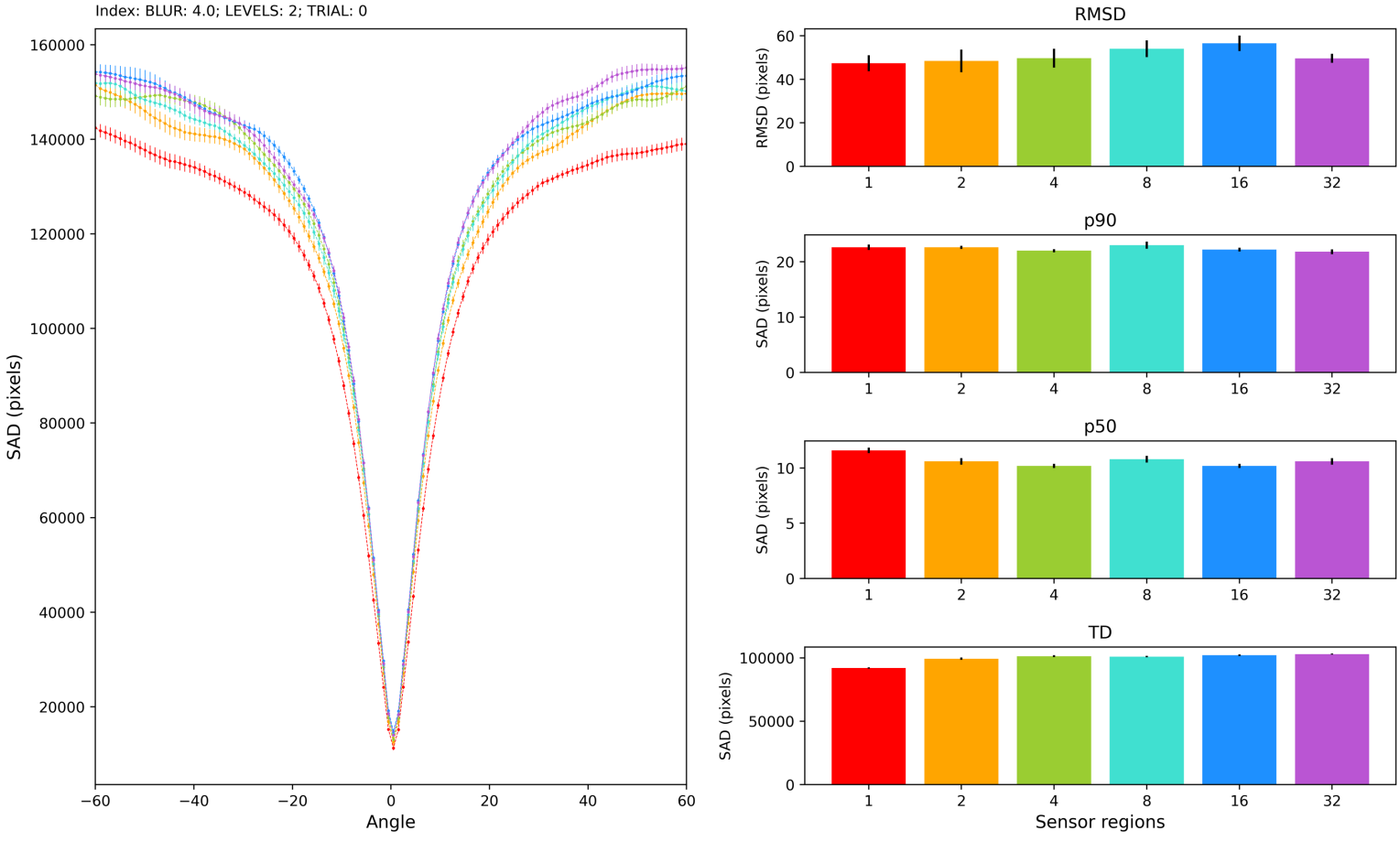
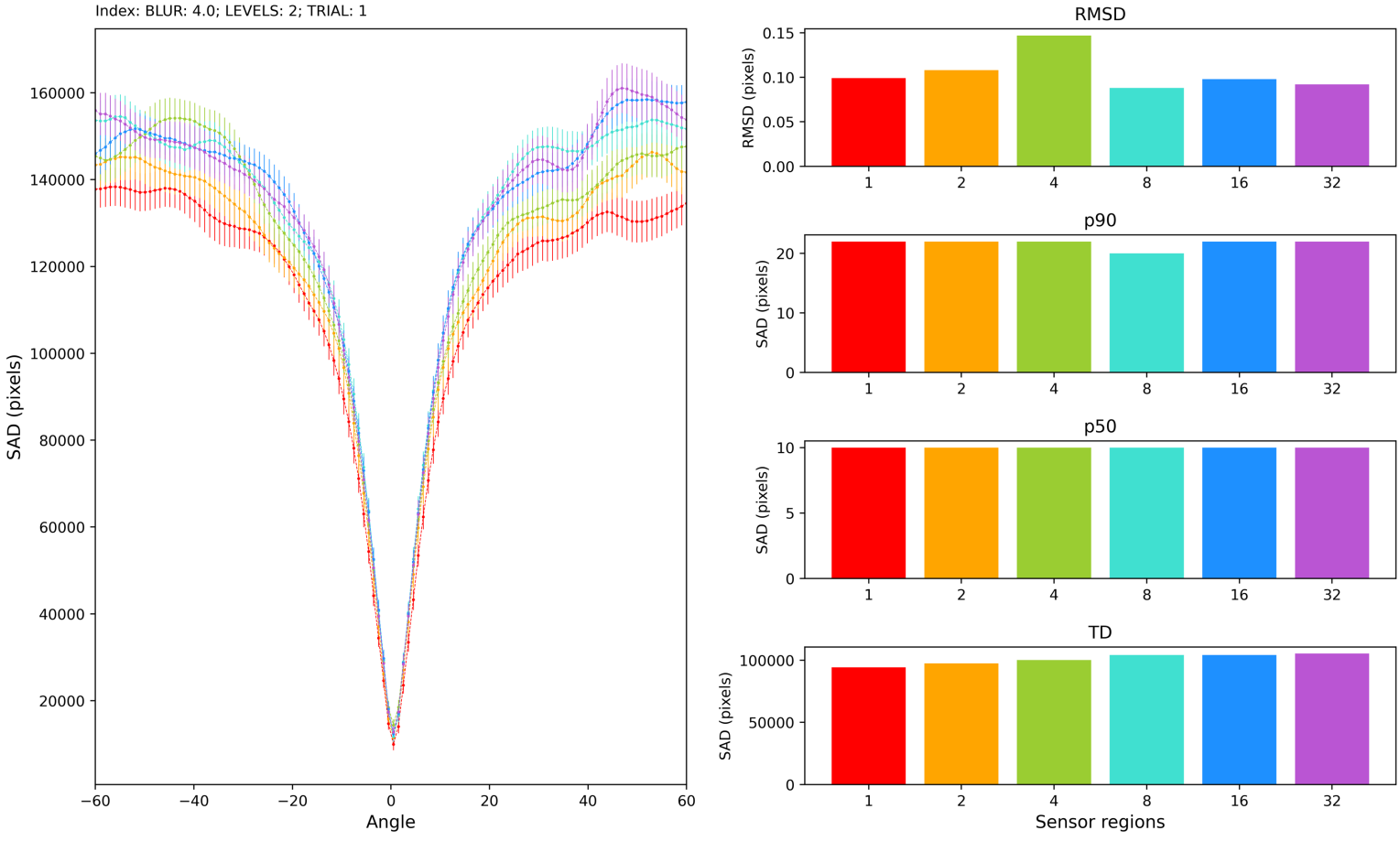
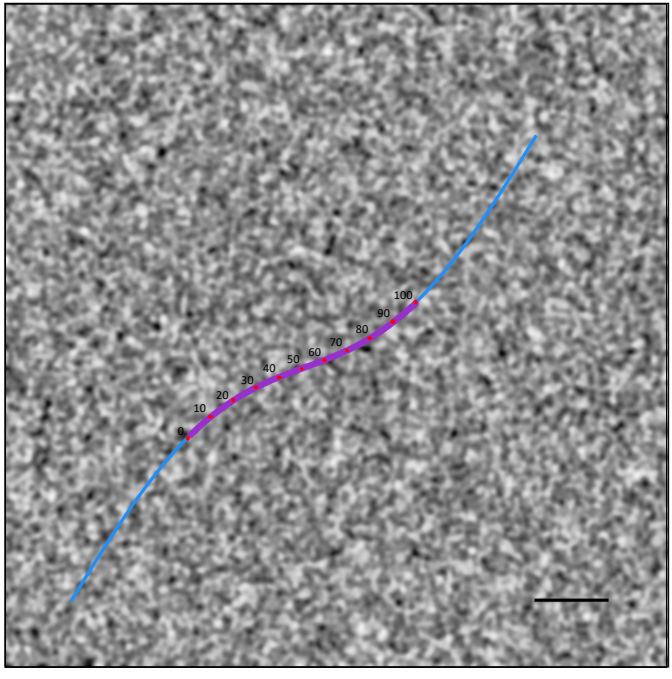
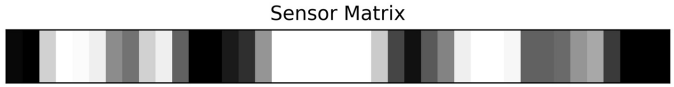
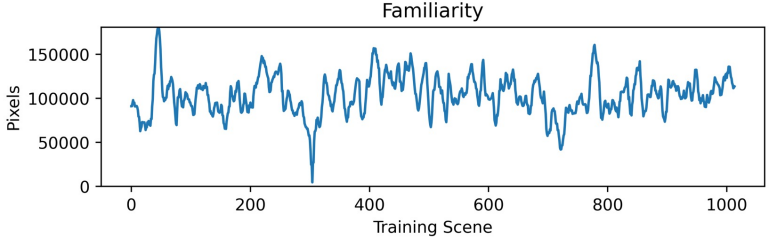

Index: BLUR: 4.0; LEVELS: 2; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

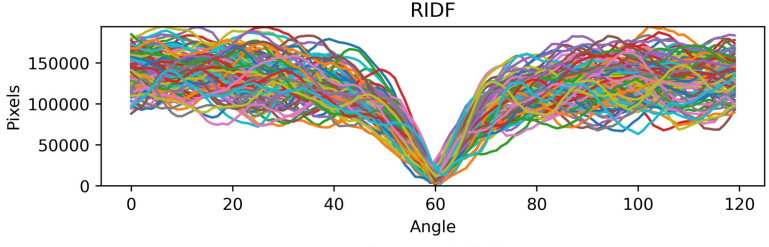

Index: BLUR: 4.0; LEVELS: 2; TRIAL: 1
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

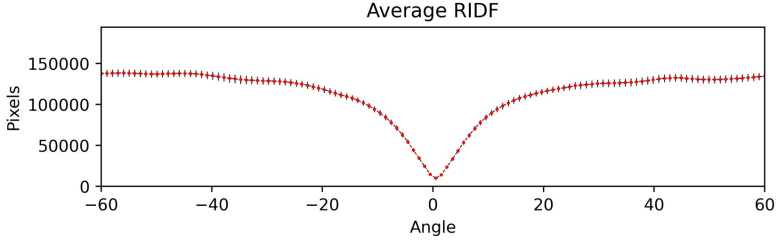
100%







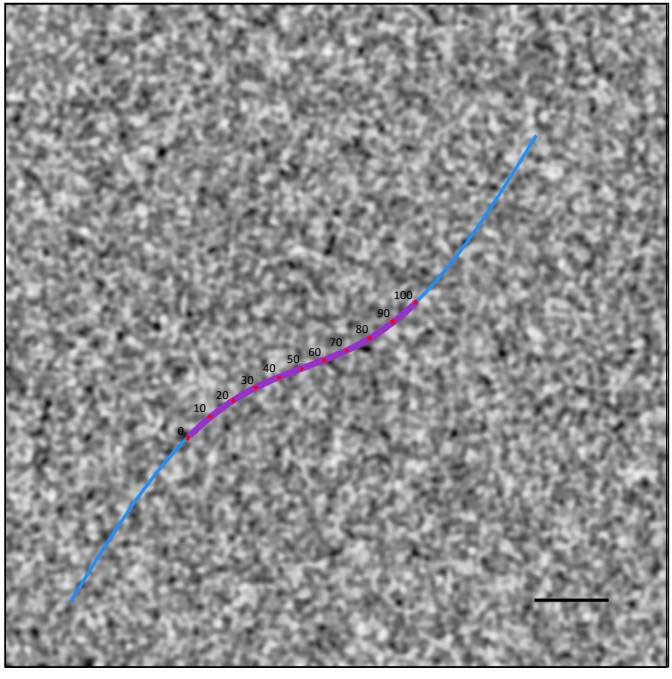


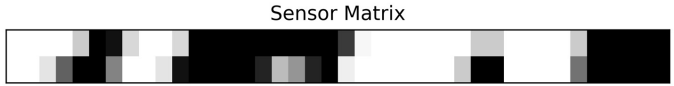


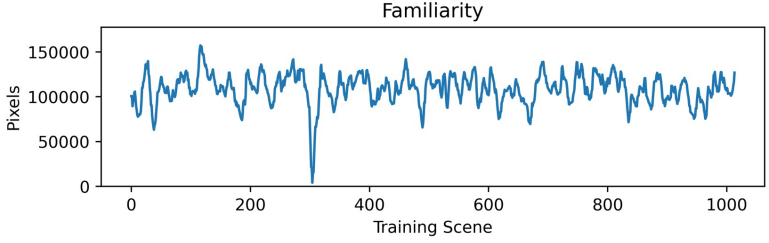
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

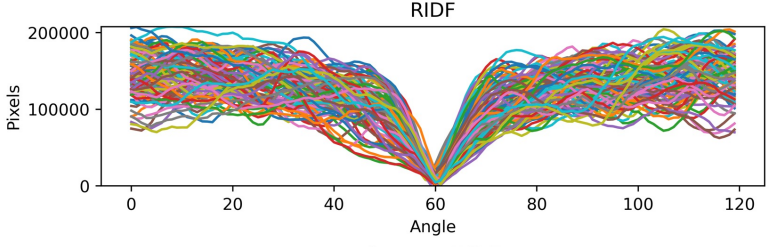
Navigation stats: RMSD error: 39.66; RMSD/dist: 0.099; TD: 94212; p90: 22; p50: 10; complete: 0

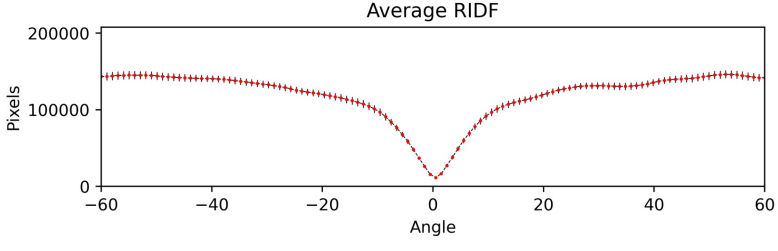
100%







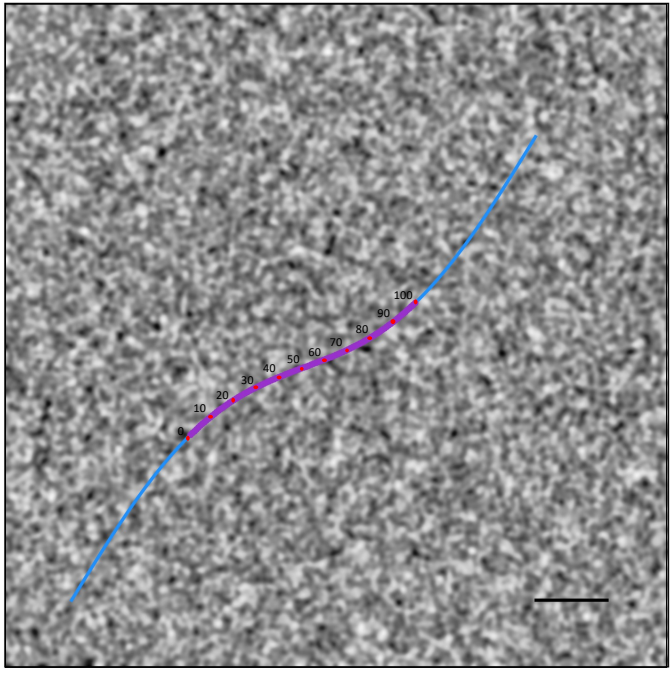


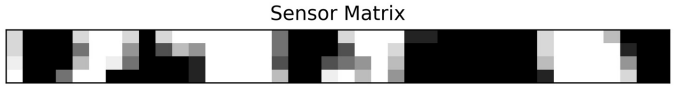


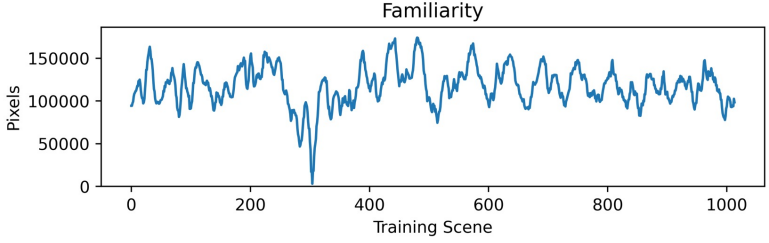
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

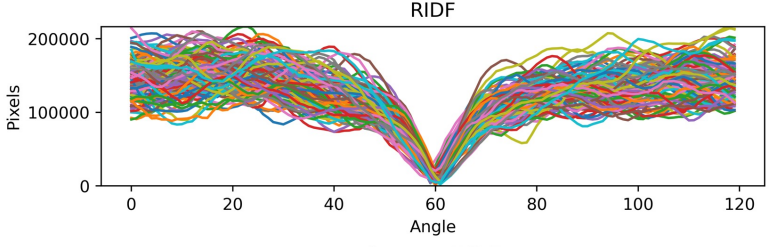
Navigation stats: RMSD error: 43.30; RMSD/dist: 0.108; TD: 97372; p90: 22; p50: 10; complete: 0

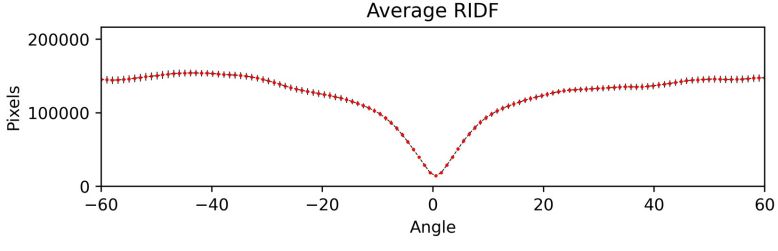
100%







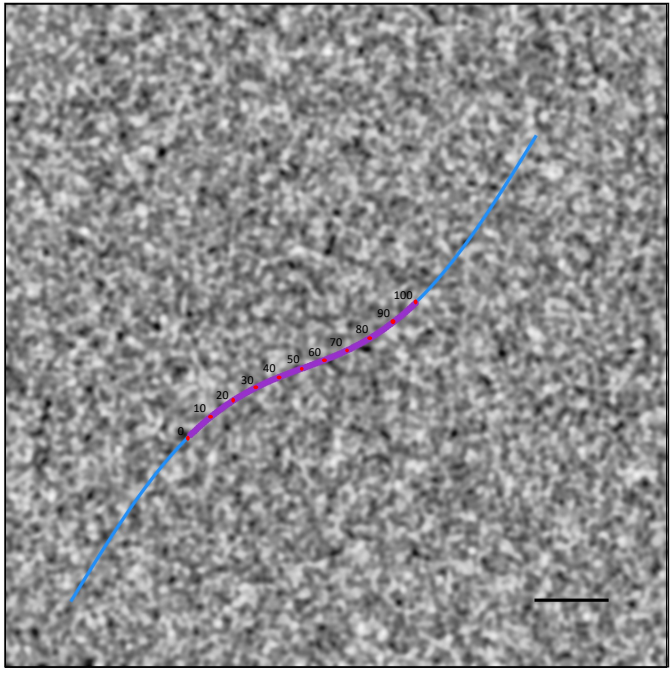


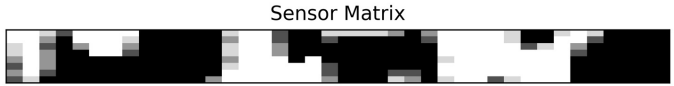


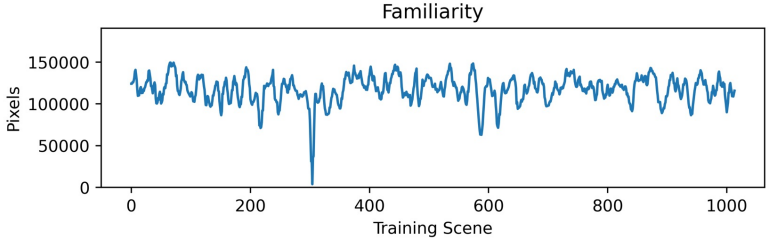
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

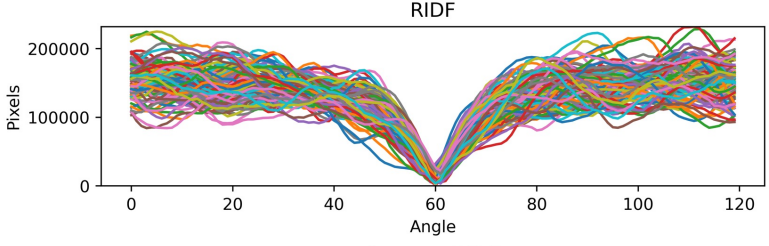
Navigation stats: RMSD error: 58.79; RMSD/dist: 0.147; TD: 100188; p90: 22; p50: 10; complete: 0

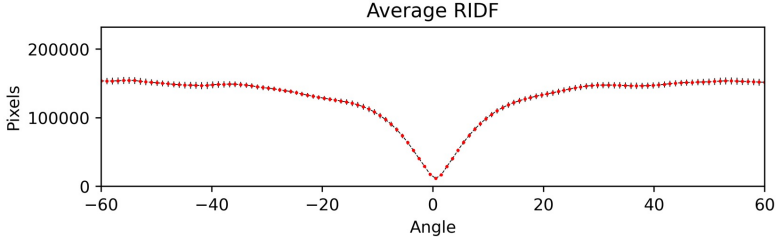
100%







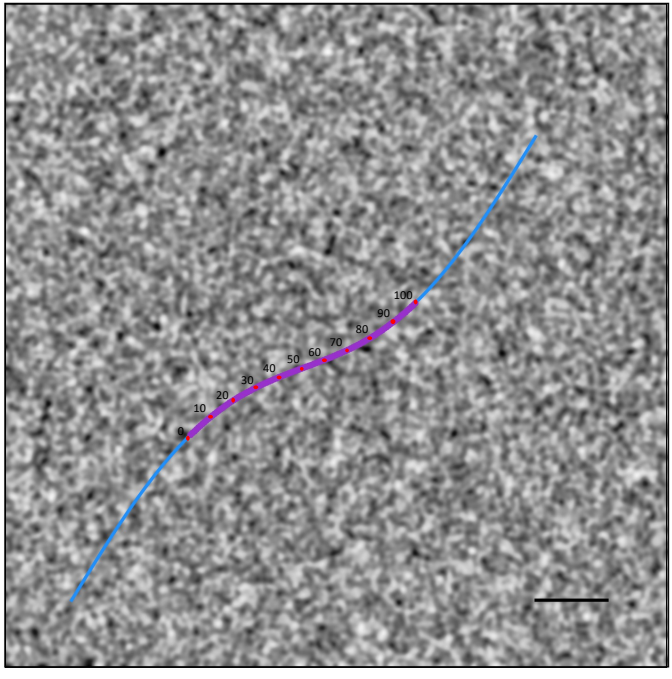


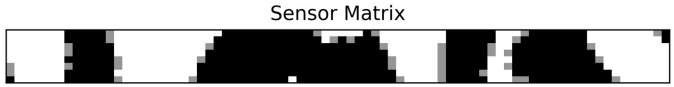


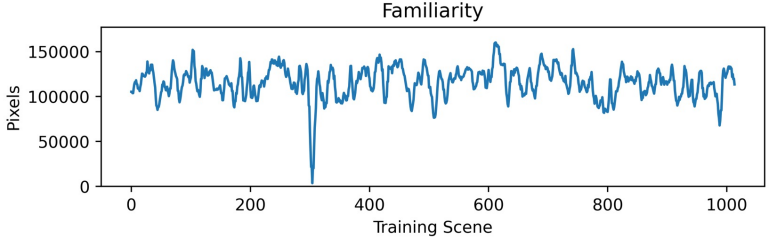
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

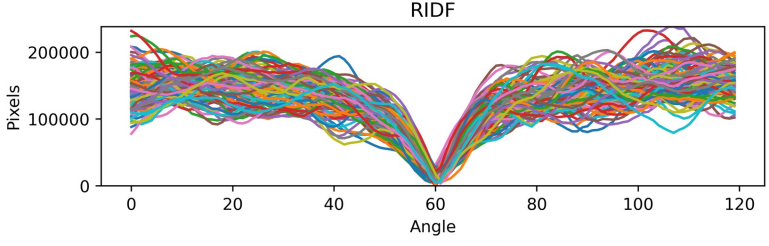
Navigation stats: RMSD error: 35.19; RMSD/dist: 0.088; TD: 104149; p90: 20; p50: 10; complete: 0

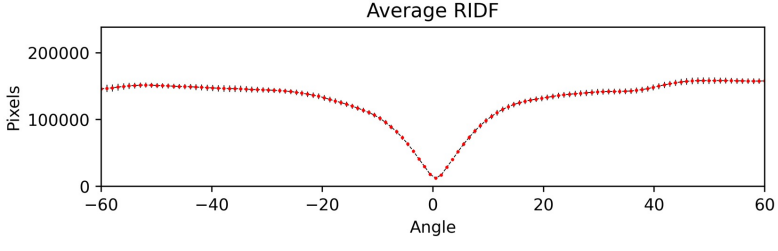
100%







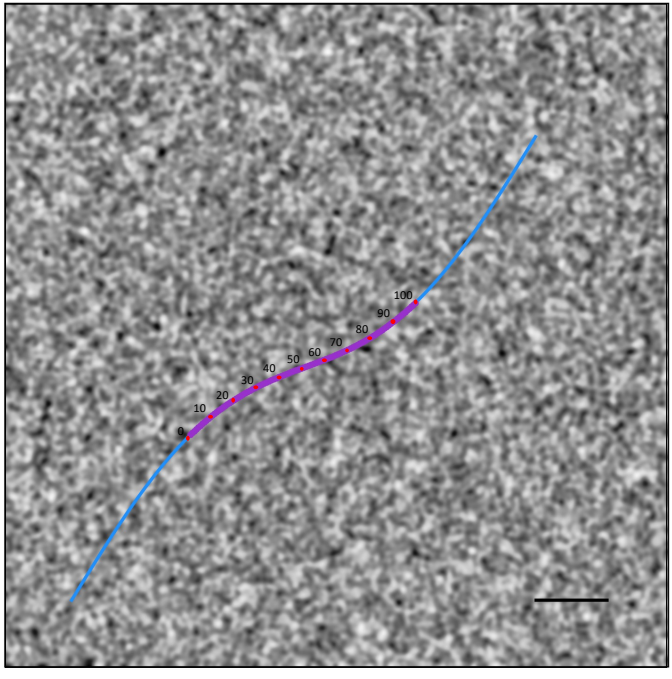


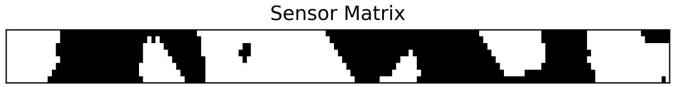


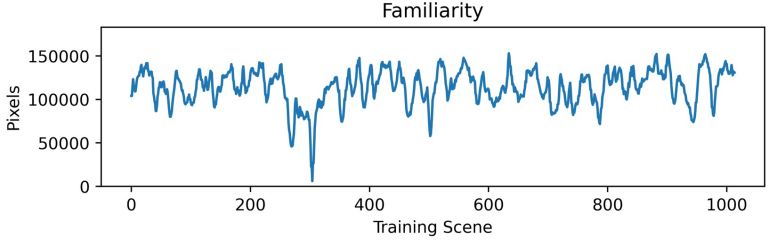
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

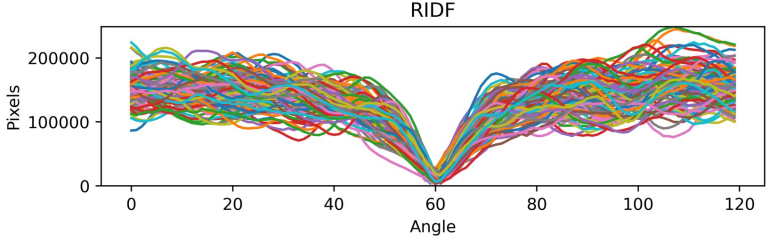
Navigation stats: RMSD error: 39.38; RMSD/dist: 0.098; TD: 104255; p90: 22; p50: 10; complete: 0

