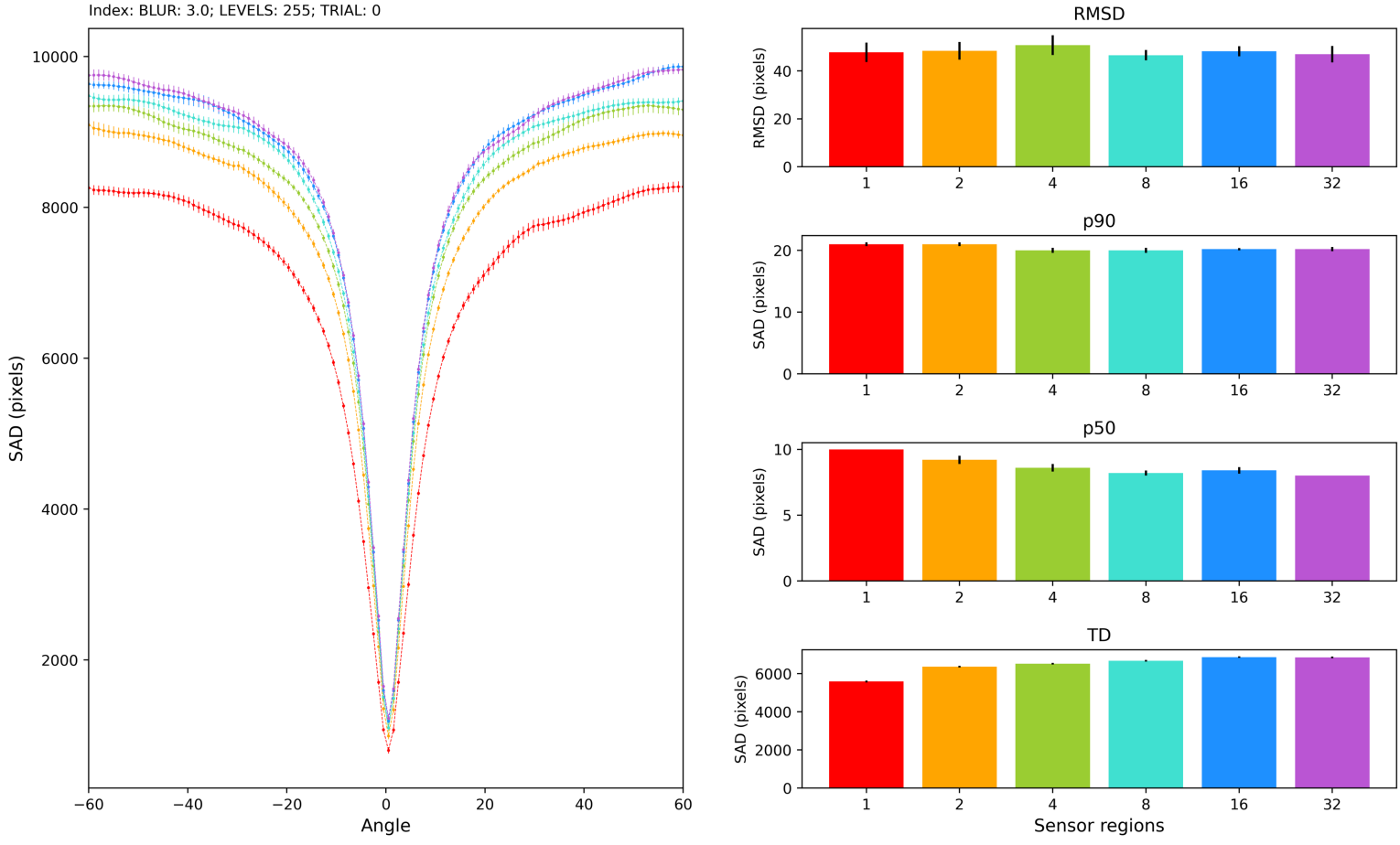
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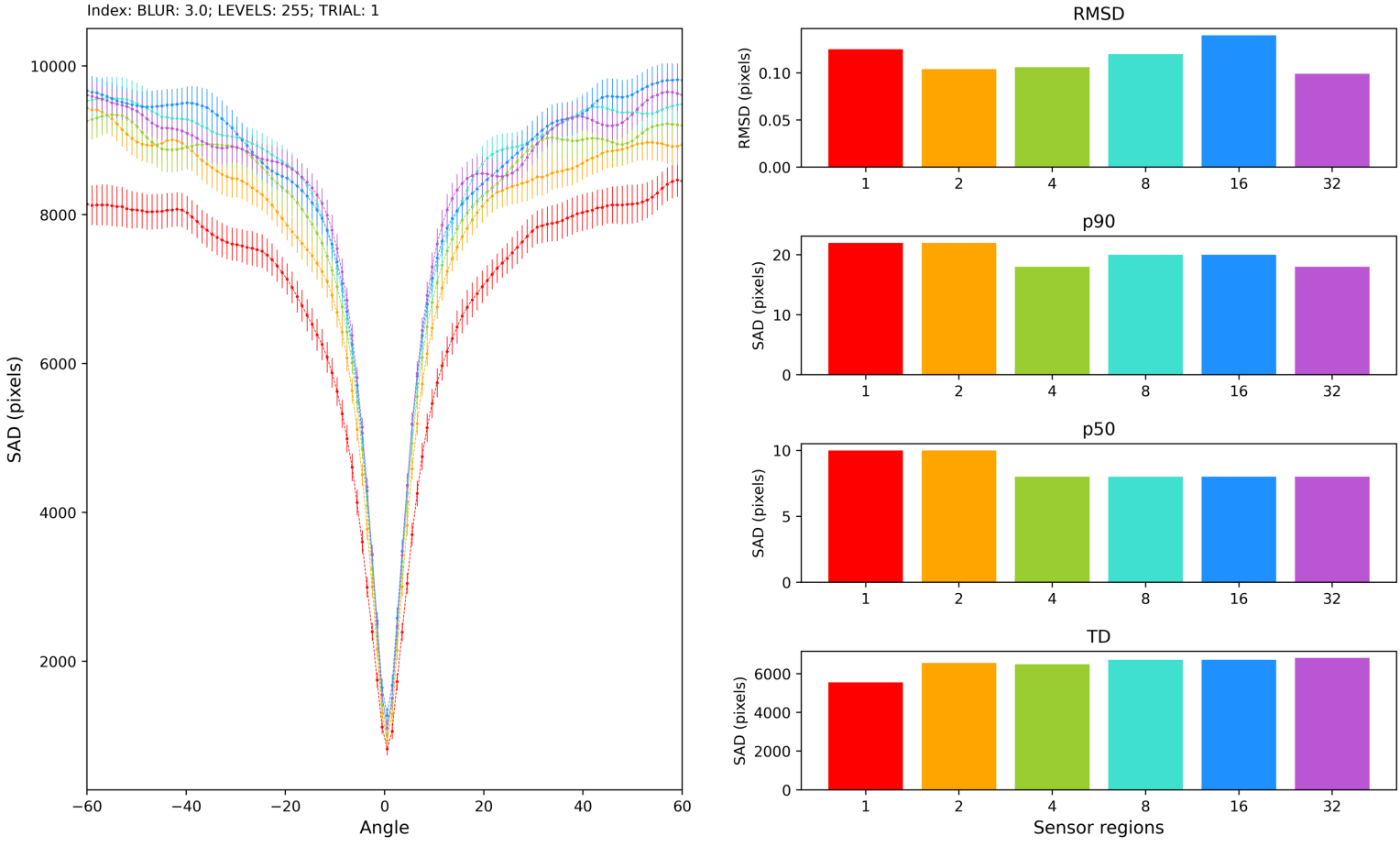
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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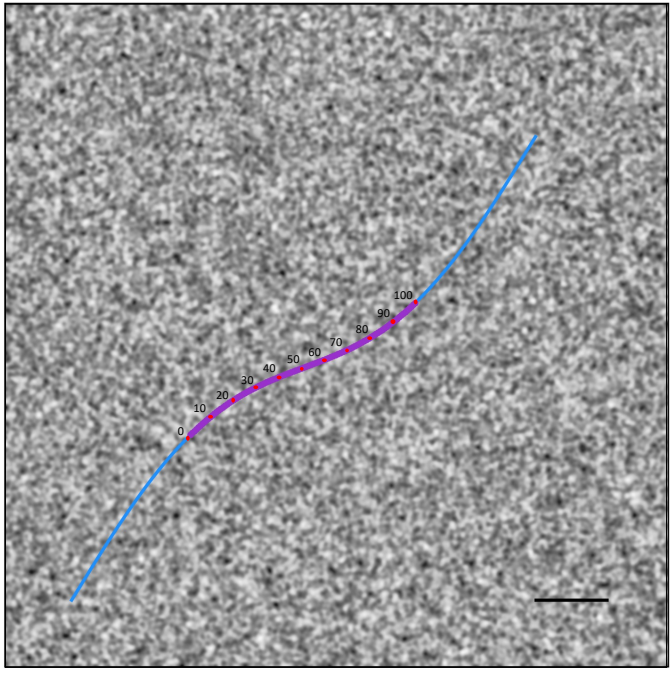
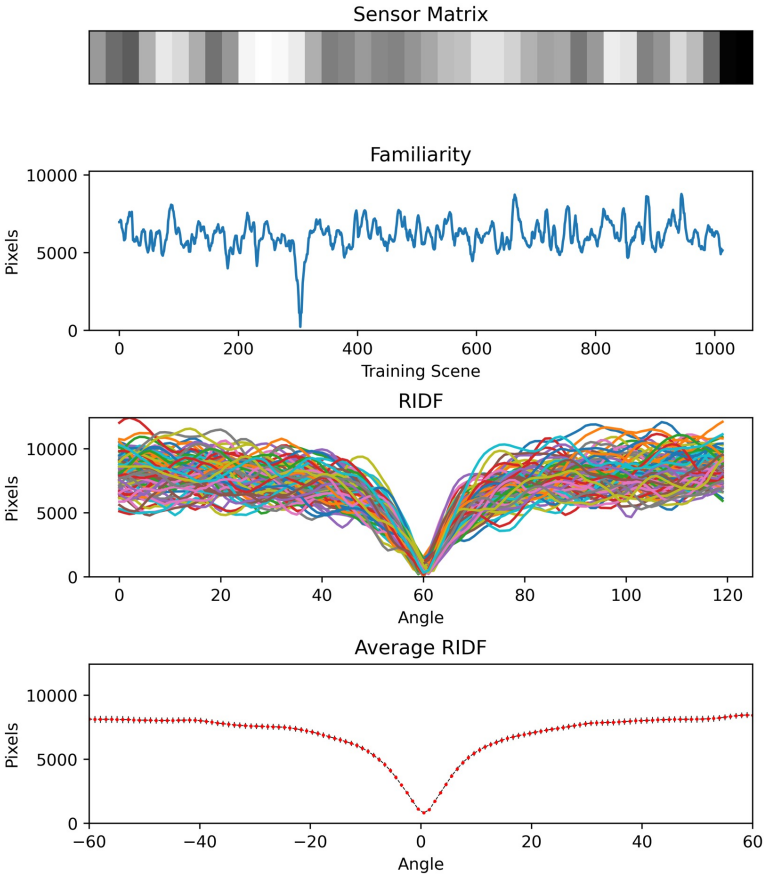
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

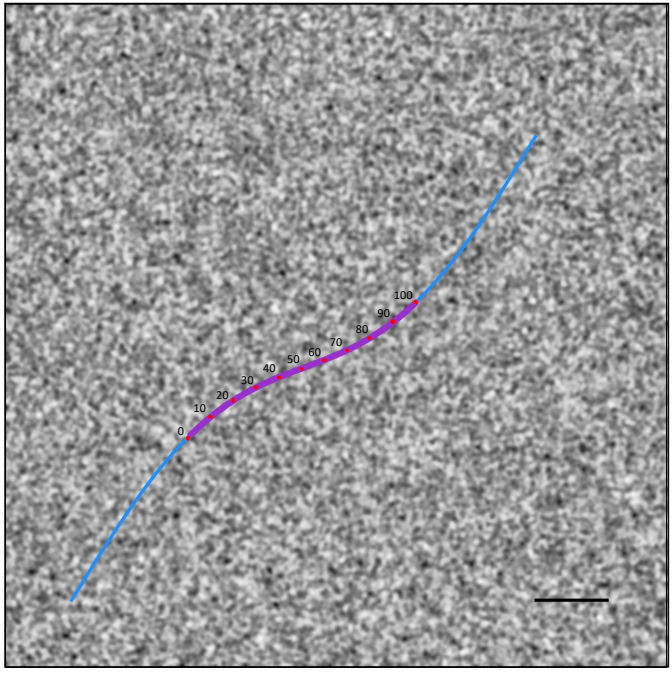


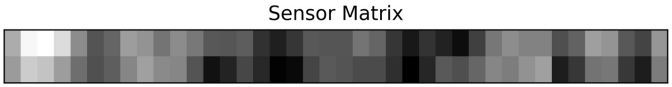


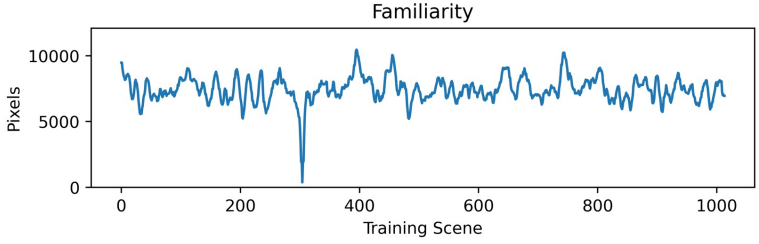
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

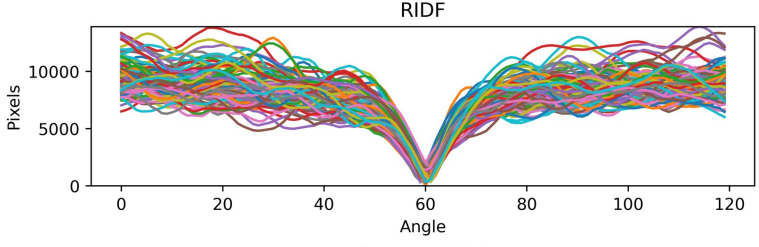
Navigation stats: RMSD error: 50.13; RMSD/dist: 0.125; TD: 5550; p90: 22; p50: 10; complete: 0

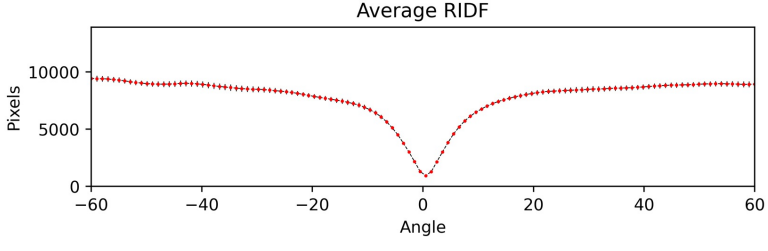
100%







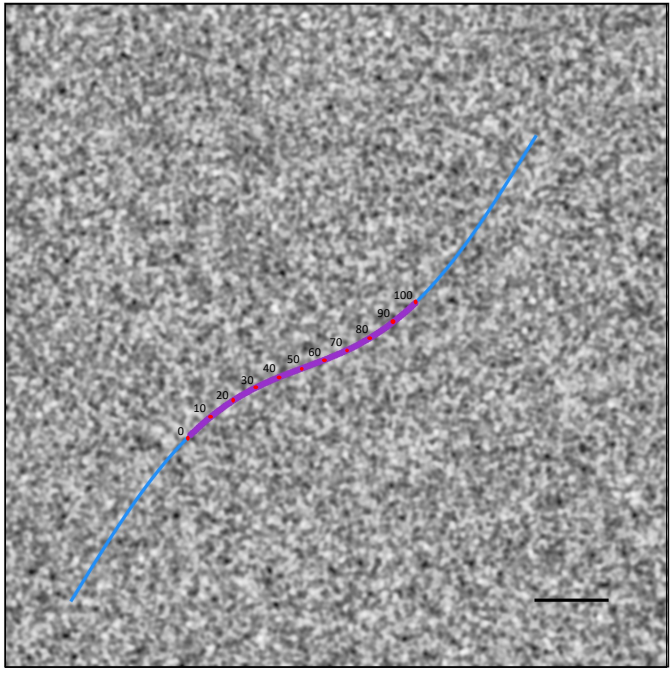


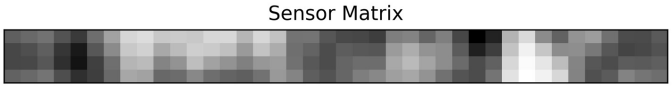


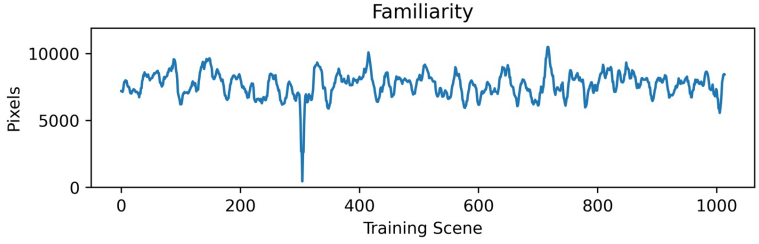
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

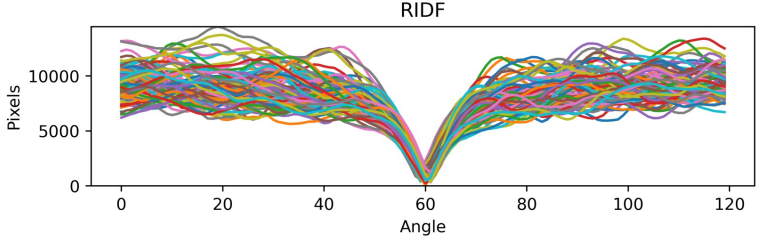
Navigation stats: RMSD error: 41.62; RMSD/dist: 0.104; TD: 6553; p90: 22; p50: 10; complete: 0

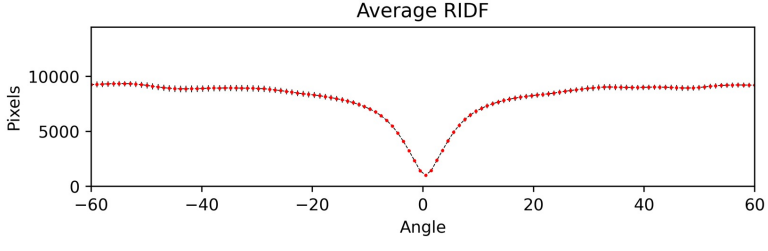
100%







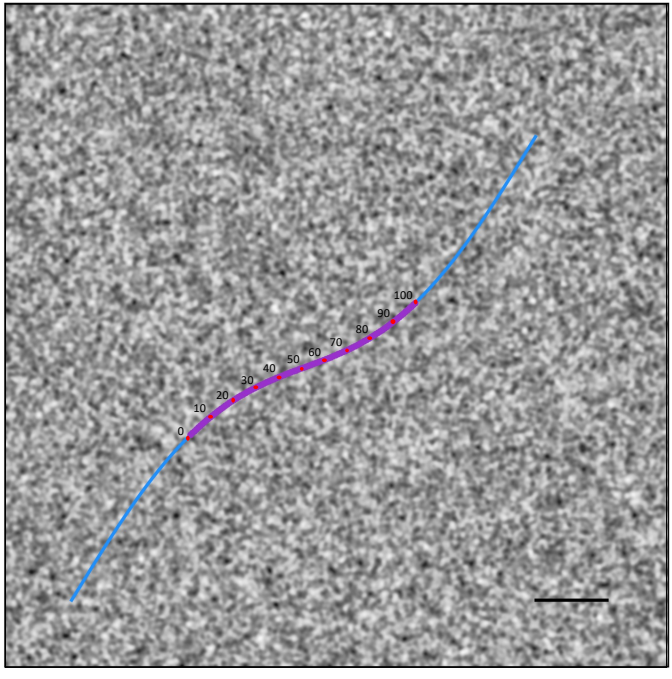


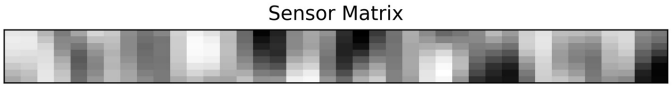


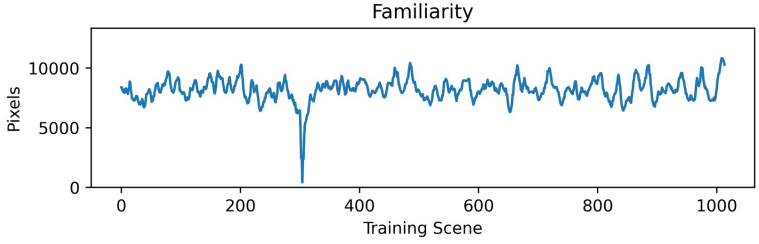
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

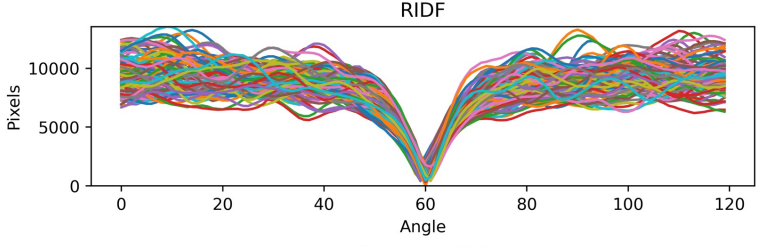
Navigation stats: RMSD error: 42.58; RMSD/dist: 0.106; TD: 6494; p90: 18; p50: 8; complete: 0

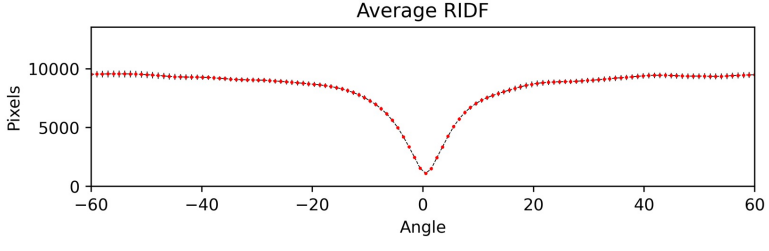
100%







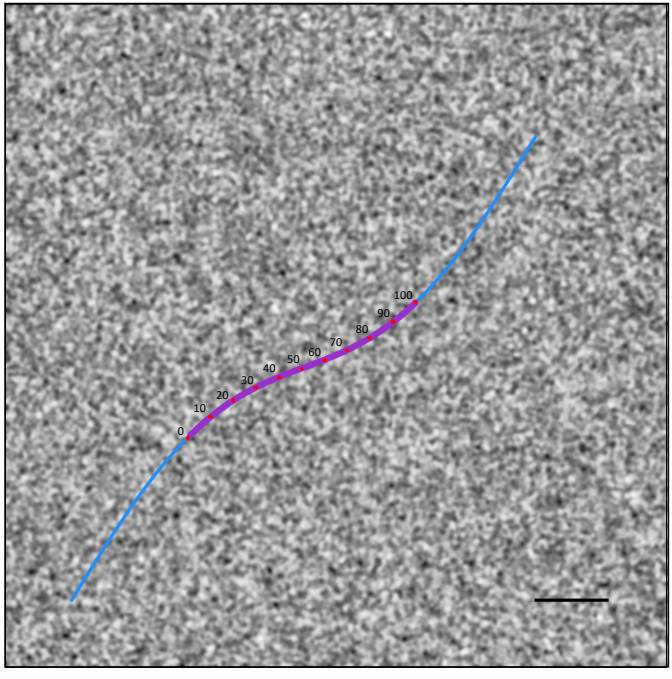


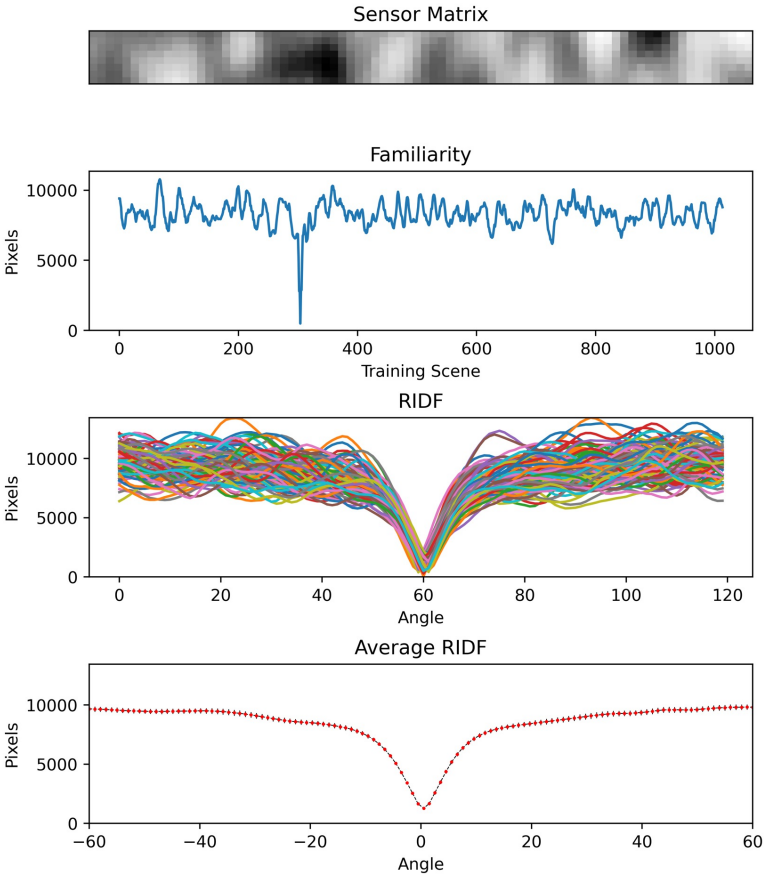


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 47.98; RMSD/dist: 0.120; TD: 6718; p90: 20; p50: 8; complete: 0

100%

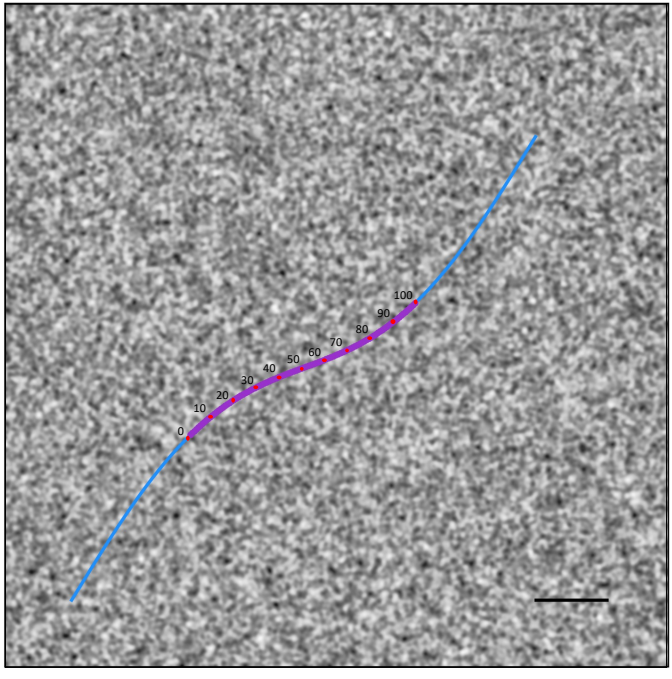


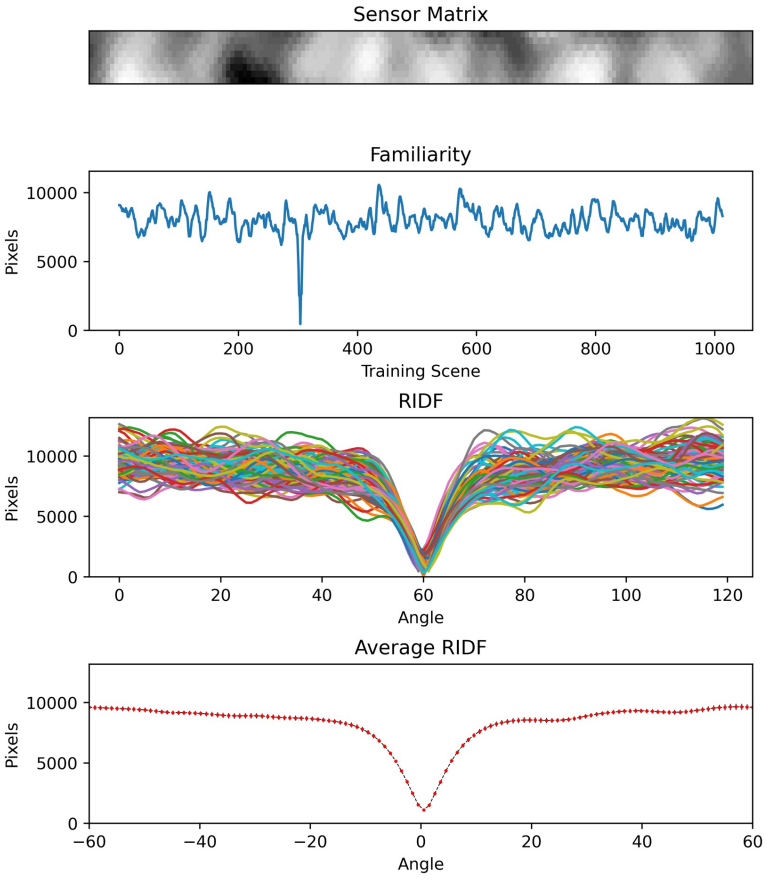


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 56.20; RMSD/dist: 0.140; TD: 6723; p90: 20; p50: 8; complete: 0

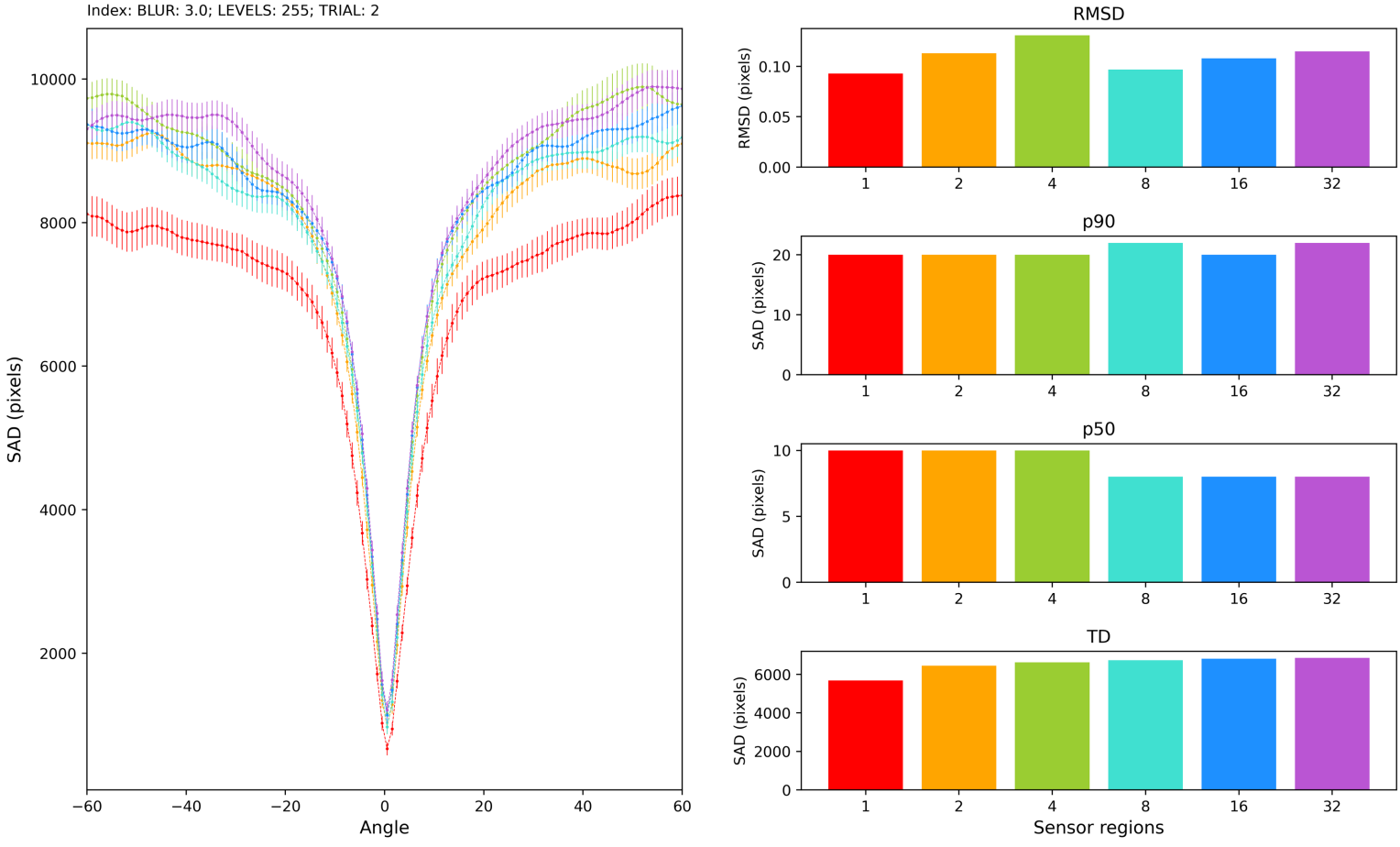
100%



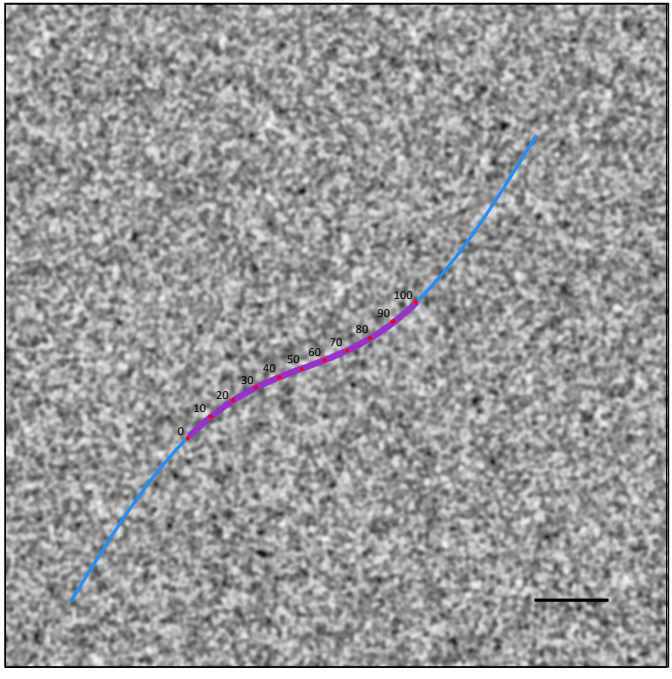


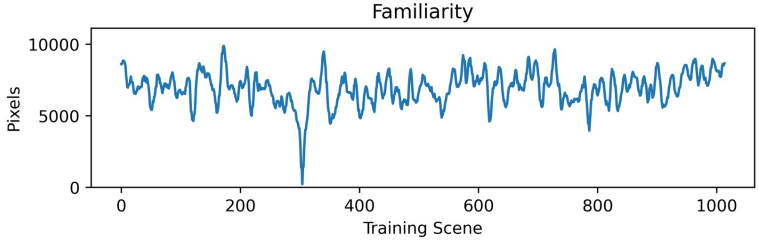
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

