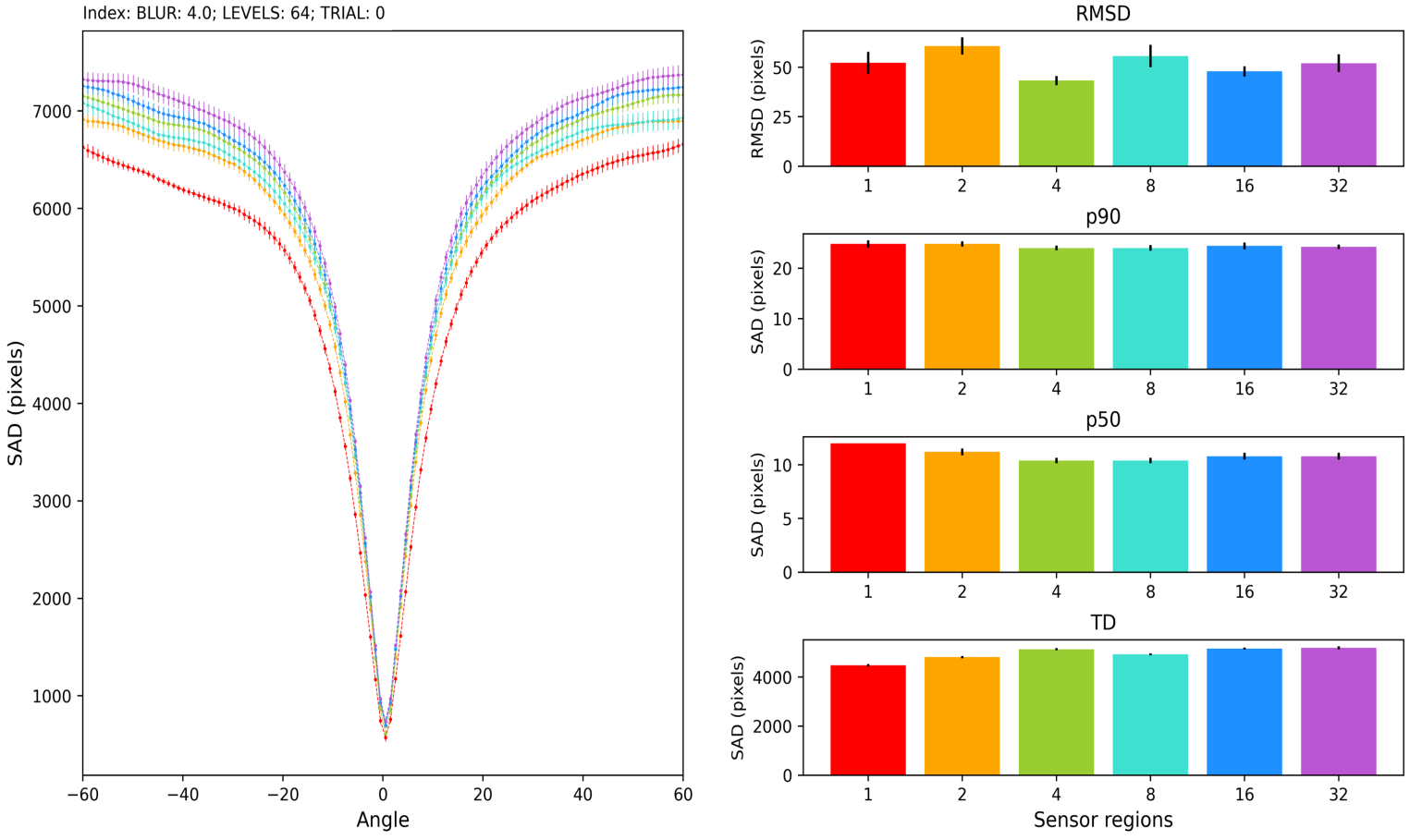
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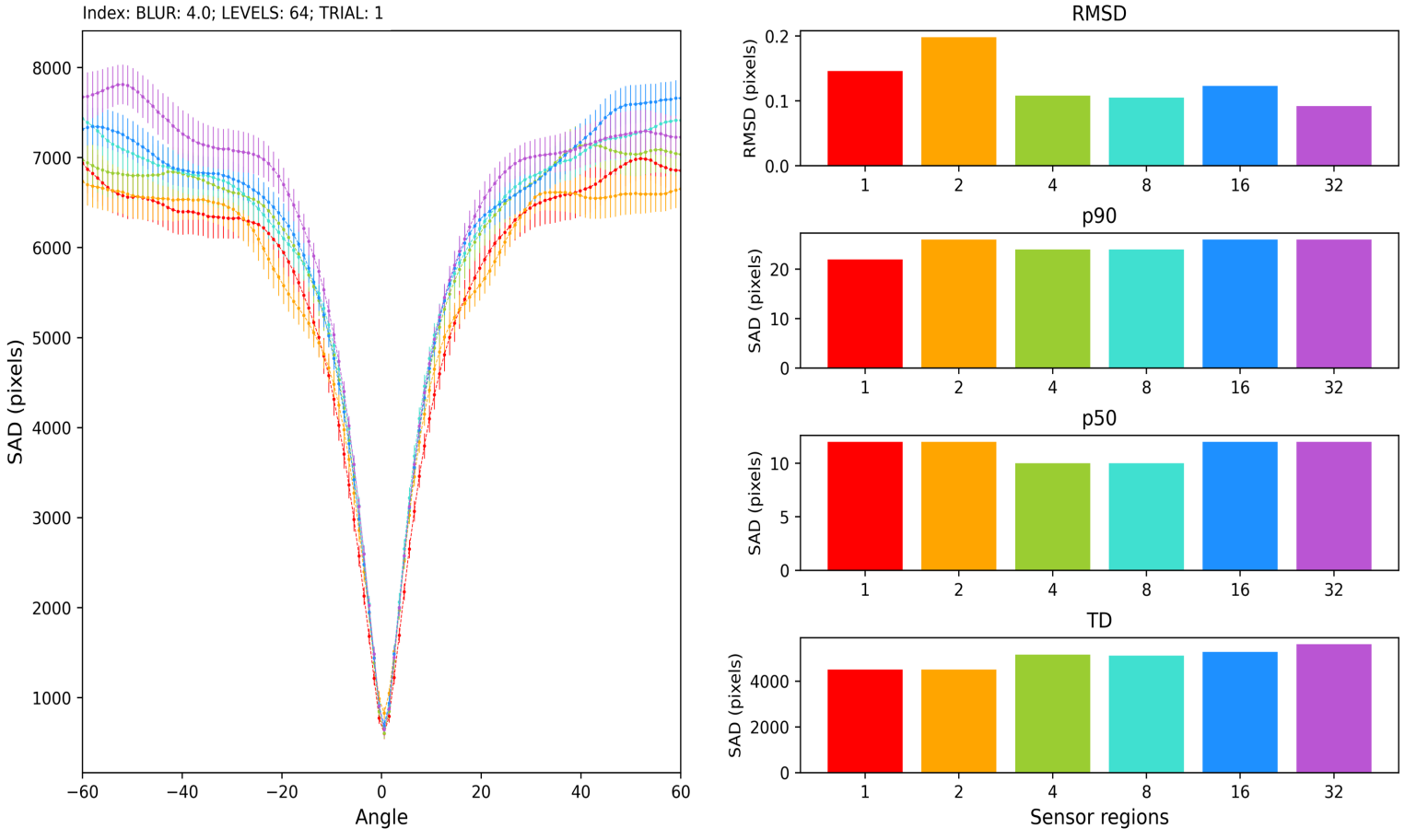
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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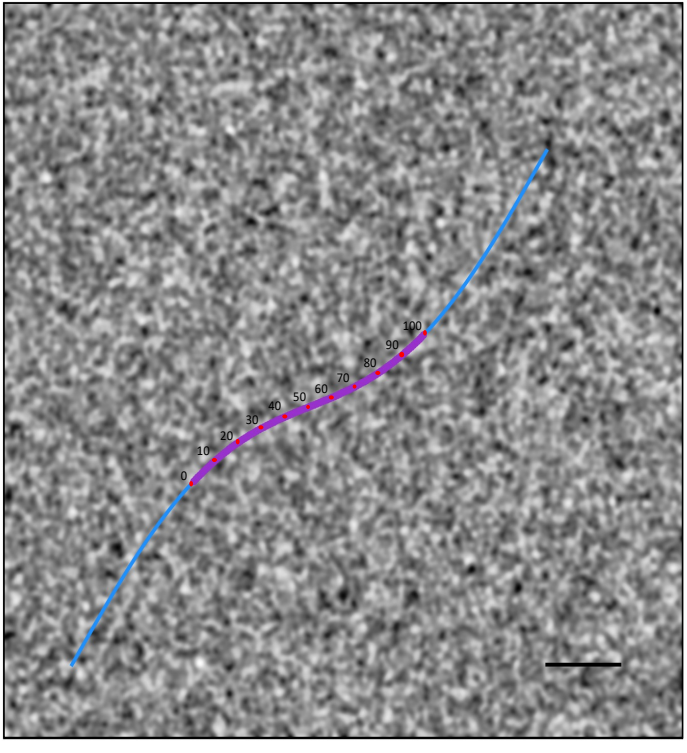
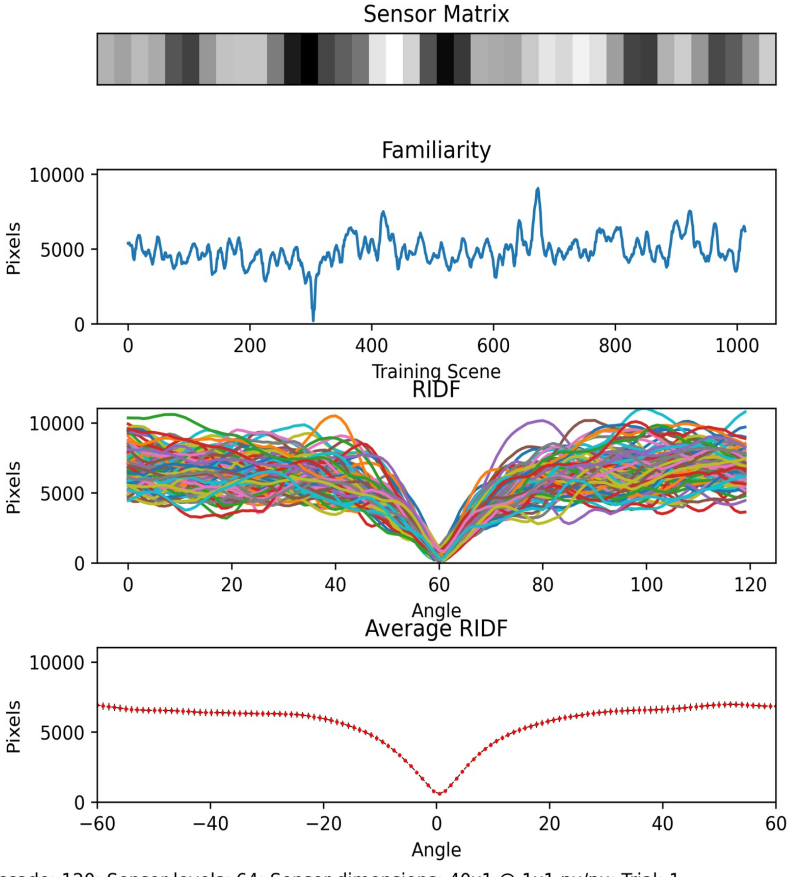
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

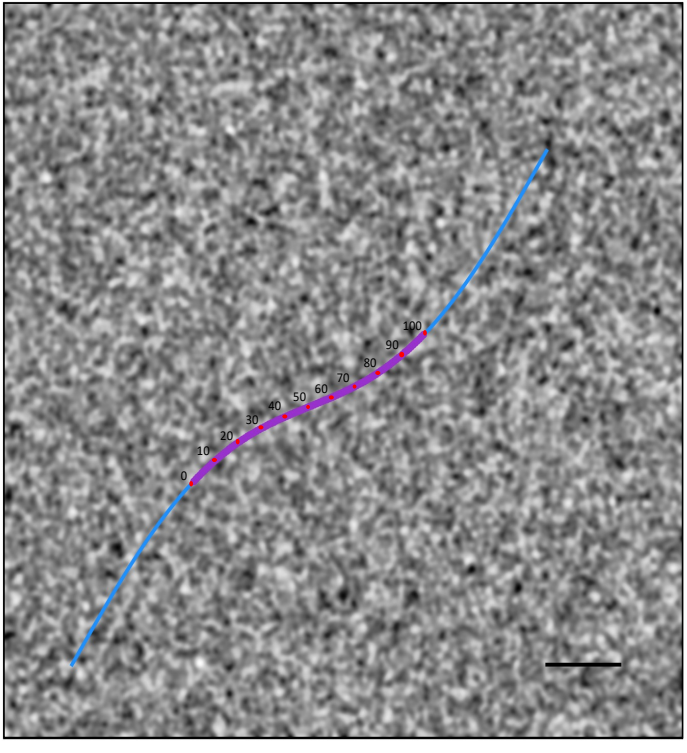


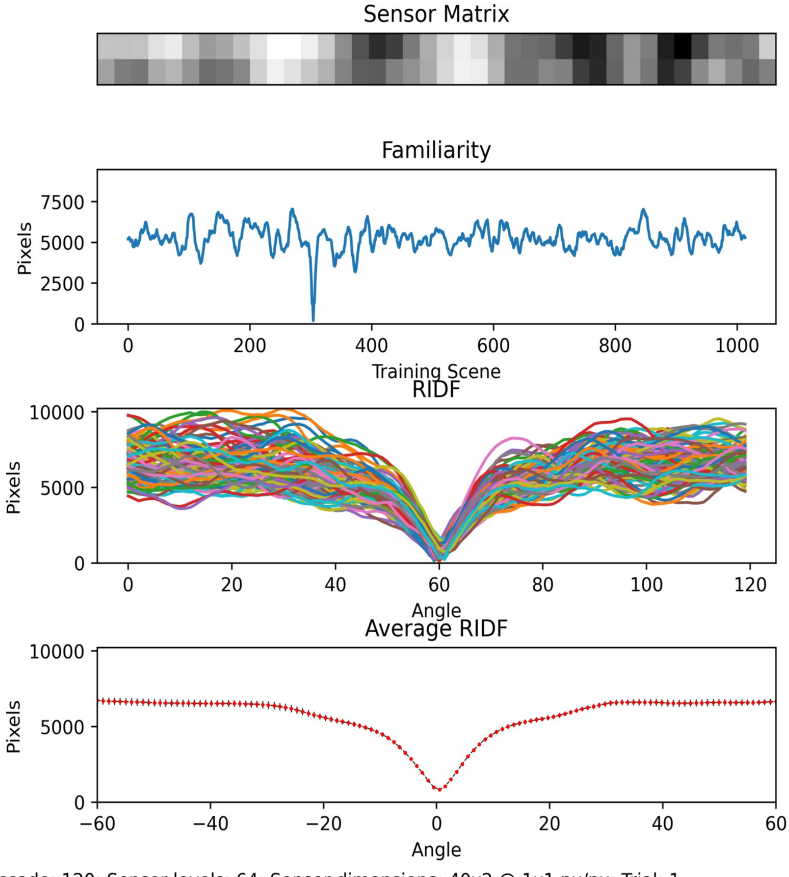


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 58.54; RMSD/dist: 0.146; TD: 4510; p90: 22; p50: 12; complete: 0

100%

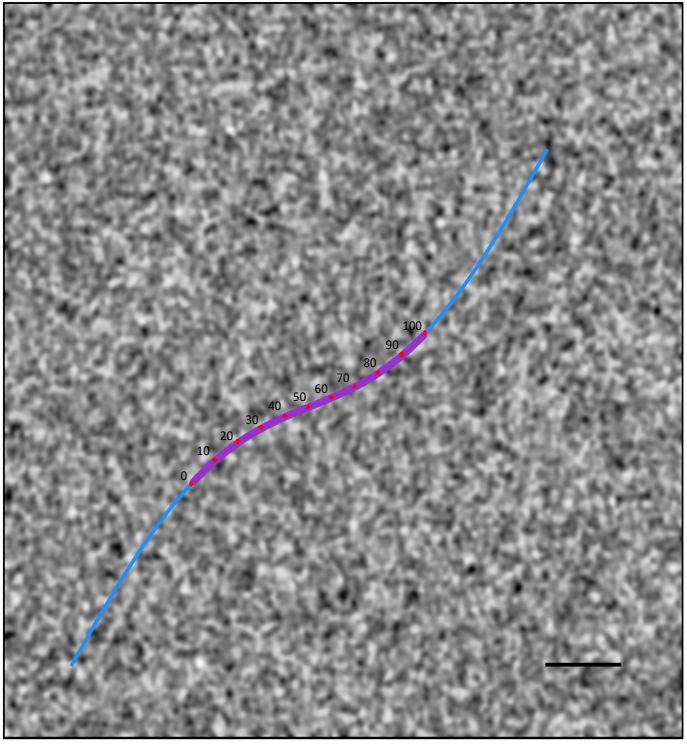


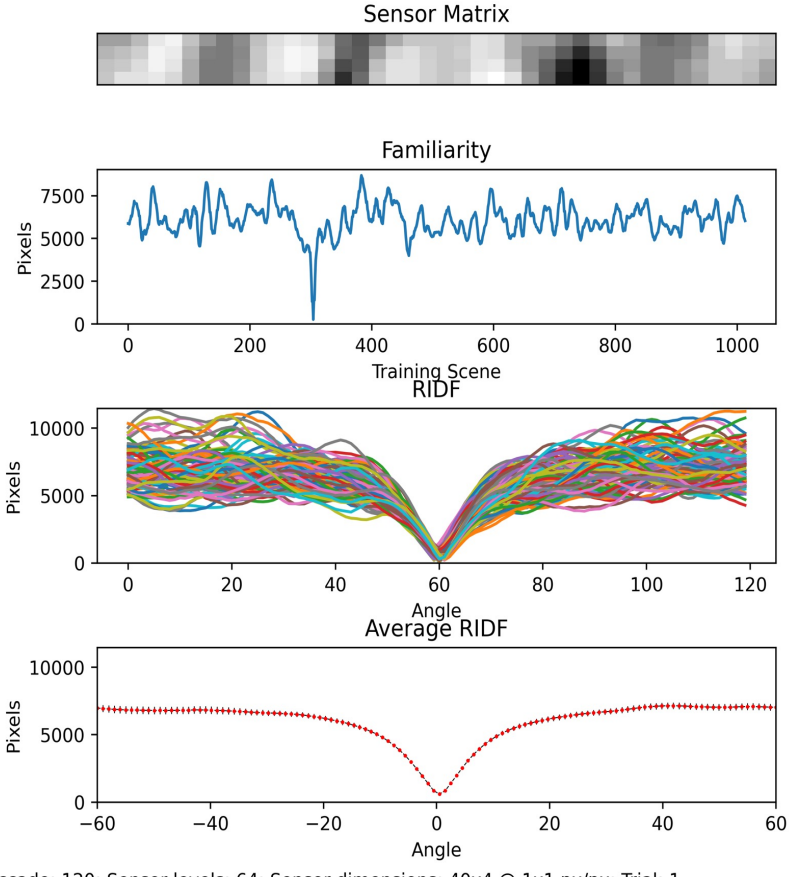


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 79.01; RMSD/dist: 0.198; TD: 4511; p90: 26; p50: 12; complete: 0

100%

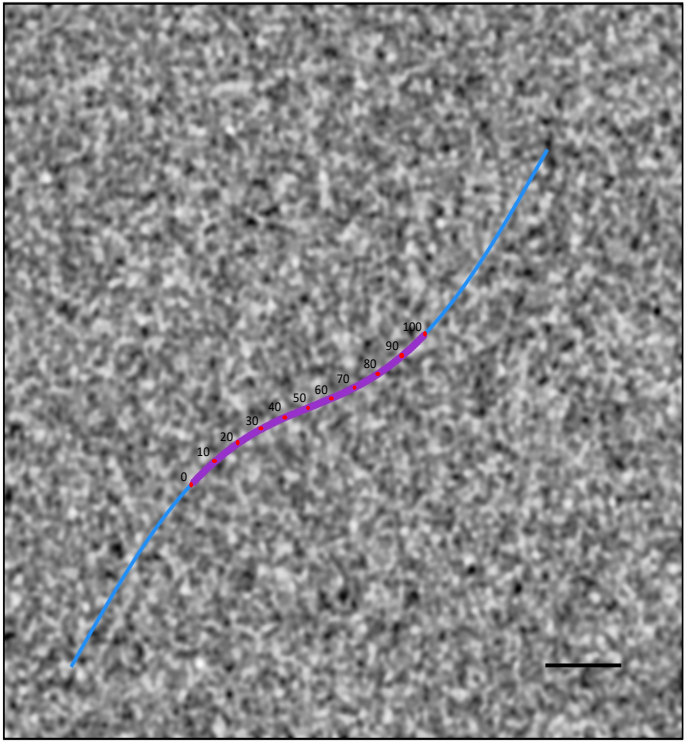


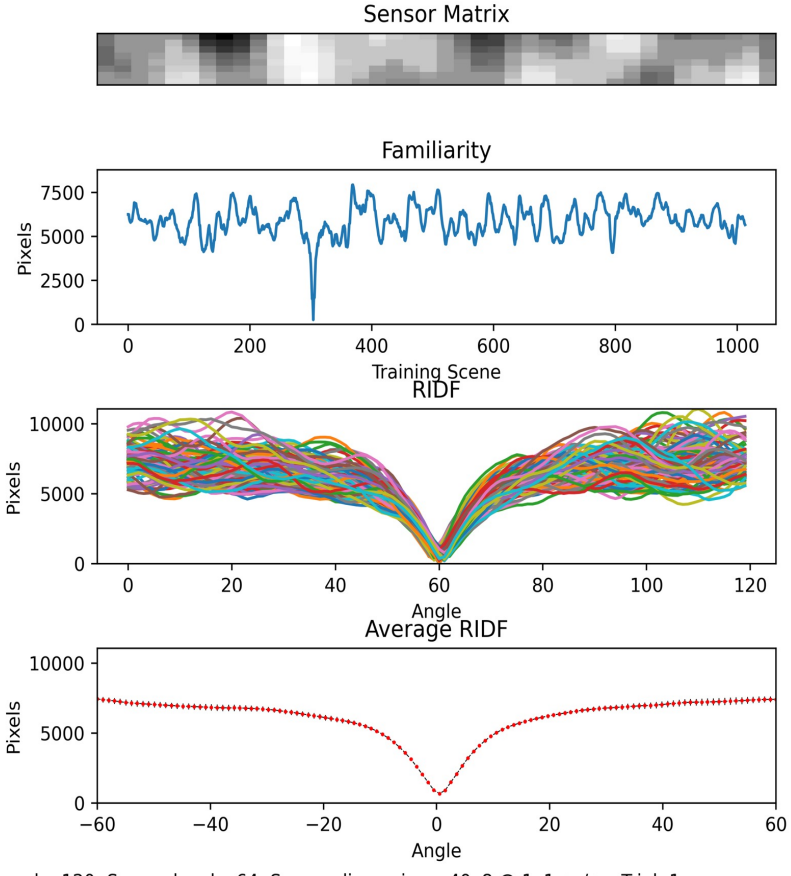


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 43.22; RMSD/dist: 0.108; TD: 5163; p90: 24; p50: 10; complete: 0

100%

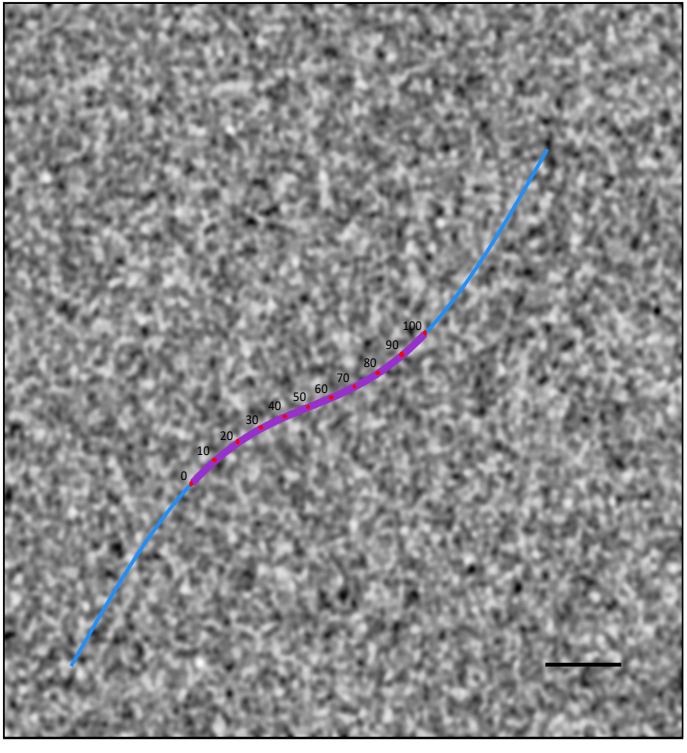


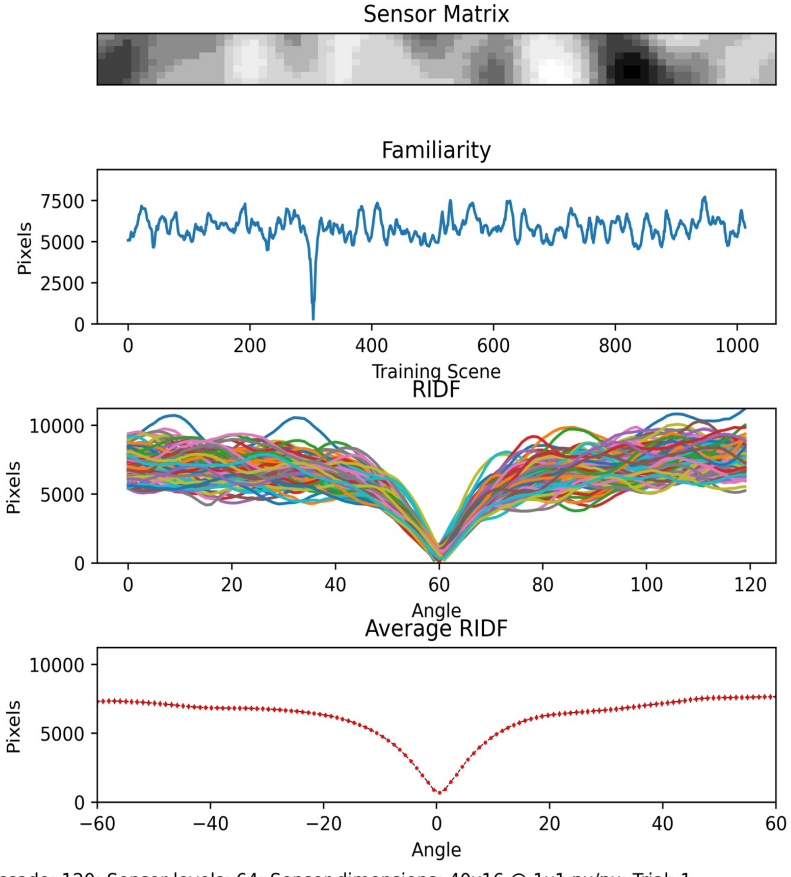


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 42.03; RMSD/dist: 0.105; TD: 5117; p90: 24; p50: 10; complete: 0

