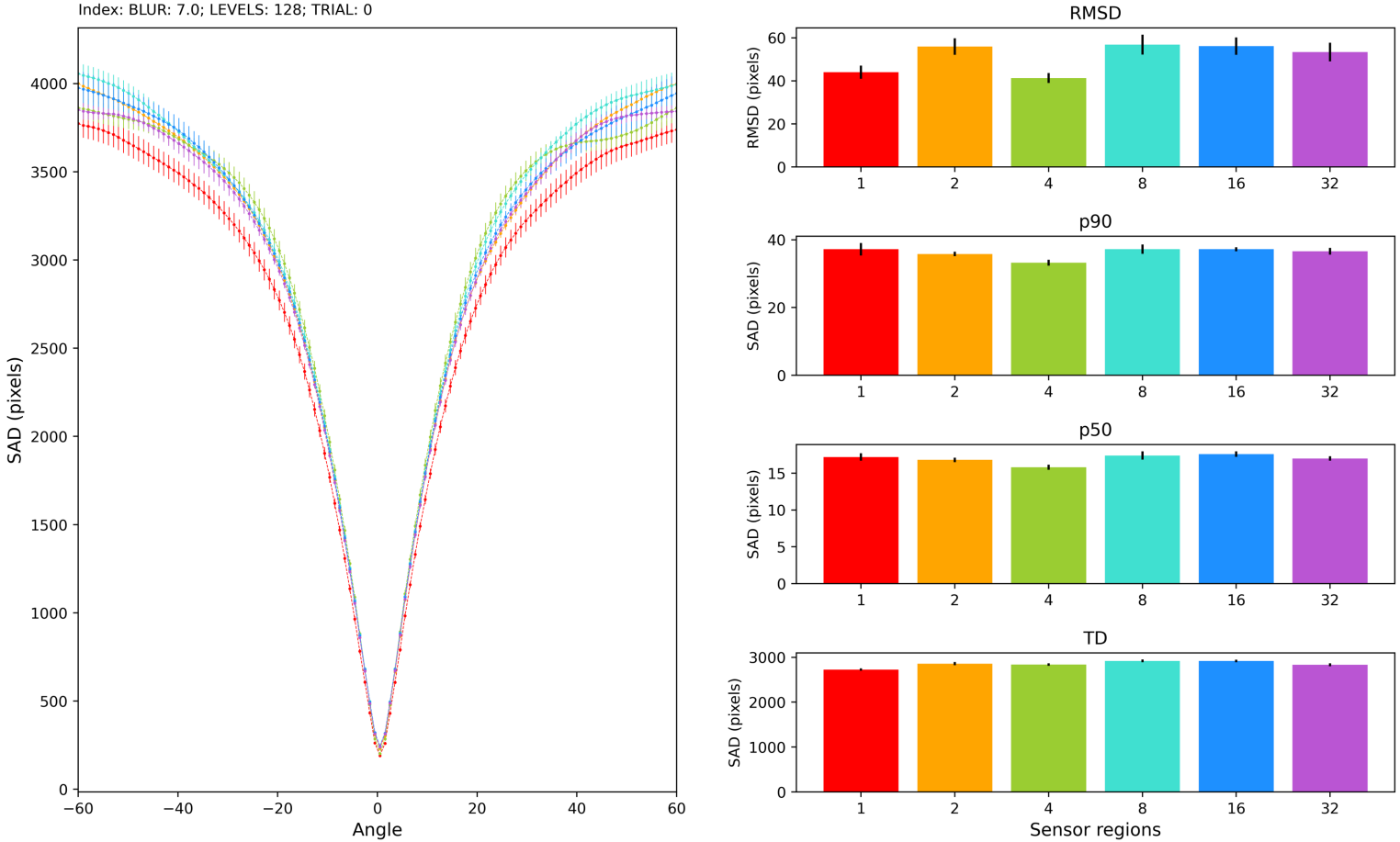
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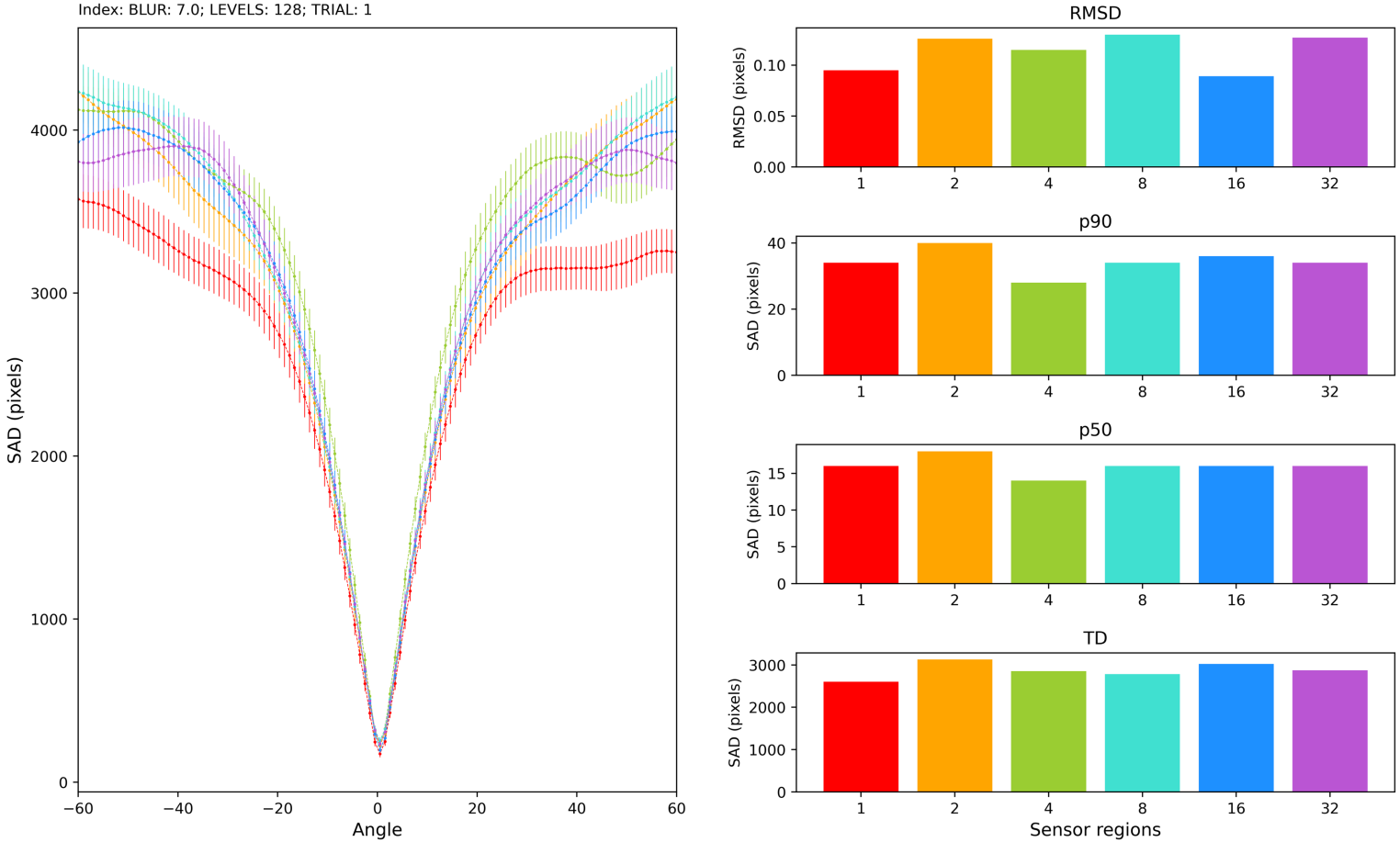
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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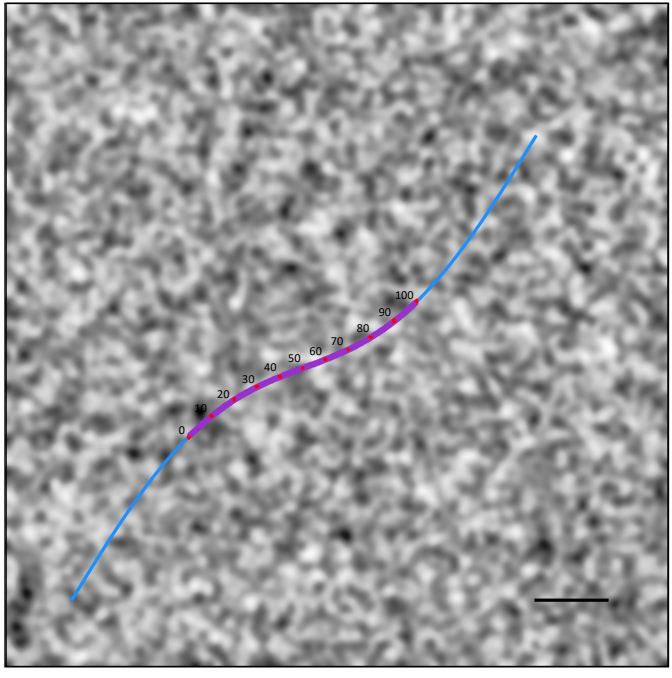
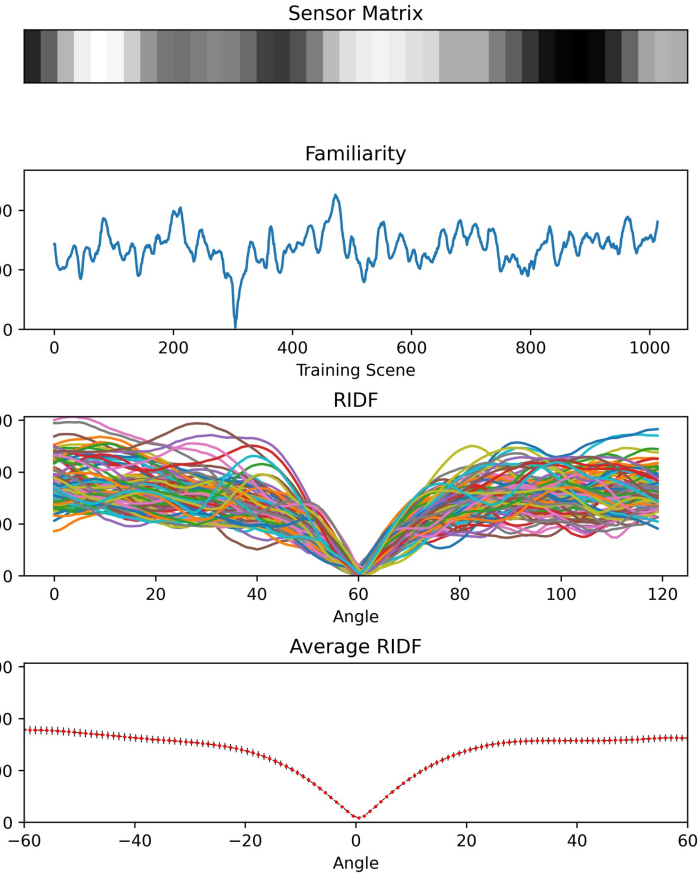
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

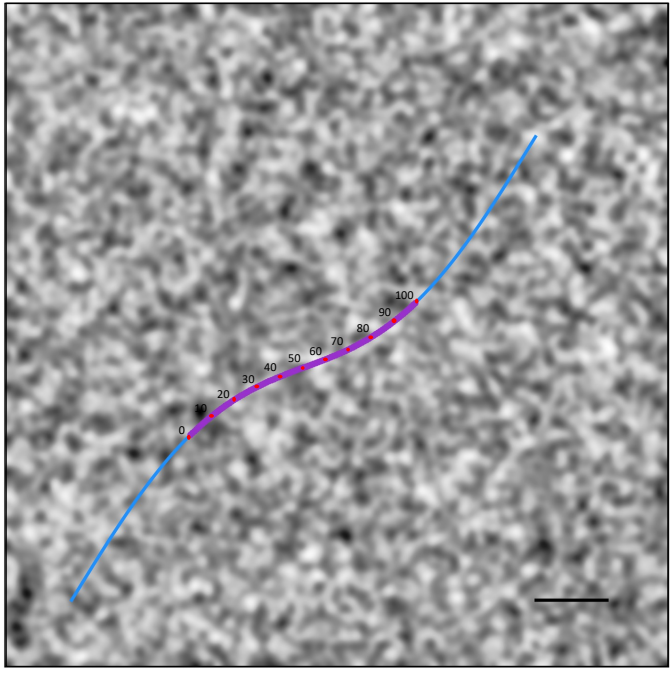


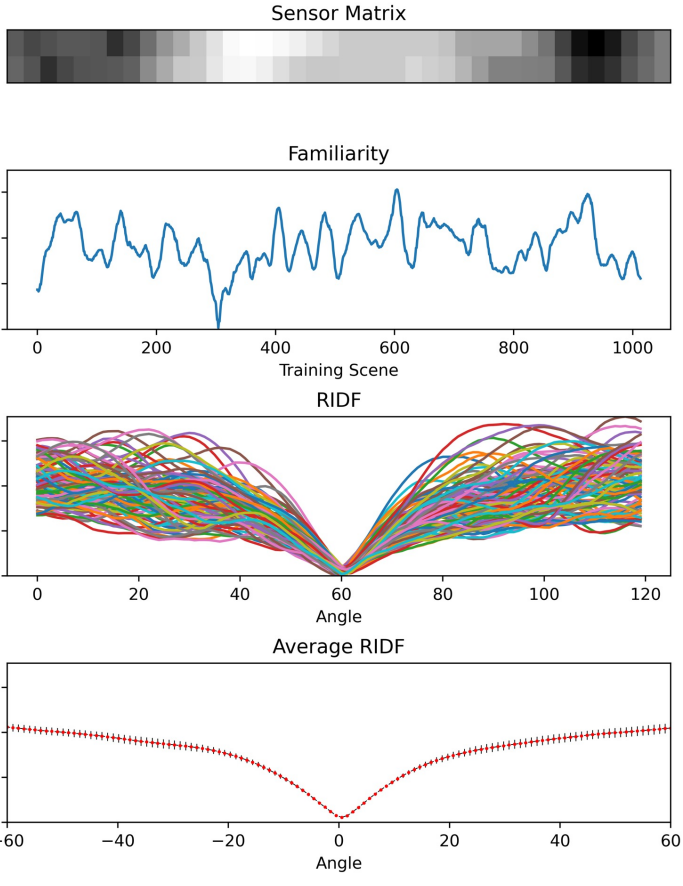




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 38.02; RMSD/dist: 0.095; TD: 2604; p90: 34; p50: 16; complete: 0

100%

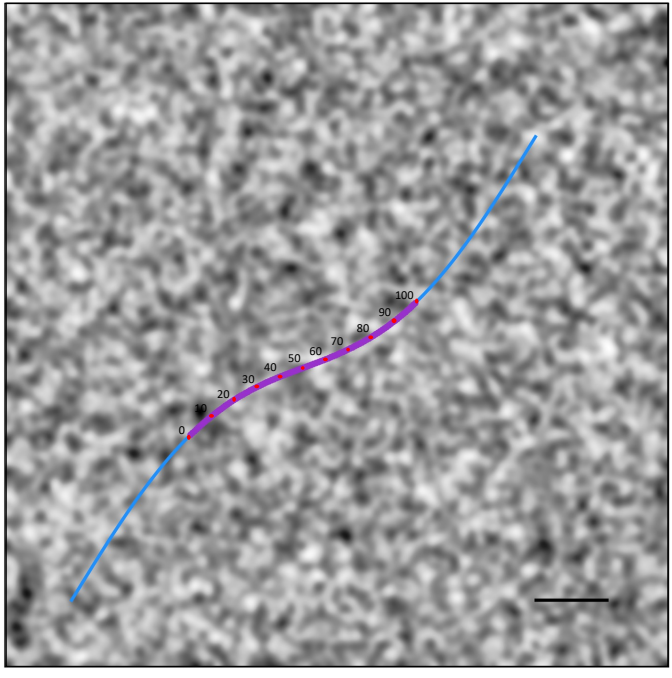


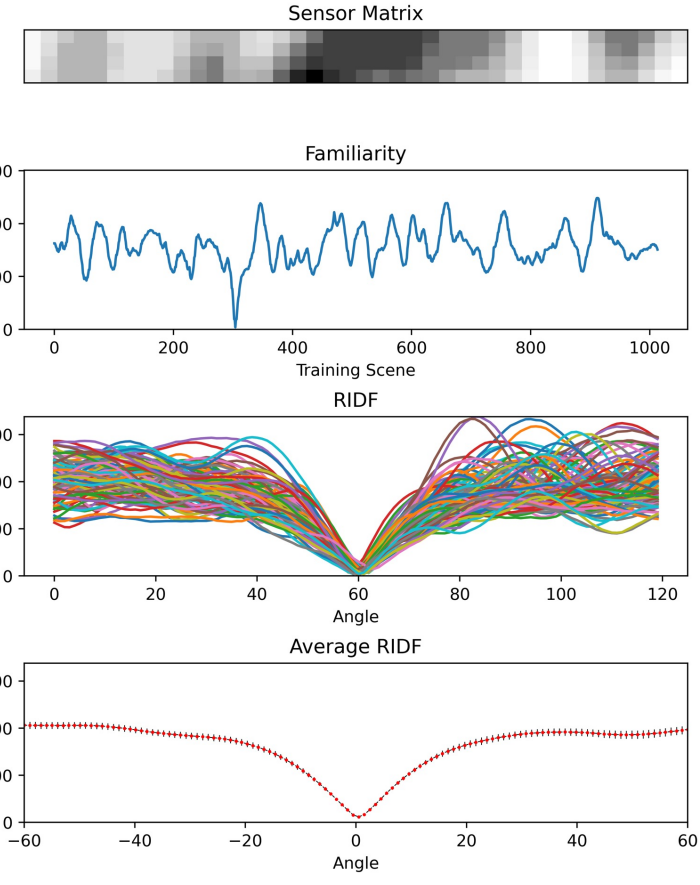




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 50.21; RMSD/dist: 0.126; TD: 3126; p90: 40; p50: 18; complete: 0

100%

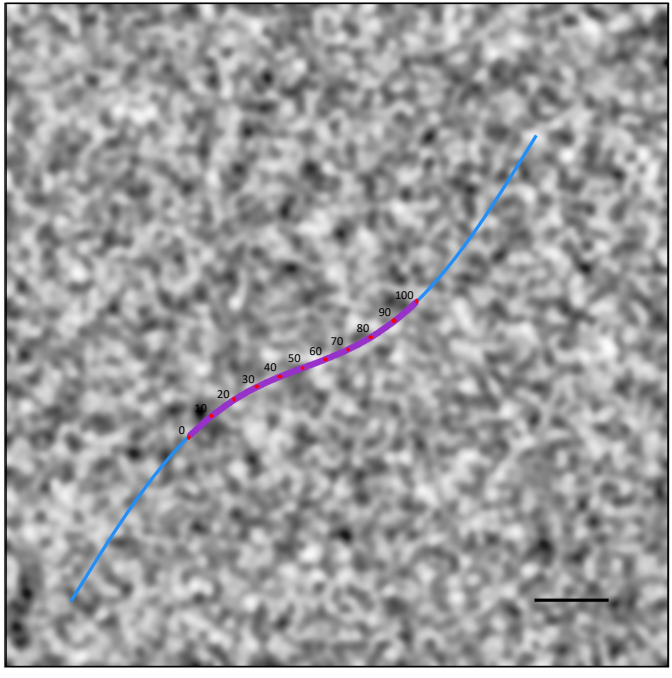


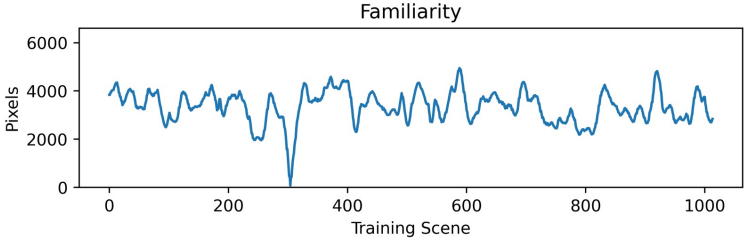



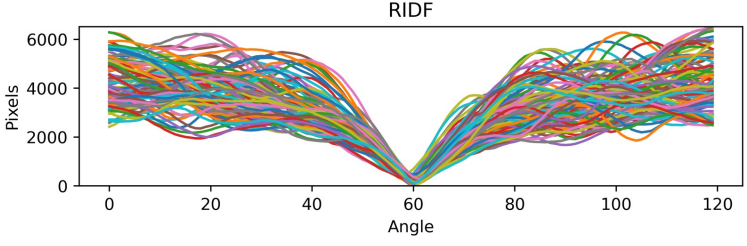

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

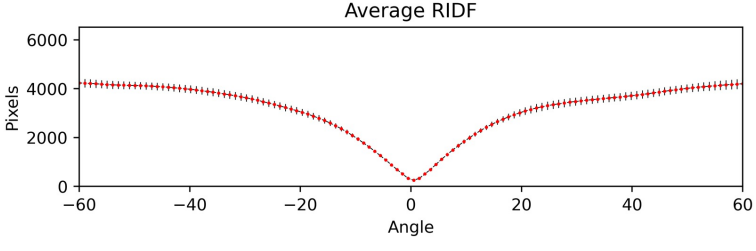
Navigation stats: RMSD error: 46.05; RMSD/dist: 0.115; TD: 2851; p90: 28; p50: 14; complete: 0

100%





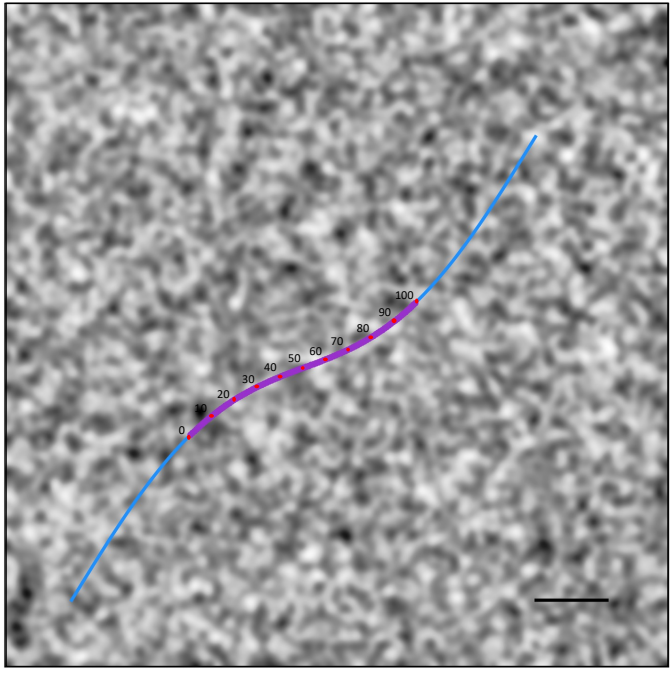



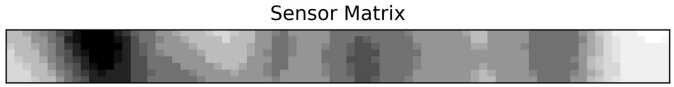



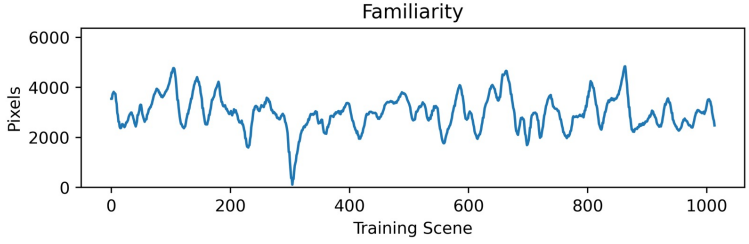

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

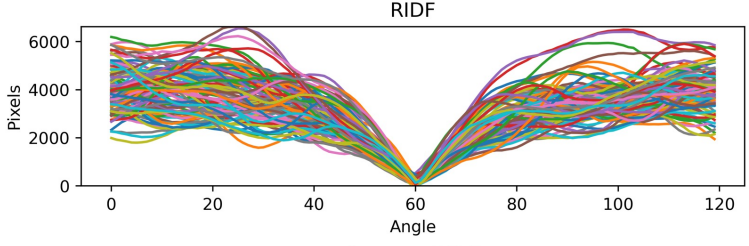
Navigation stats: RMSD error: 52.18; RMSD/dist: 0.130; TD: 2785; p90: 34; p50: 16; complete: 0

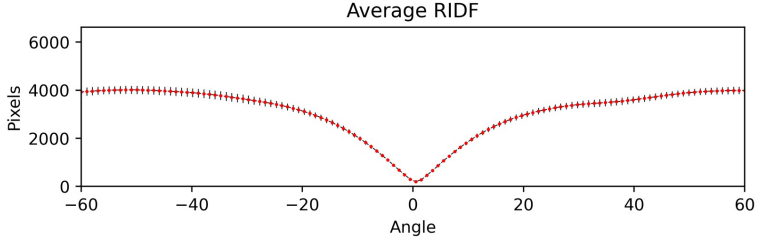
100%



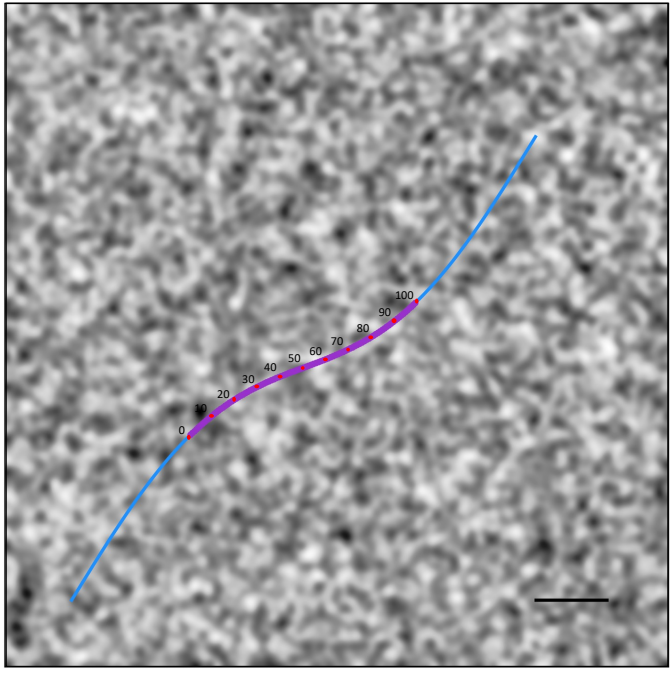



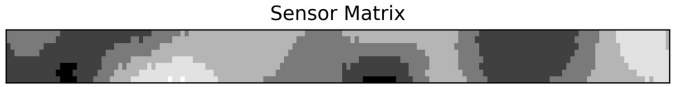



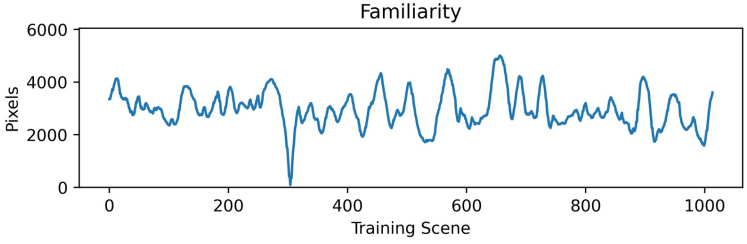

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

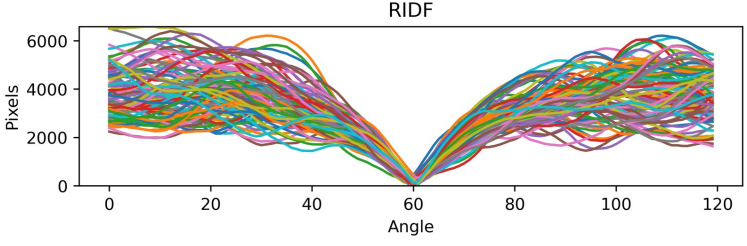
Navigation stats: RMSD error: 35.70; RMSD/dist: 0.089; TD: 3021; p90: 36; p50: 16; complete: 0

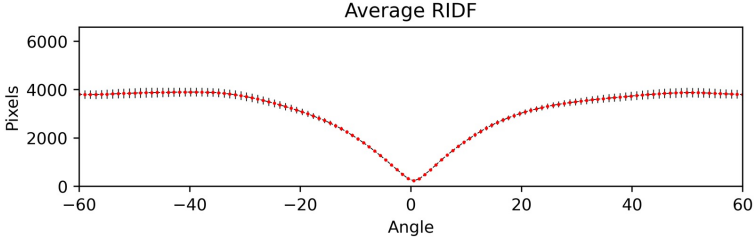
100%



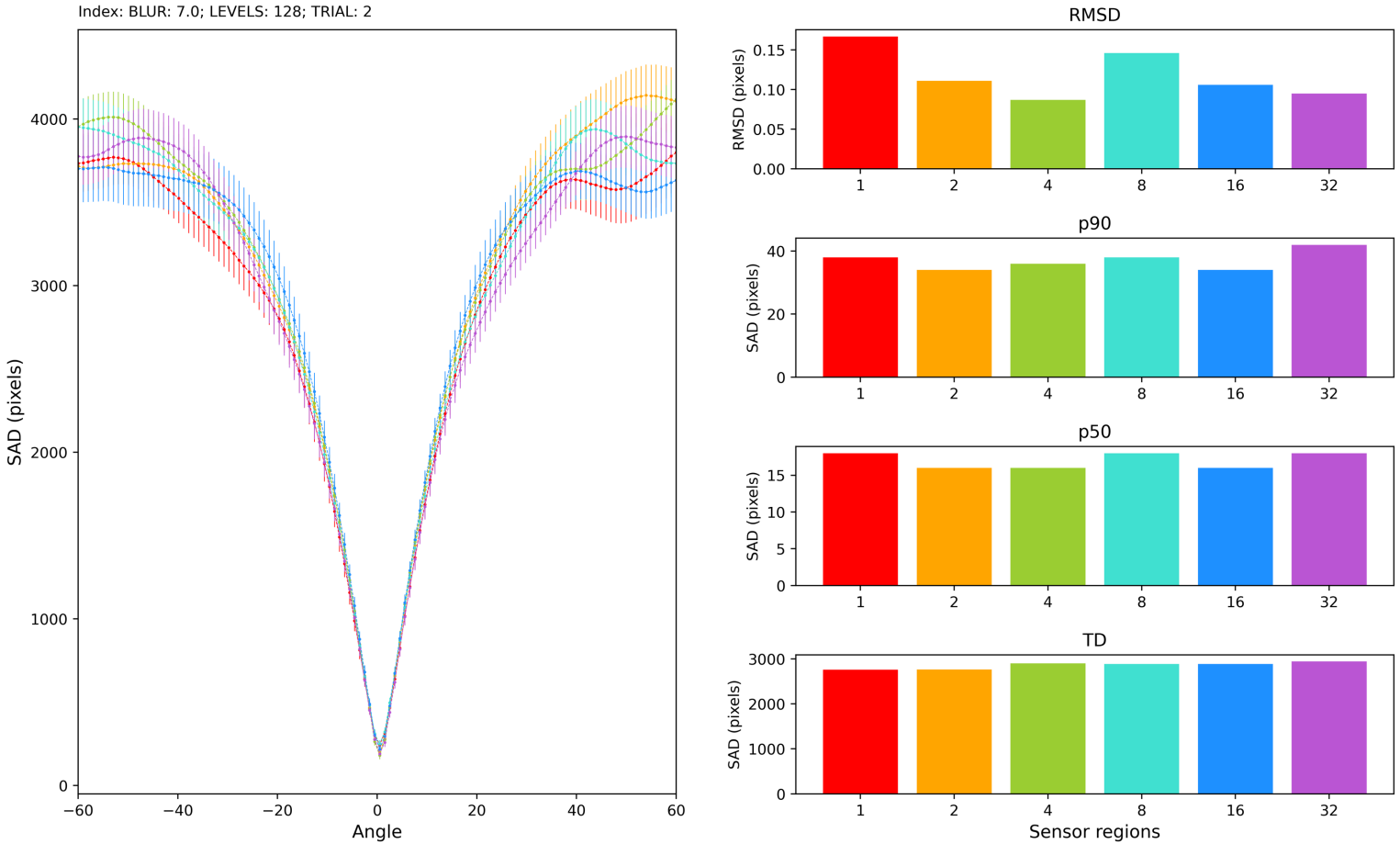



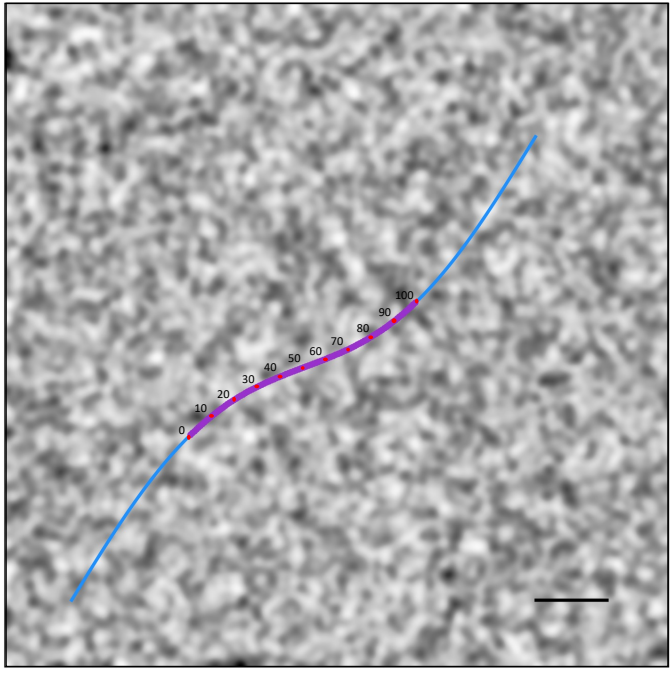



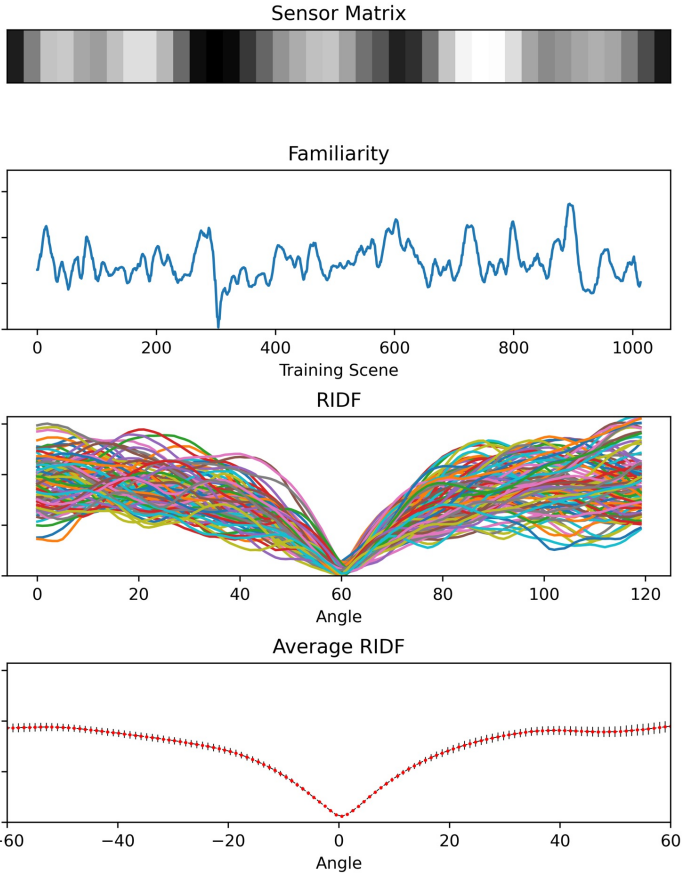

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 50.72; RMSD/dist: 0.127; TD: 2871; p90: 34; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 128; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

