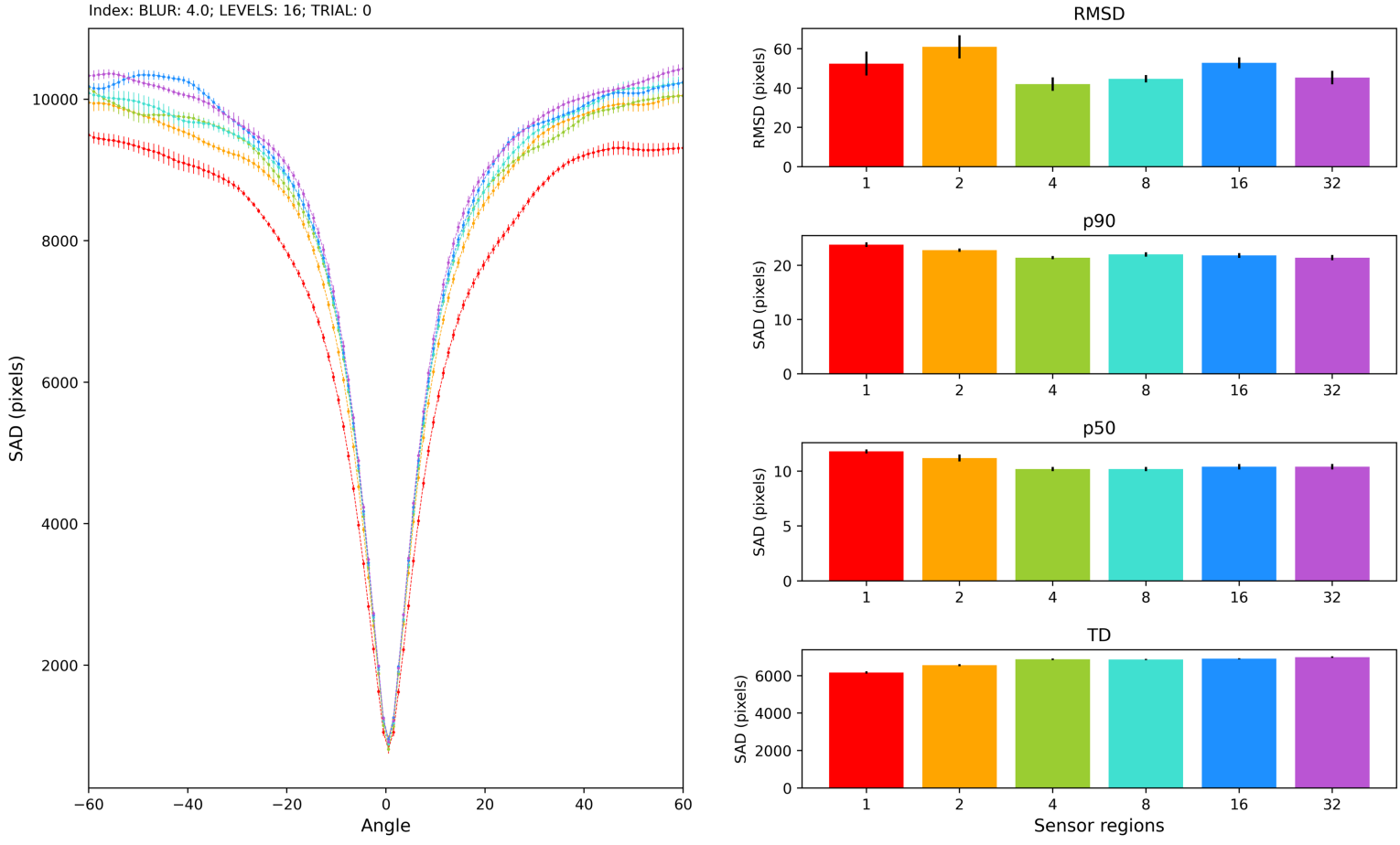
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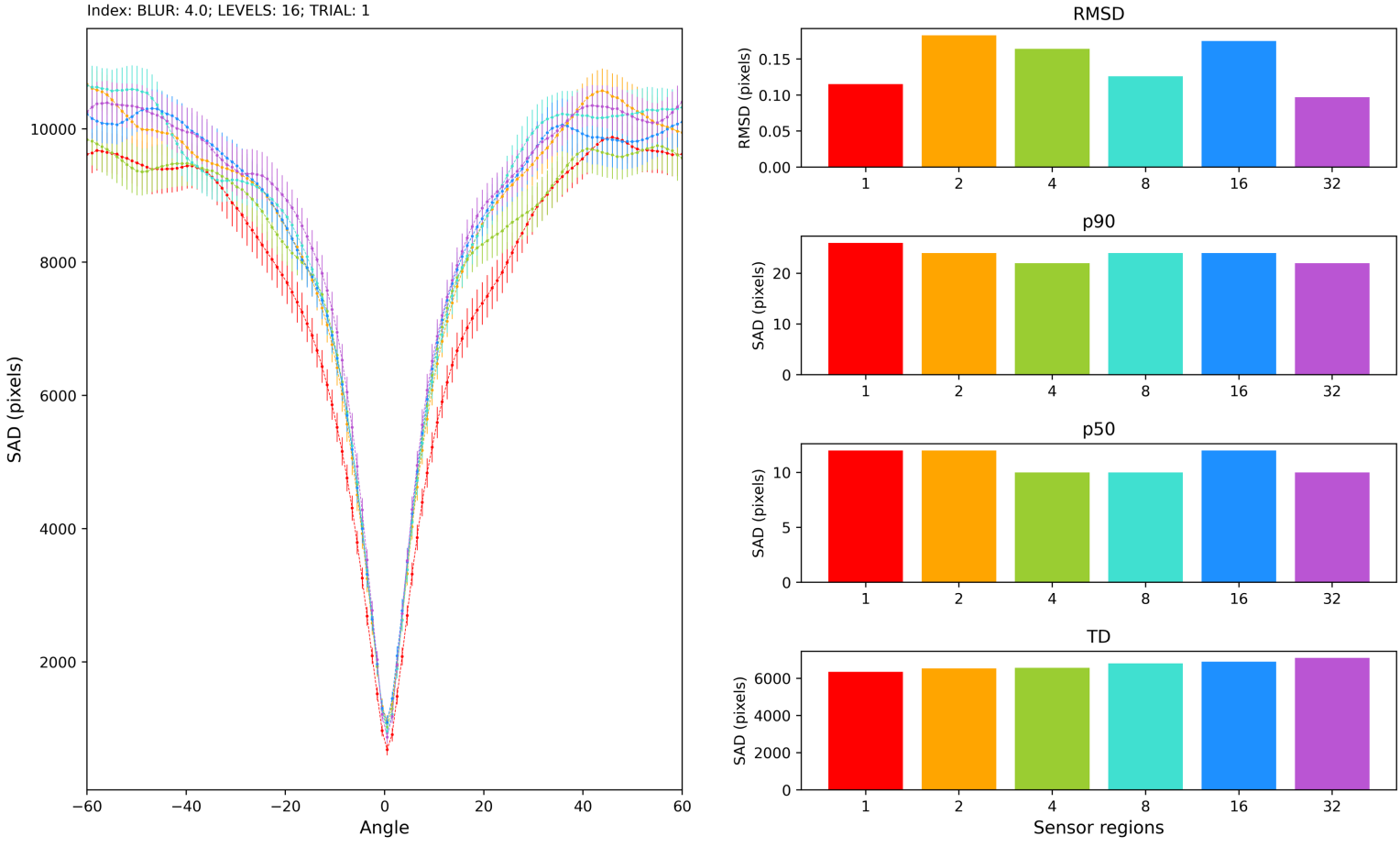
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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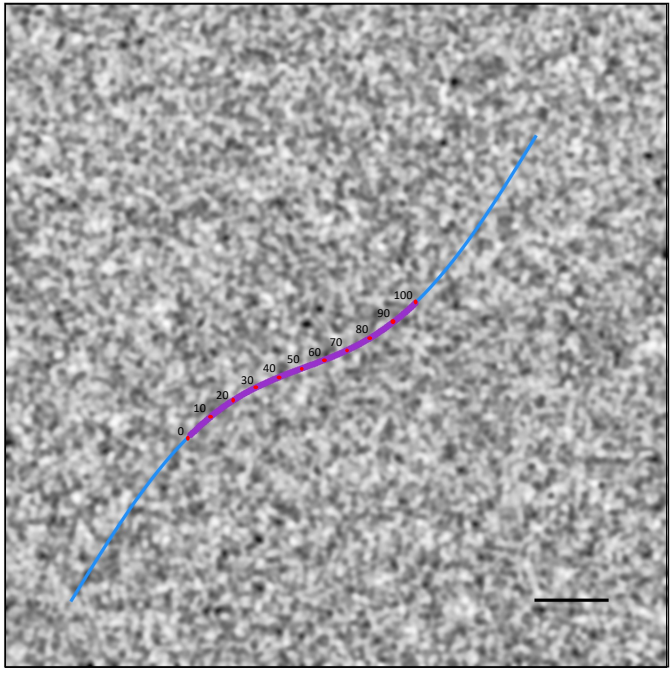
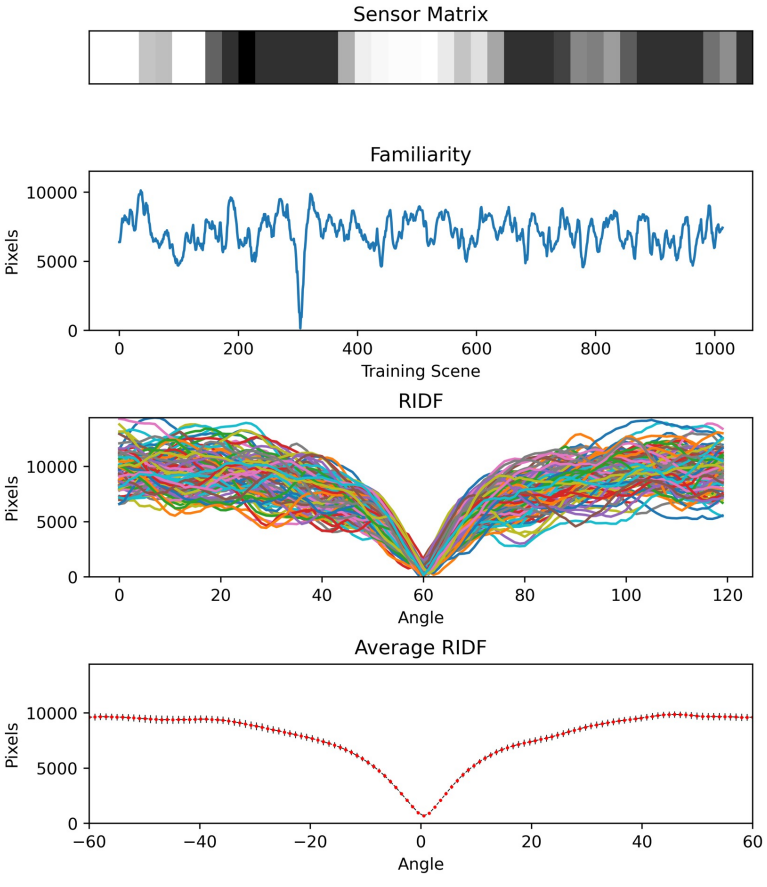
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

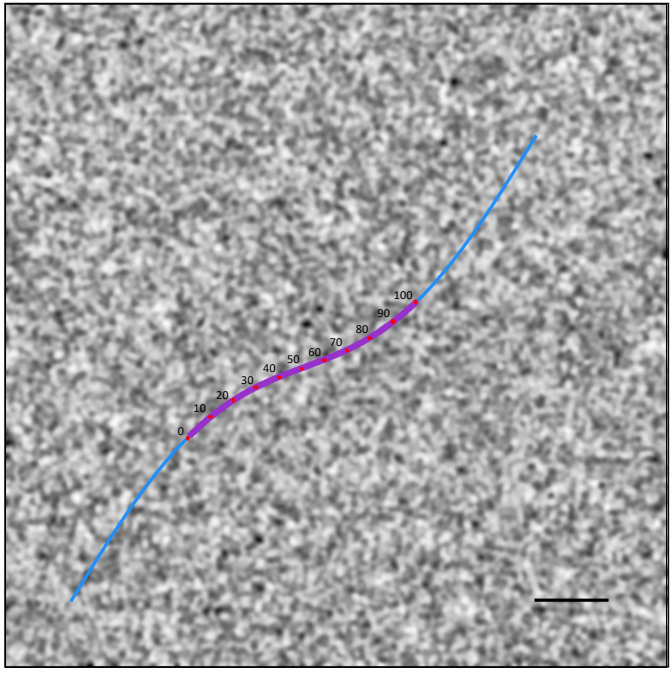


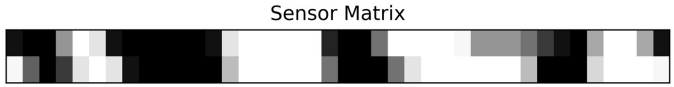



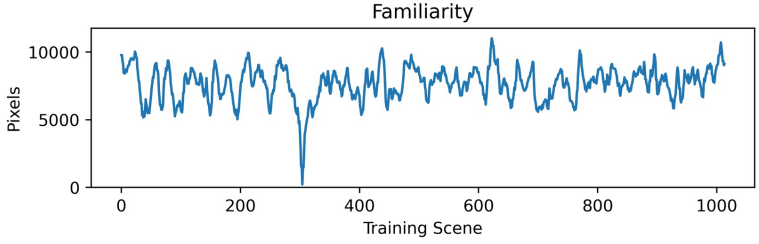

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

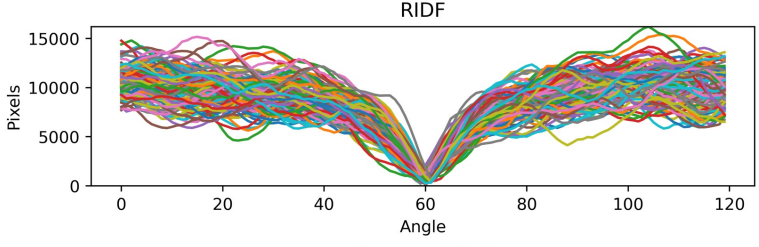
Navigation stats: RMSD error: 45.98; RMSD/dist: 0.115; TD: 6352; p90: 26; p50: 12; complete: 0

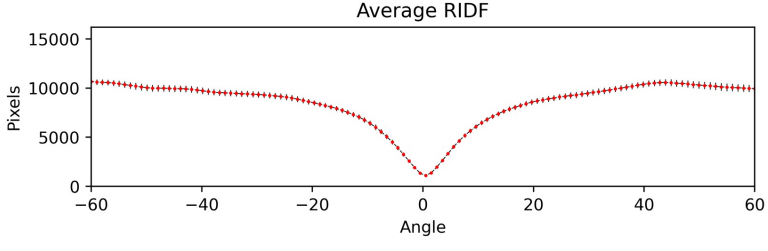
100%



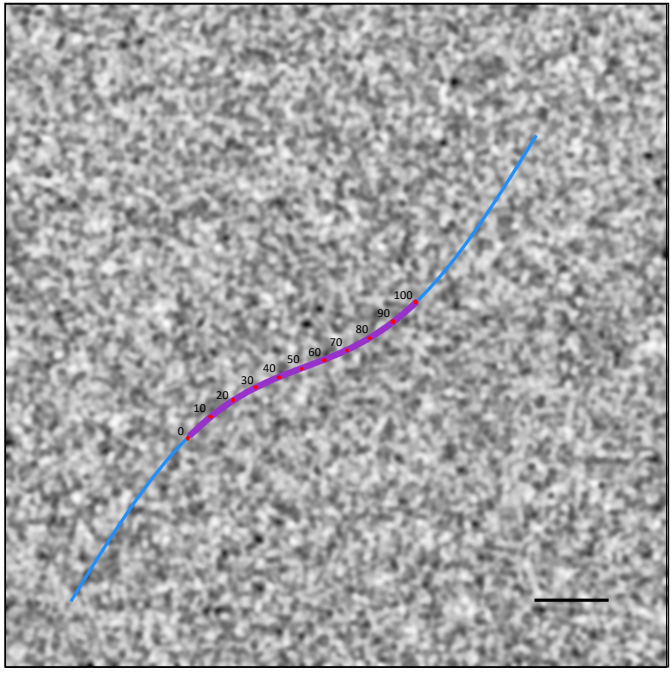



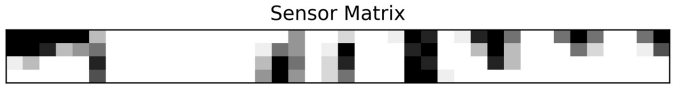



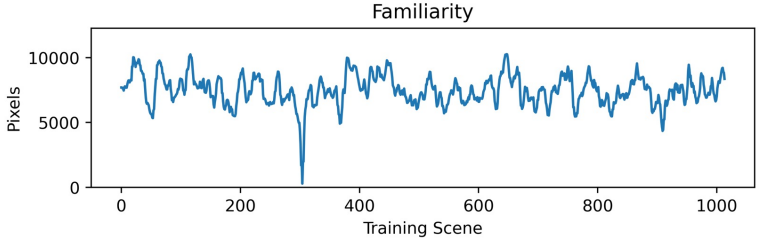

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

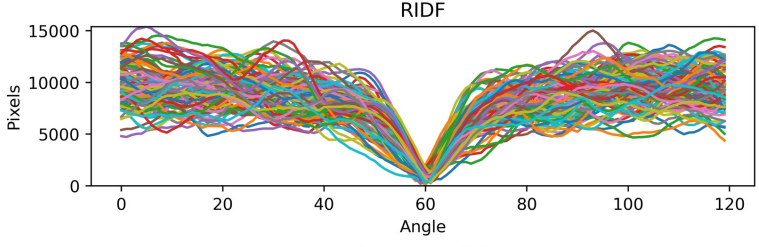
Navigation stats: RMSD error: 73.03; RMSD/dist: 0.183; TD: 6531; p90: 24; p50: 12; complete: 0

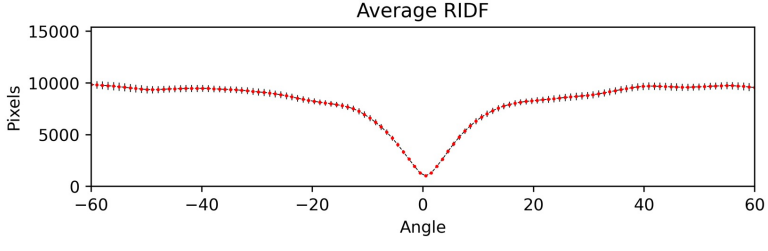
100%



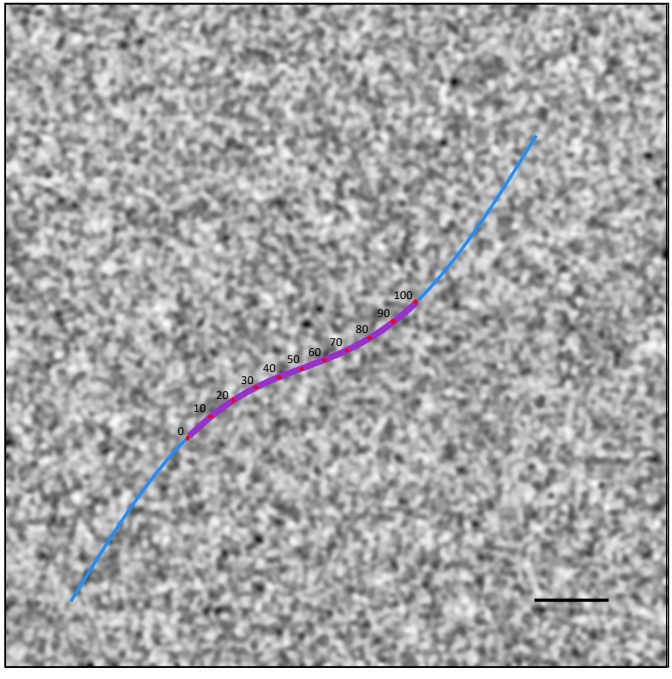



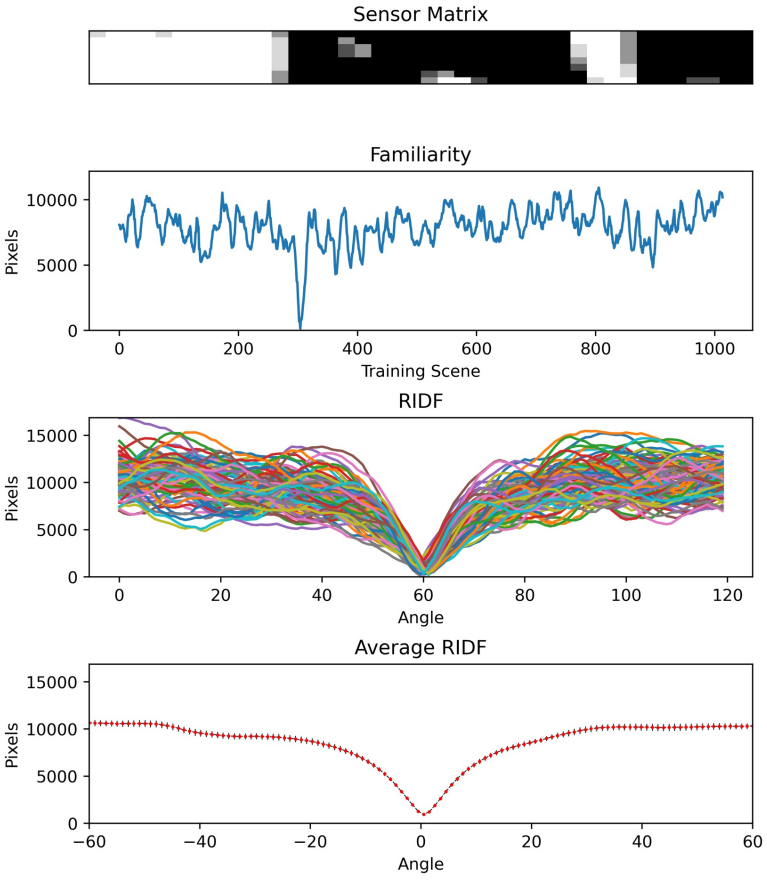




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 65.68; RMSD/dist: 0.164; TD: 6562; p90: 22; p50: 10; complete: 0

100%

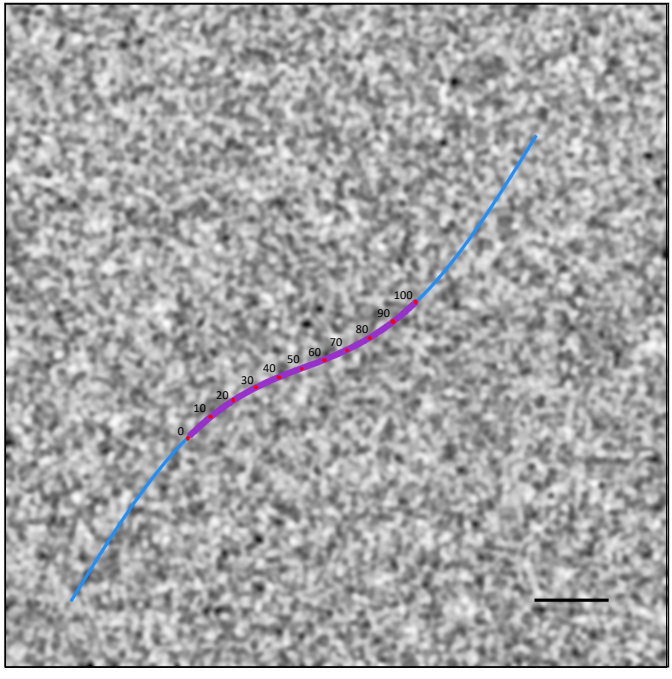


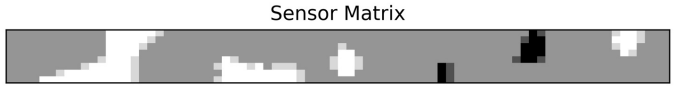



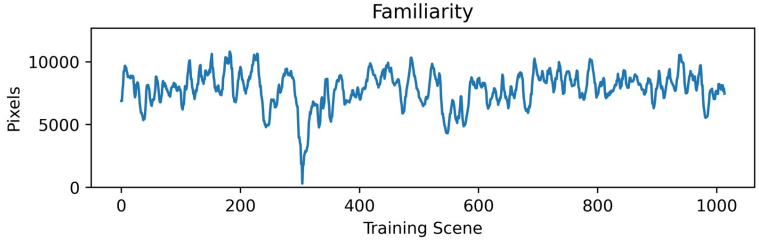

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

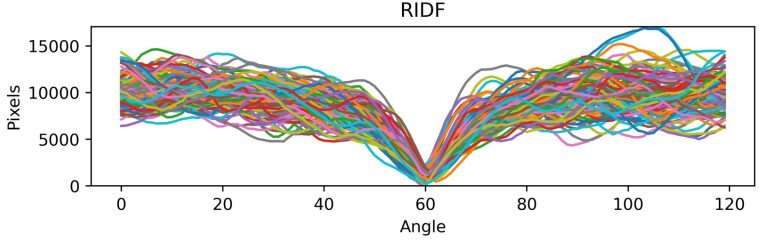
Navigation stats: RMSD error: 50.48; RMSD/dist: 0.126; TD: 6807; p90: 24; p50: 10; complete: 0

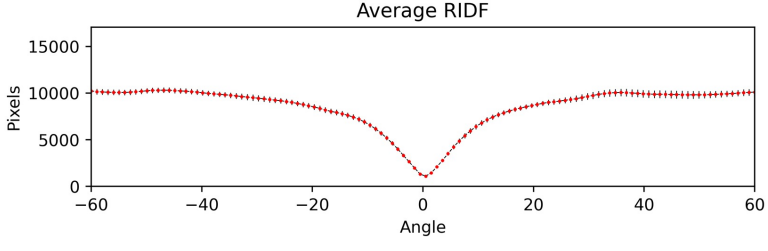
100%



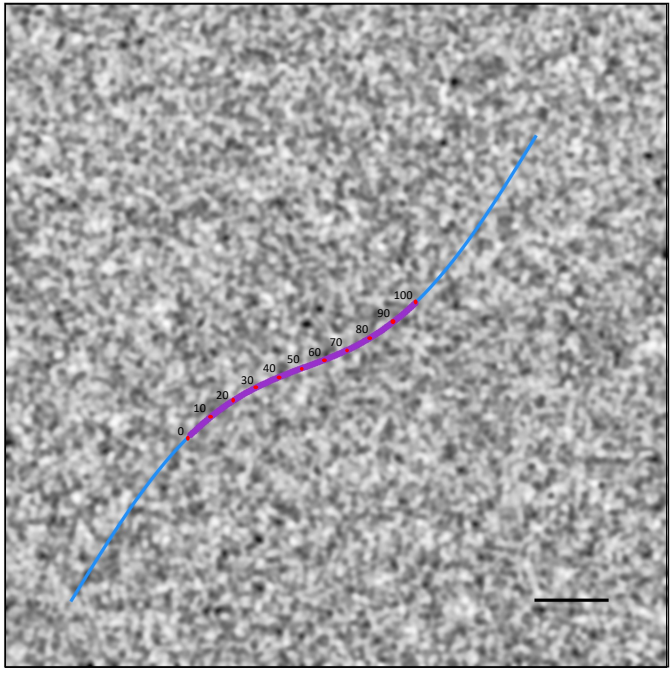



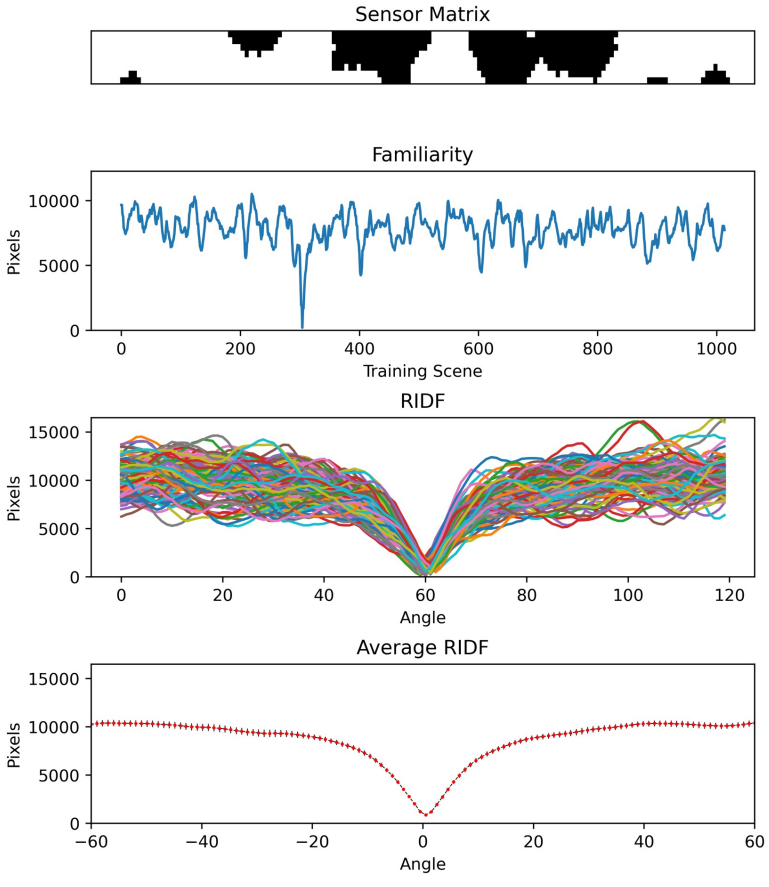




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 70.13; RMSD/dist: 0.175; TD: 6895; p90: 24; p50: 12; complete: 0