100%

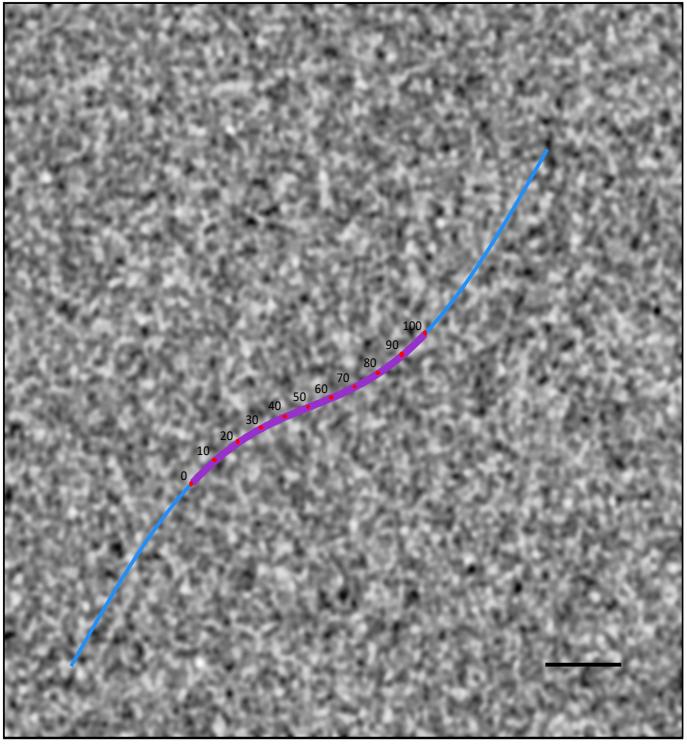


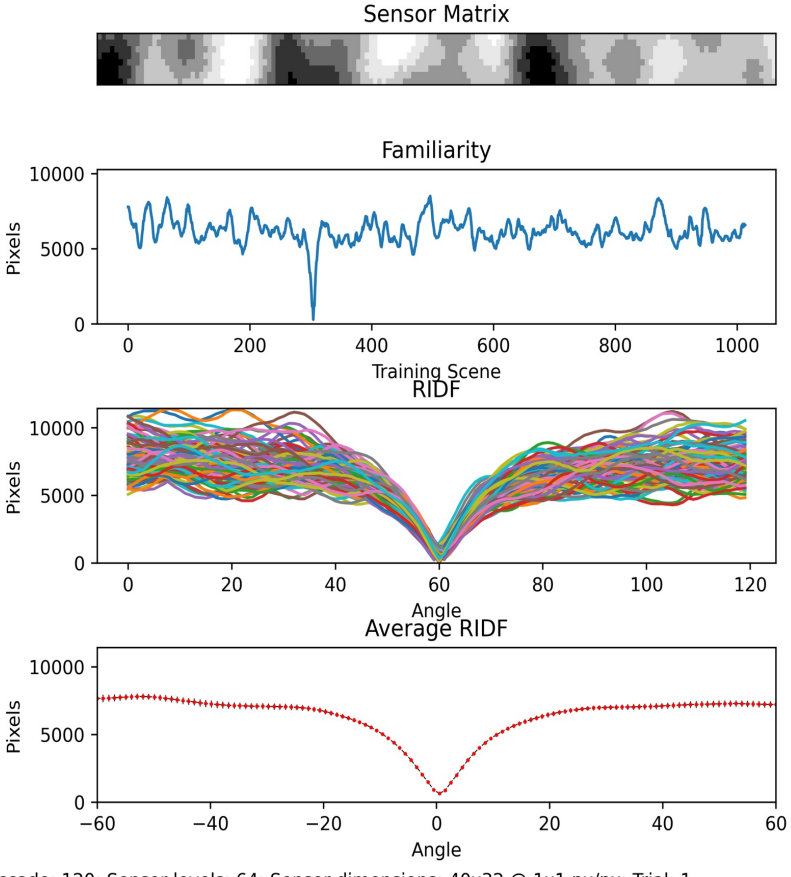


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 49.33; RMSD/dist: 0.123; TD: 5281; p90: 26; p50: 12; complete: 0

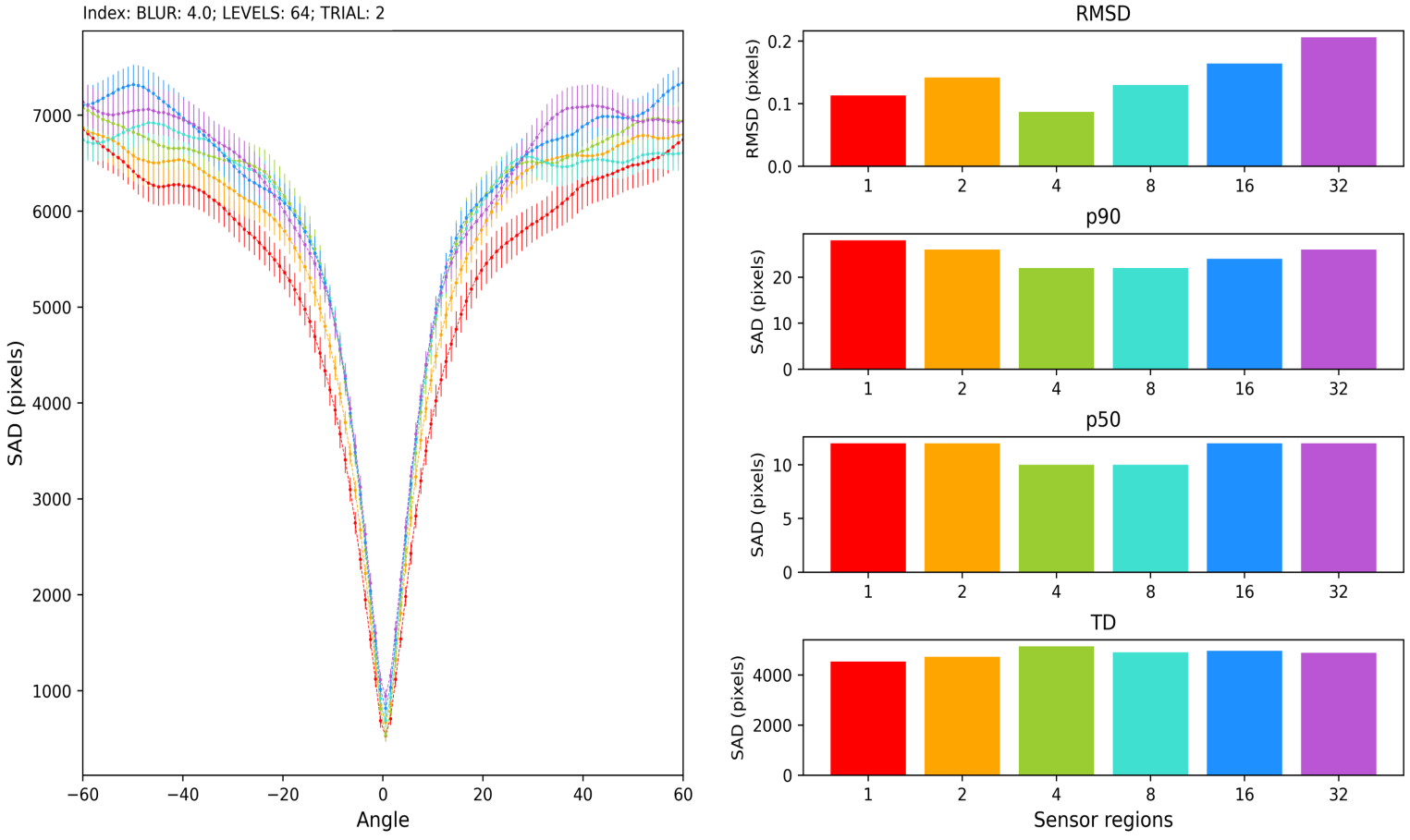
100%



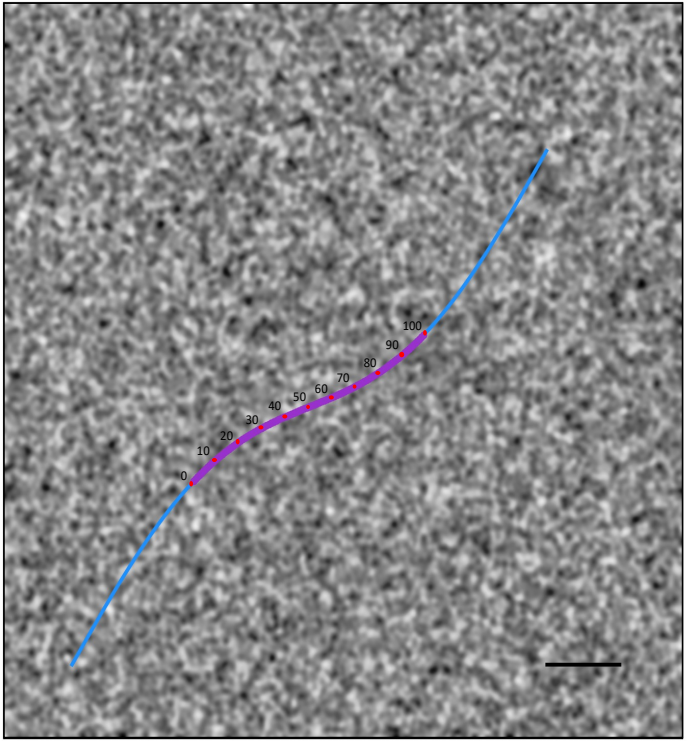


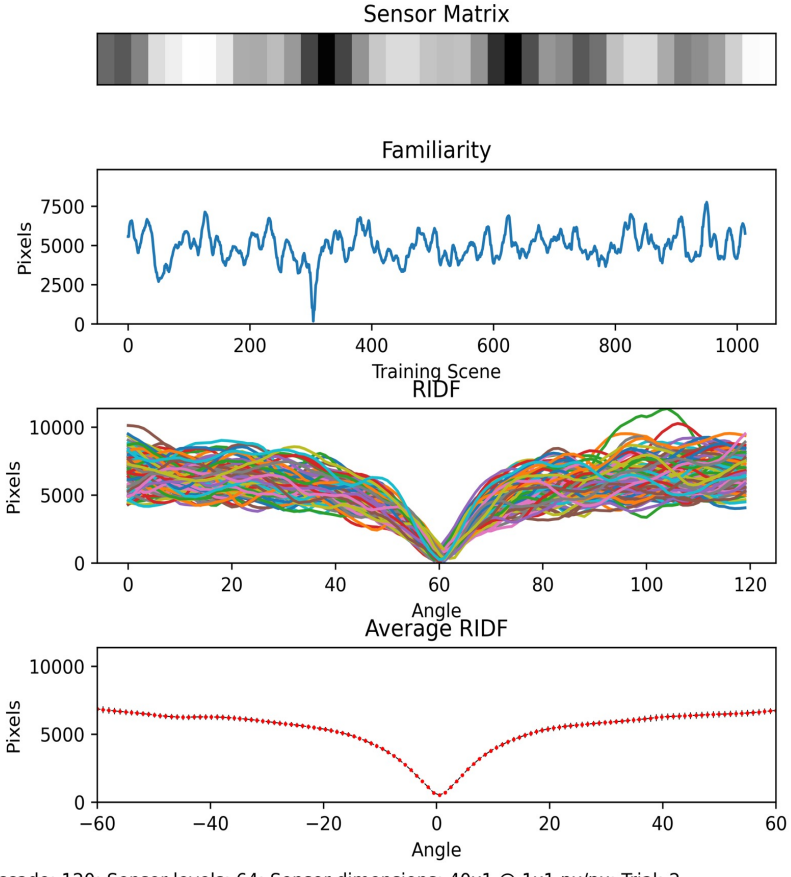
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 36.91; RMSD/dist: 0.092; TD: 5620; p90: 26; p50: 12; complete: 0


Index: BLUR: 4.0; LEVELS: 64; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

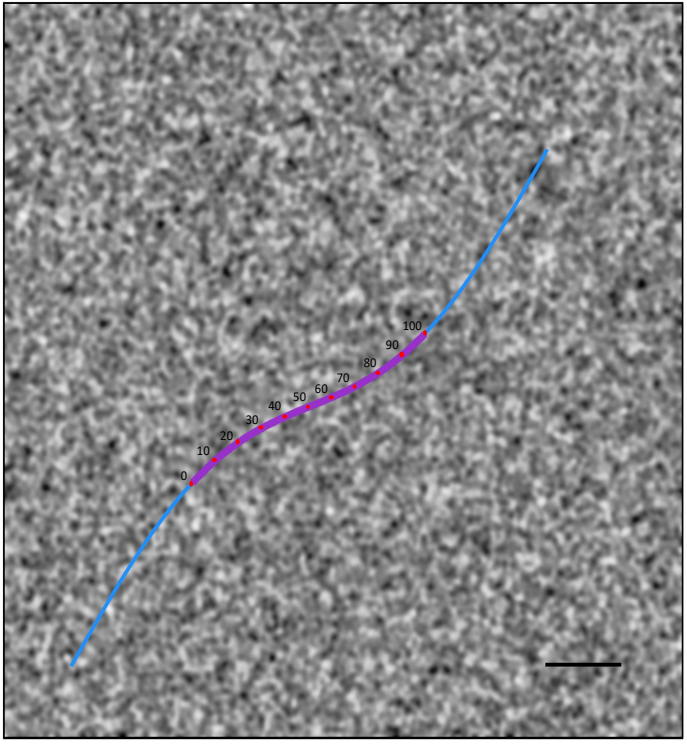


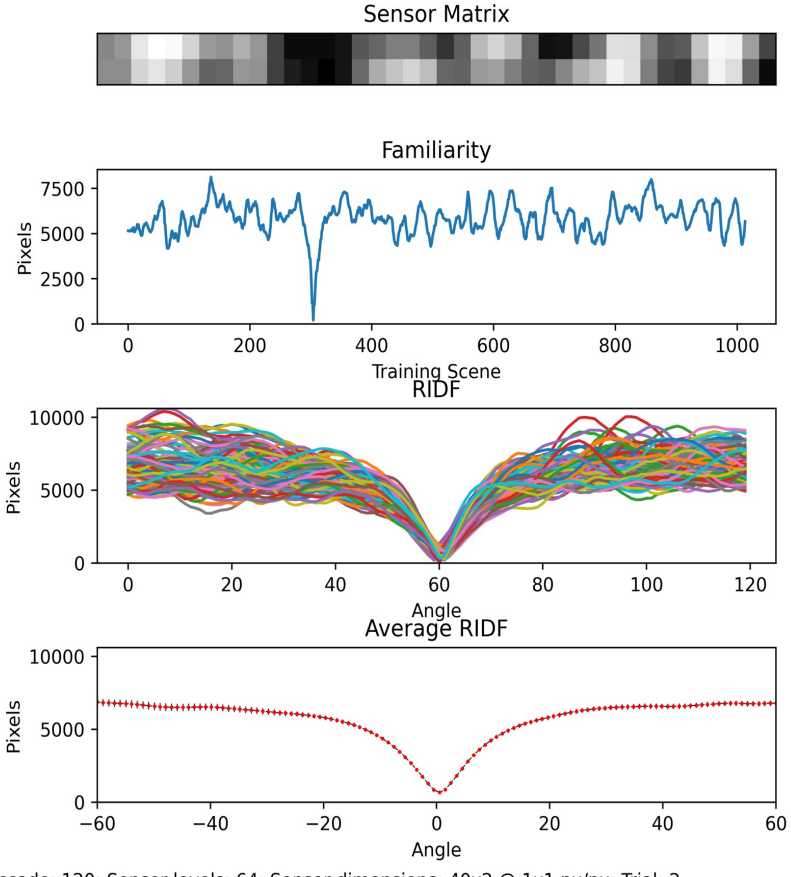


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 45.27; RMSD/dist: 0.113; TD: 4534; p90: 28; p50: 12; complete: 0

100%

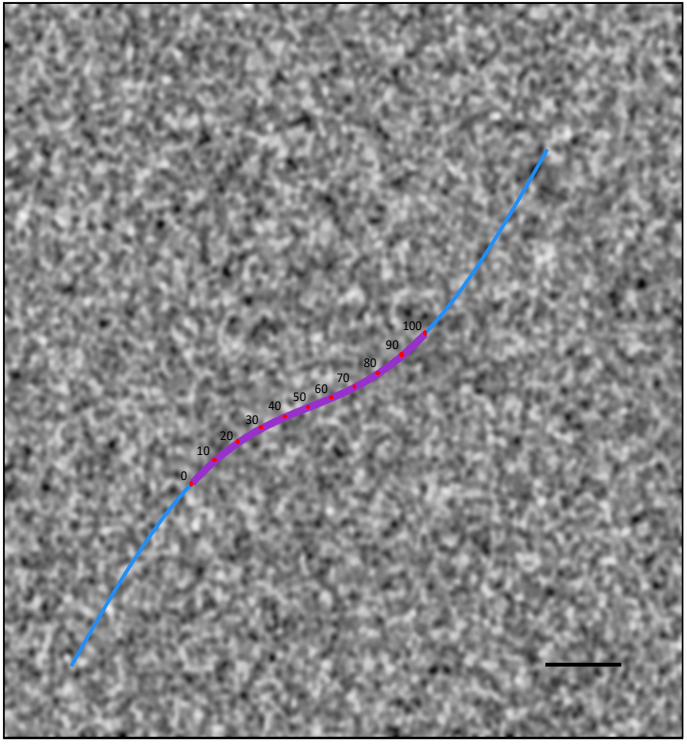


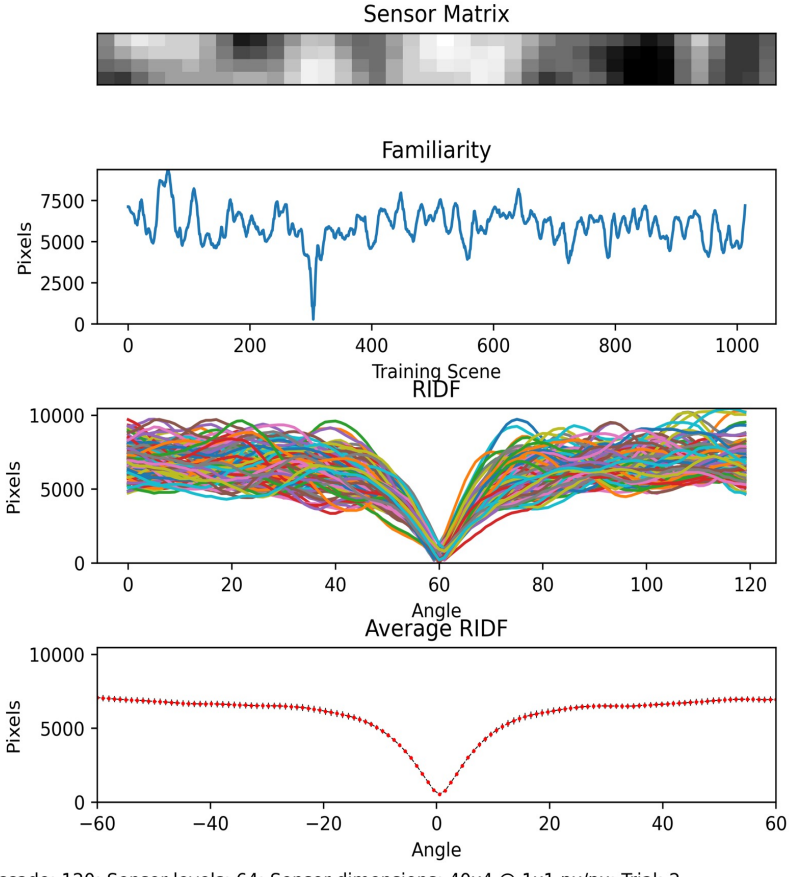


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 56.96; RMSD/dist: 0.142; TD: 4719; p90: 26; p50: 12; complete: 0

100%

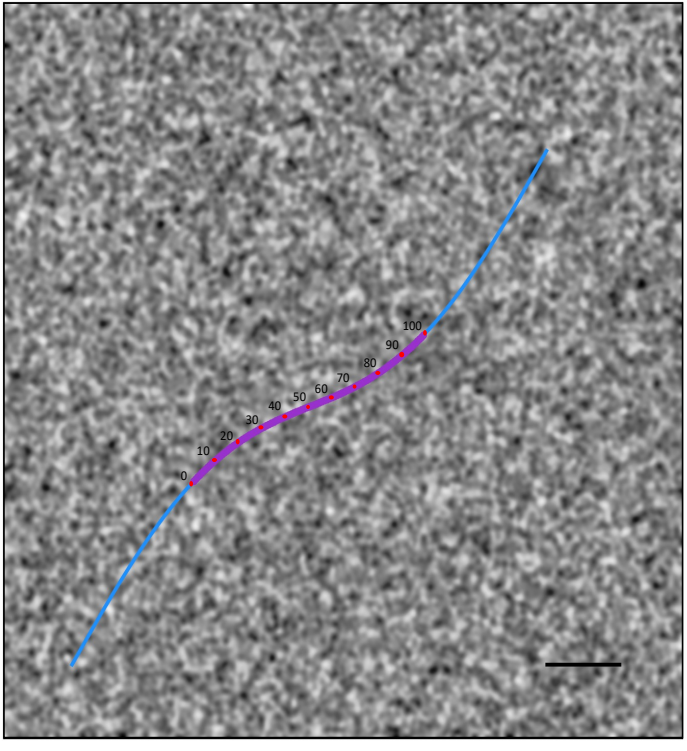


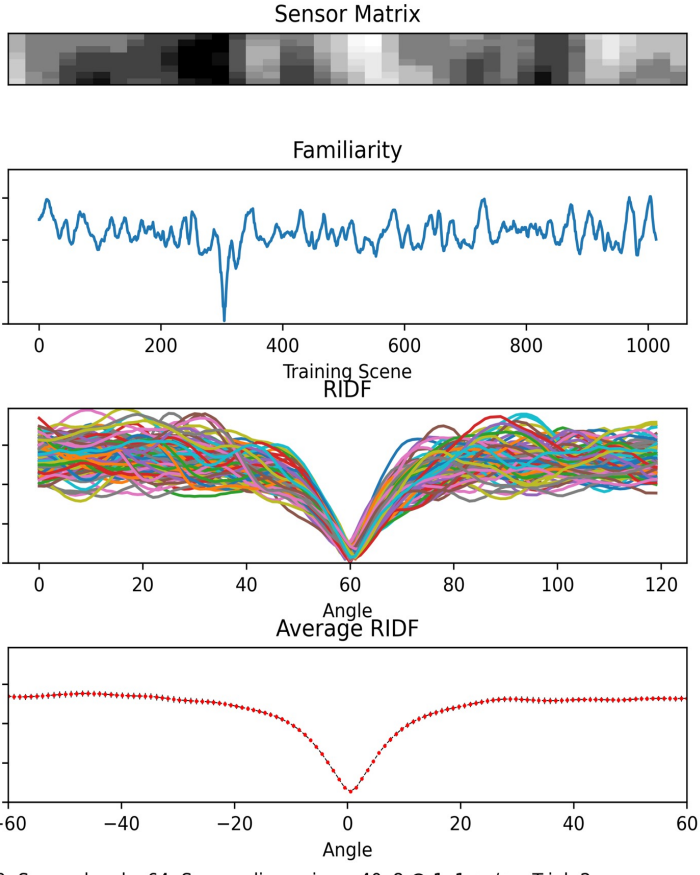


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 34.71; RMSD/dist: 0.087; TD: 5141; p90: 22; p50: 10; complete: 0

100%

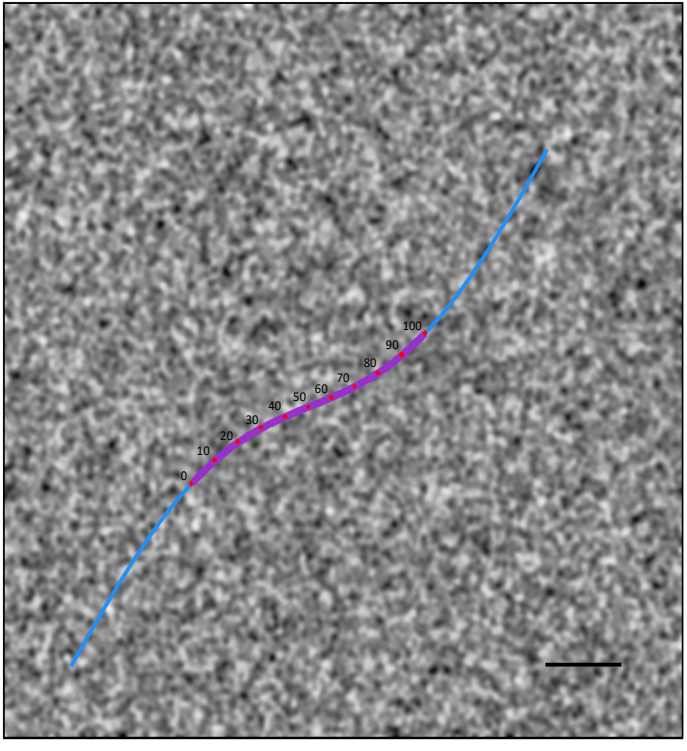


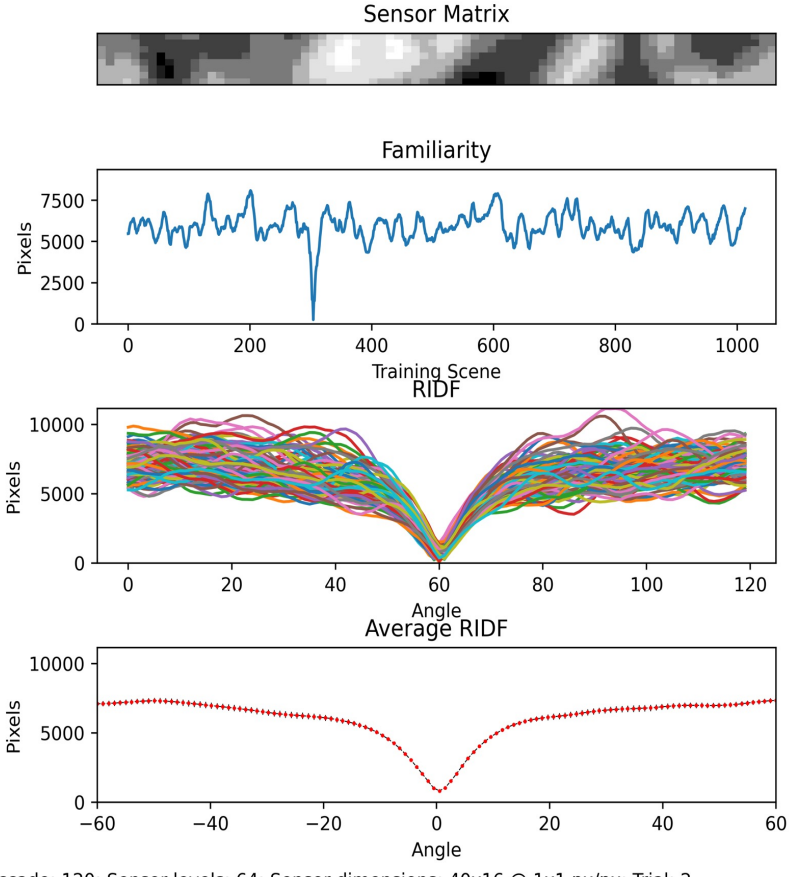


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 52.10; RMSD/dist: 0.130; TD: 4904; p90: 22; p50: 10; complete: 0