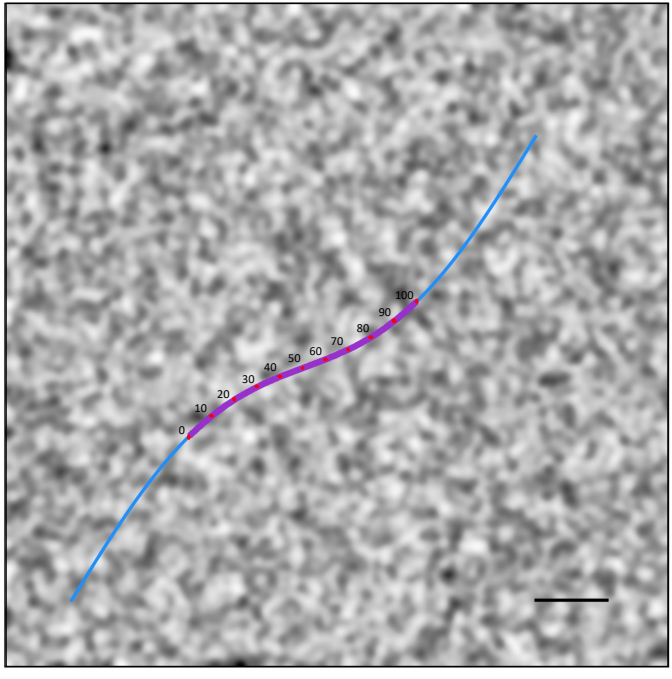


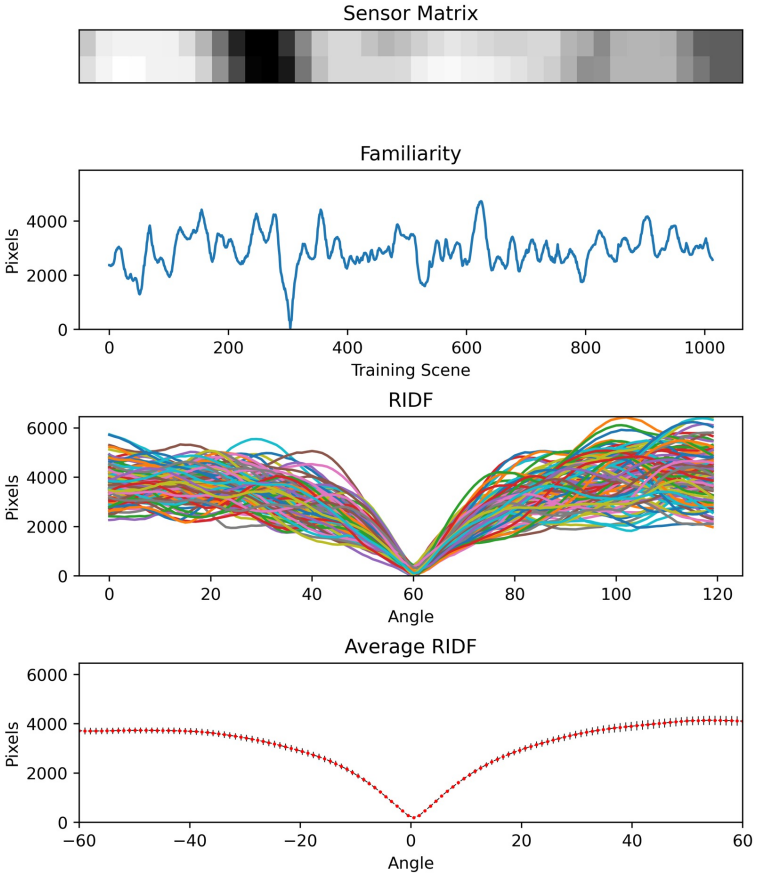




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 66.88; RMSD/dist: 0.167; TD: 2762; p90: 38; p50: 18; complete: 0

100%

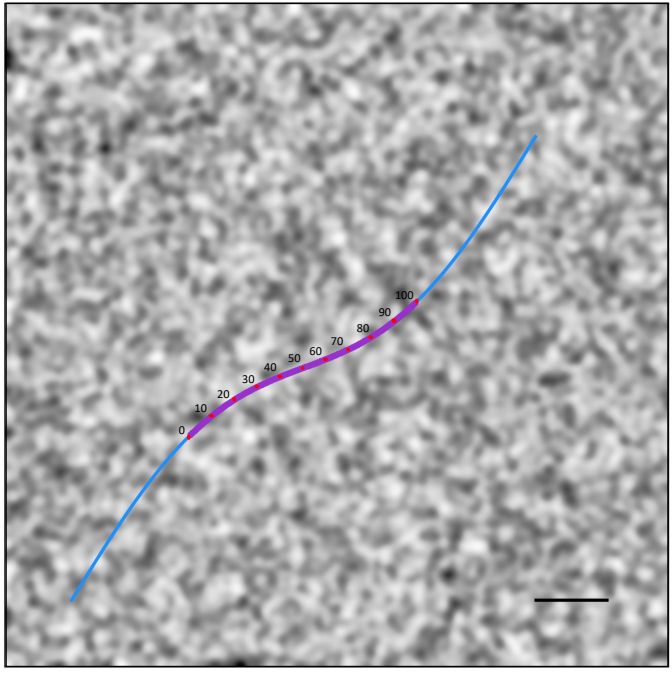


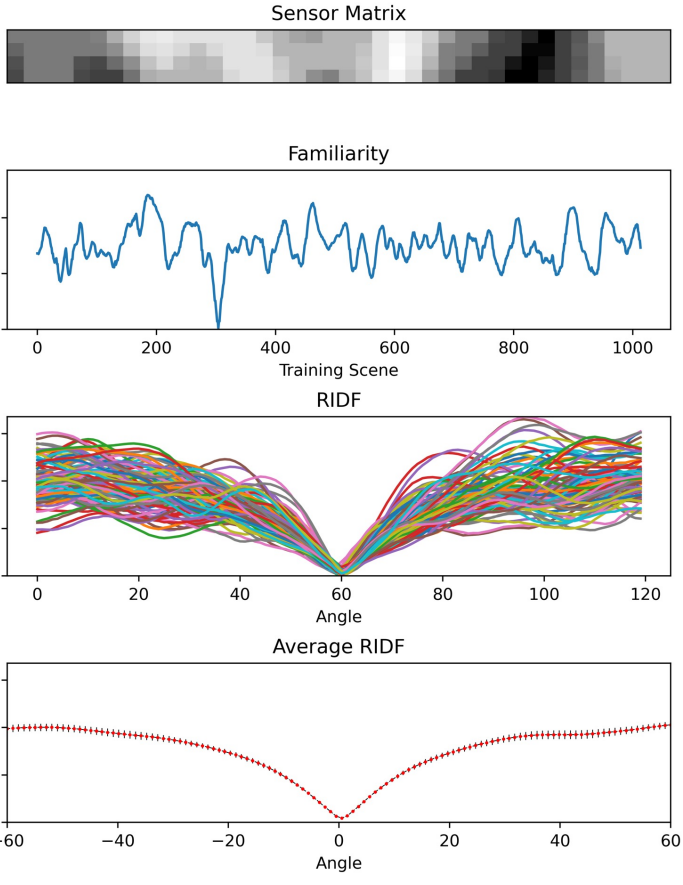




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 44.28; RMSD/dist: 0.111; TD: 2767; p90: 34; p50: 16; complete: 0

100%

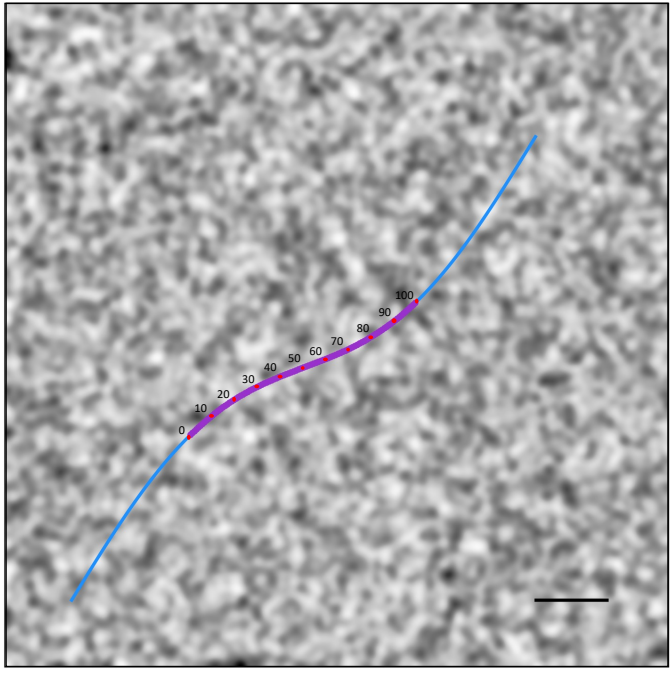


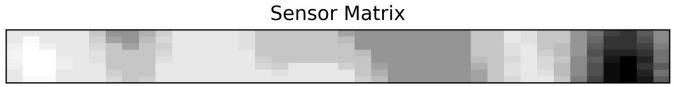



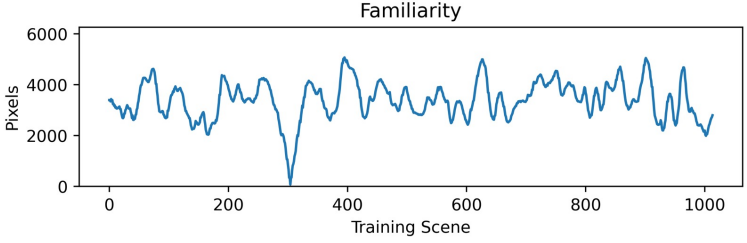

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

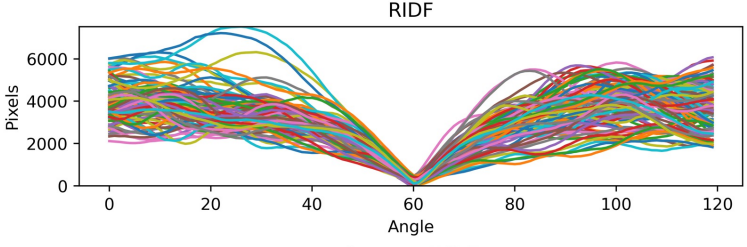
Navigation stats: RMSD error: 34.83; RMSD/dist: 0.087; TD: 2900; p90: 36; p50: 16; complete: 0

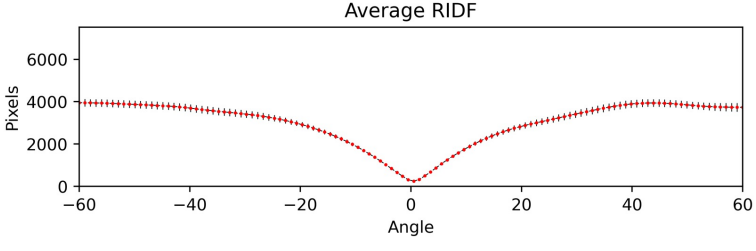
100%



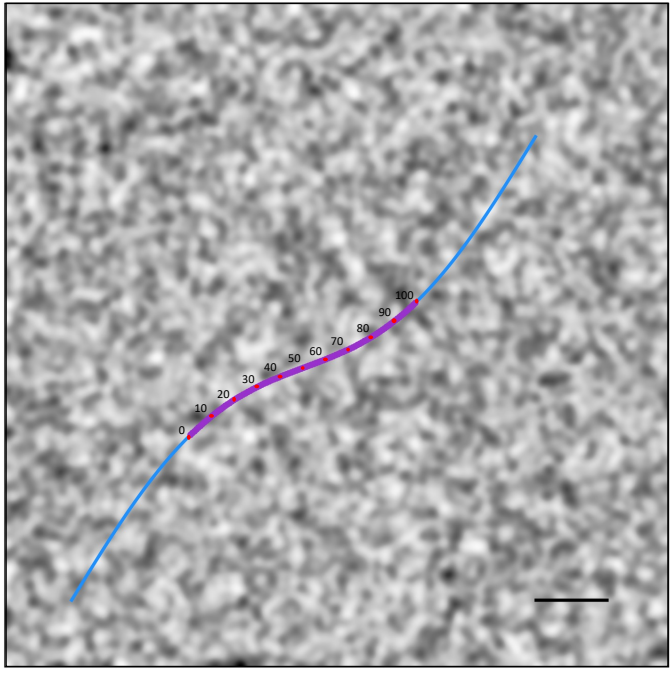



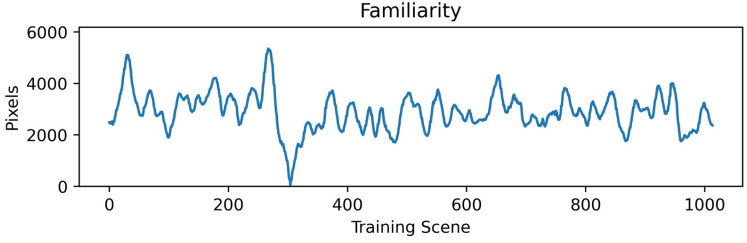



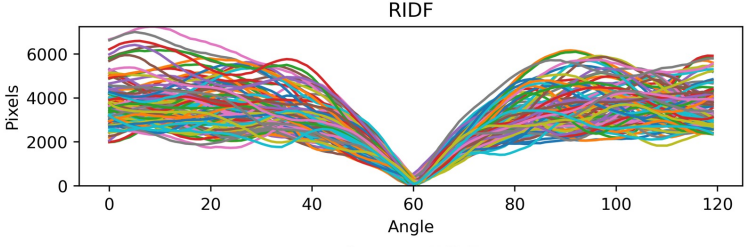

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

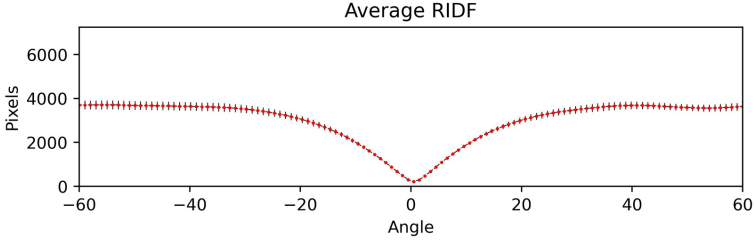
Navigation stats: RMSD error: 58.50; RMSD/dist: 0.146; TD: 2890; p90: 38; p50: 18; complete: 0

100%





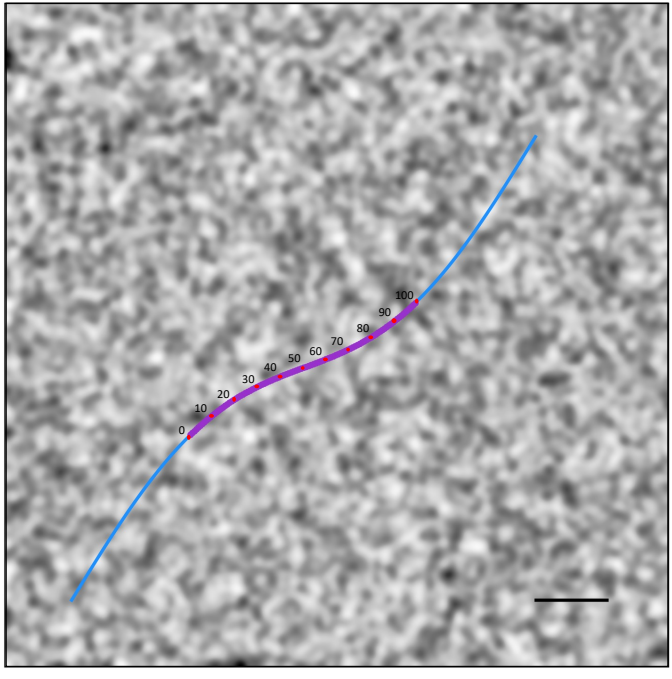



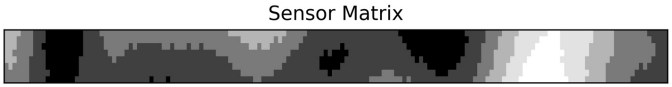



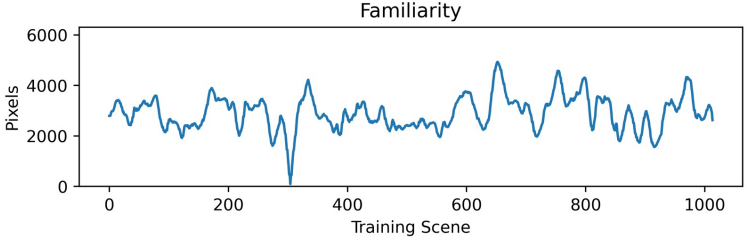

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

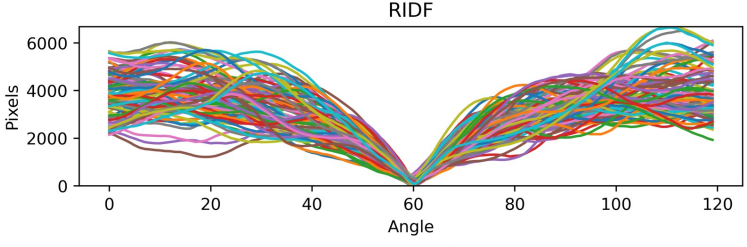
Navigation stats: RMSD error: 42.30; RMSD/dist: 0.106; TD: 2888; p90: 34; p50: 16; complete: 0

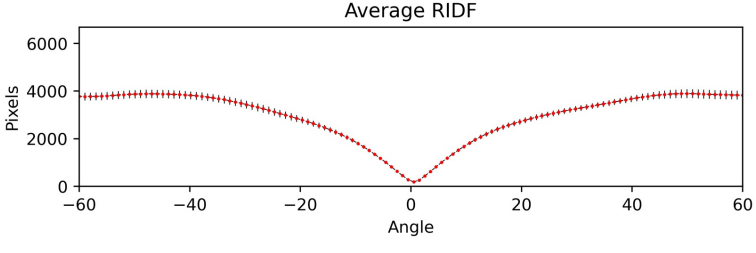
100%



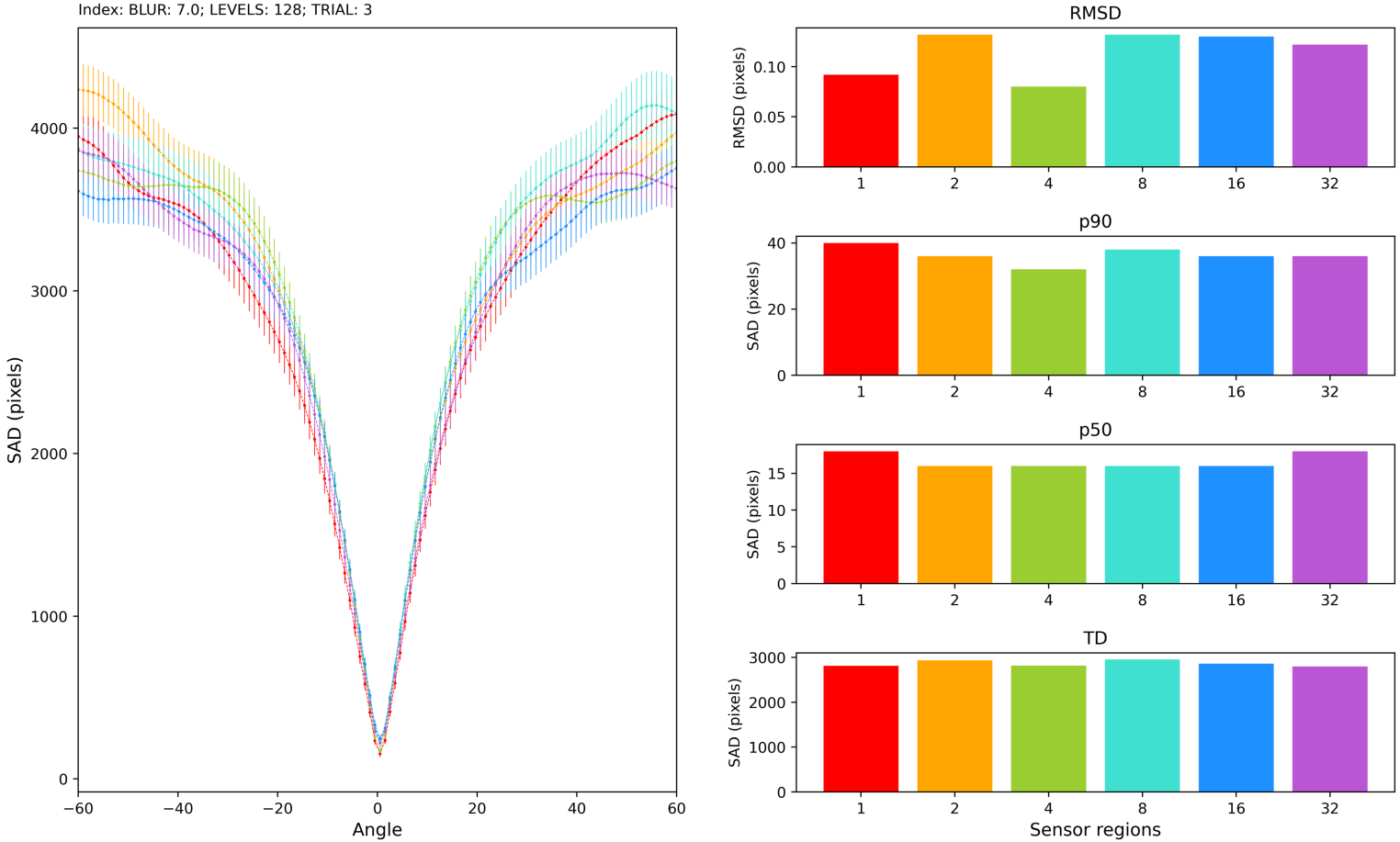



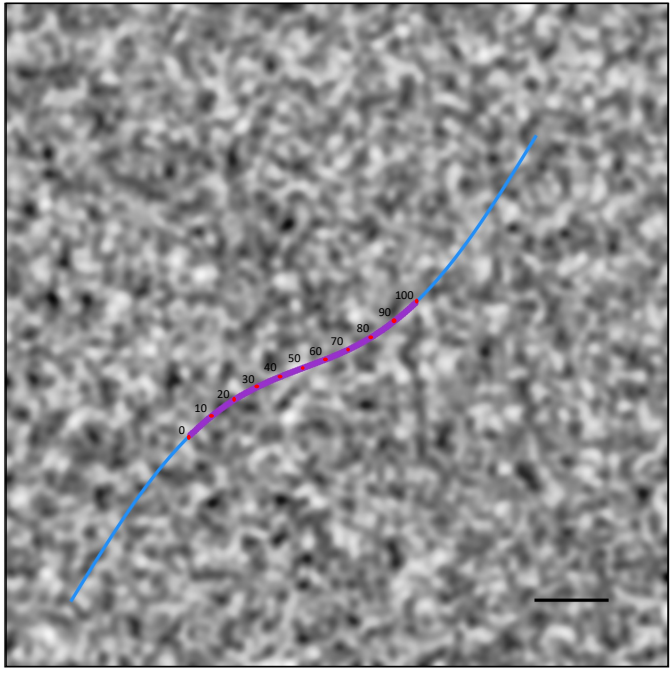



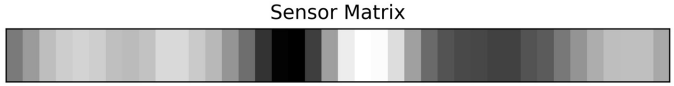

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

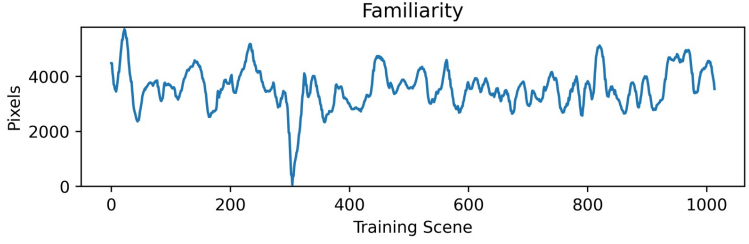
Navigation stats: RMSD error: 38.12; RMSD/dist: 0.095; TD: 2942; p90: 42; p50: 18; complete: 0

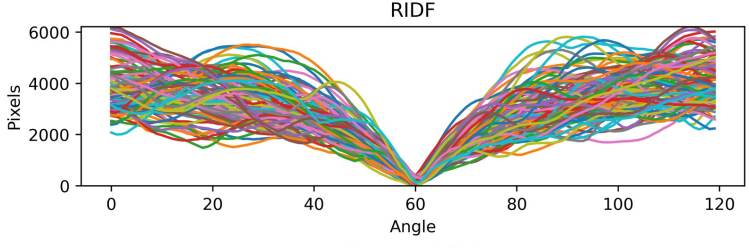

Index: BLUR: 7.0; LEVELS: 128; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

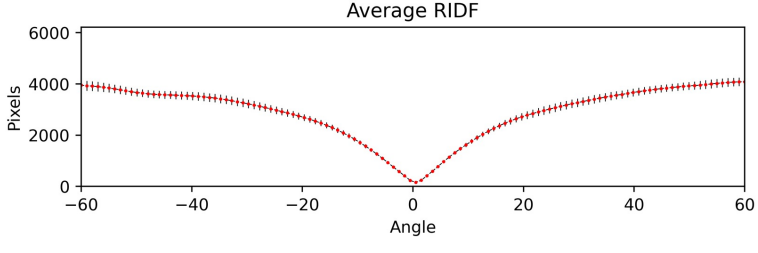
100%



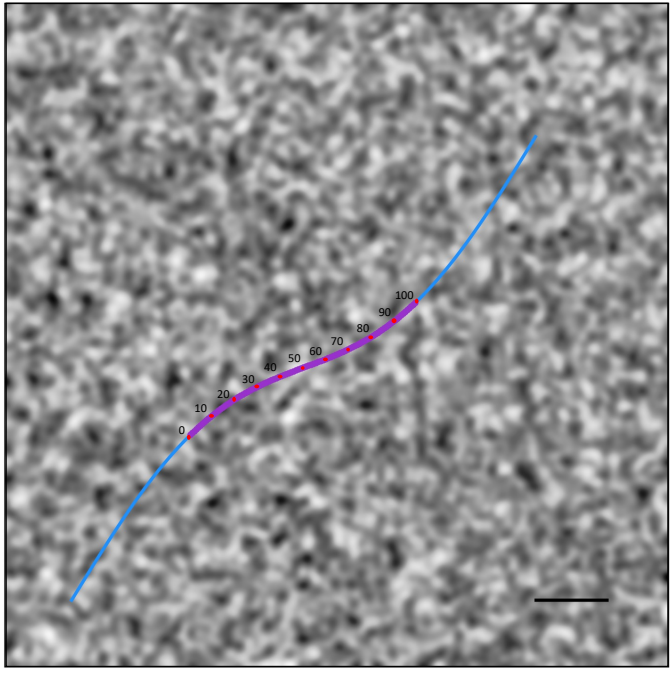



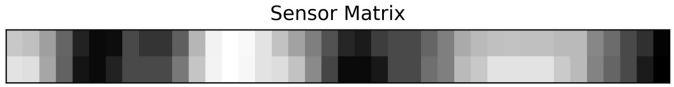



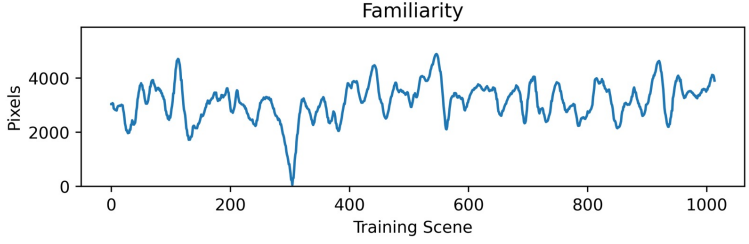

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

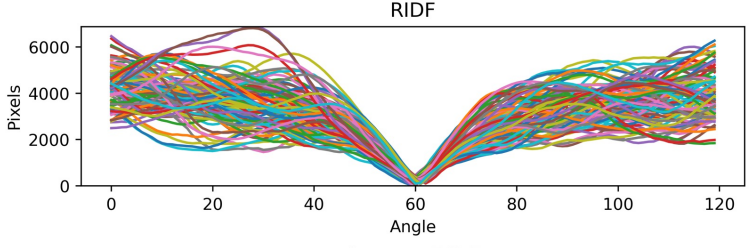
Navigation stats: RMSD error: 36.69; RMSD/dist: 0.092; TD: 2810; p90: 40; p50: 18; complete: 0

