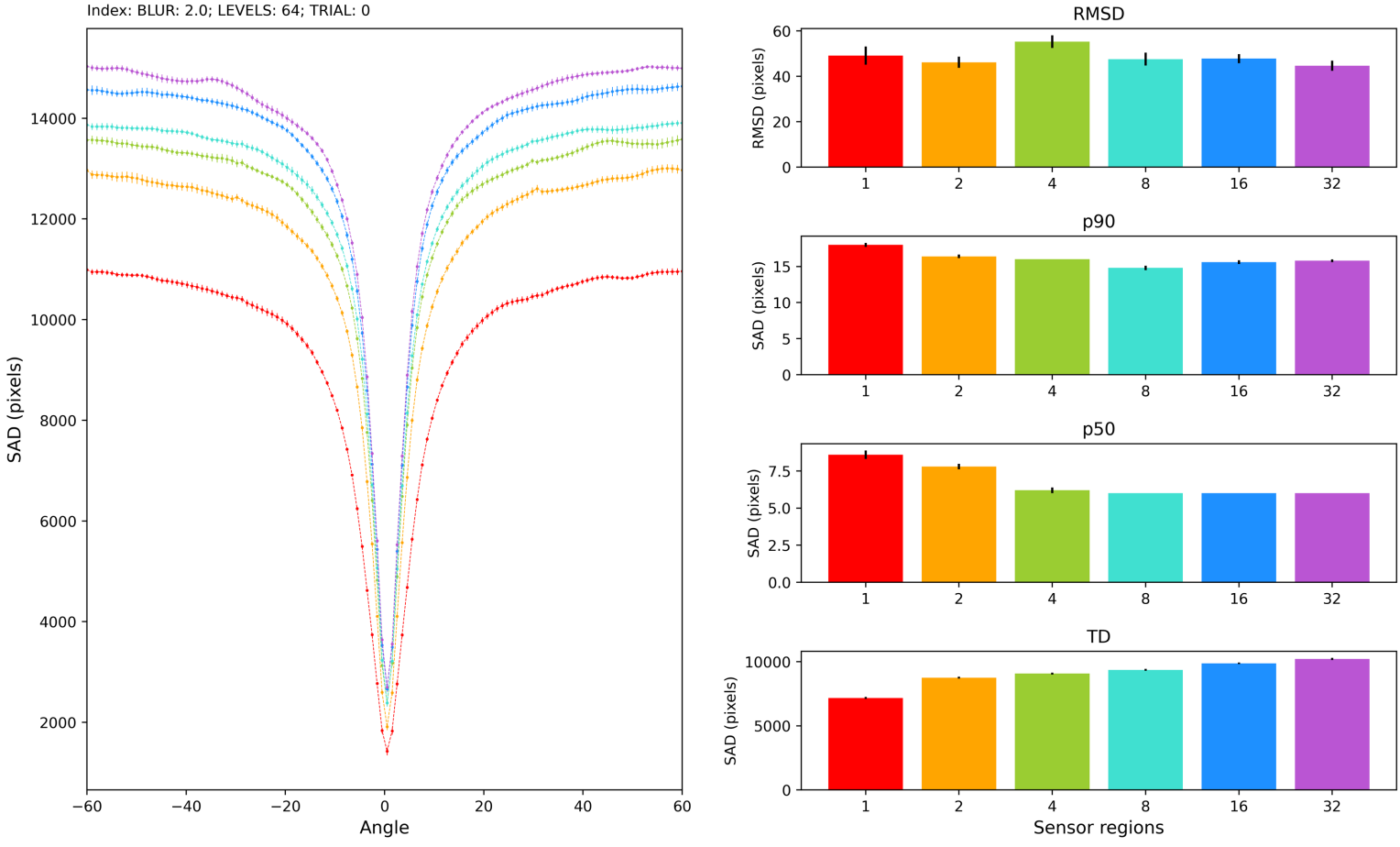
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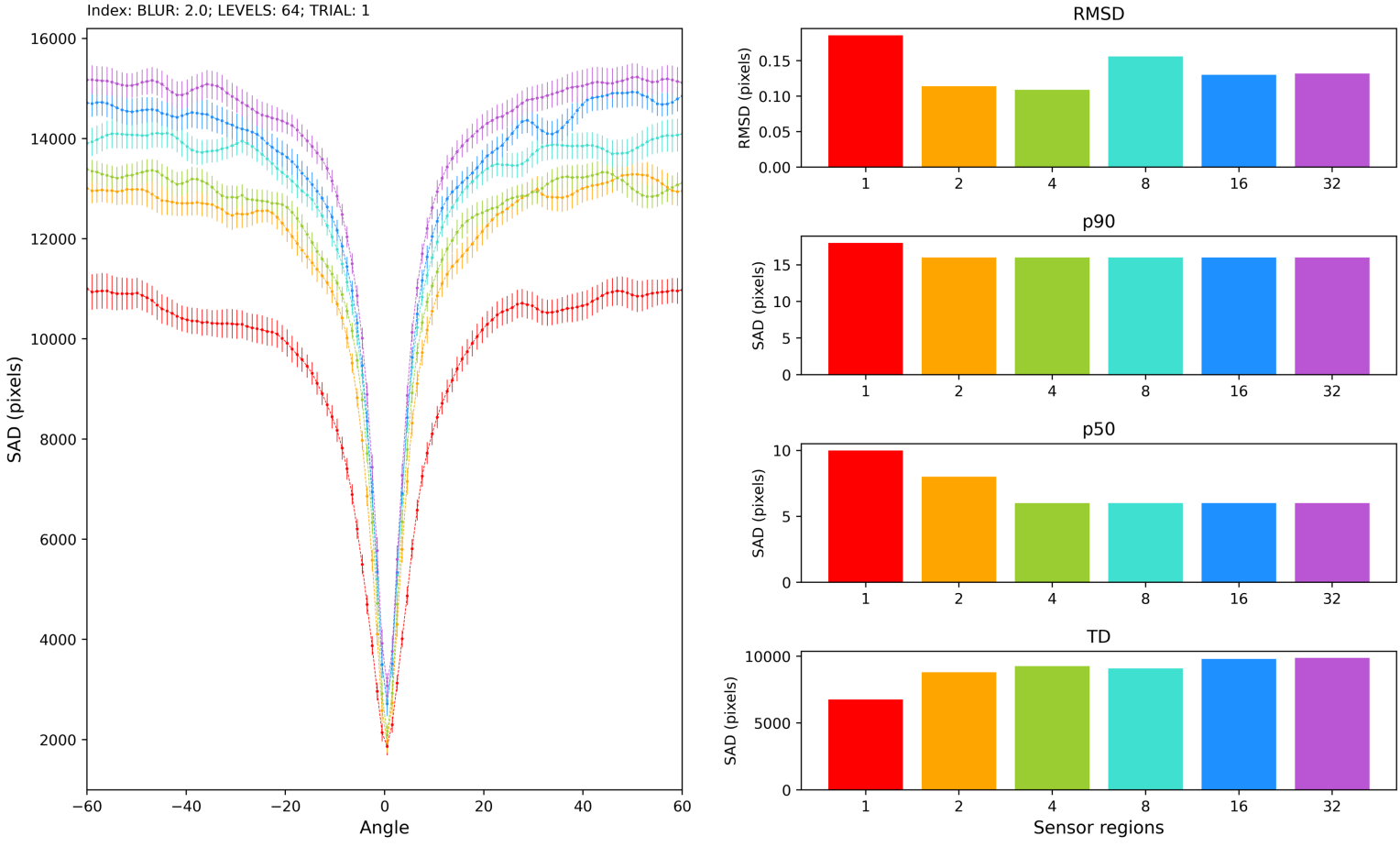
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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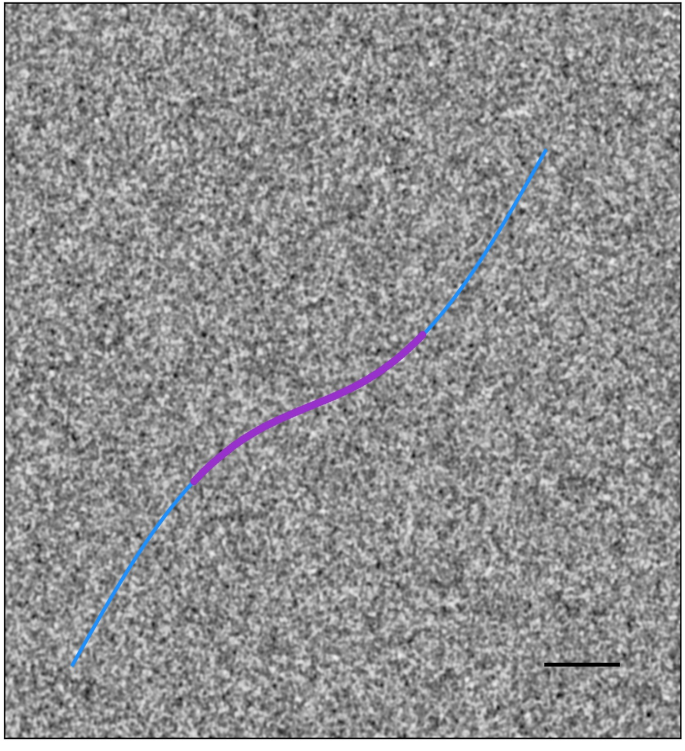
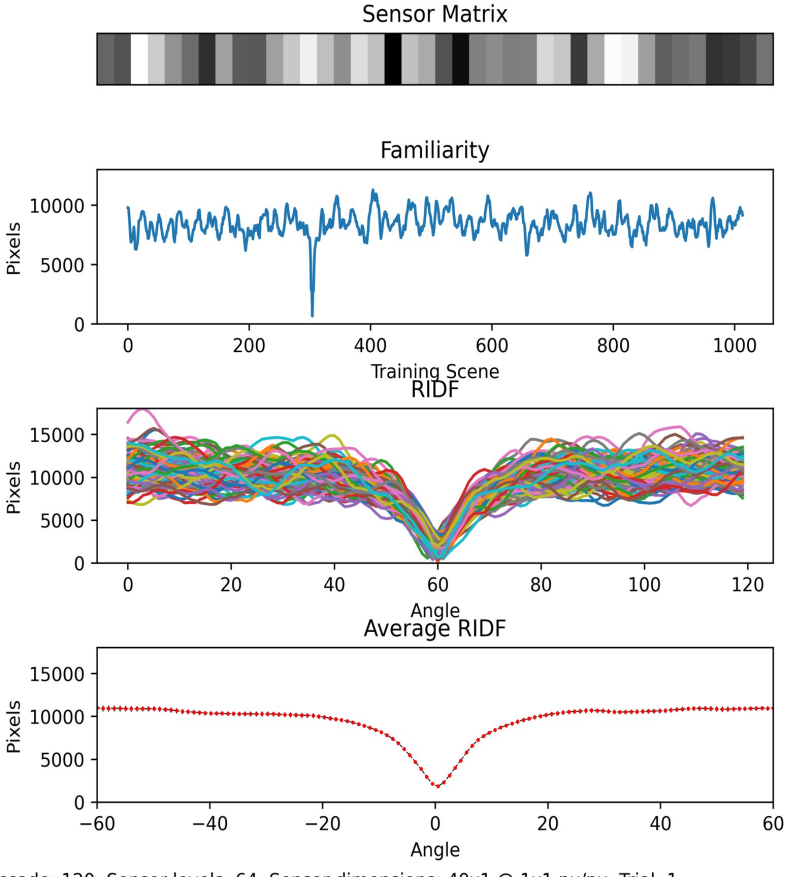
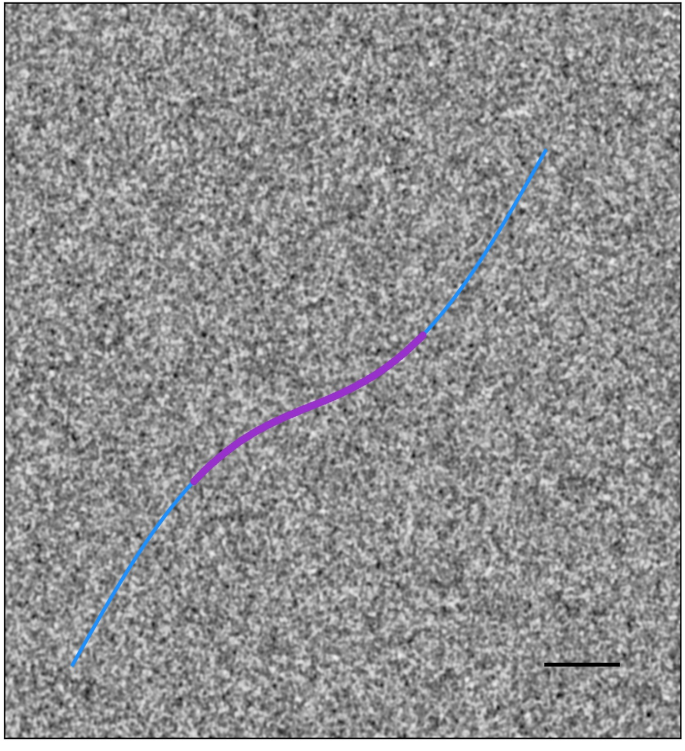
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

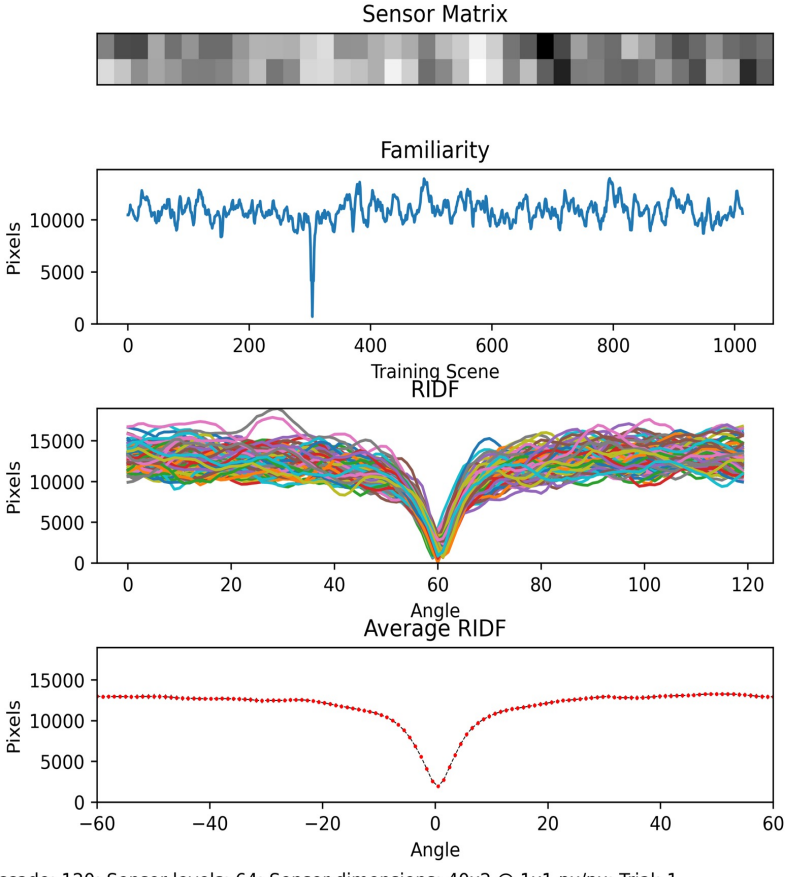




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

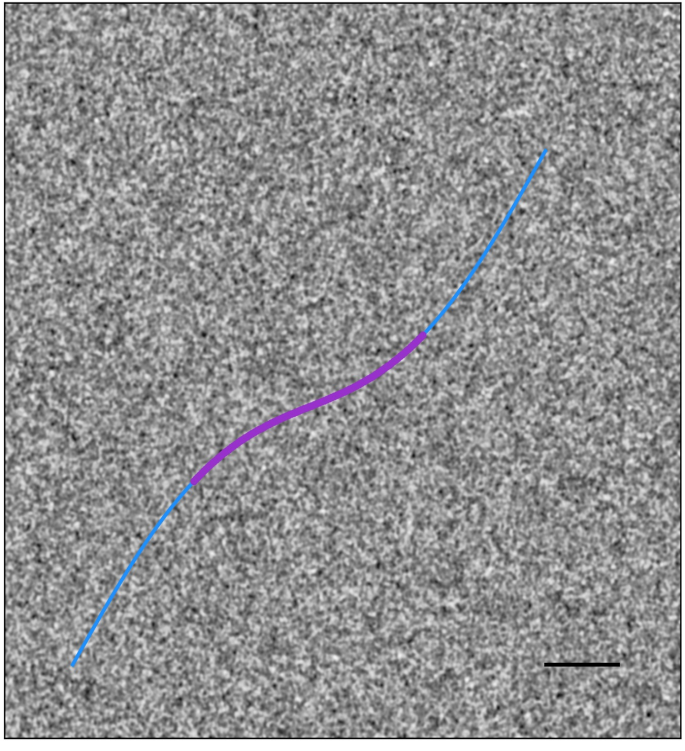
Navigation stats: RMSD error: 74.25; RMSD/dist: 0.186; TD: 6761; p90: 18; p50: 10; complete: 0

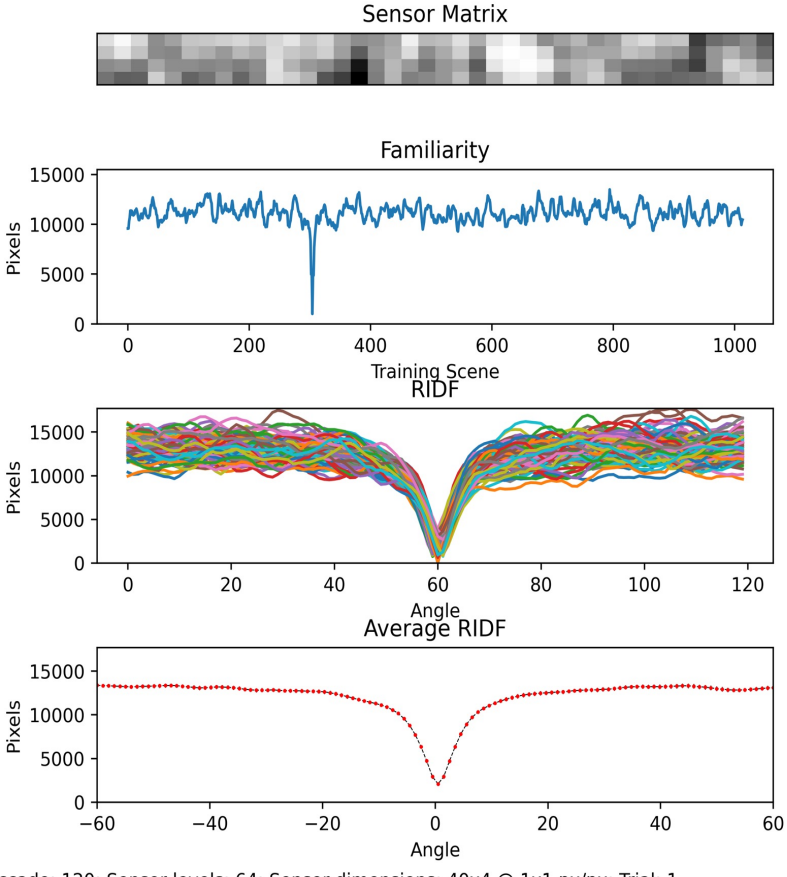




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 45.54; RMSD/dist: 0.114; TD: 8798; p90: 16; p50: 8; complete: 0





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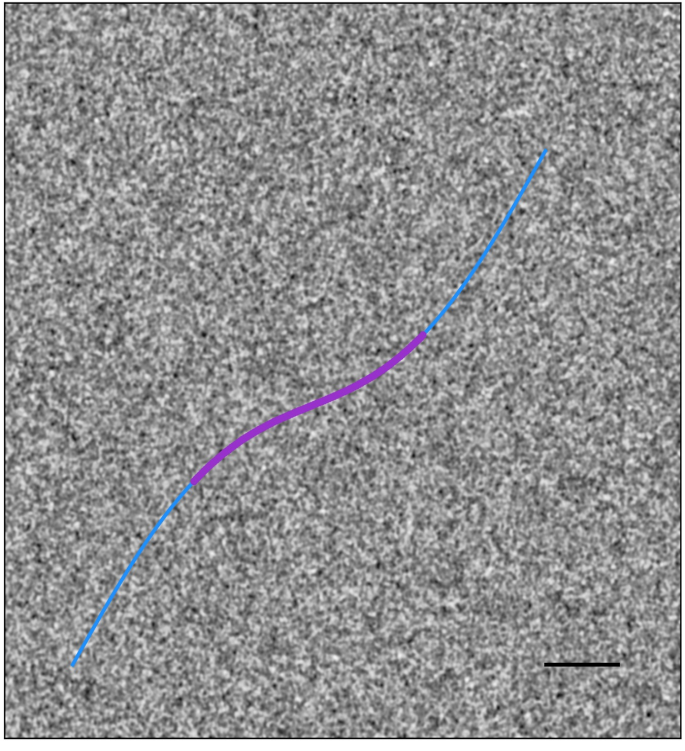
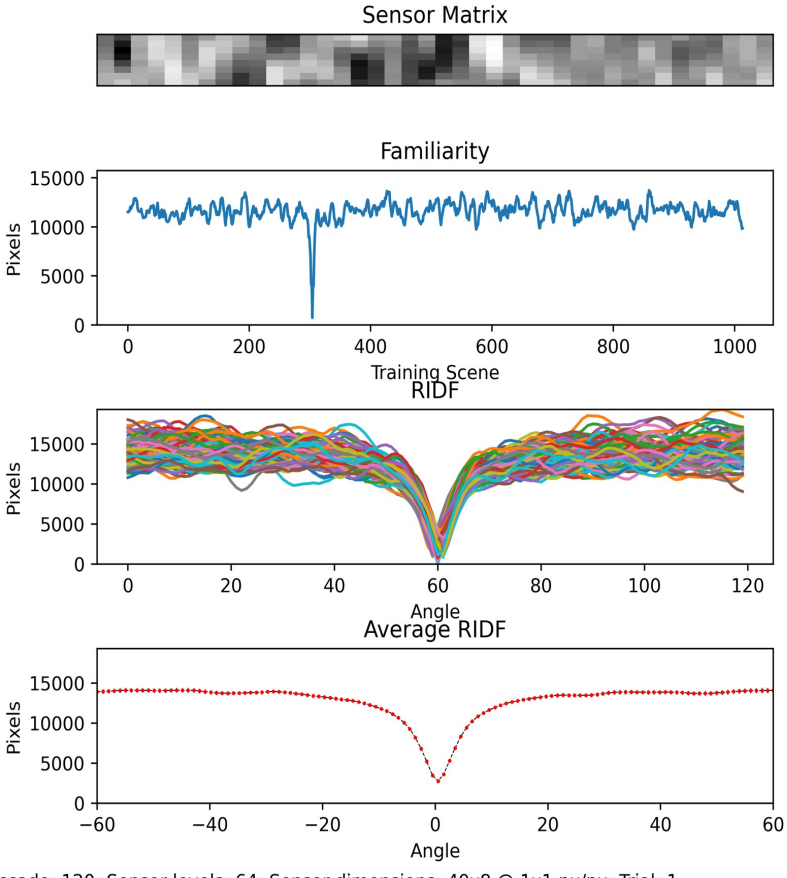
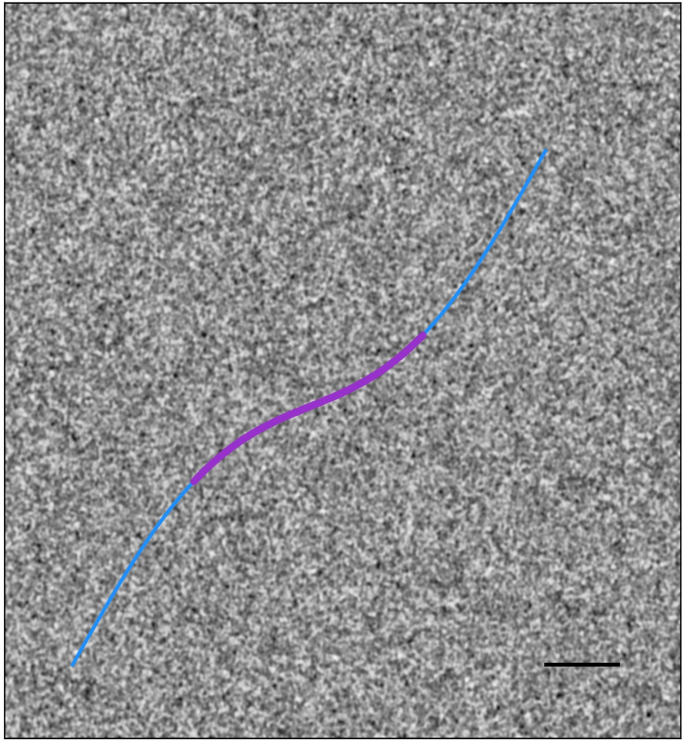
Navigation stats: RMSD error: 43.66; RMSD/dist: 0.109; TD: 9261; p90: 16; p50: 6; complete: 0

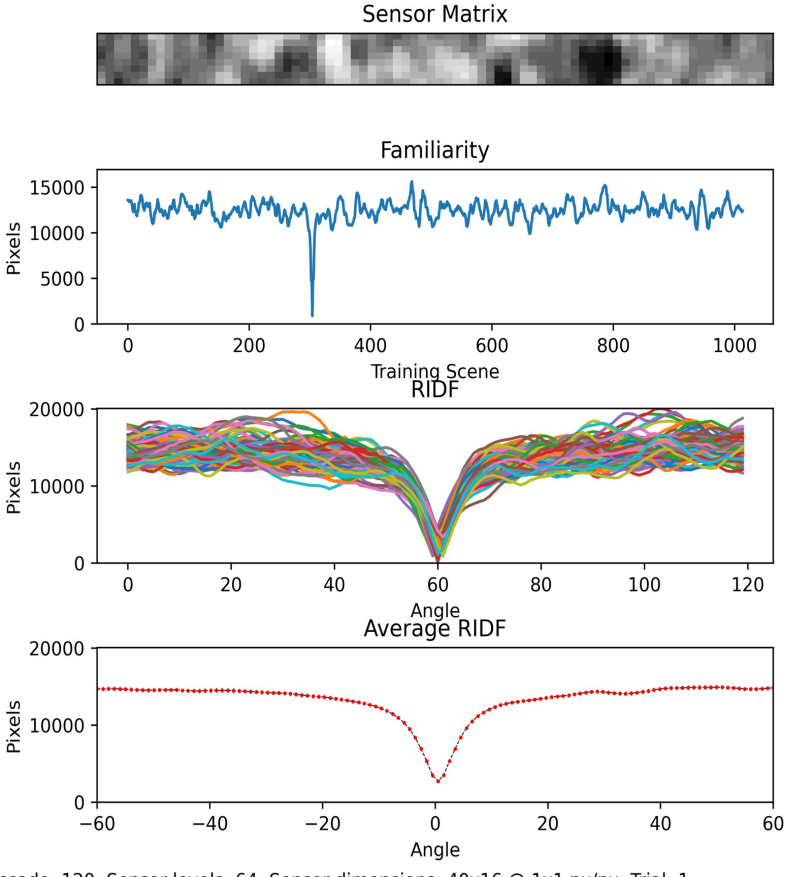




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

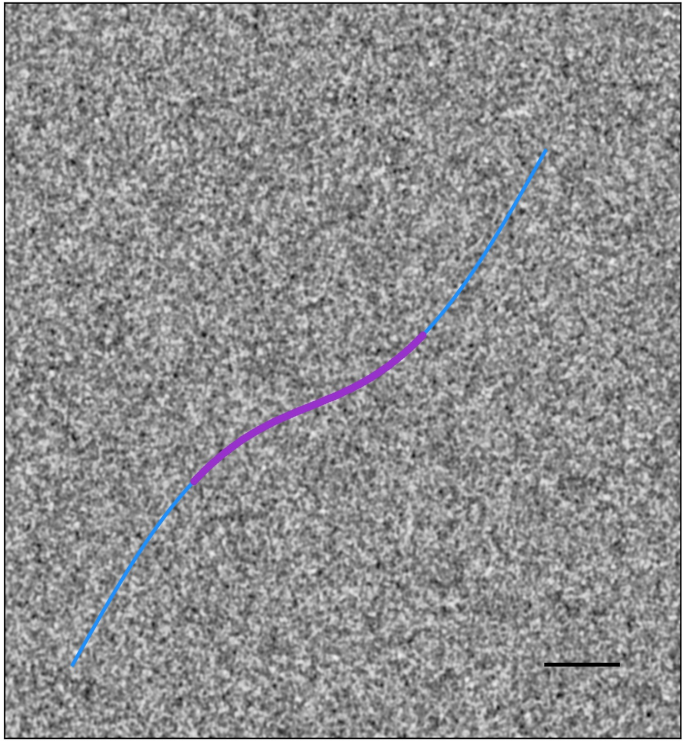
Navigation stats: RMSD error: 62.30; RMSD/dist: 0.156; TD: 9085; p90: 16; p50: 6; complete: 0

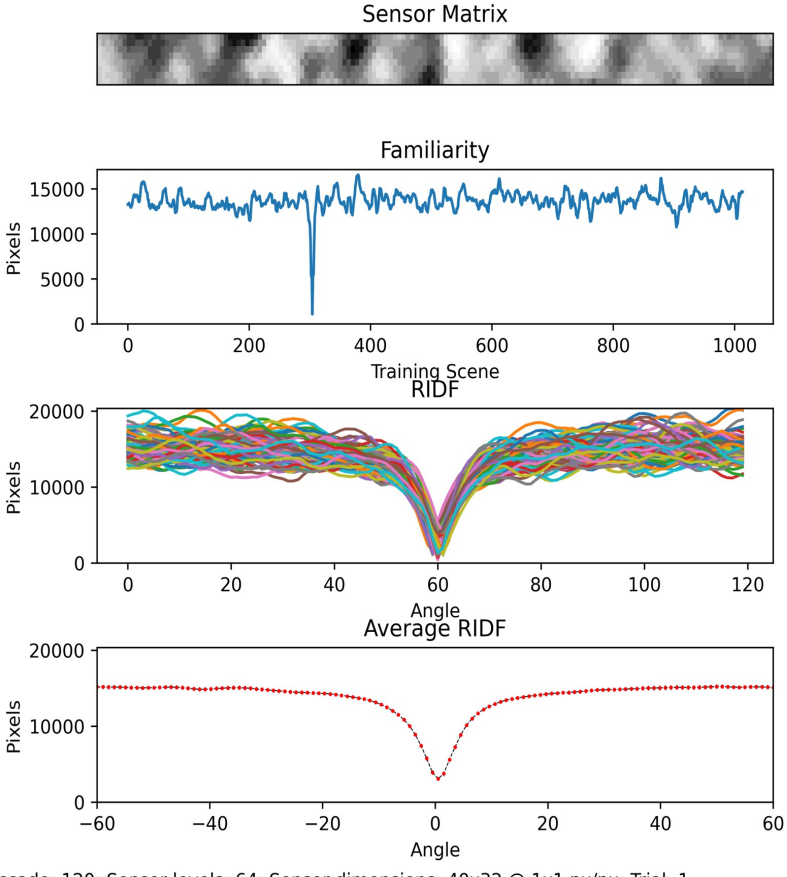




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

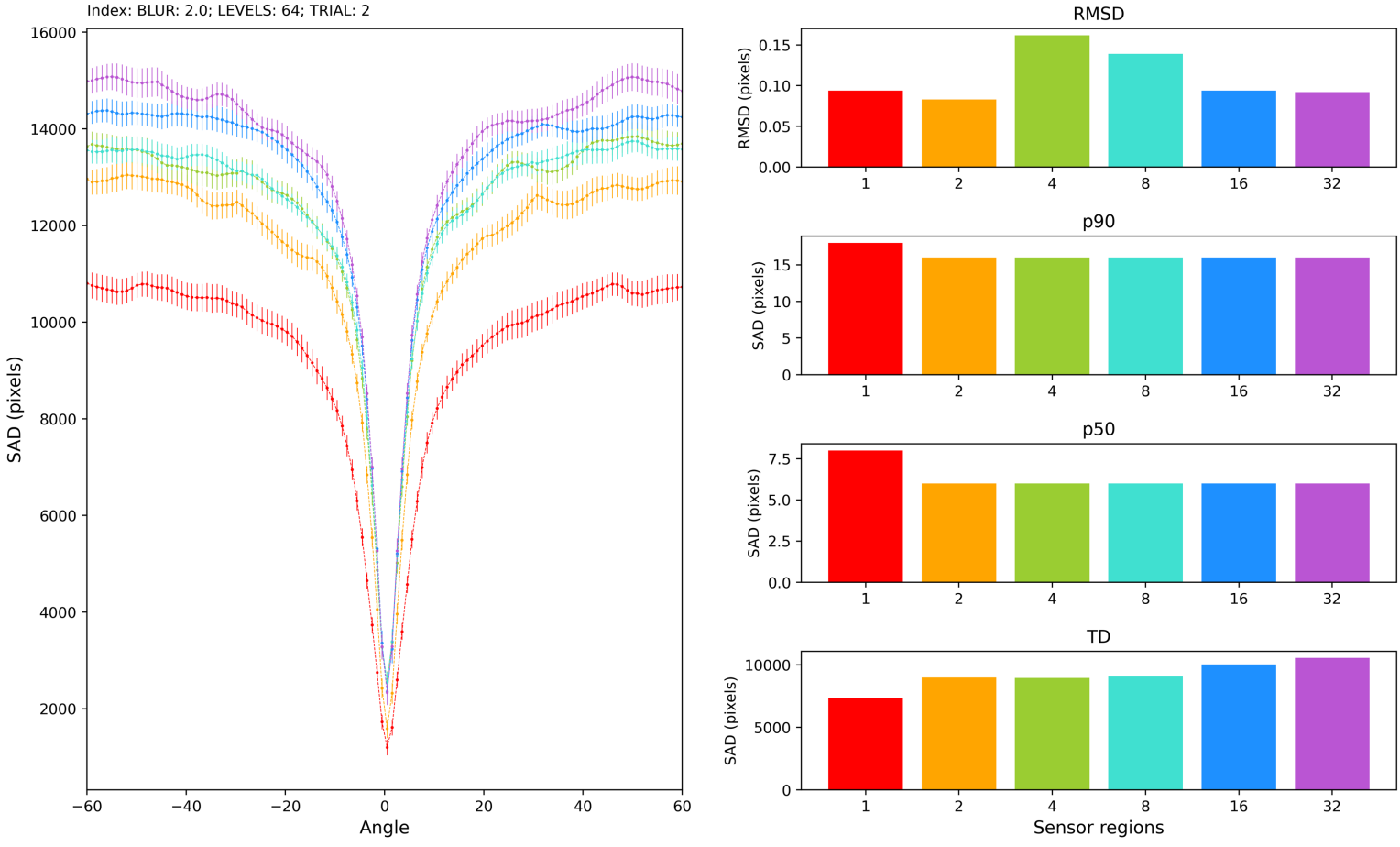
Navigation stats: RMSD error: 52.18; RMSD/dist: 0.130; TD: 9797; p90: 16; p50: 6; complete: 0

