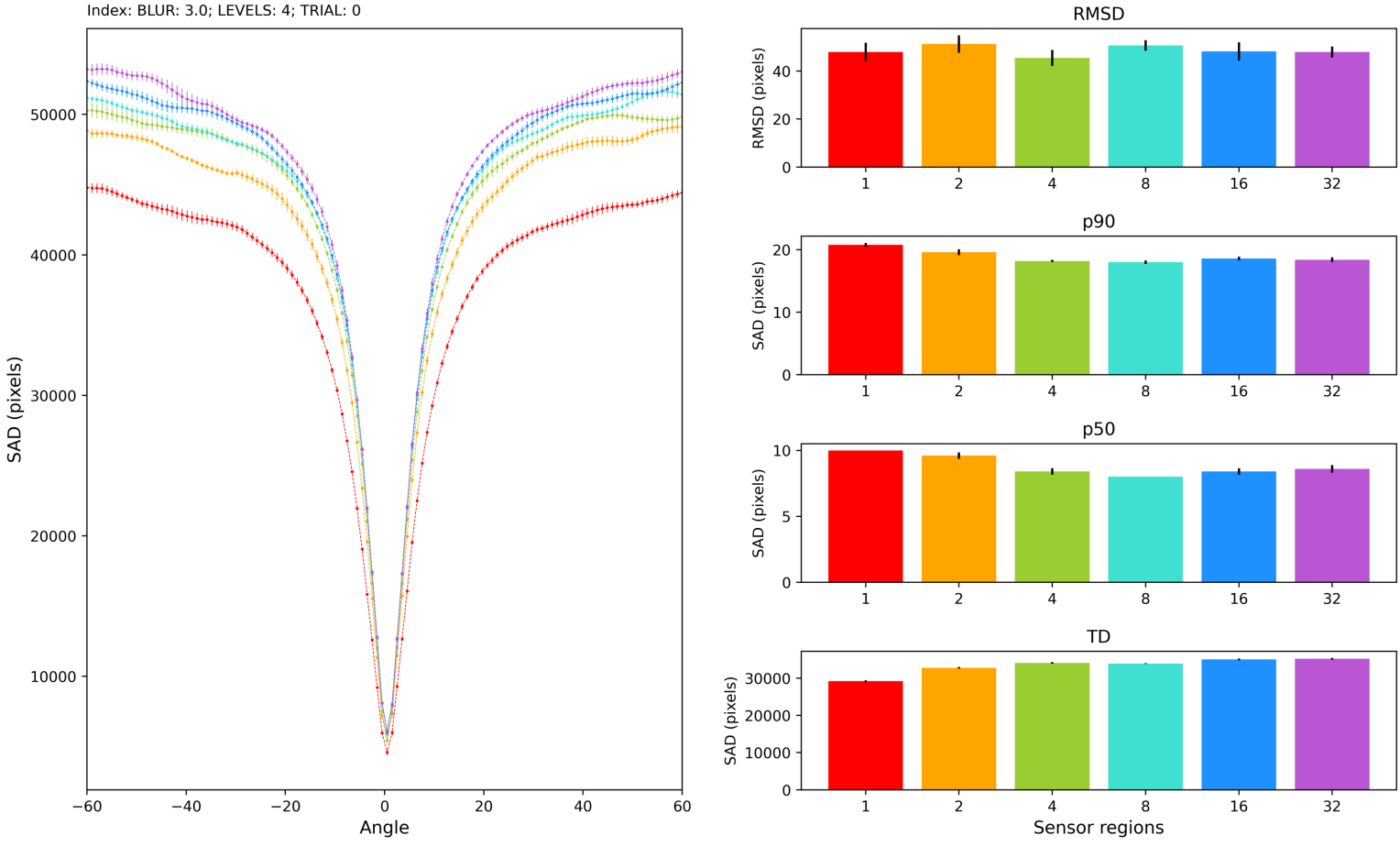
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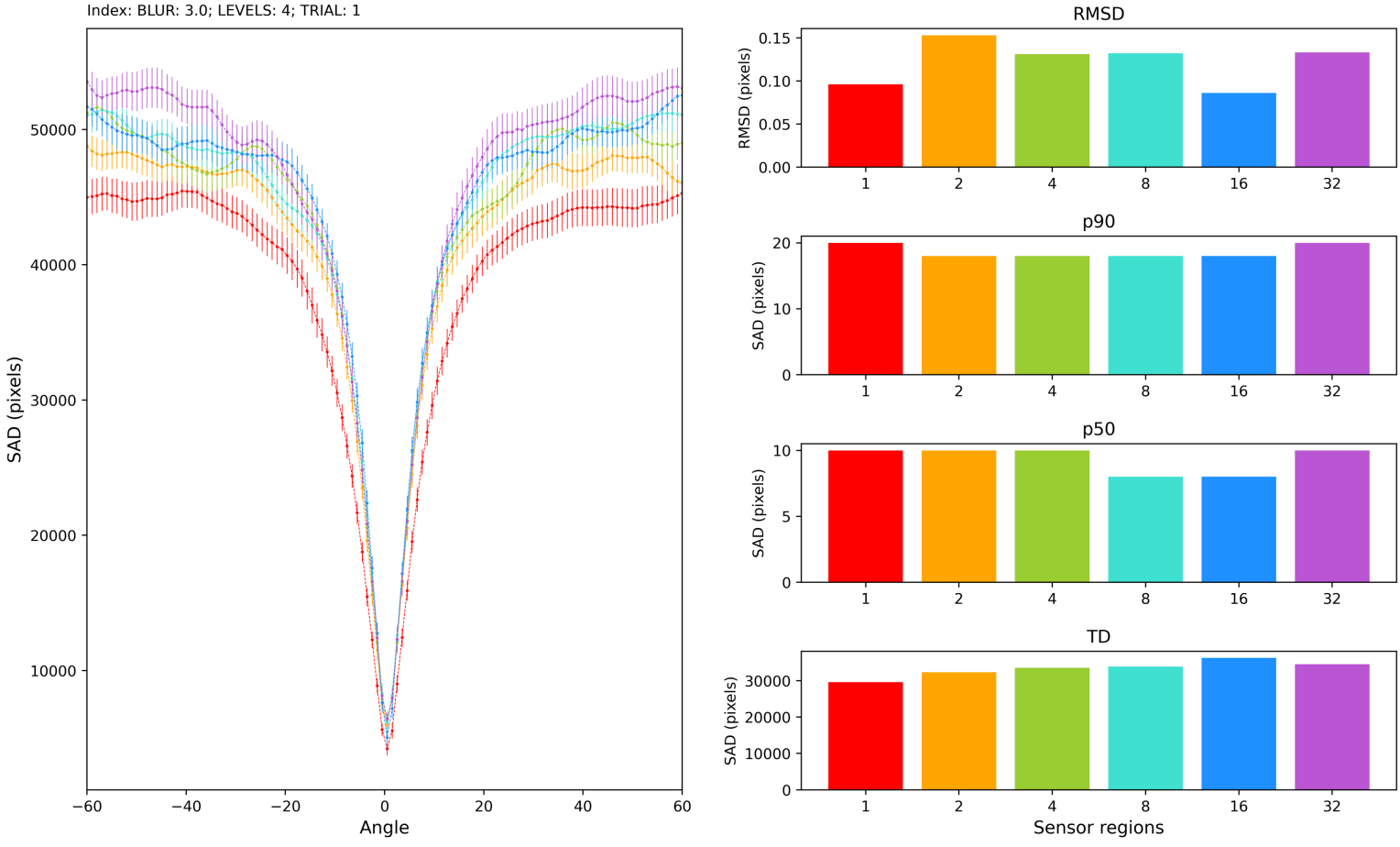
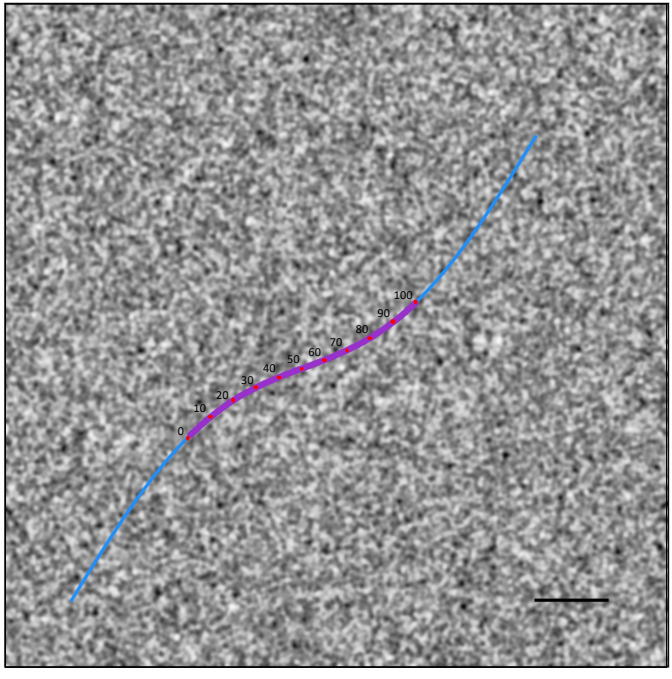
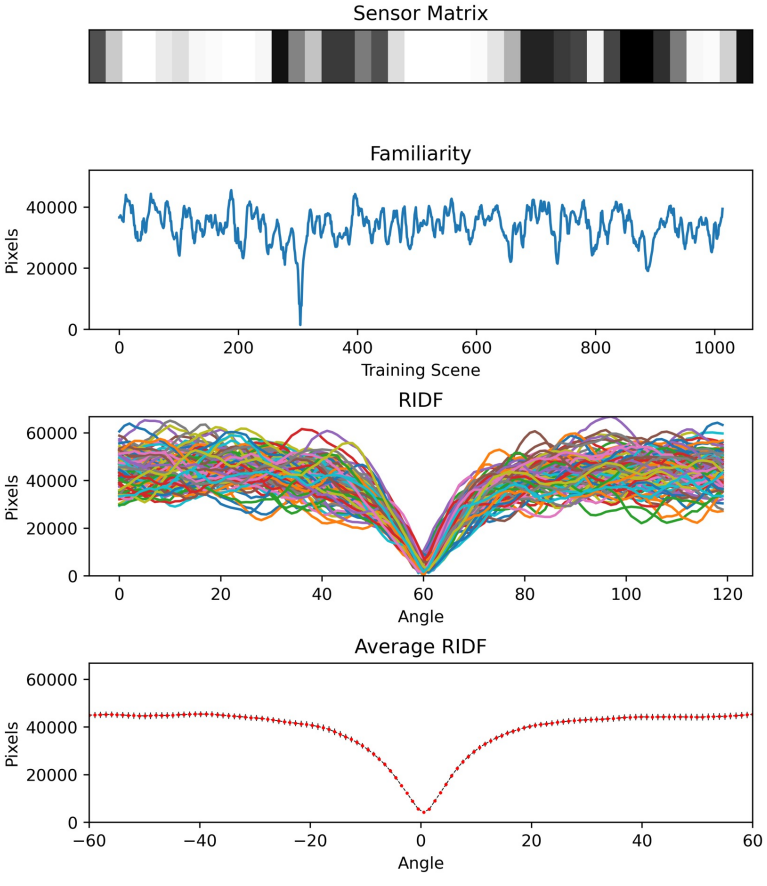
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 3.0; LEVELS: 4; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

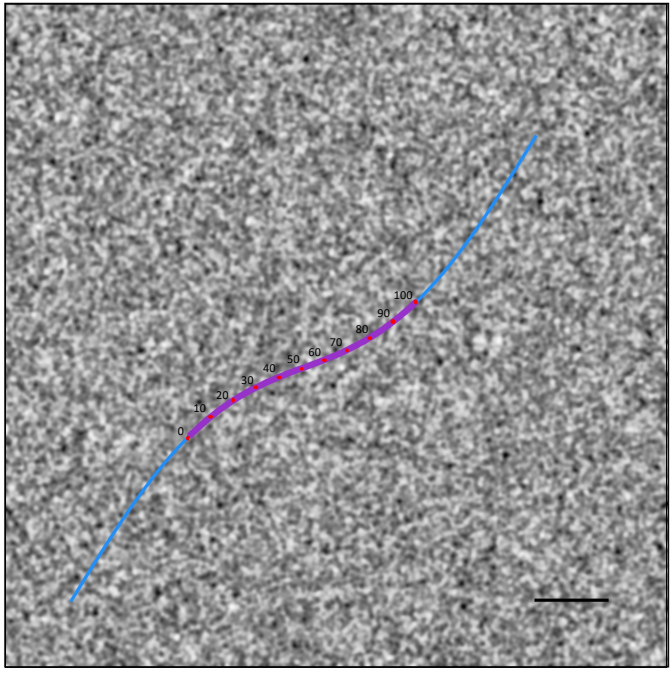


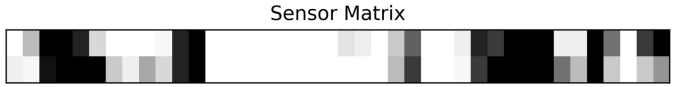


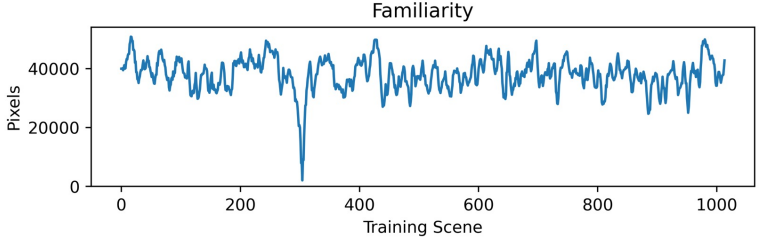
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

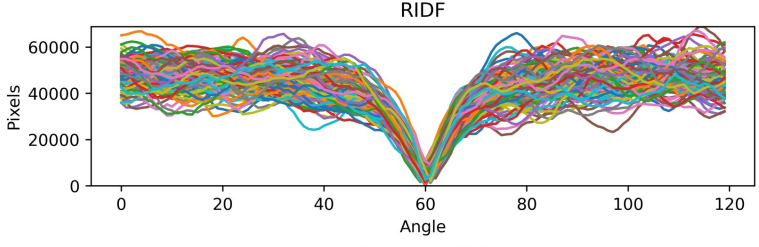
Navigation stats: RMSD error: 38.57; RMSD/dist: 0.096; TD: 29606; p90: 20; p50: 10; complete: 0

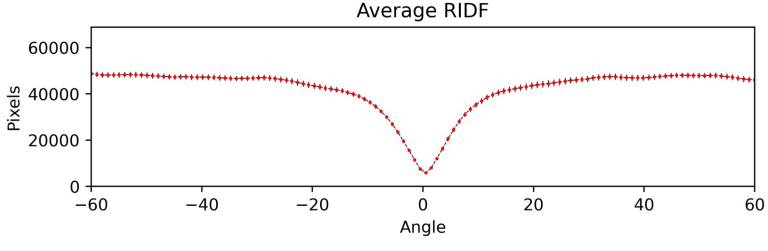
100%







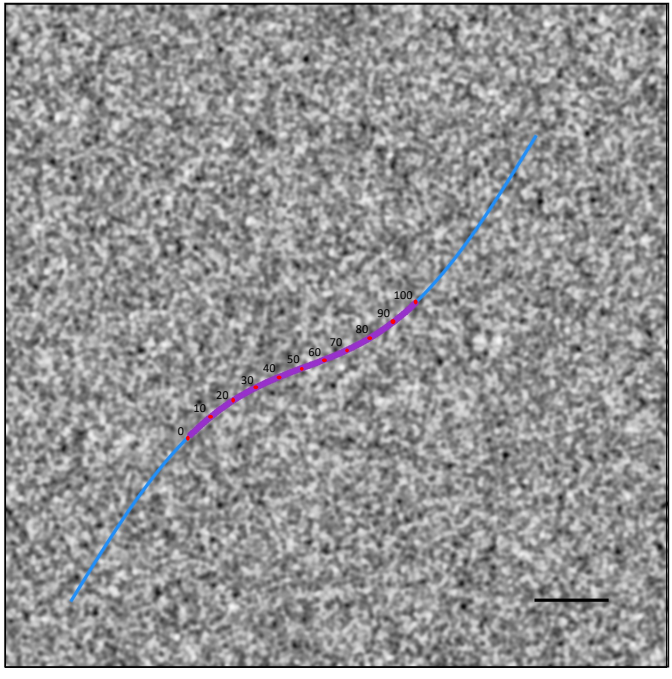


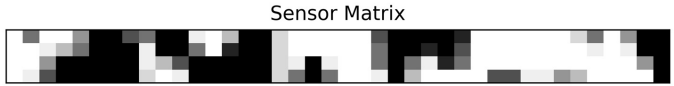


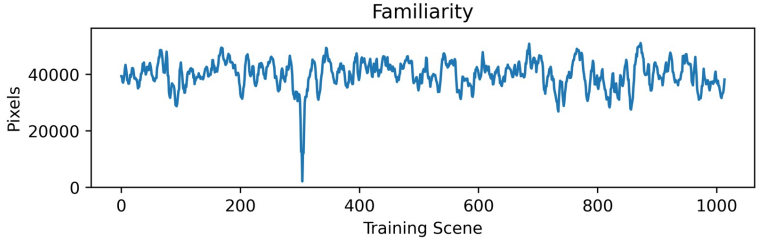
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

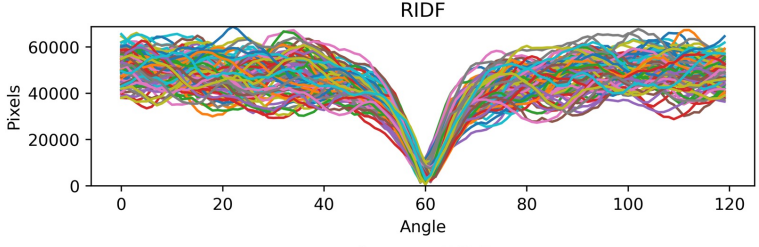
Navigation stats: RMSD error: 61.23; RMSD/dist: 0.153; TD: 32323; p90: 18; p50: 10; complete: 0

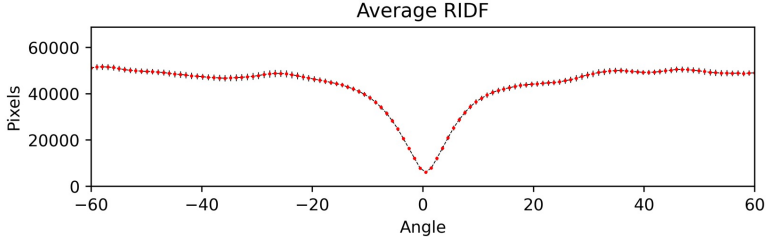
100%







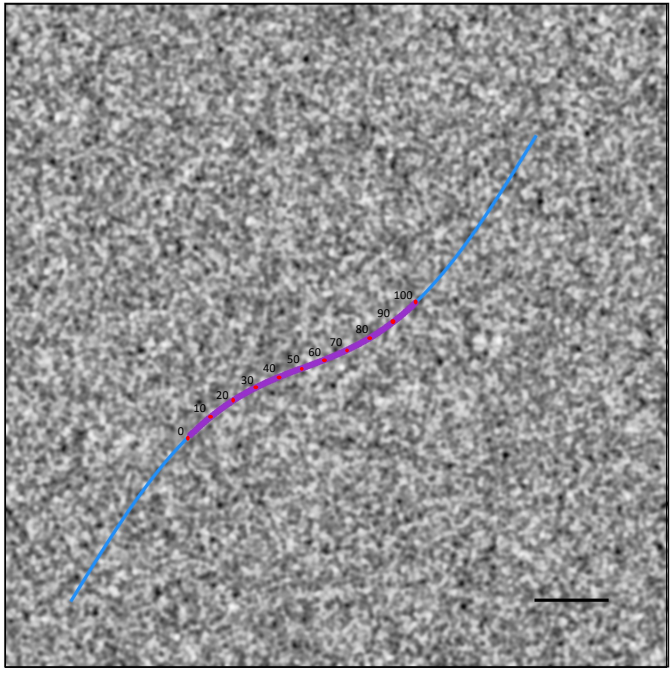


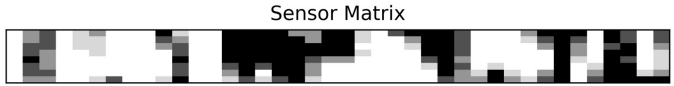


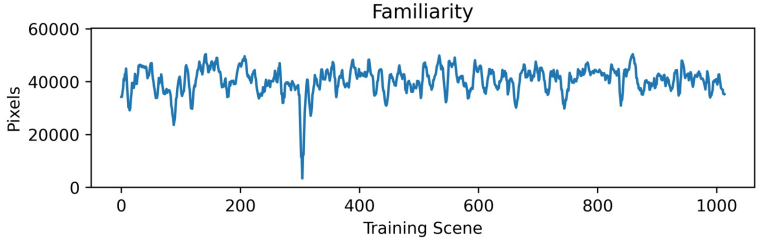
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

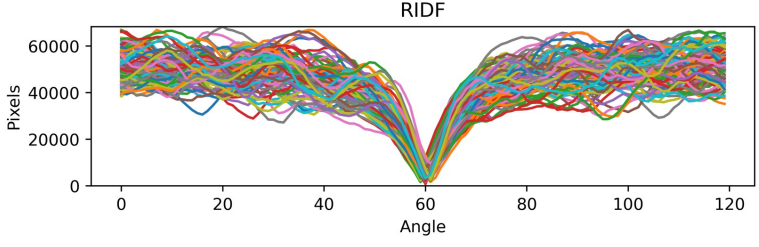
Navigation stats: RMSD error: 52.55; RMSD/dist: 0.131; TD: 33525; p90: 18; p50: 10; complete: 0

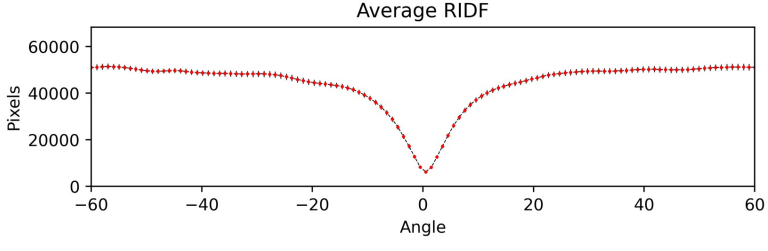
100%







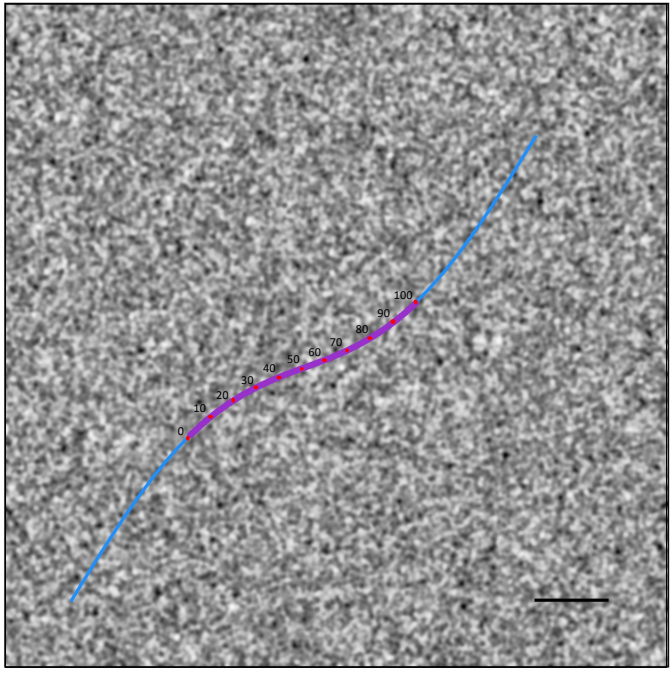


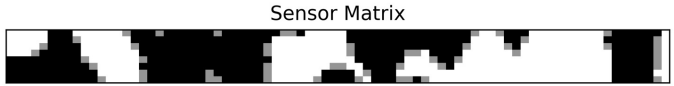


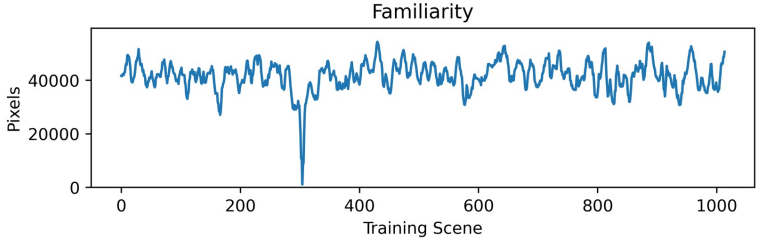
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

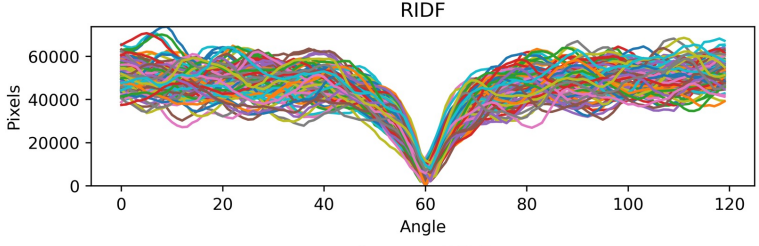
Navigation stats: RMSD error: 52.68; RMSD/dist: 0.132; TD: 33888; p90: 18; p50: 8; complete: 0

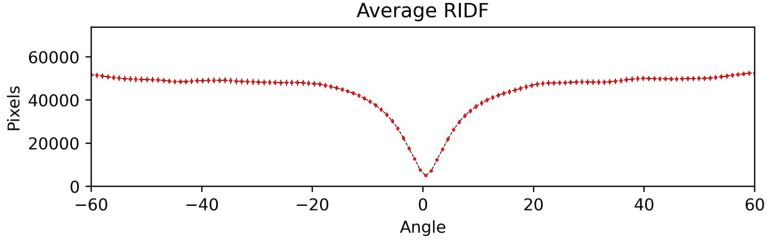
100%







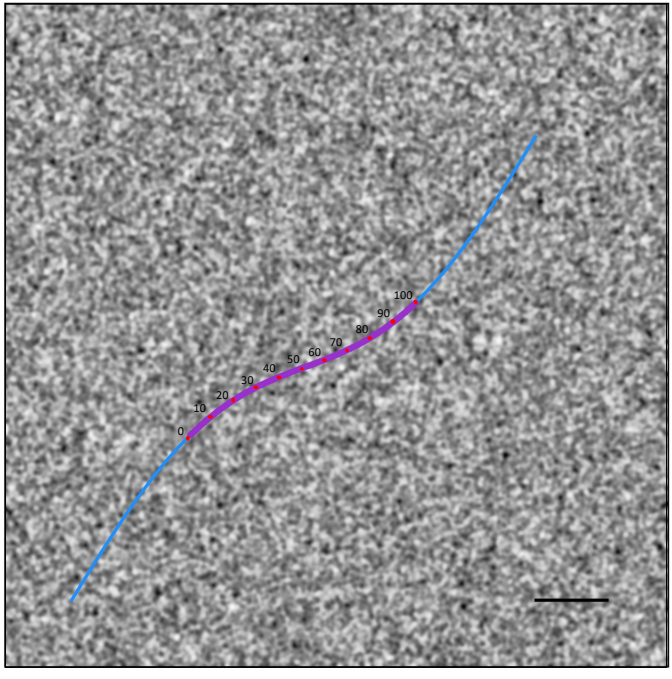


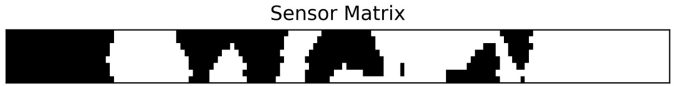


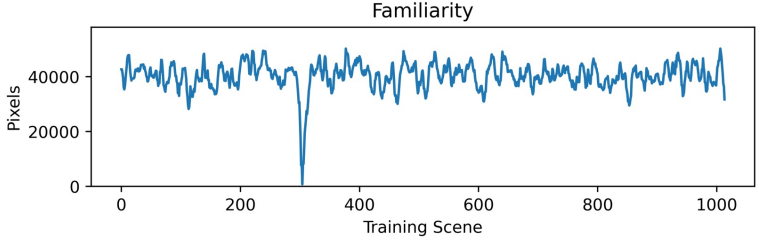
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

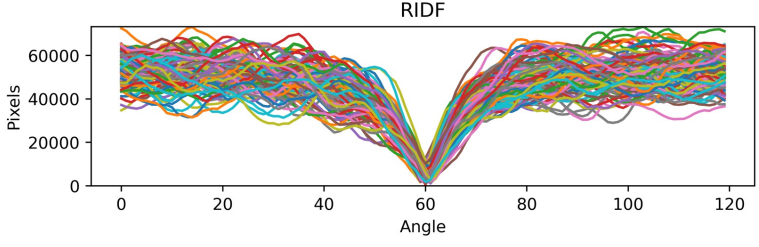
Navigation stats: RMSD error: 34.50; RMSD/dist: 0.086; TD: 36251; p90: 18; p50: 8; complete: 0

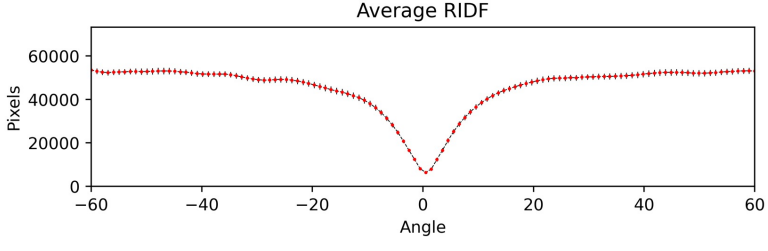
100%





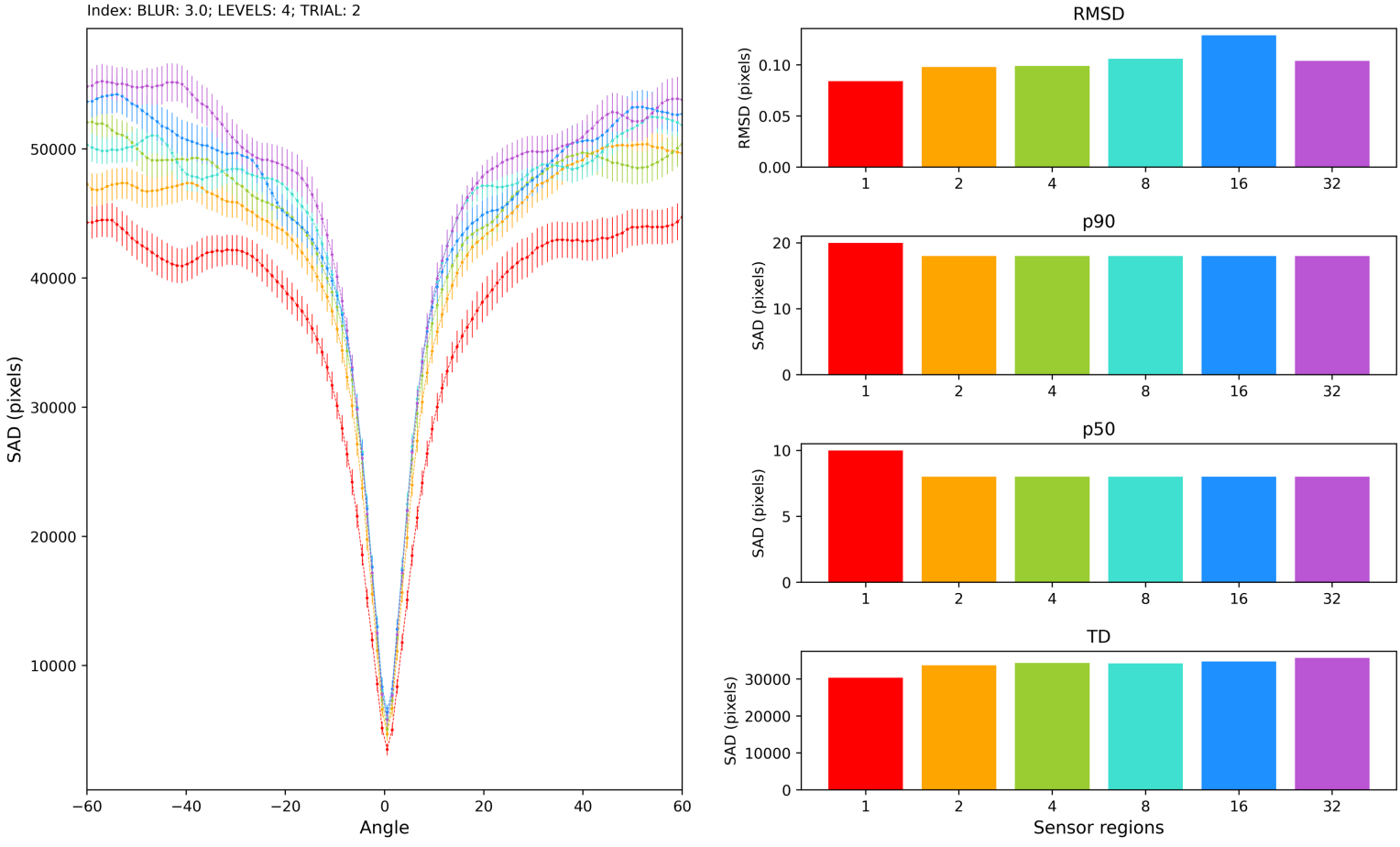




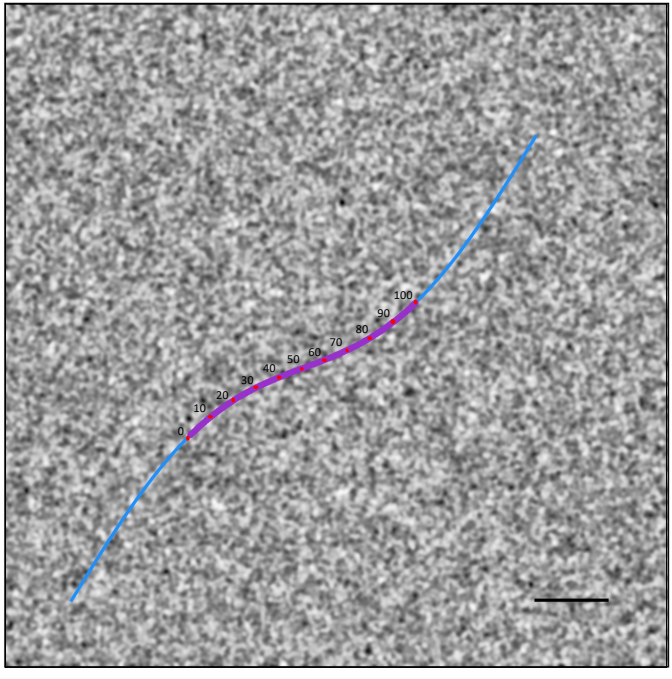


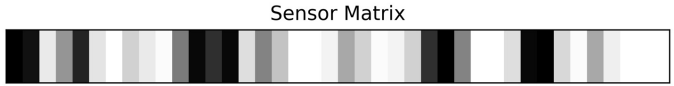
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