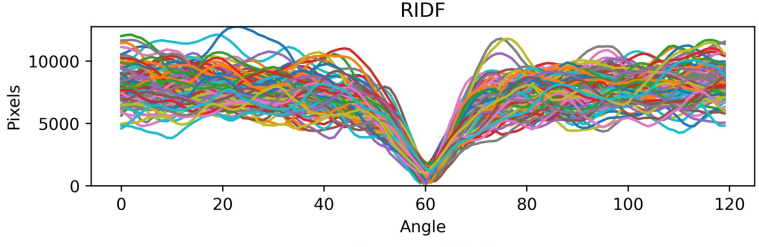
Navigation stats: RMSD error: 39.70; RMSD/dist: 0.099; TD: 6813; p90: 18; p50: 8; complete: 0

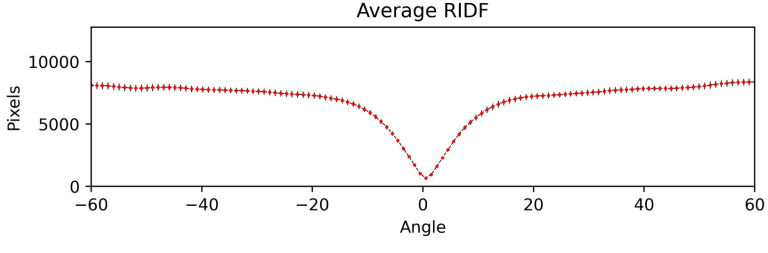

Index: BLUR: 3.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%





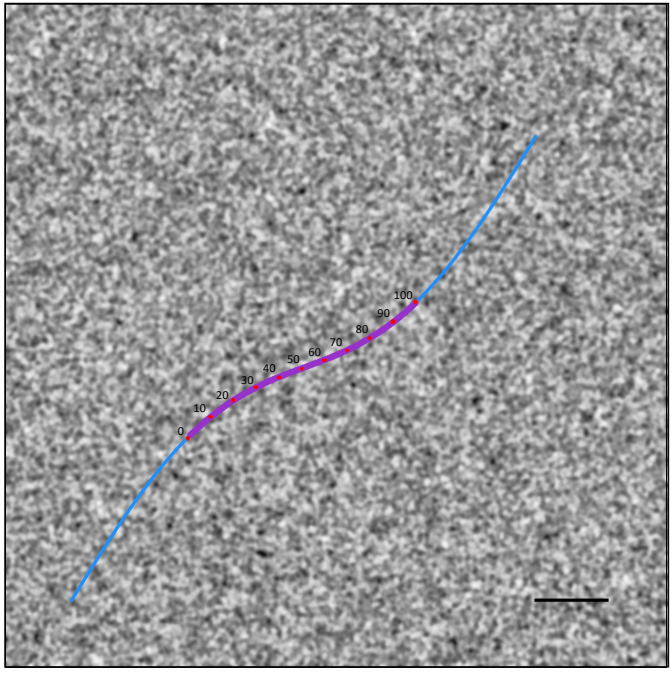


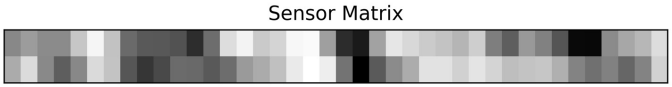


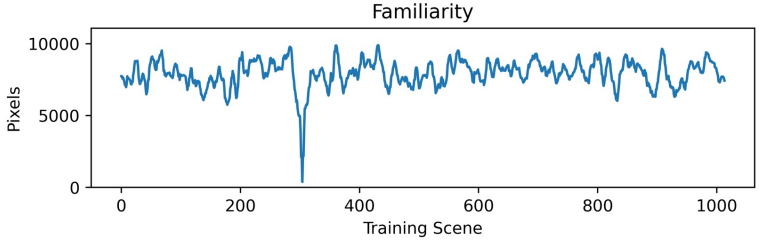
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

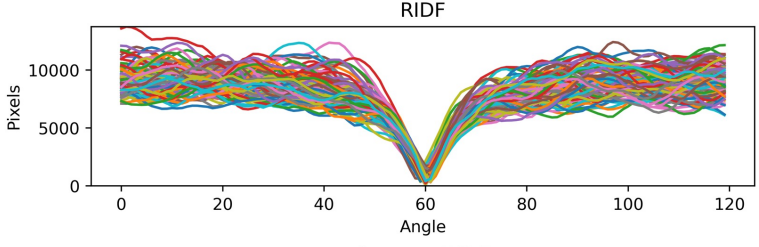
Navigation stats: RMSD error: 37.07; RMSD/dist: 0.093; TD: 5688; p90: 20; p50: 10; complete: 0

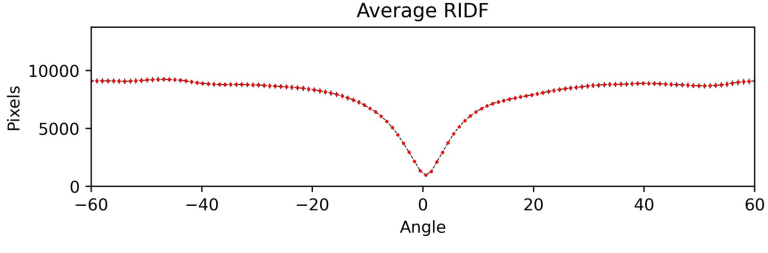
100%







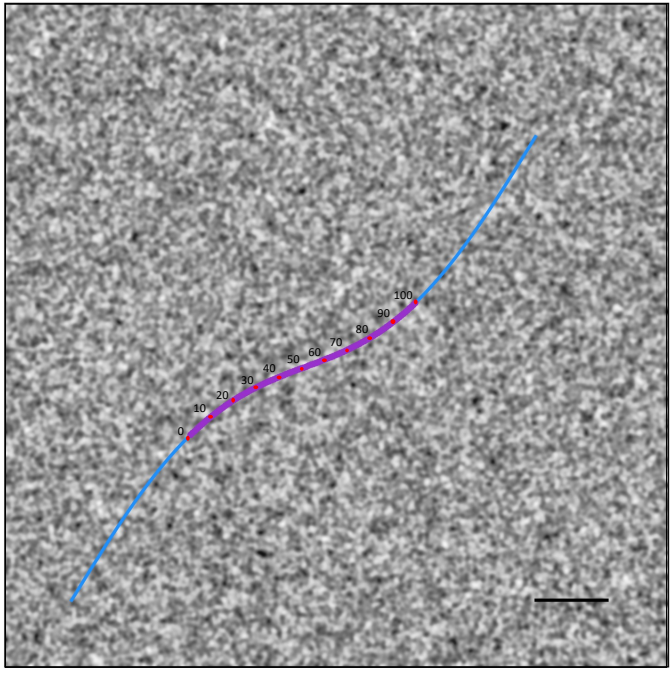


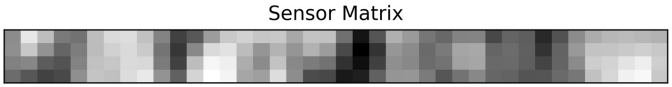


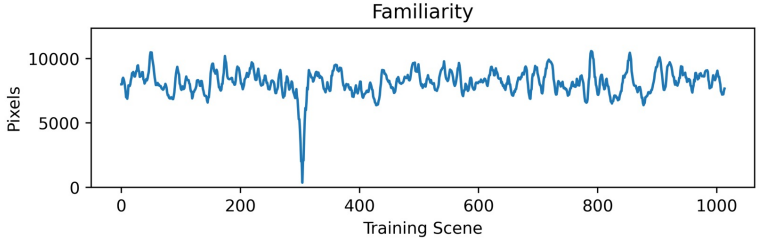
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

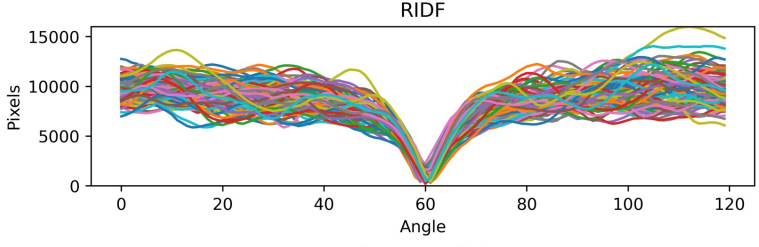
Navigation stats: RMSD error: 45.29; RMSD/dist: 0.113; TD: 6456; p90: 20; p50: 10; complete: 0

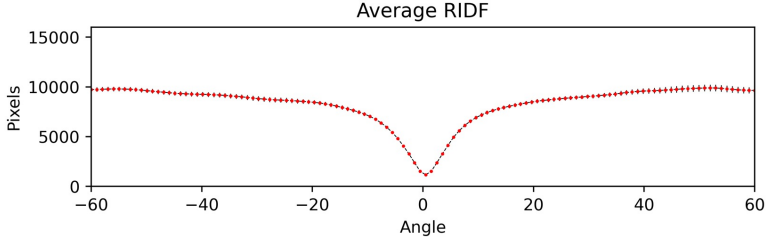
100%







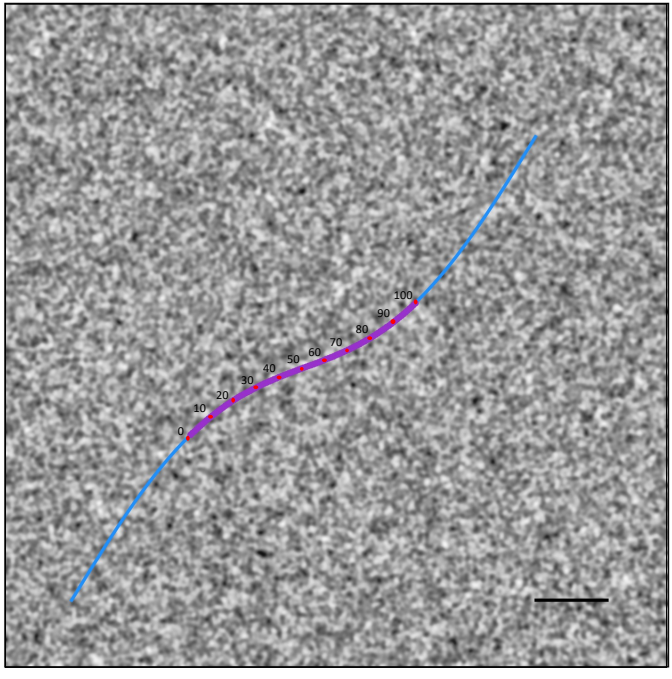


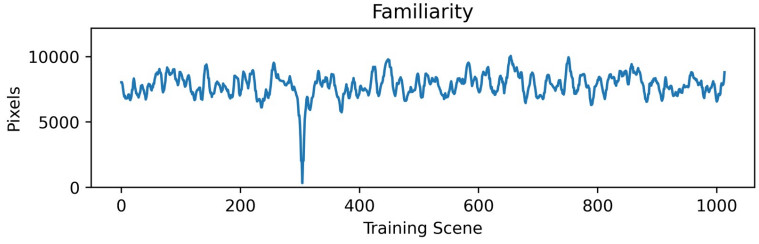


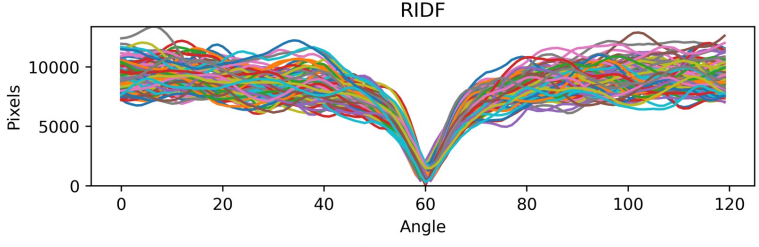
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

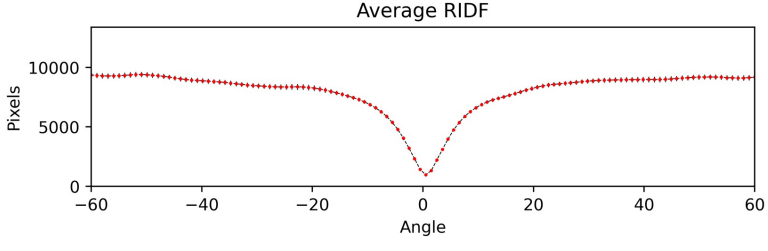
Navigation stats: RMSD error: 52.40; RMSD/dist: 0.131; TD: 6629; p90: 20; p50: 10; complete: 0

100%





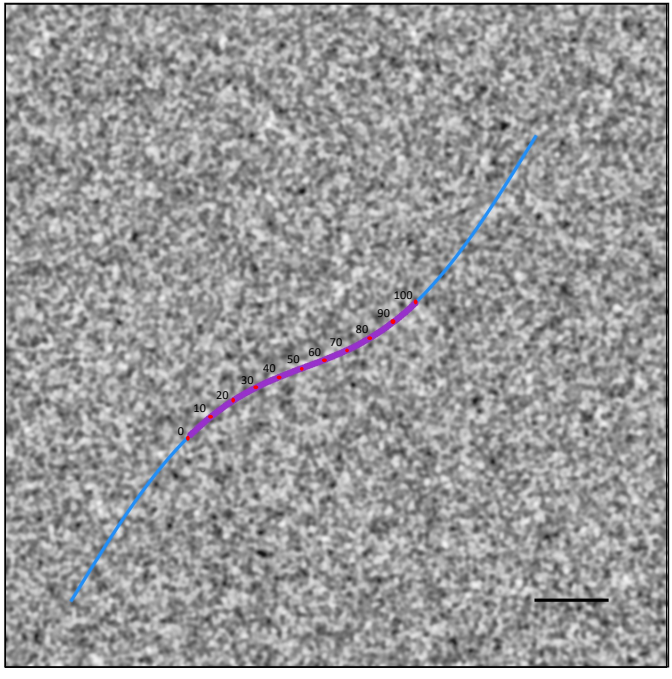


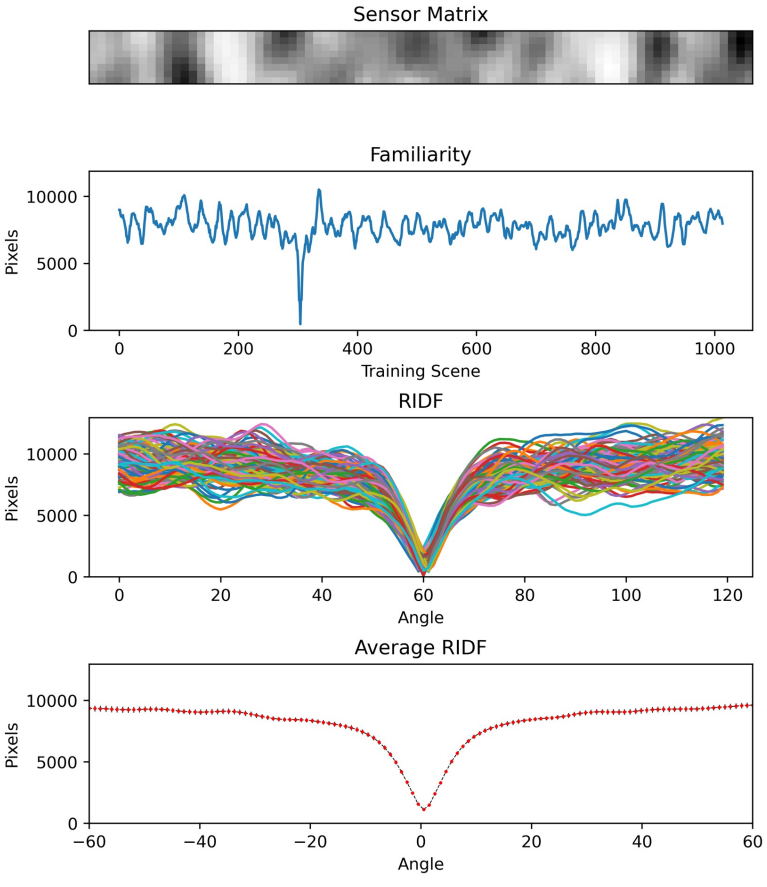


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 38.61; RMSD/dist: 0.097; TD: 6737; p90: 22; p50: 8; complete: 0

100%

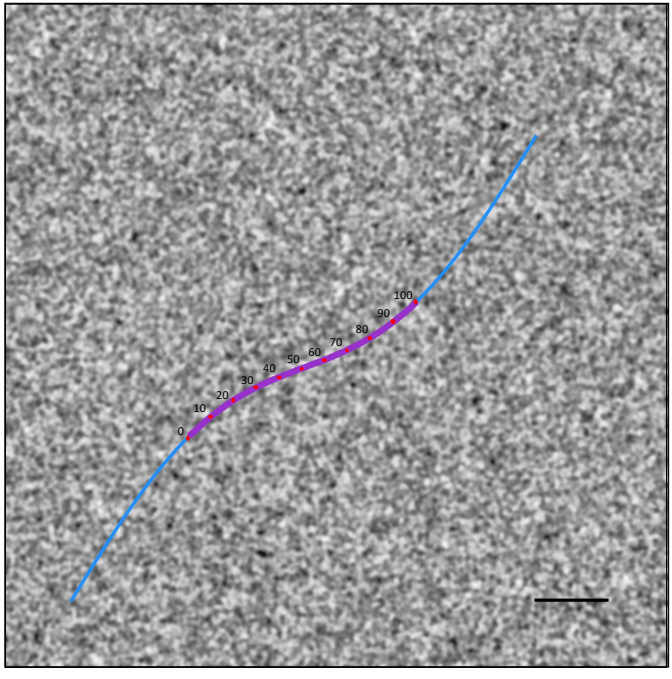


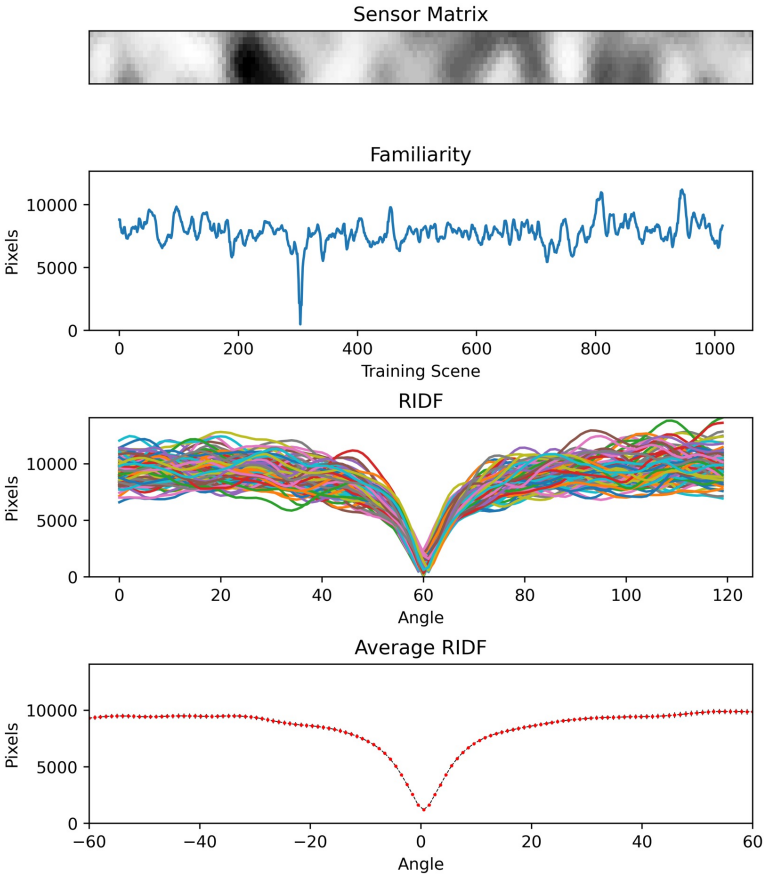


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 43.31; RMSD/dist: 0.108; TD: 6817; p90: 20; p50: 8; complete: 0

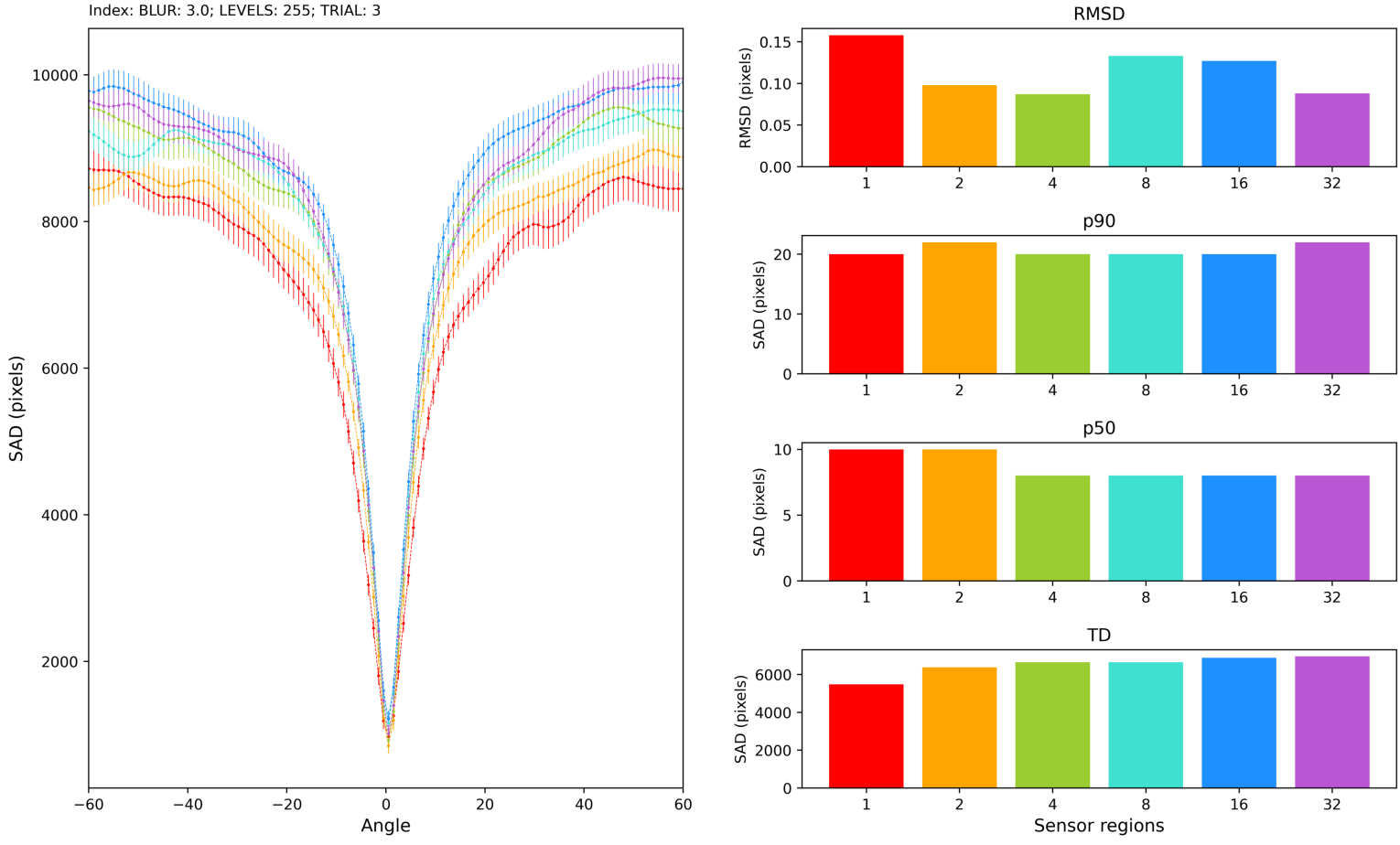
100%



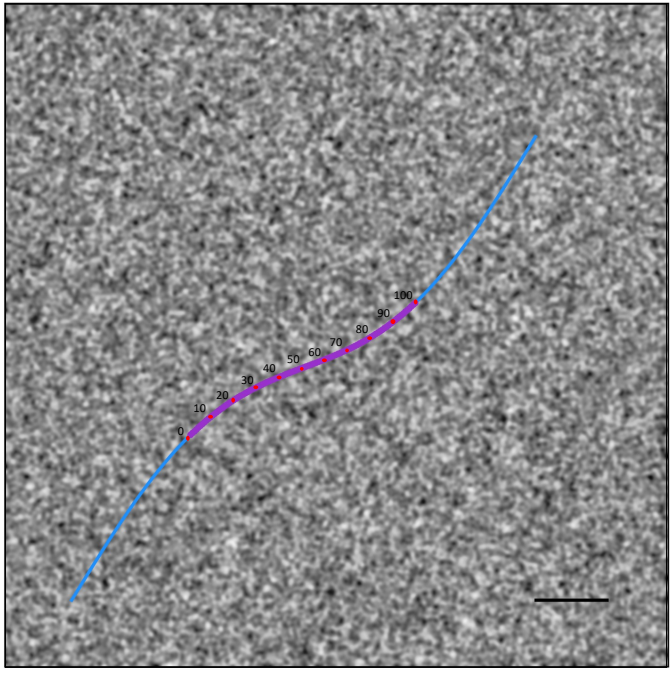


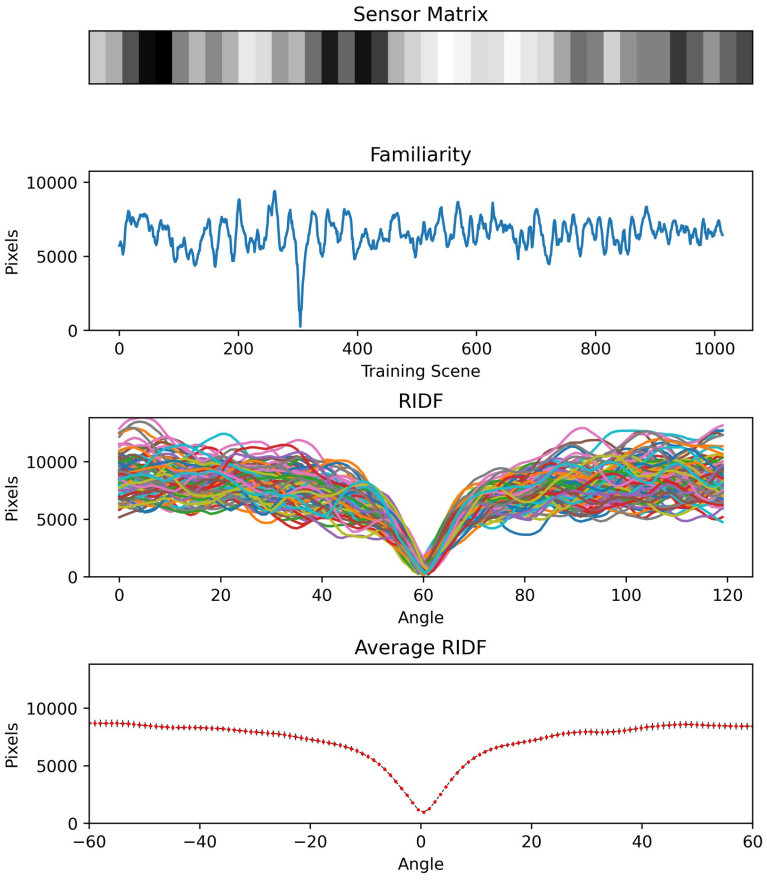
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 46.17; RMSD/dist: 0.115; TD: 6855; p90: 22; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

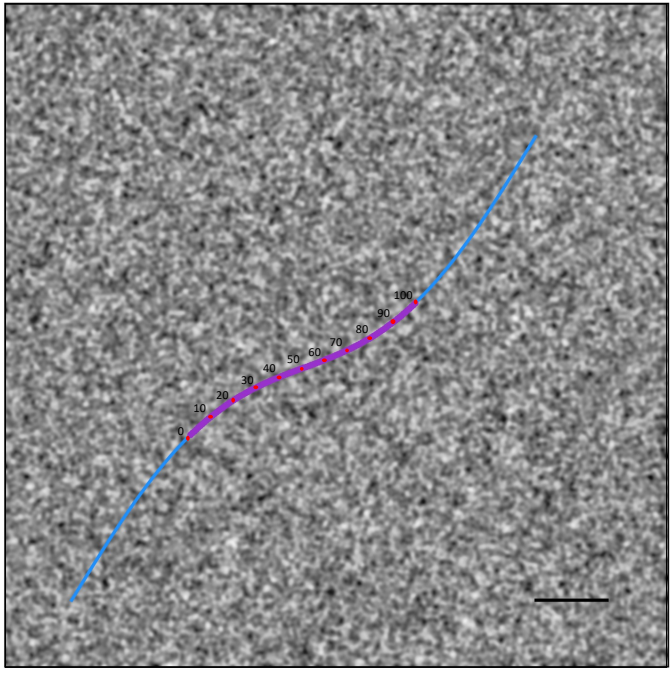


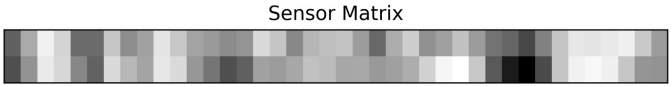


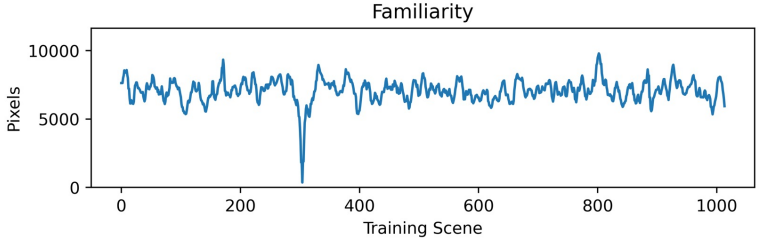
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

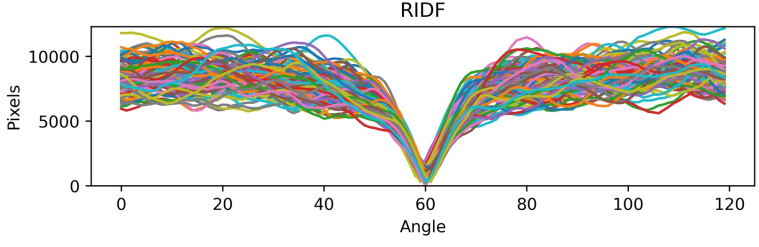
Navigation stats: RMSD error: 63.05; RMSD/dist: 0.158; TD: 5483; p90: 20; p50: 10; complete: 0

