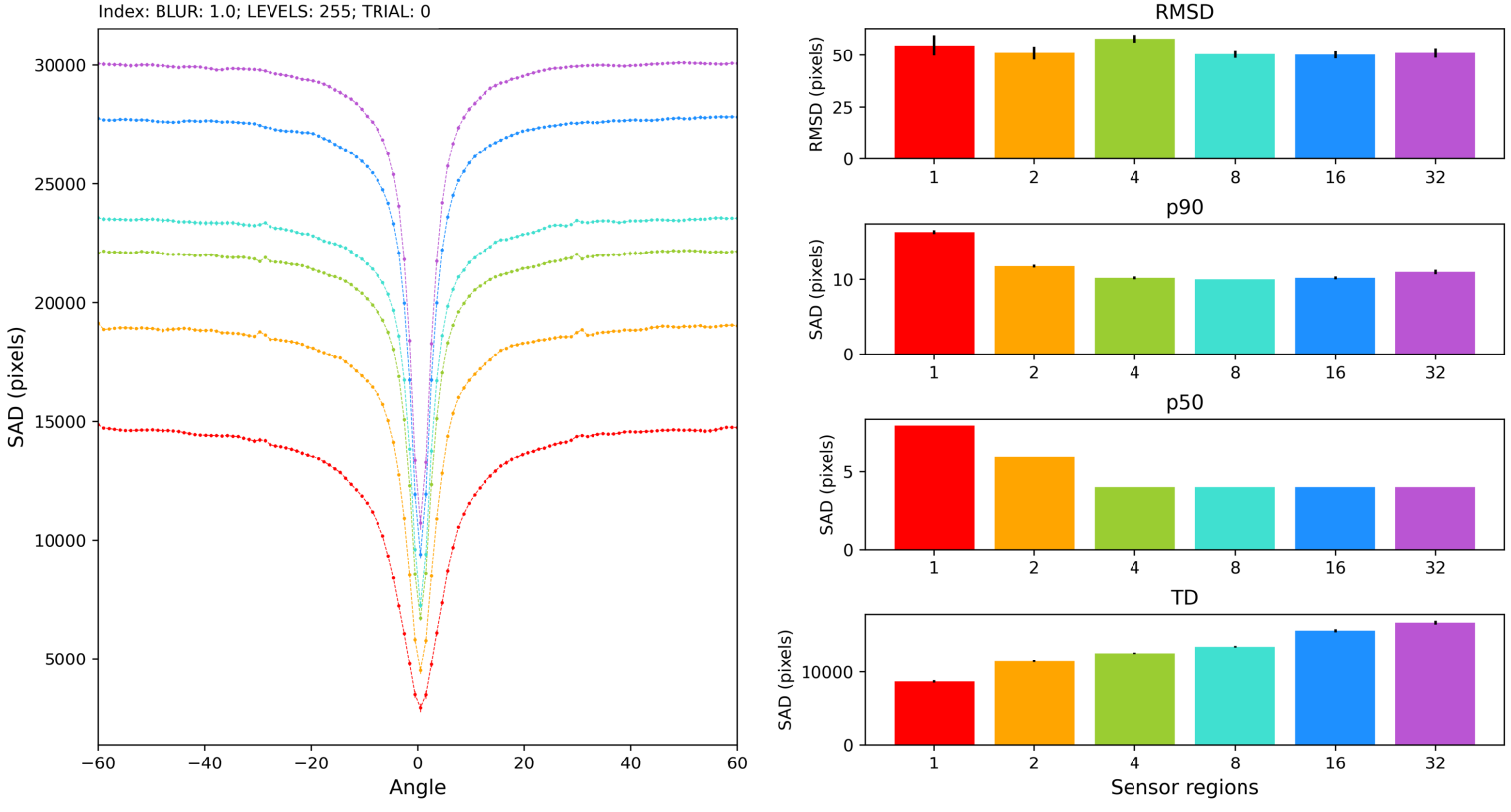
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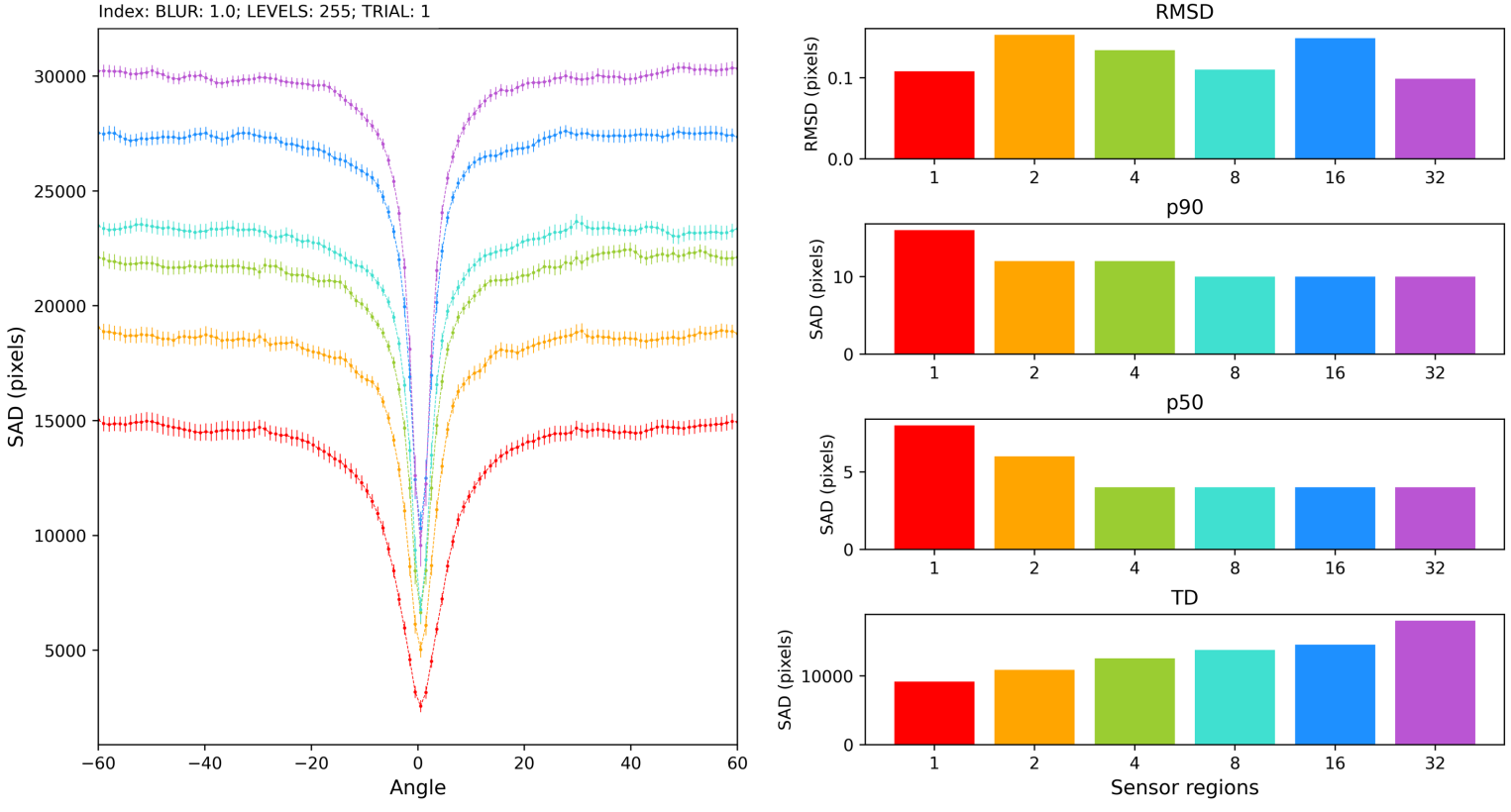
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
50
25
0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
Sensor regions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SAD (pixels)
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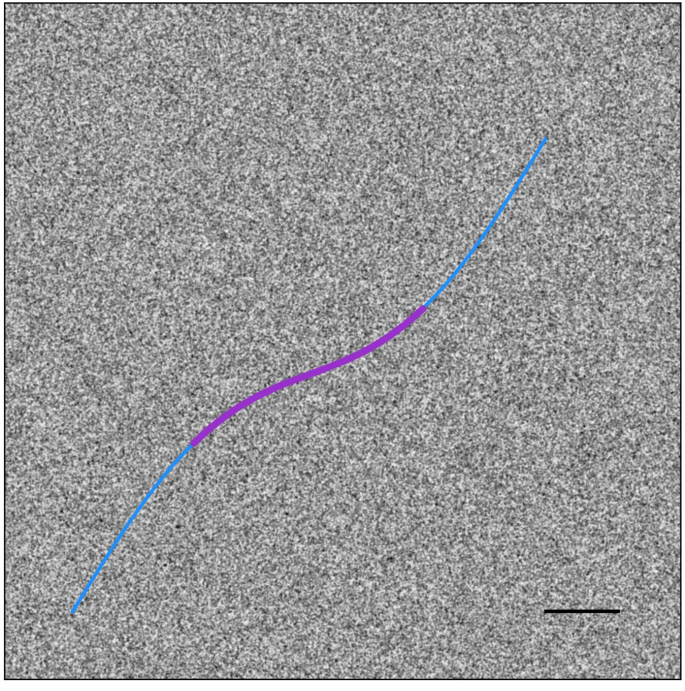
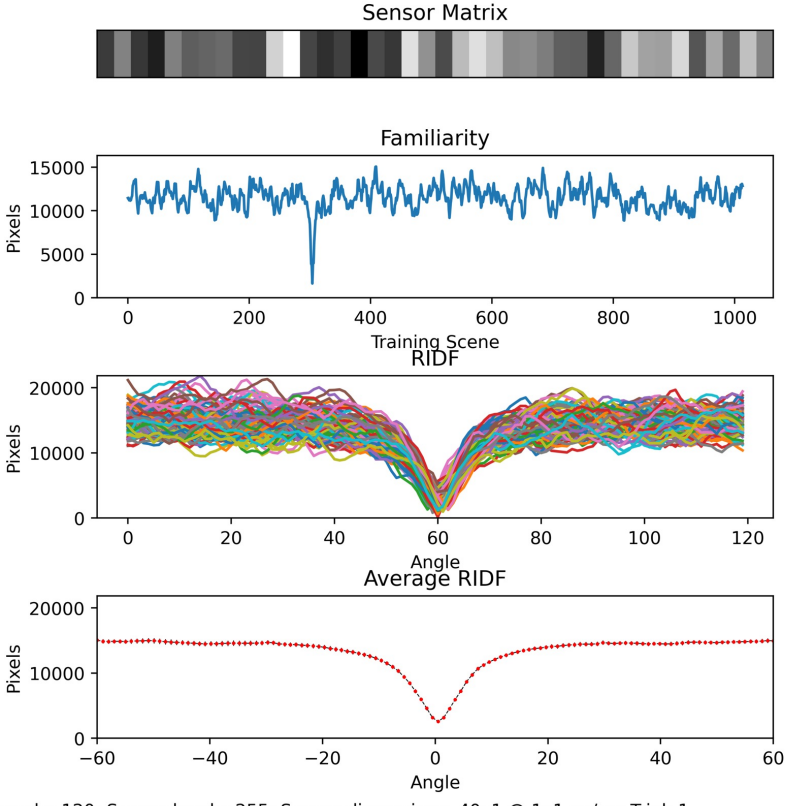
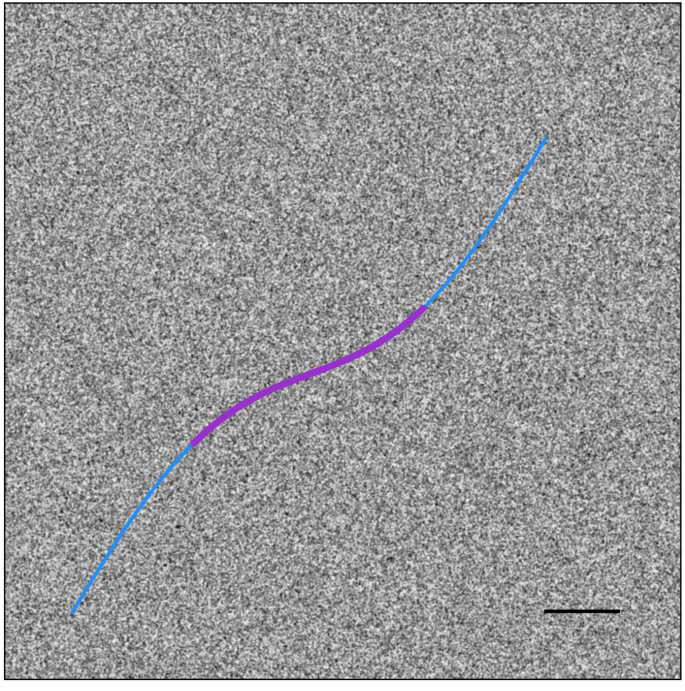
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
1
2
4
8
16
32
Sensor regions

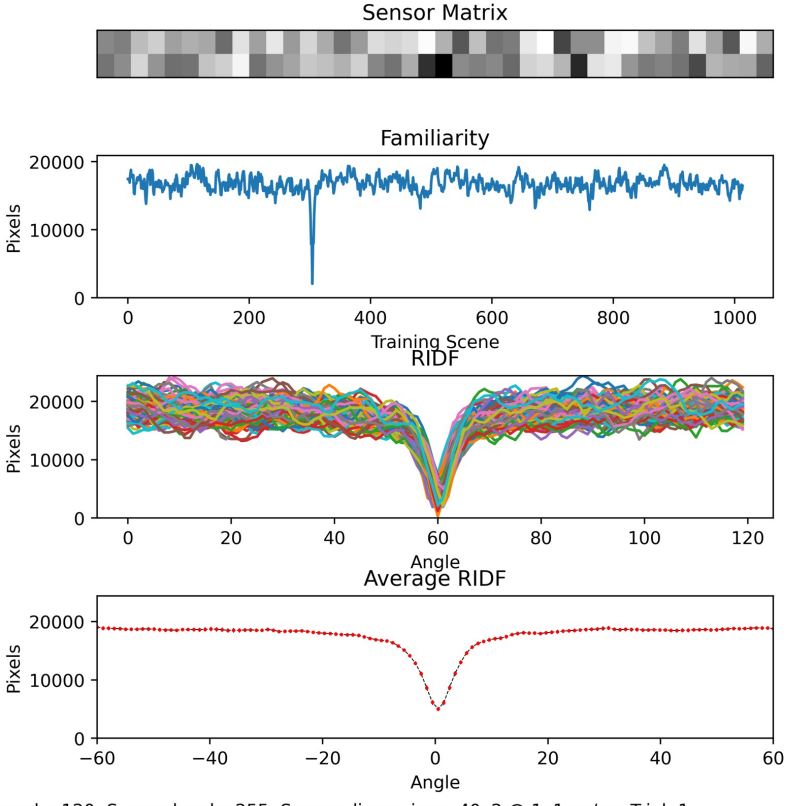




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

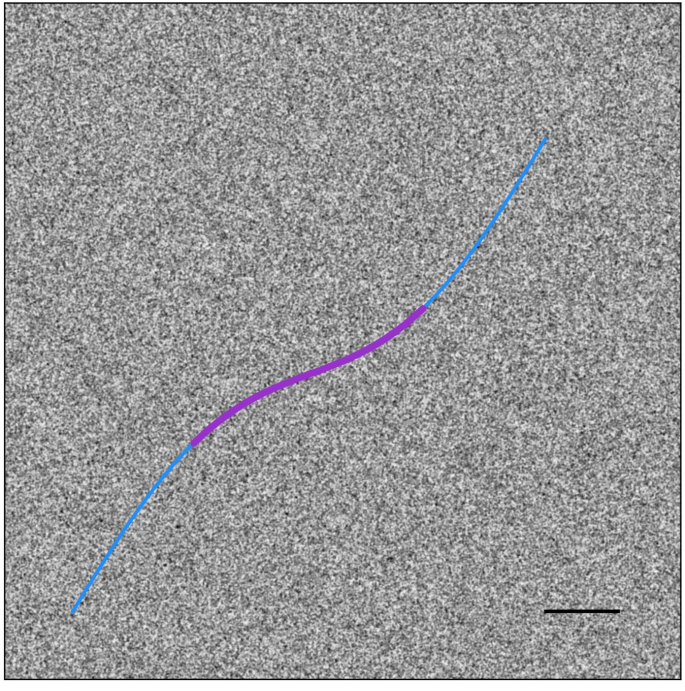
Navigation stats: RMSD error: 43.21; RMSD/dist: 0.108; TD: 9167; p90: 16; p50: 8; complete: 0

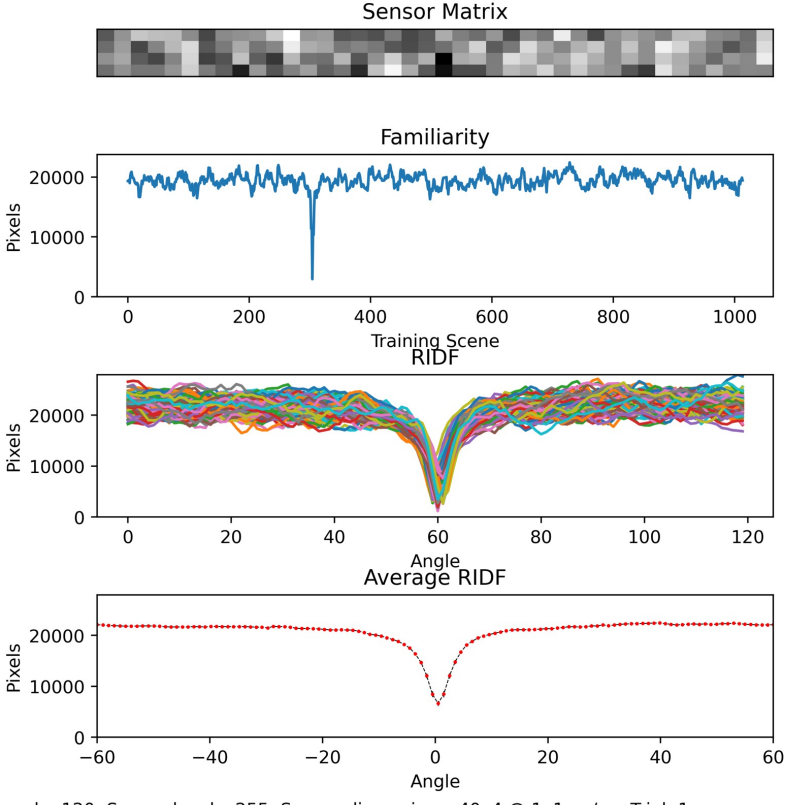




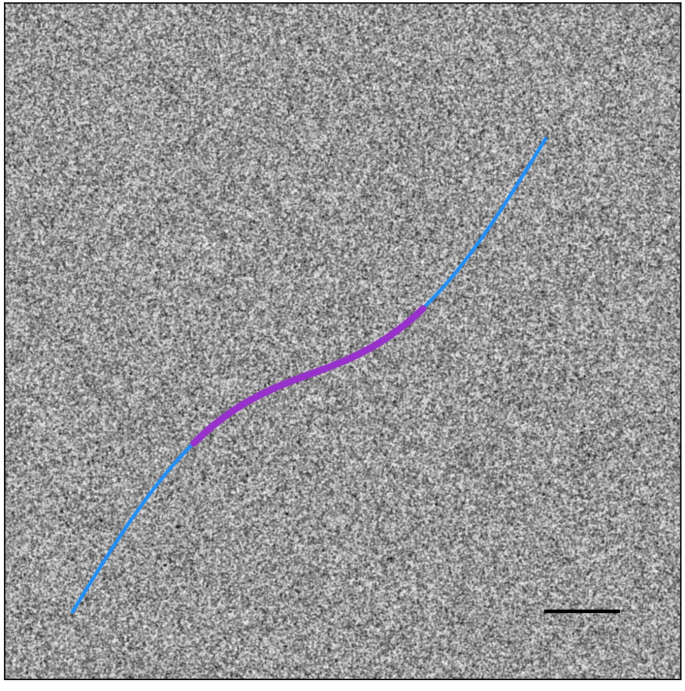
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

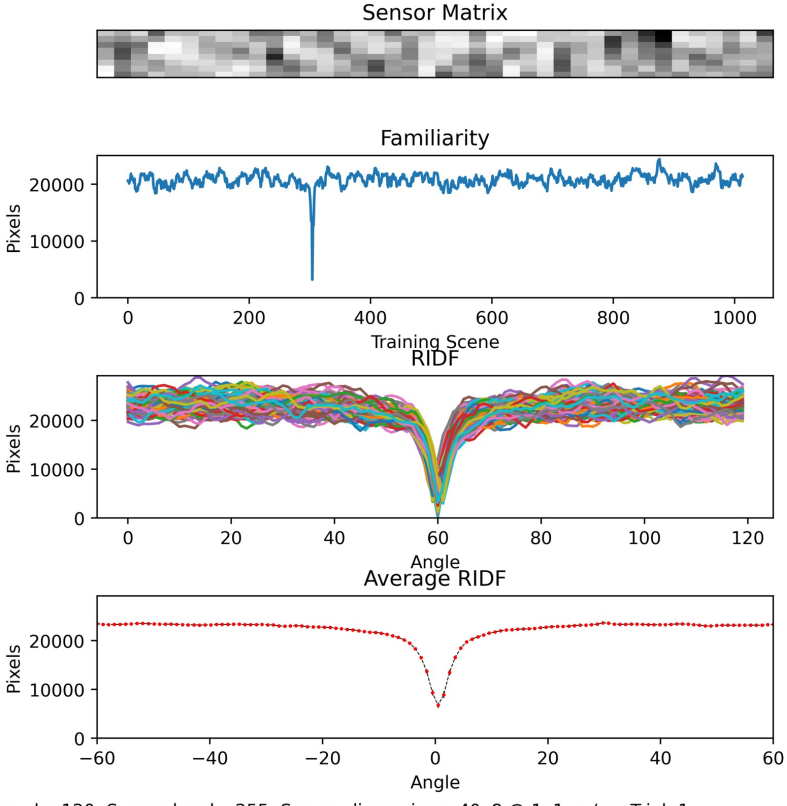
Navigation stats: RMSD error: 61.15; RMSD/dist: 0.153; TD: 10901; p90: 12; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 53.54; RMSD/dist: 0.134; TD: 12580; p90: 12; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1
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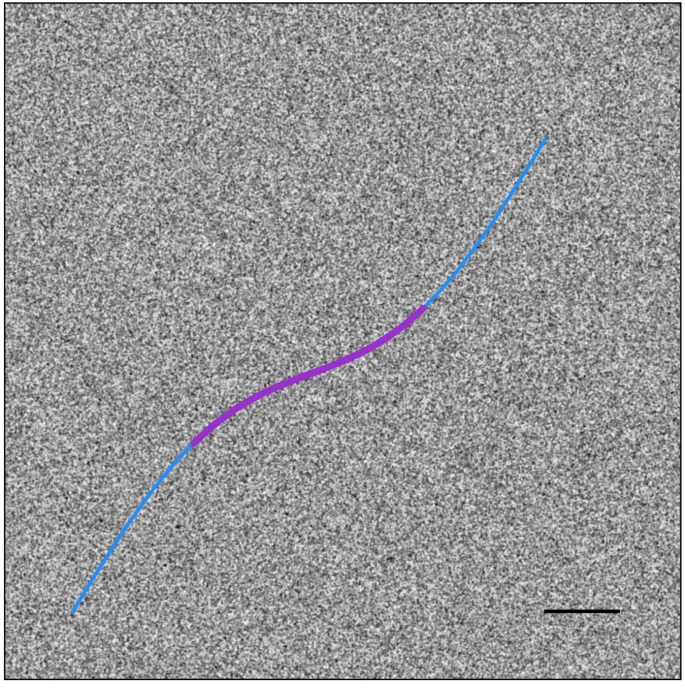
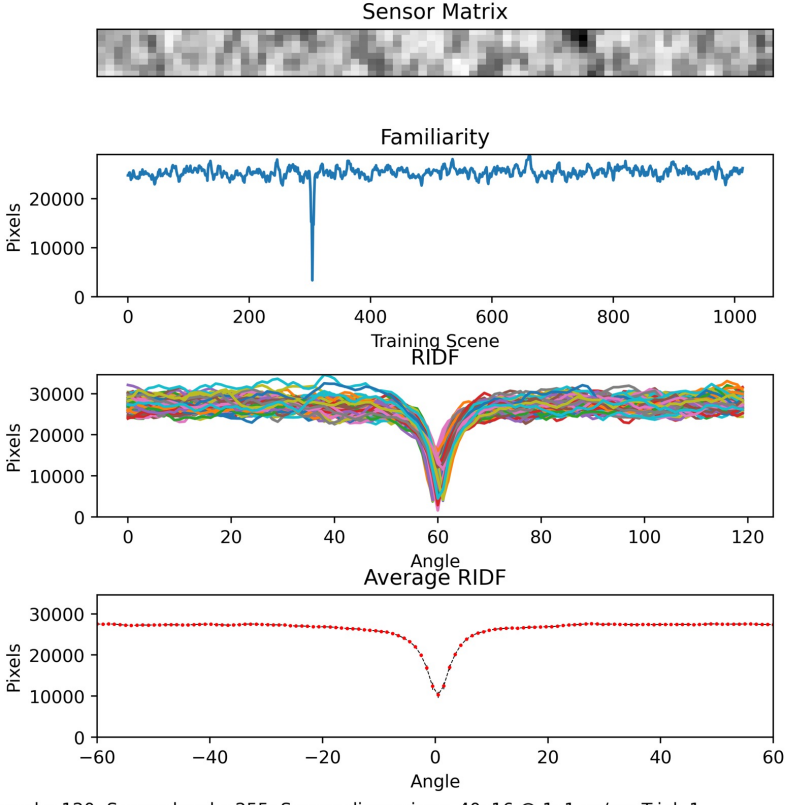
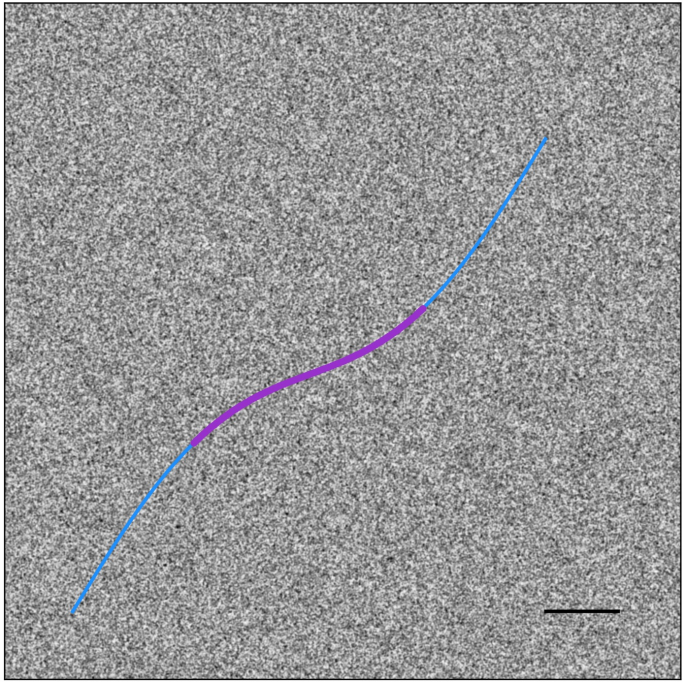
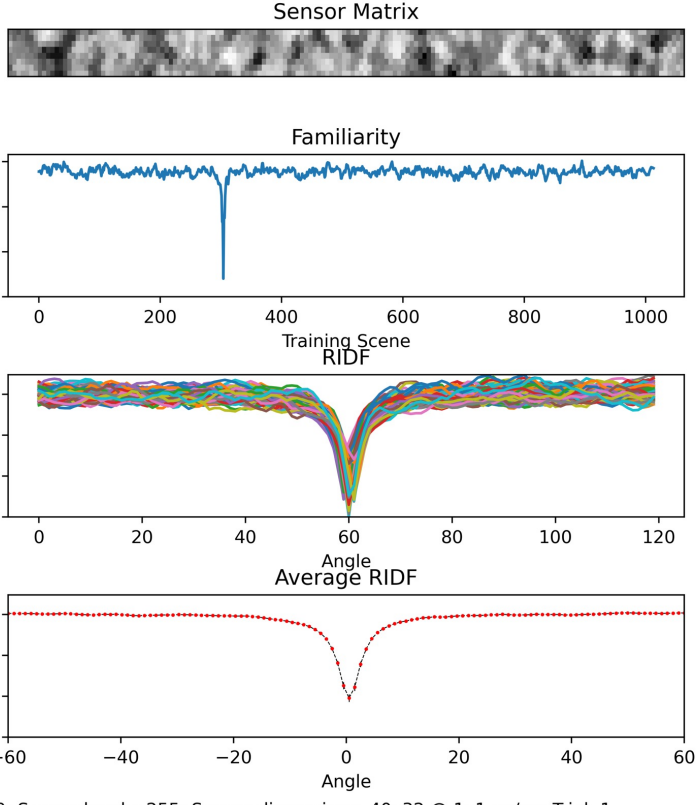


