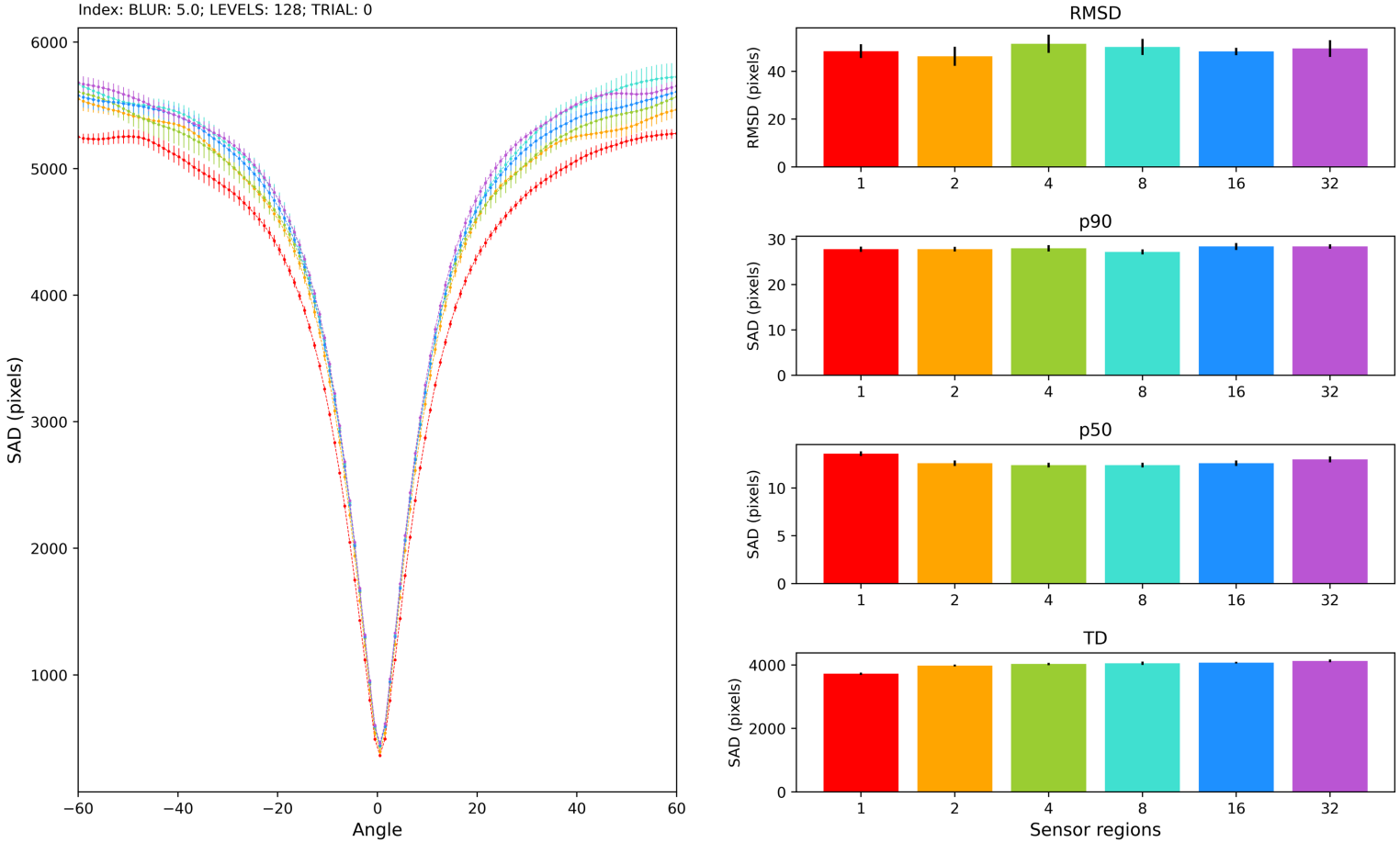
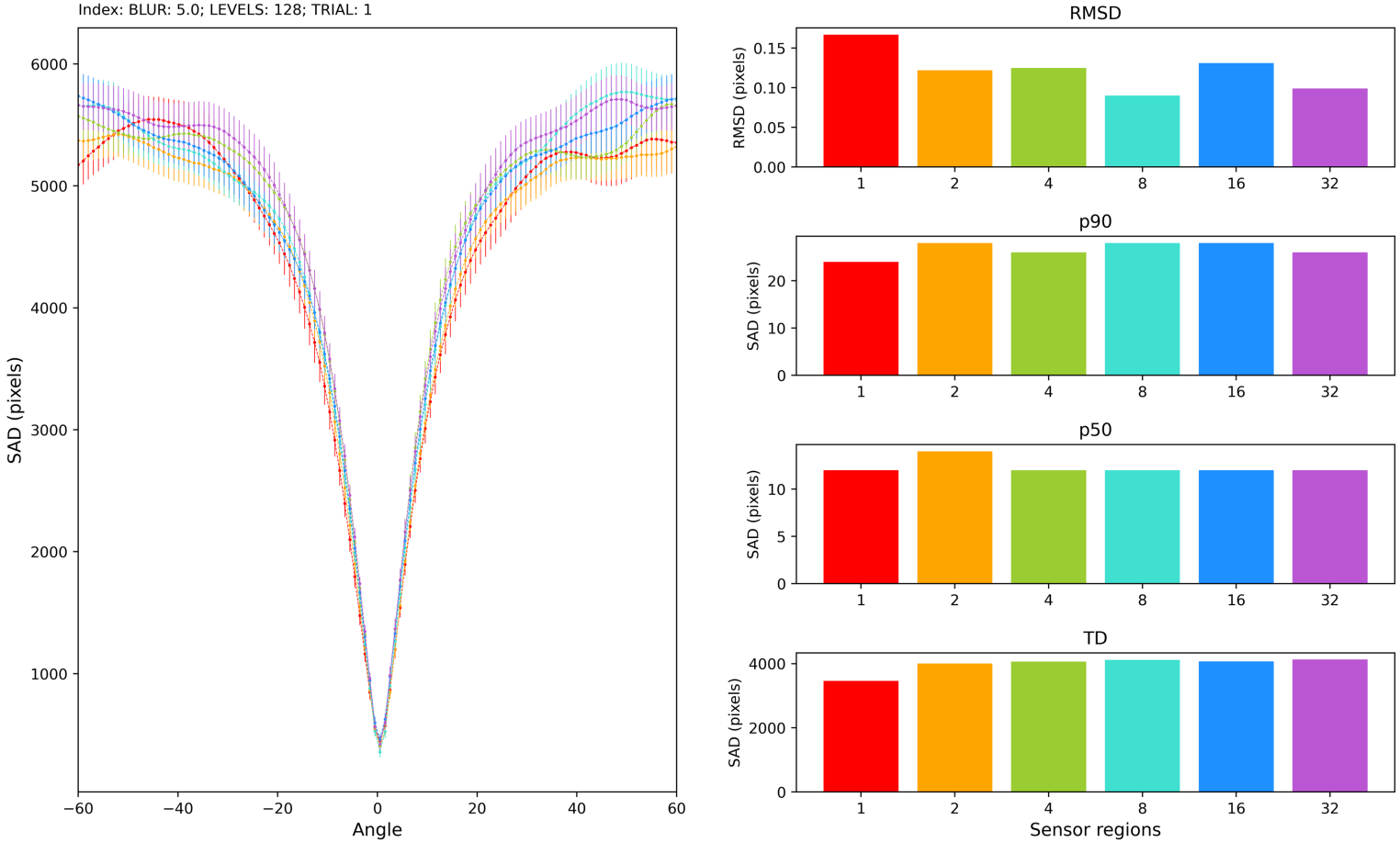
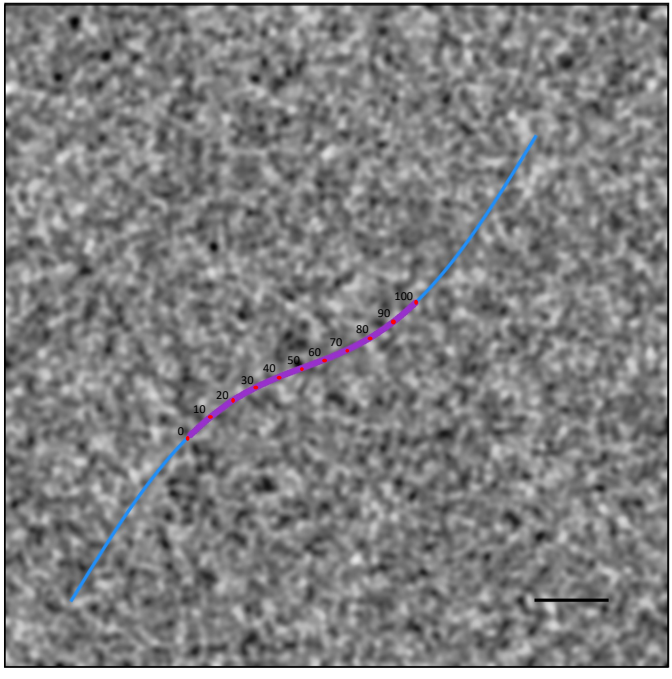
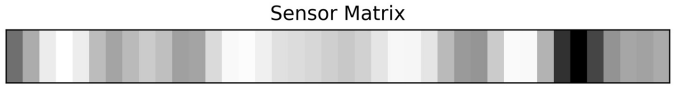
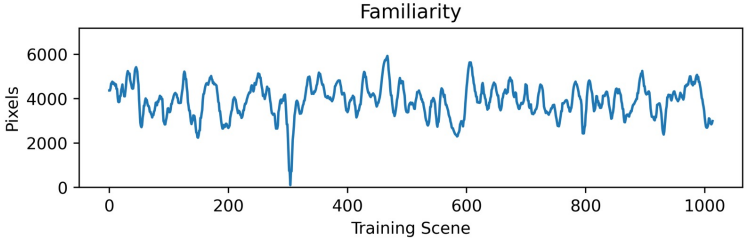

Index: BLUR: 5.0; LEVELS: 128; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

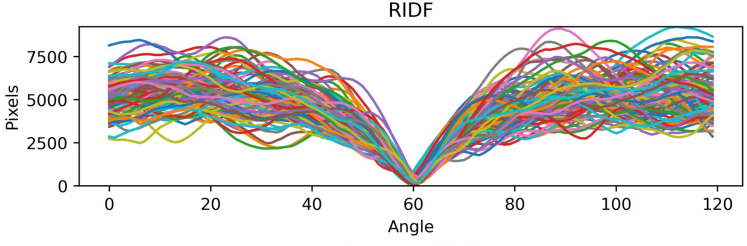

Index: BLUR: 5.0; LEVELS: 128; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

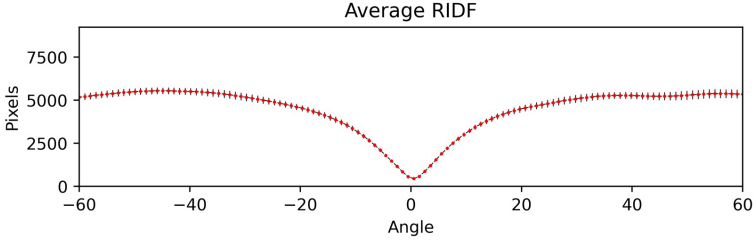
100%







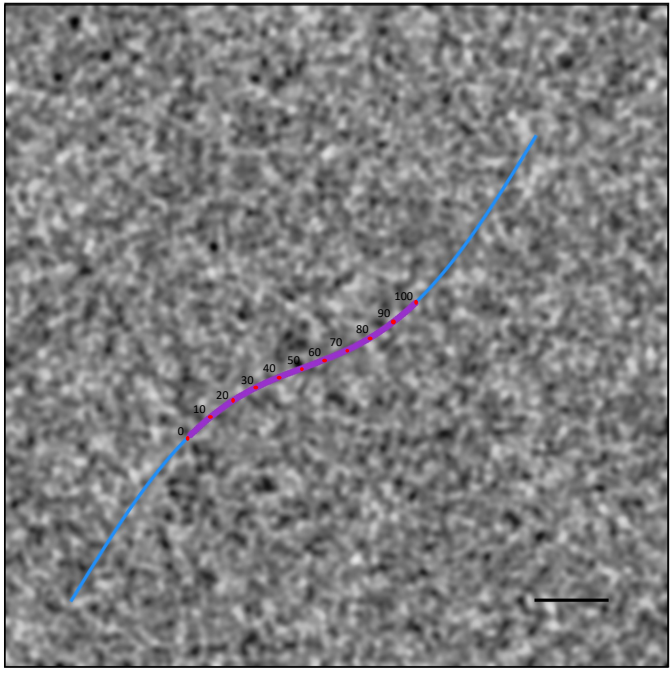


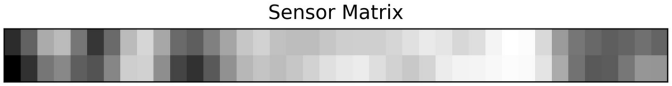


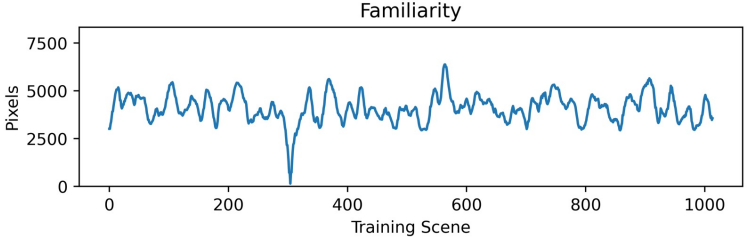
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

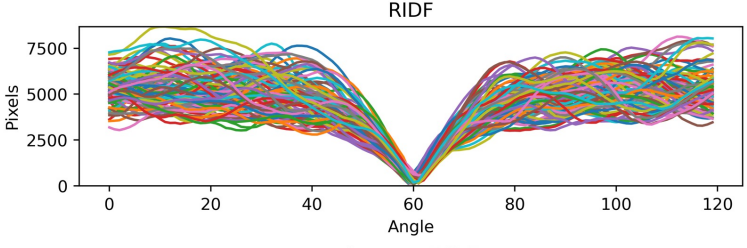
Navigation stats: RMSD error: 66.64; RMSD/dist: 0.167; TD: 3463; p90: 24; p50: 12; complete: 0

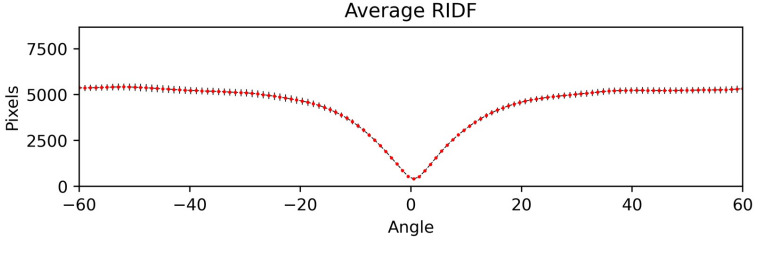
100%







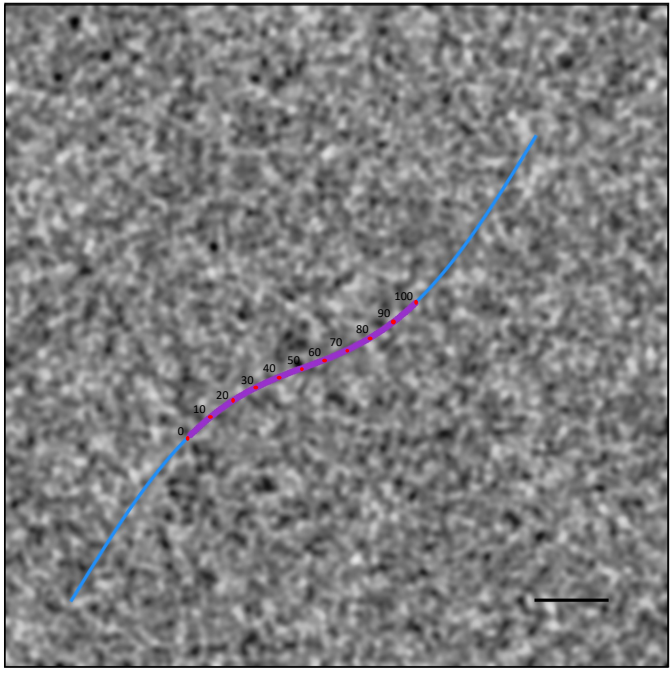


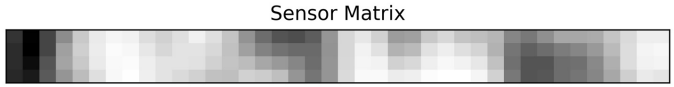


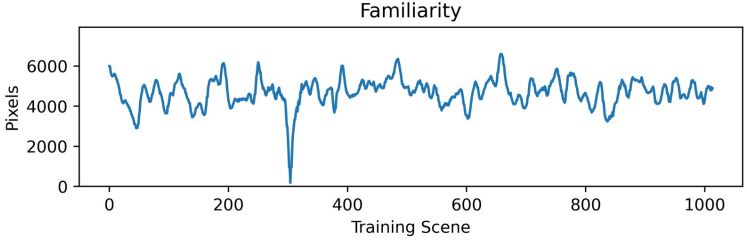
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

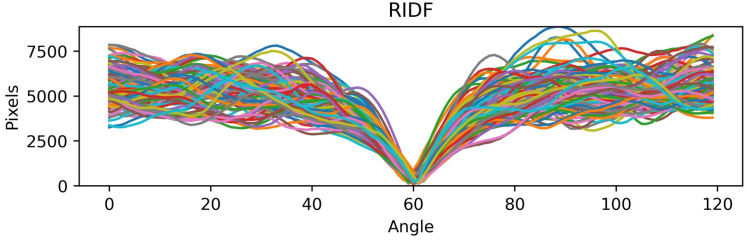
Navigation stats: RMSD error: 48.79; RMSD/dist: 0.122; TD: 4005; p90: 28; p50: 14; complete: 0

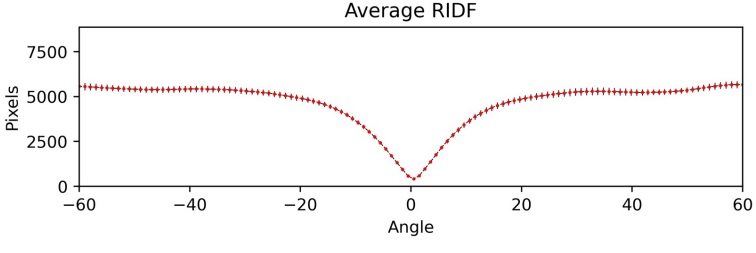
100%







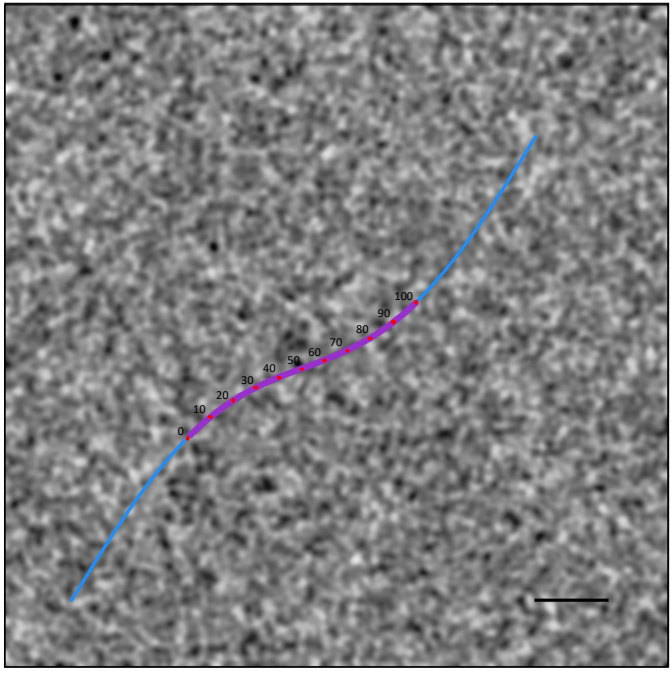


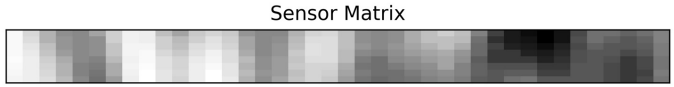


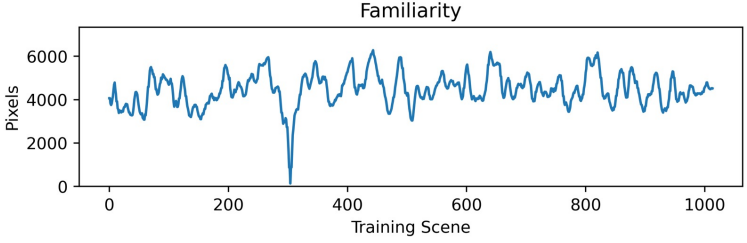
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

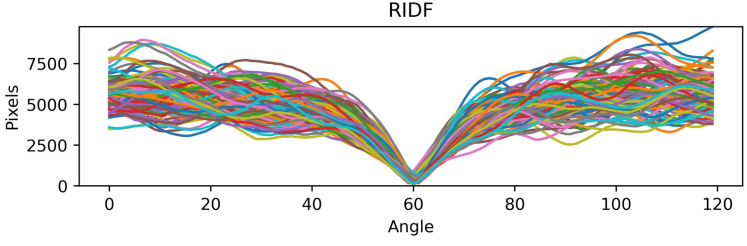
Navigation stats: RMSD error: 49.91; RMSD/dist: 0.125; TD: 4063; p90: 26; p50: 12; complete: 0

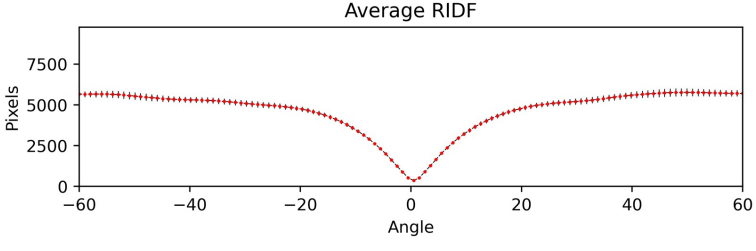
100%







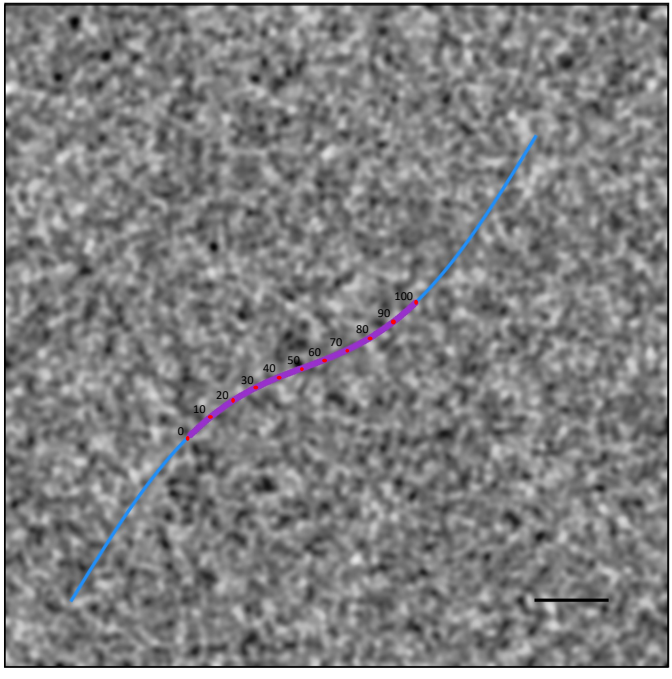


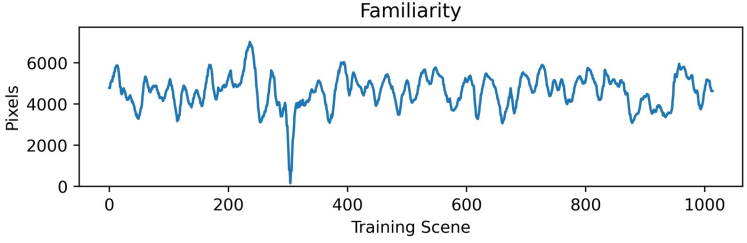


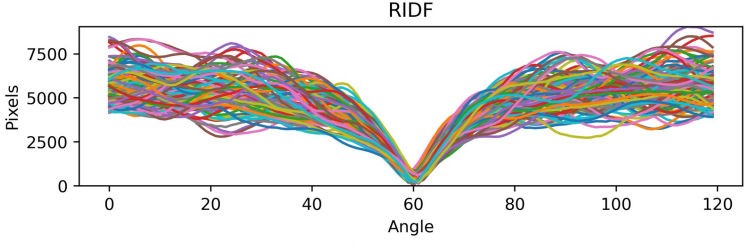
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

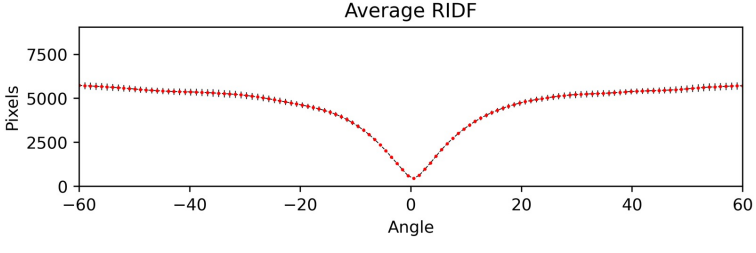
Navigation stats: RMSD error: 36.19; RMSD/dist: 0.090; TD: 4119; p90: 28; p50: 12; complete: 0

100%





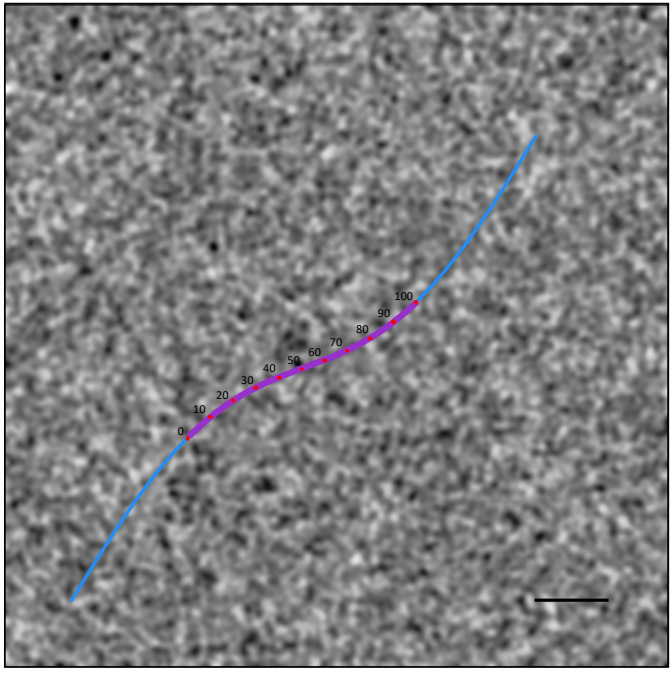


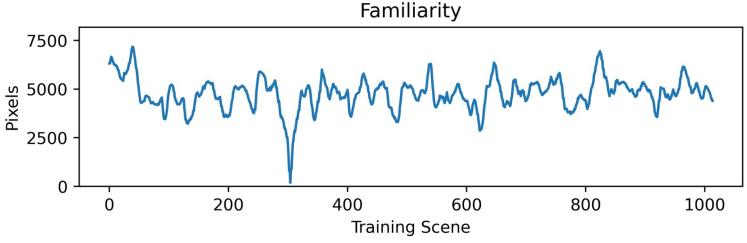


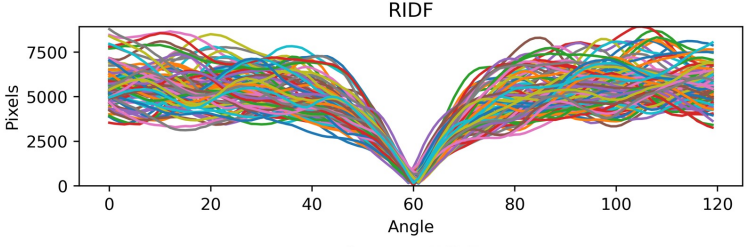
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

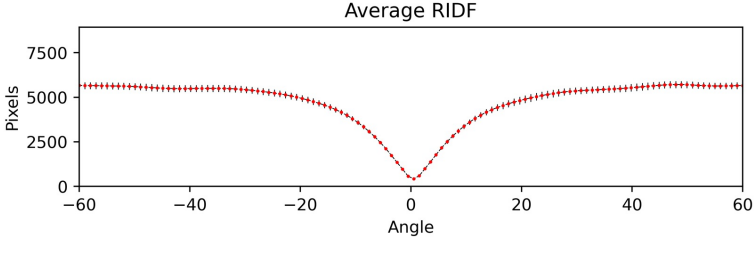
Navigation stats: RMSD error: 52.36; RMSD/dist: 0.131; TD: 4068; p90: 28; p50: 12; complete: 0

100%



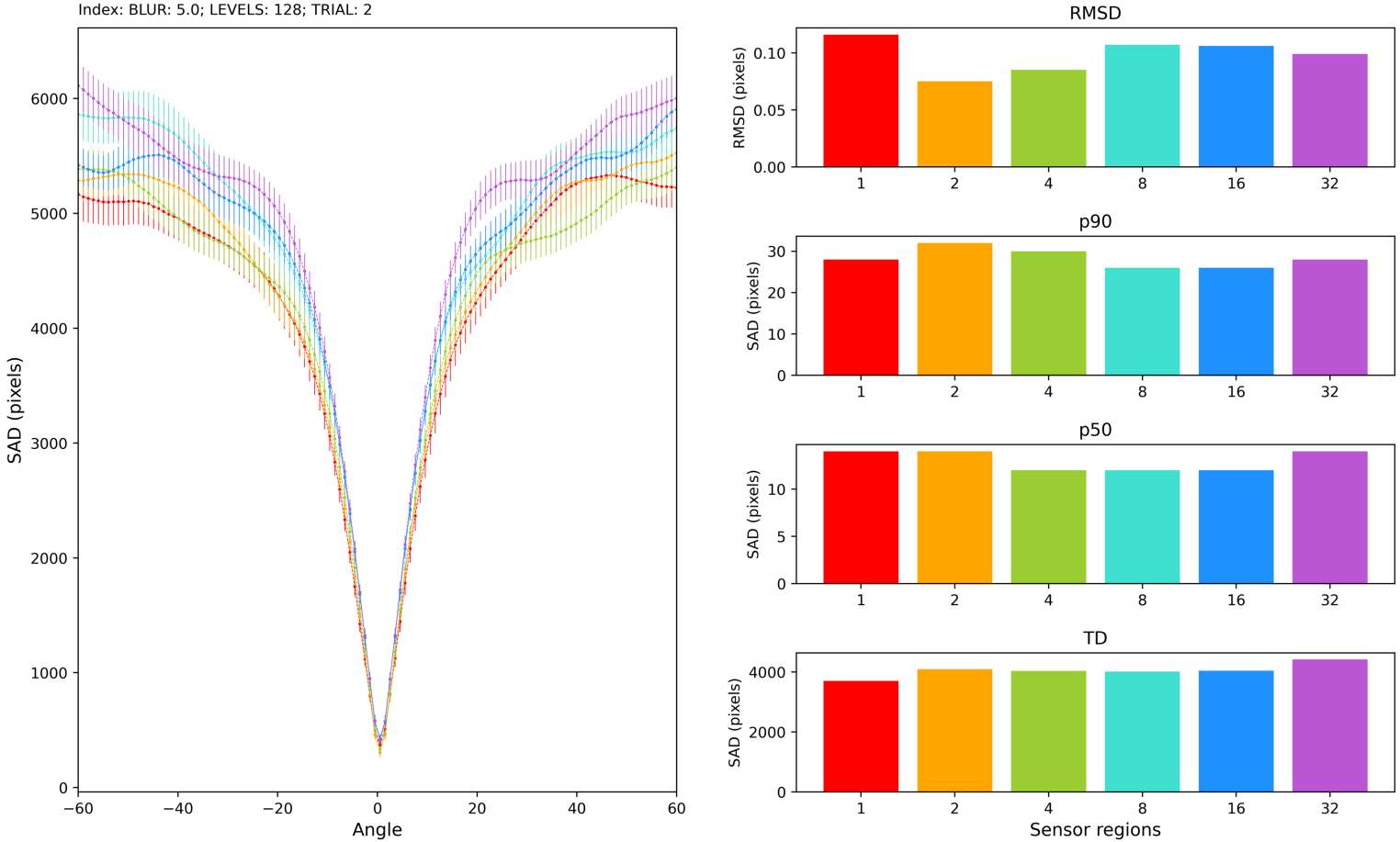




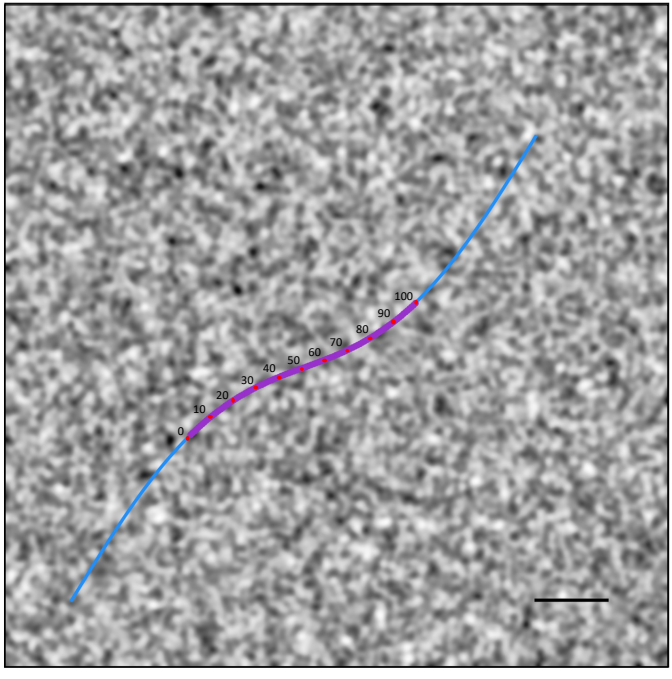


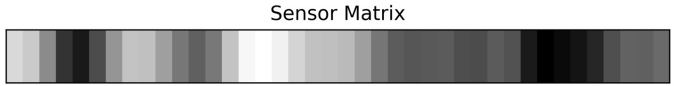
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

