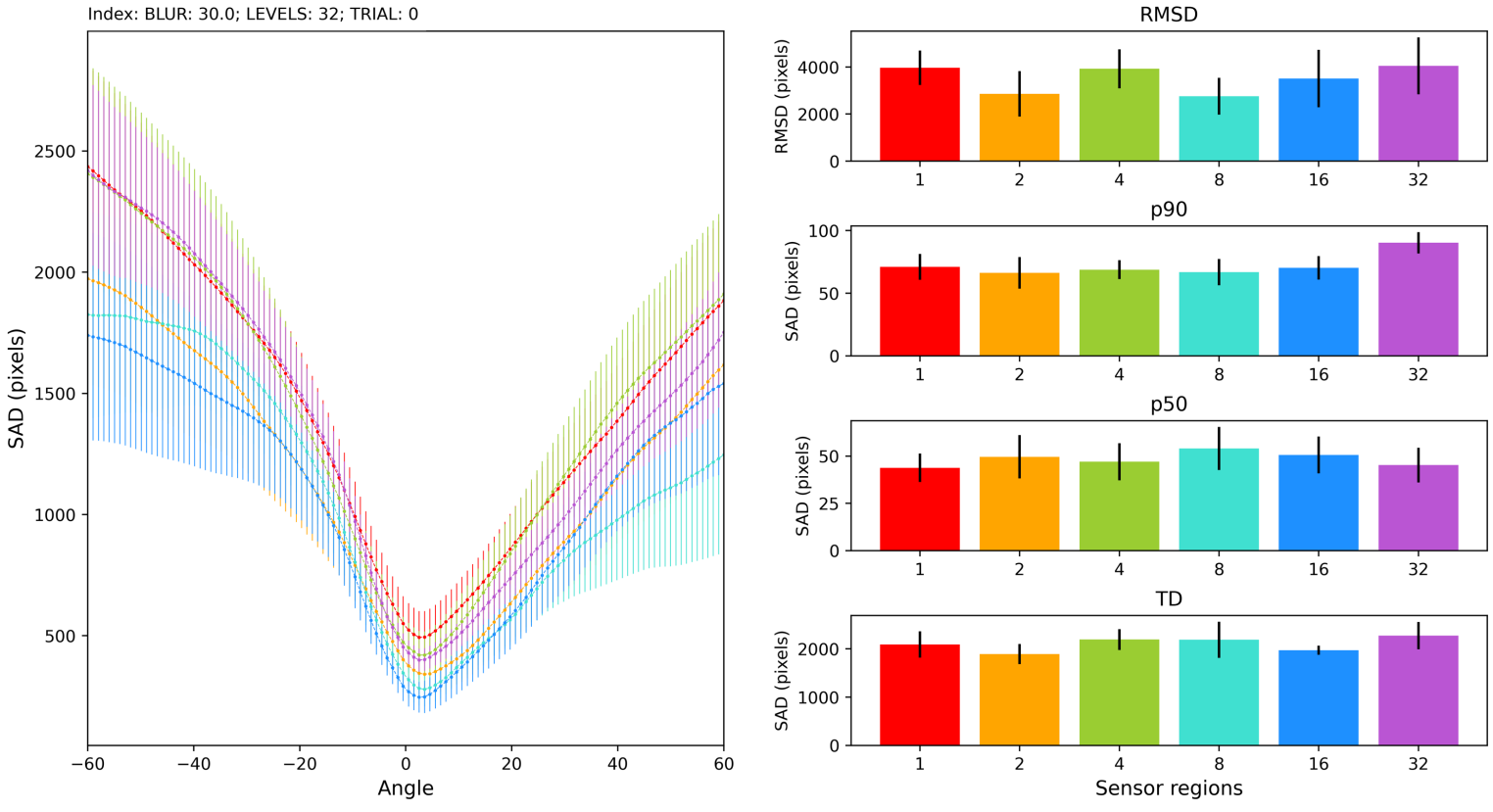
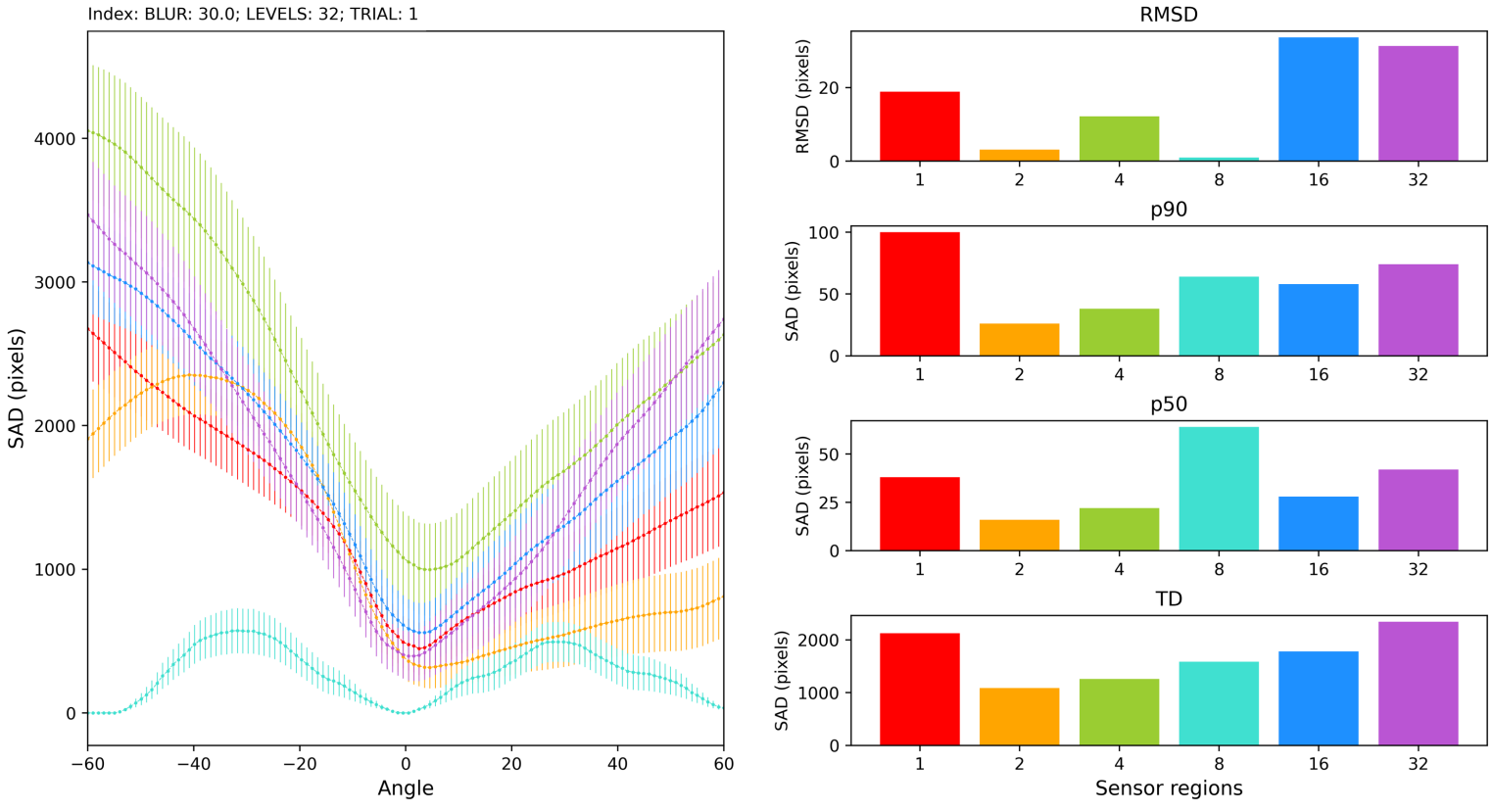
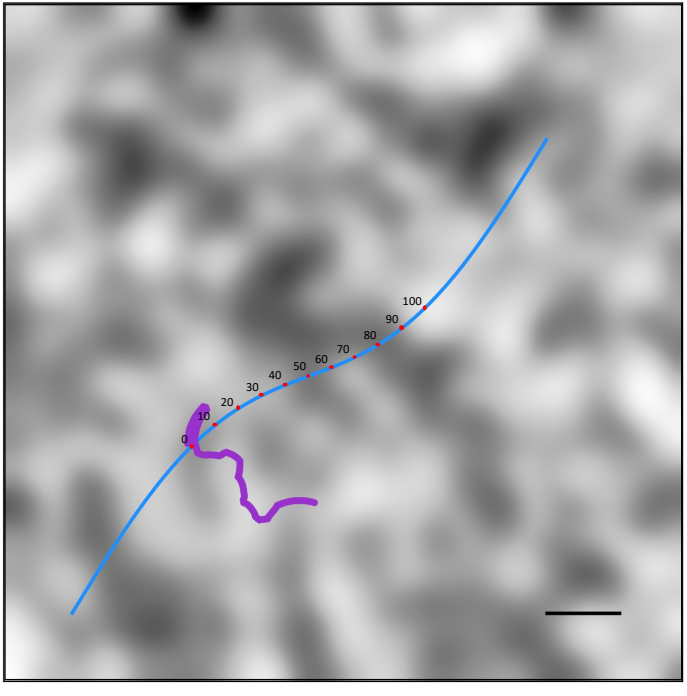
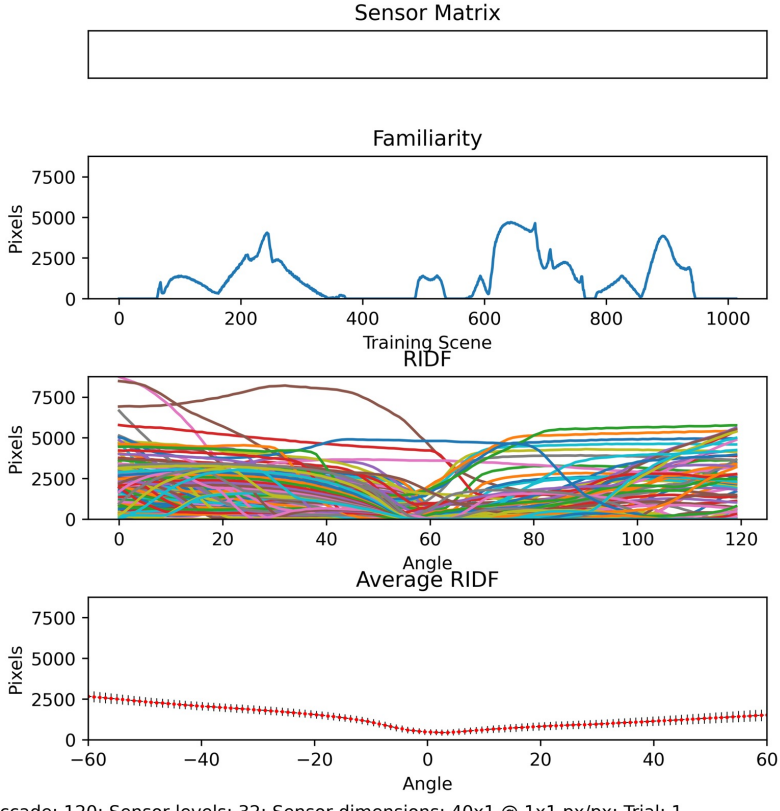

Index: BLUR: 30.0; LEVELS: 32; TRIAL: 0
SAD (pixels)
2500
2000
1500
1000
500
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4000
2000
0
p90
SAD (pixels)
100
50
0
p50
SAD (pixels)
50
25
0
TD
SAD (pixels)
2000
1000
0
1
2
4
8
16
32
Sensor regions


Index: BLUR: 30.0; LEVELS: 32; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

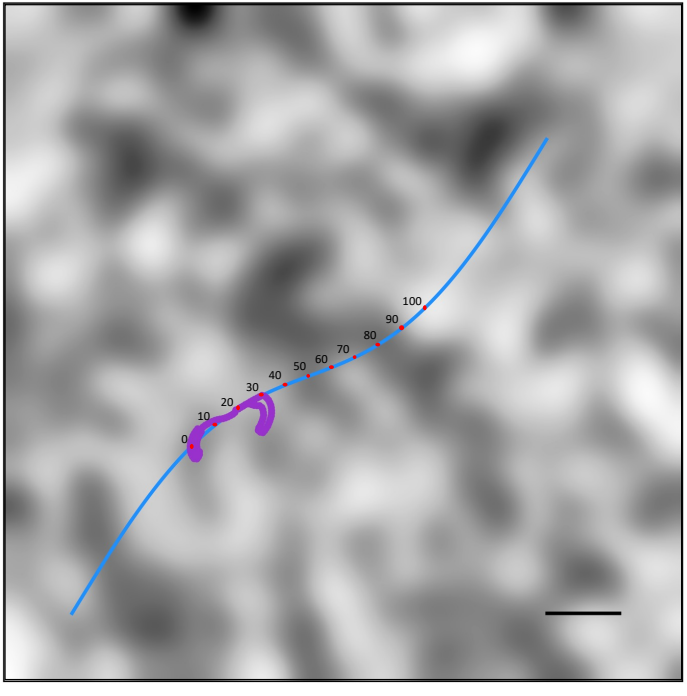
0%

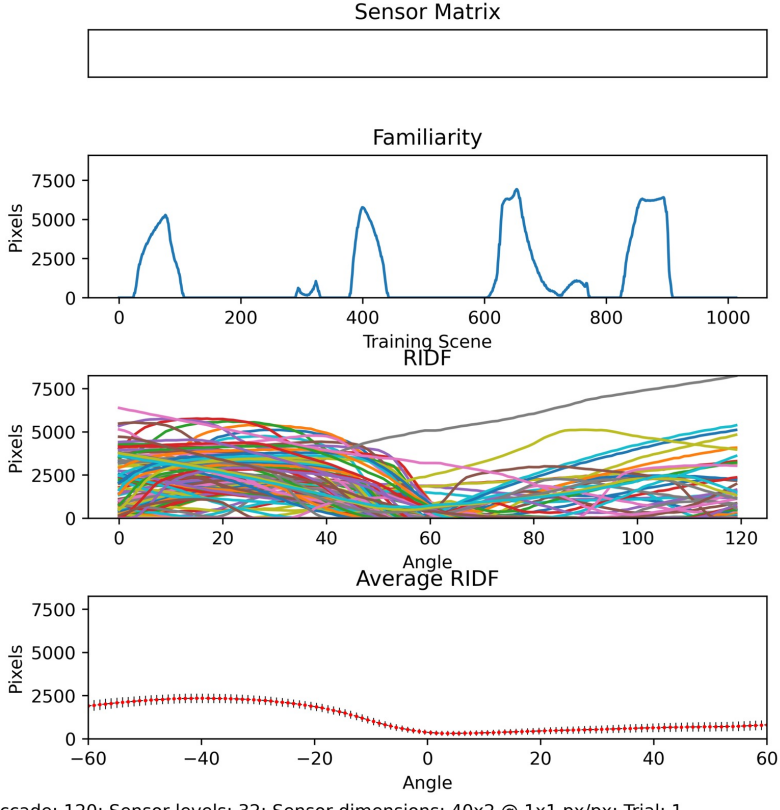




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 7556.94; RMSD/dist: 18.892; TD: 2127; p90: 100; p50: 38; complete: 0

10%

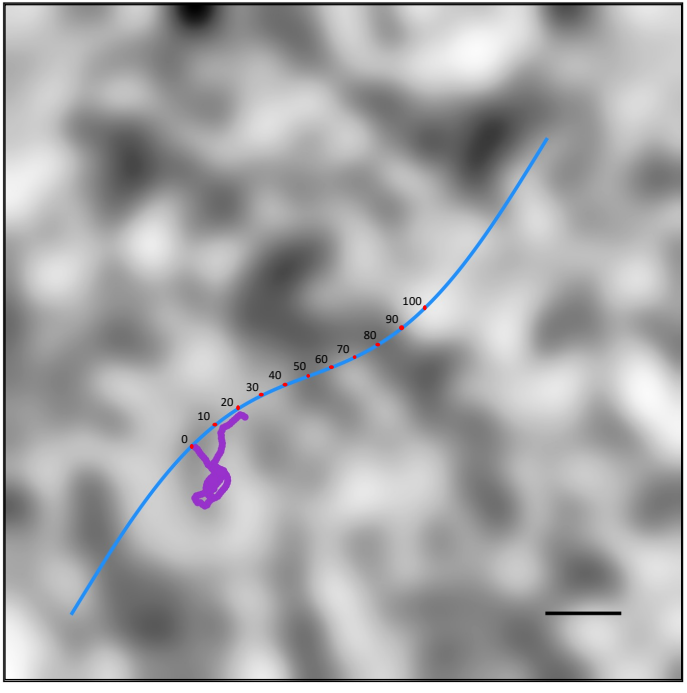


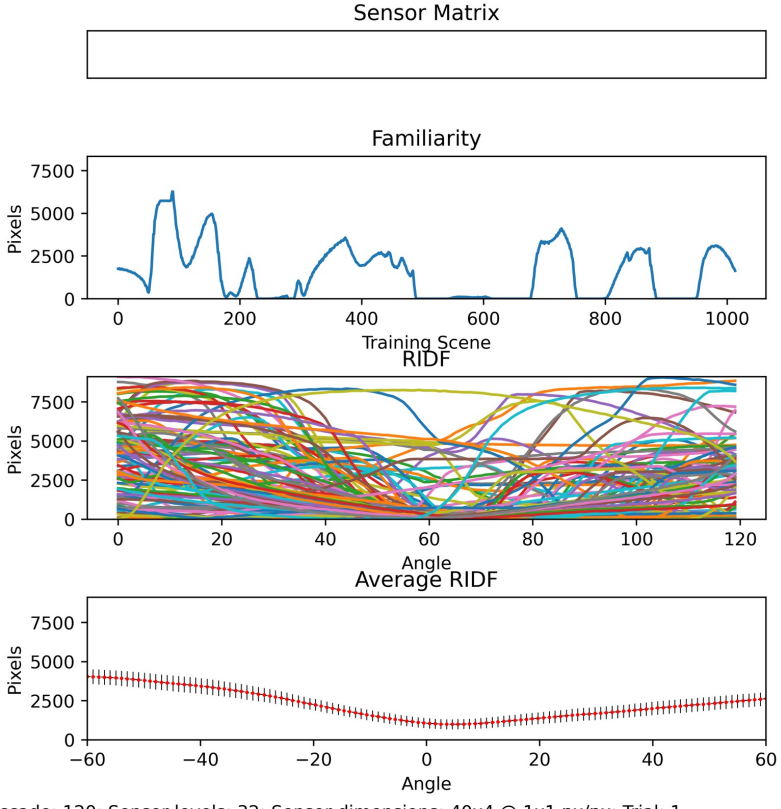


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1255.97; RMSD/dist: 3.140; TD: 1085; p90: 26; p50: 16; complete: 0

0%

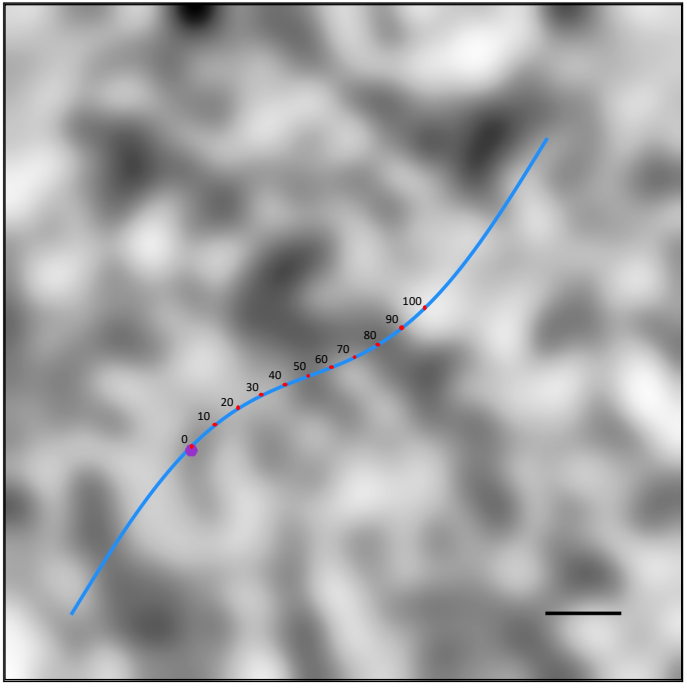


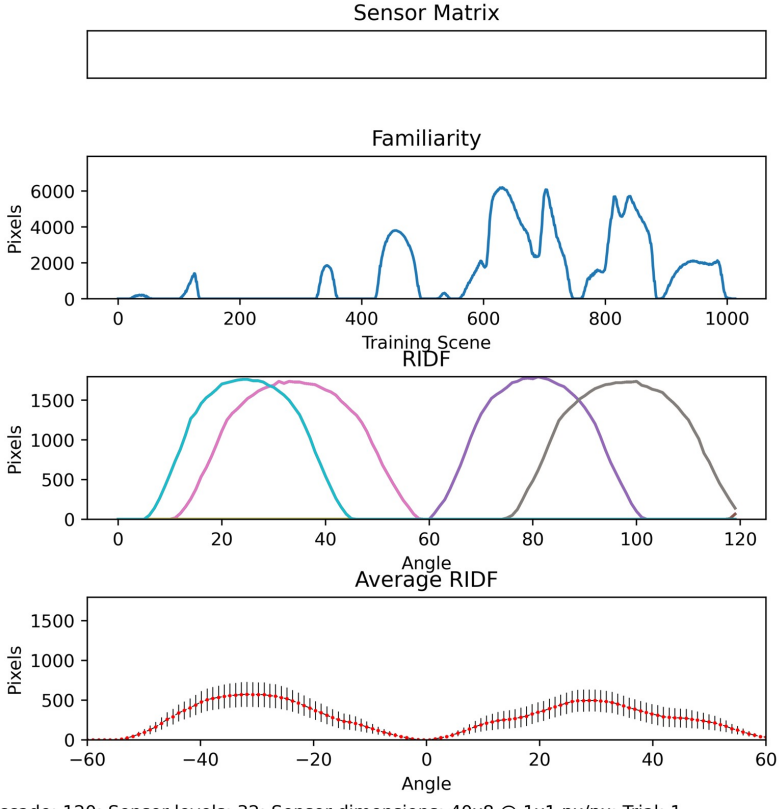


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4873.07; RMSD/dist: 12.183; TD: 1257; p90: 38; p50: 22; complete: 0

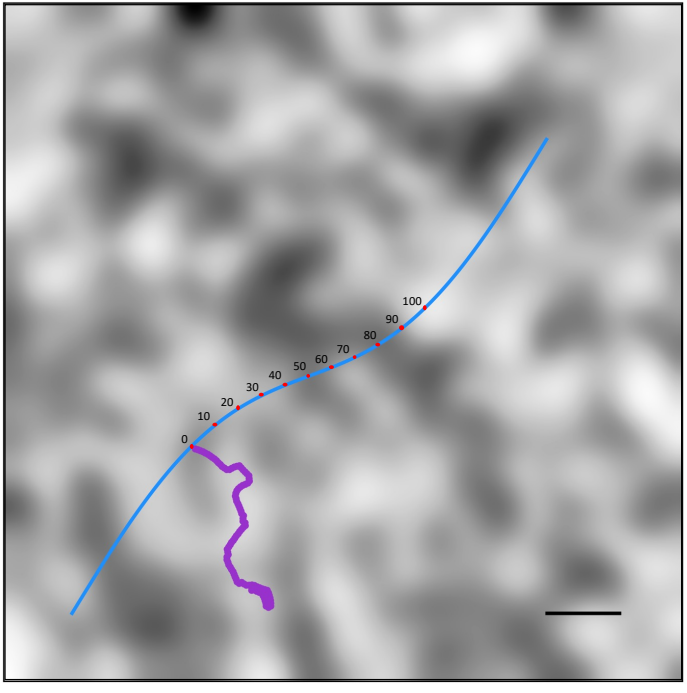
0%

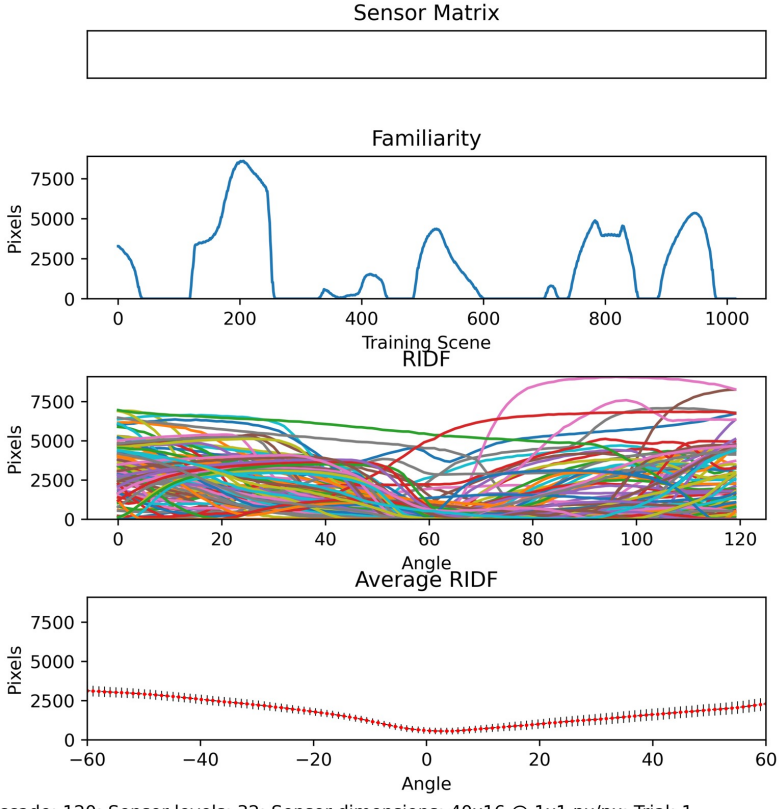




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 1587; p90: 64; p50: 64; complete: 0

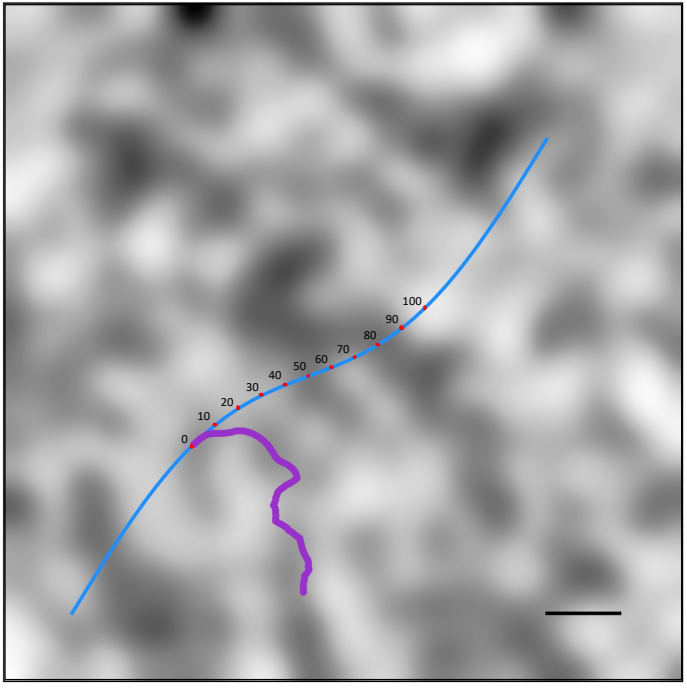
0%

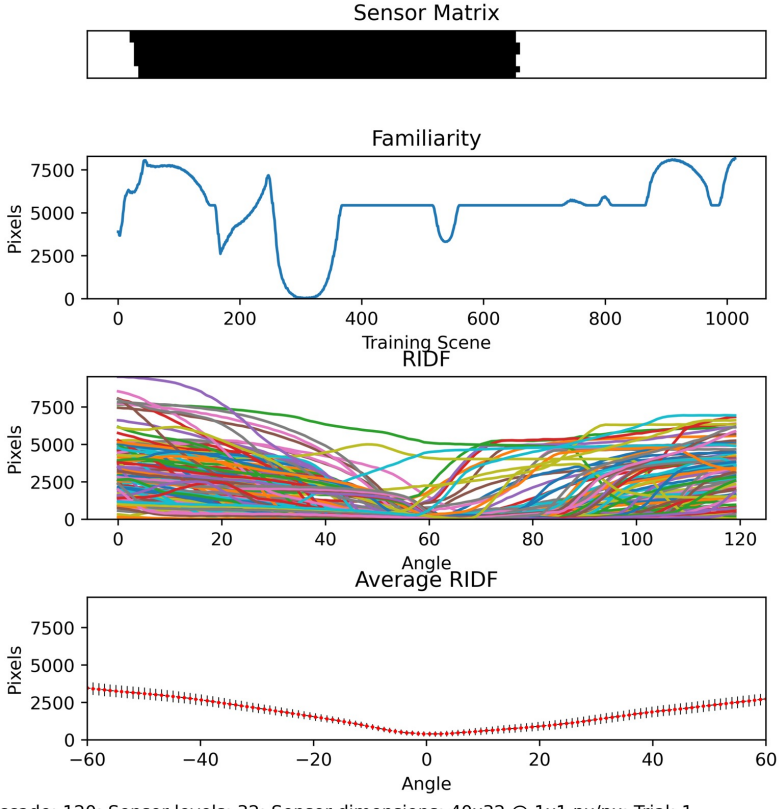




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 13456.68; RMSD/dist: 33.642; TD: 1782; p90: 58; p50: 28; complete: 0