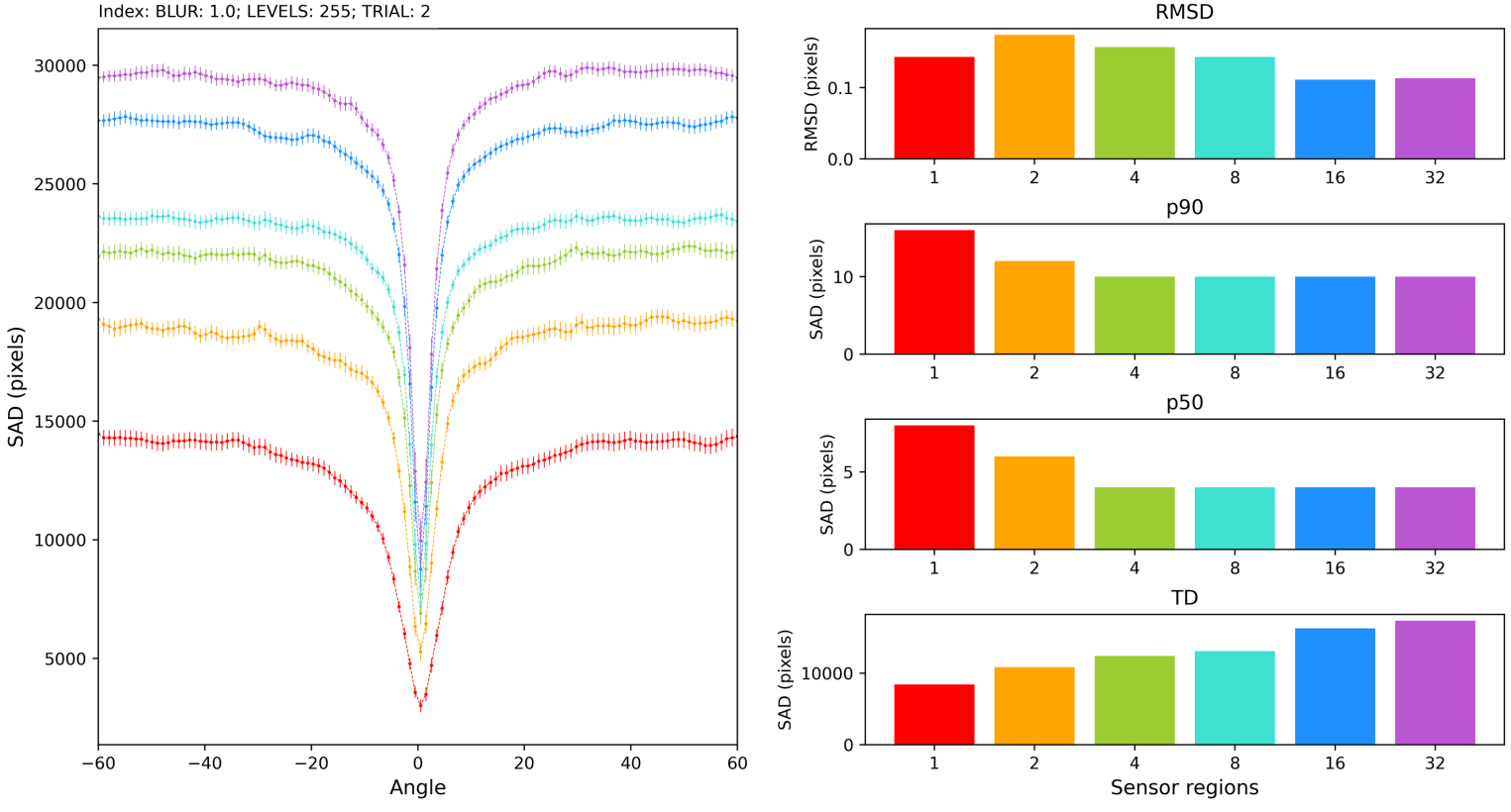


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 59.57; RMSD/dist: 0.149; TD: 14571; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 39.66; RMSD/dist: 0.099; TD: 18055; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
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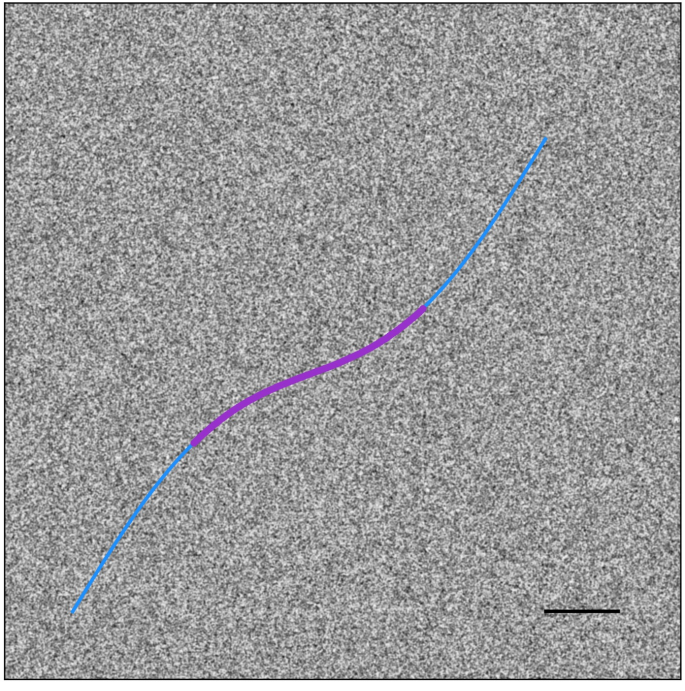
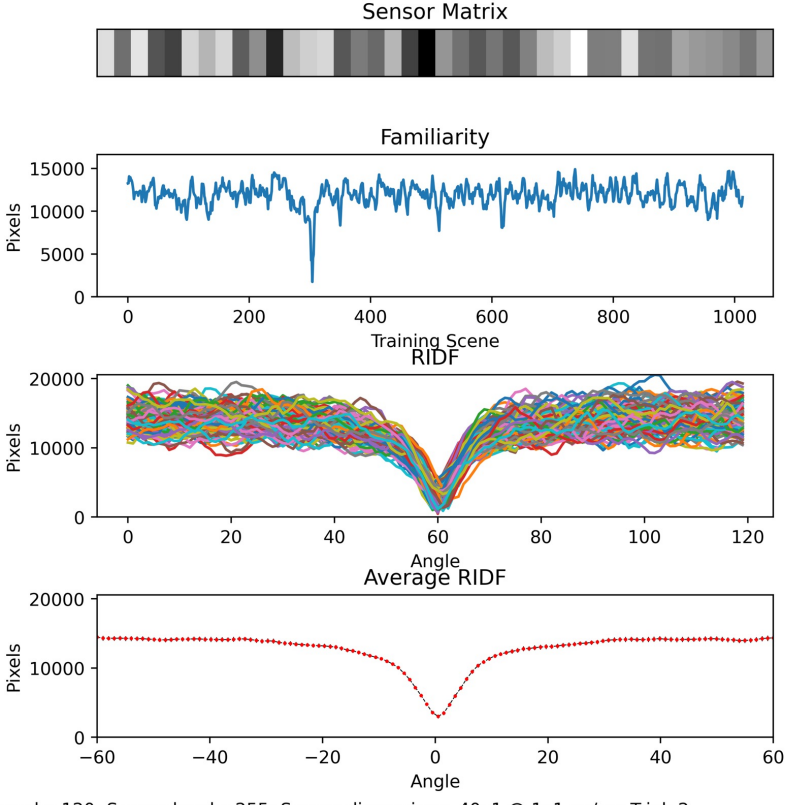
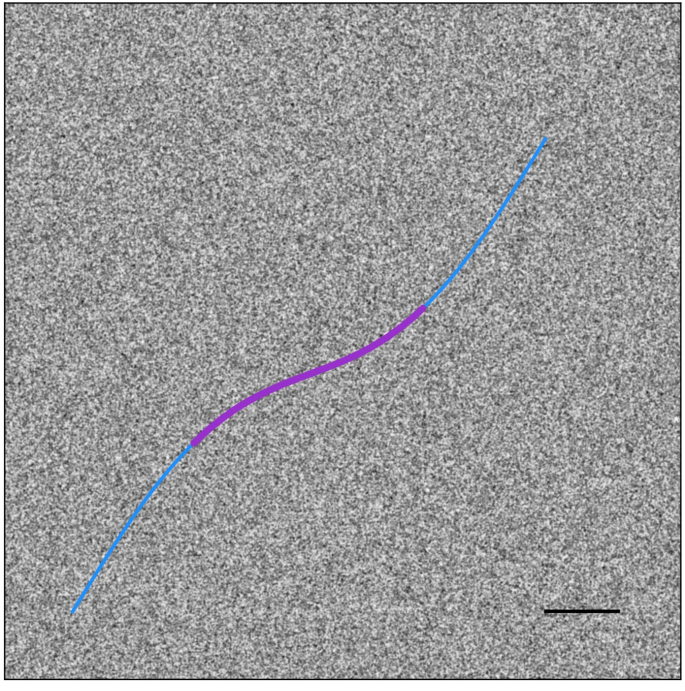
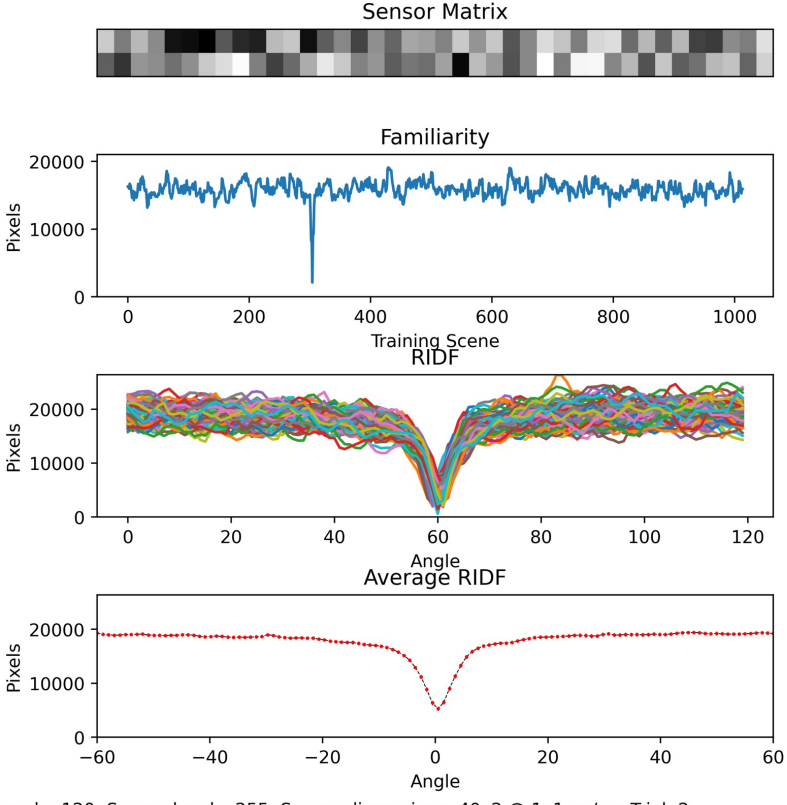
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
Sensor regions



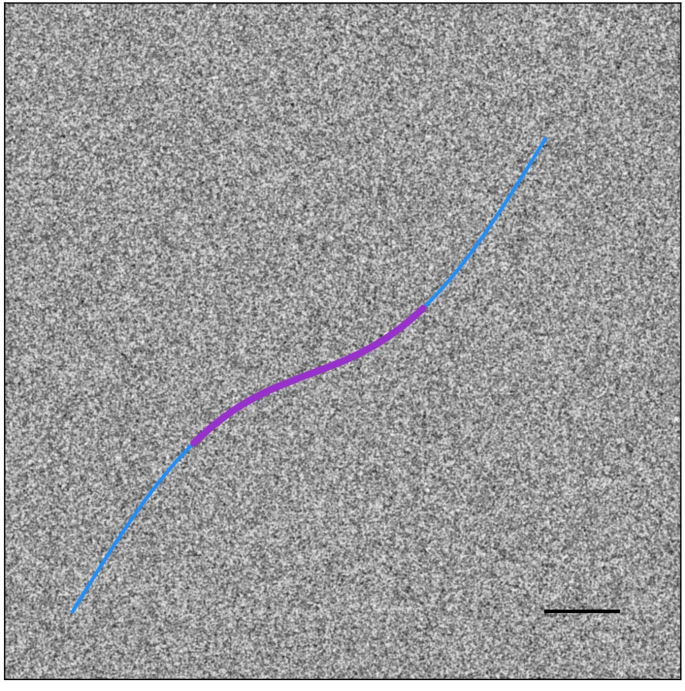


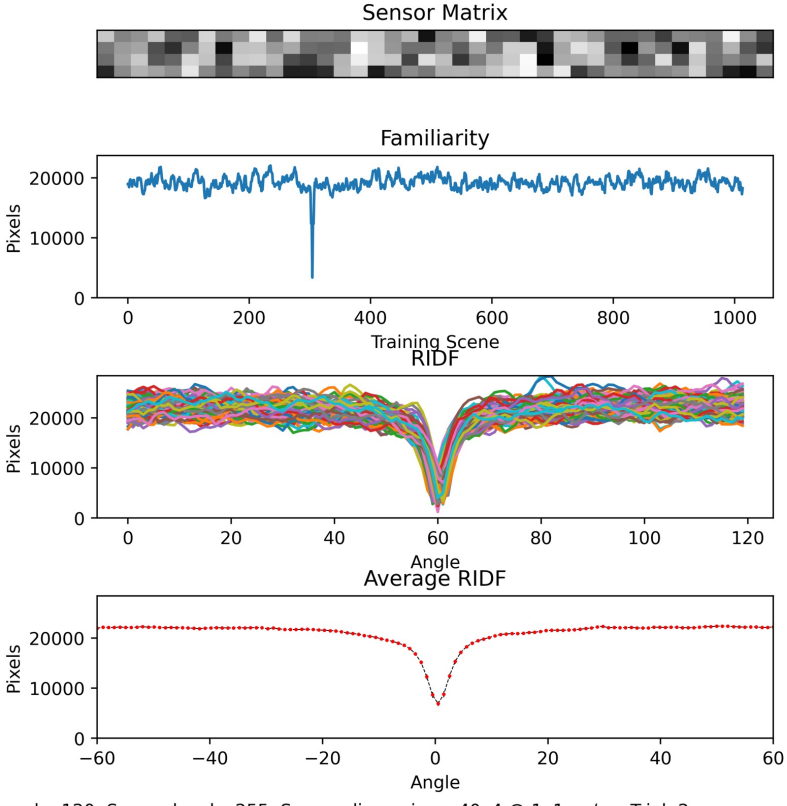
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 57.22; RMSD/dist: 0.143; TD: 8404; p90: 16; p50: 8; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 69.53; RMSD/dist: 0.174; TD: 10829; p90: 12; p50: 6; complete: 0





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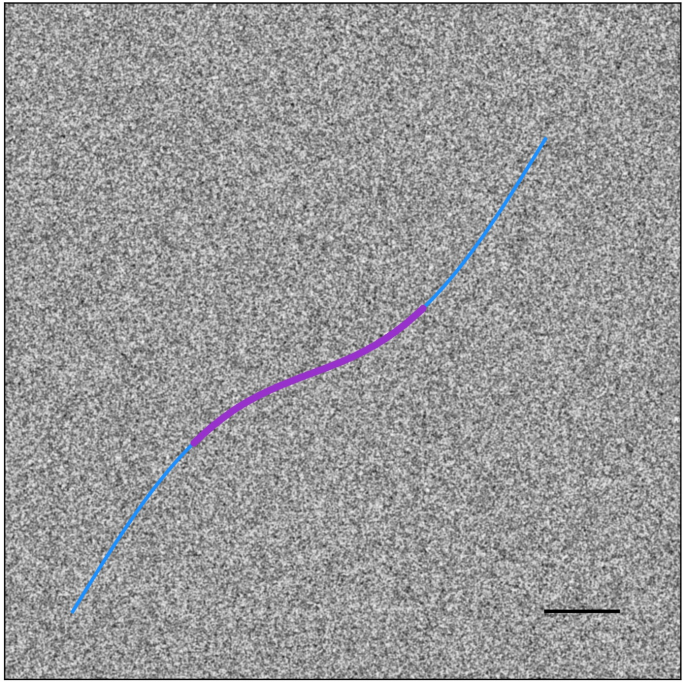

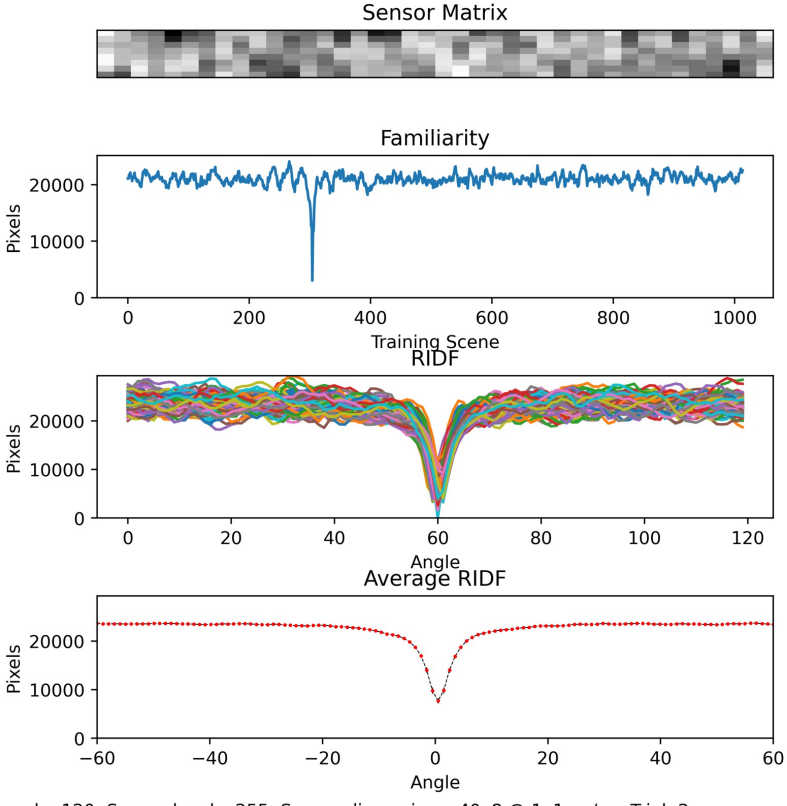

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2
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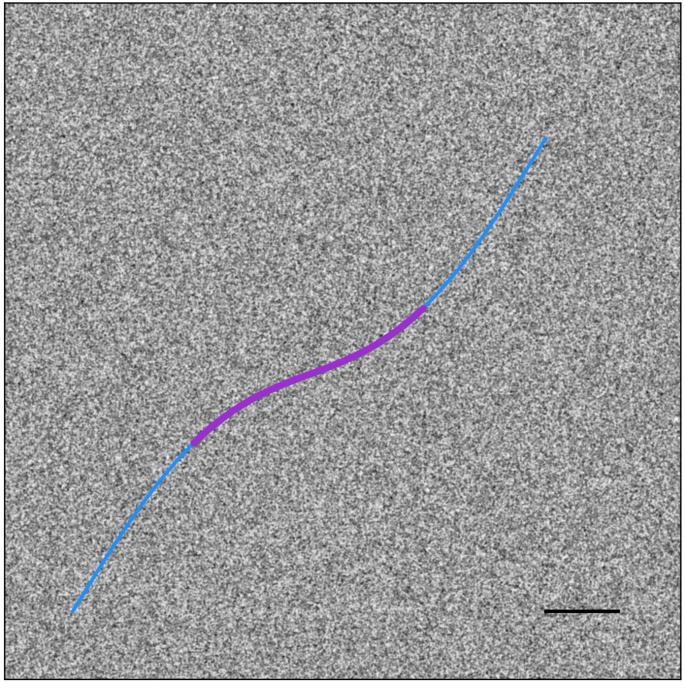
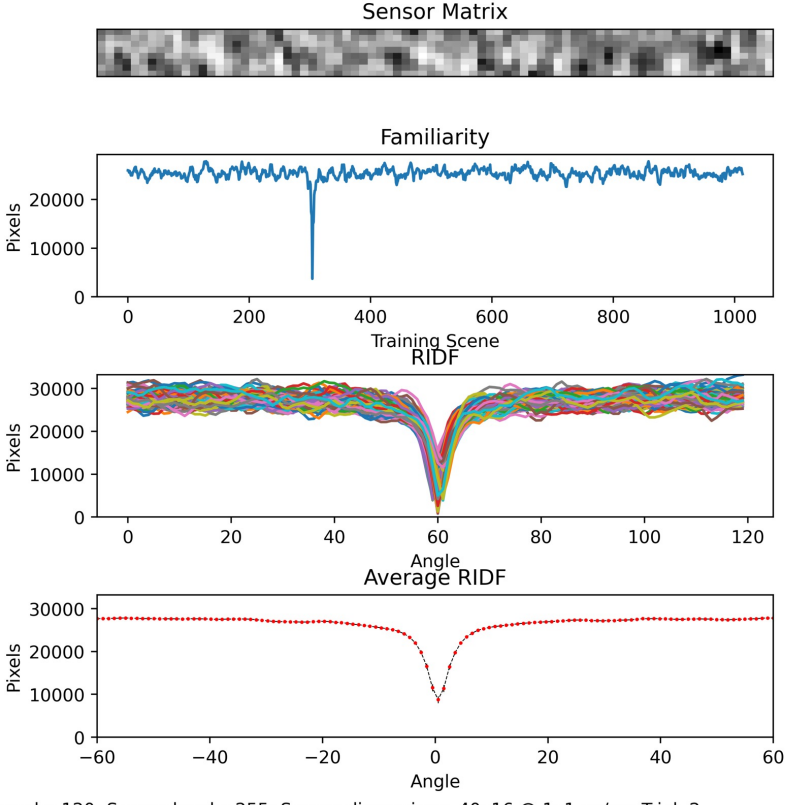
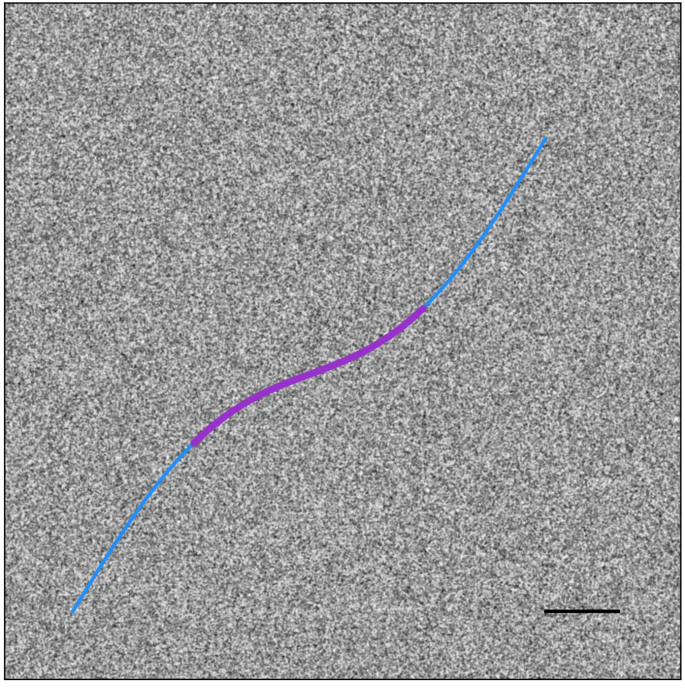
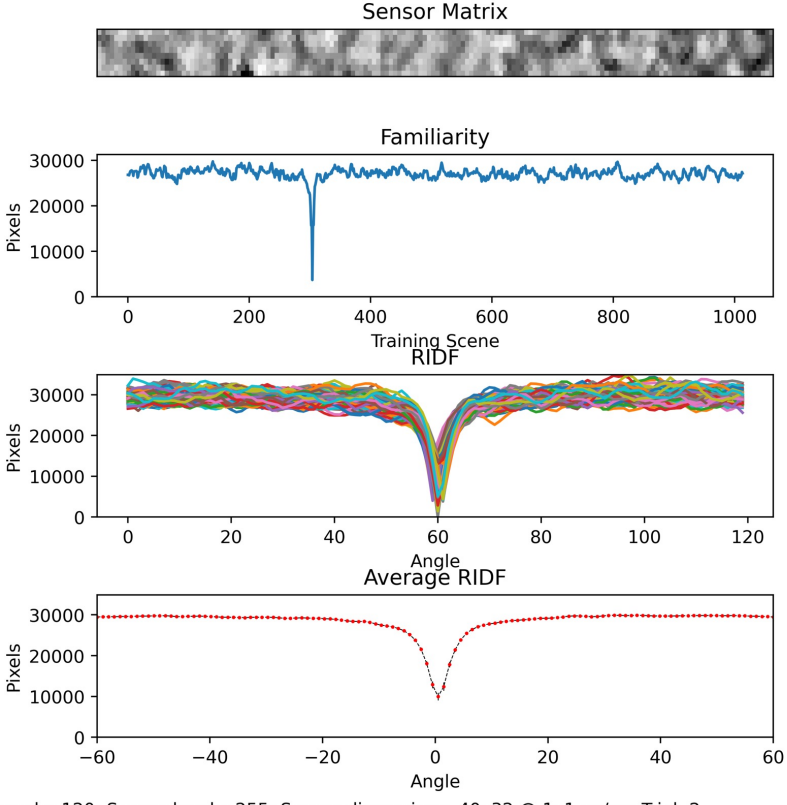




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 44.58; RMSD/dist: 0.111; TD: 16284; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2
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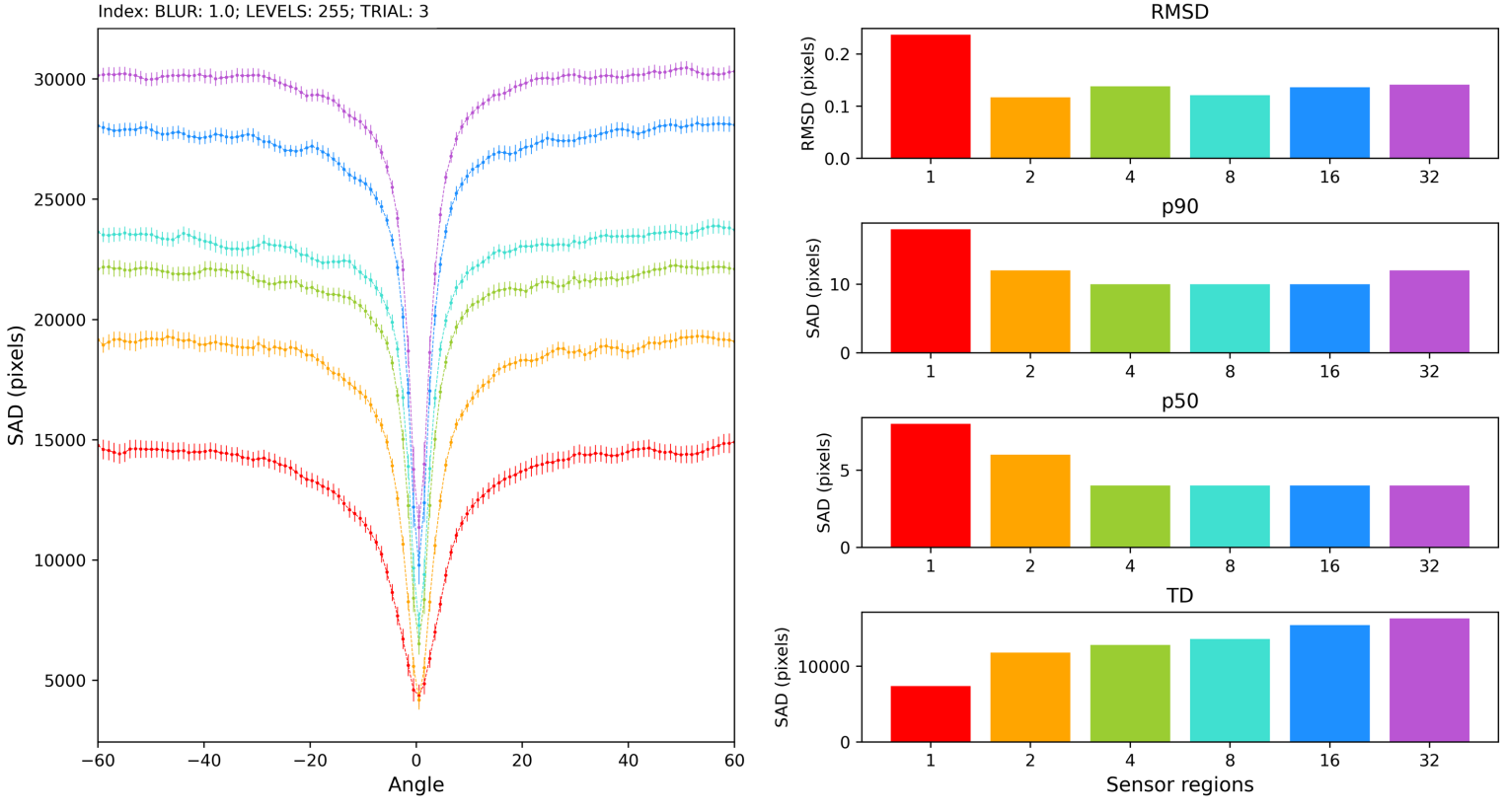
Index: BLUR: 1.0; LEVELS: 255; TRIAL: 3
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25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
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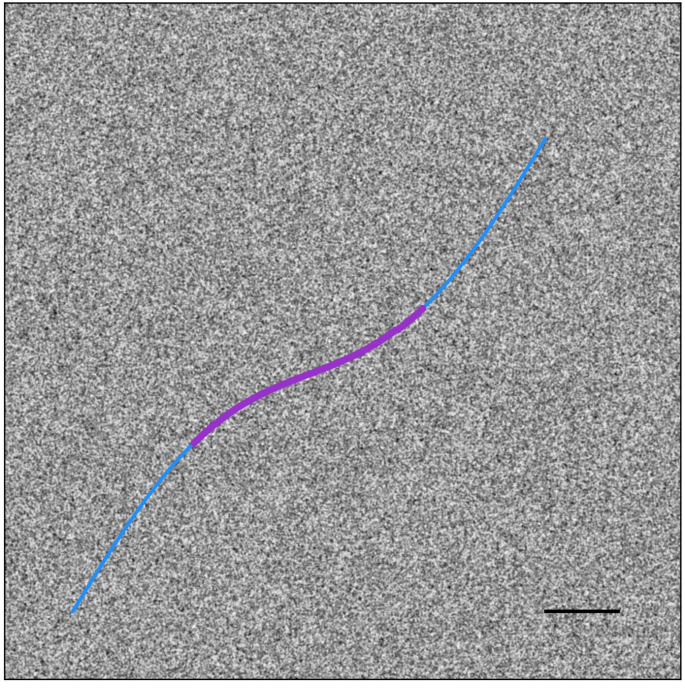
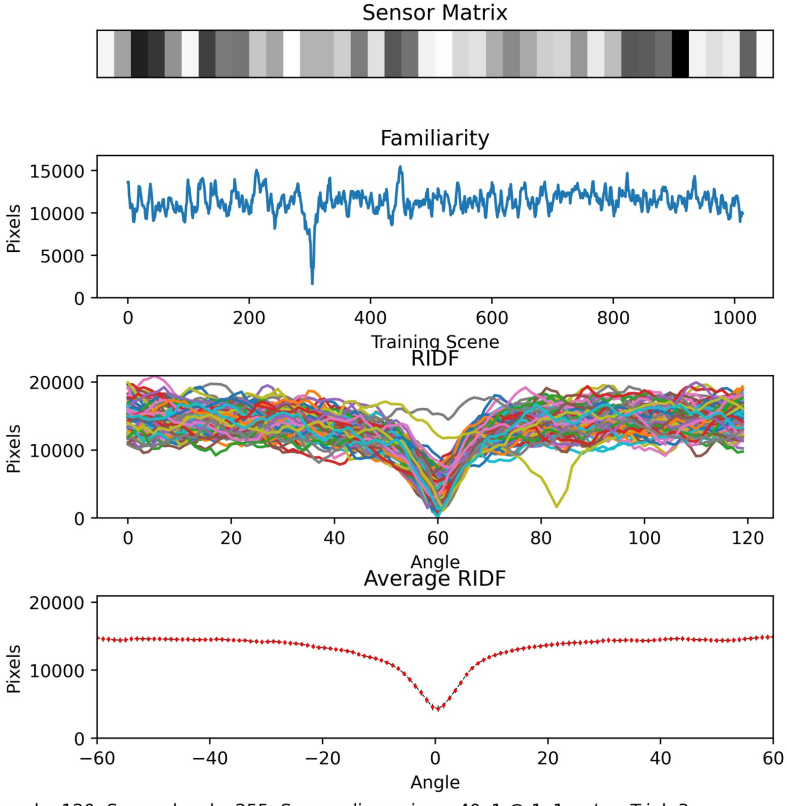
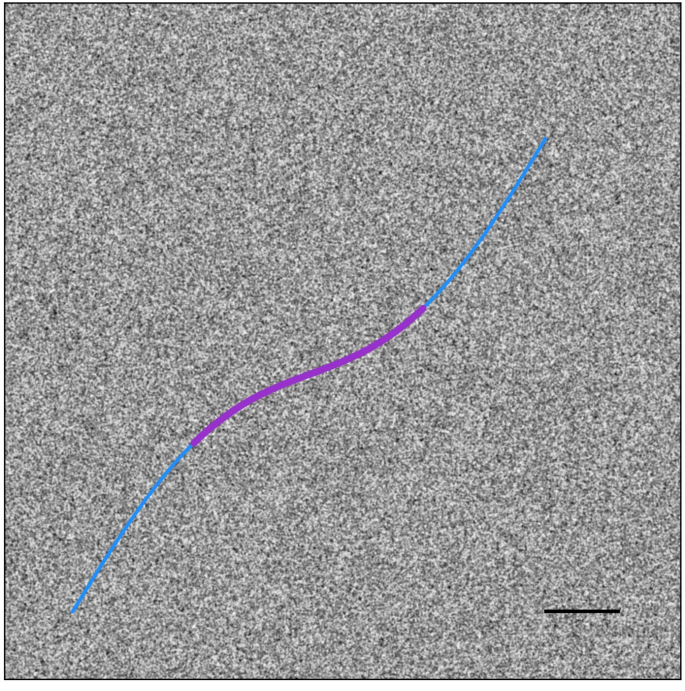
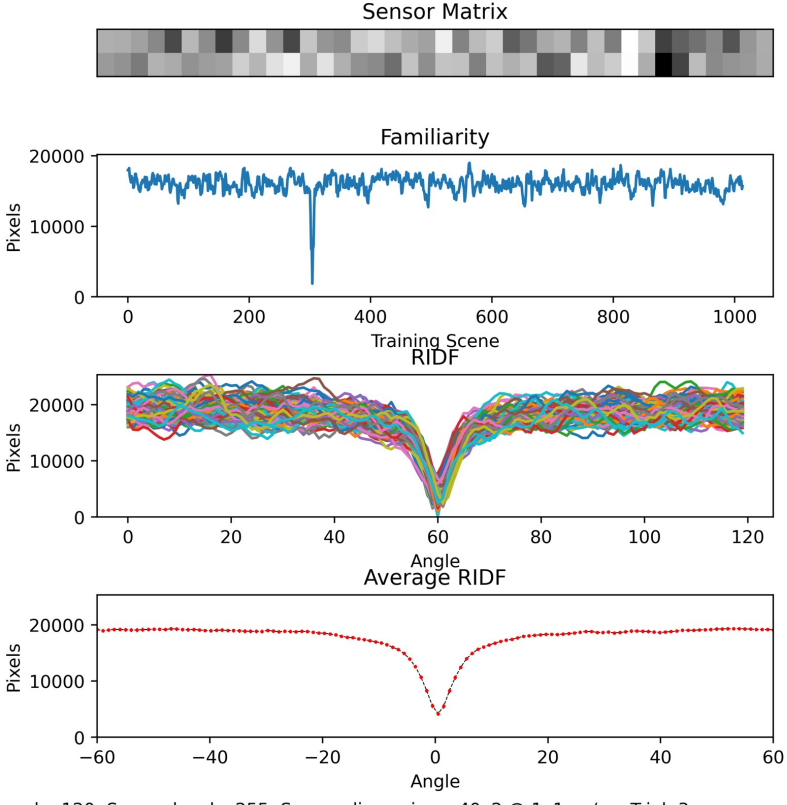
0
TD
SAD (pixels)
10000
0
Sensor regions