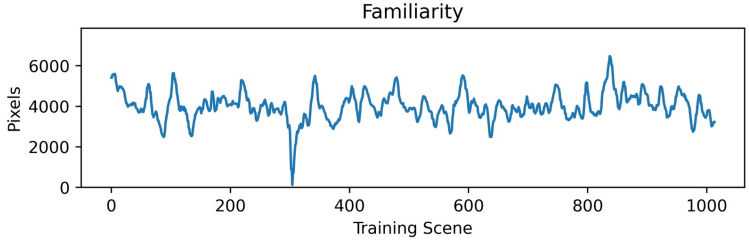
Navigation stats: RMSD error: 39.72; RMSD/dist: 0.099; TD: 4126; p90: 26; p50: 12; complete: 0

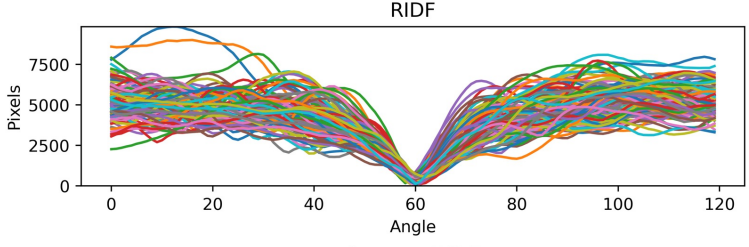

Index: BLUR: 5.0; LEVELS: 128; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

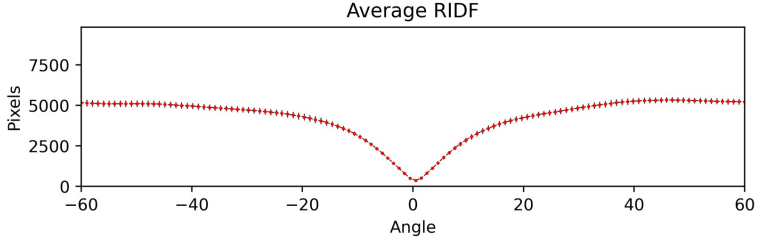
100%







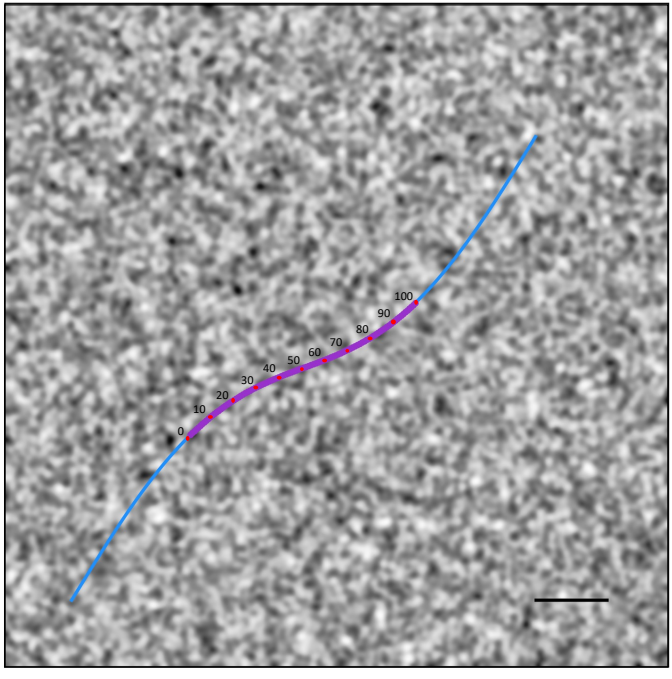


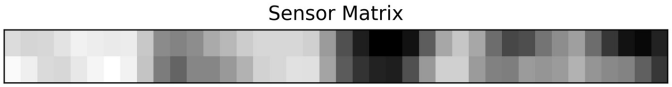


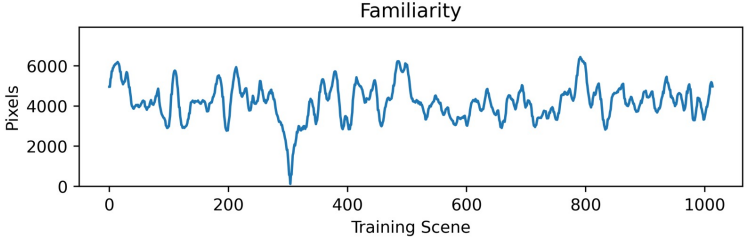
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

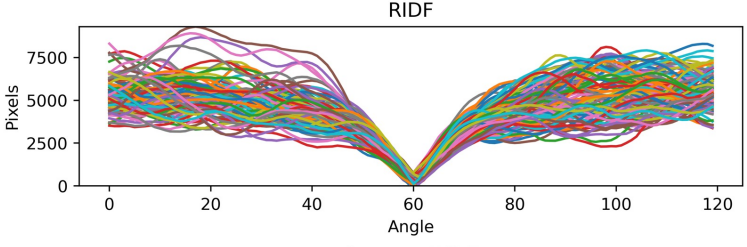
Navigation stats: RMSD error: 46.39; RMSD/dist: 0.116; TD: 3705; p90: 28; p50: 14; complete: 0

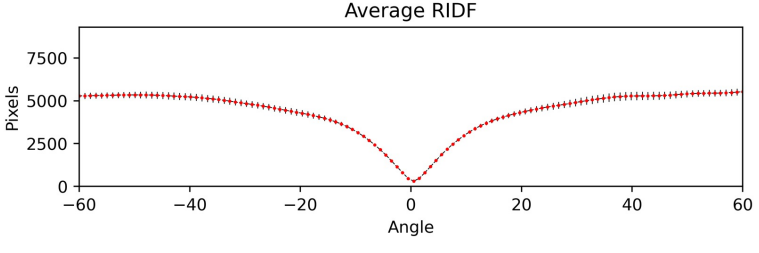
100%







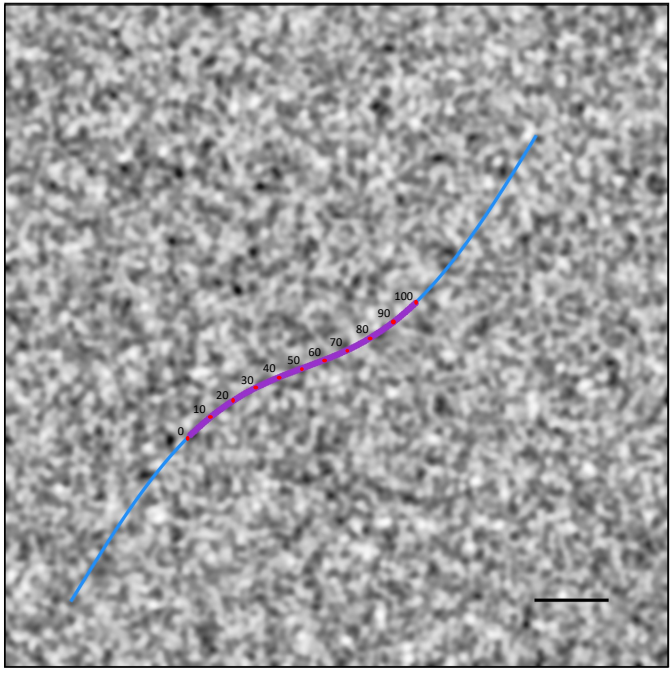


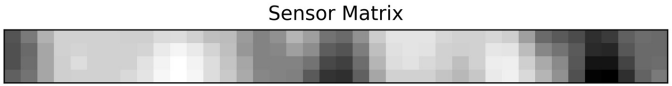


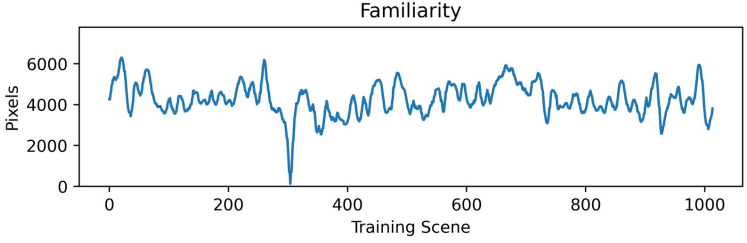
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

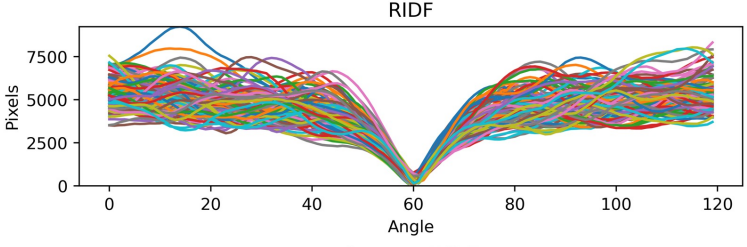
Navigation stats: RMSD error: 30.02; RMSD/dist: 0.075; TD: 4097; p90: 32; p50: 14; complete: 0

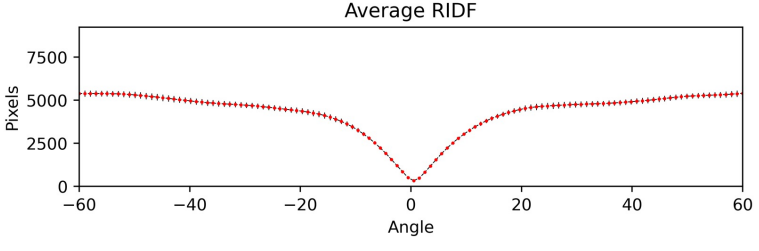
100%







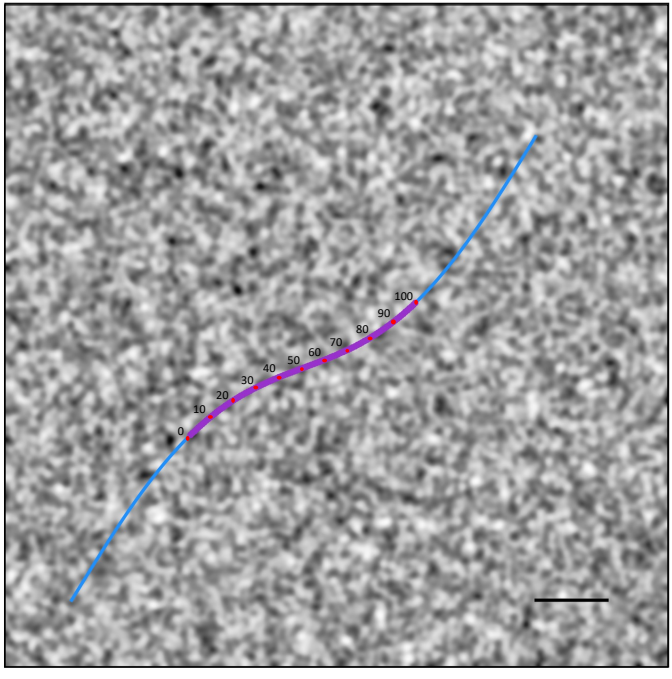


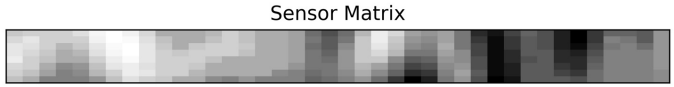


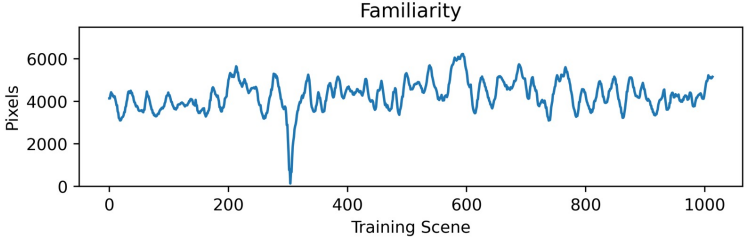
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

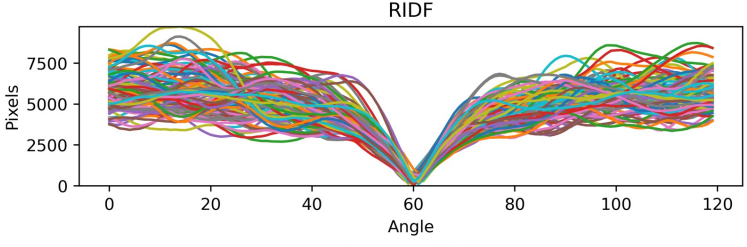
Navigation stats: RMSD error: 33.94; RMSD/dist: 0.085; TD: 4037; p90: 30; p50: 12; complete: 0

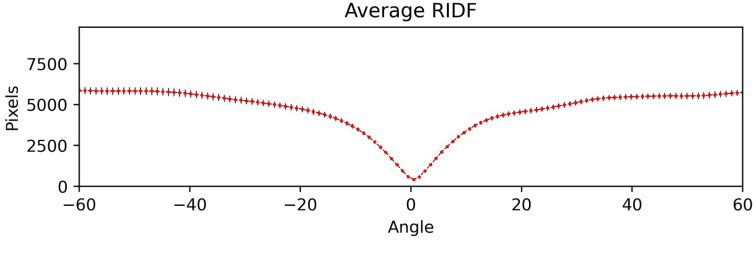
100%







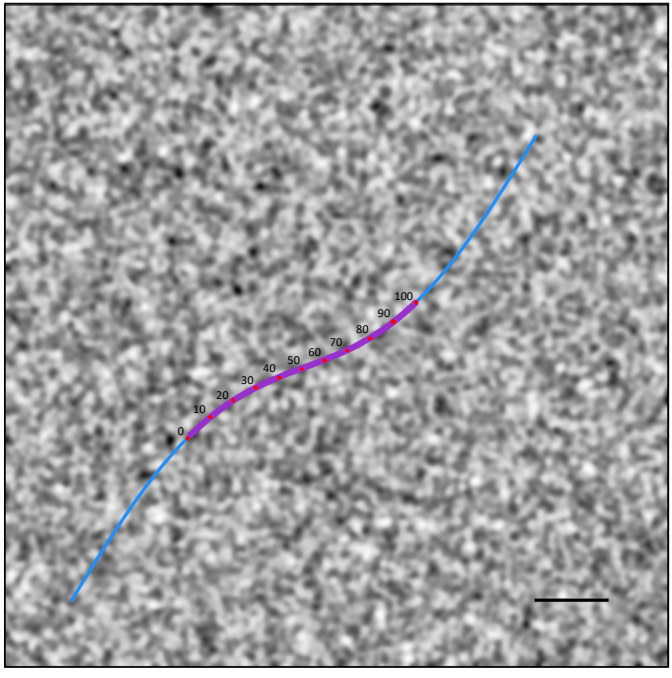


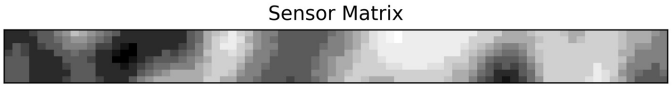


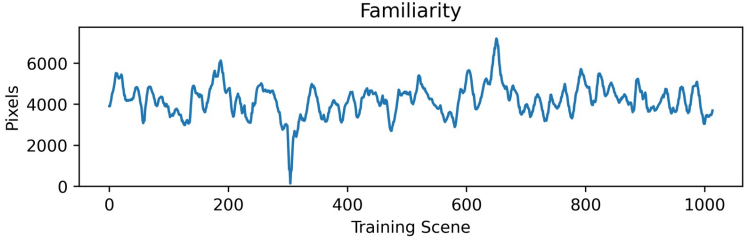
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

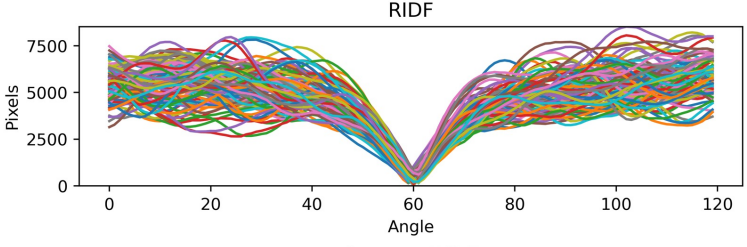
Navigation stats: RMSD error: 42.99; RMSD/dist: 0.107; TD: 4018; p90: 26; p50: 12; complete: 0

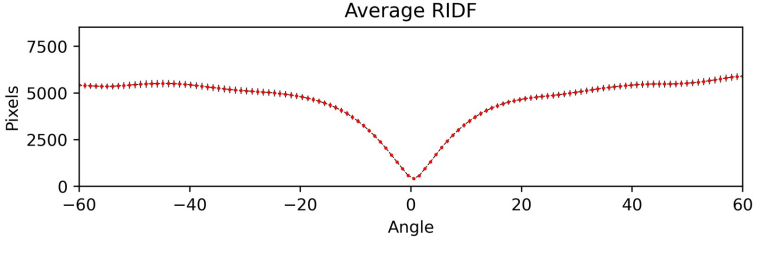
100%







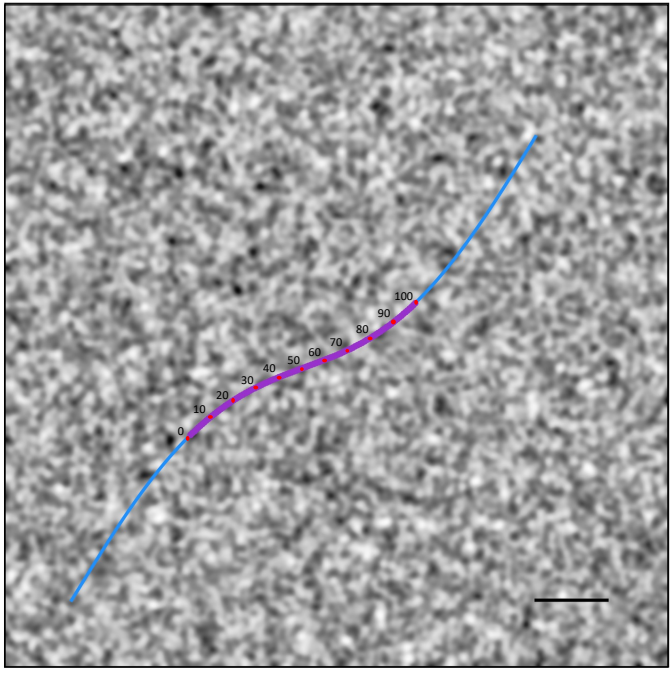


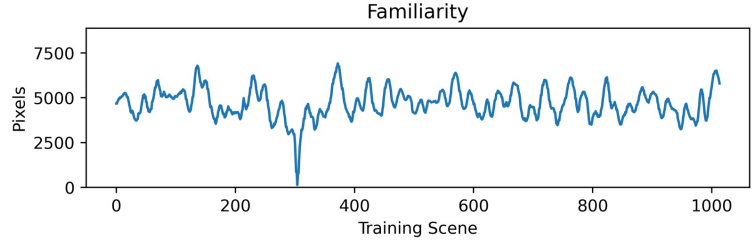


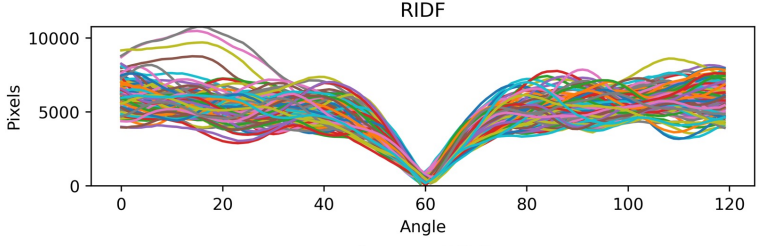
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

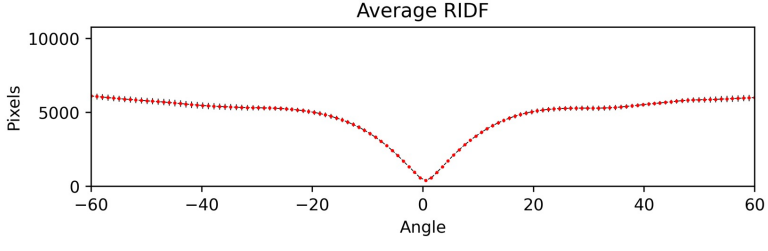
Navigation stats: RMSD error: 42.38; RMSD/dist: 0.106; TD: 4043; p90: 26; p50: 12; complete: 0

100%



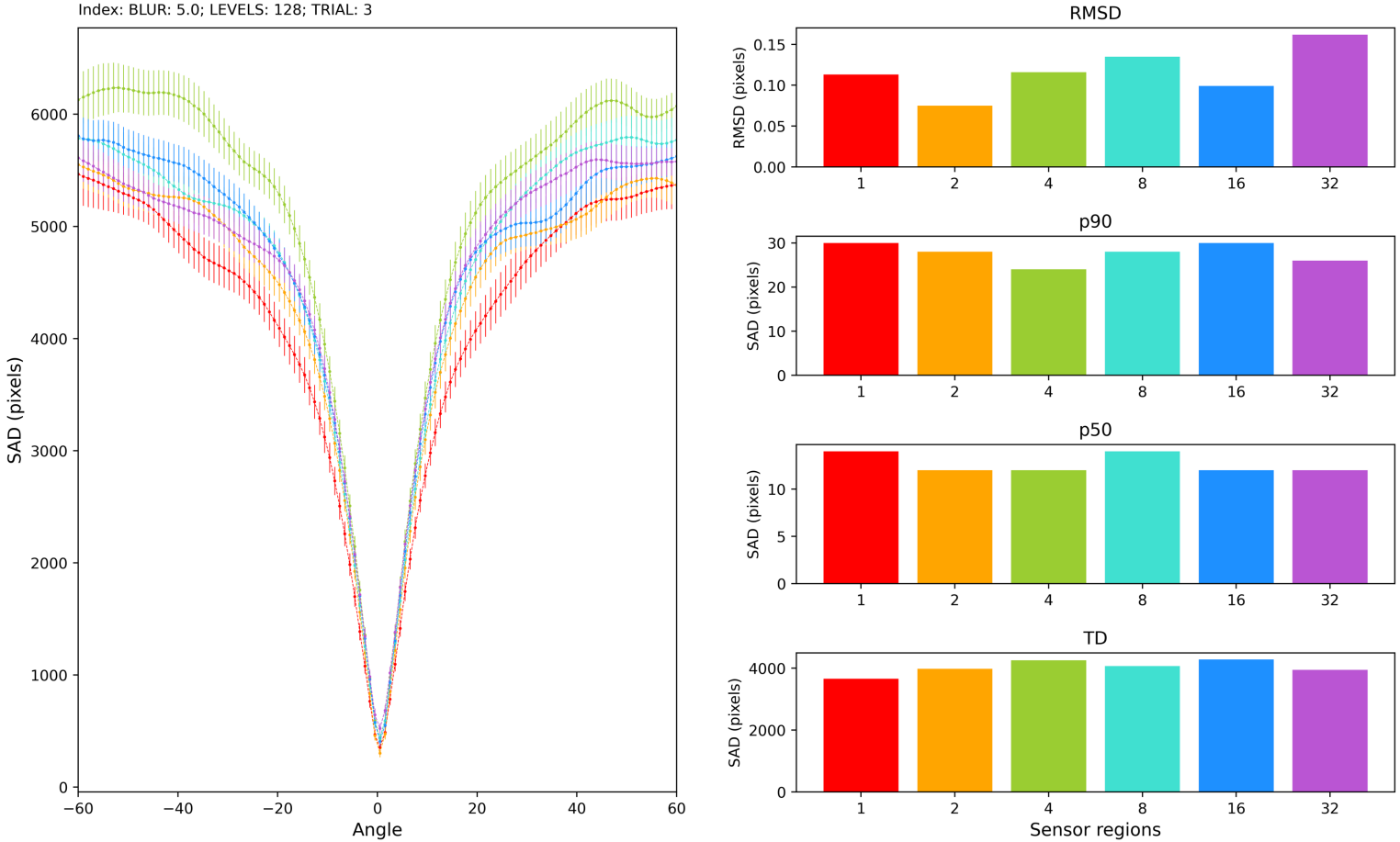




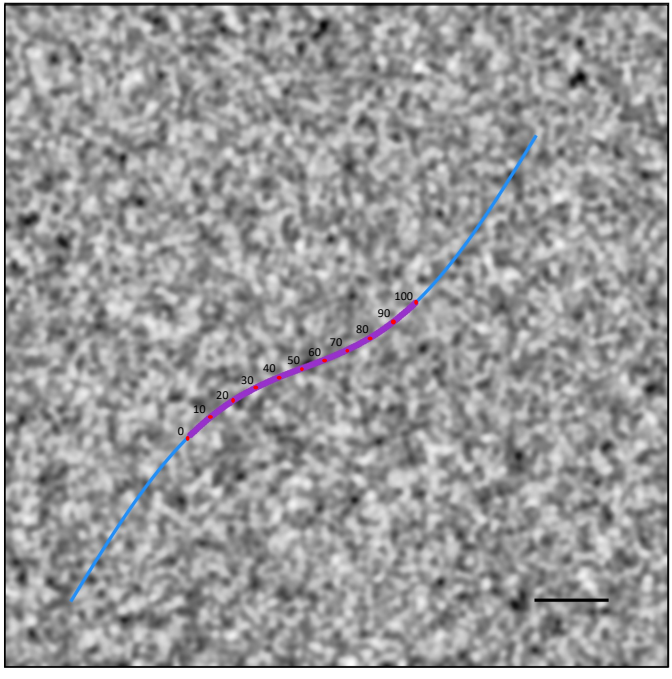


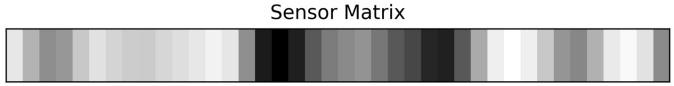
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

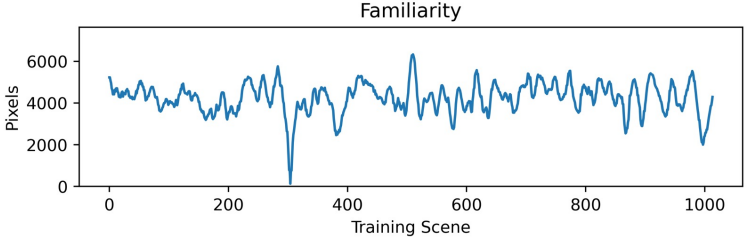
Navigation stats: RMSD error: 39.50; RMSD/dist: 0.099; TD: 4417; p90: 28; p50: 14; complete: 0

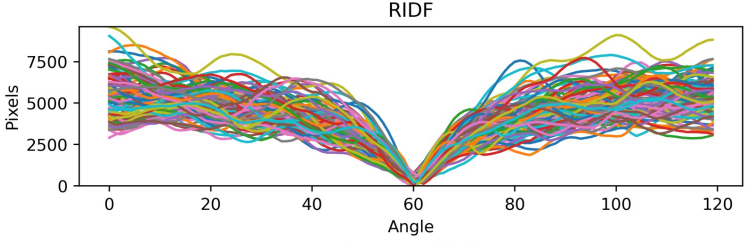

Index: BLUR: 5.0; LEVELS: 128; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

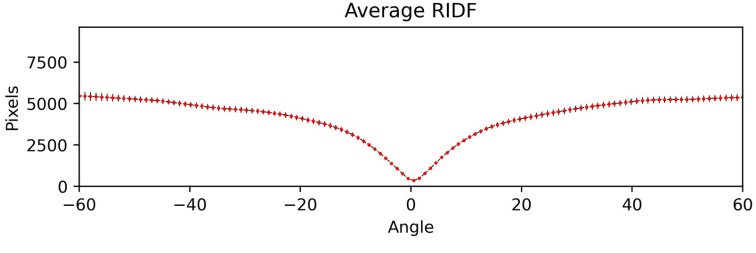
100%







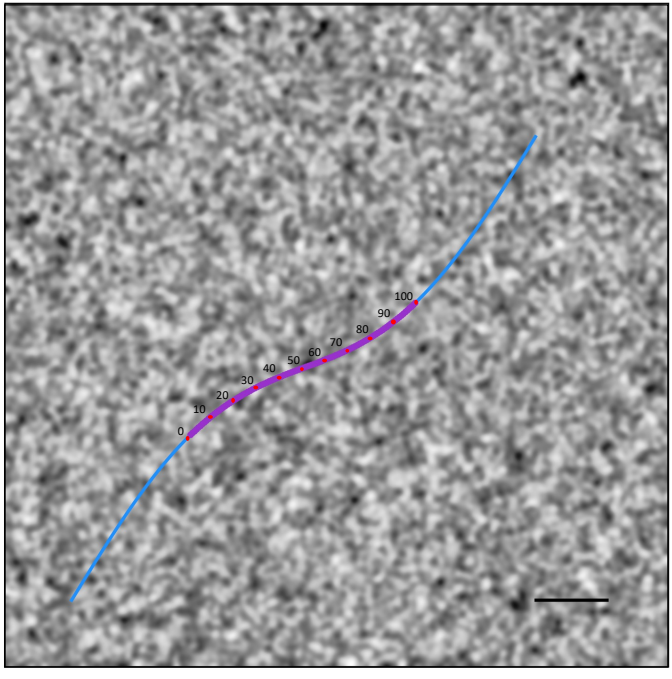


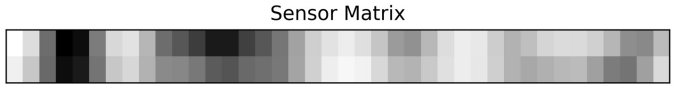


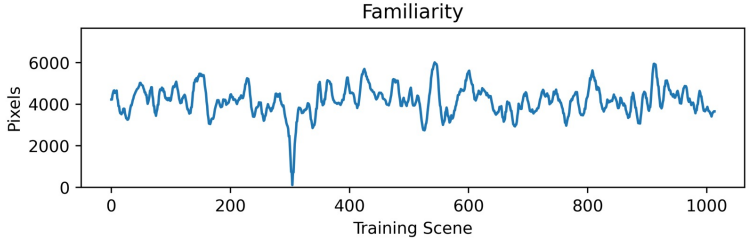
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

