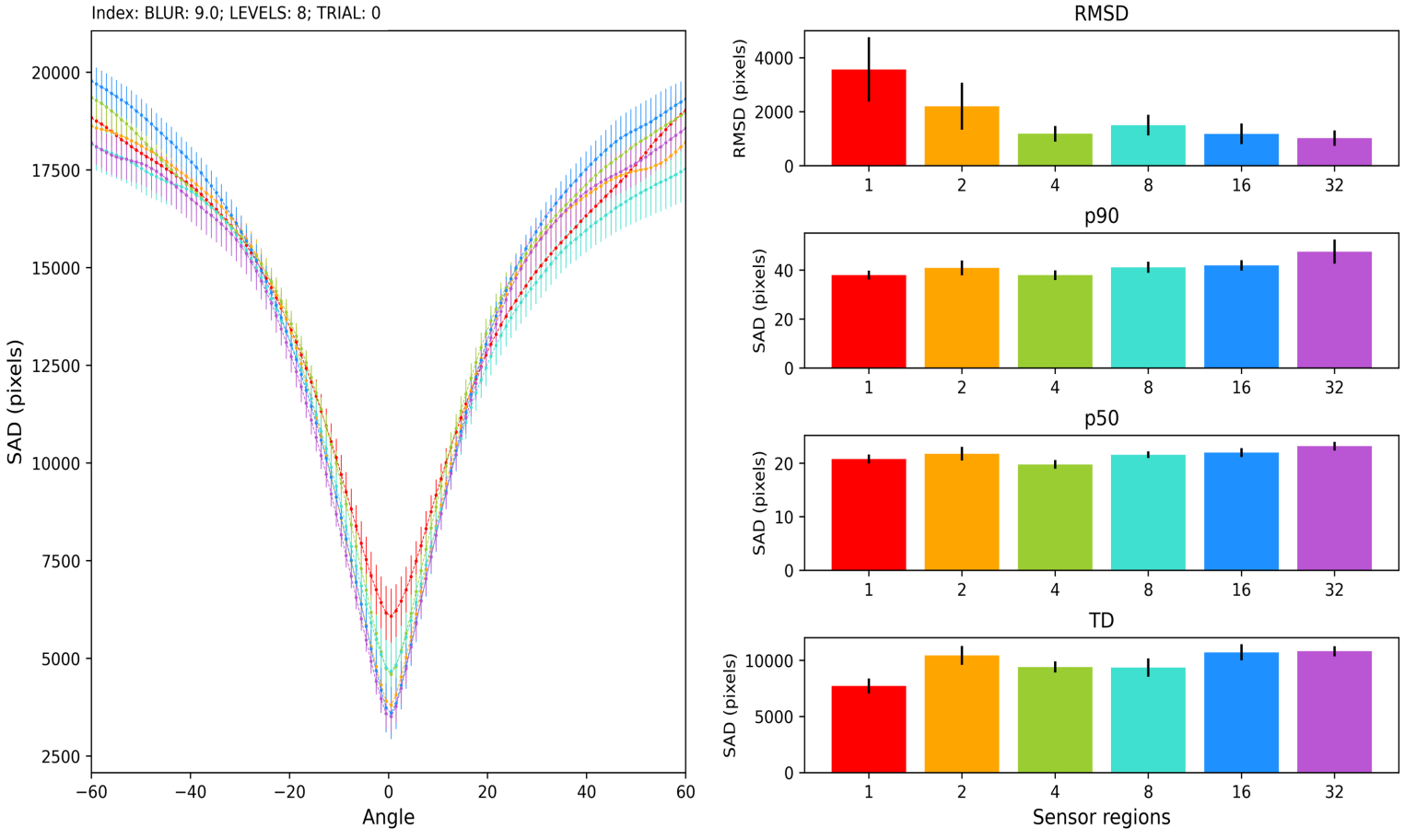
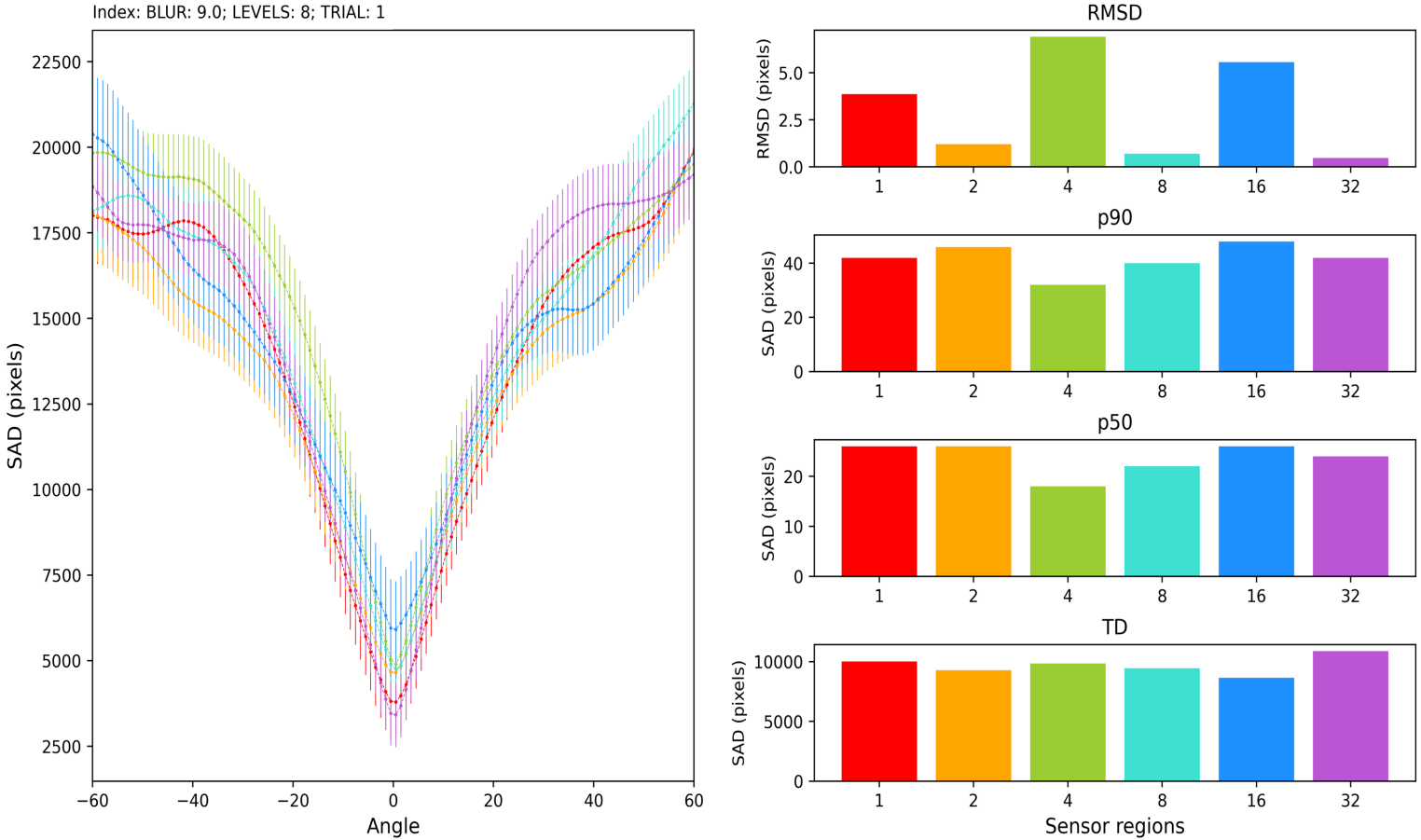
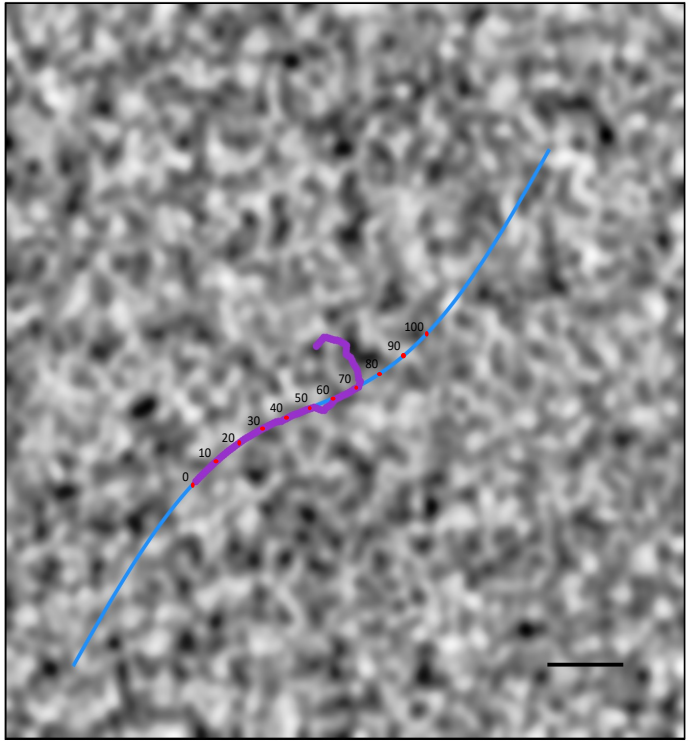
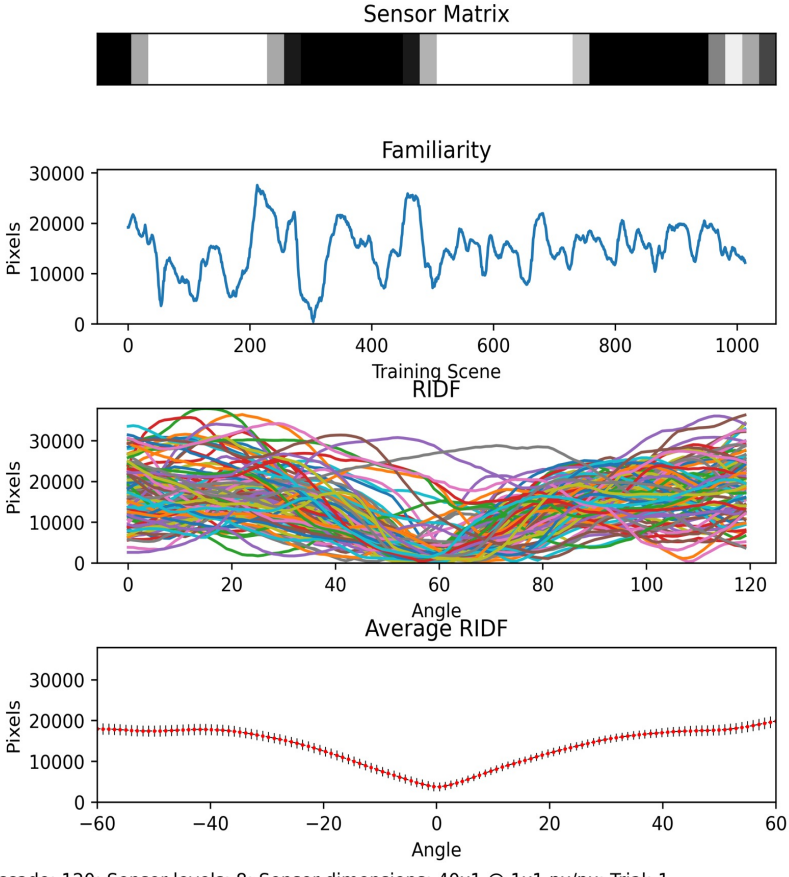

Index: BLUR: 9.0; LEVELS: 8; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 9.0; LEVELS: 8; TRIAL: 1
SAD (pixels)
22500
20000
17500
15000
12500
10000
7500
5000
2500
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
5.0
2.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
40
20
0
p50
SAD (pixels)
20
10
0
TD
SAD (pixels)
10000
5000
0
Sensor regions

50%

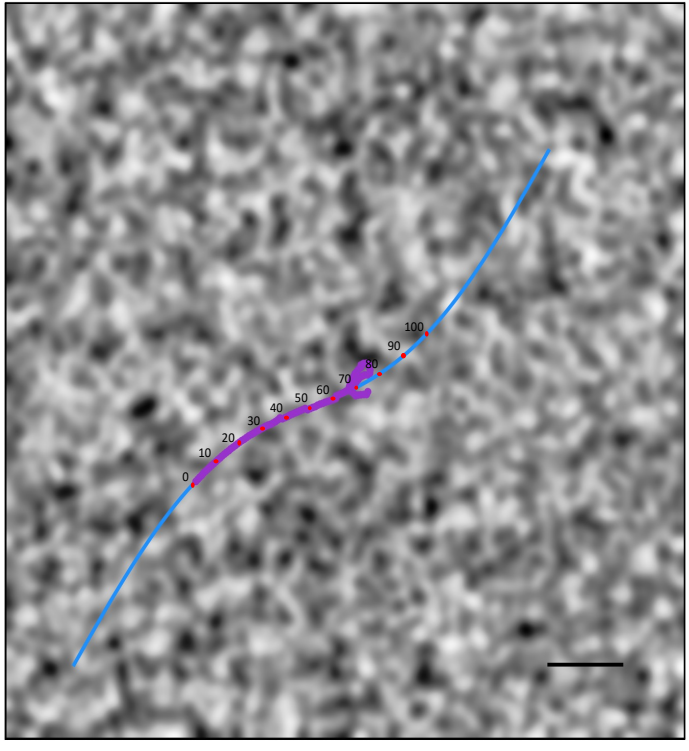


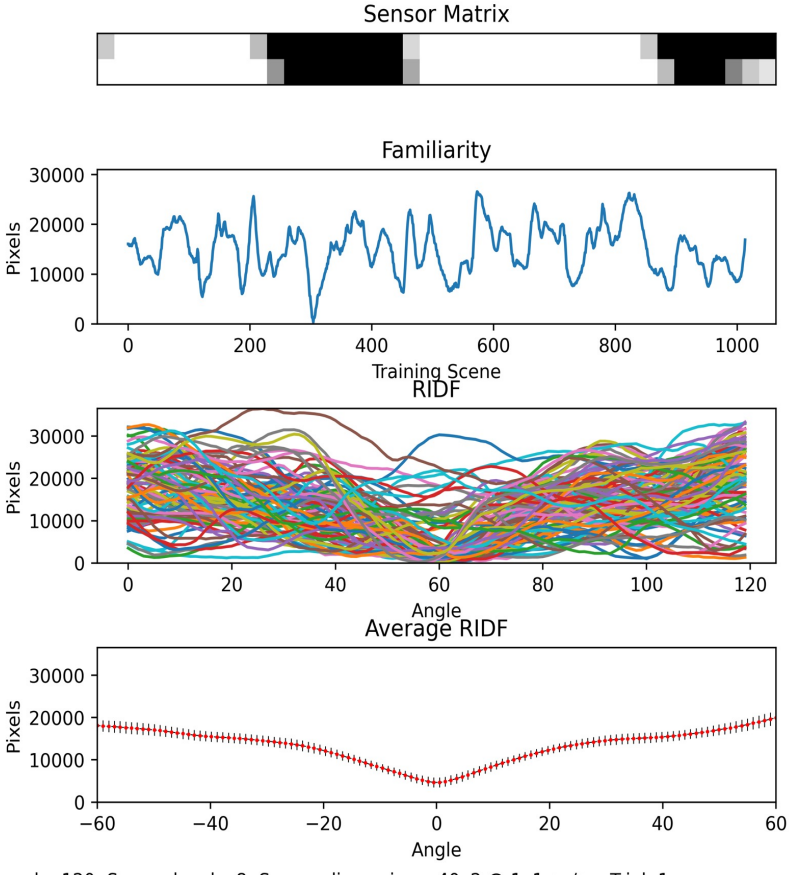


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1547.53; RMSD/dist: 3.869; TD: 10002; p90: 42; p50: 26; complete: 0

60%

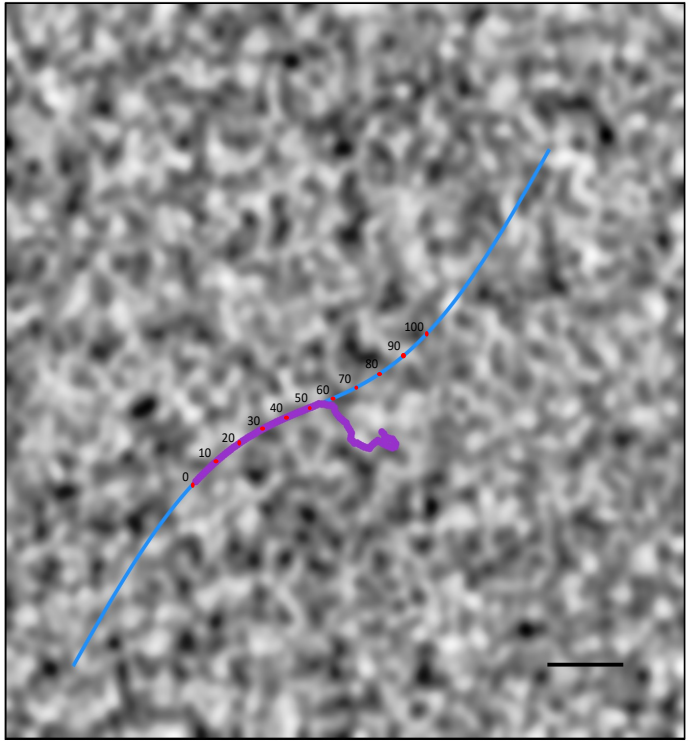


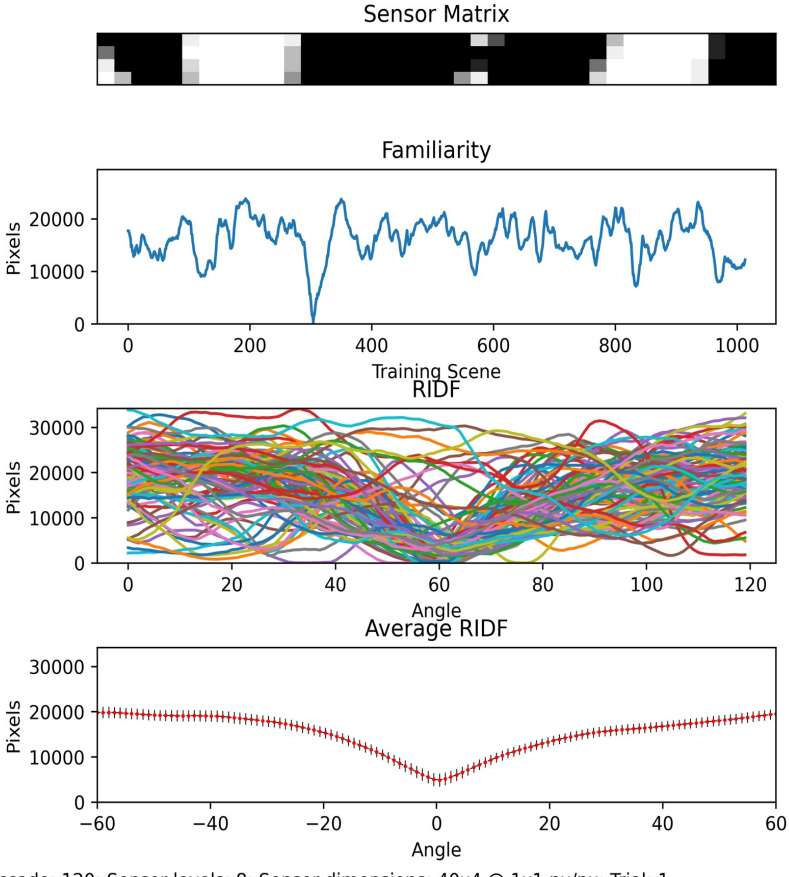


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 480.35; RMSD/dist: 1.201; TD: 9276; p90: 46; p50: 26; complete: 0

50%

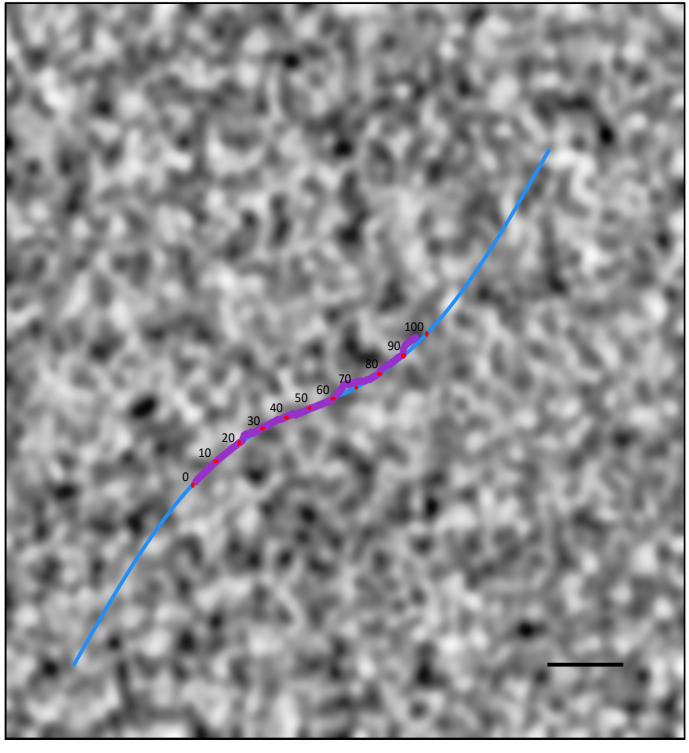


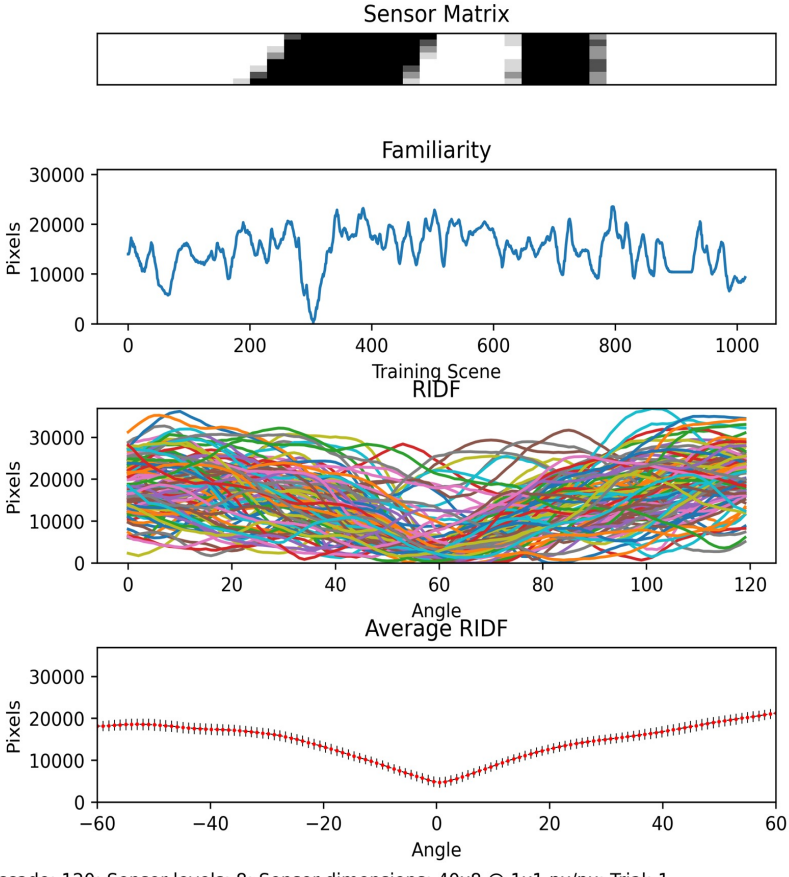


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2767.54; RMSD/dist: 6.919; TD: 9849; p90: 32; p50: 18; complete: 0

40%

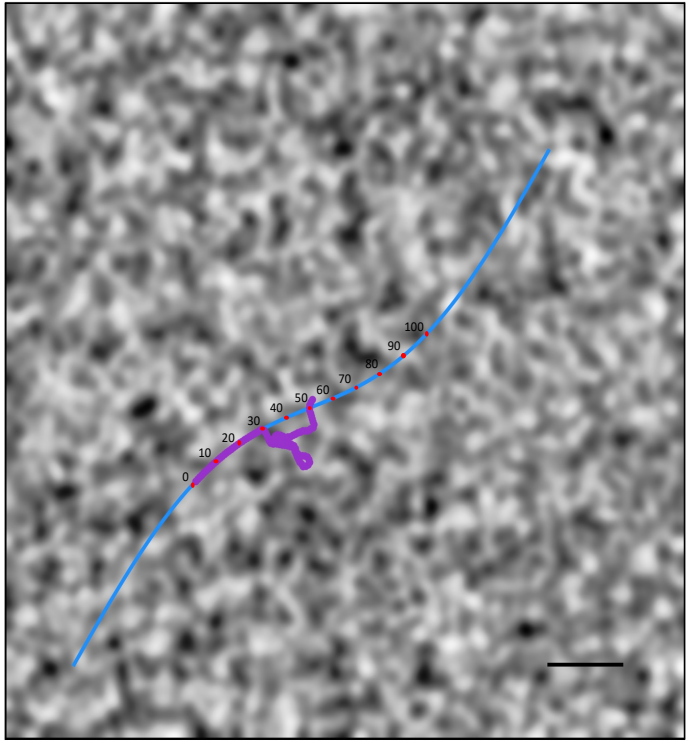


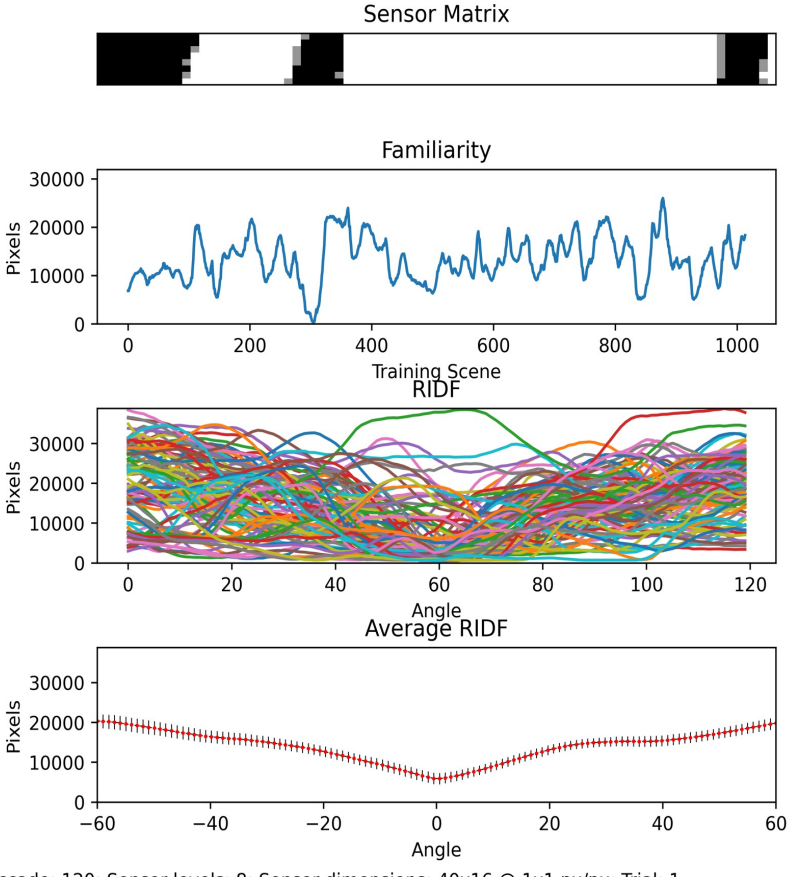


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 280.57; RMSD/dist: 0.701; TD: 9444; p90: 40; p50: 22; complete: 0

30%

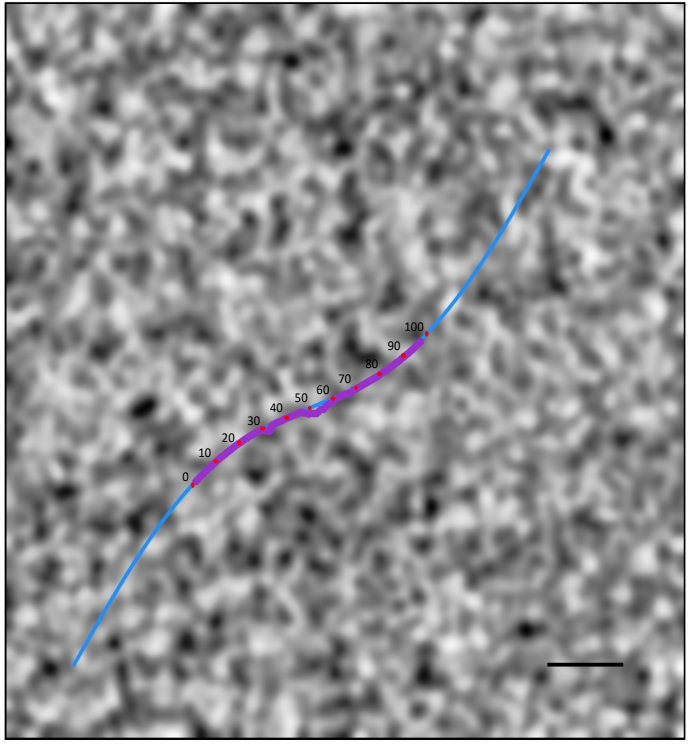


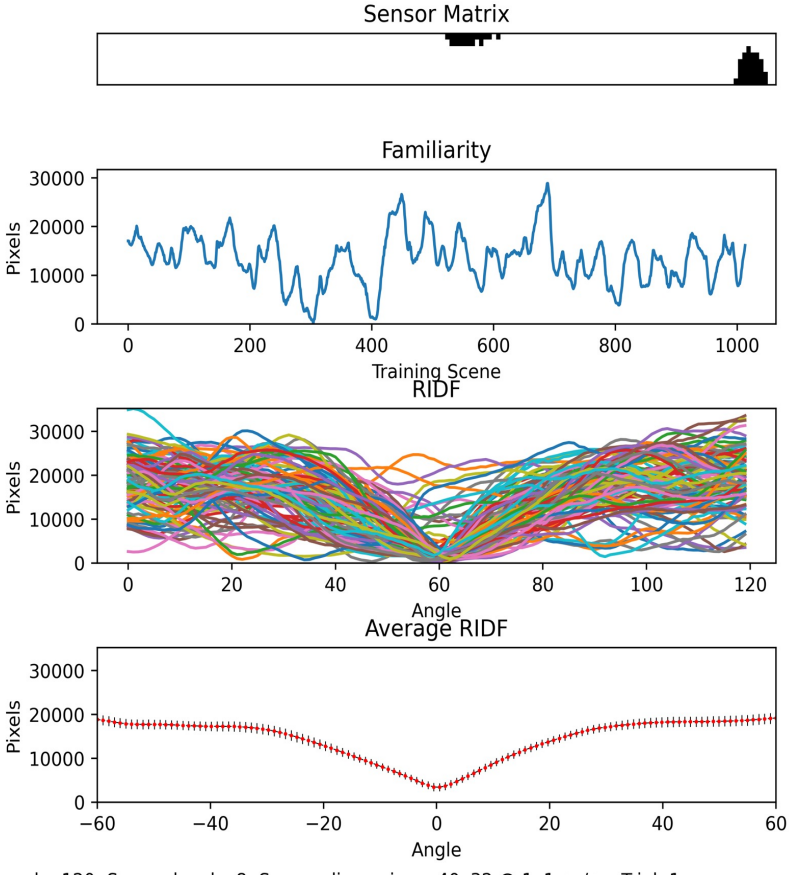


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2226.32; RMSD/dist: 5.566; TD: 8646; p90: 48; p50: 26; complete: 0