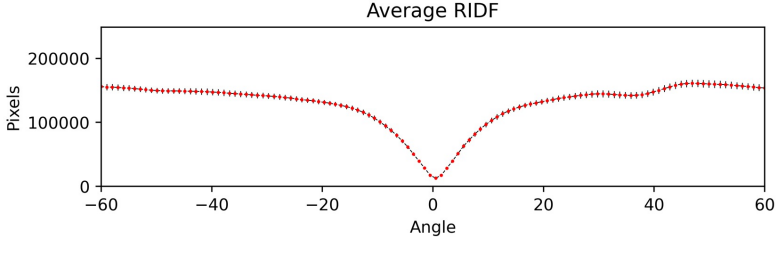
100%





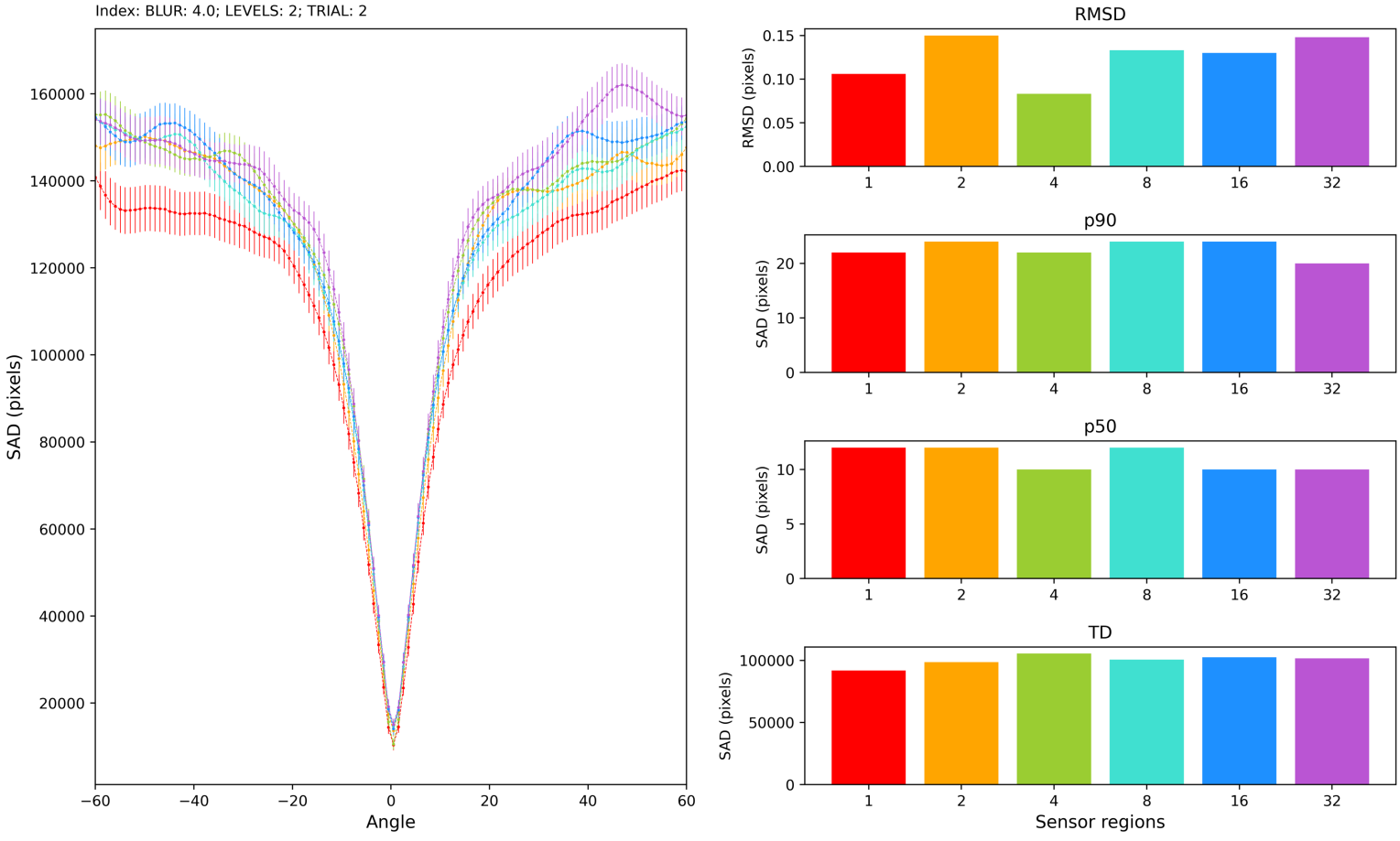




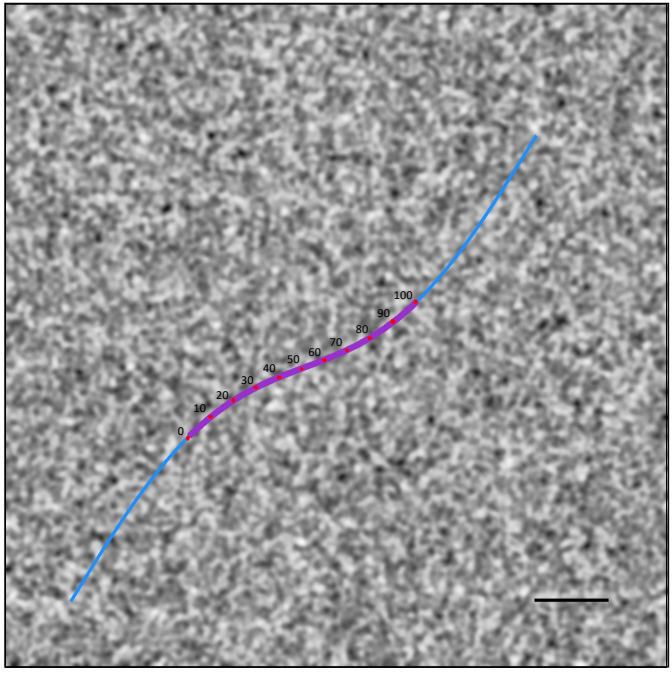


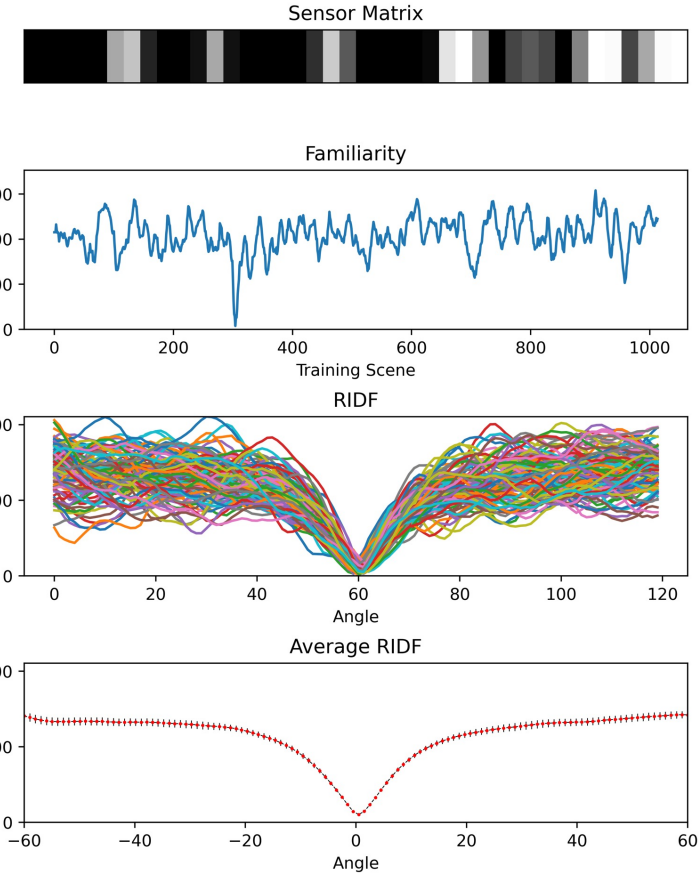
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 36.79; RMSD/dist: 0.092; TD: 105284; p90: 22; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 2; TRIAL: 2
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

100%

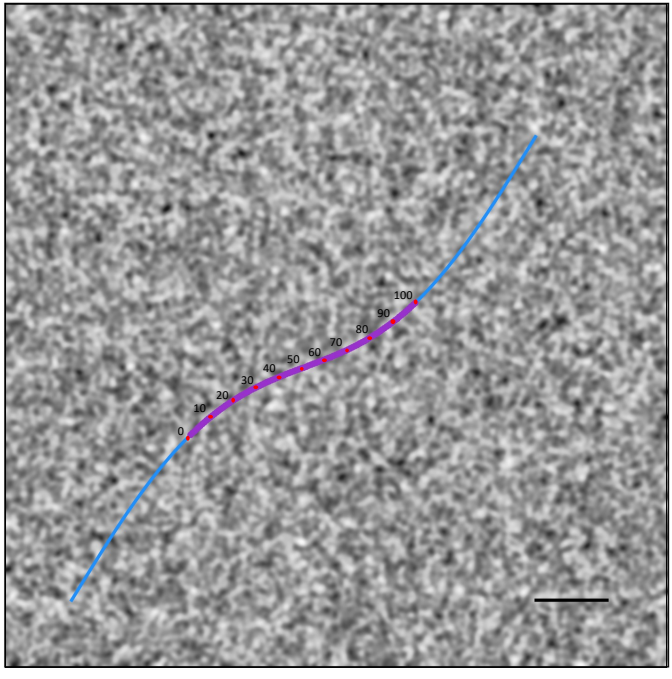


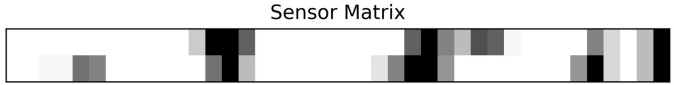


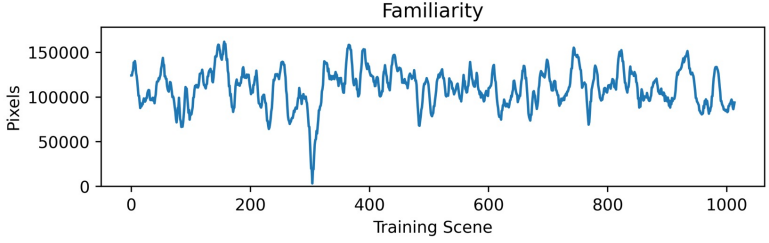
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

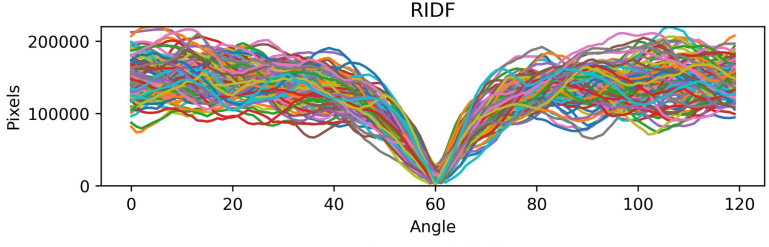
Navigation stats: RMSD error: 42.52; RMSD/dist: 0.106; TD: 91859; p90: 22; p50: 12; complete: 0

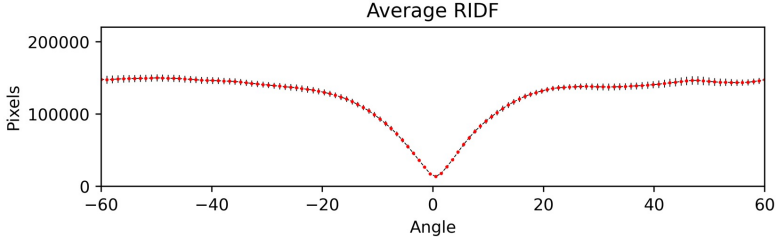
100%







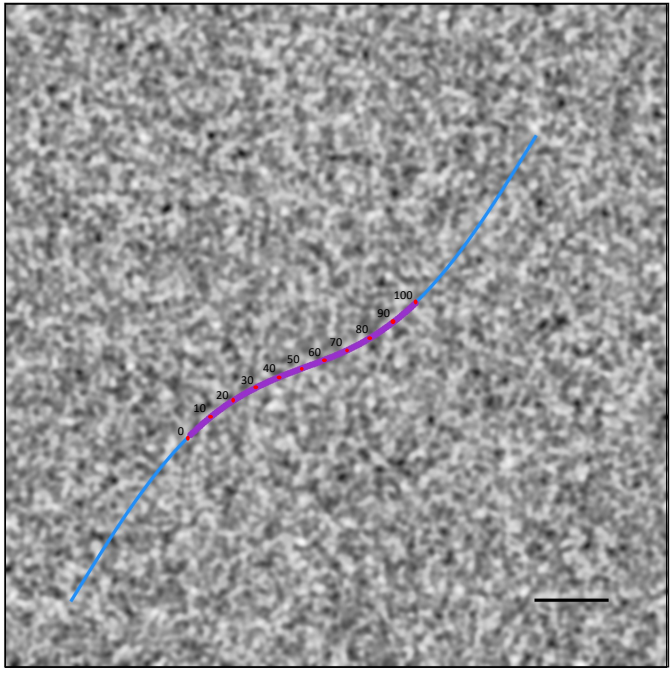


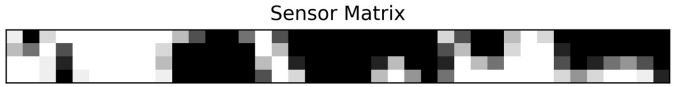


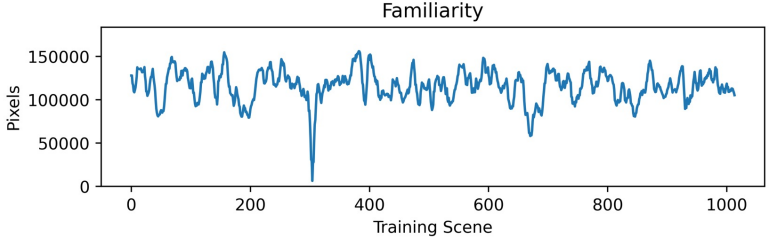
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

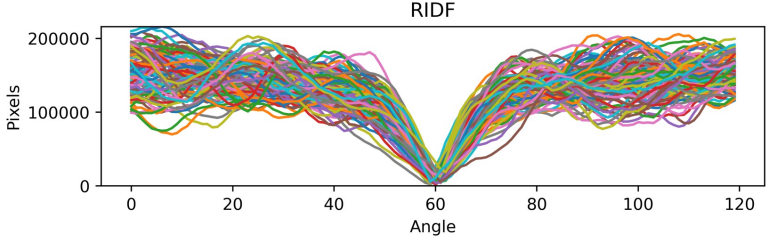
Navigation stats: RMSD error: 59.89; RMSD/dist: 0.150; TD: 98542; p90: 24; p50: 12; complete: 0

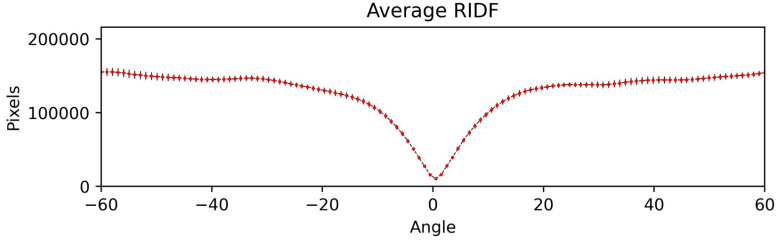
100%







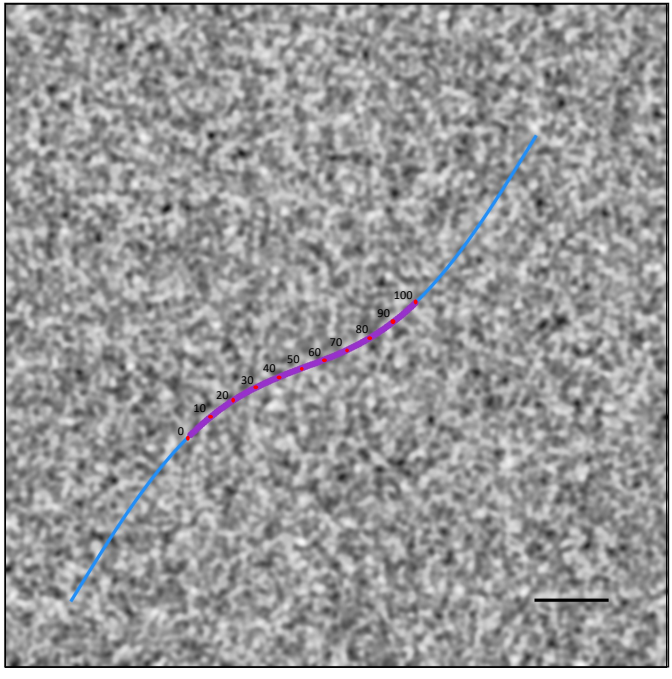


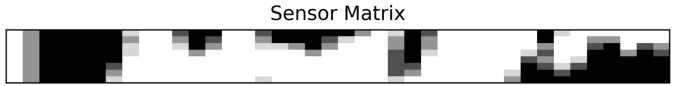


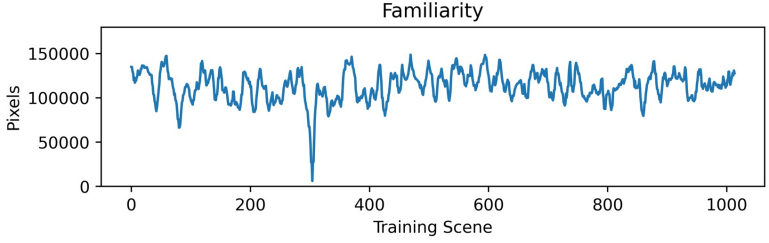
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

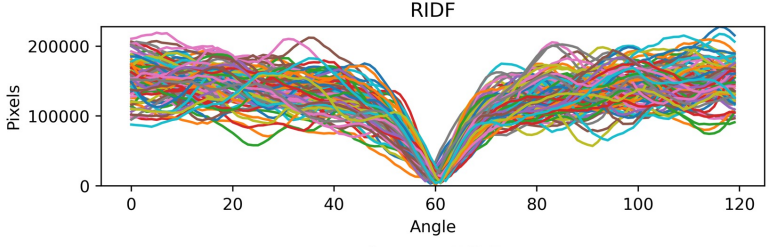
Navigation stats: RMSD error: 33.03; RMSD/dist: 0.083; TD: 105424; p90: 22; p50: 10; complete: 0

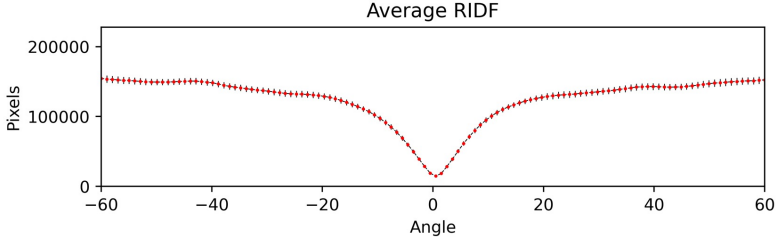
100%







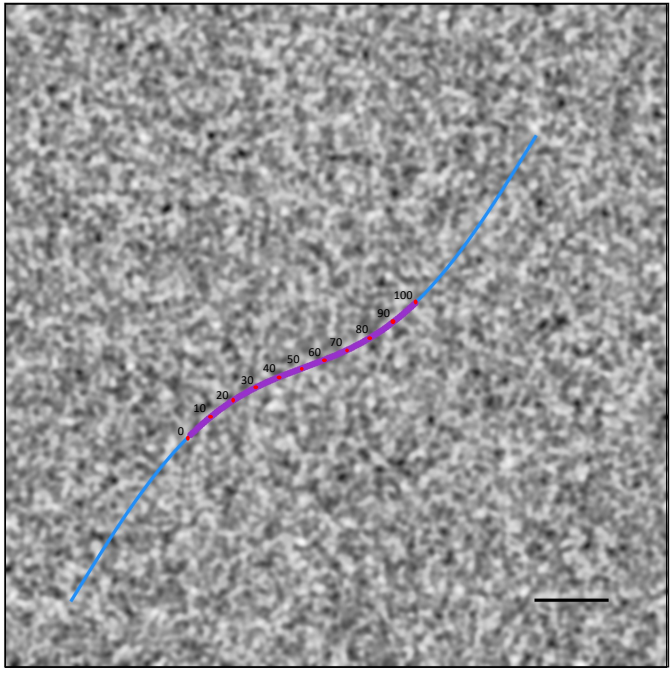


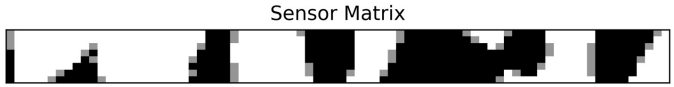


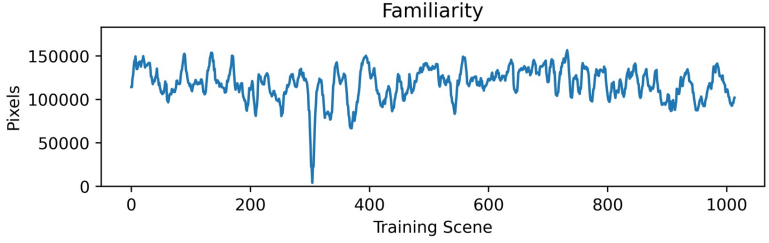
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

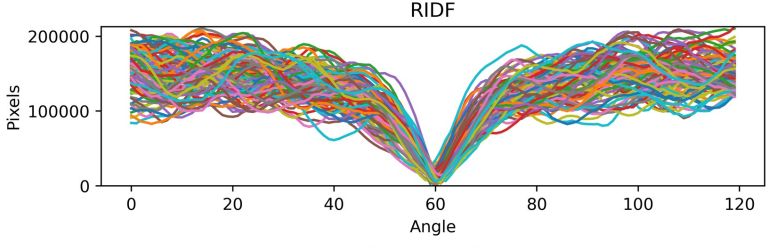
Navigation stats: RMSD error: 53.01; RMSD/dist: 0.133; TD: 100573; p90: 24; p50: 12; complete: 0

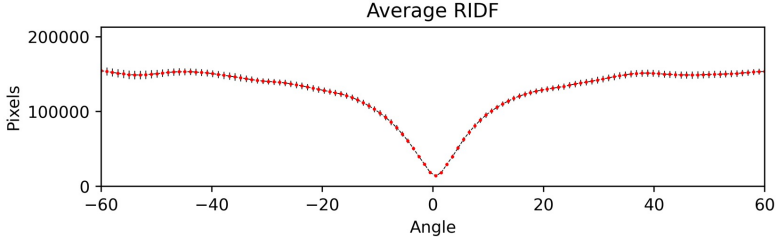
100%







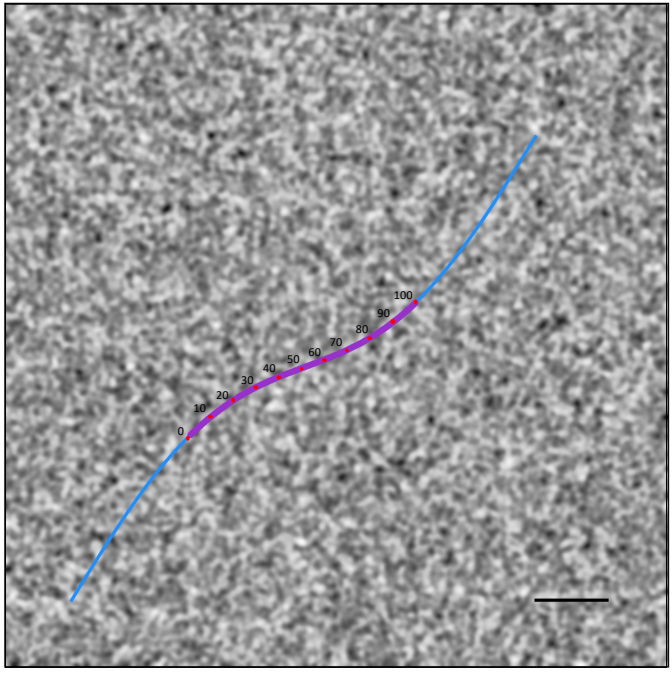


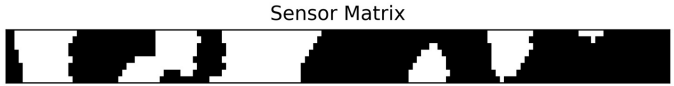


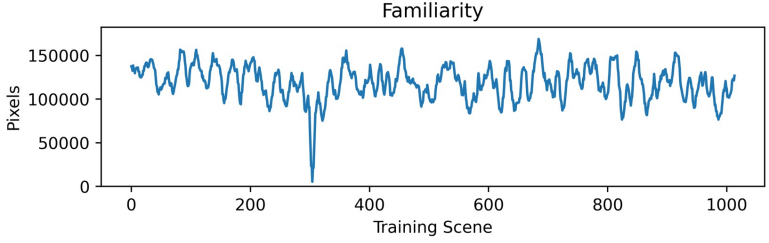
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

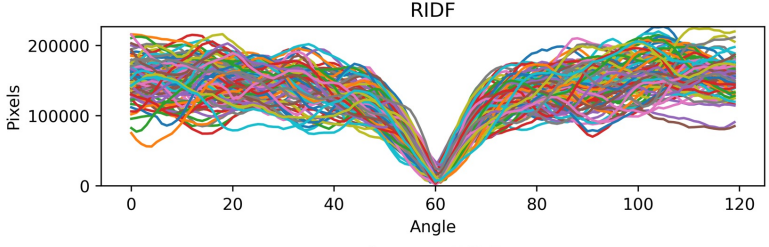
Navigation stats: RMSD error: 52.07; RMSD/dist: 0.130; TD: 102538; p90: 24; p50: 10; complete: 0

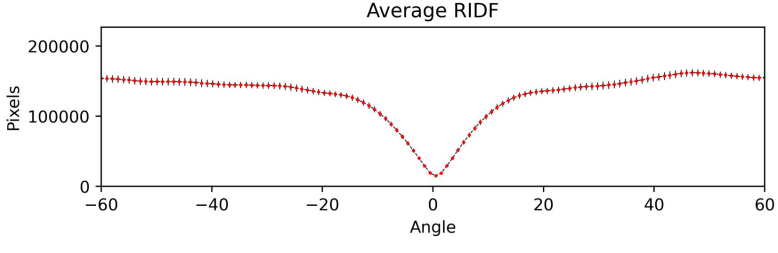
100%





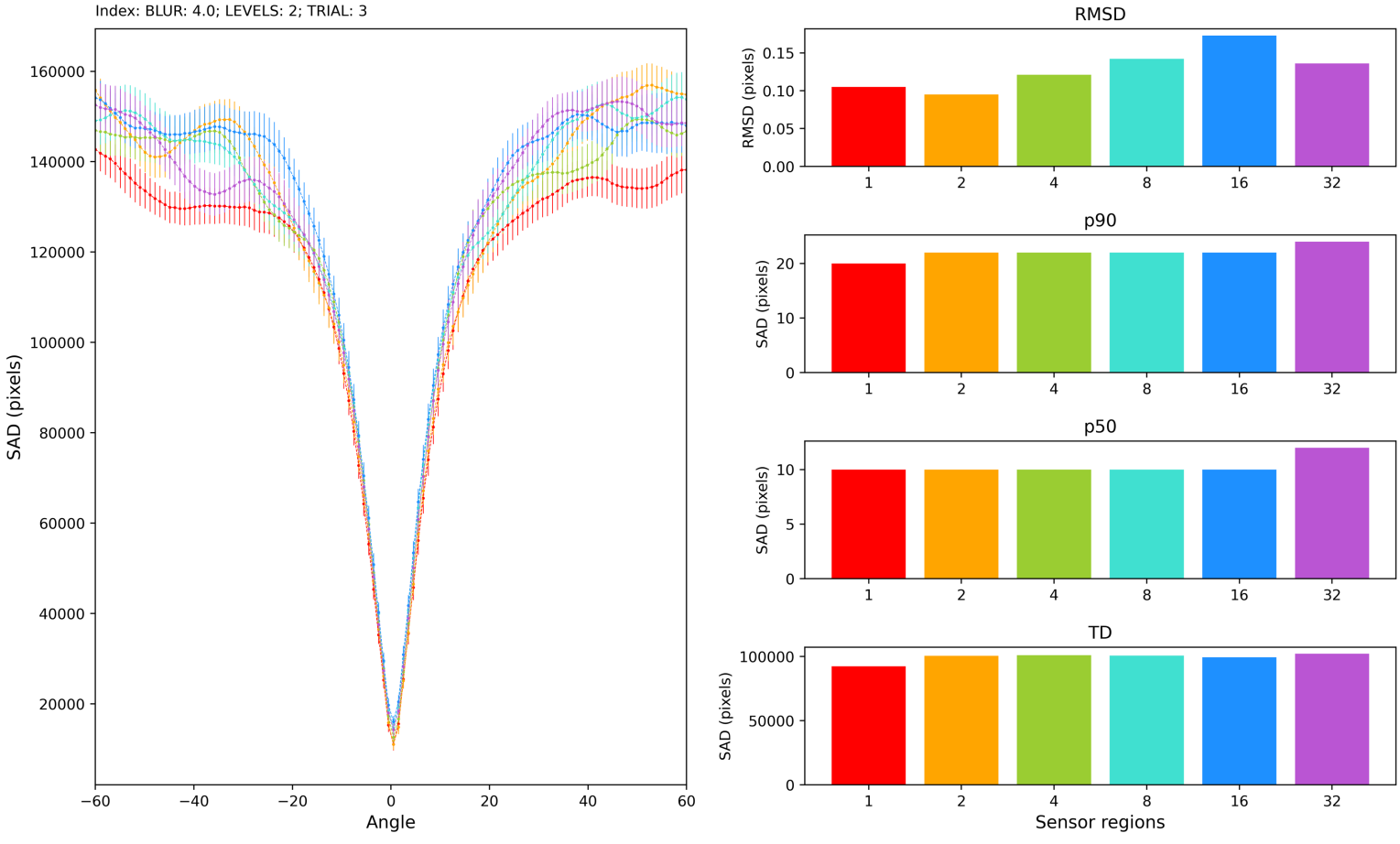




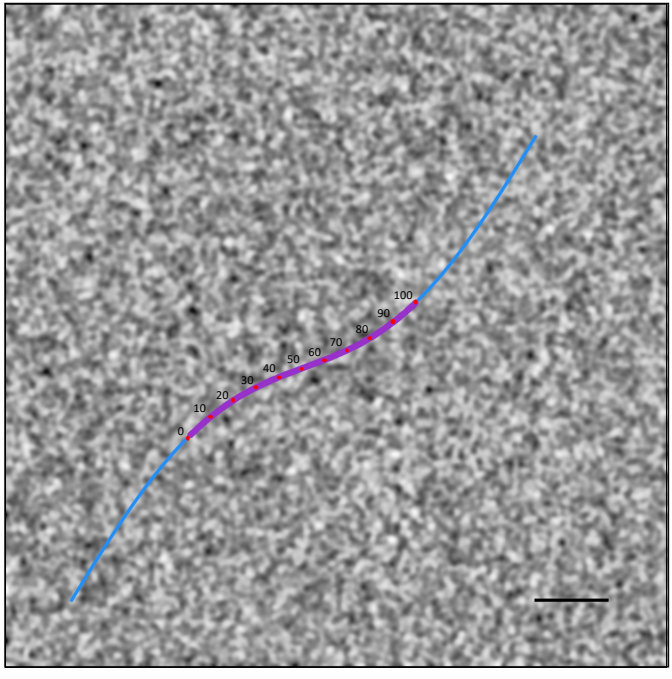


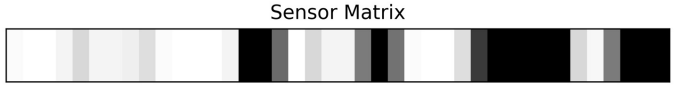
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

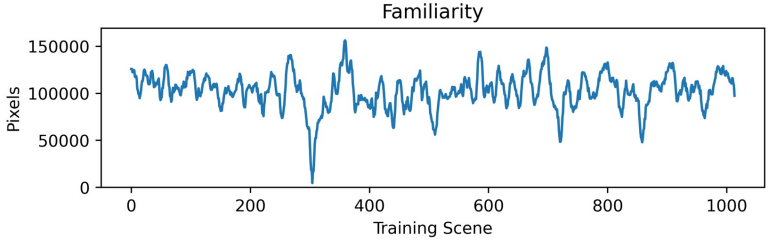
Navigation stats: RMSD error: 59.36; RMSD/dist: 0.148; TD: 101647; p90: 20; p50: 10; complete: 0

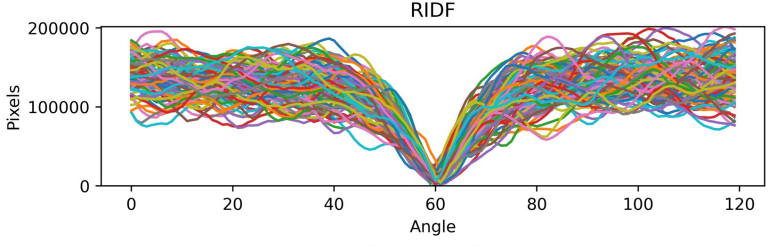

Index: BLUR: 4.0; LEVELS: 2; TRIAL: 3
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

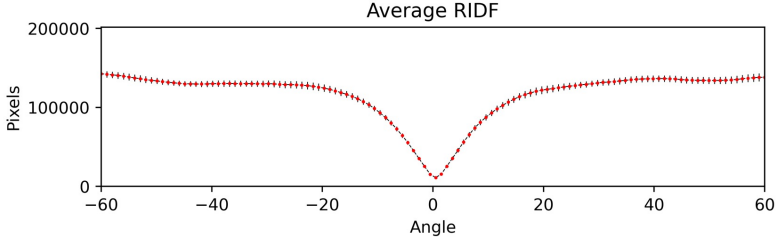
100%







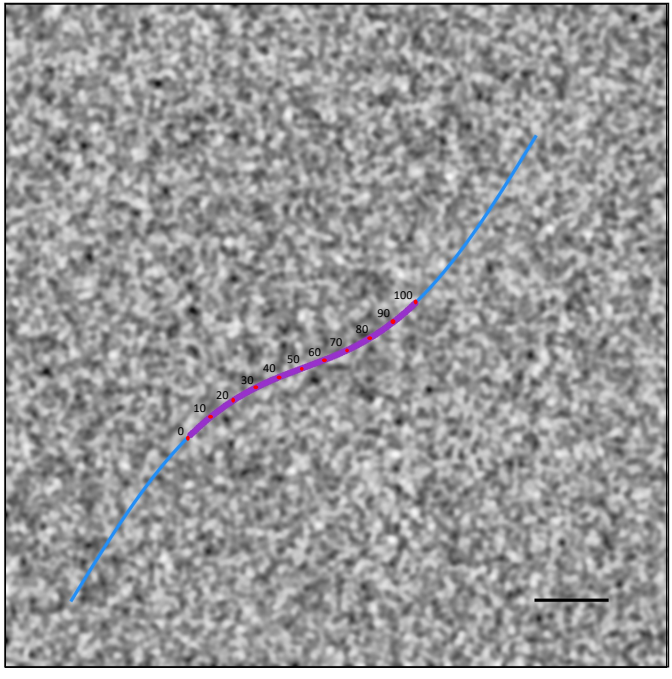


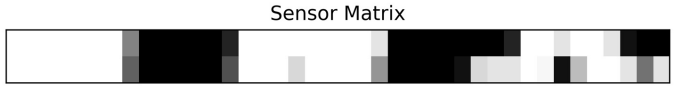


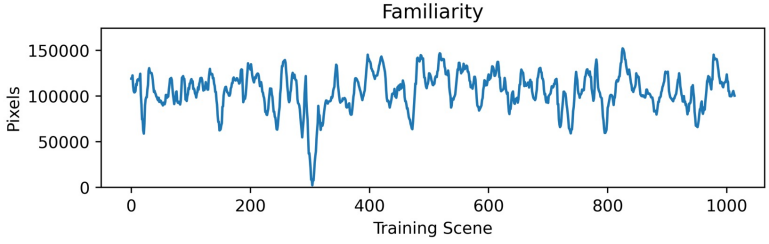
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

