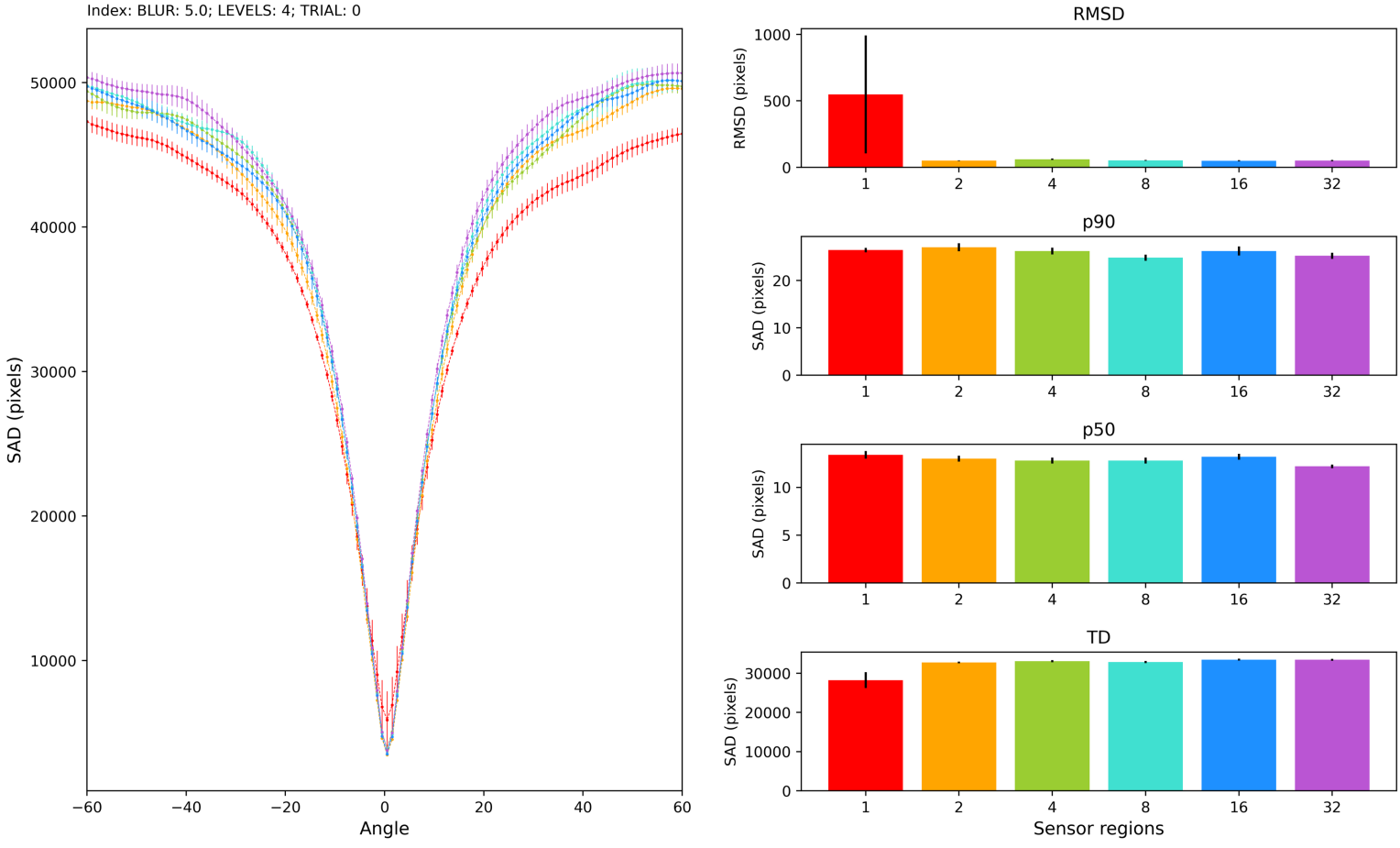
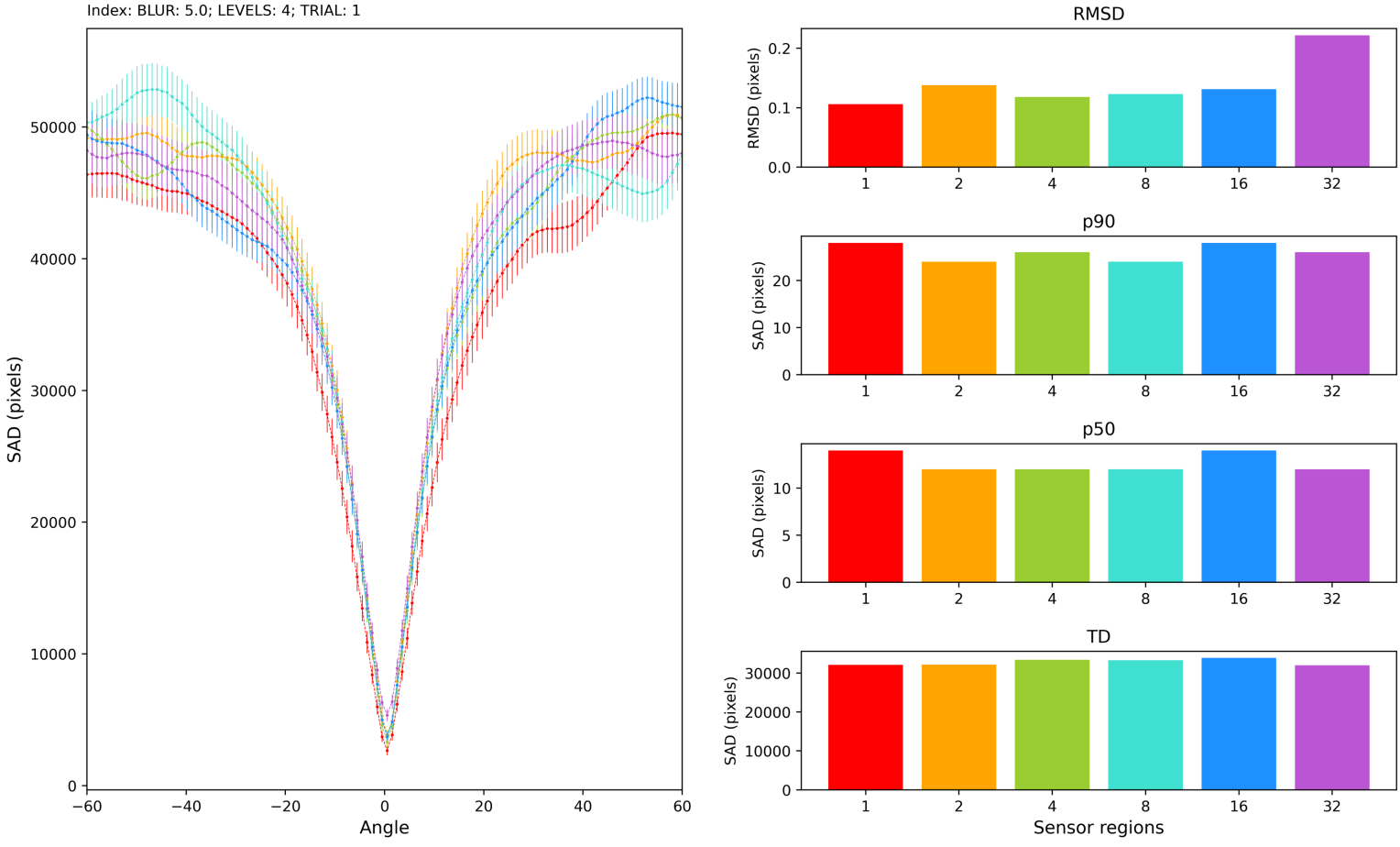
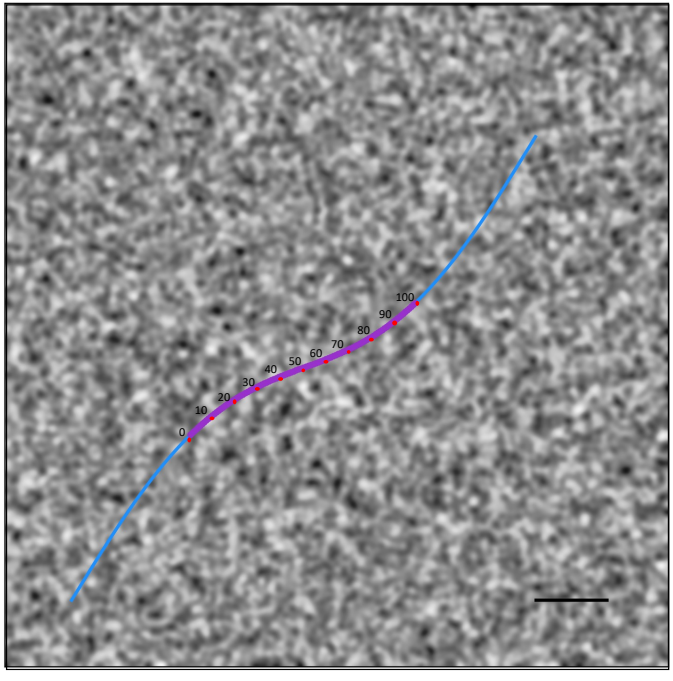
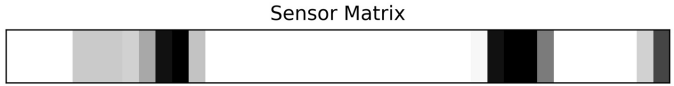
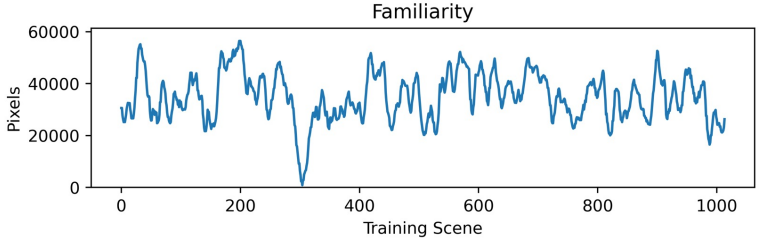

Index: BLUR: 5.0; LEVELS: 4; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

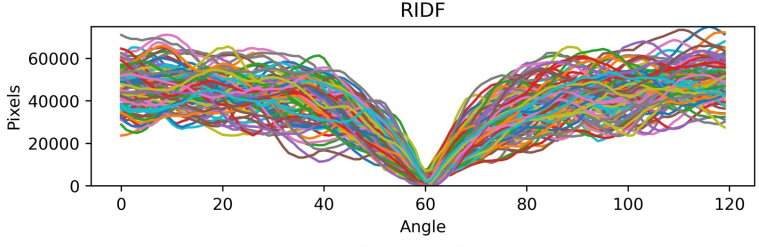

Index: BLUR: 5.0; LEVELS: 4; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

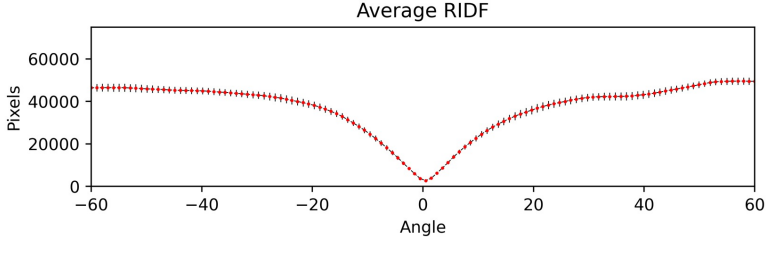
100%







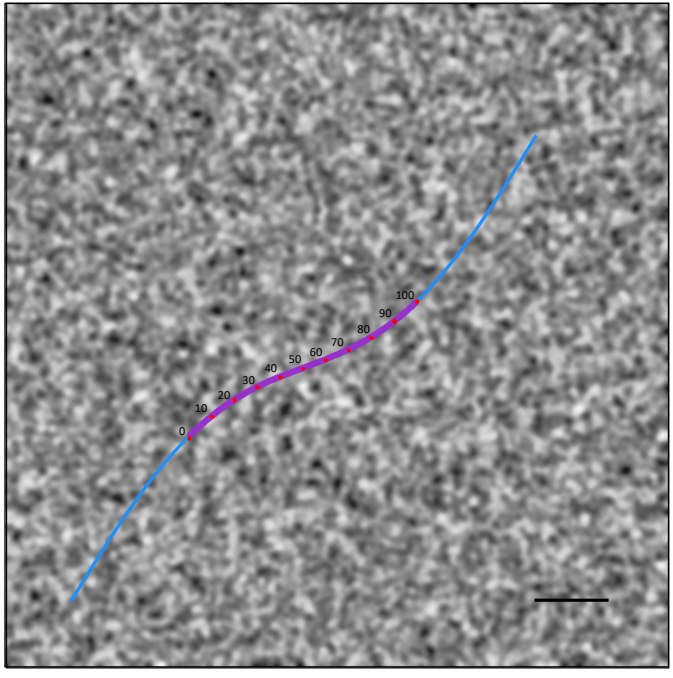


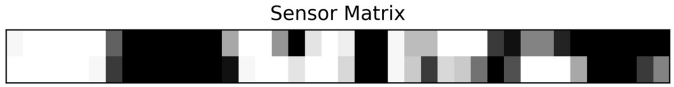


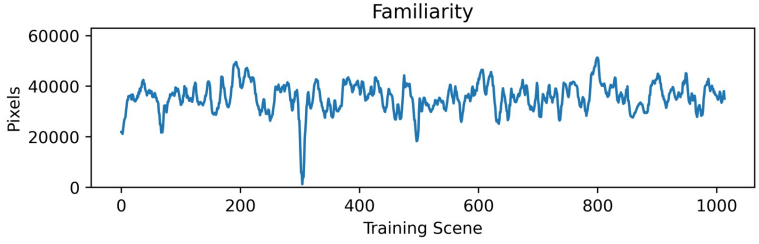
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

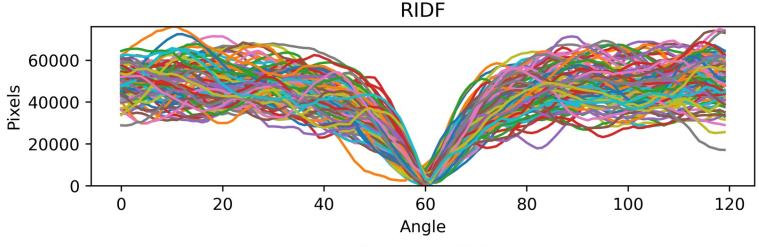
Navigation stats: RMSD error: 42.44; RMSD/dist: 0.106; TD: 32122; p90: 28; p50: 14; complete: 0

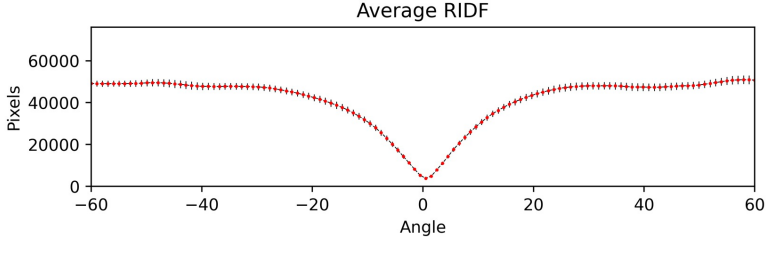
100%







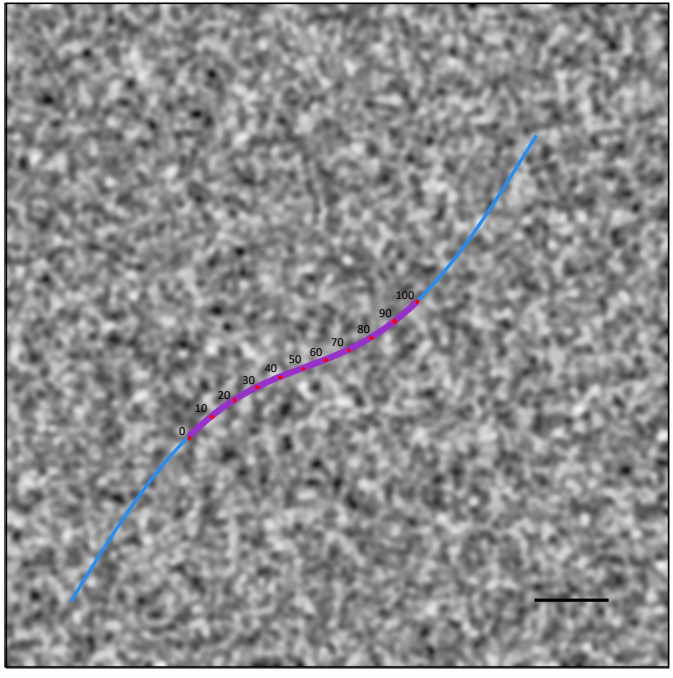


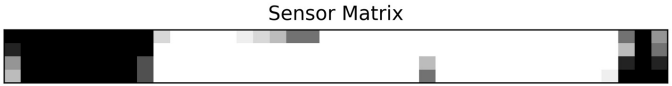


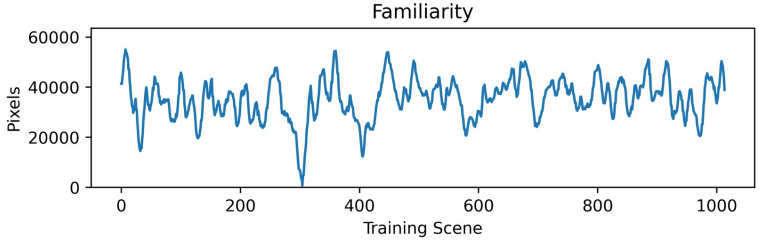
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

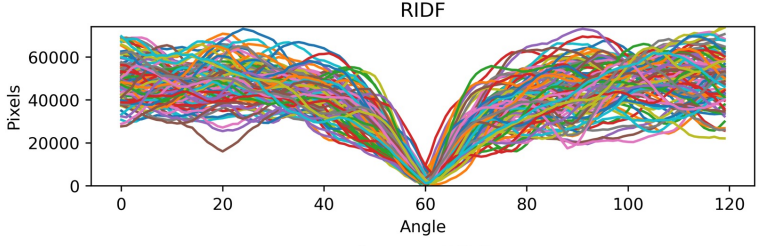
Navigation stats: RMSD error: 55.22; RMSD/dist: 0.138; TD: 32183; p90: 24; p50: 12; complete: 0

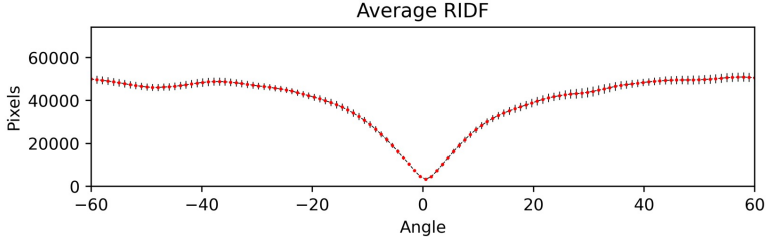
100%







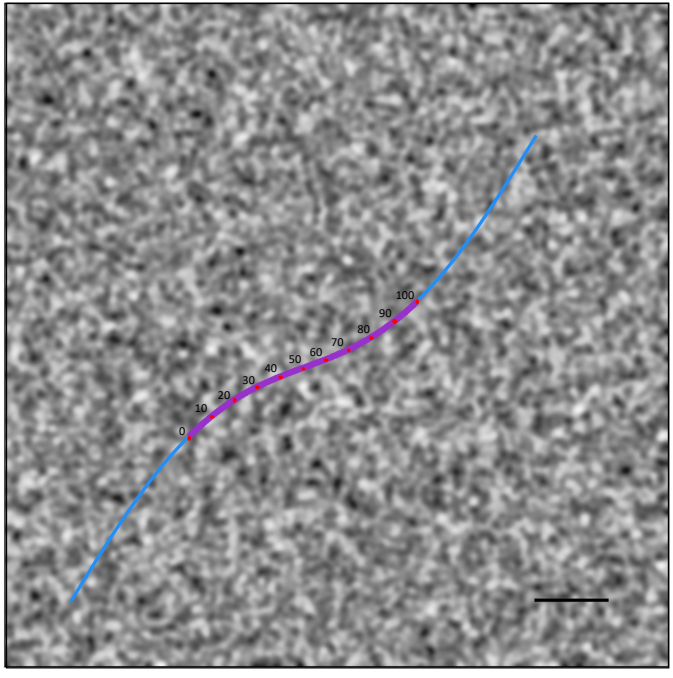


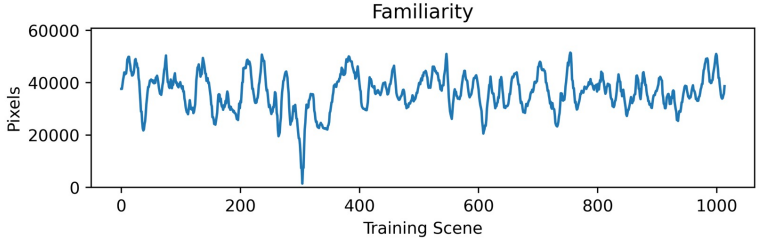


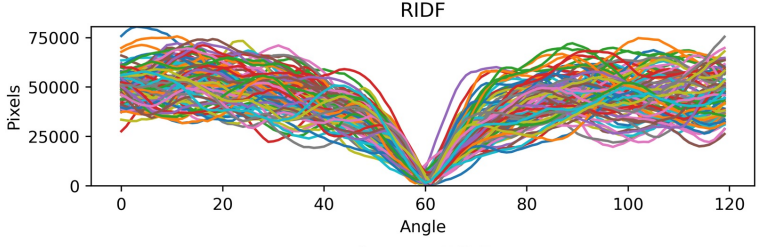
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

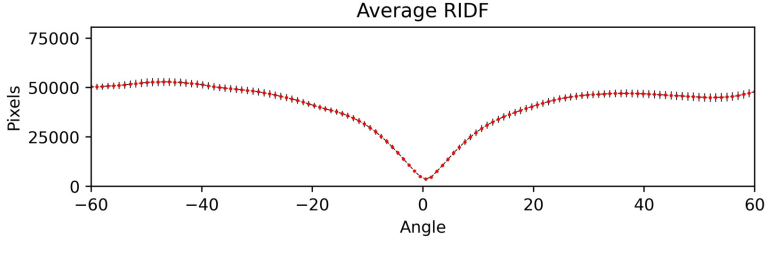
Navigation stats: RMSD error: 47.26; RMSD/dist: 0.118; TD: 33436; p90: 26; p50: 12; complete: 0

100%





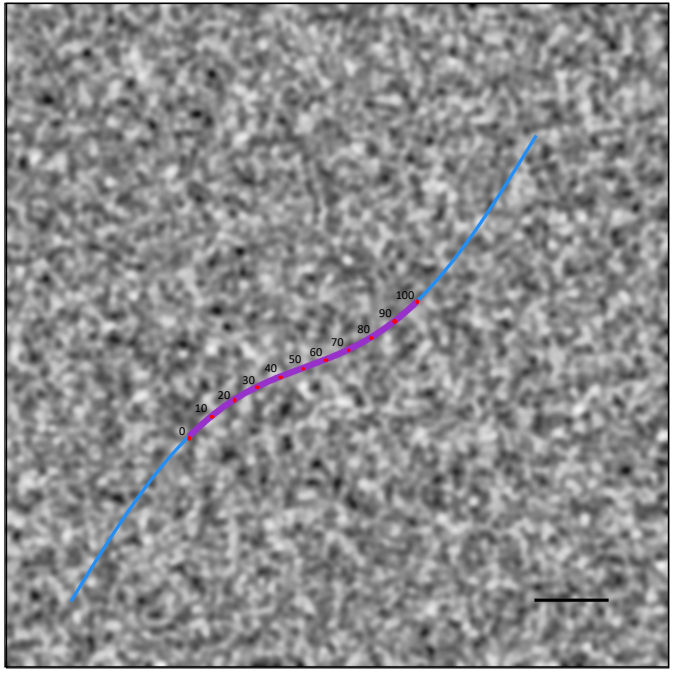


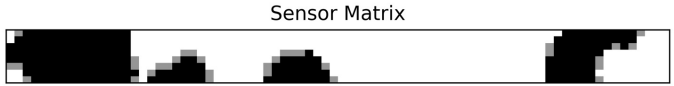


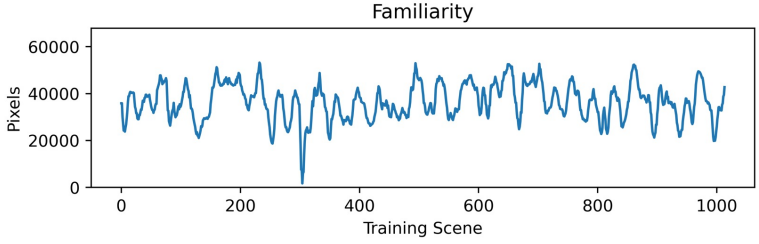
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

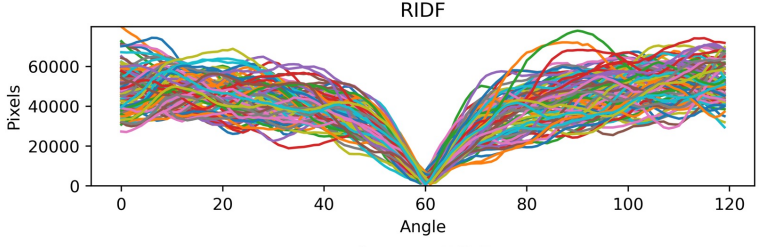
Navigation stats: RMSD error: 49.39; RMSD/dist: 0.123; TD: 33316; p90: 24; p50: 12; complete: 0

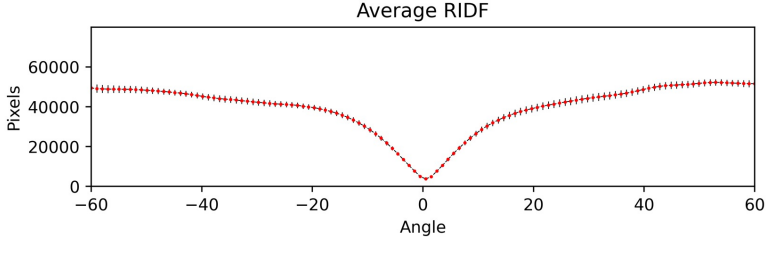
100%







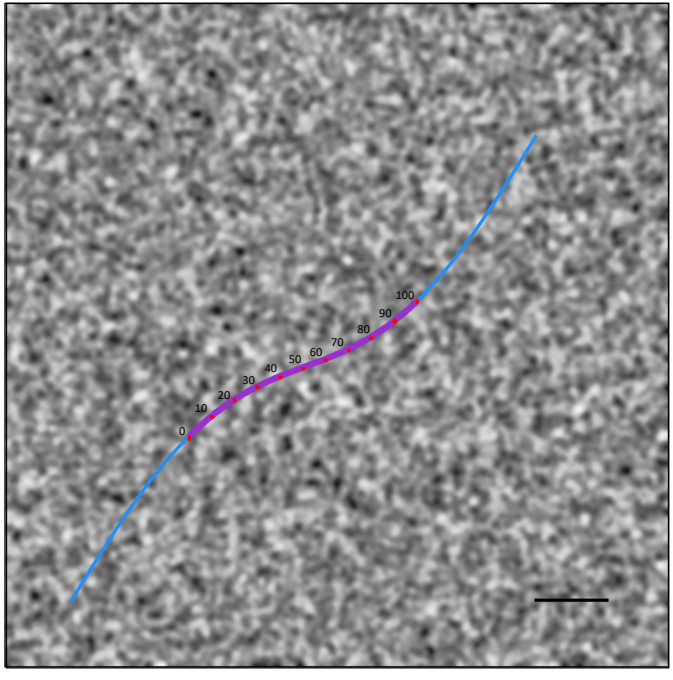


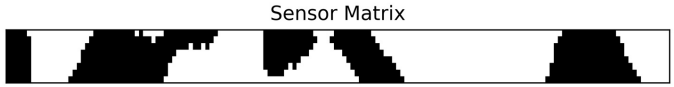


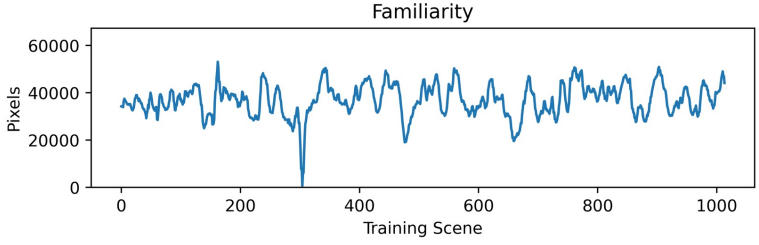
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

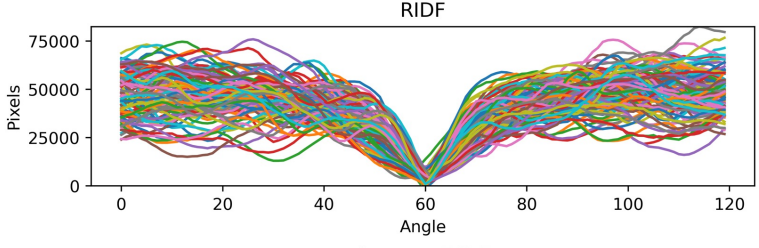
Navigation stats: RMSD error: 52.35; RMSD/dist: 0.131; TD: 33877; p90: 28; p50: 14; complete: 0

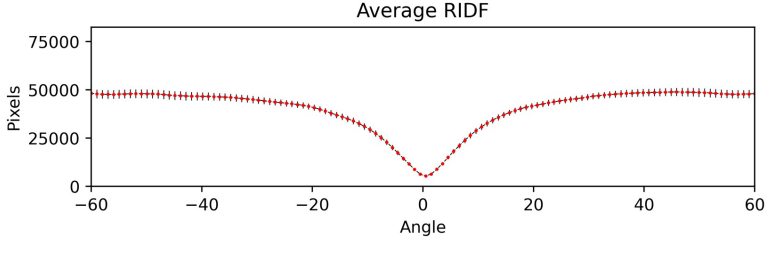
100%





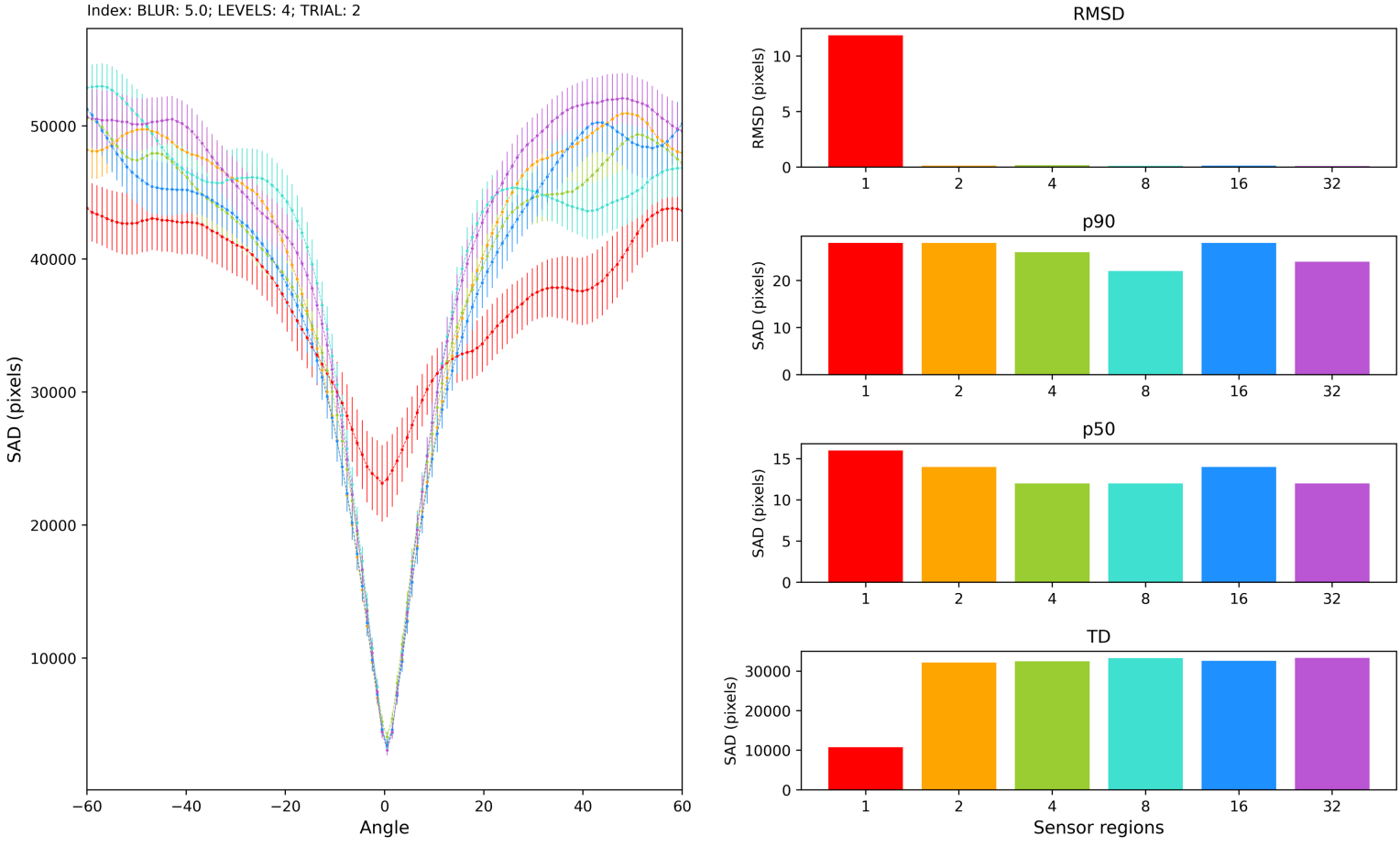




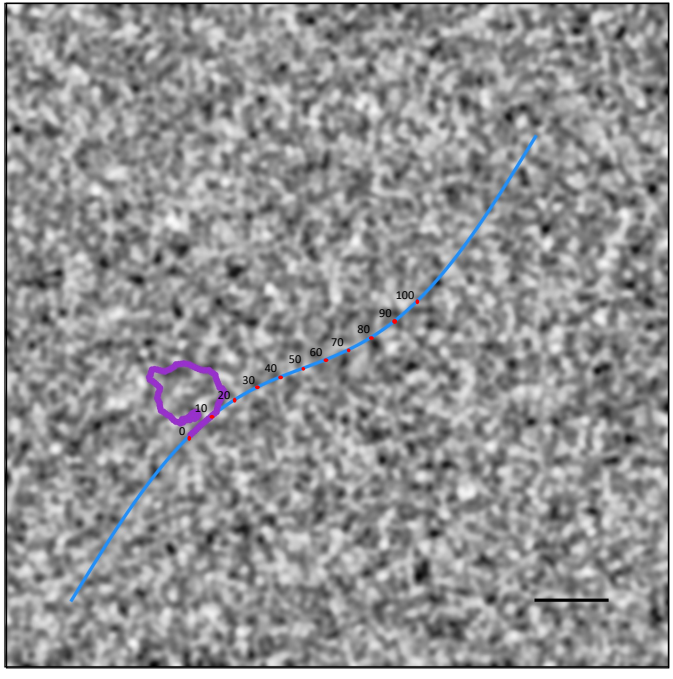


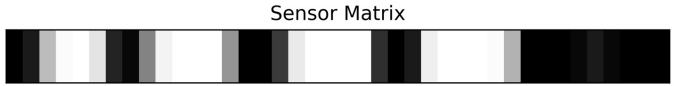
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