0%





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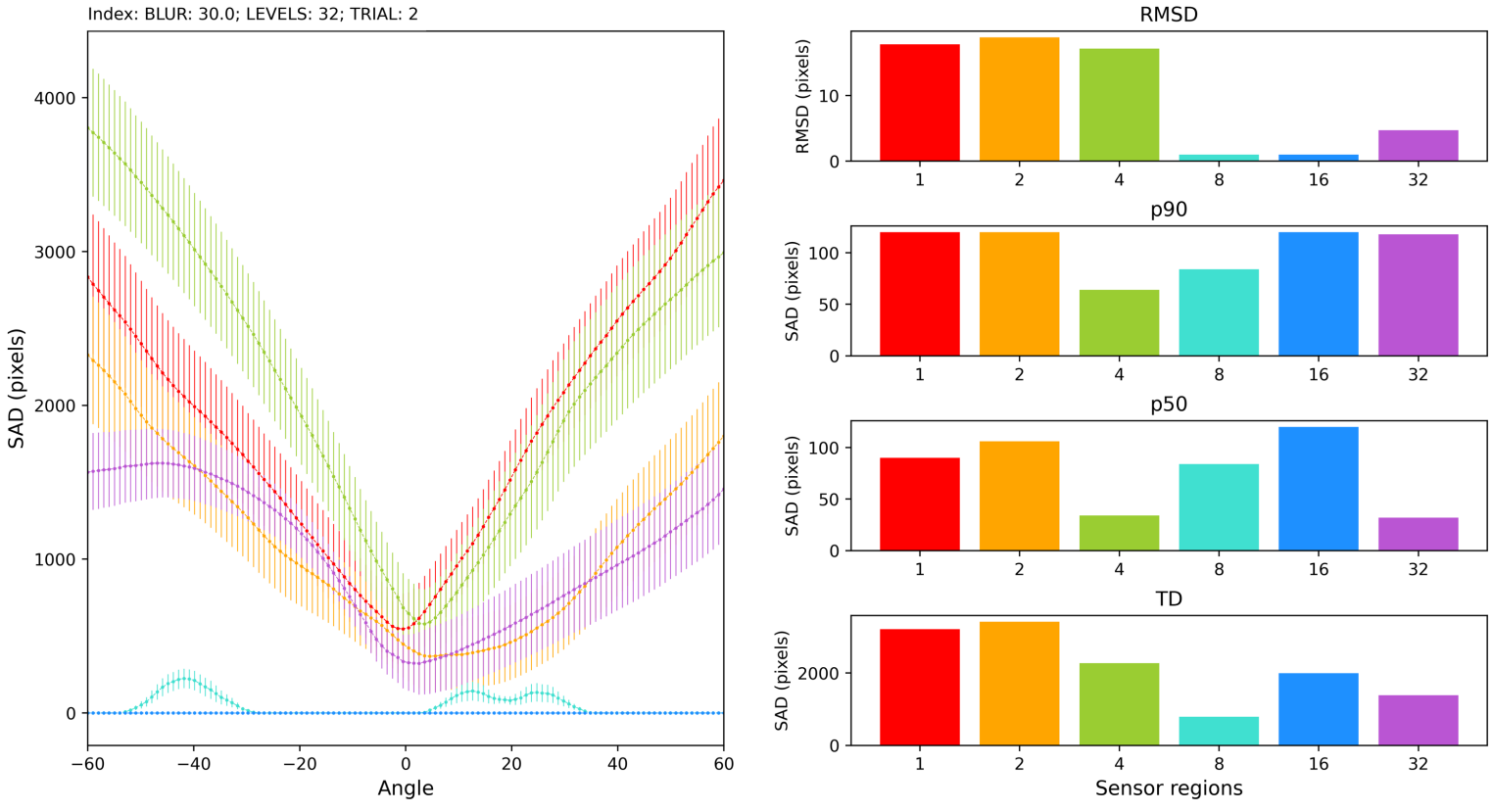
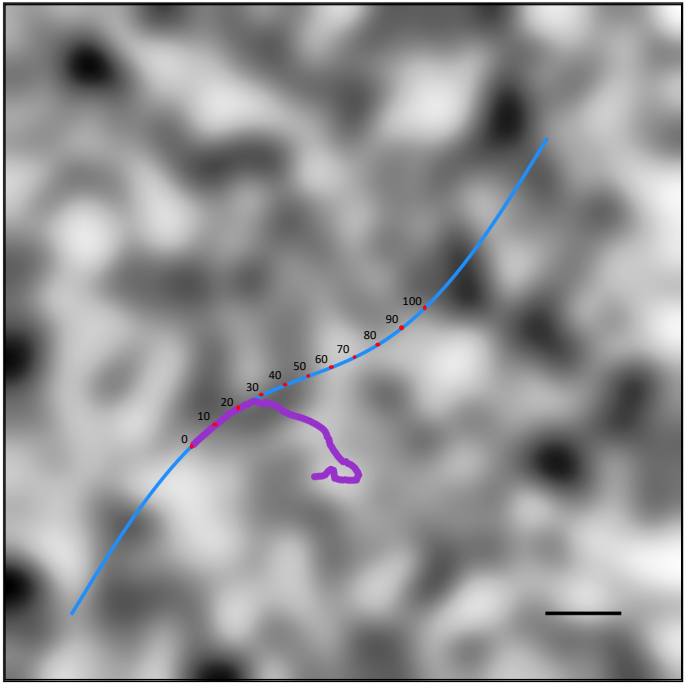
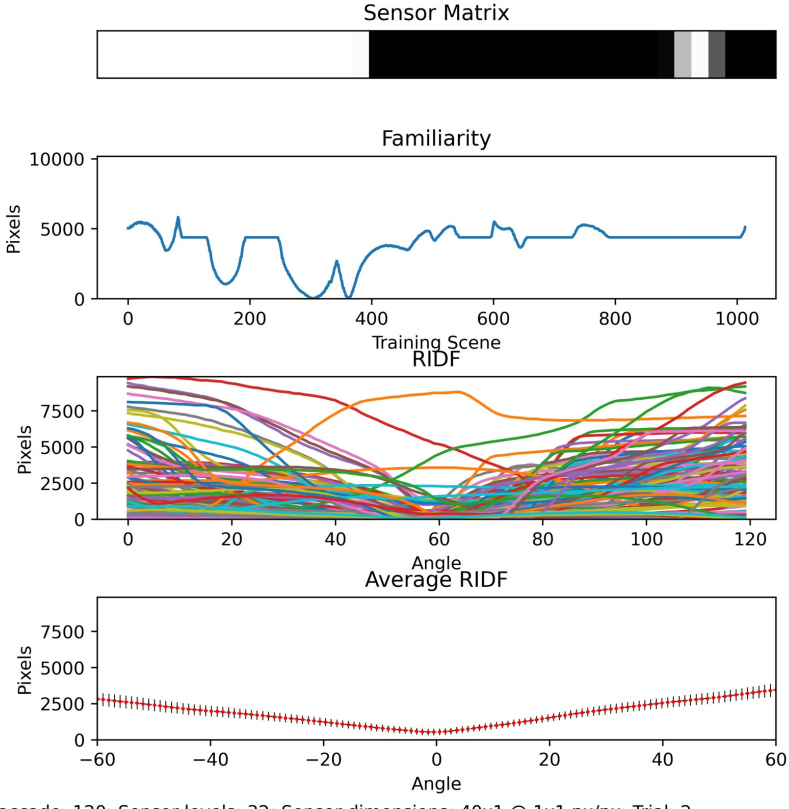
Navigation stats: RMSD error: 12520.32; RMSD/dist: 31.301; TD: 2344; p90: 74; p50: 42; complete: 0


Index: BLUR: 30.0; LEVELS: 32; TRIAL: 2
SAD (pixels)
4000
3000
2000
1000
0
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
TD
2000
Sensor regions

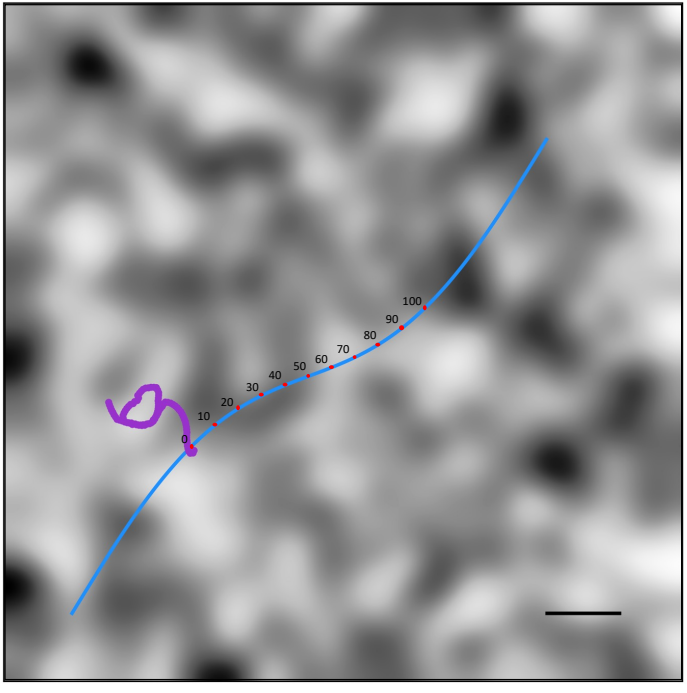
20%

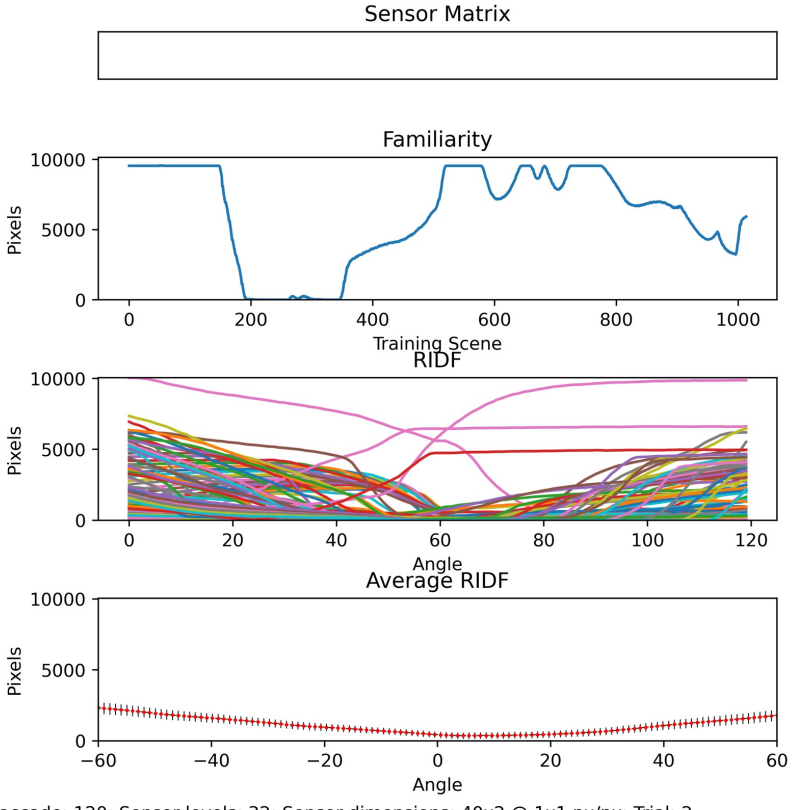




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 7138.78; RMSD/dist: 17.847; TD: 3207; p90: 120; p50: 90; complete: 0

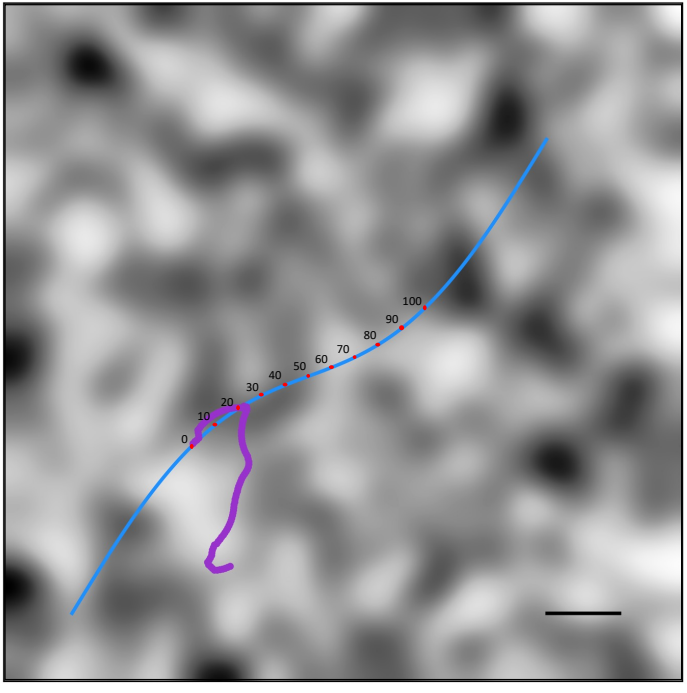
0%

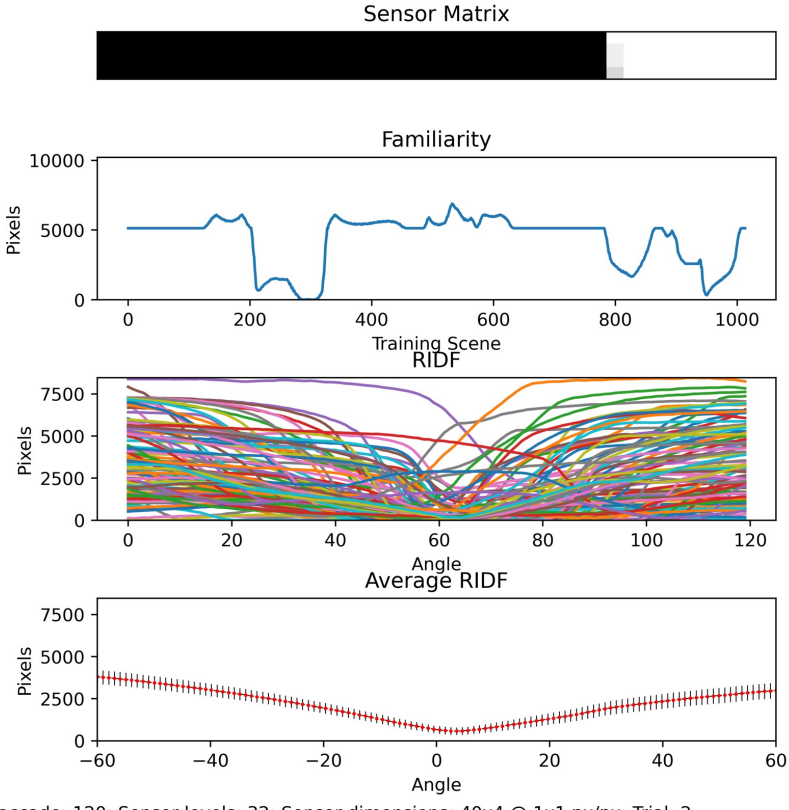




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 7558.49; RMSD/dist: 18.896; TD: 3416; p90: 120; p50: 106; complete: 0

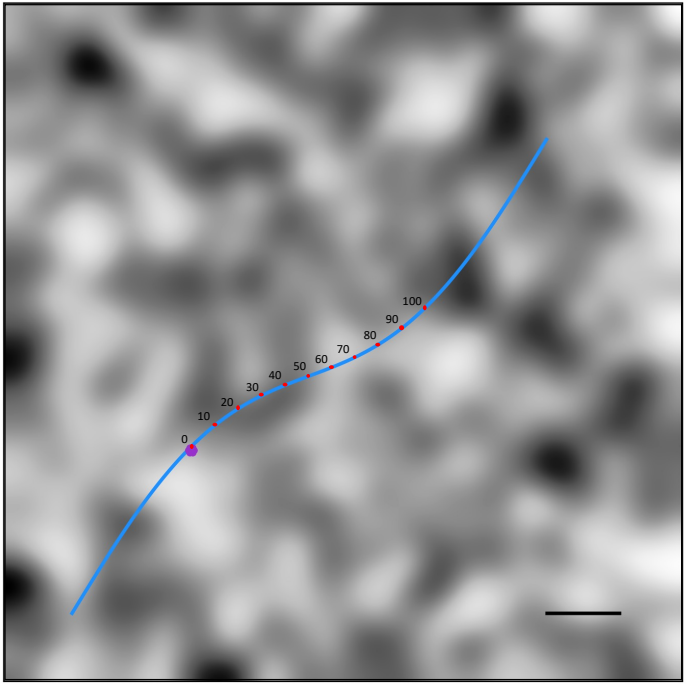
0%

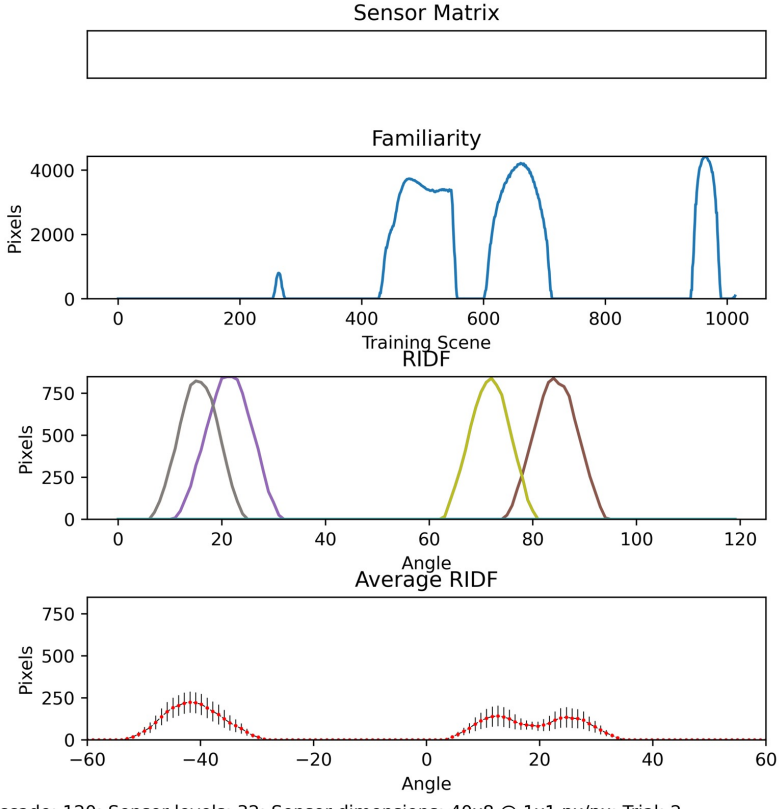




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 6866.30; RMSD/dist: 17.166; TD: 2270; p90: 64; p50: 34; complete: 0

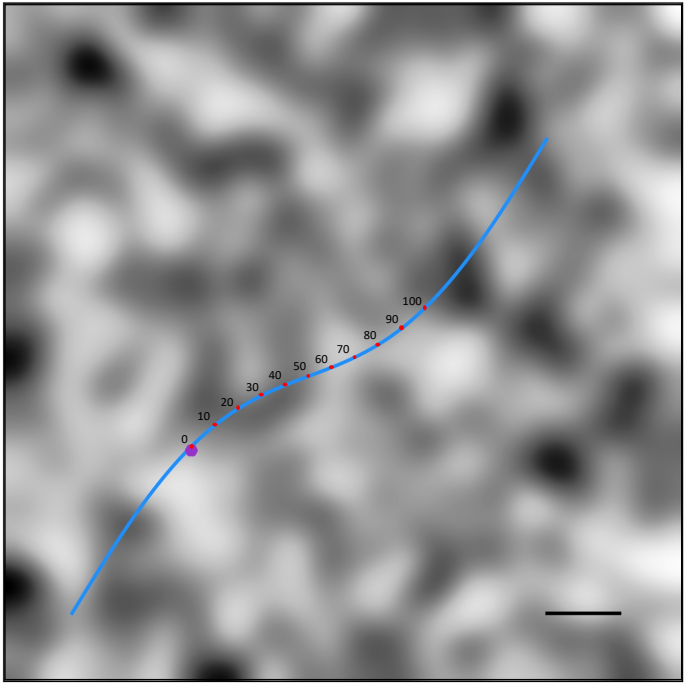
0%

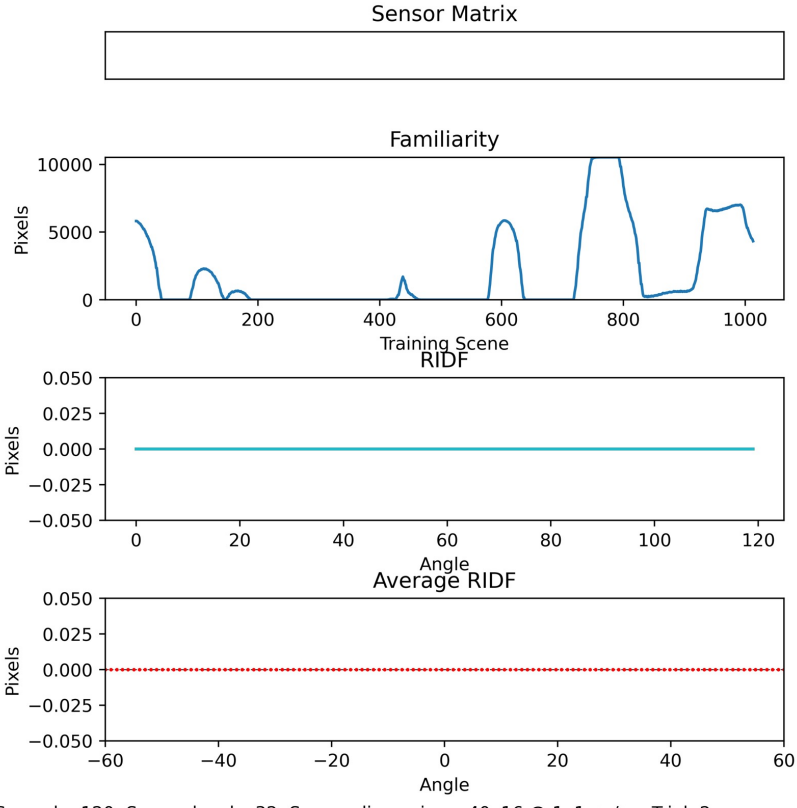




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 792; p90: 84; p50: 84; complete: 0

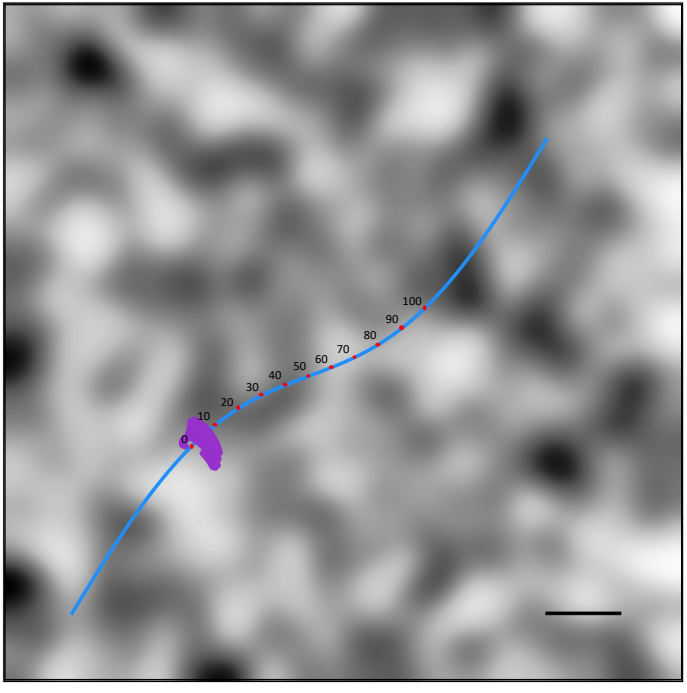
0%

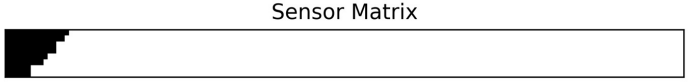


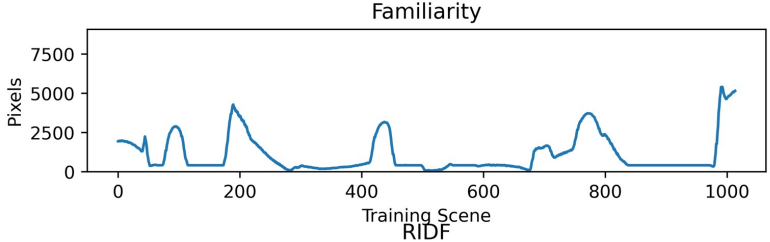


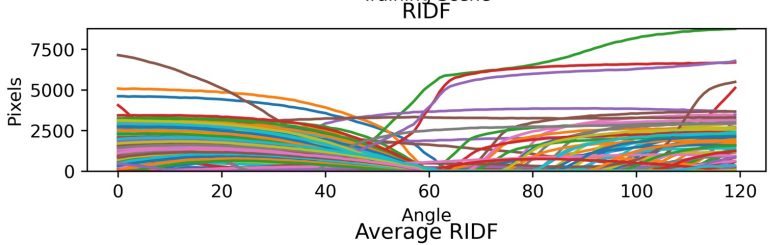
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 1993; p90: 120; p50: 120; complete: 0

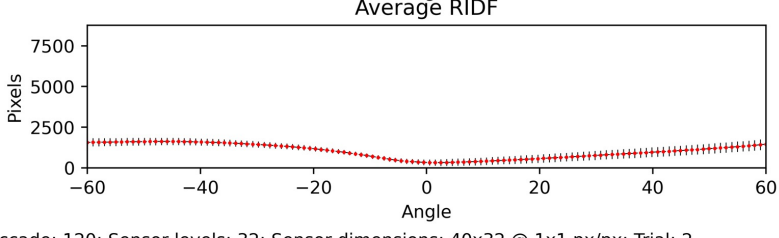
0%











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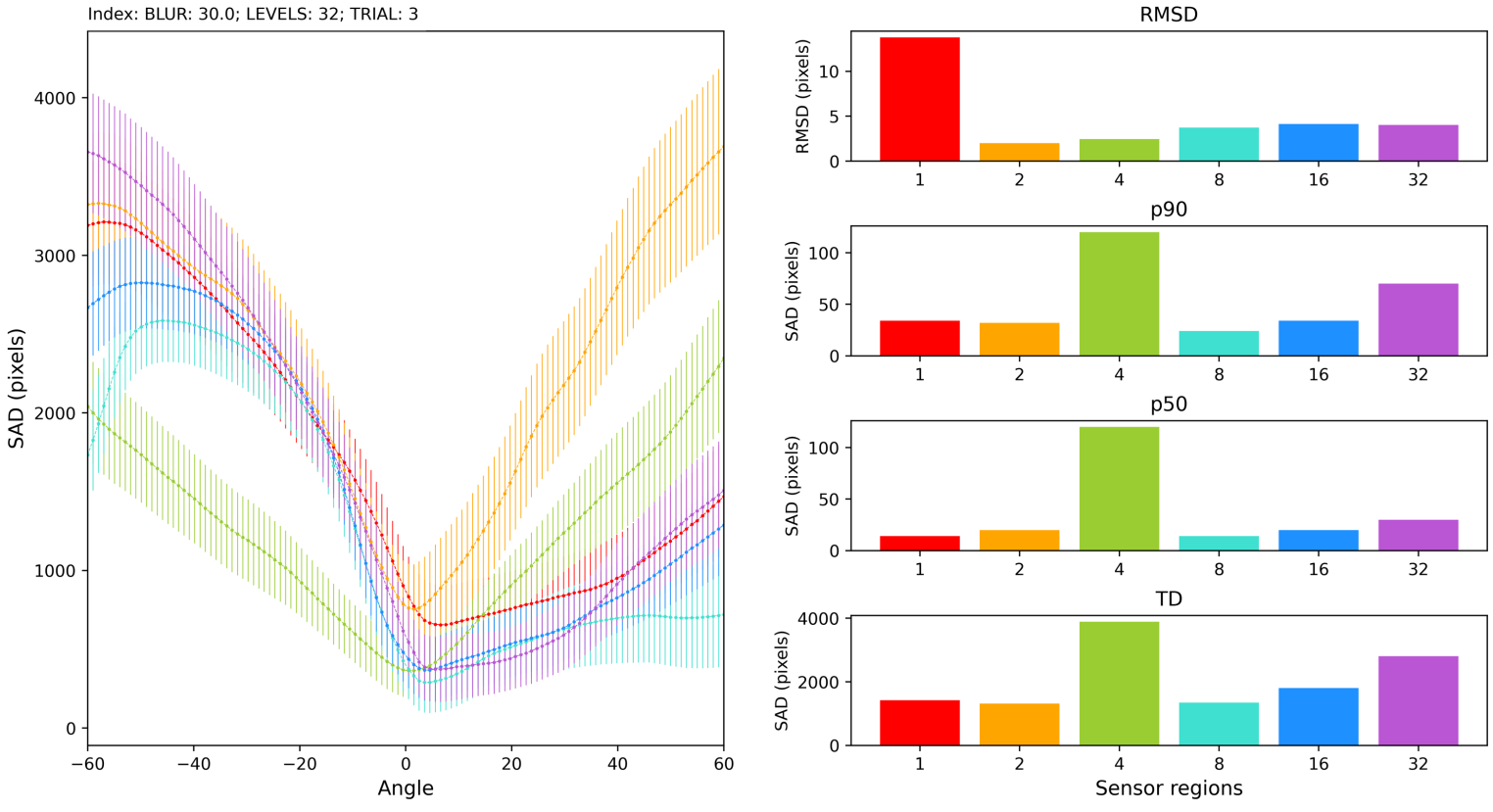
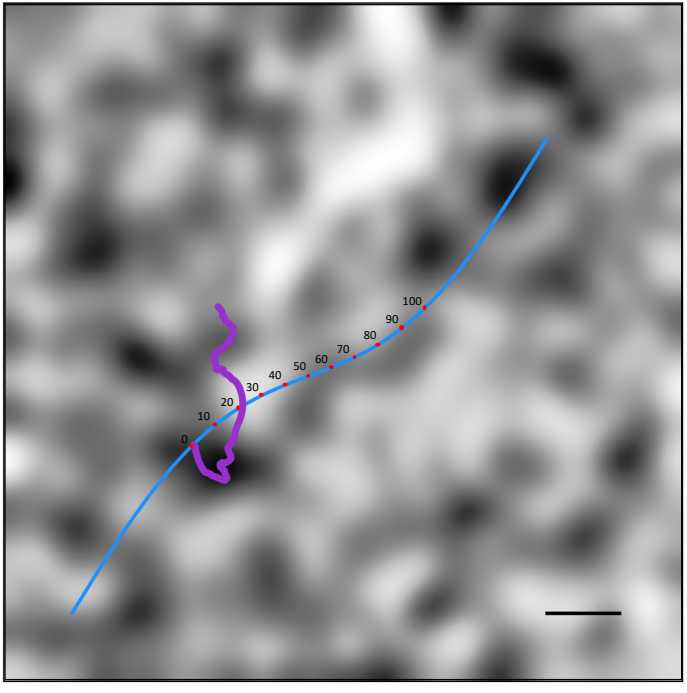
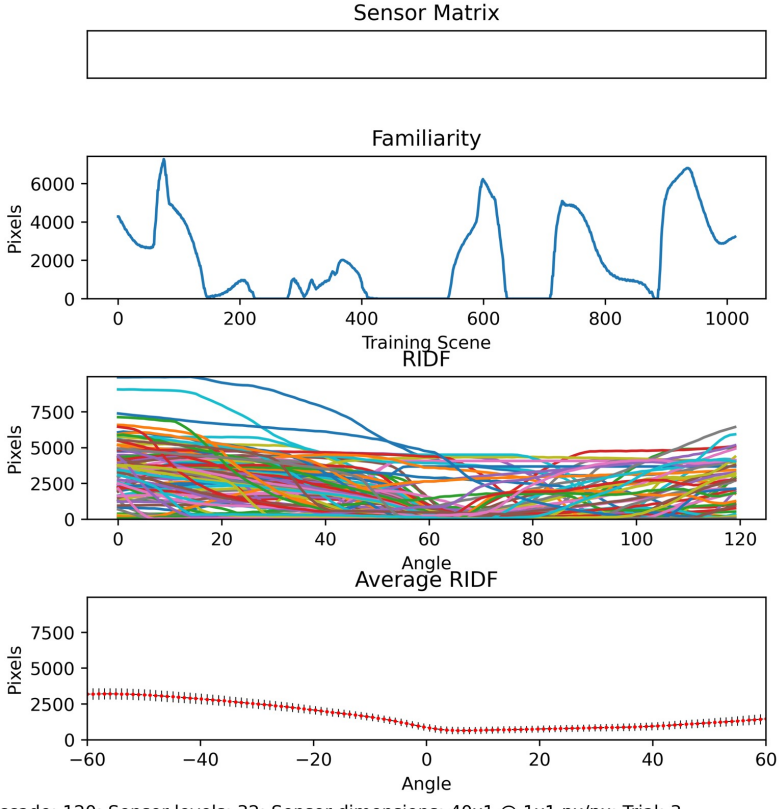

Index: BLUR: 30.0; LEVELS: 32; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

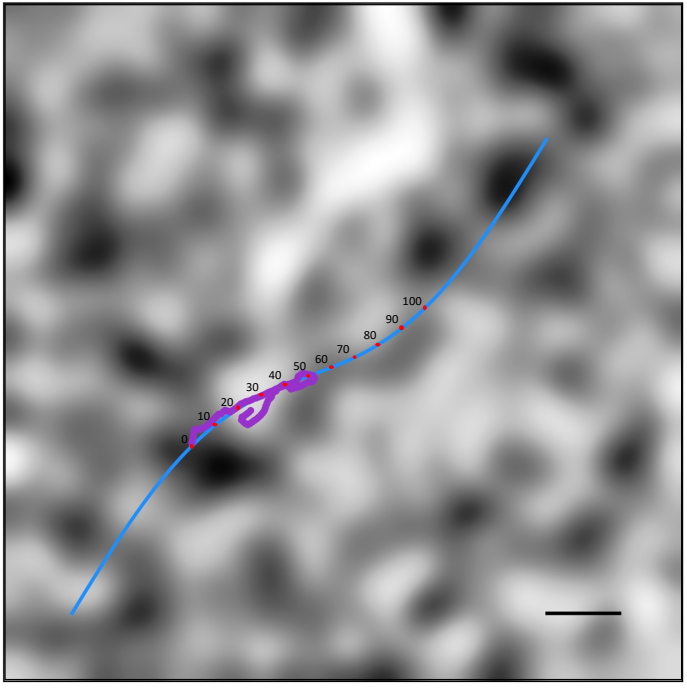
0%

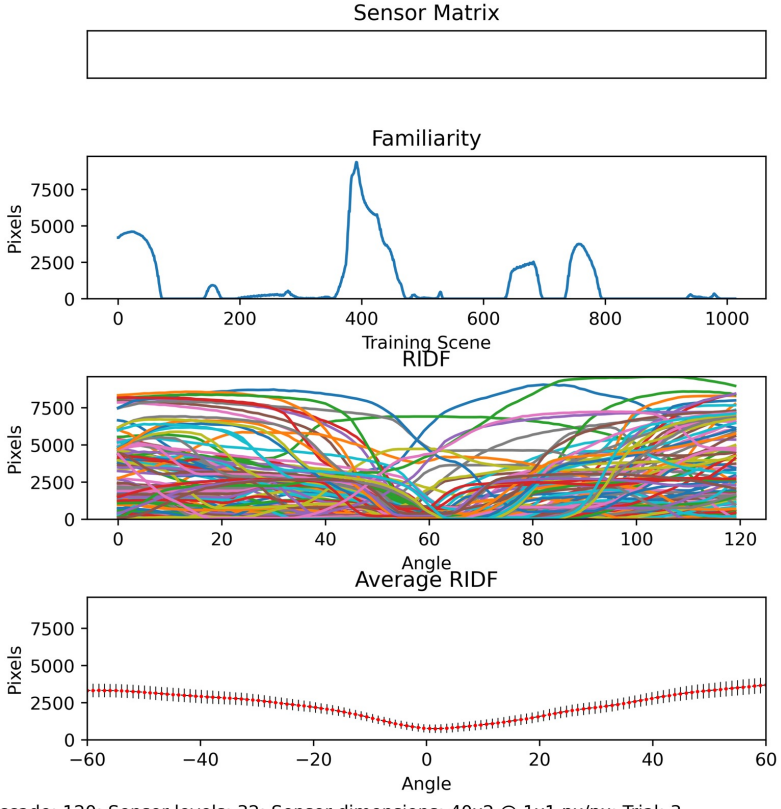




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 5509.78; RMSD/dist: 13.774; TD: 1420; p90: 34; p50: 14; complete: 0