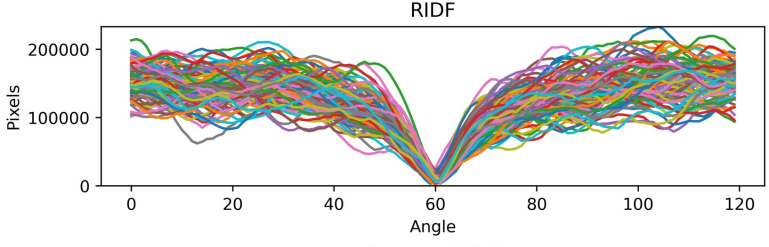
Navigation stats: RMSD error: 41.87; RMSD/dist: 0.105; TD: 92353; p90: 20; p50: 10; complete: 0

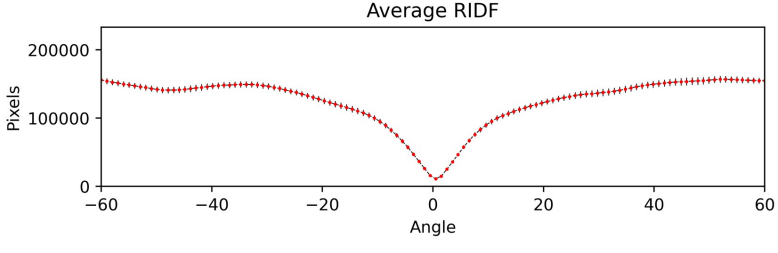
100%







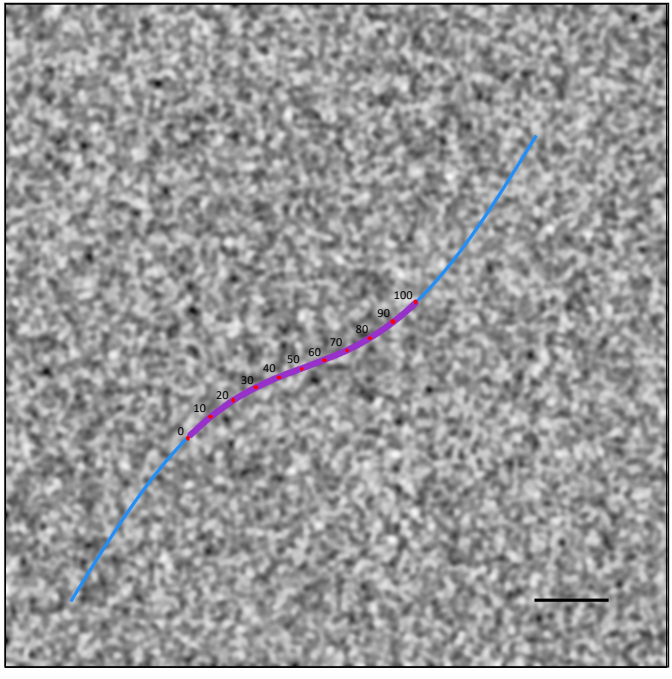


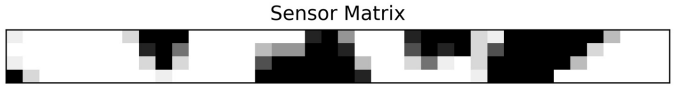


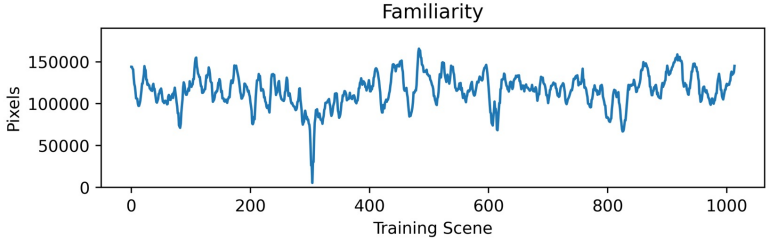
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

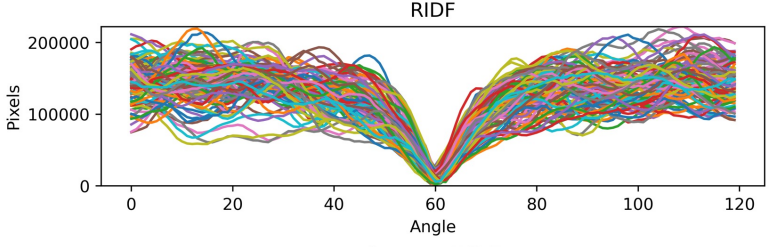
Navigation stats: RMSD error: 38.00; RMSD/dist: 0.095; TD: 100502; p90: 22; p50: 10; complete: 0

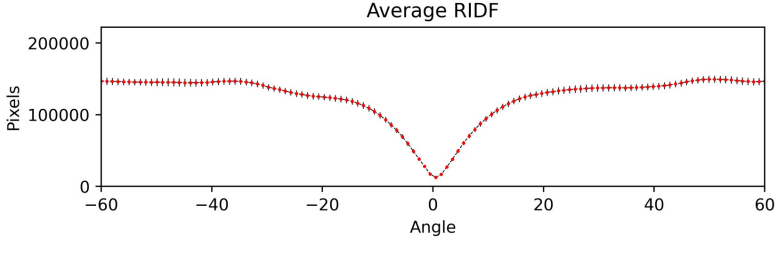
100%







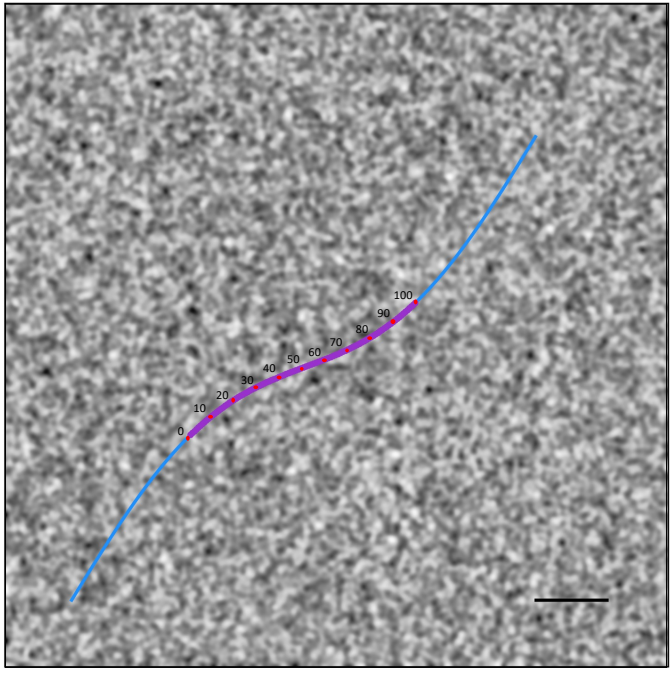


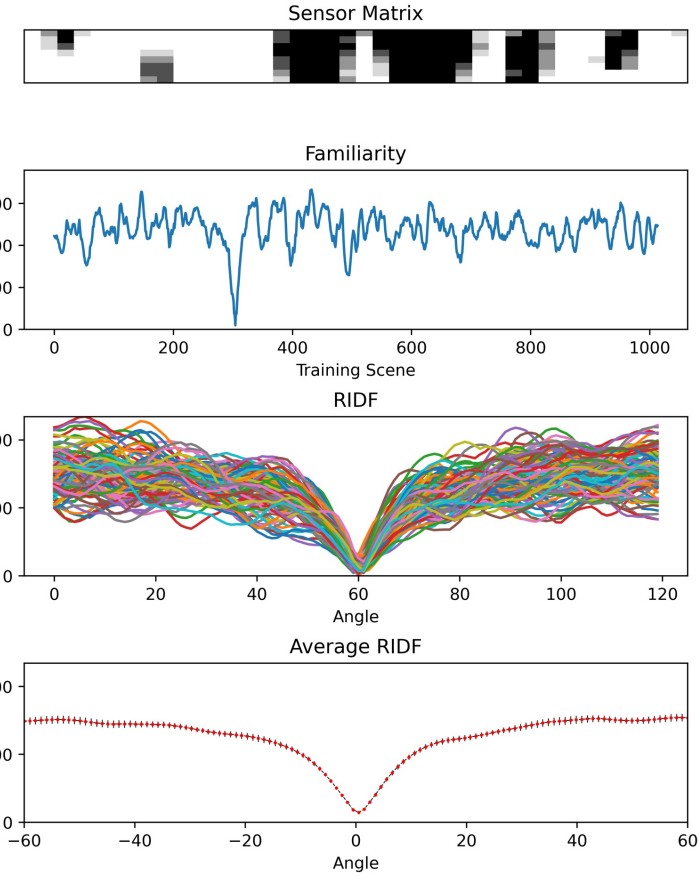


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 48.40; RMSD/dist: 0.121; TD: 101025; p90: 22; p50: 10; complete: 0

100%

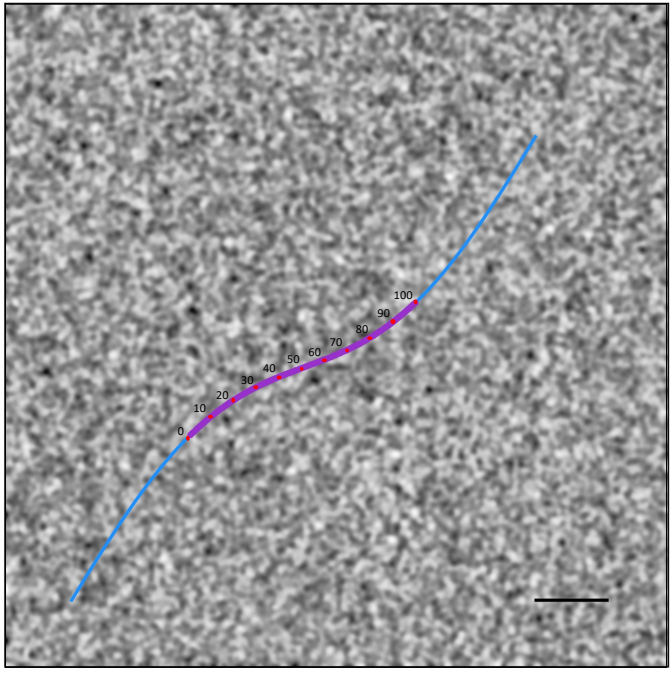


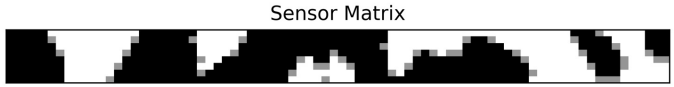


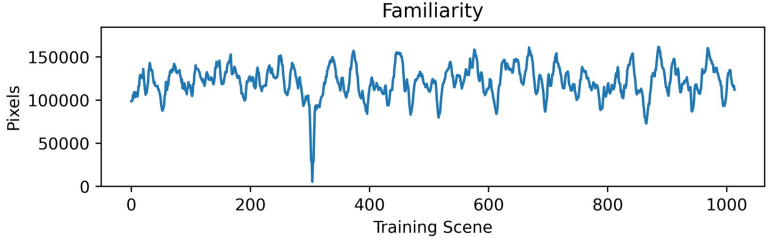
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

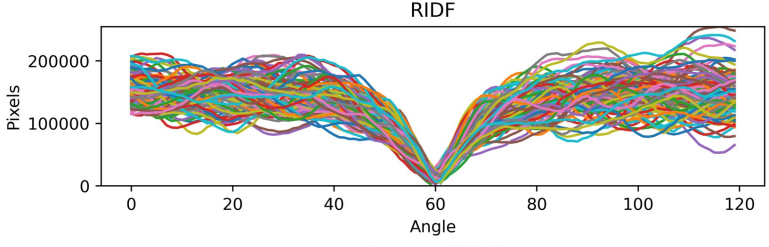
Navigation stats: RMSD error: 57.00; RMSD/dist: 0.142; TD: 100816; p90: 22; p50: 10; complete: 0

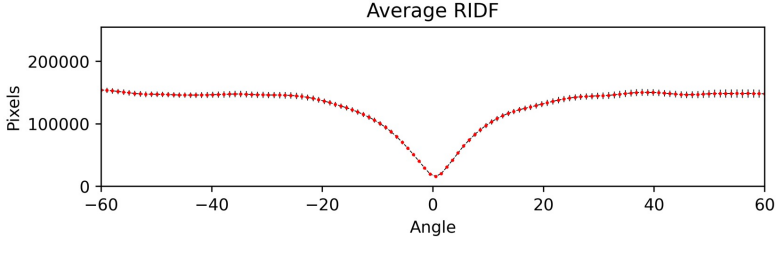
100%







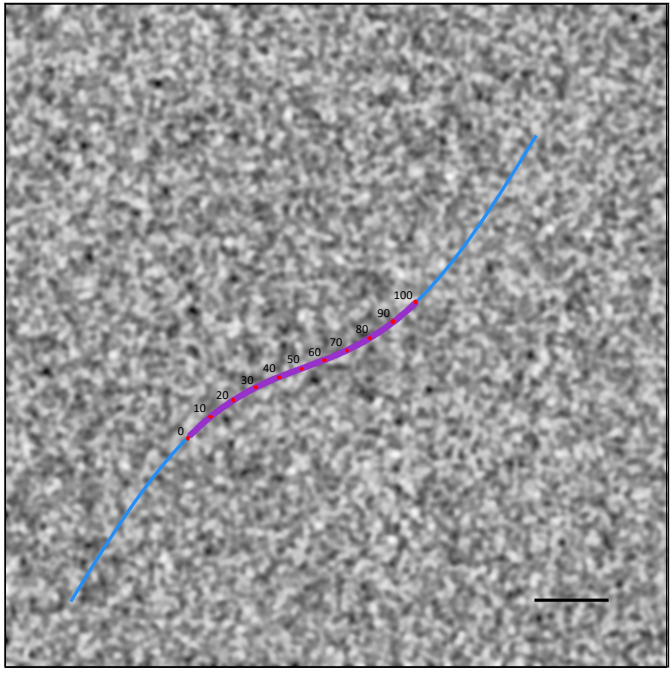


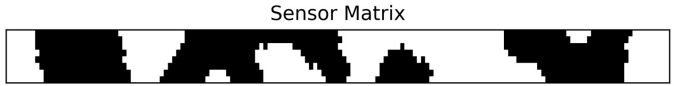


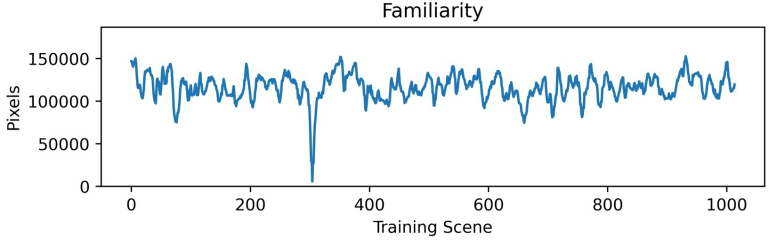
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

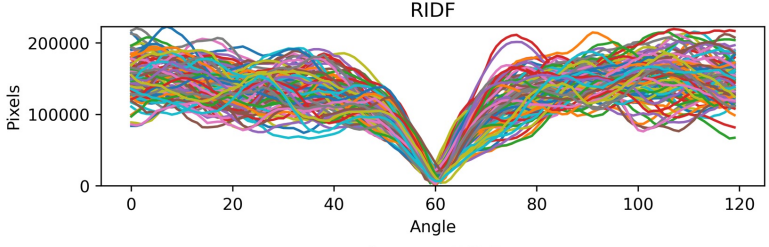
Navigation stats: RMSD error: 69.22; RMSD/dist: 0.173; TD: 99401; p90: 22; p50: 10; complete: 0

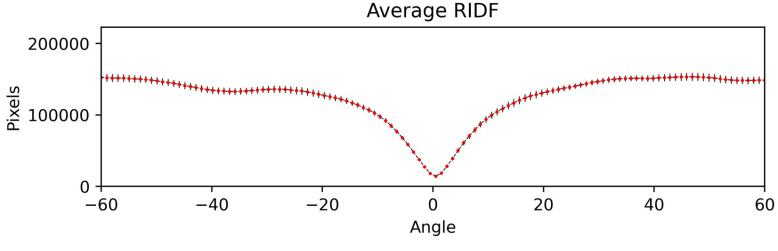
100%





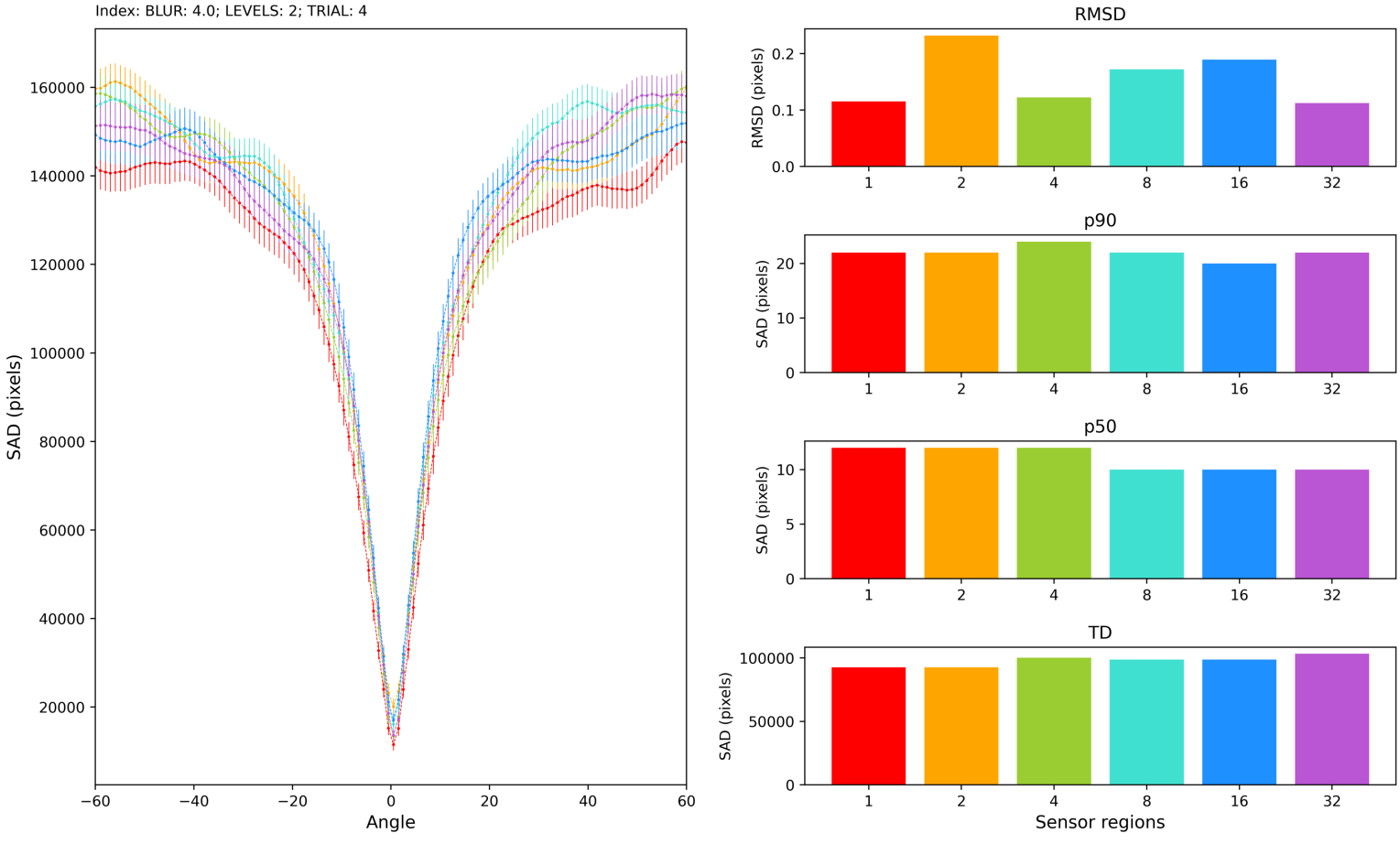




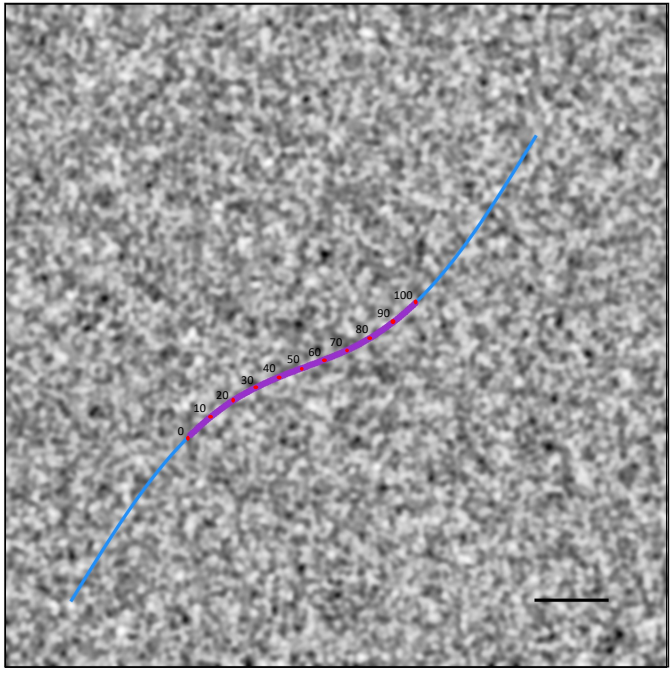


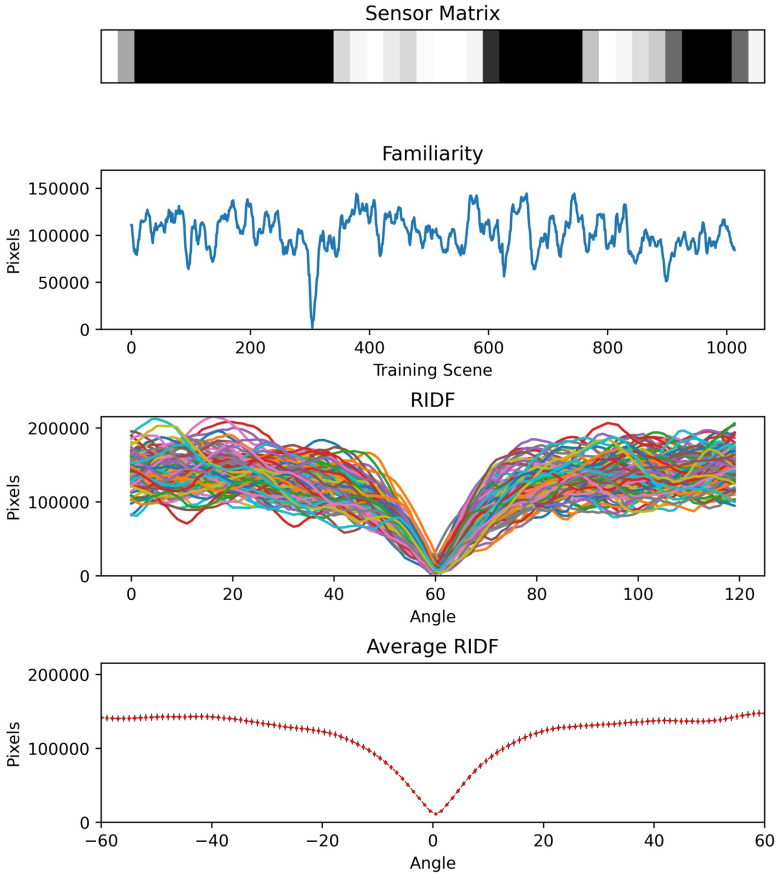
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 54.41; RMSD/dist: 0.136; TD: 102126; p90: 24; p50: 12; complete: 0


Index: BLUR: 4.0; LEVELS: 2; TRIAL: 4
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

100%

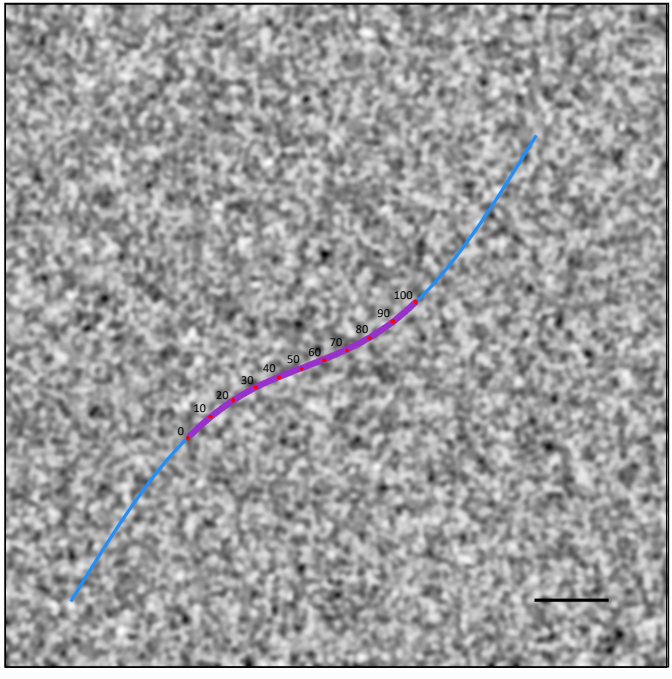


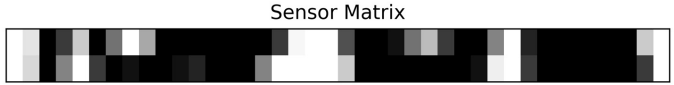


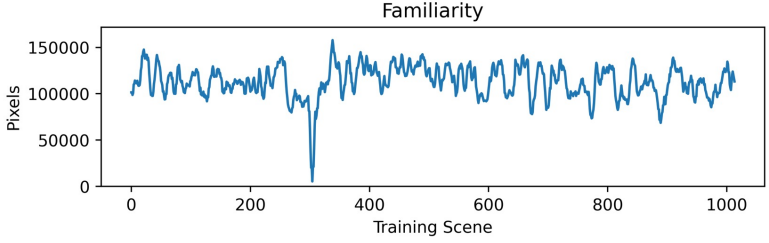
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

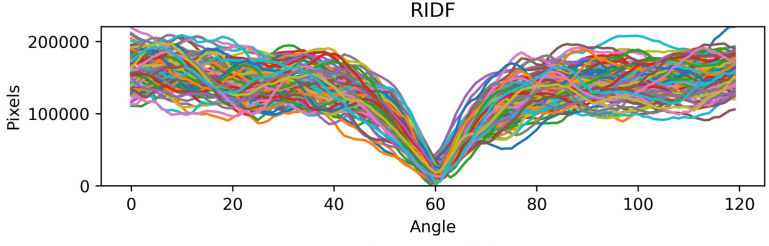
Navigation stats: RMSD error: 46.08; RMSD/dist: 0.115; TD: 92622; p90: 22; p50: 12; complete: 0

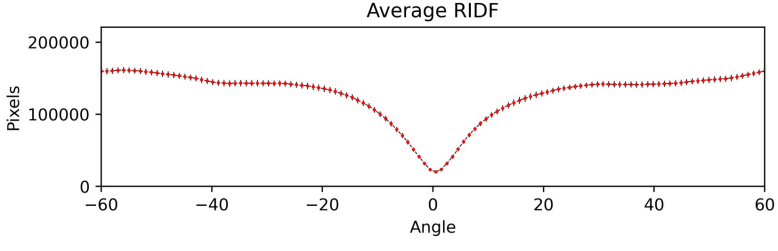
100%







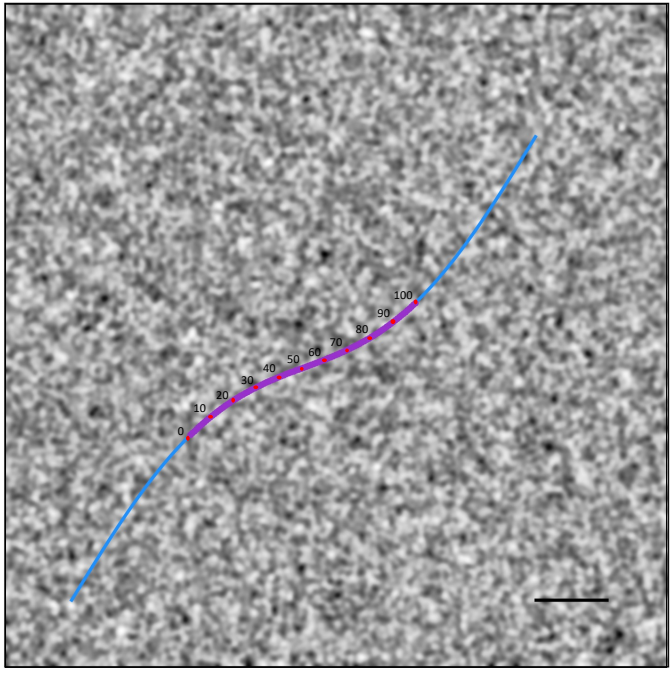


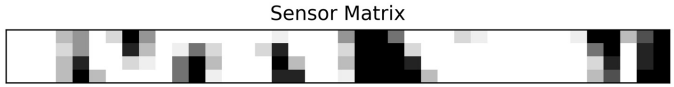


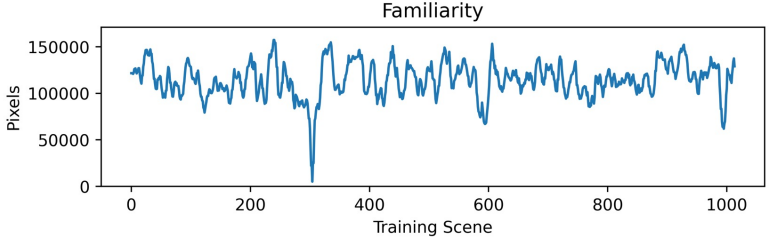
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

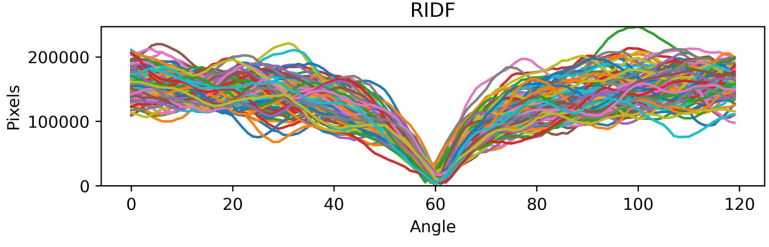
Navigation stats: RMSD error: 92.85; RMSD/dist: 0.232; TD: 92645; p90: 22; p50: 12; complete: 0

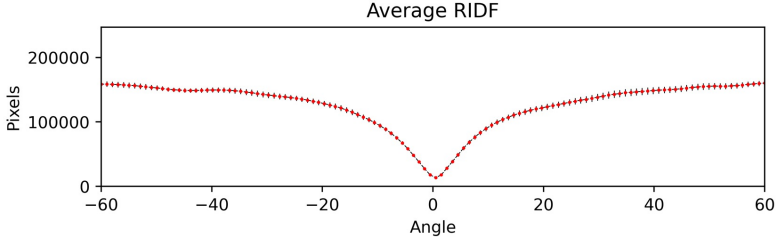
100%







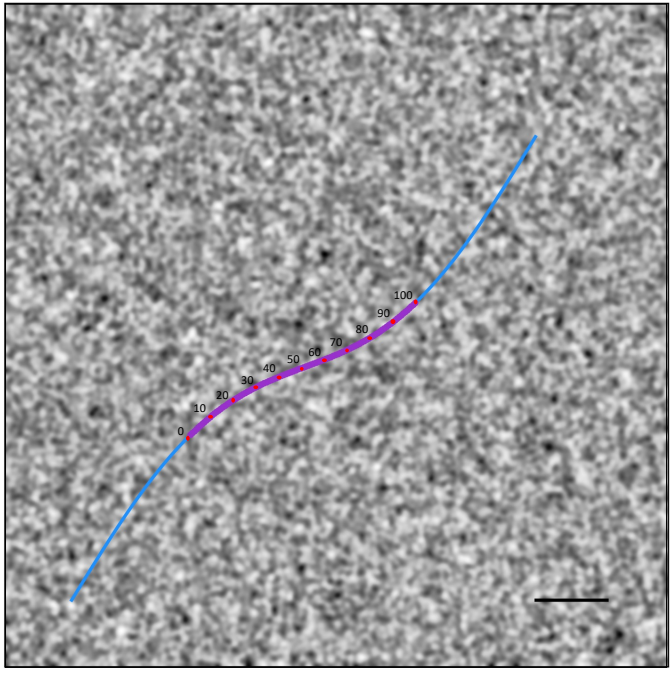


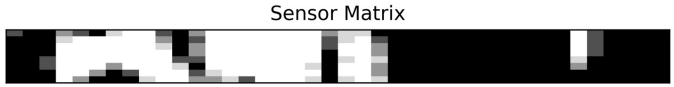


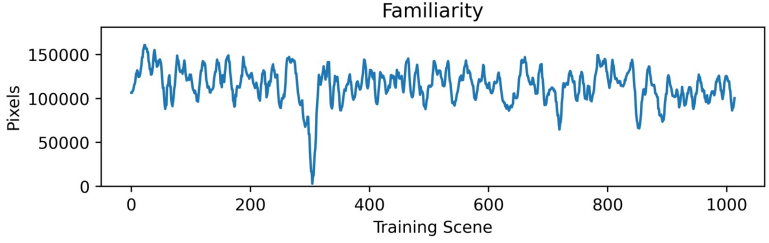
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