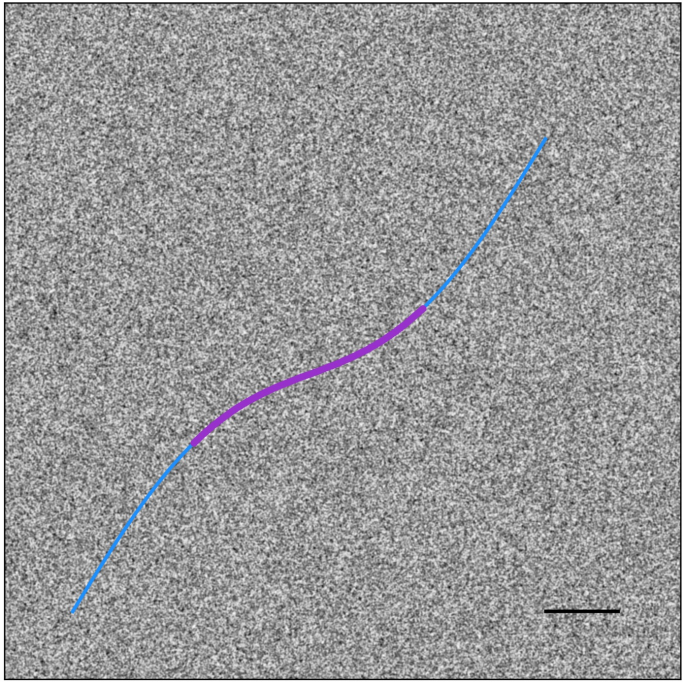


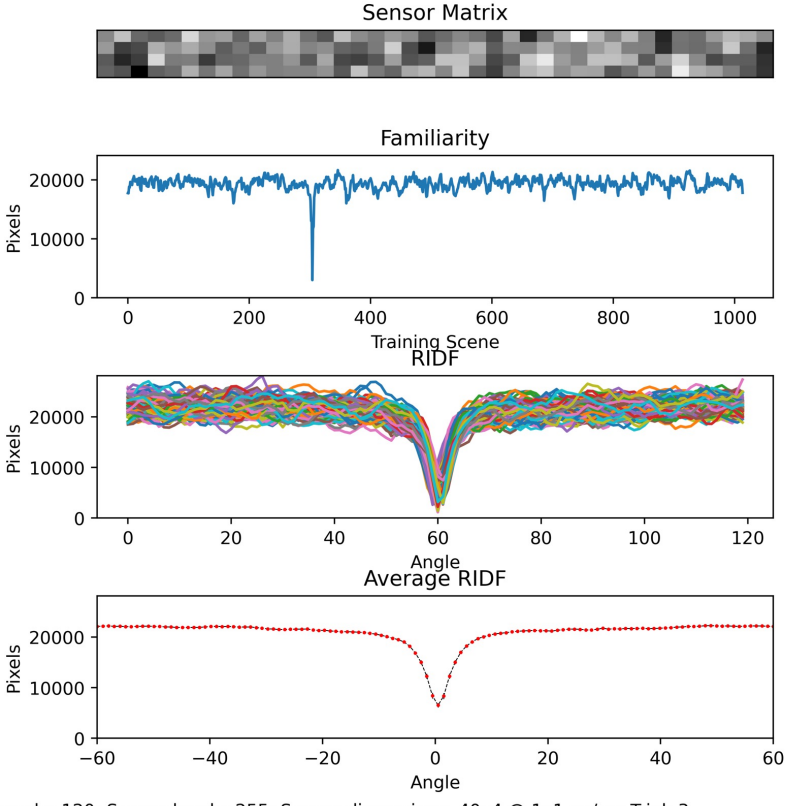
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 94.90; RMSD/dist: 0.237; TD: 7379; p90: 18; p50: 8; complete: 0



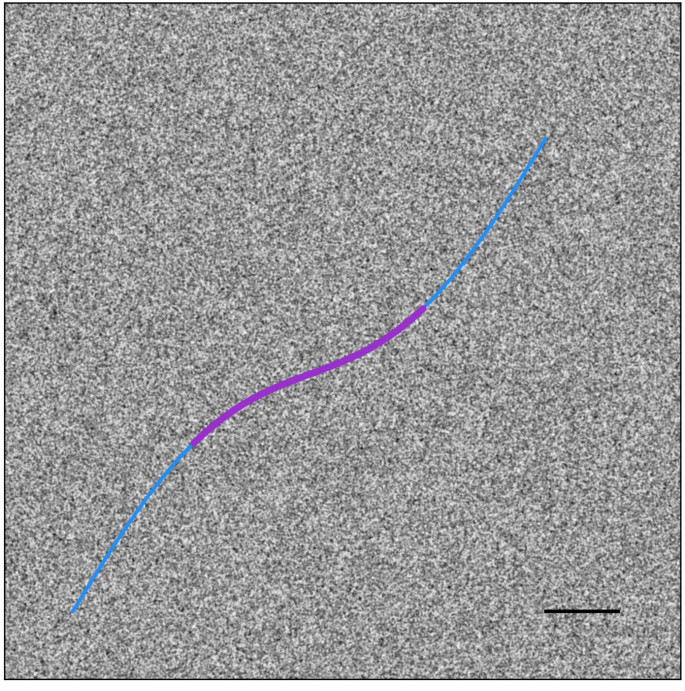


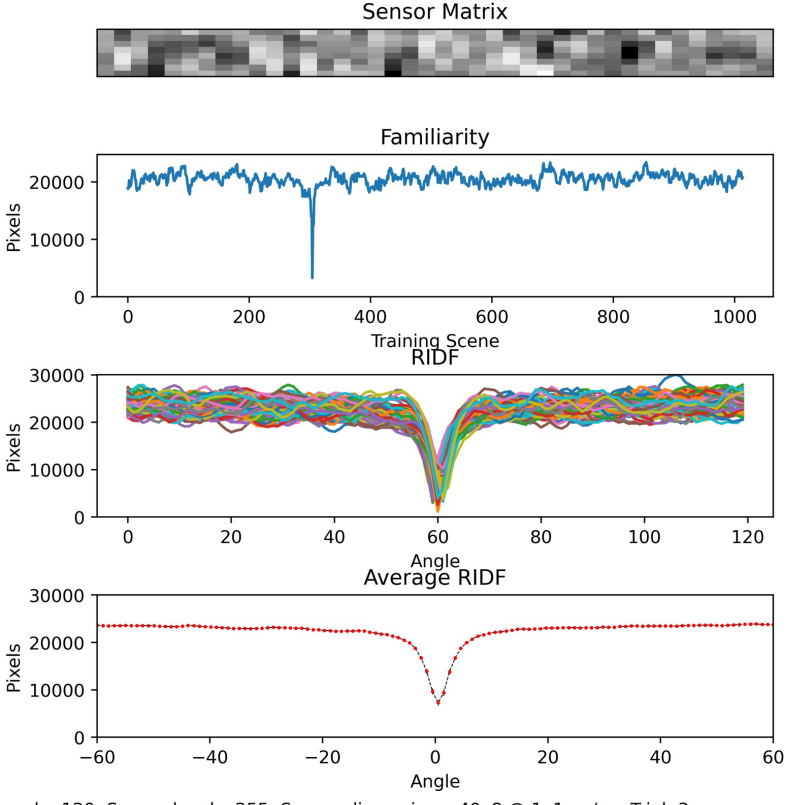
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 46.78; RMSD/dist: 0.117; TD: 11799; p90: 12; p50: 6; complete: 0



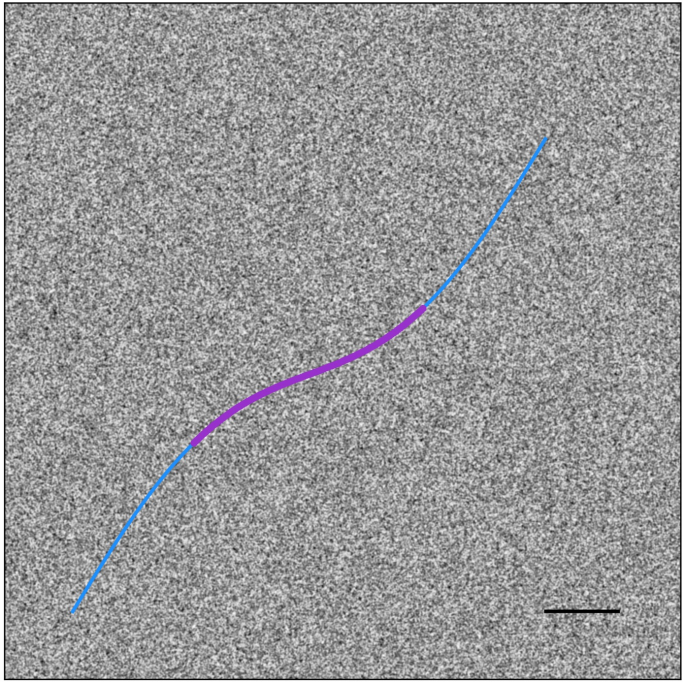


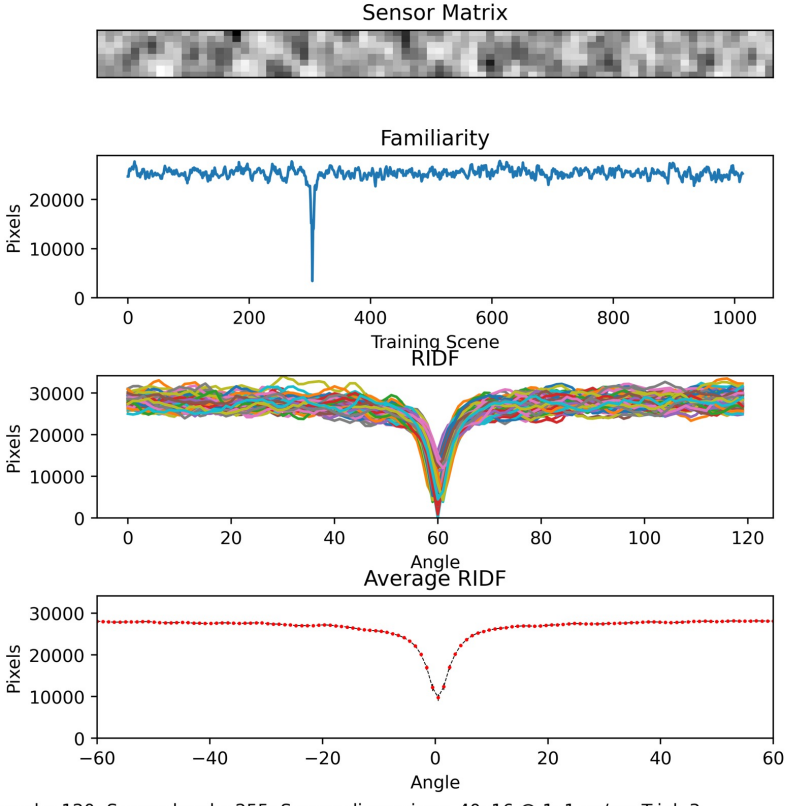
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 55.04; RMSD/dist: 0.138; TD: 12831; p90: 10; p50: 4; complete: 0



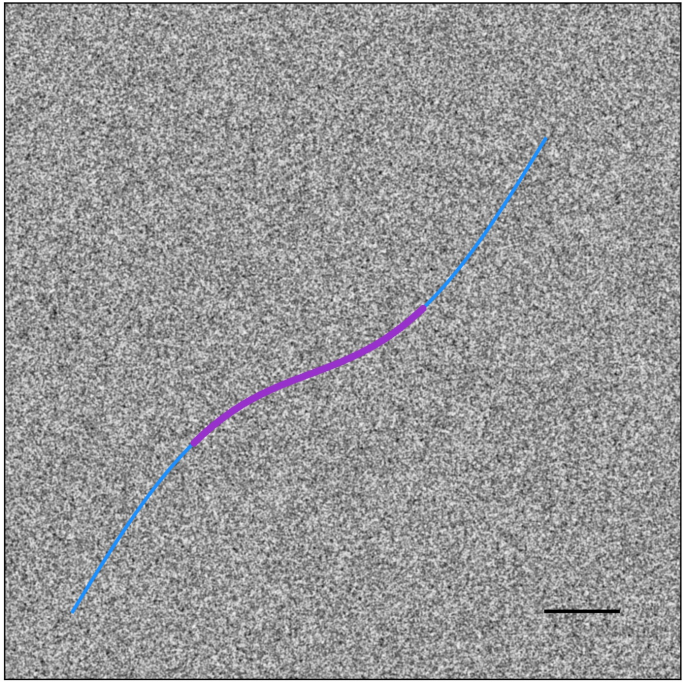


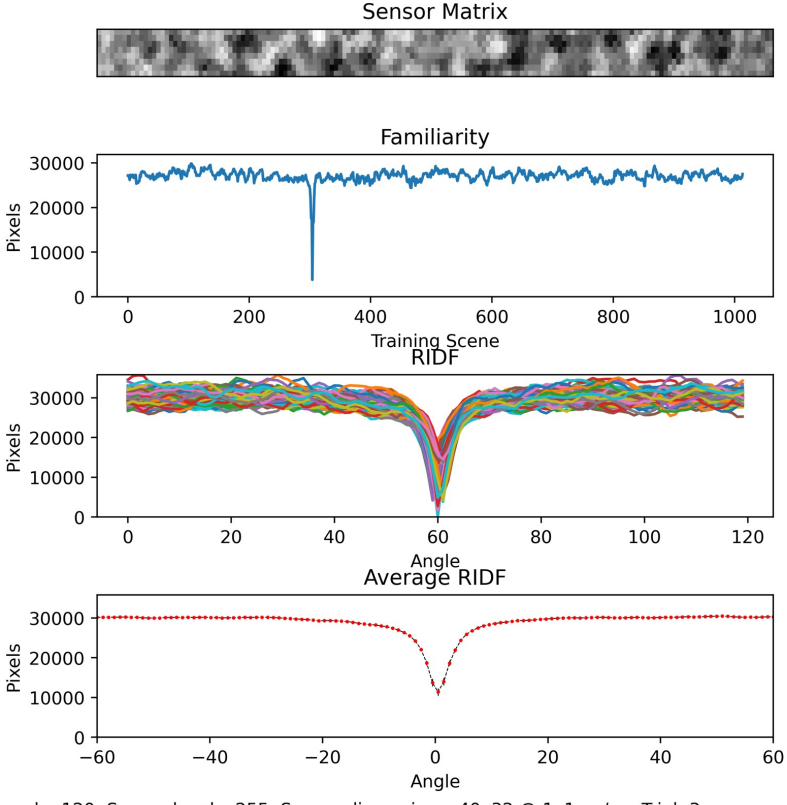
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 48.20; RMSD/dist: 0.121; TD: 13613; p90: 10; p50: 4; complete: 0



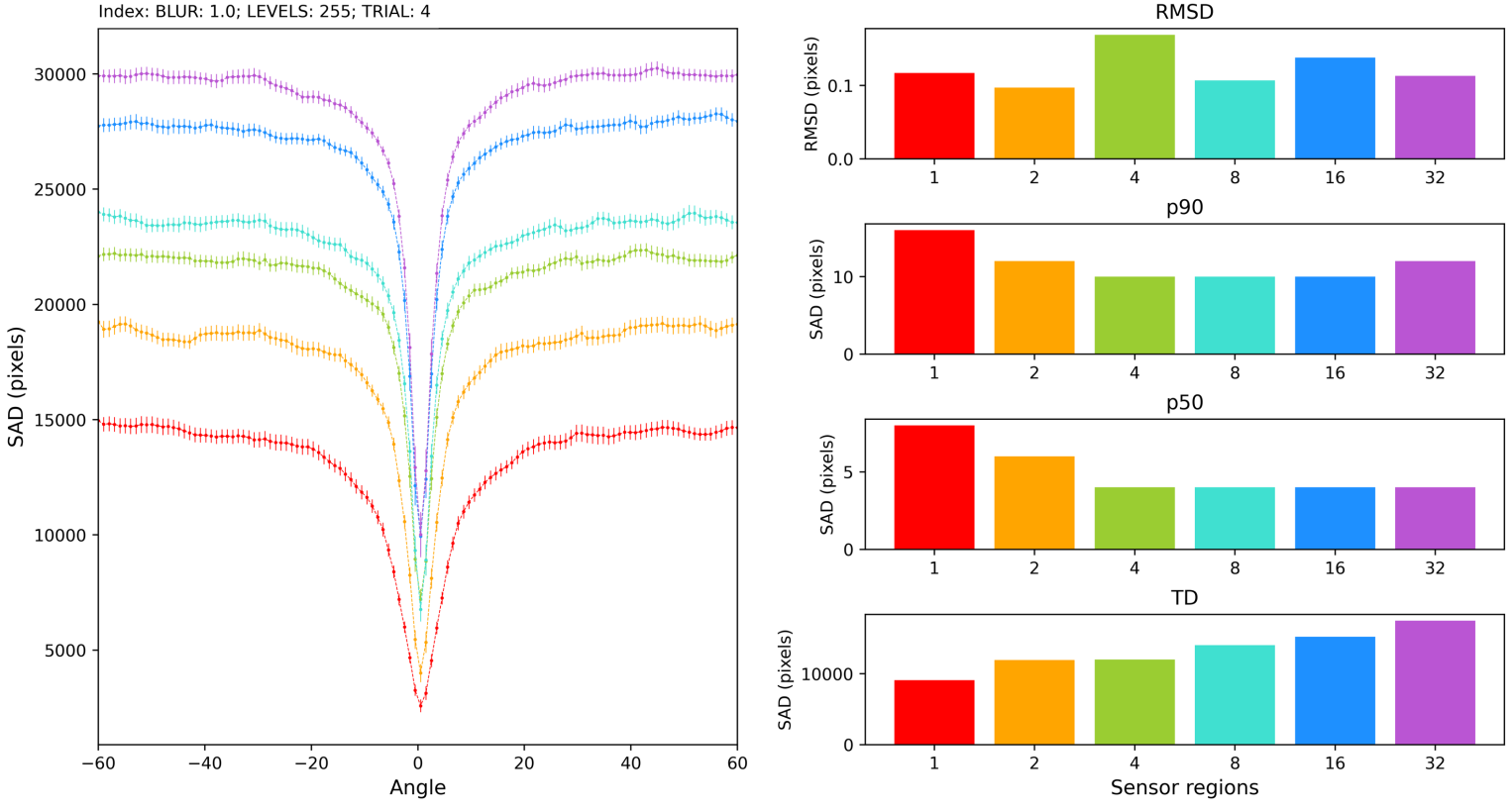


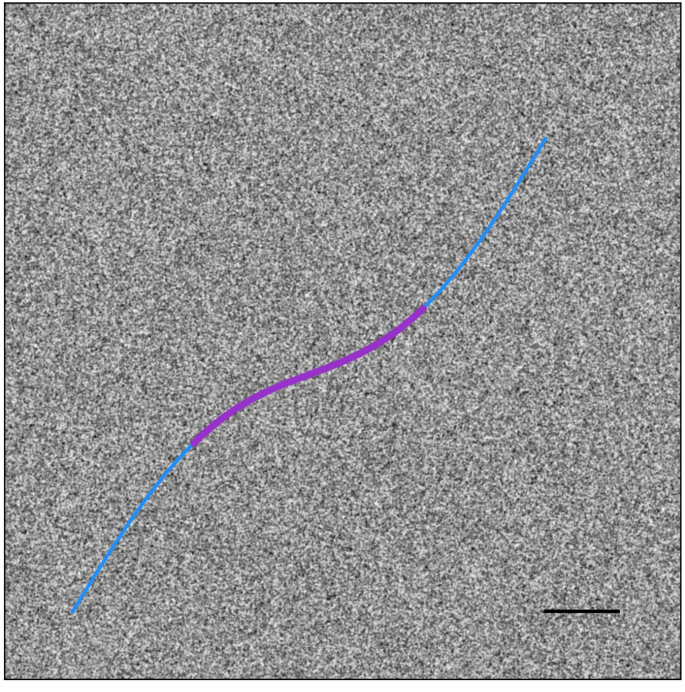
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 54.29; RMSD/dist: 0.136; TD: 15458; p90: 10; p50: 4; complete: 0

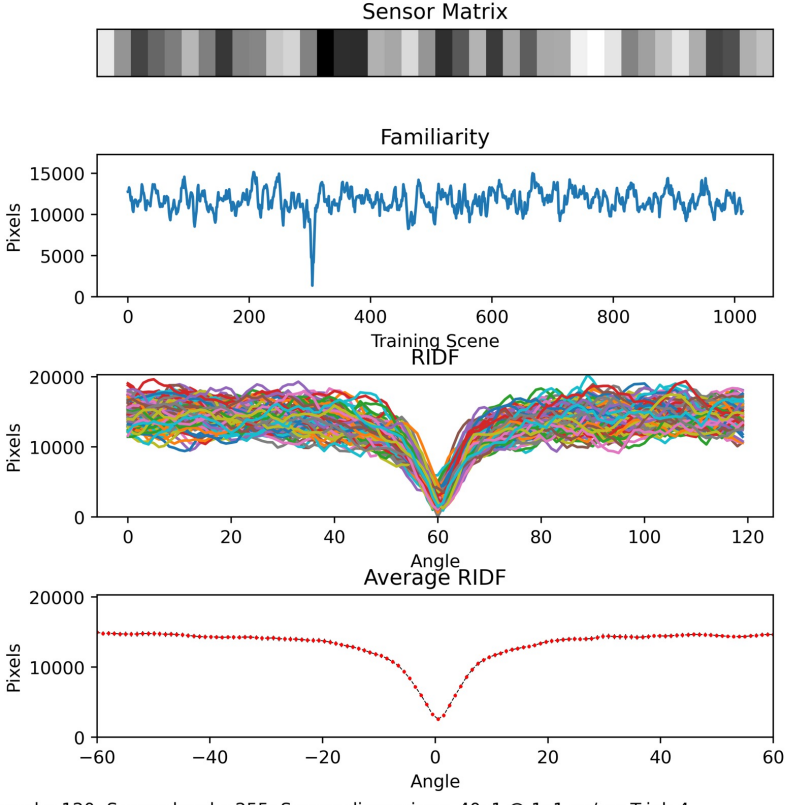




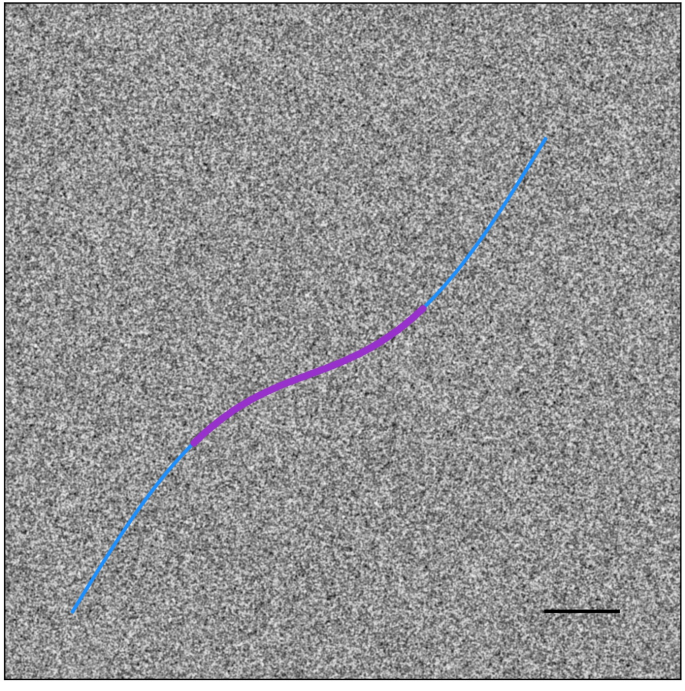
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 56.22; RMSD/dist: 0.141; TD: 16336; p90: 12; p50: 4; complete: 0

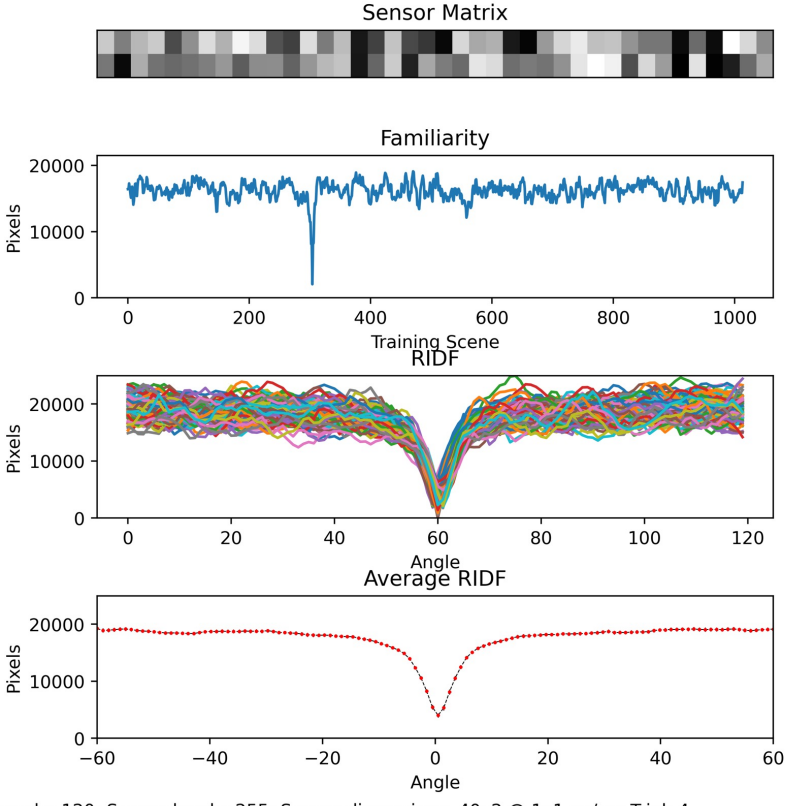

Index: BLUR: 1.0; LEVELS: 255; TRIAL: 4
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
1
2
4
8
16
32
Sensor regions



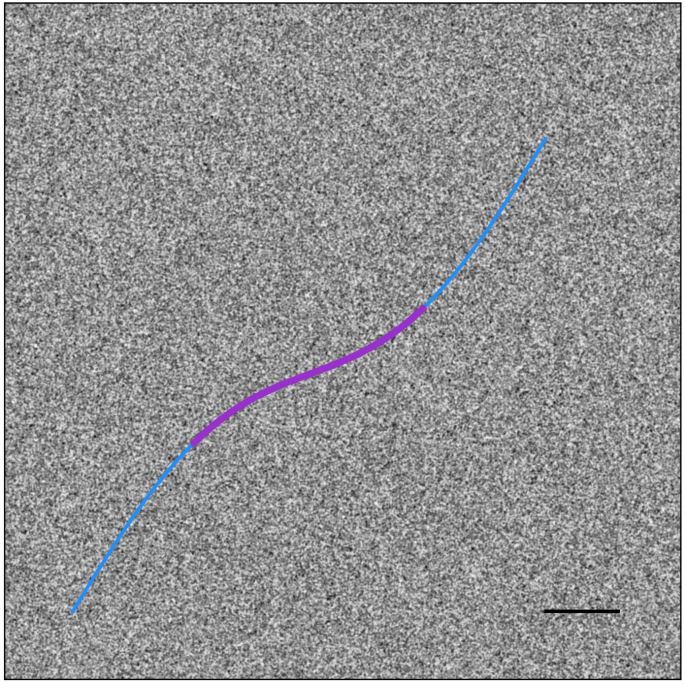


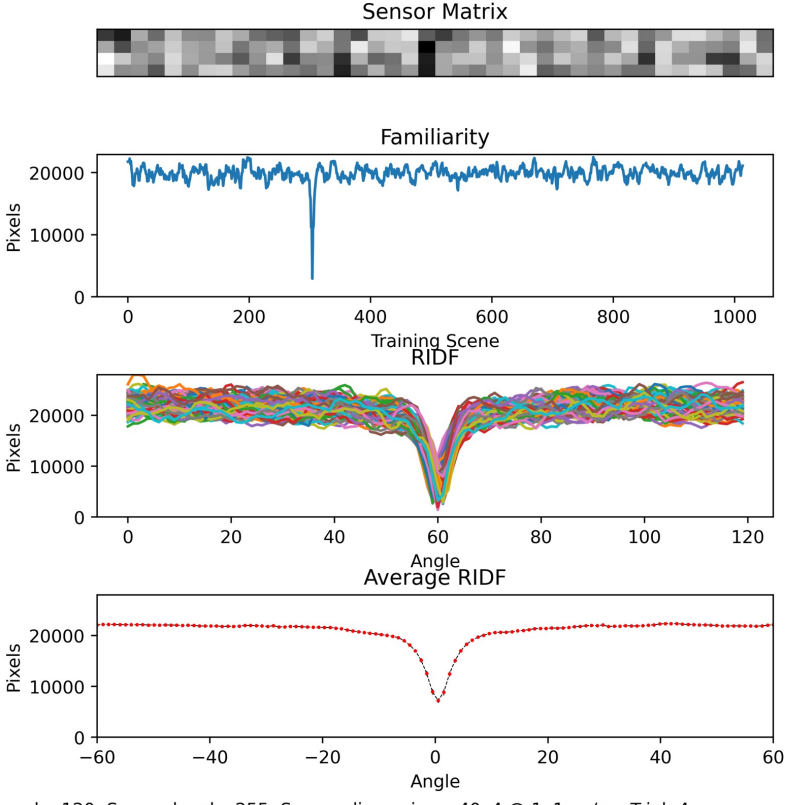
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 46.98; RMSD/dist: 0.117; TD: 9077; p90: 16; p50: 8; complete: 0



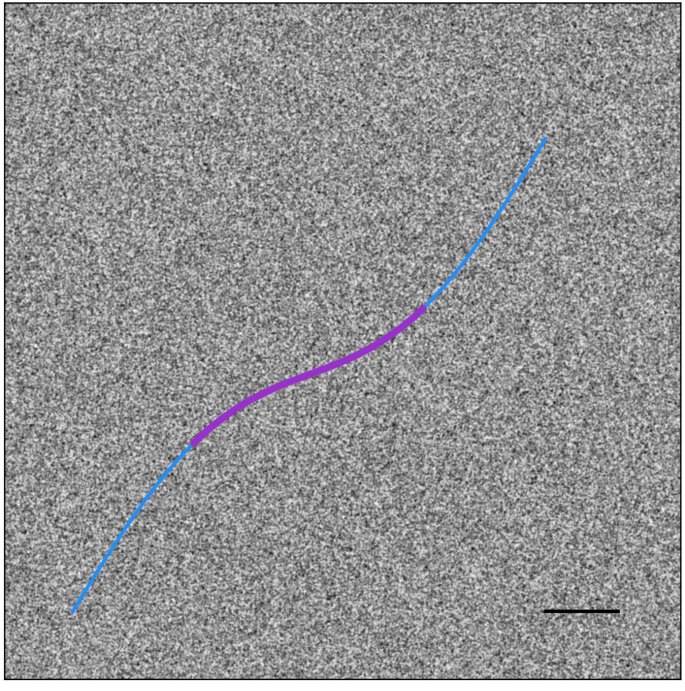


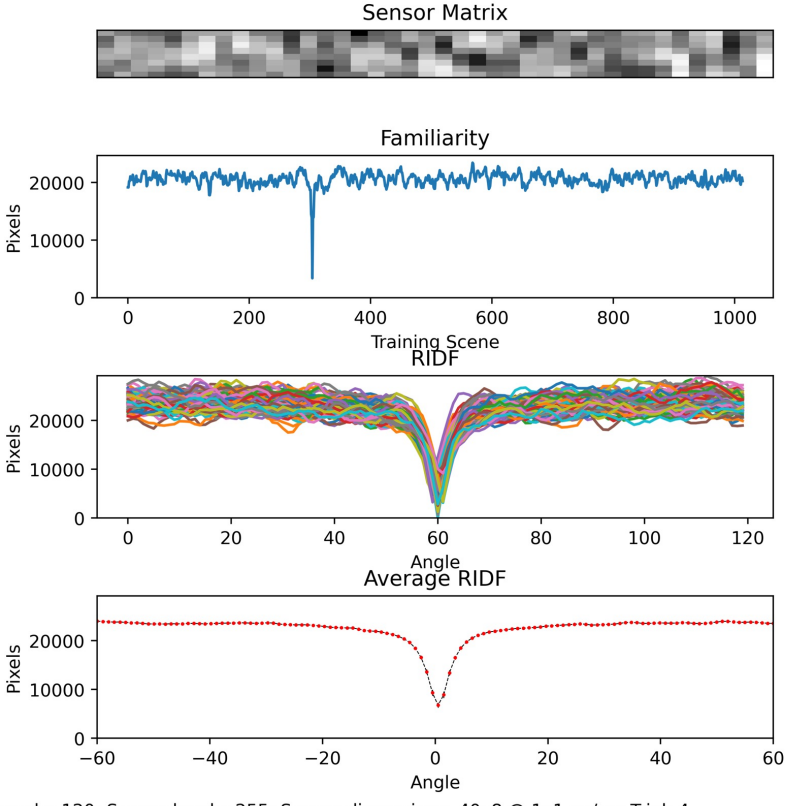
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 38.87; RMSD/dist: 0.097; TD: 11950; p90: 12; p50: 6; complete: 0