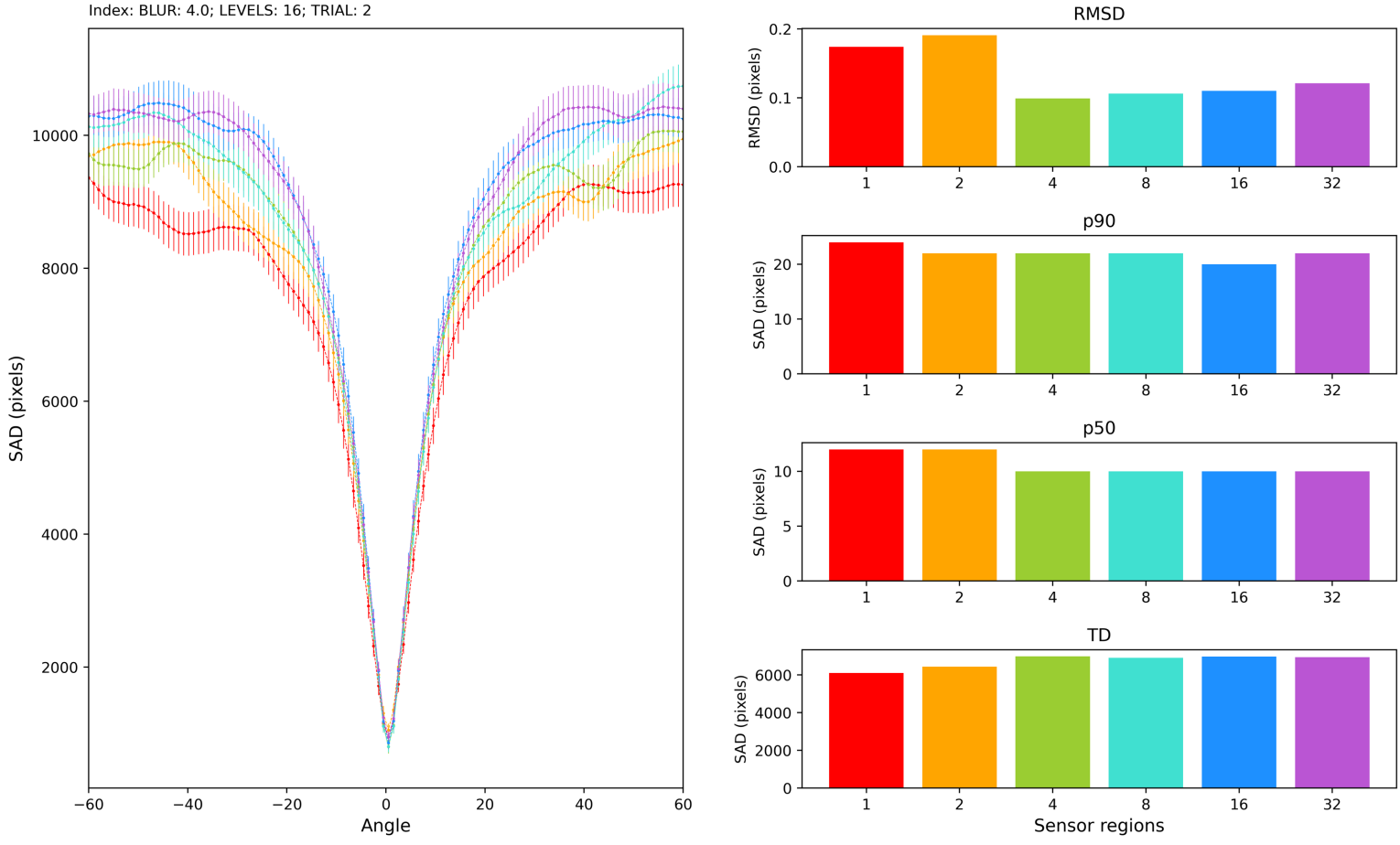
100%



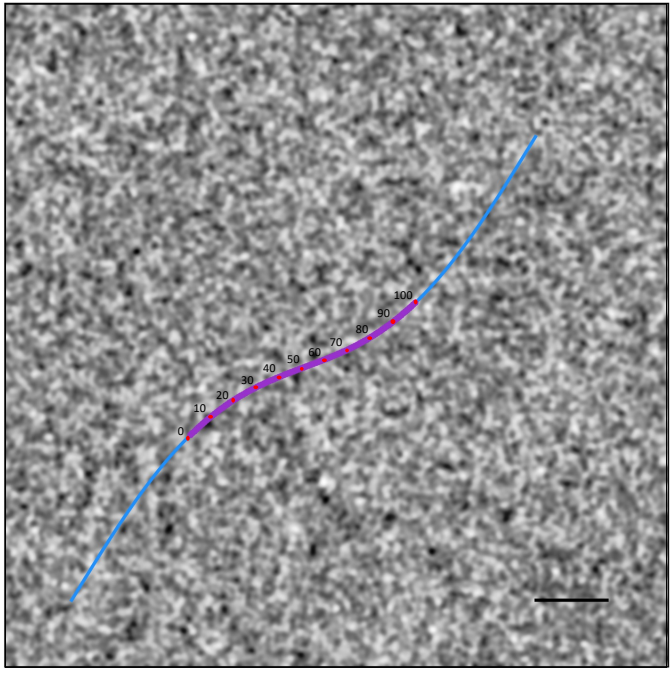



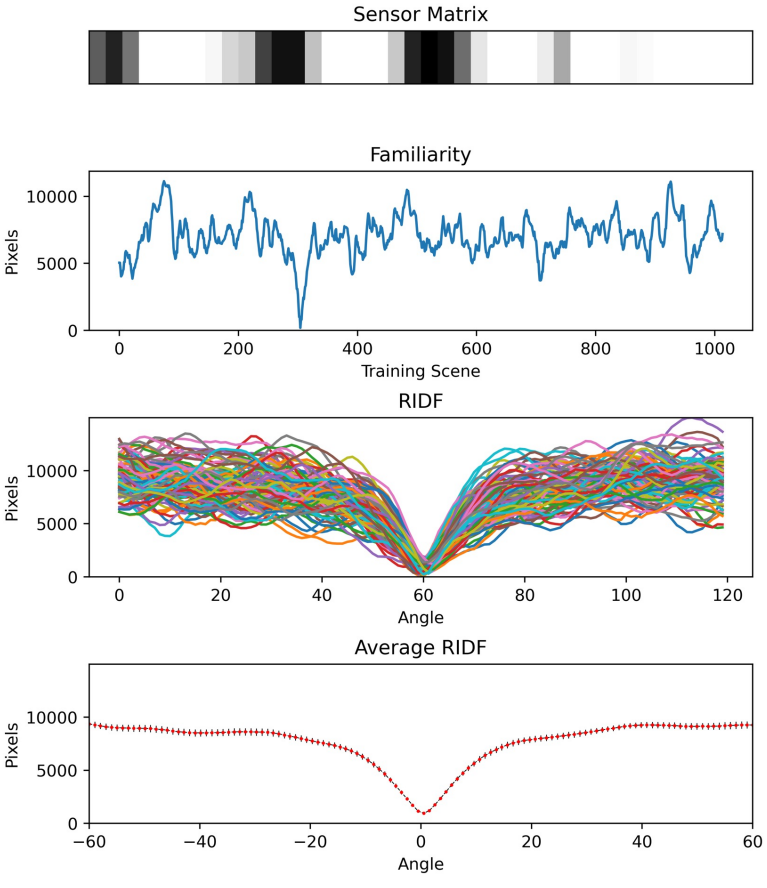

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 38.66; RMSD/dist: 0.097; TD: 7092; p90: 22; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 16; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

100%

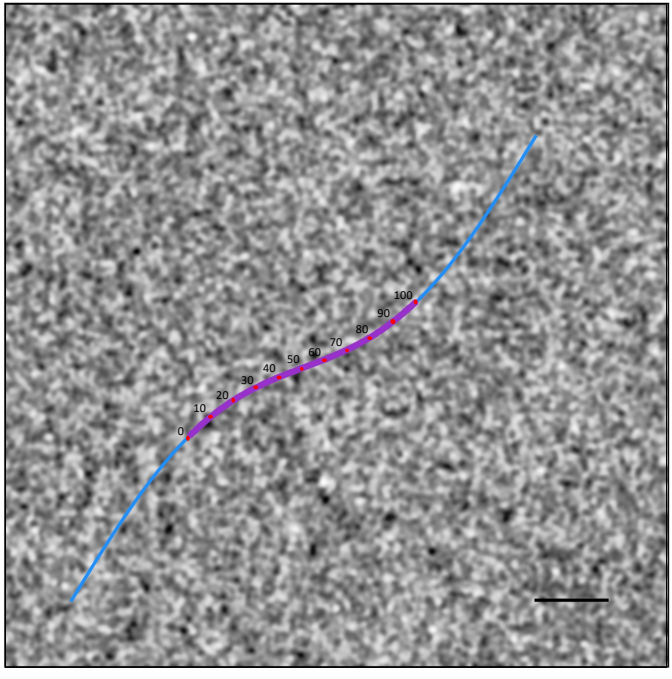


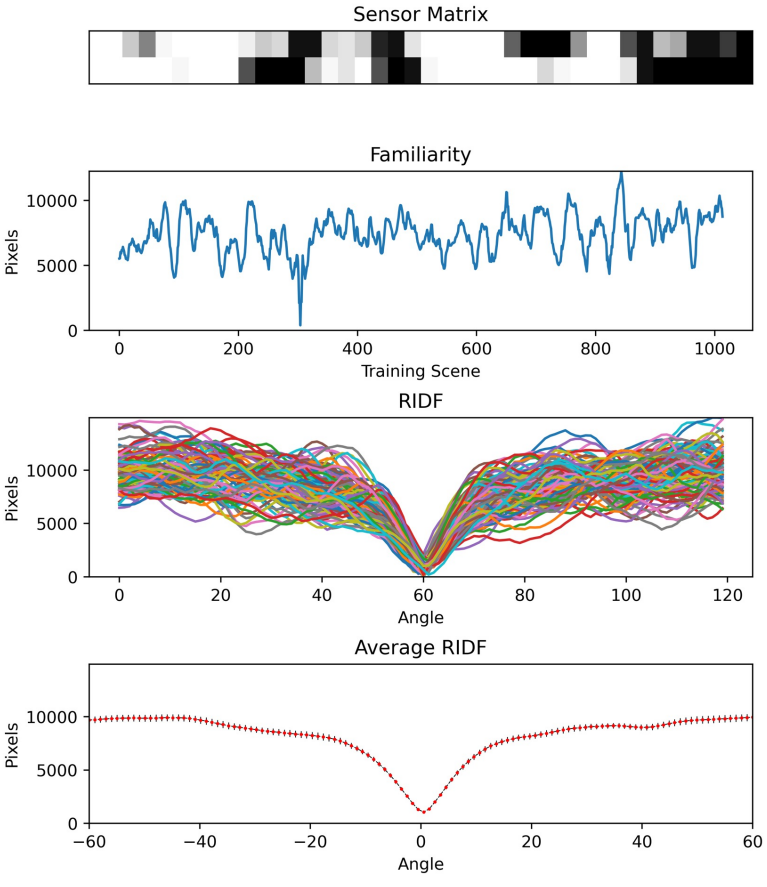




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 69.67; RMSD/dist: 0.174; TD: 6103; p90: 24; p50: 12; complete: 0

100%

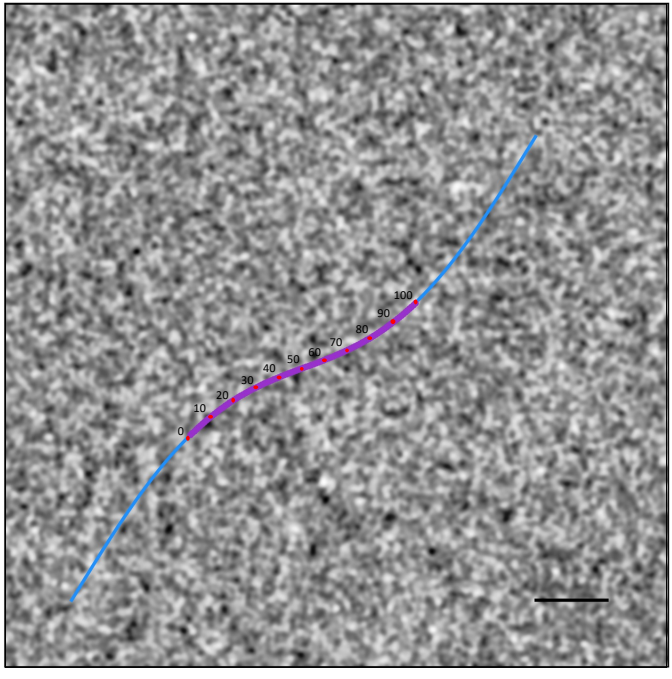


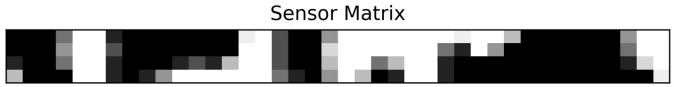



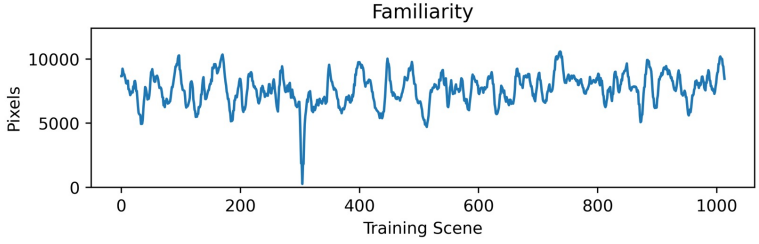

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

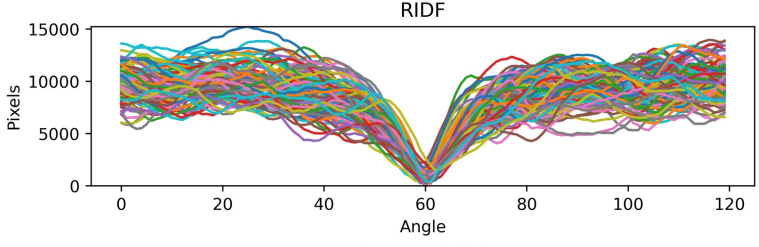
Navigation stats: RMSD error: 76.53; RMSD/dist: 0.191; TD: 6441; p90: 22; p50: 12; complete: 0

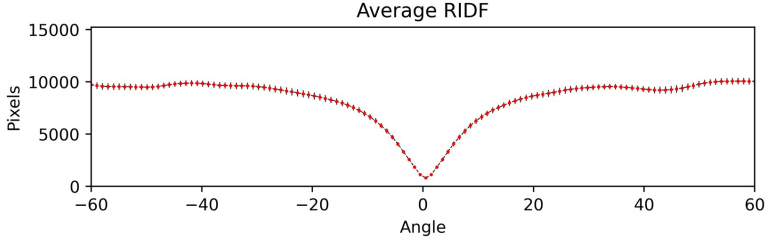
100%



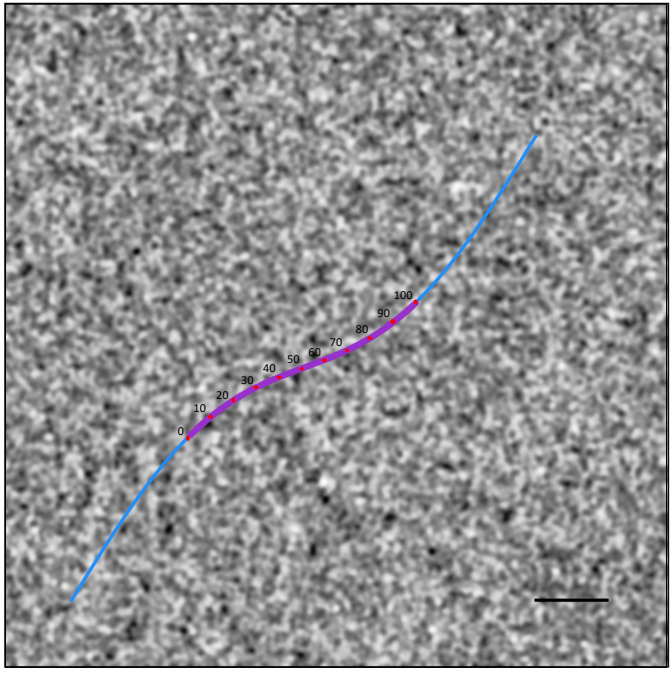



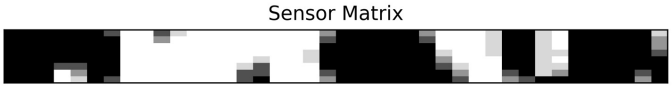



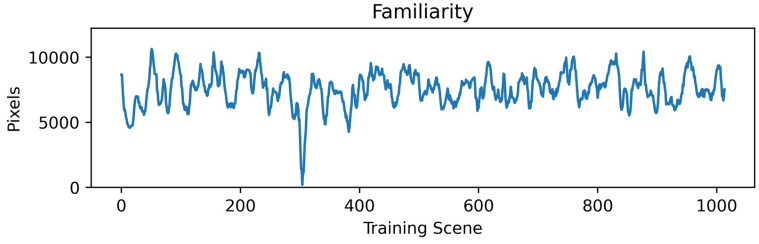

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

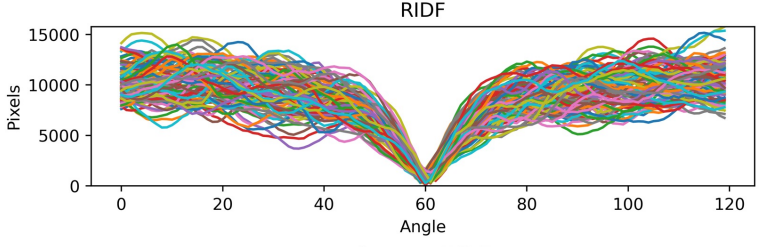
Navigation stats: RMSD error: 39.77; RMSD/dist: 0.099; TD: 6982; p90: 22; p50: 10; complete: 0

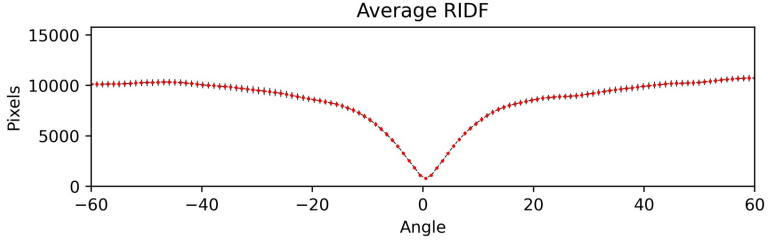
100%



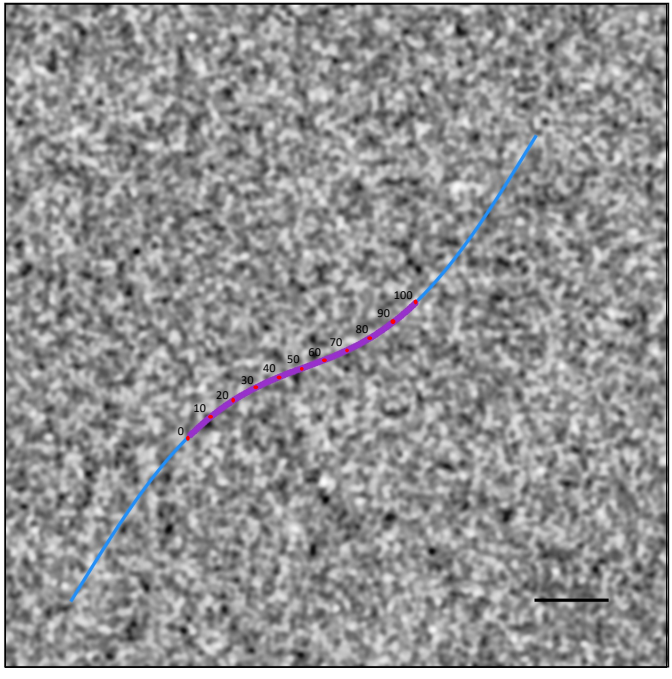



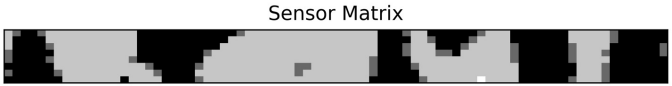



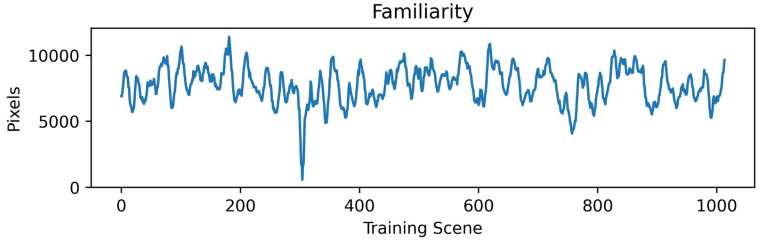

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

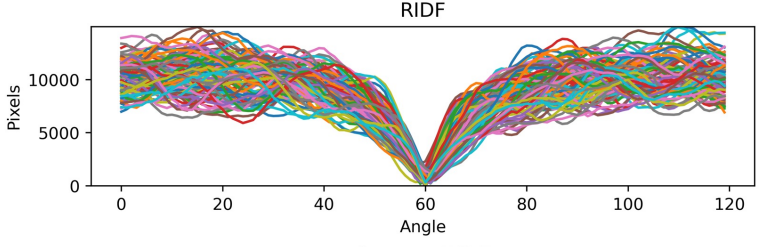
Navigation stats: RMSD error: 42.38; RMSD/dist: 0.106; TD: 6905; p90: 22; p50: 10; complete: 0

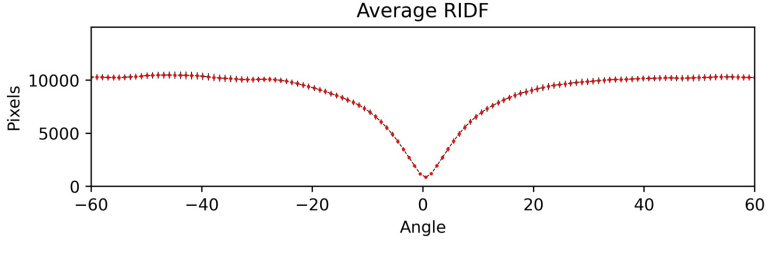
100%



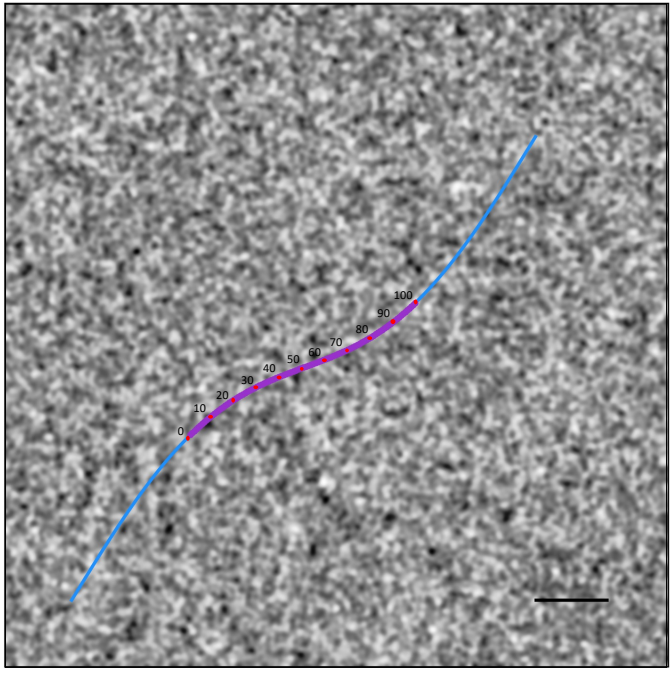



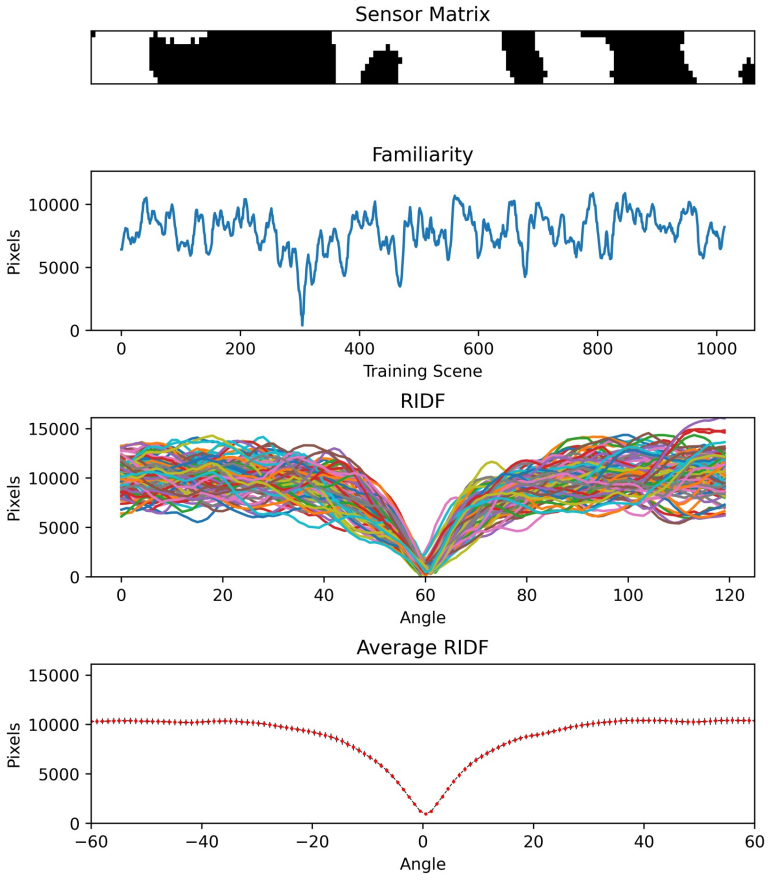




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 43.84; RMSD/dist: 0.110; TD: 6974; p90: 20; p50: 10; complete: 0

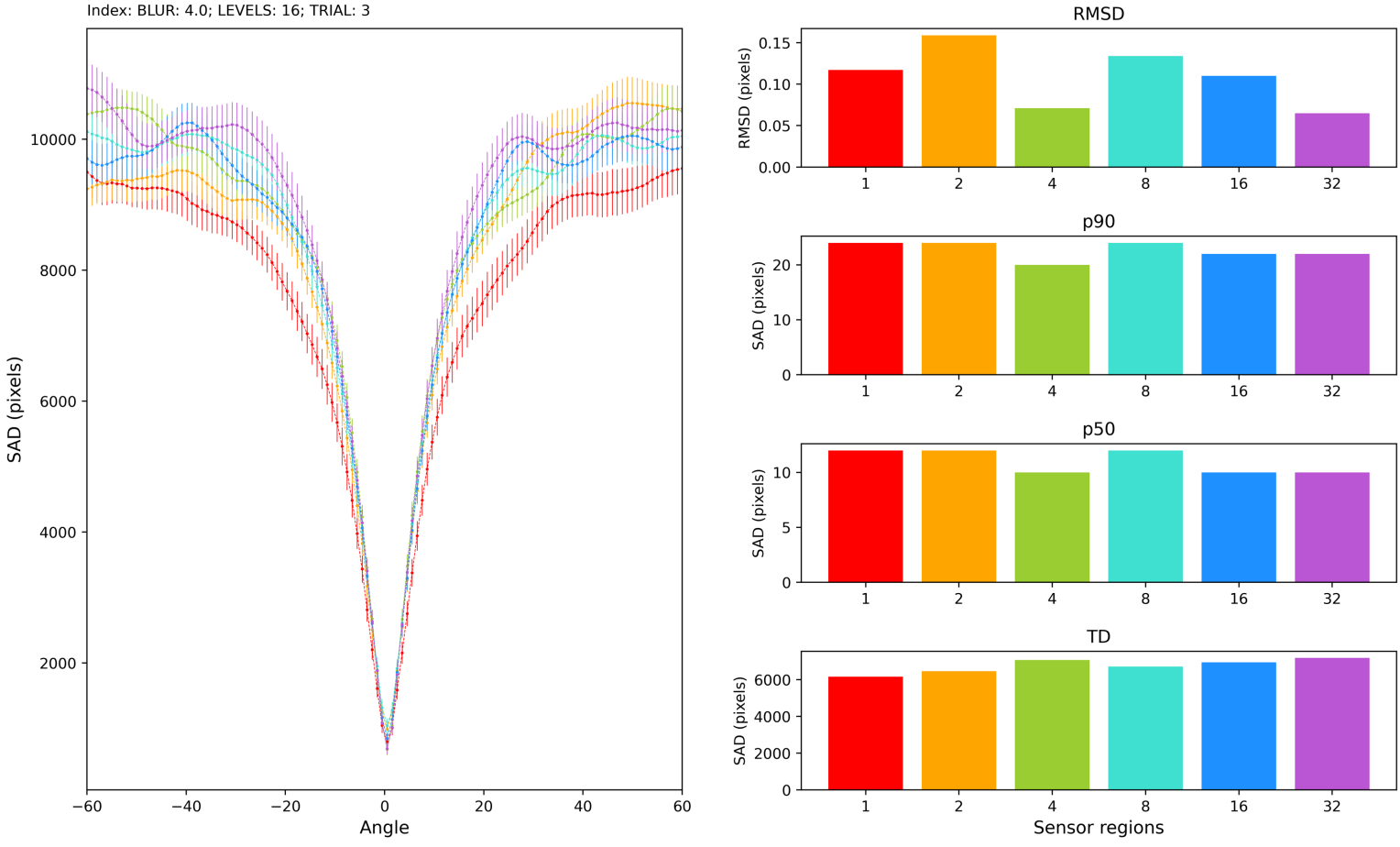
100%



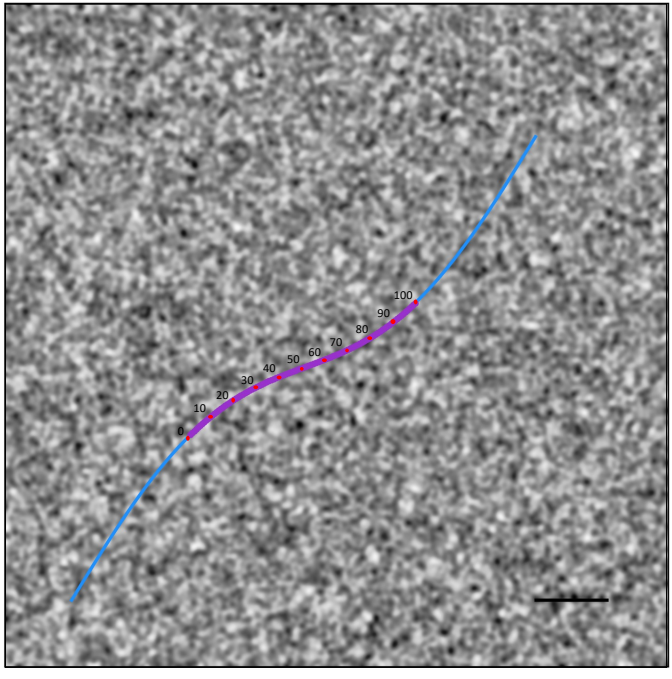



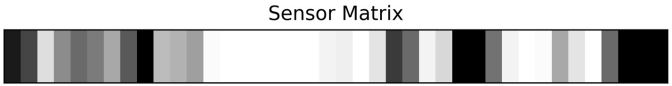

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

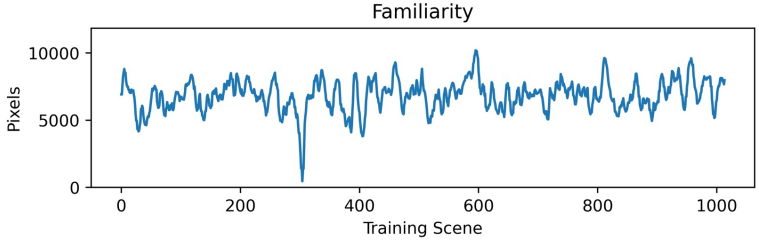
Navigation stats: RMSD error: 48.43; RMSD/dist: 0.121; TD: 6939; p90: 22; p50: 10; complete: 0

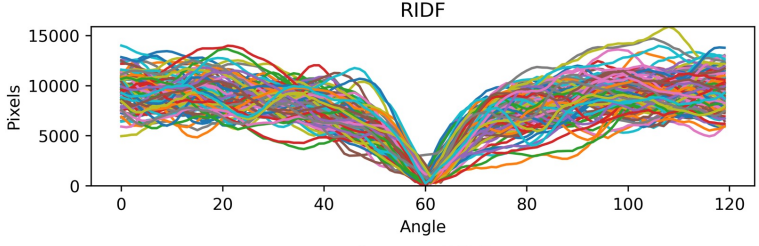

Index: BLUR: 4.0; LEVELS: 16; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

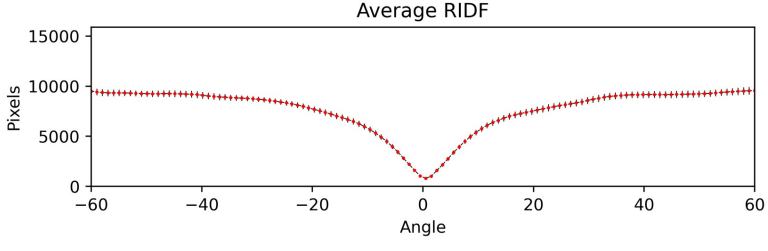
100%



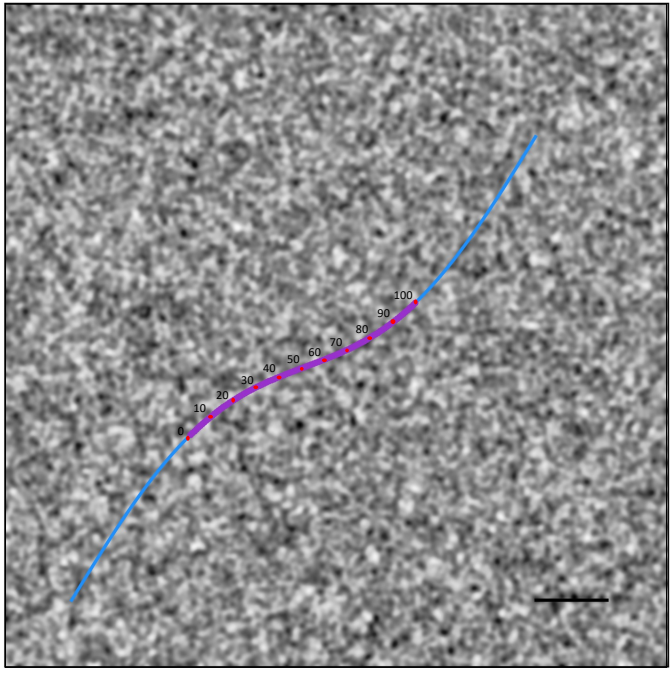



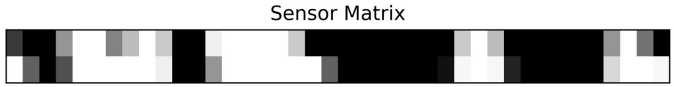



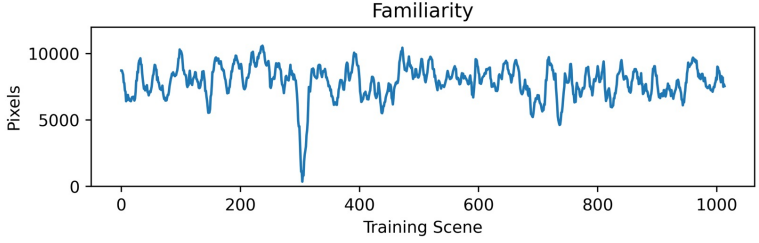

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

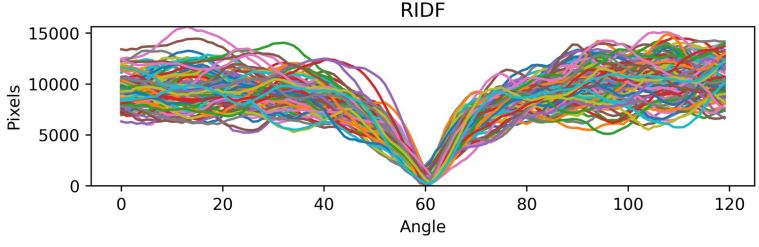
Navigation stats: RMSD error: 46.88; RMSD/dist: 0.117; TD: 6169; p90: 24; p50: 12; complete: 0