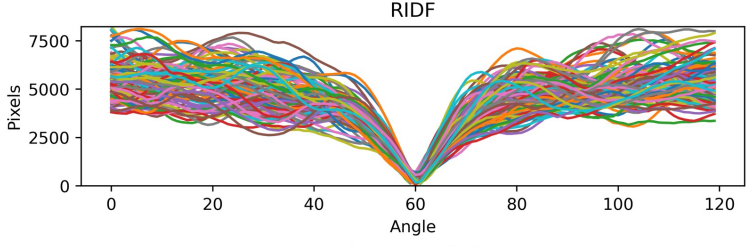
Navigation stats: RMSD error: 45.04; RMSD/dist: 0.113; TD: 3657; p90: 30; p50: 14; complete: 0

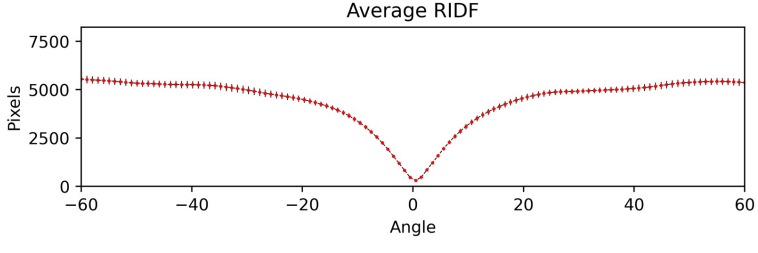
100%







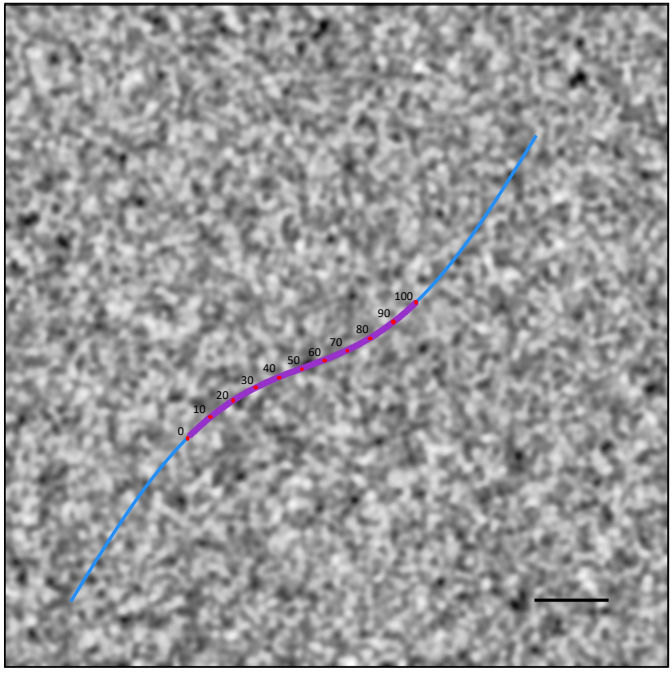


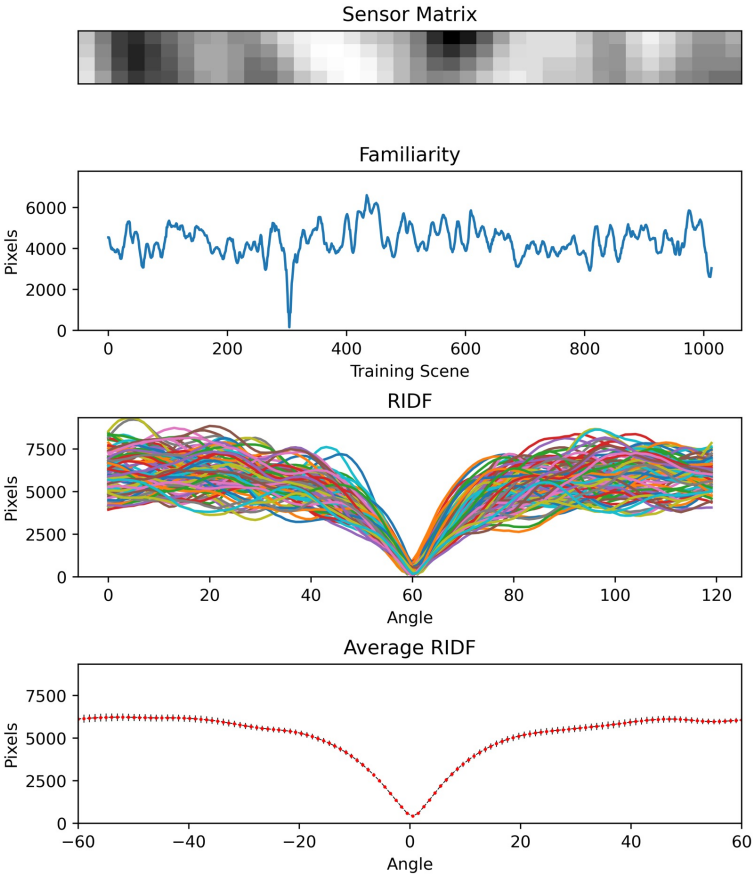


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 30.08; RMSD/dist: 0.075; TD: 3983; p90: 28; p50: 12; complete: 0

100%

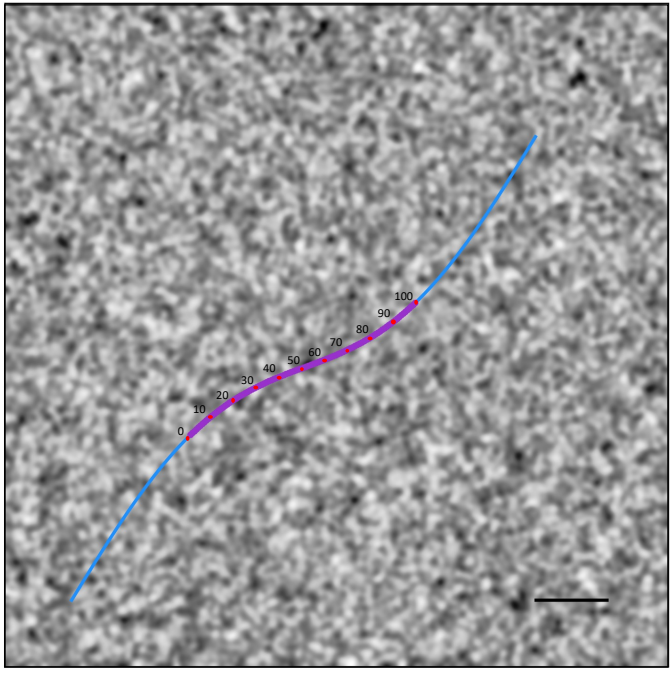


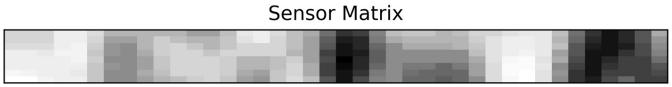


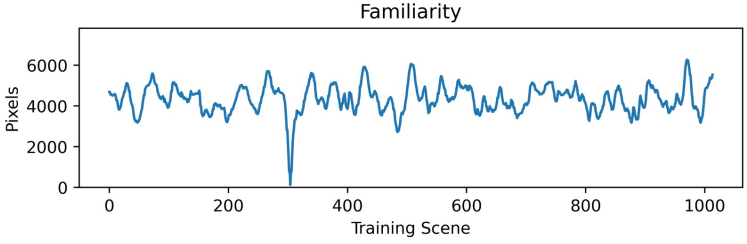
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

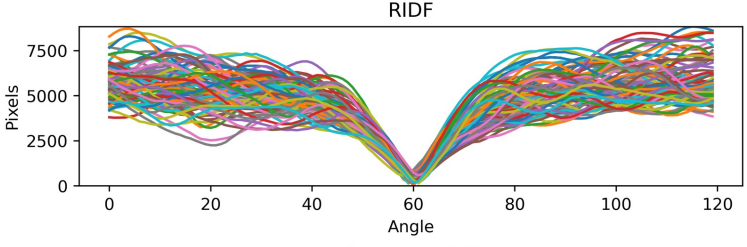
Navigation stats: RMSD error: 46.23; RMSD/dist: 0.116; TD: 4255; p90: 24; p50: 12; complete: 0

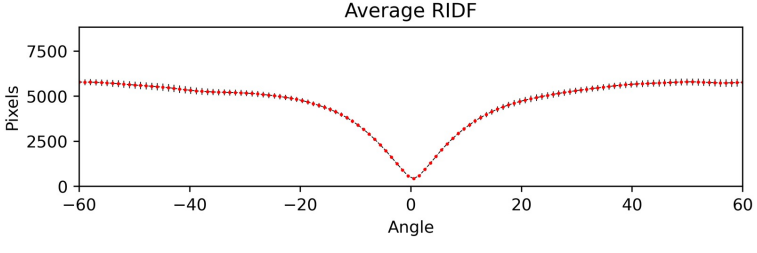
100%







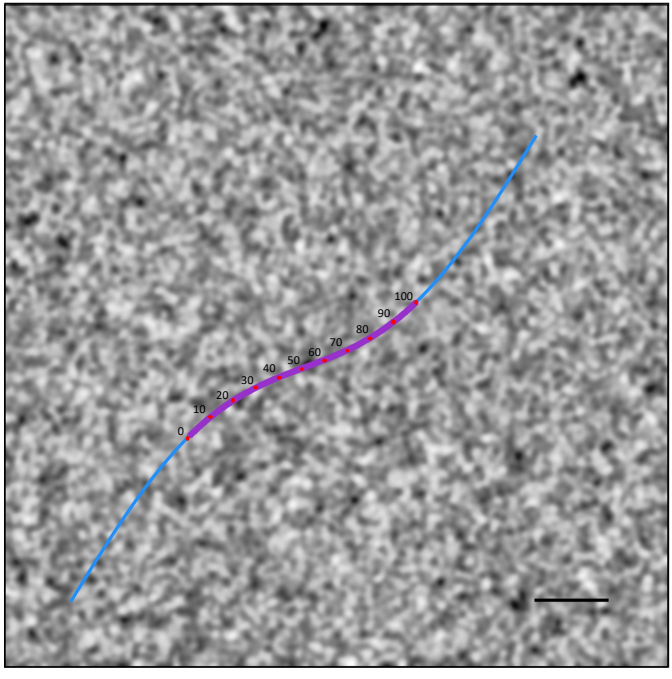


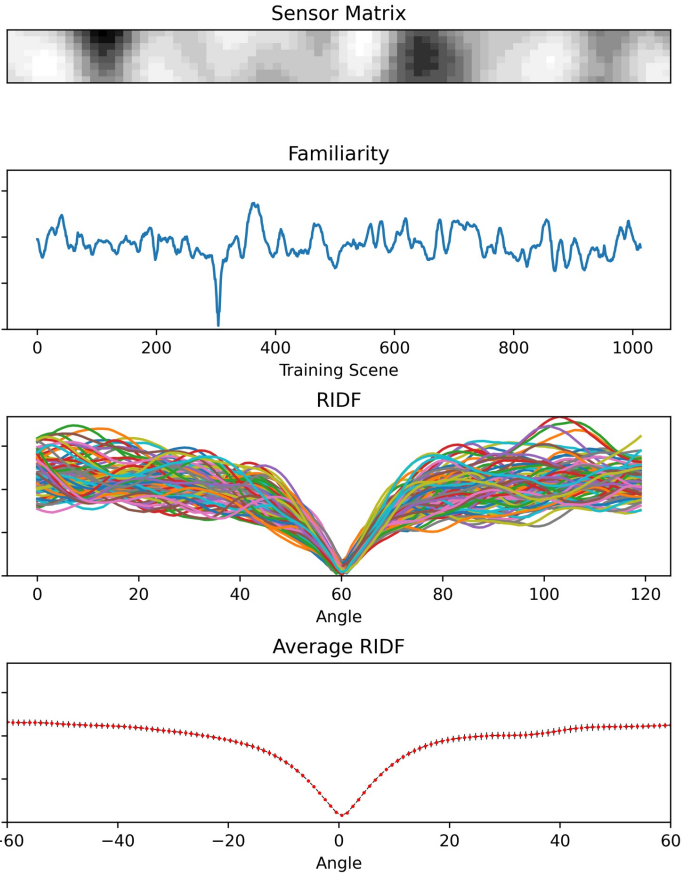


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 53.95; RMSD/dist: 0.135; TD: 4070; p90: 28; p50: 14; complete: 0

100%

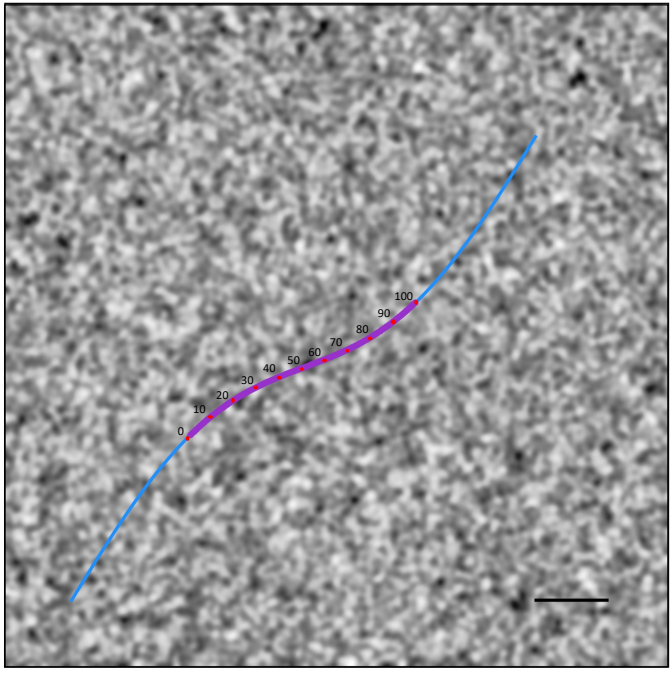


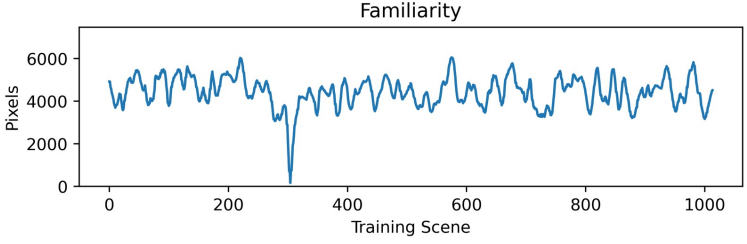


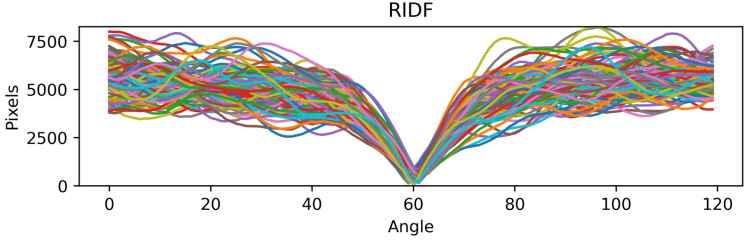
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

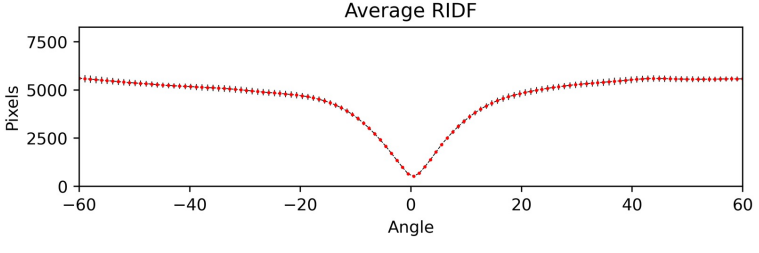
Navigation stats: RMSD error: 39.40; RMSD/dist: 0.099; TD: 4281; p90: 30; p50: 12; complete: 0

100%



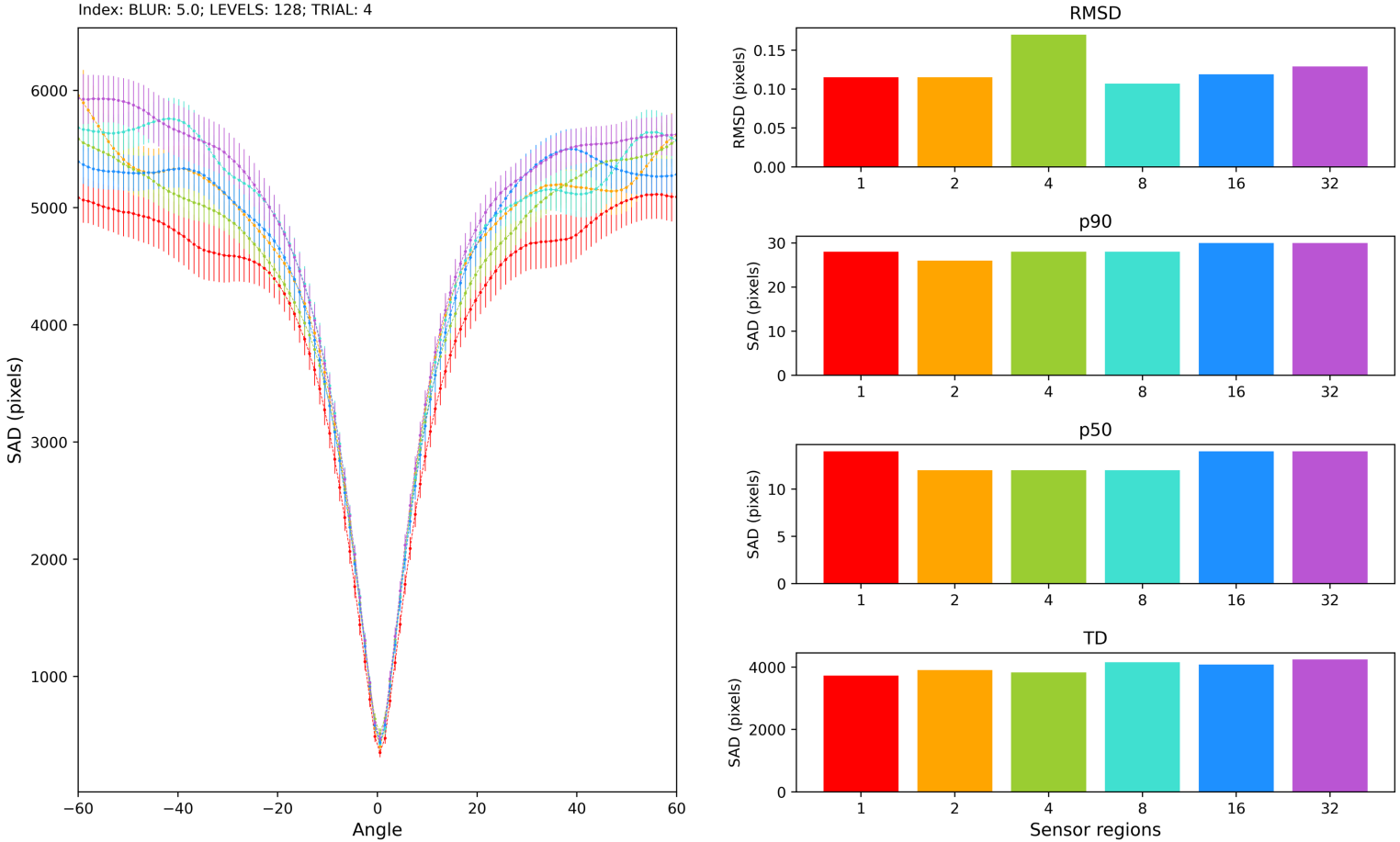




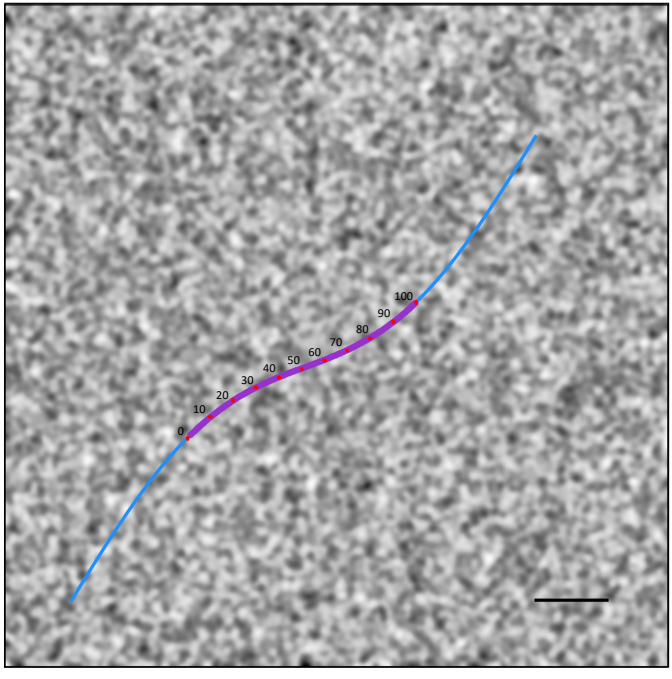


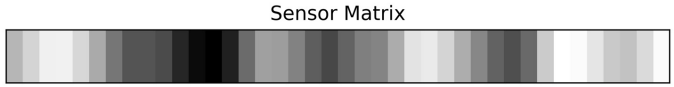
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

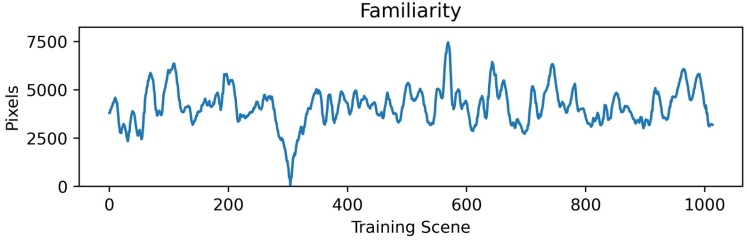
Navigation stats: RMSD error: 64.83; RMSD/dist: 0.162; TD: 3946; p90: 26; p50: 12; complete: 0

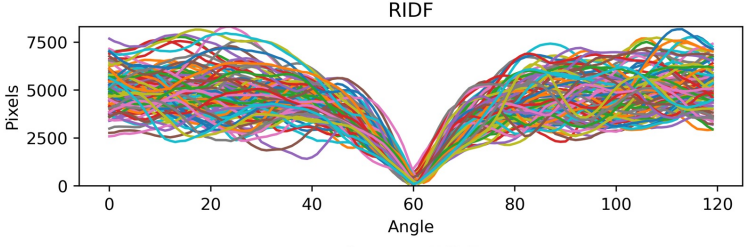

Index: BLUR: 5.0; LEVELS: 128; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

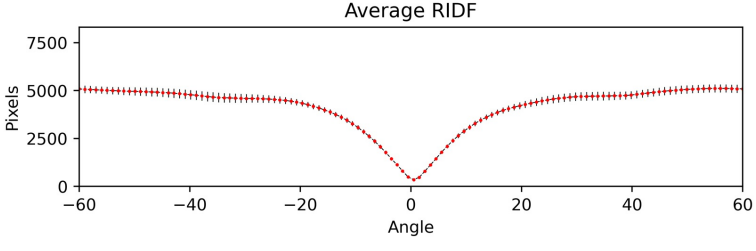
100%







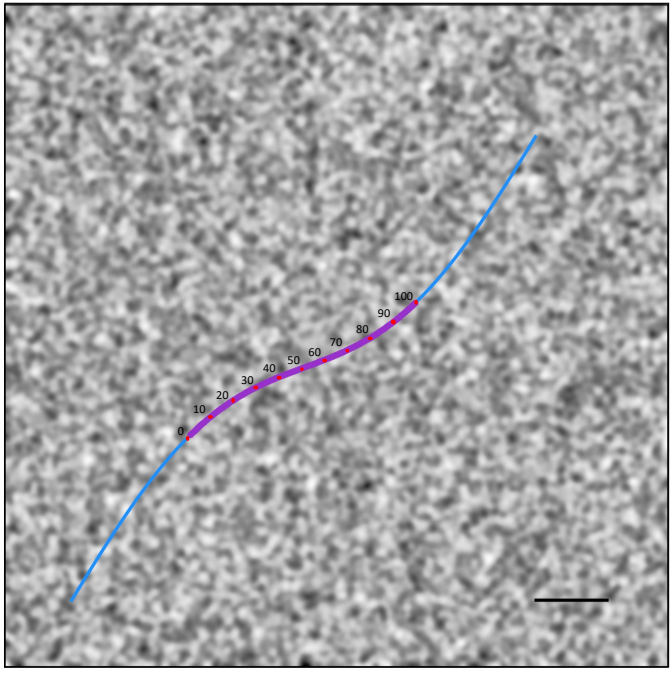


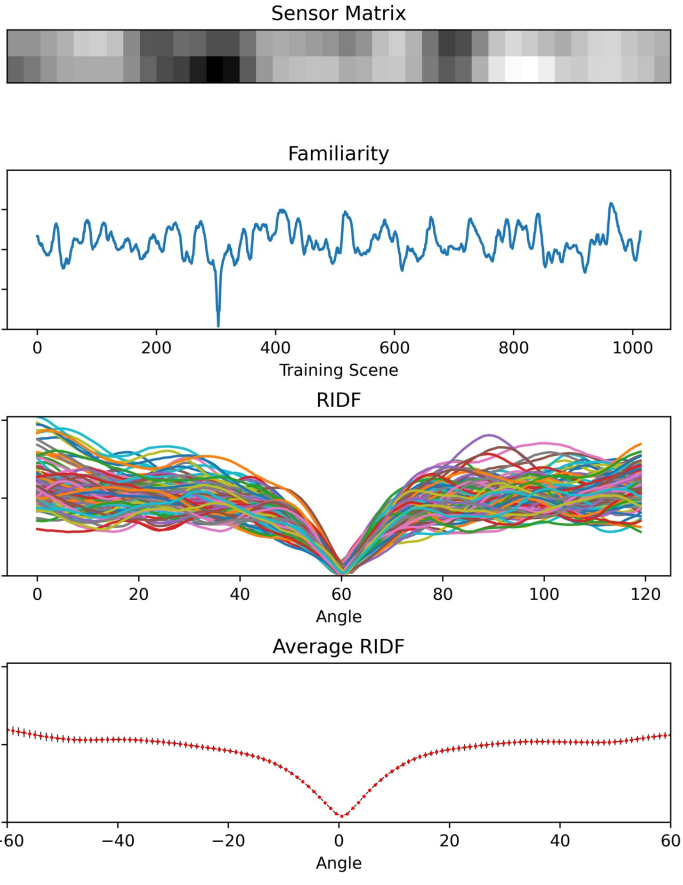


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 45.80; RMSD/dist: 0.115; TD: 3729; p90: 28; p50: 14; complete: 0

100%

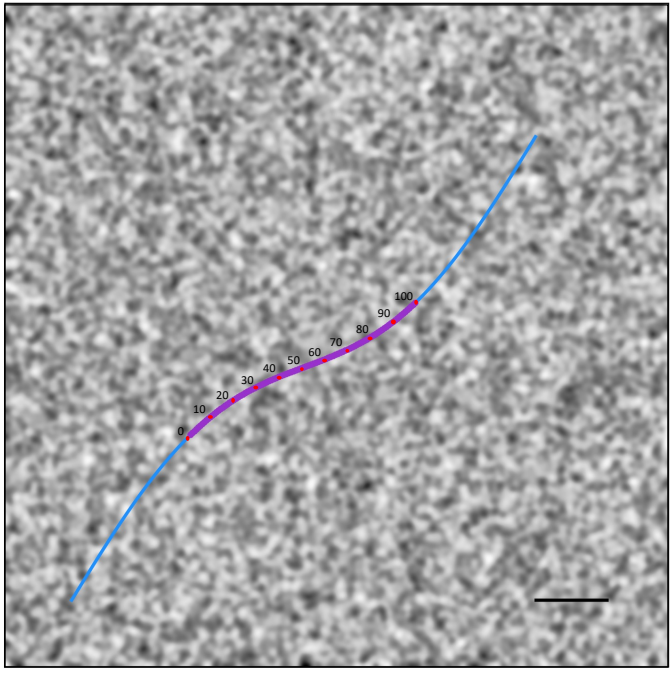


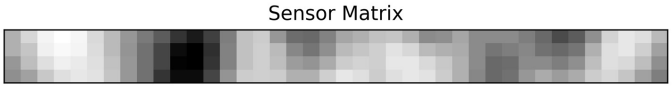


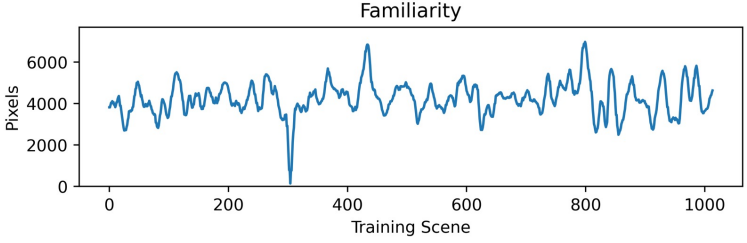
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

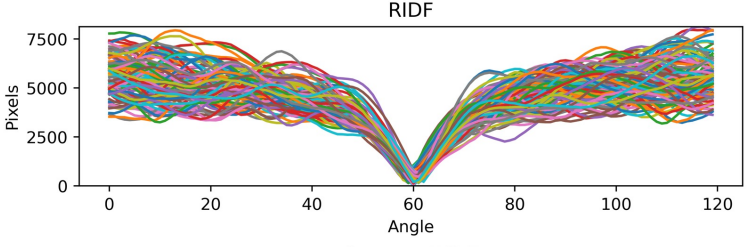
Navigation stats: RMSD error: 45.91; RMSD/dist: 0.115; TD: 3904; p90: 26; p50: 12; complete: 0

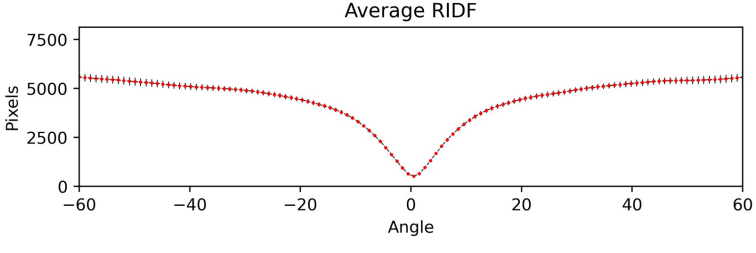
100%







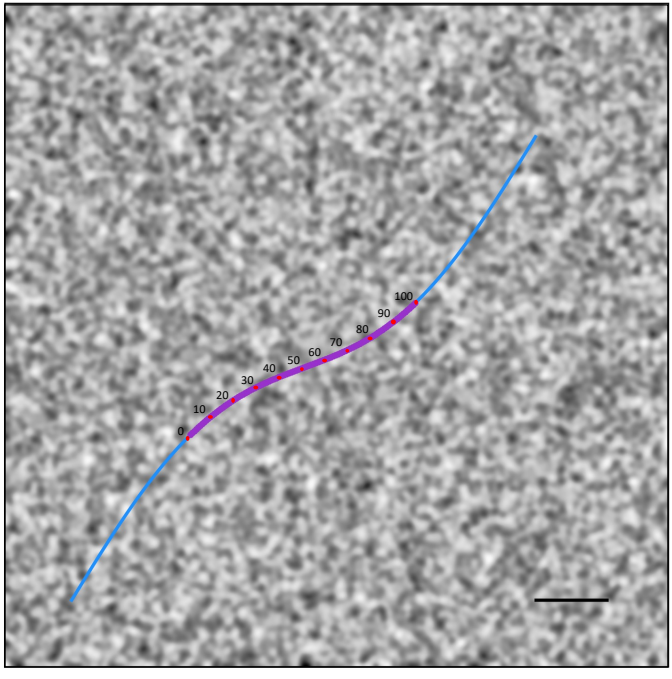


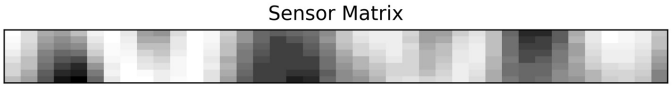


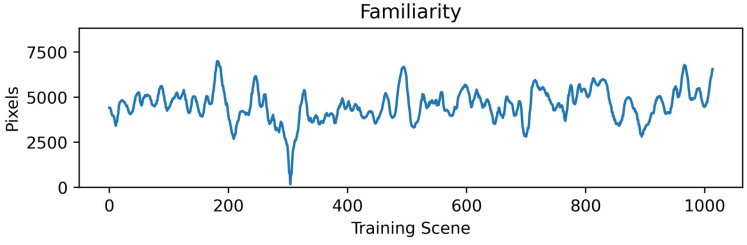
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