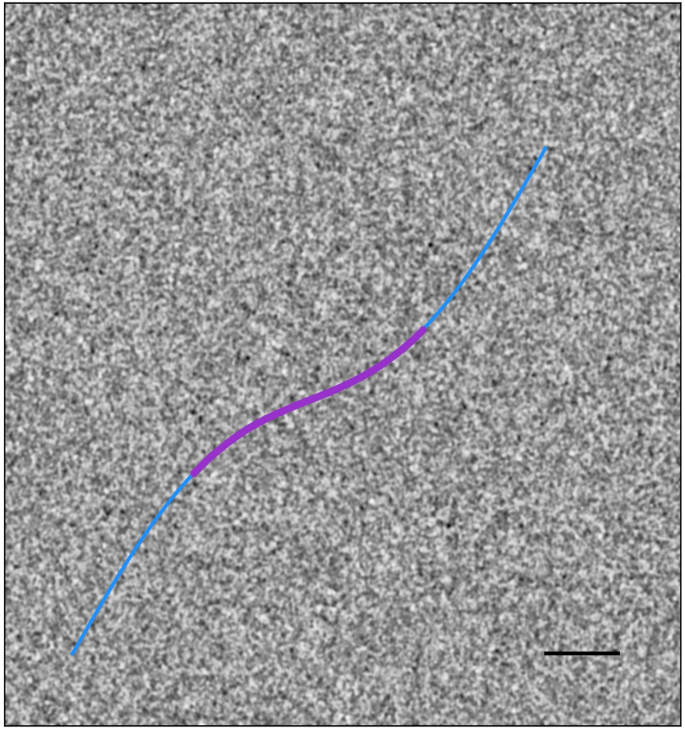


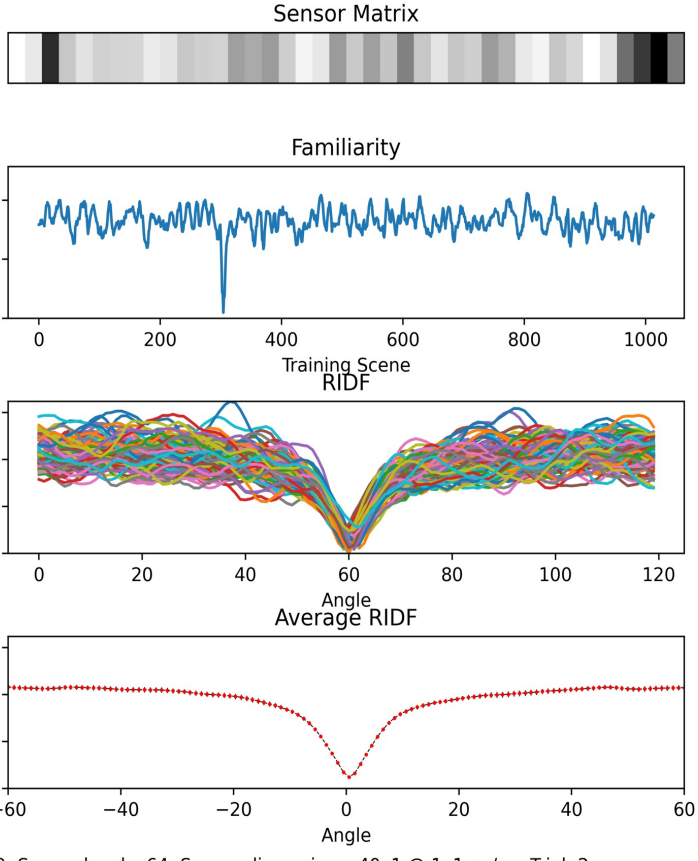


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

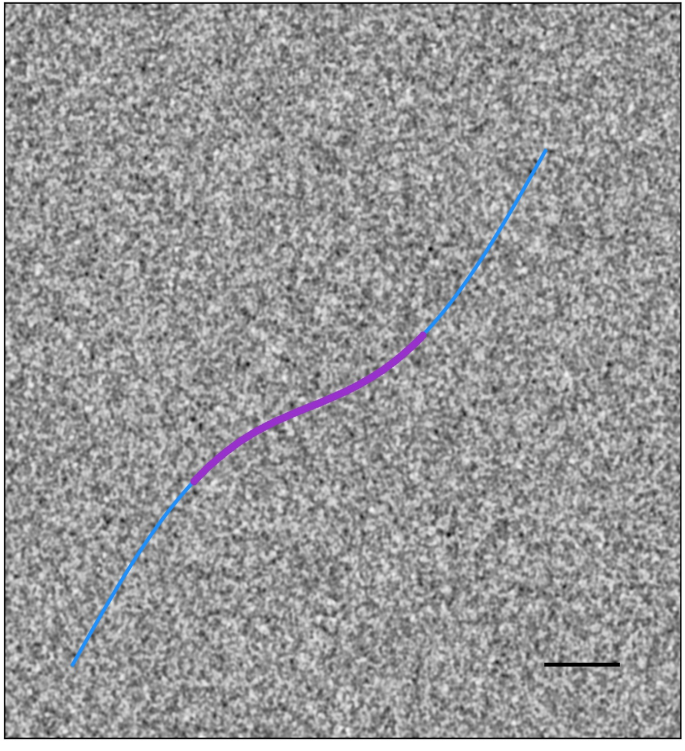
Navigation stats: RMSD error: 52.91; RMSD/dist: 0.132; TD: 9871; p90: 16; p50: 6; complete: 0

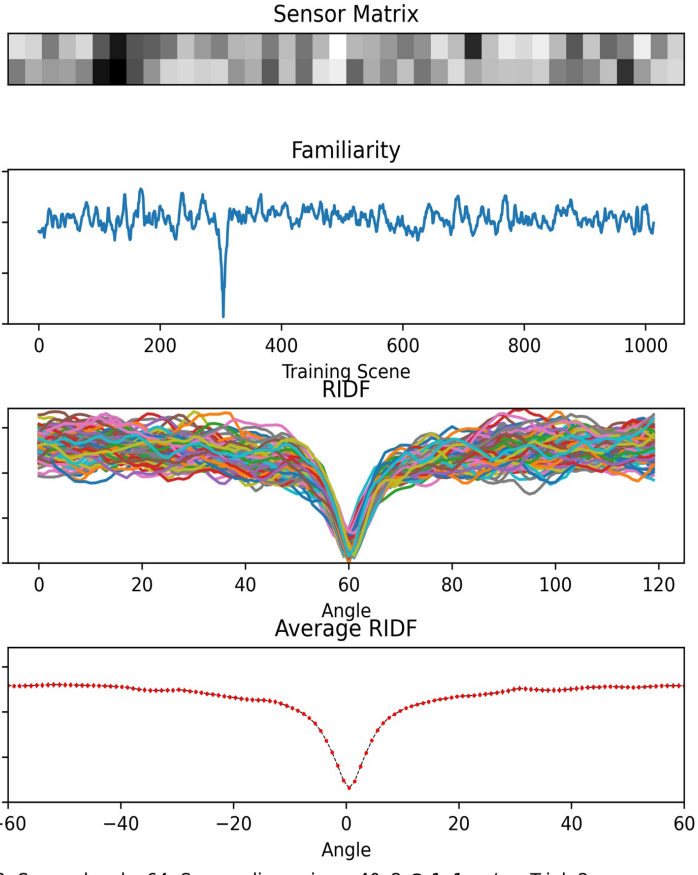

Index: BLUR: 2.0; LEVELS: 64; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions





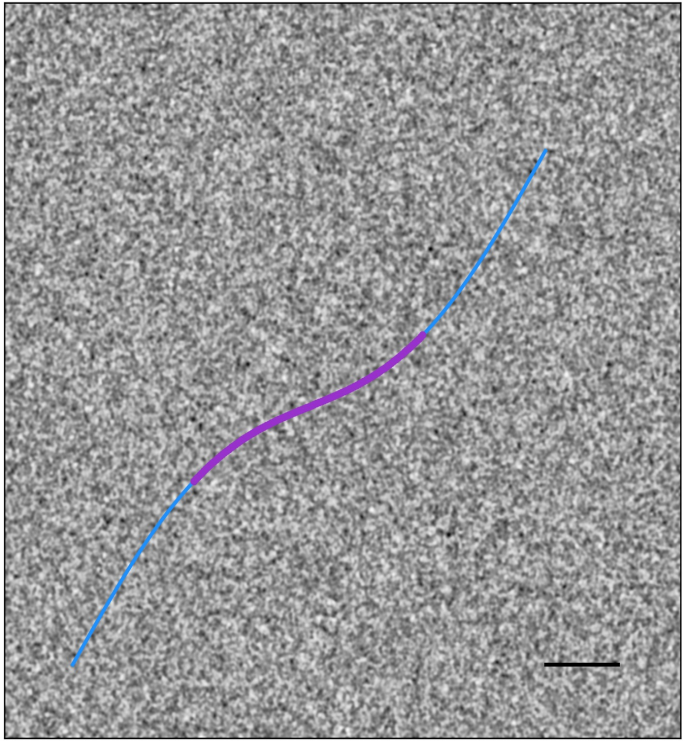
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 37.54; RMSD/dist: 0.094; TD: 7351; p90: 18; p50: 8; complete: 0

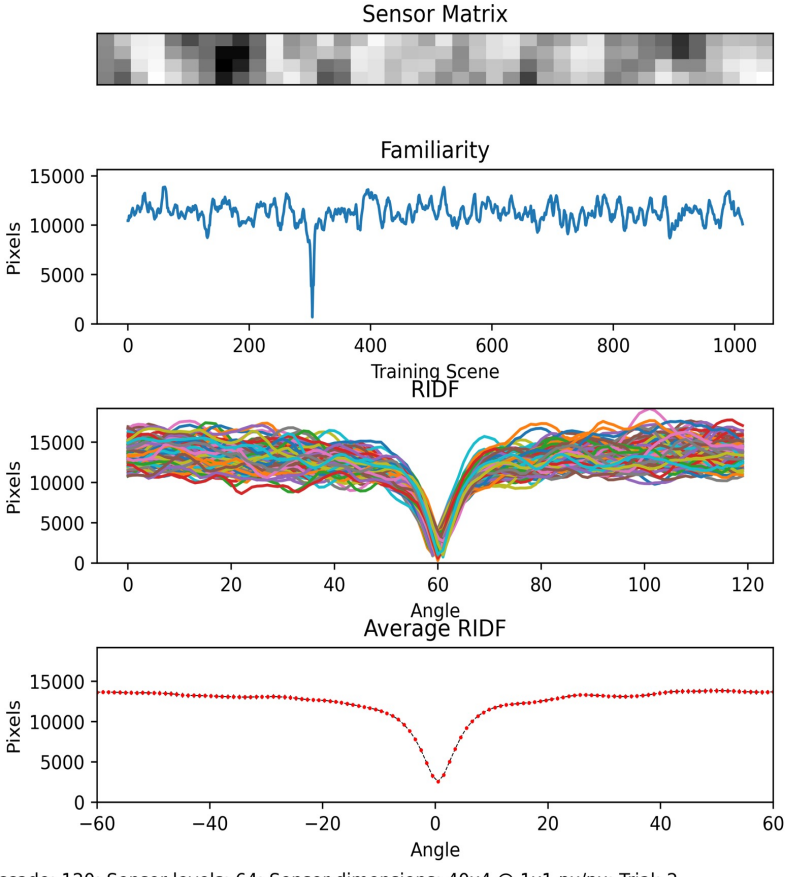




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

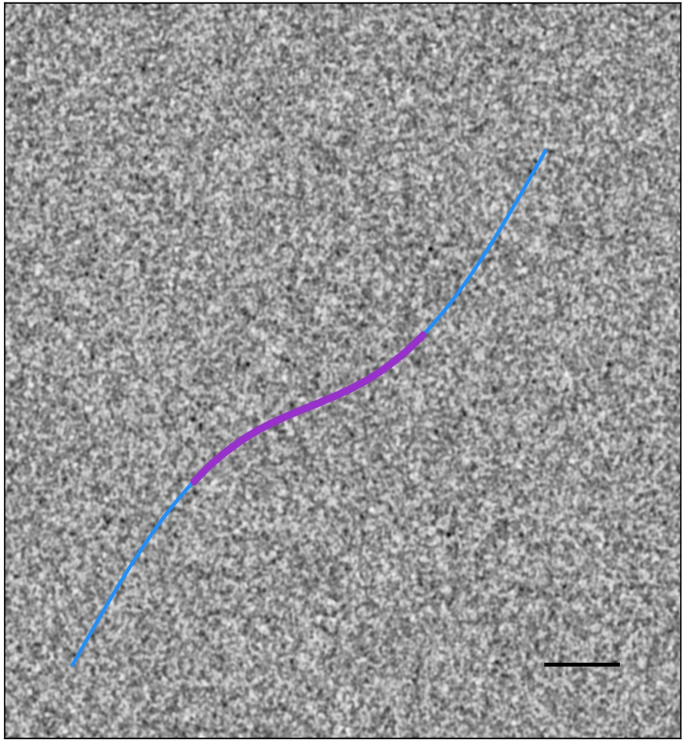
Navigation stats: RMSD error: 33.22; RMSD/dist: 0.083; TD: 8996; p90: 16; p50: 6; complete: 0

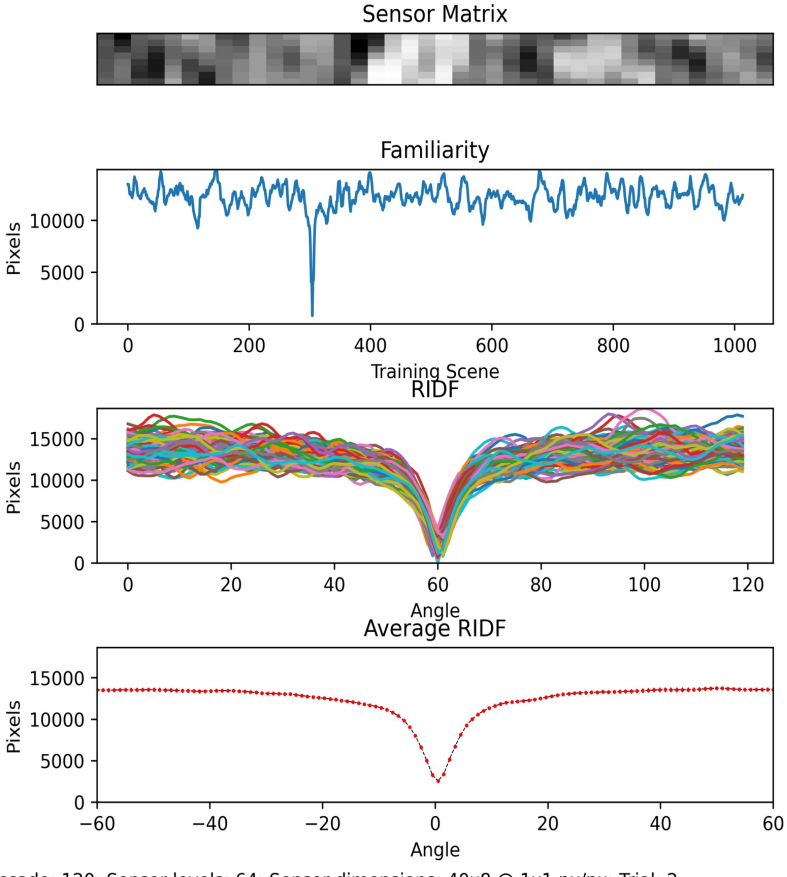




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

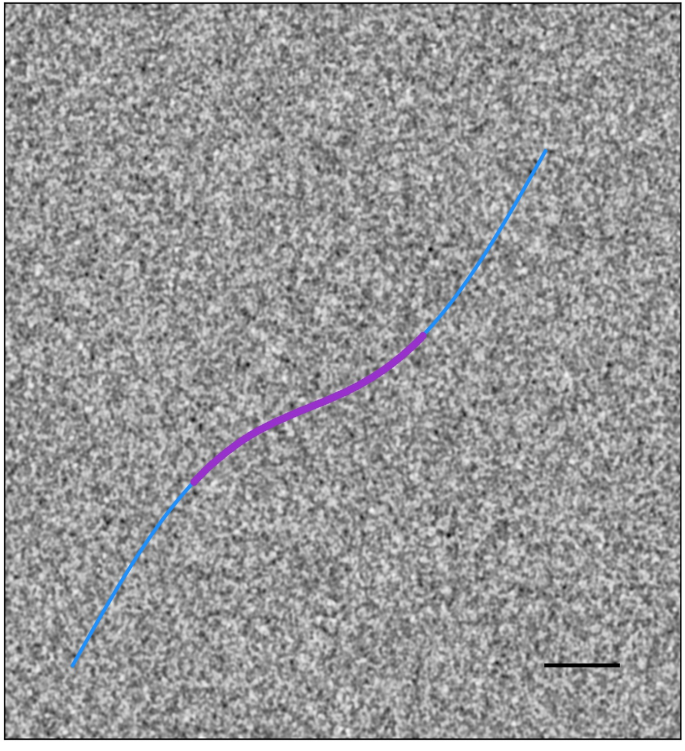
Navigation stats: RMSD error: 64.74; RMSD/dist: 0.162; TD: 8961; p90: 16; p50: 6; complete: 0

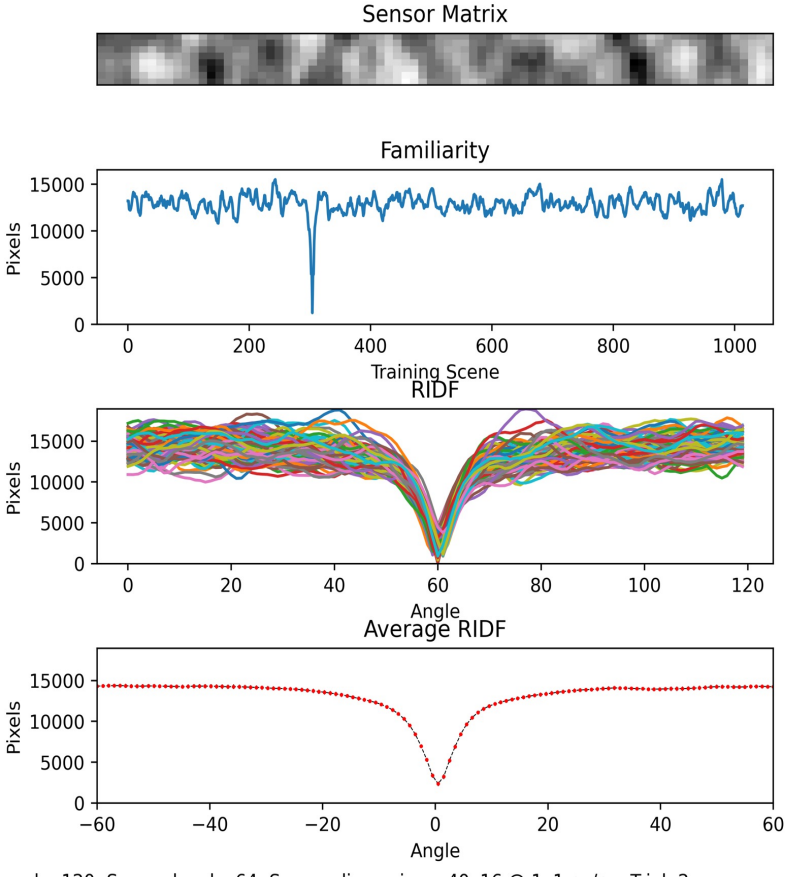




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

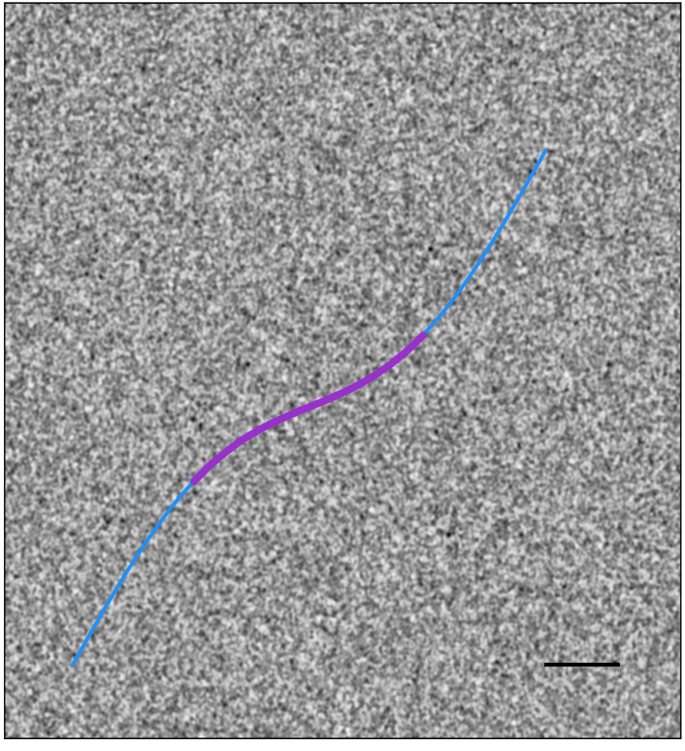
Navigation stats: RMSD error: 55.67; RMSD/dist: 0.139; TD: 9078; p90: 16; p50: 6; complete: 0

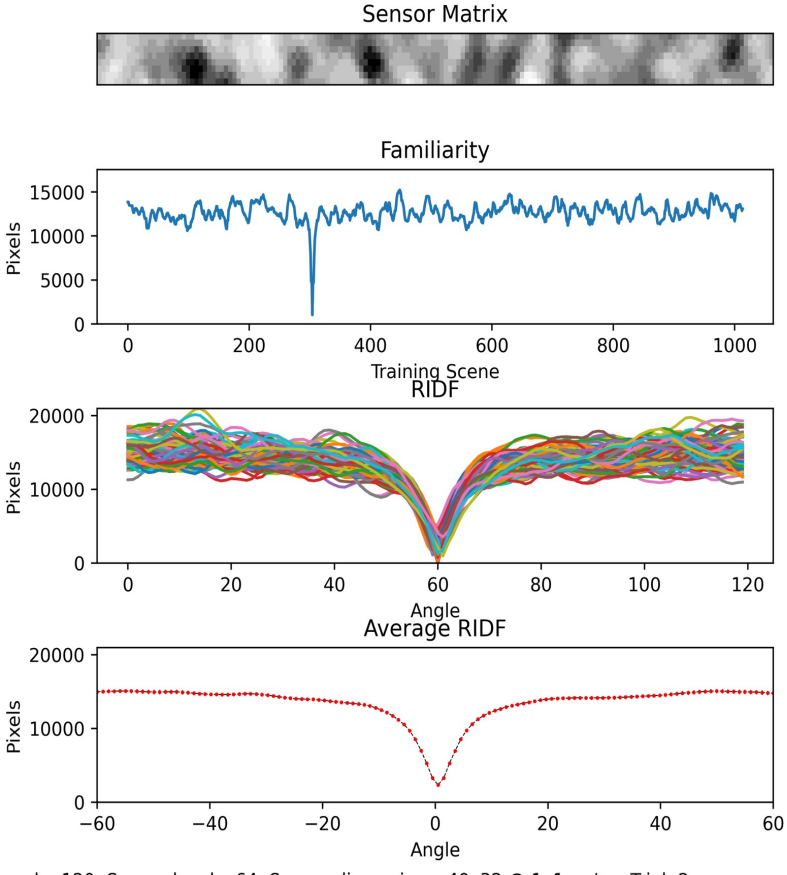




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

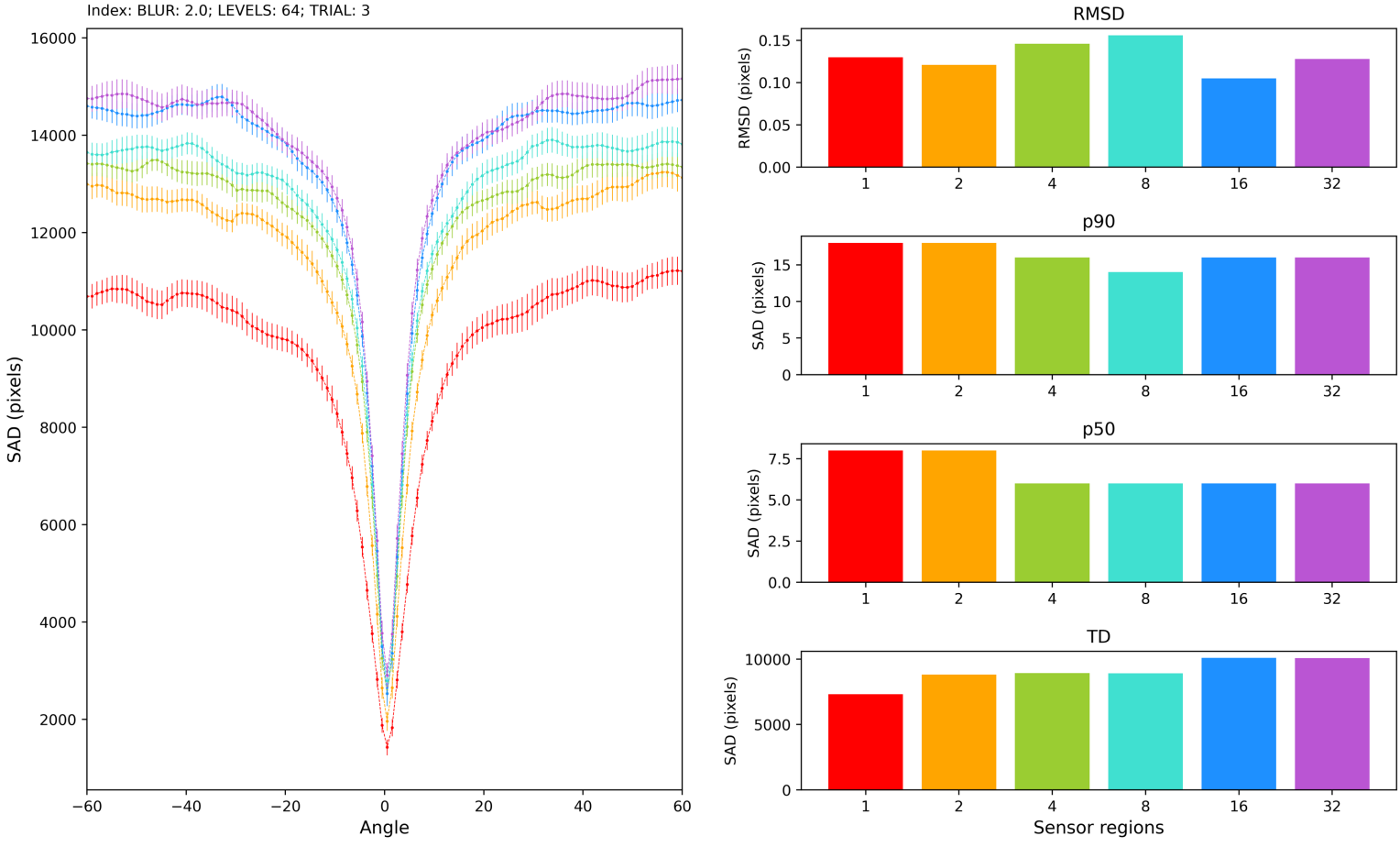
Navigation stats: RMSD error: 37.59; RMSD/dist: 0.094; TD: 10043; p90: 16; p50: 6; complete: 0

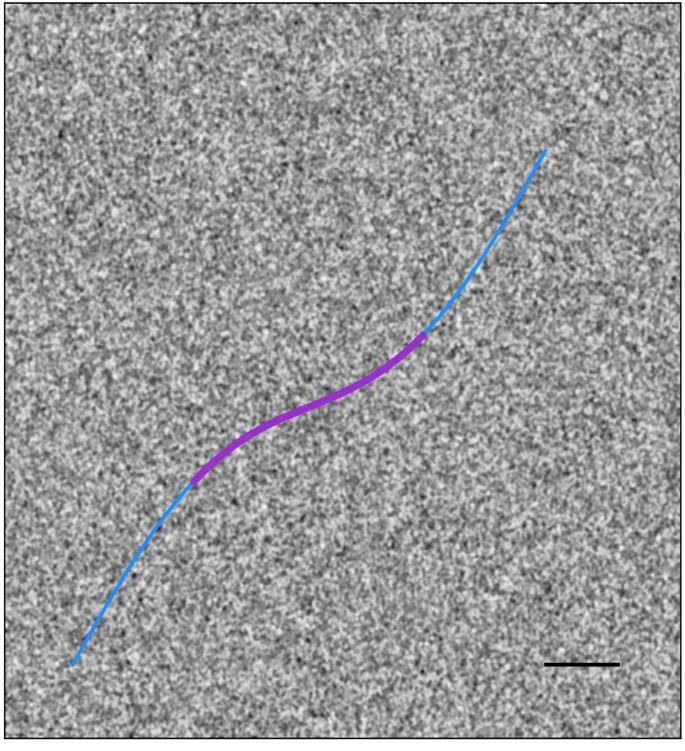


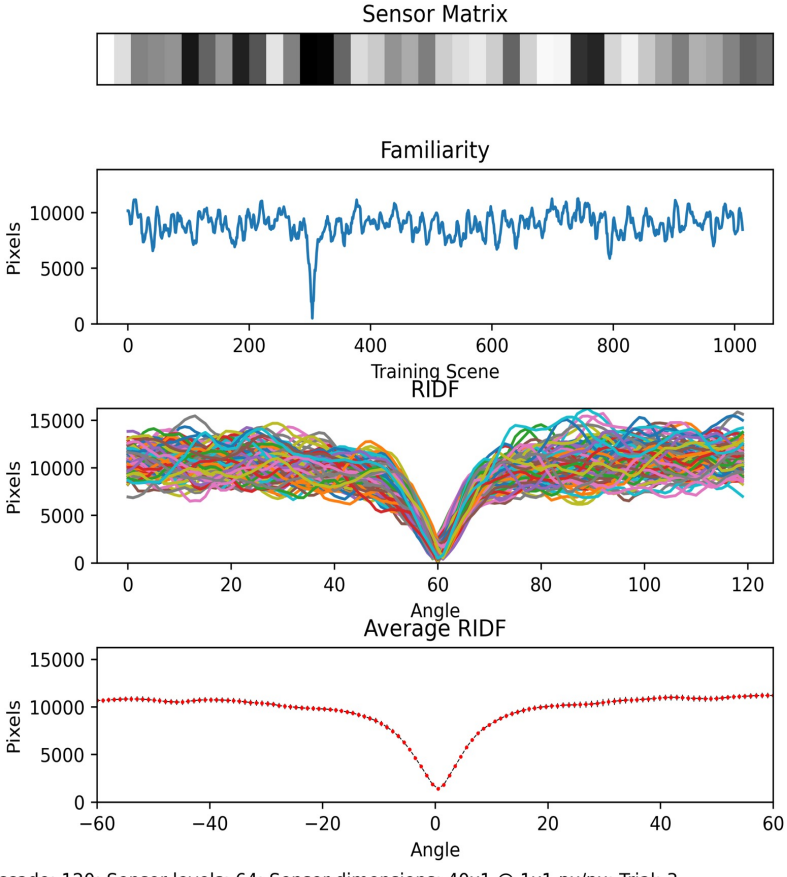


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 36.93; RMSD/dist: 0.092; TD: 10552; p90: 16; p50: 6; complete: 0

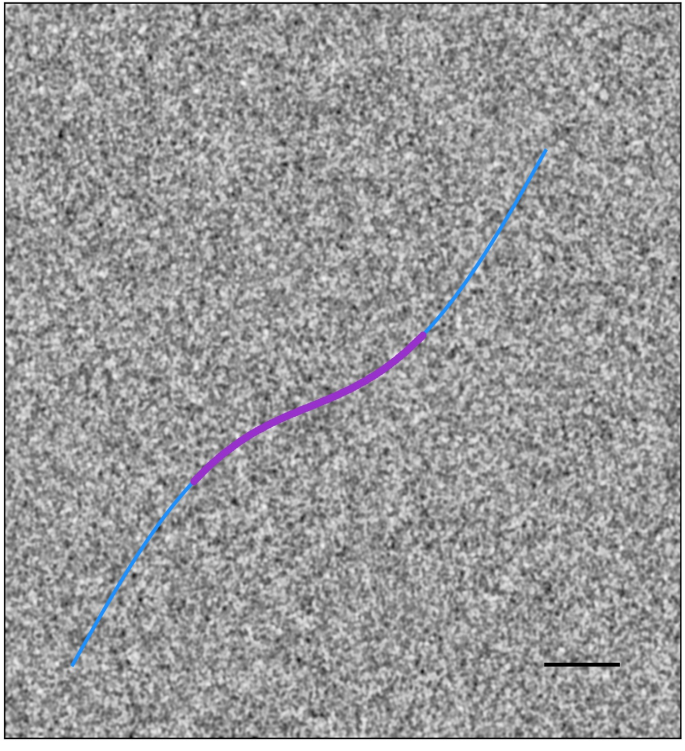

Index: BLUR: 2.0; LEVELS: 64; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

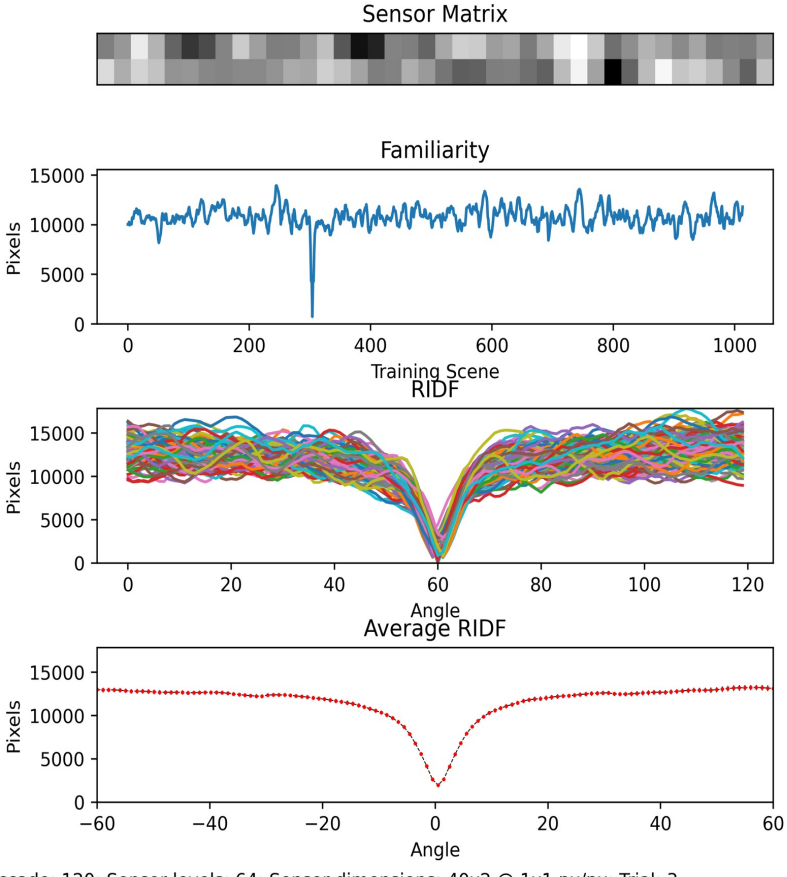




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

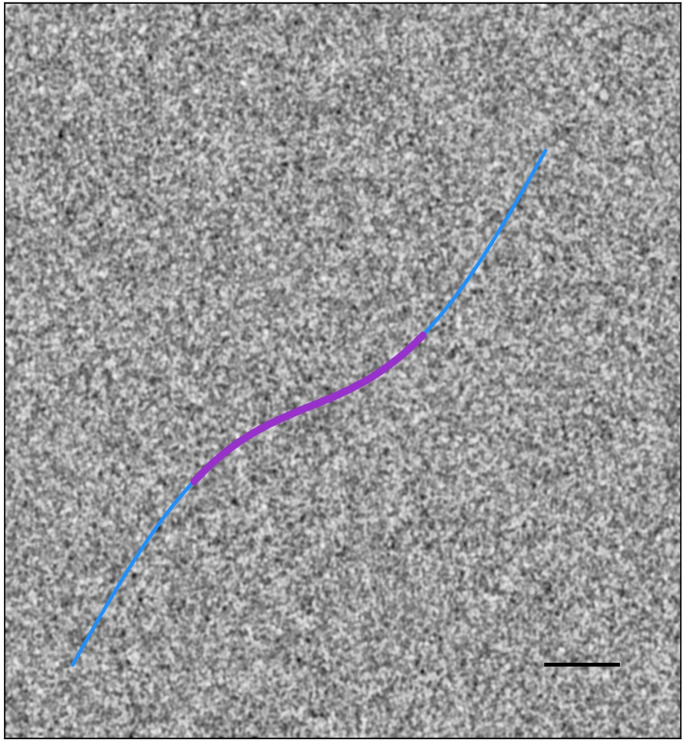
Navigation stats: RMSD error: 52.07; RMSD/dist: 0.130; TD: 7317; p90: 18; p50: 8; complete: 0