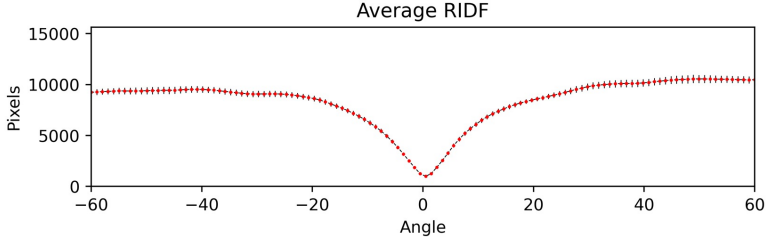
100%



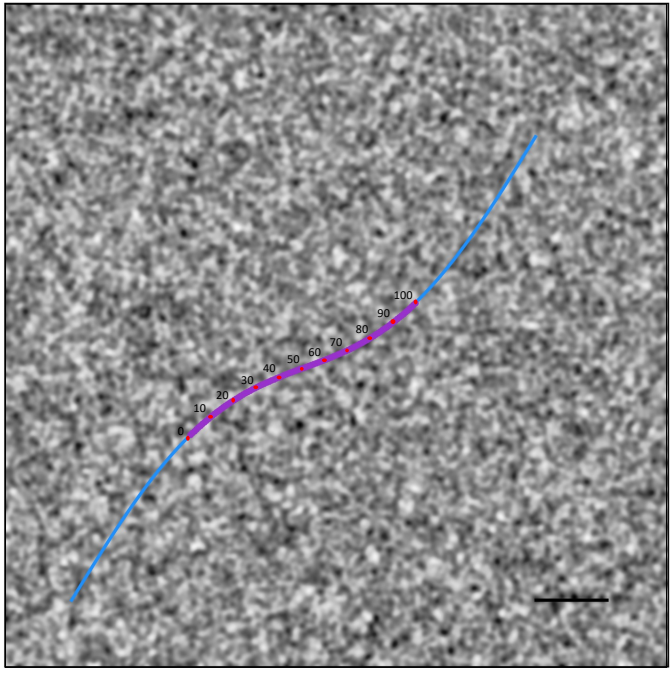



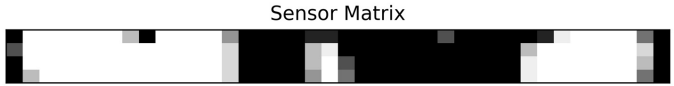



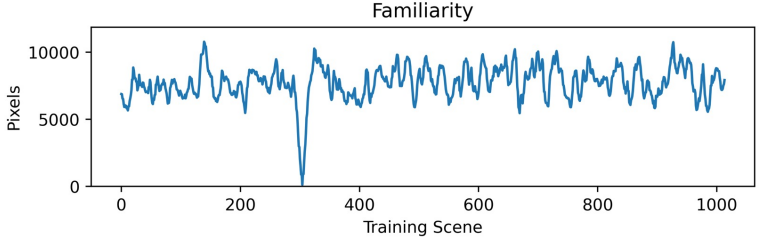

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

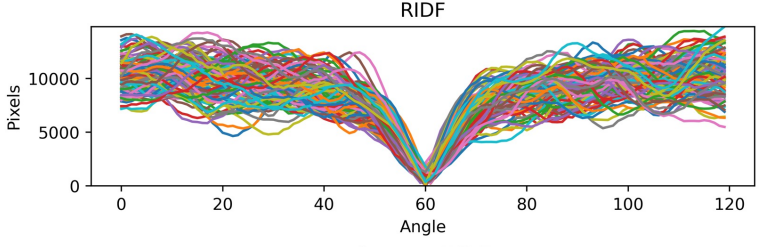
Navigation stats: RMSD error: 63.72; RMSD/dist: 0.159; TD: 6466; p90: 24; p50: 12; complete: 0

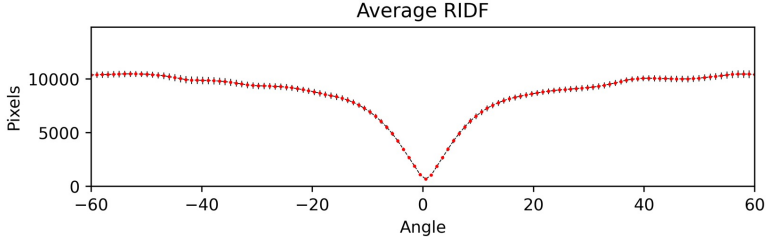
100%



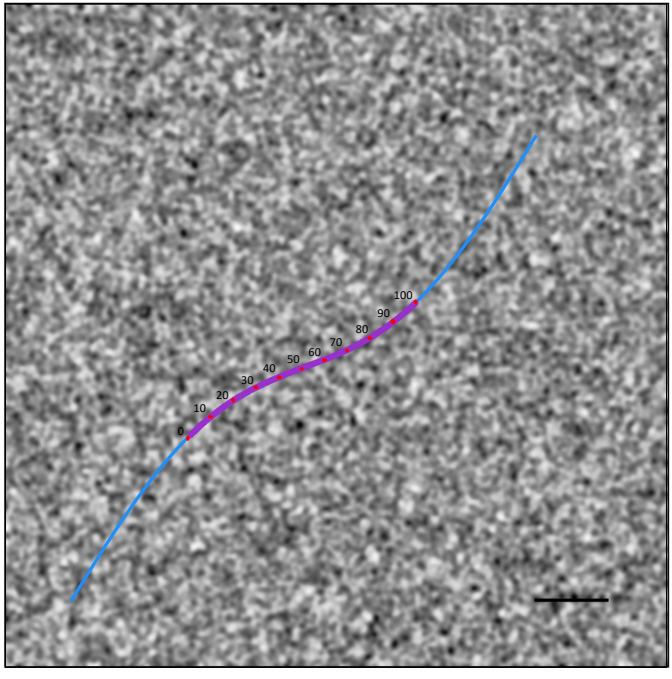



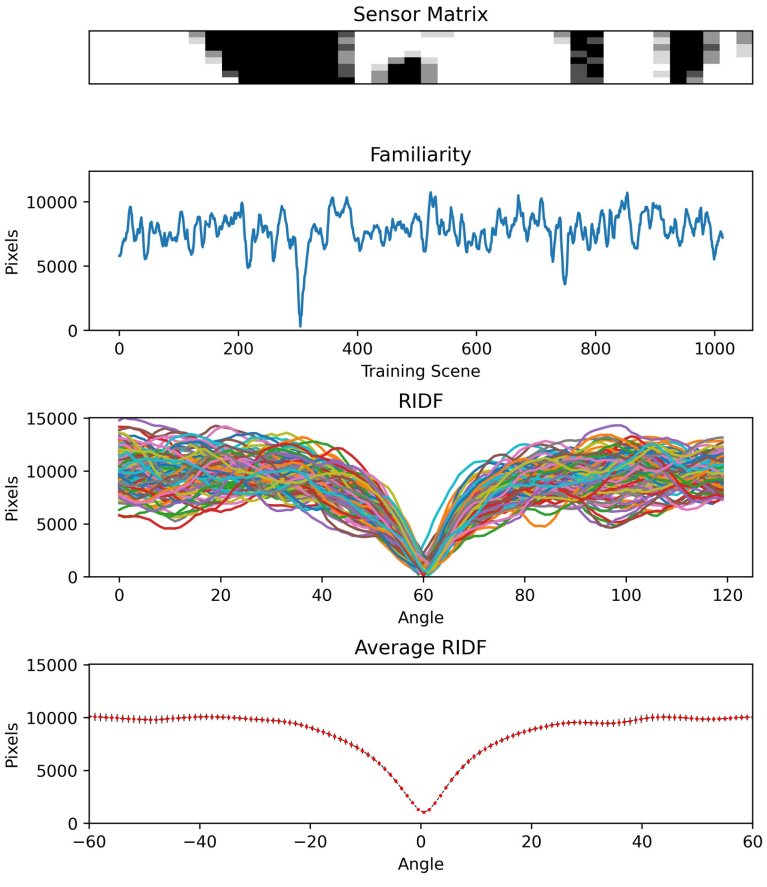




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 28.45; RMSD/dist: 0.071; TD: 7072; p90: 20; p50: 10; complete: 0

100%

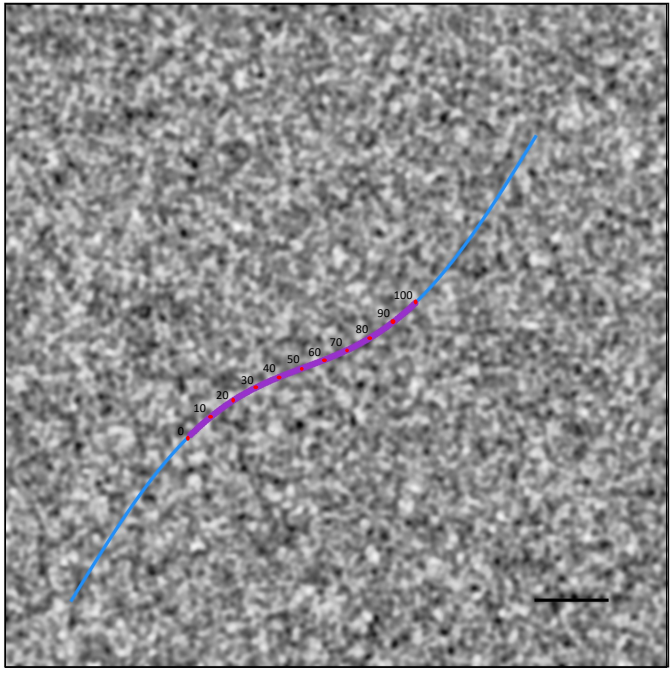


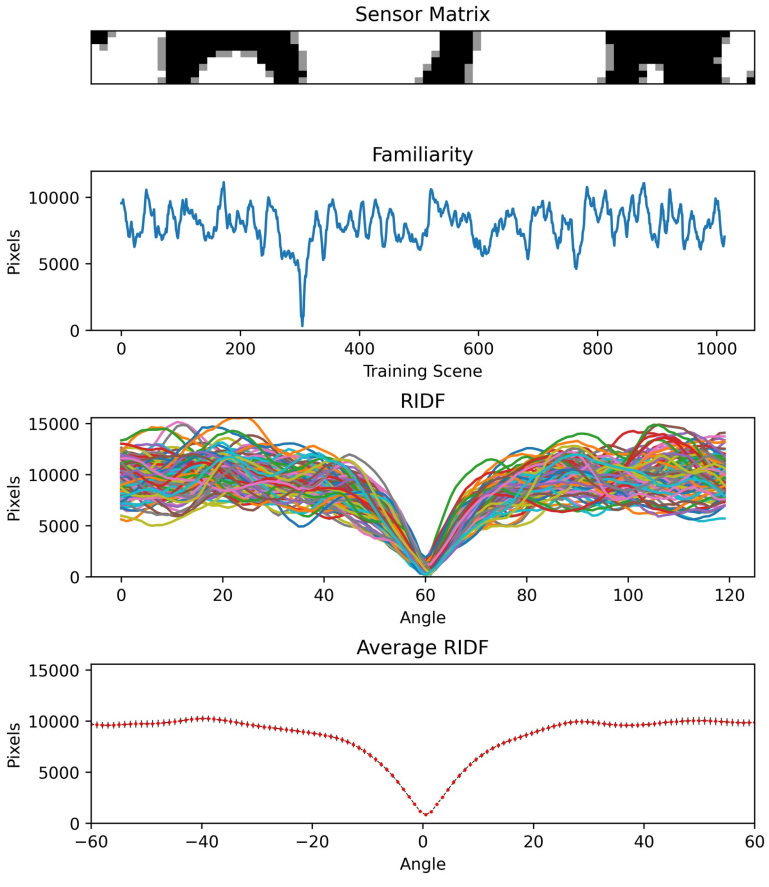




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 53.61; RMSD/dist: 0.134; TD: 6722; p90: 24; p50: 12; complete: 0

100%

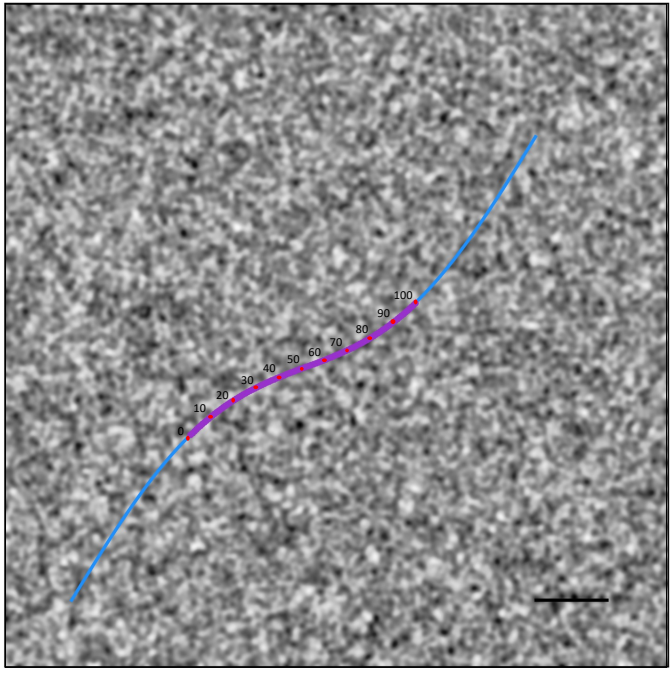


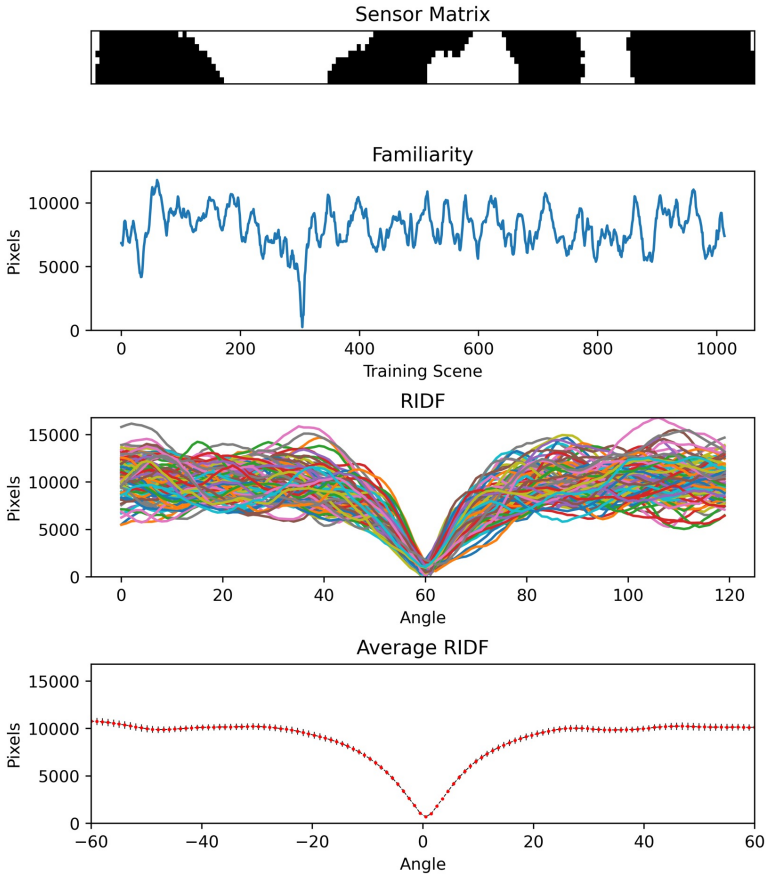




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 44.01; RMSD/dist: 0.110; TD: 6950; p90: 22; p50: 10; complete: 0

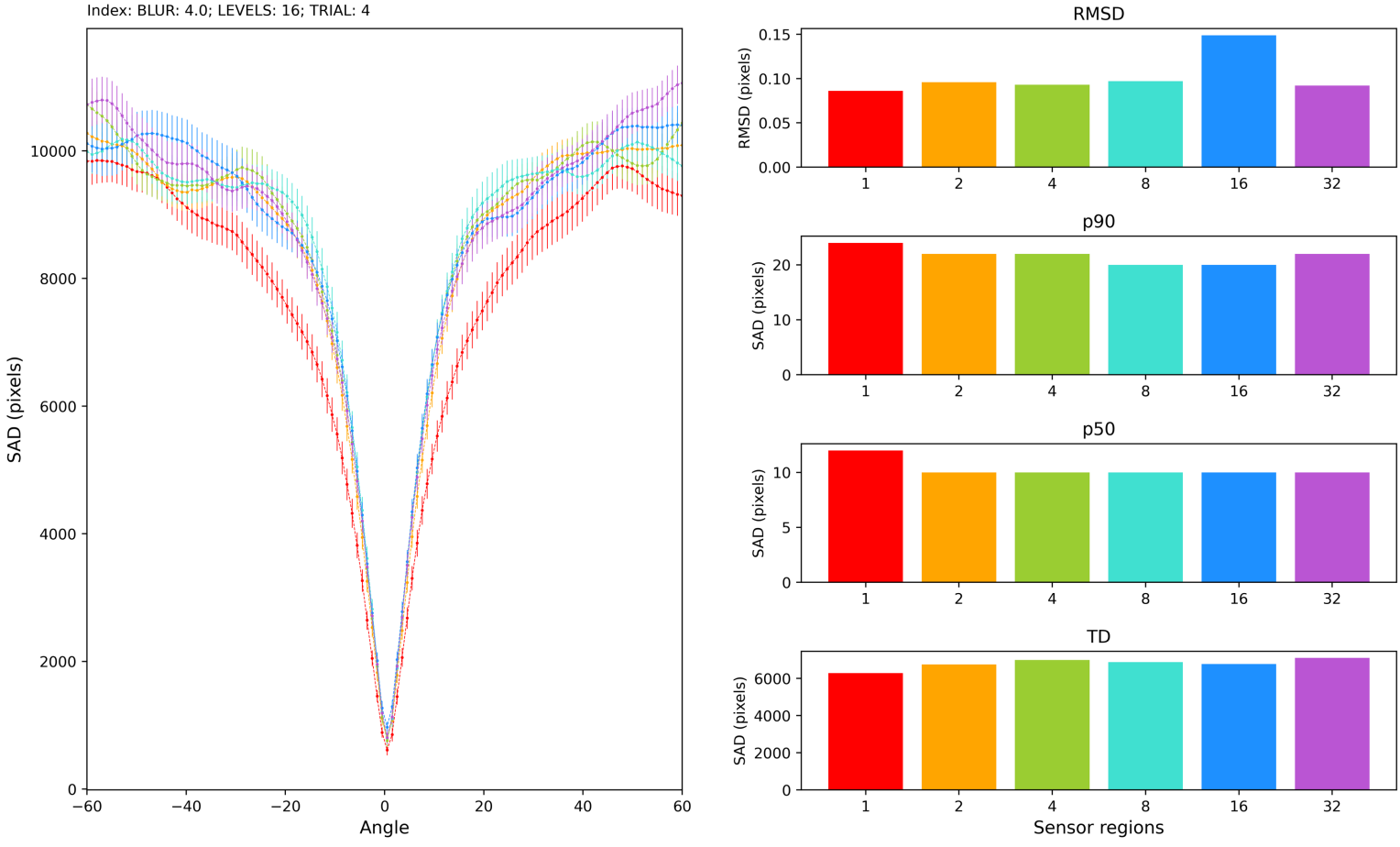
100%



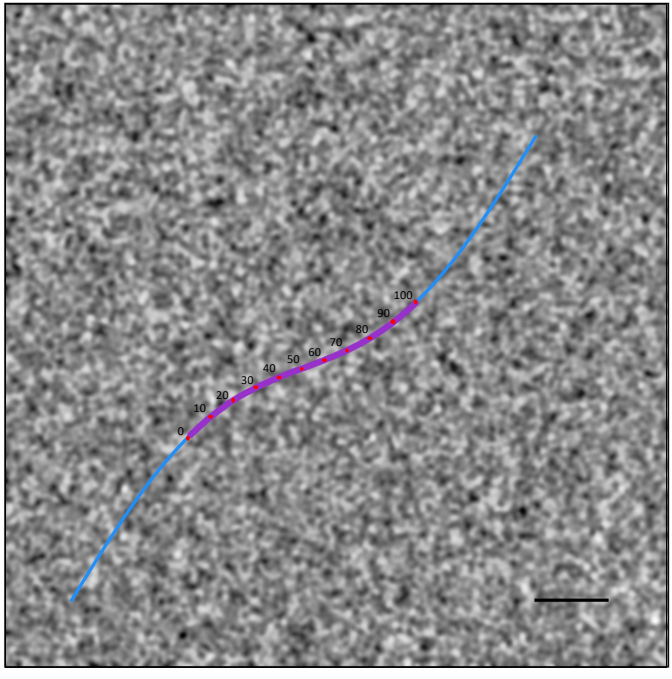



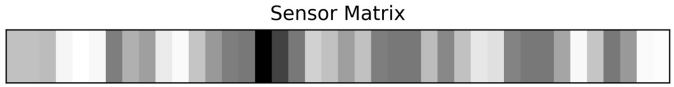

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

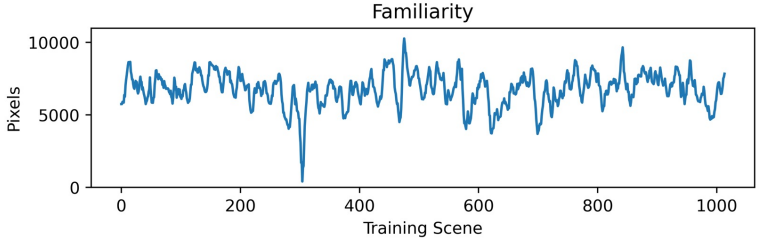
Navigation stats: RMSD error: 25.95; RMSD/dist: 0.065; TD: 7183; p90: 22; p50: 10; complete: 0

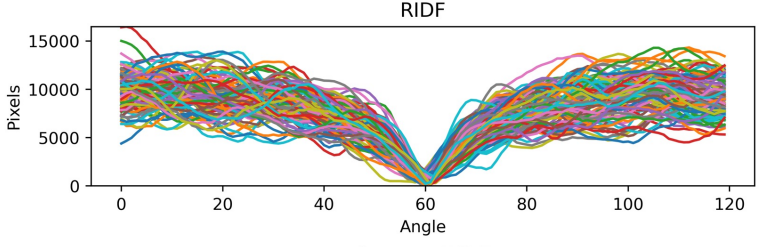

Index: BLUR: 4.0; LEVELS: 16; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

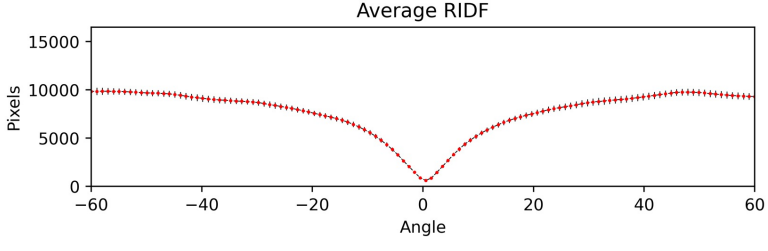
100%



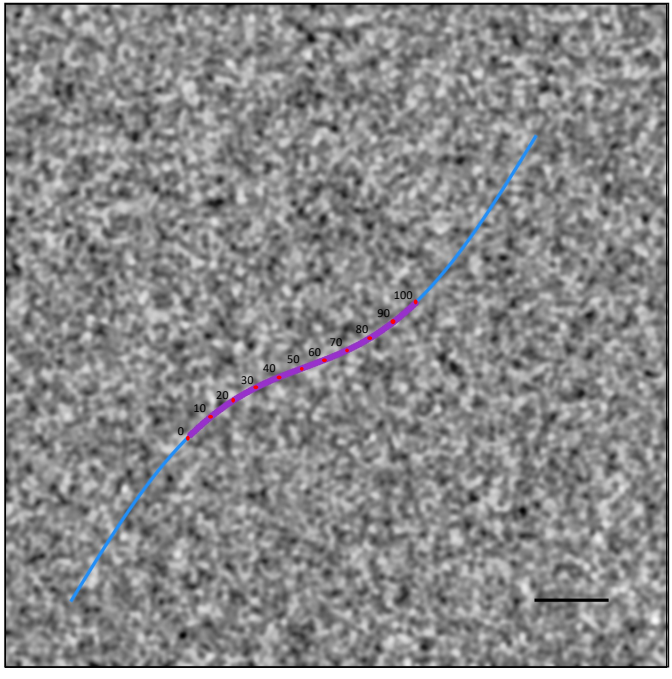



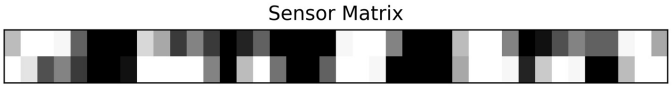



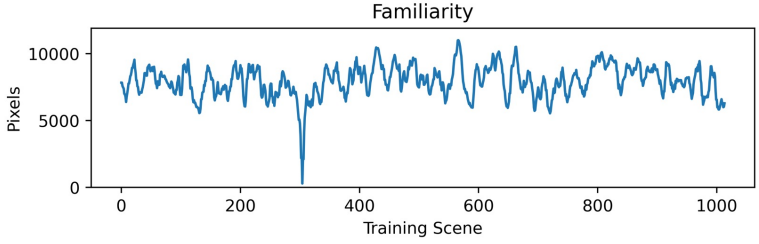

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

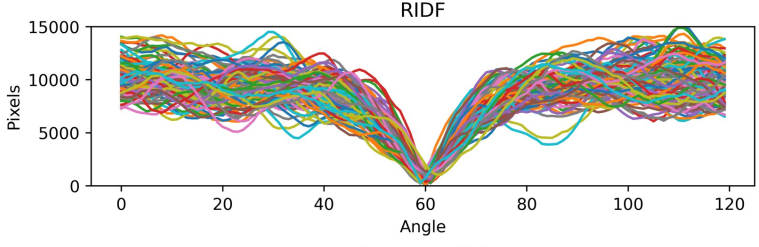
Navigation stats: RMSD error: 34.41; RMSD/dist: 0.086; TD: 6288; p90: 24; p50: 12; complete: 0

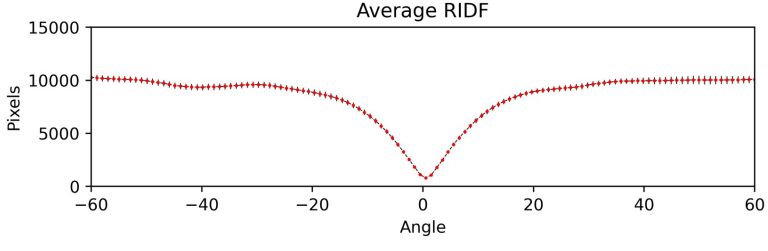
100%



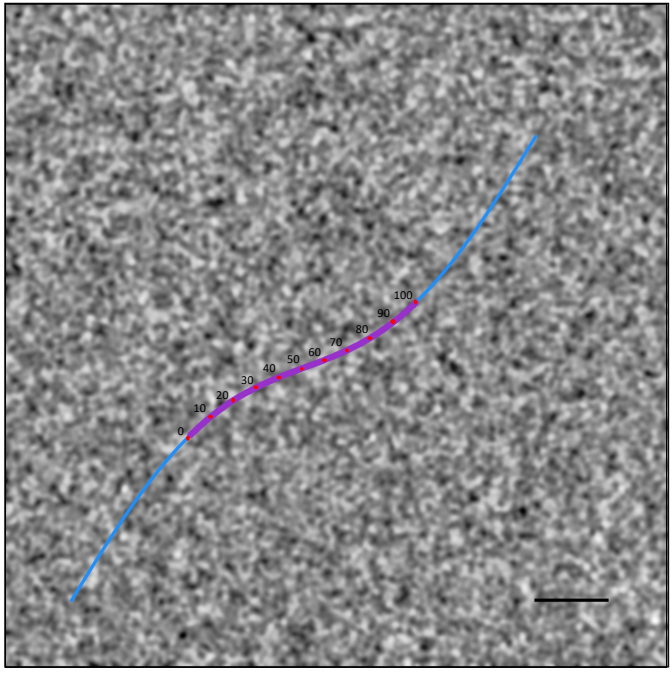



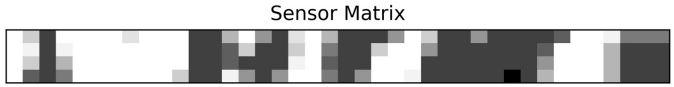



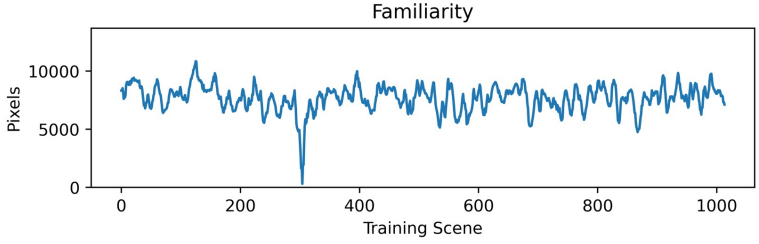

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

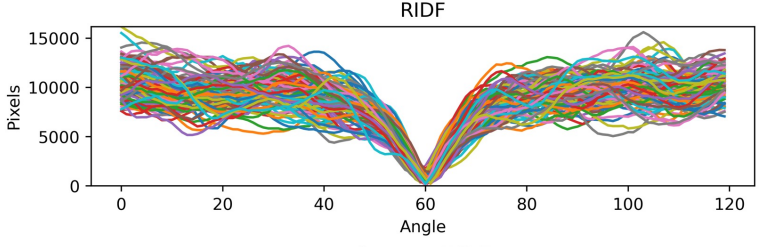
Navigation stats: RMSD error: 38.27; RMSD/dist: 0.096; TD: 6748; p90: 22; p50: 10; complete: 0

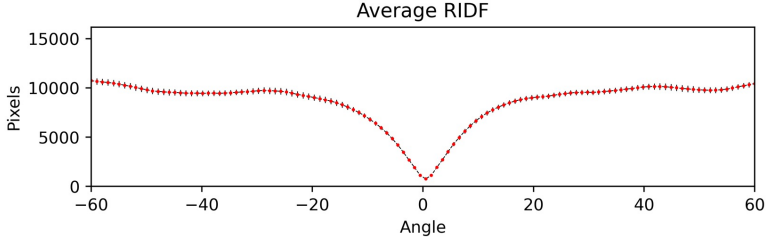
100%



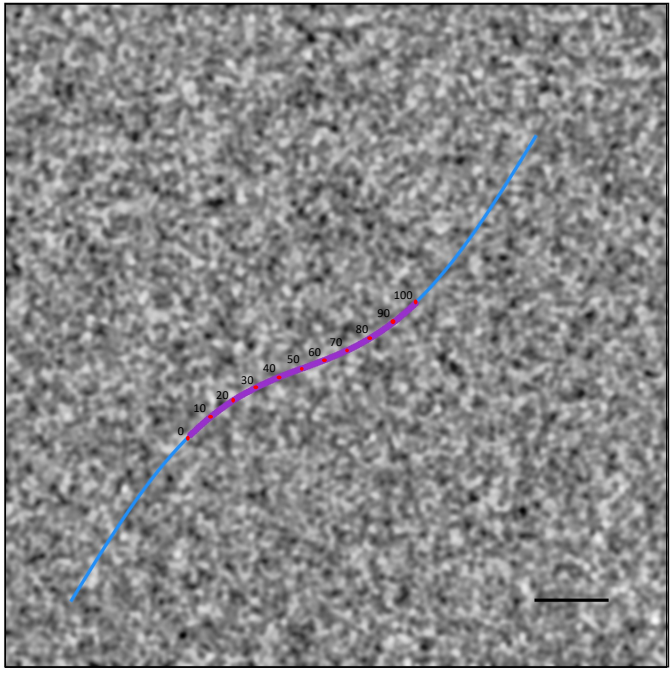



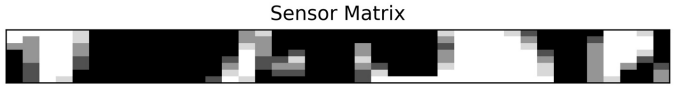



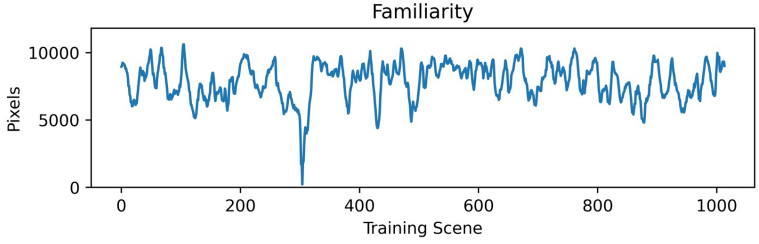

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

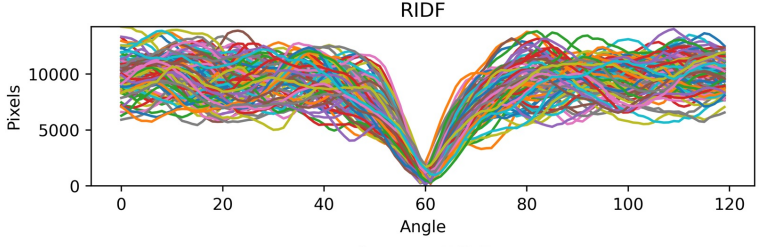
Navigation stats: RMSD error: 37.28; RMSD/dist: 0.093; TD: 6990; p90: 22; p50: 10; complete: 0