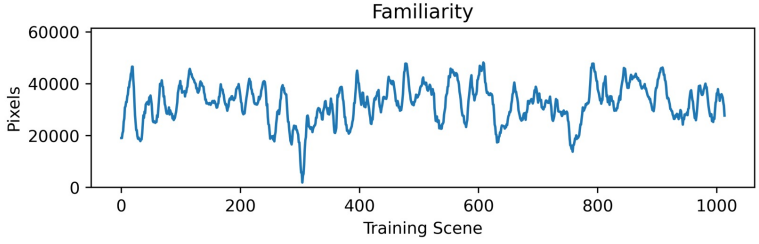
Navigation stats: RMSD error: 88.82; RMSD/dist: 0.222; TD: 31993; p90: 26; p50: 12; complete: 0

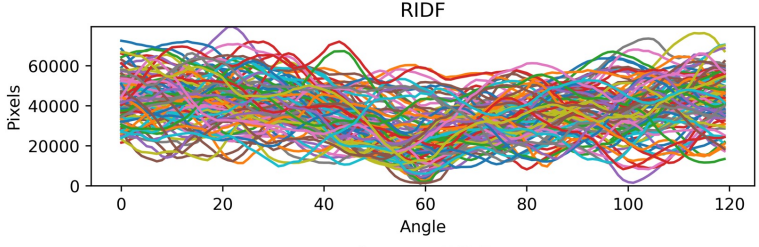

Index: BLUR: 5.0; LEVELS: 4; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

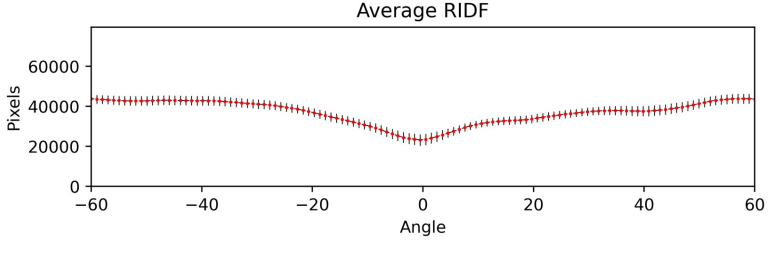
10%







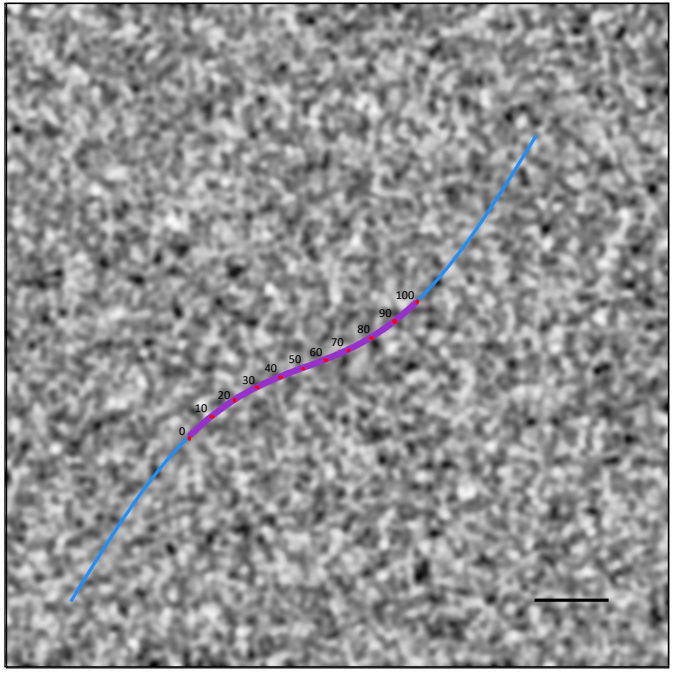


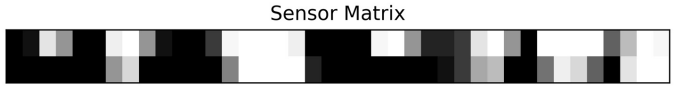


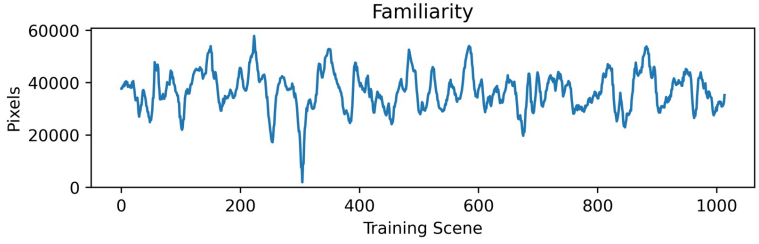
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

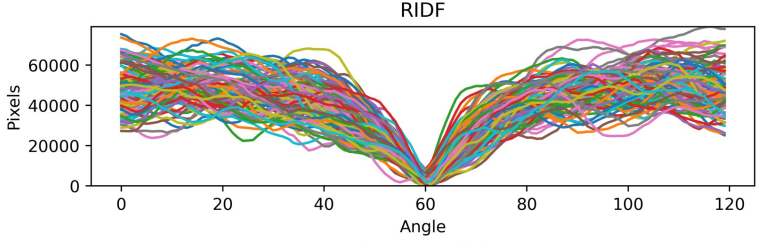
Navigation stats: RMSD error: 4752.72; RMSD/dist: 11.882; TD: 10747; p90: 28; p50: 16; complete: 0

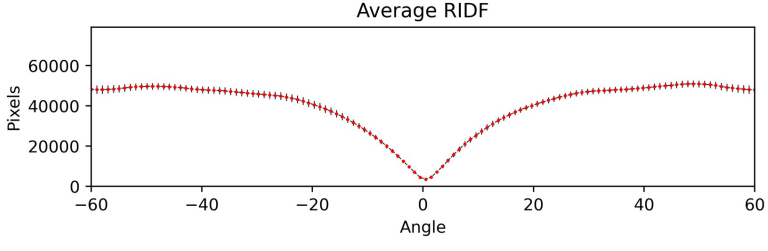
100%







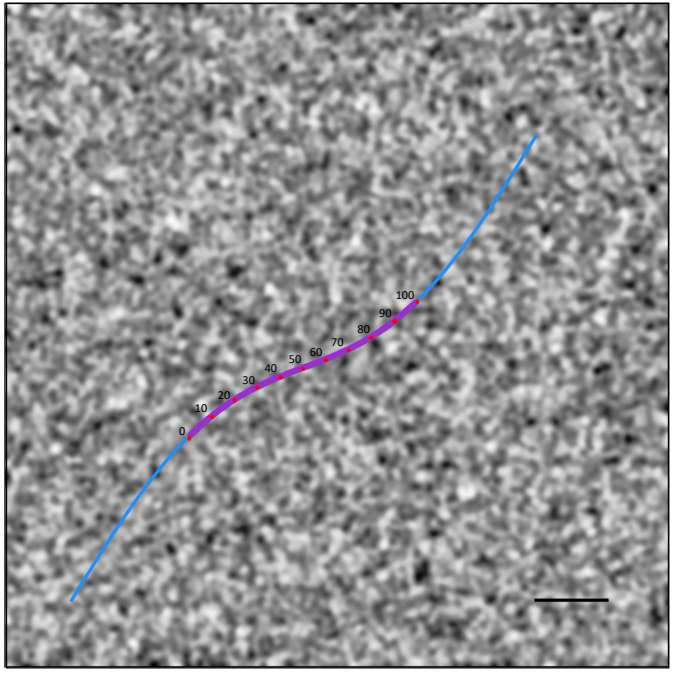


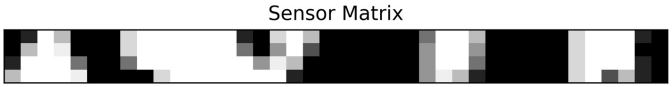


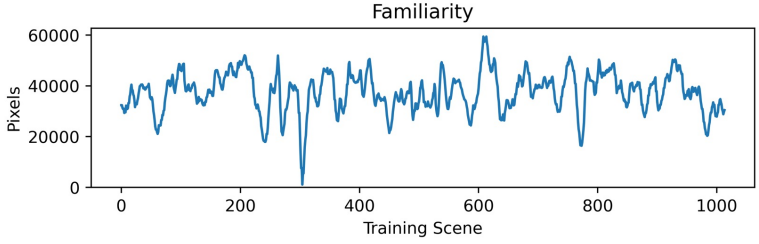
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

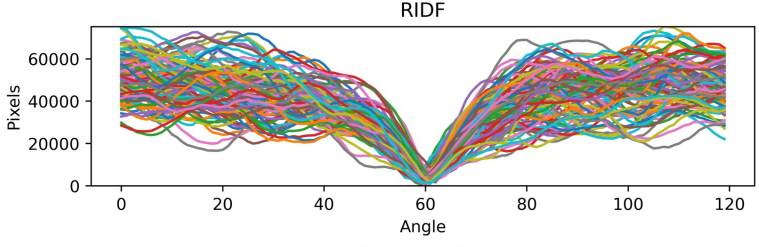
Navigation stats: RMSD error: 51.25; RMSD/dist: 0.128; TD: 32168; p90: 28; p50: 14; complete: 0

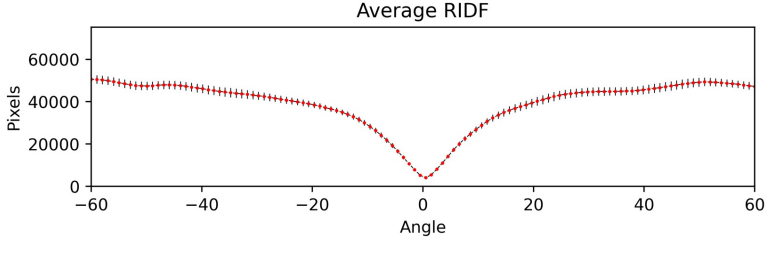
100%







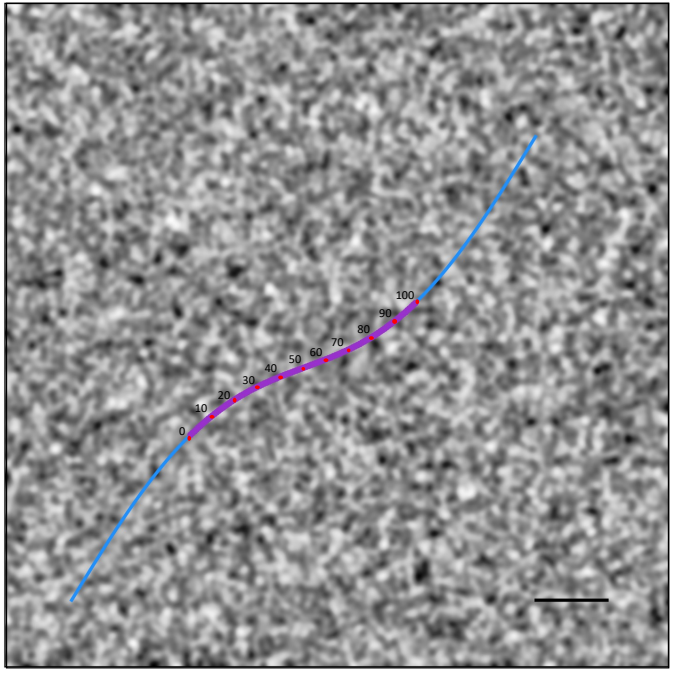


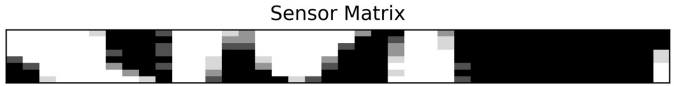


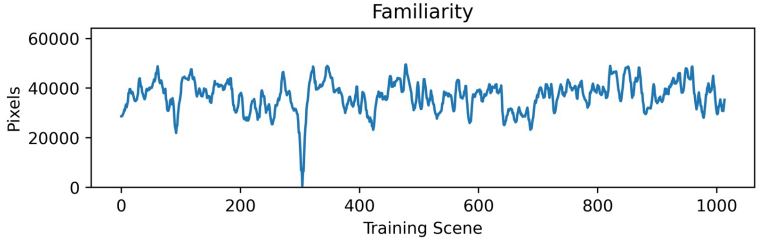
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

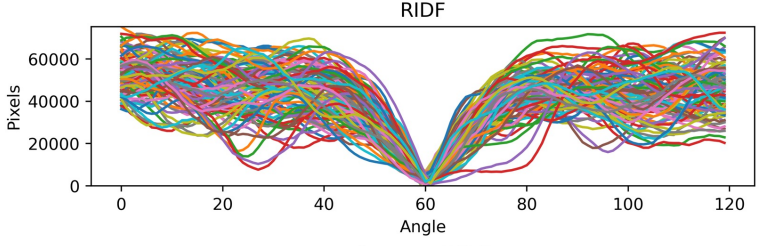
Navigation stats: RMSD error: 63.61; RMSD/dist: 0.159; TD: 32466; p90: 26; p50: 12; complete: 0

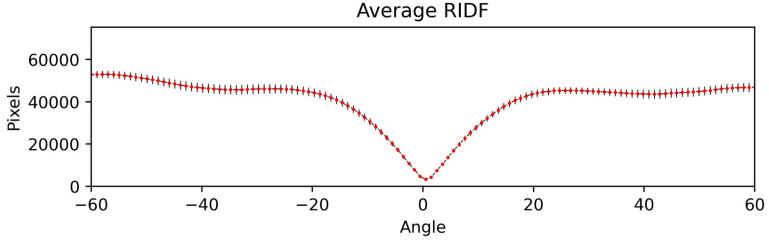
100%







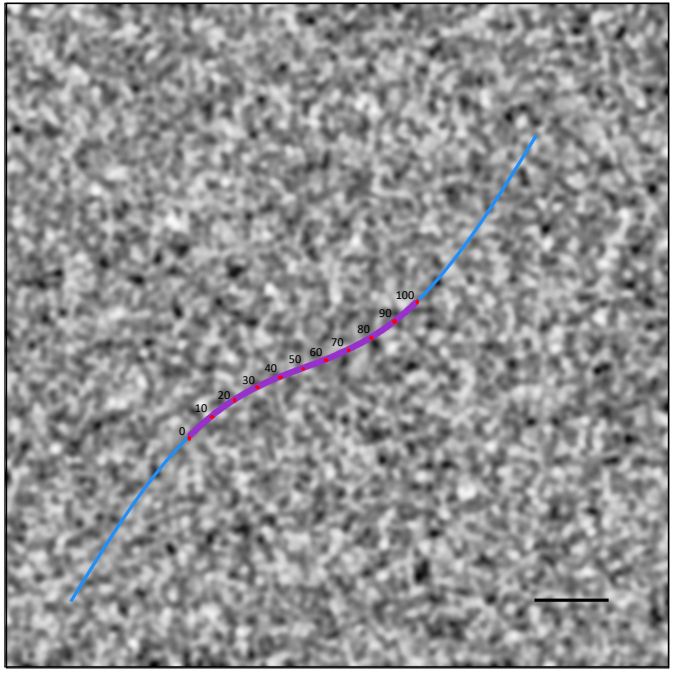


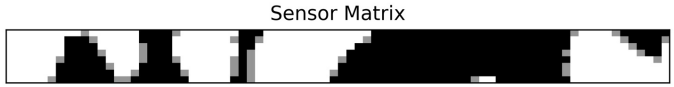


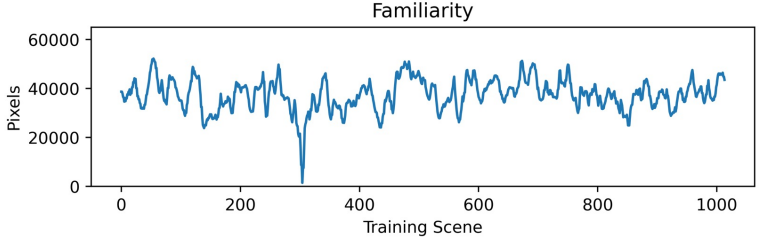
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

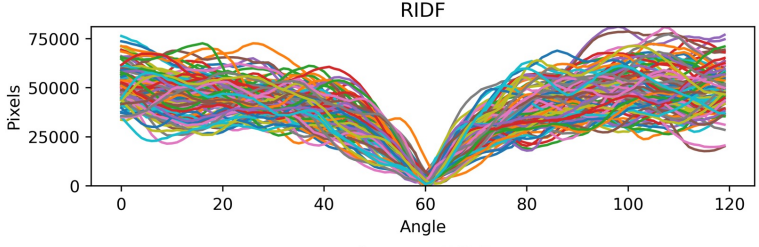
Navigation stats: RMSD error: 41.68; RMSD/dist: 0.104; TD: 33267; p90: 22; p50: 12; complete: 0

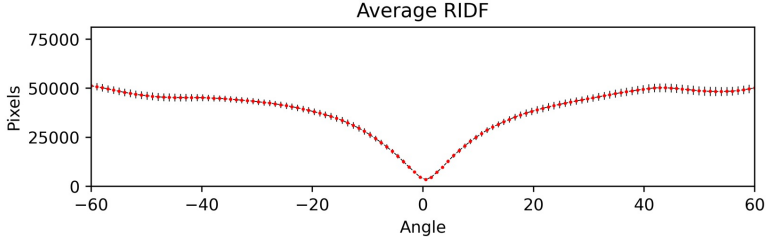
100%







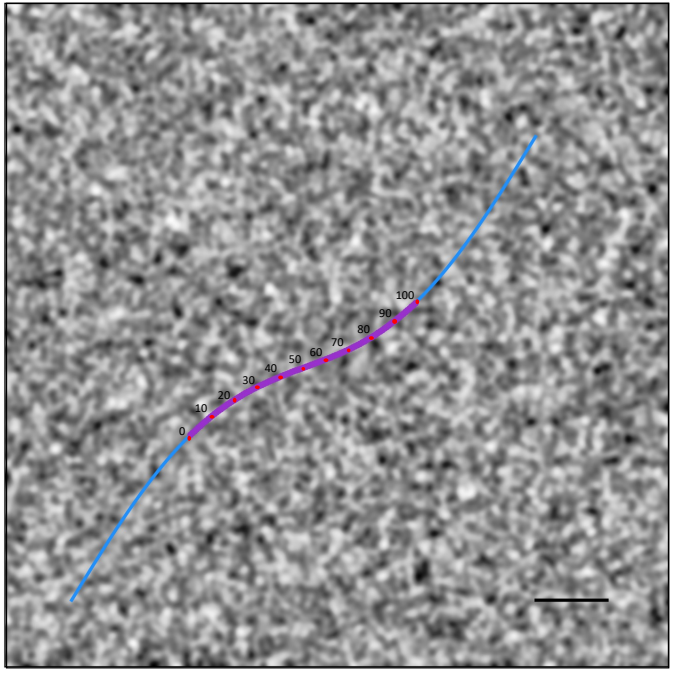


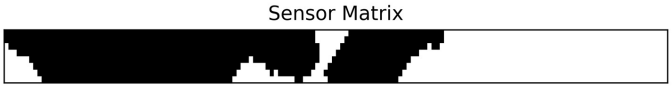


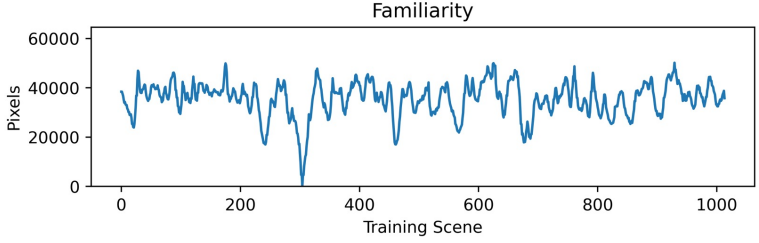
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

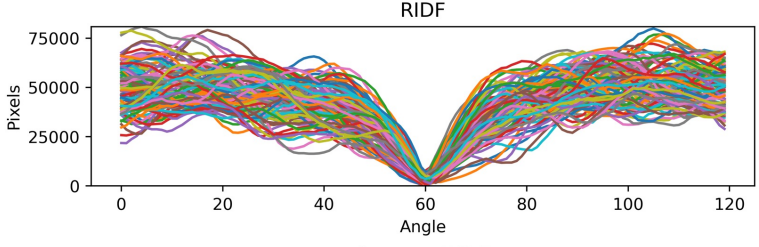
Navigation stats: RMSD error: 51.76; RMSD/dist: 0.129; TD: 32606; p90: 28; p50: 14; complete: 0

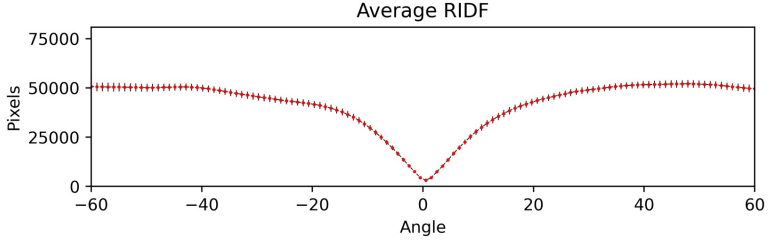
100%





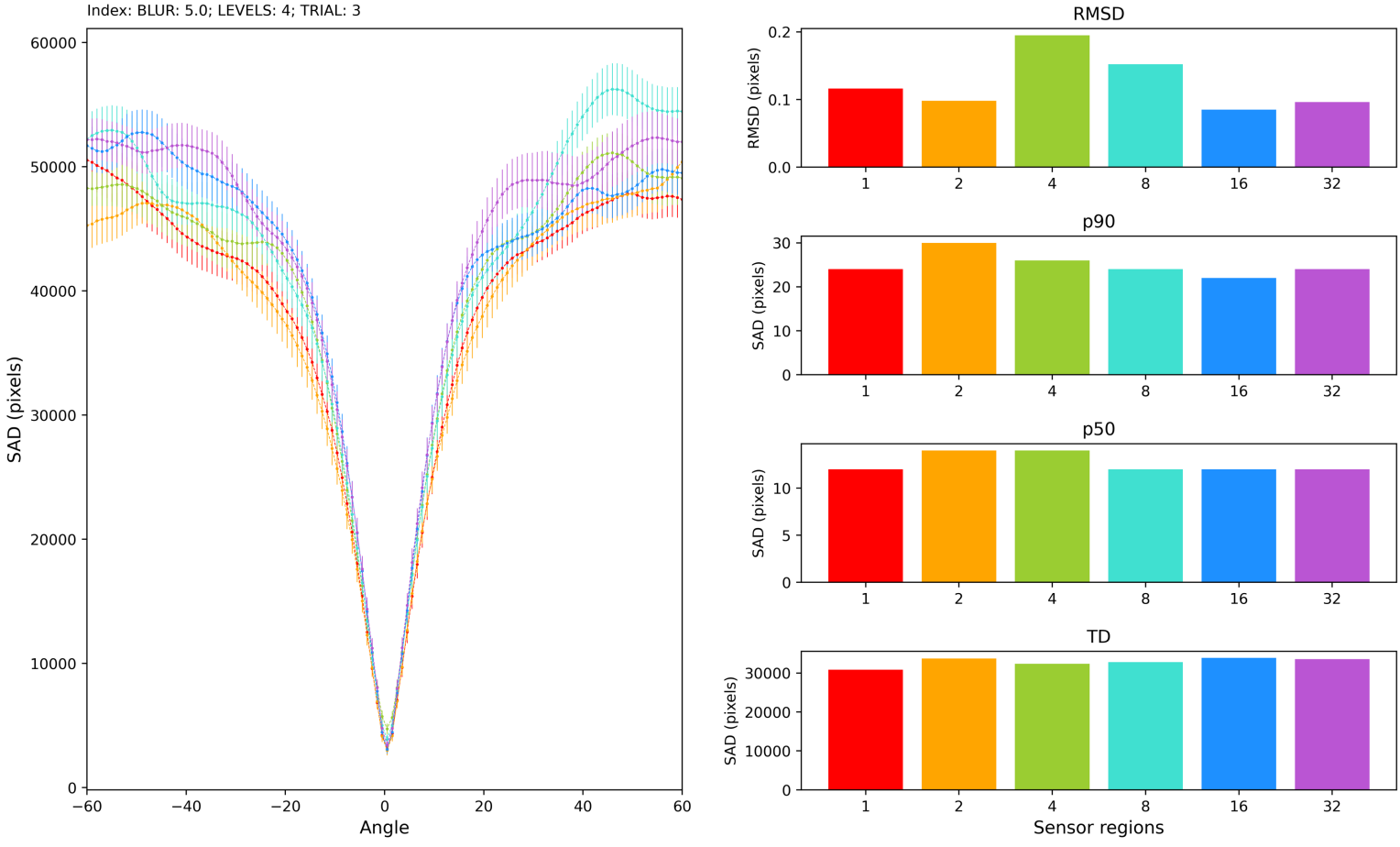




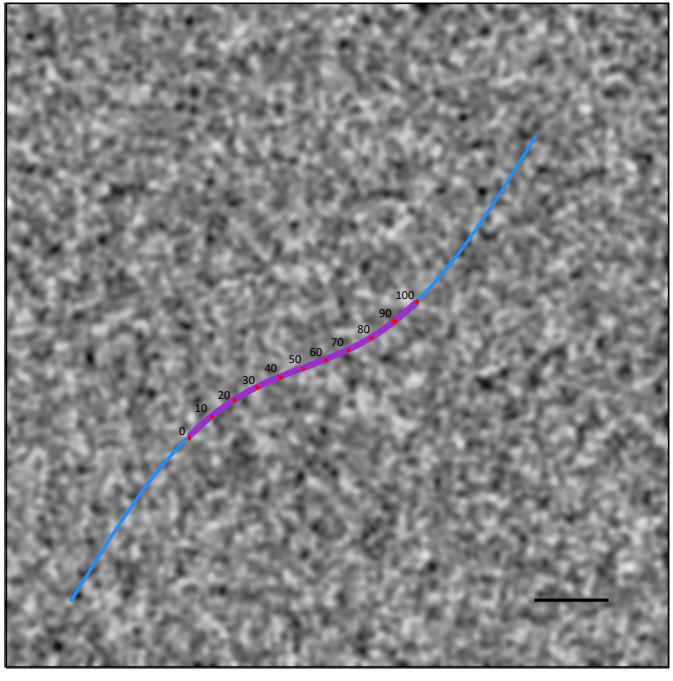


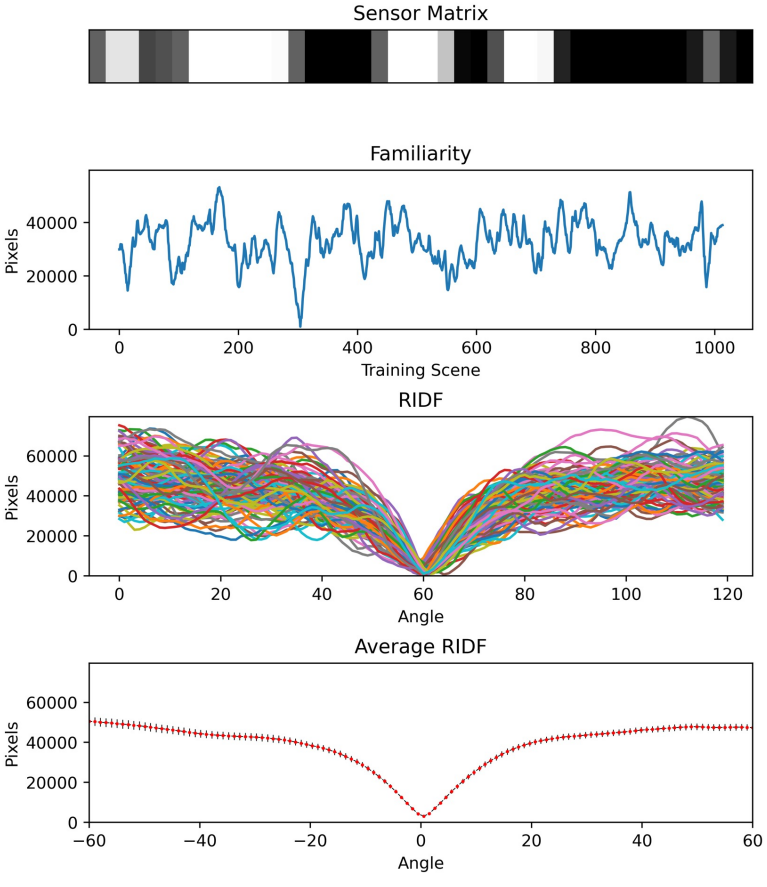
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 34.97; RMSD/dist: 0.087; TD: 33313; p90: 24; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 4; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

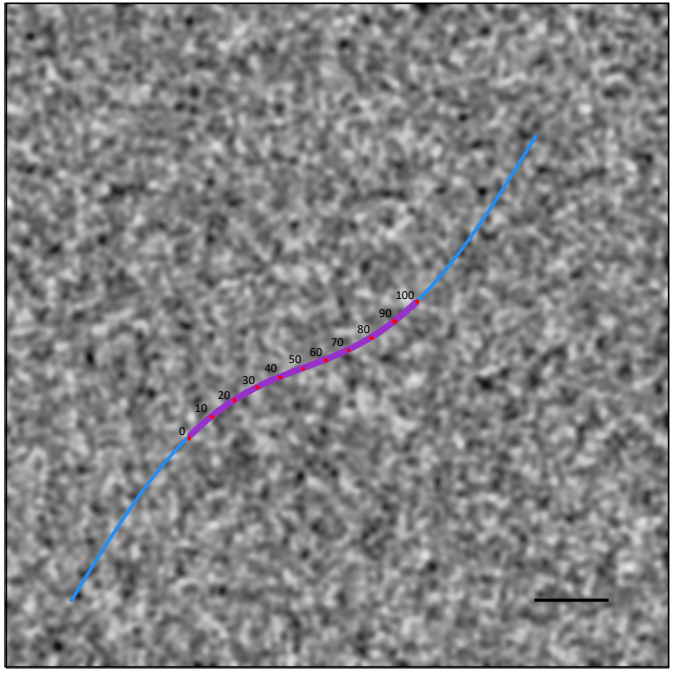


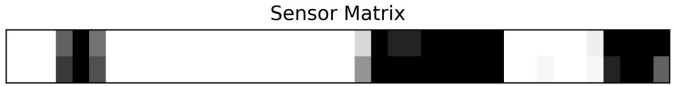


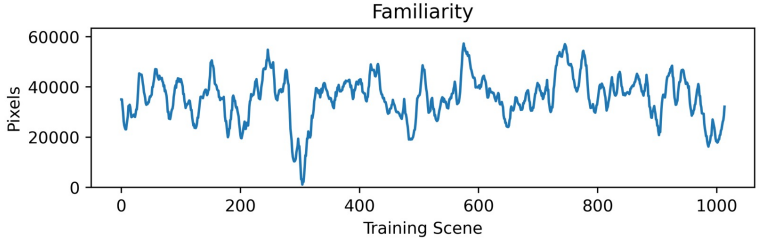
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