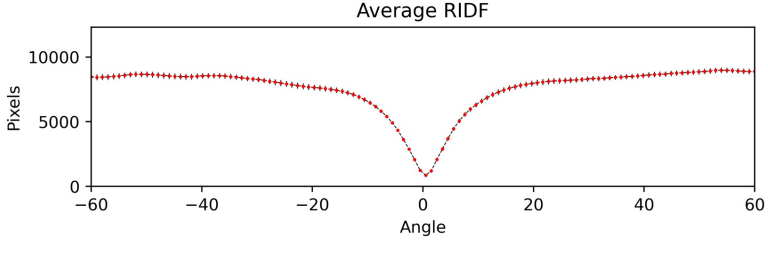
100%







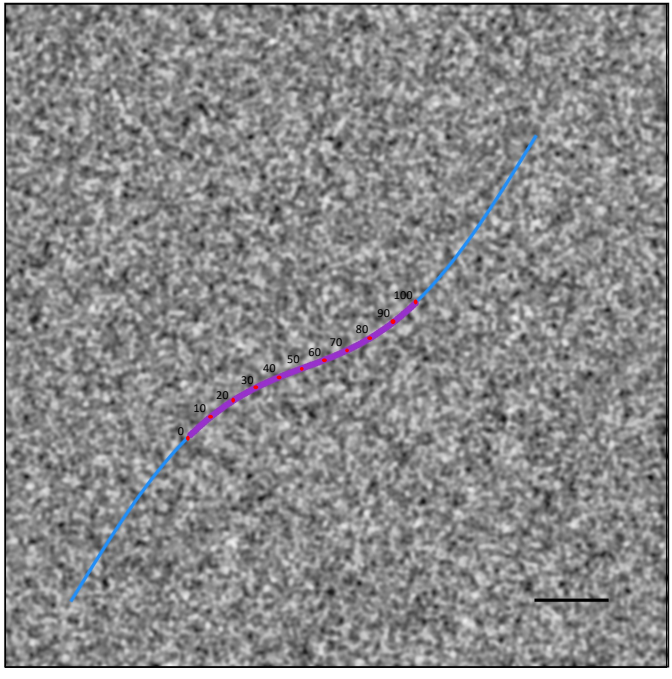


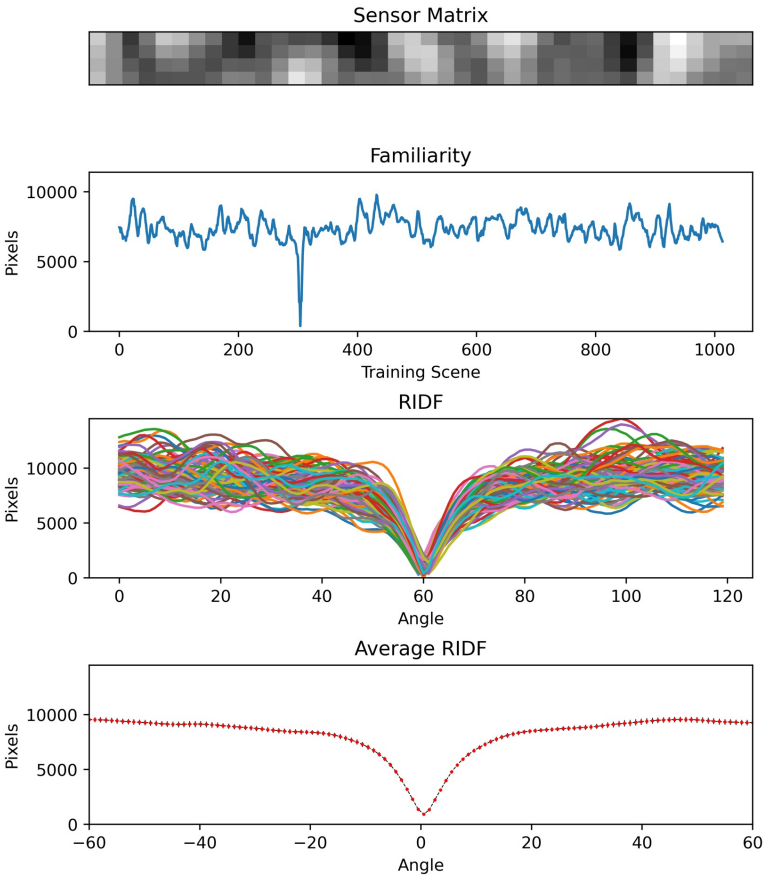


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 39.16; RMSD/dist: 0.098; TD: 6379; p90: 22; p50: 10; complete: 0

100%

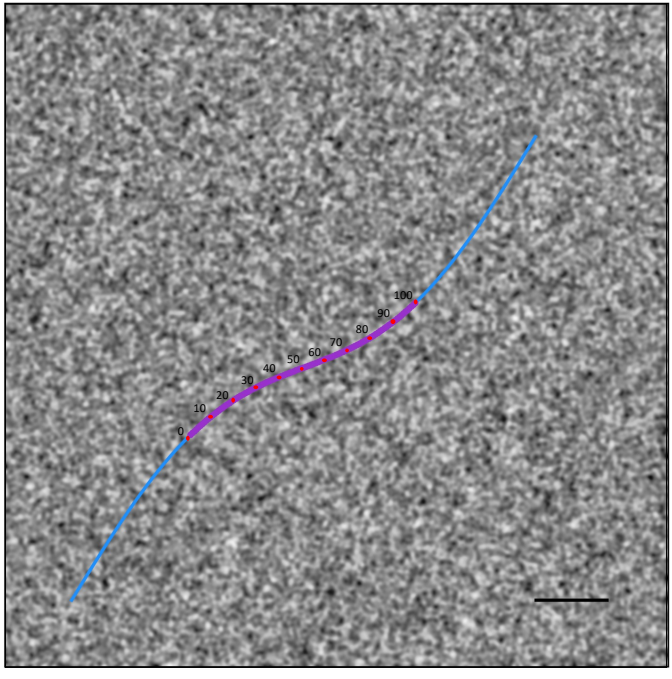


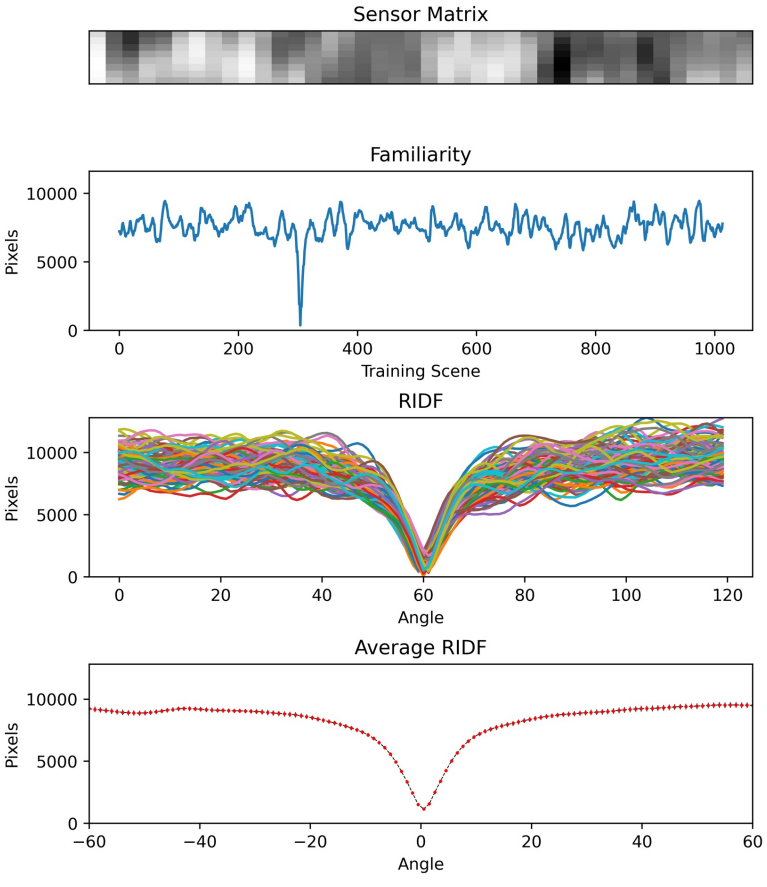


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 34.72; RMSD/dist: 0.087; TD: 6653; p90: 20; p50: 8; complete: 0

100%

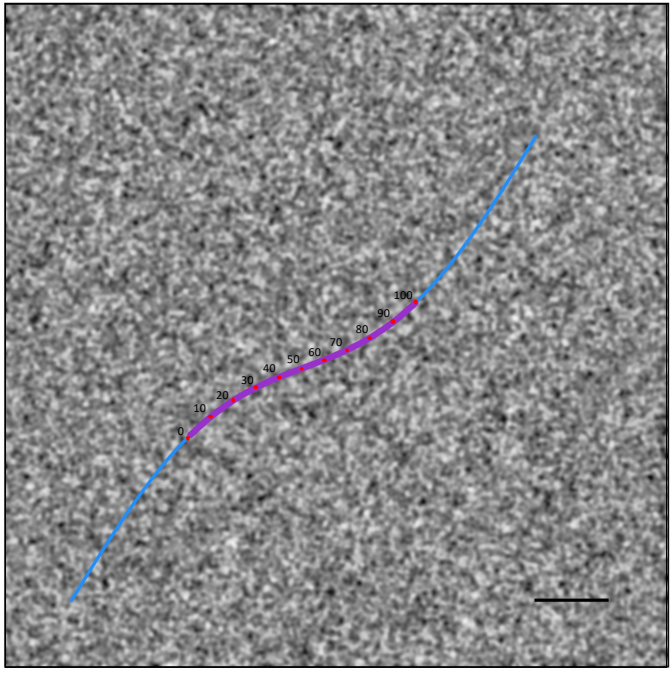


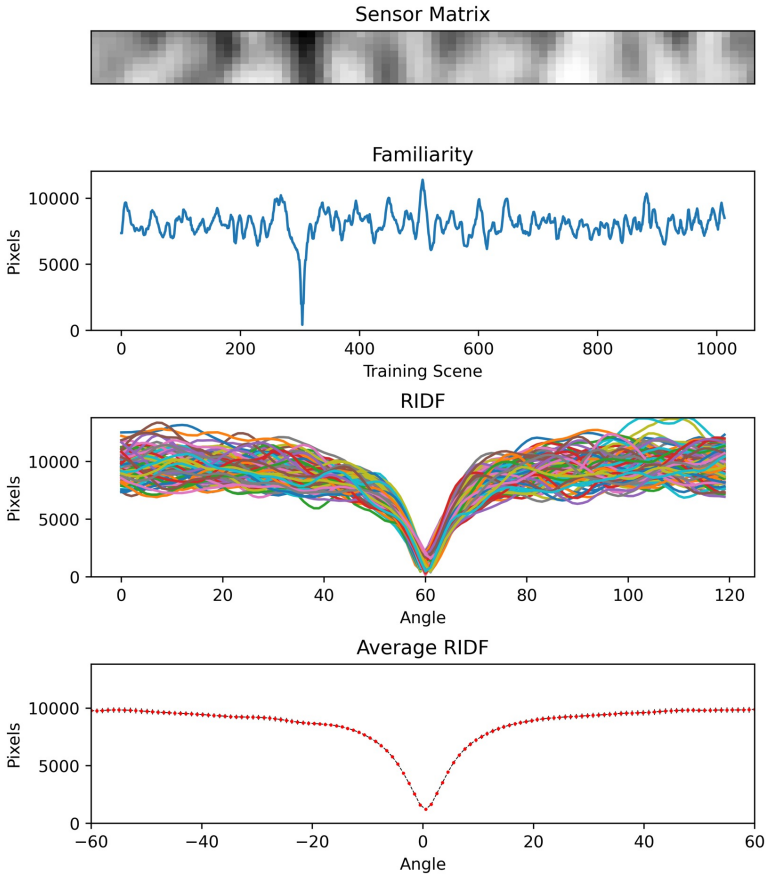


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 53.24; RMSD/dist: 0.133; TD: 6643; p90: 20; p50: 8; complete: 0

100%

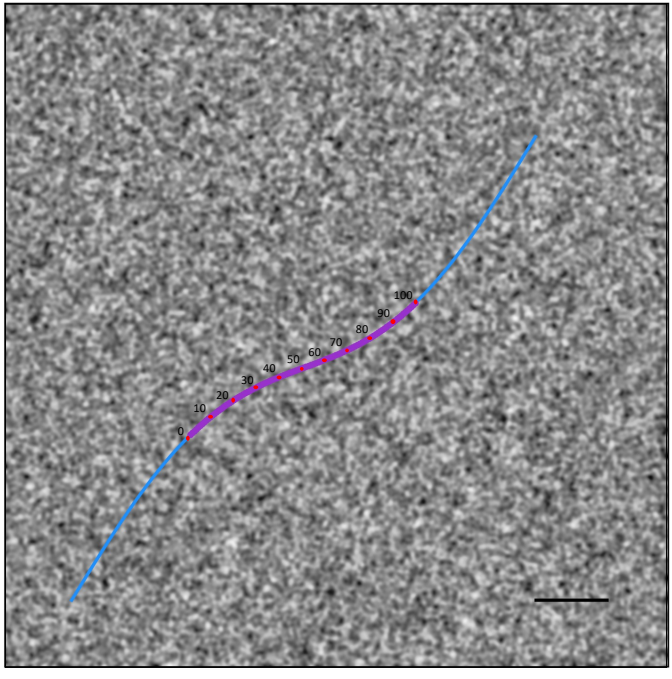


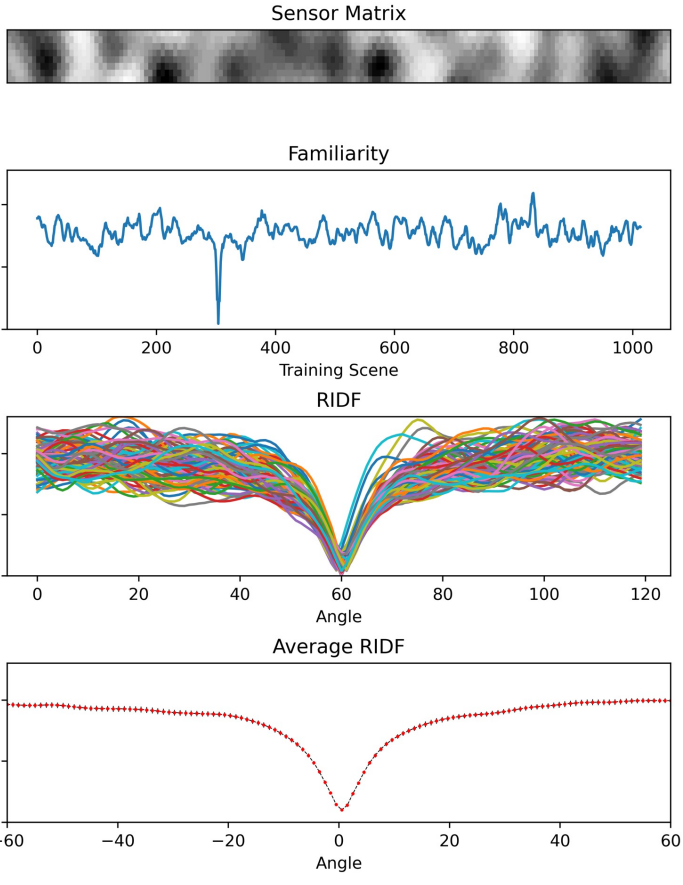


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 50.85; RMSD/dist: 0.127; TD: 6885; p90: 20; p50: 8; complete: 0

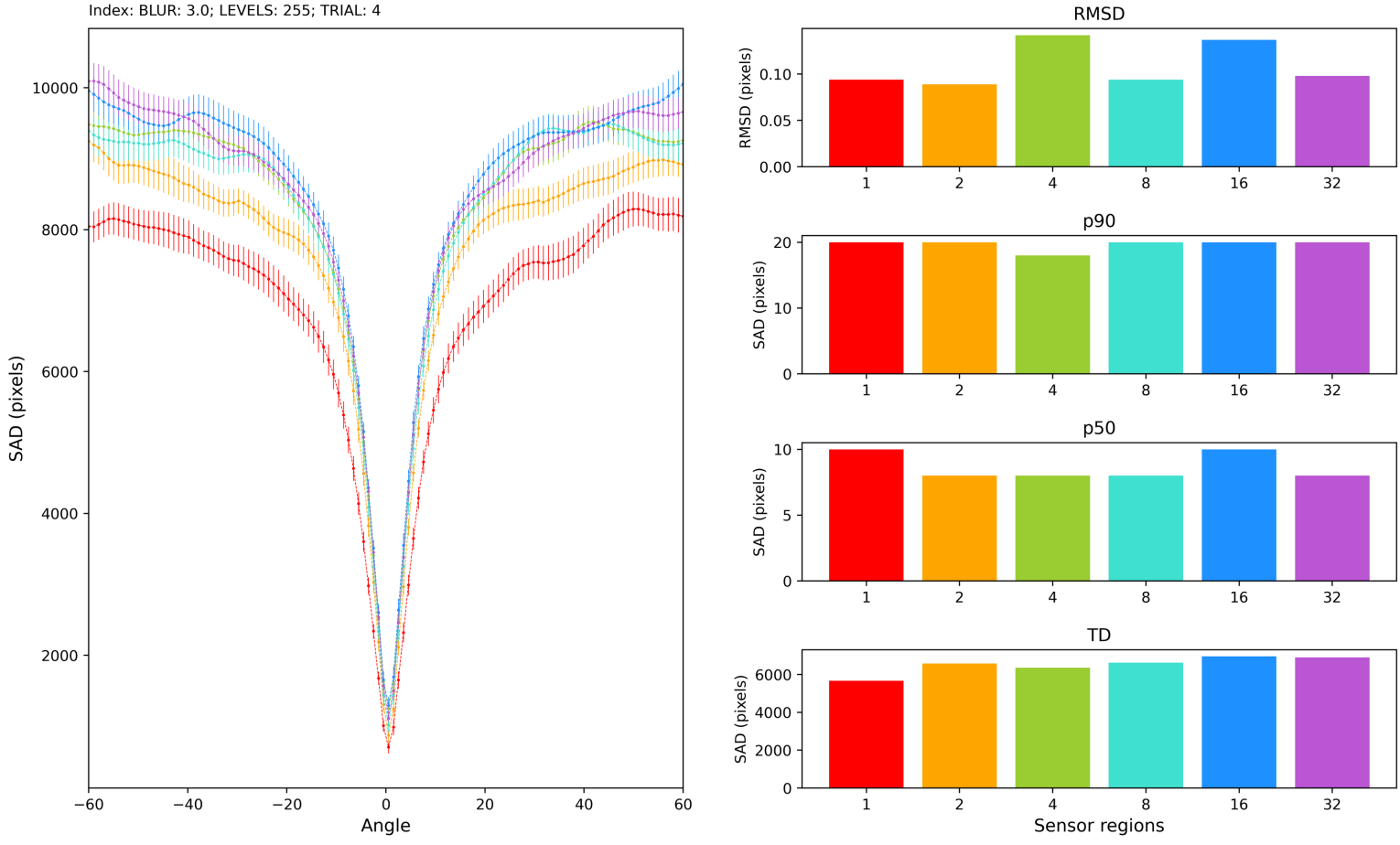
100%



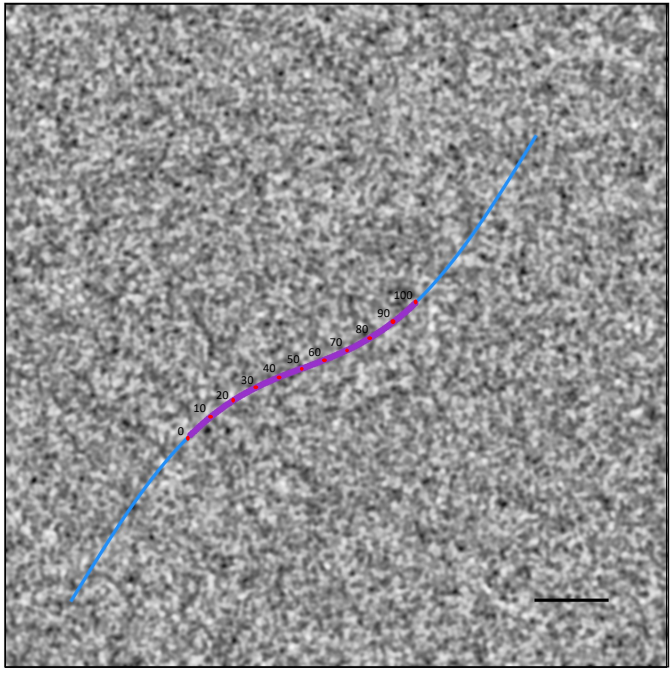


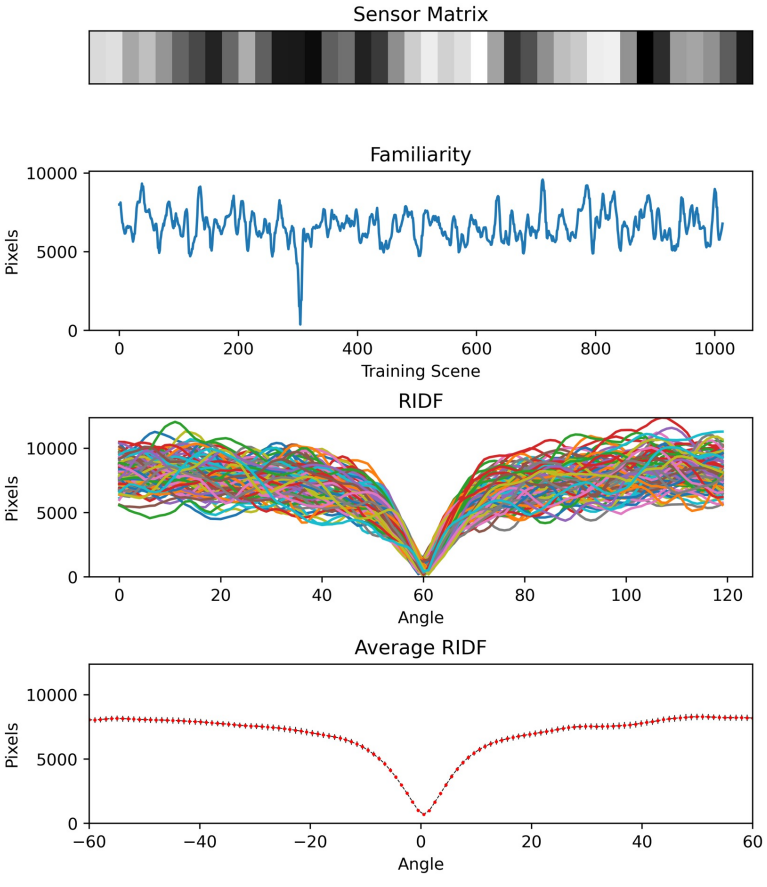
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 35.21; RMSD/dist: 0.088; TD: 6954; p90: 22; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 255; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

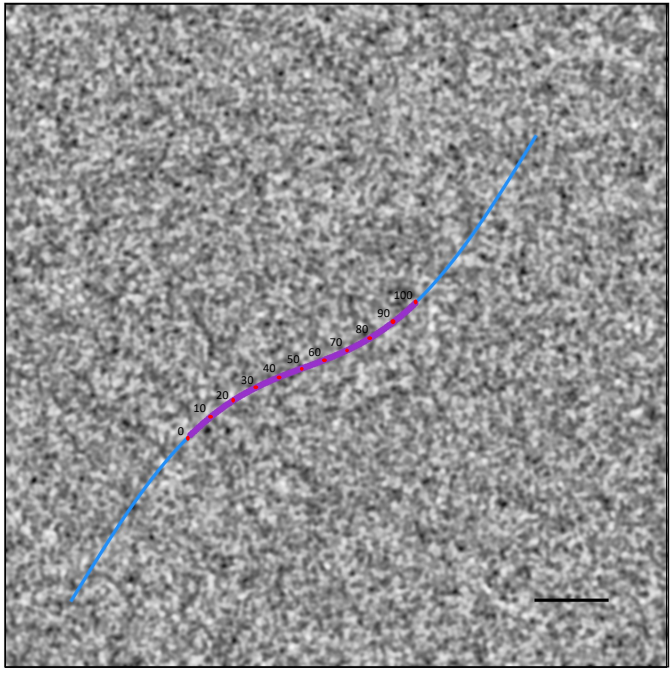


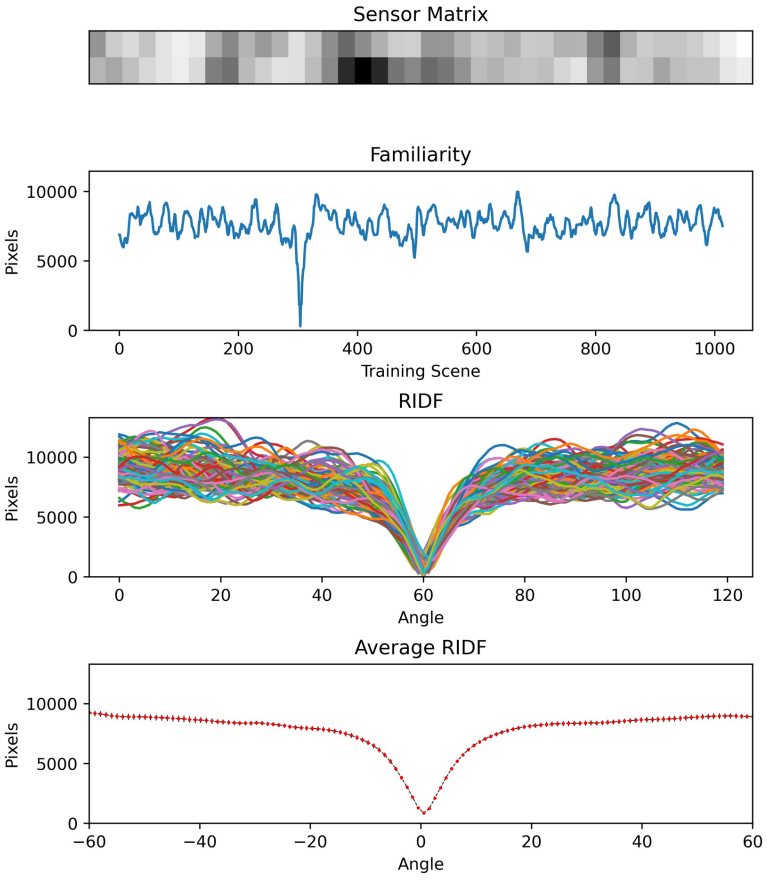


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 37.68; RMSD/dist: 0.094; TD: 5668; p90: 20; p50: 10; complete: 0

100%

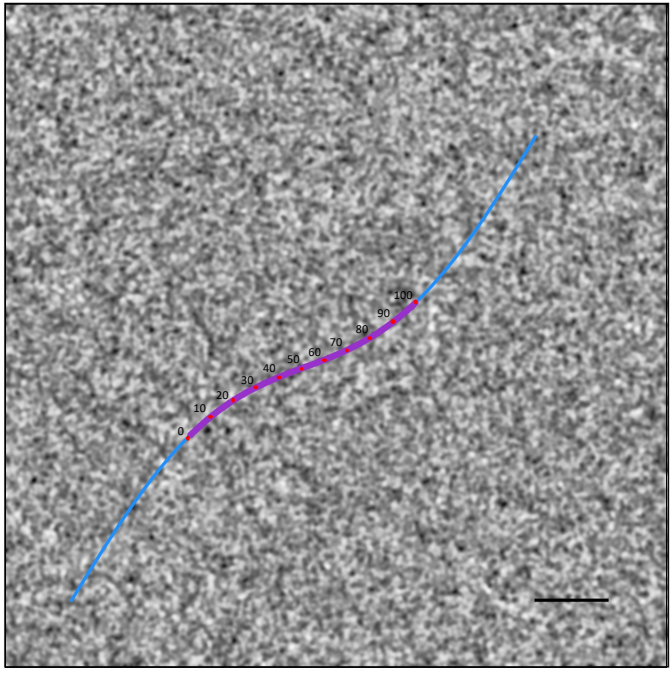


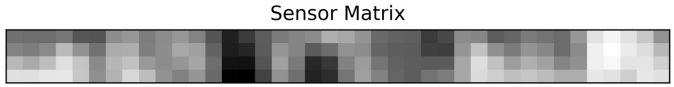


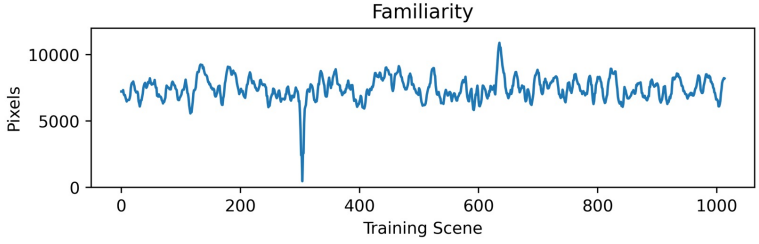
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

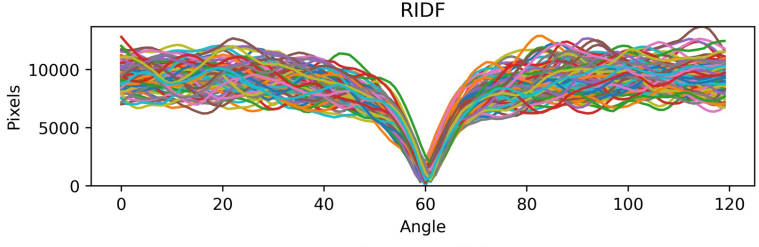
Navigation stats: RMSD error: 35.68; RMSD/dist: 0.089; TD: 6579; p90: 20; p50: 8; complete: 0

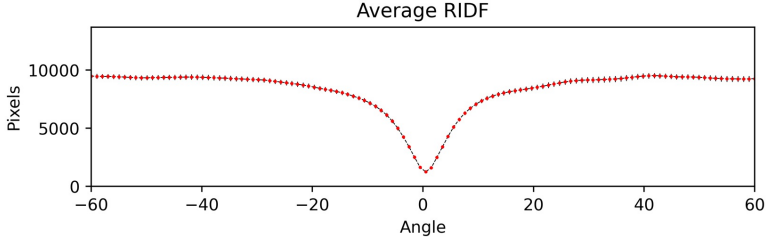
100%







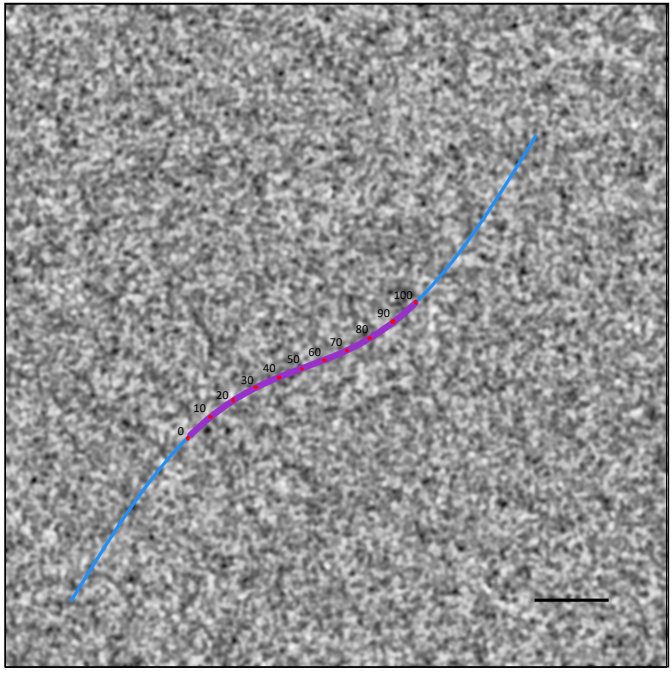


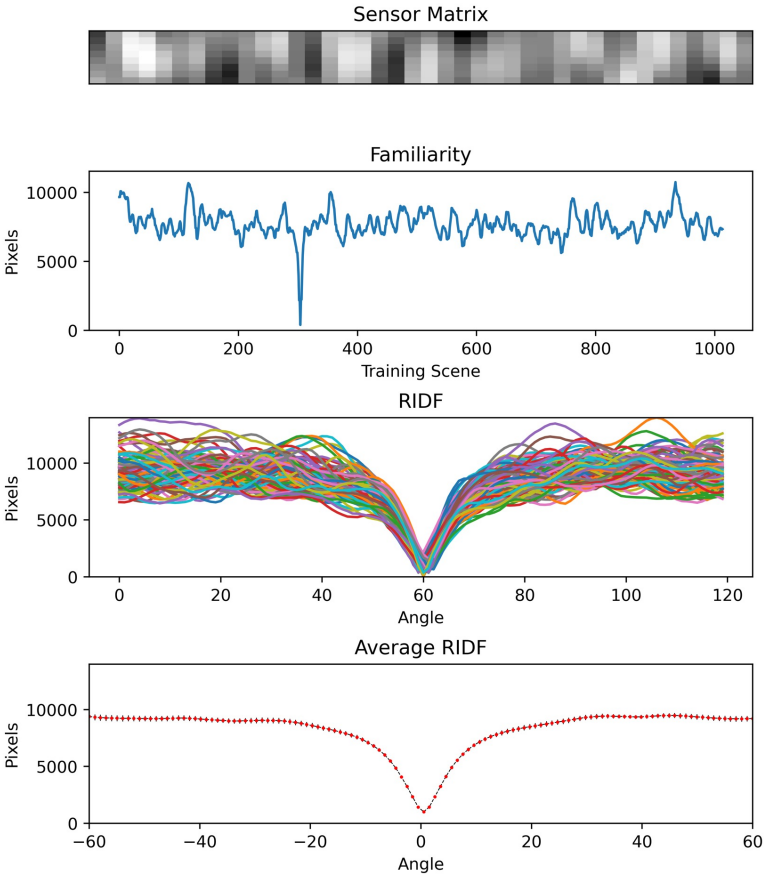


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 56.70; RMSD/dist: 0.142; TD: 6358; p90: 18; p50: 8; complete: 0