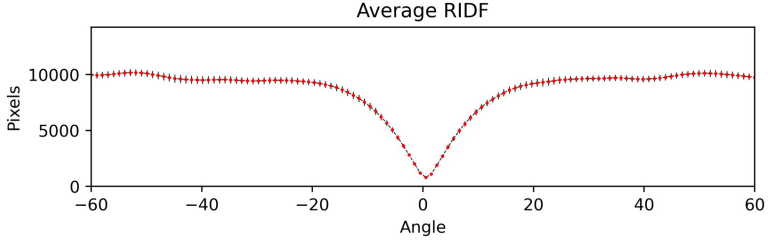
100%



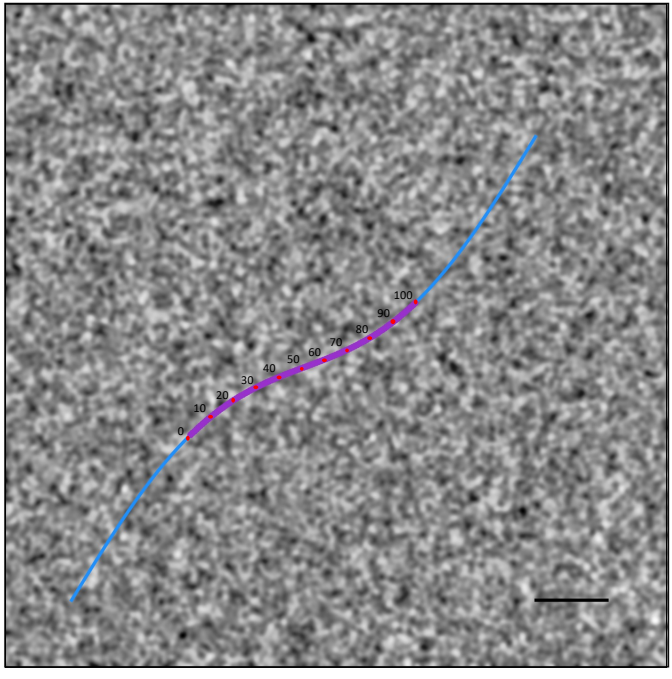



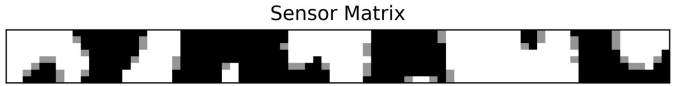



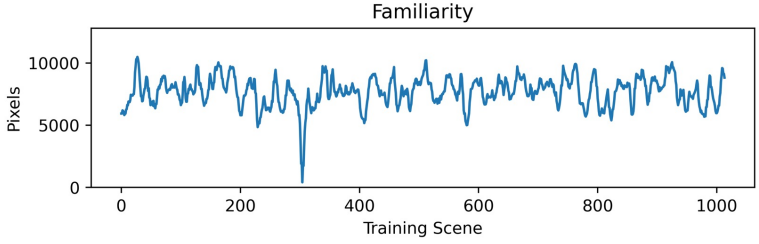

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

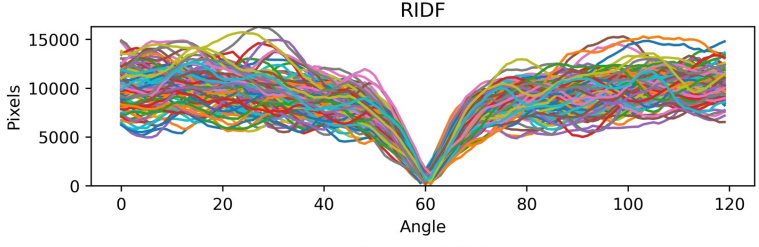
Navigation stats: RMSD error: 38.86; RMSD/dist: 0.097; TD: 6879; p90: 20; p50: 10; complete: 0

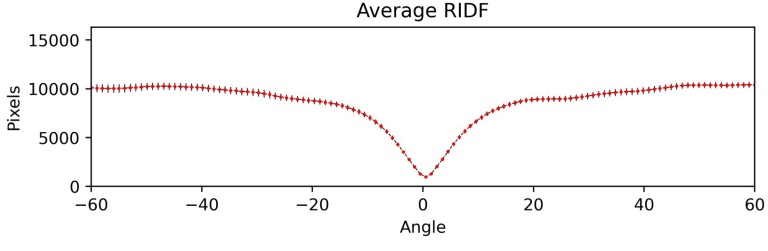
100%



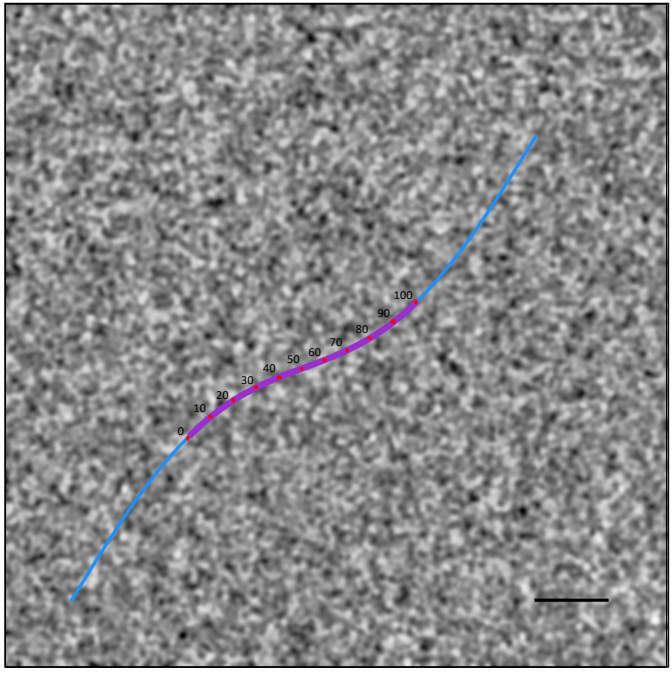



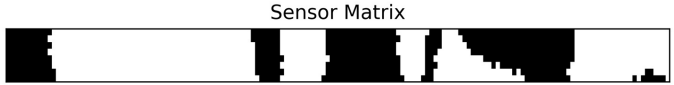



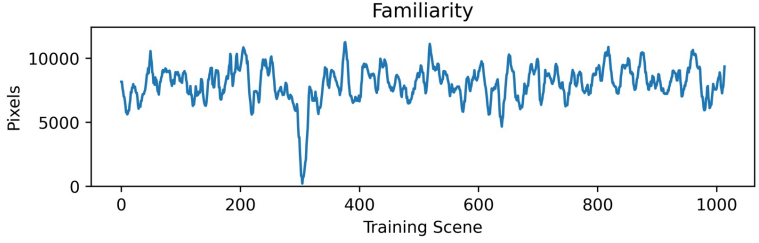

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

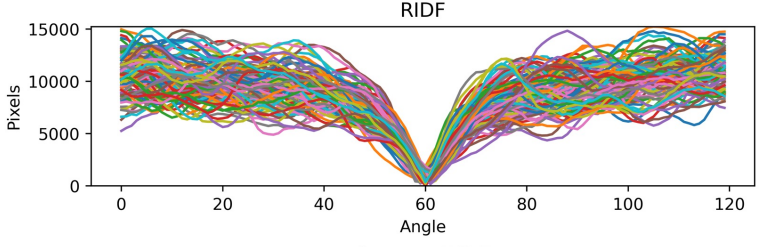
Navigation stats: RMSD error: 59.73; RMSD/dist: 0.149; TD: 6774; p90: 20; p50: 10; complete: 0

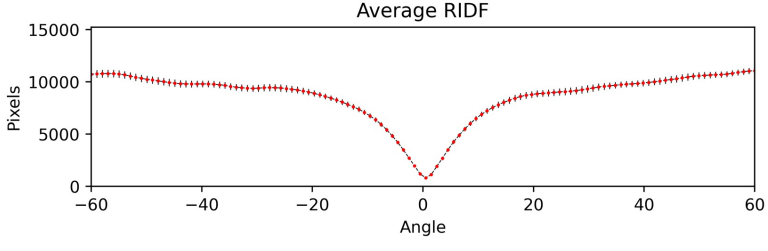
100%



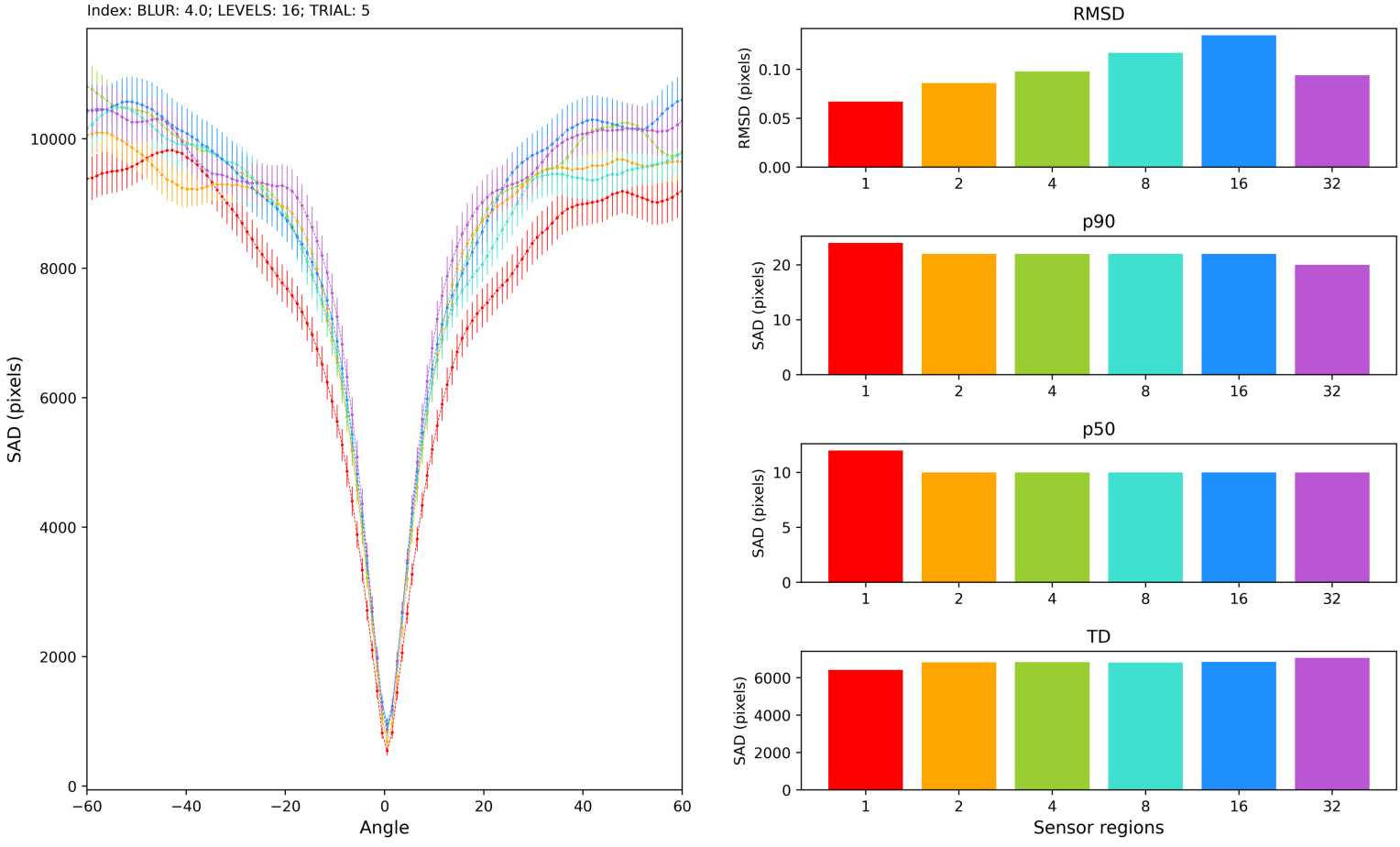



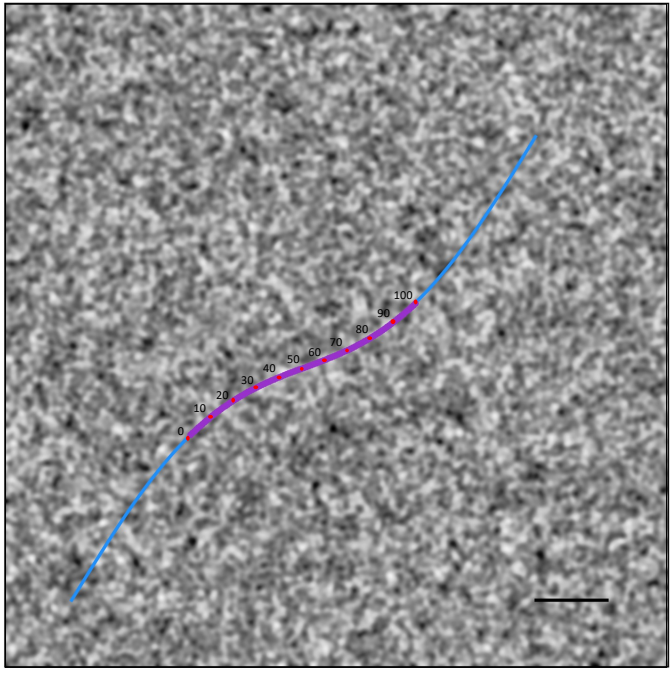



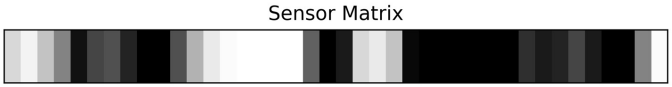

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

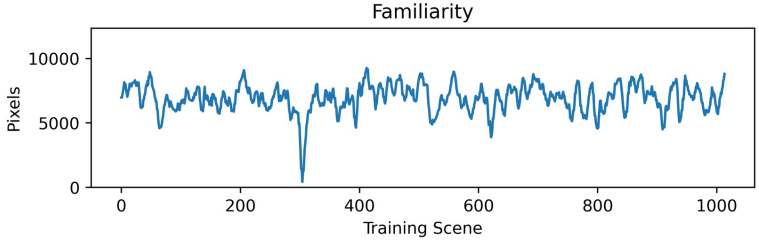
Navigation stats: RMSD error: 36.77; RMSD/dist: 0.092; TD: 7100; p90: 22; p50: 10; complete: 0

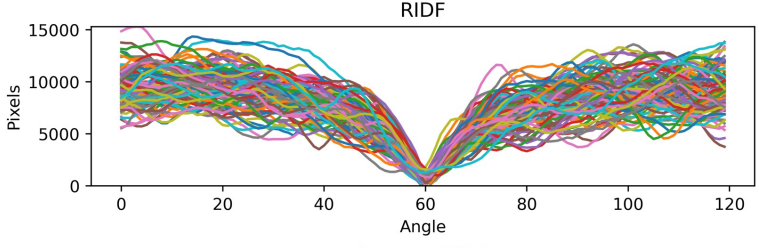

Index: BLUR: 4.0; LEVELS: 16; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

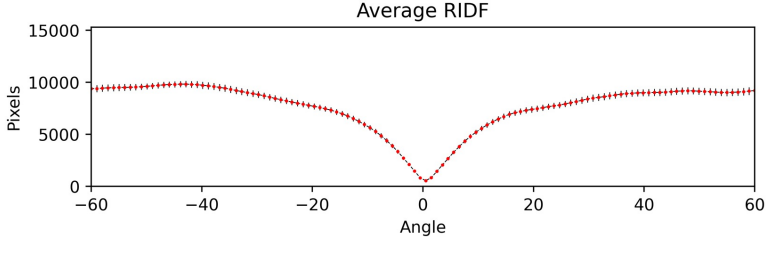
100%



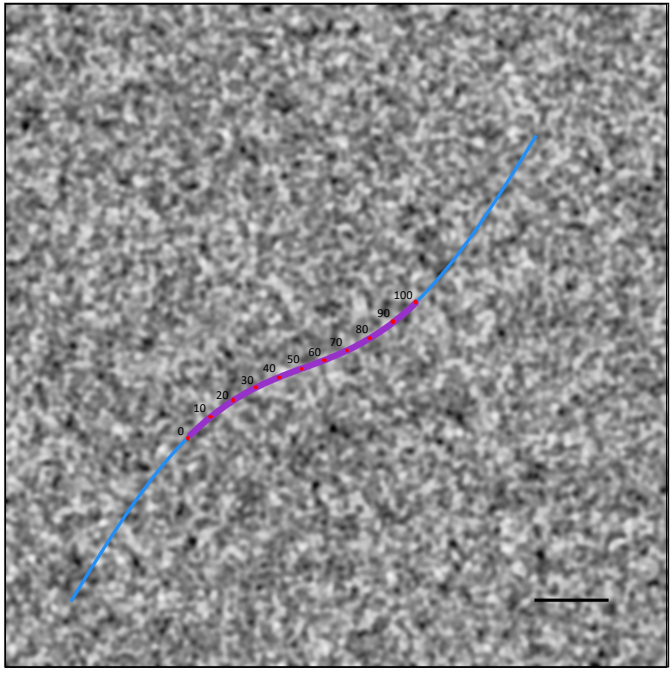



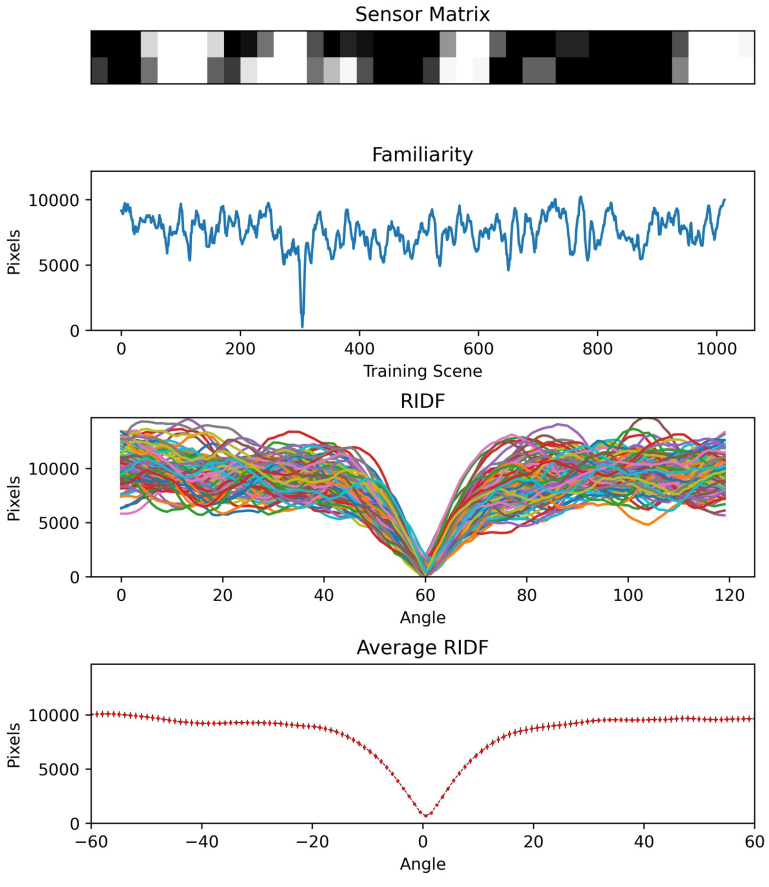




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 26.95; RMSD/dist: 0.067; TD: 6429; p90: 24; p50: 12; complete: 0

100%

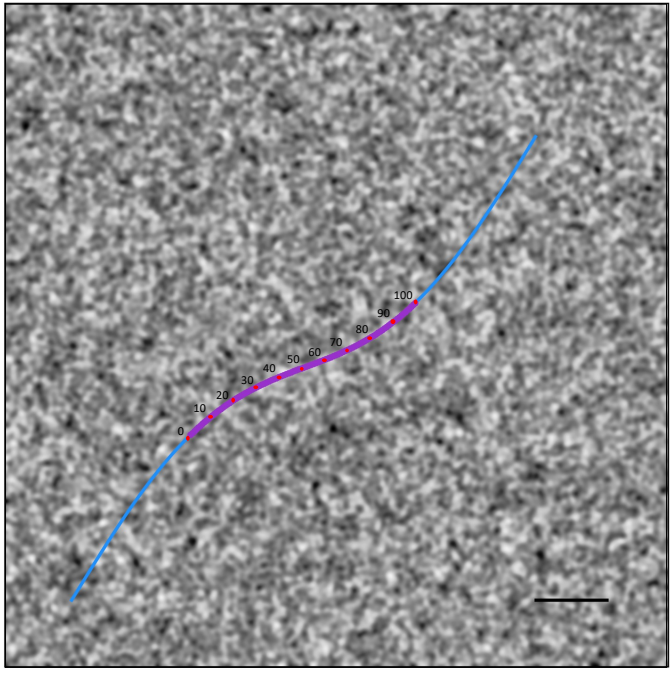


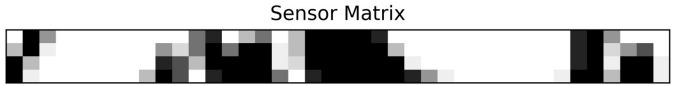



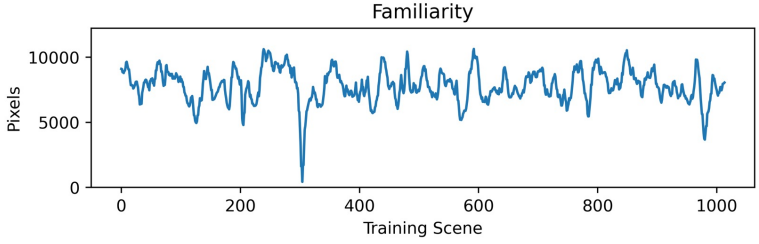

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

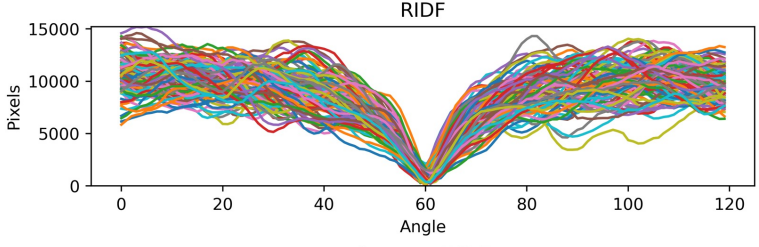
Navigation stats: RMSD error: 34.38; RMSD/dist: 0.086; TD: 6835; p90: 22; p50: 10; complete: 0

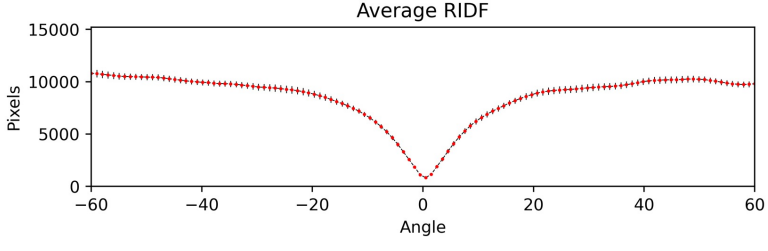
100%



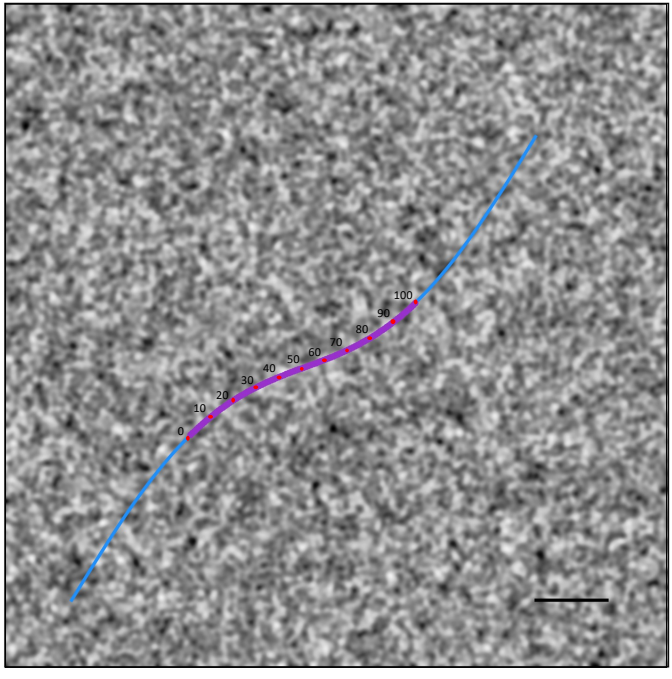



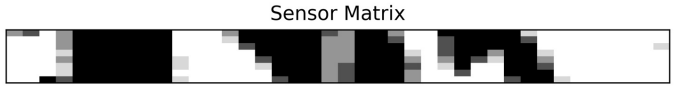



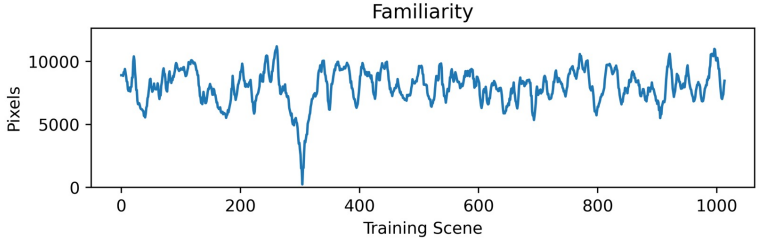

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

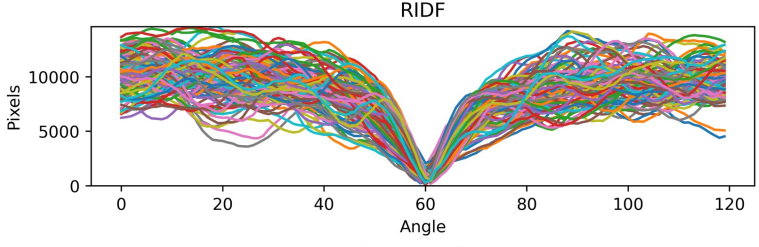
Navigation stats: RMSD error: 39.20; RMSD/dist: 0.098; TD: 6846; p90: 22; p50: 10; complete: 0

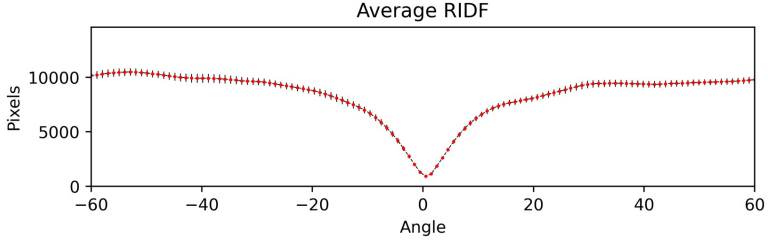
100%



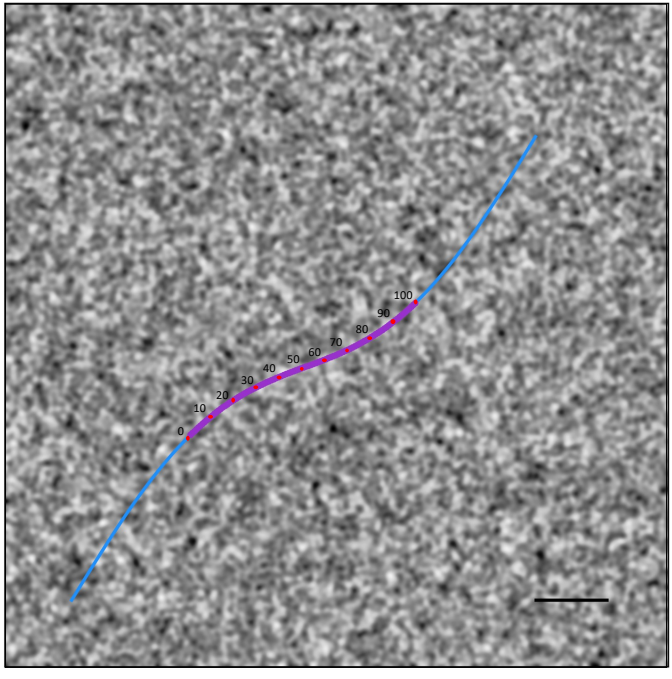



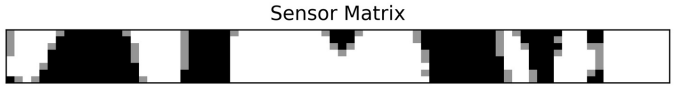



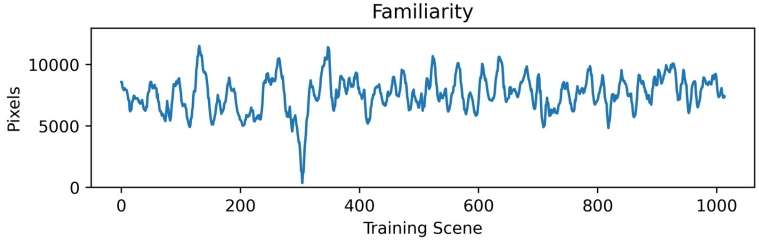

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

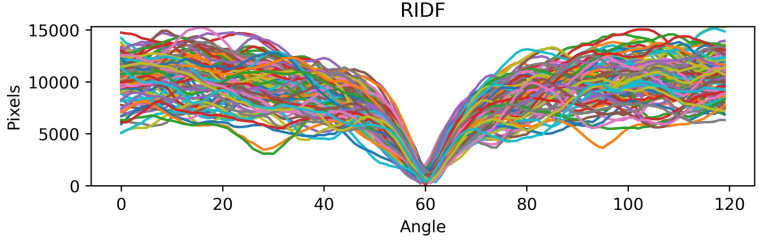
Navigation stats: RMSD error: 46.77; RMSD/dist: 0.117; TD: 6825; p90: 22; p50: 10; complete: 0

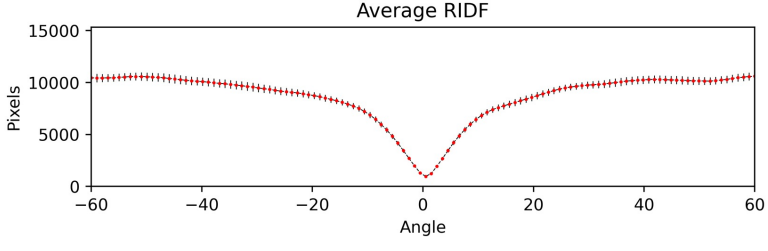
100%



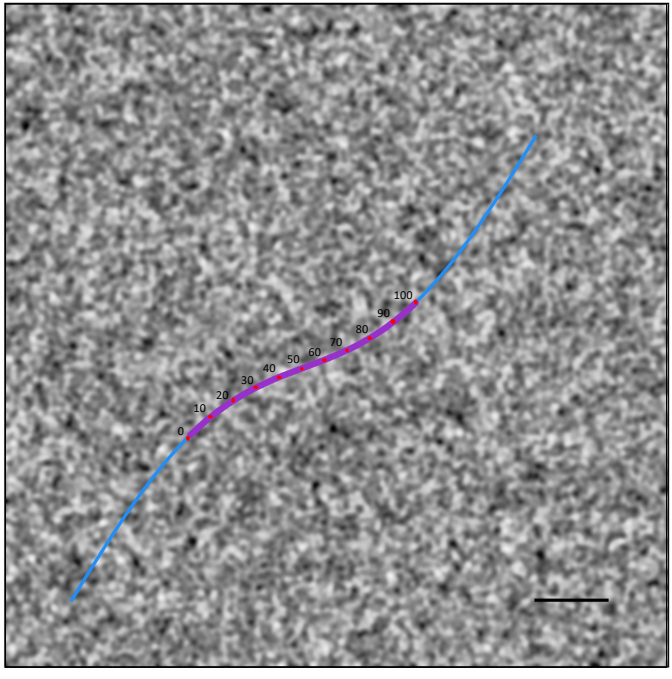



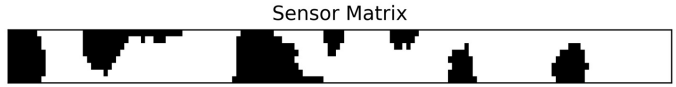



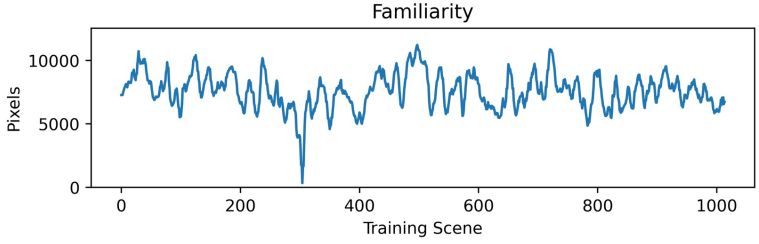

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

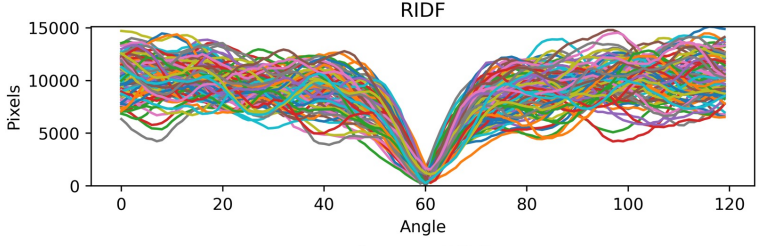
Navigation stats: RMSD error: 54.04; RMSD/dist: 0.135; TD: 6854; p90: 22; p50: 10; complete: 0