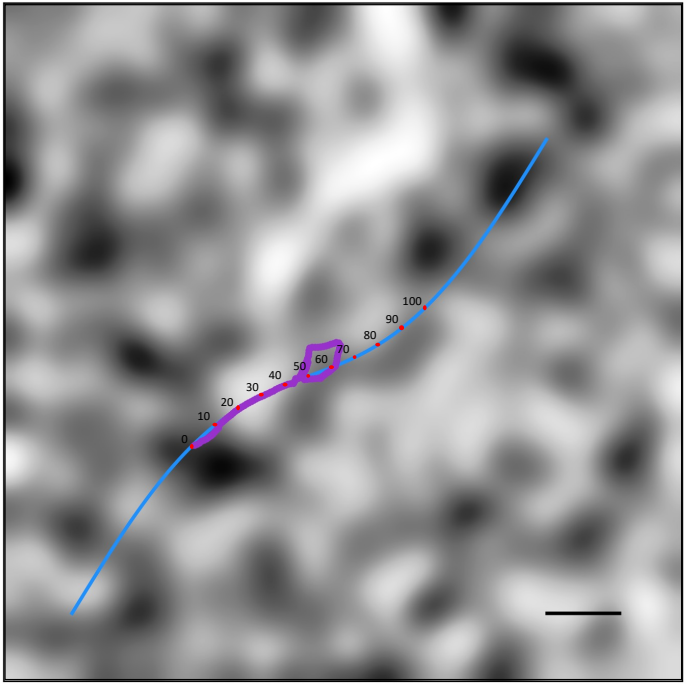
20%

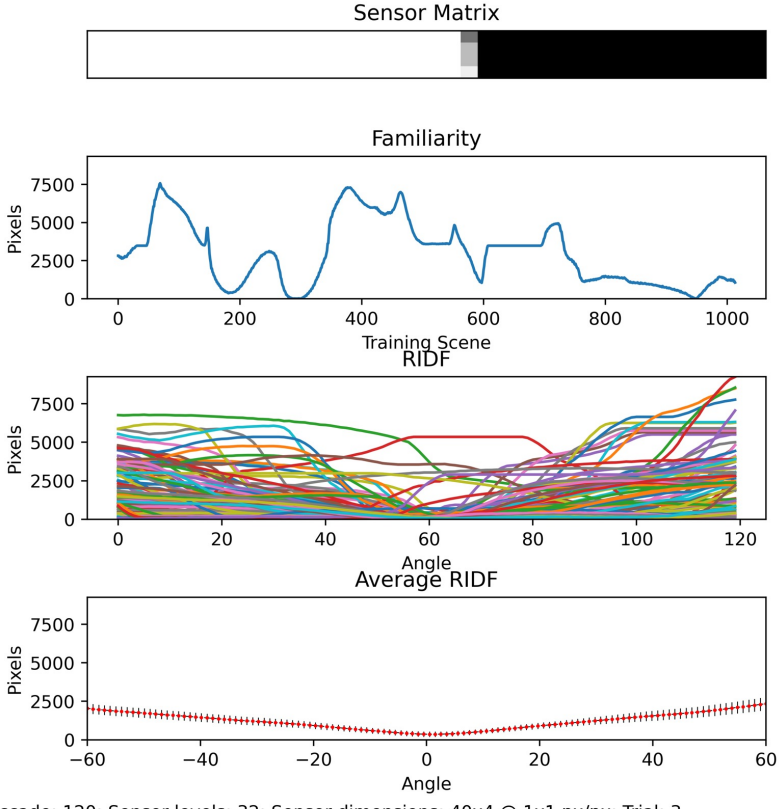




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 799.98; RMSD/dist: 2.000; TD: 1312; p90: 32; p50: 20; complete: 0

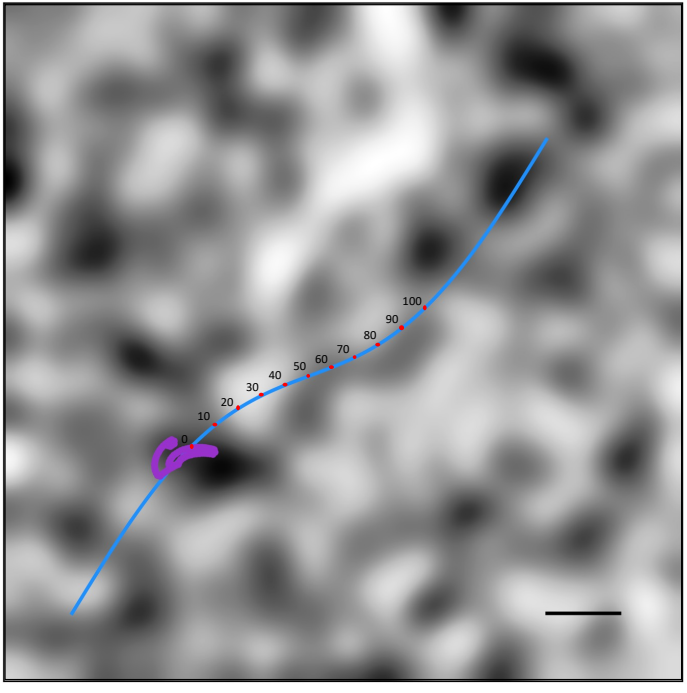
30%

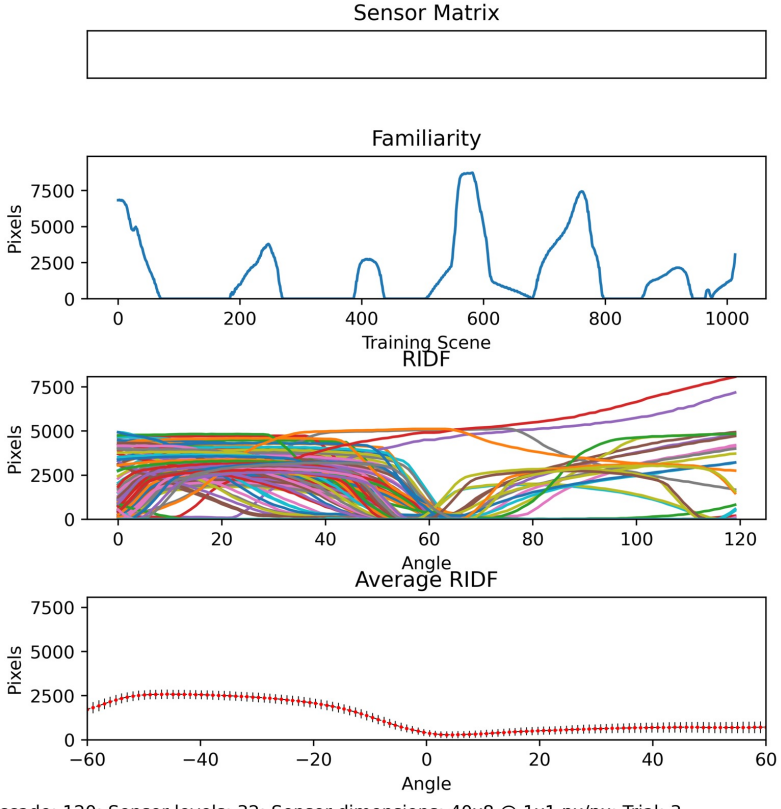




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 982.48; RMSD/dist: 2.456; TD: 3891; p90: 120; p50: 120; complete: 0

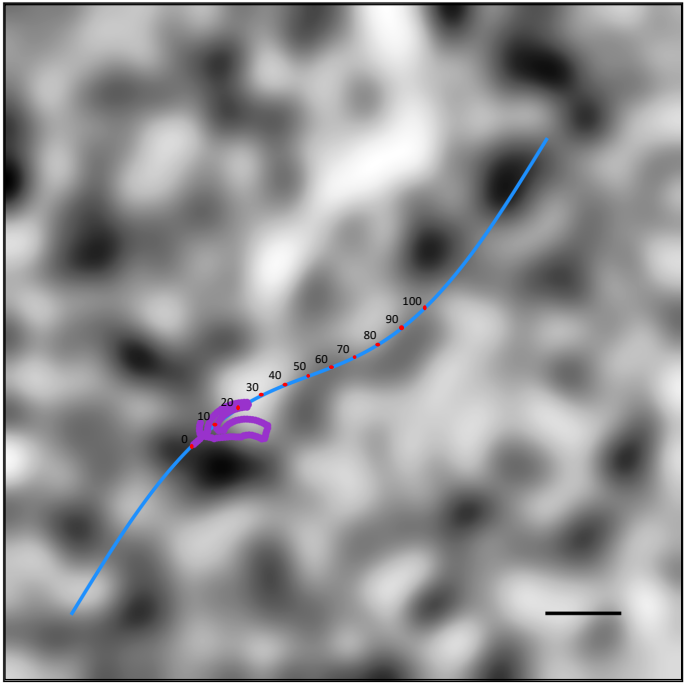
0%

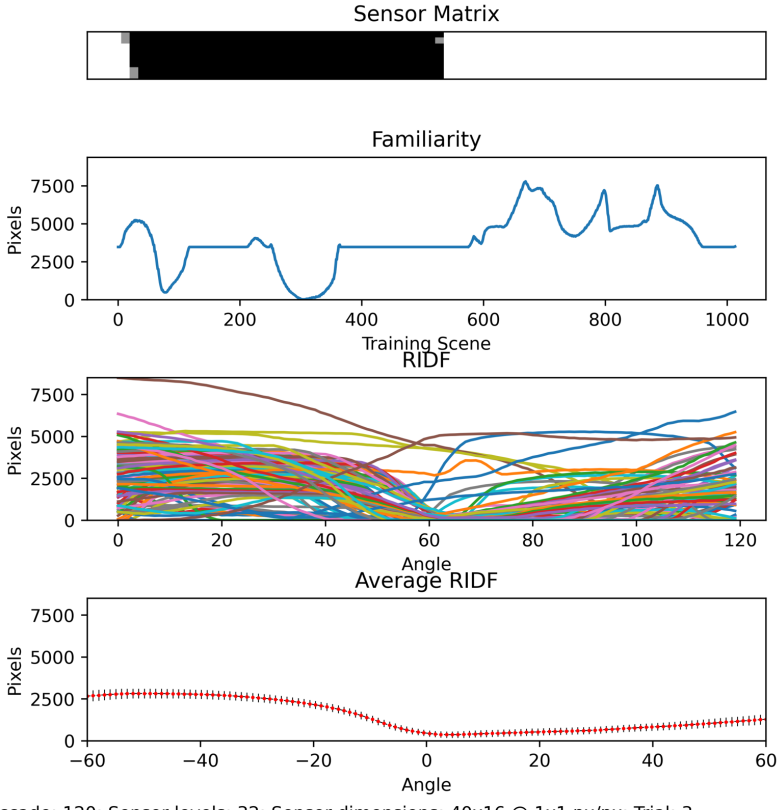




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 1487.32; RMSD/dist: 3.718; TD: 1348; p90: 24; p50: 14; complete: 0

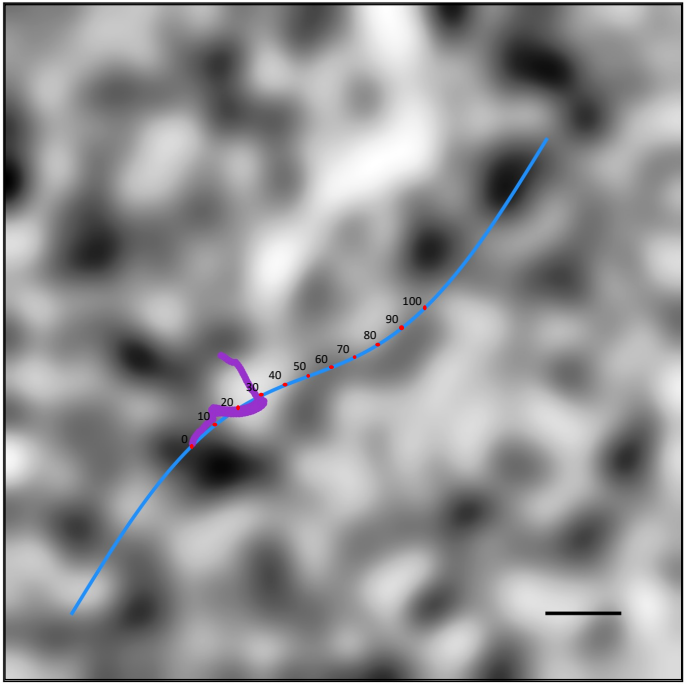
10%

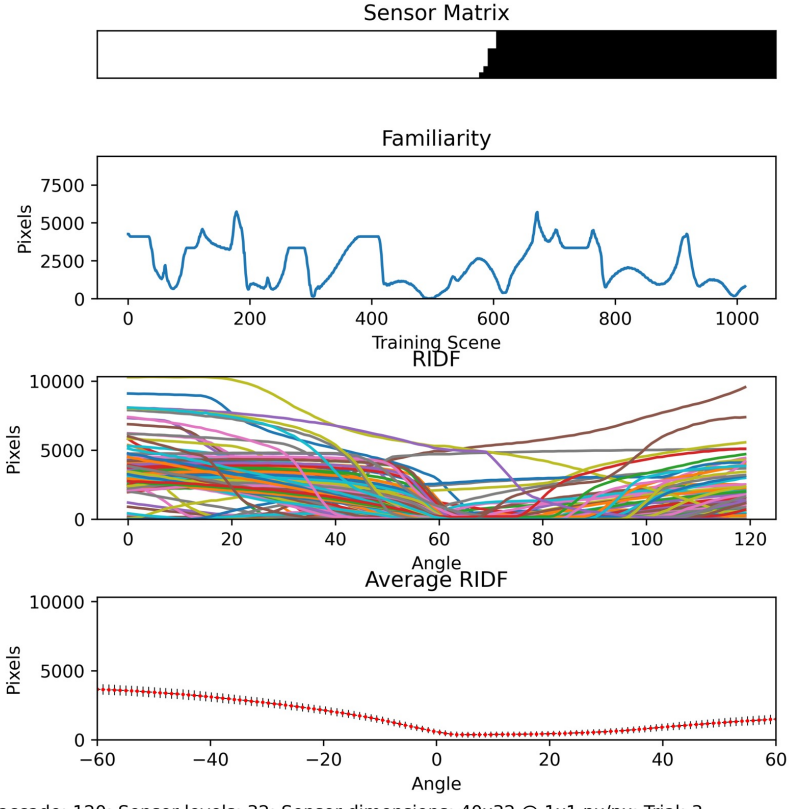




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 1647.00; RMSD/dist: 4.117; TD: 1807; p90: 34; p50: 20; complete: 0

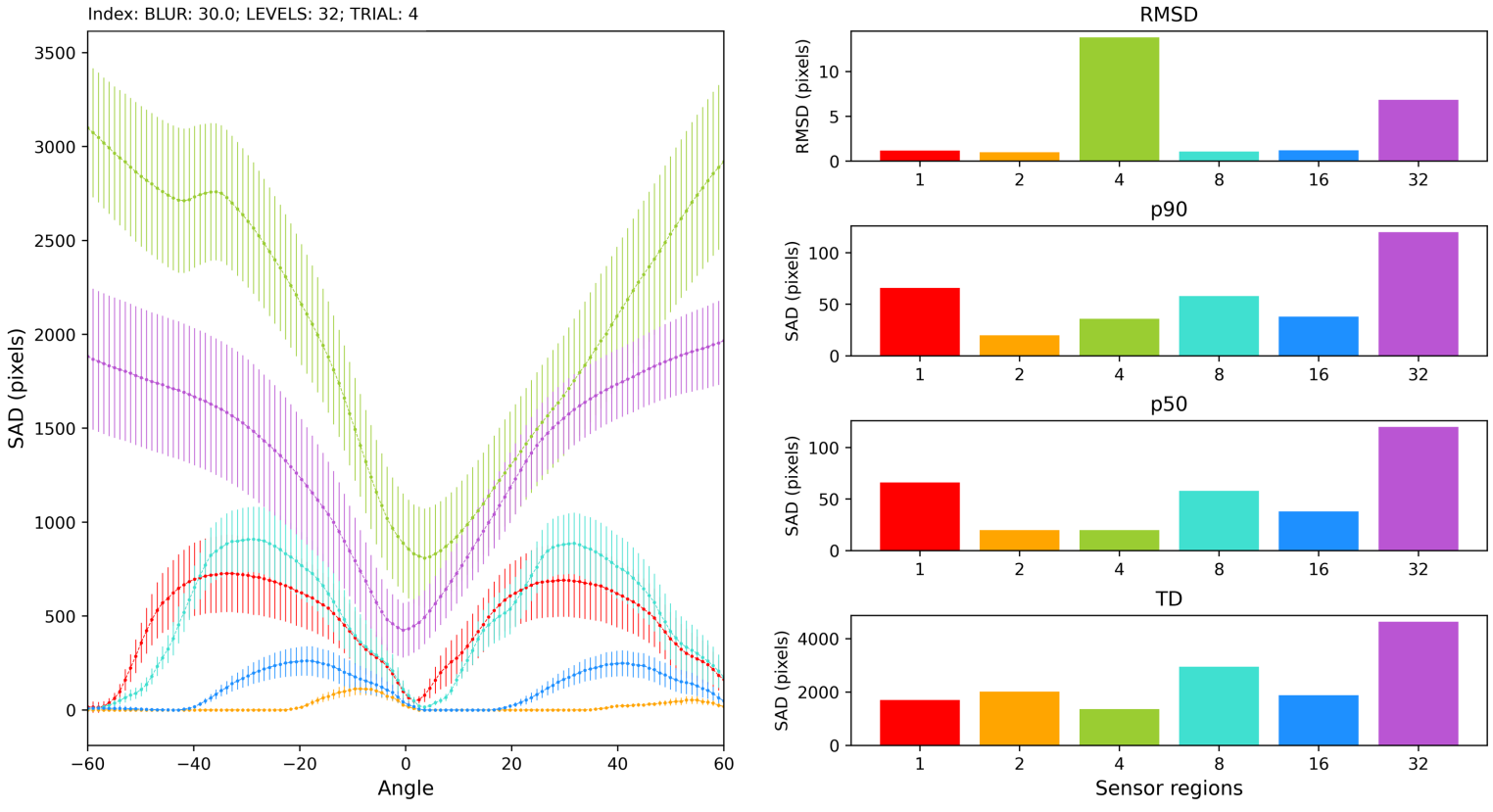
0%



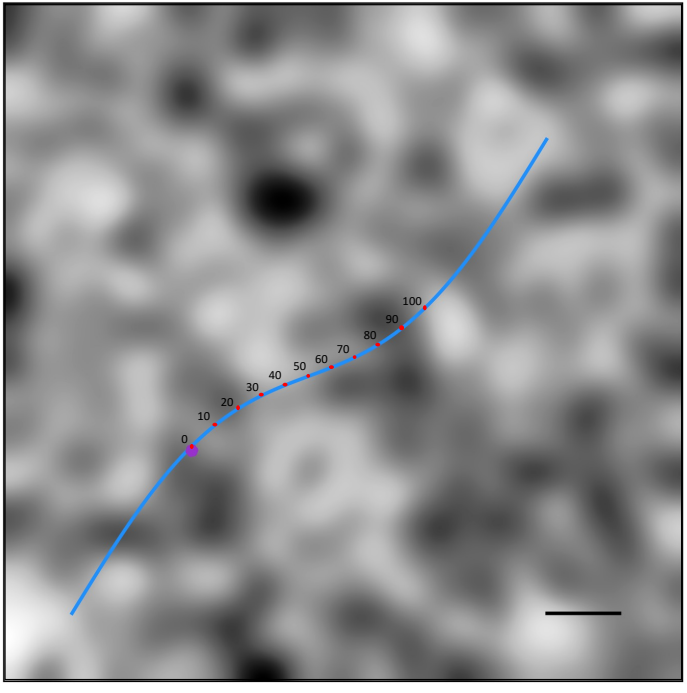


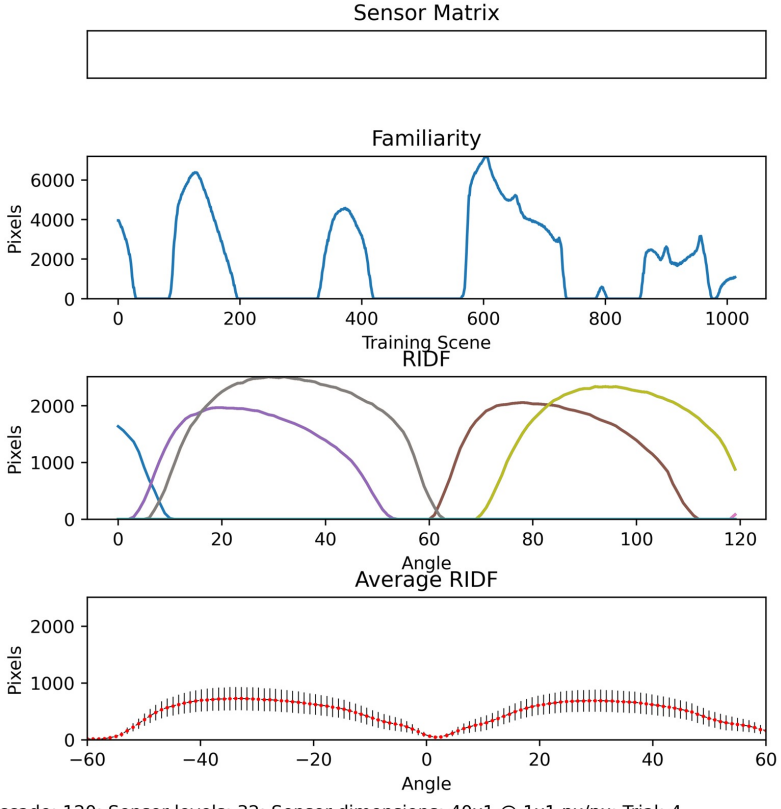
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1605.34; RMSD/dist: 4.013; TD: 2808; p90: 70; p50: 30; complete: 0


Index: BLUR: 30.0; LEVELS: 32; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





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Navigation stats: RMSD error: 466.65; RMSD/dist: 1.167; TD: 1701; p90: 66; p50: 66; complete: 0

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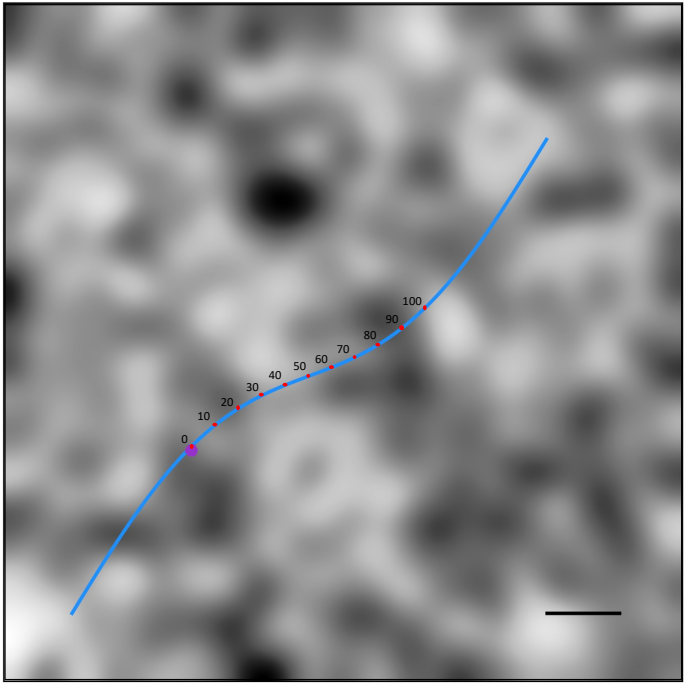

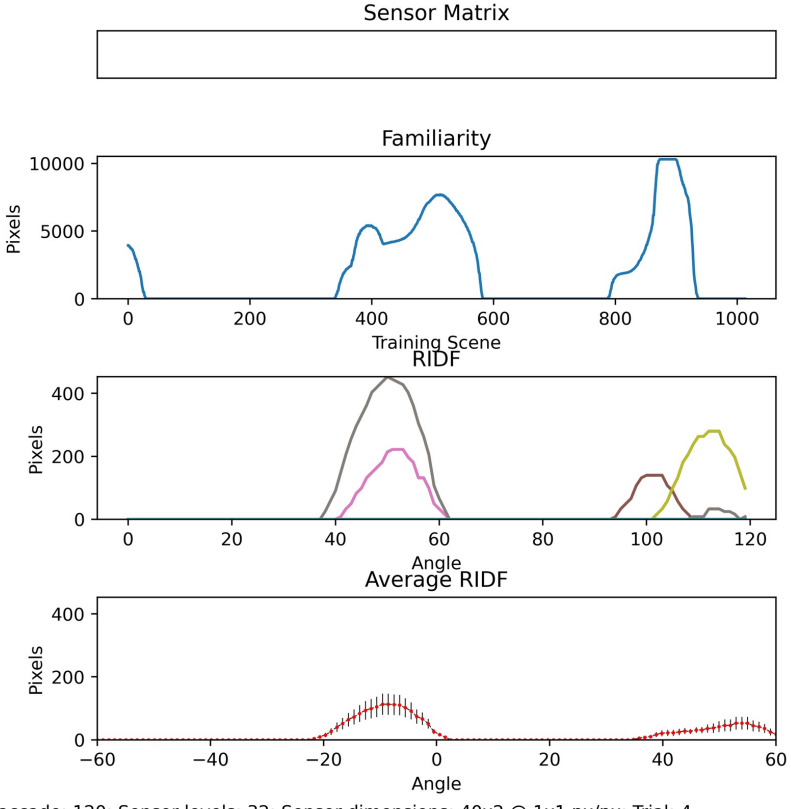

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 397.18; RMSD/dist: 0.993; TD: 2016; p90: 20; p50: 20; complete: 0

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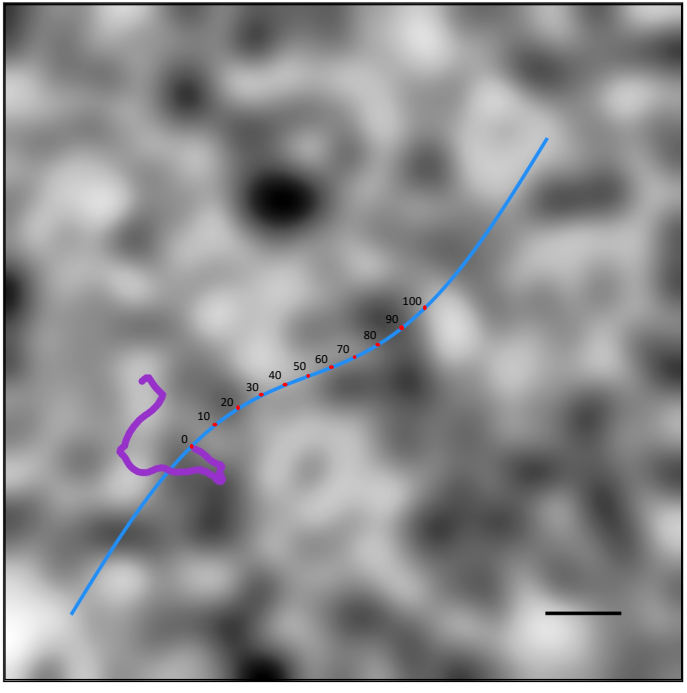

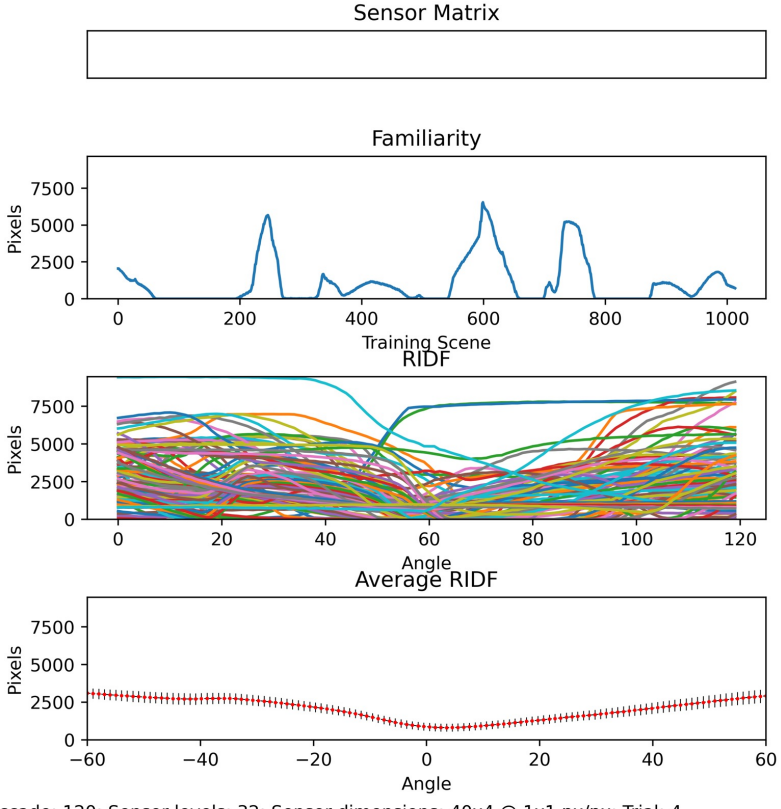

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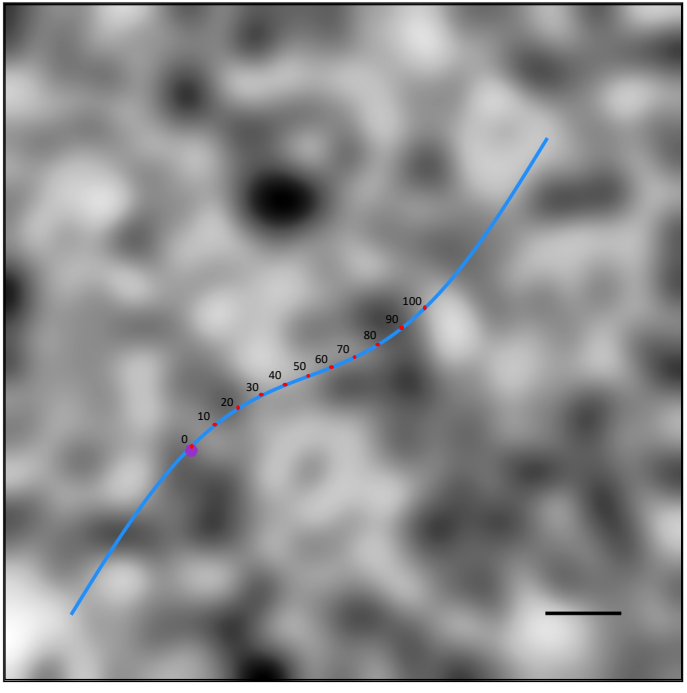