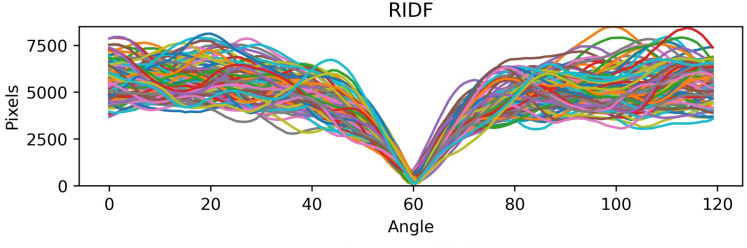
Navigation stats: RMSD error: 67.87; RMSD/dist: 0.170; TD: 3830; p90: 28; p50: 12; complete: 0

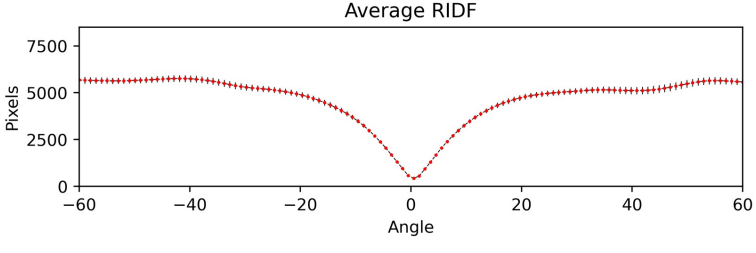
100%







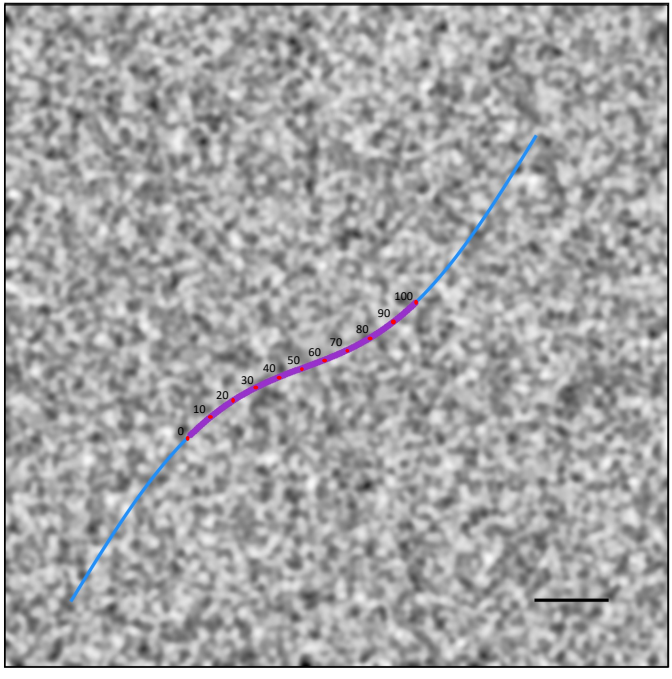


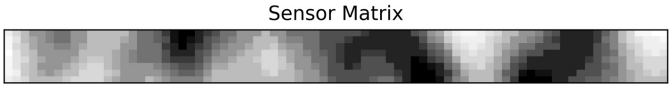


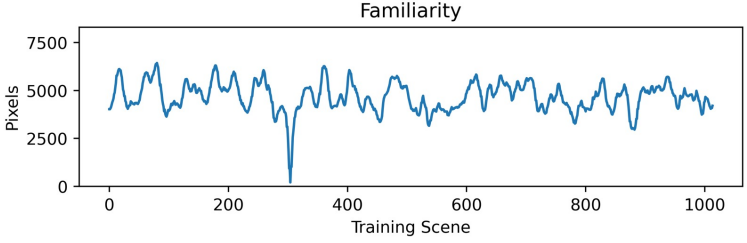
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

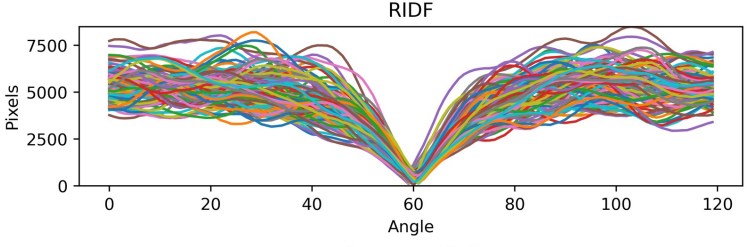
Navigation stats: RMSD error: 42.70; RMSD/dist: 0.107; TD: 4159; p90: 28; p50: 12; complete: 0

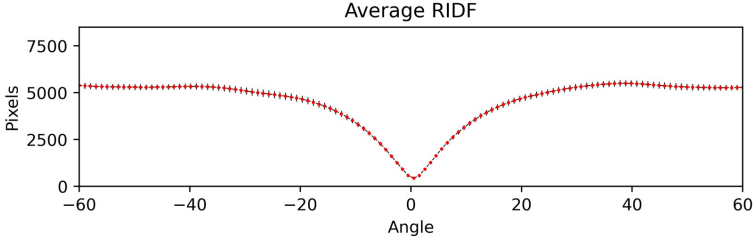
100%







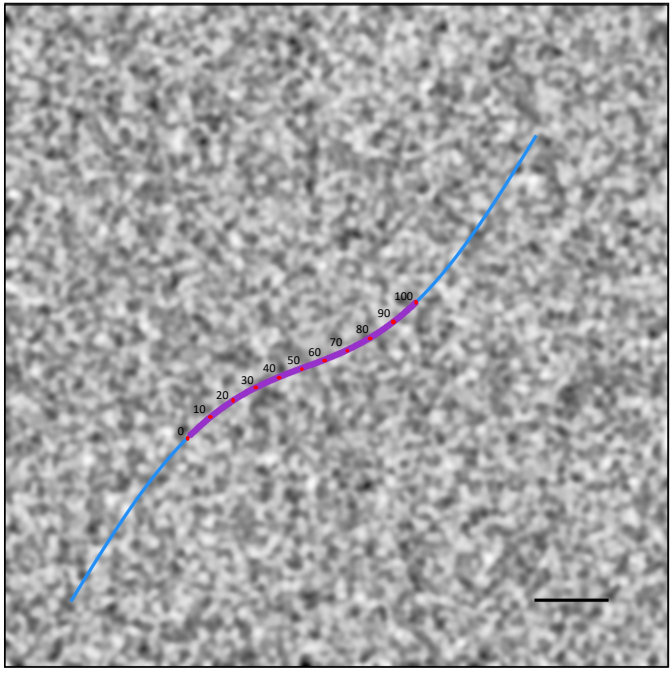


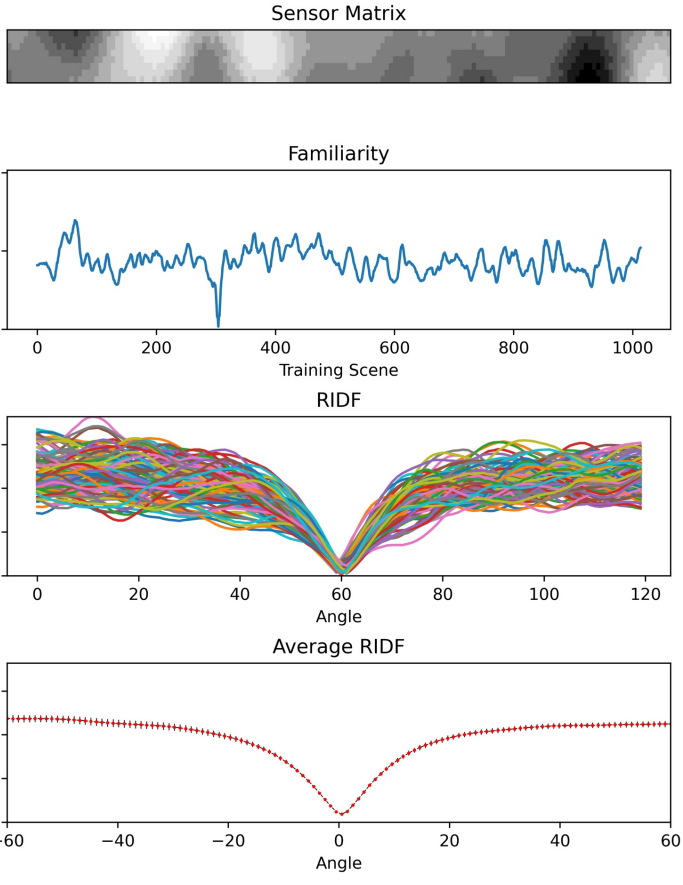


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 47.67; RMSD/dist: 0.119; TD: 4084; p90: 30; p50: 14; complete: 0

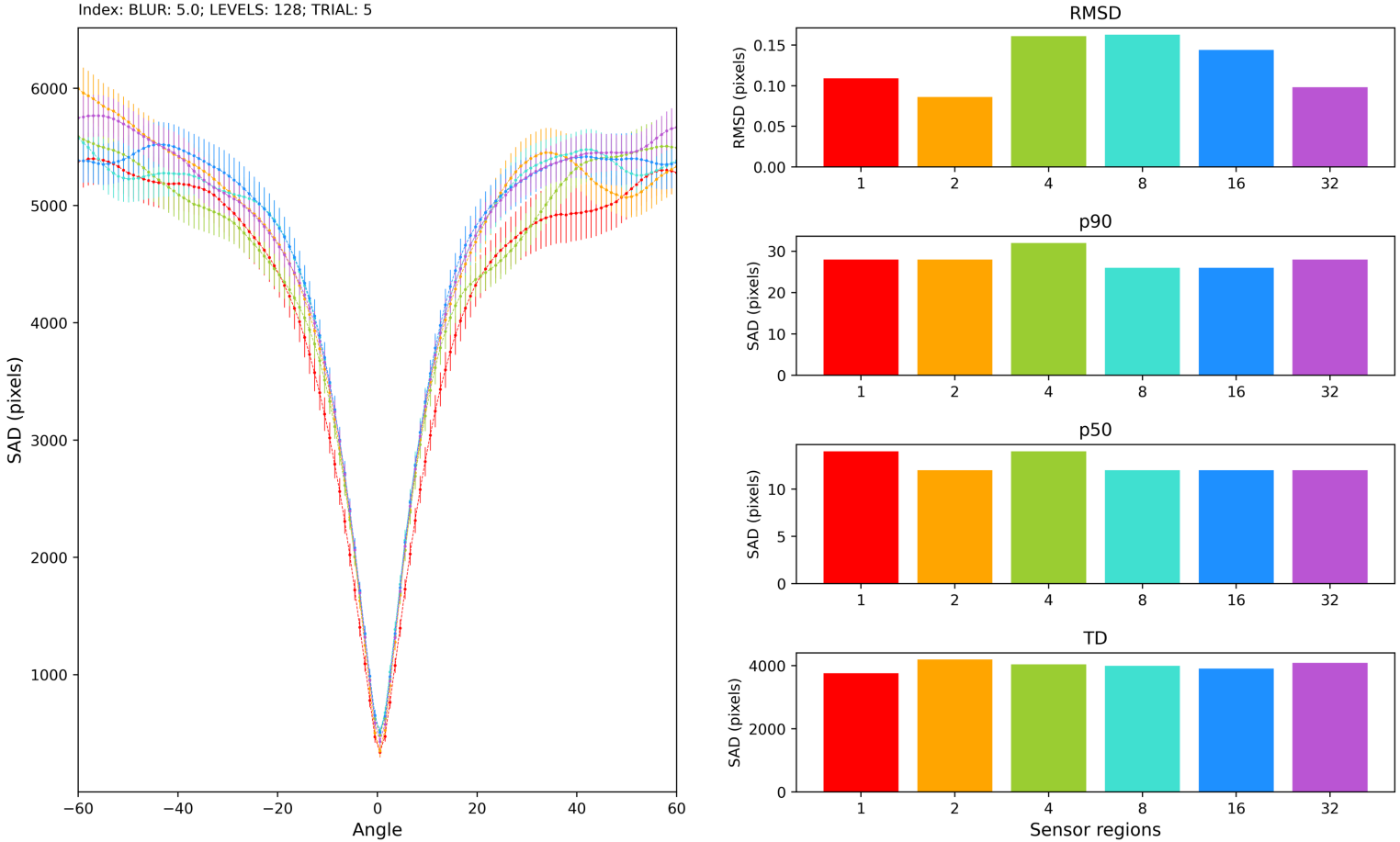
100%



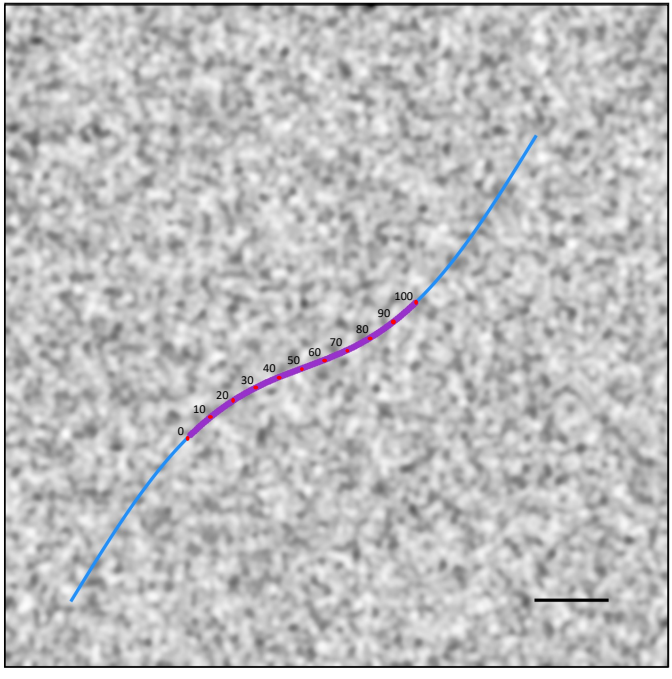


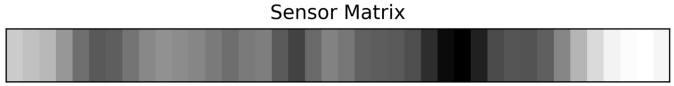
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

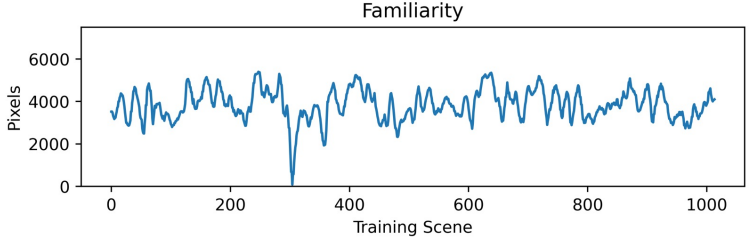
Navigation stats: RMSD error: 51.56; RMSD/dist: 0.129; TD: 4242; p90: 30; p50: 14; complete: 0

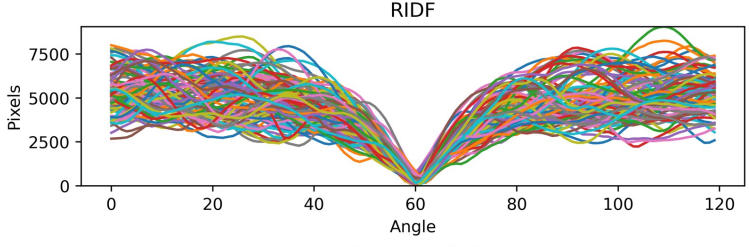

Index: BLUR: 5.0; LEVELS: 128; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

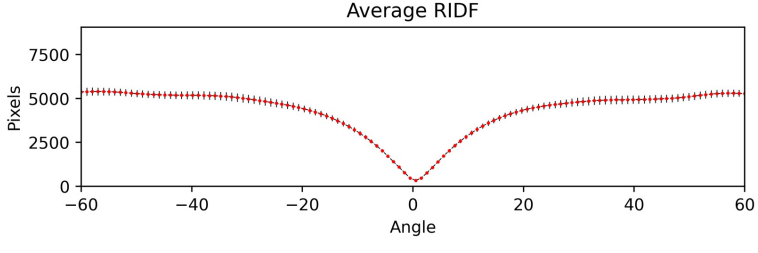
100%







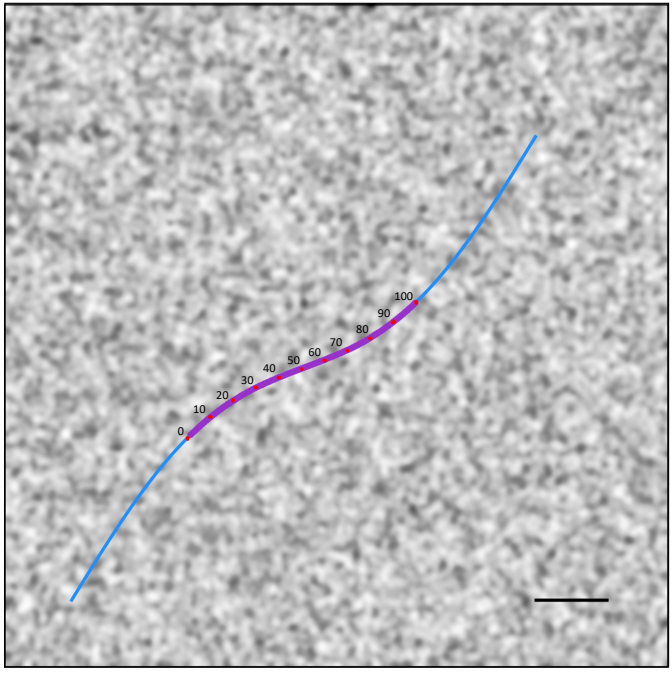


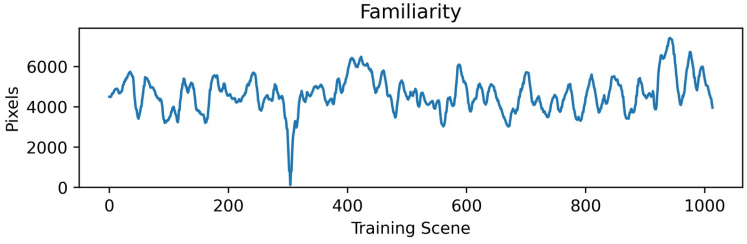


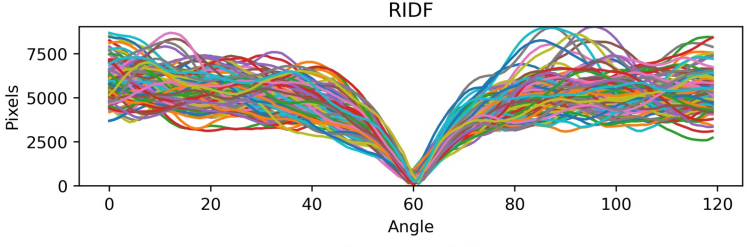
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

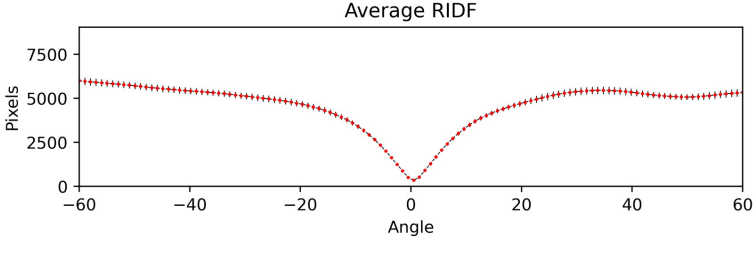
Navigation stats: RMSD error: 43.49; RMSD/dist: 0.109; TD: 3760; p90: 28; p50: 14; complete: 0

100%





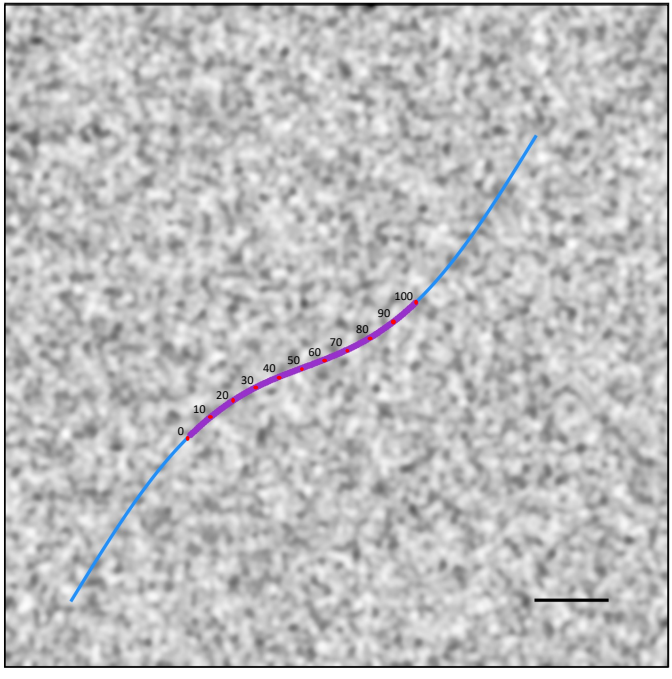


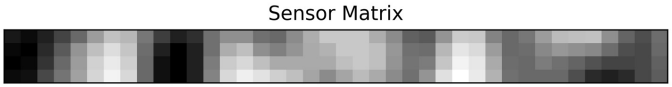


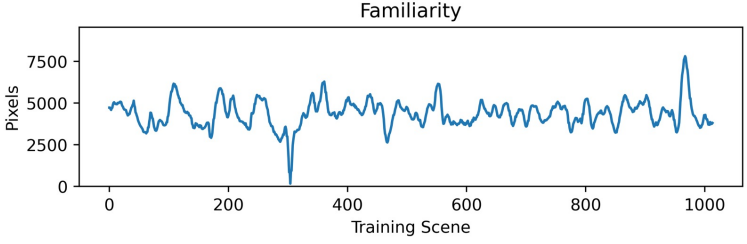
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

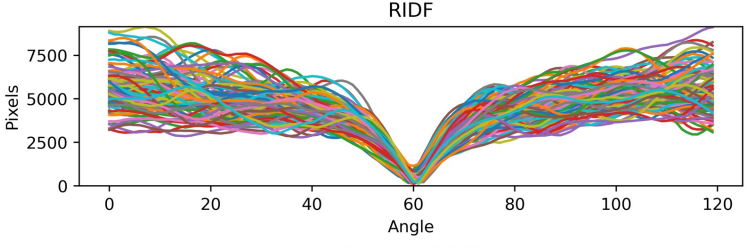
Navigation stats: RMSD error: 34.27; RMSD/dist: 0.086; TD: 4194; p90: 28; p50: 12; complete: 0

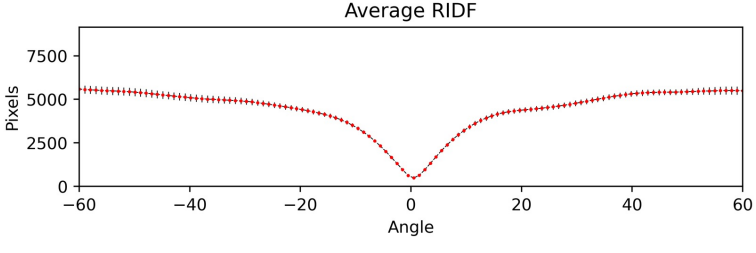
100%







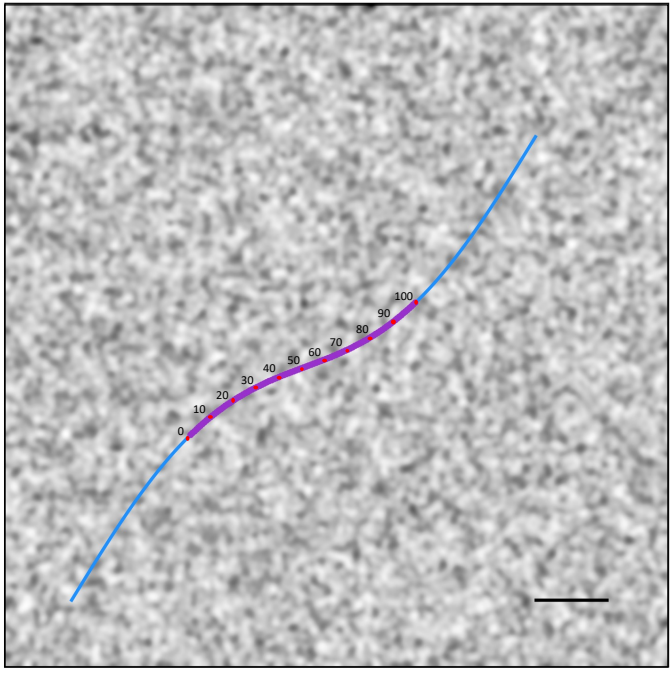


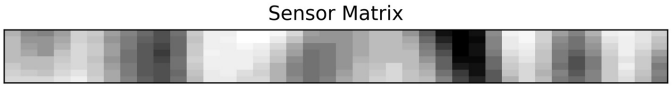


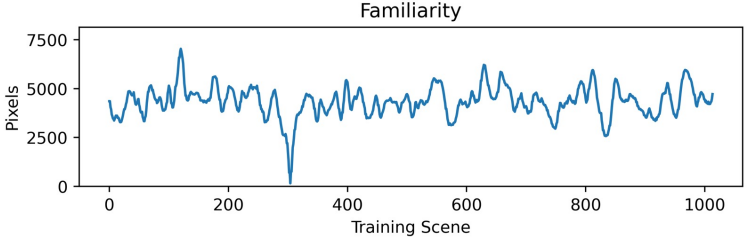
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

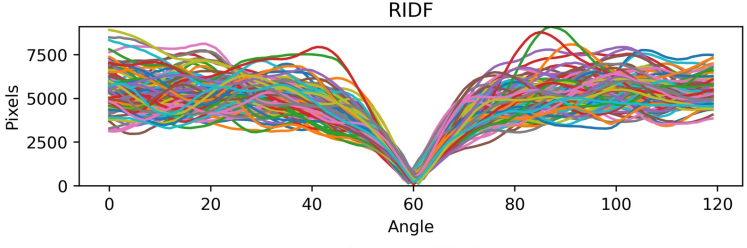
Navigation stats: RMSD error: 64.41; RMSD/dist: 0.161; TD: 4042; p90: 32; p50: 14; complete: 0

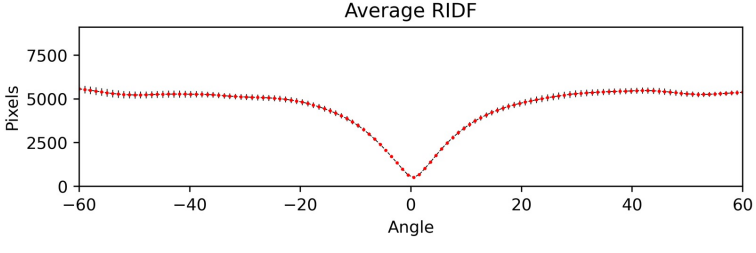
100%







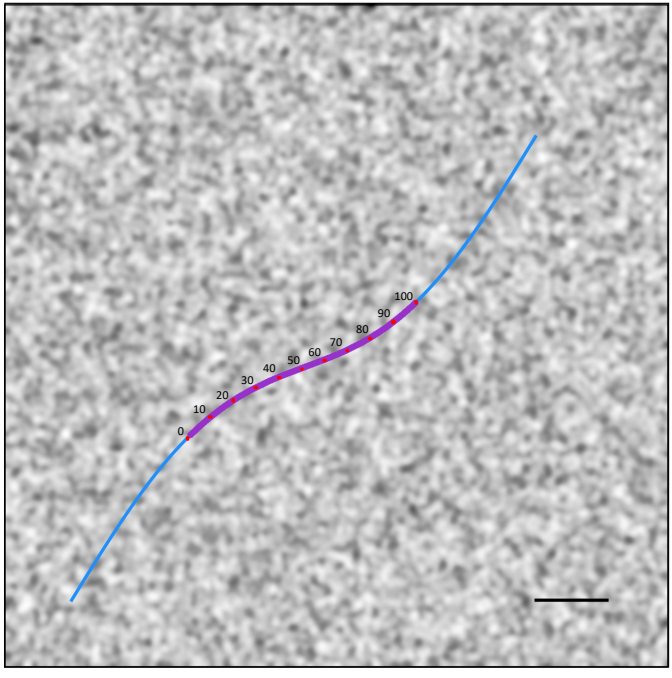


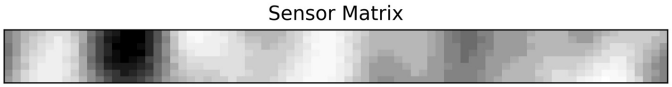


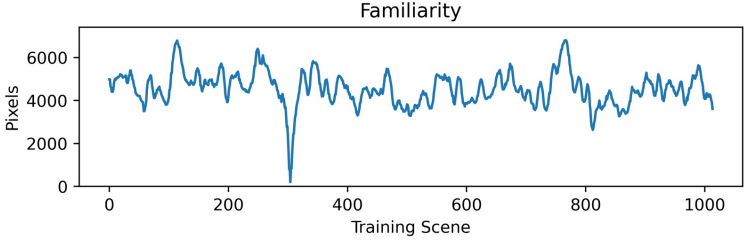
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

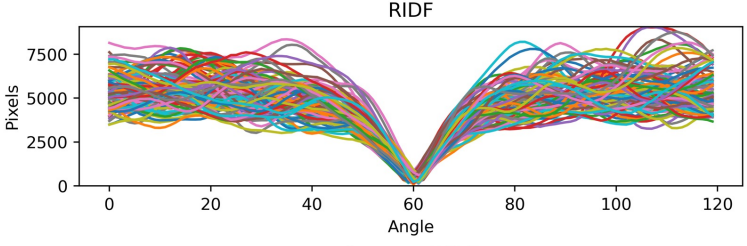
Navigation stats: RMSD error: 65.14; RMSD/dist: 0.163; TD: 3999; p90: 26; p50: 12; complete: 0

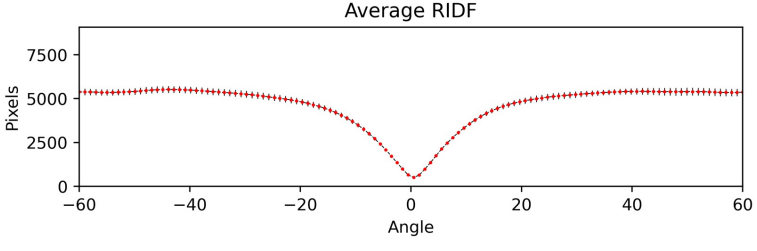
100%







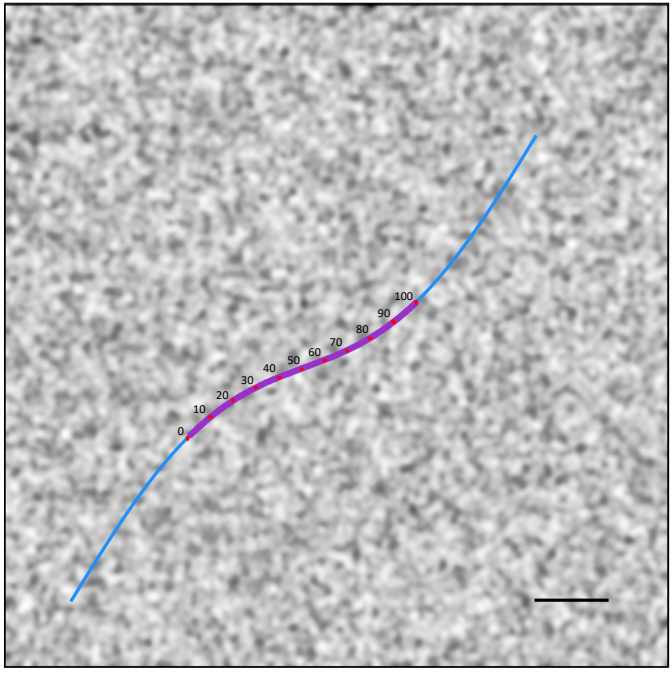


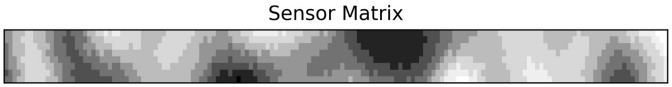


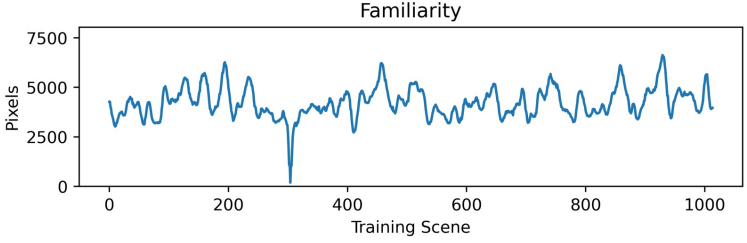
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