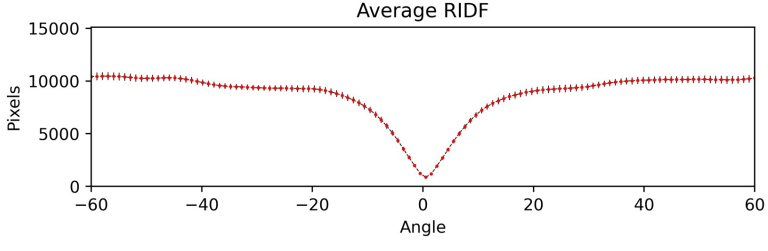
100%



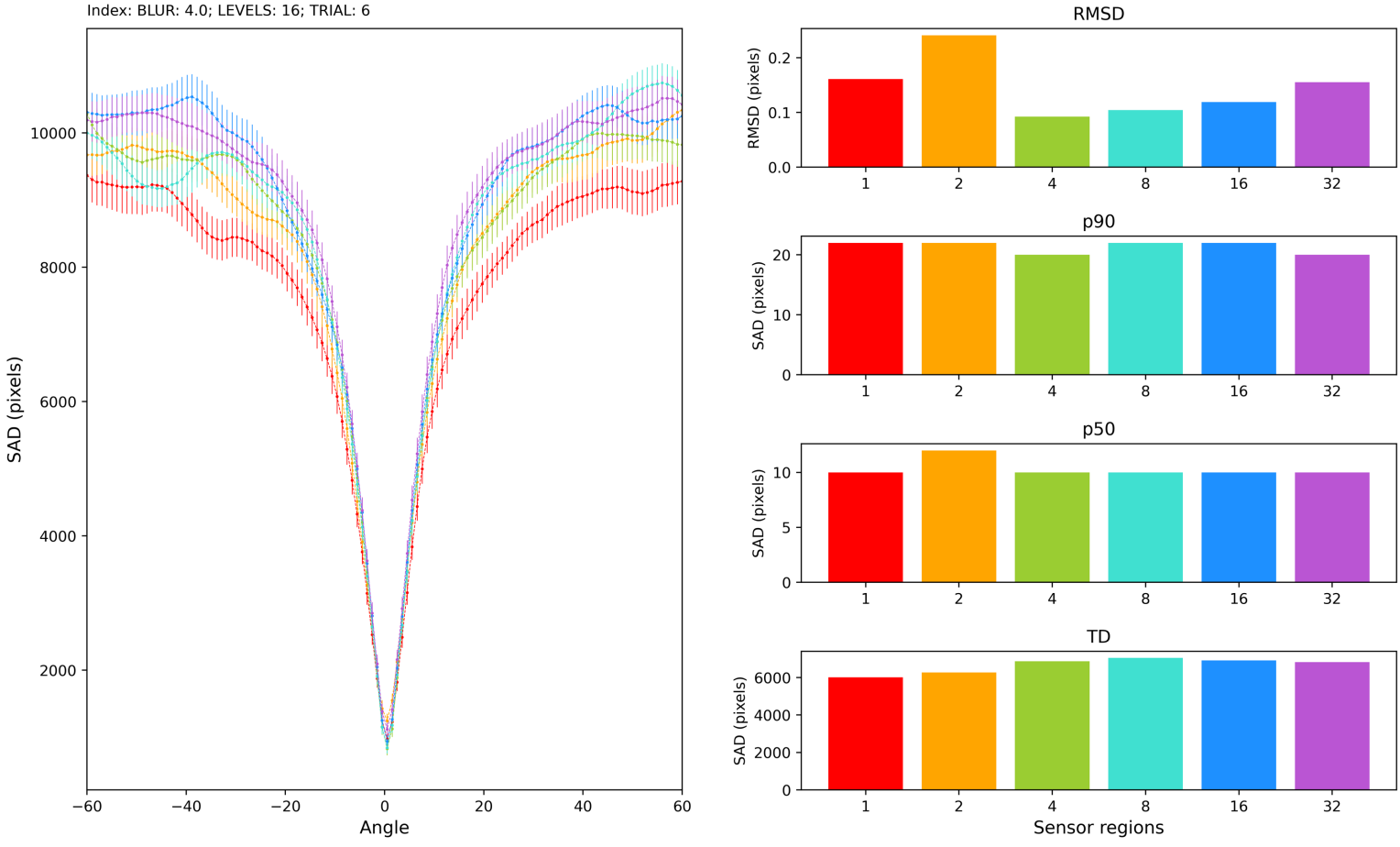



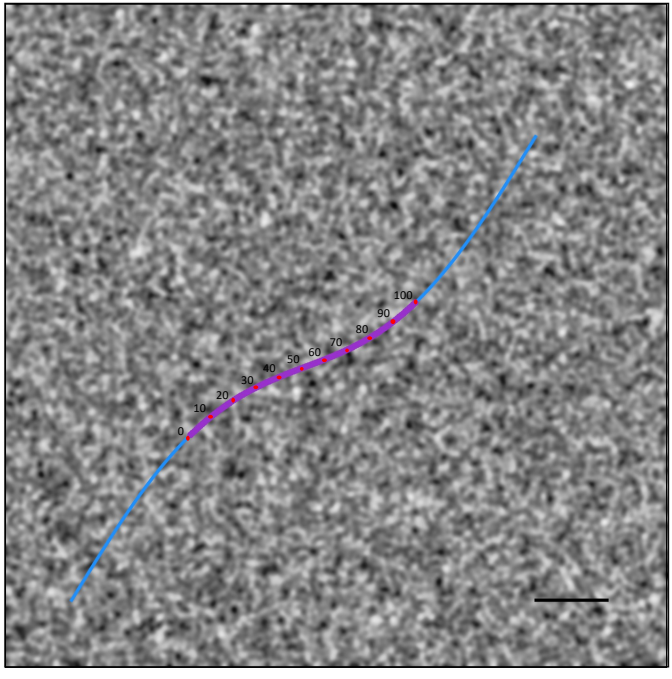



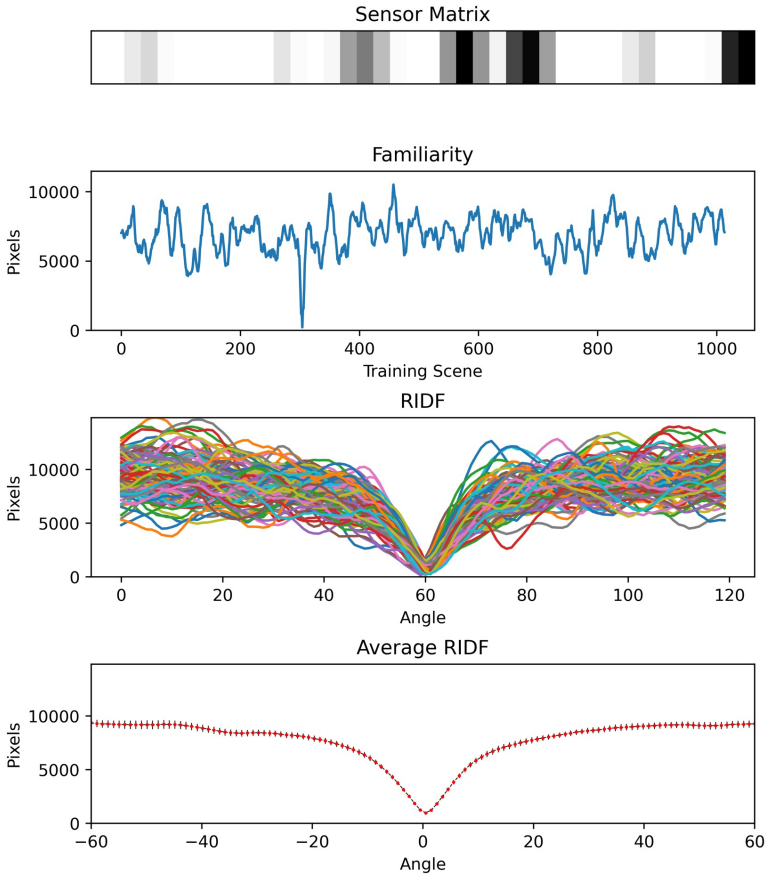

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 37.62; RMSD/dist: 0.094; TD: 7063; p90: 20; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 16; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

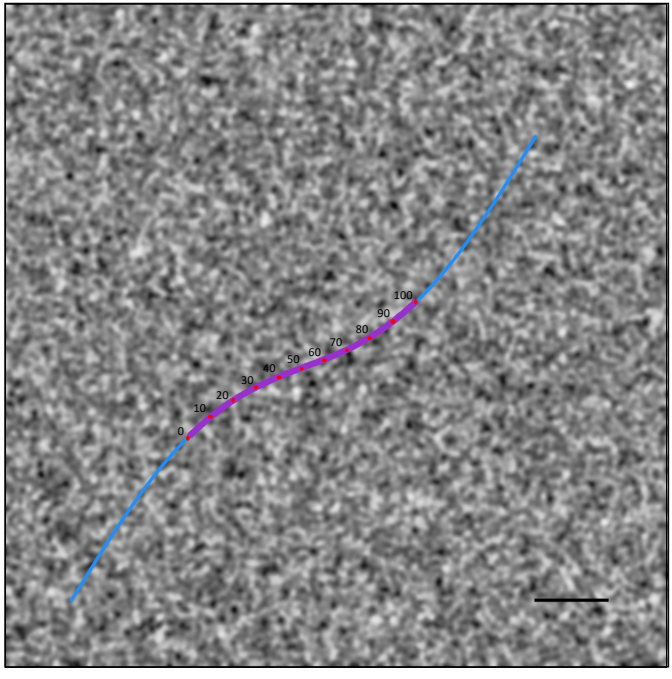


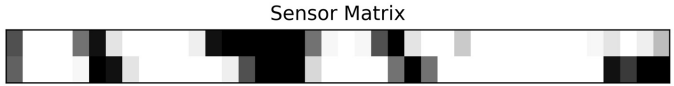



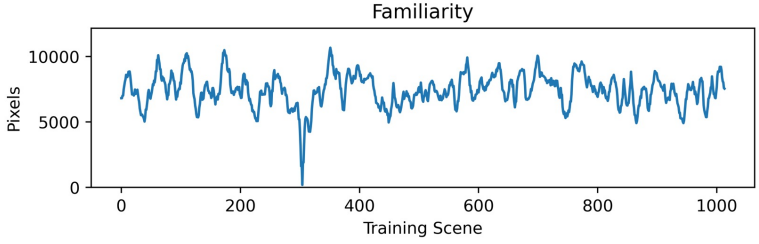

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

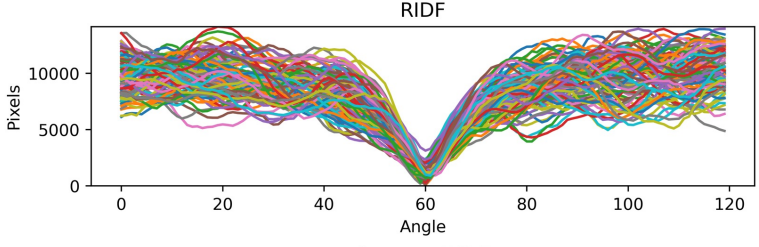
Navigation stats: RMSD error: 64.56; RMSD/dist: 0.161; TD: 6014; p90: 22; p50: 10; complete: 0

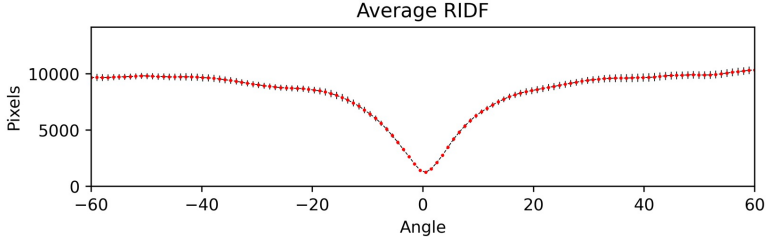
100%



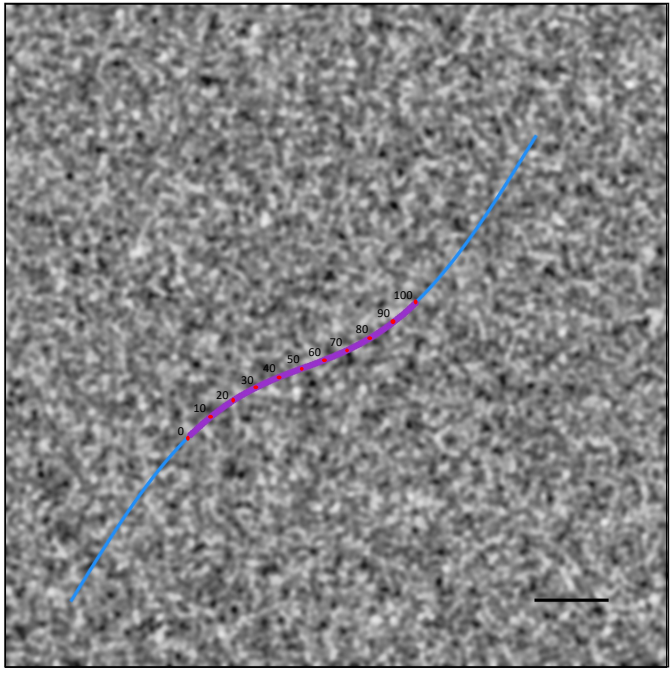



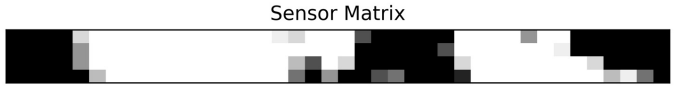



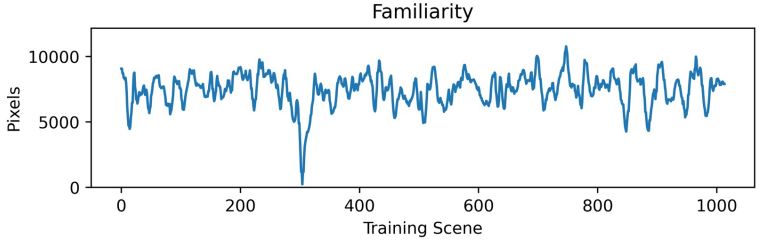

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

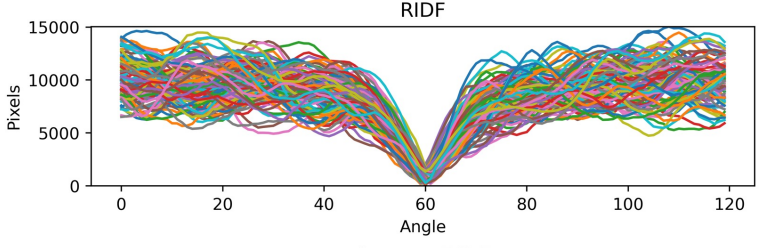
Navigation stats: RMSD error: 96.22; RMSD/dist: 0.241; TD: 6278; p90: 22; p50: 12; complete: 0

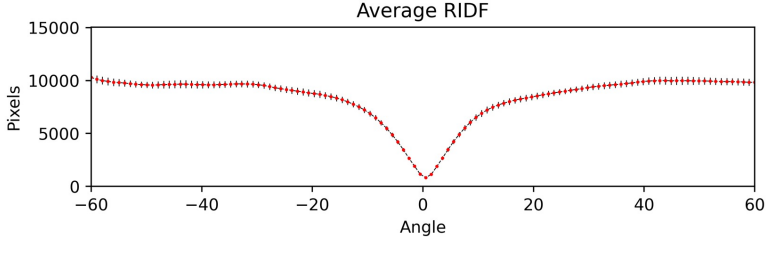
100%



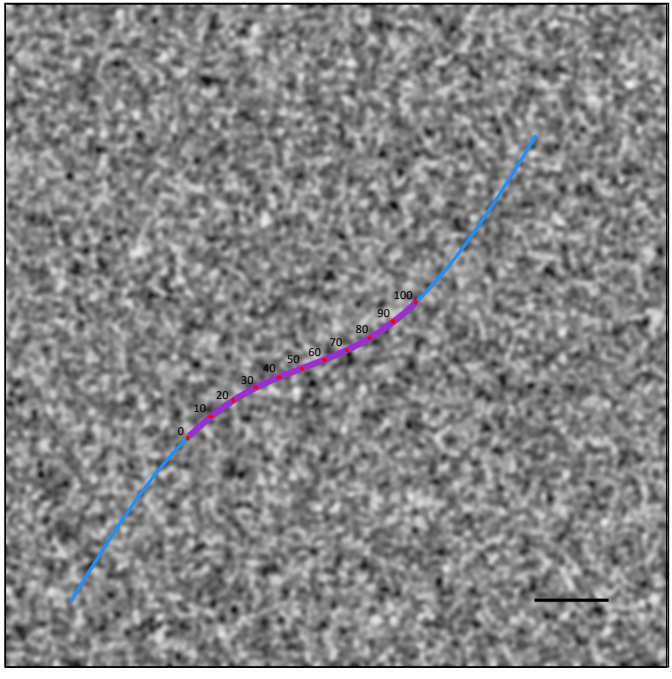



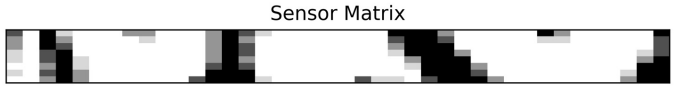



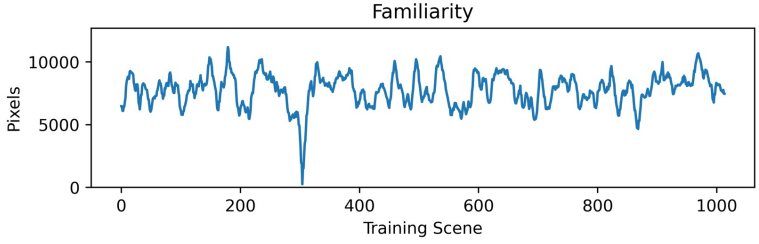

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

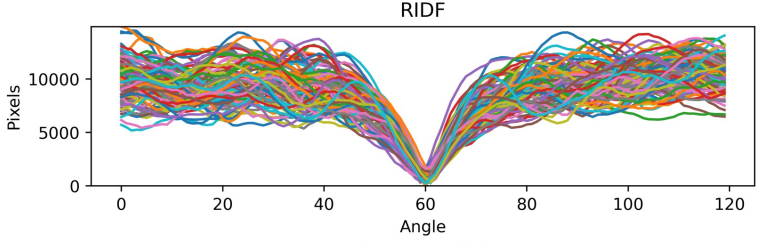
Navigation stats: RMSD error: 36.99; RMSD/dist: 0.092; TD: 6870; p90: 20; p50: 10; complete: 0

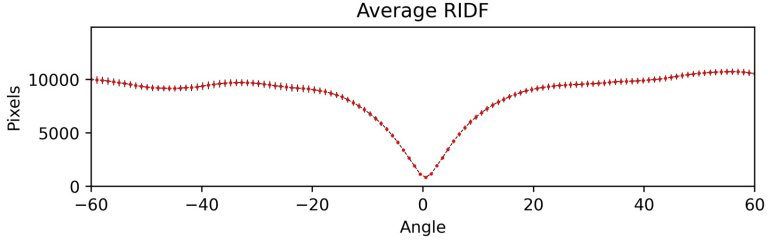
100%



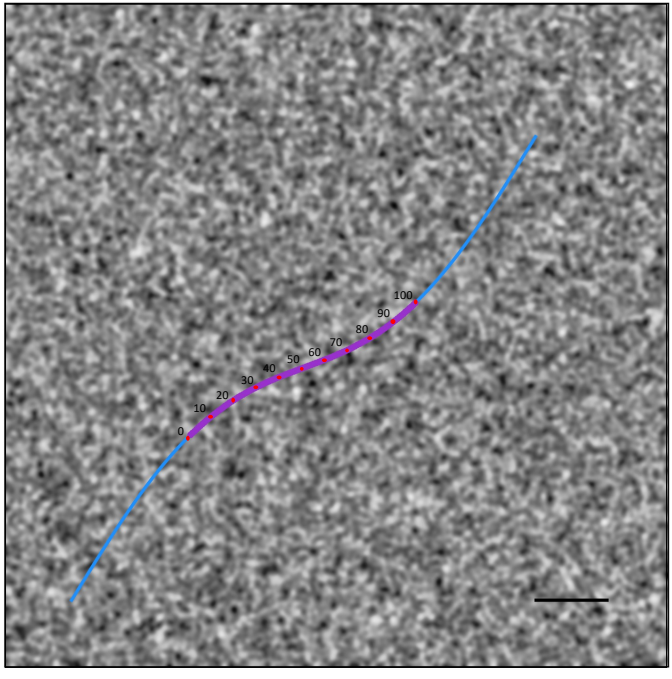



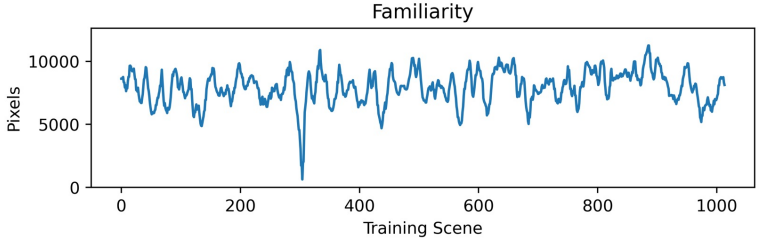



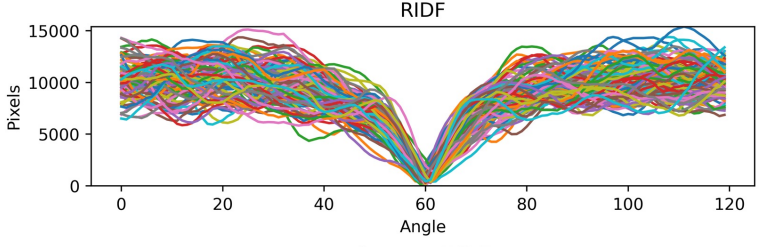

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

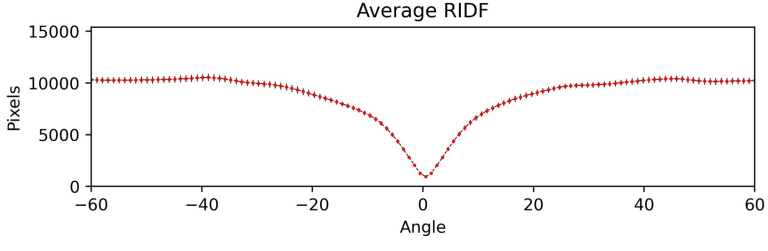
Navigation stats: RMSD error: 41.47; RMSD/dist: 0.104; TD: 7049; p90: 22; p50: 10; complete: 0

100%





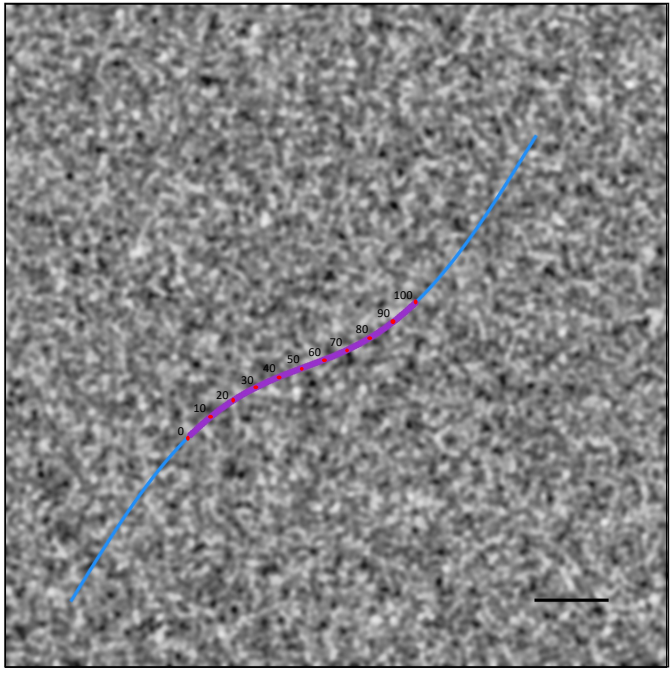



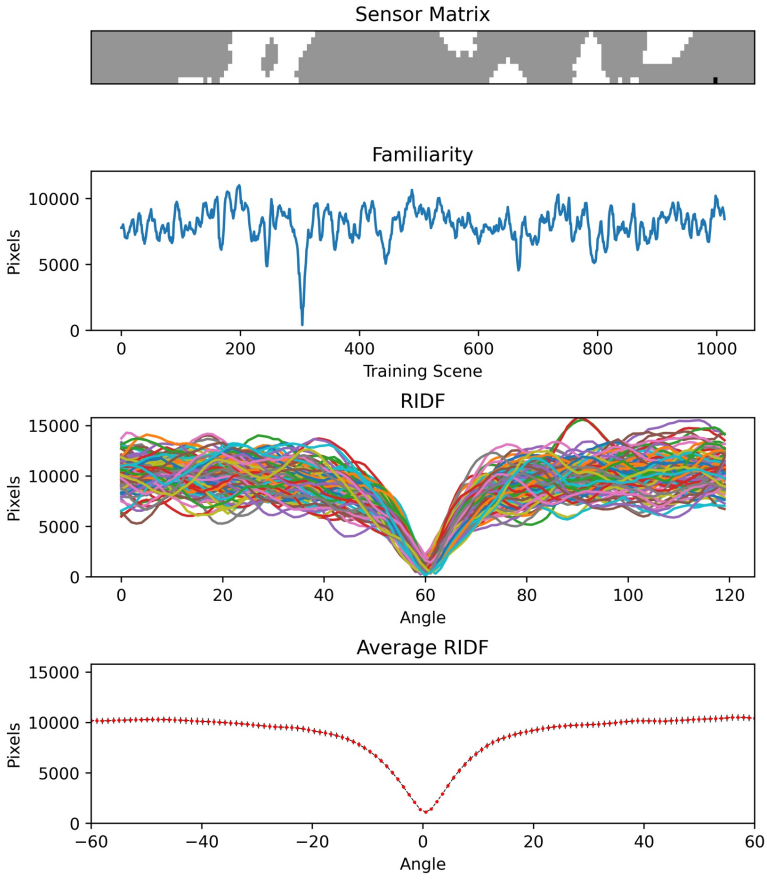




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 47.67; RMSD/dist: 0.119; TD: 6918; p90: 22; p50: 10; complete: 0

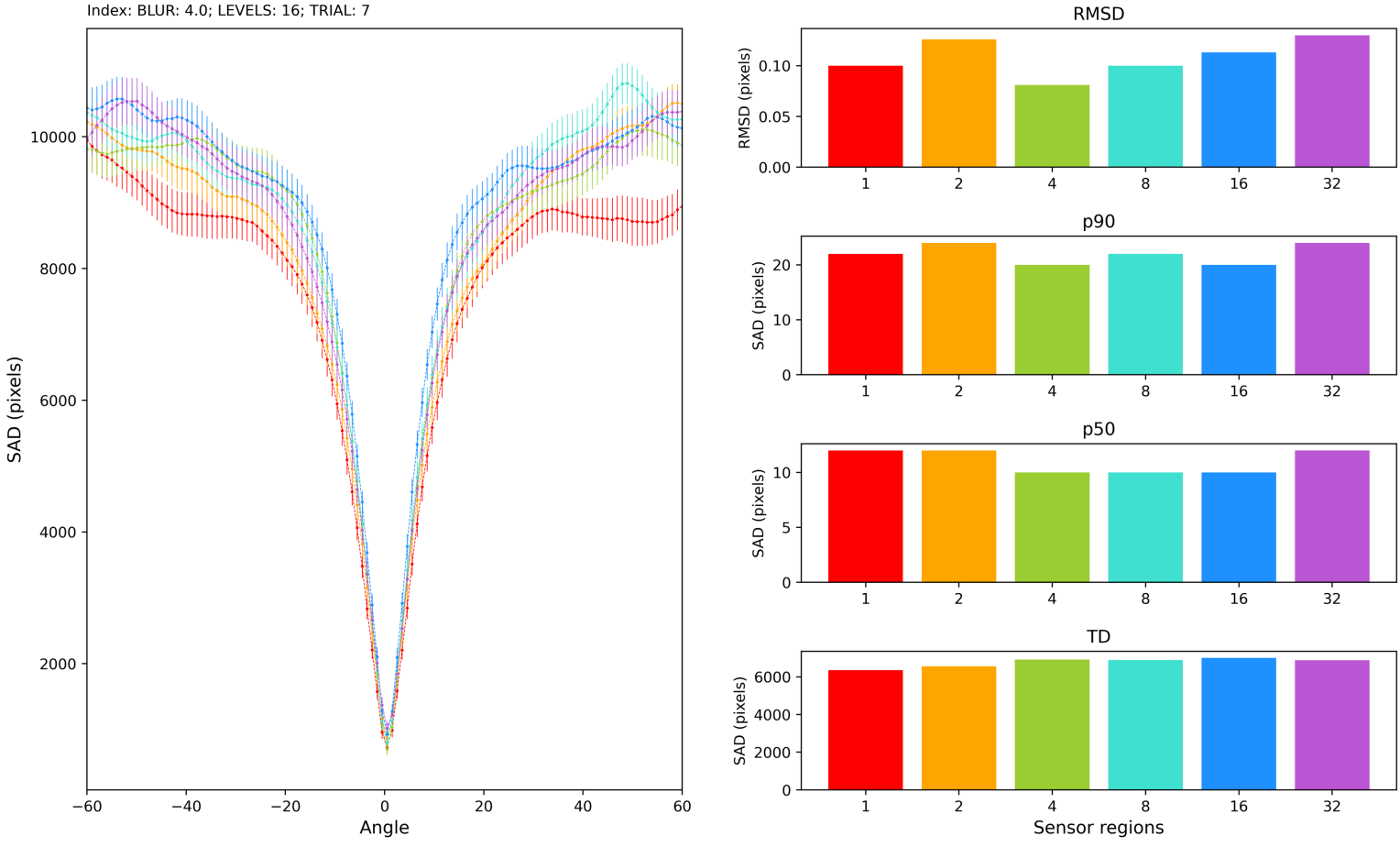
100%



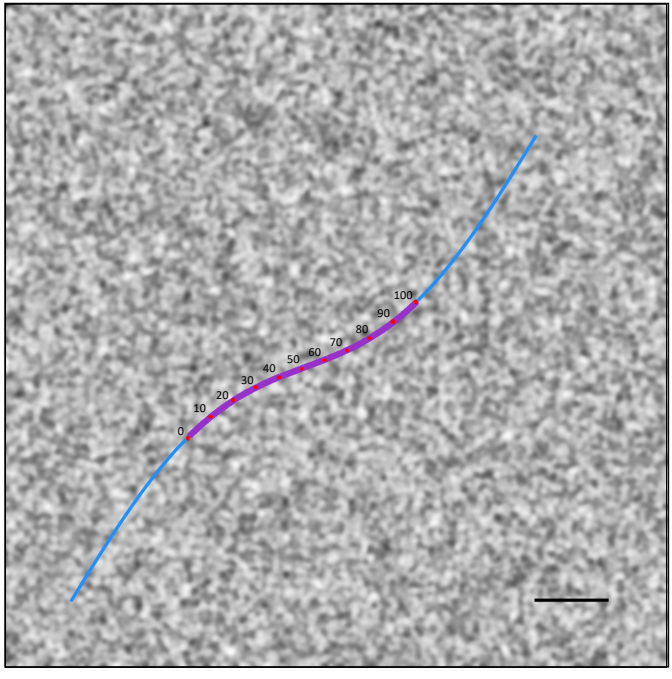



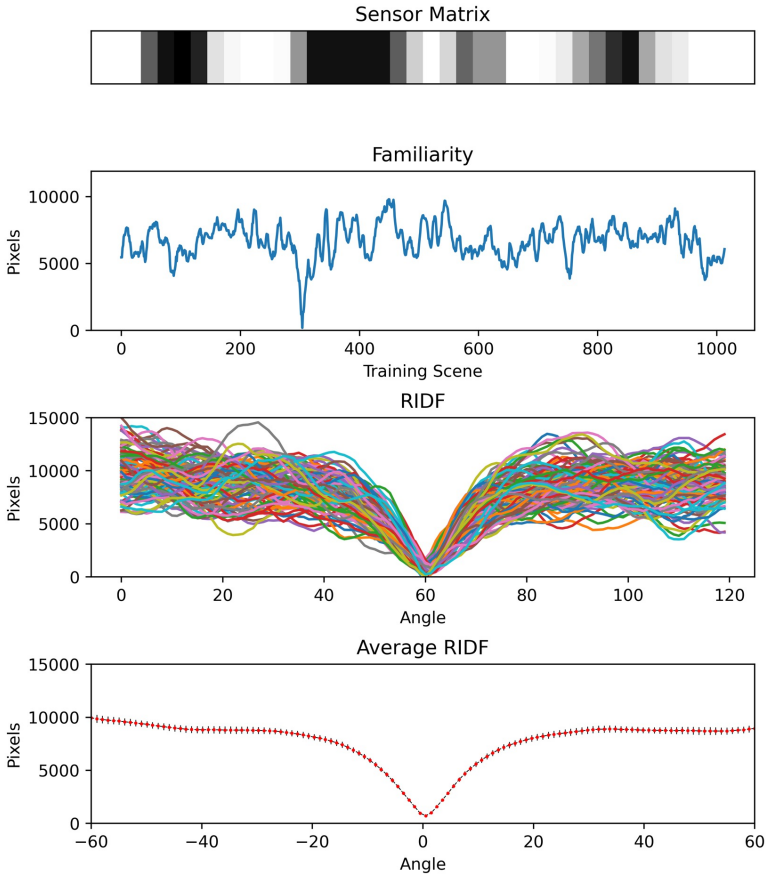

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 62.05; RMSD/dist: 0.155; TD: 6830; p90: 20; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 16; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