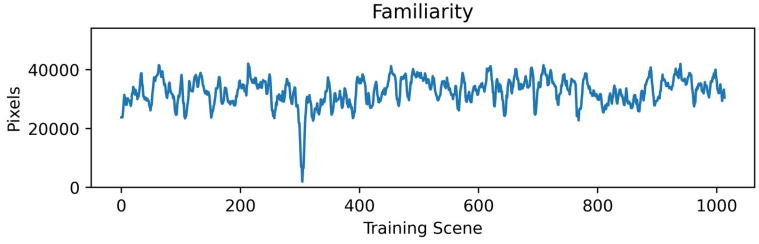
Navigation stats: RMSD error: 53.34; RMSD/dist: 0.133; TD: 34542; p90: 20; p50: 10; complete: 0

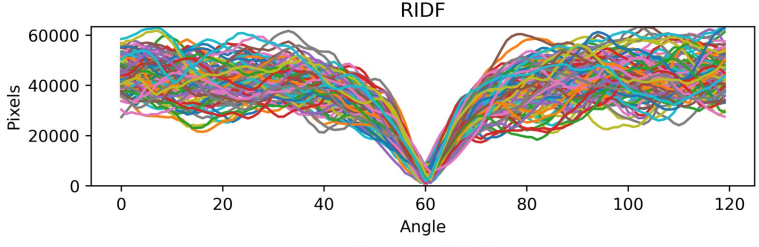

Index: BLUR: 3.0; LEVELS: 4; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

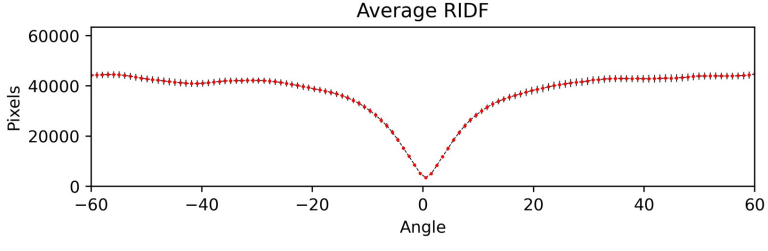
100%







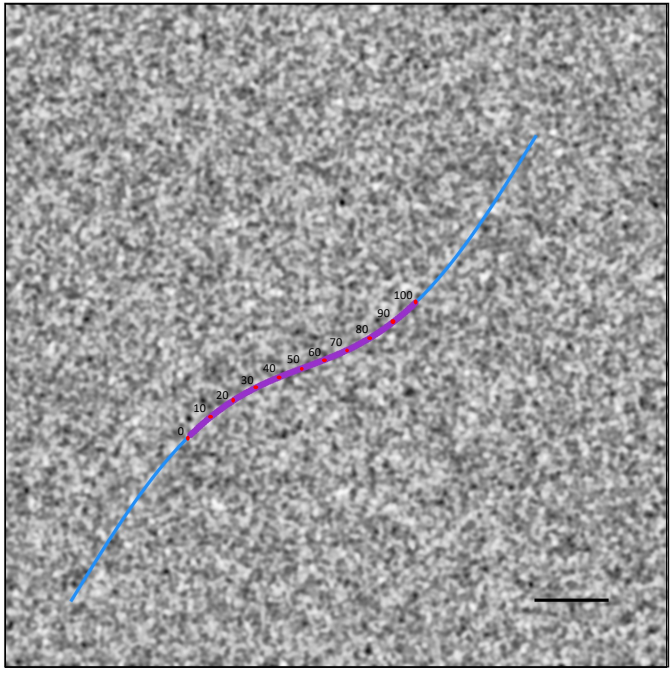


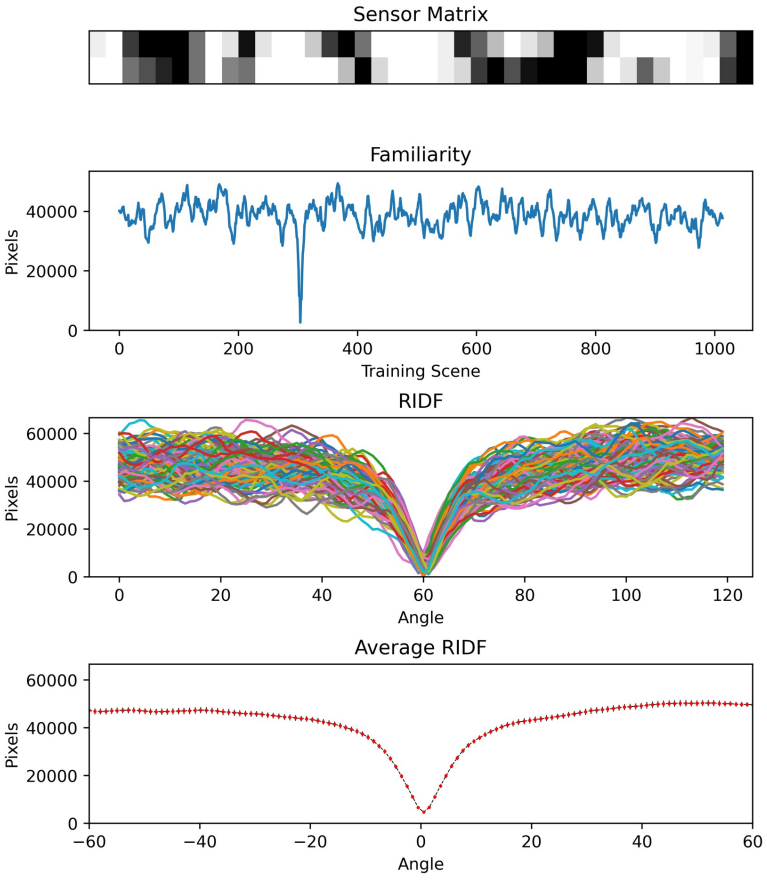


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 33.58; RMSD/dist: 0.084; TD: 30336; p90: 20; p50: 10; complete: 0

100%

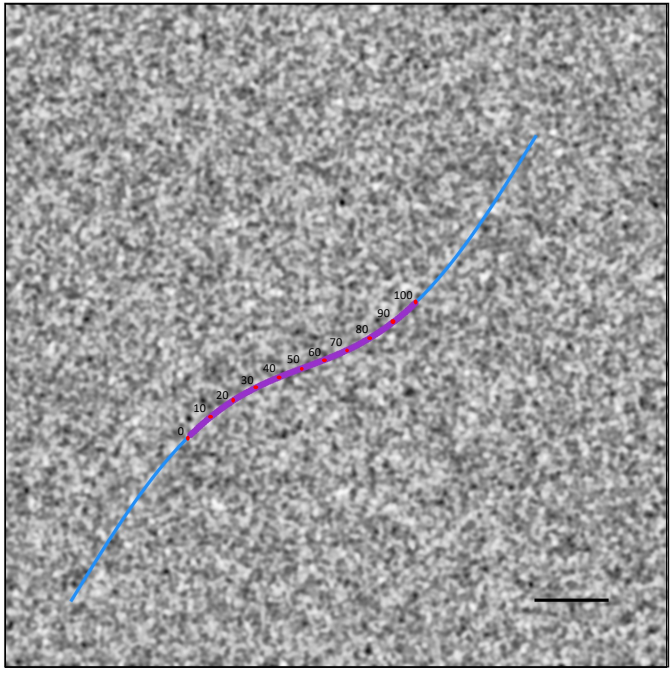


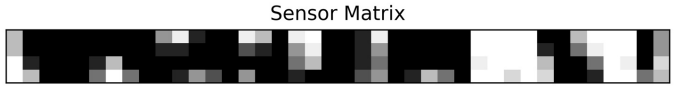


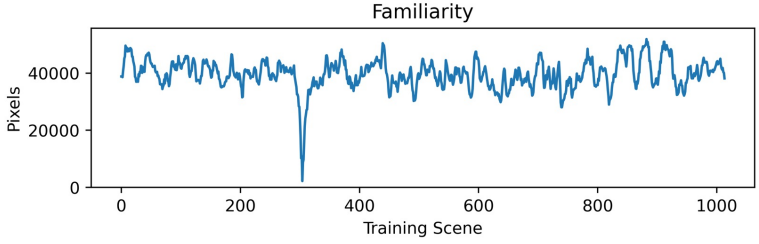
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

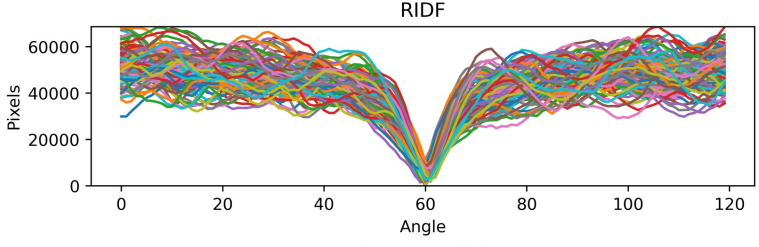
Navigation stats: RMSD error: 39.30; RMSD/dist: 0.098; TD: 33724; p90: 18; p50: 8; complete: 0

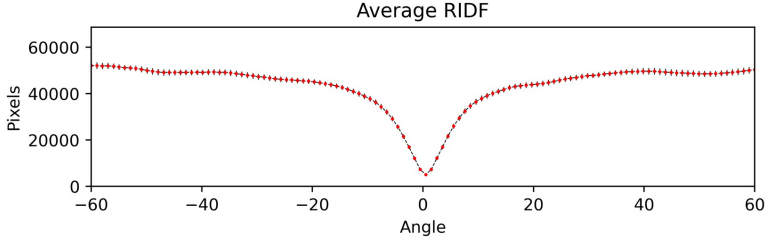
100%







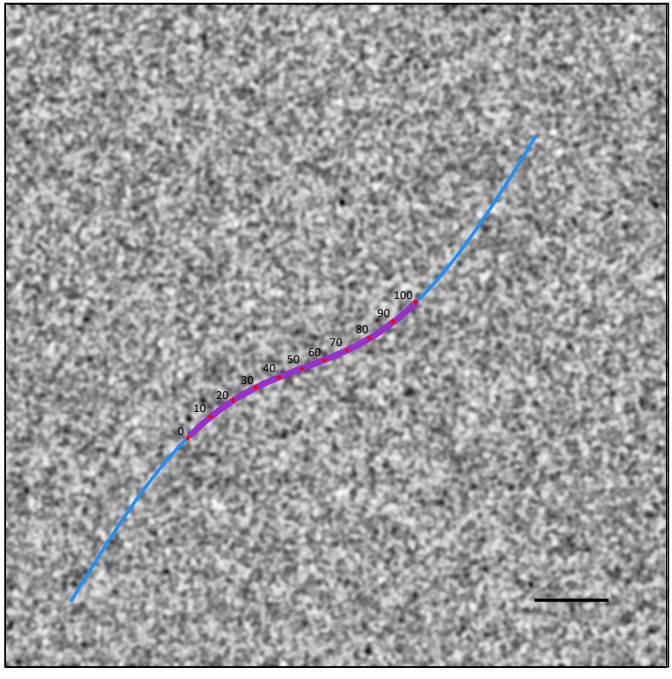


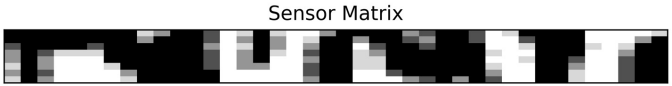


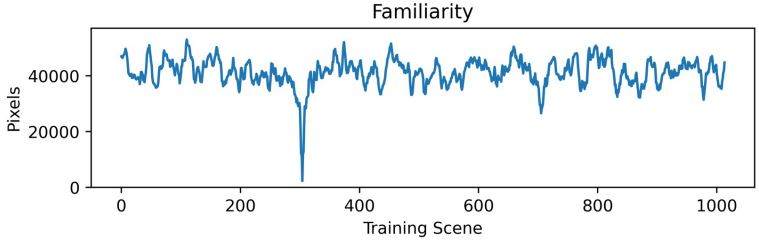
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

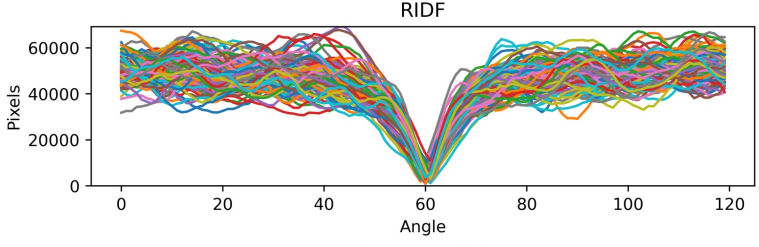
Navigation stats: RMSD error: 39.76; RMSD/dist: 0.099; TD: 34339; p90: 18; p50: 8; complete: 0

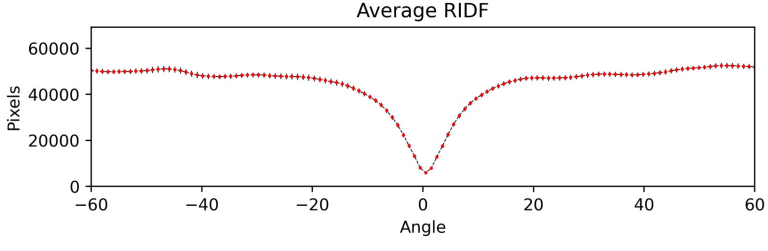
100%







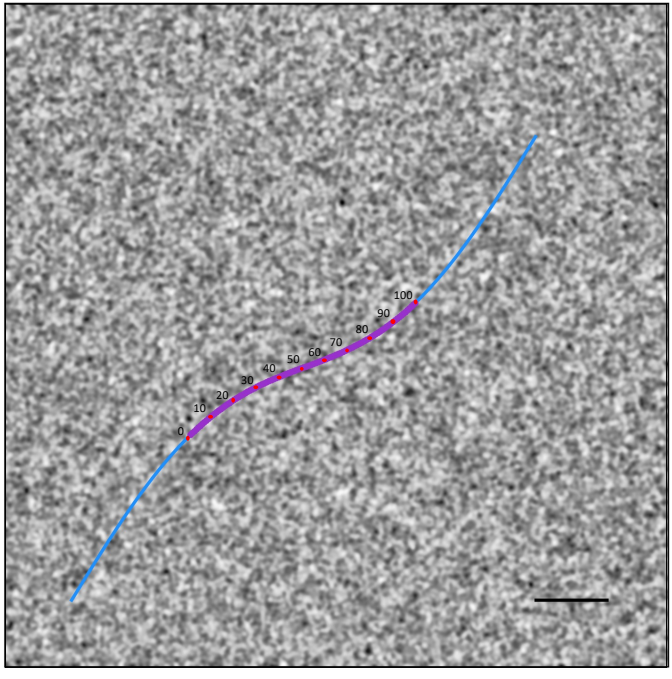


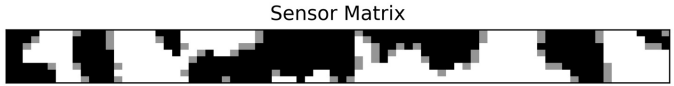


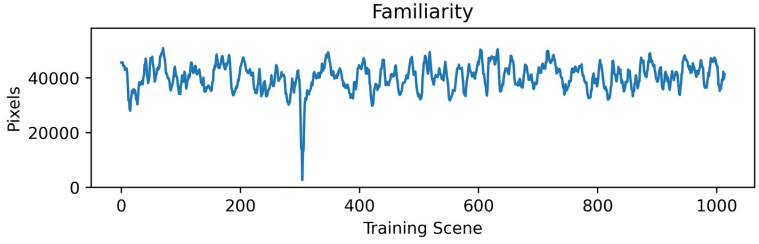
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

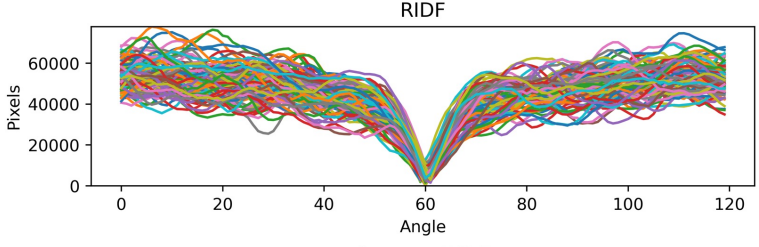
Navigation stats: RMSD error: 42.44; RMSD/dist: 0.106; TD: 34253; p90: 18; p50: 8; complete: 0

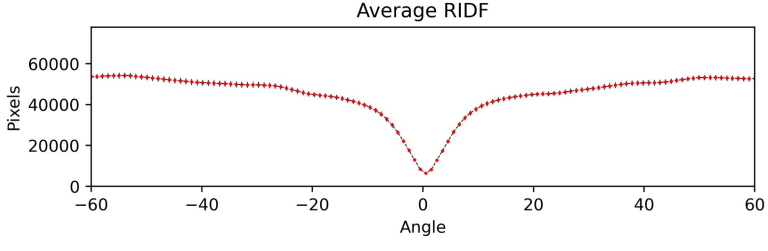
100%







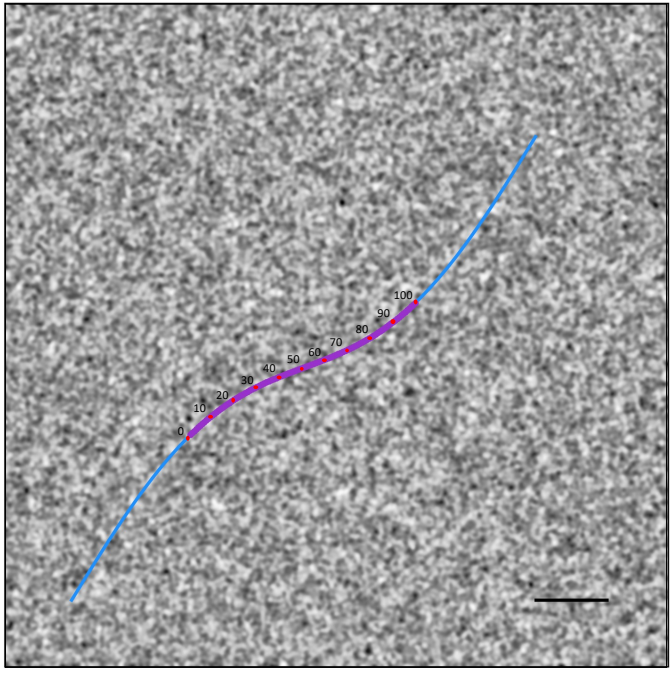


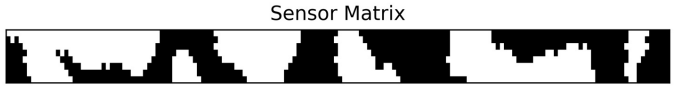


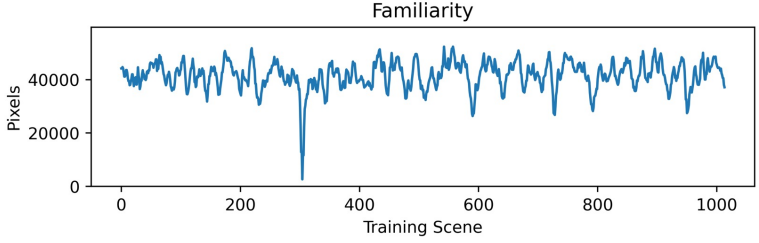
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

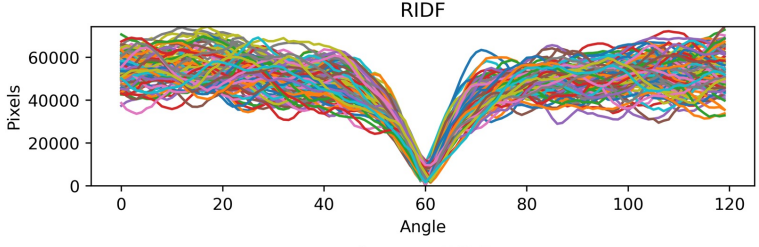
Navigation stats: RMSD error: 51.59; RMSD/dist: 0.129; TD: 34733; p90: 18; p50: 8; complete: 0

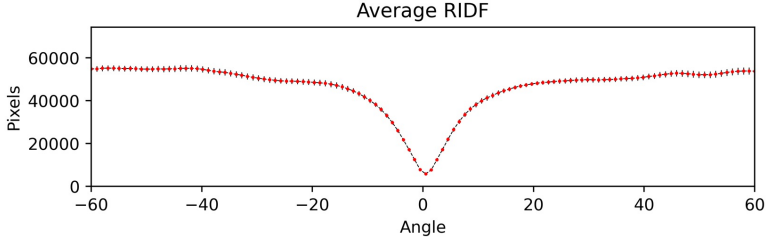
100%





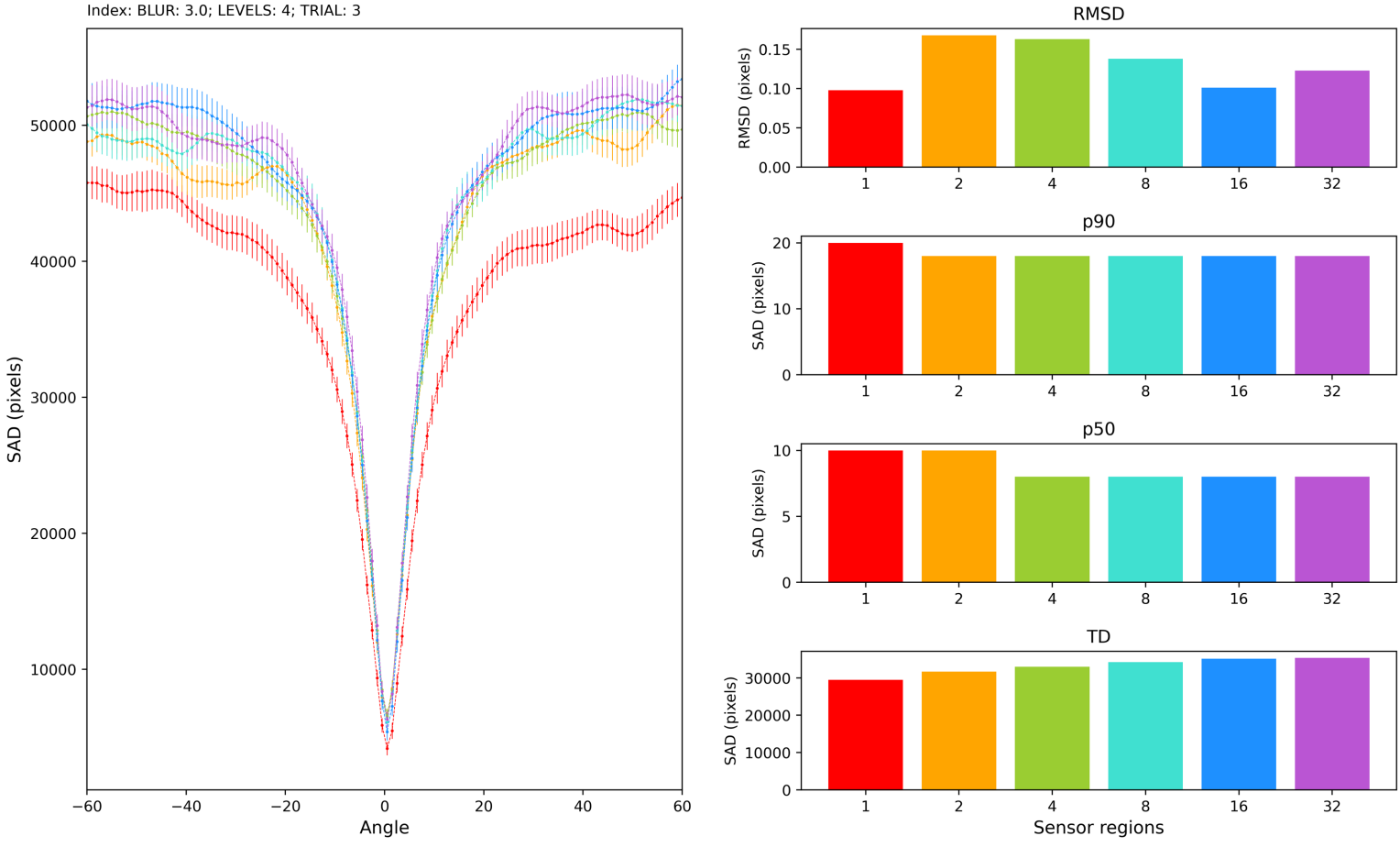




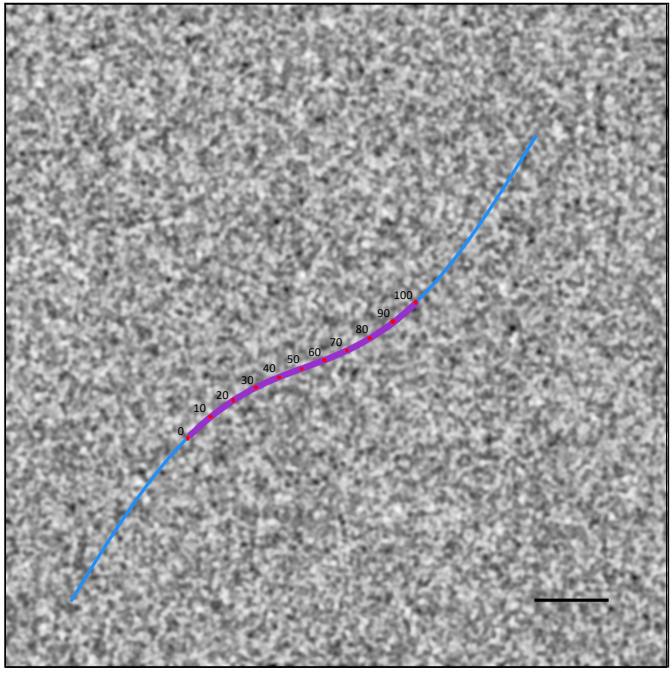


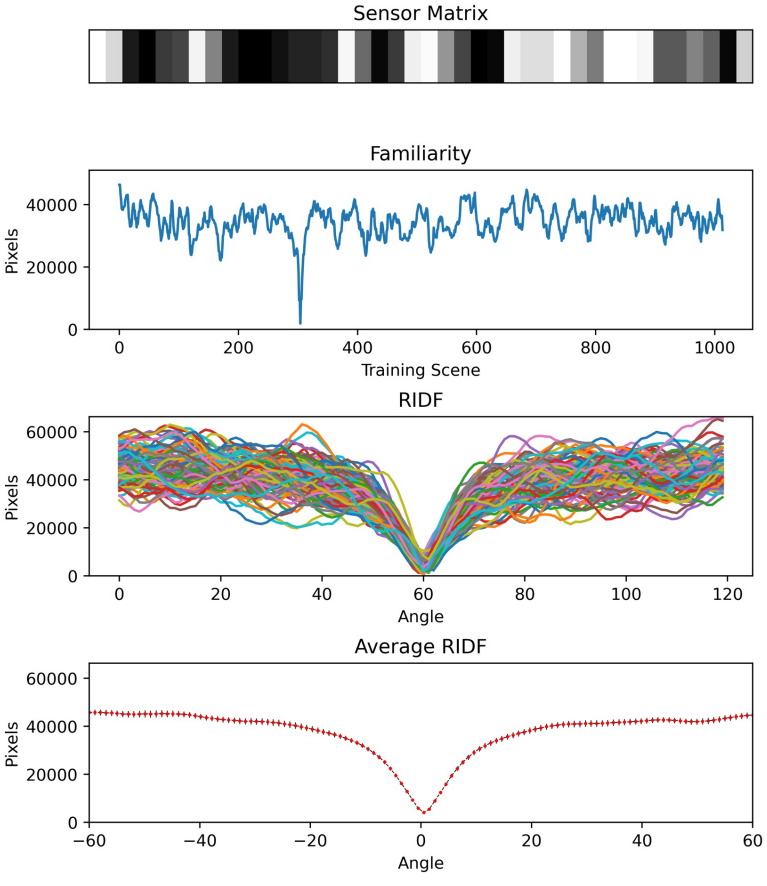
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 41.76; RMSD/dist: 0.104; TD: 35698; p90: 18; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 4; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

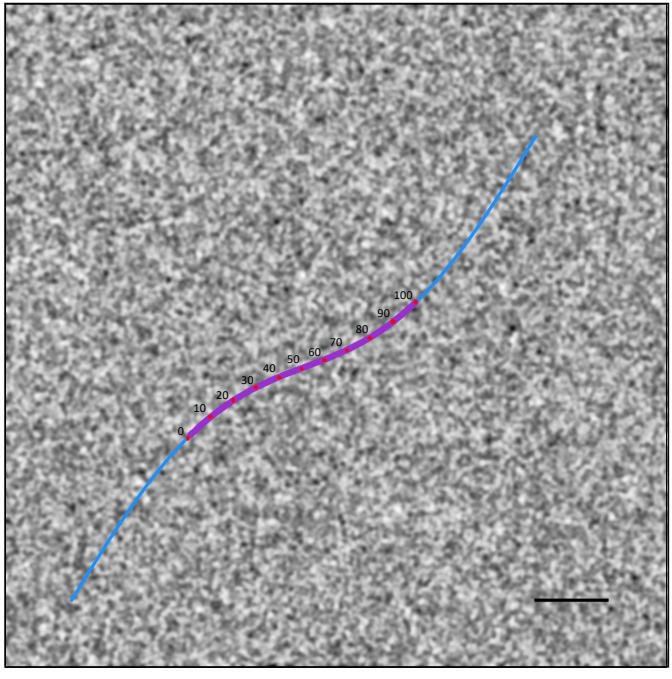


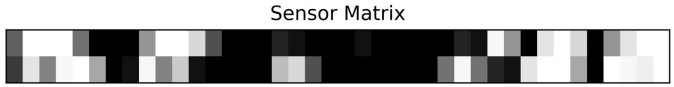


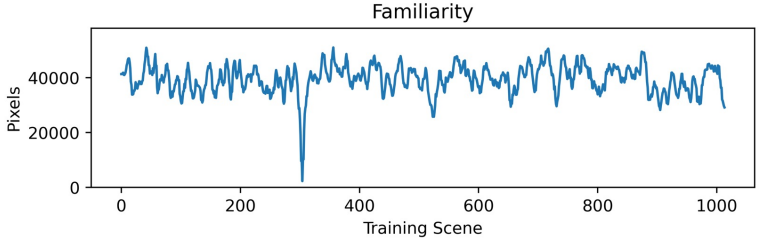
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