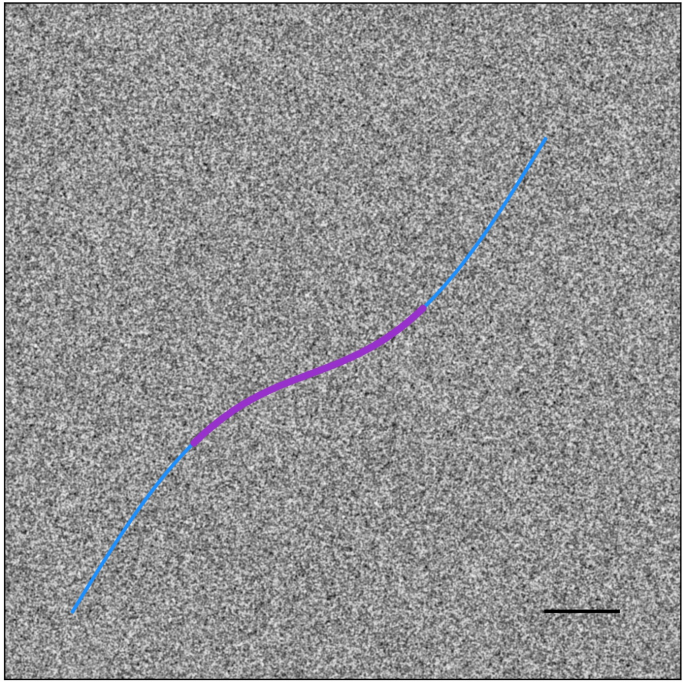


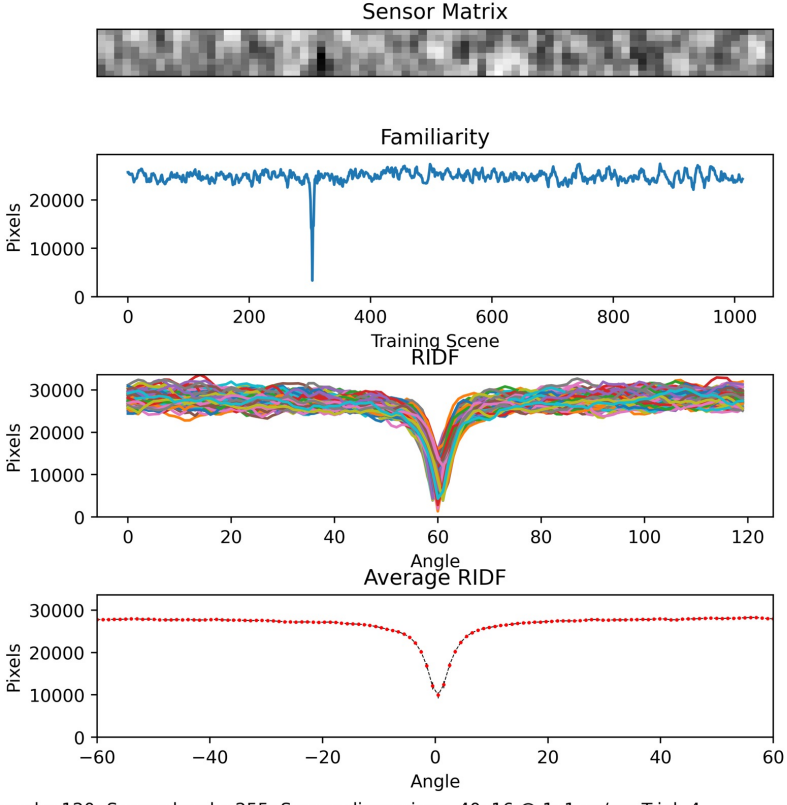
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 67.67; RMSD/dist: 0.169; TD: 11989; p90: 10; p50: 4; complete: 0



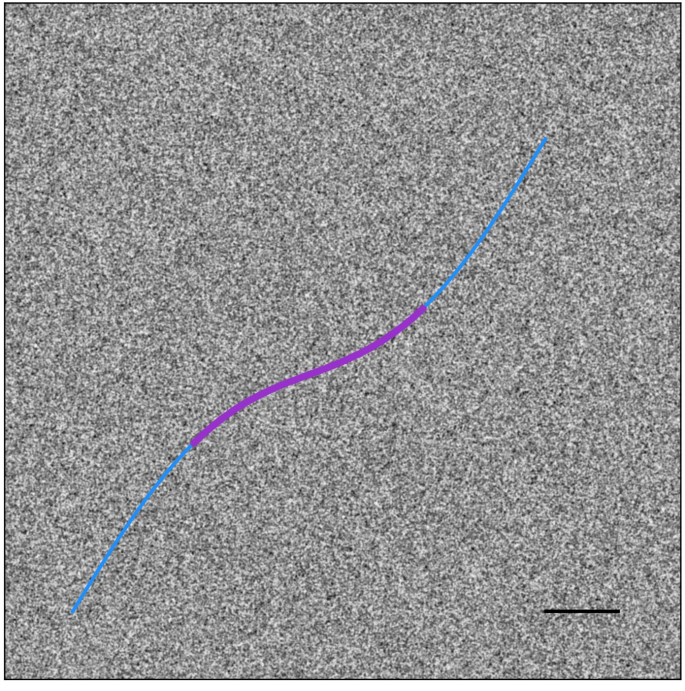


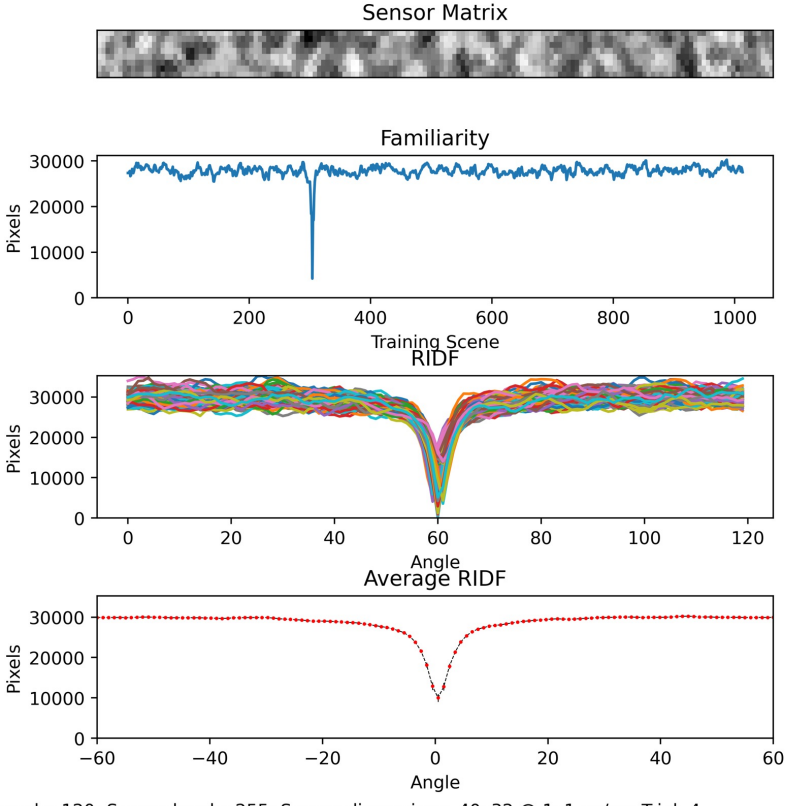
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 42.64; RMSD/dist: 0.107; TD: 14025; p90: 10; p50: 4; complete: 0



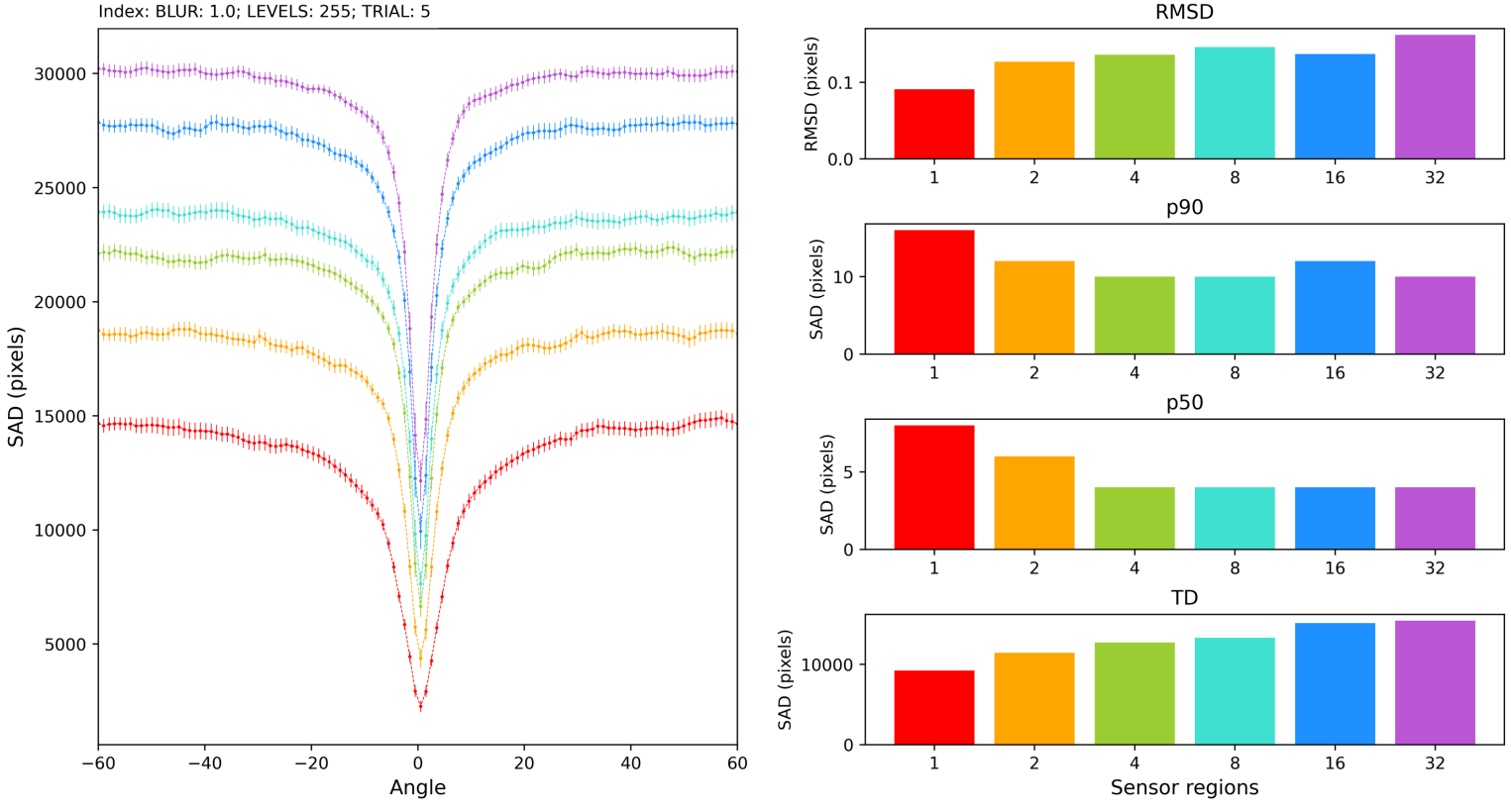


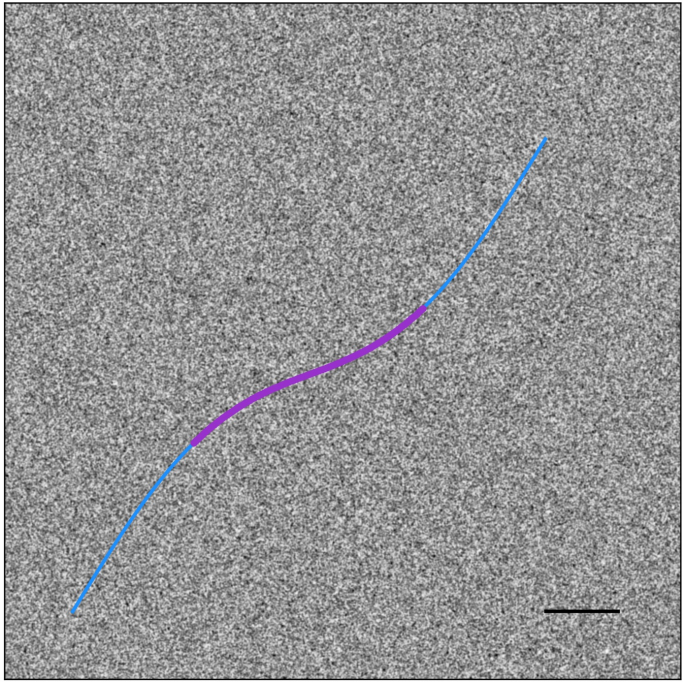
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 55.16; RMSD/dist: 0.138; TD: 15202; p90: 10; p50: 4; complete: 0

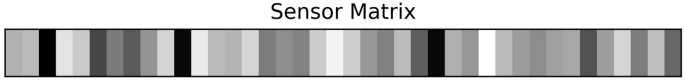


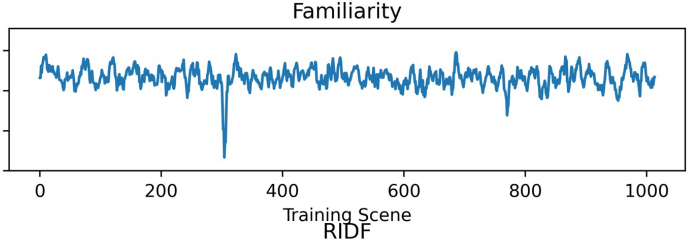


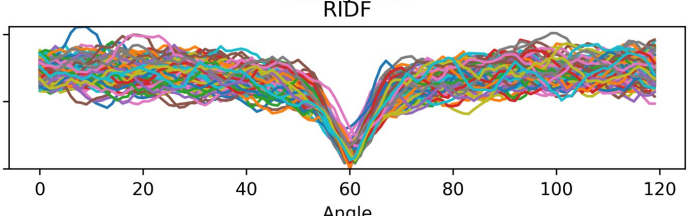
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 45.24; RMSD/dist: 0.113; TD: 17490; p90: 12; p50: 4; complete: 0

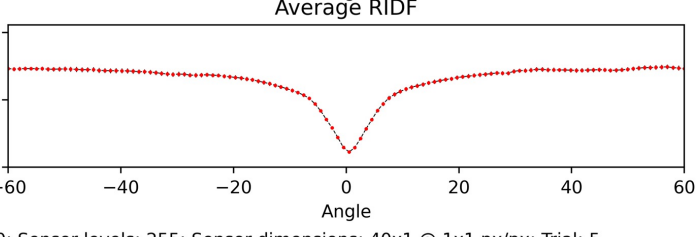

Index: BLUR: 1.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
Sensor regions



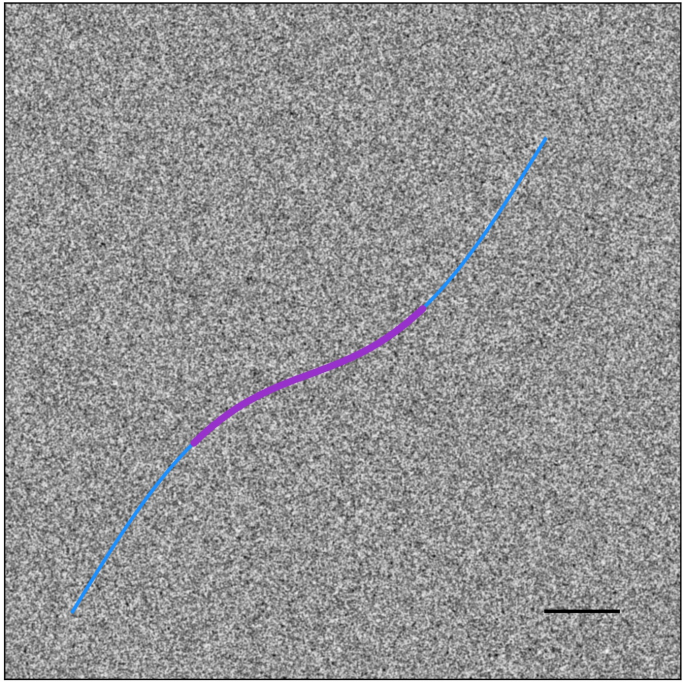


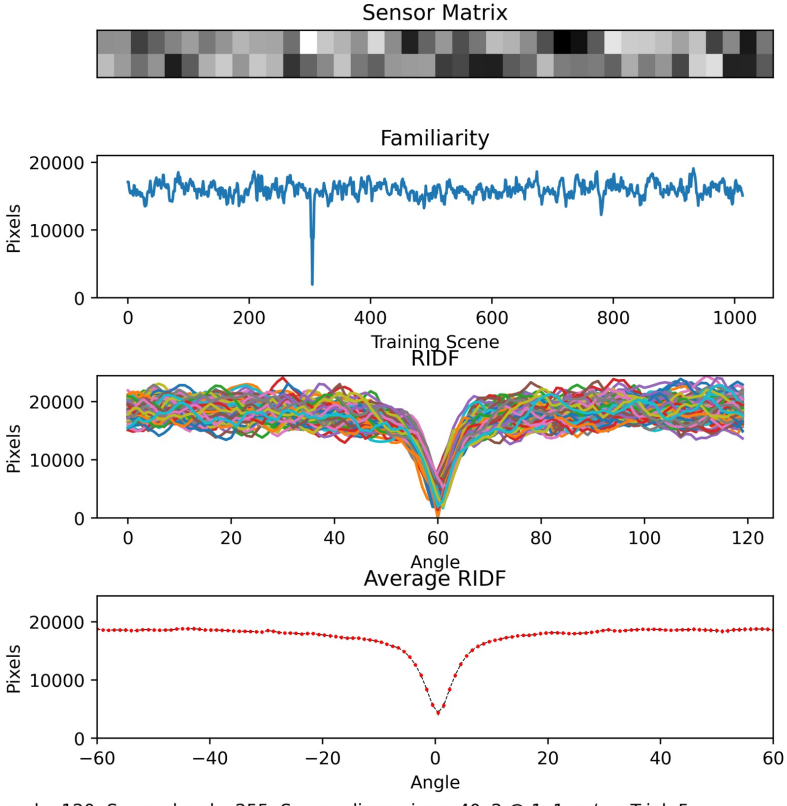




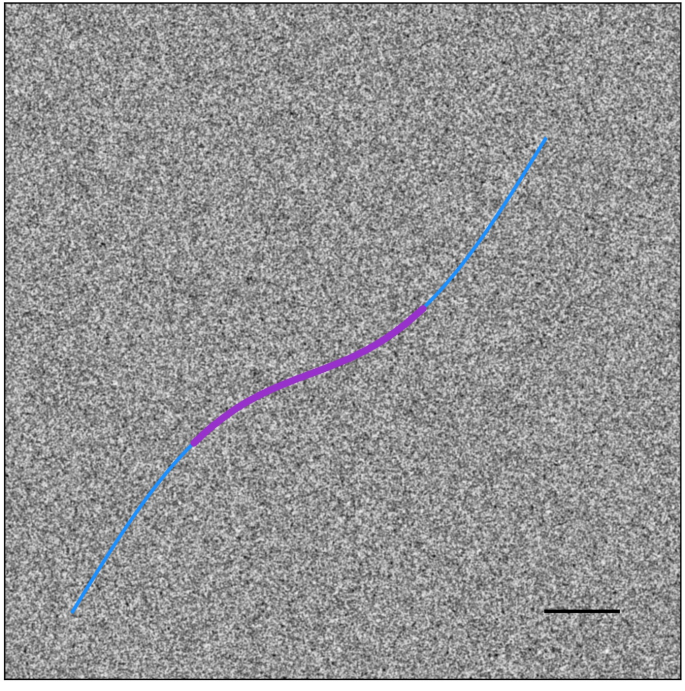


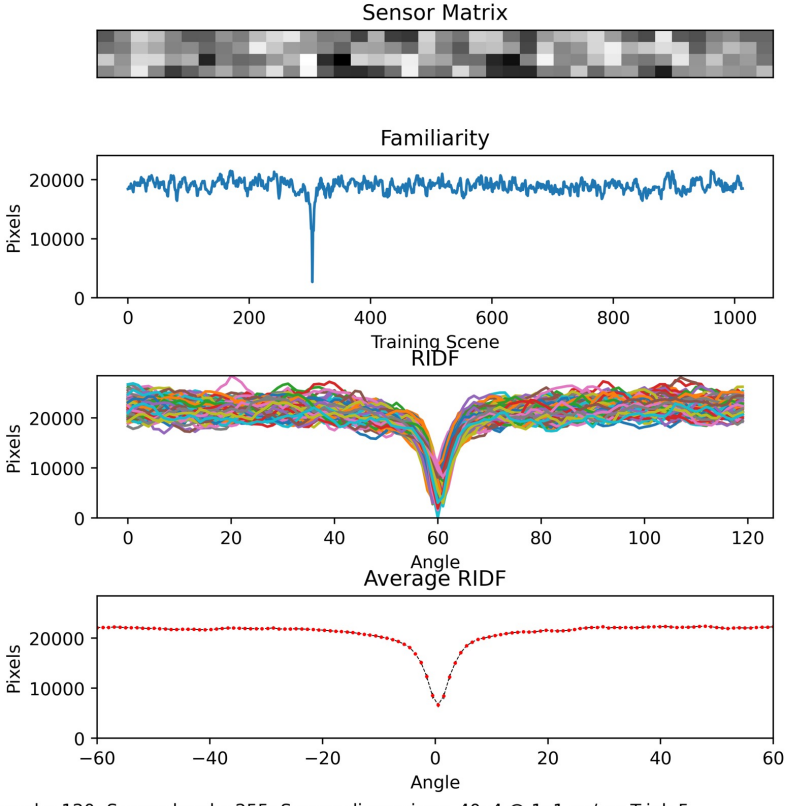
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 36.44; RMSD/dist: 0.091; TD: 9227; p90: 16; p50: 8; complete: 0



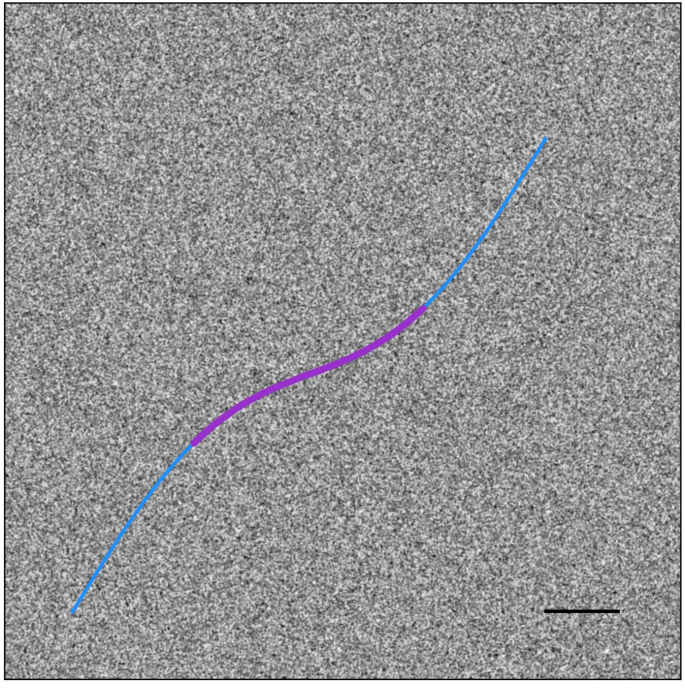


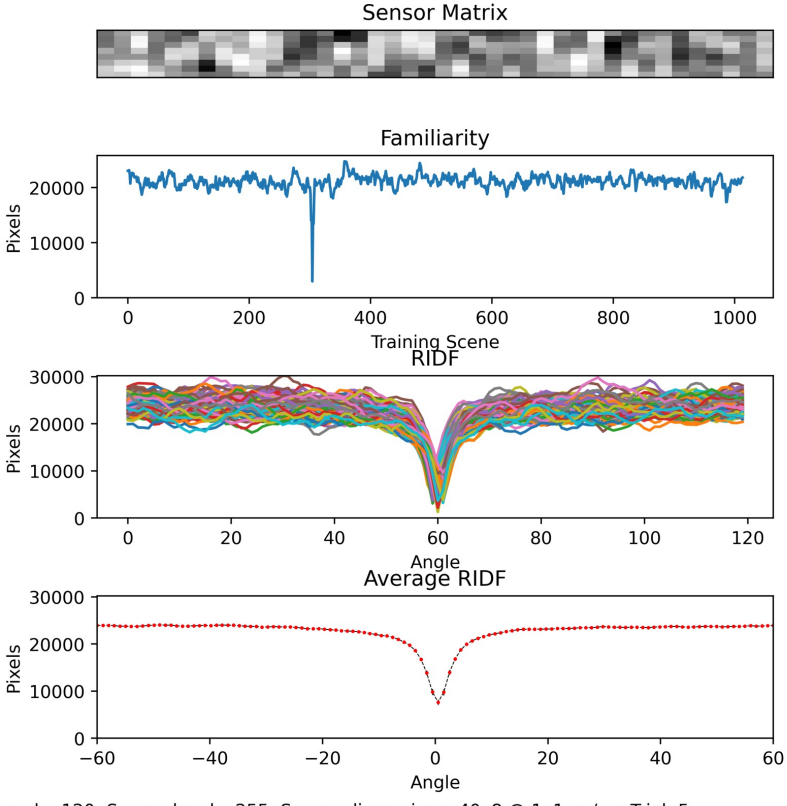
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 50.80; RMSD/dist: 0.127; TD: 11439; p90: 12; p50: 6; complete: 0



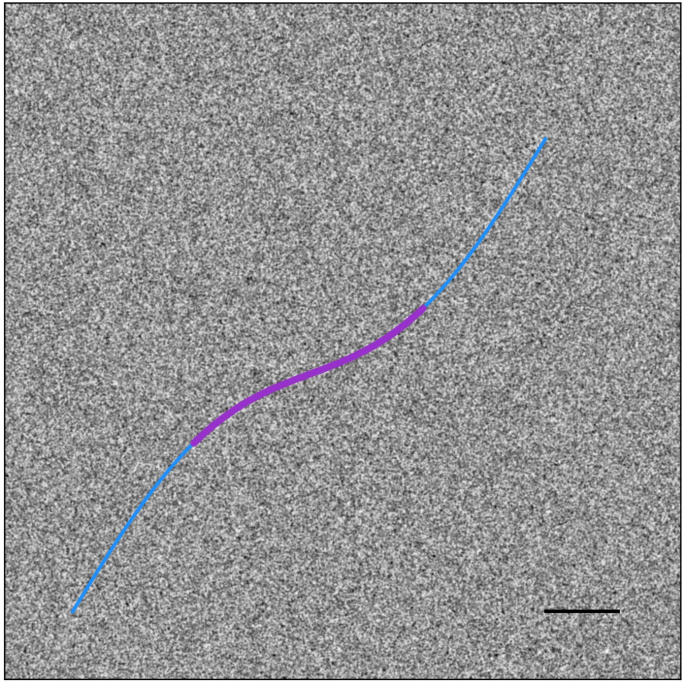


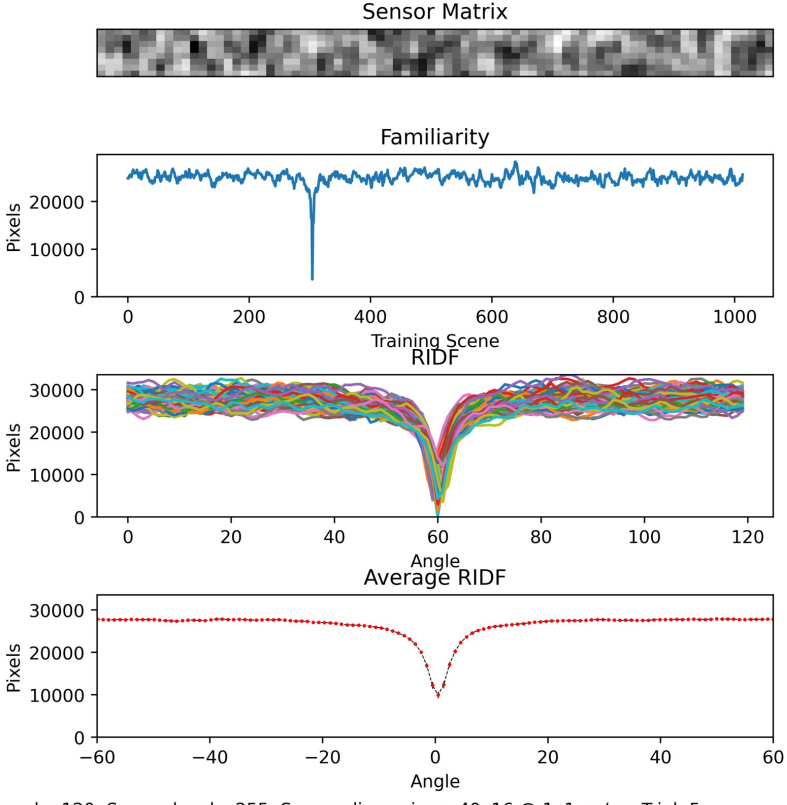
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 54.49; RMSD/dist: 0.136; TD: 12733; p90: 10; p50: 4; complete: 0