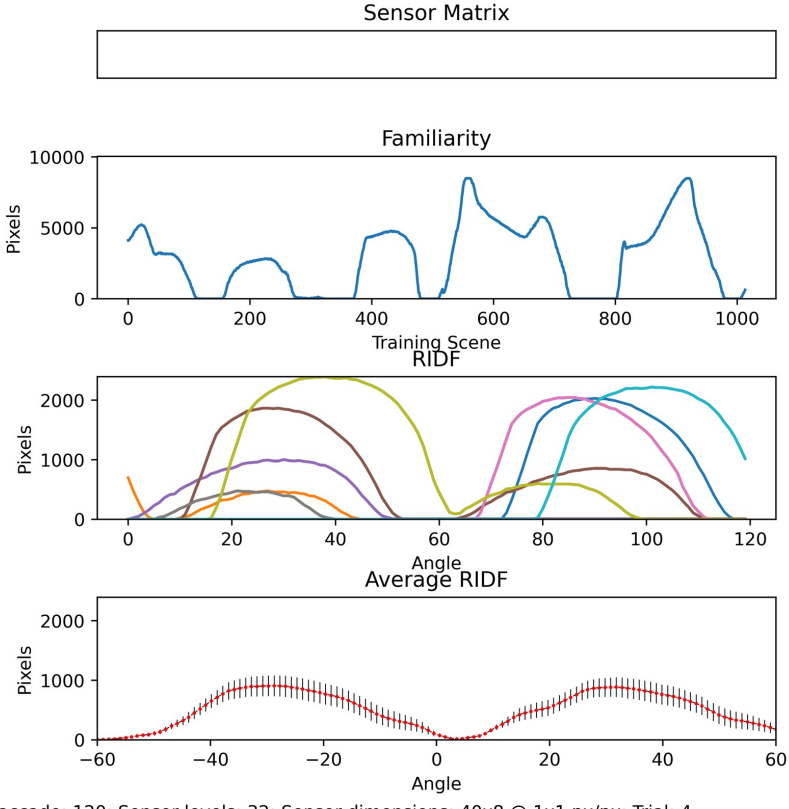

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Navigation stats: RMSD error: 423.01; RMSD/dist: 1.058; TD: 2945; p90: 58; p50: 58; complete: 0

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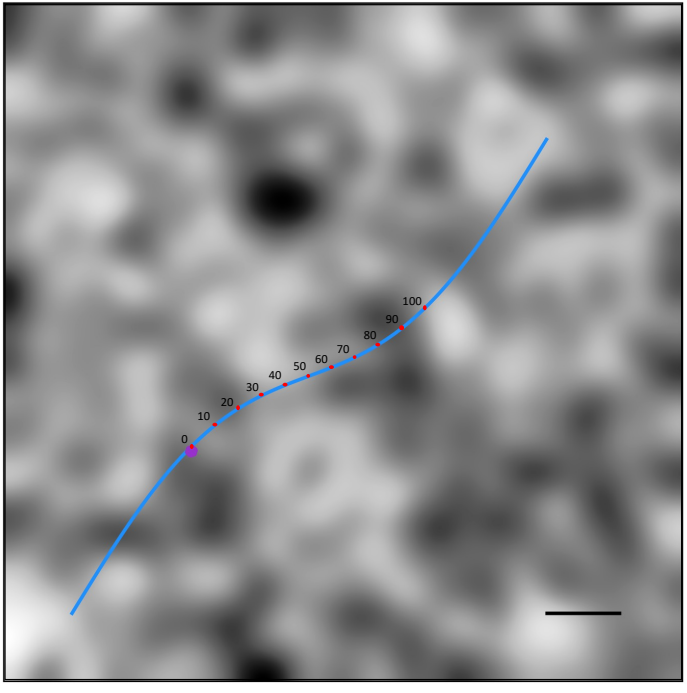

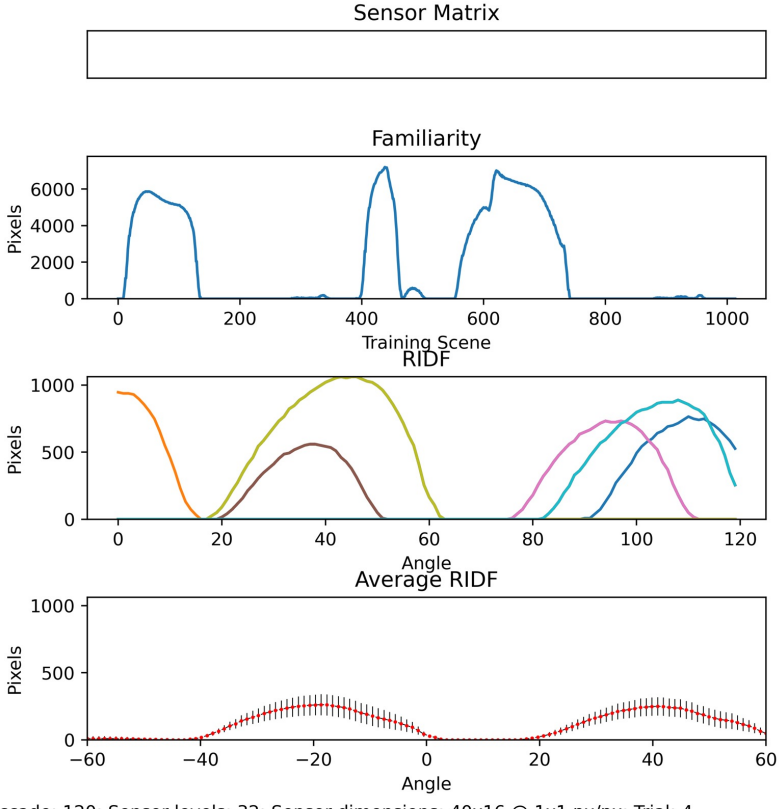

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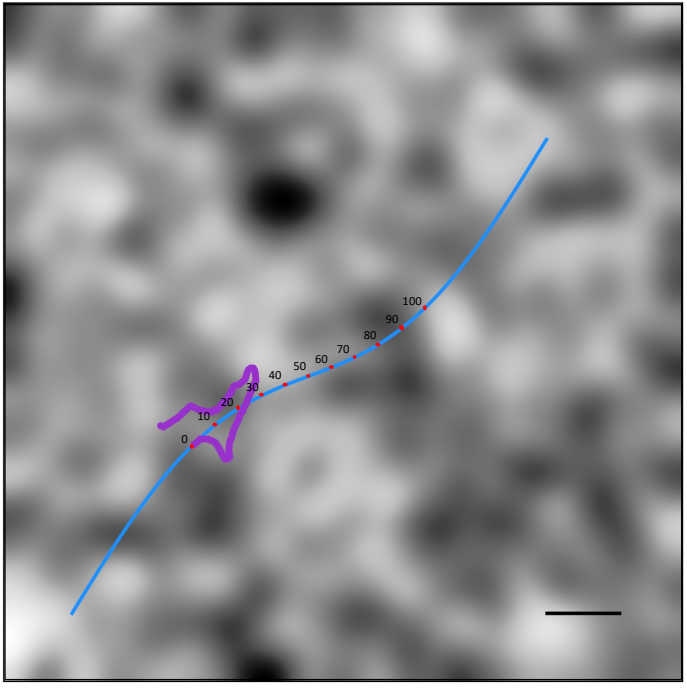

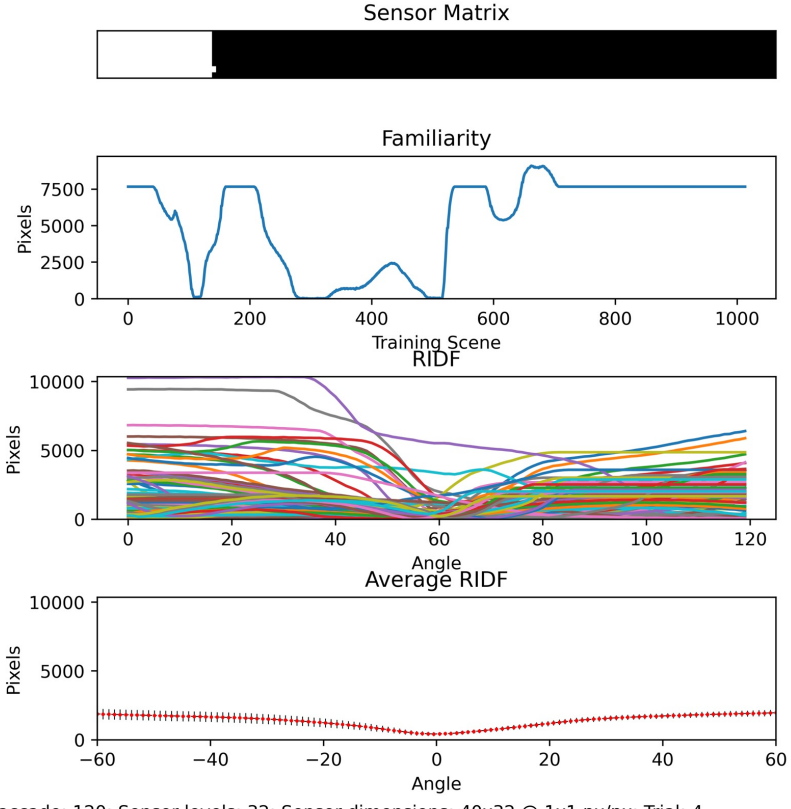

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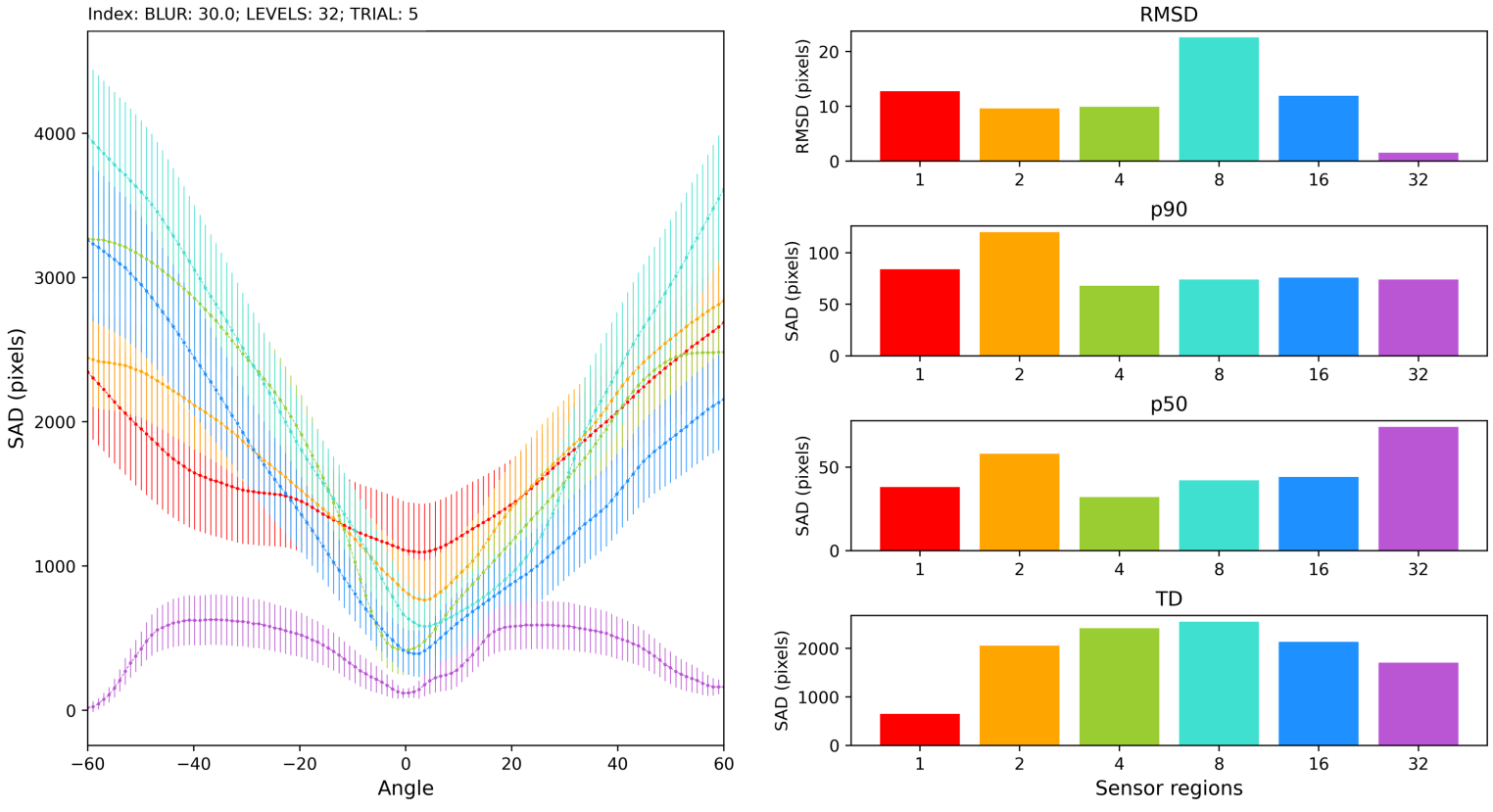
Index: BLUR: 30.0; LEVELS: 32; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

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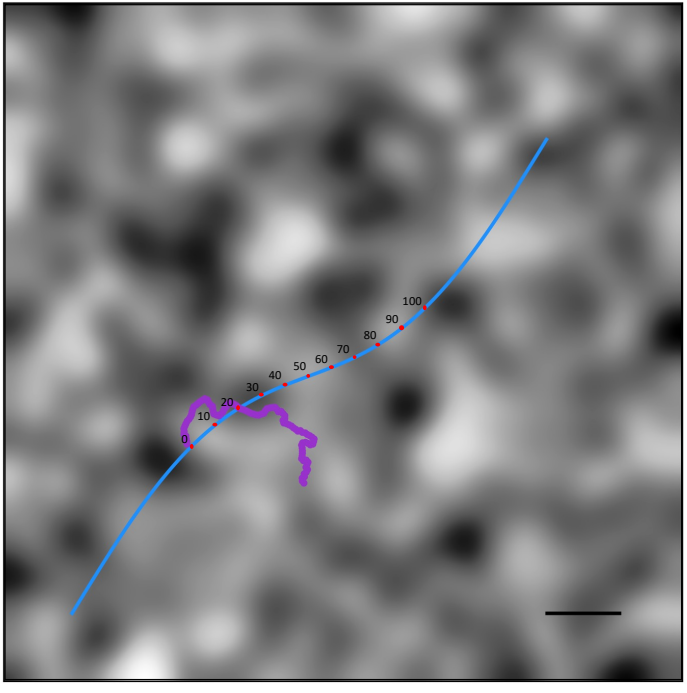

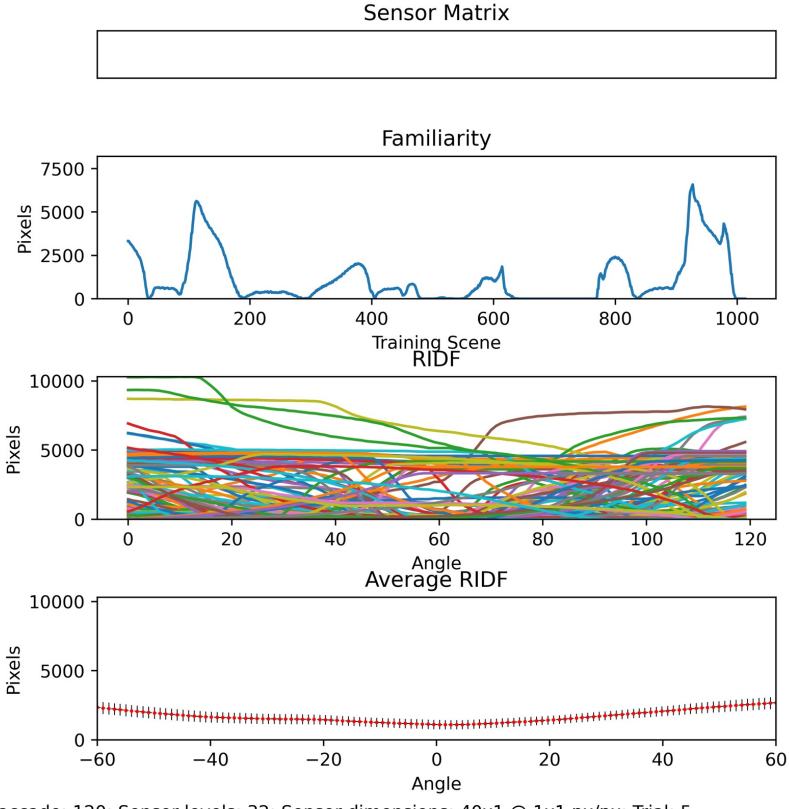

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Navigation stats: RMSD error: 5102.80; RMSD/dist: 12.757; TD: 650; p90: 84; p50: 38; complete: 0

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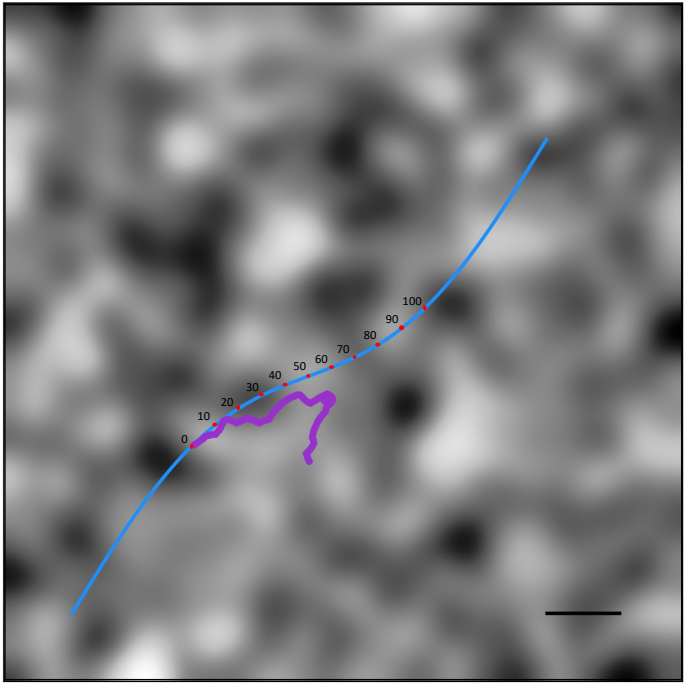

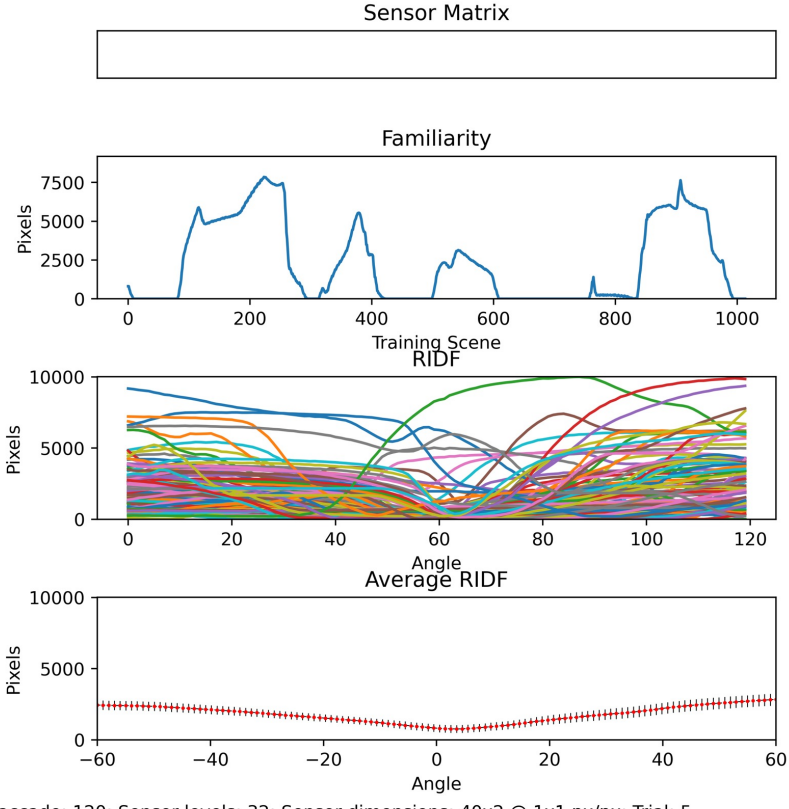

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Navigation stats: RMSD error: 3850.97; RMSD/dist: 9.627; TD: 2055; p90: 120; p50: 58; complete: 0

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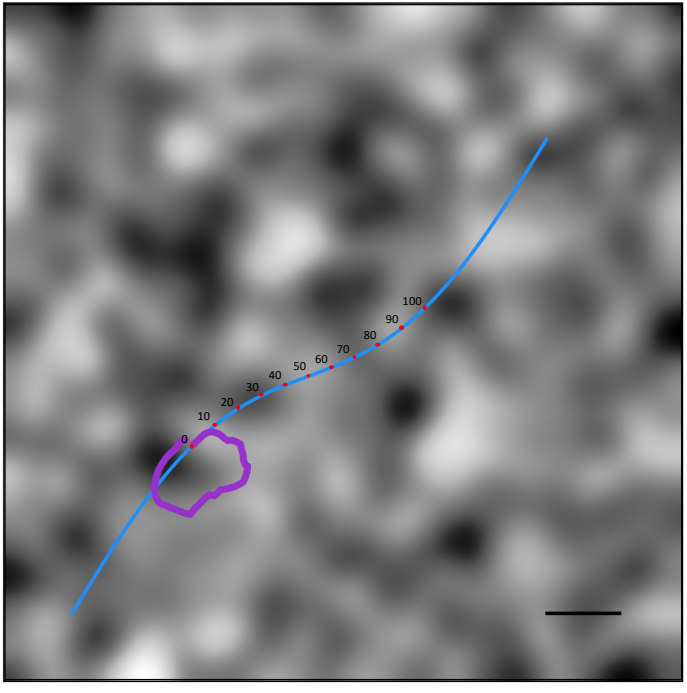

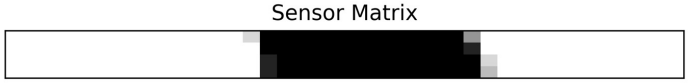

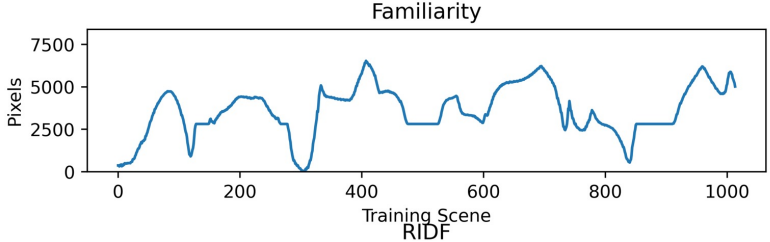

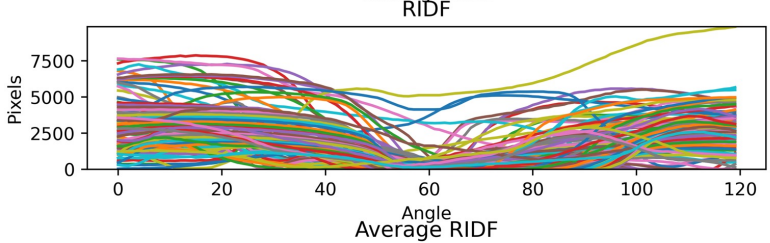

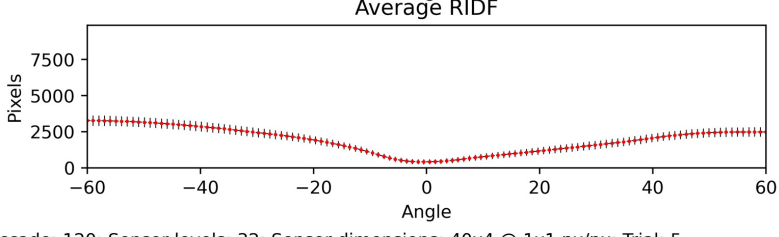

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 3963.86; RMSD/dist: 9.910; TD: 2414; p90: 68; p50: 32; complete: 0

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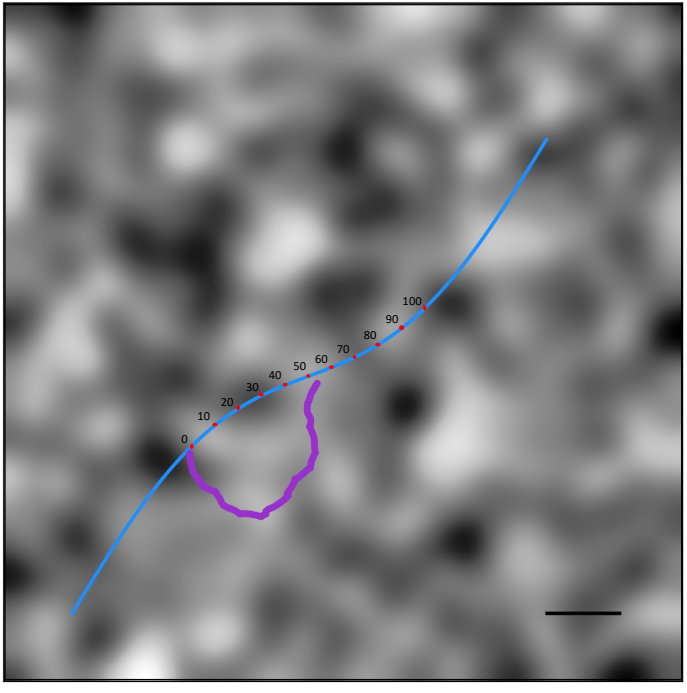

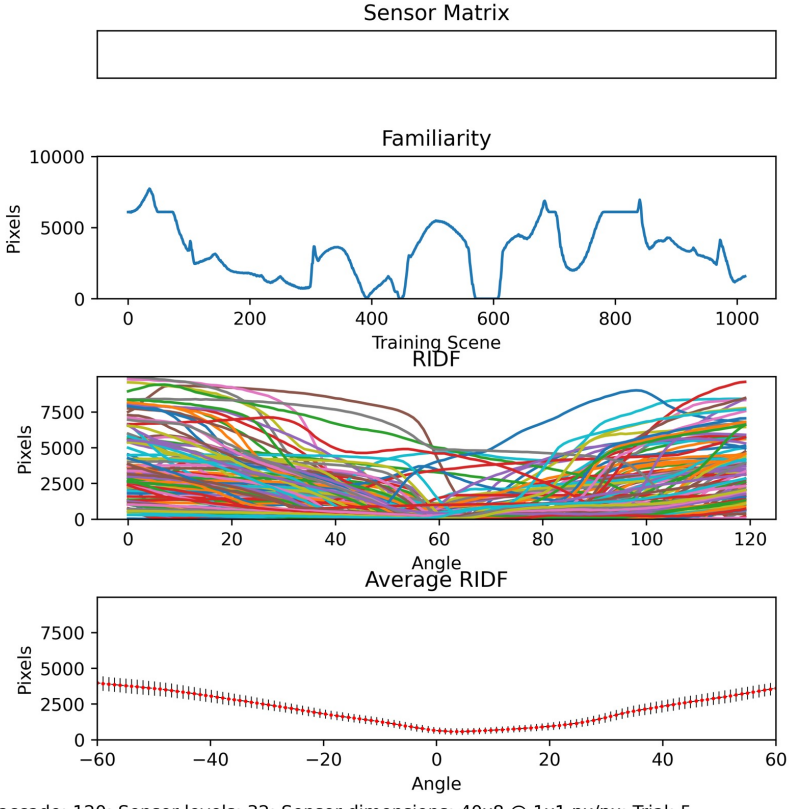

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 9029.15; RMSD/dist: 22.573; TD: 2550; p90: 74; p50: 42; complete: 0

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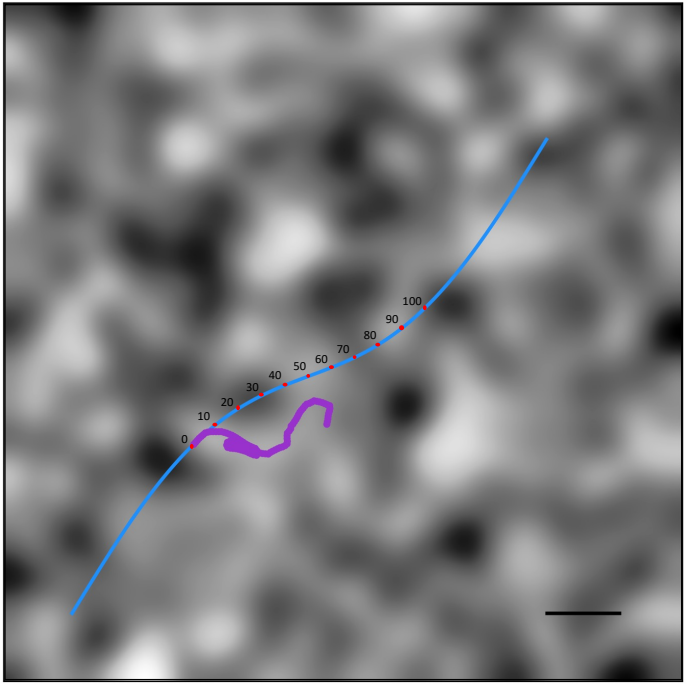

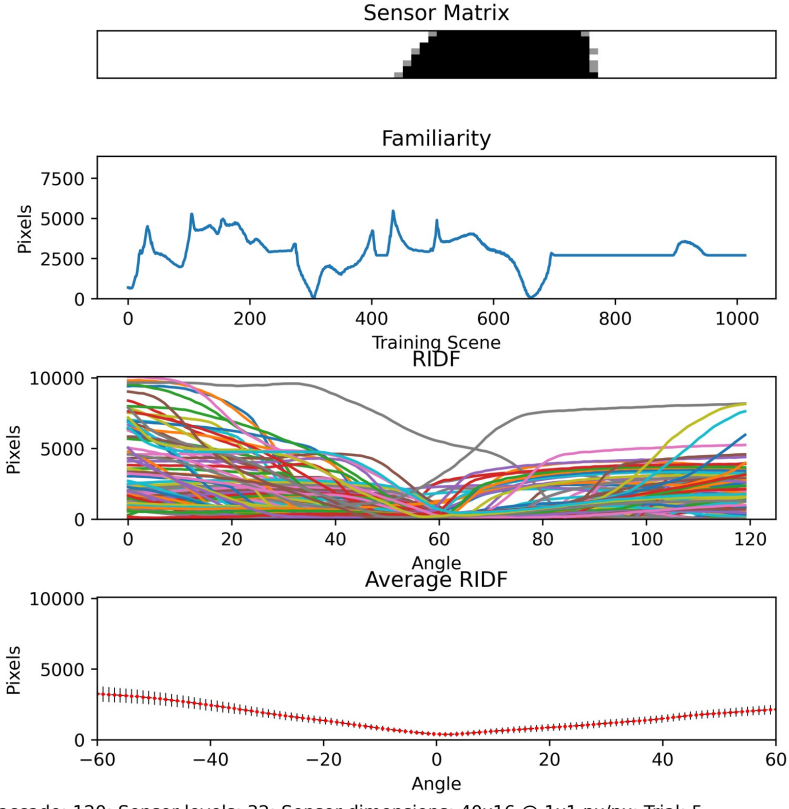

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5
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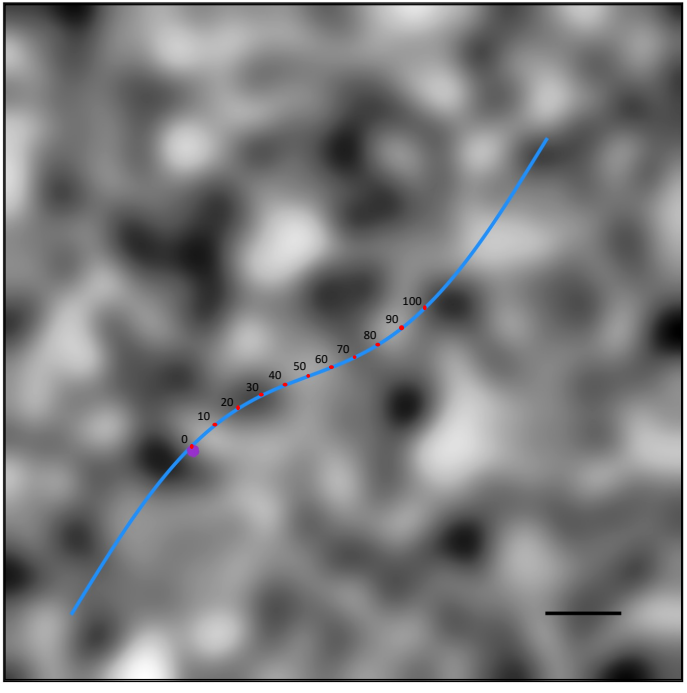