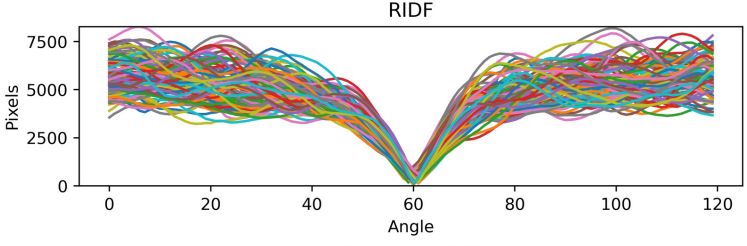
Navigation stats: RMSD error: 57.69; RMSD/dist: 0.144; TD: 3910; p90: 26; p50: 12; complete: 0

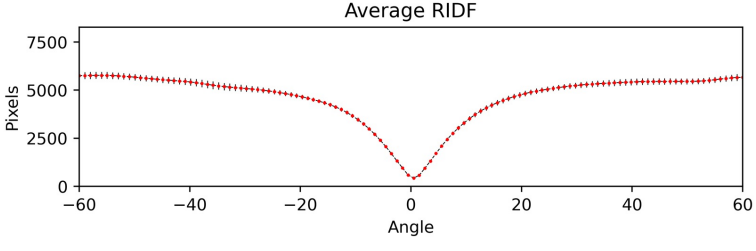
100%





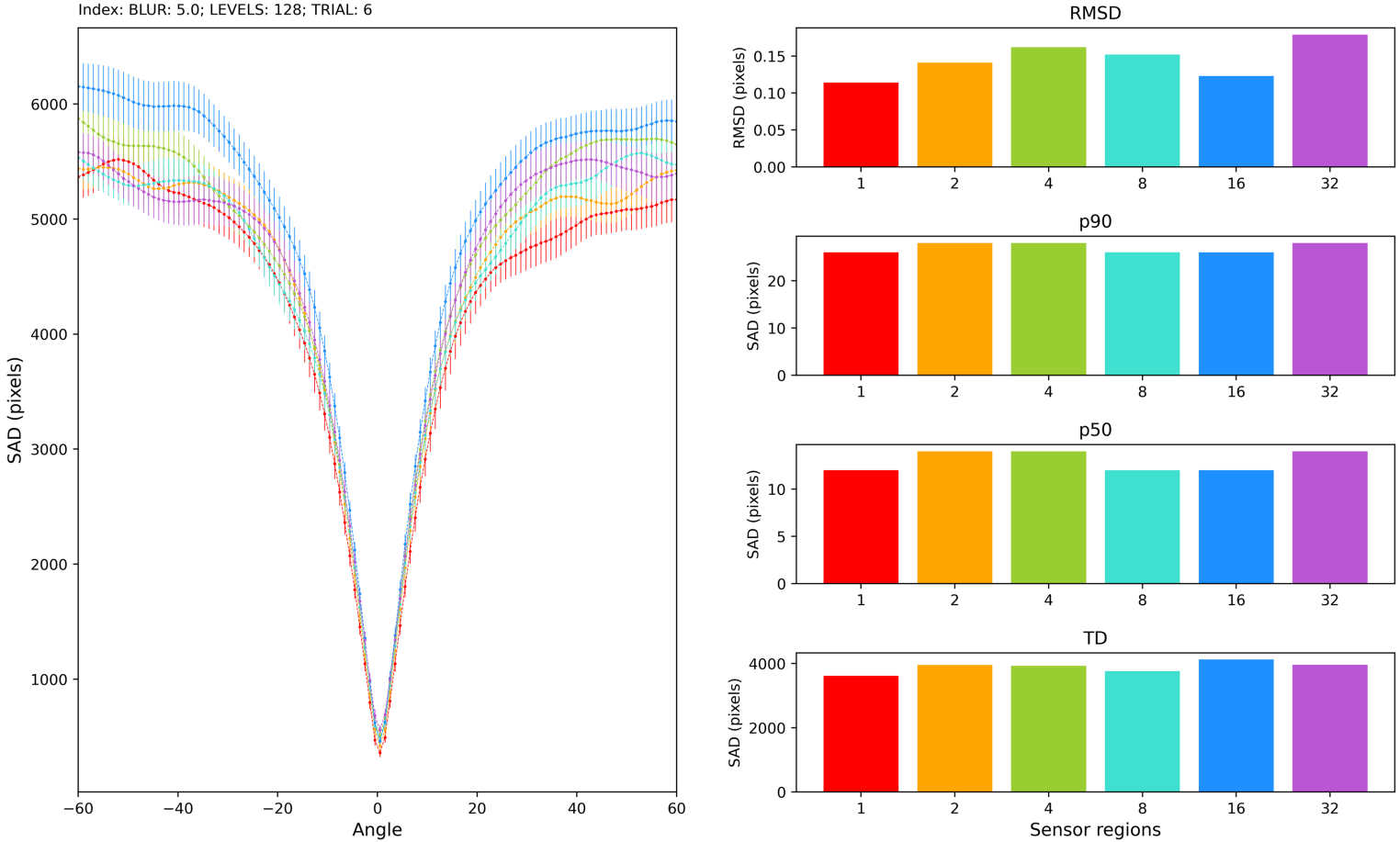




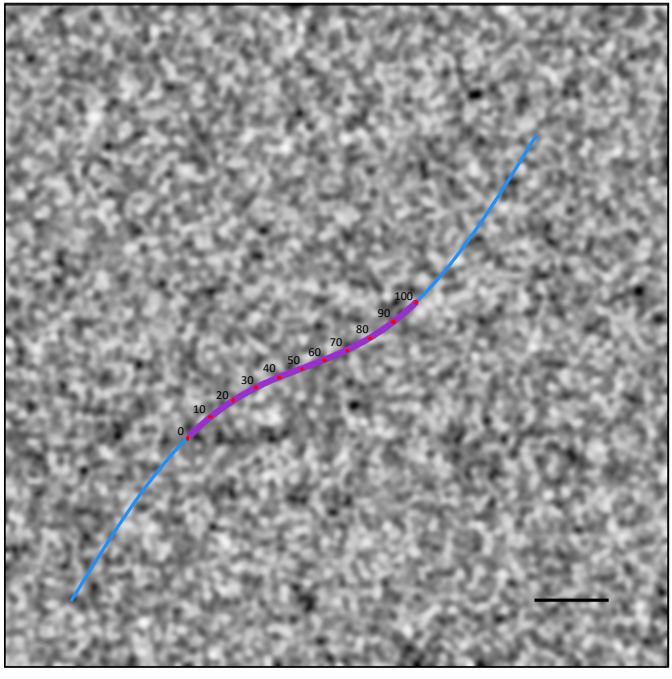


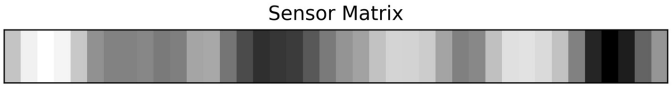
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

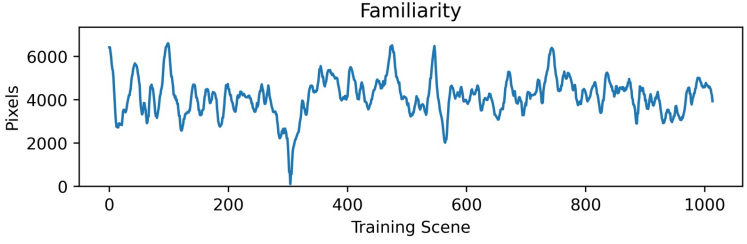
Navigation stats: RMSD error: 39.38; RMSD/dist: 0.098; TD: 4092; p90: 28; p50: 12; complete: 0

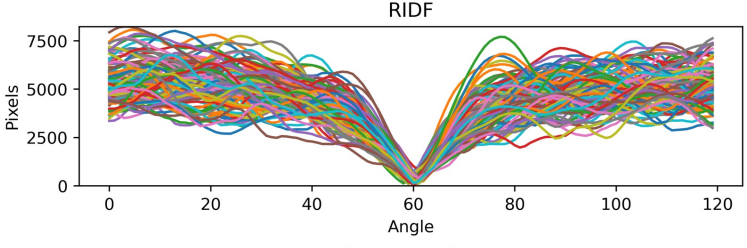

Index: BLUR: 5.0; LEVELS: 128; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

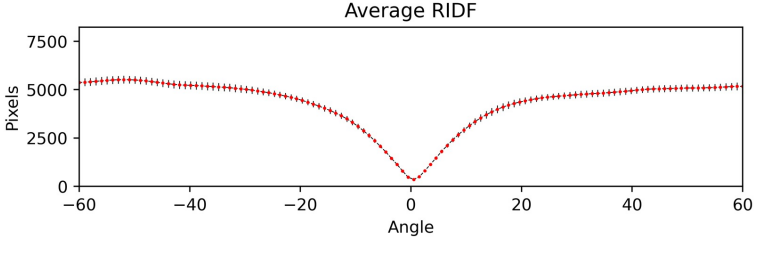
100%







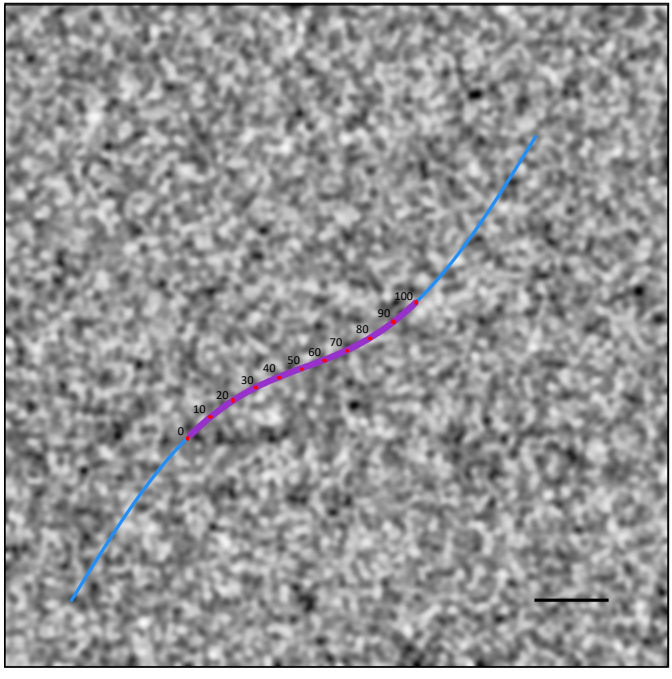


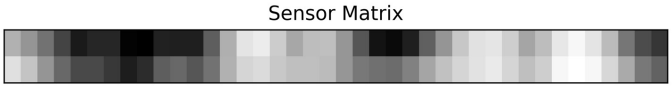


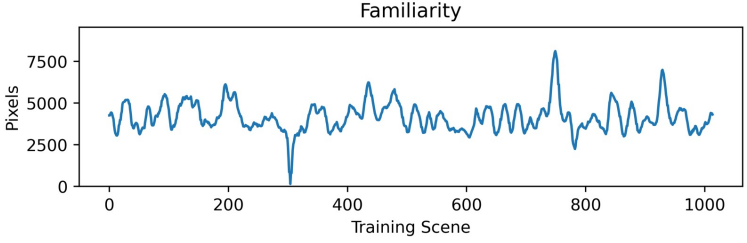
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

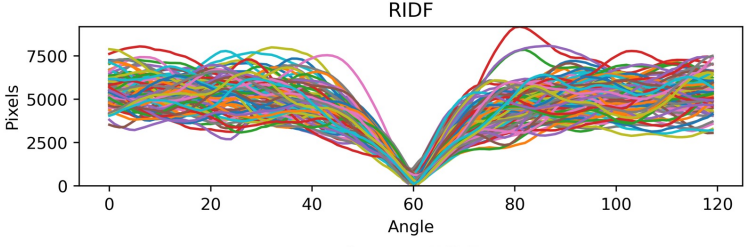
Navigation stats: RMSD error: 45.54; RMSD/dist: 0.114; TD: 3616; p90: 26; p50: 12; complete: 0

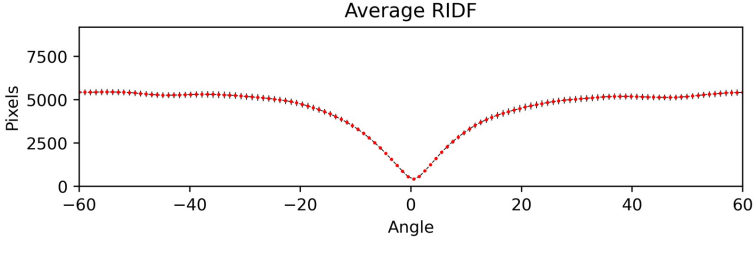
100%







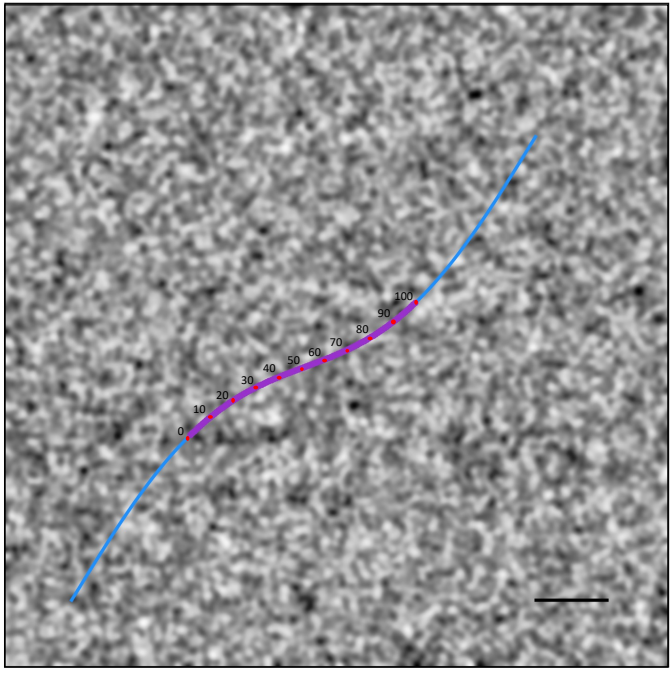


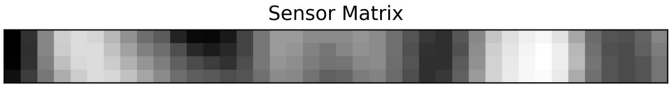


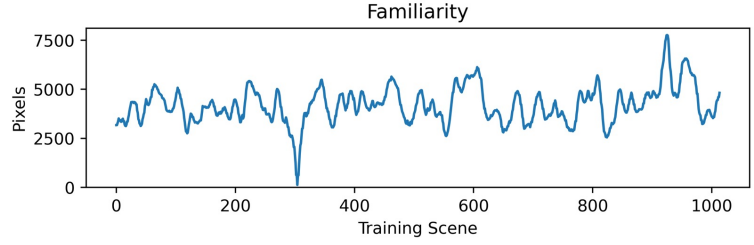
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

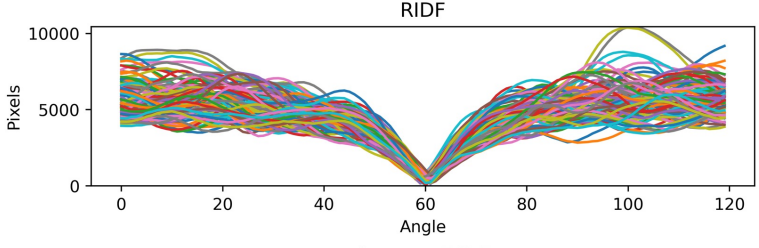
Navigation stats: RMSD error: 56.23; RMSD/dist: 0.141; TD: 3952; p90: 28; p50: 14; complete: 0

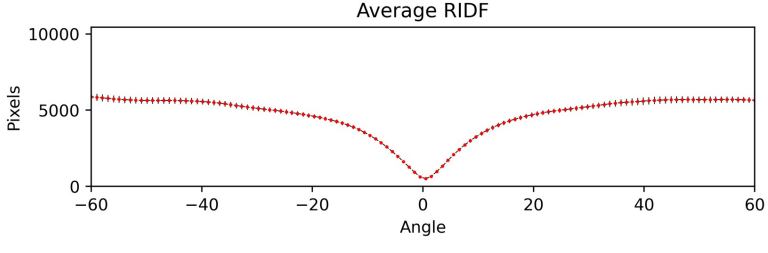
100%







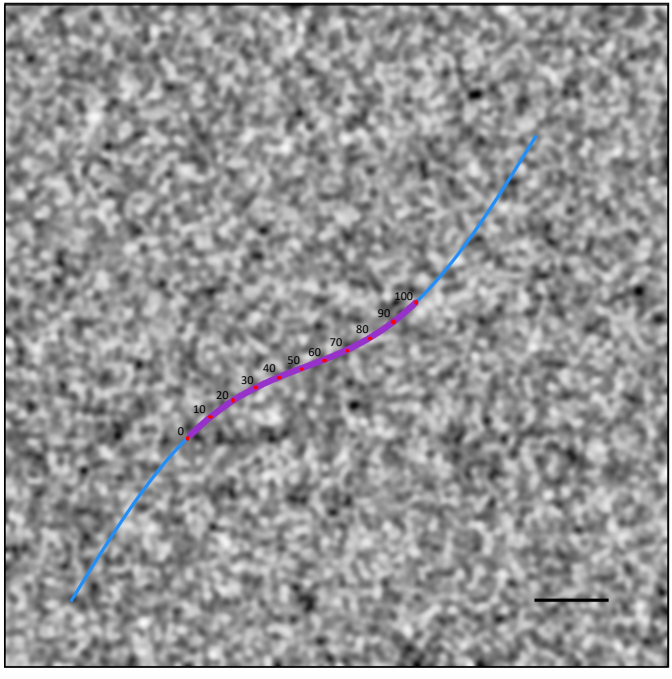


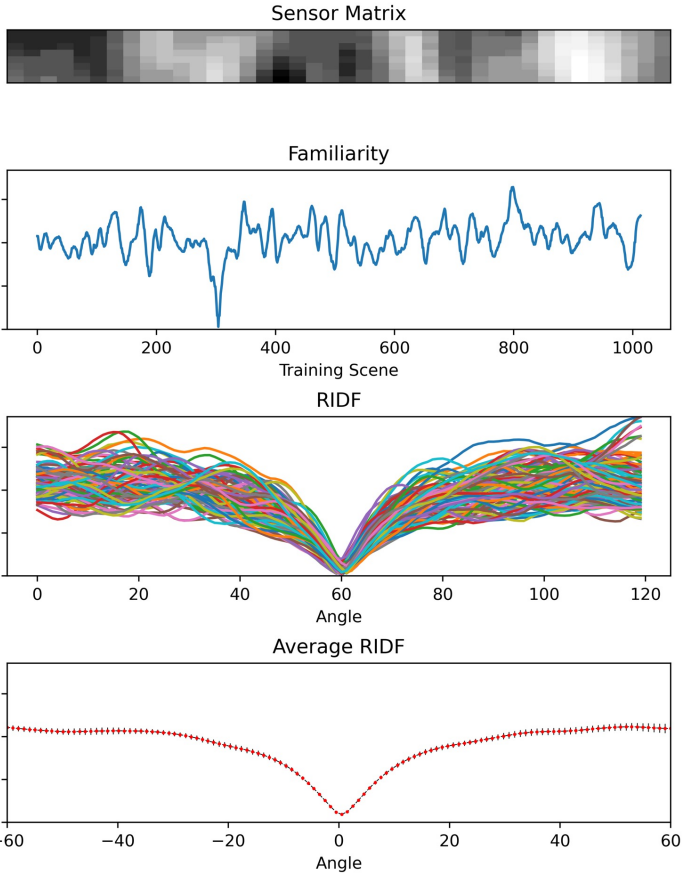


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 64.70; RMSD/dist: 0.162; TD: 3923; p90: 28; p50: 14; complete: 0

100%

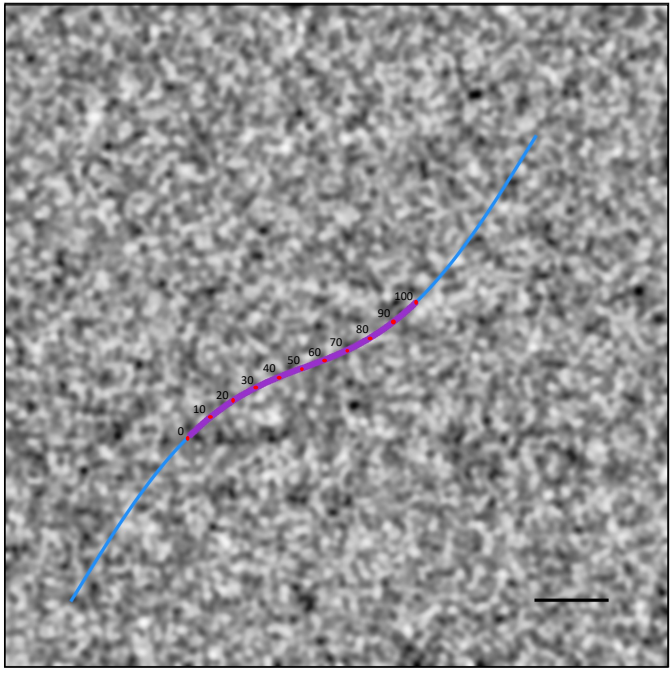


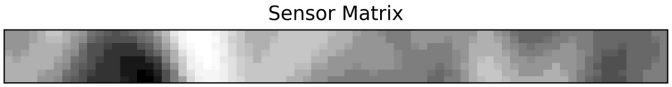


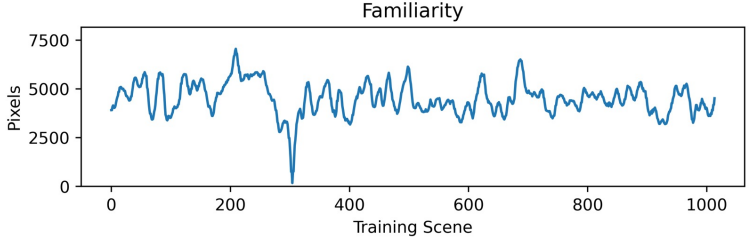
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

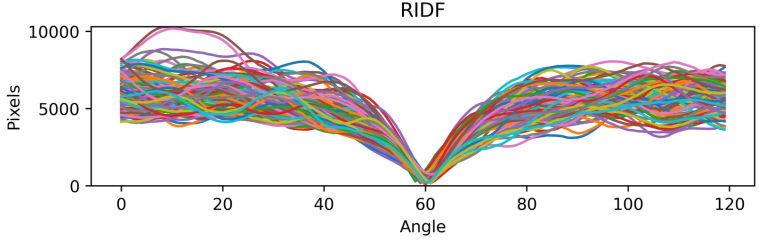
Navigation stats: RMSD error: 61.00; RMSD/dist: 0.152; TD: 3758; p90: 26; p50: 12; complete: 0

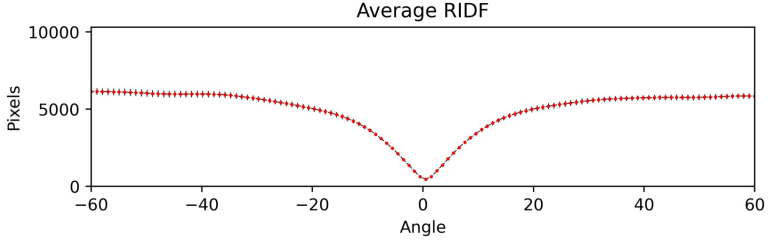
100%







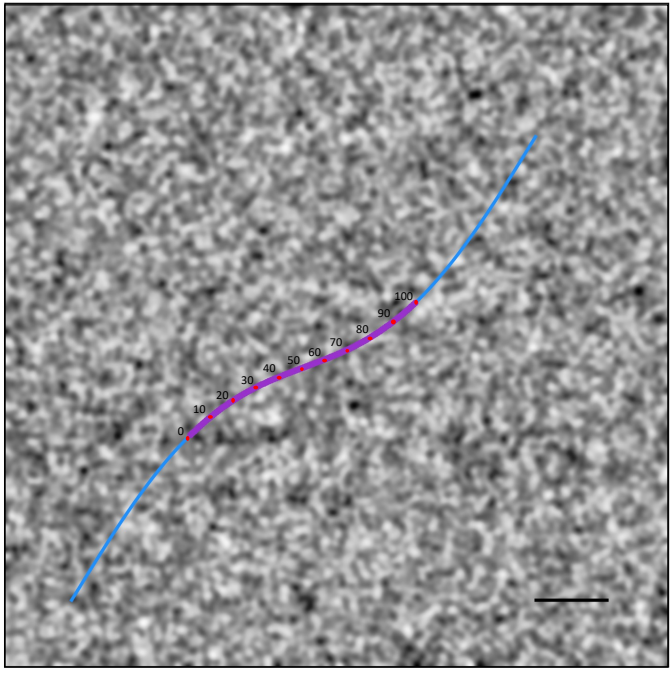


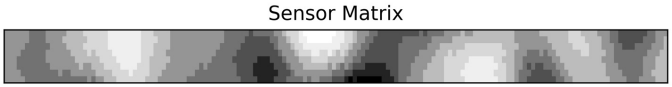


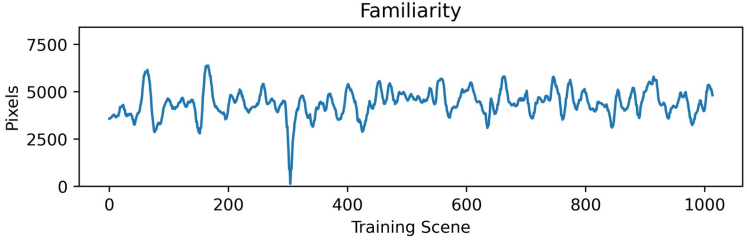
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

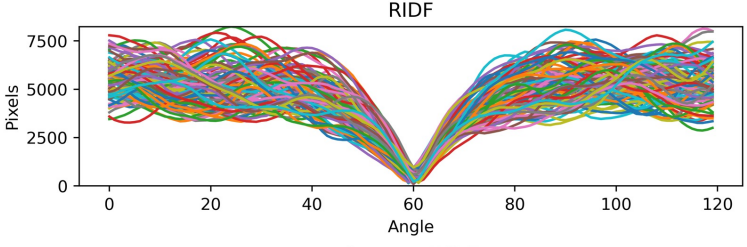
Navigation stats: RMSD error: 49.05; RMSD/dist: 0.123; TD: 4120; p90: 26; p50: 12; complete: 0

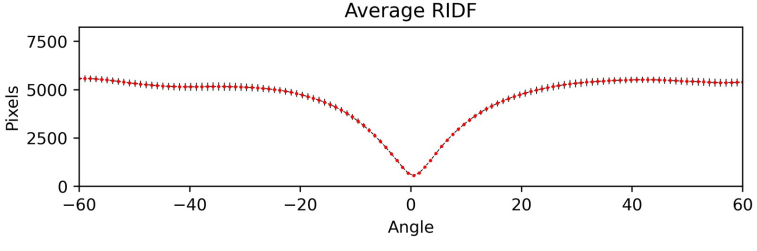
100%





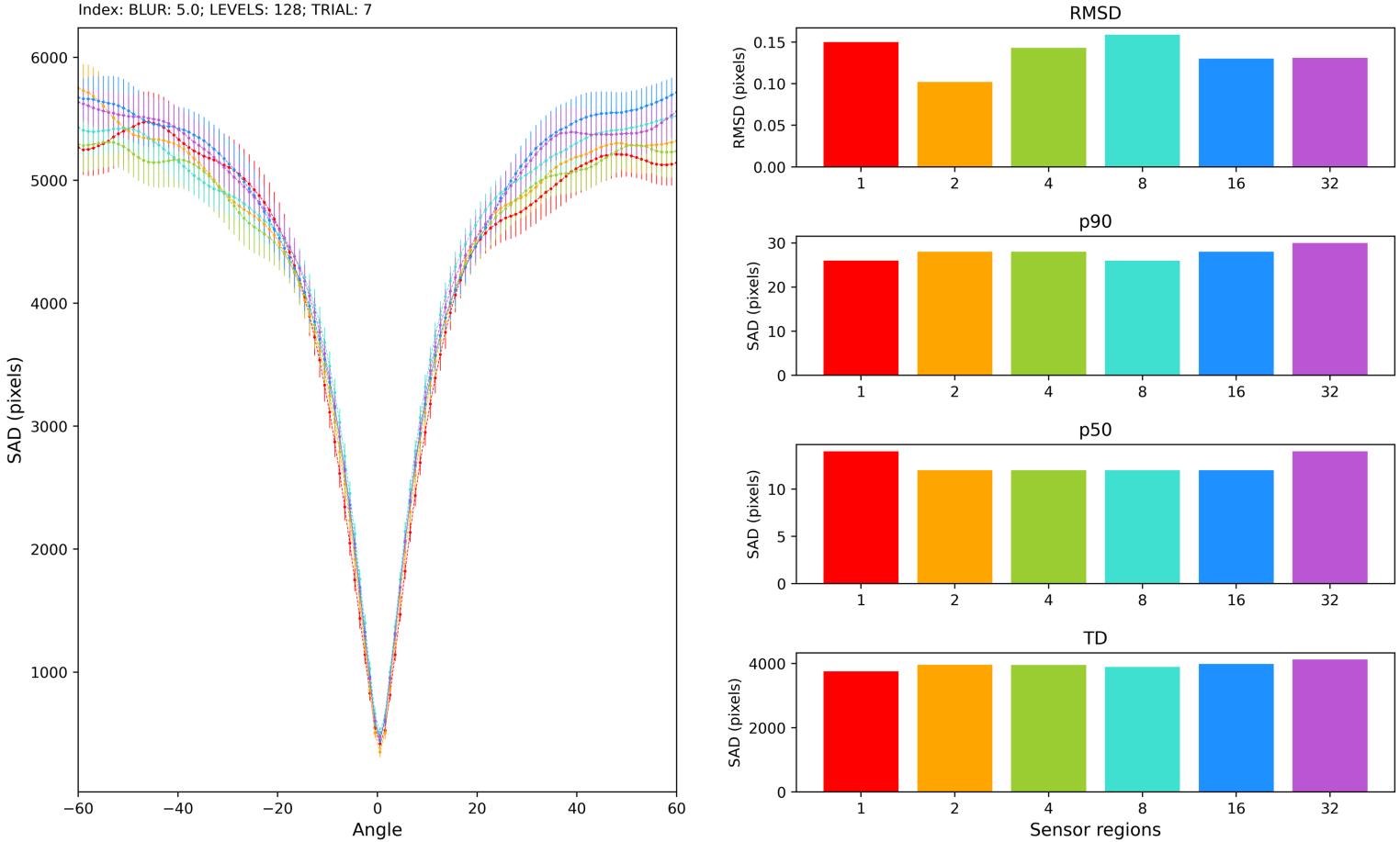




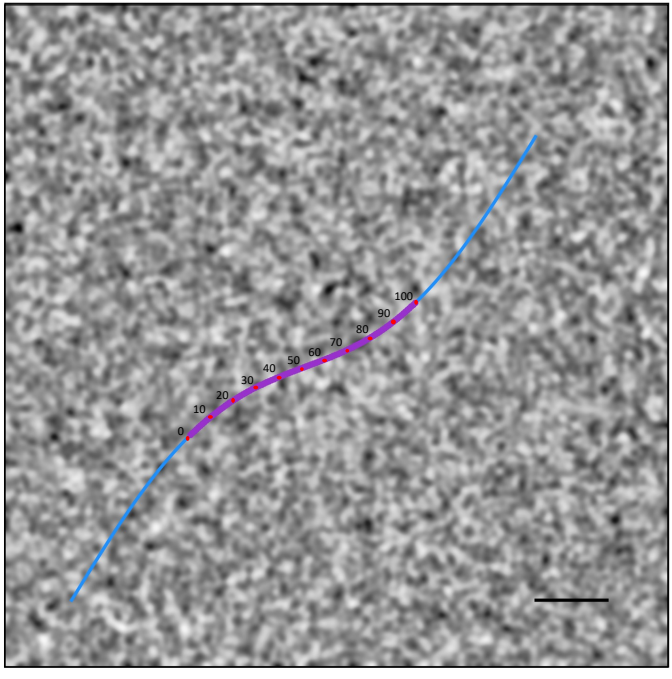


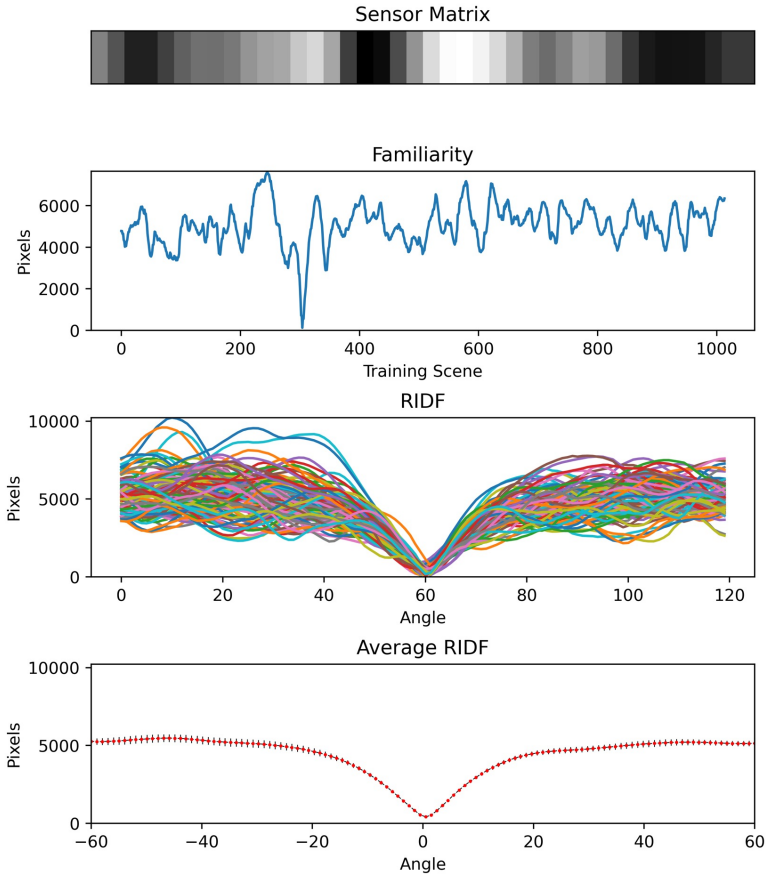
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 71.44; RMSD/dist: 0.179; TD: 3955; p90: 28; p50: 14; complete: 0