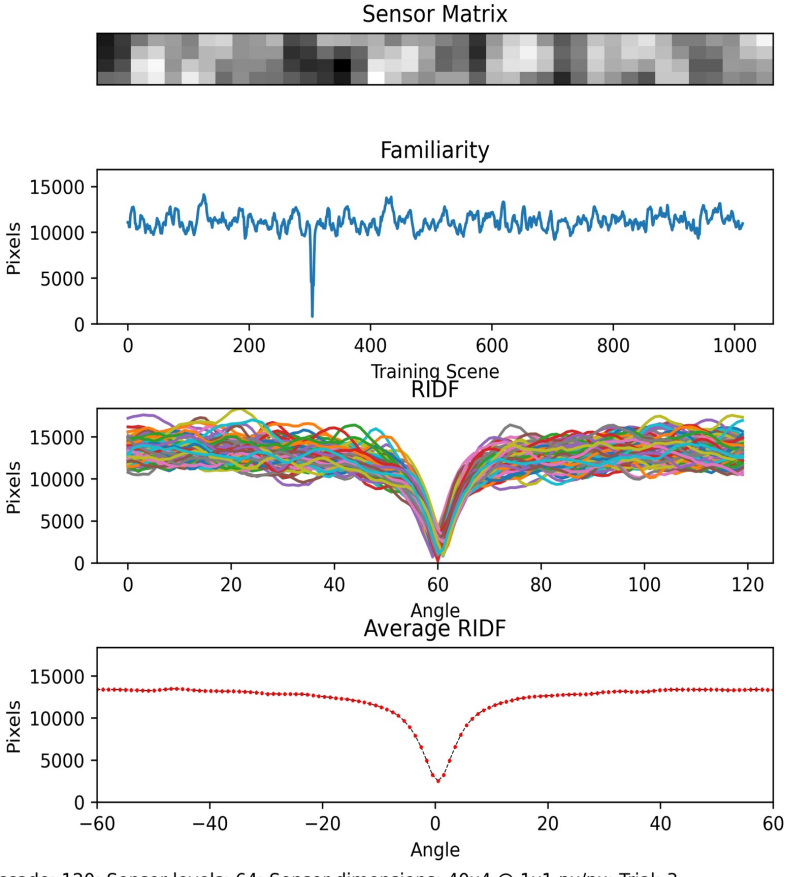




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

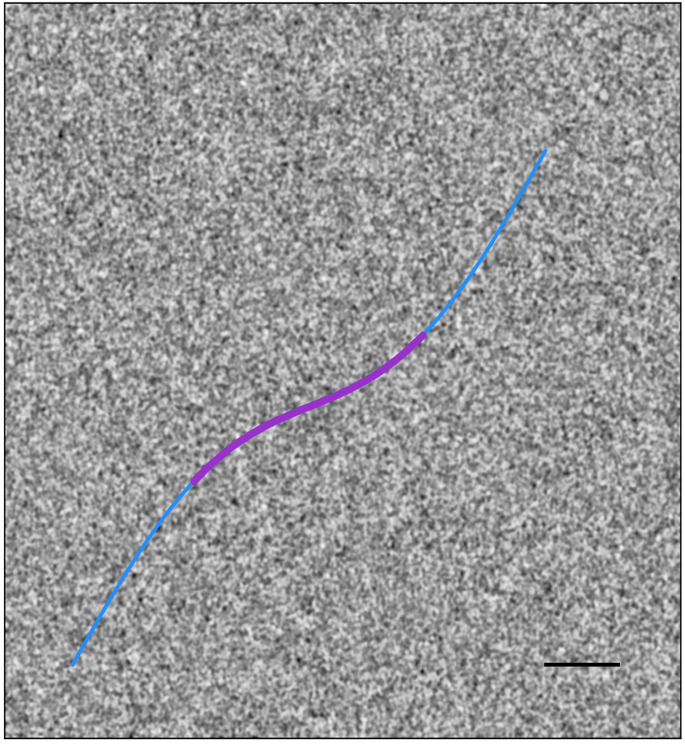
Navigation stats: RMSD error: 48.57; RMSD/dist: 0.121; TD: 8817; p90: 18; p50: 8; complete: 0

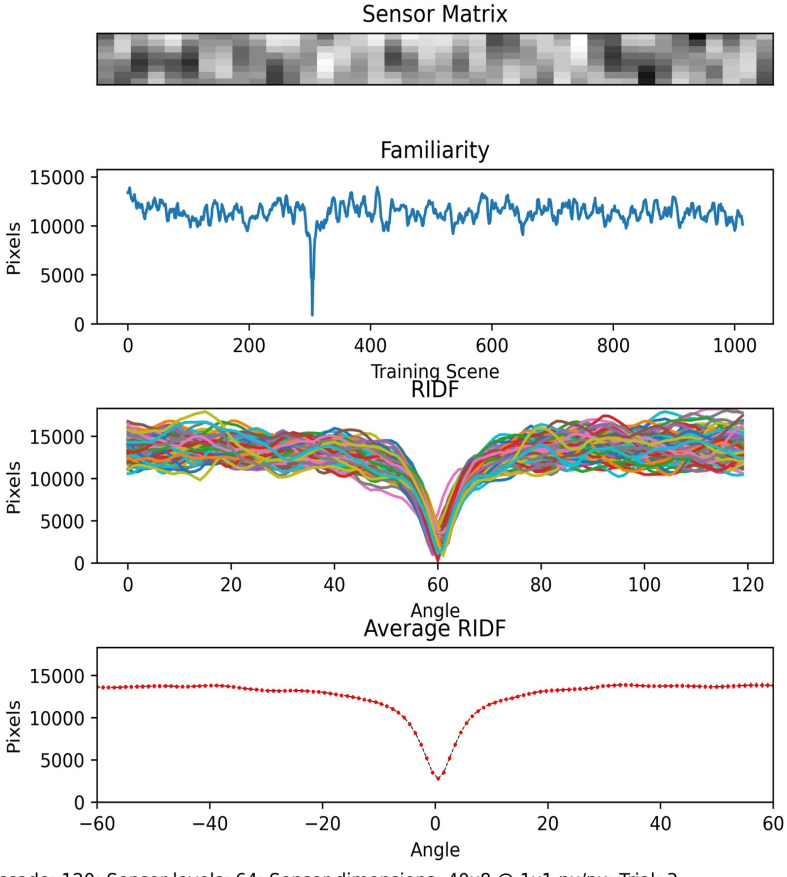




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

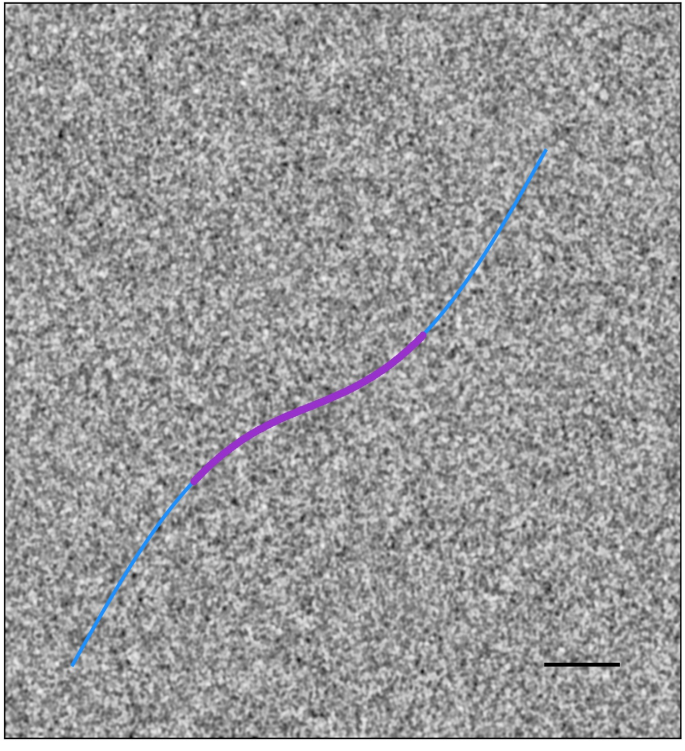
Navigation stats: RMSD error: 58.21; RMSD/dist: 0.146; TD: 8936; p90: 16; p50: 6; complete: 0

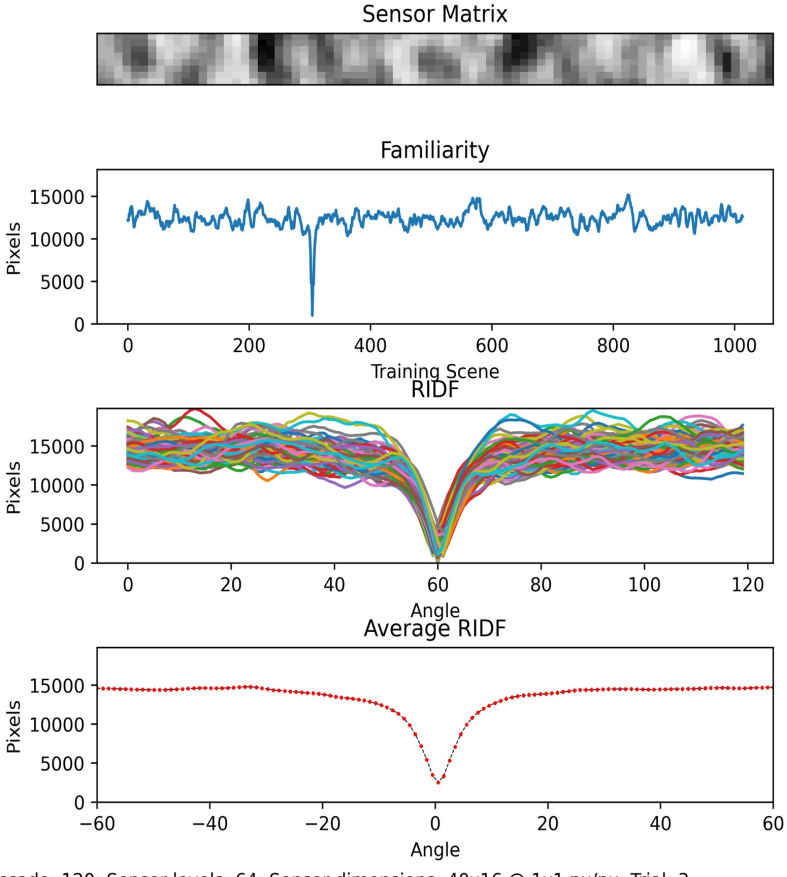




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

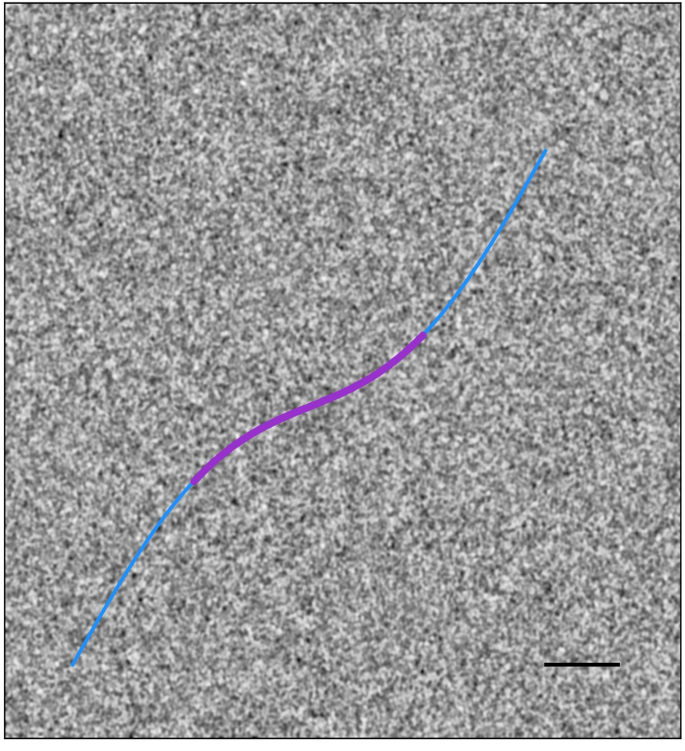
Navigation stats: RMSD error: 62.57; RMSD/dist: 0.156; TD: 8911; p90: 14; p50: 6; complete: 0

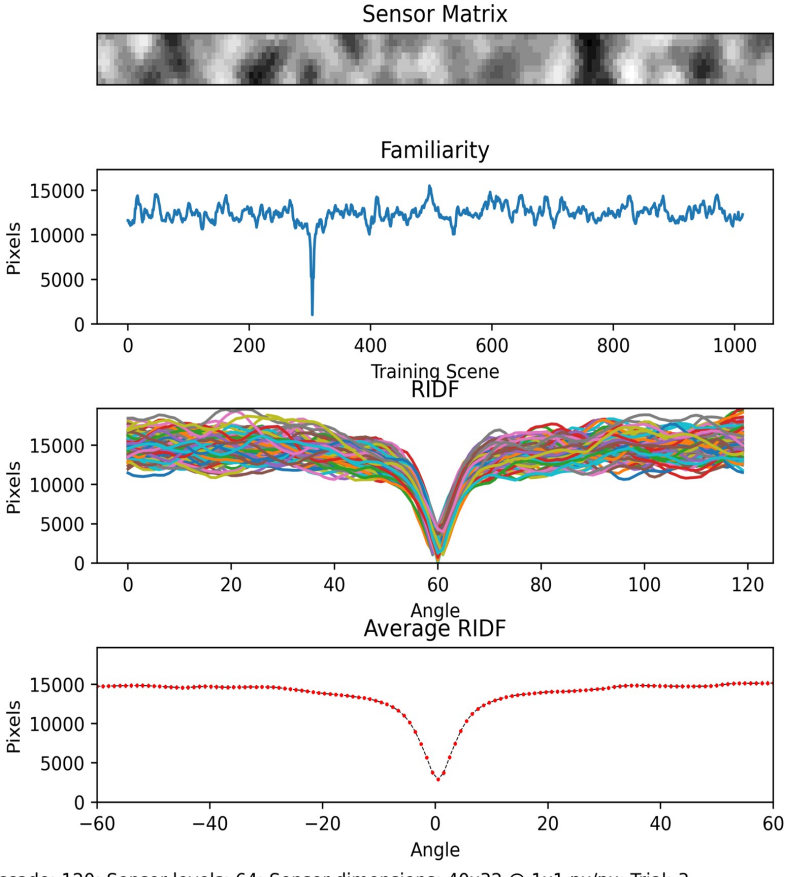




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

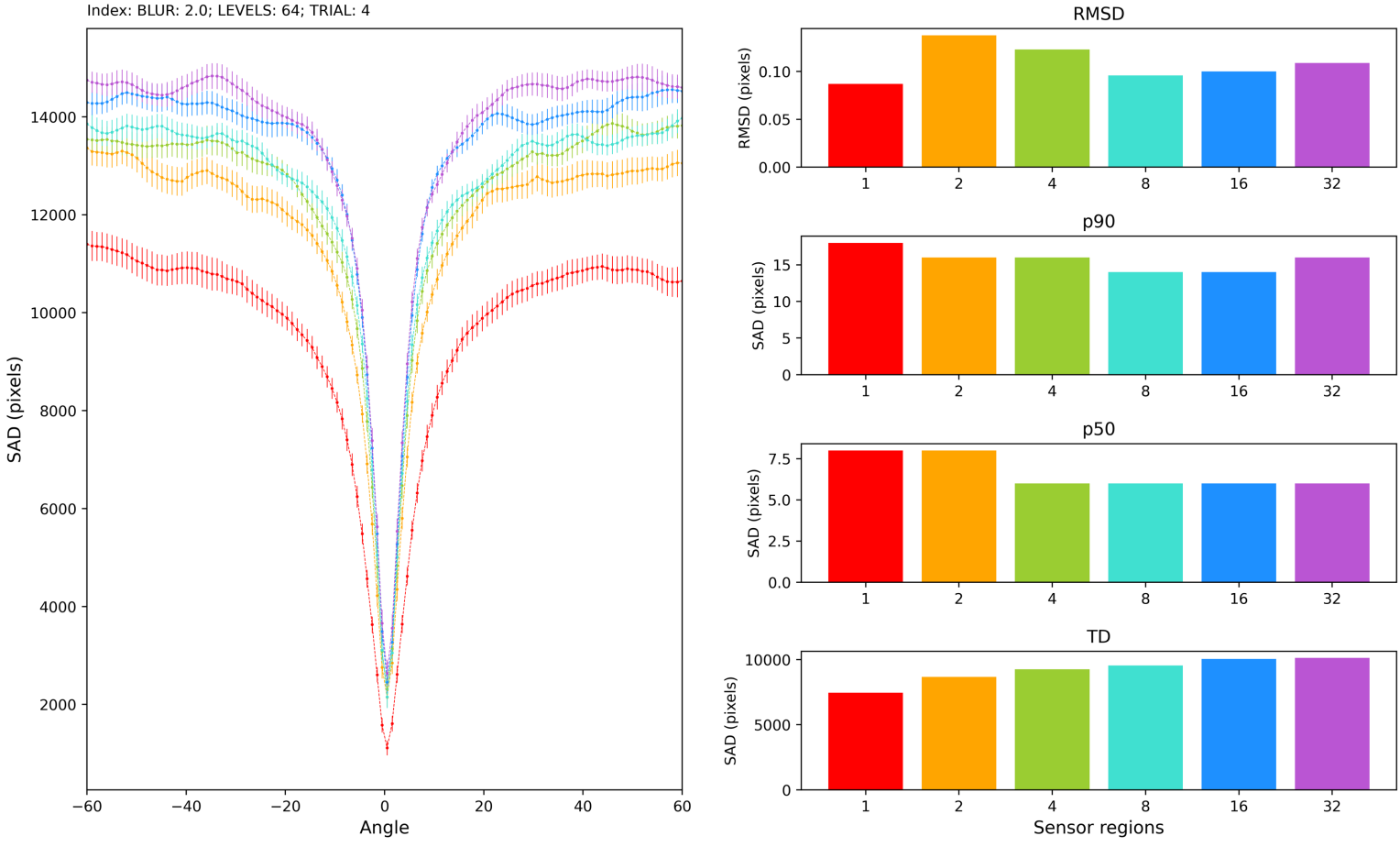
Navigation stats: RMSD error: 42.07; RMSD/dist: 0.105; TD: 10085; p90: 16; p50: 6; complete: 0

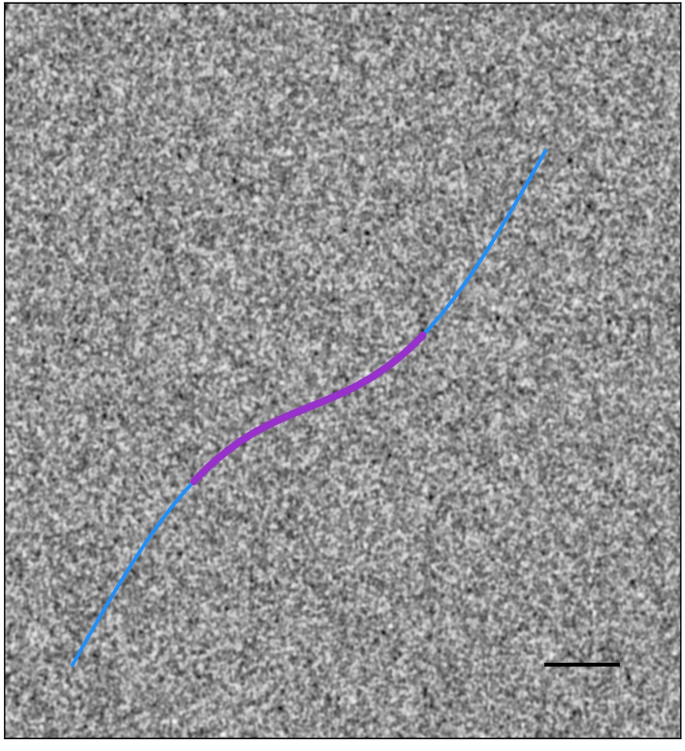


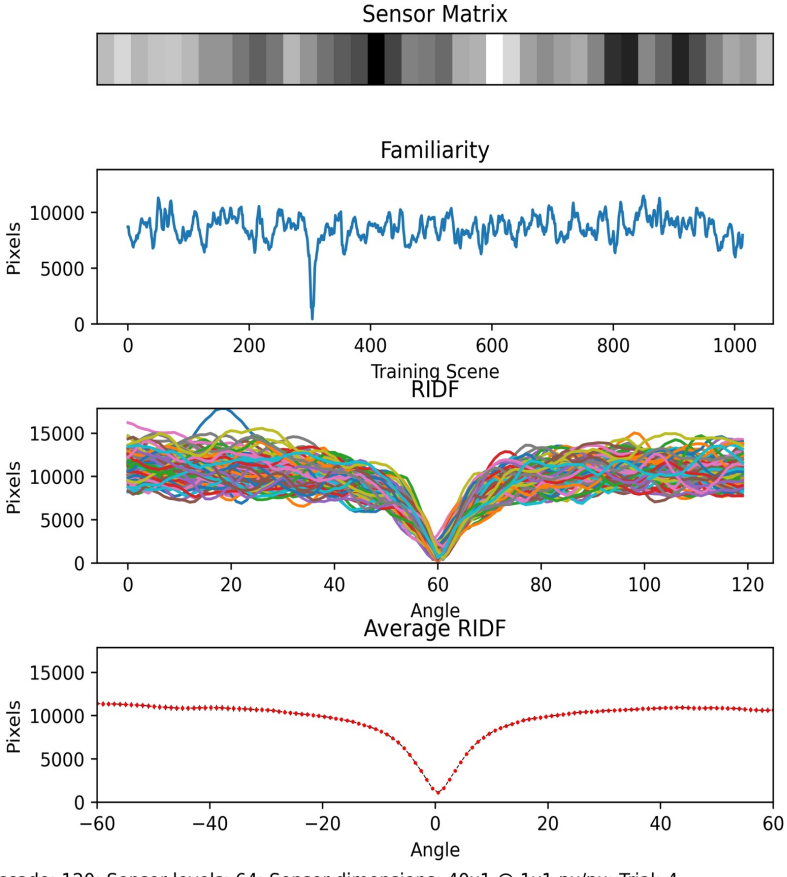


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 51.32; RMSD/dist: 0.128; TD: 10078; p90: 16; p50: 6; complete: 0

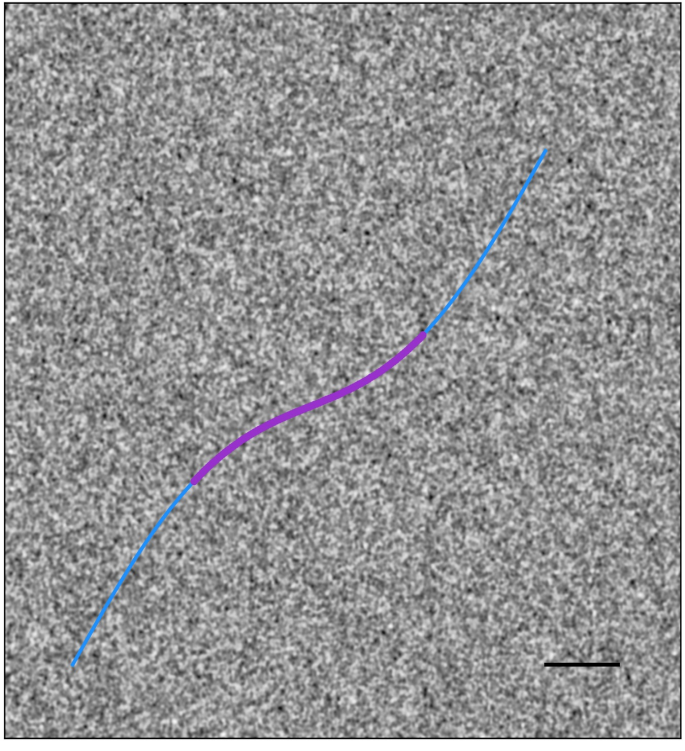

Index: BLUR: 2.0; LEVELS: 64; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

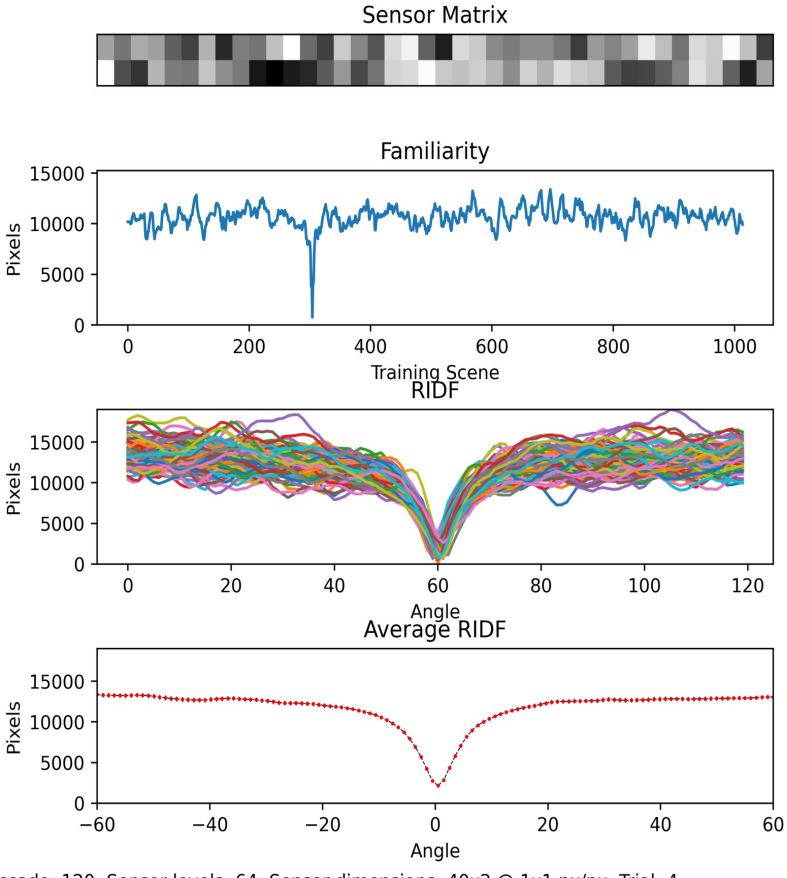




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

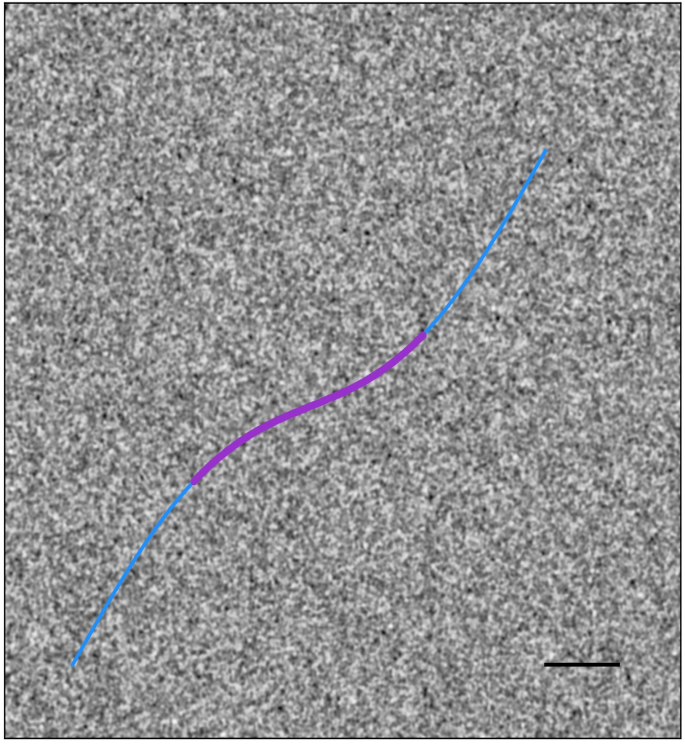
Navigation stats: RMSD error: 34.85; RMSD/dist: 0.087; TD: 7452; p90: 18; p50: 8; complete: 0

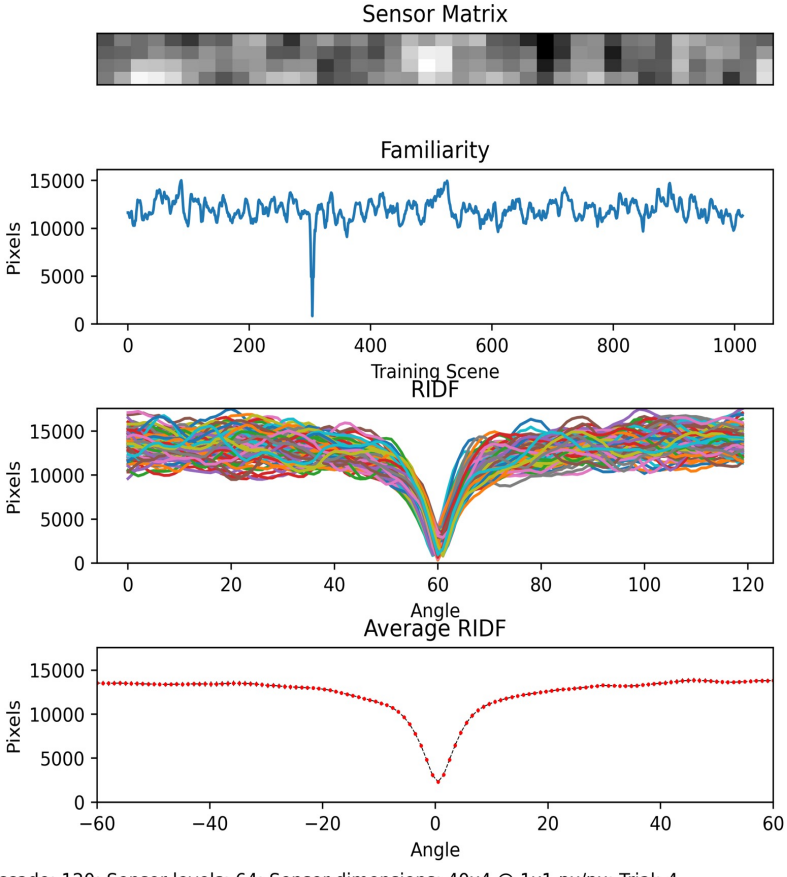




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

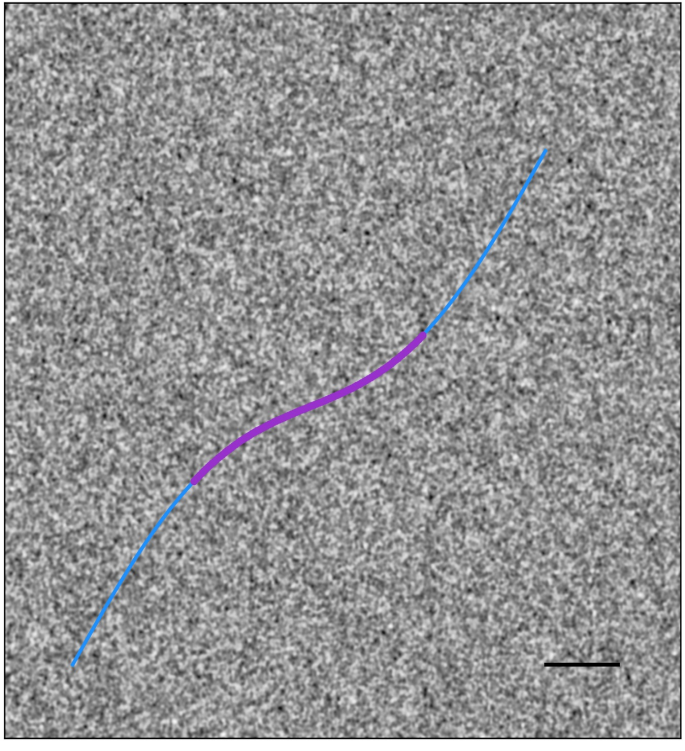
Navigation stats: RMSD error: 55.12; RMSD/dist: 0.138; TD: 8681; p90: 16; p50: 8; complete: 0