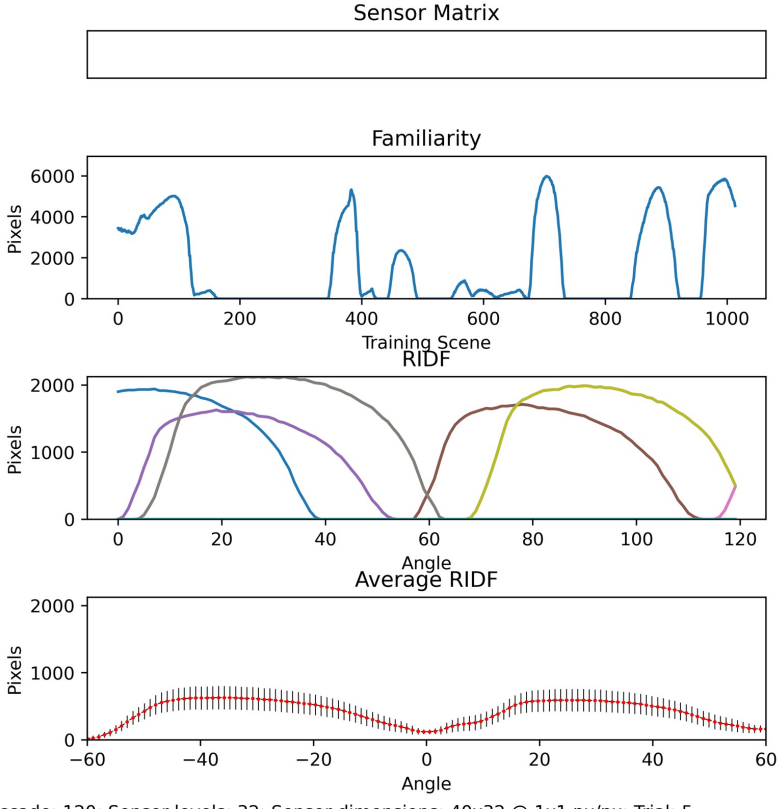

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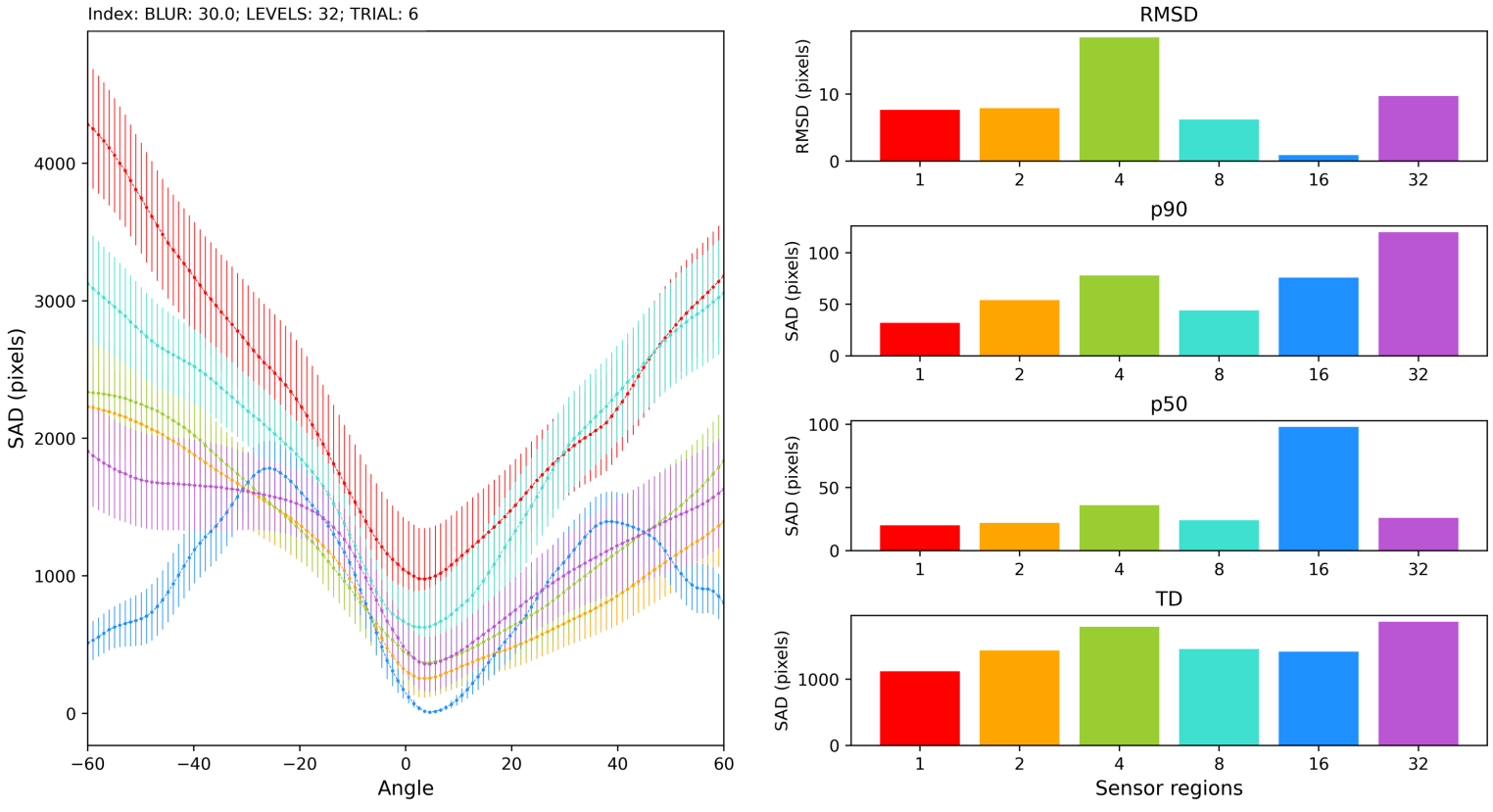
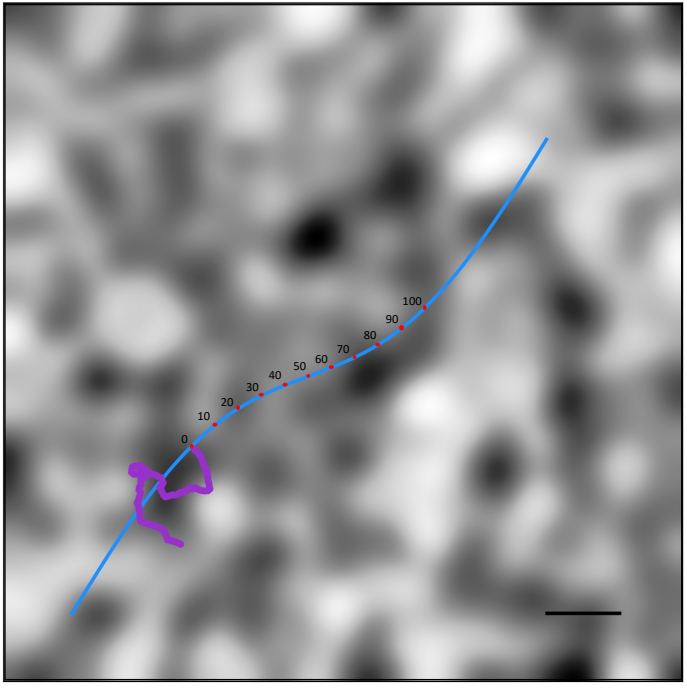
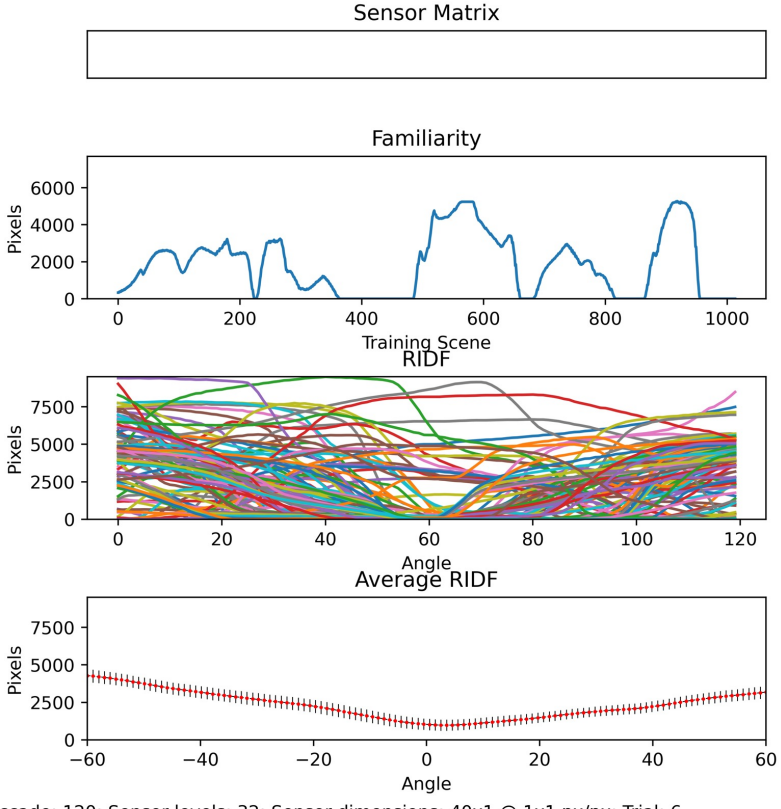

Index: BLUR: 30.0; LEVELS: 32; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3068.42; RMSD/dist: 7.671; TD: 1119; p90: 32; p50: 20; complete: 0

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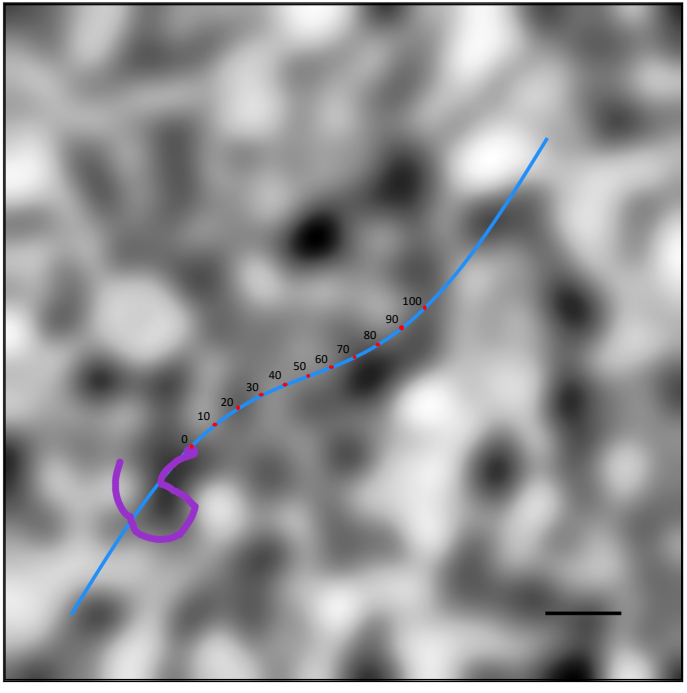

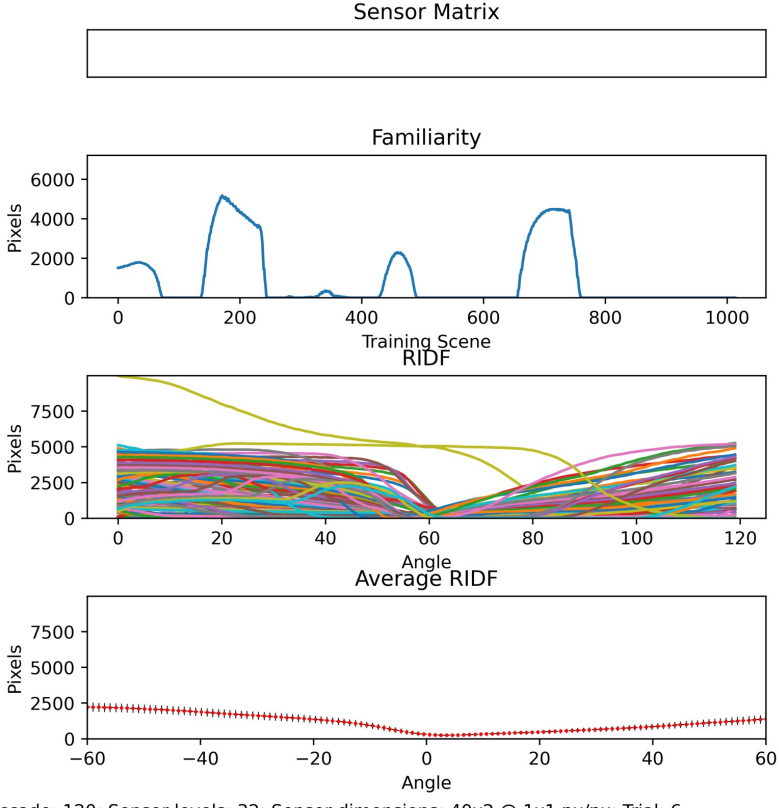

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Navigation stats: RMSD error: 3157.10; RMSD/dist: 7.893; TD: 1435; p90: 54; p50: 22; complete: 0

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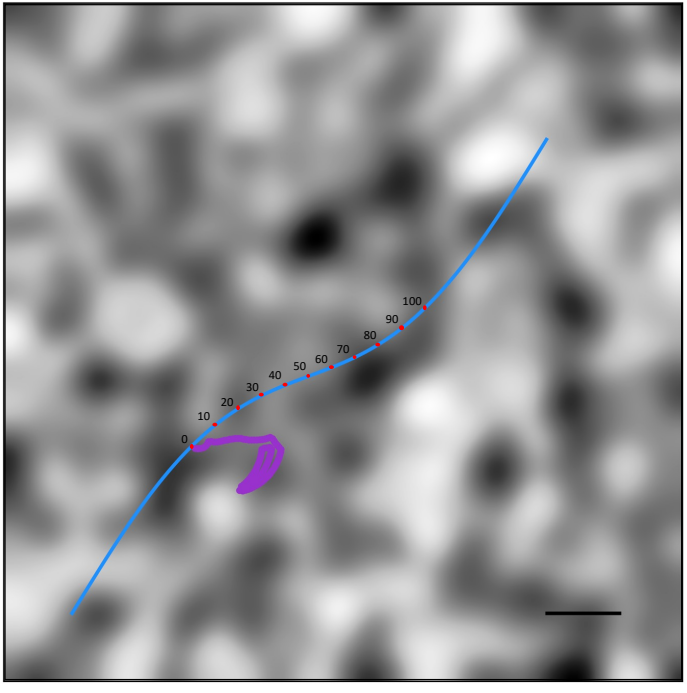

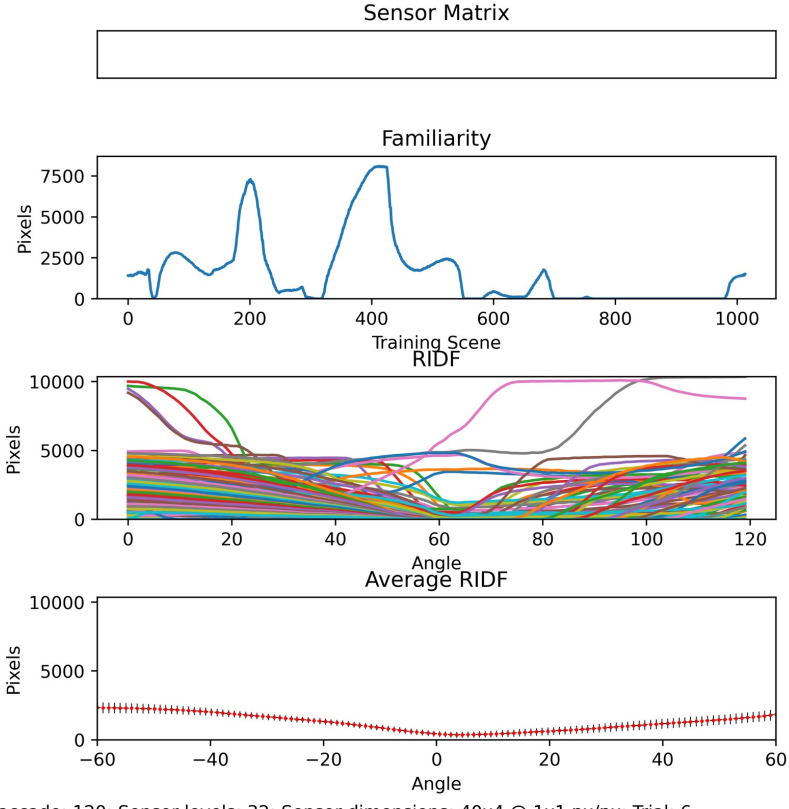

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 7398.57; RMSD/dist: 18.496; TD: 1791; p90: 78; p50: 36; complete: 0

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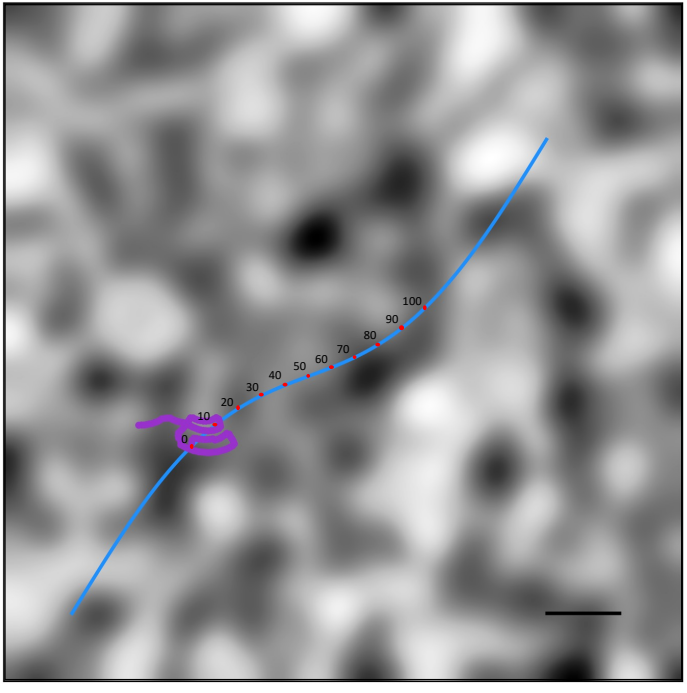

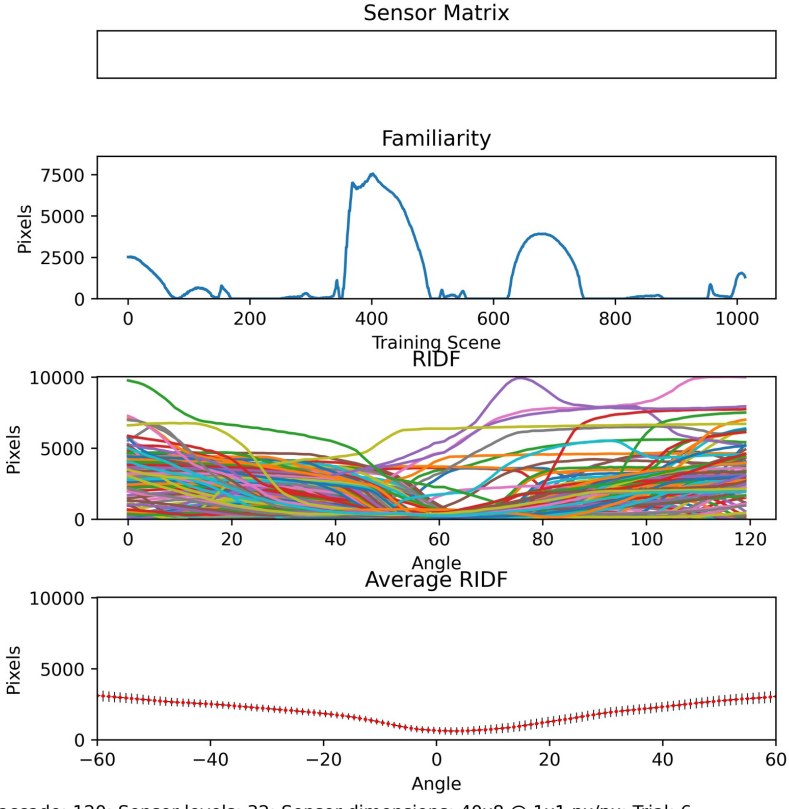

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2483.32; RMSD/dist: 6.208; TD: 1457; p90: 44; p50: 24; complete: 0

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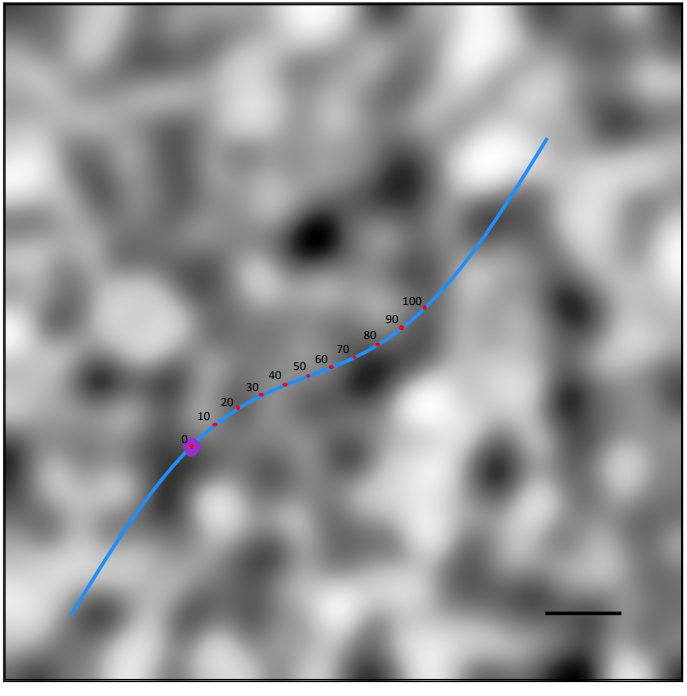
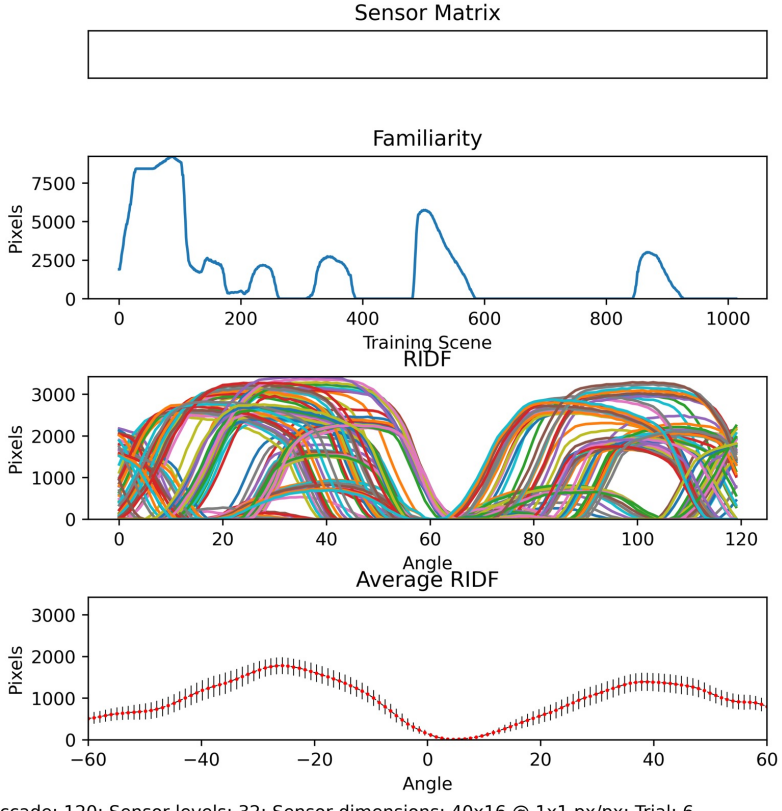
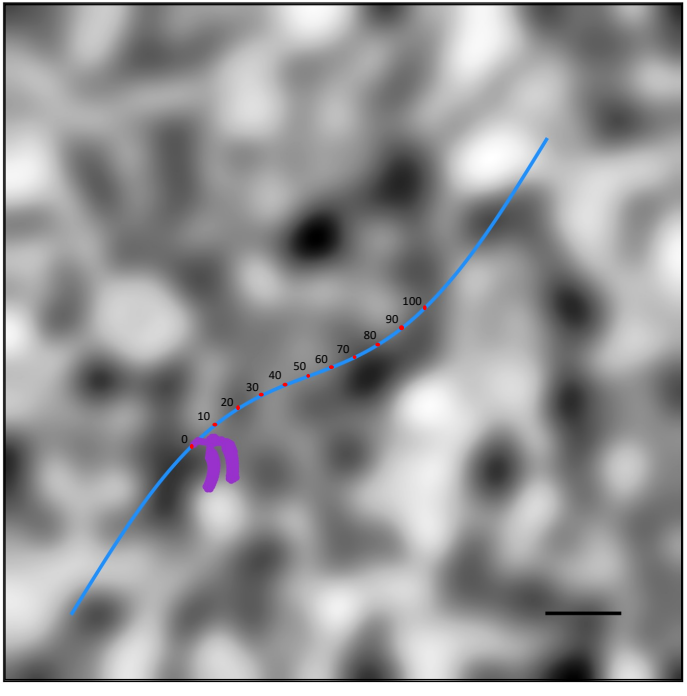
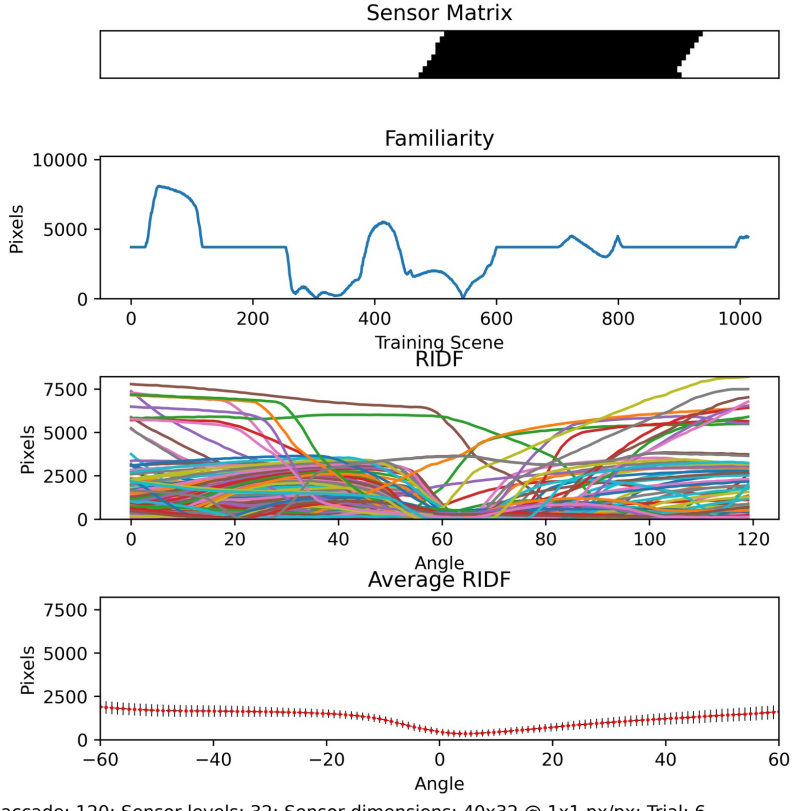




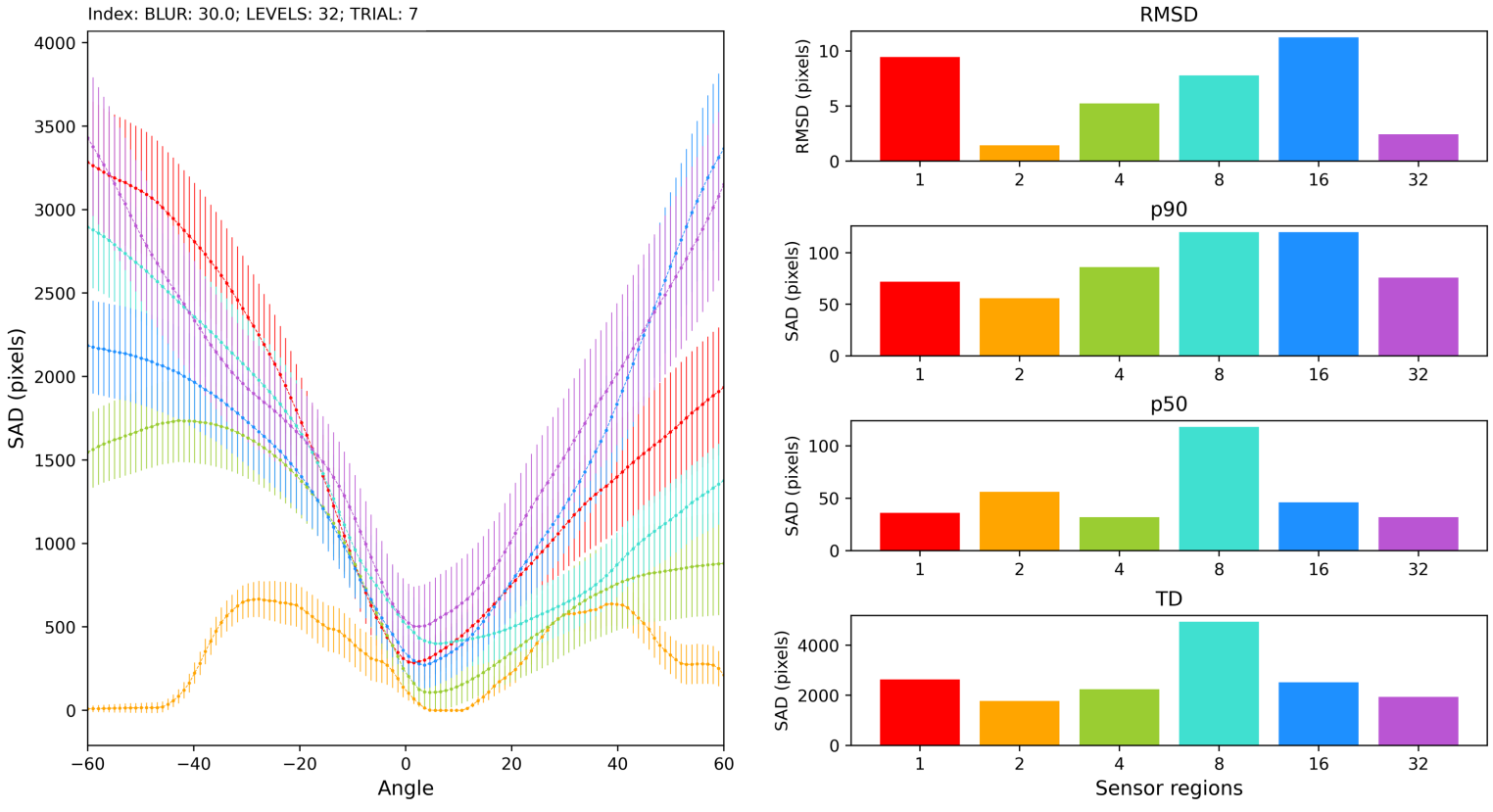
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 360.54; RMSD/dist: 0.901; TD: 1416; p90: 76; p50: 98; complete: 0

0%

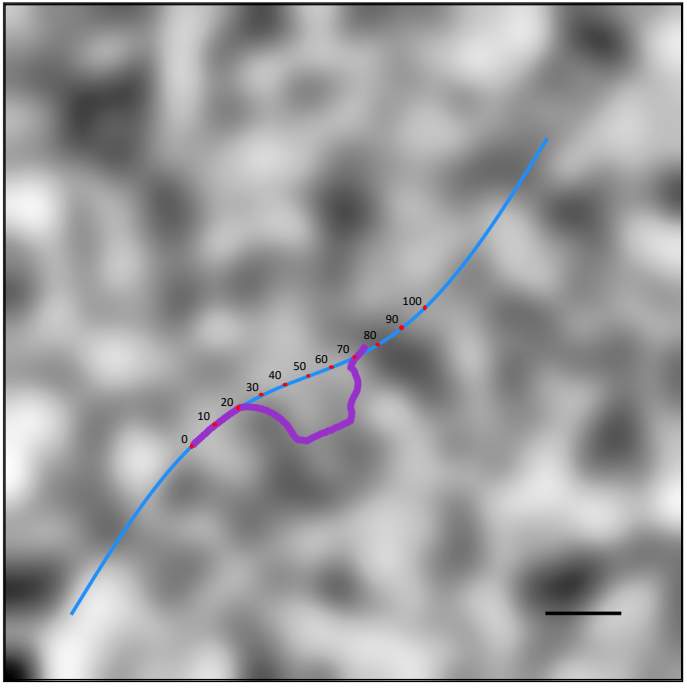


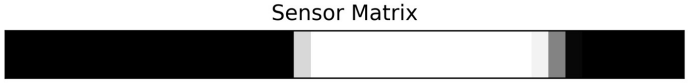


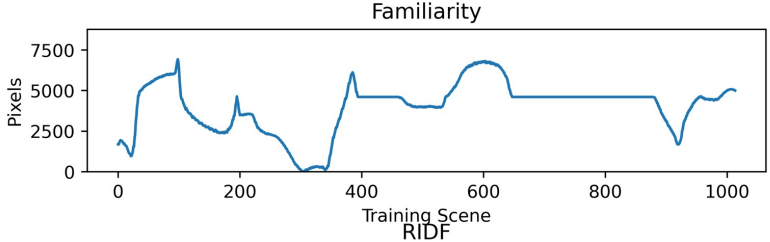
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 3893.44; RMSD/dist: 9.734; TD: 1869; p90: 120; p50: 26; complete: 0