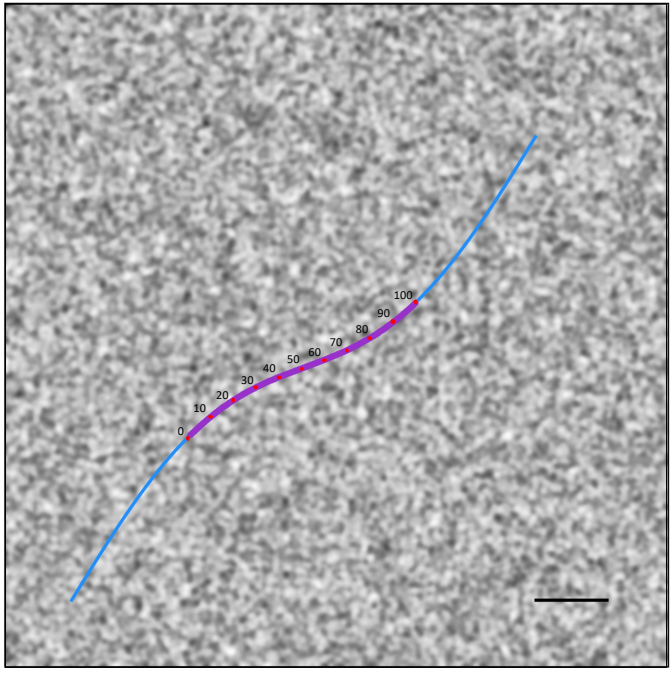


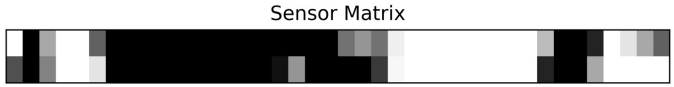



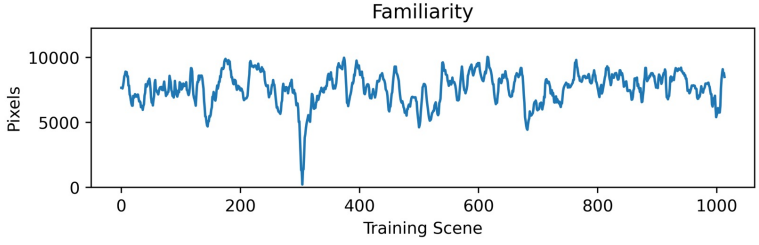

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

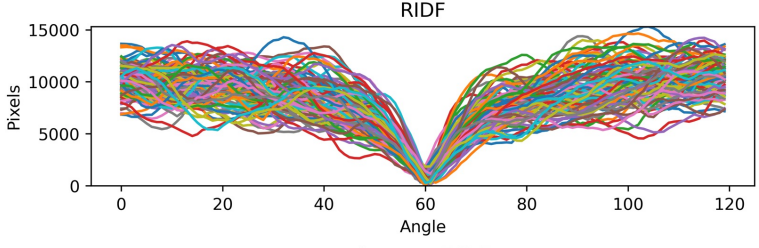
Navigation stats: RMSD error: 40.20; RMSD/dist: 0.100; TD: 6349; p90: 22; p50: 12; complete: 0

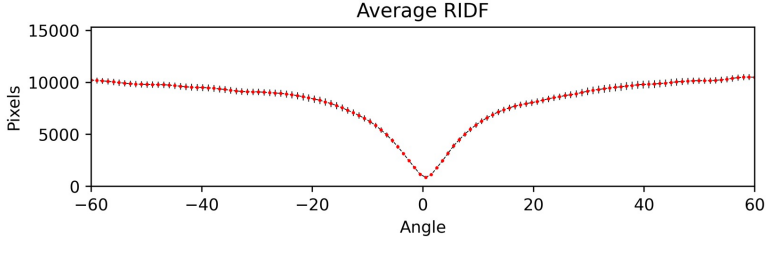
100%



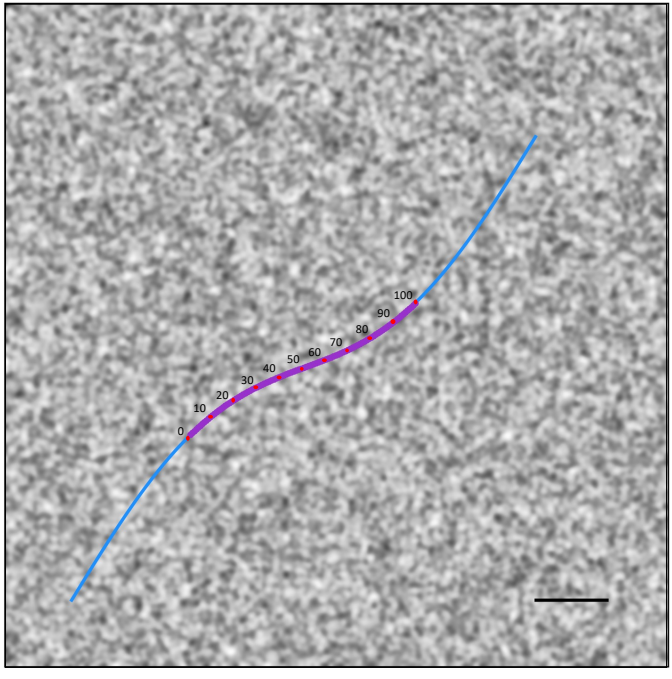



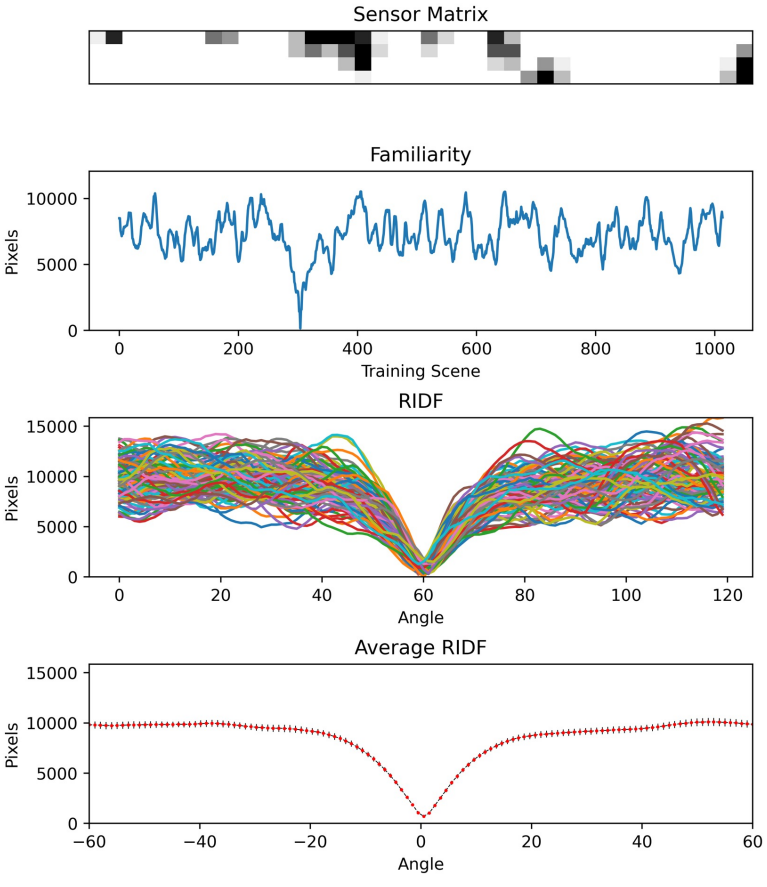




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 50.51; RMSD/dist: 0.126; TD: 6553; p90: 24; p50: 12; complete: 0

100%

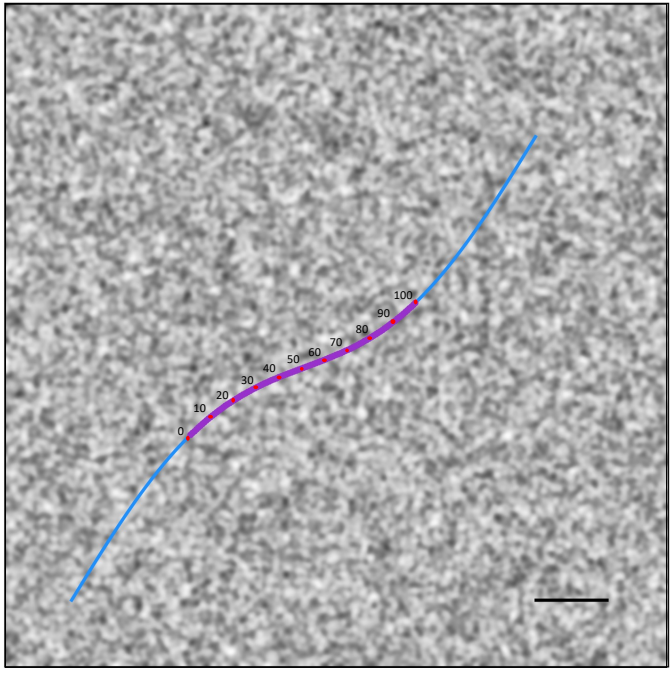


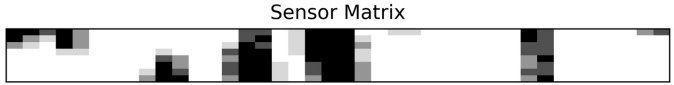



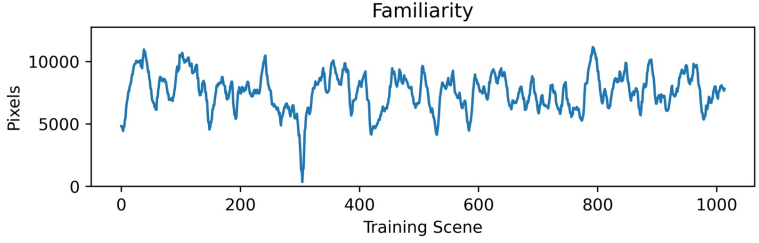

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

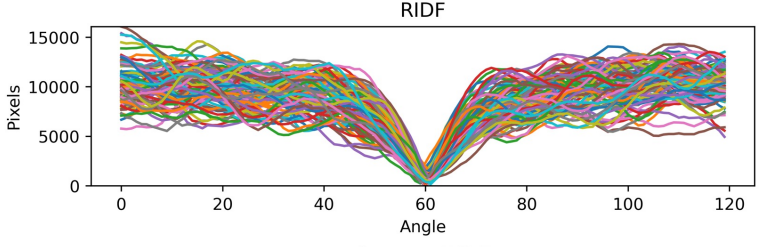
Navigation stats: RMSD error: 32.59; RMSD/dist: 0.081; TD: 6920; p90: 20; p50: 10; complete: 0

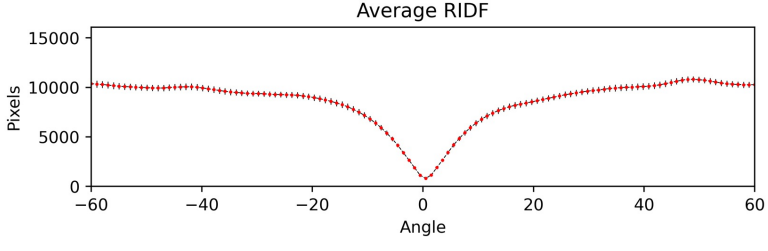
100%



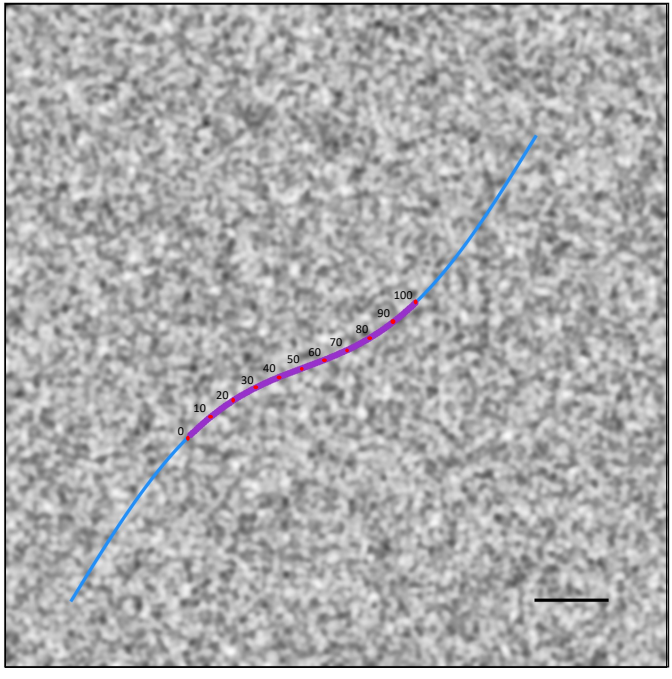



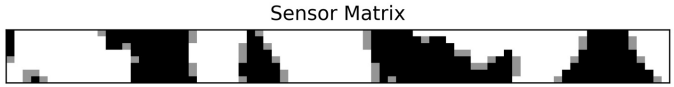



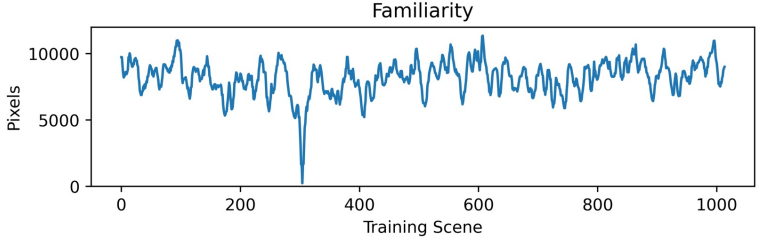

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

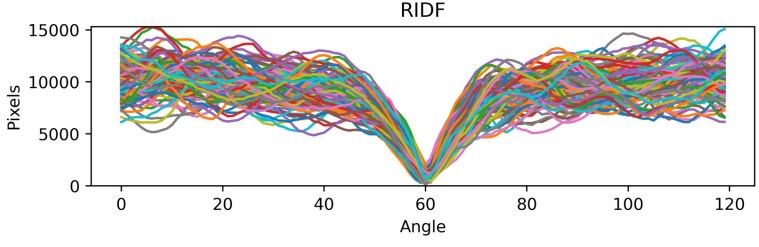
Navigation stats: RMSD error: 40.09; RMSD/dist: 0.100; TD: 6891; p90: 22; p50: 10; complete: 0

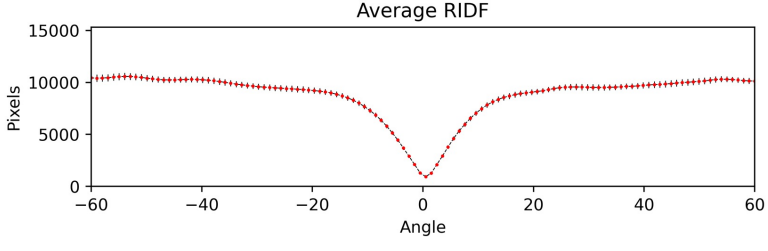
100%



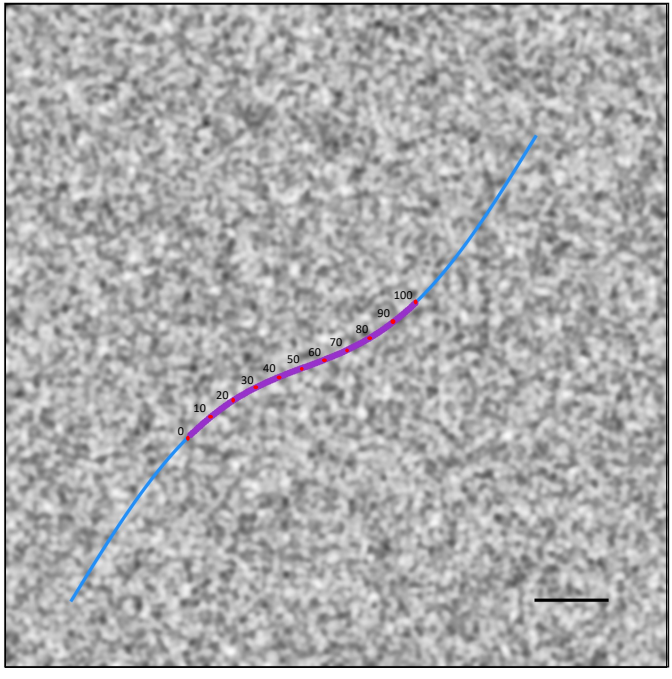



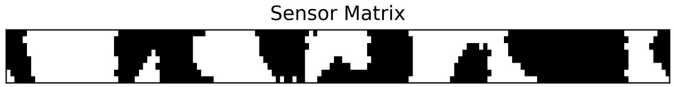



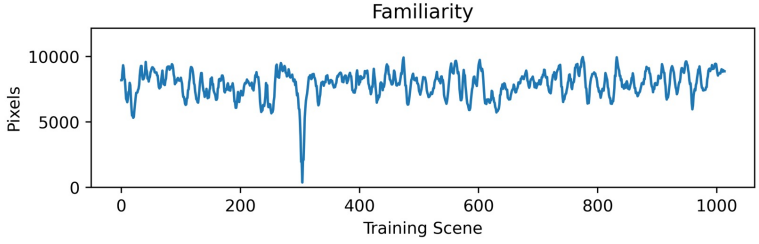

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

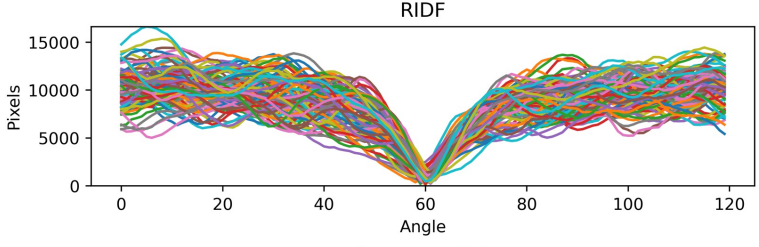
Navigation stats: RMSD error: 45.08; RMSD/dist: 0.113; TD: 6999; p90: 20; p50: 10; complete: 0

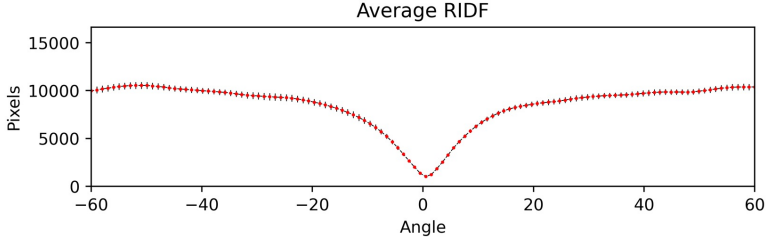
100%



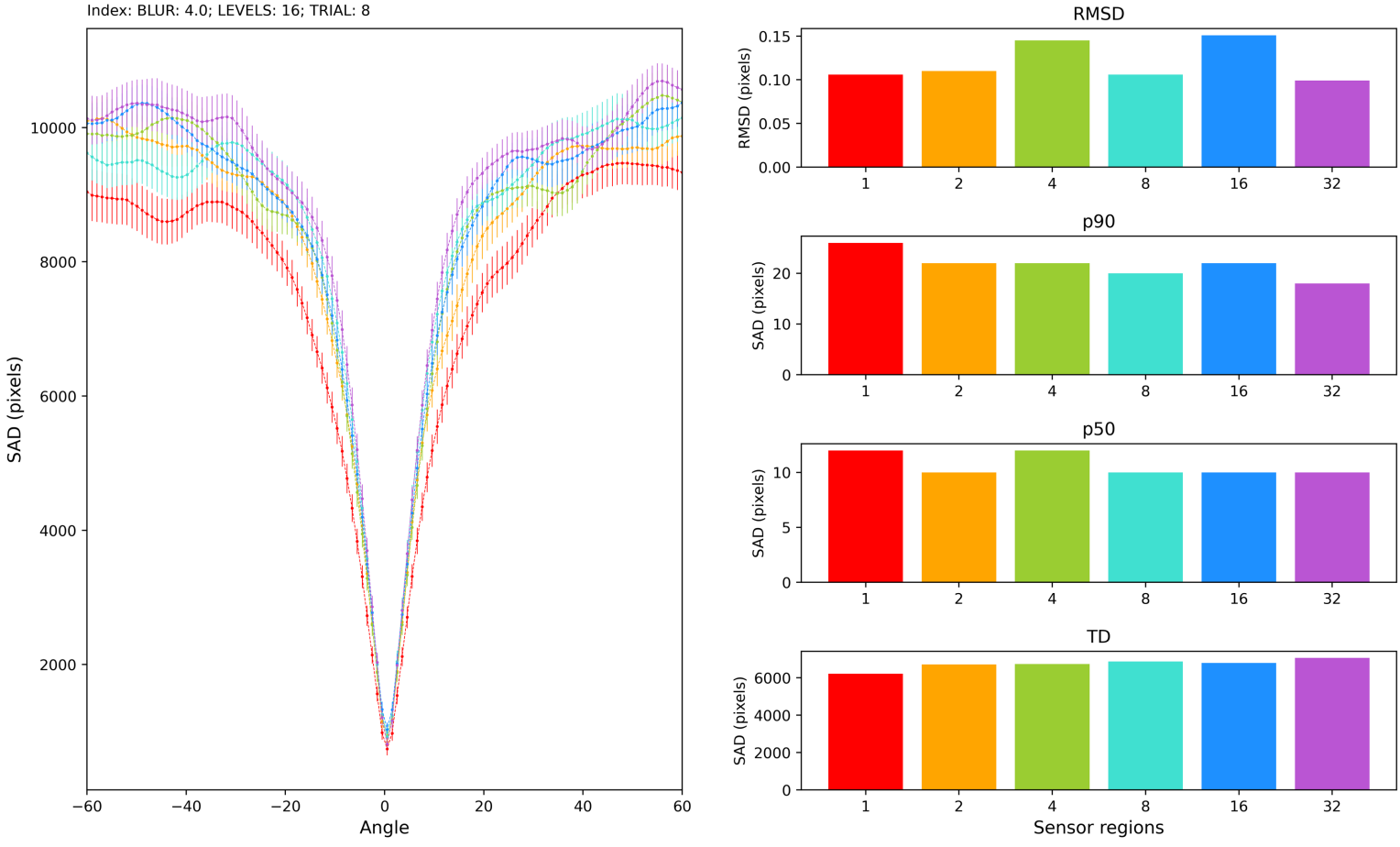



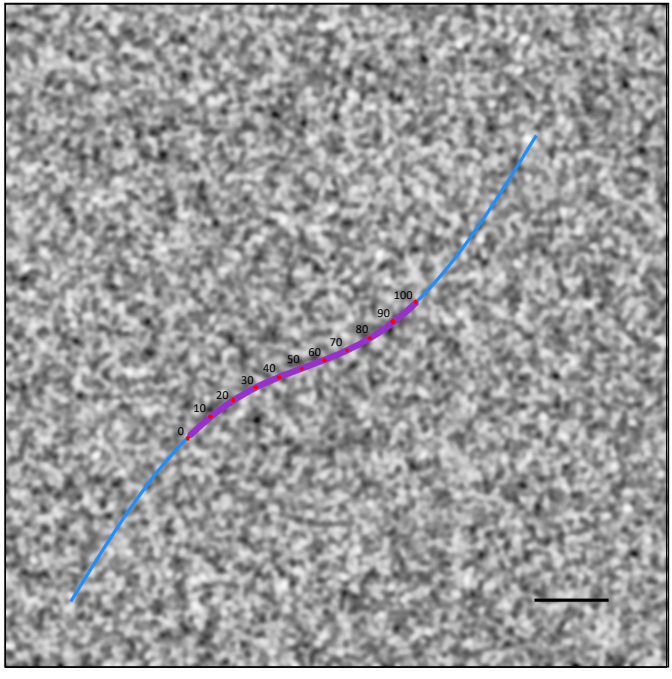



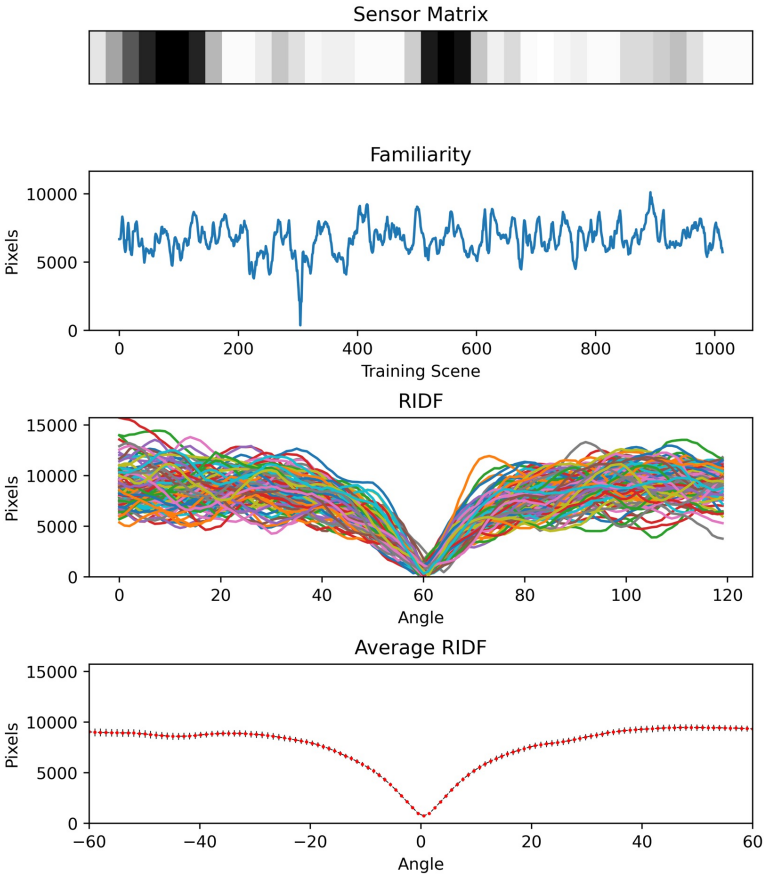

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 52.13; RMSD/dist: 0.130; TD: 6883; p90: 24; p50: 12; complete: 0


Index: BLUR: 4.0; LEVELS: 16; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

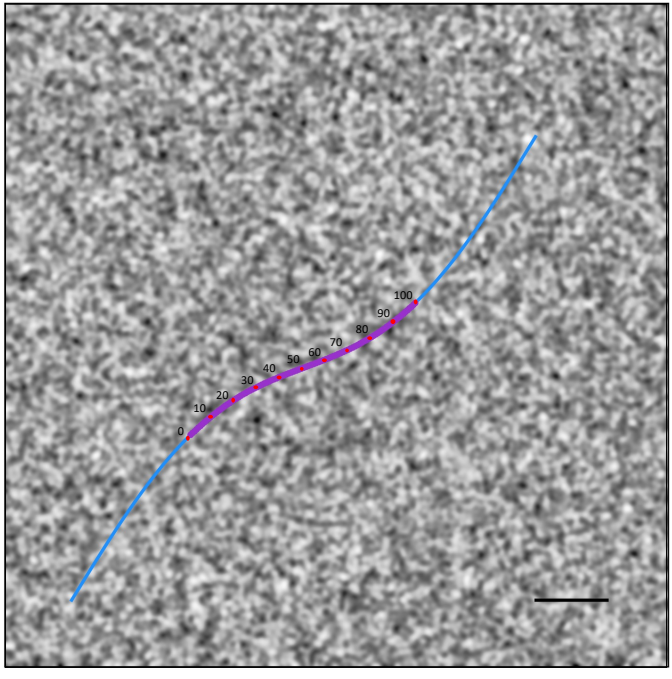


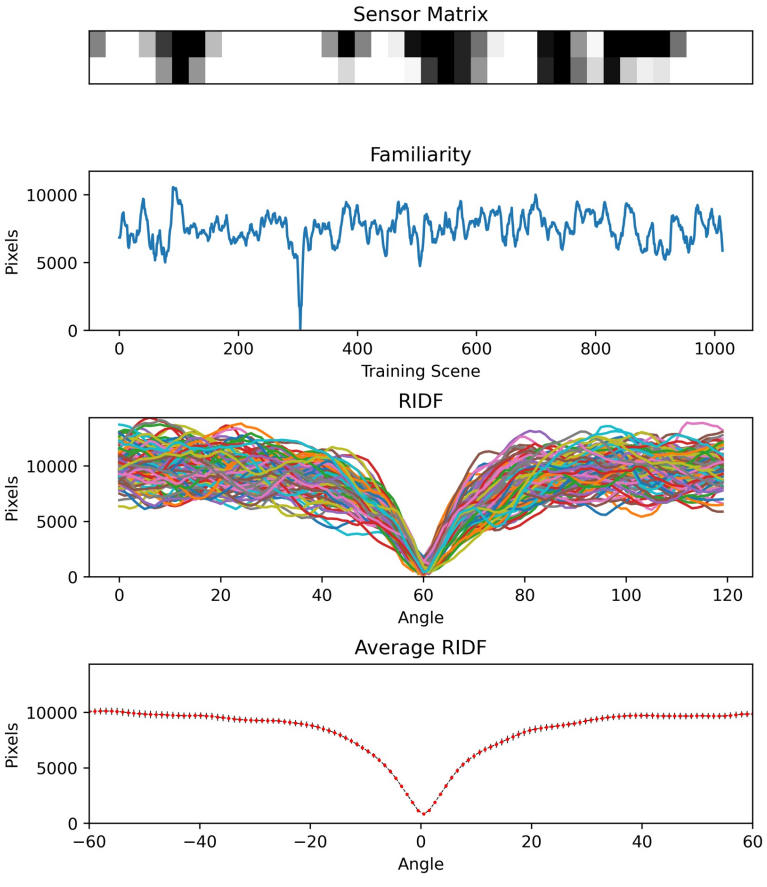




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 42.40; RMSD/dist: 0.106; TD: 6211; p90: 26; p50: 12; complete: 0