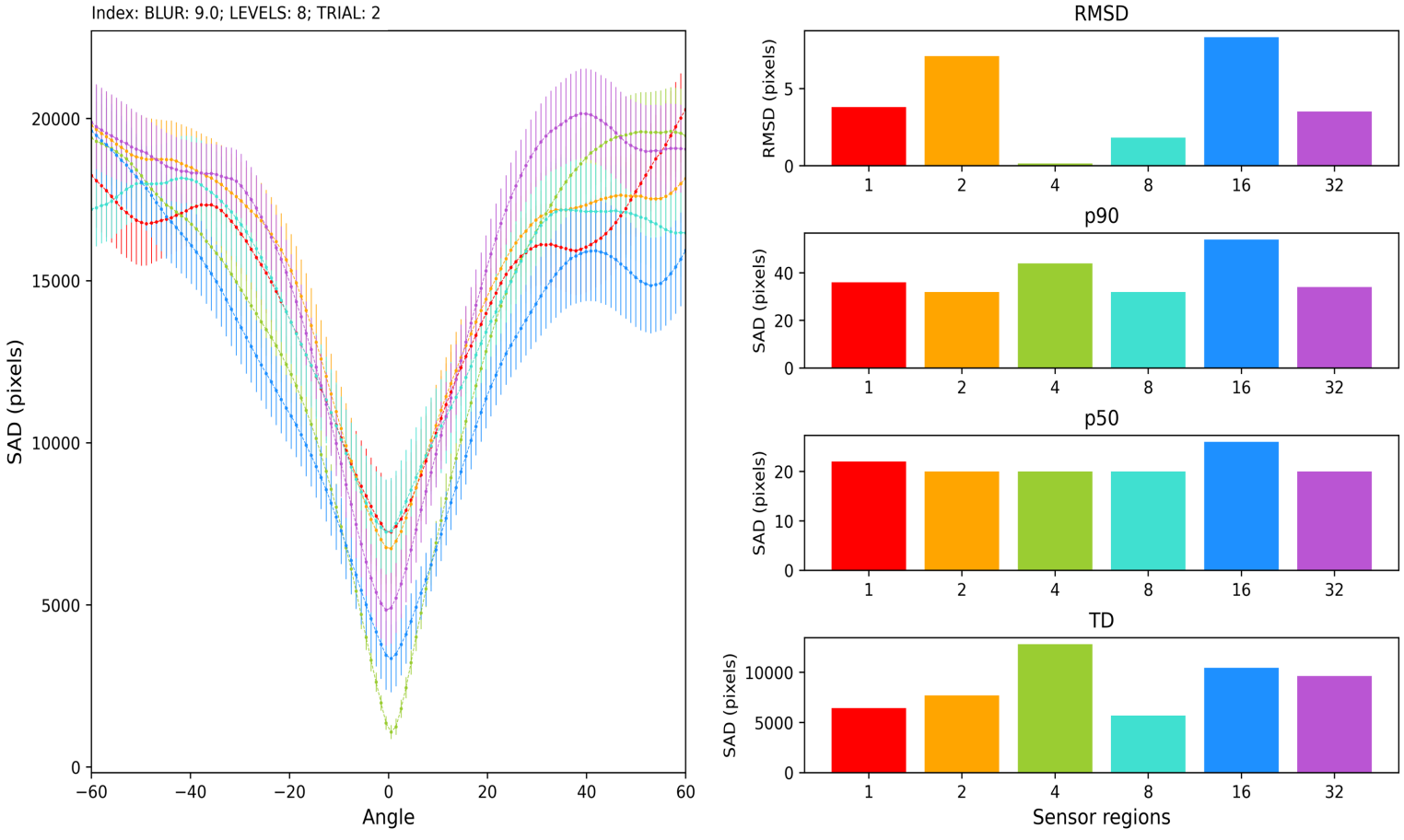
70%



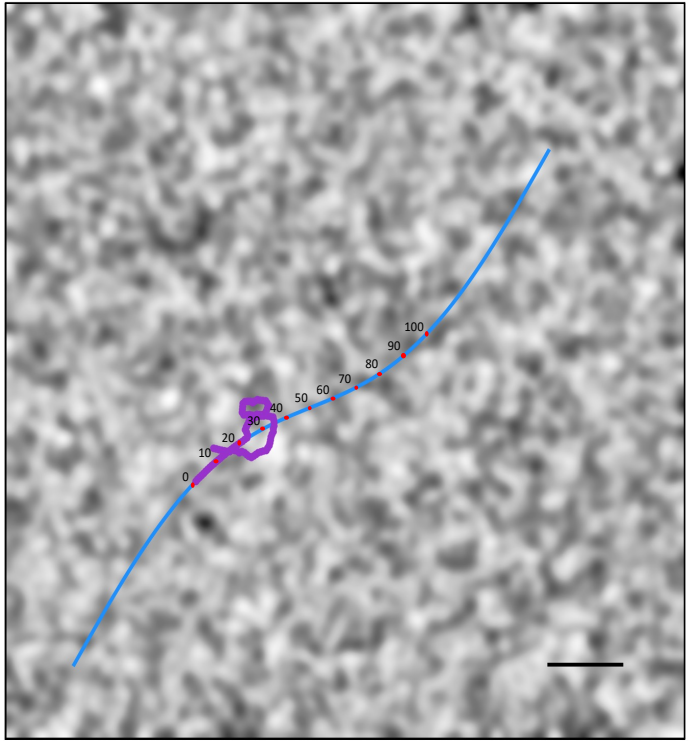


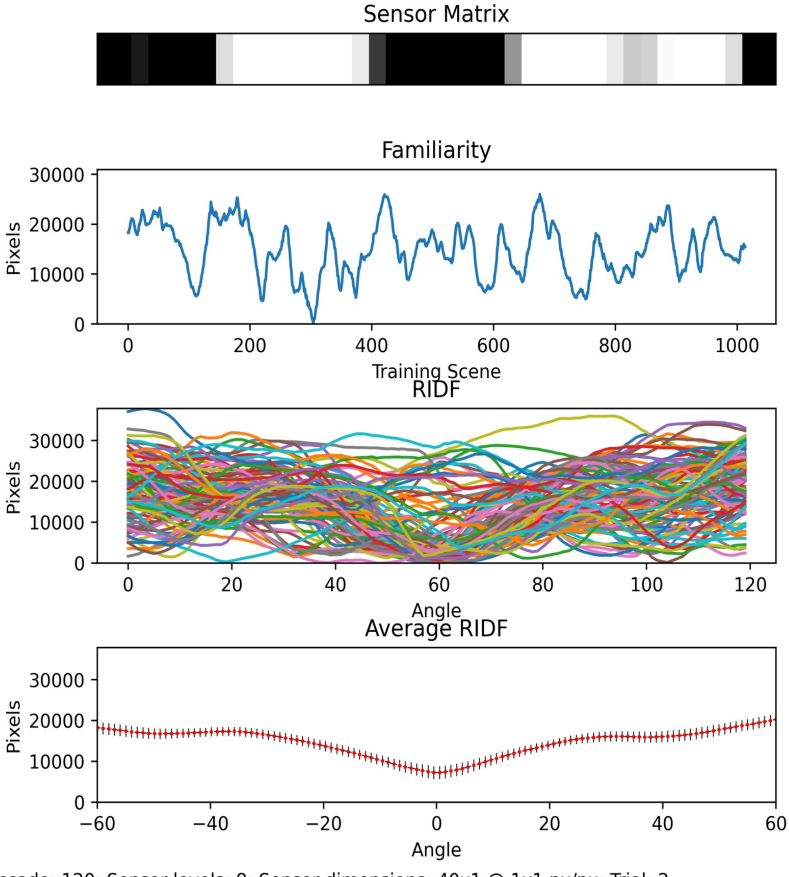
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 187.74; RMSD/dist: 0.469; TD: 10878; p90: 42; p50: 24; complete: 0


Index: BLUR: 9.0; LEVELS: 8; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

20%

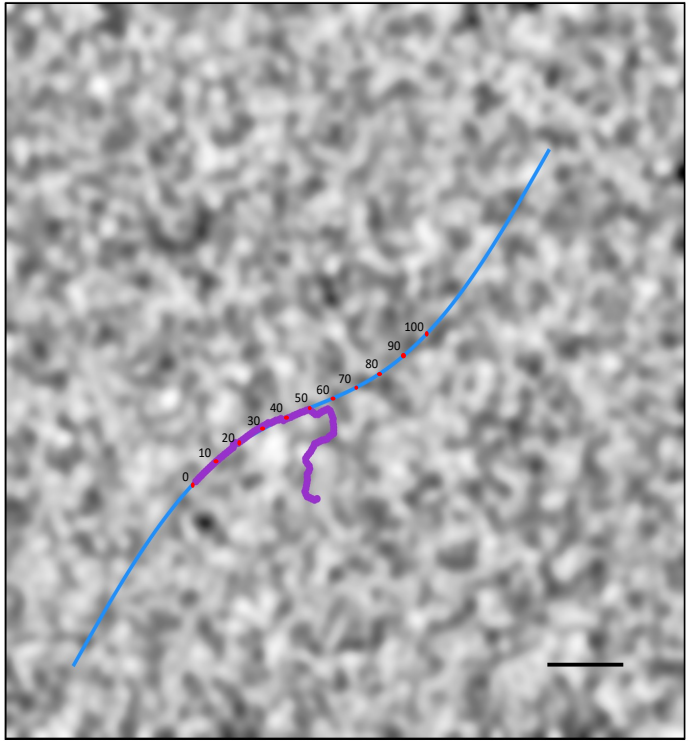


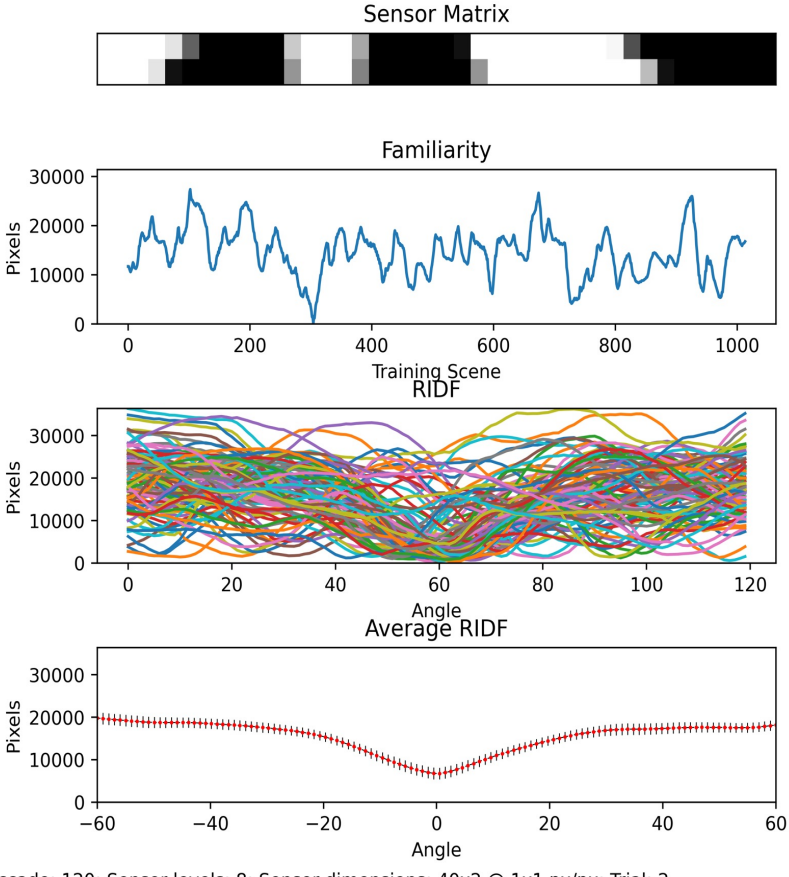


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1522.64; RMSD/dist: 3.807; TD: 6436; p90: 36; p50: 22; complete: 0

40%

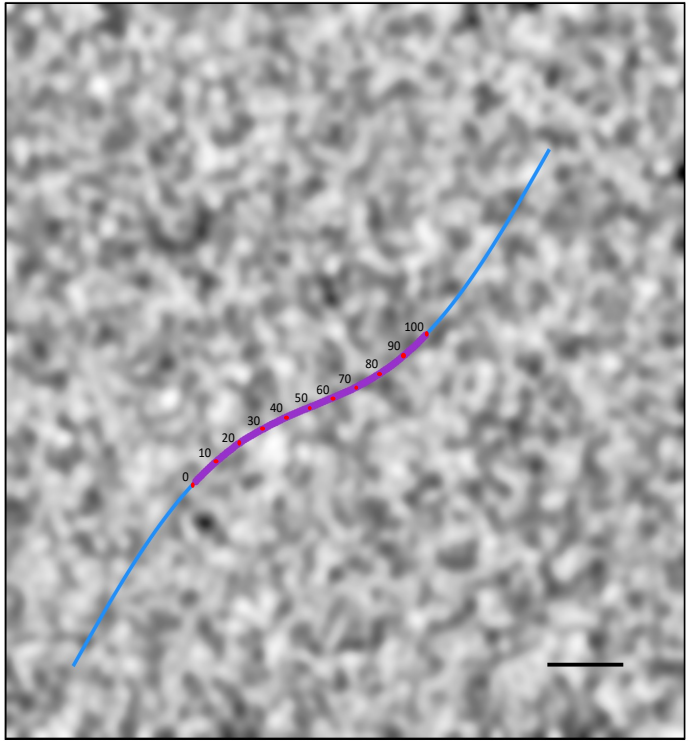


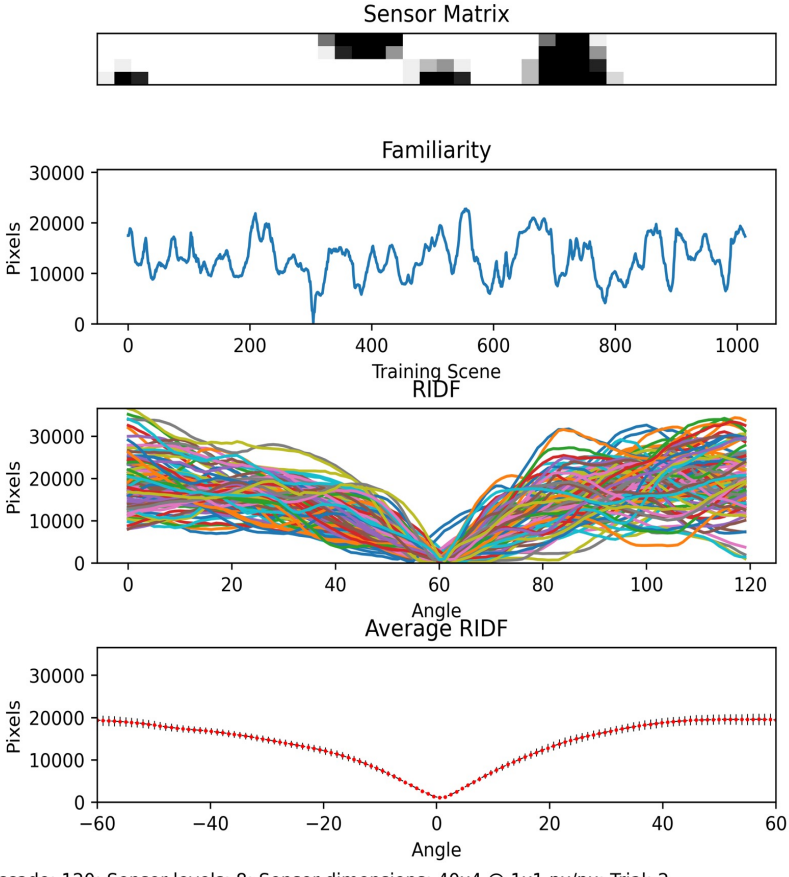


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2844.00; RMSD/dist: 7.110; TD: 7710; p90: 32; p50: 20; complete: 0

100%

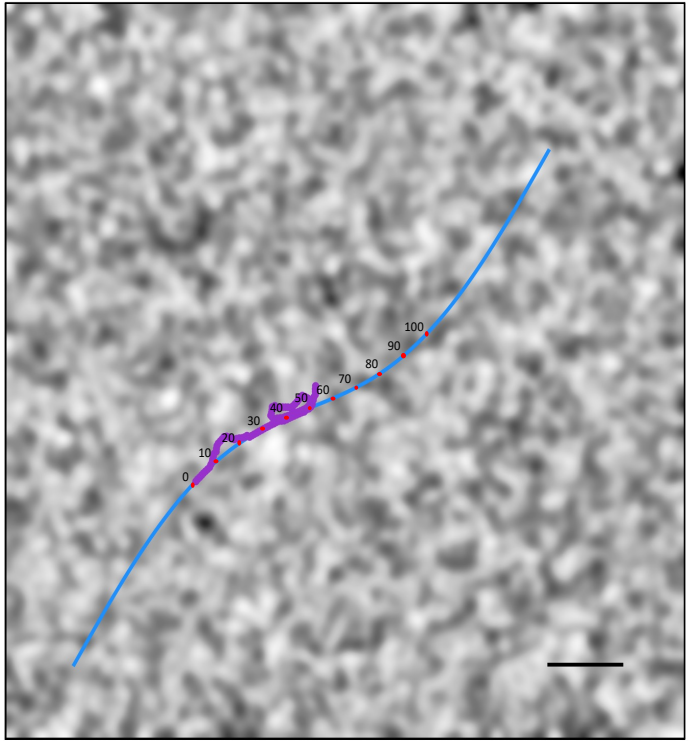


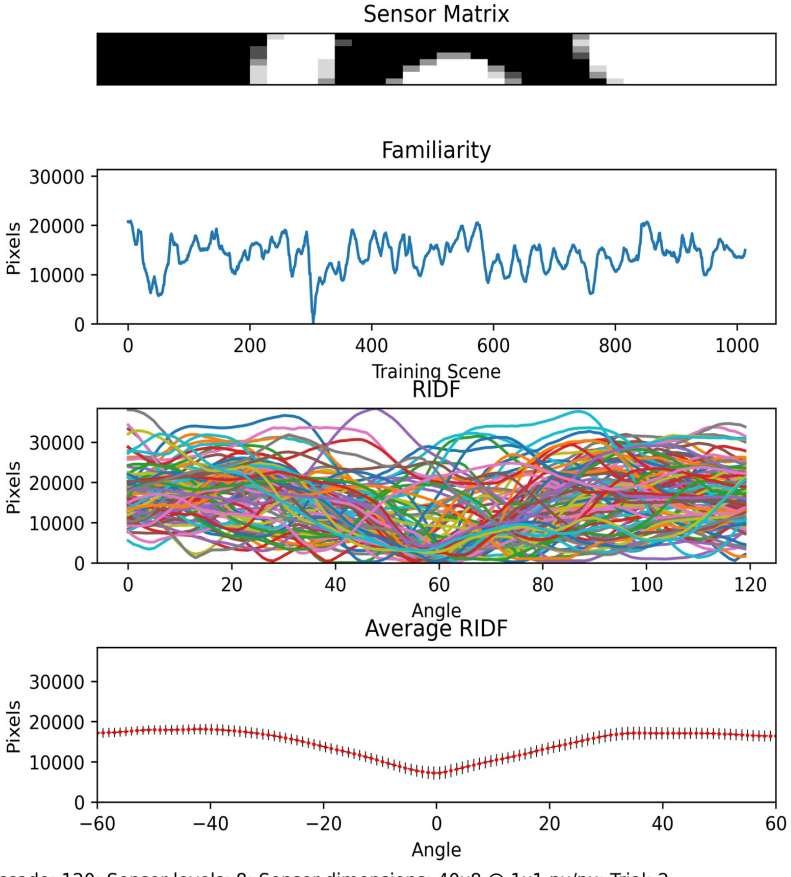


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 55.51; RMSD/dist: 0.139; TD: 12808; p90: 44; p50: 20; complete: 0

20%

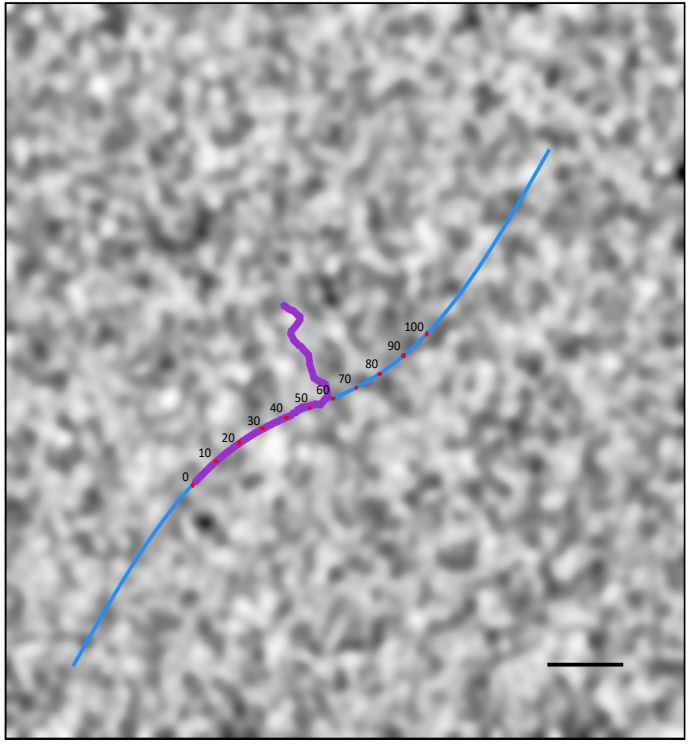


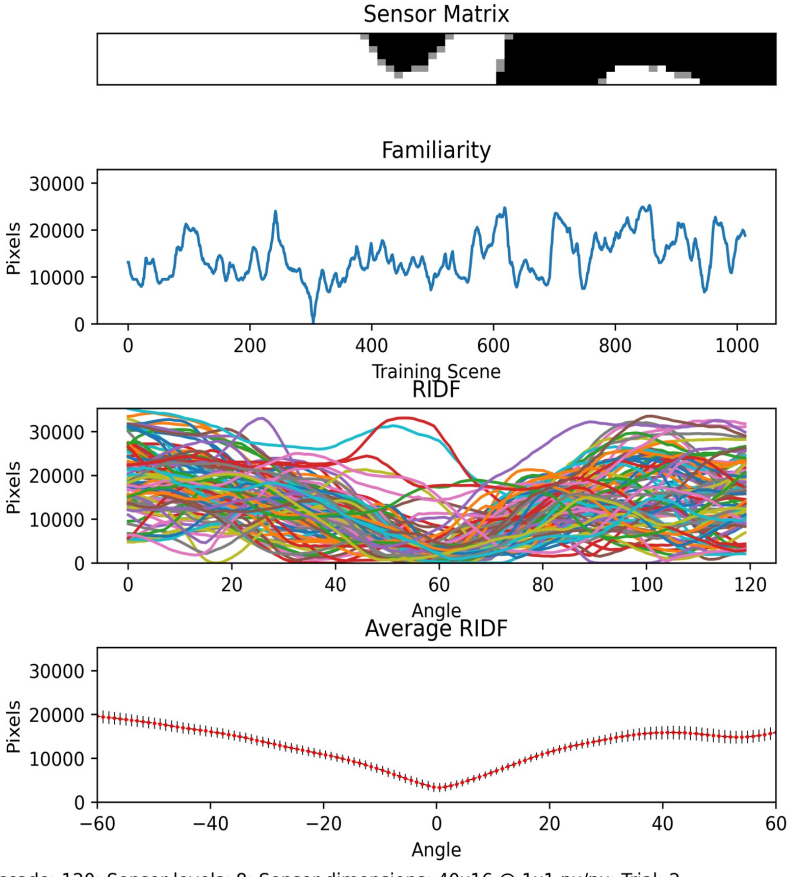


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 725.30; RMSD/dist: 1.813; TD: 5698; p90: 32; p50: 20; complete: 0

40%

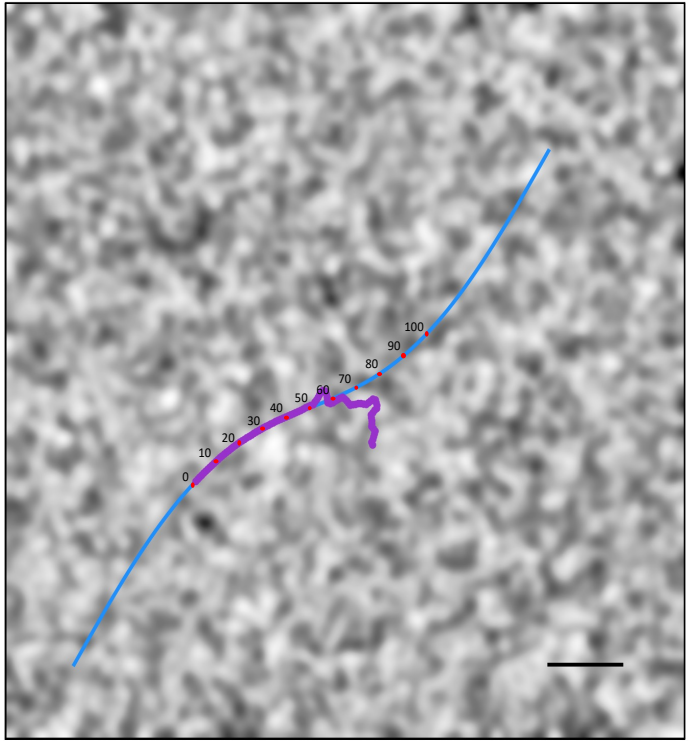


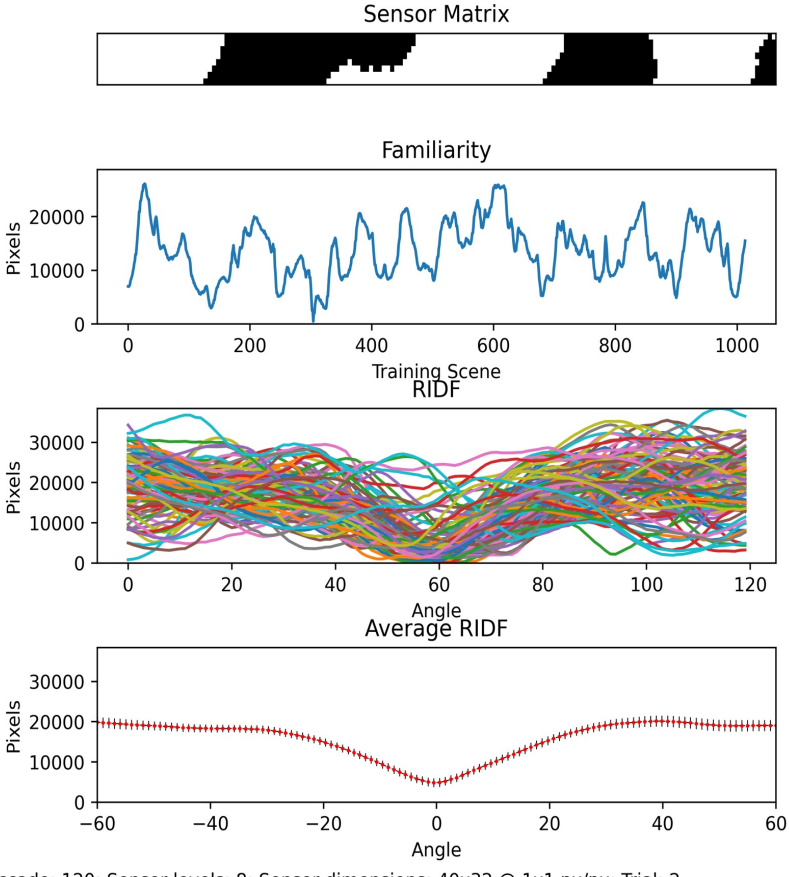


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 3330.52; RMSD/dist: 8.326; TD: 10446; p90: 54; p50: 26; complete: 0

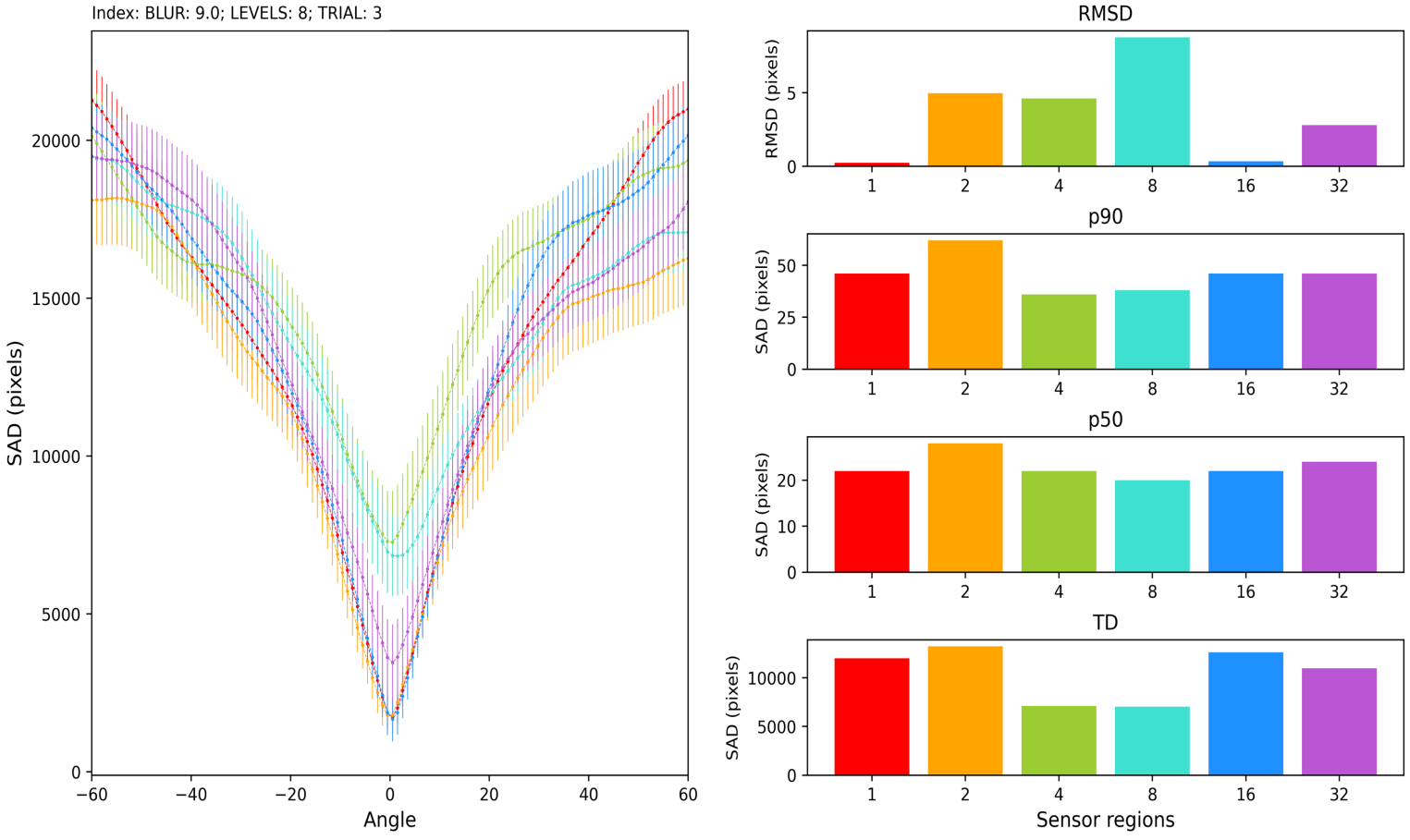
50%



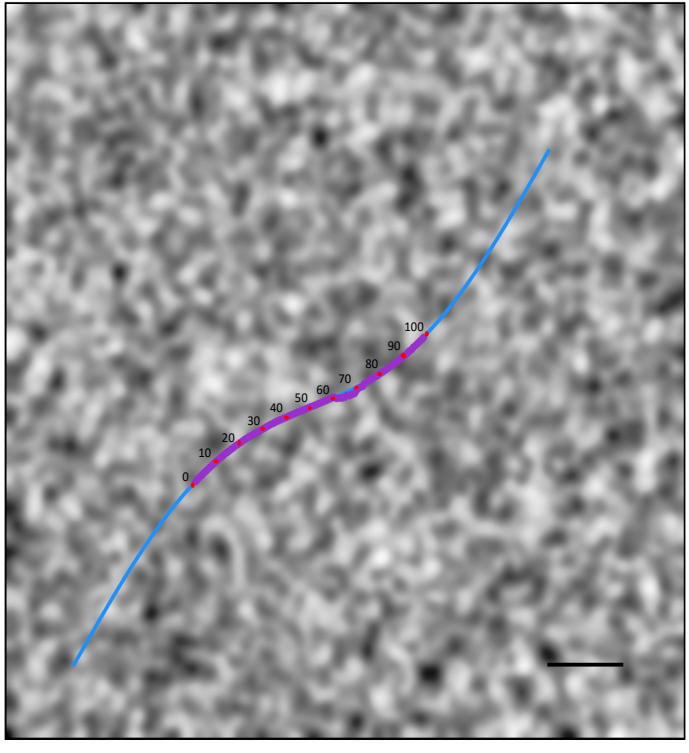


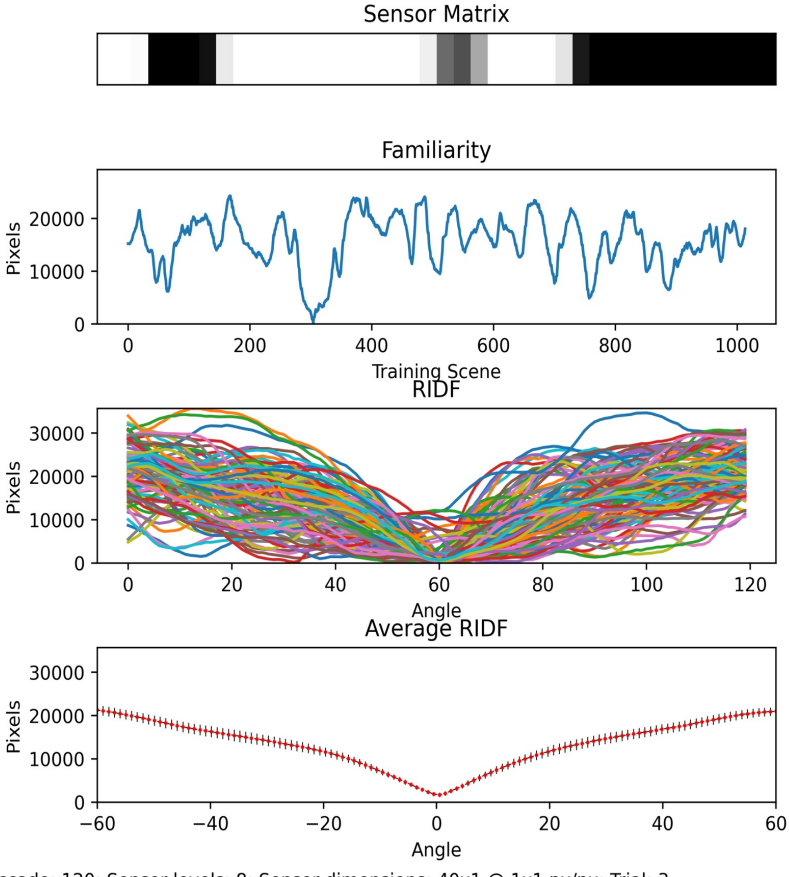
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1403.30; RMSD/dist: 3.508; TD: 9633; p90: 34; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 8; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

80%

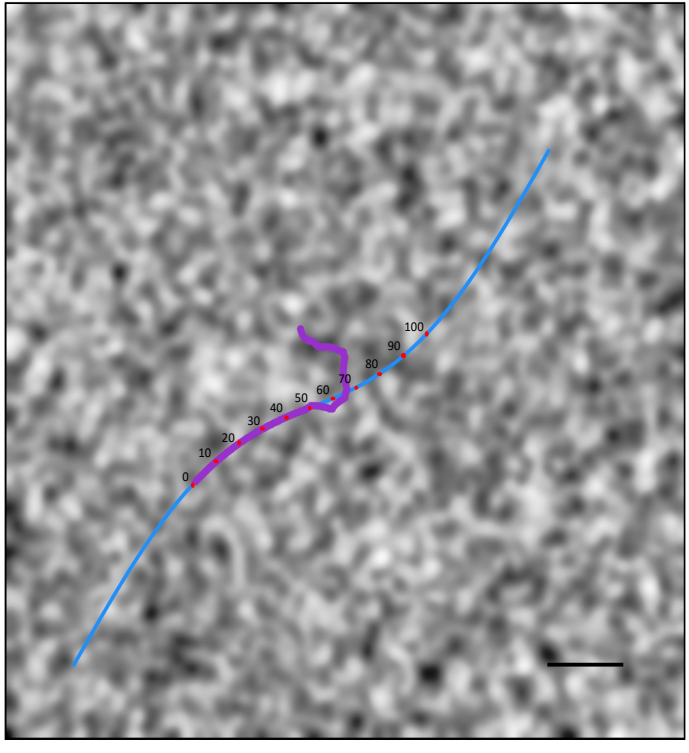


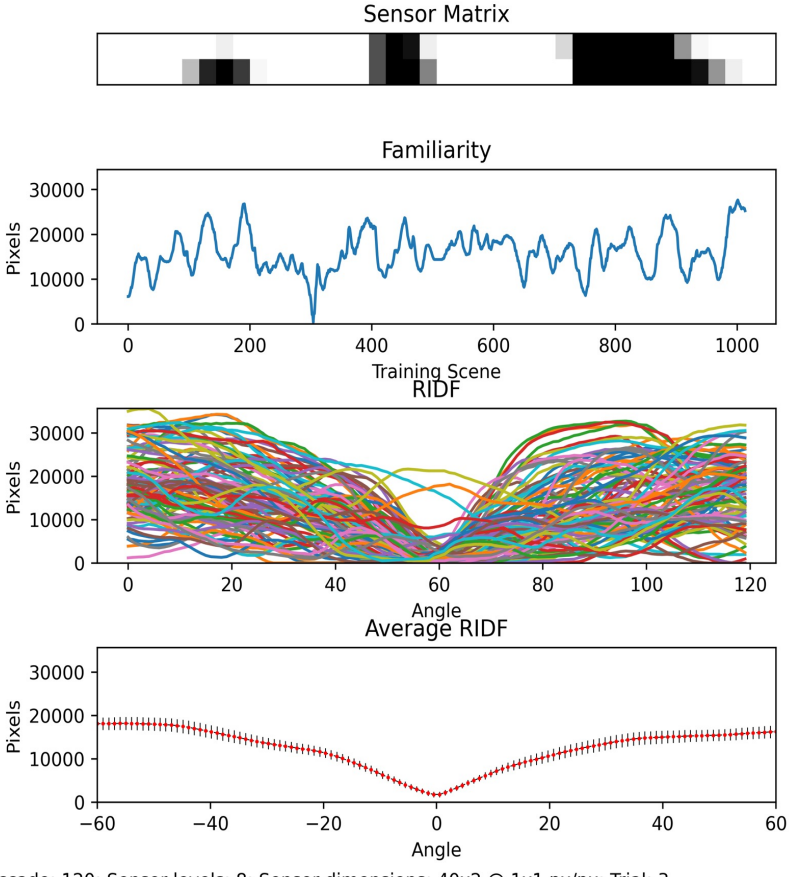


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 93.45; RMSD/dist: 0.234; TD: 11990; p90: 46; p50: 22; complete: 0