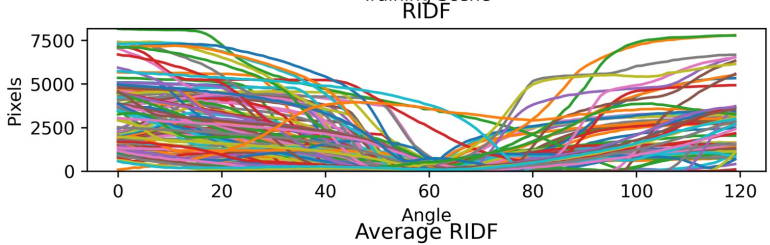

Index: BLUR: 30.0; LEVELS: 32; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

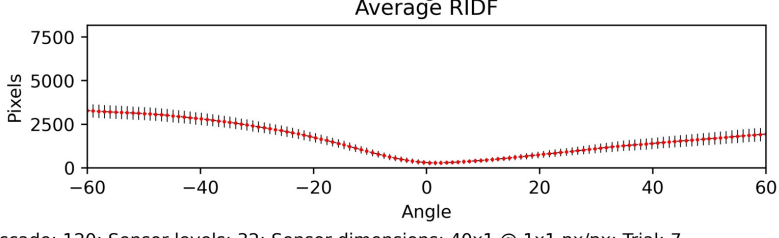
20%







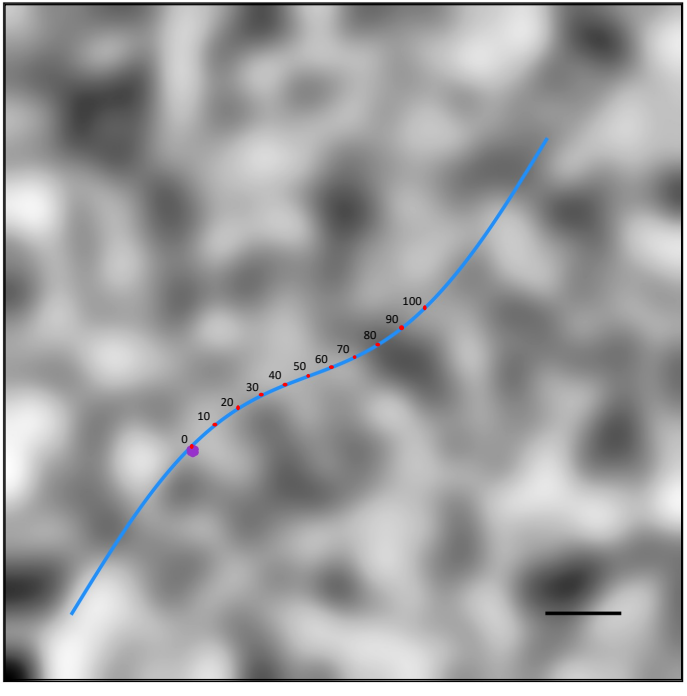


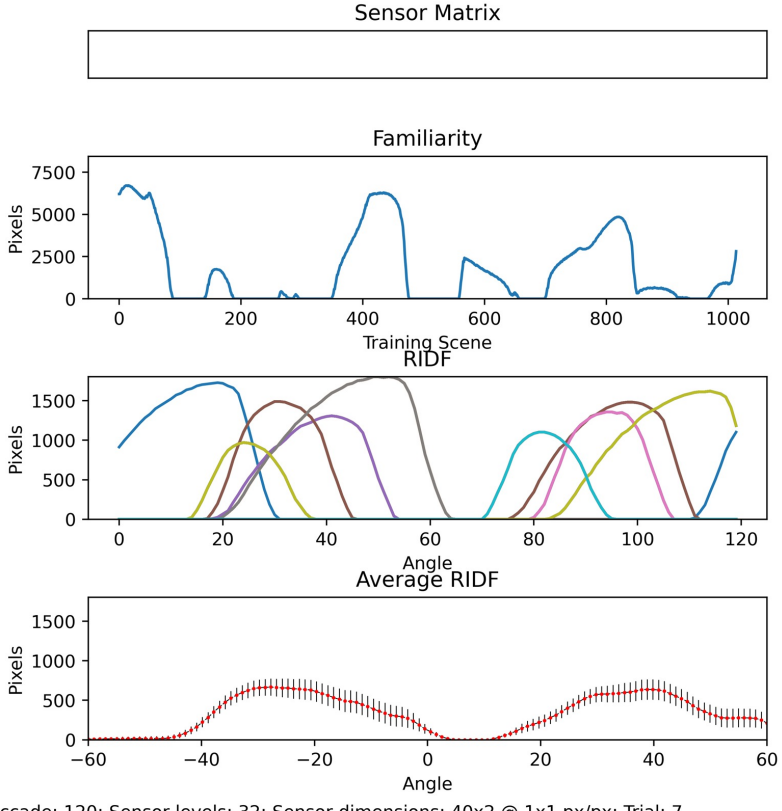


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3778.09; RMSD/dist: 9.445; TD: 2639; p90: 72; p50: 36; complete: 0

0%

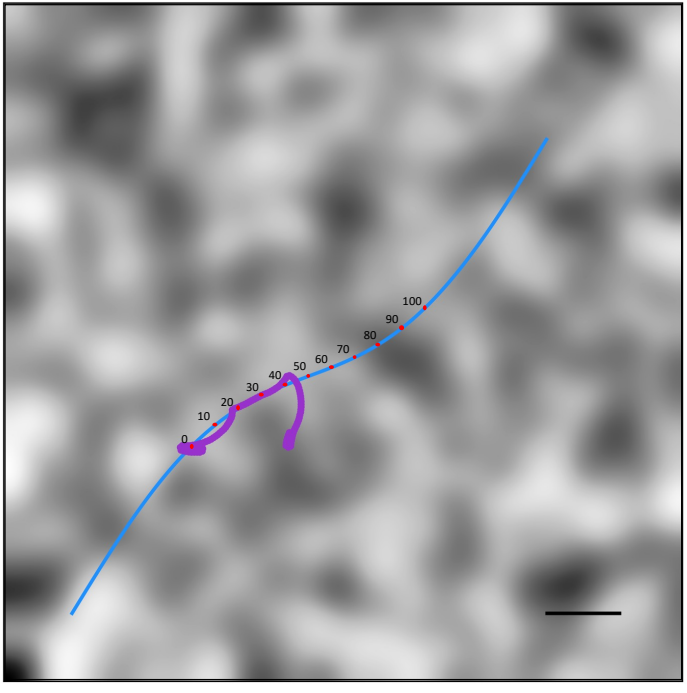


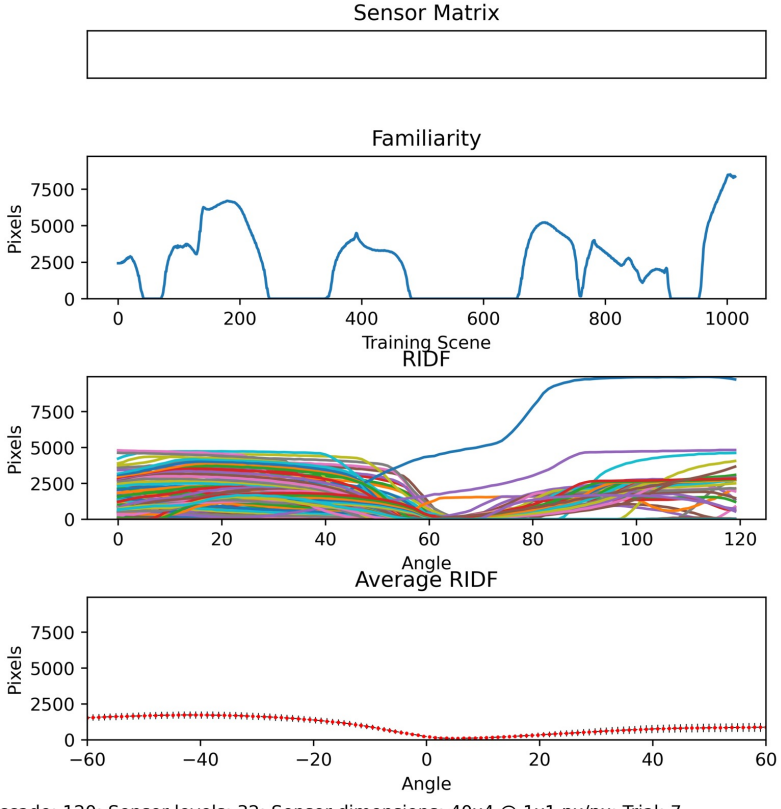


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 576.97; RMSD/dist: 1.442; TD: 1772; p90: 56; p50: 56; complete: 0

20%

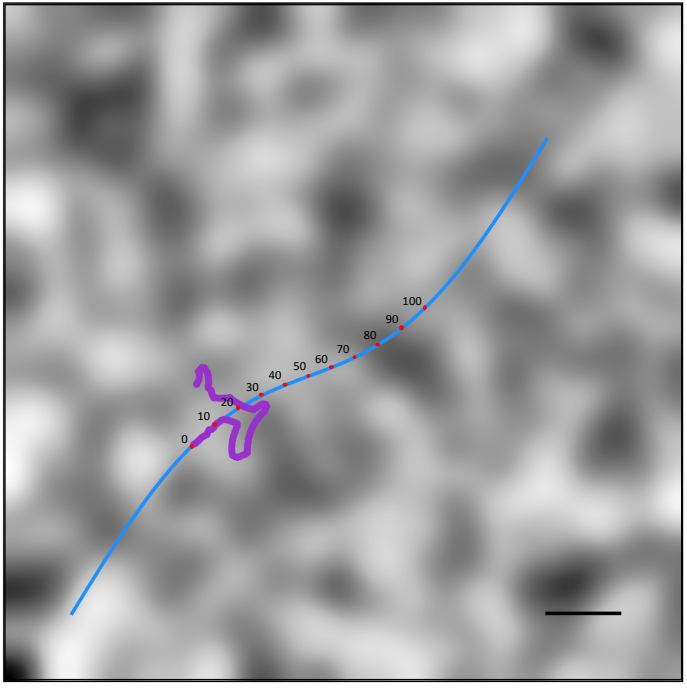


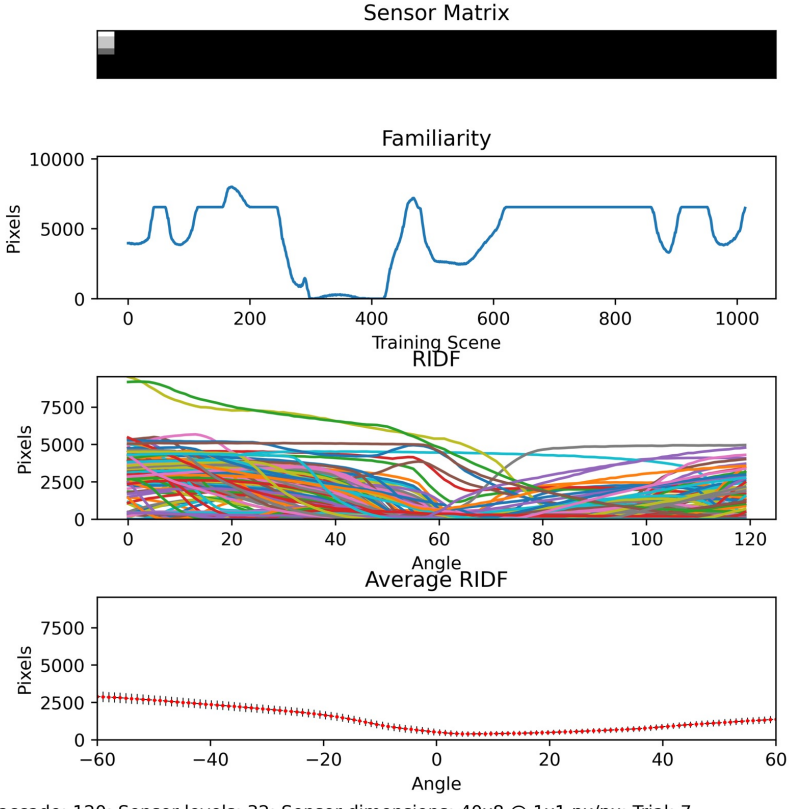


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2096.68; RMSD/dist: 5.242; TD: 2239; p90: 86; p50: 32; complete: 0

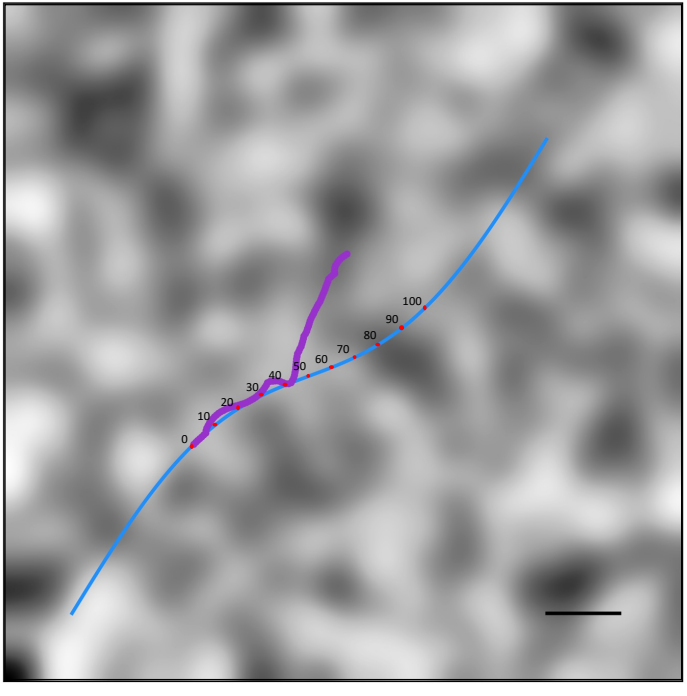
10%

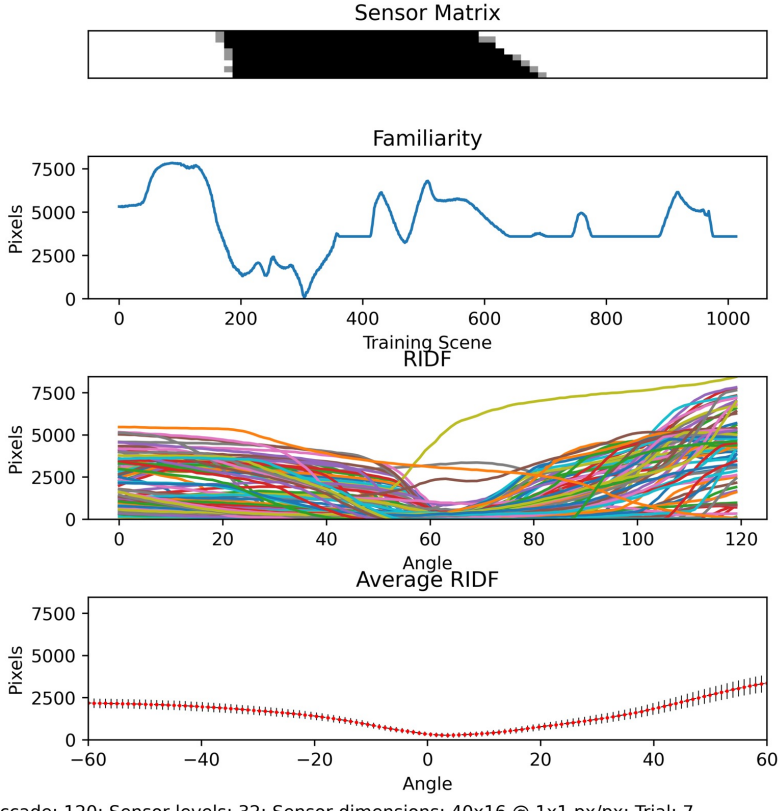




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 3110.01; RMSD/dist: 7.775; TD: 4942; p90: 120; p50: 118; complete: 0

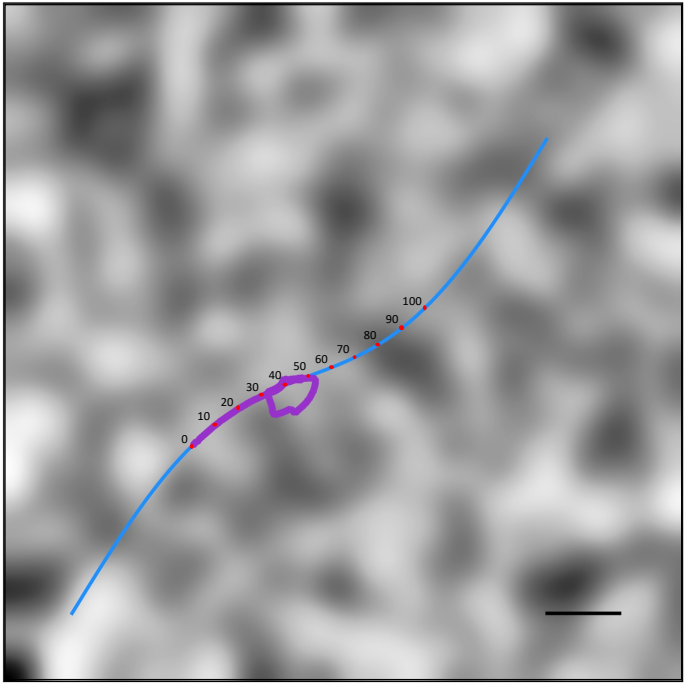
10%

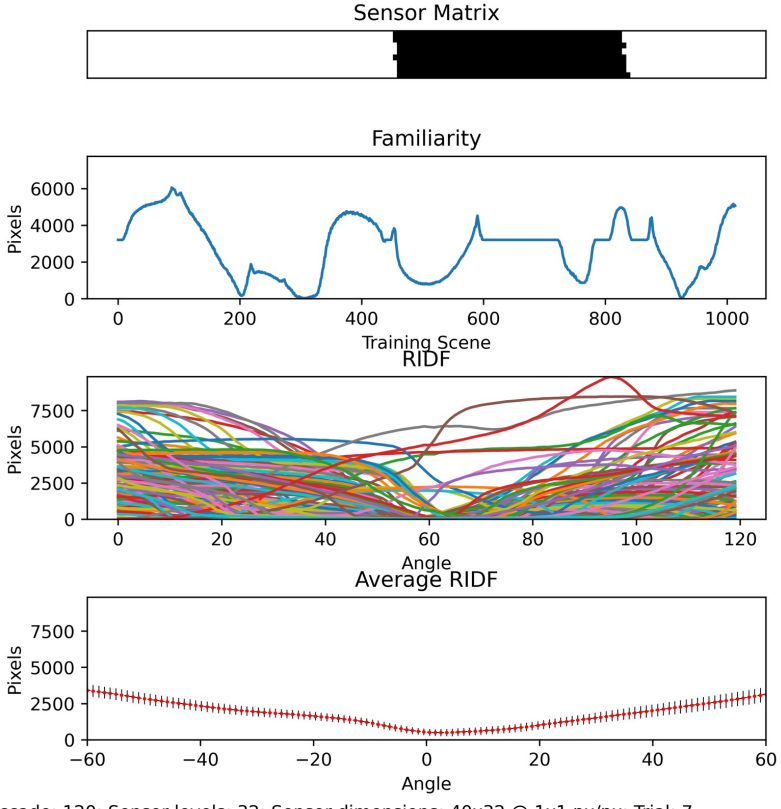




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 4491.73; RMSD/dist: 11.229; TD: 2524; p90: 120; p50: 46; complete: 0

40%





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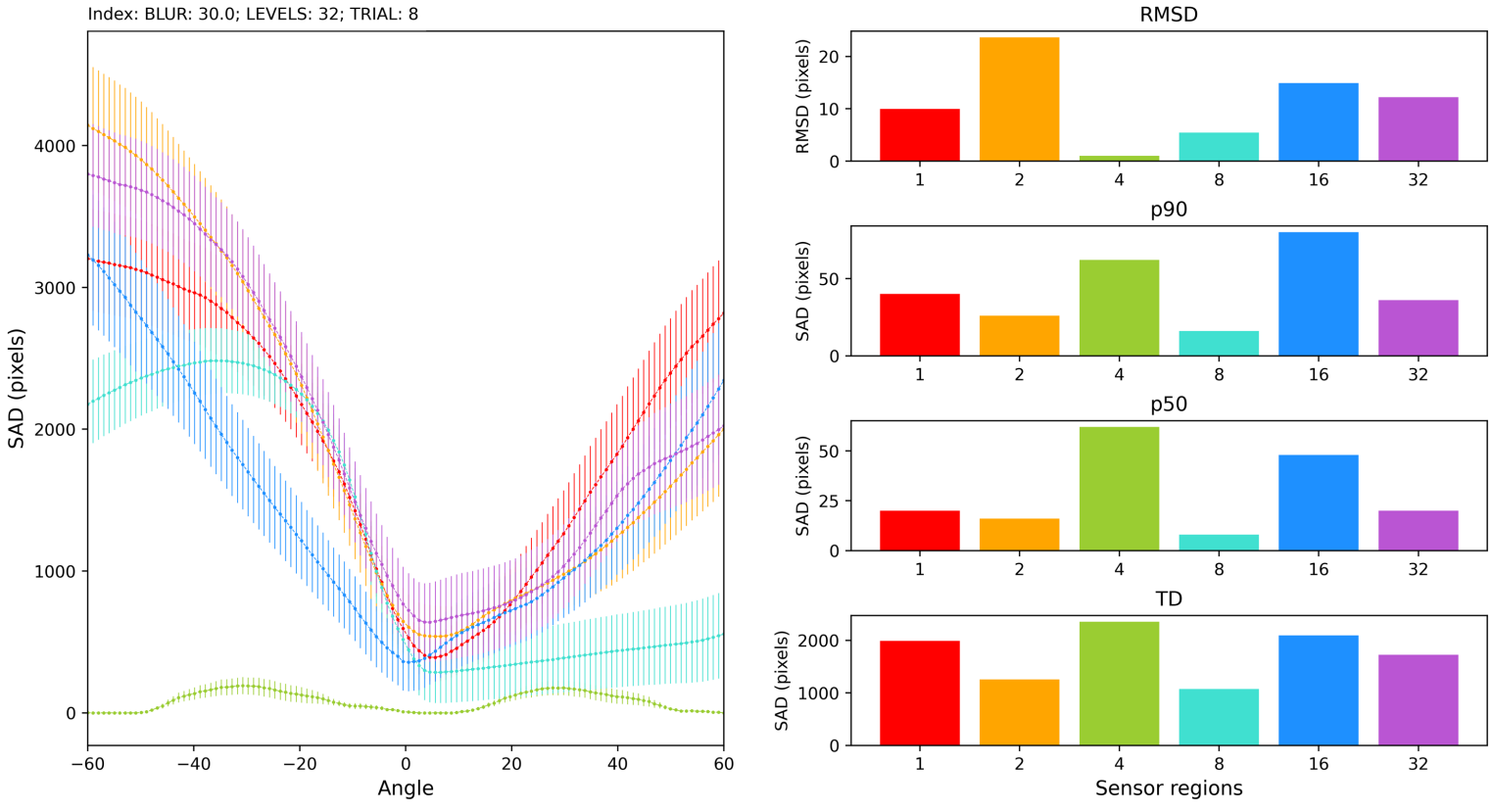
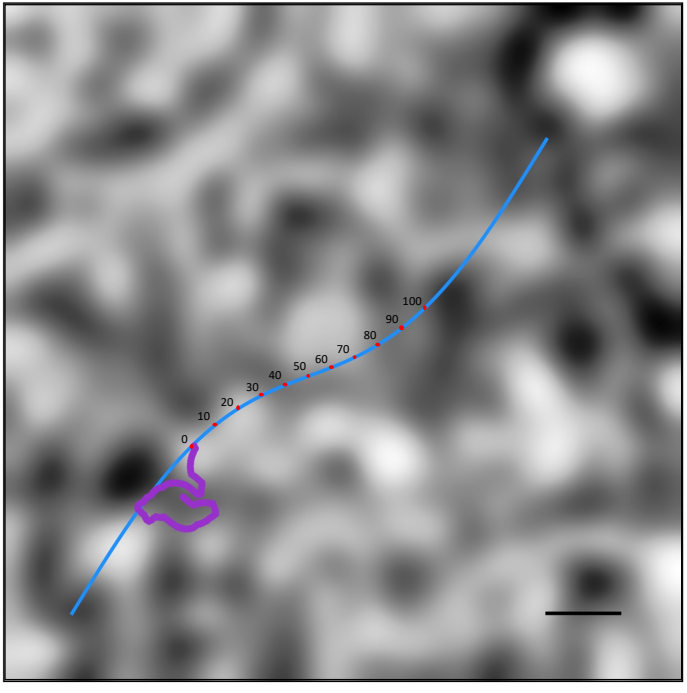
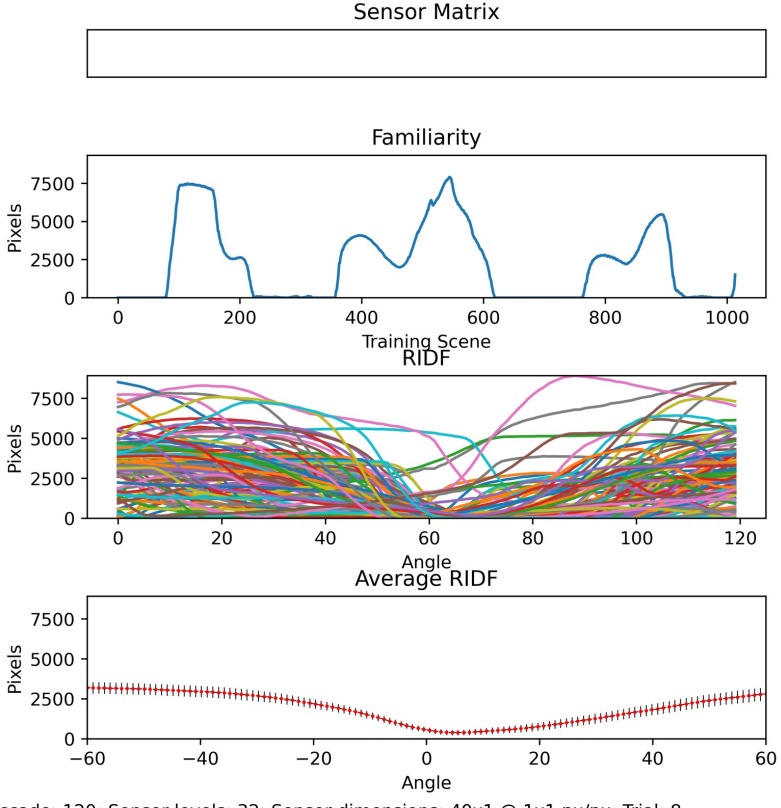

Index: BLUR: 30.0; LEVELS: 32; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

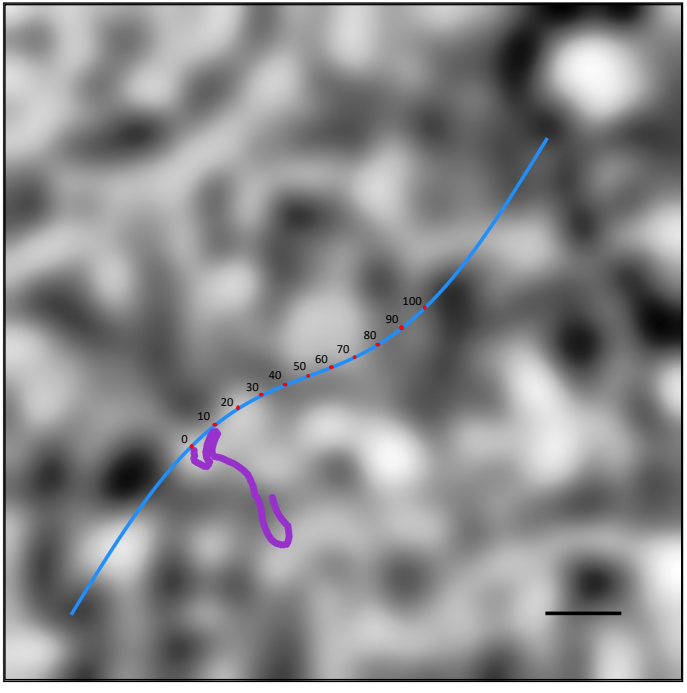


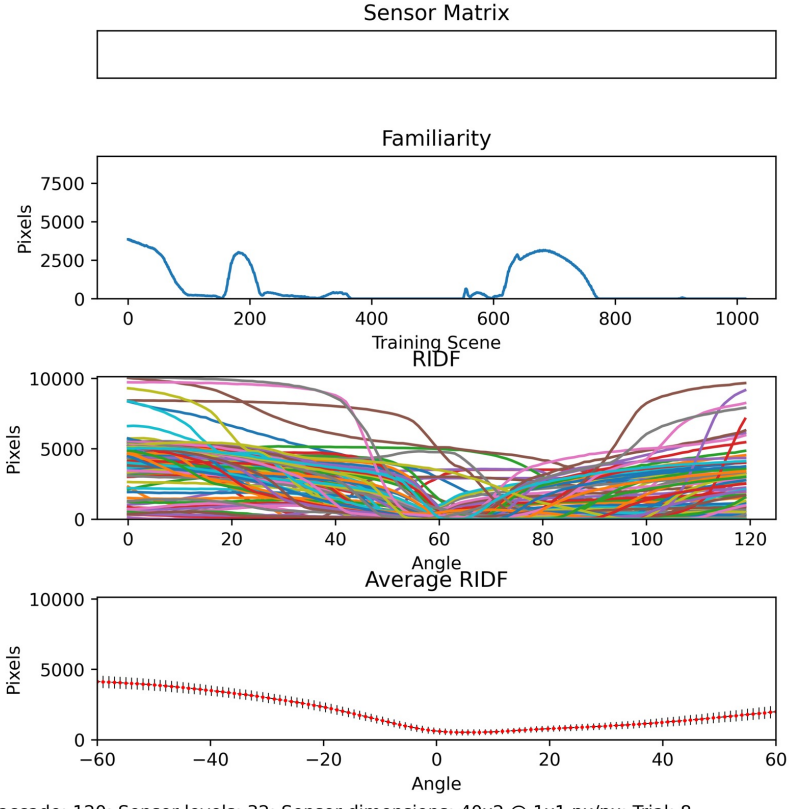


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3980.39; RMSD/dist: 9.951; TD: 1987; p90: 40; p50: 20; complete: 0