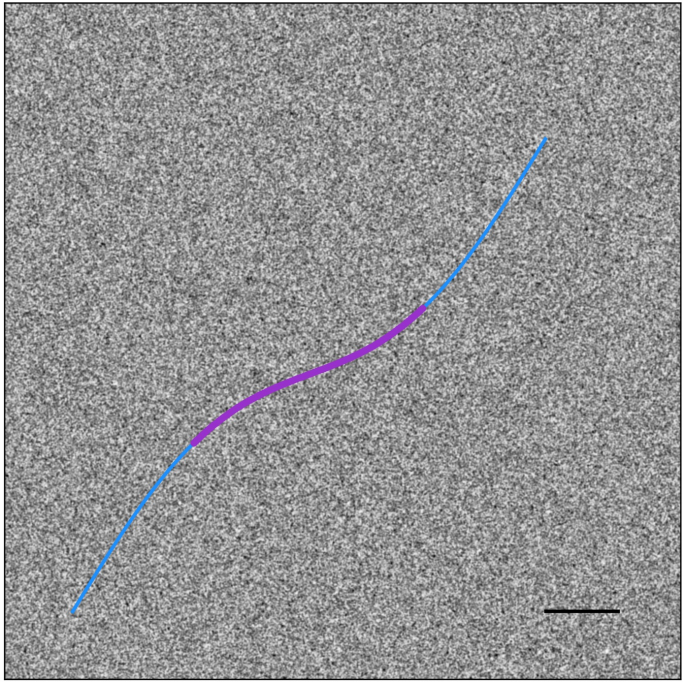


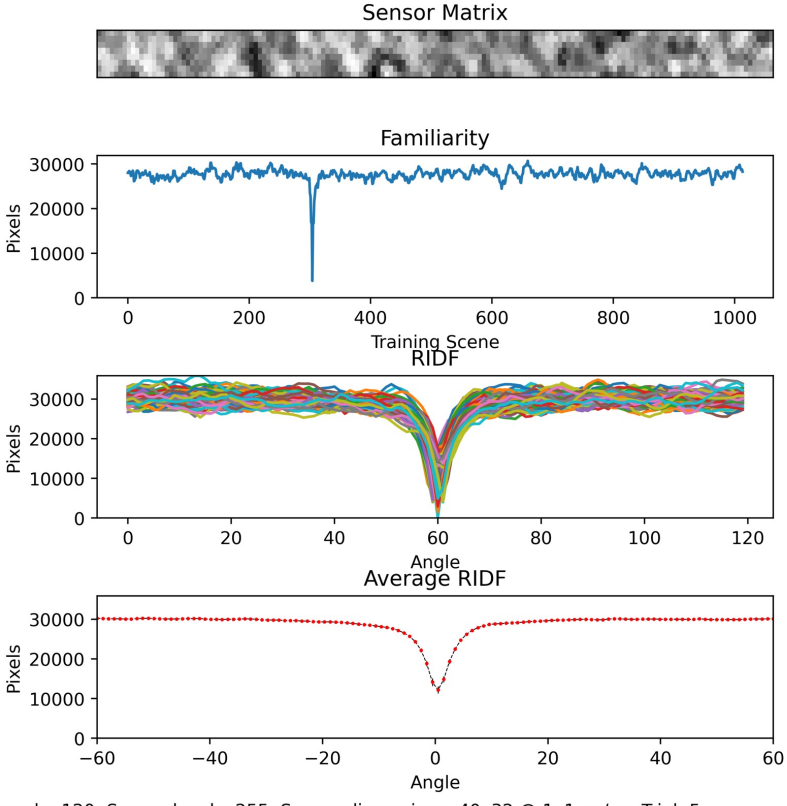
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 58.37; RMSD/dist: 0.146; TD: 13322; p90: 10; p50: 4; complete: 0



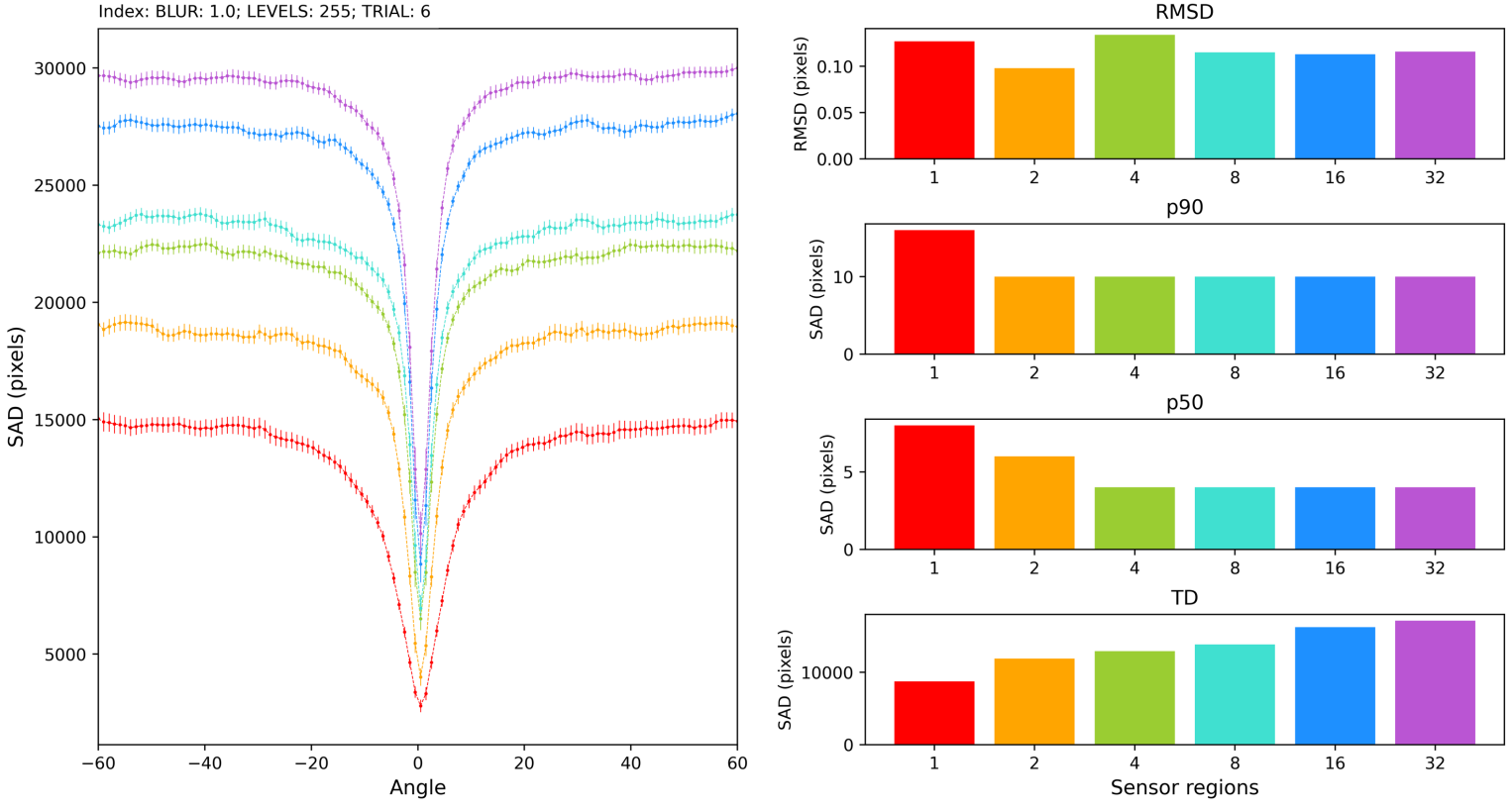


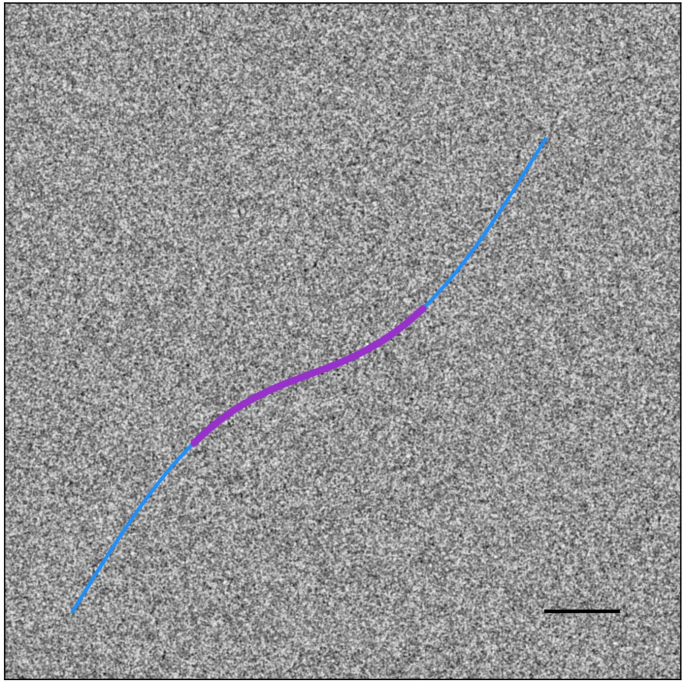
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 54.90; RMSD/dist: 0.137; TD: 15148; p90: 12; p50: 4; complete: 0

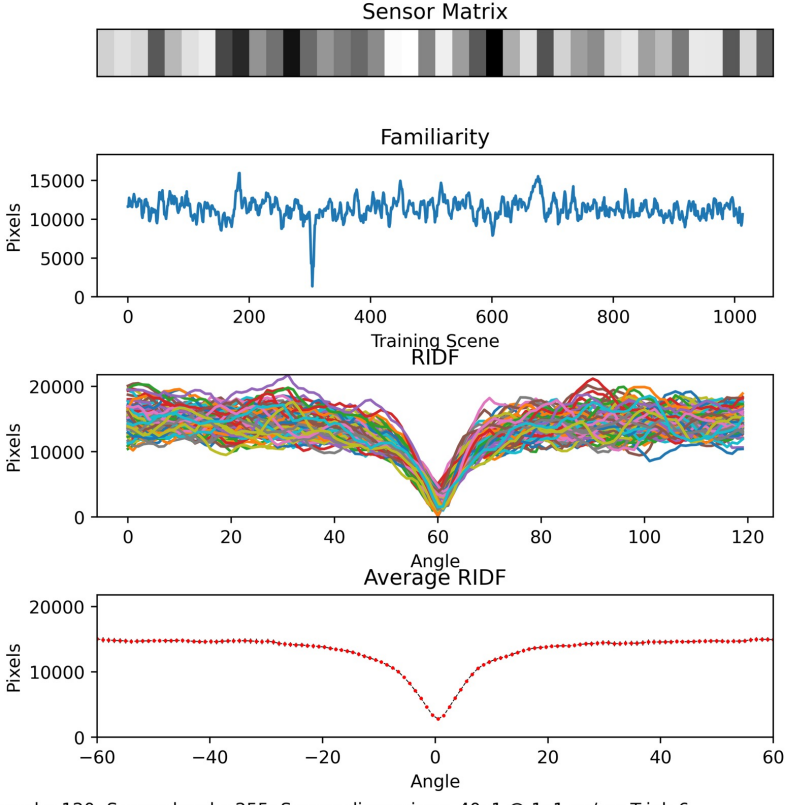




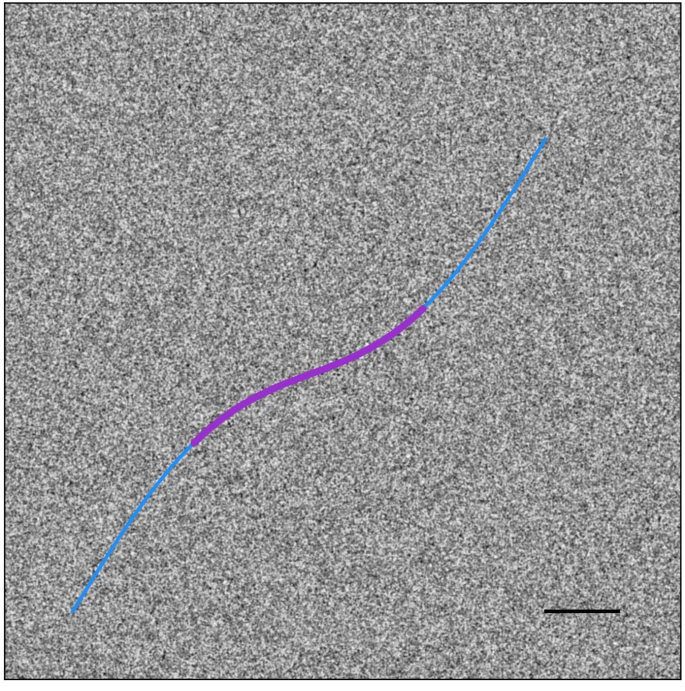
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 64.66; RMSD/dist: 0.162; TD: 15457; p90: 10; p50: 4; complete: 0

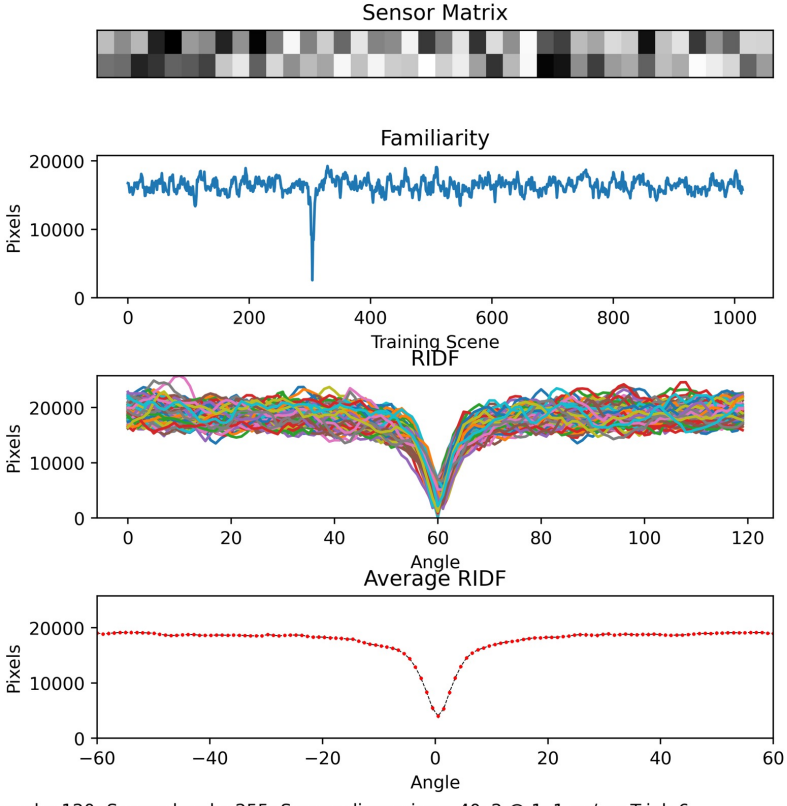

Index: BLUR: 1.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
Sensor regions





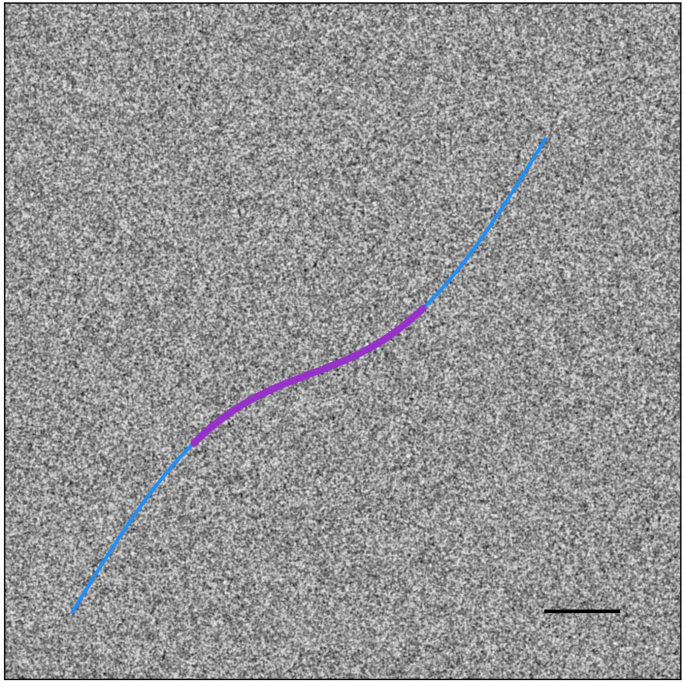
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 50.93; RMSD/dist: 0.127; TD: 8757; p90: 16; p50: 8; complete: 0

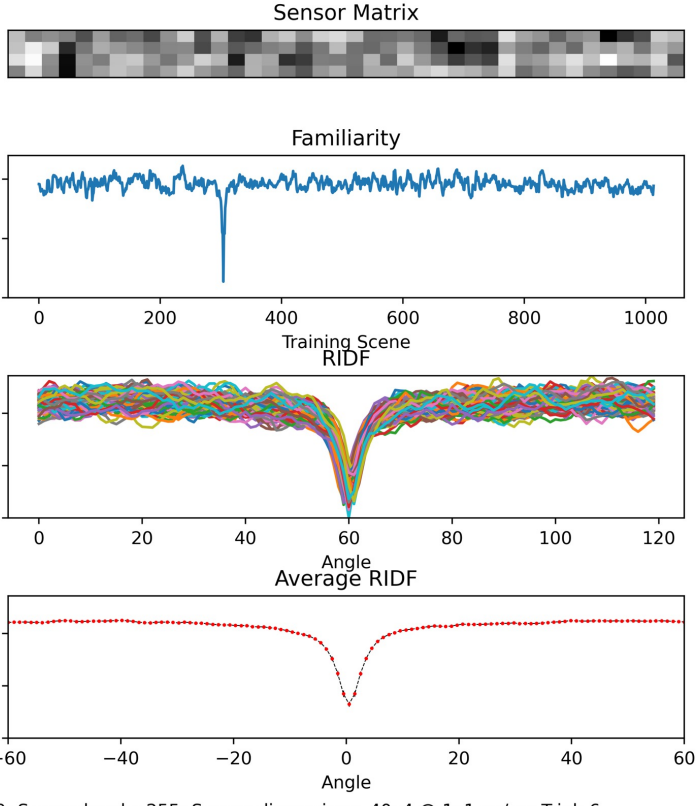




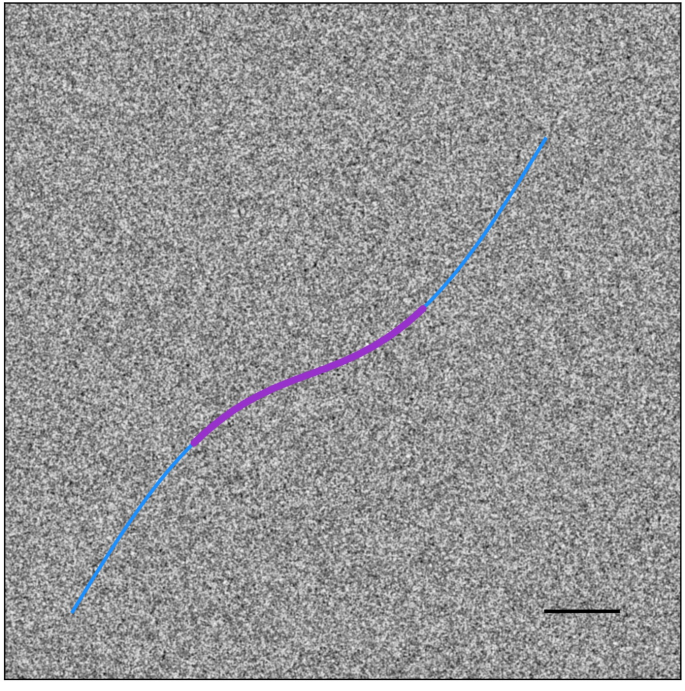
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

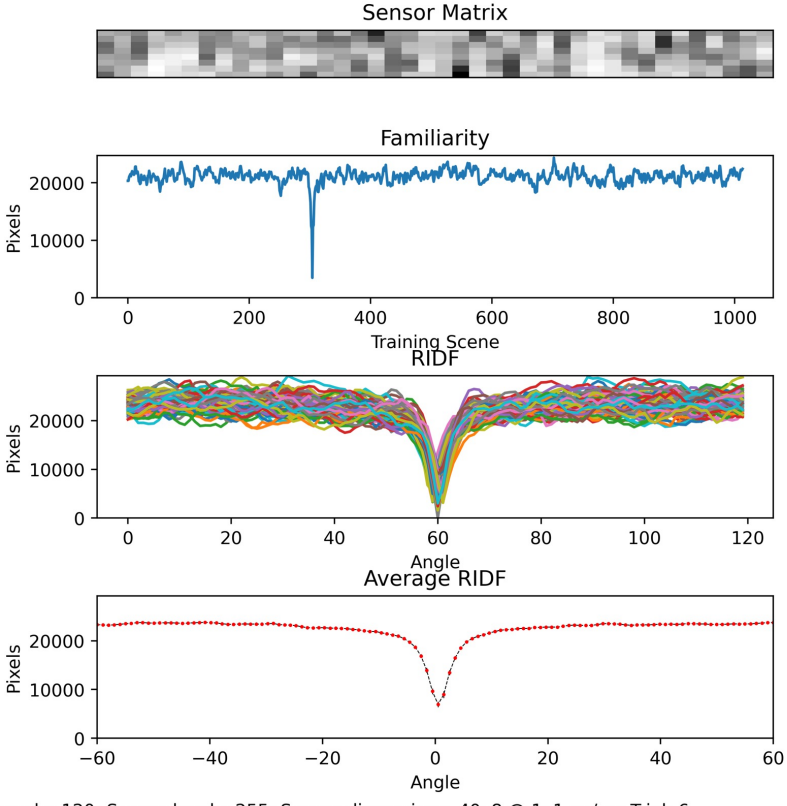
Navigation stats: RMSD error: 39.19; RMSD/dist: 0.098; TD: 11887; p90: 10; p50: 6; complete: 0



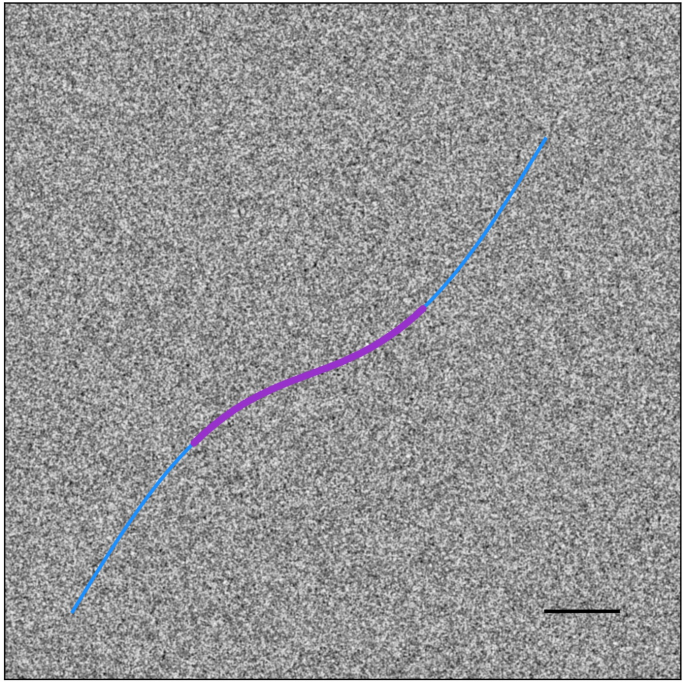


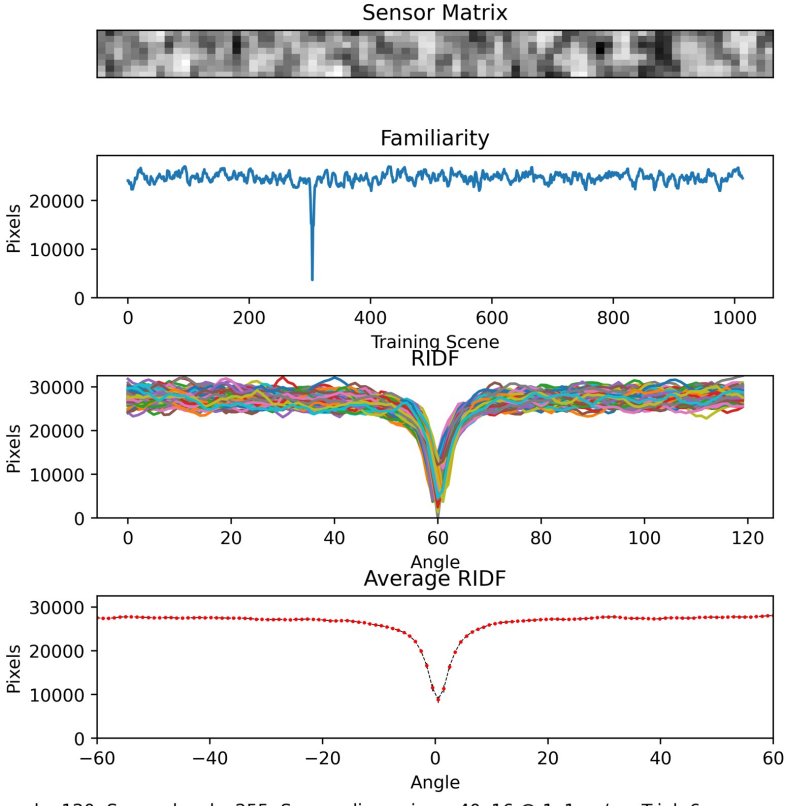
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 53.55; RMSD/dist: 0.134; TD: 12916; p90: 10; p50: 4; complete: 0



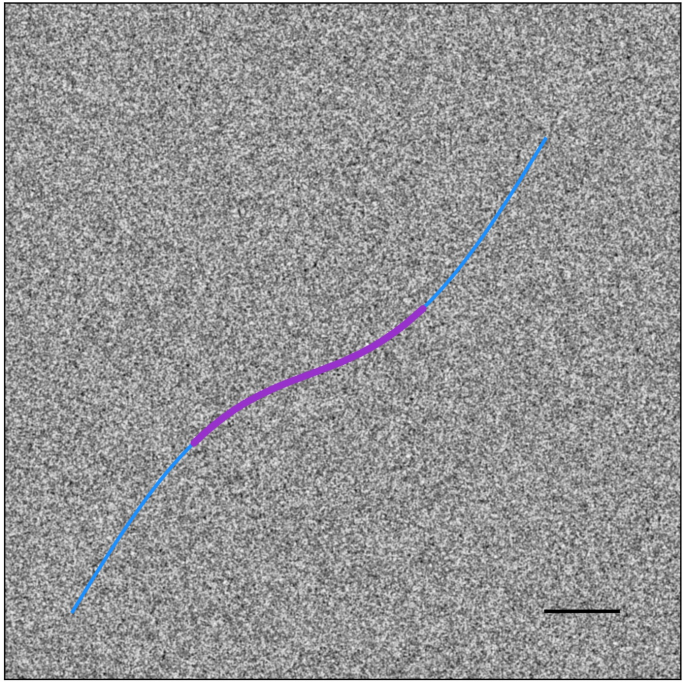


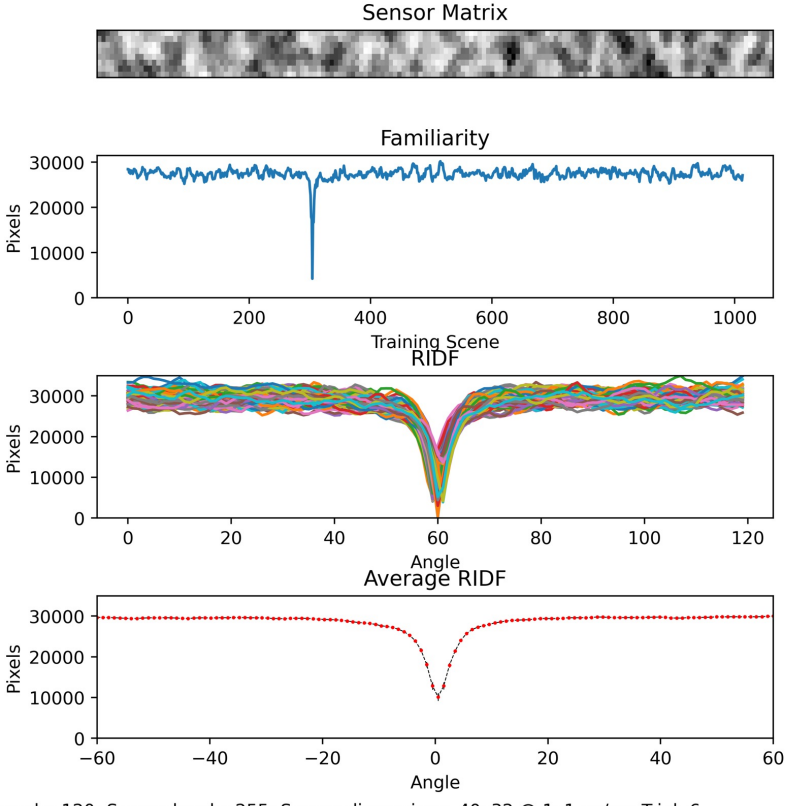
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 46.04; RMSD/dist: 0.115; TD: 13861; p90: 10; p50: 4; complete: 0



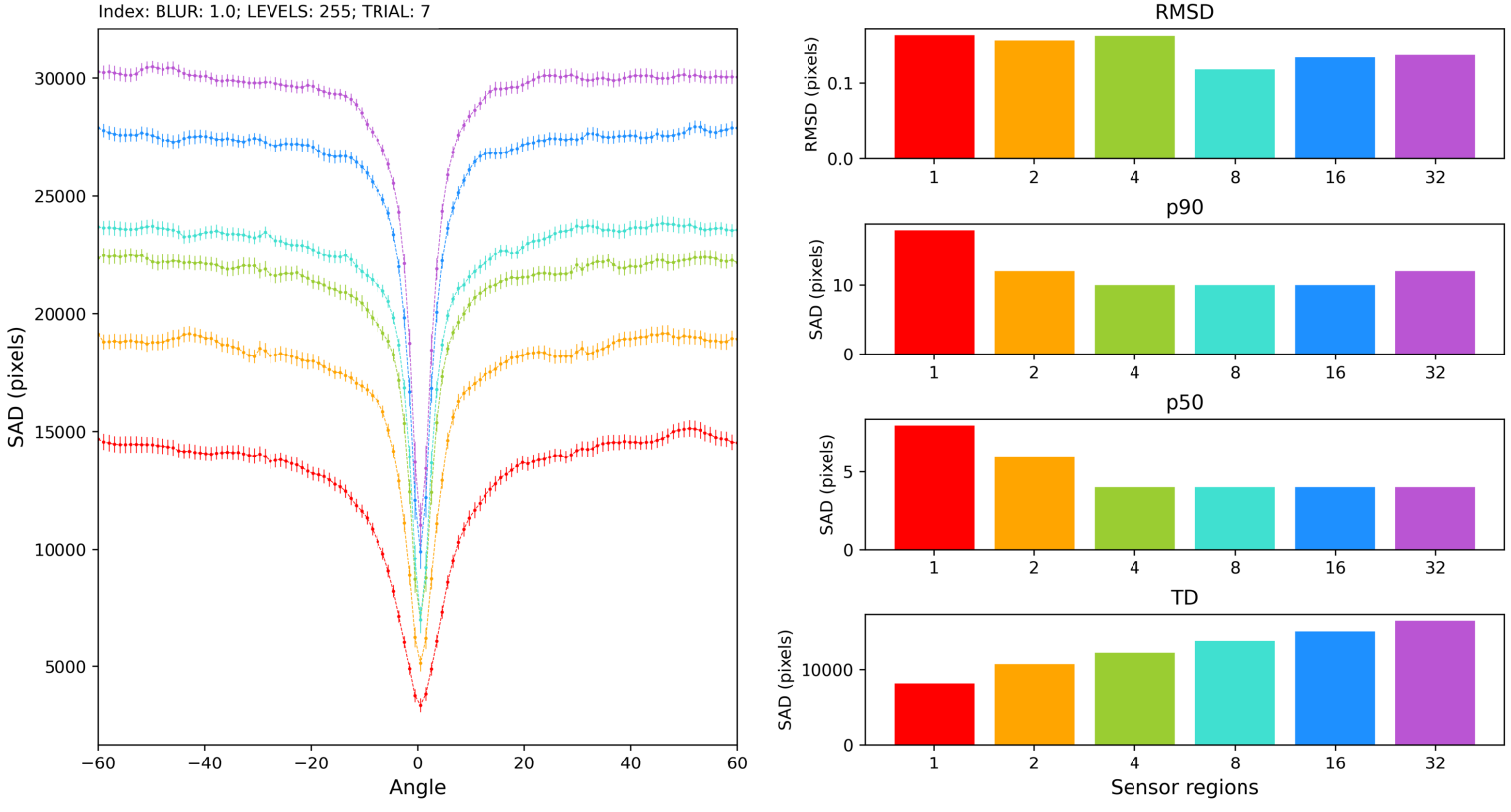


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 45.39; RMSD/dist: 0.113; TD: 16250; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 46.45; RMSD/dist: 0.116; TD: 17149; p90: 10; p50: 4; complete: 0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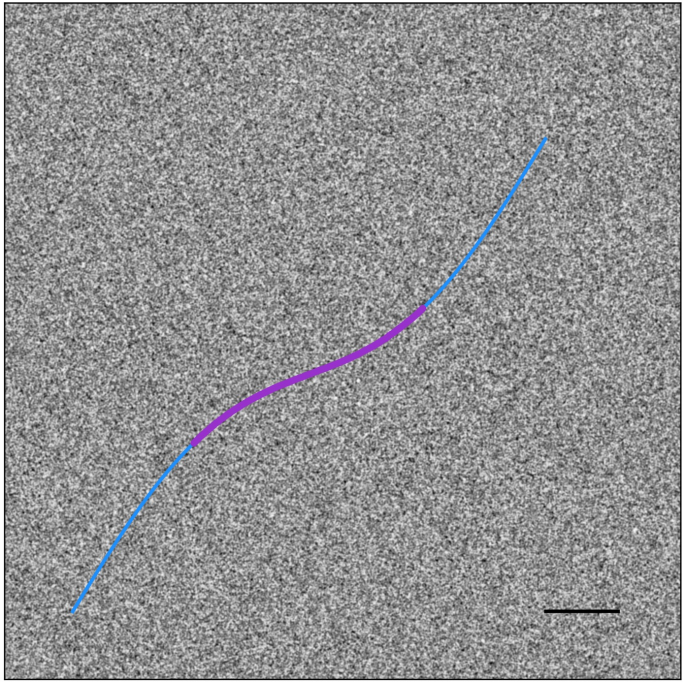
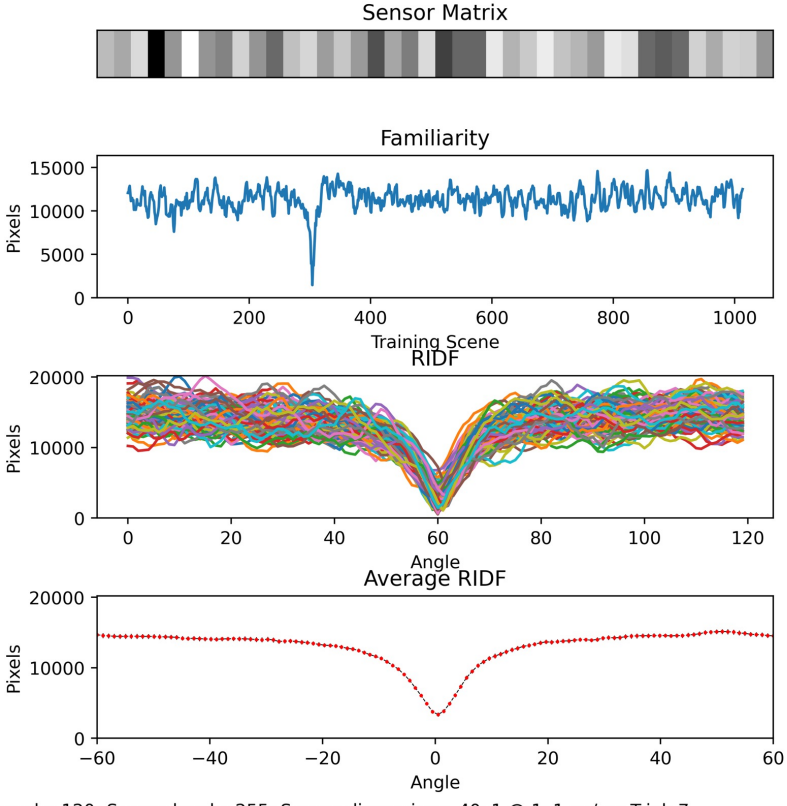
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
Sensor regions