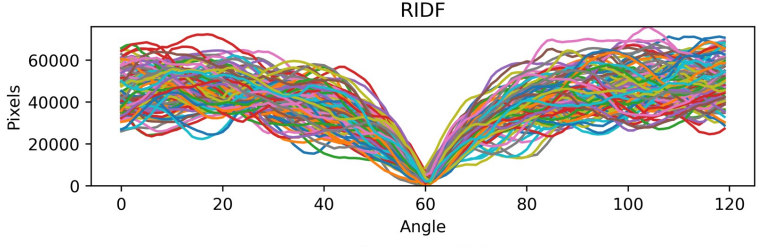
Navigation stats: RMSD error: 46.30; RMSD/dist: 0.116; TD: 30855; p90: 24; p50: 12; complete: 0

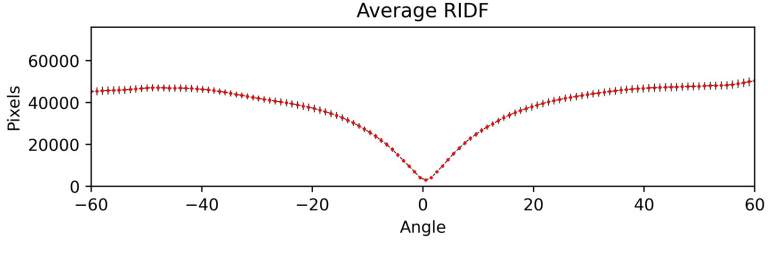
100%







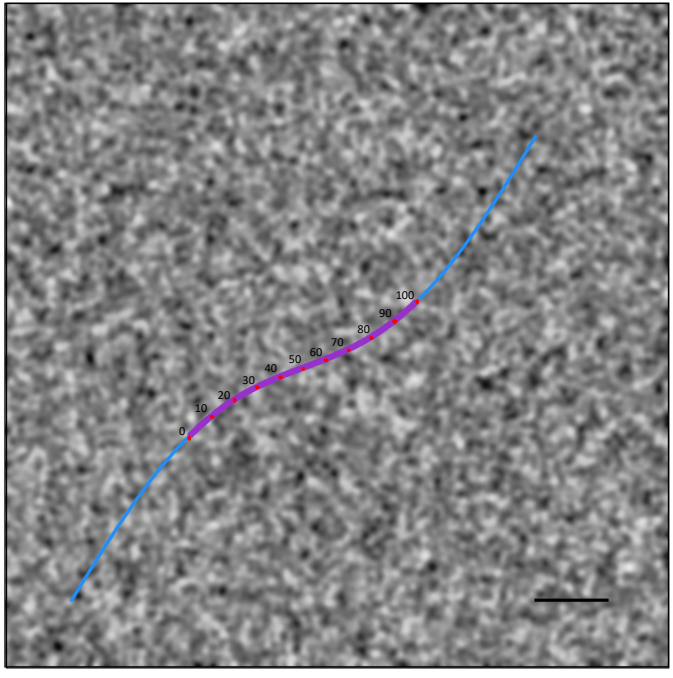


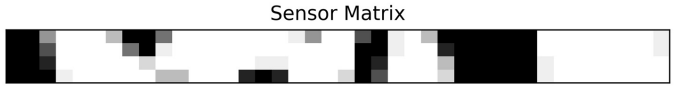


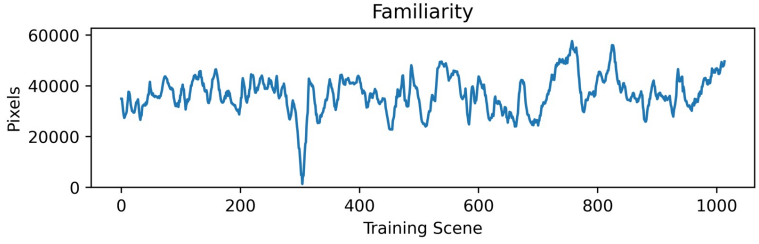
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

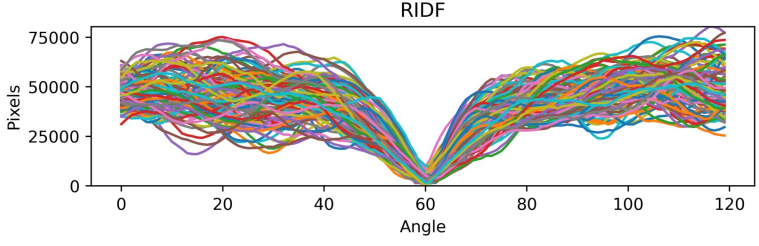
Navigation stats: RMSD error: 39.17; RMSD/dist: 0.098; TD: 33697; p90: 30; p50: 14; complete: 0

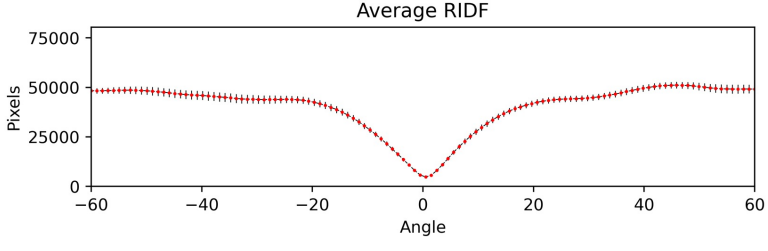
100%







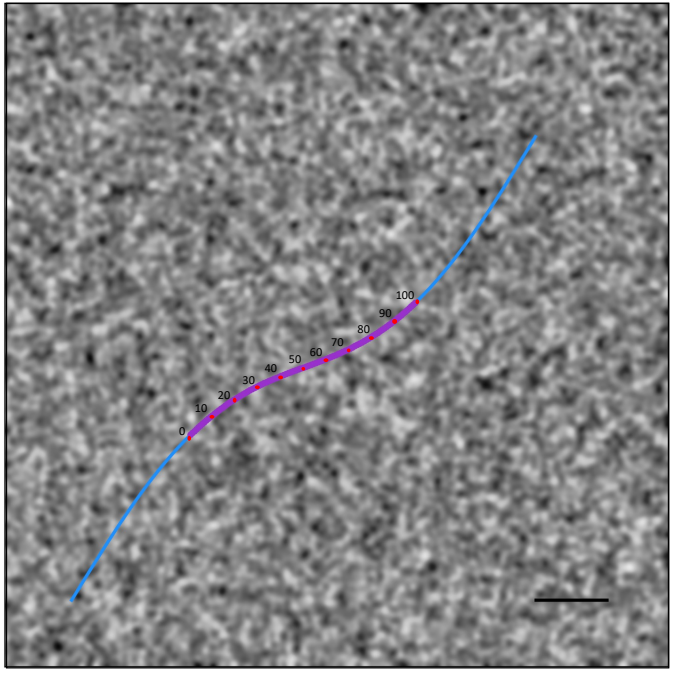


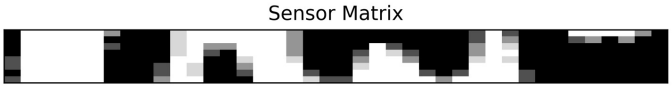


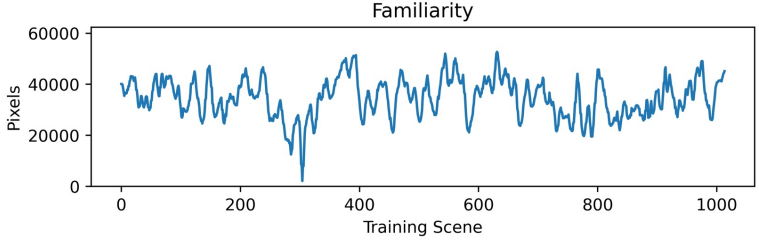
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

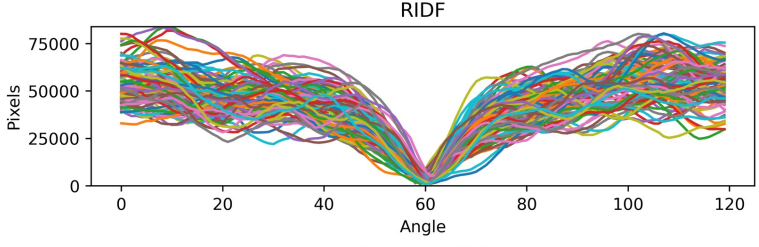
Navigation stats: RMSD error: 78.18; RMSD/dist: 0.195; TD: 32373; p90: 26; p50: 14; complete: 0

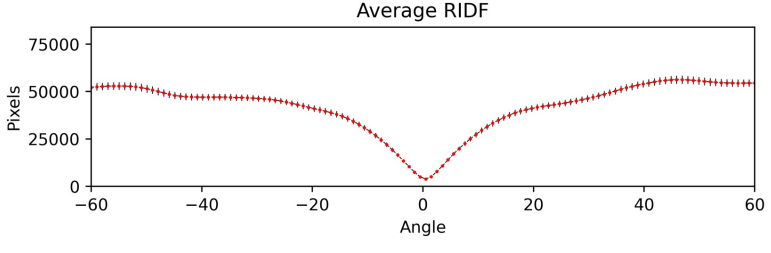
100%







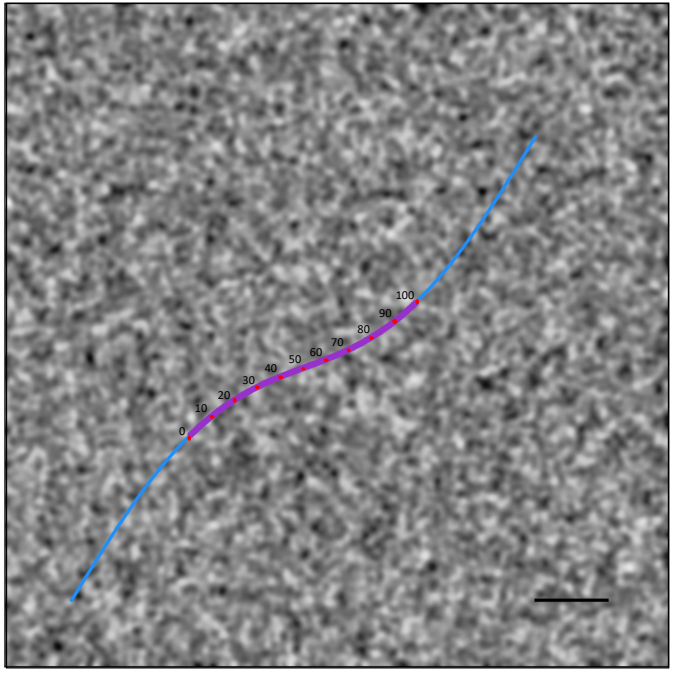


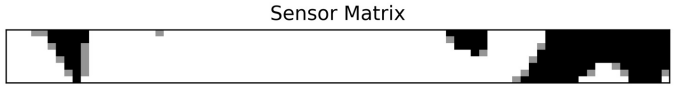


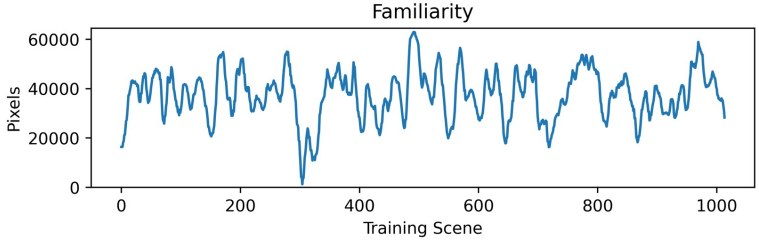
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

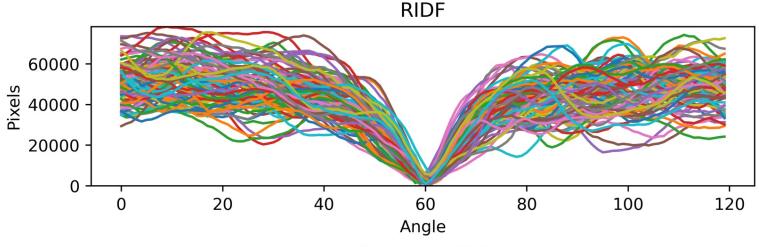
Navigation stats: RMSD error: 60.77; RMSD/dist: 0.152; TD: 32797; p90: 24; p50: 12; complete: 0

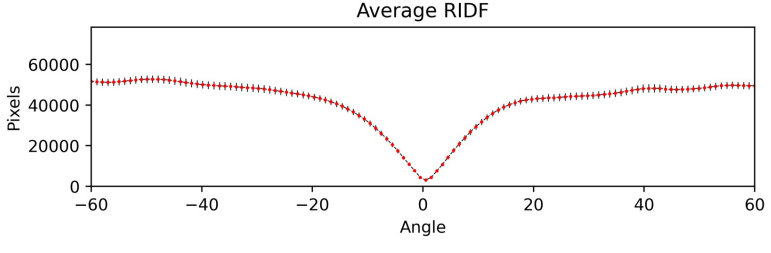
100%







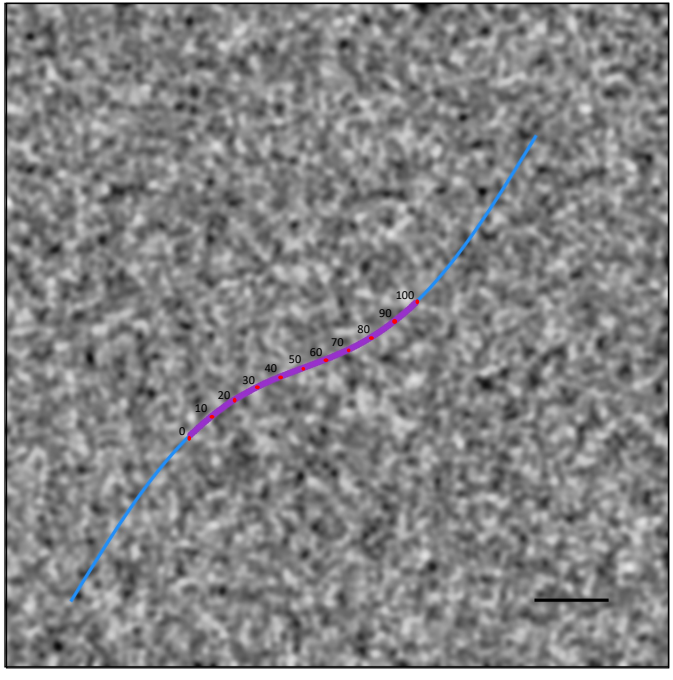


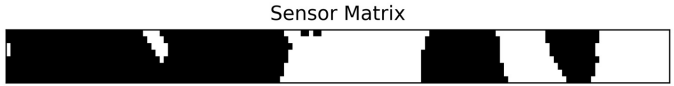


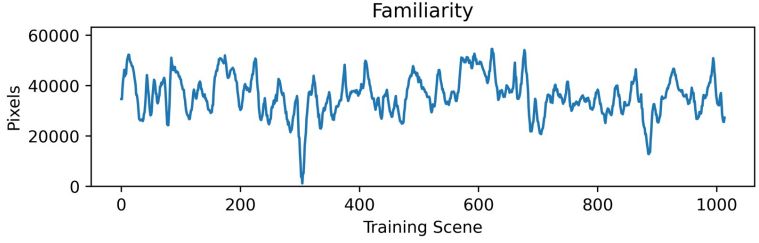
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

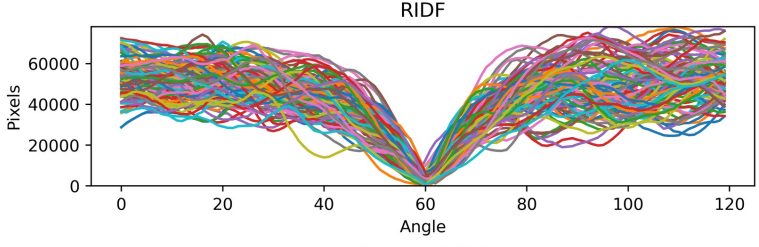
Navigation stats: RMSD error: 33.99; RMSD/dist: 0.085; TD: 33856; p90: 22; p50: 12; complete: 0

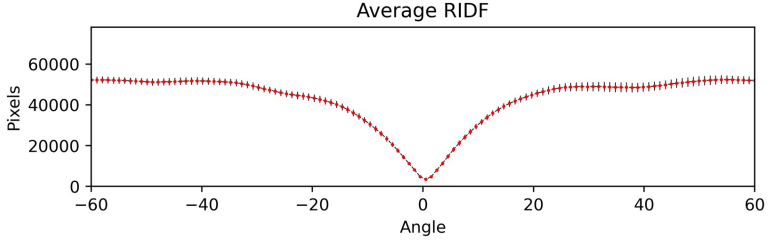
100%





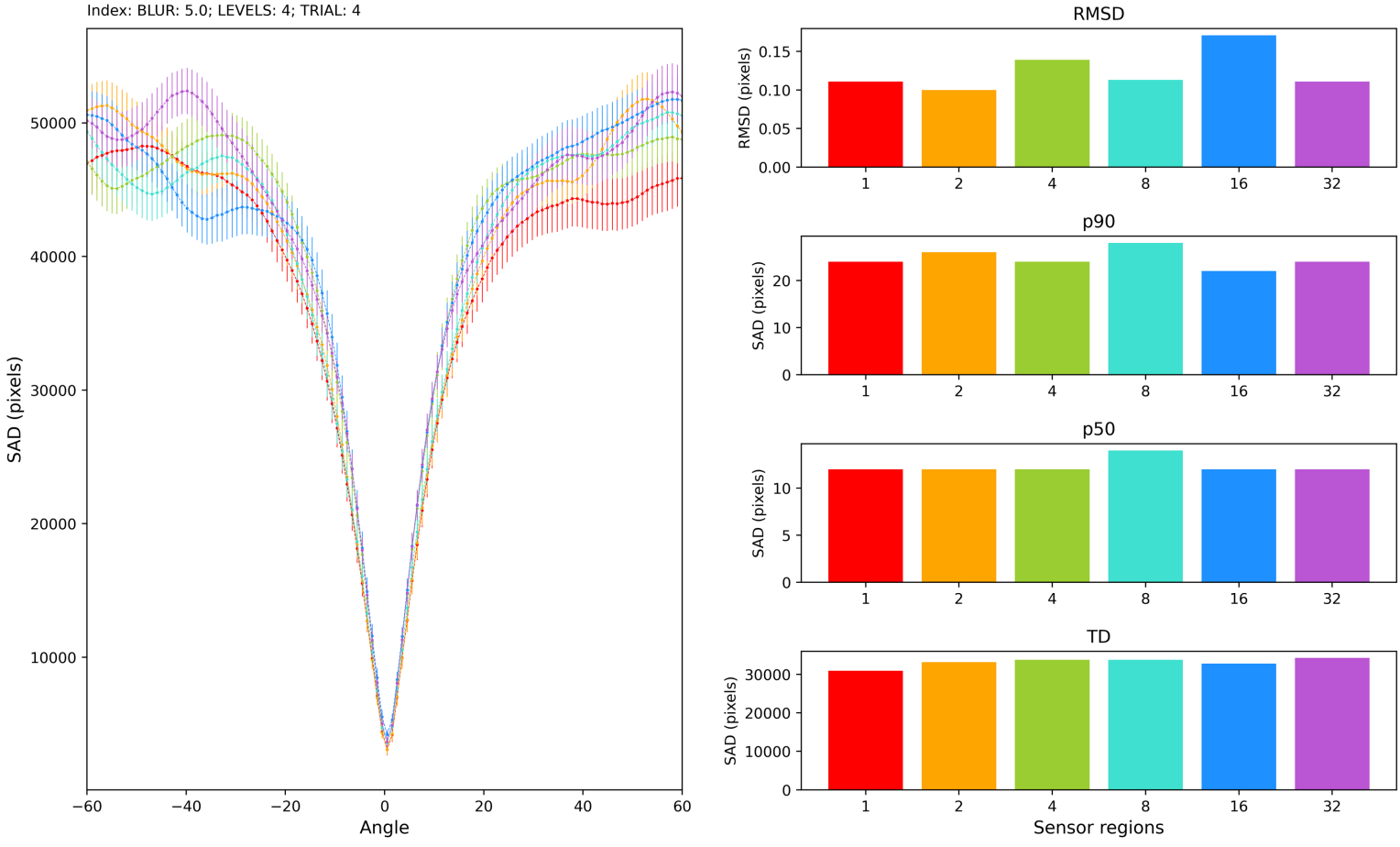




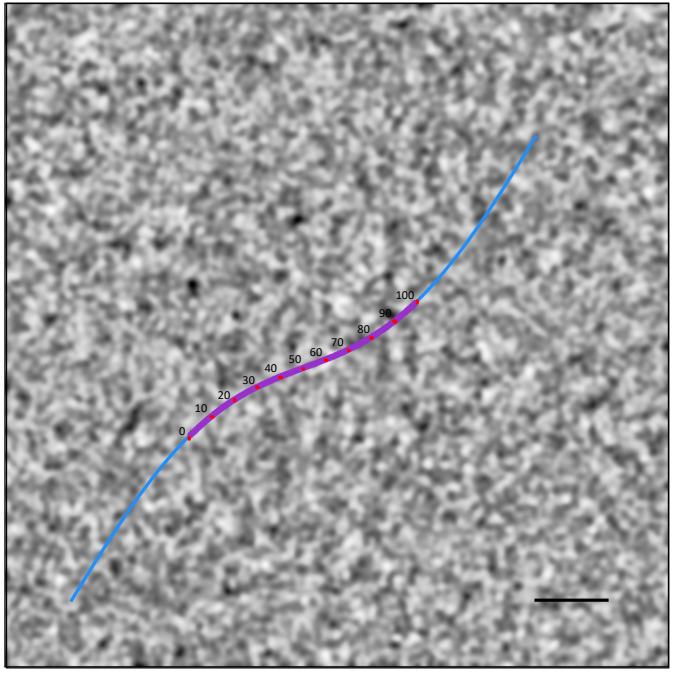


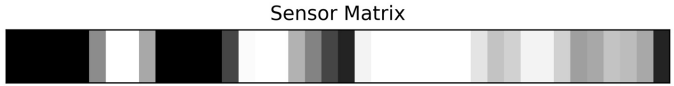
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

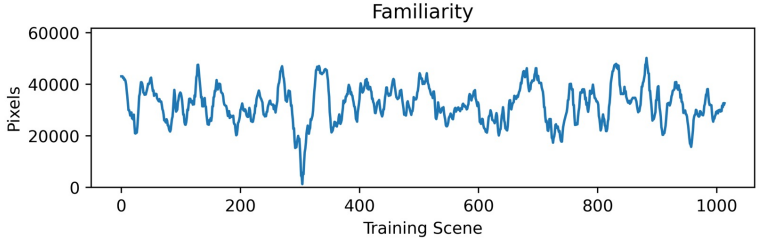
Navigation stats: RMSD error: 38.33; RMSD/dist: 0.096; TD: 33533; p90: 24; p50: 12; complete: 0

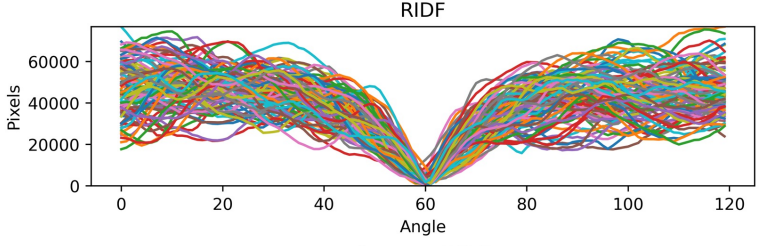

Index: BLUR: 5.0; LEVELS: 4; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

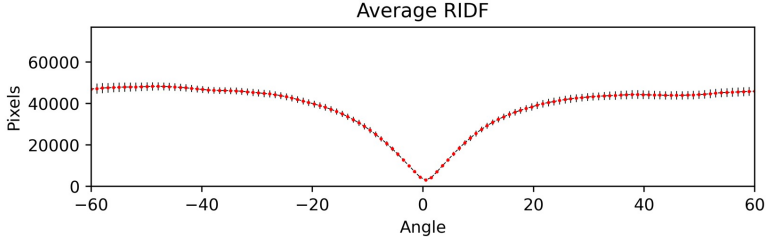
100%







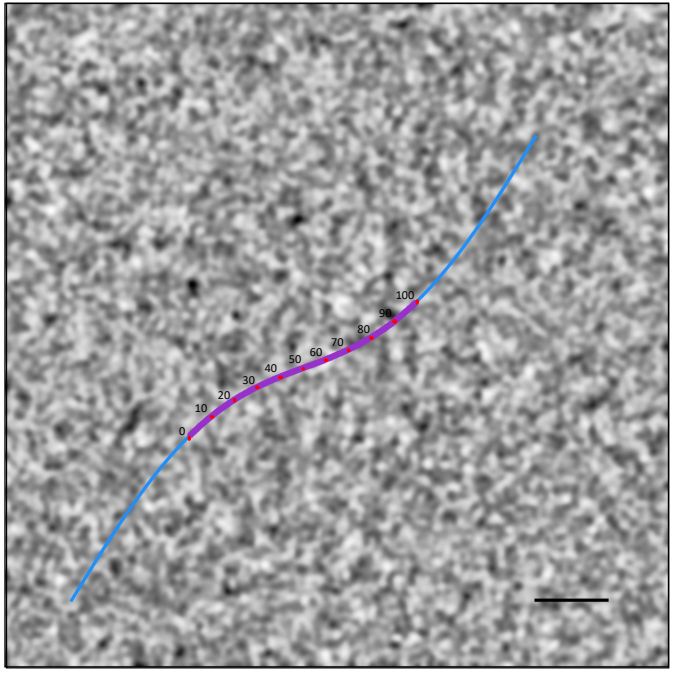


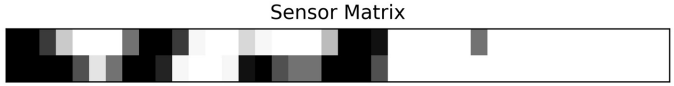


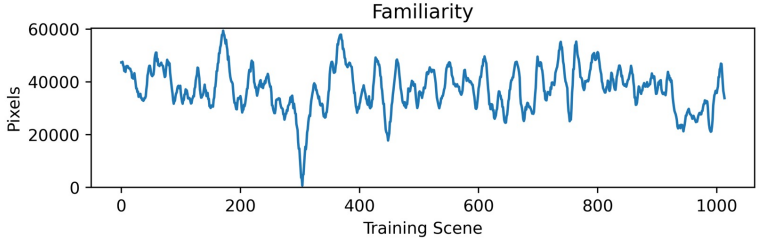
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

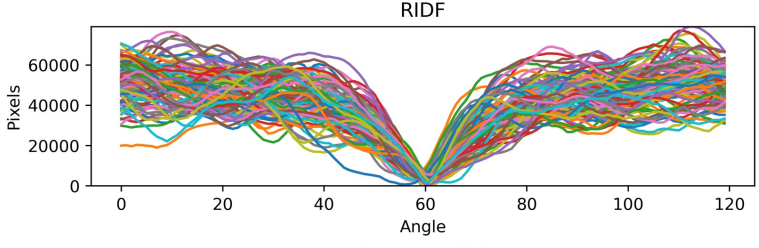
Navigation stats: RMSD error: 44.48; RMSD/dist: 0.111; TD: 30924; p90: 24; p50: 12; complete: 0

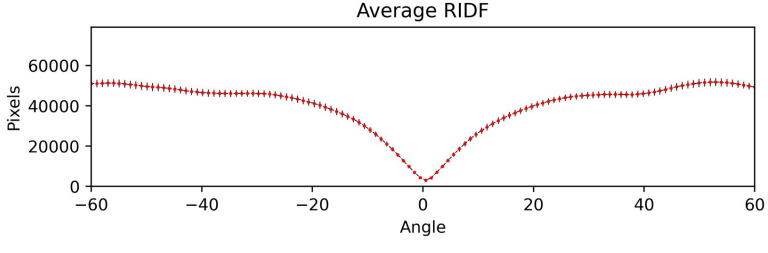
100%







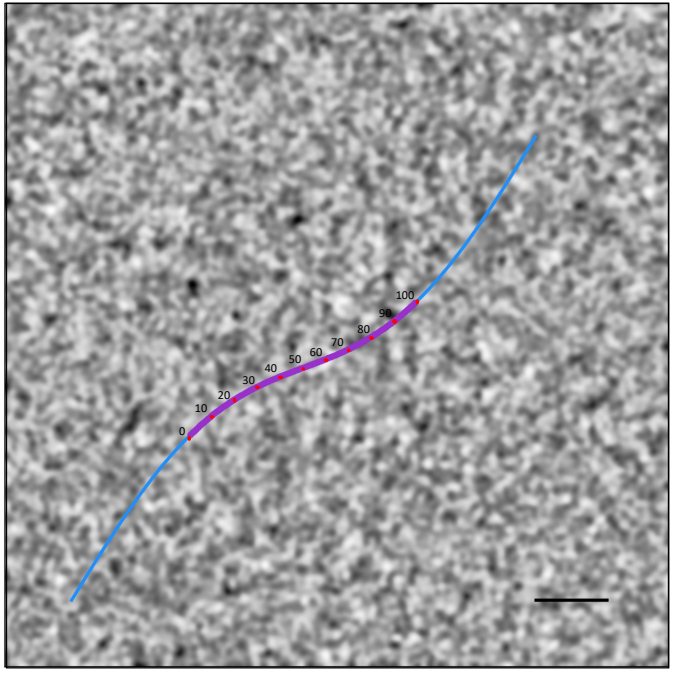


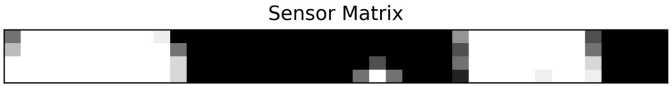


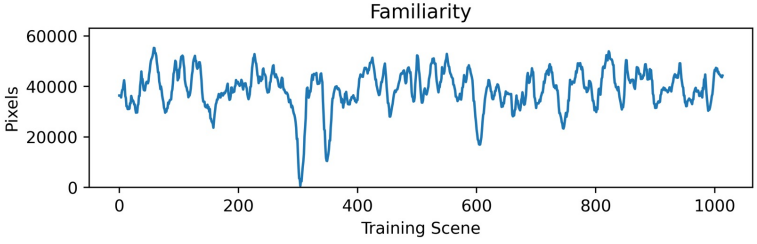
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

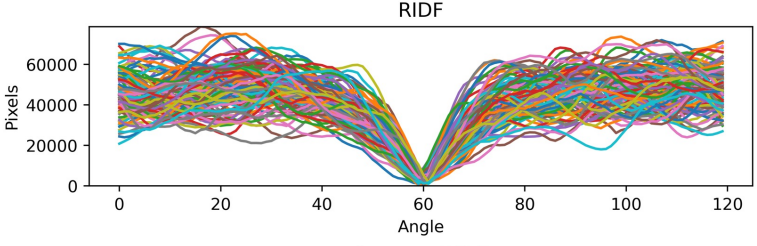
Navigation stats: RMSD error: 39.90; RMSD/dist: 0.100; TD: 33212; p90: 26; p50: 12; complete: 0

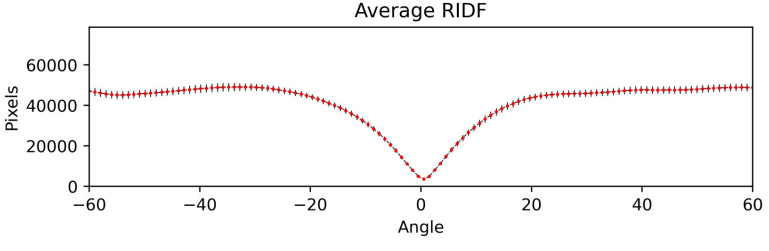
100%







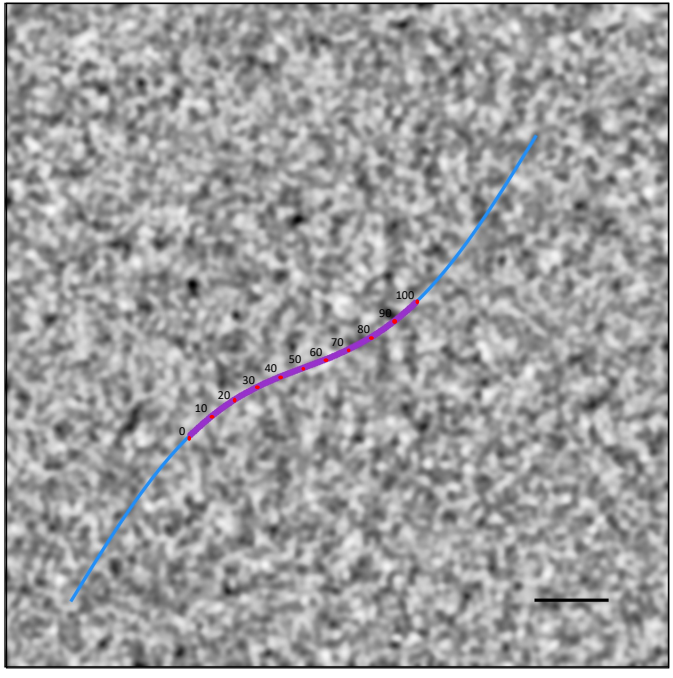


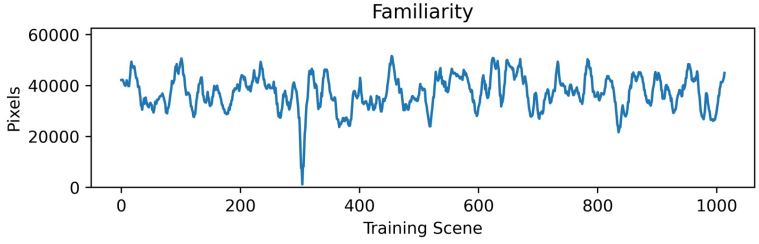


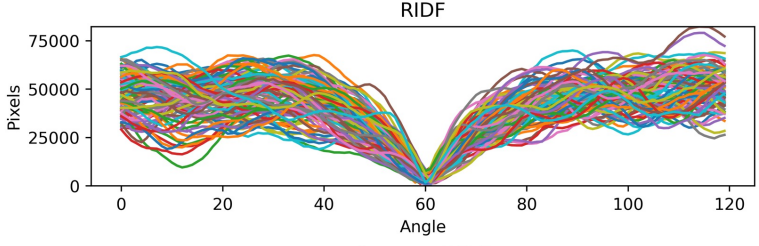
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

