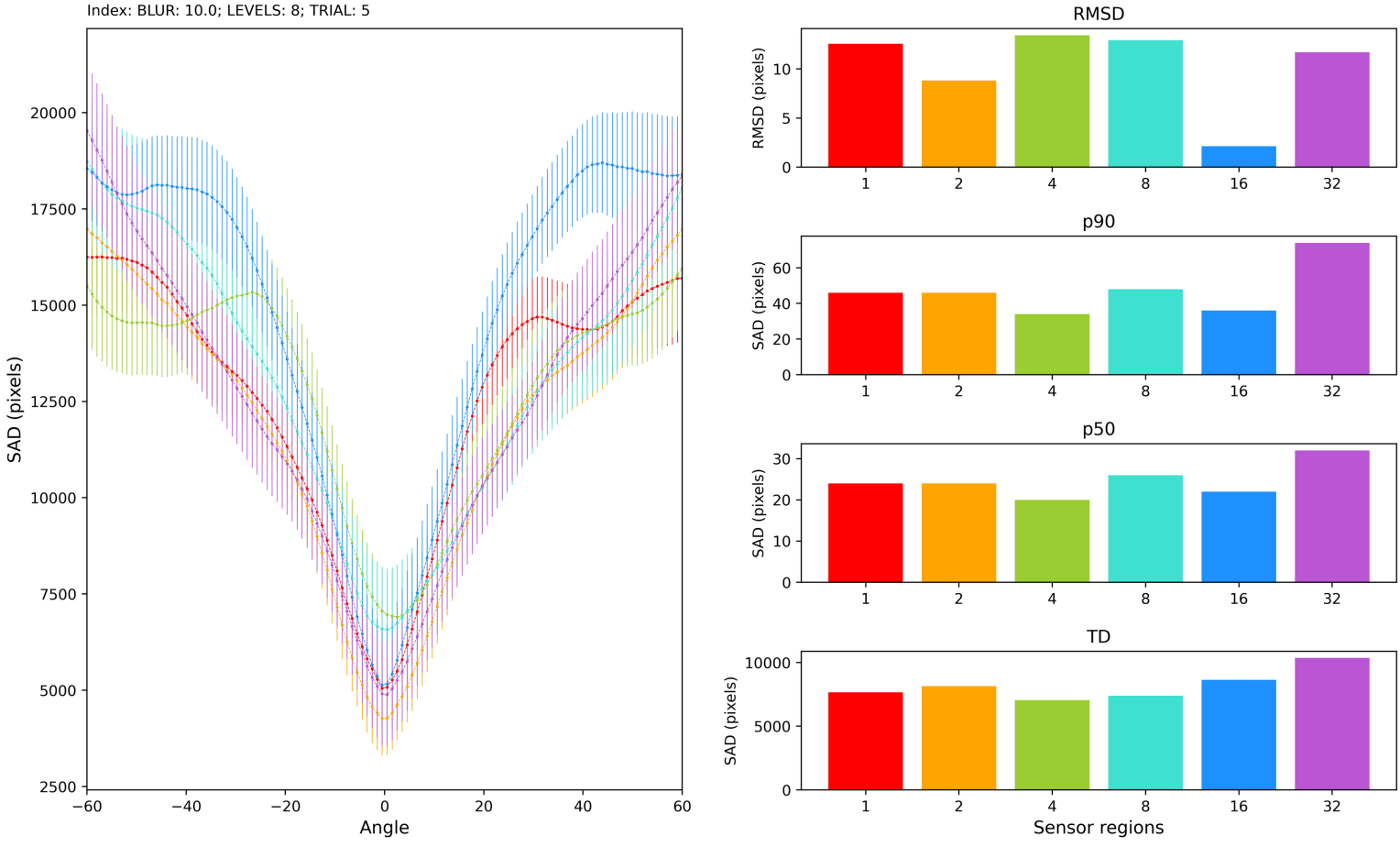




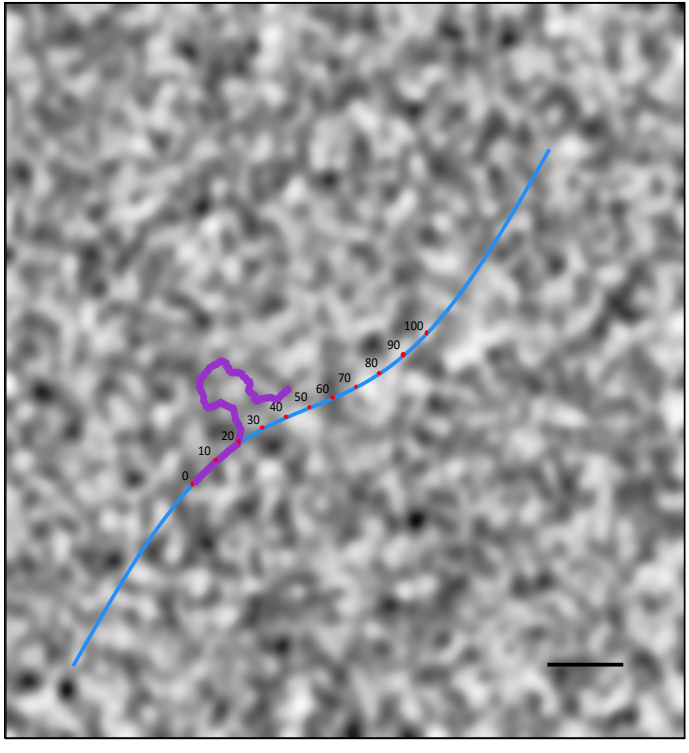


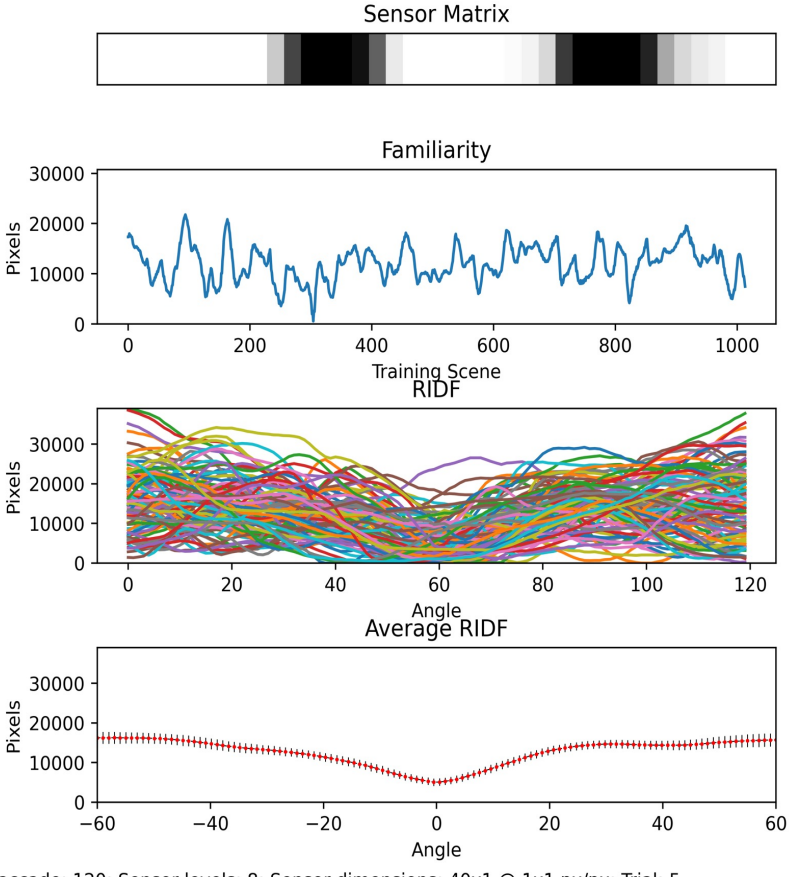
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 5436.72; RMSD/dist: 13.592; TD: 7806; p90: 34; p50: 20; complete: 0


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

20%

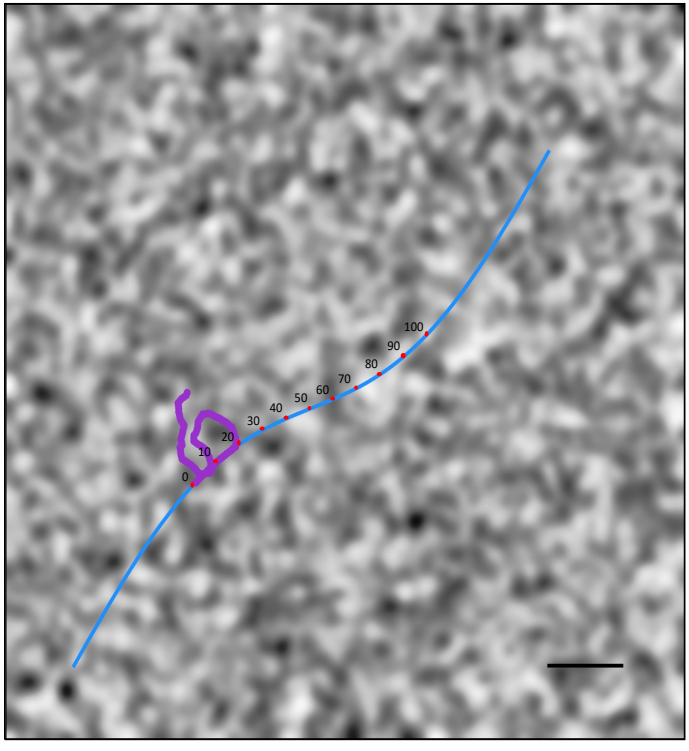


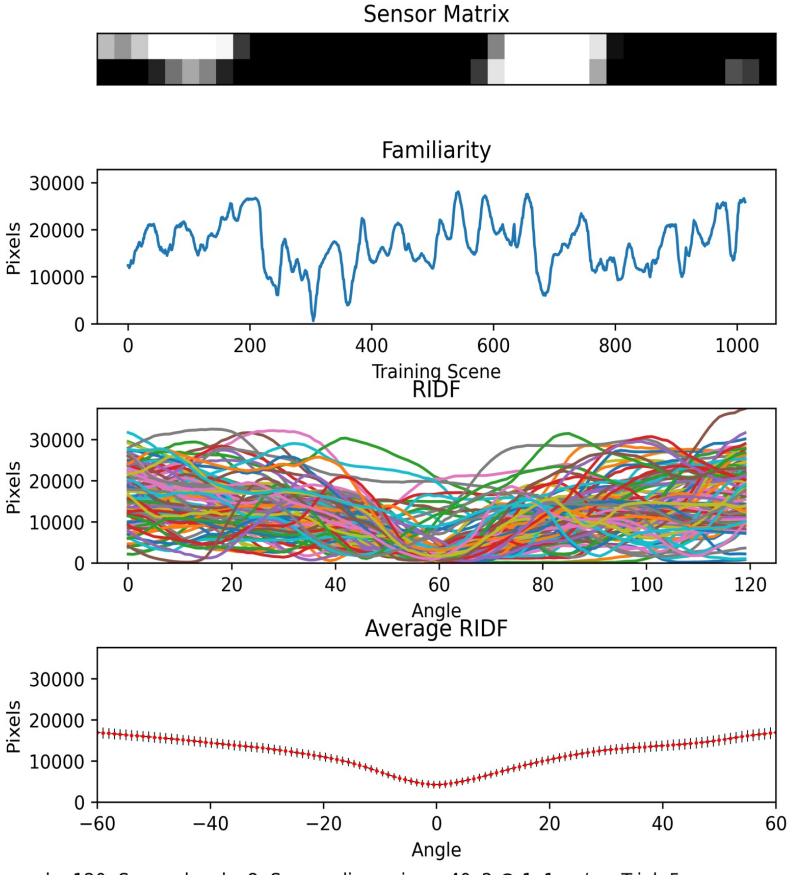


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5031.49; RMSD/dist: 12.579; TD: 7663; p90: 46; p50: 24; complete: 0

20%

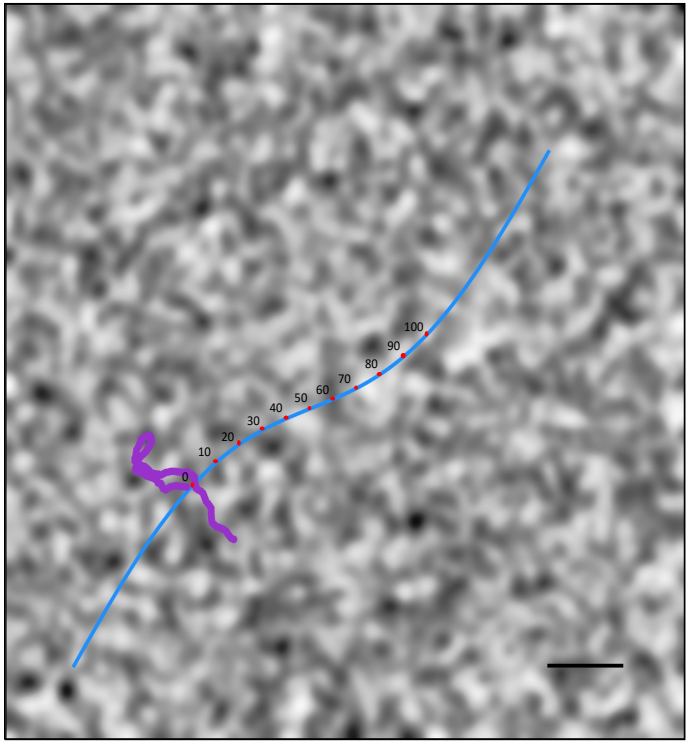


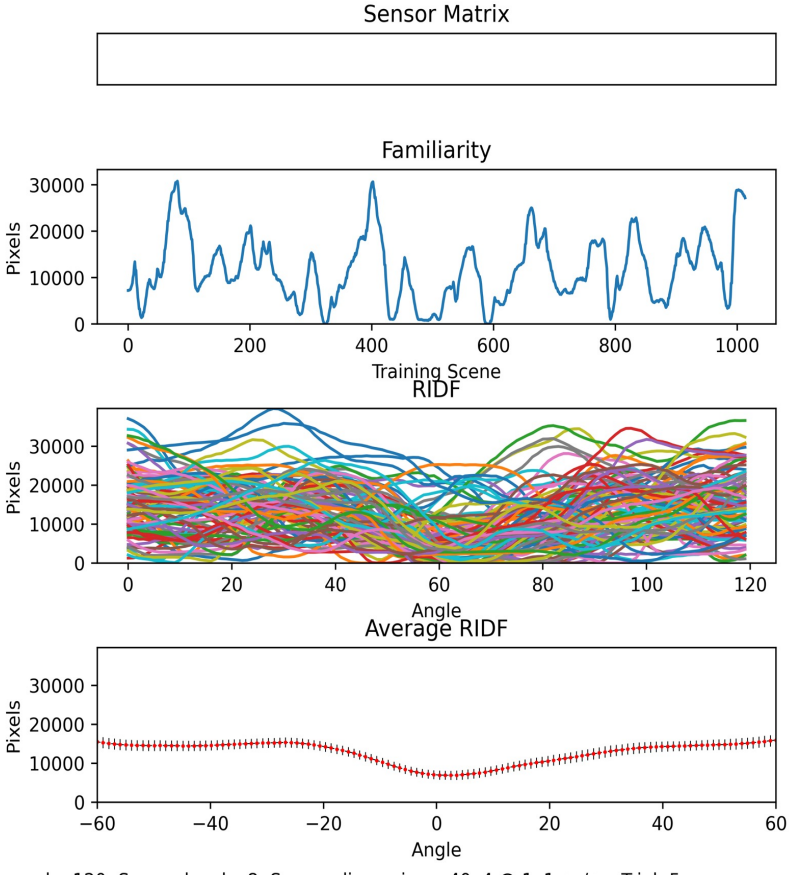


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 3527.65; RMSD/dist: 8.819; TD: 8141; p90: 46; p50: 24; complete: 0

0%

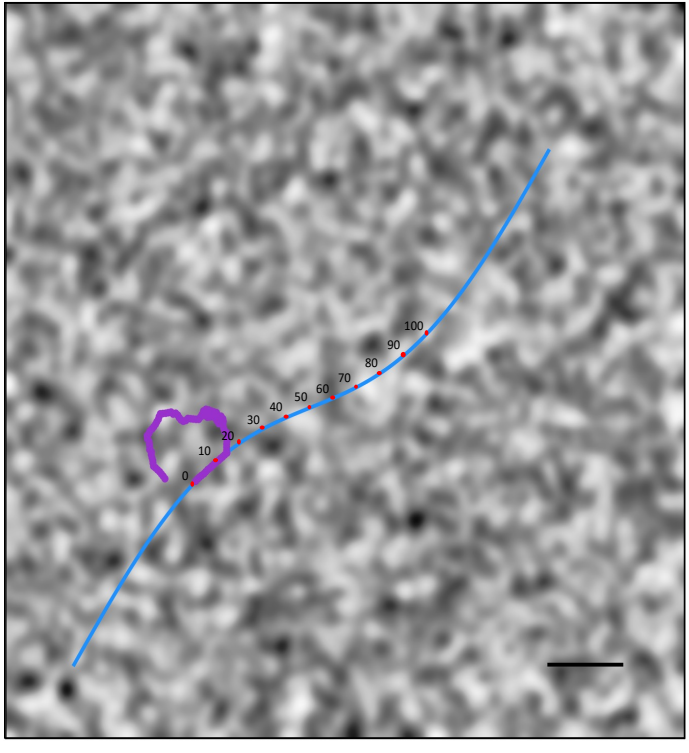


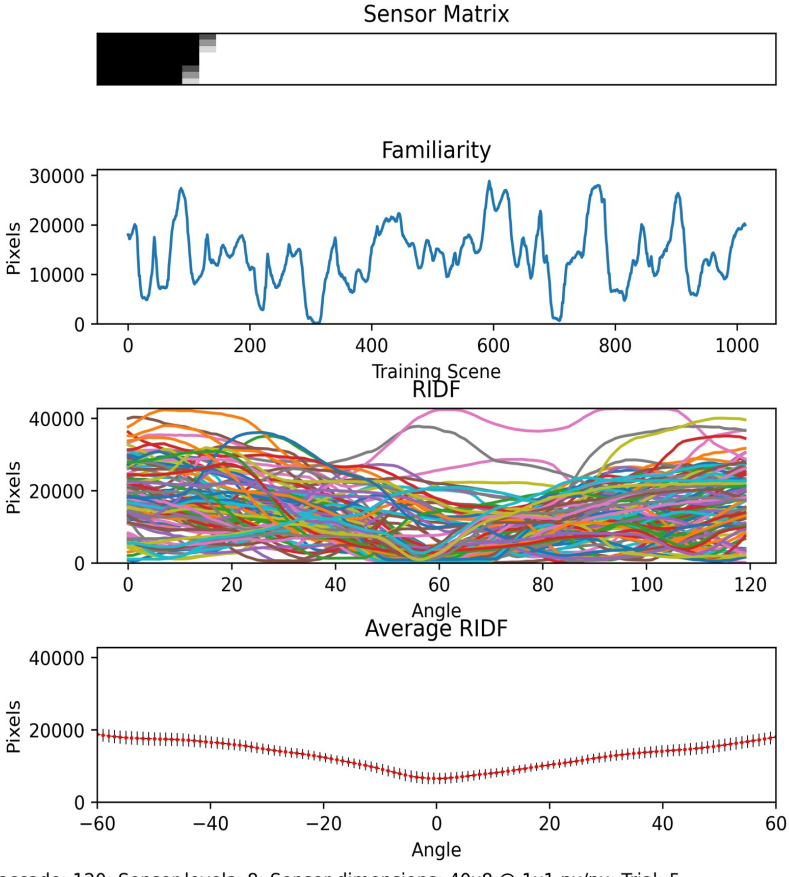


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5376.28; RMSD/dist: 13.441; TD: 7052; p90: 34; p50: 20; complete: 0