100%

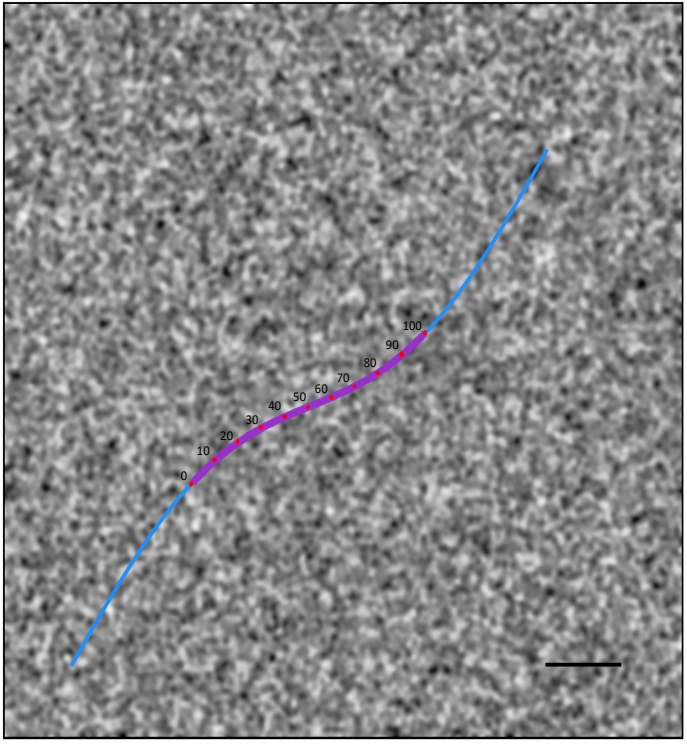


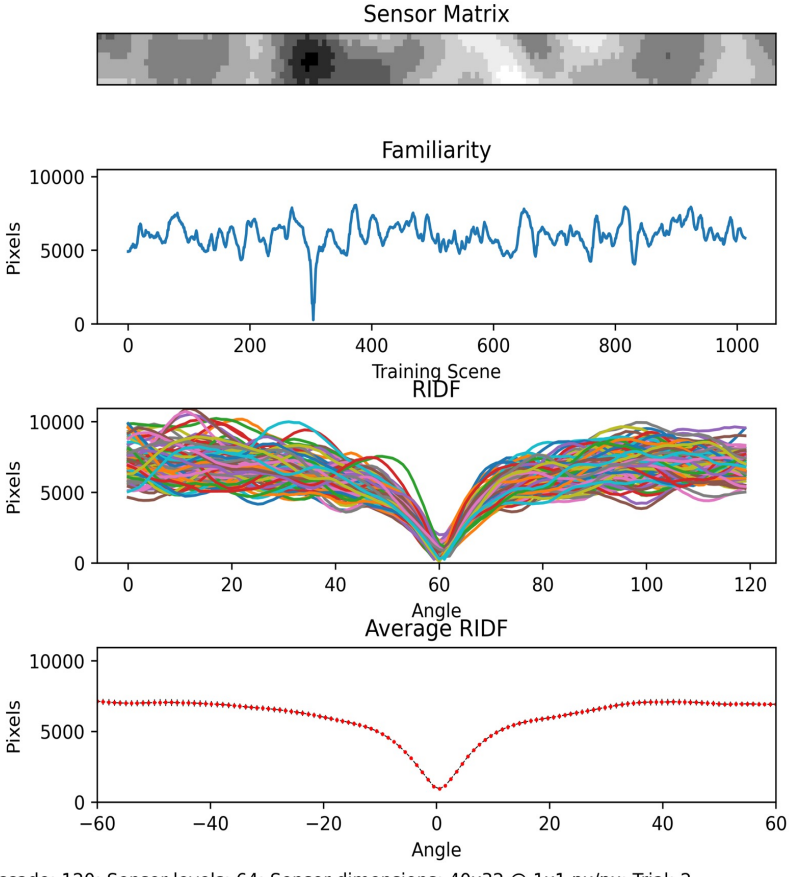


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 65.76; RMSD/dist: 0.164; TD: 4960; p90: 24; p50: 12; complete: 0

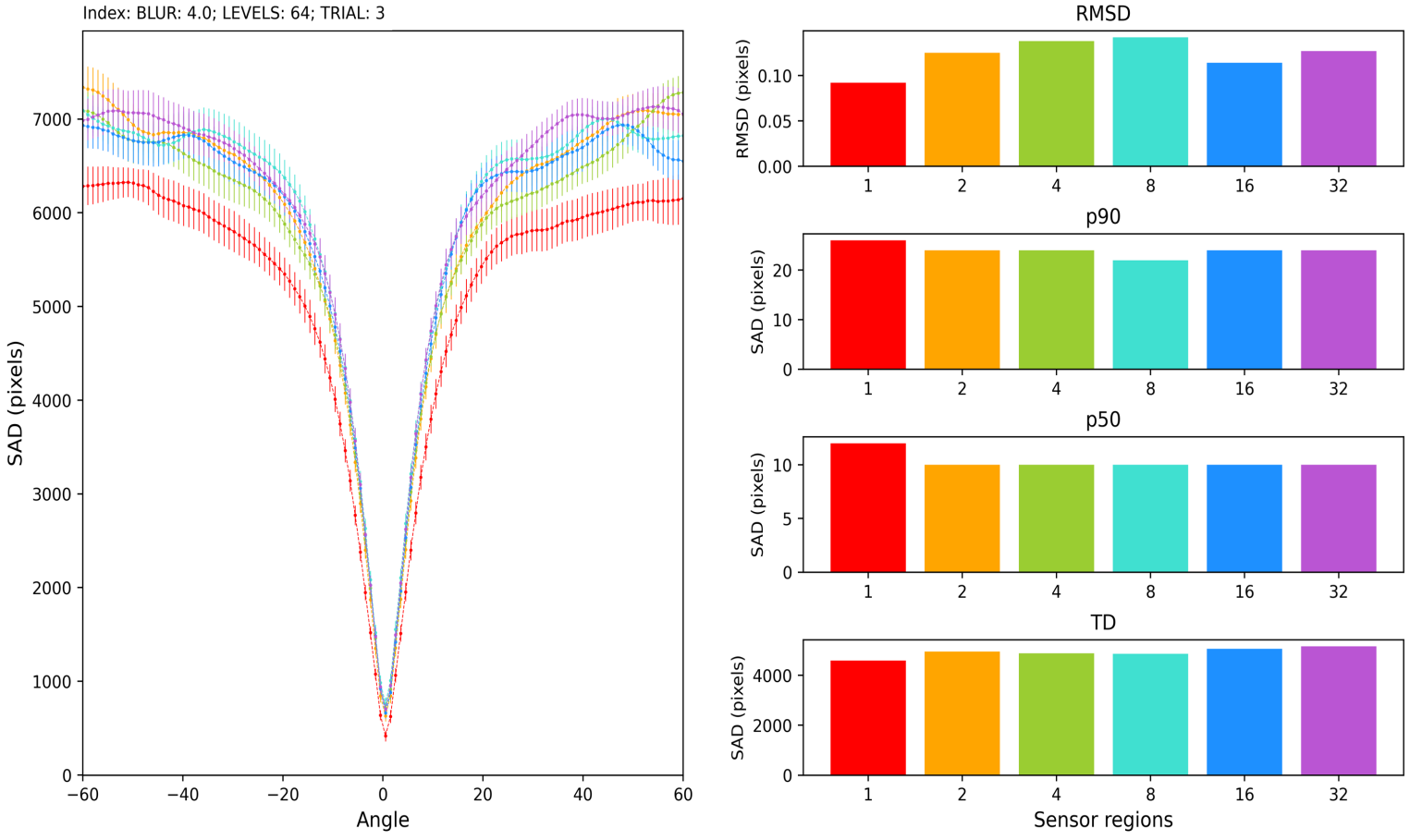
100%



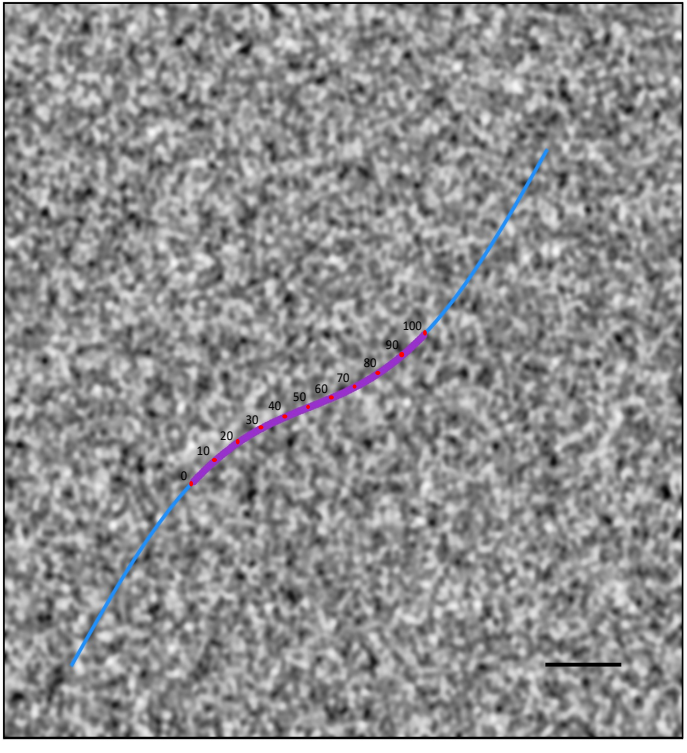


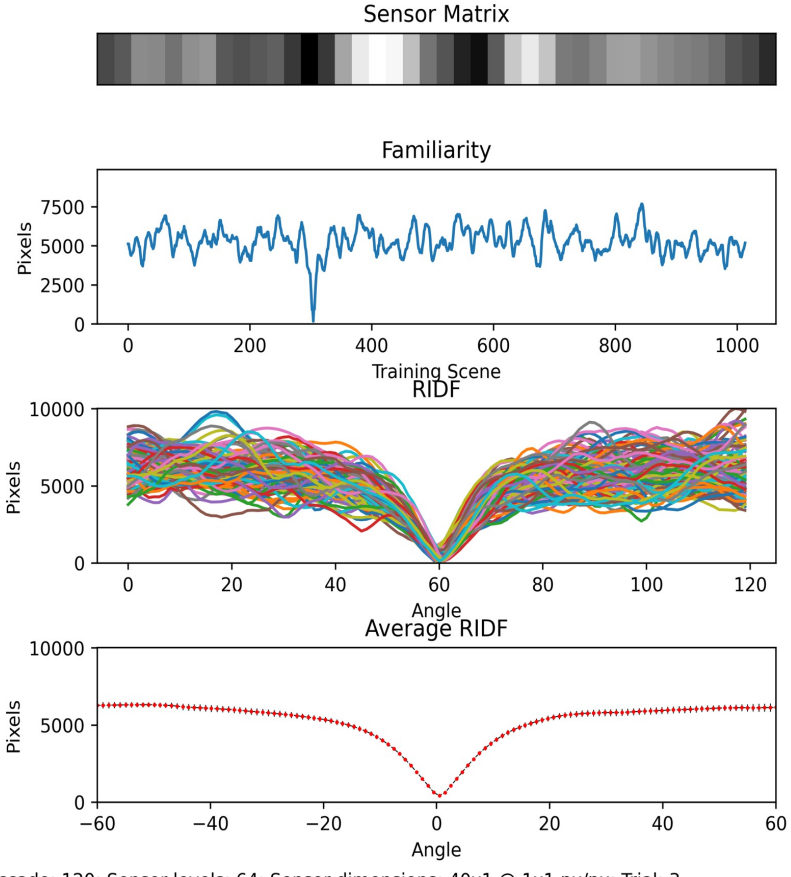
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 82.42; RMSD/dist: 0.206; TD: 4883; p90: 26; p50: 12; complete: 0


Index: BLUR: 4.0; LEVELS: 64; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

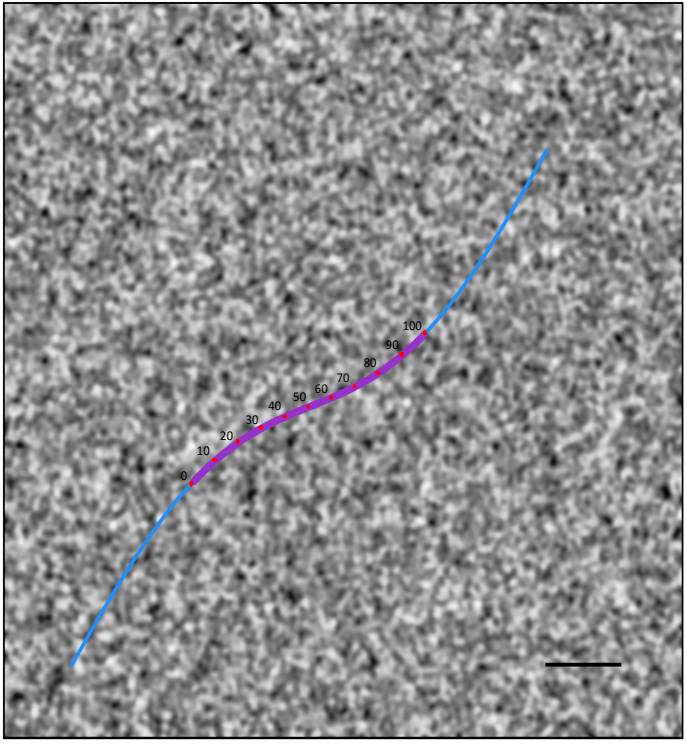


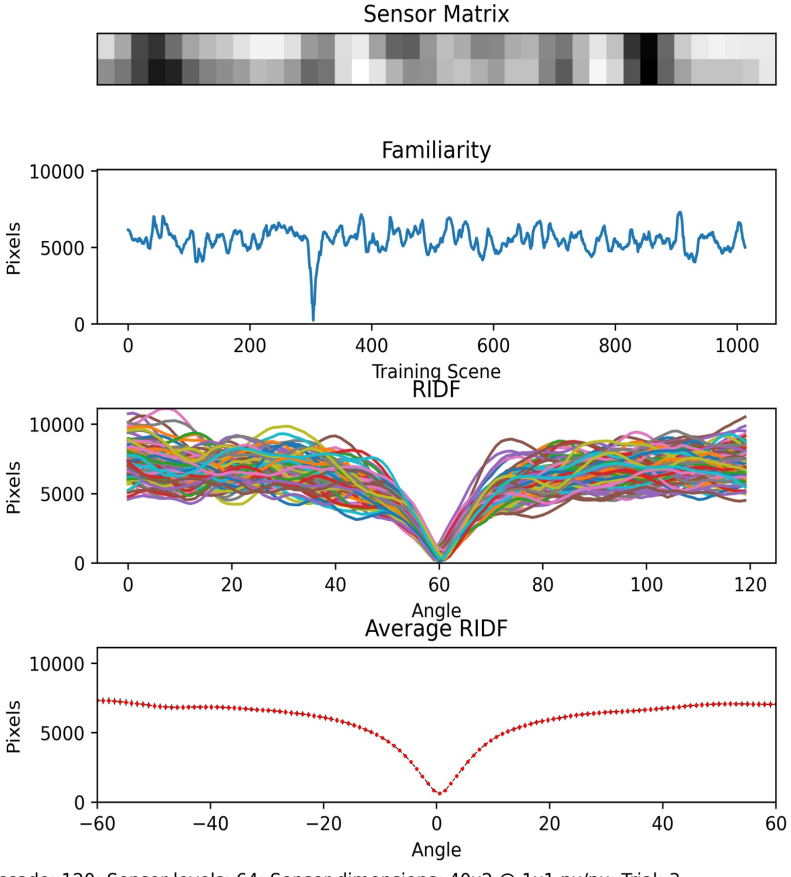


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 36.96; RMSD/dist: 0.092; TD: 4595; p90: 26; p50: 12; complete: 0

100%

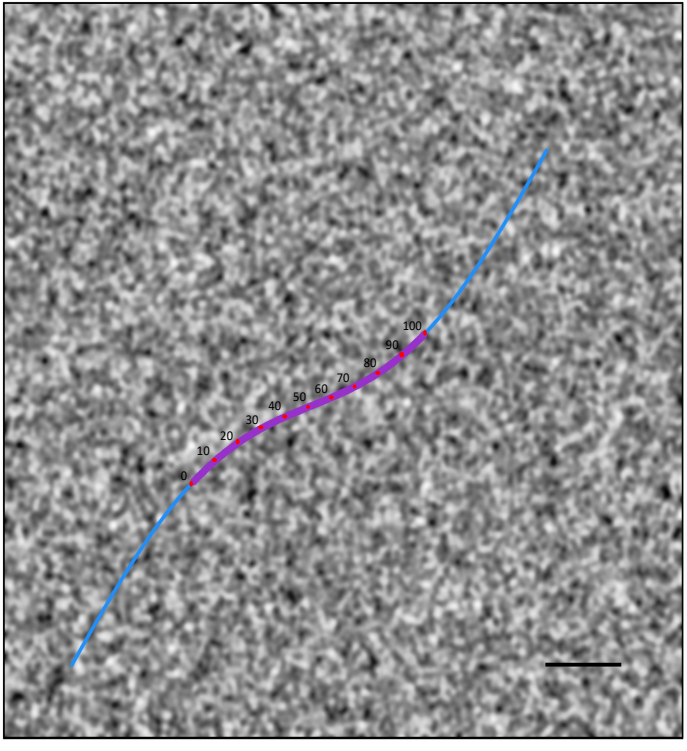


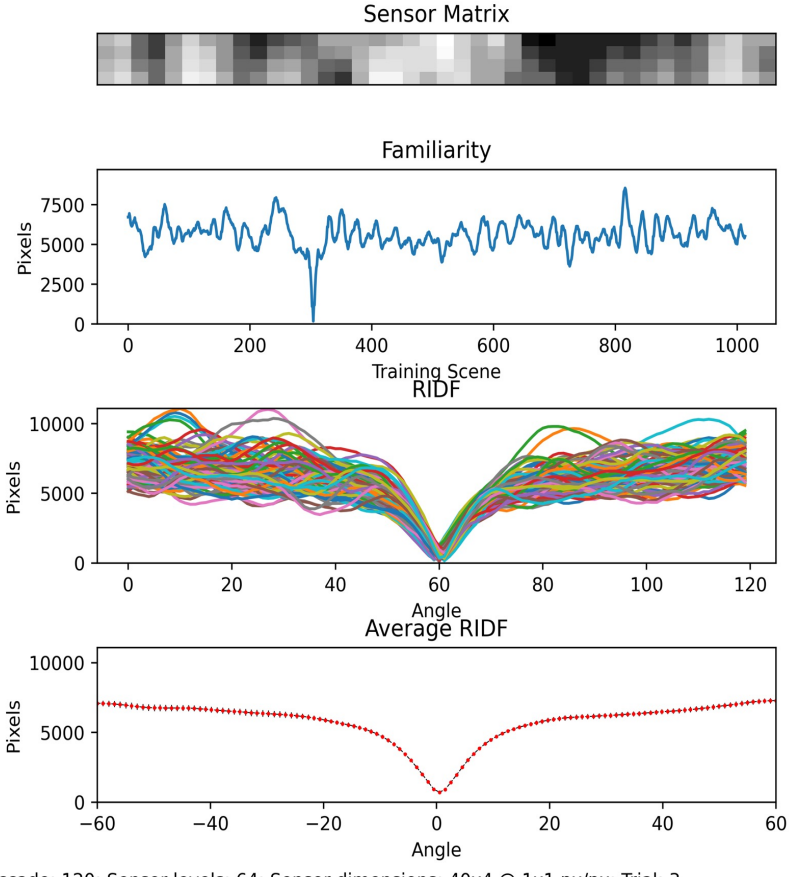


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 50.11; RMSD/dist: 0.125; TD: 4954; p90: 24; p50: 10; complete: 0

100%

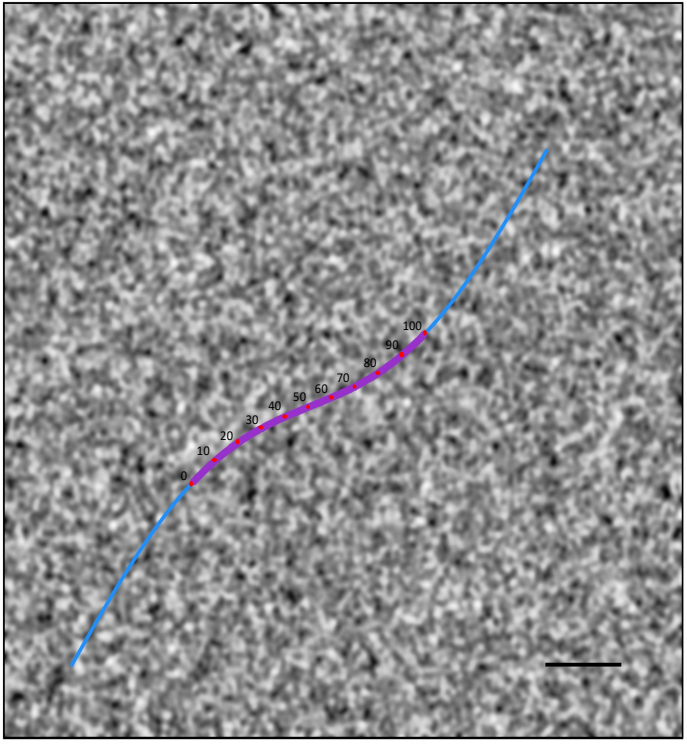


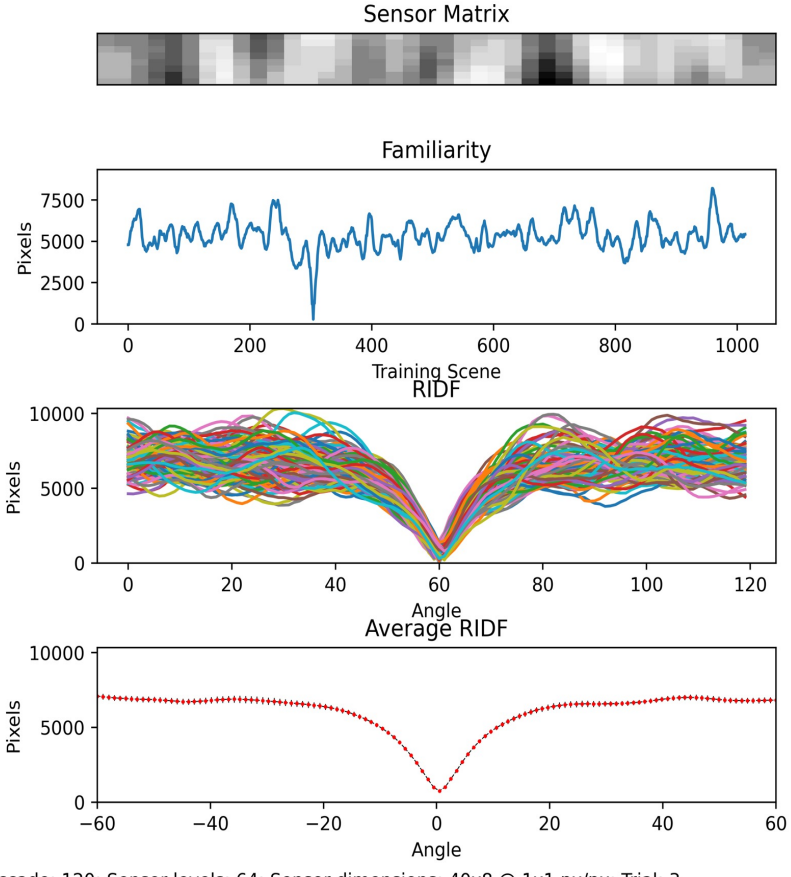


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 55.39; RMSD/dist: 0.138; TD: 4876; p90: 24; p50: 10; complete: 0

100%

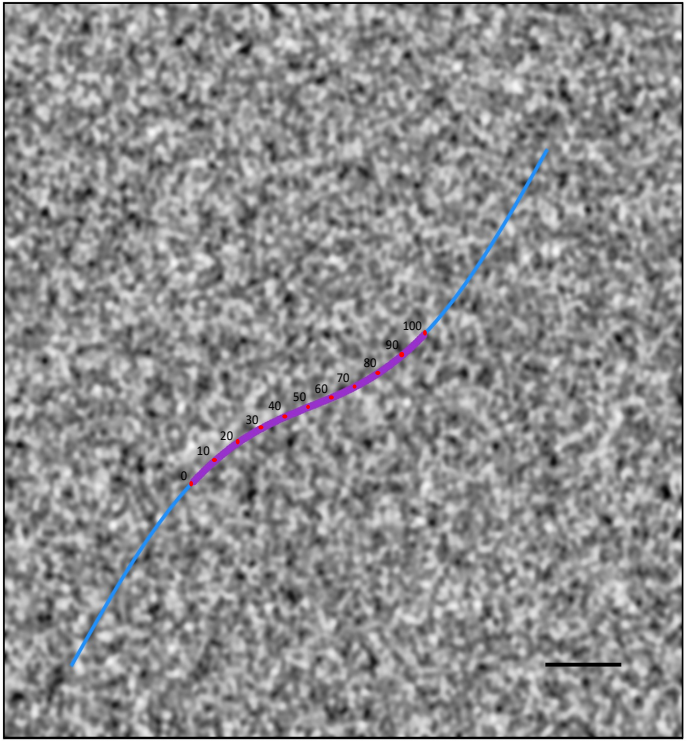


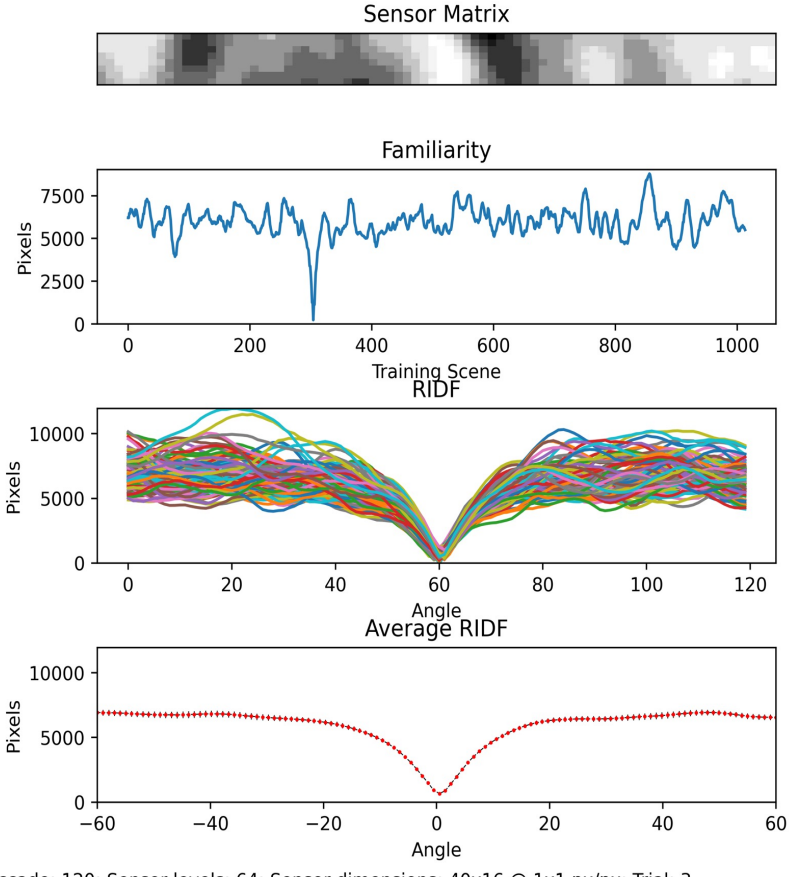


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 56.64; RMSD/dist: 0.142; TD: 4858; p90: 22; p50: 10; complete: 0

