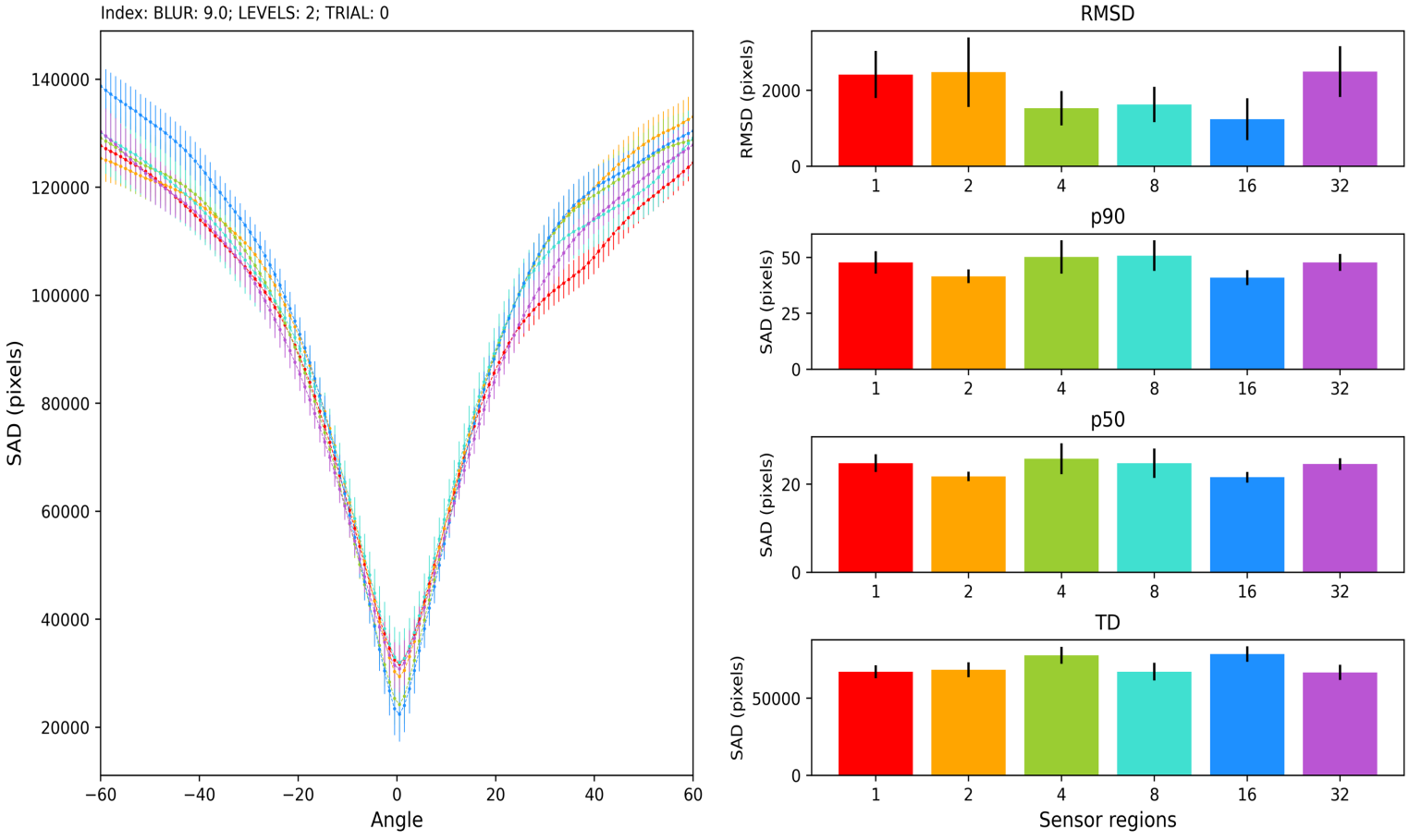
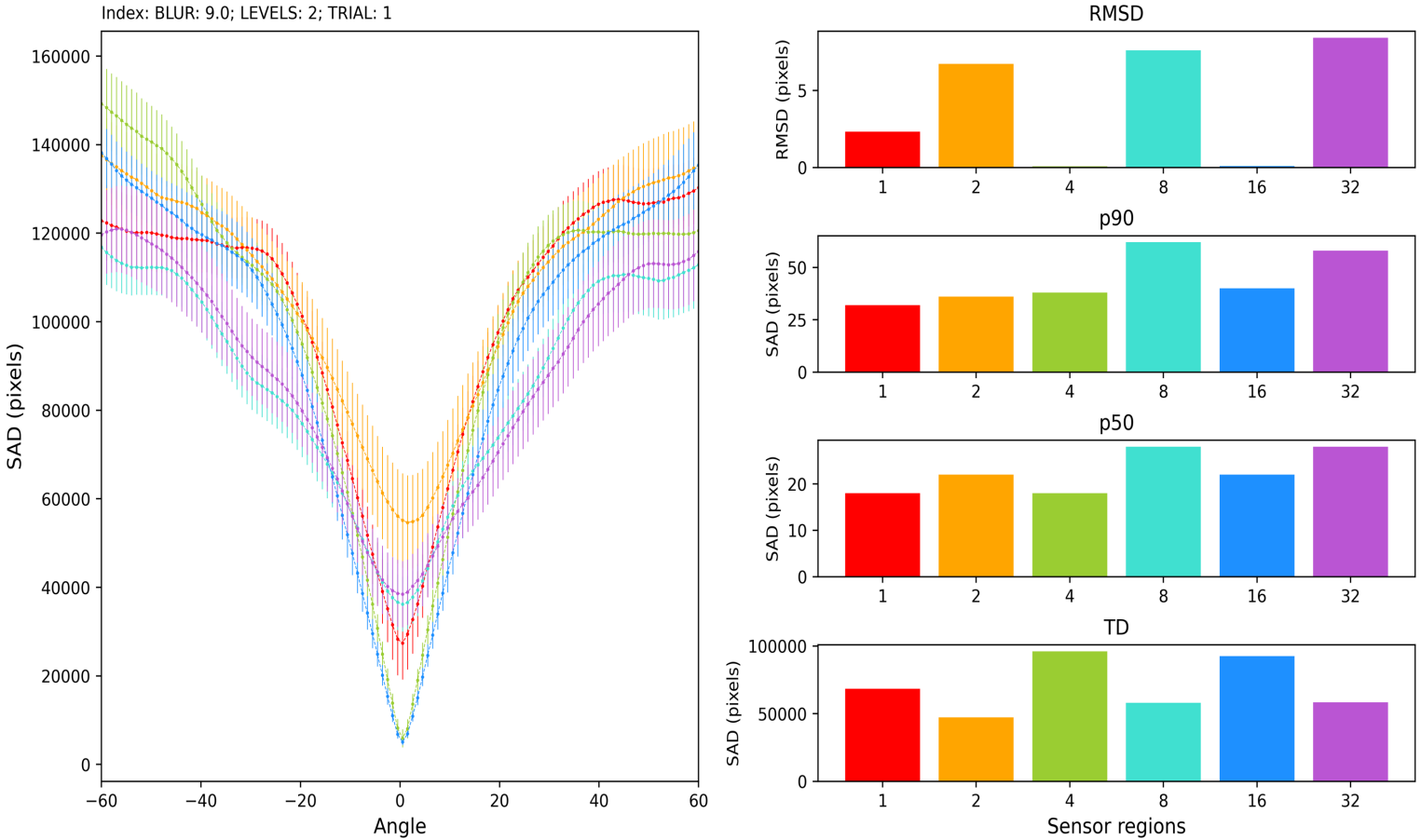
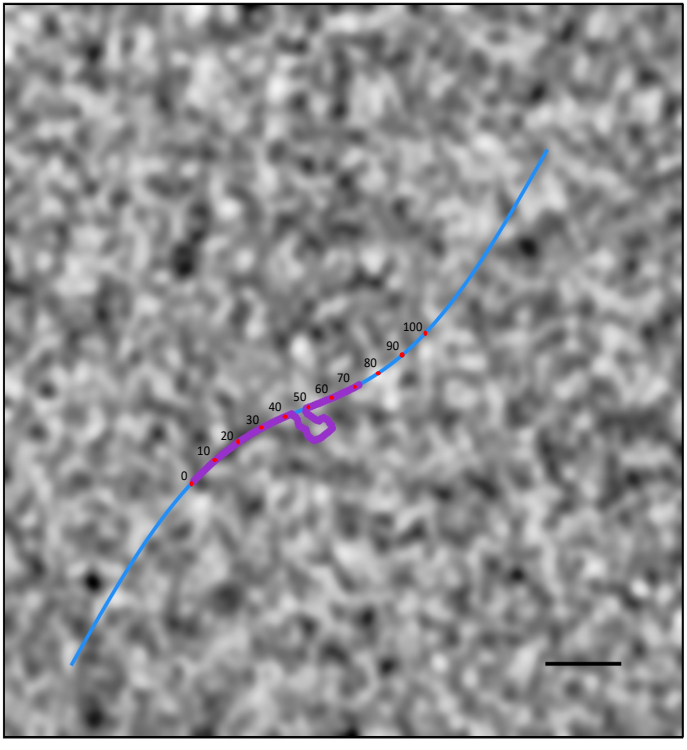
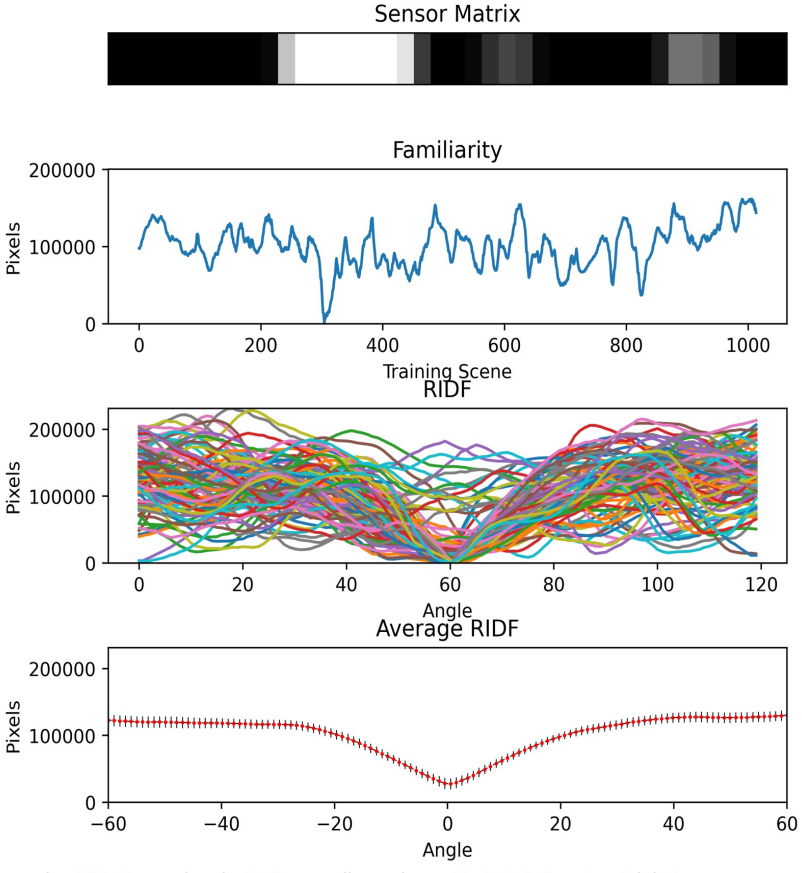

Index: BLUR: 9.0; LEVELS: 2; TRIAL: 0
SAD (pixels)
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
2000
0
1
2
4
8
16
32
p90
SAD (pixels)
50
25
0
p50
20
TD
50000
Sensor regions


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

50%

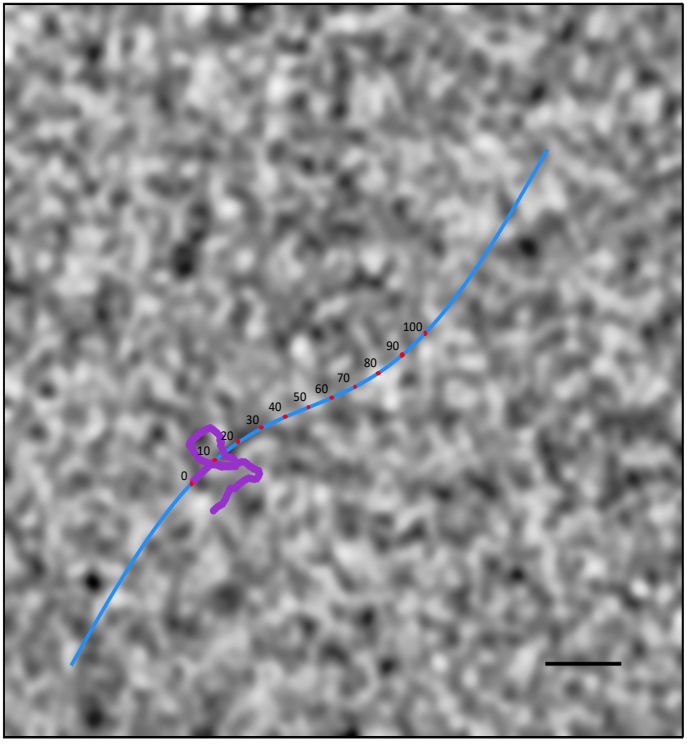


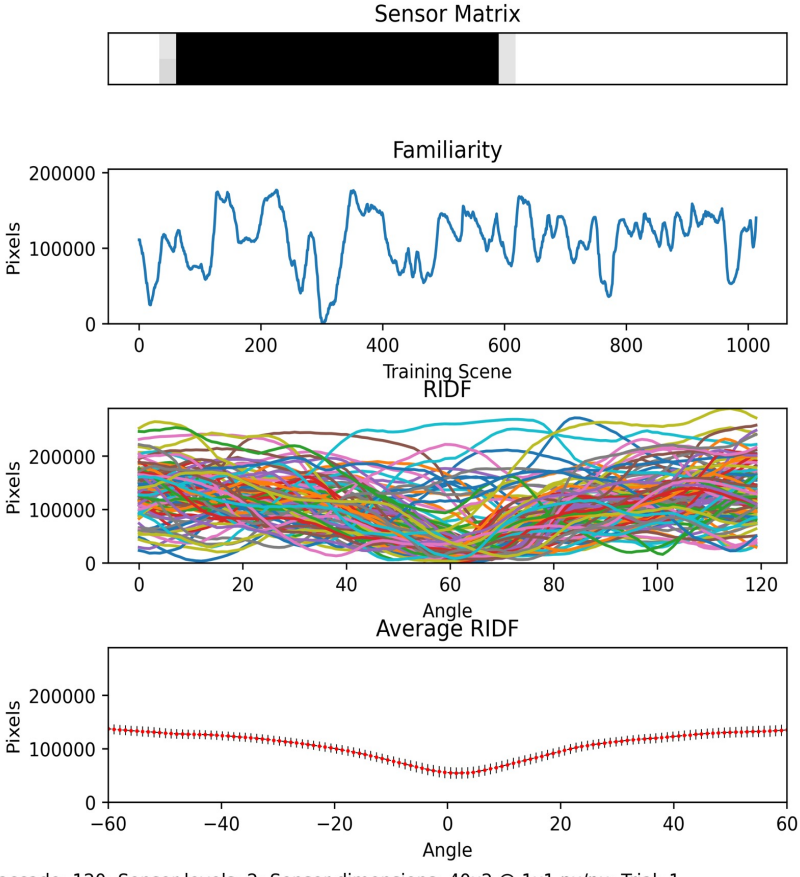


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 933.36; RMSD/dist: 2.333; TD: 68370; p90: 32; p50: 18; complete: 0

10%

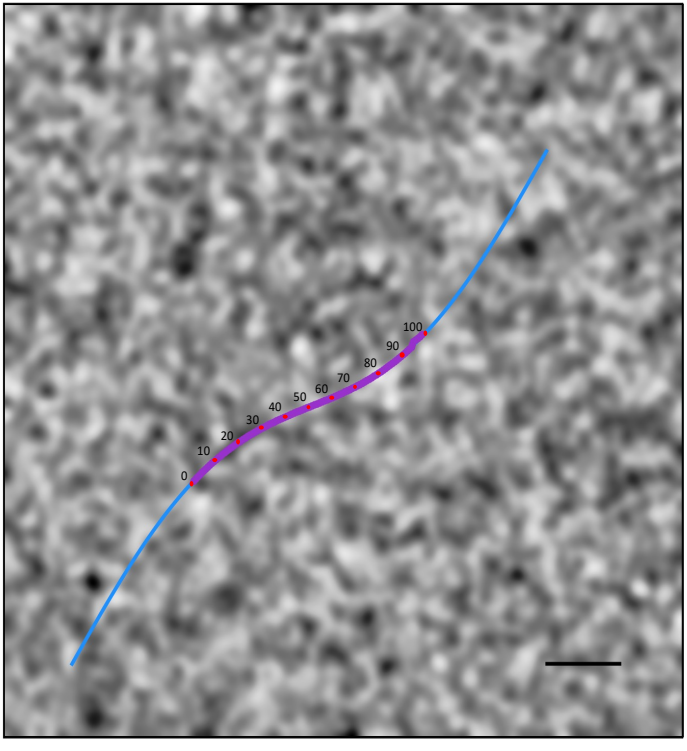


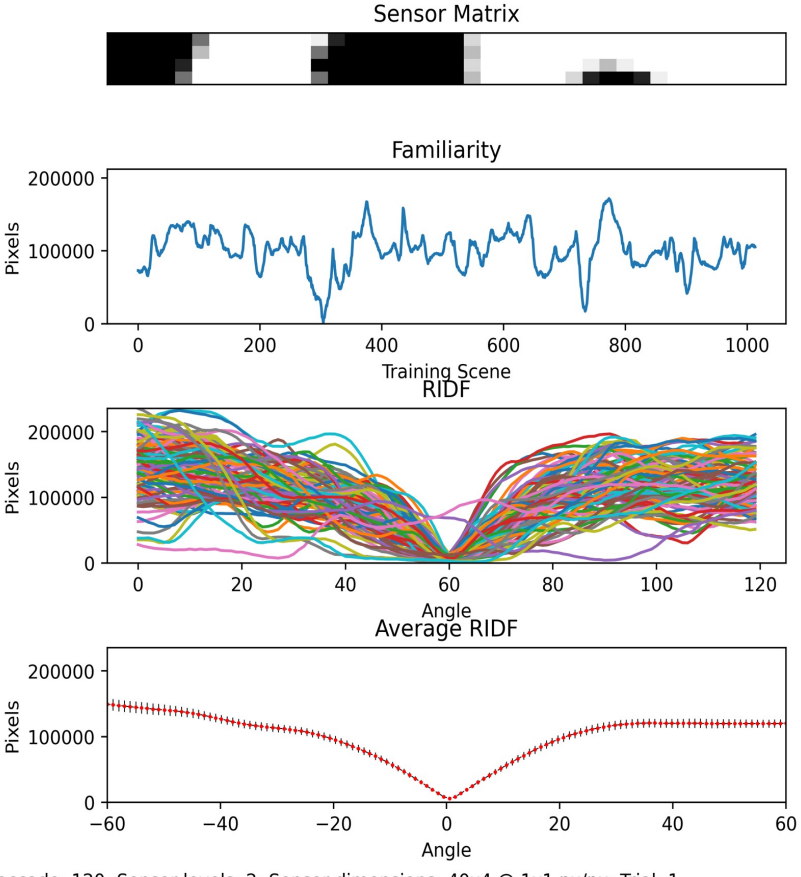


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2685.05; RMSD/dist: 6.713; TD: 47207; p90: 36; p50: 22; complete: 0

90%

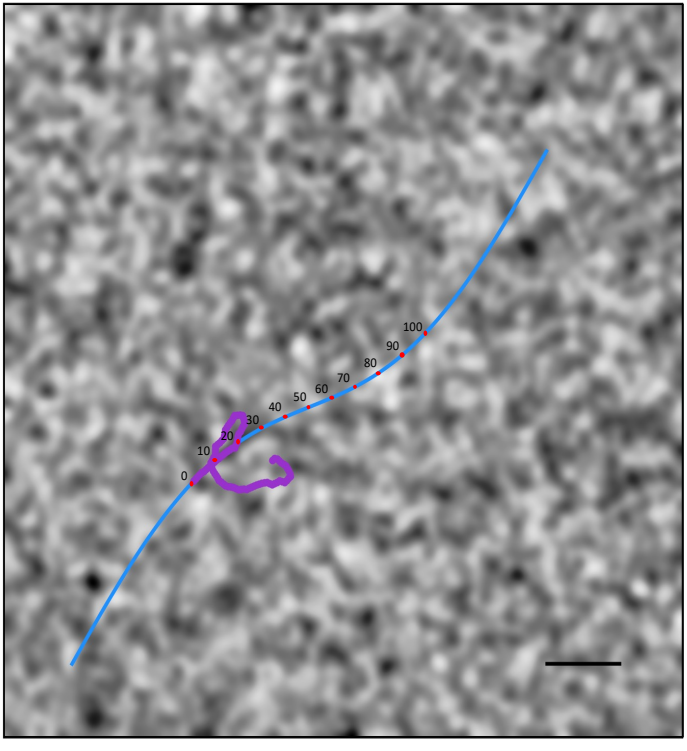


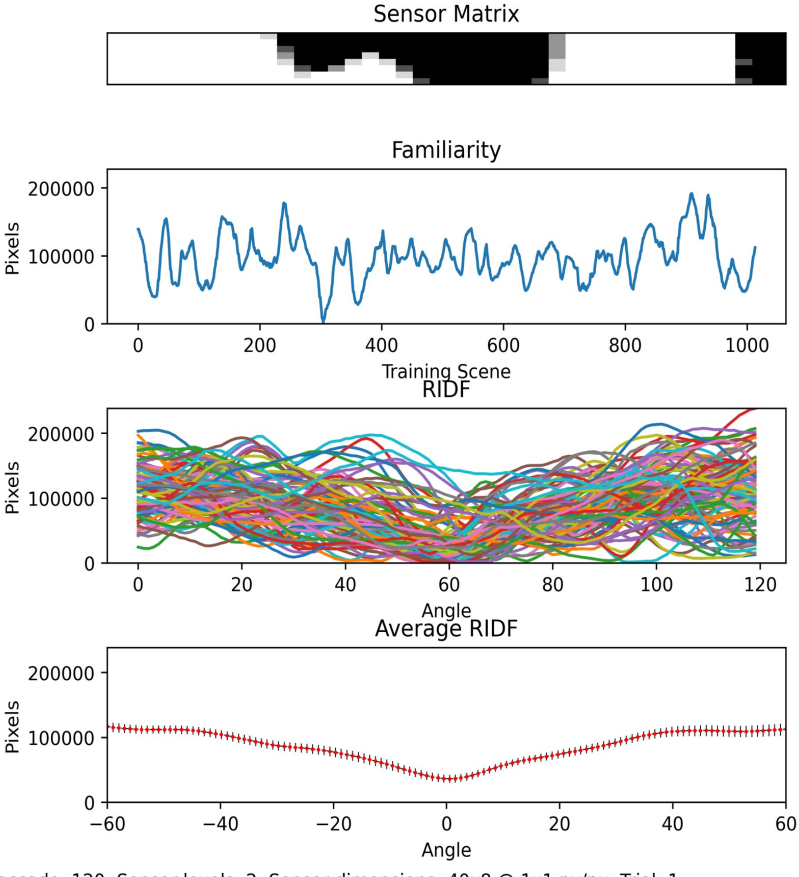


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 35.23; RMSD/dist: 0.088; TD: 95972; p90: 38; p50: 18; complete: 0

20%

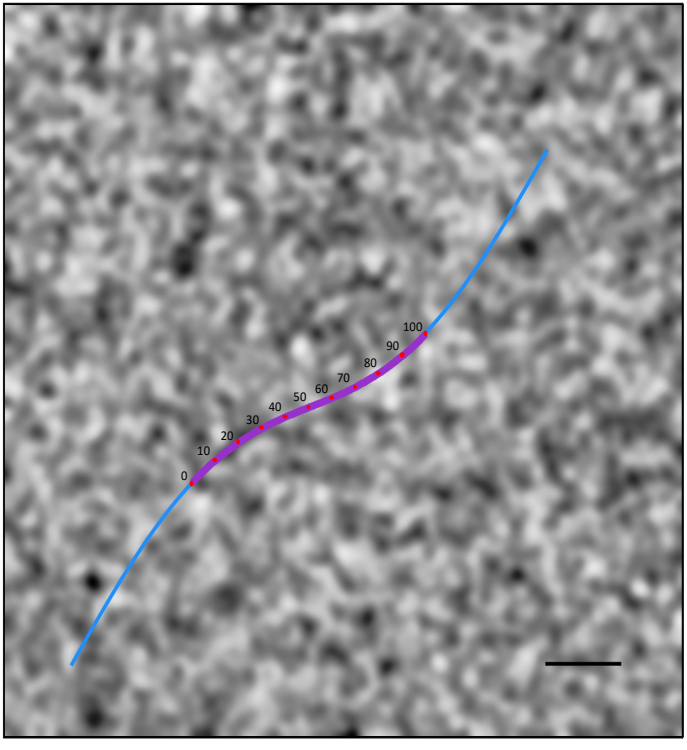


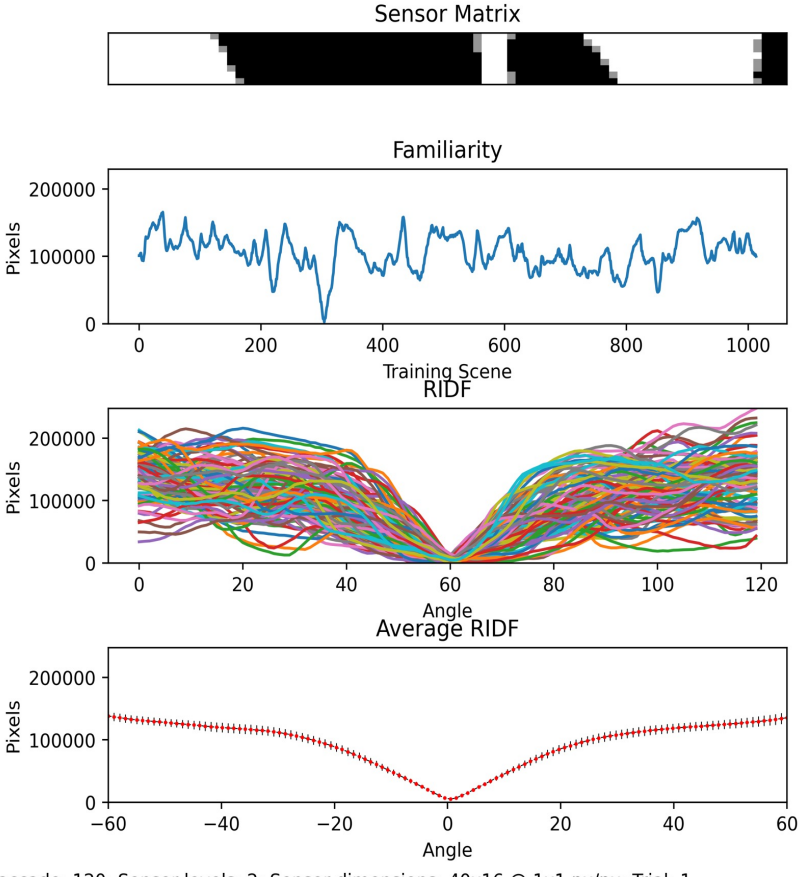


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3039.52; RMSD/dist: 7.599; TD: 58060; p90: 62; p50: 28; complete: 0

100%

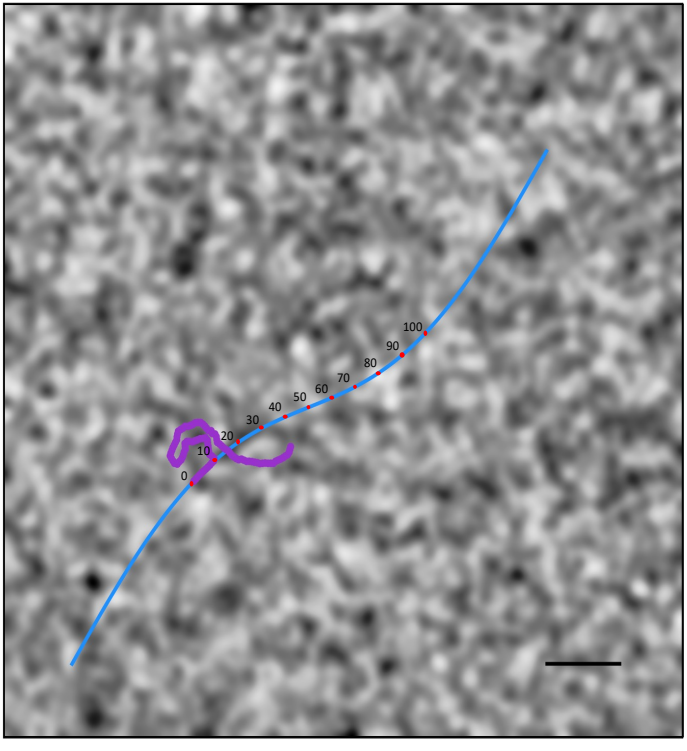


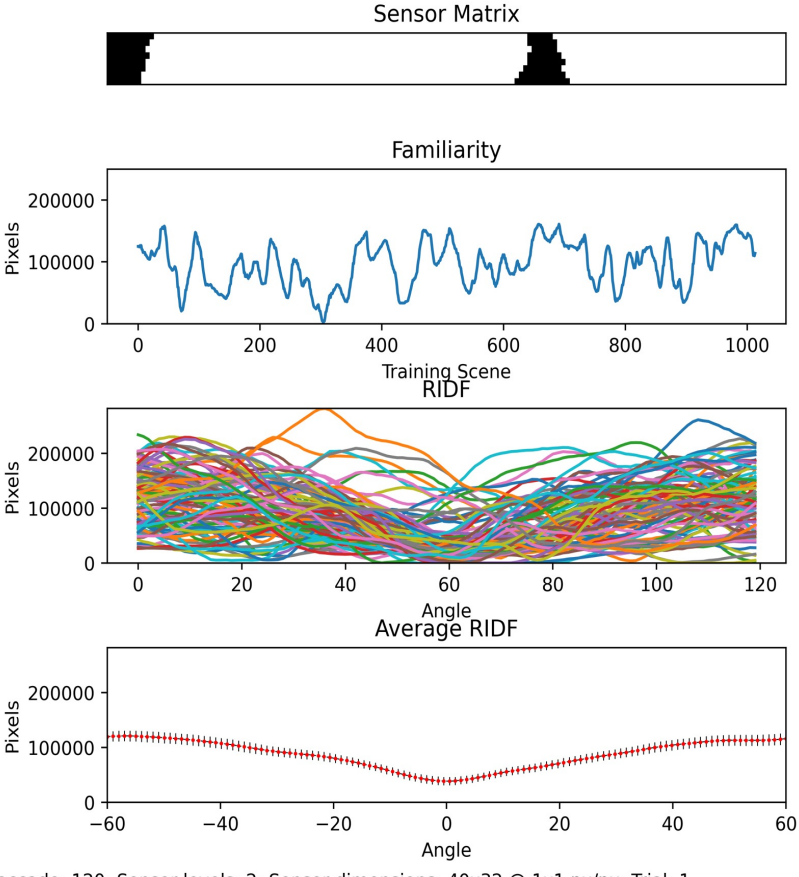


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 41.43; RMSD/dist: 0.104; TD: 92538; p90: 40; p50: 22; complete: 0