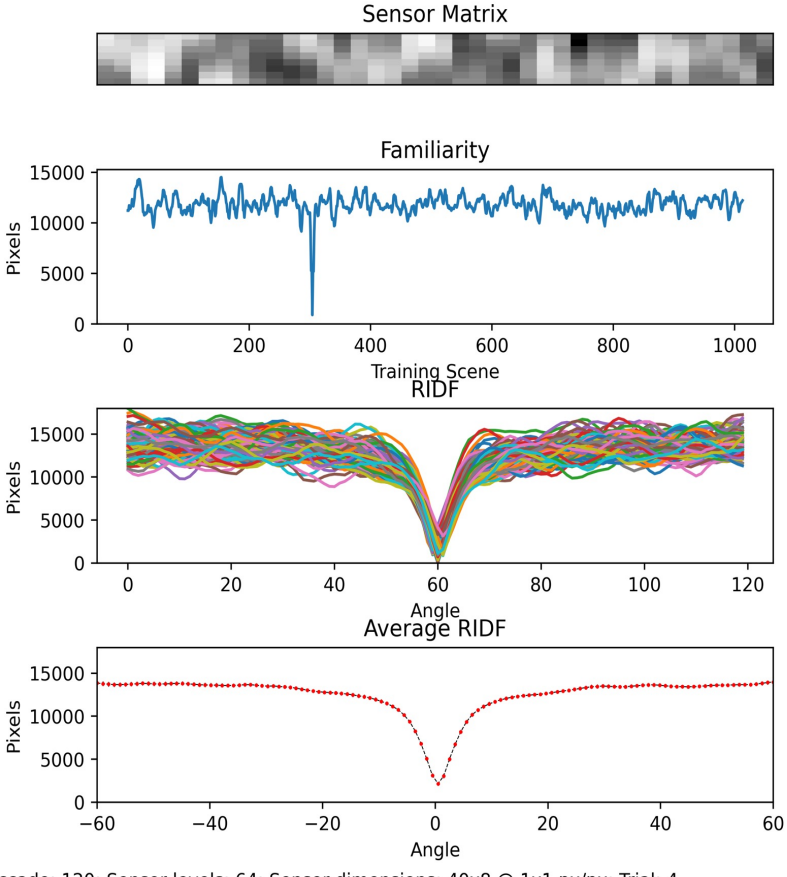




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

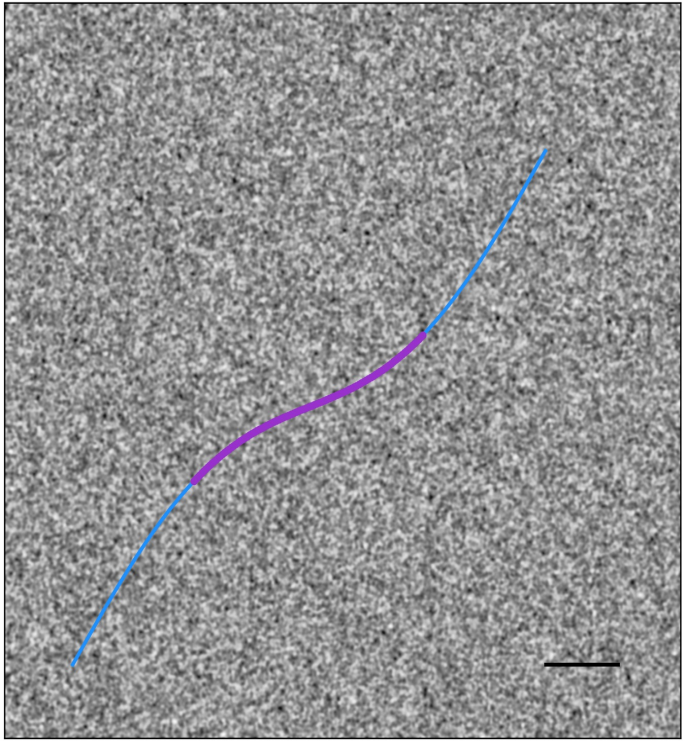
Navigation stats: RMSD error: 49.30; RMSD/dist: 0.123; TD: 9253; p90: 16; p50: 6; complete: 0

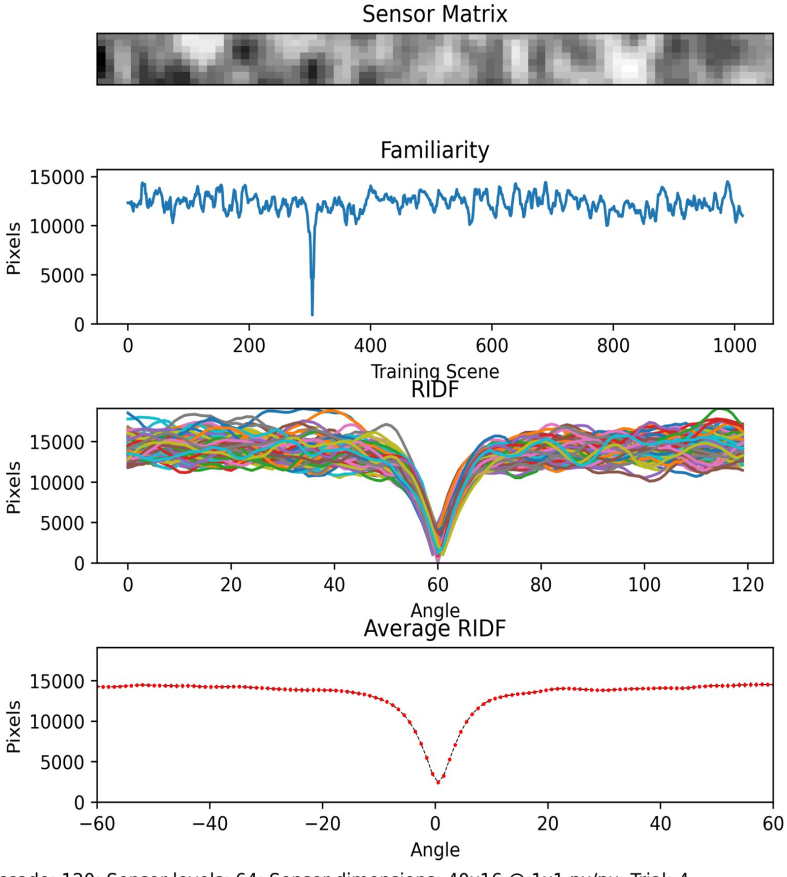




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

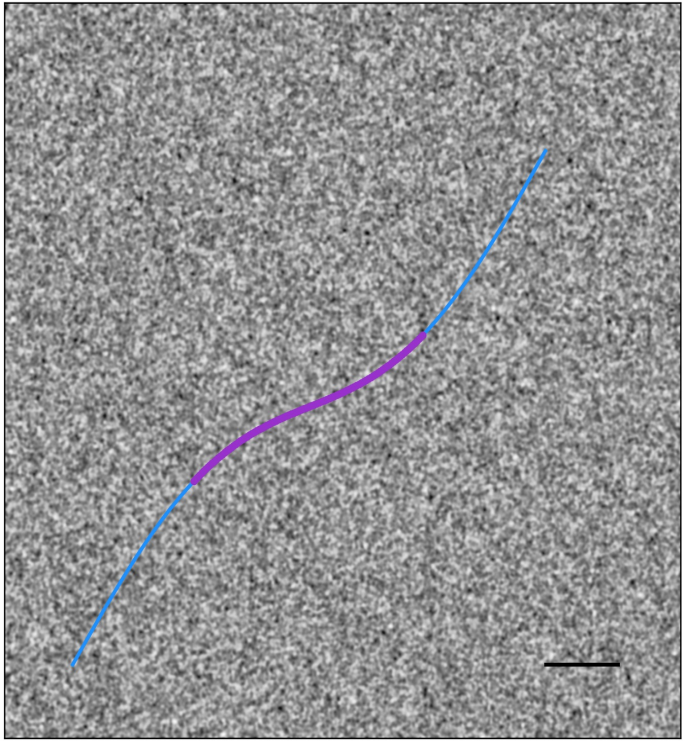
Navigation stats: RMSD error: 38.51; RMSD/dist: 0.096; TD: 9550; p90: 14; p50: 6; complete: 0

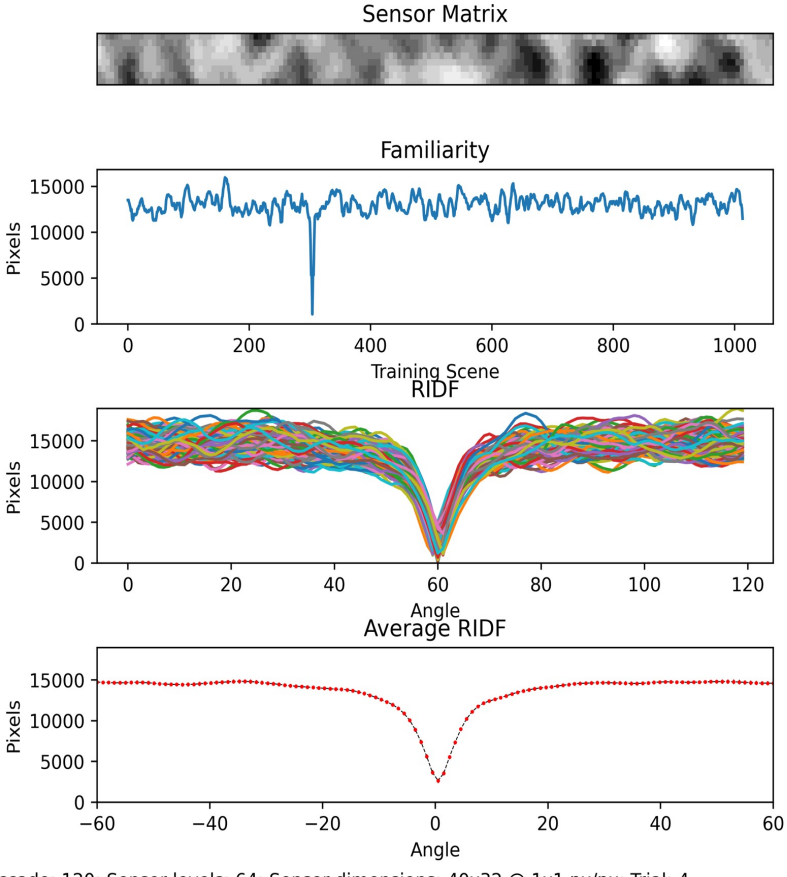




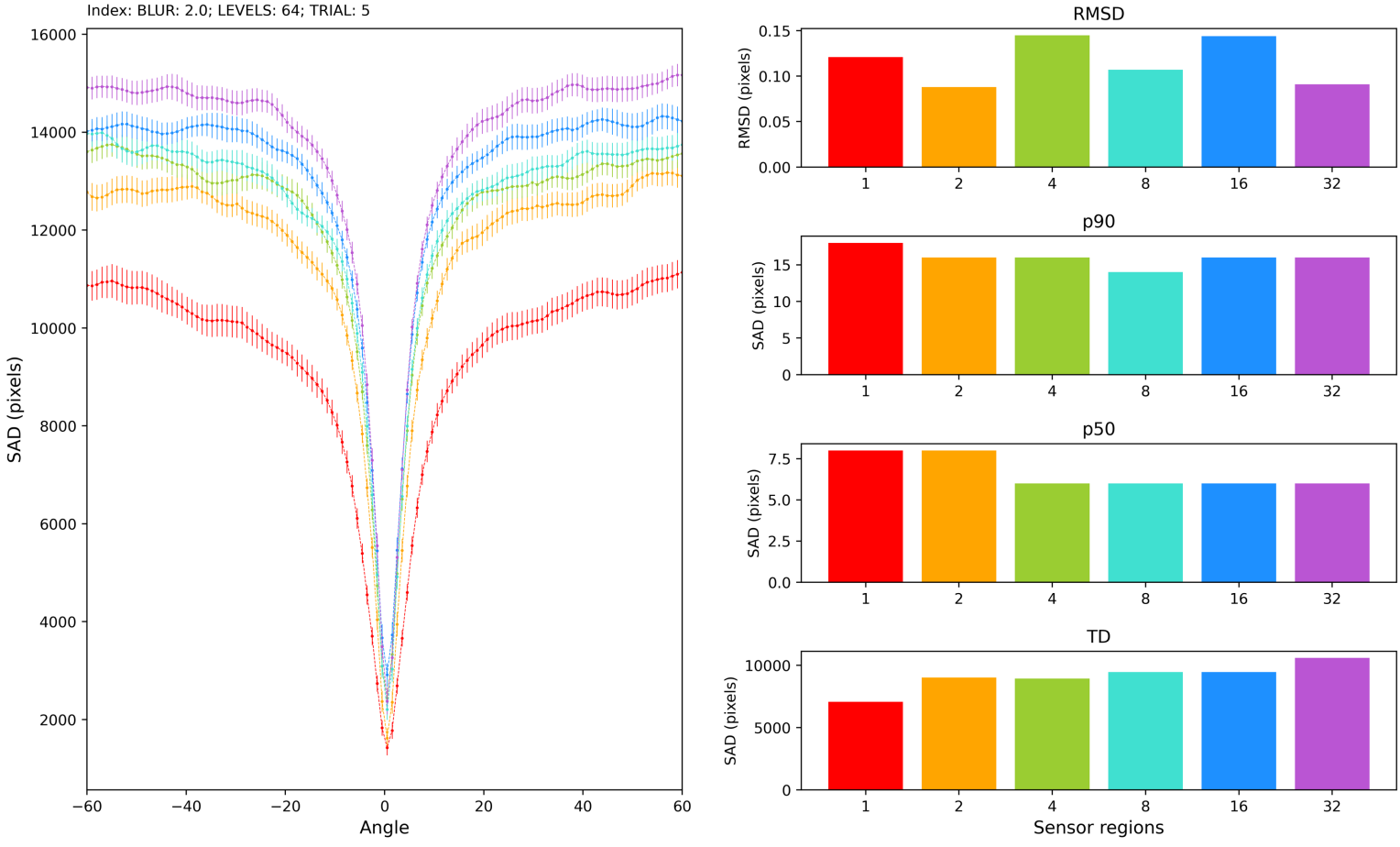
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

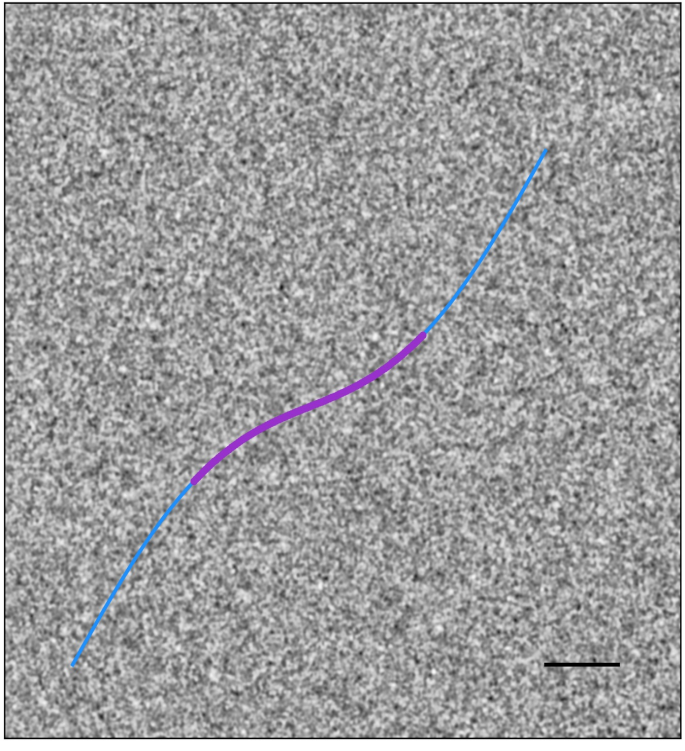
Navigation stats: RMSD error: 39.89; RMSD/dist: 0.100; TD: 10056; p90: 14; p50: 6; complete: 0

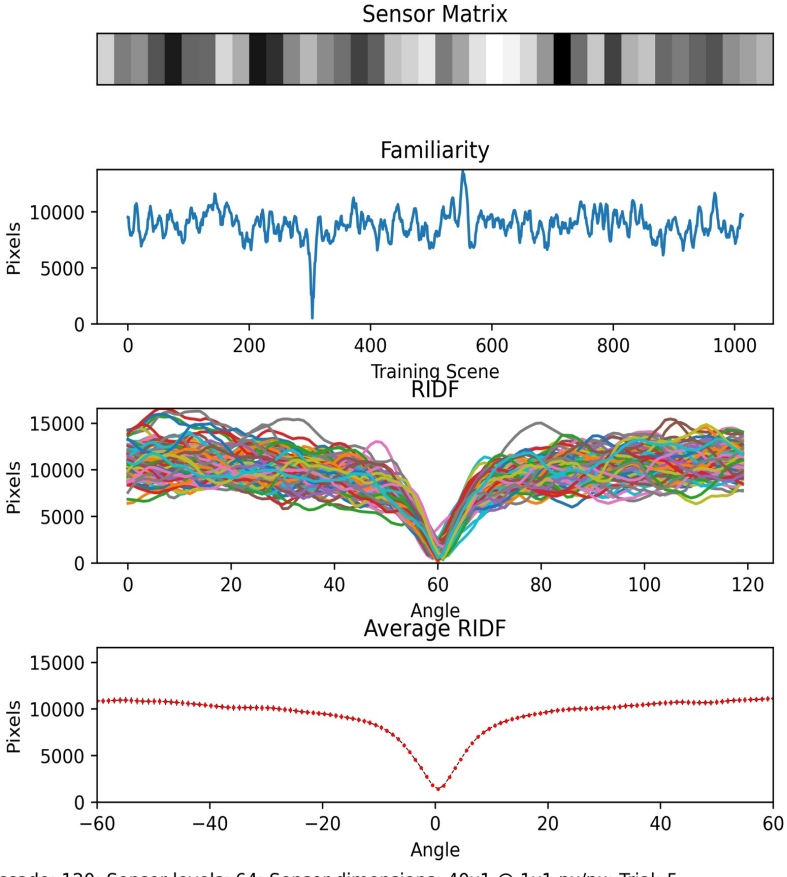




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 43.69; RMSD/dist: 0.109; TD: 10125; p90: 16; p50: 6; complete: 0

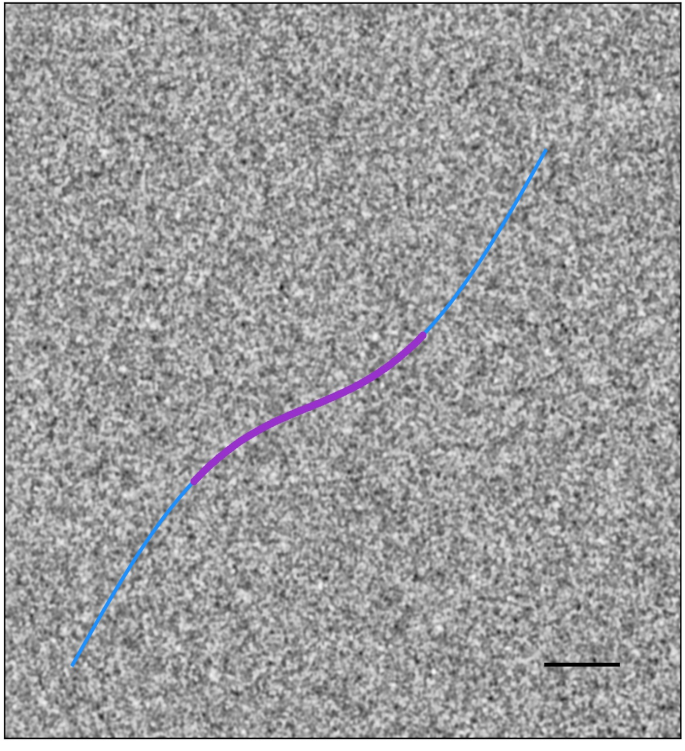

Index: BLUR: 2.0; LEVELS: 64; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

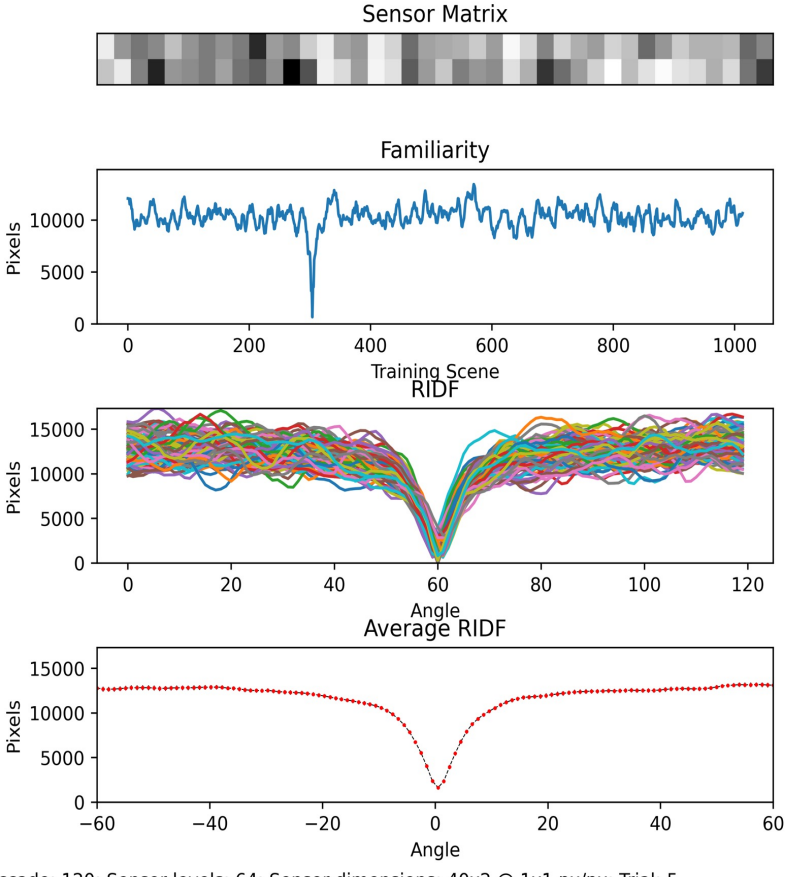




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

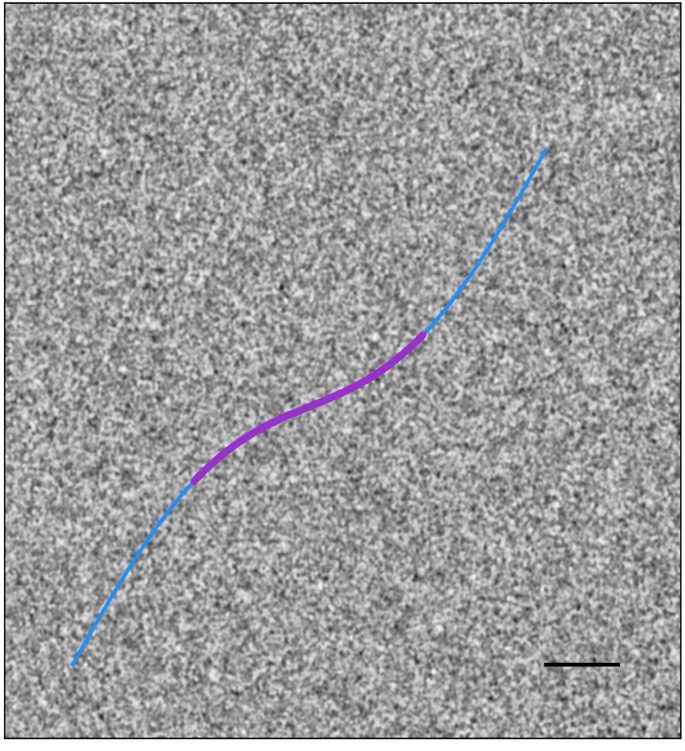
Navigation stats: RMSD error: 48.21; RMSD/dist: 0.121; TD: 7072; p90: 18; p50: 8; complete: 0

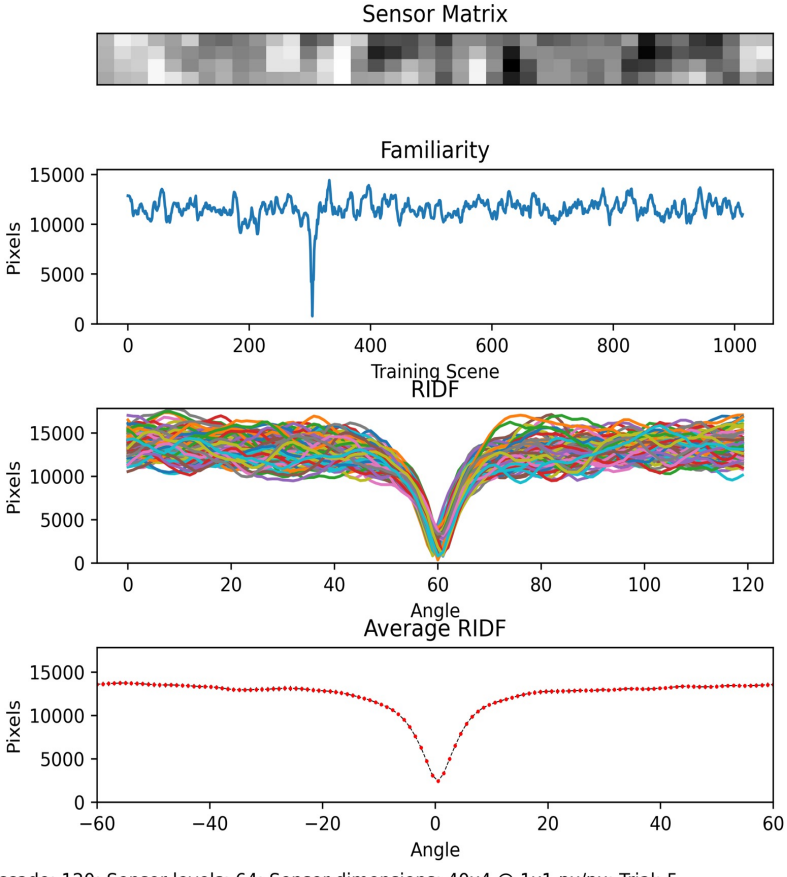




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

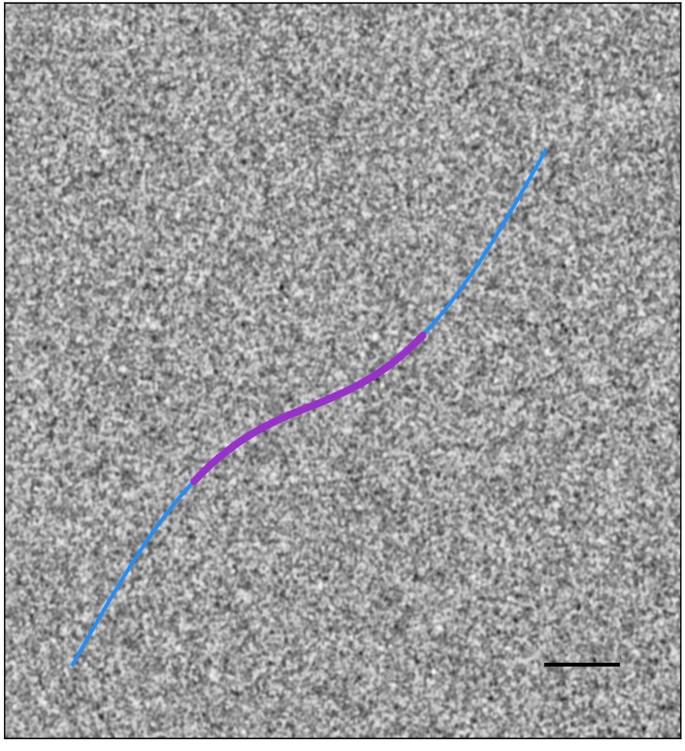
Navigation stats: RMSD error: 35.24; RMSD/dist: 0.088; TD: 9022; p90: 16; p50: 8; complete: 0

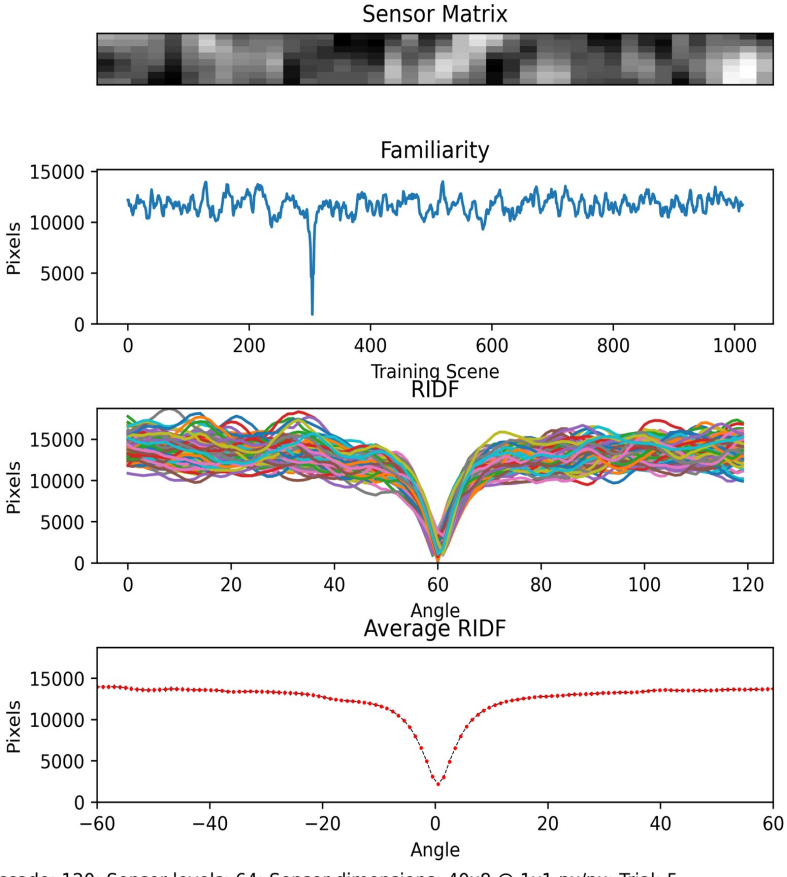




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

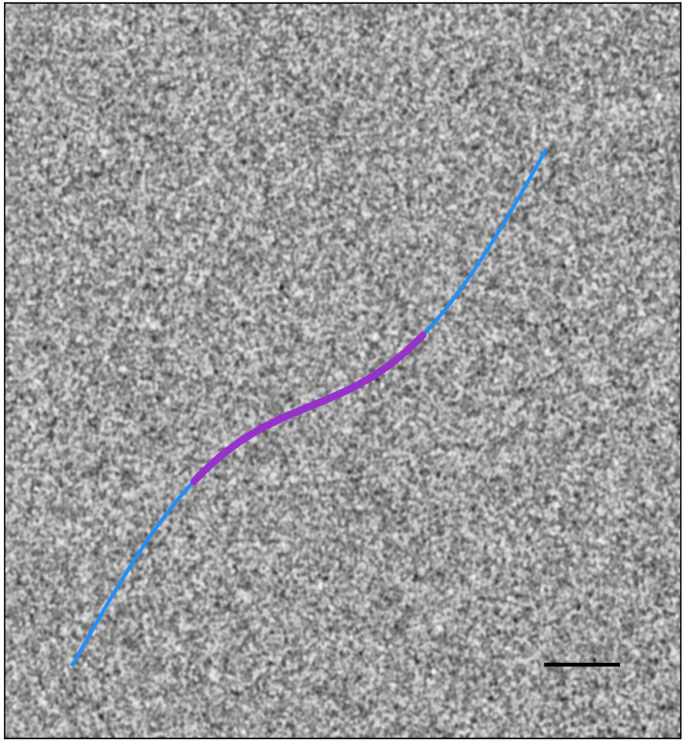
Navigation stats: RMSD error: 58.17; RMSD/dist: 0.145; TD: 8934; p90: 16; p50: 6; complete: 0

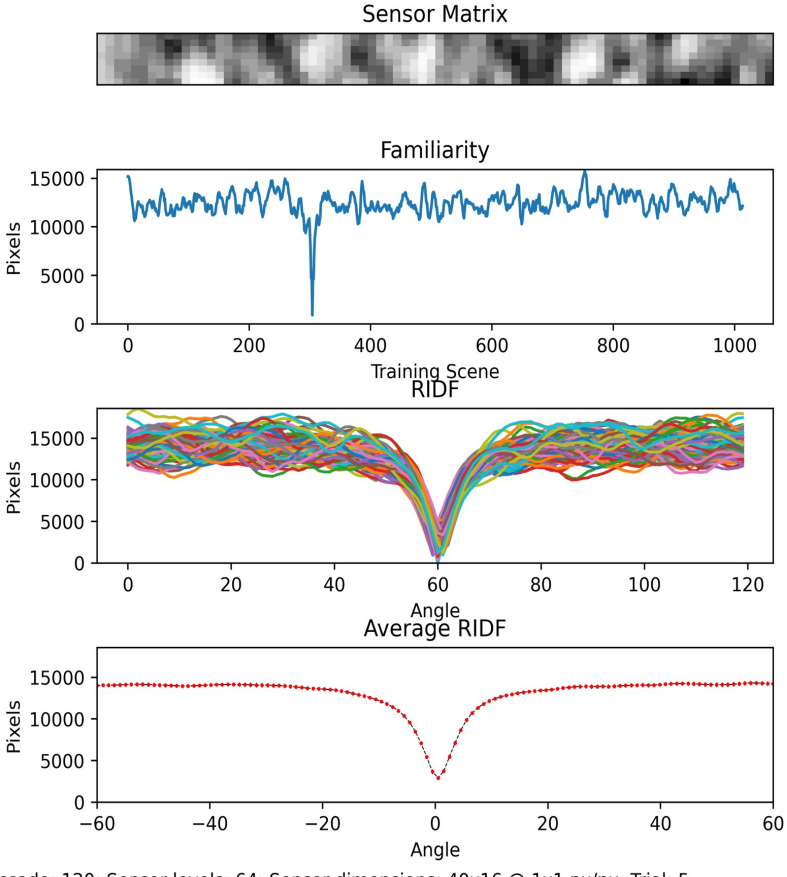




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

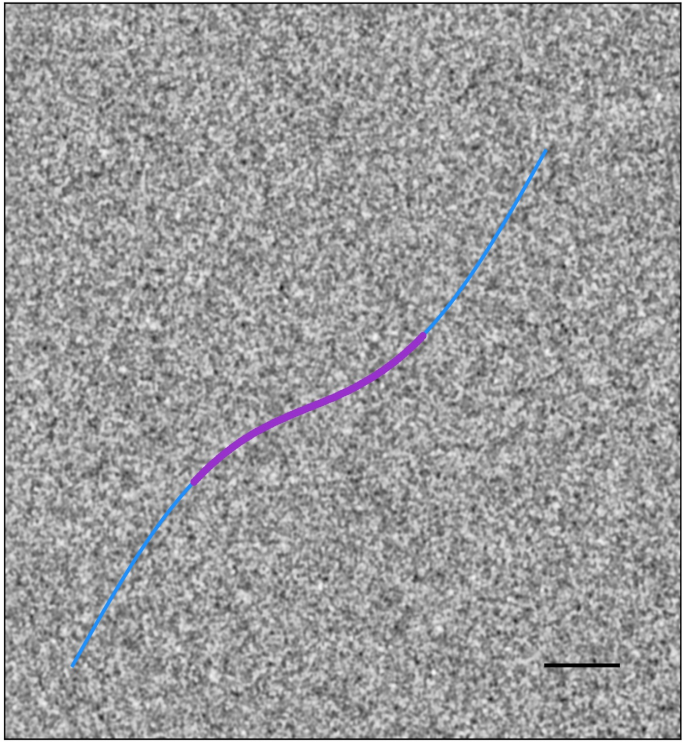
Navigation stats: RMSD error: 42.75; RMSD/dist: 0.107; TD: 9464; p90: 14; p50: 6; complete: 0