50%

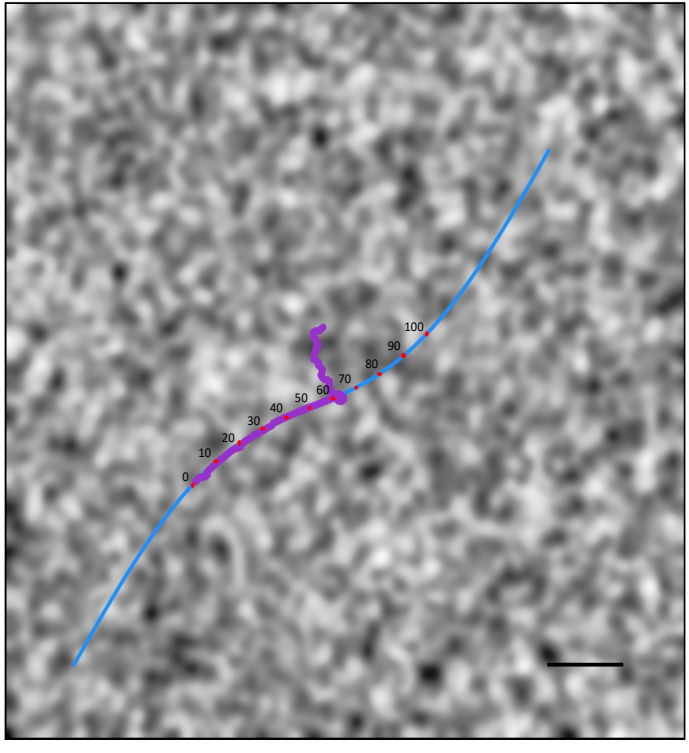


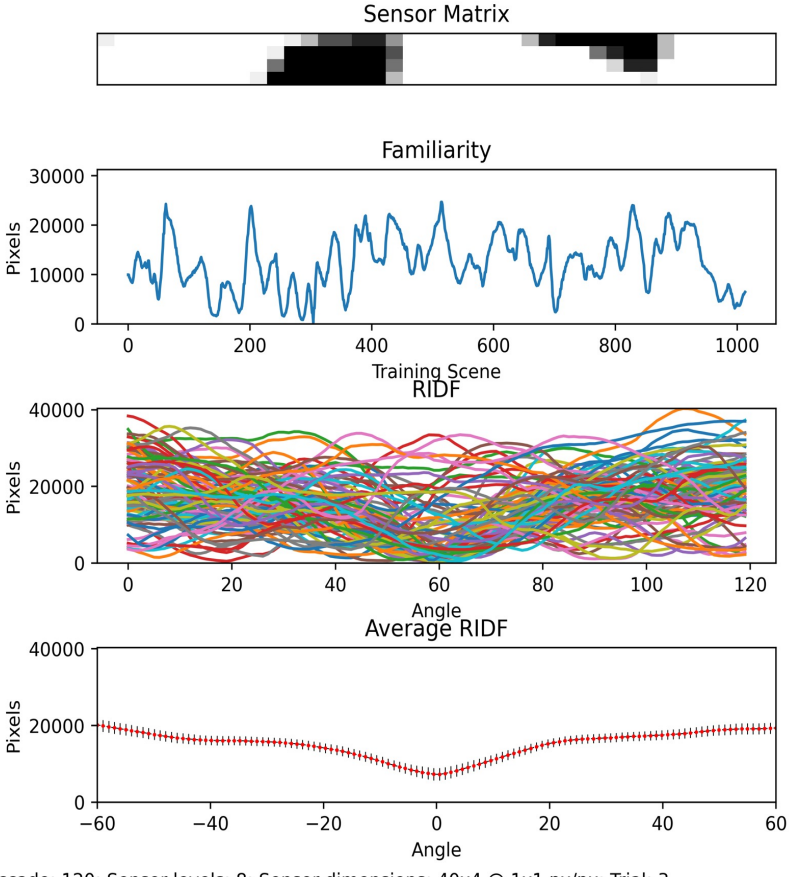


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1989.52; RMSD/dist: 4.974; TD: 13230; p90: 62; p50: 28; complete: 0

40%

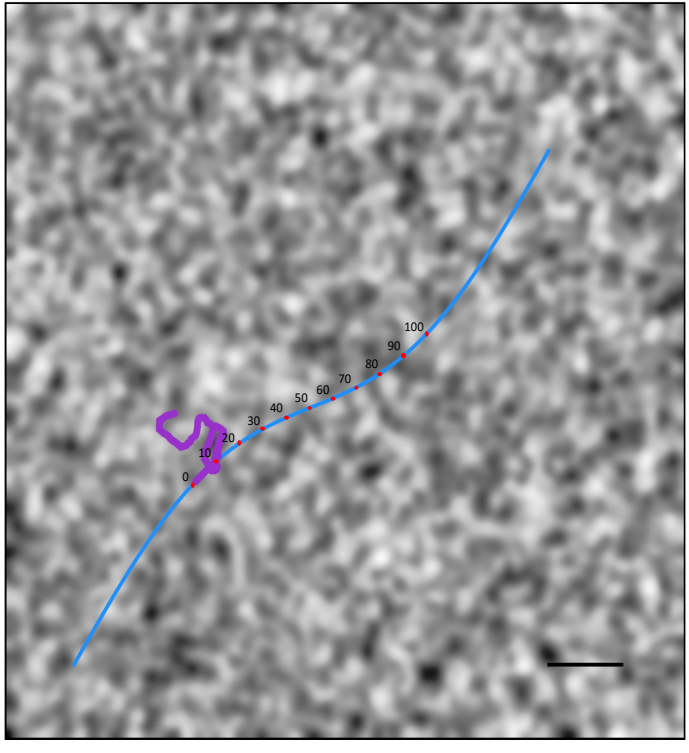


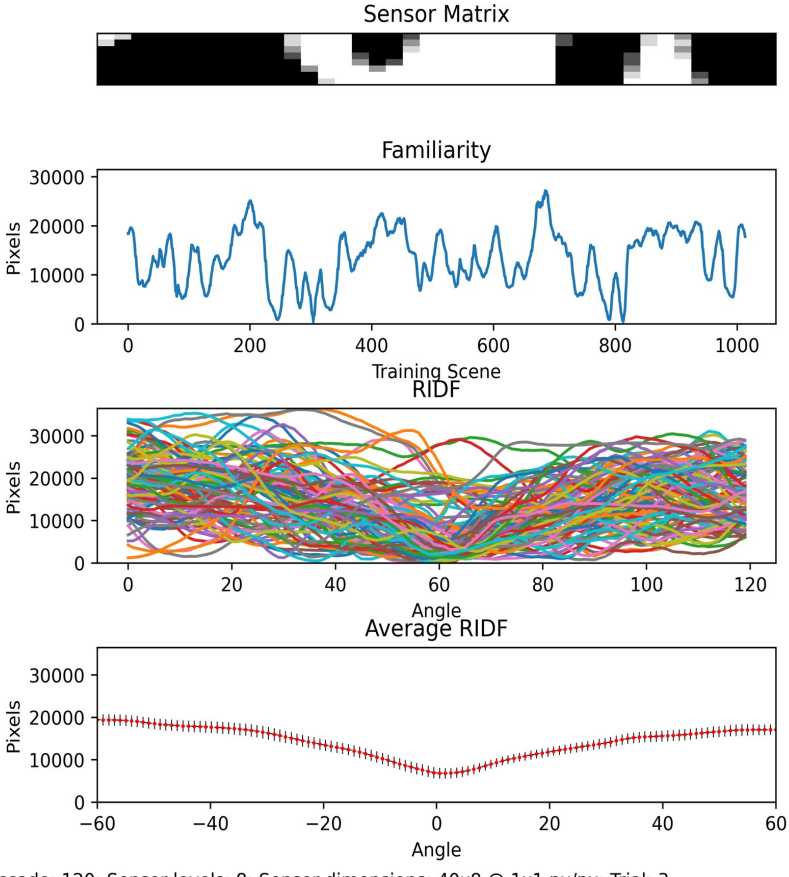


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1848.29; RMSD/dist: 4.621; TD: 7098; p90: 36; p50: 22; complete: 0

10%

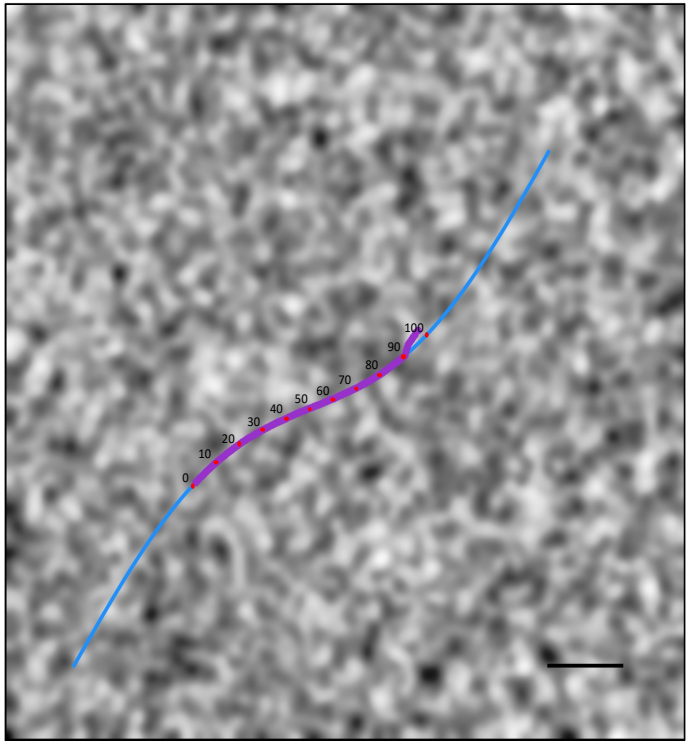


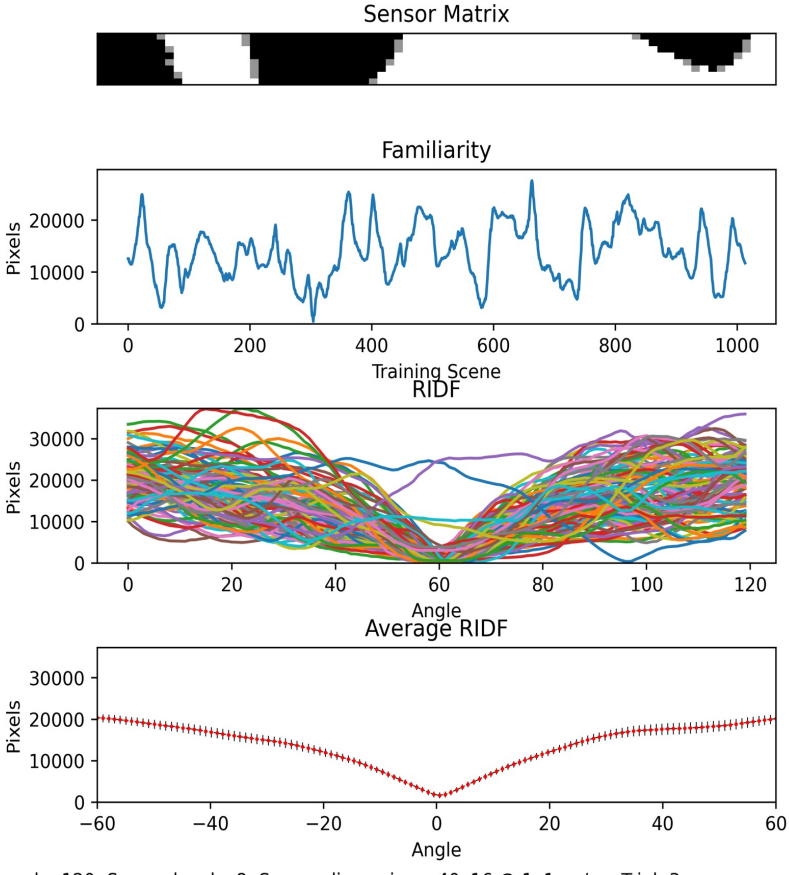


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 3506.74; RMSD/dist: 8.767; TD: 7031; p90: 38; p50: 20; complete: 0

90%

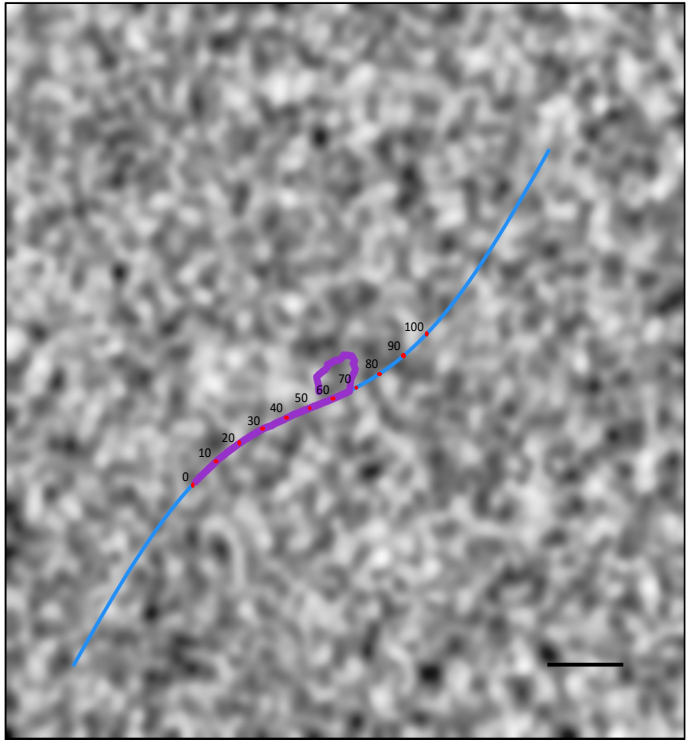


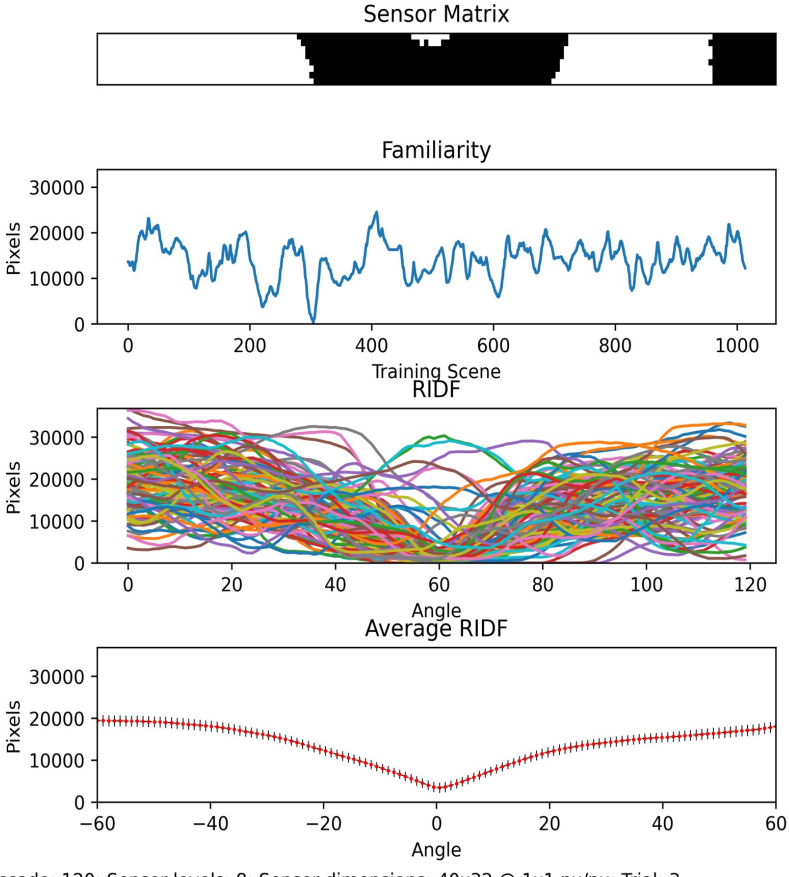


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 137.94; RMSD/dist: 0.345; TD: 12604; p90: 46; p50: 22; complete: 0

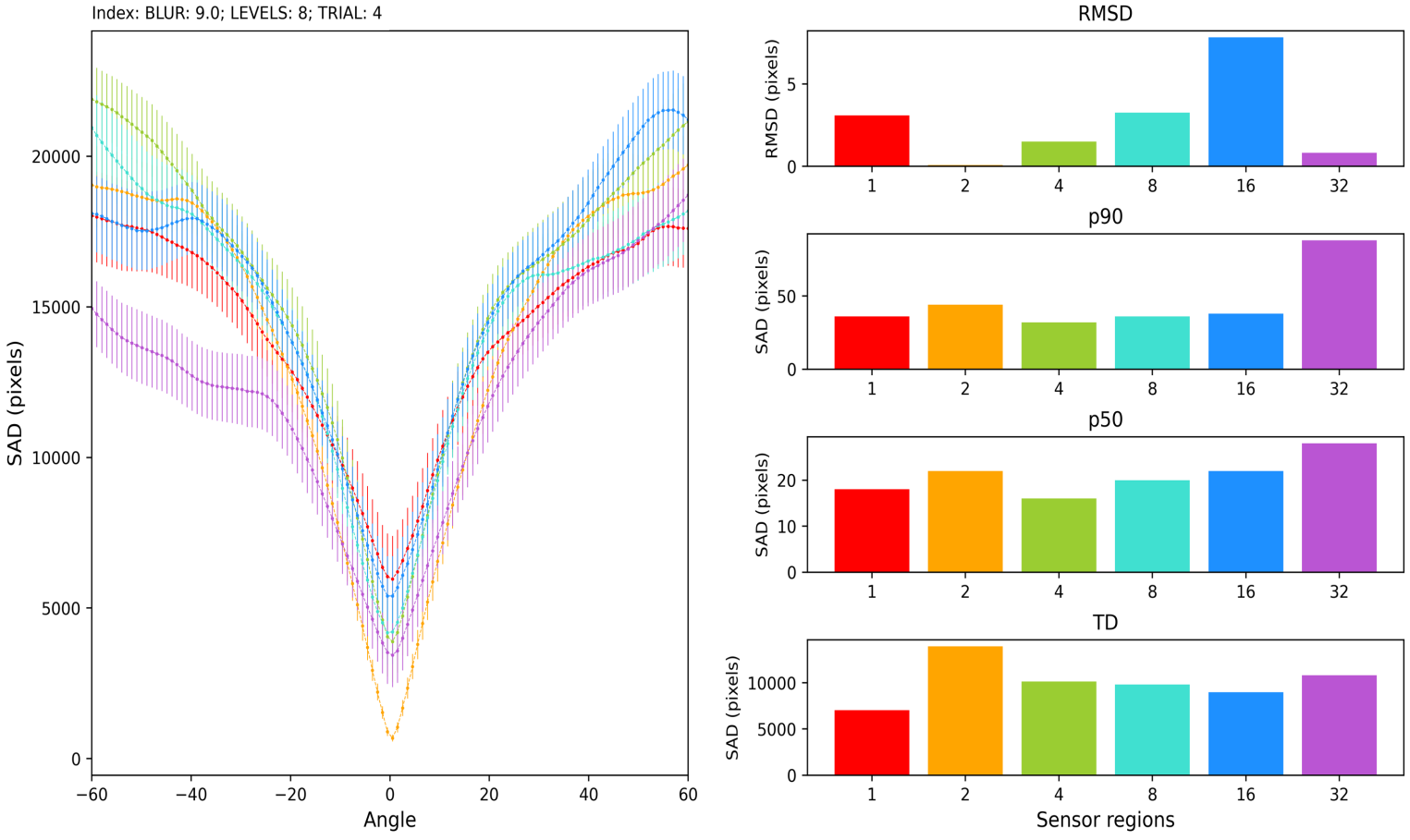
60%



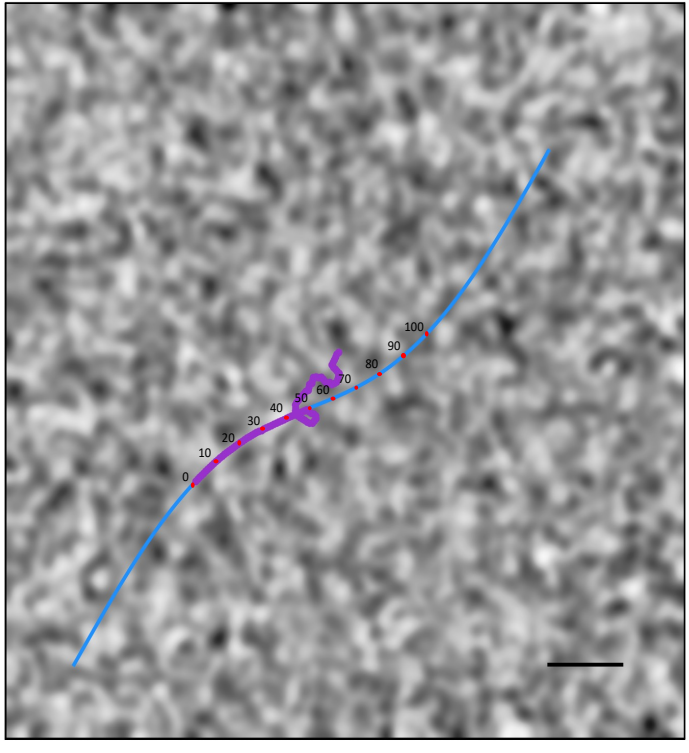


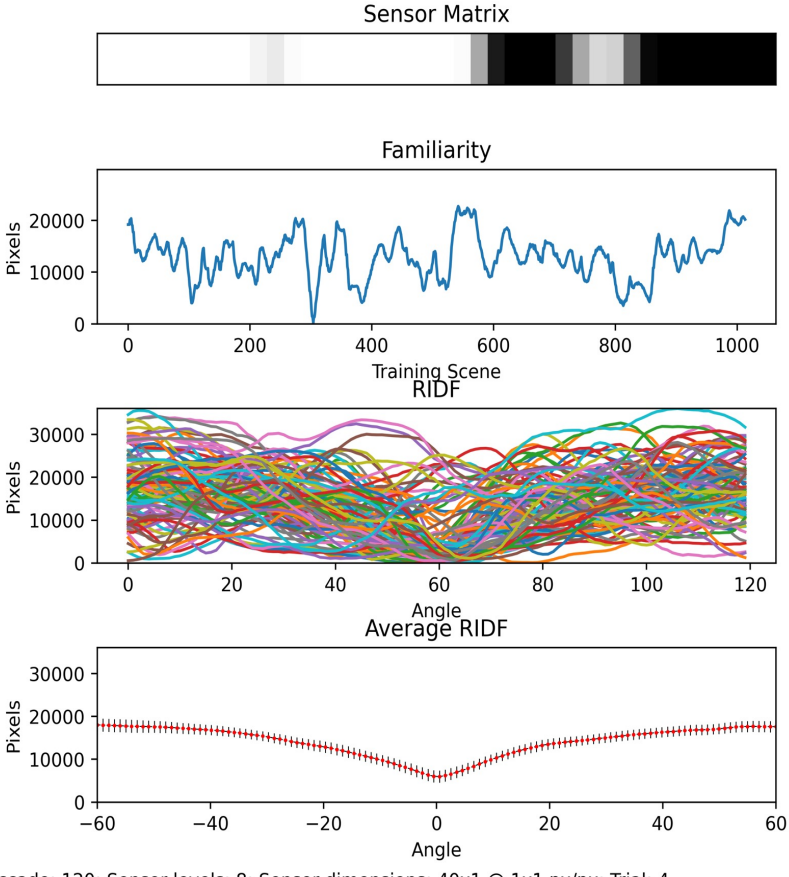
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1117.36; RMSD/dist: 2.793; TD: 10972; p90: 46; p50: 24; complete: 0


Index: BLUR: 9.0; LEVELS: 8; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

50%

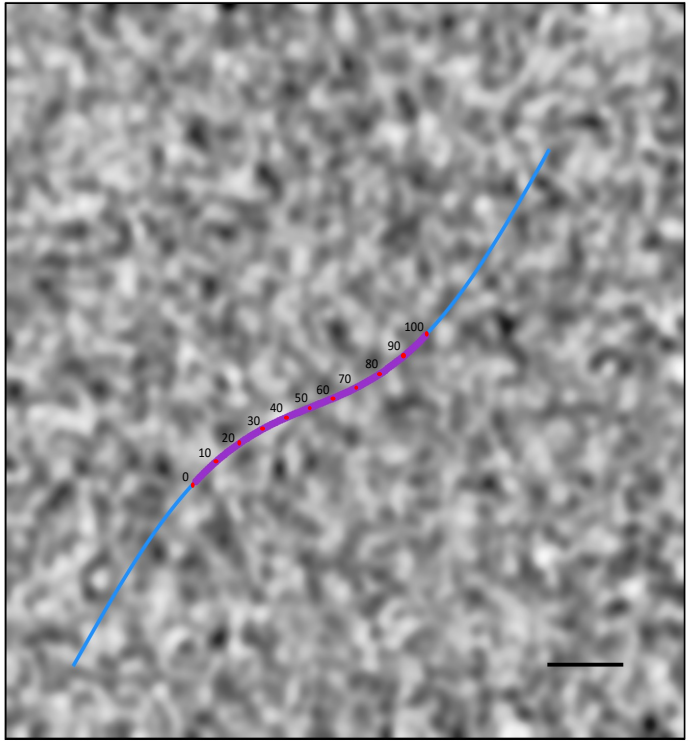


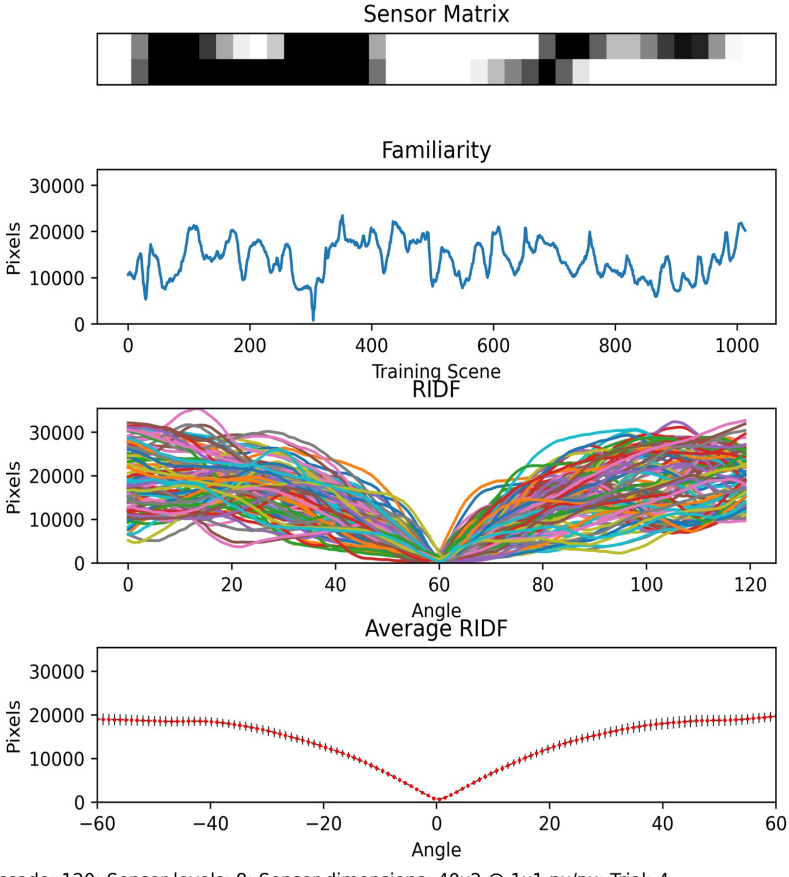


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1235.33; RMSD/dist: 3.088; TD: 7047; p90: 36; p50: 18; complete: 0

100%

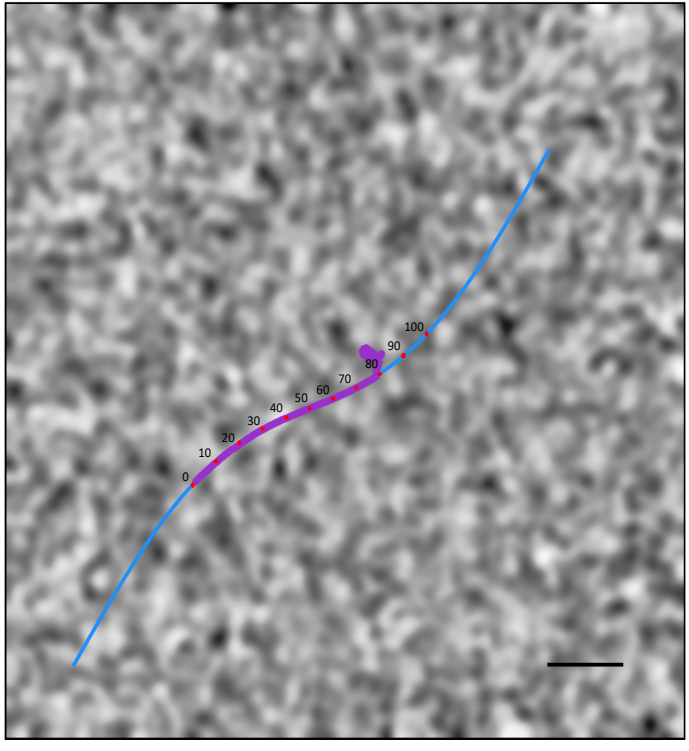


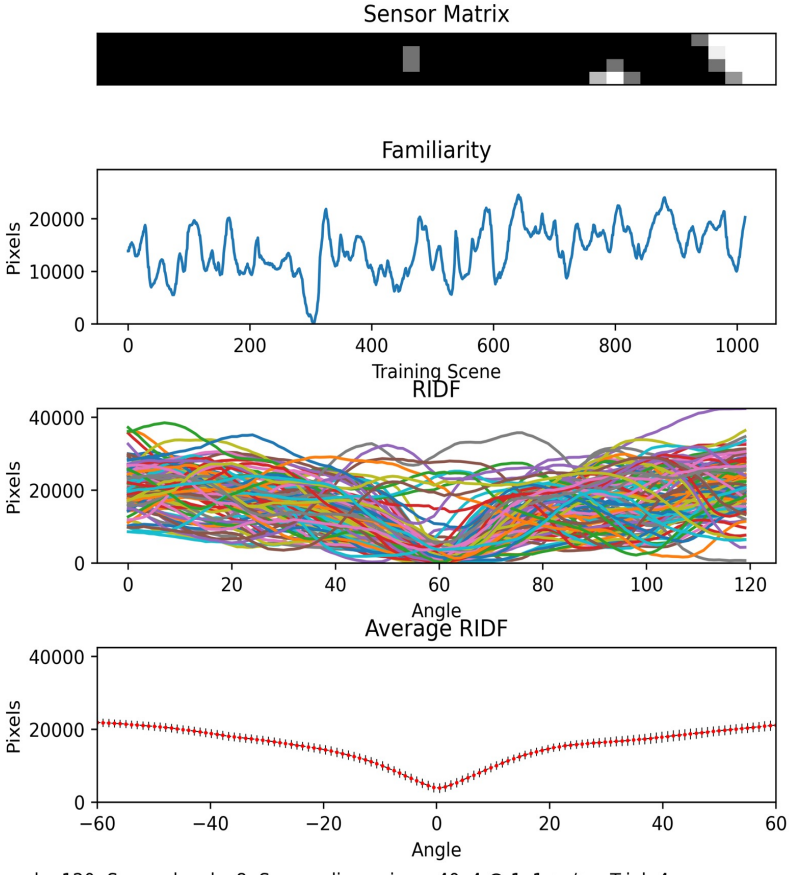


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 32.43; RMSD/dist: 0.081; TD: 13949; p90: 44; p50: 22; complete: 0

80%

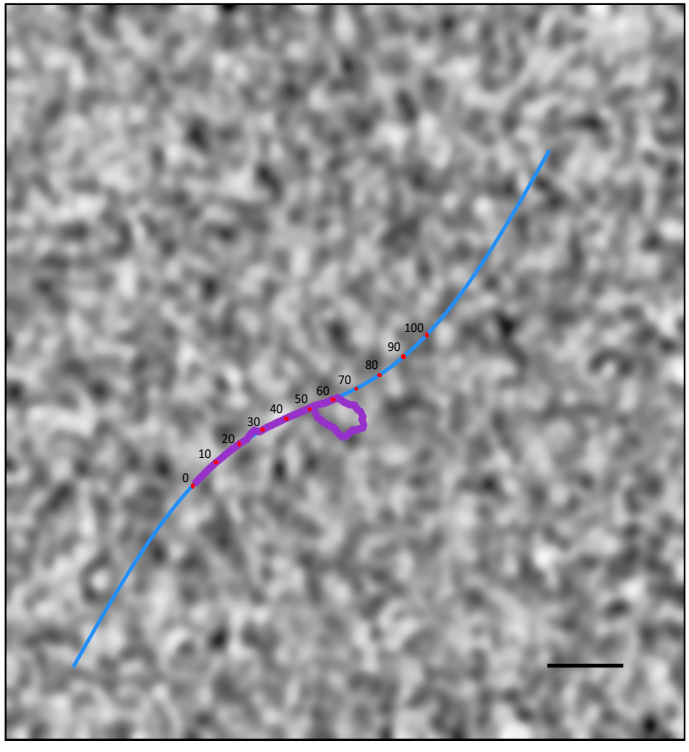


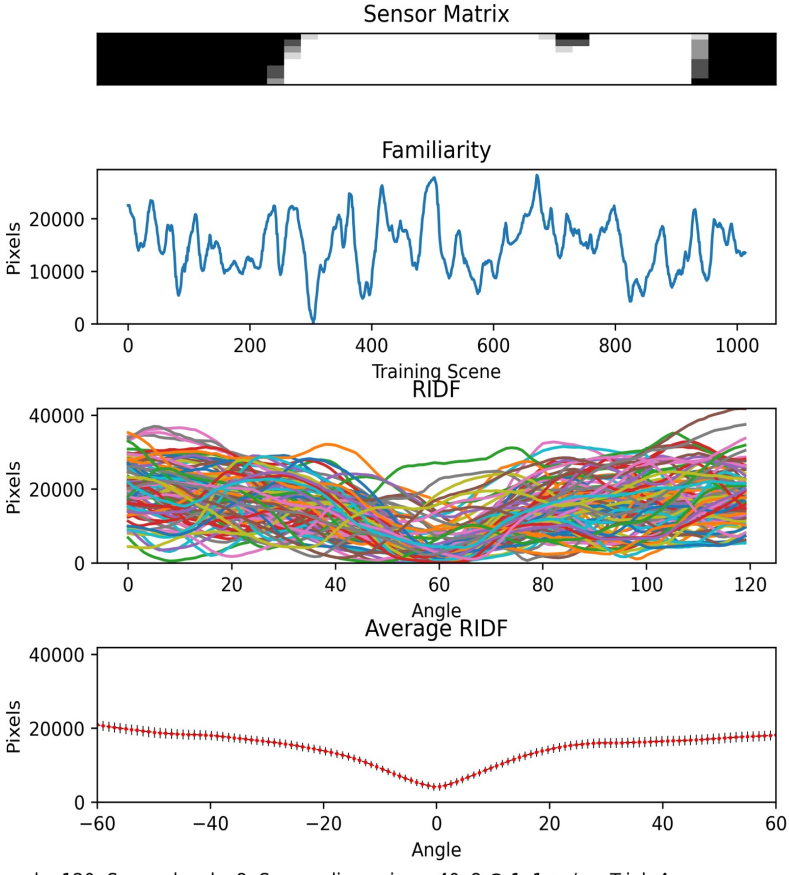


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 600.36; RMSD/dist: 1.501; TD: 10138; p90: 32; p50: 16; complete: 0