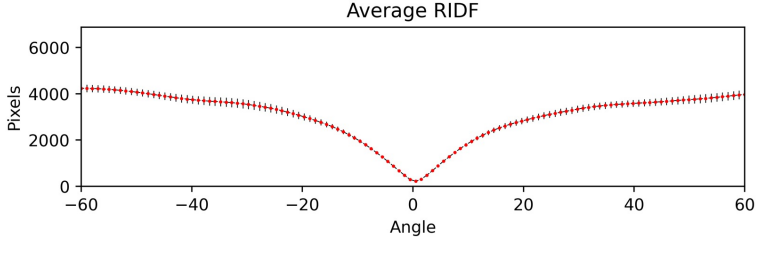
100%



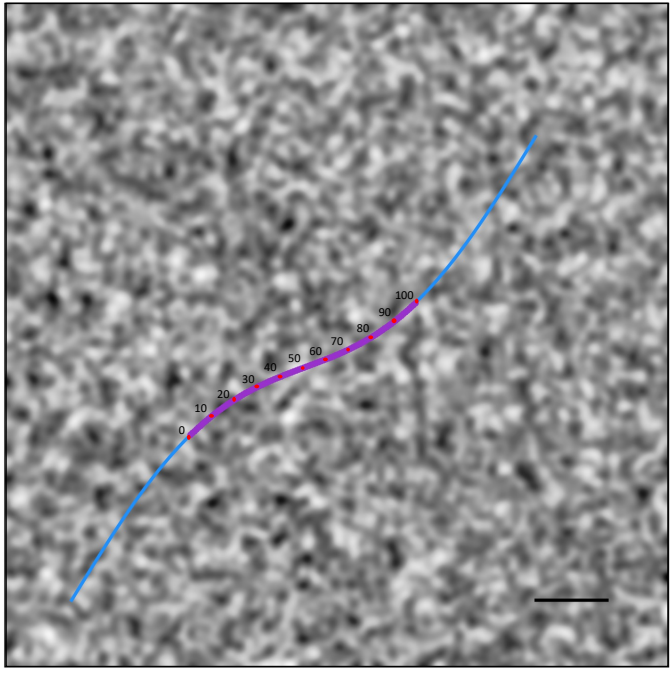



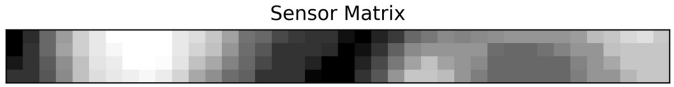



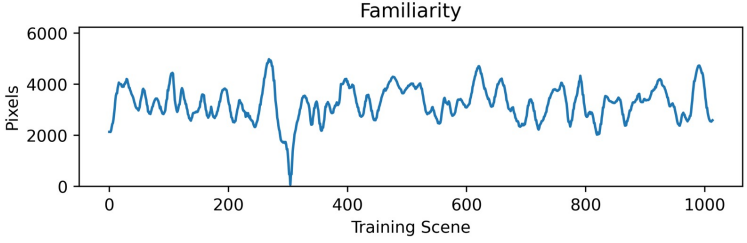

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

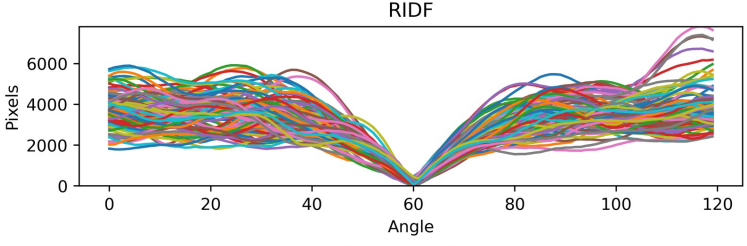
Navigation stats: RMSD error: 52.62; RMSD/dist: 0.132; TD: 2935; p90: 36; p50: 16; complete: 0

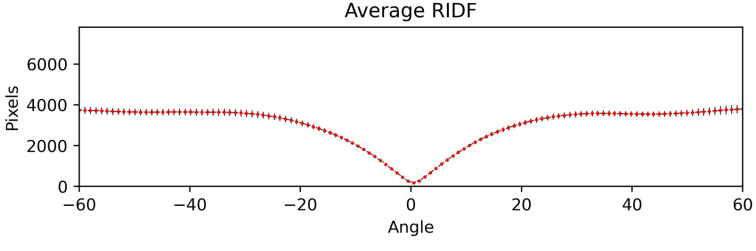
100%



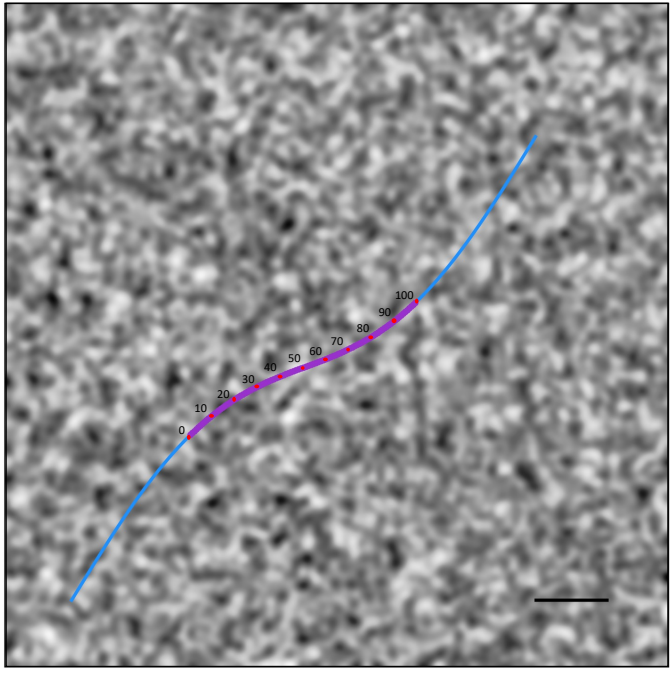



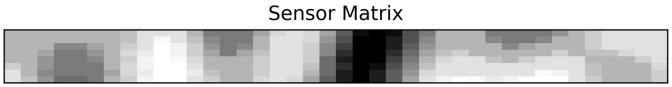



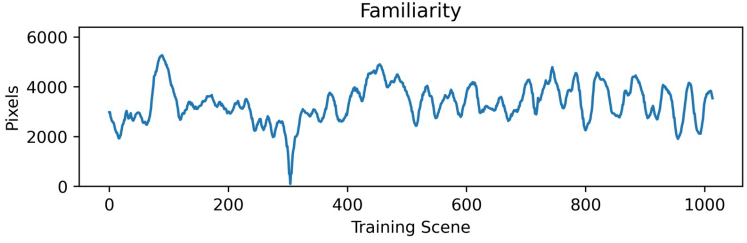

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

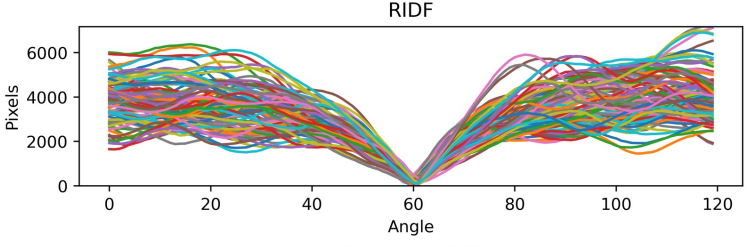
Navigation stats: RMSD error: 32.06; RMSD/dist: 0.080; TD: 2816; p90: 32; p50: 16; complete: 0

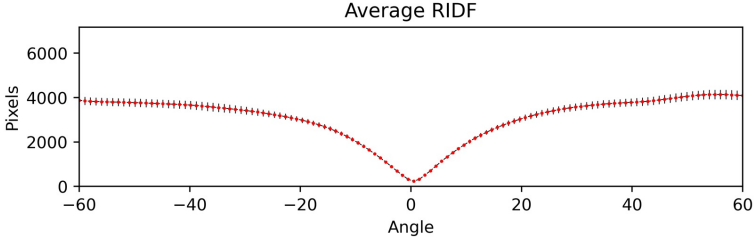
100%



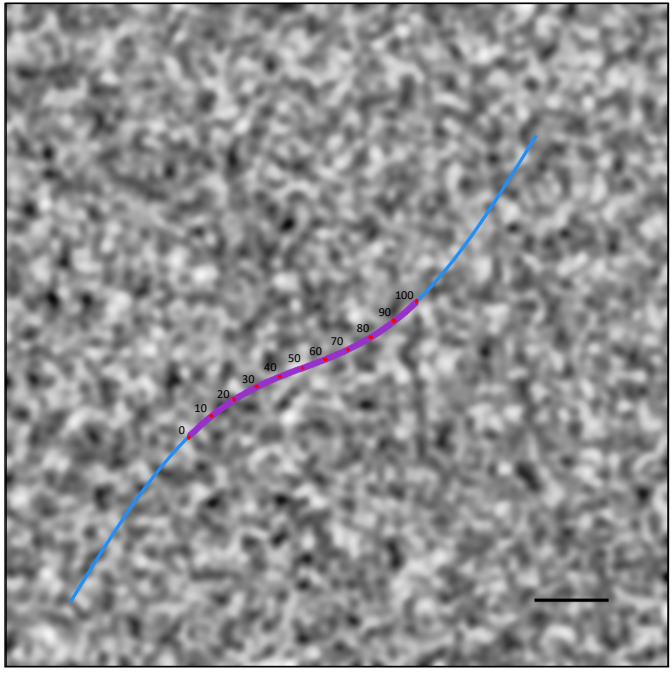



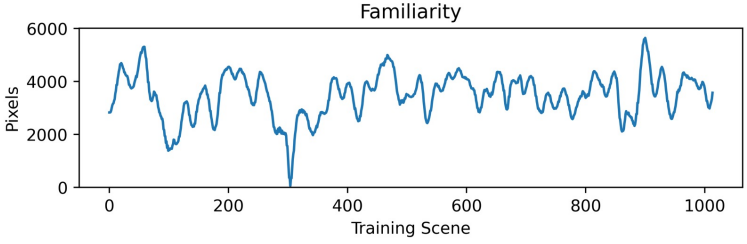



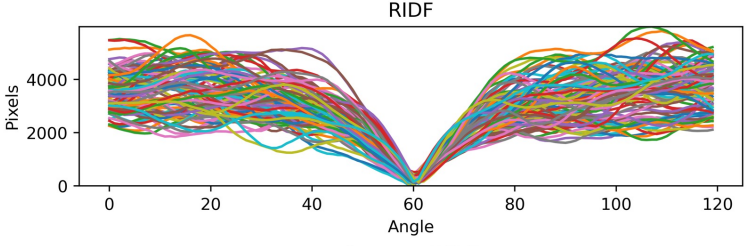

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

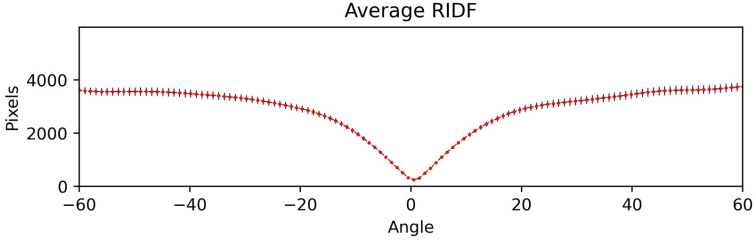
Navigation stats: RMSD error: 52.66; RMSD/dist: 0.132; TD: 2951; p90: 38; p50: 16; complete: 0

100%





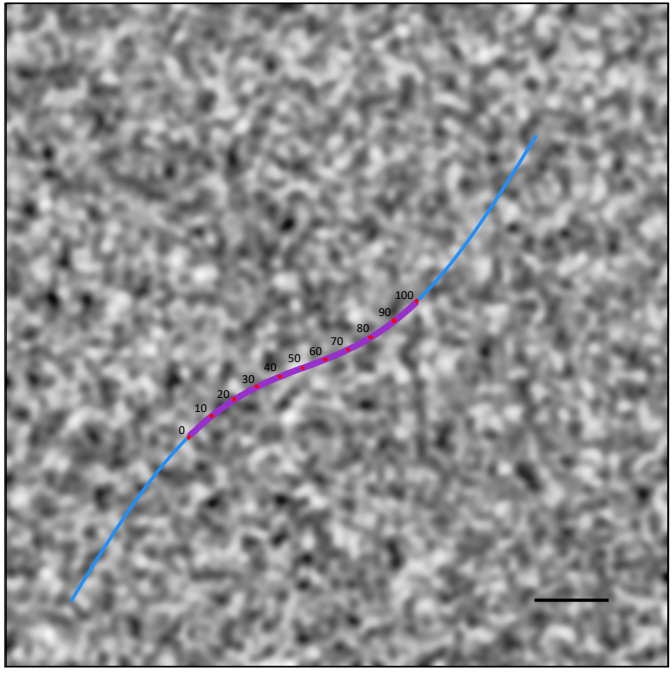



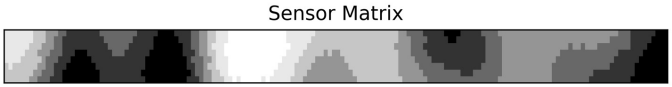



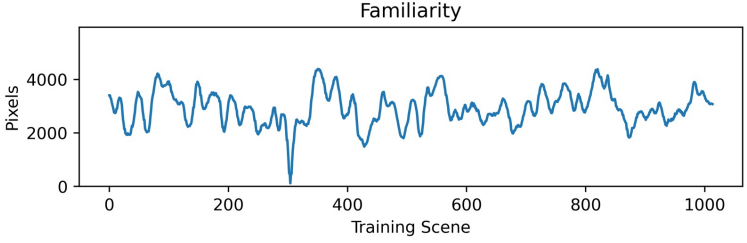

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

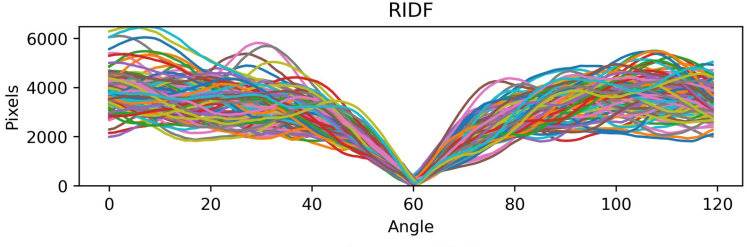
Navigation stats: RMSD error: 52.08; RMSD/dist: 0.130; TD: 2859; p90: 36; p50: 16; complete: 0

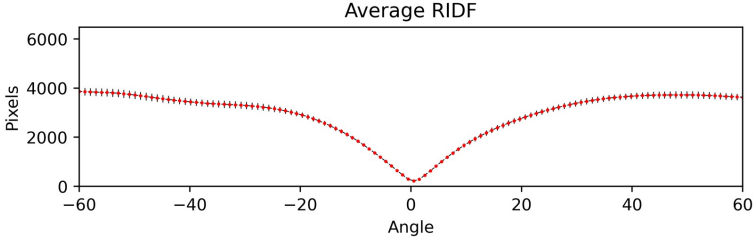
100%



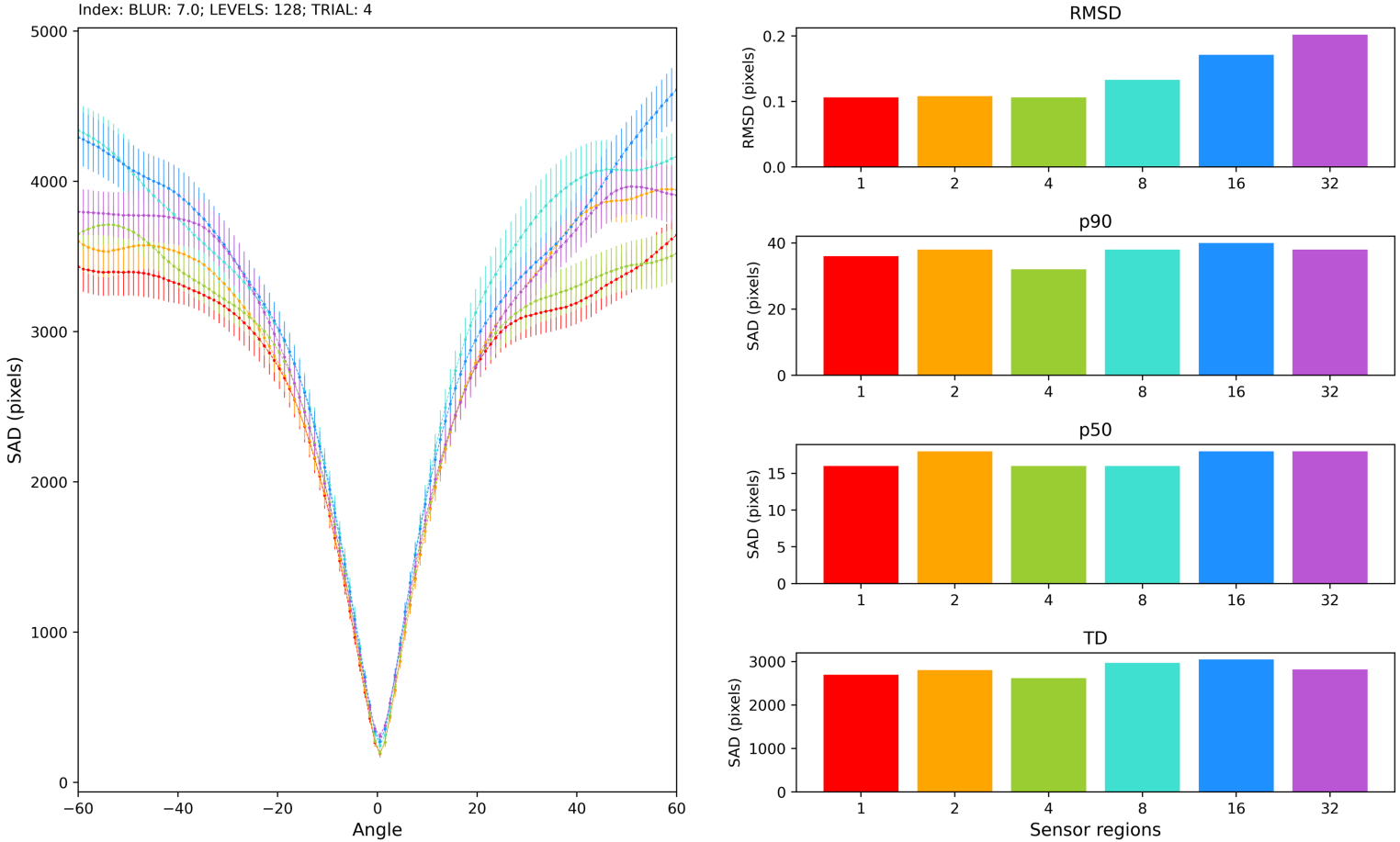



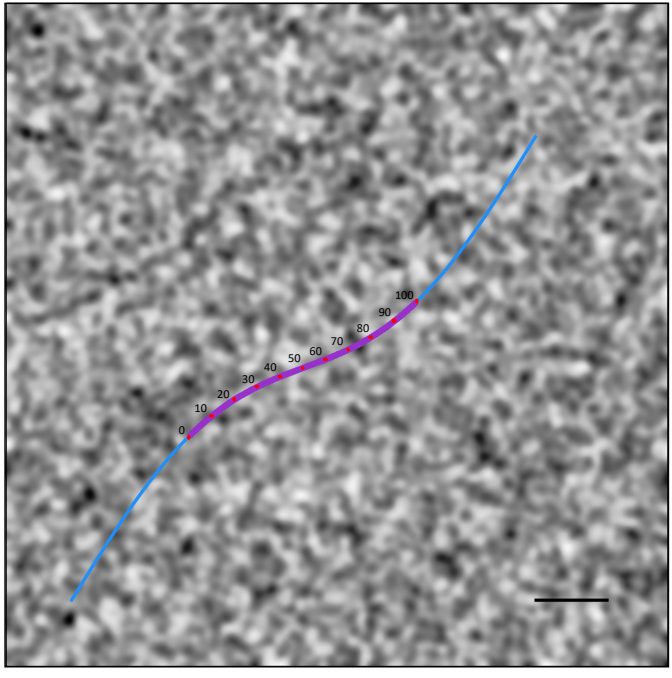



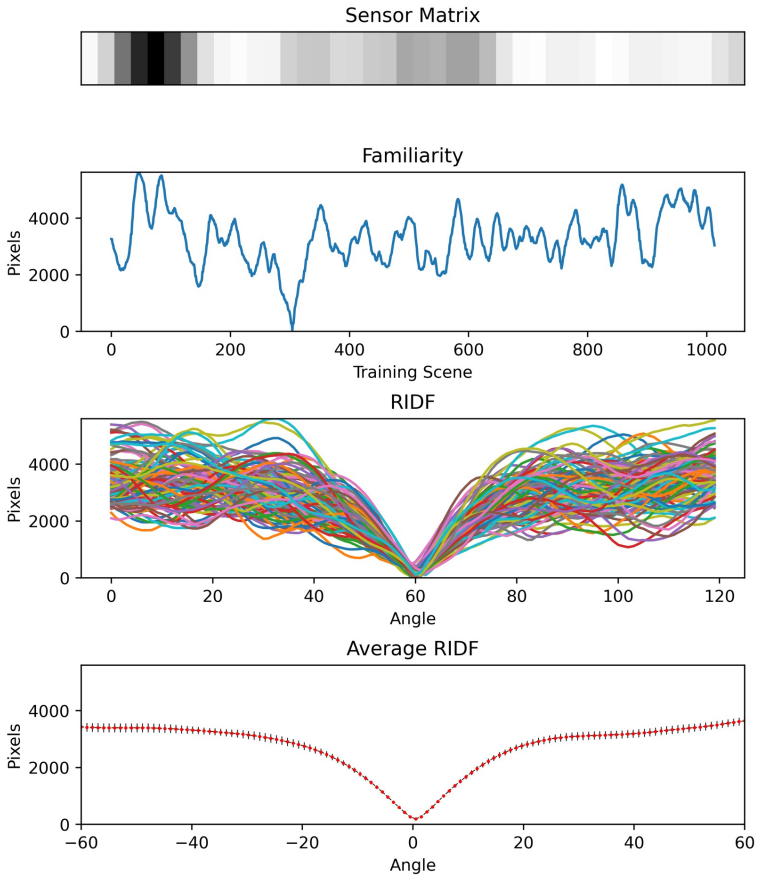

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 48.85; RMSD/dist: 0.122; TD: 2799; p90: 36; p50: 18; complete: 0


Index: BLUR: 7.0; LEVELS: 128; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

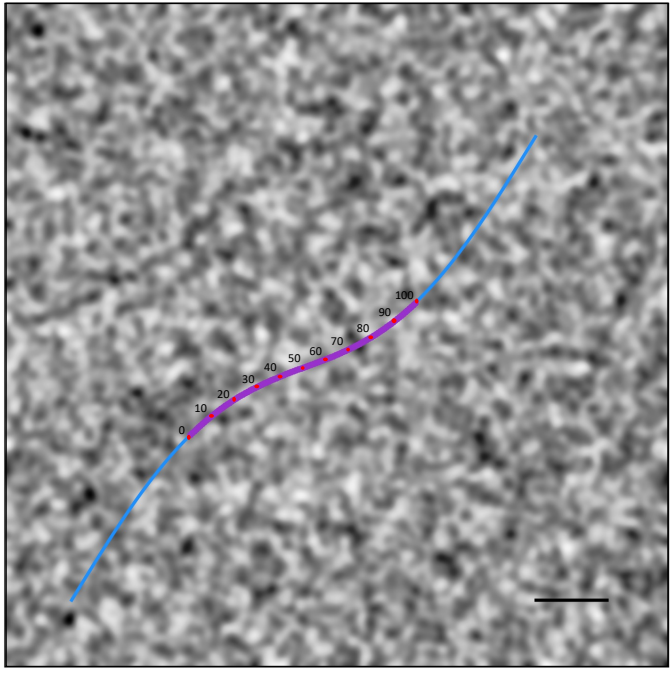


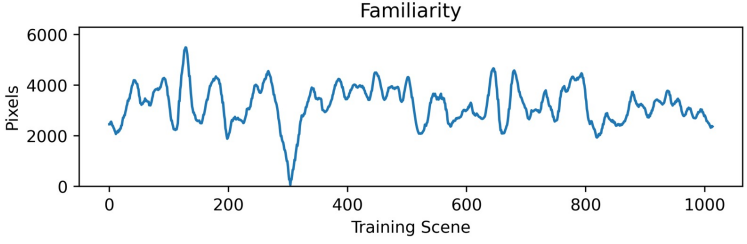



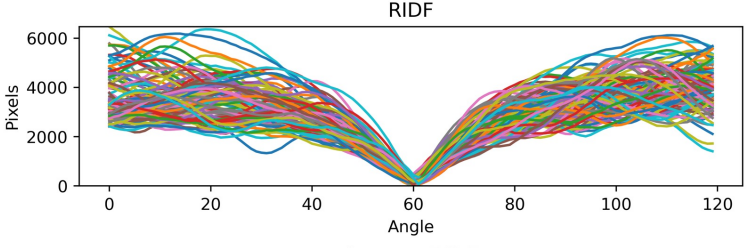

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

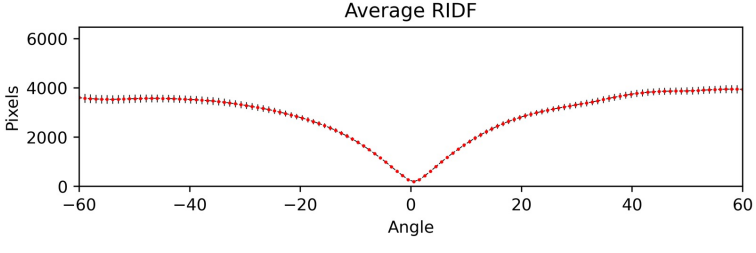
Navigation stats: RMSD error: 42.52; RMSD/dist: 0.106; TD: 2697; p90: 36; p50: 16; complete: 0

100%





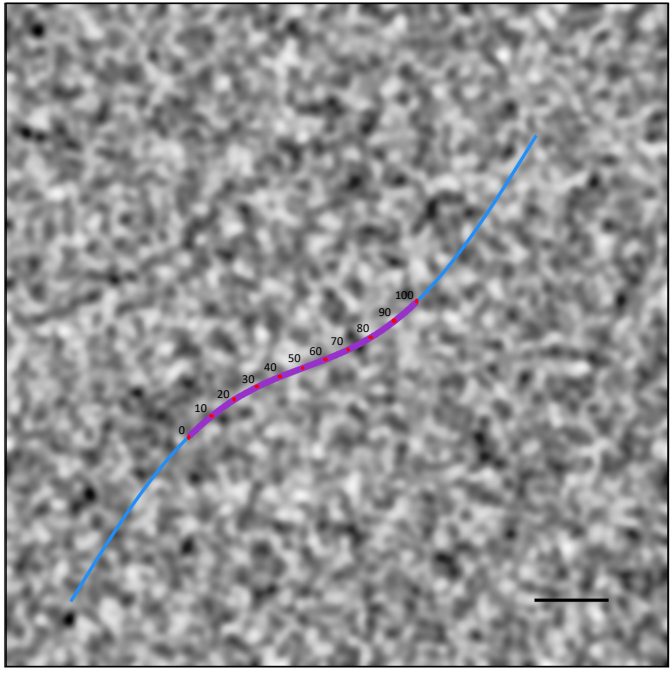



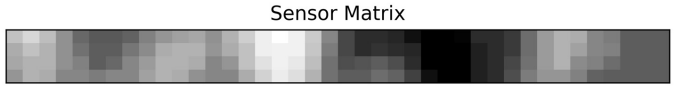



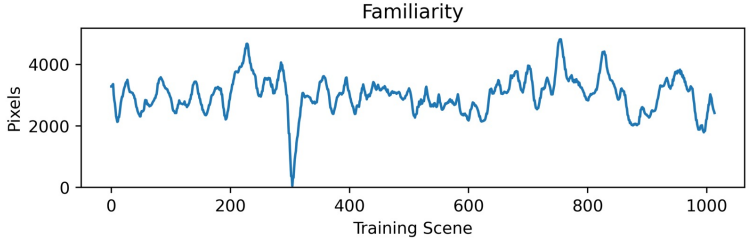

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

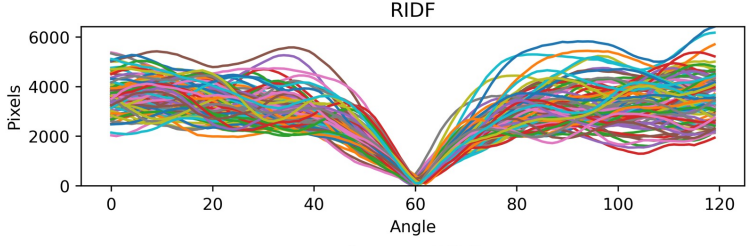
Navigation stats: RMSD error: 43.34; RMSD/dist: 0.108; TD: 2801; p90: 38; p50: 18; complete: 0

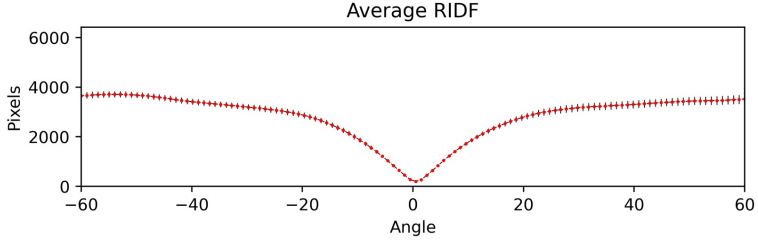
100%



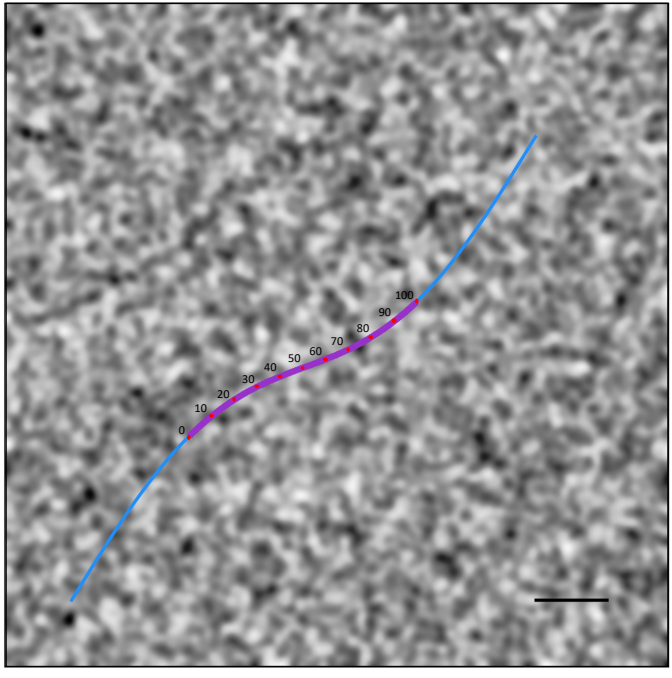



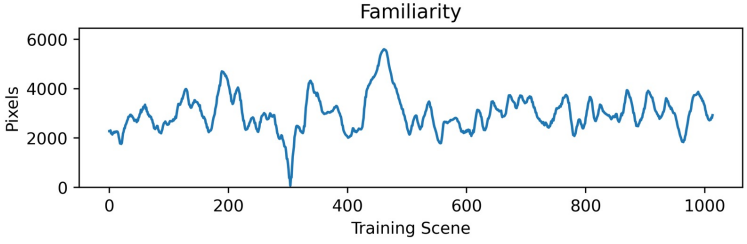



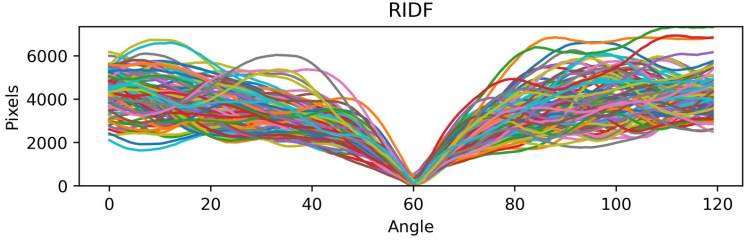

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

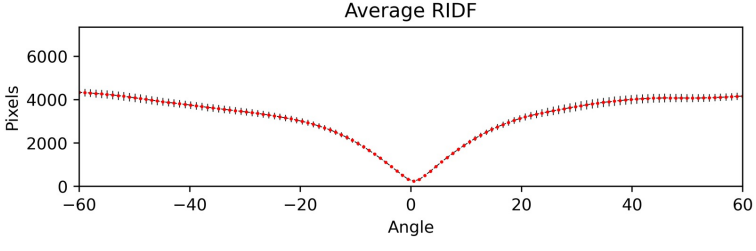
Navigation stats: RMSD error: 42.32; RMSD/dist: 0.106; TD: 2617; p90: 32; p50: 16; complete: 0