10%

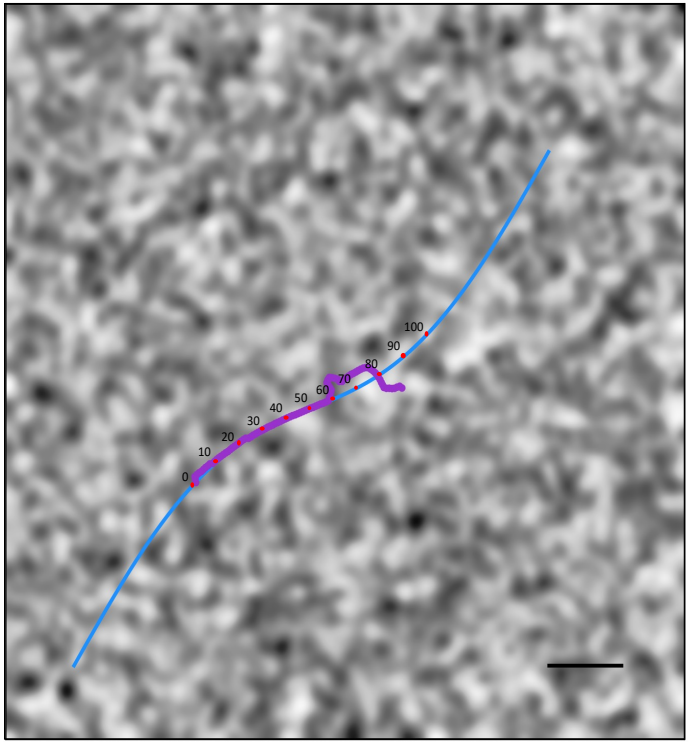


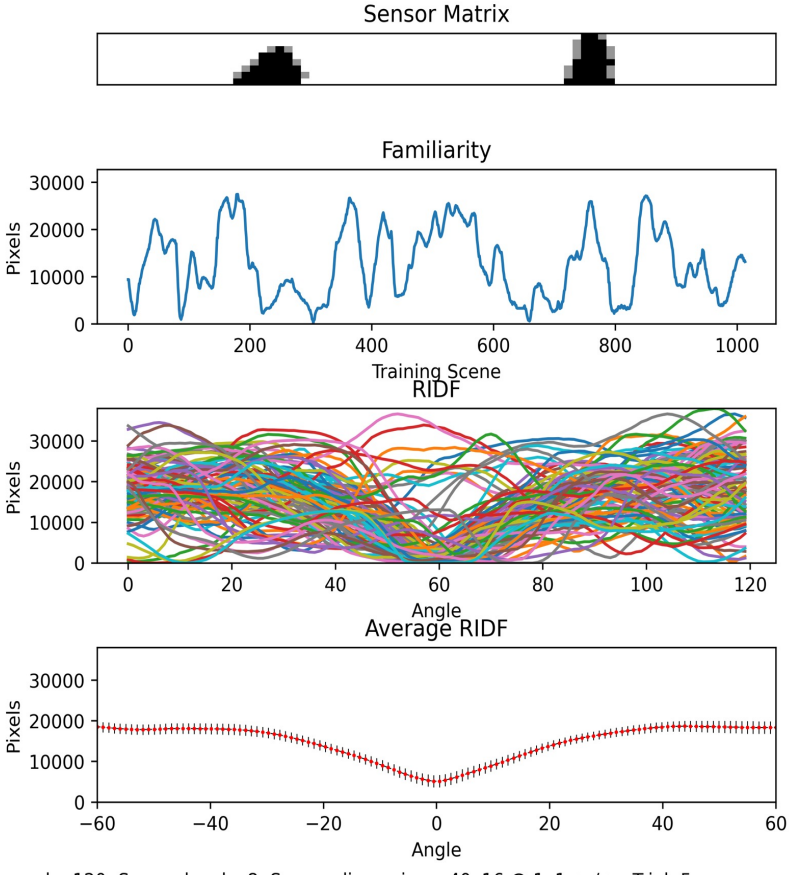


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5178.51; RMSD/dist: 12.946; TD: 7400; p90: 48; p50: 26; complete: 0

60%

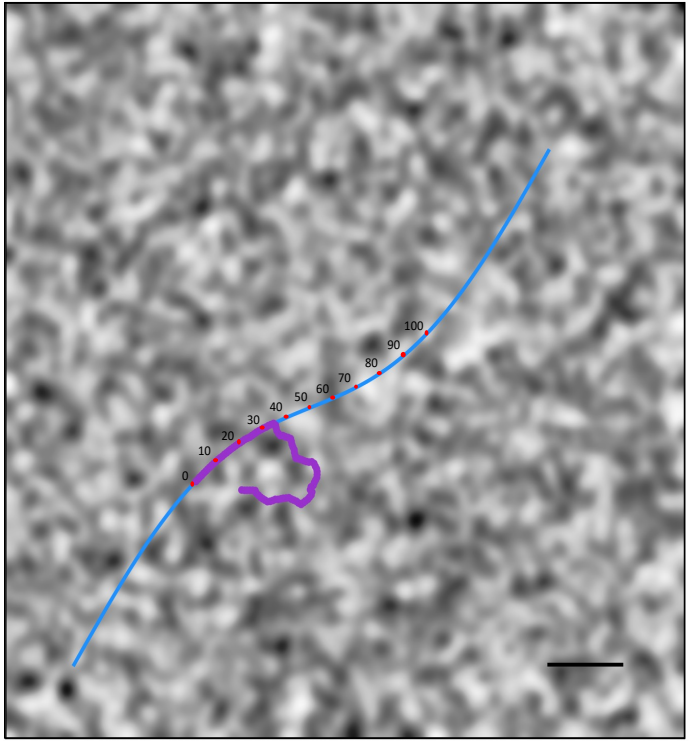


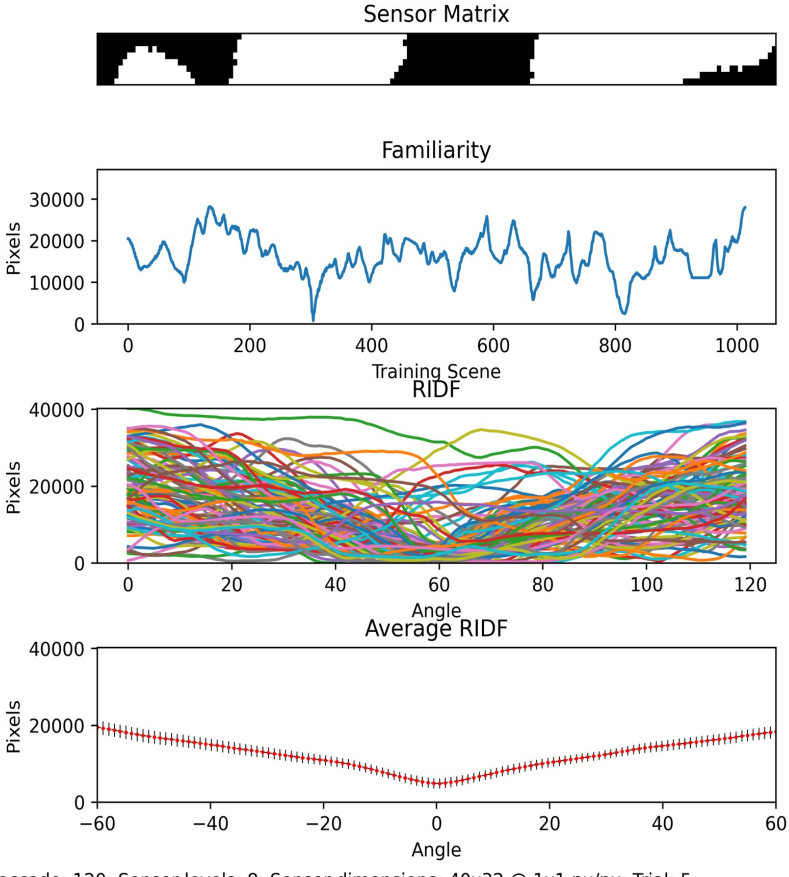


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 853.23; RMSD/dist: 2.133; TD: 8637; p90: 36; p50: 22; complete: 0

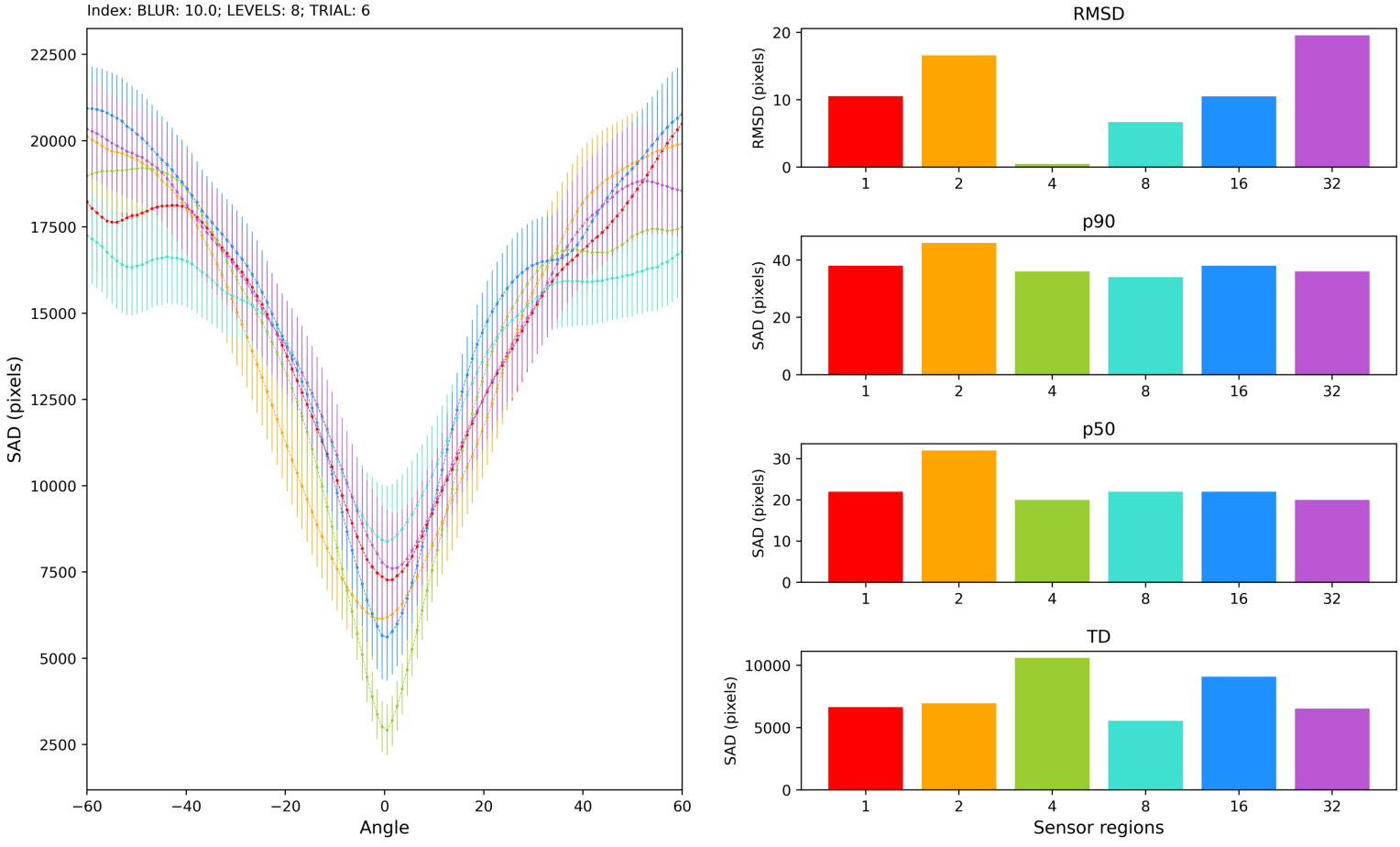
30%



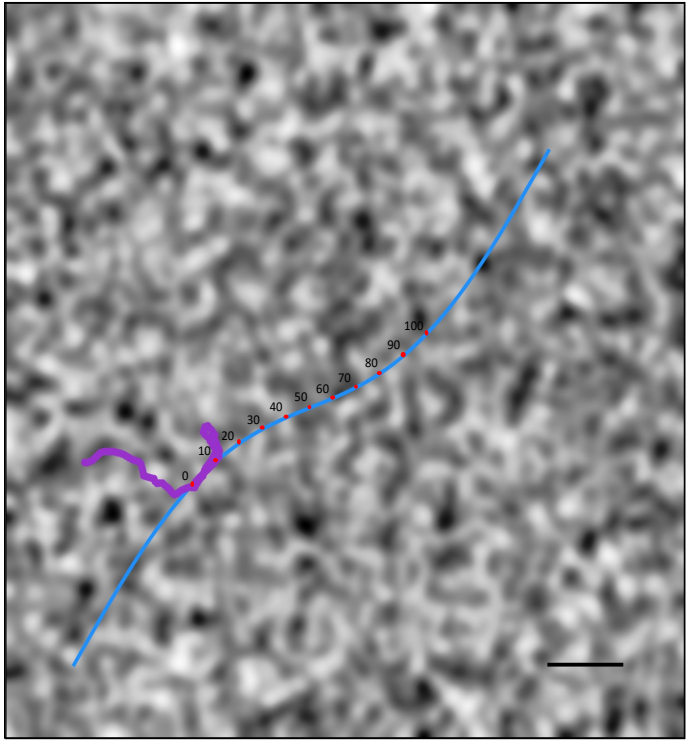


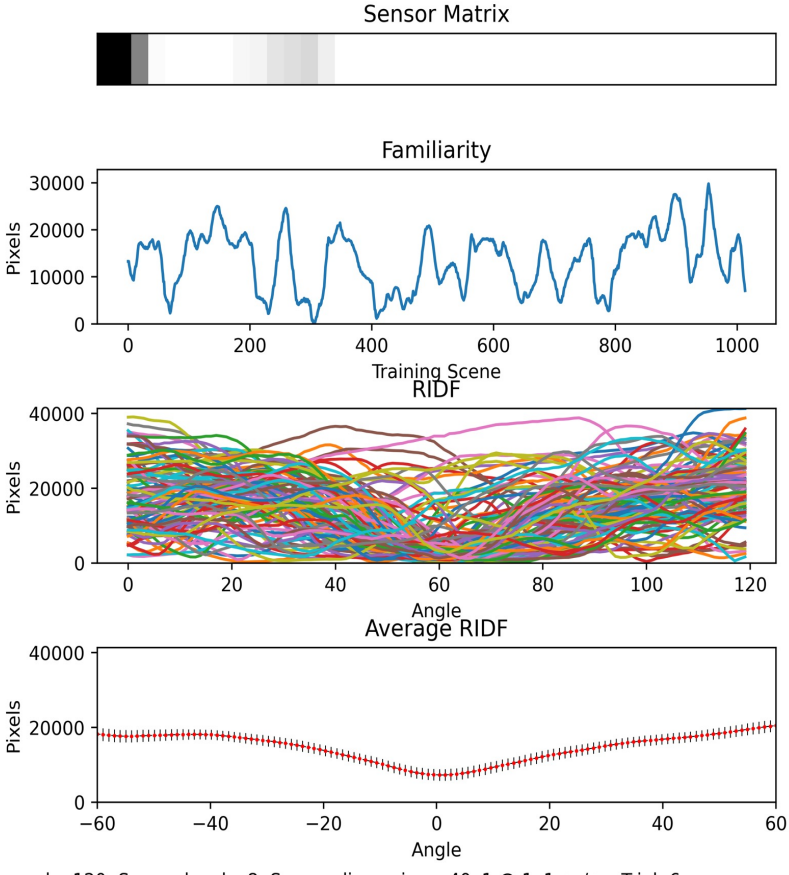
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 4683.75; RMSD/dist: 11.709; TD: 10362; p90: 74; p50: 32; complete: 0


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

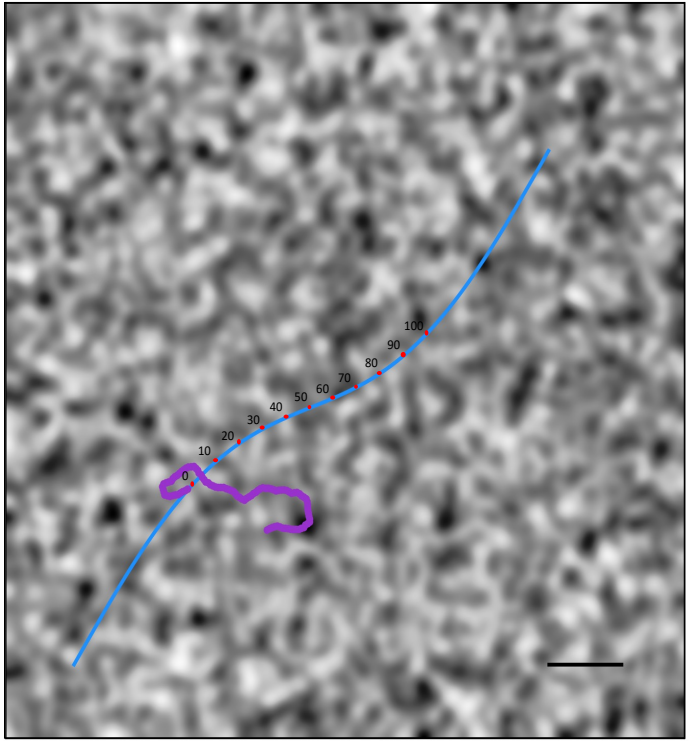


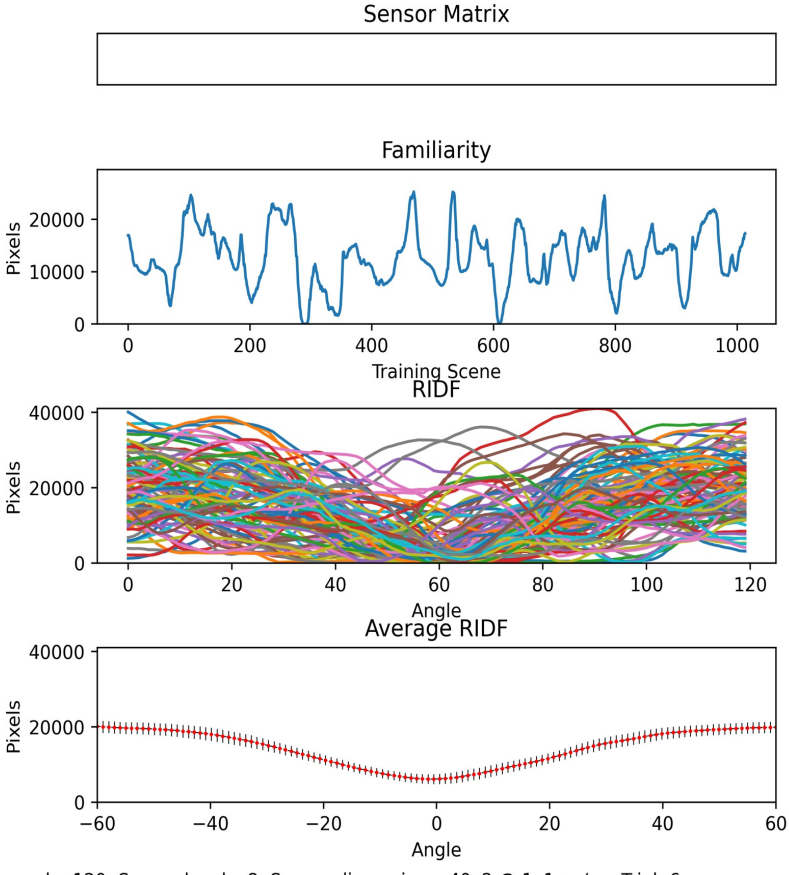


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4208.93; RMSD/dist: 10.522; TD: 6632; p90: 38; p50: 22; complete: 0

0%

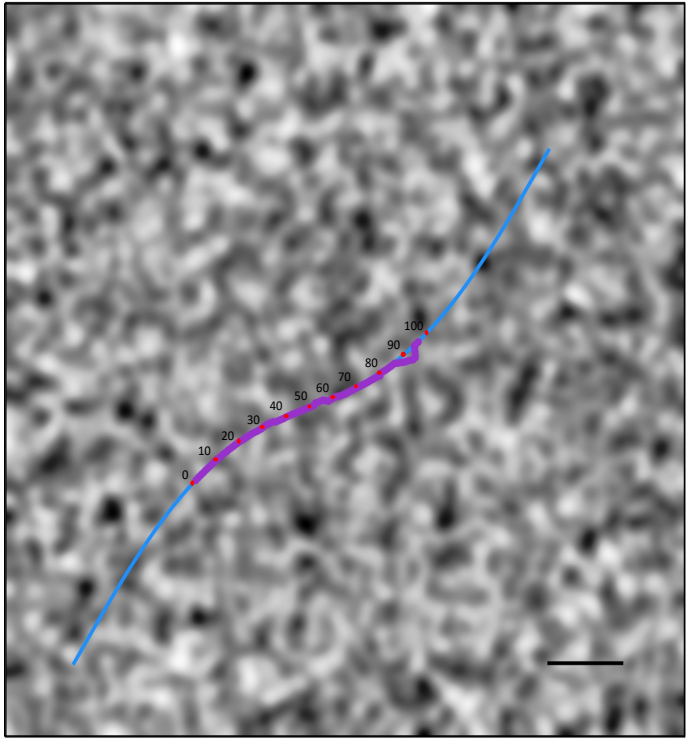


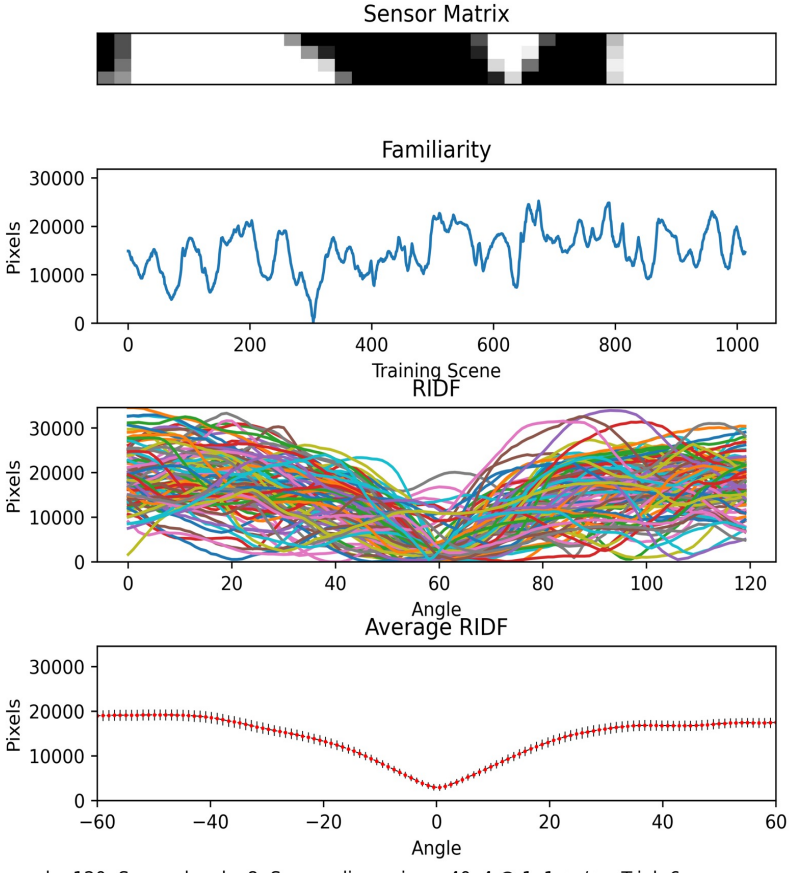


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 6635.72; RMSD/dist: 16.589; TD: 6937; p90: 46; p50: 32; complete: 0