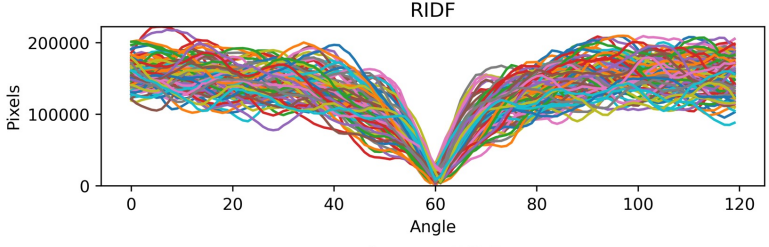
Navigation stats: RMSD error: 48.95; RMSD/dist: 0.122; TD: 100297; p90: 24; p50: 12; complete: 0

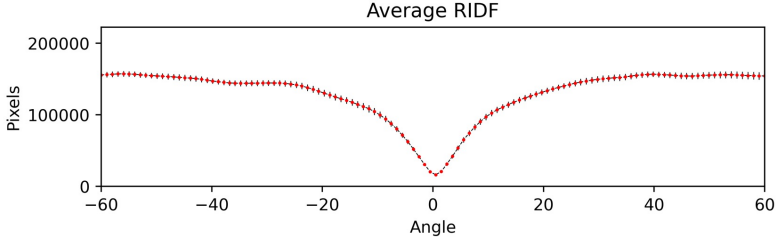
100%







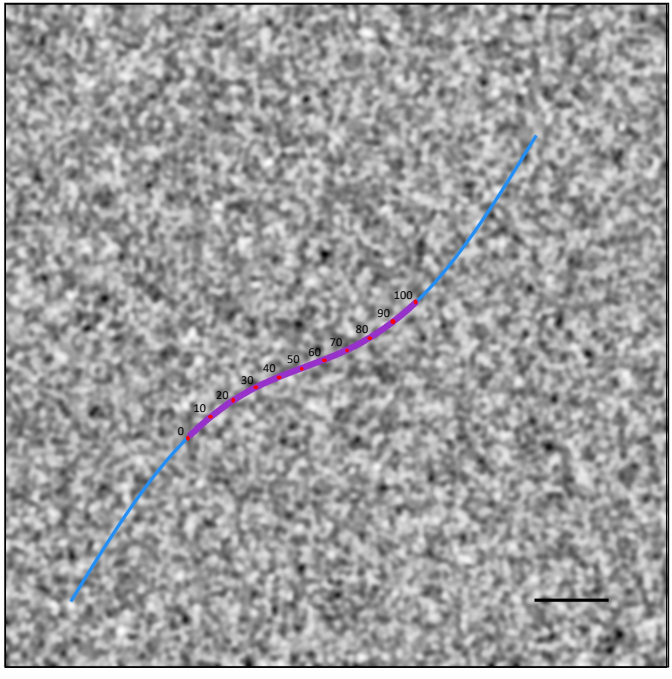


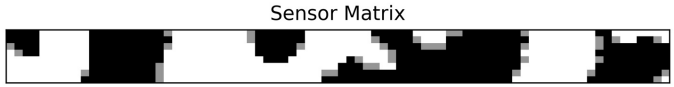


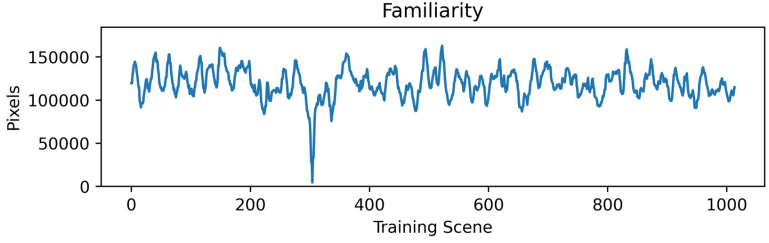
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

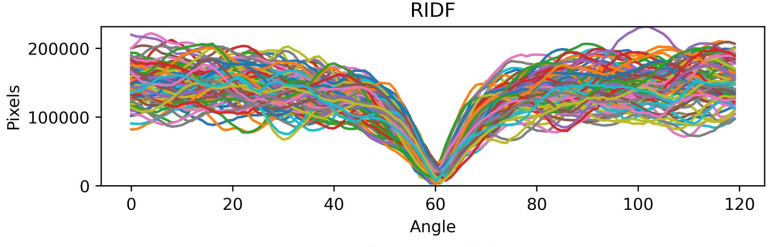
Navigation stats: RMSD error: 68.95; RMSD/dist: 0.172; TD: 98782; p90: 22; p50: 10; complete: 0

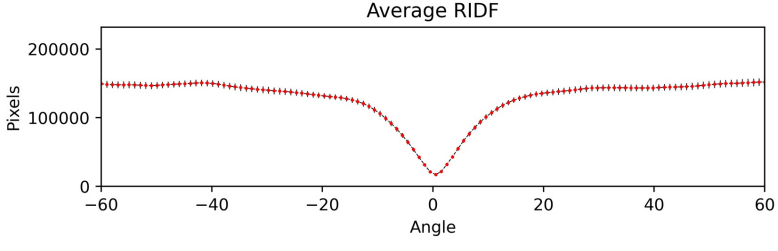
100%







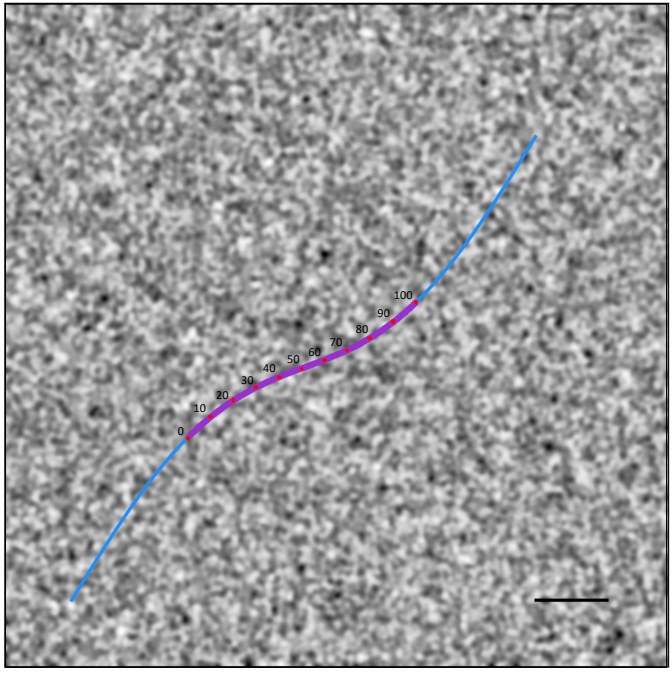


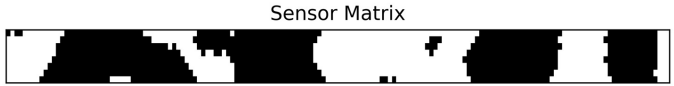


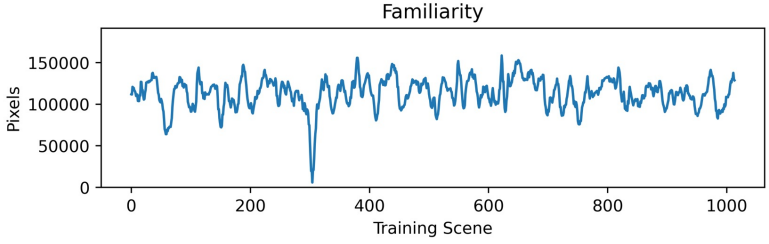
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

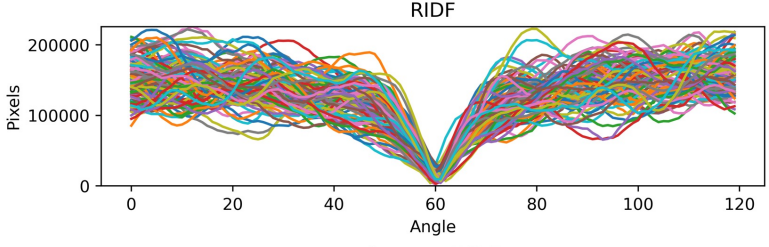
Navigation stats: RMSD error: 75.56; RMSD/dist: 0.189; TD: 98671; p90: 20; p50: 10; complete: 0

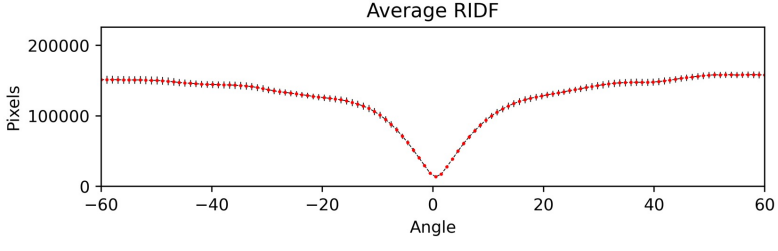
100%





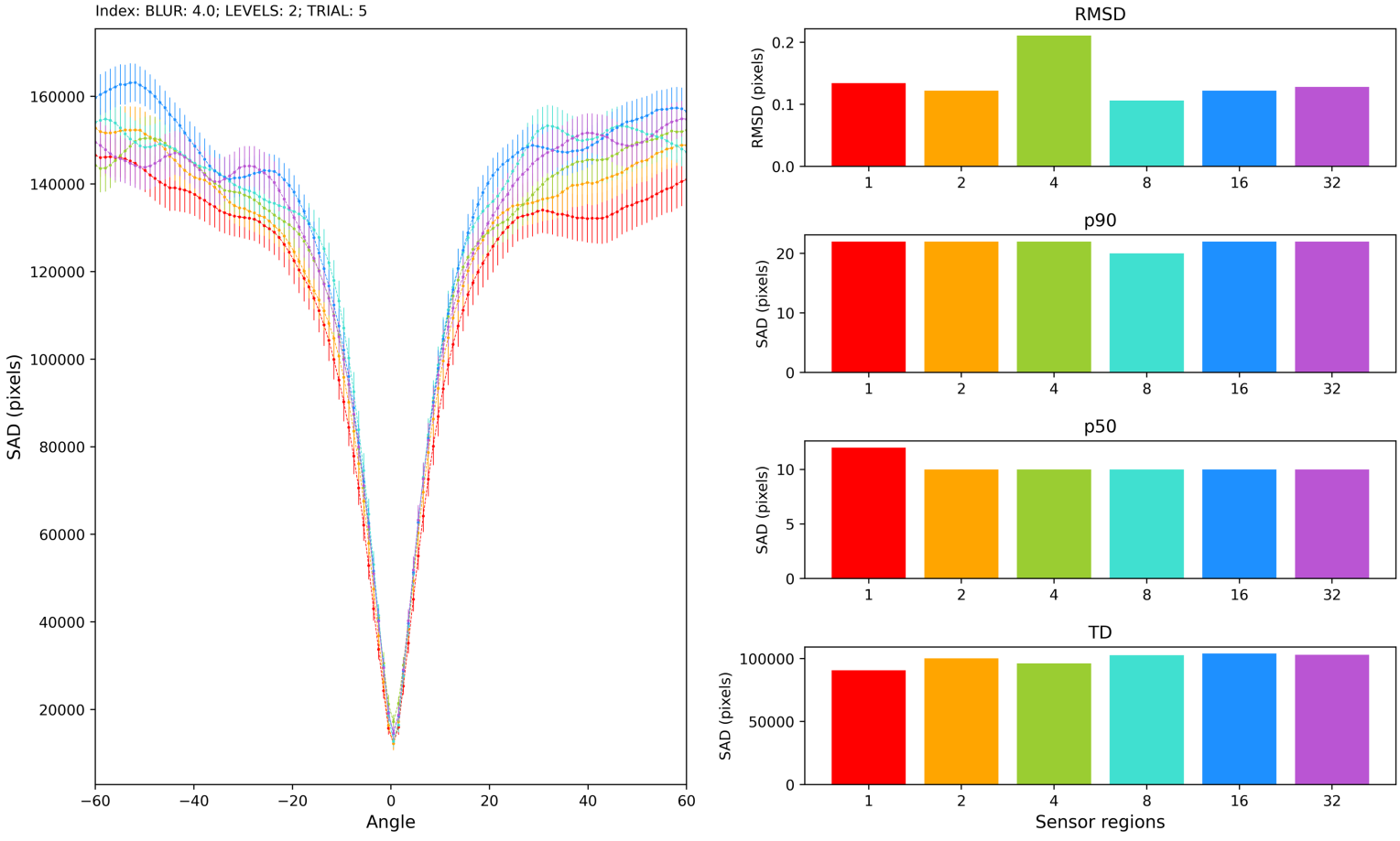




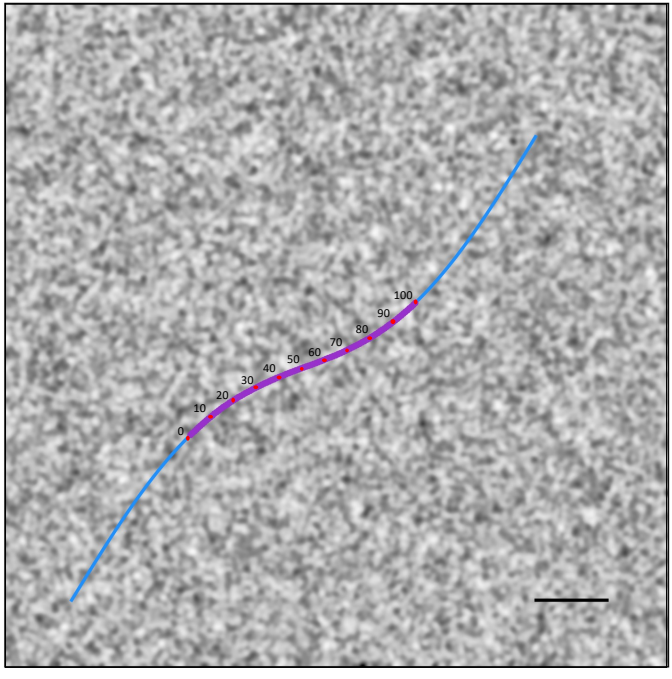


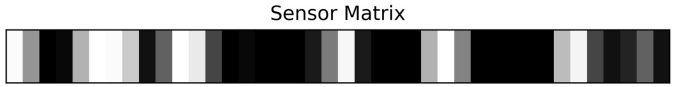
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

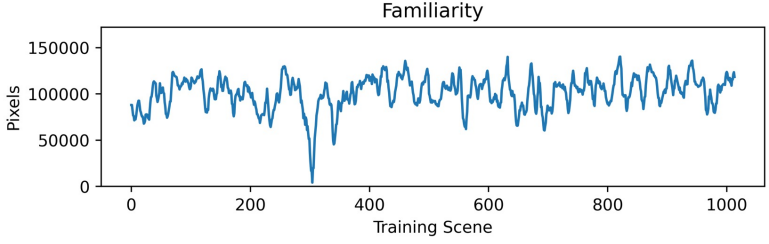
Navigation stats: RMSD error: 44.94; RMSD/dist: 0.112; TD: 103297; p90: 22; p50: 10; complete: 0

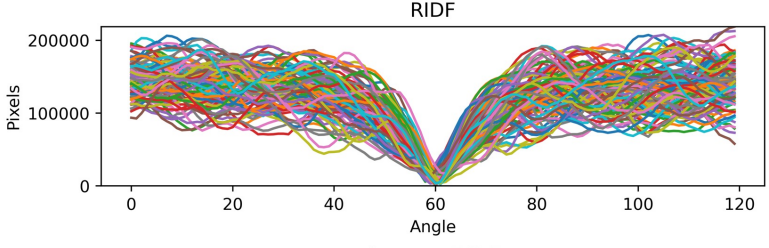

Index: BLUR: 4.0; LEVELS: 2; TRIAL: 5
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
1
2
4
8
16
32
Sensor regions

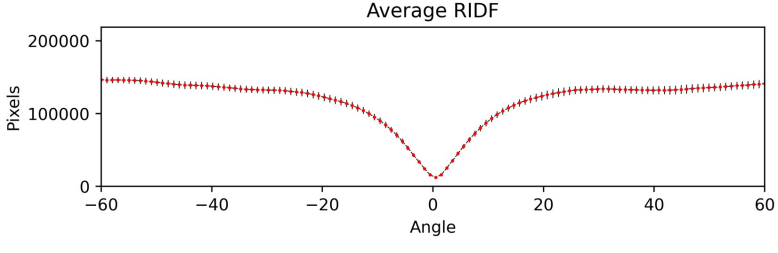
100%







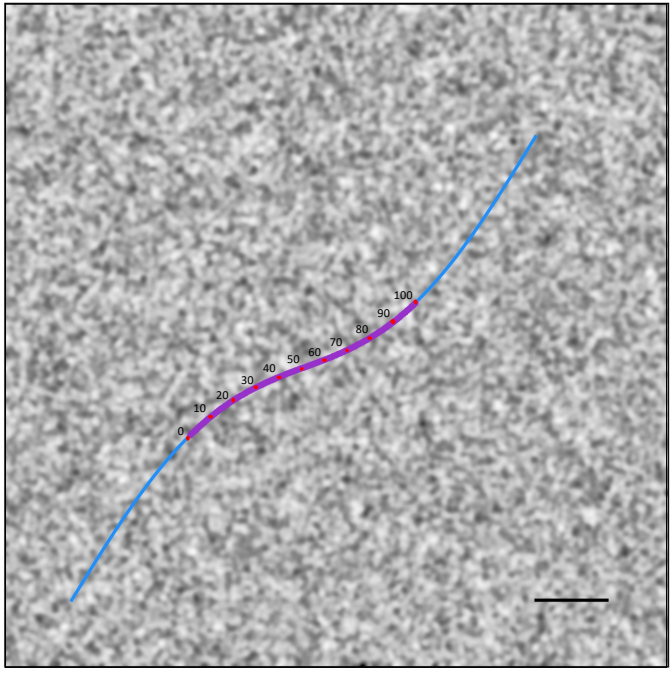


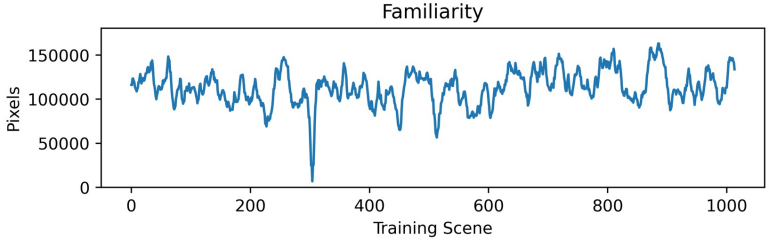


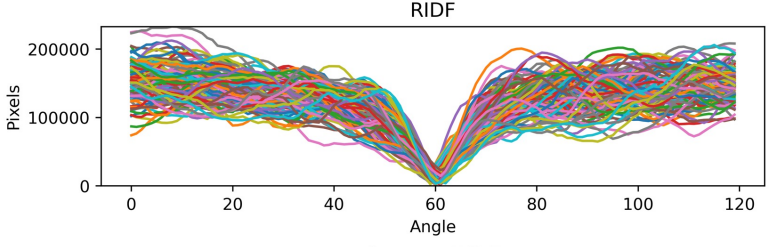
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

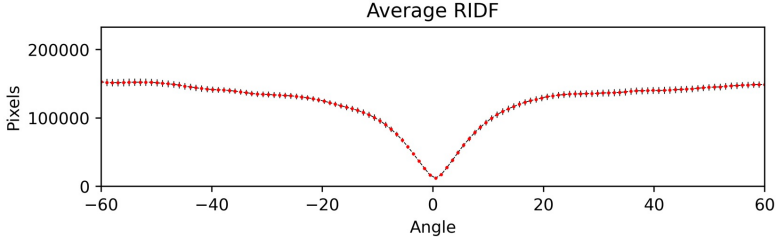
Navigation stats: RMSD error: 53.54; RMSD/dist: 0.134; TD: 90565; p90: 22; p50: 12; complete: 0

100%





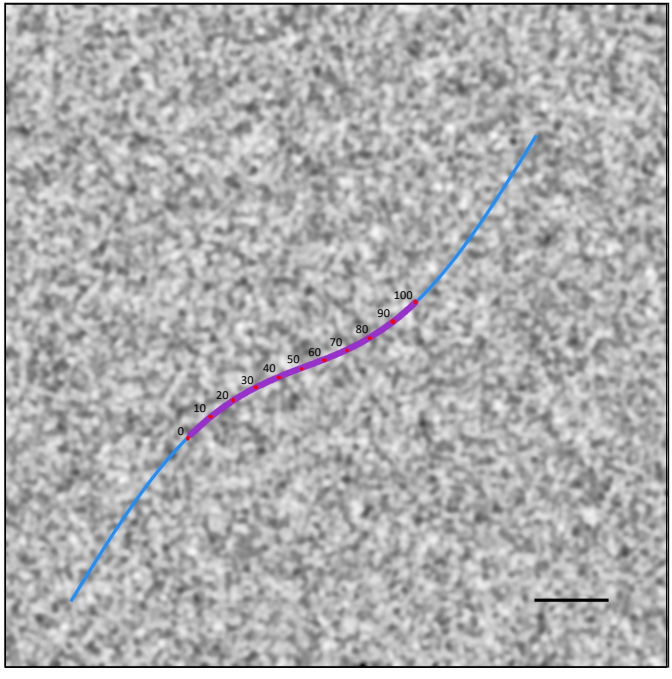


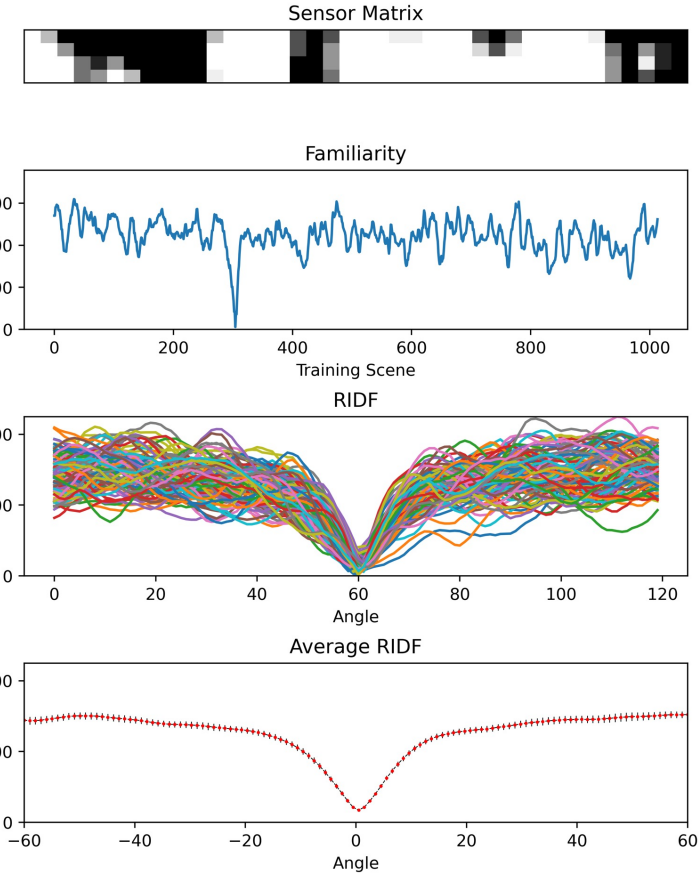


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 48.74; RMSD/dist: 0.122; TD: 100036; p90: 22; p50: 10; complete: 0

100%

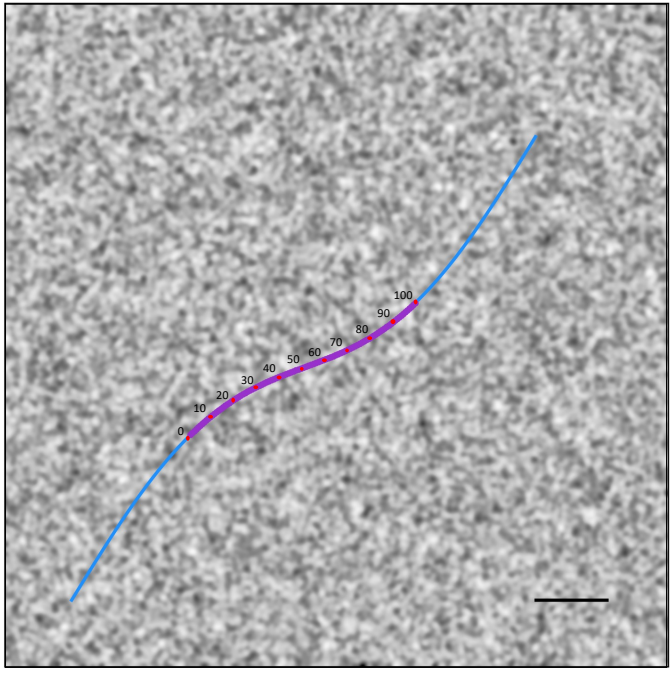


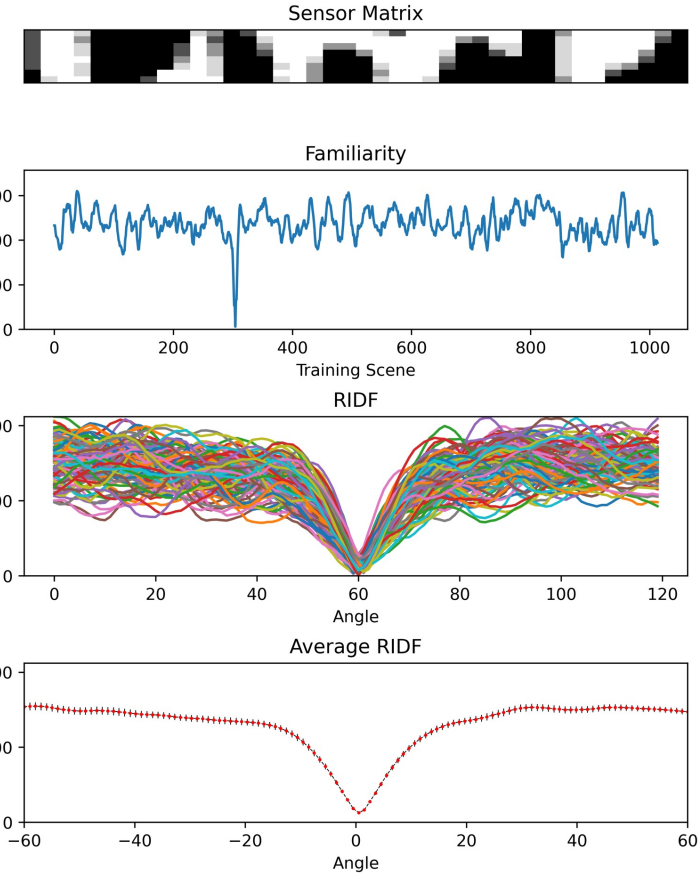


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 84.47; RMSD/dist: 0.211; TD: 96121; p90: 22; p50: 10; complete: 0

100%

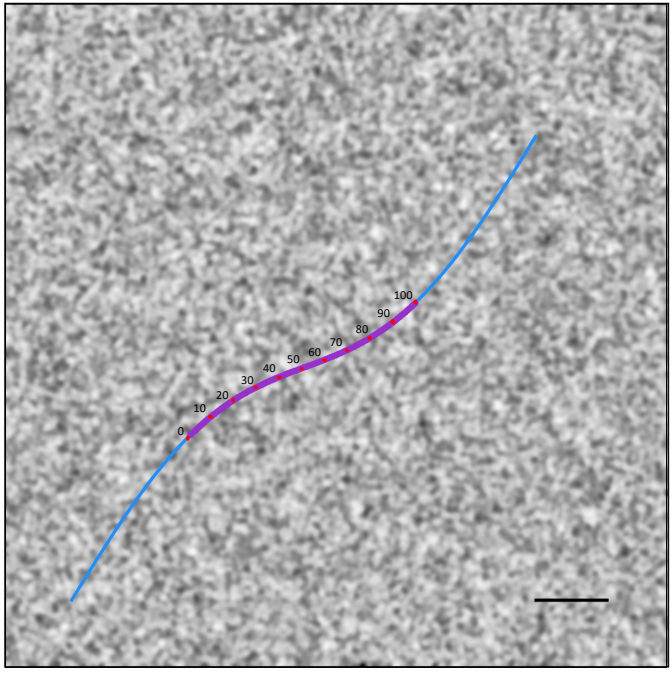


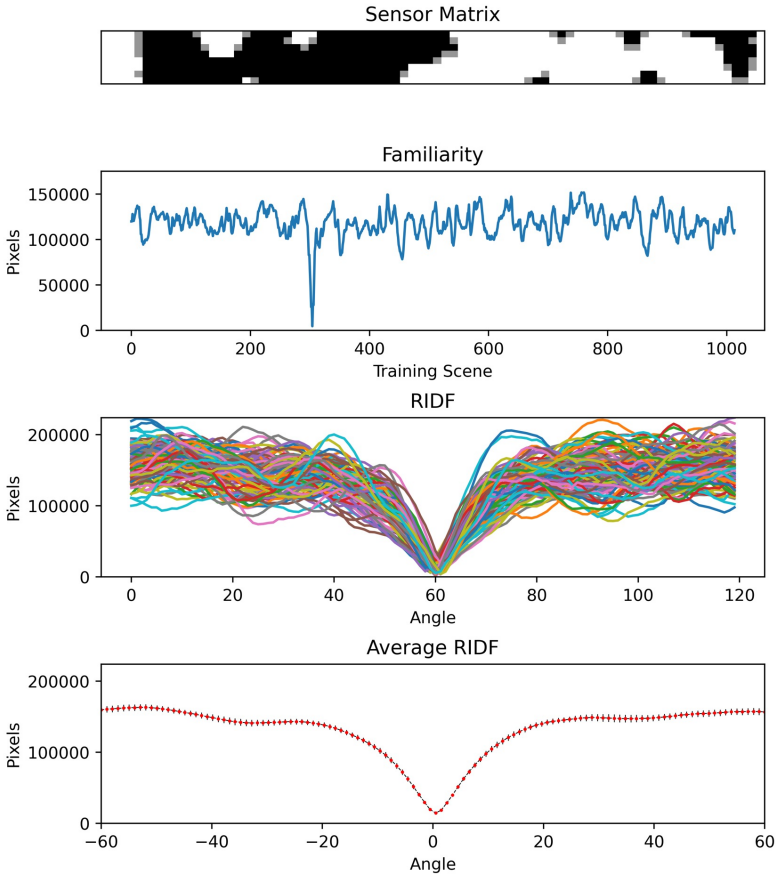


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 42.49; RMSD/dist: 0.106; TD: 102603; p90: 20; p50: 10; complete: 0

100%

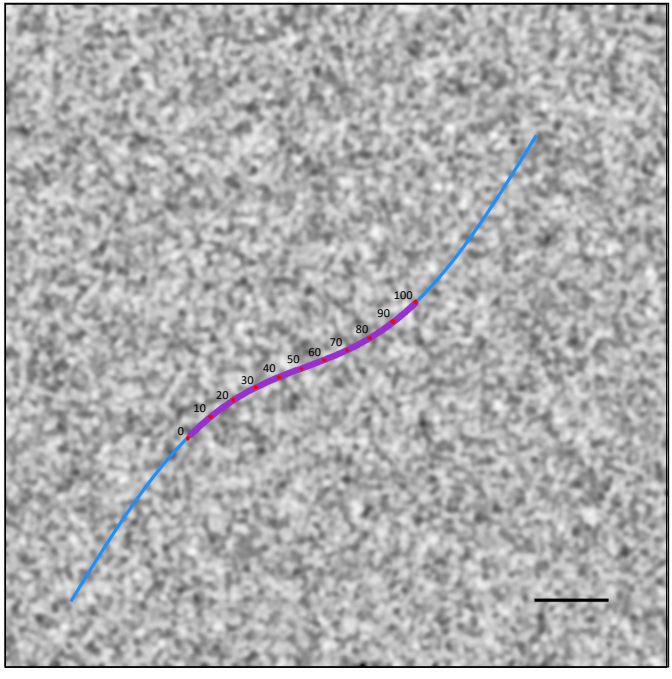


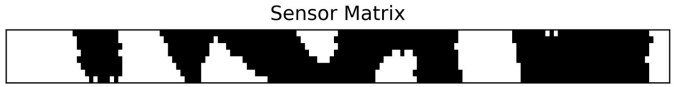


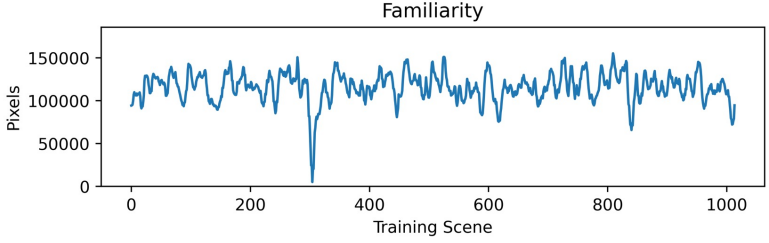
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