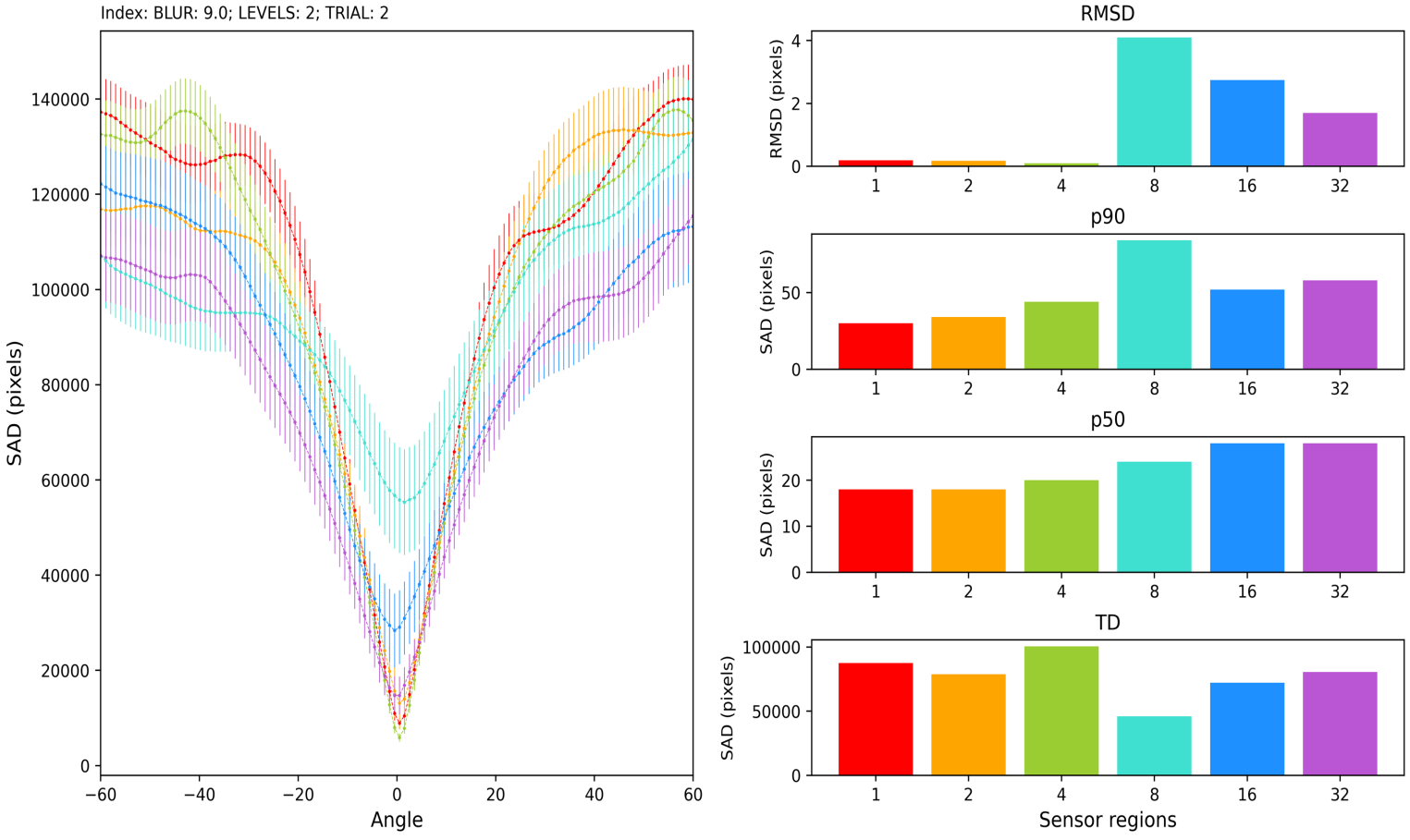
10%



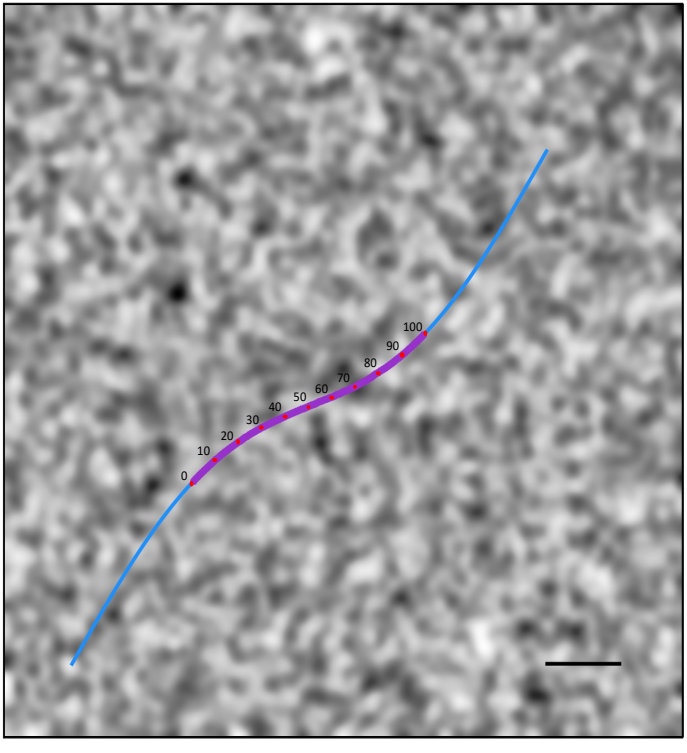


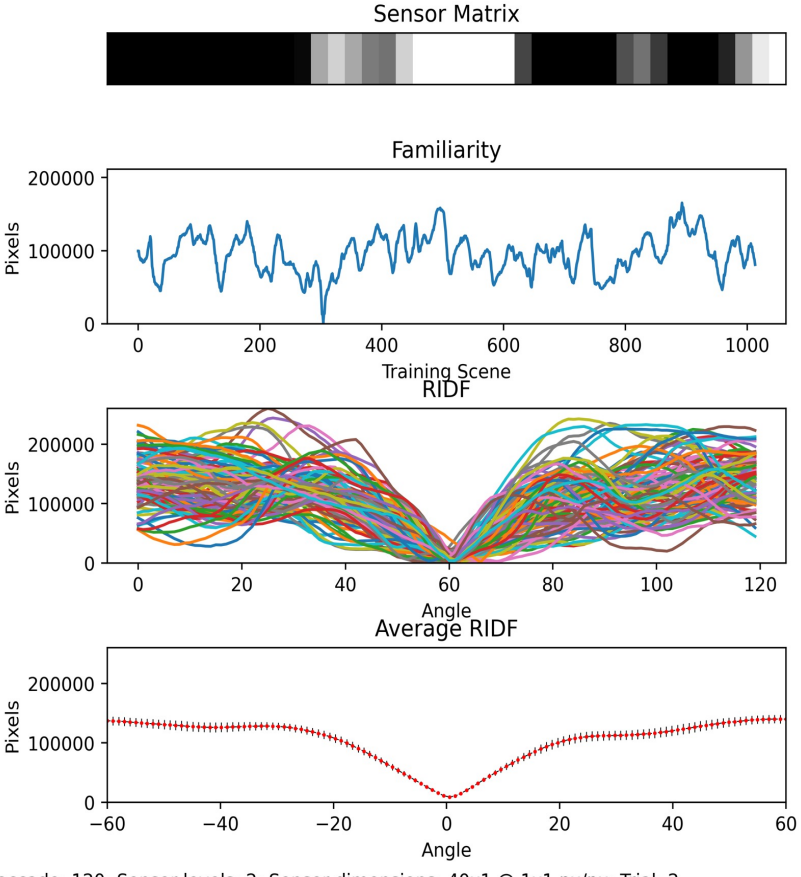
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3368.11; RMSD/dist: 8.420; TD: 58385; p90: 58; p50: 28; complete: 0


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

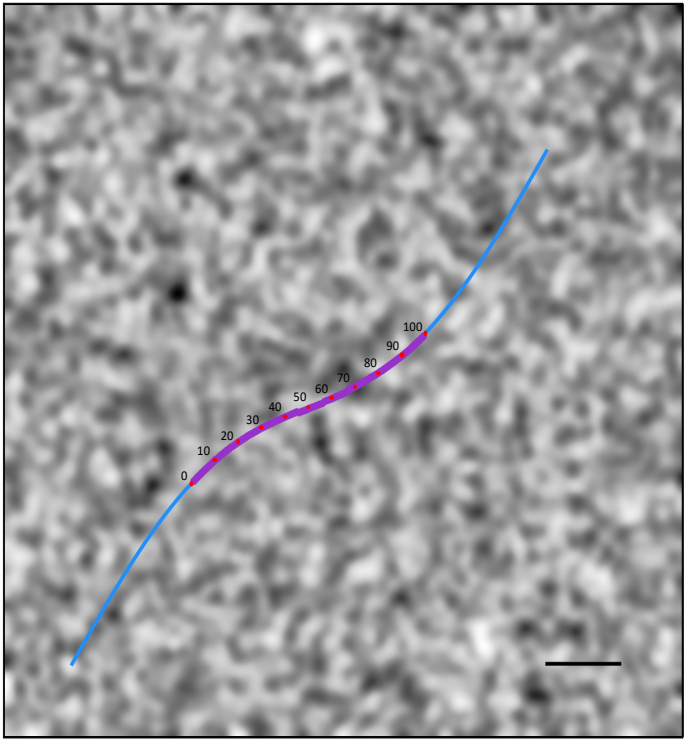


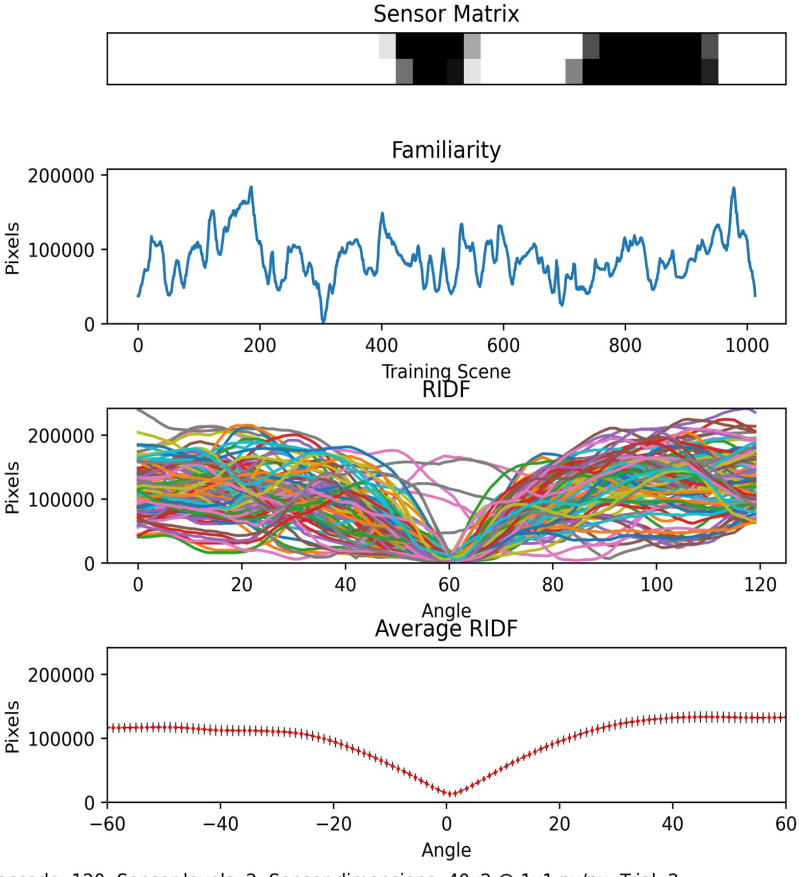


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 75.38; RMSD/dist: 0.188; TD: 87472; p90: 30; p50: 18; complete: 0

90%

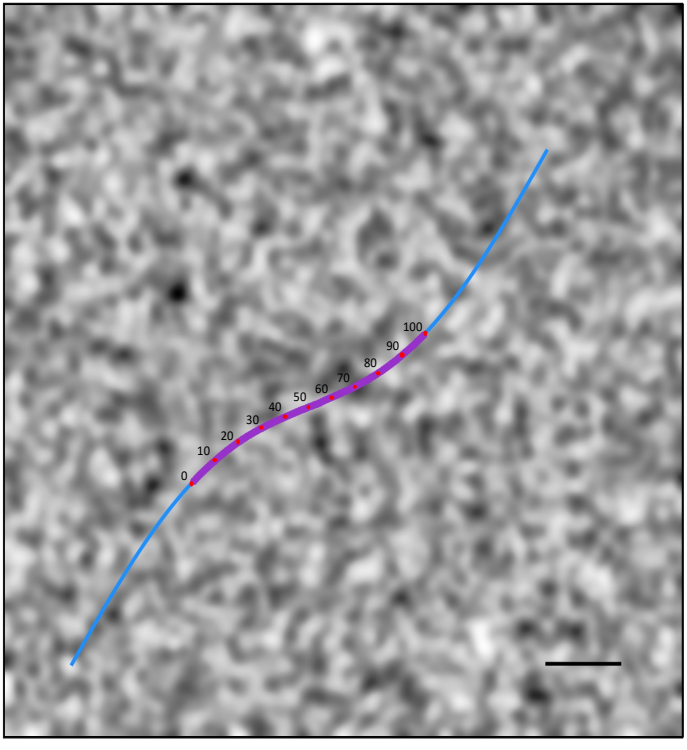


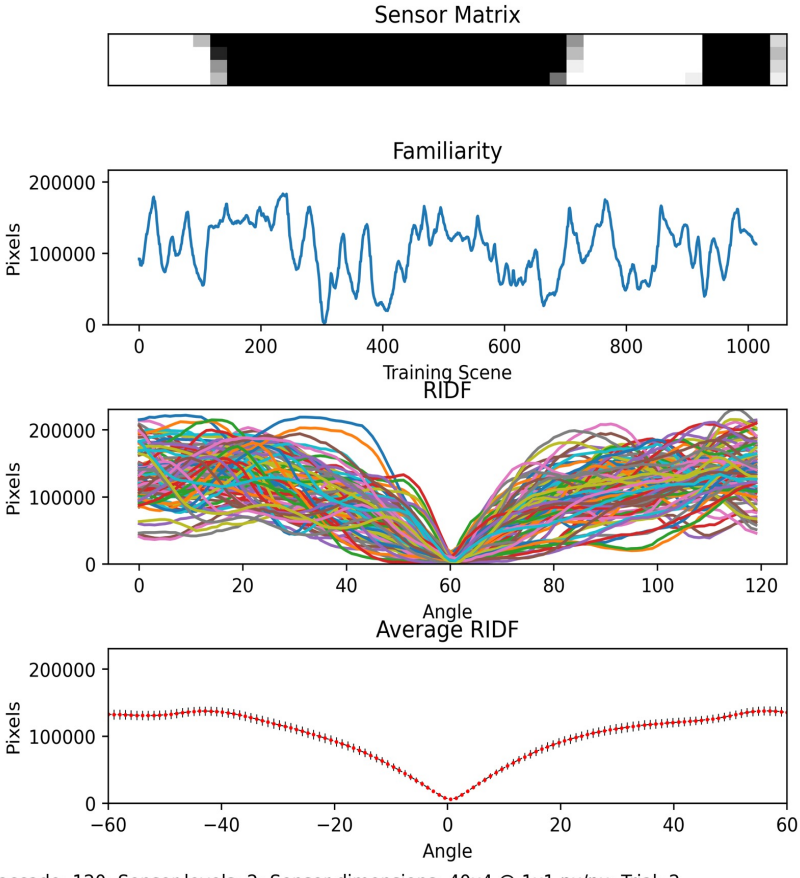


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 68.06; RMSD/dist: 0.170; TD: 78840; p90: 34; p50: 18; complete: 0

100%

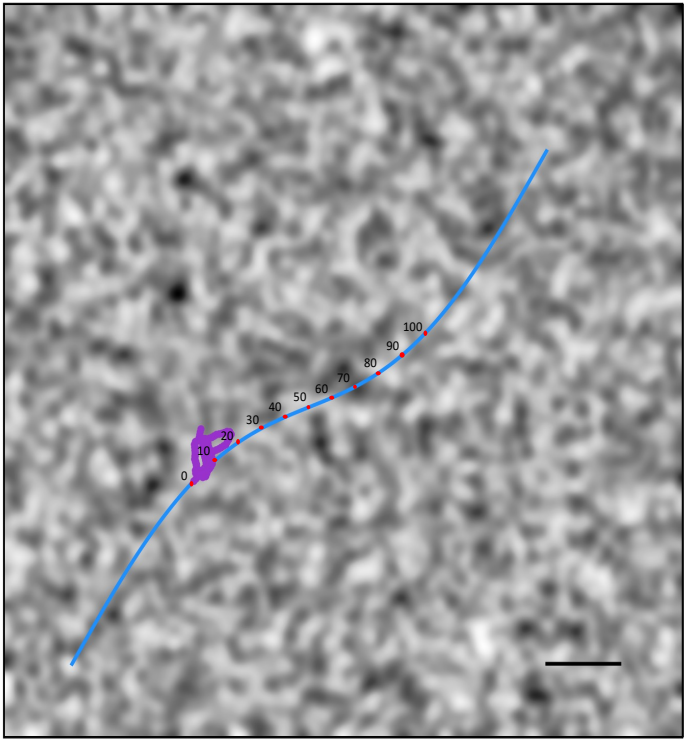


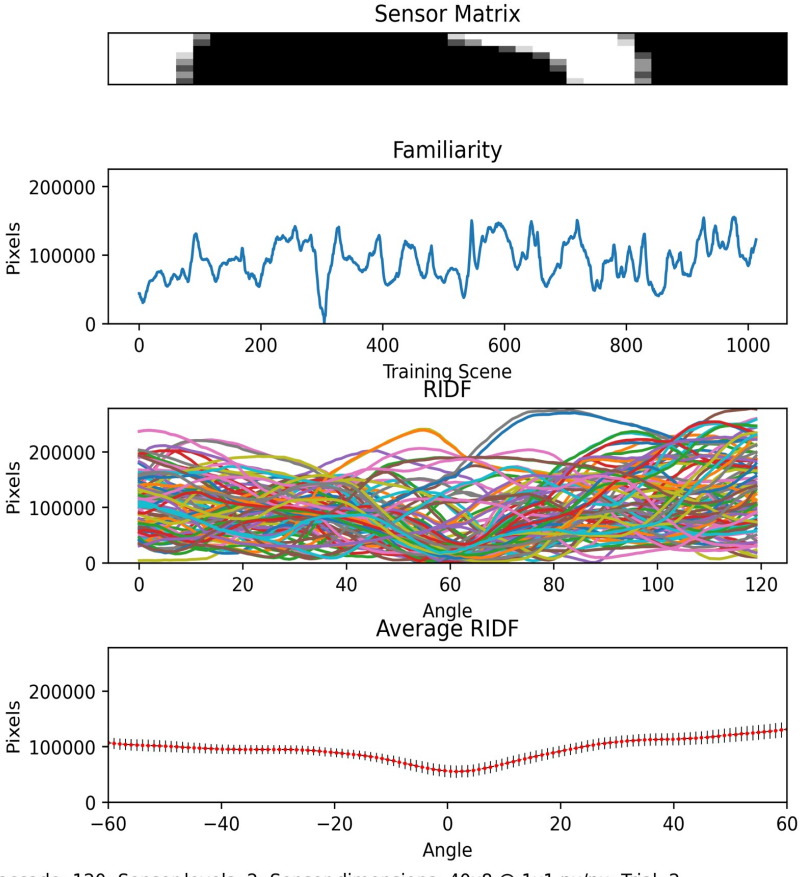


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 38.75; RMSD/dist: 0.097; TD: 100445; p90: 44; p50: 20; complete: 0

10%

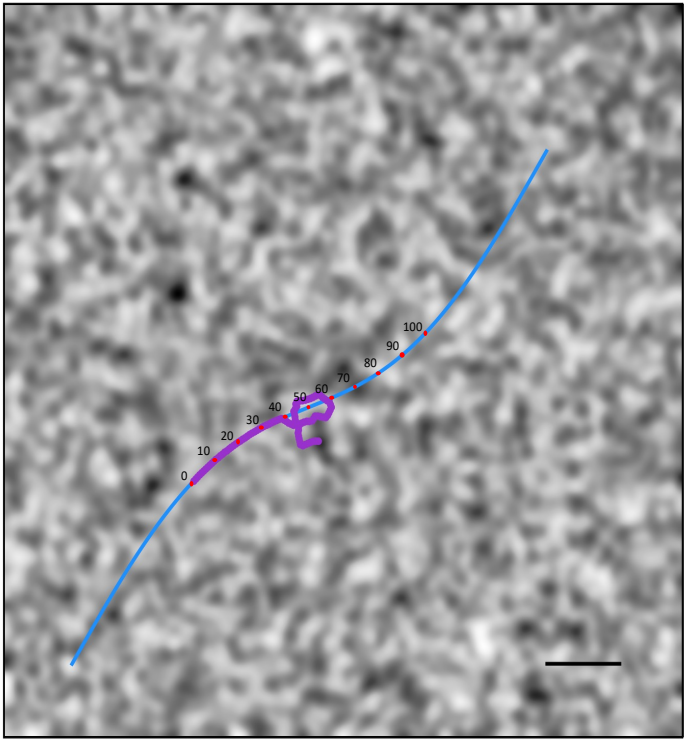


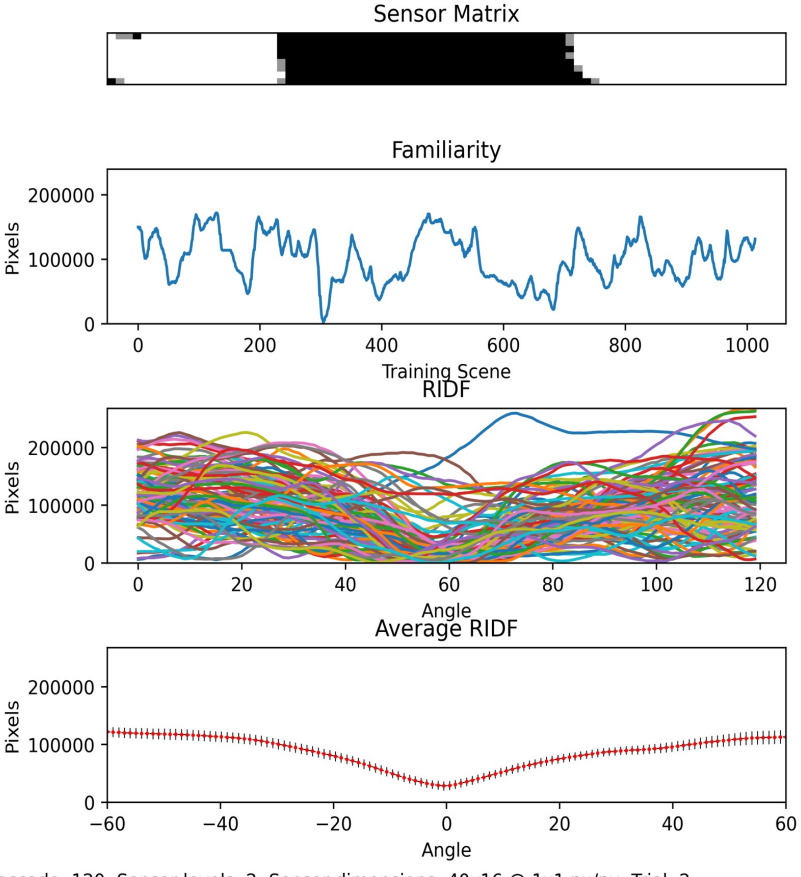


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1640.40; RMSD/dist: 4.101; TD: 45972; p90: 84; p50: 24; complete: 0

40%

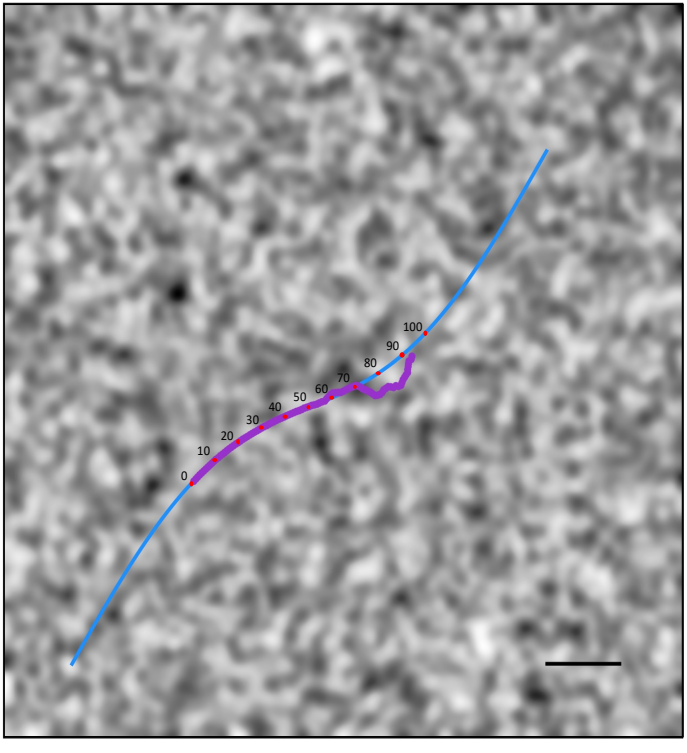


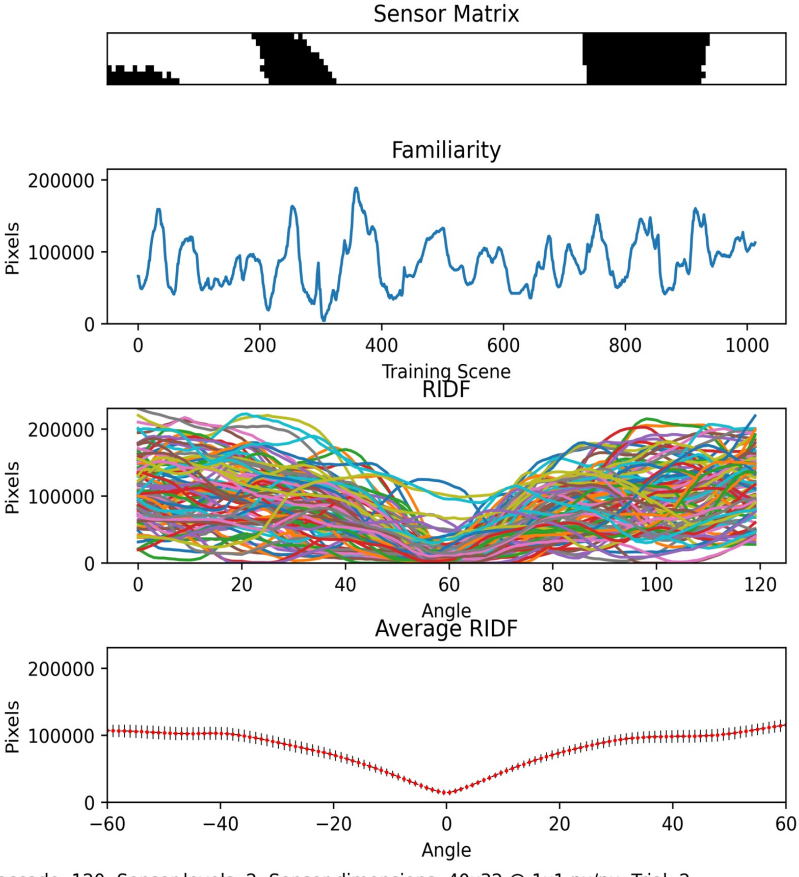


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1098.27; RMSD/dist: 2.746; TD: 72059; p90: 52; p50: 28; complete: 0

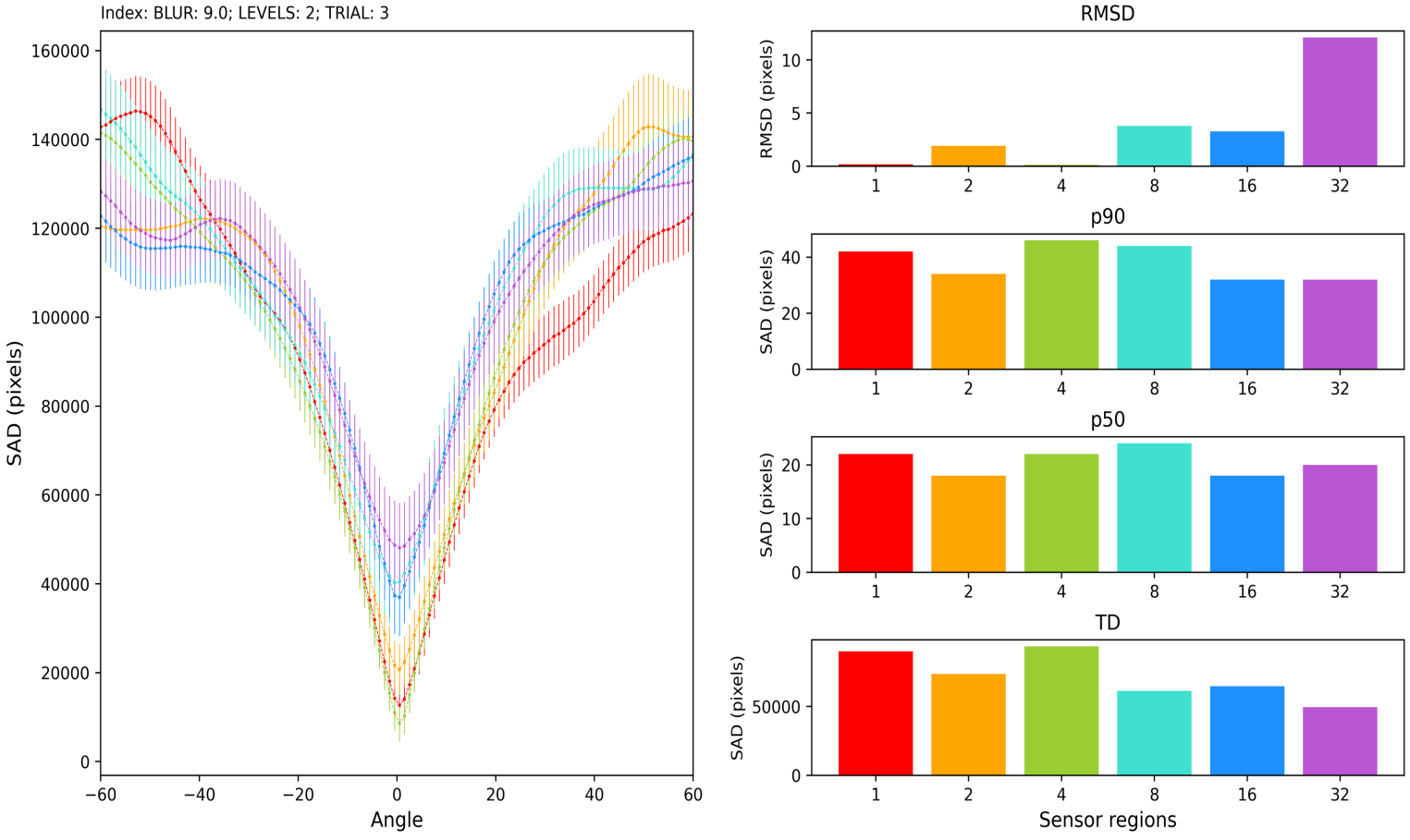
60%



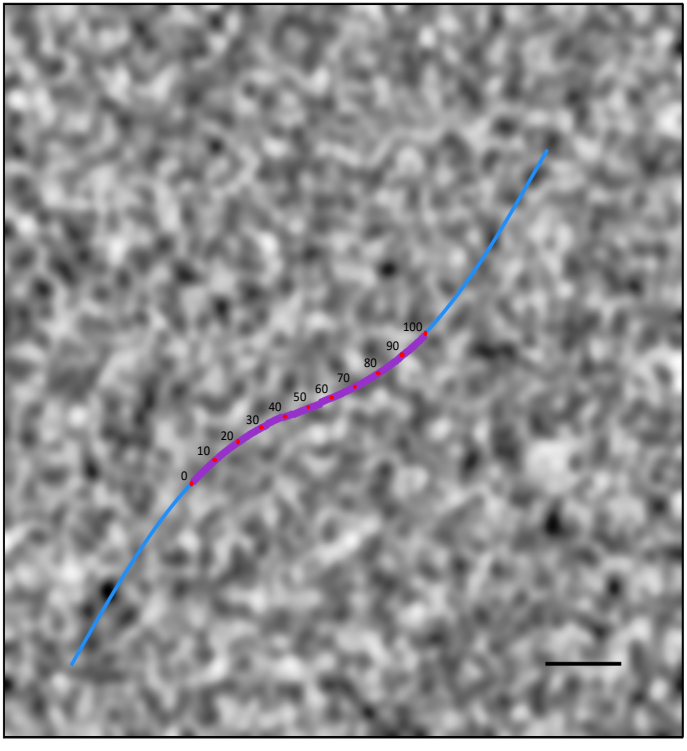


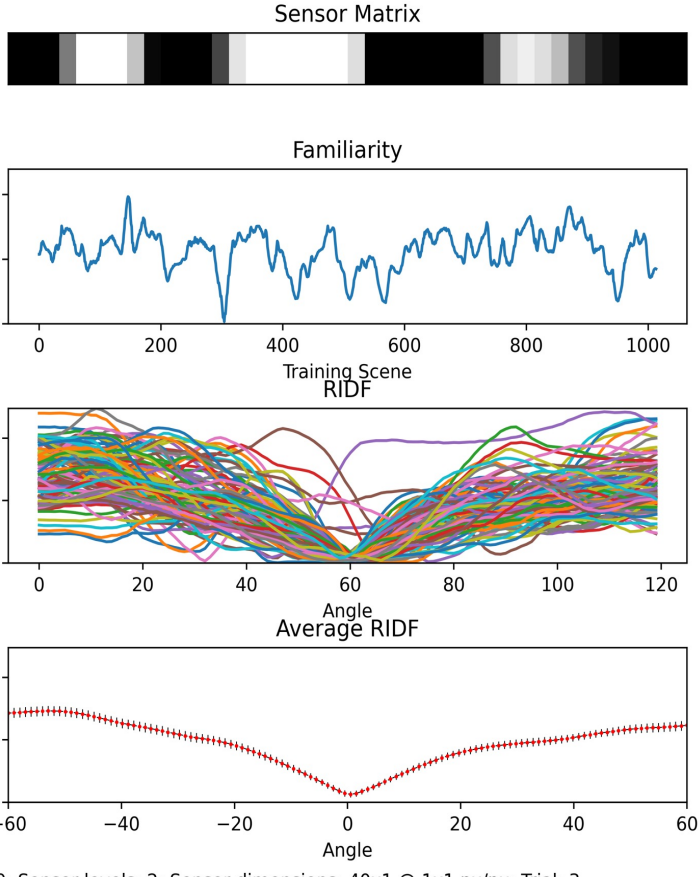
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 679.08; RMSD/dist: 1.698; TD: 80488; p90: 58; p50: 28; complete: 0


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

90%

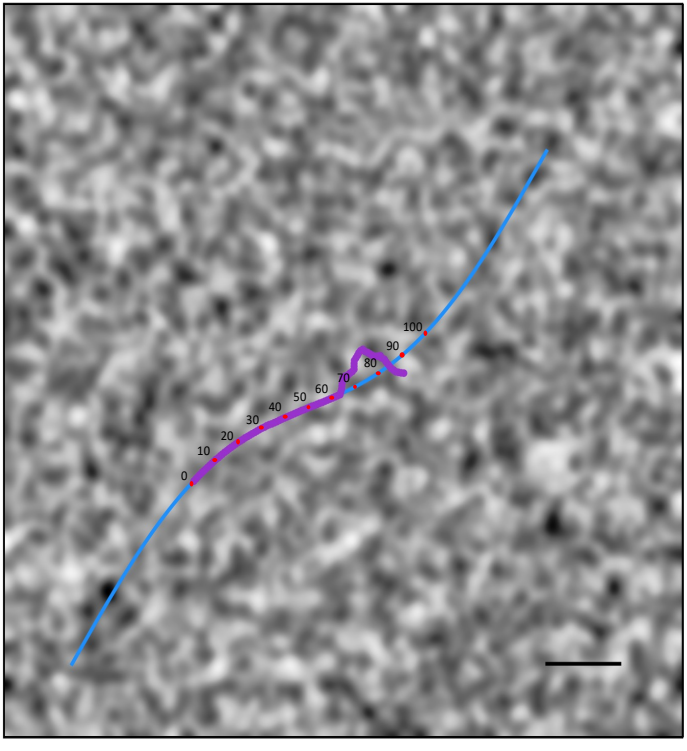


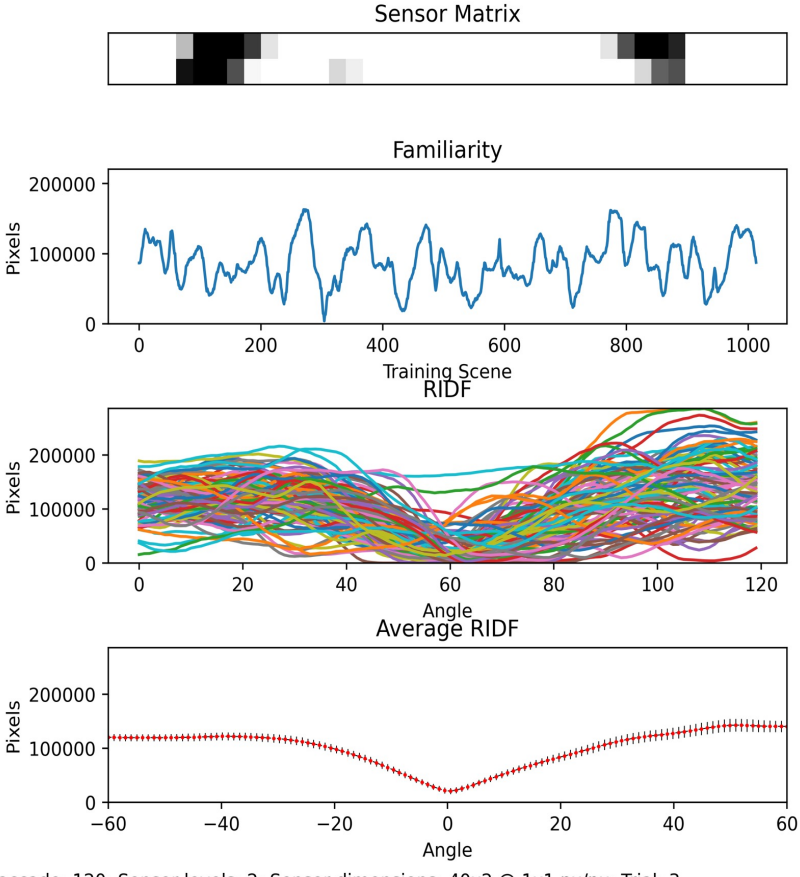


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 71.21; RMSD/dist: 0.178; TD: 90177; p90: 42; p50: 22; complete: 0