70%

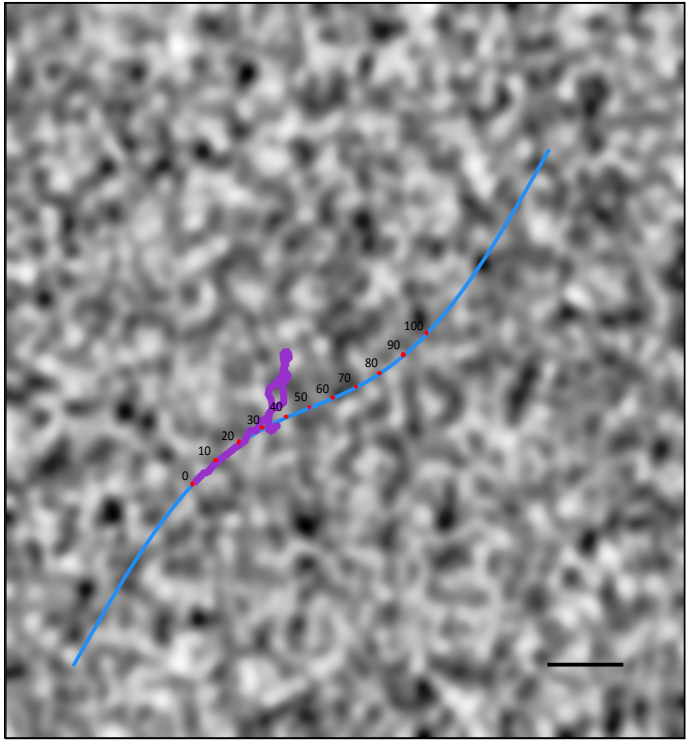


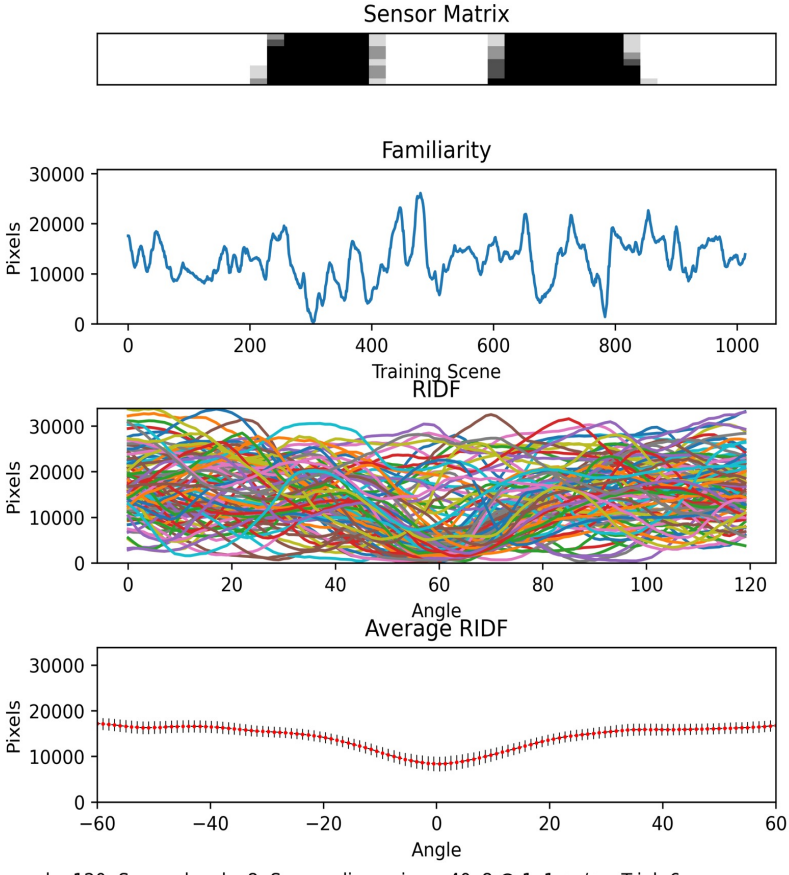


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 181.72; RMSD/dist: 0.454; TD: 10580; p90: 36; p50: 20; complete: 0

20%

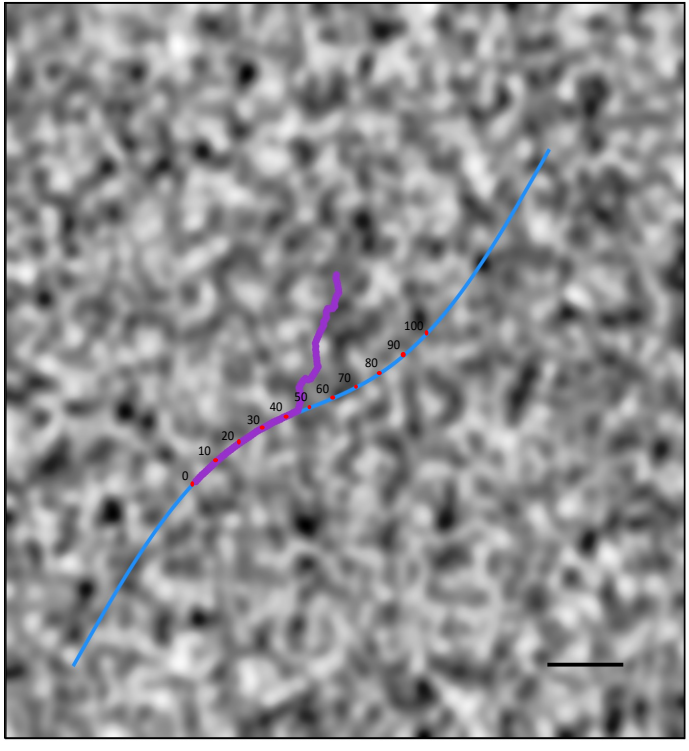


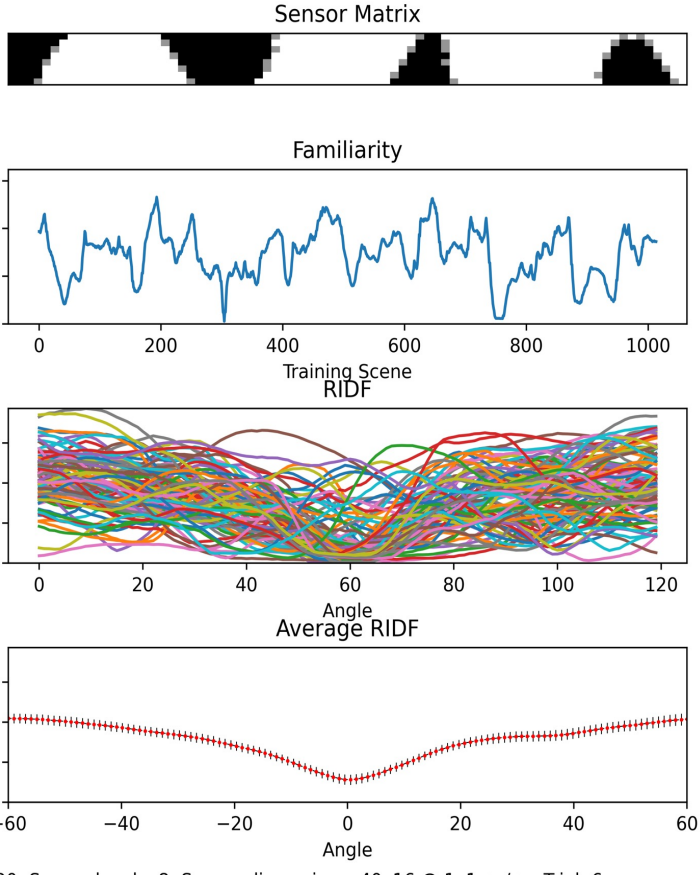


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2672.34; RMSD/dist: 6.681; TD: 5532; p90: 34; p50: 22; complete: 0

40%

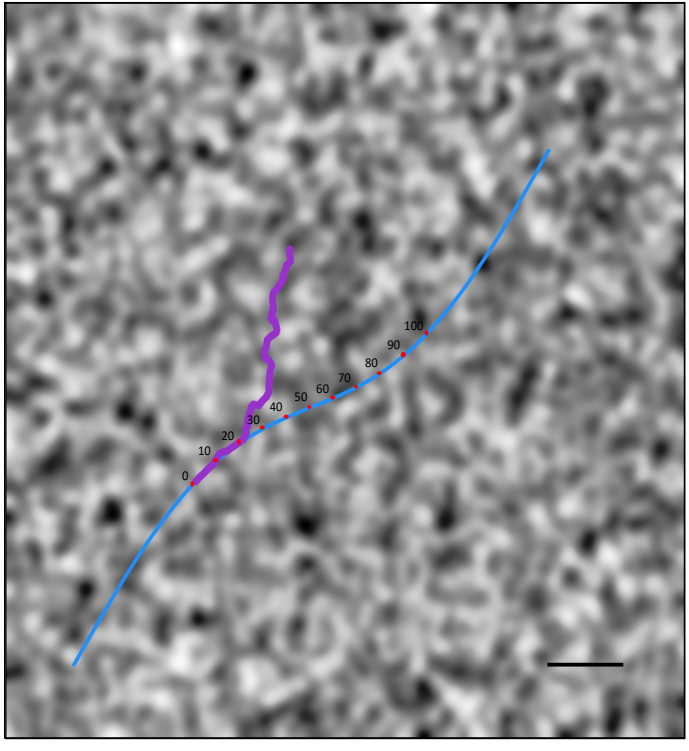


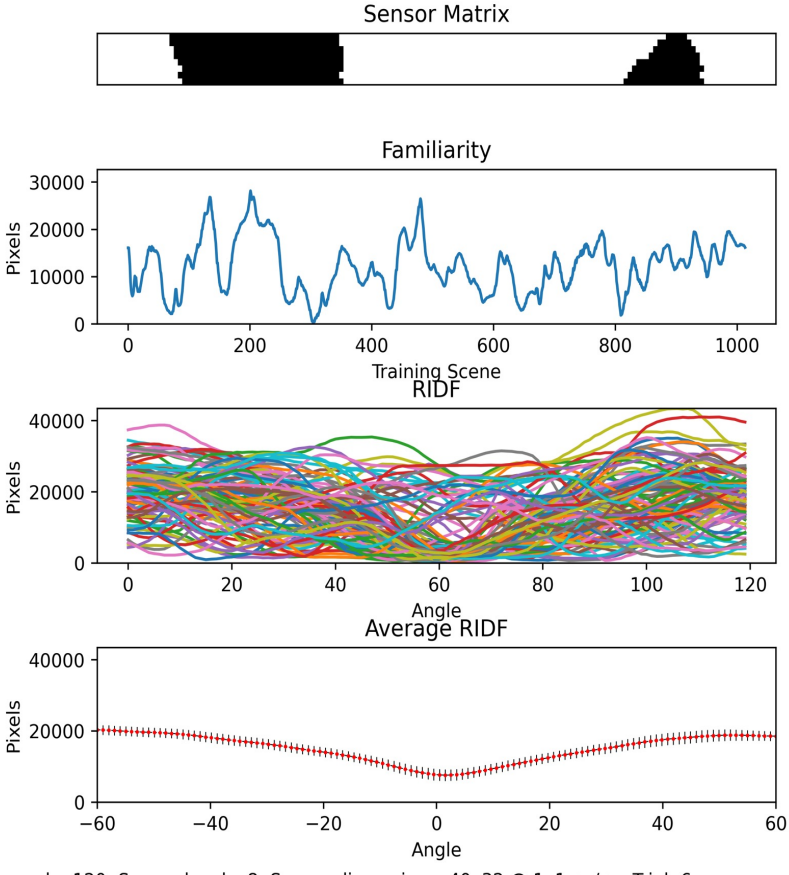


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4204.24; RMSD/dist: 10.511; TD: 9073; p90: 38; p50: 22; complete: 0

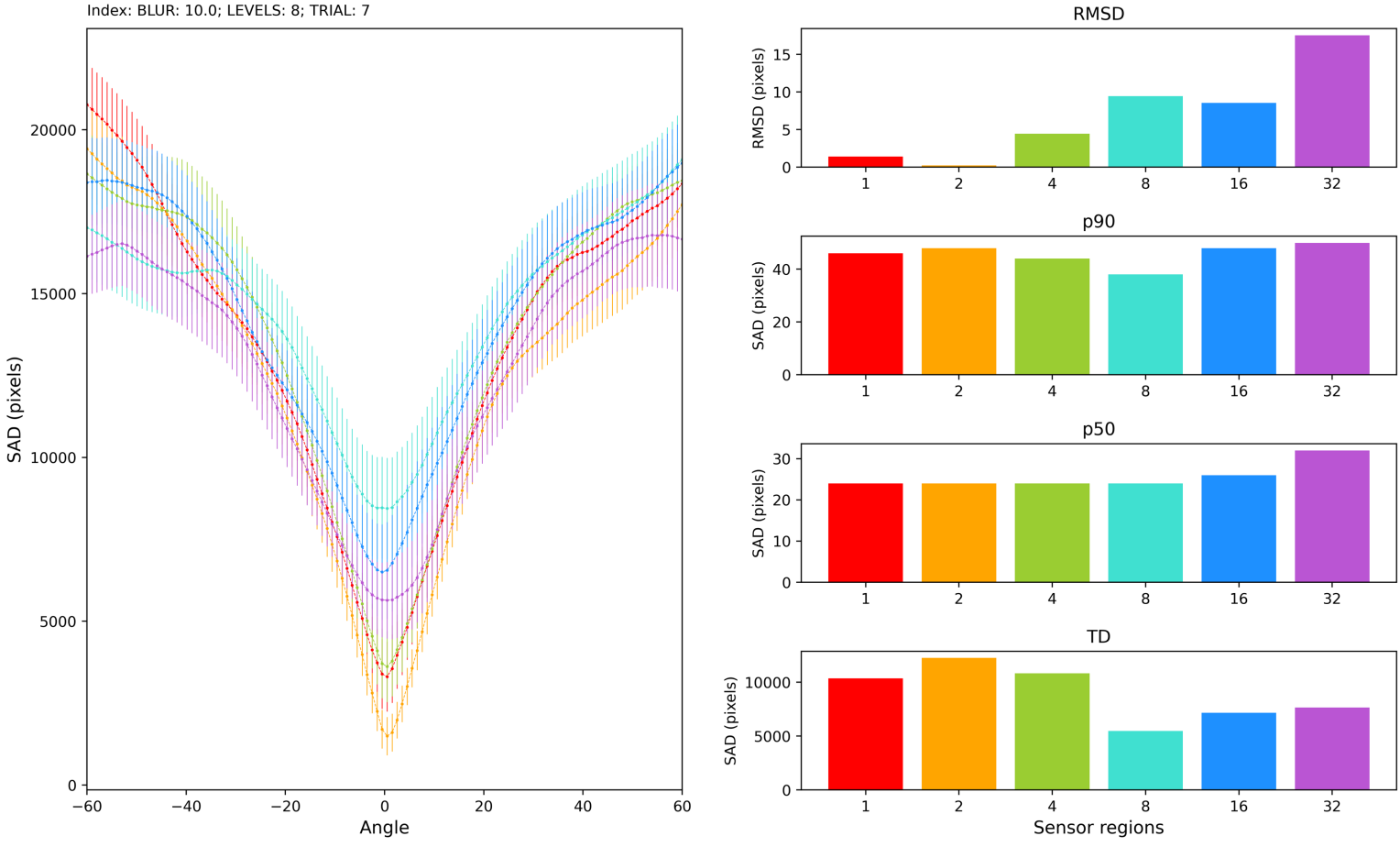
10%



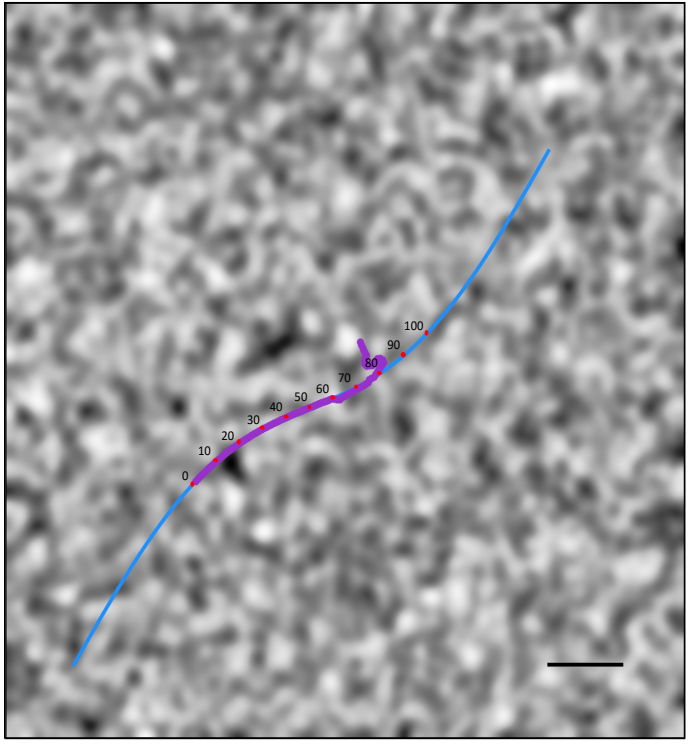


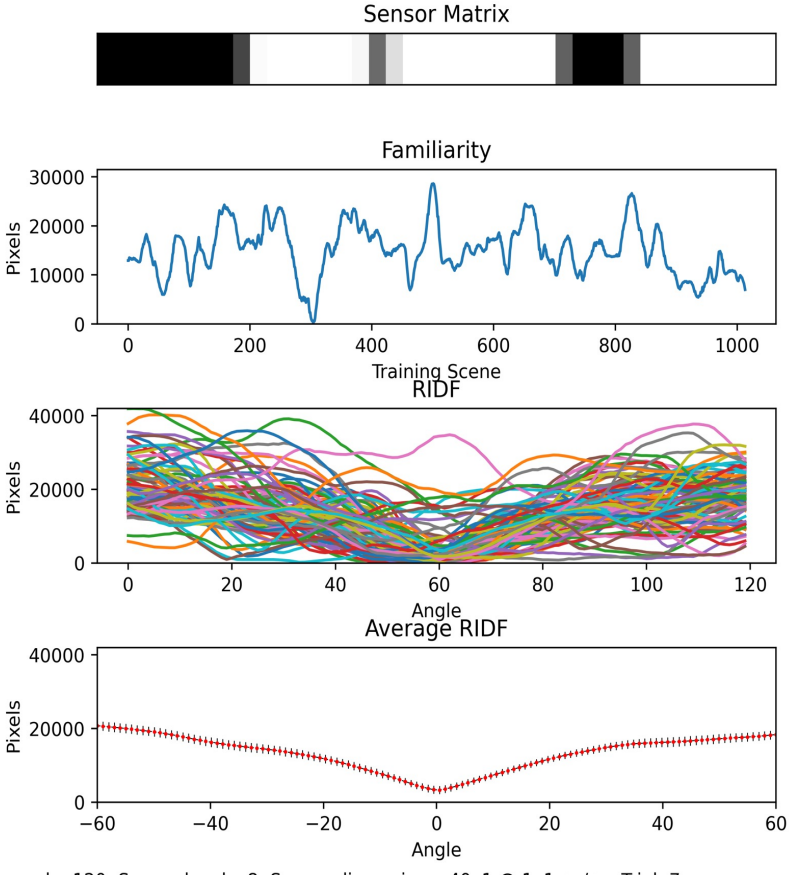
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 7830.00; RMSD/dist: 19.575; TD: 6525; p90: 36; p50: 20; complete: 0