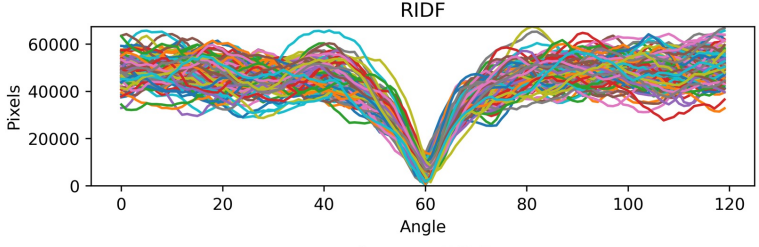
Navigation stats: RMSD error: 39.17; RMSD/dist: 0.098; TD: 29504; p90: 20; p50: 10; complete: 0

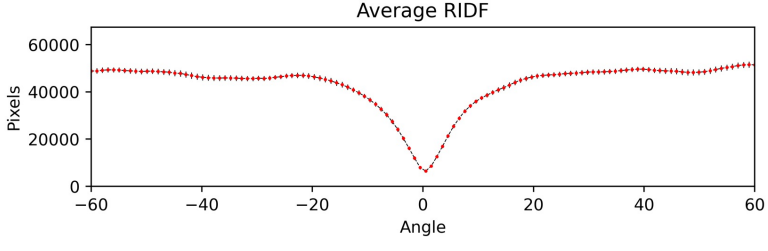
100%







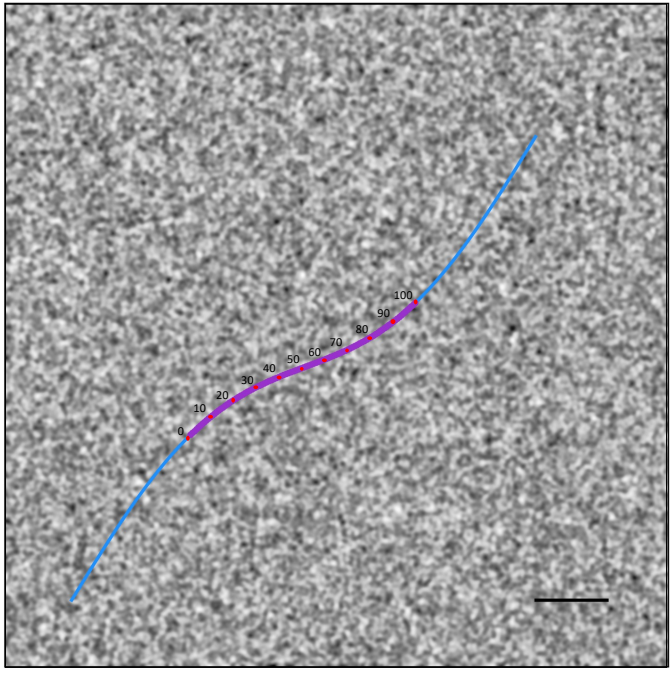


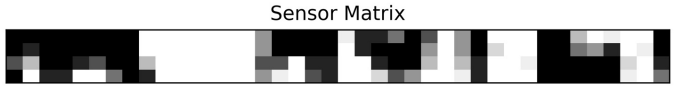


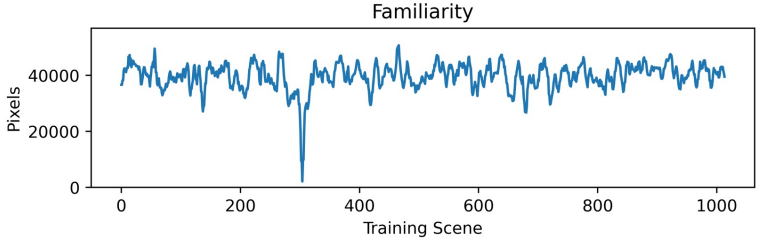
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

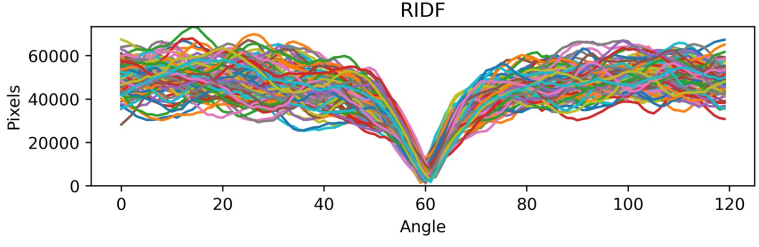
Navigation stats: RMSD error: 67.04; RMSD/dist: 0.168; TD: 31711; p90: 18; p50: 10; complete: 0

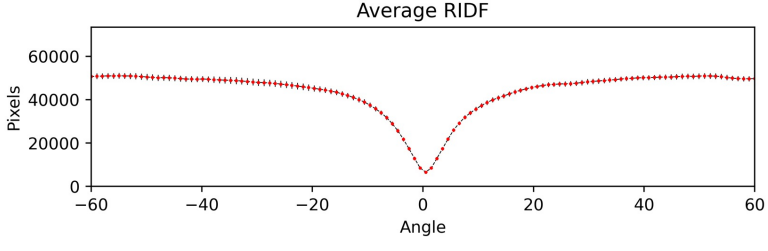
100%







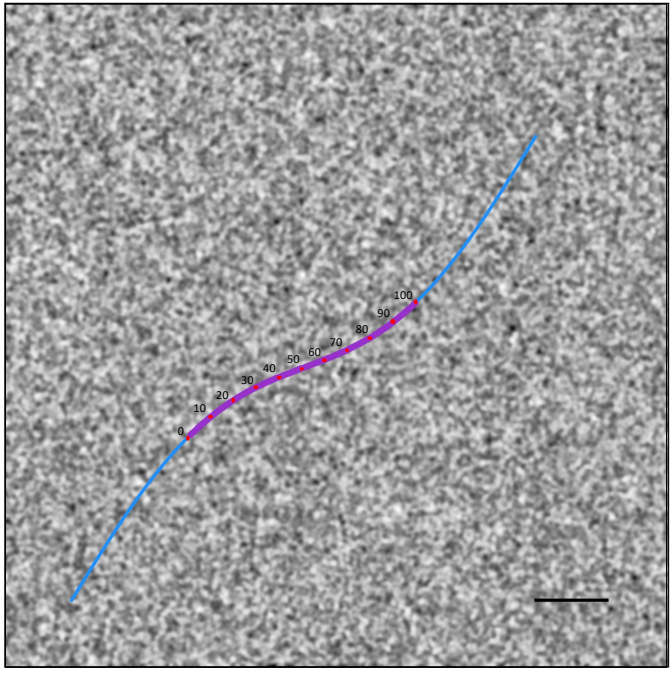


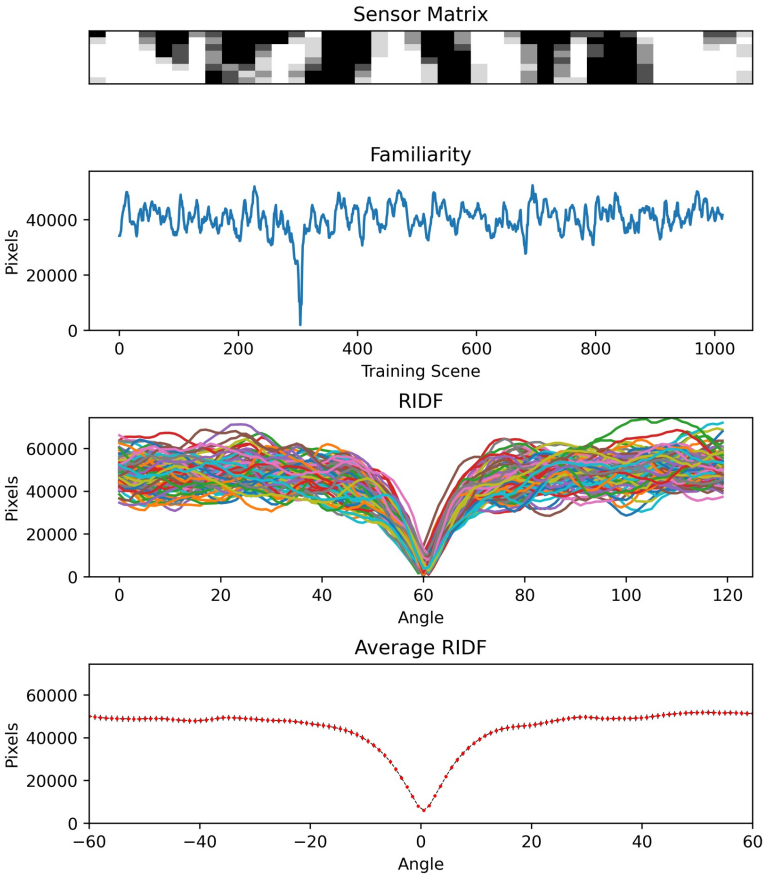


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 65.13; RMSD/dist: 0.163; TD: 33010; p90: 18; p50: 8; complete: 0

100%

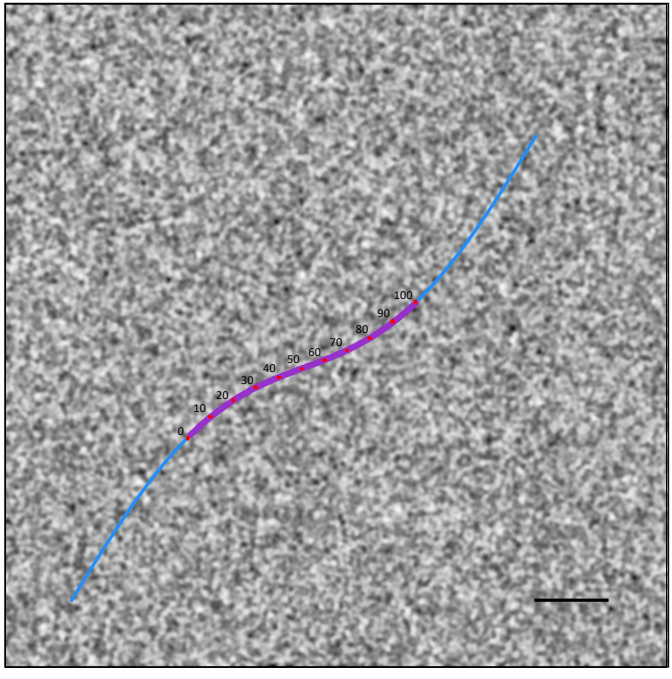


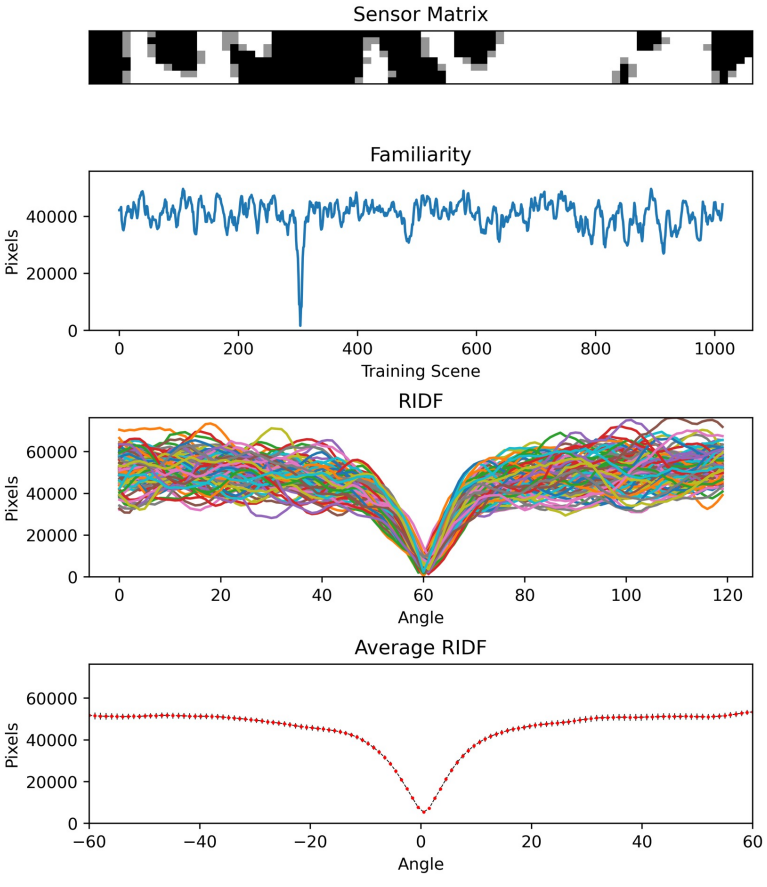


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 55.31; RMSD/dist: 0.138; TD: 34228; p90: 18; p50: 8; complete: 0

100%

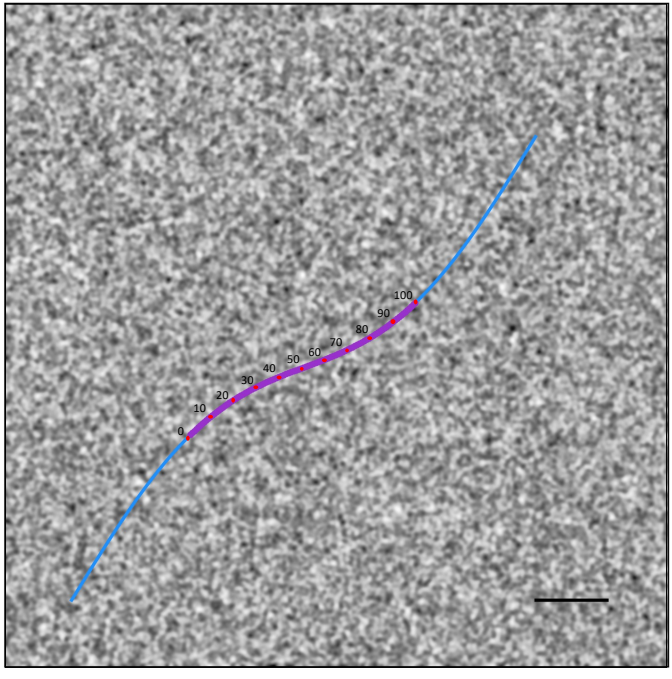


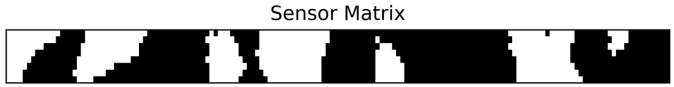


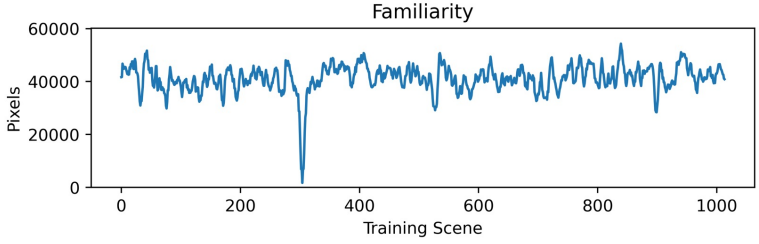
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

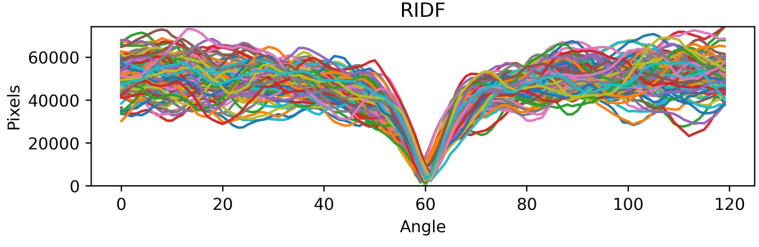
Navigation stats: RMSD error: 40.23; RMSD/dist: 0.101; TD: 35156; p90: 18; p50: 8; complete: 0

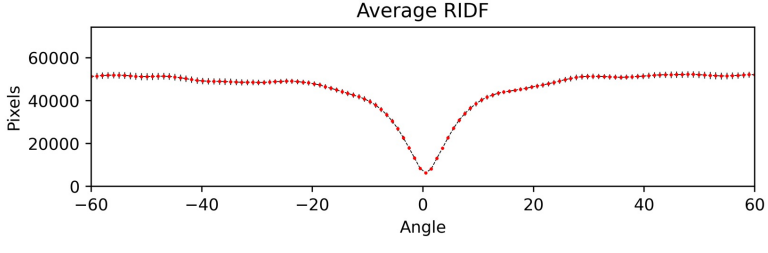
100%





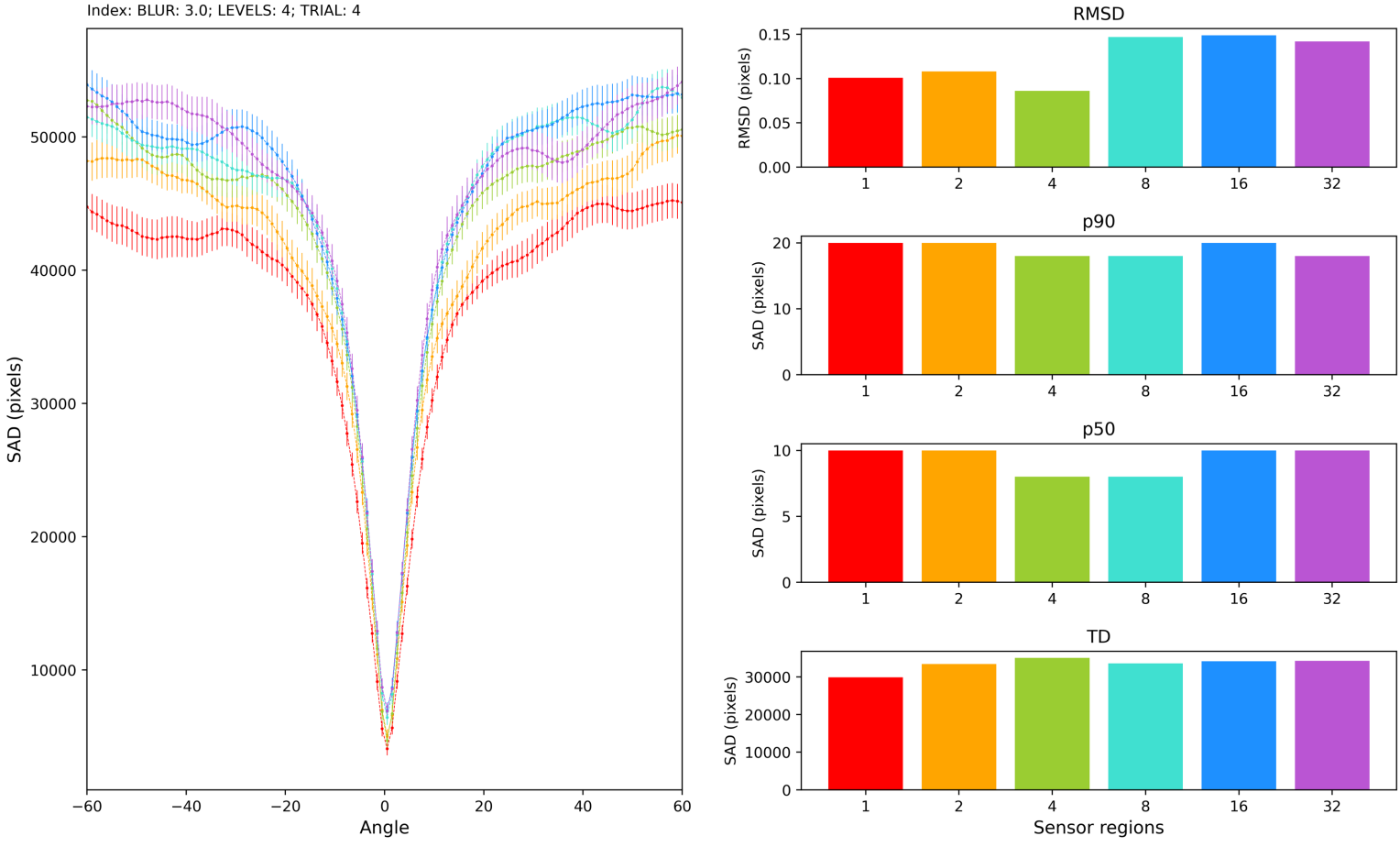




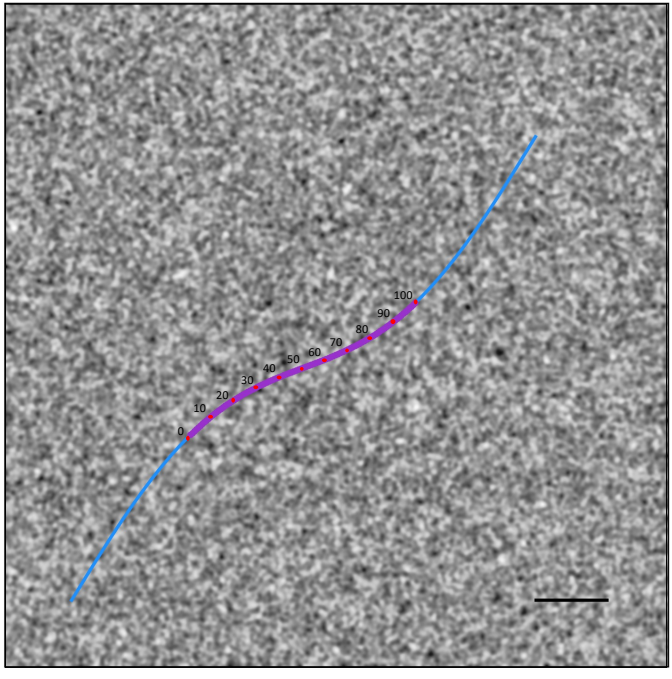


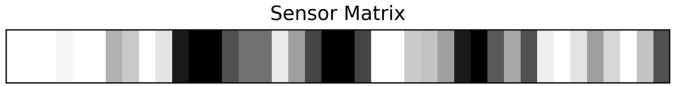
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

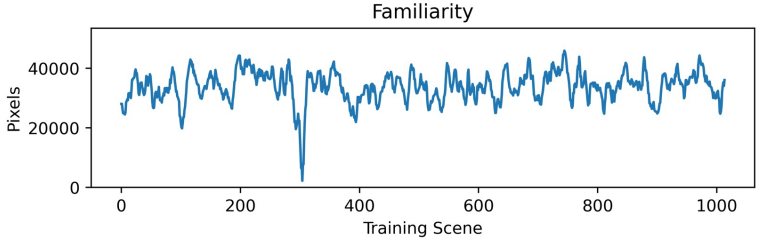
Navigation stats: RMSD error: 49.08; RMSD/dist: 0.123; TD: 35348; p90: 18; p50: 8; complete: 0

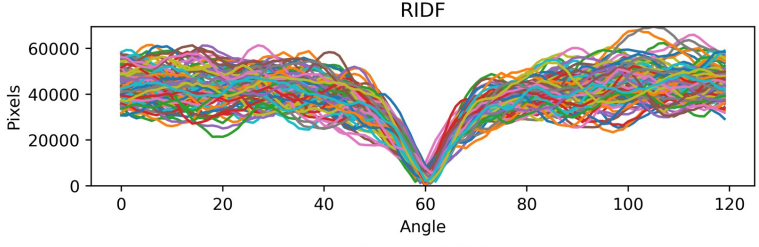

Index: BLUR: 3.0; LEVELS: 4; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

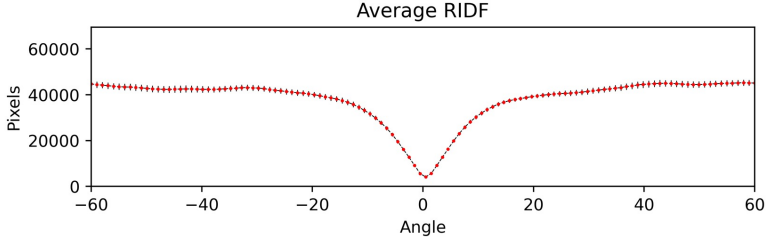
100%







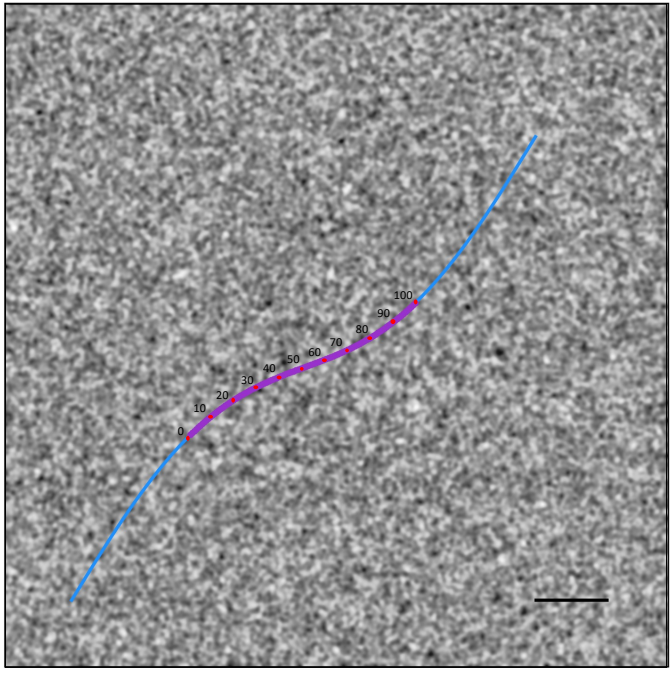


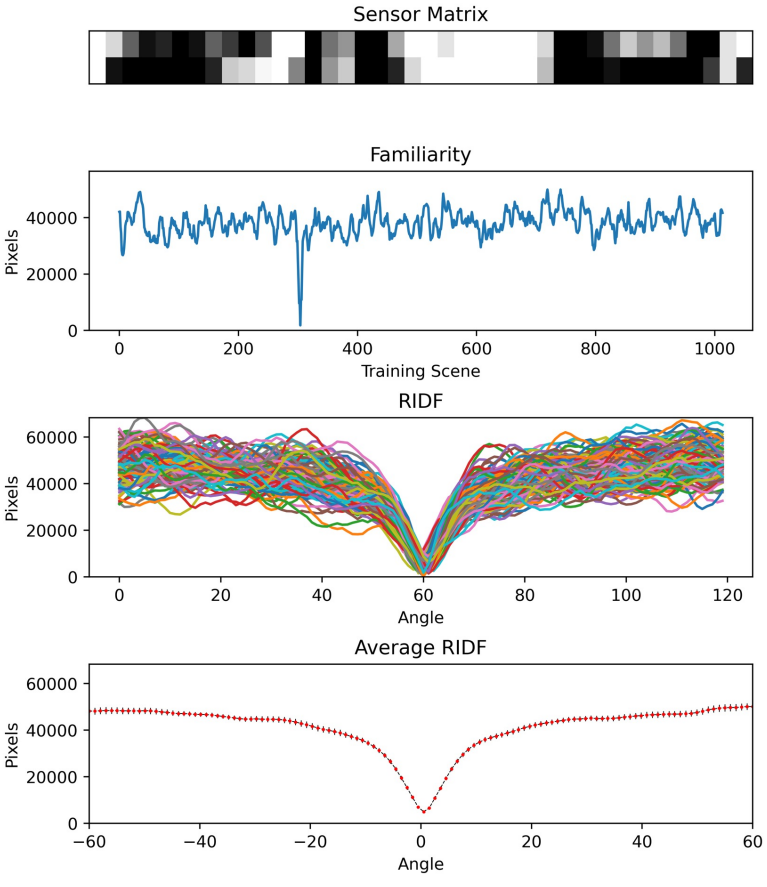


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 40.49; RMSD/dist: 0.101; TD: 29898; p90: 20; p50: 10; complete: 0

100%

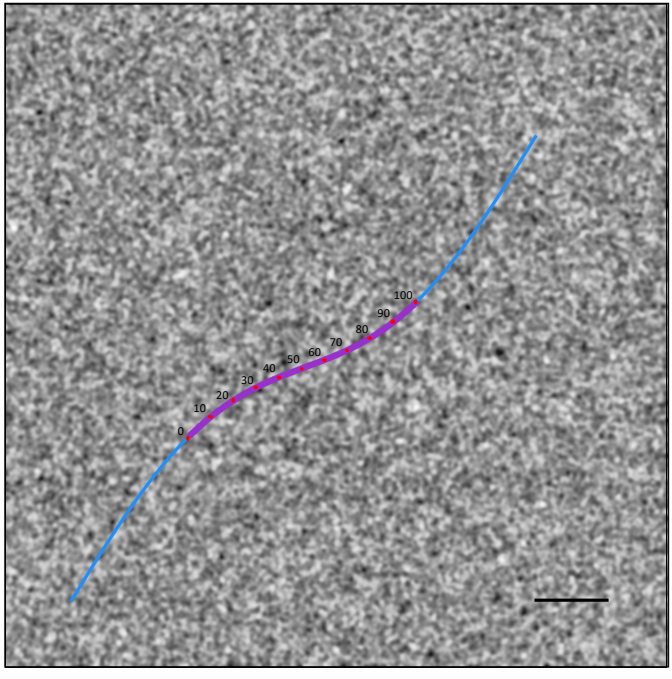


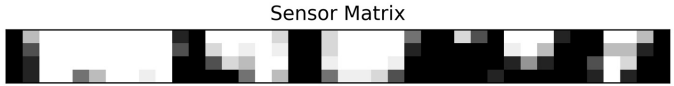


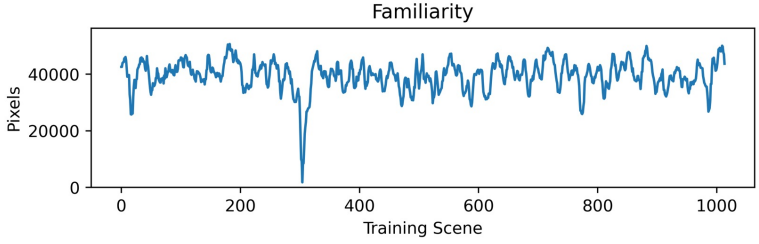
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

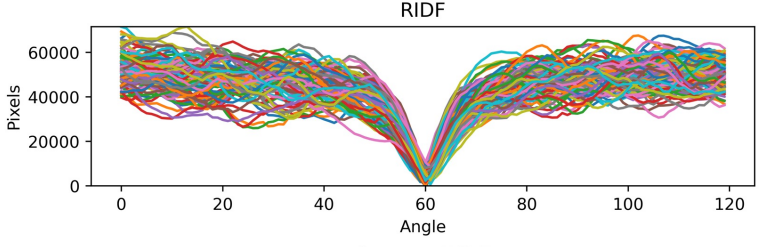
Navigation stats: RMSD error: 43.15; RMSD/dist: 0.108; TD: 33392; p90: 20; p50: 10; complete: 0

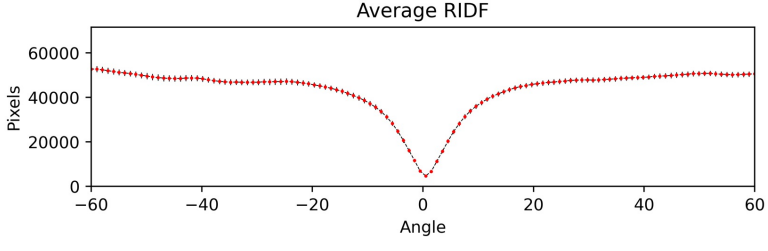
100%







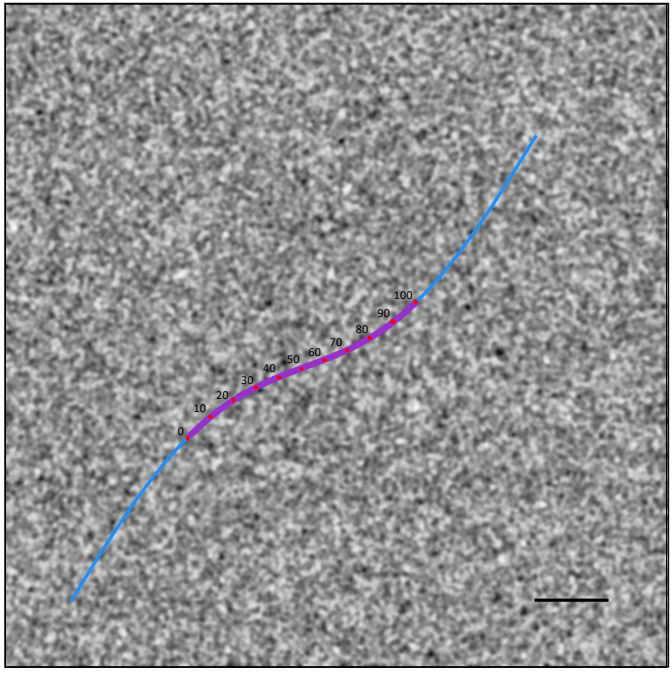


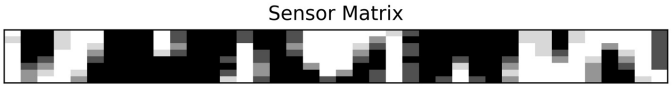


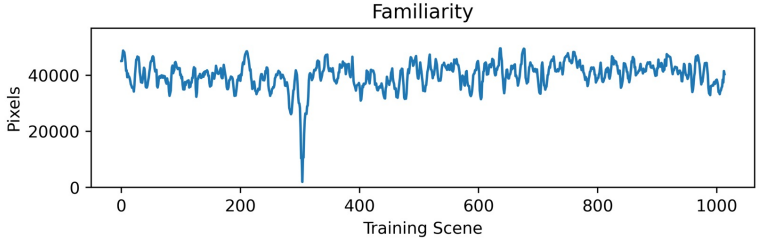
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