100%

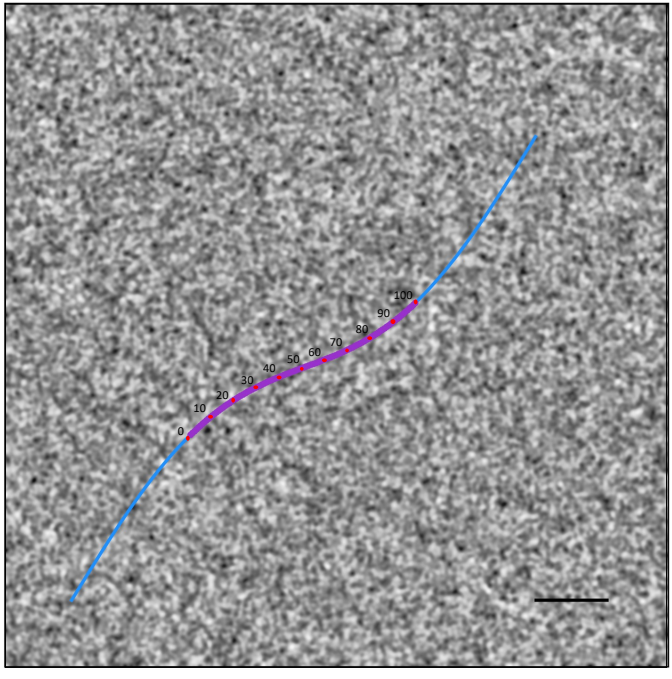


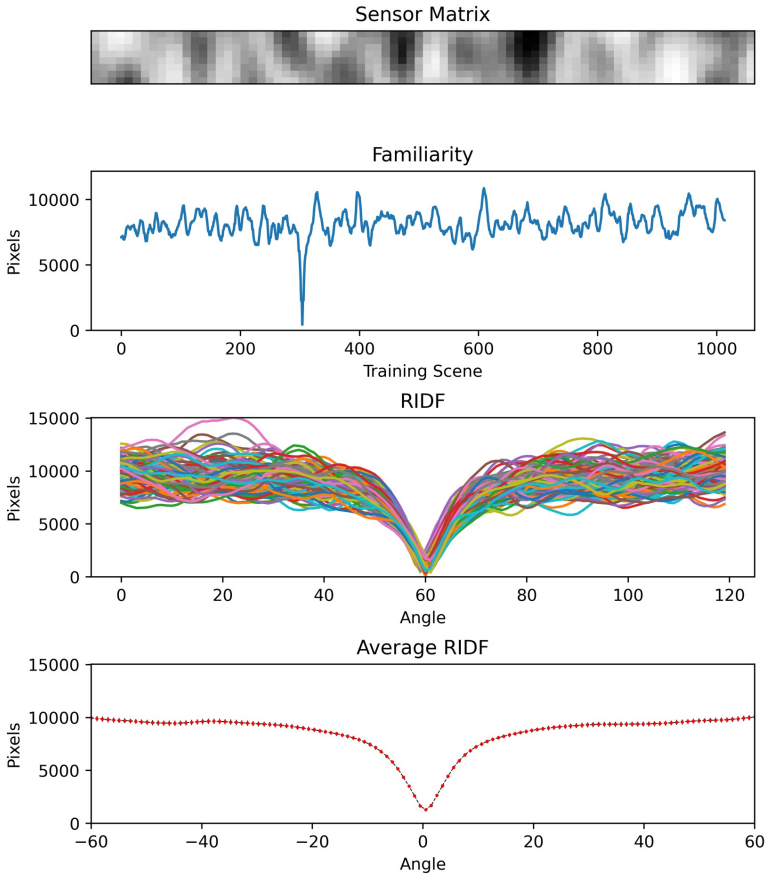


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 37.60; RMSD/dist: 0.094; TD: 6619; p90: 20; p50: 8; complete: 0

100%

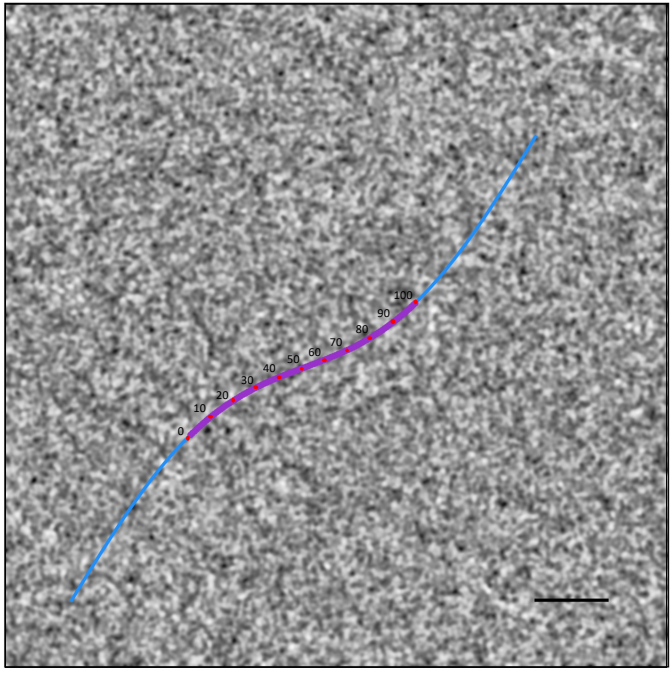


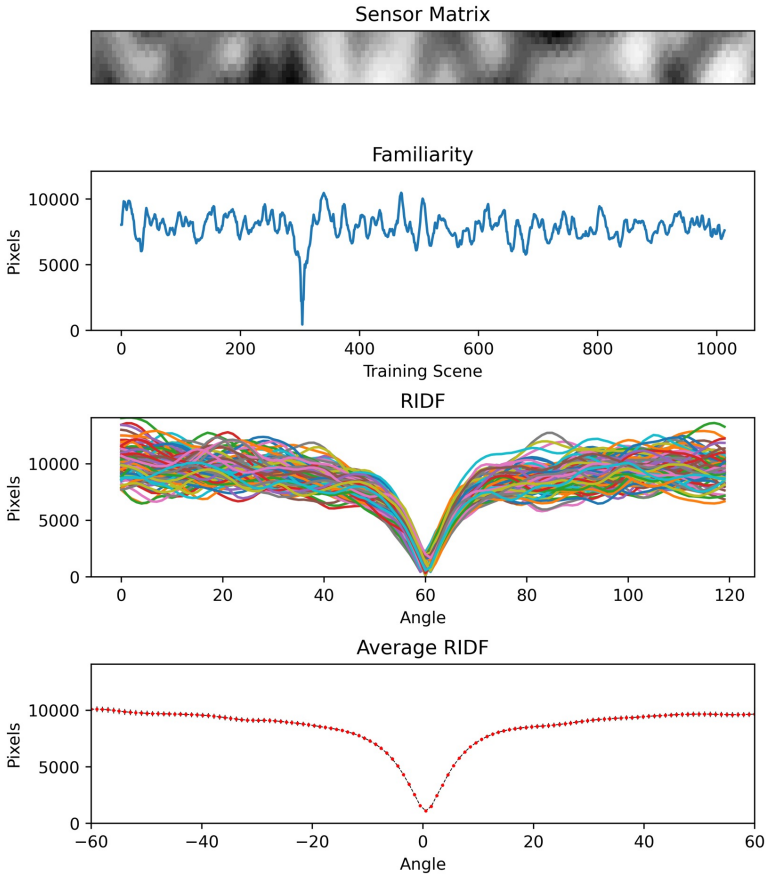


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 54.90; RMSD/dist: 0.137; TD: 6952; p90: 20; p50: 10; complete: 0

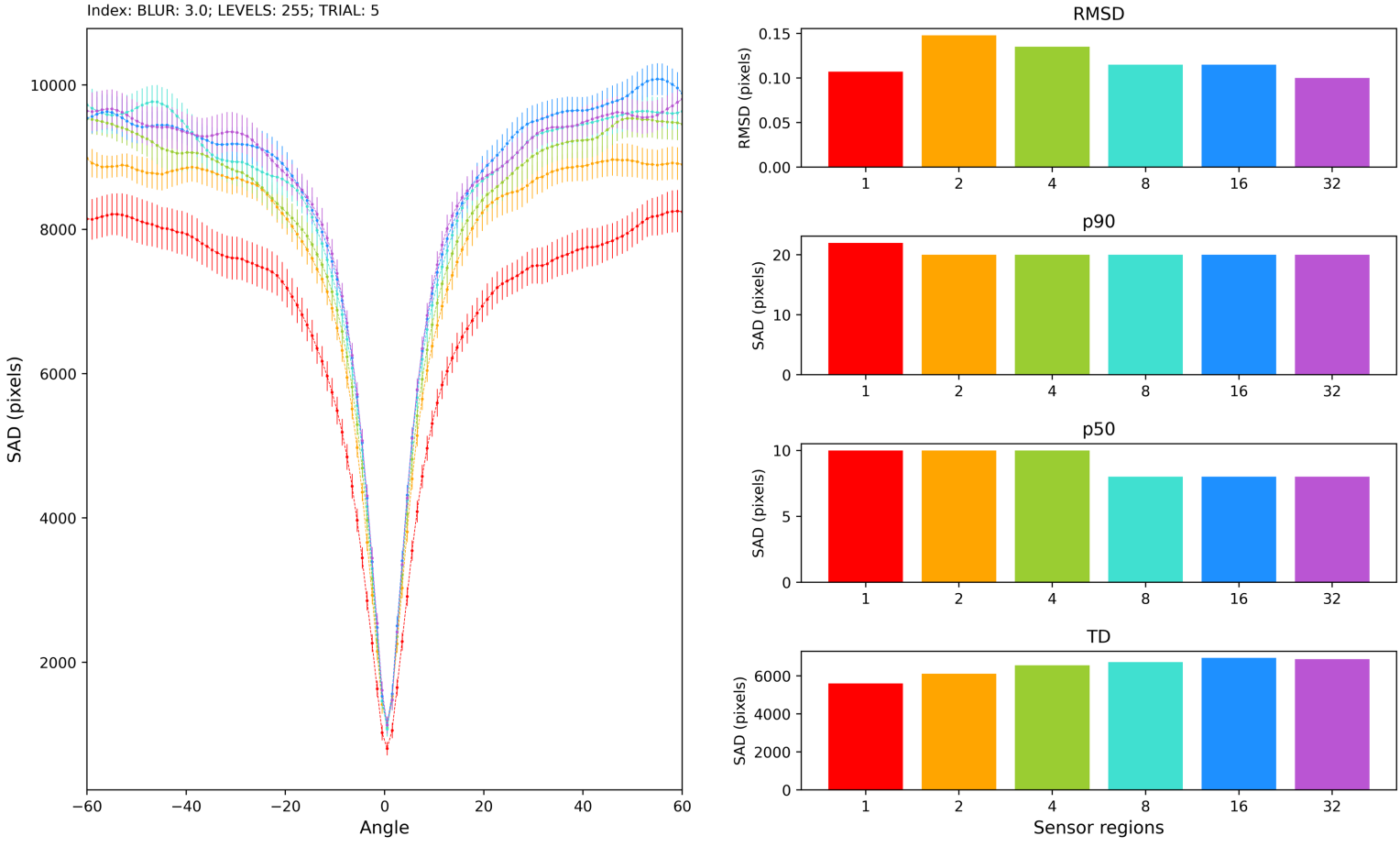
100%



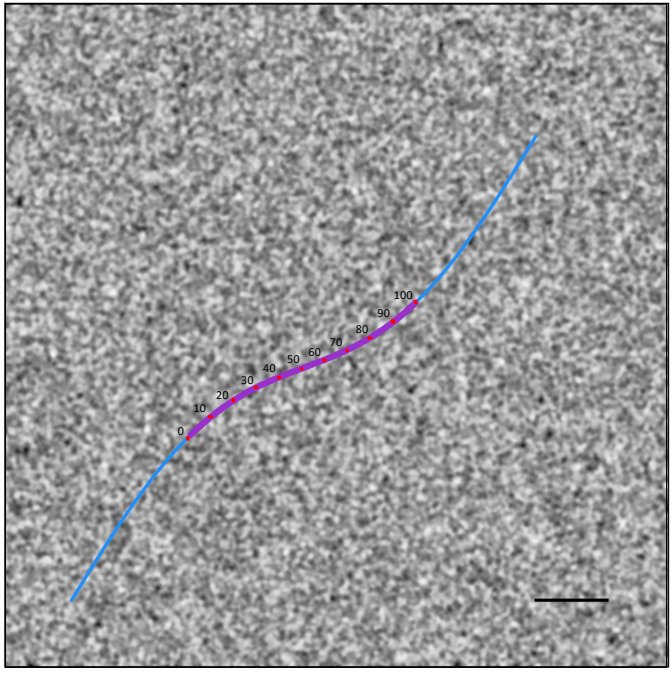


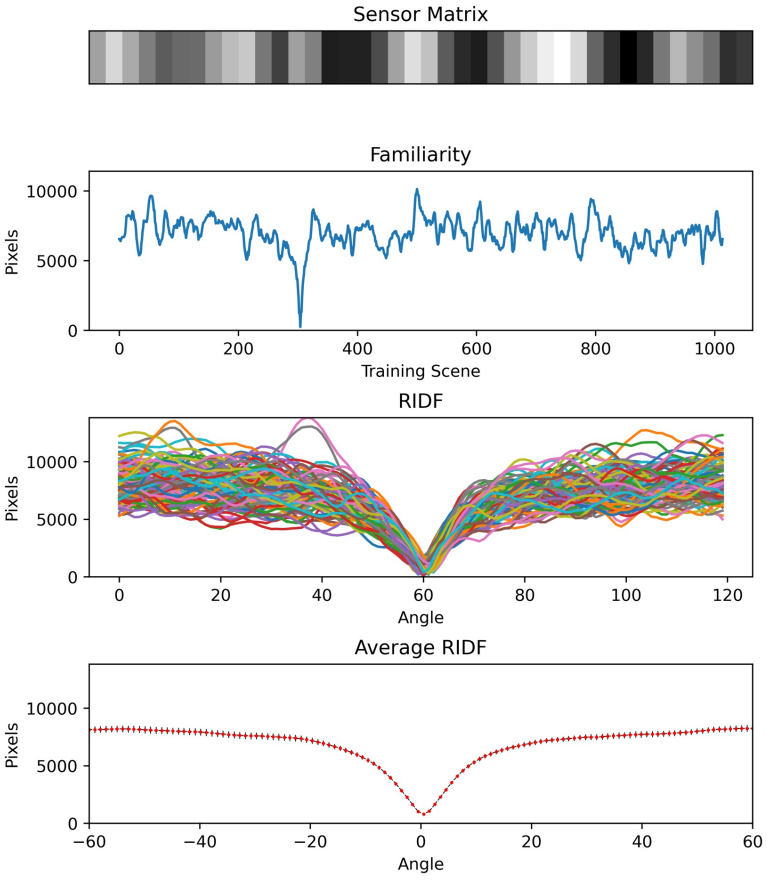
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 39.01; RMSD/dist: 0.098; TD: 6904; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

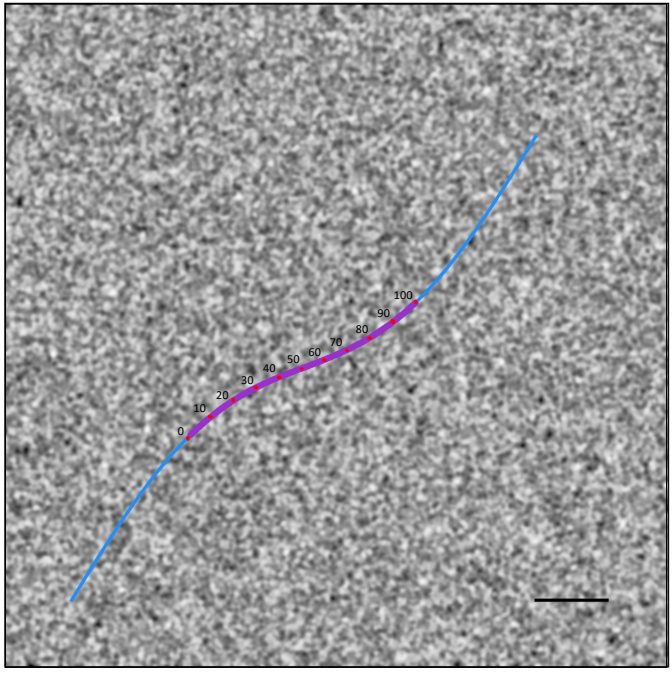


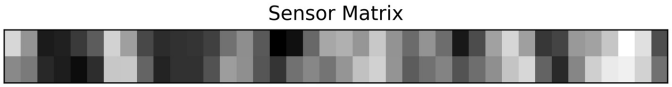


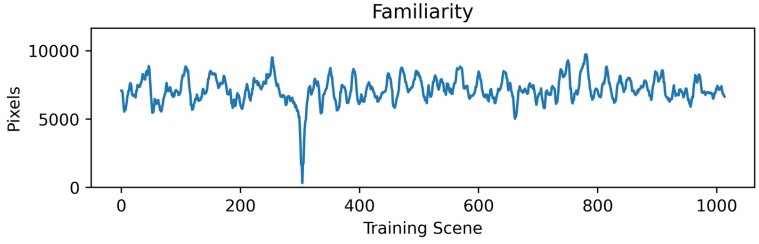
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

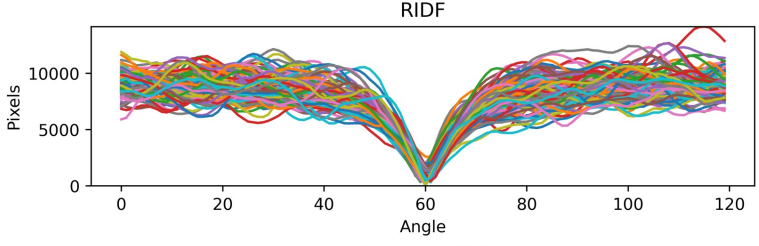
Navigation stats: RMSD error: 42.86; RMSD/dist: 0.107; TD: 5598; p90: 22; p50: 10; complete: 0

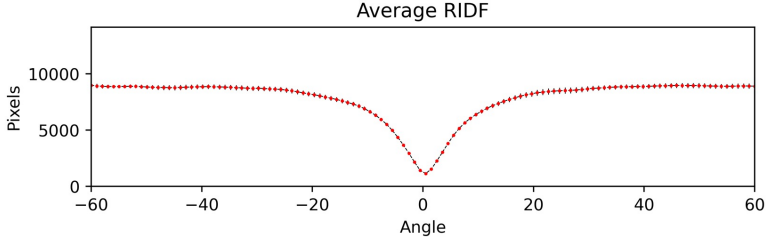
100%







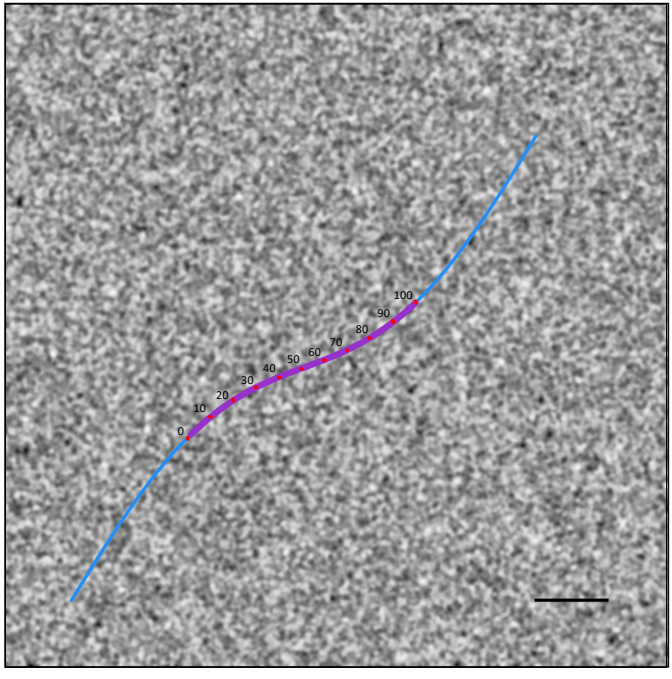


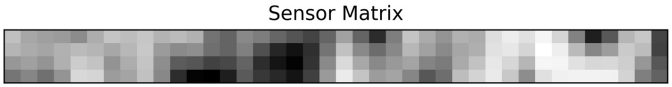


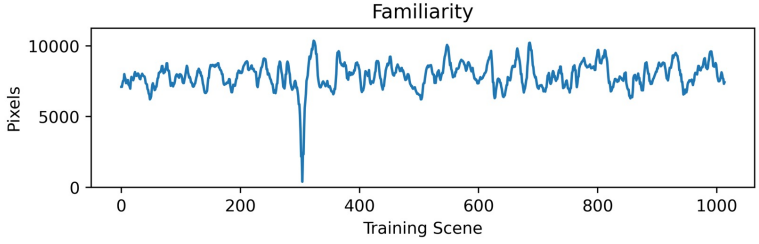
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

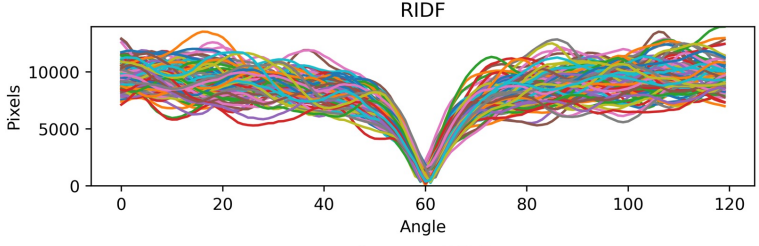
Navigation stats: RMSD error: 59.29; RMSD/dist: 0.148; TD: 6110; p90: 20; p50: 10; complete: 0

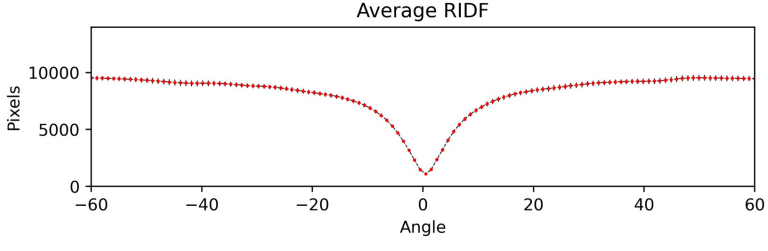
100%







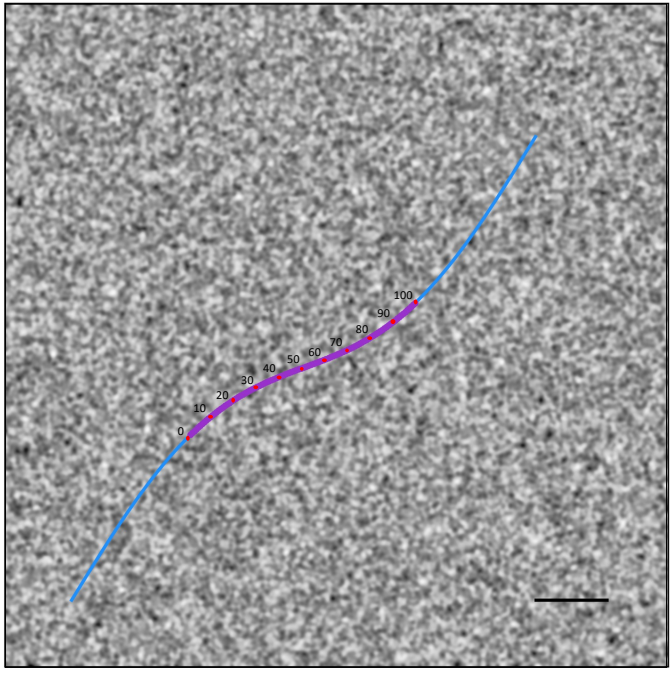


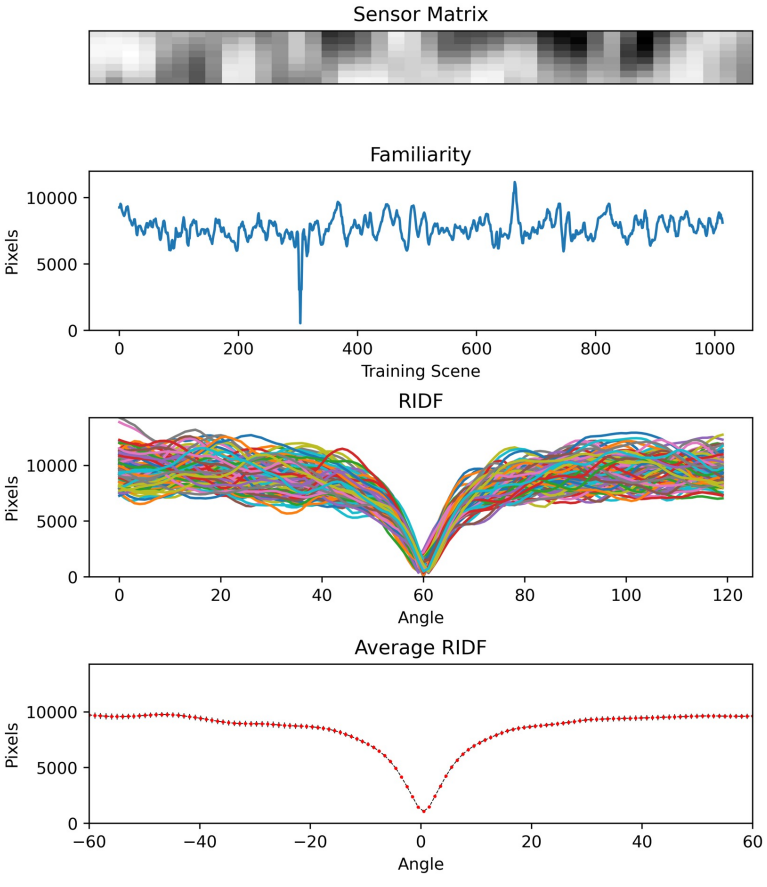


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 53.91; RMSD/dist: 0.135; TD: 6555; p90: 20; p50: 10; complete: 0

100%

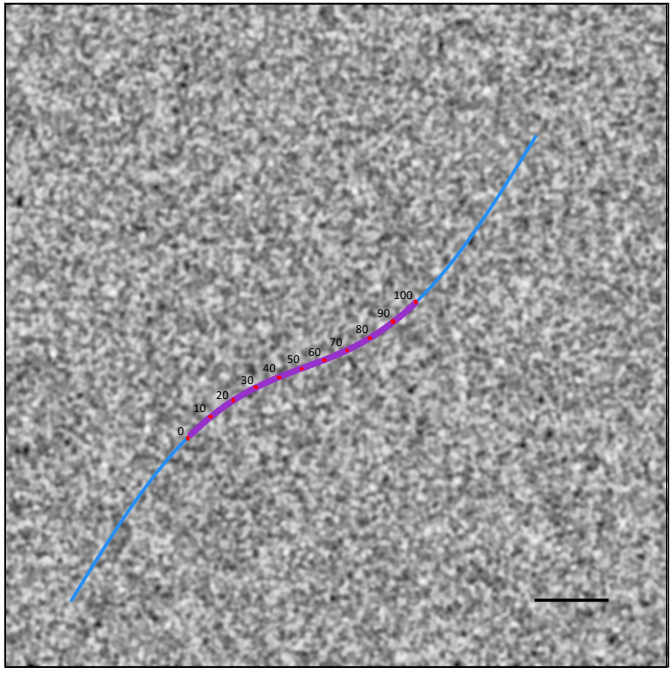


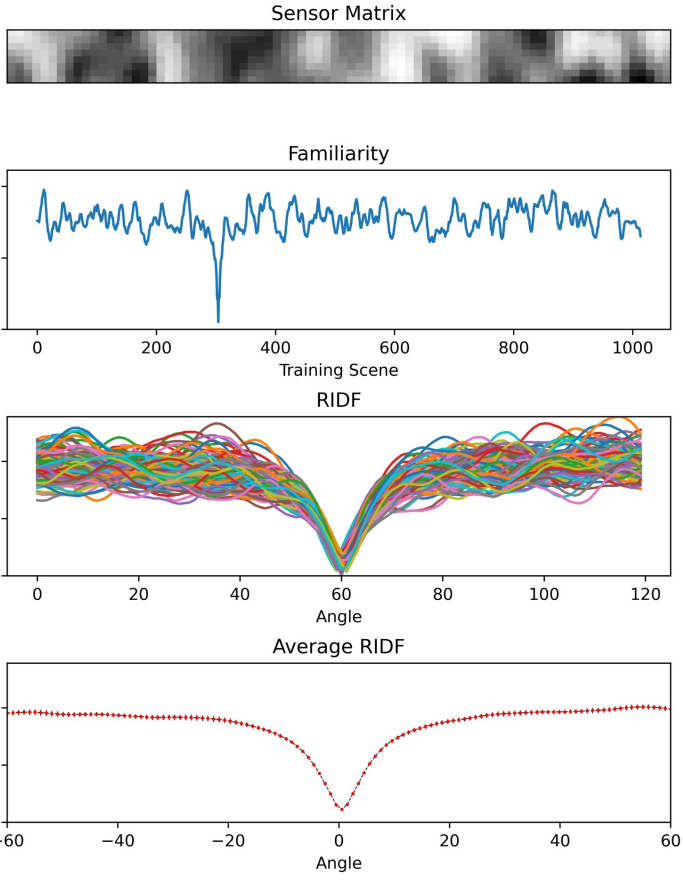


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 45.94; RMSD/dist: 0.115; TD: 6724; p90: 20; p50: 8; complete: 0

100%

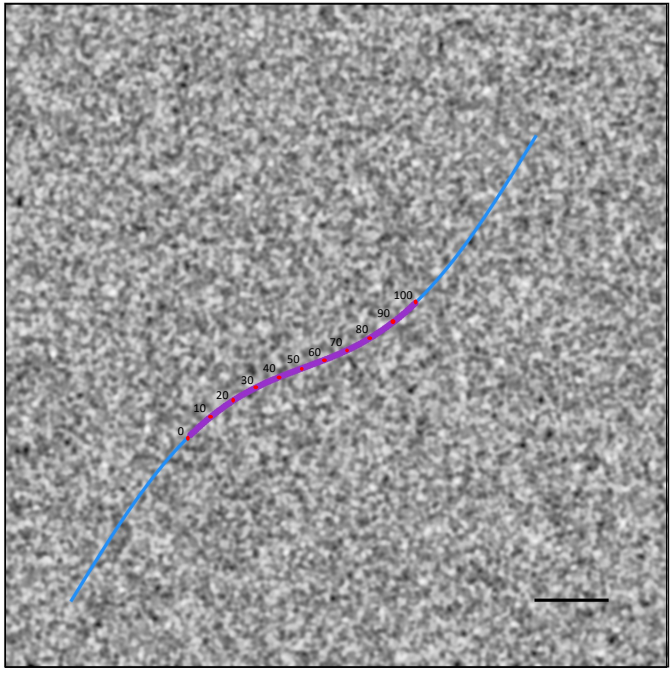


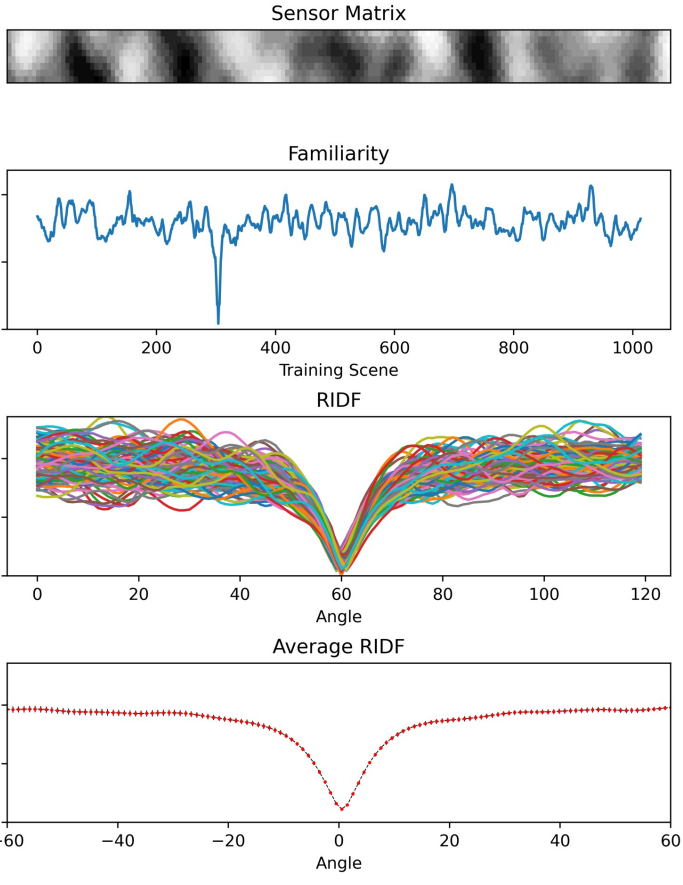


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 45.91; RMSD/dist: 0.115; TD: 6941; p90: 20; p50: 8; complete: 0