50%

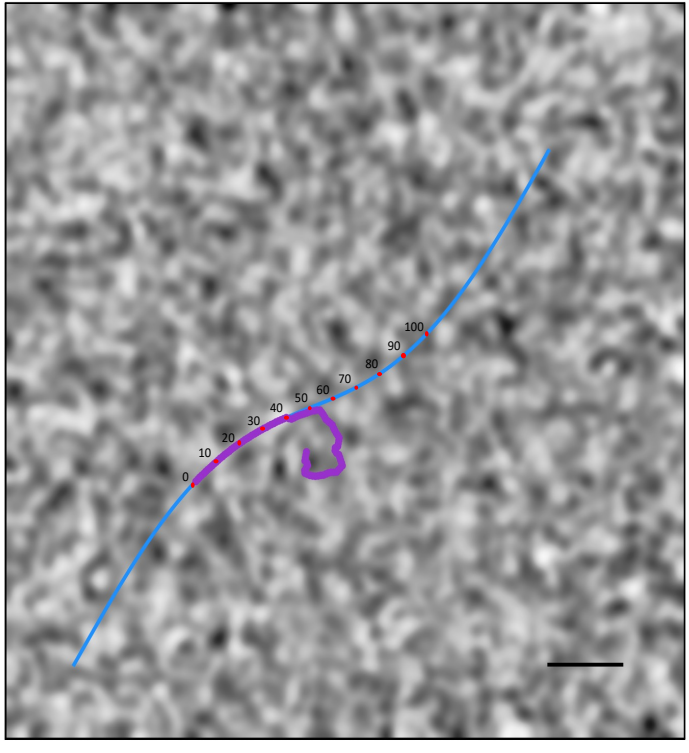


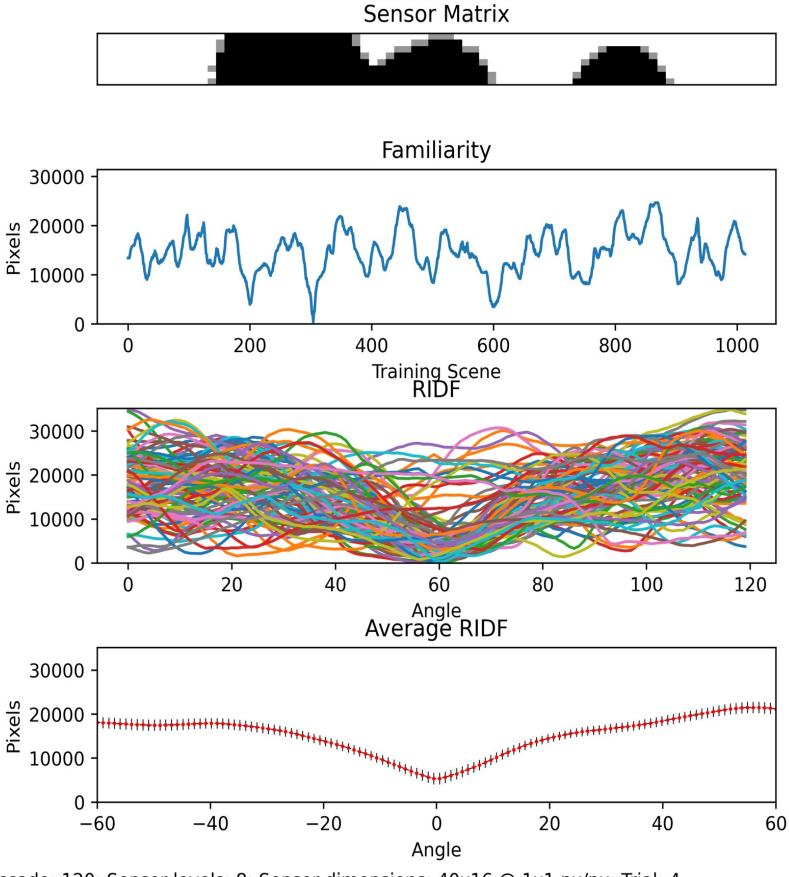


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1301.94; RMSD/dist: 3.255; TD: 9811; p90: 36; p50: 20; complete: 0

40%

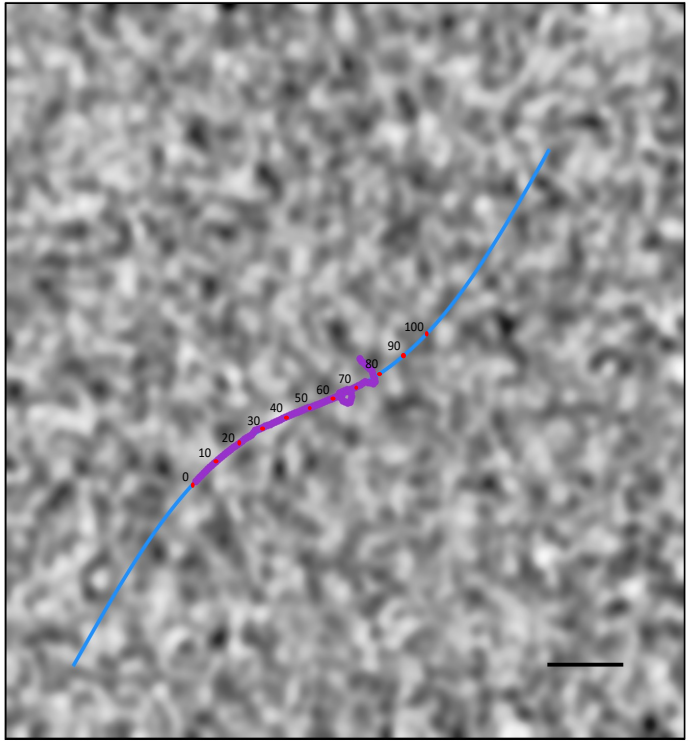


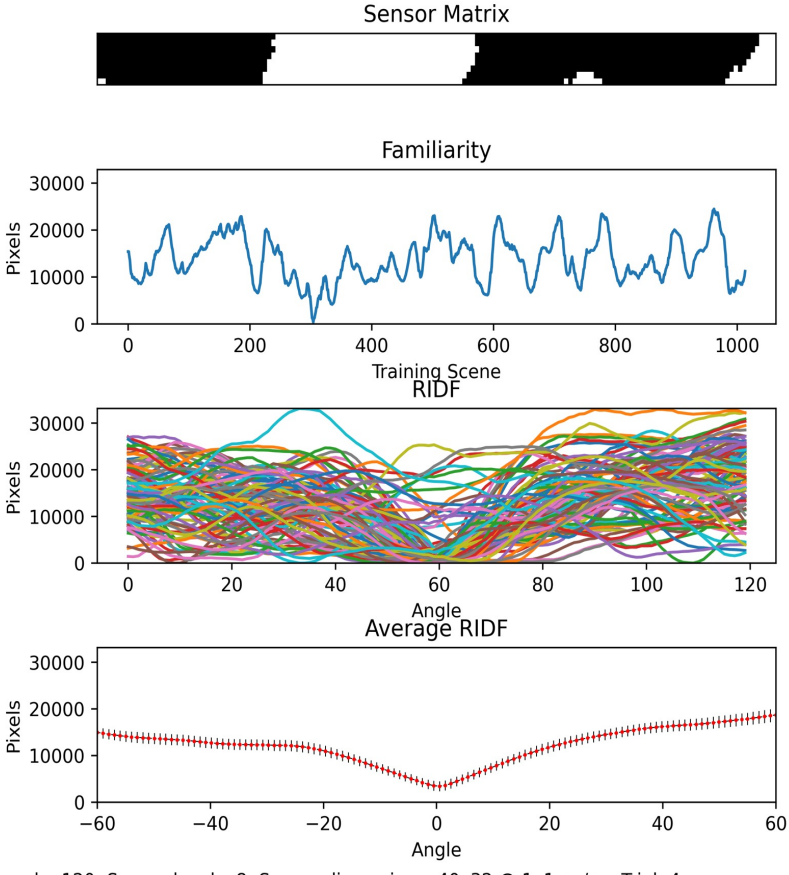


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3129.44; RMSD/dist: 7.824; TD: 8968; p90: 38; p50: 22; complete: 0

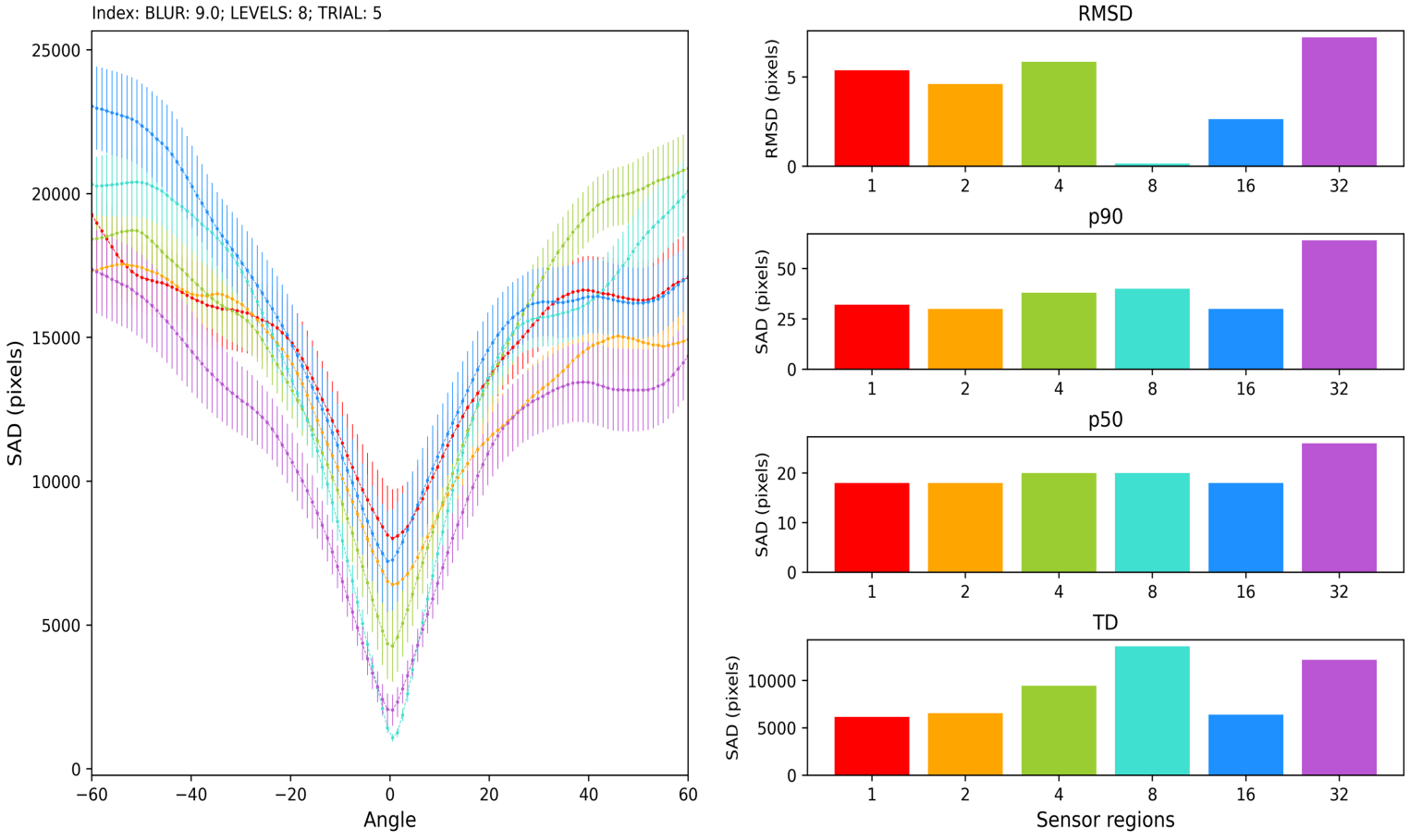
60%



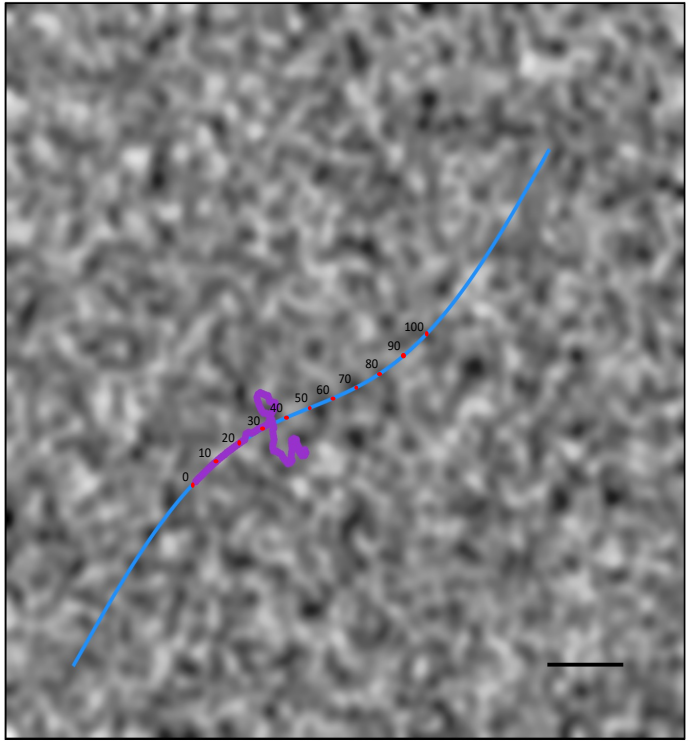


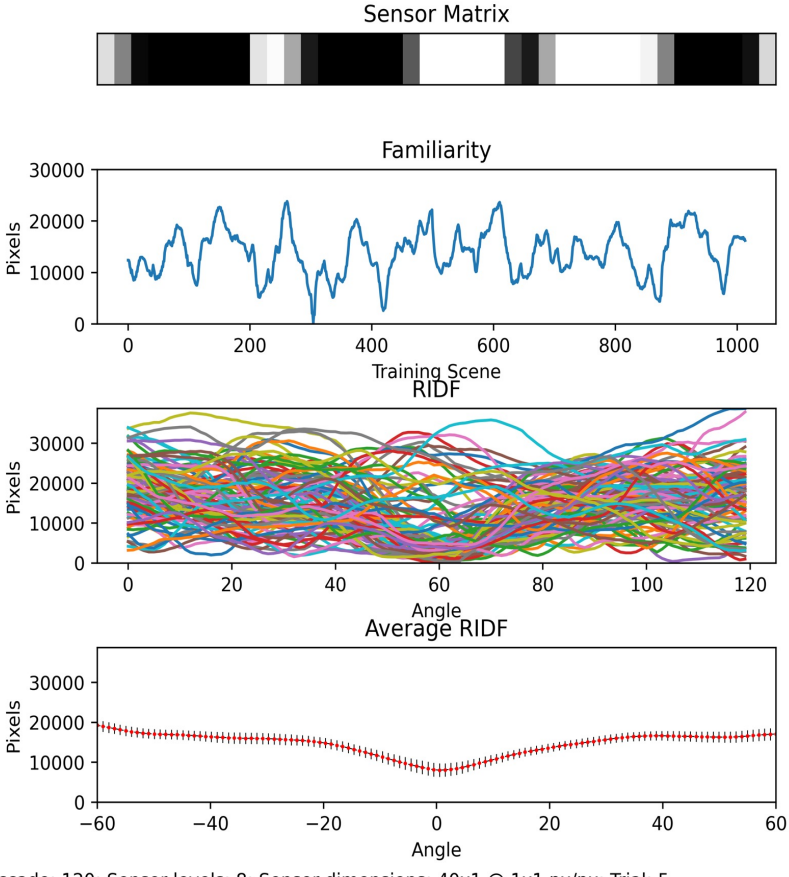
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 328.71; RMSD/dist: 0.822; TD: 10811; p90: 88; p50: 28; complete: 0


Index: BLUR: 9.0; LEVELS: 8; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

20%

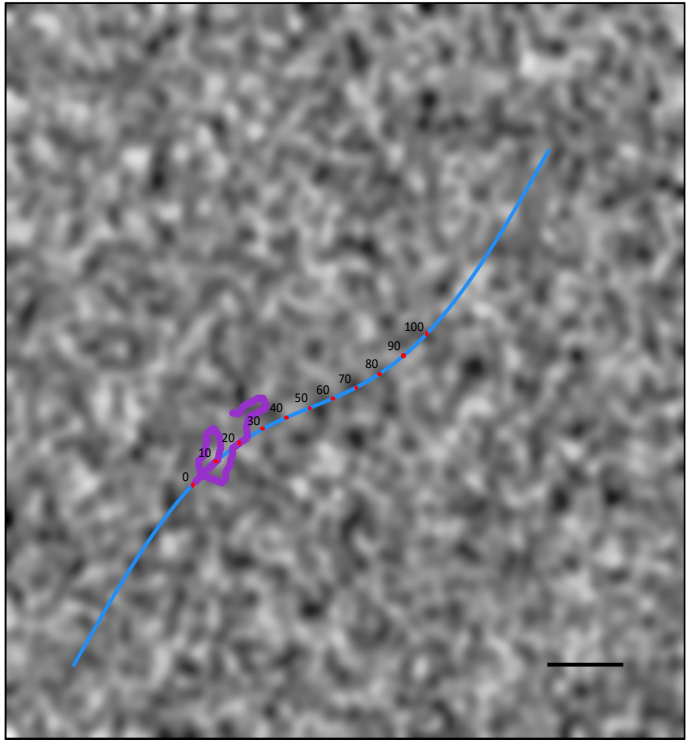


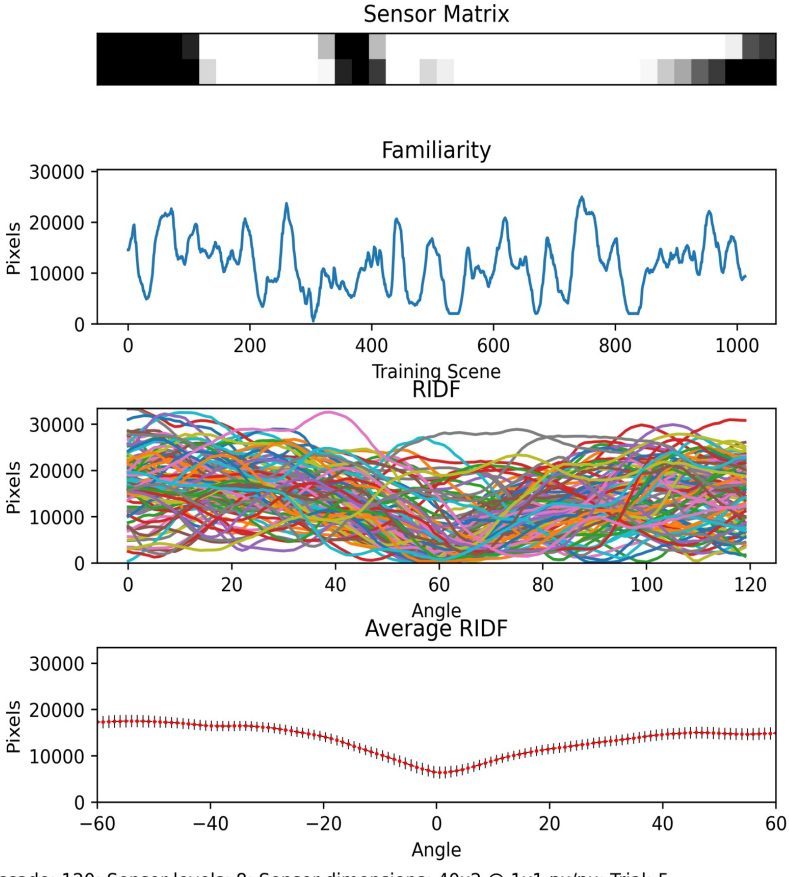


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2152.70; RMSD/dist: 5.382; TD: 6150; p90: 32; p50: 18; complete: 0

10%

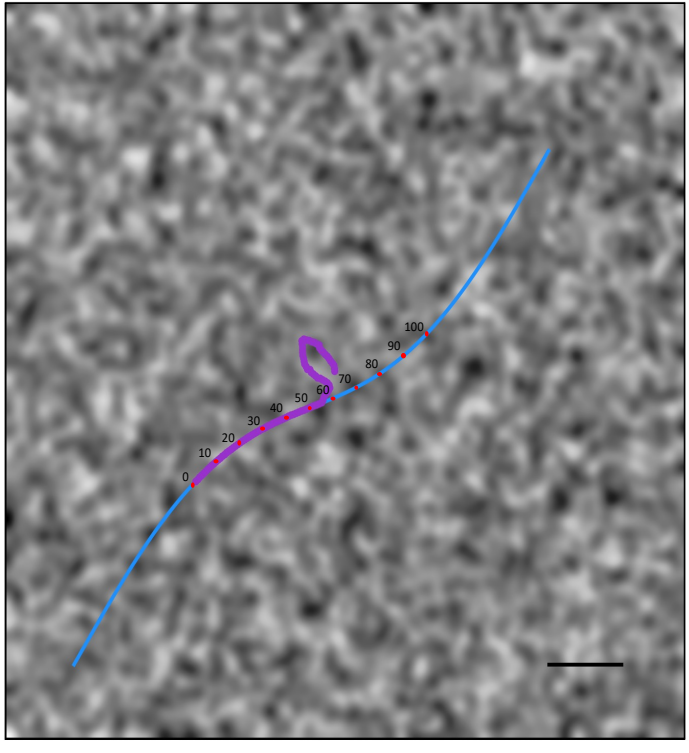


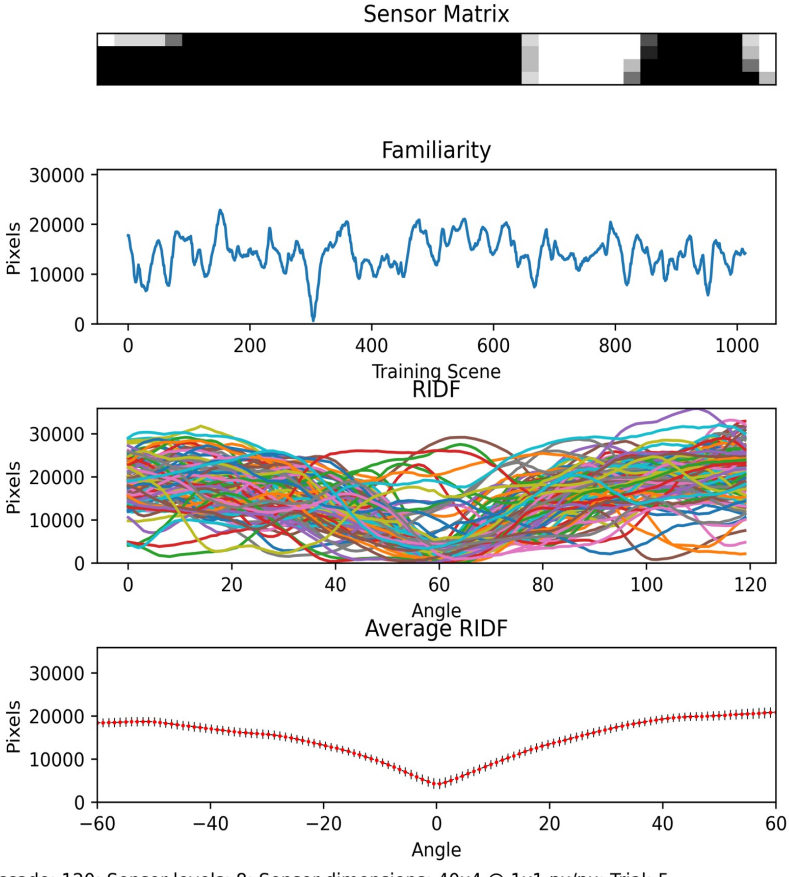


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1844.57; RMSD/dist: 4.611; TD: 6554; p90: 30; p50: 18; complete: 0

50%

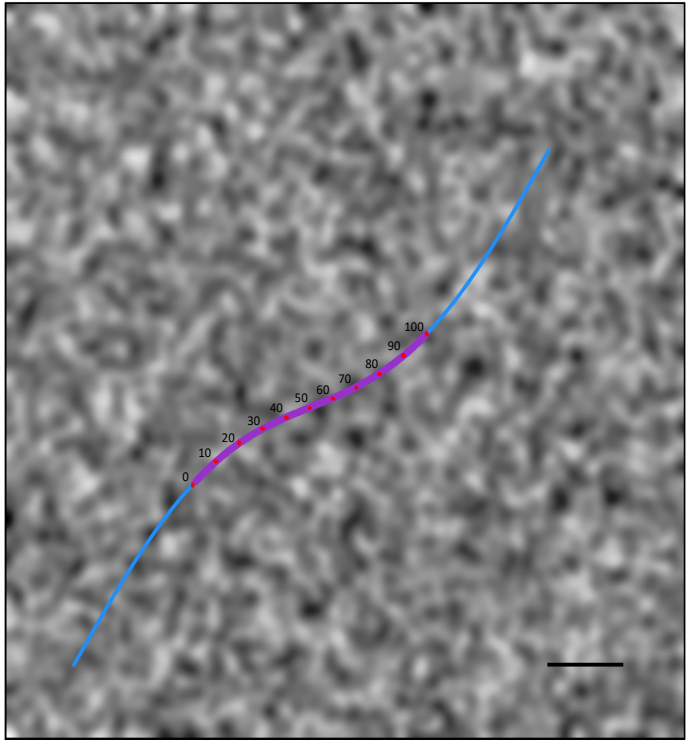


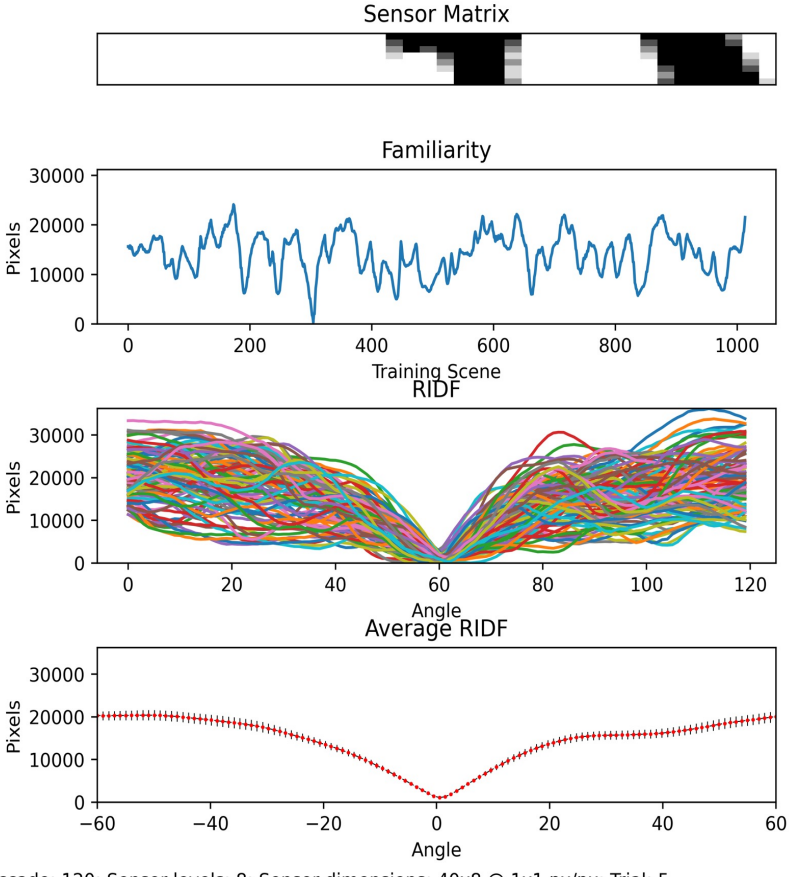


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2346.09; RMSD/dist: 5.865; TD: 9452; p90: 38; p50: 20; complete: 0

100%

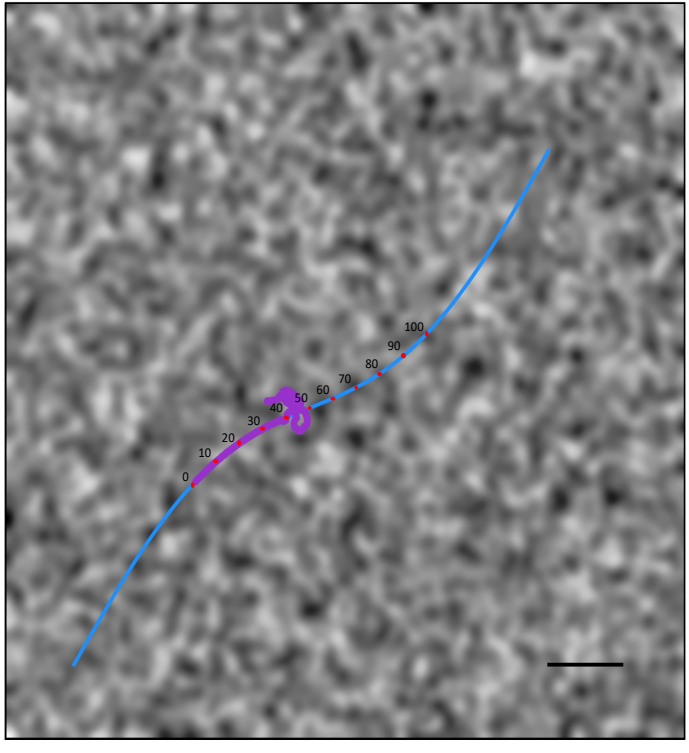


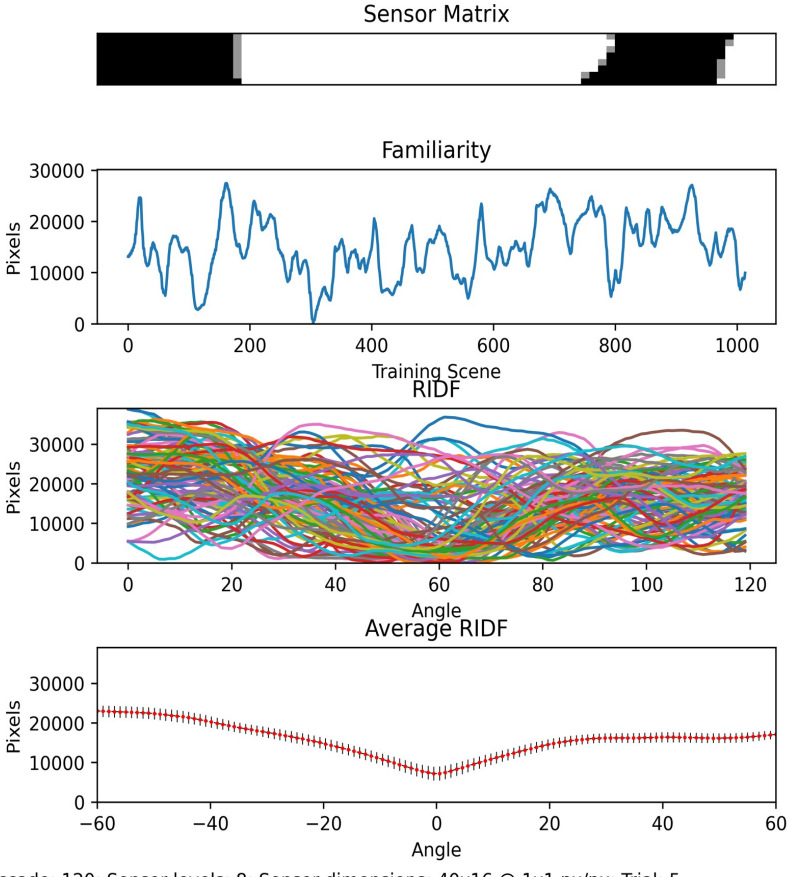


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 60.77; RMSD/dist: 0.152; TD: 13611; p90: 40; p50: 20; complete: 0

40%

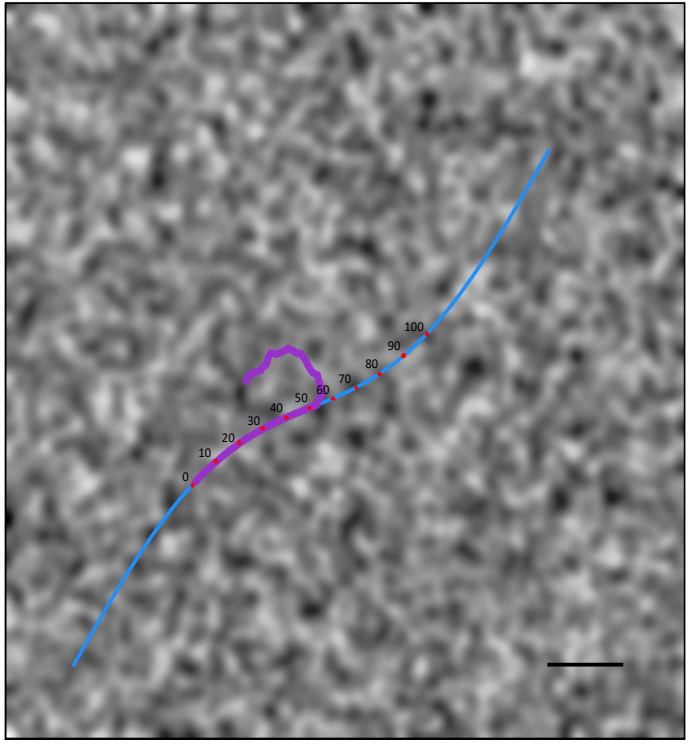


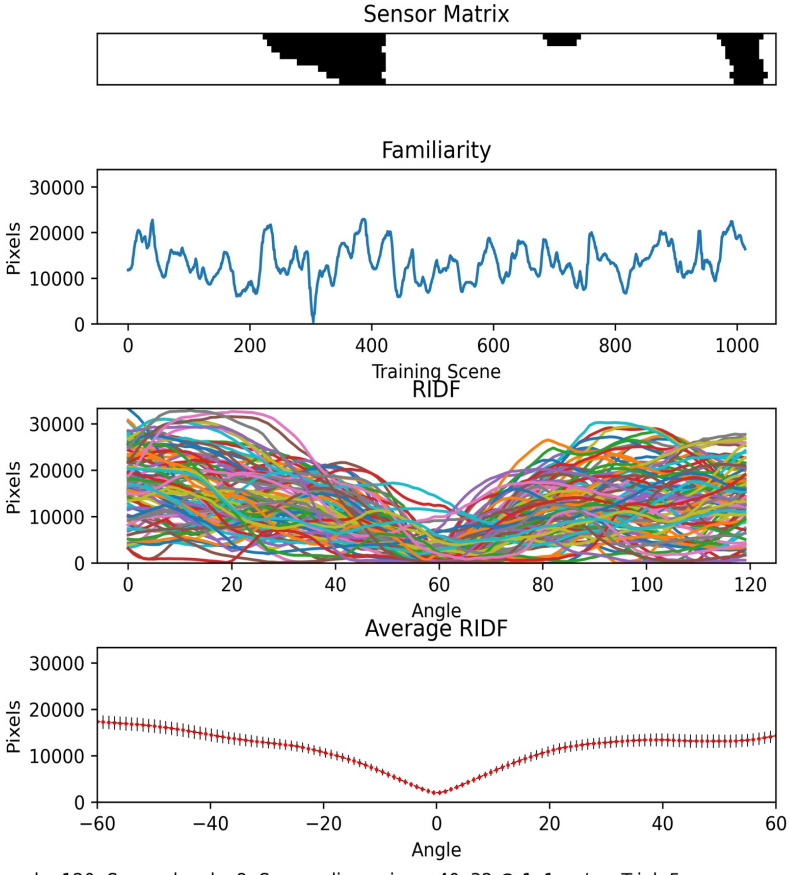


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1054.44; RMSD/dist: 2.636; TD: 6402; p90: 30; p50: 18; complete: 0