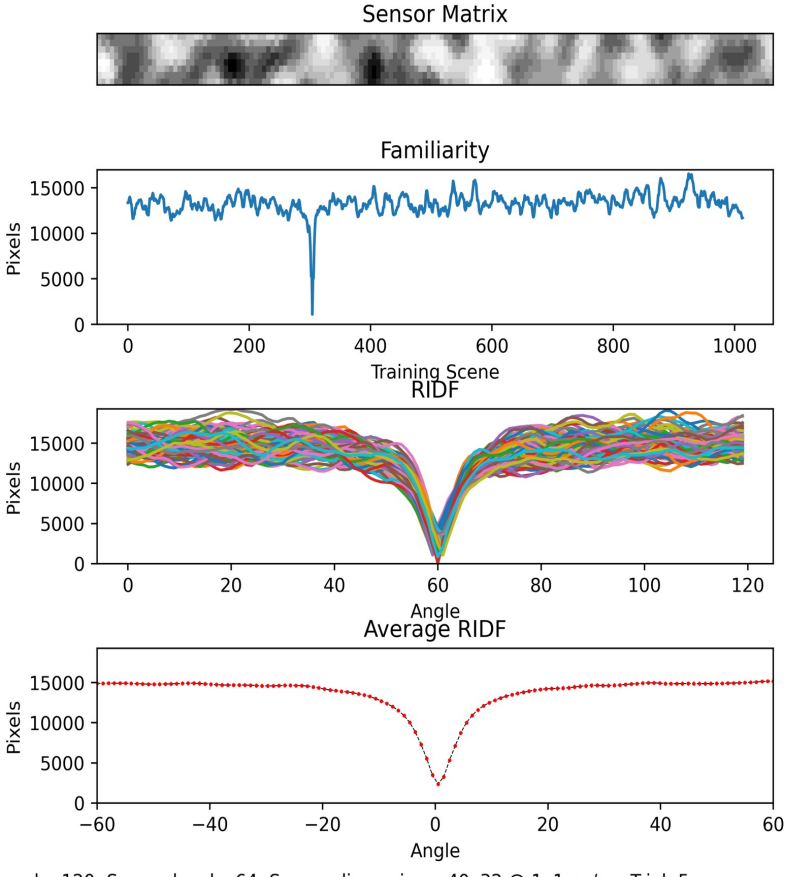




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

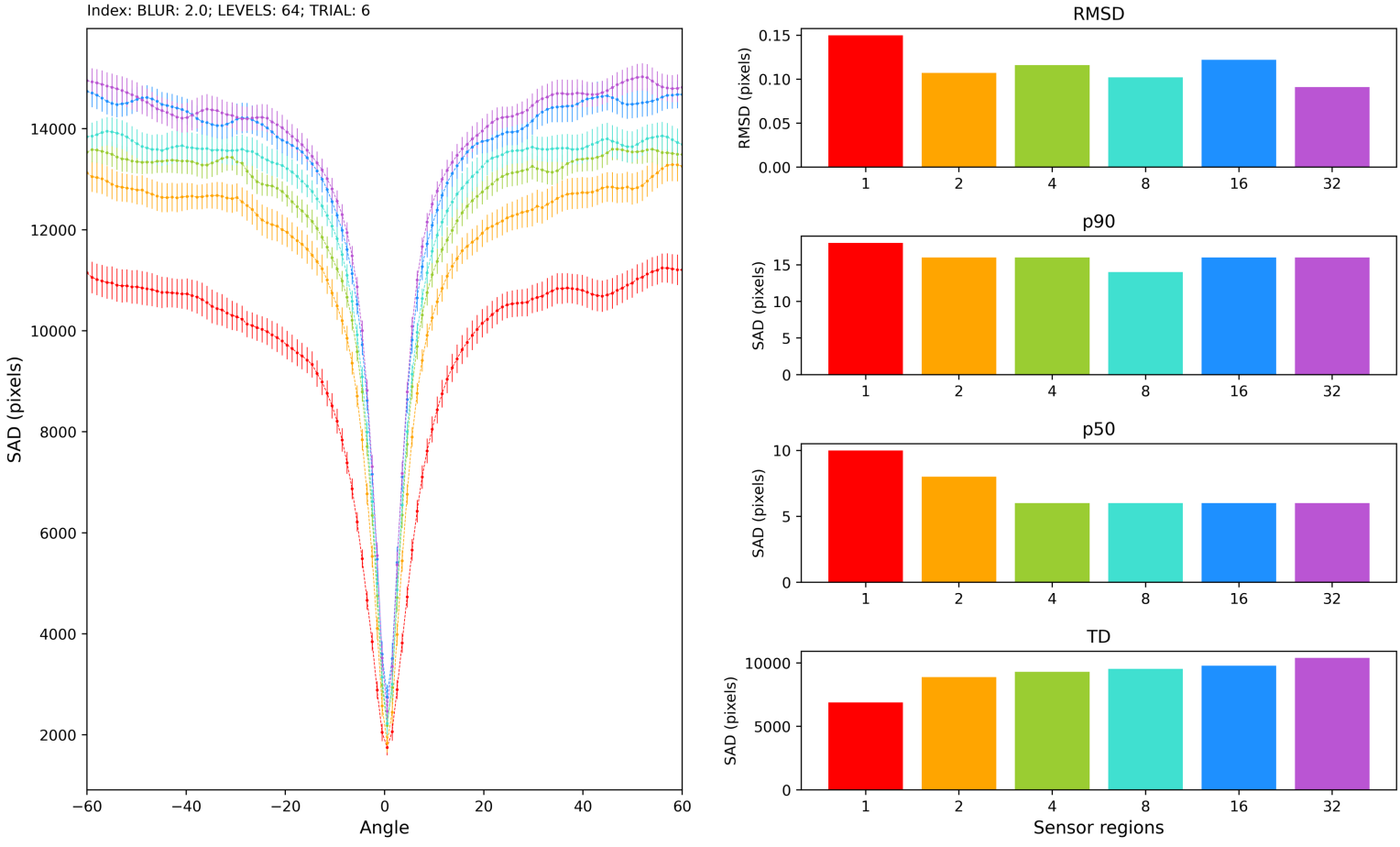
Navigation stats: RMSD error: 57.75; RMSD/dist: 0.144; TD: 9451; p90: 16; p50: 6; complete: 0

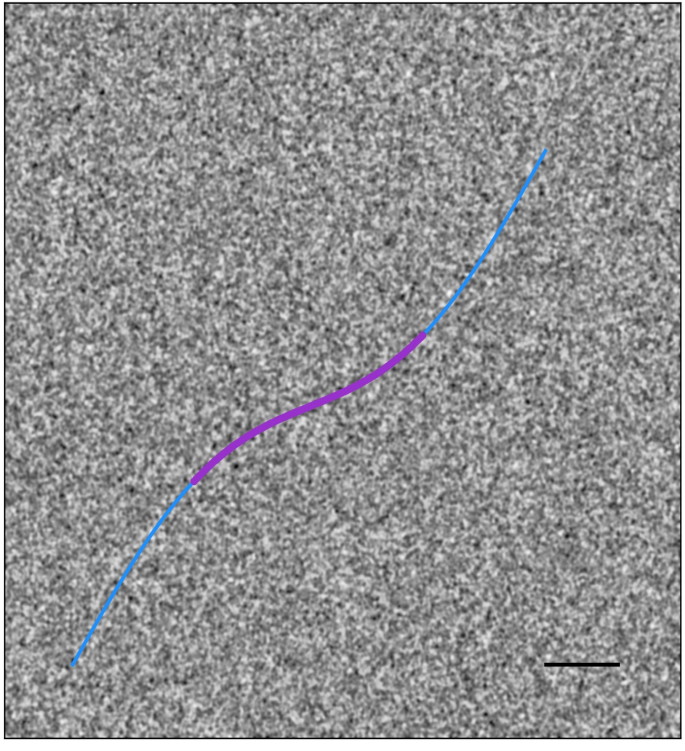


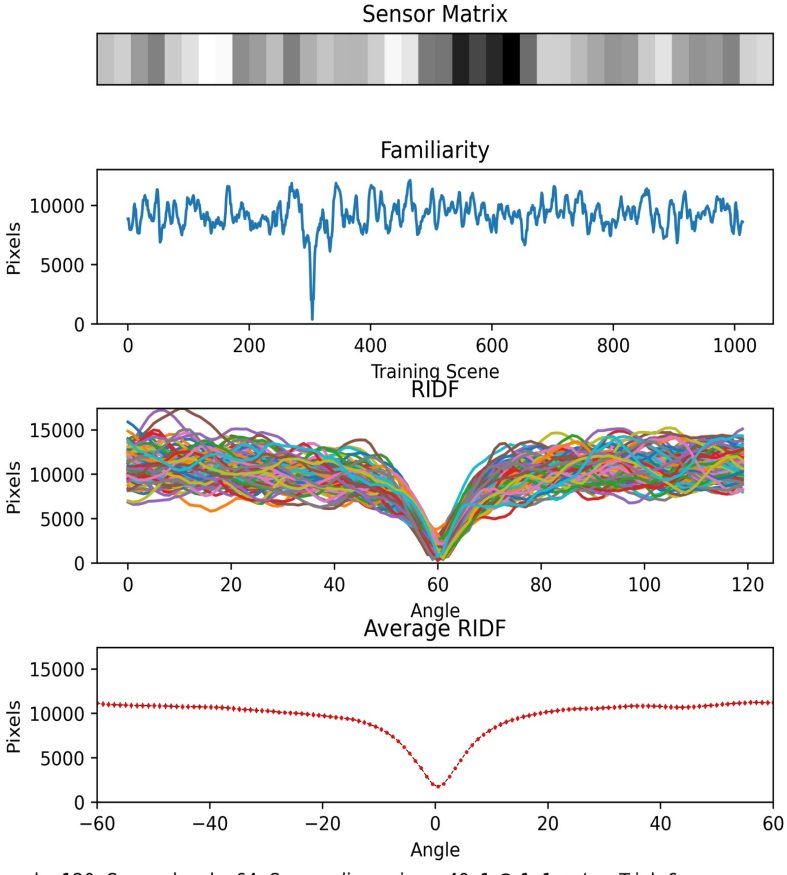


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 36.26; RMSD/dist: 0.091; TD: 10584; p90: 16; p50: 6; complete: 0

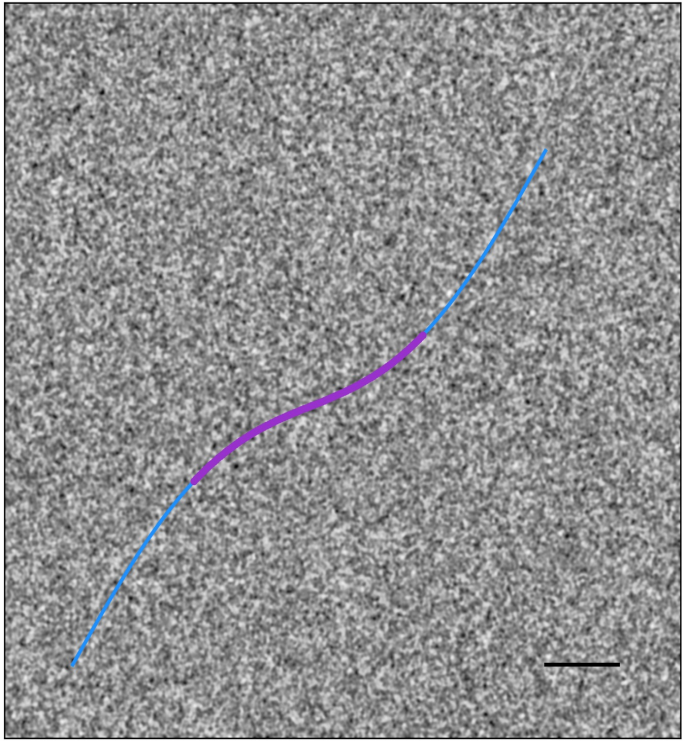

Index: BLUR: 2.0; LEVELS: 64; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

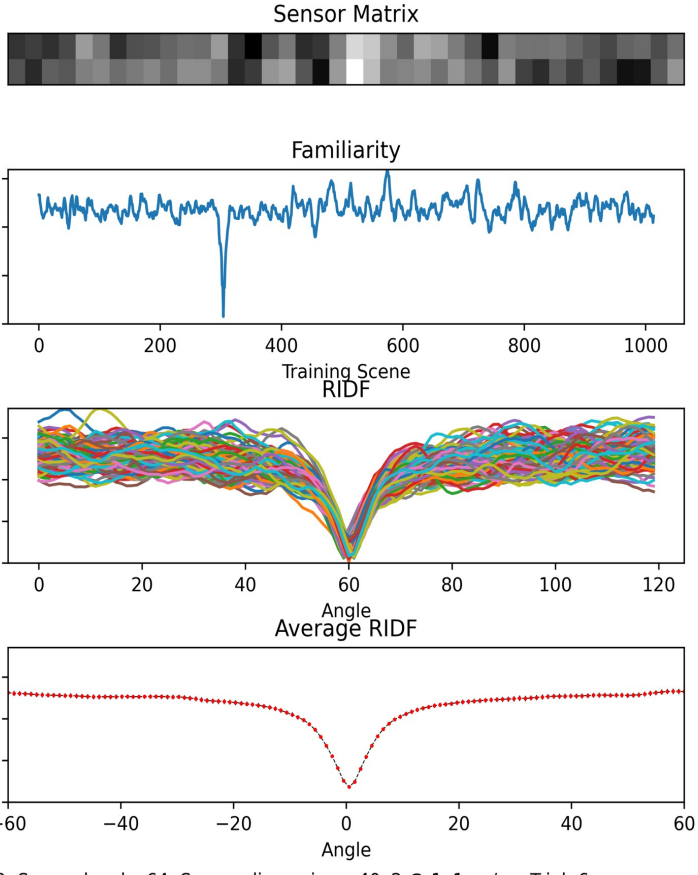




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

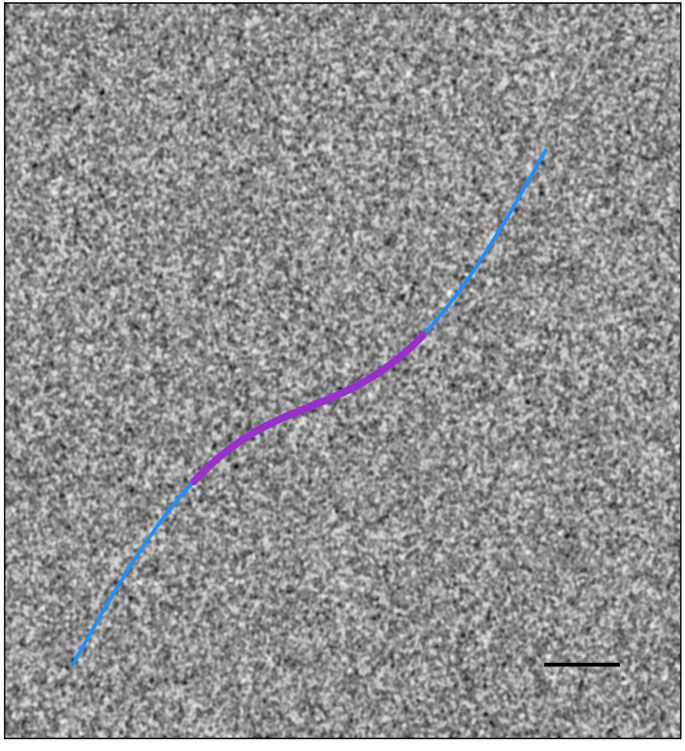
Navigation stats: RMSD error: 60.13; RMSD/dist: 0.150; TD: 6883; p90: 18; p50: 10; complete: 0

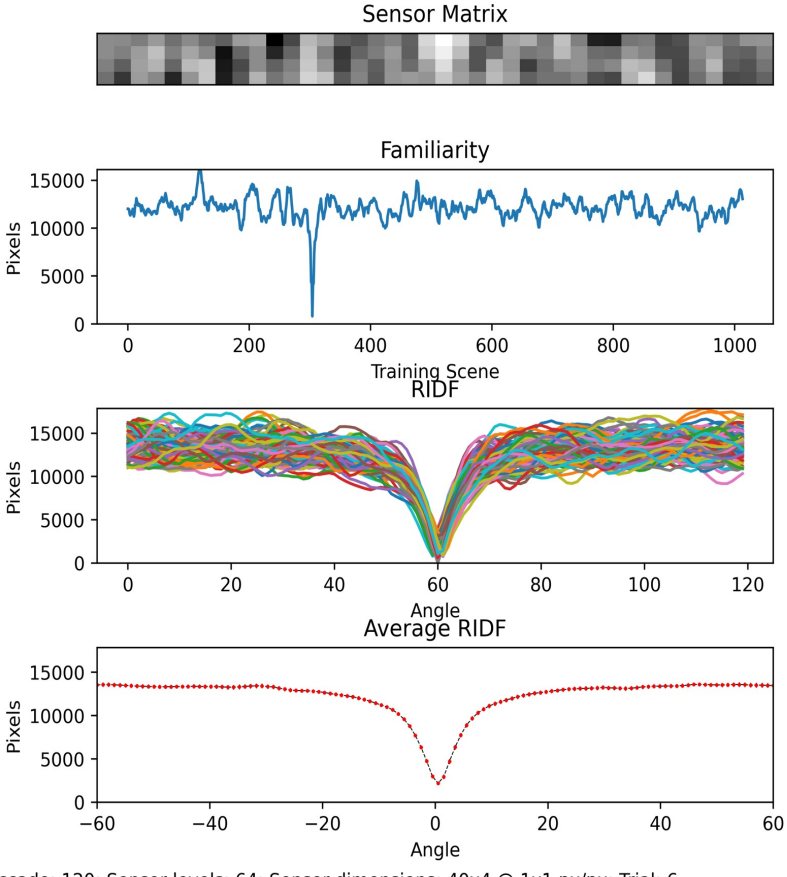




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

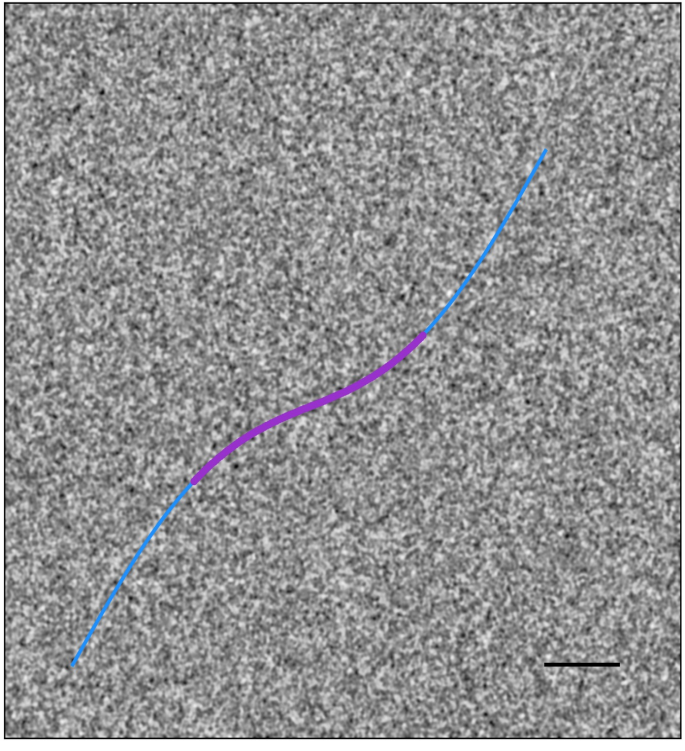
Navigation stats: RMSD error: 42.92; RMSD/dist: 0.107; TD: 8880; p90: 16; p50: 8; complete: 0

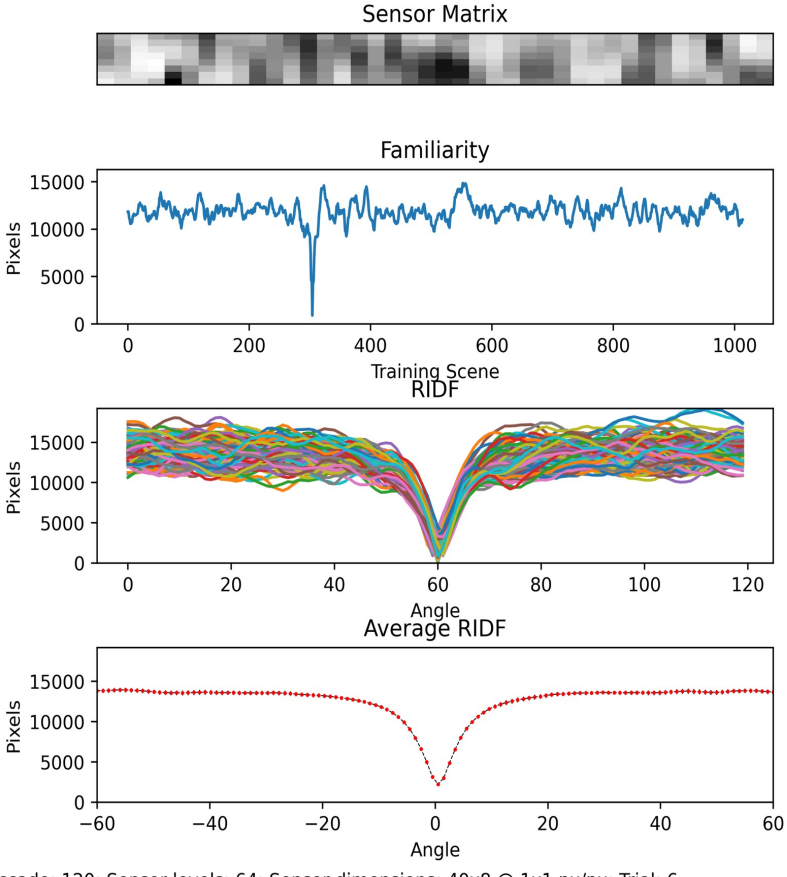




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

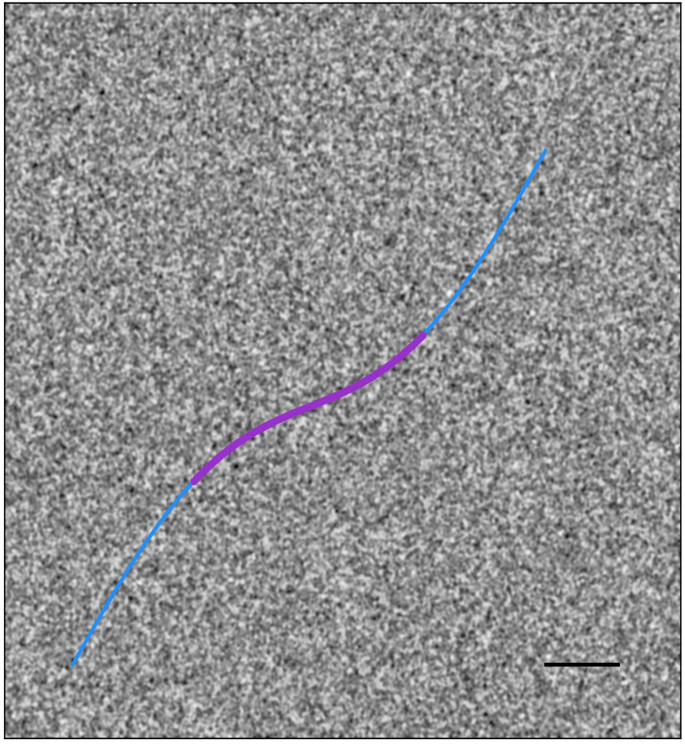
Navigation stats: RMSD error: 46.39; RMSD/dist: 0.116; TD: 9309; p90: 16; p50: 6; complete: 0

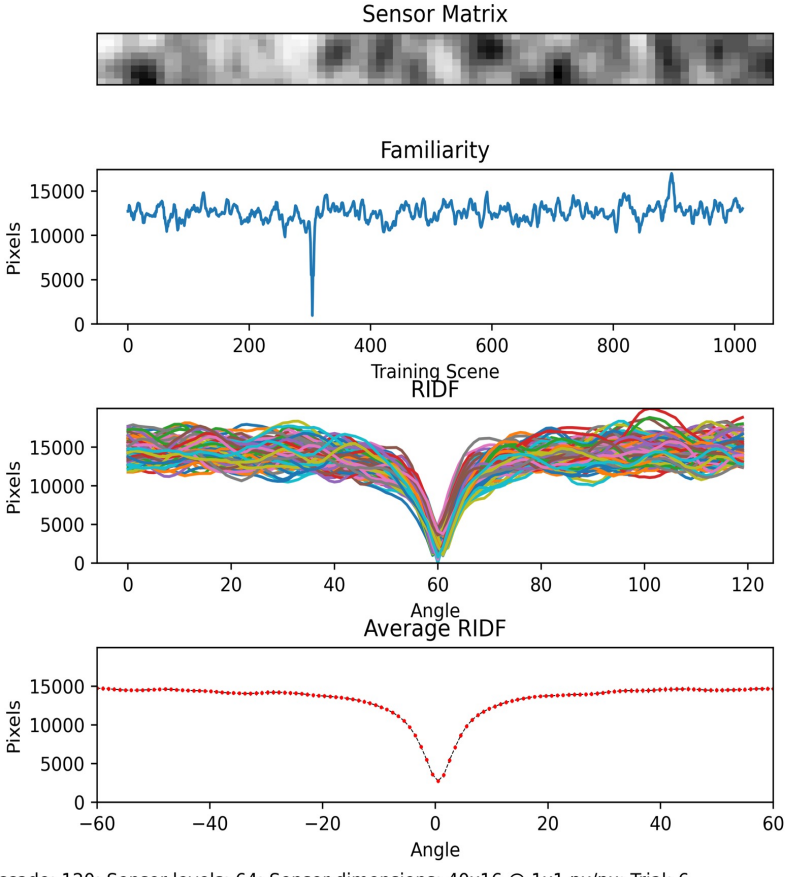




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

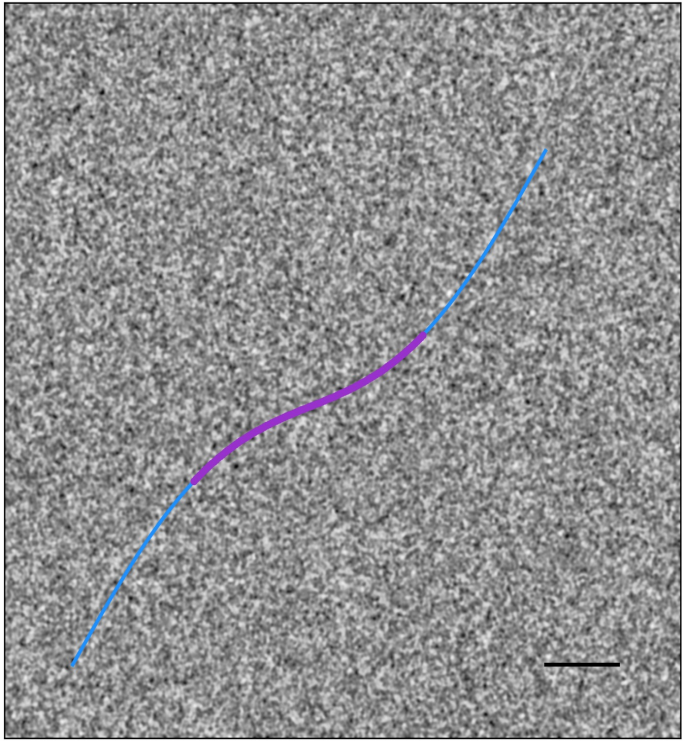
Navigation stats: RMSD error: 40.96; RMSD/dist: 0.102; TD: 9541; p90: 14; p50: 6; complete: 0

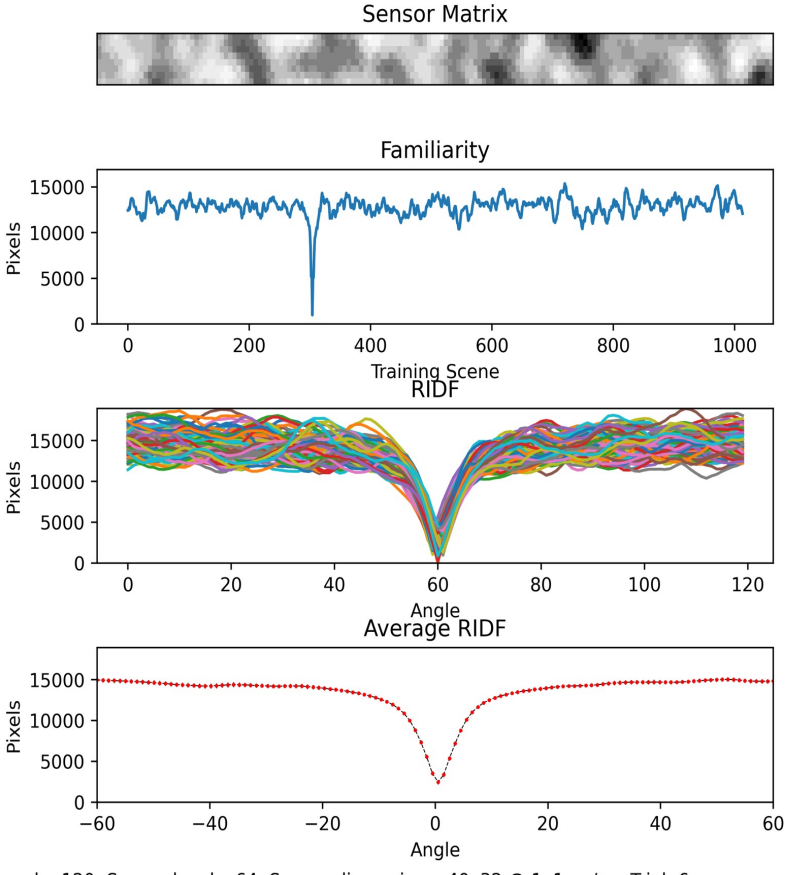




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

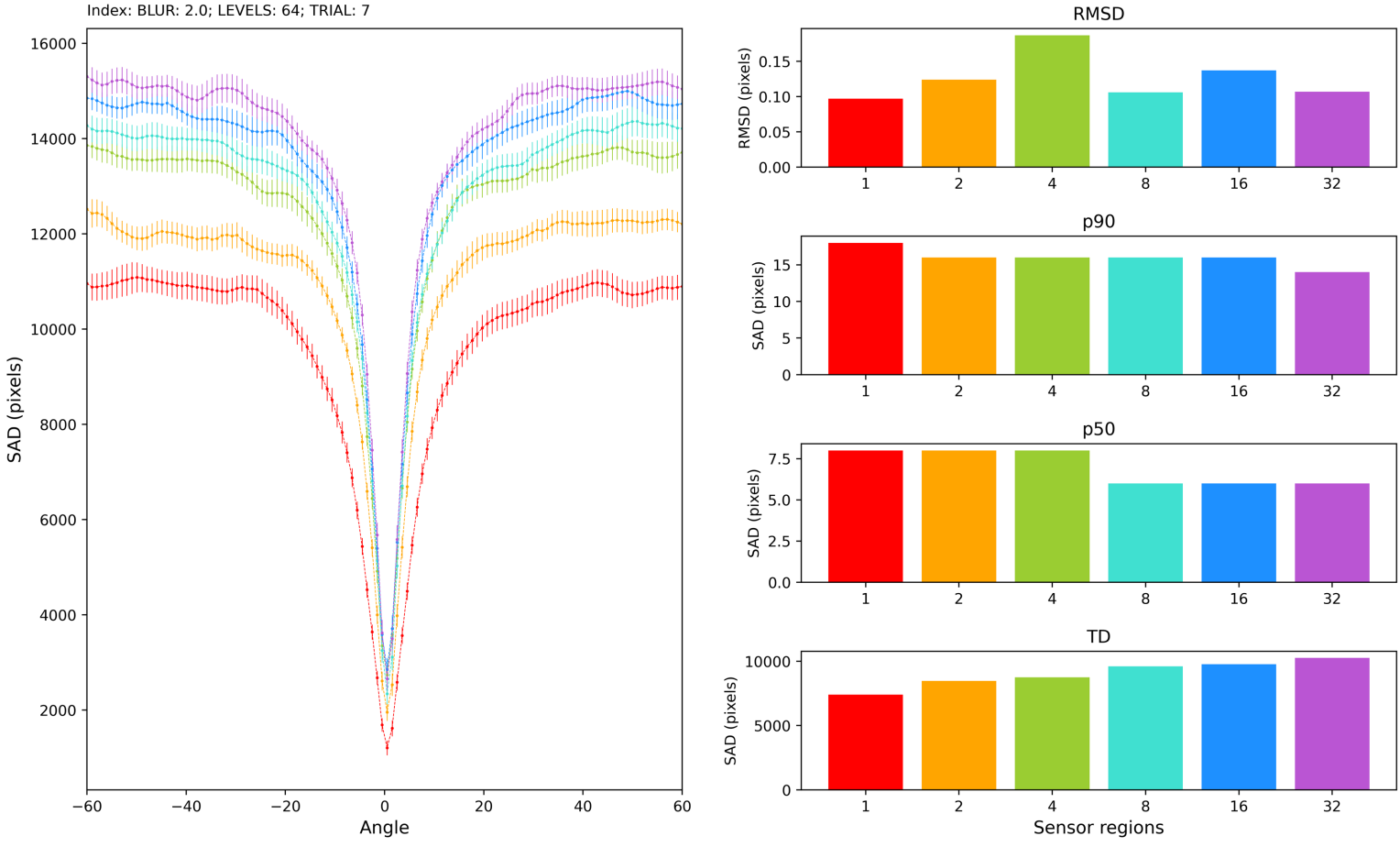
Navigation stats: RMSD error: 48.62; RMSD/dist: 0.122; TD: 9777; p90: 16; p50: 6; complete: 0

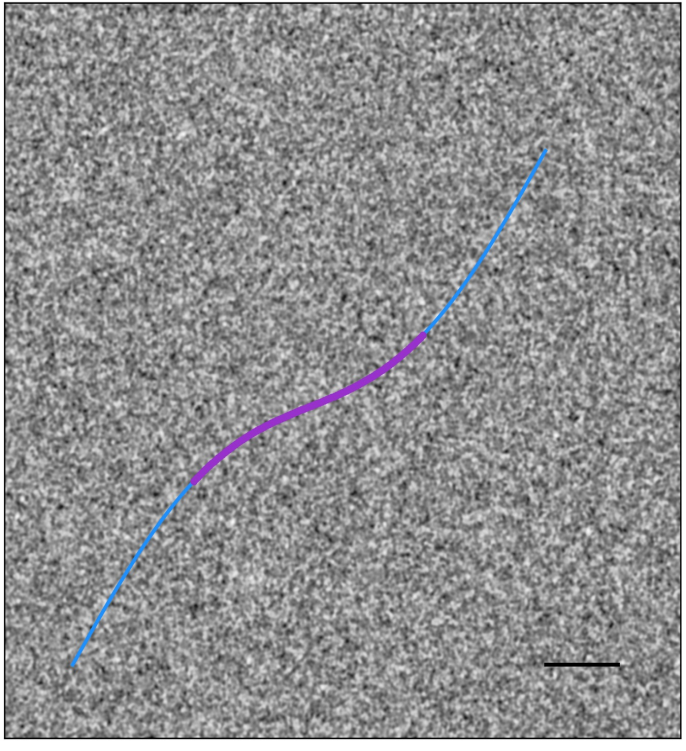


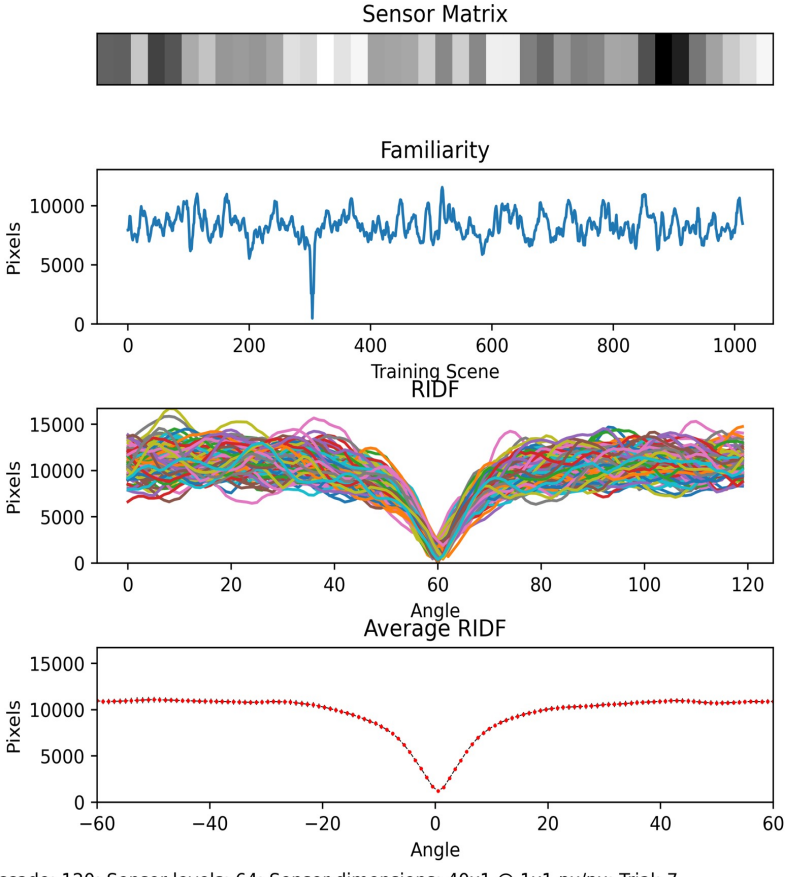


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 36.34; RMSD/dist: 0.091; TD: 10392; p90: 16; p50: 6; complete: 0