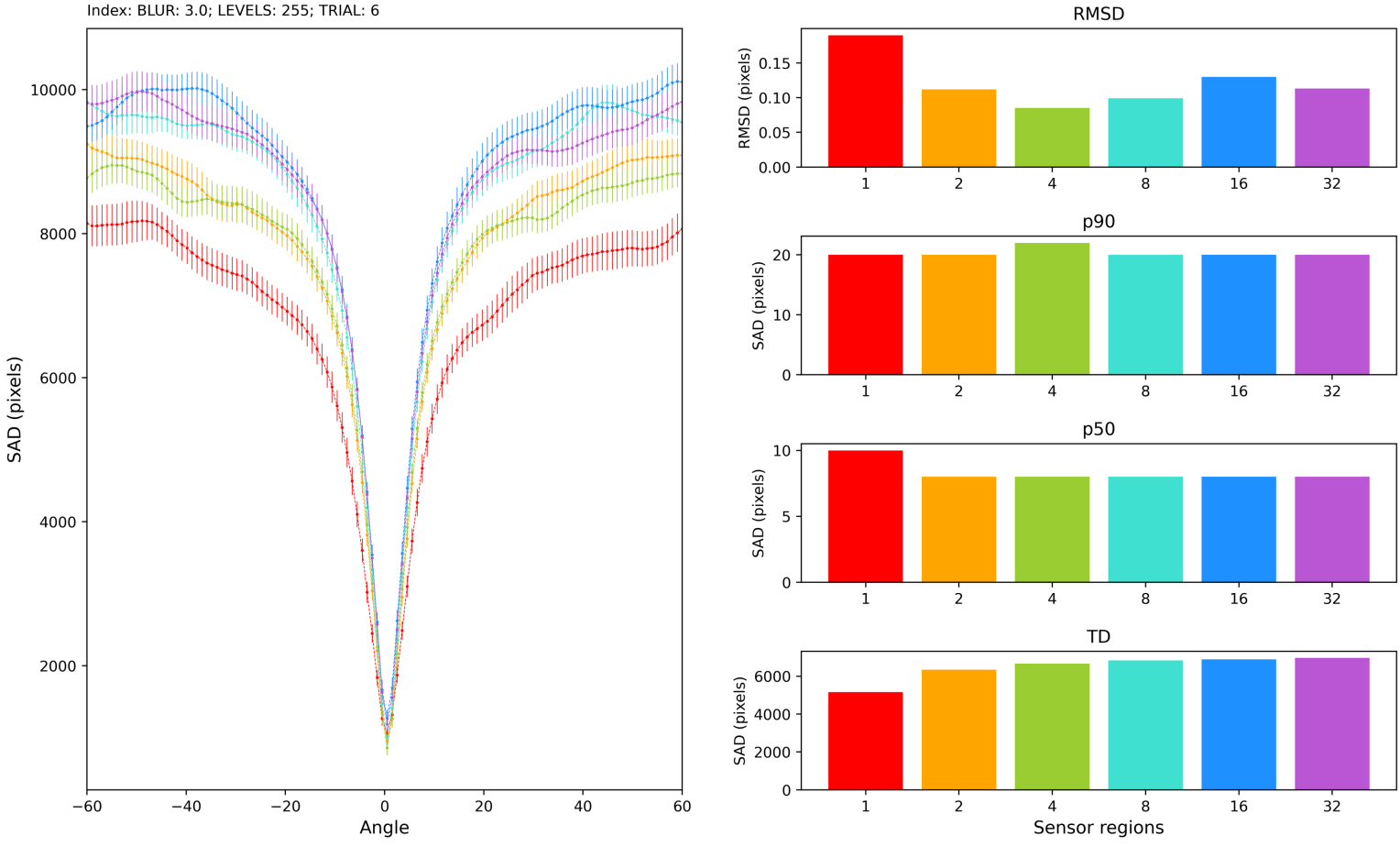
100%



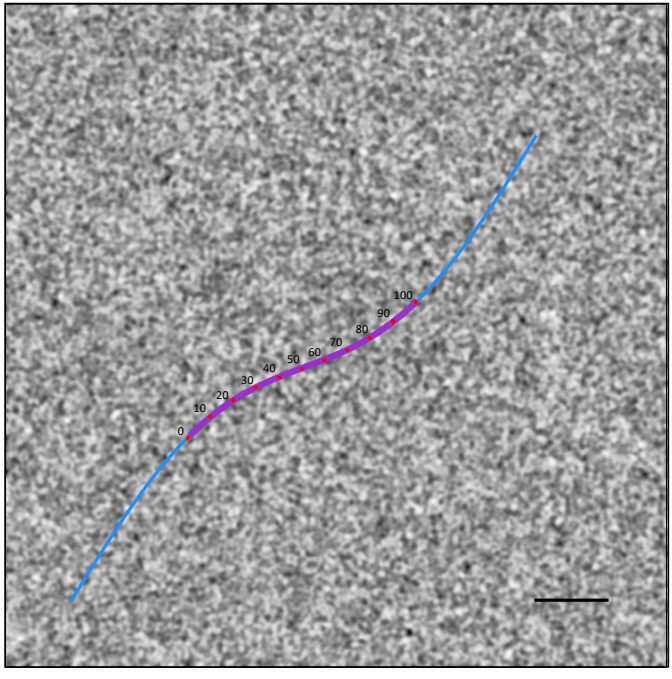


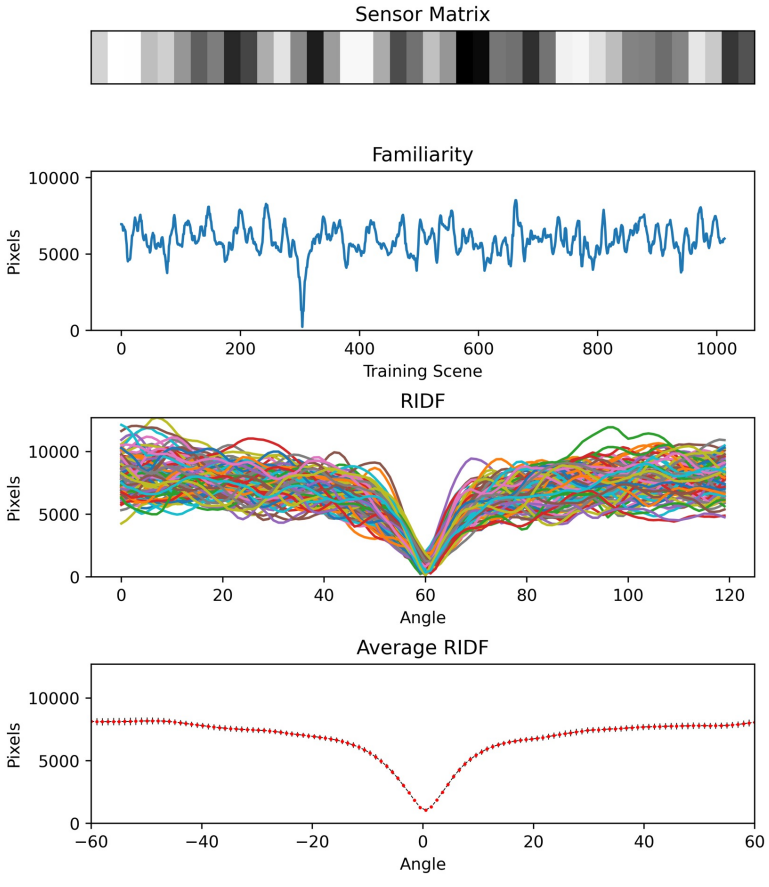
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 40.04; RMSD/dist: 0.100; TD: 6878; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

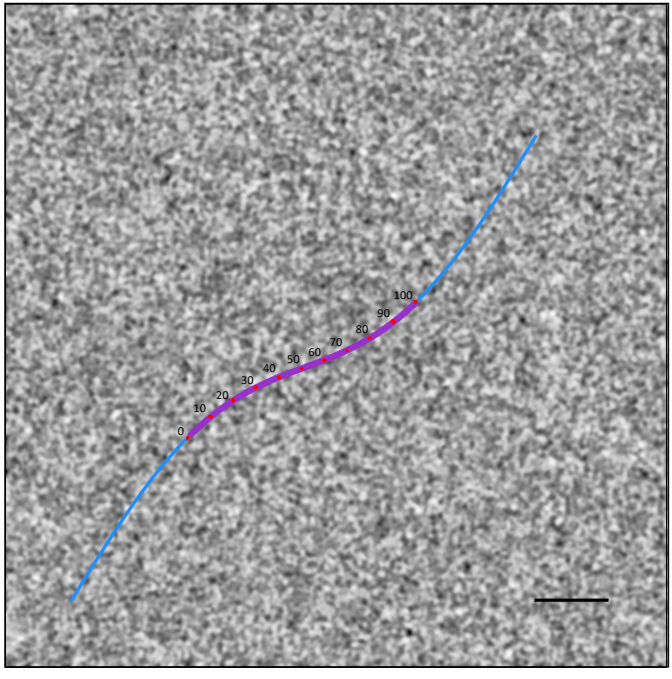


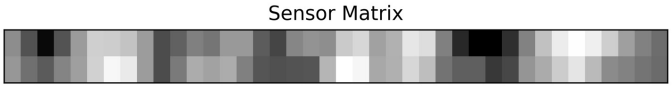


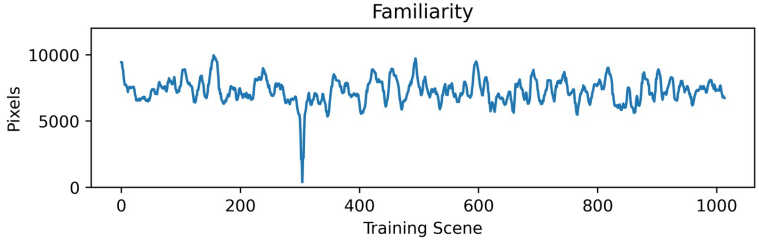
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

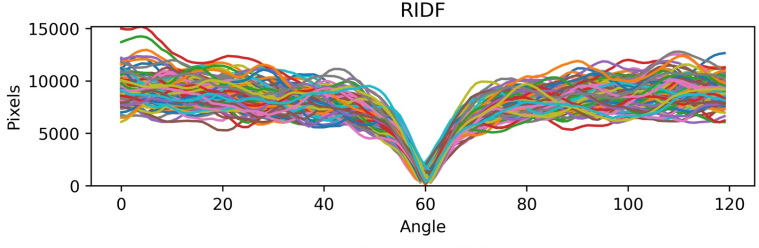
Navigation stats: RMSD error: 75.91; RMSD/dist: 0.190; TD: 5158; p90: 20; p50: 10; complete: 0

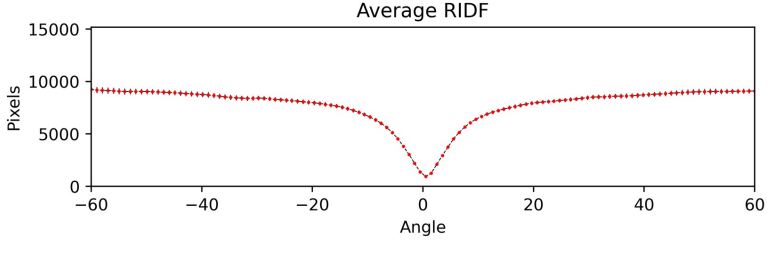
100%







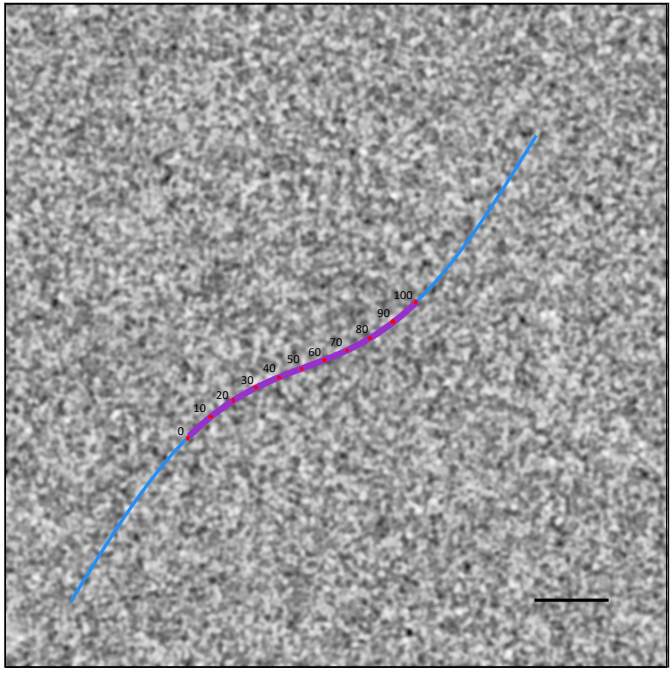


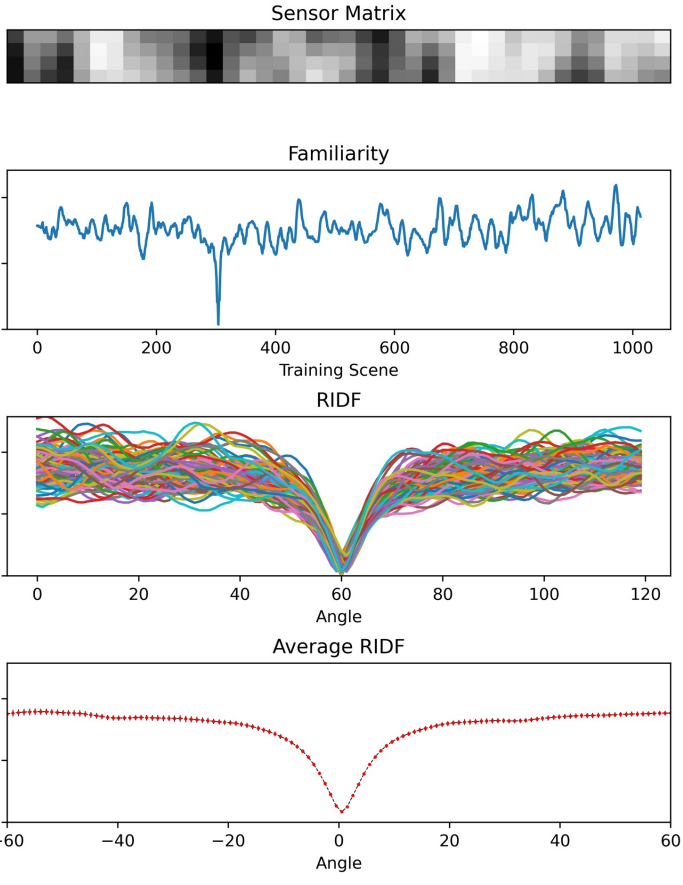


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 44.73; RMSD/dist: 0.112; TD: 6346; p90: 20; p50: 8; complete: 0

100%

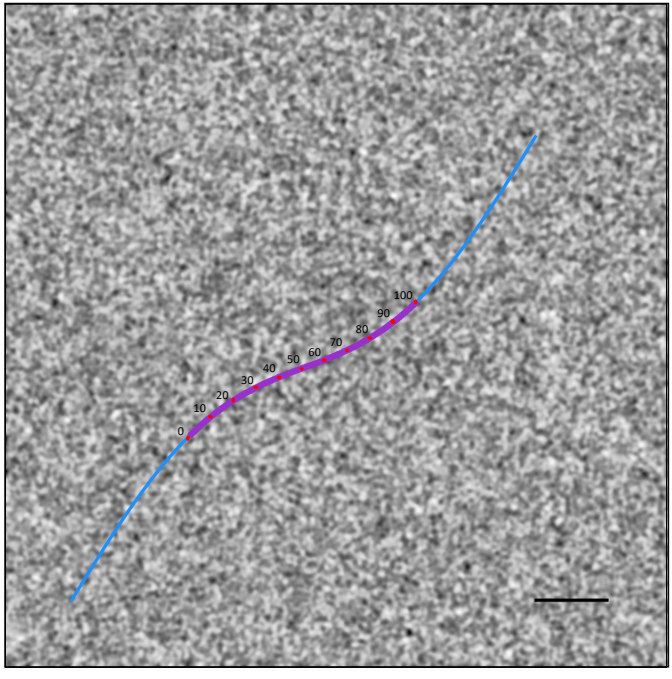


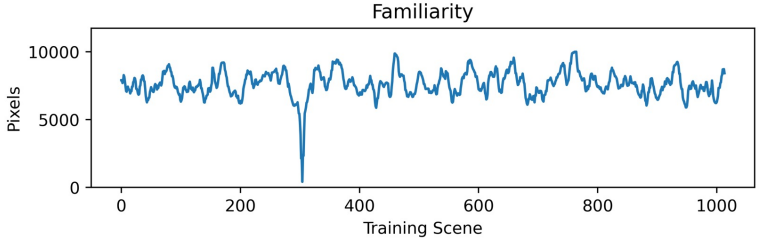


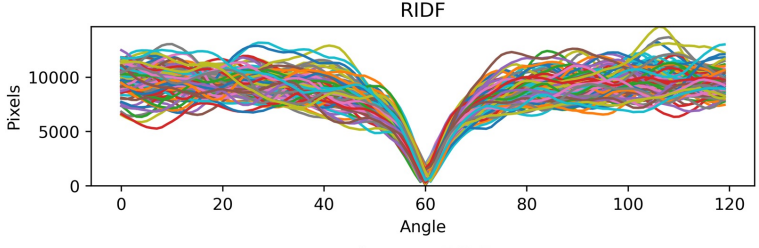
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

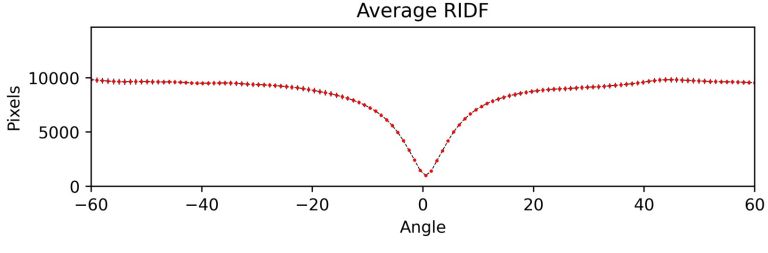
Navigation stats: RMSD error: 34.00; RMSD/dist: 0.085; TD: 6665; p90: 22; p50: 8; complete: 0

100%





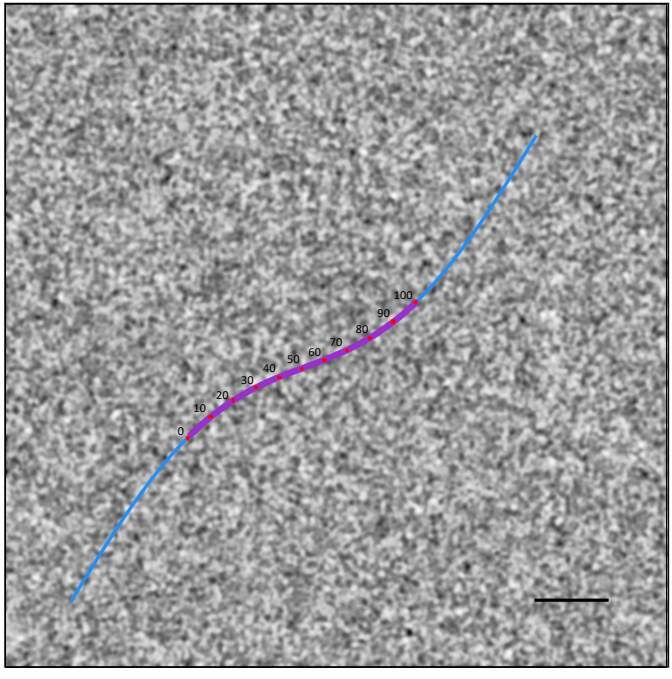


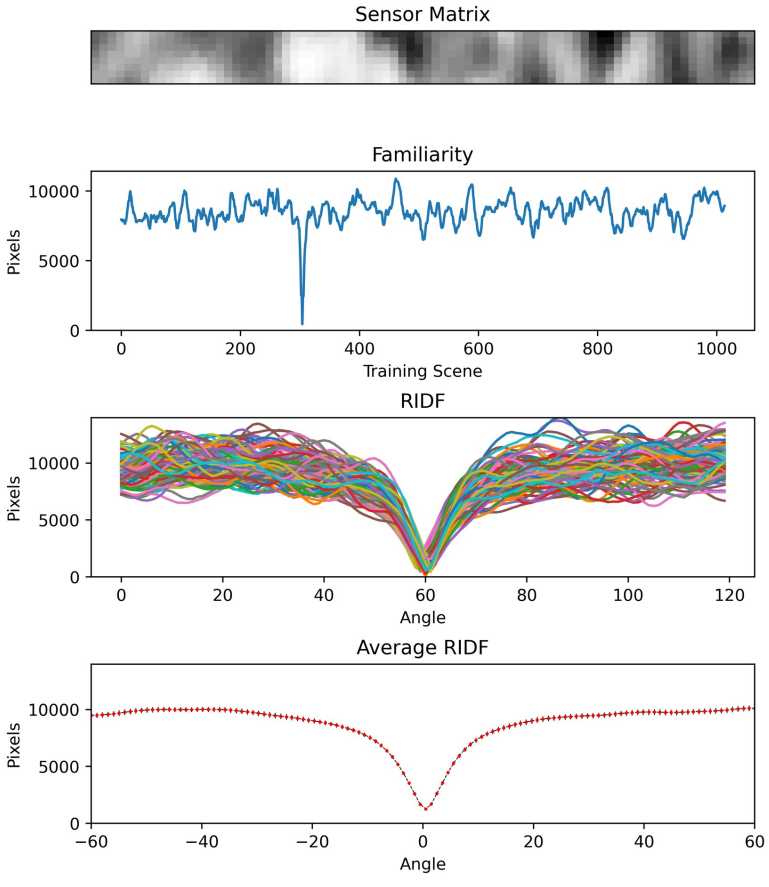


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 39.44; RMSD/dist: 0.099; TD: 6830; p90: 20; p50: 8; complete: 0

100%

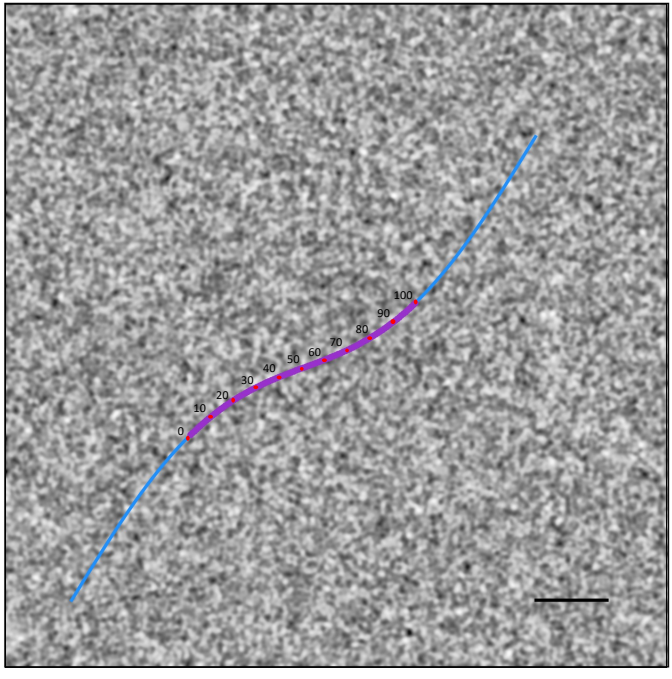


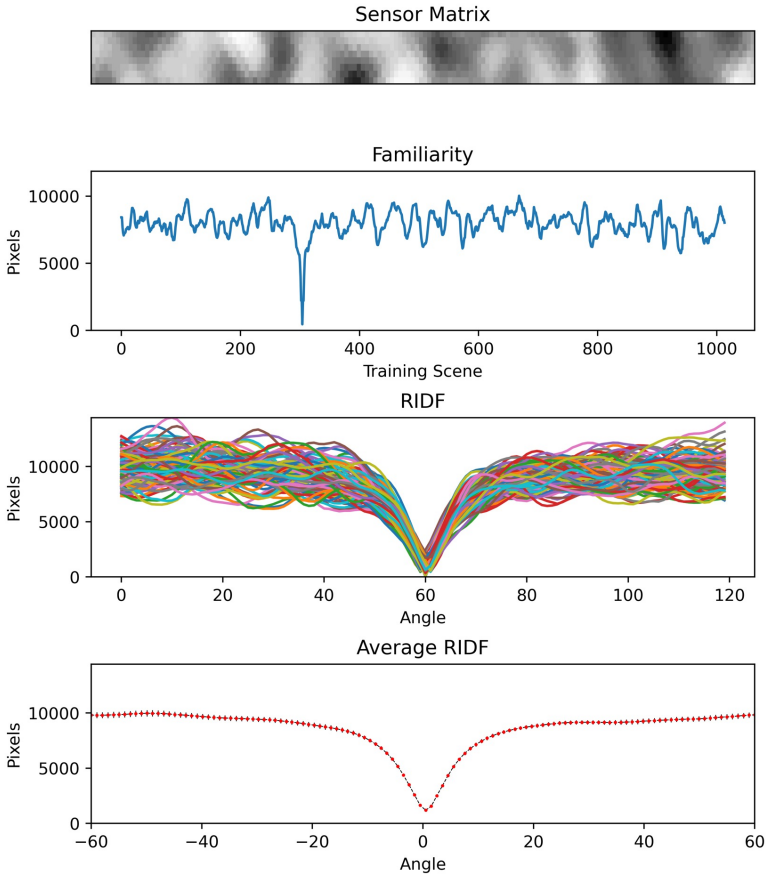


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 52.03; RMSD/dist: 0.130; TD: 6882; p90: 20; p50: 8; complete: 0

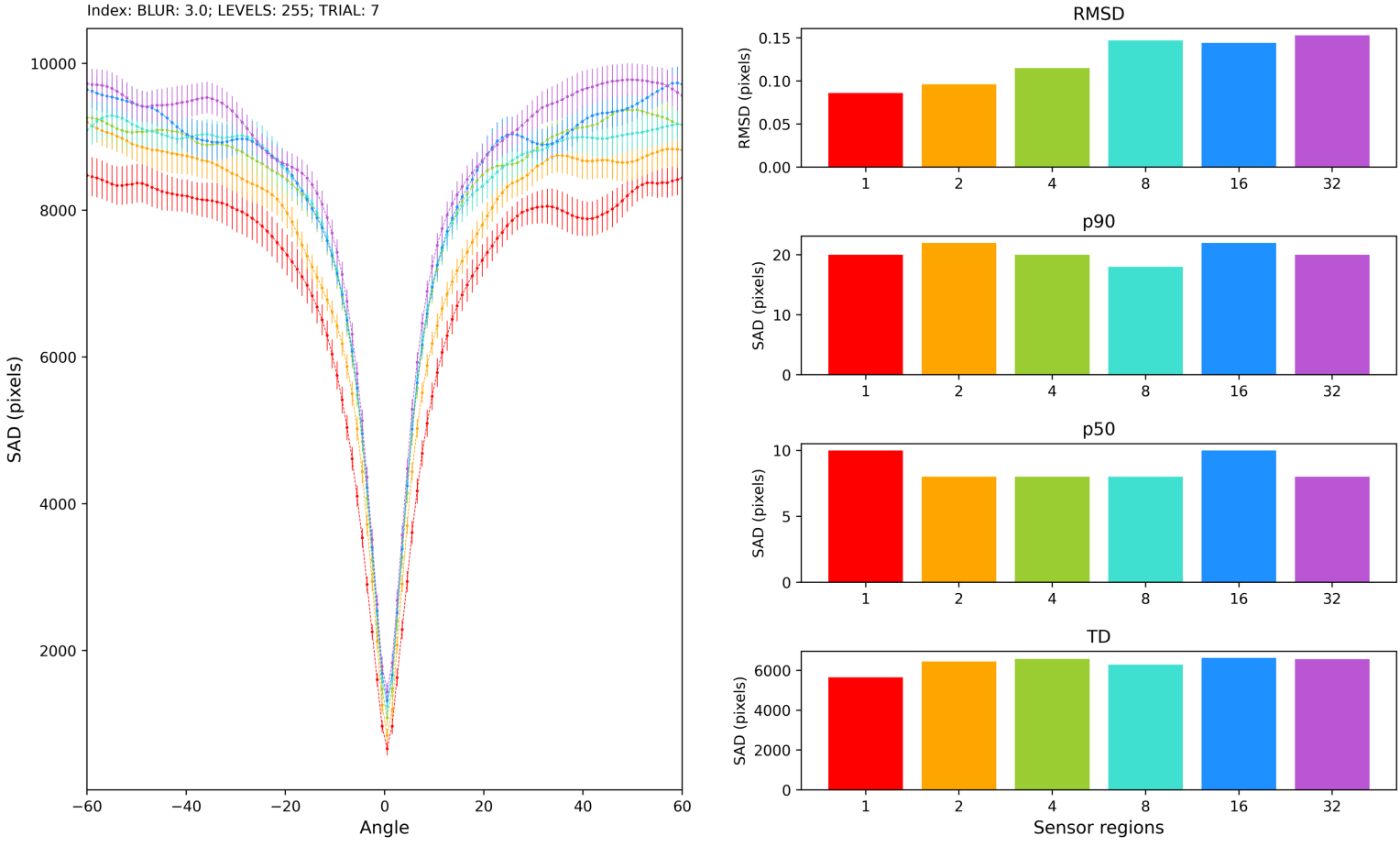
100%



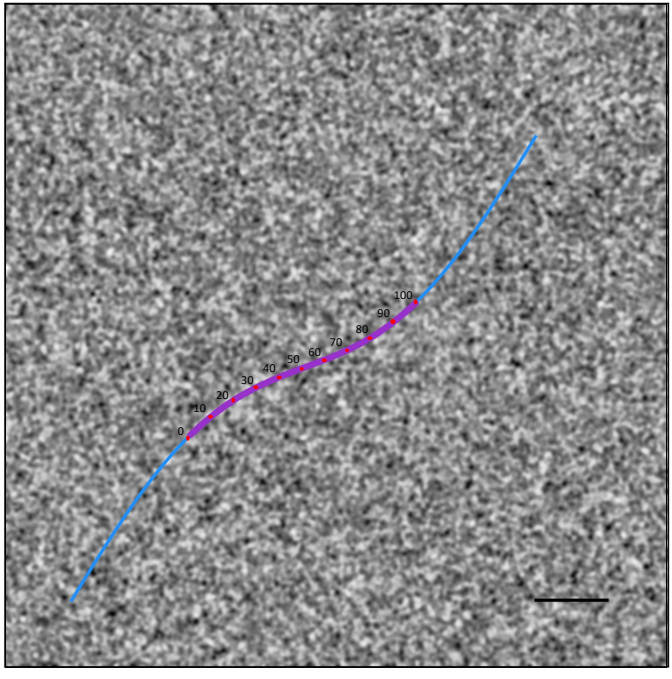


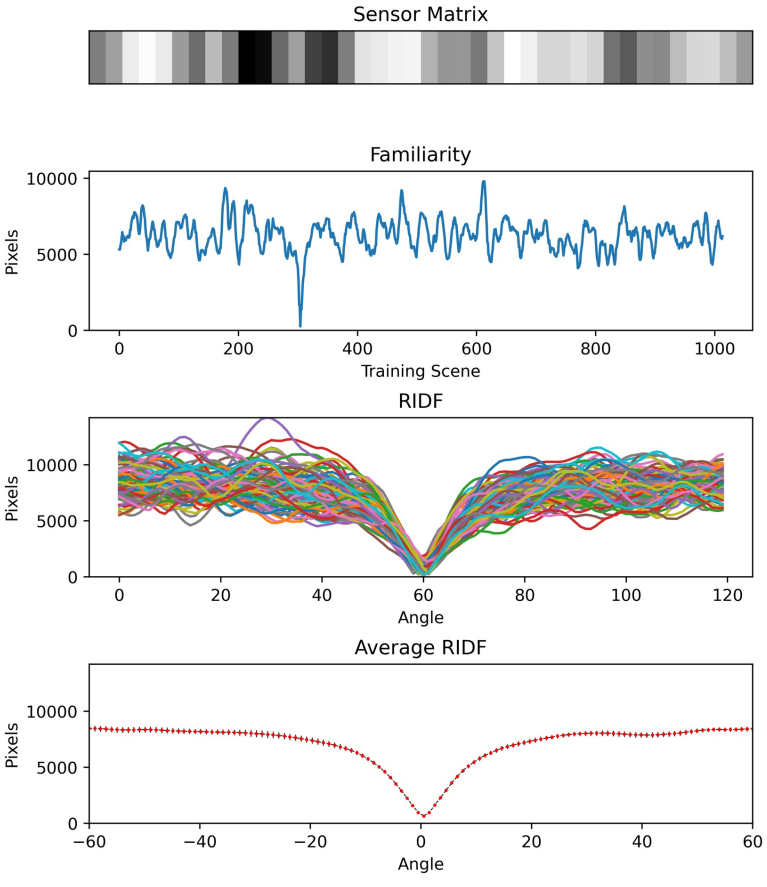
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 45.39; RMSD/dist: 0.113; TD: 6960; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 255; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