60%

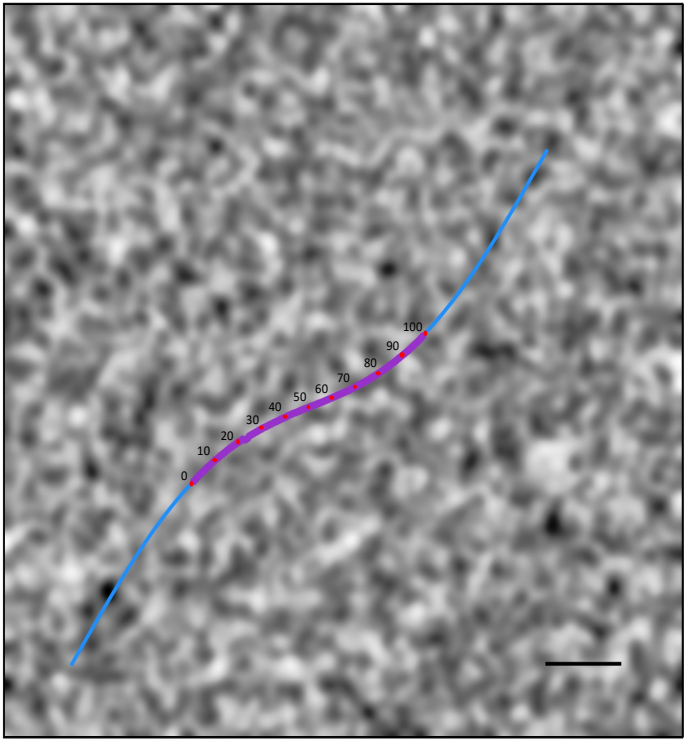


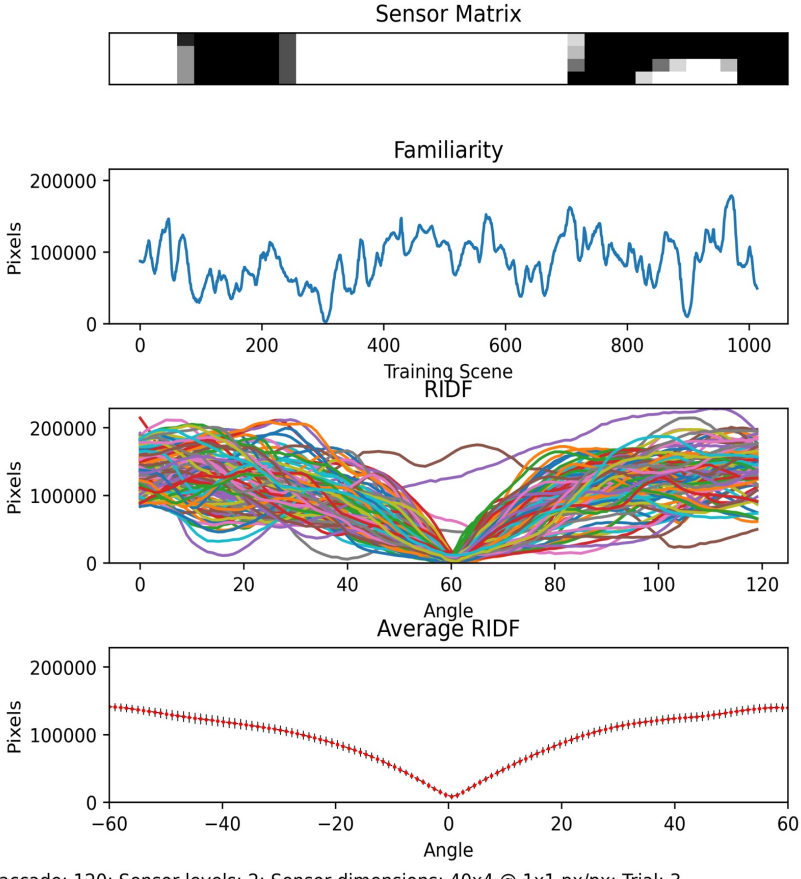


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 772.18; RMSD/dist: 1.930; TD: 73613; p90: 34; p50: 18; complete: 0

90%

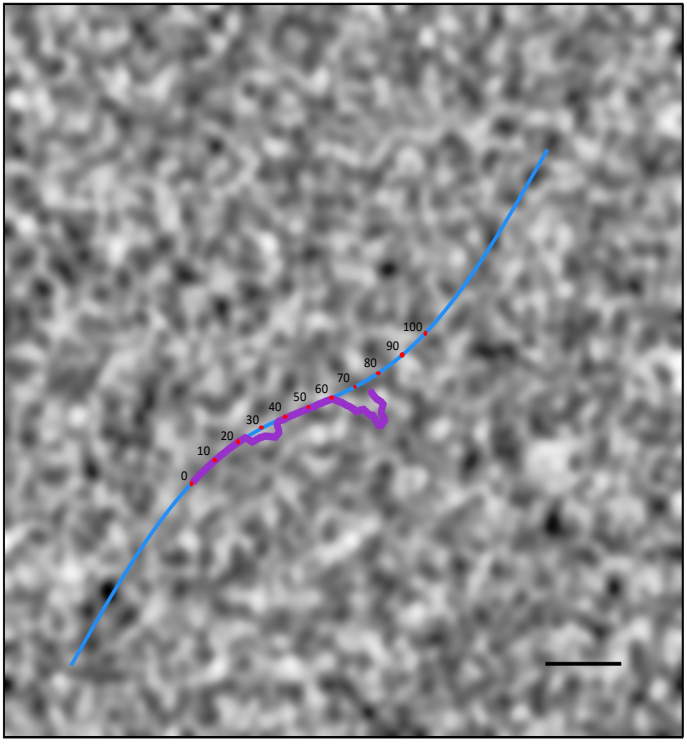


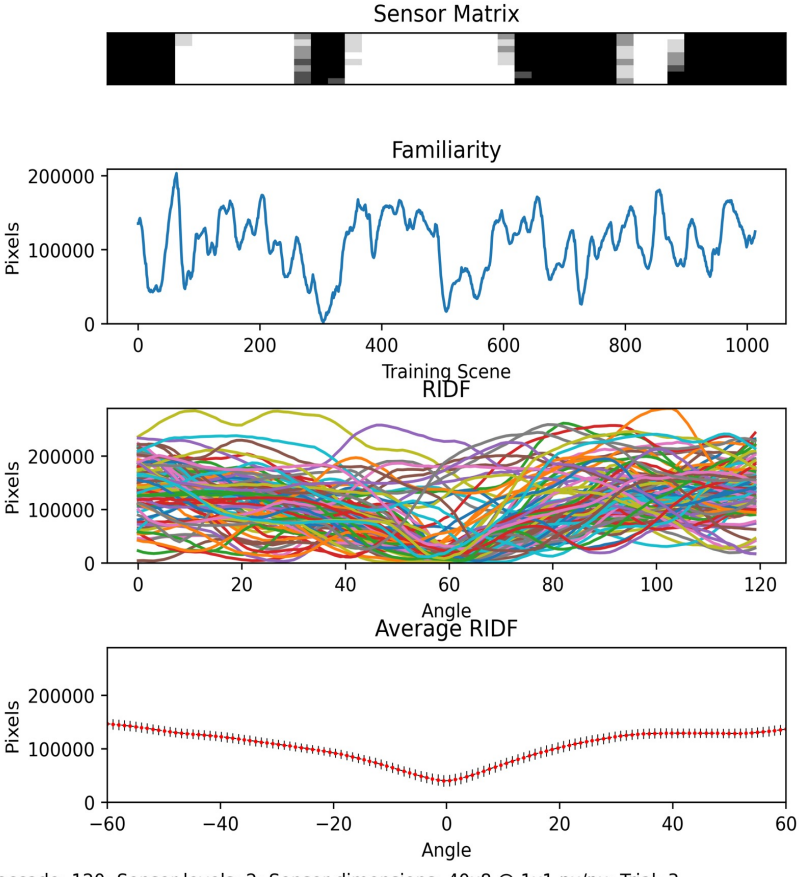


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 52.69; RMSD/dist: 0.132; TD: 93689; p90: 46; p50: 22; complete: 0

40%

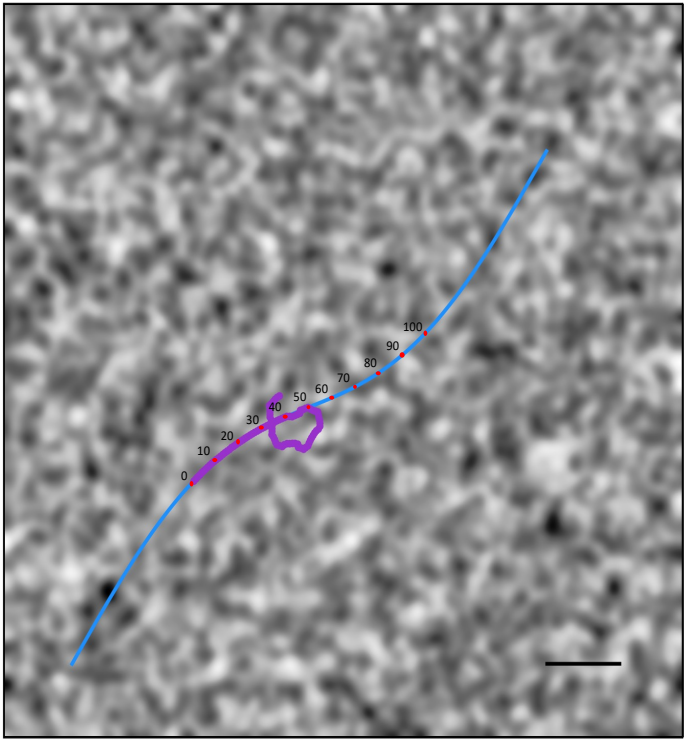


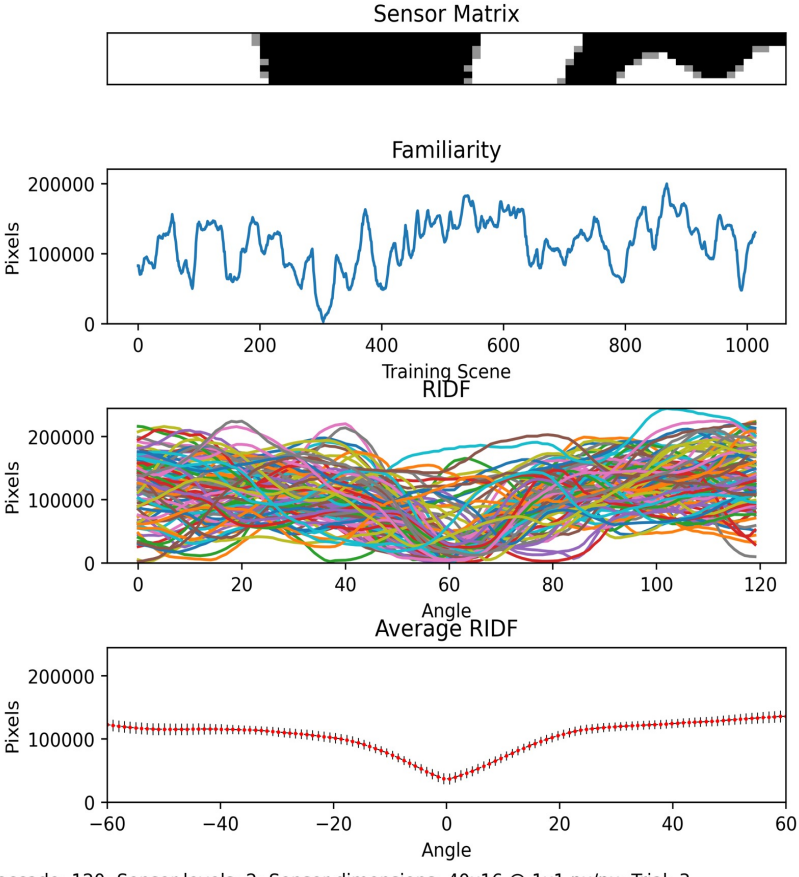


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1518.66; RMSD/dist: 3.797; TD: 61365; p90: 44; p50: 24; complete: 0

40%

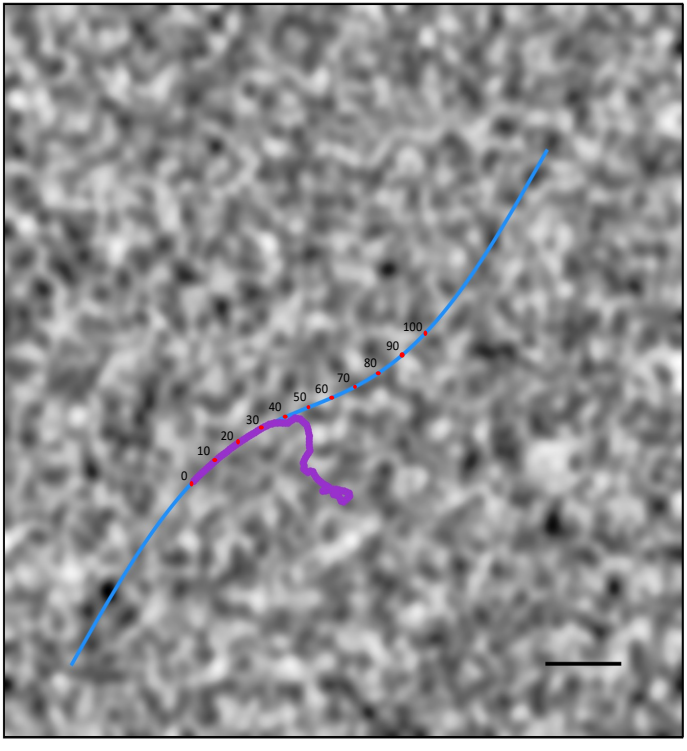


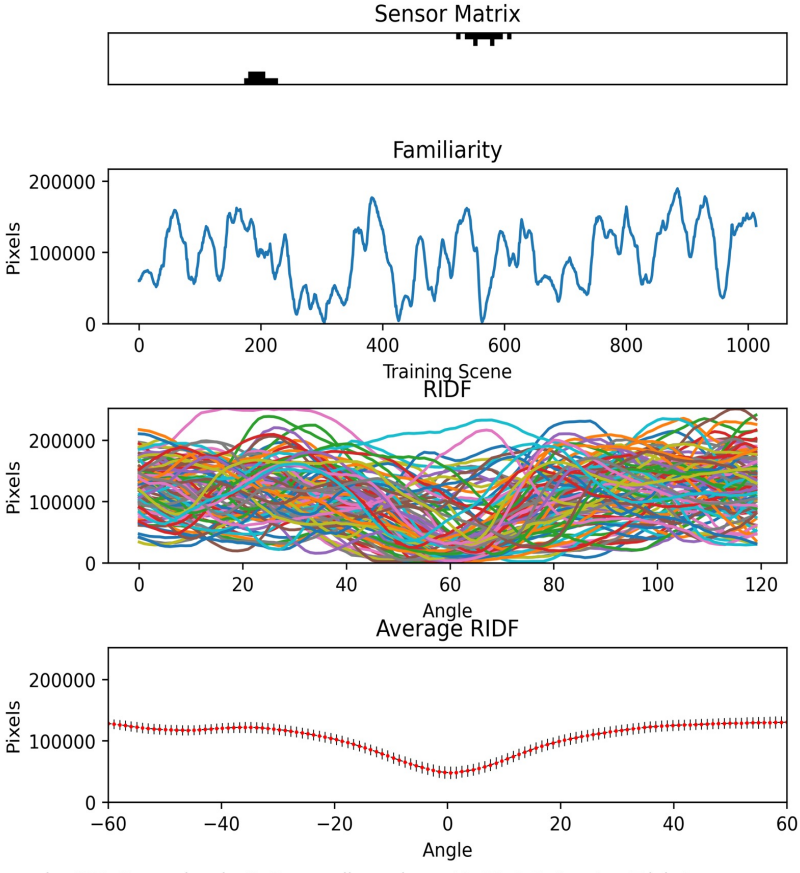


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1314.40; RMSD/dist: 3.286; TD: 64772; p90: 32; p50: 18; complete: 0

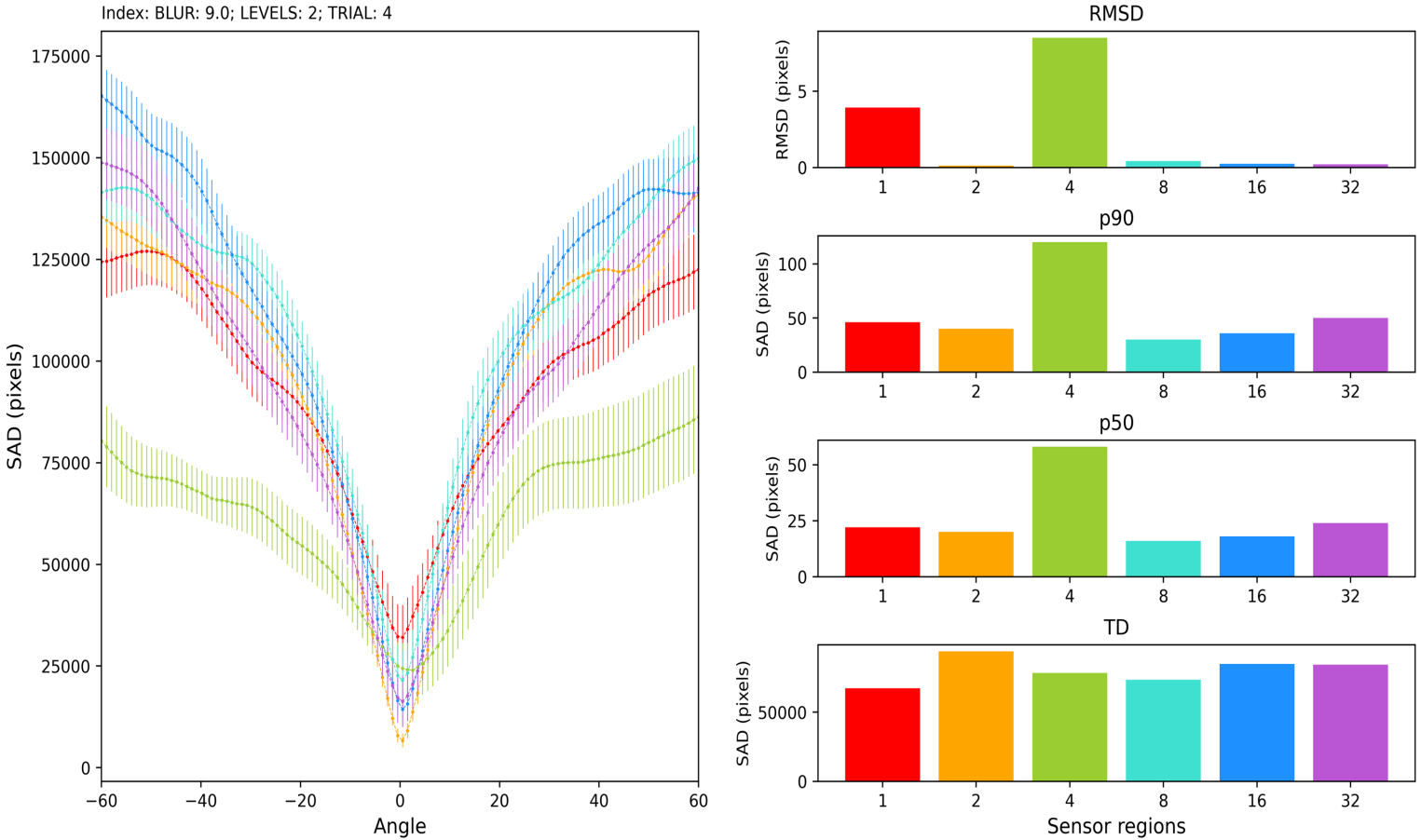
30%



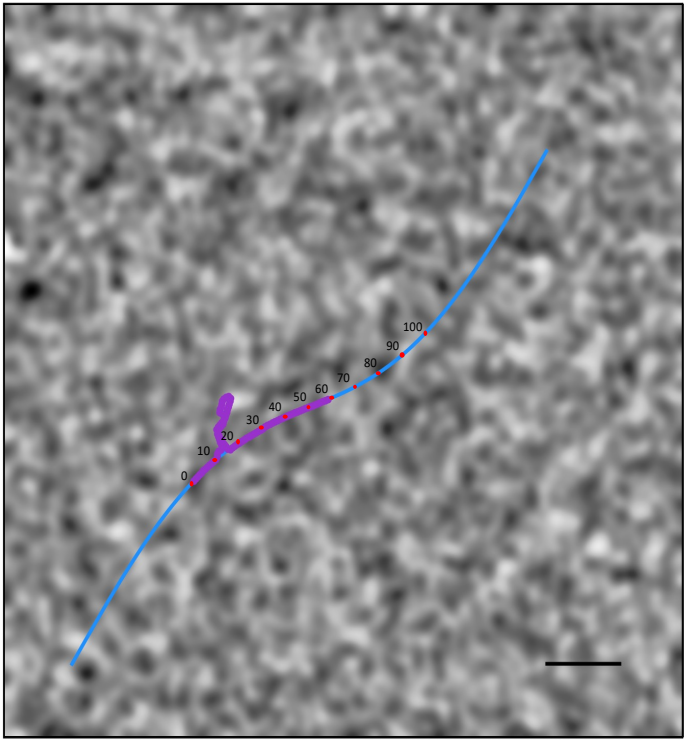


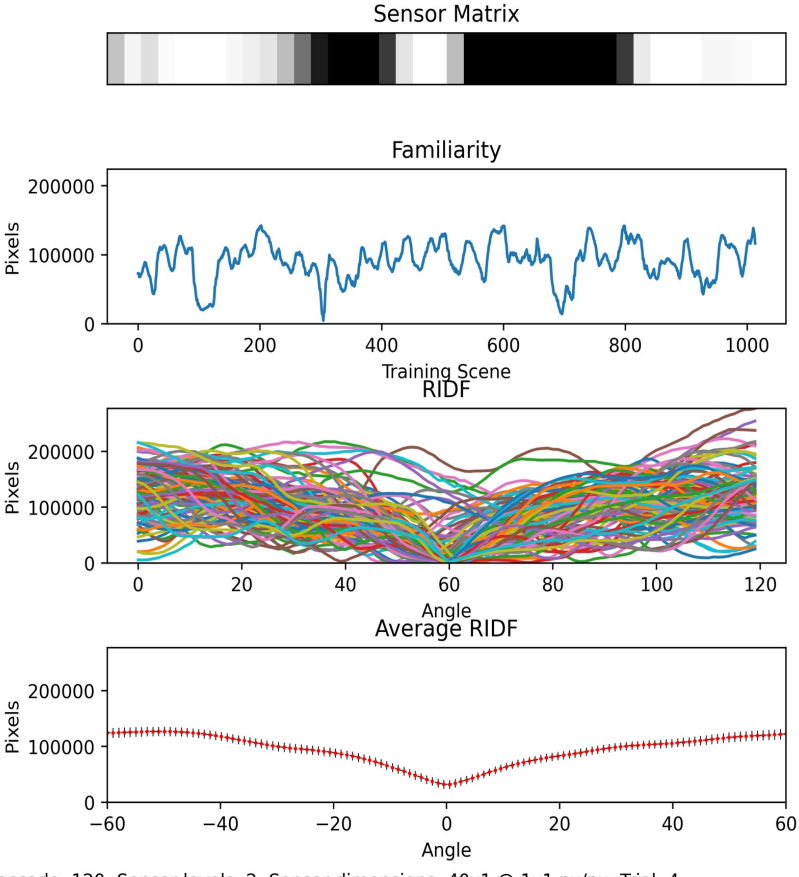
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4847.89; RMSD/dist: 12.120; TD: 49524; p90: 32; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 4
SAD (pixels)
175000
150000
125000
100000
75000
50000
25000
0
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
5
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
SAD (pixels)
50
25
0
TD
SAD (pixels)
50000
0
Sensor regions

50%

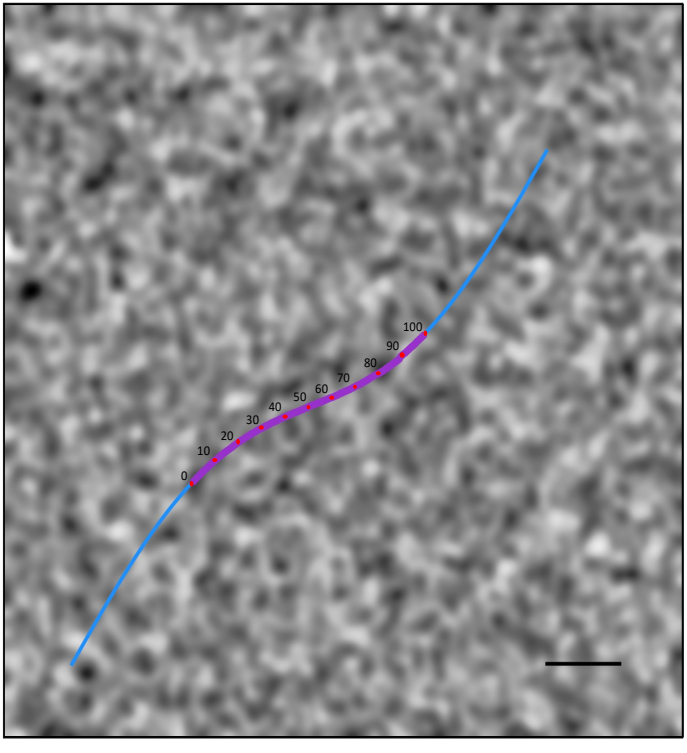


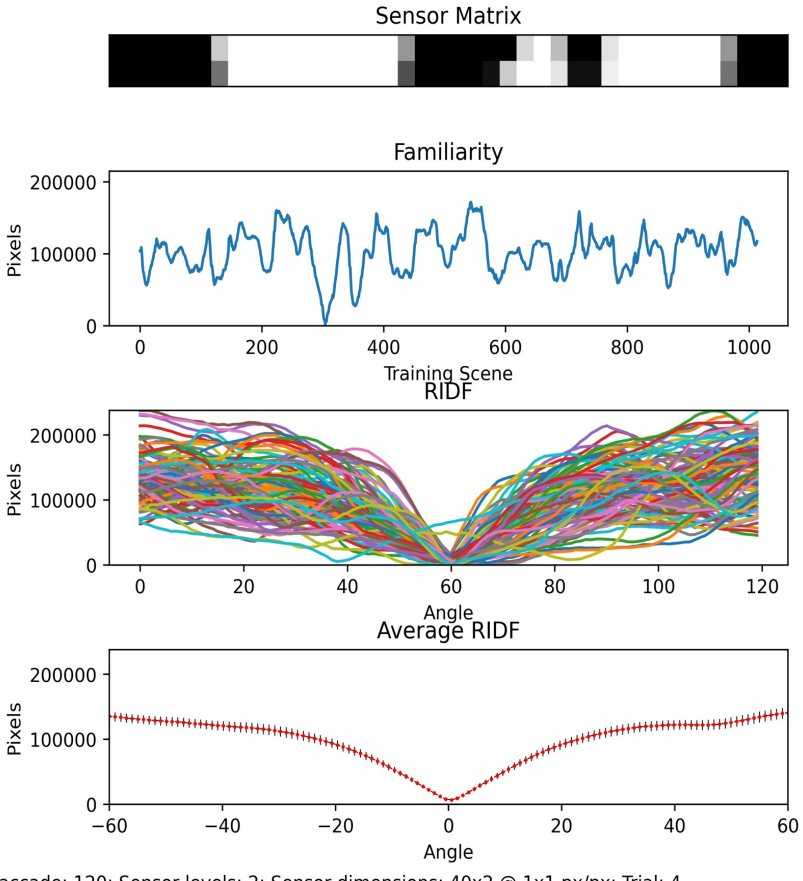


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1573.79; RMSD/dist: 3.934; TD: 67327; p90: 46; p50: 22; complete: 0

100%

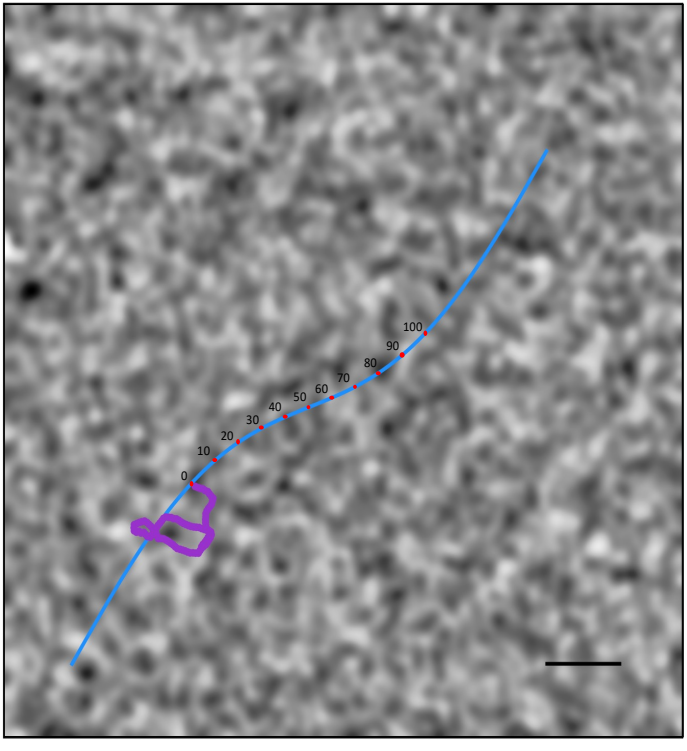


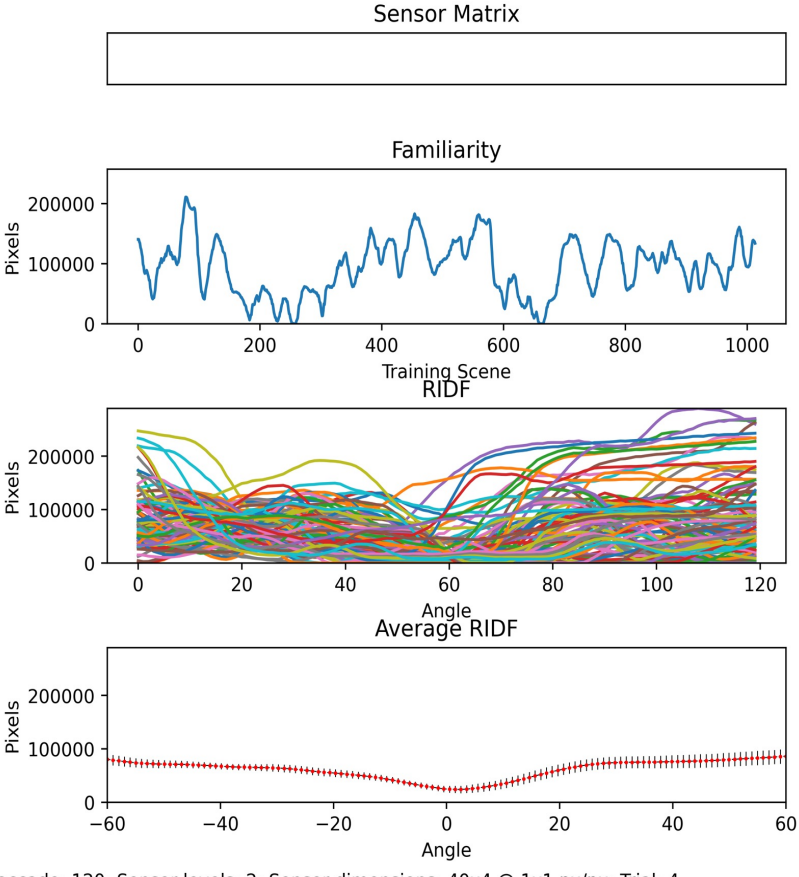


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 50.13; RMSD/dist: 0.125; TD: 94018; p90: 40; p50: 20; complete: 0

0%

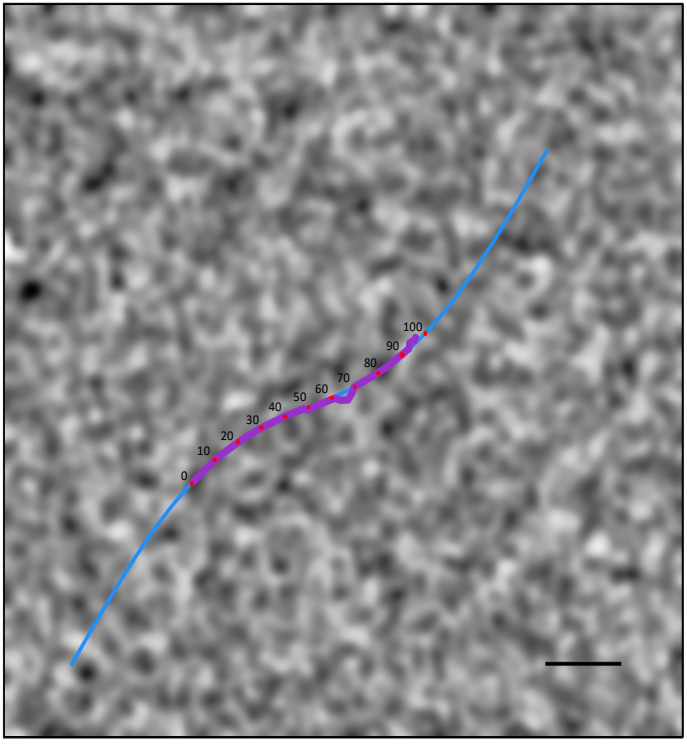


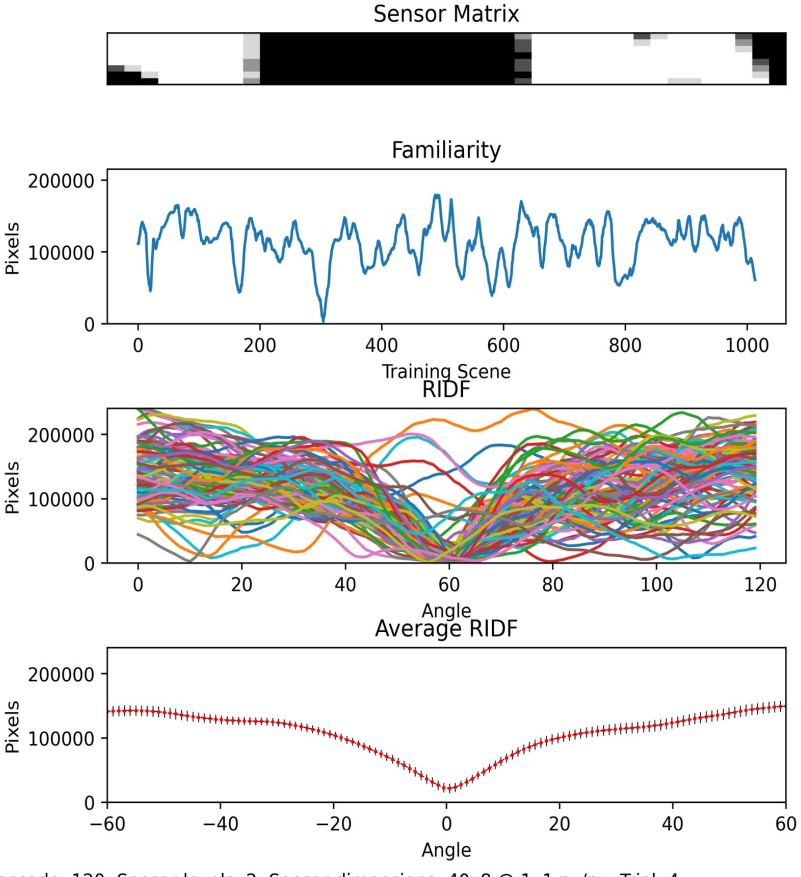


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3402.81; RMSD/dist: 8.507; TD: 78502; p90: 120; p50: 58; complete: 0