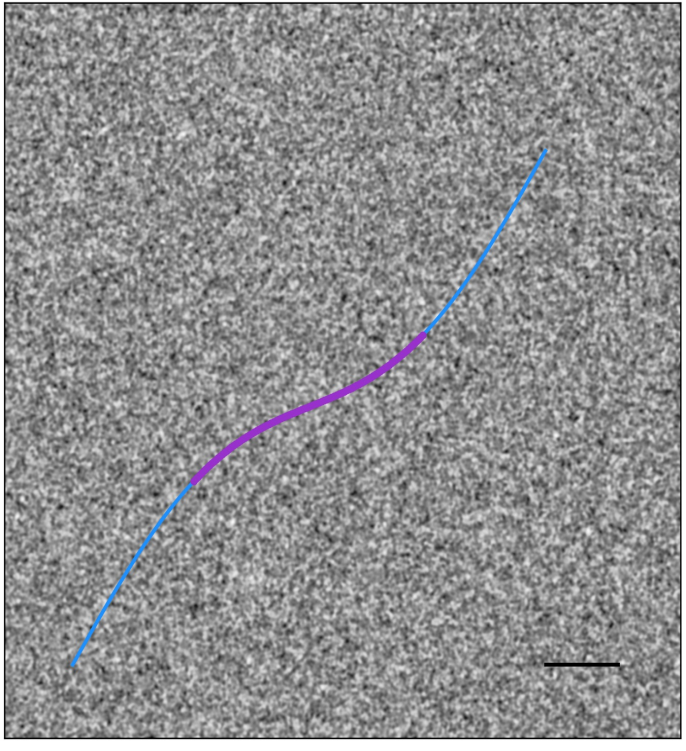

Index: BLUR: 2.0; LEVELS: 64; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

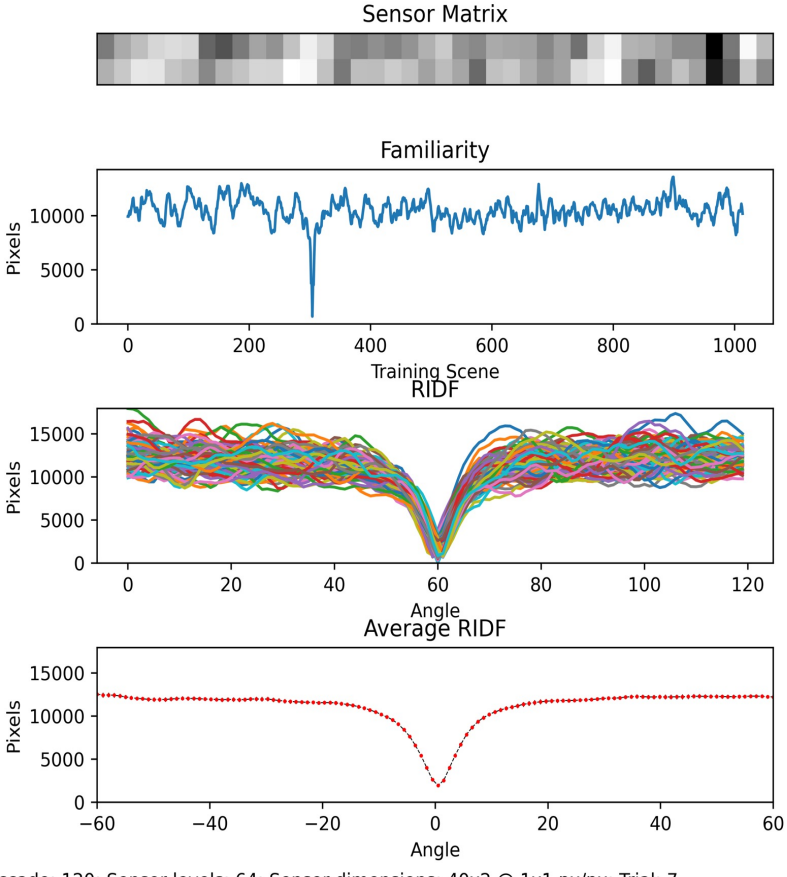




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

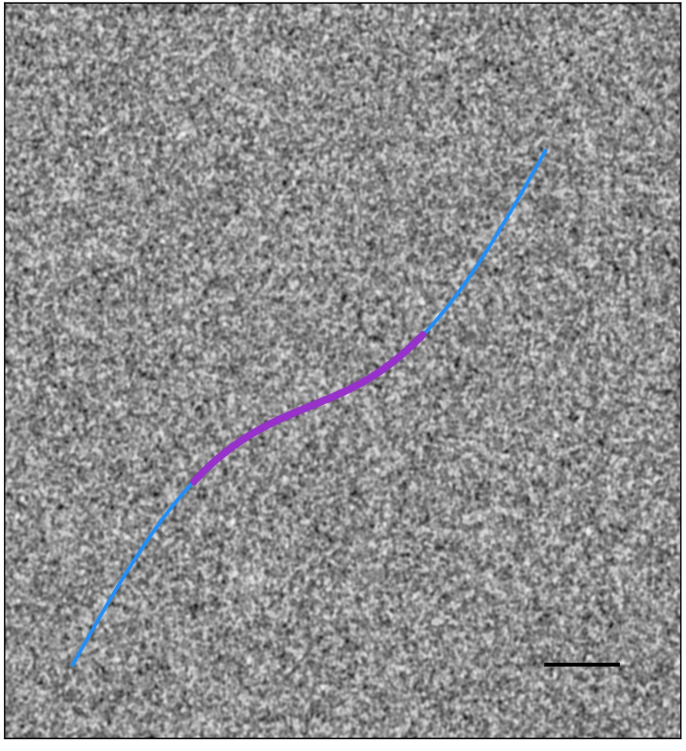
Navigation stats: RMSD error: 38.96; RMSD/dist: 0.097; TD: 7403; p90: 18; p50: 8; complete: 0

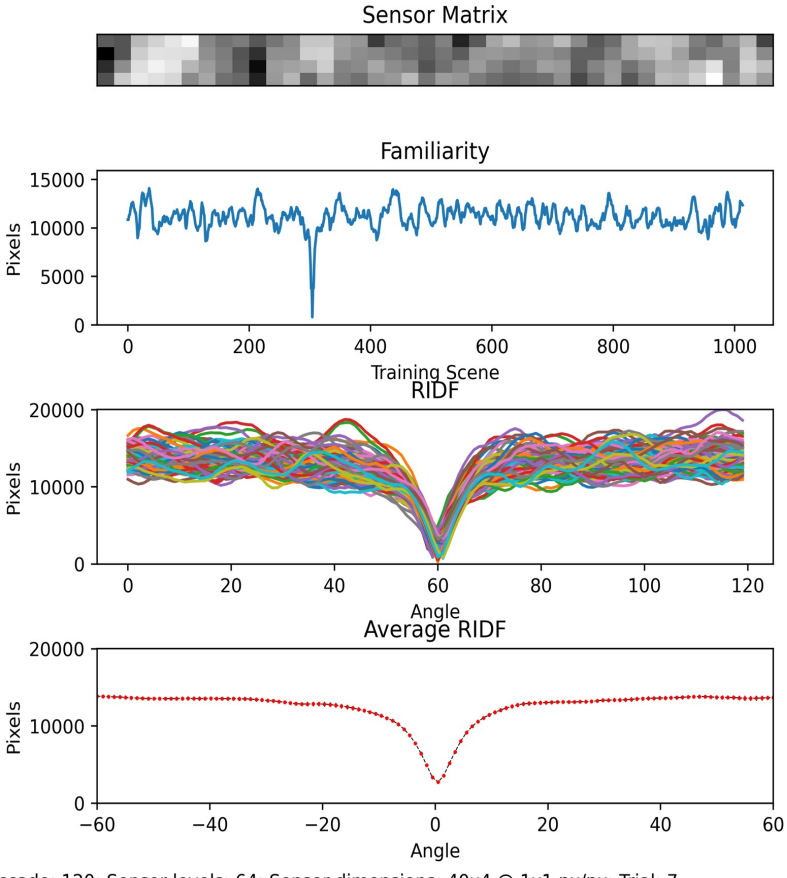




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

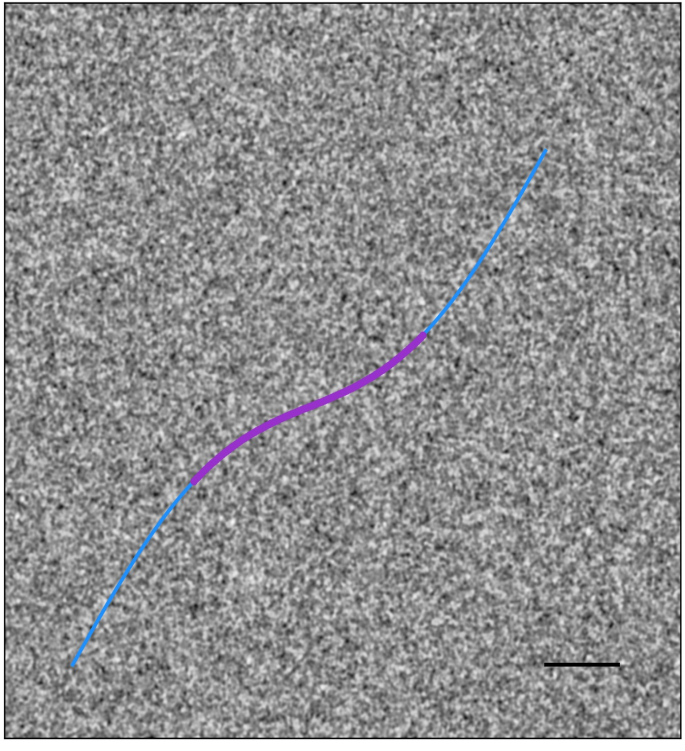
Navigation stats: RMSD error: 49.62; RMSD/dist: 0.124; TD: 8472; p90: 16; p50: 8; complete: 0

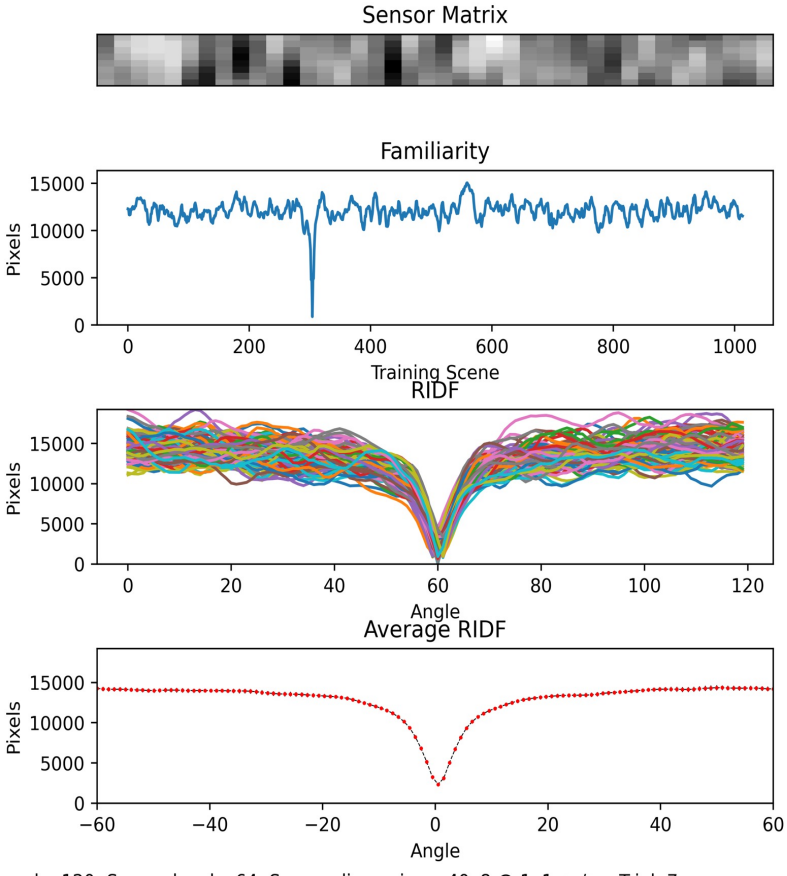




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

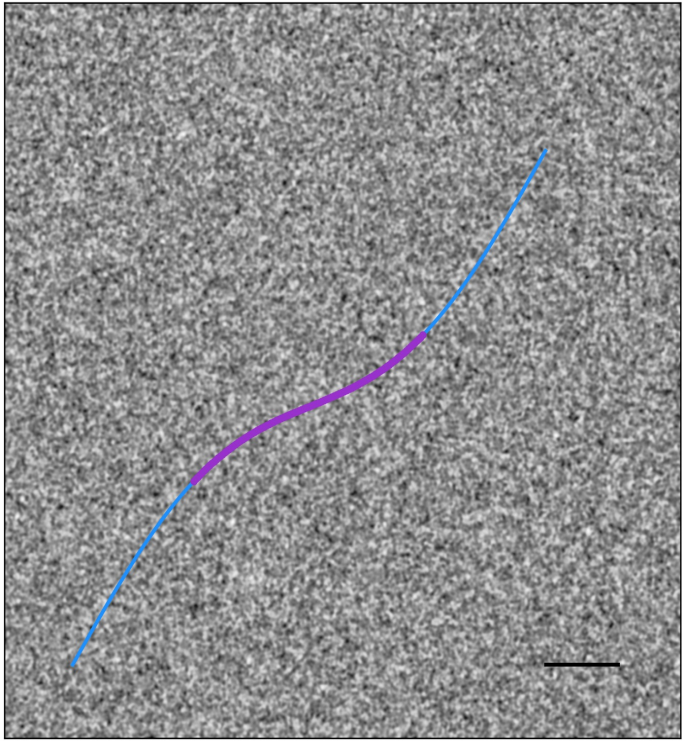
Navigation stats: RMSD error: 74.64; RMSD/dist: 0.187; TD: 8748; p90: 16; p50: 8; complete: 0

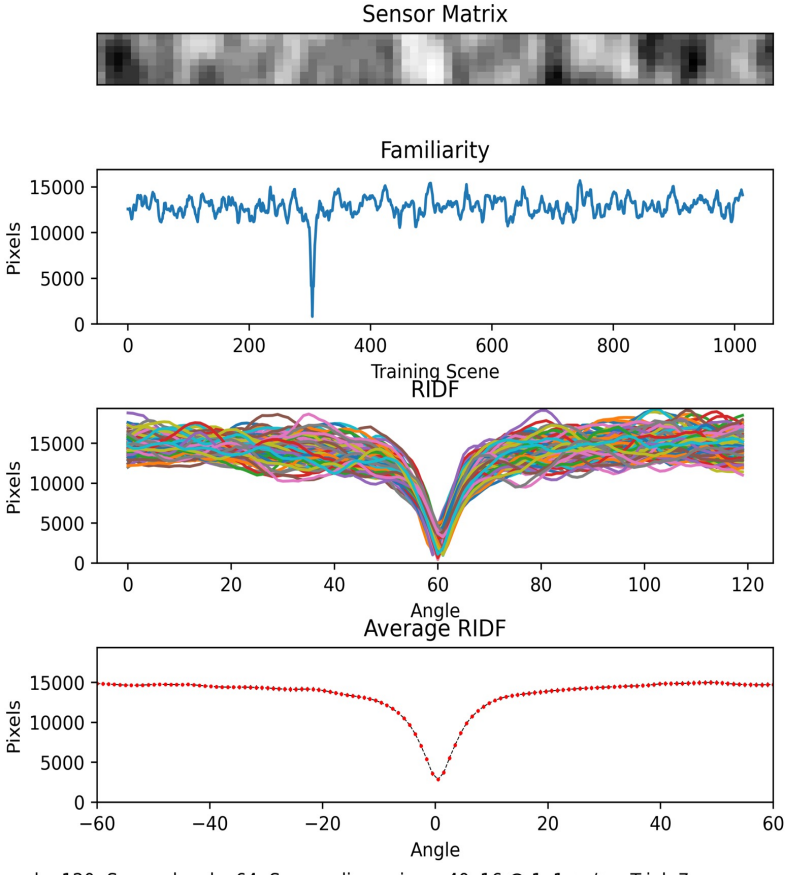




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

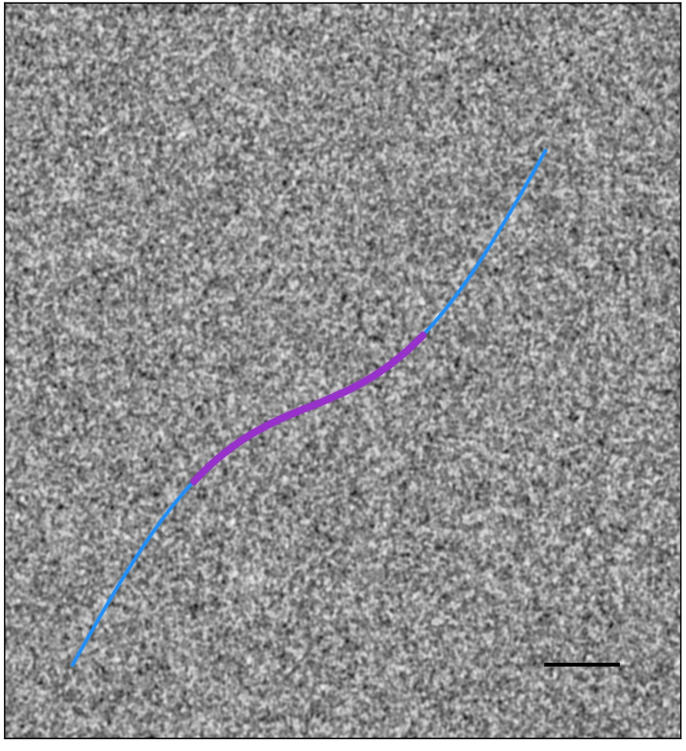
Navigation stats: RMSD error: 42.39; RMSD/dist: 0.106; TD: 9602; p90: 16; p50: 6; complete: 0

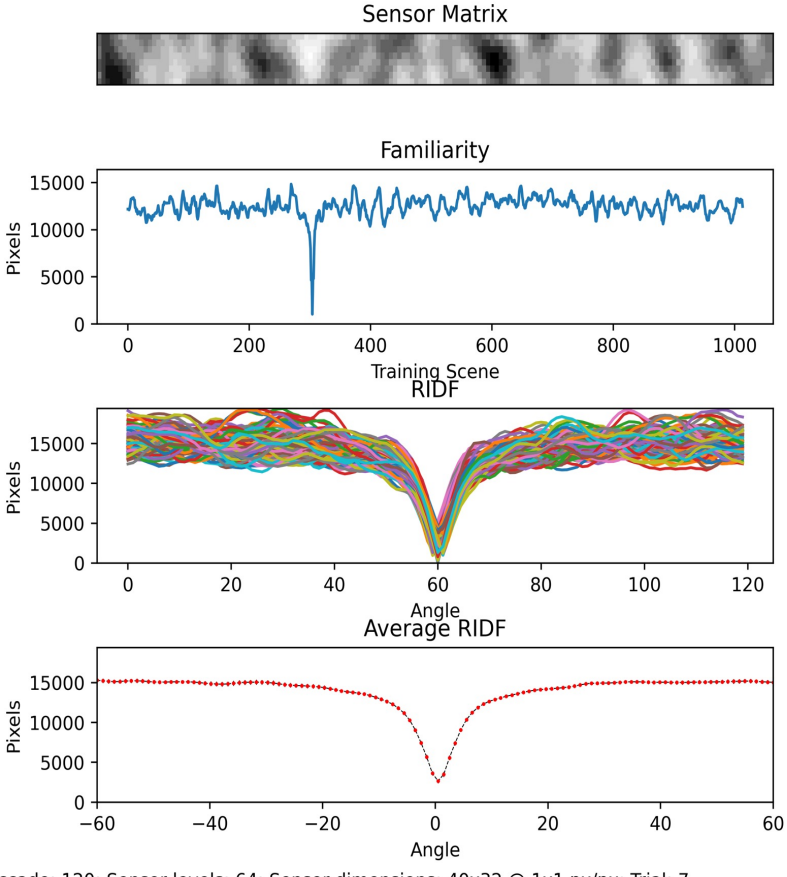




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

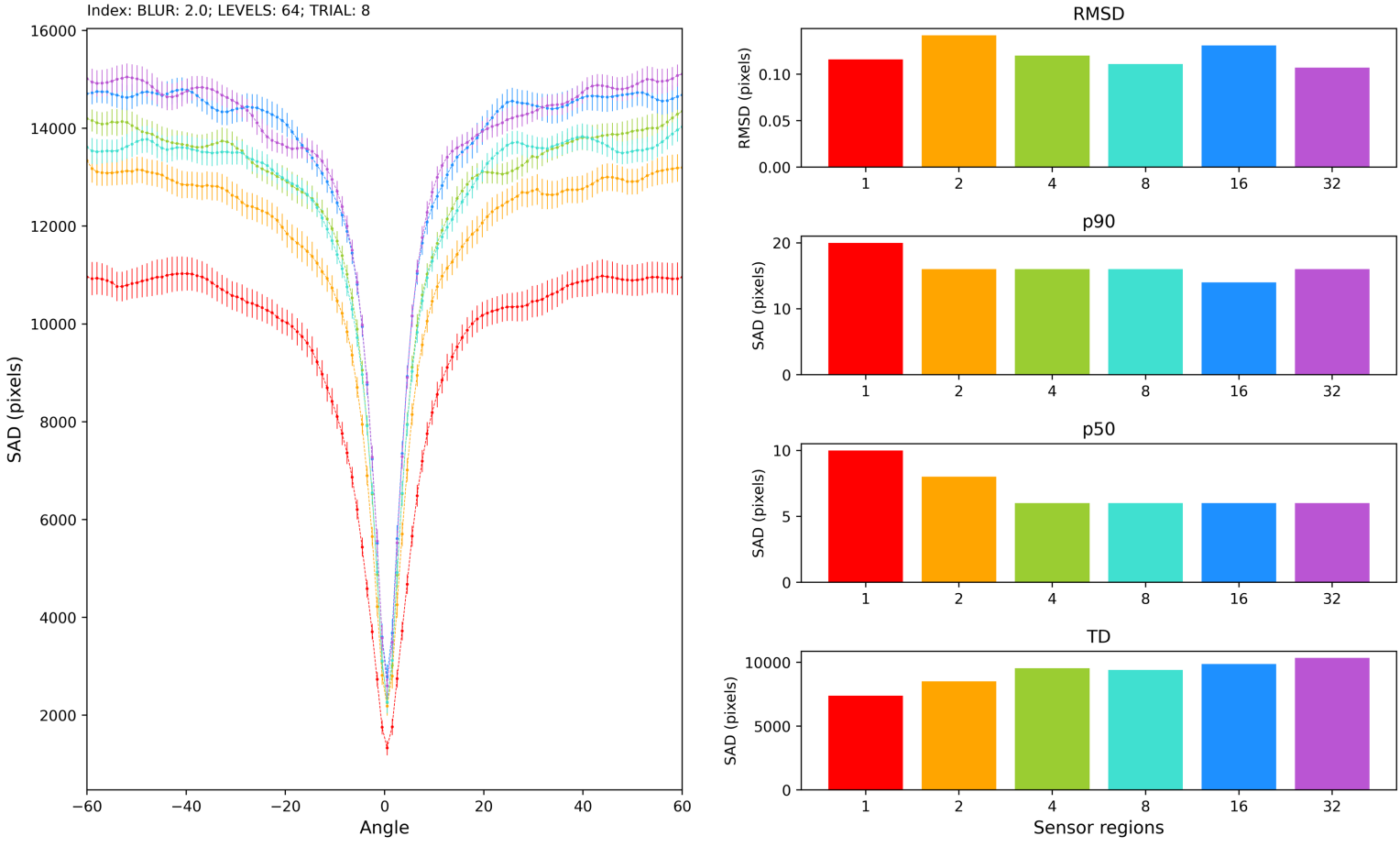
Navigation stats: RMSD error: 54.98; RMSD/dist: 0.137; TD: 9770; p90: 16; p50: 6; complete: 0

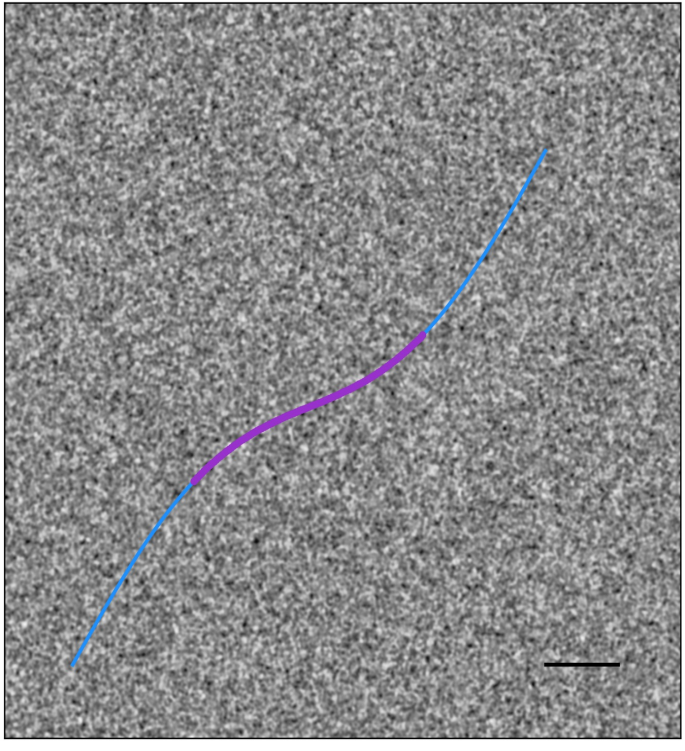


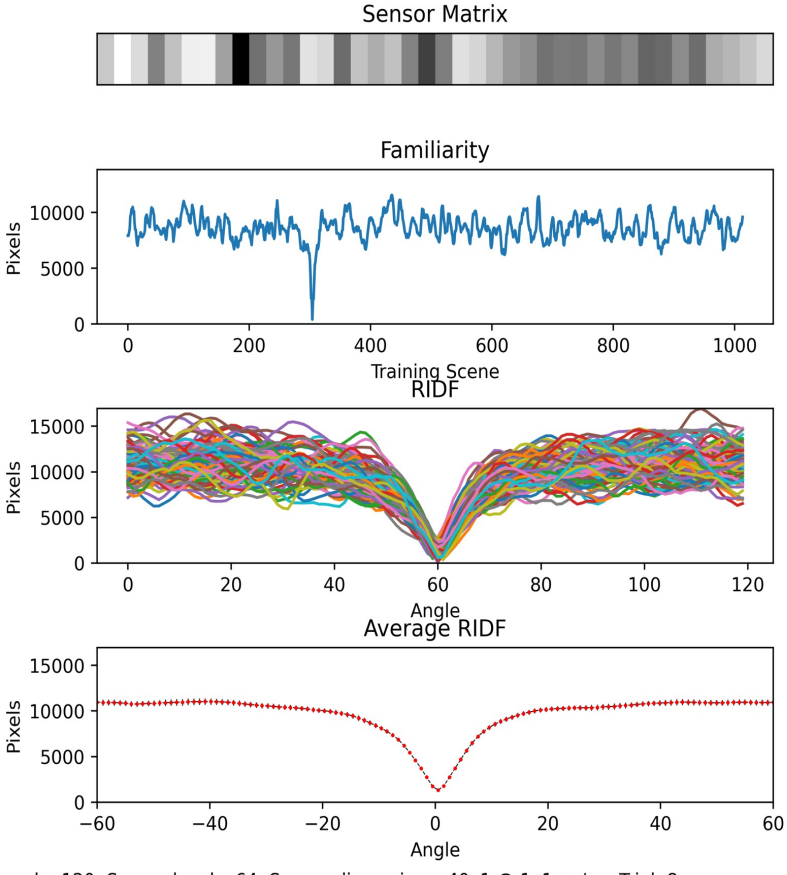


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 42.63; RMSD/dist: 0.107; TD: 10252; p90: 14; p50: 6; complete: 0

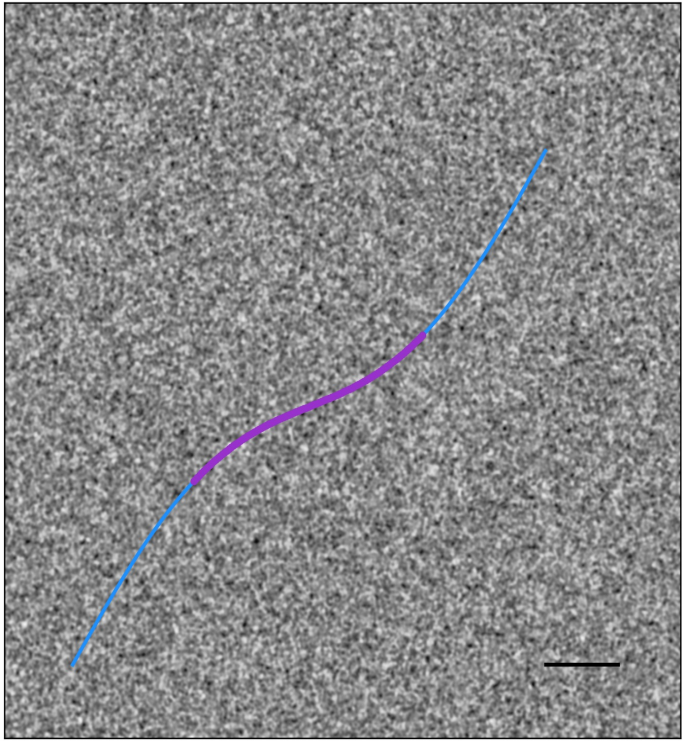

Index: BLUR: 2.0; LEVELS: 64; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

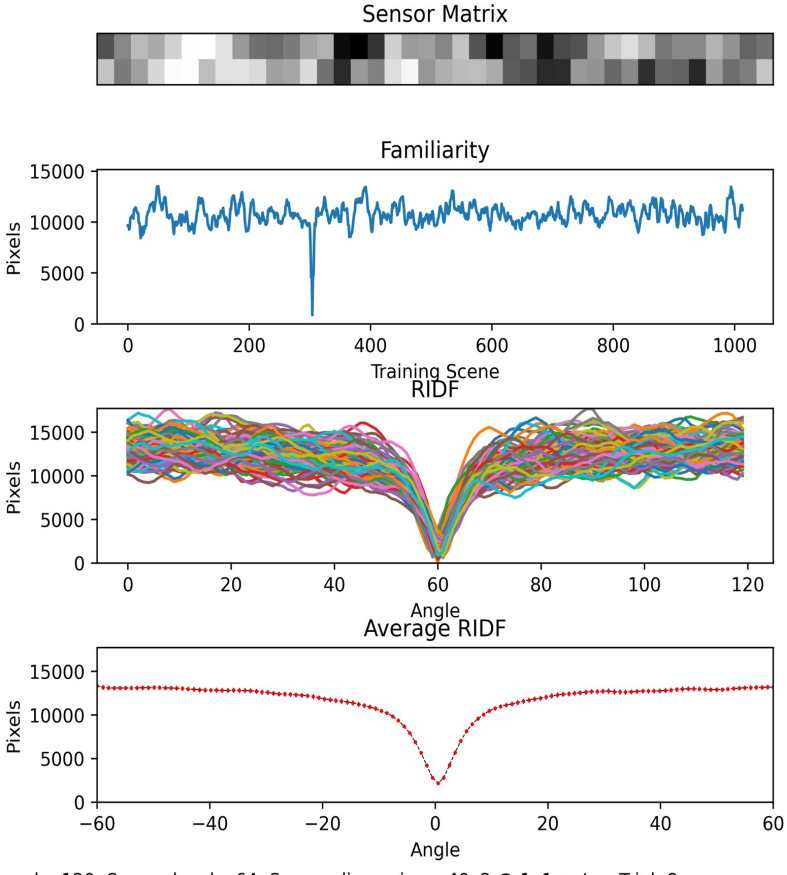




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

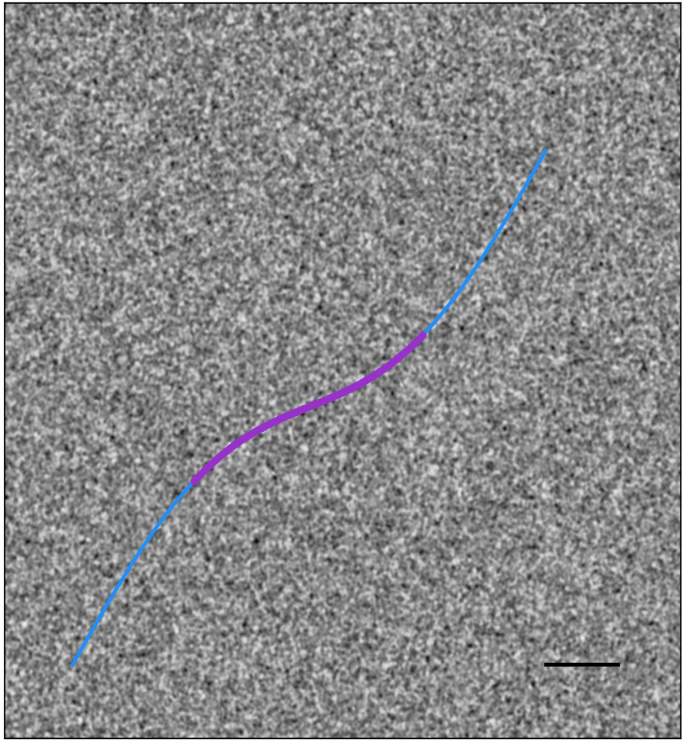
Navigation stats: RMSD error: 46.24; RMSD/dist: 0.116; TD: 7388; p90: 20; p50: 10; complete: 0