100%





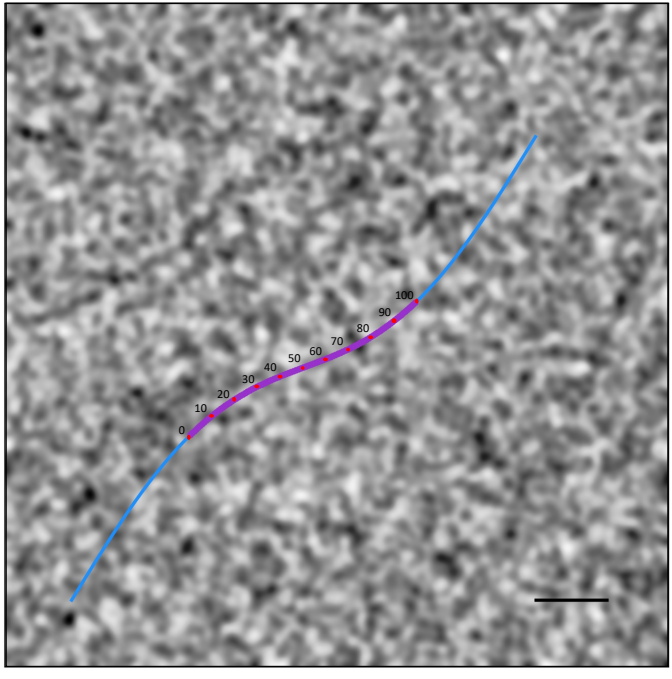



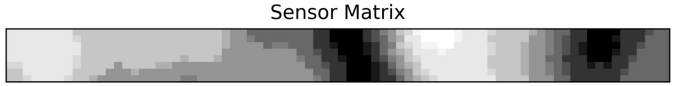



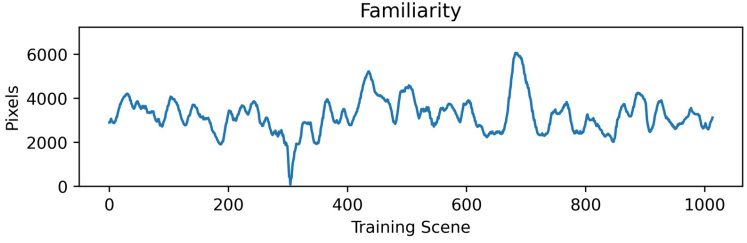

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

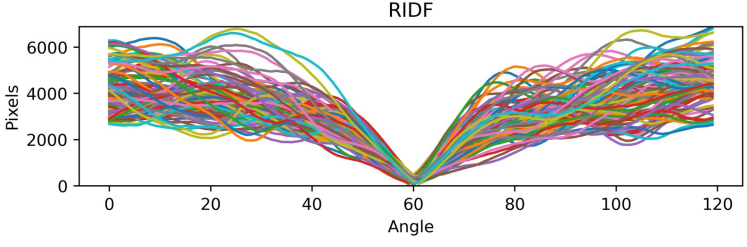
Navigation stats: RMSD error: 53.06; RMSD/dist: 0.133; TD: 2970; p90: 38; p50: 16; complete: 0

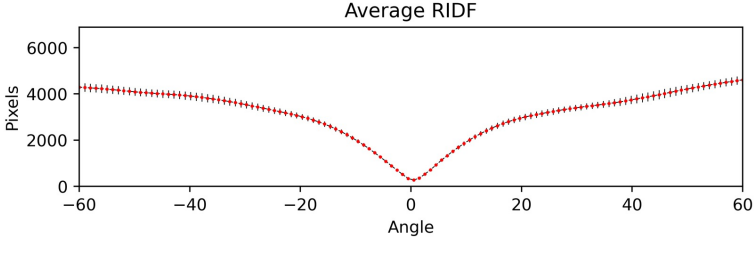
100%



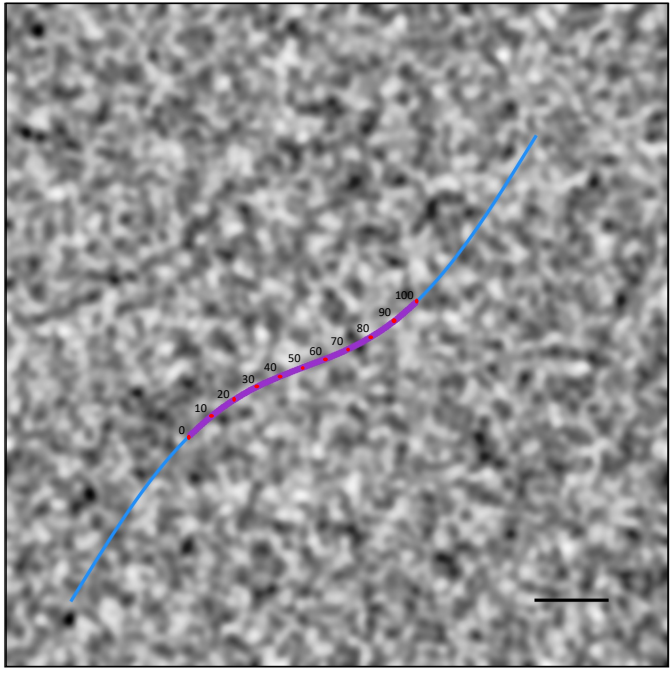



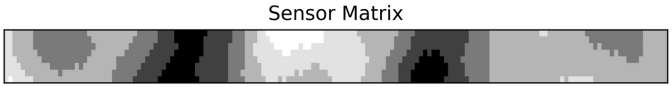



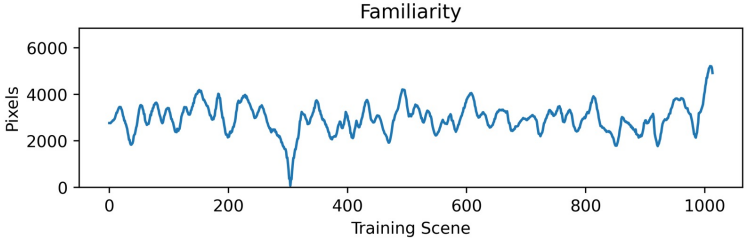

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

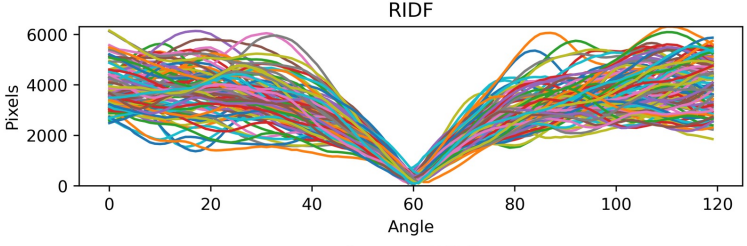
Navigation stats: RMSD error: 68.30; RMSD/dist: 0.171; TD: 3044; p90: 40; p50: 18; complete: 0

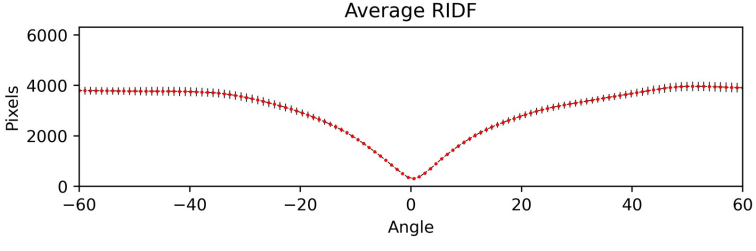
100%



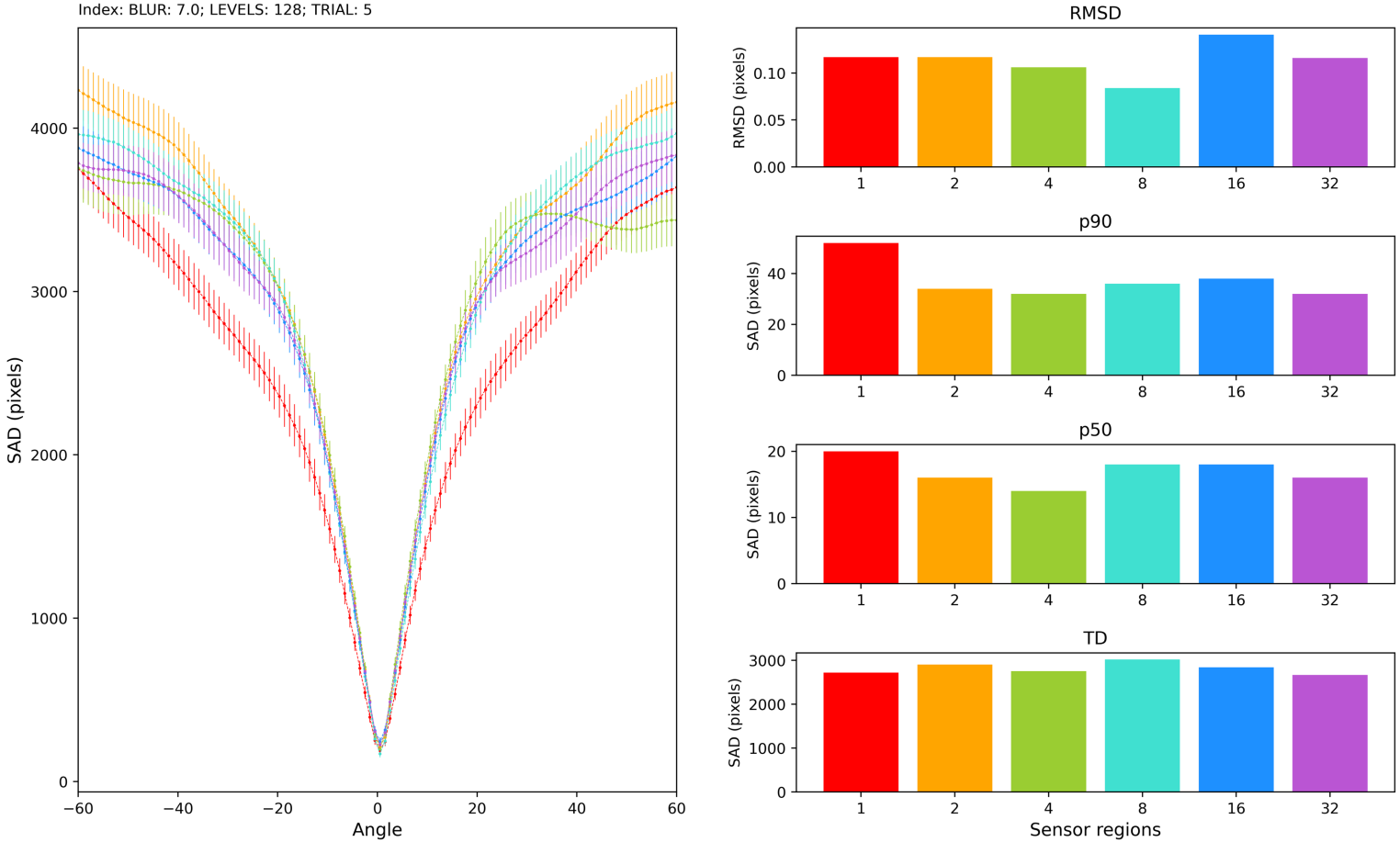



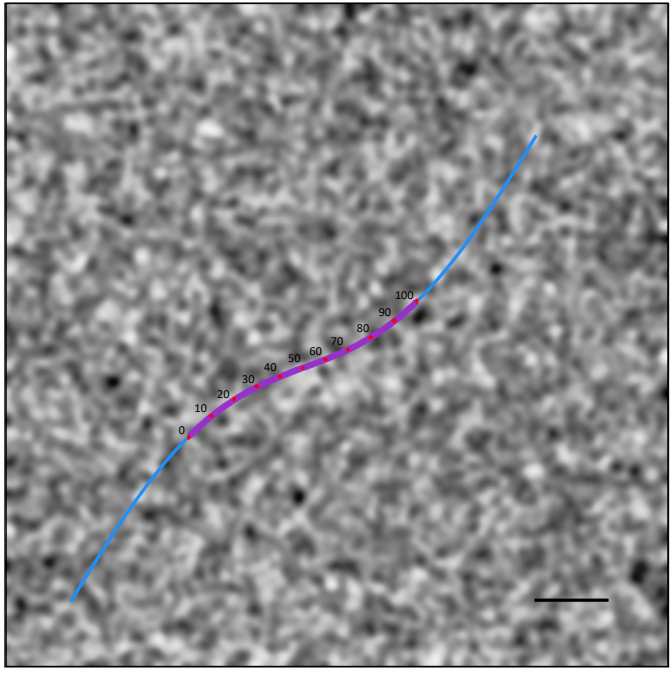



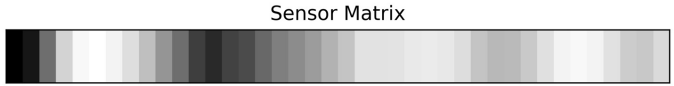

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

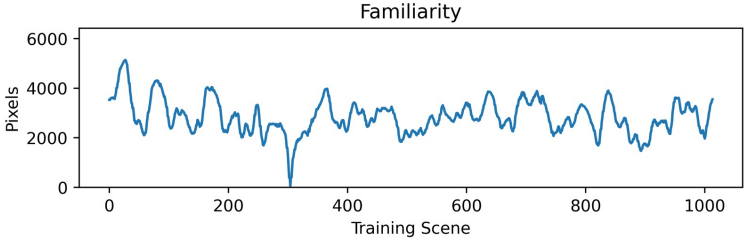
Navigation stats: RMSD error: 80.73; RMSD/dist: 0.202; TD: 2819; p90: 38; p50: 18; complete: 0

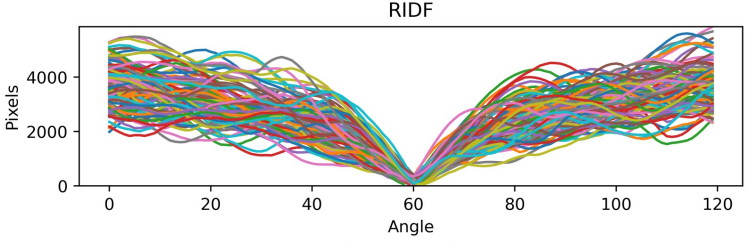

Index: BLUR: 7.0; LEVELS: 128; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

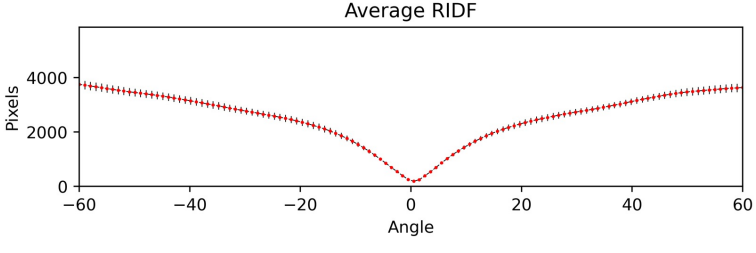
100%



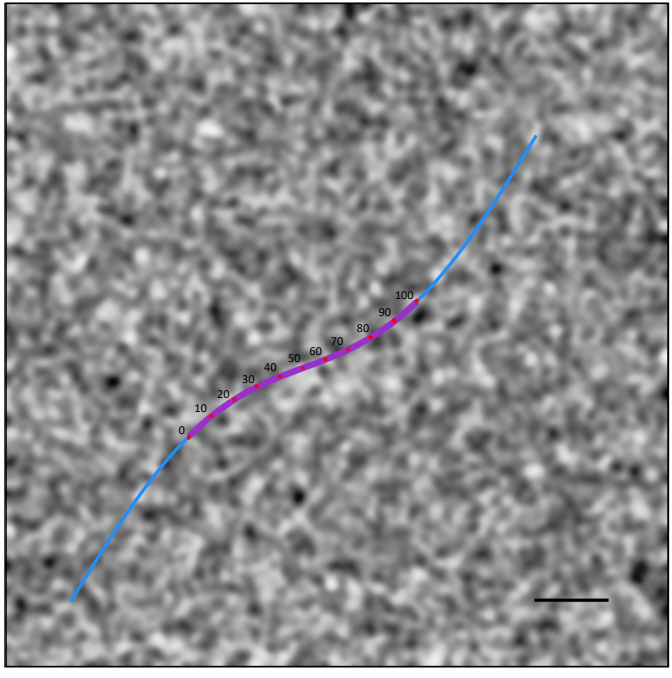



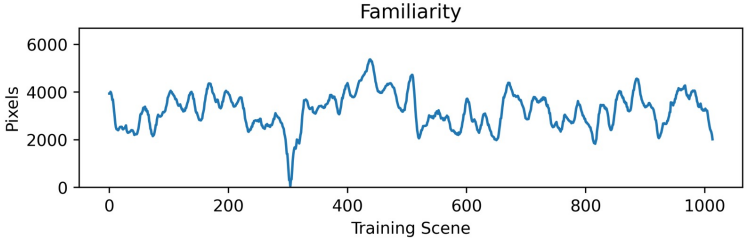



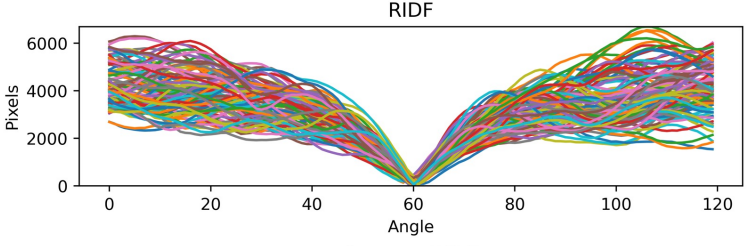

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

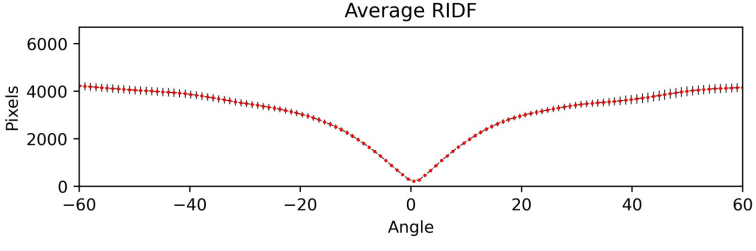
Navigation stats: RMSD error: 46.98; RMSD/dist: 0.117; TD: 2720; p90: 52; p50: 20; complete: 0

100%





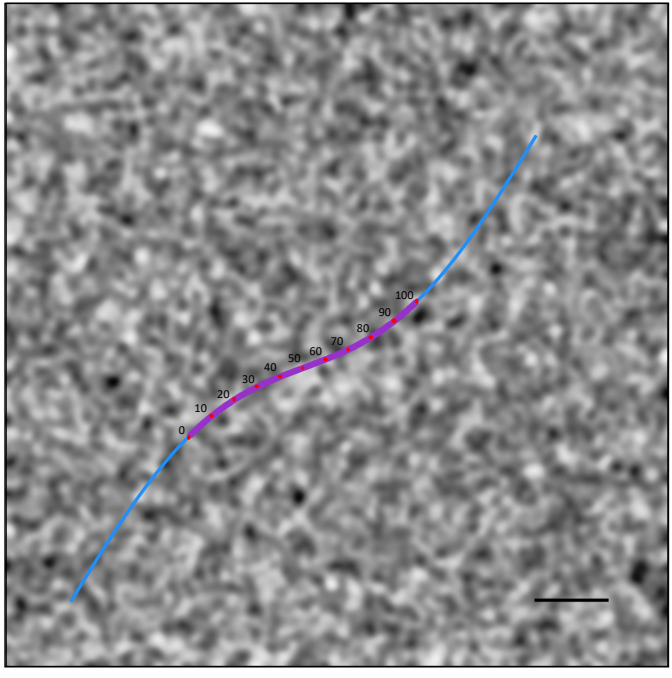



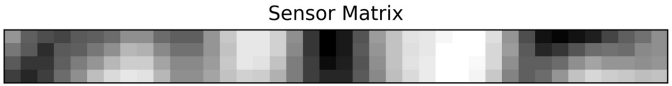



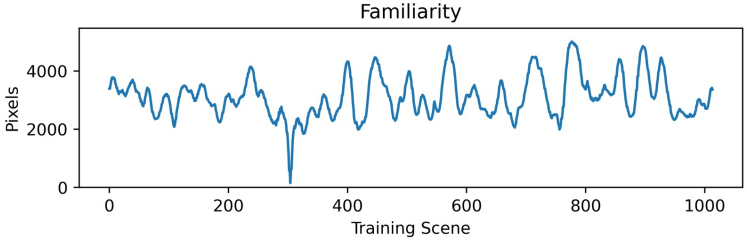

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

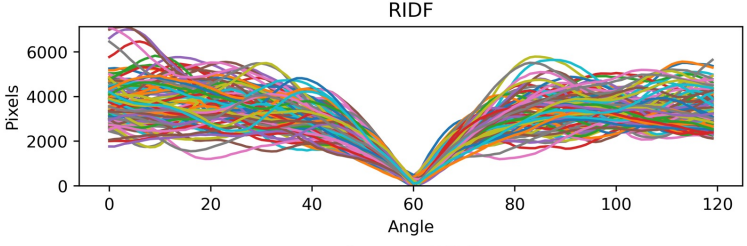
Navigation stats: RMSD error: 46.89; RMSD/dist: 0.117; TD: 2904; p90: 34; p50: 16; complete: 0

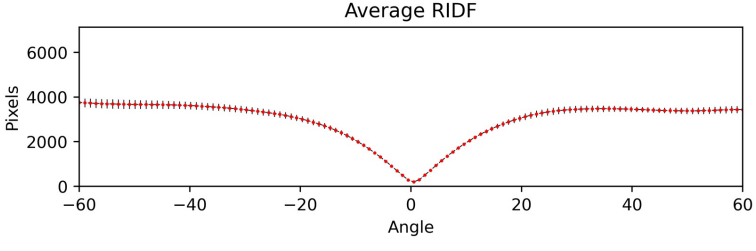
100%



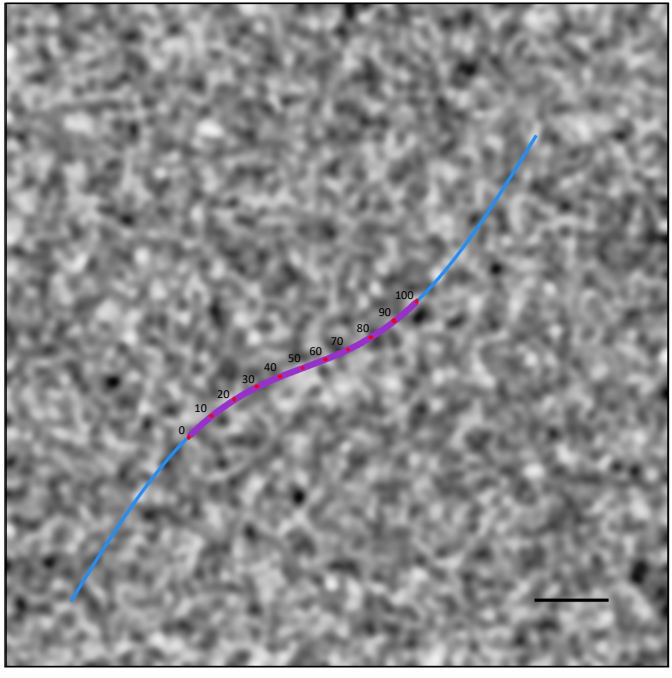



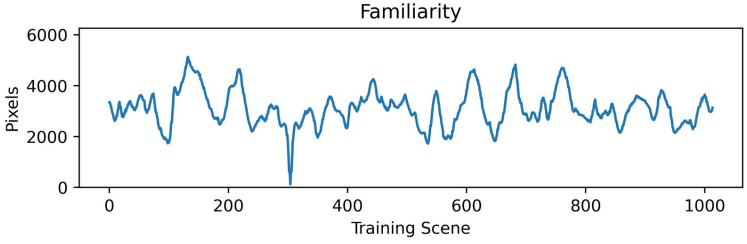



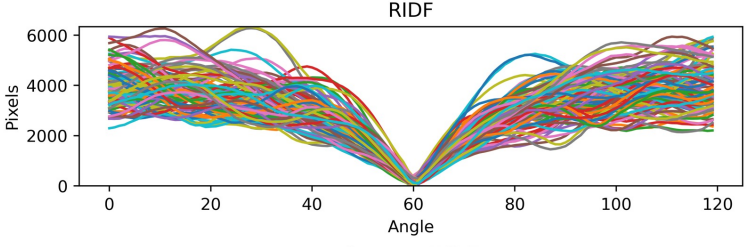

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

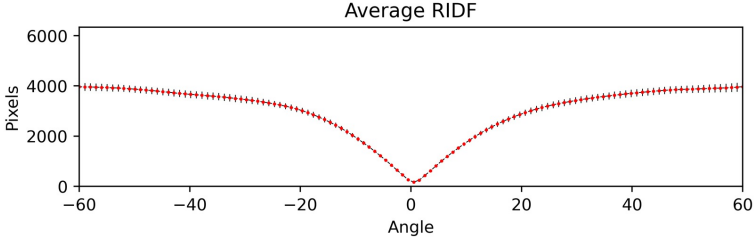
Navigation stats: RMSD error: 42.53; RMSD/dist: 0.106; TD: 2755; p90: 32; p50: 14; complete: 0

100%





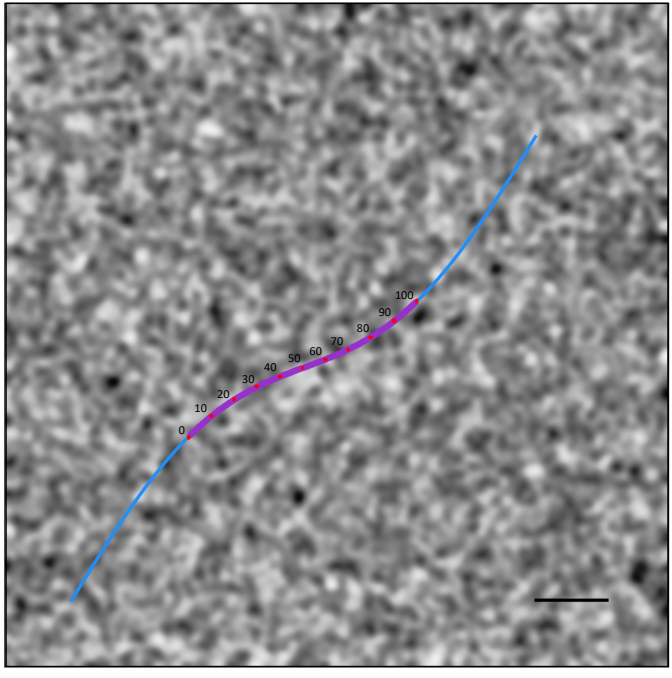



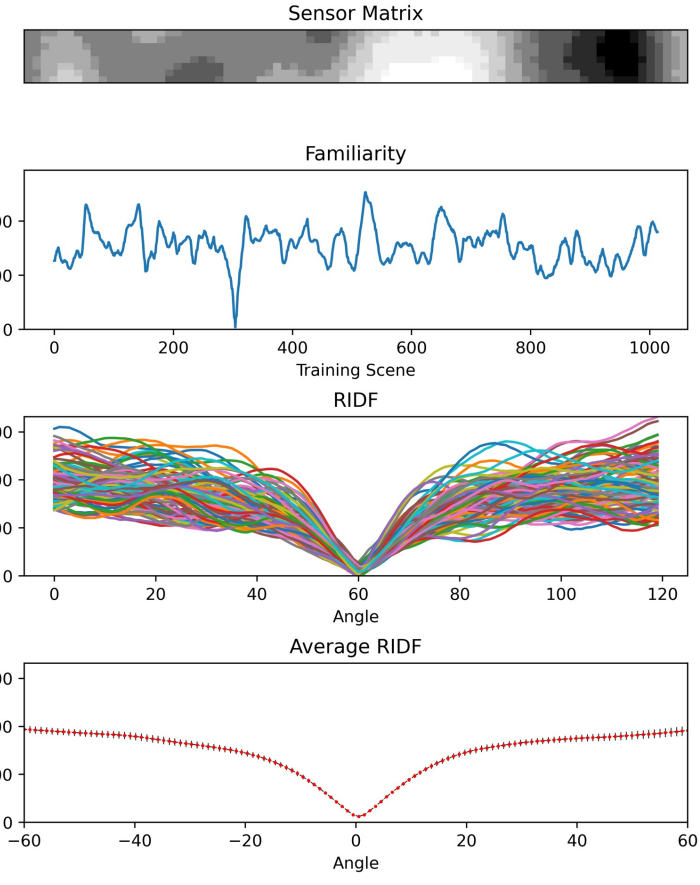




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 33.55; RMSD/dist: 0.084; TD: 3018; p90: 36; p50: 18; complete: 0

100%

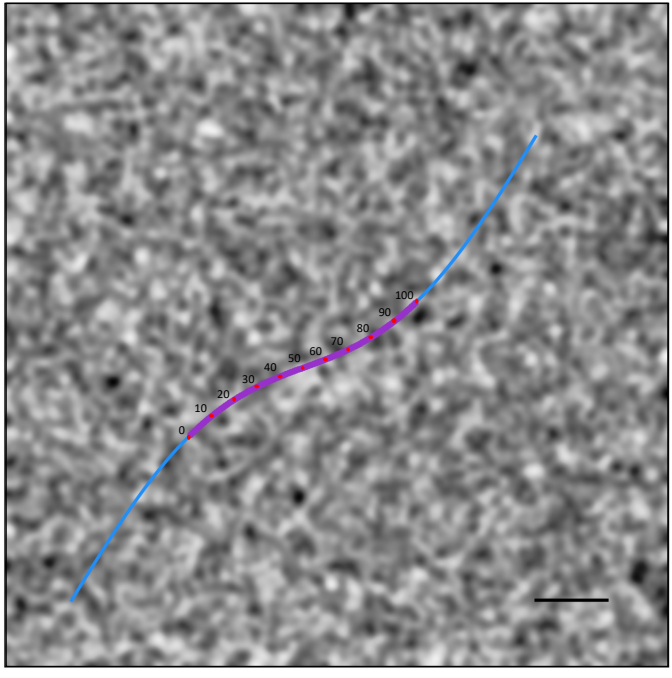


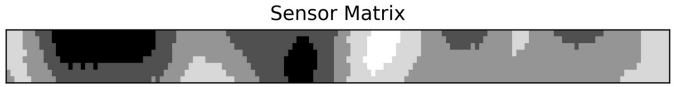



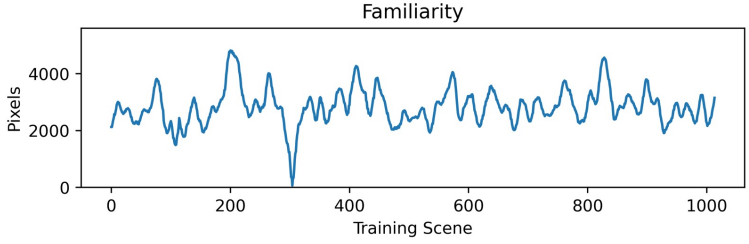

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

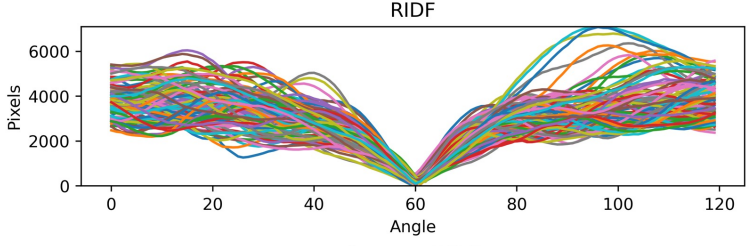
Navigation stats: RMSD error: 56.53; RMSD/dist: 0.141; TD: 2843; p90: 38; p50: 18; complete: 0