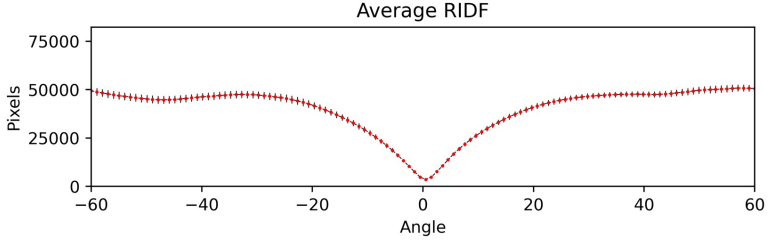
Navigation stats: RMSD error: 55.68; RMSD/dist: 0.139; TD: 33816; p90: 24; p50: 12; complete: 0

100%





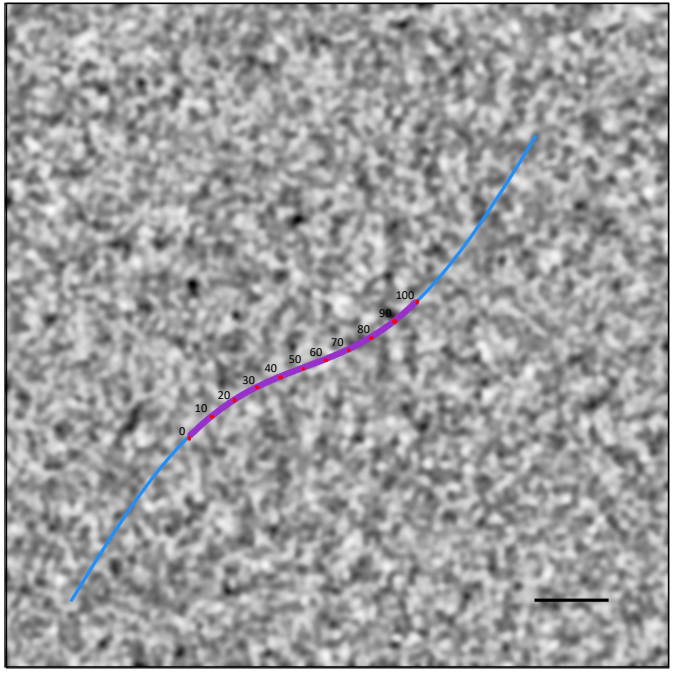


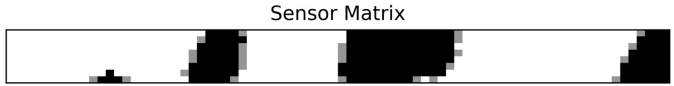


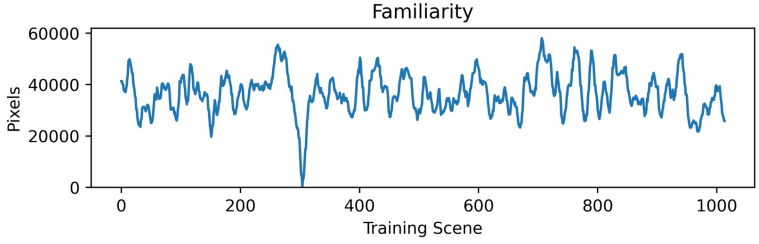
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

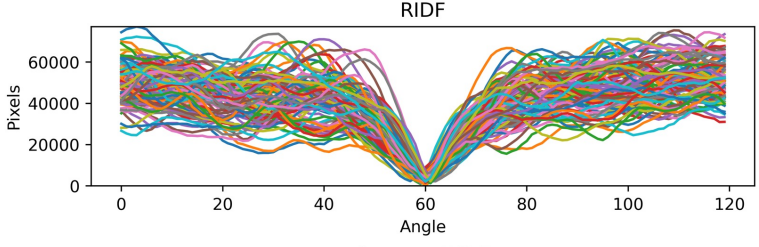
Navigation stats: RMSD error: 45.21; RMSD/dist: 0.113; TD: 33816; p90: 28; p50: 14; complete: 0

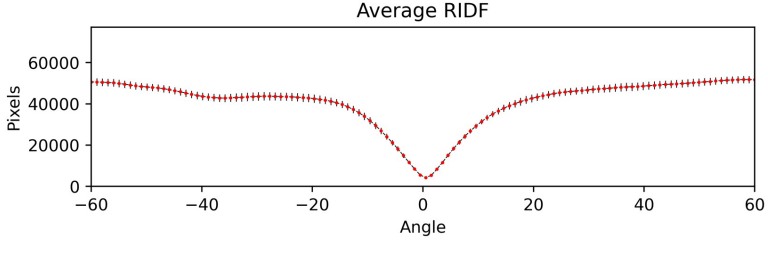
100%







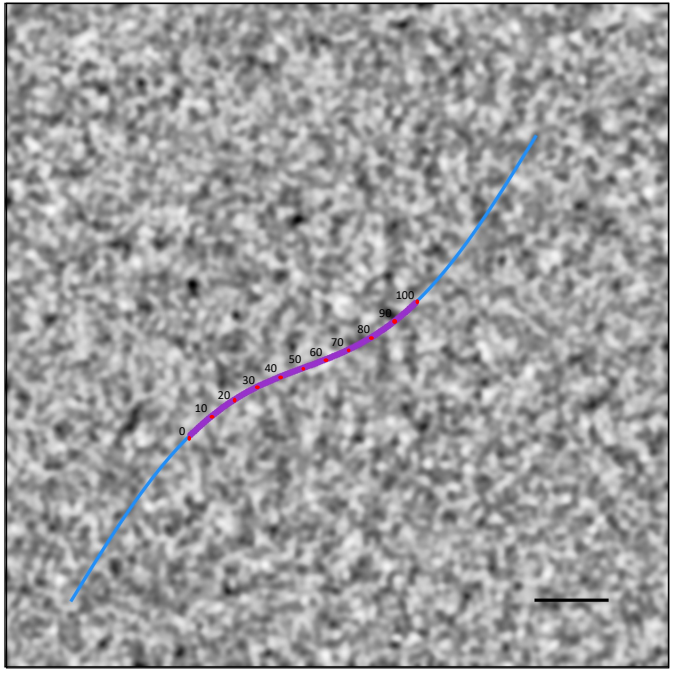


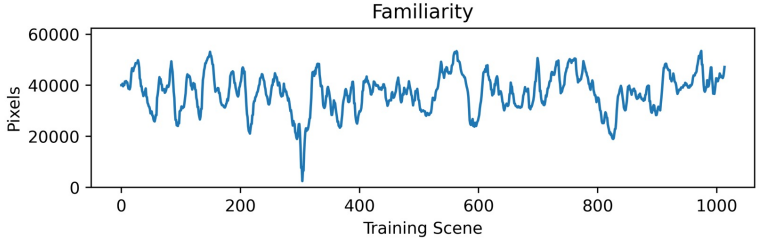


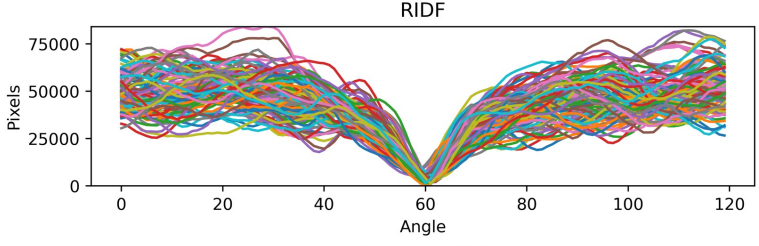
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

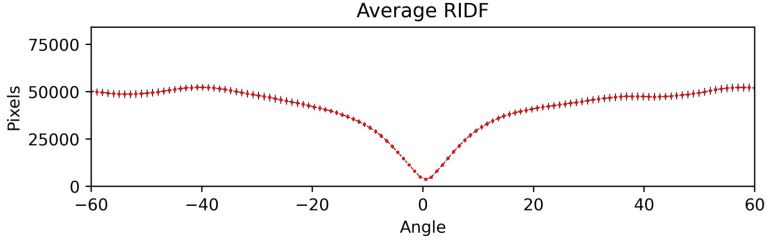
Navigation stats: RMSD error: 68.60; RMSD/dist: 0.171; TD: 32789; p90: 22; p50: 12; complete: 0

100%



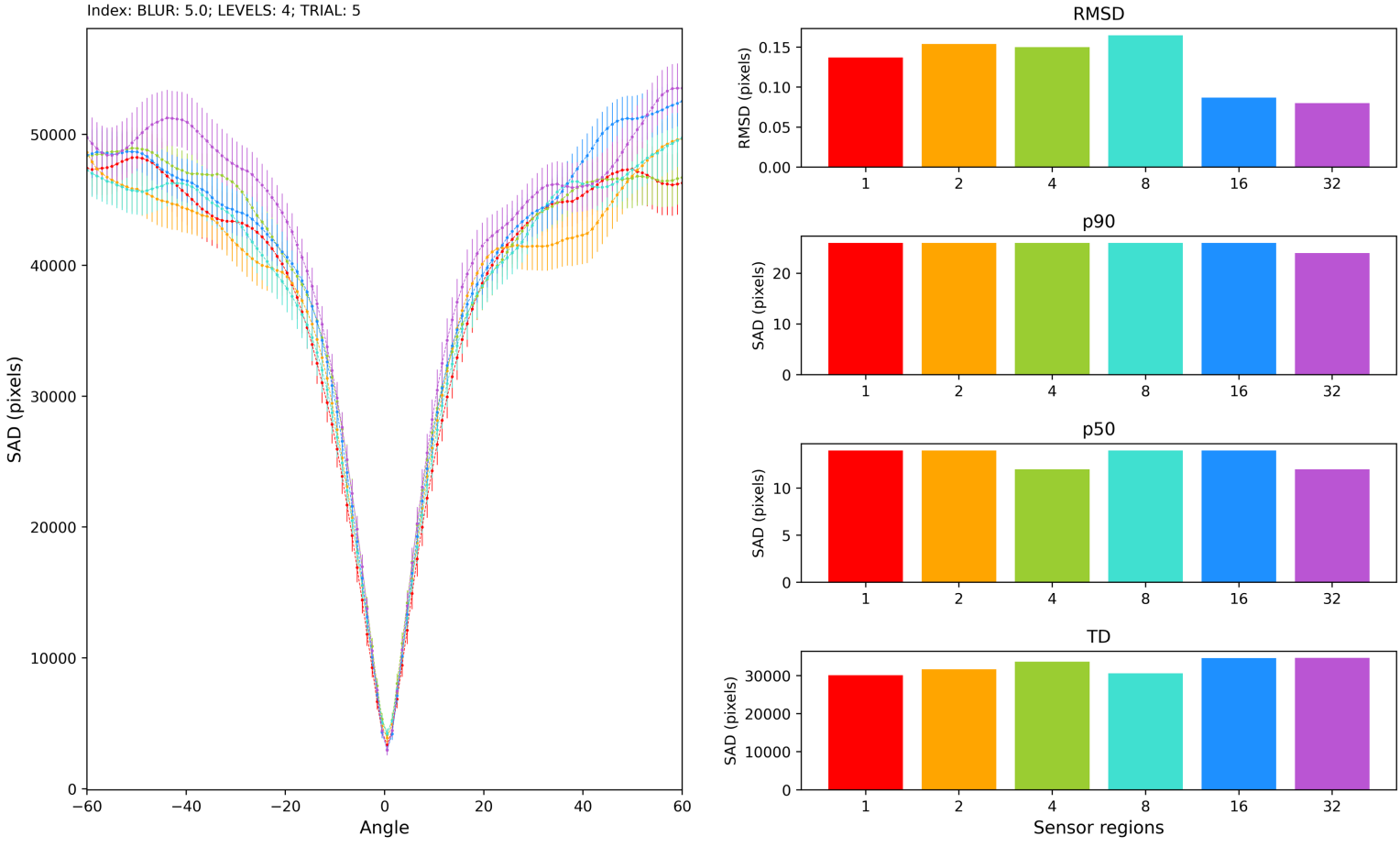




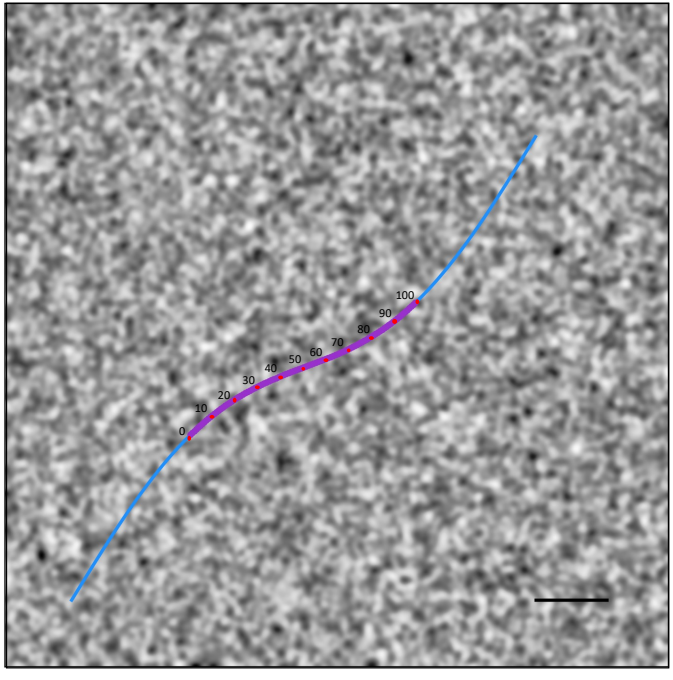


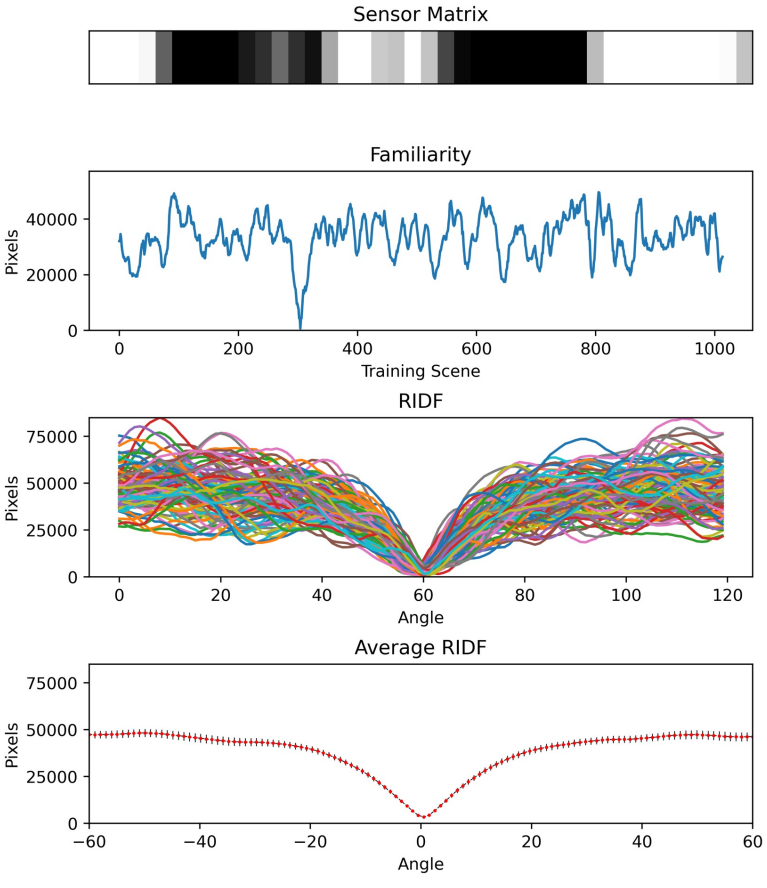
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 44.33; RMSD/dist: 0.111; TD: 34260; p90: 24; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 4; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

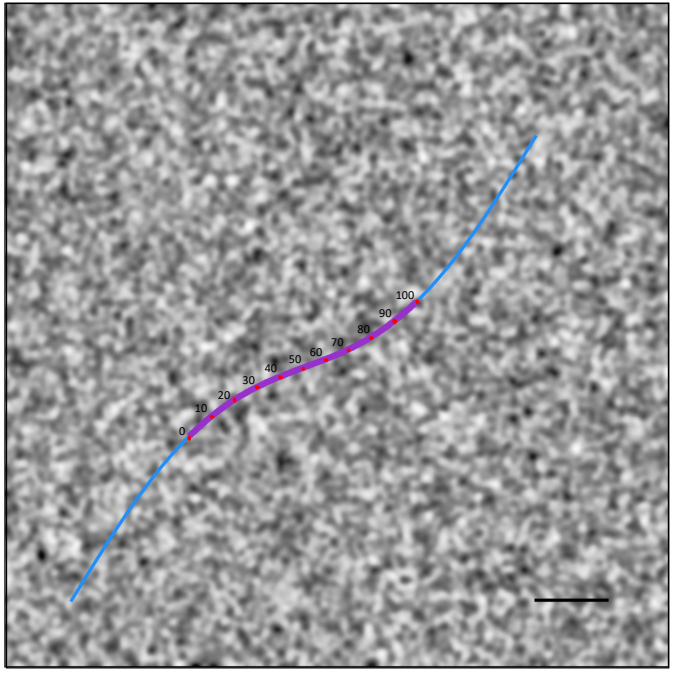


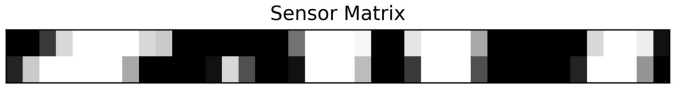


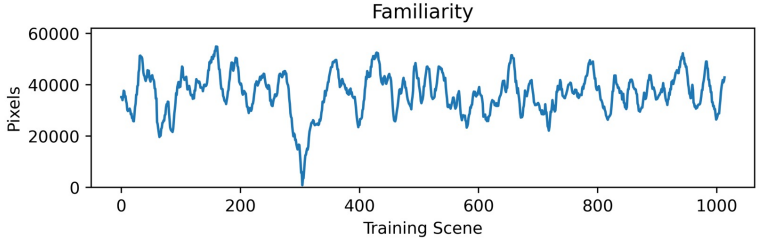
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

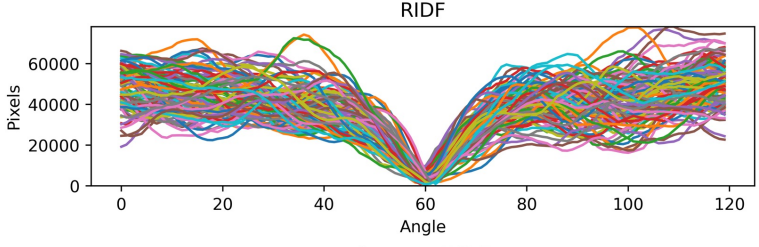
Navigation stats: RMSD error: 54.89; RMSD/dist: 0.137; TD: 30113; p90: 26; p50: 14; complete: 0

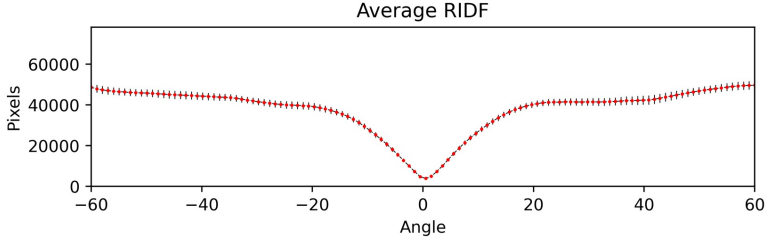
100%







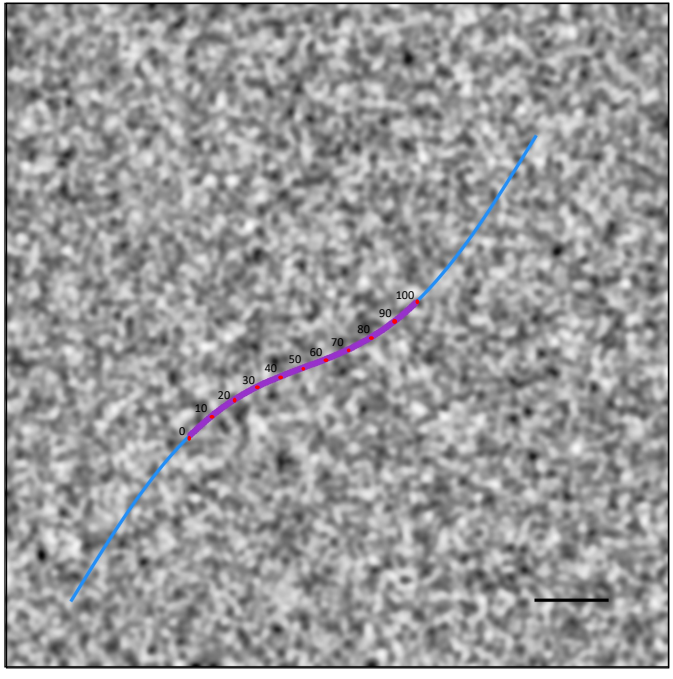


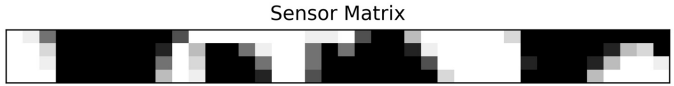


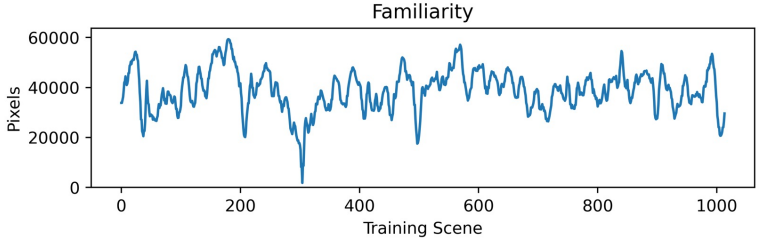
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

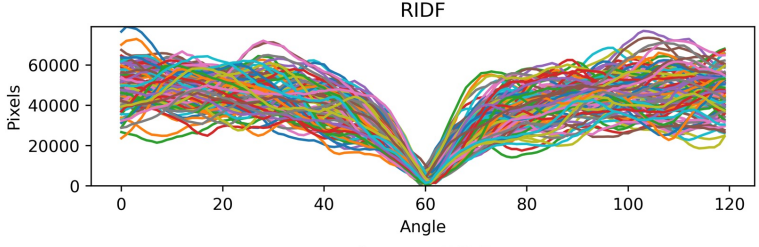
Navigation stats: RMSD error: 61.69; RMSD/dist: 0.154; TD: 31690; p90: 26; p50: 14; complete: 0

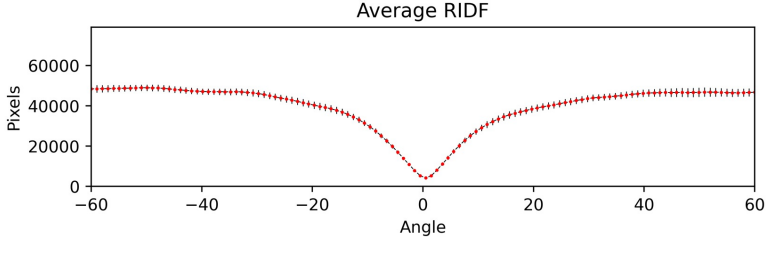
100%







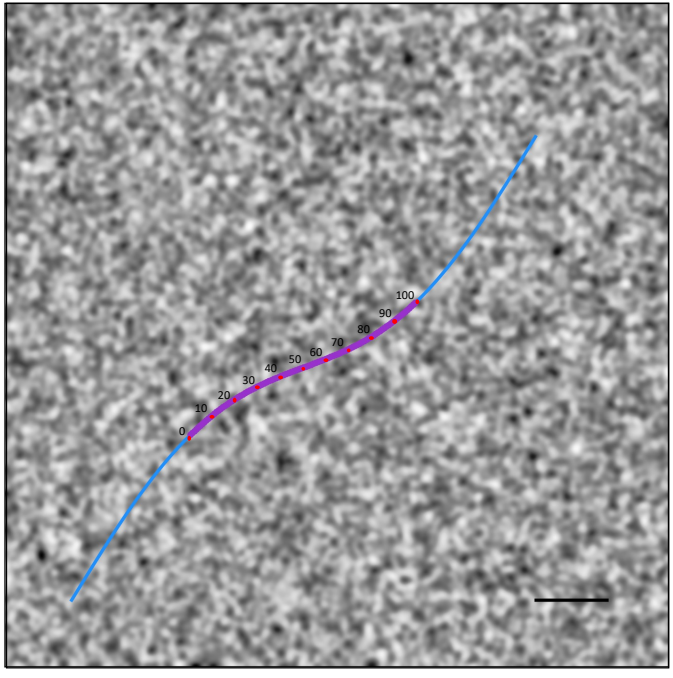


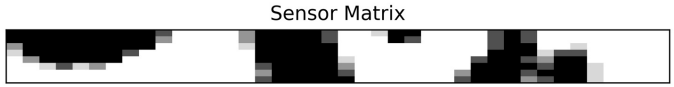


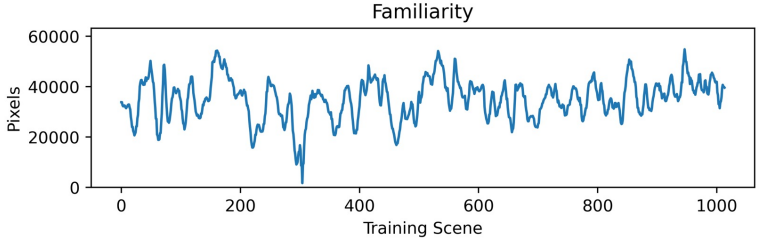
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

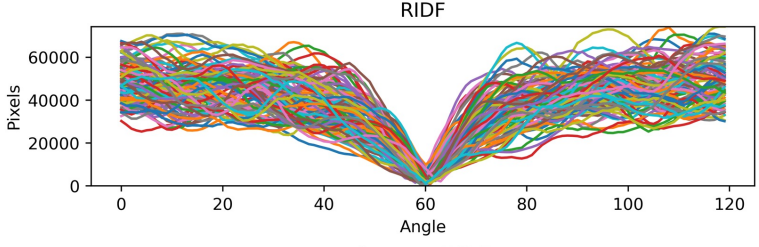
Navigation stats: RMSD error: 59.97; RMSD/dist: 0.150; TD: 33670; p90: 26; p50: 12; complete: 0

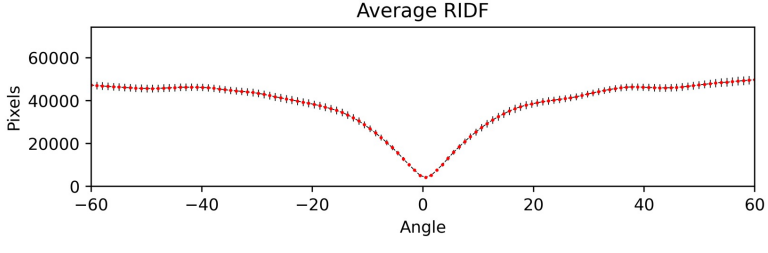
100%







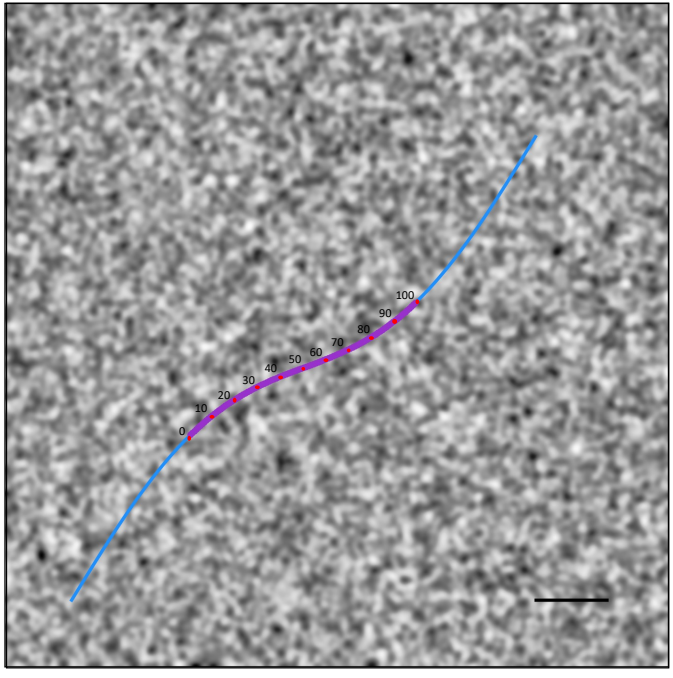


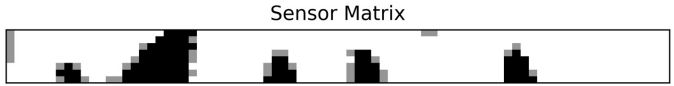


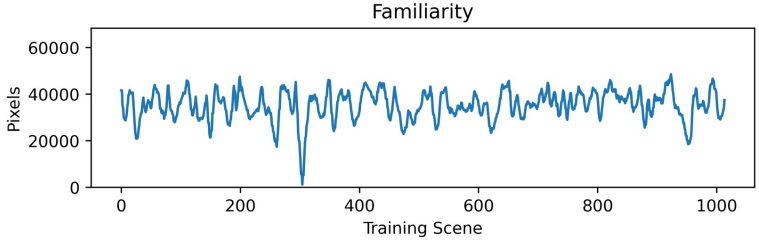
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

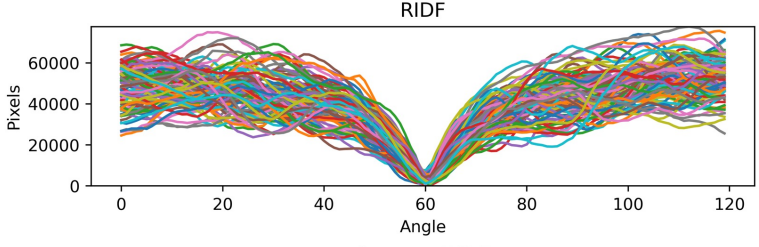
Navigation stats: RMSD error: 66.03; RMSD/dist: 0.165; TD: 30611; p90: 26; p50: 14; complete: 0

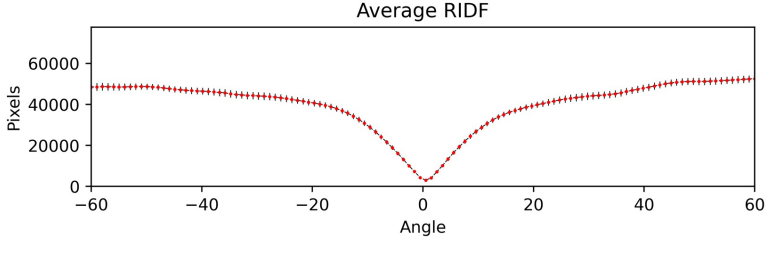
100%







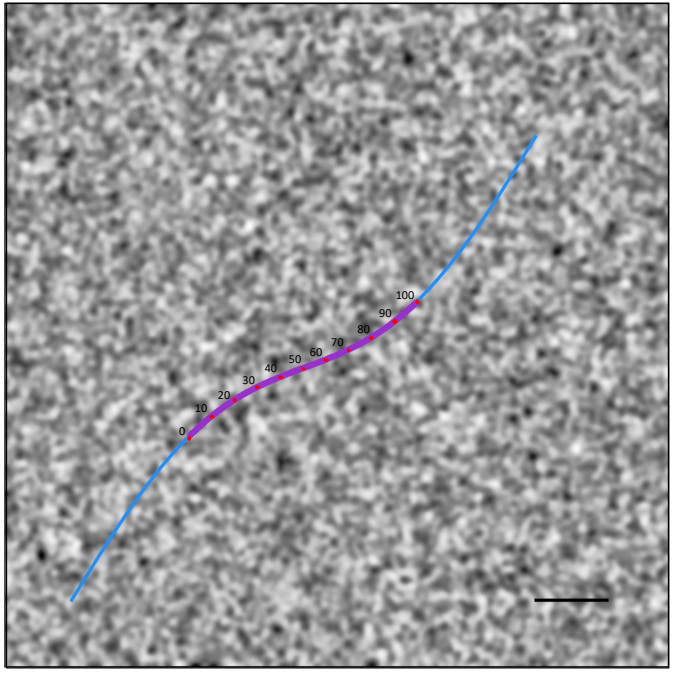


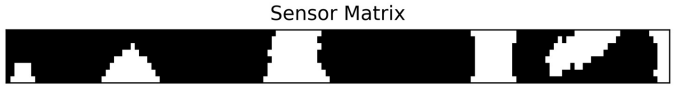


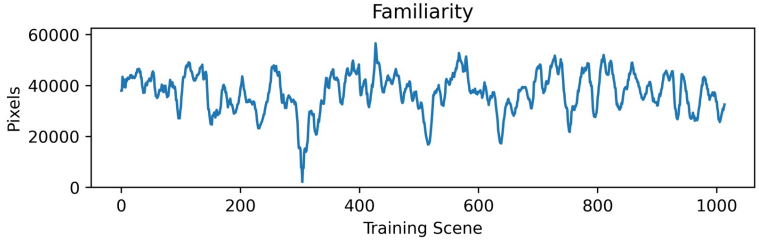
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