Index: BLUR: 5.0; LEVELS: 128; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

100%

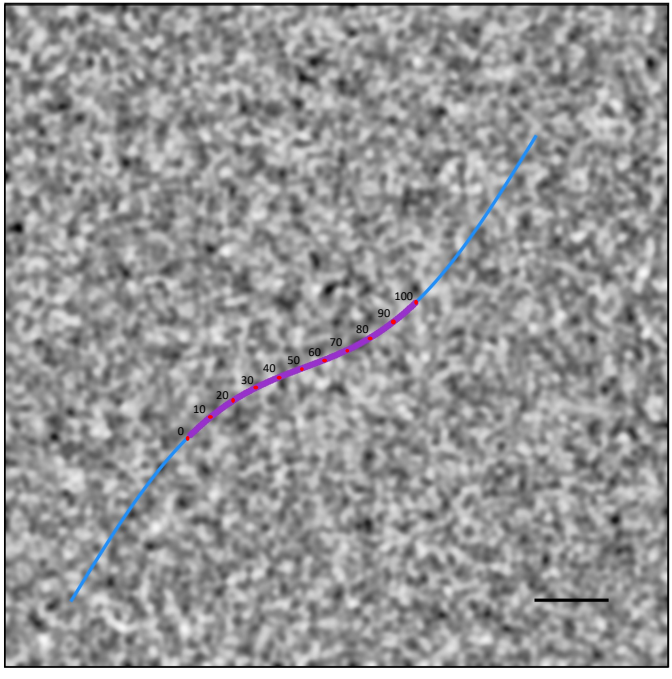


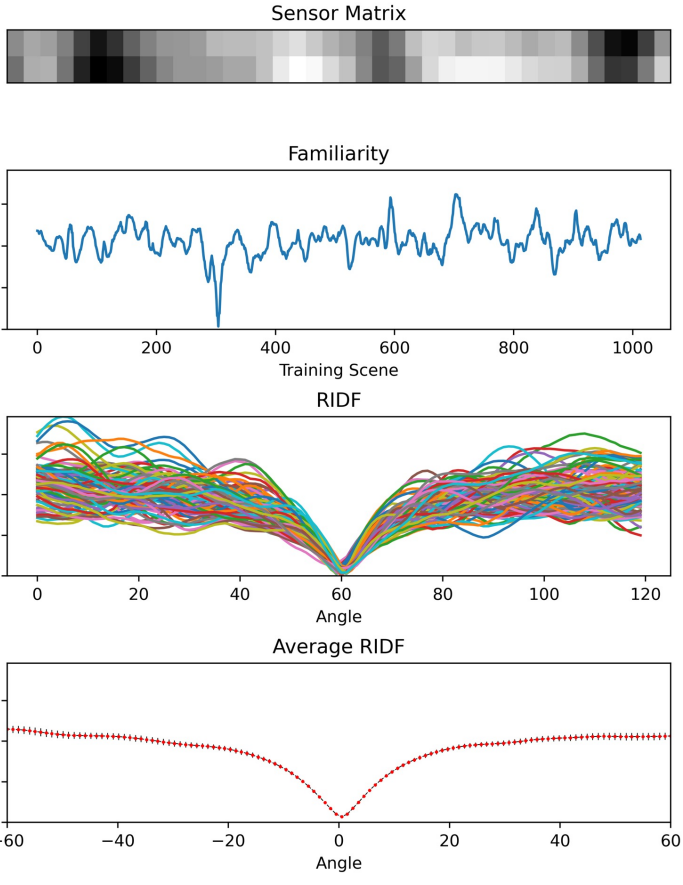


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 60.04; RMSD/dist: 0.150; TD: 3751; p90: 26; p50: 14; complete: 0

100%

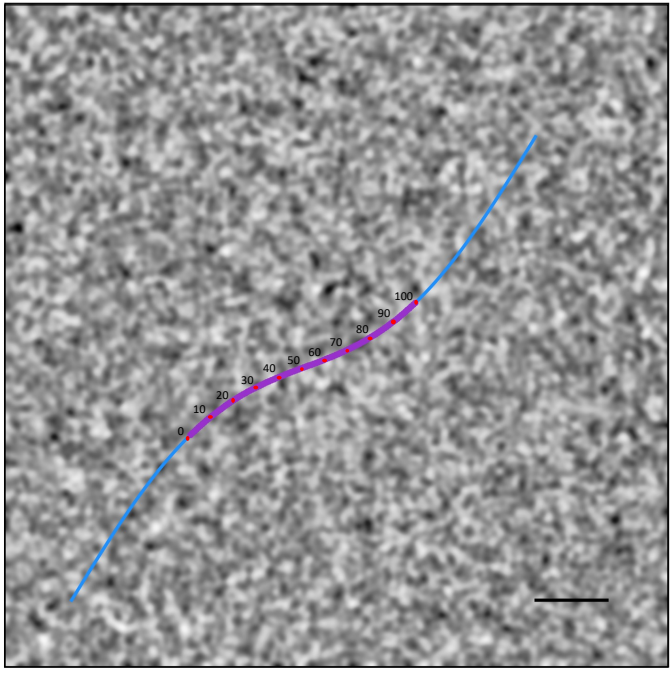


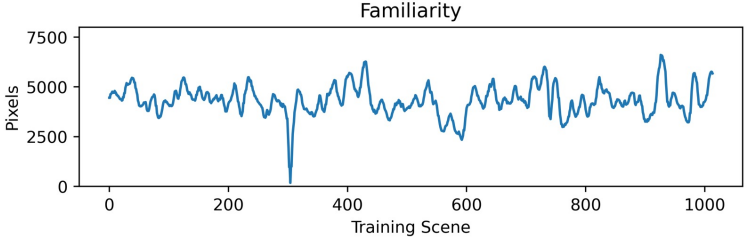


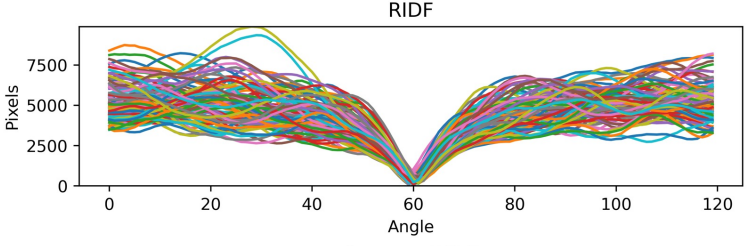
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

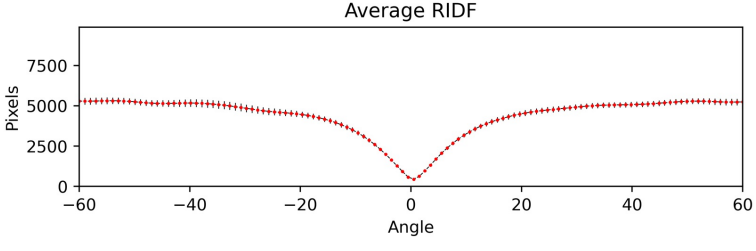
Navigation stats: RMSD error: 40.64; RMSD/dist: 0.102; TD: 3955; p90: 28; p50: 12; complete: 0

100%





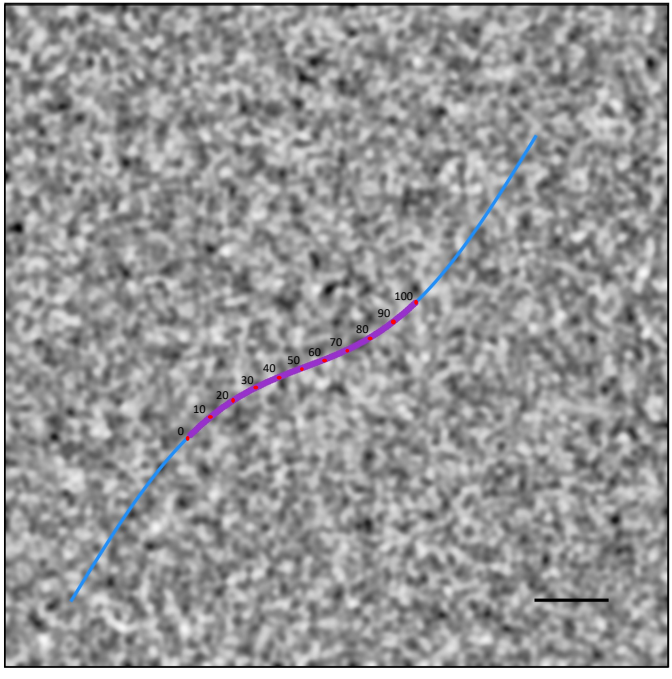


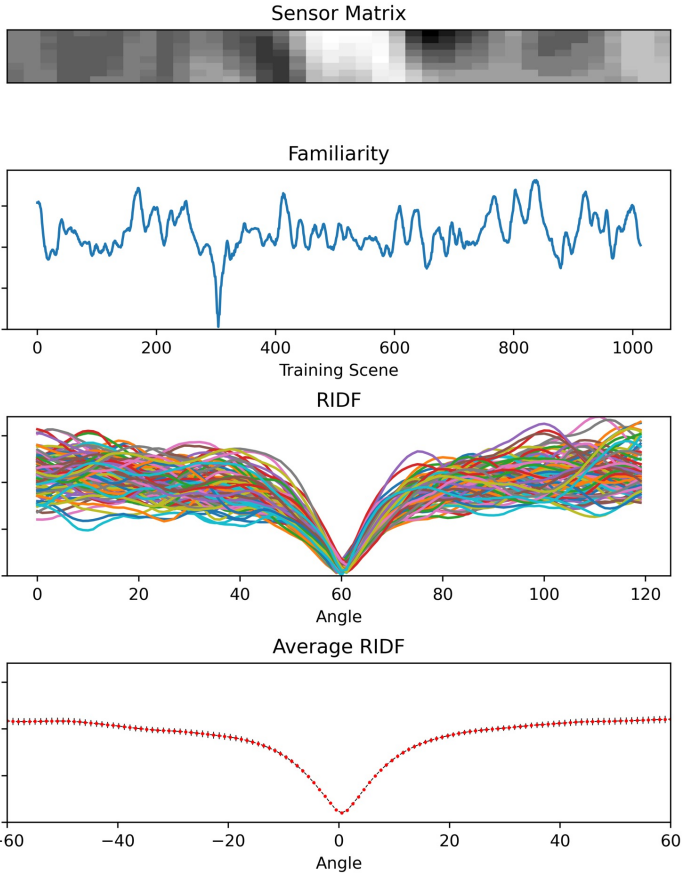


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 57.29; RMSD/dist: 0.143; TD: 3954; p90: 28; p50: 12; complete: 0

100%

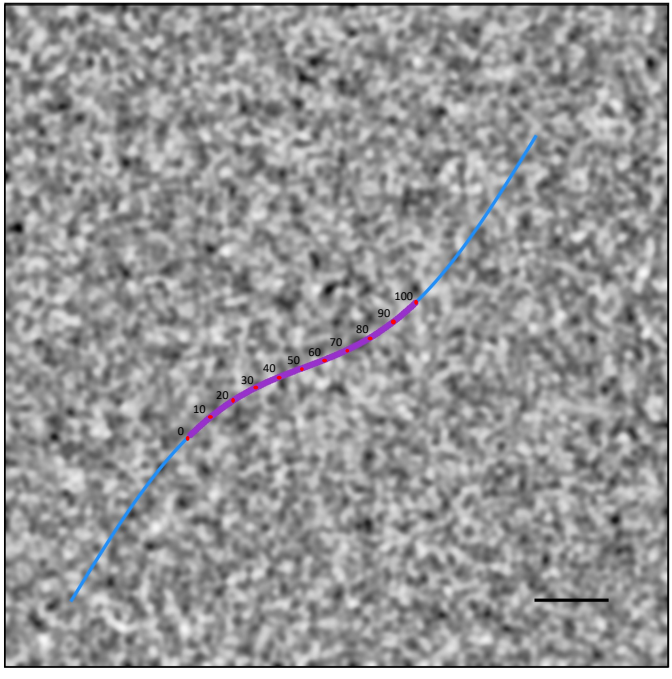


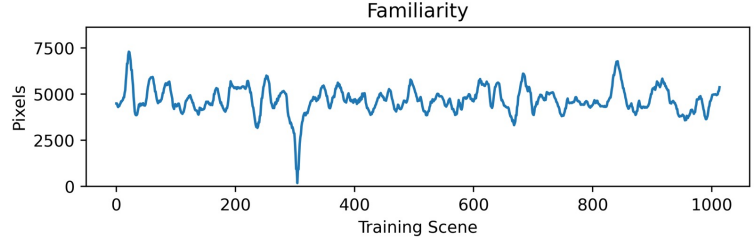


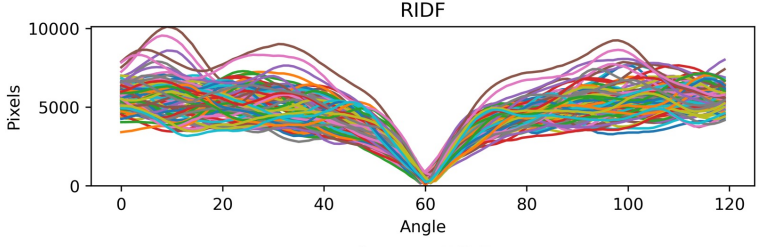
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

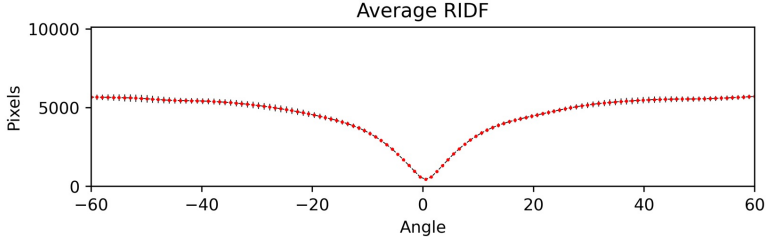
Navigation stats: RMSD error: 63.75; RMSD/dist: 0.159; TD: 3894; p90: 26; p50: 12; complete: 0

100%





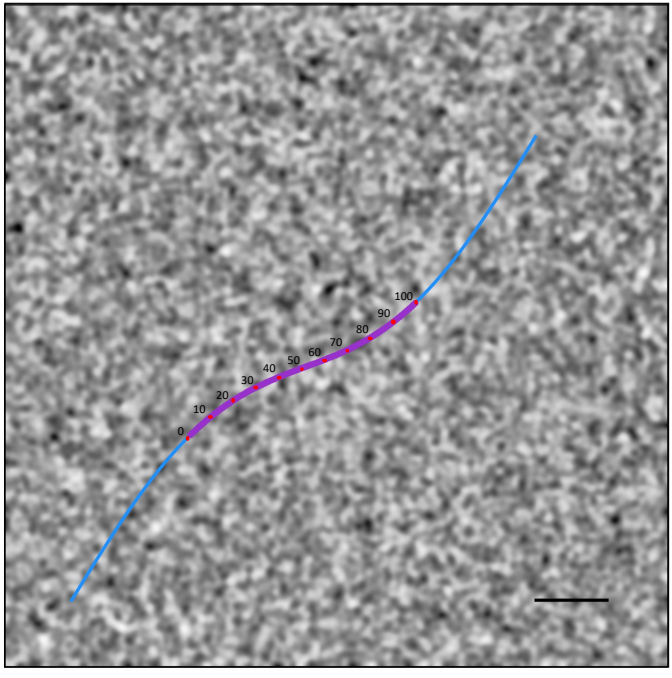


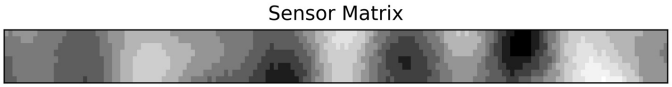


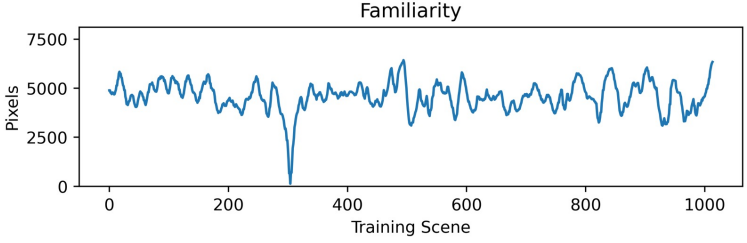
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

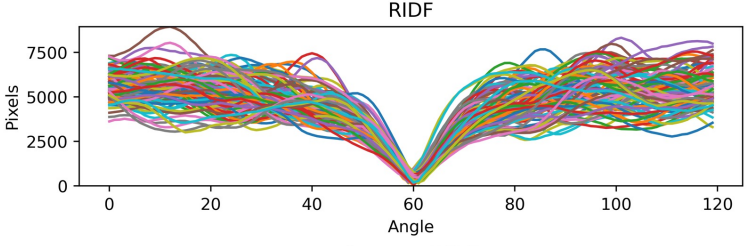
Navigation stats: RMSD error: 51.95; RMSD/dist: 0.130; TD: 3985; p90: 28; p50: 12; complete: 0

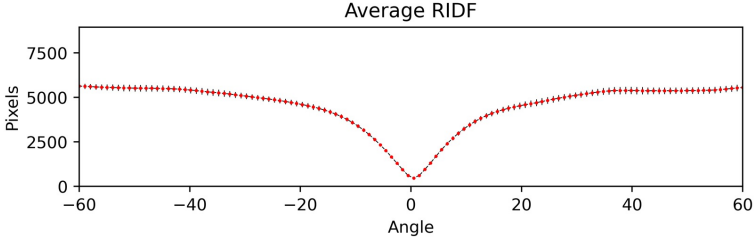
100%





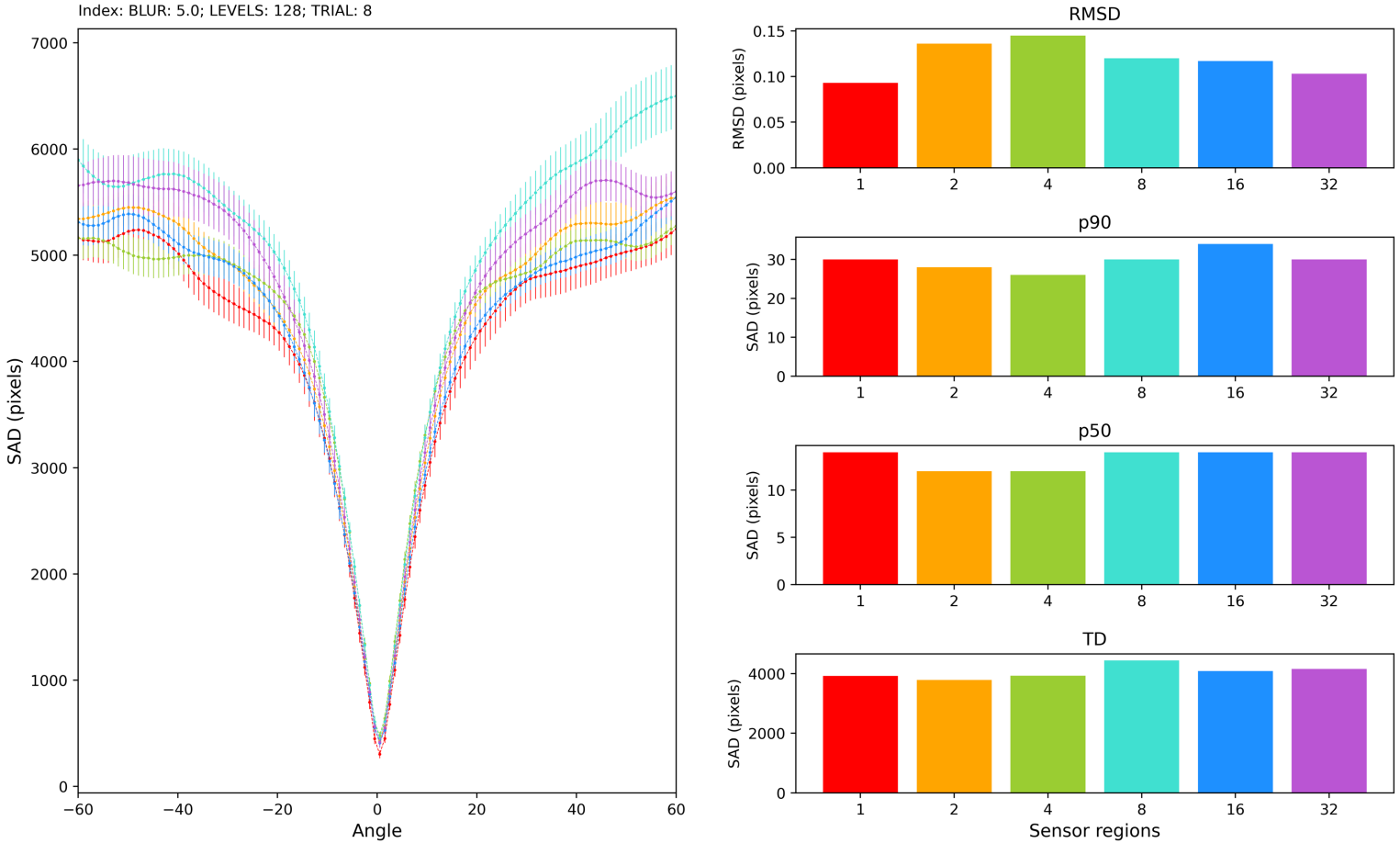




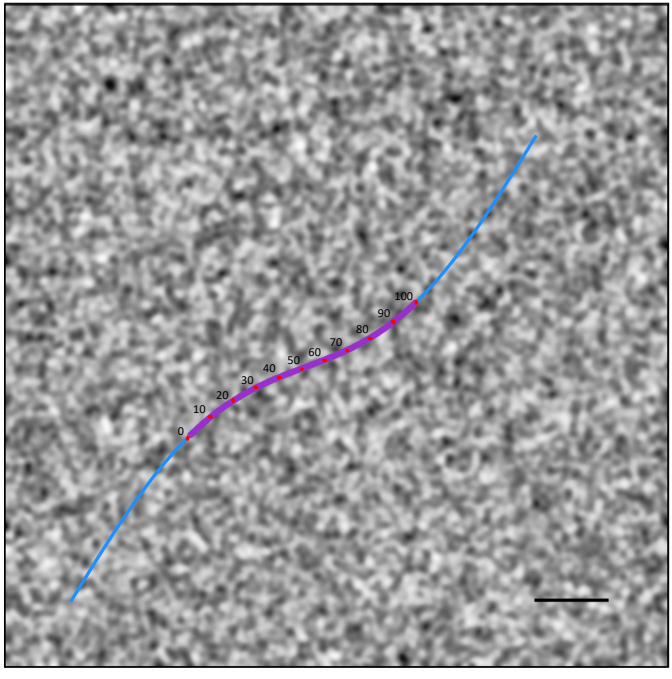


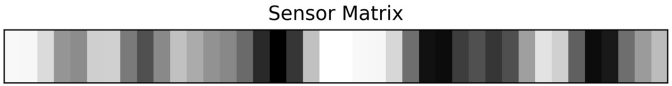
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

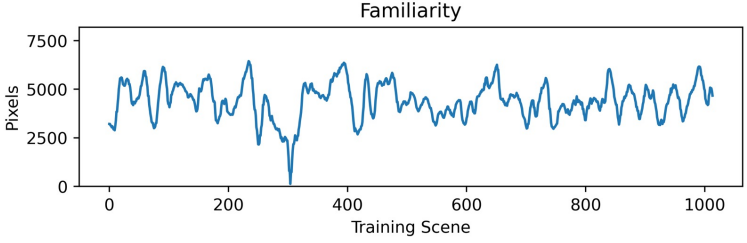
Navigation stats: RMSD error: 52.29; RMSD/dist: 0.131; TD: 4120; p90: 30; p50: 14; complete: 0

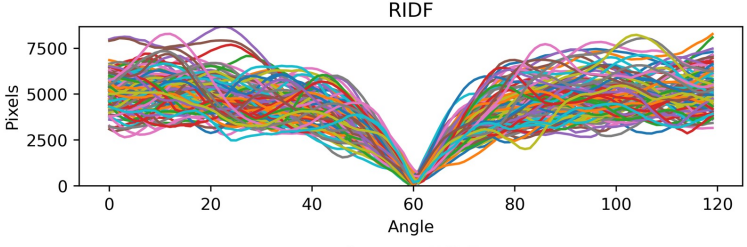

Index: BLUR: 5.0; LEVELS: 128; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

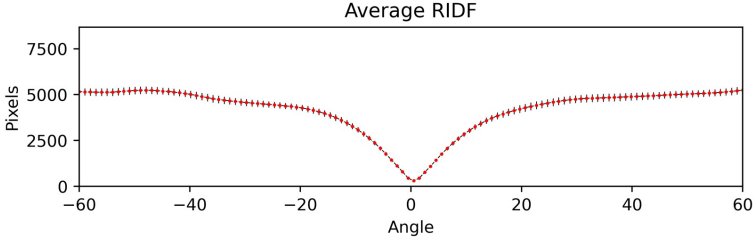
100%







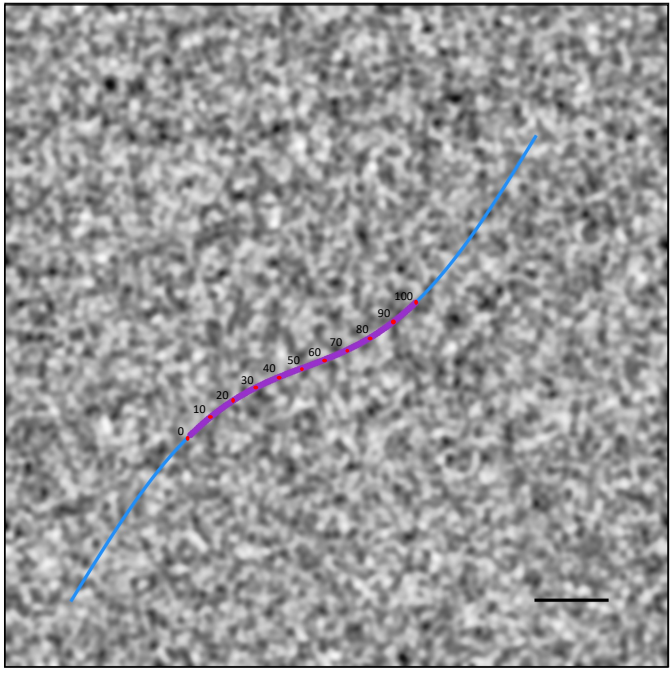


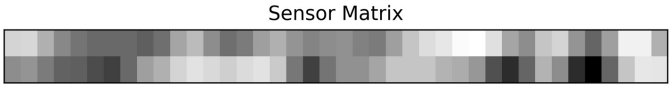


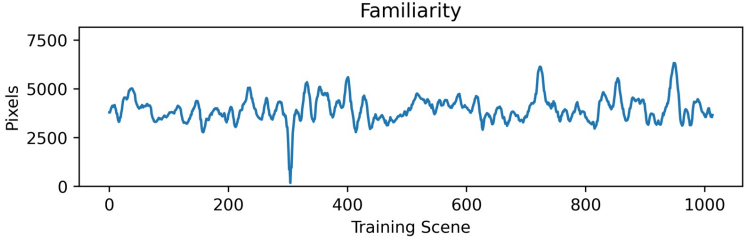
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

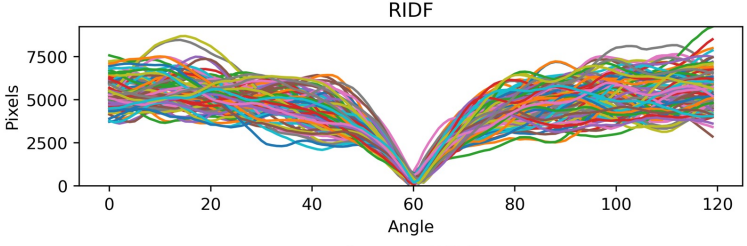
Navigation stats: RMSD error: 37.22; RMSD/dist: 0.093; TD: 3923; p90: 30; p50: 14; complete: 0

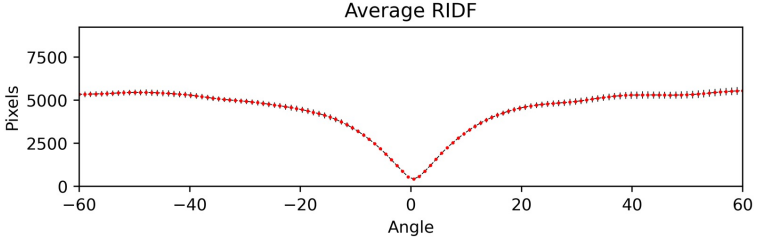
100%







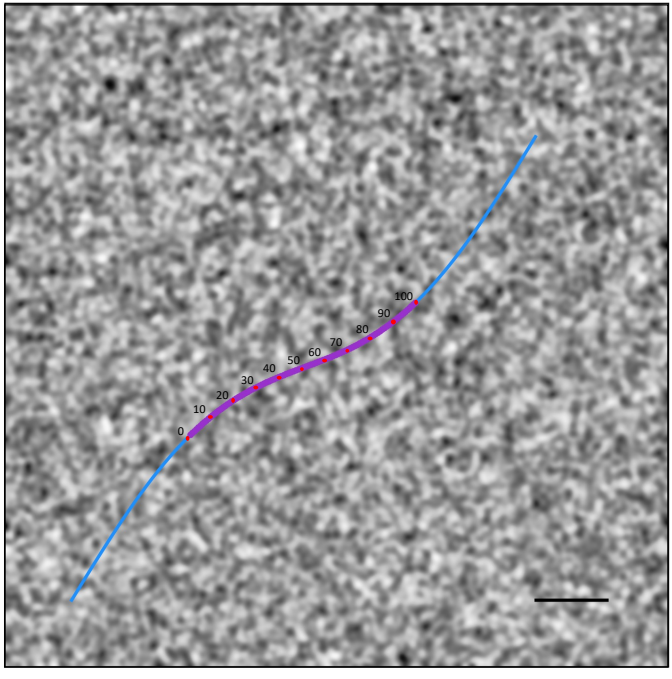


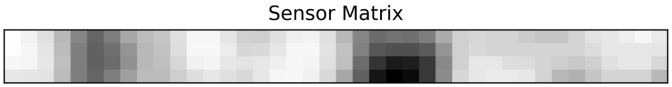


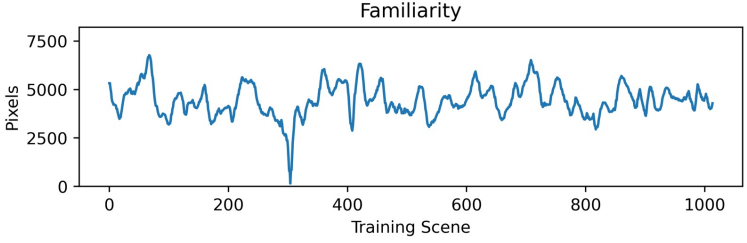
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