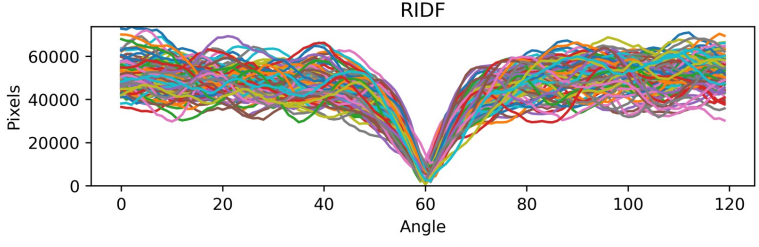
Navigation stats: RMSD error: 34.41; RMSD/dist: 0.086; TD: 35003; p90: 18; p50: 8; complete: 0

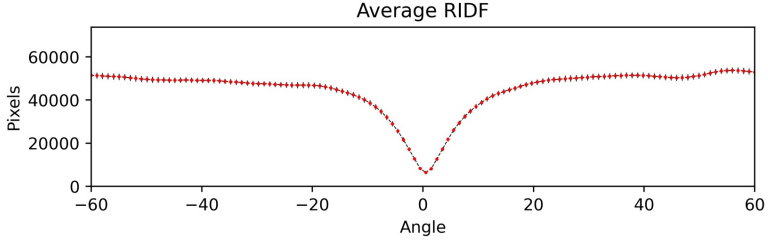
100%







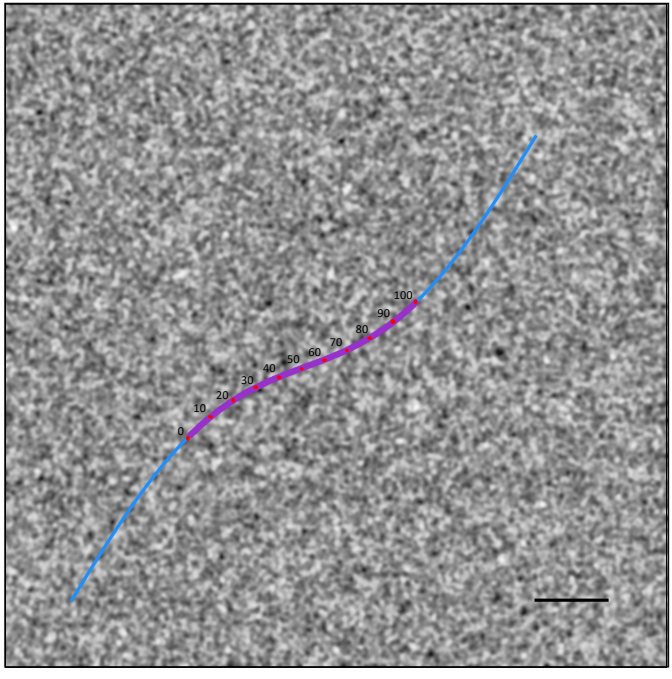


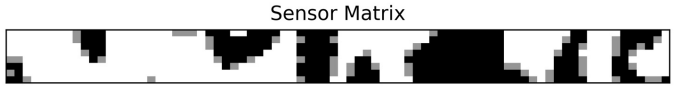


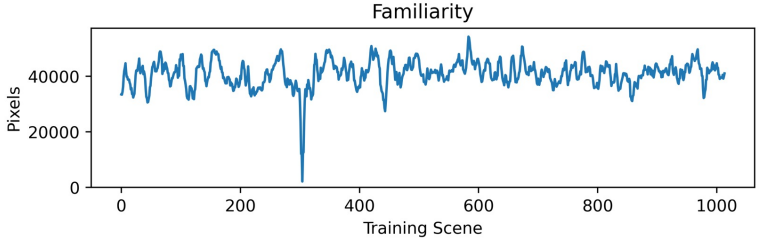
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

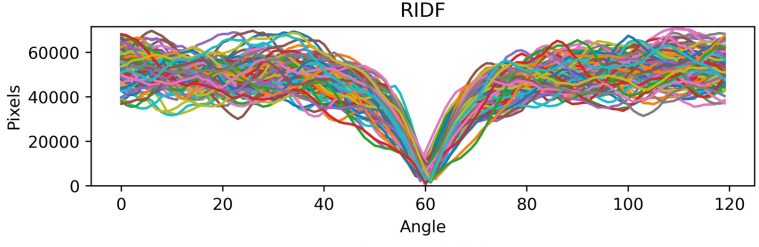
Navigation stats: RMSD error: 58.97; RMSD/dist: 0.147; TD: 33596; p90: 18; p50: 8; complete: 0

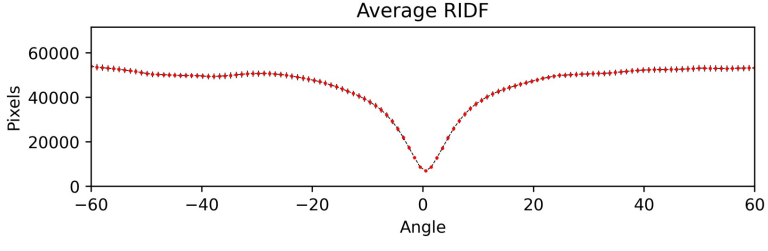
100%







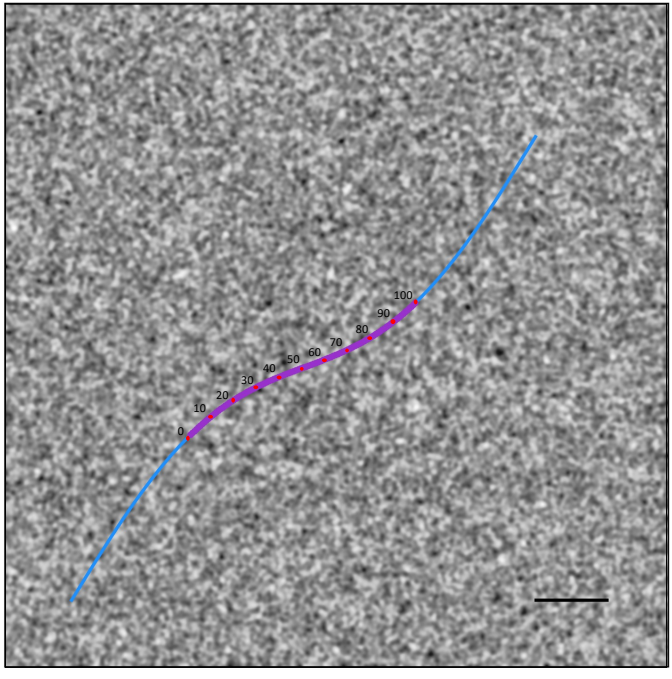


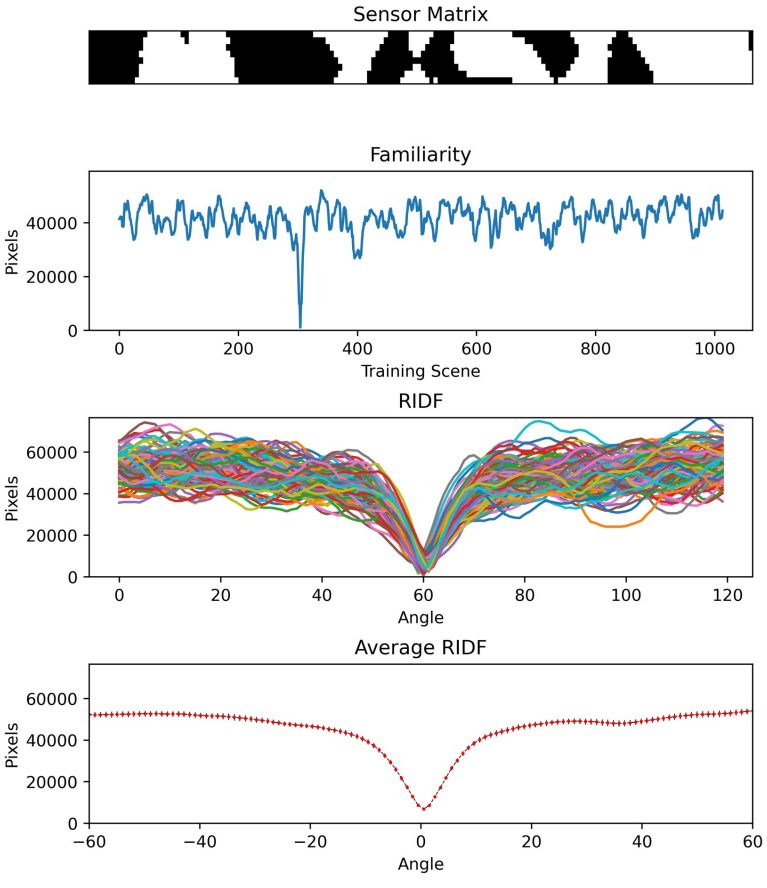


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 59.71; RMSD/dist: 0.149; TD: 34161; p90: 20; p50: 10; complete: 0

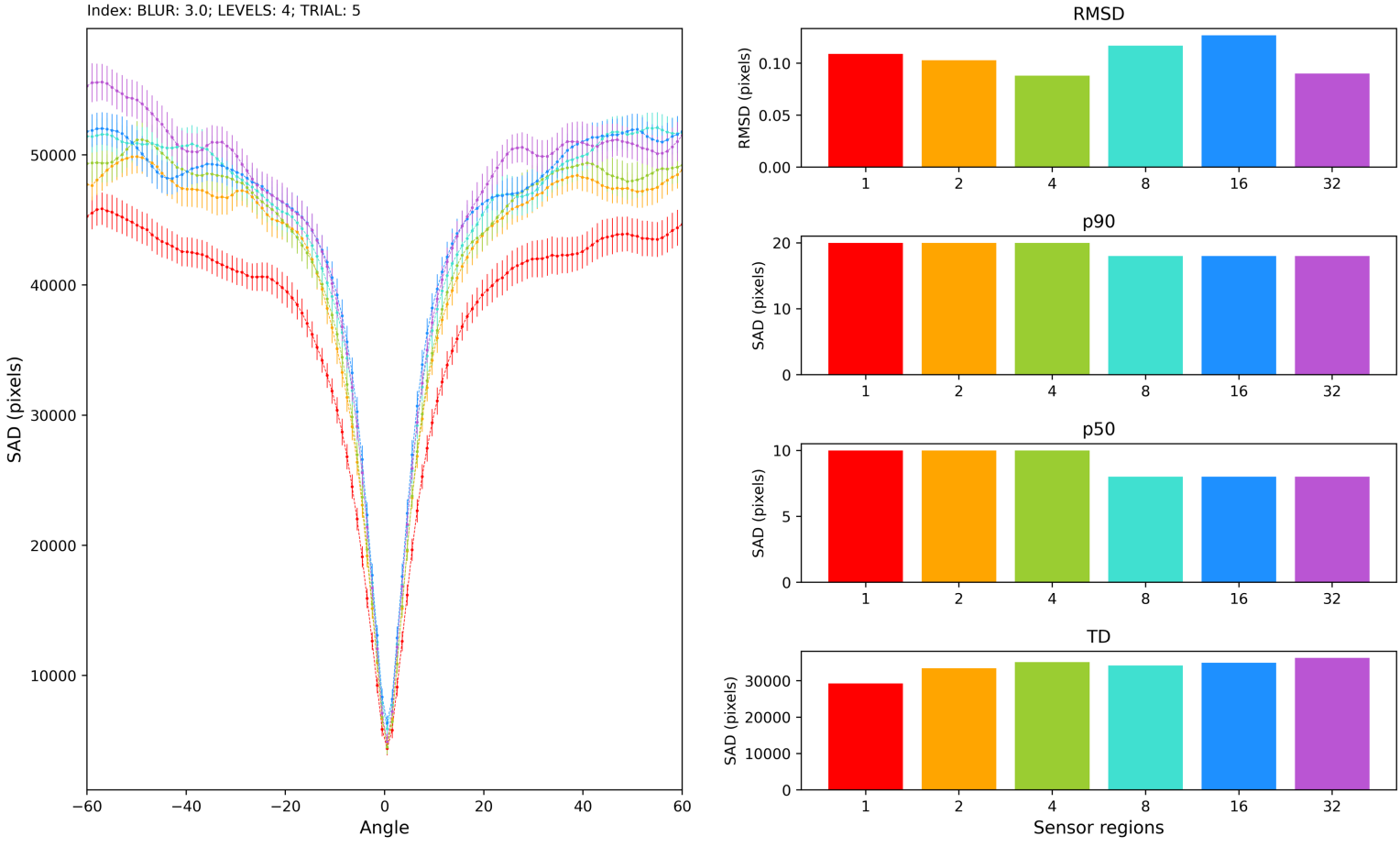
100%



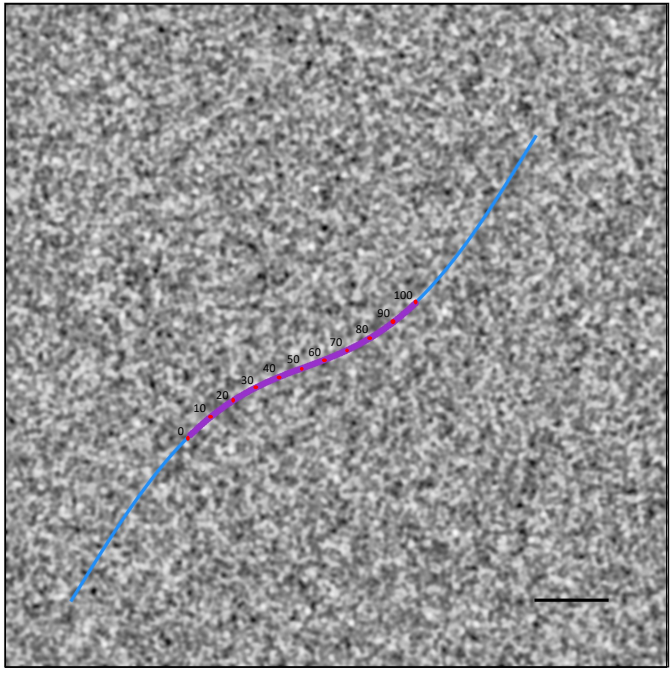


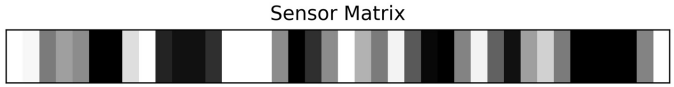
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

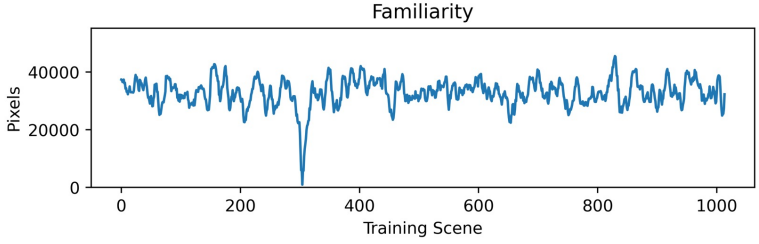
Navigation stats: RMSD error: 56.81; RMSD/dist: 0.142; TD: 34270; p90: 18; p50: 10; complete: 0

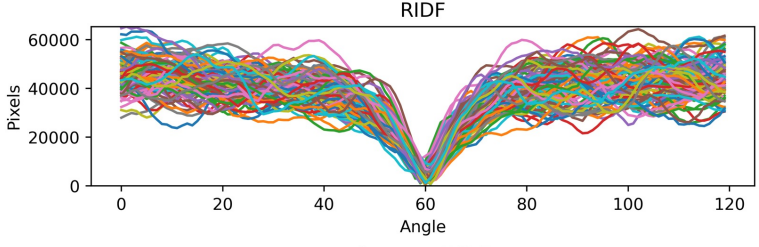

Index: BLUR: 3.0; LEVELS: 4; TRIAL: 5
SAD (pixels)
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
30000
20000
10000
0
Sensor regions

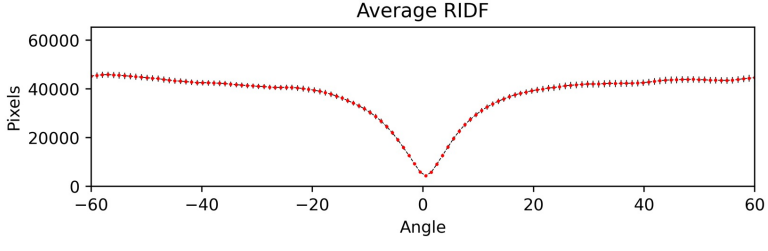
100%







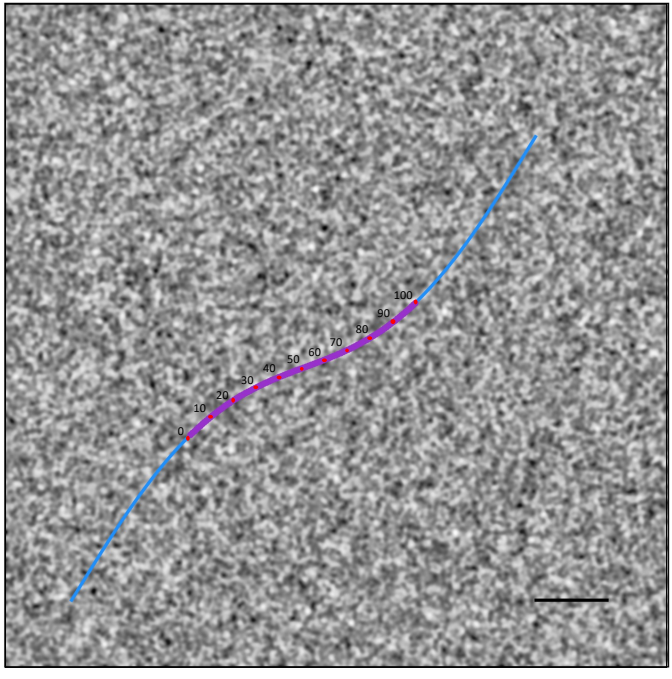


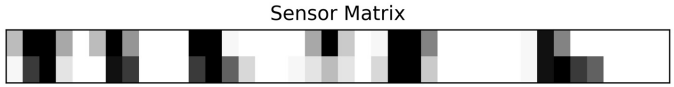


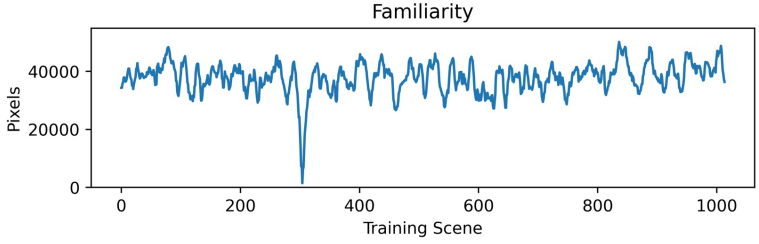
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

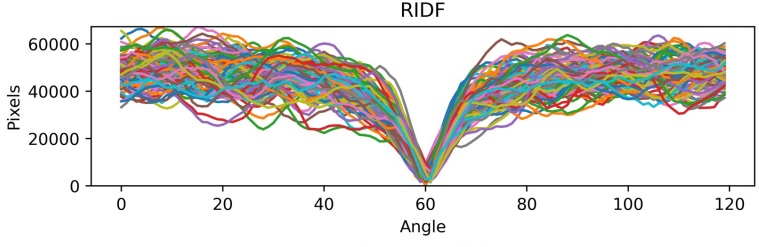
Navigation stats: RMSD error: 43.69; RMSD/dist: 0.109; TD: 29273; p90: 20; p50: 10; complete: 0

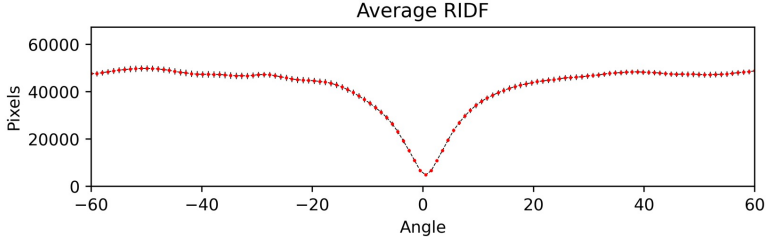
100%







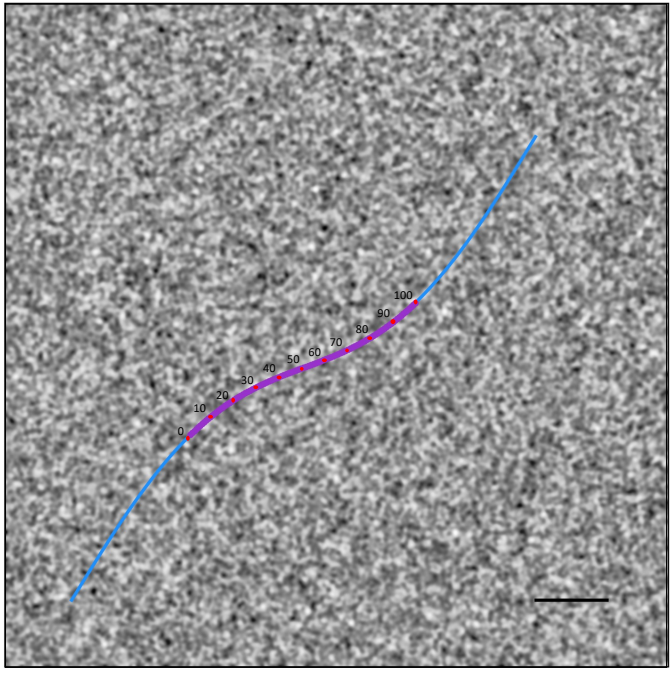


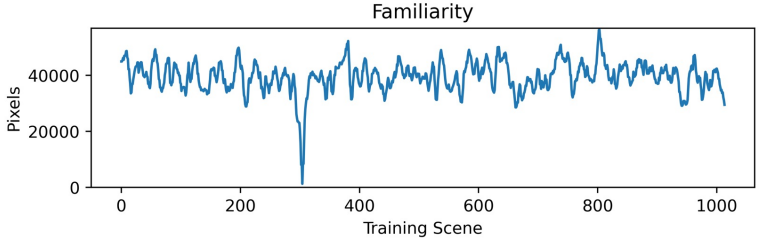


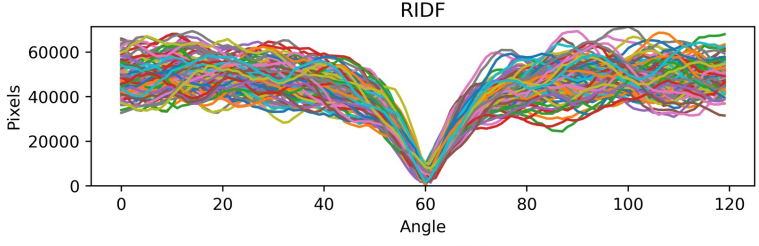
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

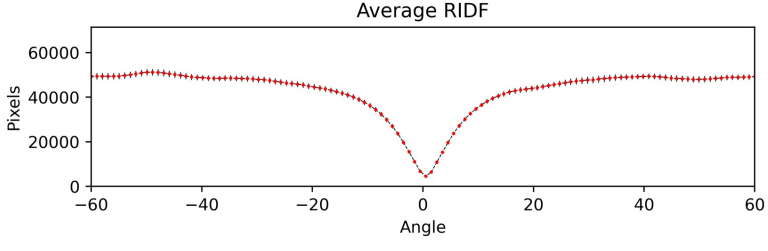
Navigation stats: RMSD error: 41.36; RMSD/dist: 0.103; TD: 33465; p90: 20; p50: 10; complete: 0

100%





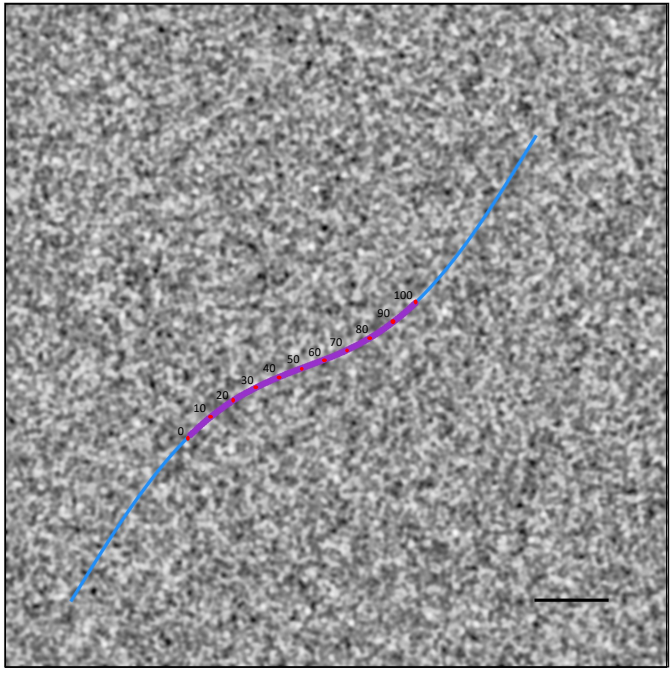


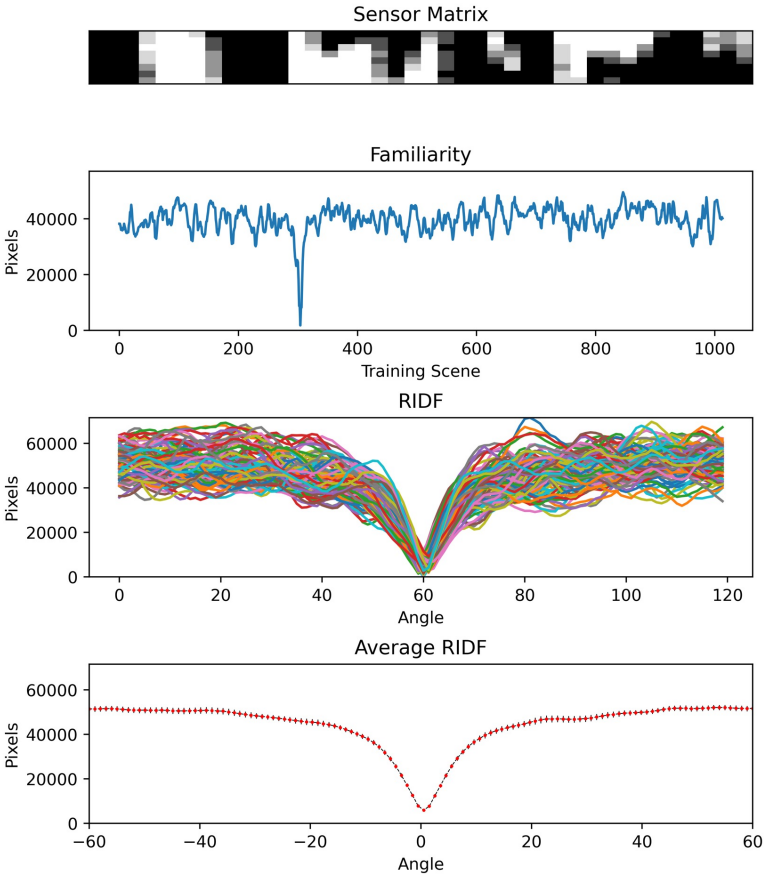


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 35.33; RMSD/dist: 0.088; TD: 35146; p90: 20; p50: 10; complete: 0

100%

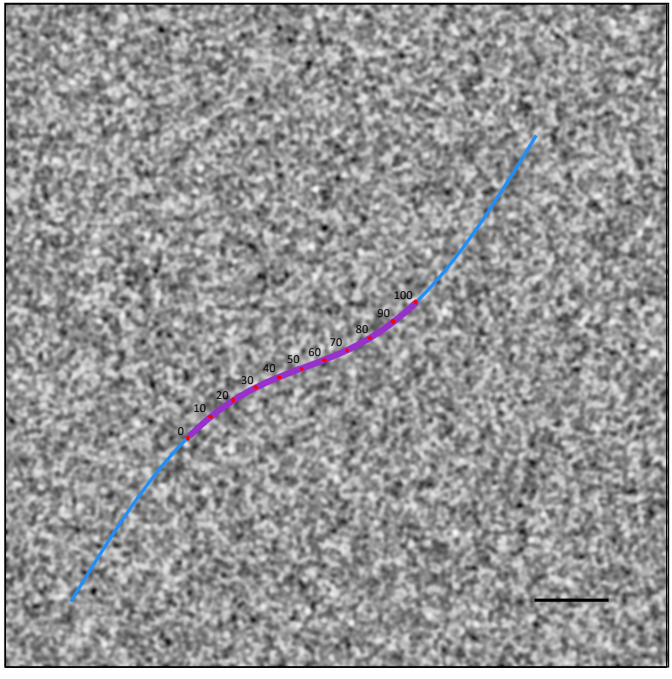


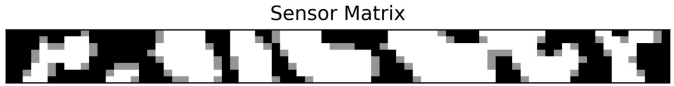


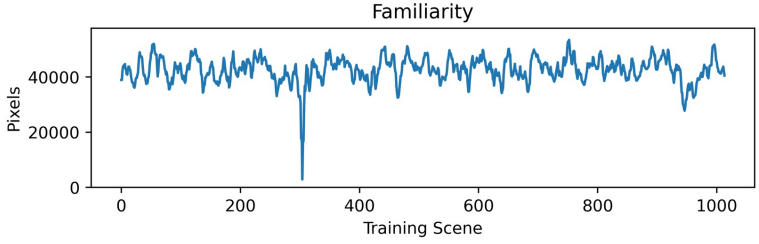
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

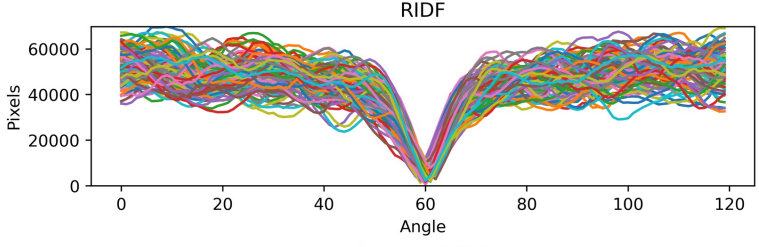
Navigation stats: RMSD error: 46.95; RMSD/dist: 0.117; TD: 34202; p90: 18; p50: 8; complete: 0

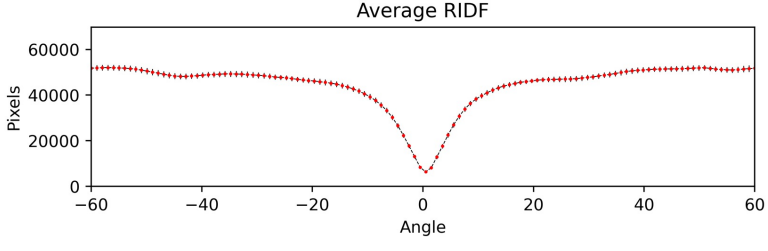
100%







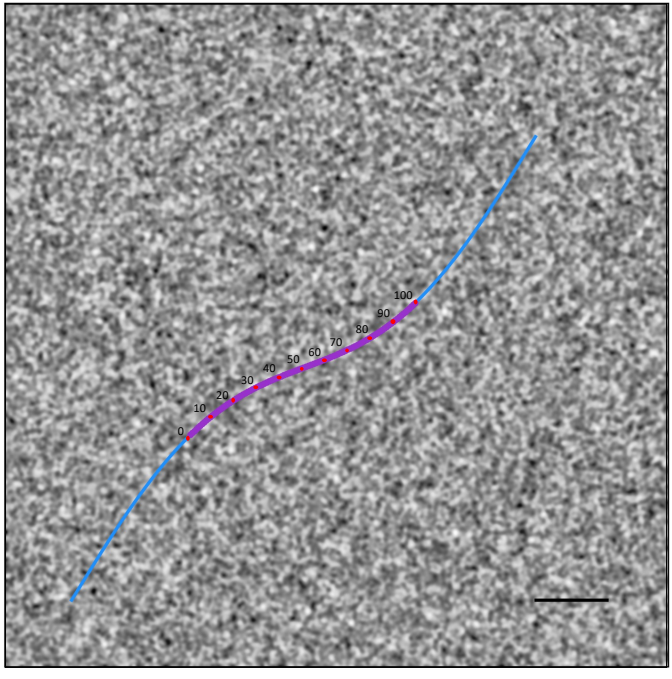


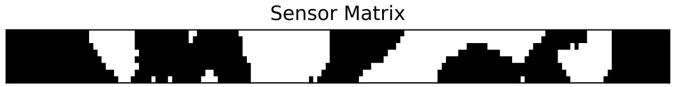


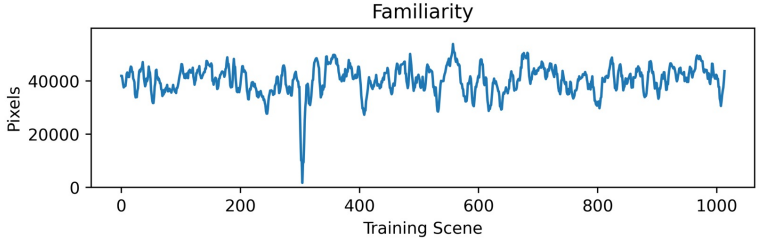
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