80%

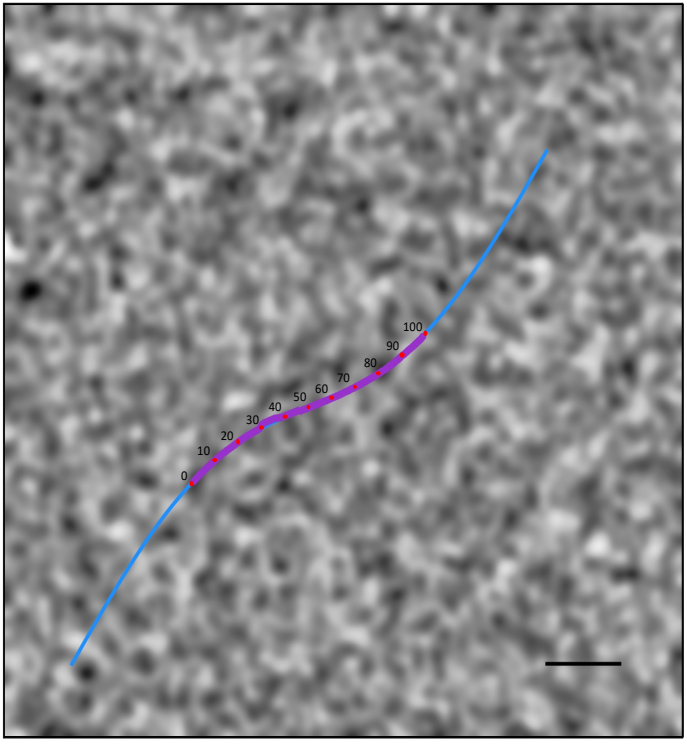


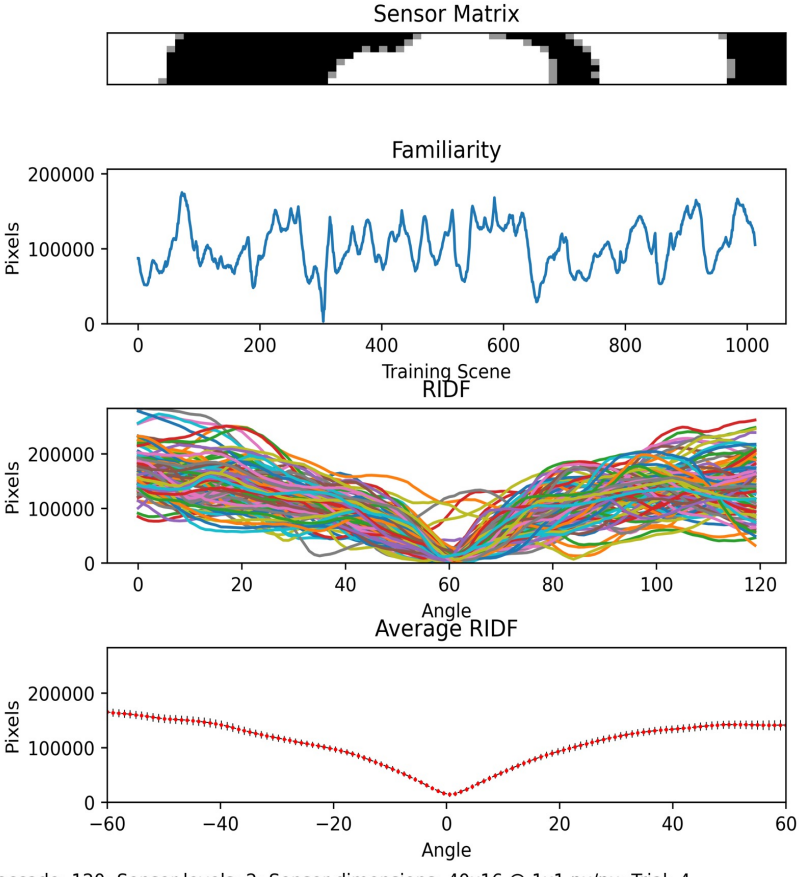


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 169.26; RMSD/dist: 0.423; TD: 73570; p90: 30; p50: 16; complete: 0

90%

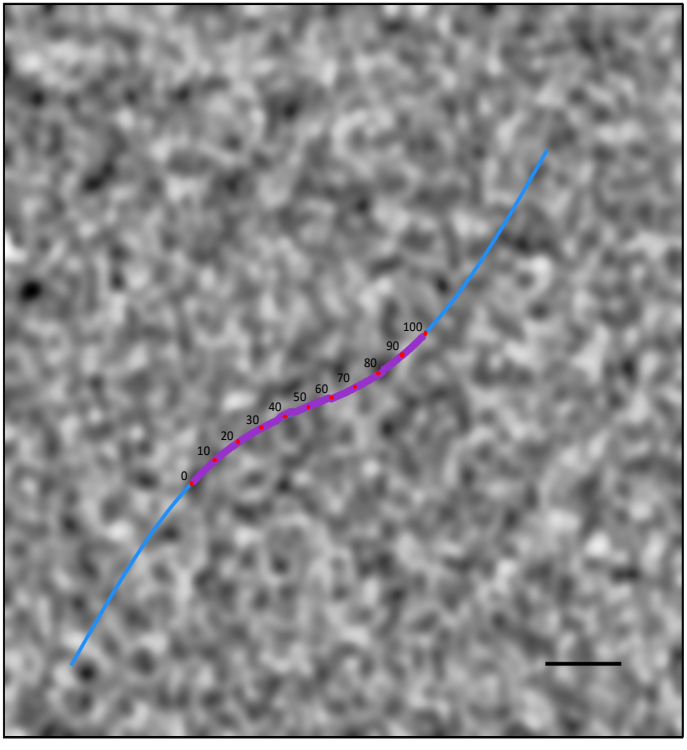


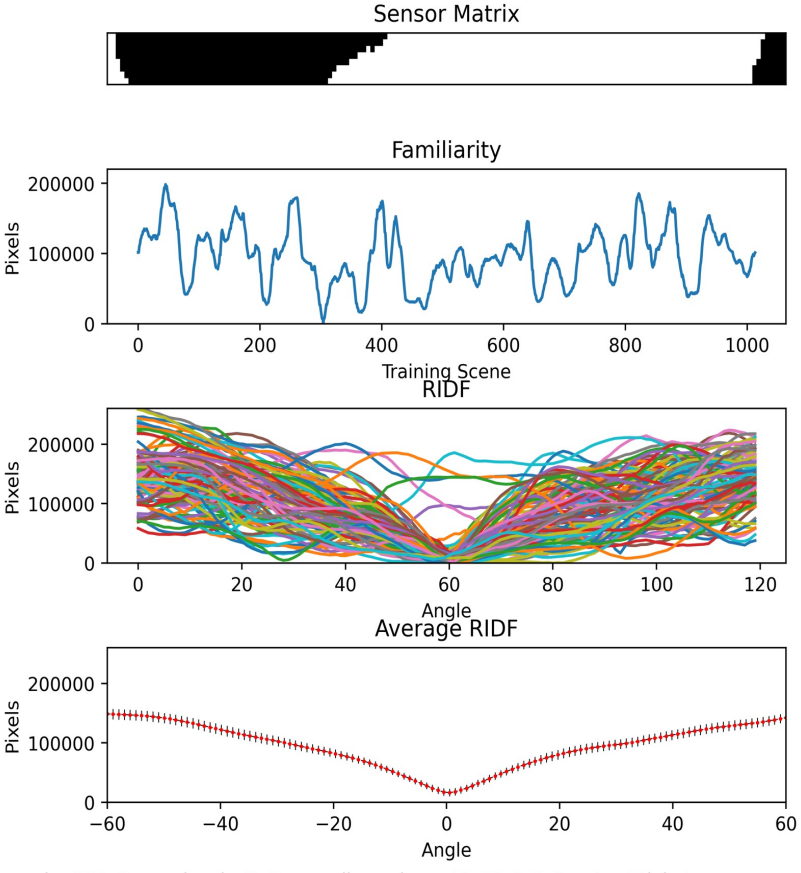


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 97.15; RMSD/dist: 0.243; TD: 84969; p90: 36; p50: 18; complete: 0

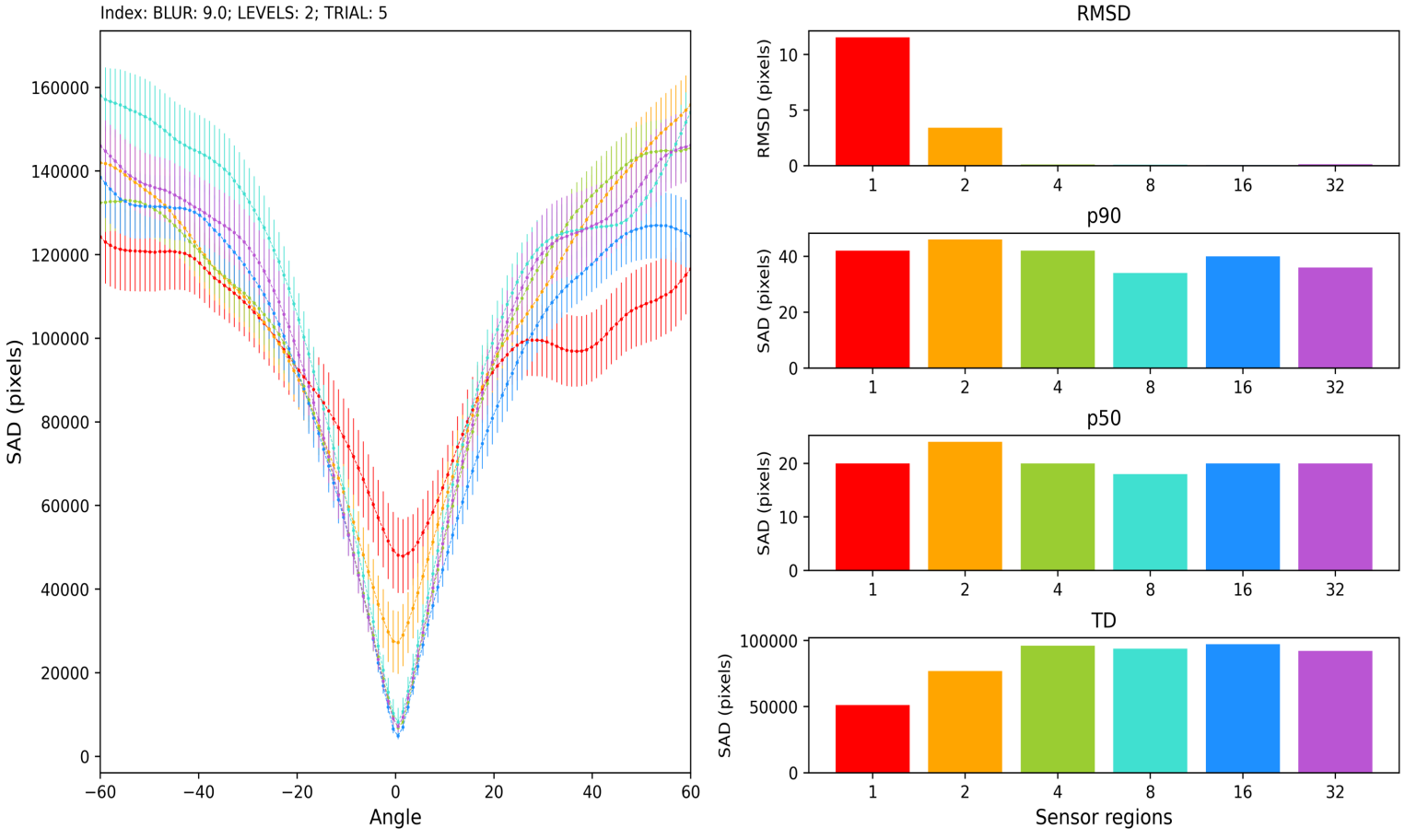
90%



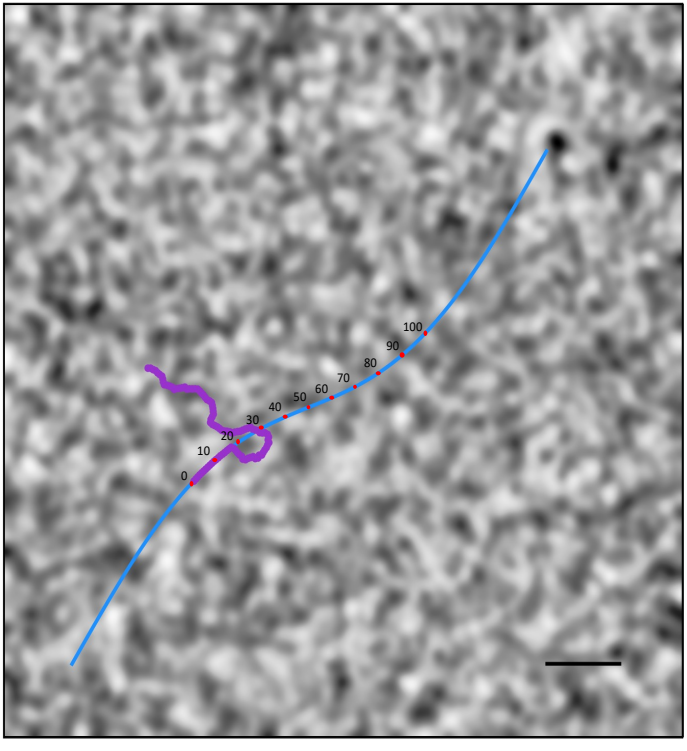


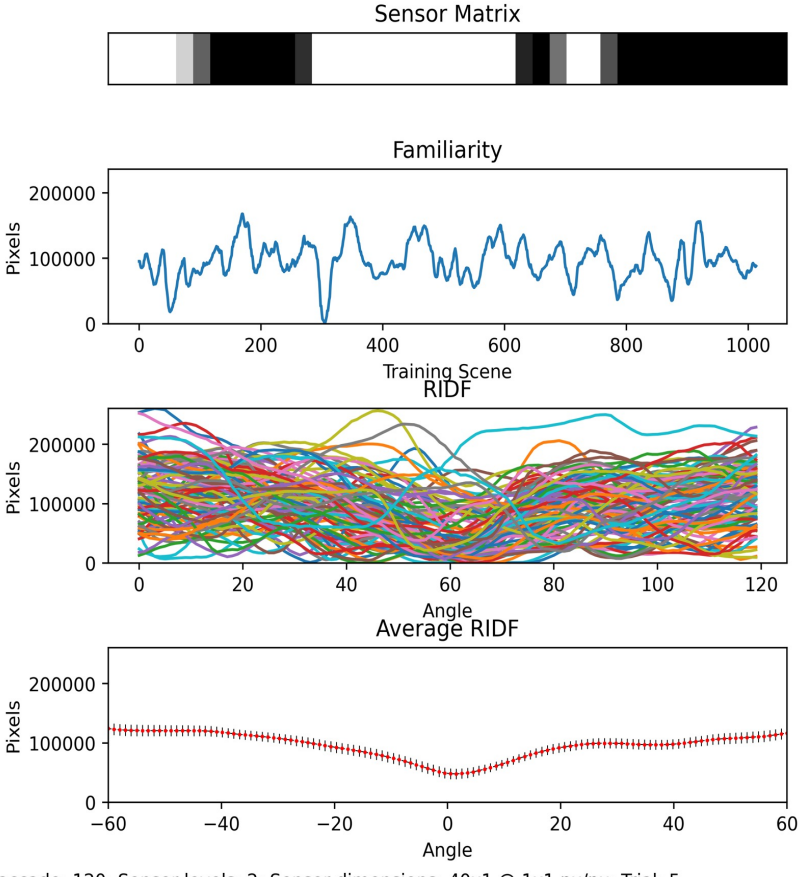
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 84.12; RMSD/dist: 0.210; TD: 84472; p90: 50; p50: 24; complete: 0


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

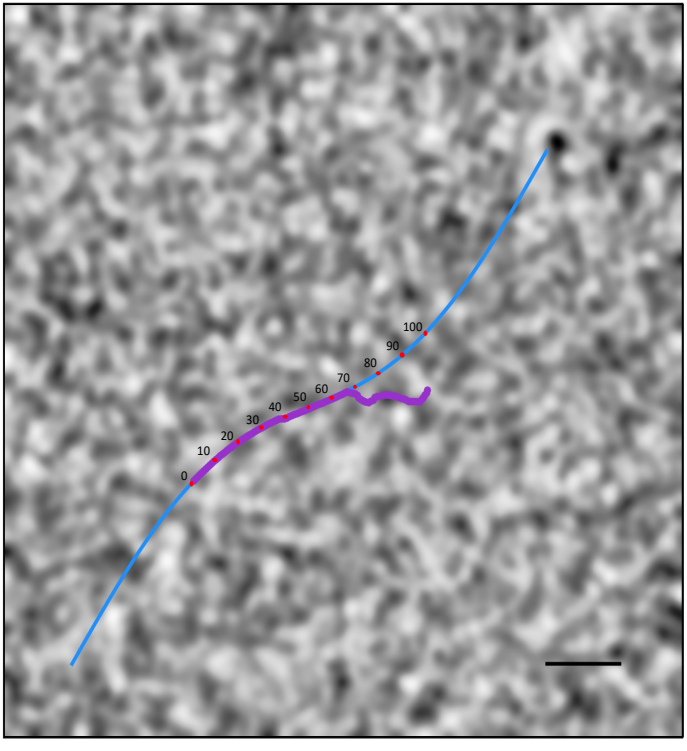


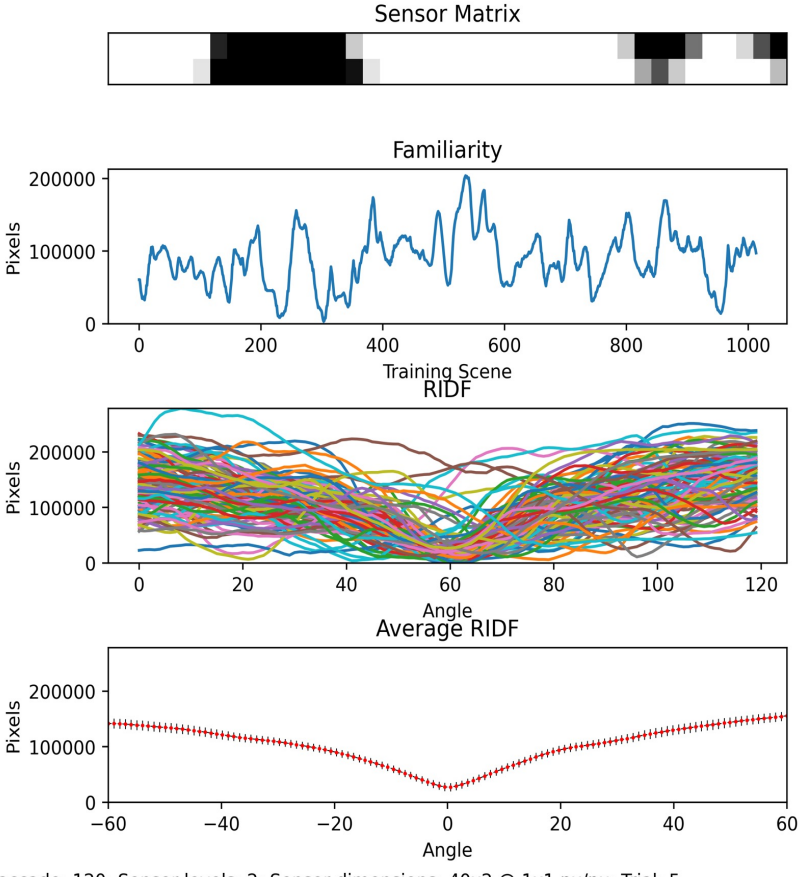


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 4622.97; RMSD/dist: 11.557; TD: 51227; p90: 42; p50: 20; complete: 0

60%

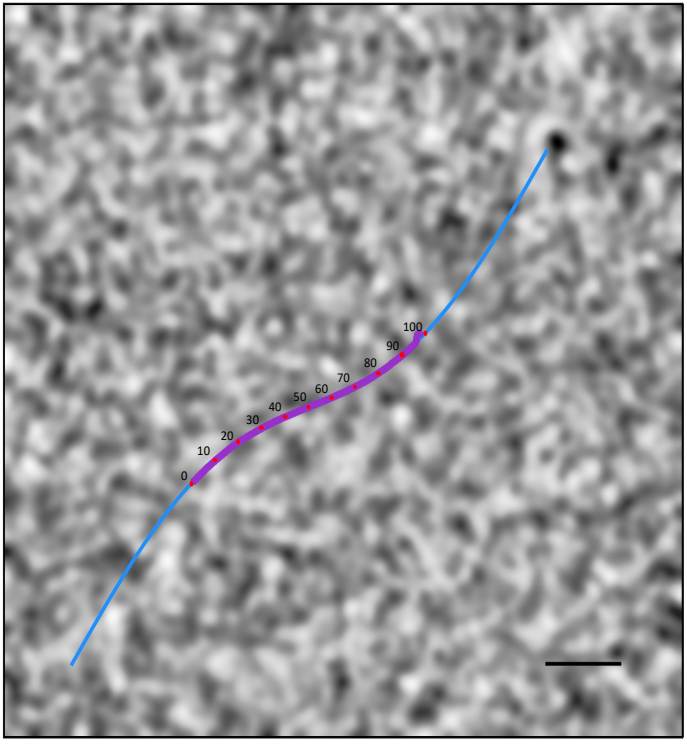


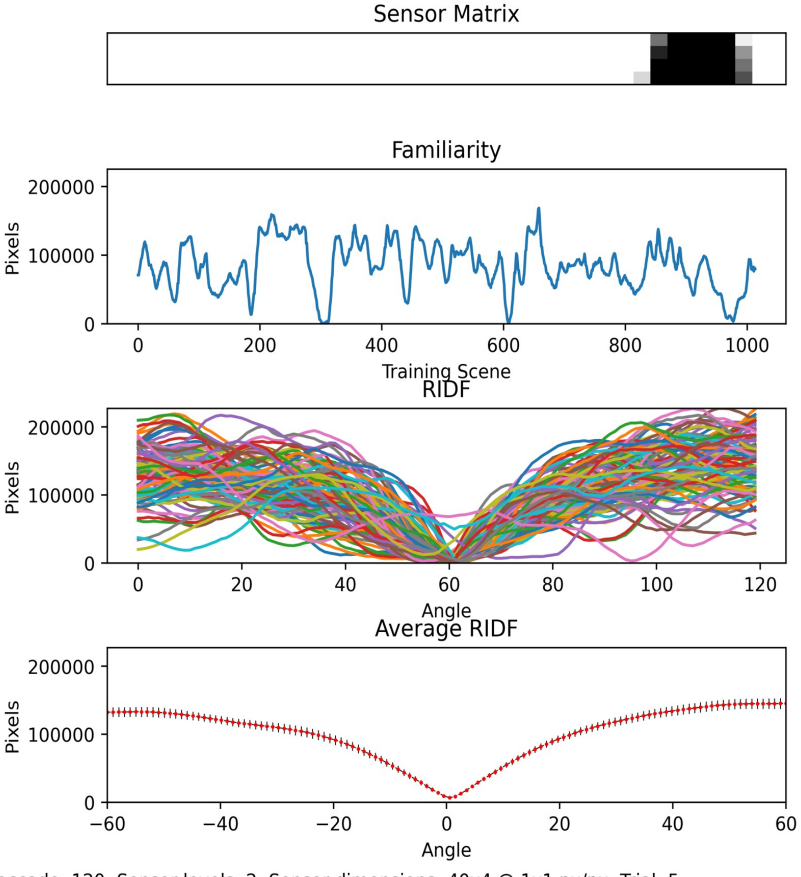


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1363.31; RMSD/dist: 3.408; TD: 76927; p90: 46; p50: 24; complete: 0

90%

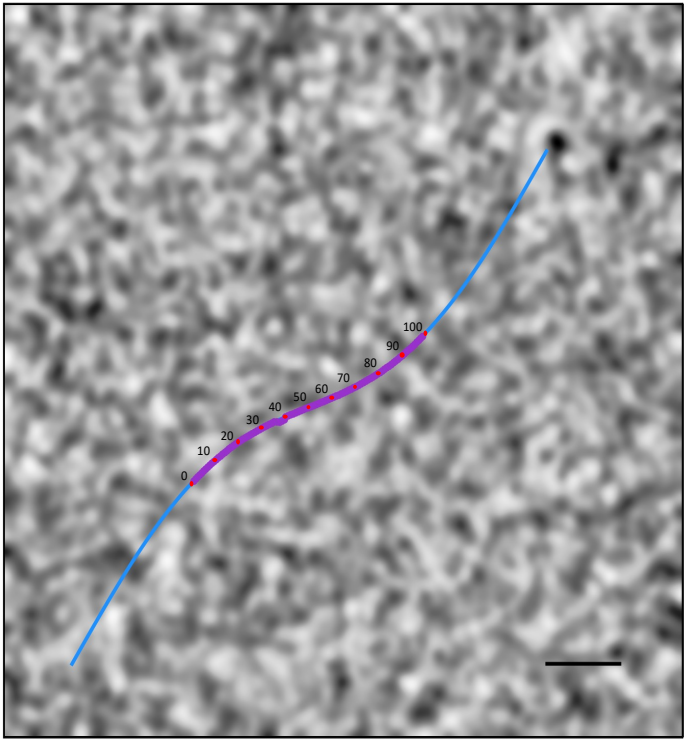


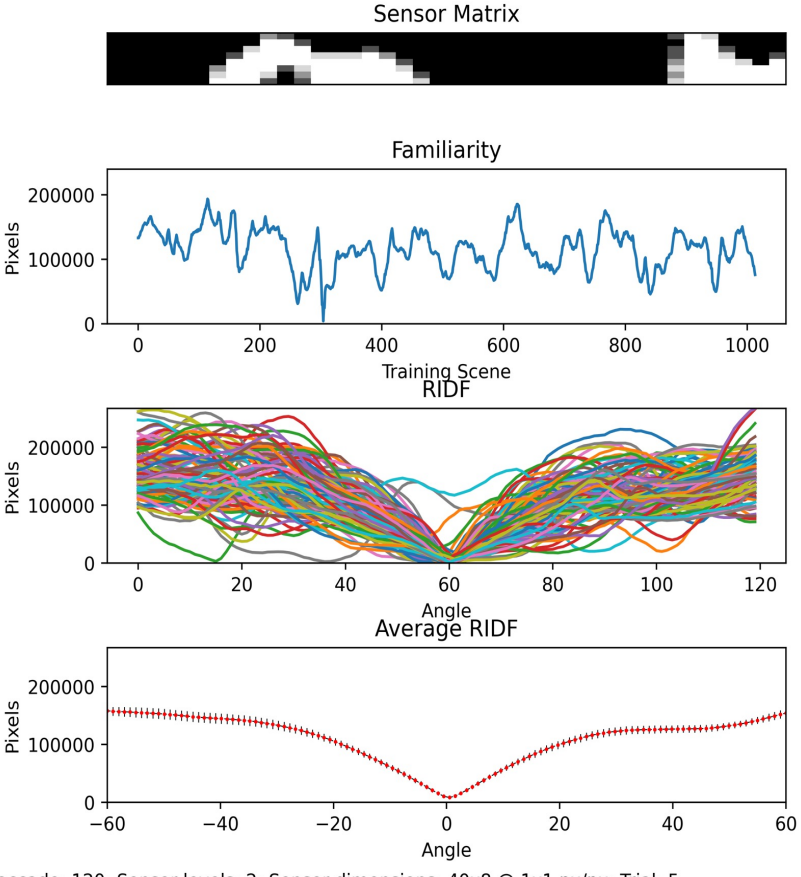


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 45.50; RMSD/dist: 0.114; TD: 95972; p90: 42; p50: 20; complete: 0

90%

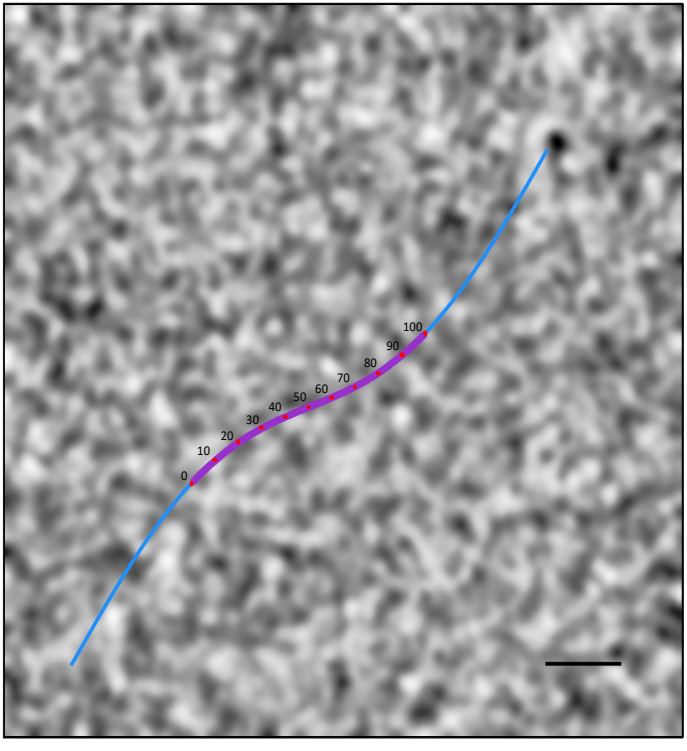


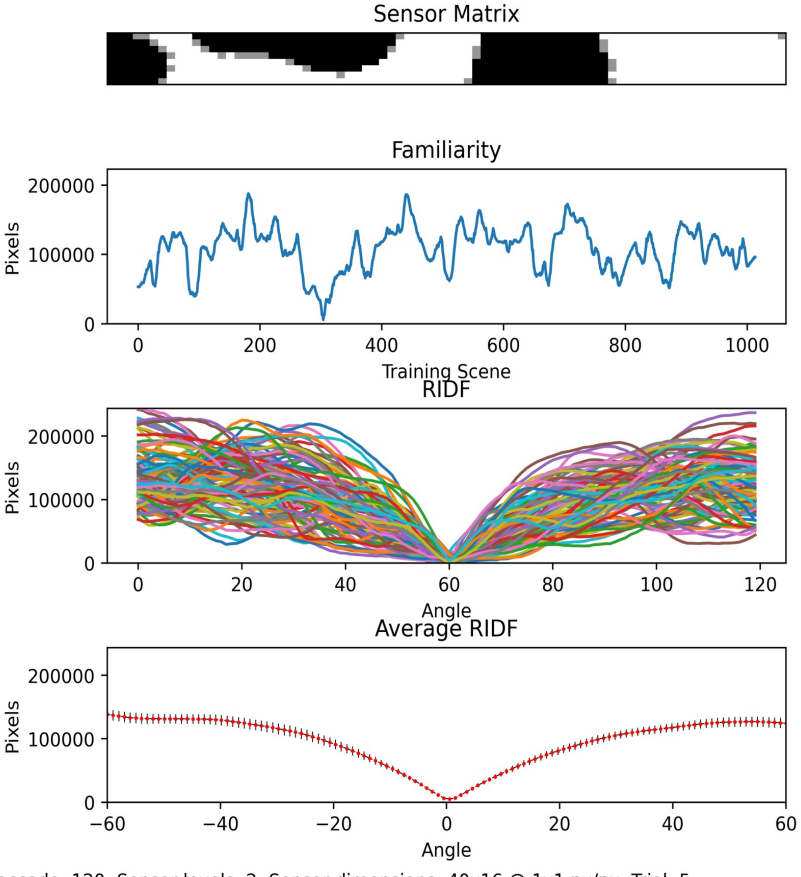


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 33.45; RMSD/dist: 0.084; TD: 93790; p90: 34; p50: 18; complete: 0

100%

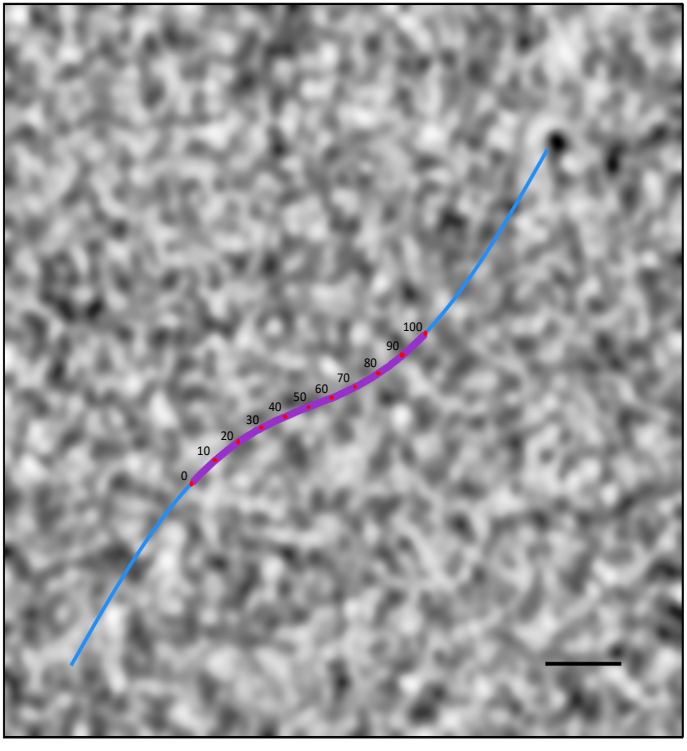


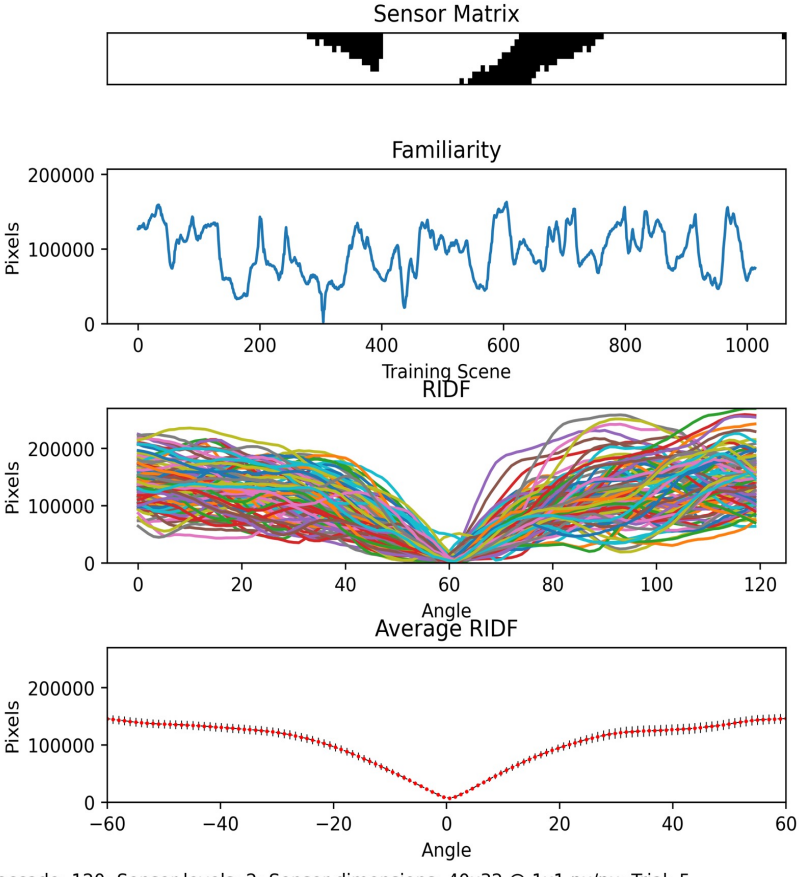


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 27.70; RMSD/dist: 0.069; TD: 97136; p90: 40; p50: 20; complete: 0