100%

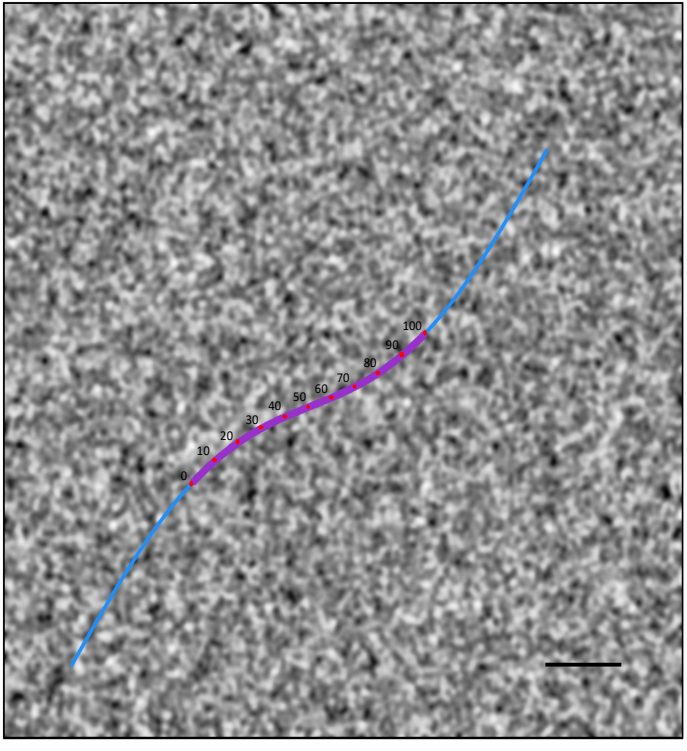


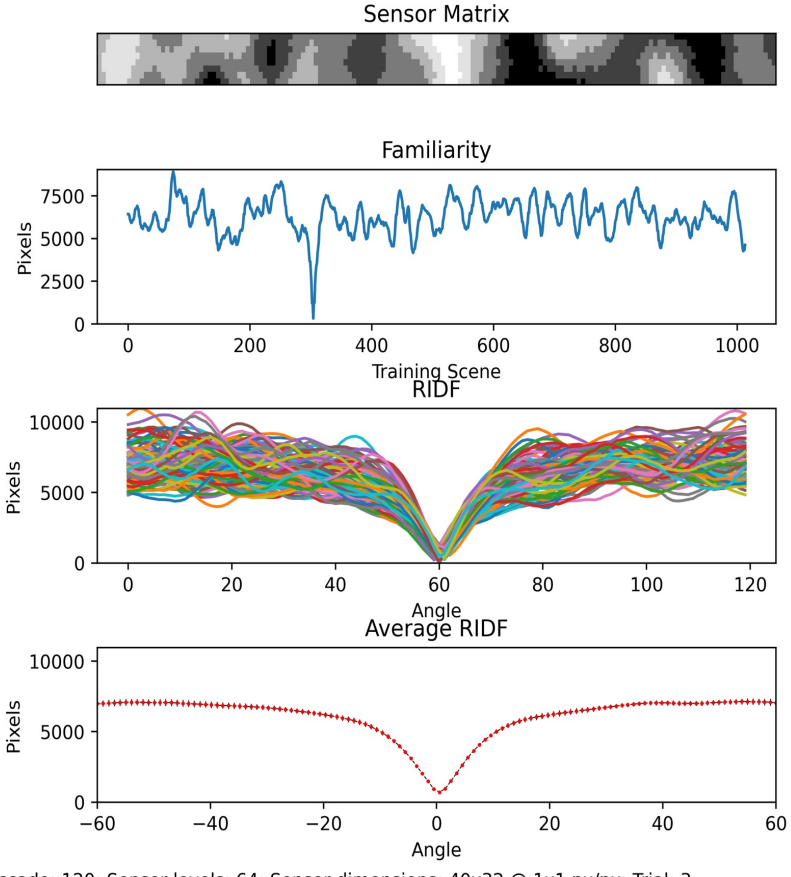


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 45.77; RMSD/dist: 0.114; TD: 5057; p90: 24; p50: 10; complete: 0

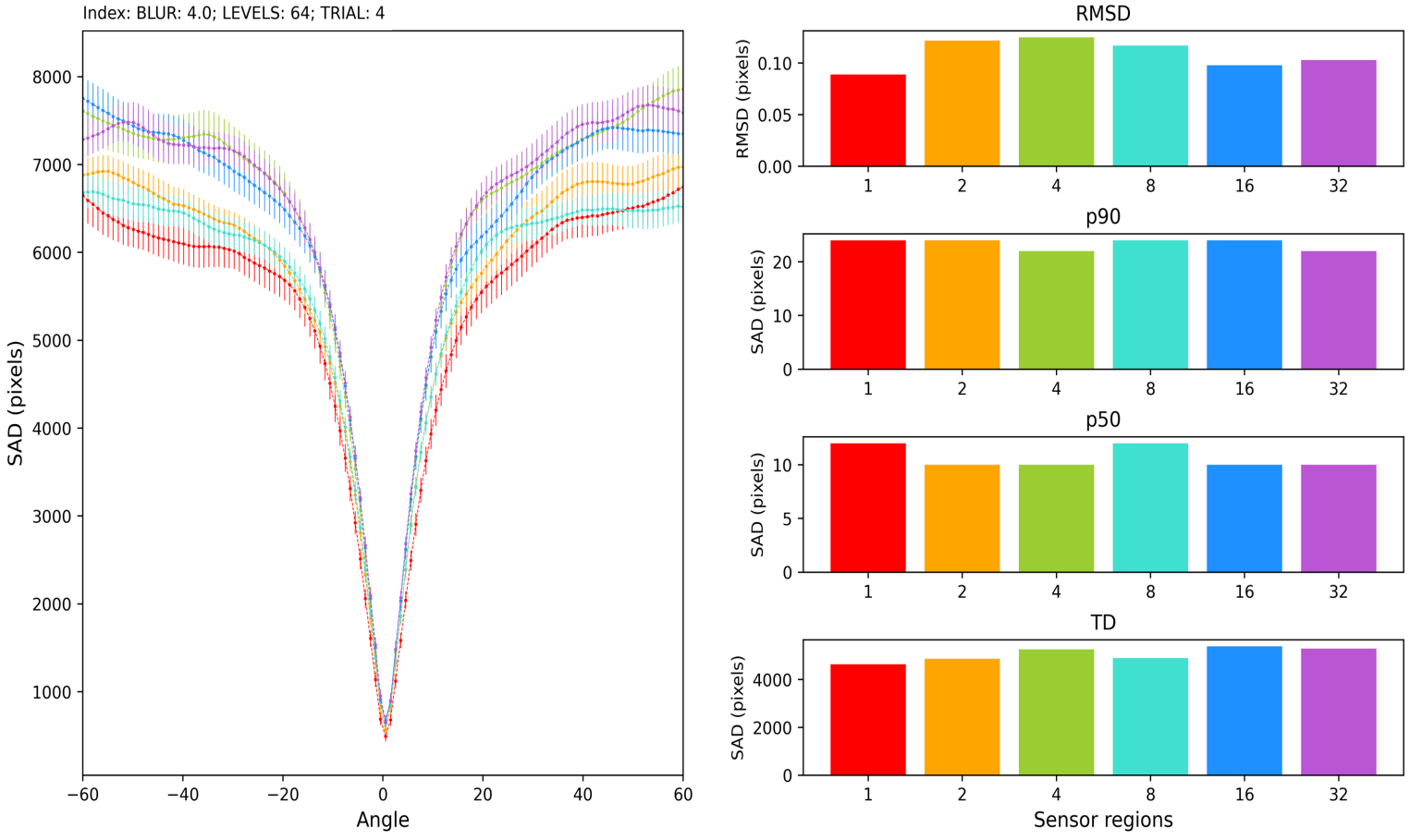
100%



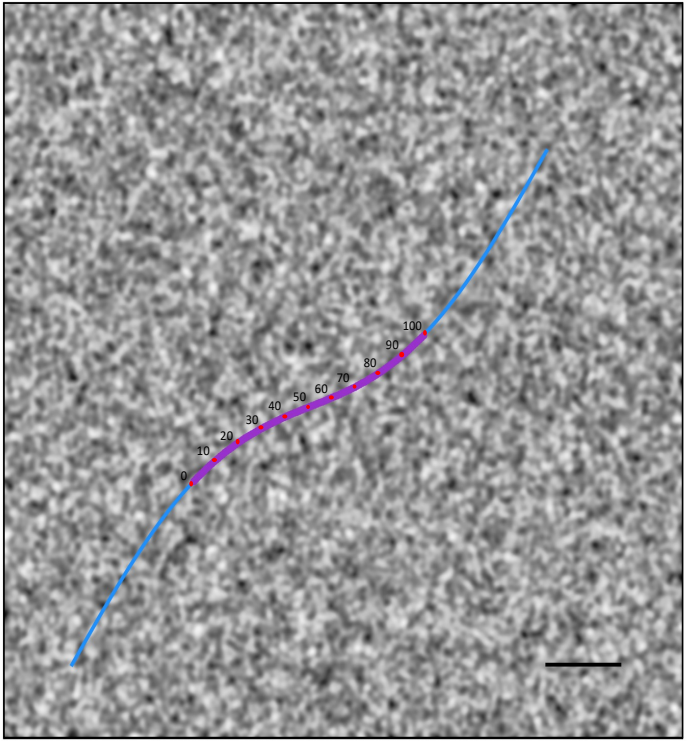


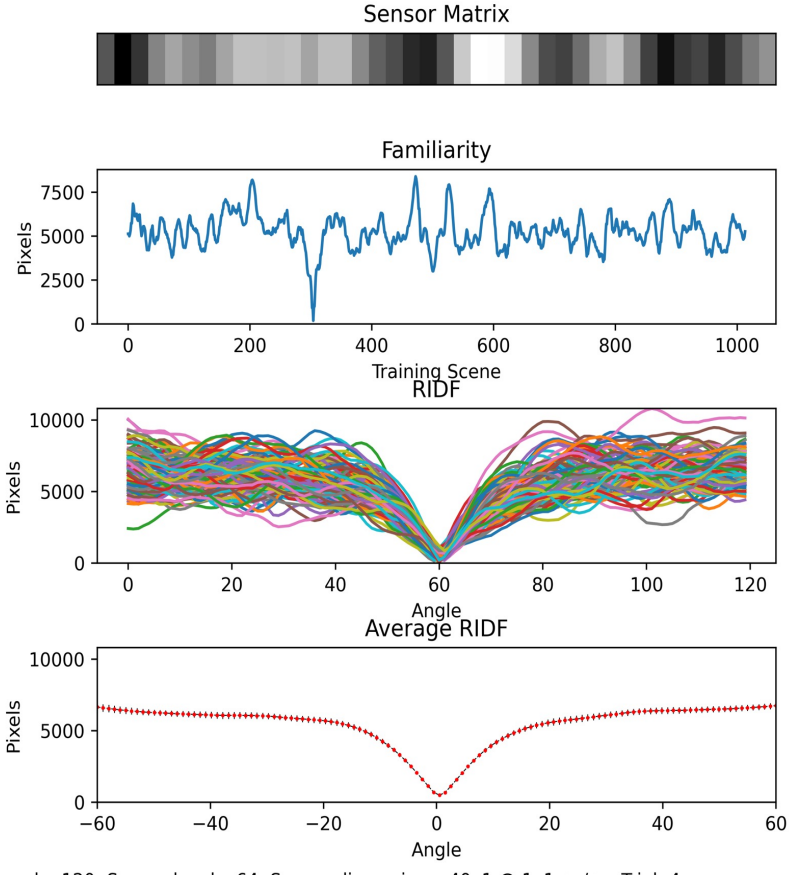
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 50.92; RMSD/dist: 0.127; TD: 5161; p90: 24; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 64; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

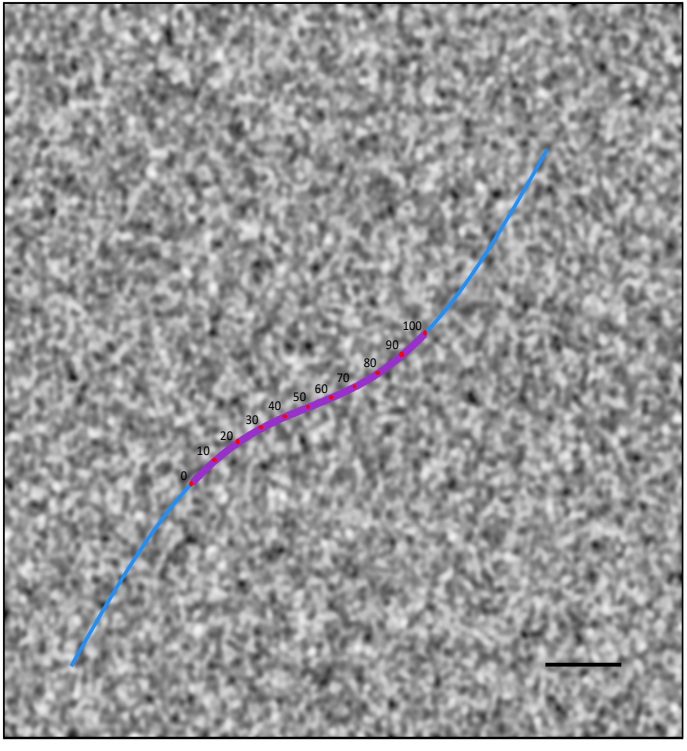


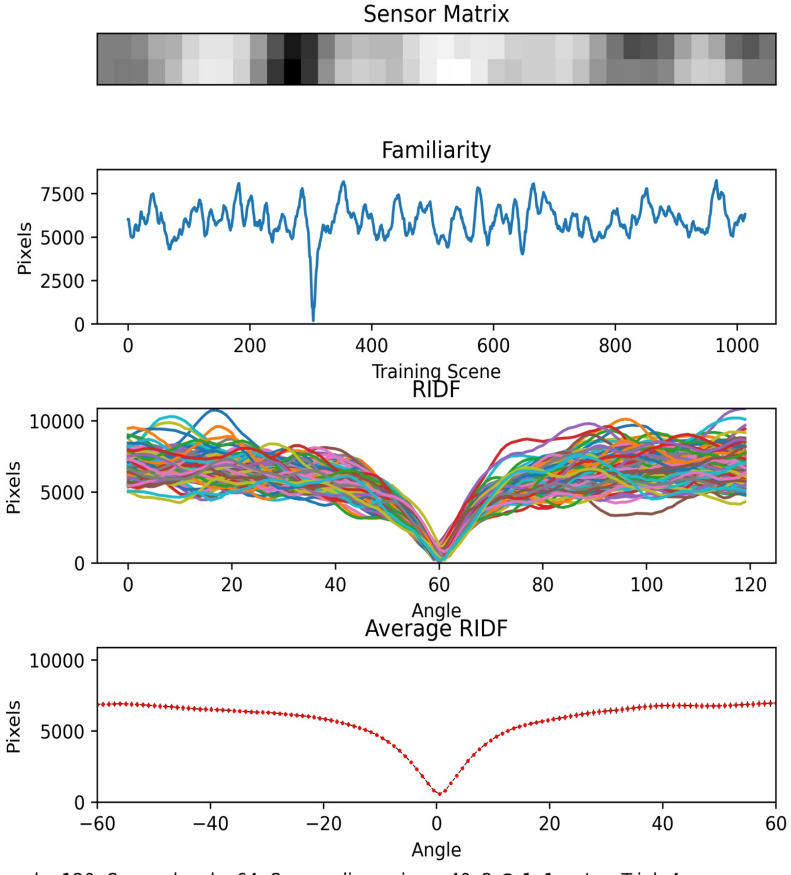


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 35.40; RMSD/dist: 0.089; TD: 4636; p90: 24; p50: 12; complete: 0

100%

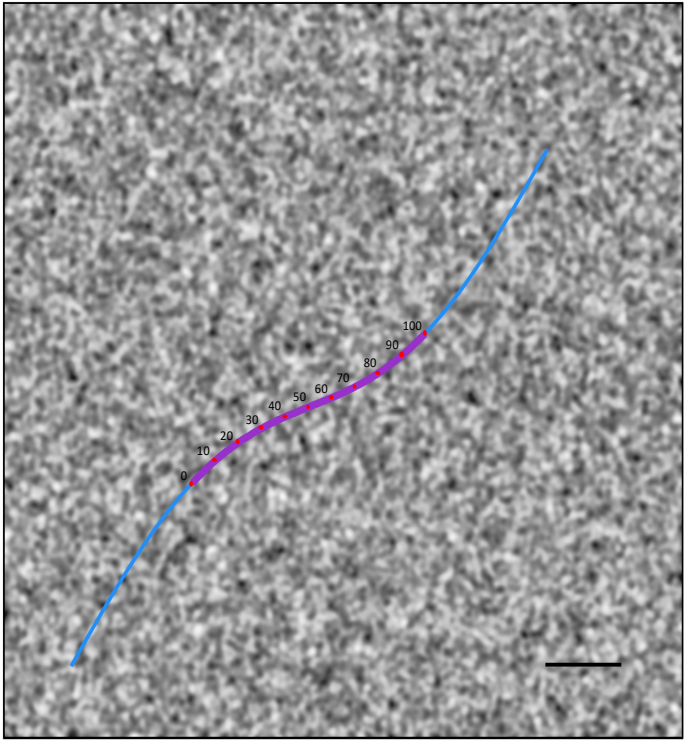


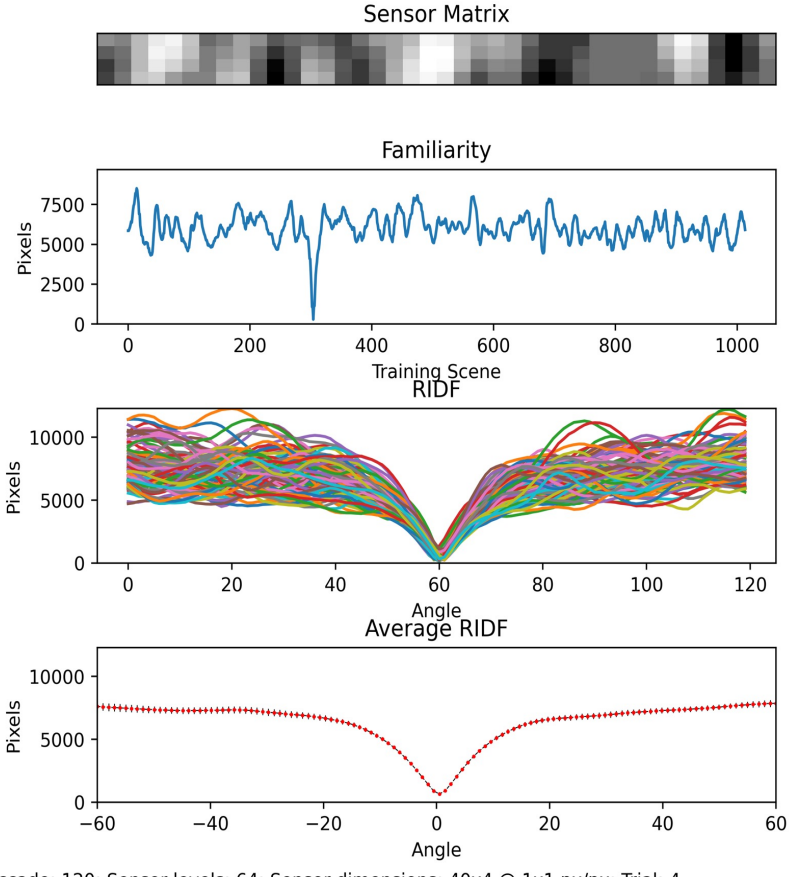


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 48.89; RMSD/dist: 0.122; TD: 4864; p90: 24; p50: 10; complete: 0

100%

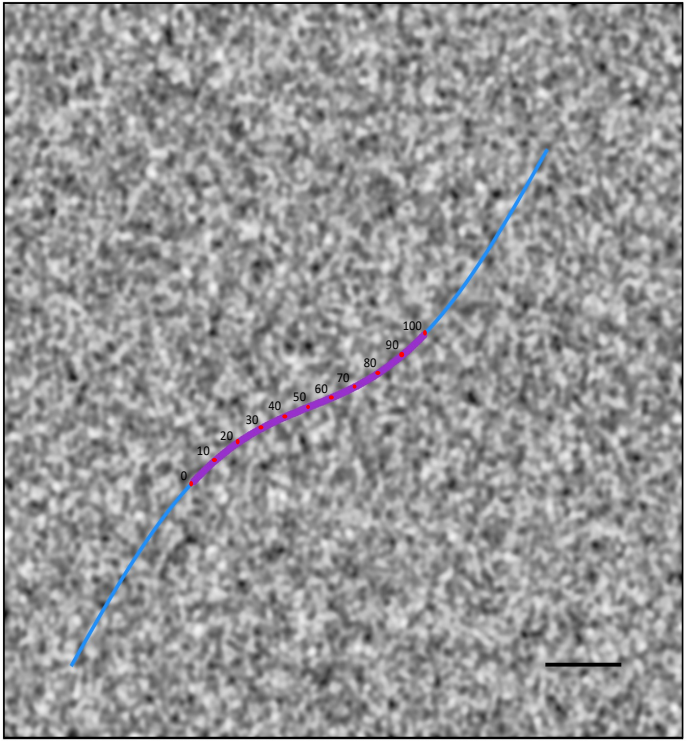


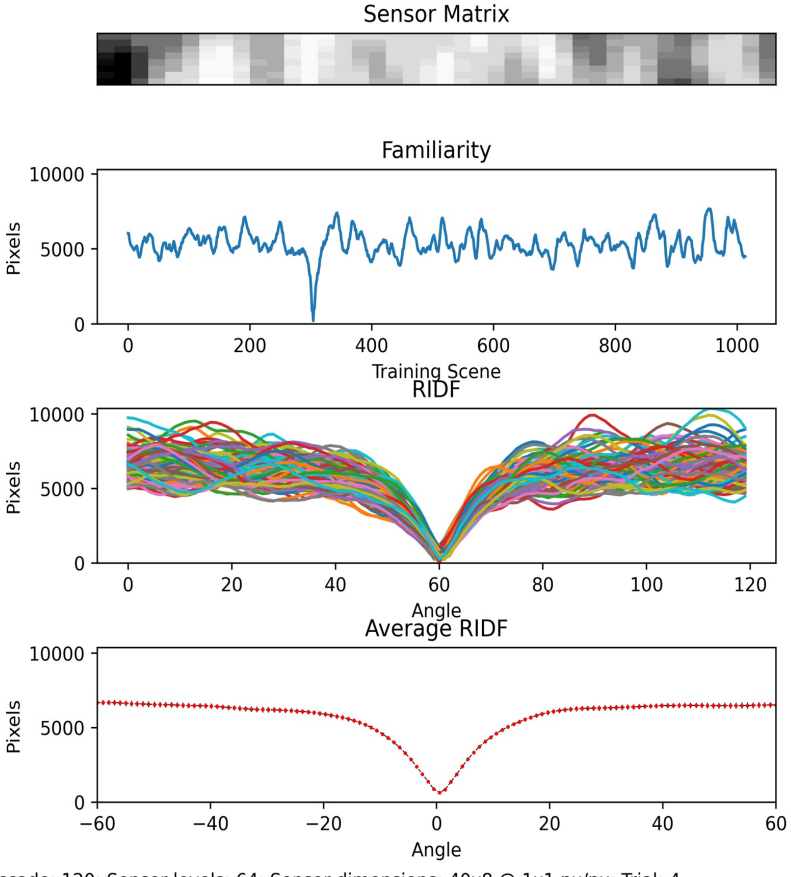


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 49.84; RMSD/dist: 0.125; TD: 5265; p90: 22; p50: 10; complete: 0