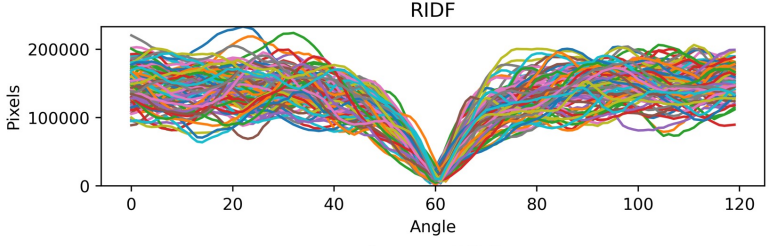
Navigation stats: RMSD error: 48.85; RMSD/dist: 0.122; TD: 103856; p90: 22; p50: 10; complete: 0

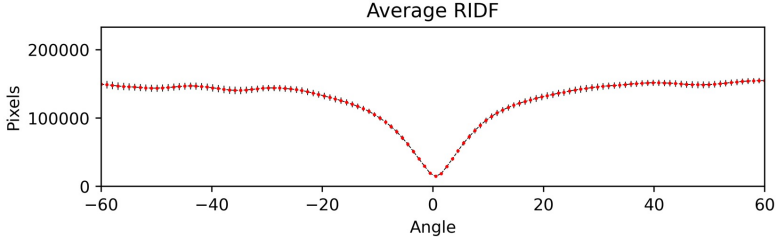
100%





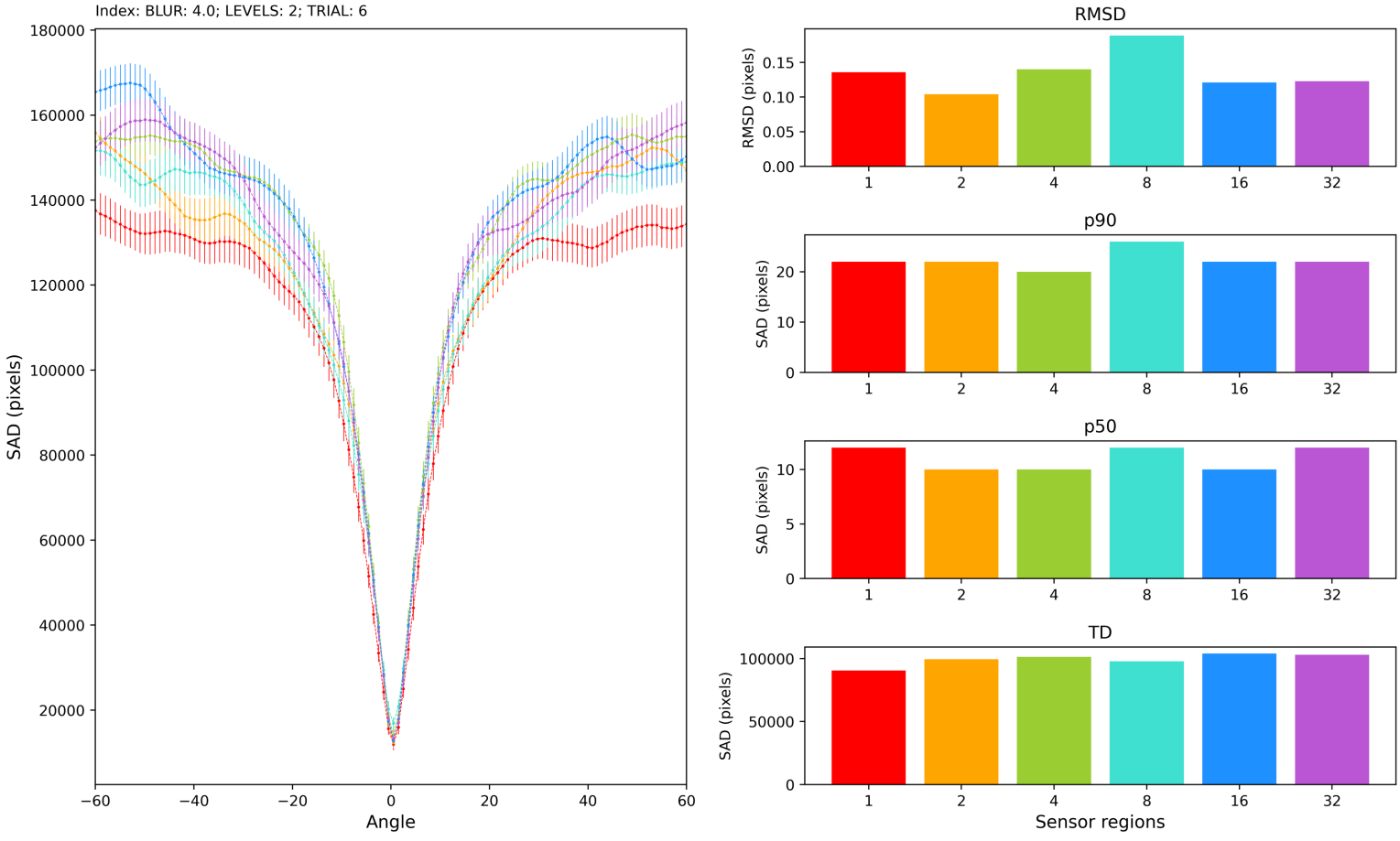




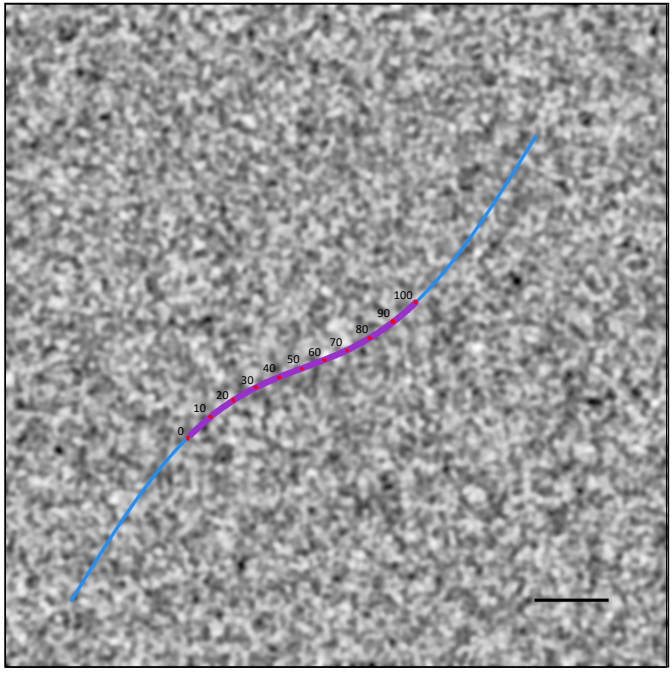


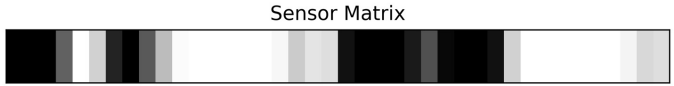
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

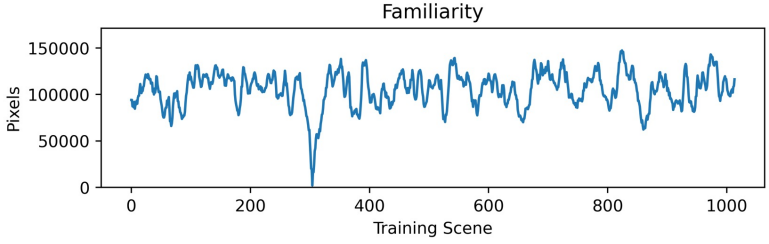
Navigation stats: RMSD error: 51.17; RMSD/dist: 0.128; TD: 102879; p90: 22; p50: 10; complete: 0

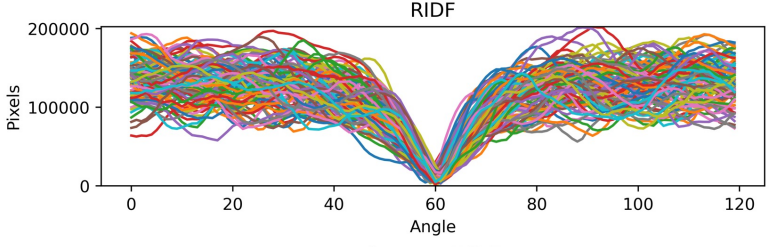

Index: BLUR: 4.0; LEVELS: 2; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

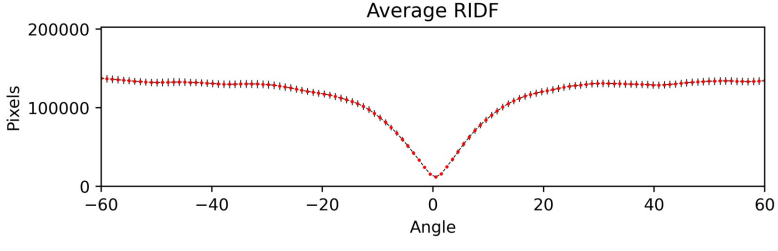
100%







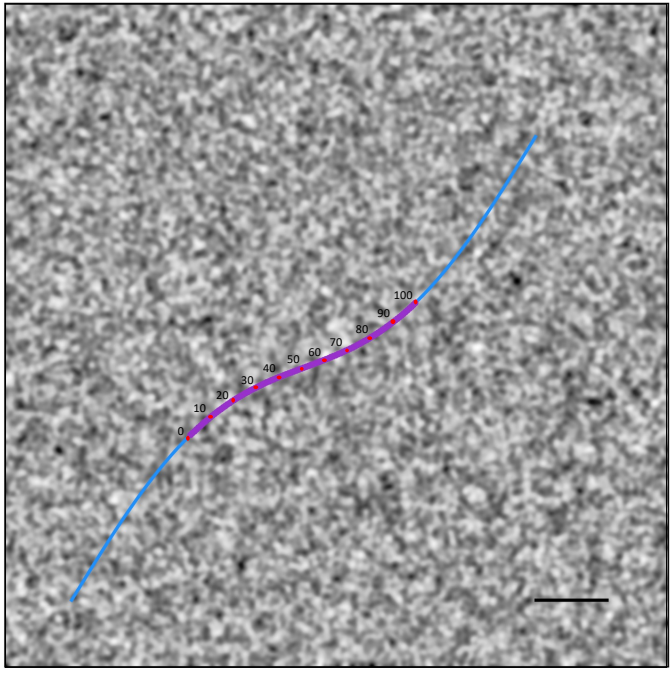


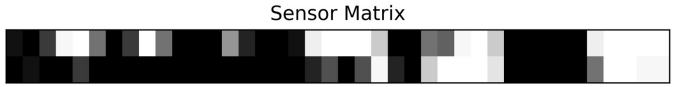


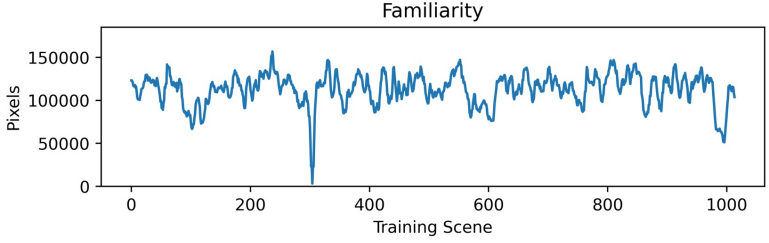
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

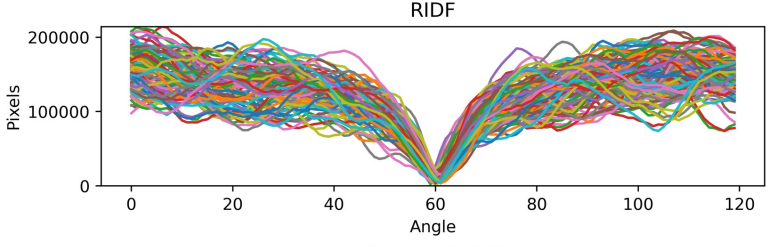
Navigation stats: RMSD error: 54.55; RMSD/dist: 0.136; TD: 90502; p90: 22; p50: 12; complete: 0

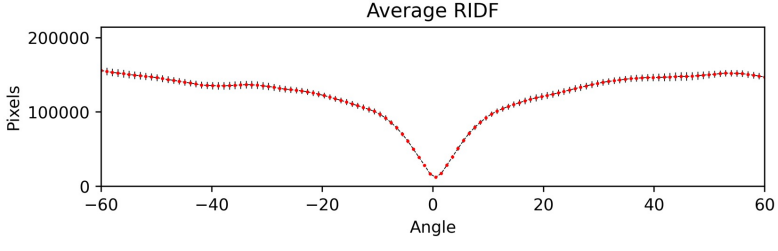
100%







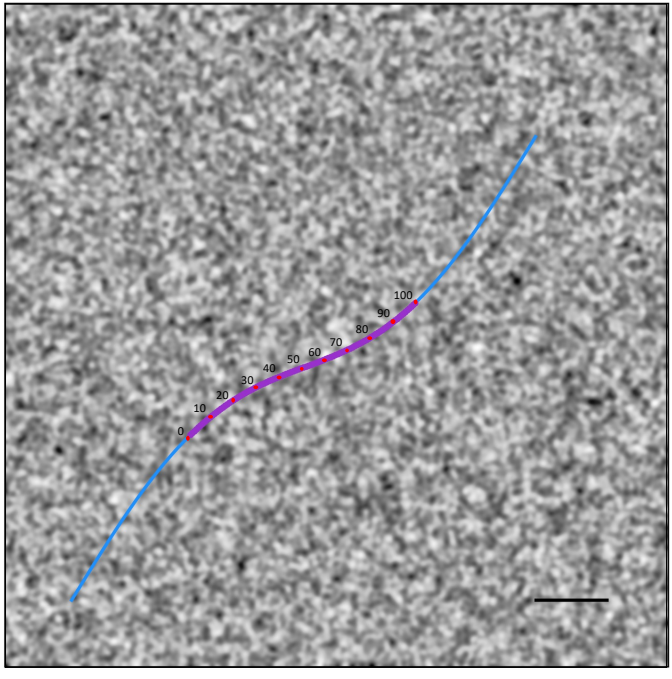


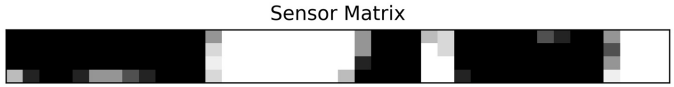


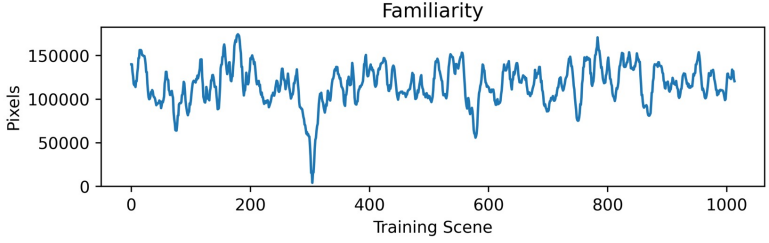
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

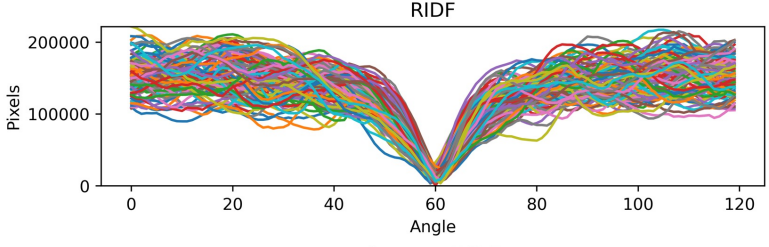
Navigation stats: RMSD error: 41.76; RMSD/dist: 0.104; TD: 99478; p90: 22; p50: 10; complete: 0

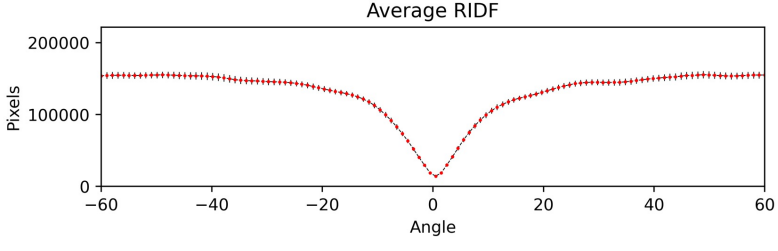
100%







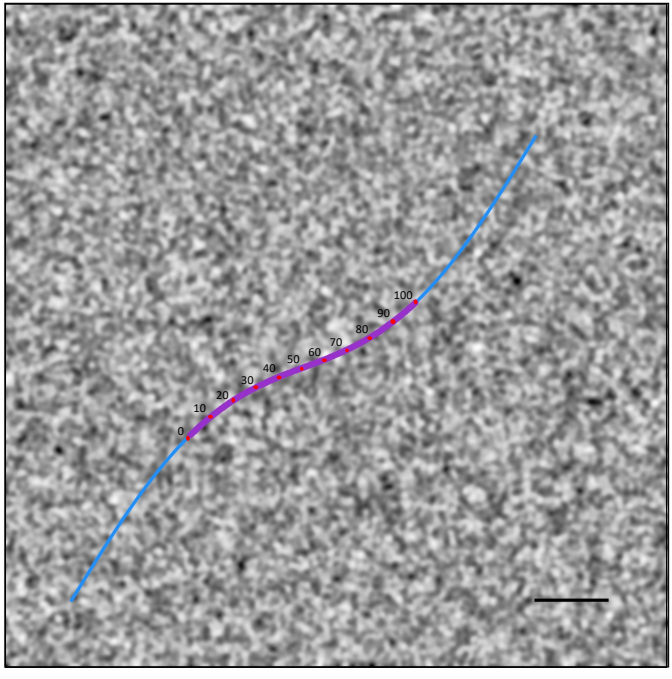


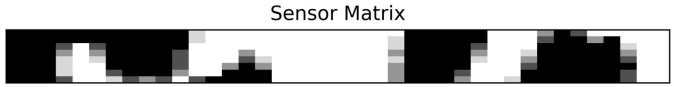


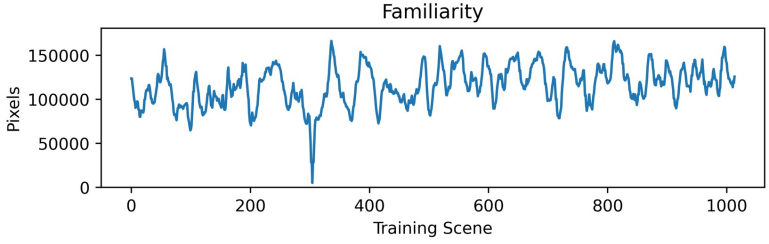
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

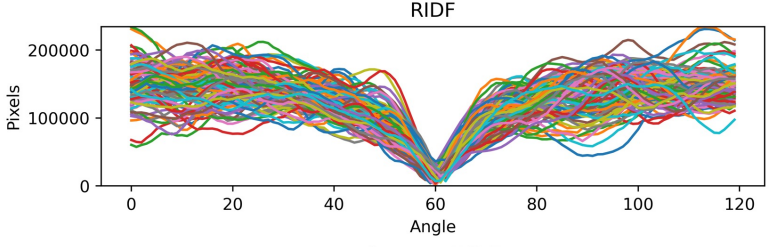
Navigation stats: RMSD error: 55.90; RMSD/dist: 0.140; TD: 101371; p90: 20; p50: 10; complete: 0

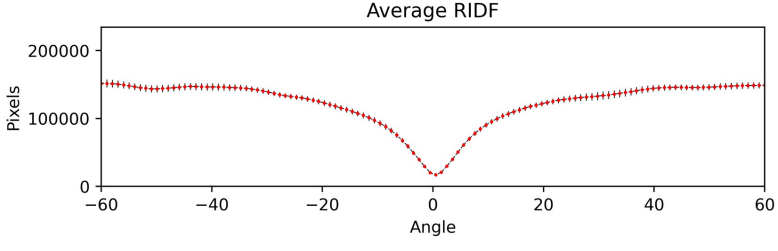
100%







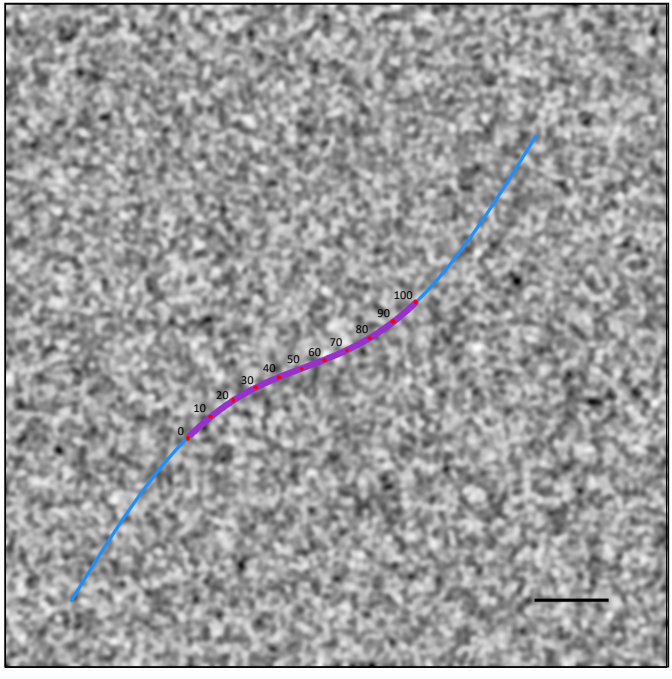


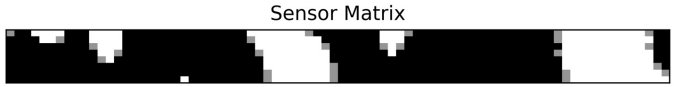


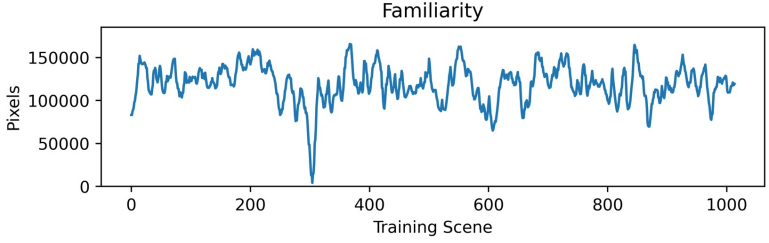
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

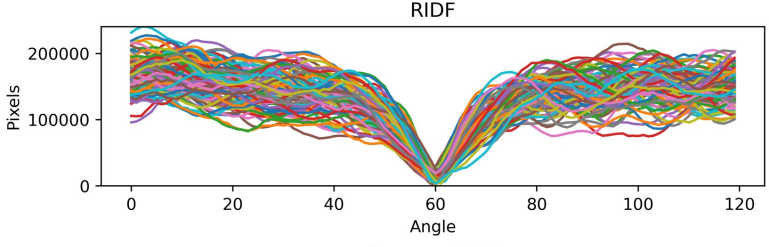
Navigation stats: RMSD error: 75.55; RMSD/dist: 0.189; TD: 97801; p90: 26; p50: 12; complete: 0

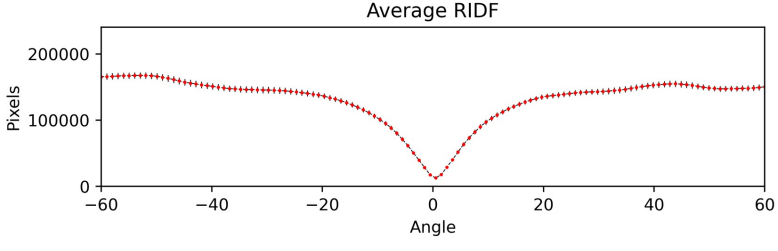
100%







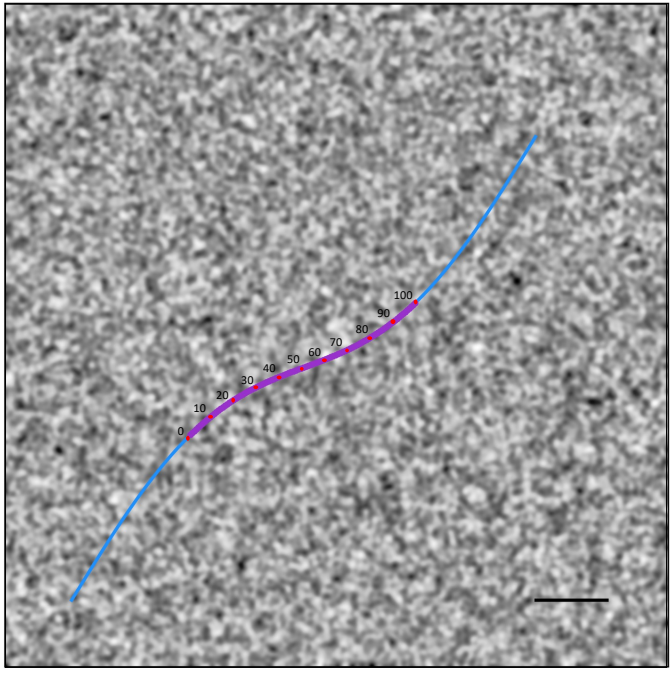


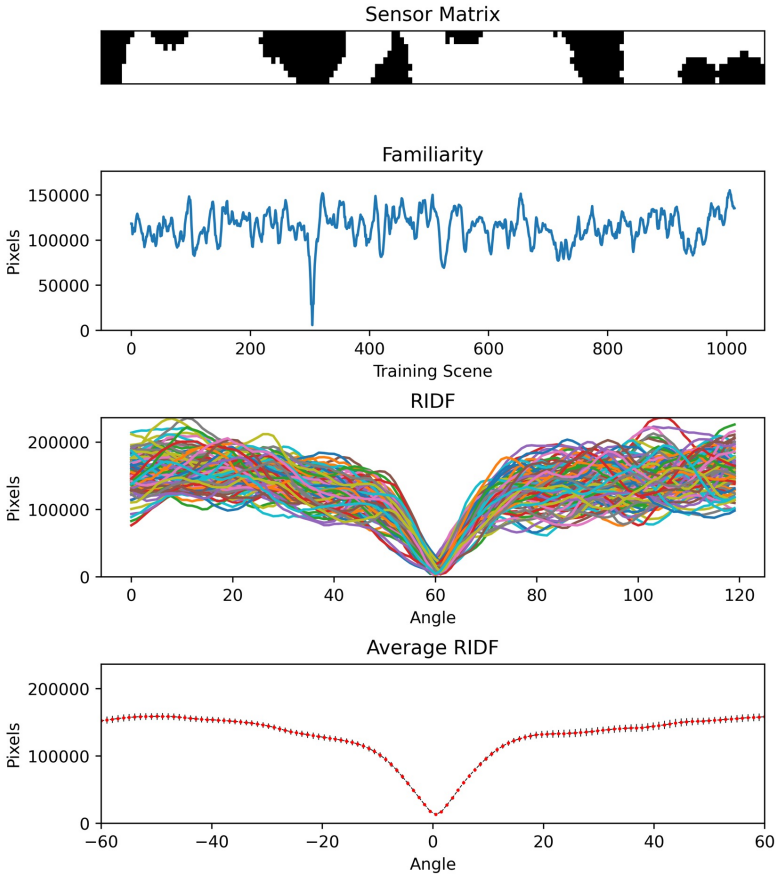


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 48.29; RMSD/dist: 0.121; TD: 103896; p90: 22; p50: 10; complete: 0

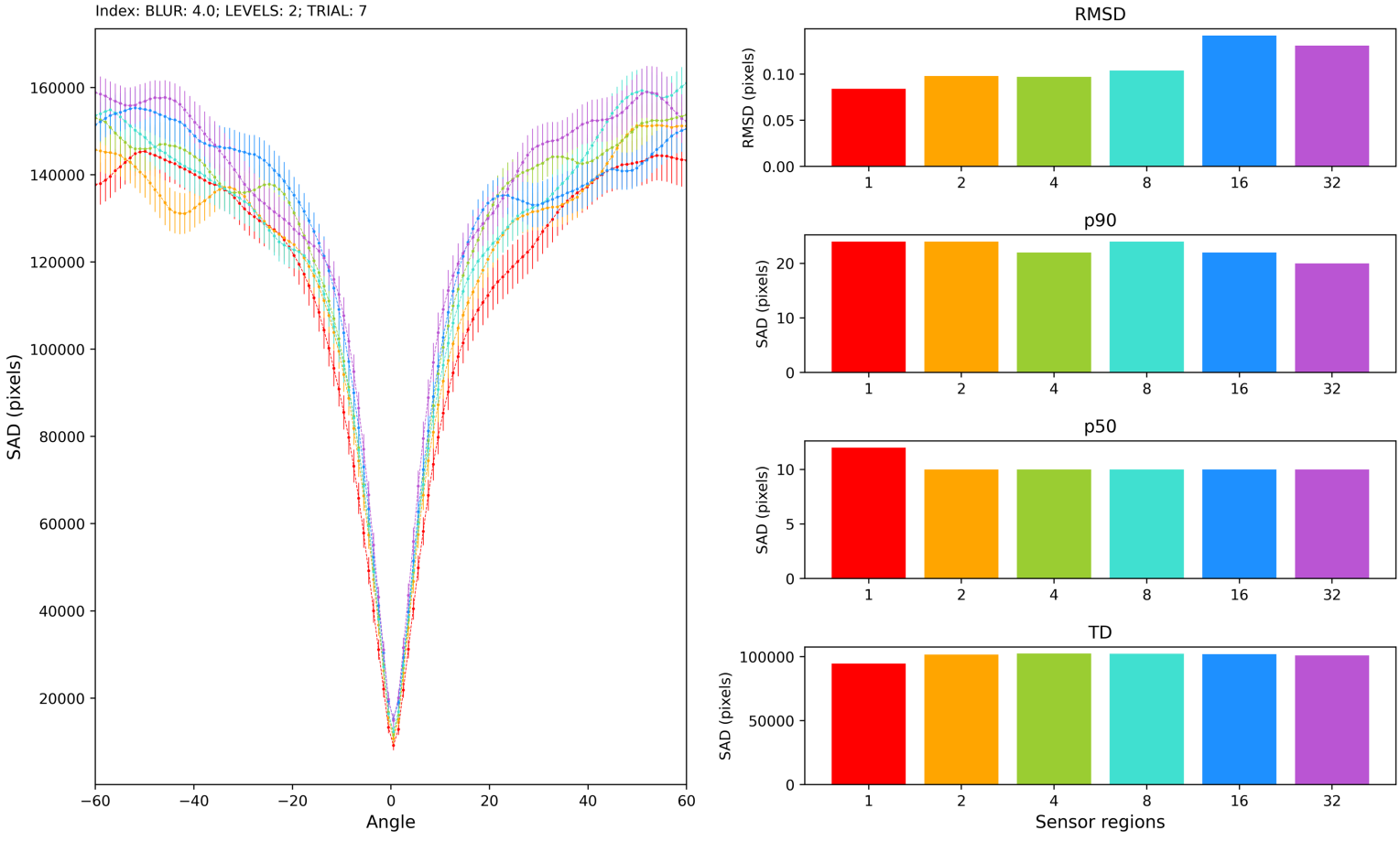
100%



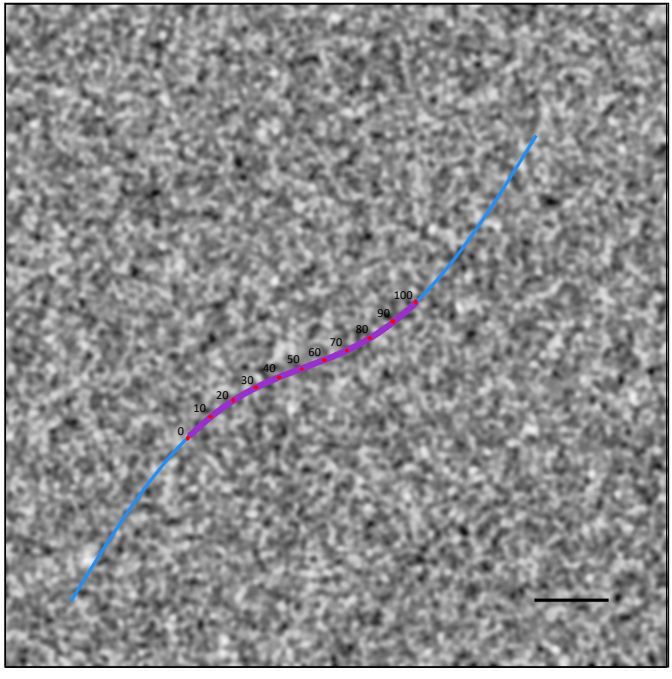


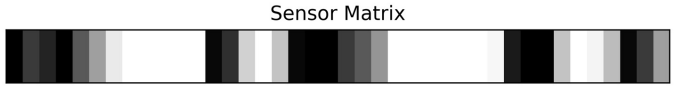
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