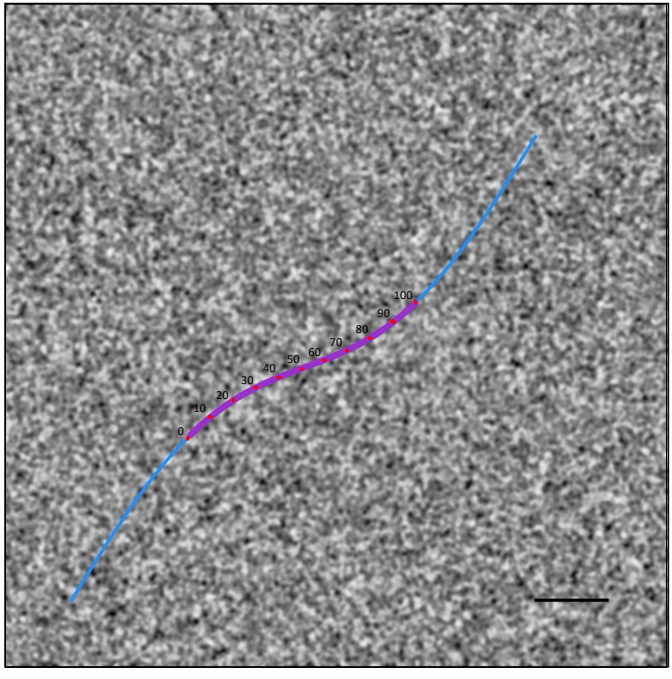


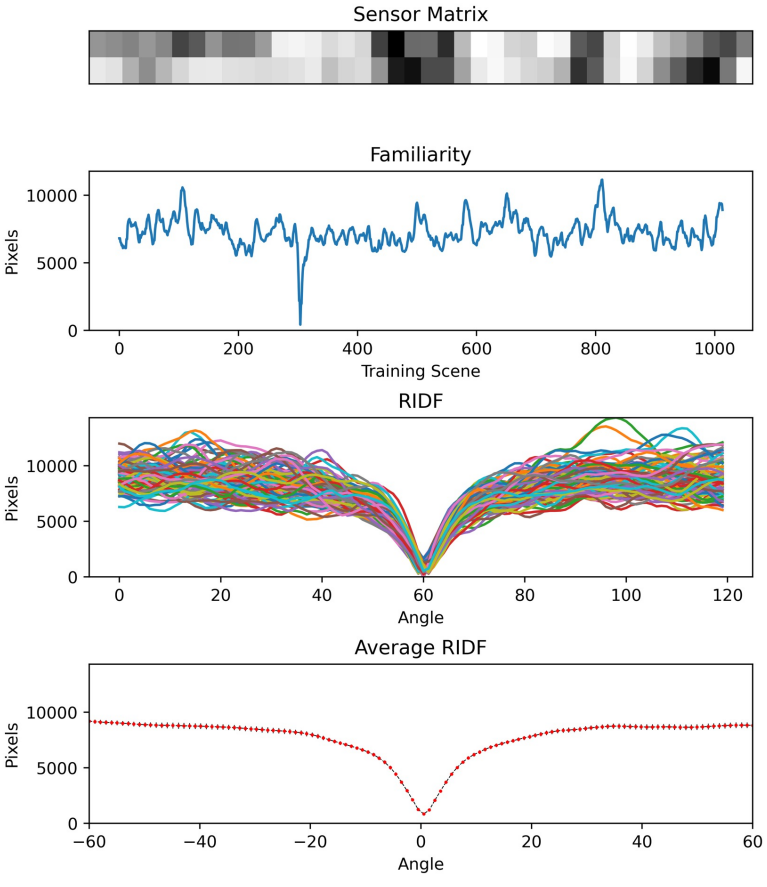


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 34.25; RMSD/dist: 0.086; TD: 5648; p90: 20; p50: 10; complete: 0

100%

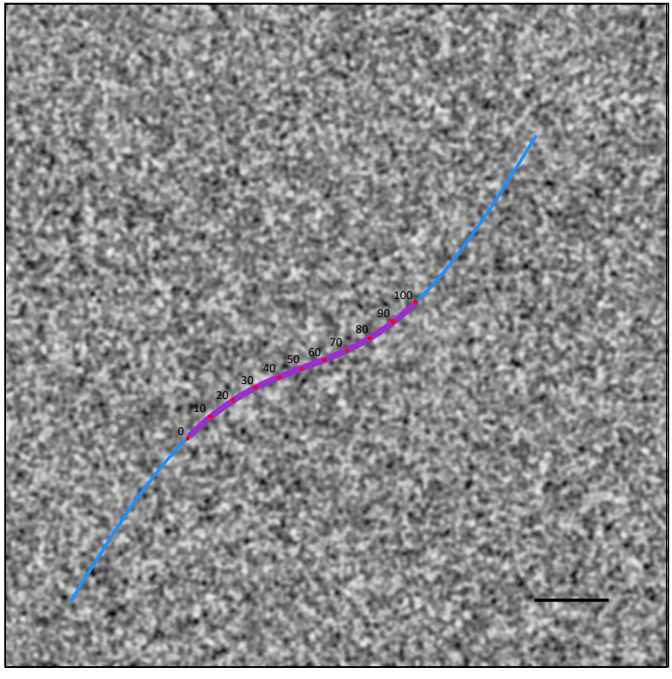


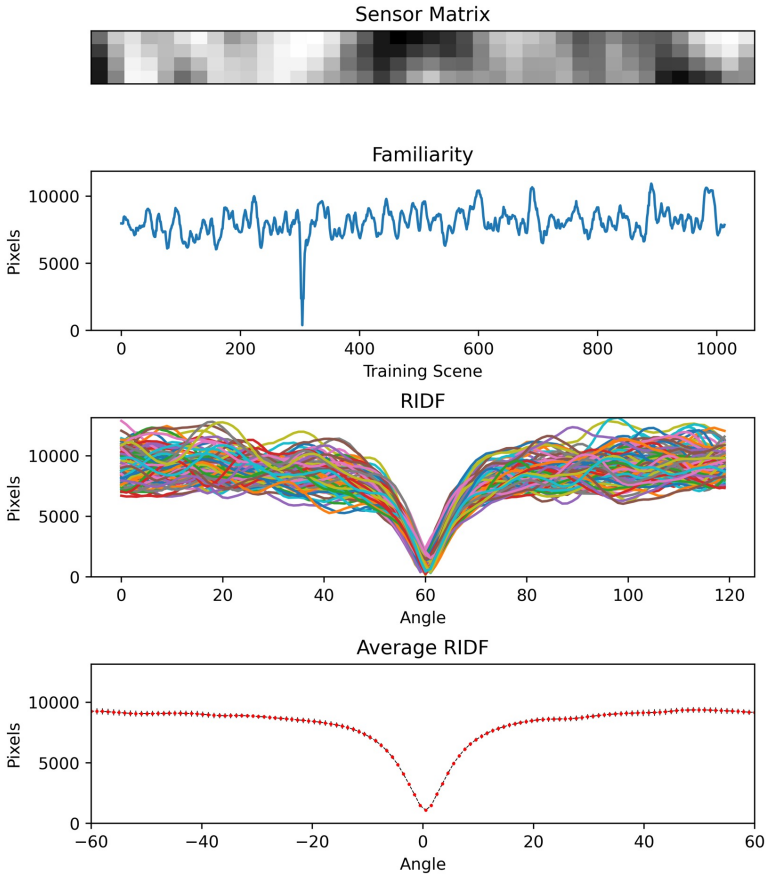


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 38.36; RMSD/dist: 0.096; TD: 6440; p90: 22; p50: 8; complete: 0

100%

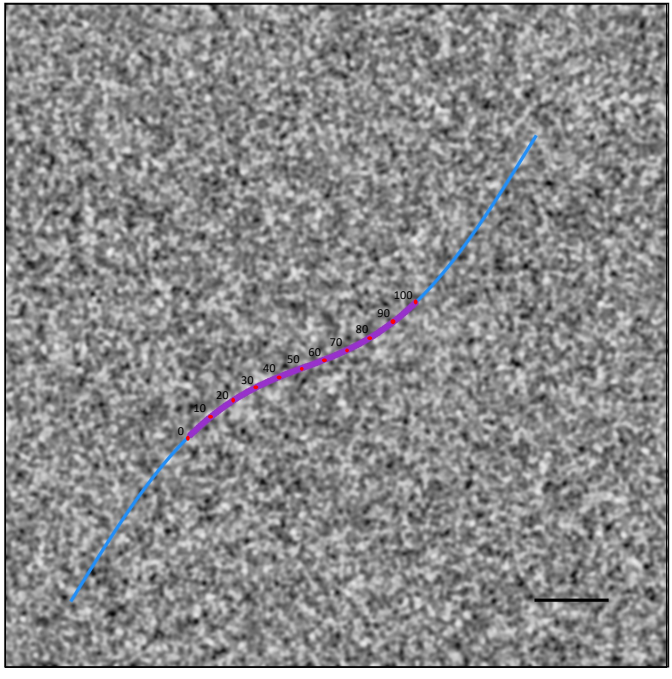


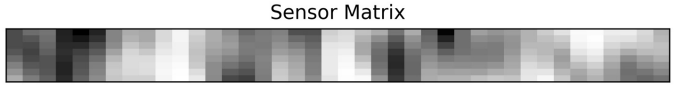


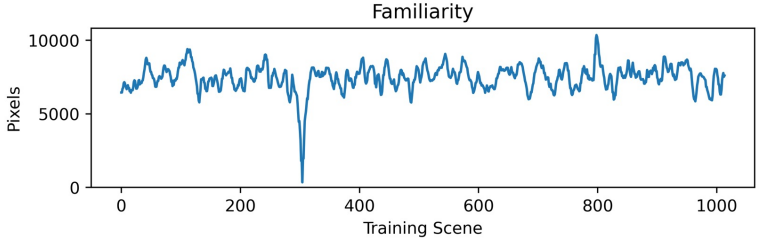
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

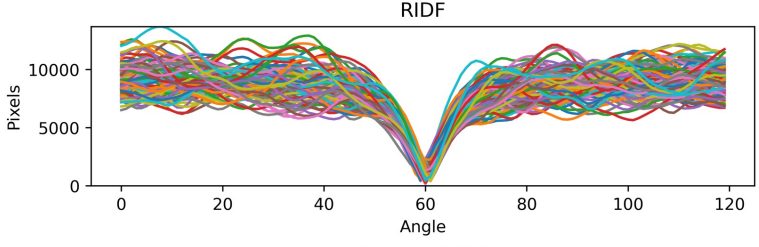
Navigation stats: RMSD error: 46.19; RMSD/dist: 0.115; TD: 6569; p90: 20; p50: 8; complete: 0

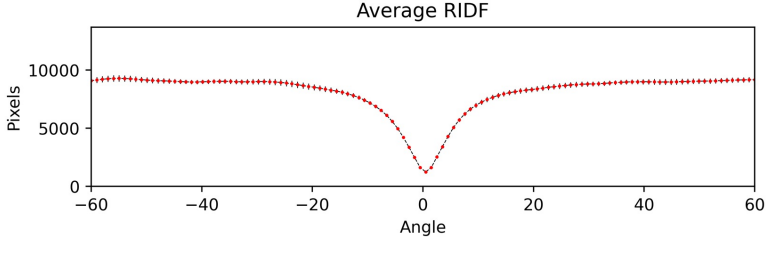
100%







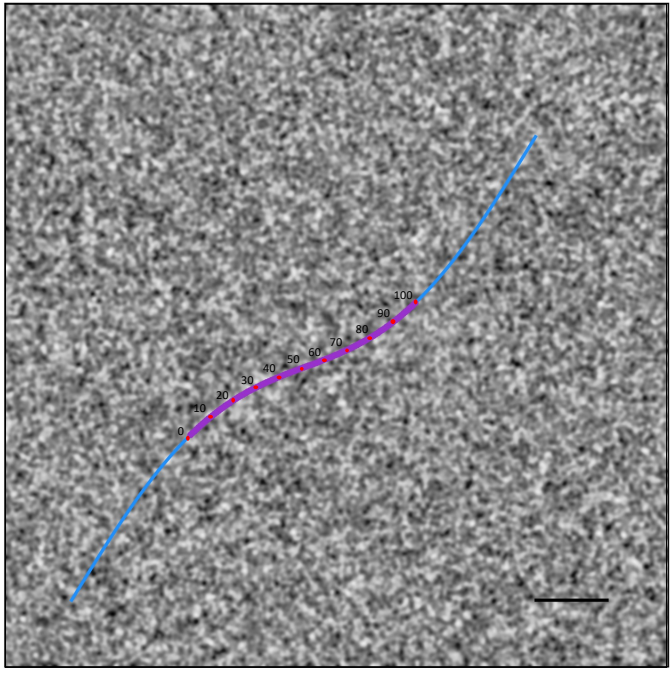


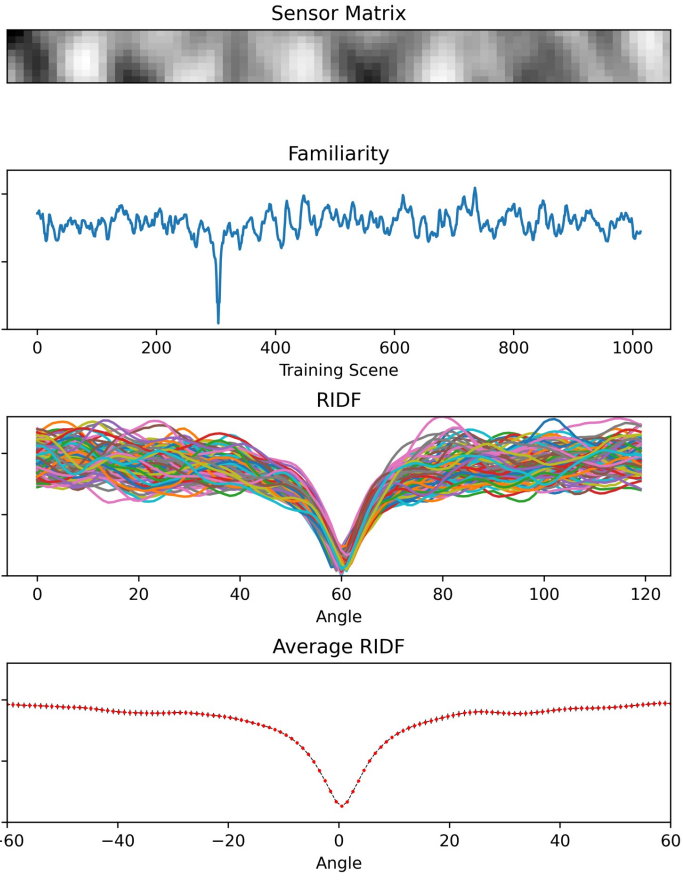


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 58.67; RMSD/dist: 0.147; TD: 6284; p90: 18; p50: 8; complete: 0

100%

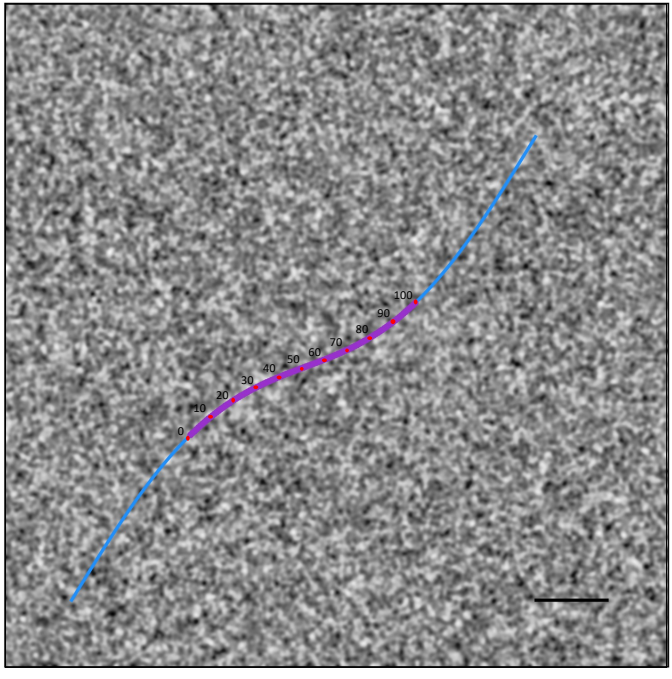


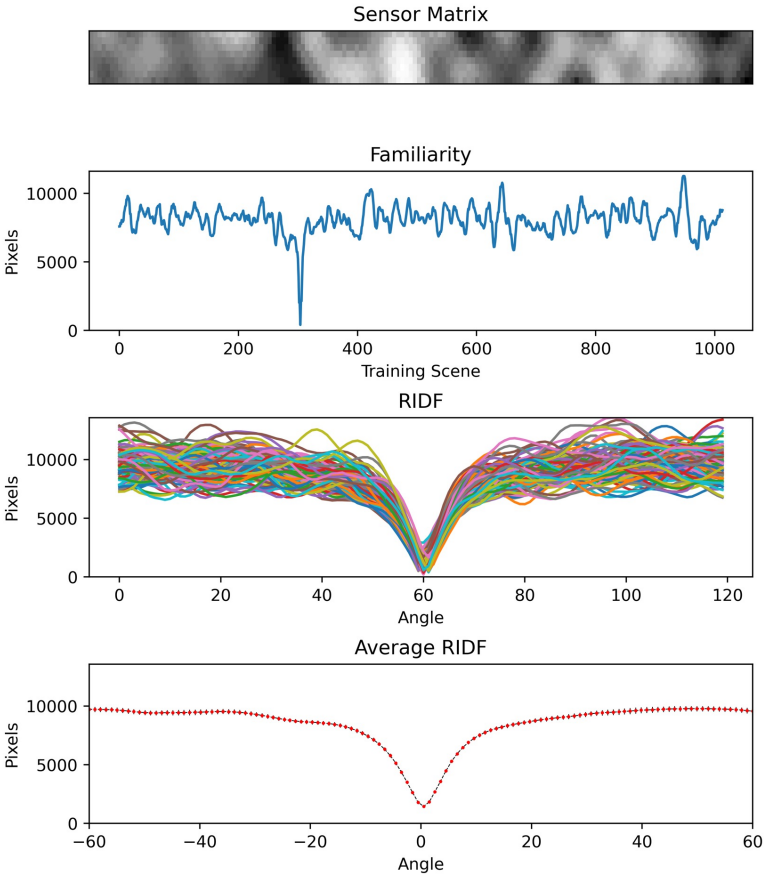


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 57.52; RMSD/dist: 0.144; TD: 6620; p90: 22; p50: 10; complete: 0

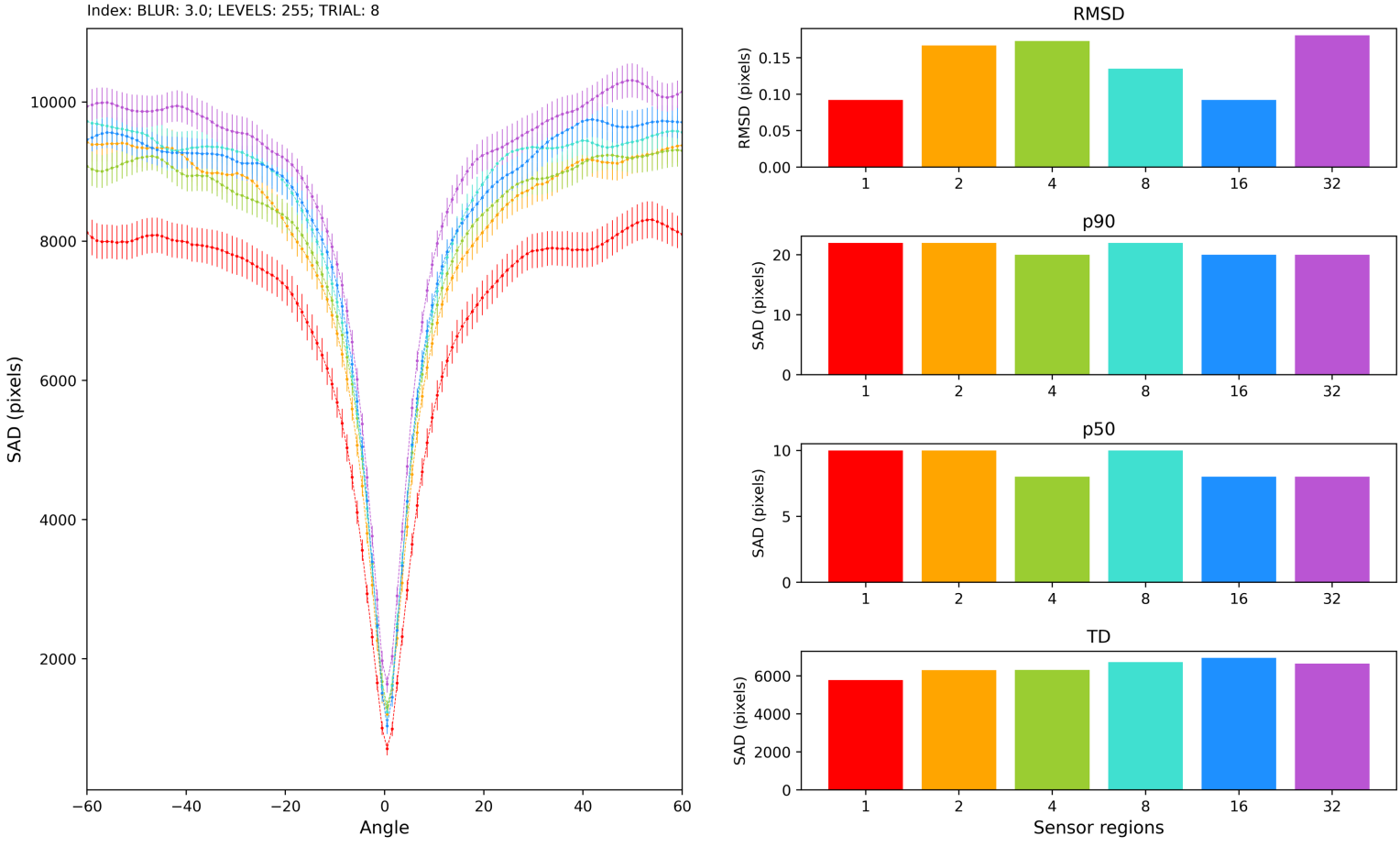
100%



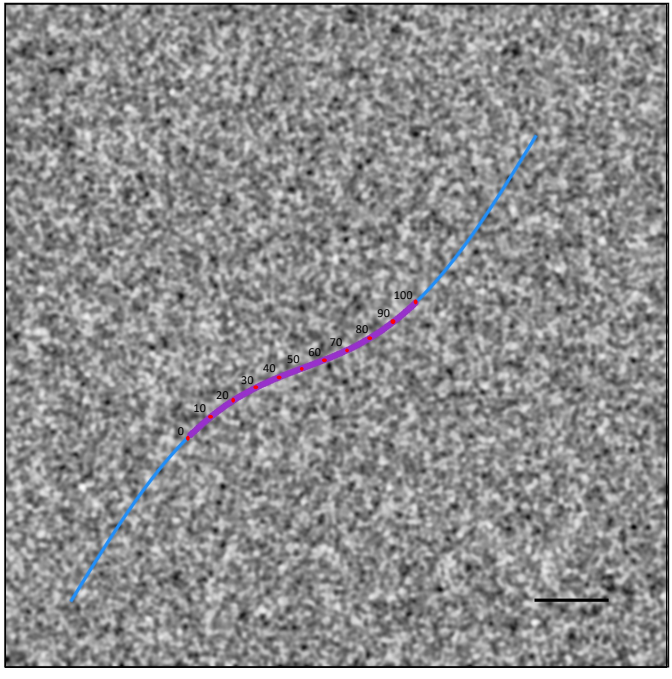


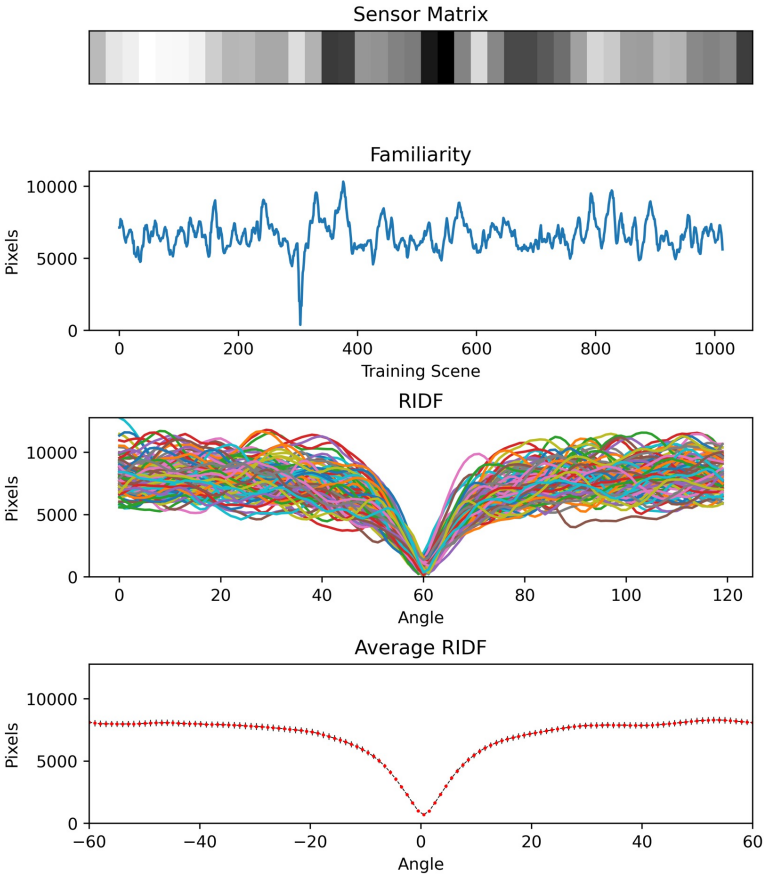
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 61.29; RMSD/dist: 0.153; TD: 6558; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 255; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

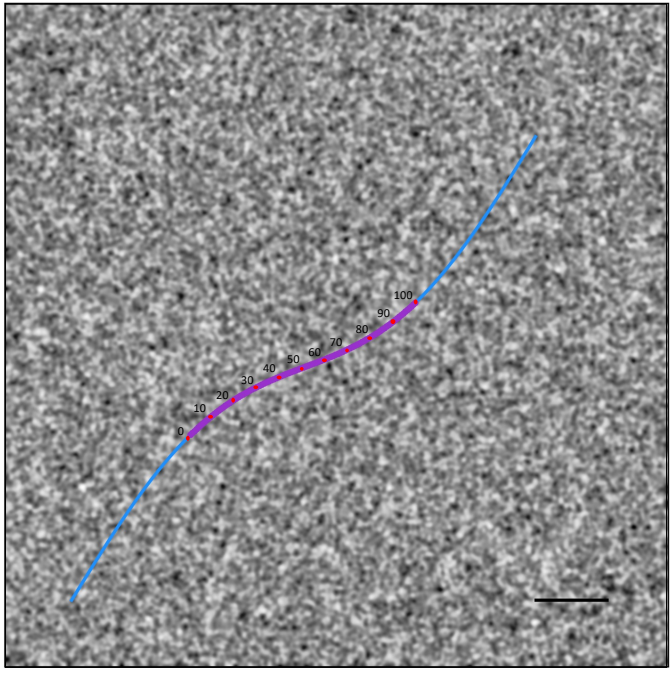


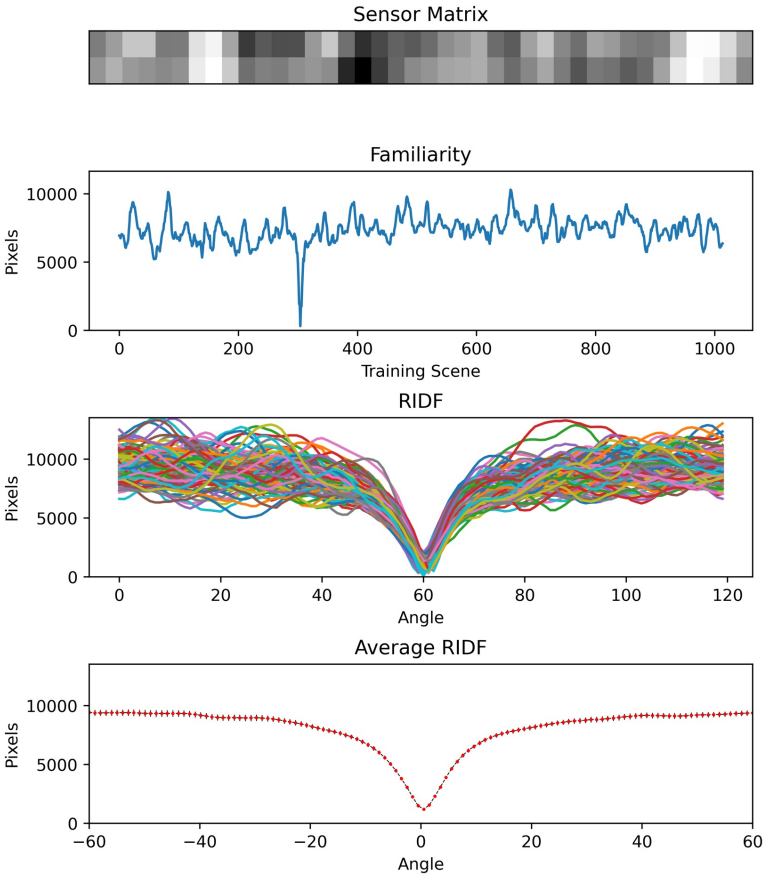


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 36.65; RMSD/dist: 0.092; TD: 5786; p90: 22; p50: 10; complete: 0