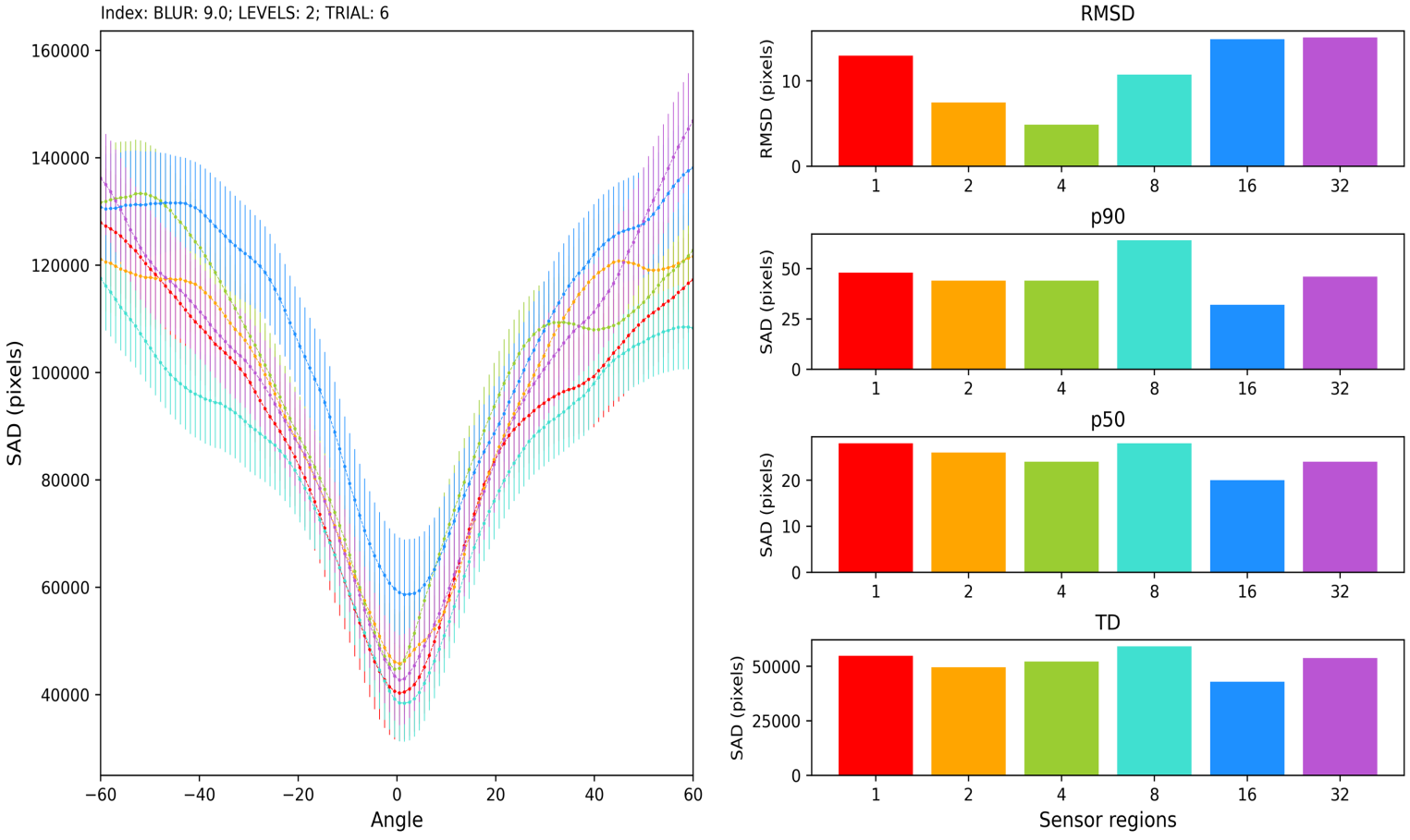
100%



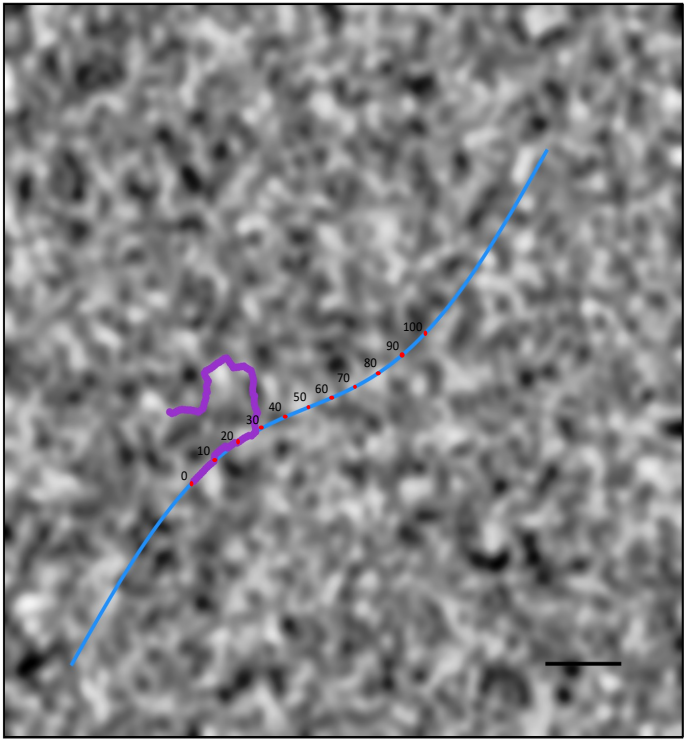


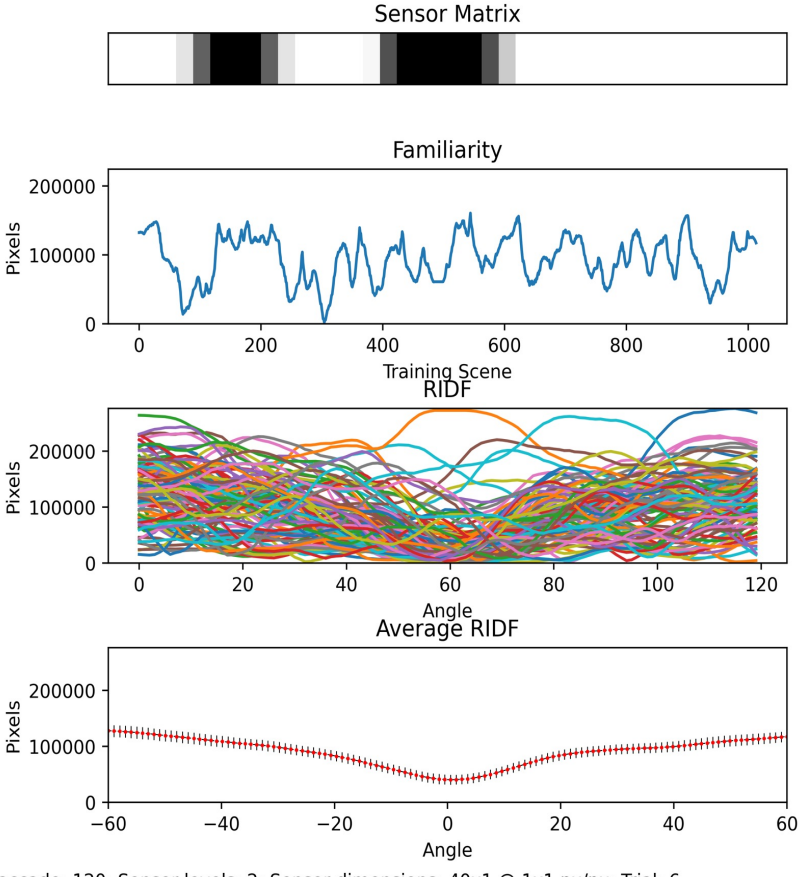
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 51.24; RMSD/dist: 0.128; TD: 92089; p90: 36; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 6
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
50
25
0
p50
SAD (pixels)
20
10
0
TD
SAD (pixels)
50000
25000
0
Sensor regions

10%

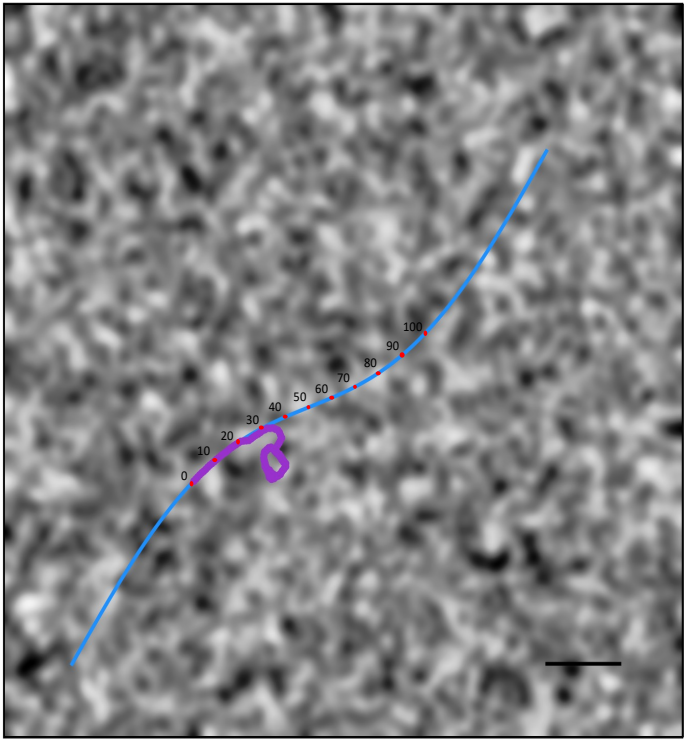


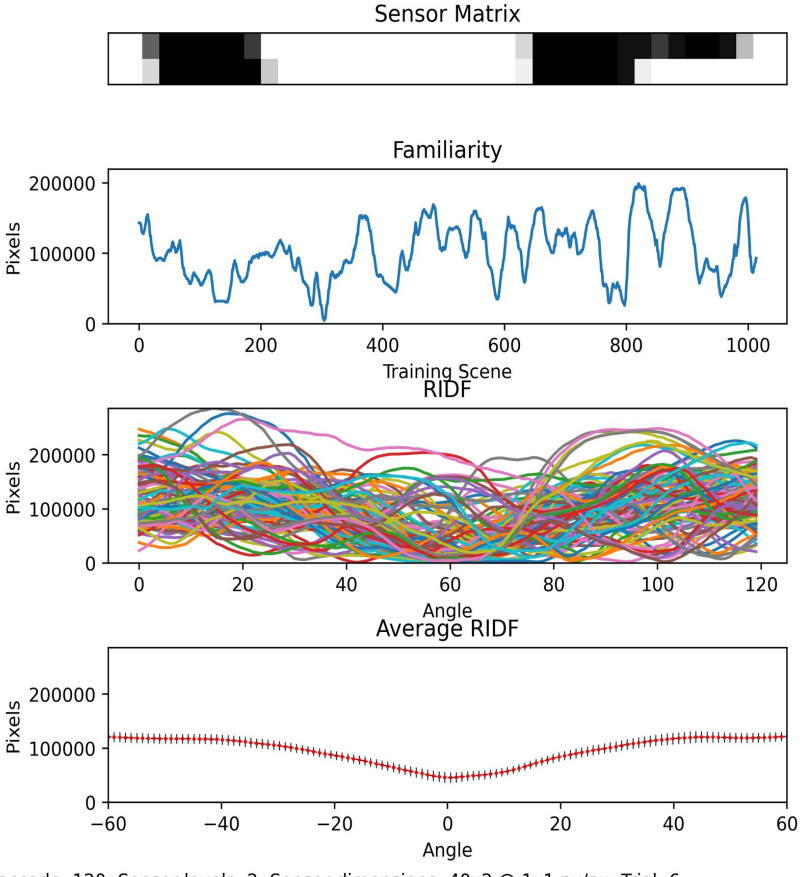


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 5185.29; RMSD/dist: 12.963; TD: 54796; p90: 48; p50: 28; complete: 0

20%

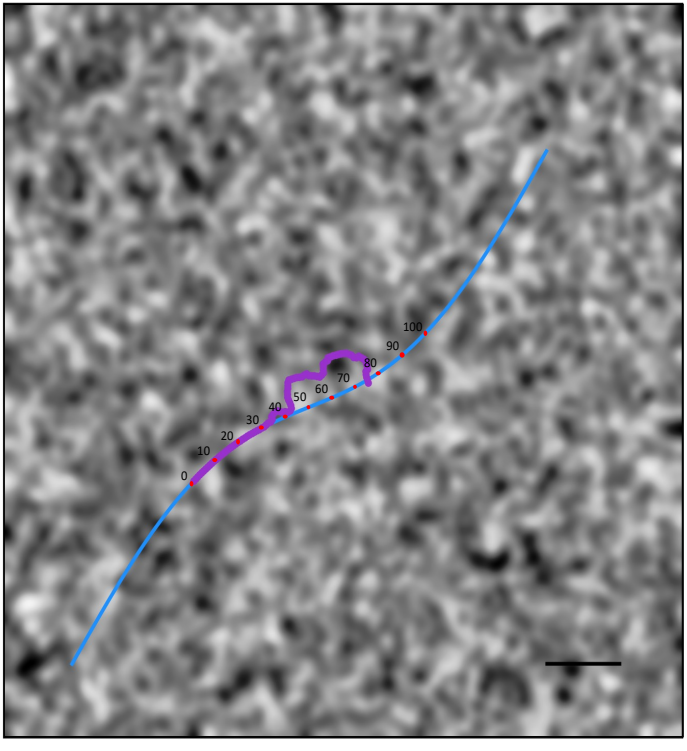


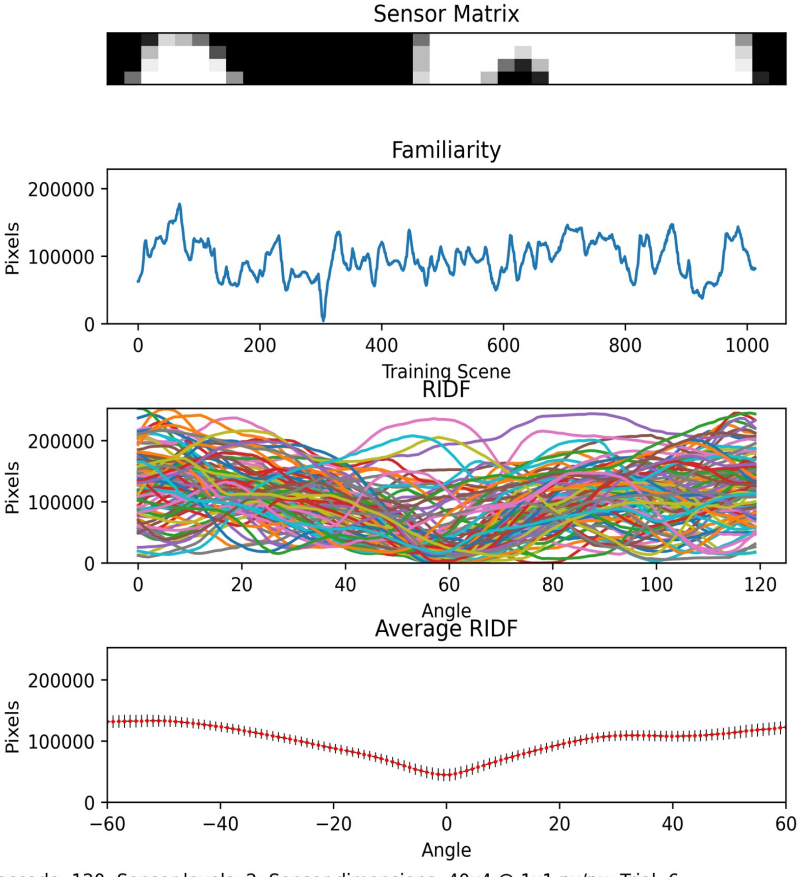


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2984.21; RMSD/dist: 7.461; TD: 49581; p90: 44; p50: 26; complete: 0

30%

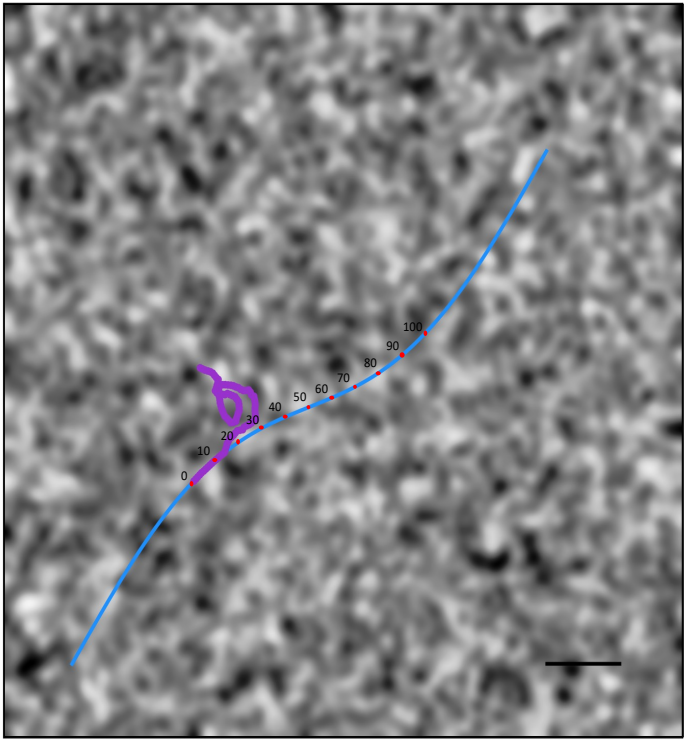


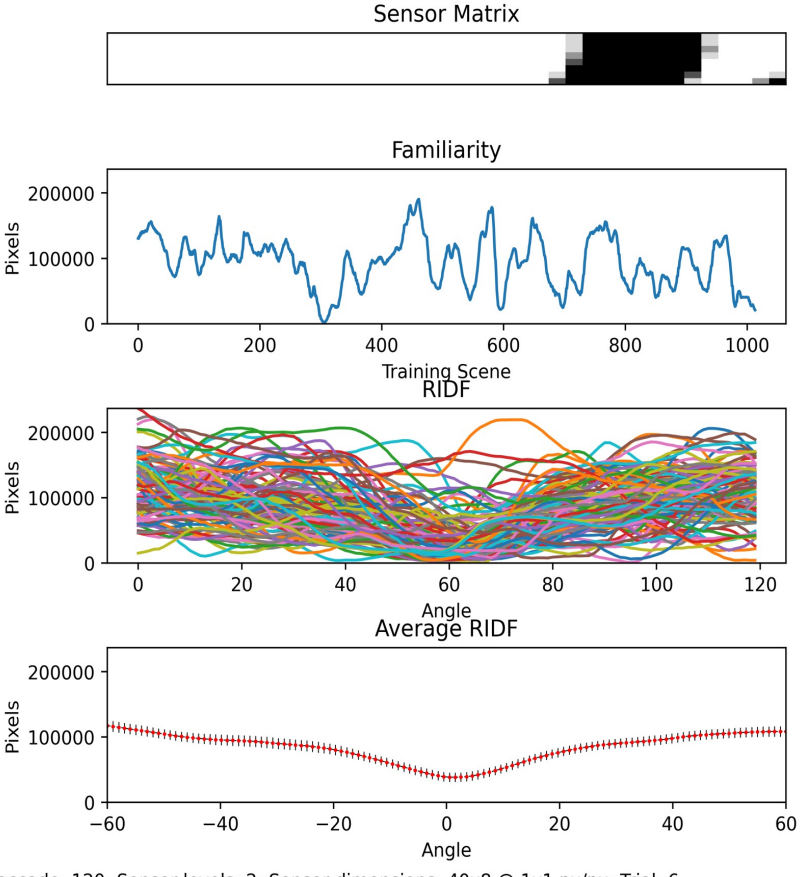


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1948.15; RMSD/dist: 4.870; TD: 52195; p90: 44; p50: 24; complete: 0

10%

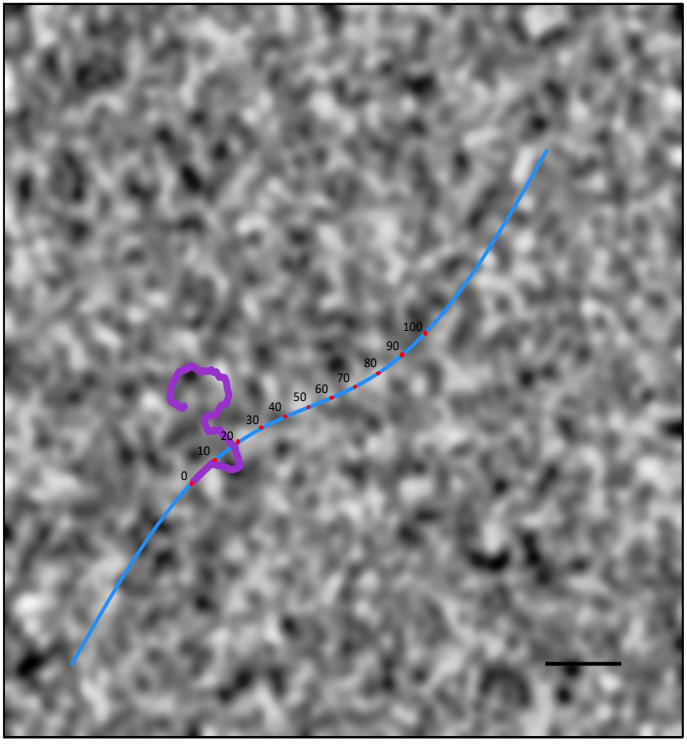


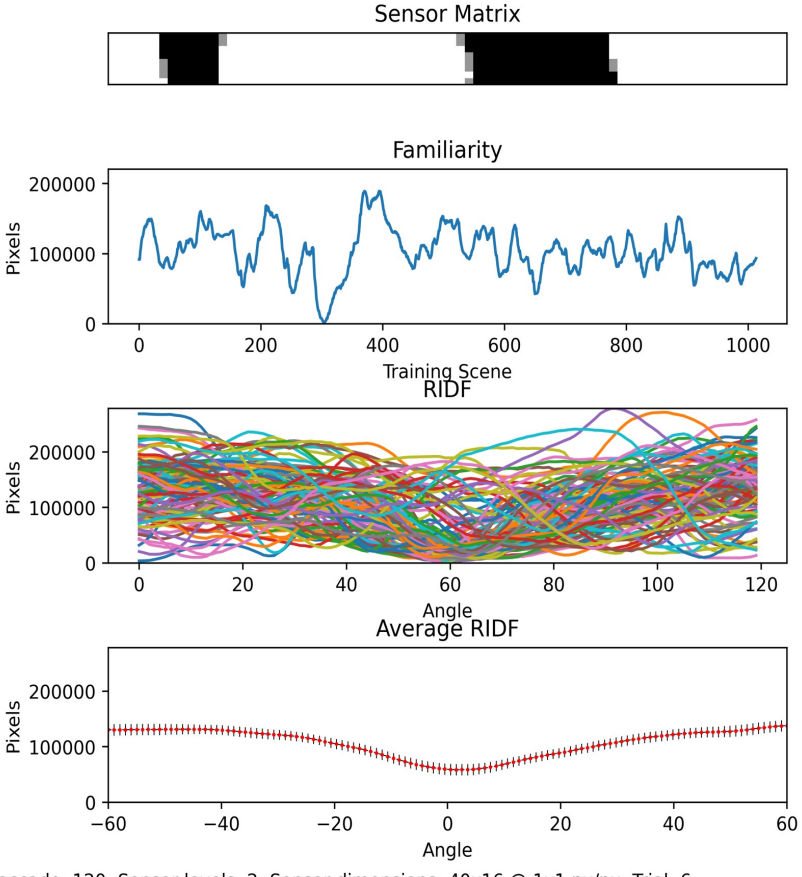


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4288.62; RMSD/dist: 10.722; TD: 59146; p90: 64; p50: 28; complete: 0

10%

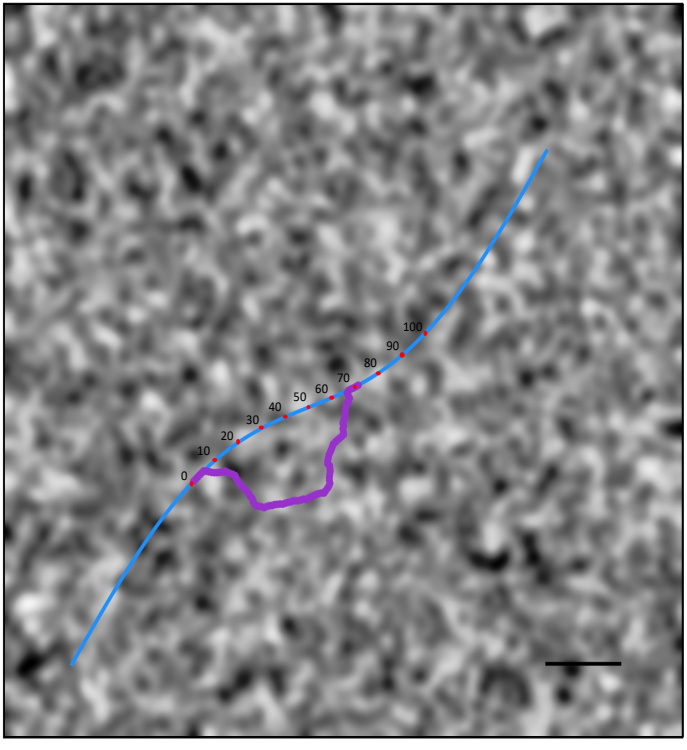


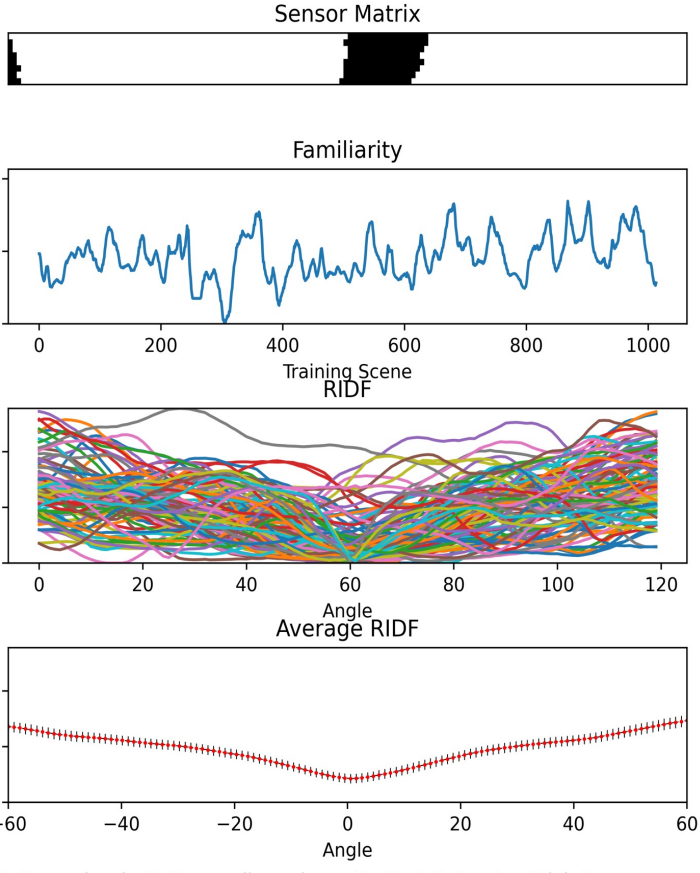


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 5949.29; RMSD/dist: 14.873; TD: 42954; p90: 32; p50: 20; complete: 0

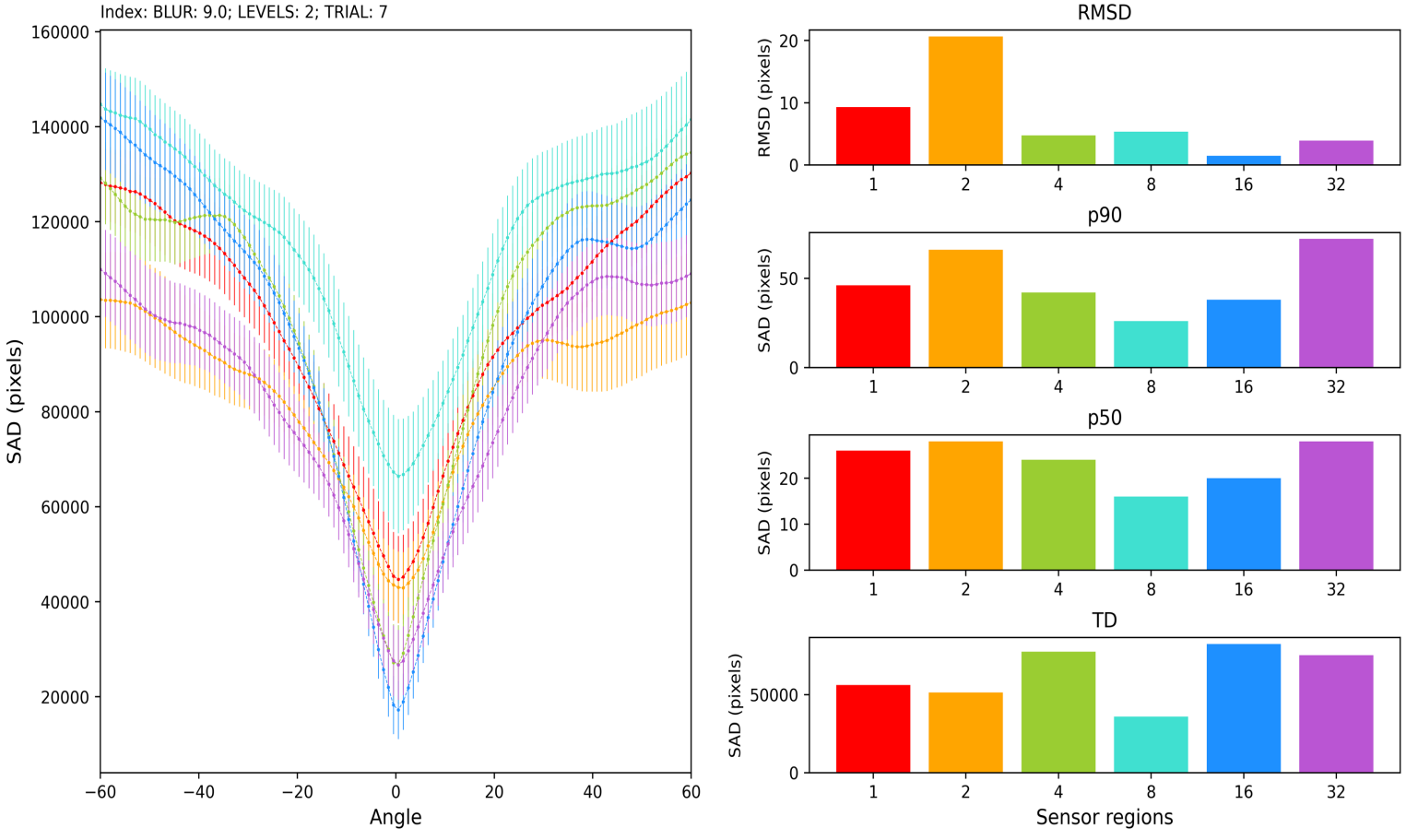
0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 6036.39; RMSD/dist: 15.091; TD: 53819; p90: 46; p50: 24; complete: 0


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 7
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
p90
SAD (pixels)
50
0
p50
SAD (pixels)
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SAD (pixels)
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0
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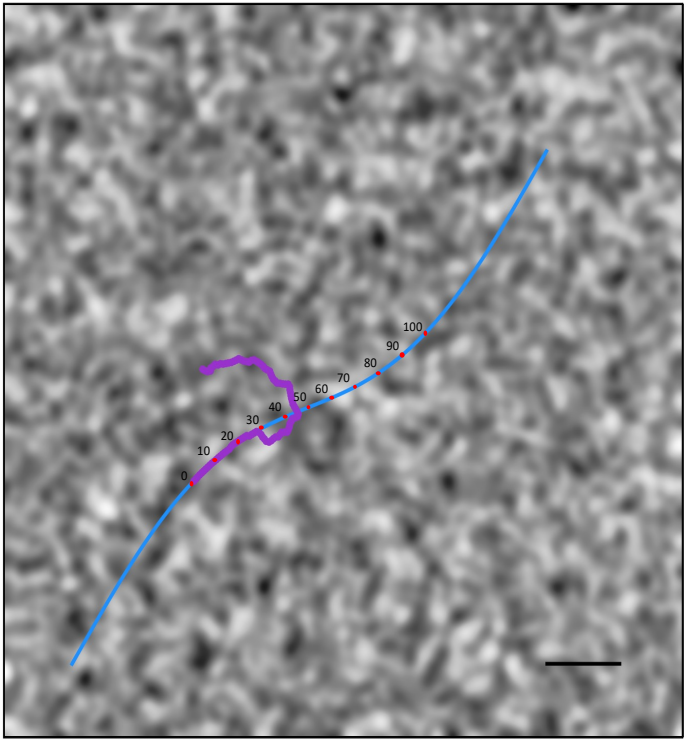
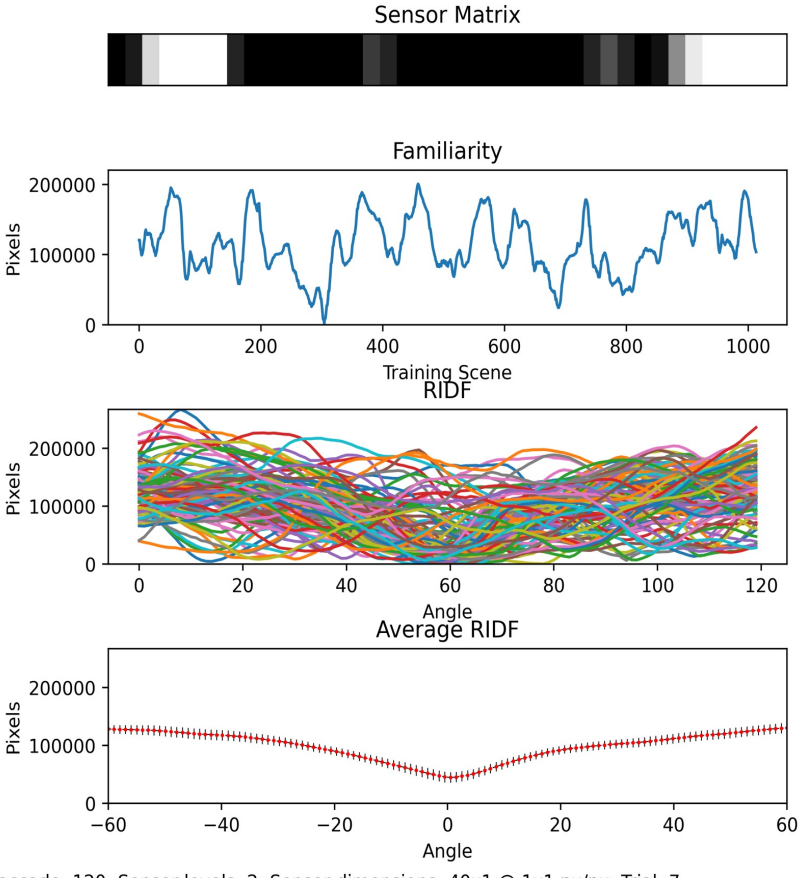
2
4
8
16
32
Sensor regions