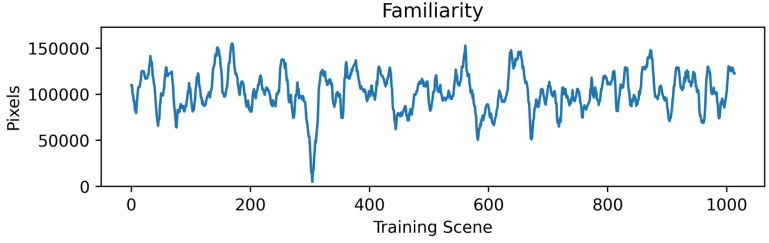
Navigation stats: RMSD error: 49.36; RMSD/dist: 0.123; TD: 103013; p90: 22; p50: 12; complete: 0

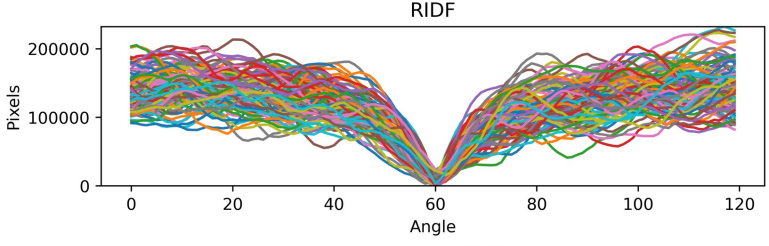

Index: BLUR: 4.0; LEVELS: 2; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

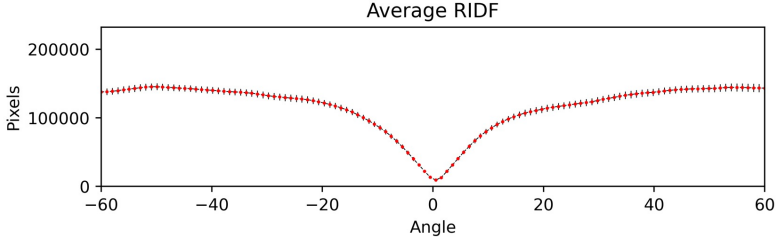
100%







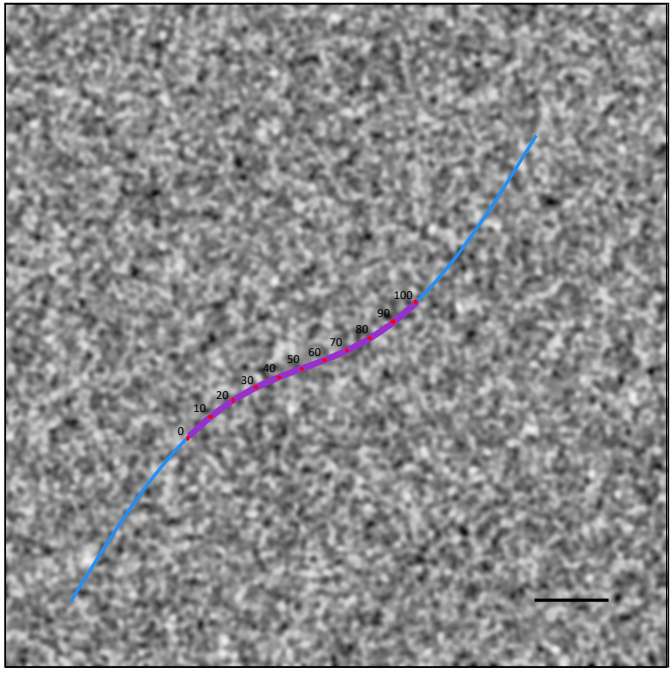


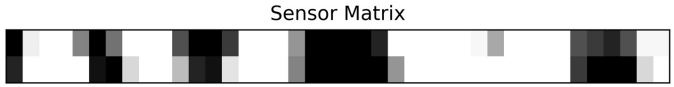


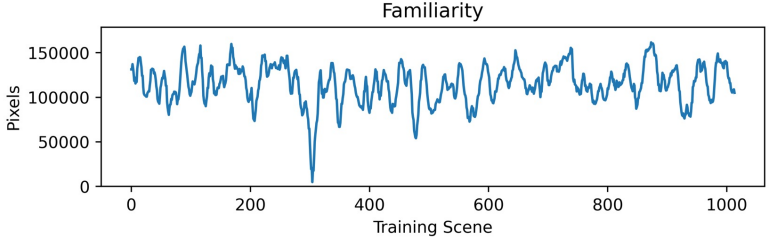
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

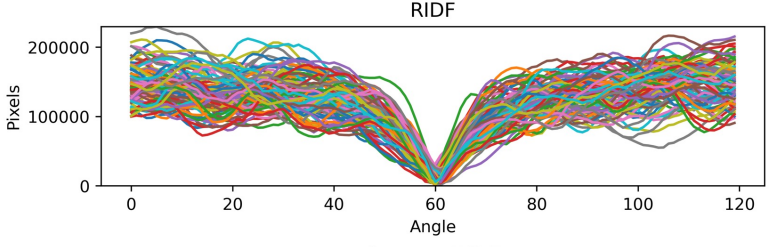
Navigation stats: RMSD error: 33.67; RMSD/dist: 0.084; TD: 94636; p90: 24; p50: 12; complete: 0

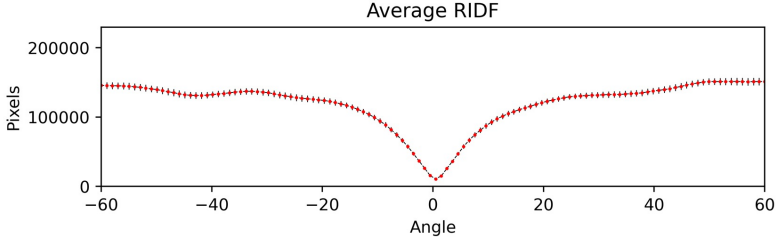
100%







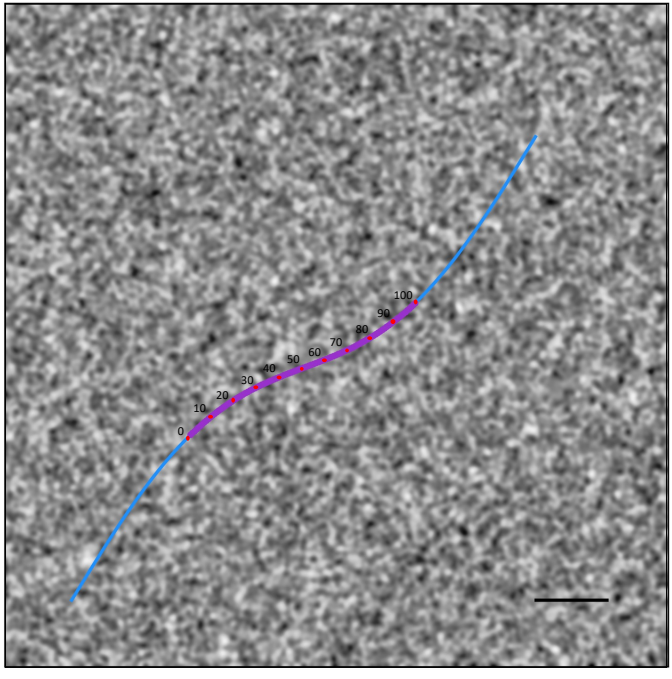


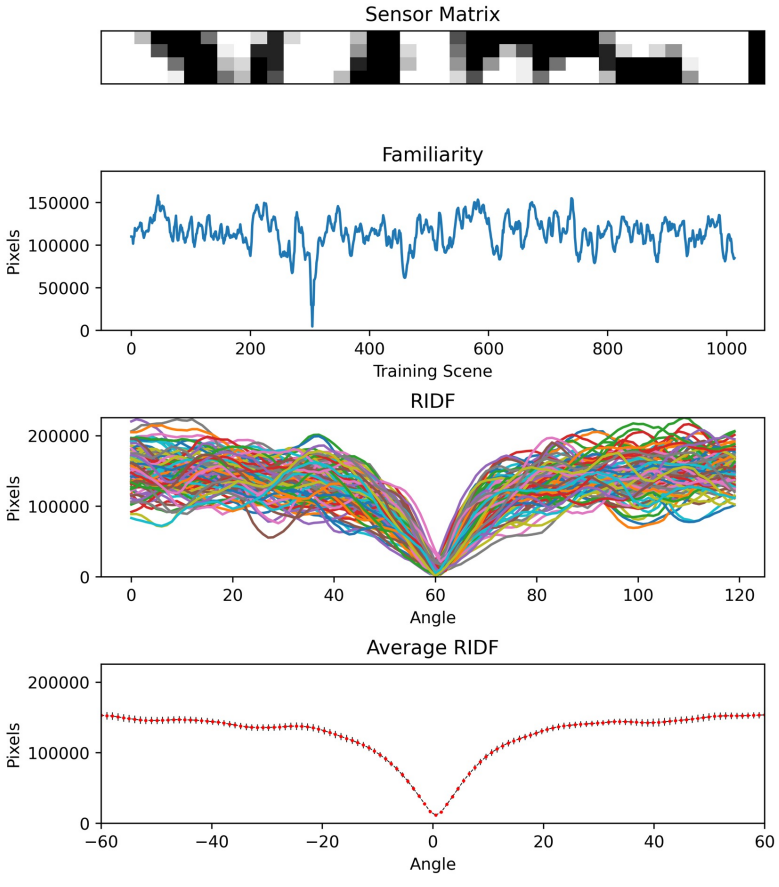


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 39.04; RMSD/dist: 0.098; TD: 101717; p90: 24; p50: 10; complete: 0

100%

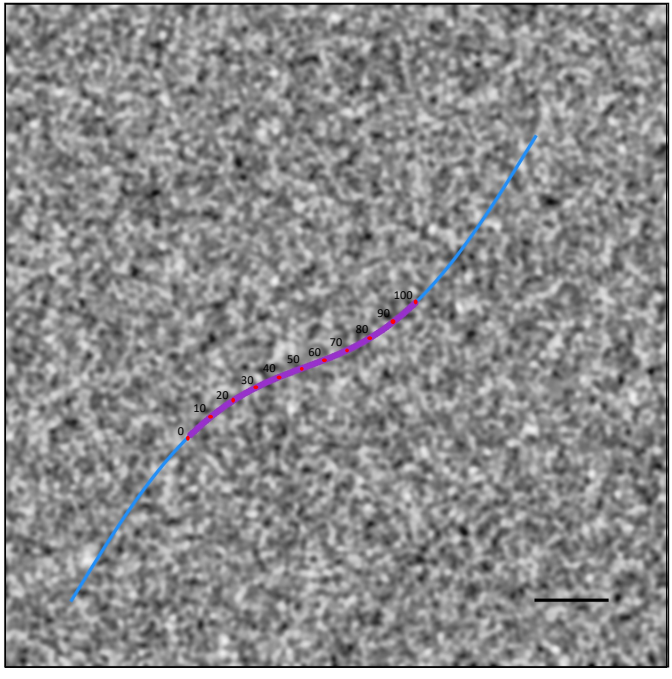


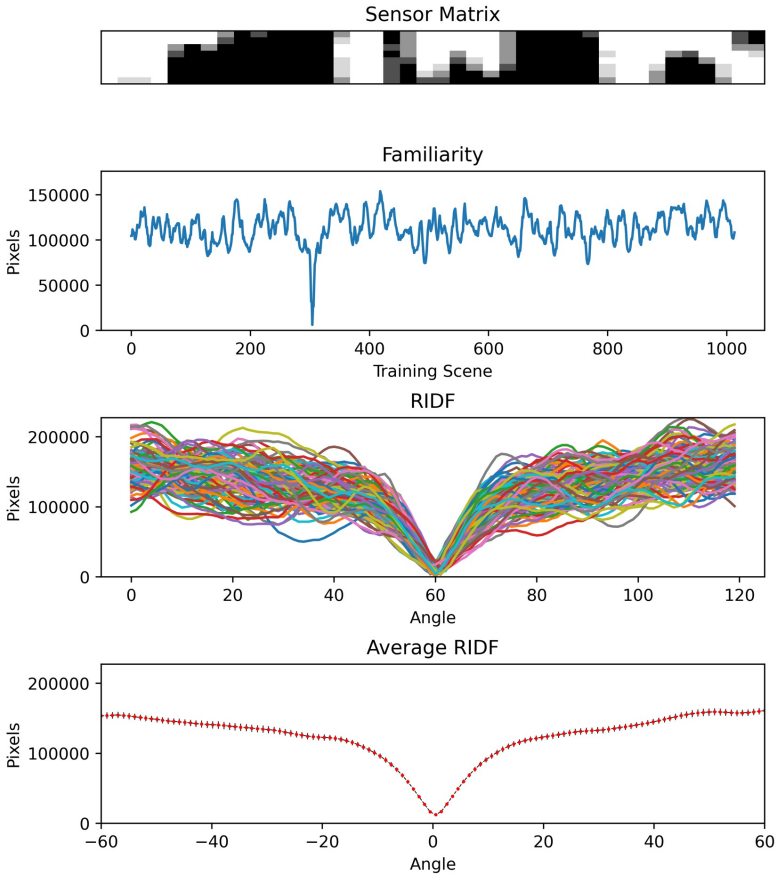


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 38.97; RMSD/dist: 0.097; TD: 102439; p90: 22; p50: 10; complete: 0

100%

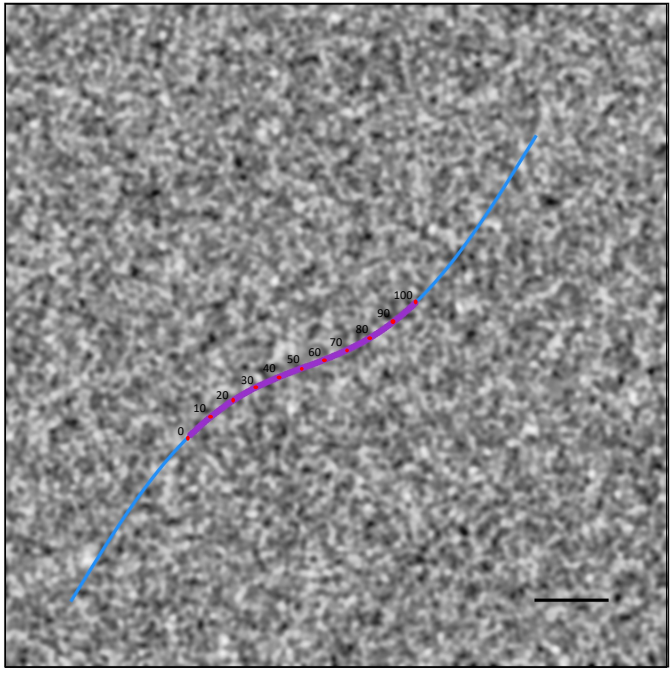


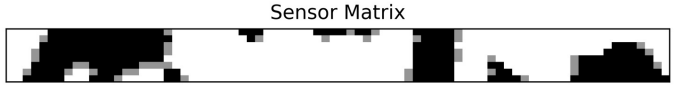


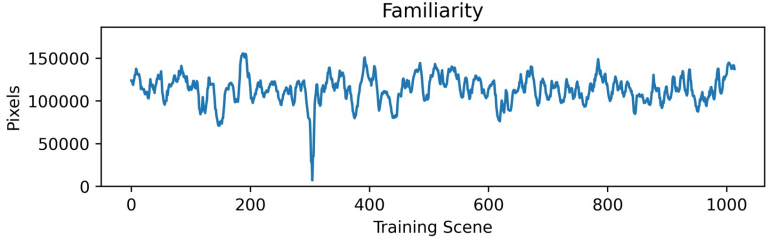
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

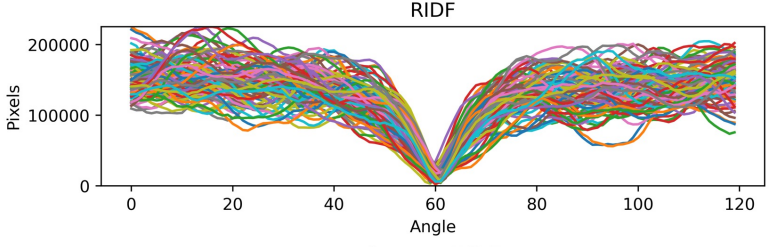
Navigation stats: RMSD error: 41.79; RMSD/dist: 0.104; TD: 102405; p90: 24; p50: 10; complete: 0

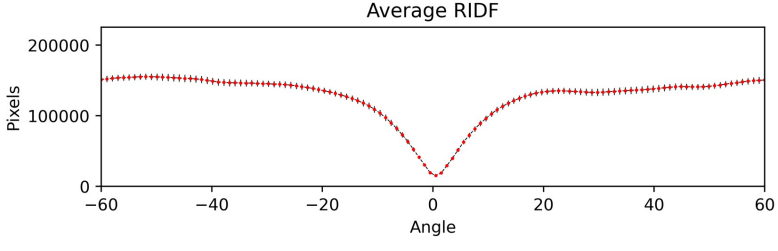
100%







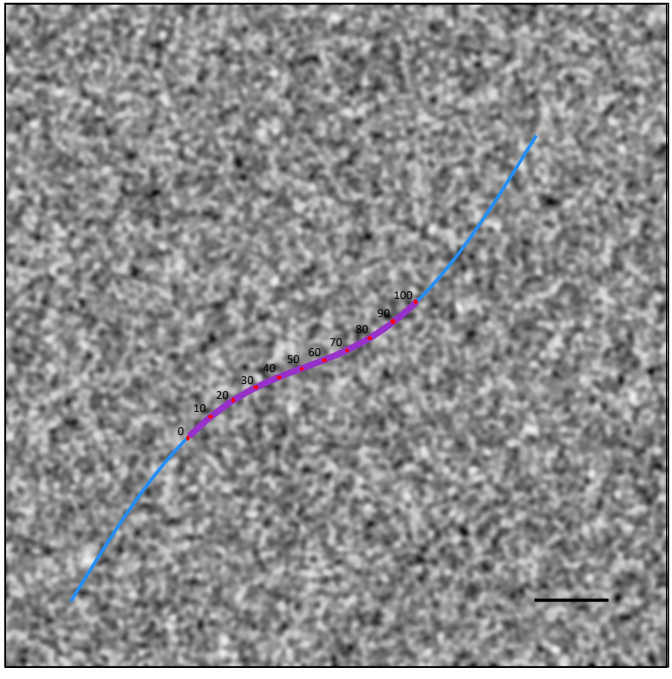


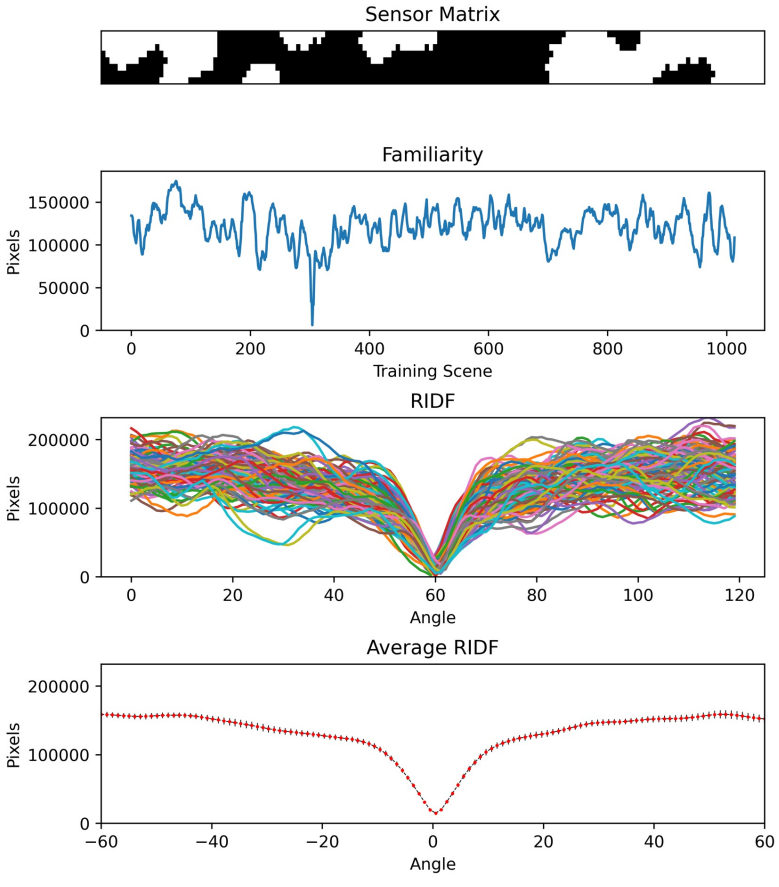


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 56.71; RMSD/dist: 0.142; TD: 101954; p90: 22; p50: 10; complete: 0

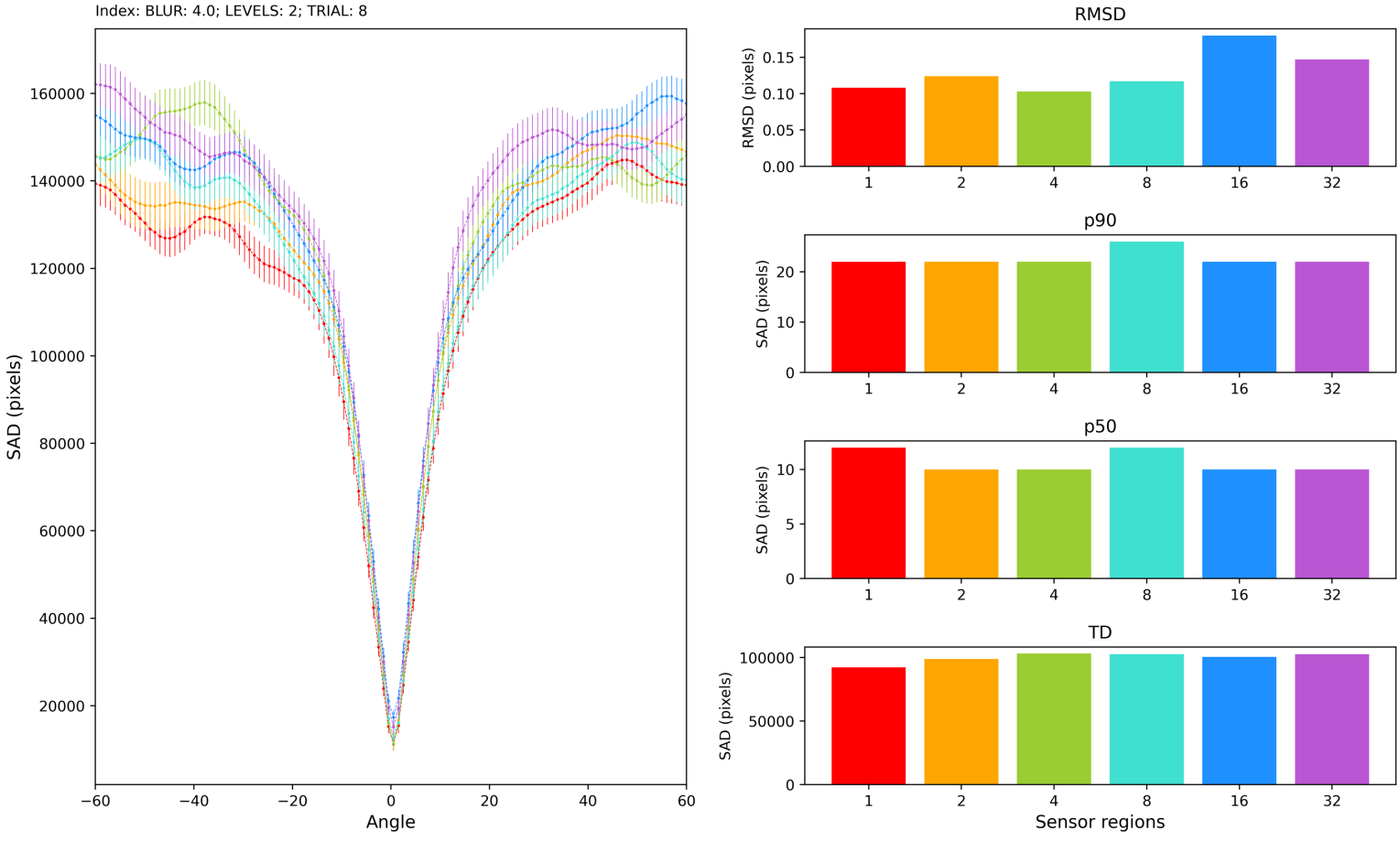
100%



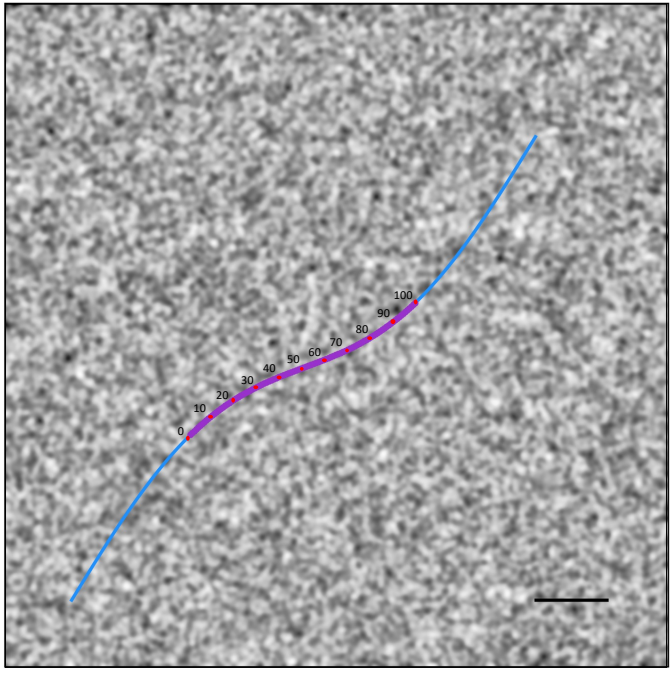


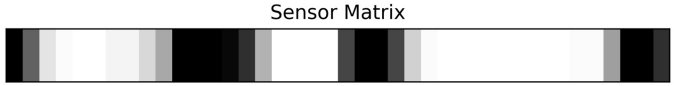
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

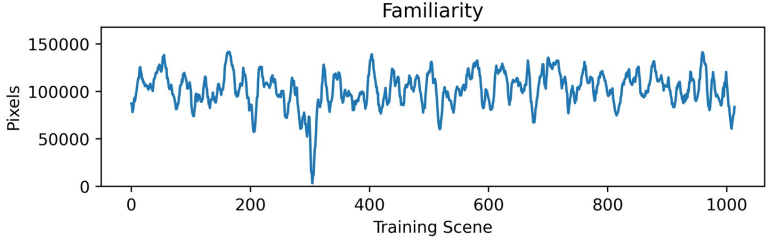
Navigation stats: RMSD error: 52.42; RMSD/dist: 0.131; TD: 101039; p90: 20; p50: 10; complete: 0

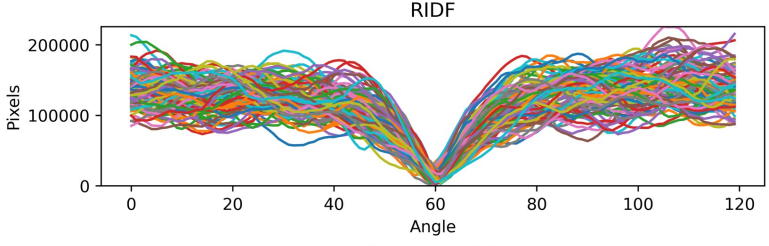

Index: BLUR: 4.0; LEVELS: 2; TRIAL: 8
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
Sensor regions

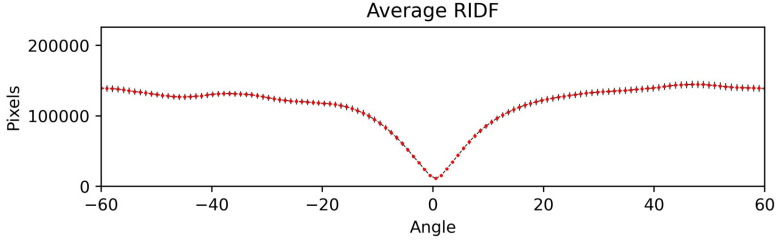
100%







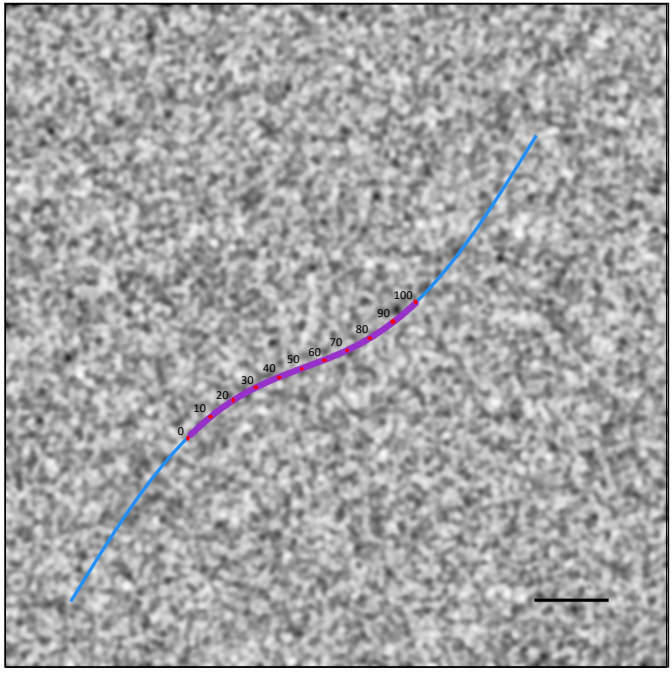


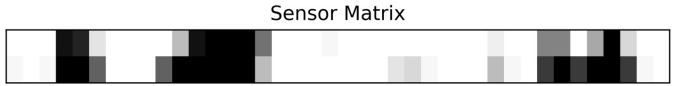


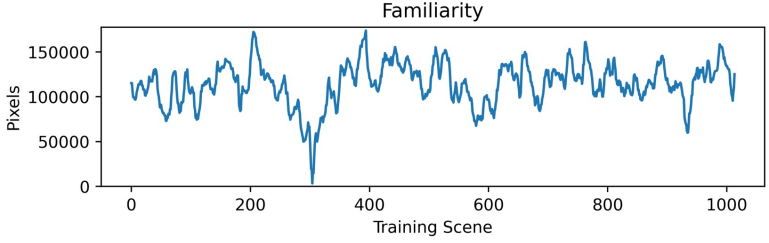
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

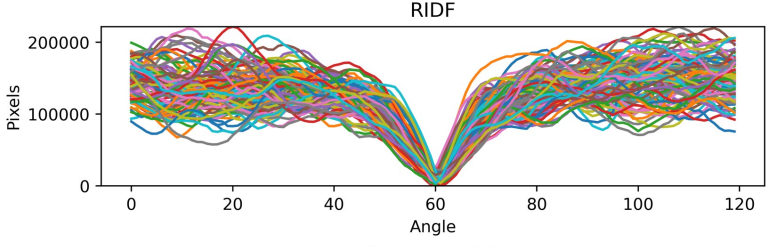
Navigation stats: RMSD error: 43.10; RMSD/dist: 0.108; TD: 92112; p90: 22; p50: 12; complete: 0