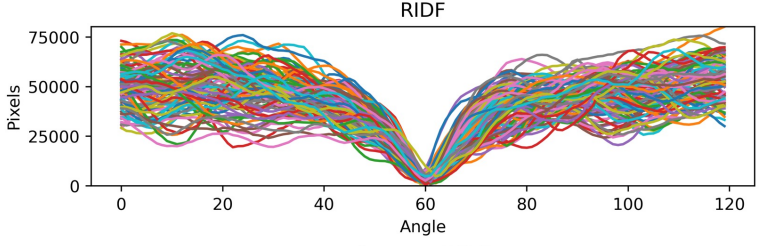
Navigation stats: RMSD error: 34.93; RMSD/dist: 0.087; TD: 34629; p90: 26; p50: 14; complete: 0

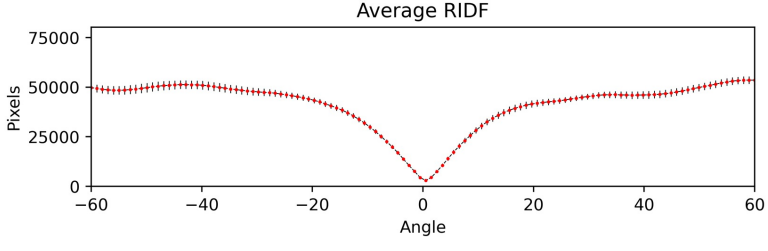
100%





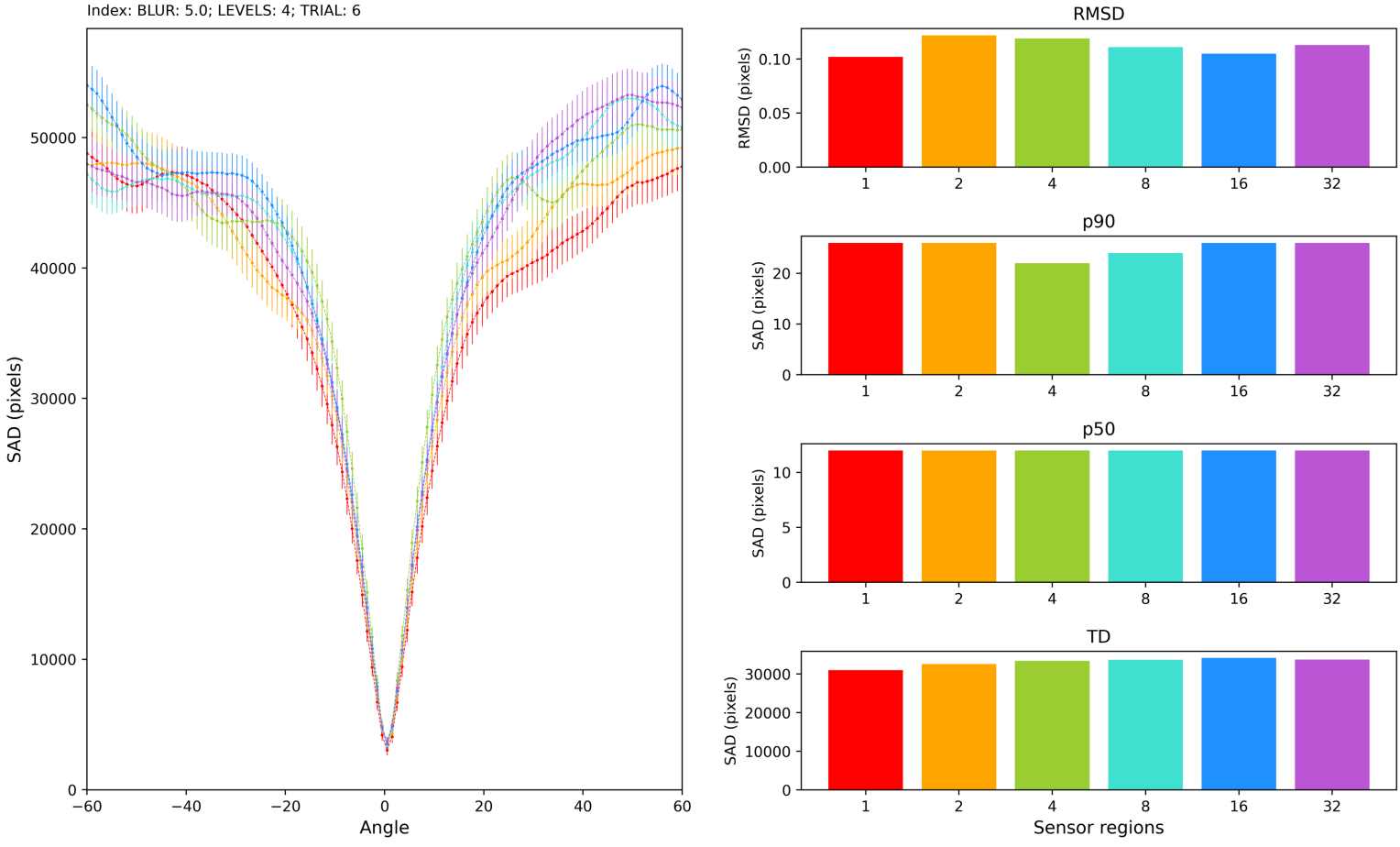




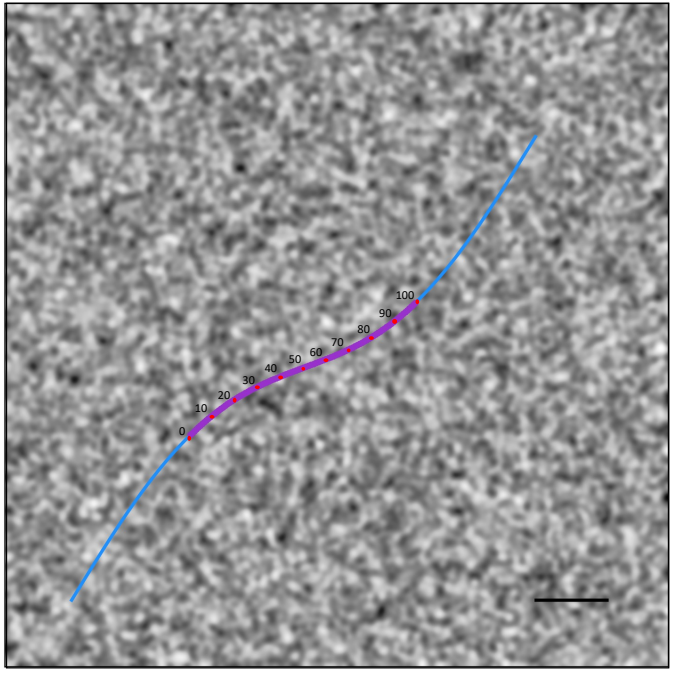


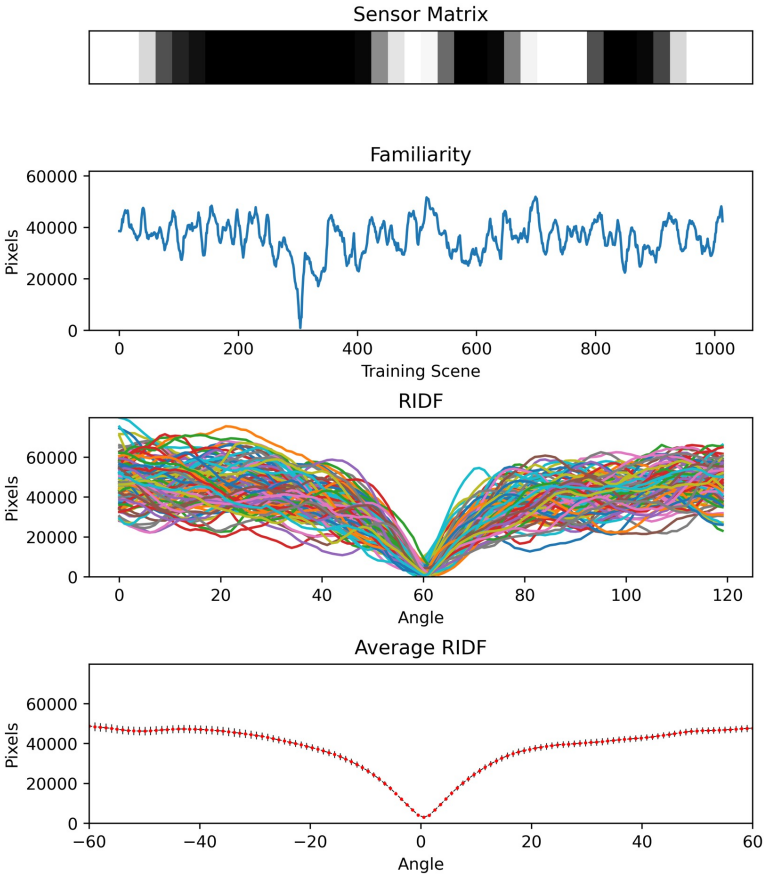
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 32.10; RMSD/dist: 0.080; TD: 34649; p90: 24; p50: 12; complete: 0


Index: BLUR: 5.0; LEVELS: 4; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

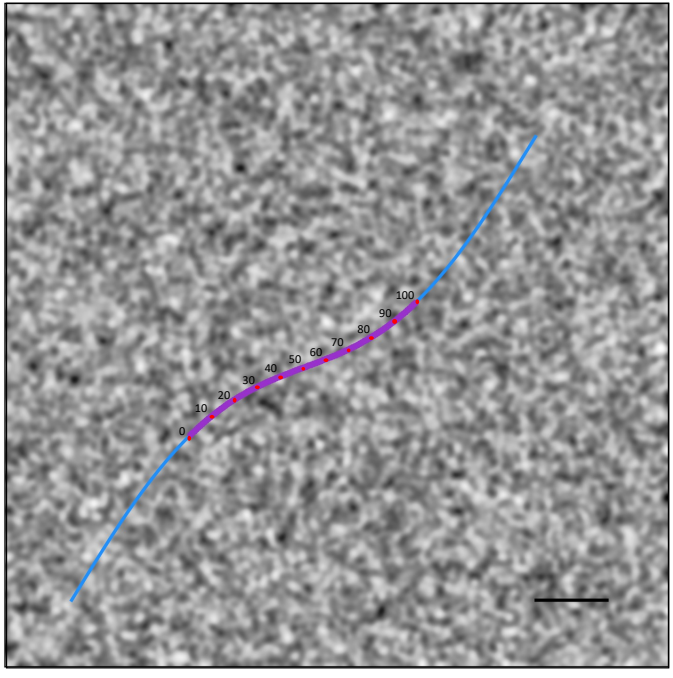


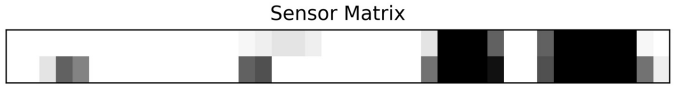


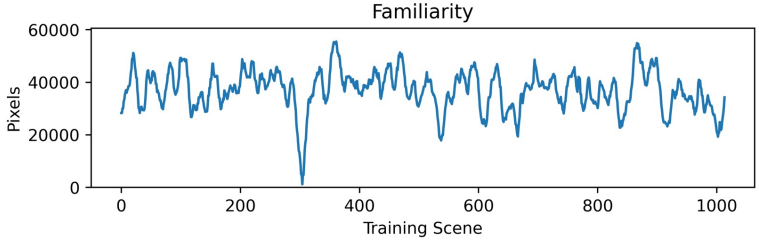
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

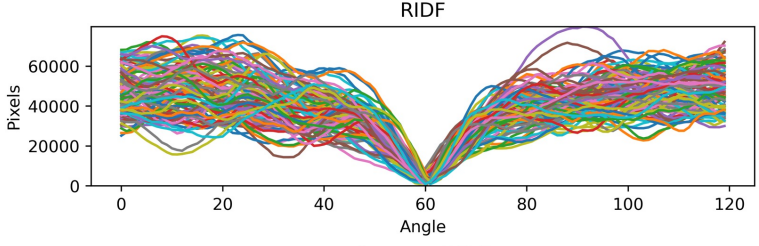
Navigation stats: RMSD error: 40.96; RMSD/dist: 0.102; TD: 30981; p90: 26; p50: 12; complete: 0

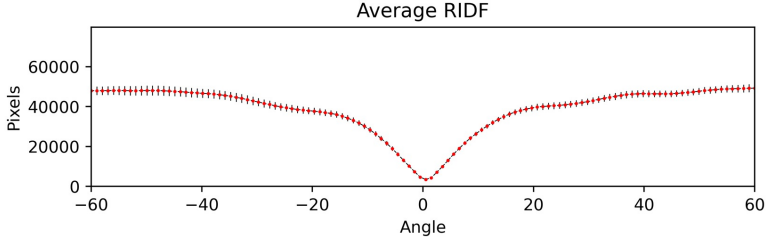
100%







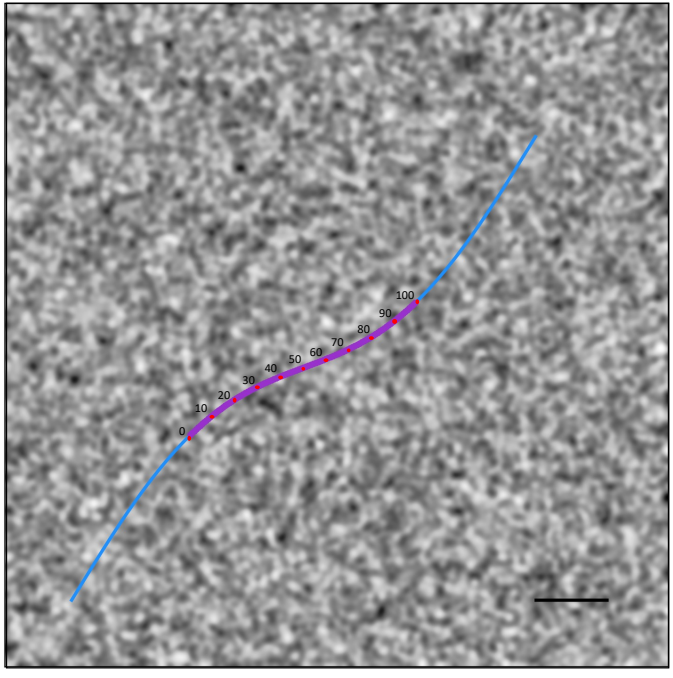


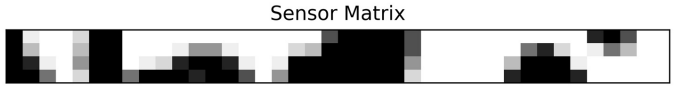


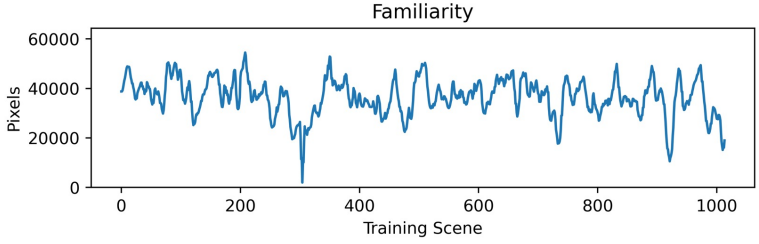
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

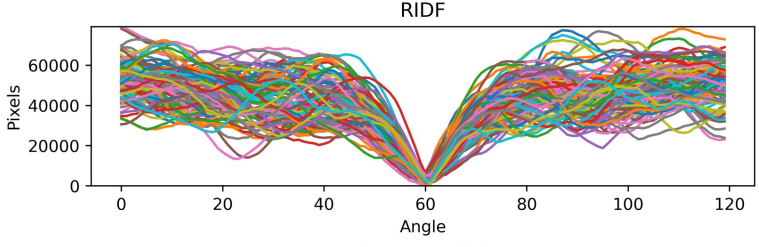
Navigation stats: RMSD error: 48.89; RMSD/dist: 0.122; TD: 32569; p90: 26; p50: 12; complete: 0

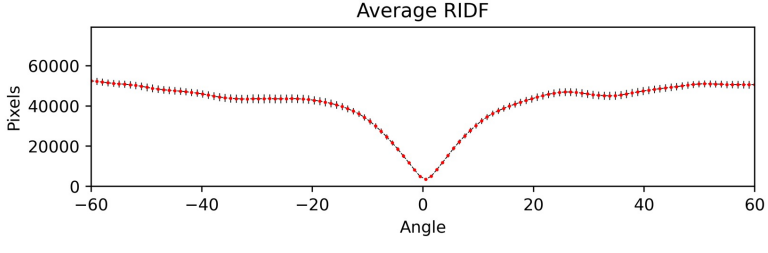
100%







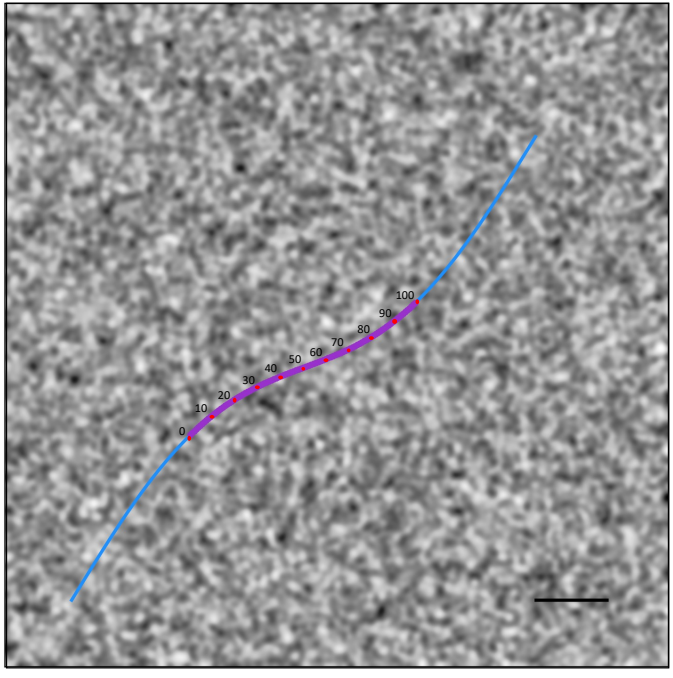


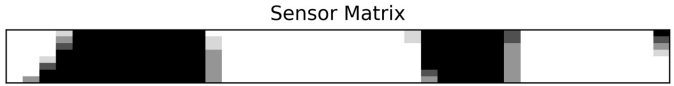


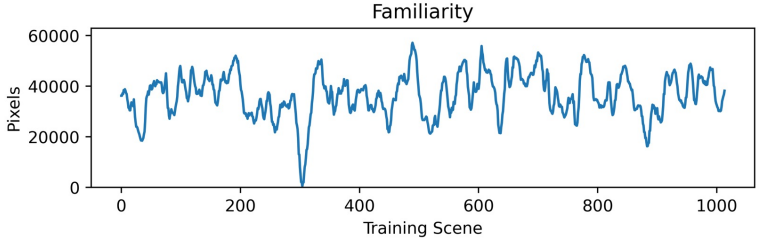
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

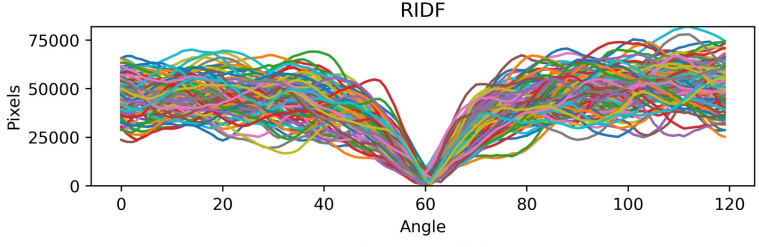
Navigation stats: RMSD error: 47.53; RMSD/dist: 0.119; TD: 33391; p90: 22; p50: 12; complete: 0

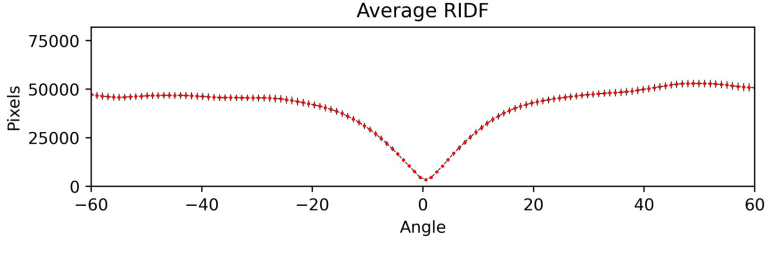
100%







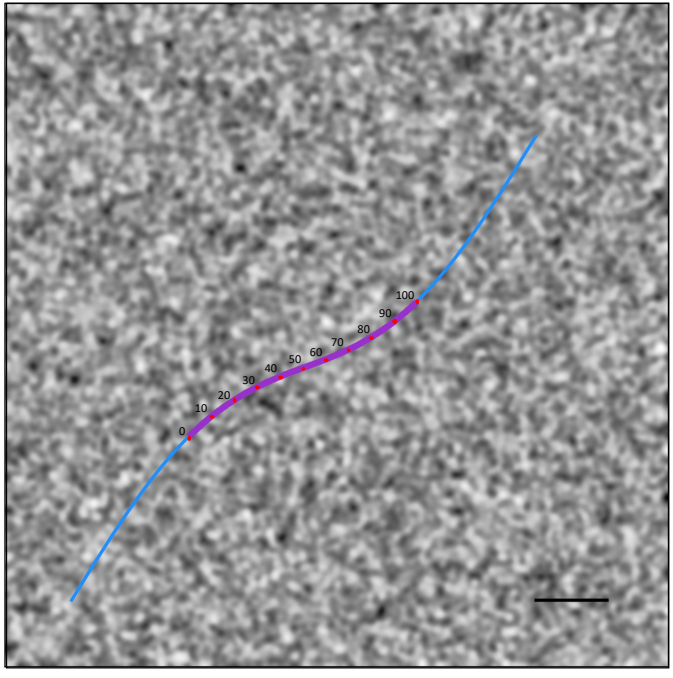


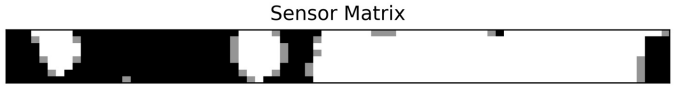


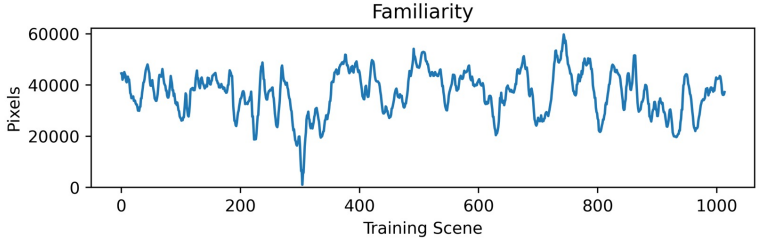
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

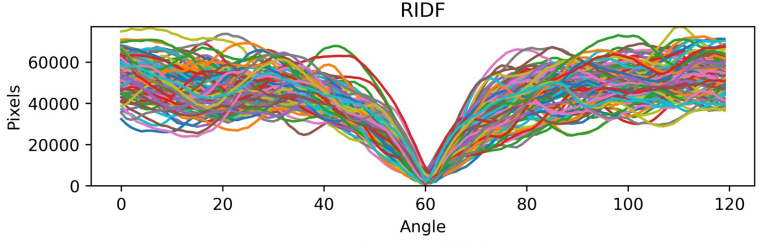
Navigation stats: RMSD error: 44.25; RMSD/dist: 0.111; TD: 33632; p90: 24; p50: 12; complete: 0

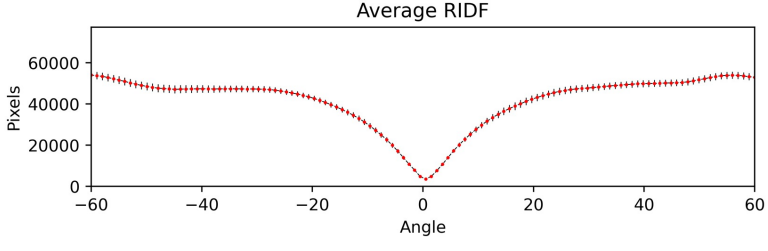
100%







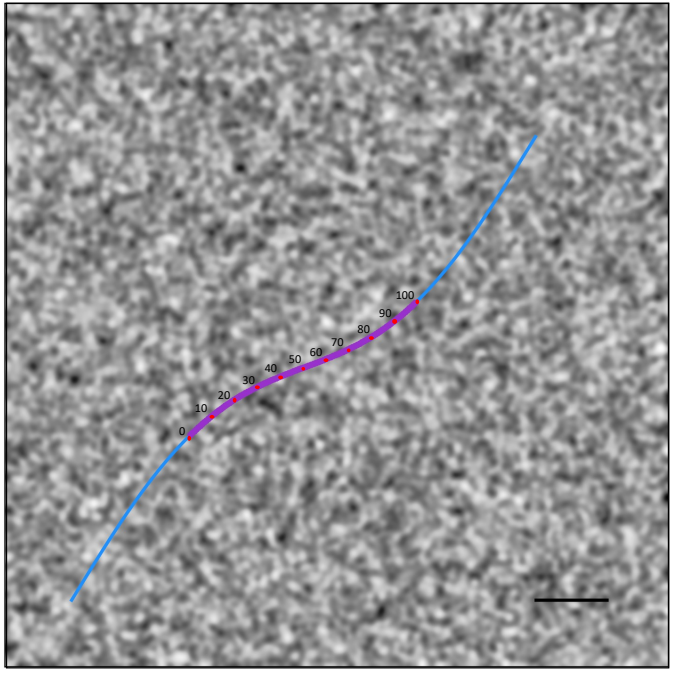


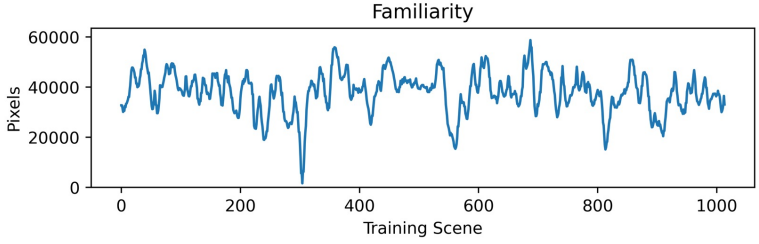


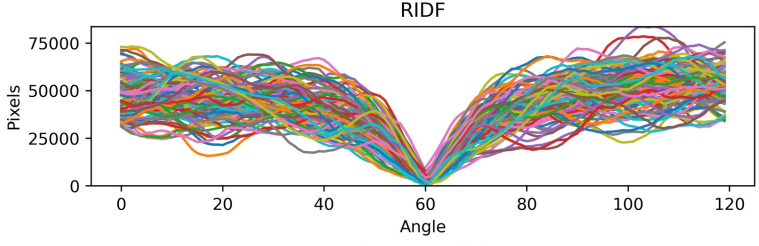
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

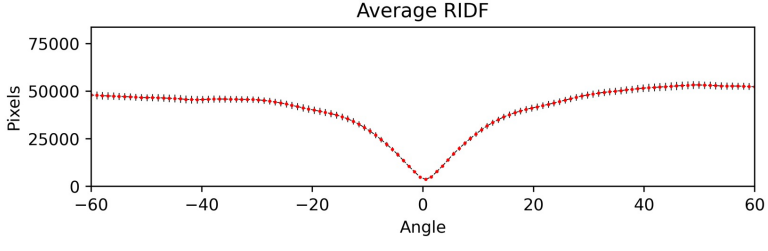
Navigation stats: RMSD error: 41.87; RMSD/dist: 0.105; TD: 34106; p90: 26; p50: 12; complete: 0

100%



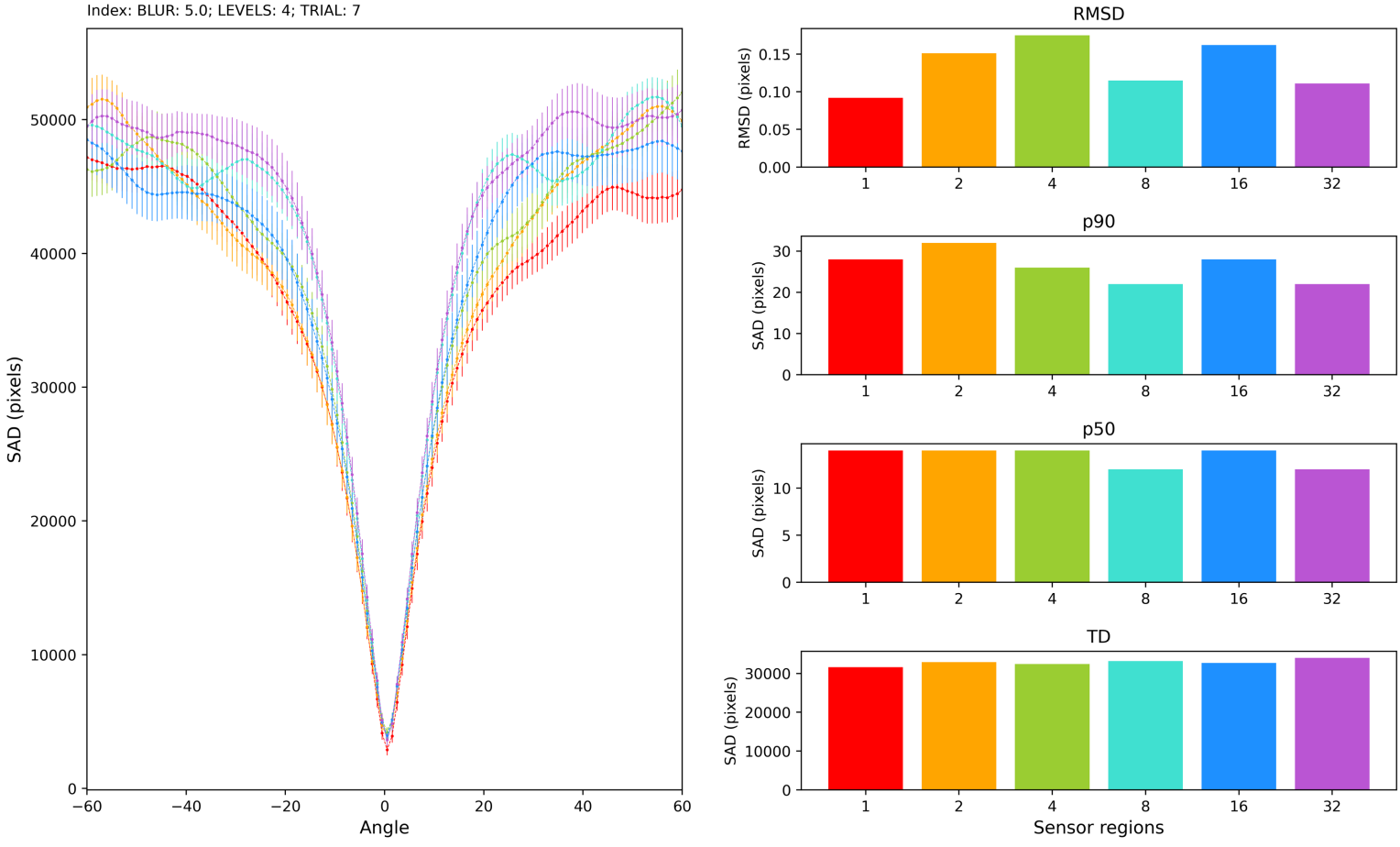




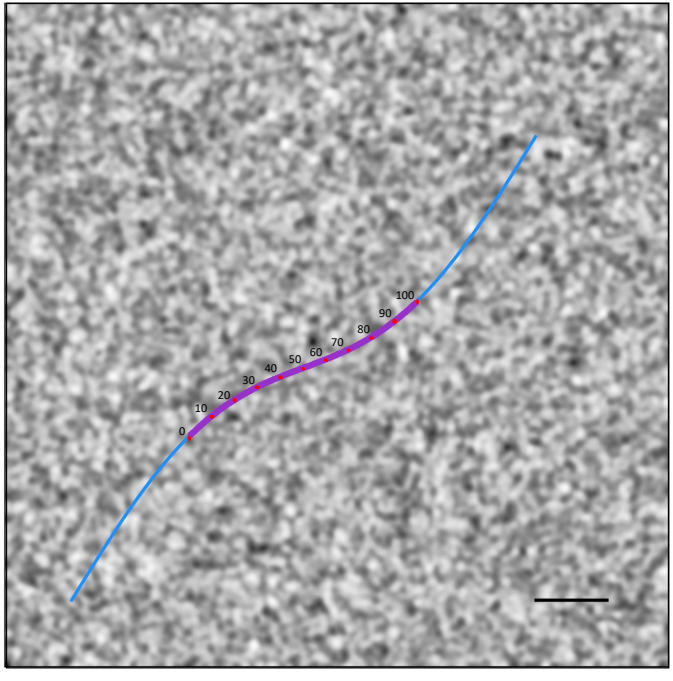


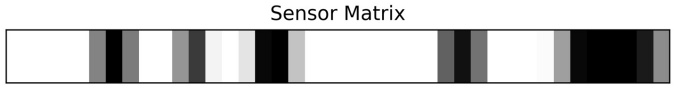
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