0%

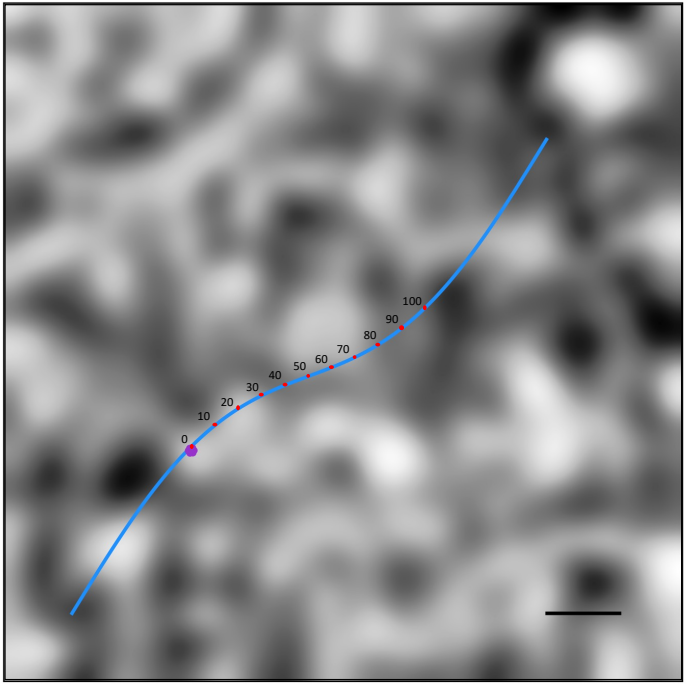


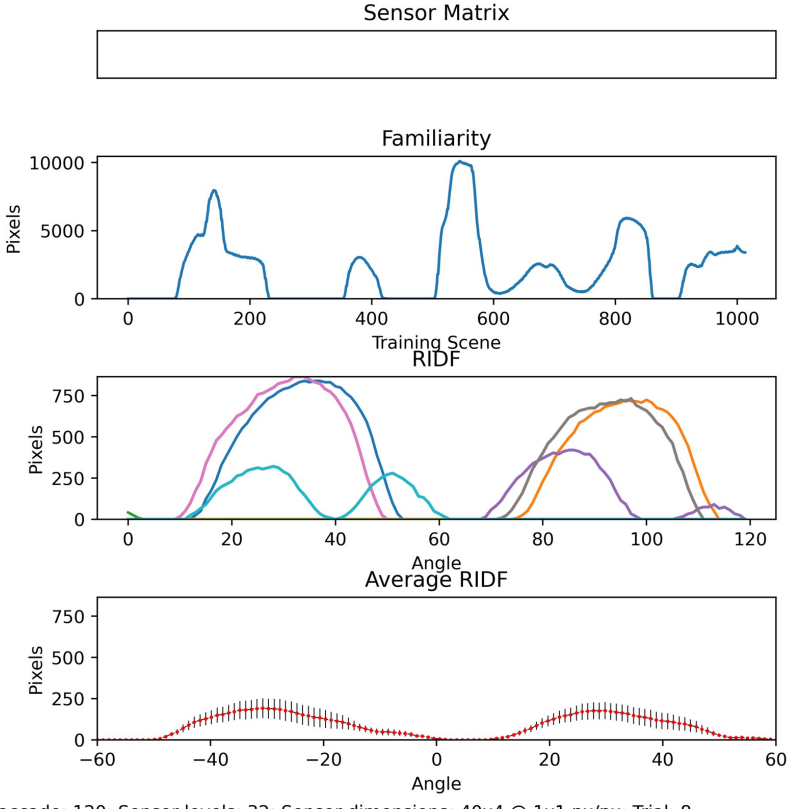


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 9453.29; RMSD/dist: 23.633; TD: 1255; p90: 26; p50: 16; complete: 0

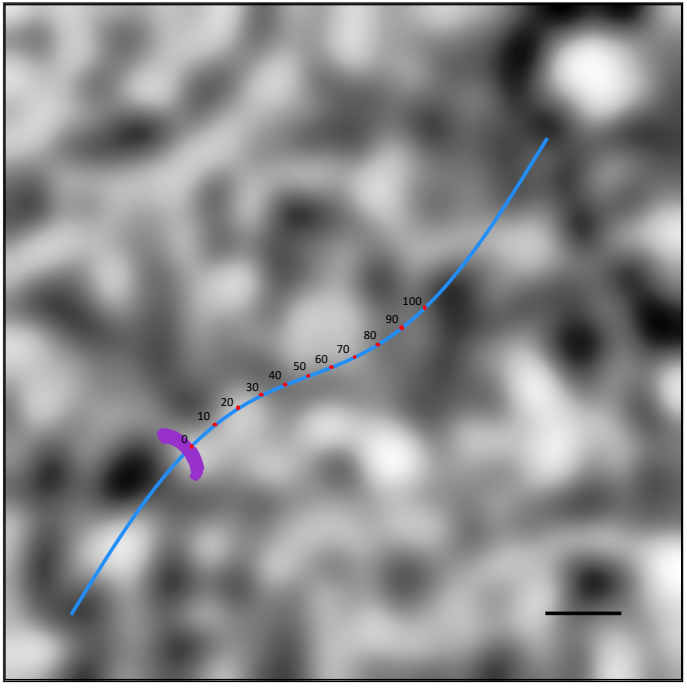
0%

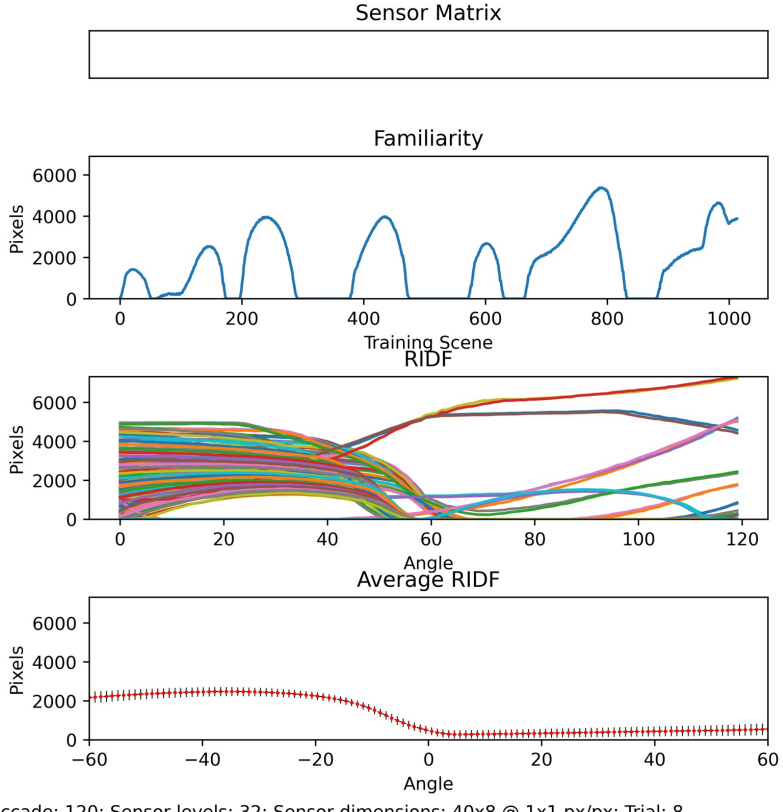




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 395.30; RMSD/dist: 0.988; TD: 2354; p90: 62; p50: 62; complete: 0

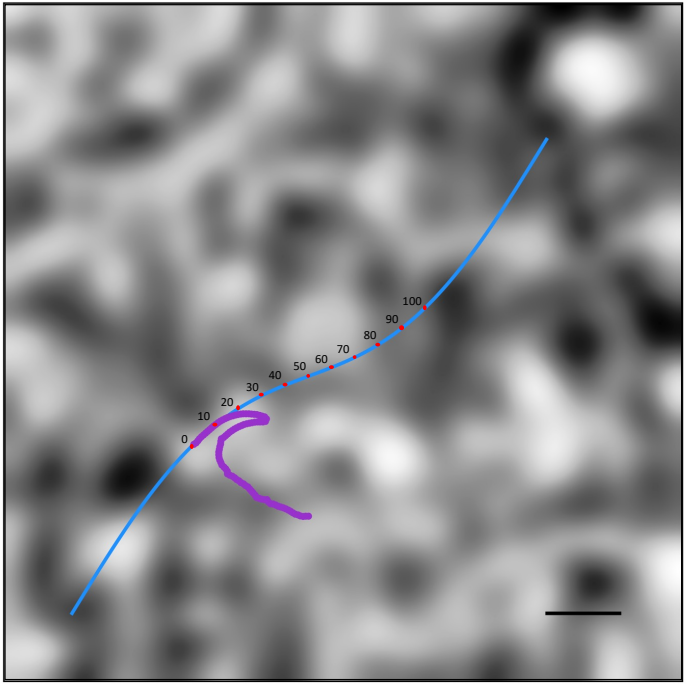
0%

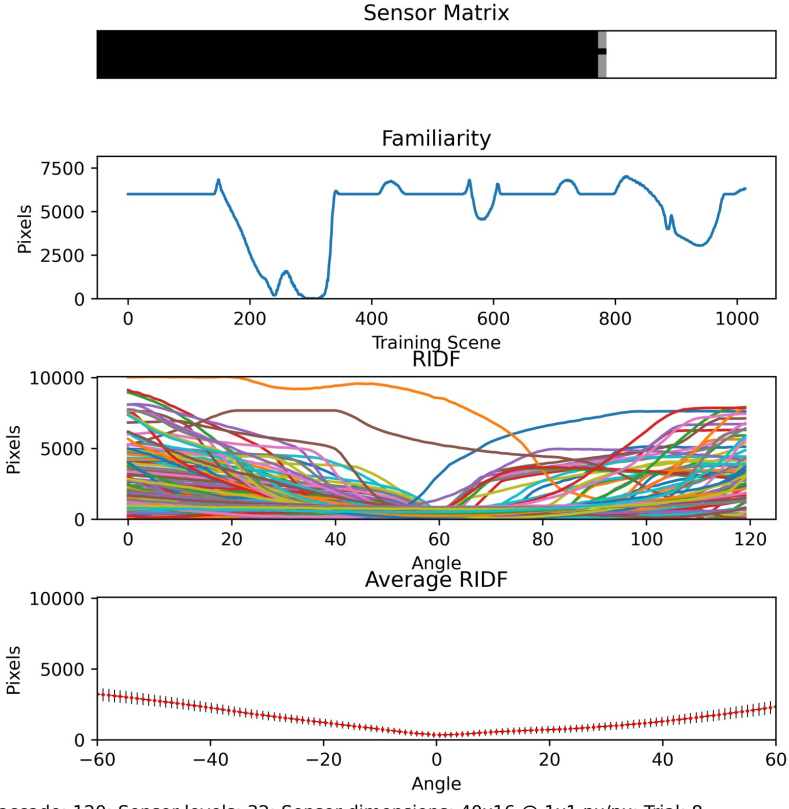




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 2176.18; RMSD/dist: 5.440; TD: 1075; p90: 16; p50: 8; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8
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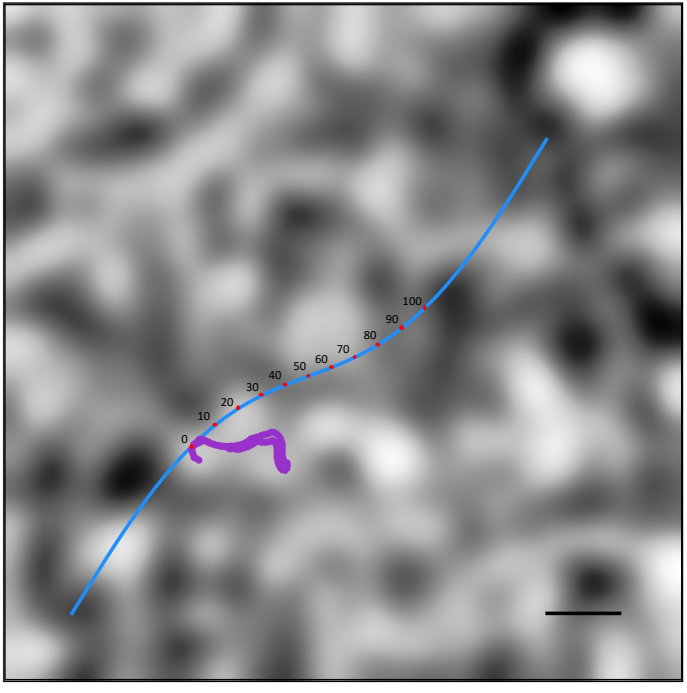
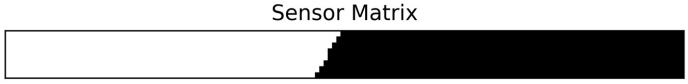
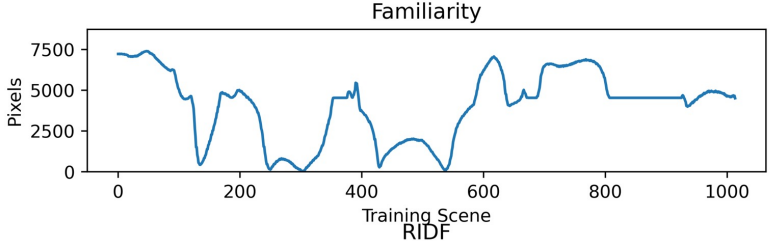
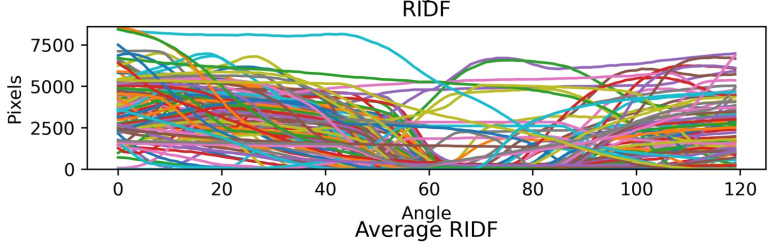
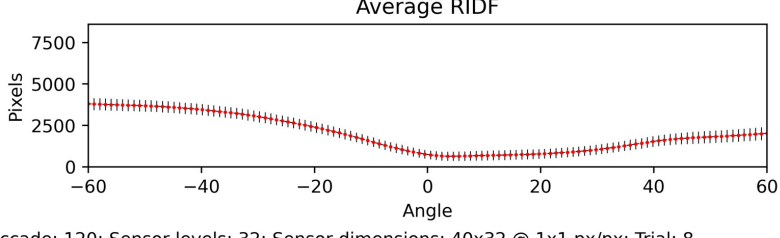
0%



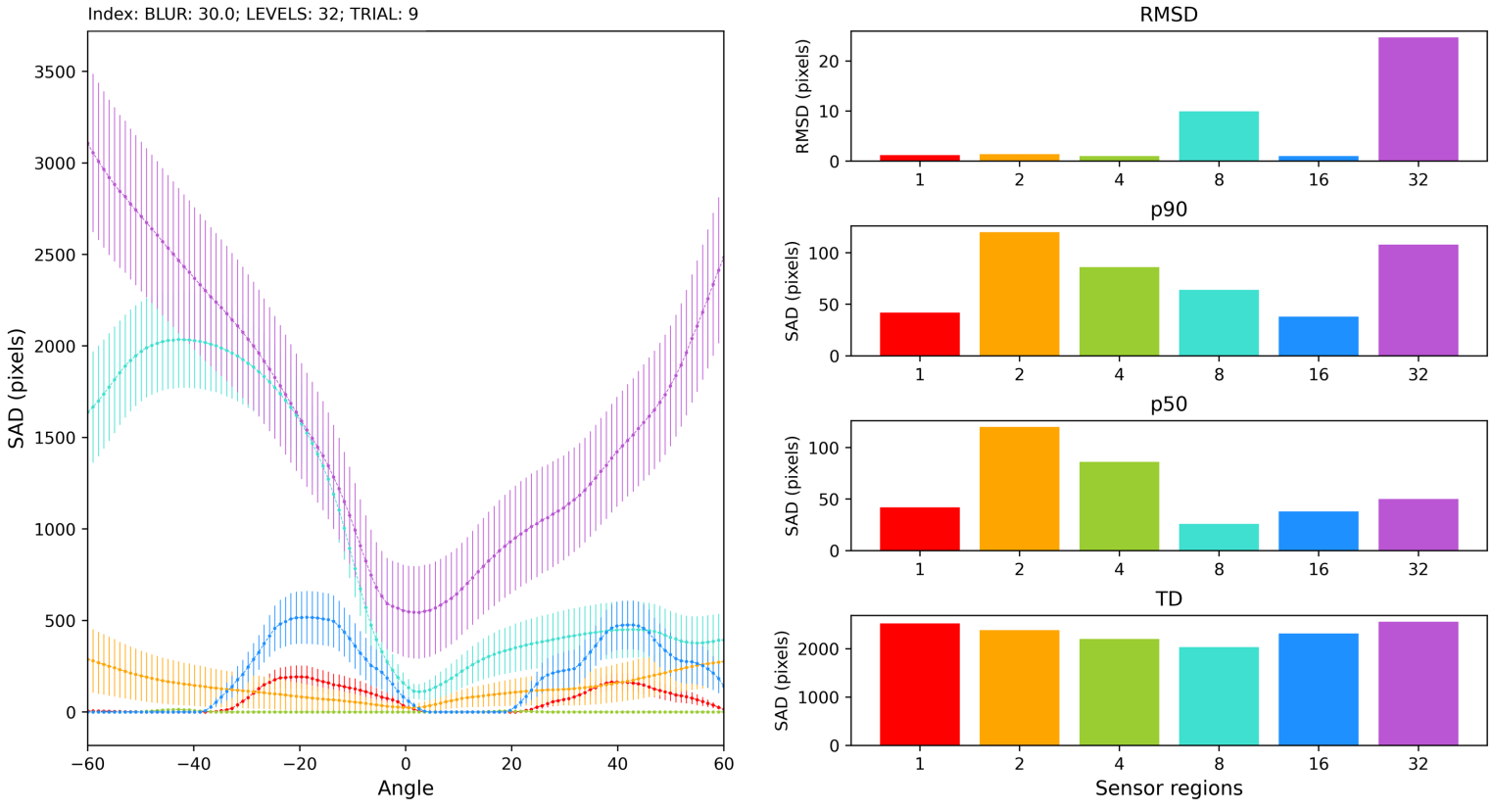




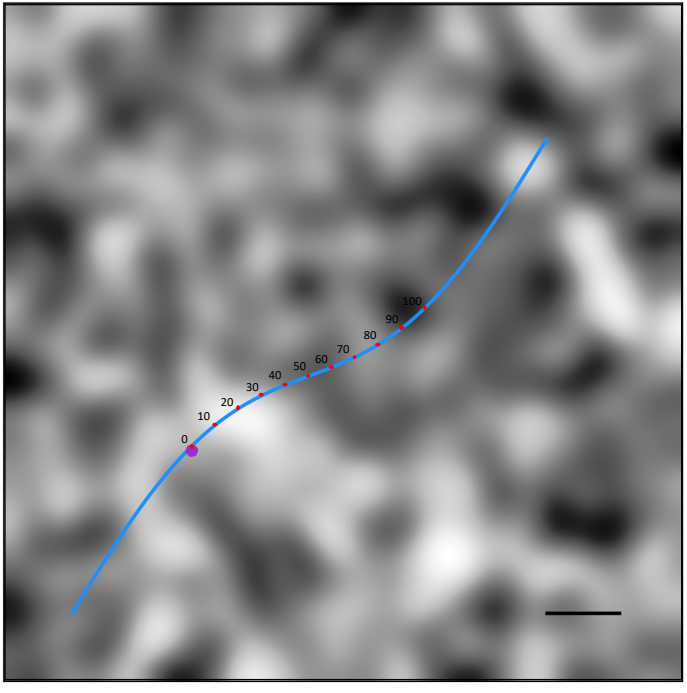


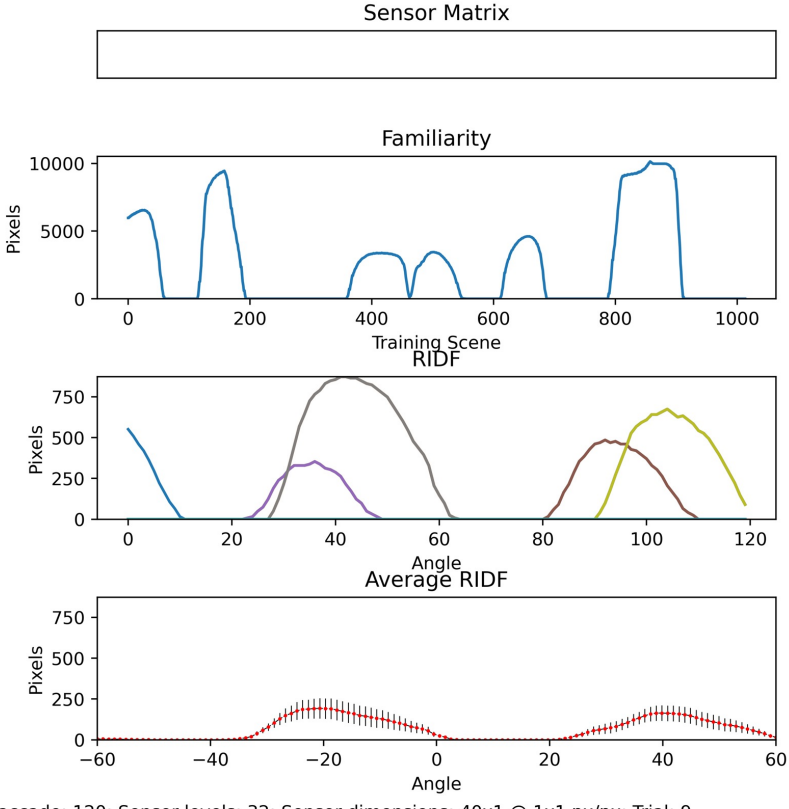


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 4874.88; RMSD/dist: 12.187; TD: 1726; p90: 36; p50: 20; complete: 0


Index: BLUR: 30.0; LEVELS: 32; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

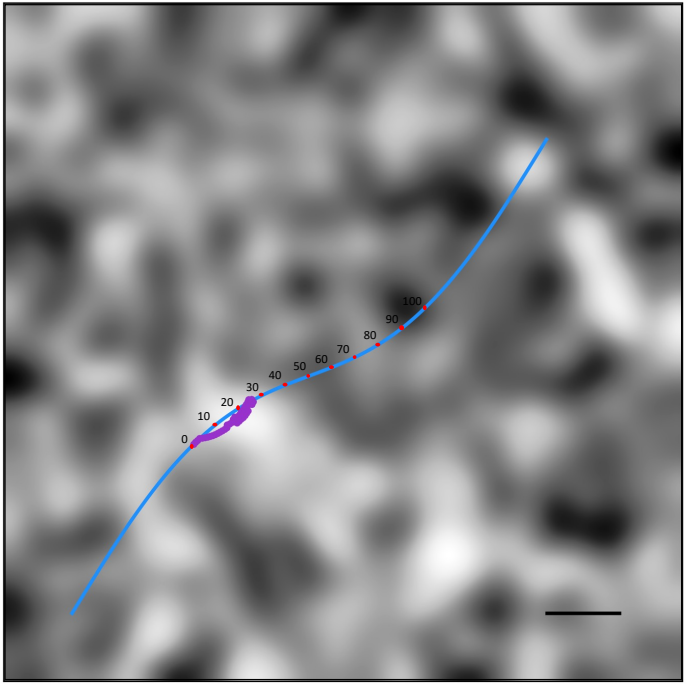
0%

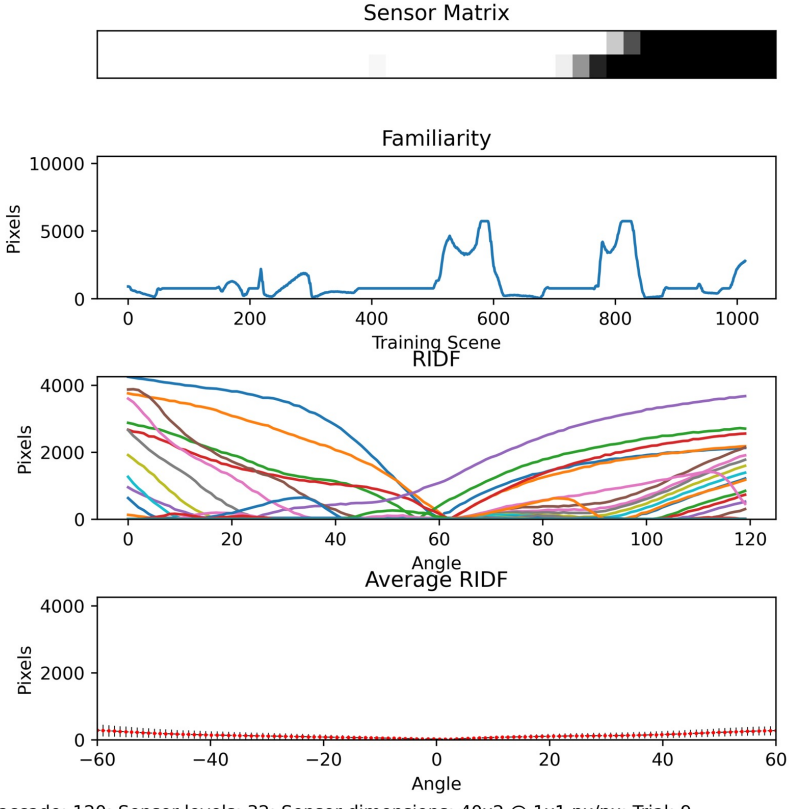




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 466.65; RMSD/dist: 1.167; TD: 2523; p90: 42; p50: 42; complete: 0

0%

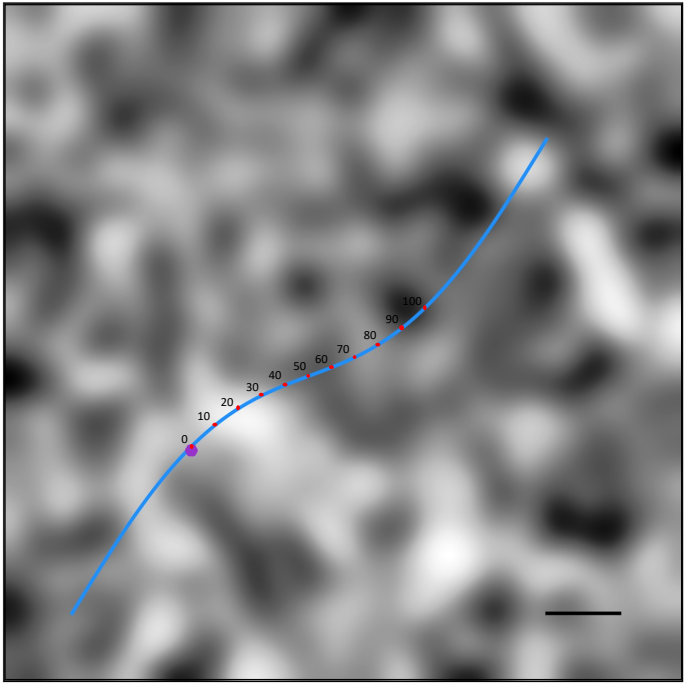


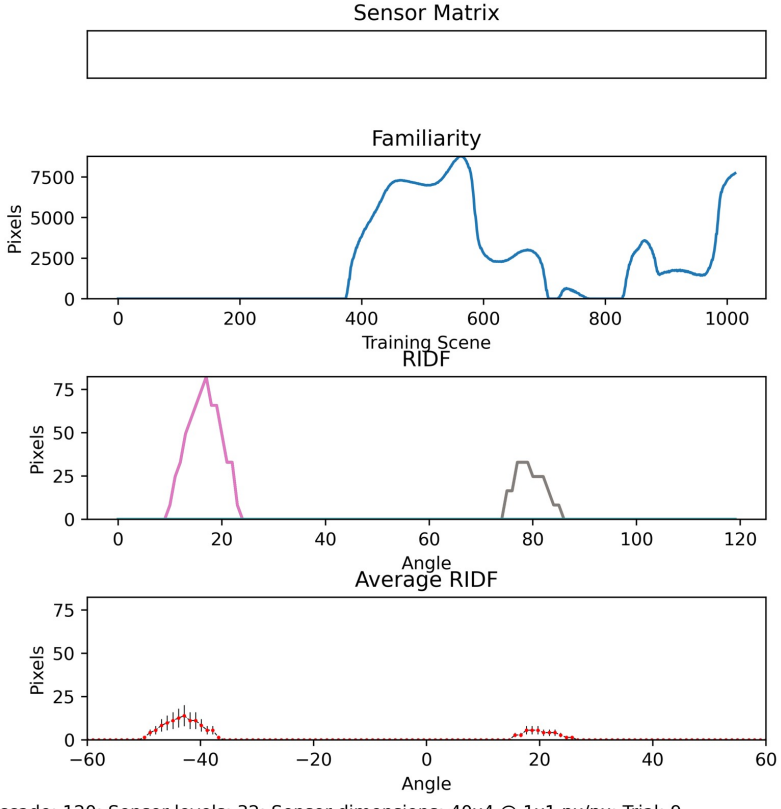


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 543.16; RMSD/dist: 1.358; TD: 2383; p90: 120; p50: 120; complete: 0

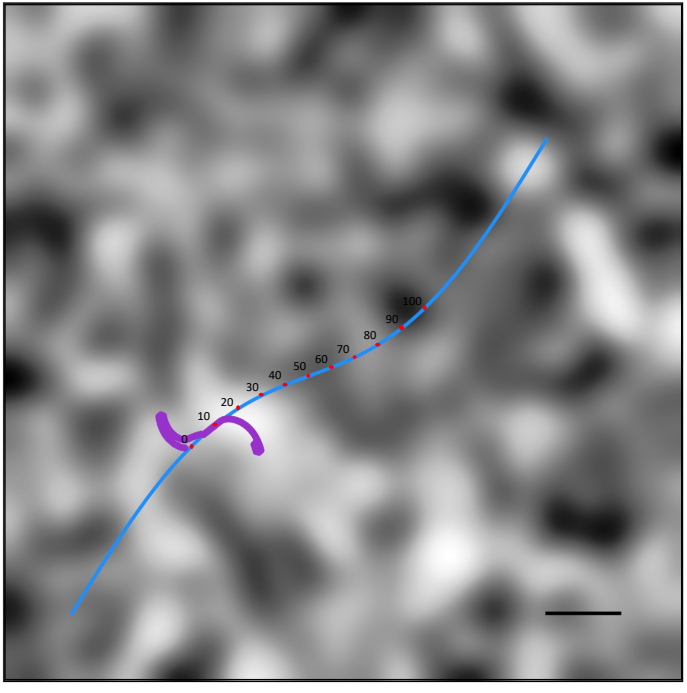
0%

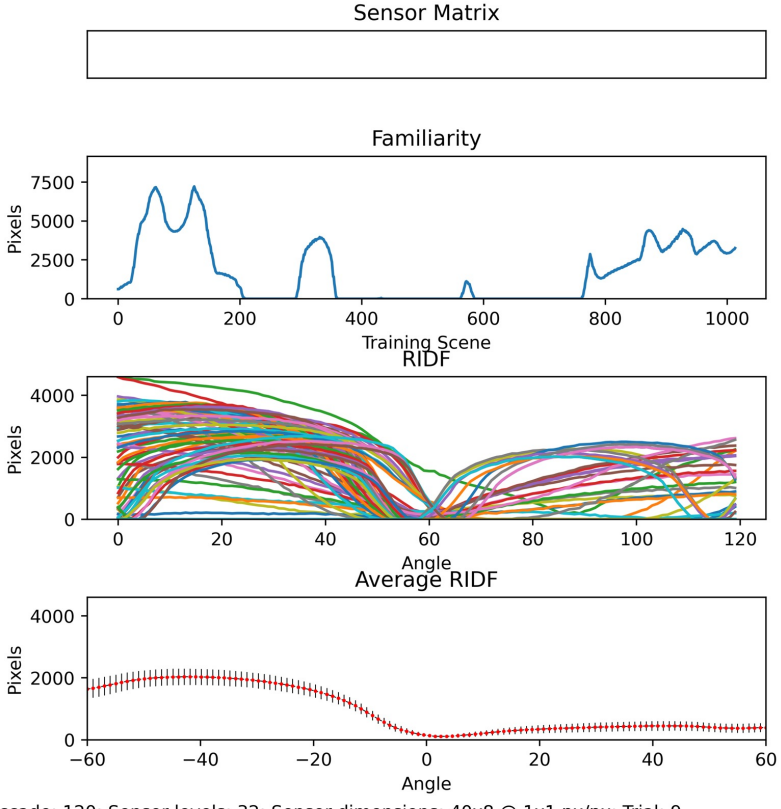




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 2202; p90: 86; p50: 86; complete: 0