100%

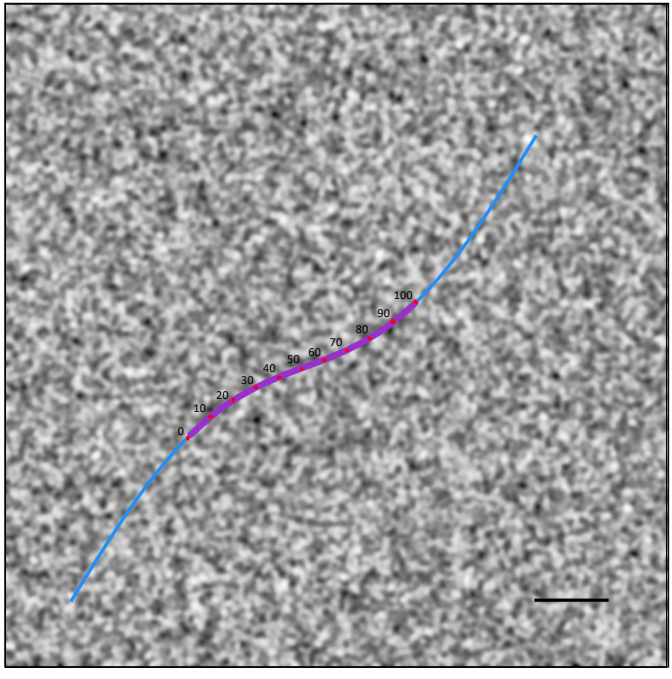


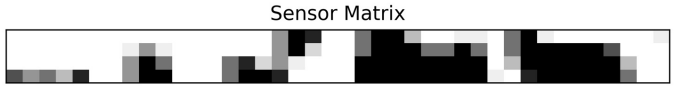



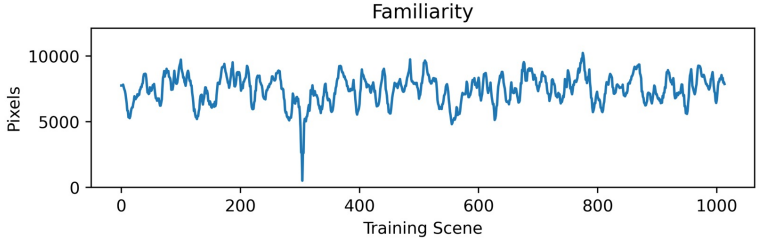

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

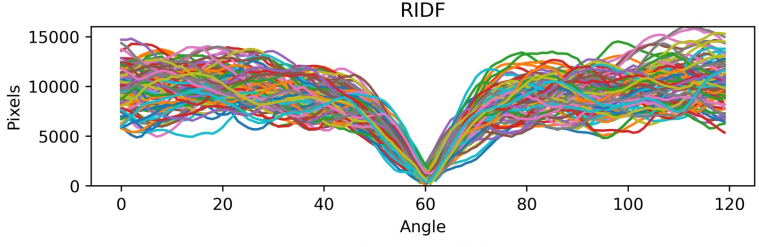
Navigation stats: RMSD error: 43.83; RMSD/dist: 0.110; TD: 6713; p90: 22; p50: 10; complete: 0

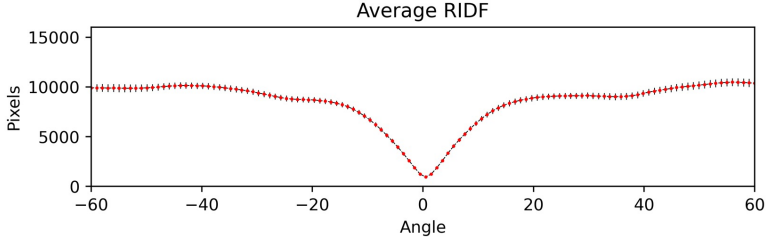
100%



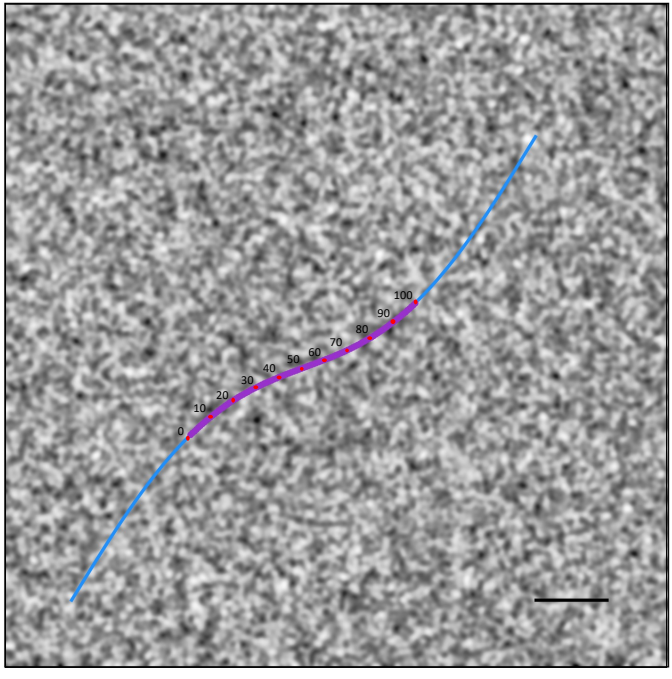



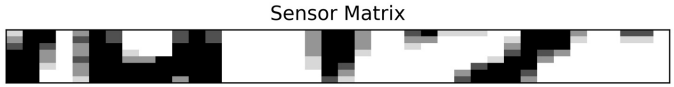



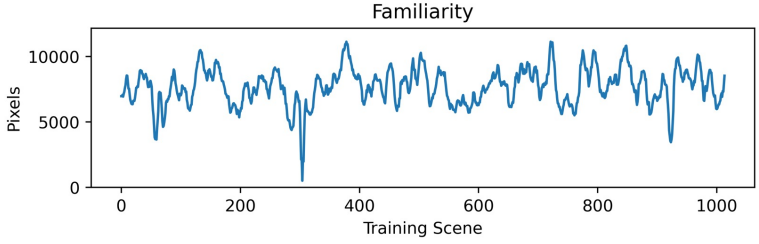

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

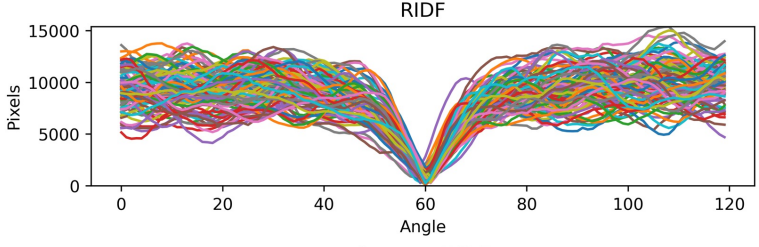
Navigation stats: RMSD error: 58.13; RMSD/dist: 0.145; TD: 6740; p90: 22; p50: 12; complete: 0

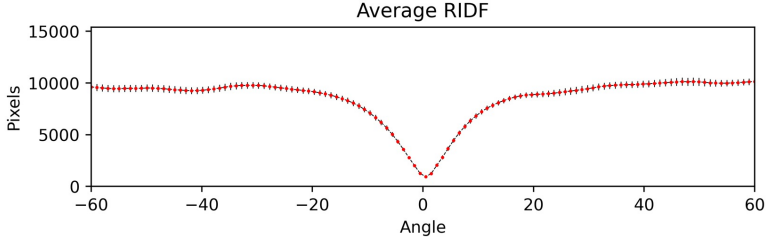
100%



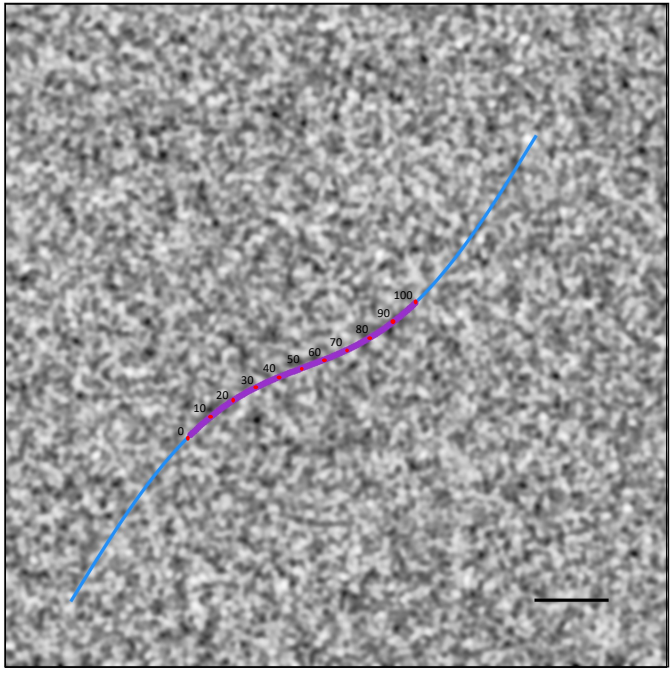



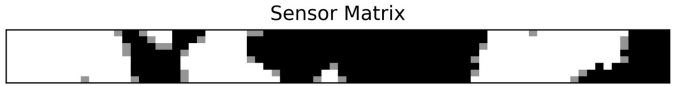



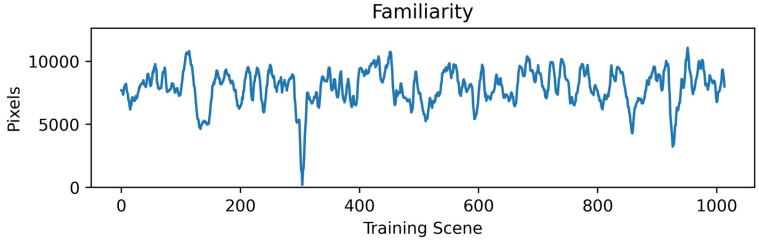

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

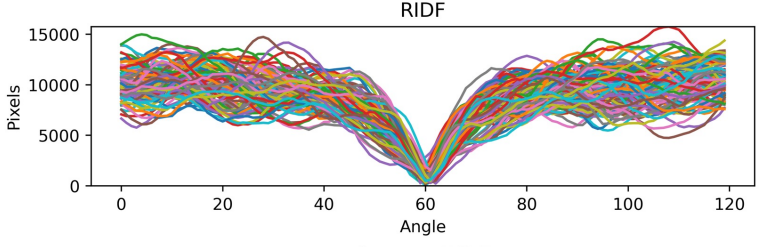
Navigation stats: RMSD error: 42.20; RMSD/dist: 0.106; TD: 6866; p90: 20; p50: 10; complete: 0

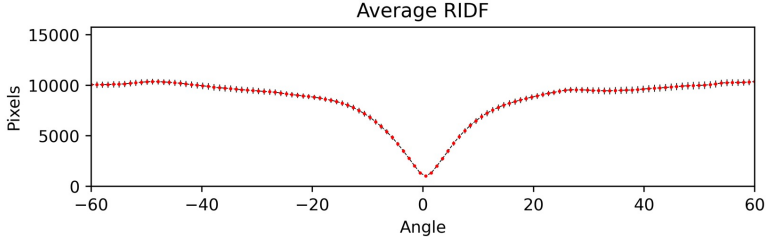
100%



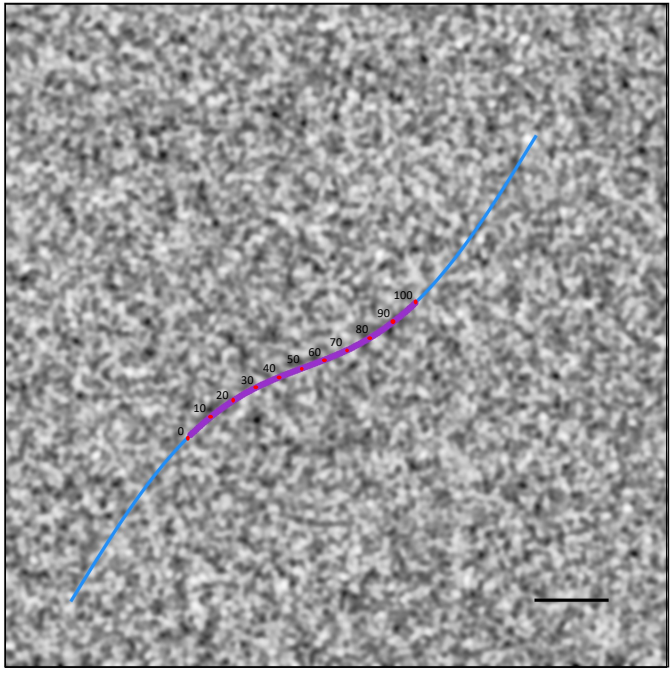



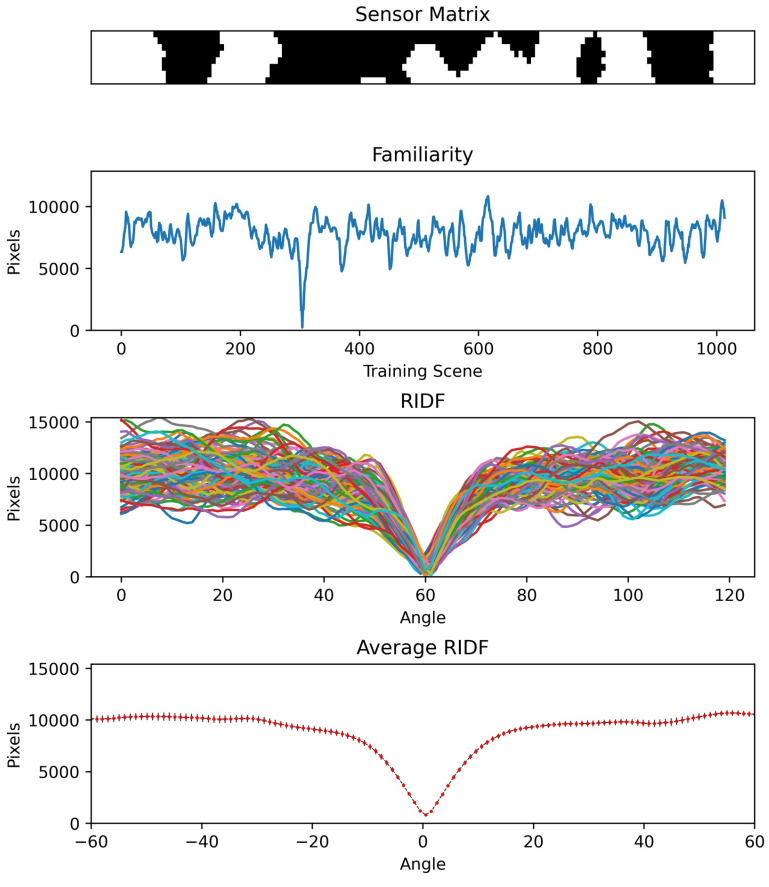




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 60.56; RMSD/dist: 0.151; TD: 6790; p90: 22; p50: 10; complete: 0

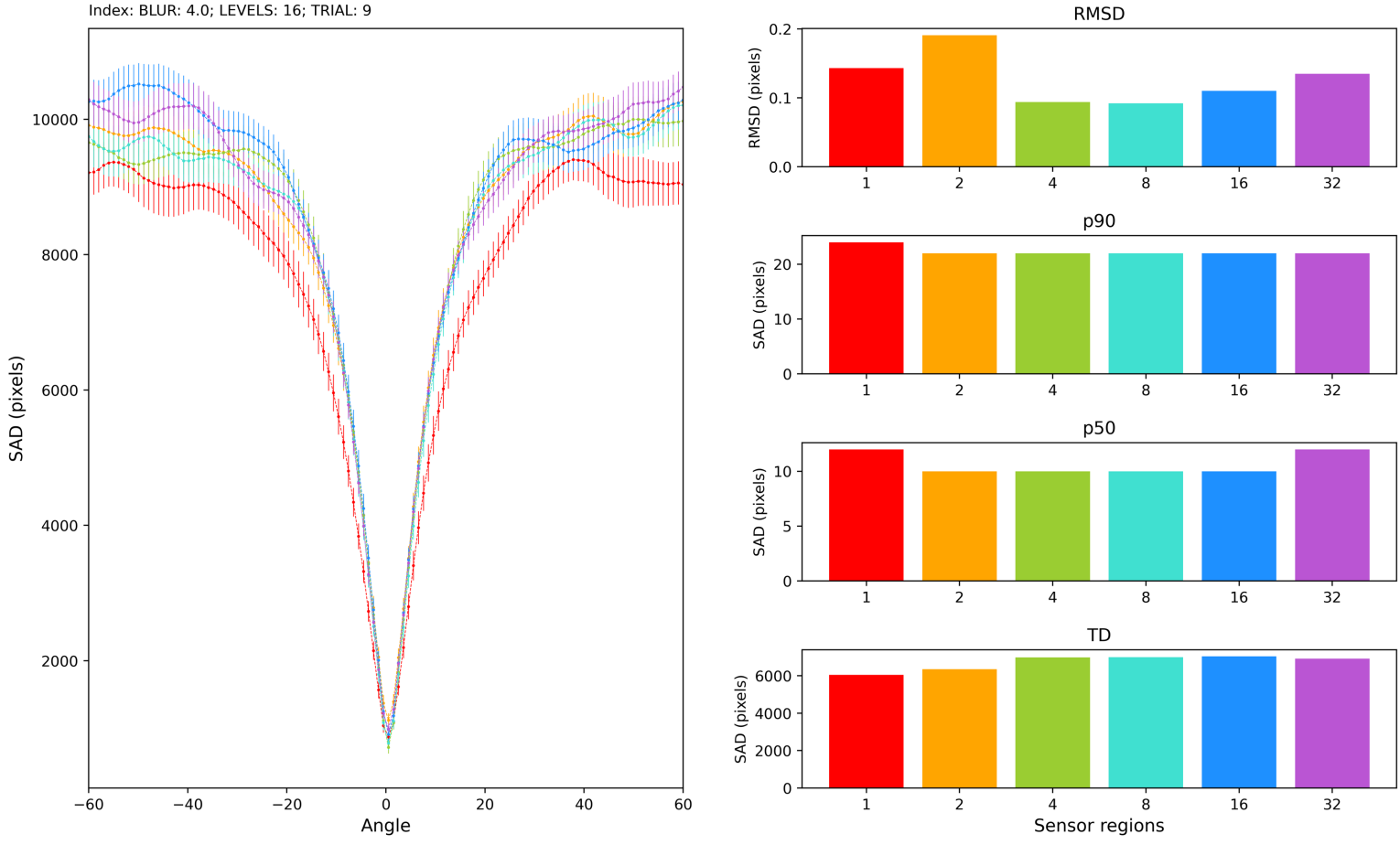
100%



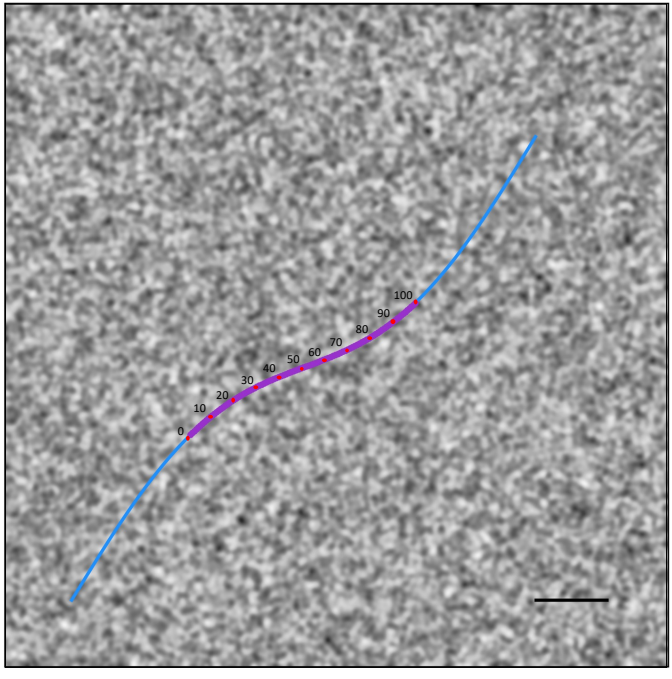



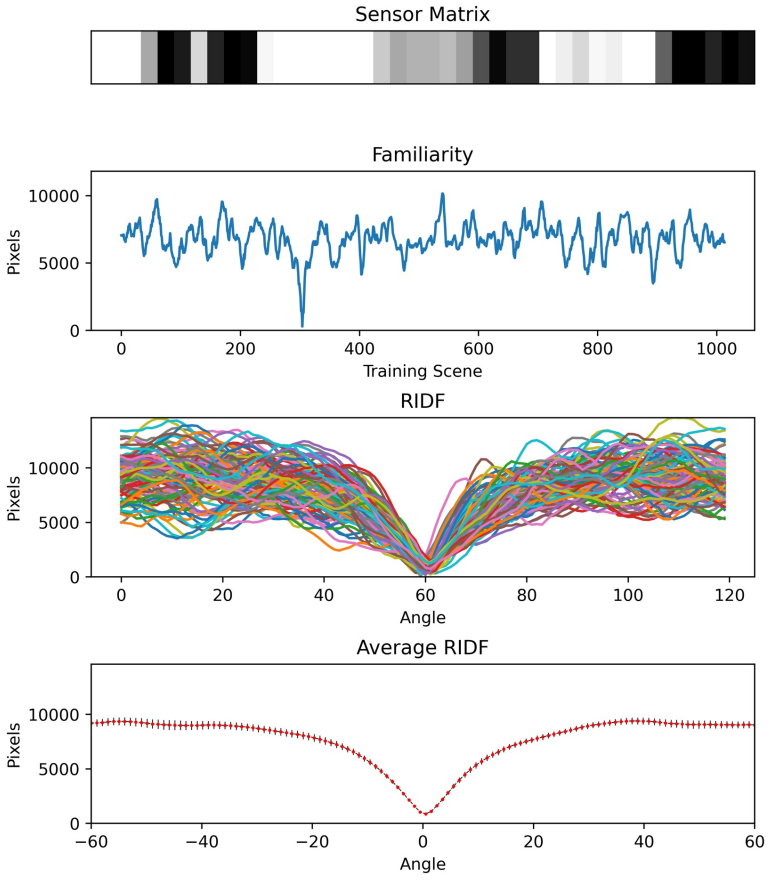

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 39.72; RMSD/dist: 0.099; TD: 7058; p90: 18; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 16; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

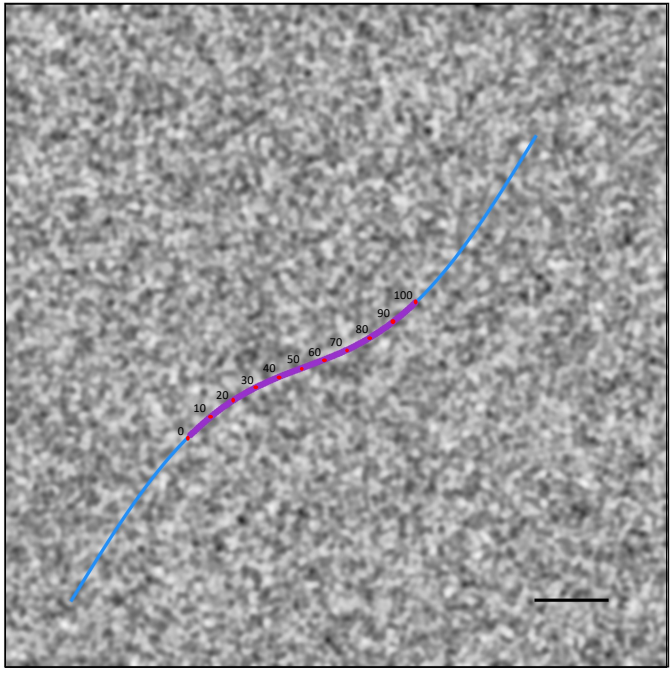


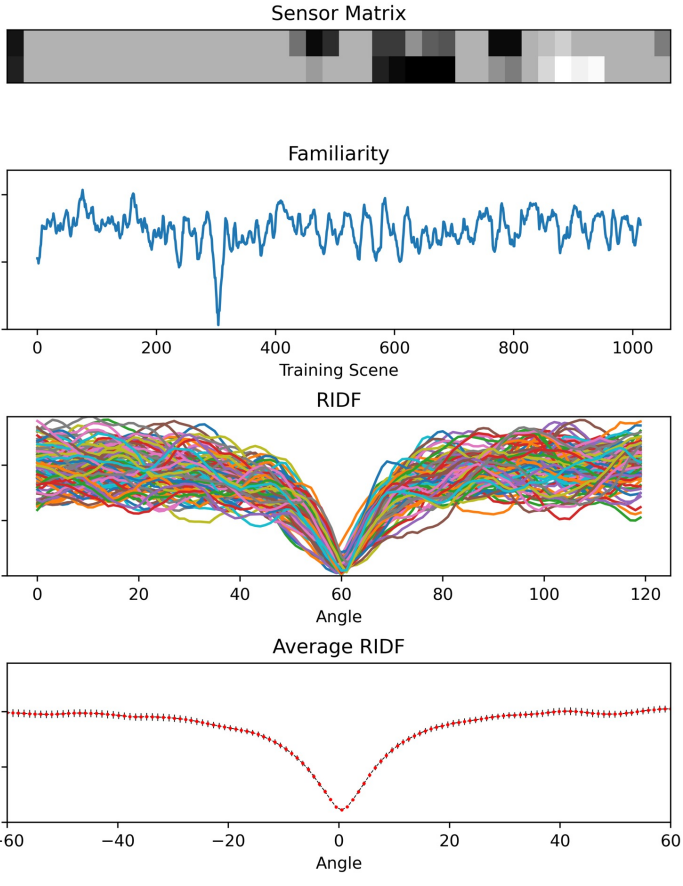




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 57.12; RMSD/dist: 0.143; TD: 6046; p90: 24; p50: 12; complete: 0

100%

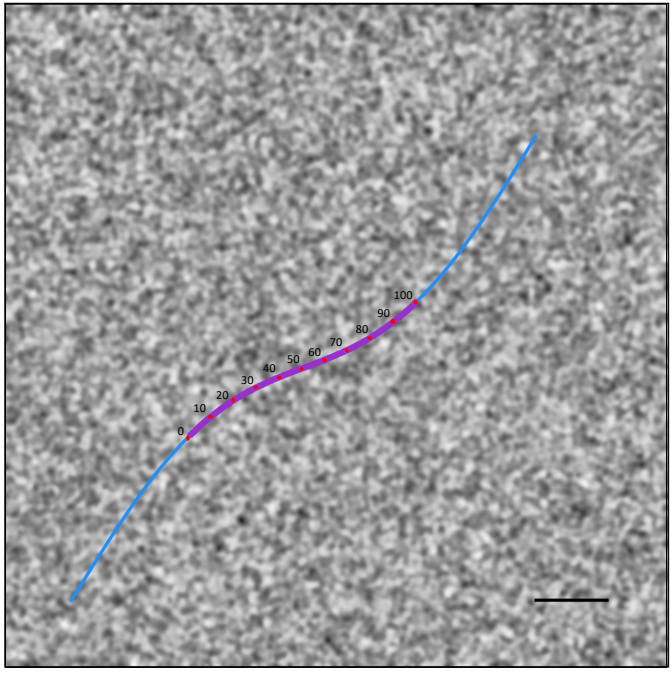


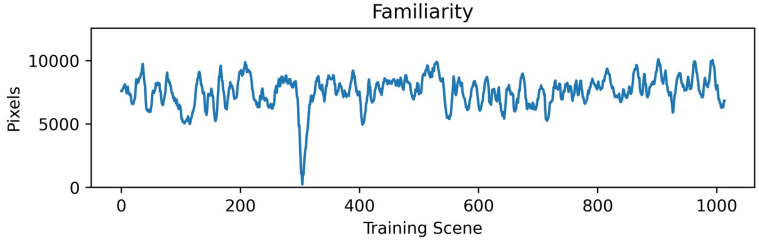



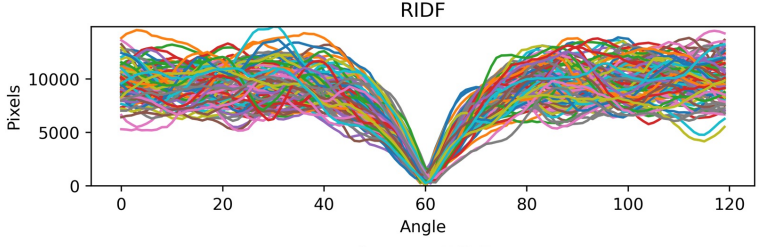

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

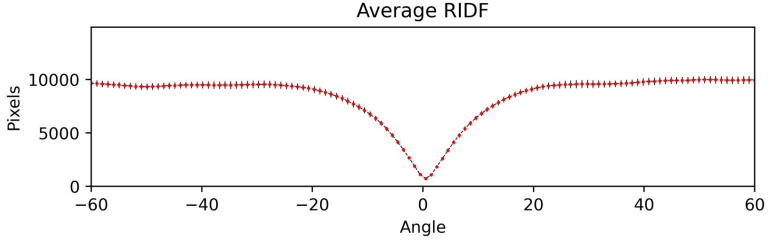
Navigation stats: RMSD error: 76.32; RMSD/dist: 0.191; TD: 6350; p90: 22; p50: 10; complete: 0

100%





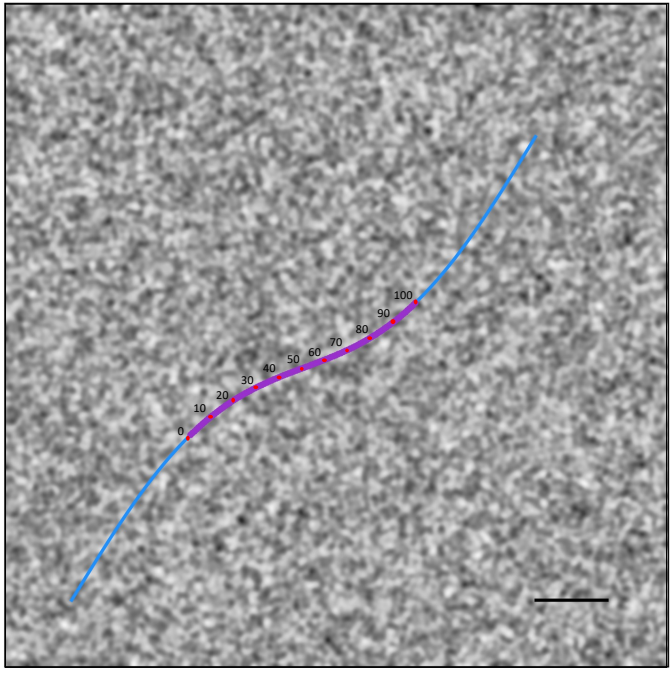



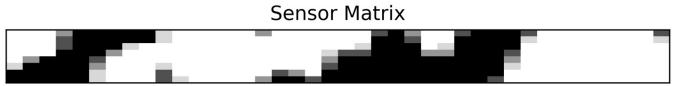



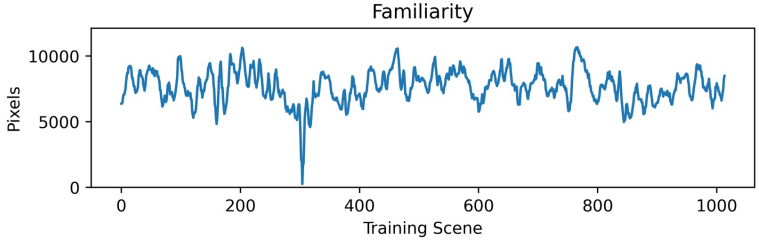

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

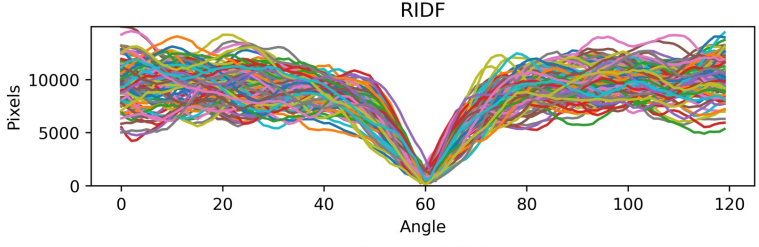
Navigation stats: RMSD error: 37.62; RMSD/dist: 0.094; TD: 6985; p90: 22; p50: 10; complete: 0