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

60%

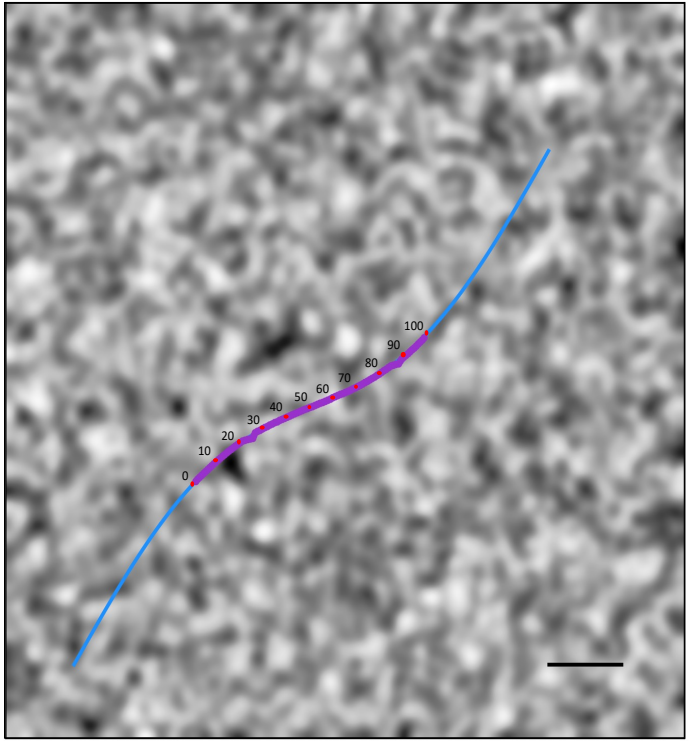


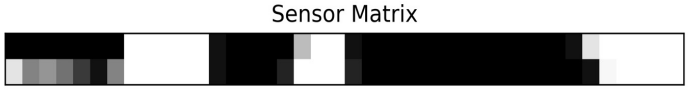


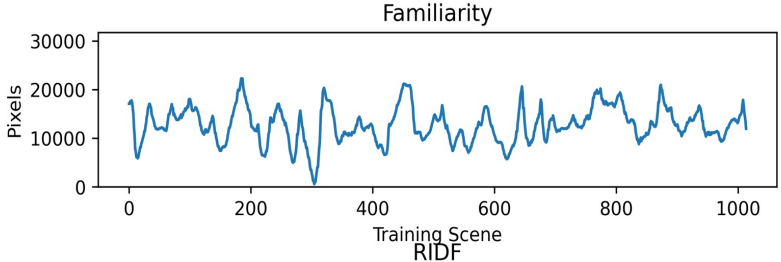
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

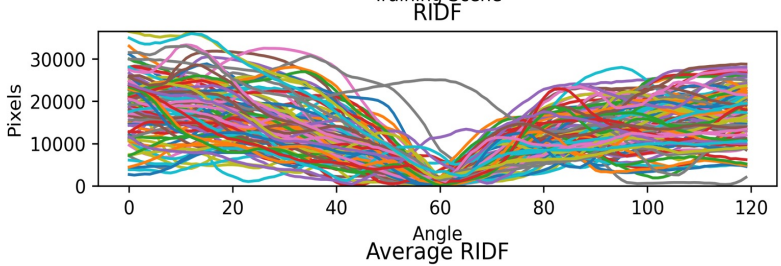
Navigation stats: RMSD error: 561.44; RMSD/dist: 1.404; TD: 10364; p90: 46; p50: 24; complete: 0

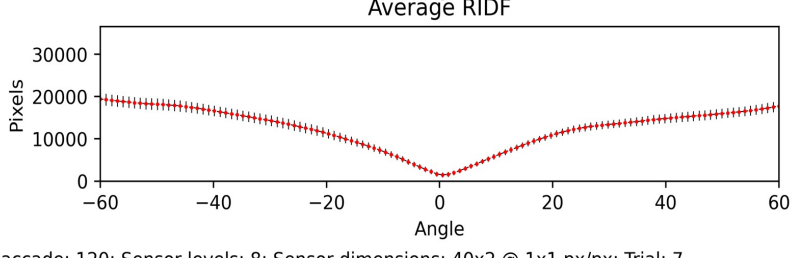
90%







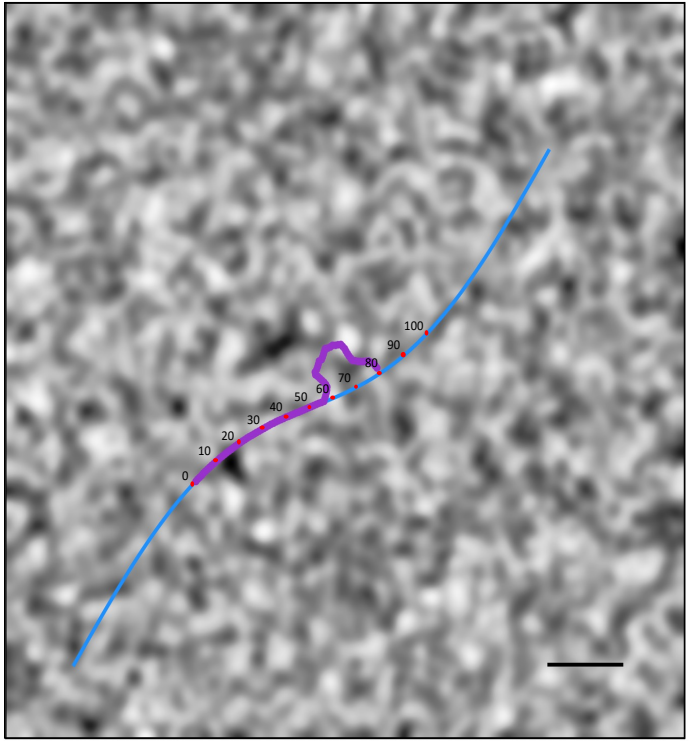


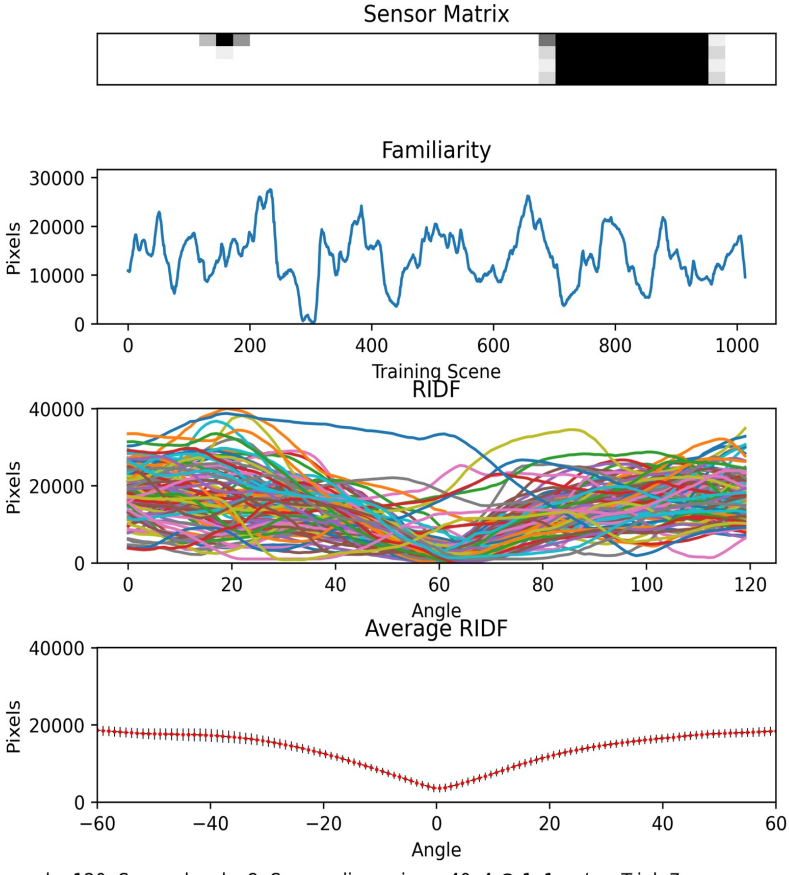


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 81.91; RMSD/dist: 0.205; TD: 12257; p90: 48; p50: 24; complete: 0

50%

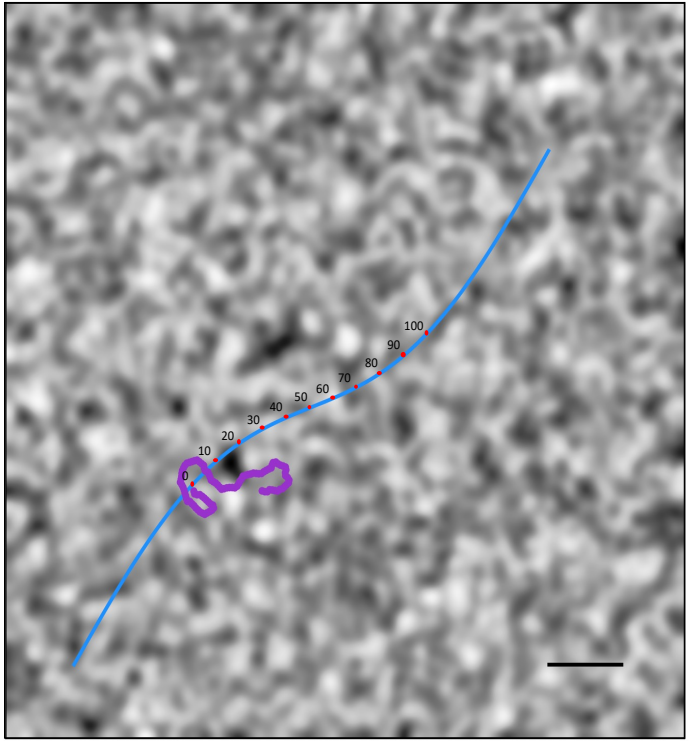


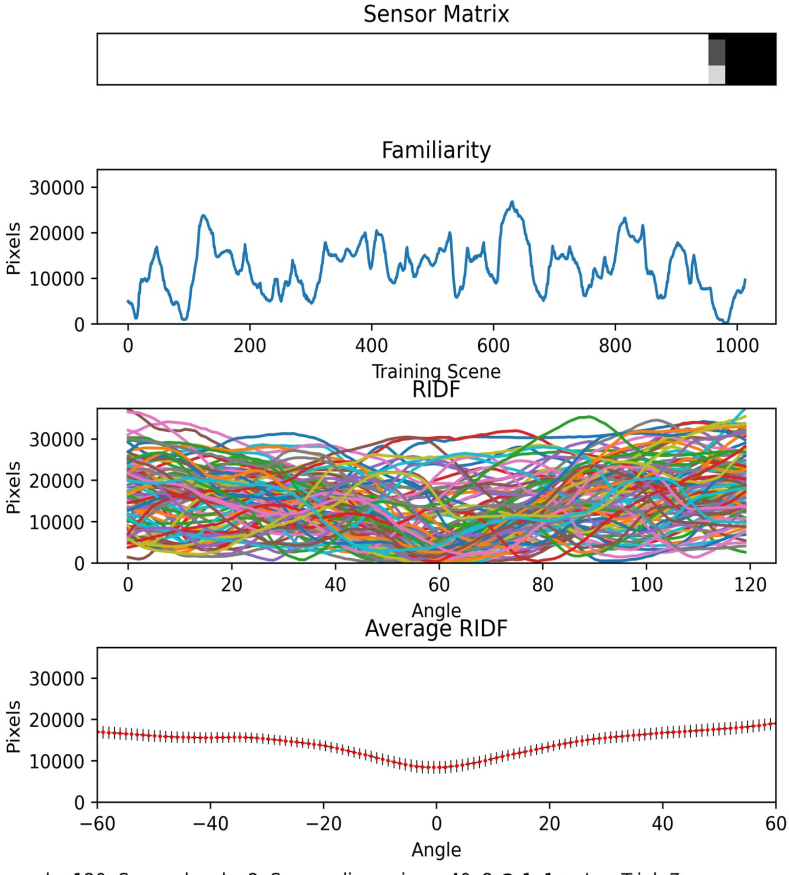


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1771.54; RMSD/dist: 4.429; TD: 10832; p90: 44; p50: 24; complete: 0

0%

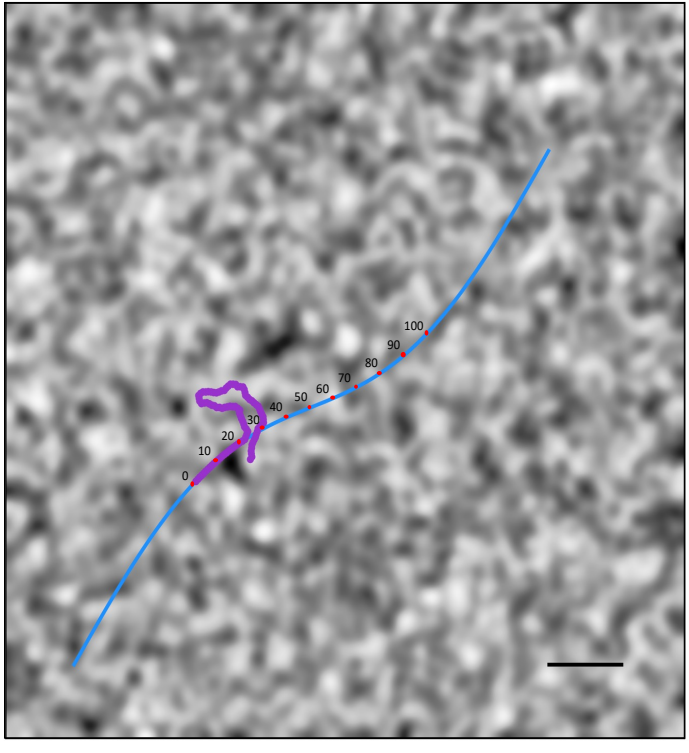


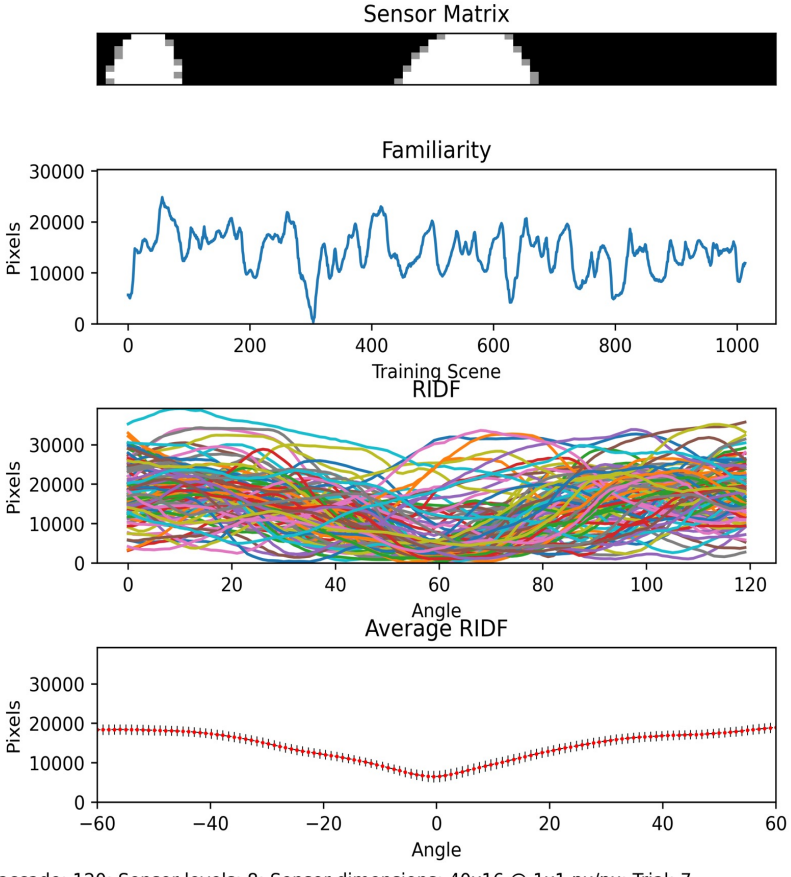


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3775.38; RMSD/dist: 9.438; TD: 5464; p90: 38; p50: 24; complete: 0

20%

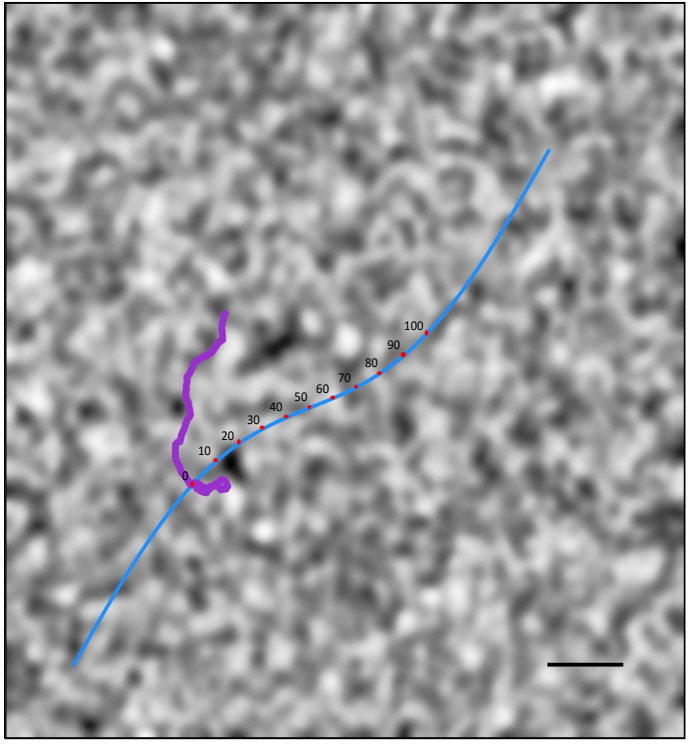


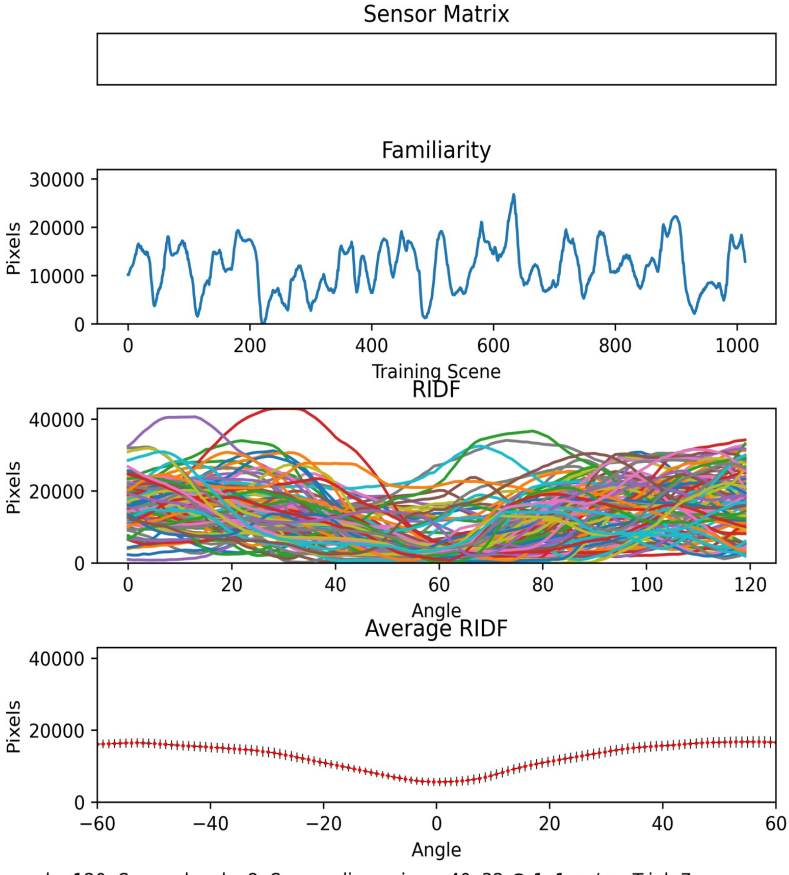


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3413.50; RMSD/dist: 8.534; TD: 7153; p90: 48; p50: 26; complete: 0