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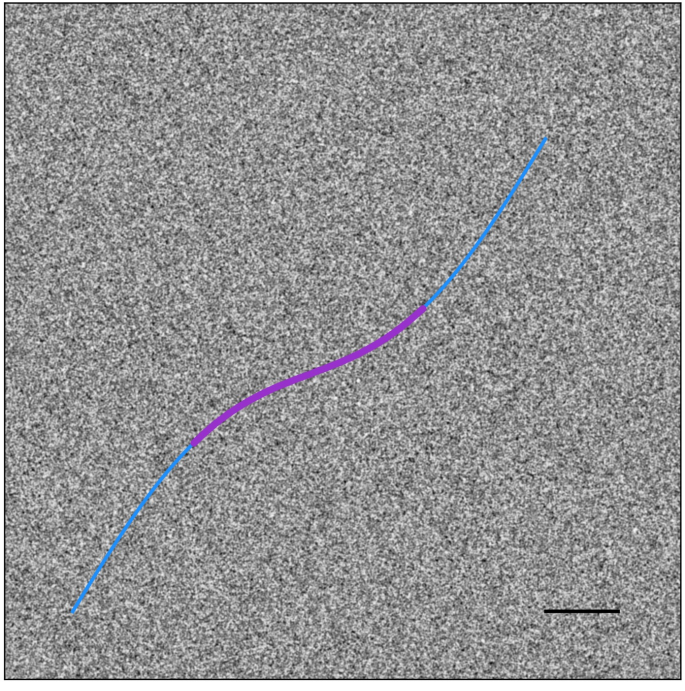
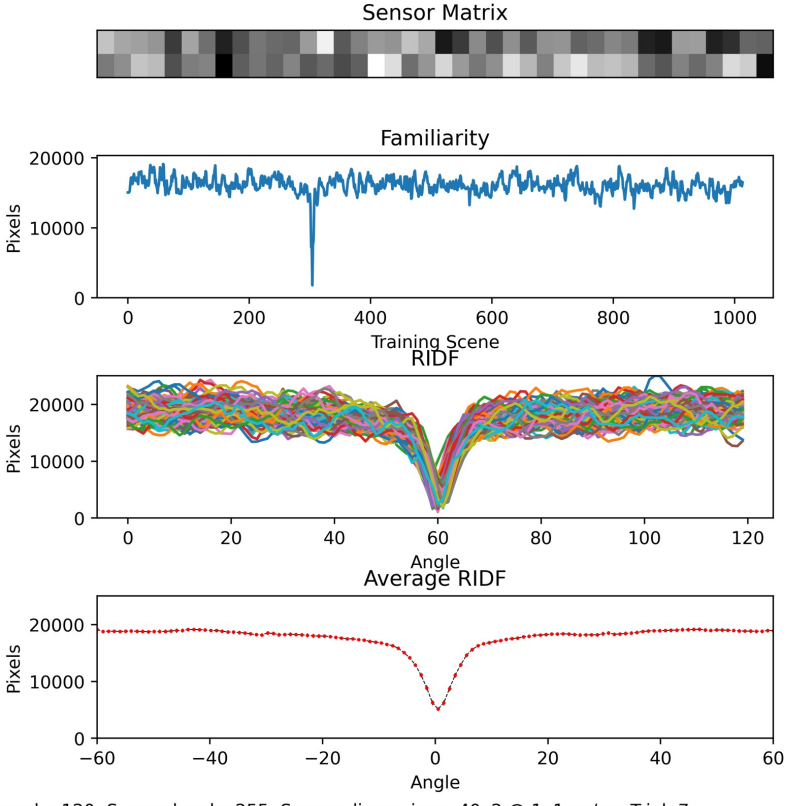
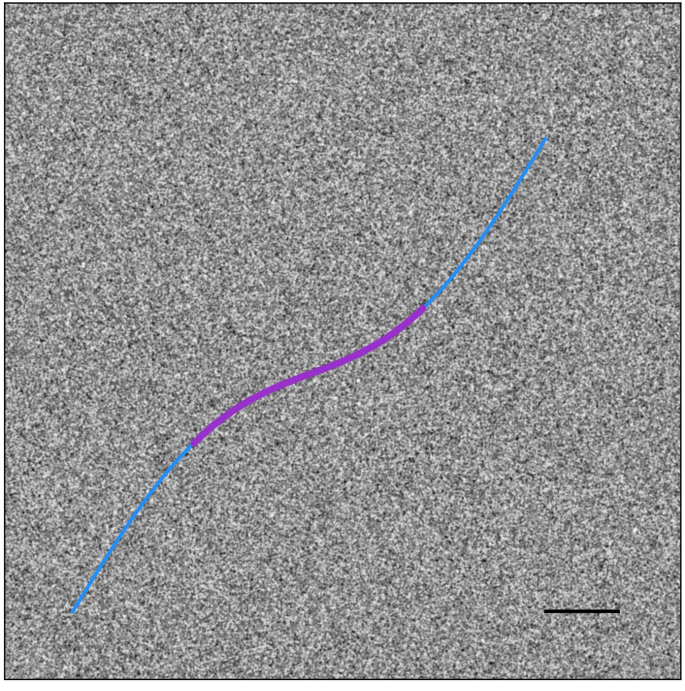
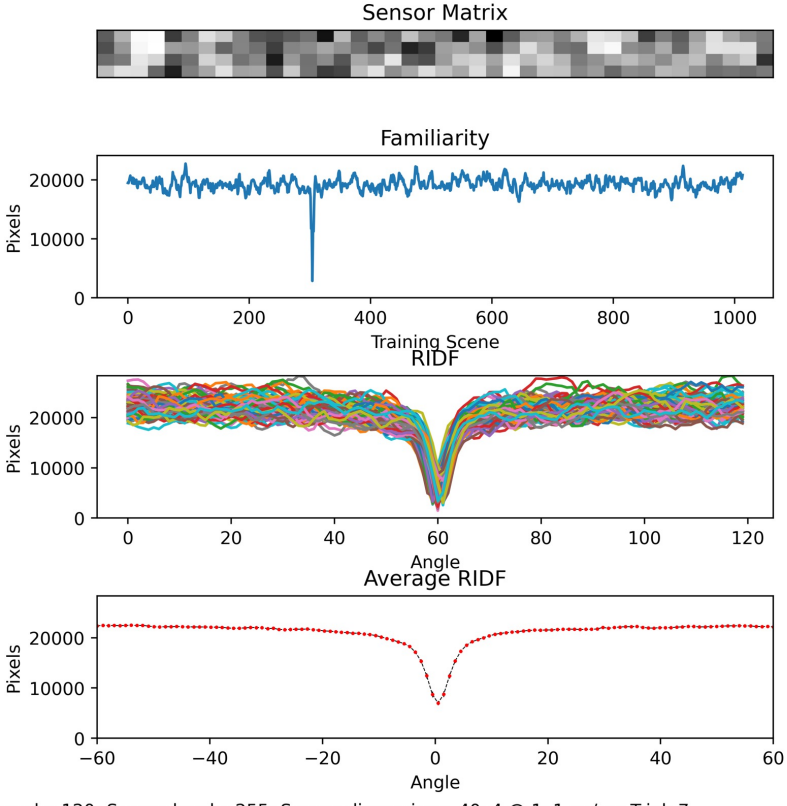
Navigation stats: RMSD error: 65.49; RMSD/dist: 0.164; TD: 8145; p90: 18; p50: 8; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 62.98; RMSD/dist: 0.157; TD: 10728; p90: 12; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7
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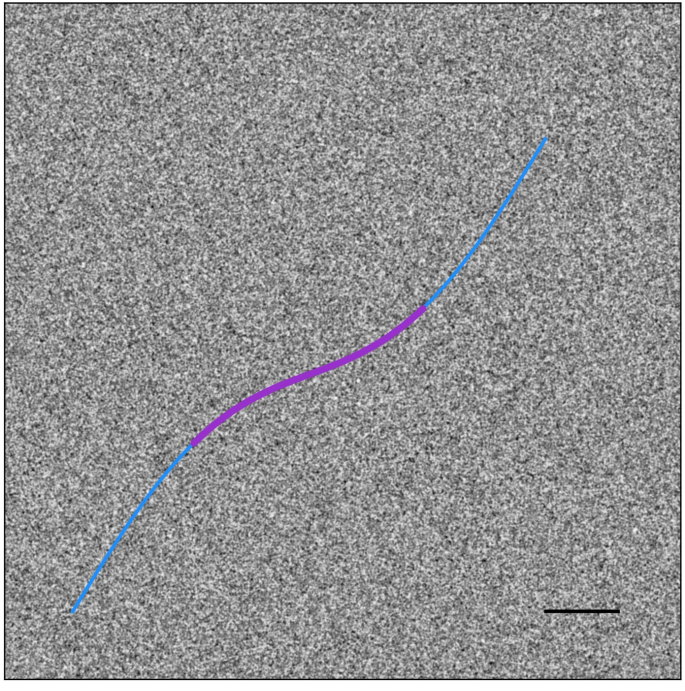
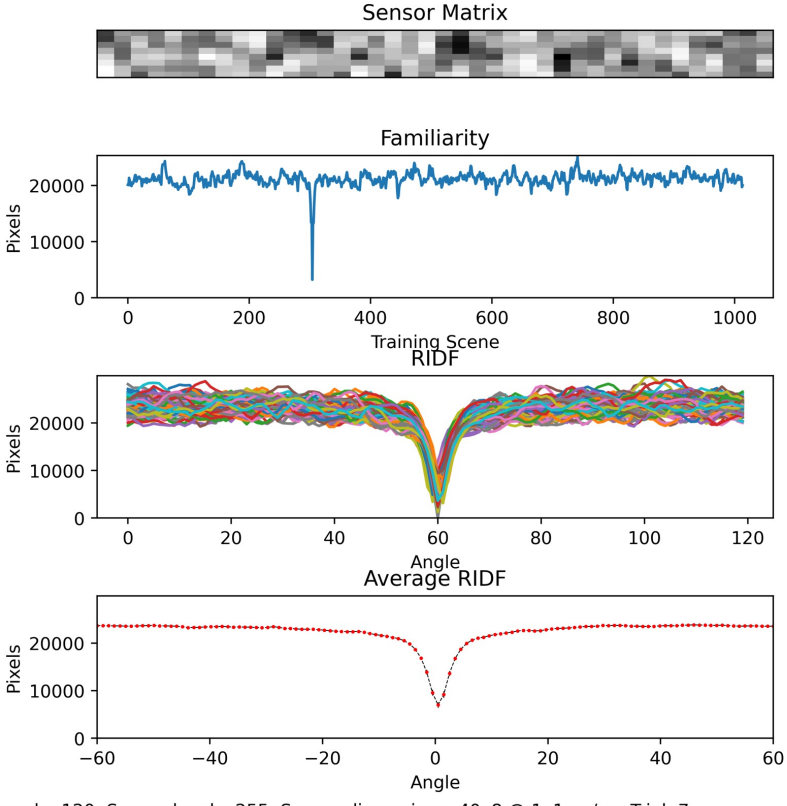
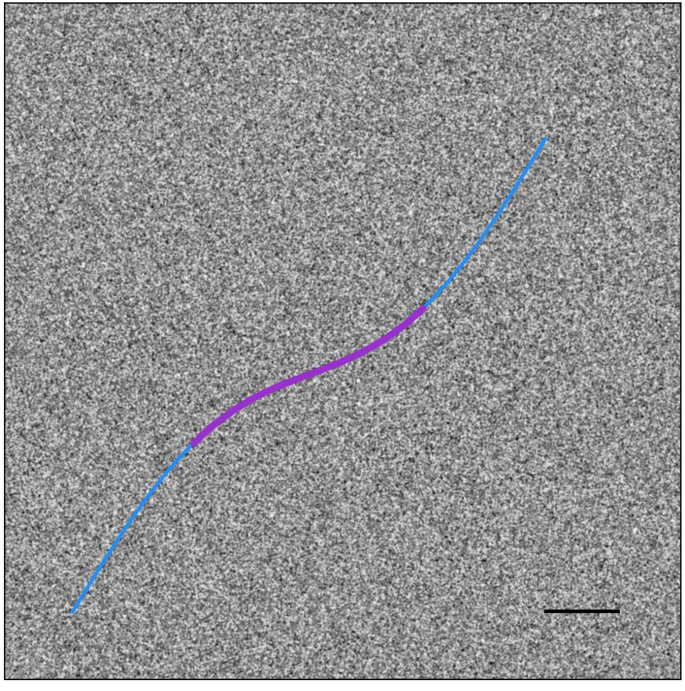
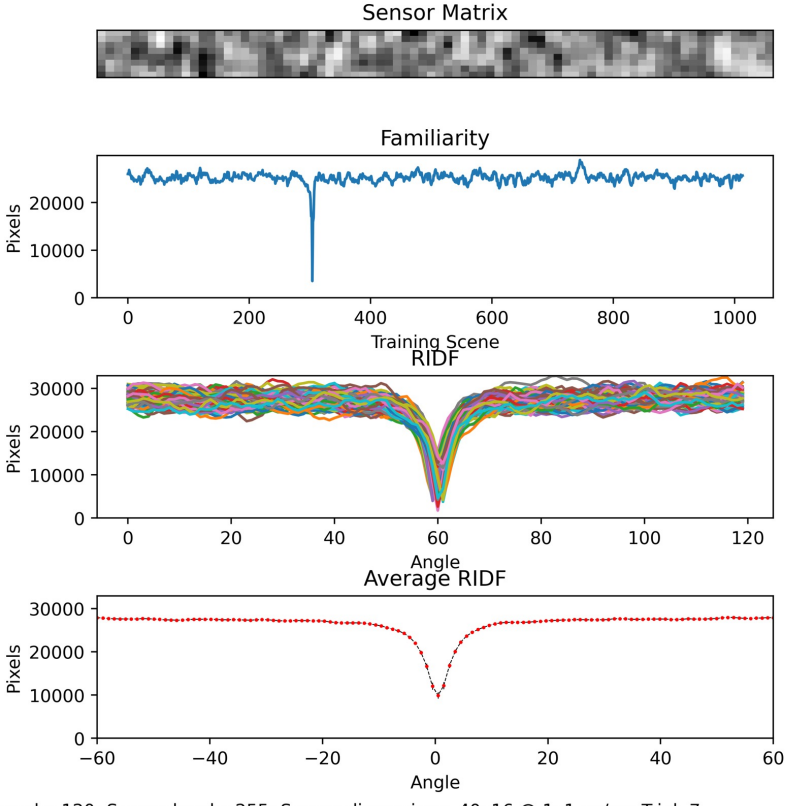


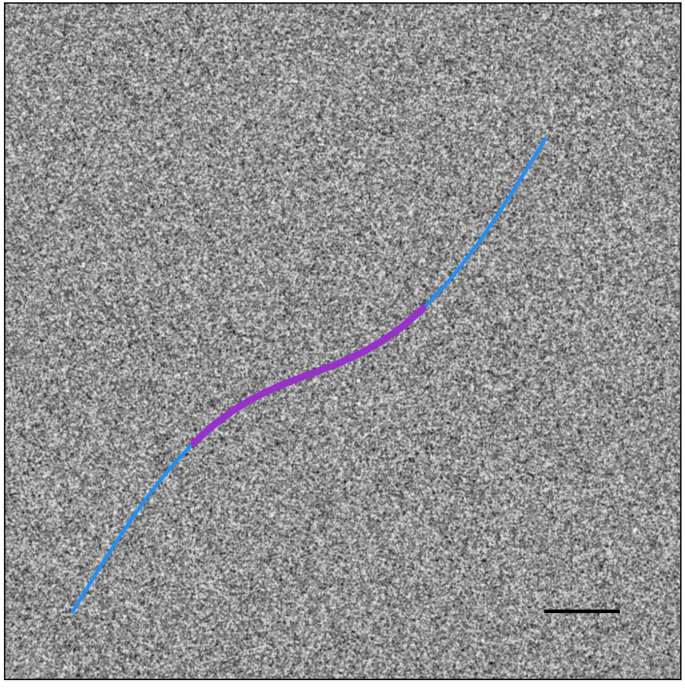


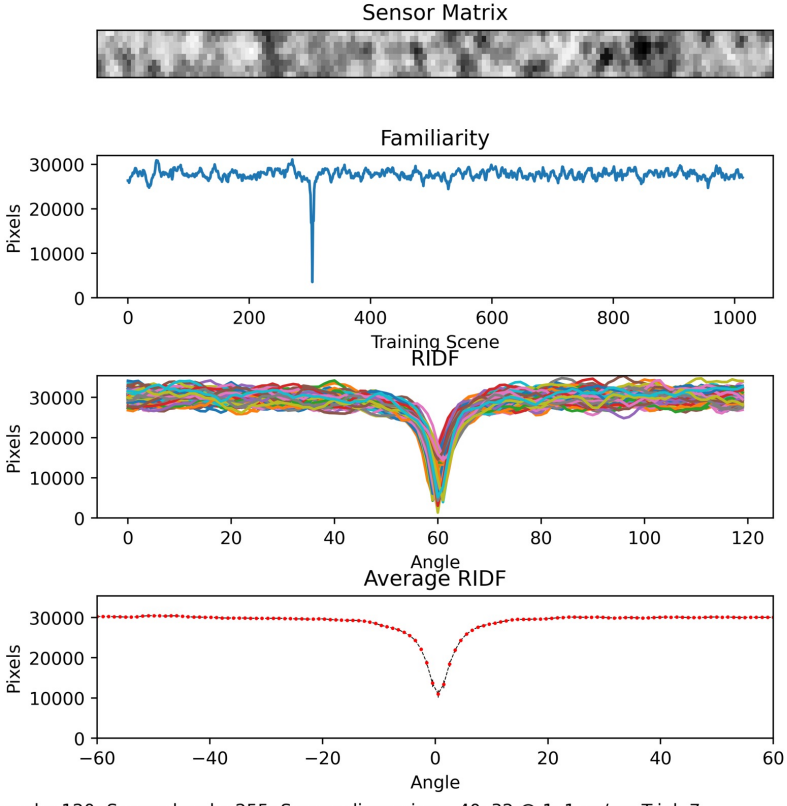
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 47.00; RMSD/dist: 0.118; TD: 13951; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 53.65; RMSD/dist: 0.134; TD: 15219; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7
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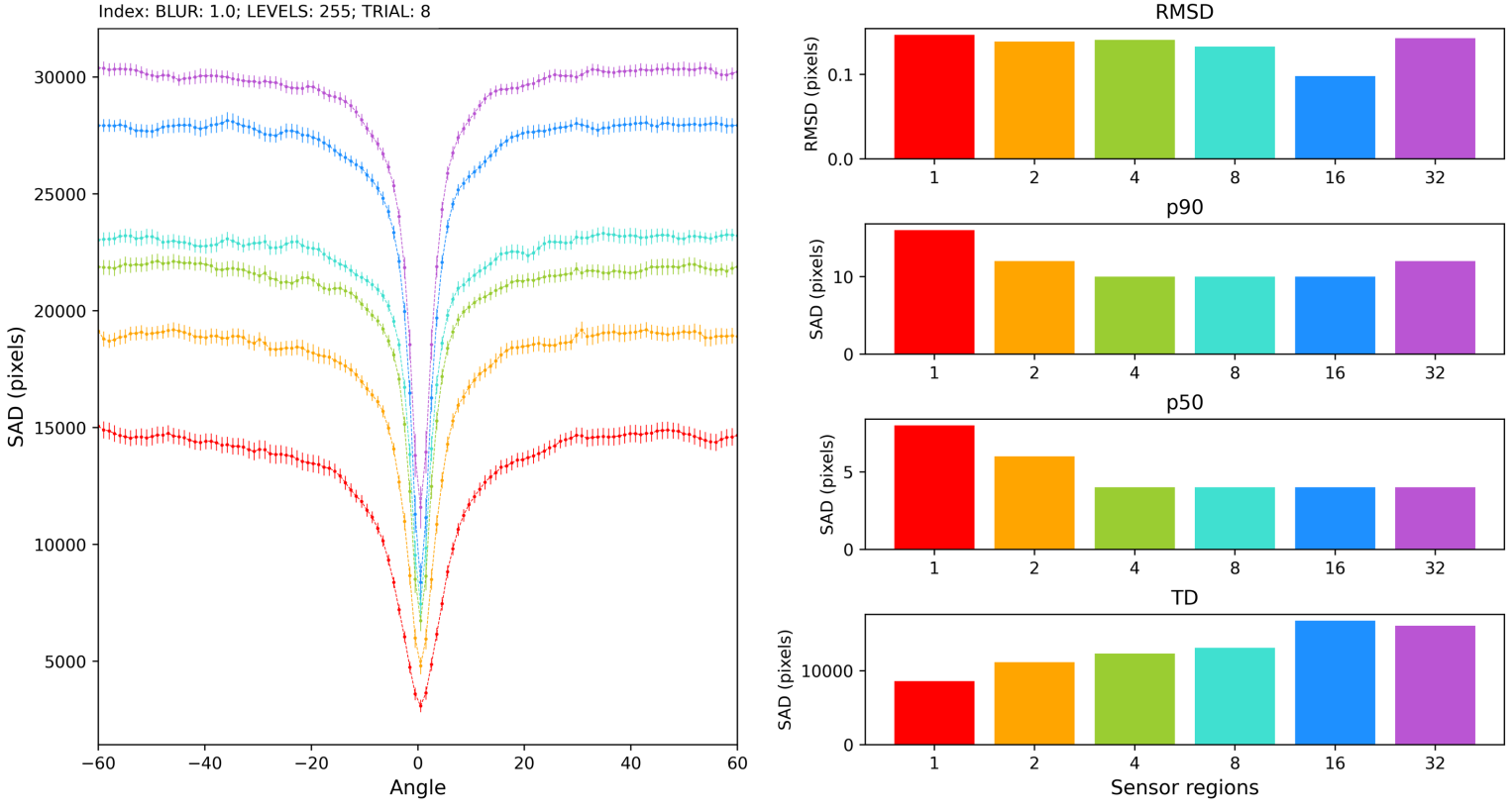
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15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
p90
SAD (pixels)
10
0
p50
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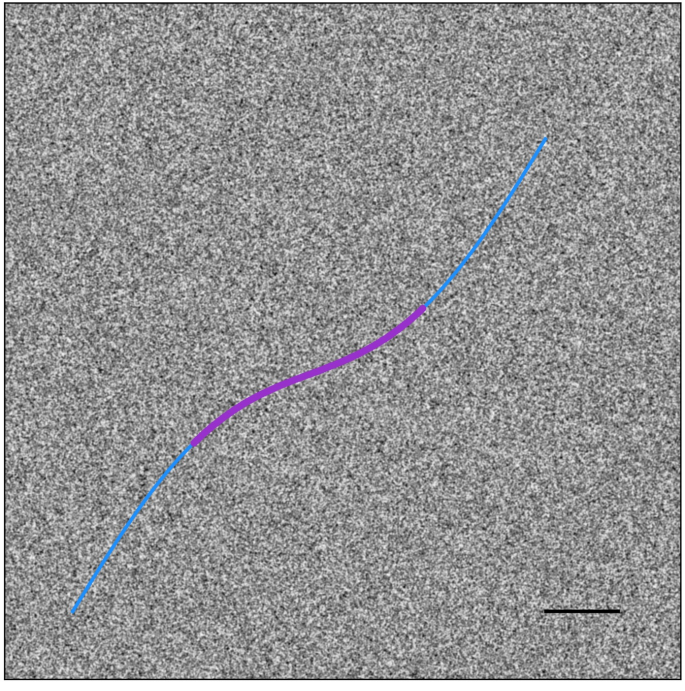
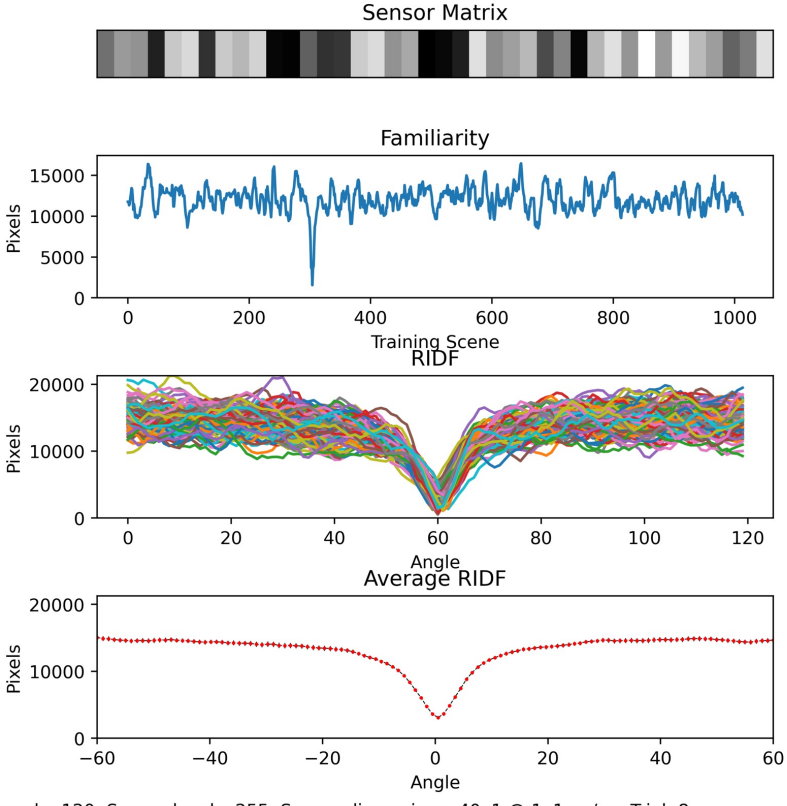
0
TD
SAD (pixels)
10000
0
1
2
4
8
16
32
Sensor regions





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8
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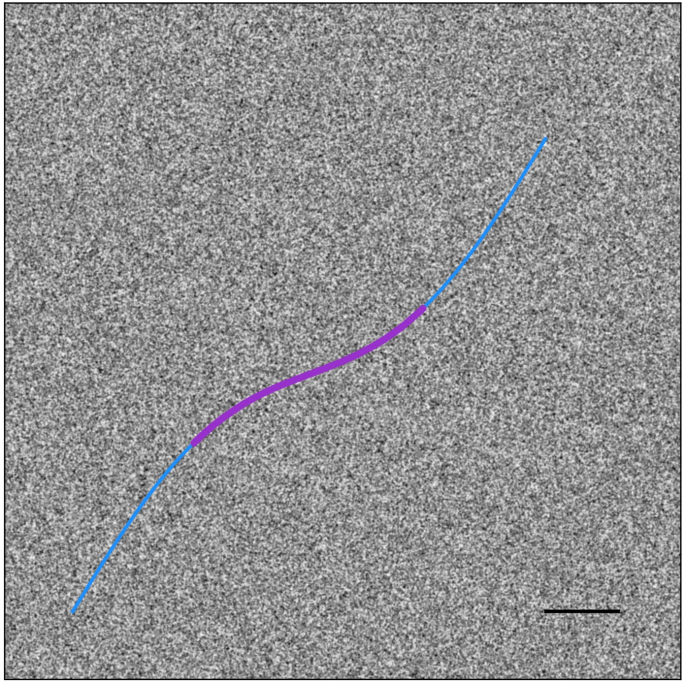

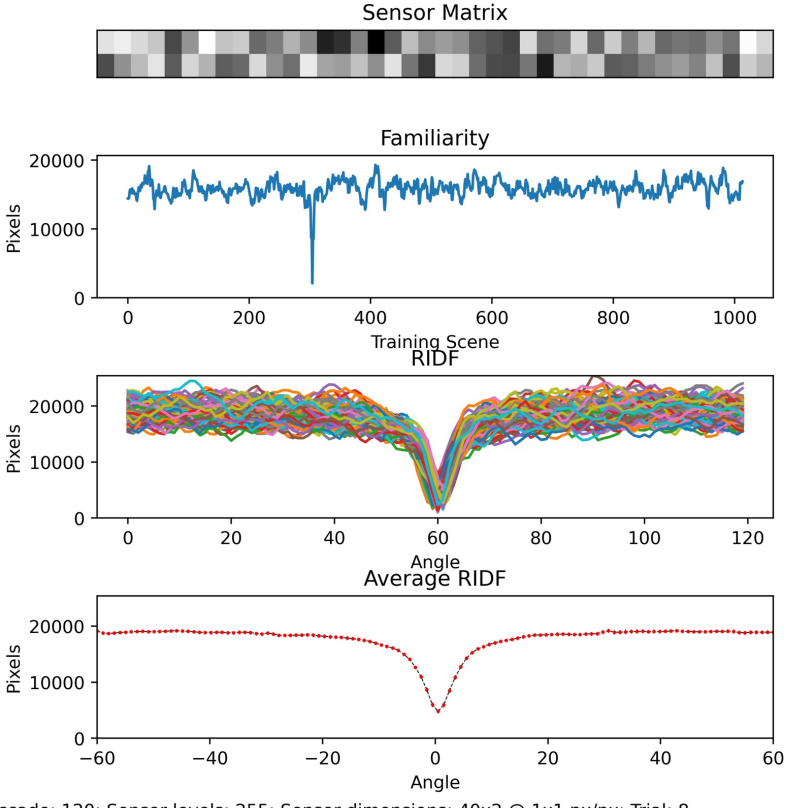

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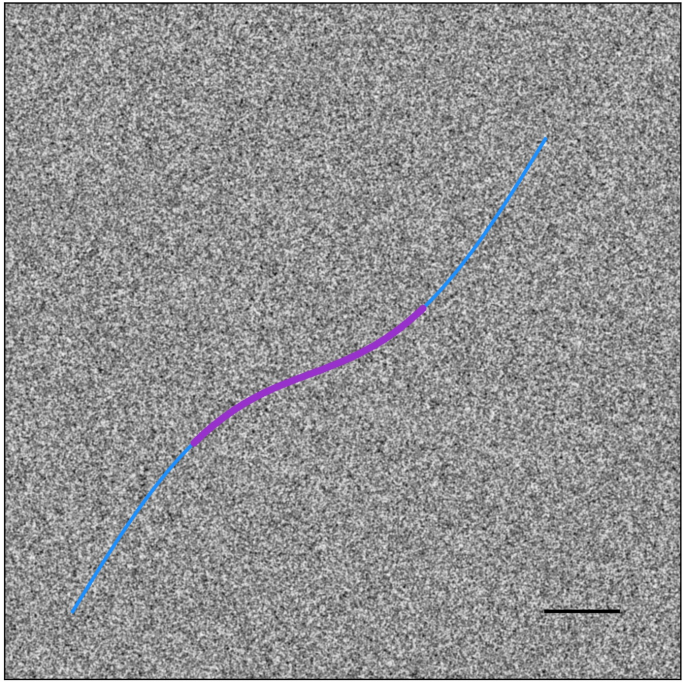