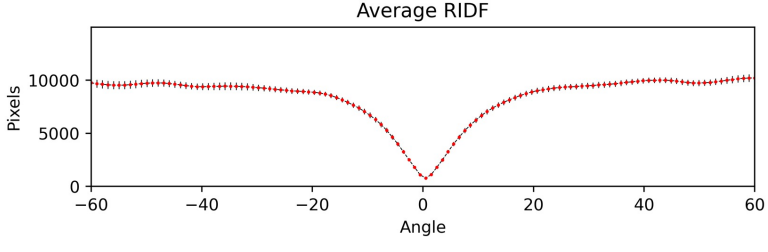
100%



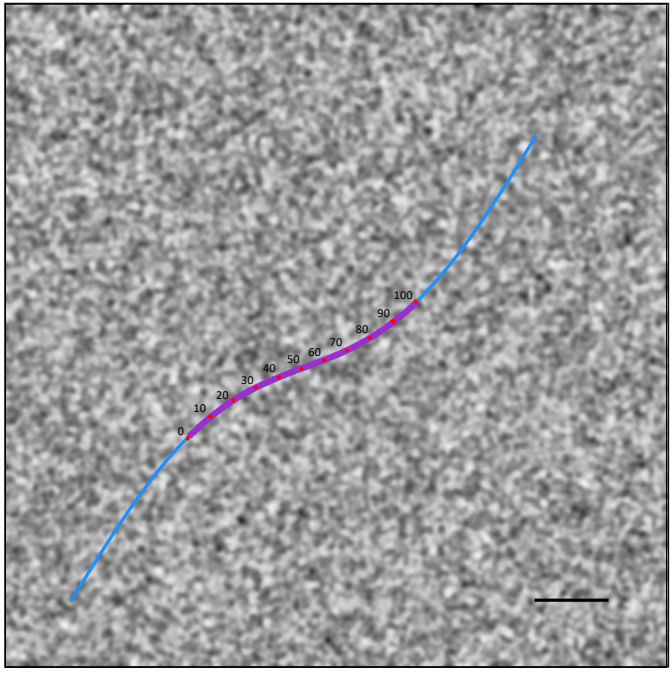



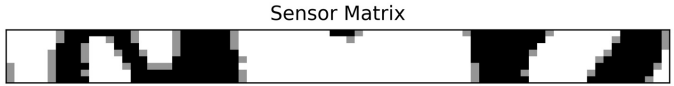



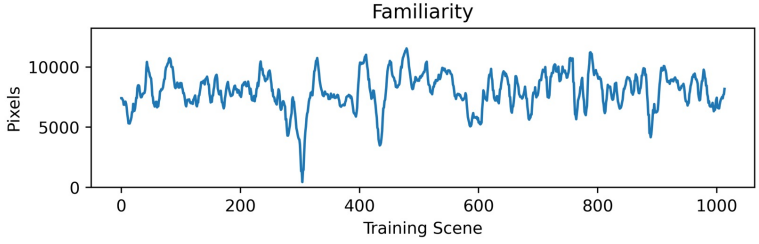

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

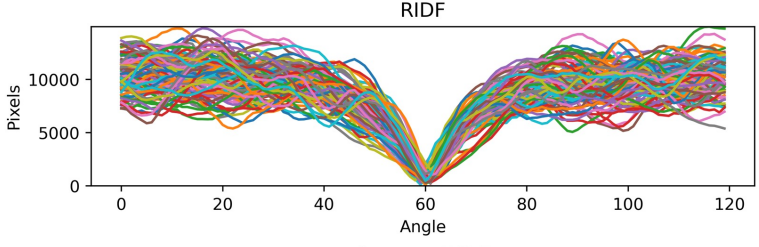
Navigation stats: RMSD error: 36.67; RMSD/dist: 0.092; TD: 6992; p90: 22; p50: 10; complete: 0

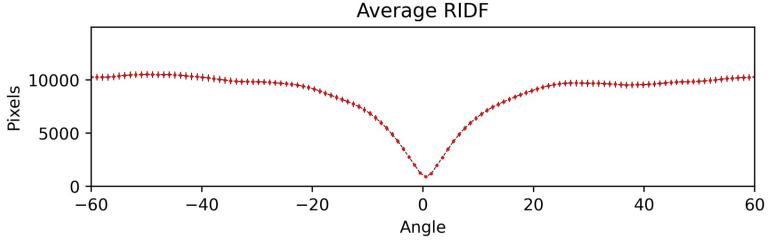
100%



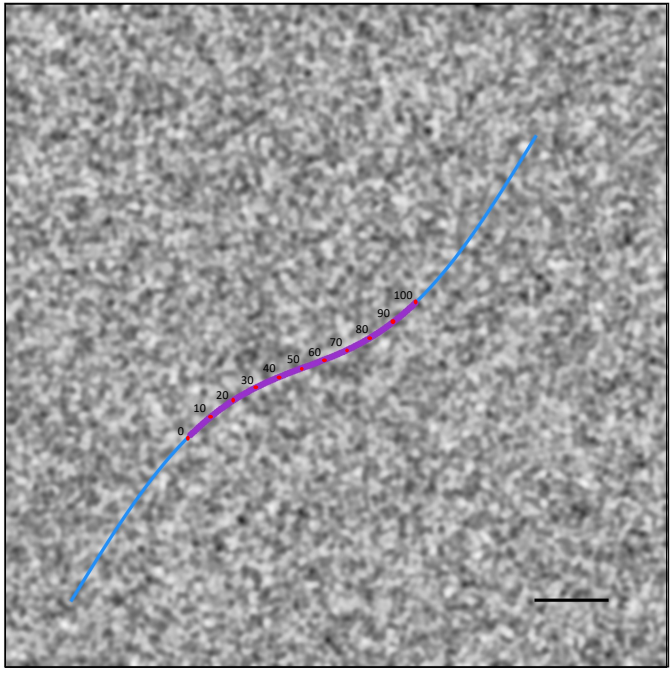



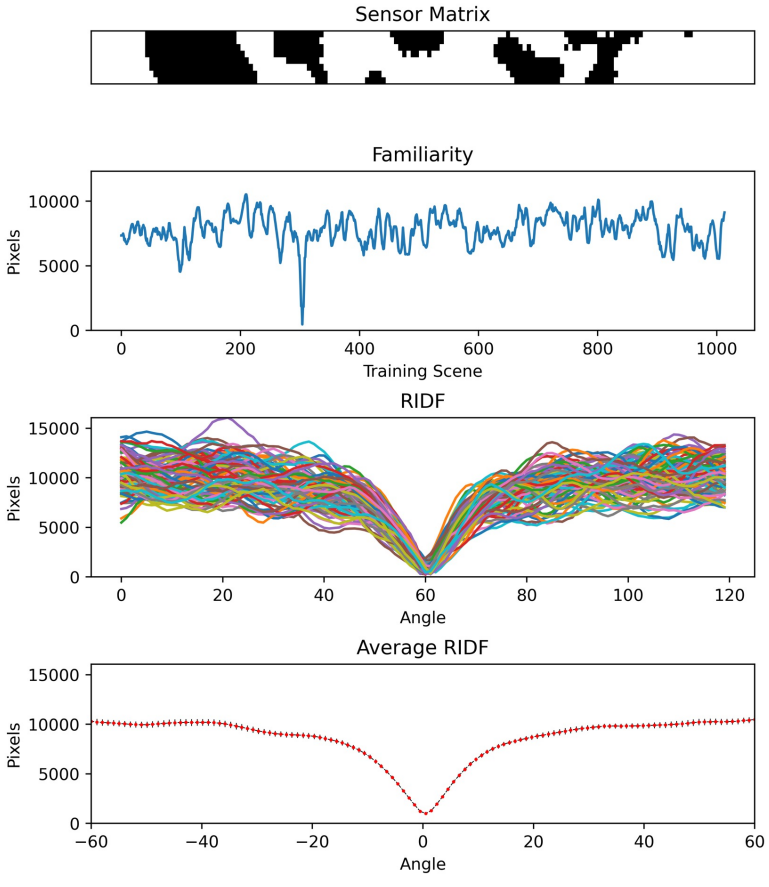




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 43.99; RMSD/dist: 0.110; TD: 7036; p90: 22; p50: 10; complete: 0

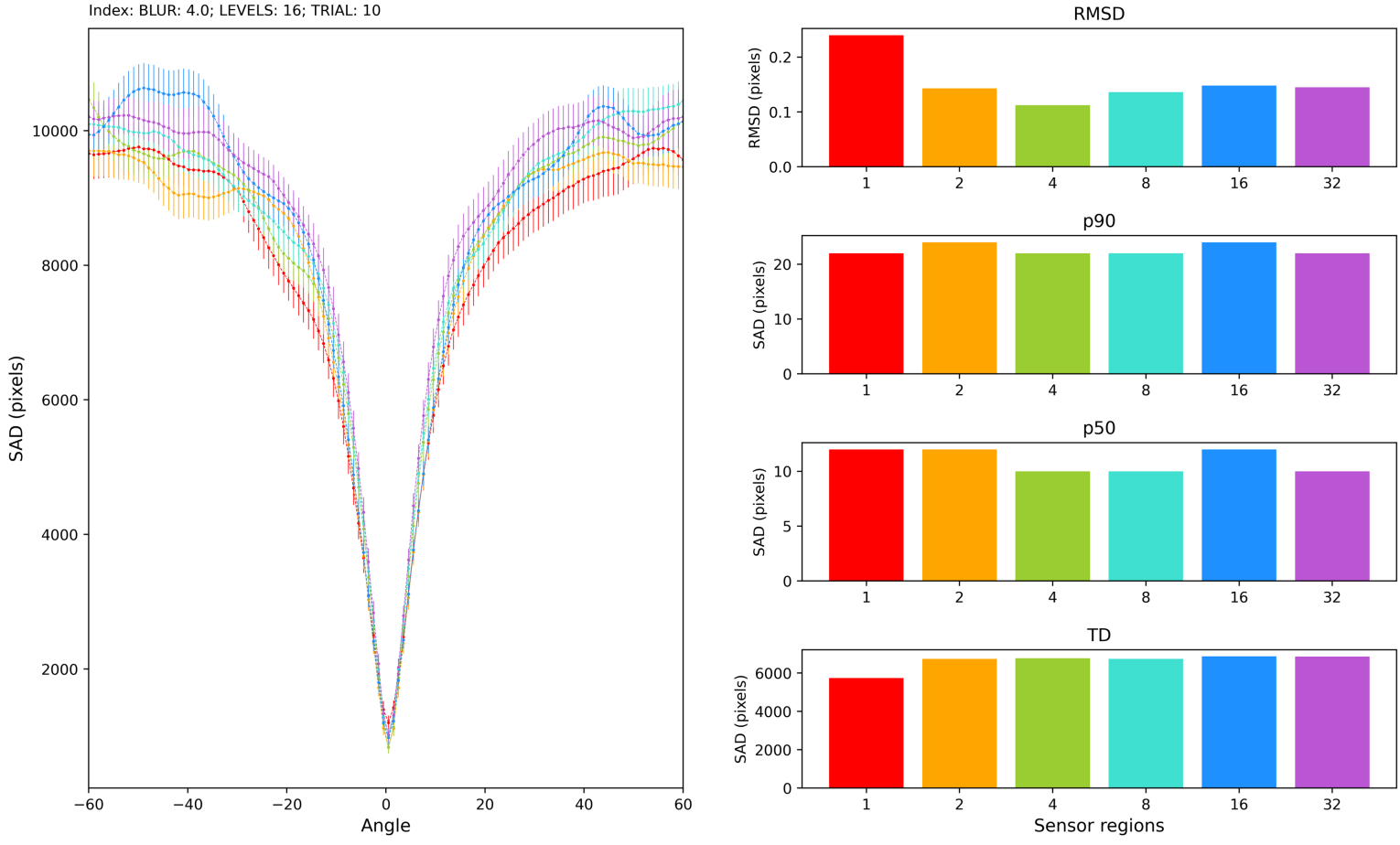
100%



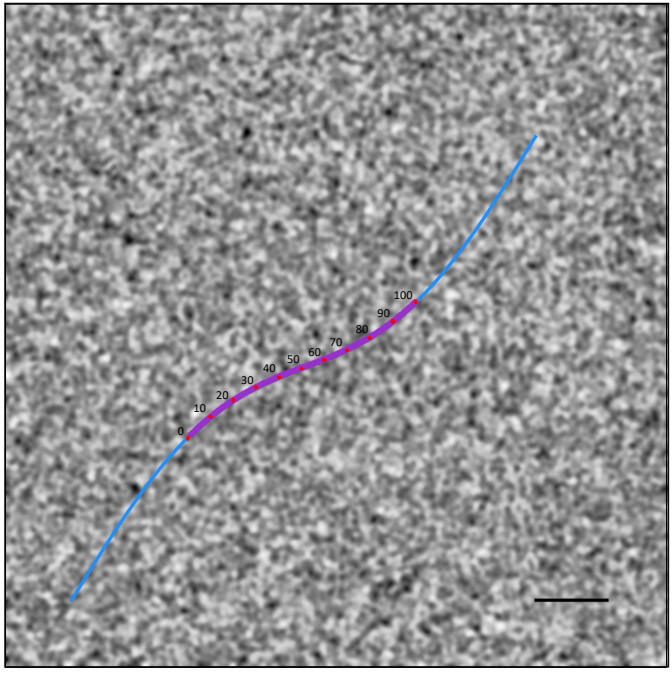



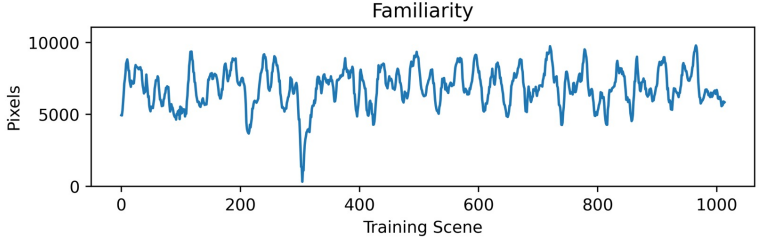

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

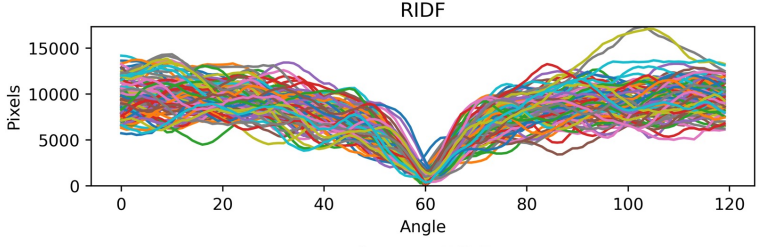
Navigation stats: RMSD error: 53.91; RMSD/dist: 0.135; TD: 6920; p90: 22; p50: 12; complete: 0

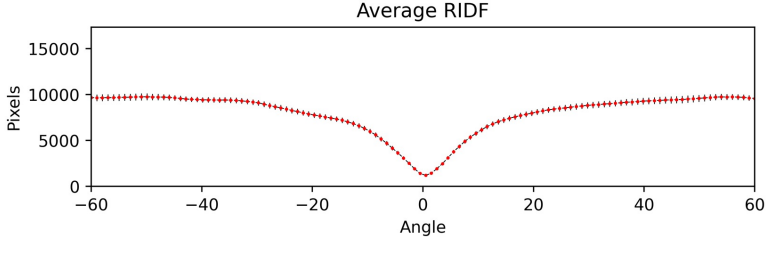

Index: BLUR: 4.0; LEVELS: 16; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

100%





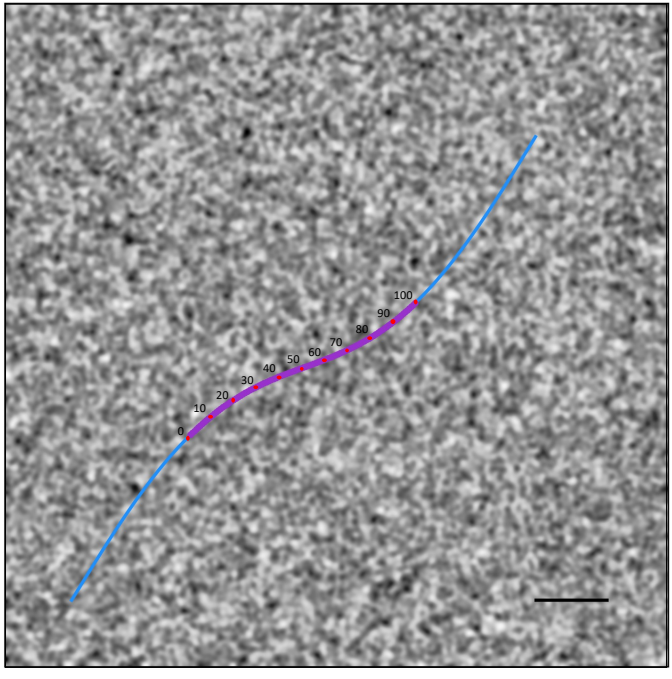



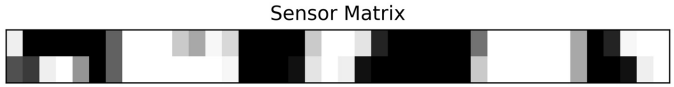



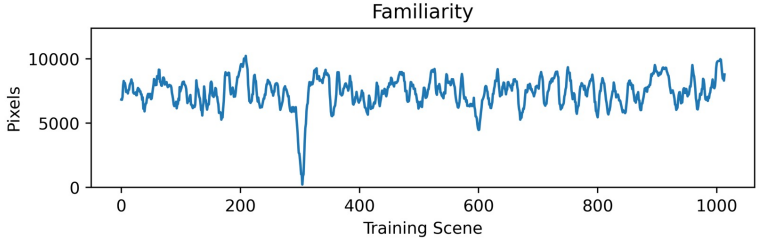

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

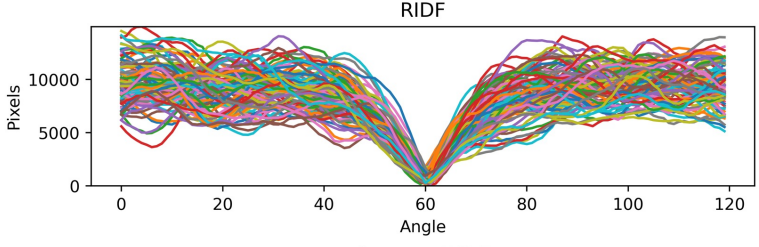
Navigation stats: RMSD error: 96.12; RMSD/dist: 0.240; TD: 5740; p90: 22; p50: 12; complete: 0

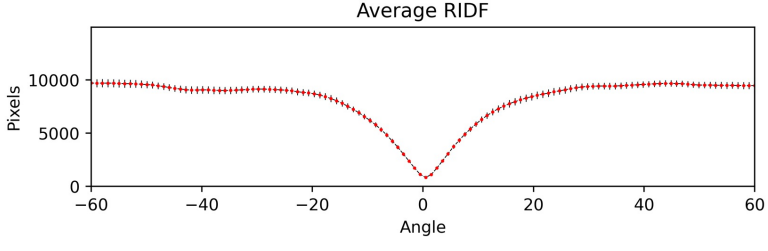
100%



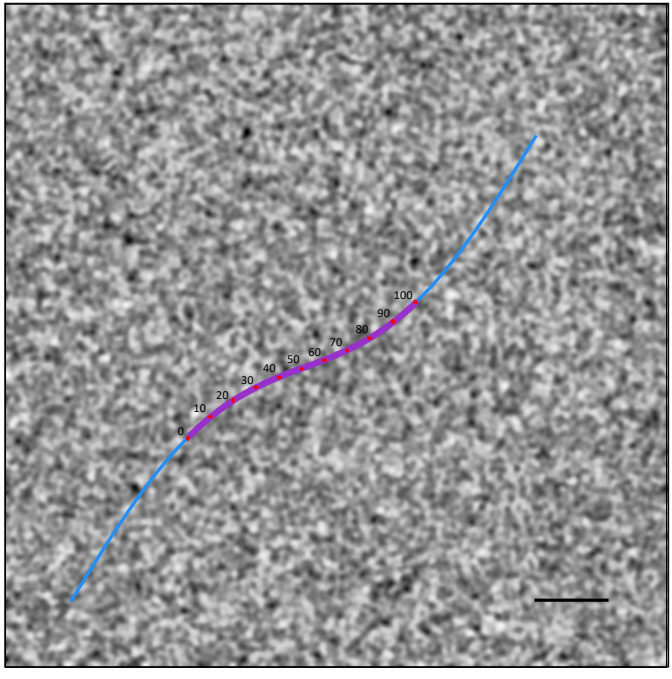



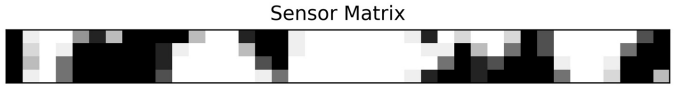



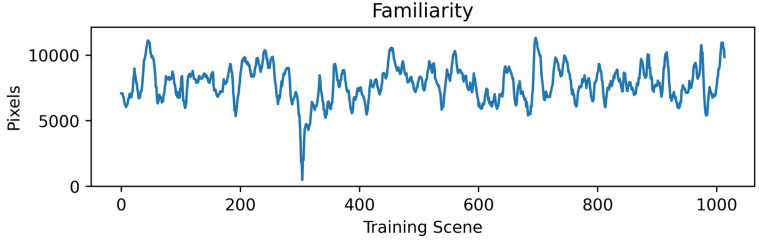

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

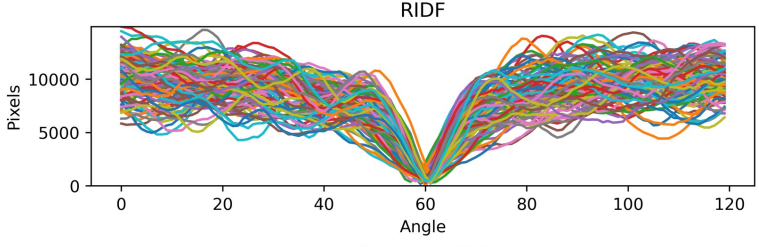
Navigation stats: RMSD error: 57.30; RMSD/dist: 0.143; TD: 6732; p90: 24; p50: 12; complete: 0

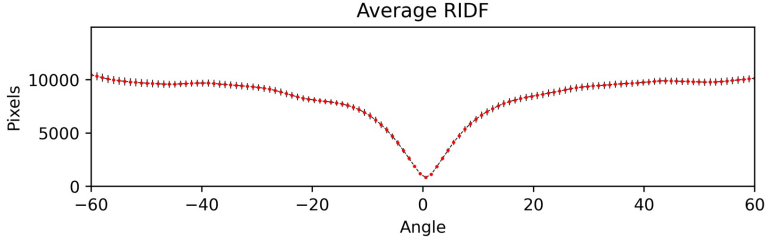
100%



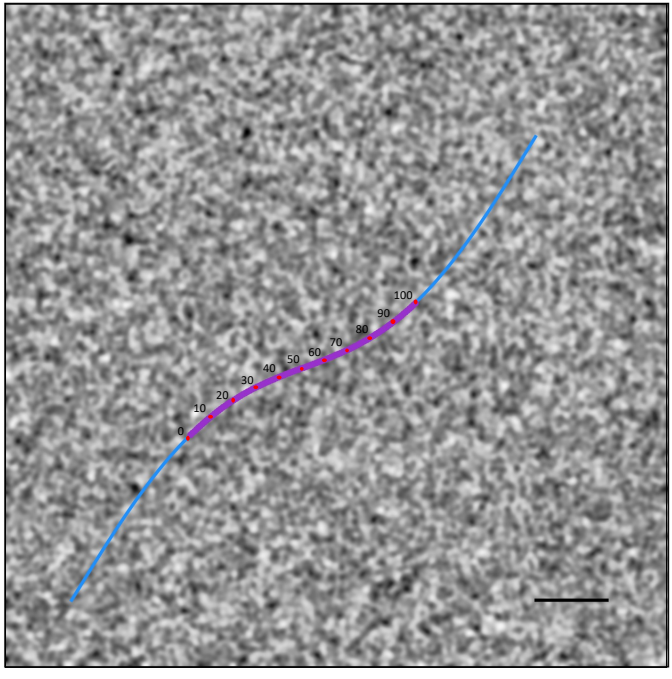



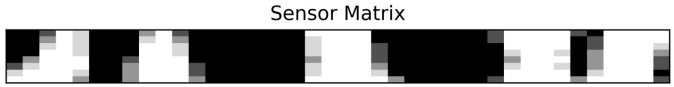



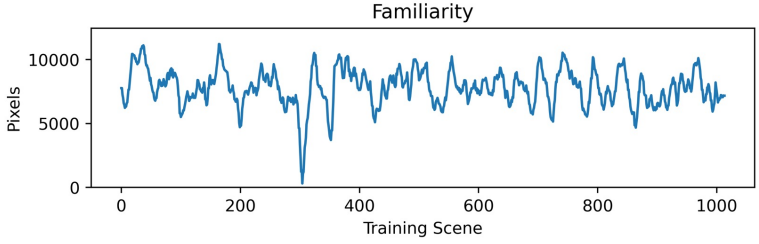

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

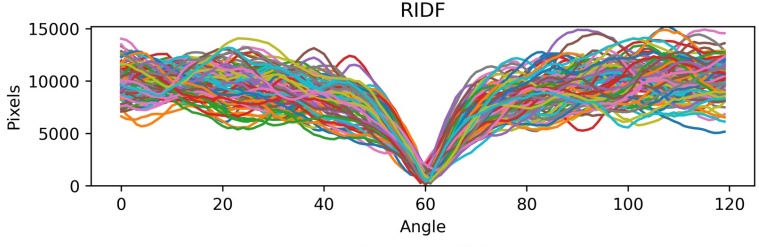
Navigation stats: RMSD error: 44.73; RMSD/dist: 0.112; TD: 6765; p90: 22; p50: 10; complete: 0

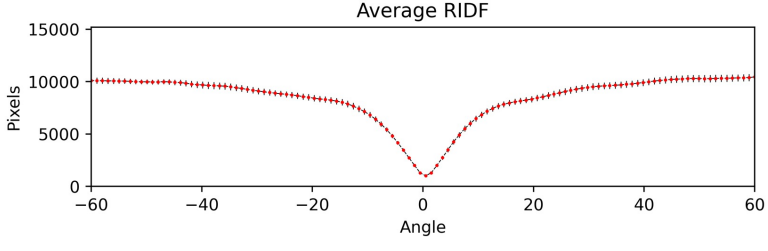
100%



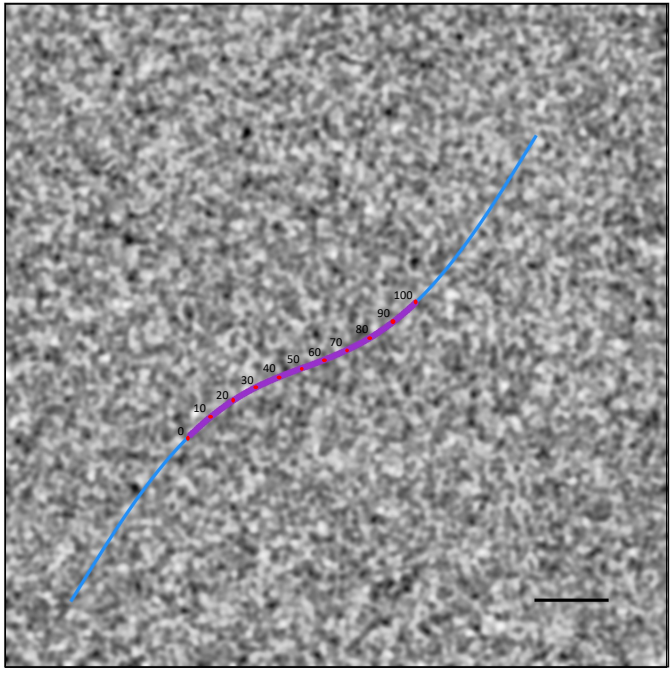



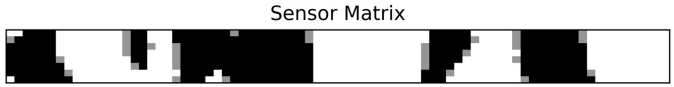



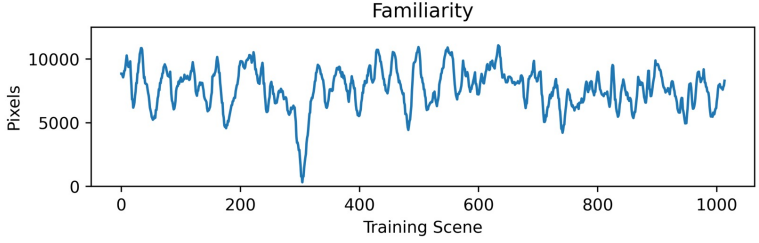

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

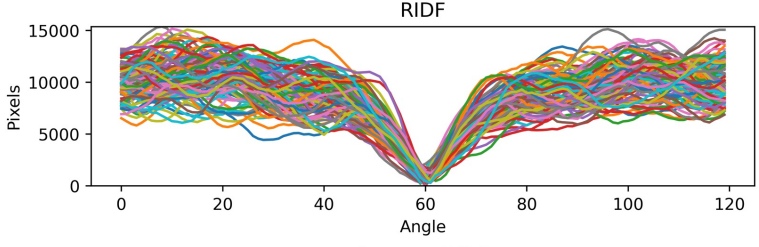
Navigation stats: RMSD error: 54.41; RMSD/dist: 0.136; TD: 6736; p90: 22; p50: 10; complete: 0

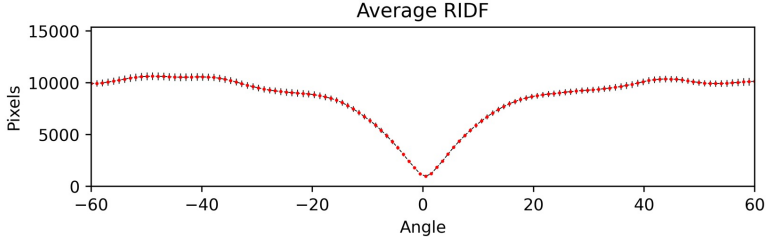
100%



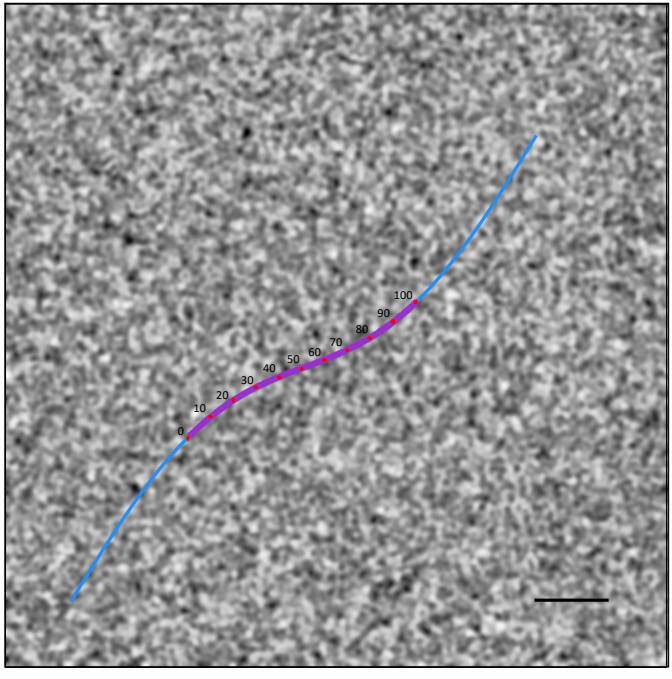



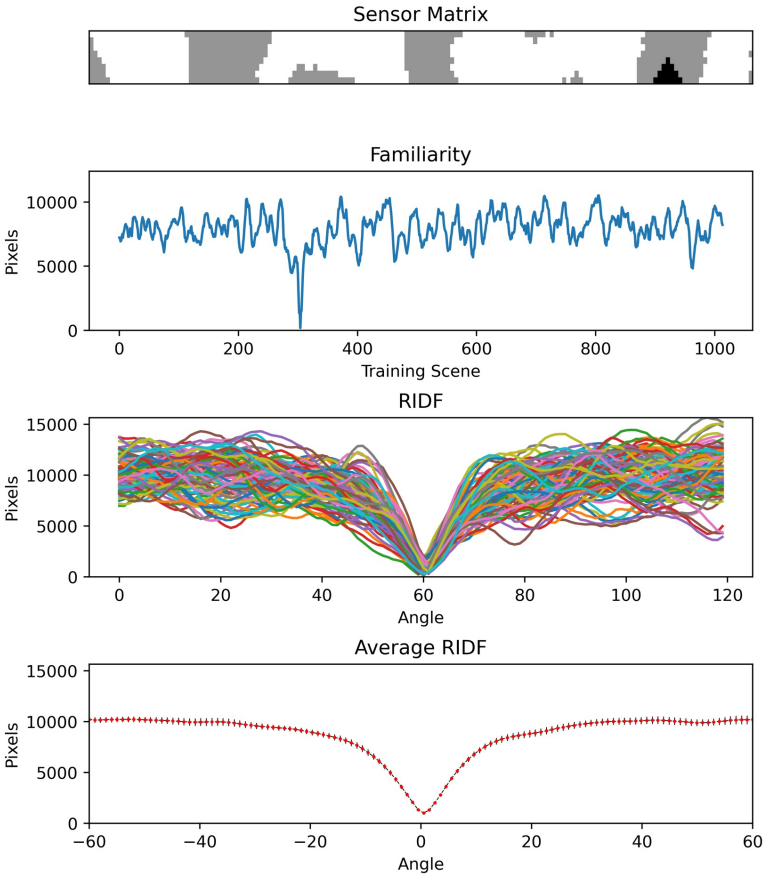




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 59.15; RMSD/dist: 0.148; TD: 6862; p90: 24; p50: 12; complete: 0

100%




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 58.07; RMSD/dist: 0.145; TD: 6854; p90: 22; p50: 10; complete: 0