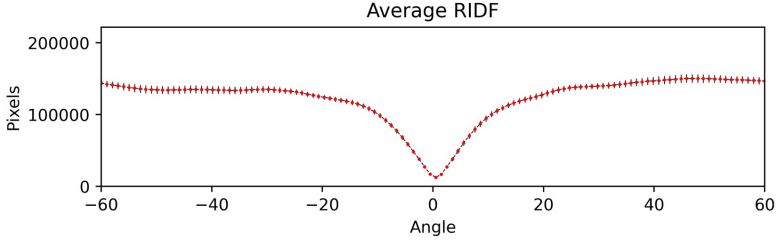
100%







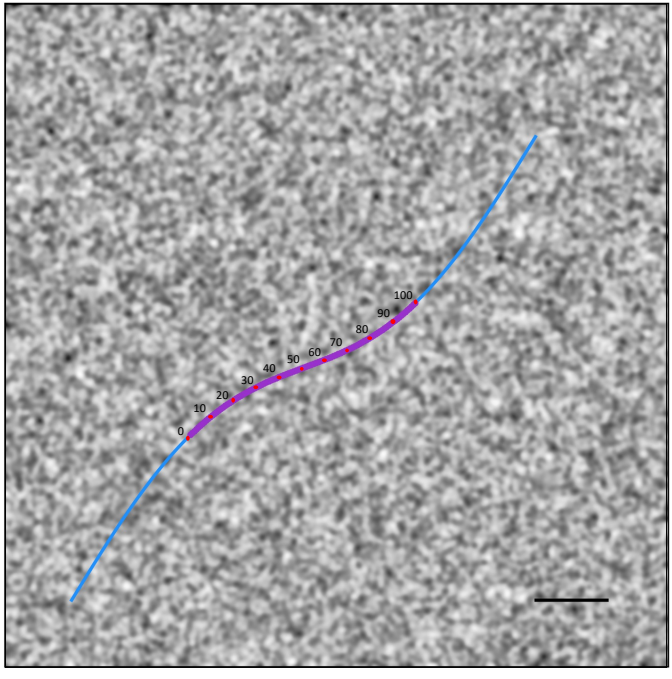


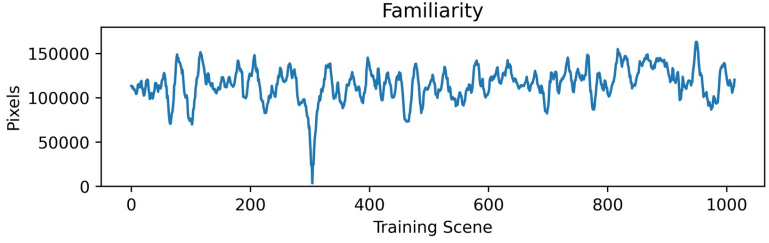


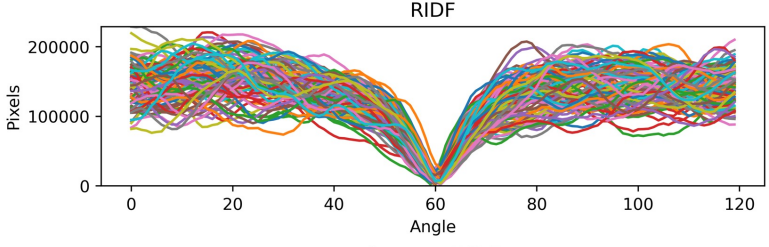
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

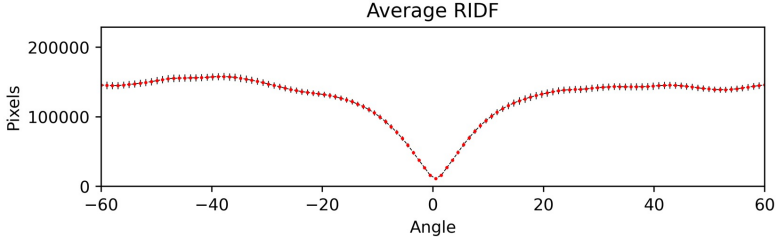
Navigation stats: RMSD error: 49.55; RMSD/dist: 0.124; TD: 98838; p90: 22; p50: 10; complete: 0

100%





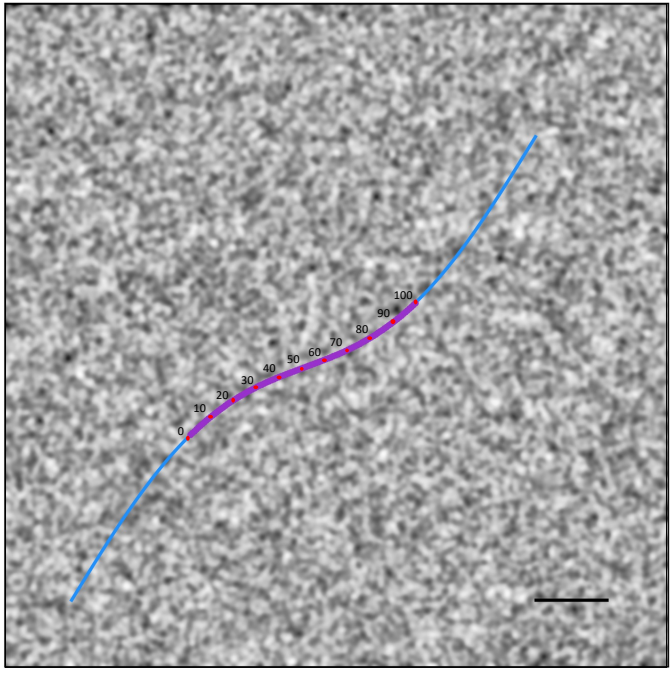


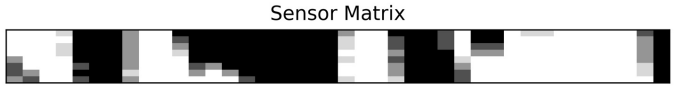


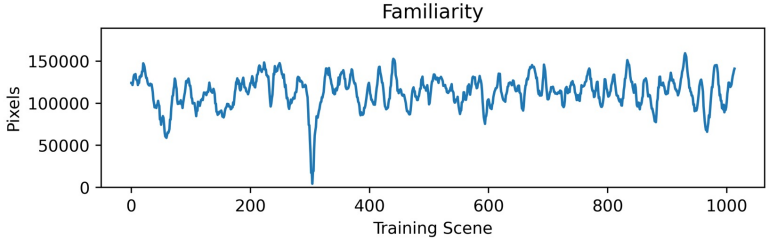
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

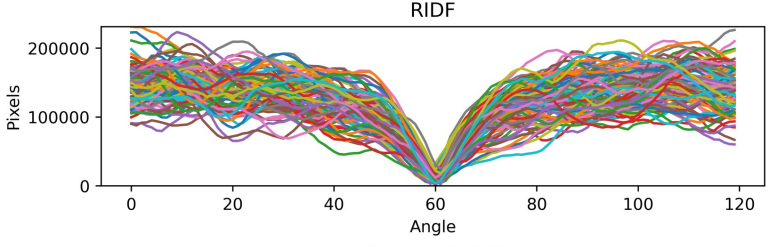
Navigation stats: RMSD error: 41.19; RMSD/dist: 0.103; TD: 103004; p90: 22; p50: 10; complete: 0

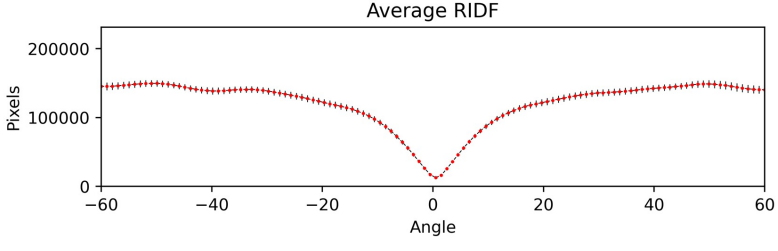
100%







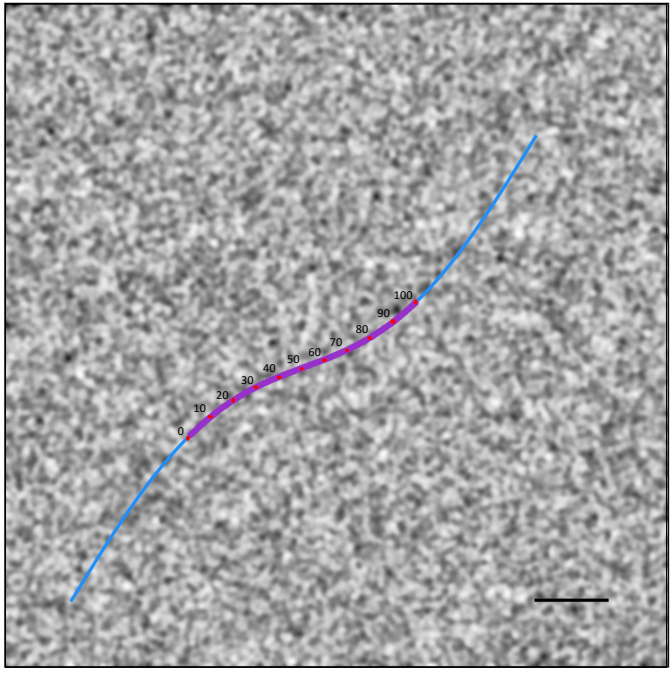


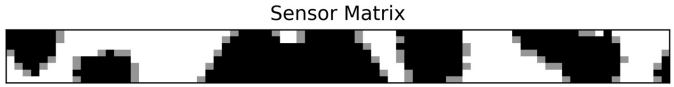


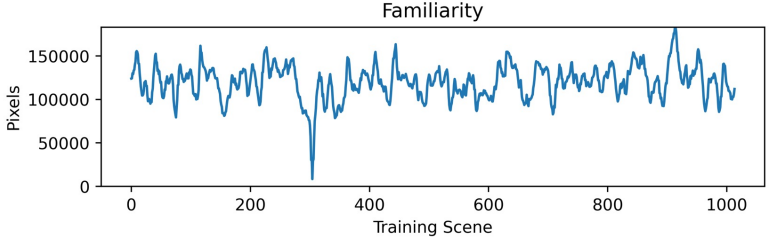
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

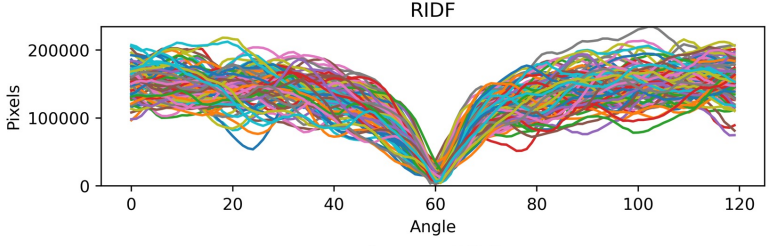
Navigation stats: RMSD error: 46.97; RMSD/dist: 0.117; TD: 102662; p90: 26; p50: 12; complete: 0

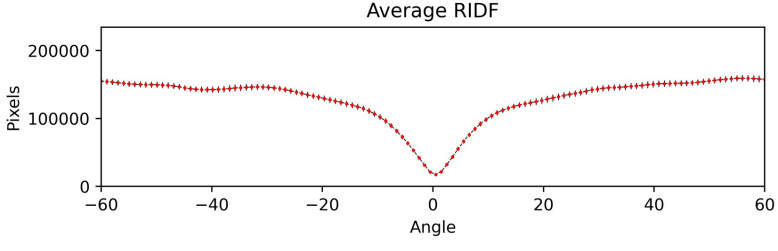
100%







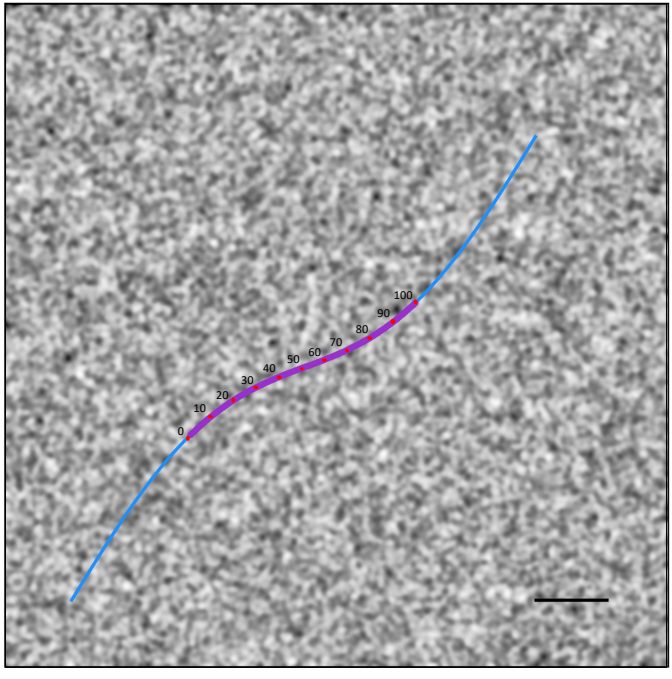


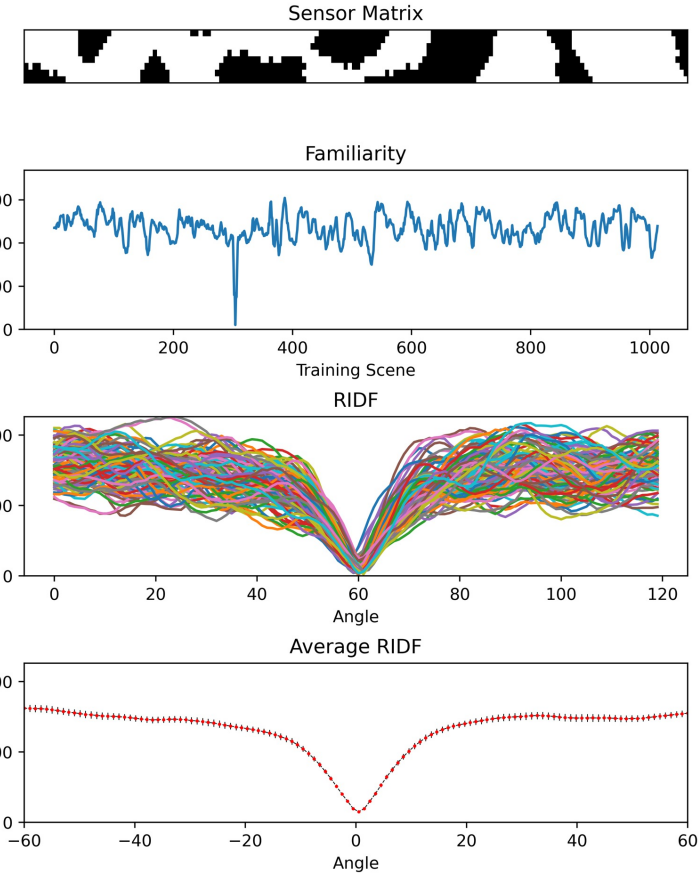


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 71.93; RMSD/dist: 0.180; TD: 100497; p90: 22; p50: 10; complete: 0

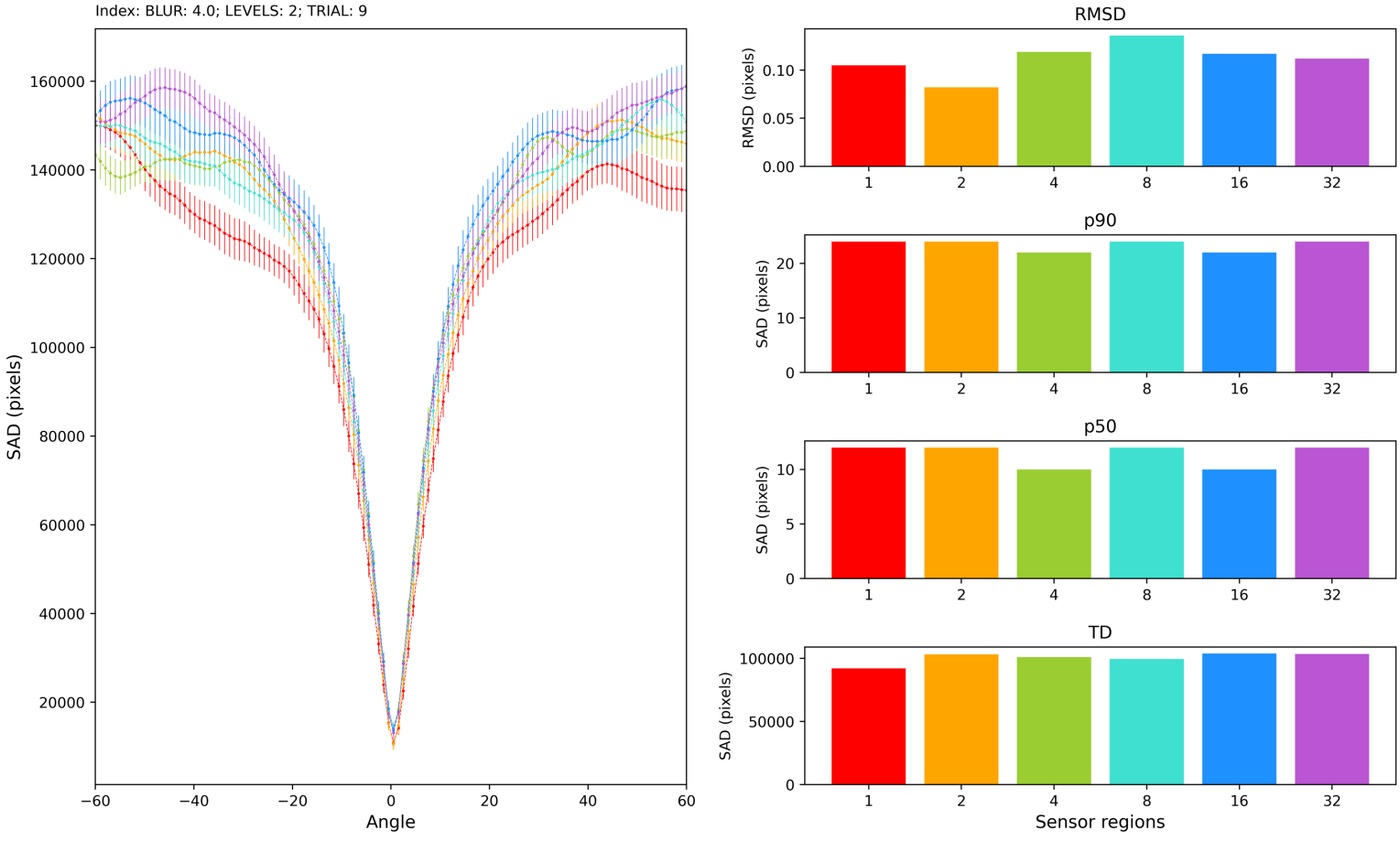
100%



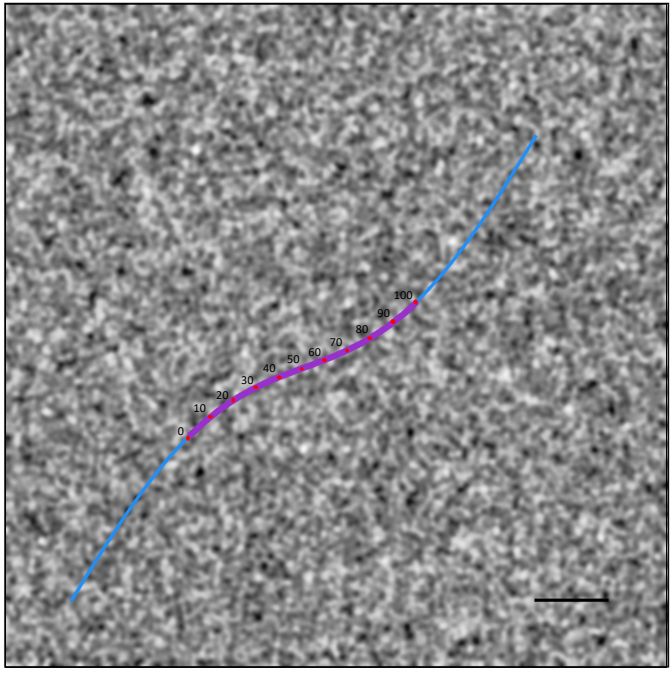


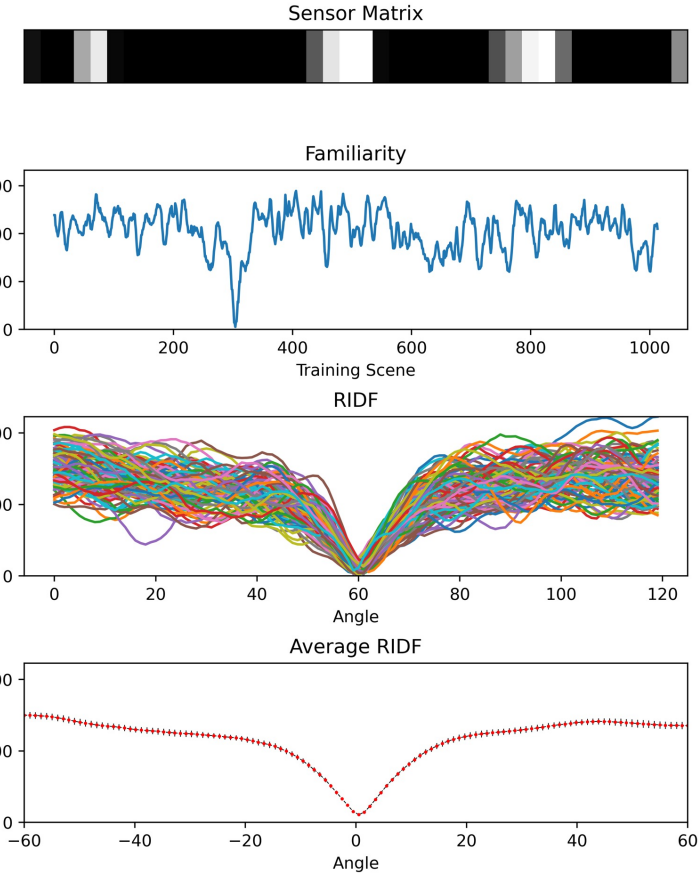
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 58.71; RMSD/dist: 0.147; TD: 102534; p90: 22; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 2; TRIAL: 9
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
100000
50000
0
1
2
4
8
16
32
Sensor regions

100%

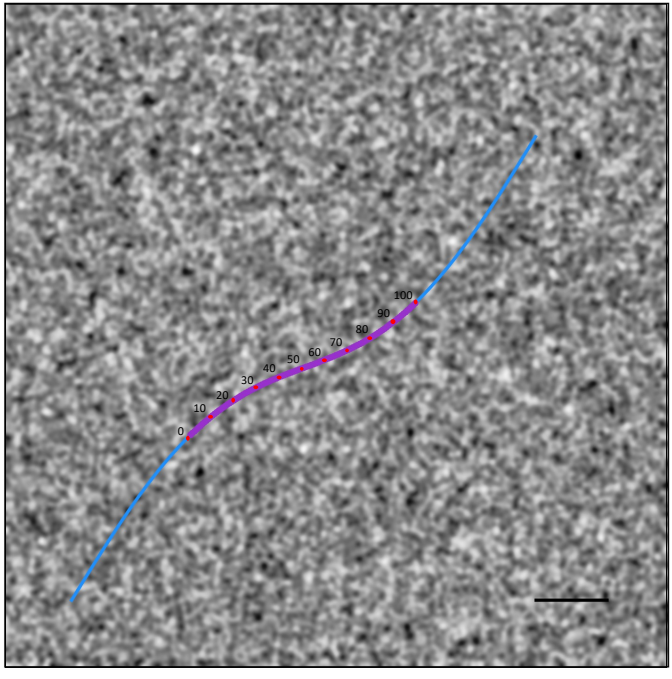


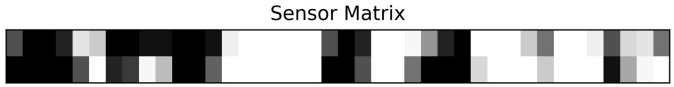


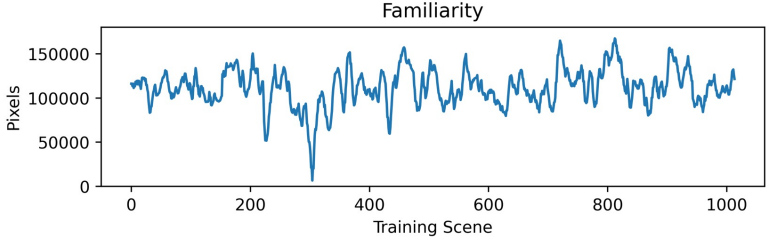
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

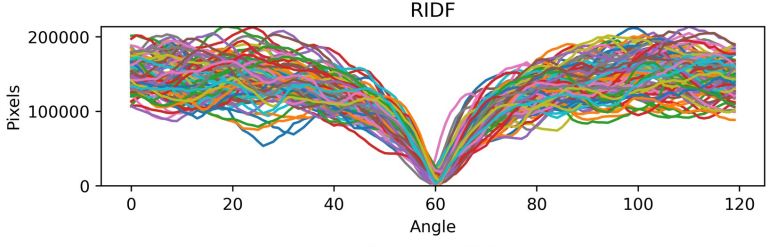
Navigation stats: RMSD error: 41.82; RMSD/dist: 0.105; TD: 92118; p90: 24; p50: 12; complete: 0

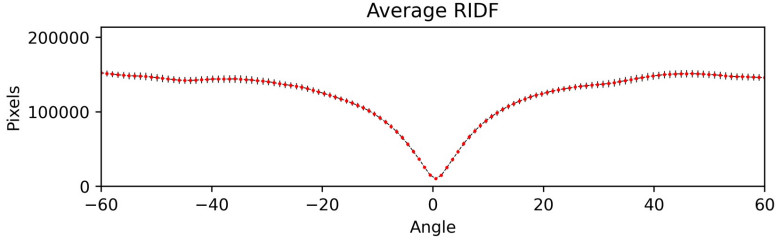
100%







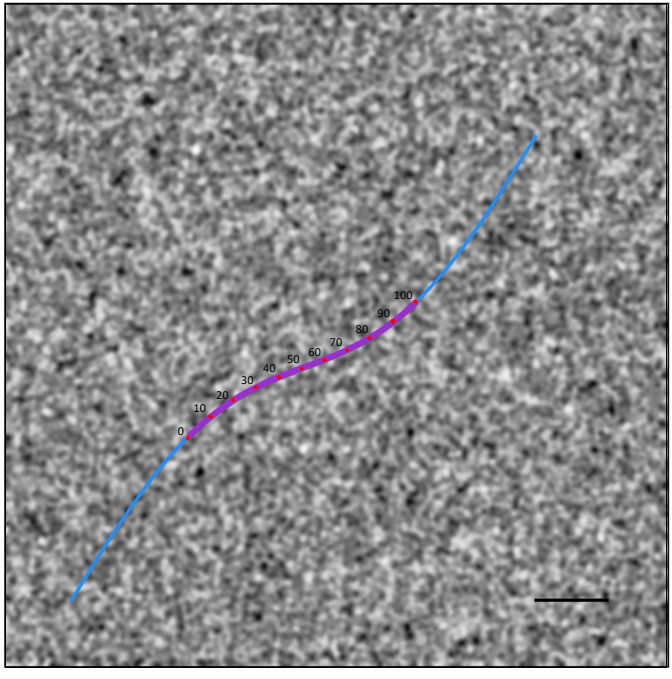


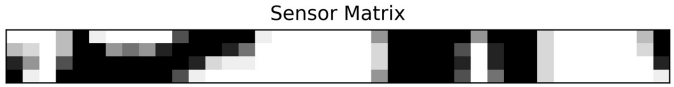


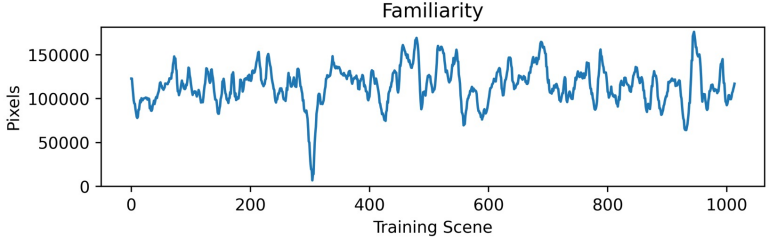
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

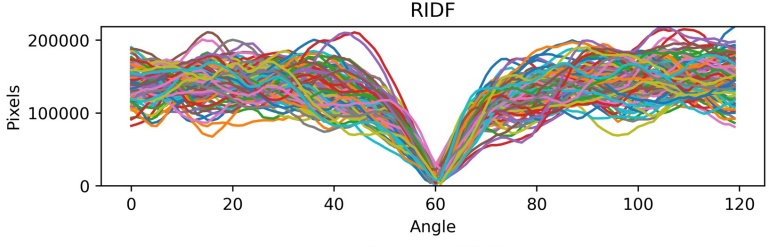
Navigation stats: RMSD error: 32.96; RMSD/dist: 0.082; TD: 103158; p90: 24; p50: 12; complete: 0

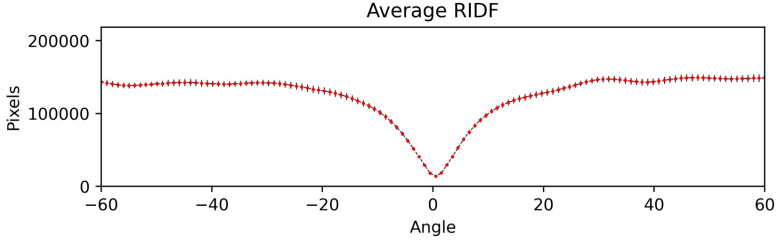
100%







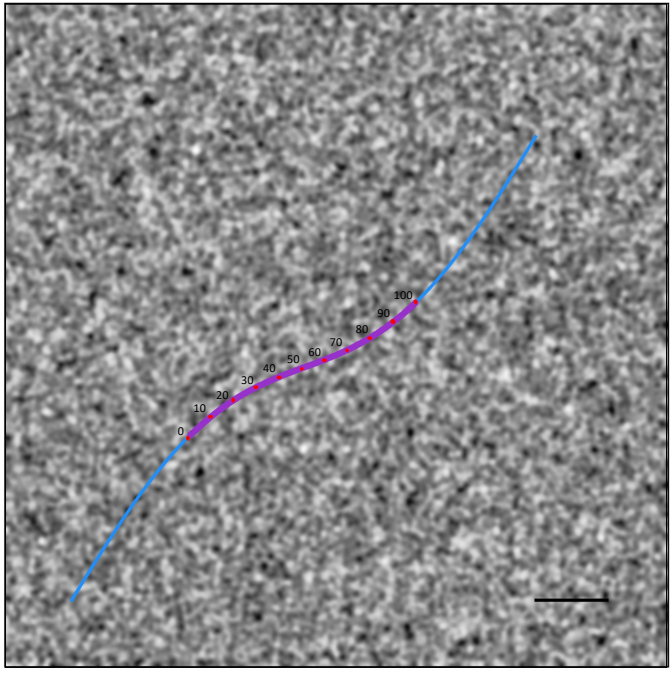


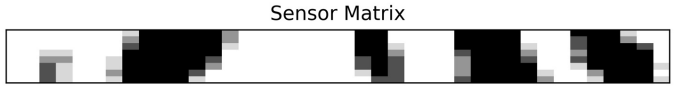


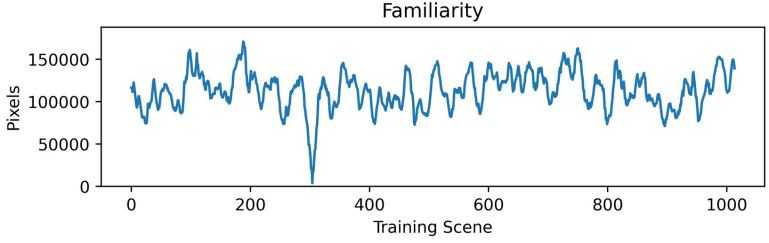
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

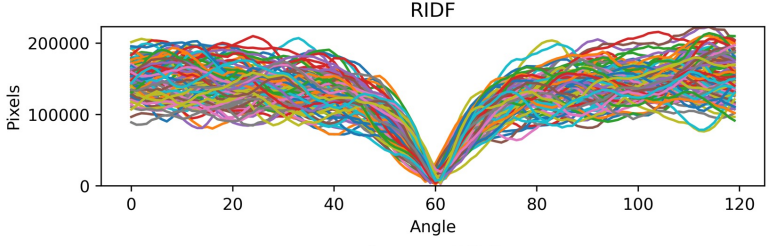
Navigation stats: RMSD error: 47.51; RMSD/dist: 0.119; TD: 101060; p90: 22; p50: 10; complete: 0