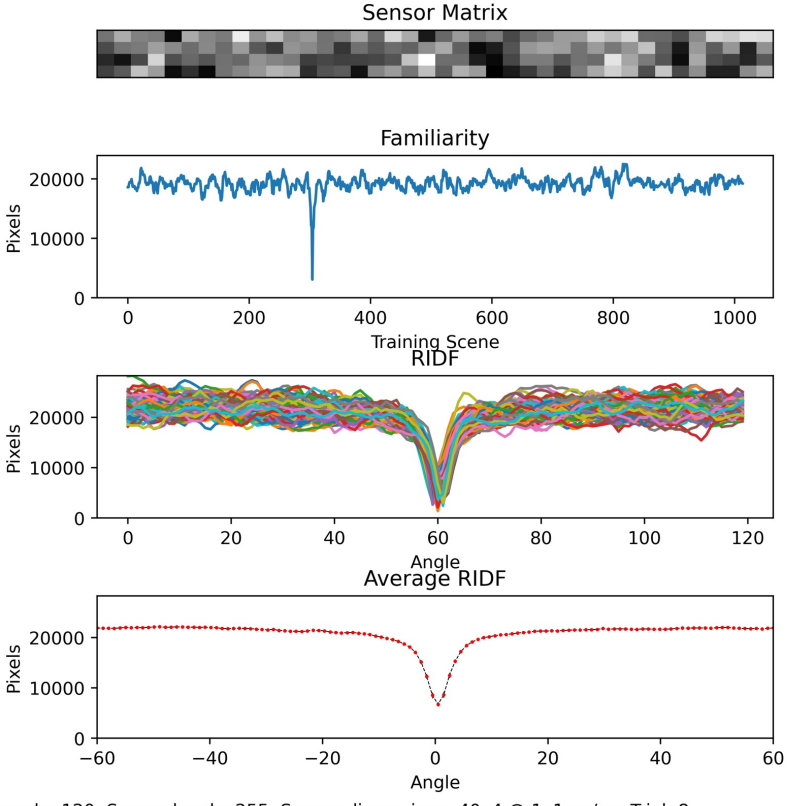

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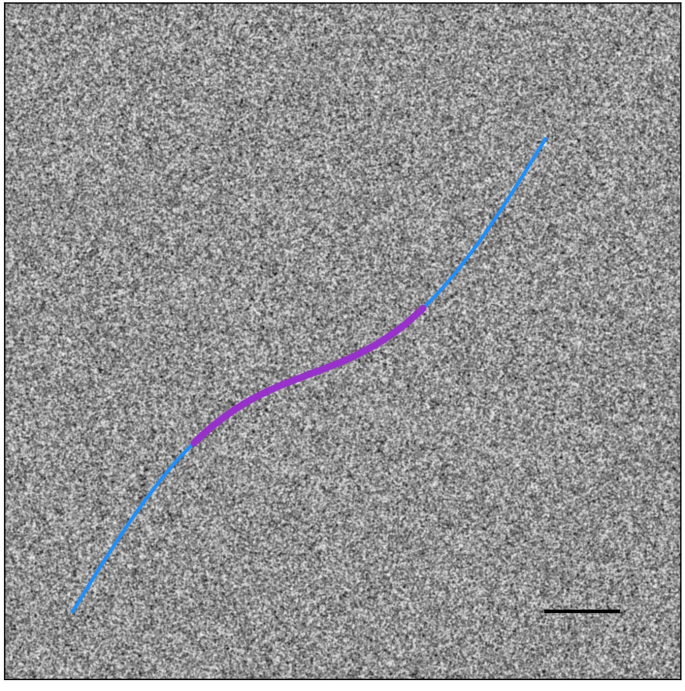

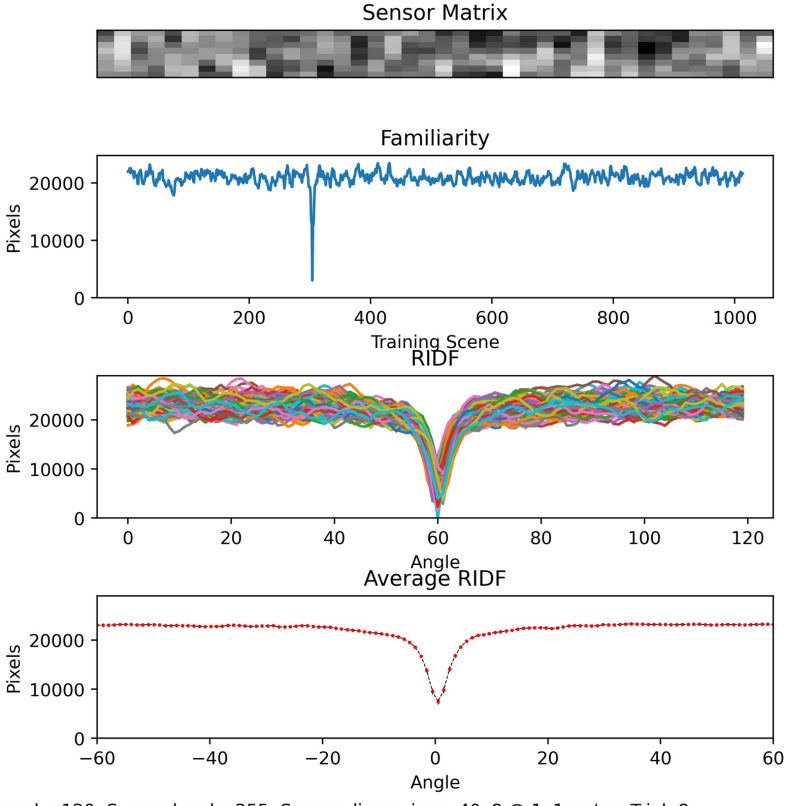

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8
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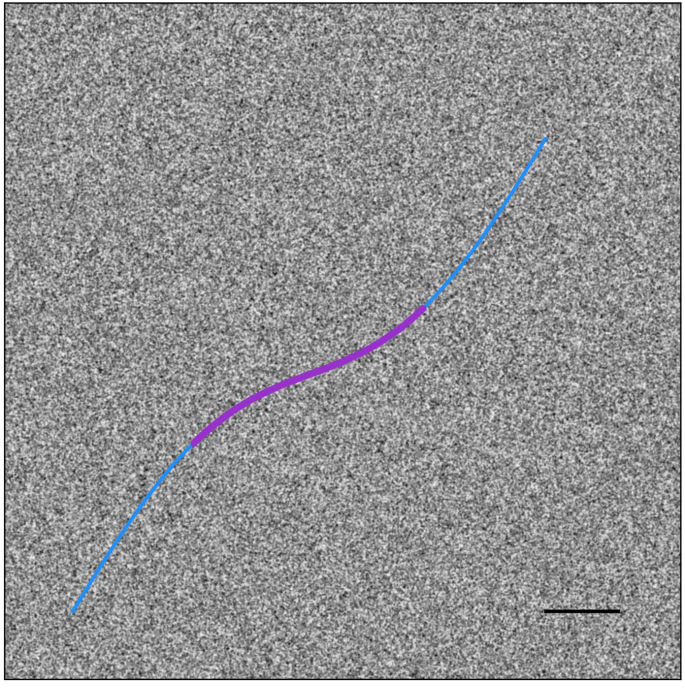

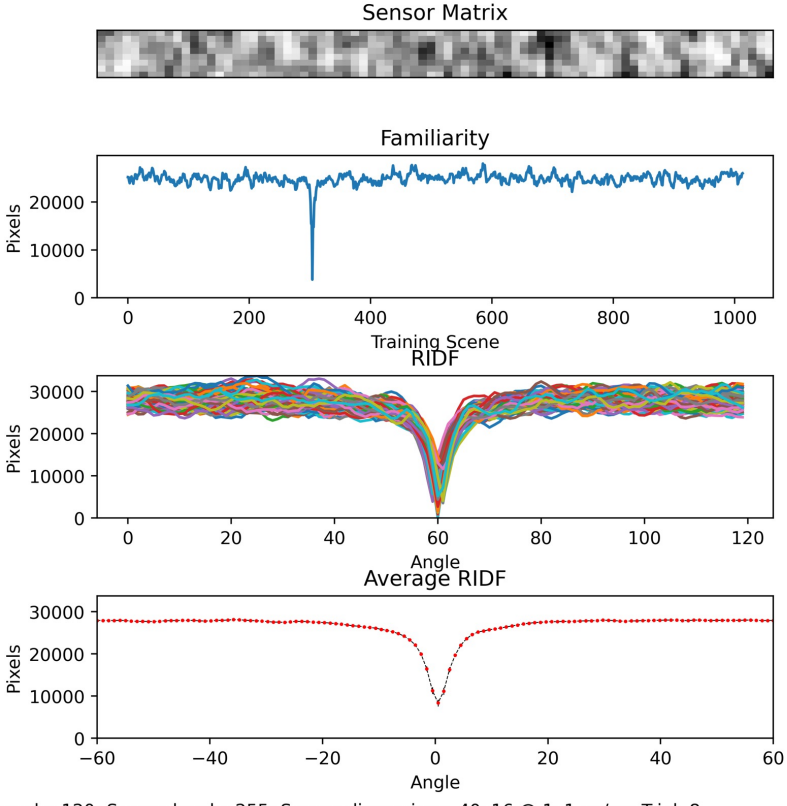

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8
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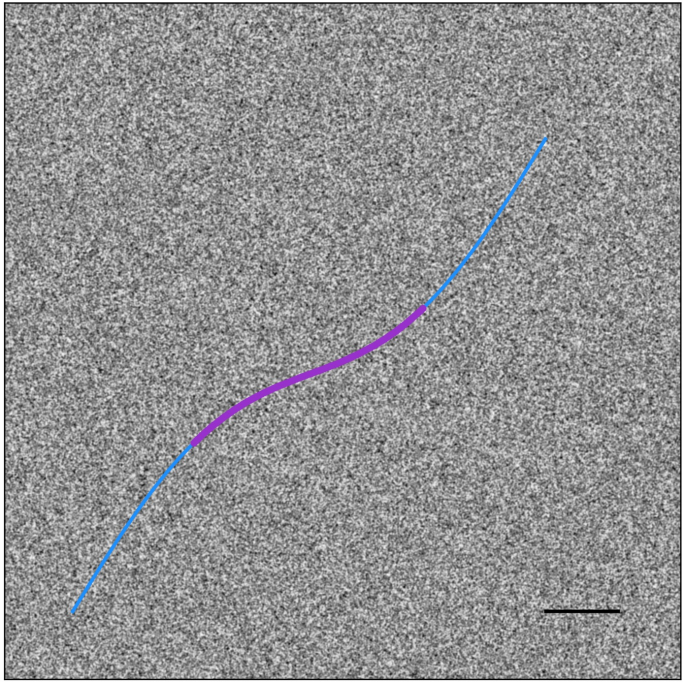

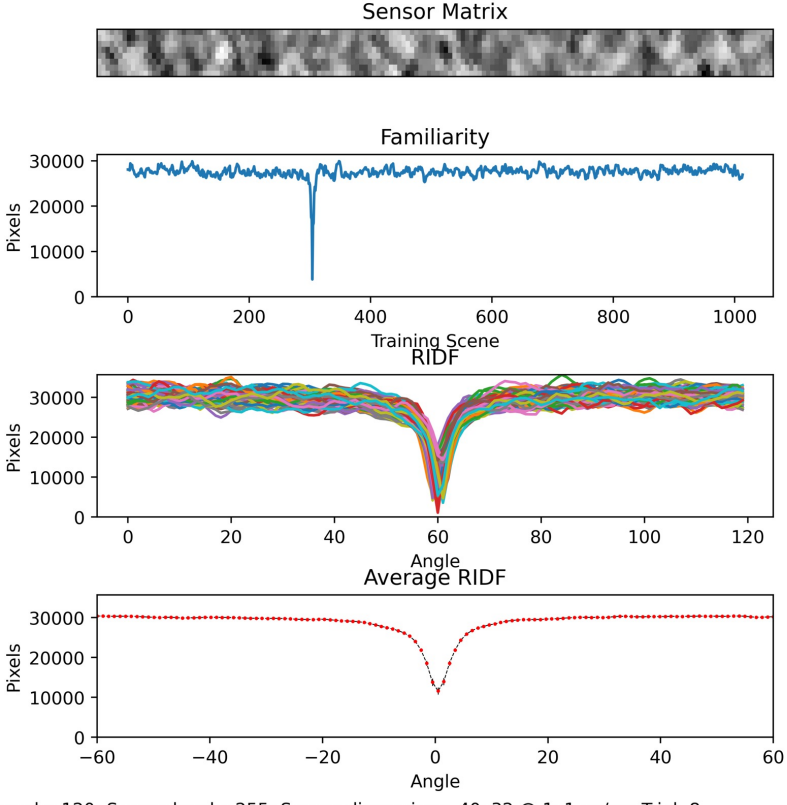

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8
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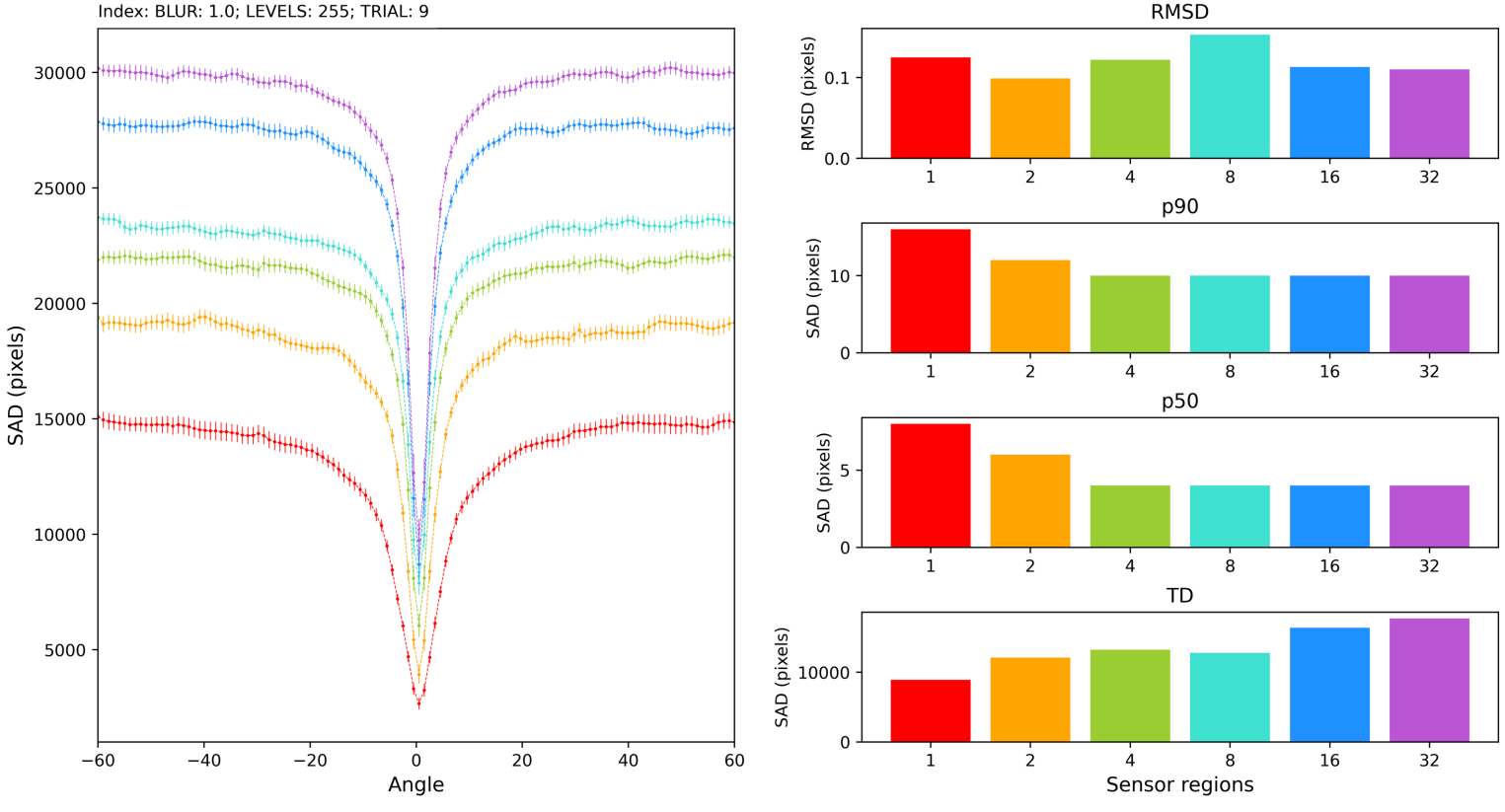
Index: BLUR: 1.0; LEVELS: 255; TRIAL: 9
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15000
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5000
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−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
p90
SAD (pixels)
10
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1
2
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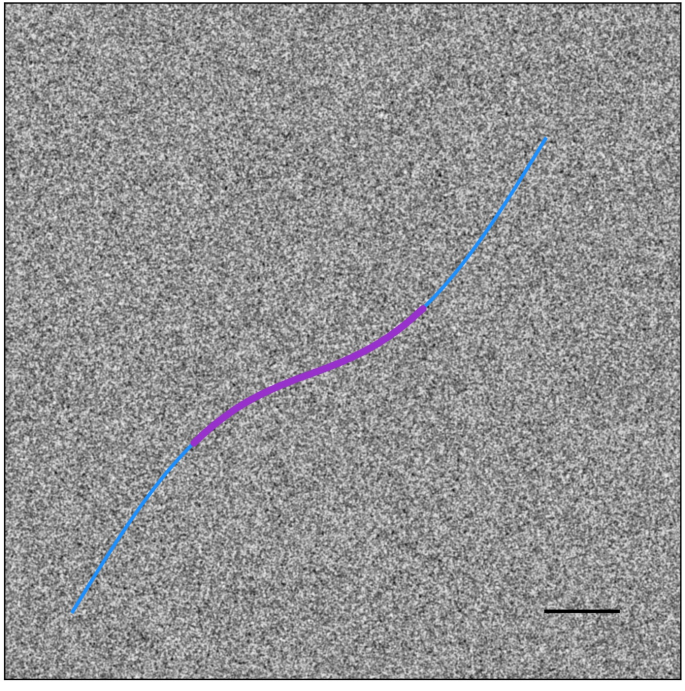
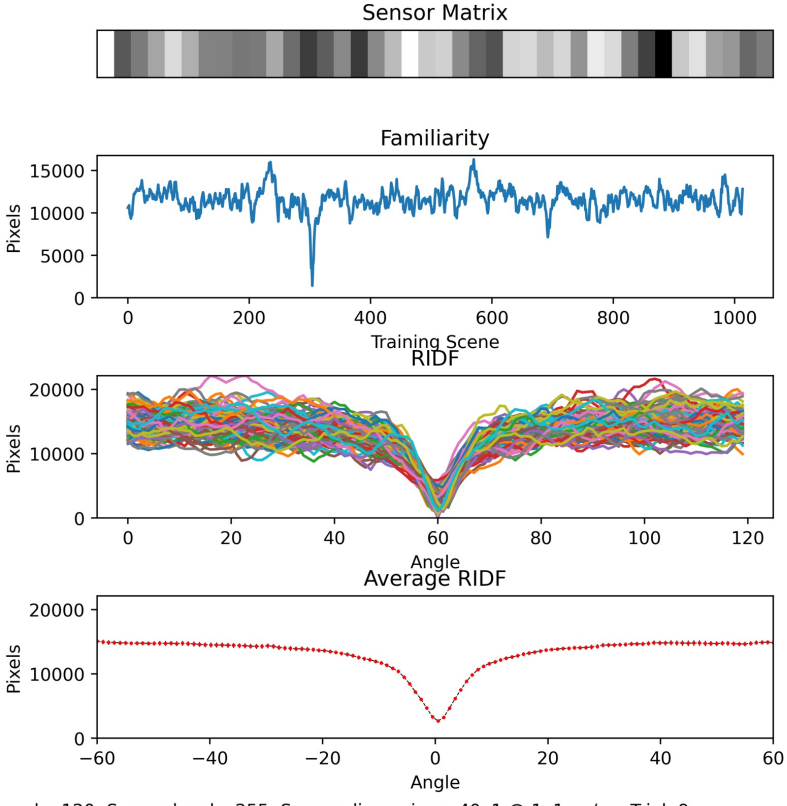
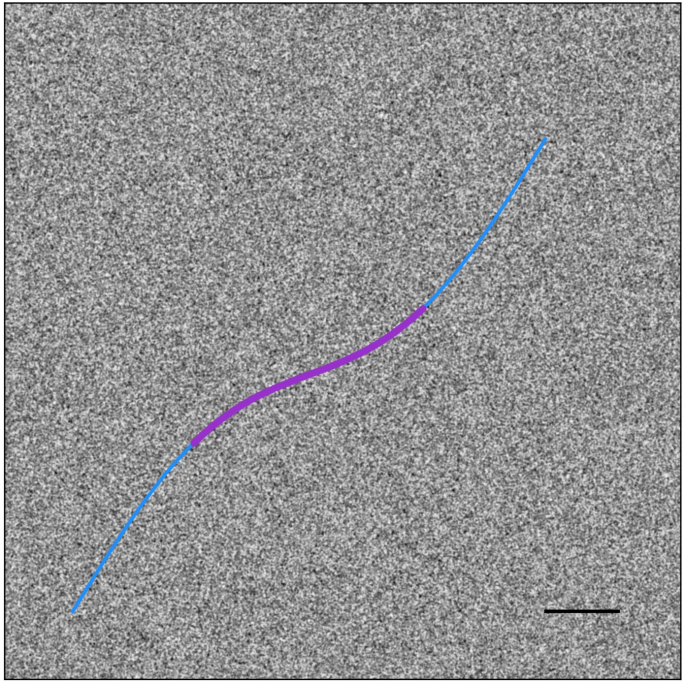
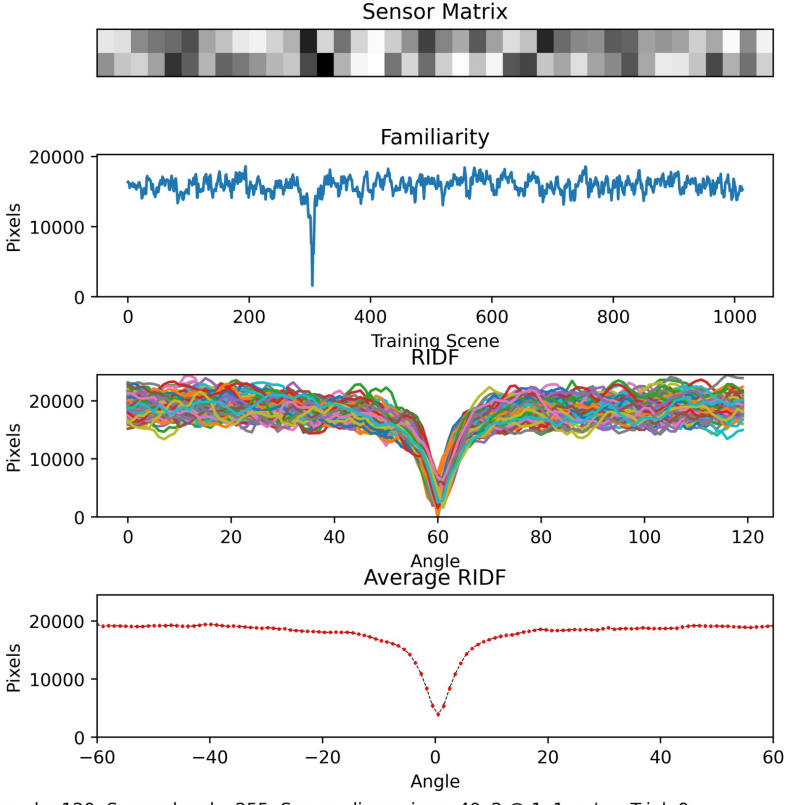
8
16
32
Sensor regions





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 49.87; RMSD/dist: 0.125; TD: 8922; p90: 16; p50: 8; complete: 0





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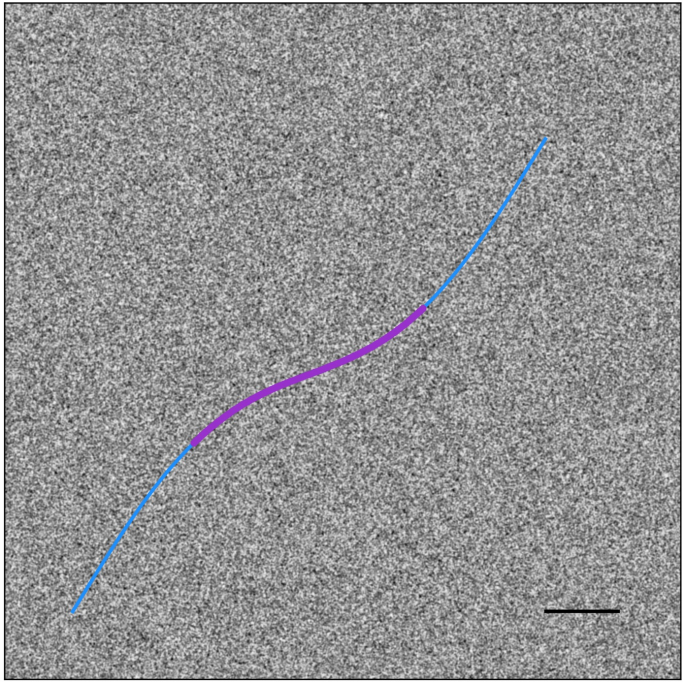
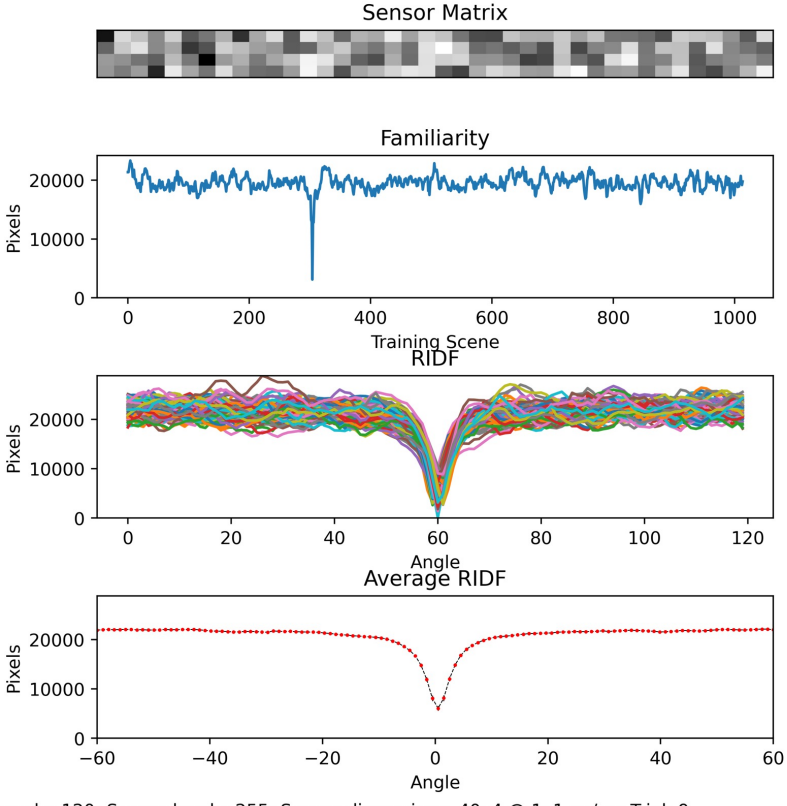
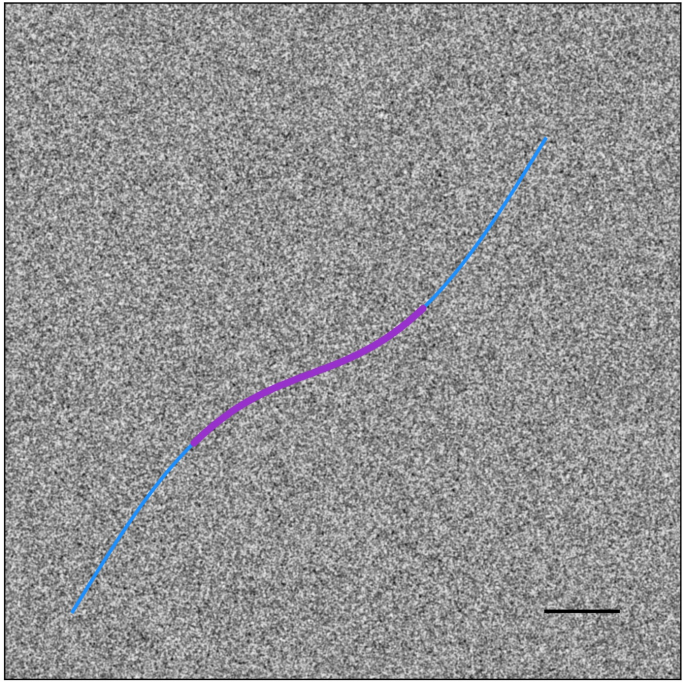
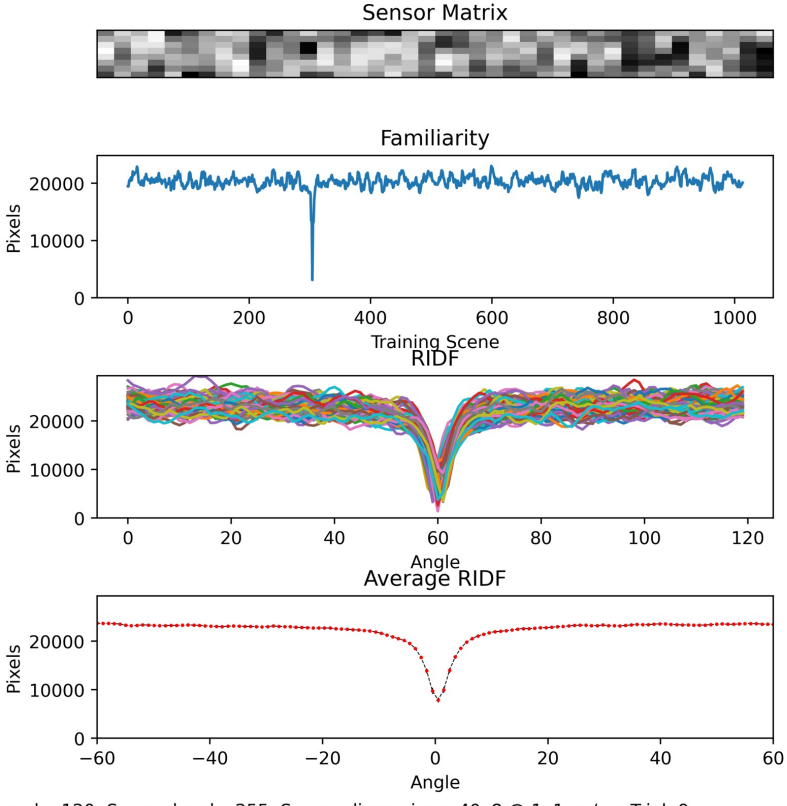