100%

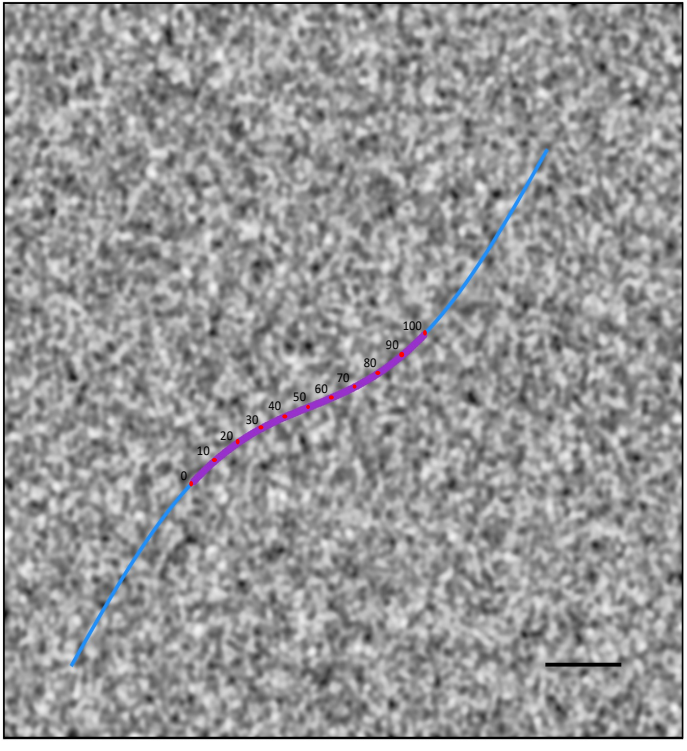


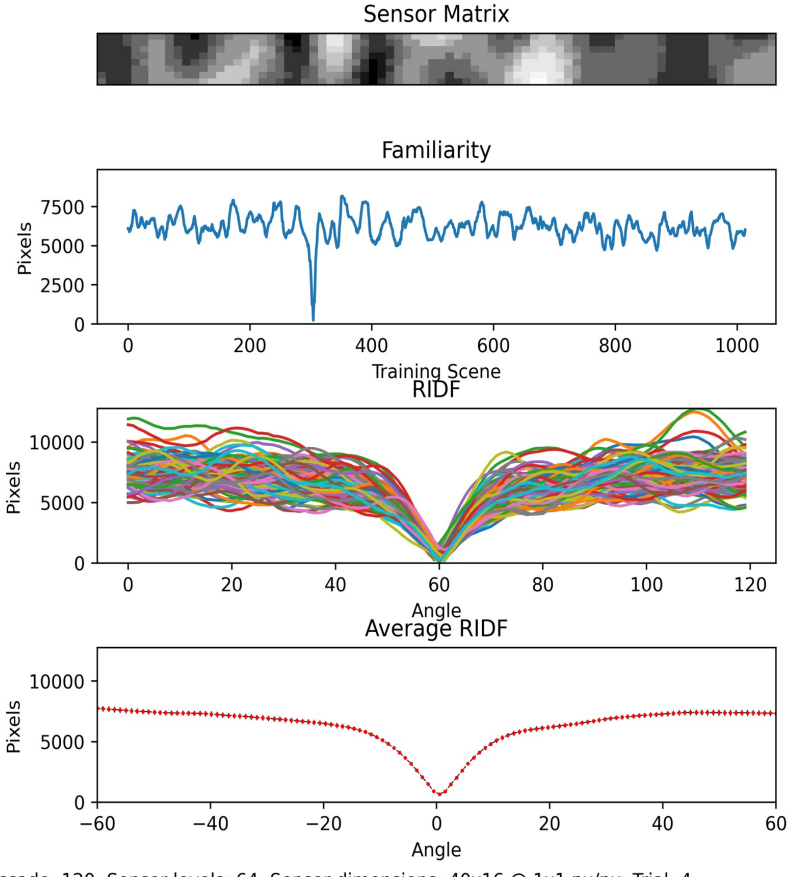


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 46.63; RMSD/dist: 0.117; TD: 4897; p90: 24; p50: 12; complete: 0

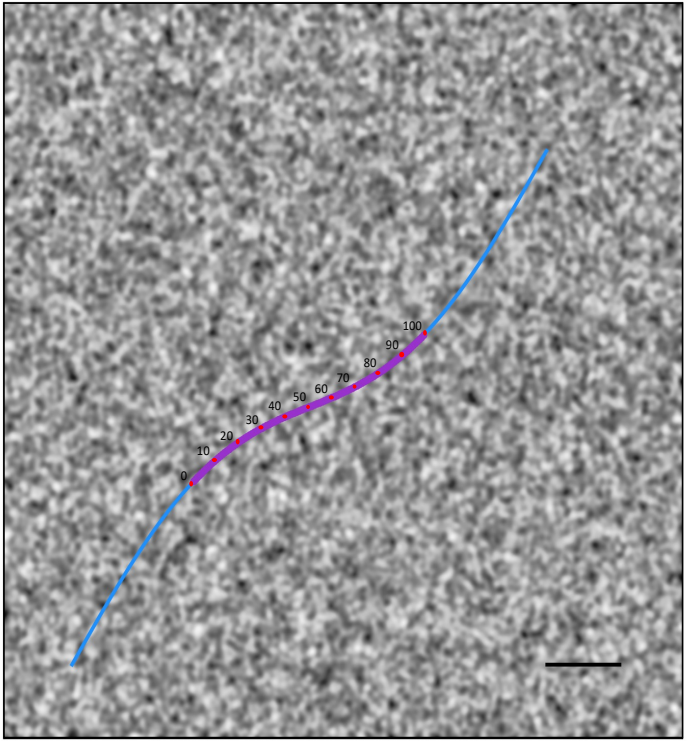
100%

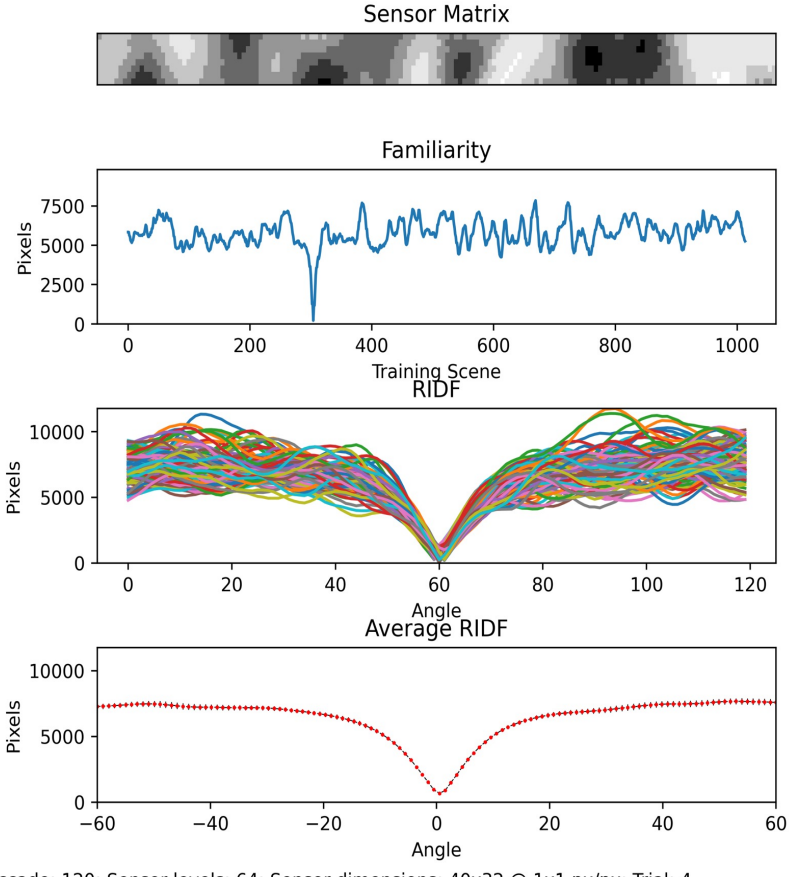




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 39.21; RMSD/dist: 0.098; TD: 5389; p90: 24; p50: 10; complete: 0

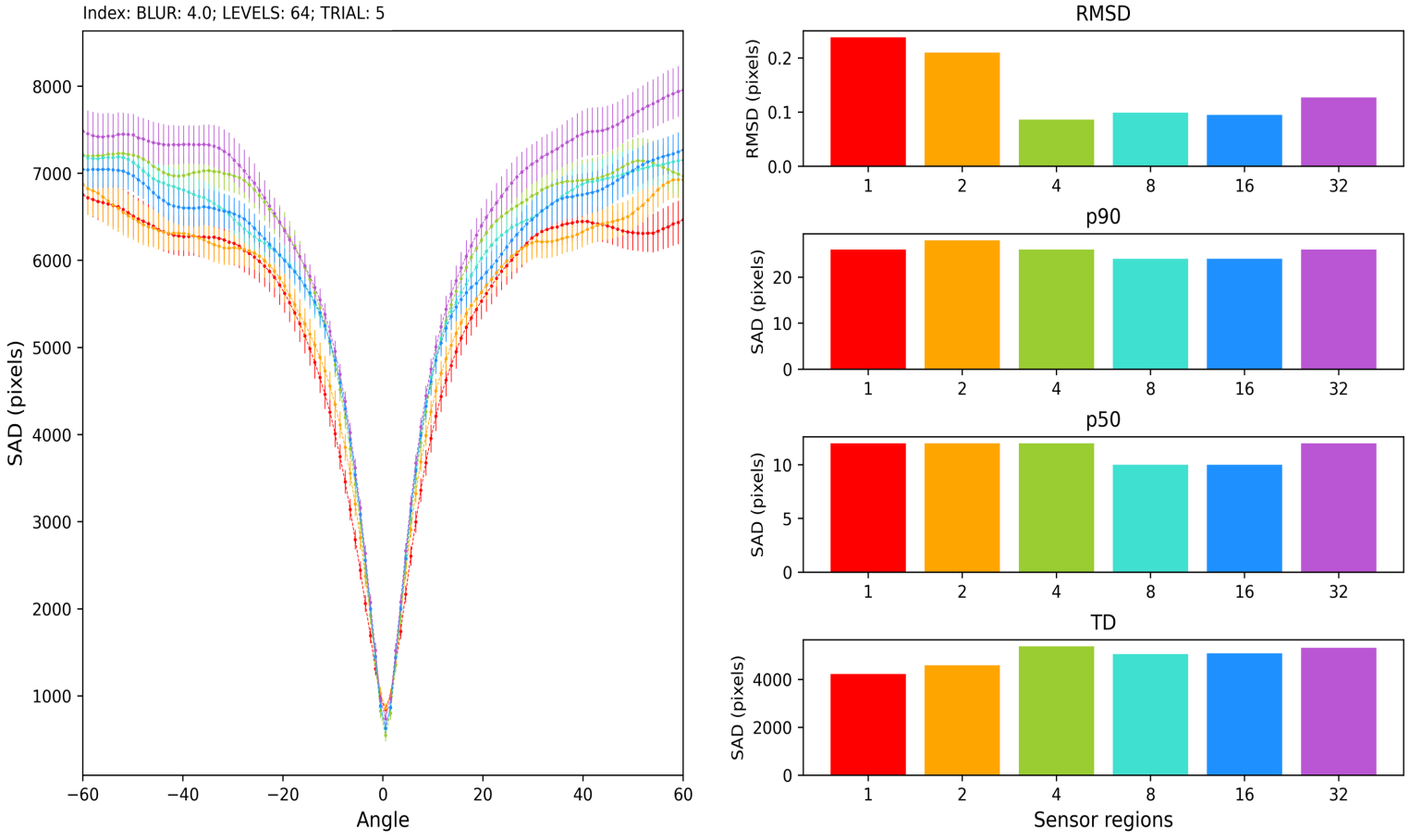
100%



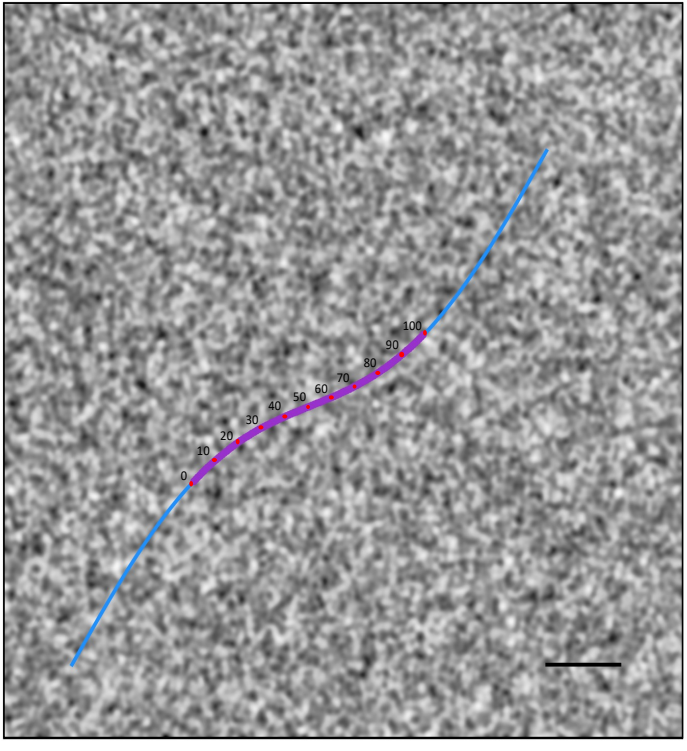


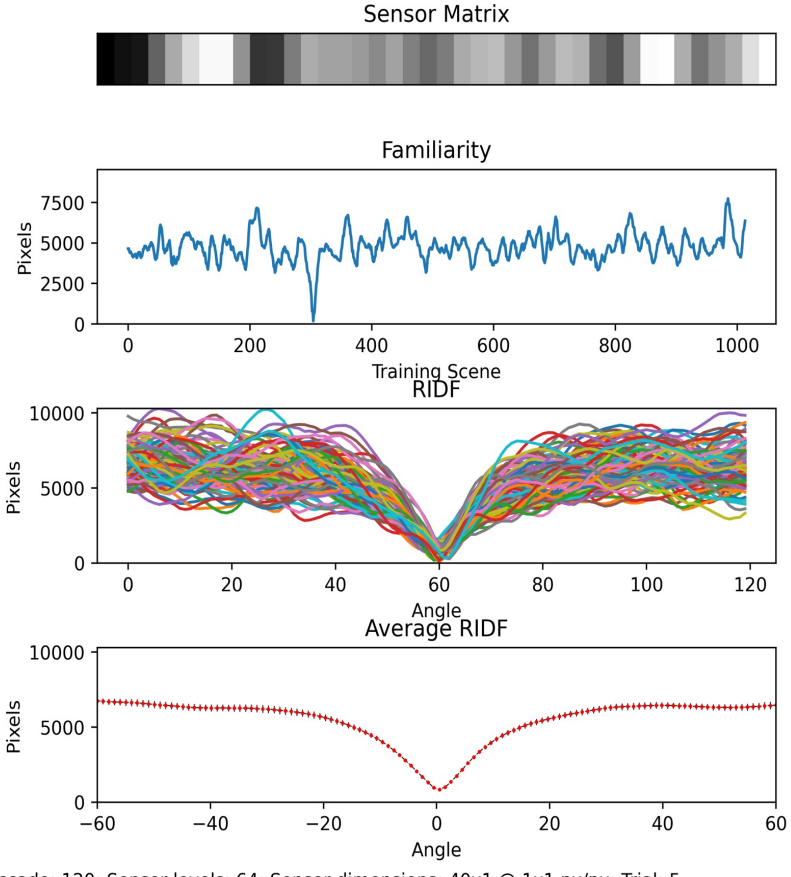
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 41.03; RMSD/dist: 0.103; TD: 5298; p90: 22; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 64; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

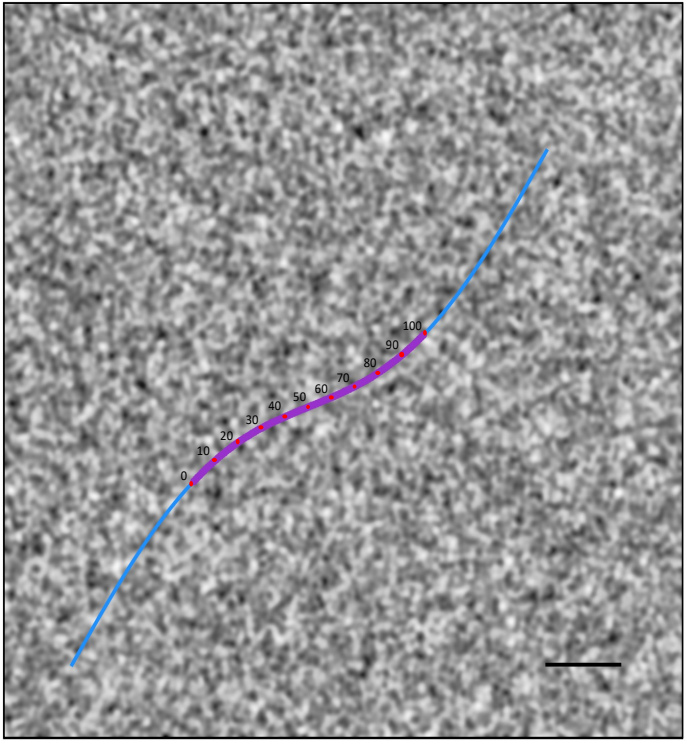


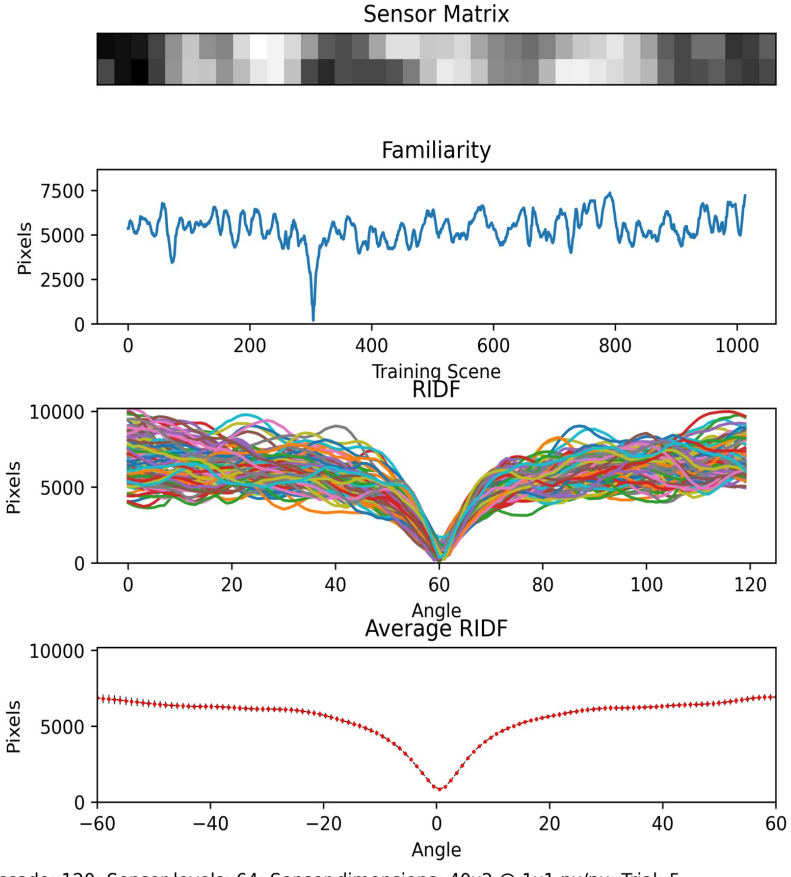


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 95.08; RMSD/dist: 0.238; TD: 4228; p90: 26; p50: 12; complete: 0

100%

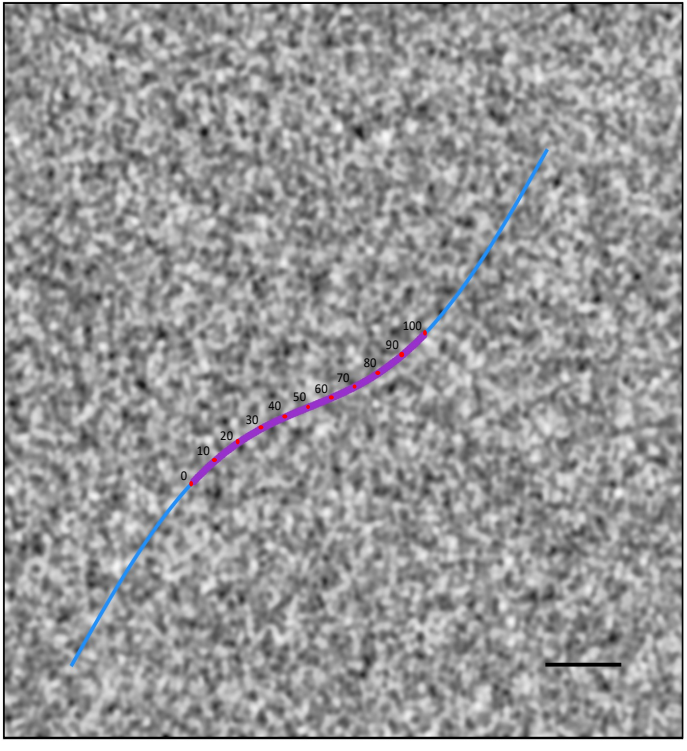


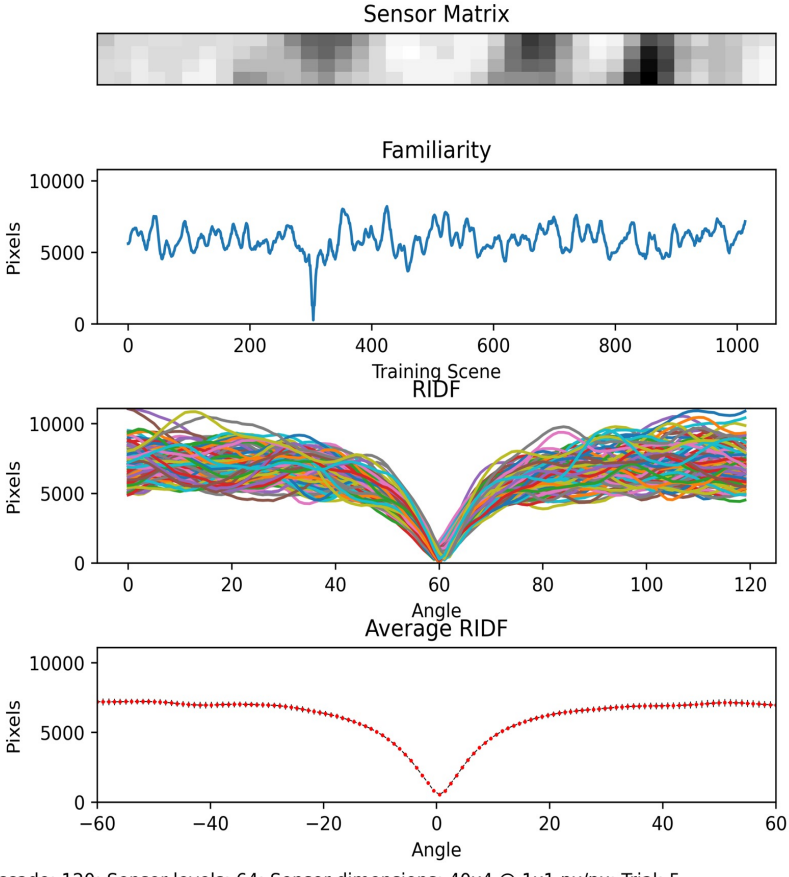


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 83.86; RMSD/dist: 0.210; TD: 4584; p90: 28; p50: 12; complete: 0

100%

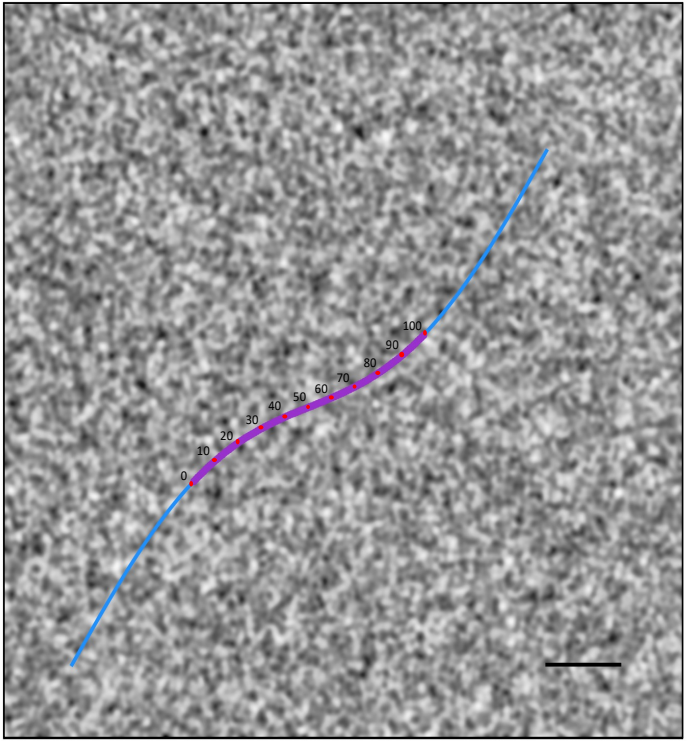


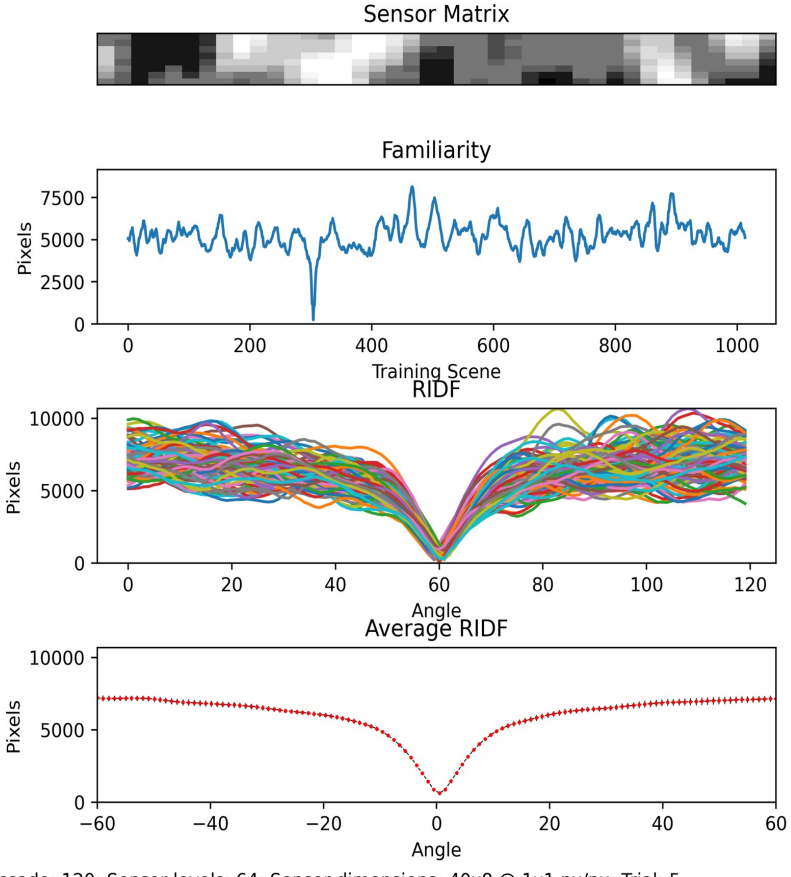


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 34.33; RMSD/dist: 0.086; TD: 5382; p90: 26; p50: 12; complete: 0