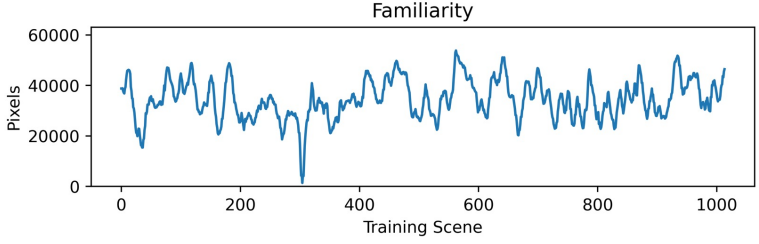
Navigation stats: RMSD error: 45.39; RMSD/dist: 0.113; TD: 33721; p90: 26; p50: 12; complete: 0

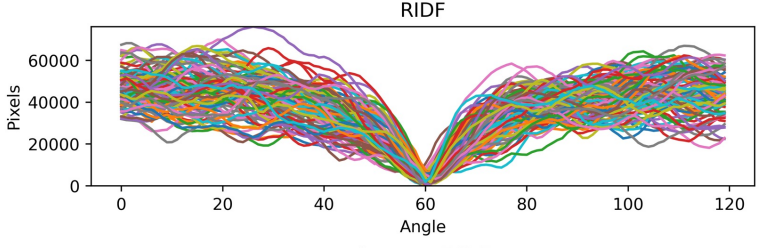

Index: BLUR: 5.0; LEVELS: 4; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

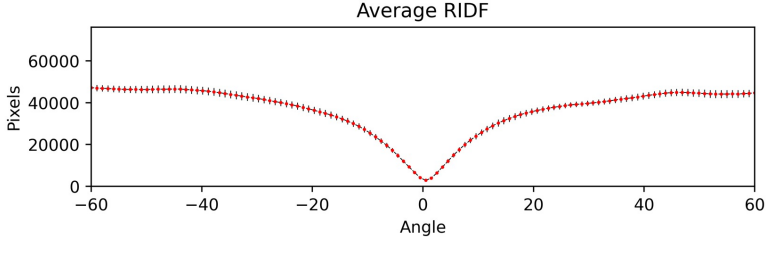
100%







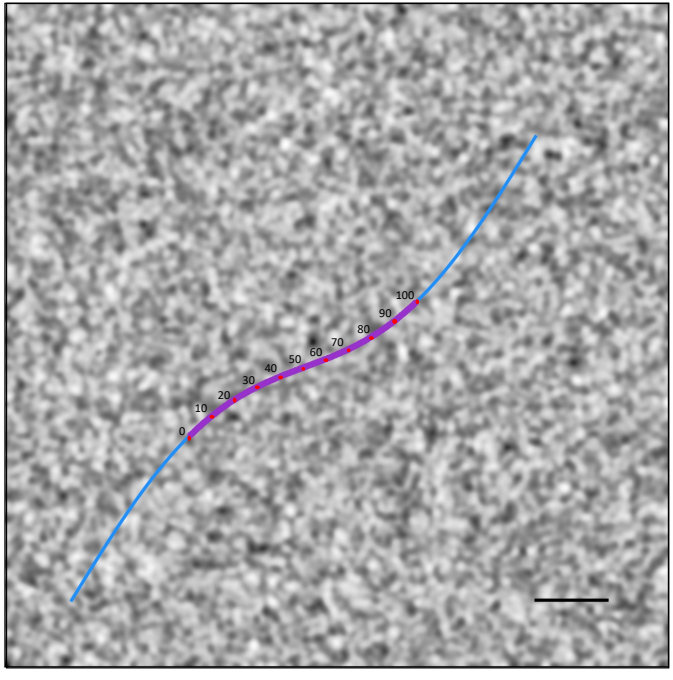


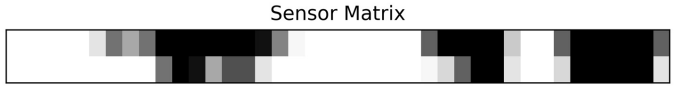


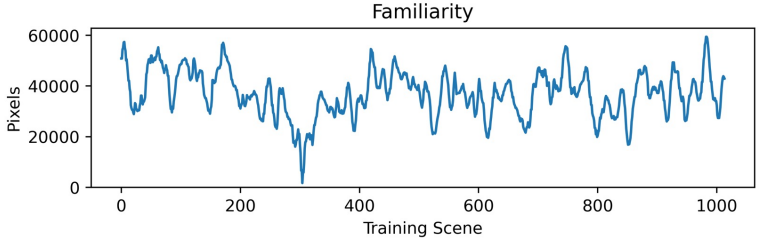
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

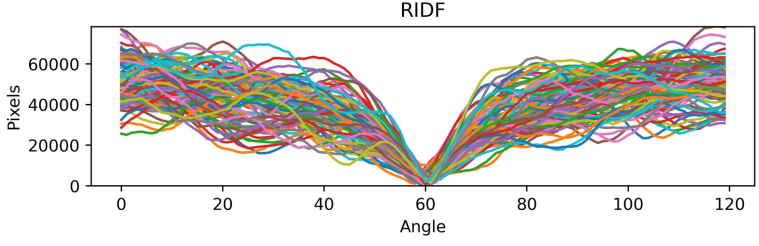
Navigation stats: RMSD error: 36.89; RMSD/dist: 0.092; TD: 31594; p90: 28; p50: 14; complete: 0

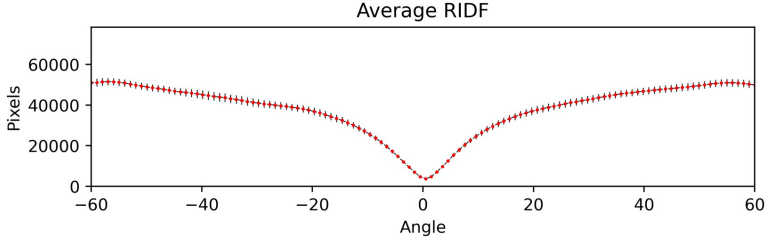
100%







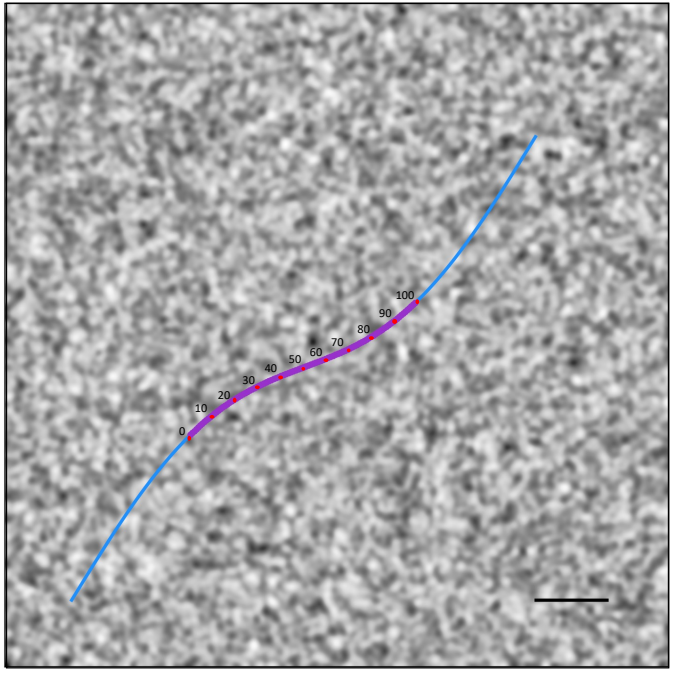


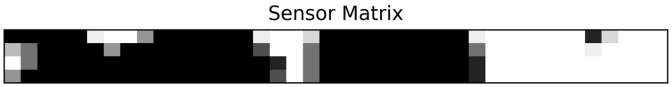


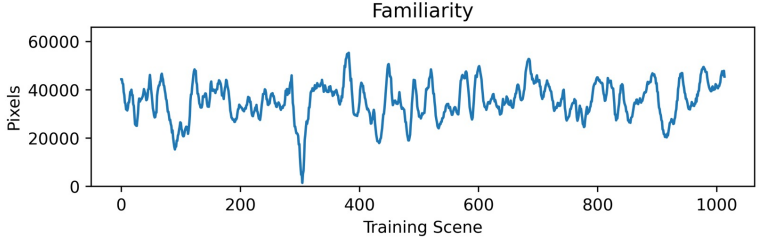
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

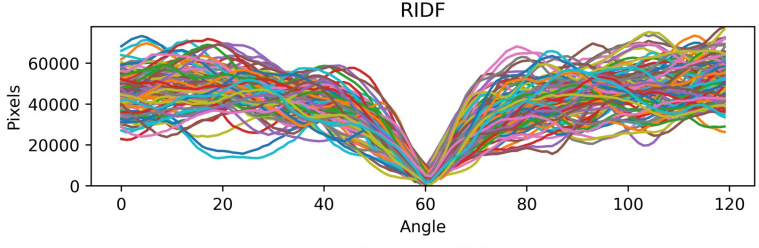
Navigation stats: RMSD error: 60.54; RMSD/dist: 0.151; TD: 32927; p90: 32; p50: 14; complete: 0

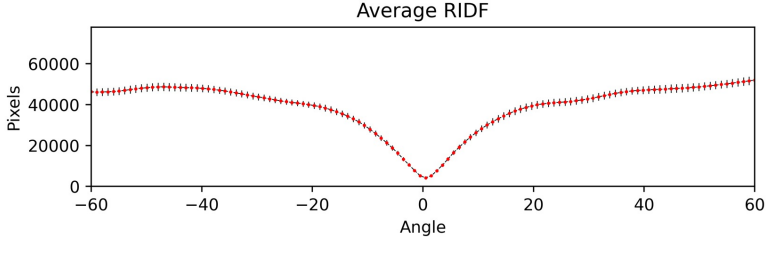
100%







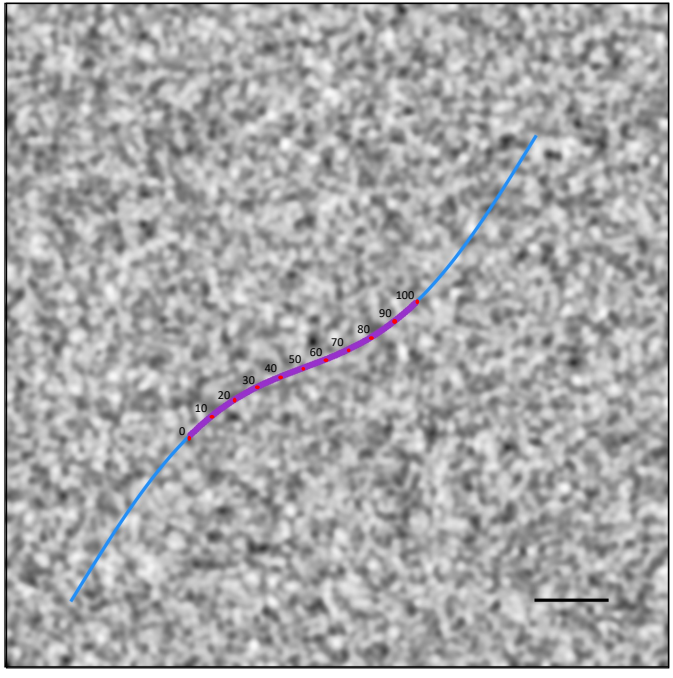


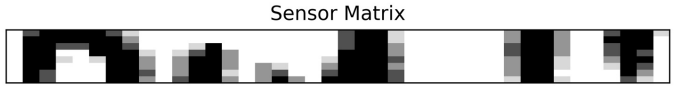


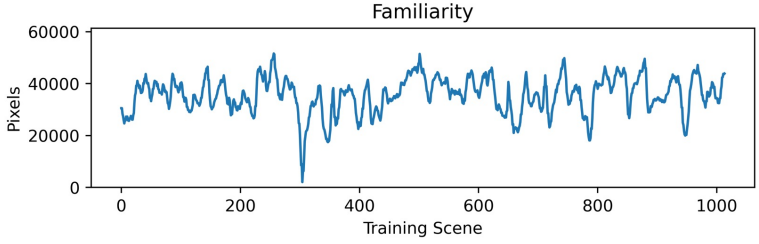
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

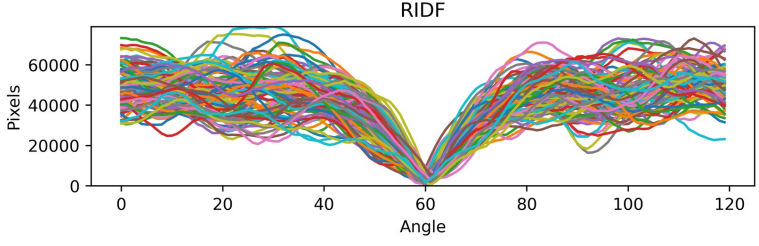
Navigation stats: RMSD error: 69.80; RMSD/dist: 0.175; TD: 32445; p90: 26; p50: 14; complete: 0

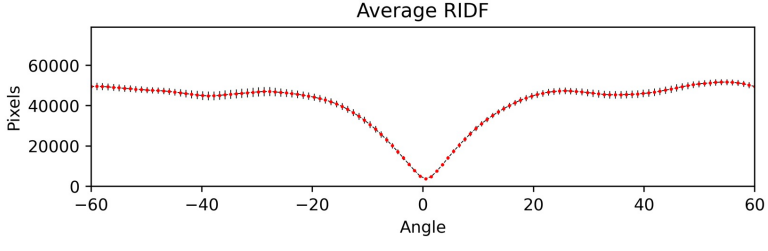
100%







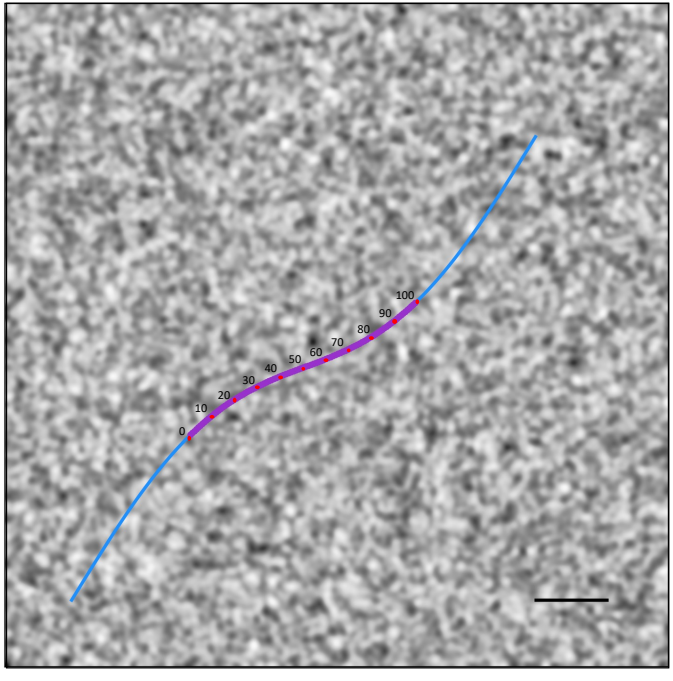


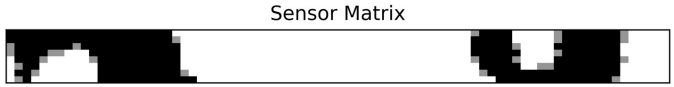


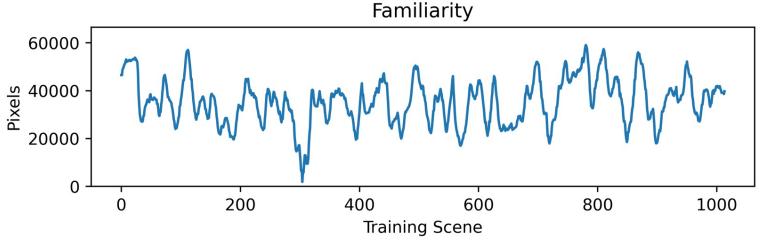
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

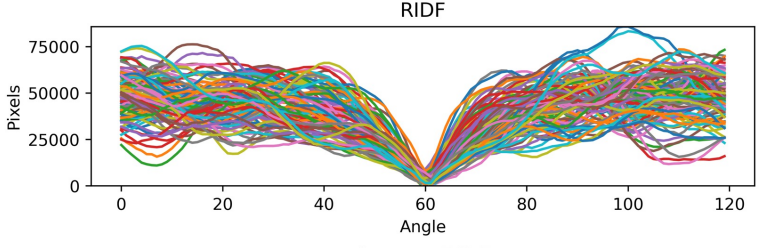
Navigation stats: RMSD error: 45.95; RMSD/dist: 0.115; TD: 33205; p90: 22; p50: 12; complete: 0

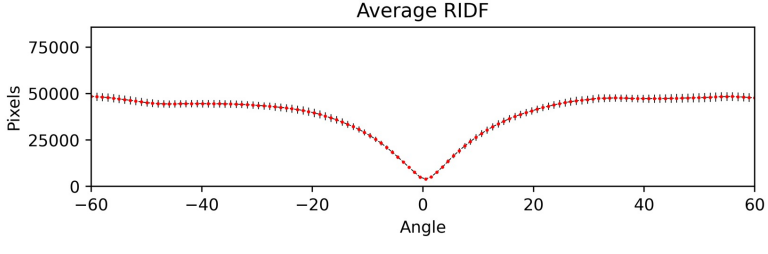
100%







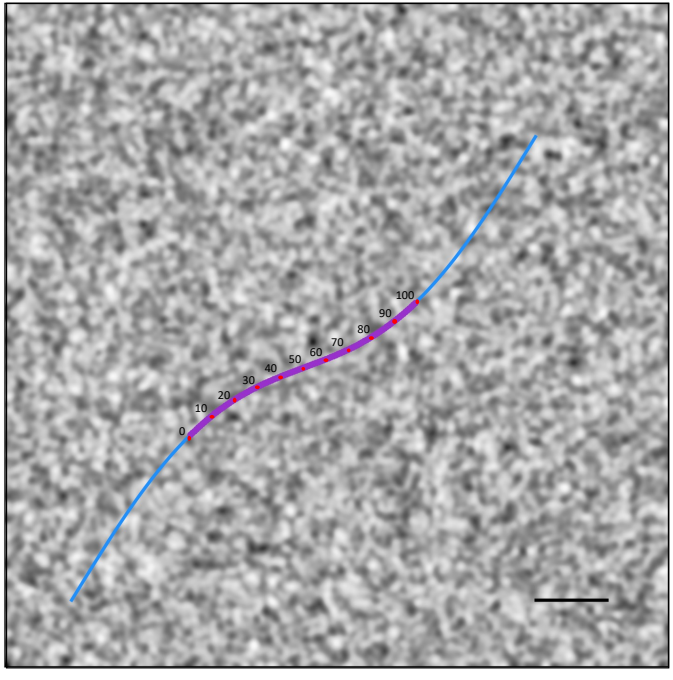


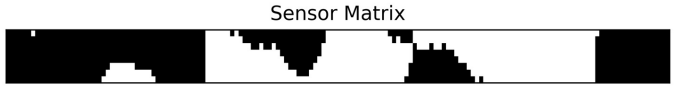


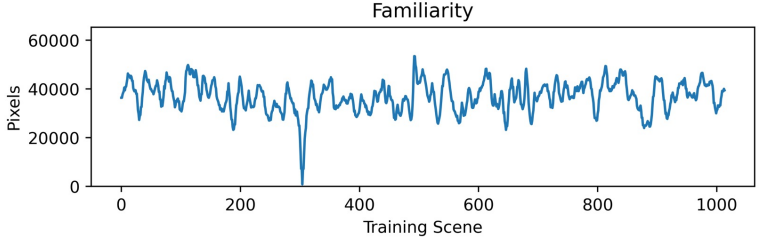
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

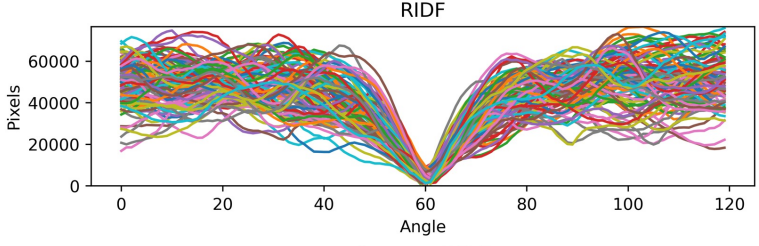
Navigation stats: RMSD error: 64.94; RMSD/dist: 0.162; TD: 32676; p90: 28; p50: 14; complete: 0

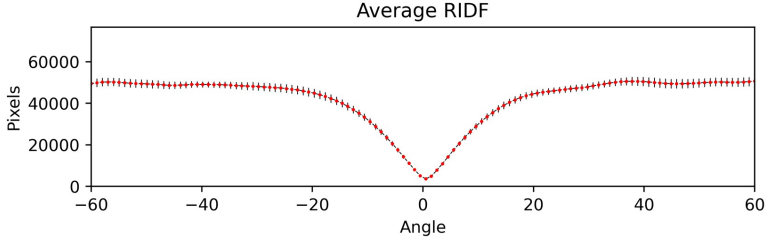
100%





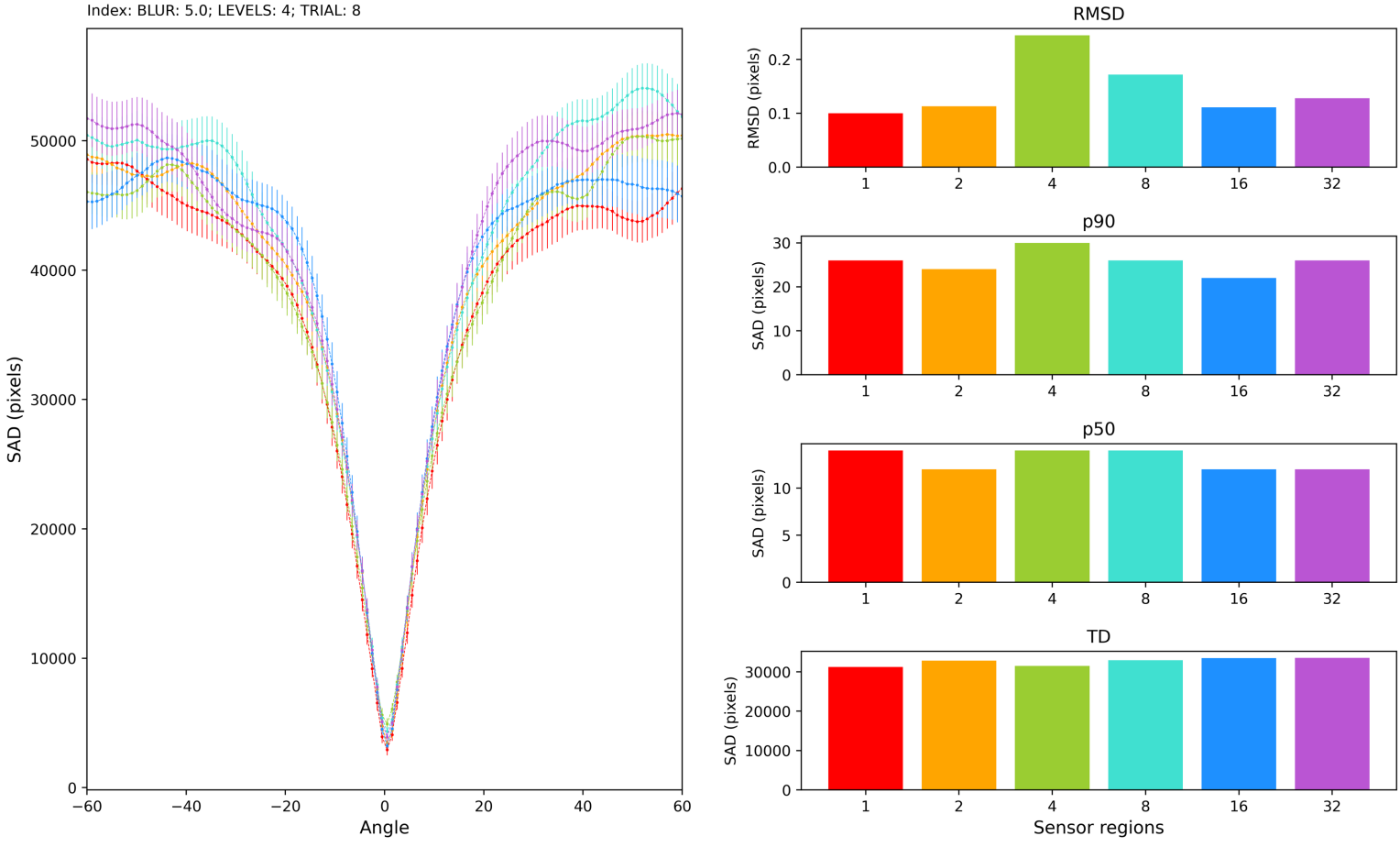




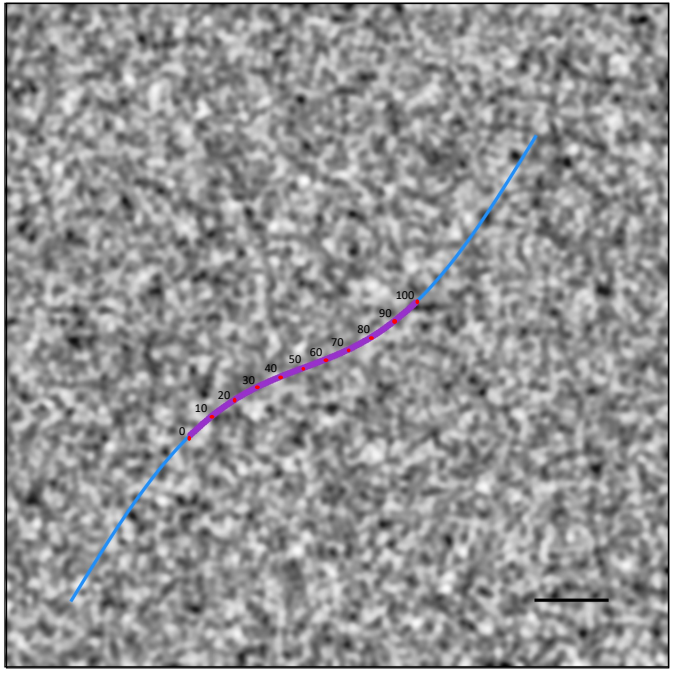


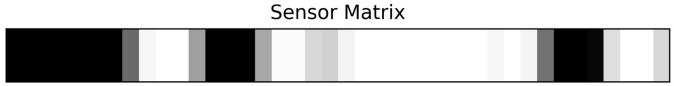
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

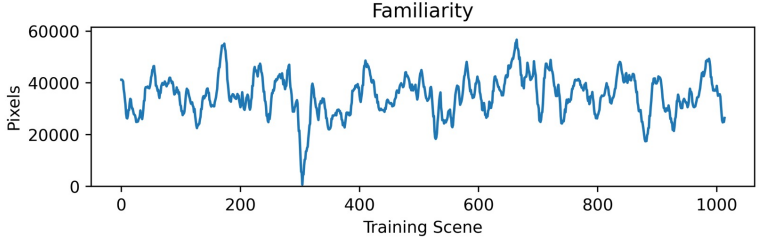
Navigation stats: RMSD error: 44.60; RMSD/dist: 0.111; TD: 33979; p90: 22; p50: 12; complete: 0

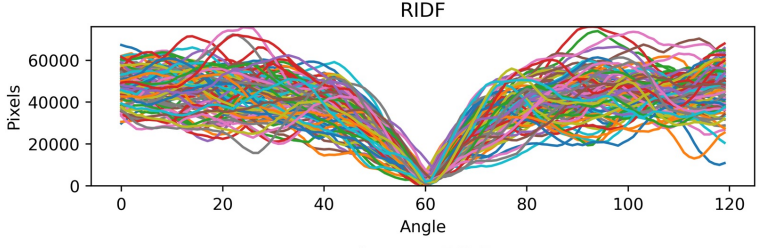

Index: BLUR: 5.0; LEVELS: 4; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

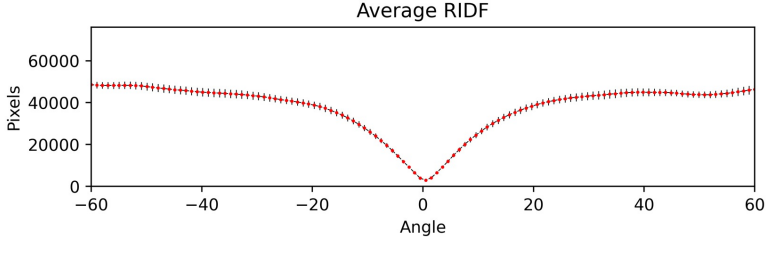
100%







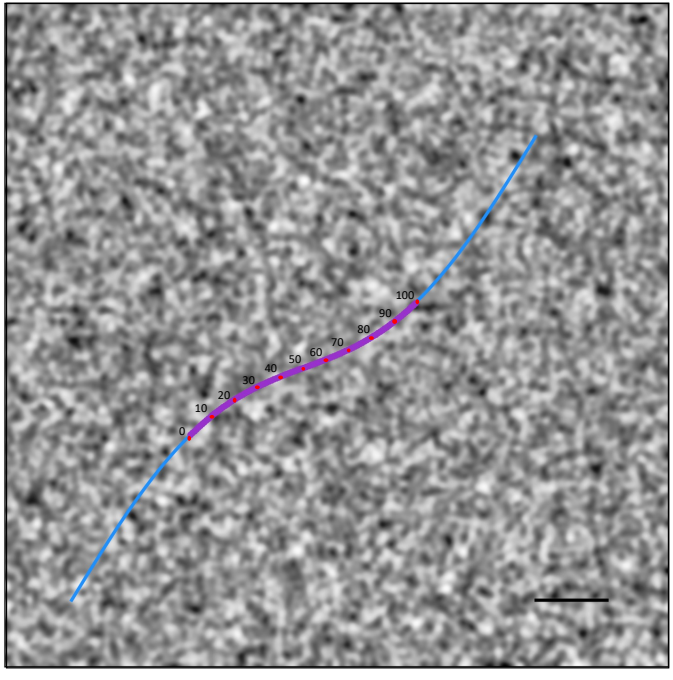


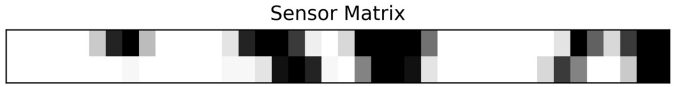


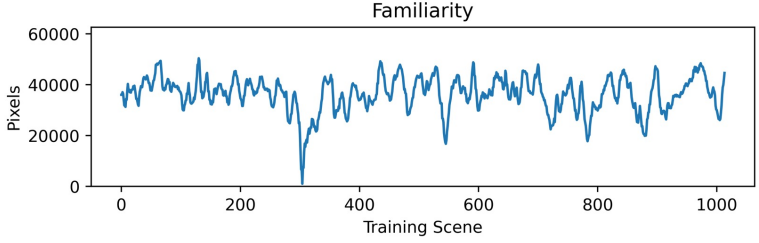
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

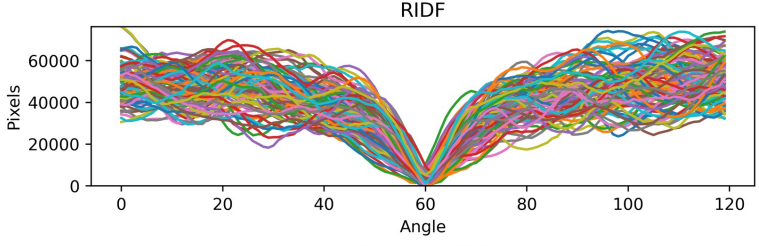
Navigation stats: RMSD error: 40.20; RMSD/dist: 0.100; TD: 31278; p90: 26; p50: 14; complete: 0