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 48.69; RMSD/dist: 0.122; TD: 13224; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9
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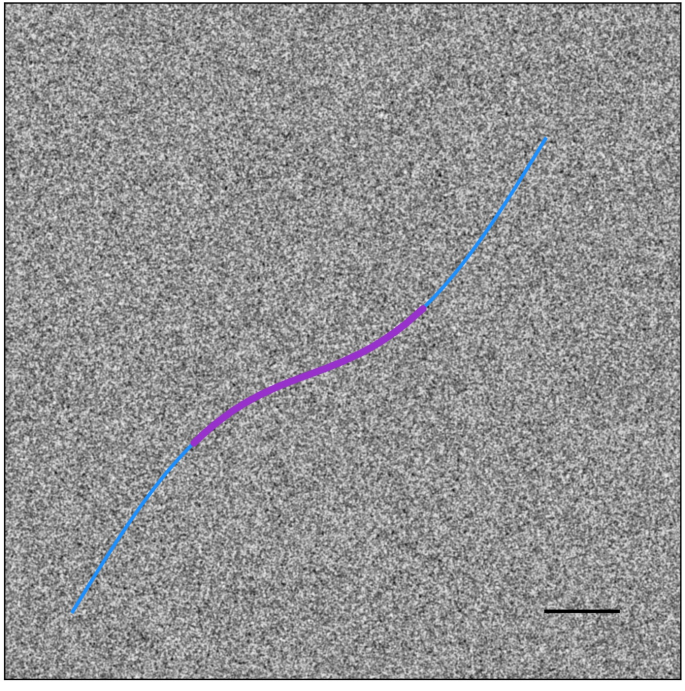

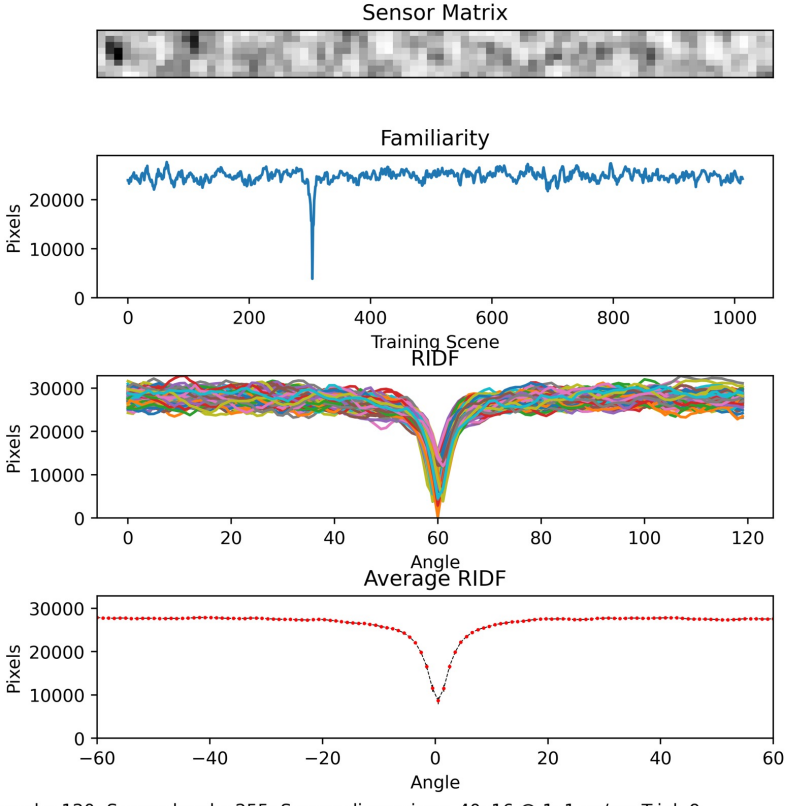

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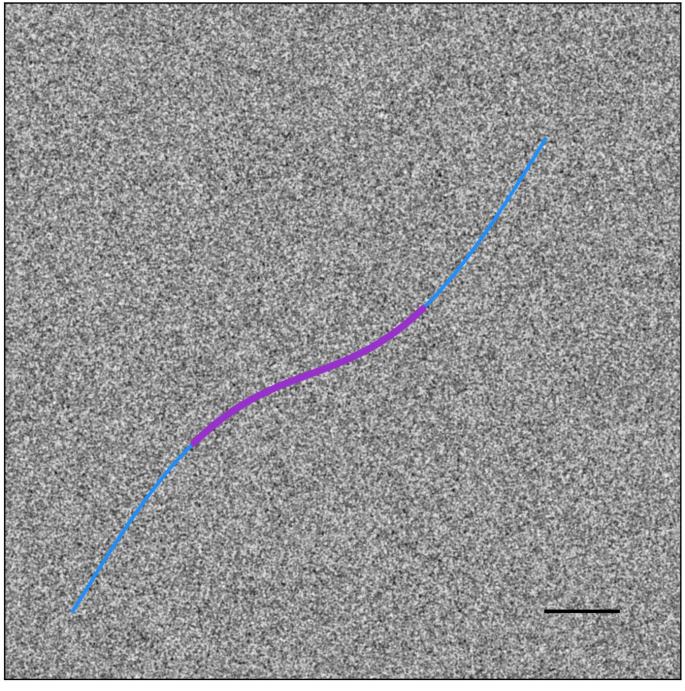
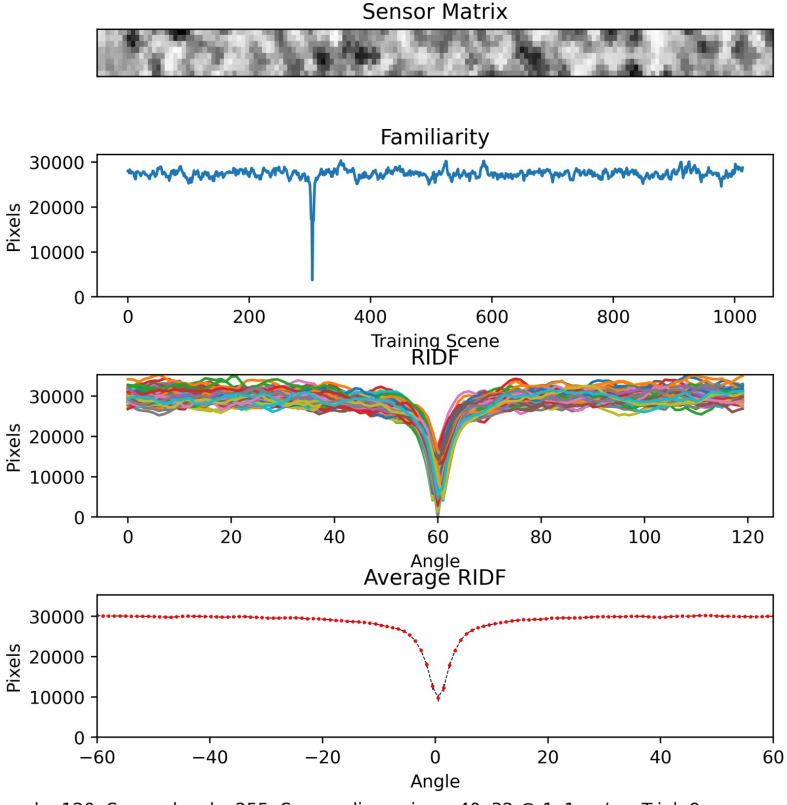
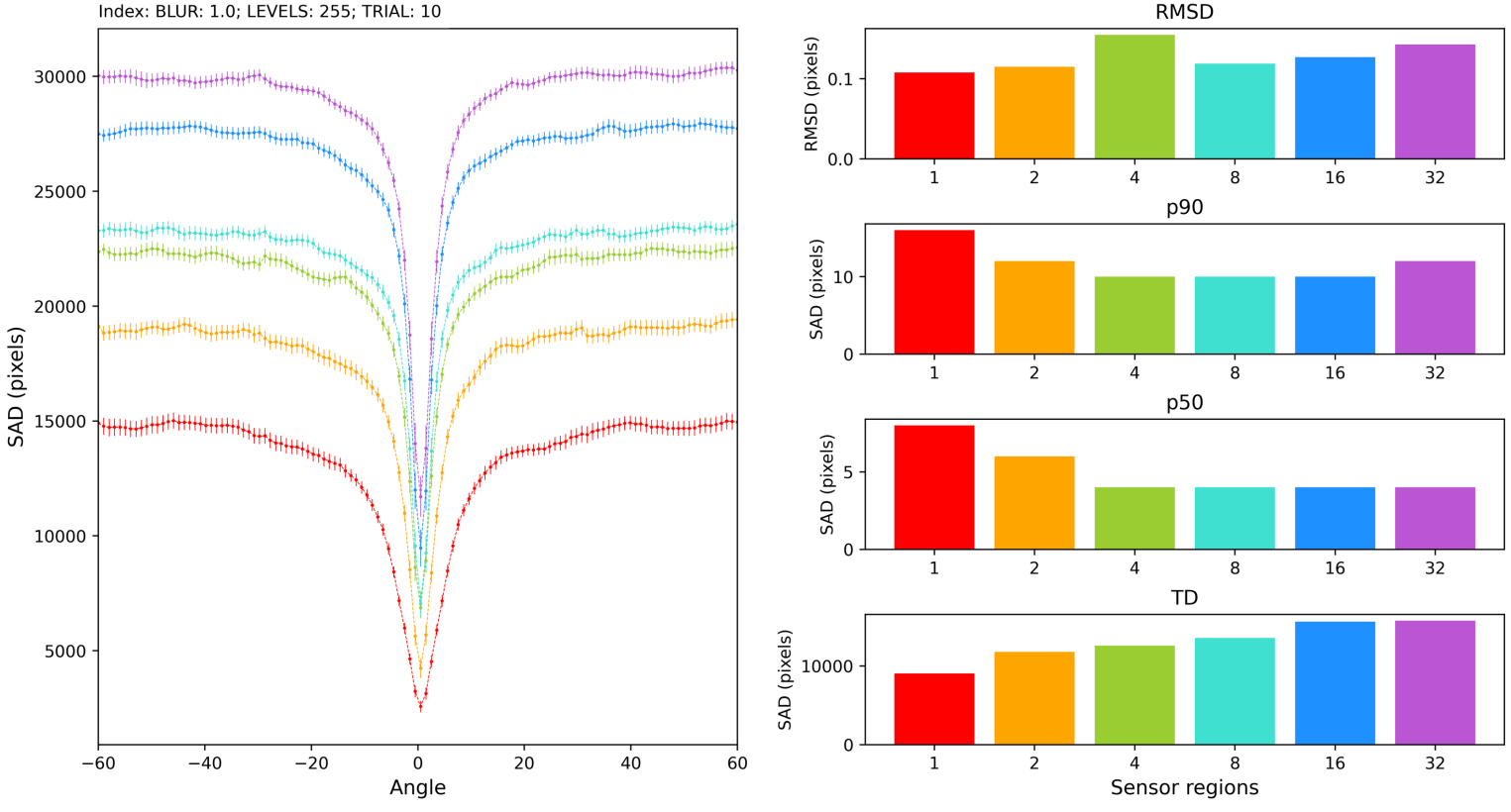
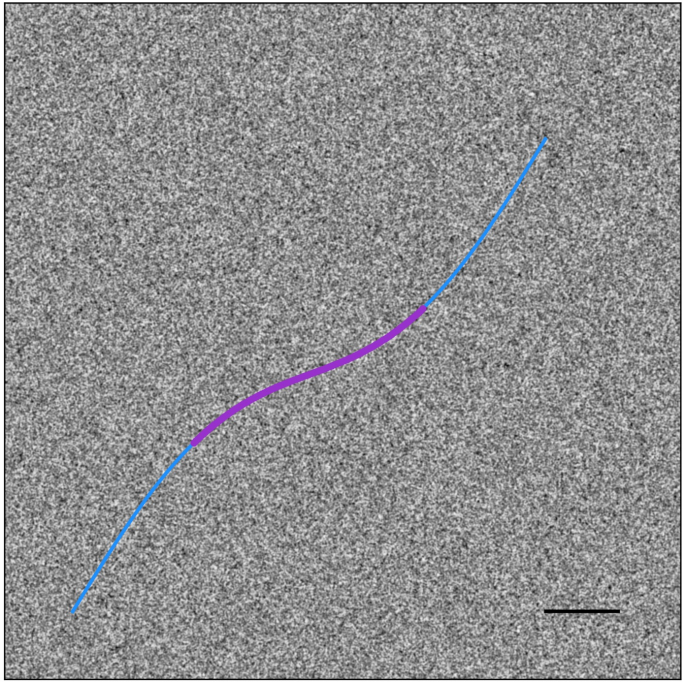
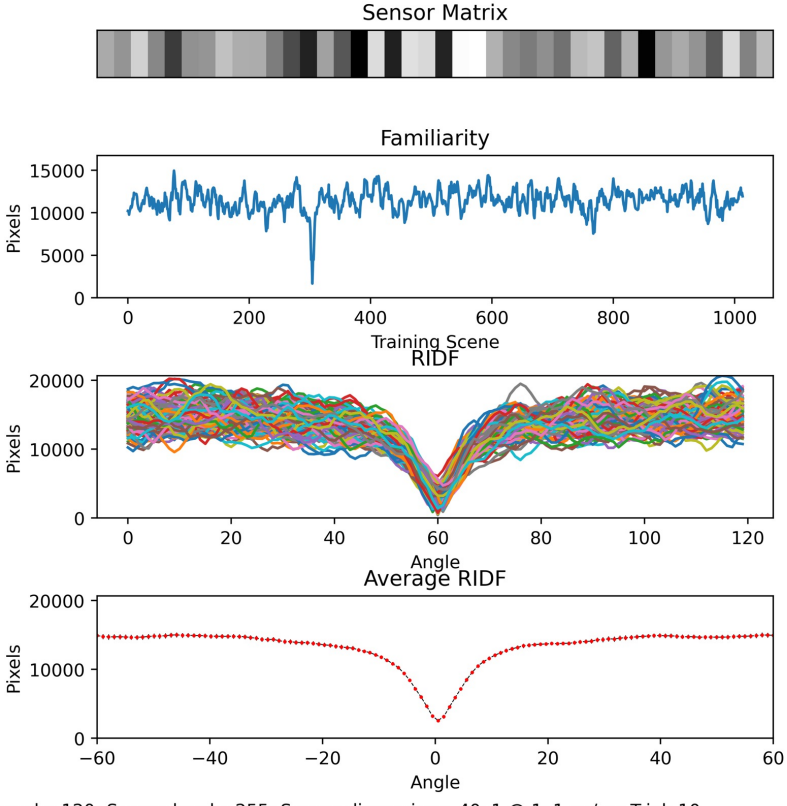




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 44.08; RMSD/dist: 0.110; TD: 17733; p90: 10; p50: 4; complete: 0

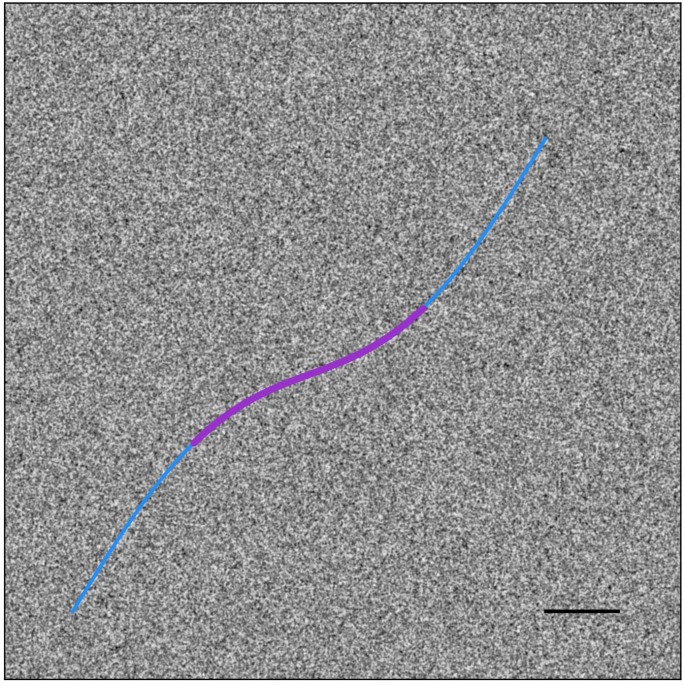

Index: BLUR: 1.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
Sensor regions

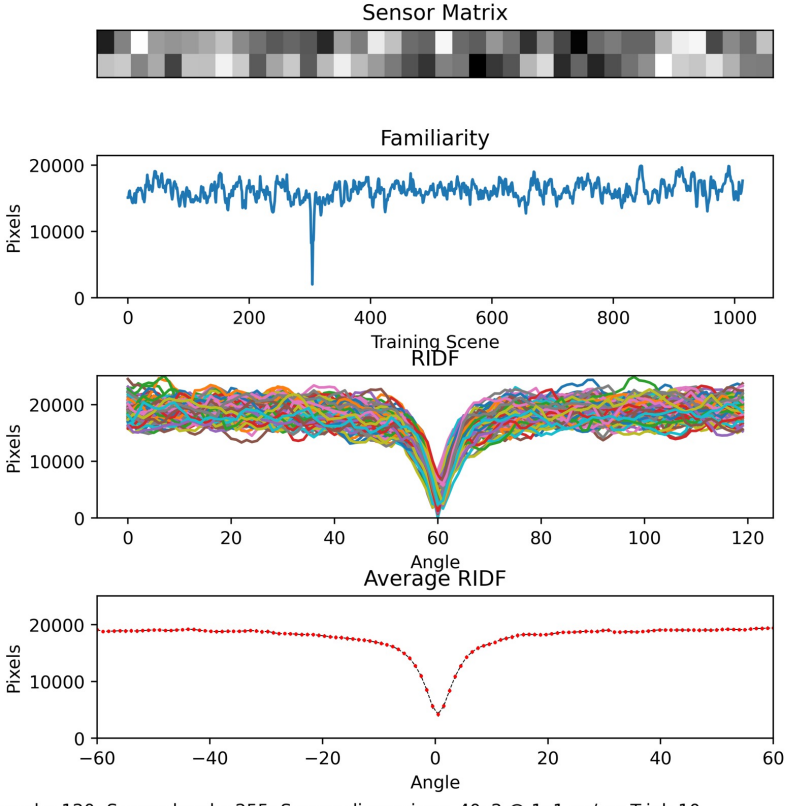




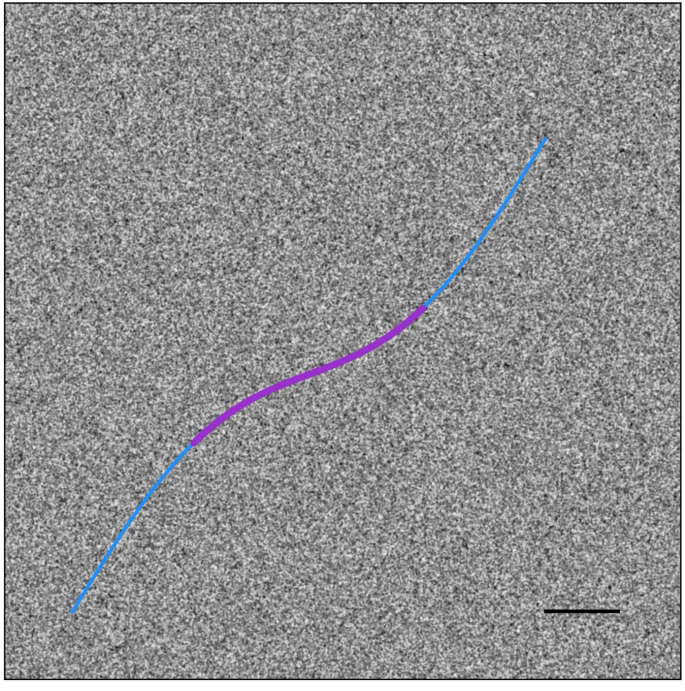
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

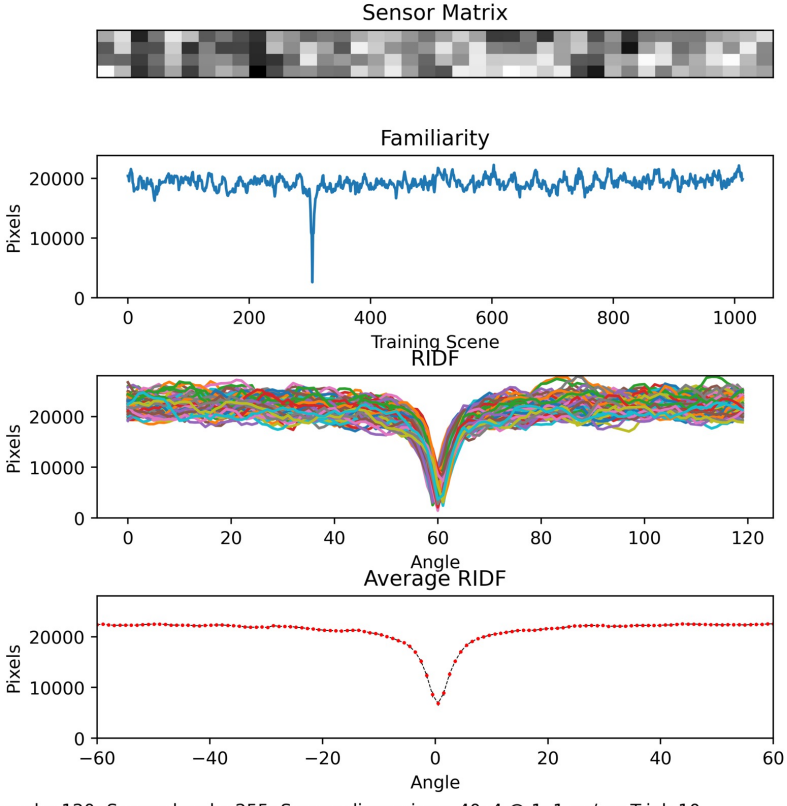
Navigation stats: RMSD error: 43.25; RMSD/dist: 0.108; TD: 9042; p90: 16; p50: 8; complete: 0



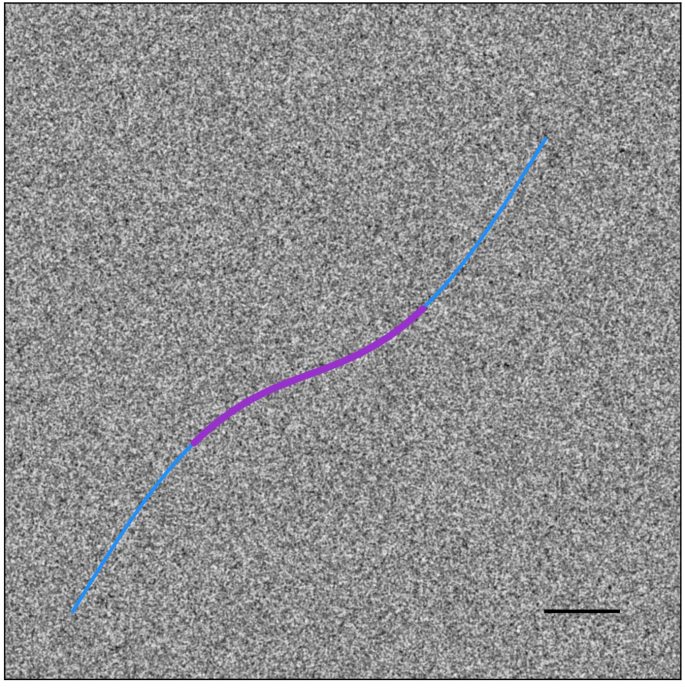


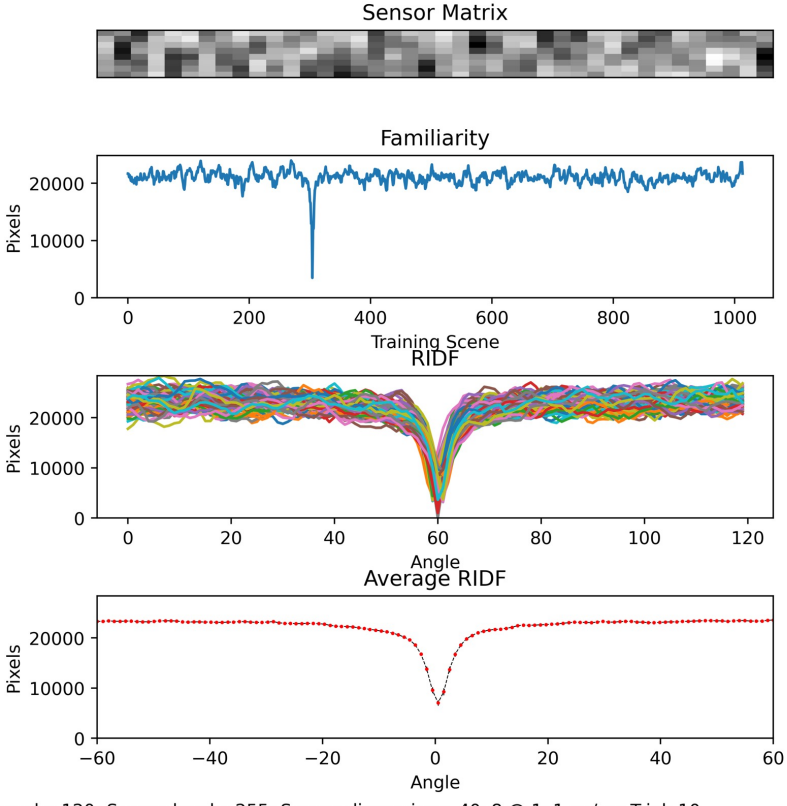
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 46.07; RMSD/dist: 0.115; TD: 11773; p90: 12; p50: 6; complete: 0



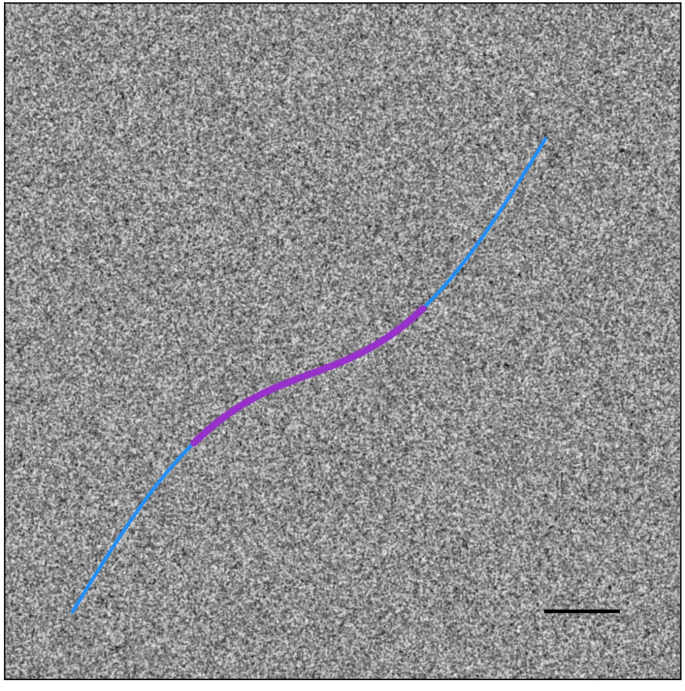


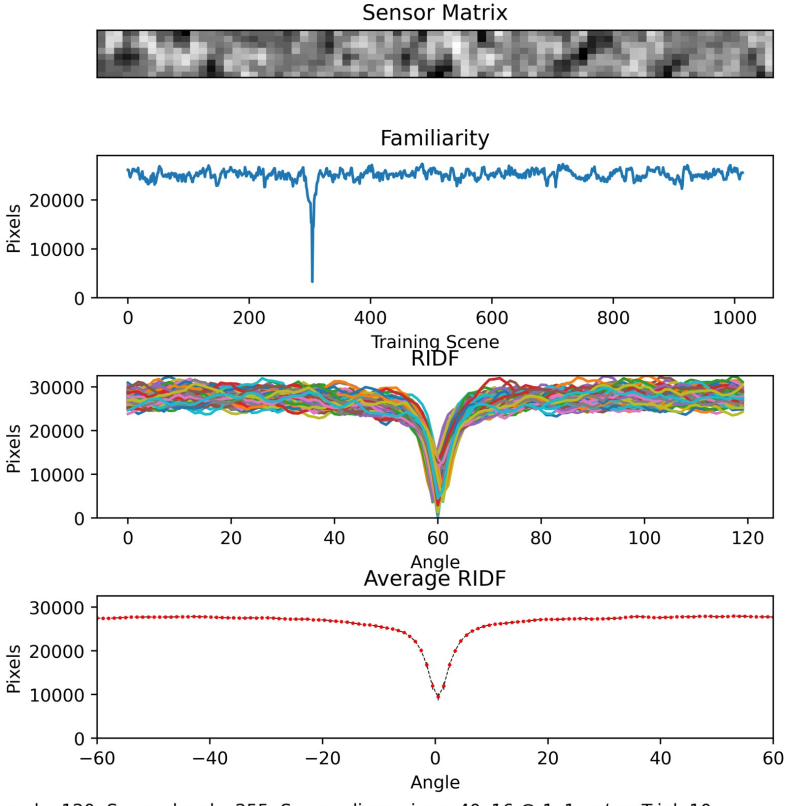
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 62.18; RMSD/dist: 0.155; TD: 12583; p90: 10; p50: 4; complete: 0



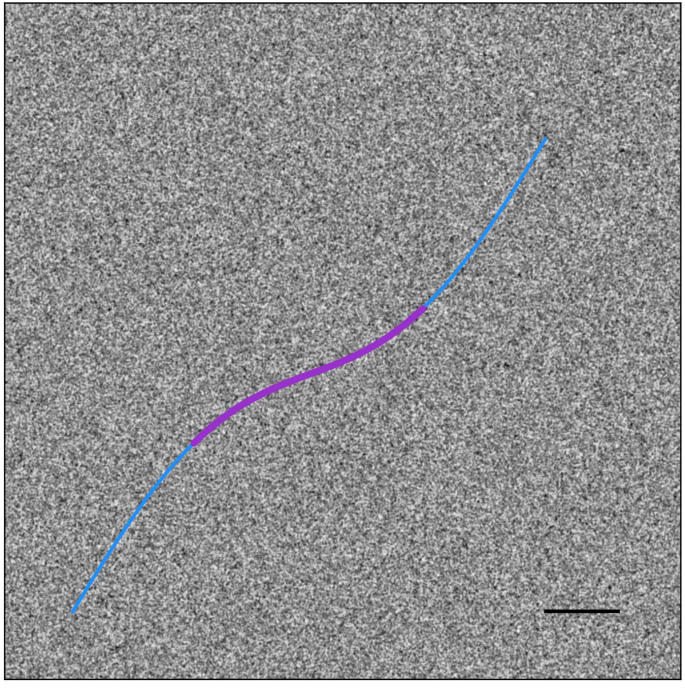


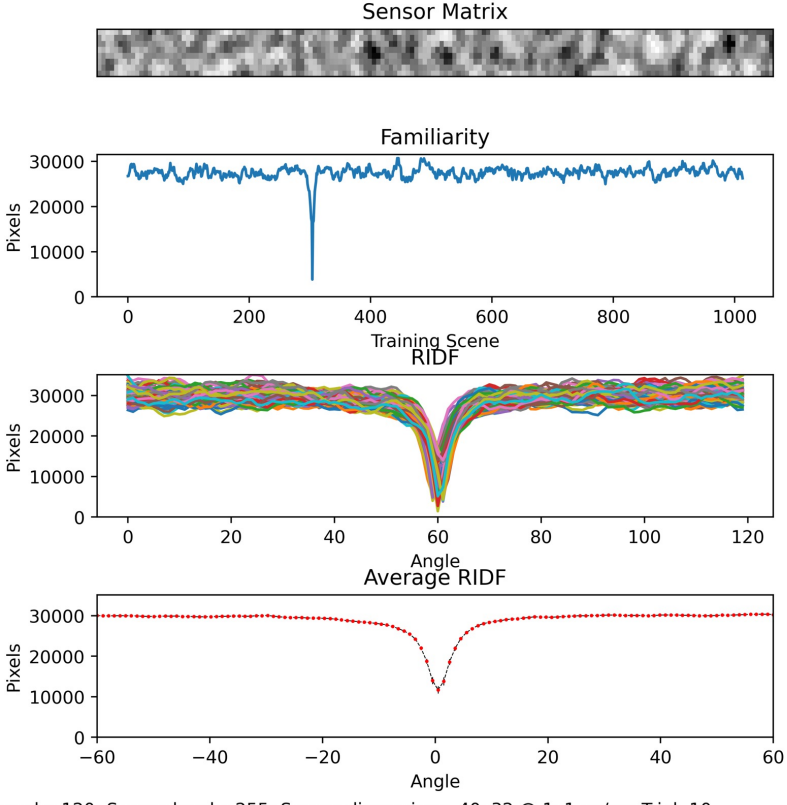
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 47.41; RMSD/dist: 0.119; TD: 13562; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 50.83; RMSD/dist: 0.127; TD: 15636; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 57.29; RMSD/dist: 0.143; TD: 15754; p90: 12; p50: 4; complete: 0