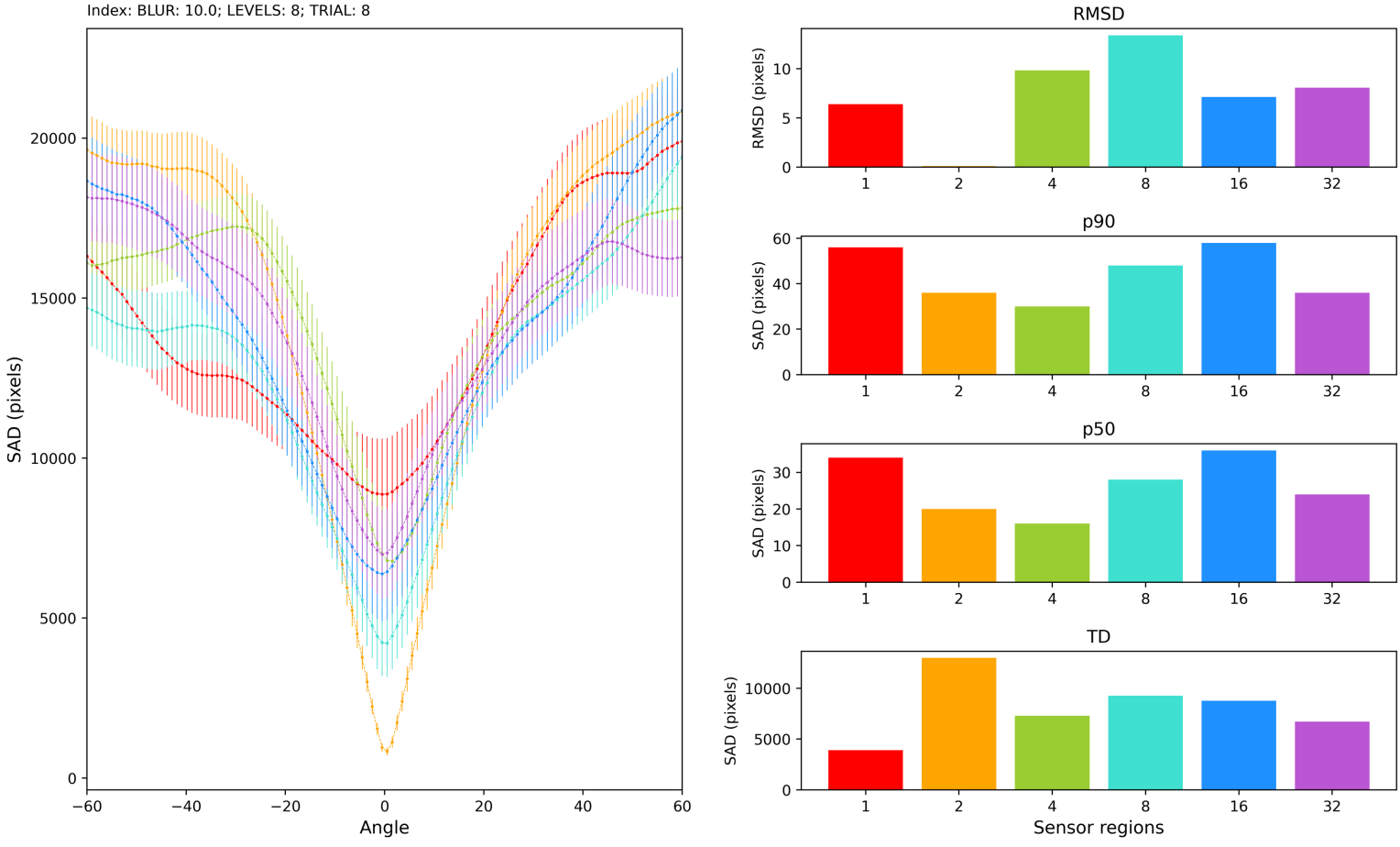
0%



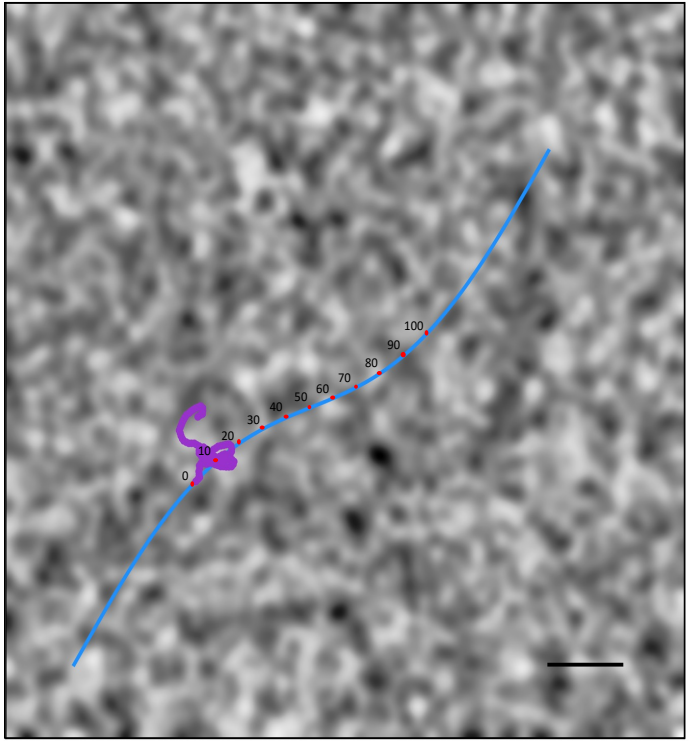


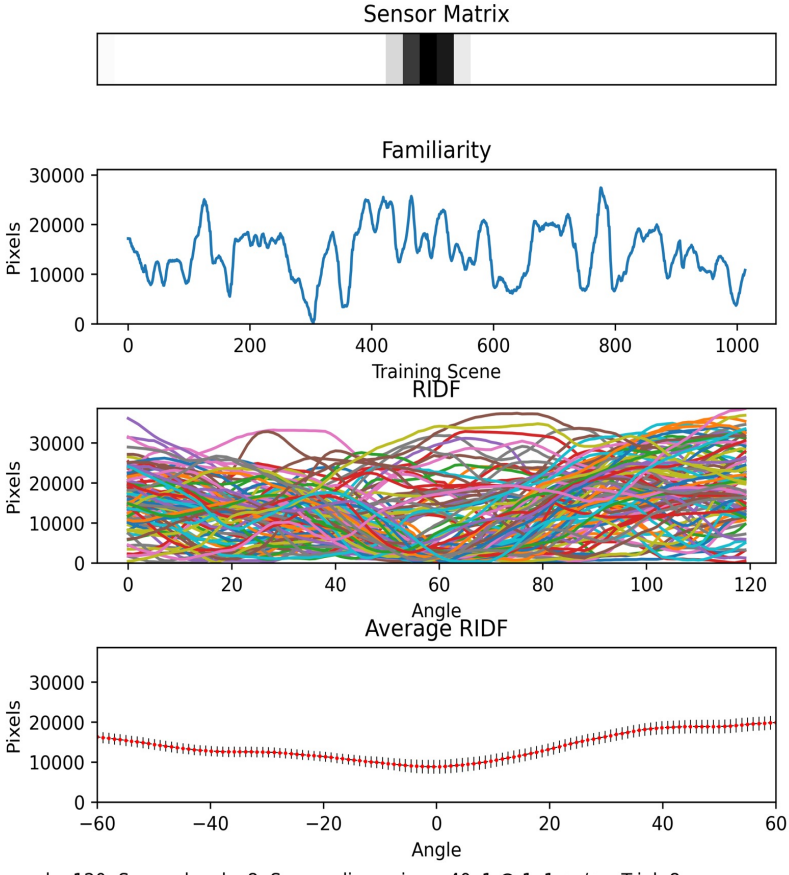
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 7013.86; RMSD/dist: 17.535; TD: 7642; p90: 50; p50: 32; complete: 0


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

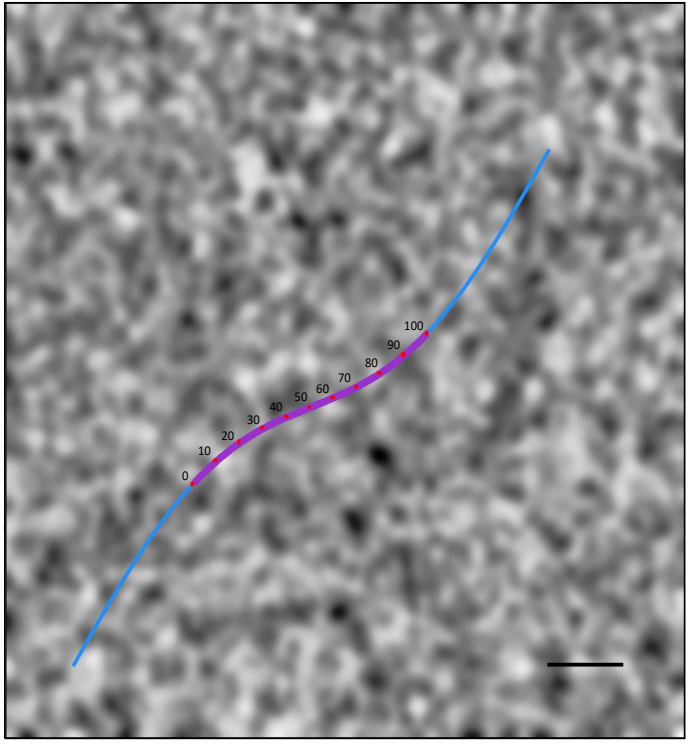


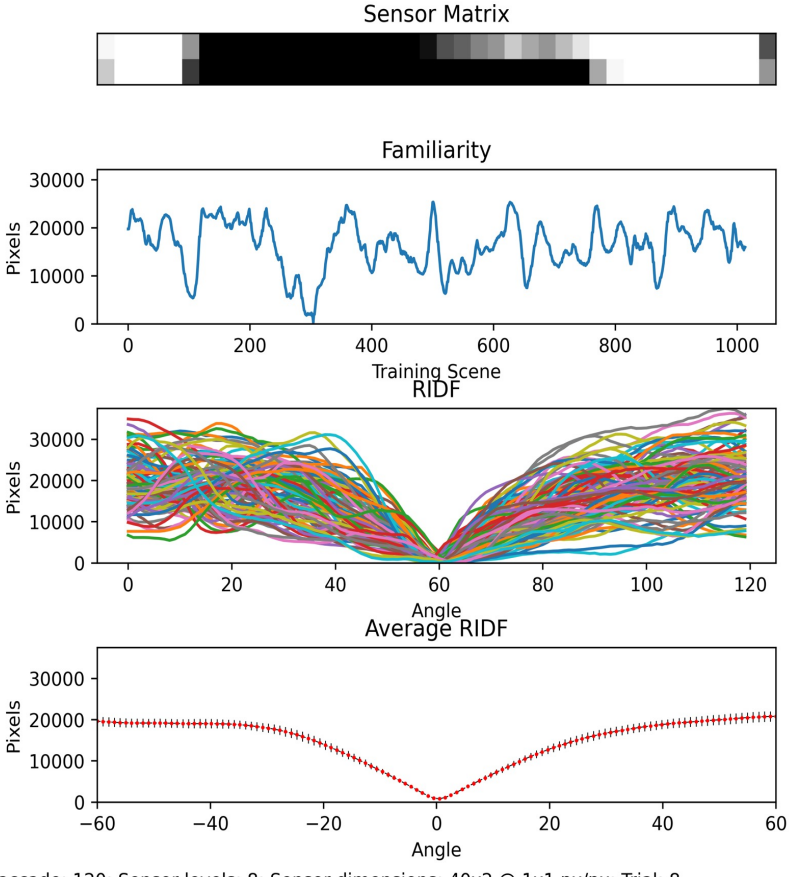


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2560.07; RMSD/dist: 6.400; TD: 3900; p90: 56; p50: 34; complete: 0

100%

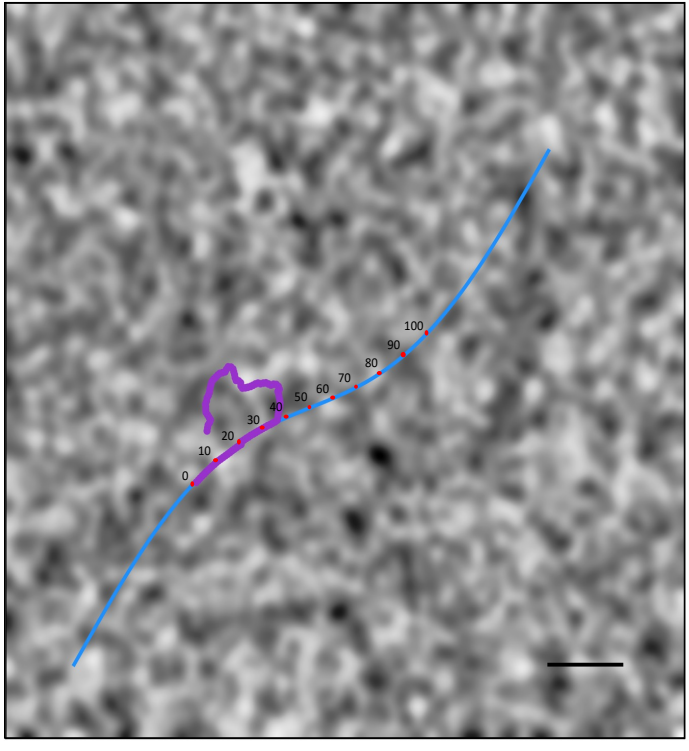


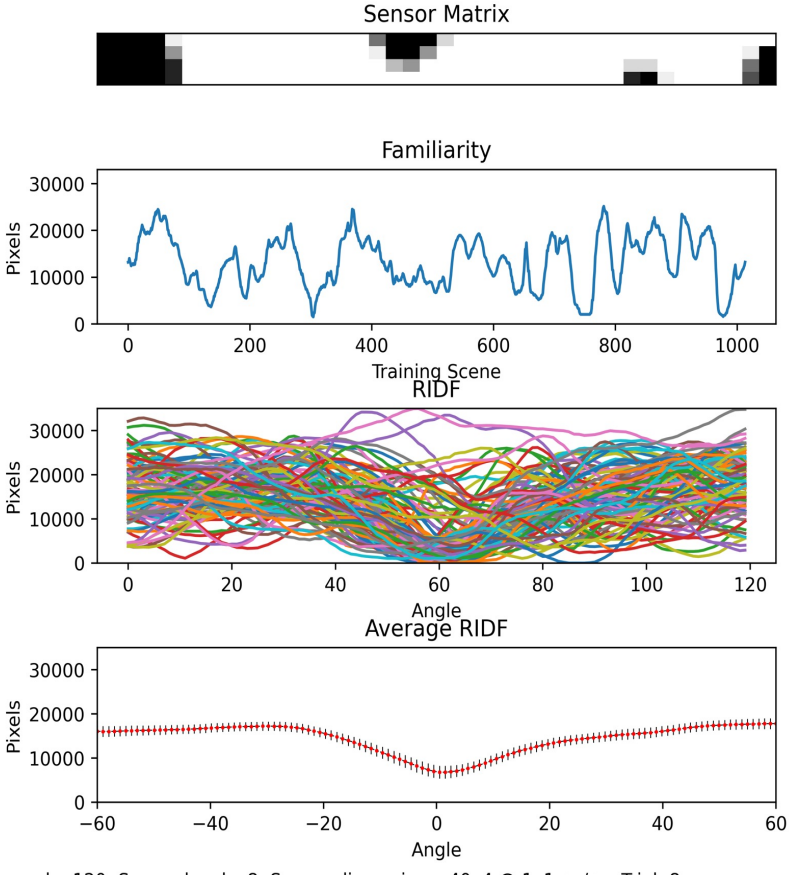


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 37.92; RMSD/dist: 0.095; TD: 12985; p90: 36; p50: 20; complete: 0

30%

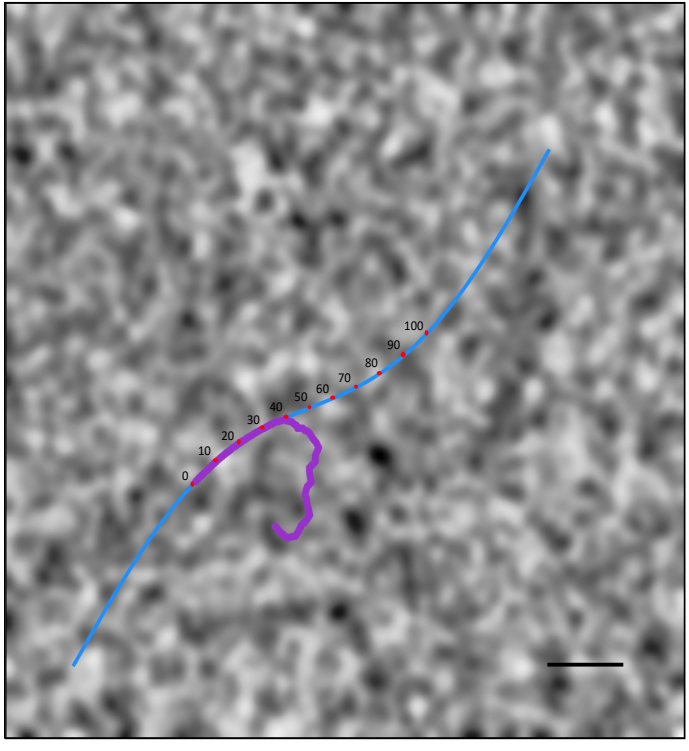


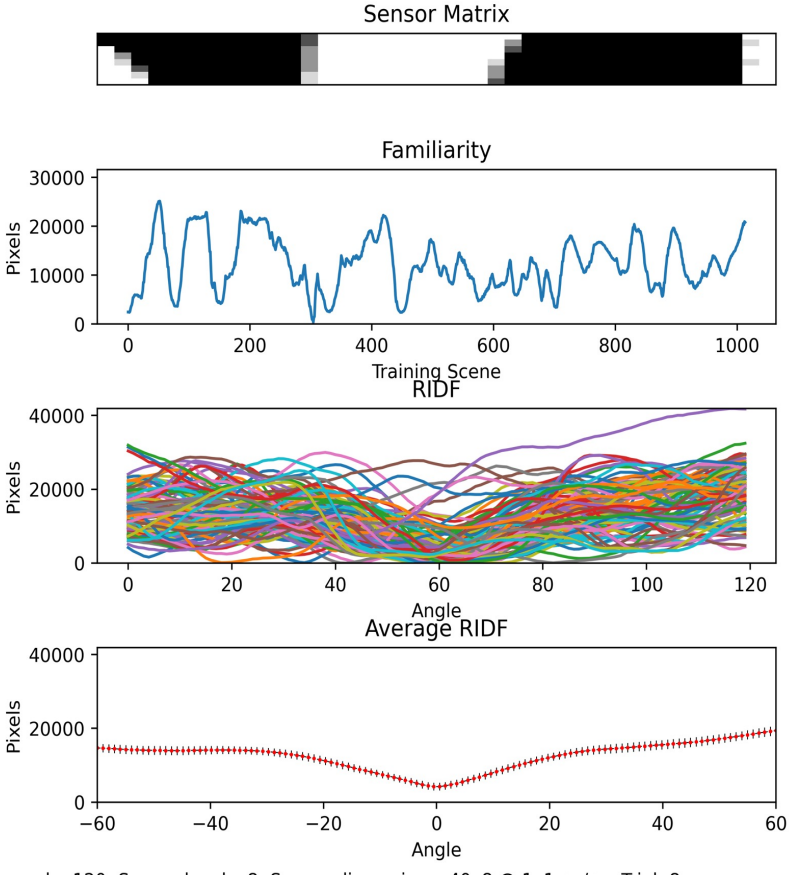


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3931.77; RMSD/dist: 9.829; TD: 7305; p90: 30; p50: 16; complete: 0