100%

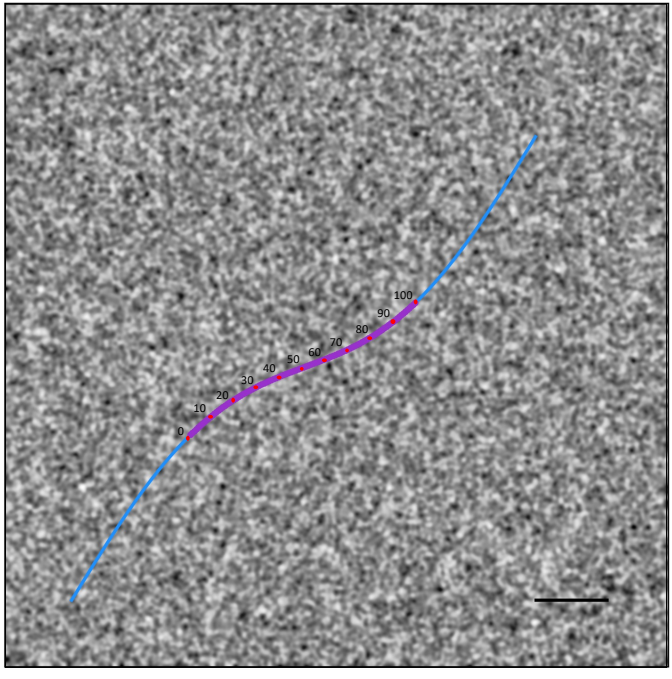


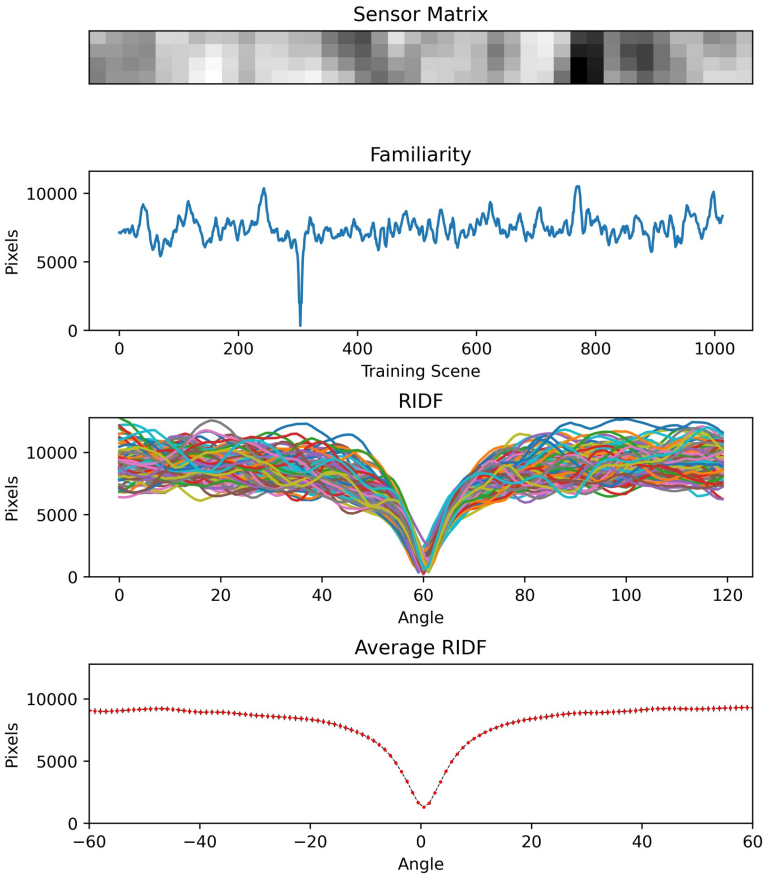


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 67.00; RMSD/dist: 0.167; TD: 6304; p90: 22; p50: 10; complete: 0

100%

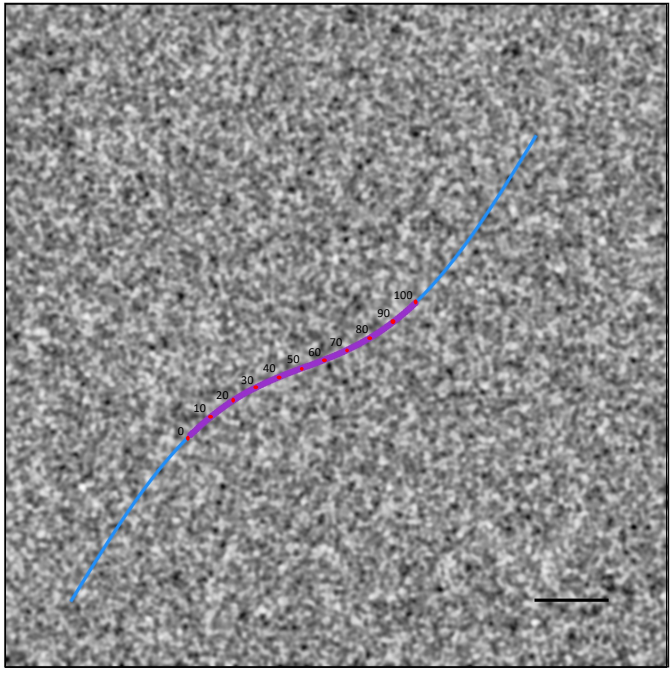


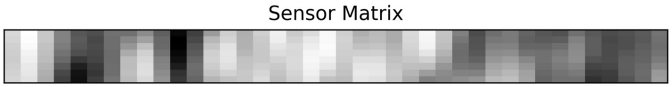


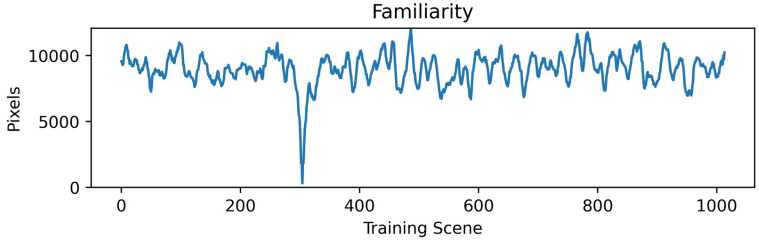
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

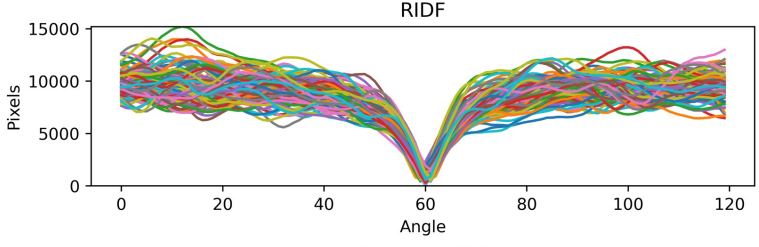
Navigation stats: RMSD error: 69.28; RMSD/dist: 0.173; TD: 6312; p90: 20; p50: 8; complete: 0

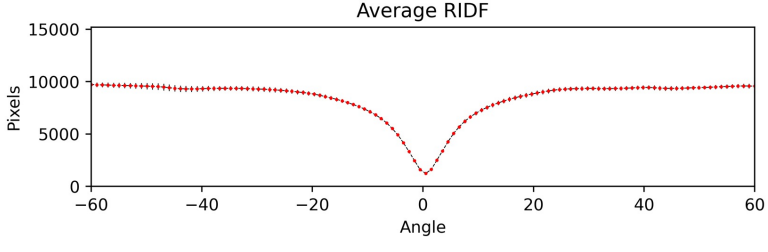
100%







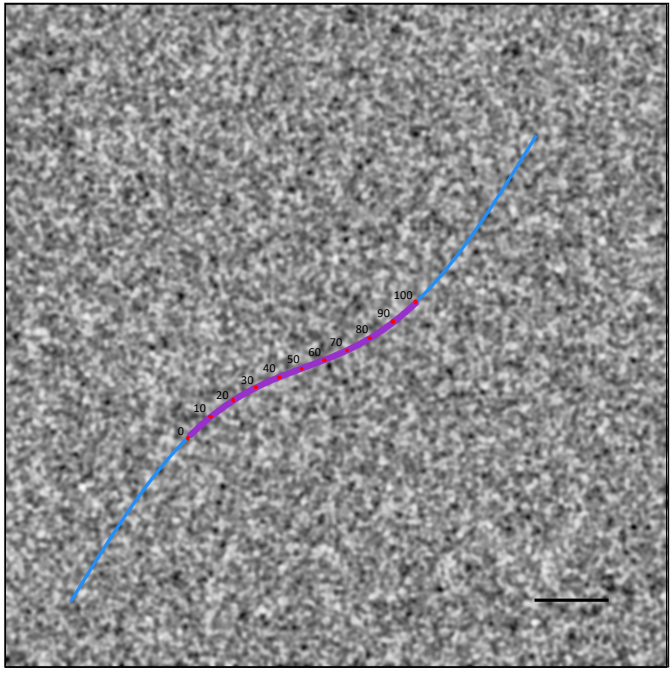


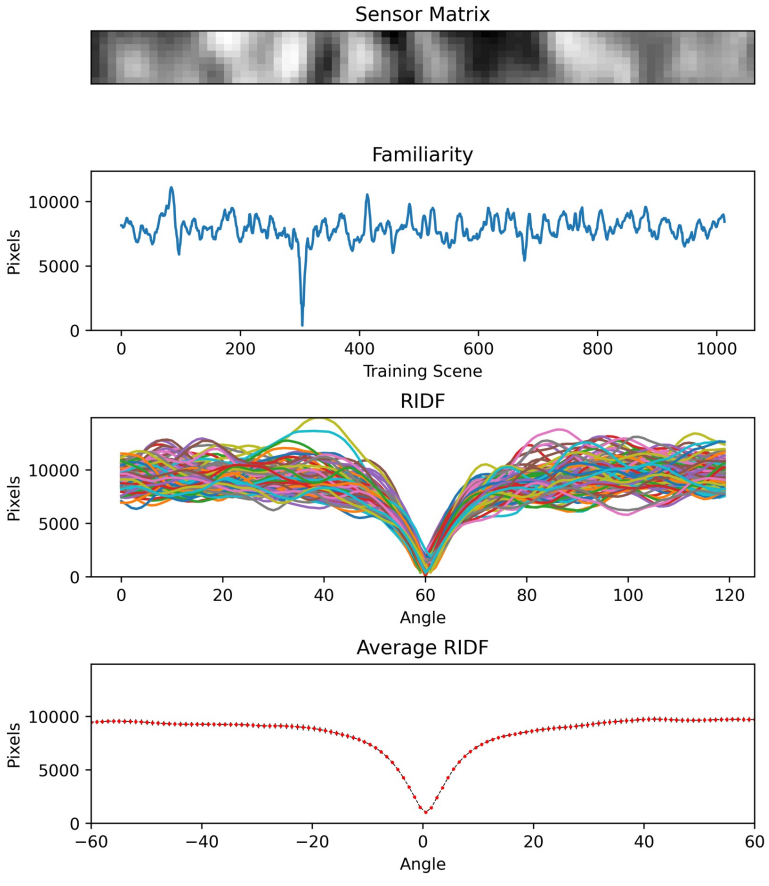


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 53.90; RMSD/dist: 0.135; TD: 6725; p90: 22; p50: 10; complete: 0

100%

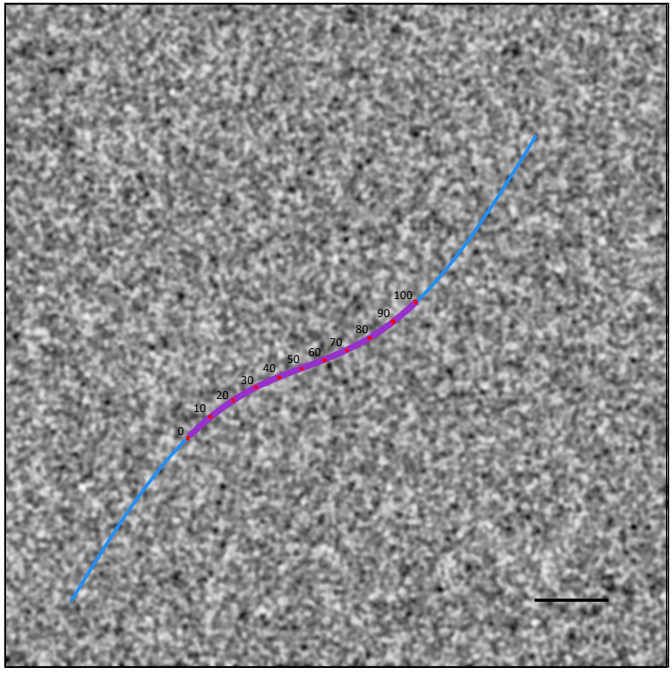


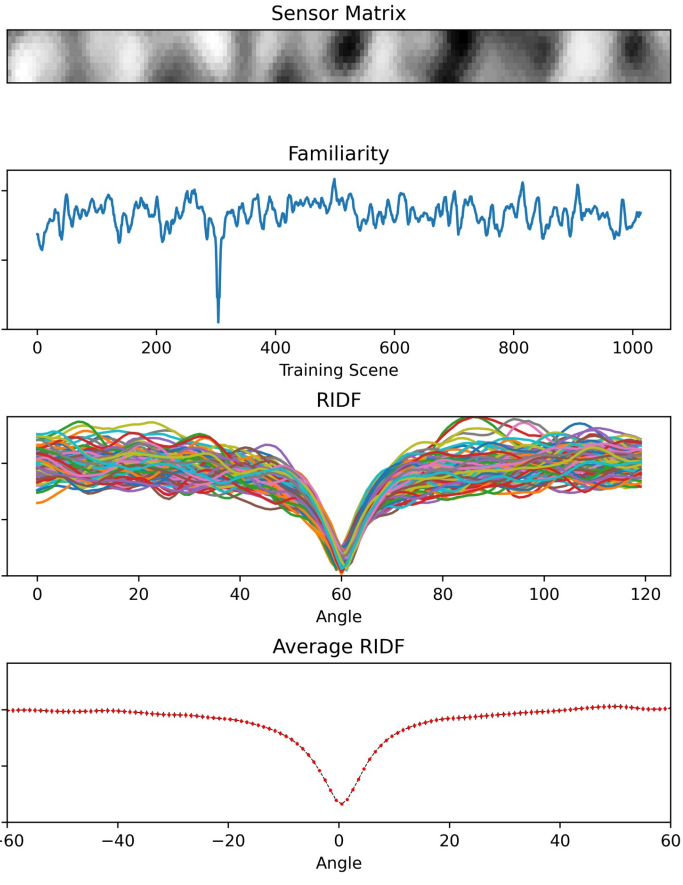


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 36.92; RMSD/dist: 0.092; TD: 6945; p90: 20; p50: 8; complete: 0

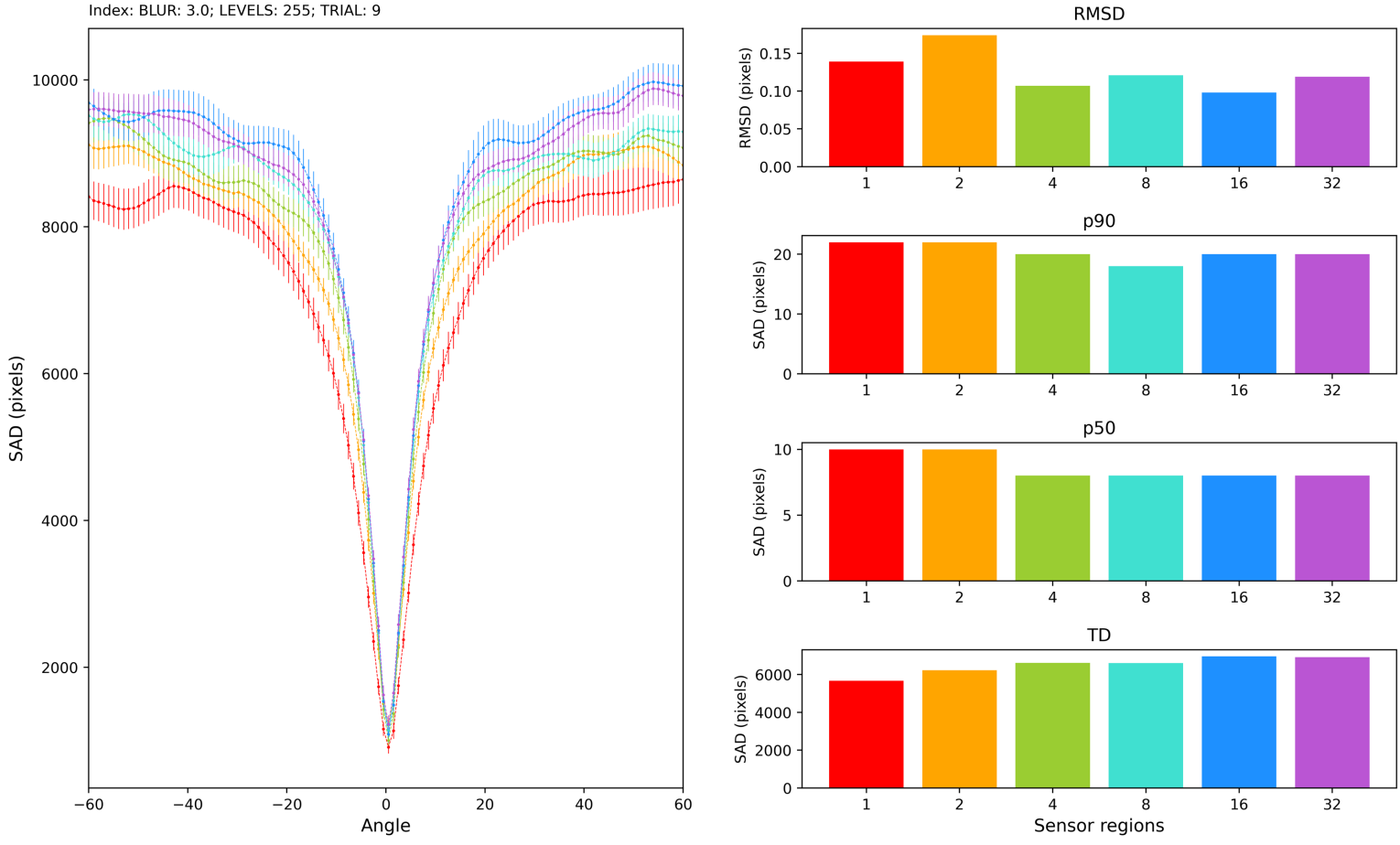
100%



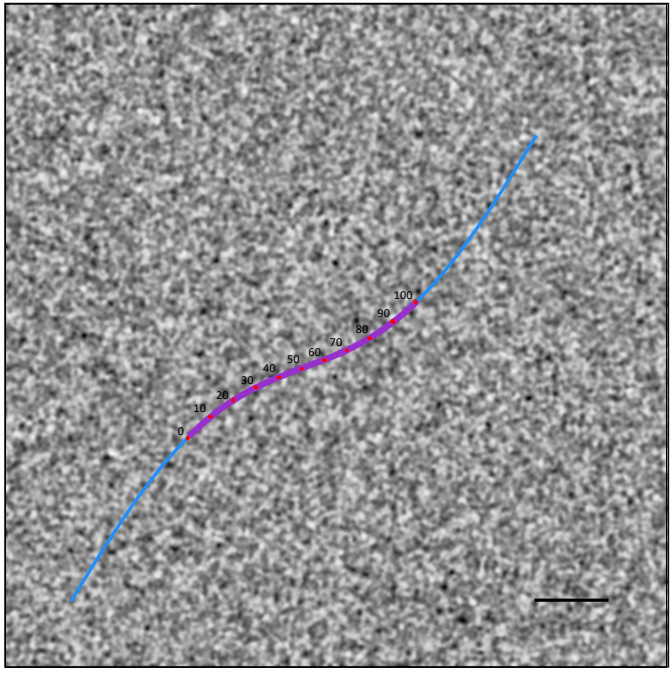


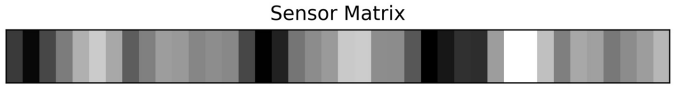
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

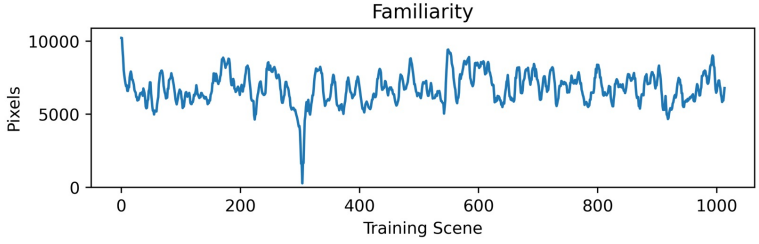
Navigation stats: RMSD error: 72.57; RMSD/dist: 0.181; TD: 6654; p90: 20; p50: 8; complete: 0

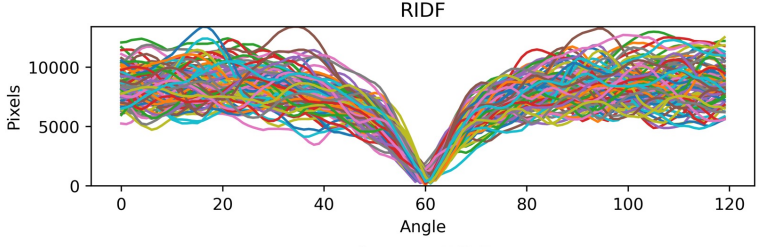

Index: BLUR: 3.0; LEVELS: 255; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

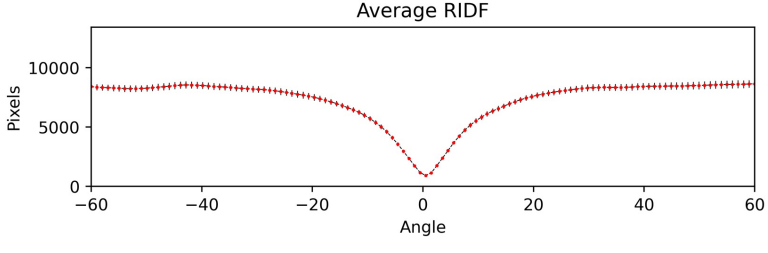
100%







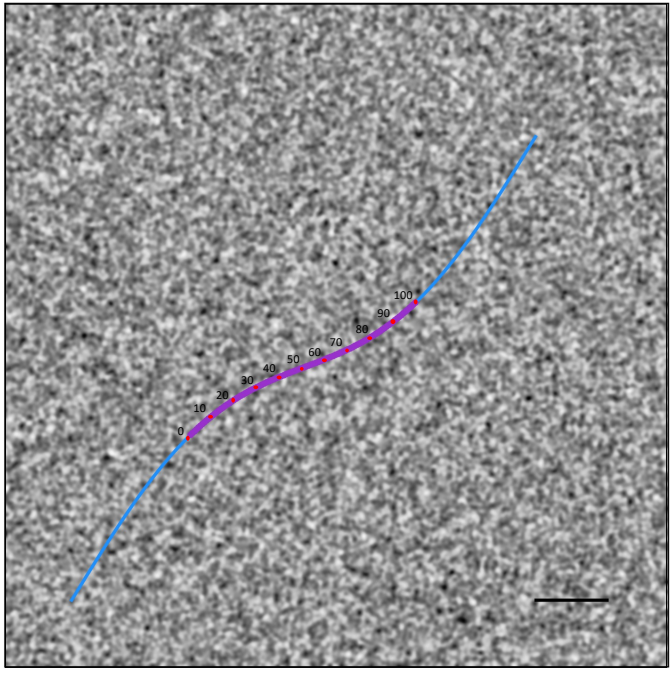


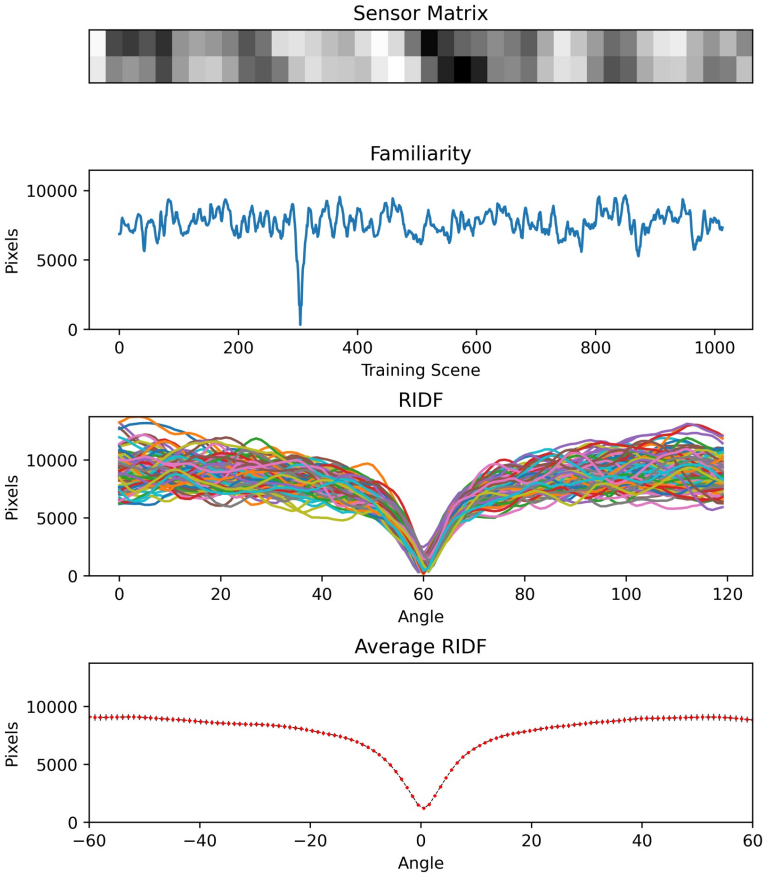


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 55.44; RMSD/dist: 0.139; TD: 5665; p90: 22; p50: 10; complete: 0

100%

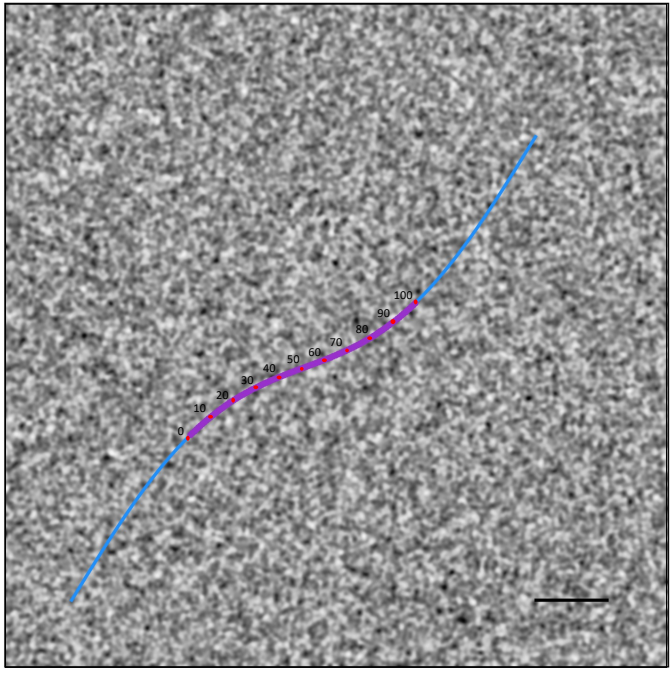


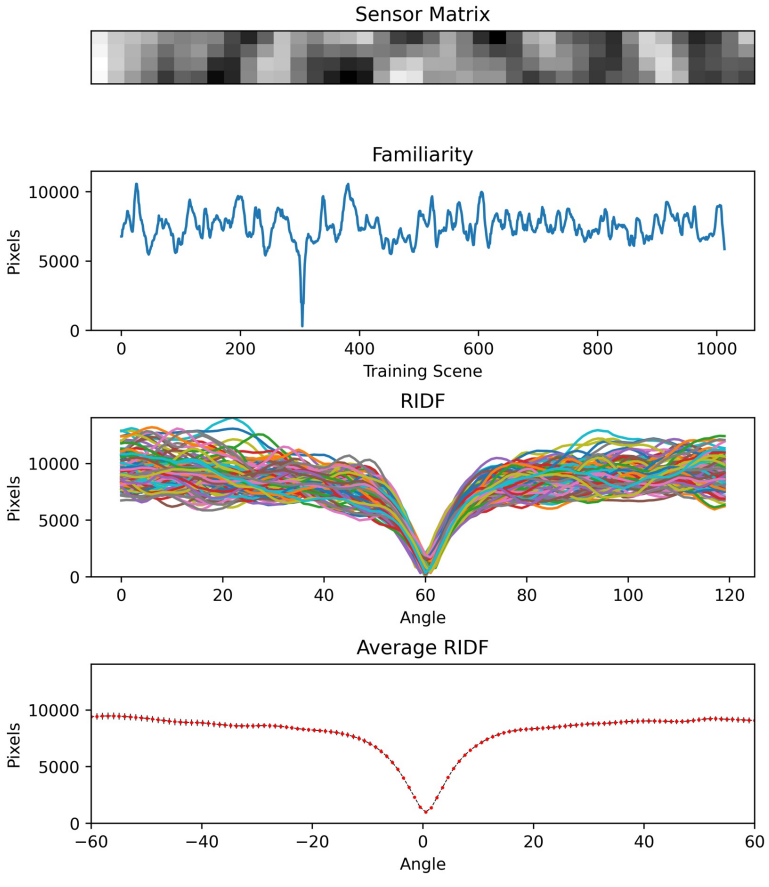


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 69.59; RMSD/dist: 0.174; TD: 6231; p90: 22; p50: 10; complete: 0

100%

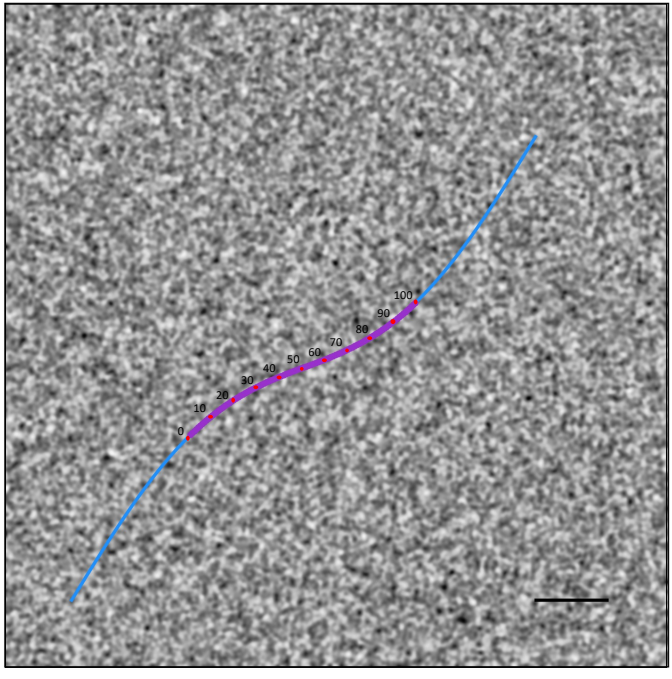


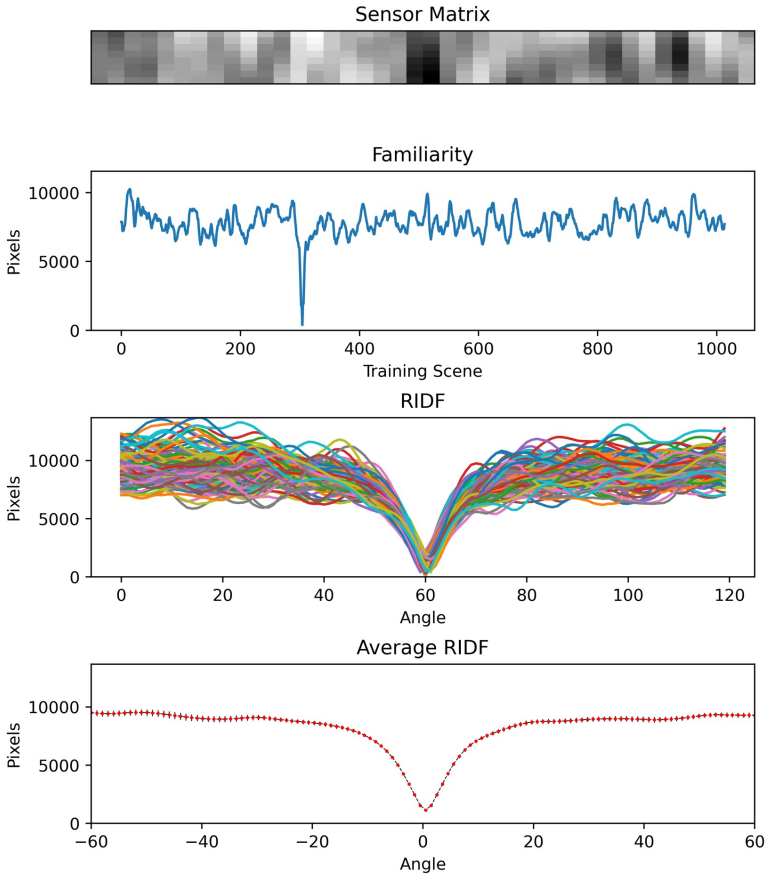


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 42.66; RMSD/dist: 0.107; TD: 6623; p90: 20; p50: 8; complete: 0