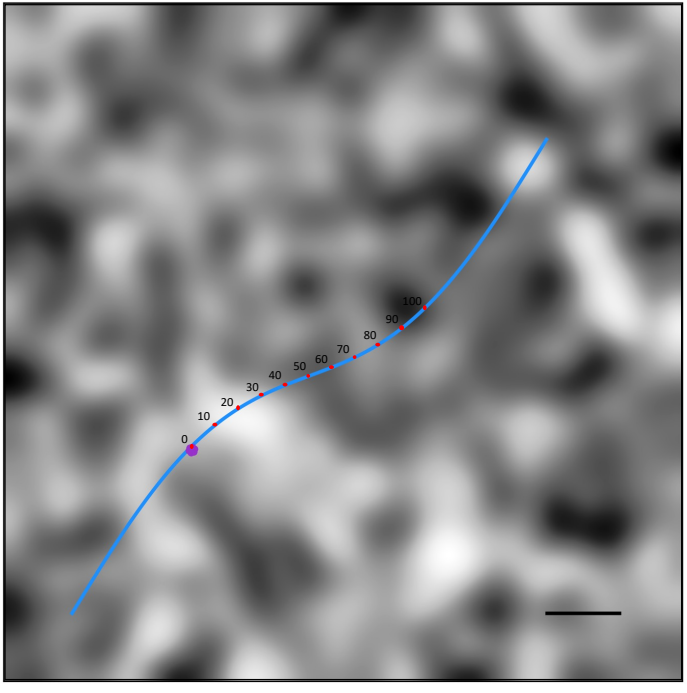
10%

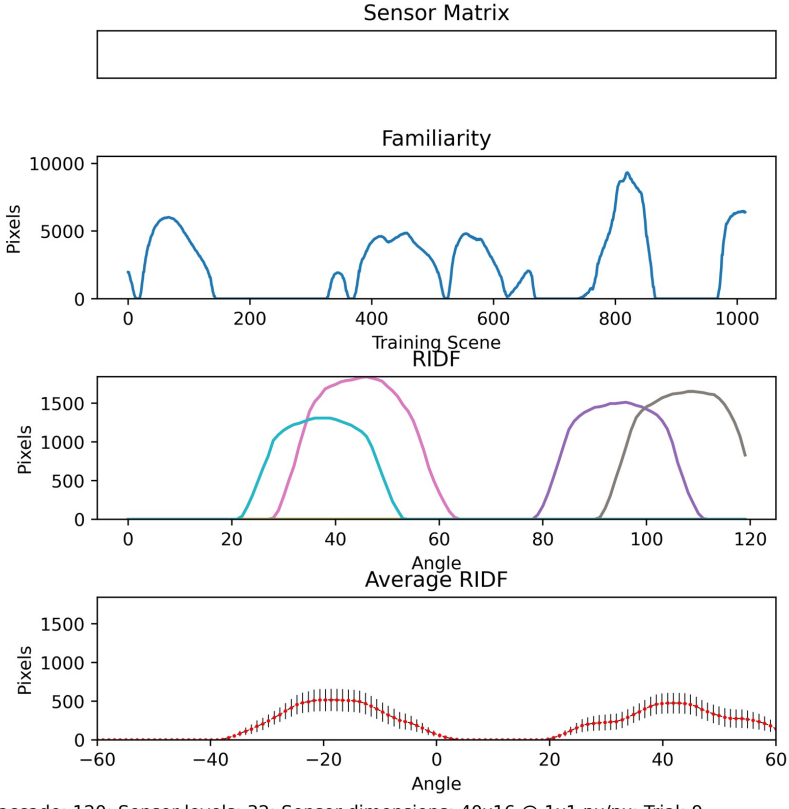




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 3985.77; RMSD/dist: 9.964; TD: 2035; p90: 64; p50: 26; complete: 0

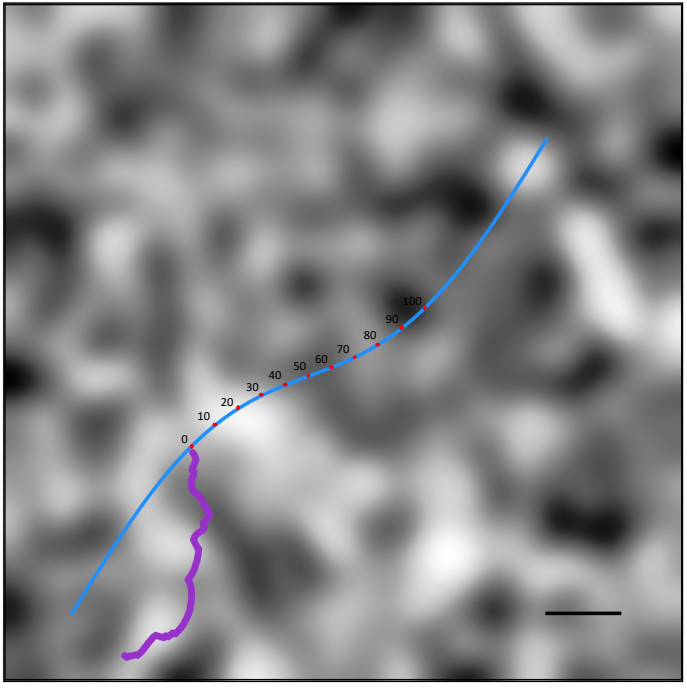
0%

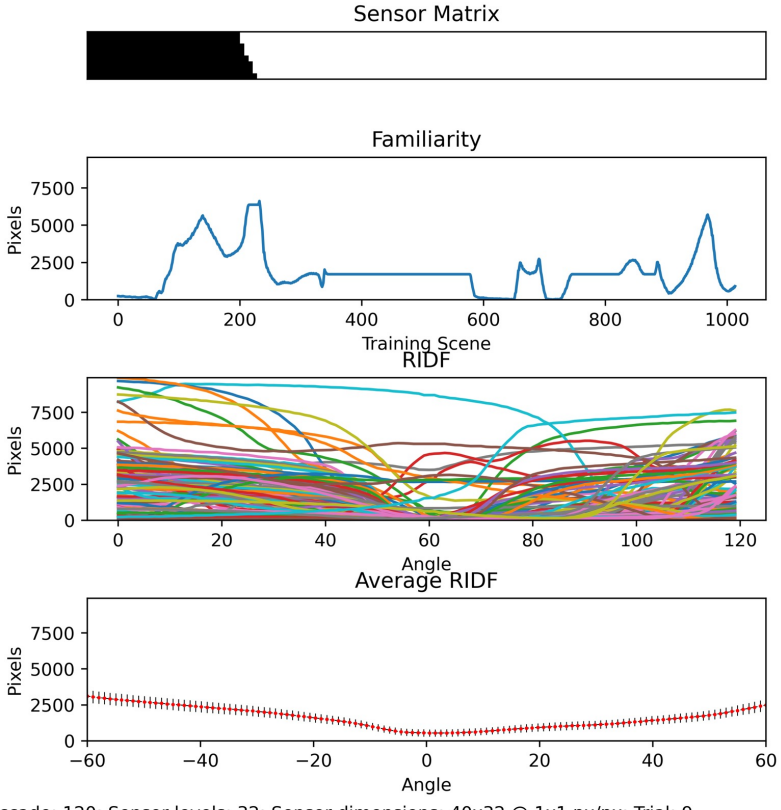




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 407.12; RMSD/dist: 1.018; TD: 2317; p90: 38; p50: 38; complete: 0

0%





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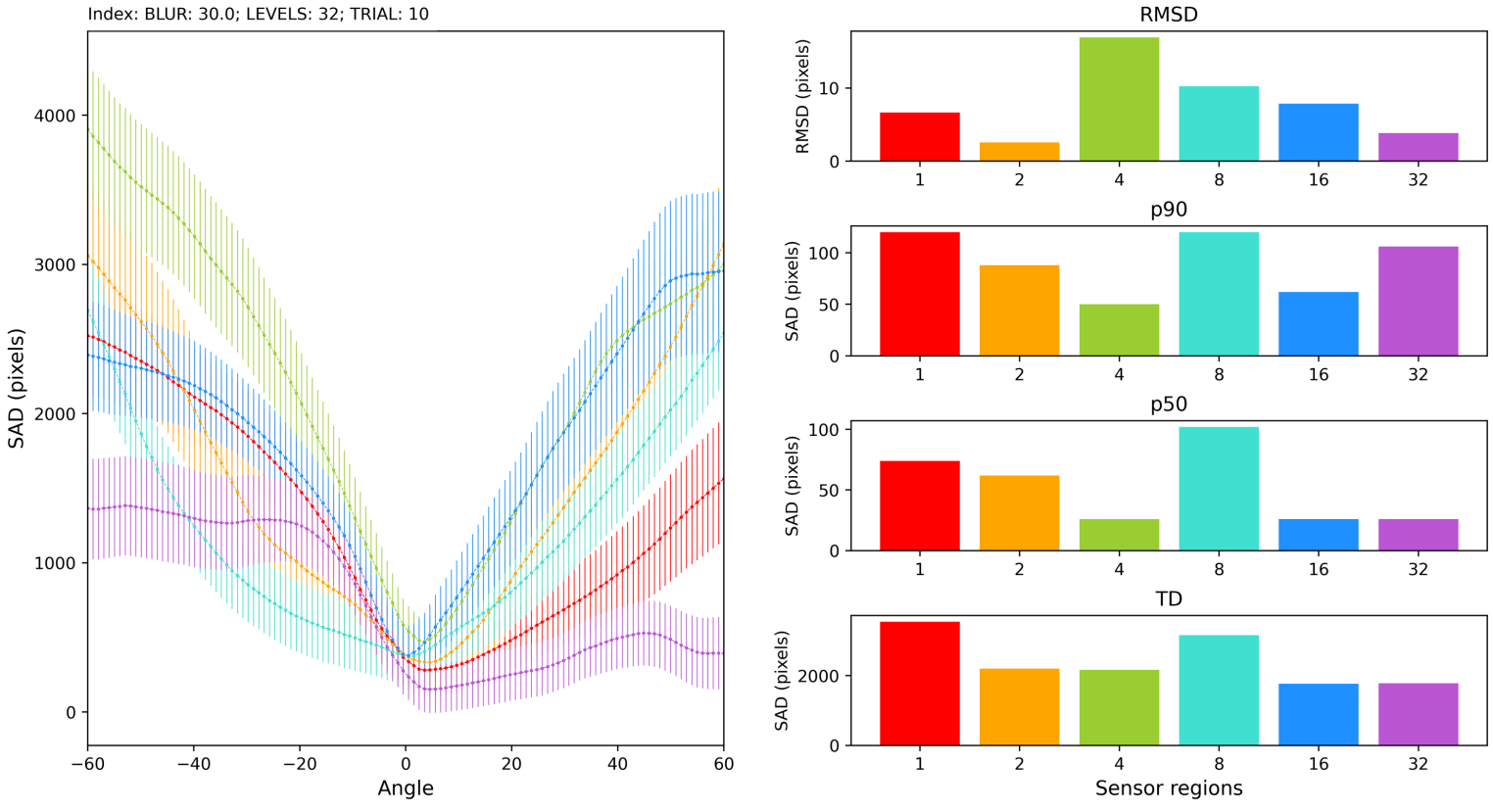
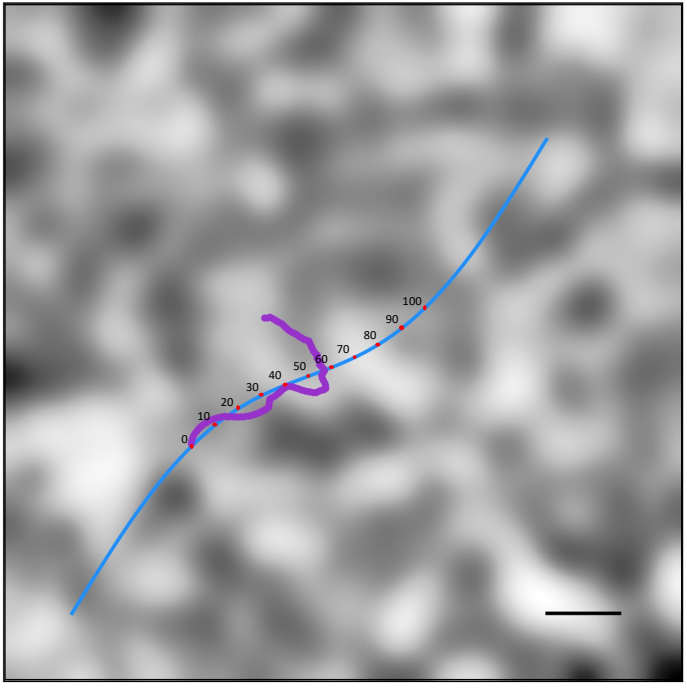
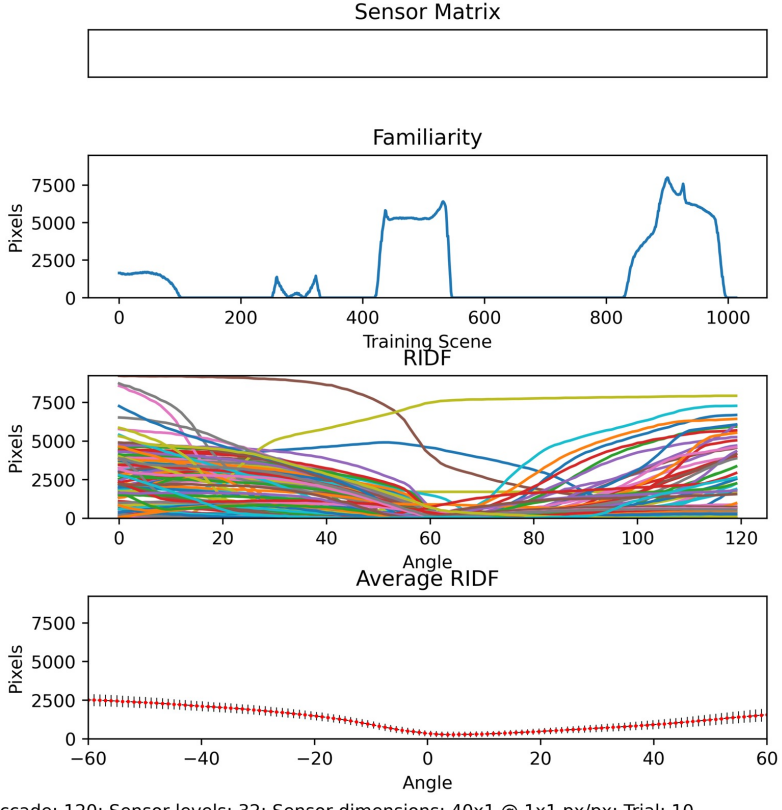
Navigation stats: RMSD error: 9884.82; RMSD/dist: 24.712; TD: 2559; p90: 108; p50: 50; complete: 0


Index: BLUR: 30.0; LEVELS: 32; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

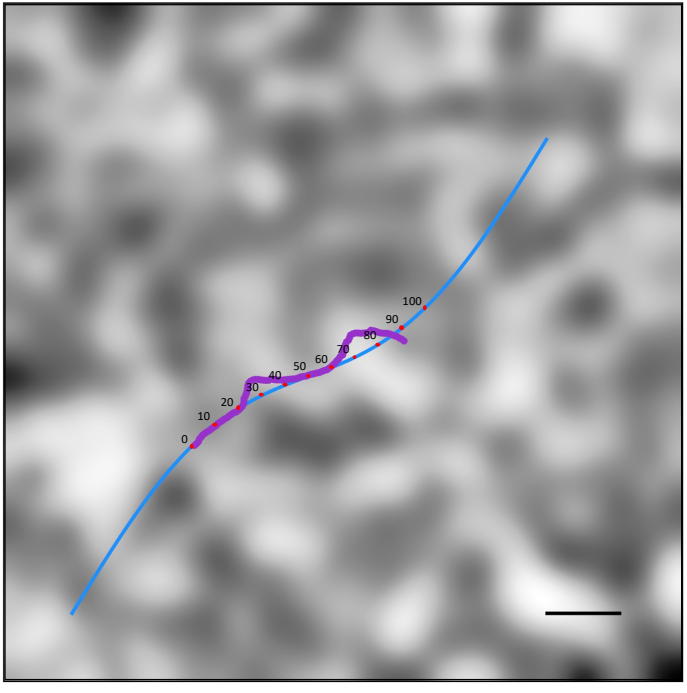
0%

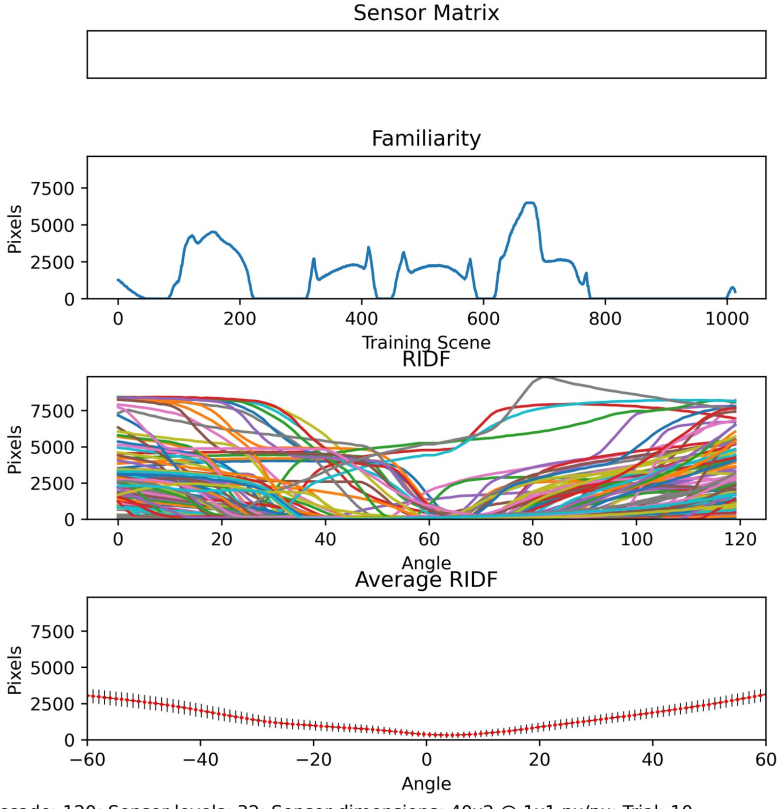




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 2663.51; RMSD/dist: 6.659; TD: 3543; p90: 120; p50: 74; complete: 0

20%

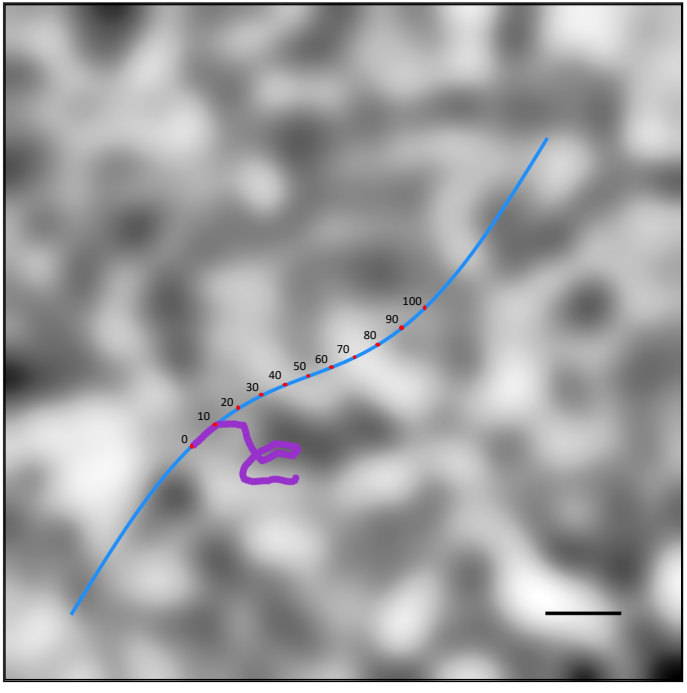


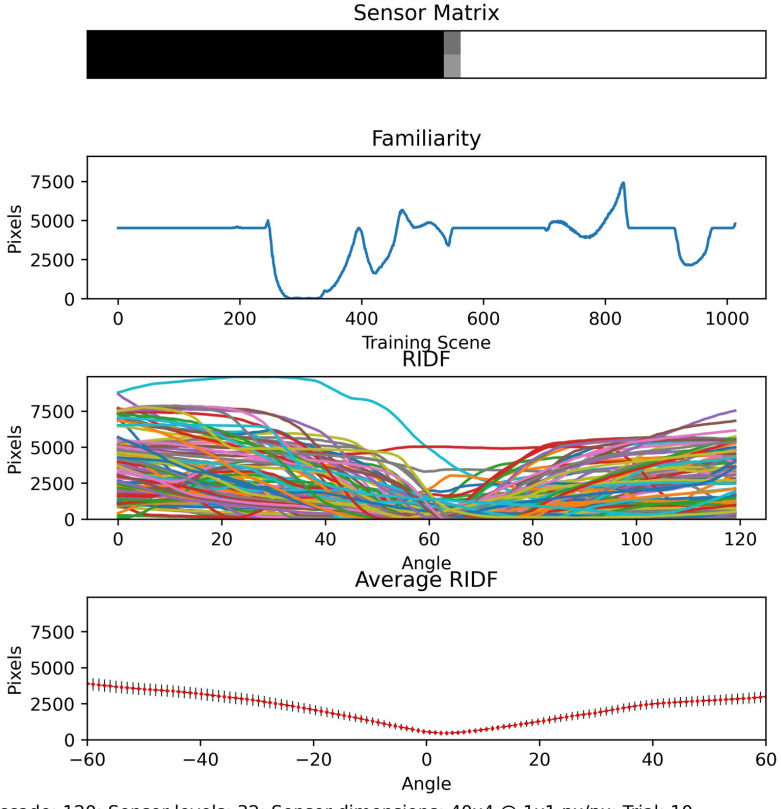


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1024.66; RMSD/dist: 2.562; TD: 2198; p90: 88; p50: 62; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 6775.37; RMSD/dist: 16.938; TD: 2161; p90: 50; p50: 26; complete: 0

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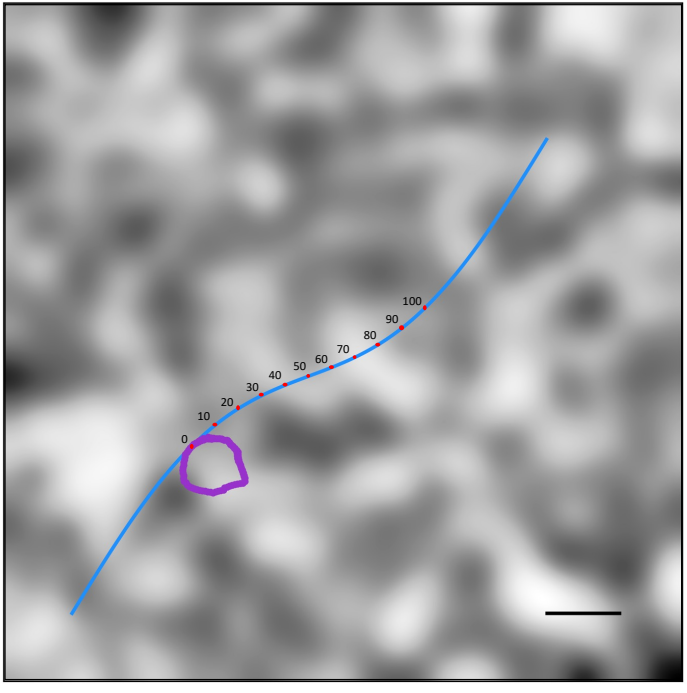
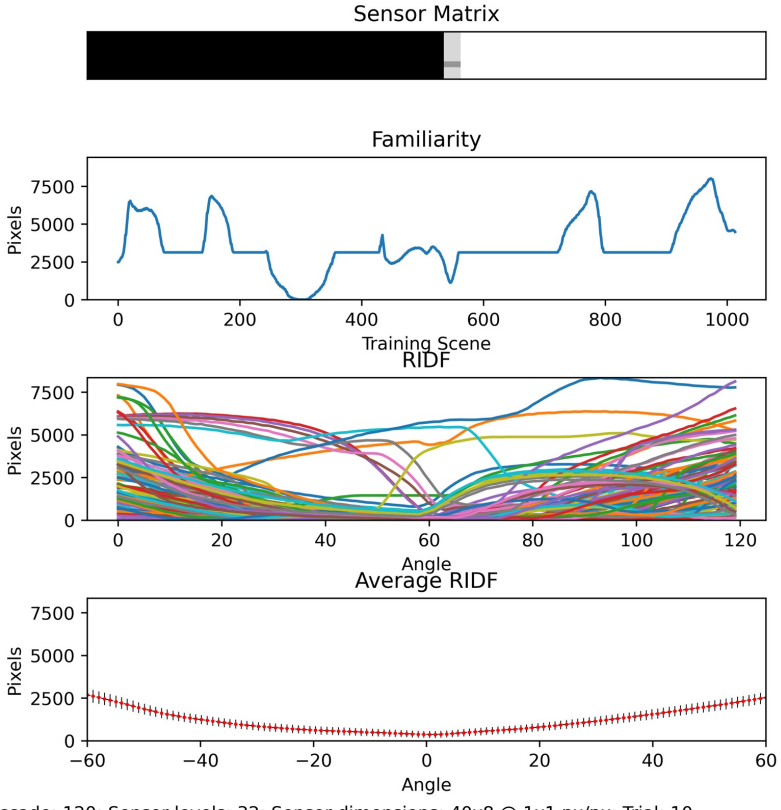
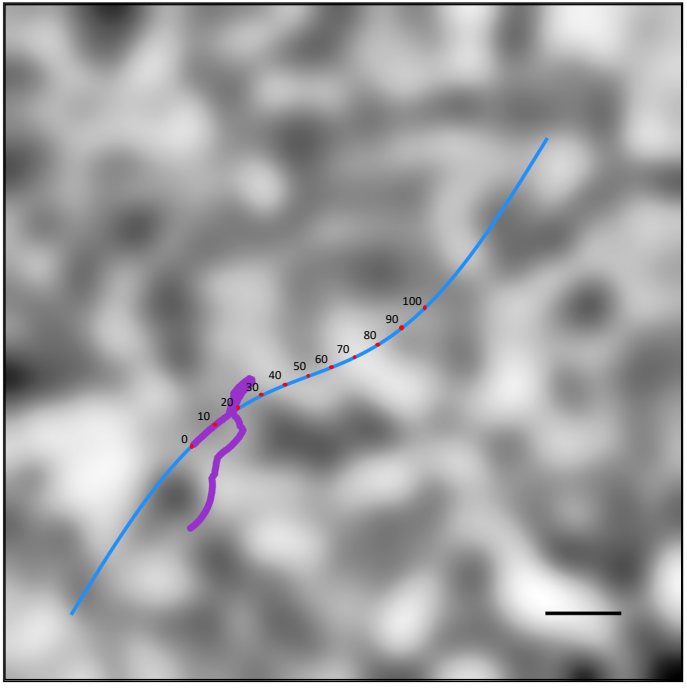


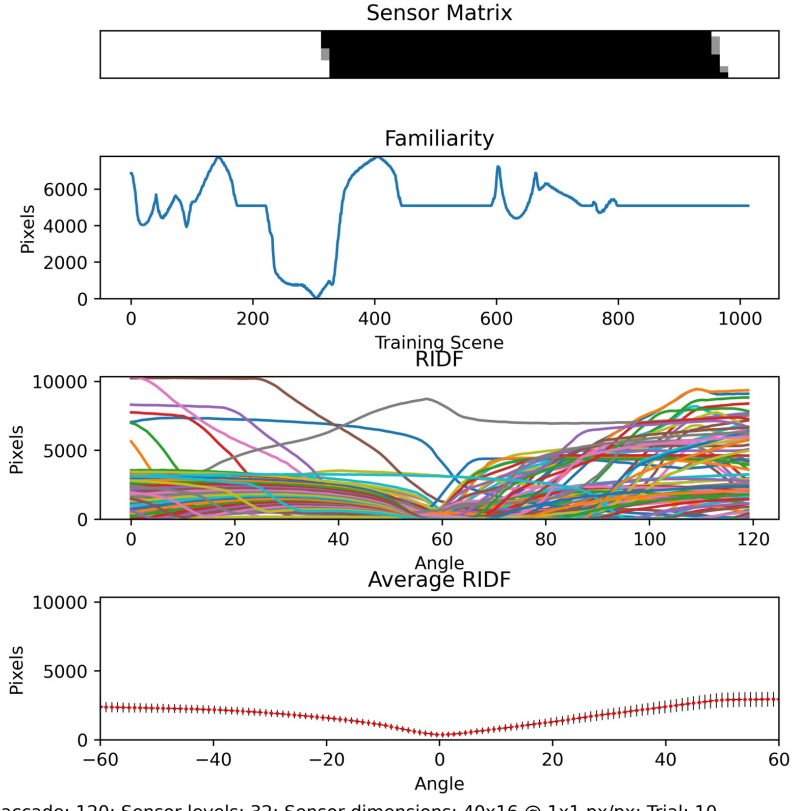


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4096.65; RMSD/dist: 10.242; TD: 3159; p90: 120; p50: 102; complete: 0

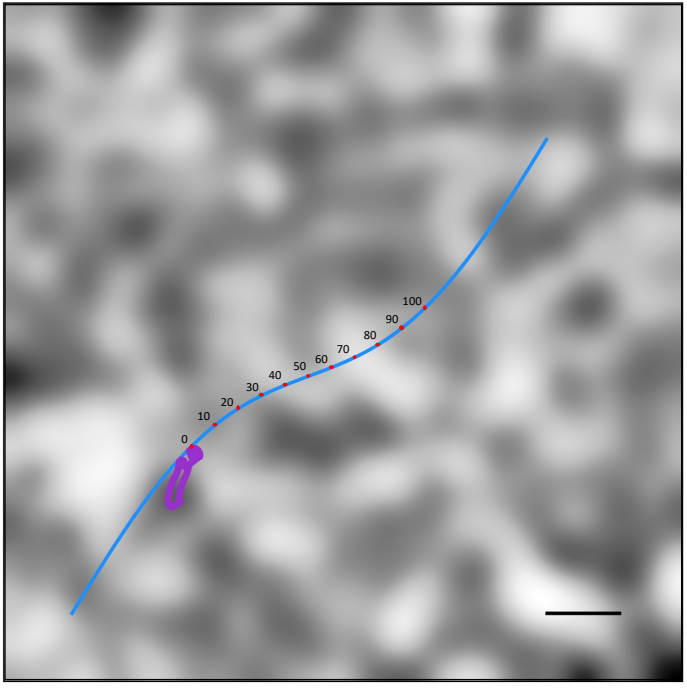
20%

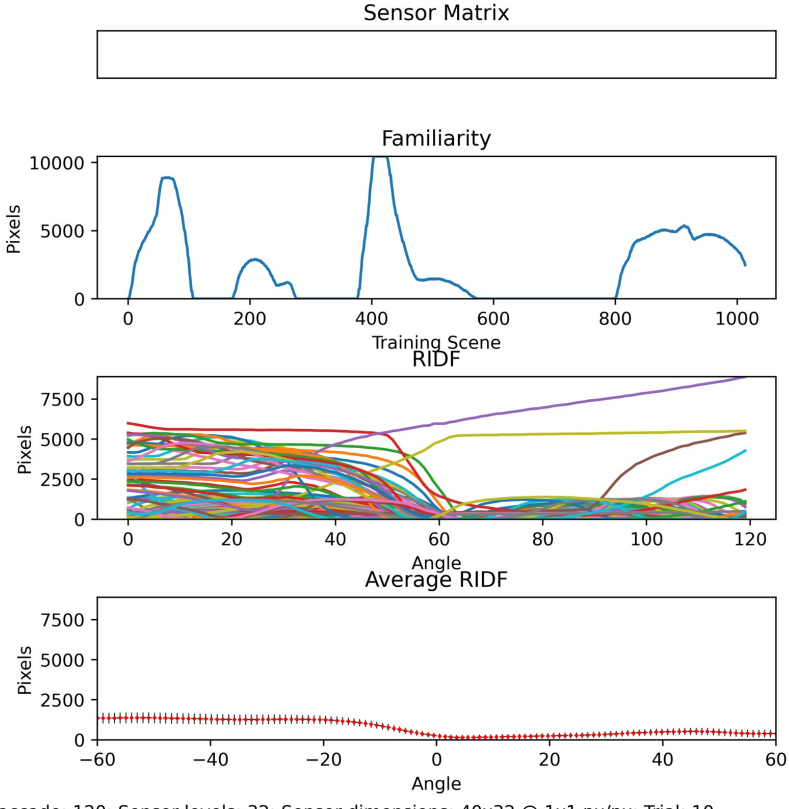




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 3144.20; RMSD/dist: 7.860; TD: 1769; p90: 62; p50: 26; complete: 0

0%





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Navigation stats: RMSD error: 1527.59; RMSD/dist: 3.819; TD: 1780; p90: 106; p50: 26; complete: 0