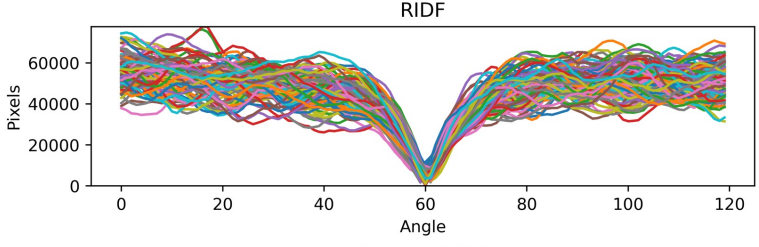
Navigation stats: RMSD error: 50.62; RMSD/dist: 0.127; TD: 34950; p90: 18; p50: 8; complete: 0

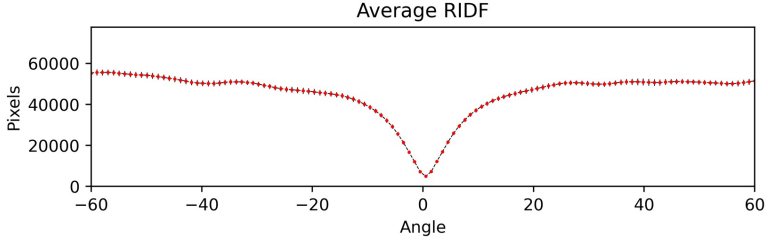
100%





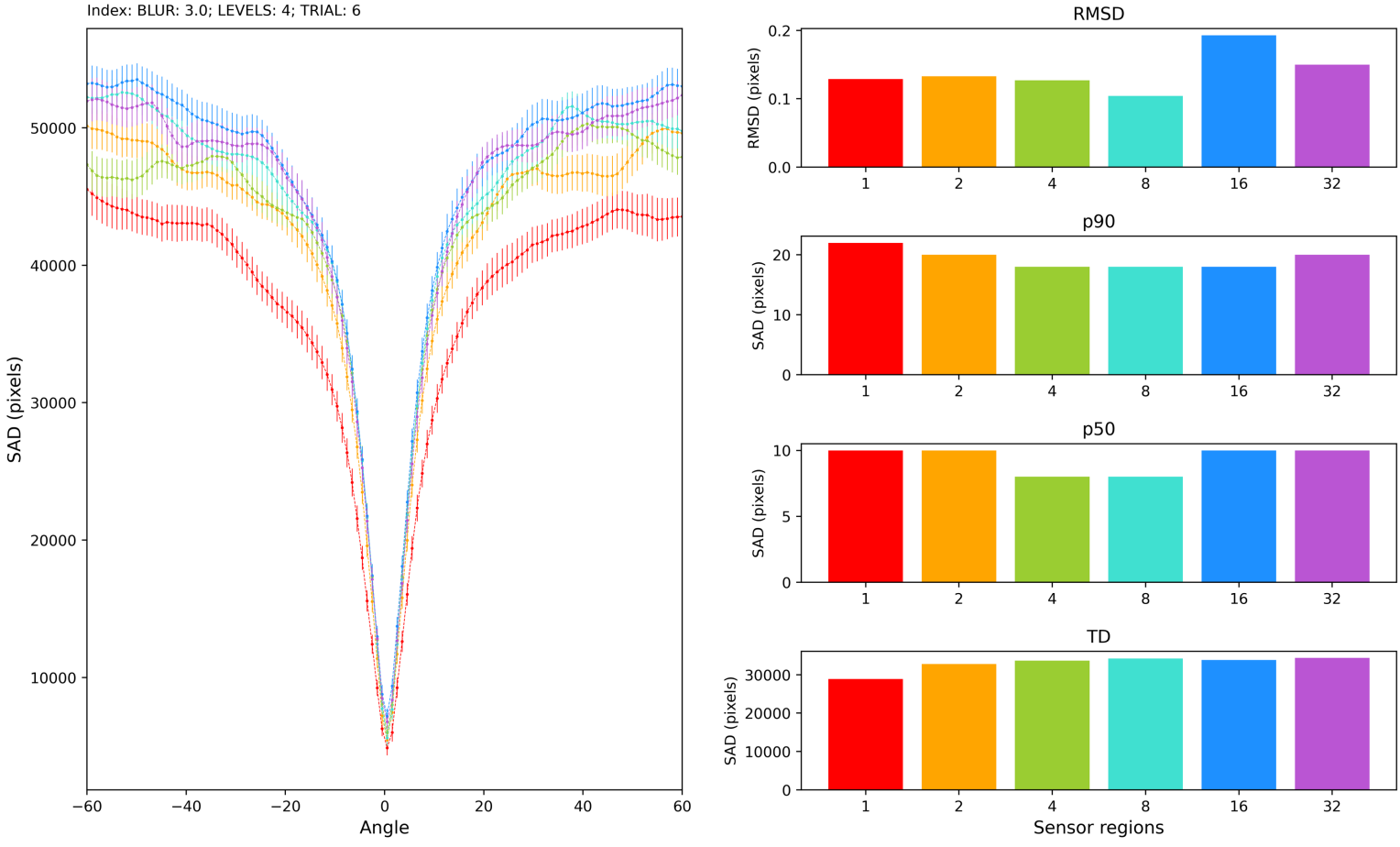




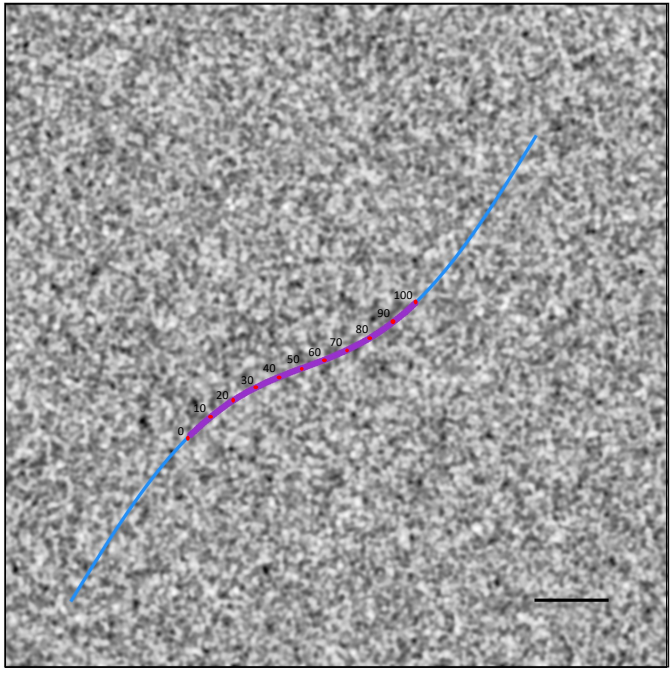


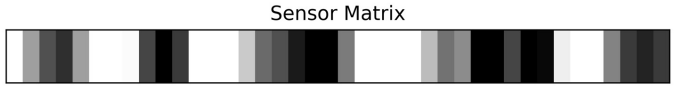
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

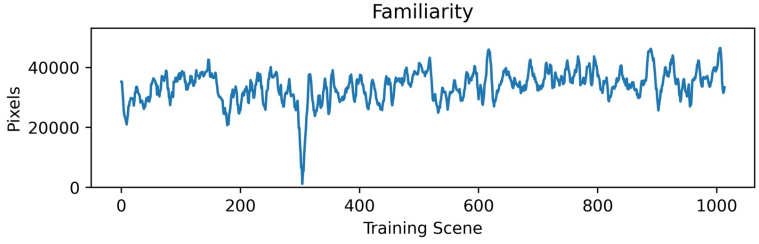
Navigation stats: RMSD error: 35.92; RMSD/dist: 0.090; TD: 36277; p90: 18; p50: 8; complete: 0

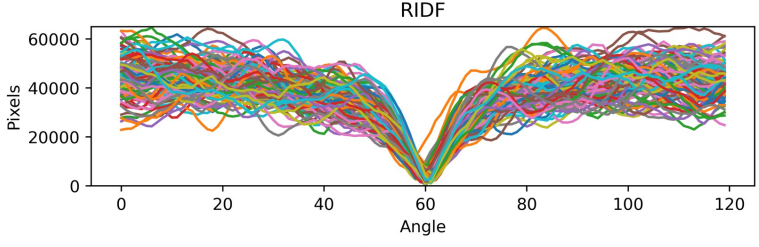

Index: BLUR: 3.0; LEVELS: 4; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

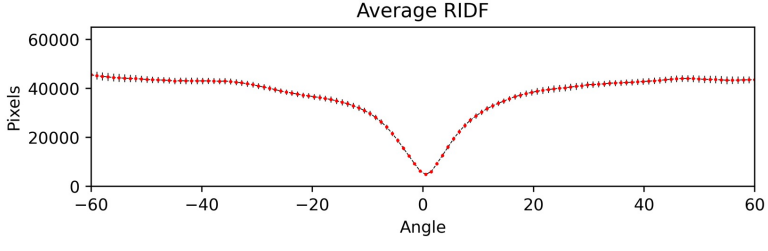
100%







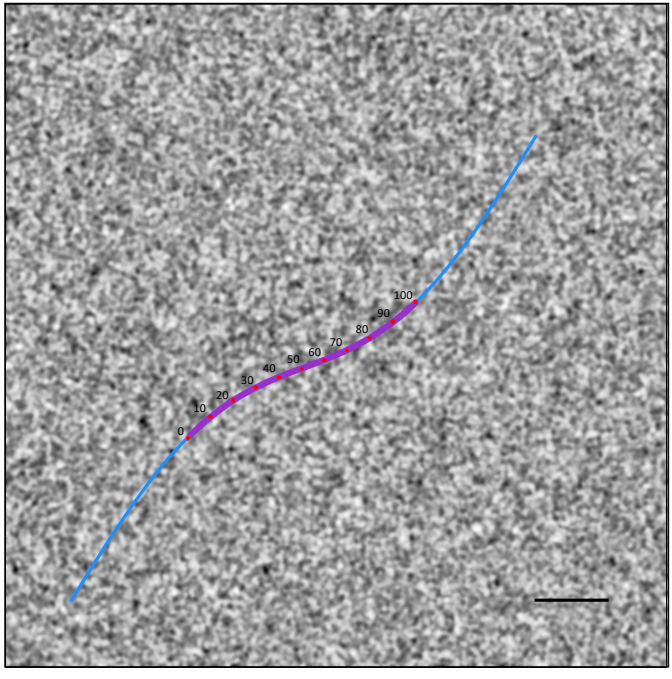


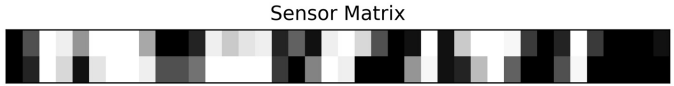


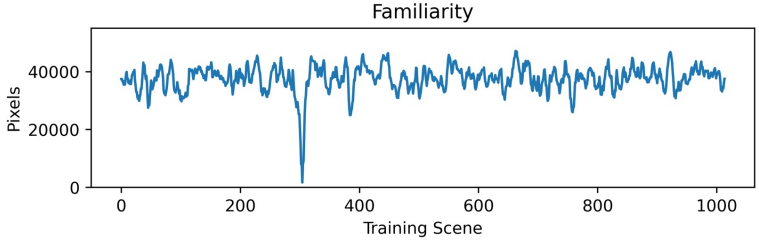
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

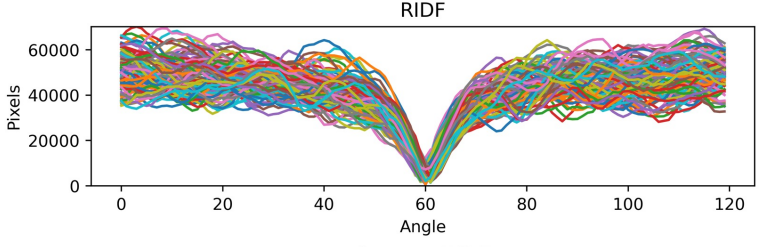
Navigation stats: RMSD error: 51.77; RMSD/dist: 0.129; TD: 28880; p90: 22; p50: 10; complete: 0

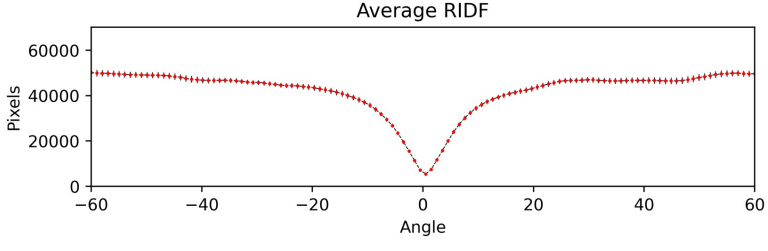
100%







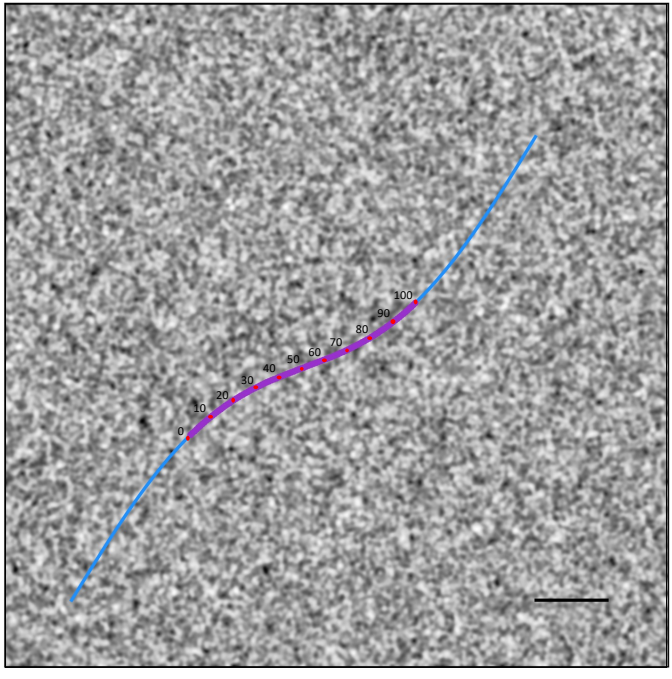


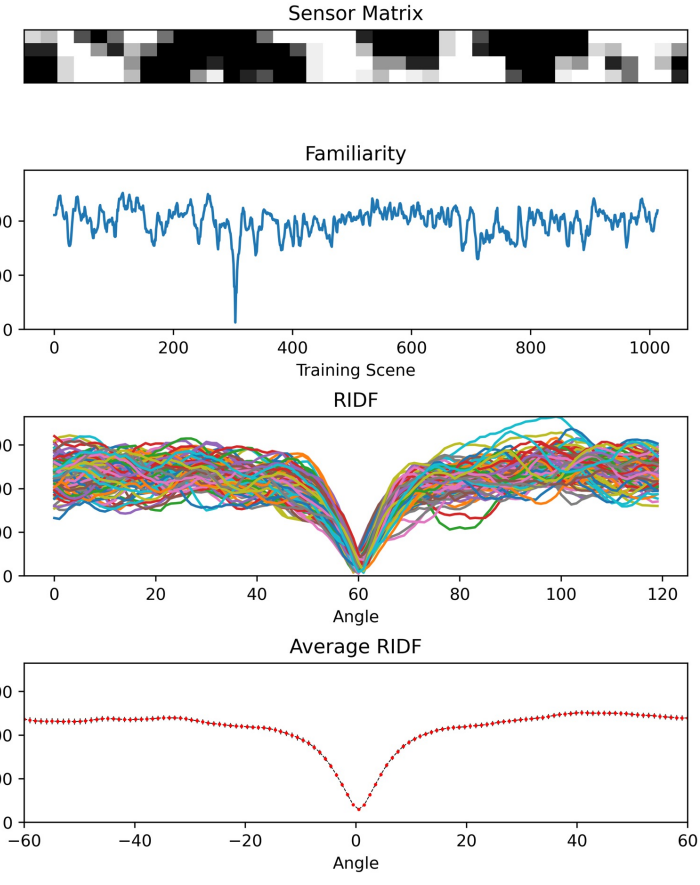


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 53.03; RMSD/dist: 0.133; TD: 32778; p90: 20; p50: 10; complete: 0

100%

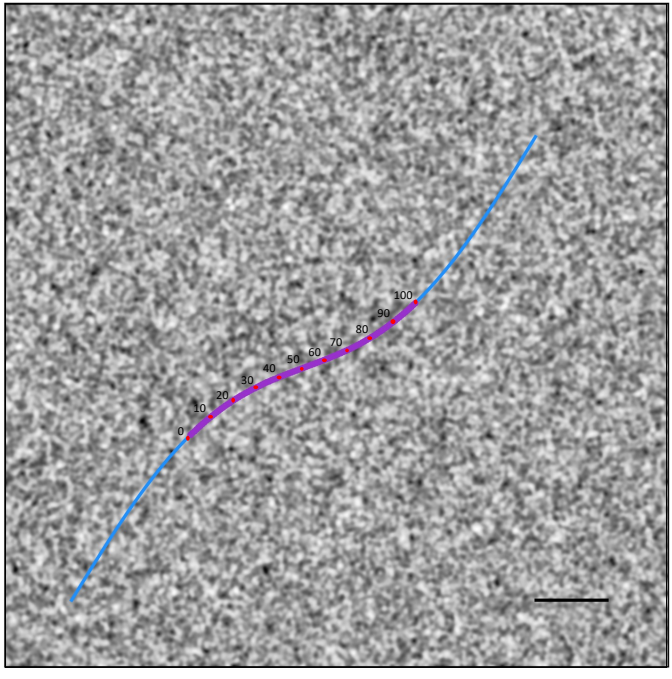


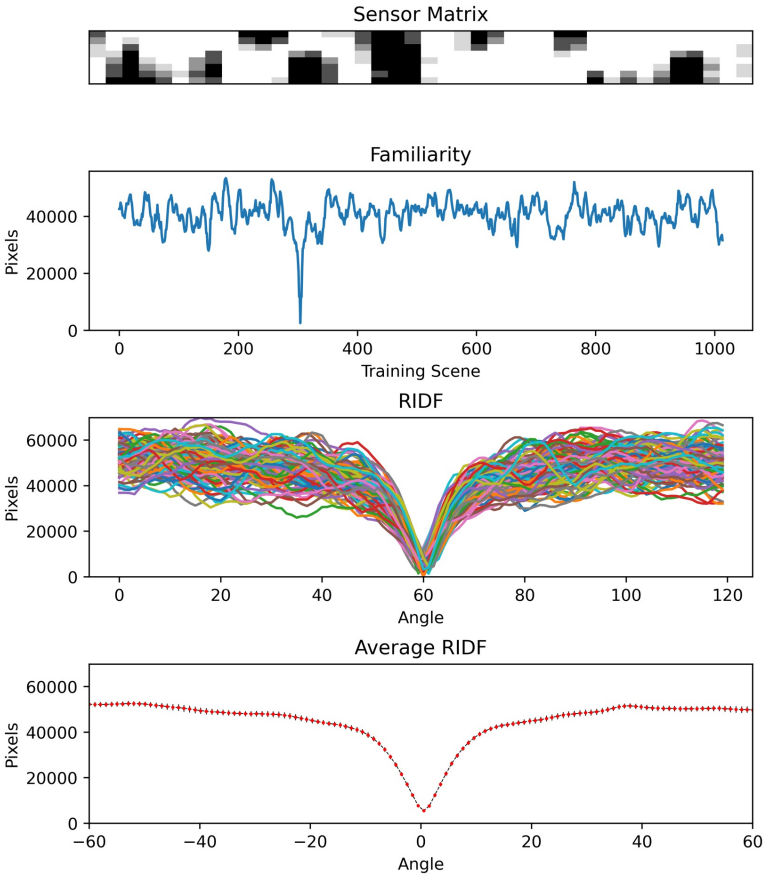


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 50.79; RMSD/dist: 0.127; TD: 33668; p90: 18; p50: 8; complete: 0

100%

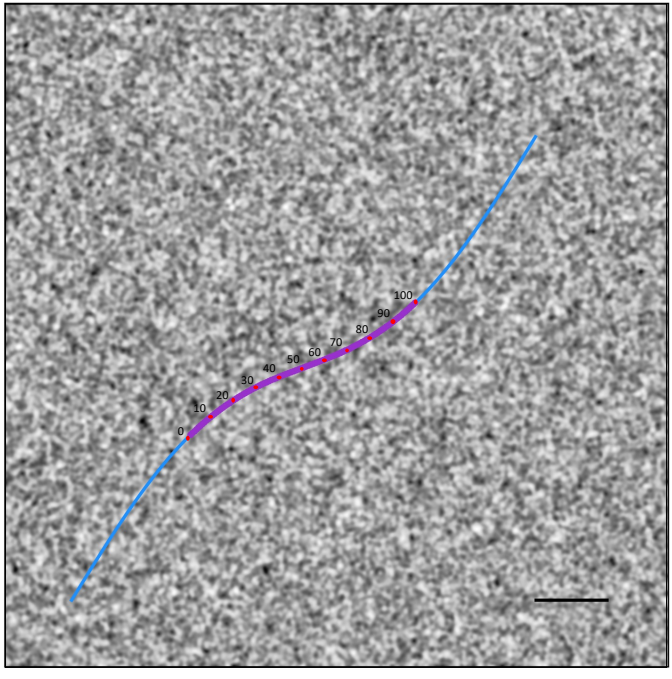


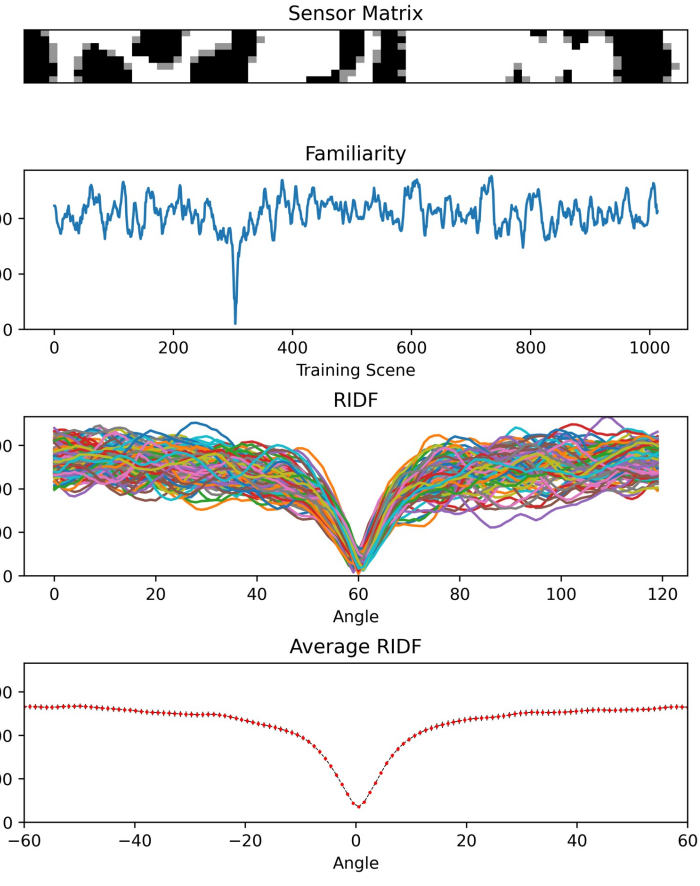


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 41.45; RMSD/dist: 0.104; TD: 34244; p90: 18; p50: 8; complete: 0

100%

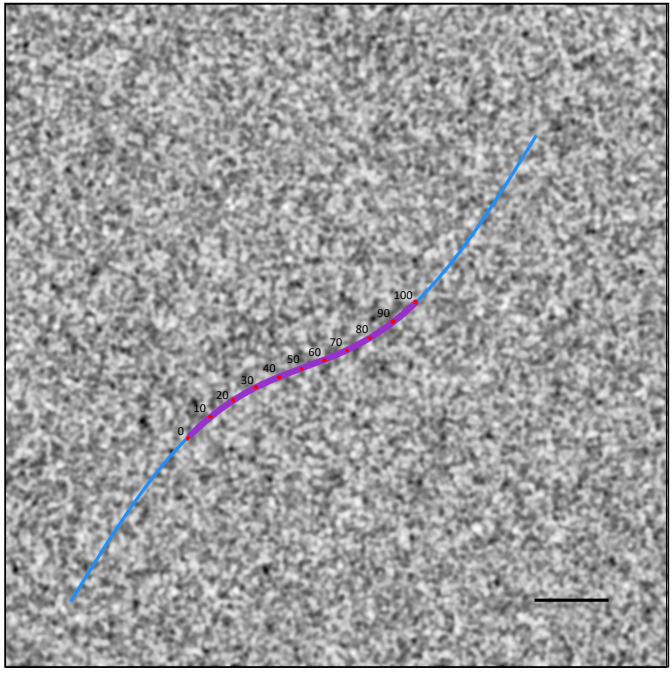


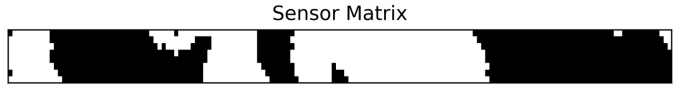


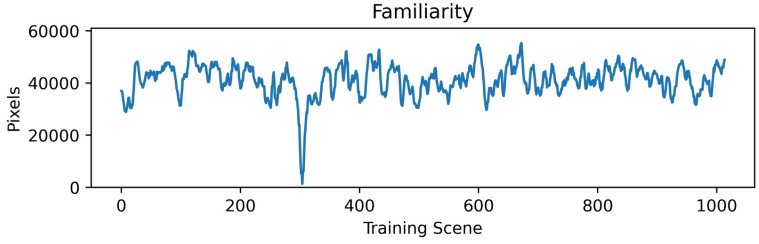
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

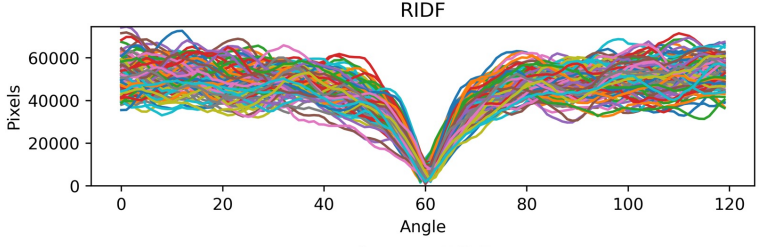
Navigation stats: RMSD error: 77.18; RMSD/dist: 0.193; TD: 33864; p90: 18; p50: 10; complete: 0

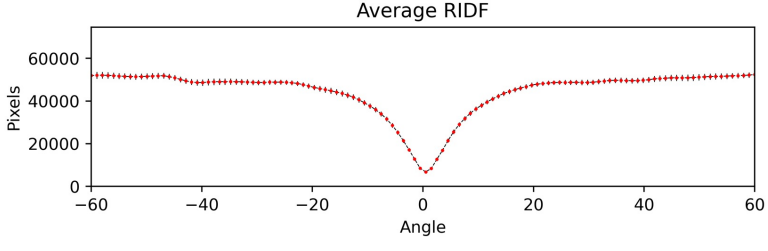
100%





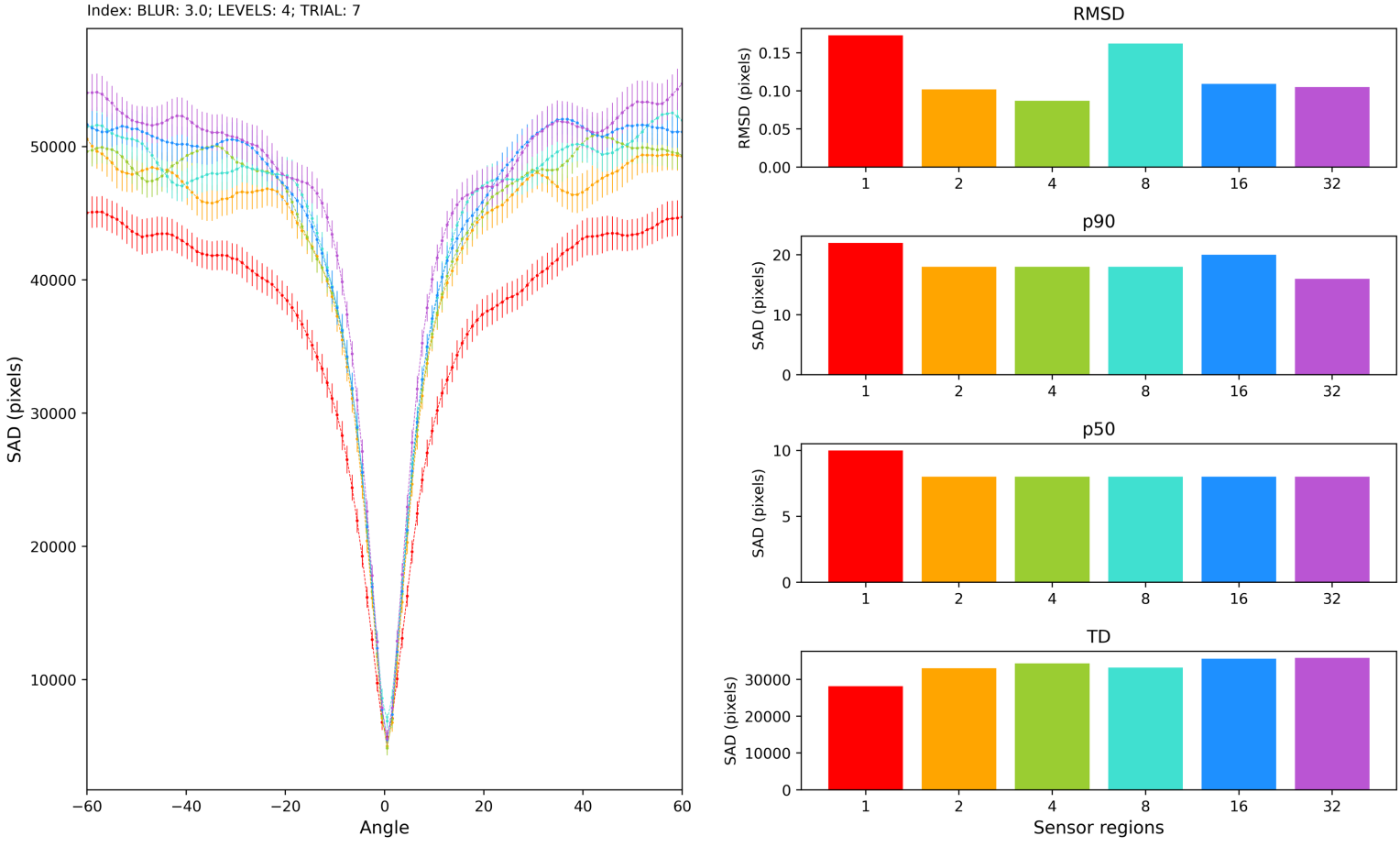




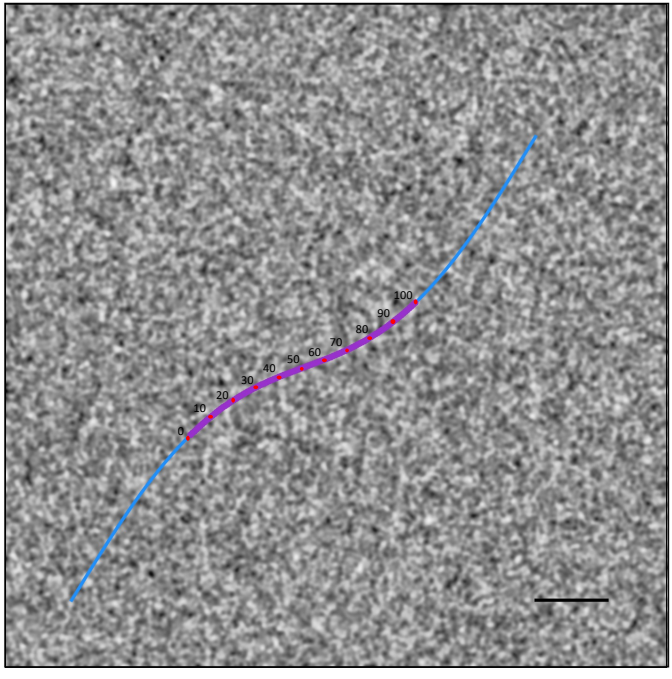


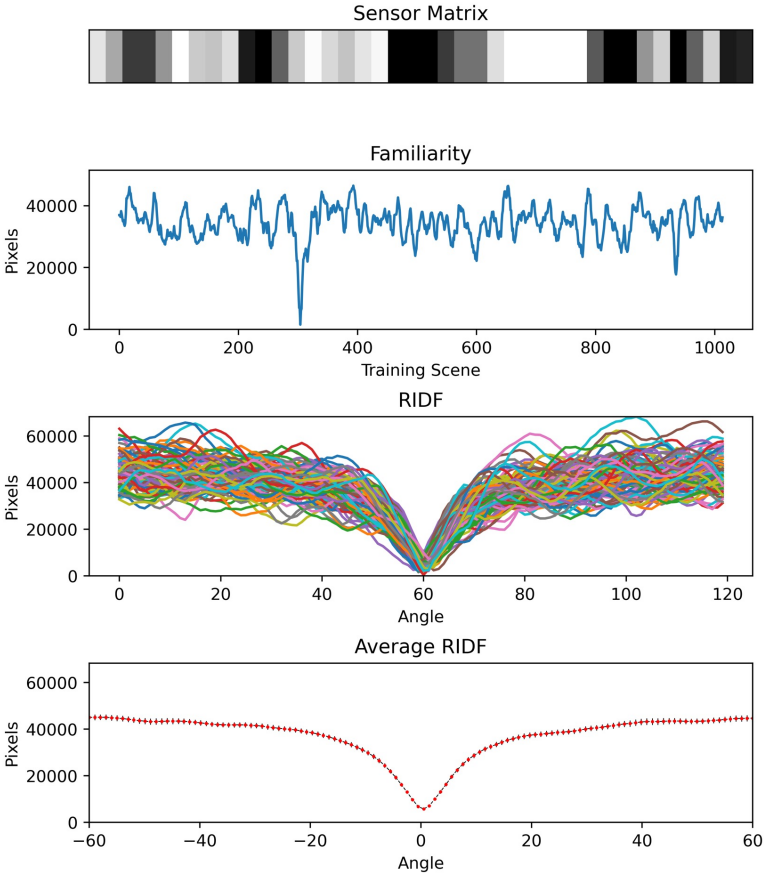
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 60.01; RMSD/dist: 0.150; TD: 34367; p90: 20; p50: 10; complete: 0