40%

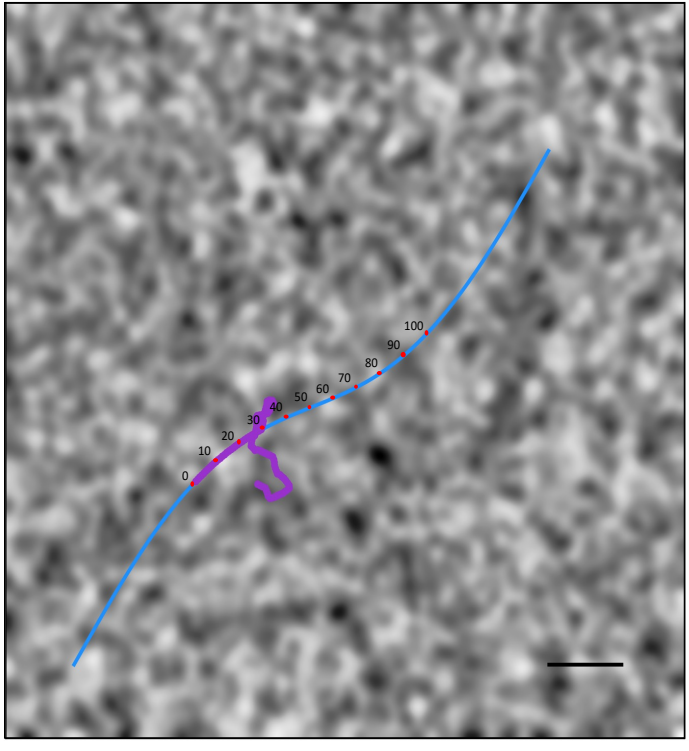


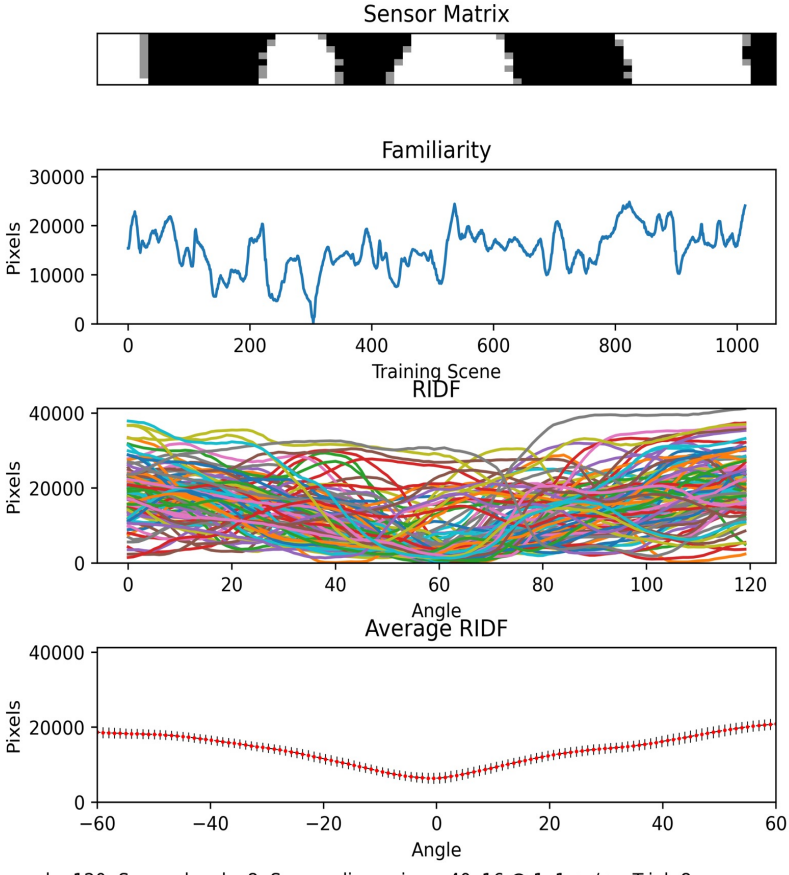


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5359.62; RMSD/dist: 13.399; TD: 9262; p90: 48; p50: 28; complete: 0

30%

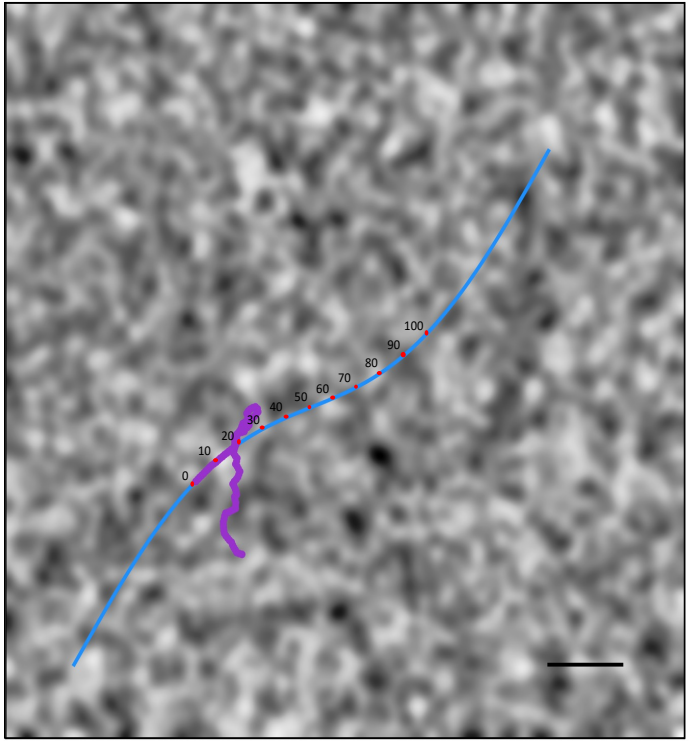


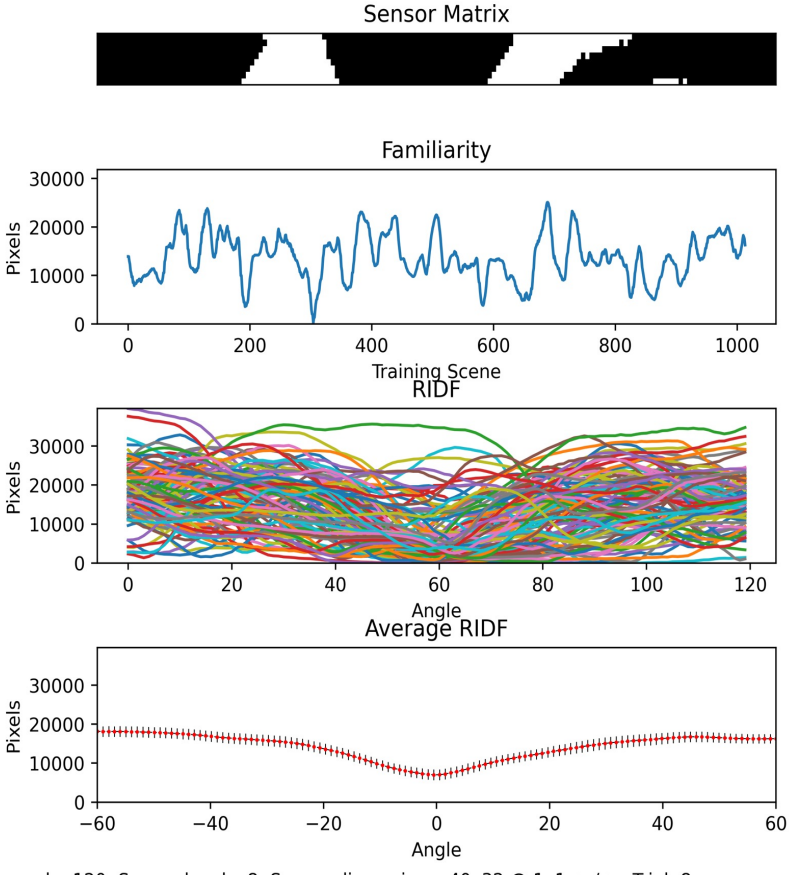


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2844.09; RMSD/dist: 7.110; TD: 8767; p90: 58; p50: 36; complete: 0

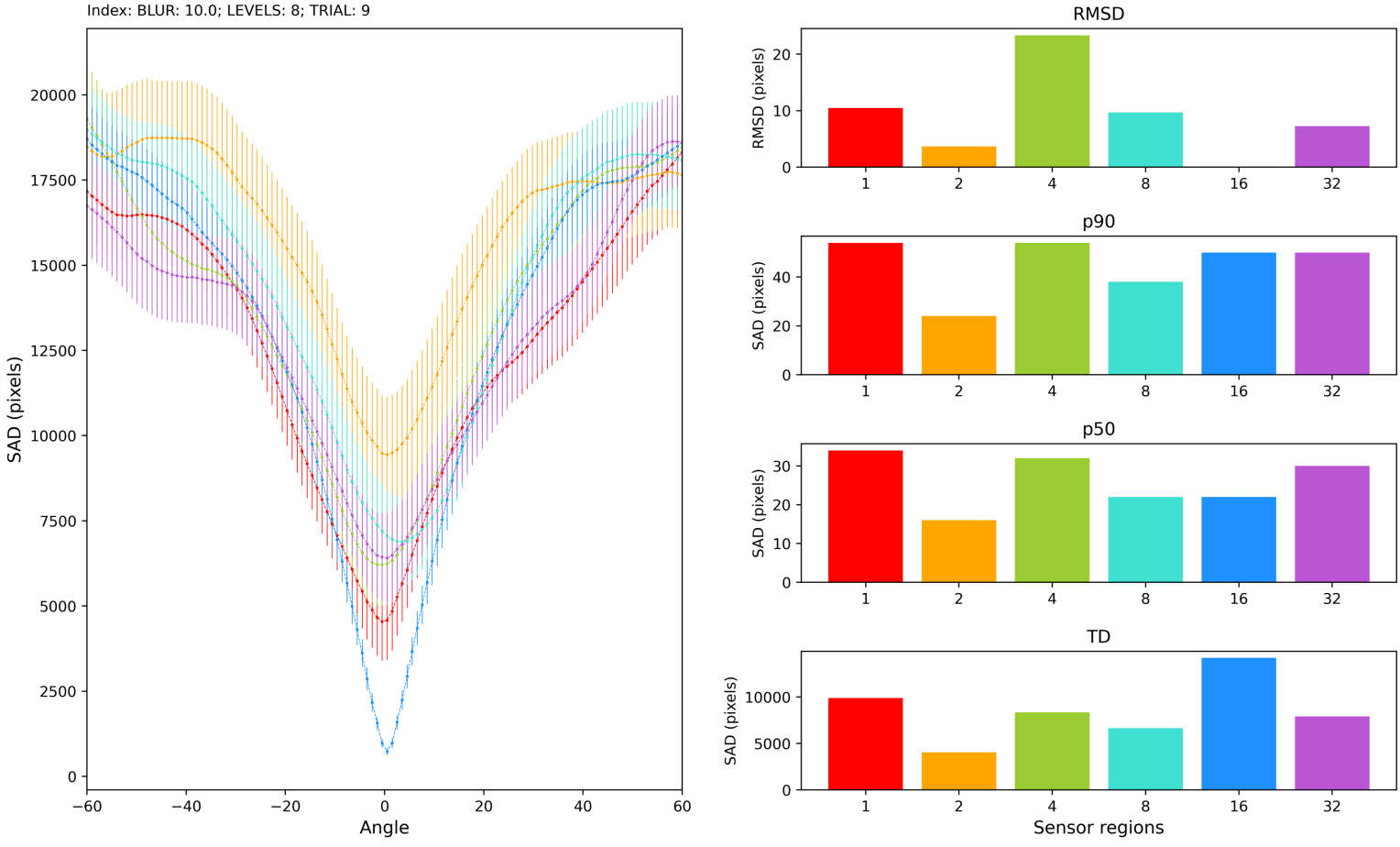
20%



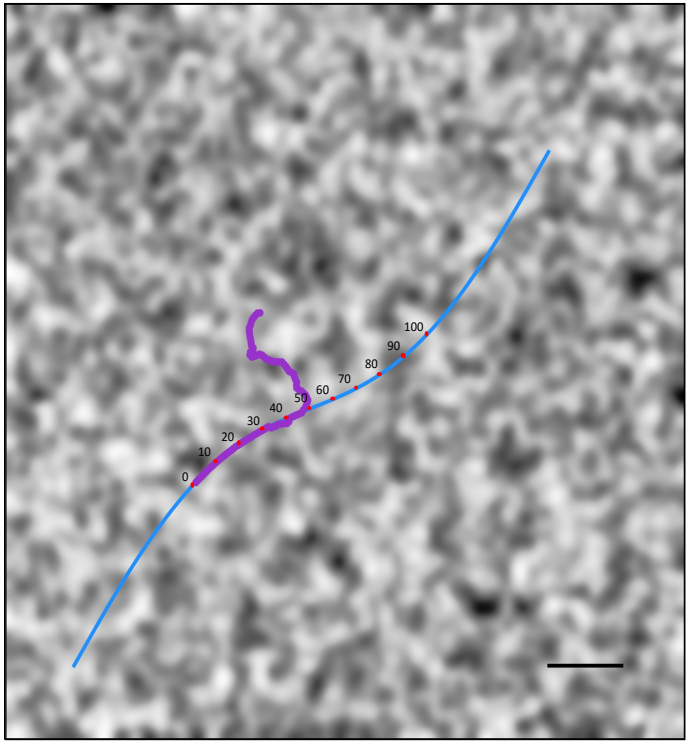


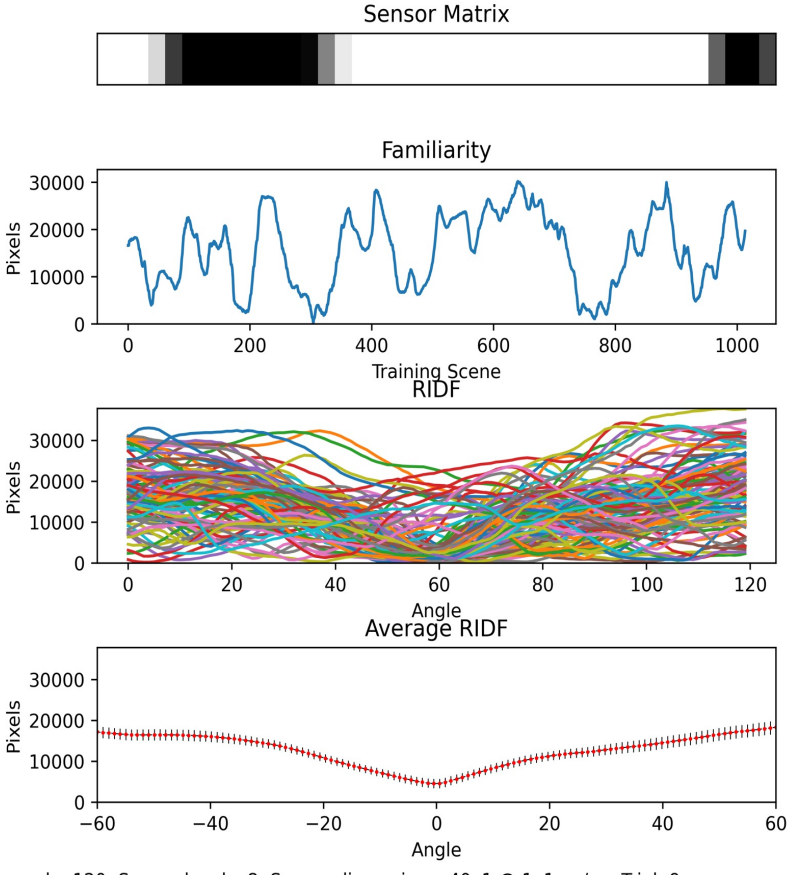
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3227.52; RMSD/dist: 8.069; TD: 6722; p90: 36; p50: 24; complete: 0


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

30%

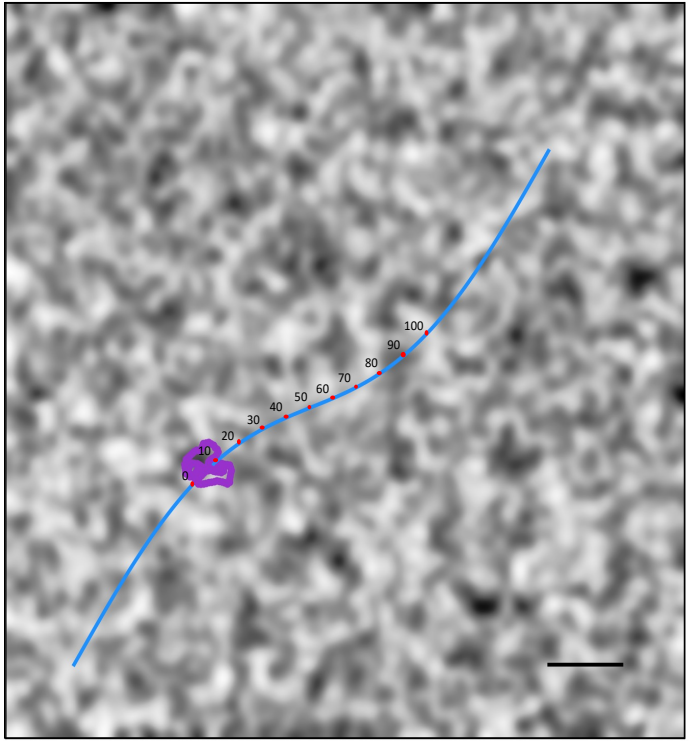


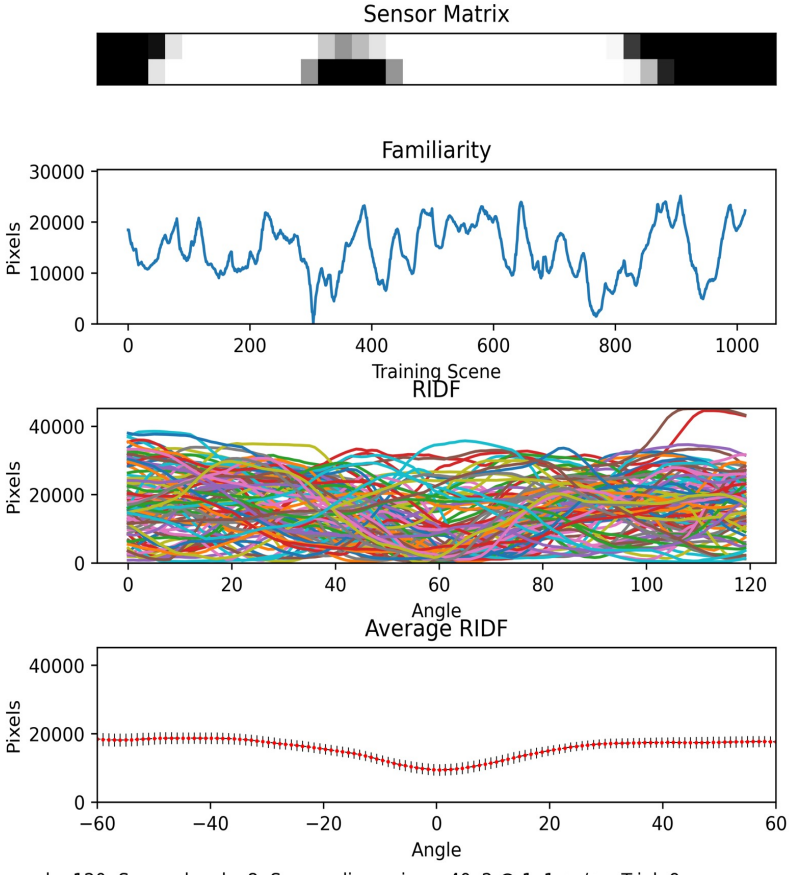


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 4190.74; RMSD/dist: 10.477; TD: 9876; p90: 54; p50: 34; complete: 0

0%





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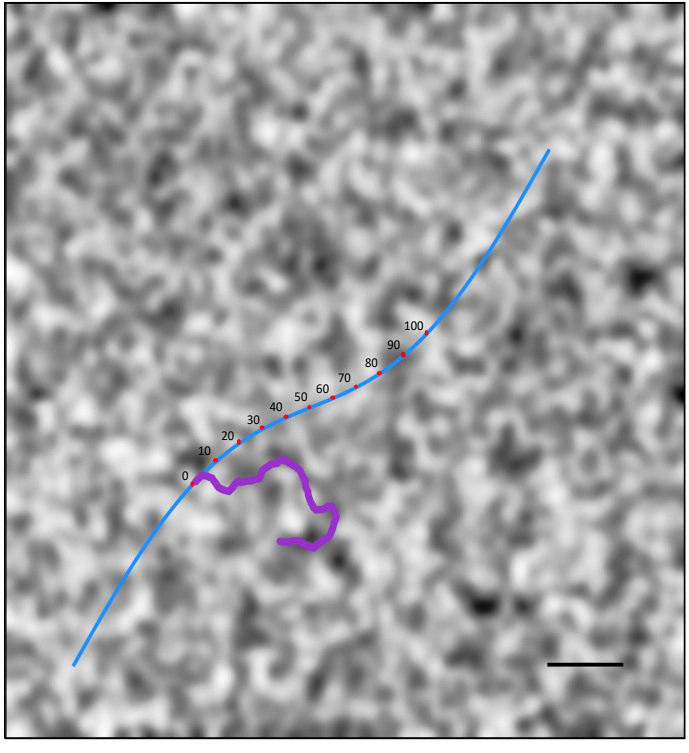
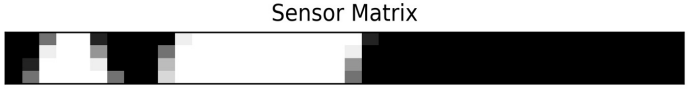
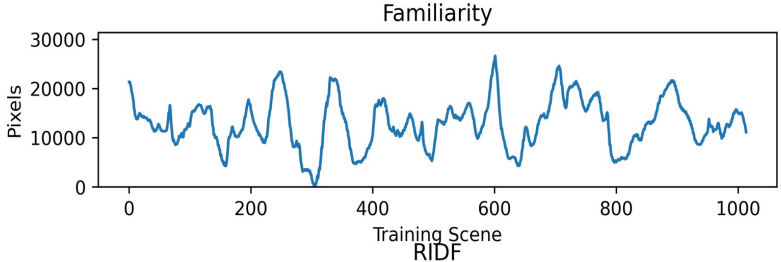
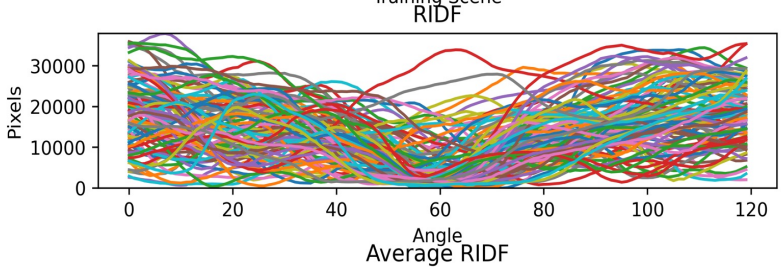
Navigation stats: RMSD error: 1456.00; RMSD/dist: 3.640; TD: 4032; p90: 24; p50: 16; complete: 0