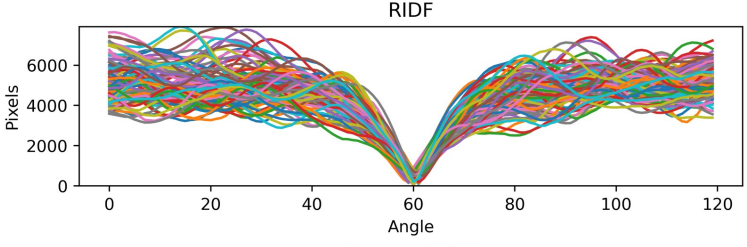
Navigation stats: RMSD error: 54.36; RMSD/dist: 0.136; TD: 3784; p90: 28; p50: 12; complete: 0

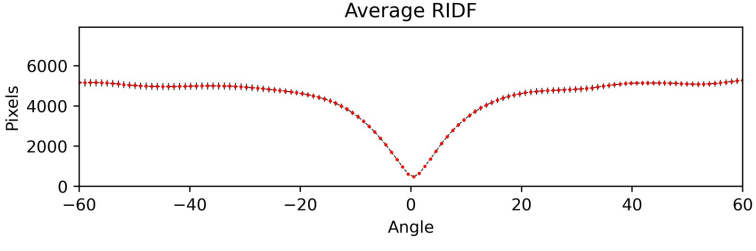
100%







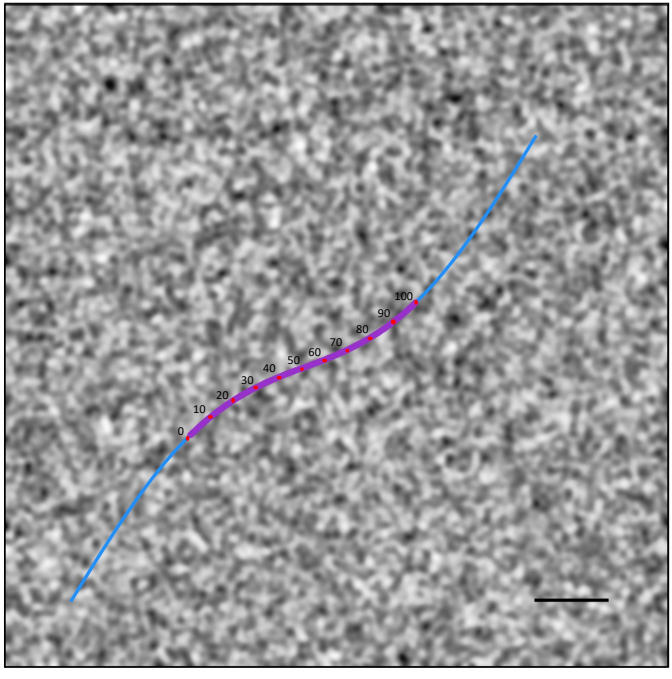


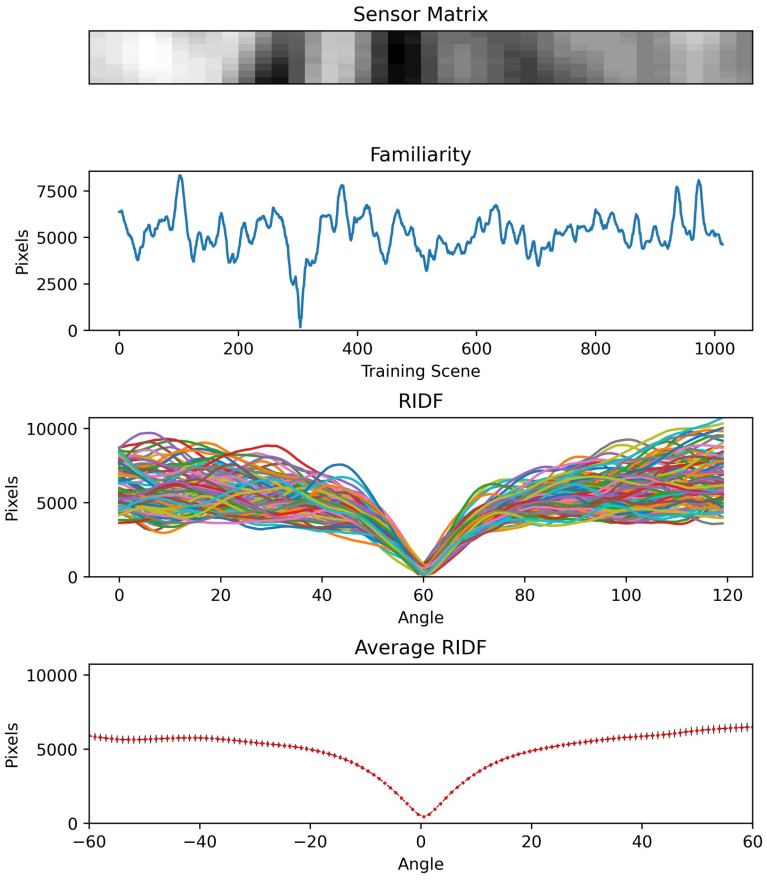


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 57.91; RMSD/dist: 0.145; TD: 3929; p90: 26; p50: 12; complete: 0

100%

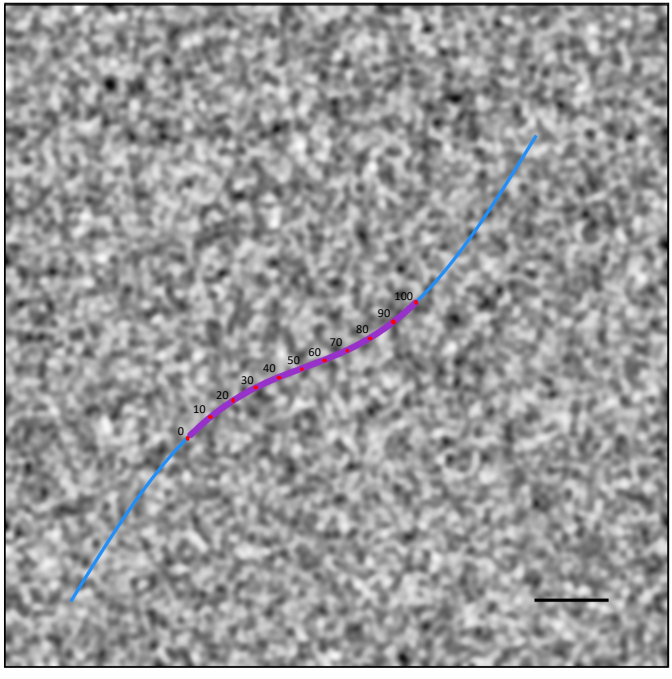


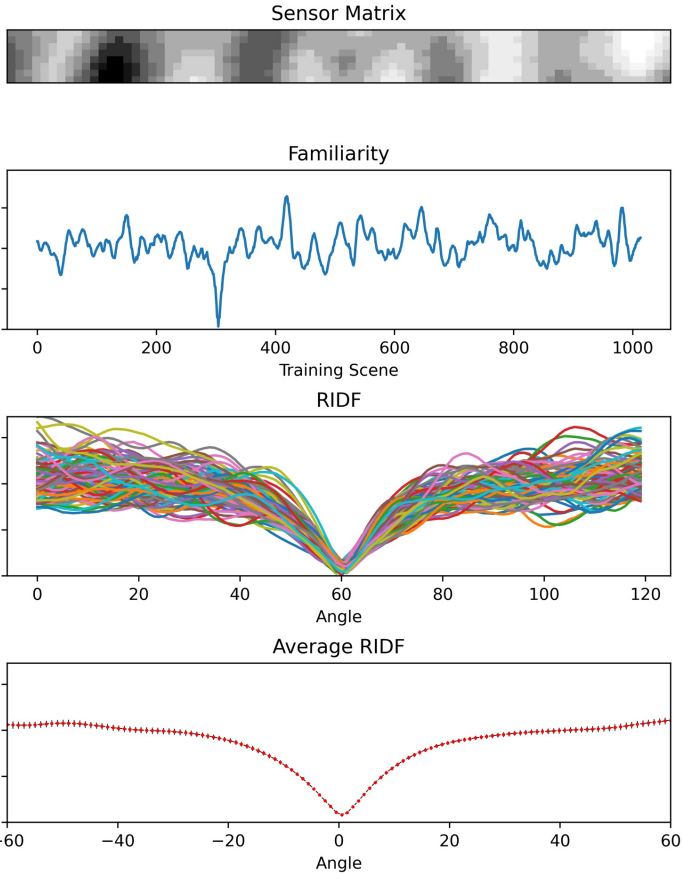


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 47.94; RMSD/dist: 0.120; TD: 4438; p90: 30; p50: 14; complete: 0

100%

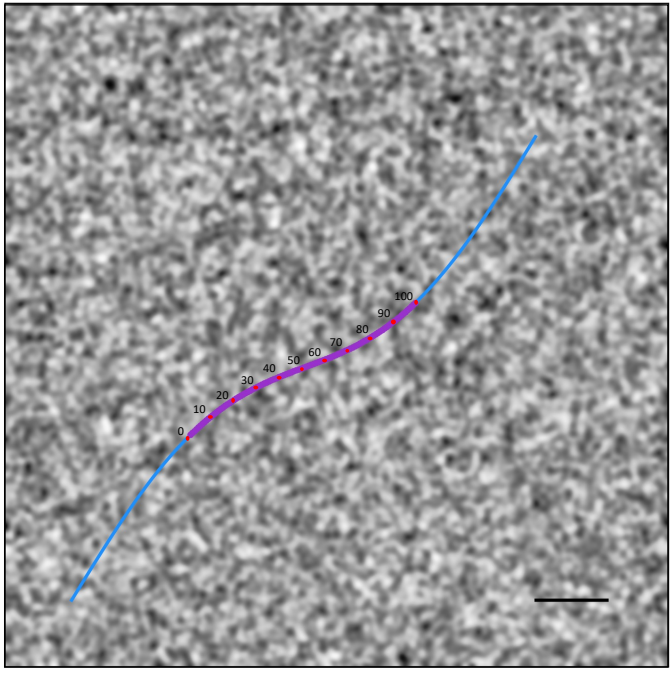


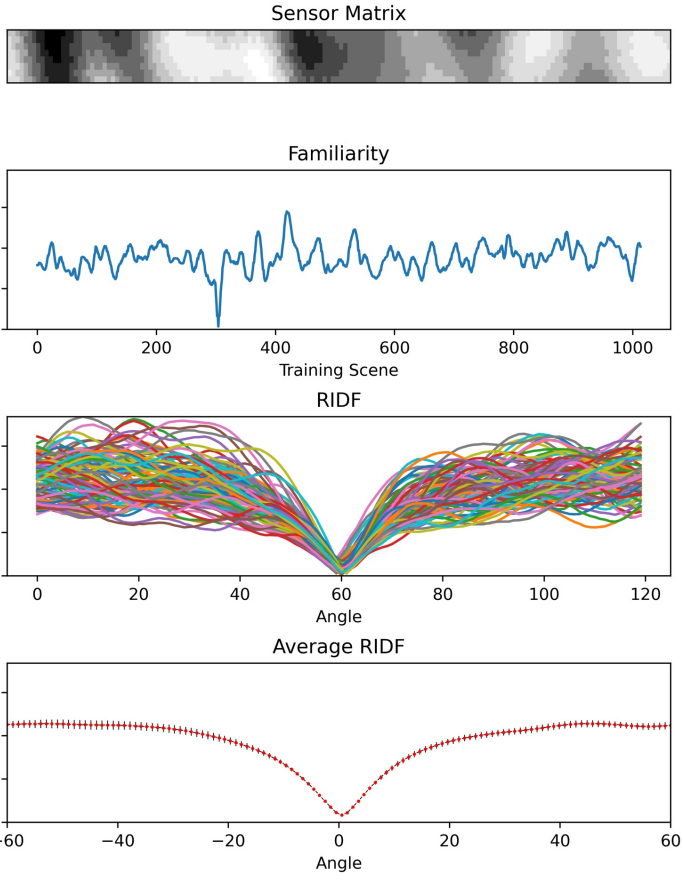


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 46.76; RMSD/dist: 0.117; TD: 4089; p90: 34; p50: 14; complete: 0

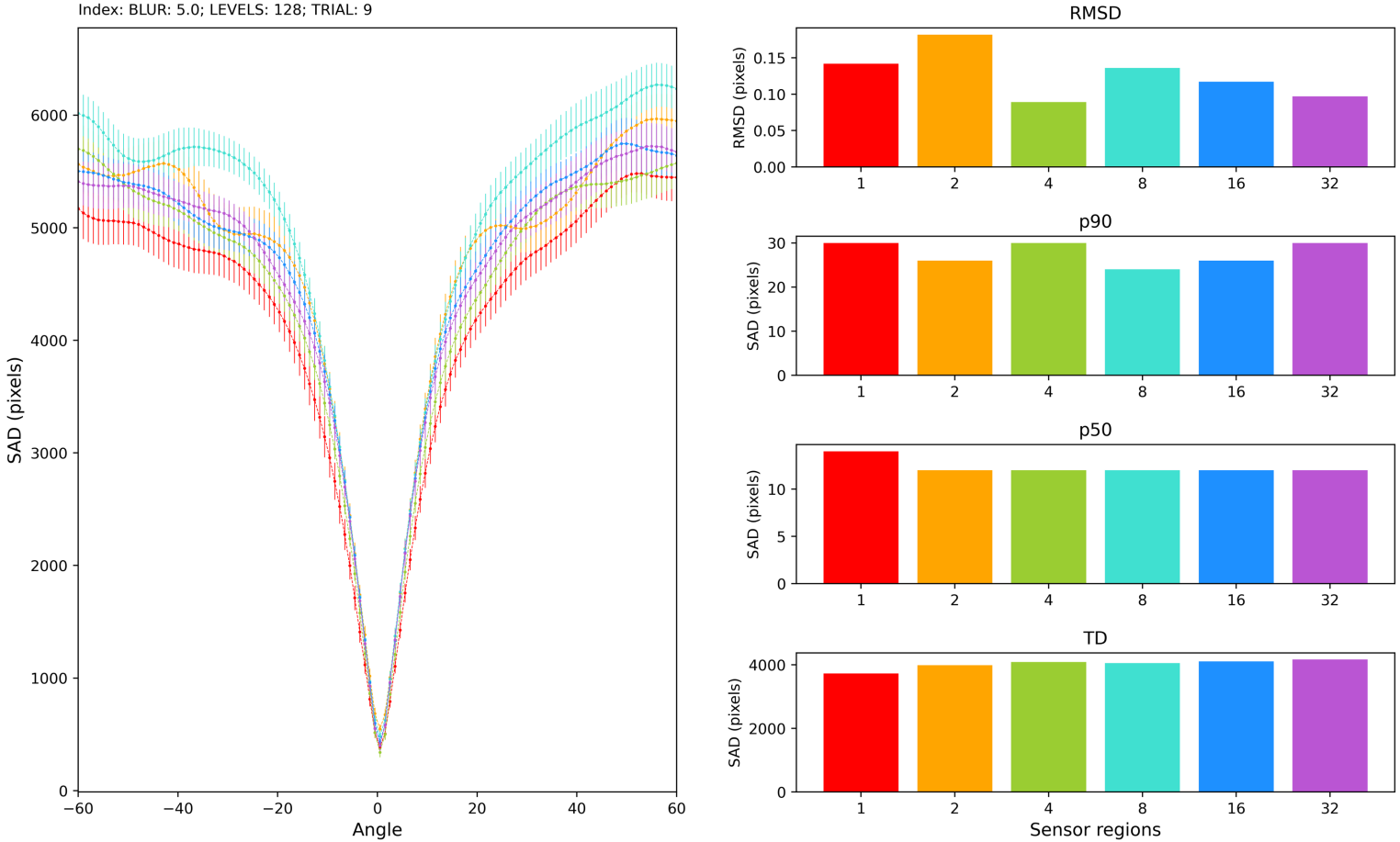
100%



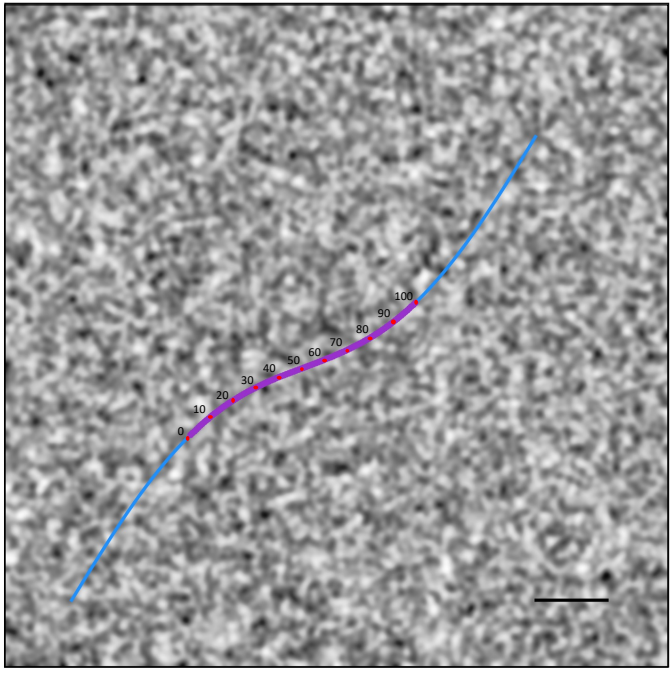


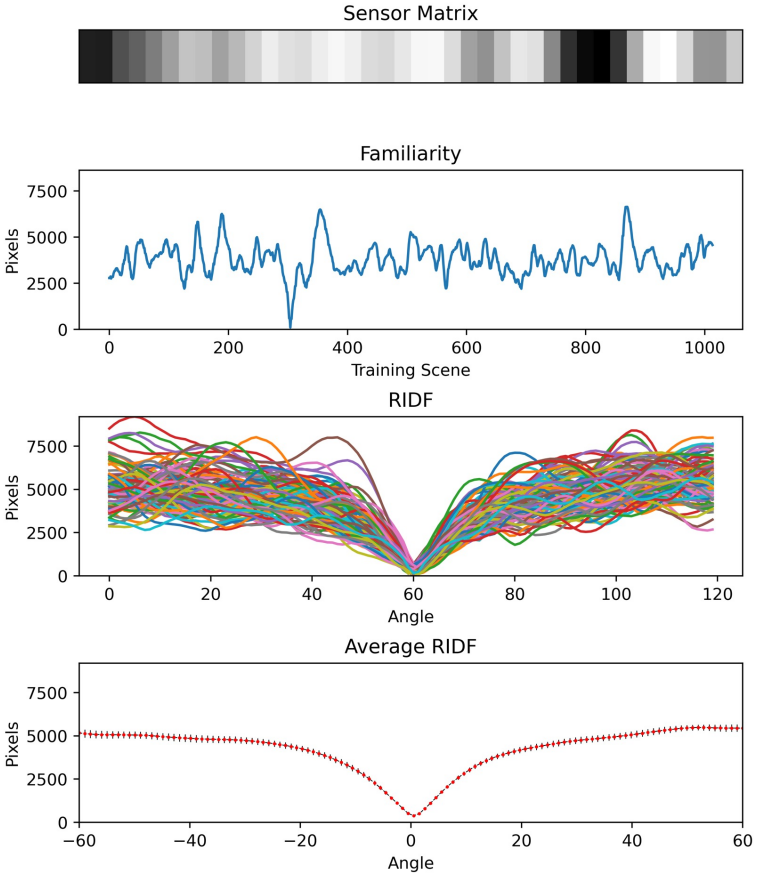
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 41.40; RMSD/dist: 0.103; TD: 4155; p90: 30; p50: 14; complete: 0


Index: BLUR: 5.0; LEVELS: 128; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

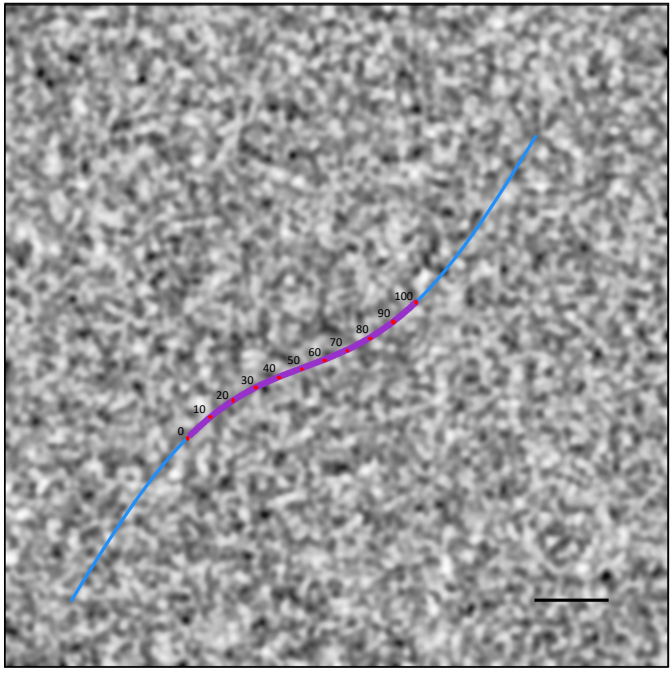


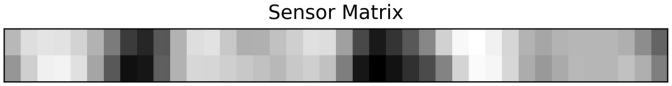


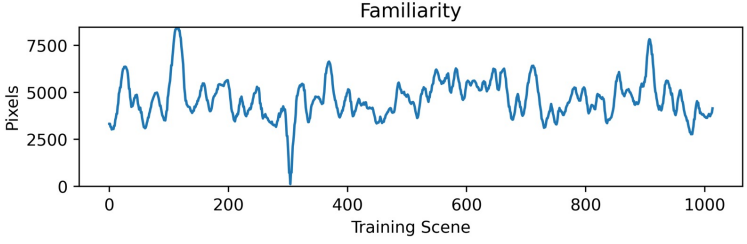
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

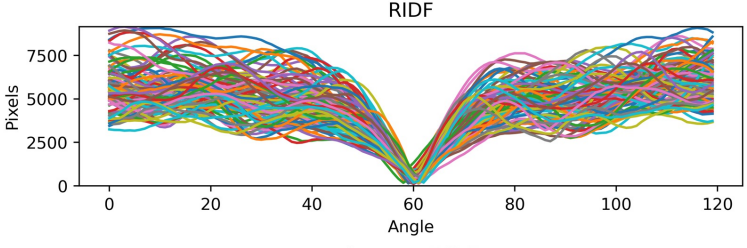
Navigation stats: RMSD error: 56.64; RMSD/dist: 0.142; TD: 3730; p90: 30; p50: 14; complete: 0

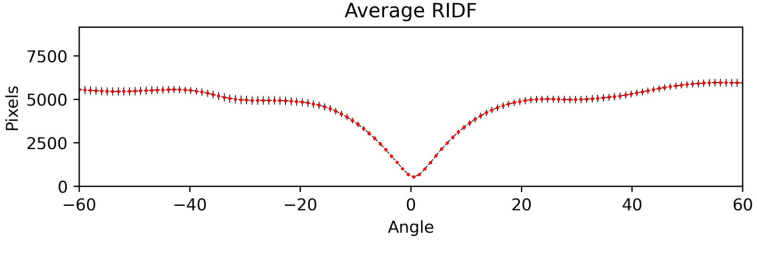
100%







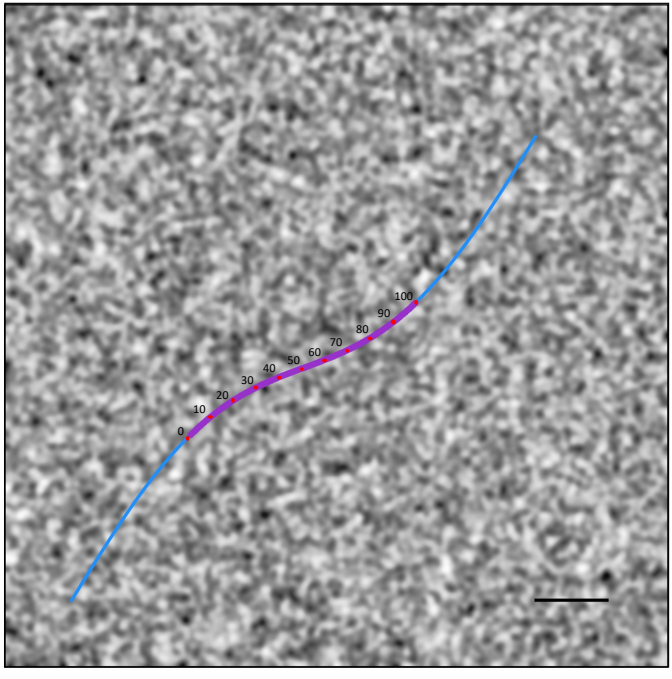


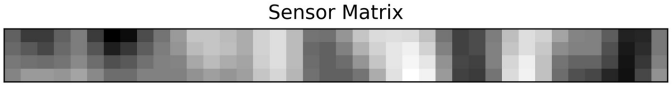


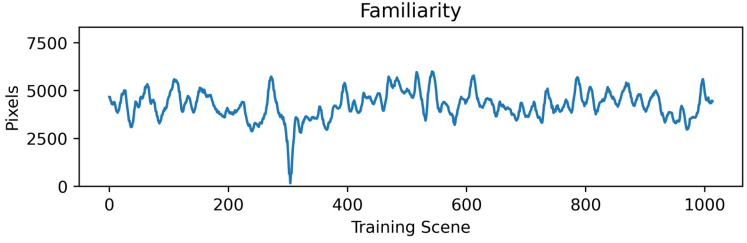
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

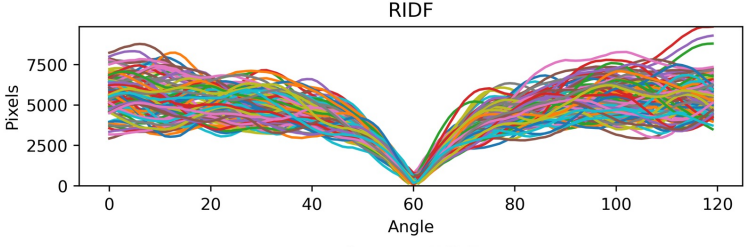
Navigation stats: RMSD error: 72.90; RMSD/dist: 0.182; TD: 3986; p90: 26; p50: 12; complete: 0

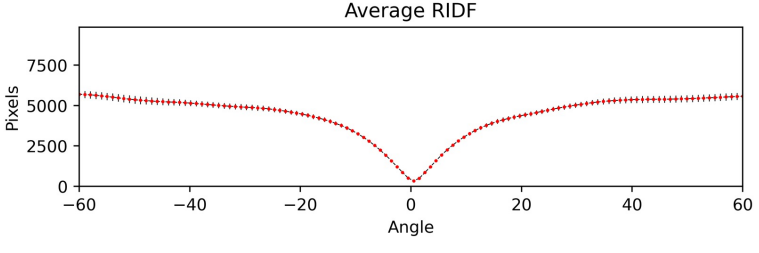
100%







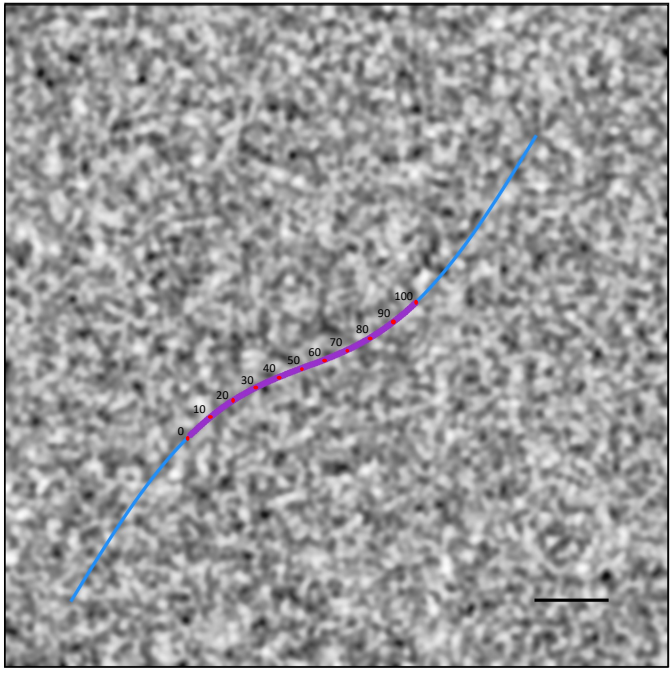


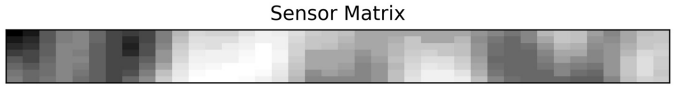


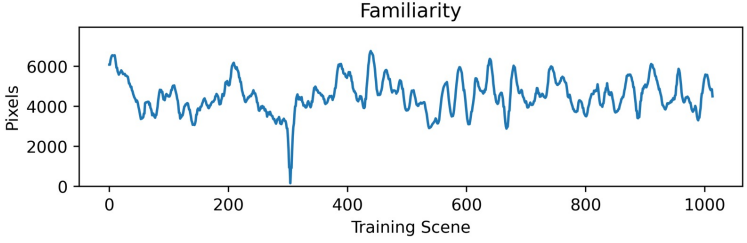
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

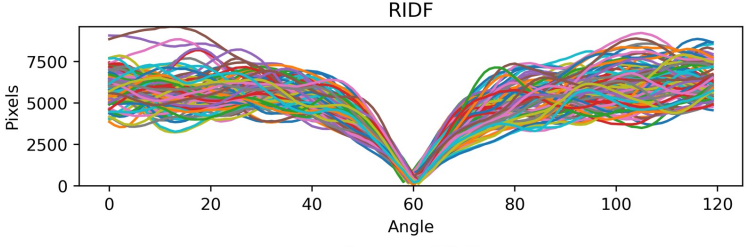
Navigation stats: RMSD error: 35.40; RMSD/dist: 0.089; TD: 4086; p90: 30; p50: 12; complete: 0