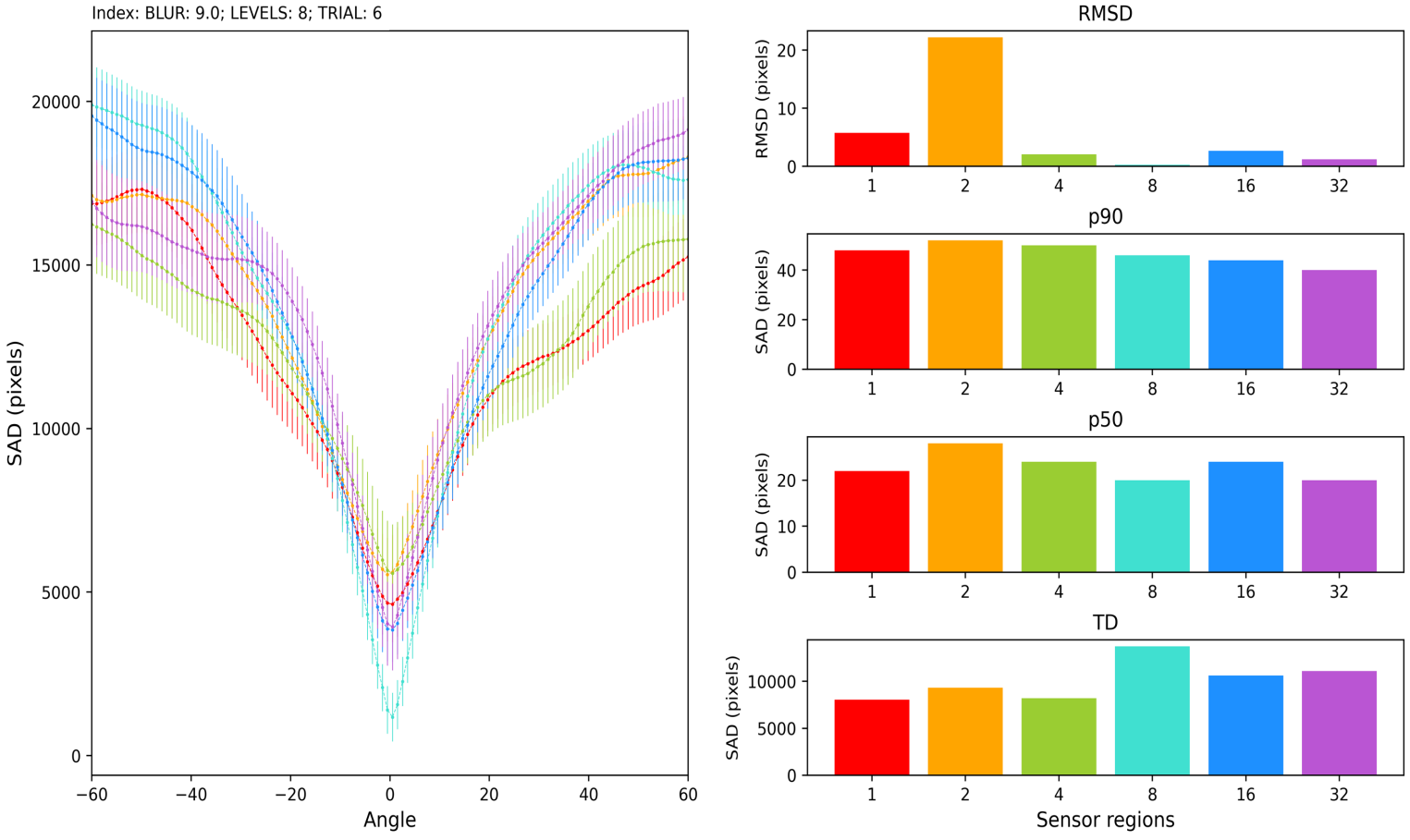
50%



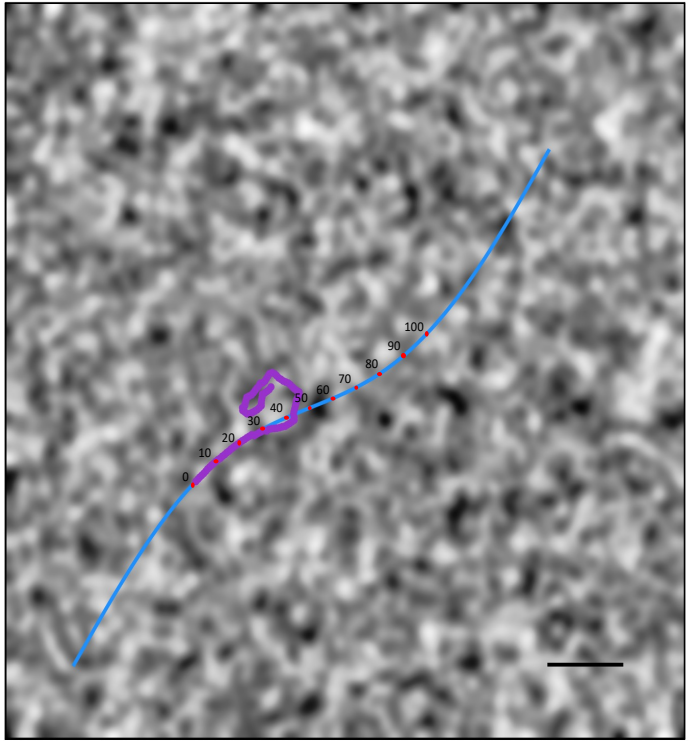


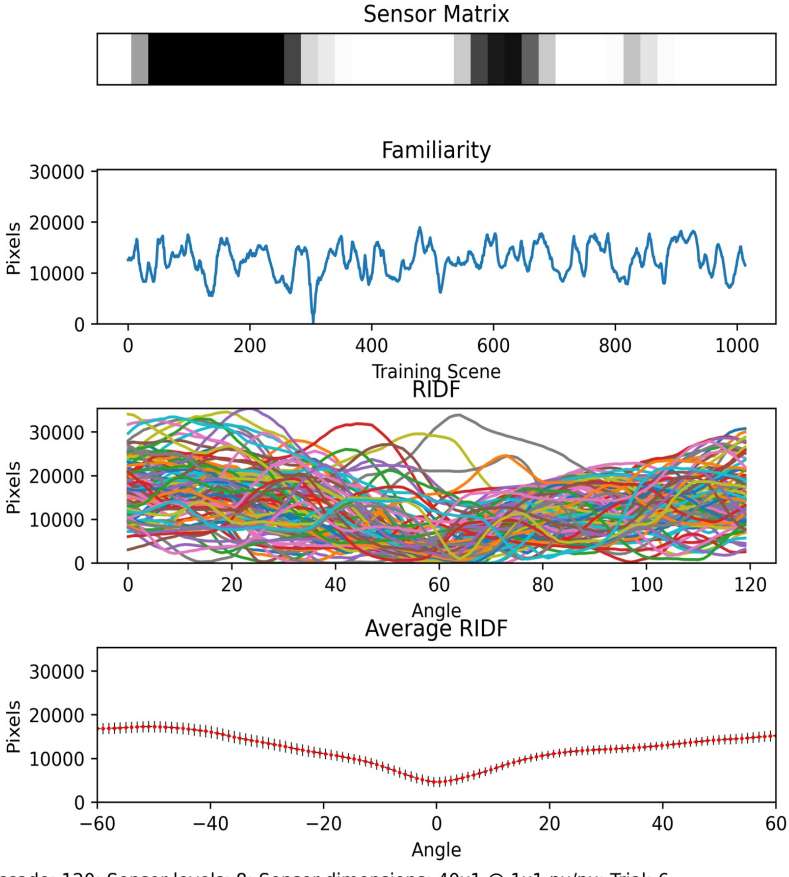
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2890.75; RMSD/dist: 7.227; TD: 12190; p90: 64; p50: 26; complete: 0


Index: BLUR: 9.0; LEVELS: 8; TRIAL: 6
SAD (pixels)
20000
15000
10000
5000
0
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
40
20
0
p50
SAD (pixels)
20
10
0
TD
SAD (pixels)
10000
5000
0
Sensor regions

20%

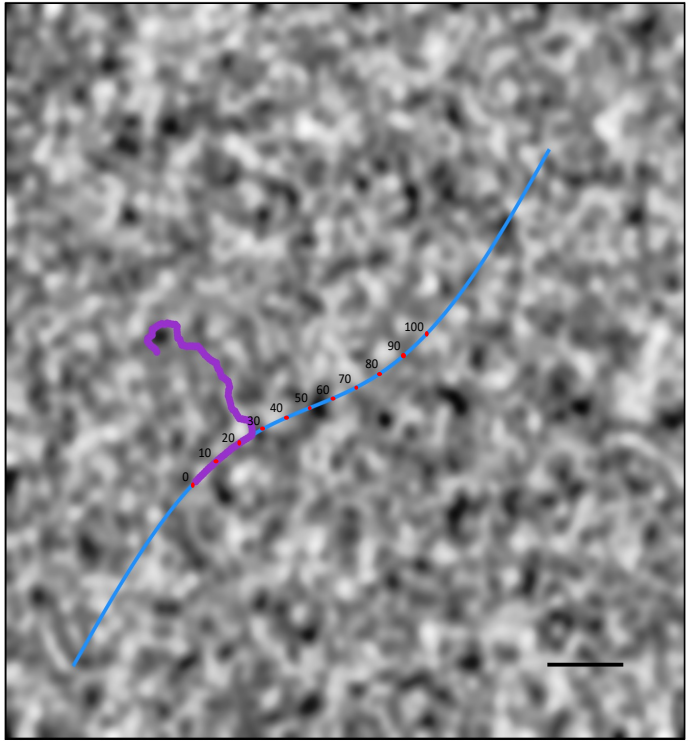


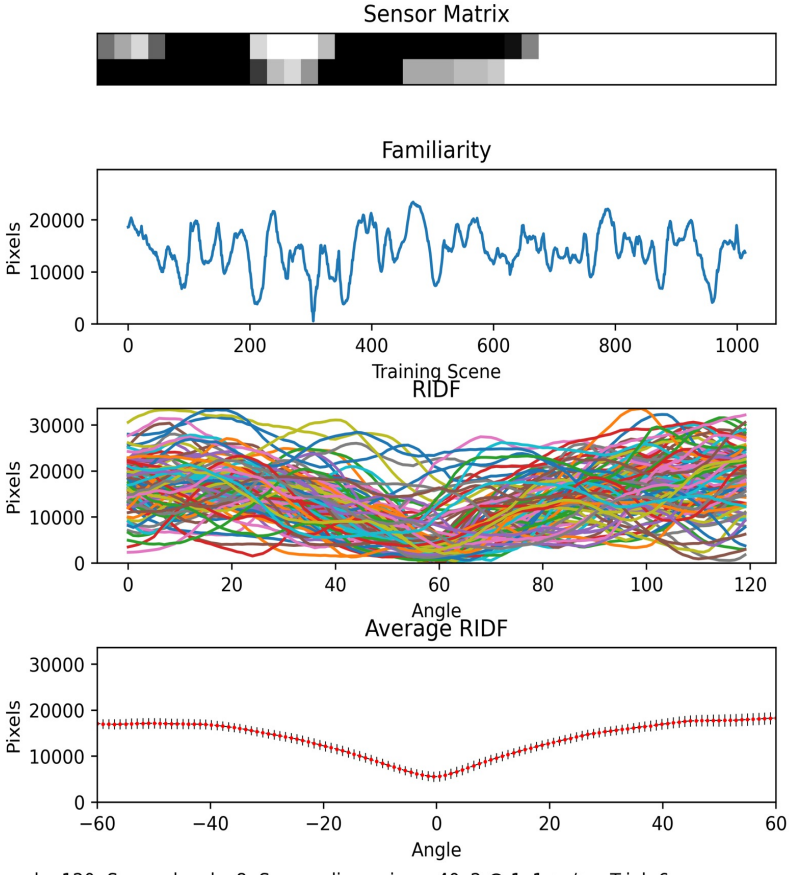


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2294.76; RMSD/dist: 5.737; TD: 8050; p90: 48; p50: 22; complete: 0

20%

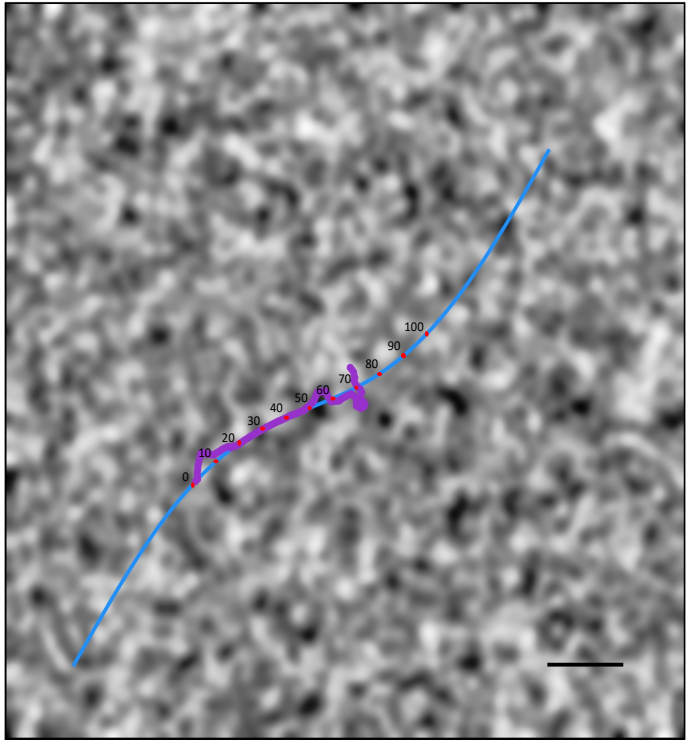


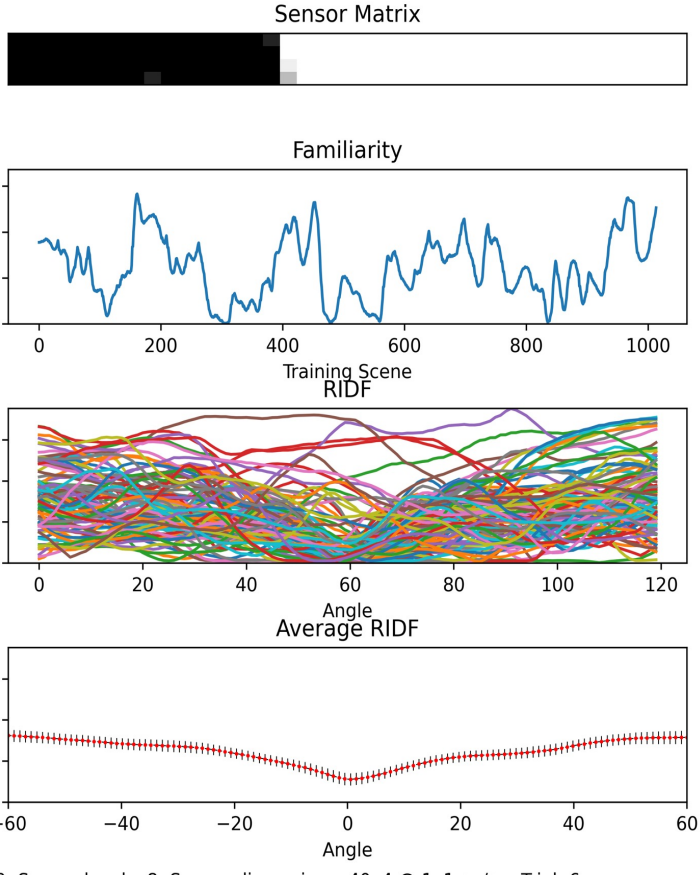


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 8875.40; RMSD/dist: 22.188; TD: 9318; p90: 52; p50: 28; complete: 0

30%

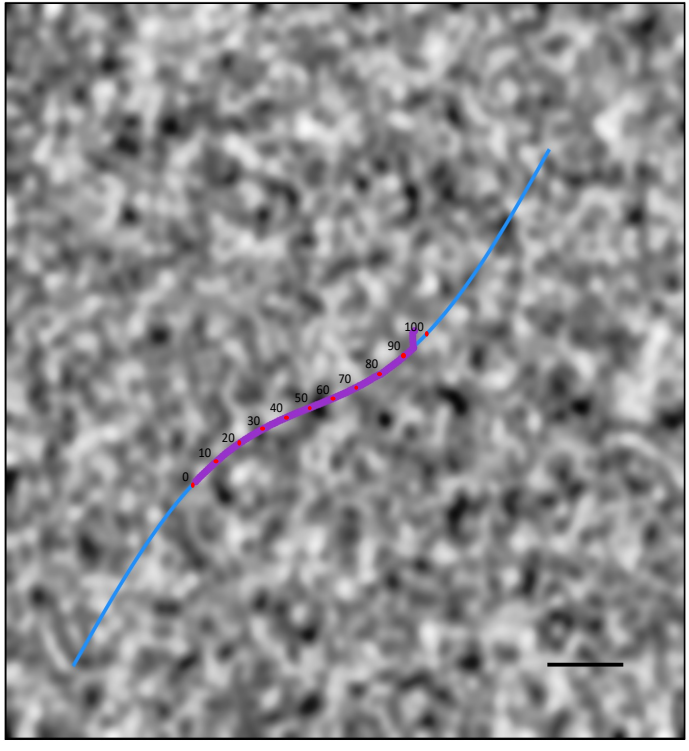


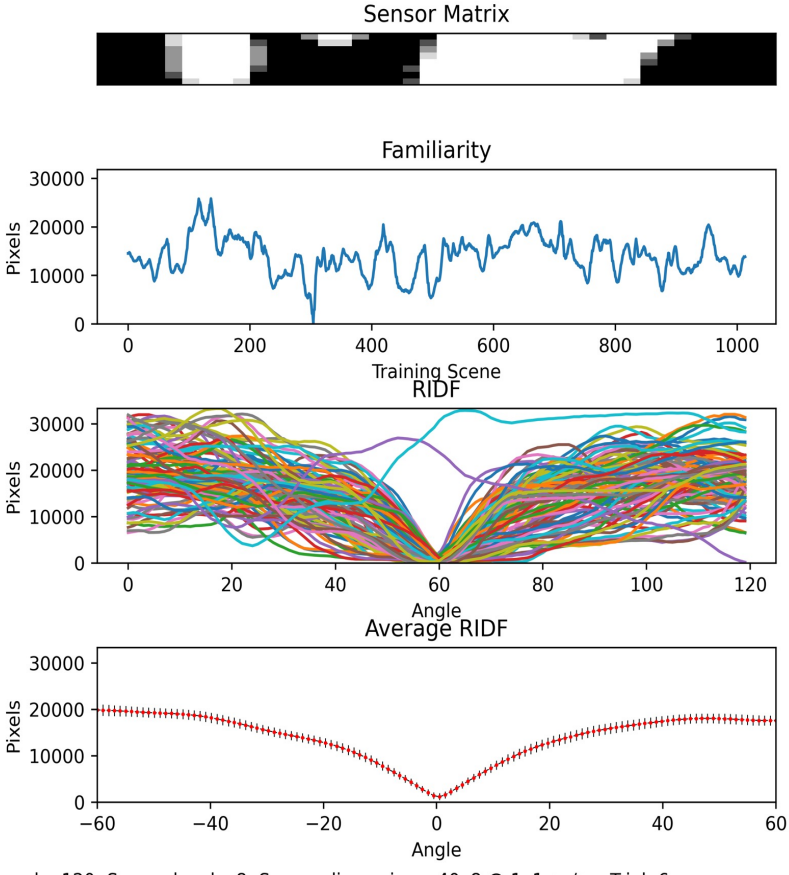


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 815.71; RMSD/dist: 2.039; TD: 8209; p90: 50; p50: 24; complete: 0

90%

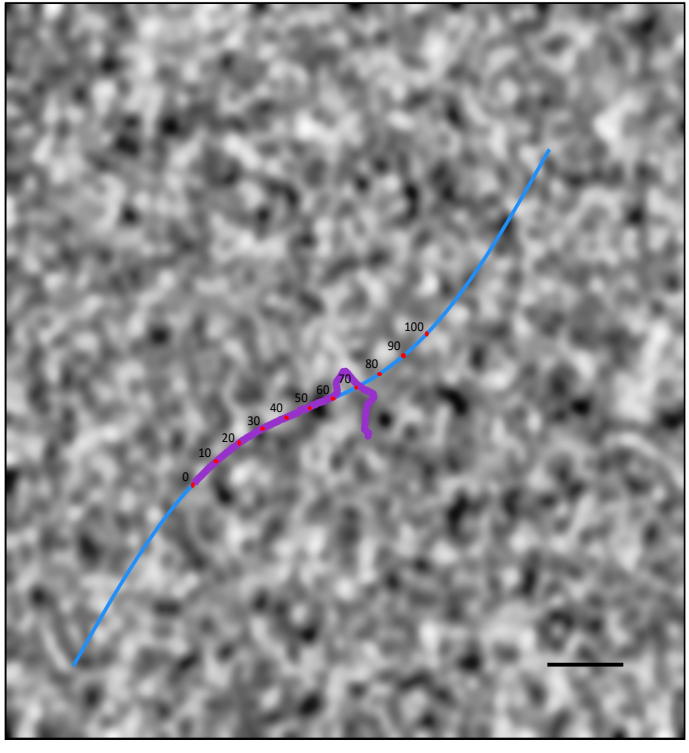


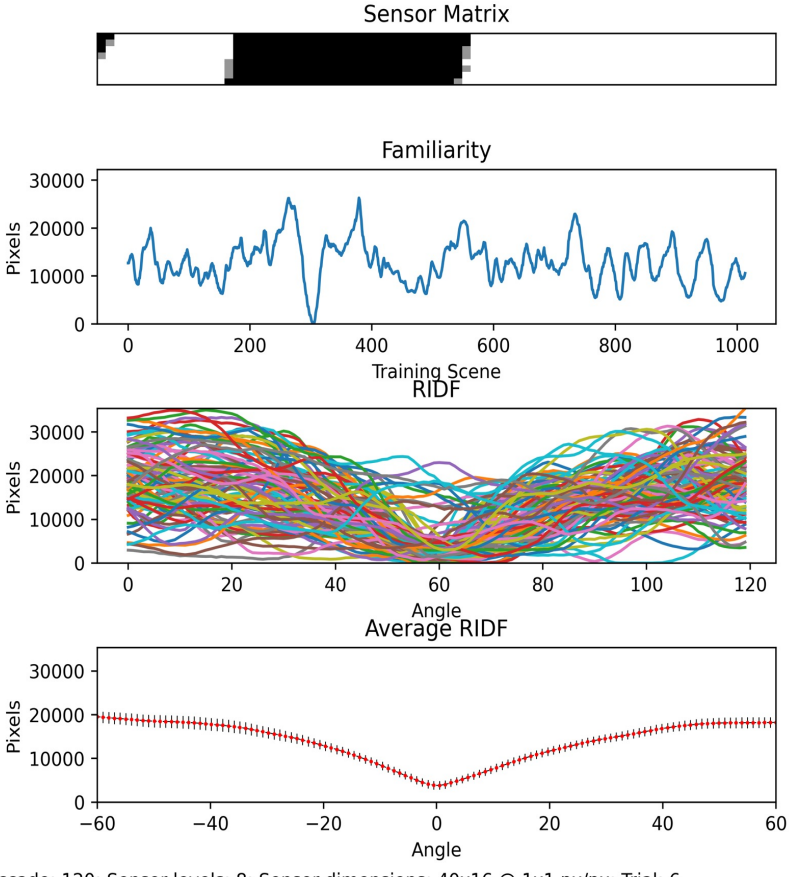


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 98.42; RMSD/dist: 0.246; TD: 13736; p90: 46; p50: 20; complete: 0

60%

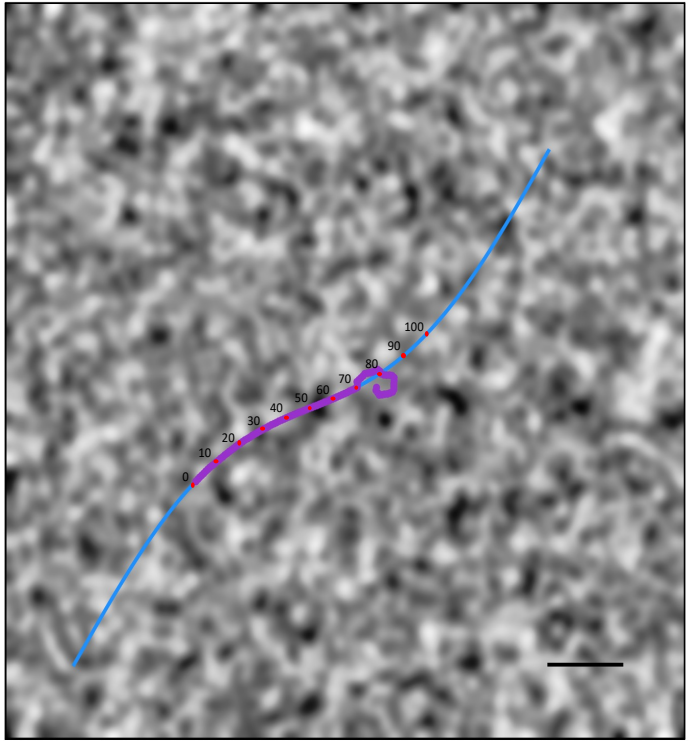


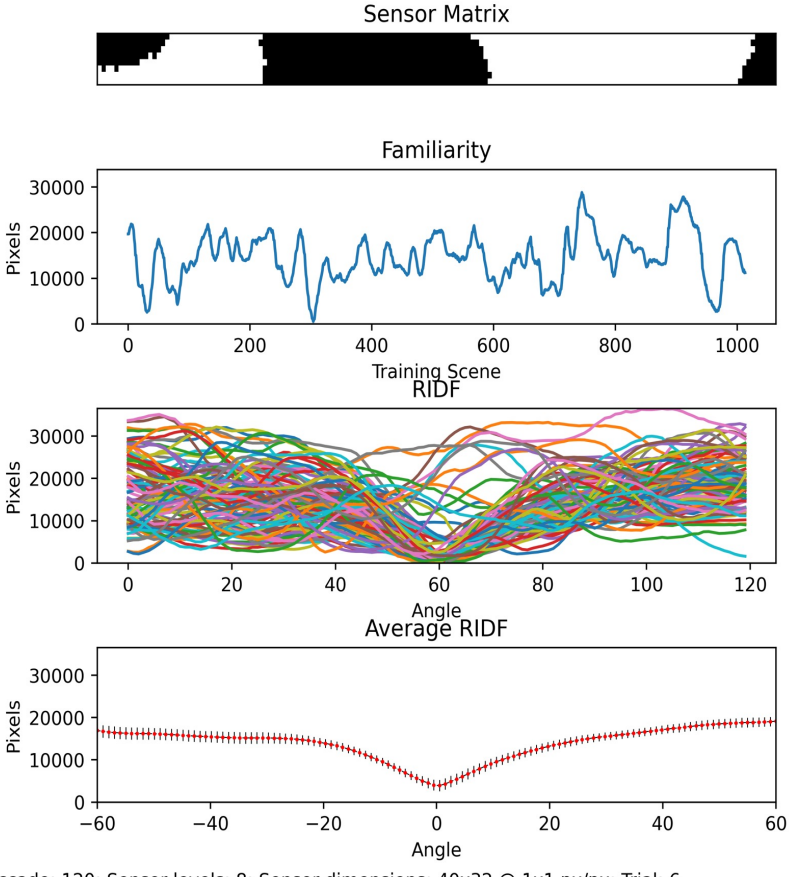


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1062.76; RMSD/dist: 2.657; TD: 10609; p90: 44; p50: 24; complete: 0

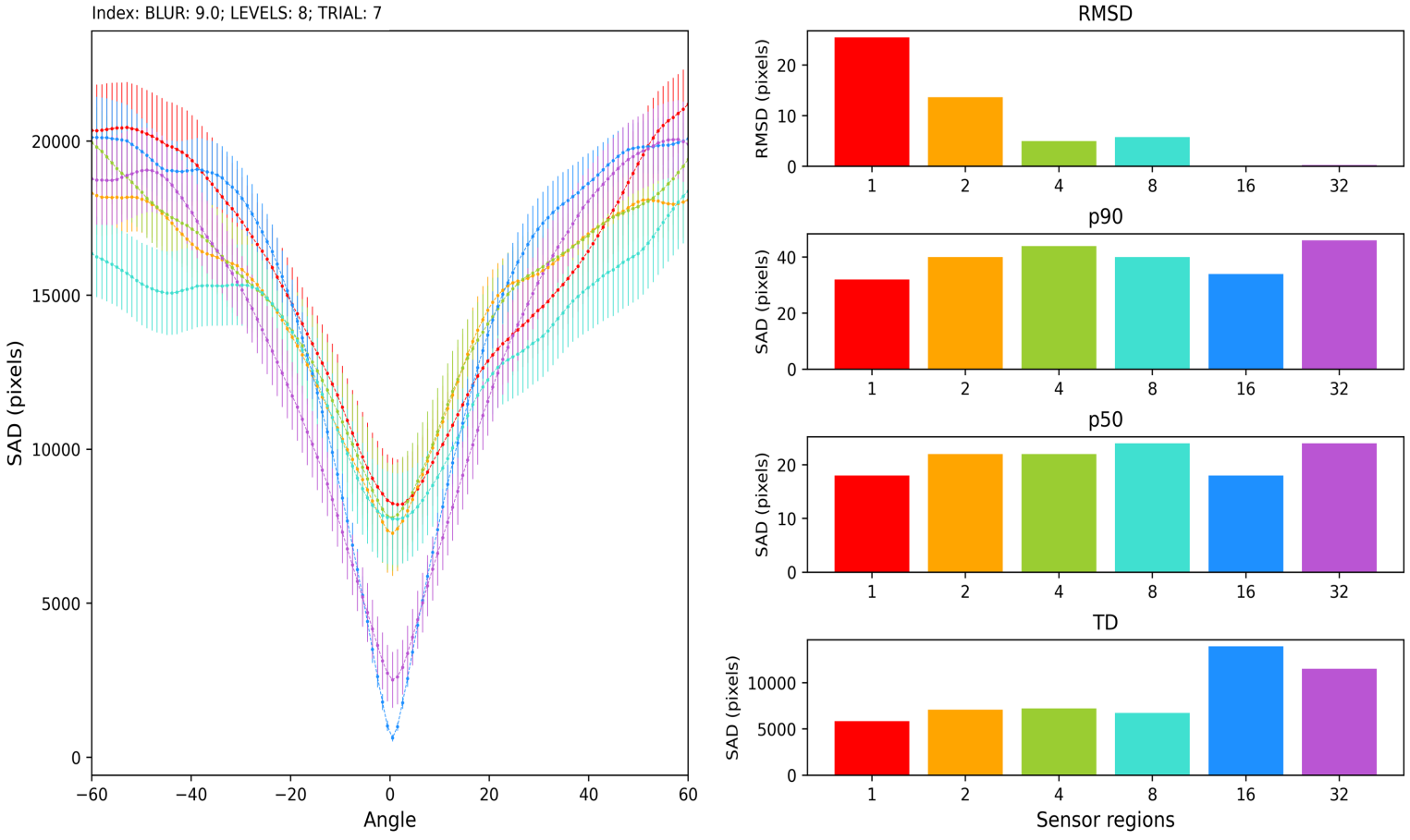
70%



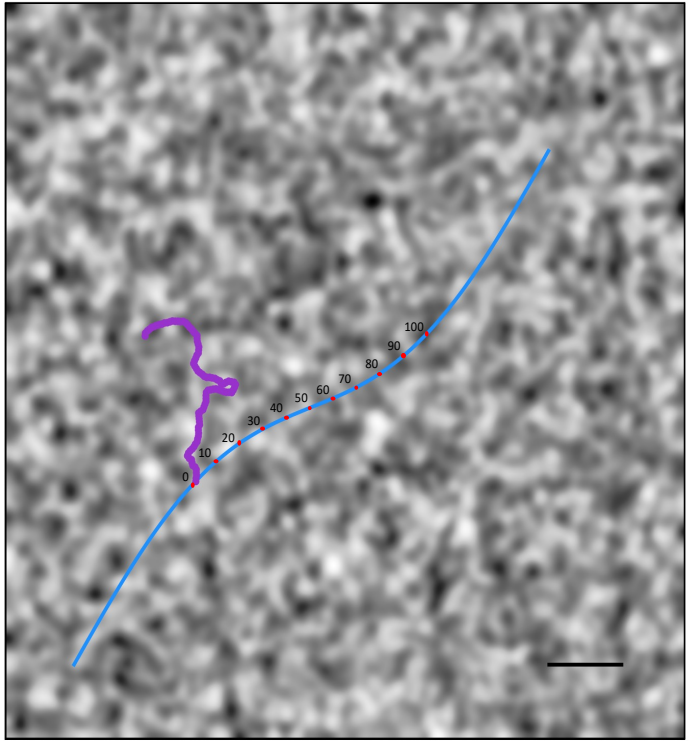


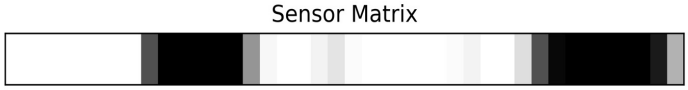
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