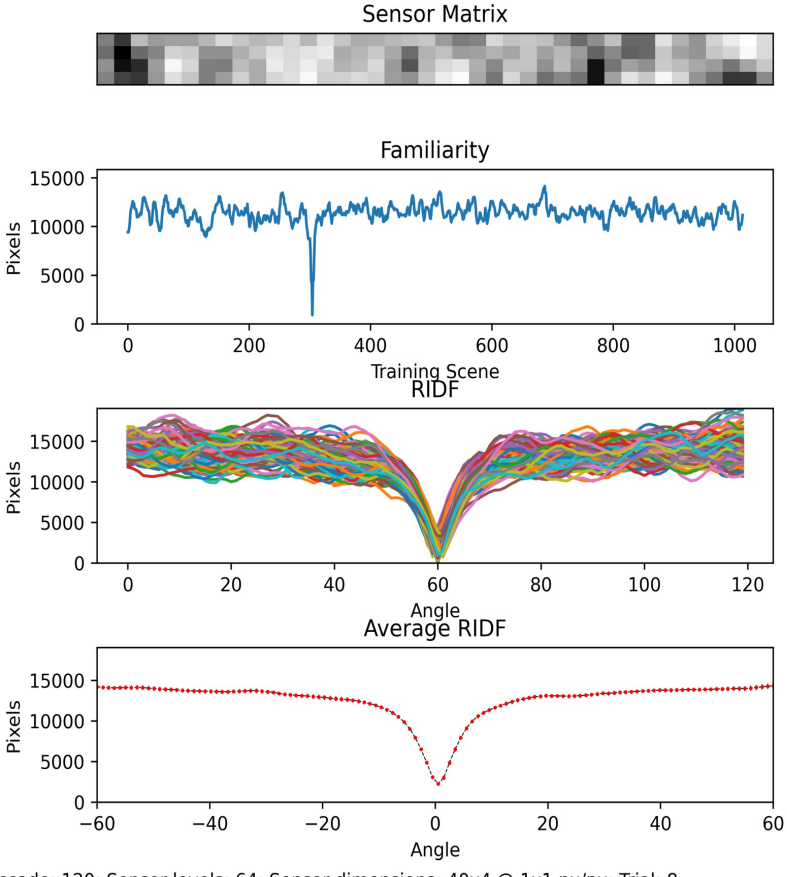




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

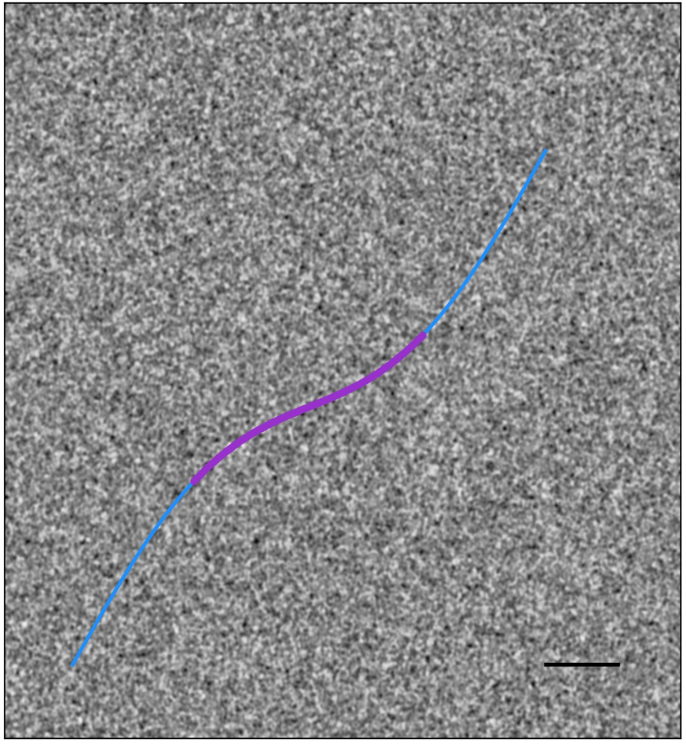
Navigation stats: RMSD error: 56.71; RMSD/dist: 0.142; TD: 8513; p90: 16; p50: 8; complete: 0

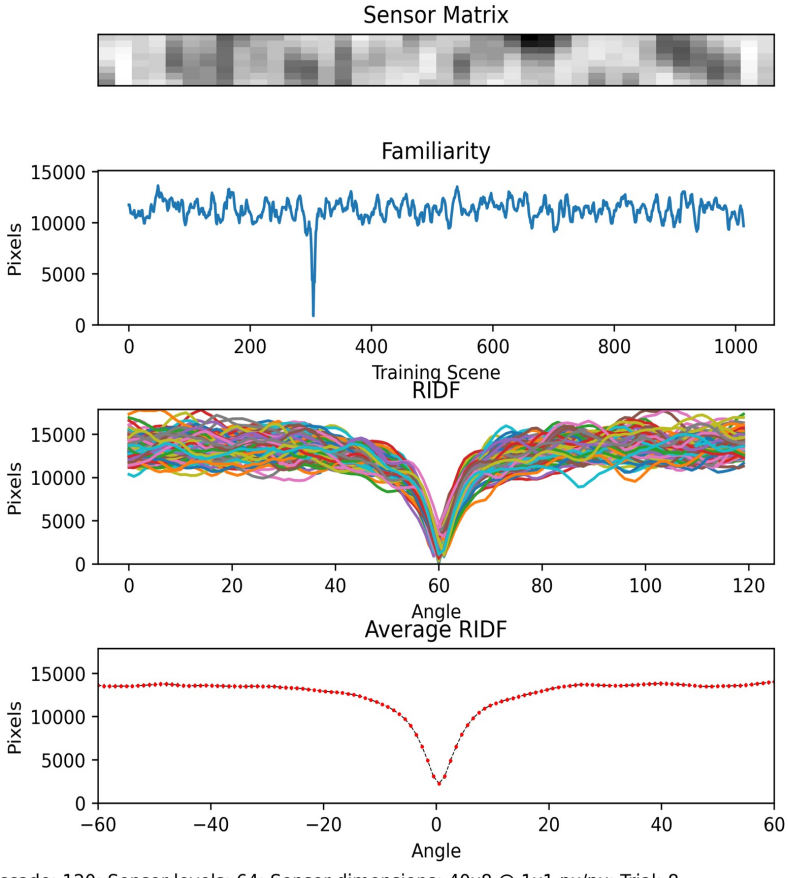




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

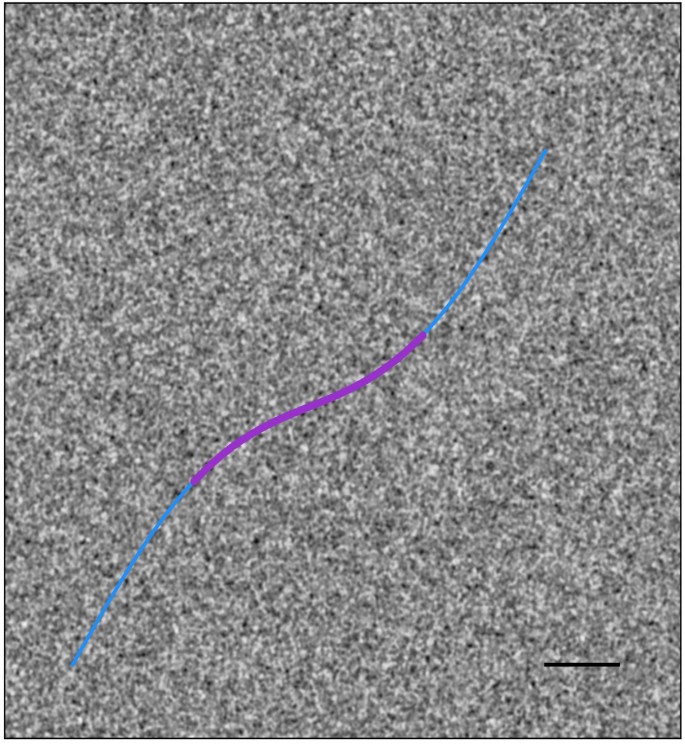
Navigation stats: RMSD error: 48.19; RMSD/dist: 0.120; TD: 9535; p90: 16; p50: 6; complete: 0

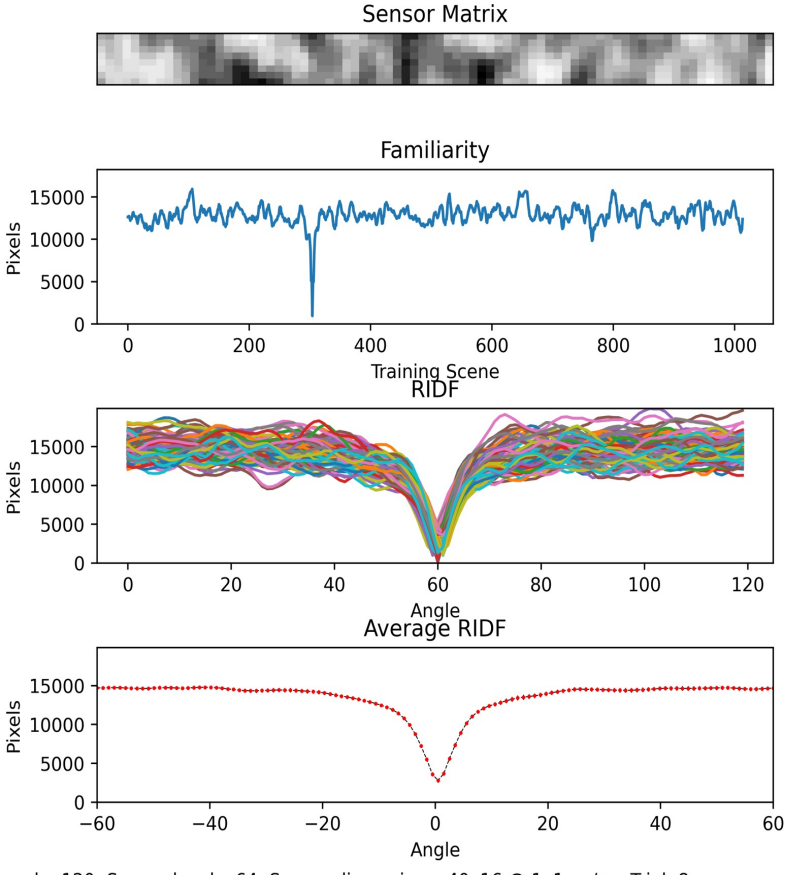




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

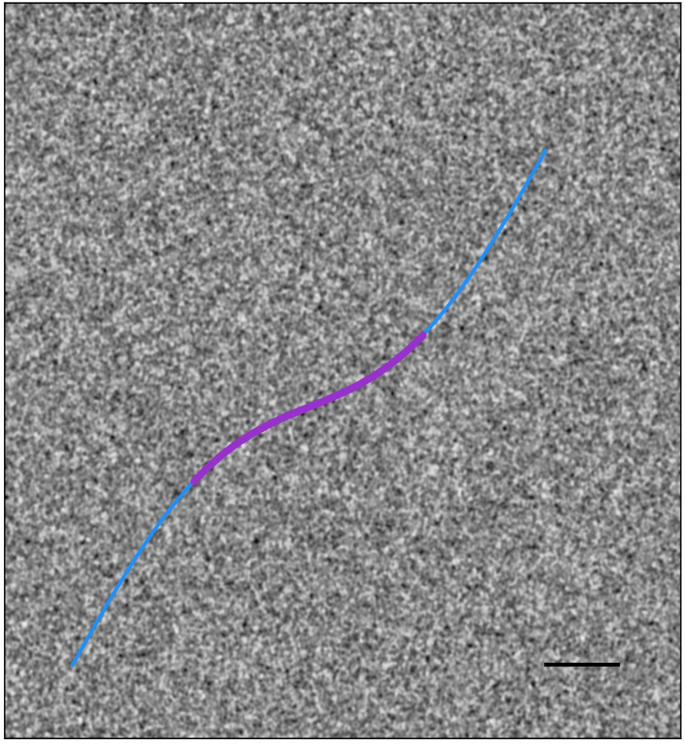
Navigation stats: RMSD error: 44.34; RMSD/dist: 0.111; TD: 9410; p90: 16; p50: 6; complete: 0

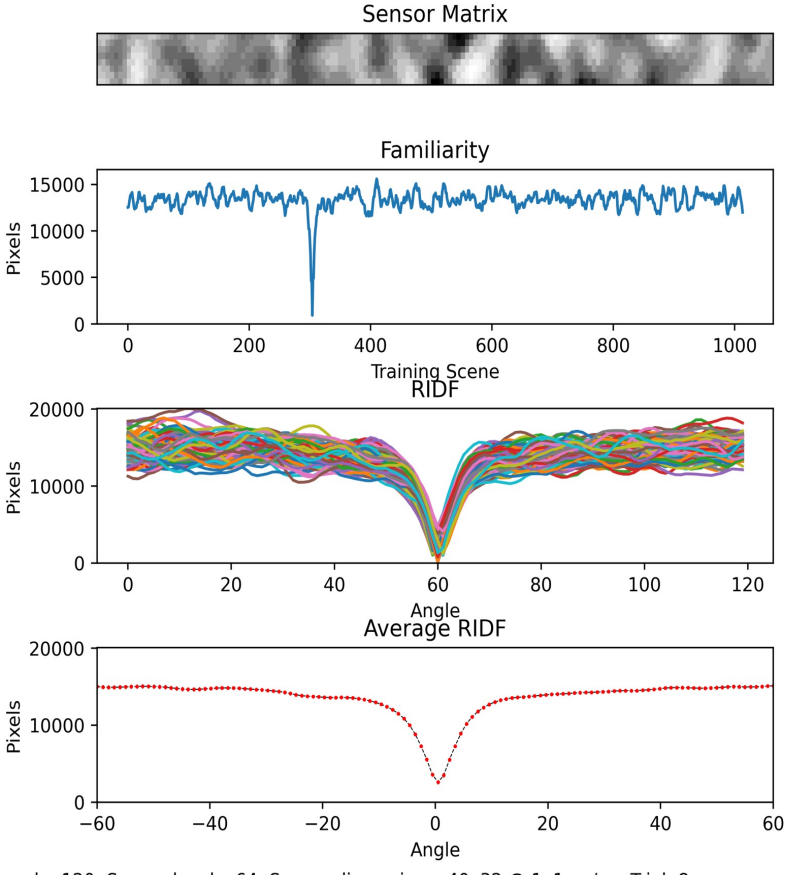




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

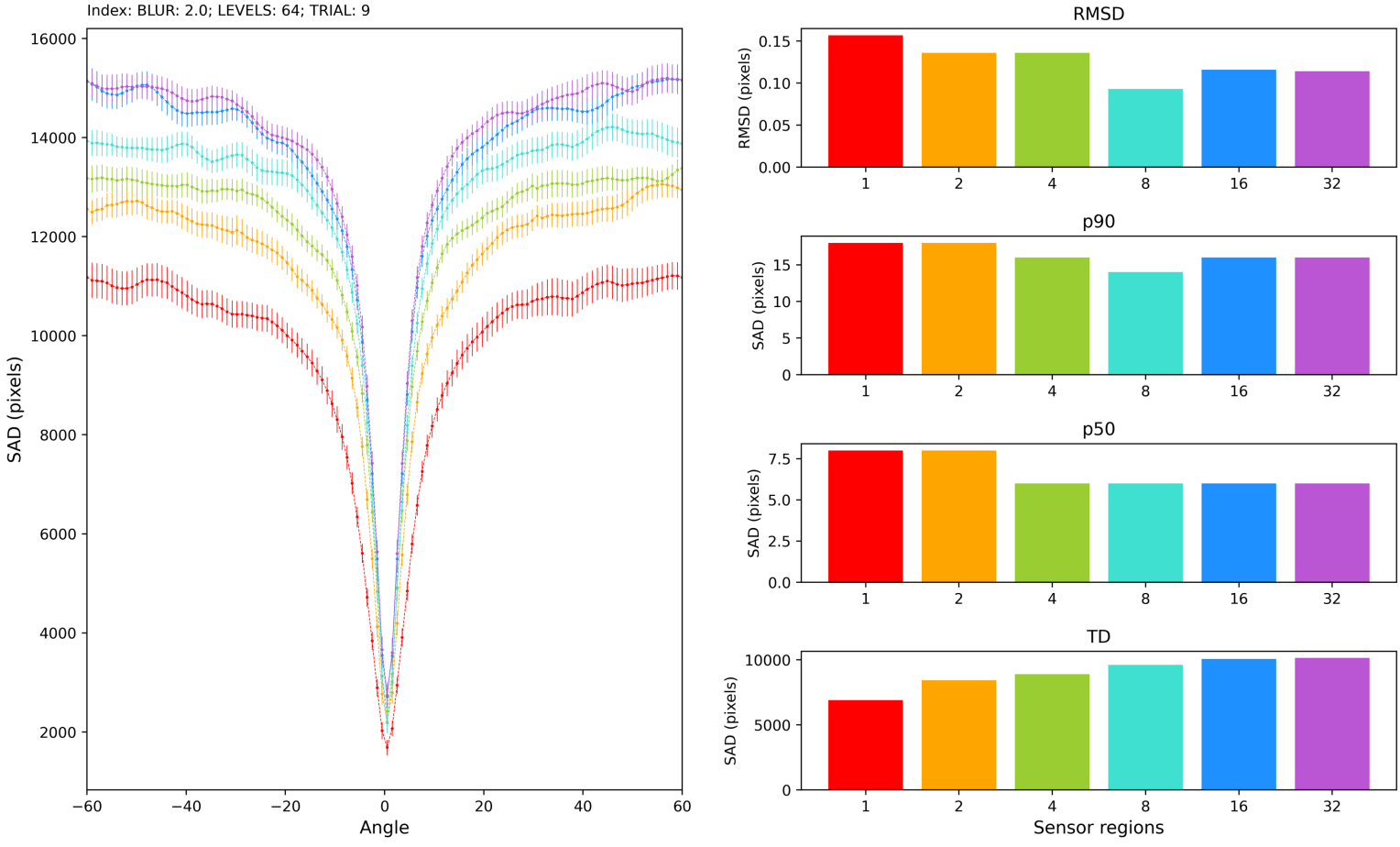
Navigation stats: RMSD error: 52.20; RMSD/dist: 0.131; TD: 9867; p90: 14; p50: 6; complete: 0

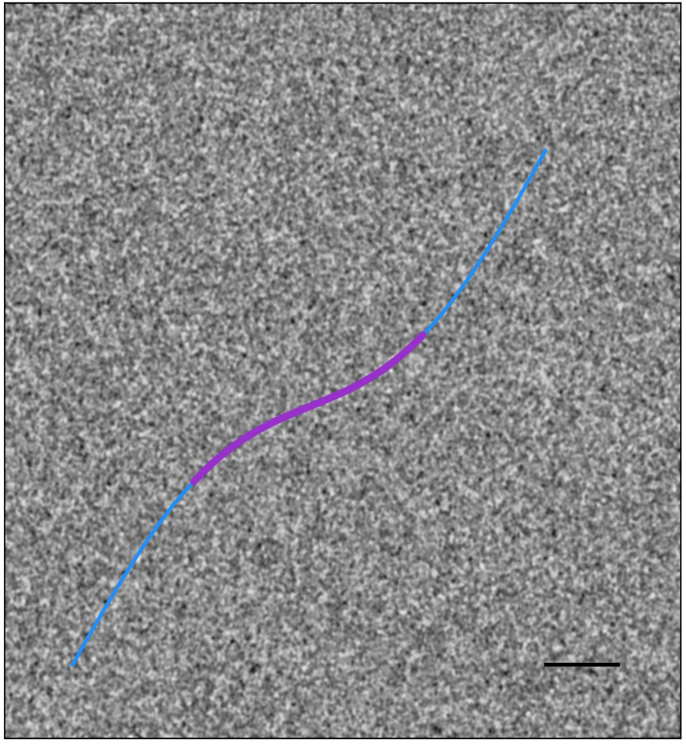


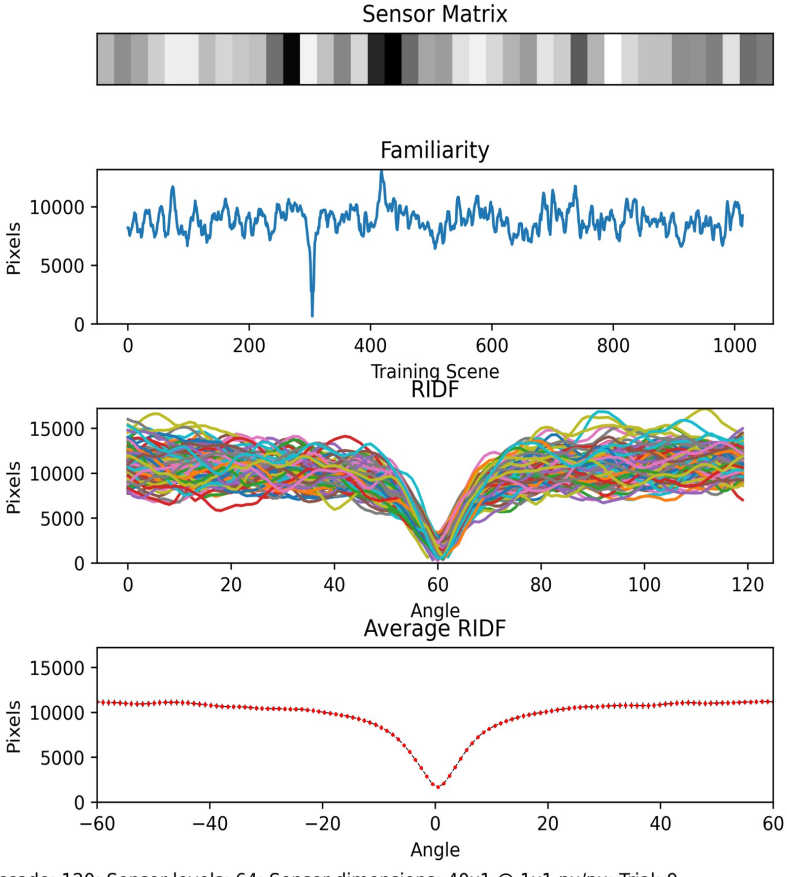


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 42.76; RMSD/dist: 0.107; TD: 10345; p90: 16; p50: 6; complete: 0

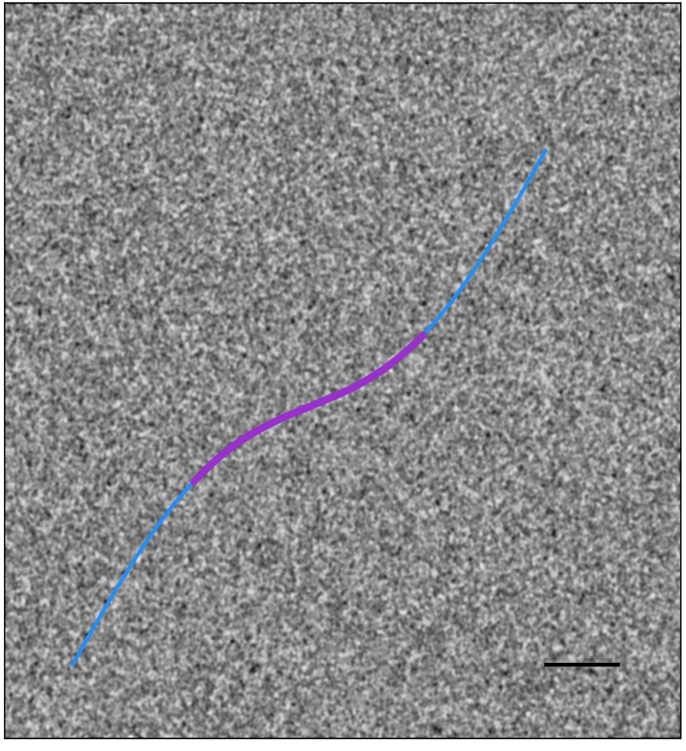

Index: BLUR: 2.0; LEVELS: 64; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

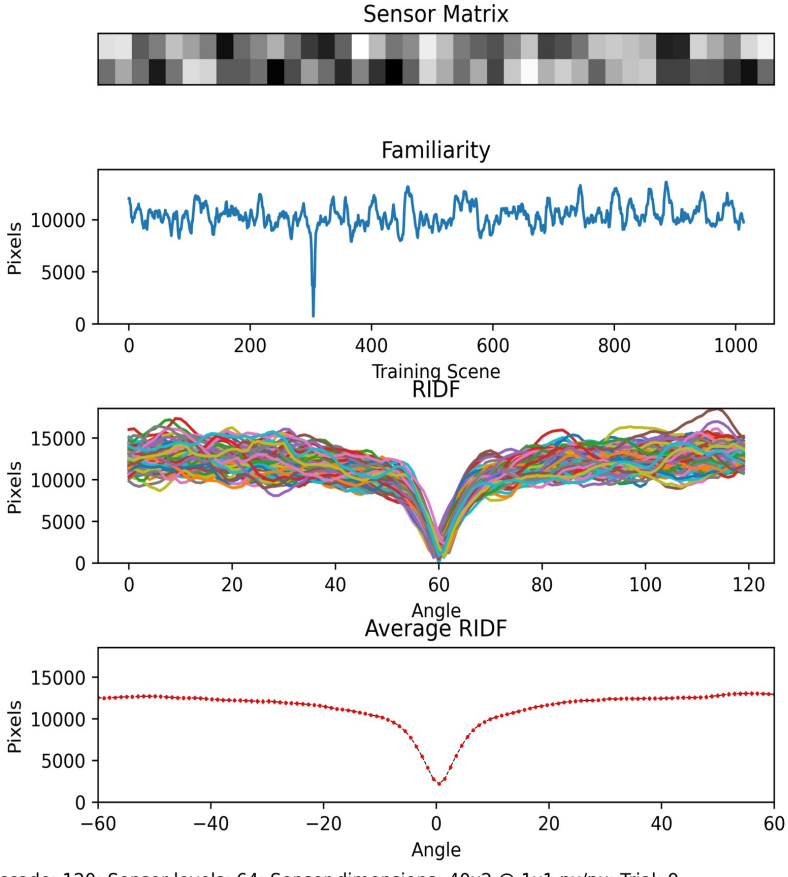




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

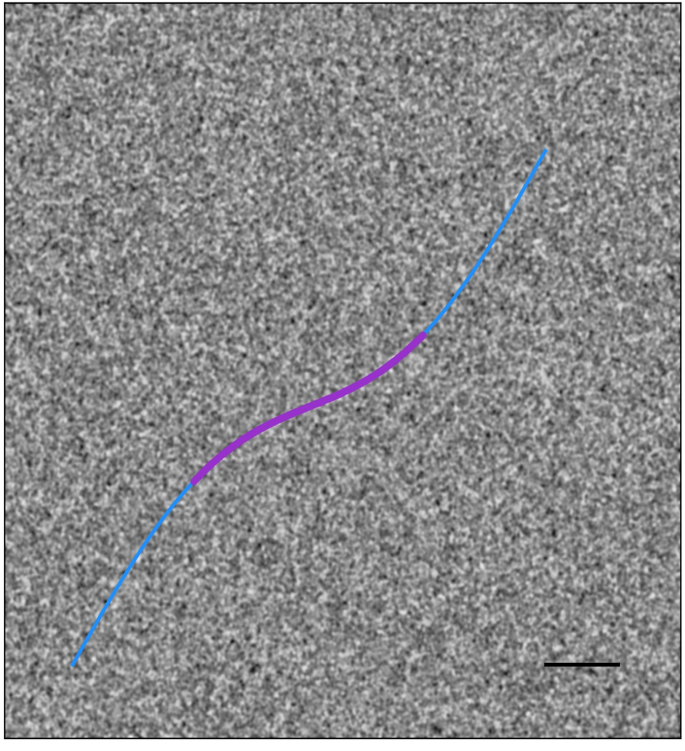
Navigation stats: RMSD error: 62.99; RMSD/dist: 0.157; TD: 6901; p90: 18; p50: 8; complete: 0

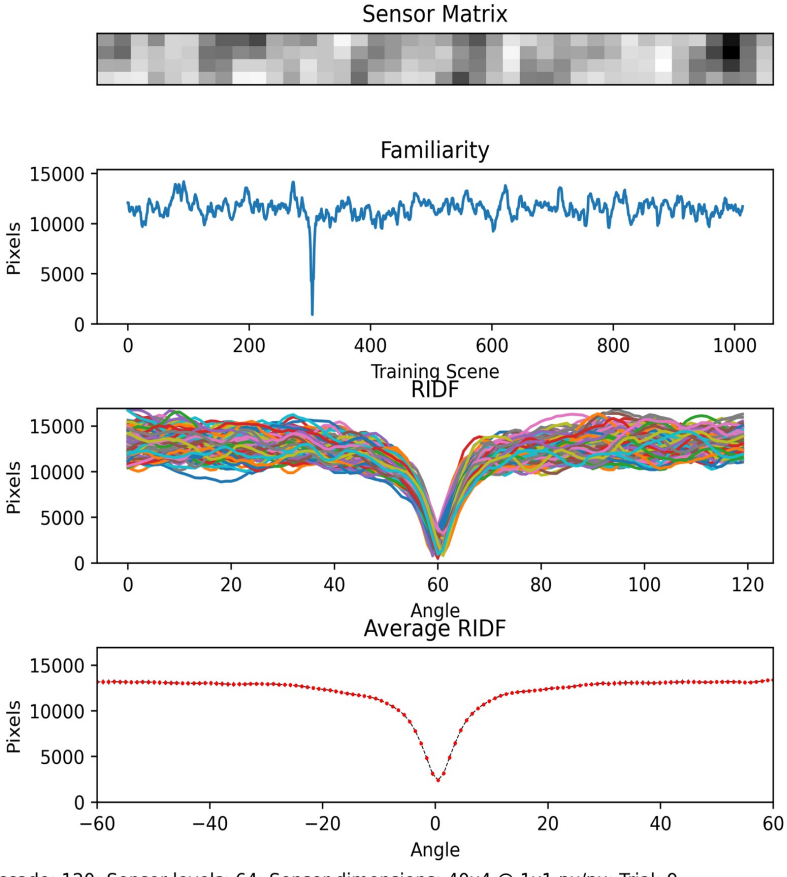




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

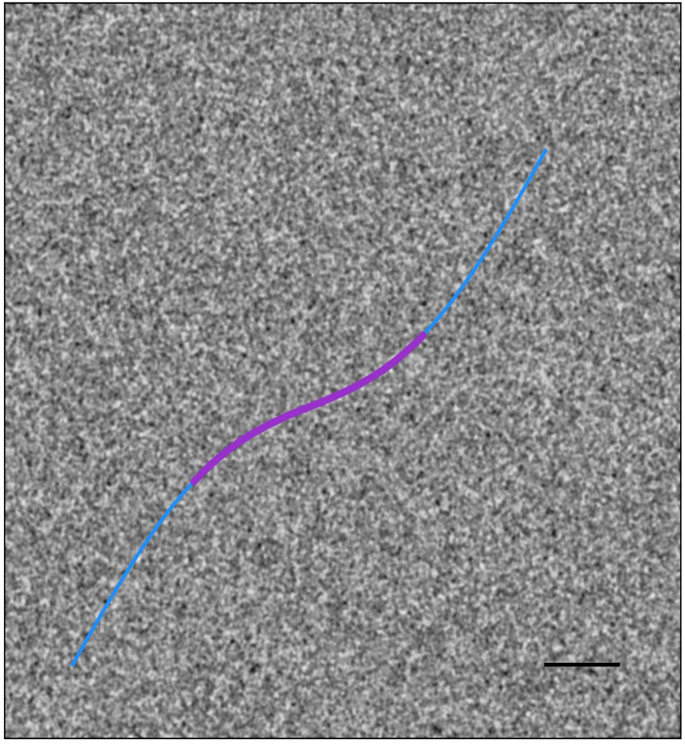
Navigation stats: RMSD error: 54.56; RMSD/dist: 0.136; TD: 8426; p90: 18; p50: 8; complete: 0

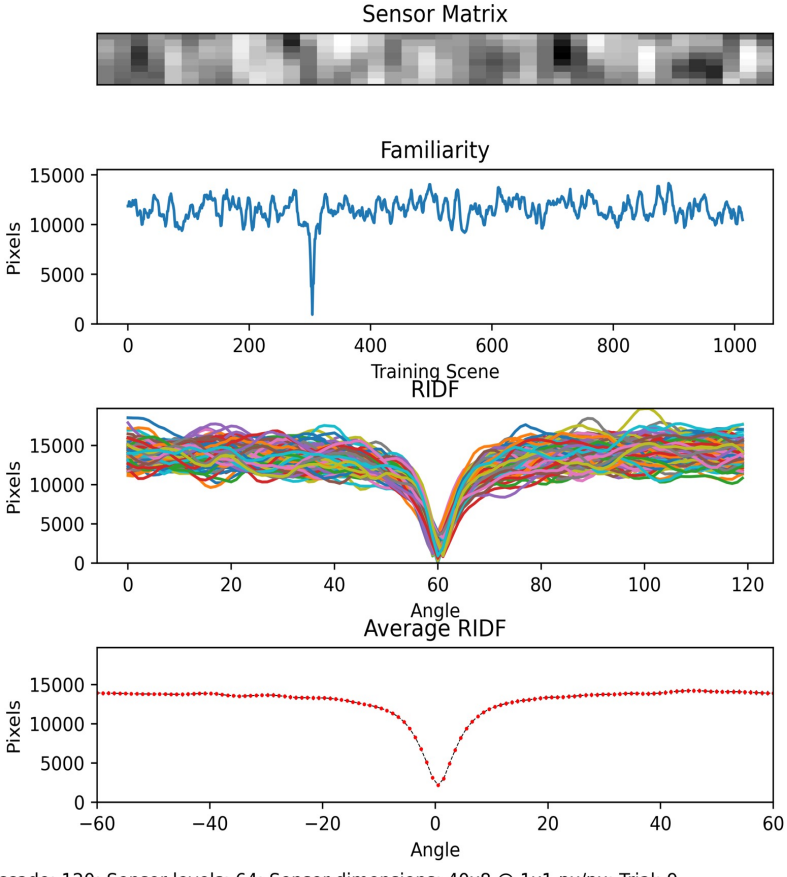




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

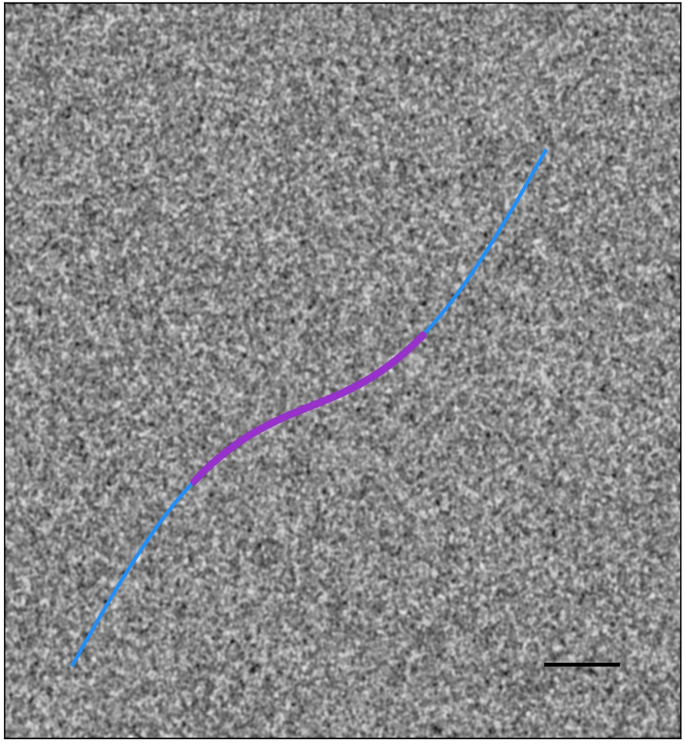
Navigation stats: RMSD error: 54.52; RMSD/dist: 0.136; TD: 8900; p90: 16; p50: 6; complete: 0