100%

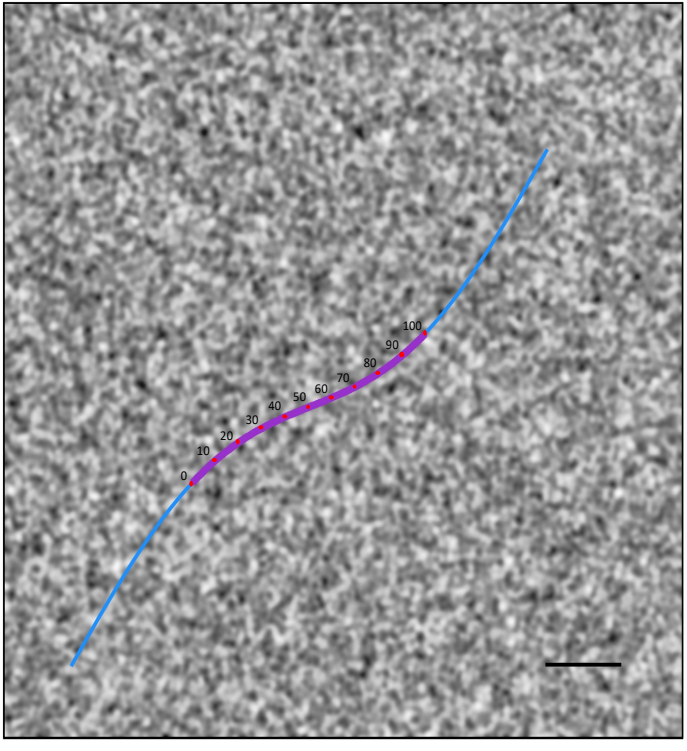


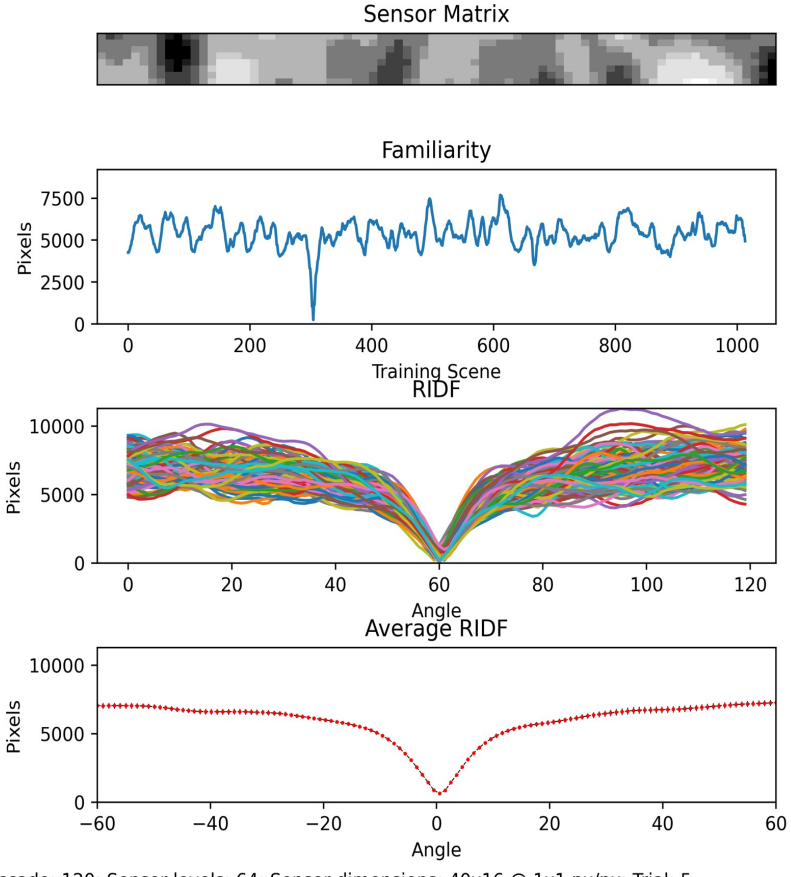


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 39.46; RMSD/dist: 0.099; TD: 5060; p90: 24; p50: 10; complete: 0

100%

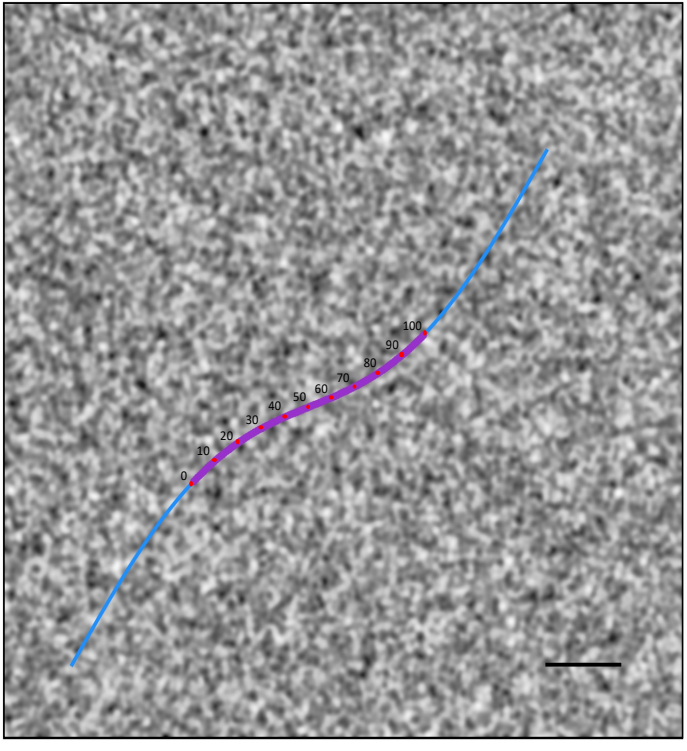


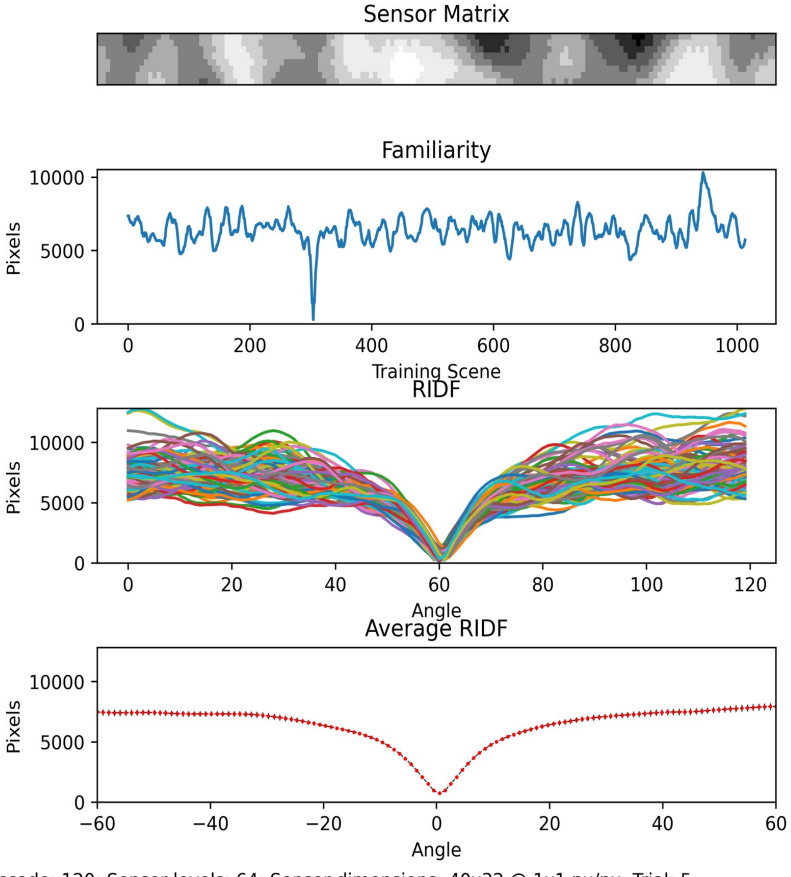


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 37.89; RMSD/dist: 0.095; TD: 5092; p90: 24; p50: 10; complete: 0

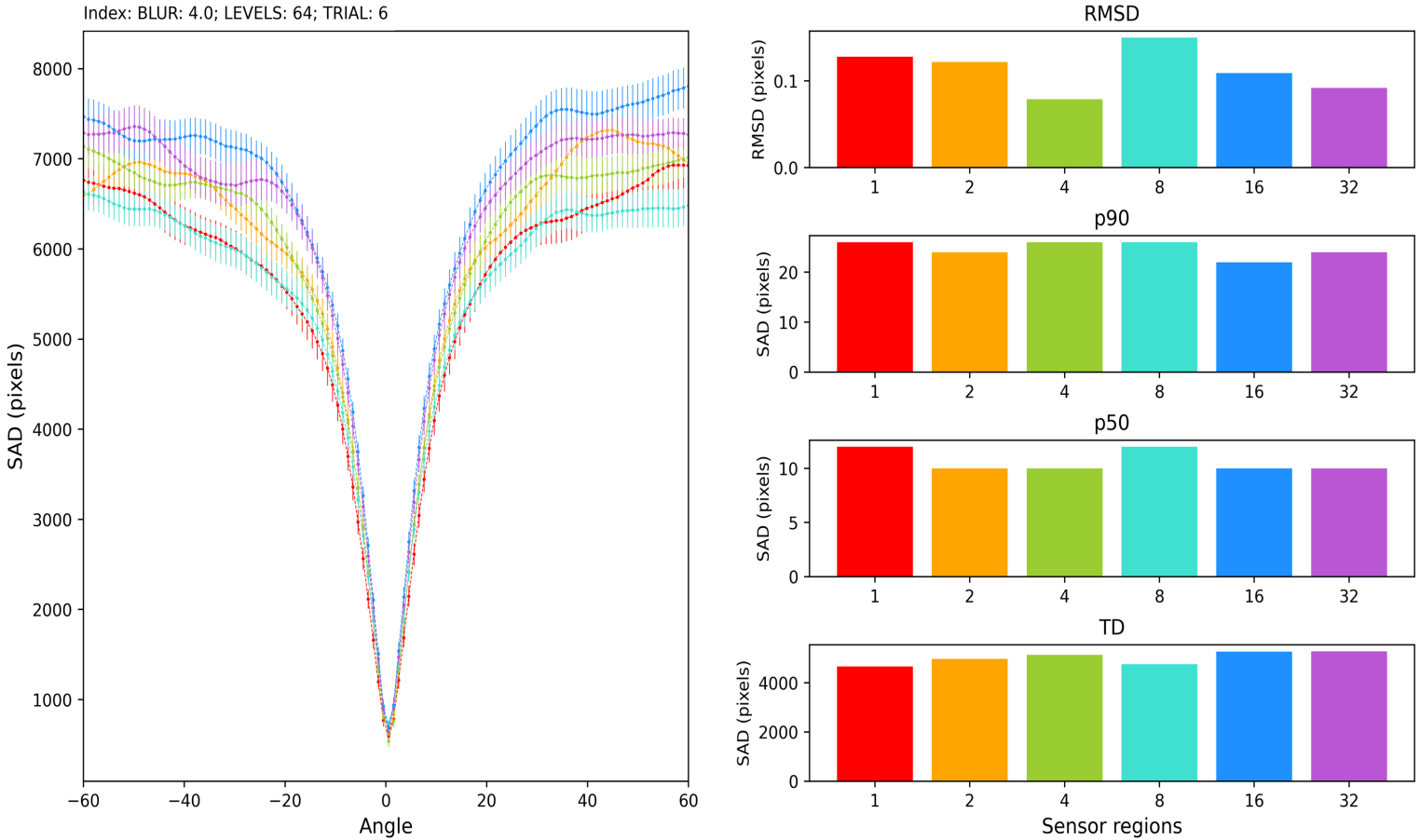
100%



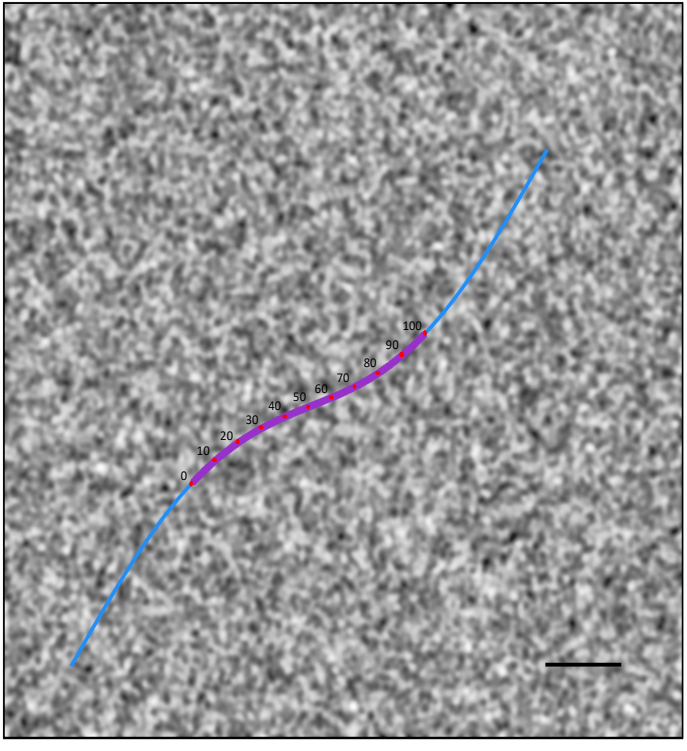


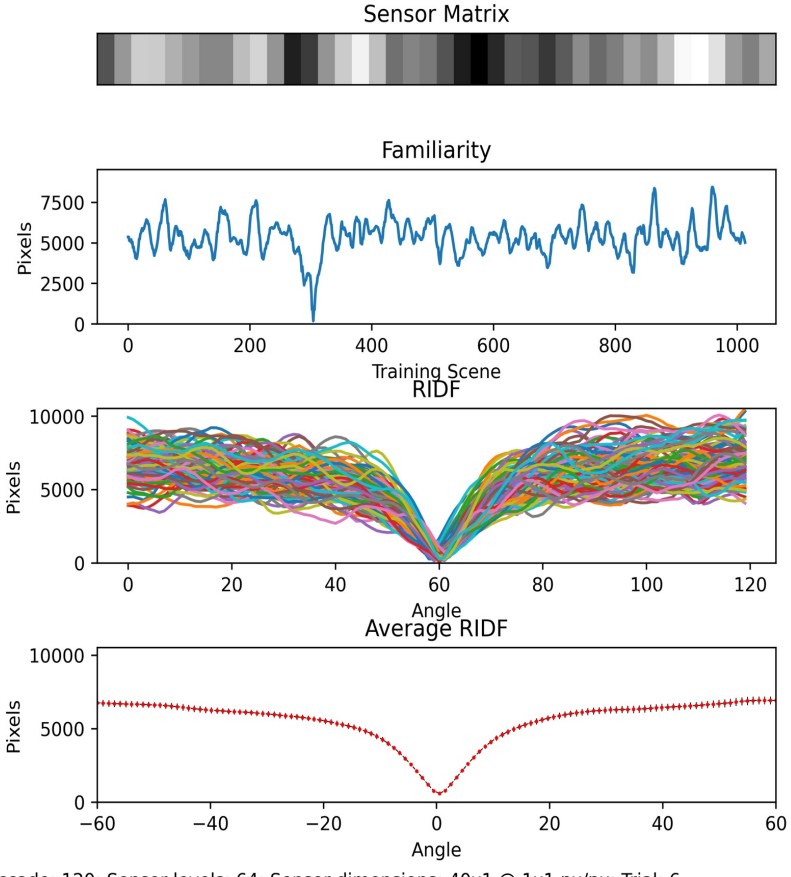
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 50.66; RMSD/dist: 0.127; TD: 5316; p90: 26; p50: 12; complete: 0


Index: BLUR: 4.0; LEVELS: 64; TRIAL: 6
SAD (pixels)
8000
7000
6000
5000
4000
3000
2000
1000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
20
10
0
p50
SAD (pixels)
10
5
0
TD
SAD (pixels)
4000
2000
0
Sensor regions

100%

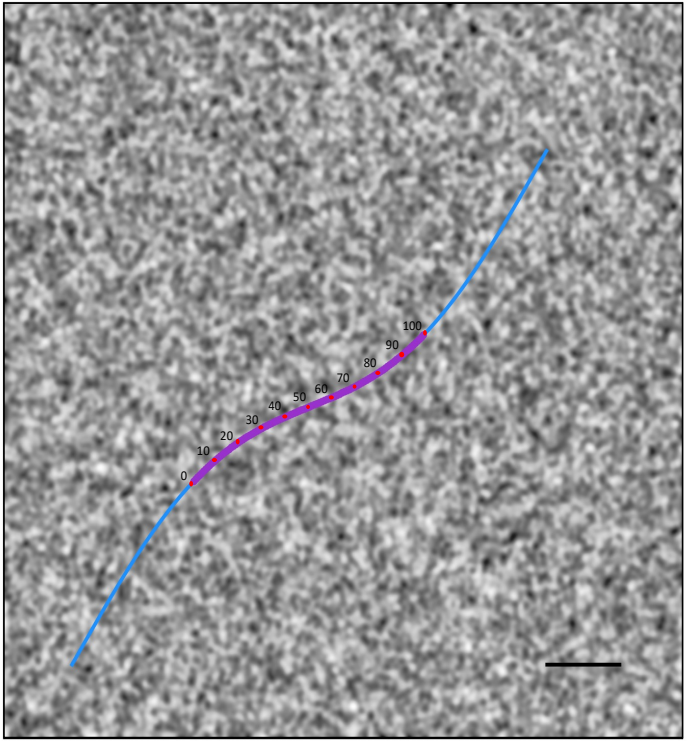


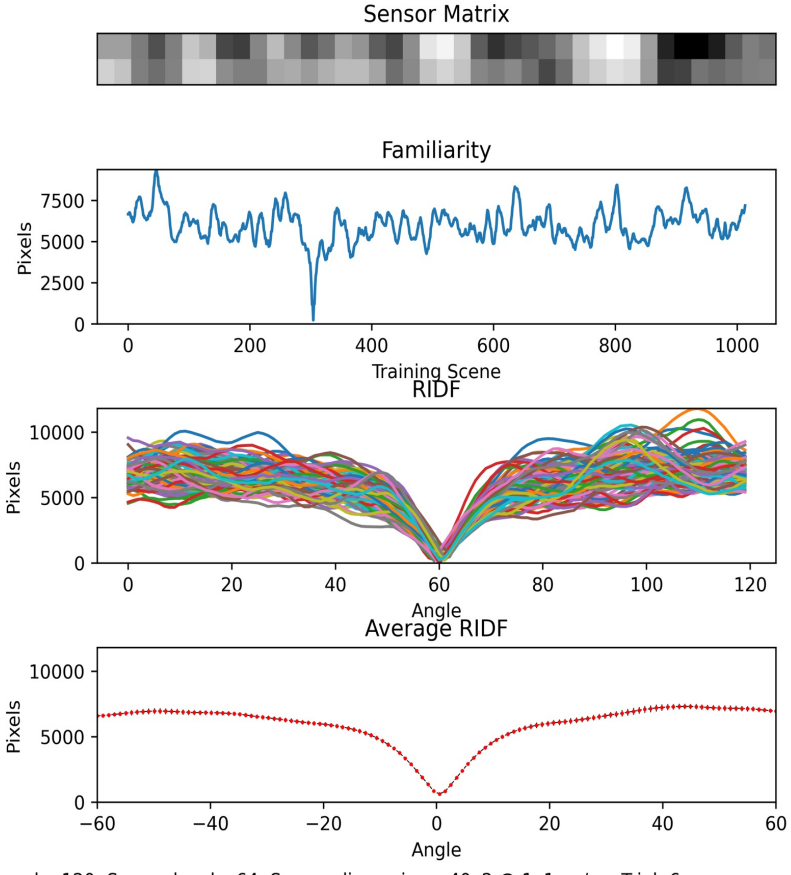


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 51.10; RMSD/dist: 0.128; TD: 4660; p90: 26; p50: 12; complete: 0

100%

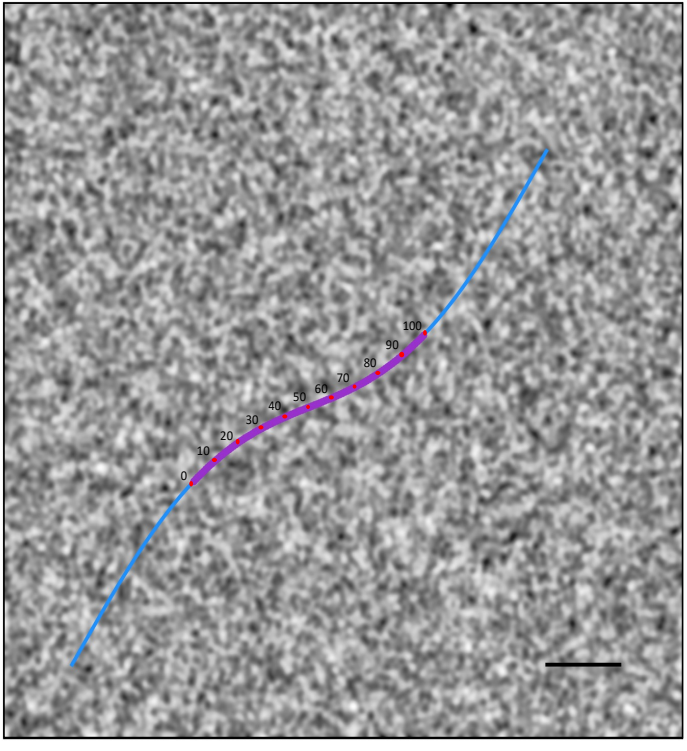


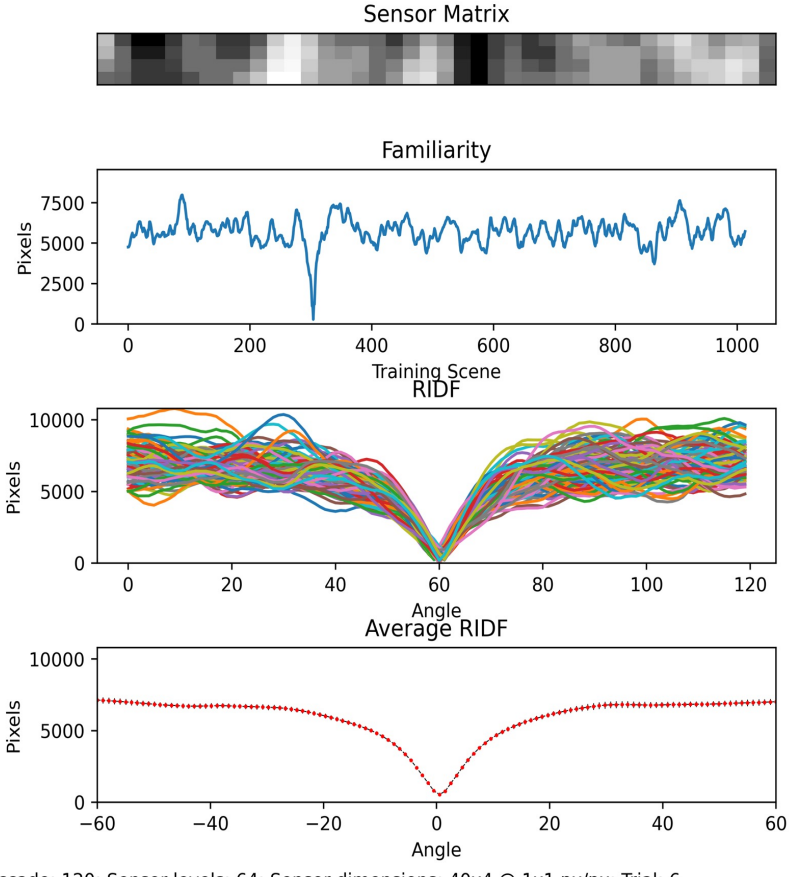


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 48.61; RMSD/dist: 0.122; TD: 4965; p90: 24; p50: 10; complete: 0

100%

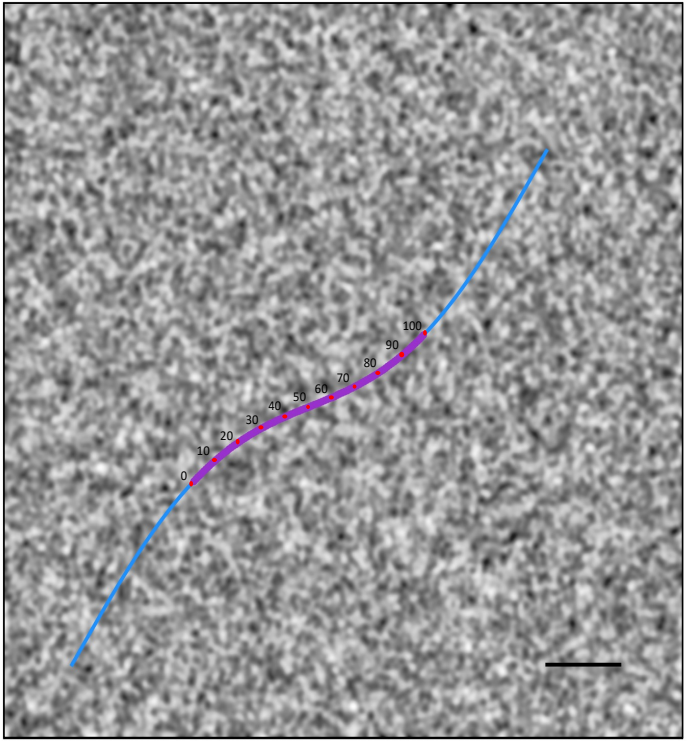


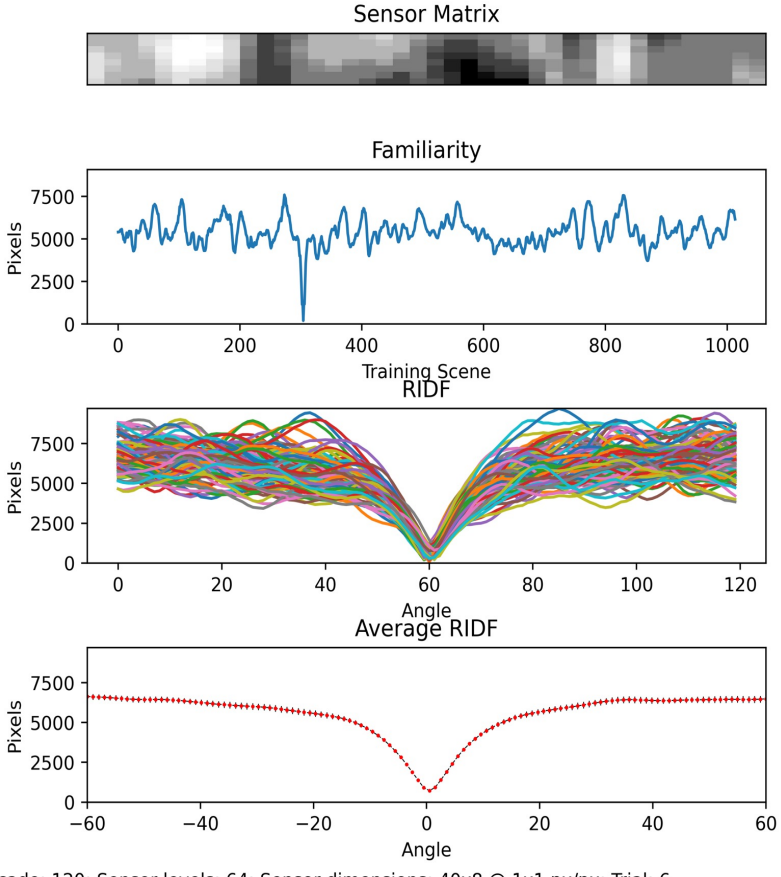


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 31.72; RMSD/dist: 0.079; TD: 5129; p90: 26; p50: 10; complete: 0