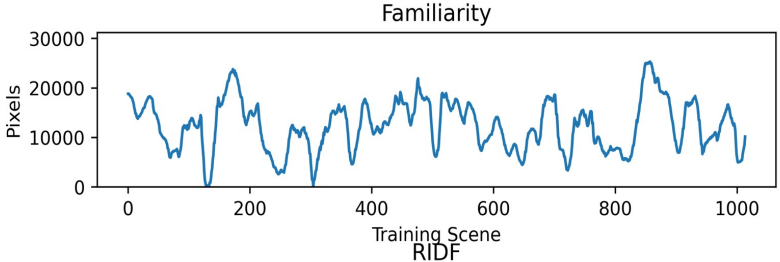
Navigation stats: RMSD error: 475.92; RMSD/dist: 1.190; TD: 11093; p90: 40; p50: 20; complete: 0

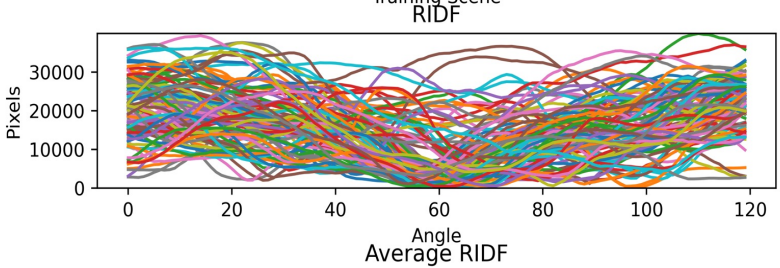

Index: BLUR: 9.0; LEVELS: 8; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

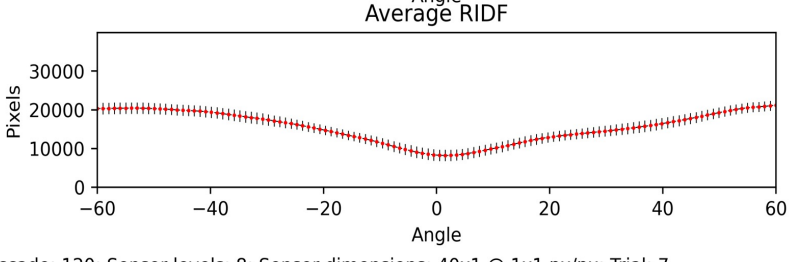
0%







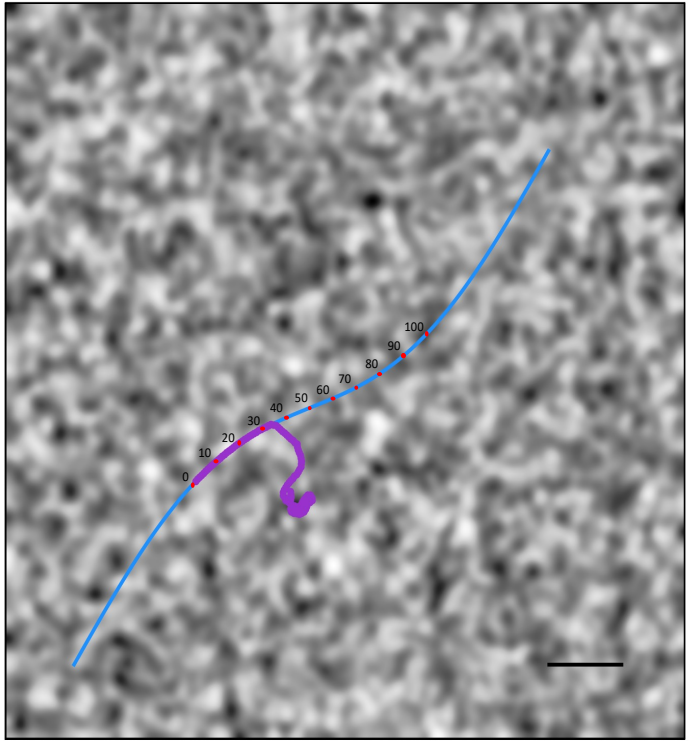


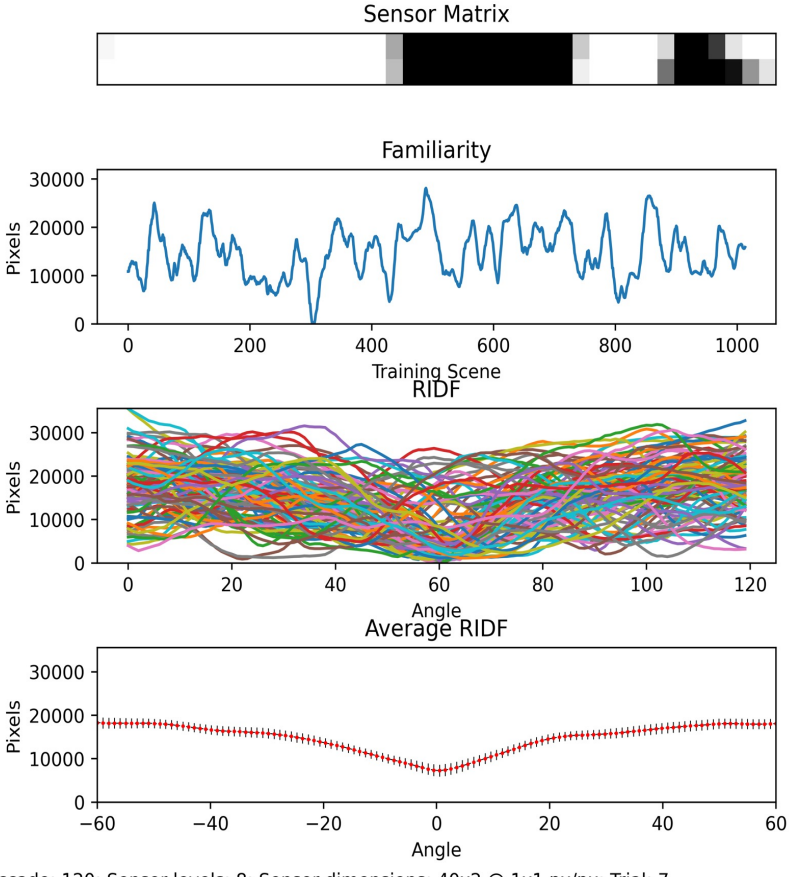


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 10183.26; RMSD/dist: 25.458; TD: 5846; p90: 32; p50: 18; complete: 0

30%

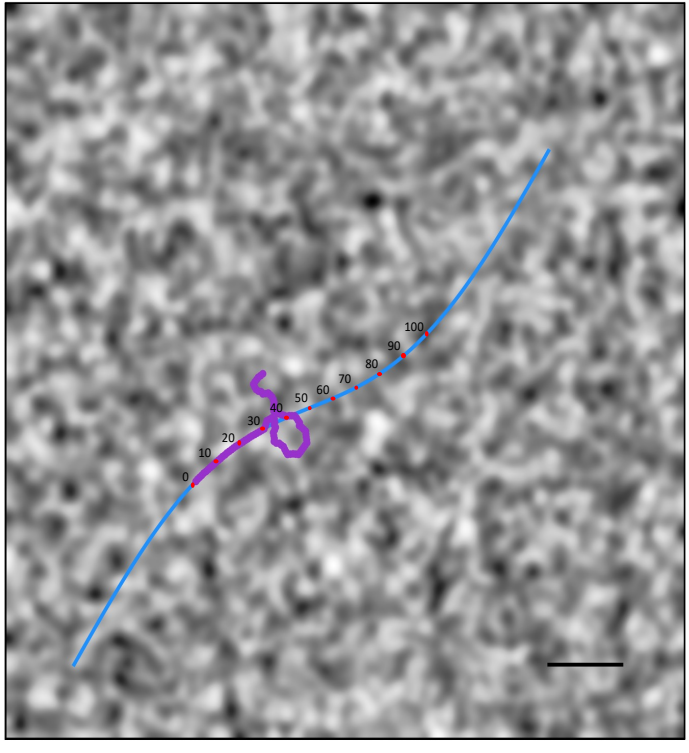


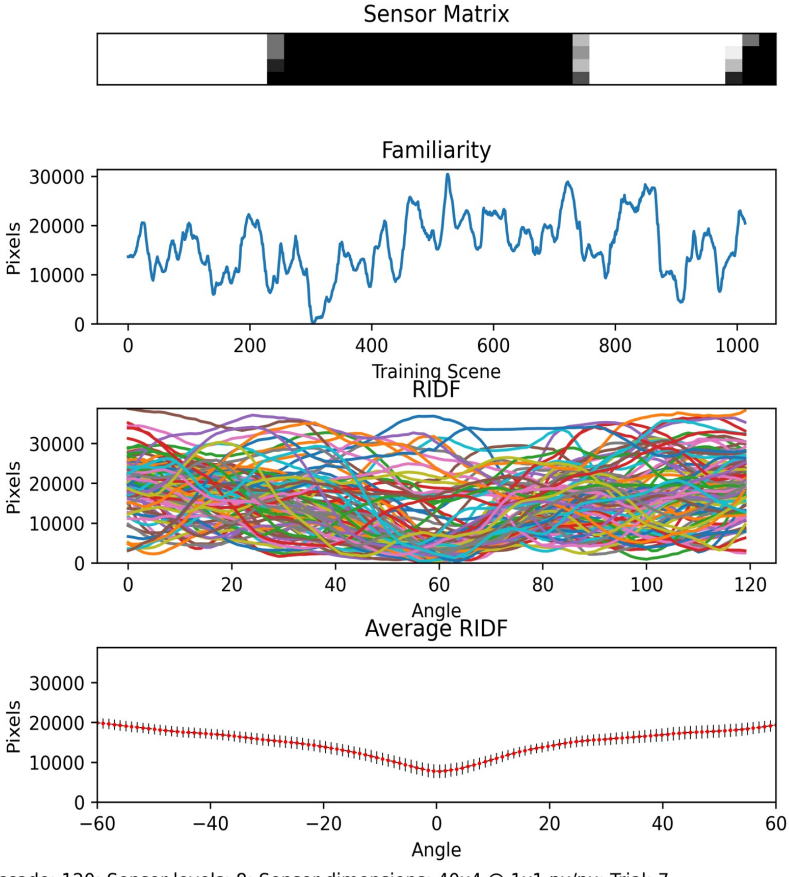


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 5452.62; RMSD/dist: 13.632; TD: 7092; p90: 40; p50: 22; complete: 0

30%





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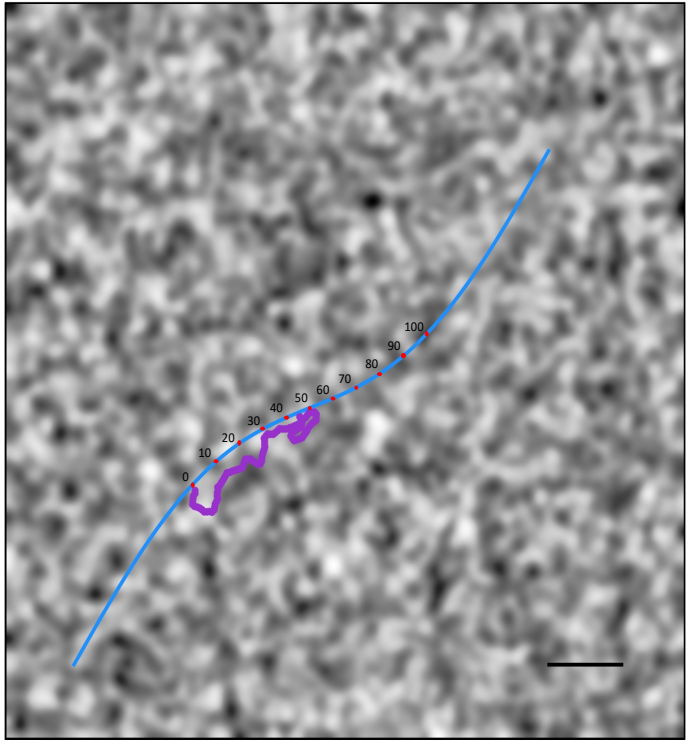
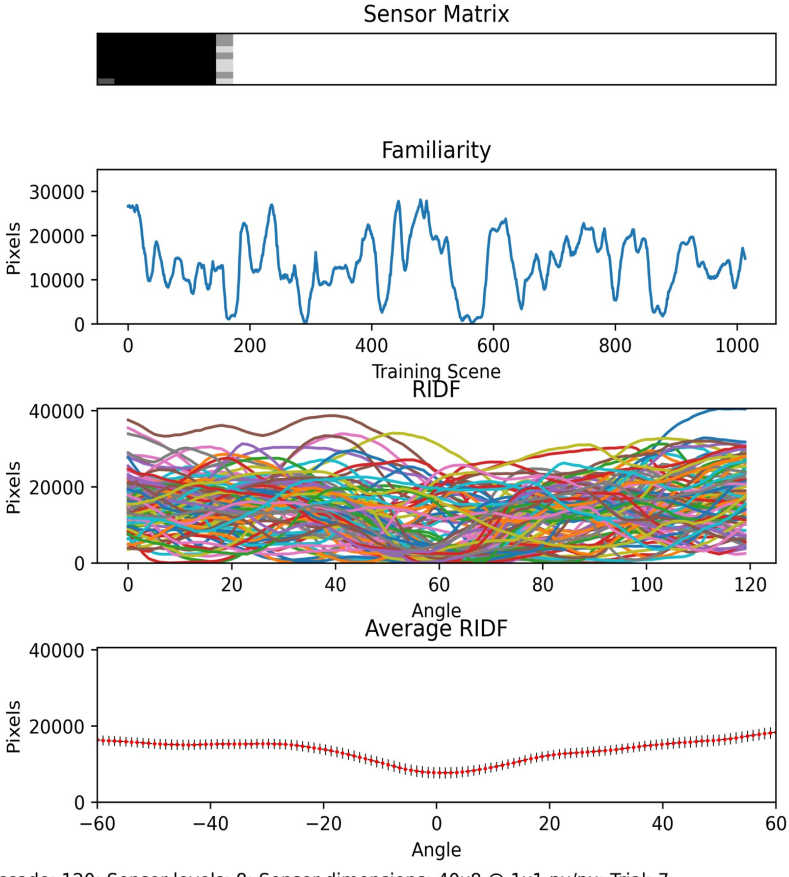
Navigation stats: RMSD error: 1988.33; RMSD/dist: 4.971; TD: 7215; p90: 44; p50: 22; complete: 0

0%

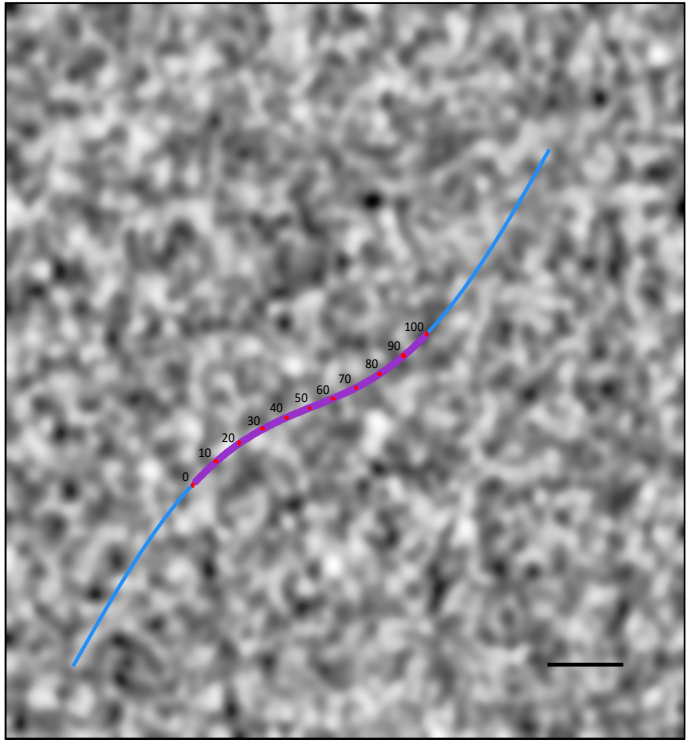


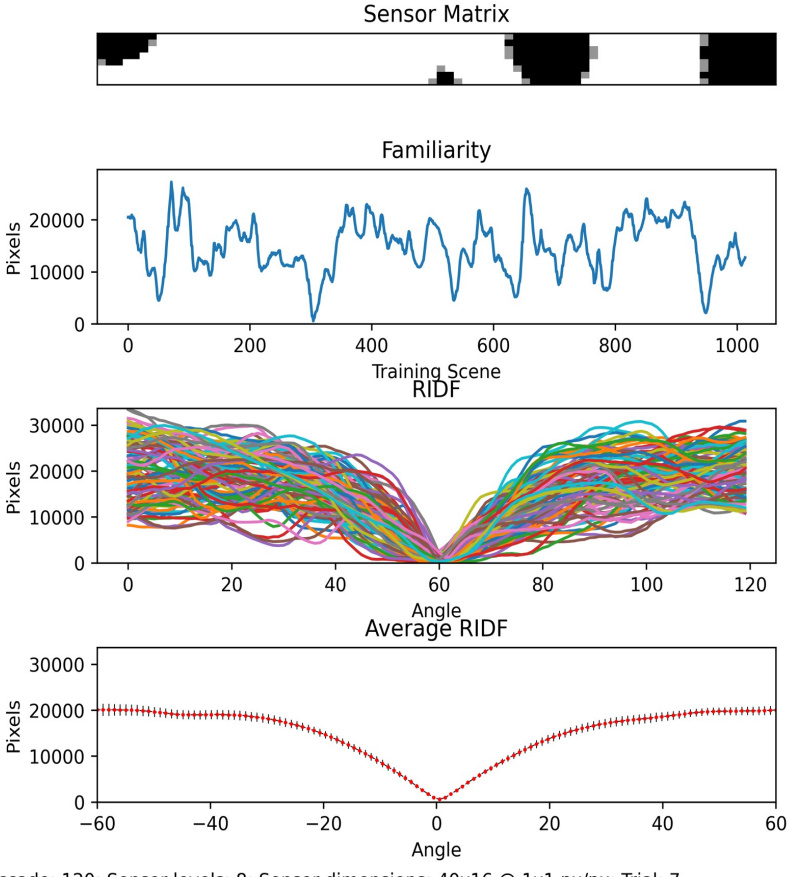


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2312.93; RMSD/dist: 5.782; TD: 6747; p90: 40; p50: 24; complete: 0

100%

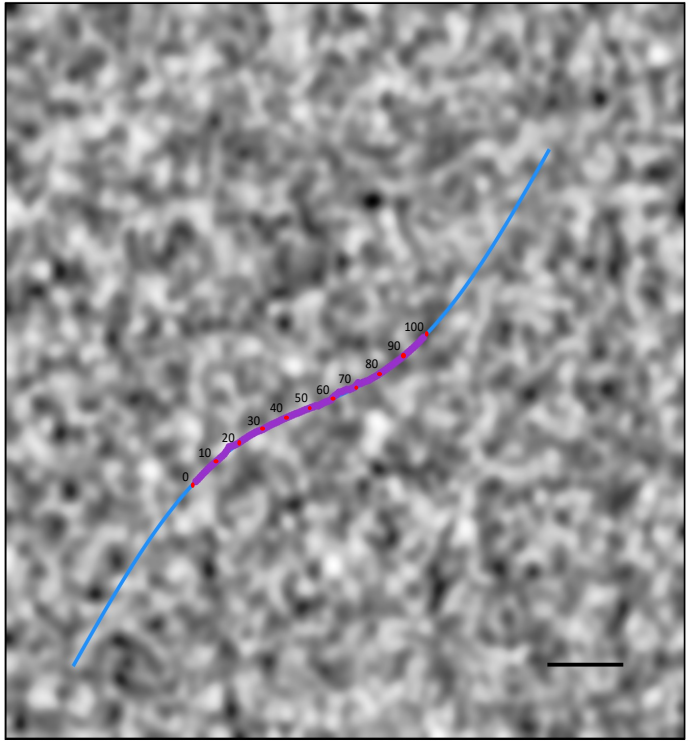


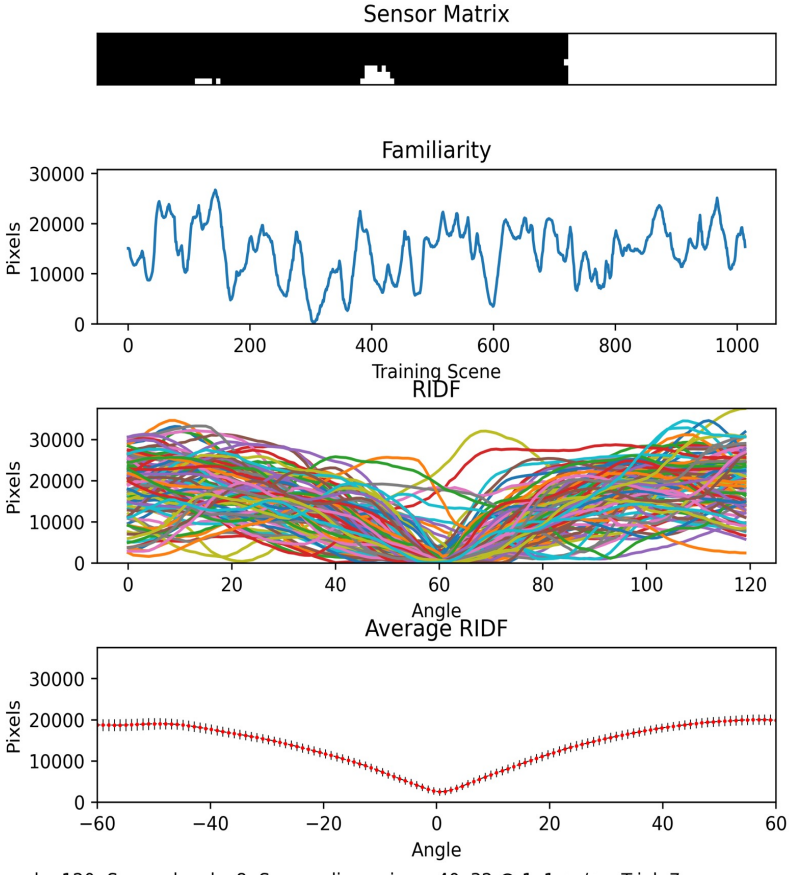


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 22.17; RMSD/dist: 0.055; TD: 13943; p90: 34; p50: 18; complete: 0

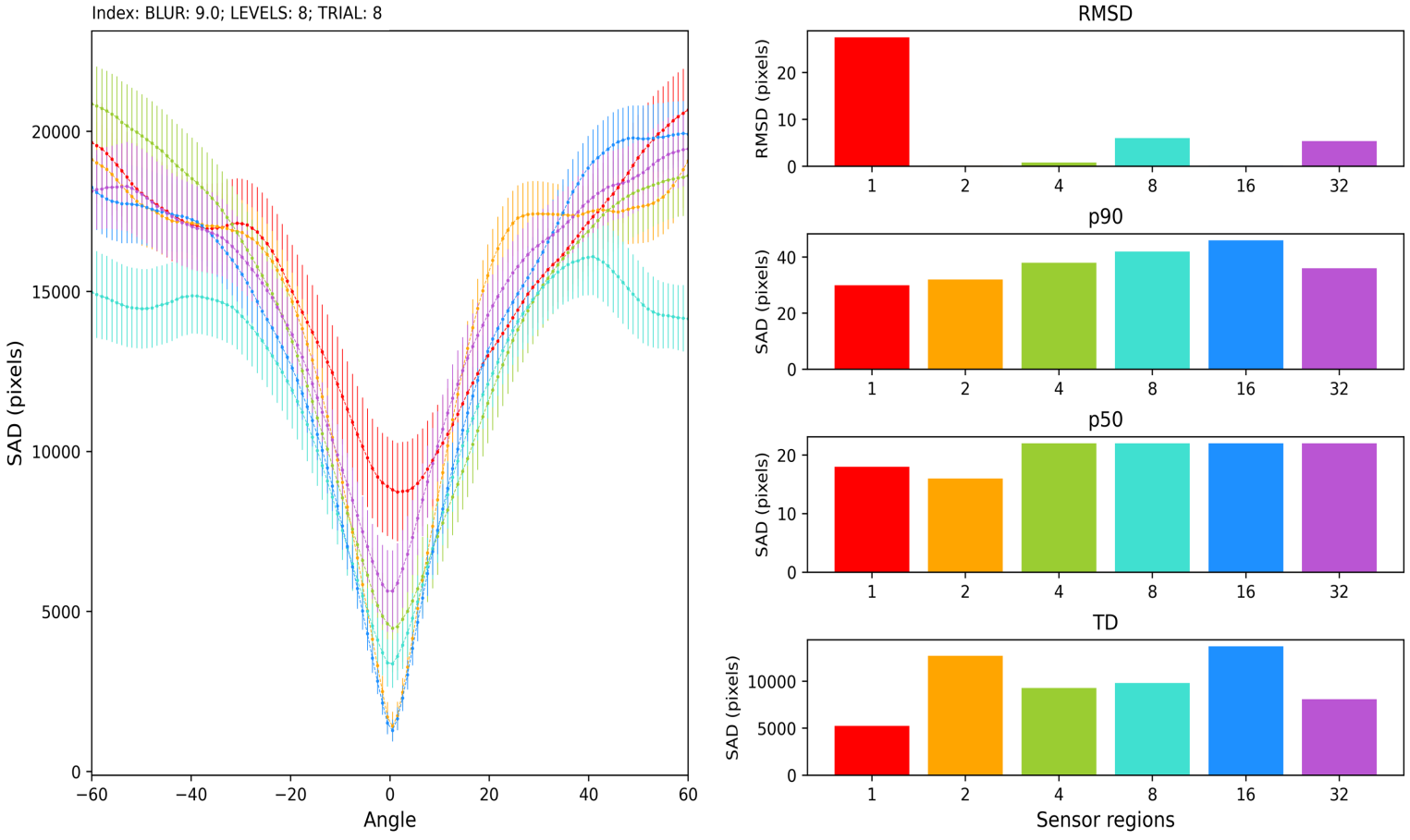
90%



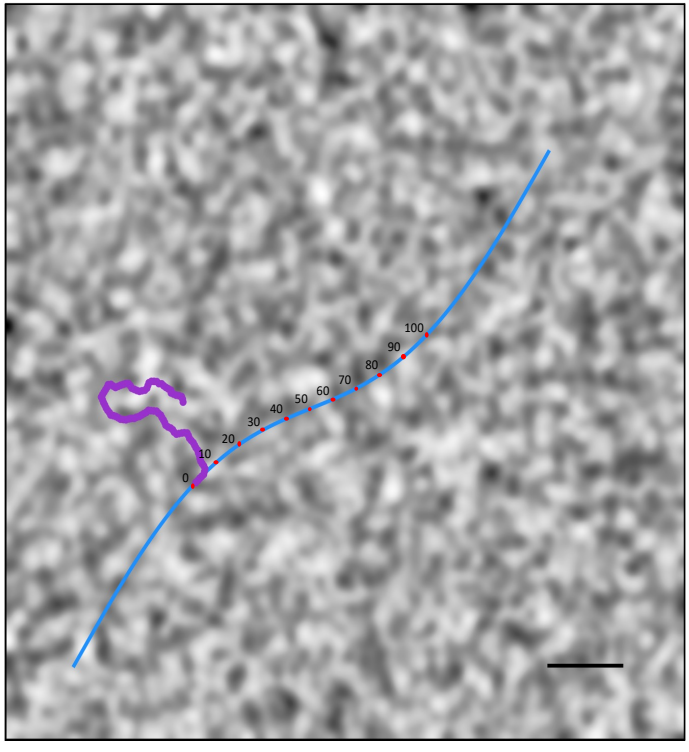


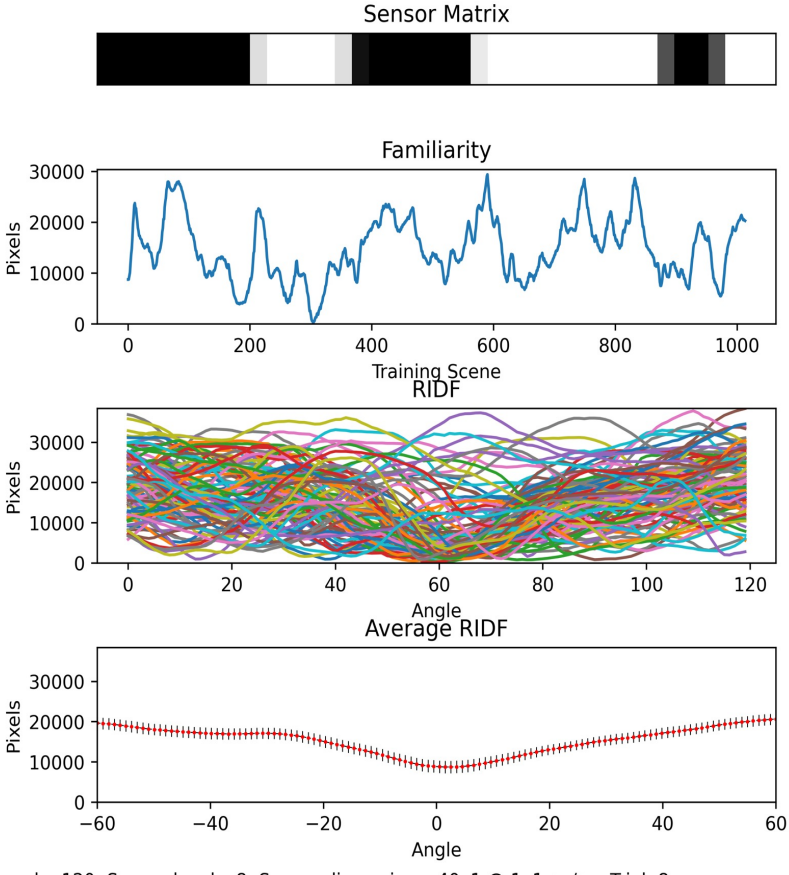
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 101.12; RMSD/dist: 0.253; TD: 11513; p90: 46; p50: 24; complete: 0


Index: BLUR: 9.0; LEVELS: 8; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

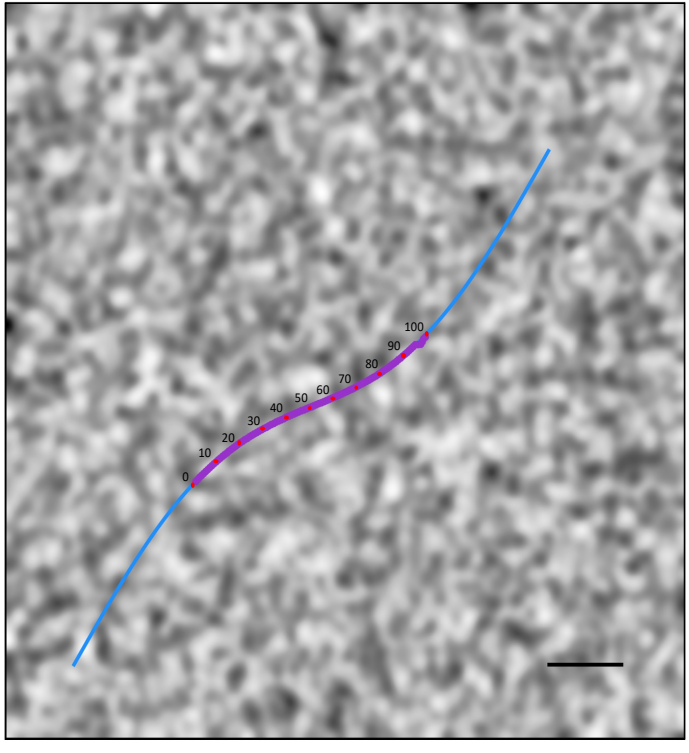


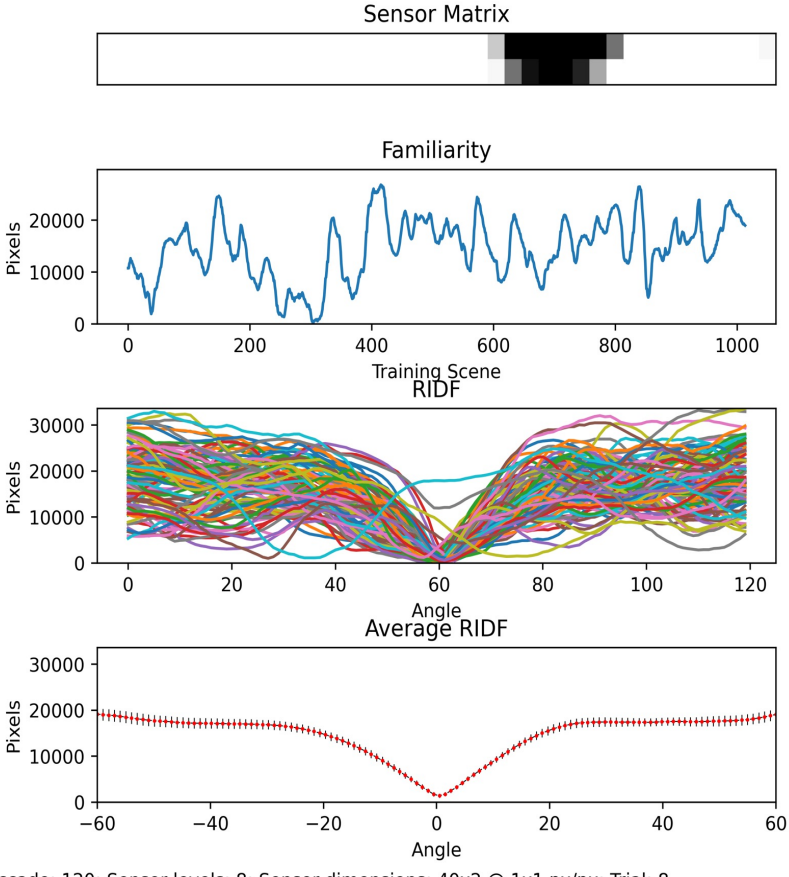


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 10993.41; RMSD/dist: 27.484; TD: 5256; p90: 30; p50: 18; complete: 0