Index: BLUR: 3.0; LEVELS: 4; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

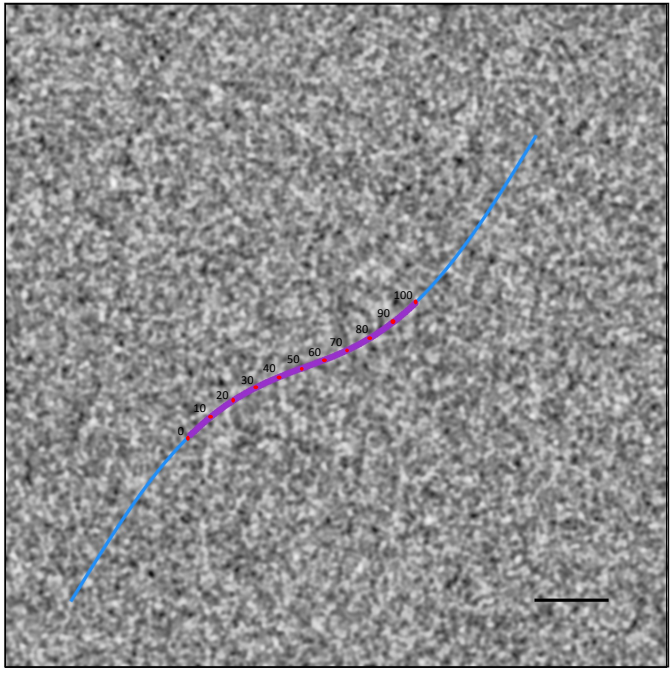


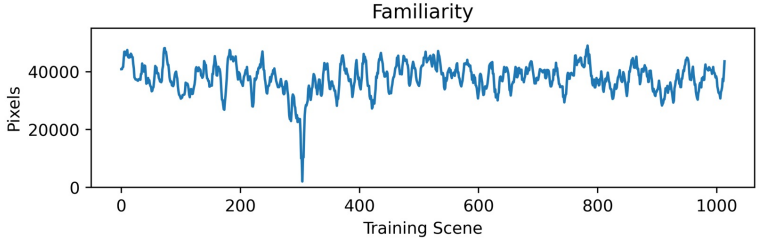


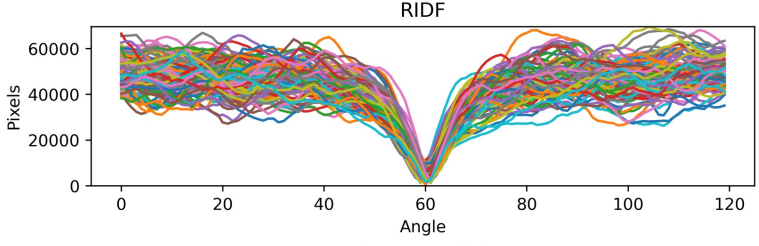
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

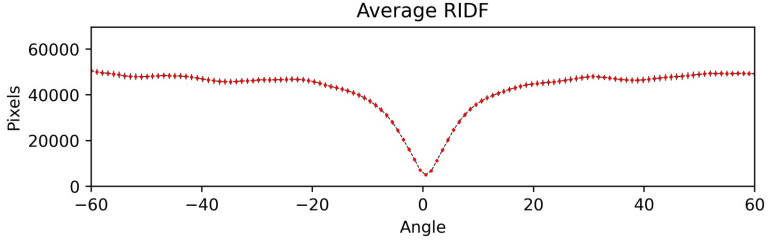
Navigation stats: RMSD error: 69.33; RMSD/dist: 0.173; TD: 28143; p90: 22; p50: 10; complete: 0

100%





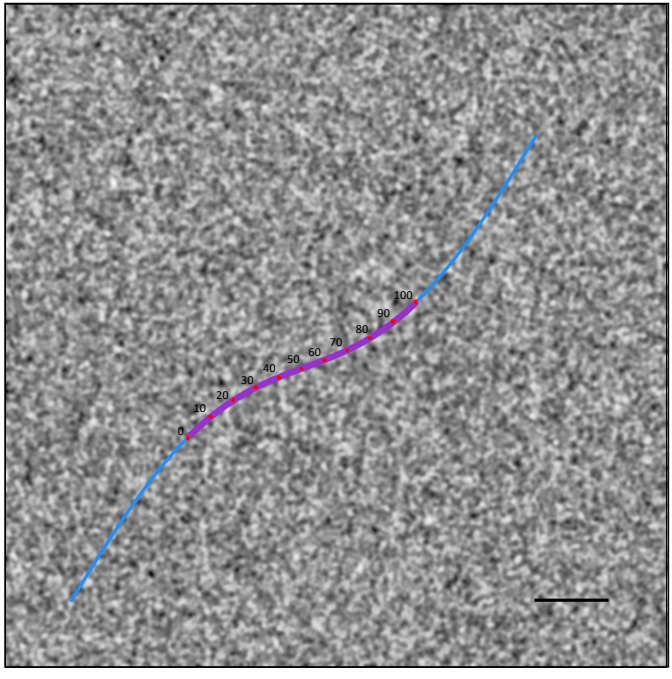


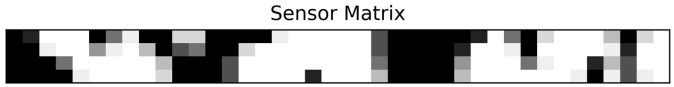


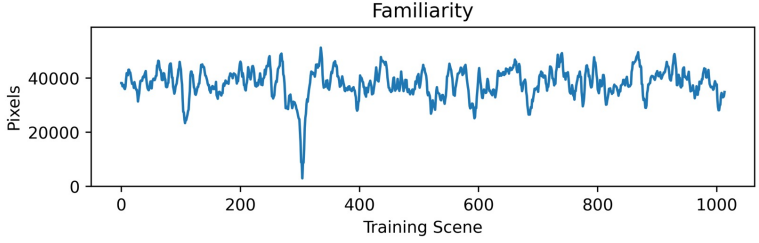
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

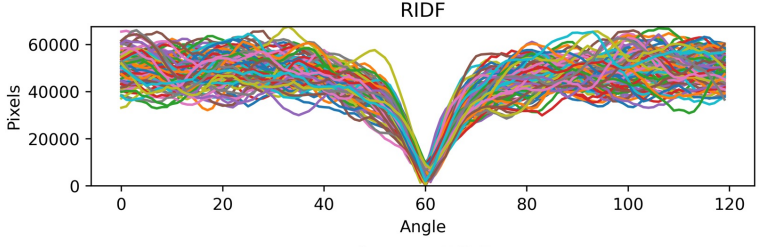
Navigation stats: RMSD error: 40.99; RMSD/dist: 0.102; TD: 33016; p90: 18; p50: 8; complete: 0

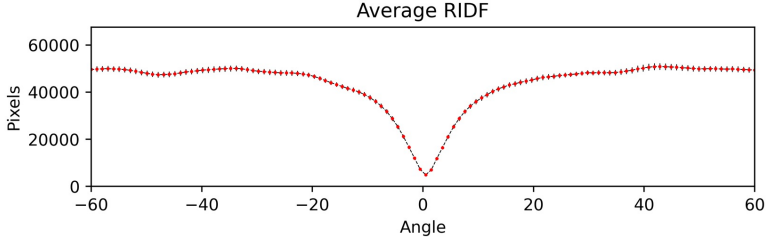
100%







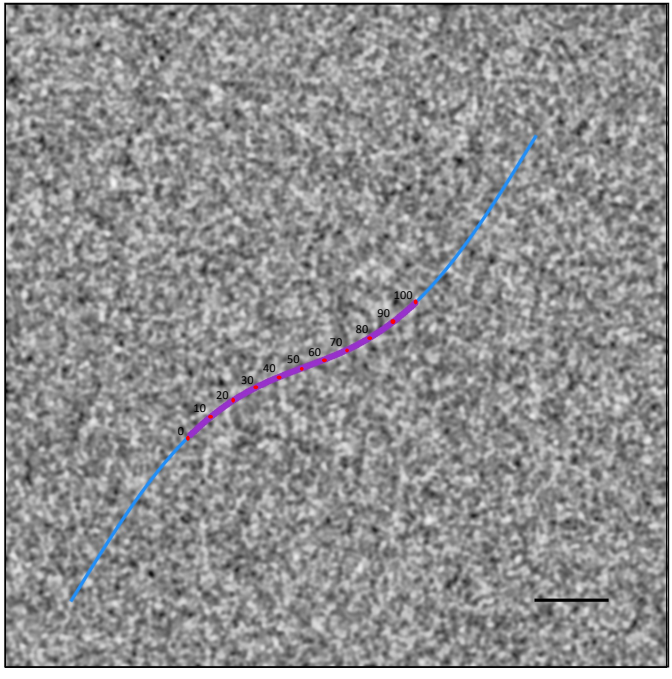


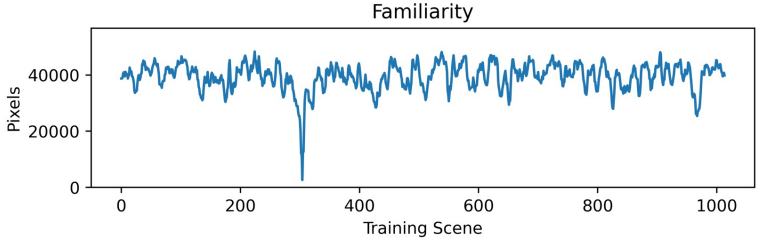


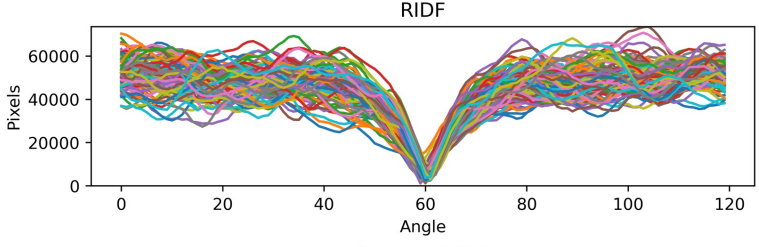
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

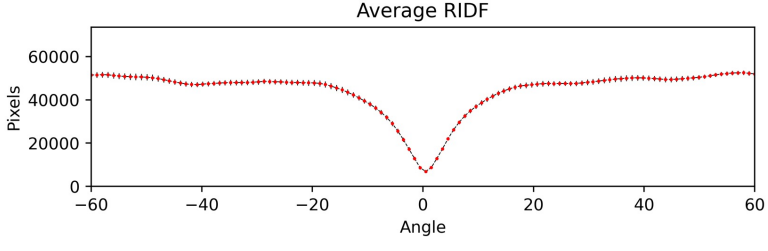
Navigation stats: RMSD error: 34.62; RMSD/dist: 0.087; TD: 34359; p90: 18; p50: 8; complete: 0

100%





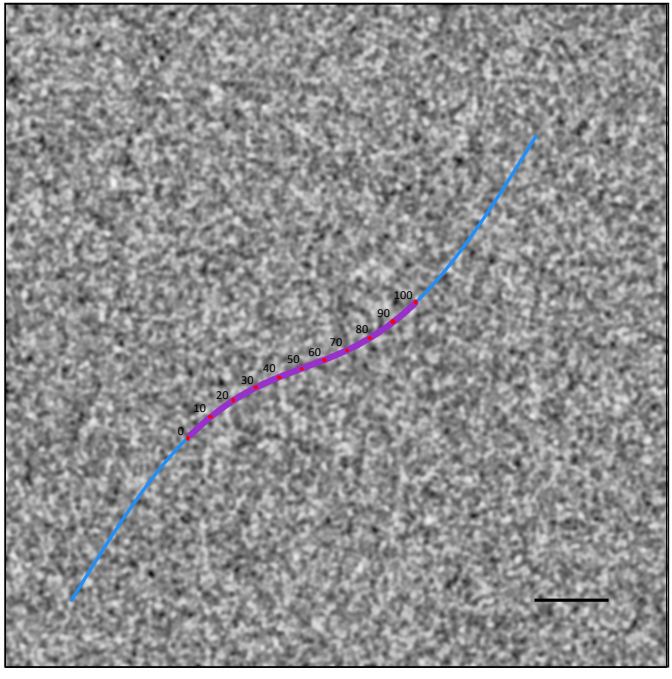


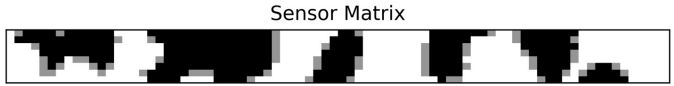


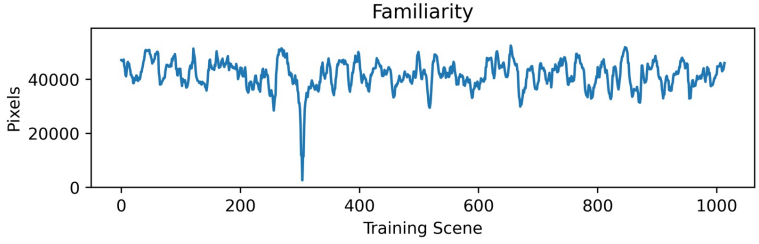
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

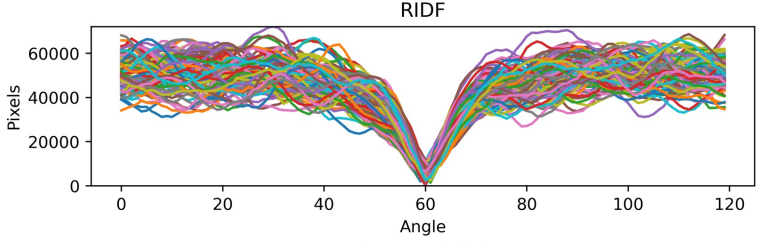
Navigation stats: RMSD error: 64.66; RMSD/dist: 0.162; TD: 33222; p90: 18; p50: 8; complete: 0

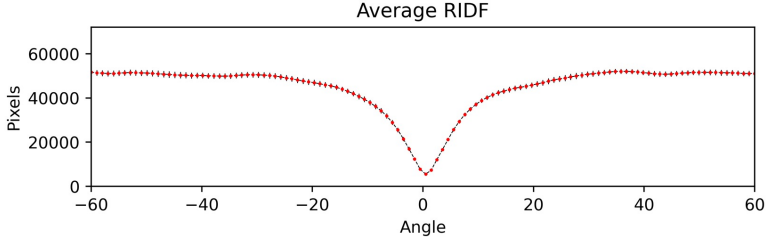
100%







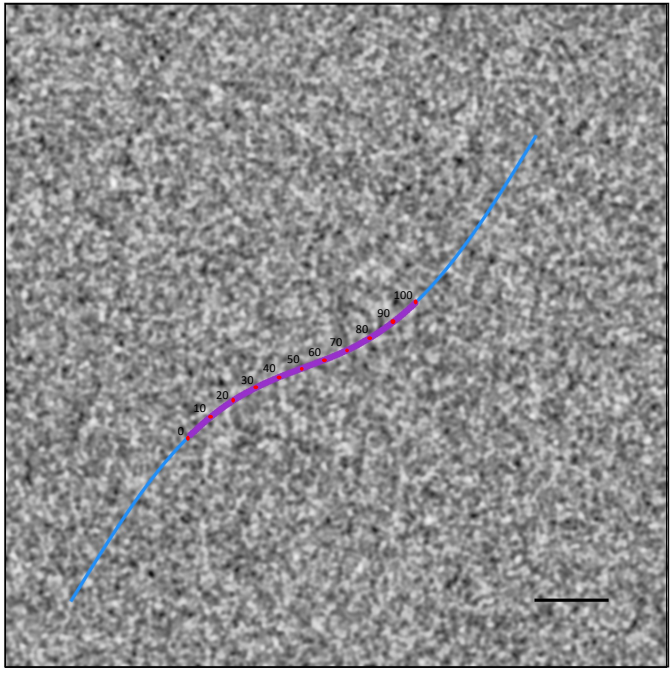


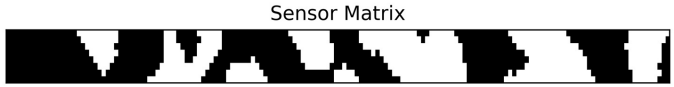


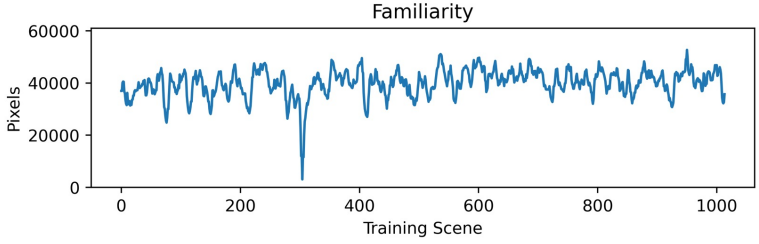
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

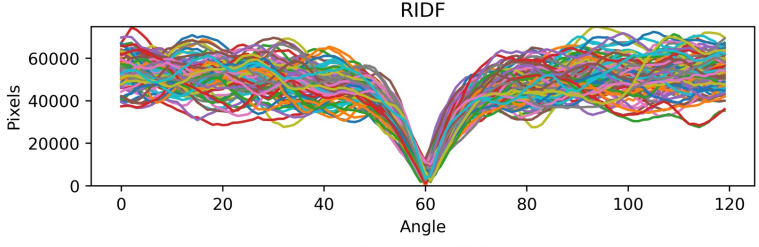
Navigation stats: RMSD error: 43.54; RMSD/dist: 0.109; TD: 35608; p90: 20; p50: 8; complete: 0

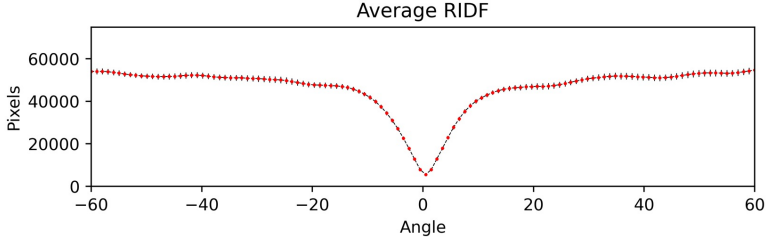
100%





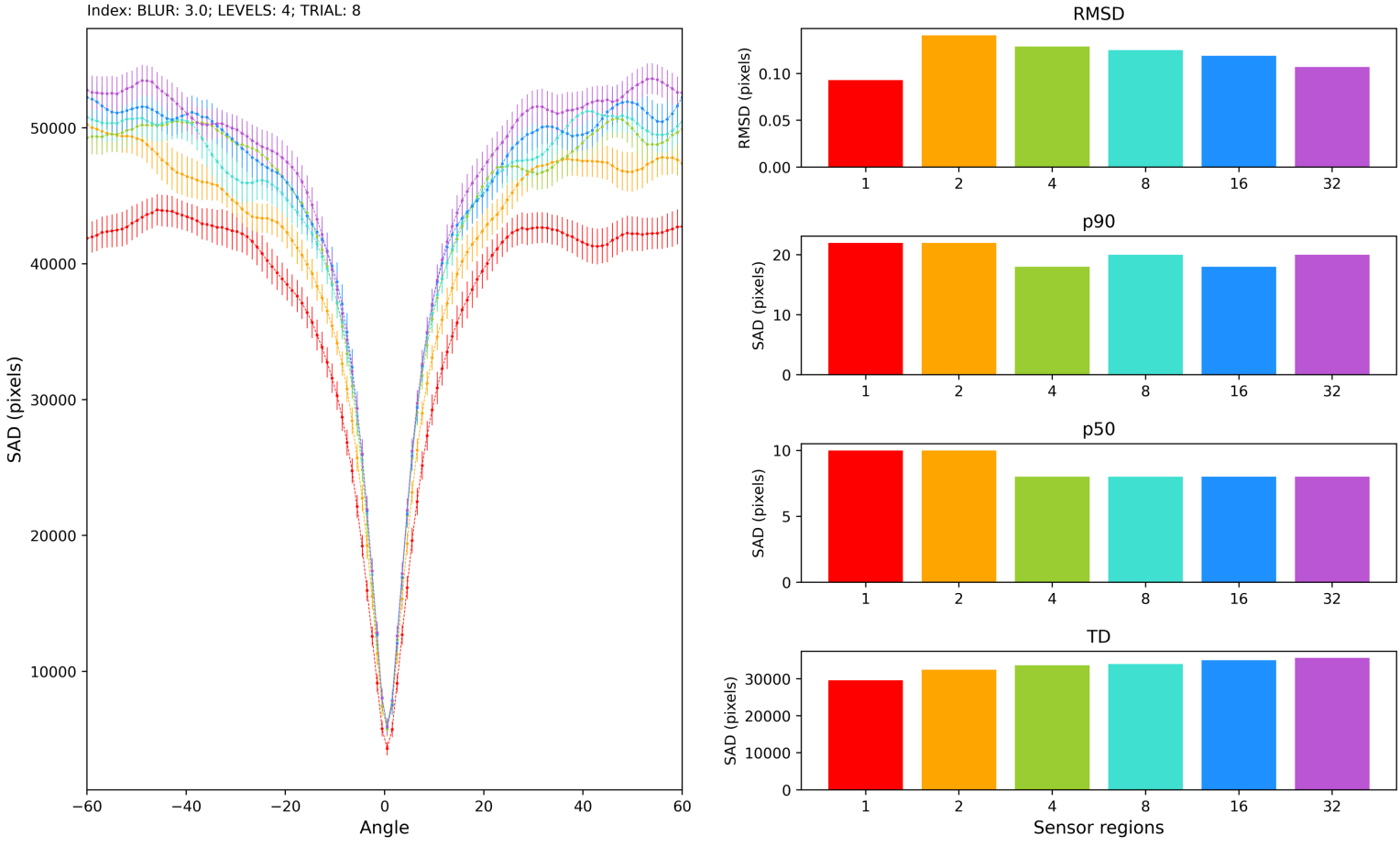




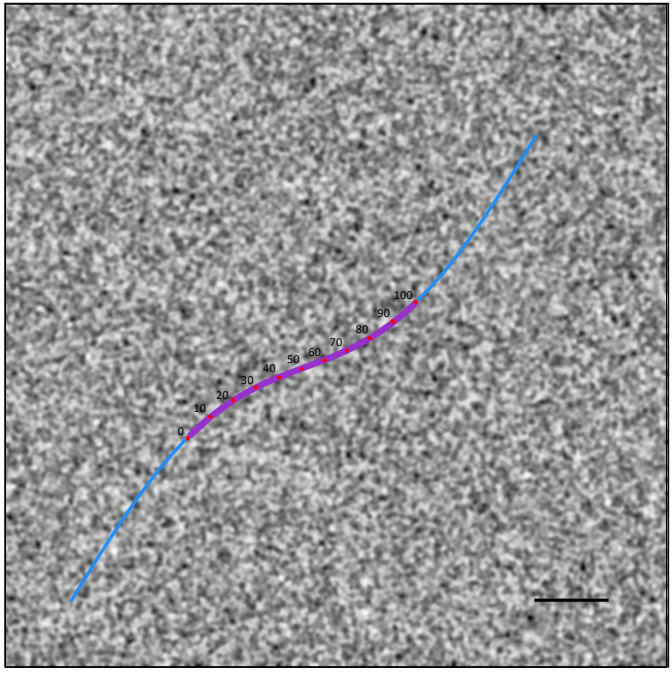


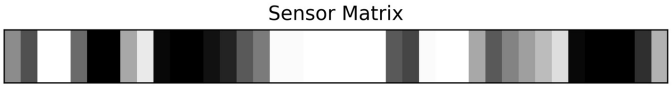
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

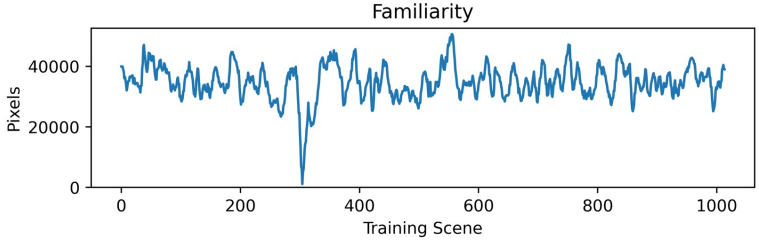
Navigation stats: RMSD error: 42.01; RMSD/dist: 0.105; TD: 35829; p90: 16; p50: 8; complete: 0

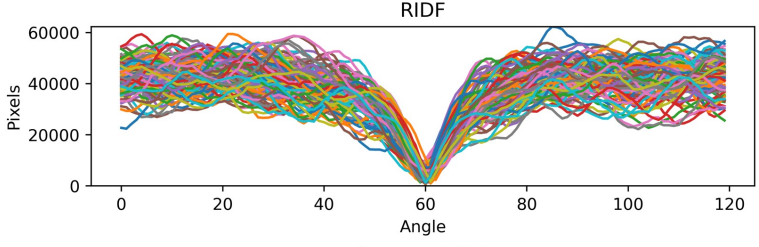

Index: BLUR: 3.0; LEVELS: 4; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

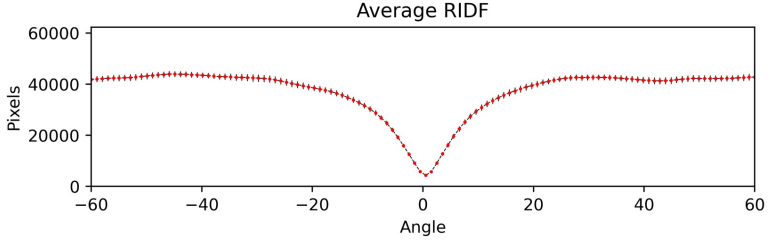
100%







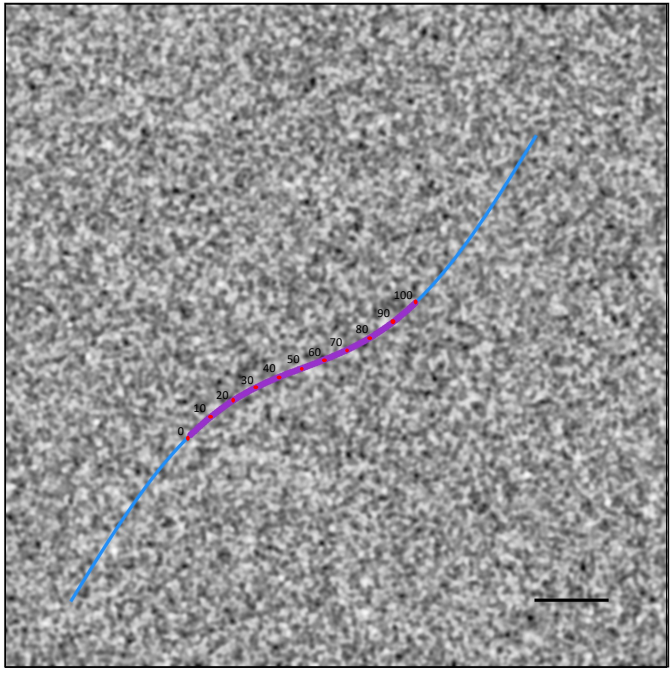


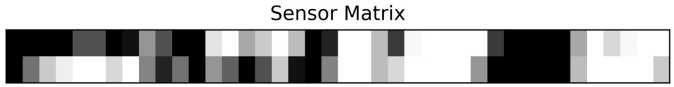


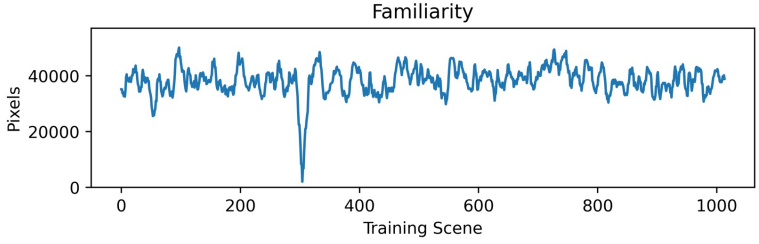
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

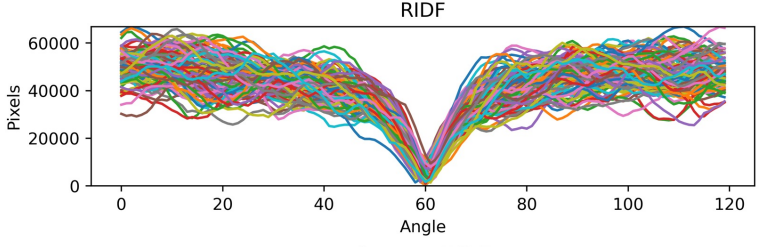
Navigation stats: RMSD error: 37.00; RMSD/dist: 0.093; TD: 29587; p90: 22; p50: 10; complete: 0