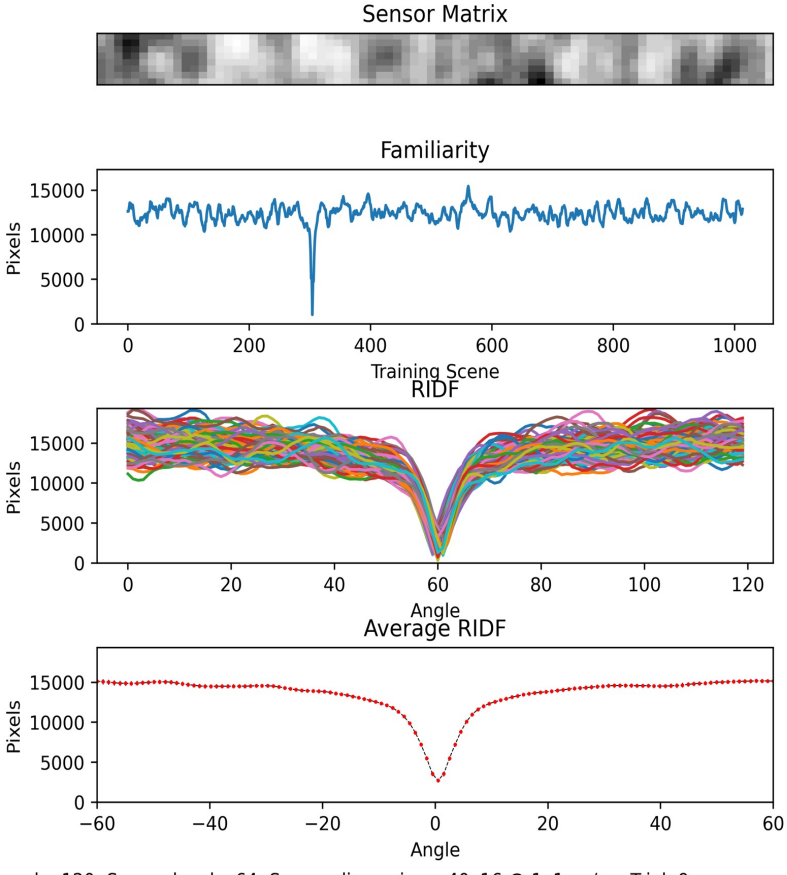




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

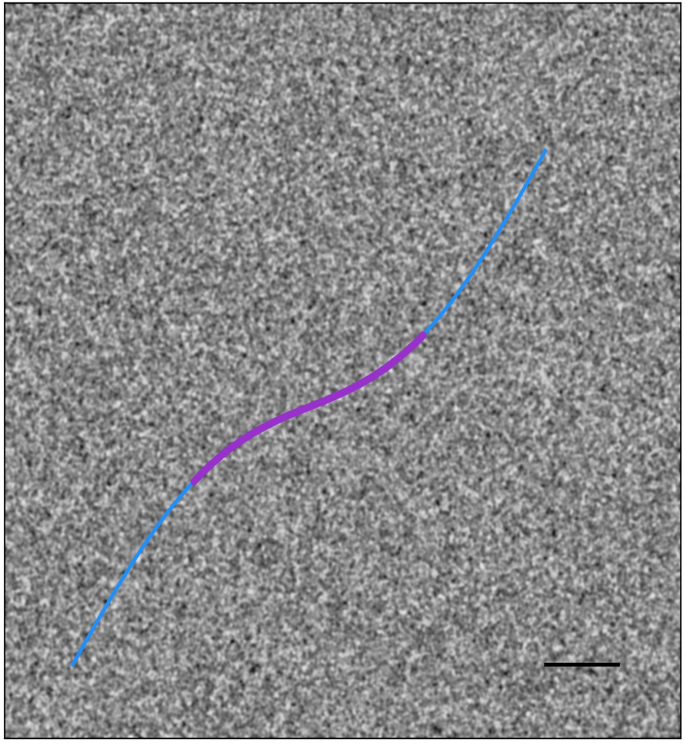
Navigation stats: RMSD error: 37.24; RMSD/dist: 0.093; TD: 9624; p90: 14; p50: 6; complete: 0

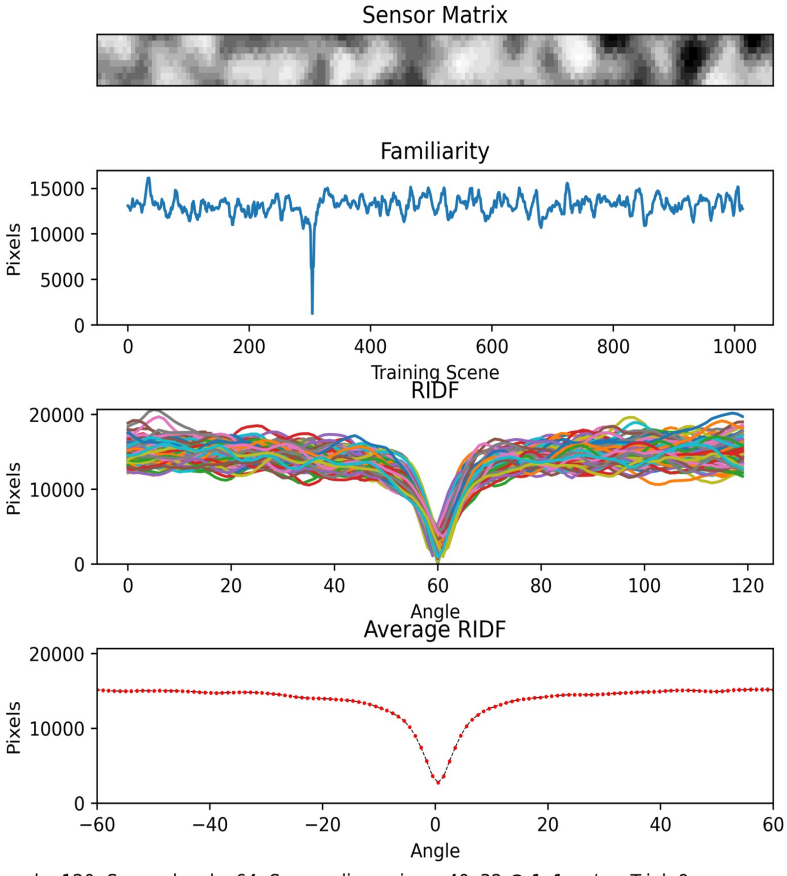




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

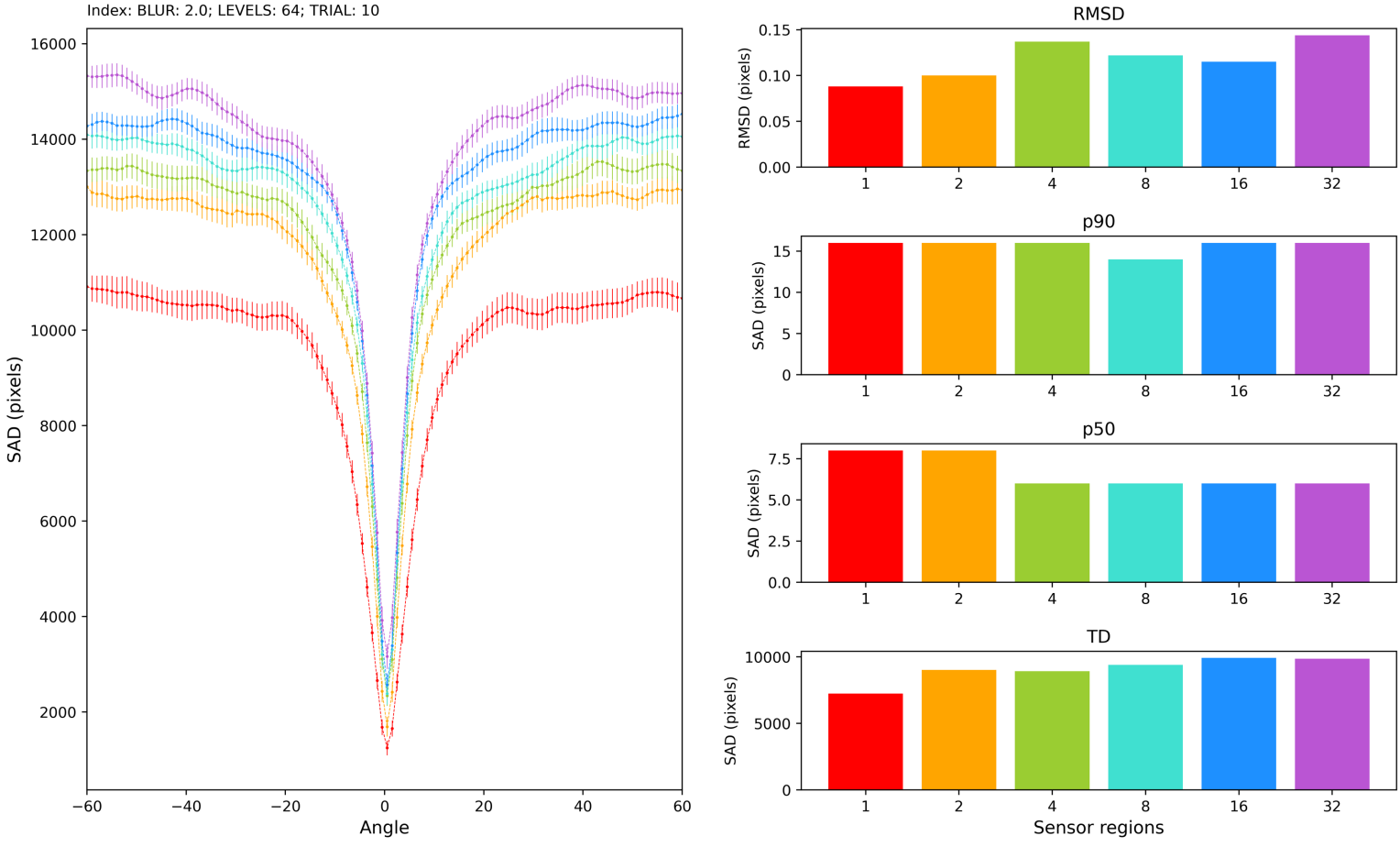
Navigation stats: RMSD error: 46.42; RMSD/dist: 0.116; TD: 10071; p90: 16; p50: 6; complete: 0

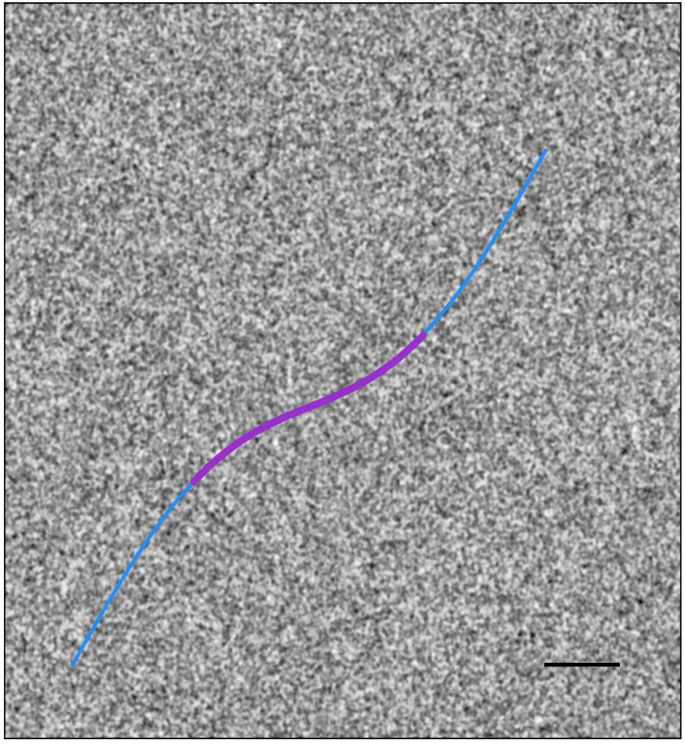


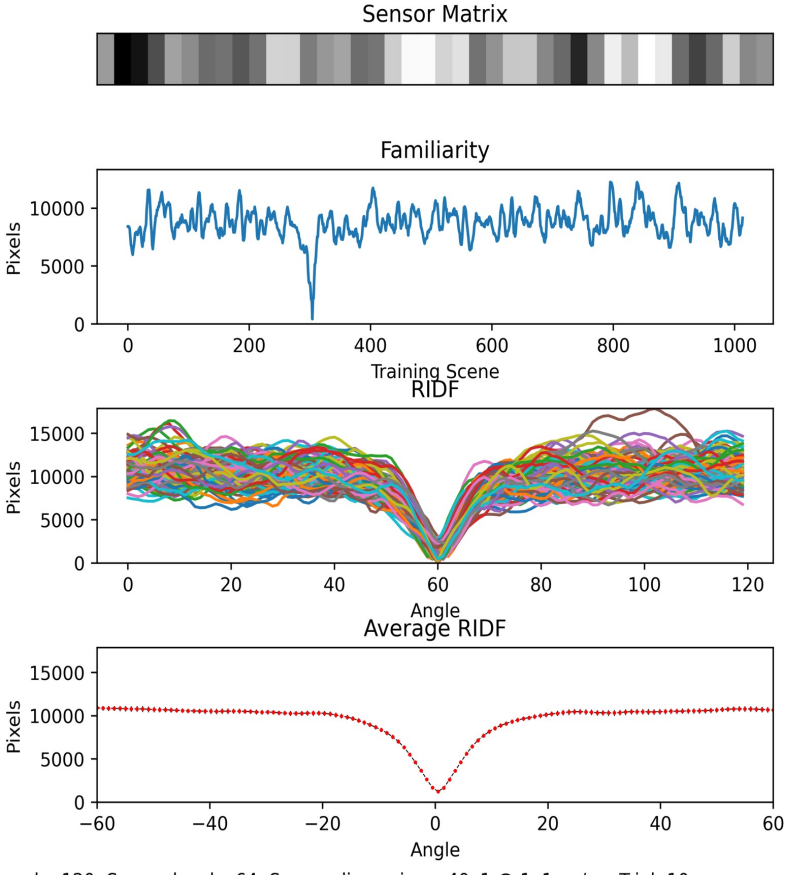


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 45.52; RMSD/dist: 0.114; TD: 10145; p90: 16; p50: 6; complete: 0

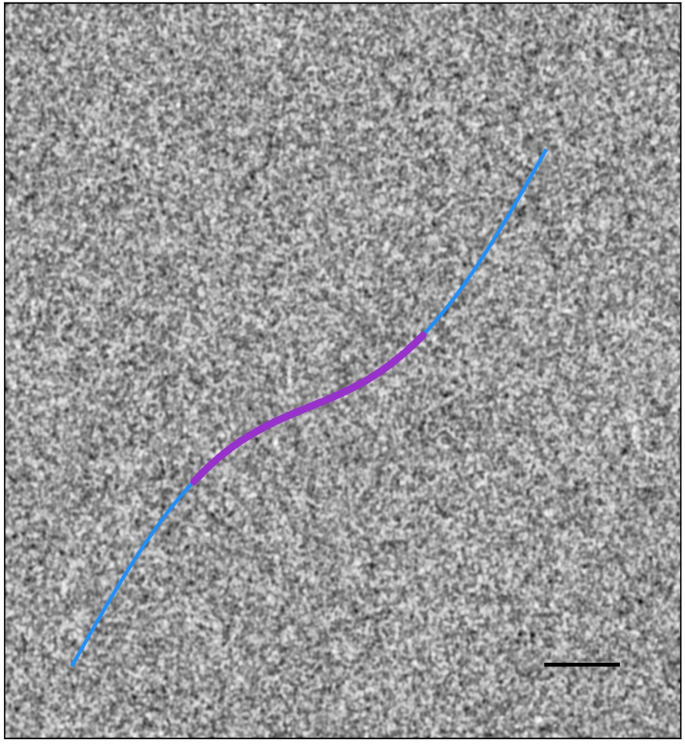

Index: BLUR: 2.0; LEVELS: 64; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

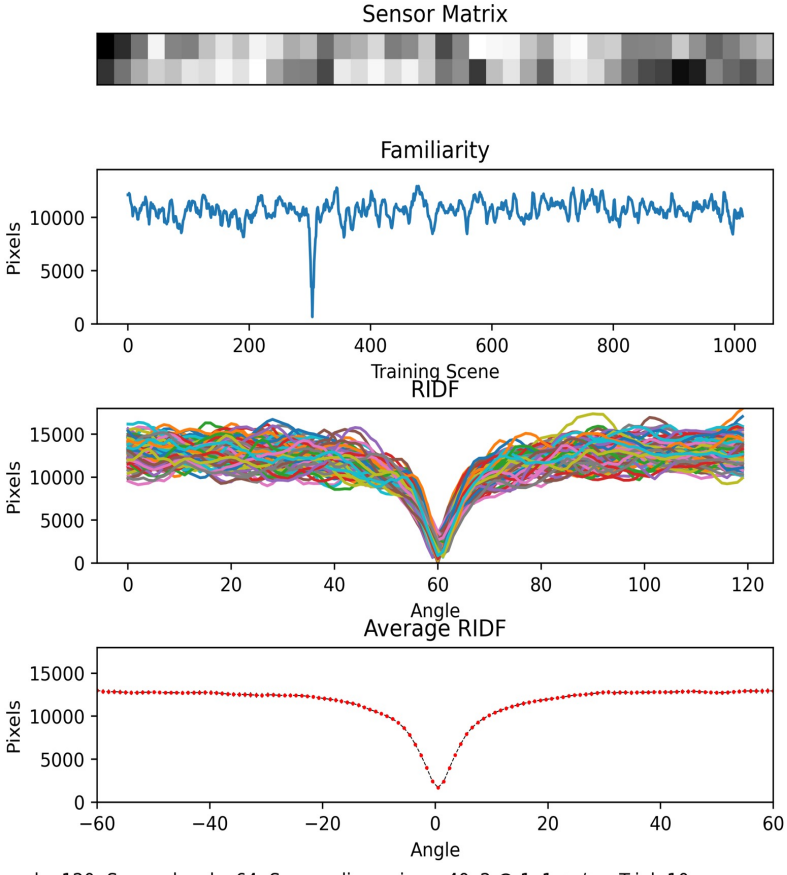




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

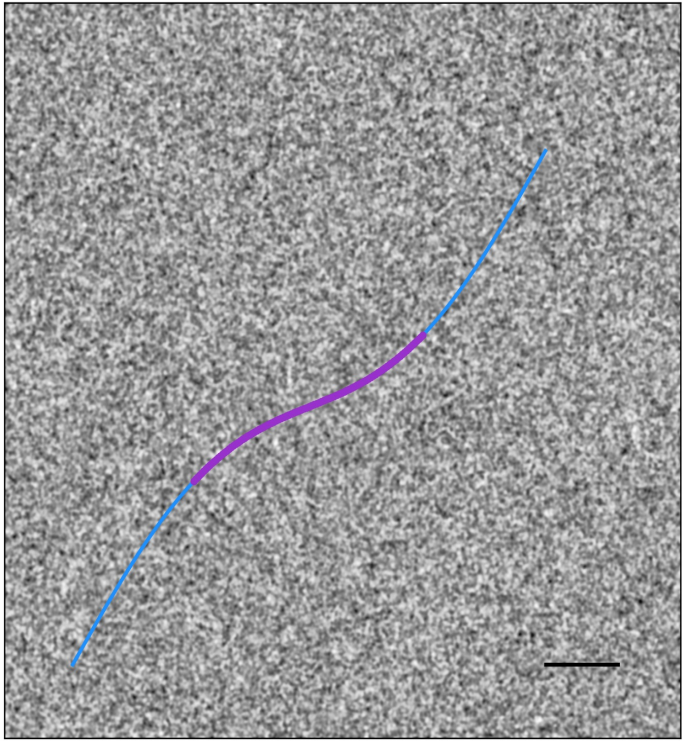
Navigation stats: RMSD error: 35.31; RMSD/dist: 0.088; TD: 7246; p90: 16; p50: 8; complete: 0

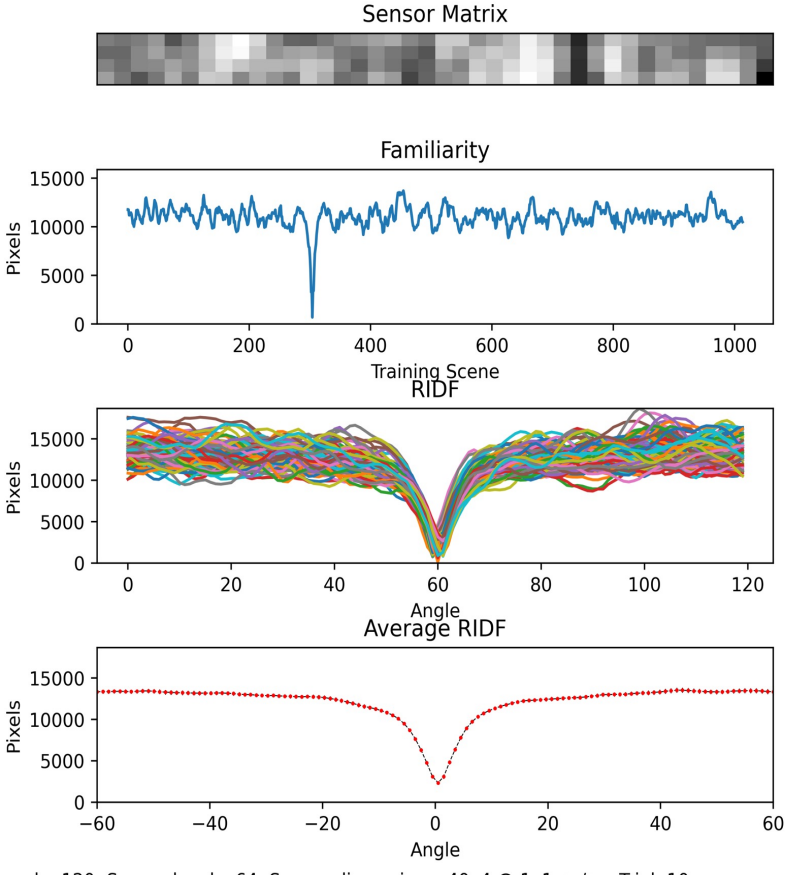




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

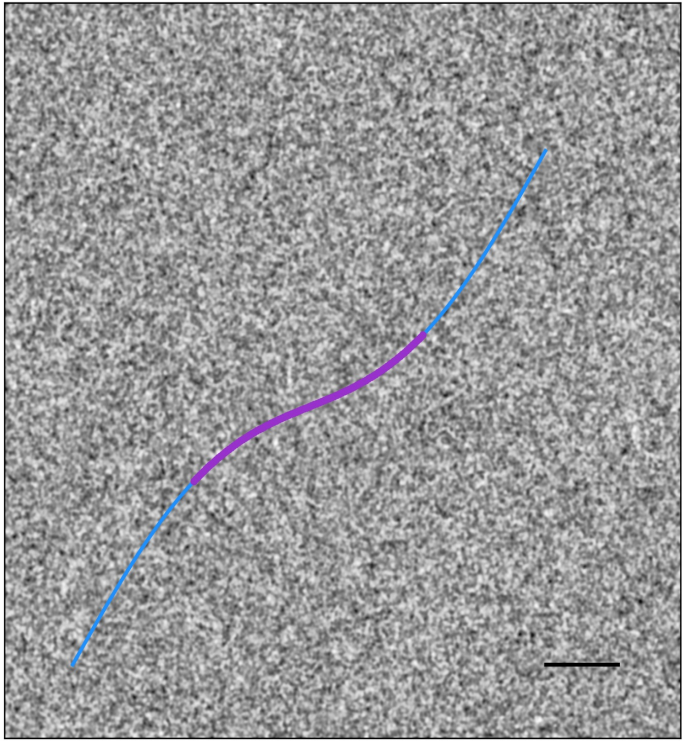
Navigation stats: RMSD error: 39.91; RMSD/dist: 0.100; TD: 9015; p90: 16; p50: 8; complete: 0

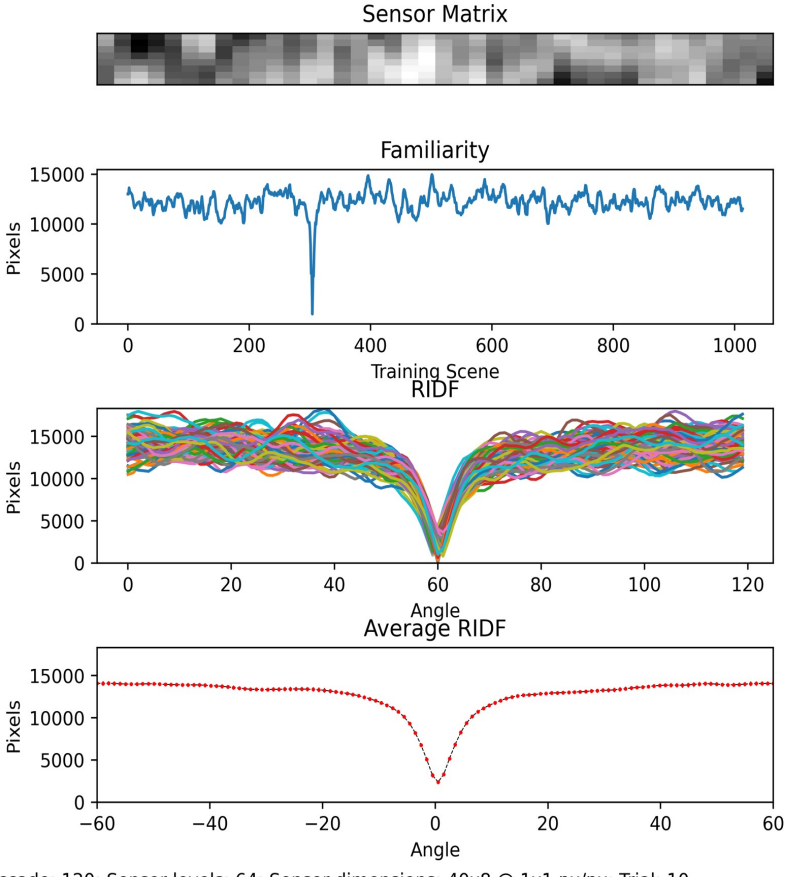




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

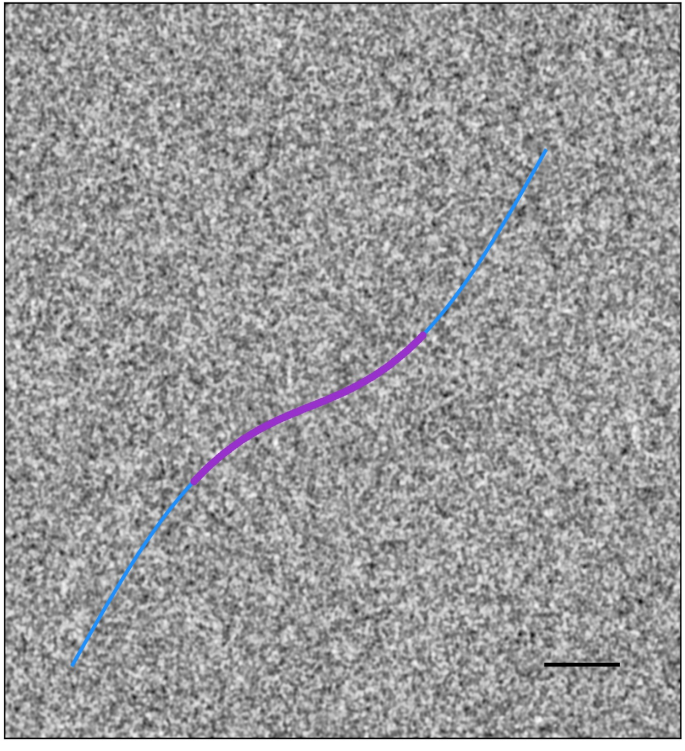
Navigation stats: RMSD error: 54.84; RMSD/dist: 0.137; TD: 8929; p90: 16; p50: 6; complete: 0

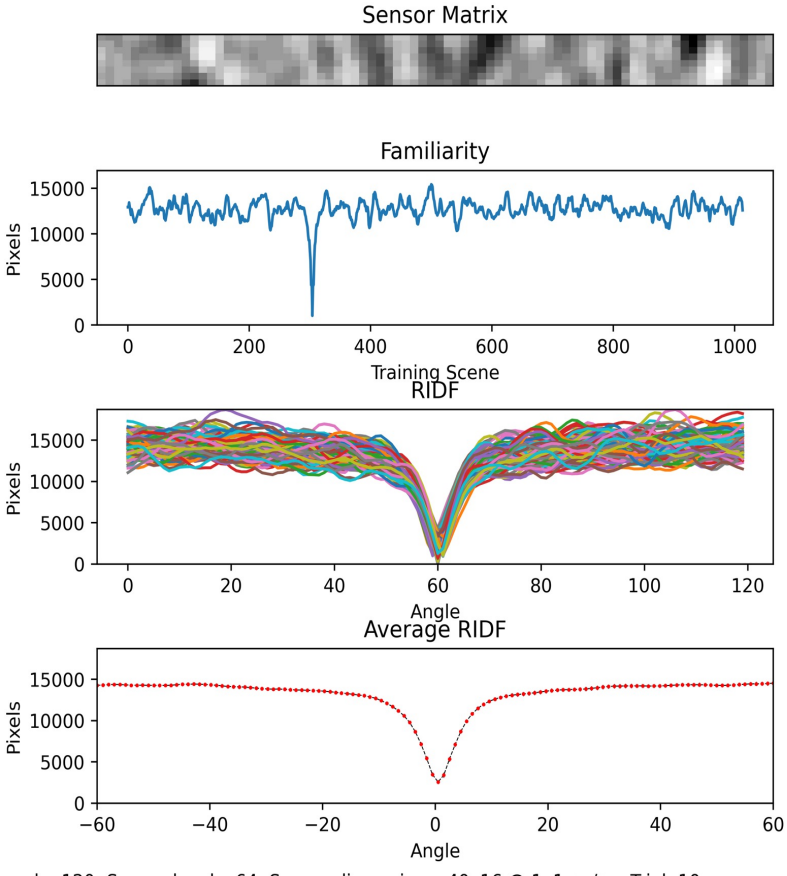




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

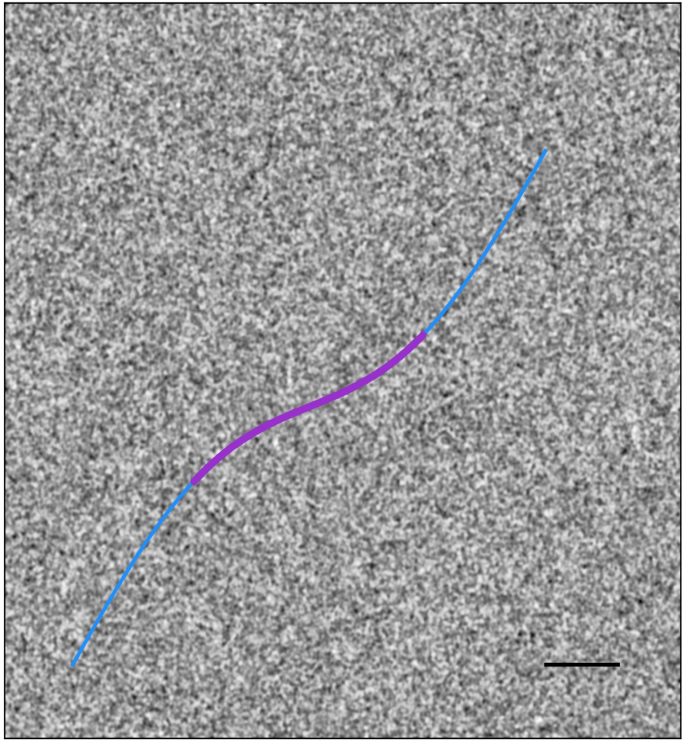
Navigation stats: RMSD error: 48.62; RMSD/dist: 0.122; TD: 9392; p90: 14; p50: 6; complete: 0

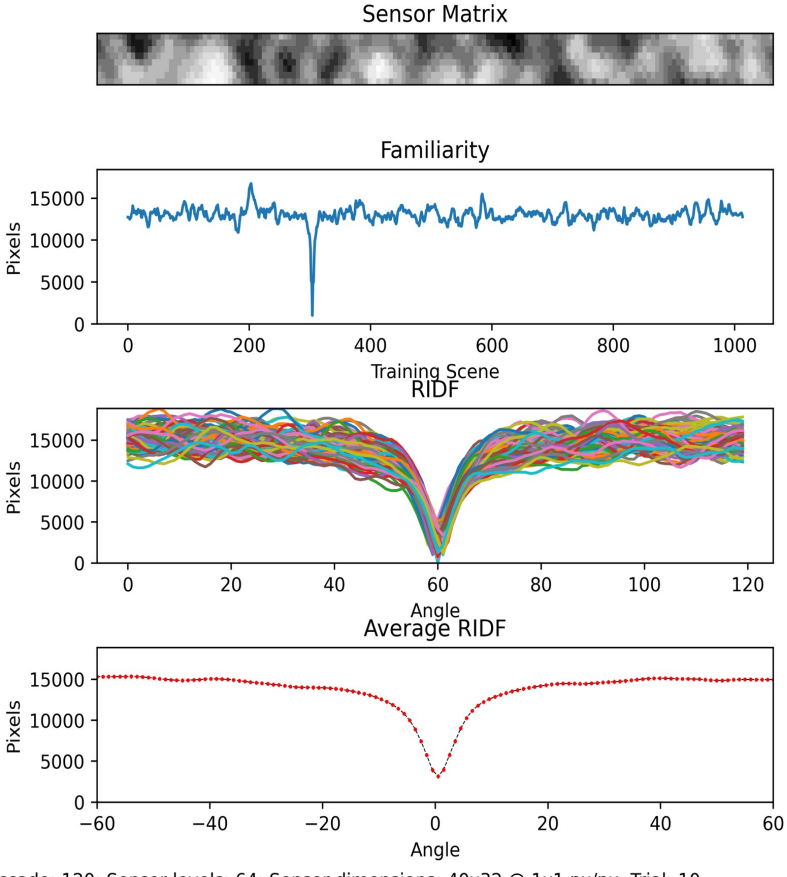




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 45.80; RMSD/dist: 0.115; TD: 9915; p90: 16; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 2; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 57.73; RMSD/dist: 0.144; TD: 9865; p90: 16; p50: 6; complete: 0