90%

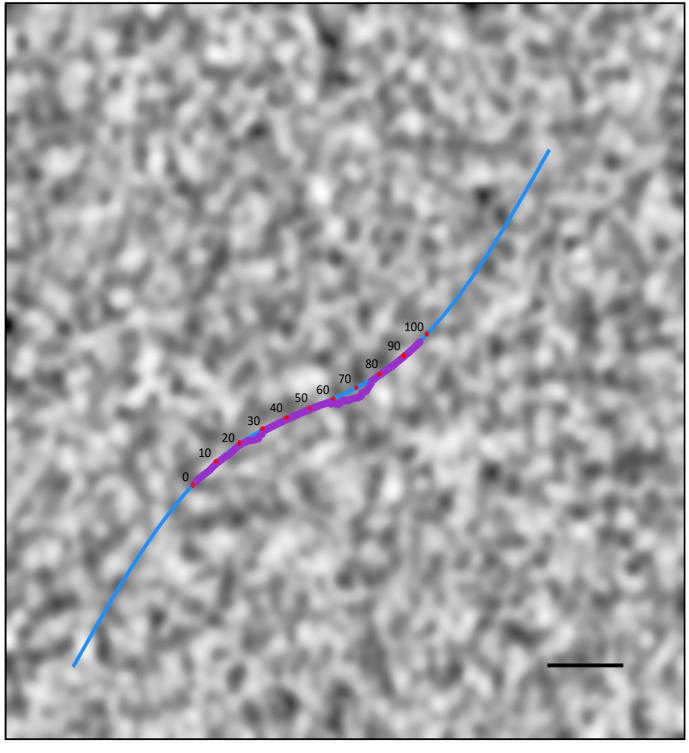


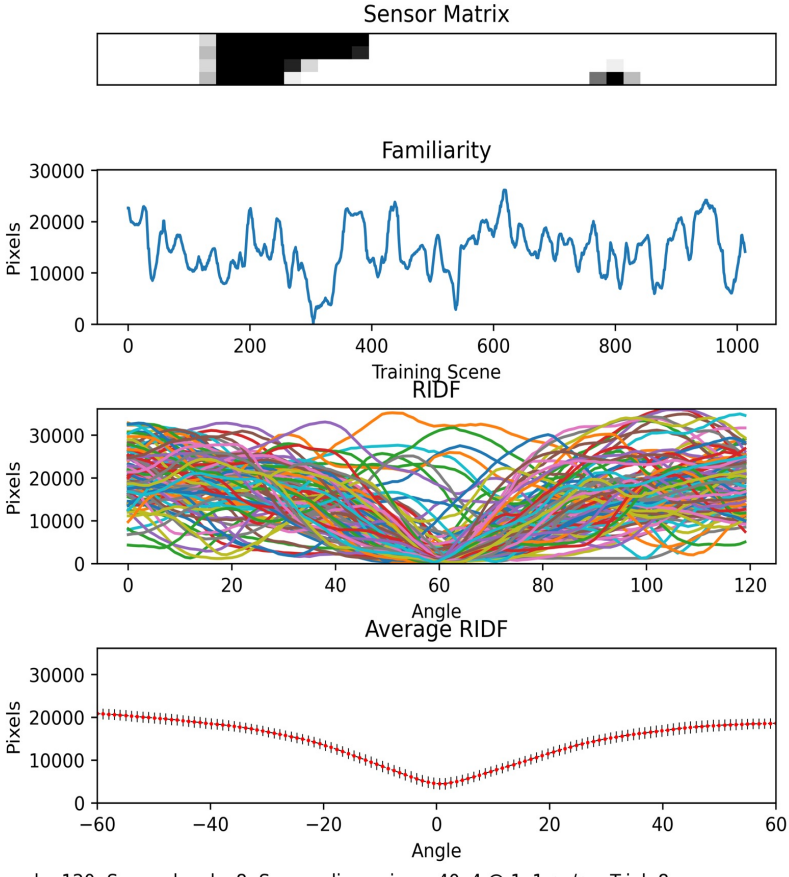


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 62.92; RMSD/dist: 0.157; TD: 12718; p90: 32; p50: 16; complete: 0

60%

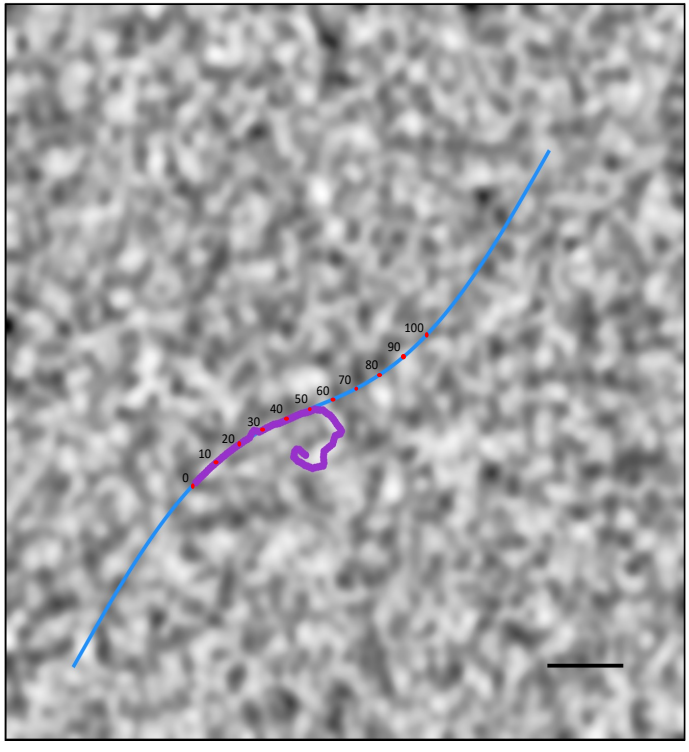


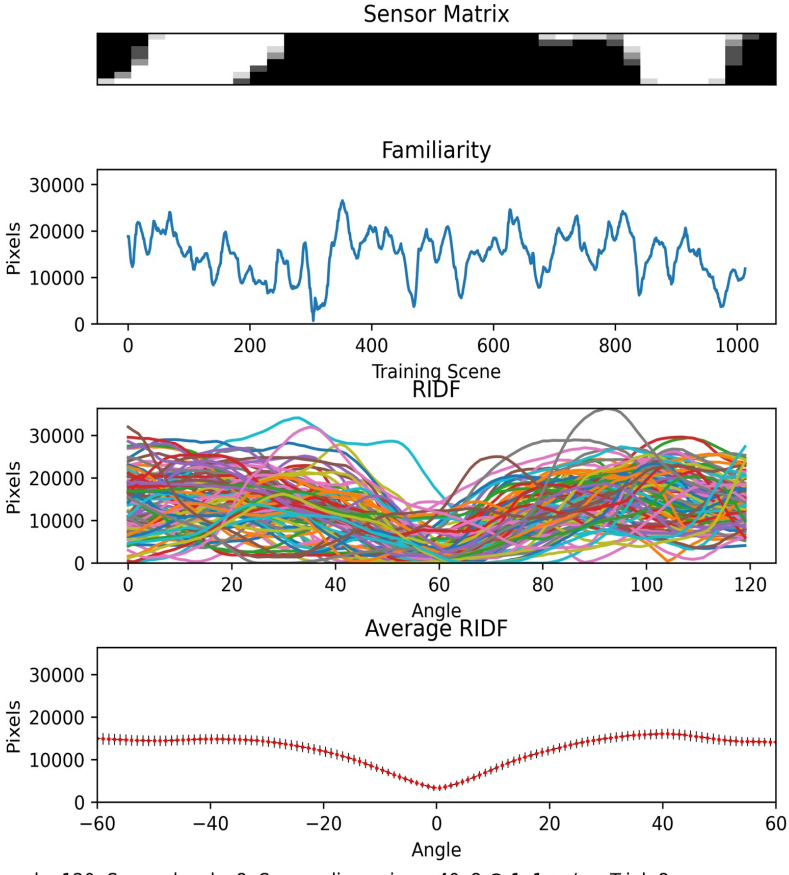


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 309.85; RMSD/dist: 0.775; TD: 9277; p90: 38; p50: 22; complete: 0

40%

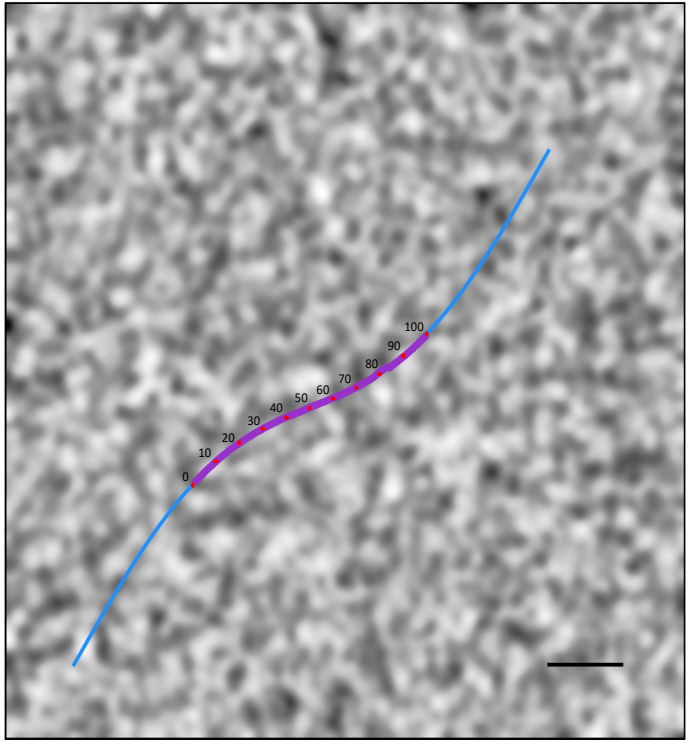


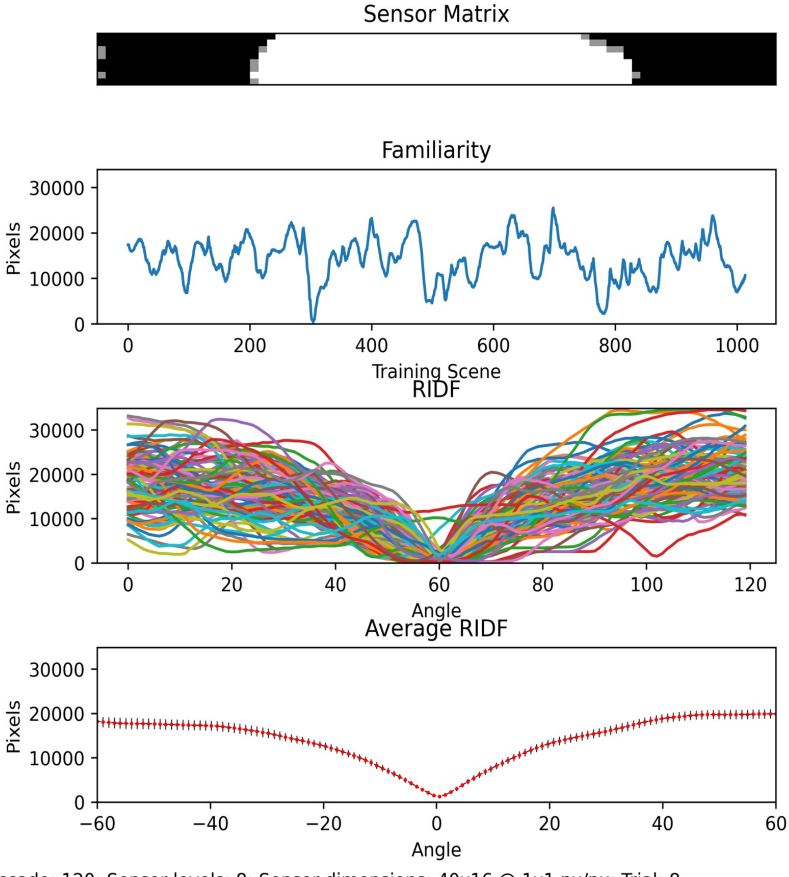


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2411.22; RMSD/dist: 6.028; TD: 9830; p90: 42; p50: 22; complete: 0

100%

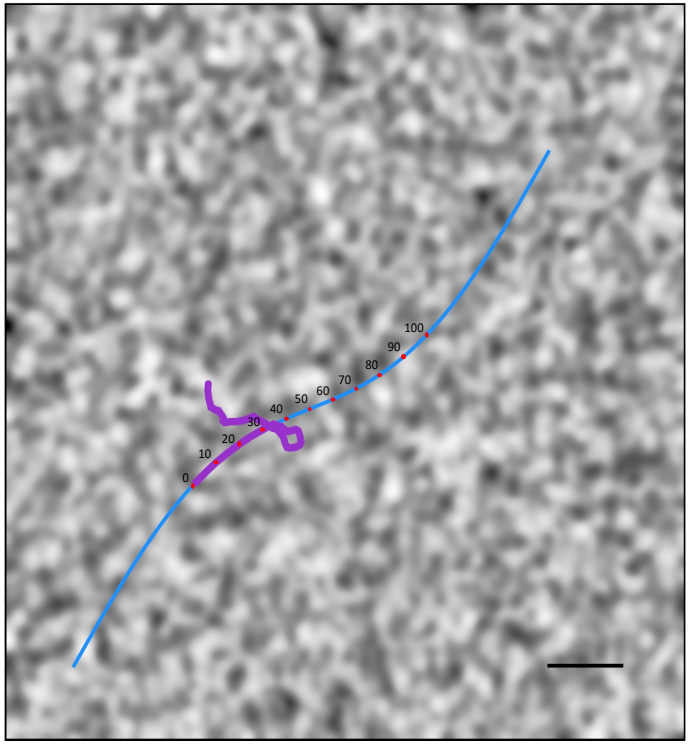


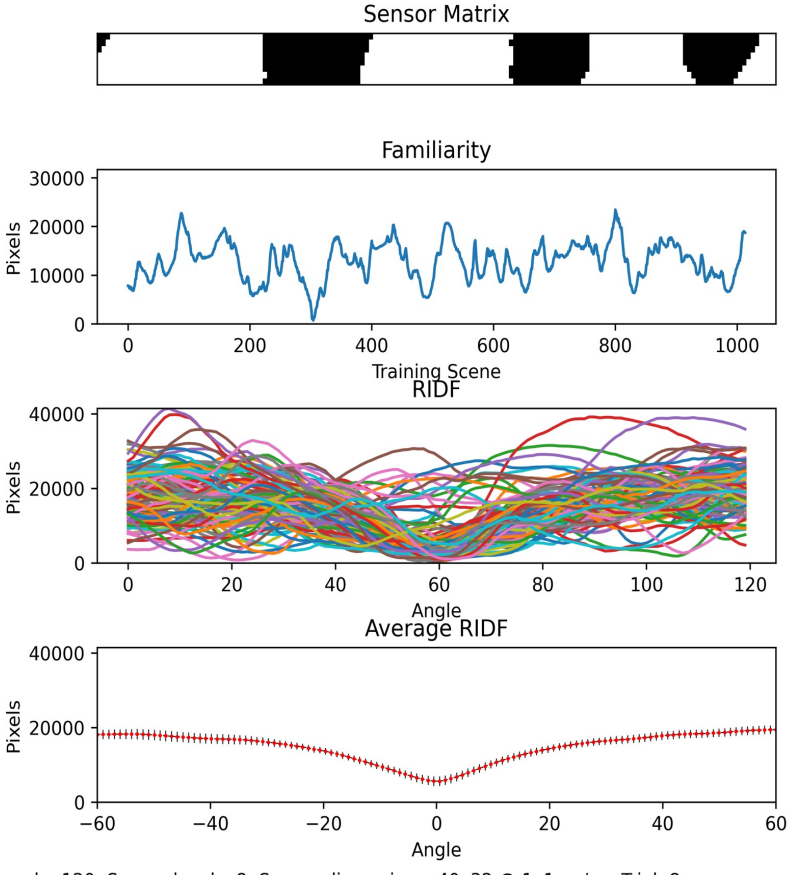


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 66.72; RMSD/dist: 0.167; TD: 13726; p90: 46; p50: 22; complete: 0

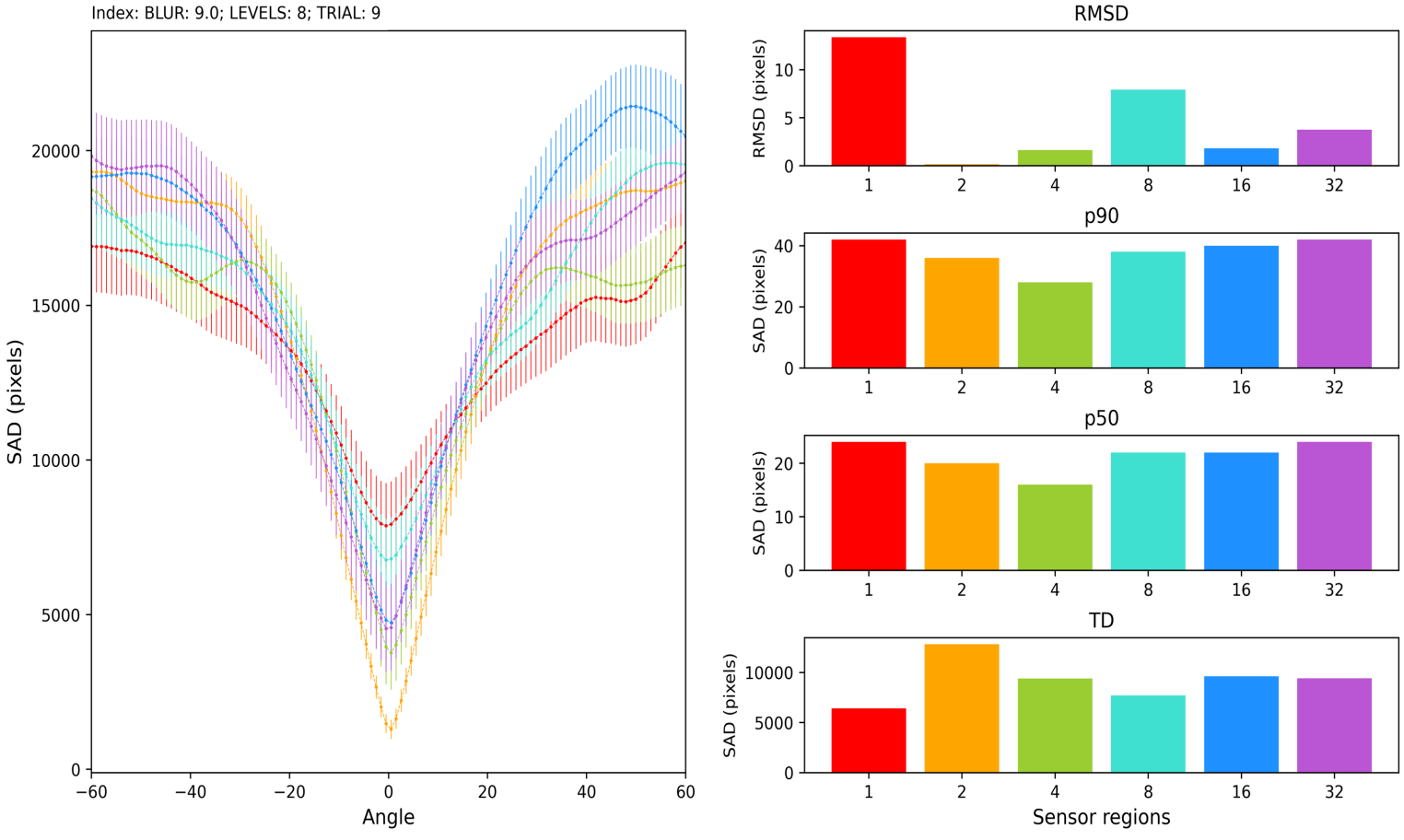
30%



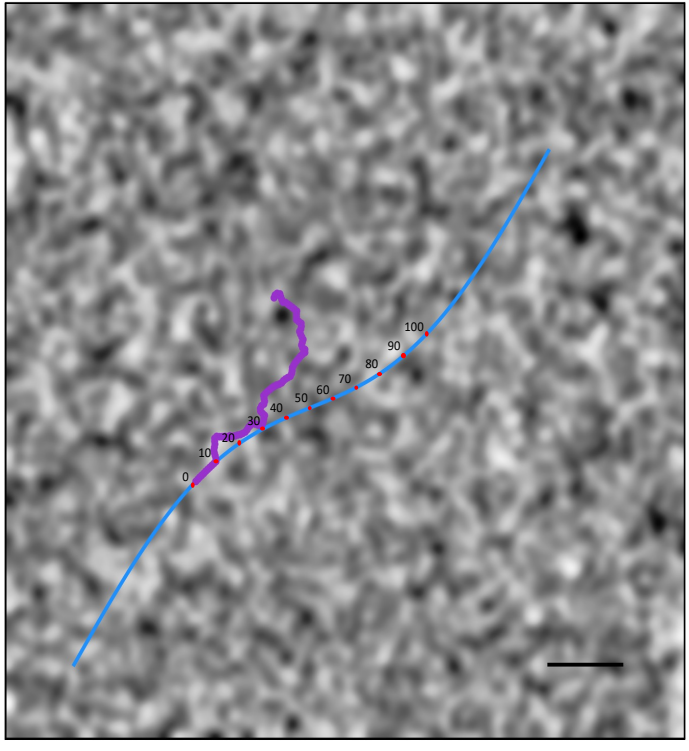


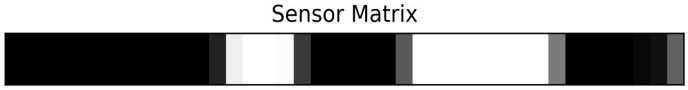
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

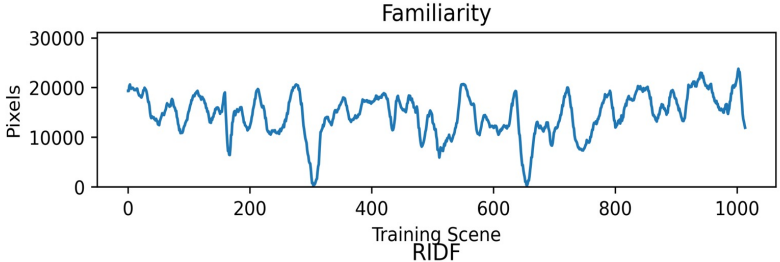
Navigation stats: RMSD error: 2145.87; RMSD/dist: 5.365; TD: 8083; p90: 36; p50: 22; complete: 0

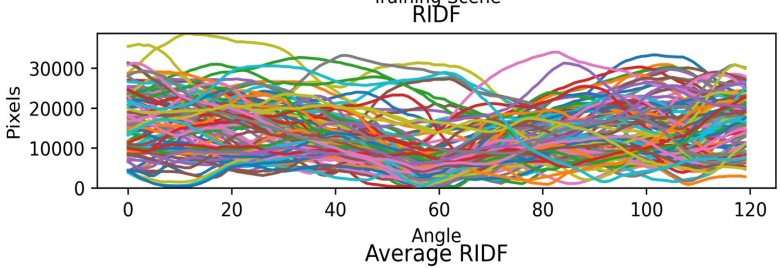

Index: BLUR: 9.0; LEVELS: 8; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

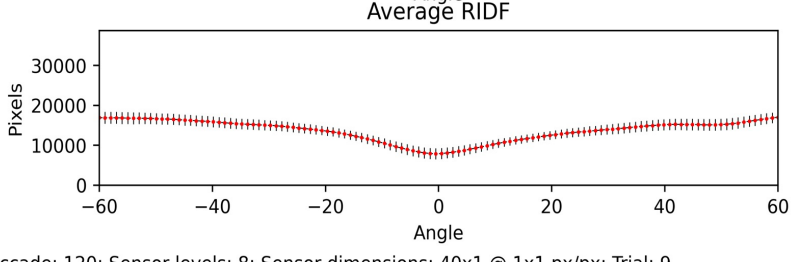
10%







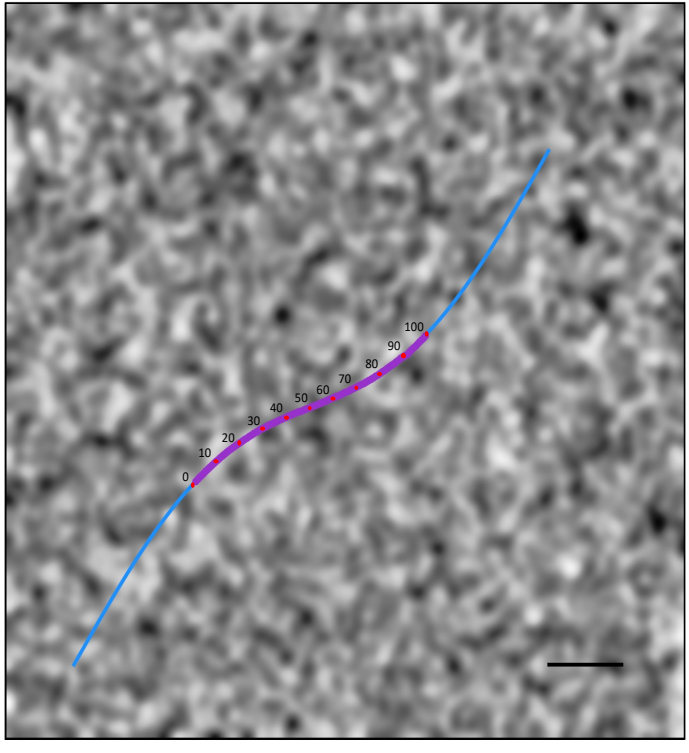


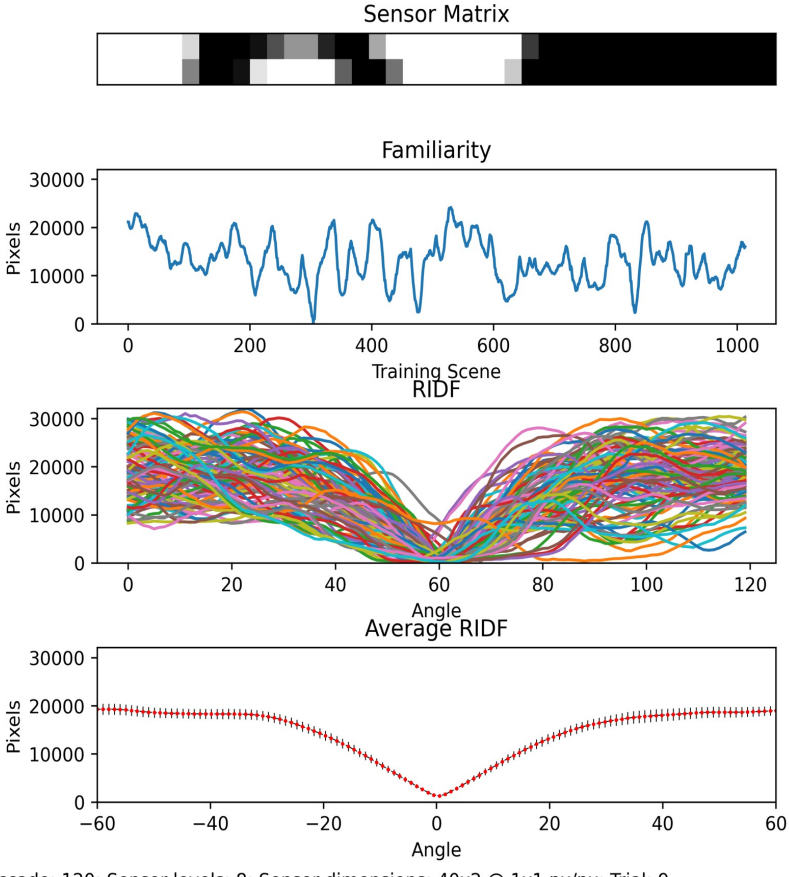


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 5353.18; RMSD/dist: 13.383; TD: 6419; p90: 42; p50: 24; complete: 0

100%

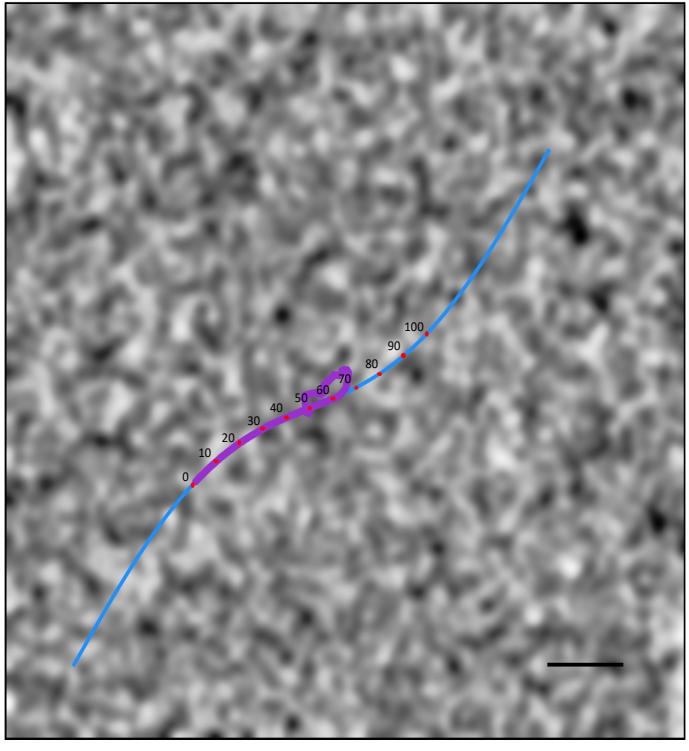


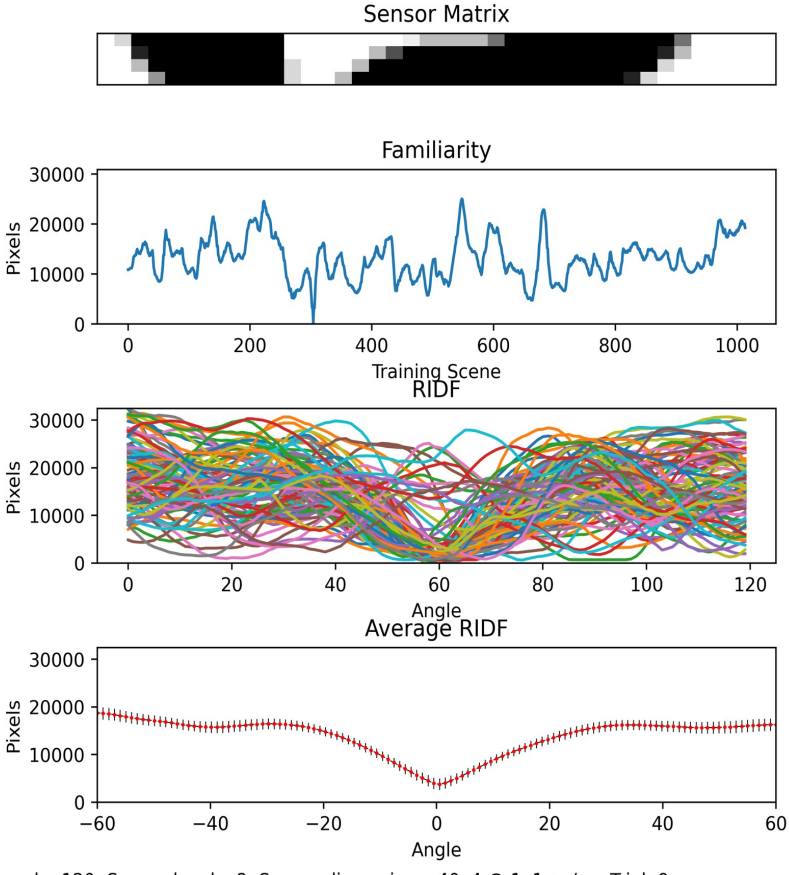


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 63.35; RMSD/dist: 0.158; TD: 12820; p90: 36; p50: 20; complete: 0

60%

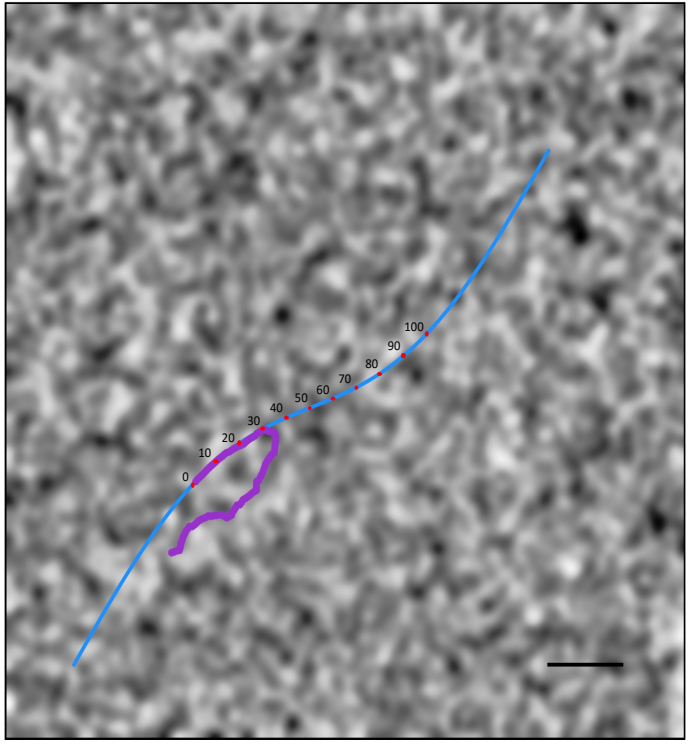


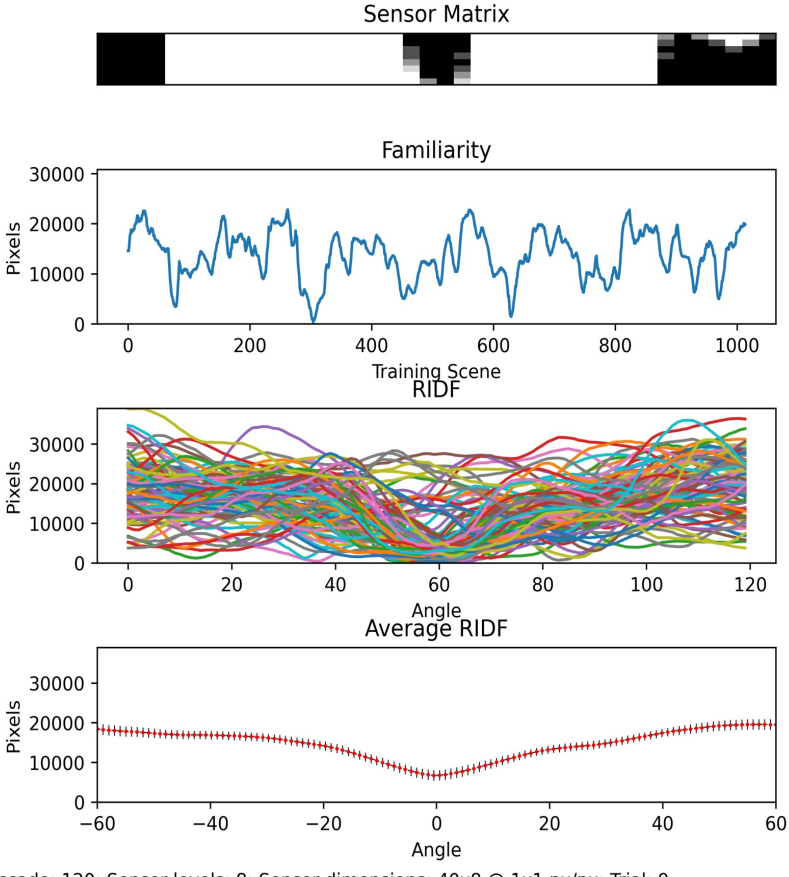


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 646.26; RMSD/dist: 1.616; TD: 9396; p90: 28; p50: 16; complete: 0