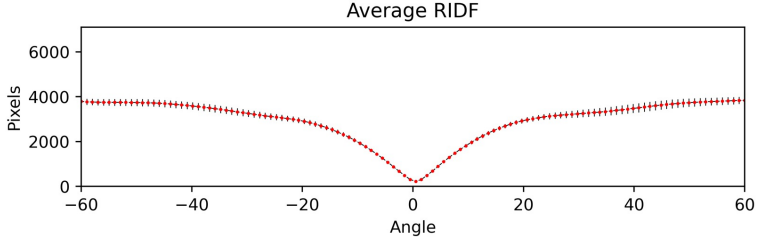
100%



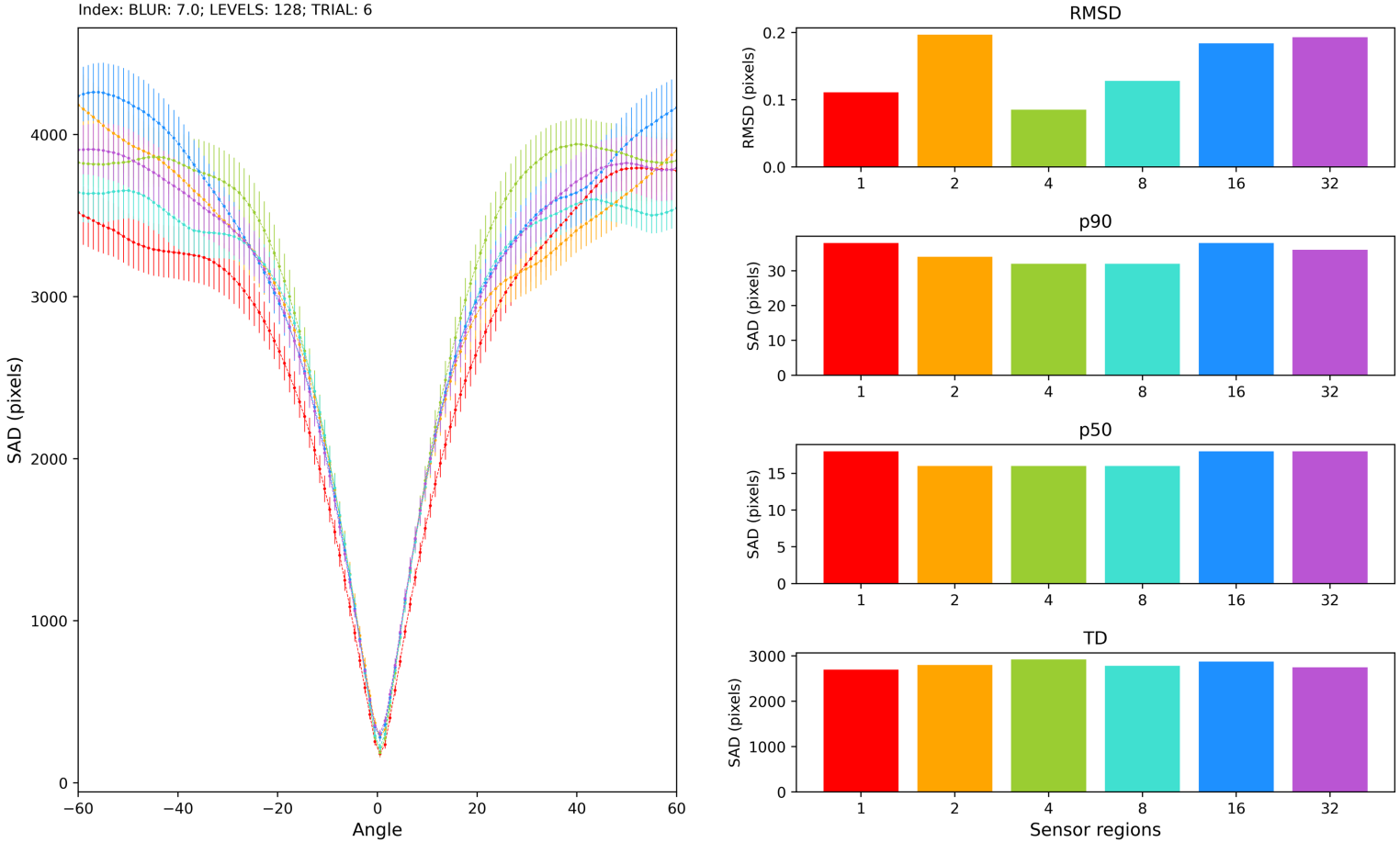



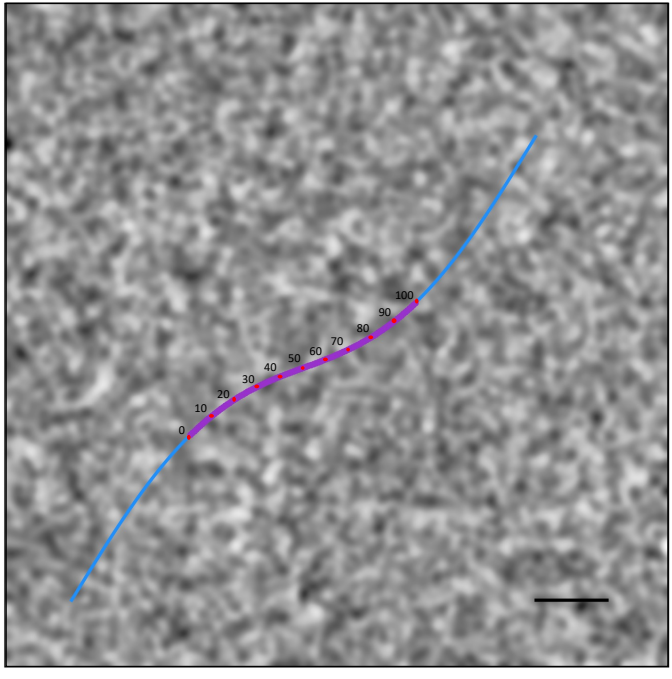



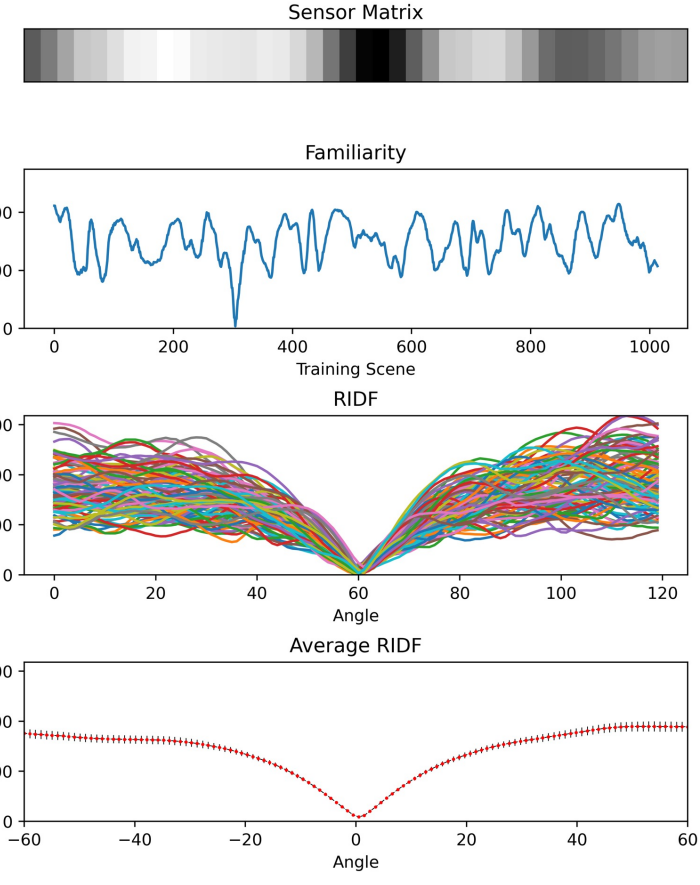

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 46.49; RMSD/dist: 0.116; TD: 2666; p90: 32; p50: 16; complete: 0


Index: BLUR: 7.0; LEVELS: 128; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

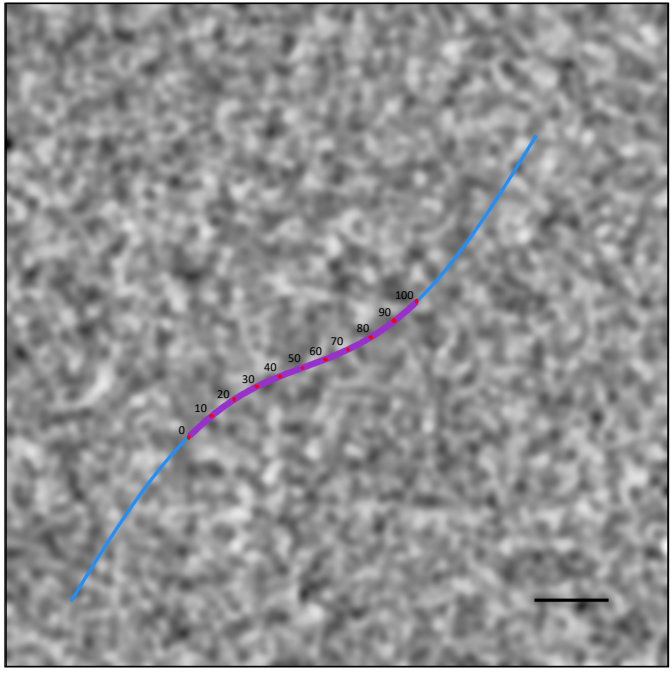


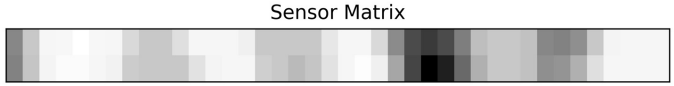



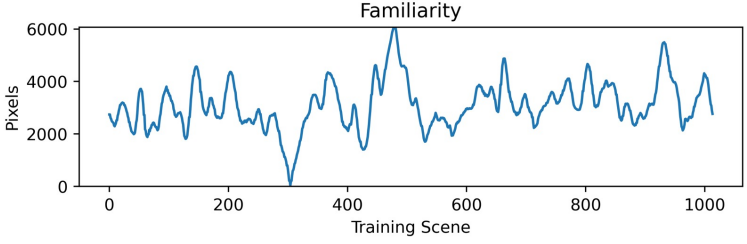

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

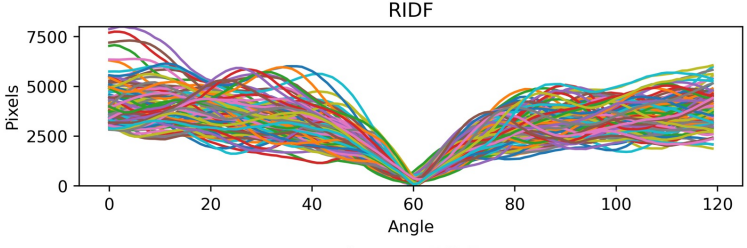
Navigation stats: RMSD error: 44.59; RMSD/dist: 0.111; TD: 2694; p90: 38; p50: 18; complete: 0

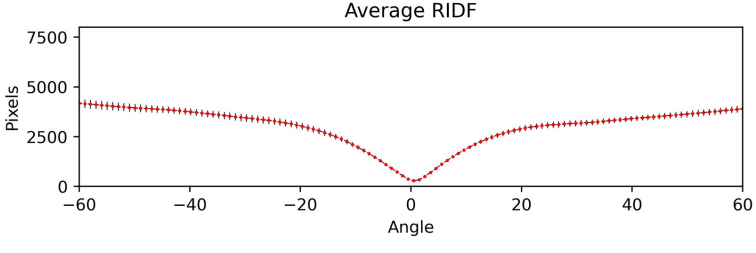
100%



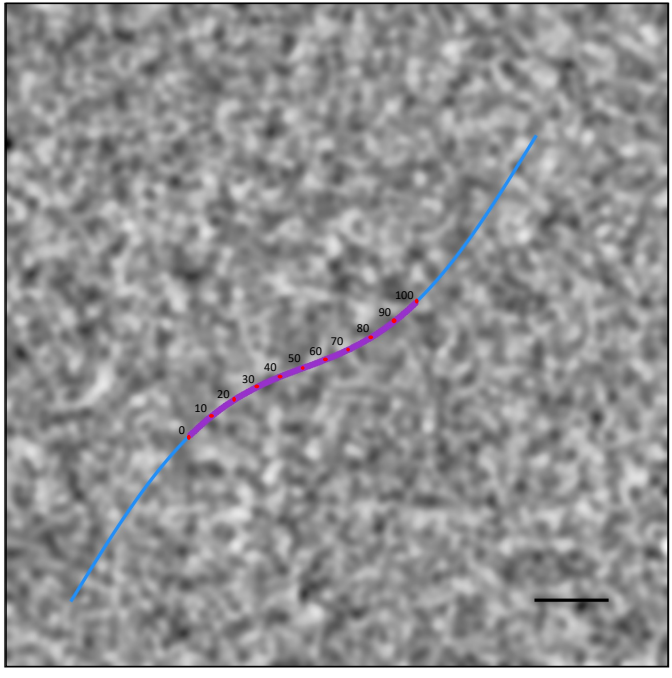



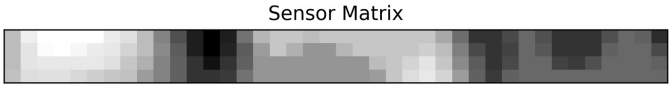



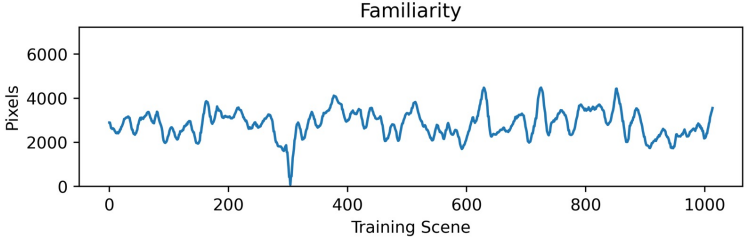

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

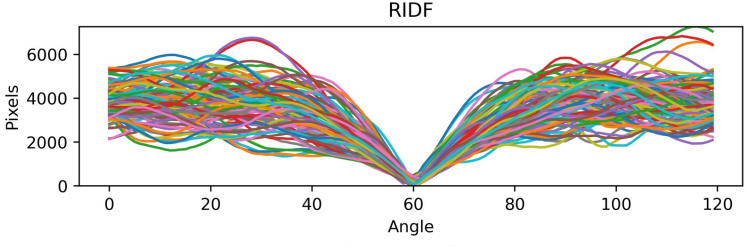
Navigation stats: RMSD error: 78.75; RMSD/dist: 0.197; TD: 2796; p90: 34; p50: 16; complete: 0

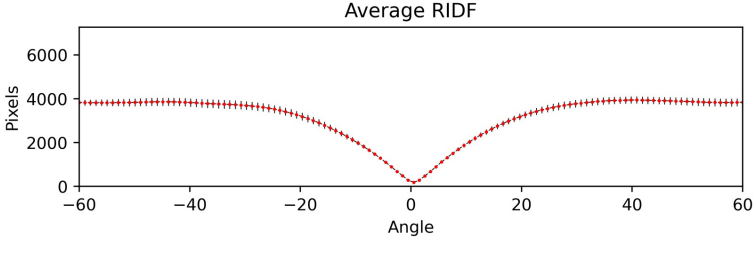
100%



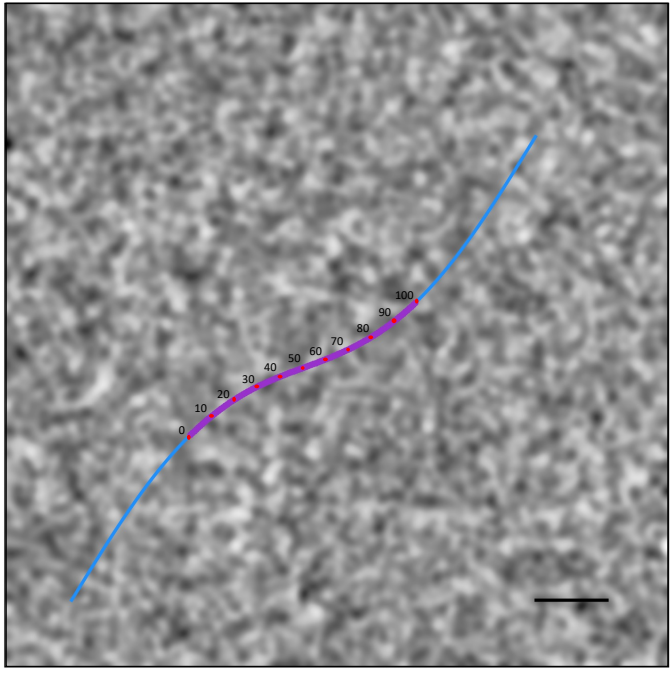



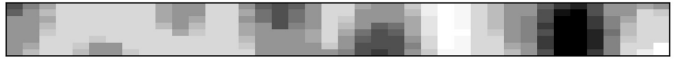



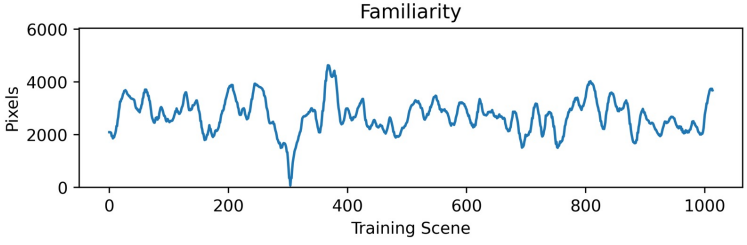

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

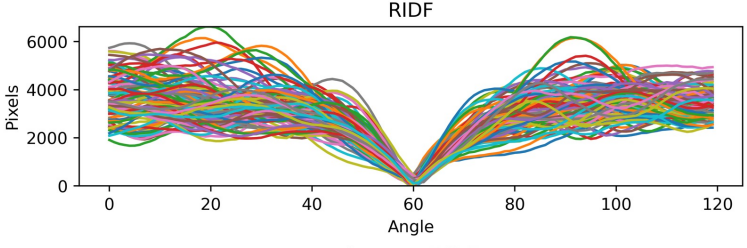
Navigation stats: RMSD error: 34.18; RMSD/dist: 0.085; TD: 2917; p90: 32; p50: 16; complete: 0

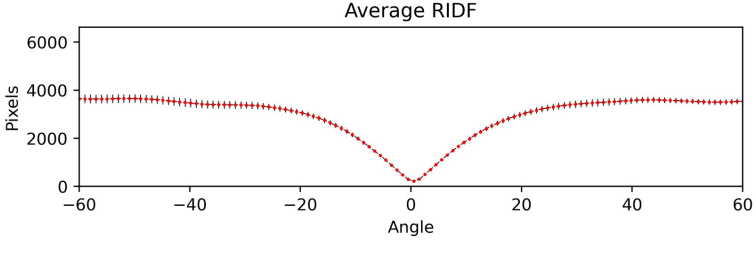
100%



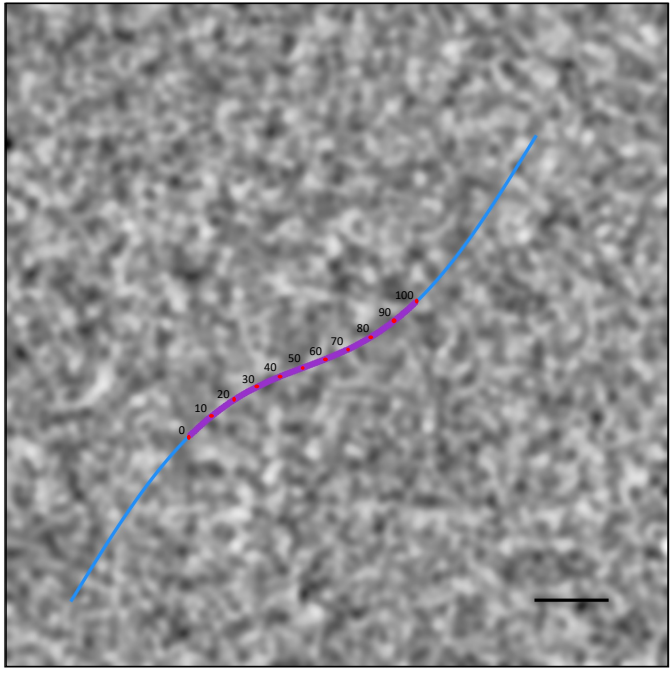



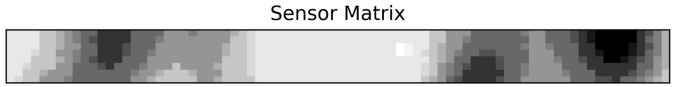



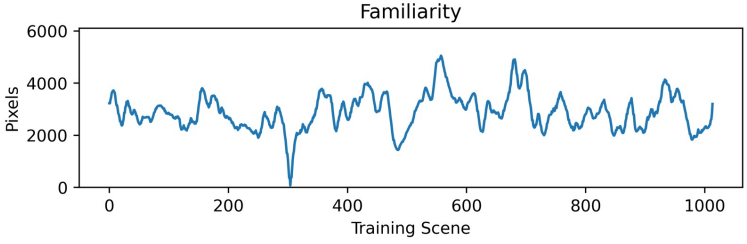

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

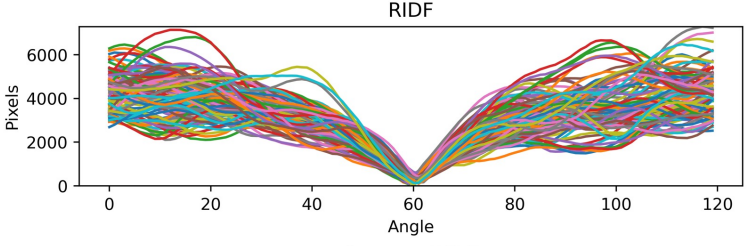
Navigation stats: RMSD error: 51.06; RMSD/dist: 0.128; TD: 2781; p90: 32; p50: 16; complete: 0

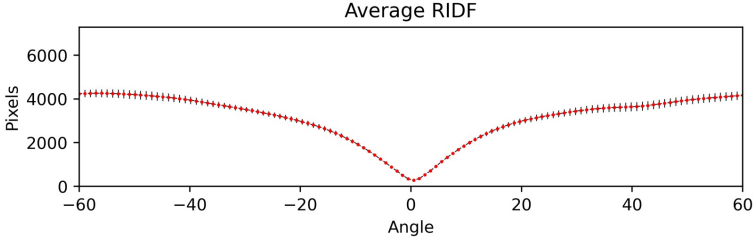
100%



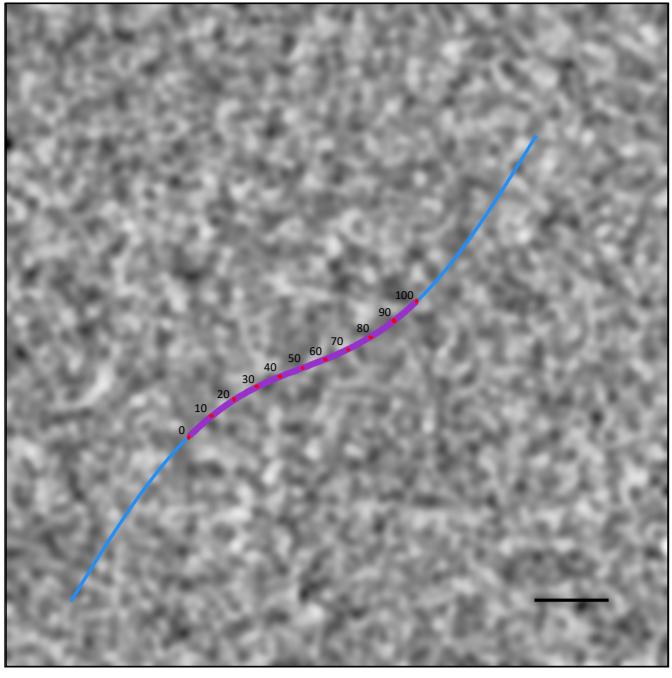



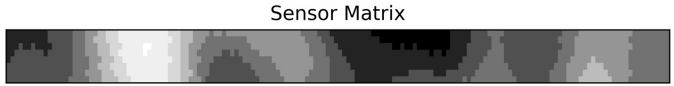



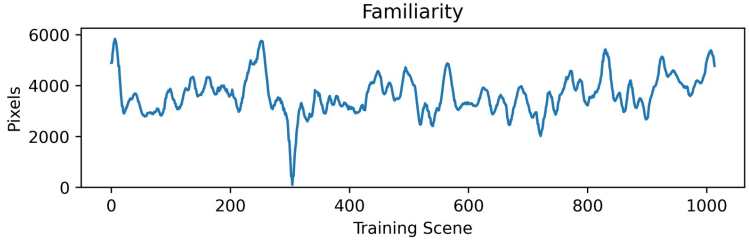

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

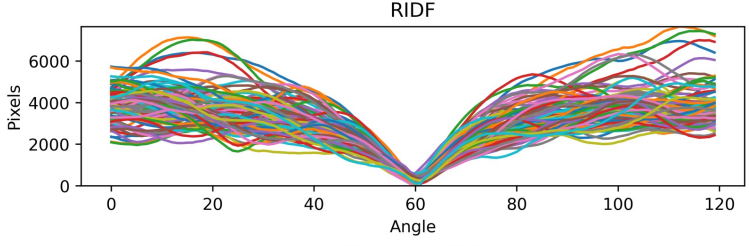
Navigation stats: RMSD error: 73.74; RMSD/dist: 0.184; TD: 2872; p90: 38; p50: 18; complete: 0

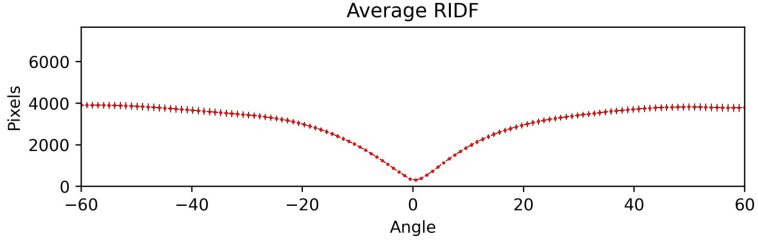
100%



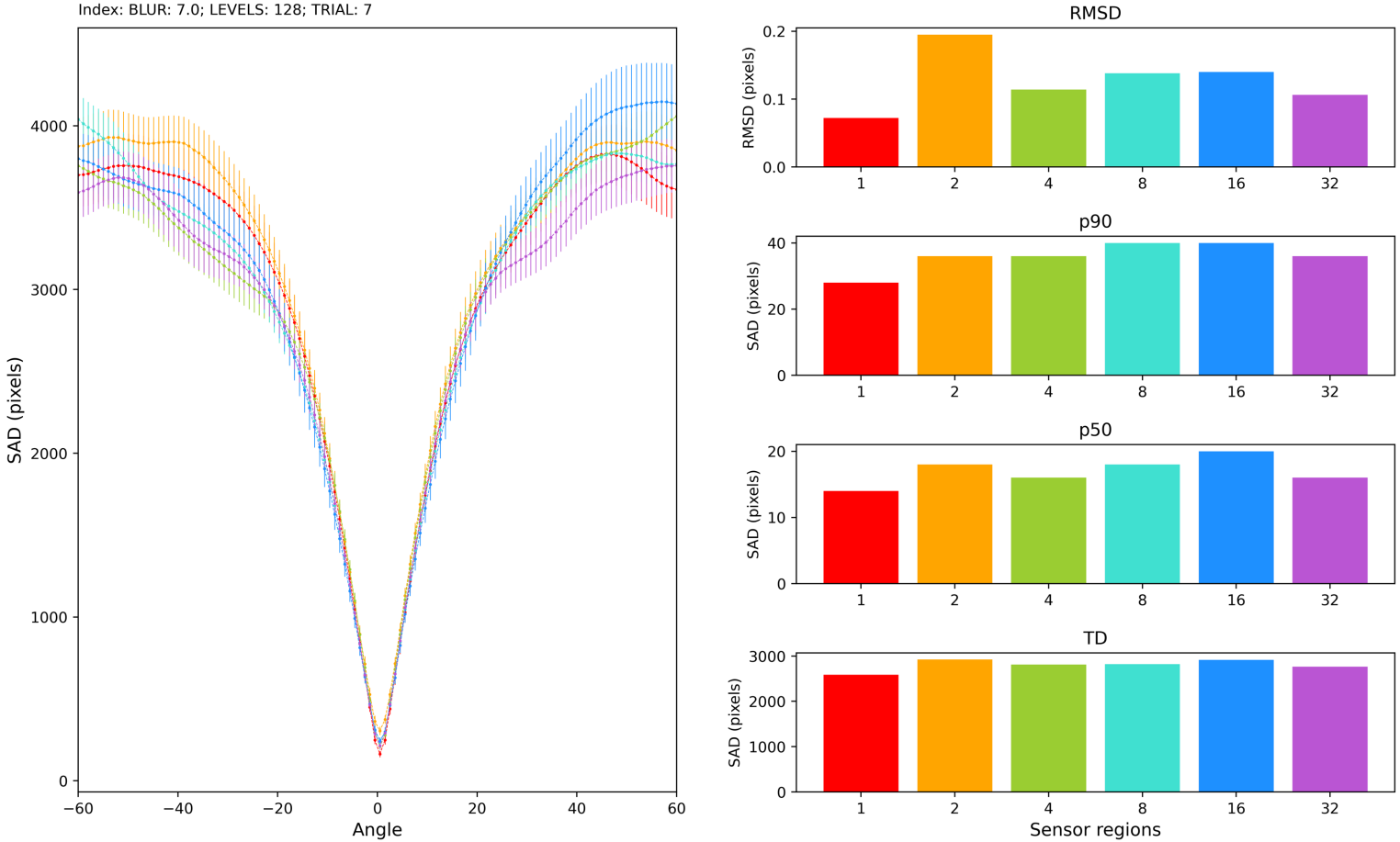



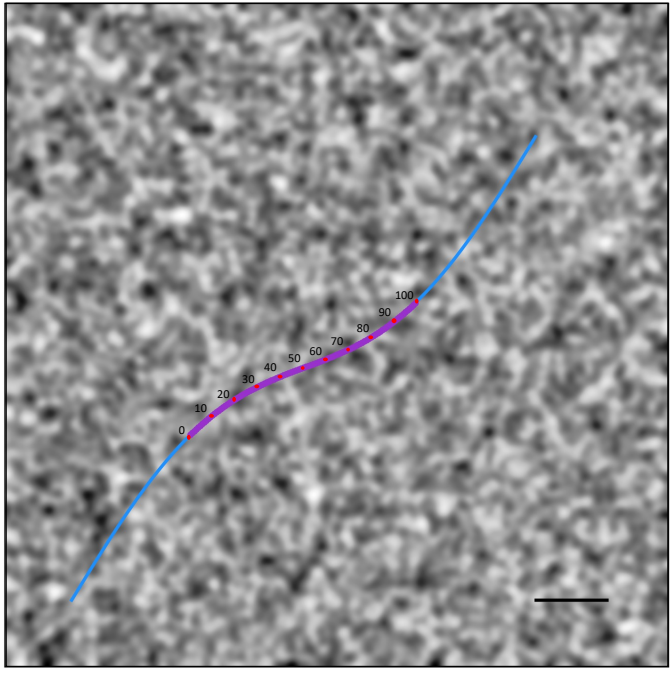



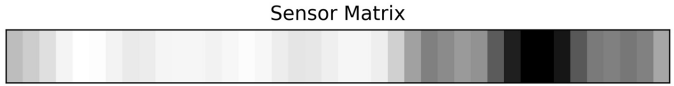

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

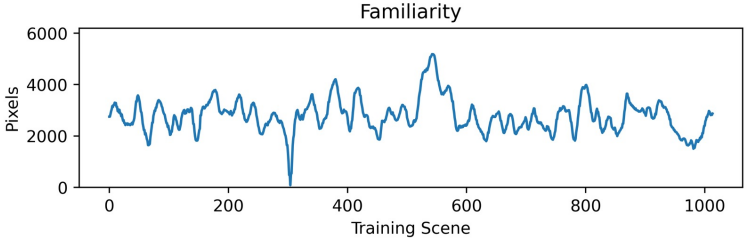
Navigation stats: RMSD error: 77.38; RMSD/dist: 0.193; TD: 2745; p90: 36; p50: 18; complete: 0