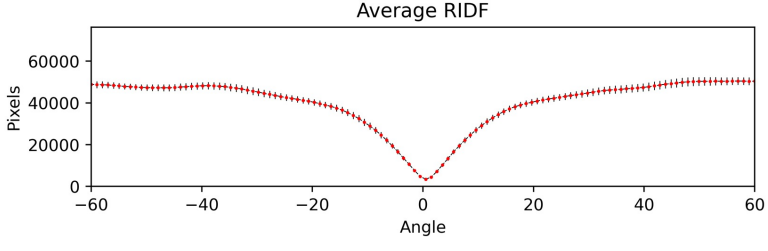
100%







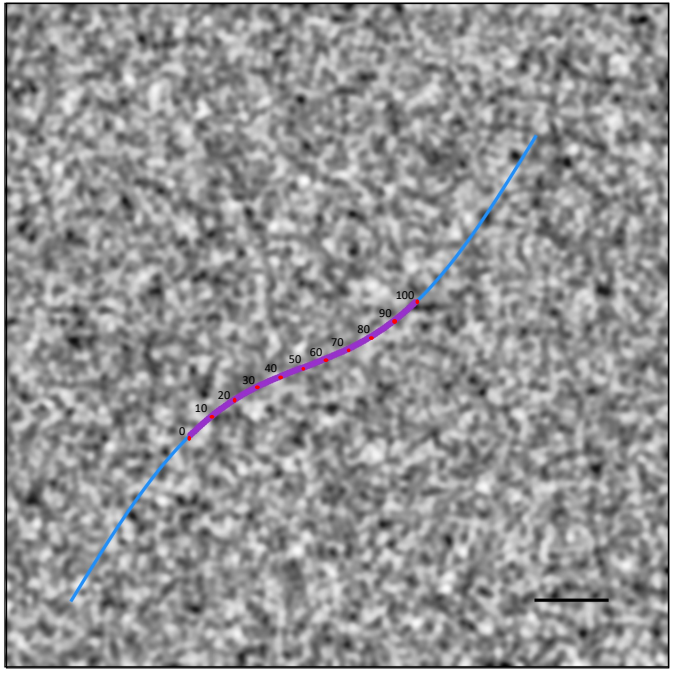


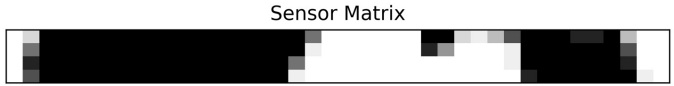


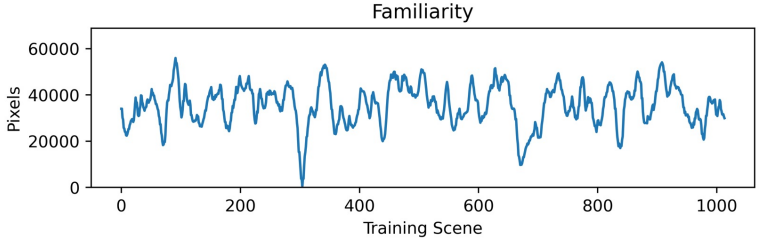
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

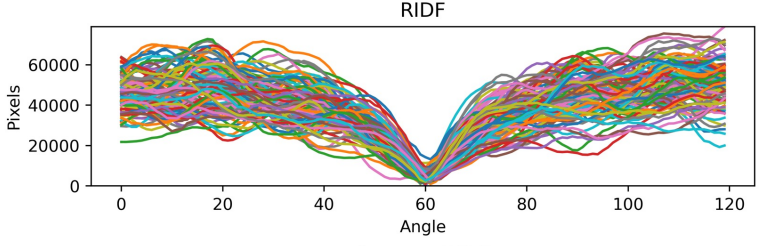
Navigation stats: RMSD error: 45.10; RMSD/dist: 0.113; TD: 32847; p90: 24; p50: 12; complete: 0

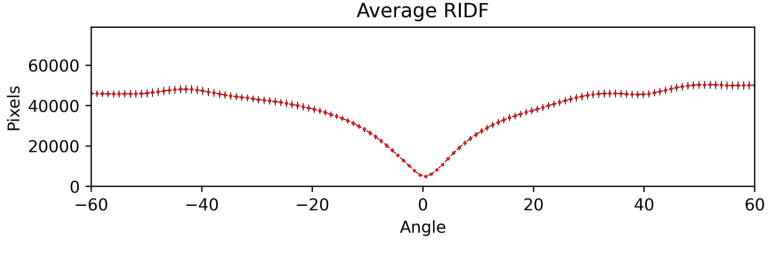
100%







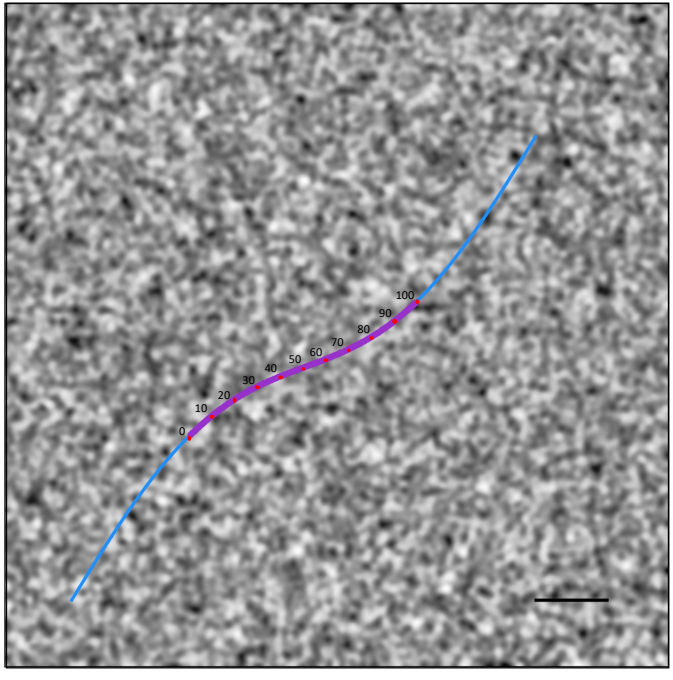


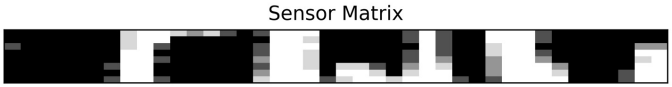


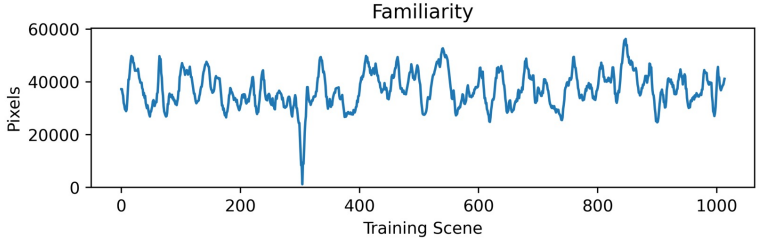
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

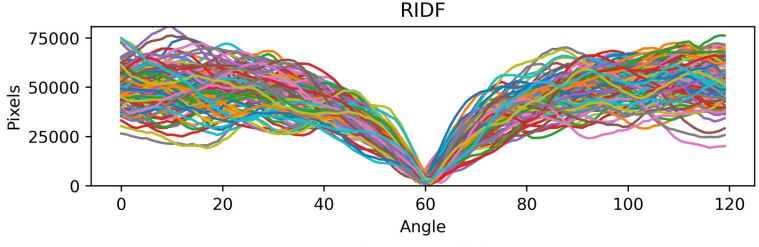
Navigation stats: RMSD error: 97.91; RMSD/dist: 0.245; TD: 31535; p90: 30; p50: 14; complete: 0

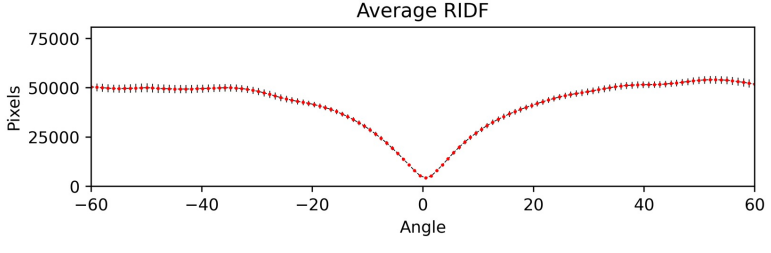
100%







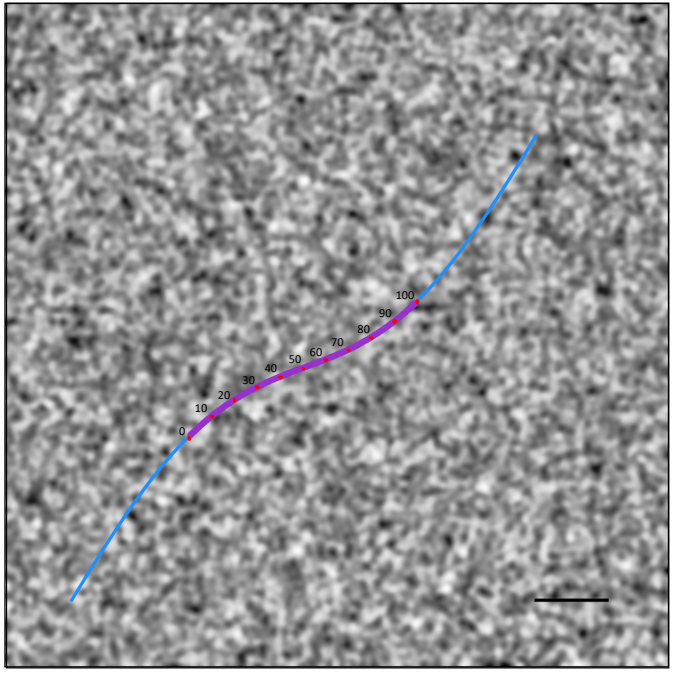


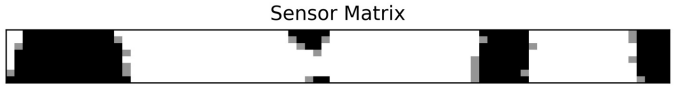


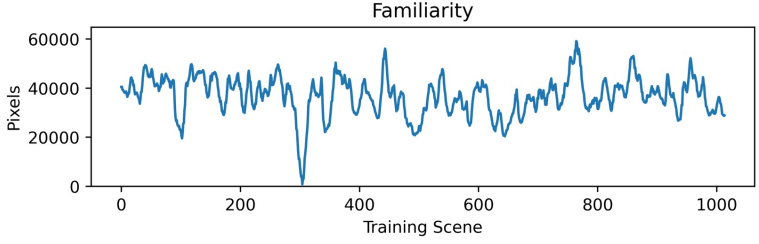
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

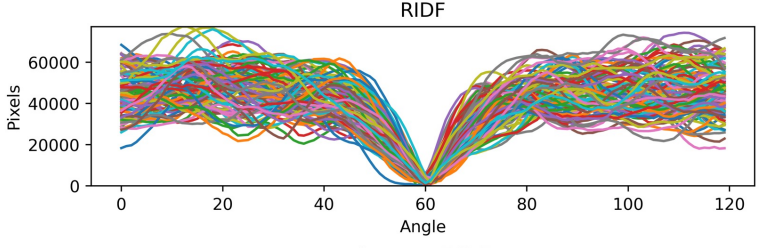
Navigation stats: RMSD error: 68.67; RMSD/dist: 0.172; TD: 32949; p90: 26; p50: 14; complete: 0

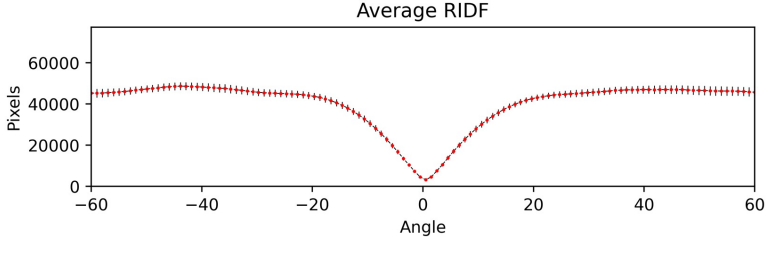
100%







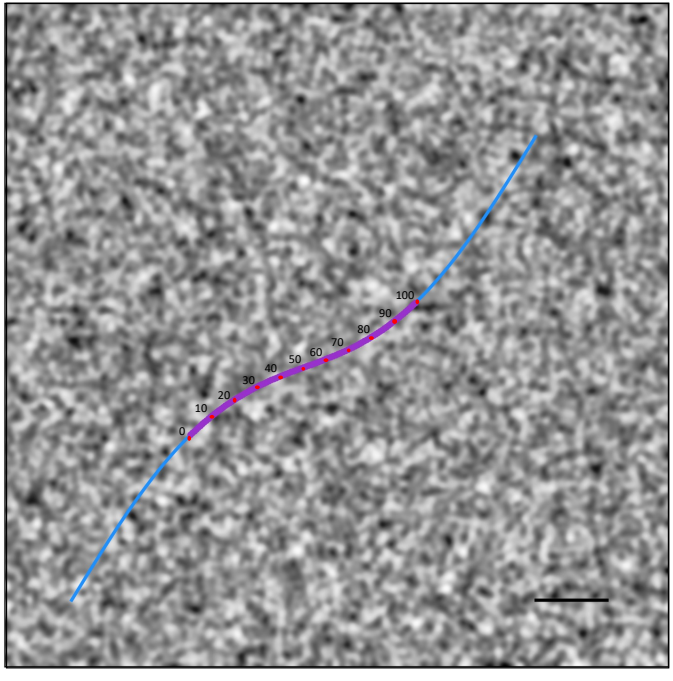


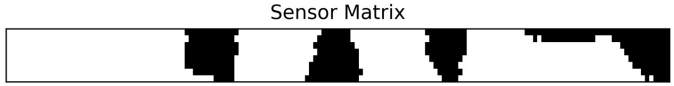


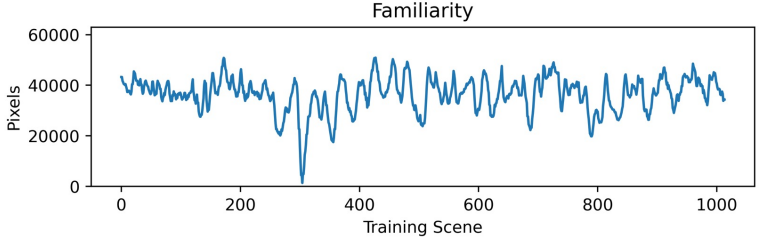
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

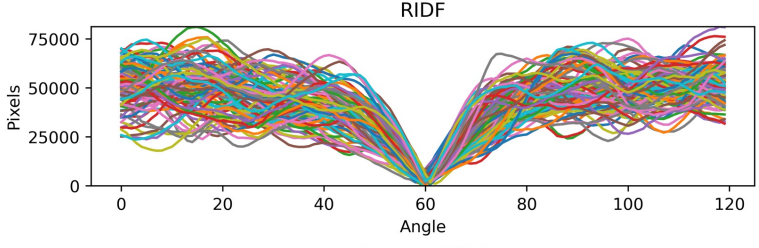
Navigation stats: RMSD error: 44.43; RMSD/dist: 0.111; TD: 33506; p90: 22; p50: 12; complete: 0

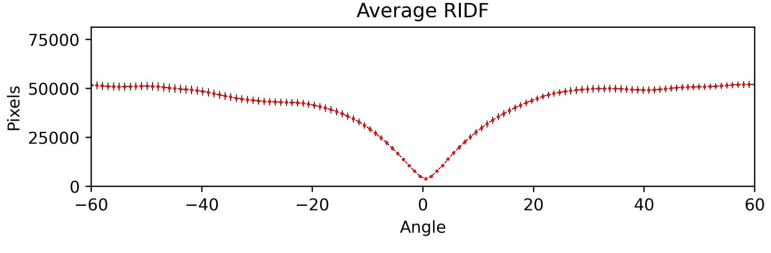
100%





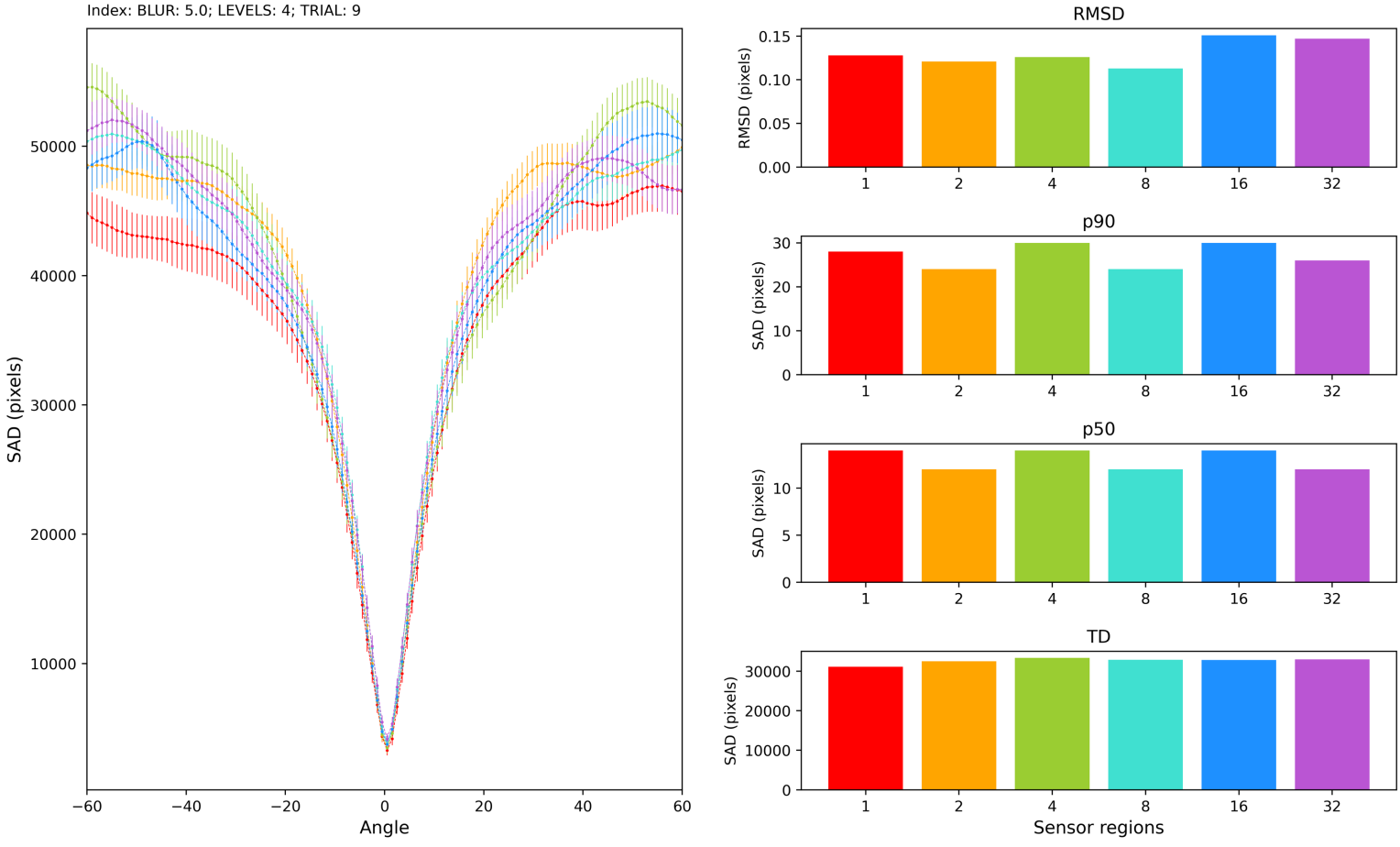




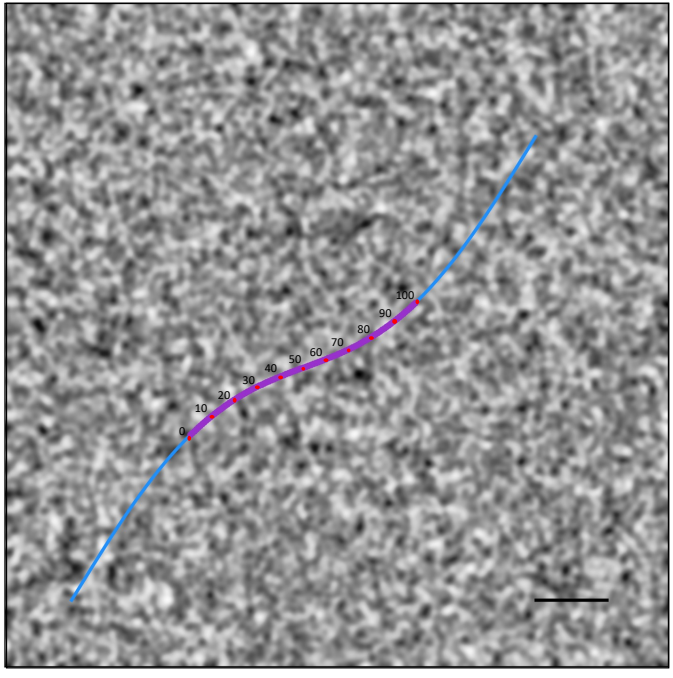


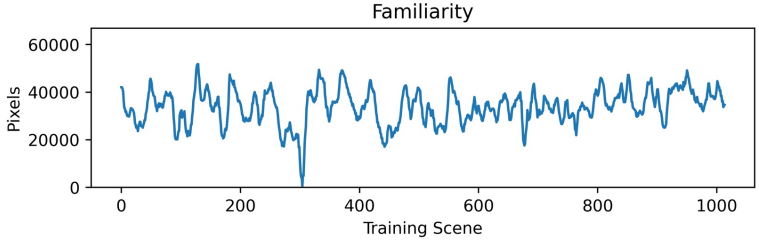
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

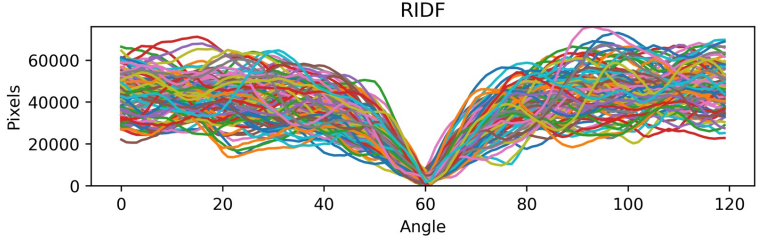
Navigation stats: RMSD error: 51.38; RMSD/dist: 0.128; TD: 33540; p90: 26; p50: 12; complete: 0

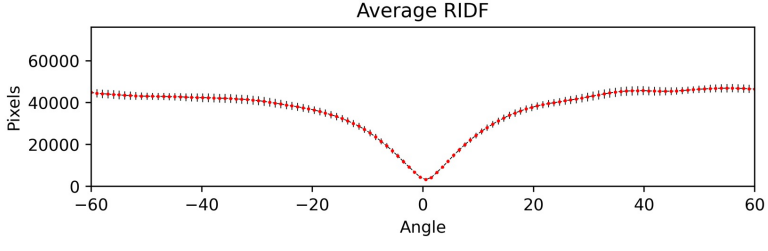

Index: BLUR: 5.0; LEVELS: 4; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%





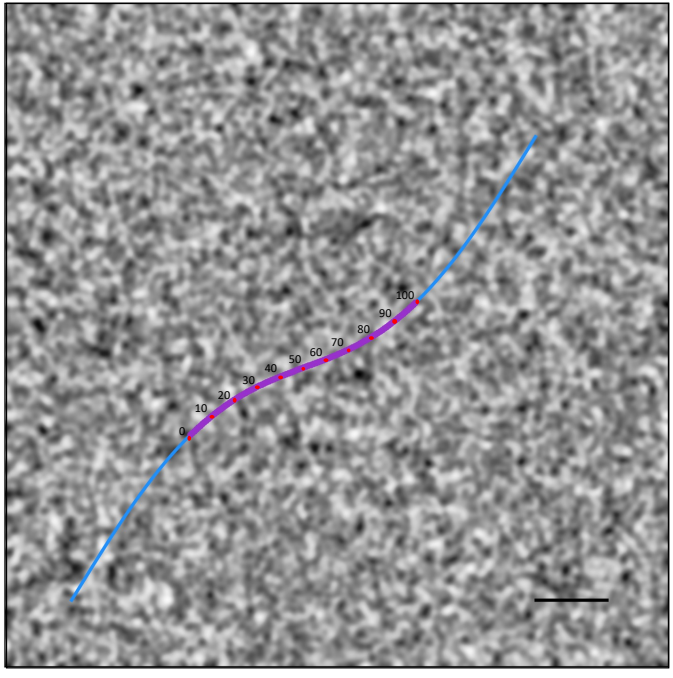


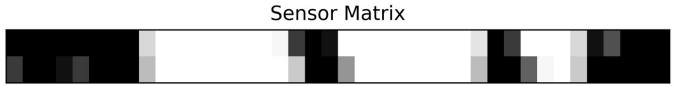


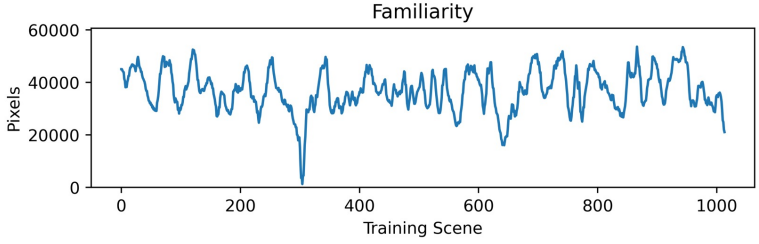
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

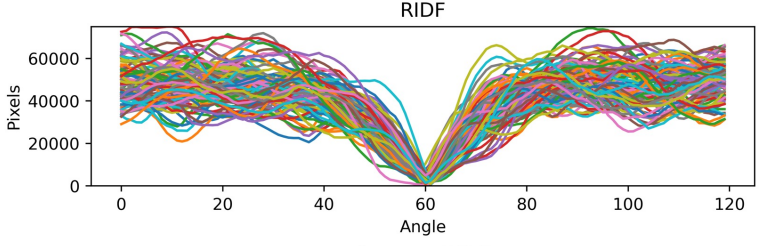
Navigation stats: RMSD error: 51.13; RMSD/dist: 0.128; TD: 31108; p90: 28; p50: 14; complete: 0

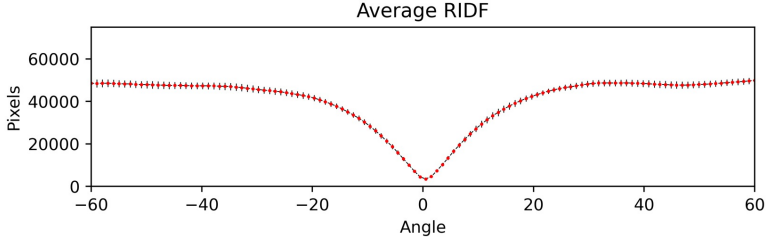
100%







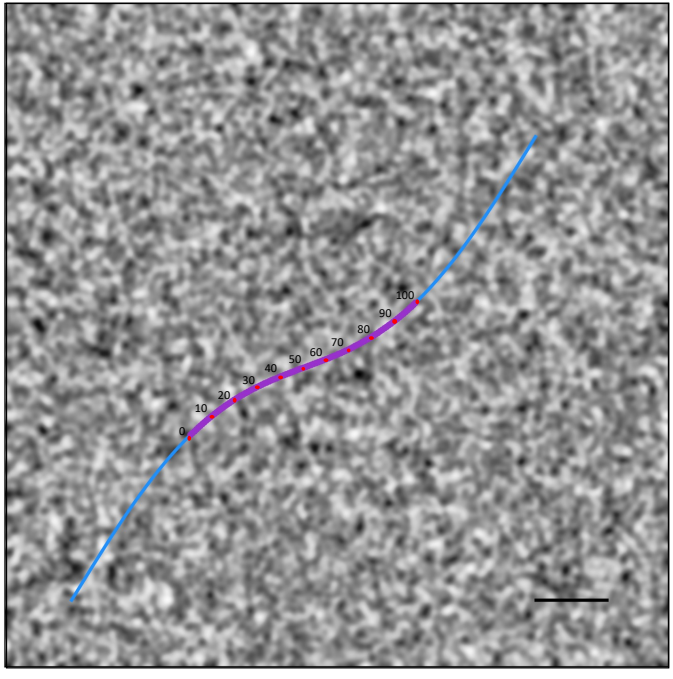


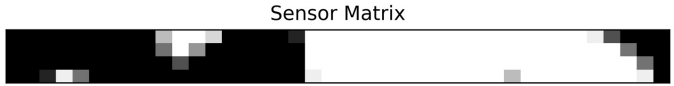


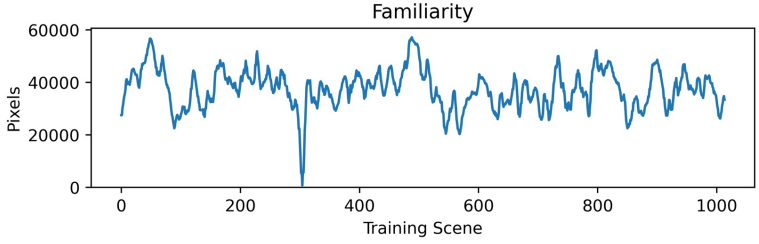
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

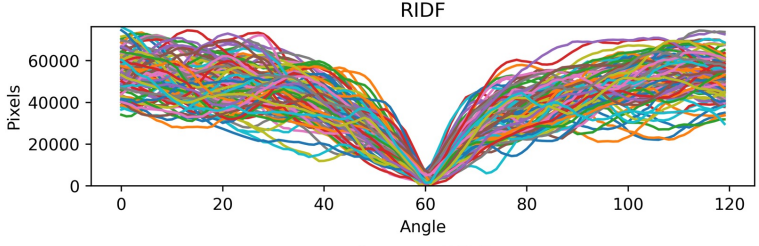
Navigation stats: RMSD error: 48.29; RMSD/dist: 0.121; TD: 32530; p90: 24; p50: 12; complete: 0

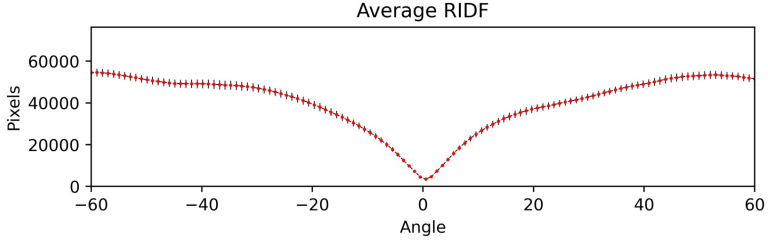
100%







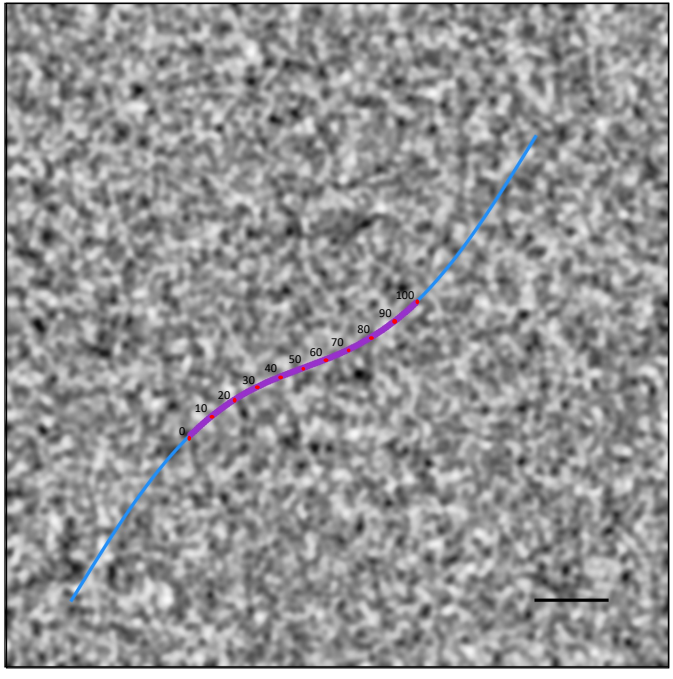


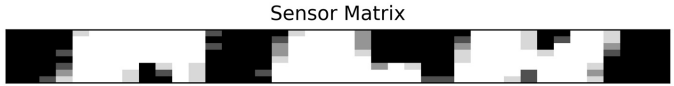


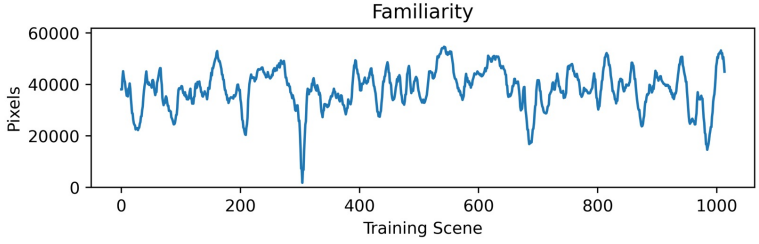
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

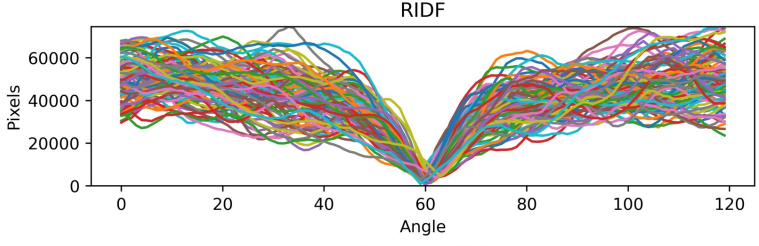
Navigation stats: RMSD error: 50.24; RMSD/dist: 0.126; TD: 33341; p90: 30; p50: 14; complete: 0