100%

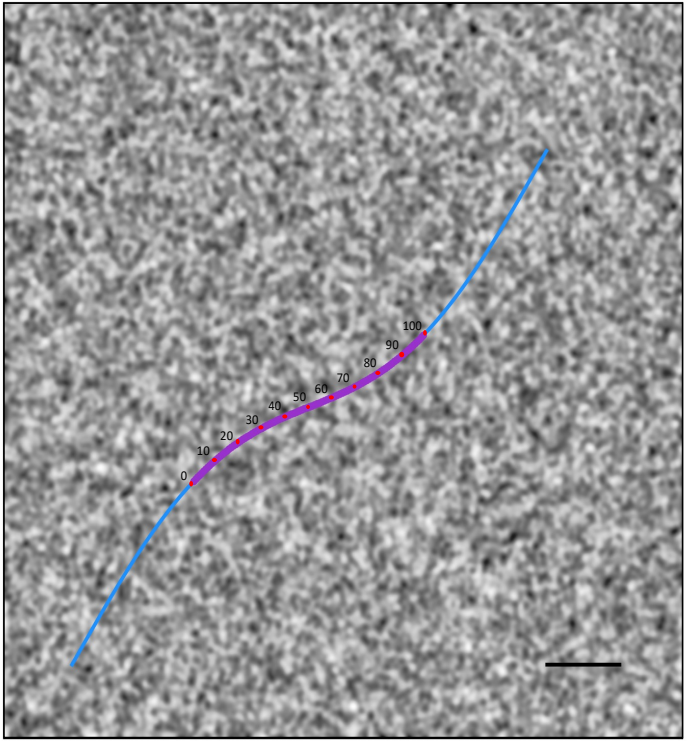


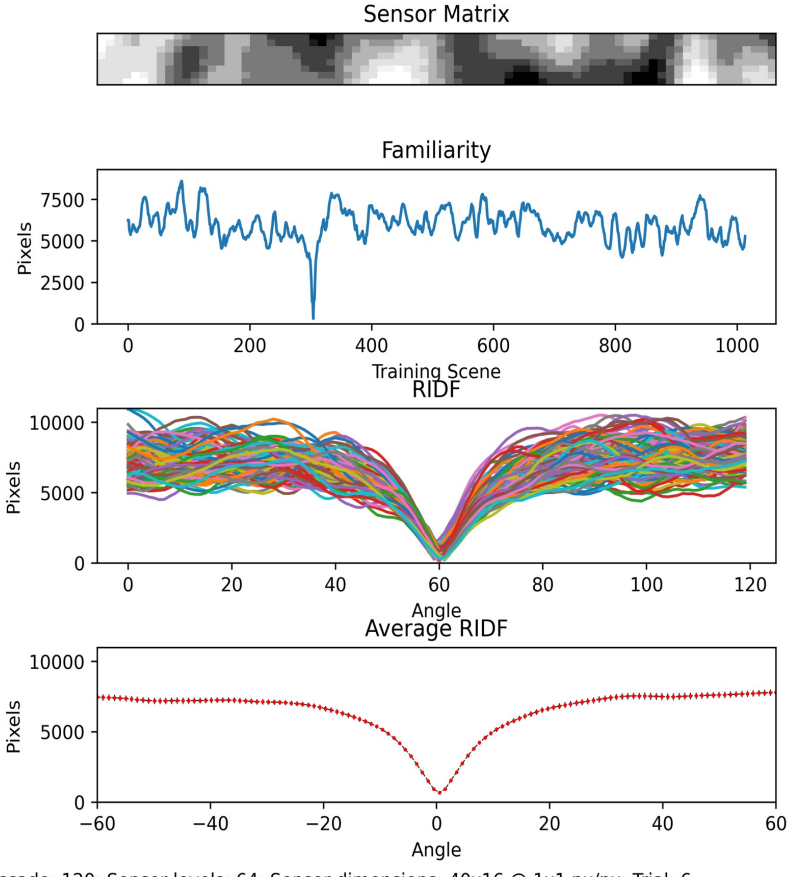


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 59.97; RMSD/dist: 0.150; TD: 4749; p90: 26; p50: 12; complete: 0

100%

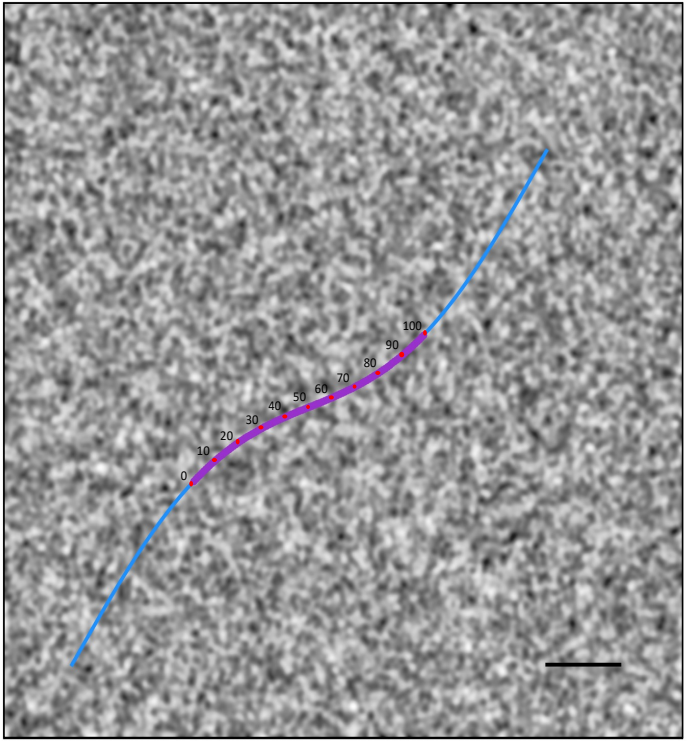


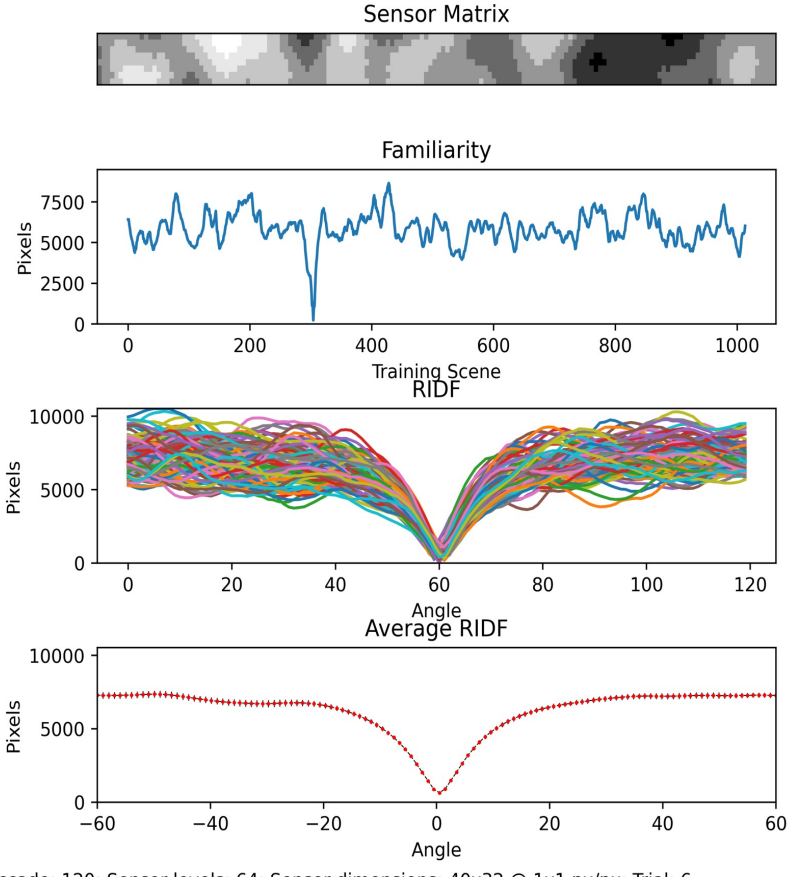


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 43.57; RMSD/dist: 0.109; TD: 5263; p90: 22; p50: 10; complete: 0

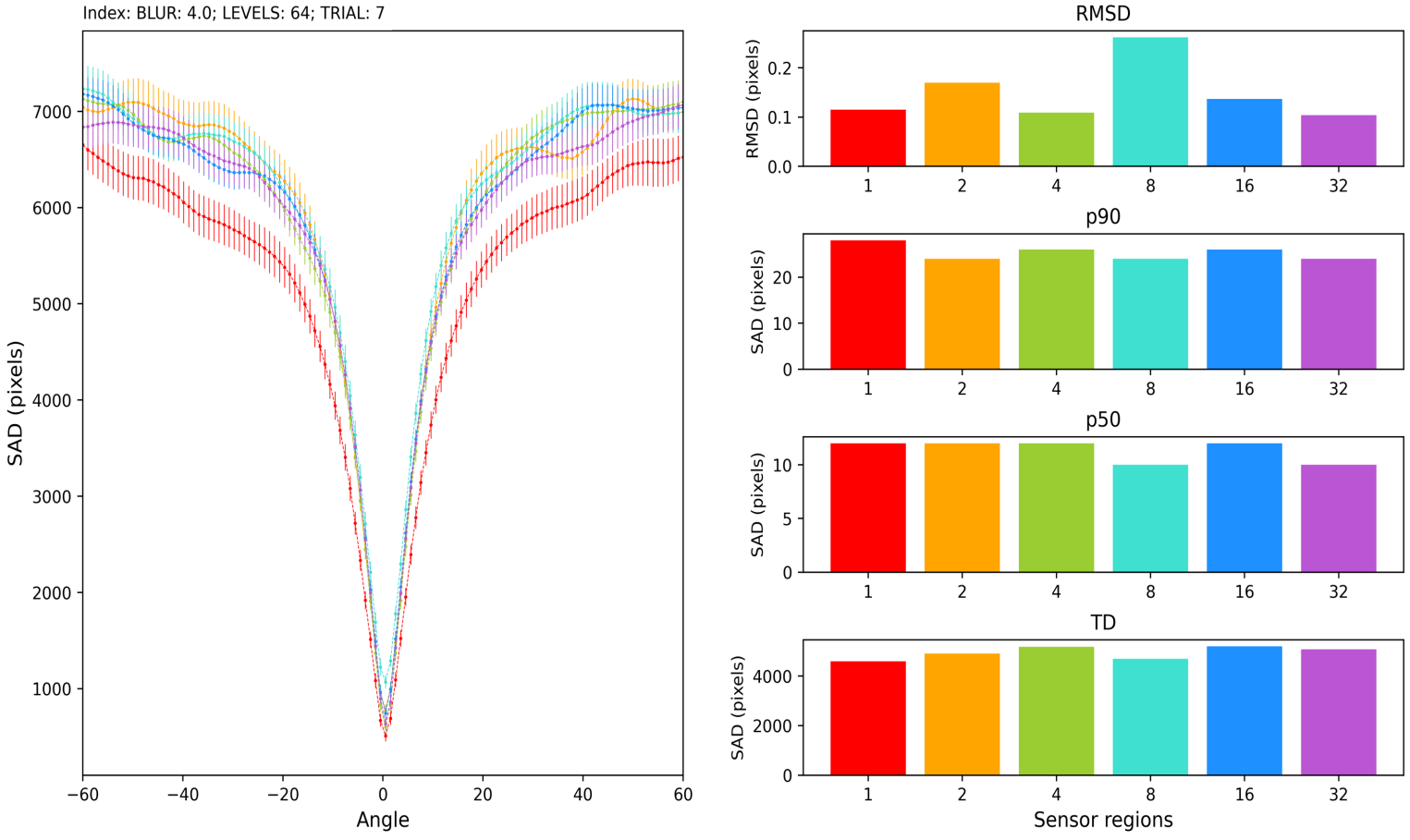
100%



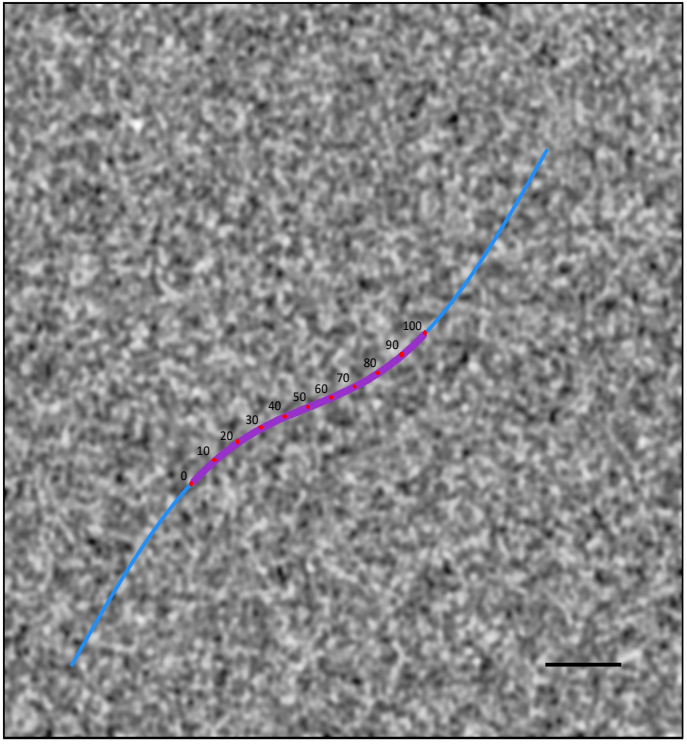


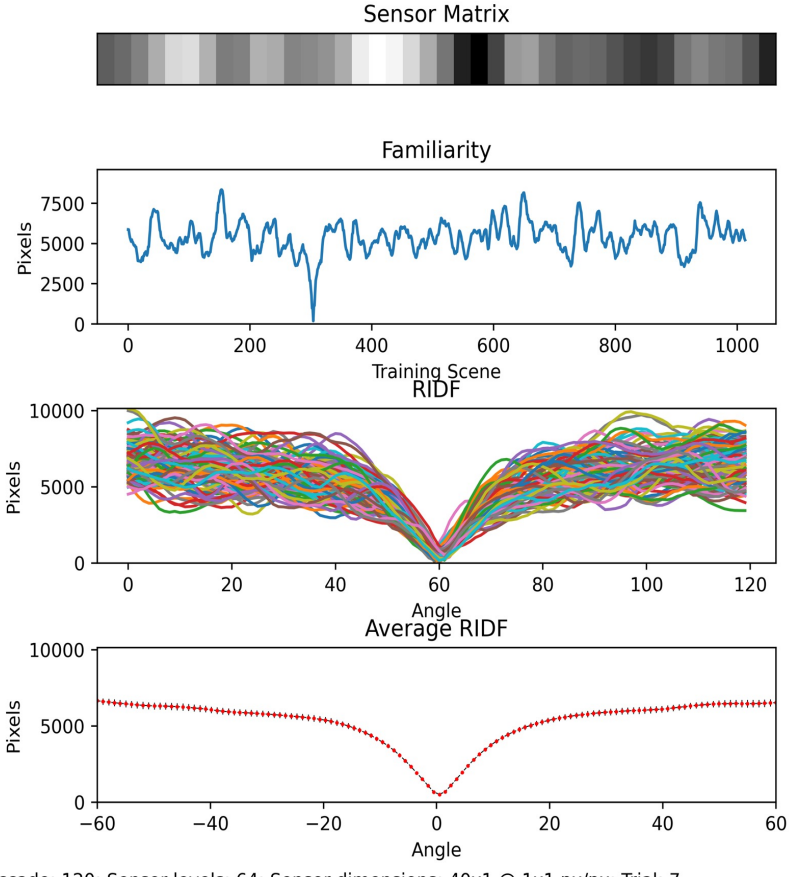
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 37.00; RMSD/dist: 0.092; TD: 5276; p90: 24; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 64; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

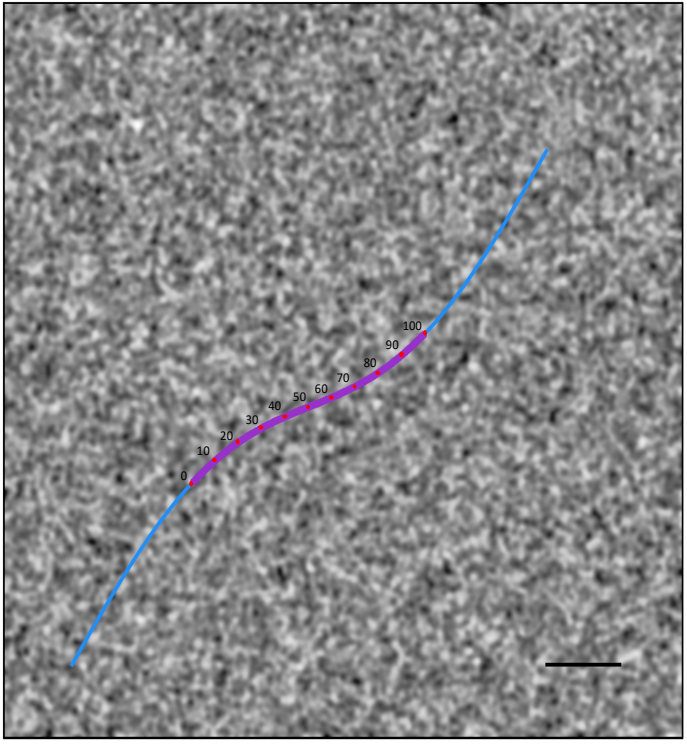


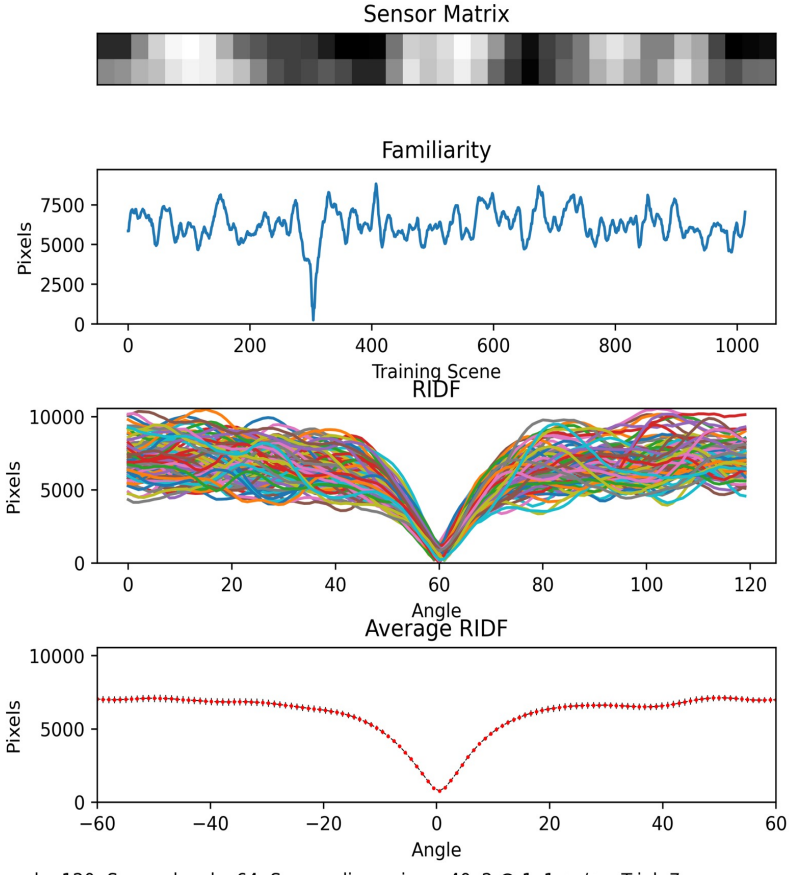


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 45.90; RMSD/dist: 0.115; TD: 4590; p90: 28; p50: 12; complete: 0

100%

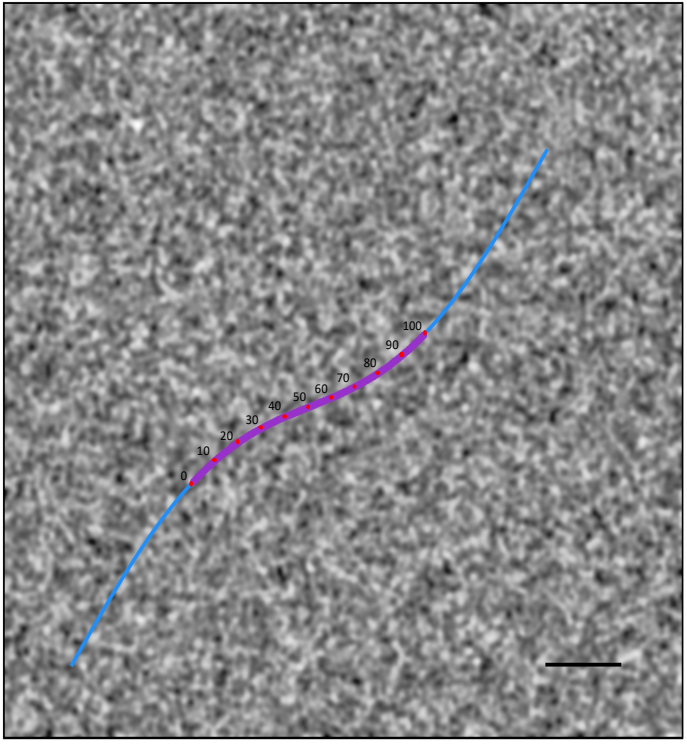


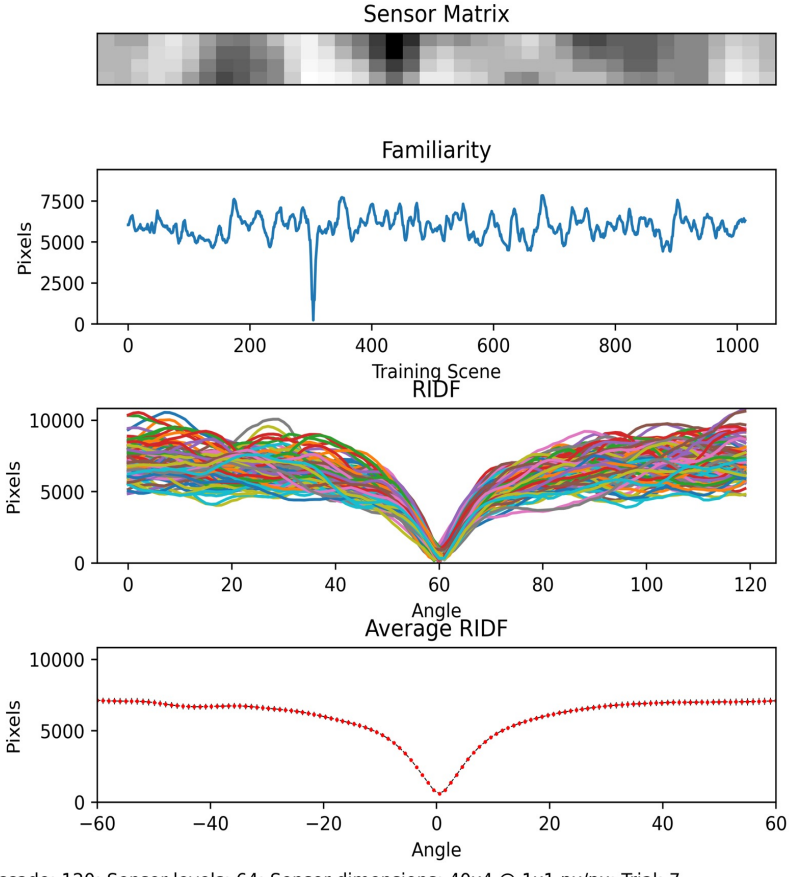


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 67.91; RMSD/dist: 0.170; TD: 4906; p90: 24; p50: 12; complete: 0

100%

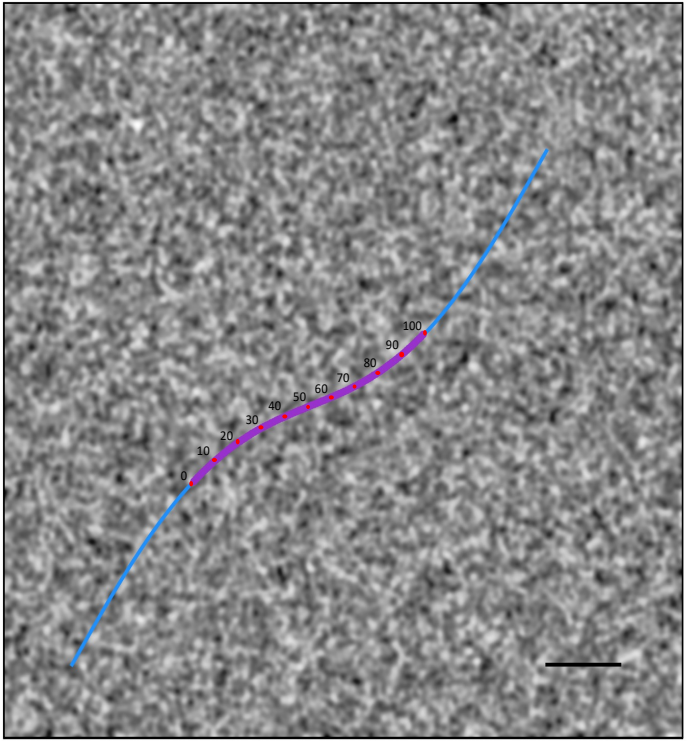


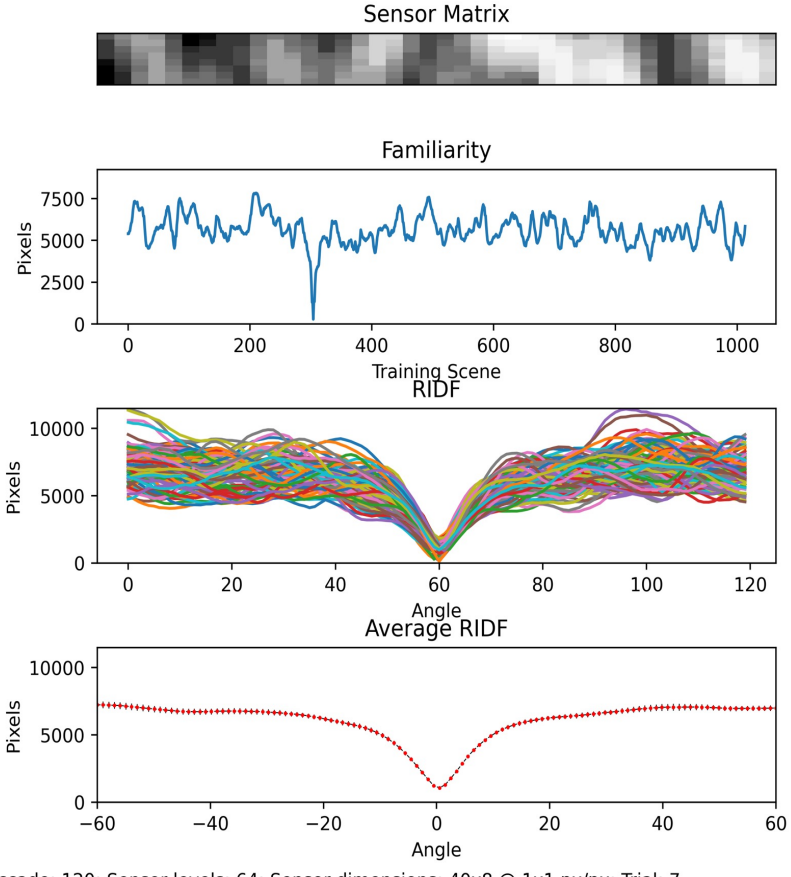


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 43.45; RMSD/dist: 0.109; TD: 5172; p90: 26; p50: 12; complete: 0