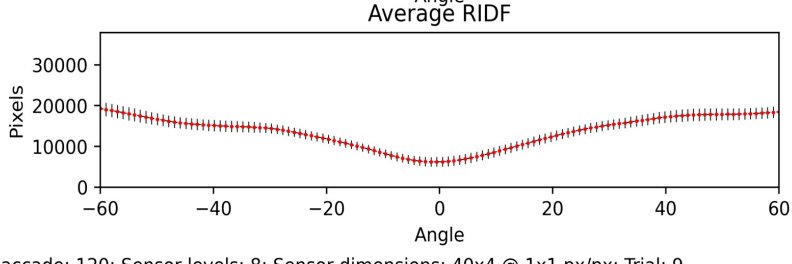
0%







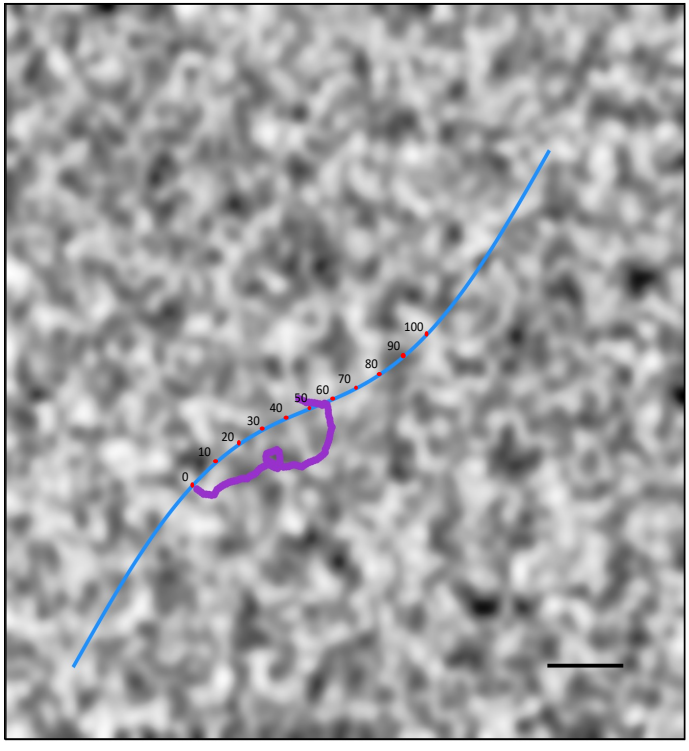


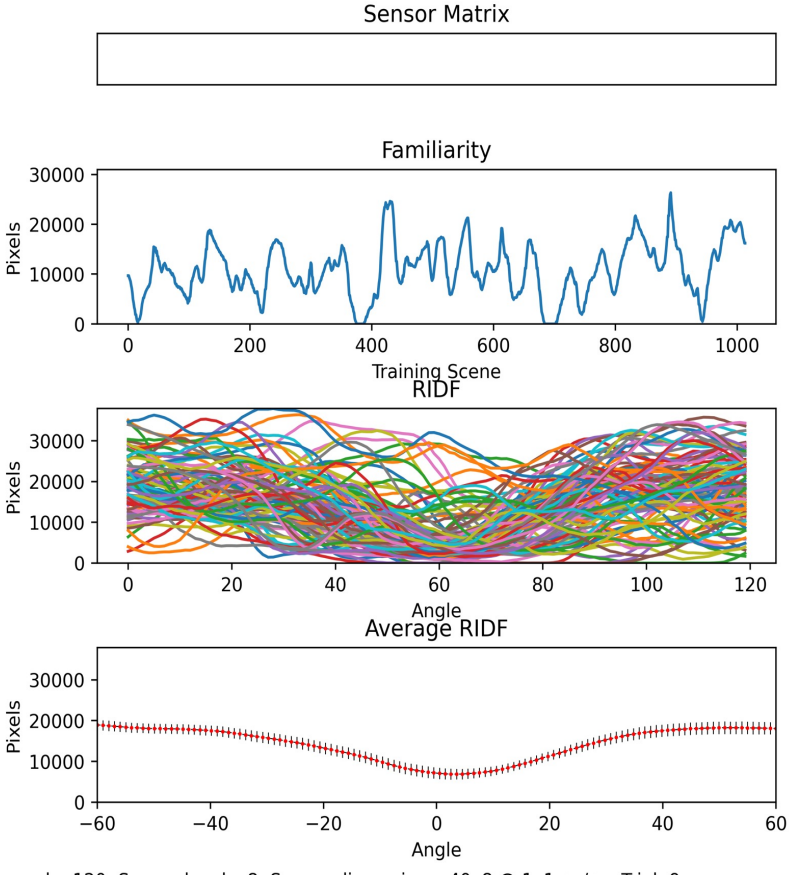


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 9344.66; RMSD/dist: 23.362; TD: 8329; p90: 54; p50: 32; complete: 0

0%

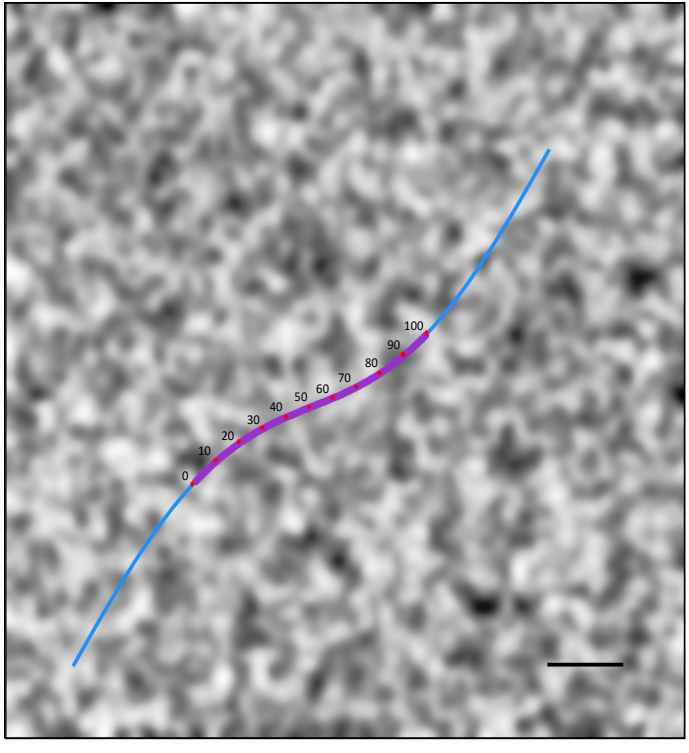


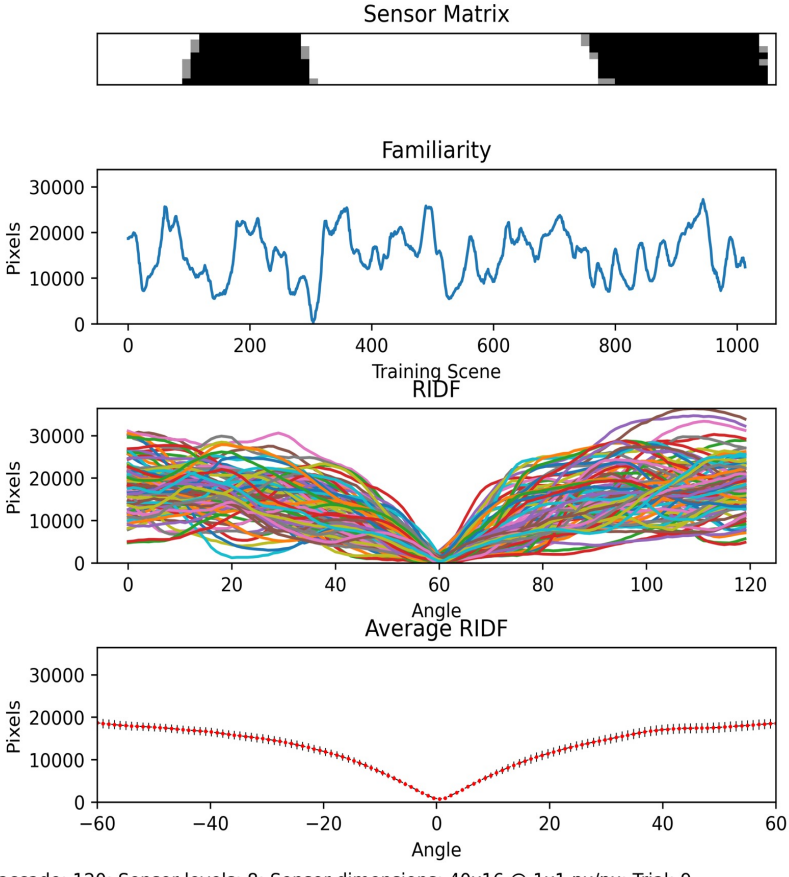


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3871.42; RMSD/dist: 9.679; TD: 6637; p90: 38; p50: 22; complete: 0

100%

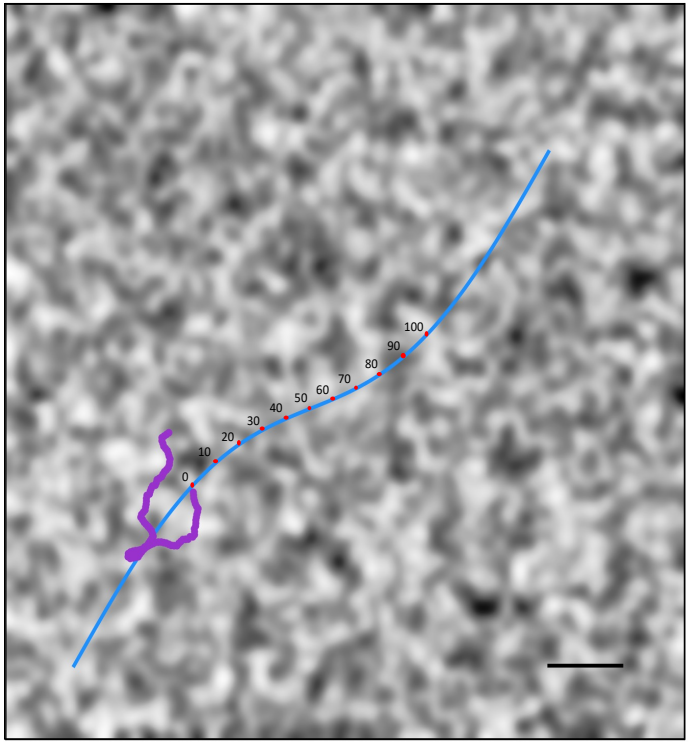


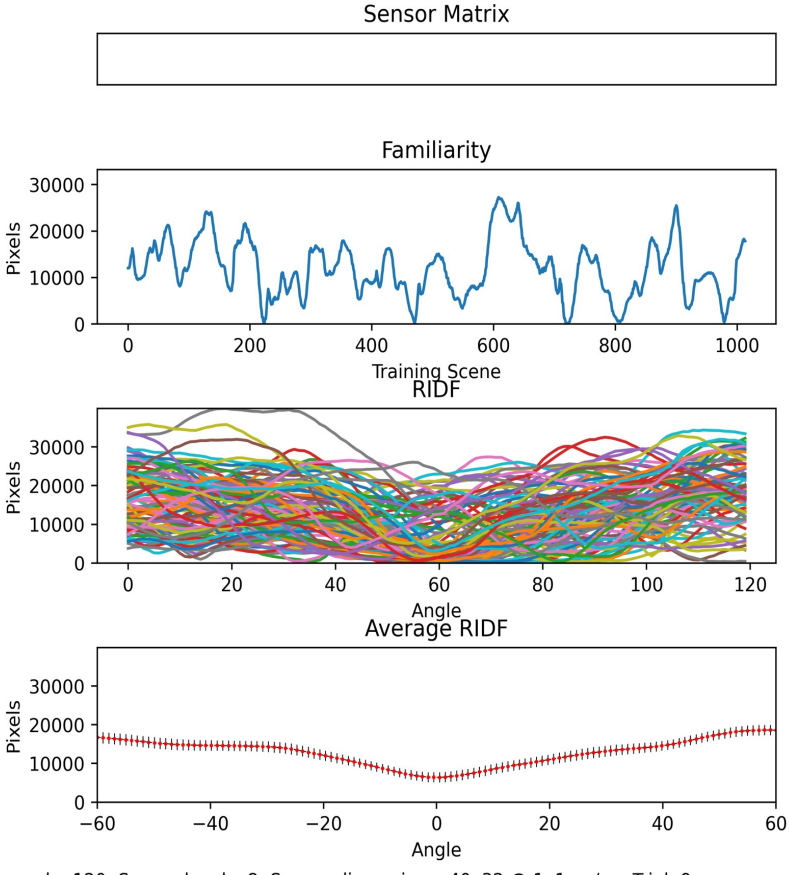


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 38.86; RMSD/dist: 0.097; TD: 14197; p90: 50; p50: 22; complete: 0

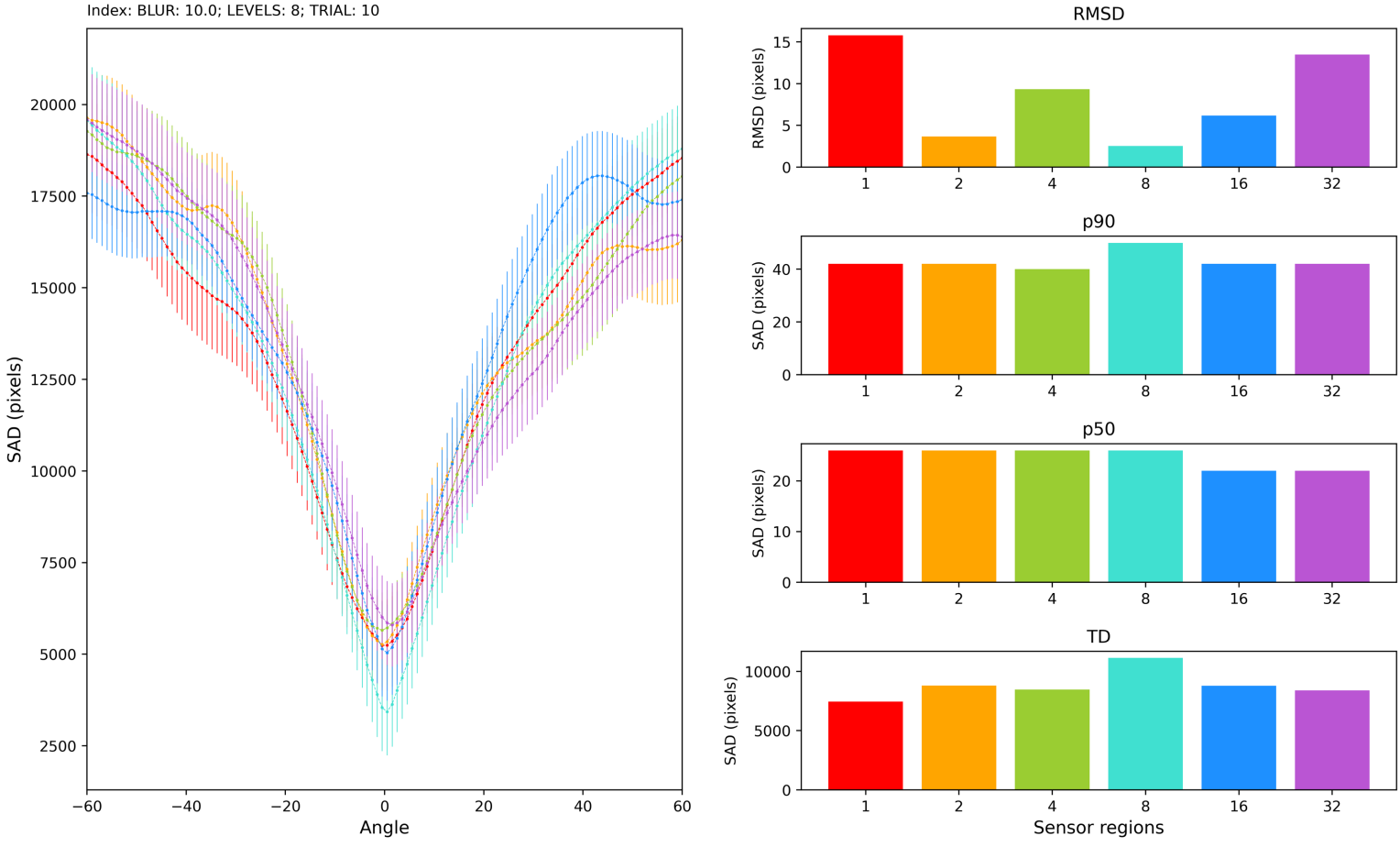
0%



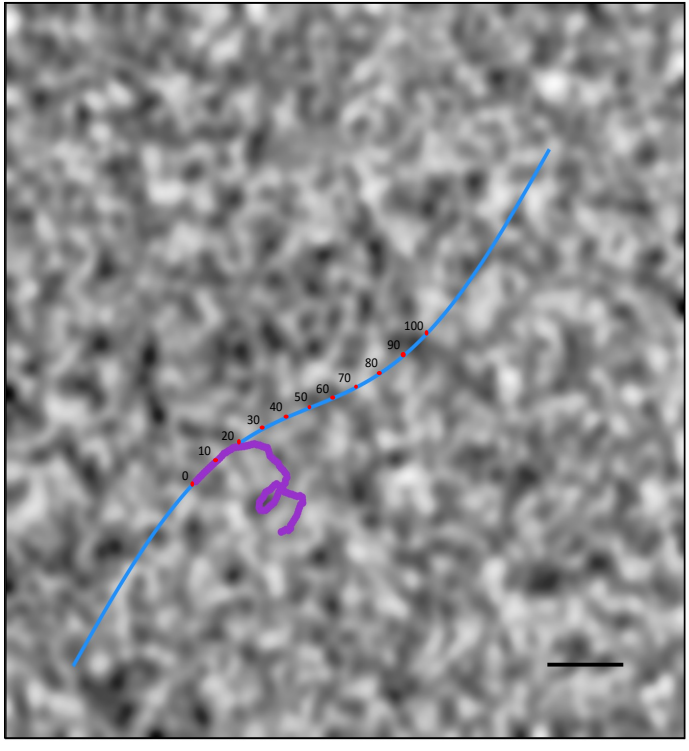


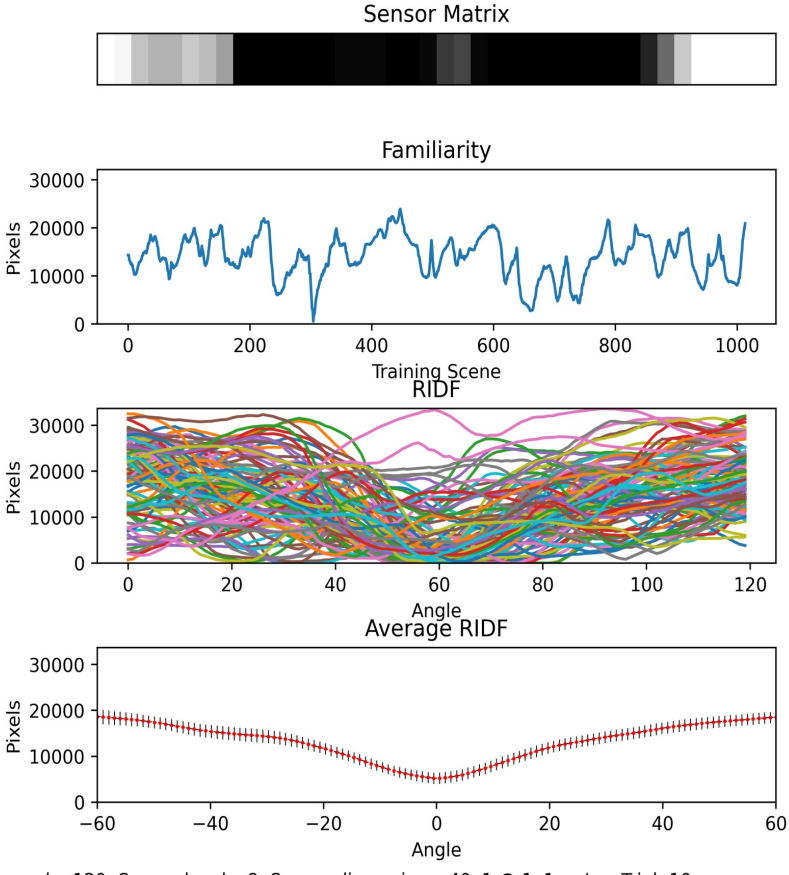
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2905.62; RMSD/dist: 7.264; TD: 7918; p90: 50; p50: 30; complete: 0