20%

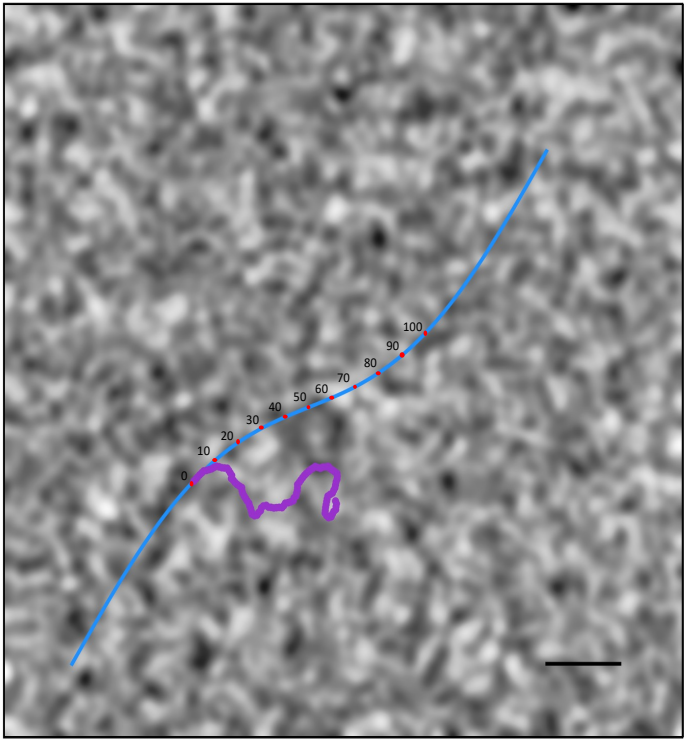


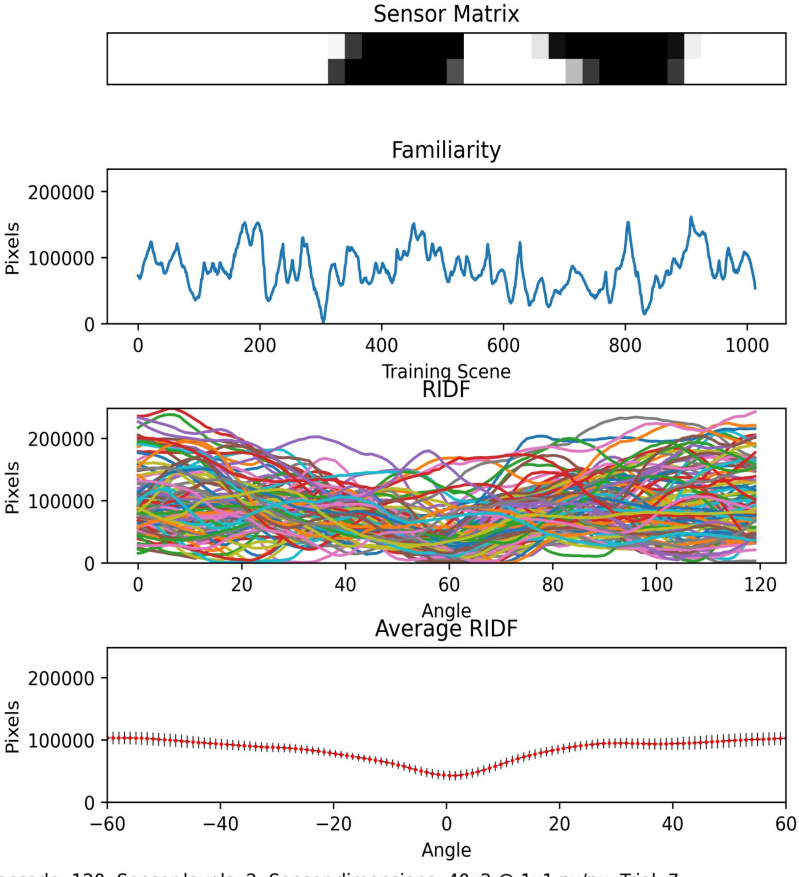


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3728.39; RMSD/dist: 9.321; TD: 56135; p90: 46; p50: 26; complete: 0

0%

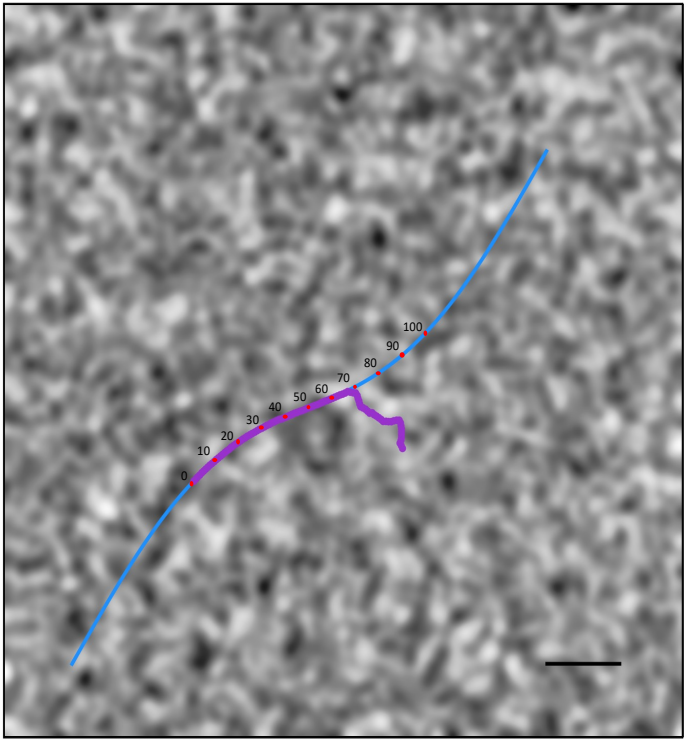


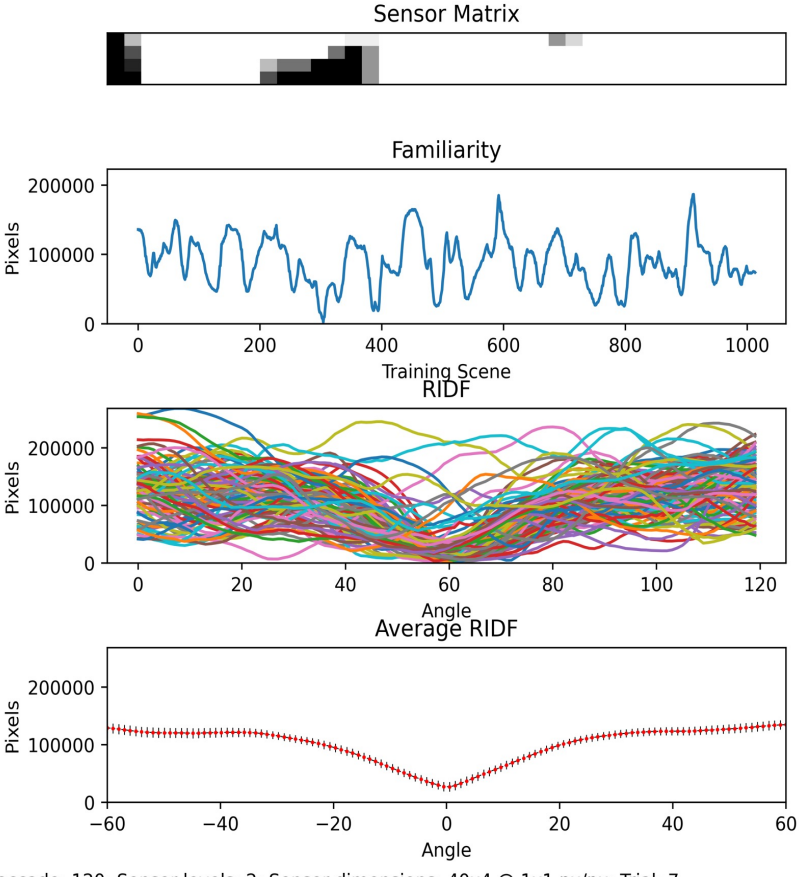


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 8267.09; RMSD/dist: 20.668; TD: 51425; p90: 66; p50: 28; complete: 0

60%

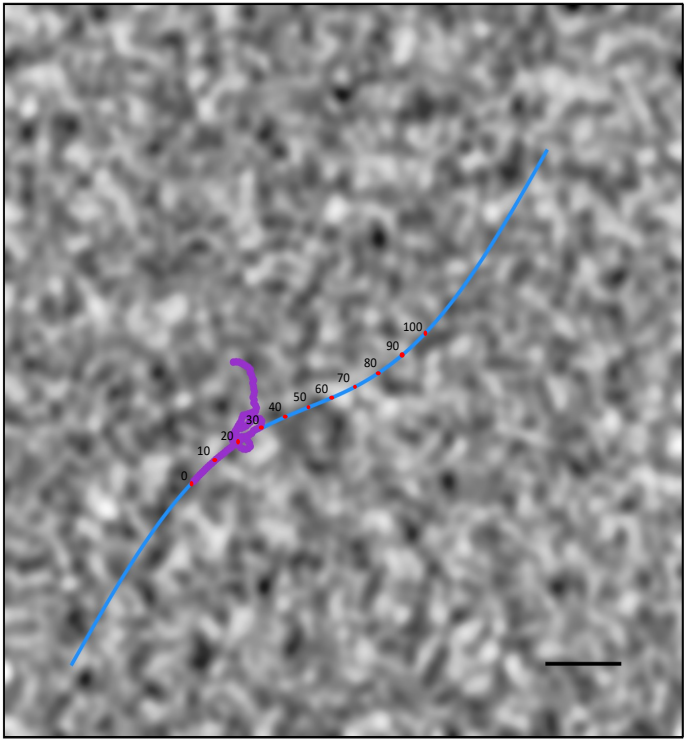


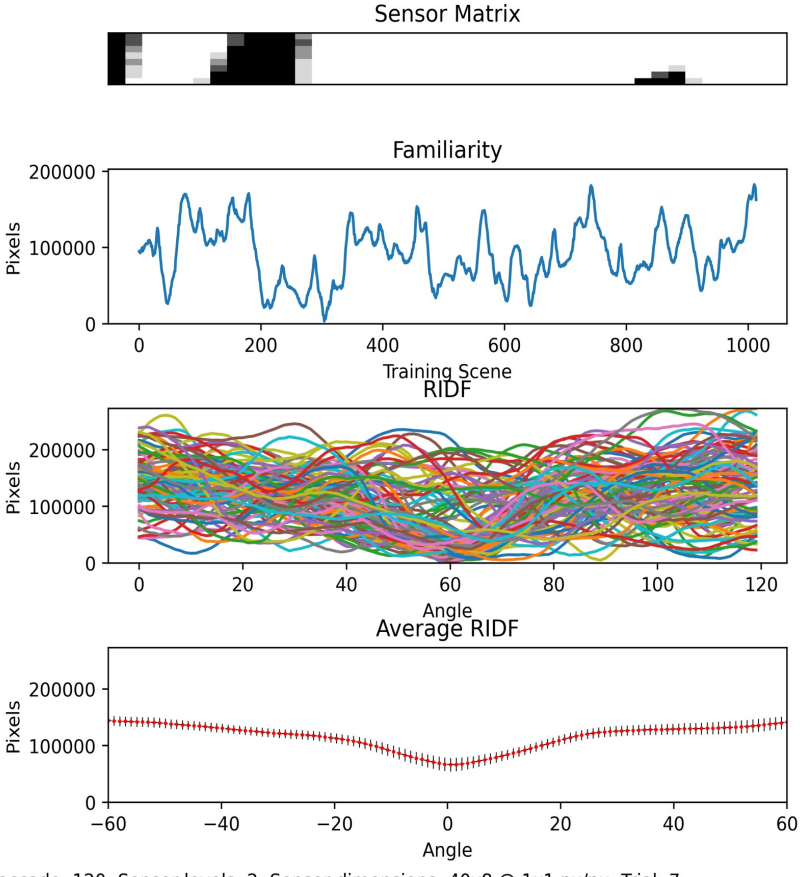


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1903.78; RMSD/dist: 4.759; TD: 77510; p90: 42; p50: 24; complete: 0

30%

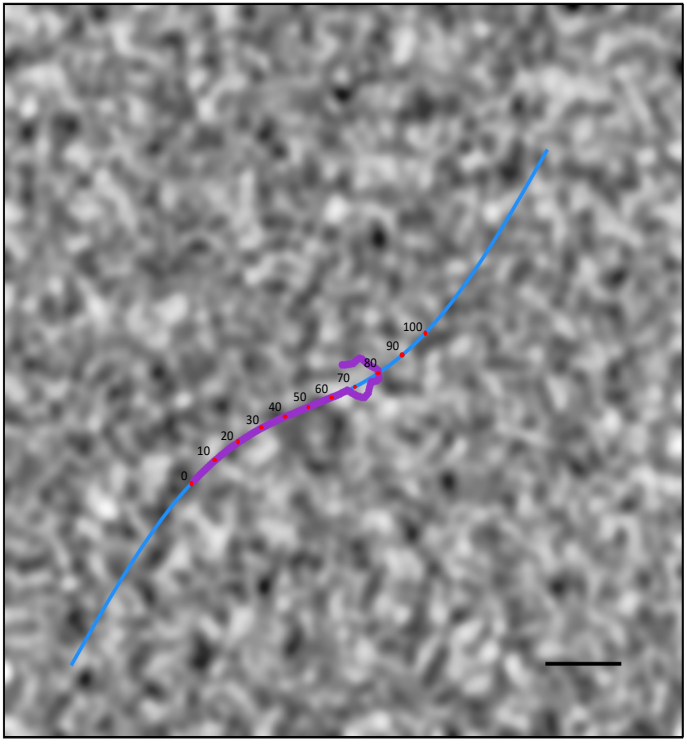


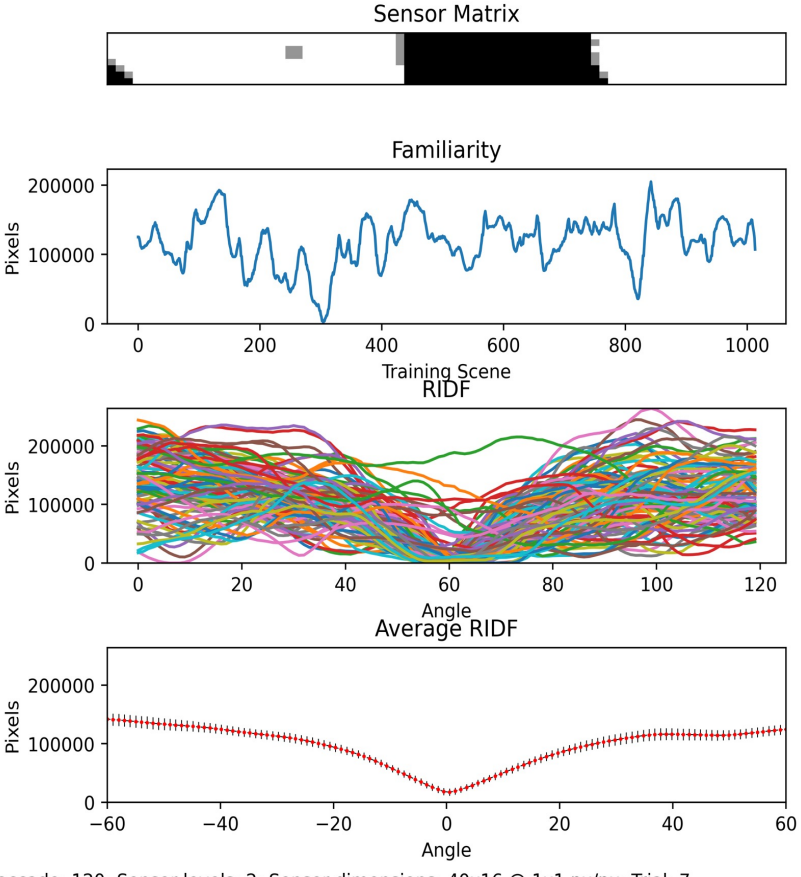


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2140.26; RMSD/dist: 5.351; TD: 35990; p90: 26; p50: 16; complete: 0

60%

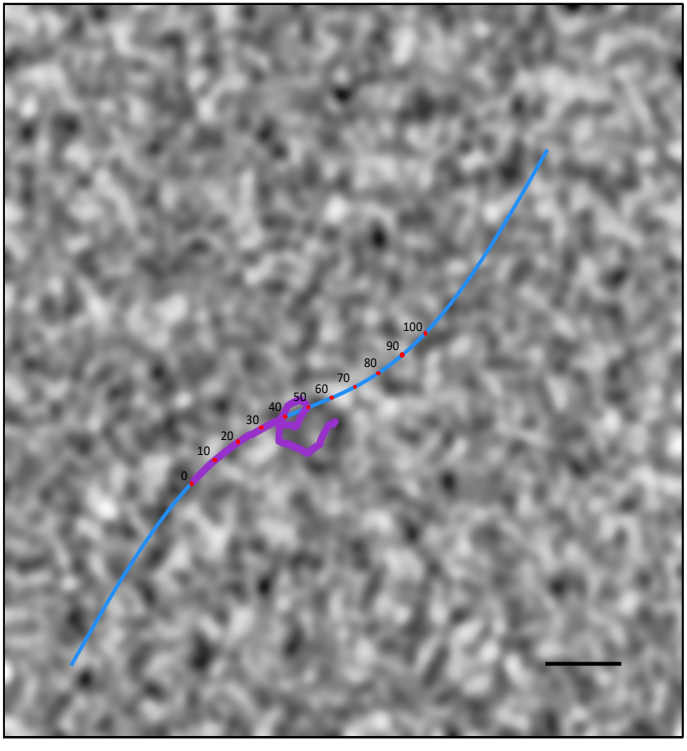


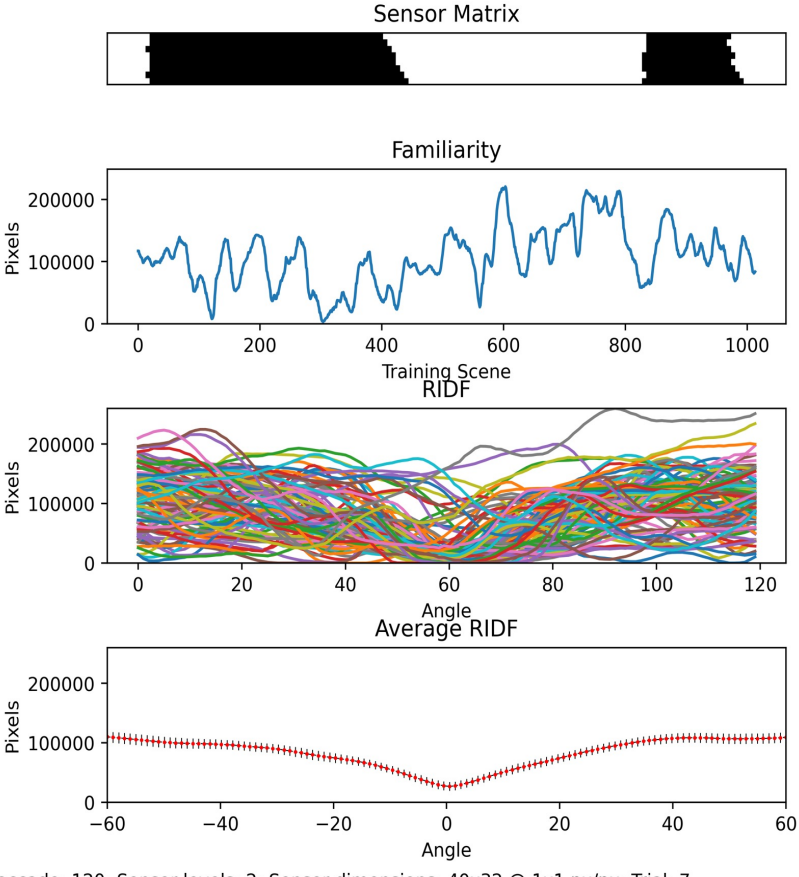


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 593.67; RMSD/dist: 1.484; TD: 82470; p90: 38; p50: 20; complete: 0

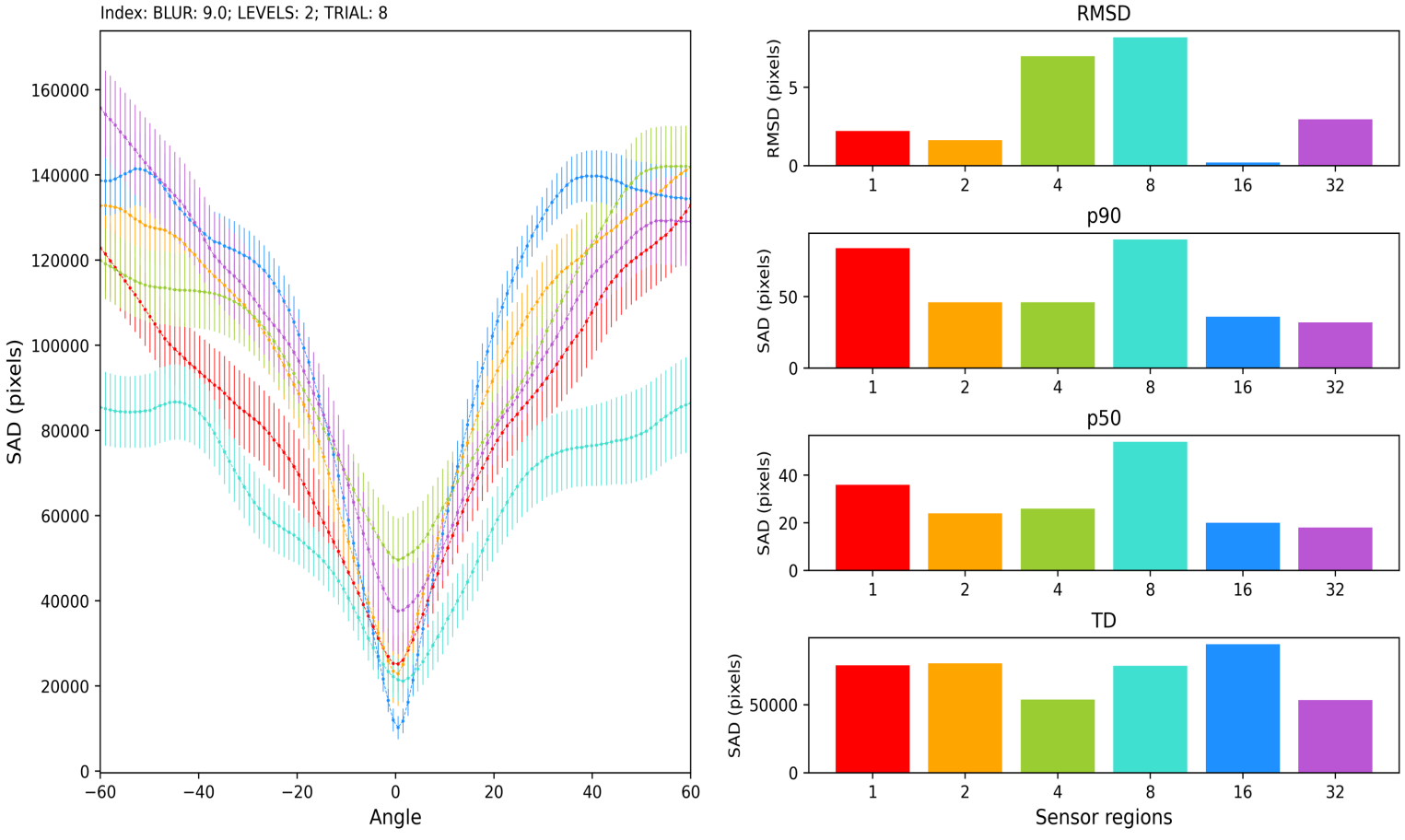
40%



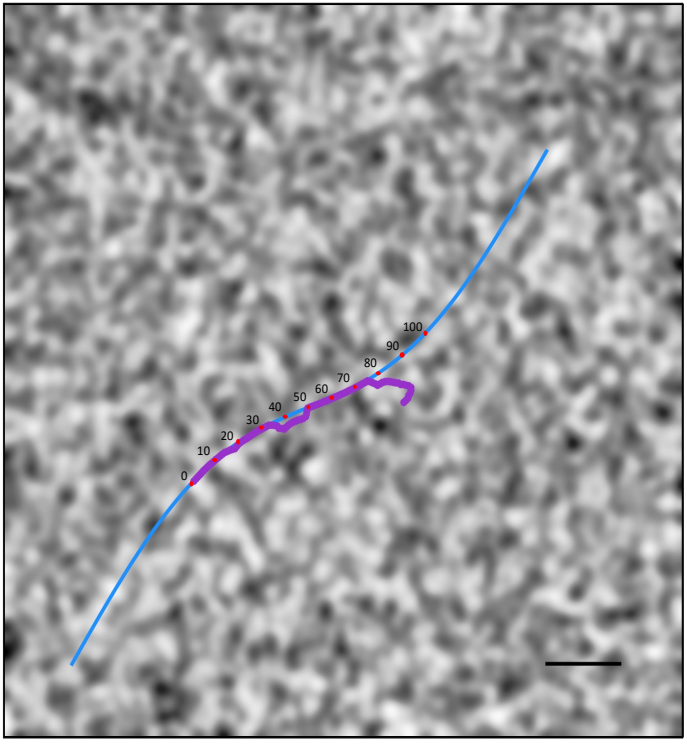


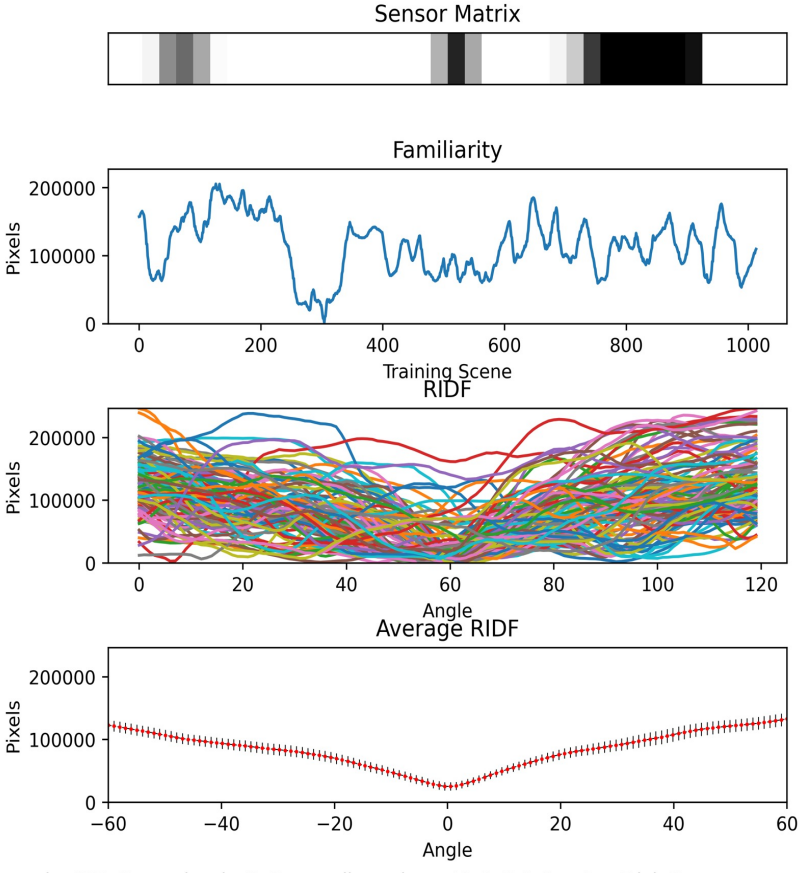
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1570.06; RMSD/dist: 3.925; TD: 75285; p90: 72; p50: 28; complete: 0


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

50%

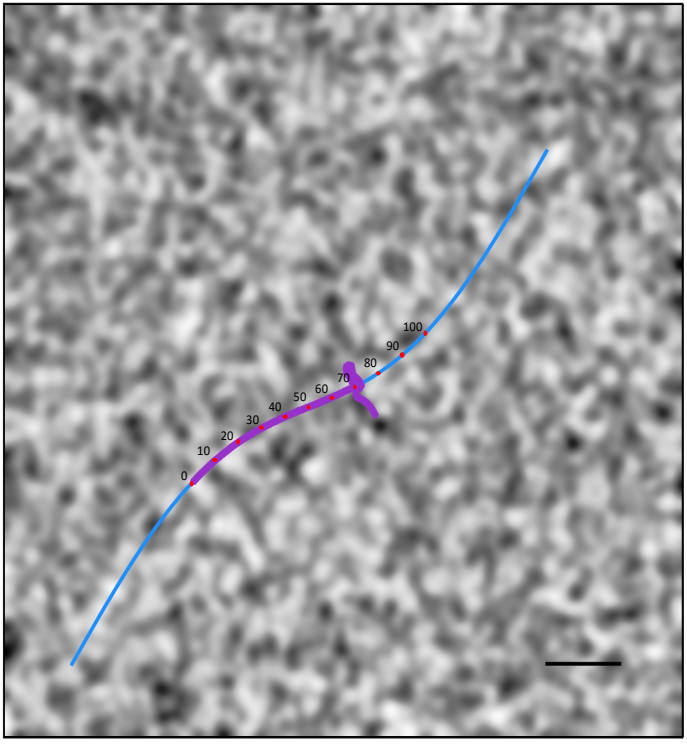


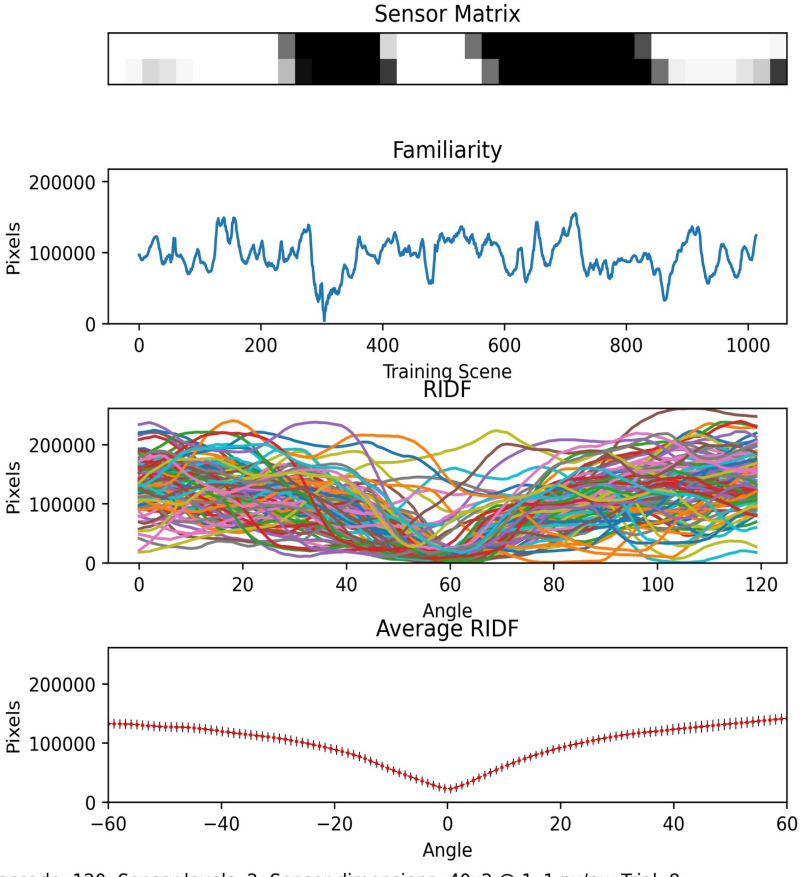


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 884.80; RMSD/dist: 2.212; TD: 78972; p90: 84; p50: 36; complete: 0