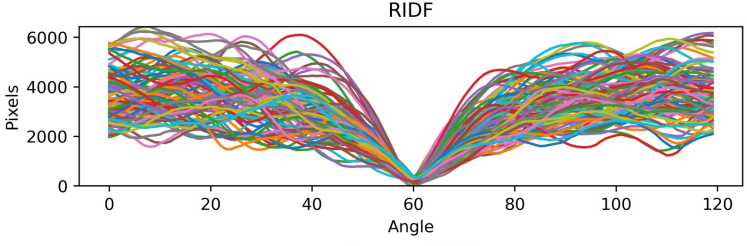

Index: BLUR: 7.0; LEVELS: 128; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

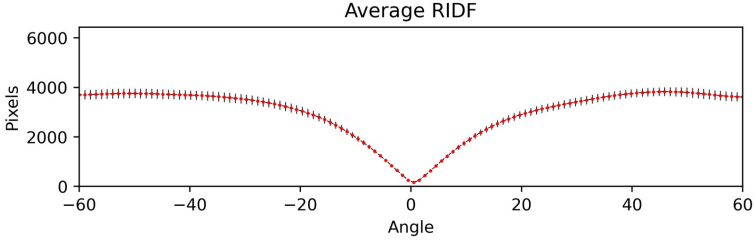
100%



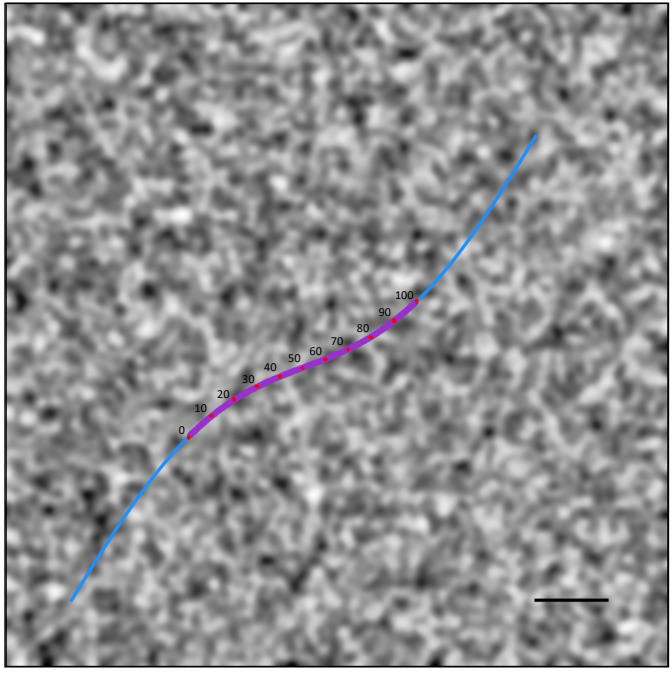



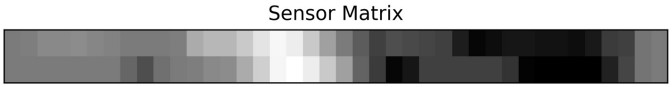



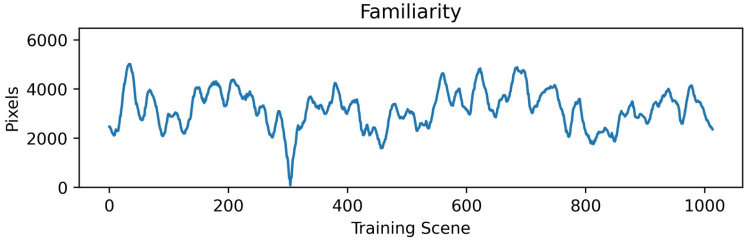

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

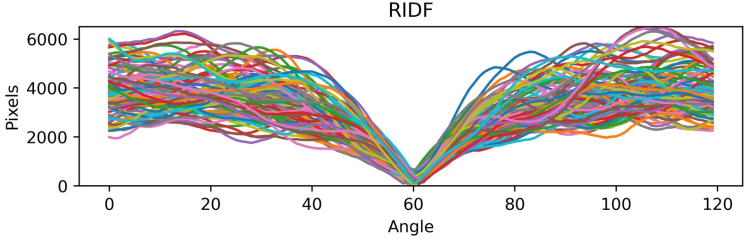
Navigation stats: RMSD error: 28.74; RMSD/dist: 0.072; TD: 2586; p90: 28; p50: 14; complete: 0

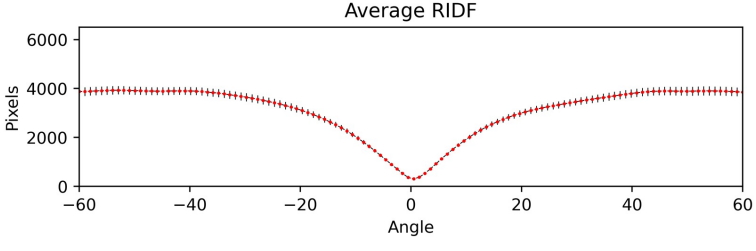
100%



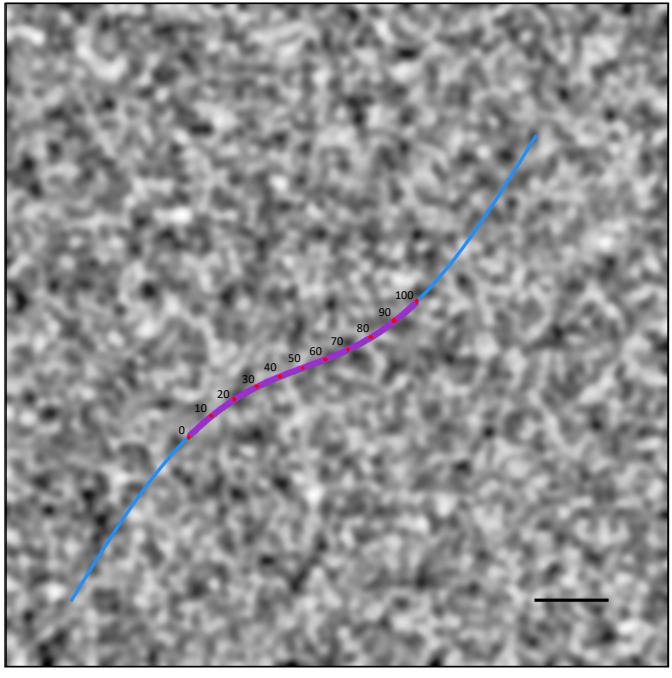



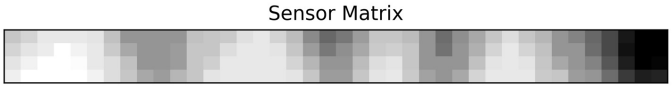



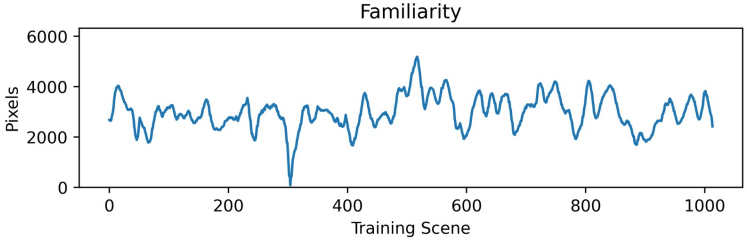

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

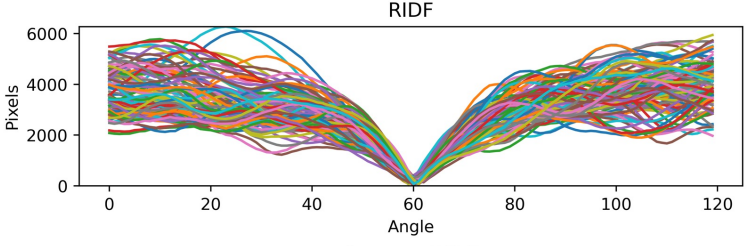
Navigation stats: RMSD error: 77.81; RMSD/dist: 0.195; TD: 2921; p90: 36; p50: 18; complete: 0

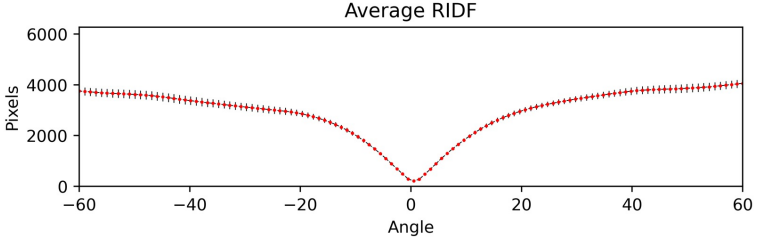
100%



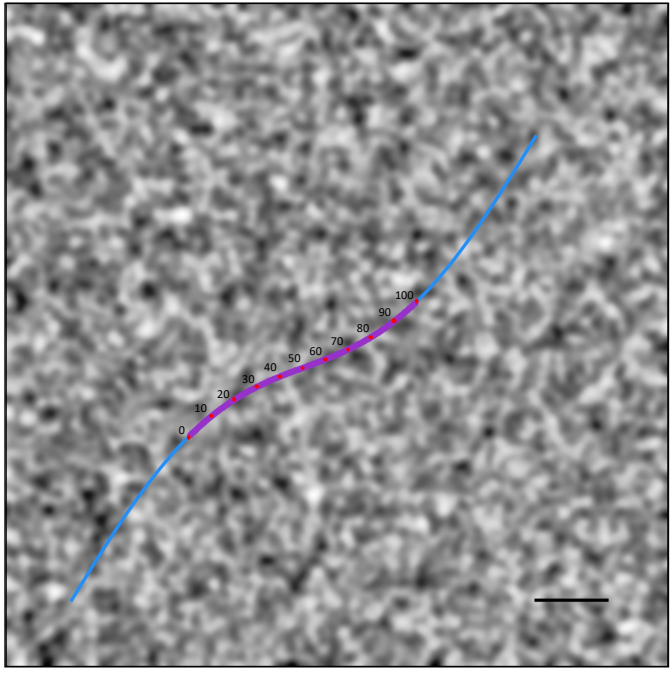



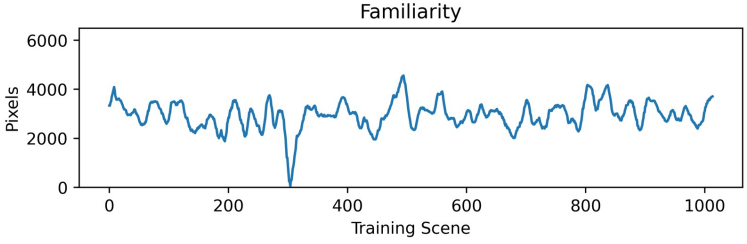



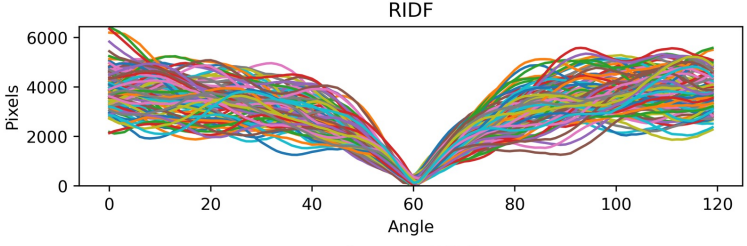

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

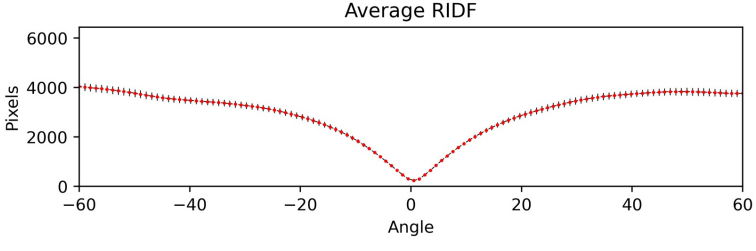
Navigation stats: RMSD error: 45.61; RMSD/dist: 0.114; TD: 2809; p90: 36; p50: 16; complete: 0

100%





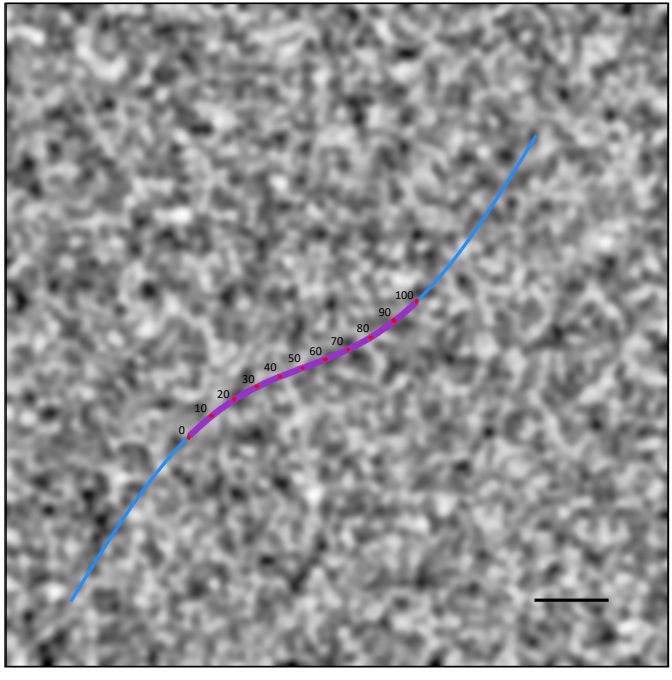



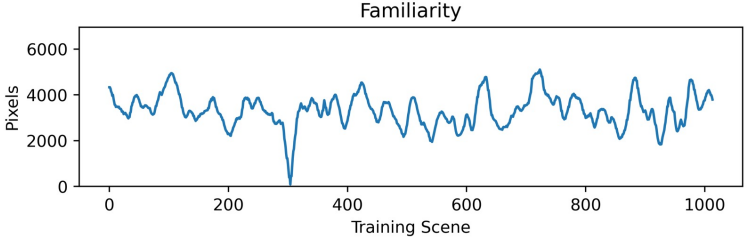



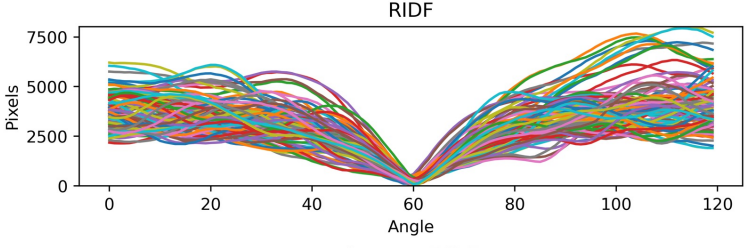

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

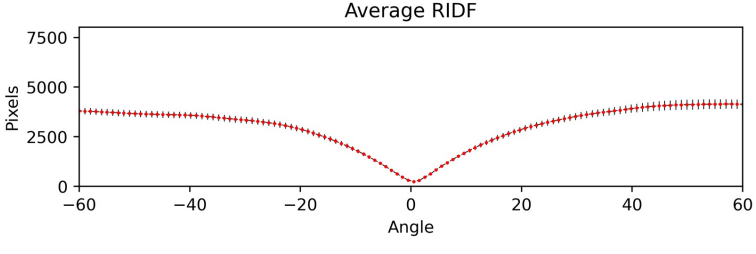
Navigation stats: RMSD error: 55.30; RMSD/dist: 0.138; TD: 2822; p90: 40; p50: 18; complete: 0

100%





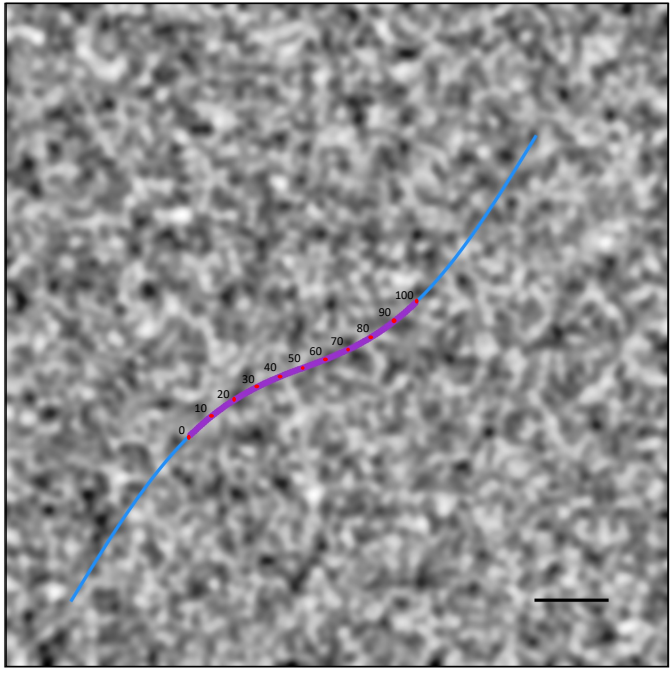



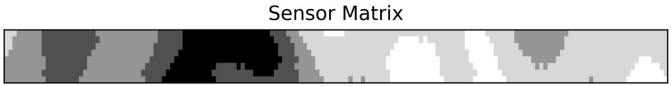



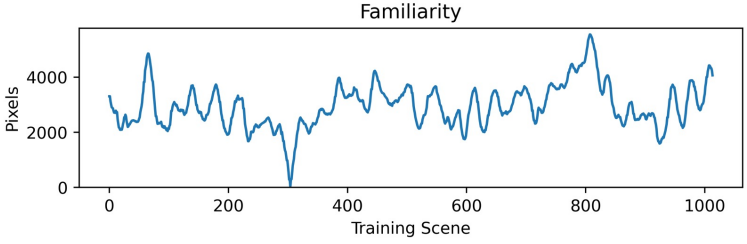

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

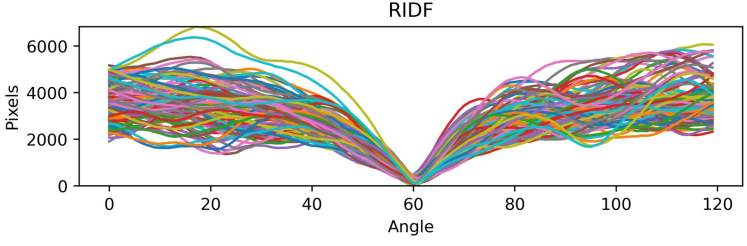
Navigation stats: RMSD error: 56.05; RMSD/dist: 0.140; TD: 2914; p90: 40; p50: 20; complete: 0

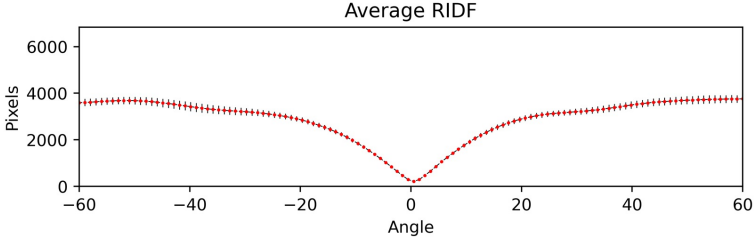
100%



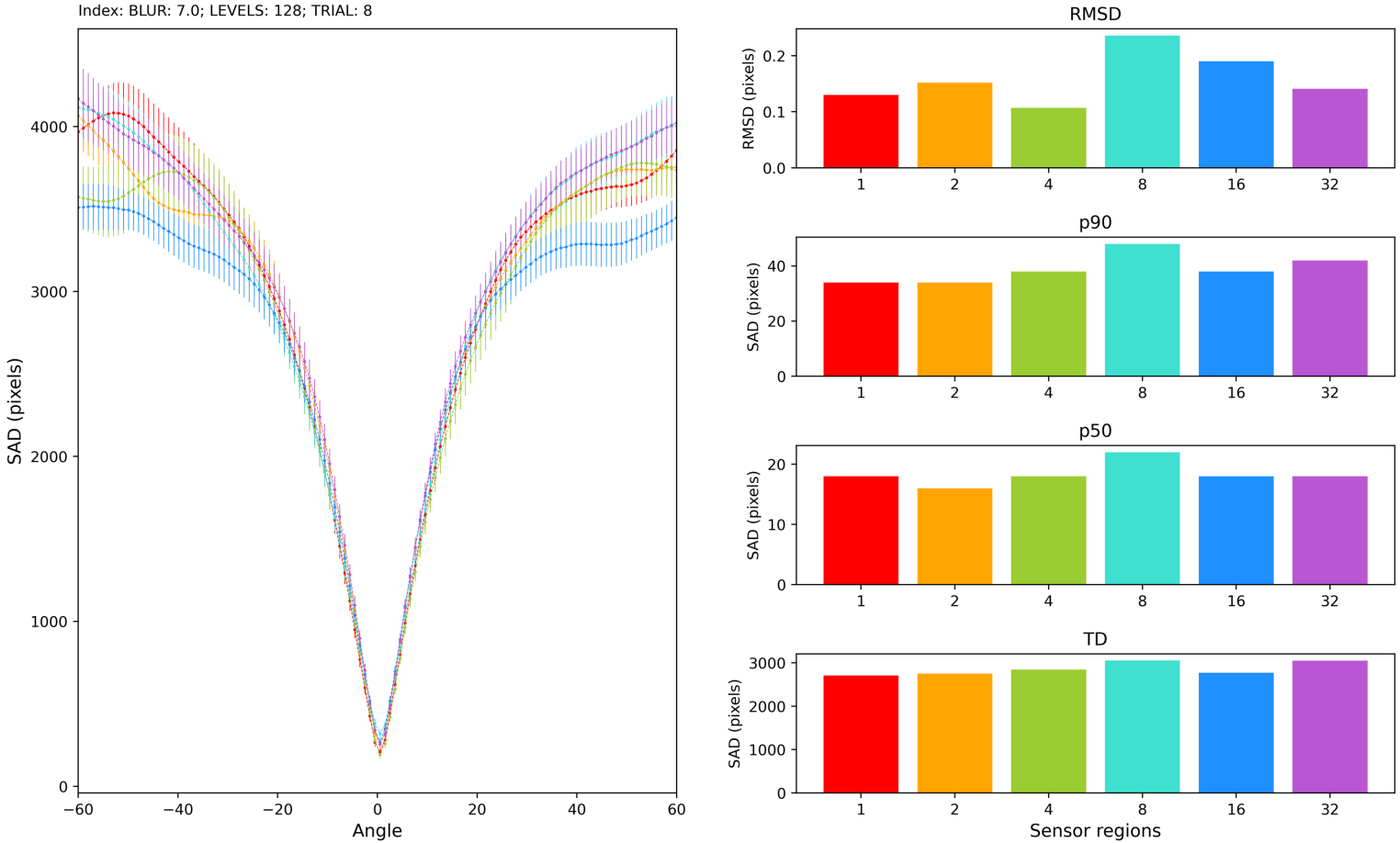



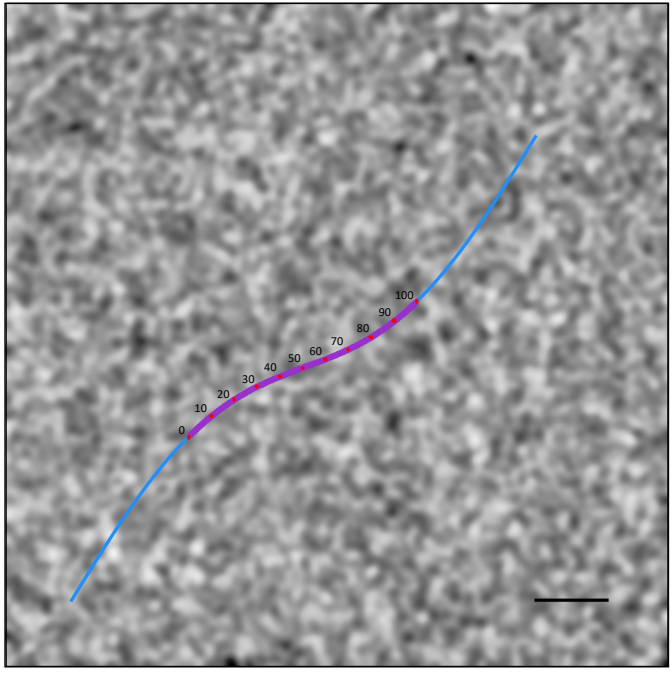



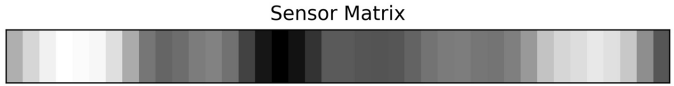

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

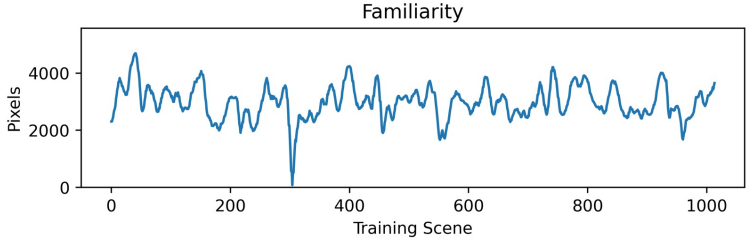
Navigation stats: RMSD error: 42.55; RMSD/dist: 0.106; TD: 2765; p90: 36; p50: 16; complete: 0

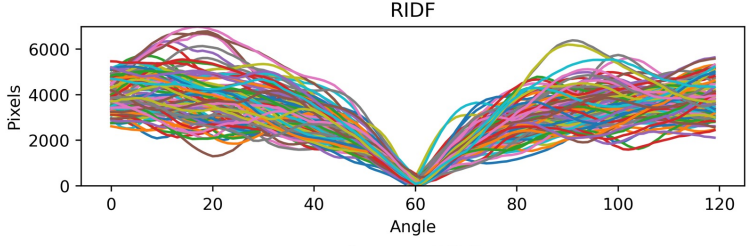

Index: BLUR: 7.0; LEVELS: 128; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

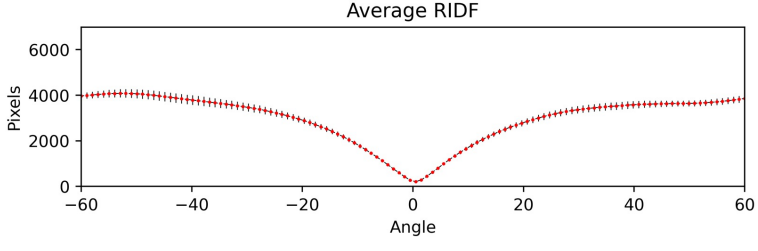
100%



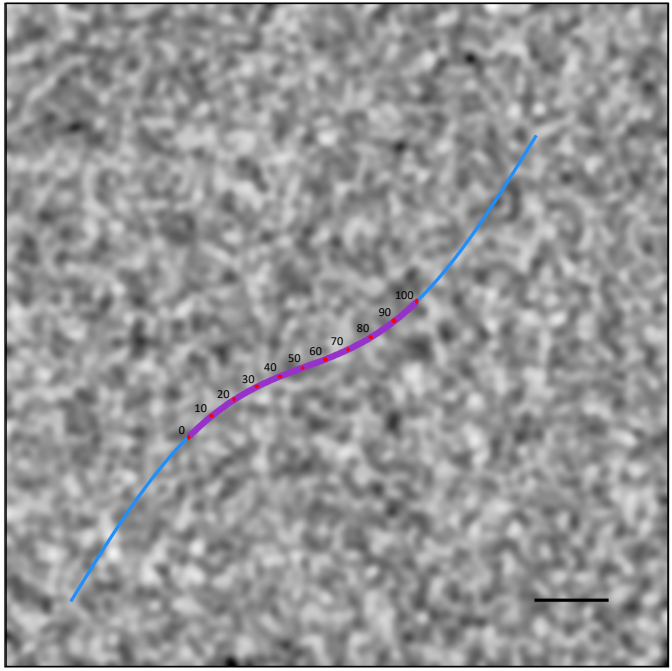



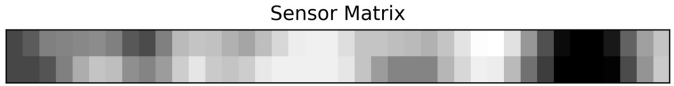



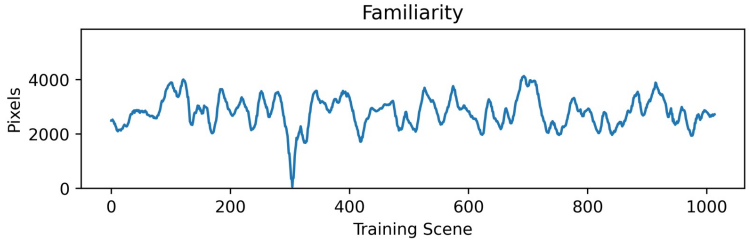

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

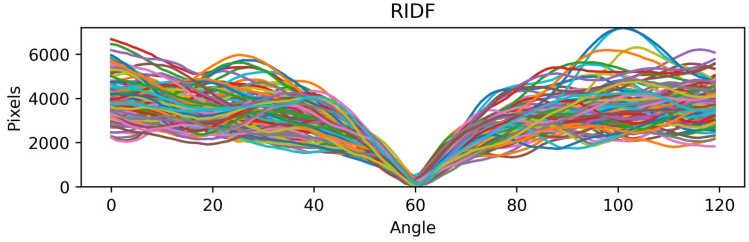
Navigation stats: RMSD error: 52.03; RMSD/dist: 0.130; TD: 2705; p90: 34; p50: 18; complete: 0