100%

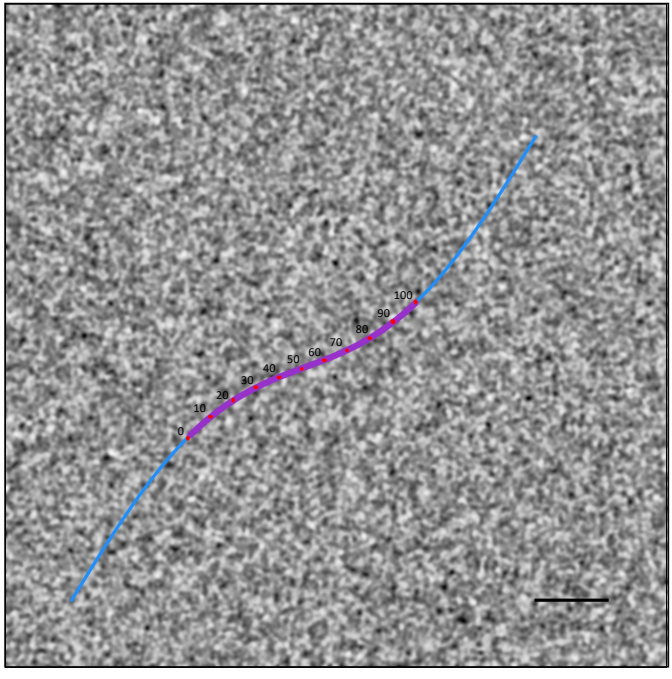


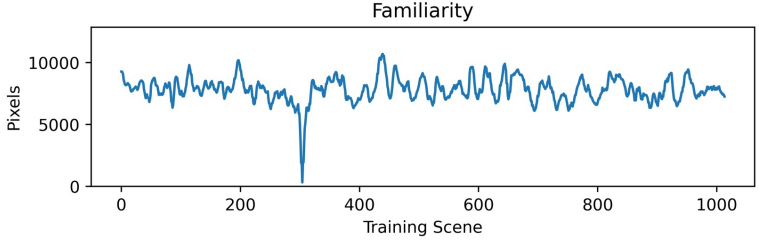


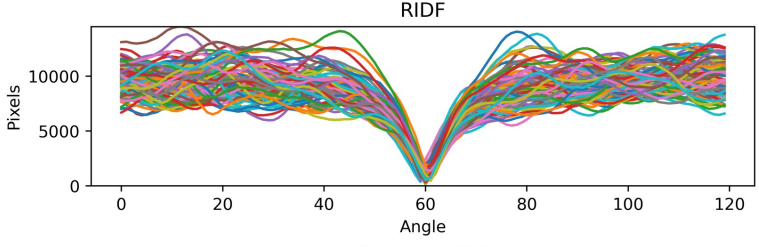
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

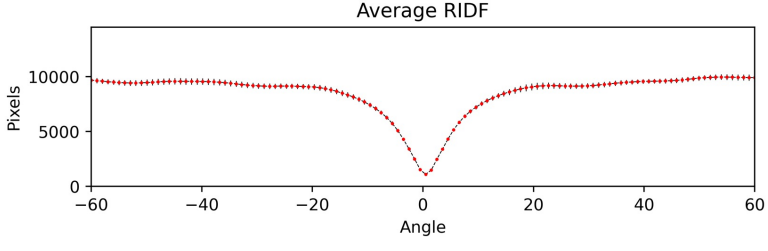
Navigation stats: RMSD error: 48.30; RMSD/dist: 0.121; TD: 6603; p90: 18; p50: 8; complete: 0

100%





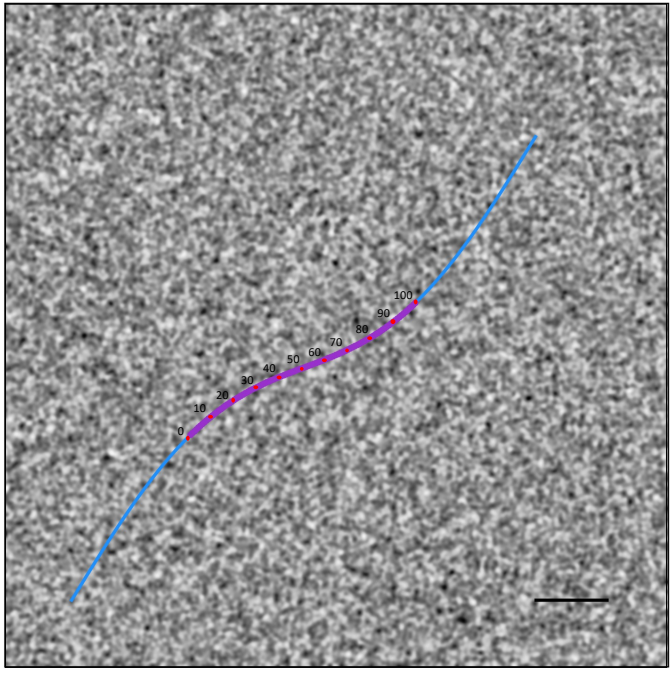


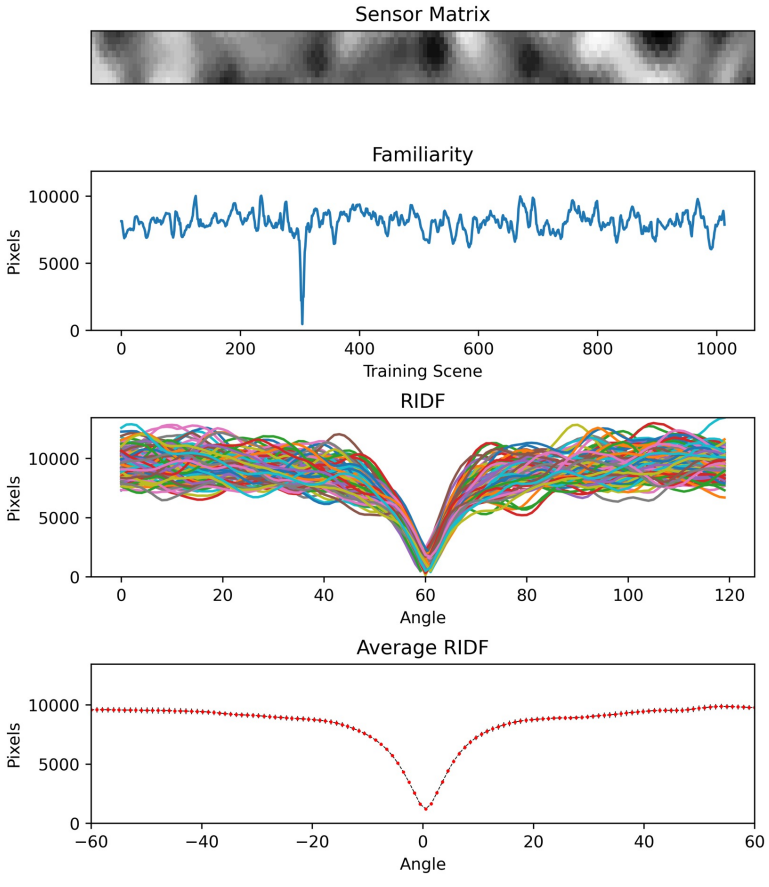


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 39.22; RMSD/dist: 0.098; TD: 6958; p90: 20; p50: 8; complete: 0

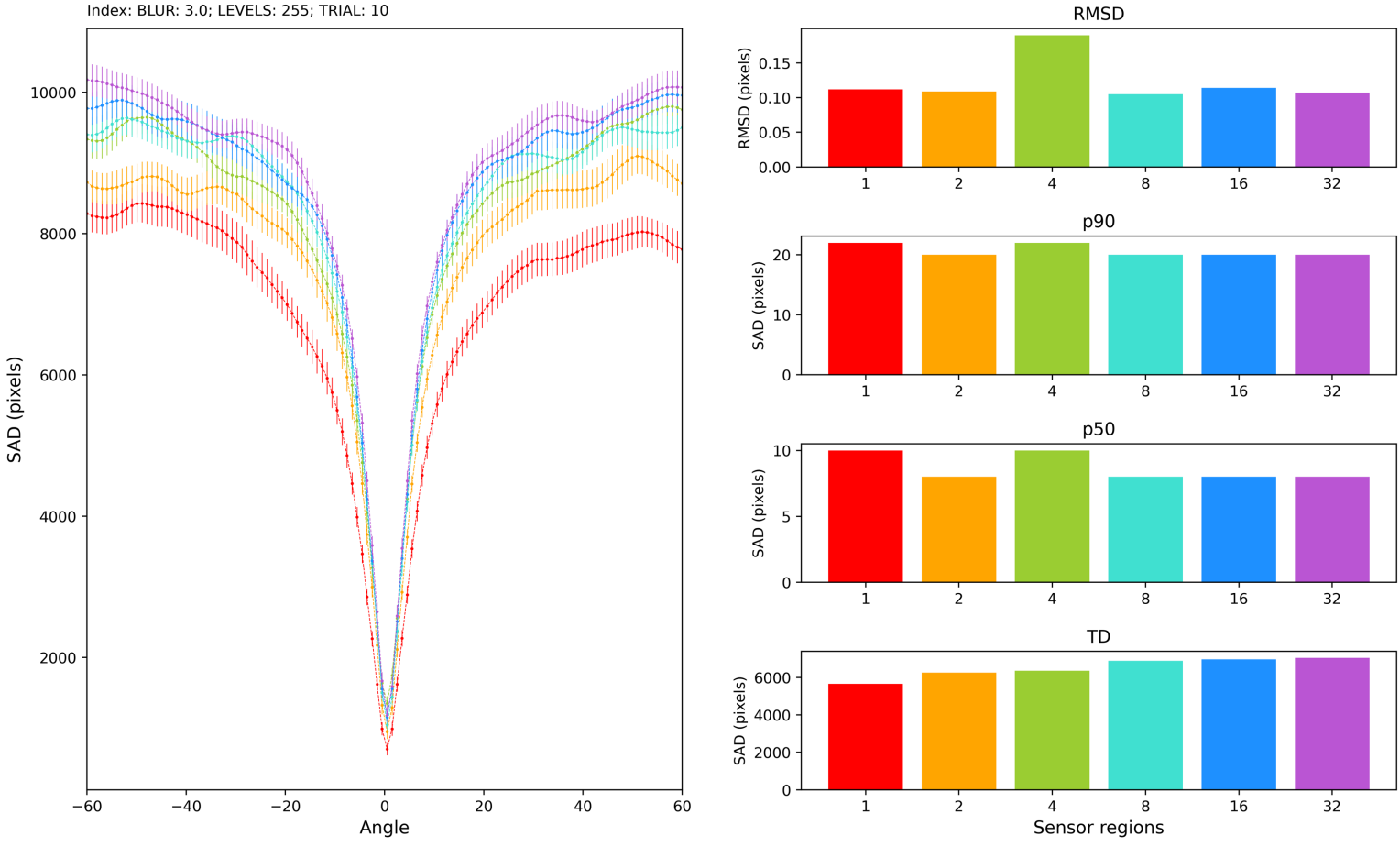
100%



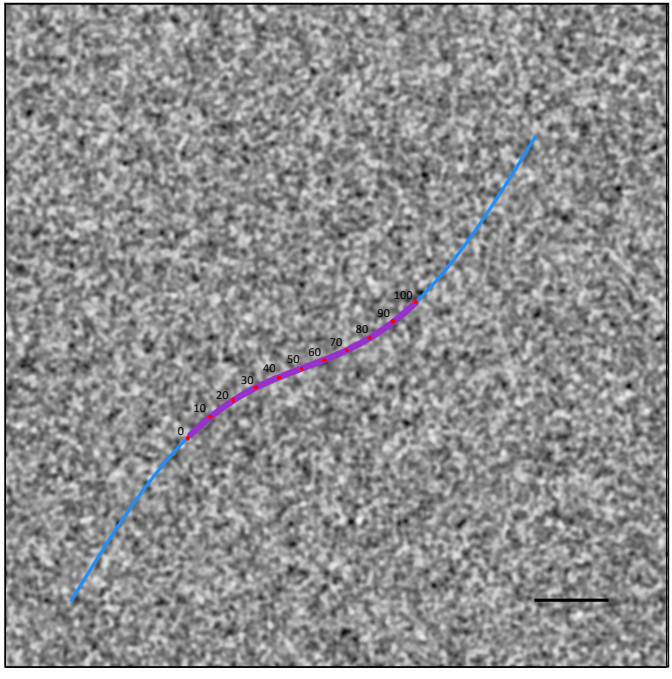


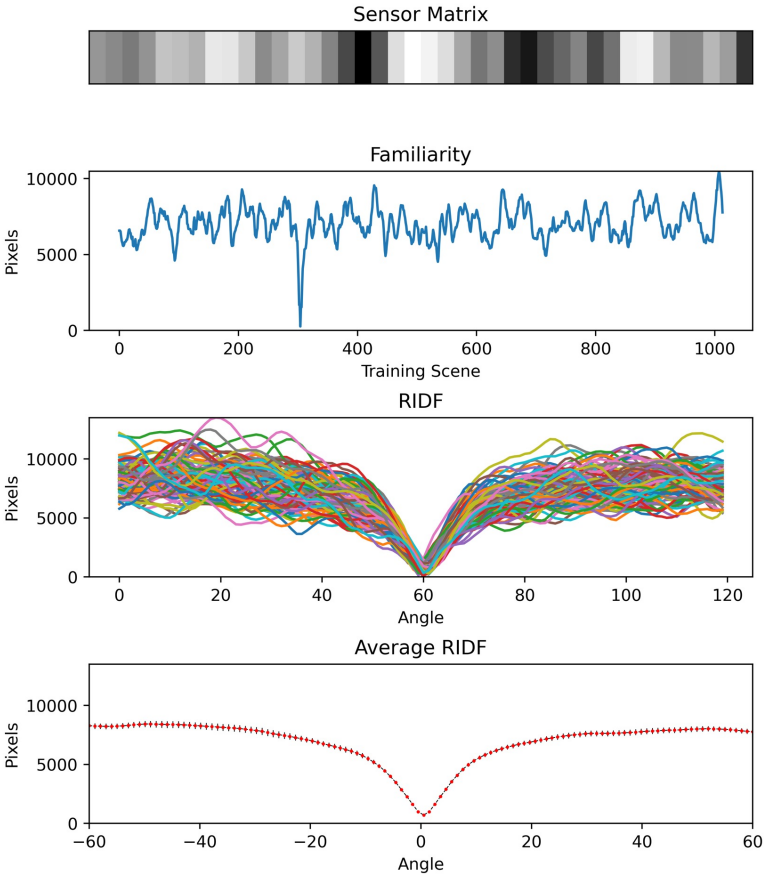
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 47.51; RMSD/dist: 0.119; TD: 6921; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

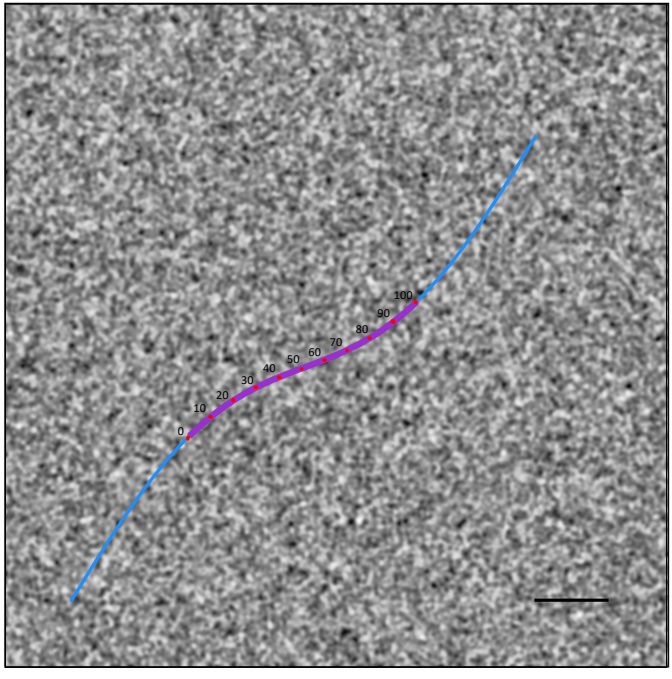


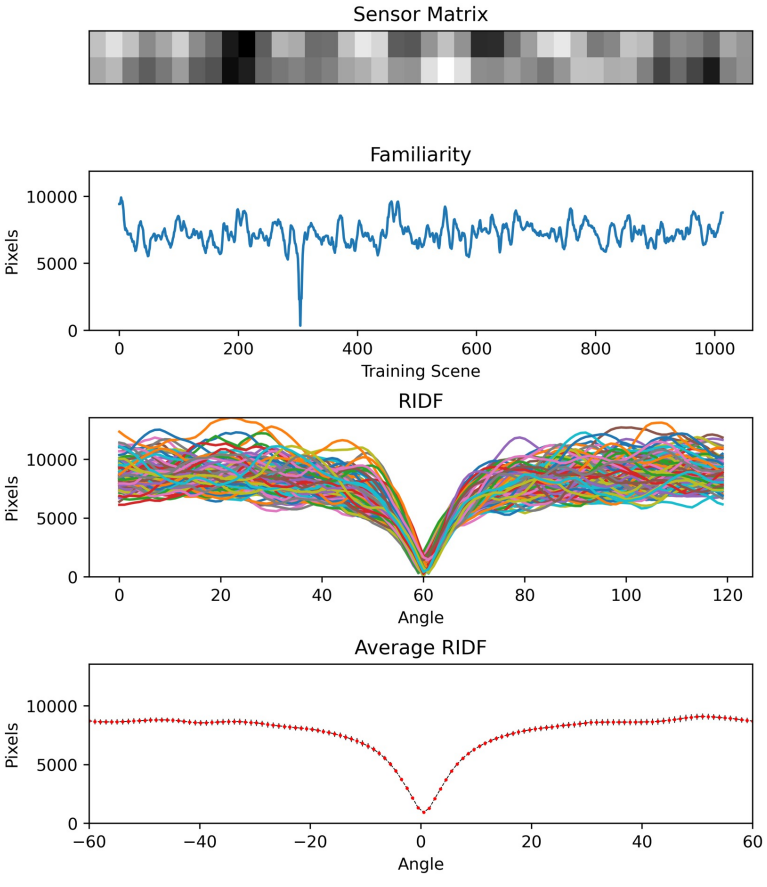


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 44.86; RMSD/dist: 0.112; TD: 5659; p90: 22; p50: 10; complete: 0

100%

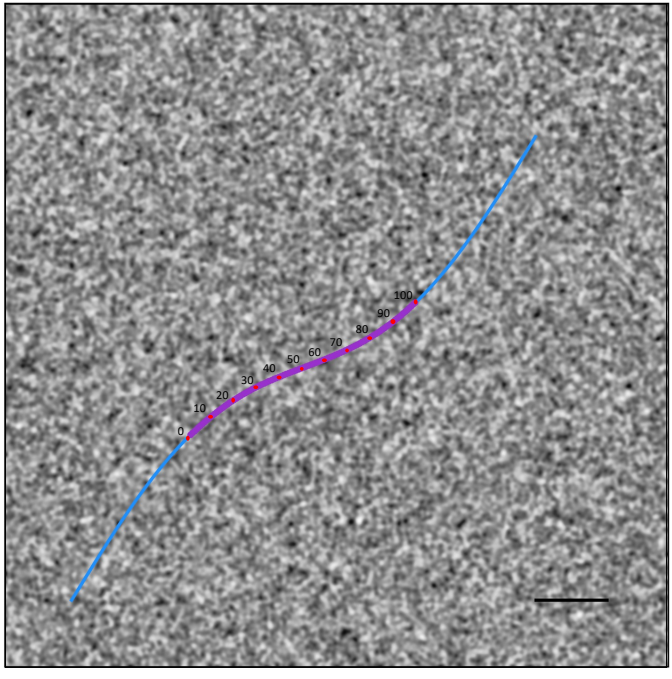


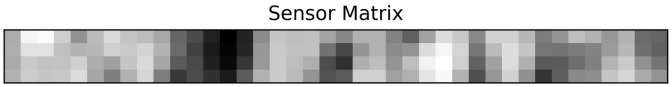


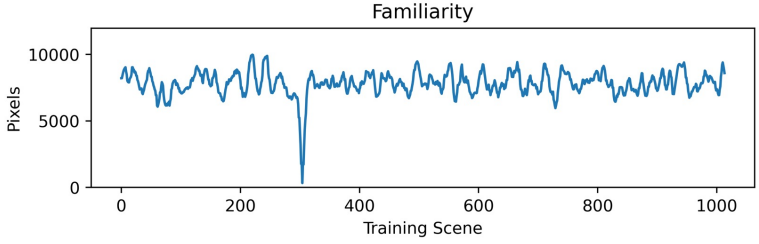
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

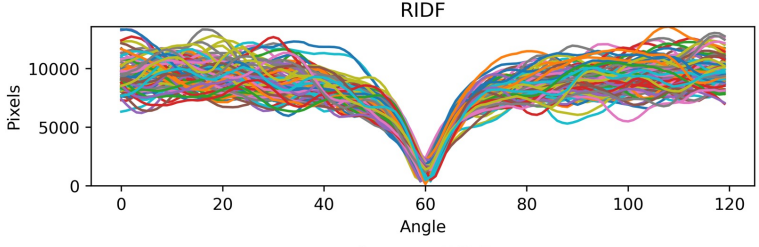
Navigation stats: RMSD error: 43.44; RMSD/dist: 0.109; TD: 6262; p90: 20; p50: 8; complete: 0

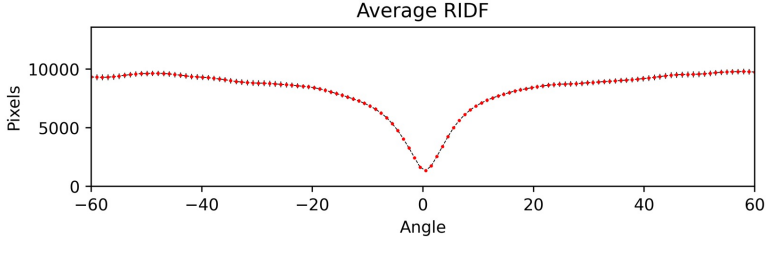
100%







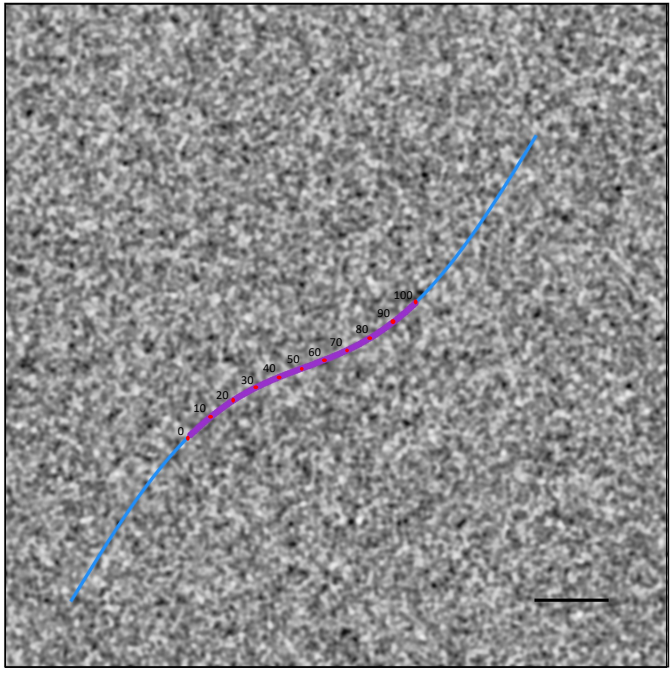


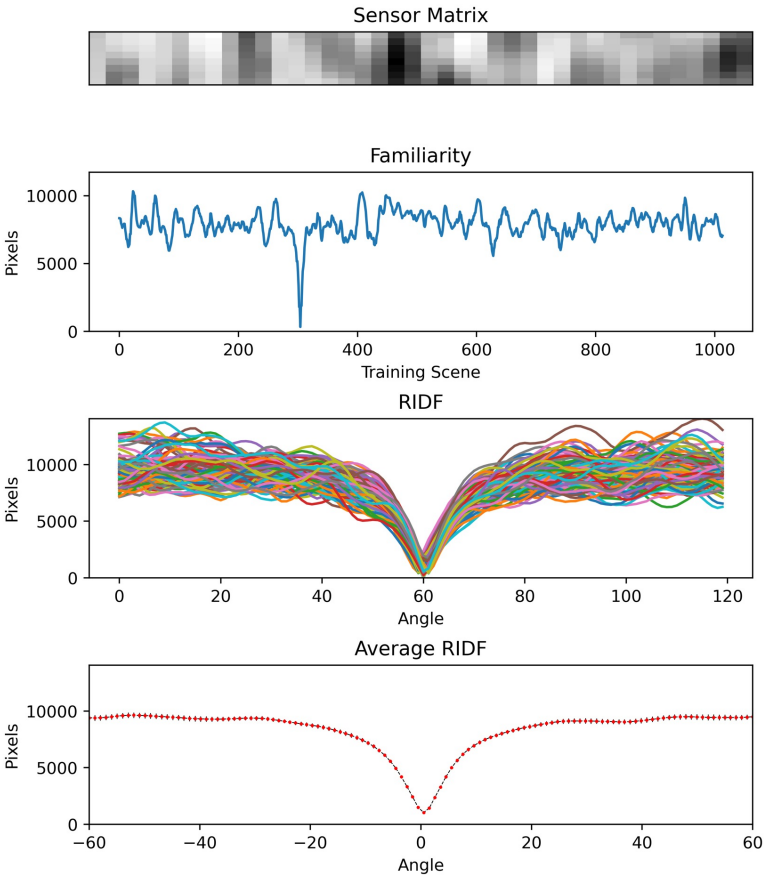


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 75.84; RMSD/dist: 0.190; TD: 6363; p90: 22; p50: 10; complete: 0

100%

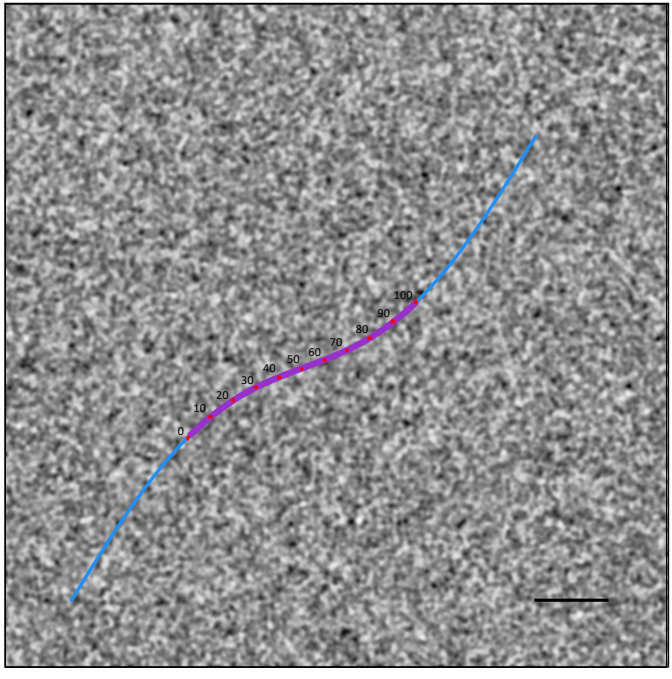


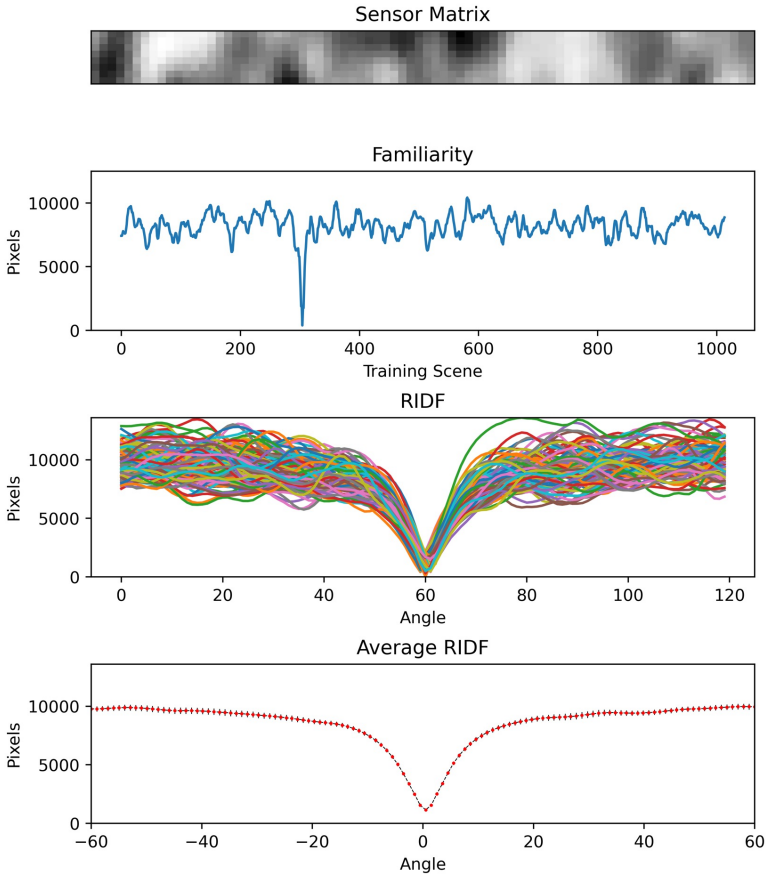


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 41.96; RMSD/dist: 0.105; TD: 6888; p90: 20; p50: 8; complete: 0

100%

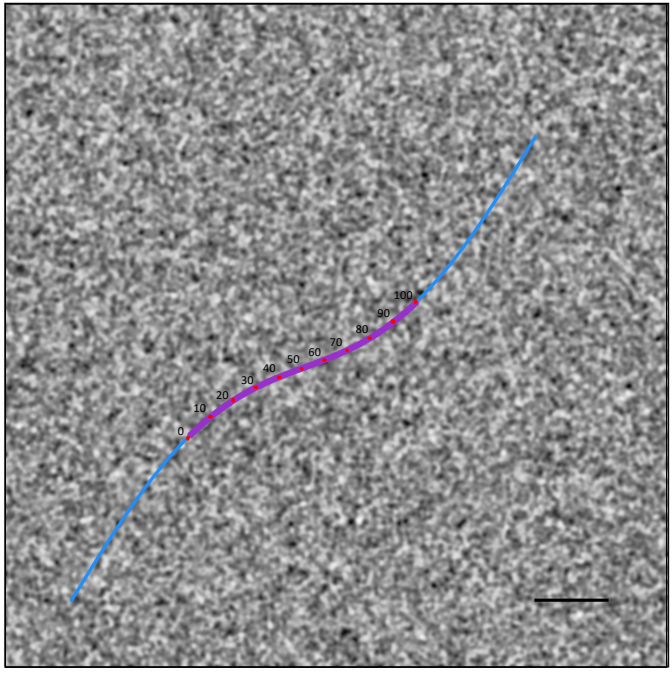


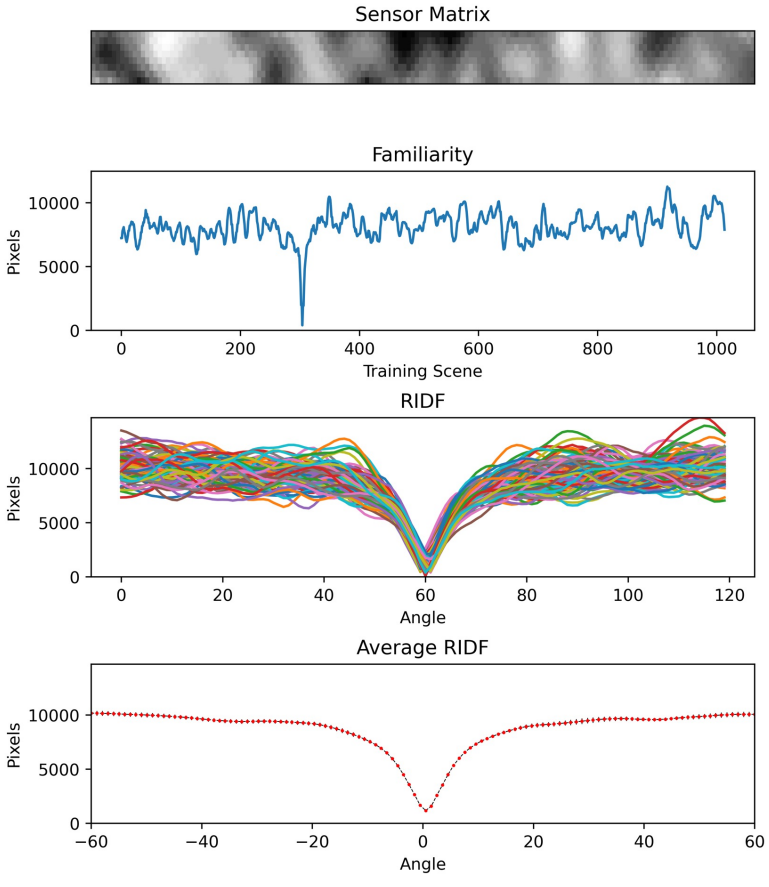


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 45.53; RMSD/dist: 0.114; TD: 6964; p90: 20; p50: 8; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 42.95; RMSD/dist: 0.107; TD: 7043; p90: 20; p50: 8; complete: 0