70%

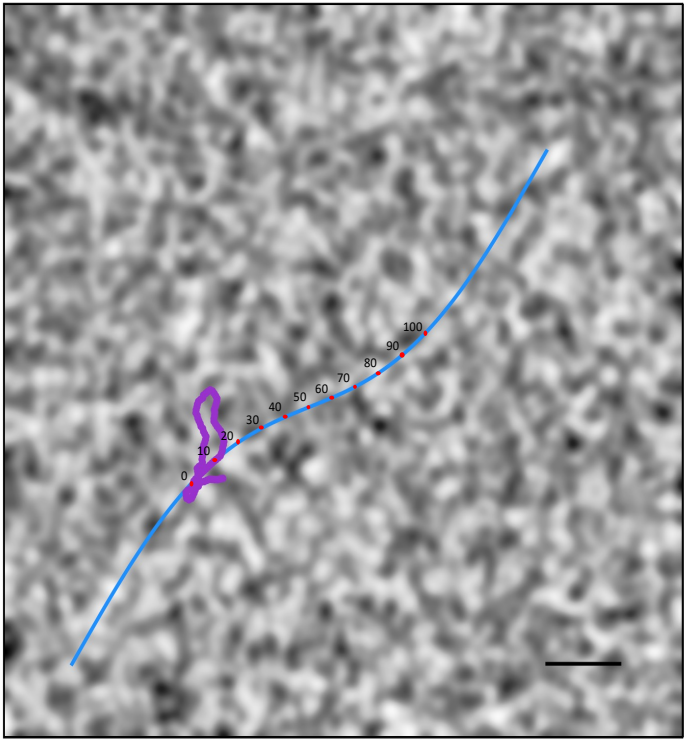


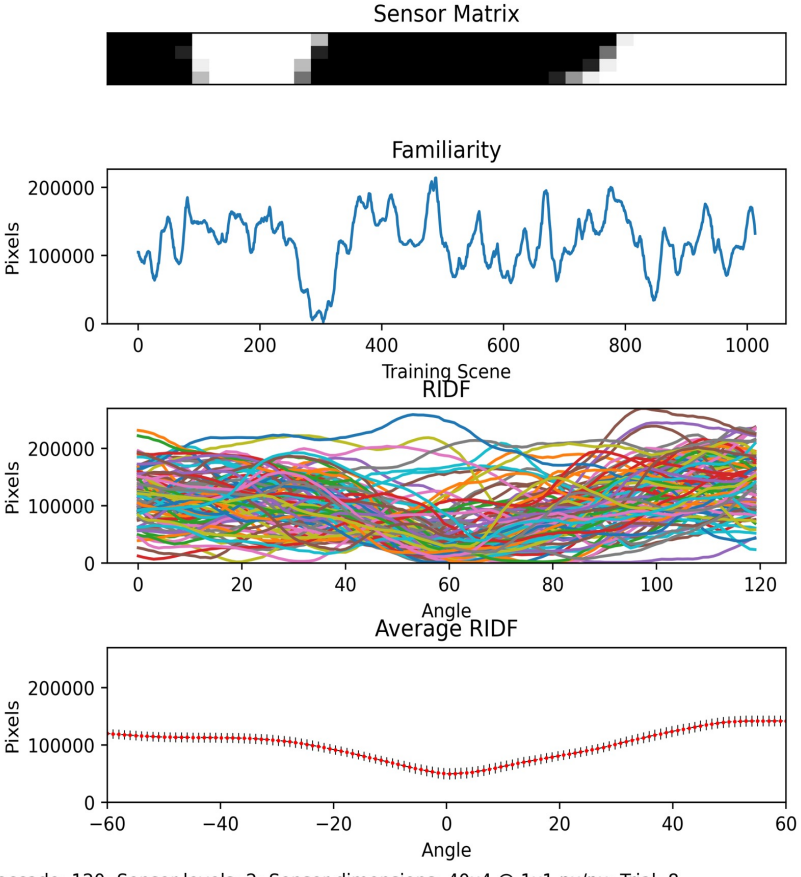


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 649.18; RMSD/dist: 1.623; TD: 80520; p90: 46; p50: 24; complete: 0

10%

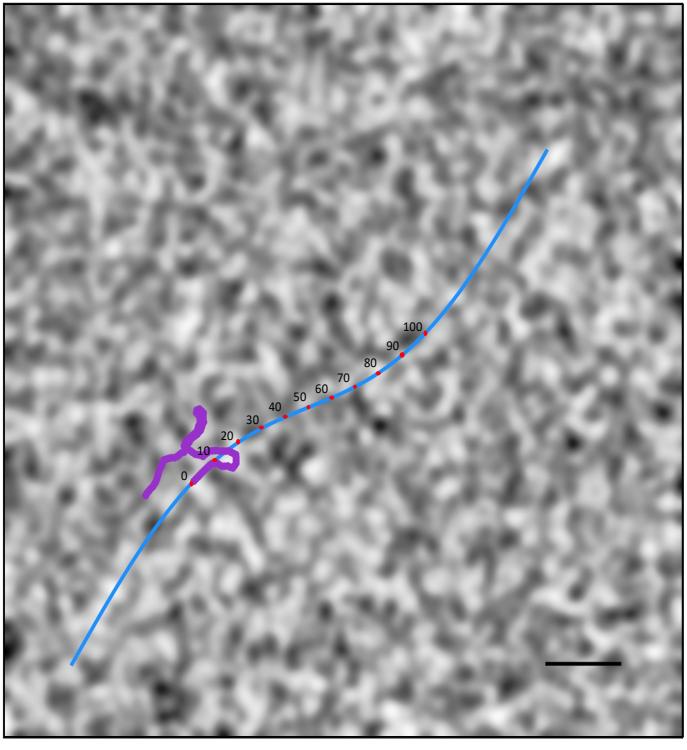


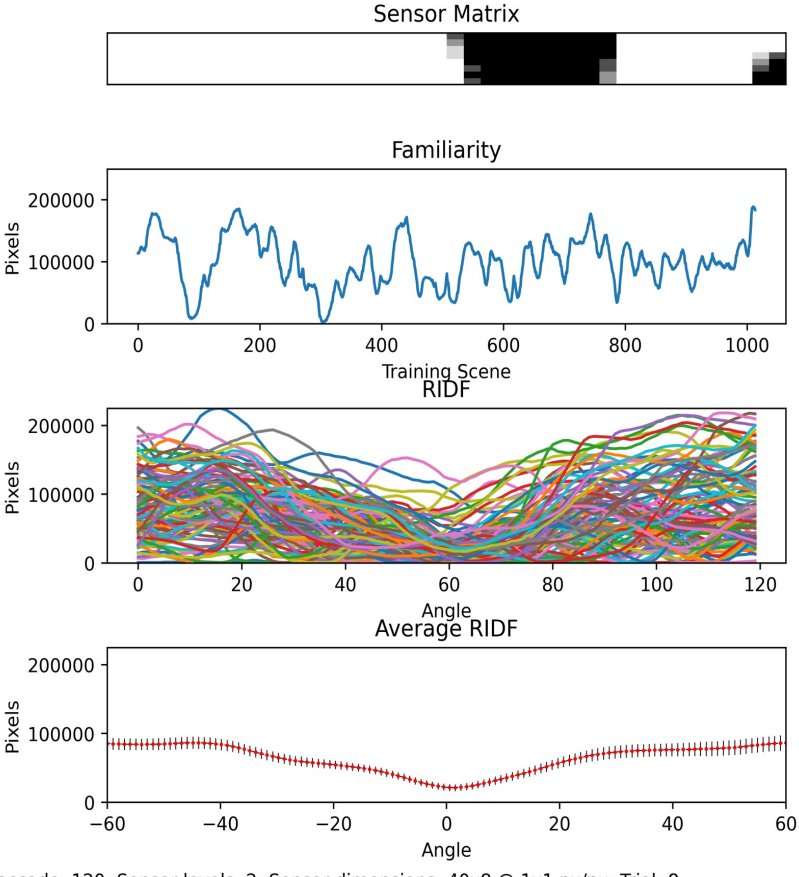


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2791.48; RMSD/dist: 6.979; TD: 53877; p90: 46; p50: 26; complete: 0

10%

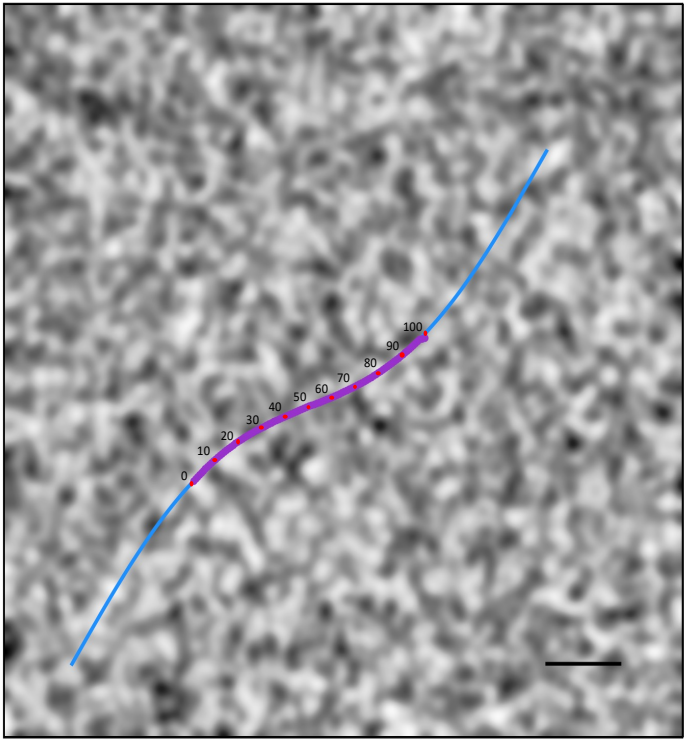


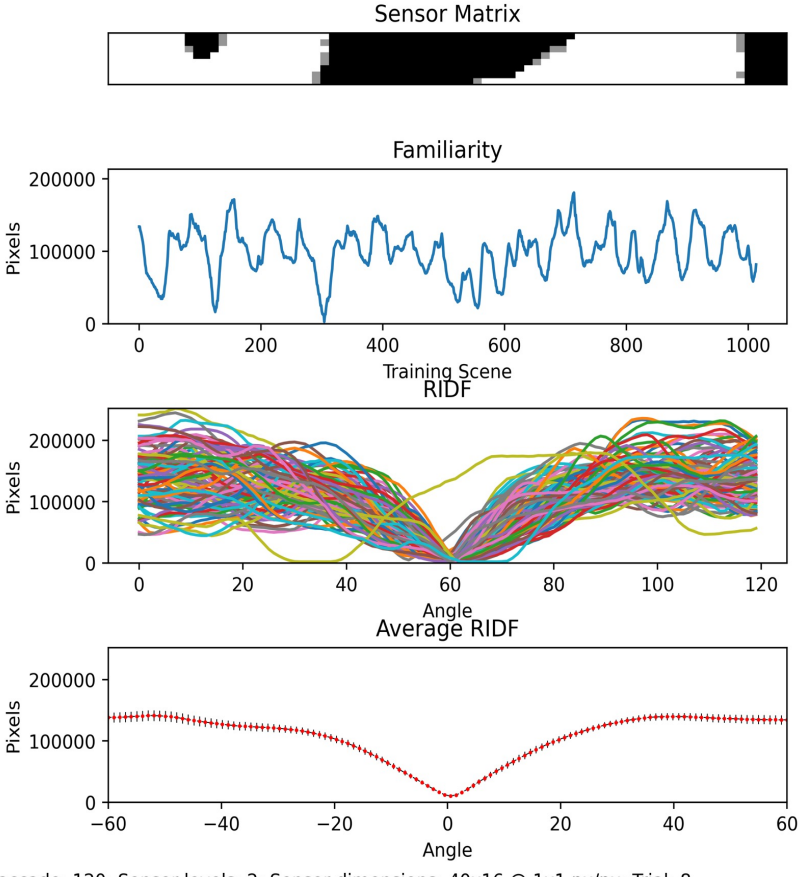


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3277.87; RMSD/dist: 8.195; TD: 78615; p90: 90; p50: 54; complete: 0

90%

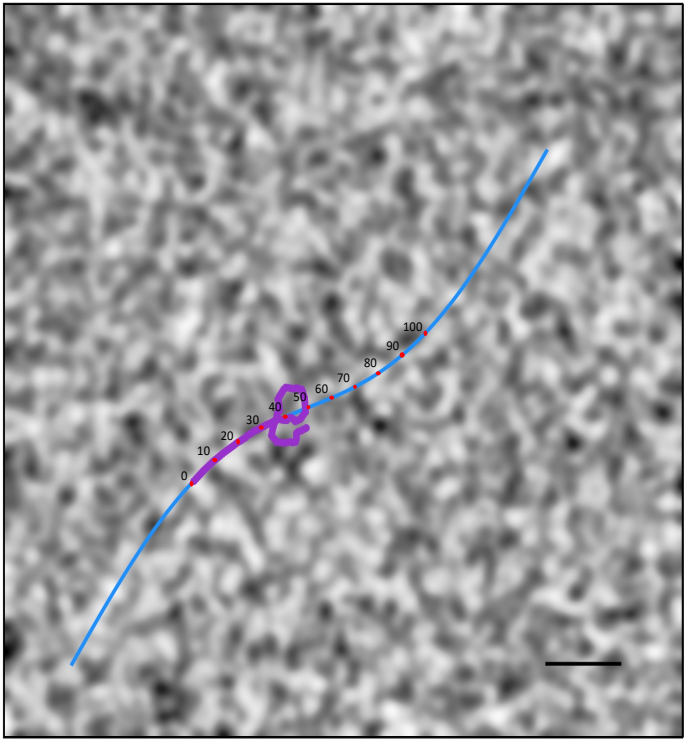


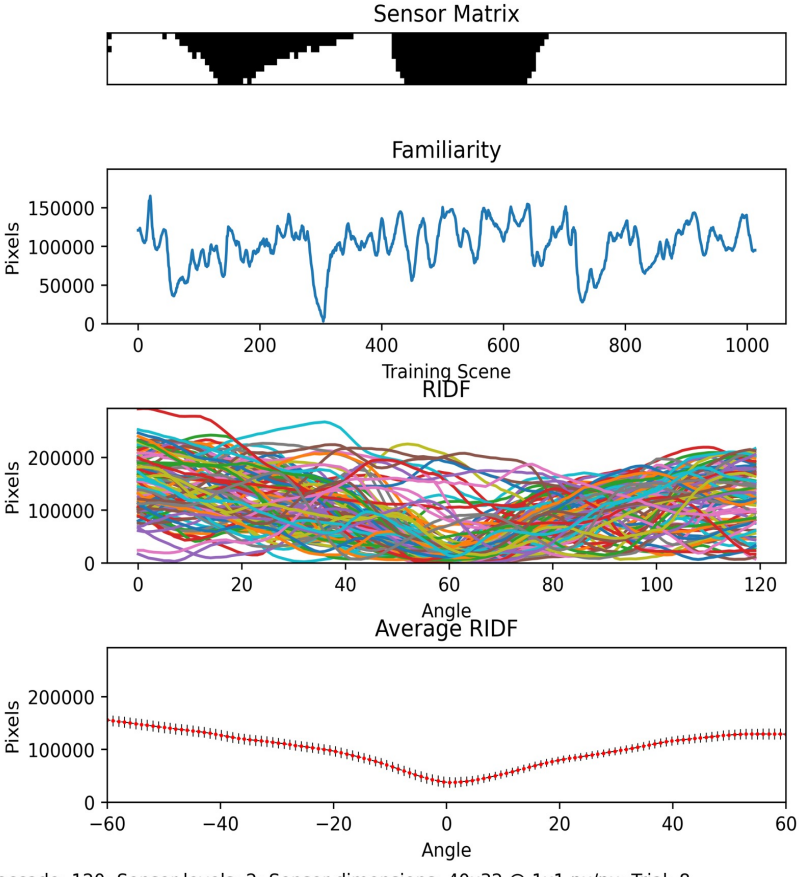


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 83.64; RMSD/dist: 0.209; TD: 94506; p90: 36; p50: 20; complete: 0

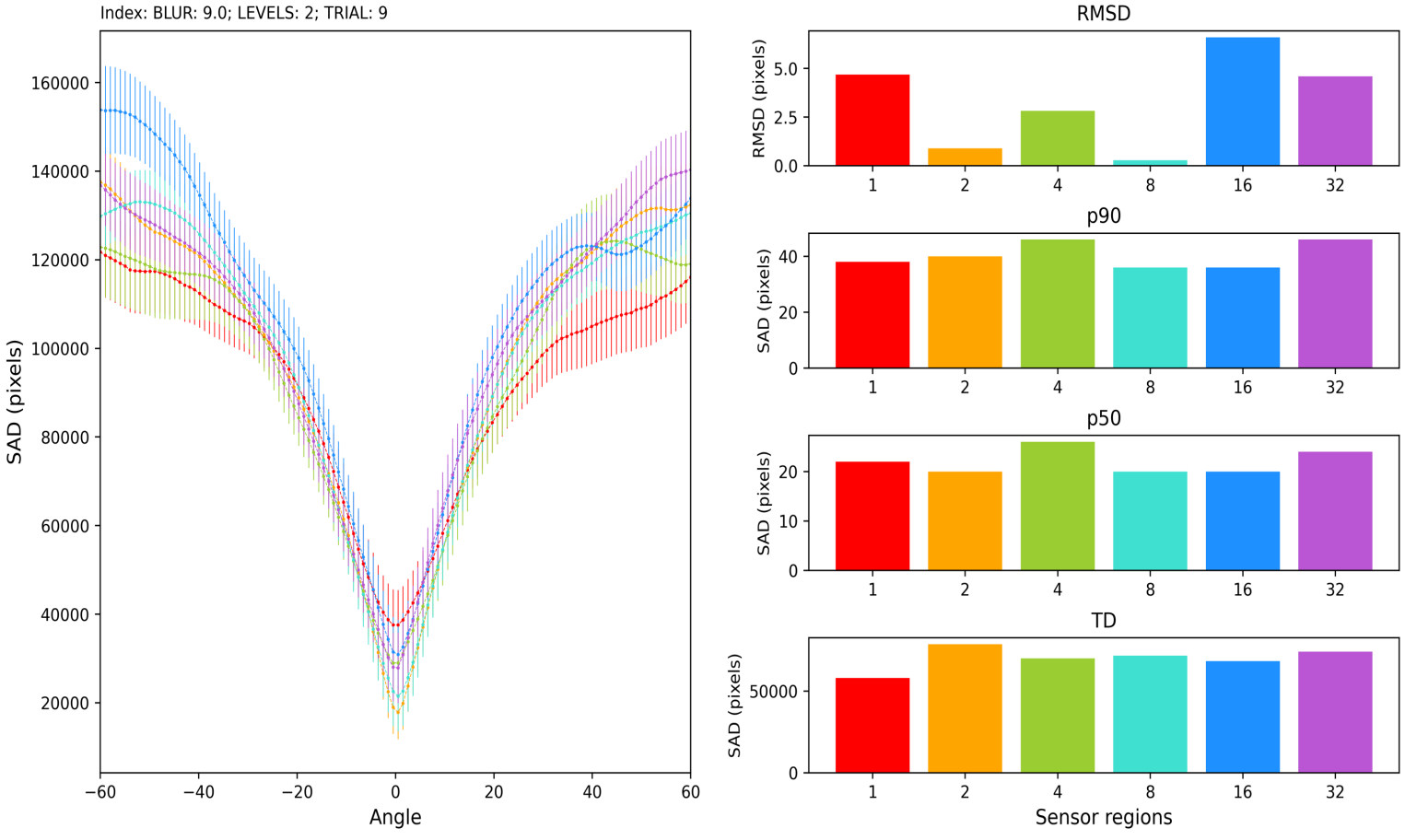
40%



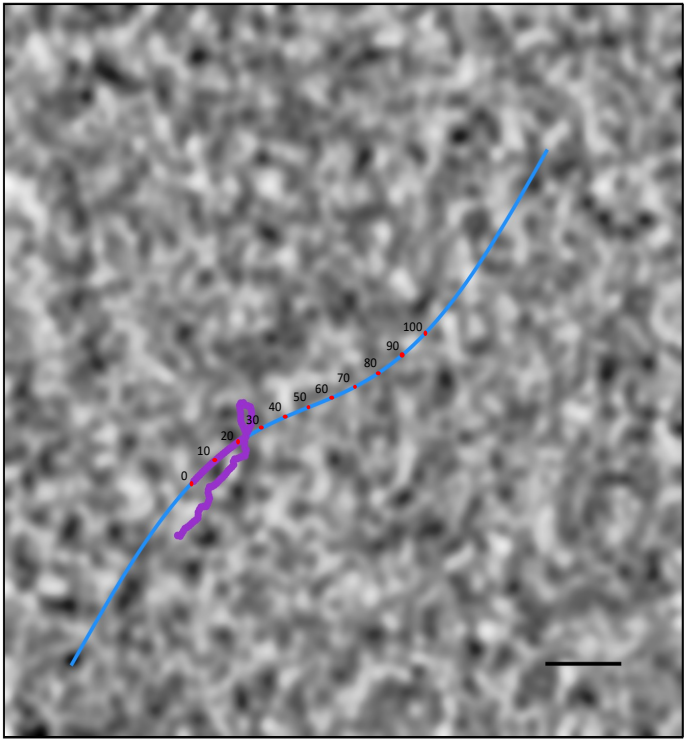


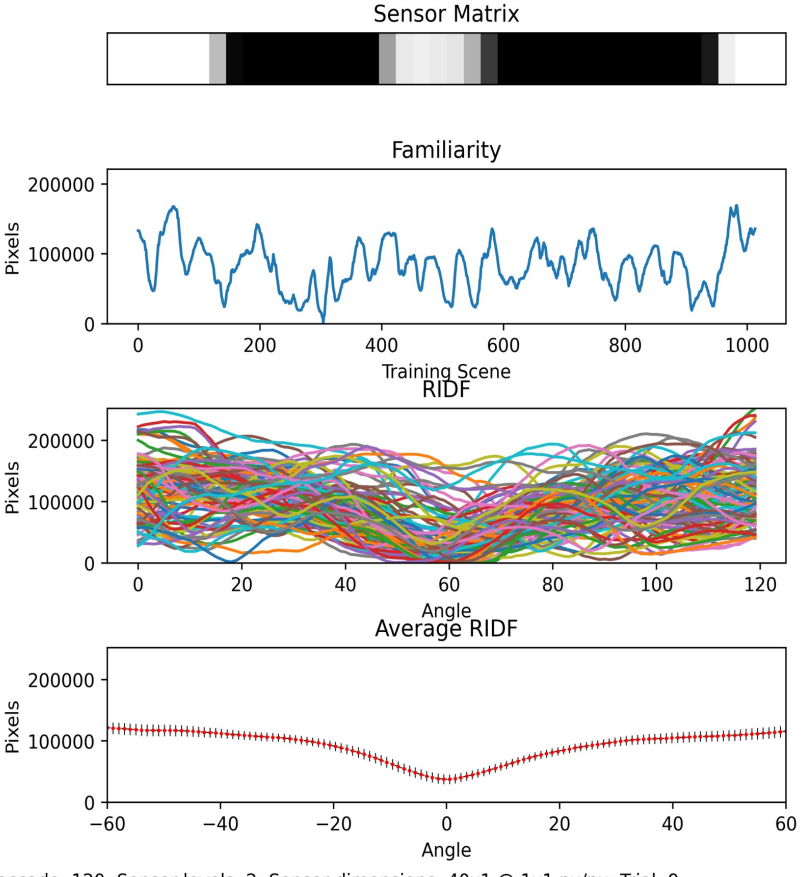
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1185.92; RMSD/dist: 2.965; TD: 53525; p90: 32; p50: 18; complete: 0


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 9
SAD (pixels)
160000
140000
120000
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
5.0
2.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
40
20
0
p50
SAD (pixels)
20
10
0
TD
SAD (pixels)
50000
0
Sensor regions

20%

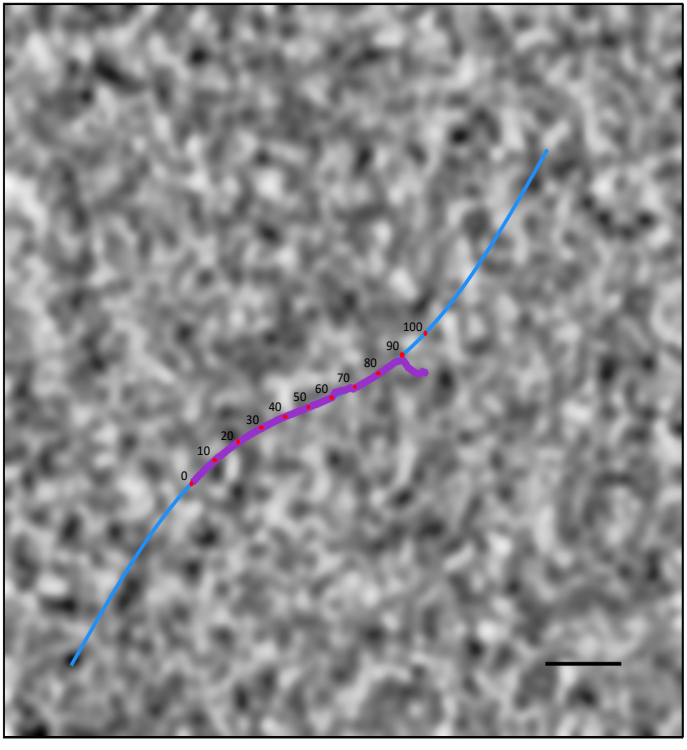


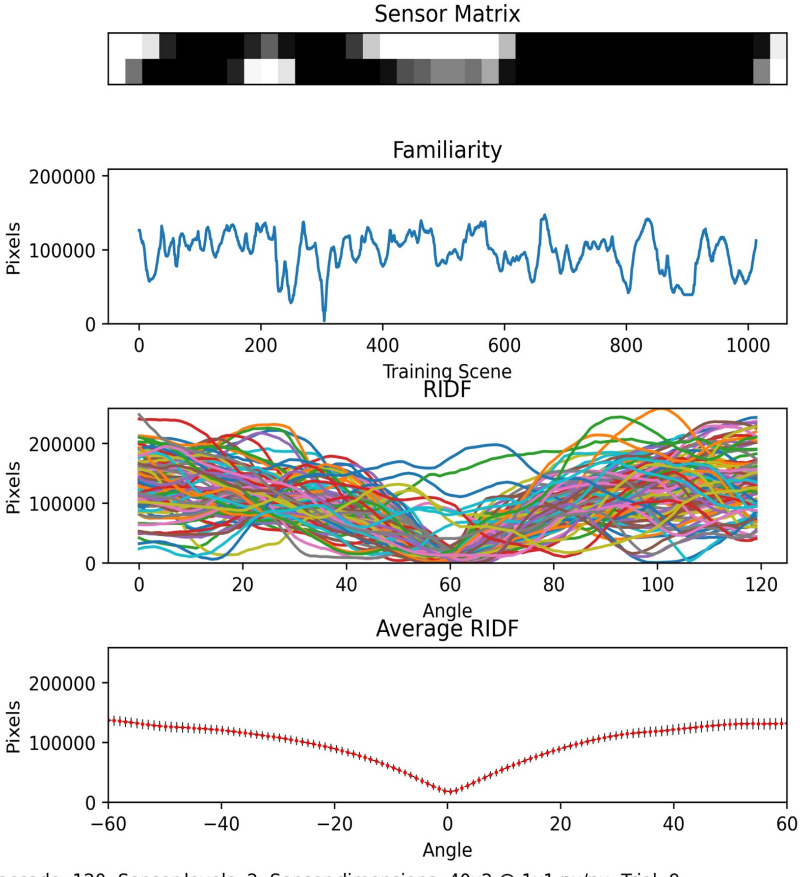


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1875.11; RMSD/dist: 4.688; TD: 58027; p90: 38; p50: 22; complete: 0

80%

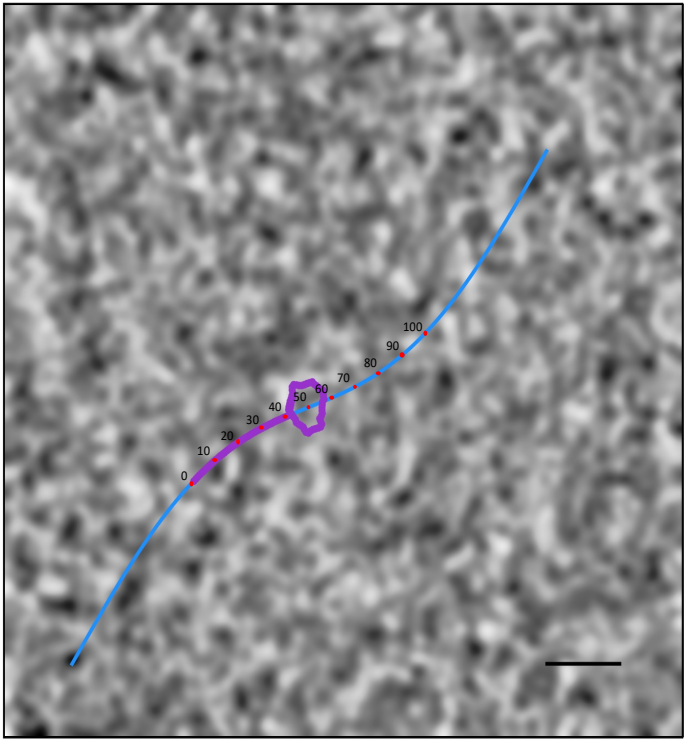


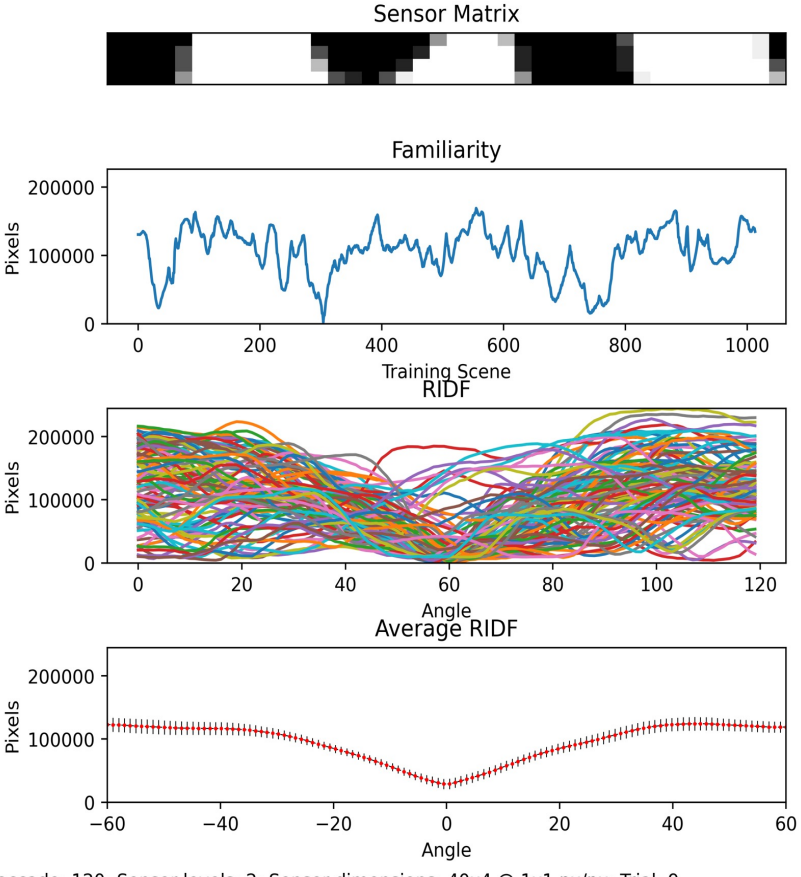


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 355.67; RMSD/dist: 0.889; TD: 78665; p90: 40; p50: 20; complete: 0

40%

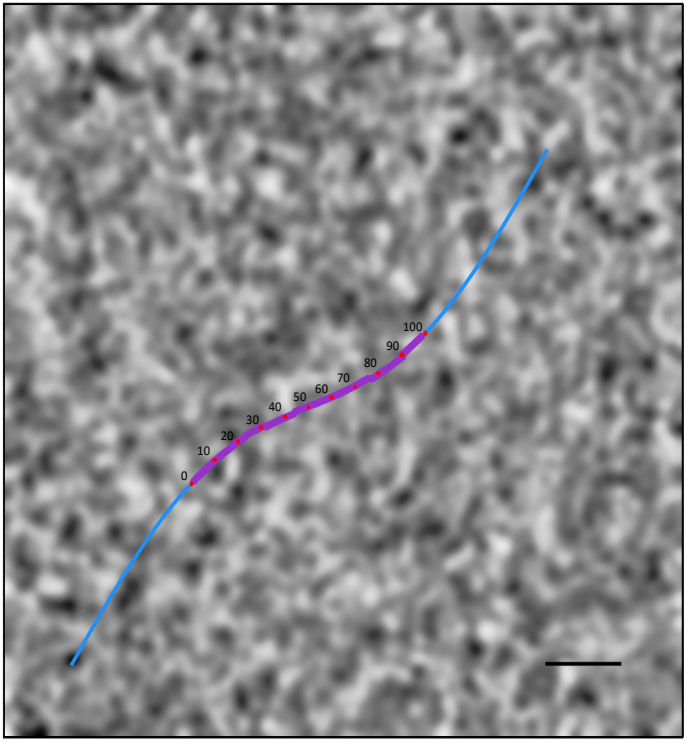


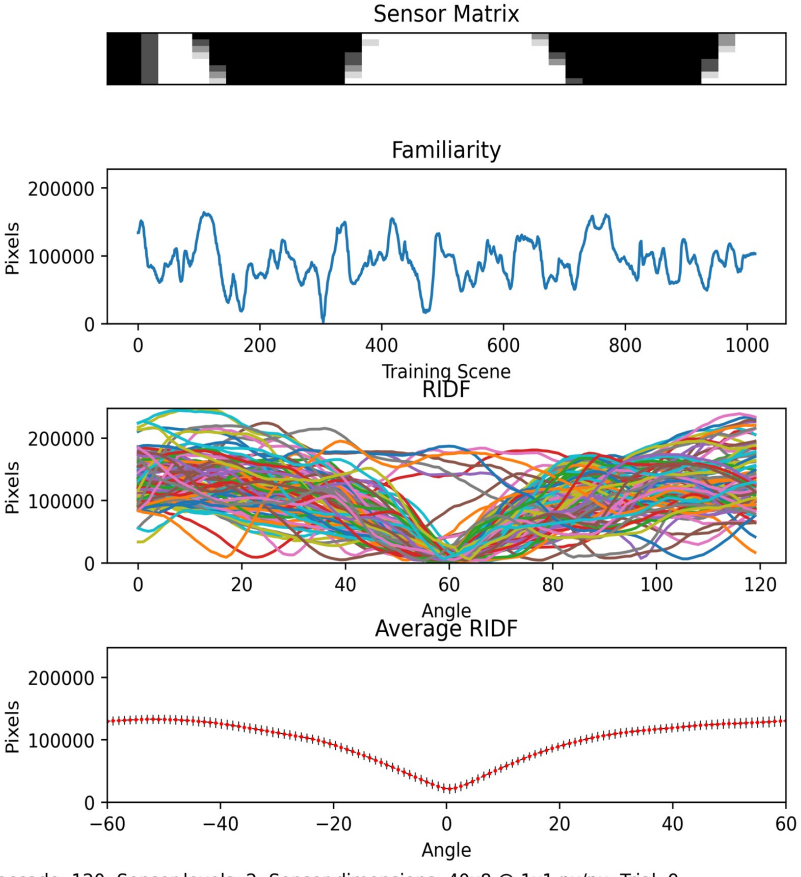


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1127.72; RMSD/dist: 2.819; TD: 70046; p90: 46; p50: 26; complete: 0