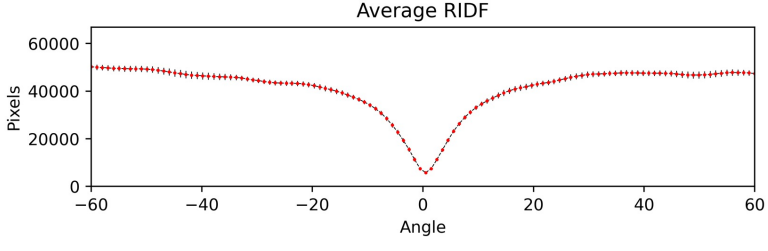
100%







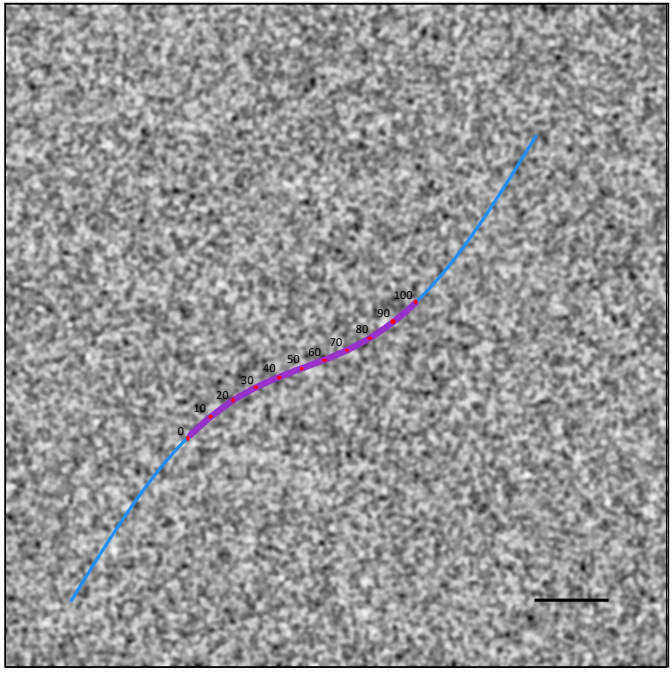


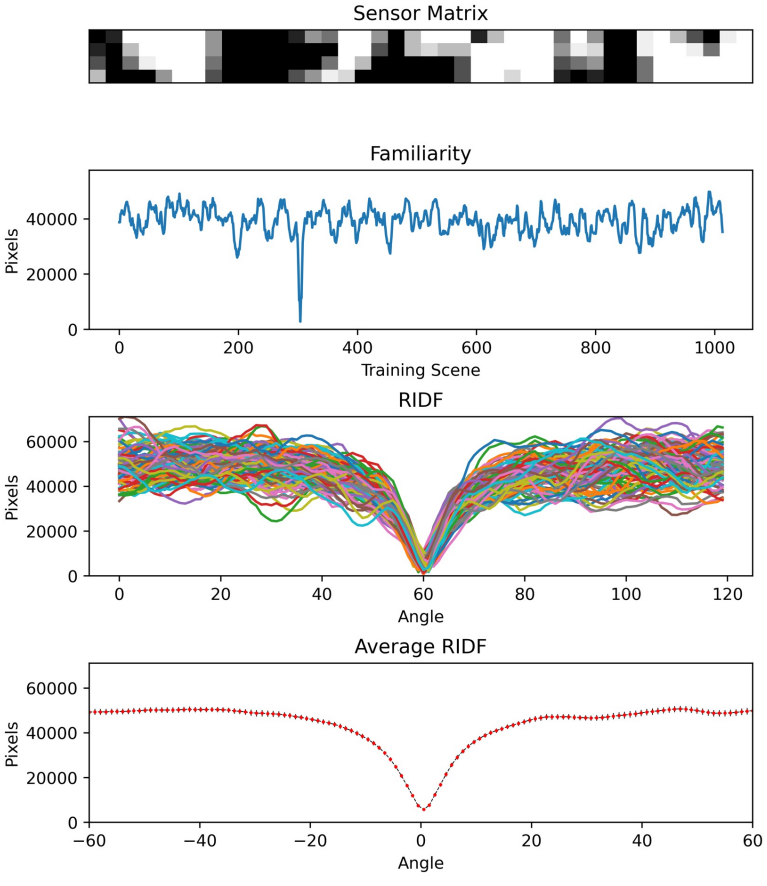


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 56.59; RMSD/dist: 0.141; TD: 32449; p90: 22; p50: 10; complete: 0

100%

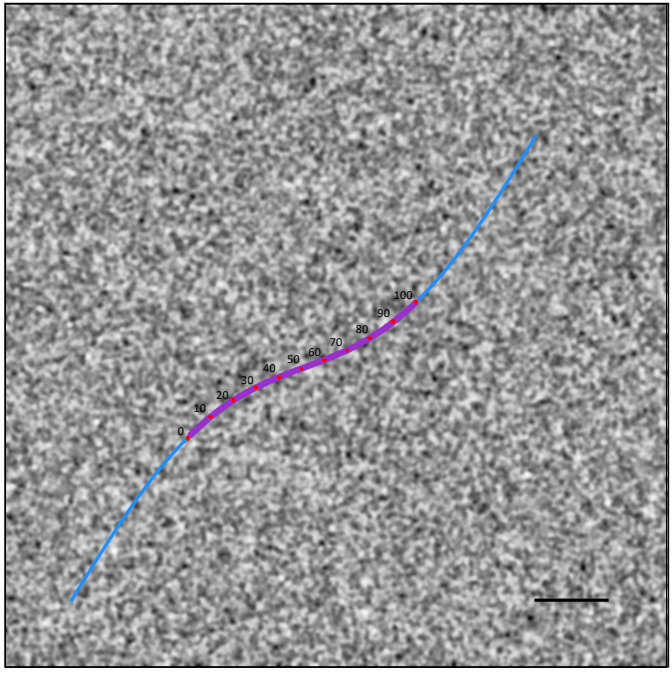


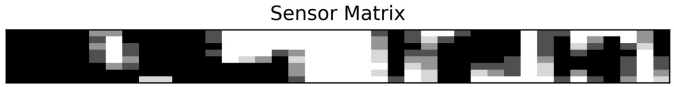


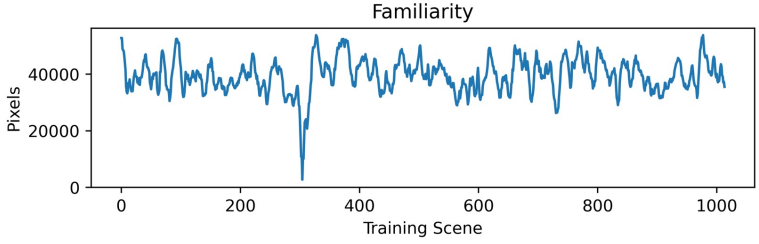
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

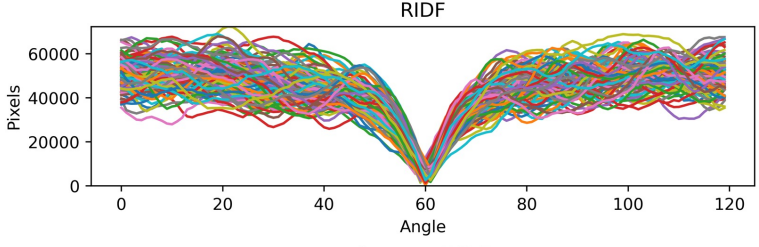
Navigation stats: RMSD error: 51.46; RMSD/dist: 0.129; TD: 33645; p90: 18; p50: 8; complete: 0

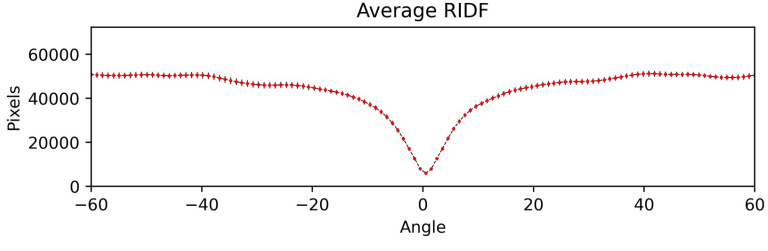
100%







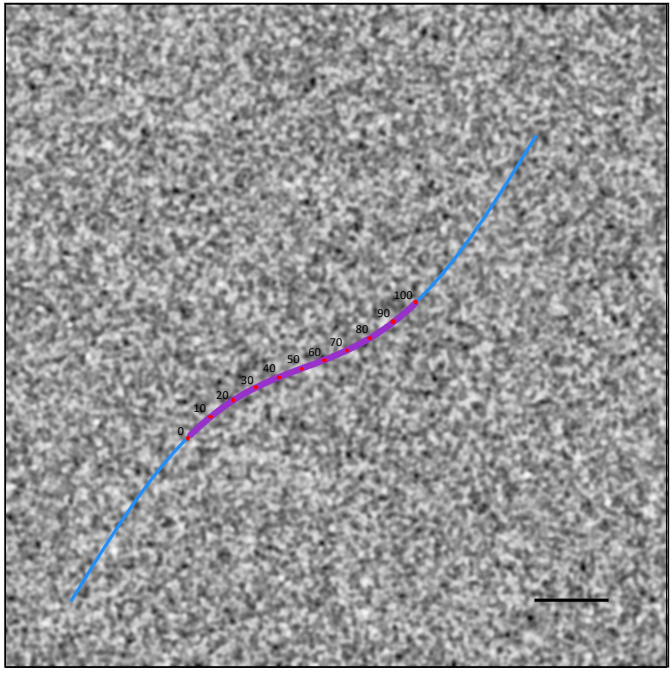


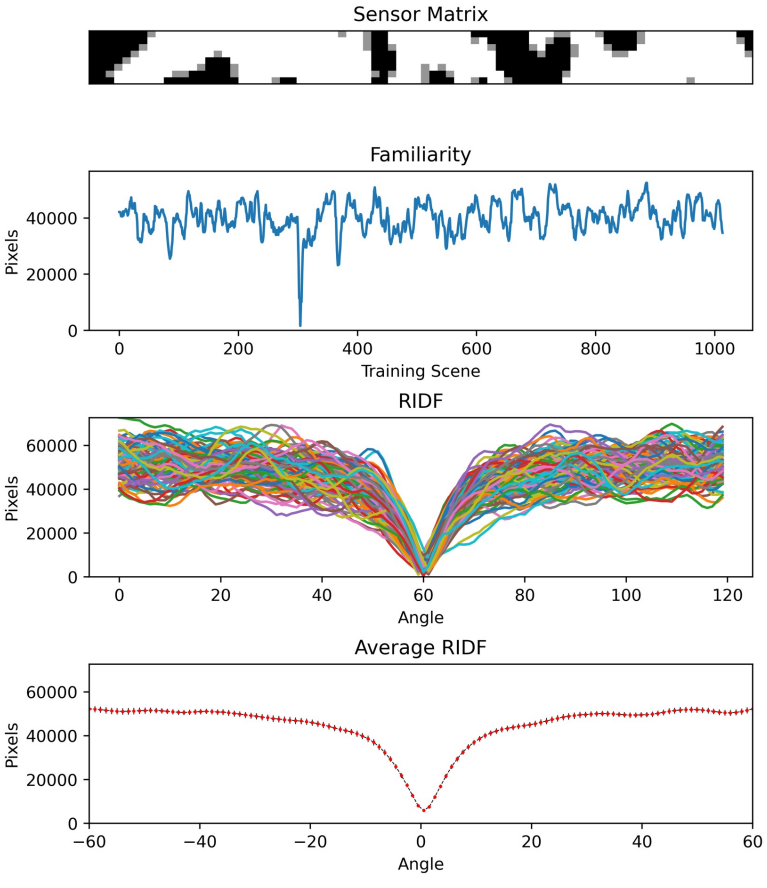


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 49.83; RMSD/dist: 0.125; TD: 33997; p90: 20; p50: 8; complete: 0

100%

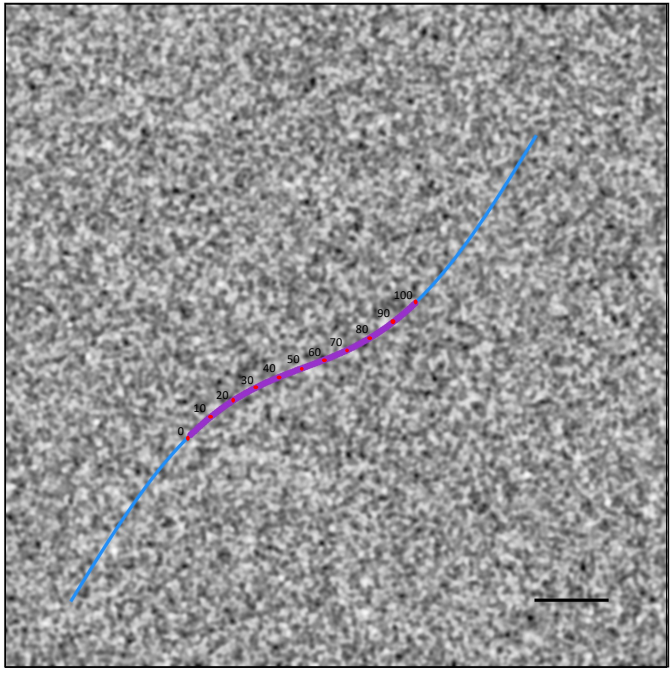


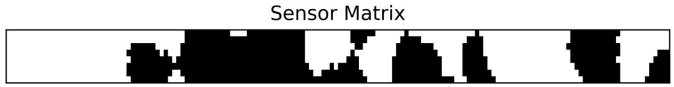


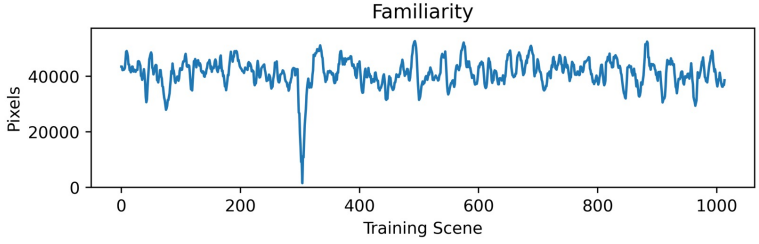
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

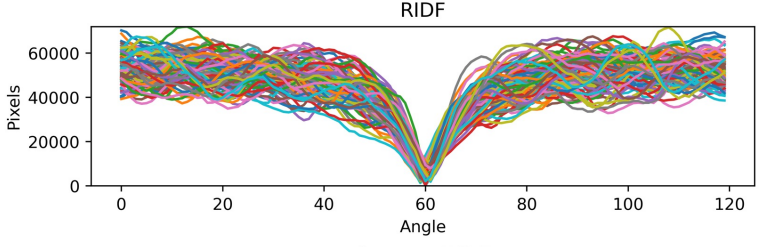
Navigation stats: RMSD error: 47.61; RMSD/dist: 0.119; TD: 34991; p90: 18; p50: 8; complete: 0

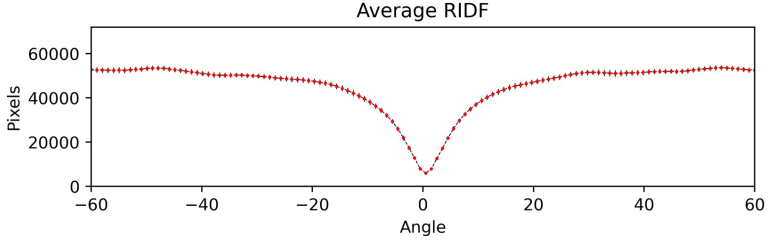
100%





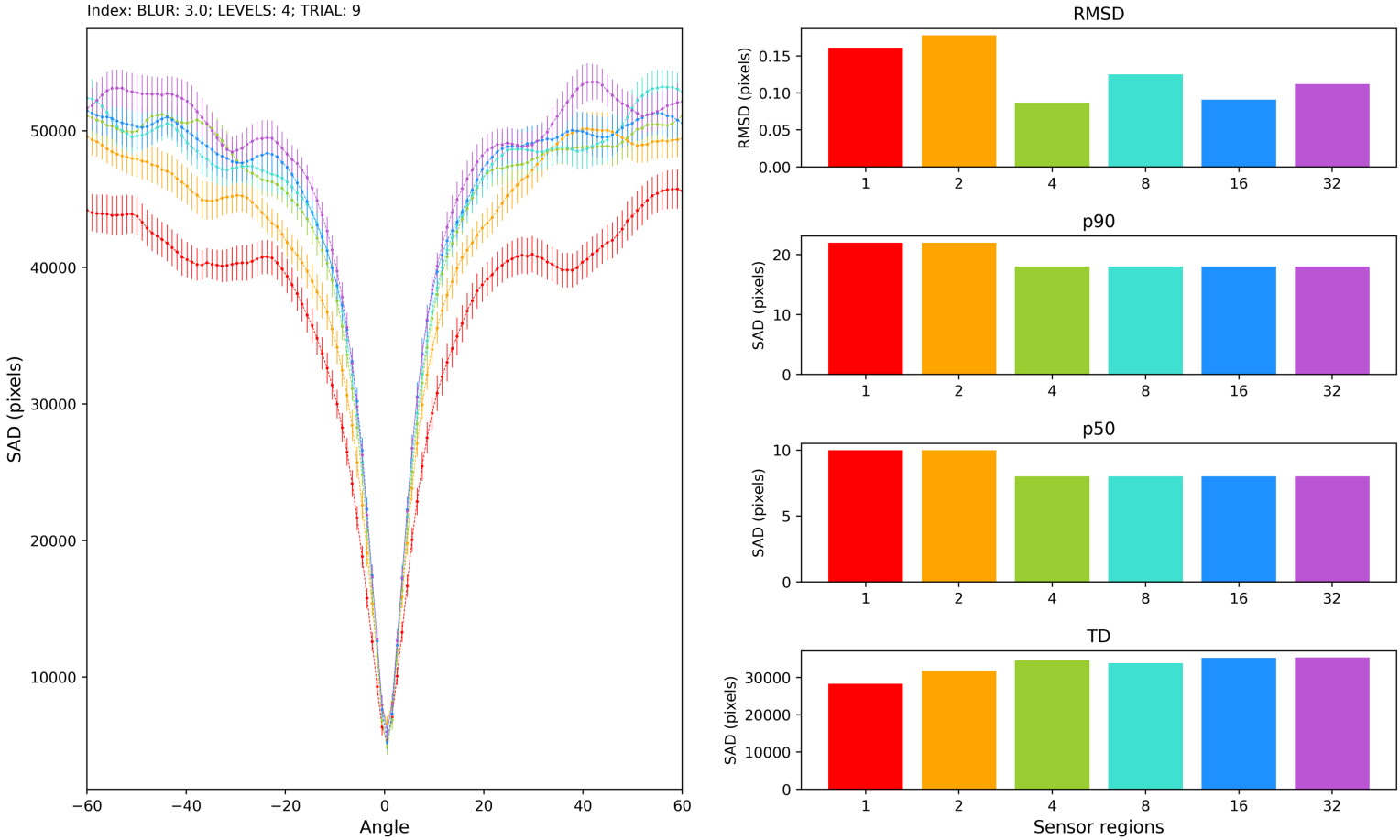




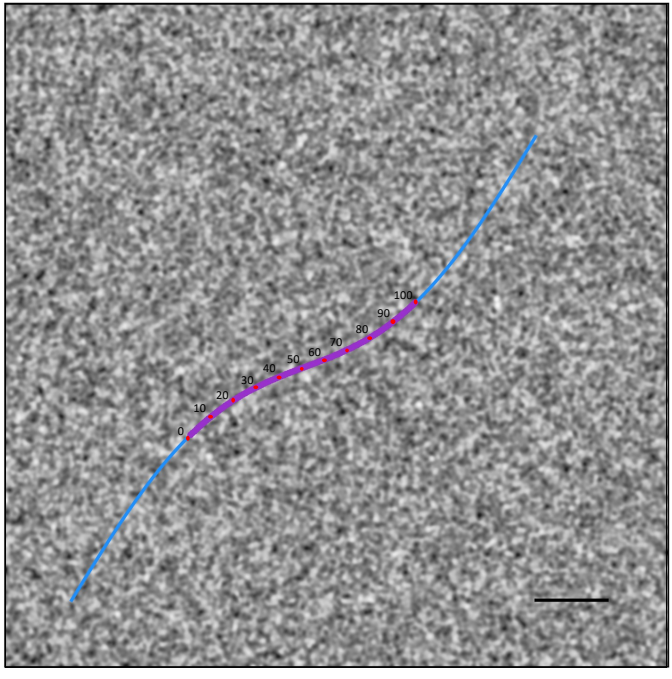


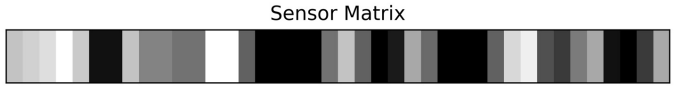
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

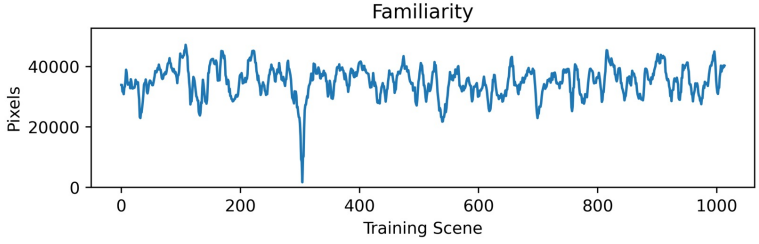
Navigation stats: RMSD error: 42.91; RMSD/dist: 0.107; TD: 35617; p90: 20; p50: 8; complete: 0

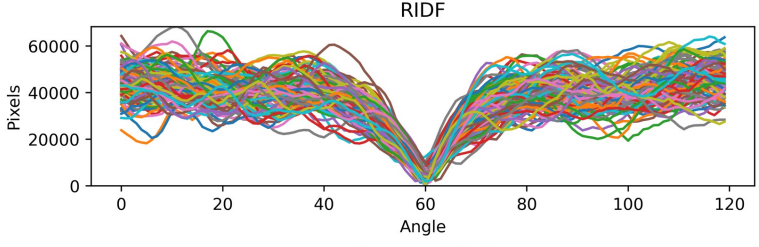

Index: BLUR: 3.0; LEVELS: 4; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

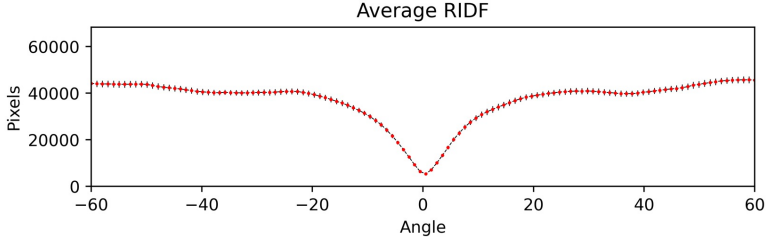
100%







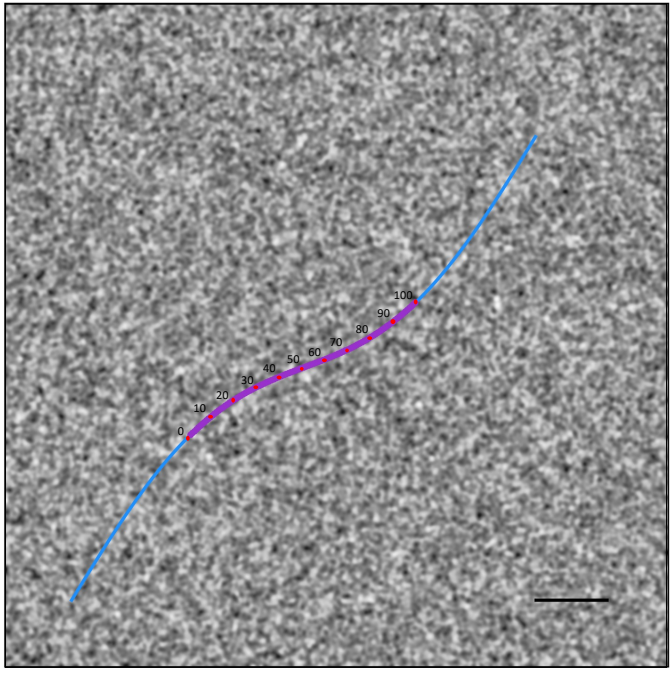


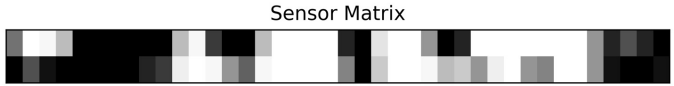


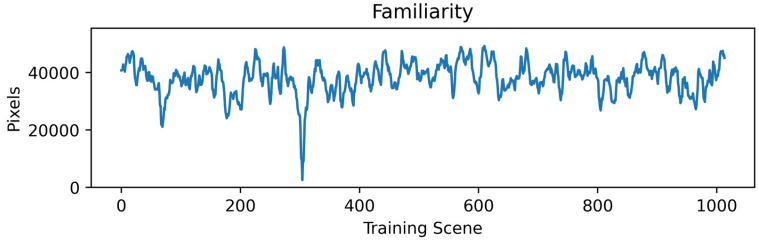
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

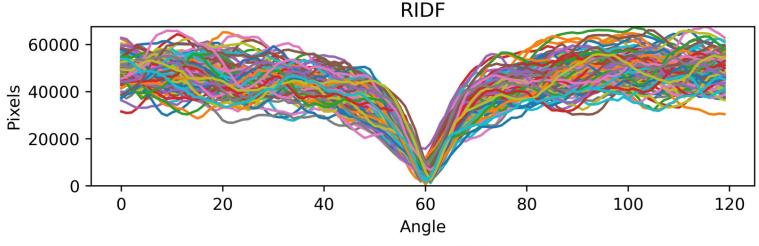
Navigation stats: RMSD error: 64.37; RMSD/dist: 0.161; TD: 28277; p90: 22; p50: 10; complete: 0

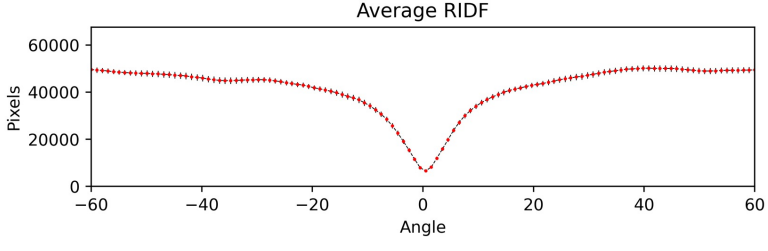
100%







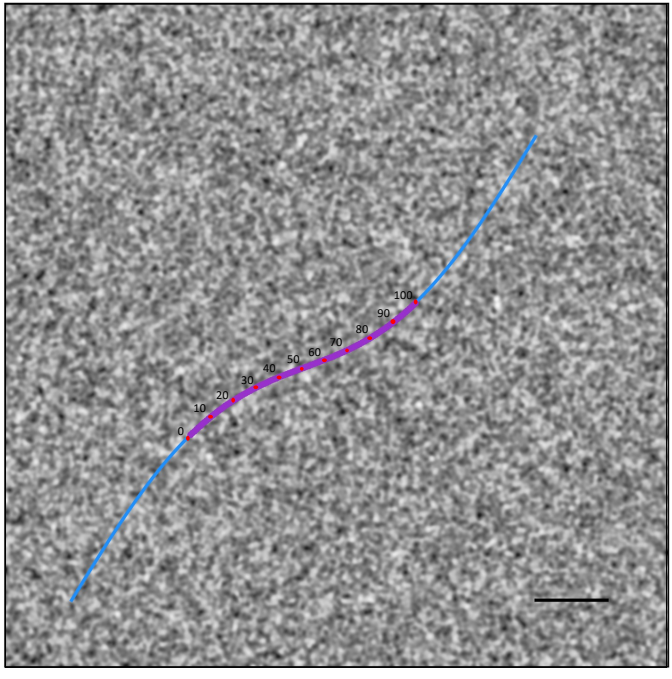


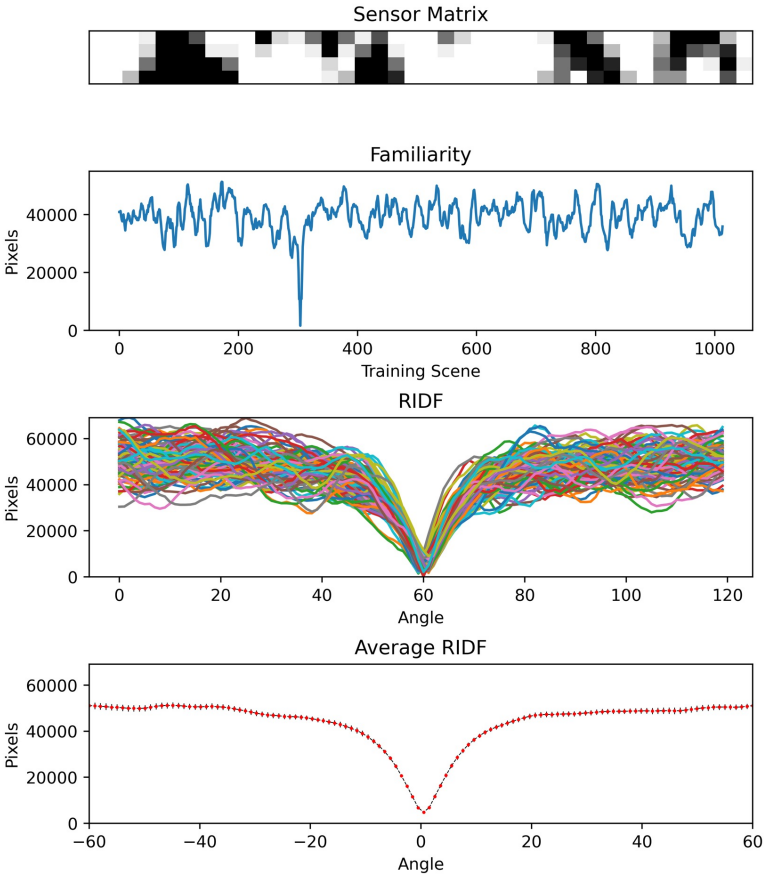


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 71.09; RMSD/dist: 0.178; TD: 31776; p90: 22; p50: 10; complete: 0

100%

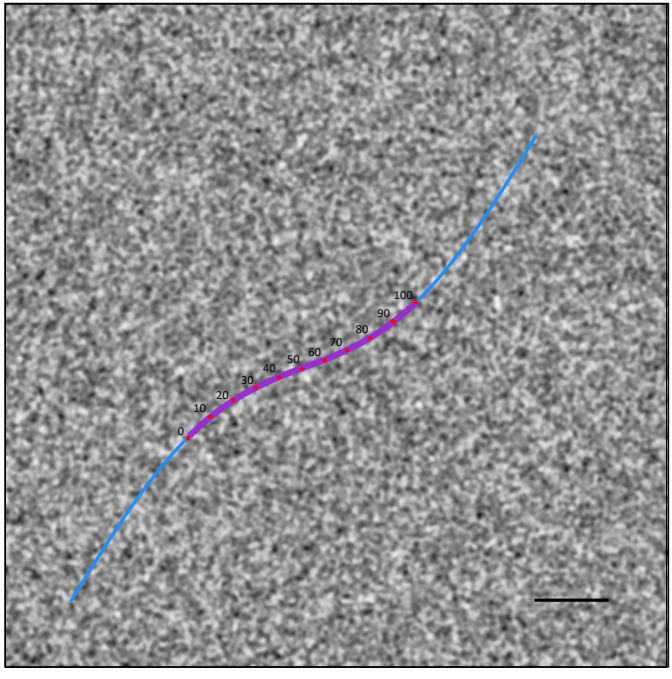


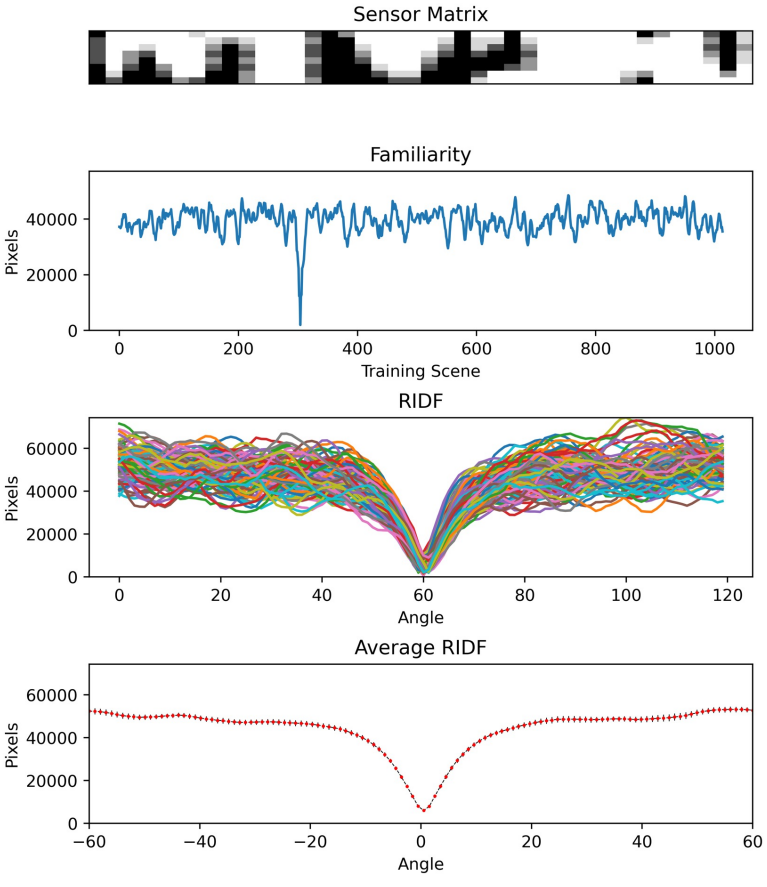


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 34.75; RMSD/dist: 0.087; TD: 34629; p90: 18; p50: 8; complete: 0