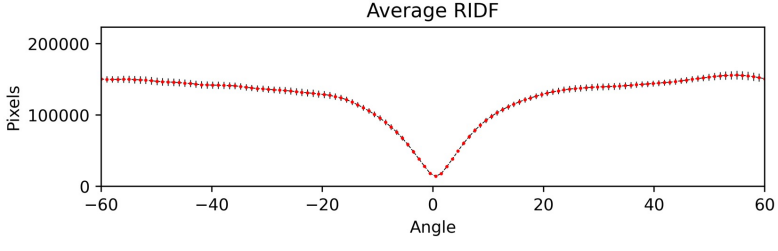
100%







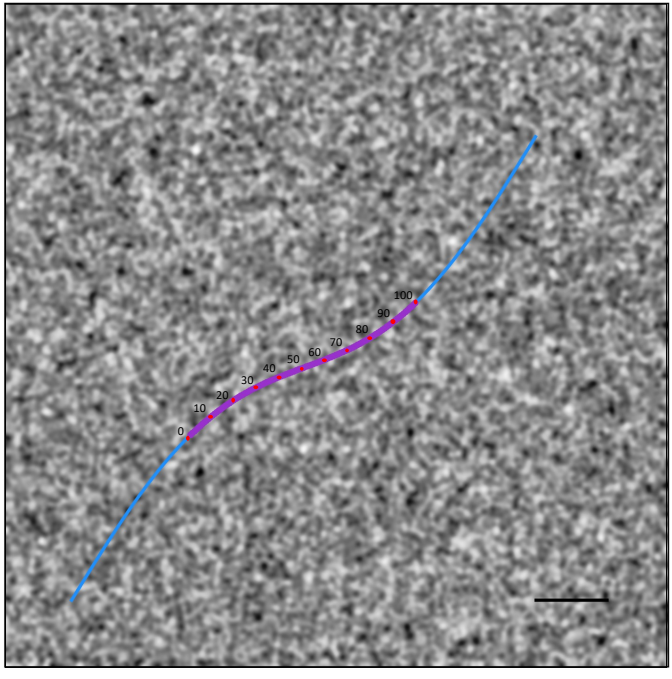


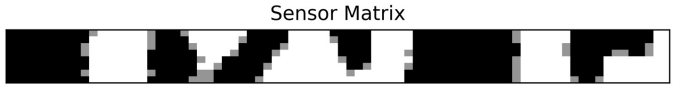


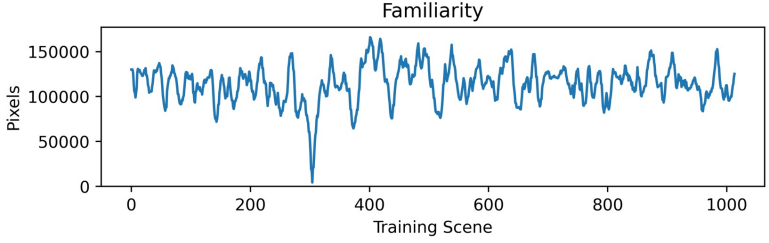
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

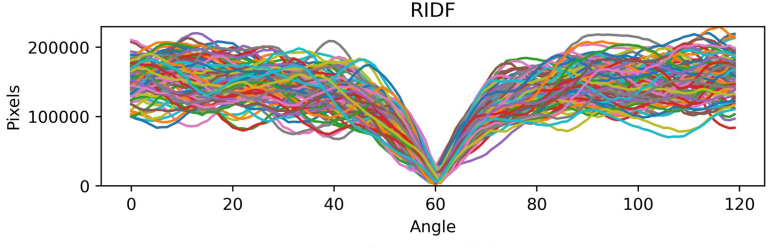
Navigation stats: RMSD error: 54.50; RMSD/dist: 0.136; TD: 99515; p90: 24; p50: 12; complete: 0

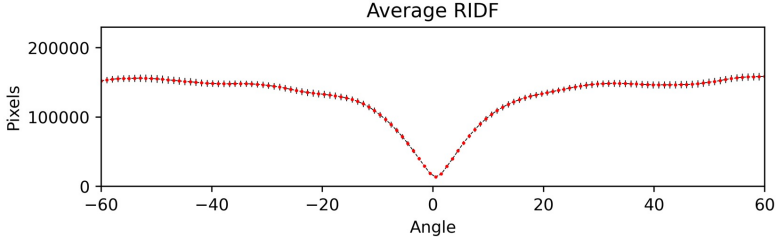
100%







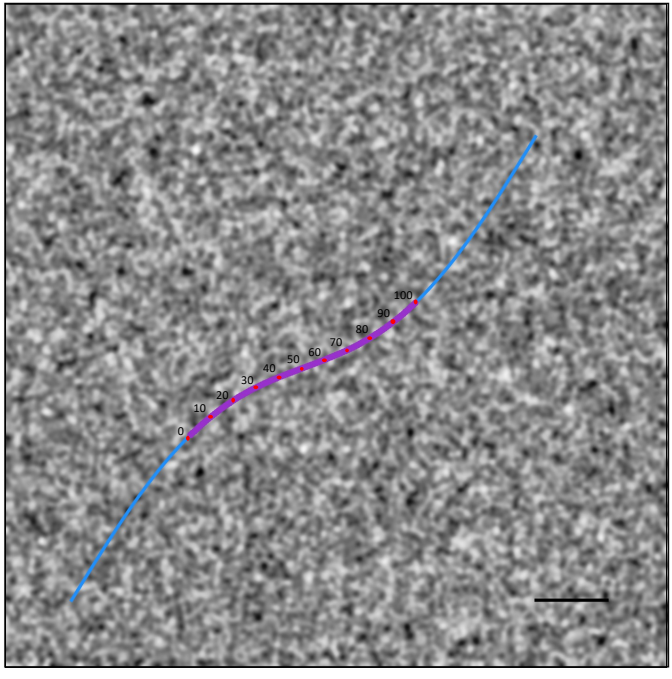


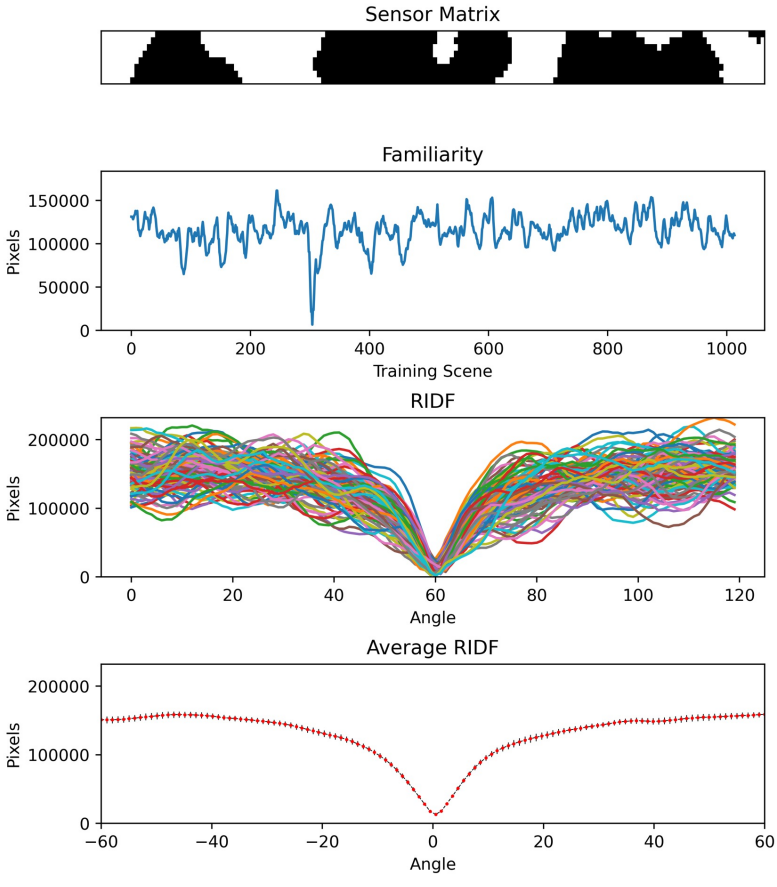


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 46.91; RMSD/dist: 0.117; TD: 103767; p90: 22; p50: 10; complete: 0

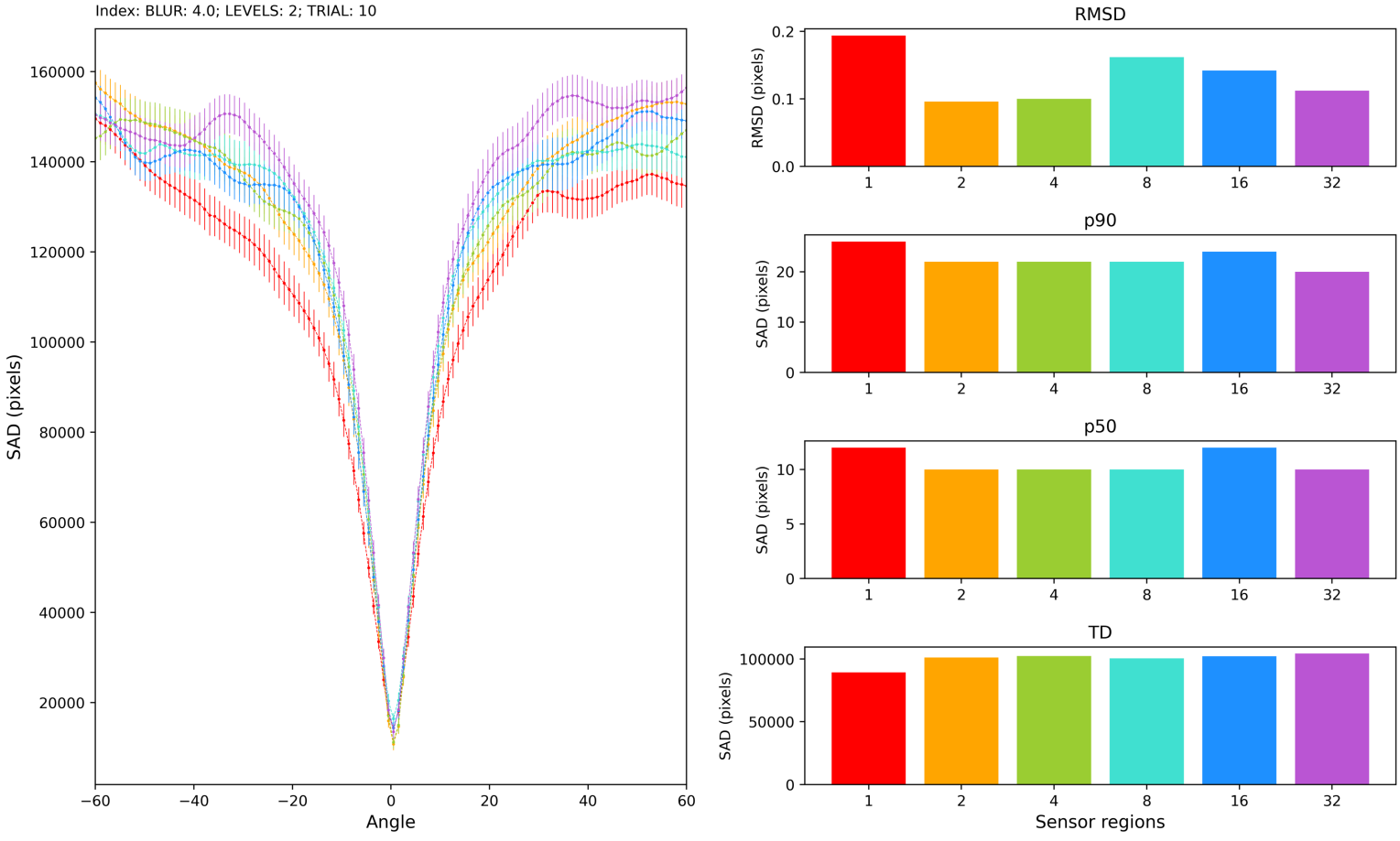
100%



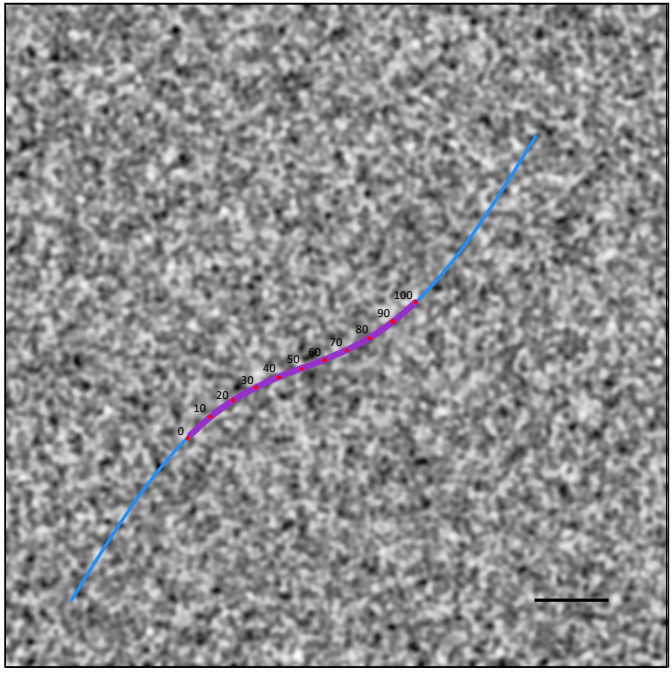


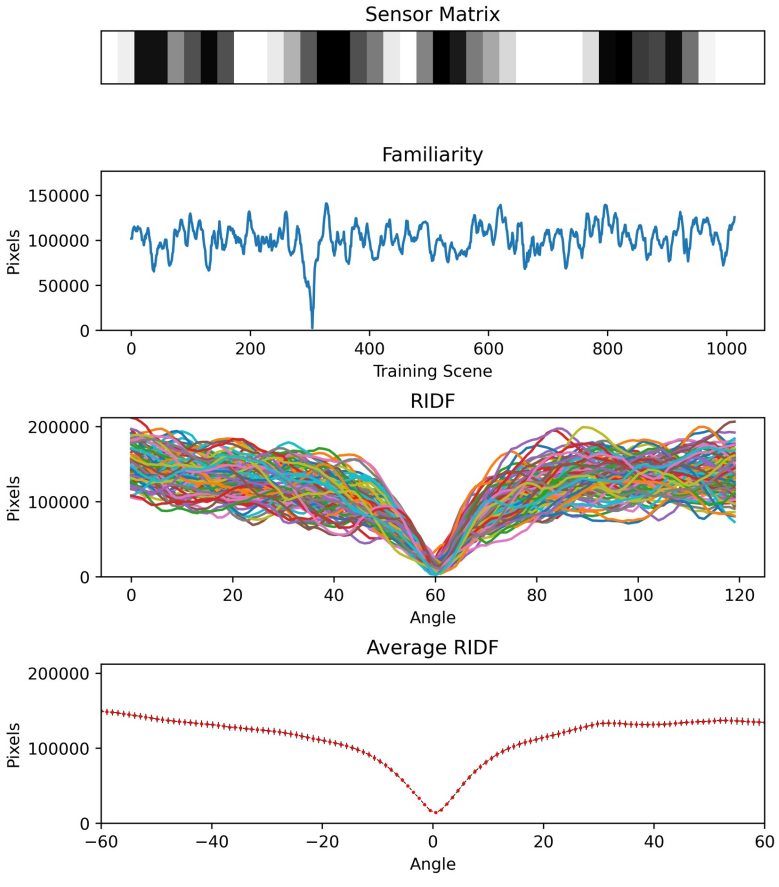
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 44.82; RMSD/dist: 0.112; TD: 103514; p90: 24; p50: 12; complete: 0


Index: BLUR: 4.0; LEVELS: 2; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

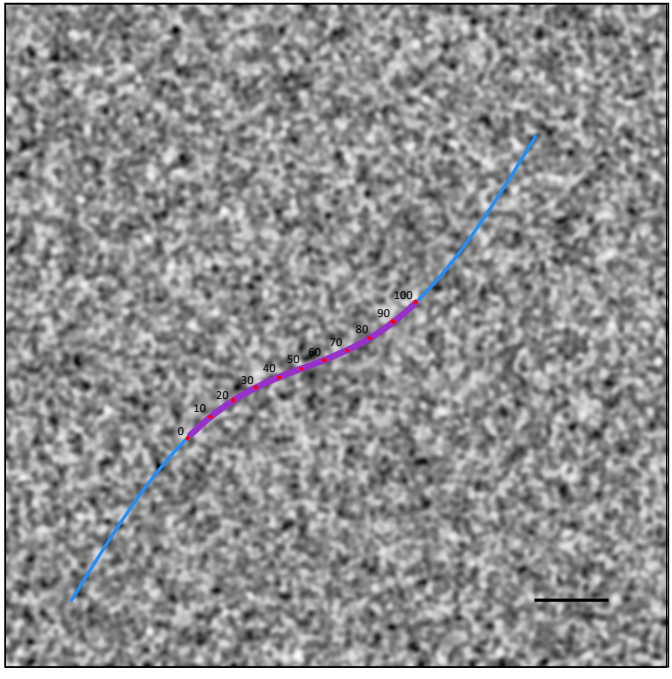


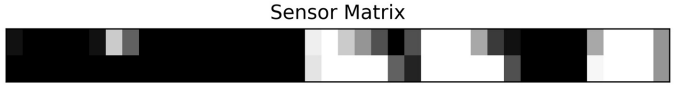


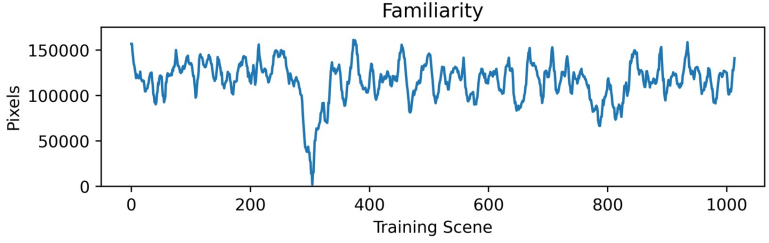
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

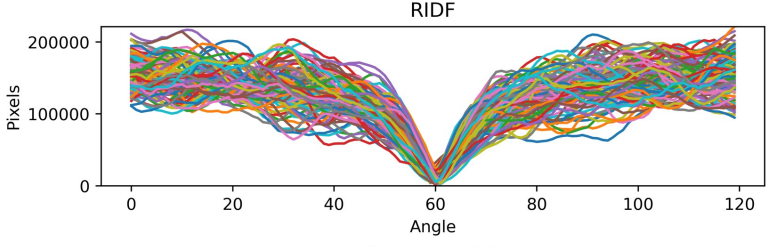
Navigation stats: RMSD error: 77.47; RMSD/dist: 0.194; TD: 89288; p90: 26; p50: 12; complete: 0

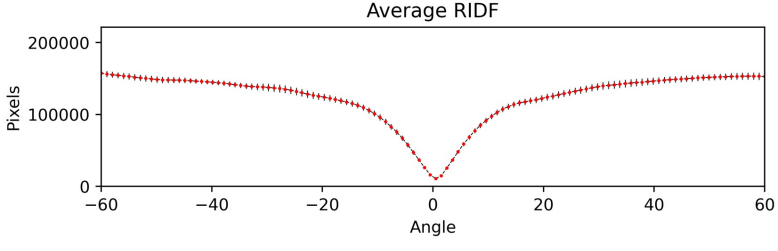
100%







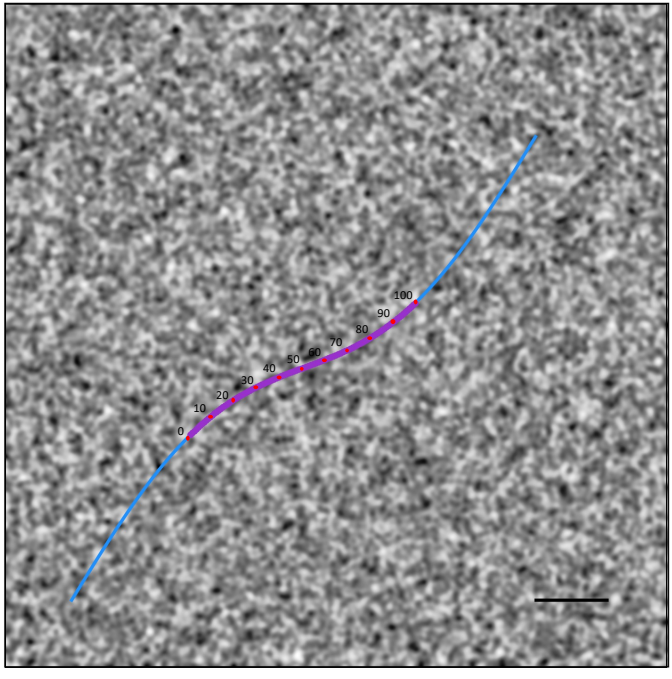


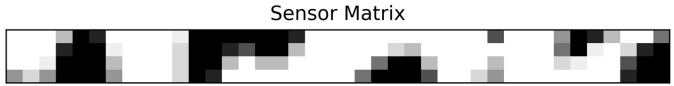


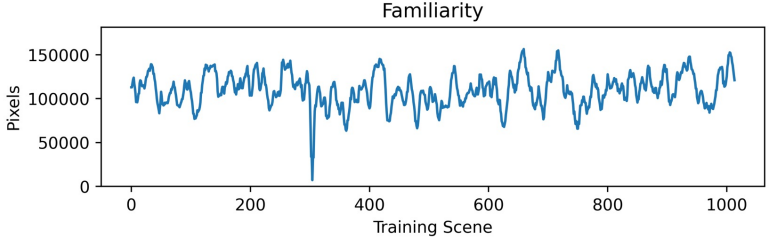
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

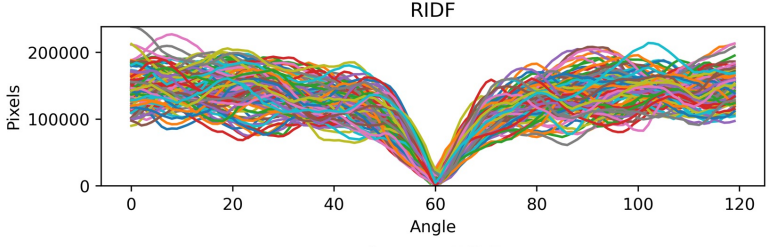
Navigation stats: RMSD error: 38.32; RMSD/dist: 0.096; TD: 101210; p90: 22; p50: 10; complete: 0

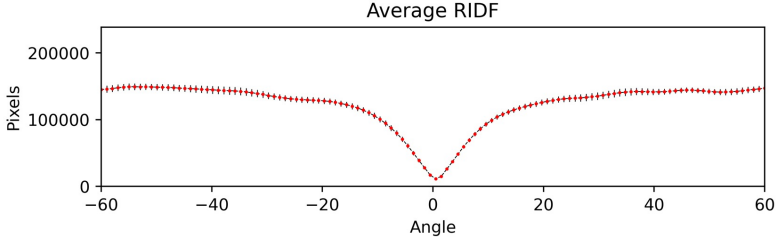
100%







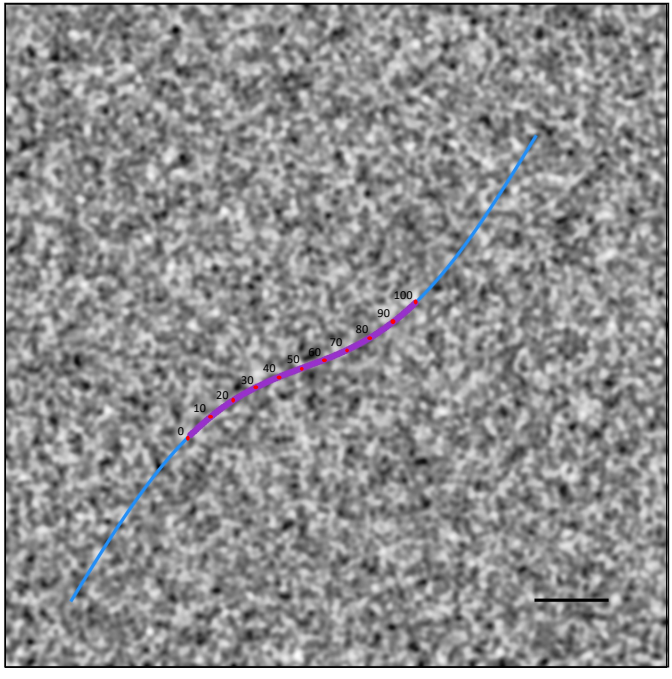


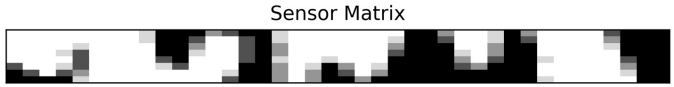


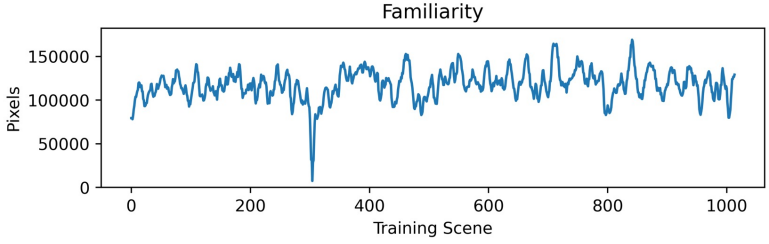
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

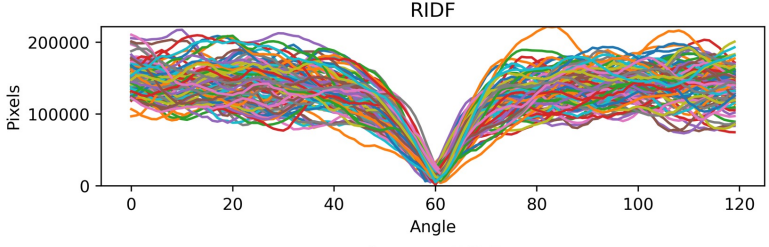
Navigation stats: RMSD error: 39.90; RMSD/dist: 0.100; TD: 102312; p90: 22; p50: 10; complete: 0

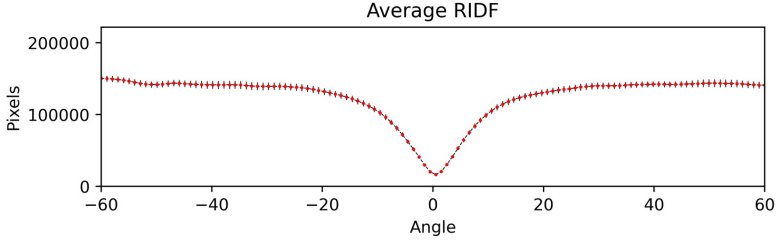
100%







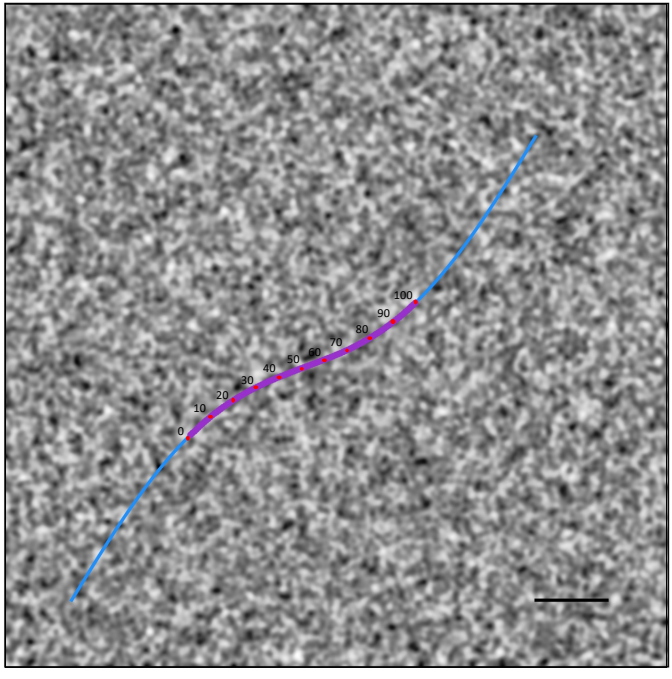


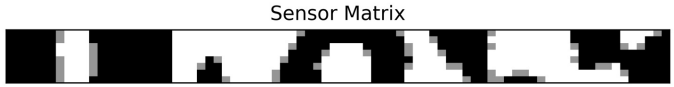


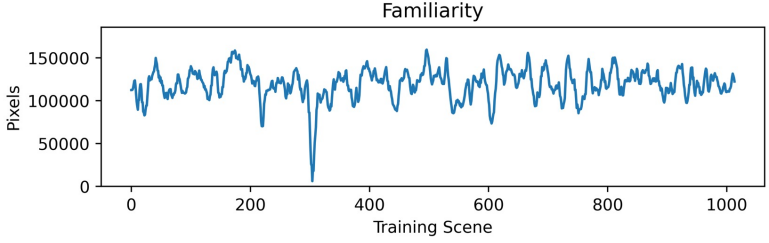
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

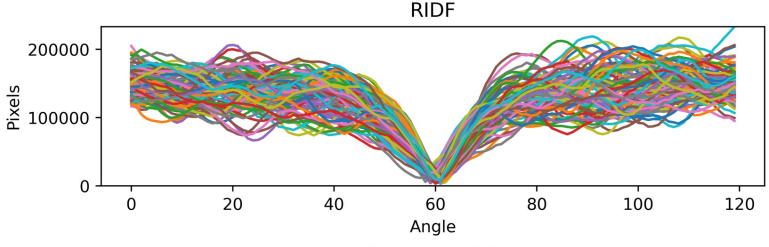
Navigation stats: RMSD error: 64.82; RMSD/dist: 0.162; TD: 100401; p90: 22; p50: 10; complete: 0

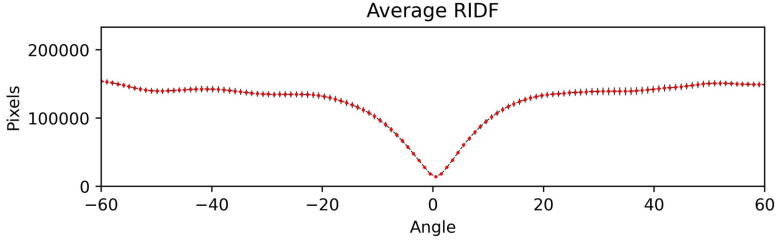
100%







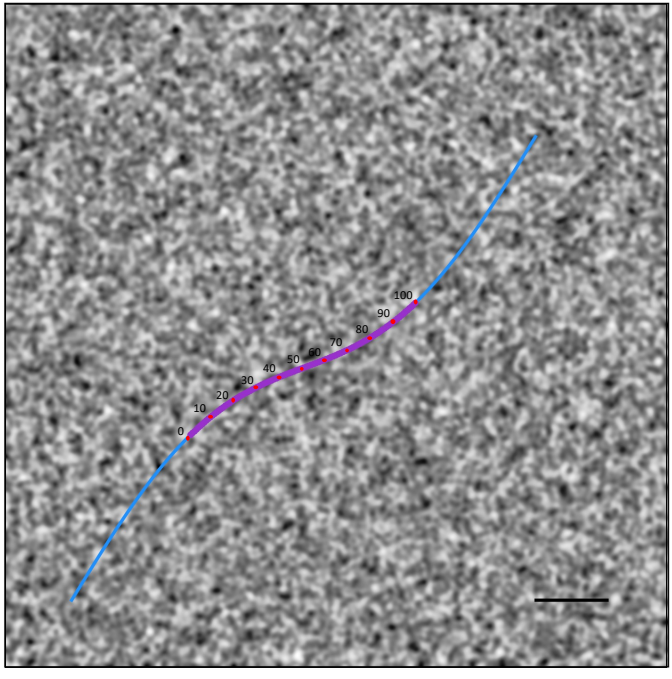


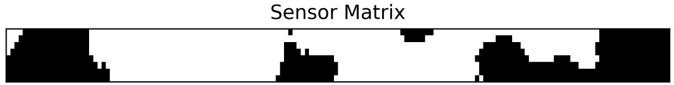


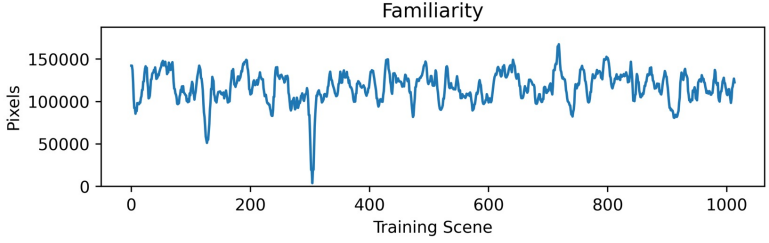
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

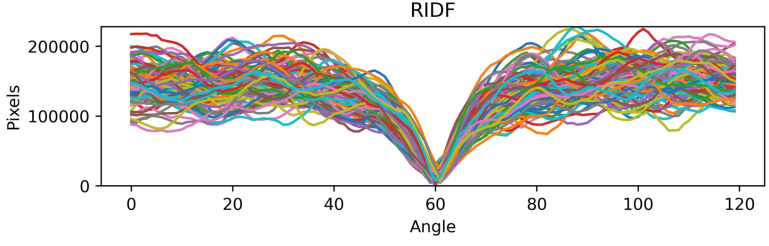
Navigation stats: RMSD error: 56.84; RMSD/dist: 0.142; TD: 102184; p90: 24; p50: 12; complete: 0

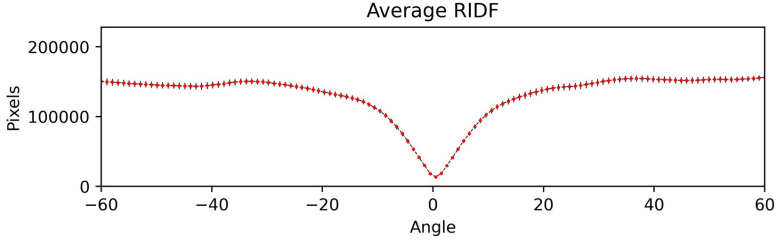
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 44.70; RMSD/dist: 0.112; TD: 104233; p90: 20; p50: 10; complete: 0