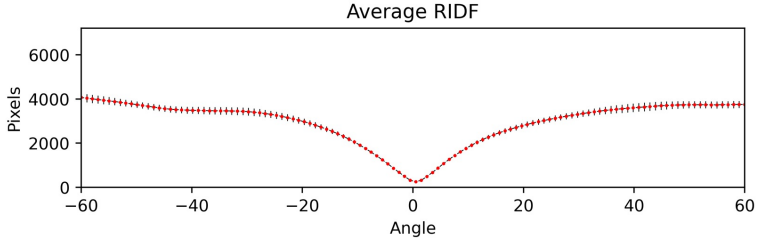
100%



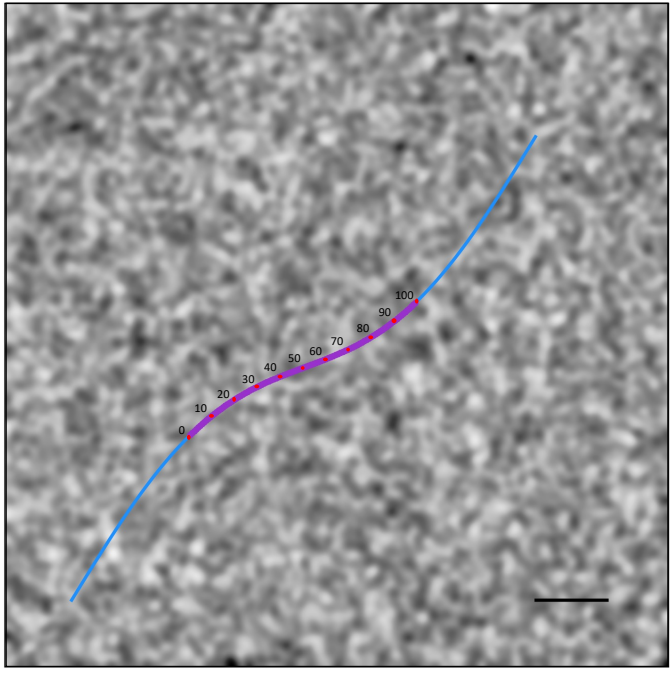



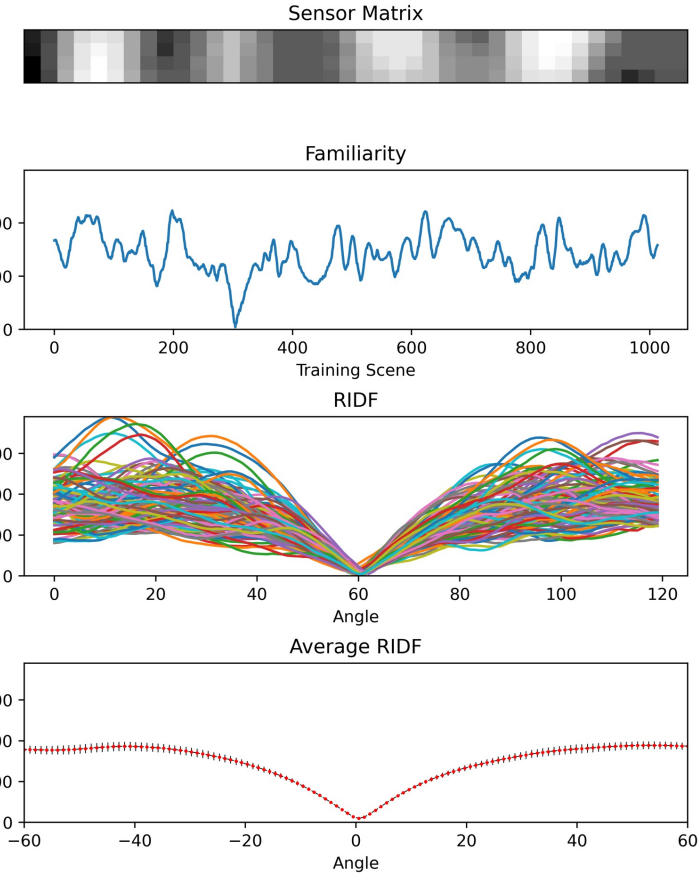




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 60.81; RMSD/dist: 0.152; TD: 2751; p90: 34; p50: 16; complete: 0

100%

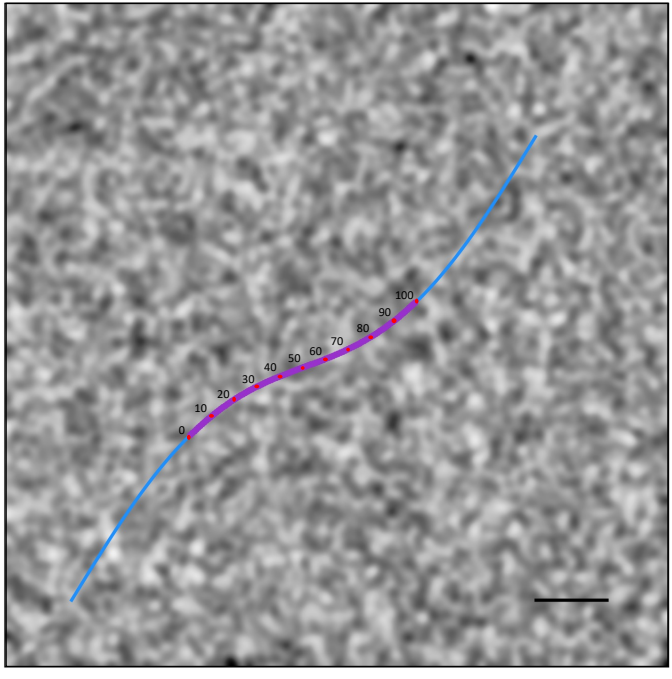


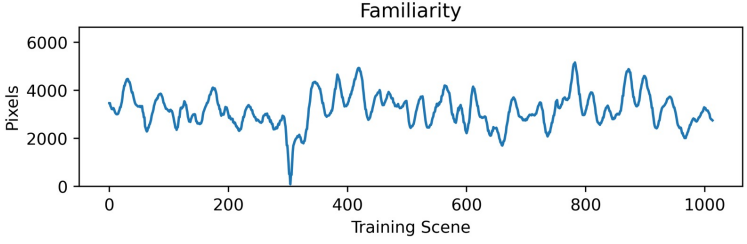



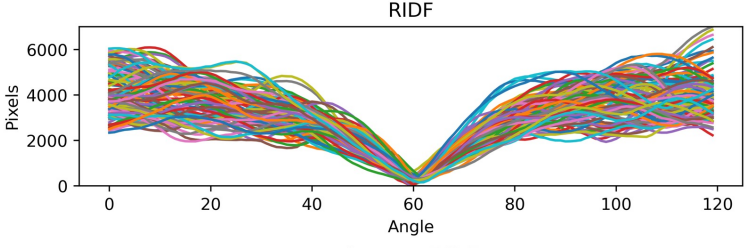

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

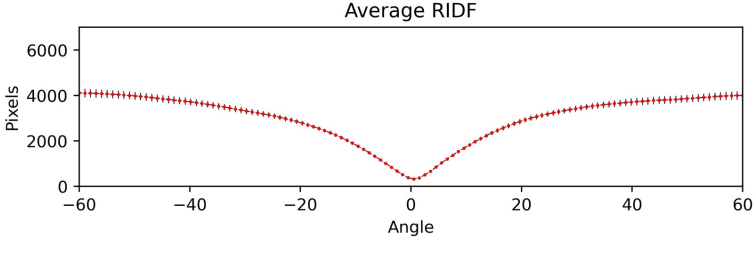
Navigation stats: RMSD error: 42.76; RMSD/dist: 0.107; TD: 2845; p90: 38; p50: 18; complete: 0

100%





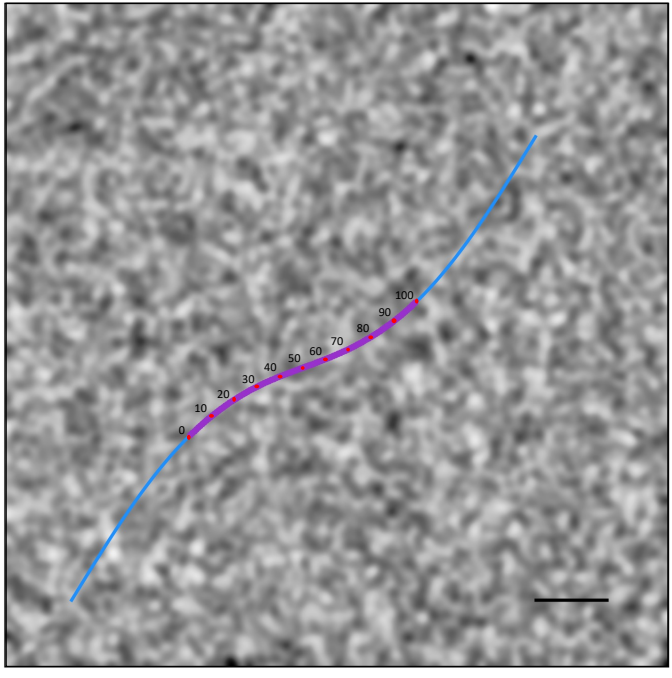



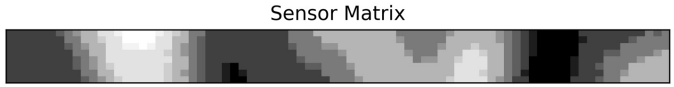



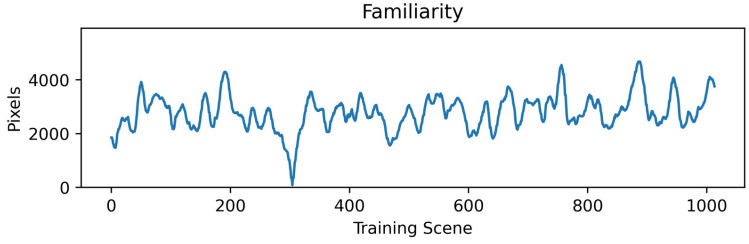

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

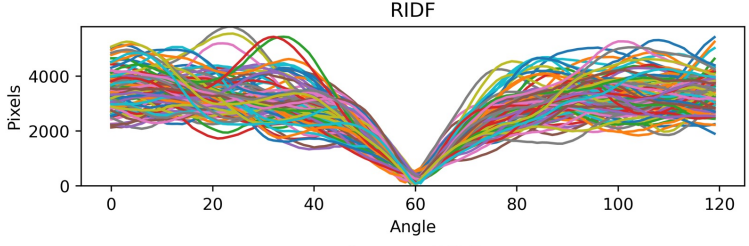
Navigation stats: RMSD error: 94.48; RMSD/dist: 0.236; TD: 3052; p90: 48; p50: 22; complete: 0

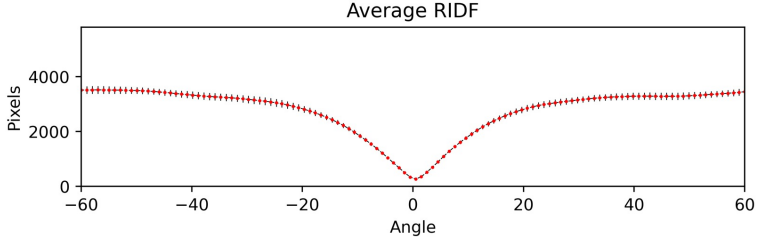
100%



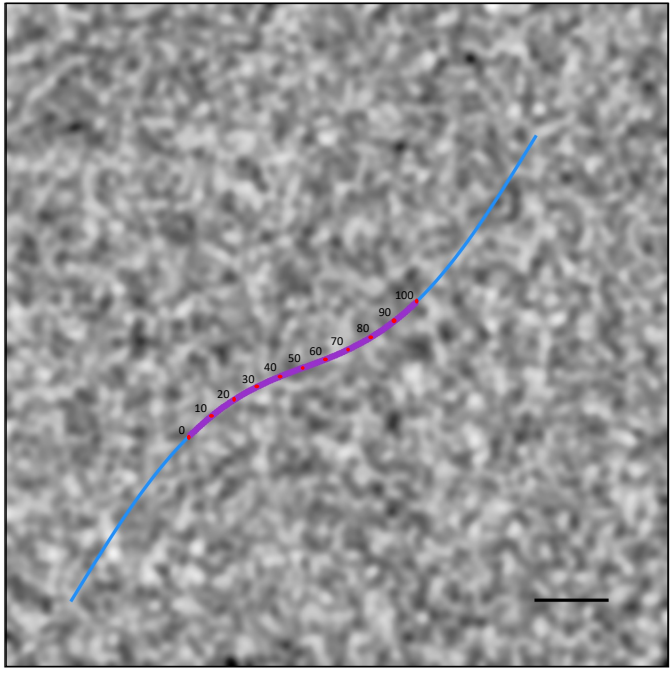



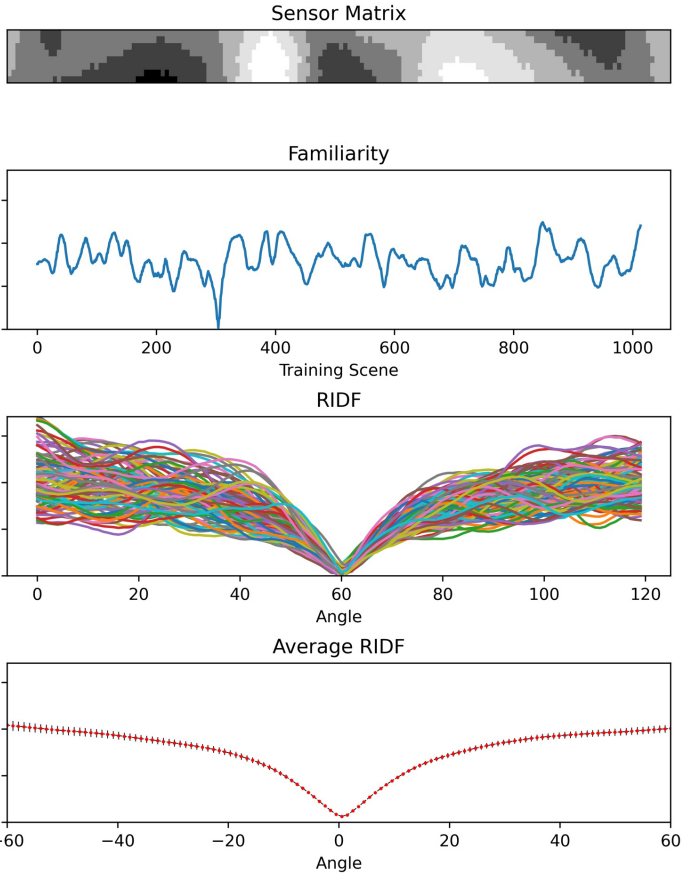




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 76.04; RMSD/dist: 0.190; TD: 2773; p90: 38; p50: 18; complete: 0

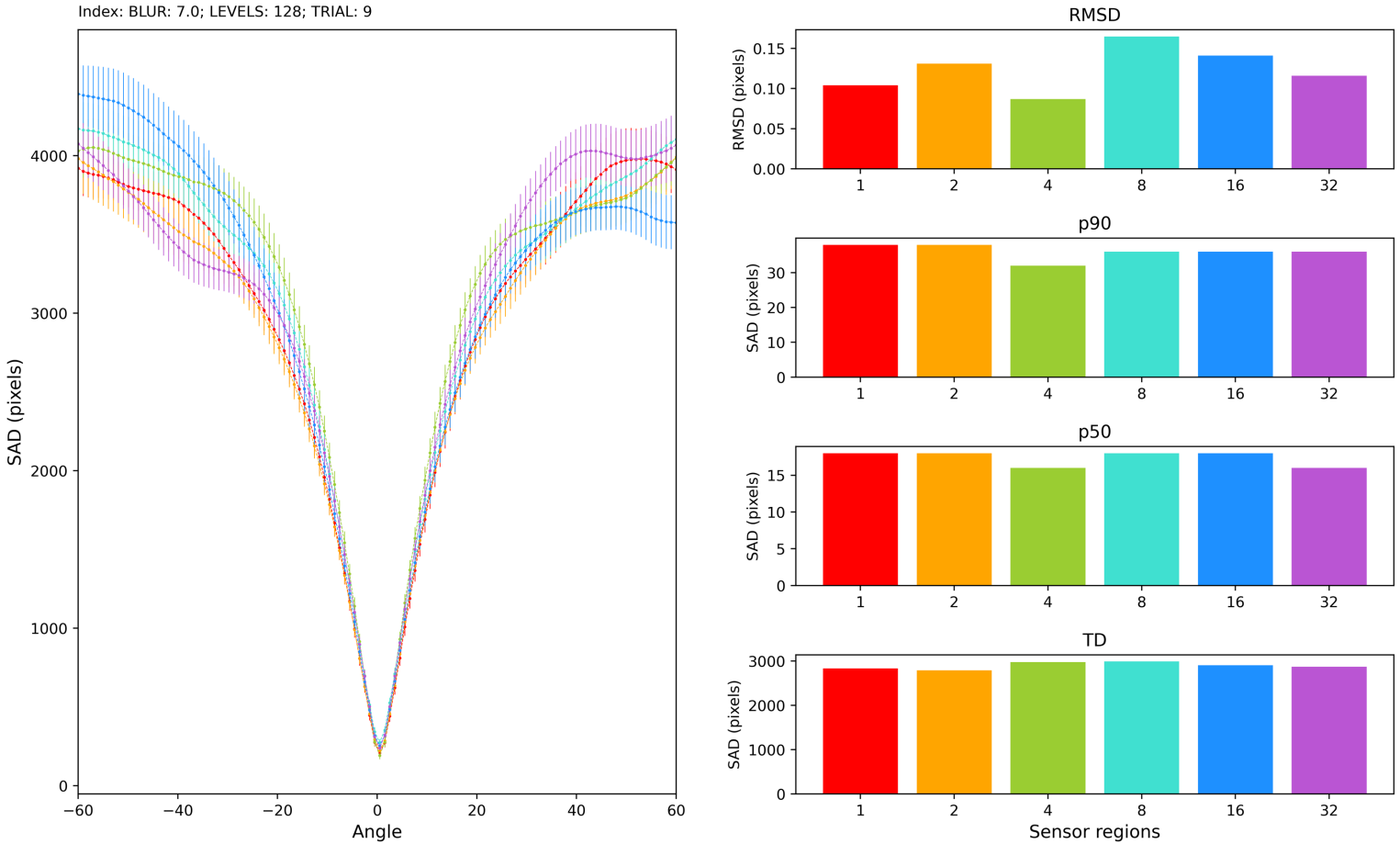
100%



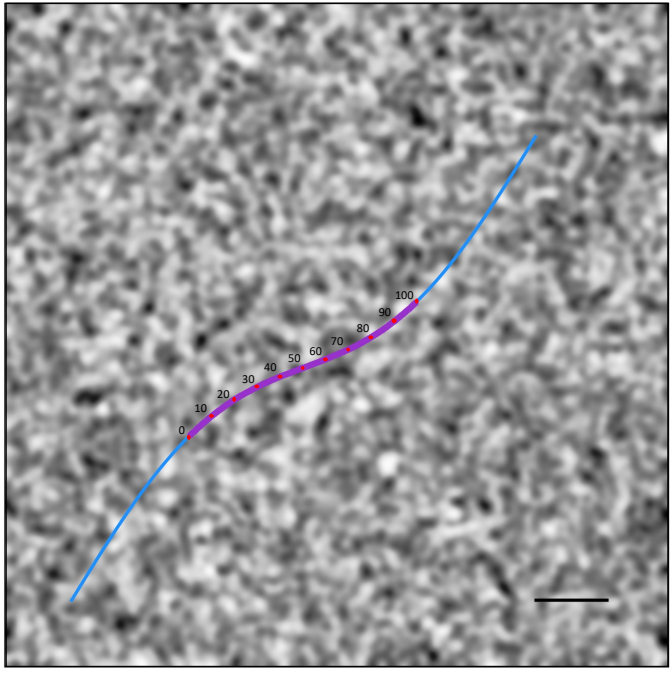



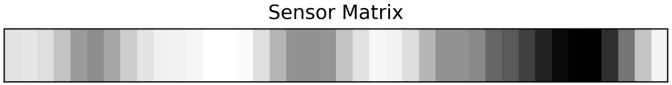

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

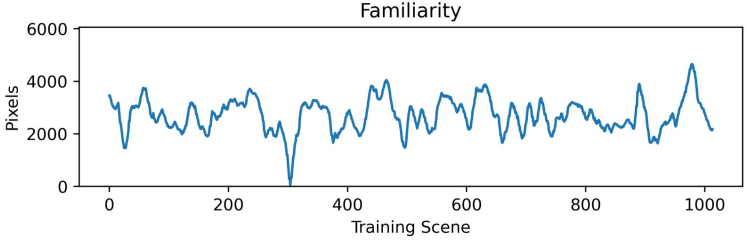
Navigation stats: RMSD error: 56.56; RMSD/dist: 0.141; TD: 3050; p90: 42; p50: 18; complete: 0

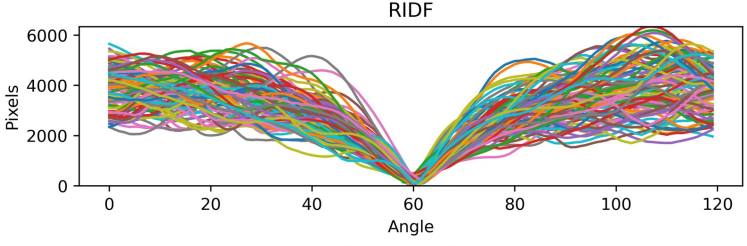

Index: BLUR: 7.0; LEVELS: 128; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

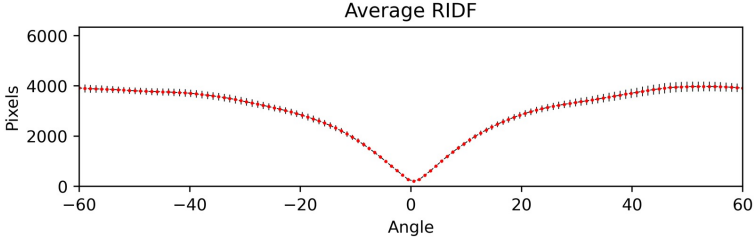
100%



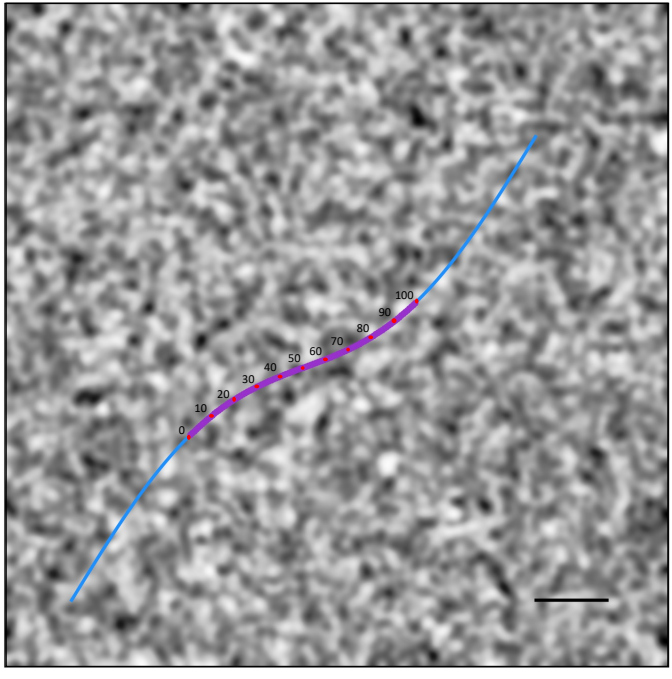



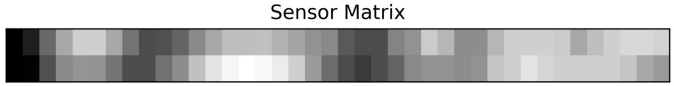



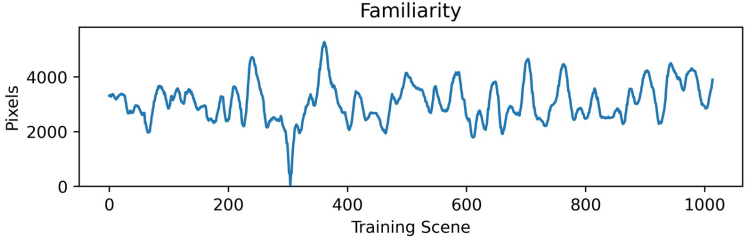

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

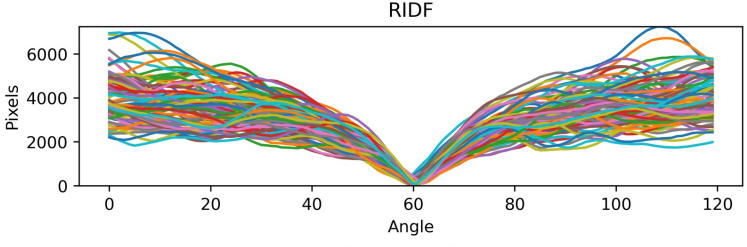
Navigation stats: RMSD error: 41.66; RMSD/dist: 0.104; TD: 2835; p90: 38; p50: 18; complete: 0

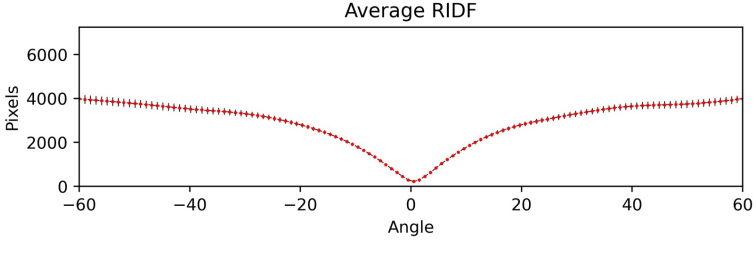
100%



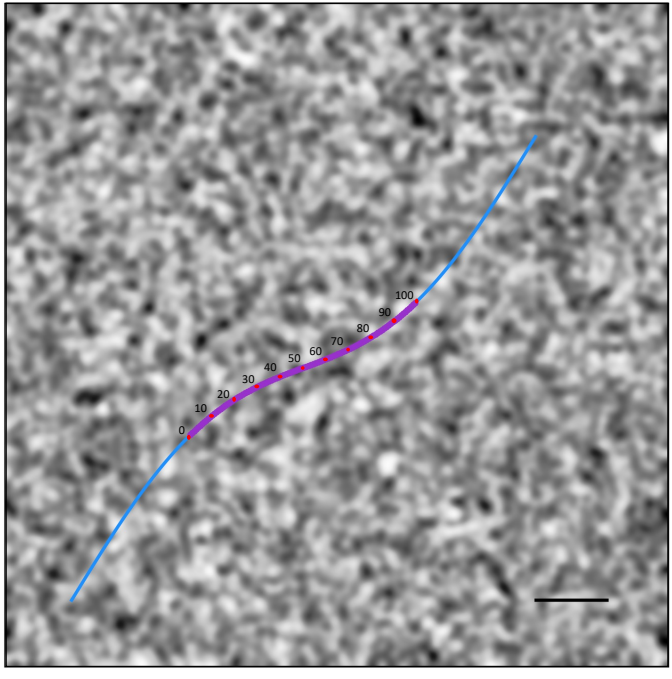



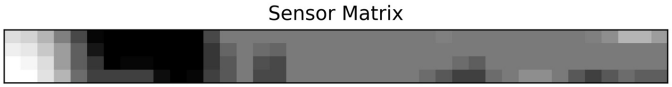



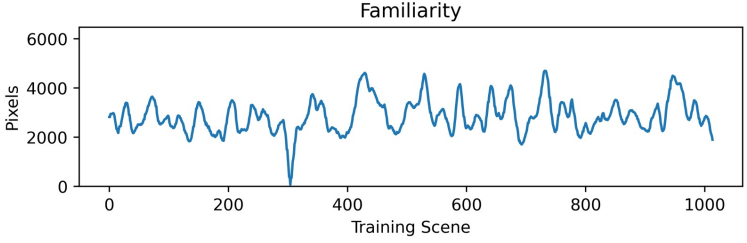

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

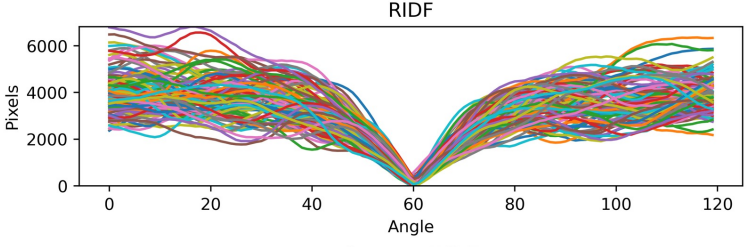
Navigation stats: RMSD error: 52.60; RMSD/dist: 0.131; TD: 2789; p90: 38; p50: 18; complete: 0

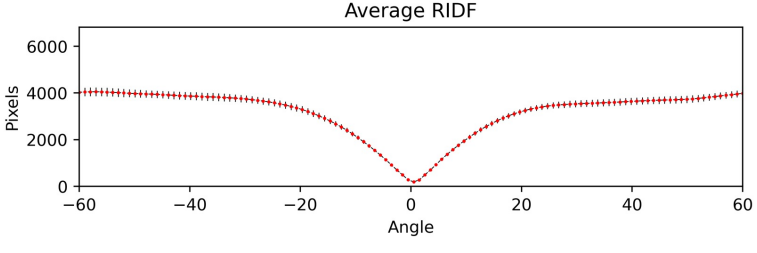
100%



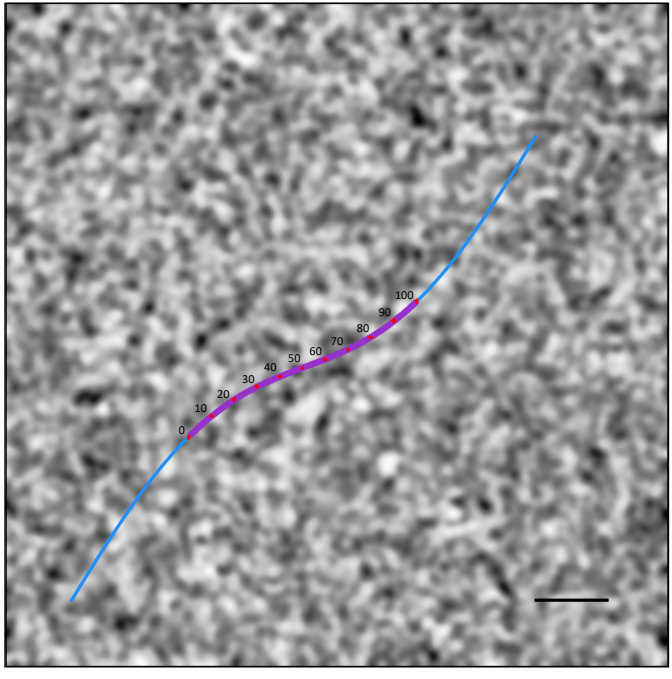



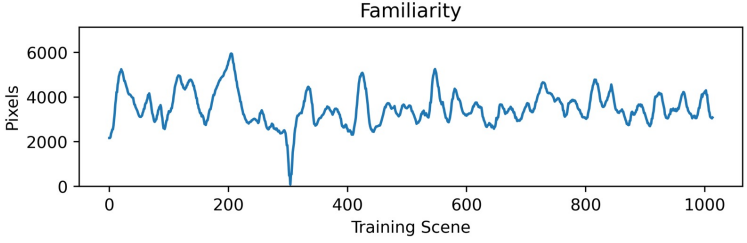



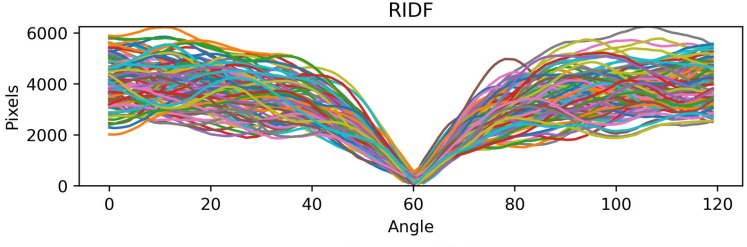

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

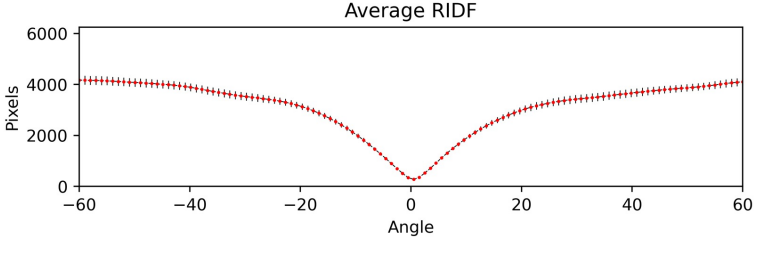
Navigation stats: RMSD error: 34.75; RMSD/dist: 0.087; TD: 2979; p90: 32; p50: 16; complete: 0