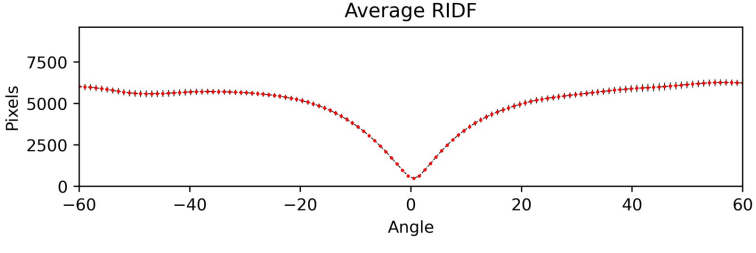
100%







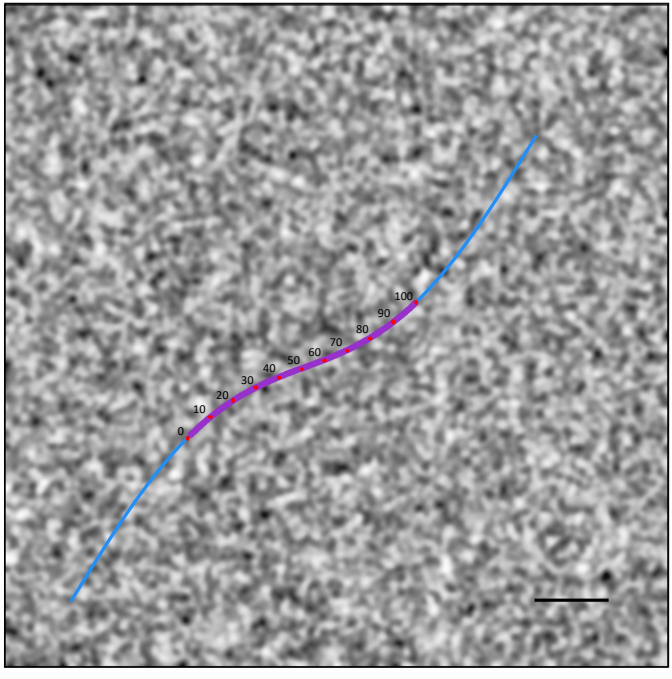


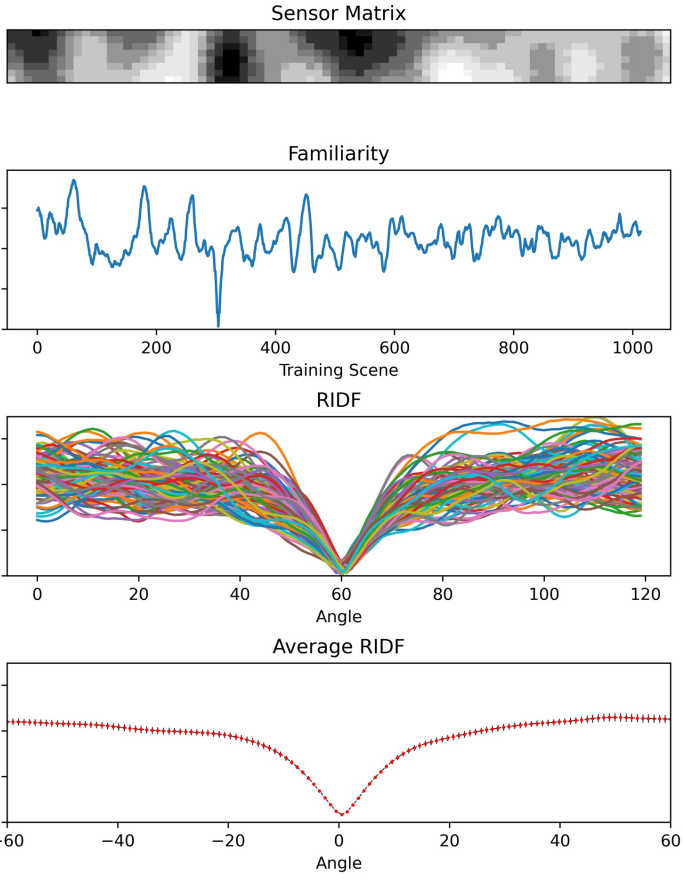


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 54.59; RMSD/dist: 0.136; TD: 4057; p90: 24; p50: 12; complete: 0

100%

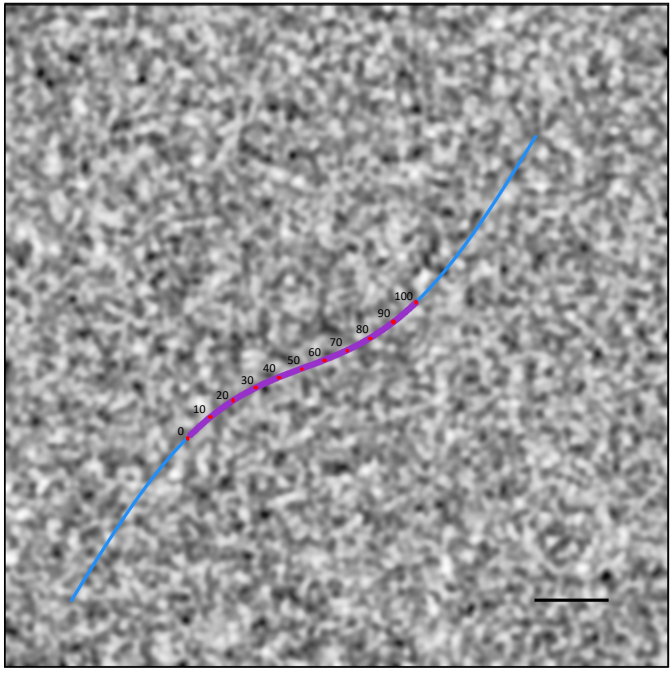


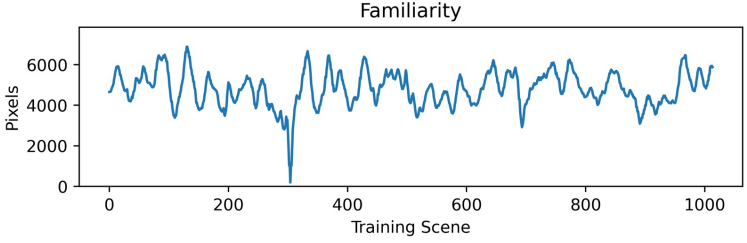


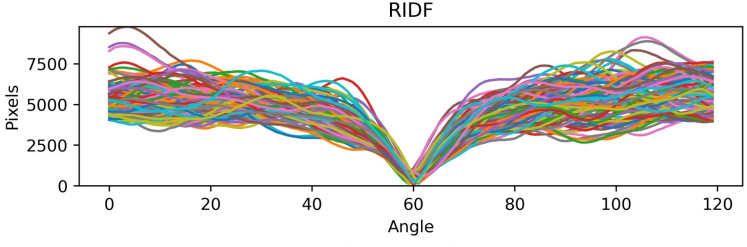
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

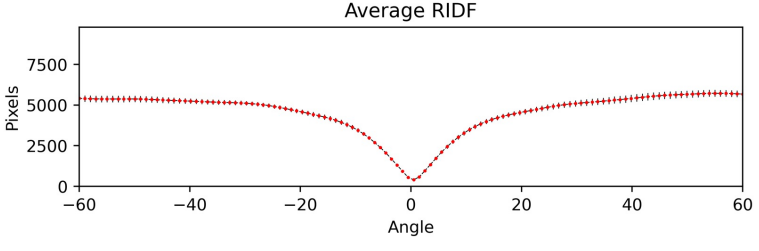
Navigation stats: RMSD error: 46.98; RMSD/dist: 0.117; TD: 4106; p90: 26; p50: 12; complete: 0

100%



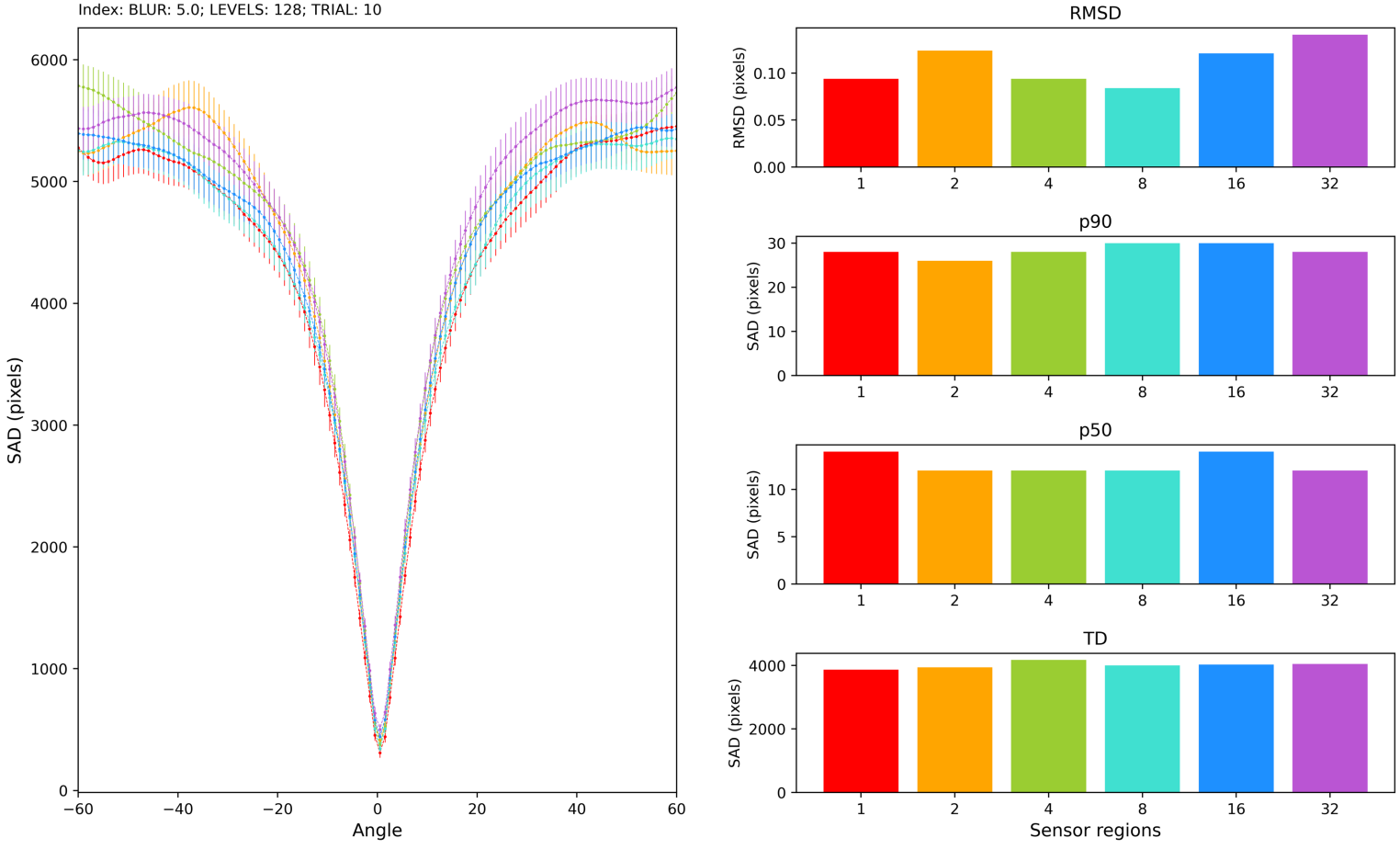




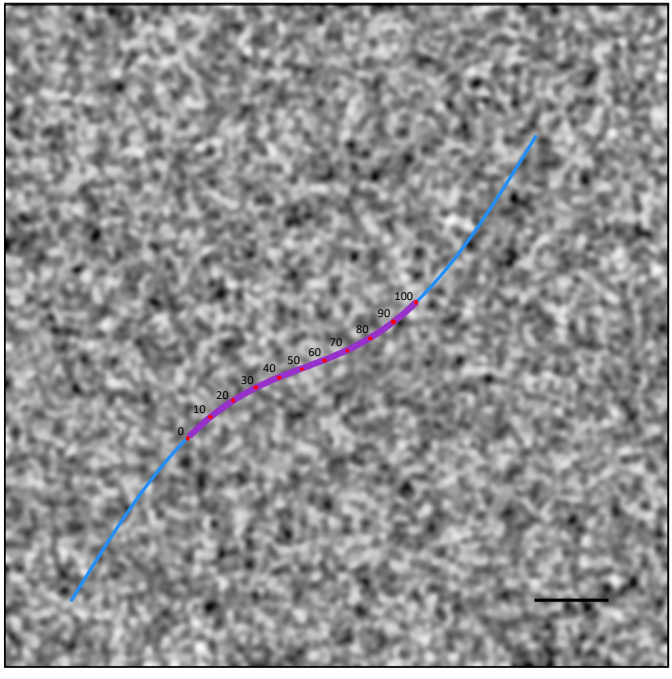


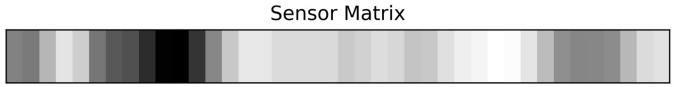
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

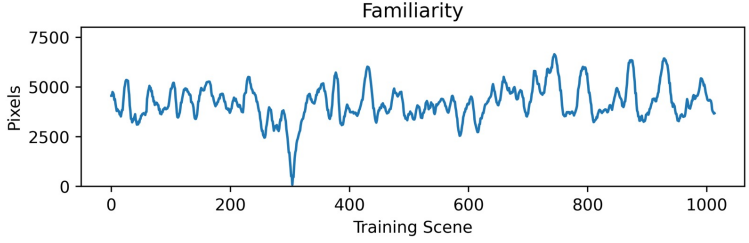
Navigation stats: RMSD error: 38.82; RMSD/dist: 0.097; TD: 4165; p90: 30; p50: 12; complete: 0

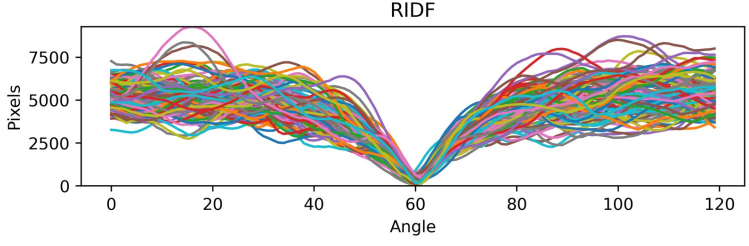

Index: BLUR: 5.0; LEVELS: 128; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

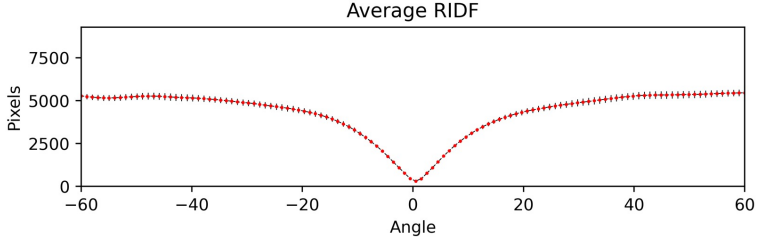
100%







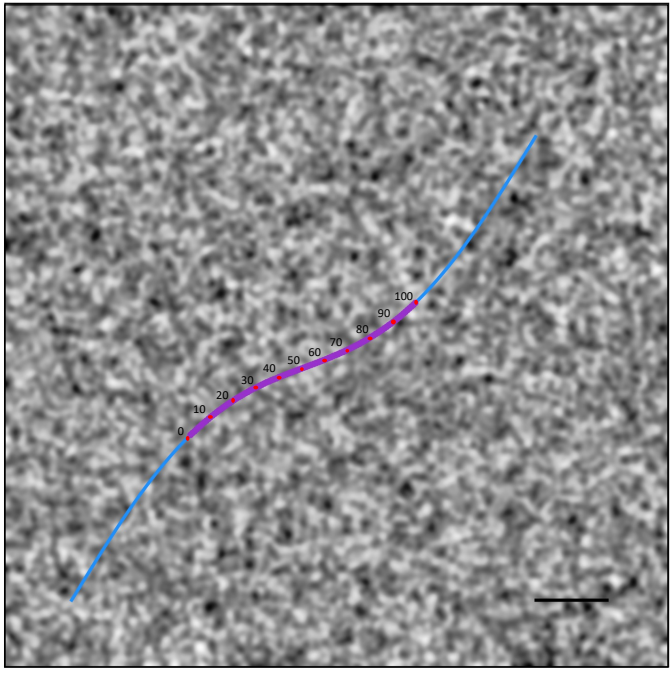


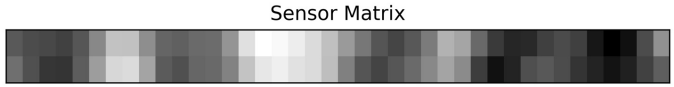


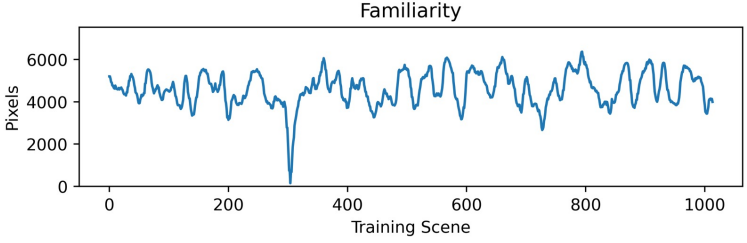
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

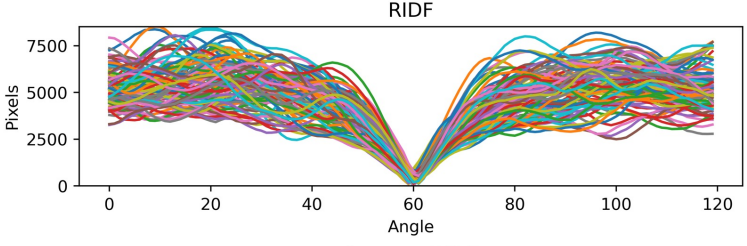
Navigation stats: RMSD error: 37.65; RMSD/dist: 0.094; TD: 3870; p90: 28; p50: 14; complete: 0

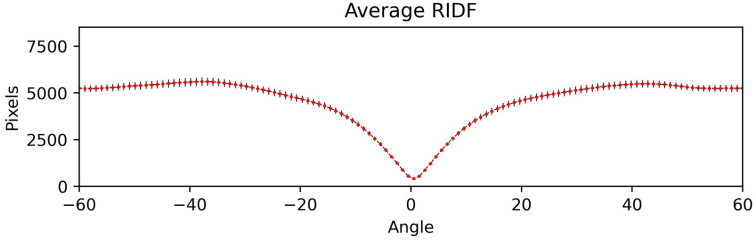
100%







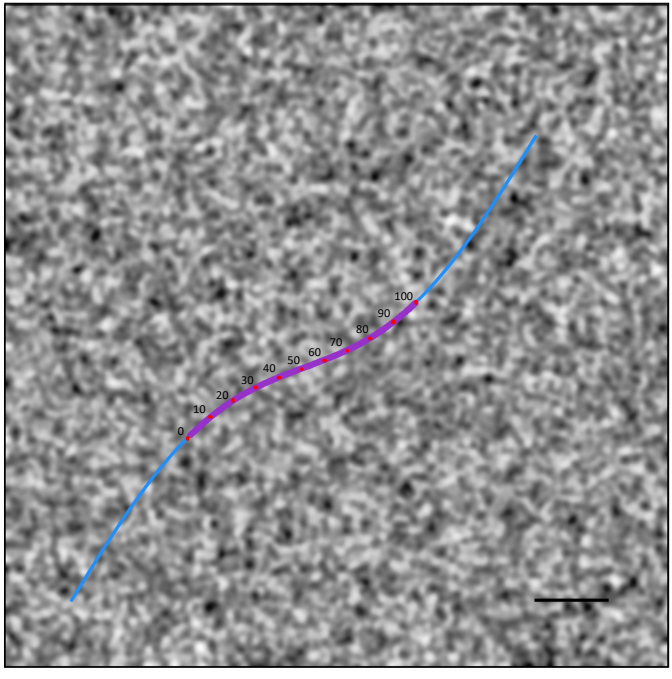


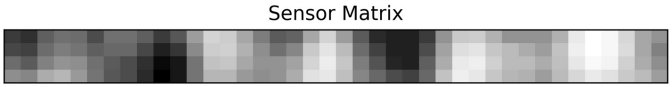


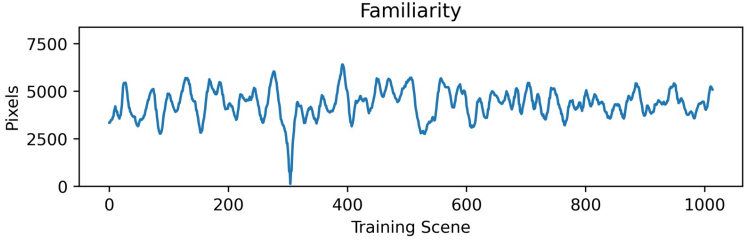
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

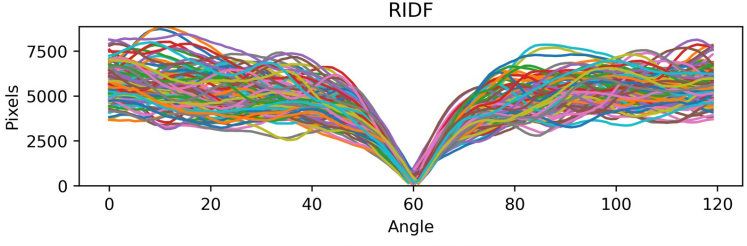
Navigation stats: RMSD error: 49.69; RMSD/dist: 0.124; TD: 3944; p90: 26; p50: 12; complete: 0

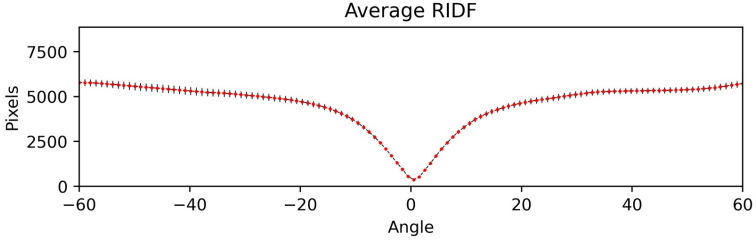
100%







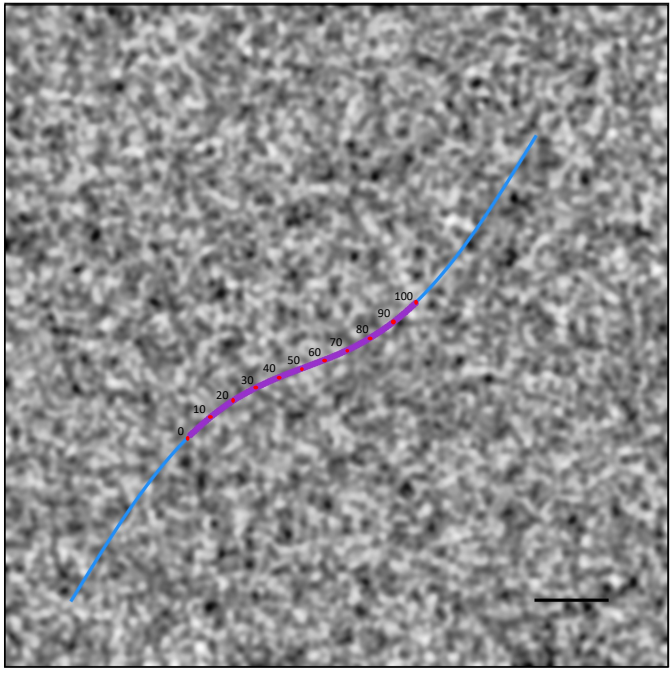


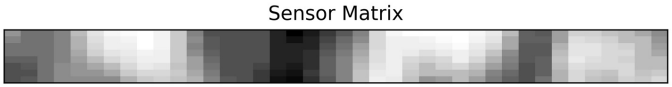


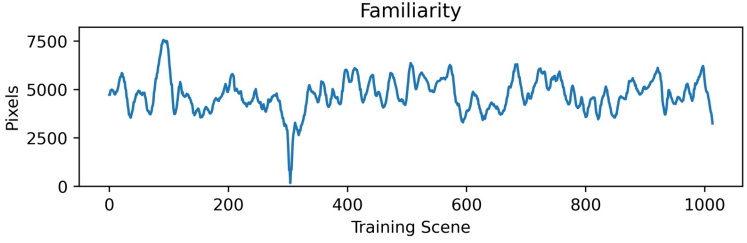
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

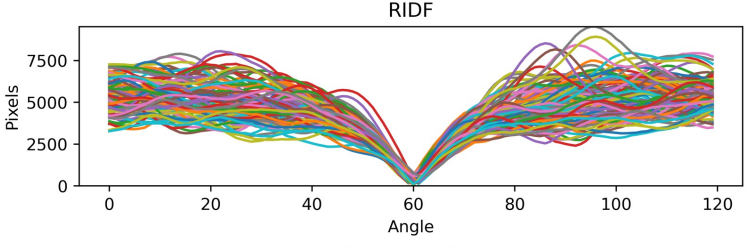
Navigation stats: RMSD error: 37.49; RMSD/dist: 0.094; TD: 4172; p90: 28; p50: 12; complete: 0

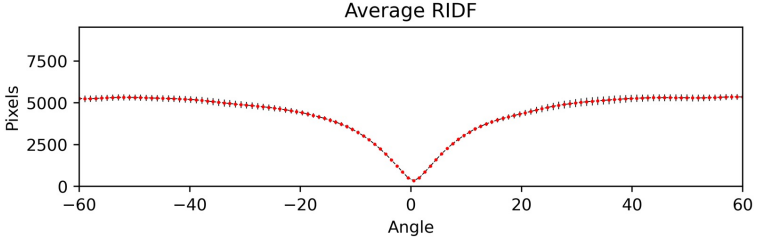
100%







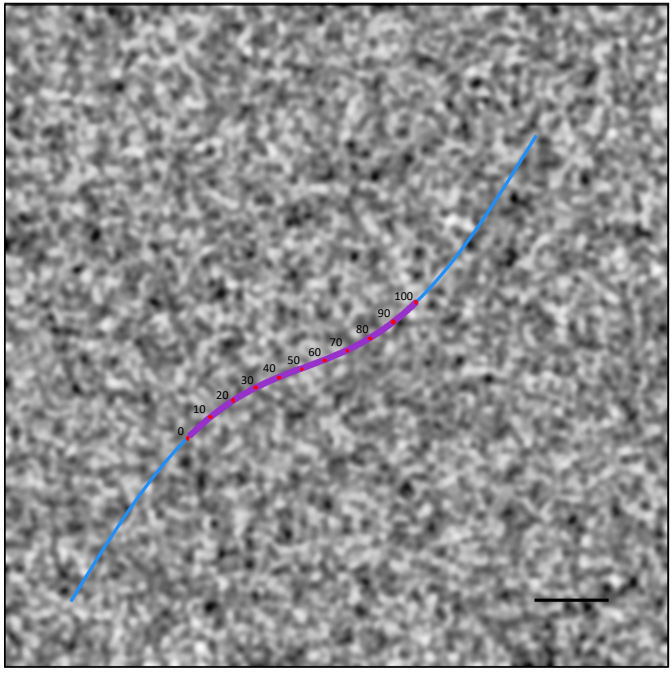


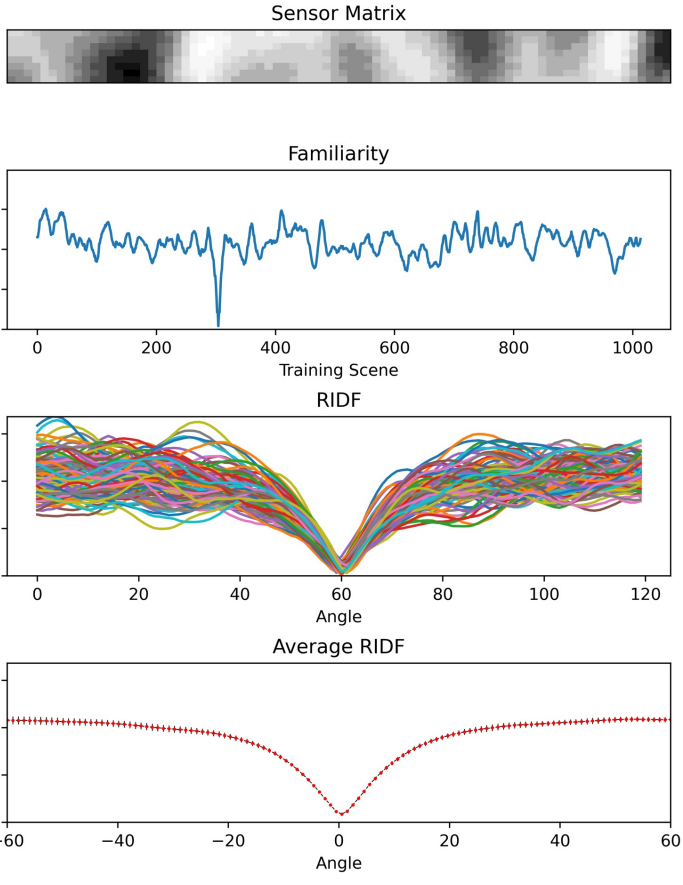


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 33.78; RMSD/dist: 0.084; TD: 4001; p90: 30; p50: 12; complete: 0

100%

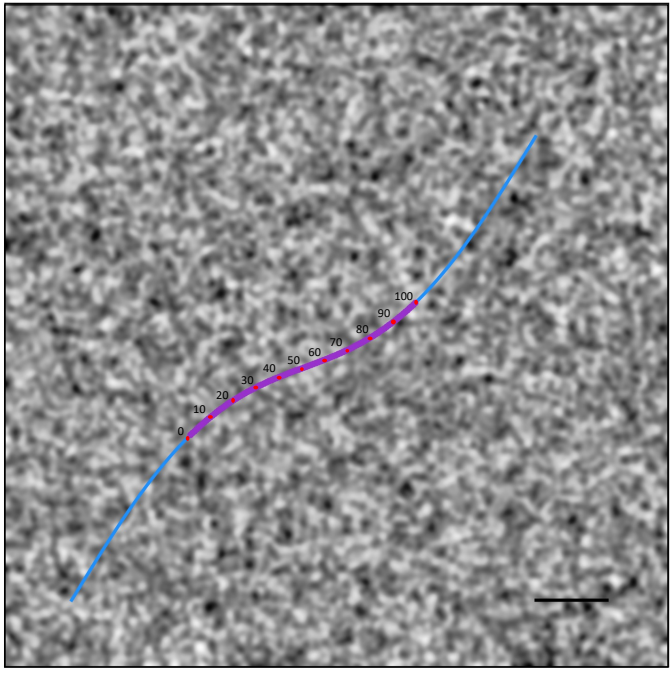


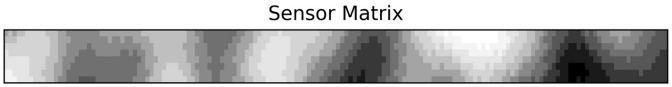


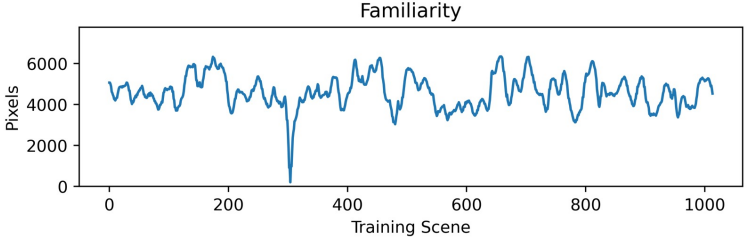
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

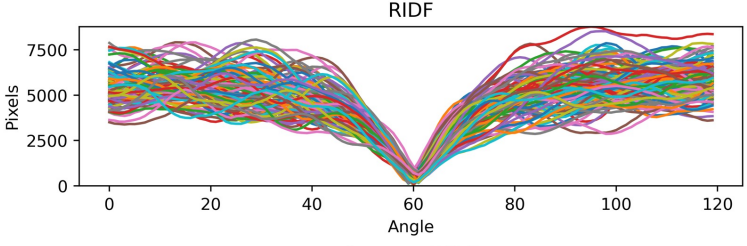
Navigation stats: RMSD error: 48.58; RMSD/dist: 0.121; TD: 4028; p90: 30; p50: 14; complete: 0

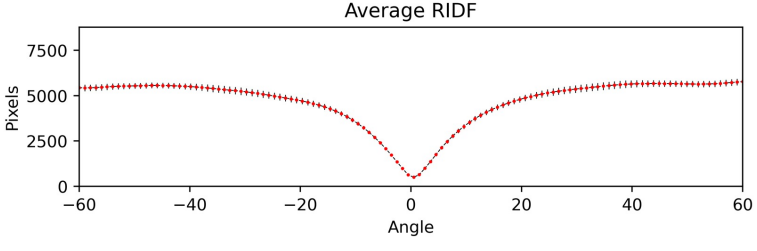
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 56.21; RMSD/dist: 0.141; TD: 4048; p90: 28; p50: 12; complete: 0