100%

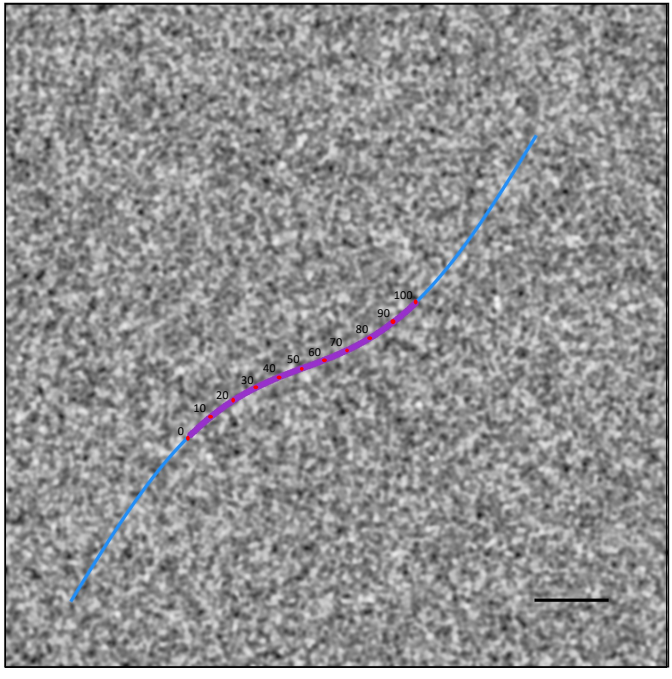


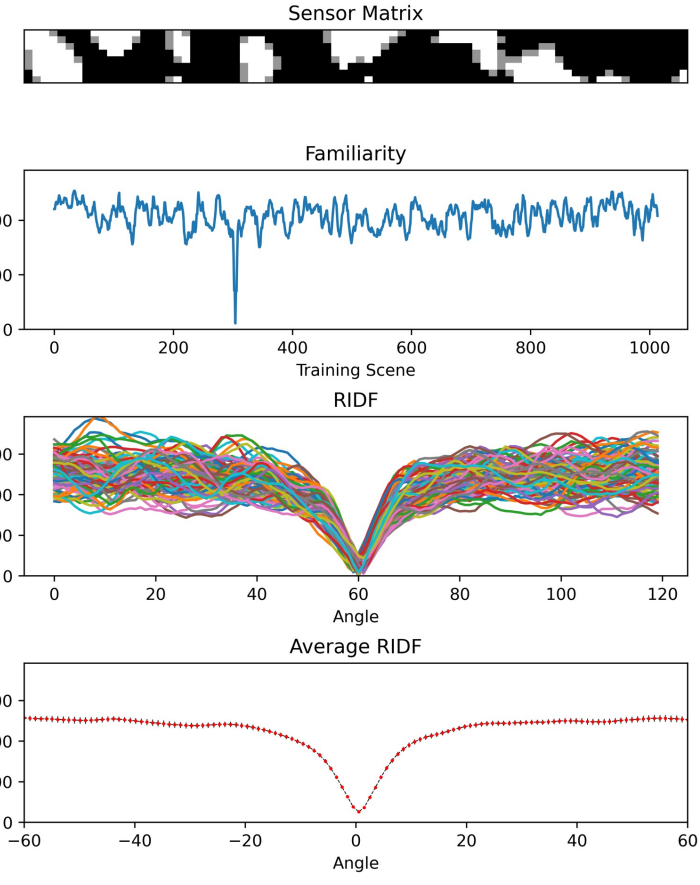


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 50.07; RMSD/dist: 0.125; TD: 33853; p90: 18; p50: 8; complete: 0

100%

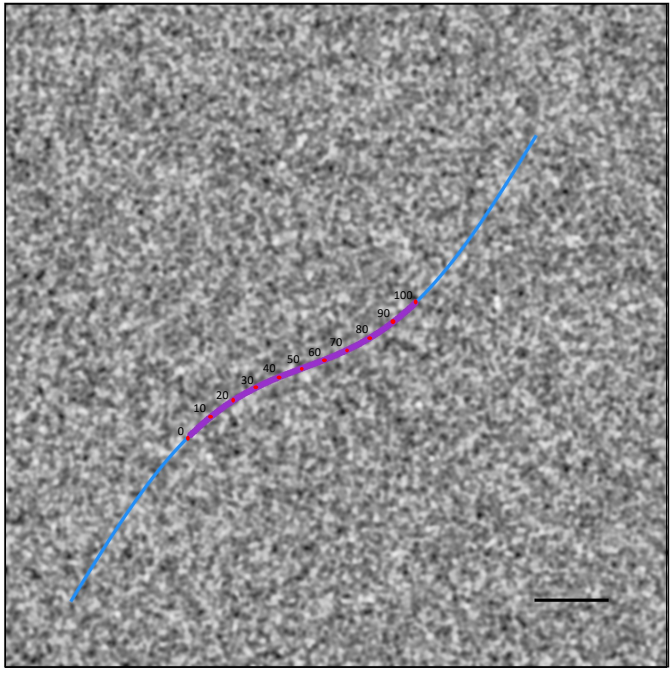


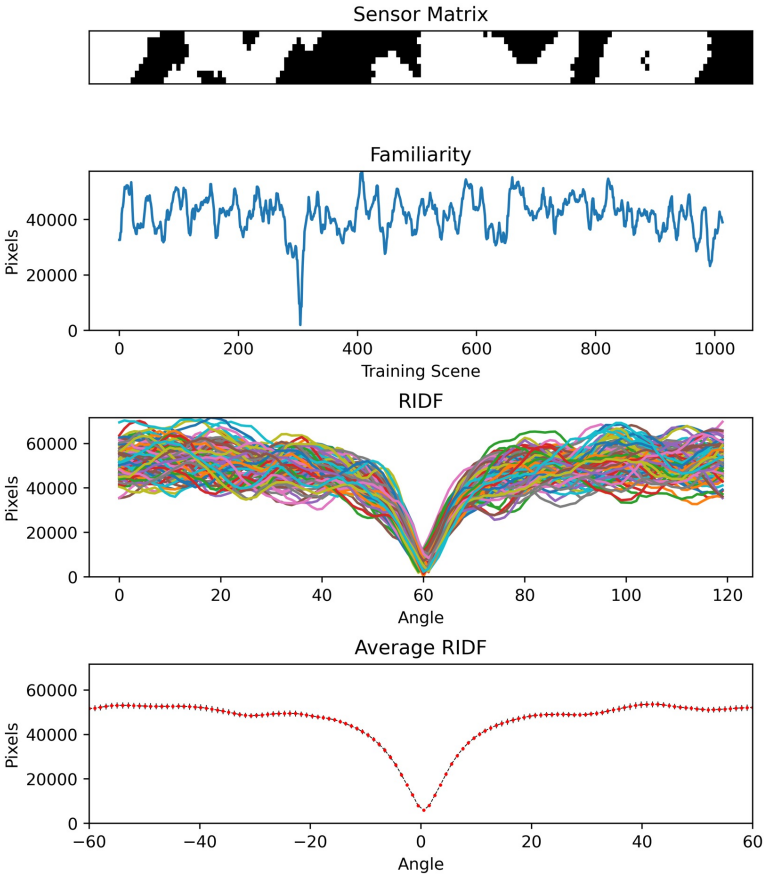


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 36.38; RMSD/dist: 0.091; TD: 35290; p90: 18; p50: 8; complete: 0

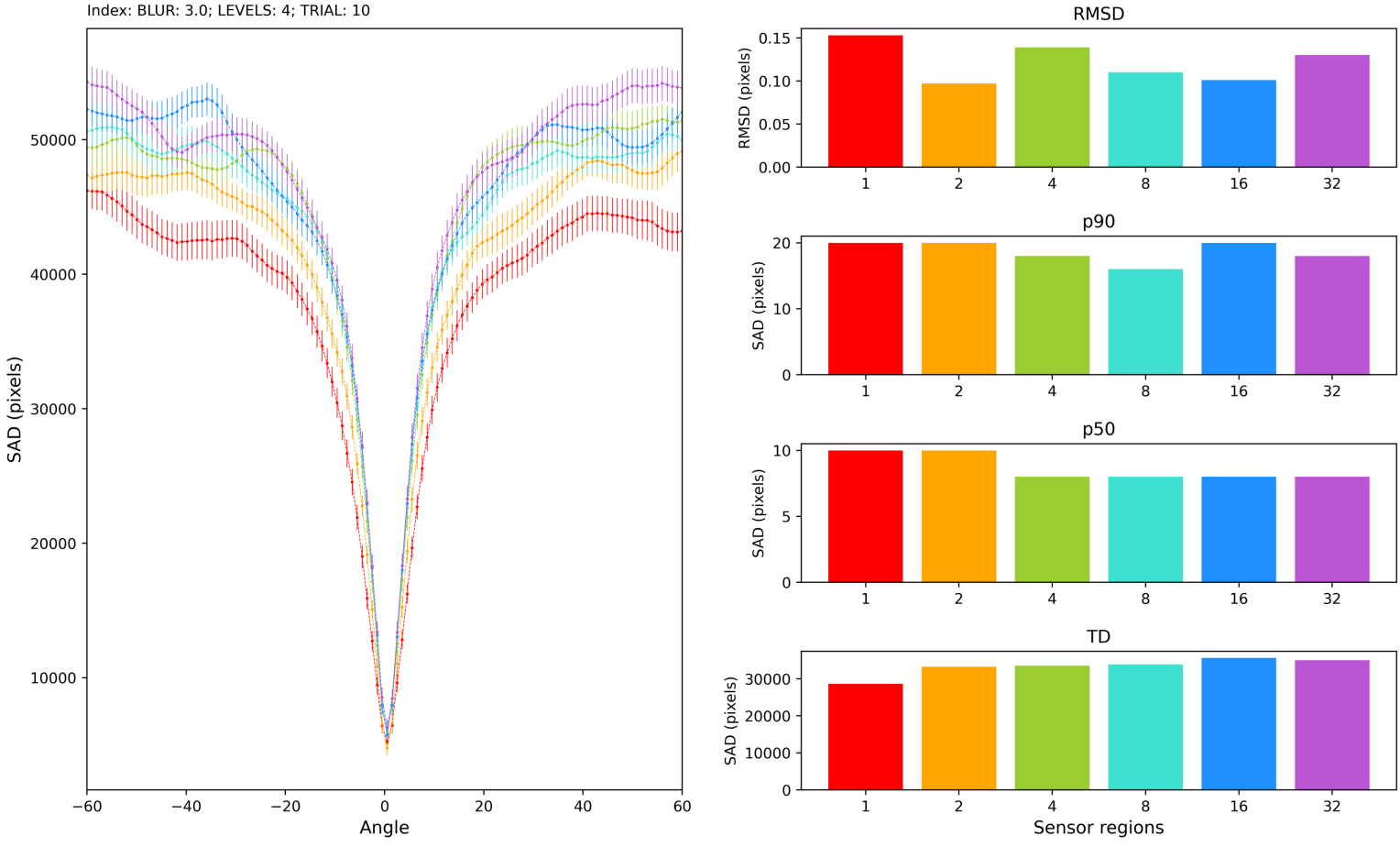
100%



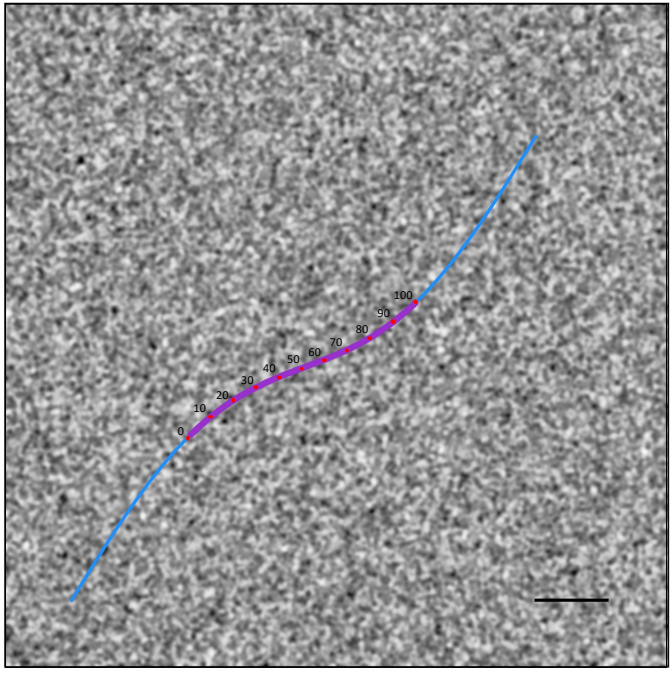


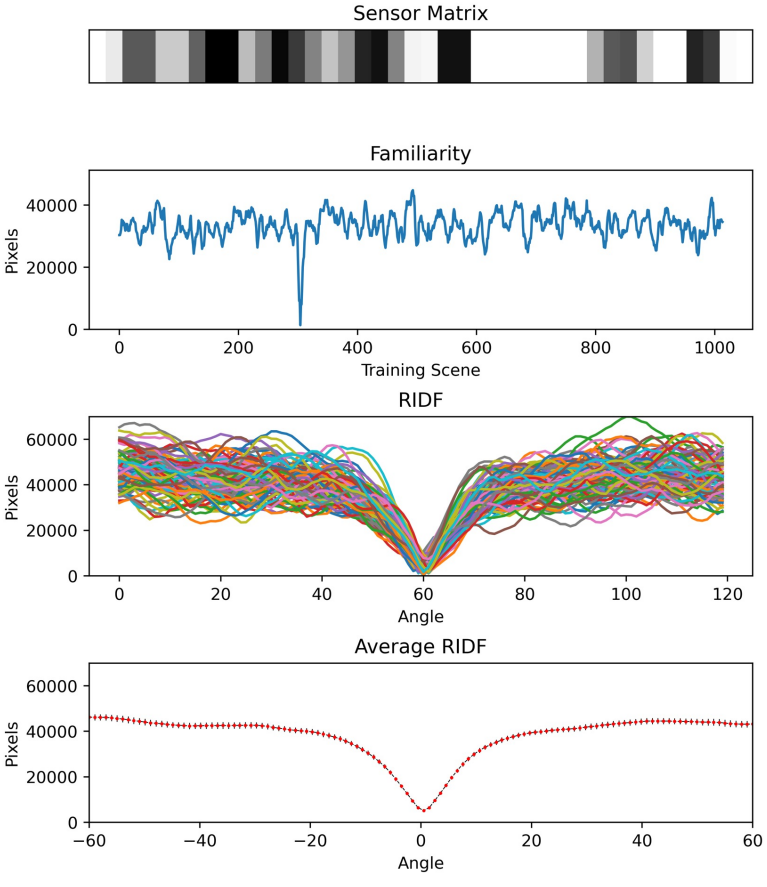
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 44.88; RMSD/dist: 0.112; TD: 35357; p90: 18; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 4; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

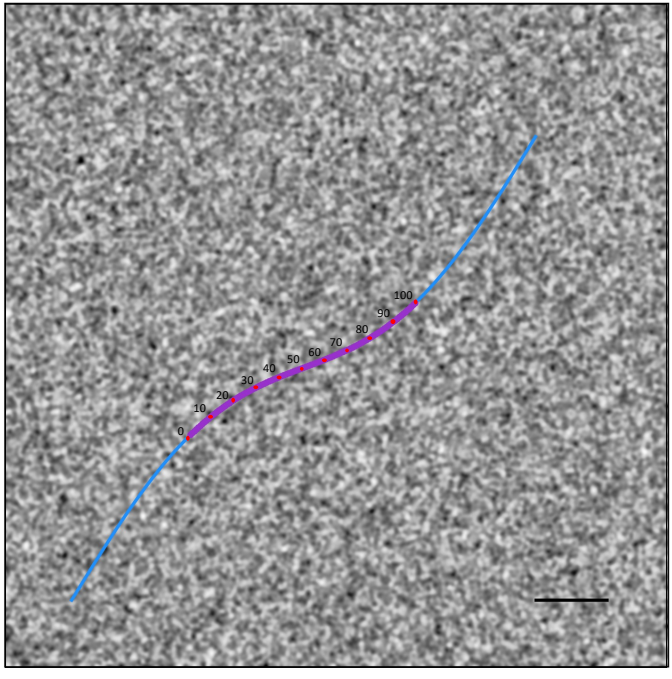


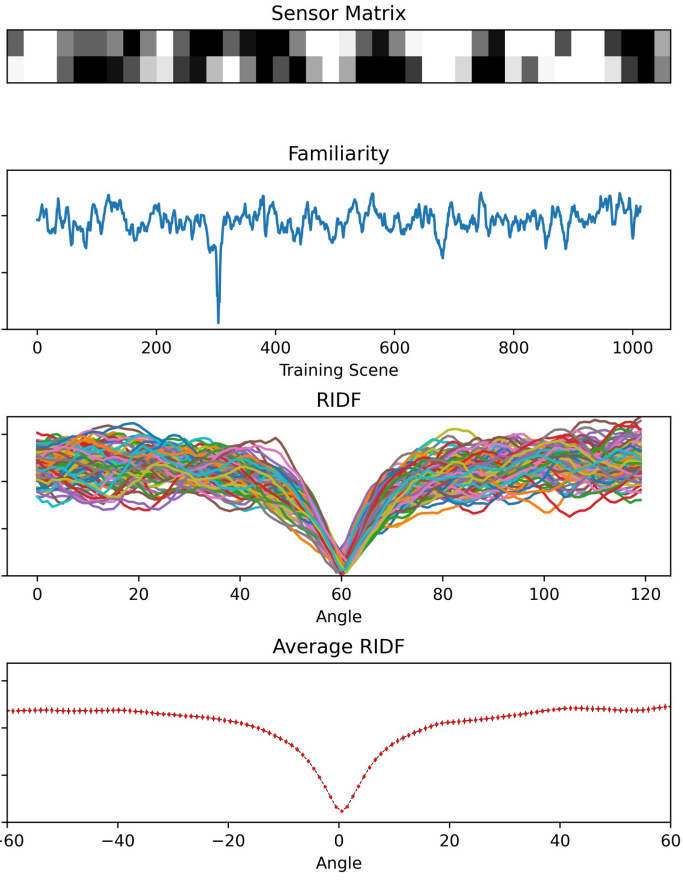


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 61.39; RMSD/dist: 0.153; TD: 28676; p90: 20; p50: 10; complete: 0

100%

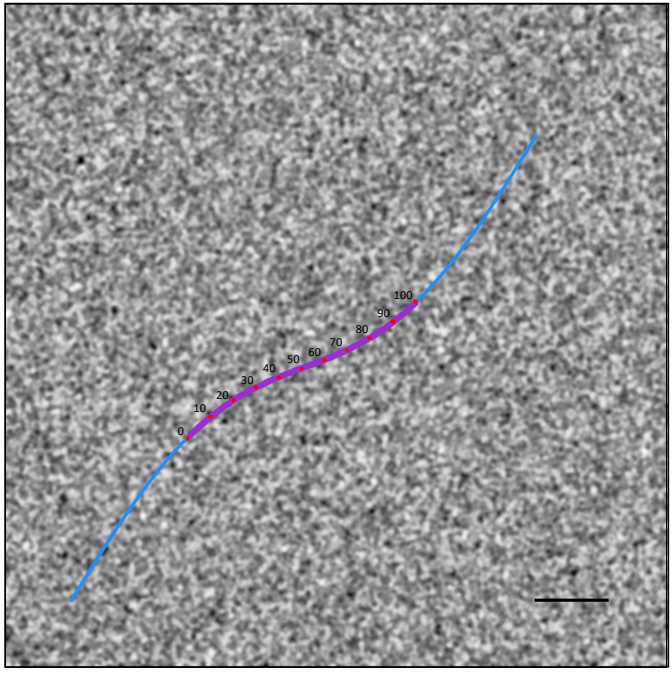


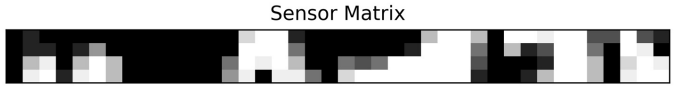


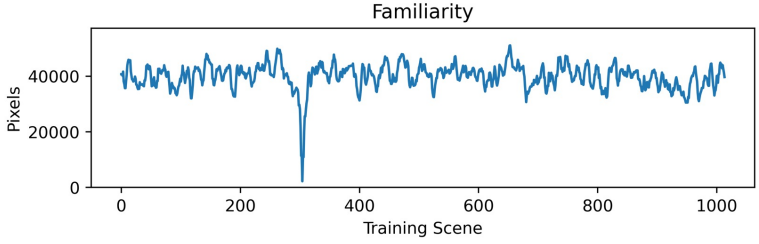
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

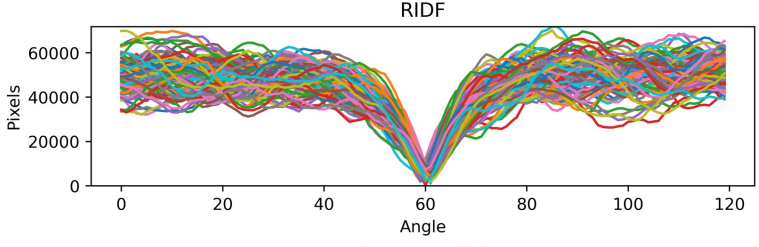
Navigation stats: RMSD error: 38.71; RMSD/dist: 0.097; TD: 33264; p90: 20; p50: 10; complete: 0

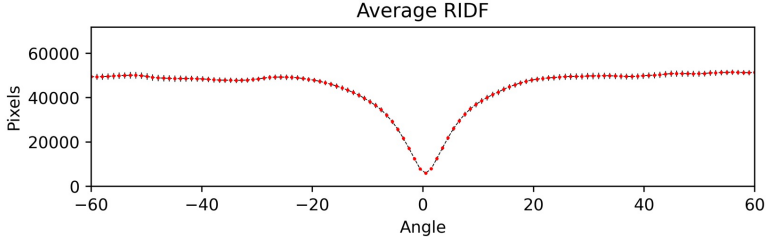
100%







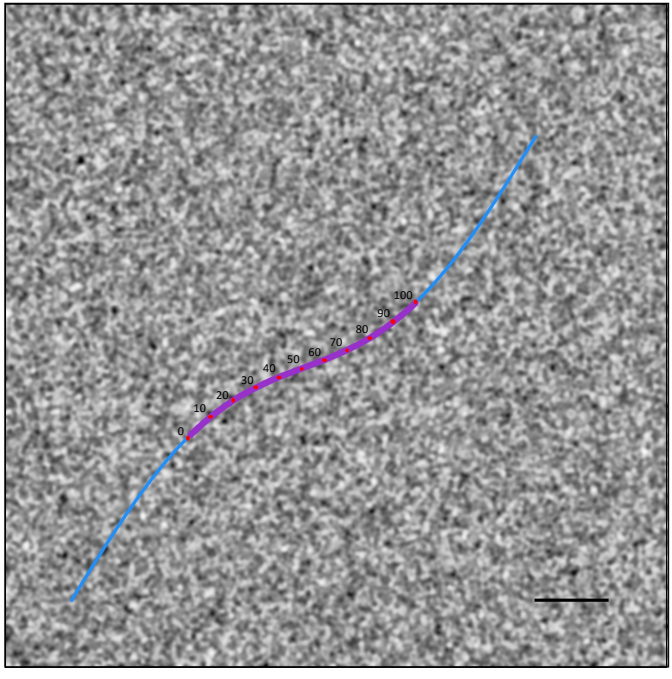


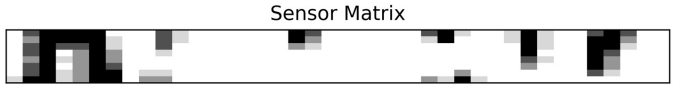


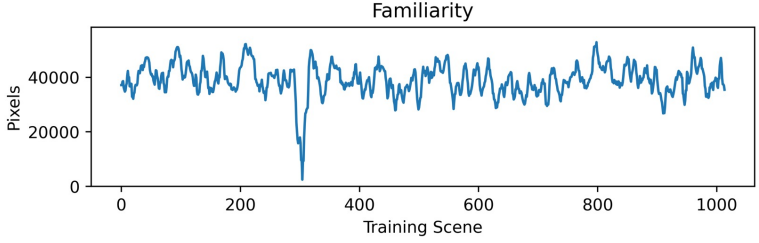
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

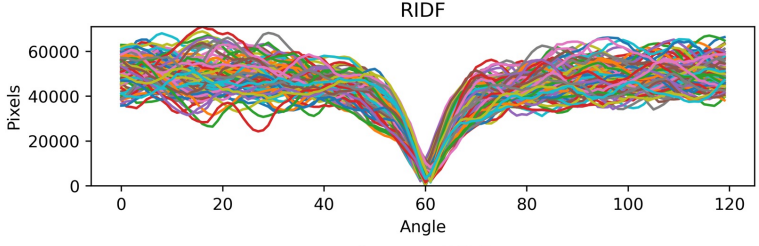
Navigation stats: RMSD error: 55.79; RMSD/dist: 0.139; TD: 33554; p90: 18; p50: 8; complete: 0

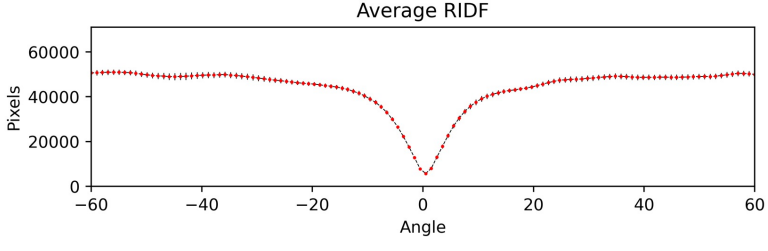
100%







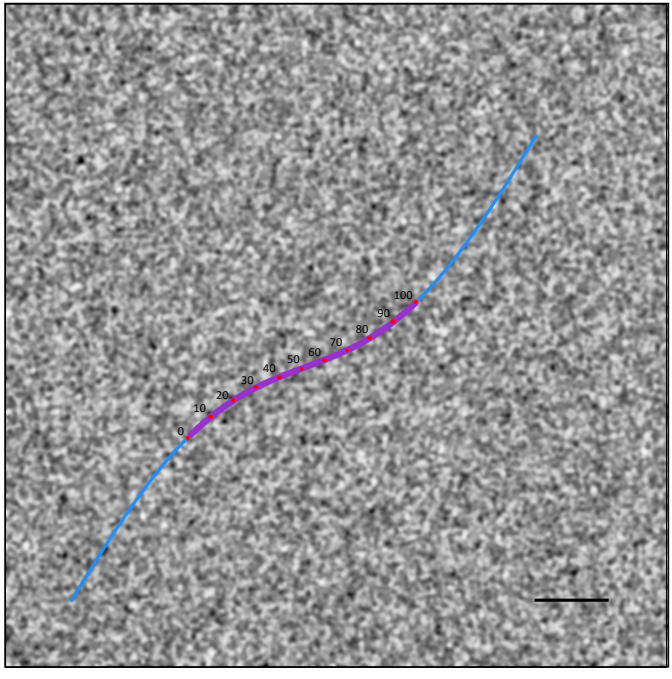


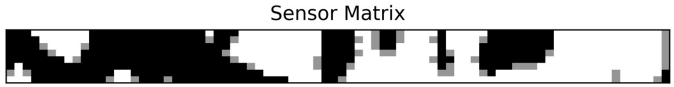


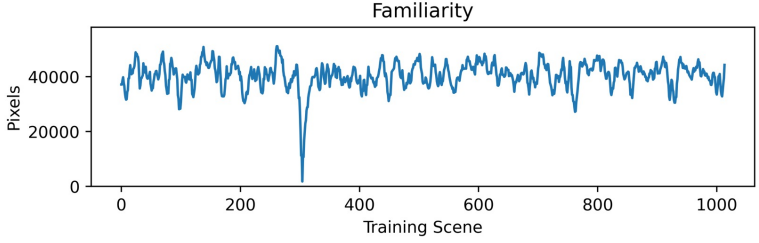
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

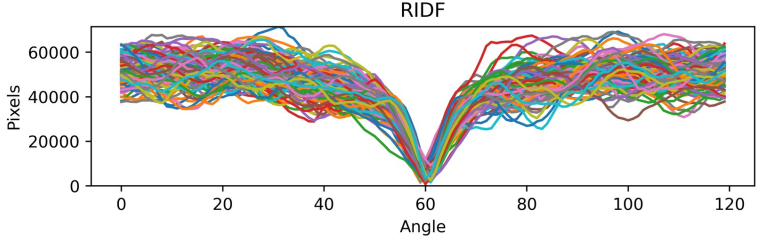
Navigation stats: RMSD error: 44.17; RMSD/dist: 0.110; TD: 33924; p90: 16; p50: 8; complete: 0

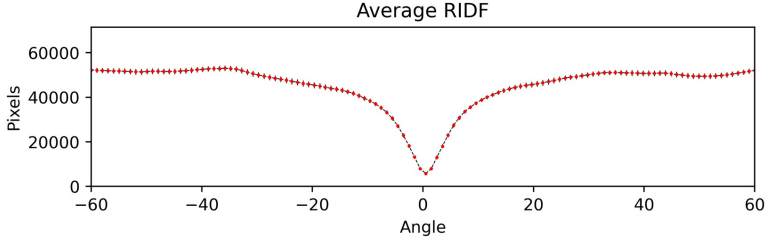
100%







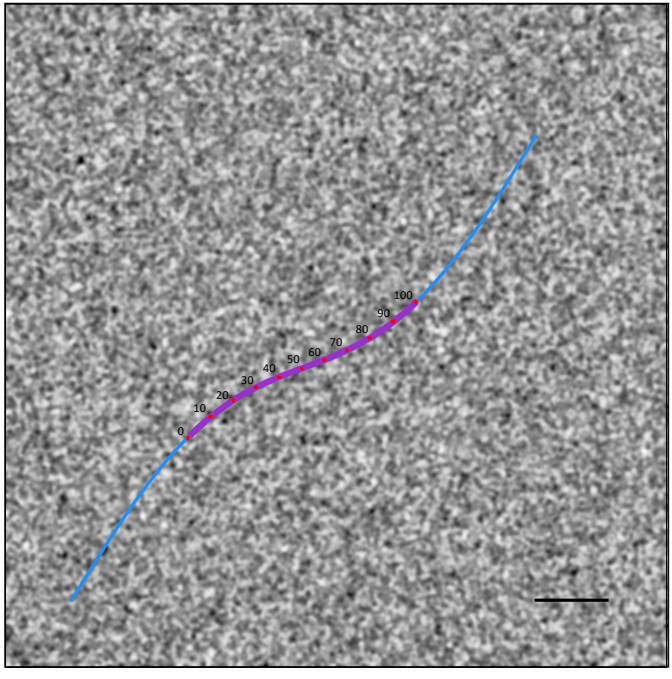


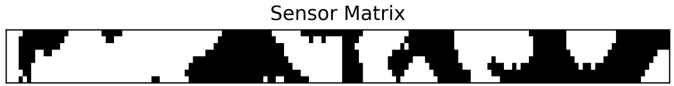


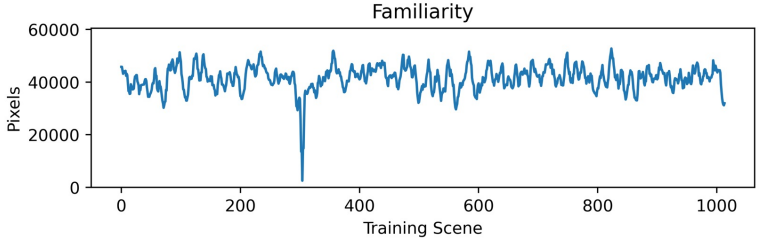
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

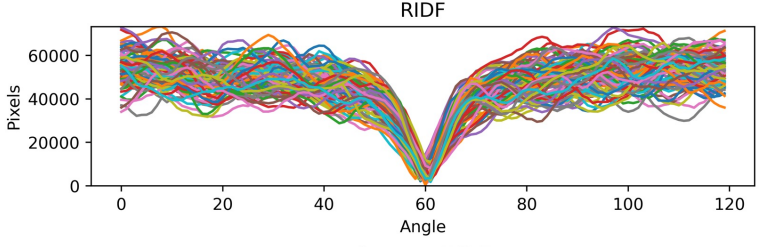
Navigation stats: RMSD error: 40.24; RMSD/dist: 0.101; TD: 35648; p90: 20; p50: 8; complete: 0

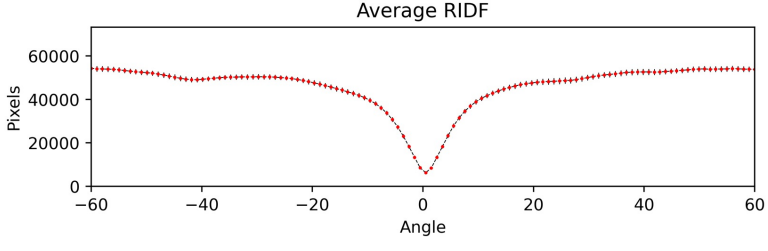
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 4; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 52.17; RMSD/dist: 0.130; TD: 35049; p90: 18; p50: 8; complete: 0