90%

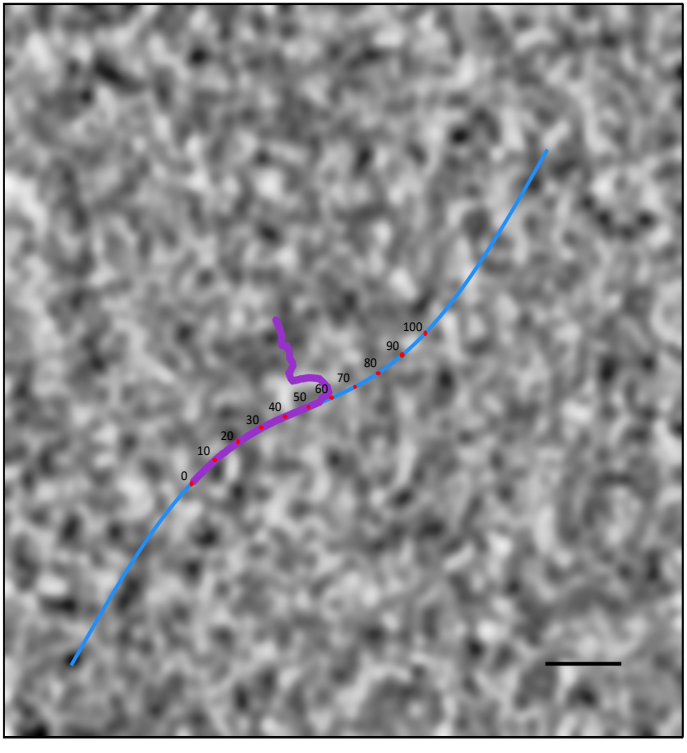


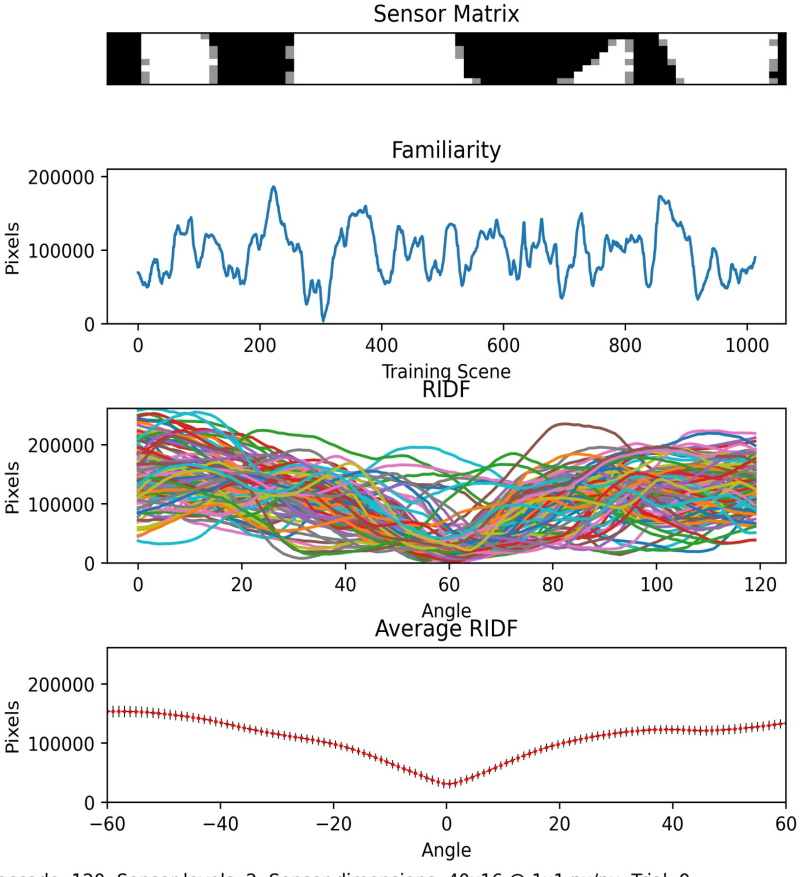


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 109.86; RMSD/dist: 0.275; TD: 71749; p90: 36; p50: 20; complete: 0

50%

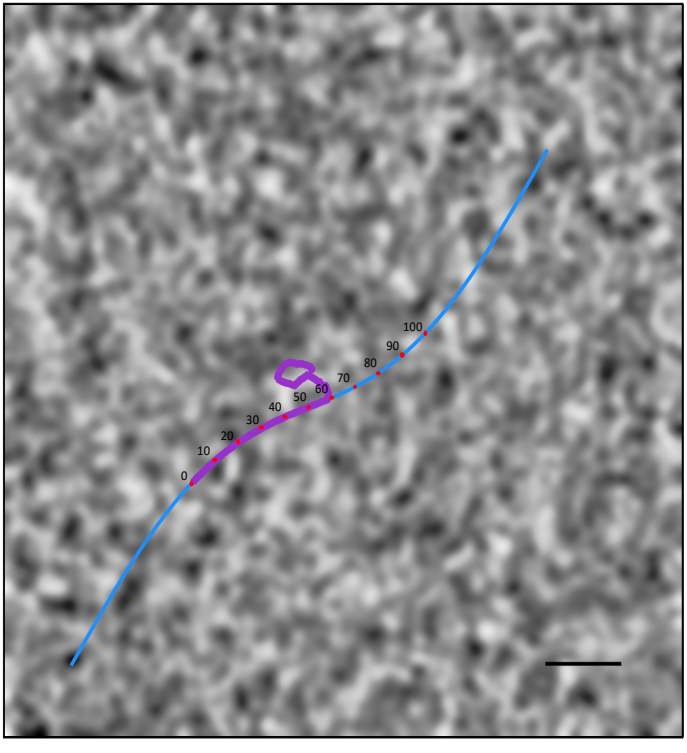


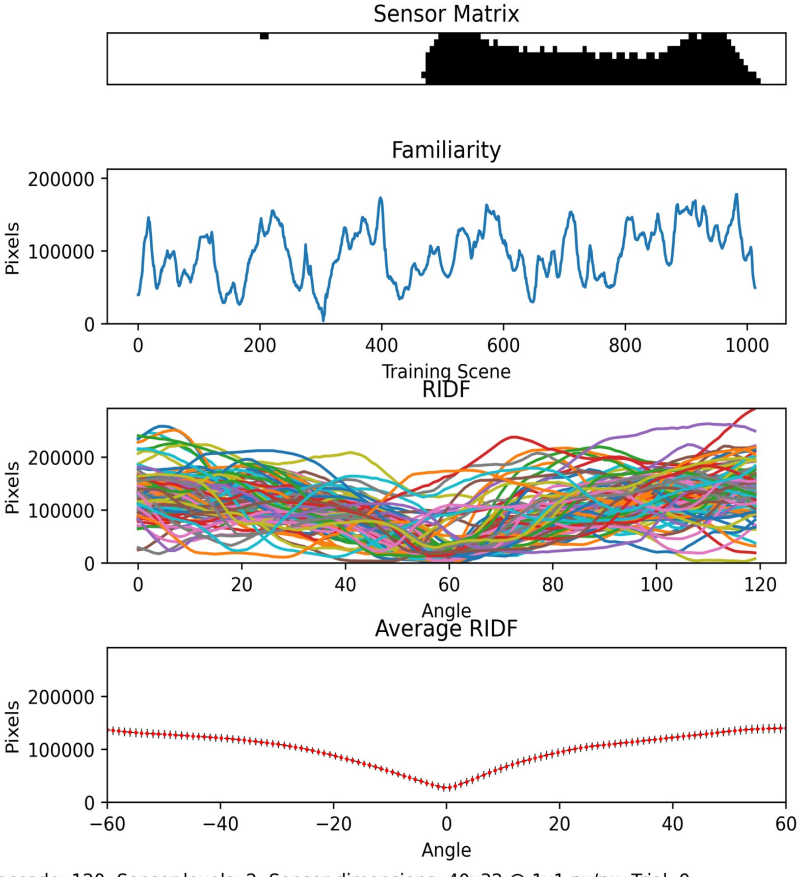


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2641.80; RMSD/dist: 6.605; TD: 68429; p90: 36; p50: 20; complete: 0

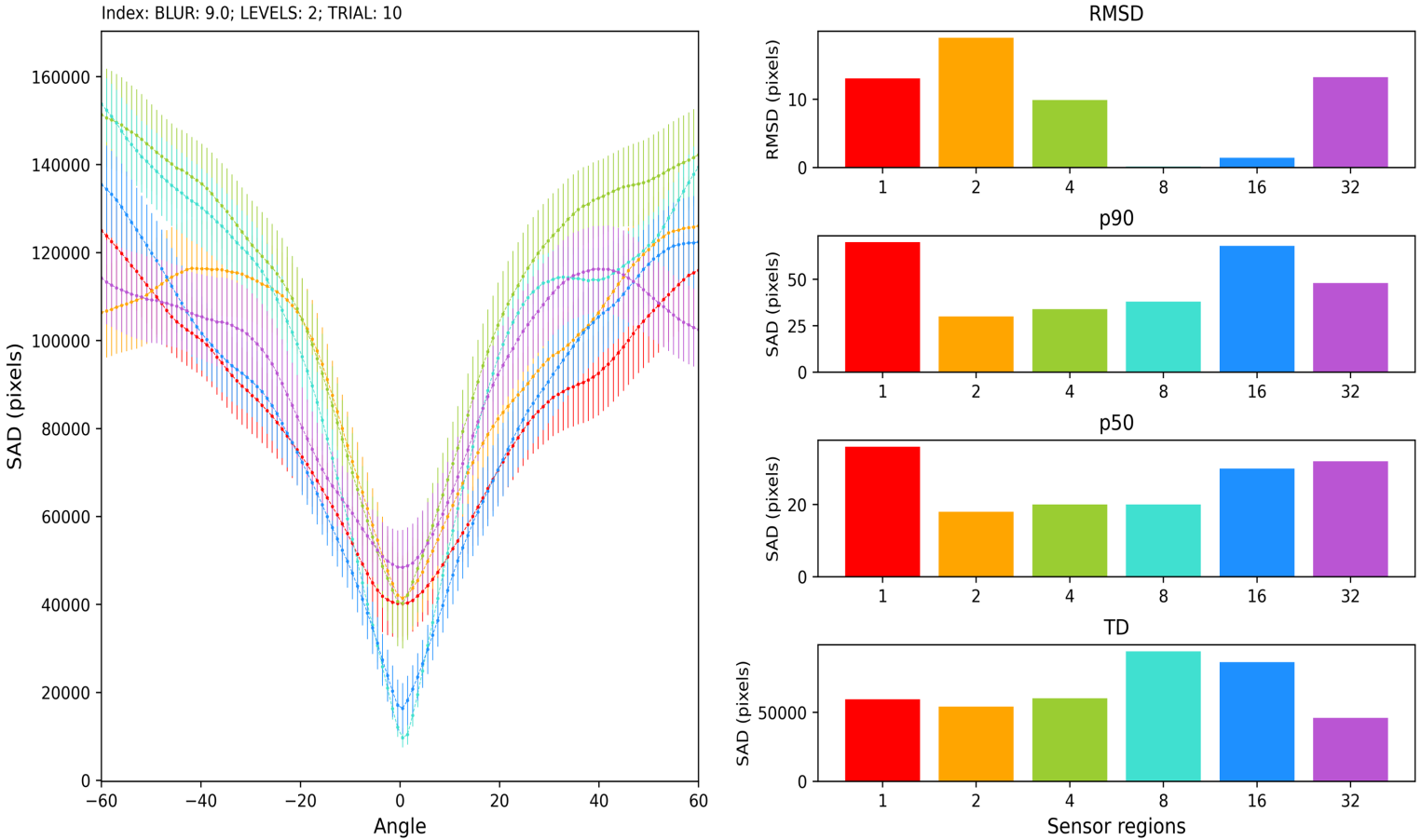
60%



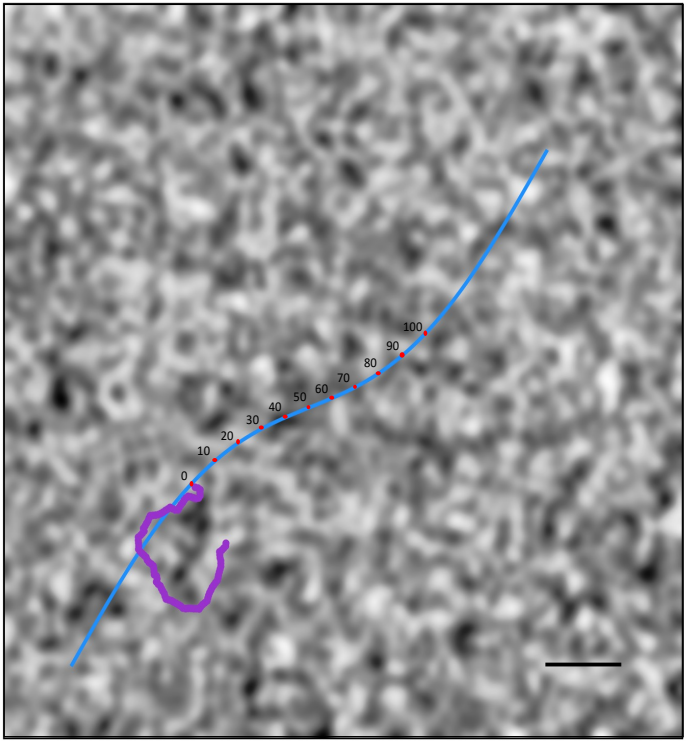


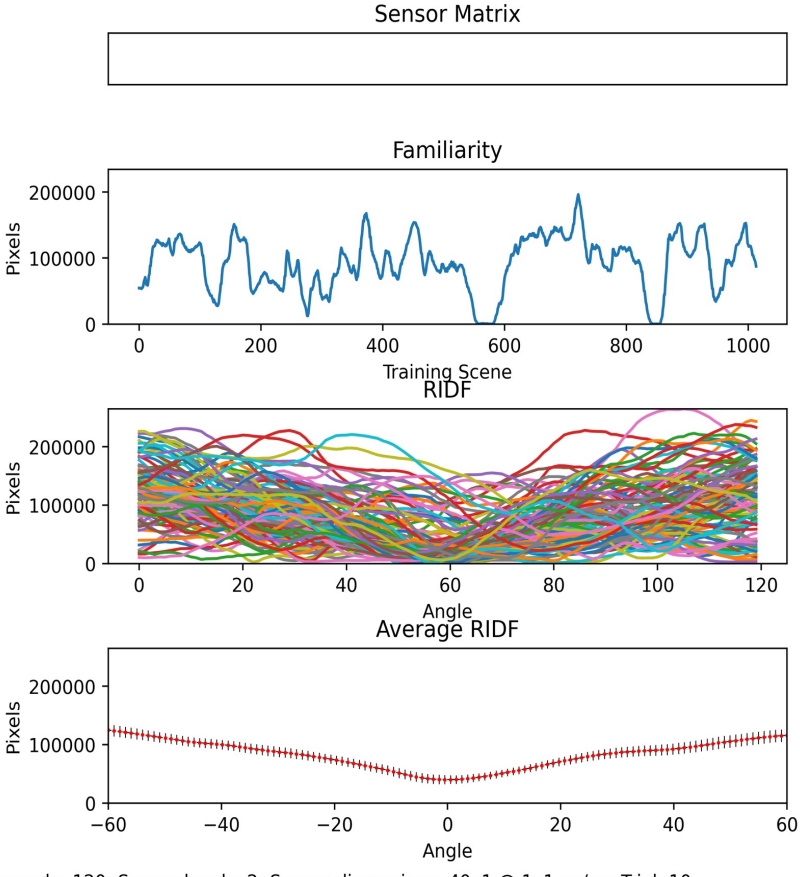
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1839.88; RMSD/dist: 4.600; TD: 74197; p90: 46; p50: 24; complete: 0


Index: BLUR: 9.0; LEVELS: 2; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

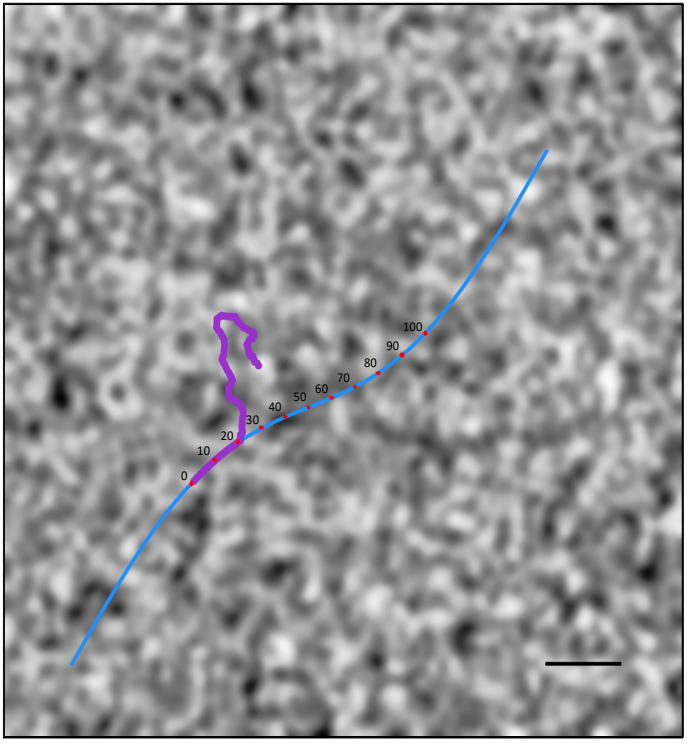


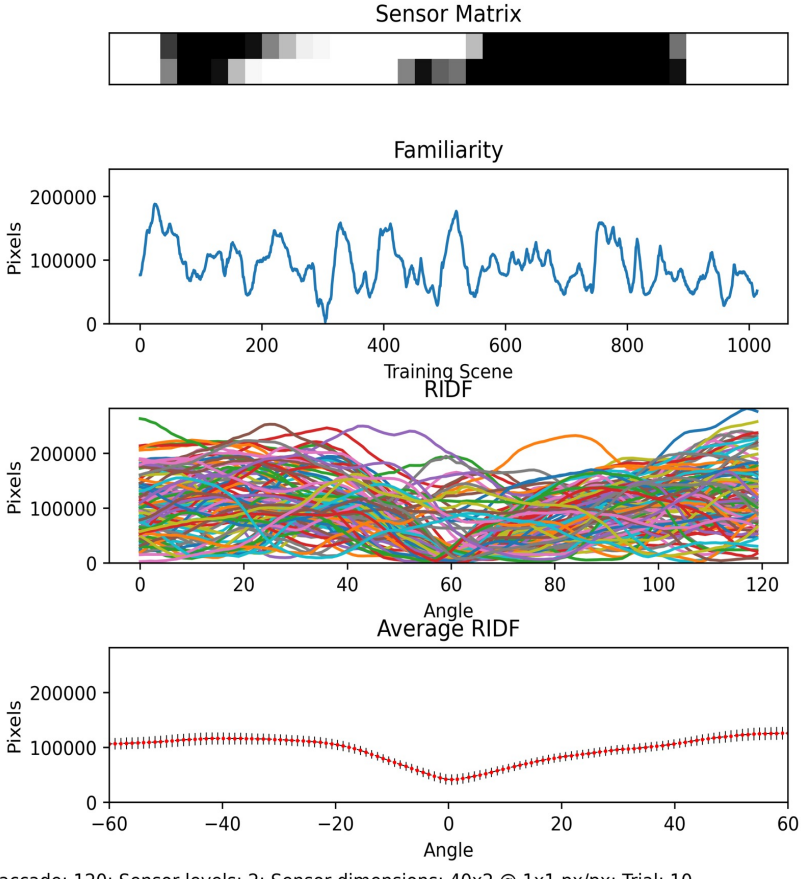


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 5232.58; RMSD/dist: 13.081; TD: 59494; p90: 70; p50: 36; complete: 0

20%

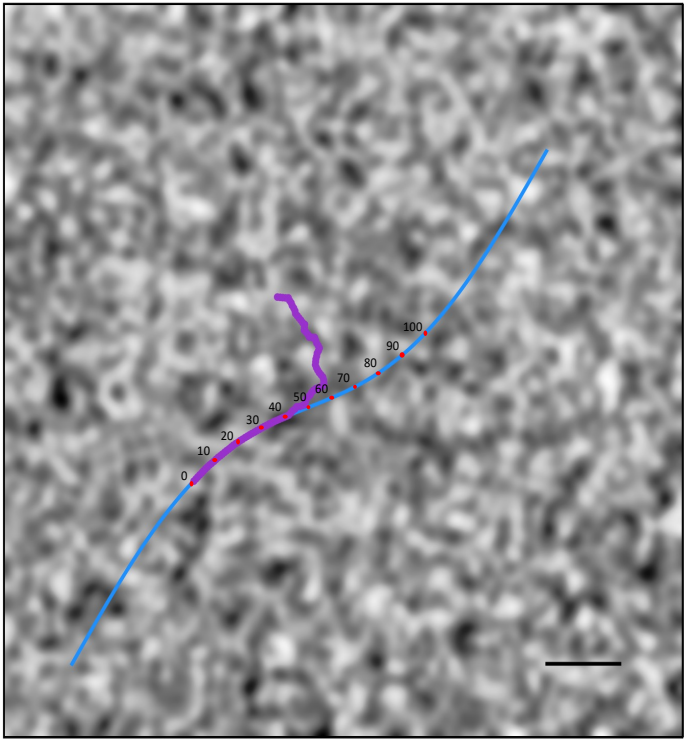


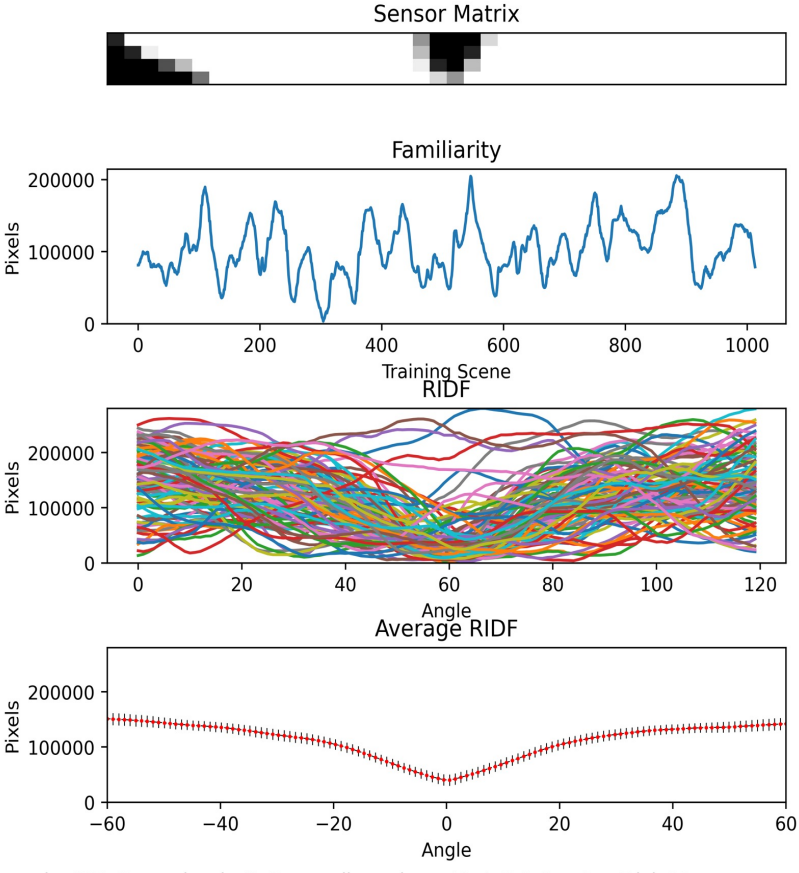


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 7618.52; RMSD/dist: 19.046; TD: 54182; p90: 30; p50: 18; complete: 0

40%

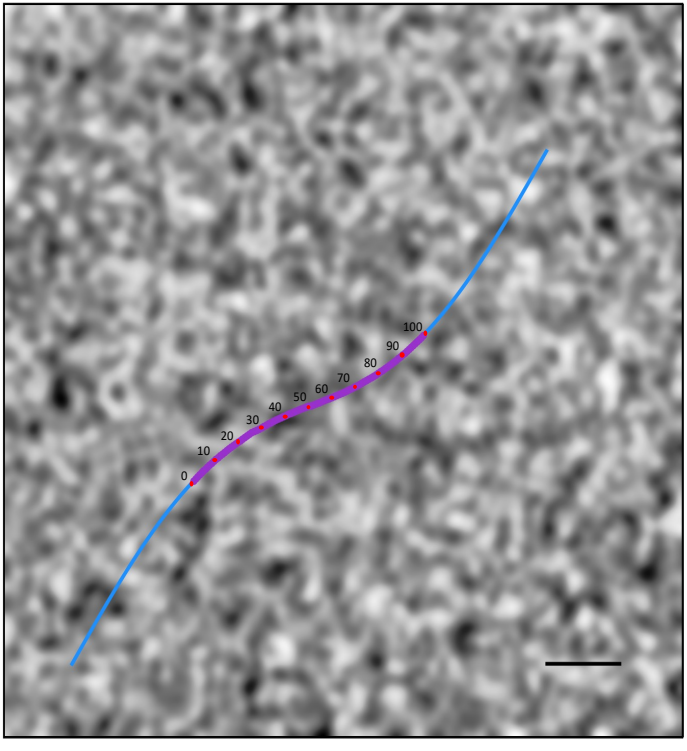


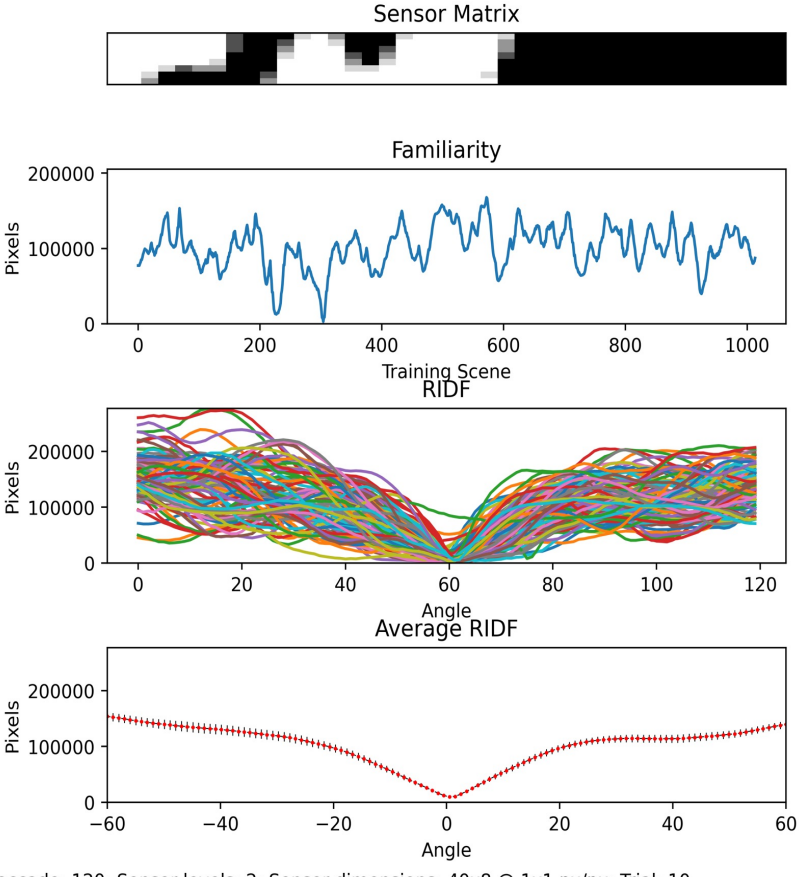


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3953.99; RMSD/dist: 9.885; TD: 60210; p90: 34; p50: 20; complete: 0

100%

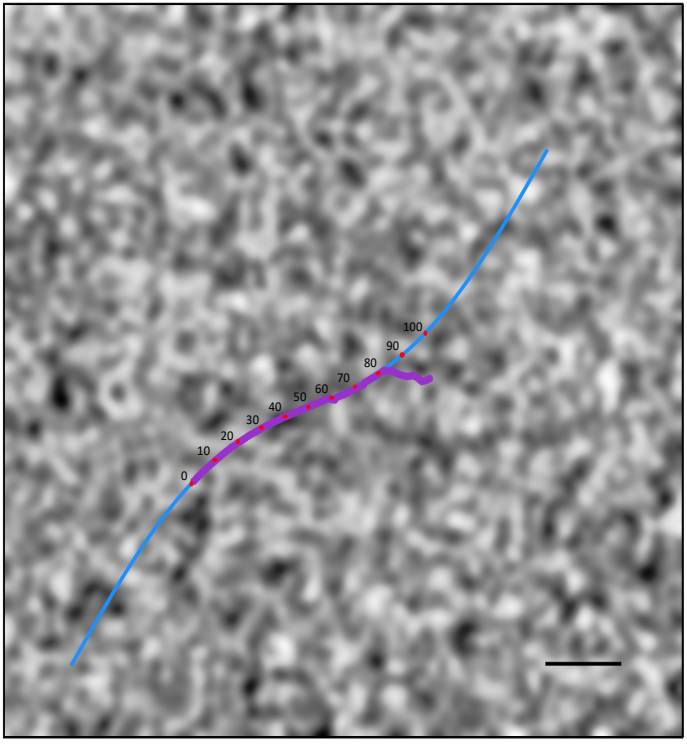


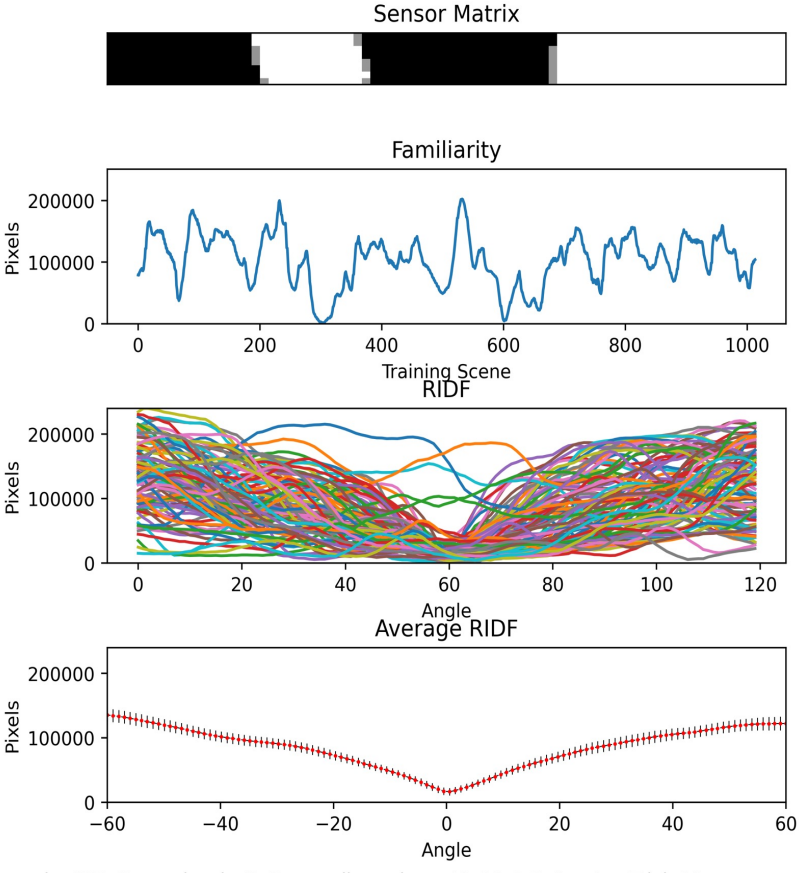


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 64.39; RMSD/dist: 0.161; TD: 94288; p90: 38; p50: 20; complete: 0

80%

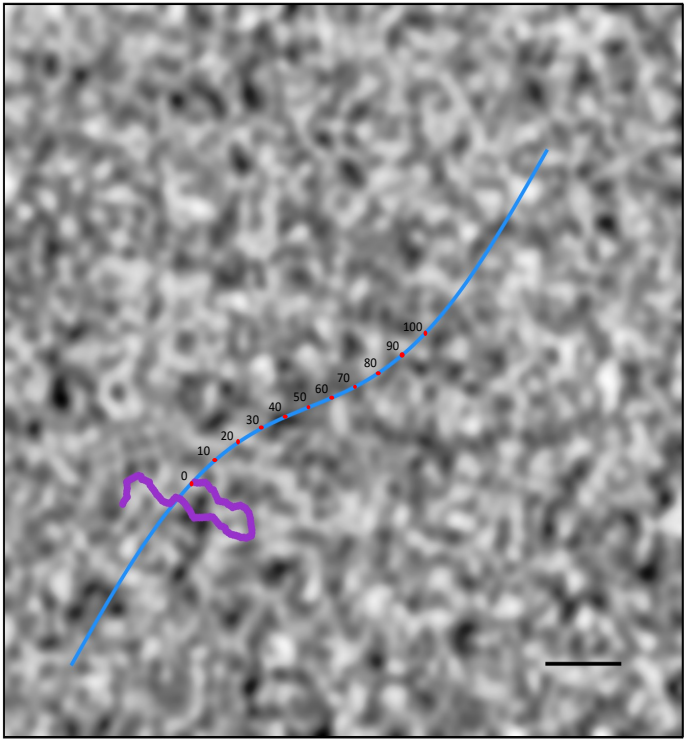


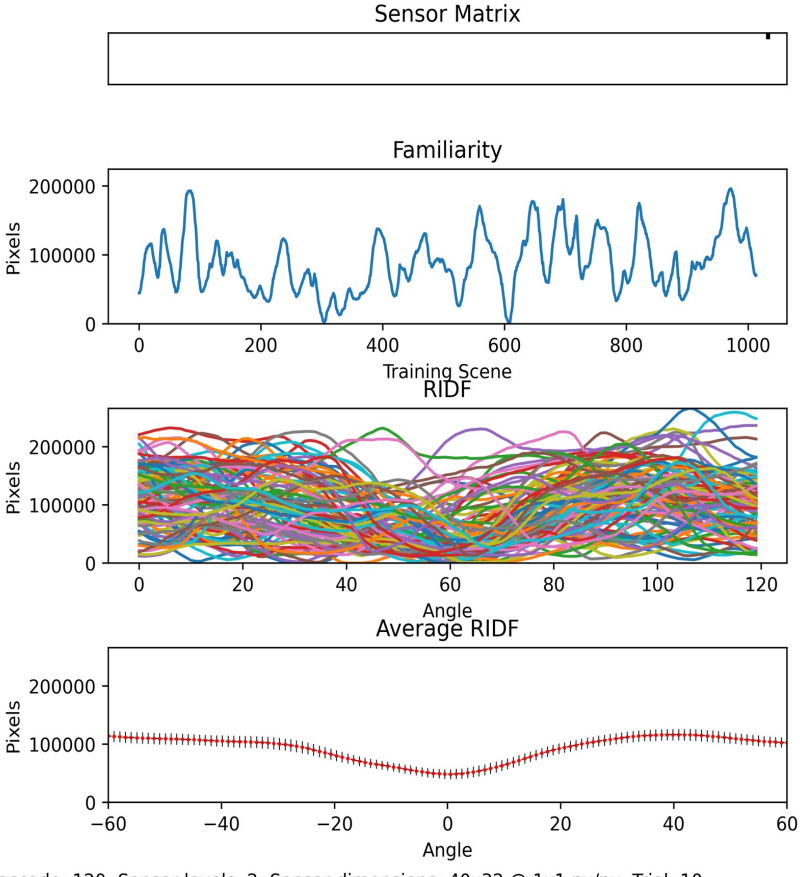


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 575.43; RMSD/dist: 1.439; TD: 86472; p90: 68; p50: 30; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 5297.65; RMSD/dist: 13.244; TD: 46055; p90: 48; p50: 32; complete: 0