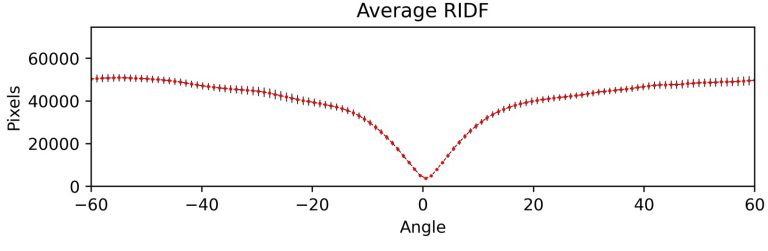
100%







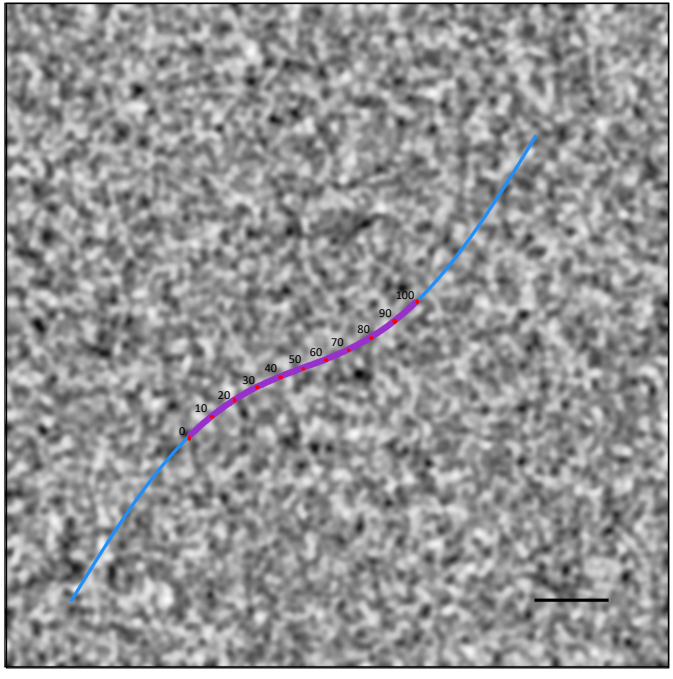


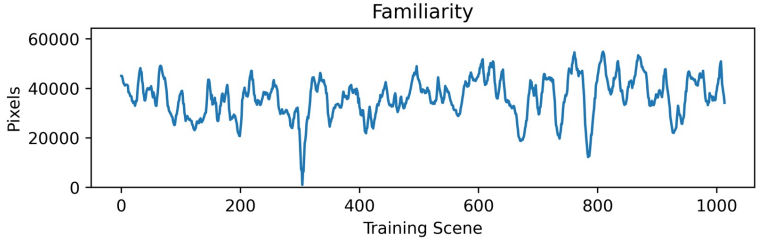


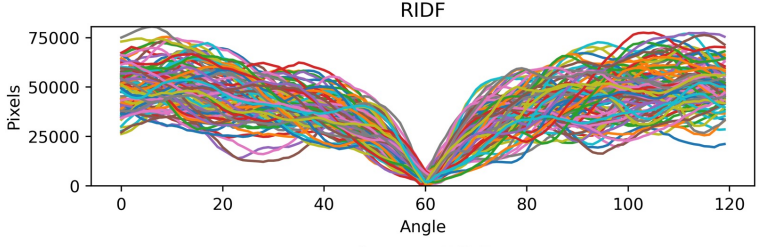
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

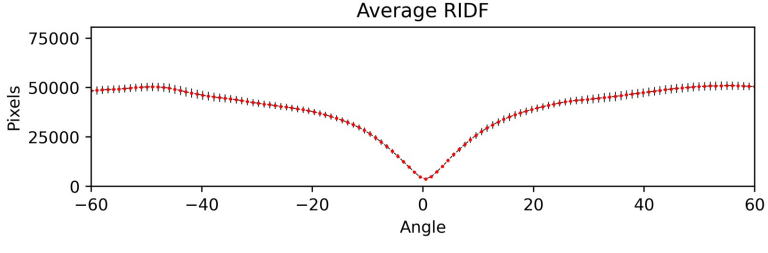
Navigation stats: RMSD error: 45.13; RMSD/dist: 0.113; TD: 32874; p90: 24; p50: 12; complete: 0

100%





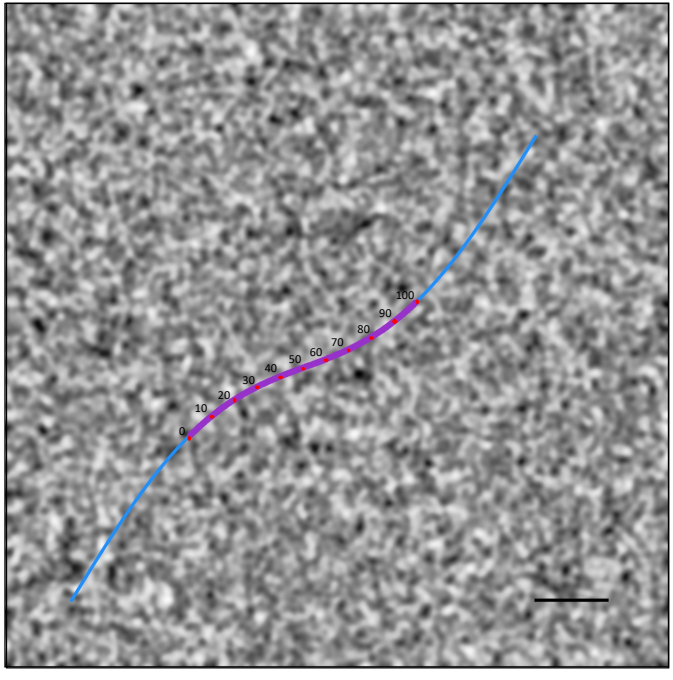


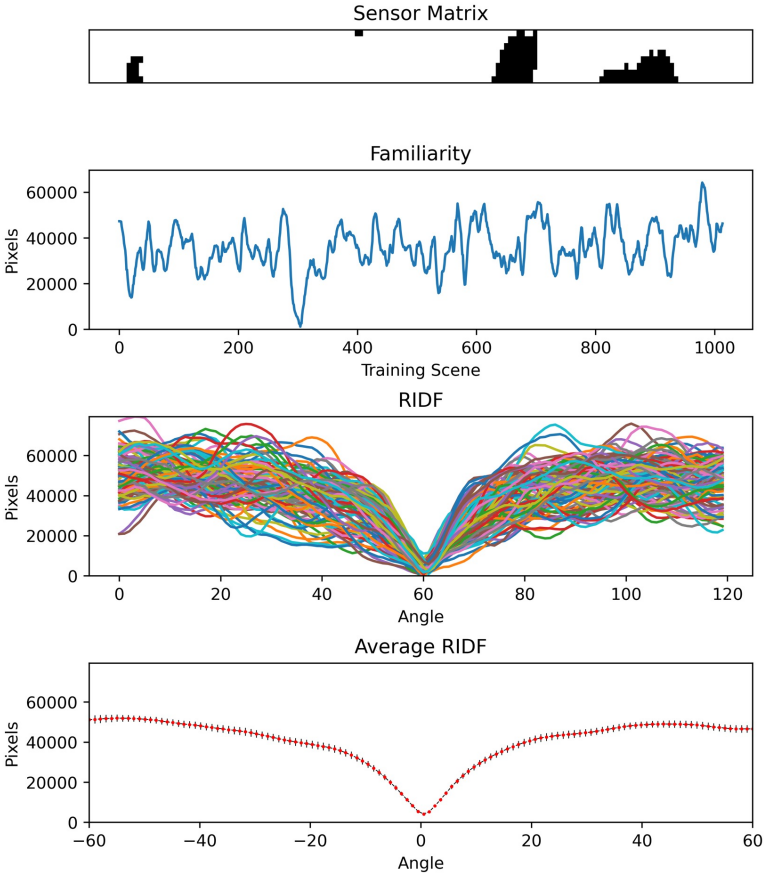


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 60.35; RMSD/dist: 0.151; TD: 32838; p90: 30; p50: 14; complete: 0

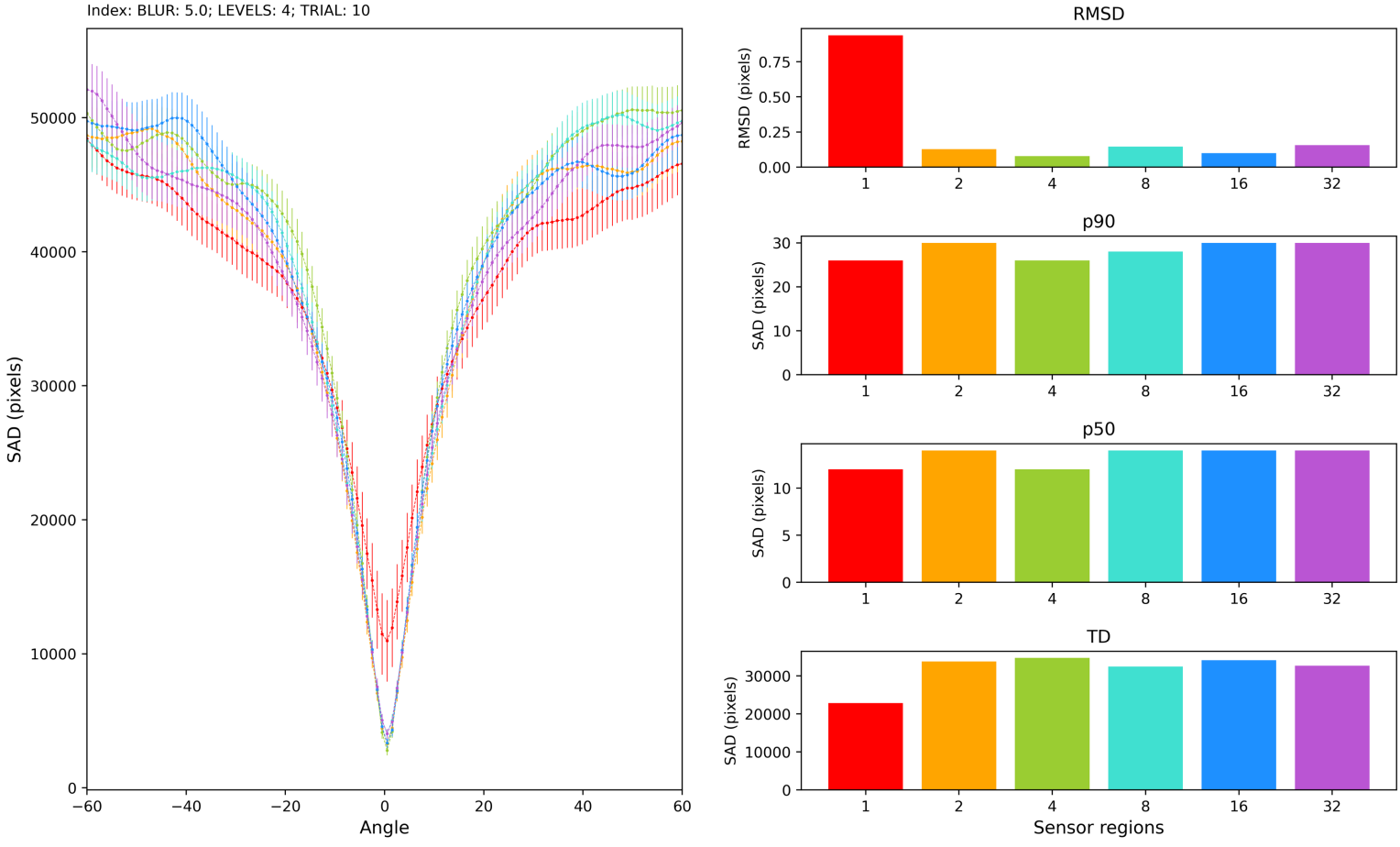
100%



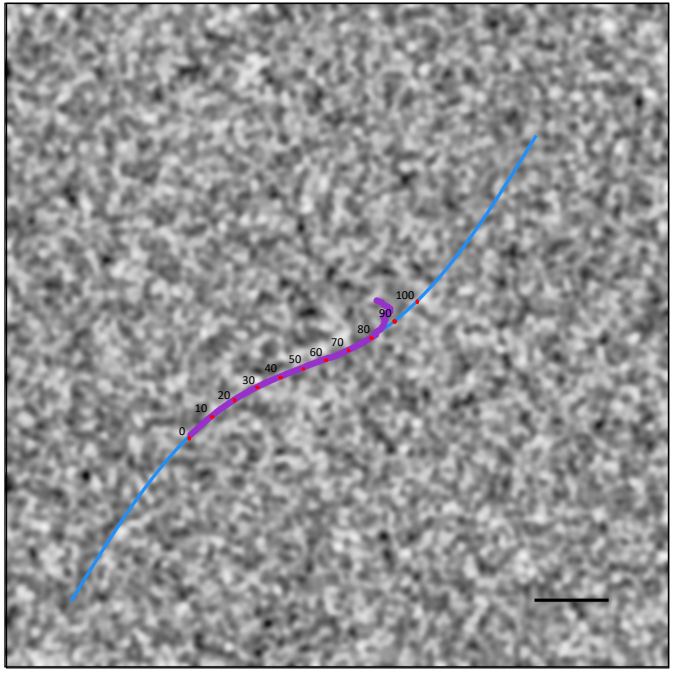


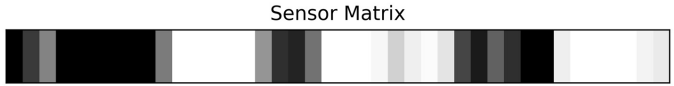
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

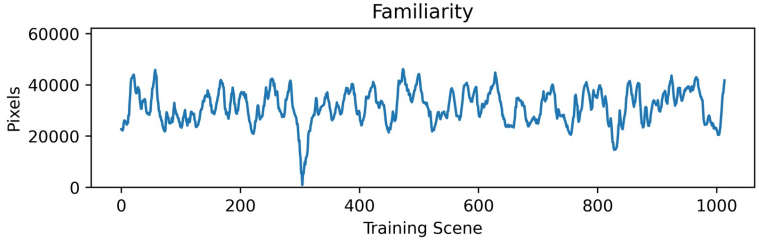
Navigation stats: RMSD error: 58.90; RMSD/dist: 0.147; TD: 33001; p90: 26; p50: 12; complete: 0

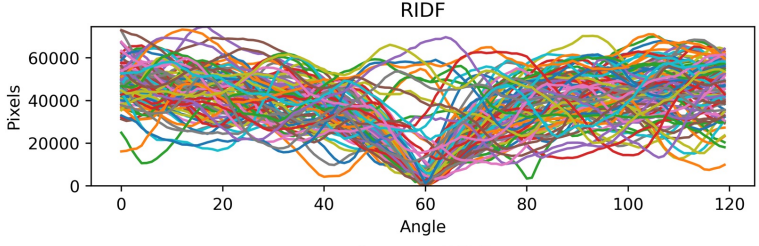

Index: BLUR: 5.0; LEVELS: 4; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

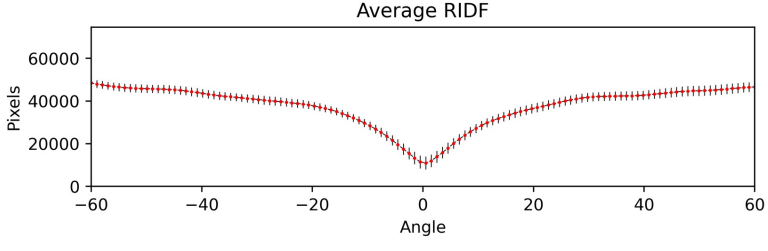
80%







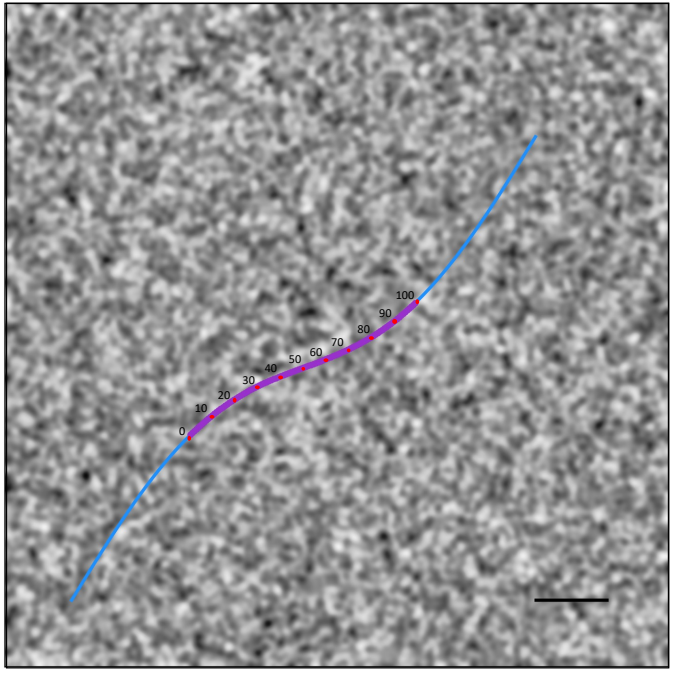


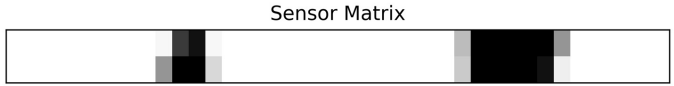


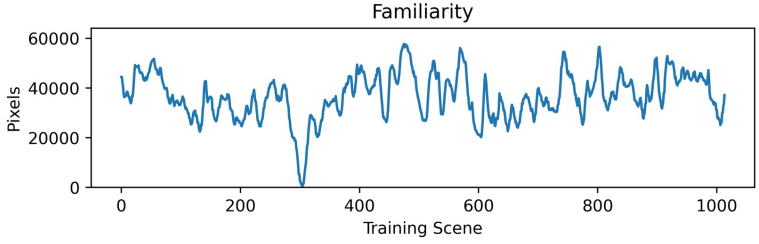
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

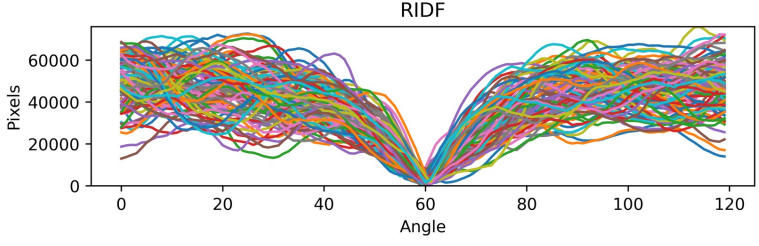
Navigation stats: RMSD error: 375.43; RMSD/dist: 0.939; TD: 22835; p90: 26; p50: 12; complete: 0

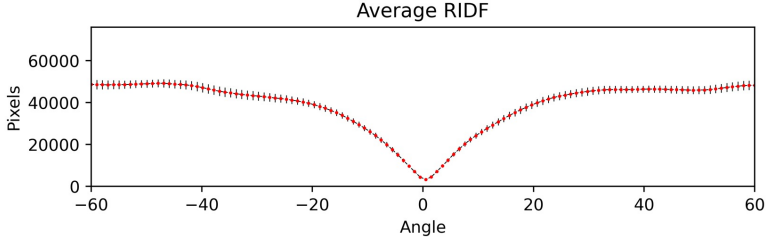
100%







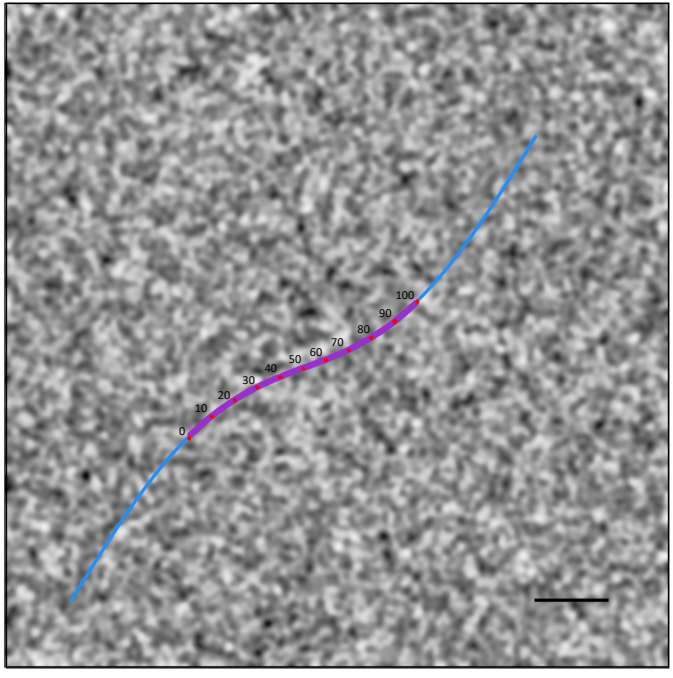


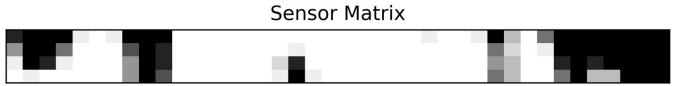


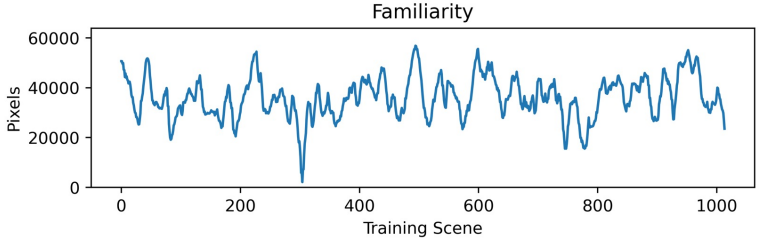
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

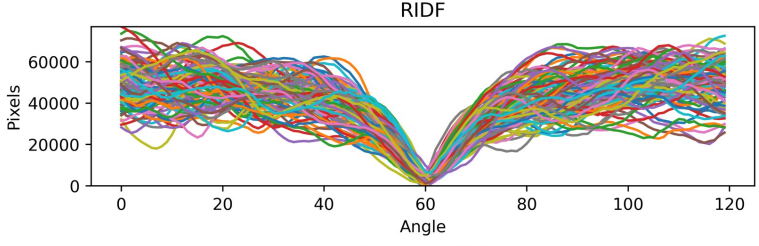
Navigation stats: RMSD error: 50.74; RMSD/dist: 0.127; TD: 33798; p90: 30; p50: 14; complete: 0

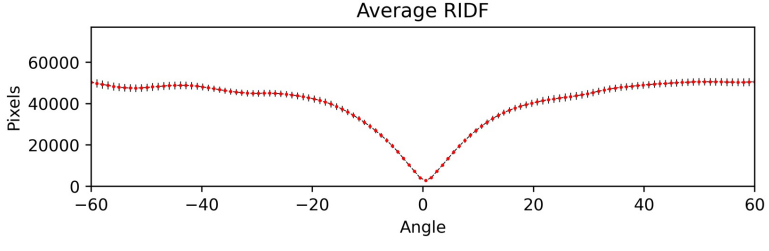
100%







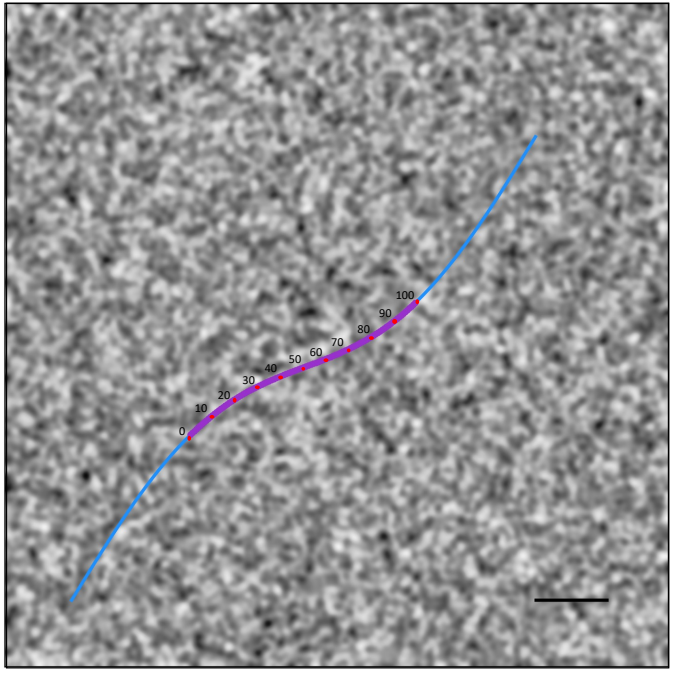


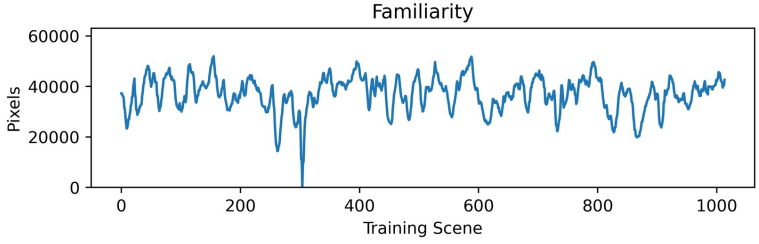


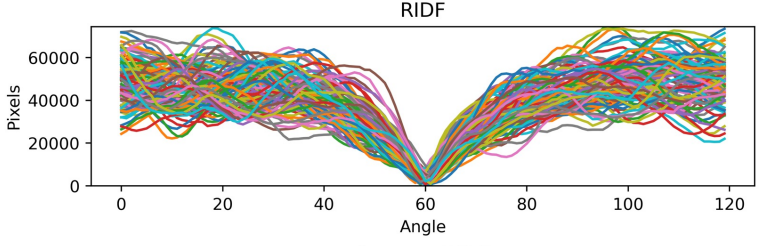
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

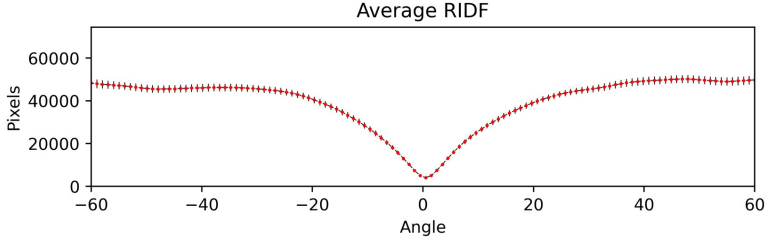
Navigation stats: RMSD error: 31.17; RMSD/dist: 0.078; TD: 34729; p90: 26; p50: 12; complete: 0

100%





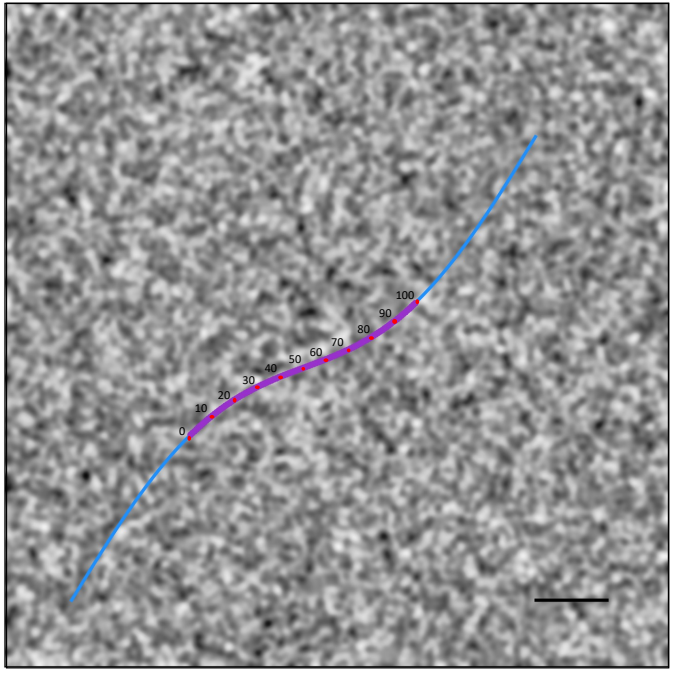


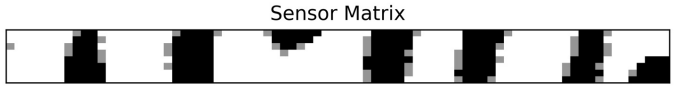


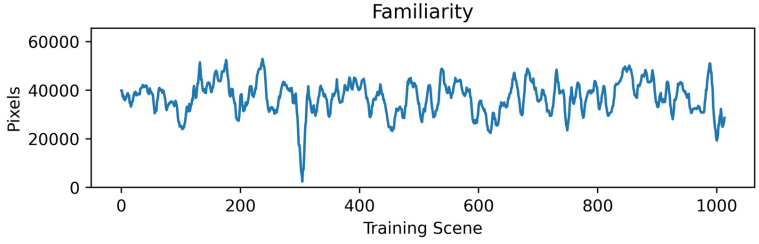
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

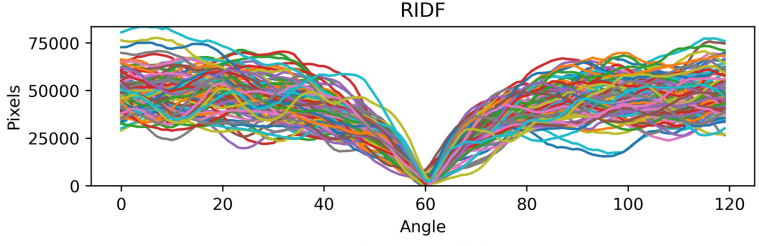
Navigation stats: RMSD error: 58.38; RMSD/dist: 0.146; TD: 32488; p90: 28; p50: 14; complete: 0

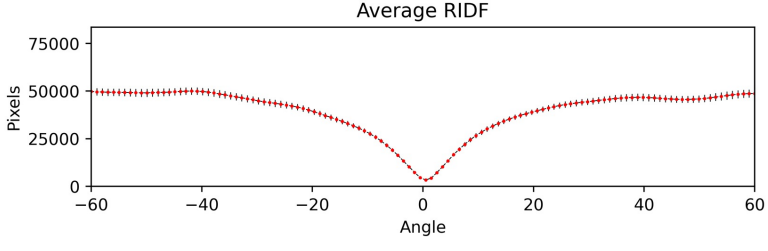
100%







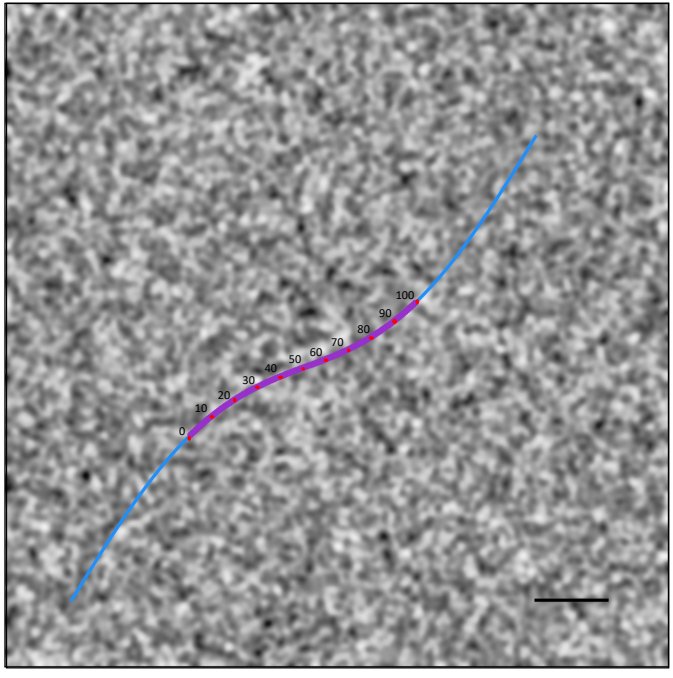


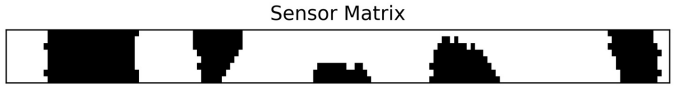


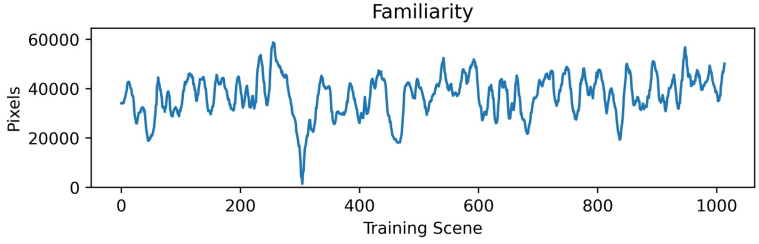
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

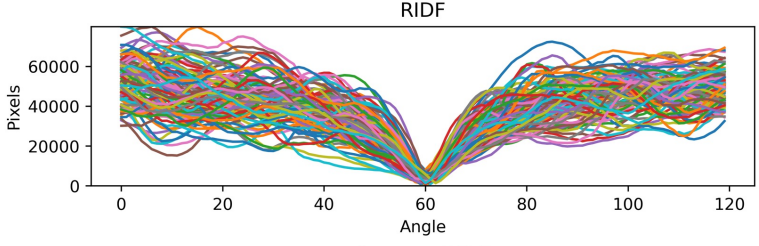
Navigation stats: RMSD error: 39.55; RMSD/dist: 0.099; TD: 34144; p90: 30; p50: 14; complete: 0

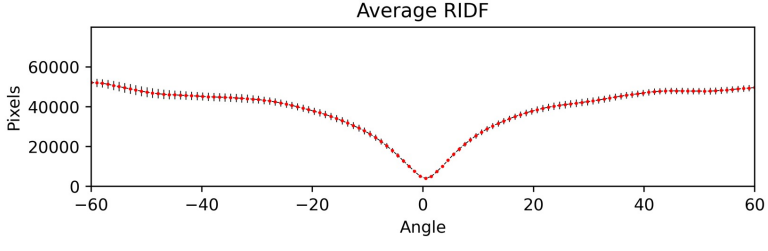
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 5; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 62.27; RMSD/dist: 0.156; TD: 32672; p90: 30; p50: 14; complete: 0