100%





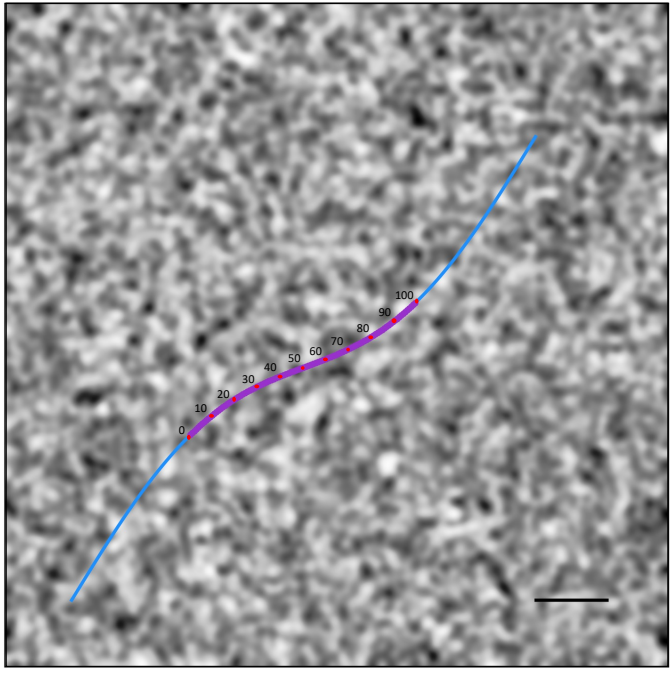



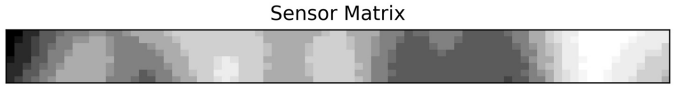



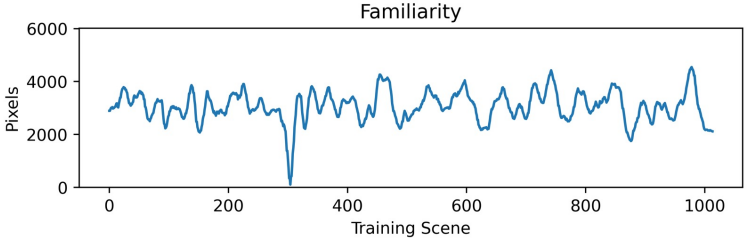

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

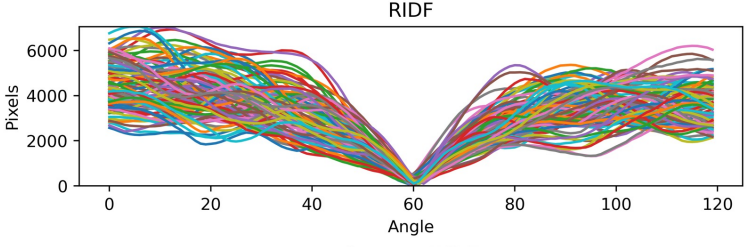
Navigation stats: RMSD error: 65.99; RMSD/dist: 0.165; TD: 2989; p90: 36; p50: 18; complete: 0

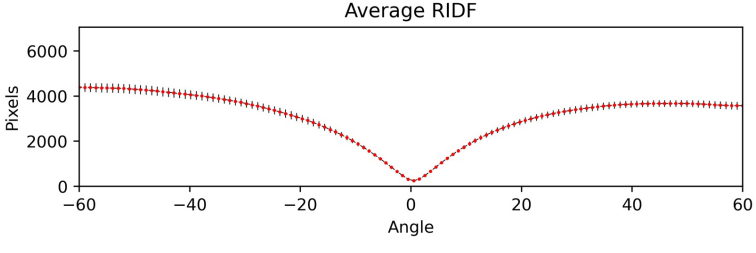
100%



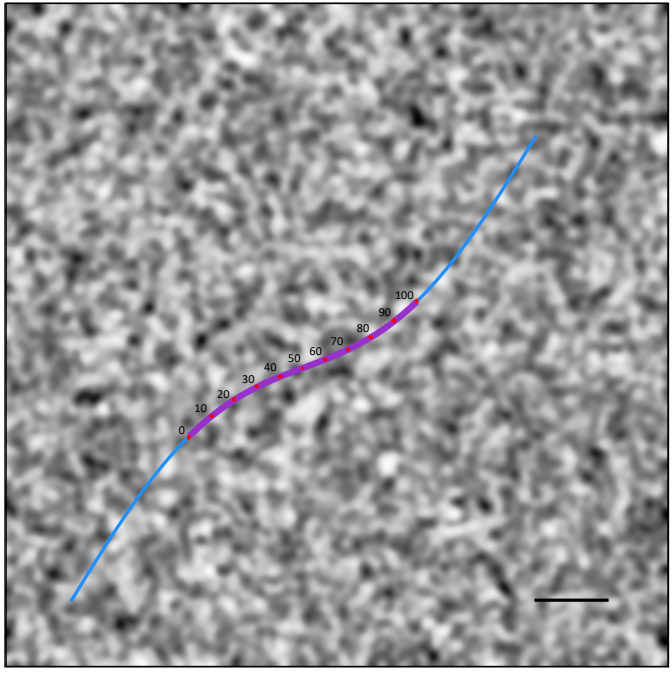



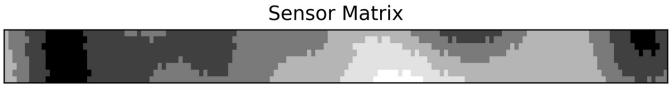



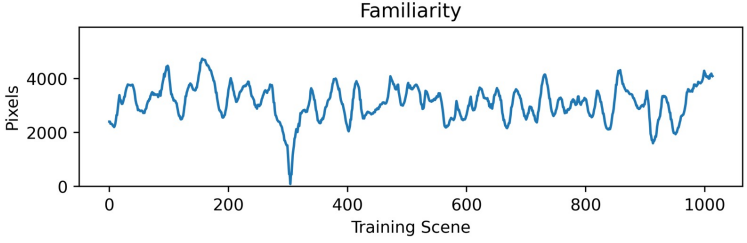

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

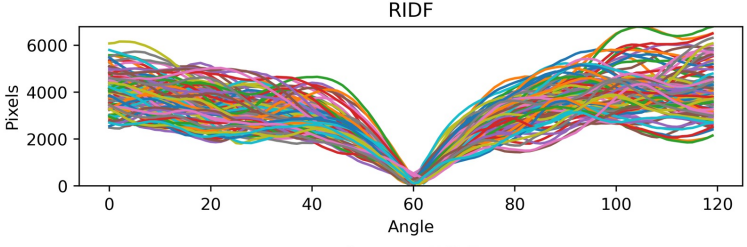
Navigation stats: RMSD error: 56.31; RMSD/dist: 0.141; TD: 2906; p90: 36; p50: 18; complete: 0

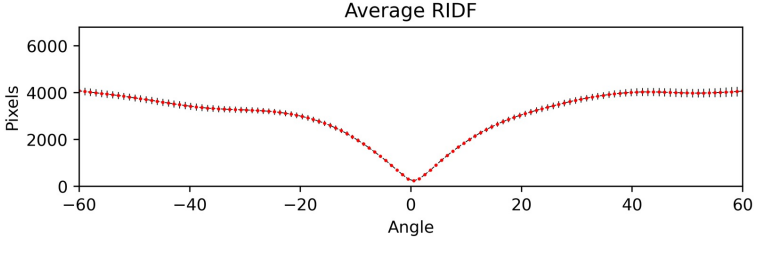
100%



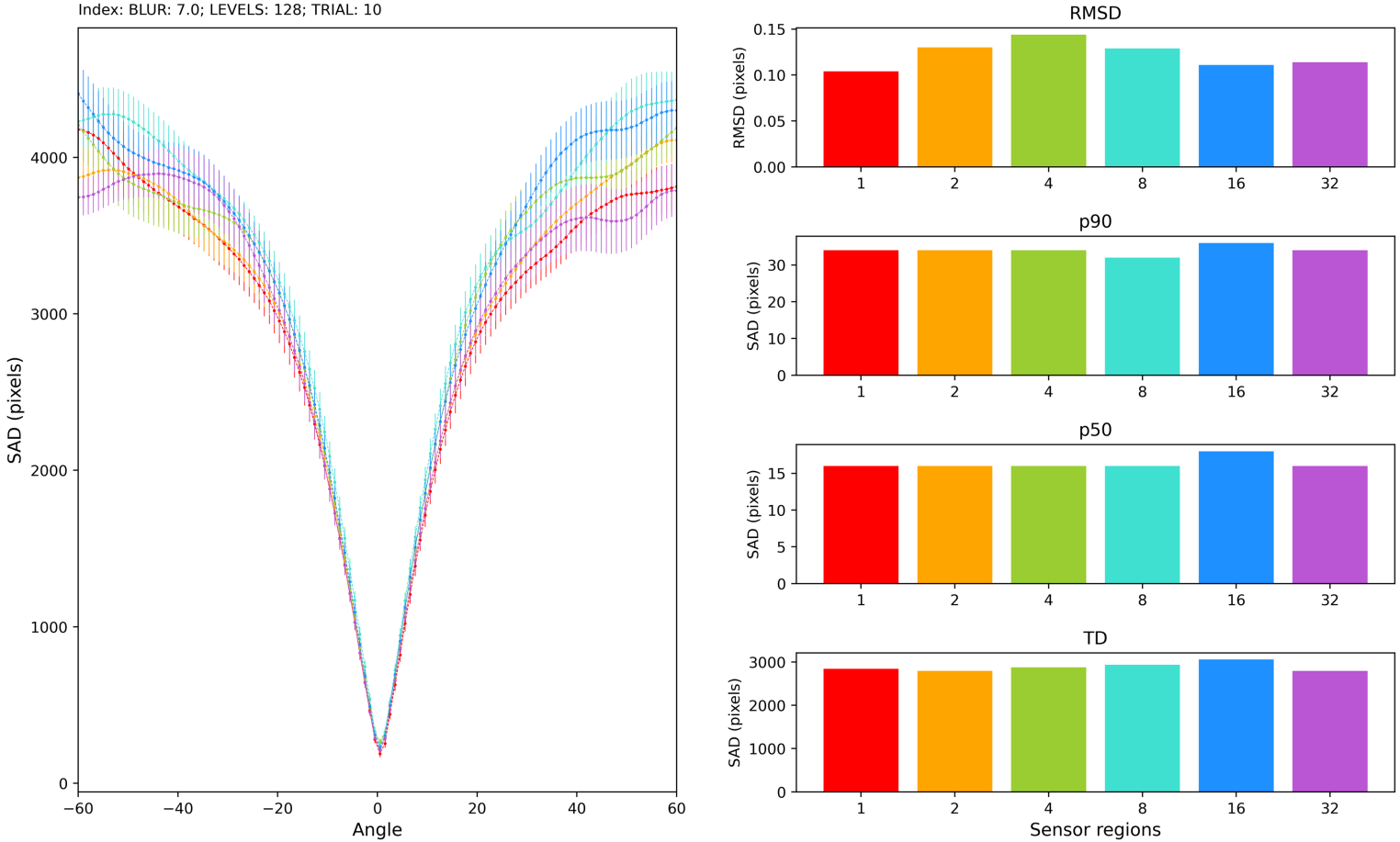



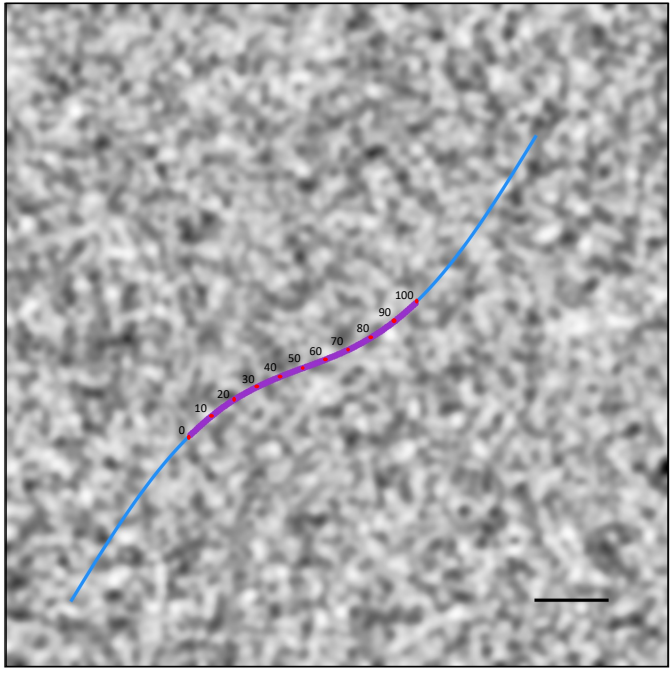



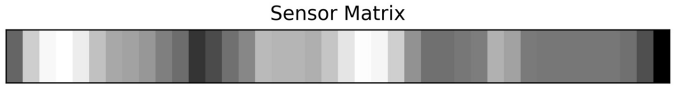

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

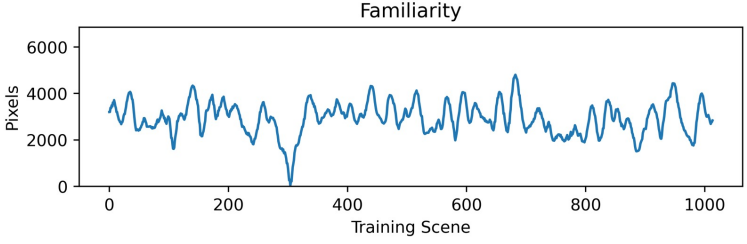
Navigation stats: RMSD error: 46.44; RMSD/dist: 0.116; TD: 2874; p90: 36; p50: 16; complete: 0

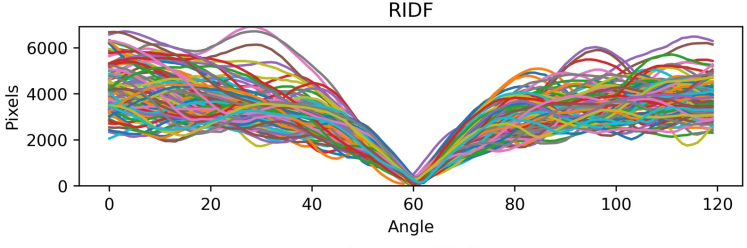

Index: BLUR: 7.0; LEVELS: 128; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

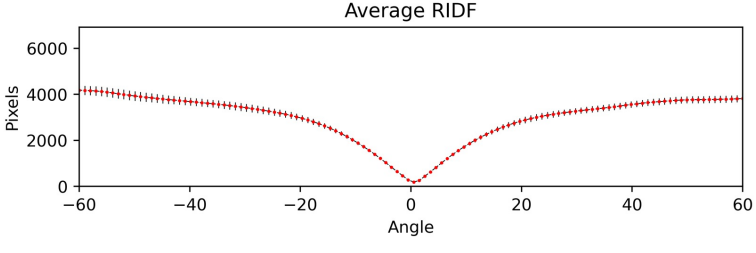
100%



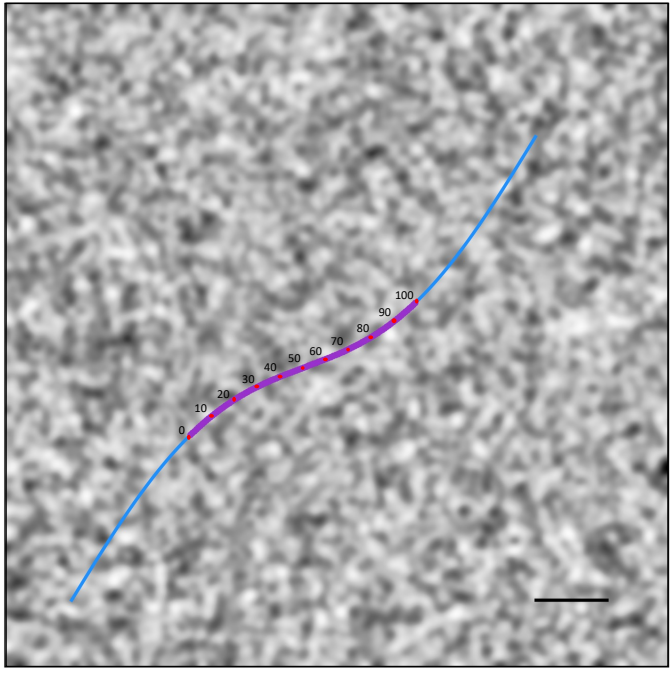



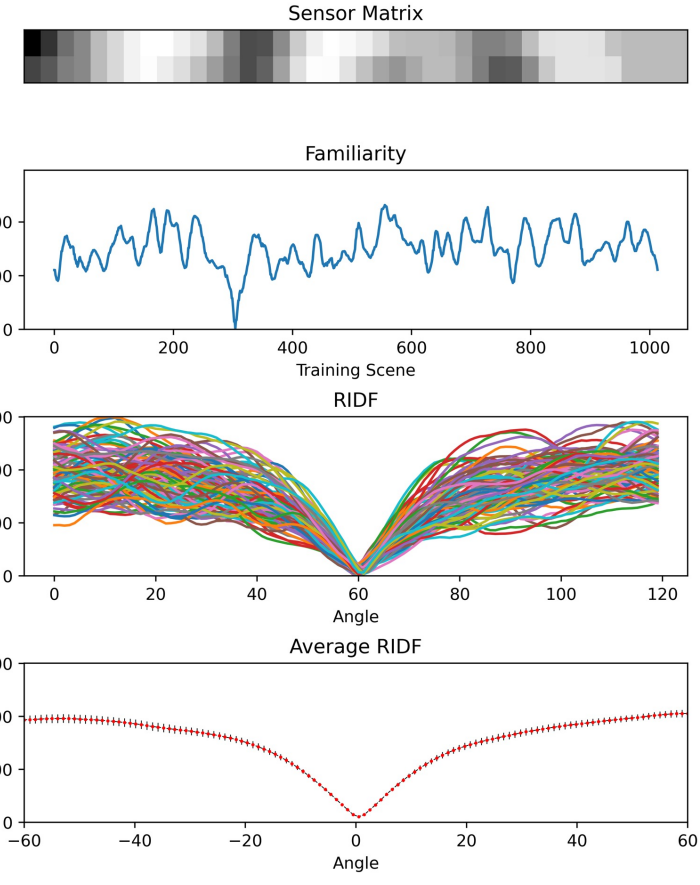




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 41.57; RMSD/dist: 0.104; TD: 2845; p90: 34; p50: 16; complete: 0

100%

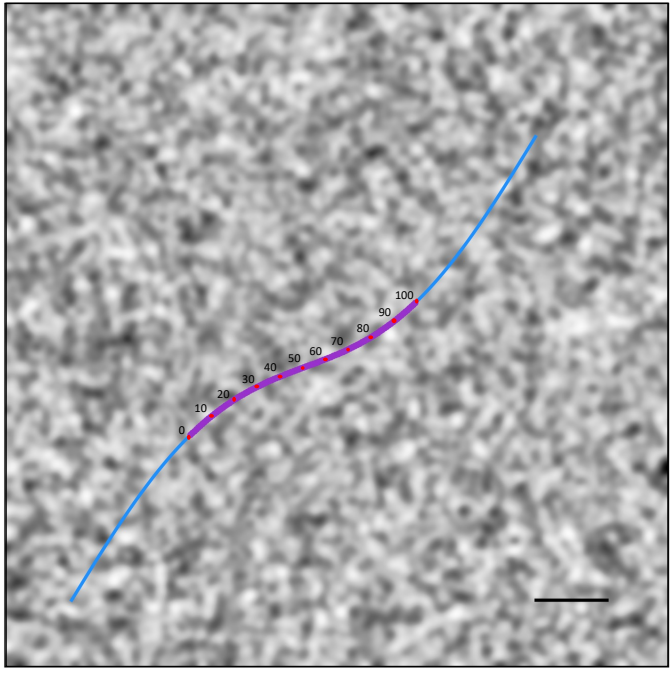


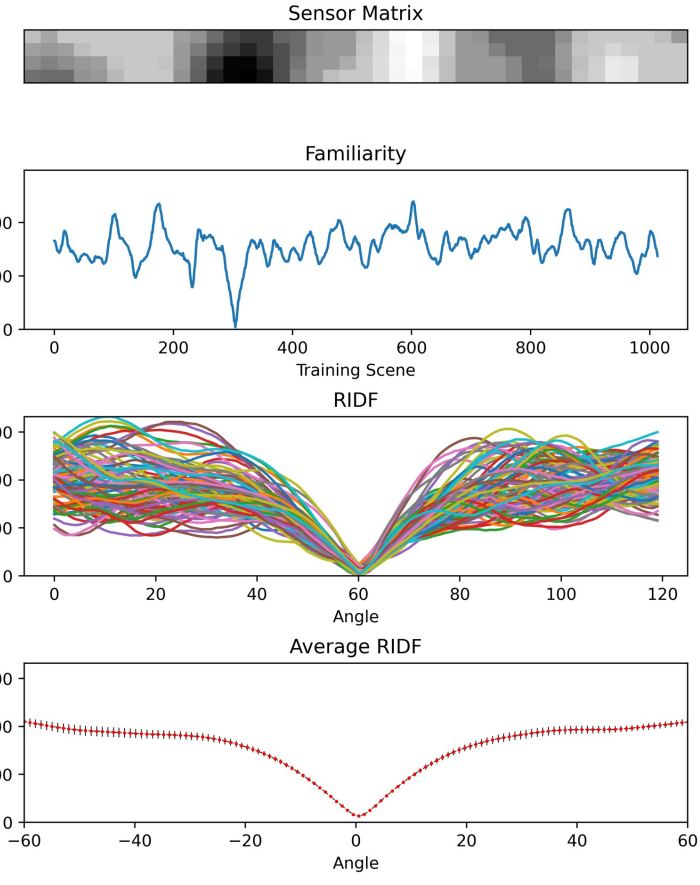




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 51.93; RMSD/dist: 0.130; TD: 2794; p90: 34; p50: 16; complete: 0

100%

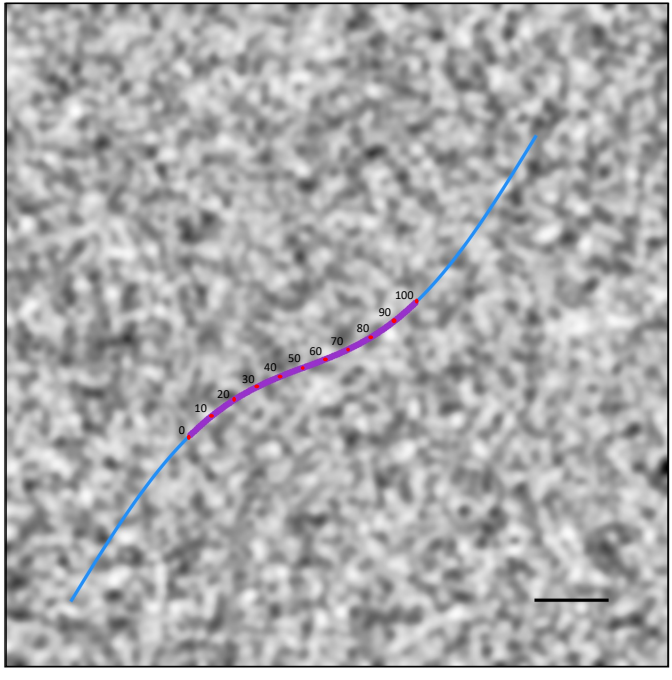


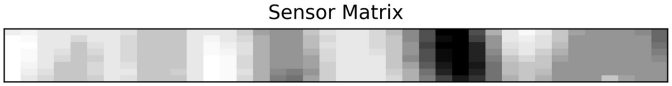



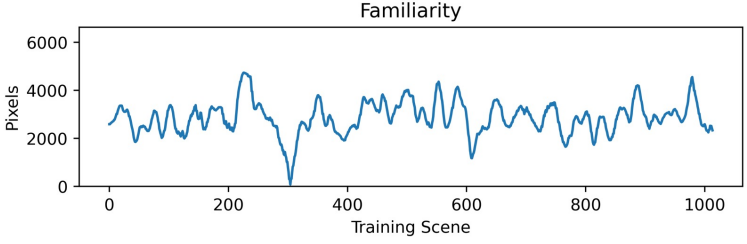

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

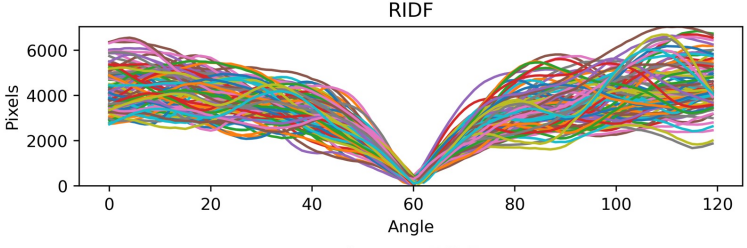
Navigation stats: RMSD error: 57.53; RMSD/dist: 0.144; TD: 2877; p90: 34; p50: 16; complete: 0

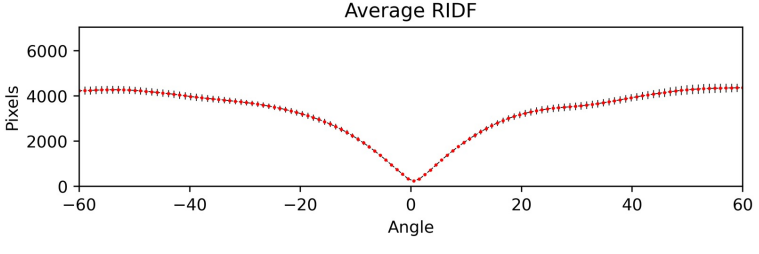
100%



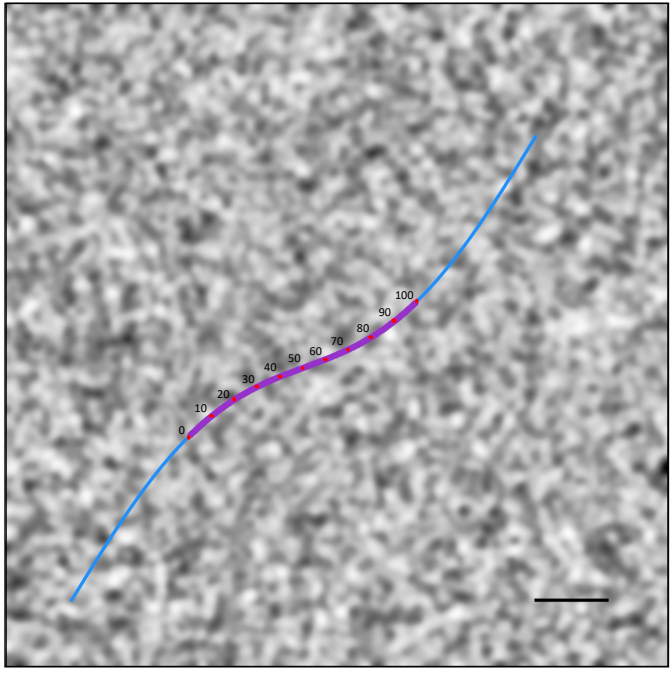



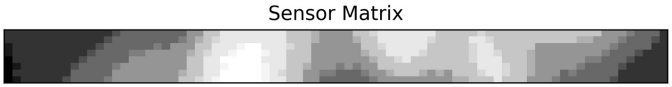



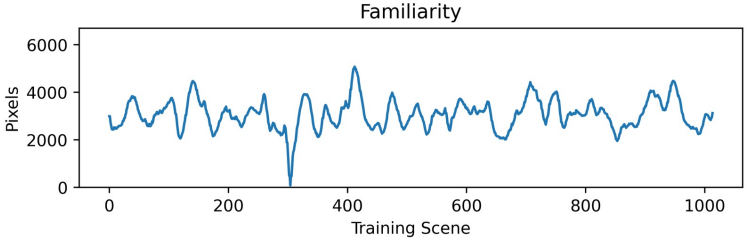

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

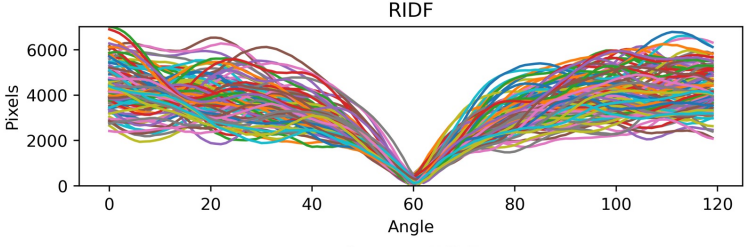
Navigation stats: RMSD error: 51.49; RMSD/dist: 0.129; TD: 2935; p90: 32; p50: 16; complete: 0

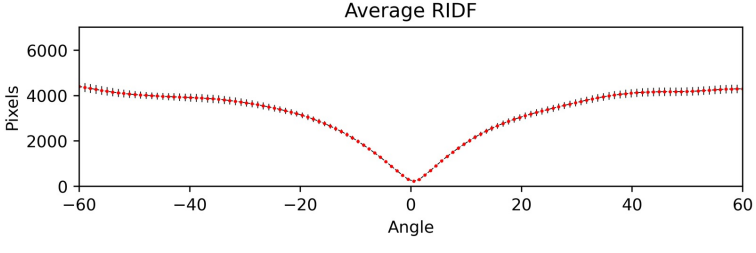
100%



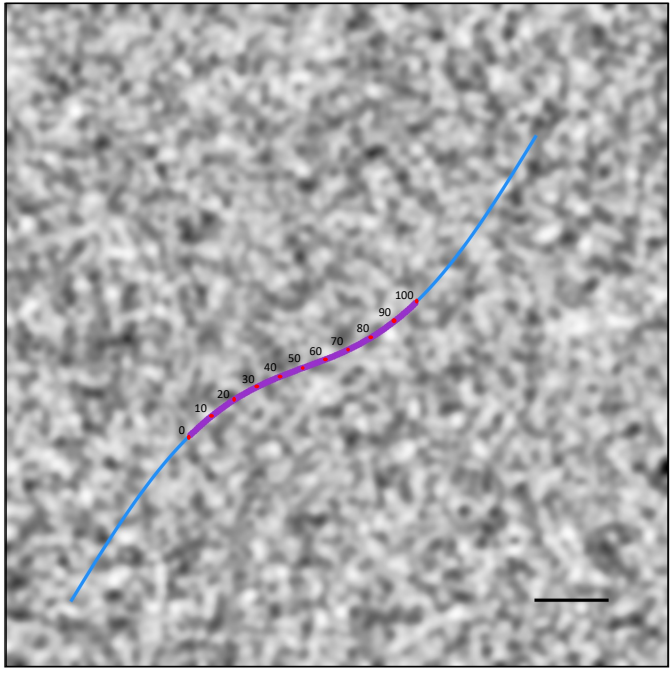



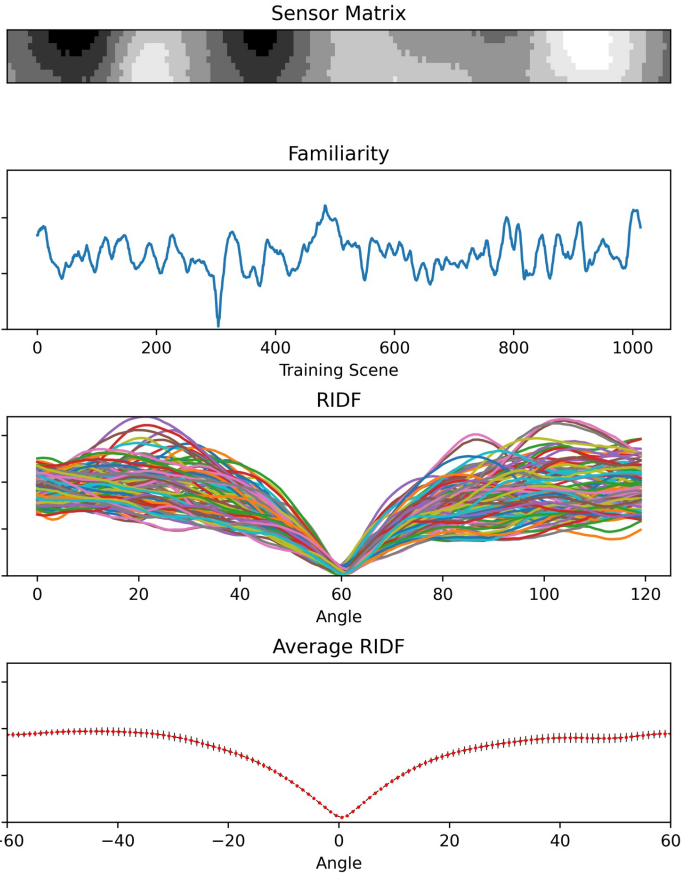




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 44.24; RMSD/dist: 0.111; TD: 3056; p90: 36; p50: 18; complete: 0

100%




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 7; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 45.61; RMSD/dist: 0.114; TD: 2792; p90: 34; p50: 16; complete: 0