Index: BLUR: 10.0; LEVELS: 8; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

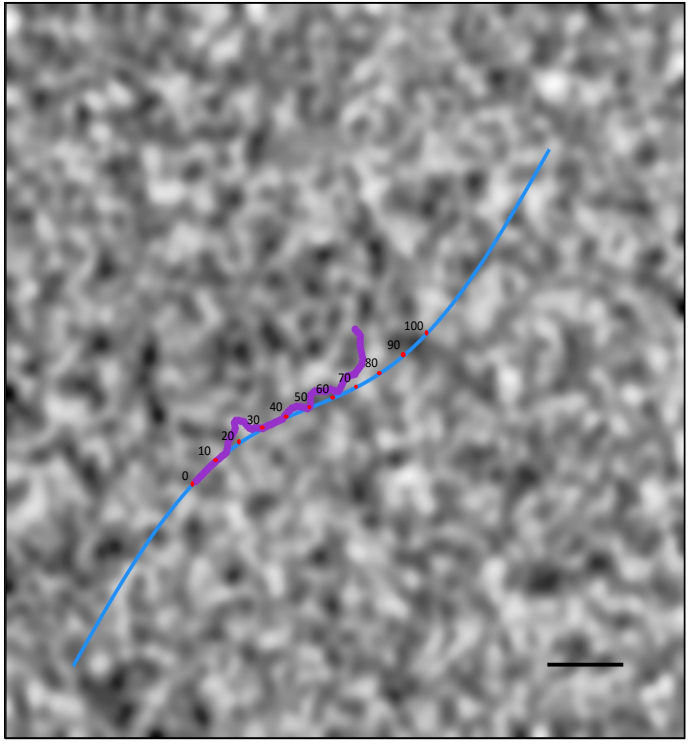


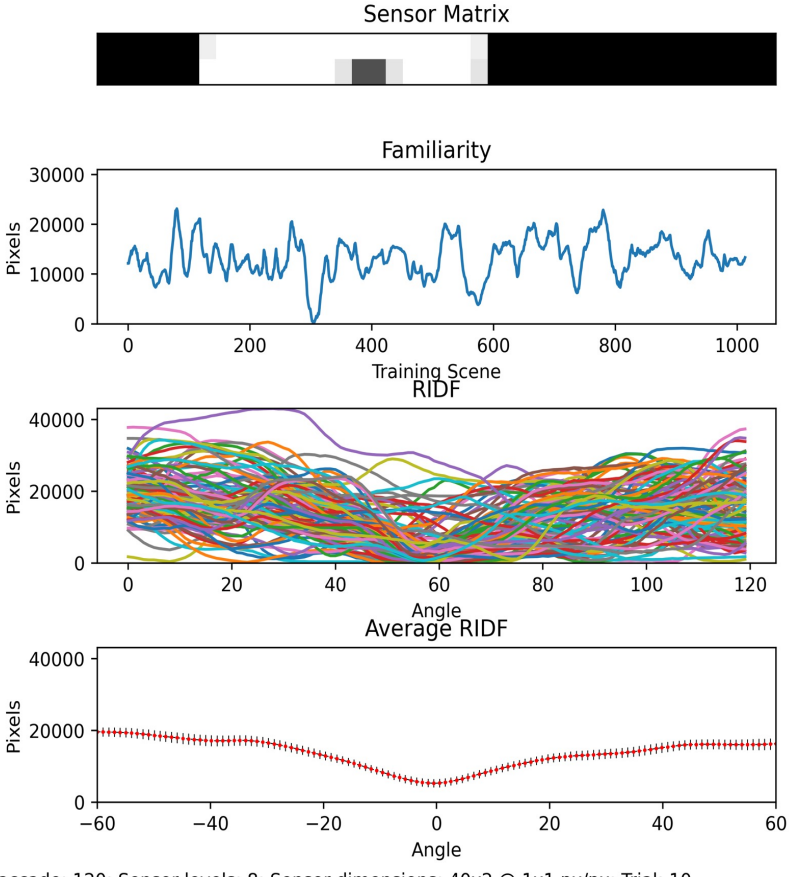


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 6320.15; RMSD/dist: 15.800; TD: 7450; p90: 42; p50: 26; complete: 0

20%

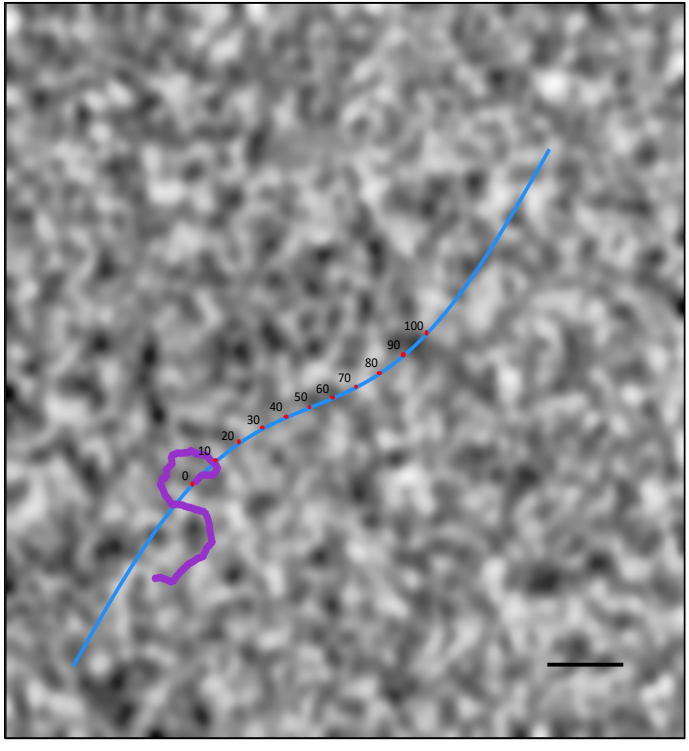


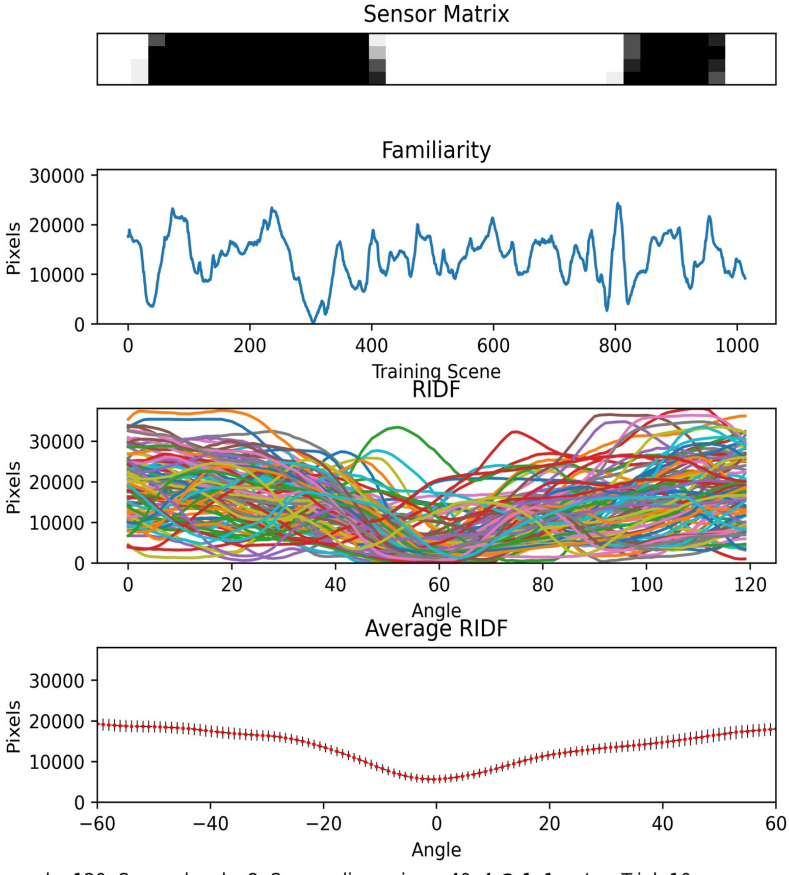


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1465.13; RMSD/dist: 3.663; TD: 8811; p90: 42; p50: 26; complete: 0

0%

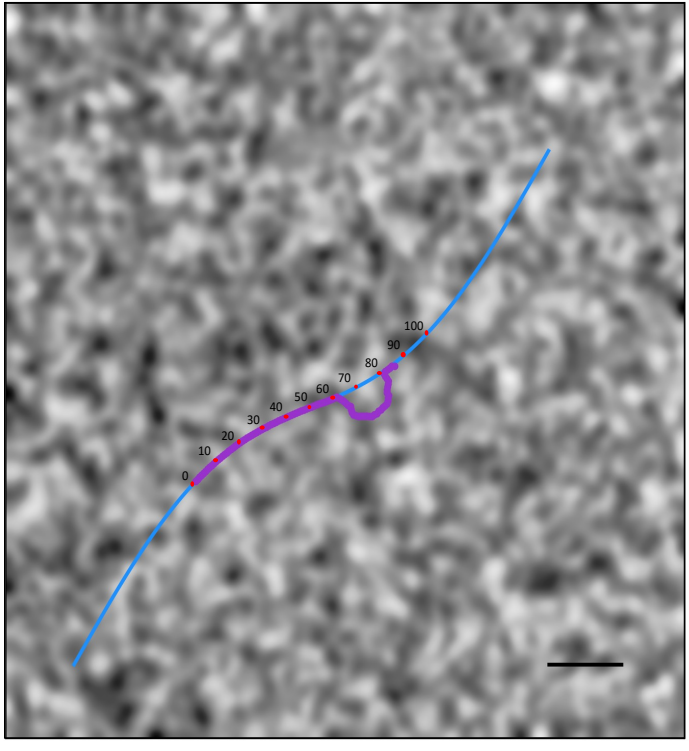


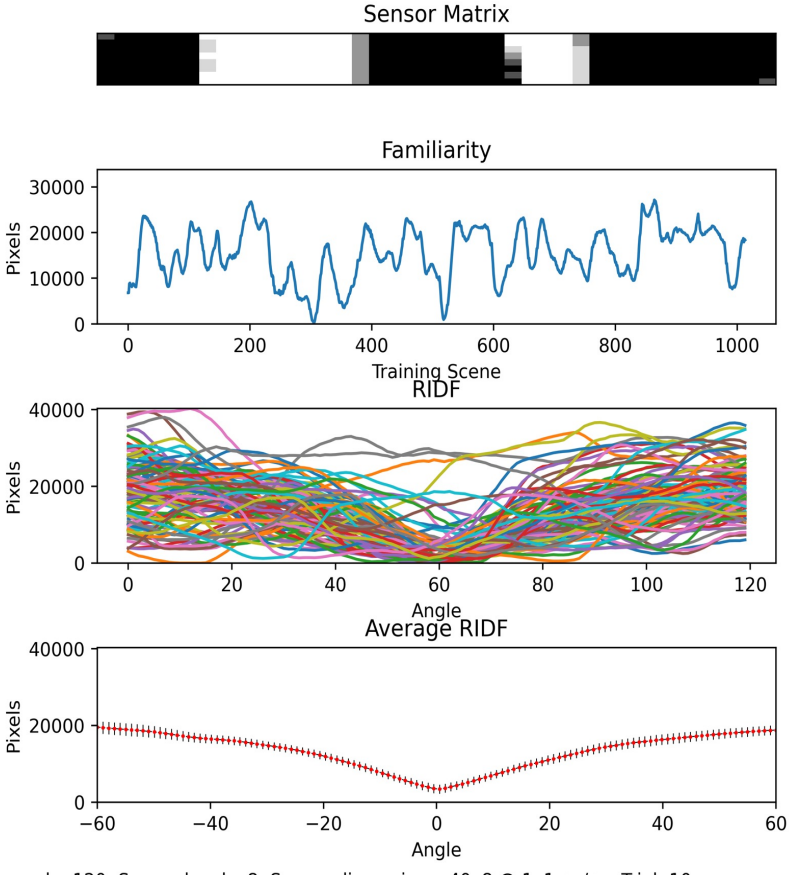


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3731.97; RMSD/dist: 9.330; TD: 8466; p90: 40; p50: 26; complete: 0

60%

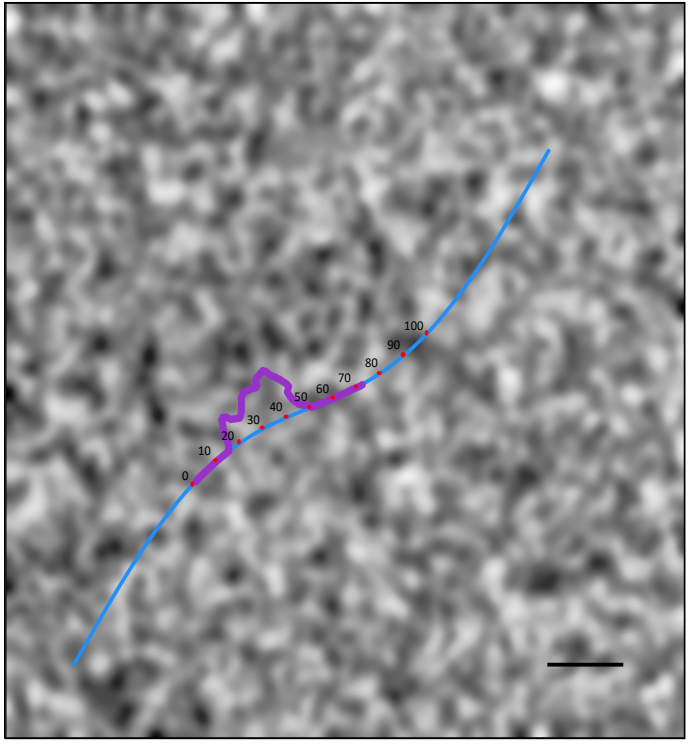


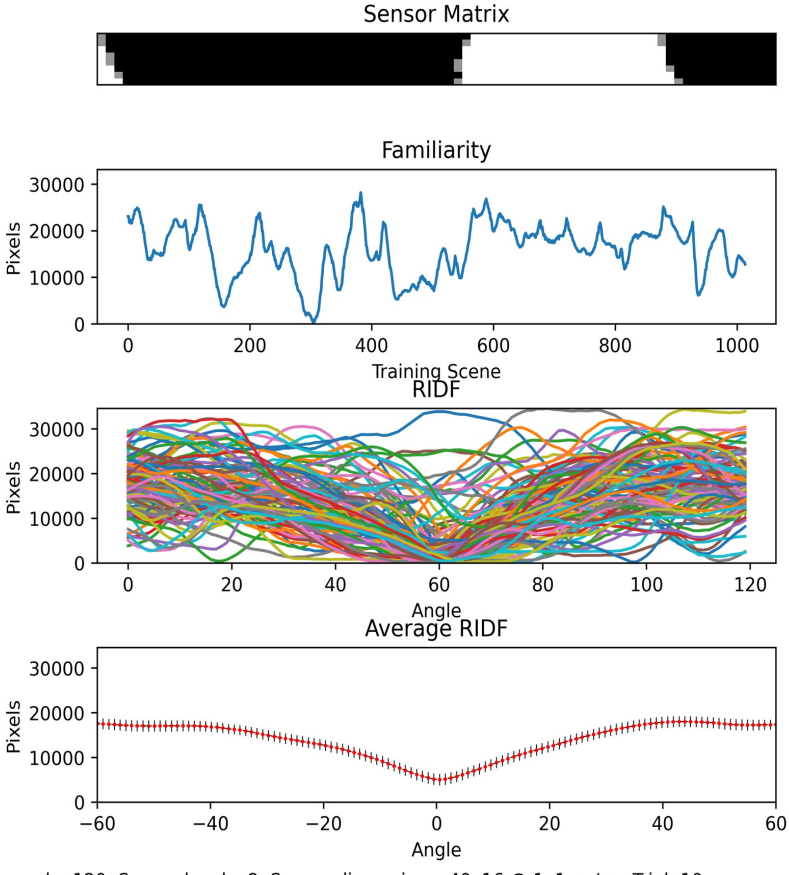


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1005.12; RMSD/dist: 2.513; TD: 11130; p90: 50; p50: 26; complete: 0

30%

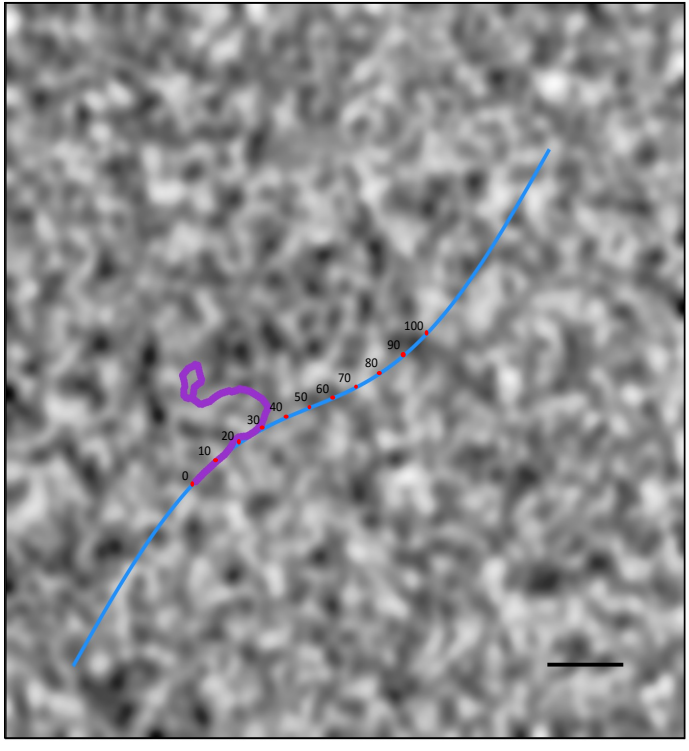


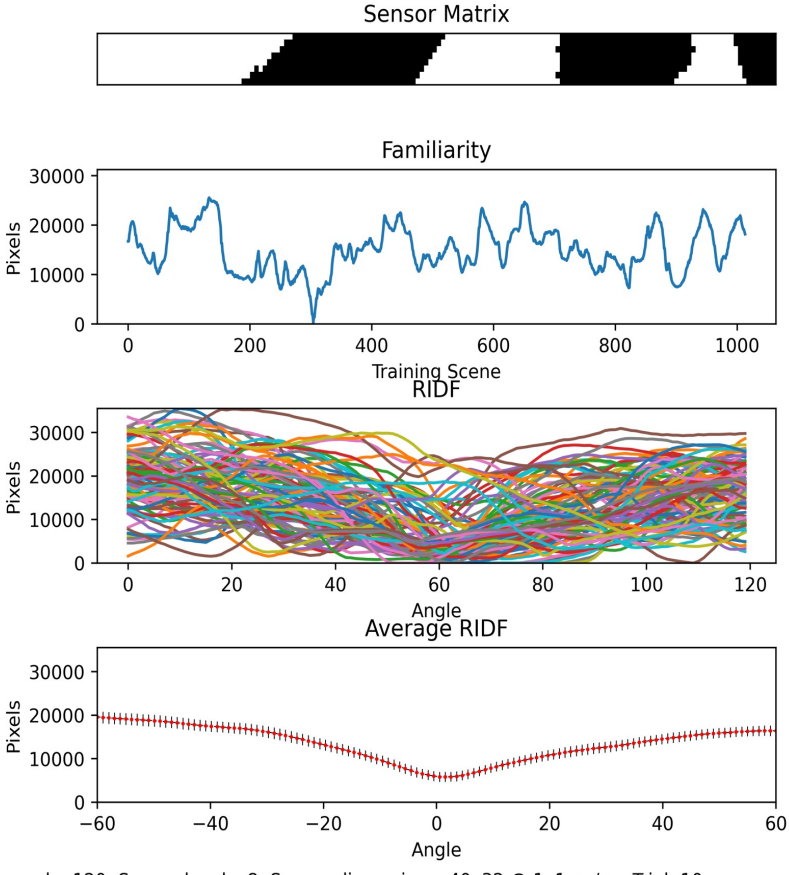


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2463.20; RMSD/dist: 6.158; TD: 8787; p90: 42; p50: 22; complete: 0

20%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 10; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 5395.78; RMSD/dist: 13.489; TD: 8394; p90: 42; p50: 22; complete: 0