30%





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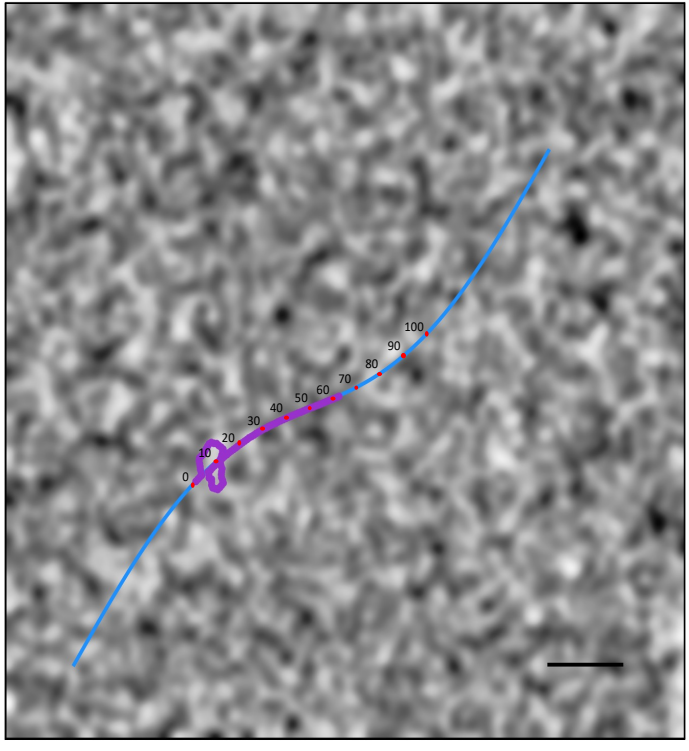
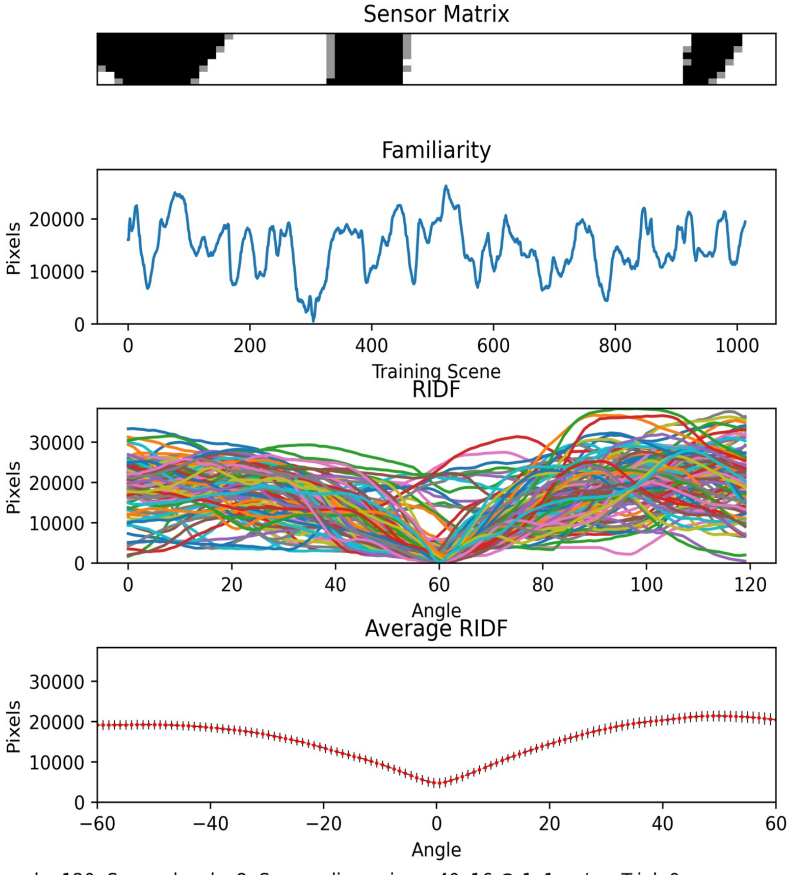
Navigation stats: RMSD error: 3172.57; RMSD/dist: 7.931; TD: 7704; p90: 38; p50: 22; complete: 0

60%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

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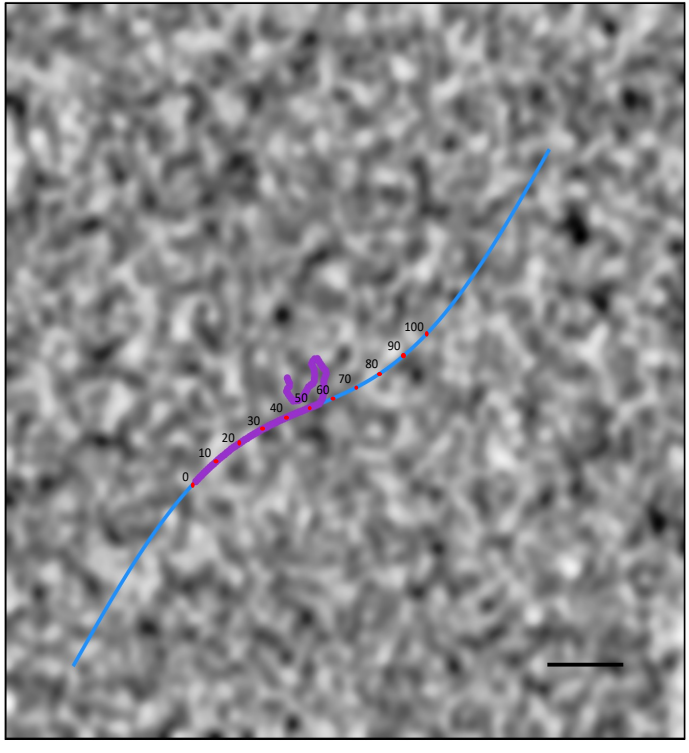
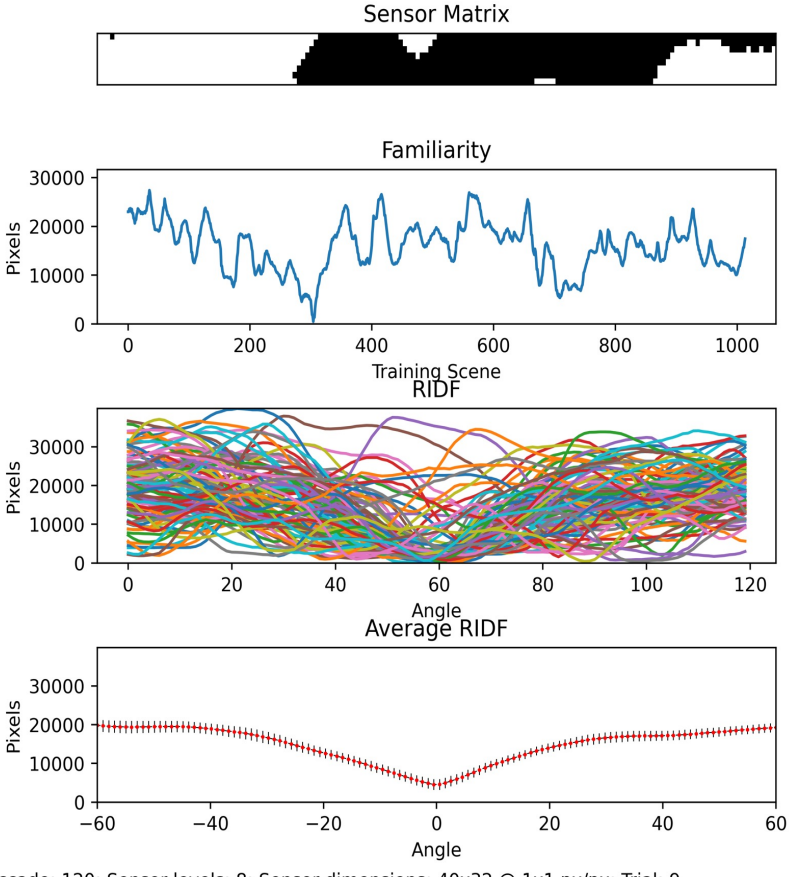
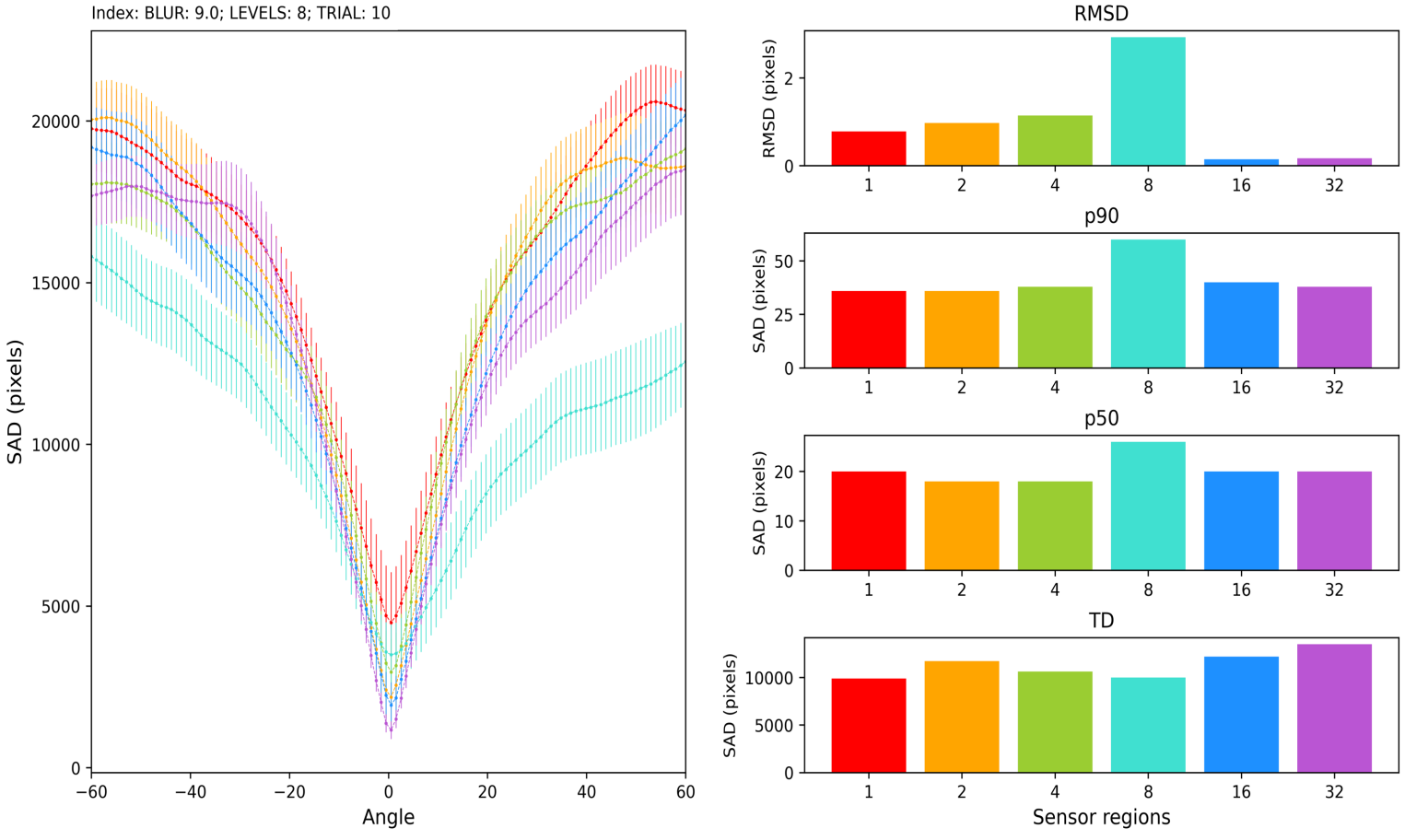
50%



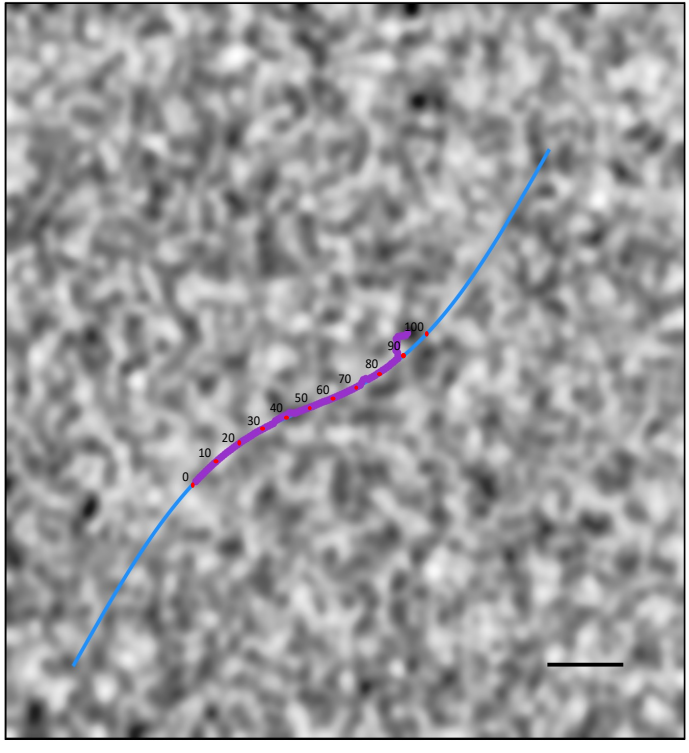


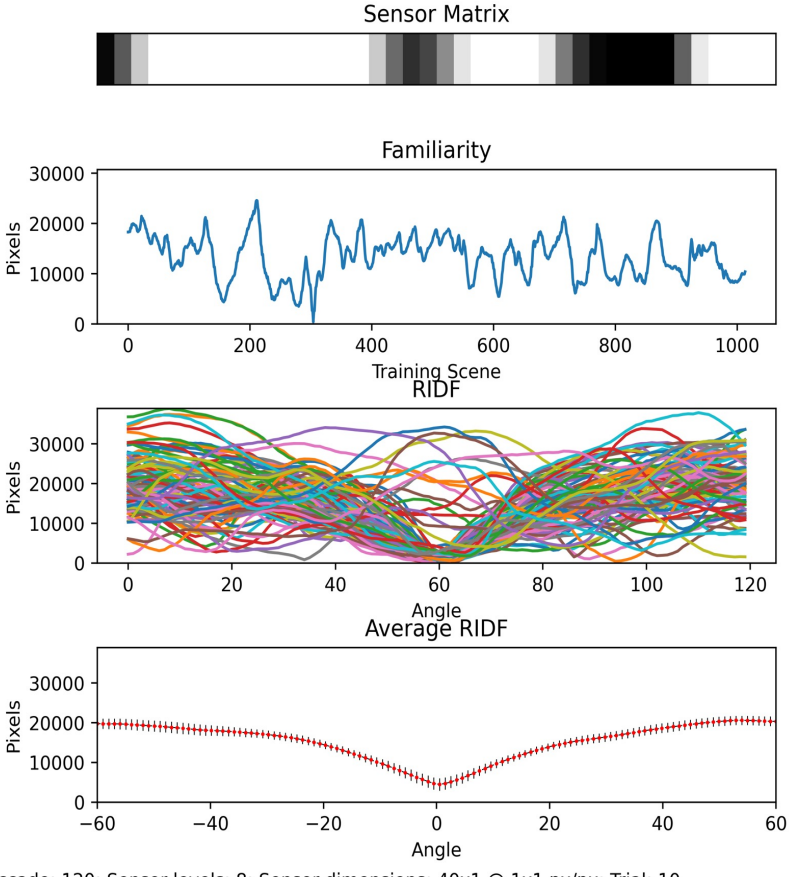
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1498.81; RMSD/dist: 3.747; TD: 9421; p90: 42; p50: 24; complete: 0


Index: BLUR: 9.0; LEVELS: 8; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

70%

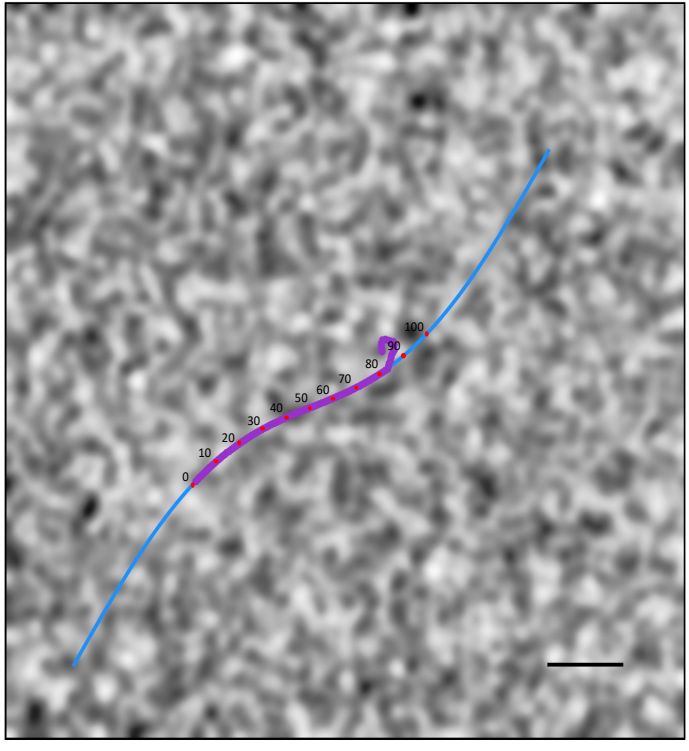


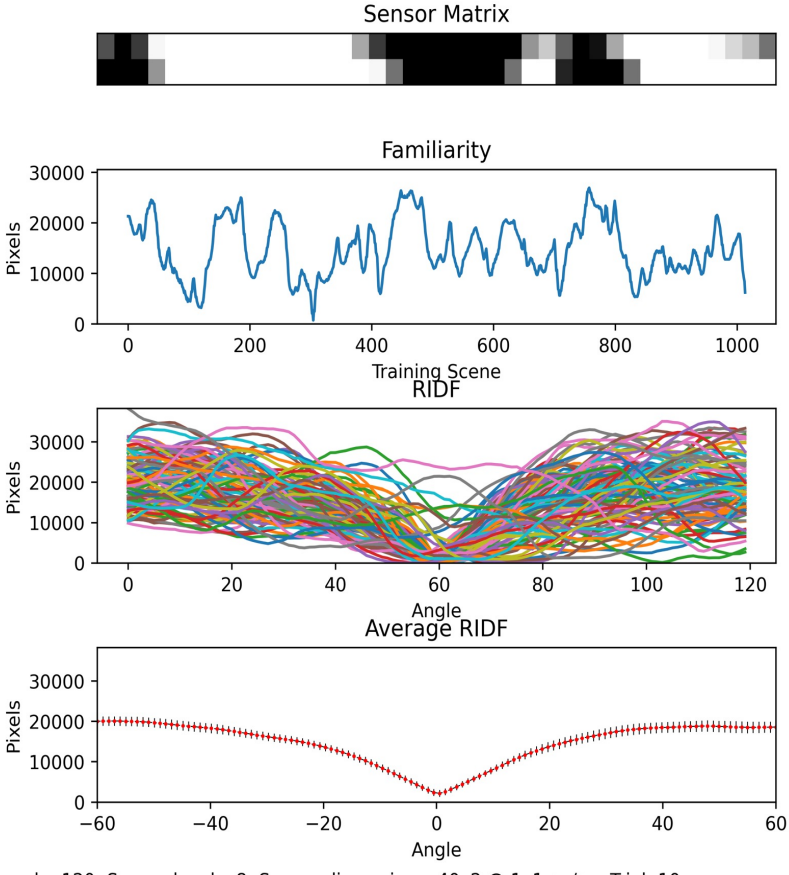


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 312.65; RMSD/dist: 0.782; TD: 9900; p90: 36; p50: 20; complete: 0

80%

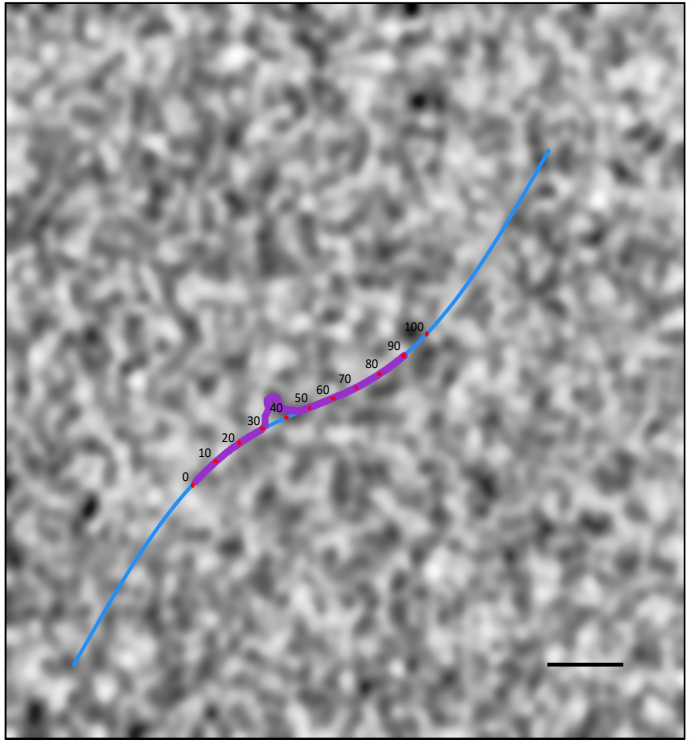


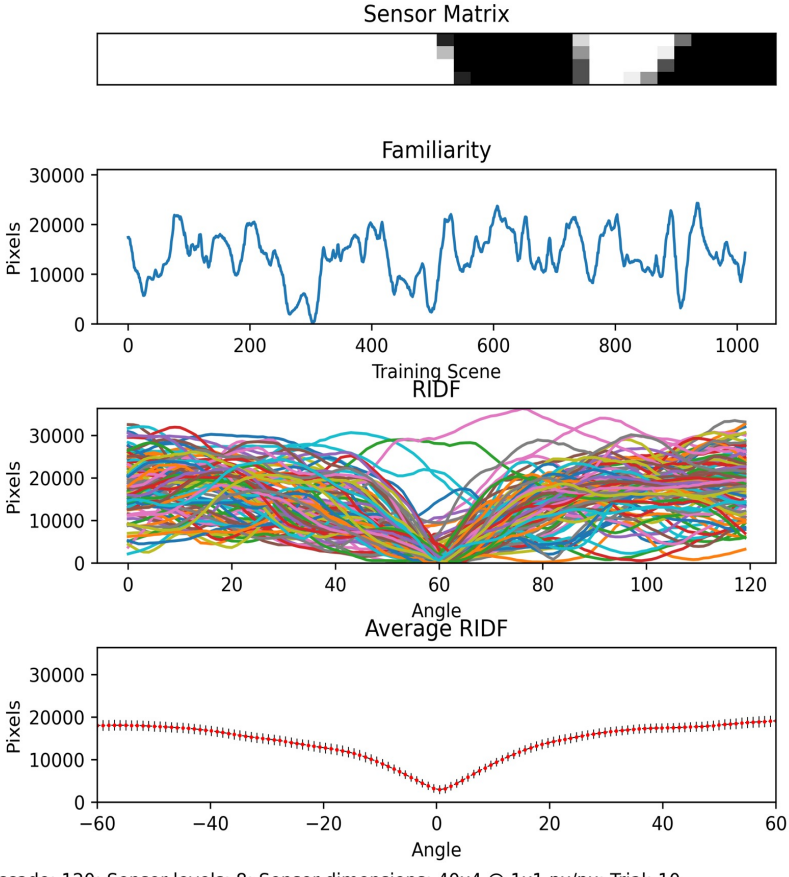


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 389.89; RMSD/dist: 0.975; TD: 11733; p90: 36; p50: 18; complete: 0

70%

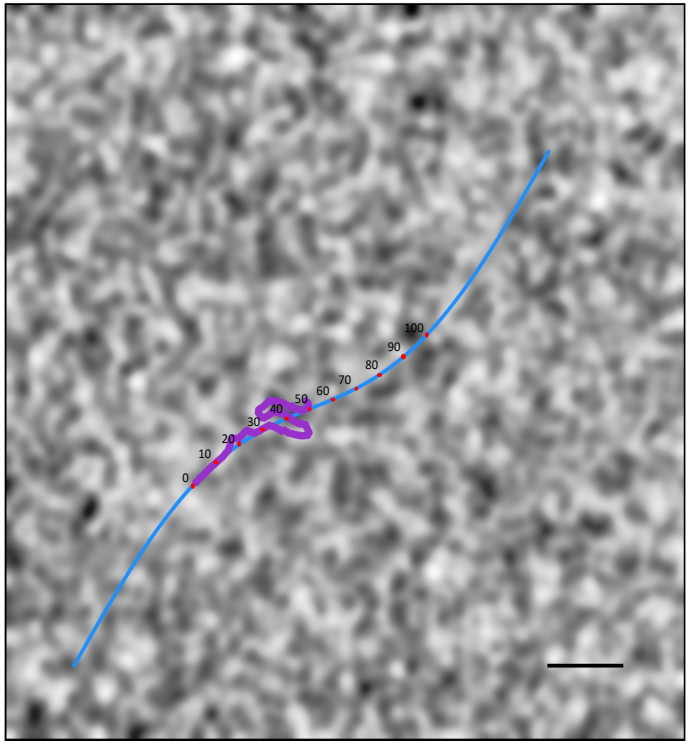


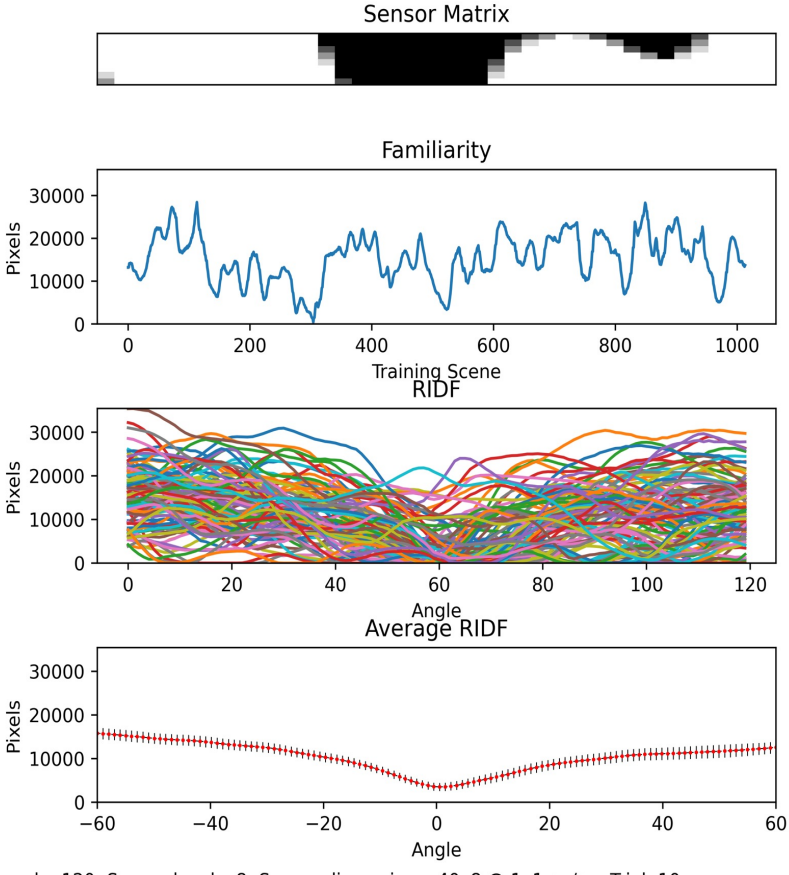


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 458.34; RMSD/dist: 1.146; TD: 10628; p90: 38; p50: 18; complete: 0

10%

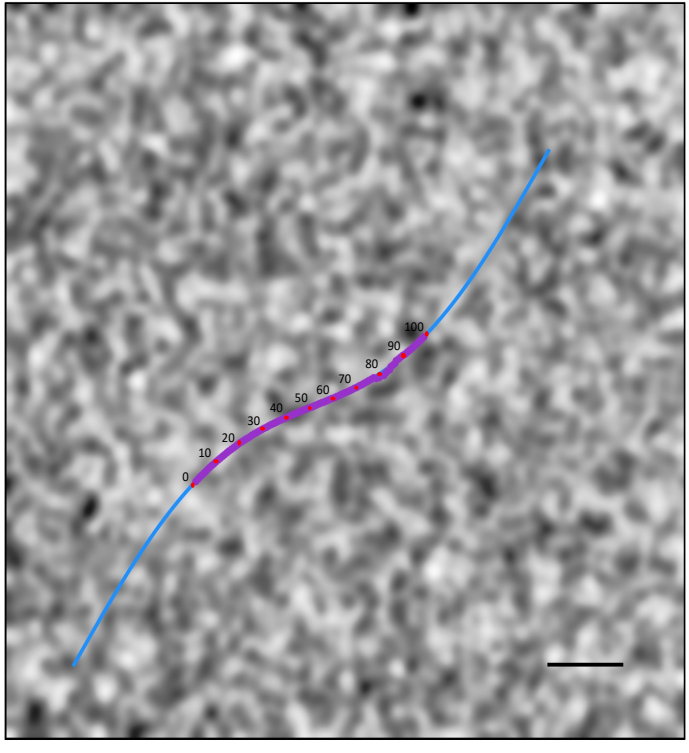


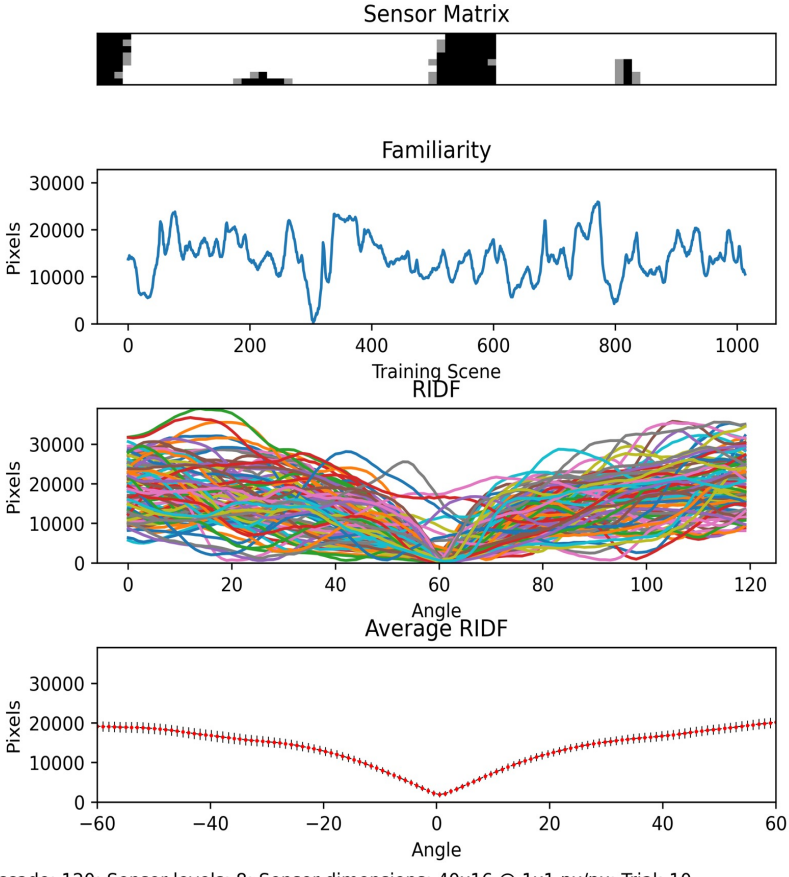


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1172.85; RMSD/dist: 2.932; TD: 9999; p90: 60; p50: 26; complete: 0

90%

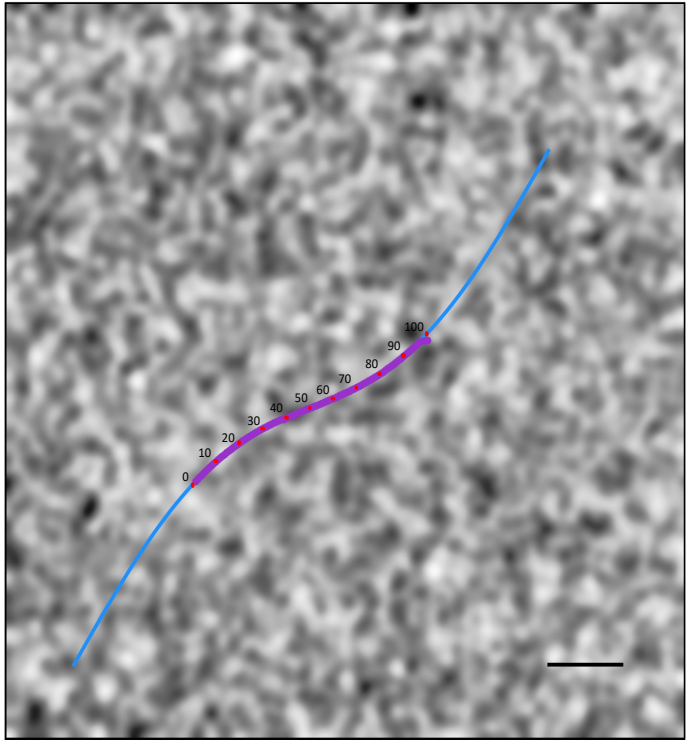


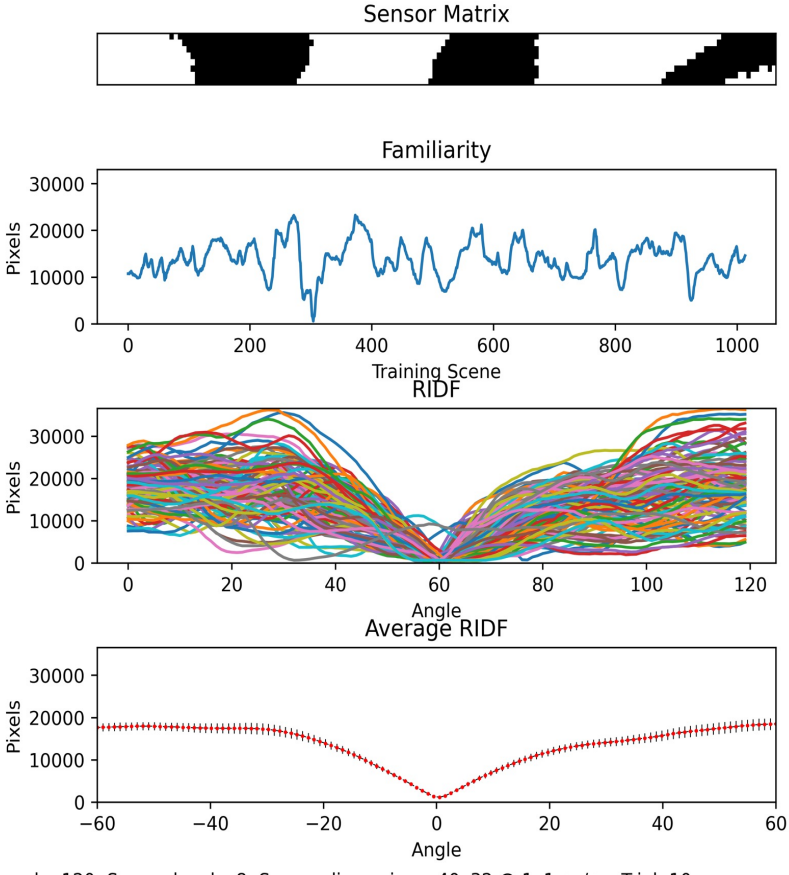


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 58.90; RMSD/dist: 0.147; TD: 12185; p90: 40; p50: 20; complete: 0

90%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 68.88; RMSD/dist: 0.172; TD: 13501; p90: 38; p50: 20; complete: 0