100%

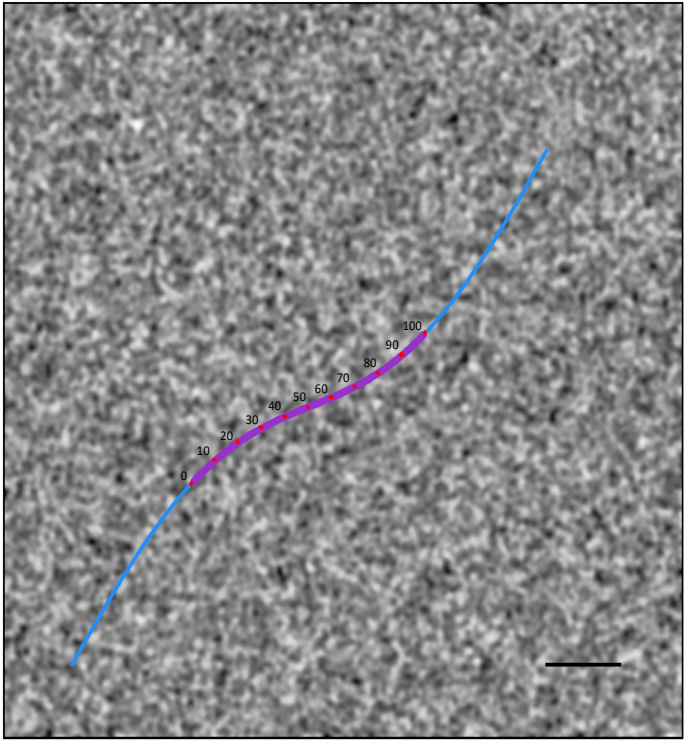


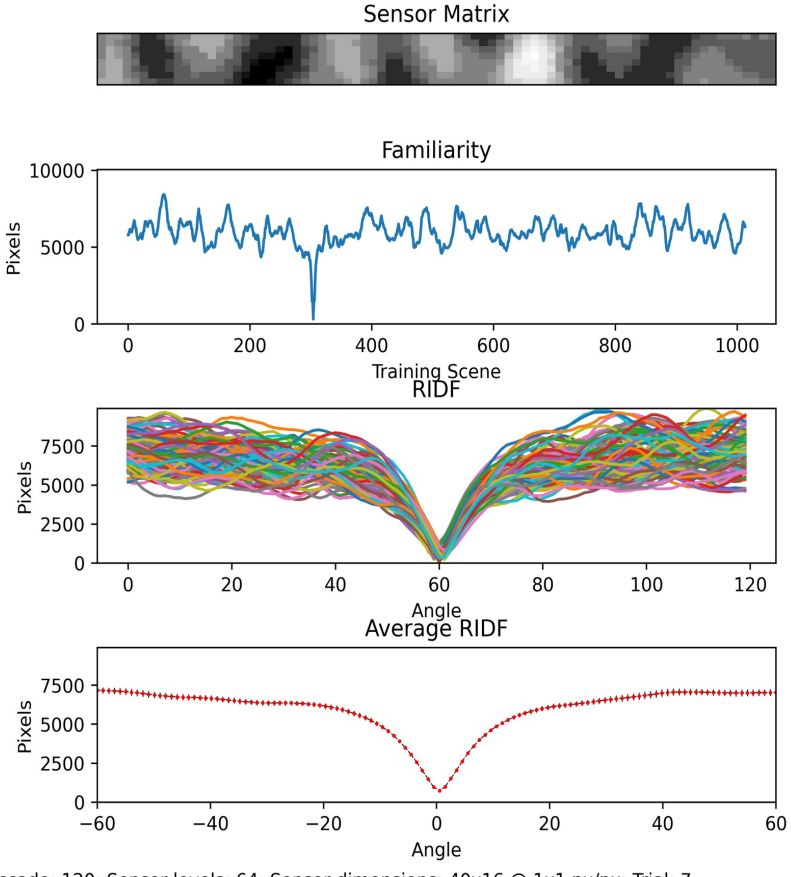


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 104.89; RMSD/dist: 0.262; TD: 4690; p90: 24; p50: 10; complete: 0

100%

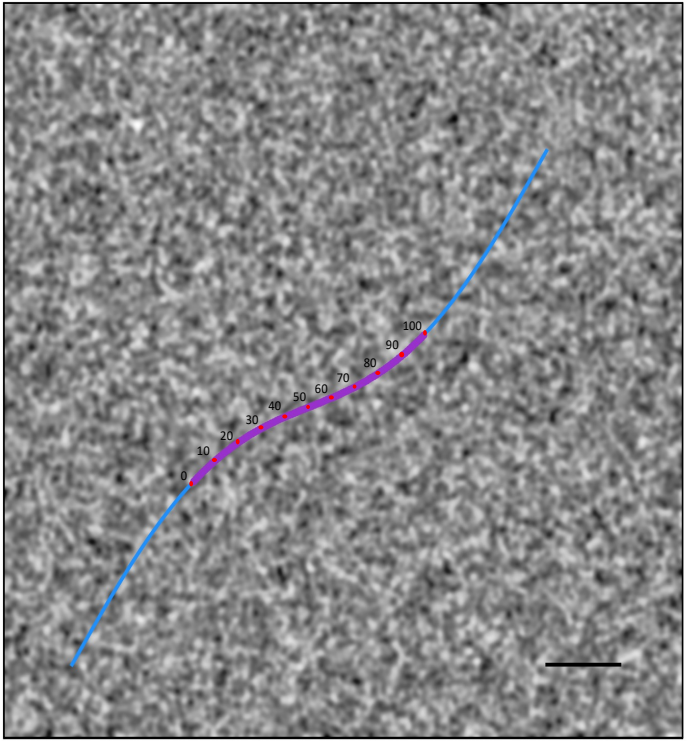


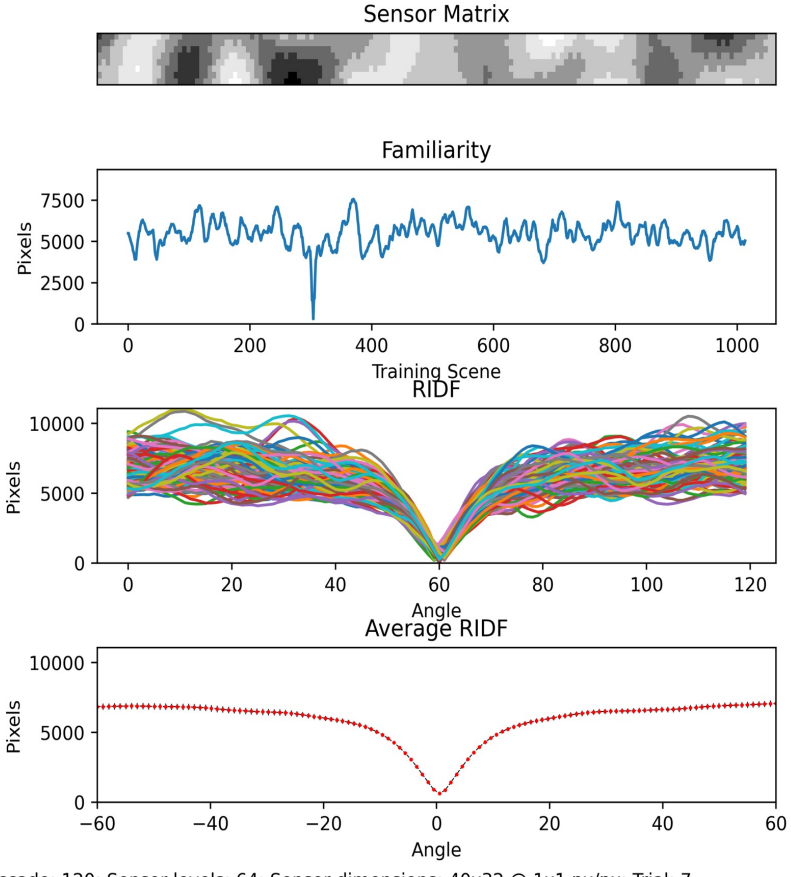


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 54.62; RMSD/dist: 0.137; TD: 5198; p90: 26; p50: 12; complete: 0

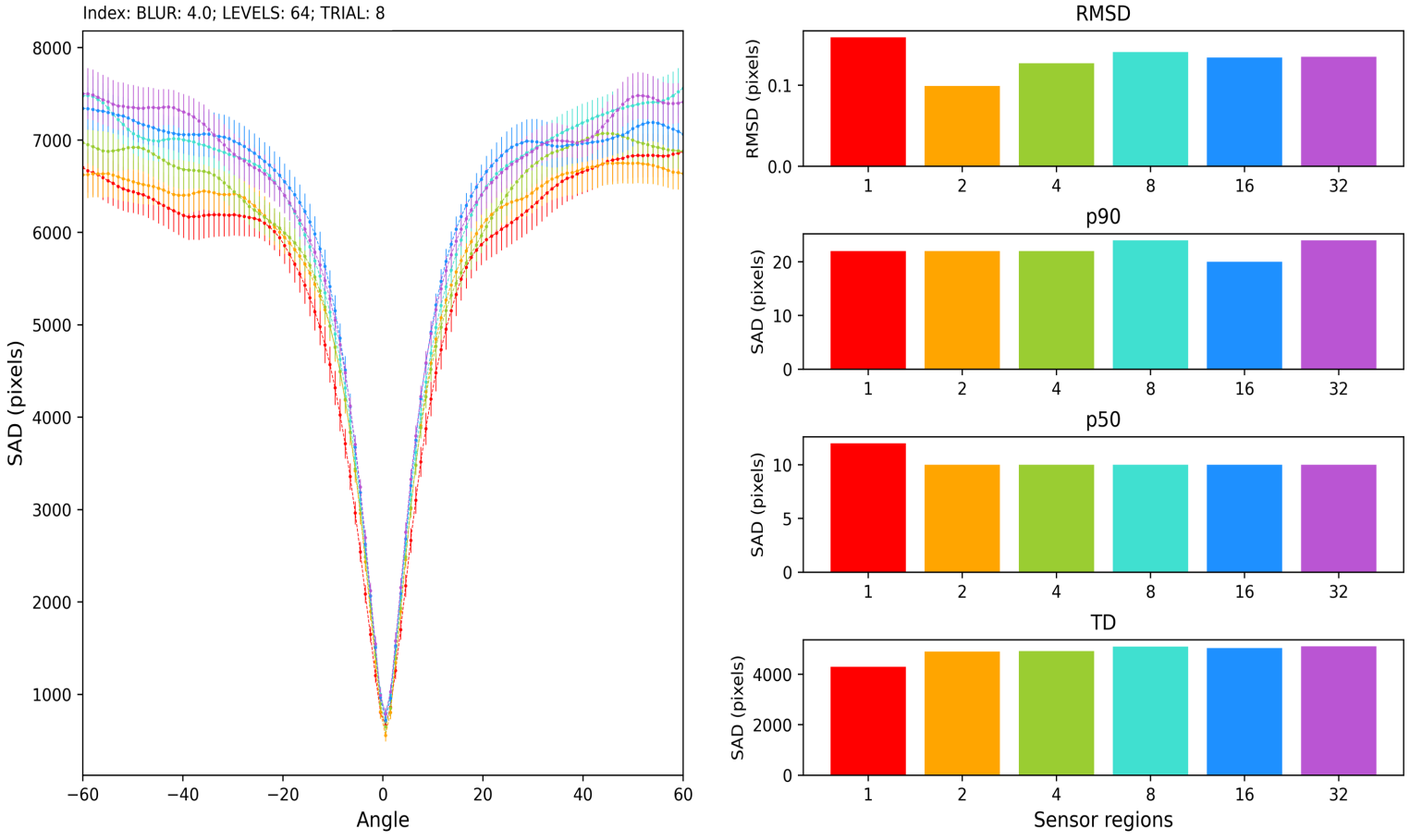
100%



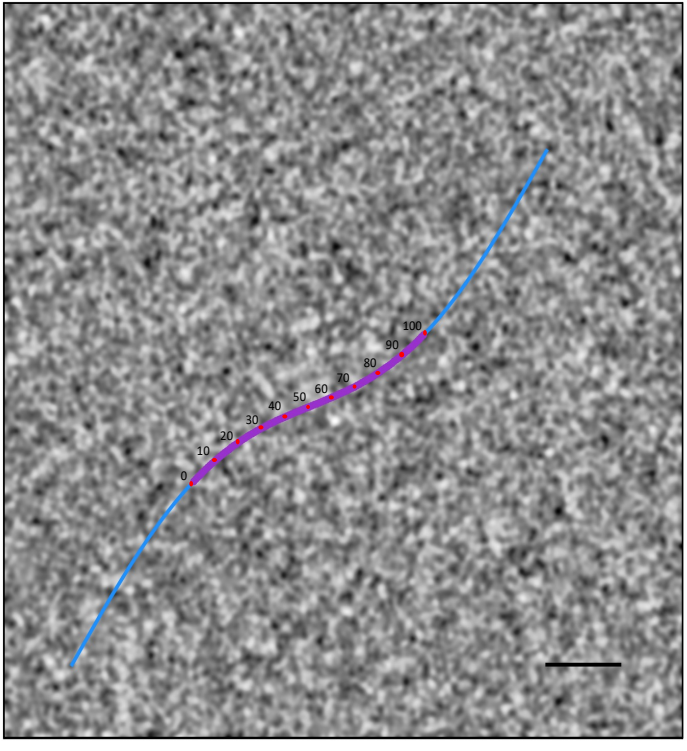


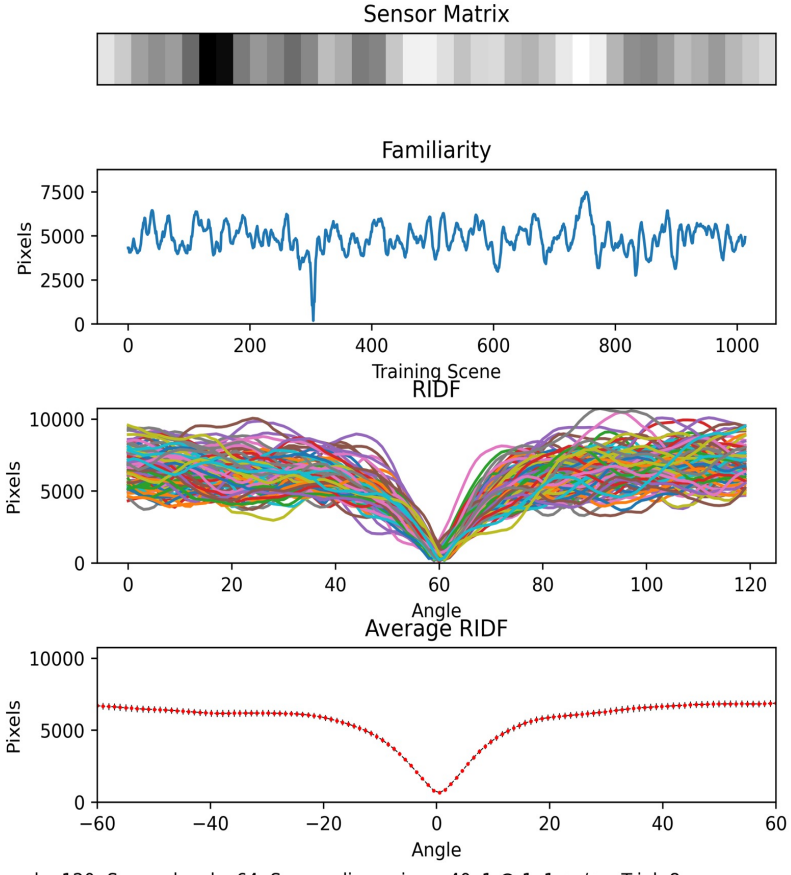
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 41.60; RMSD/dist: 0.104; TD: 5071; p90: 24; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 64; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

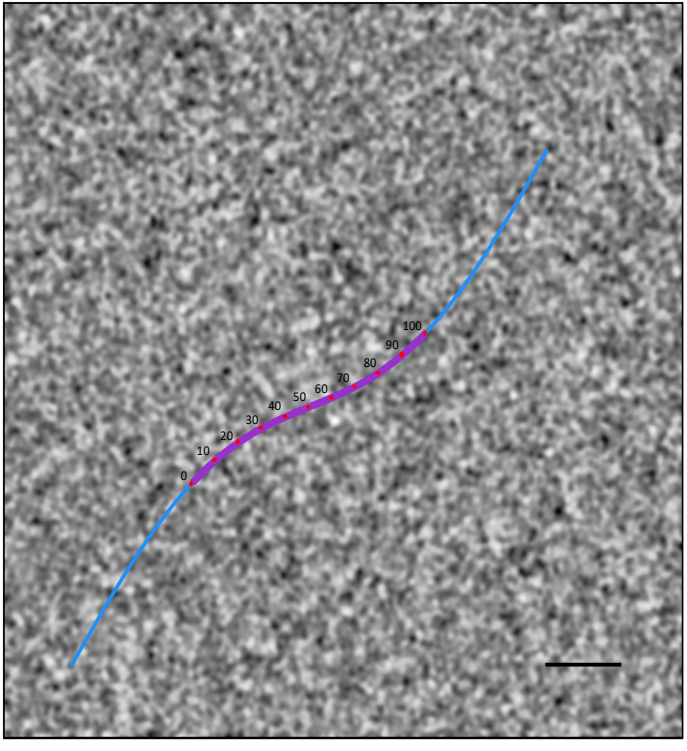


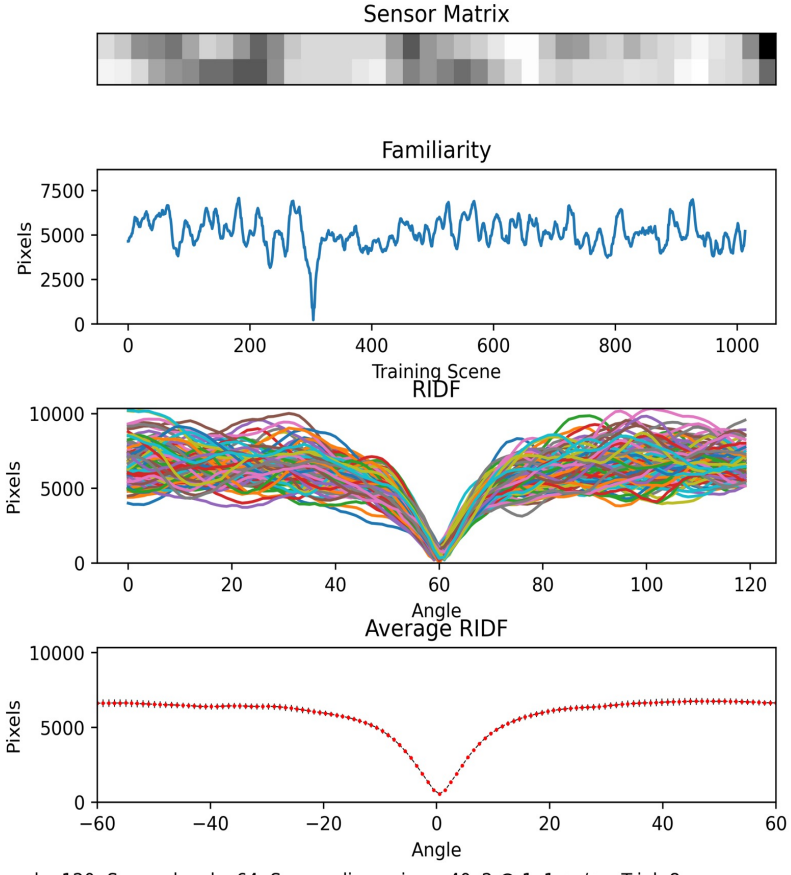


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 63.56; RMSD/dist: 0.159; TD: 4292; p90: 22; p50: 12; complete: 0

100%

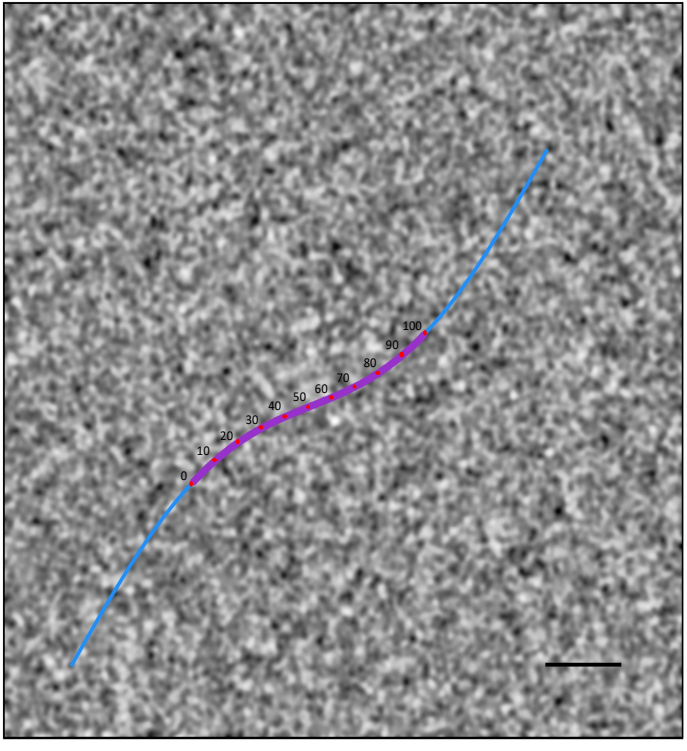


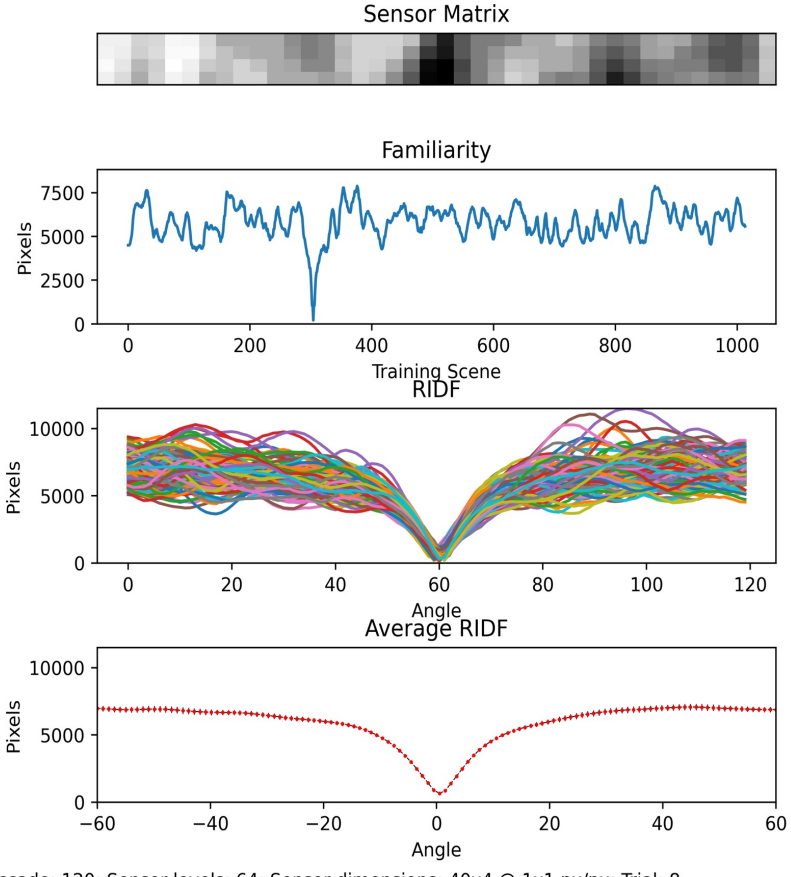


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 39.69; RMSD/dist: 0.099; TD: 4896; p90: 22; p50: 10; complete: 0

100%

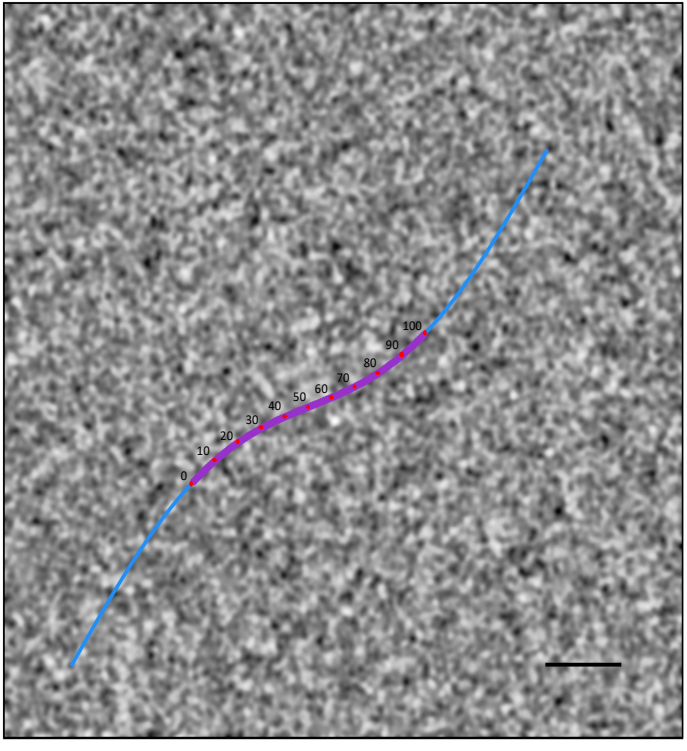


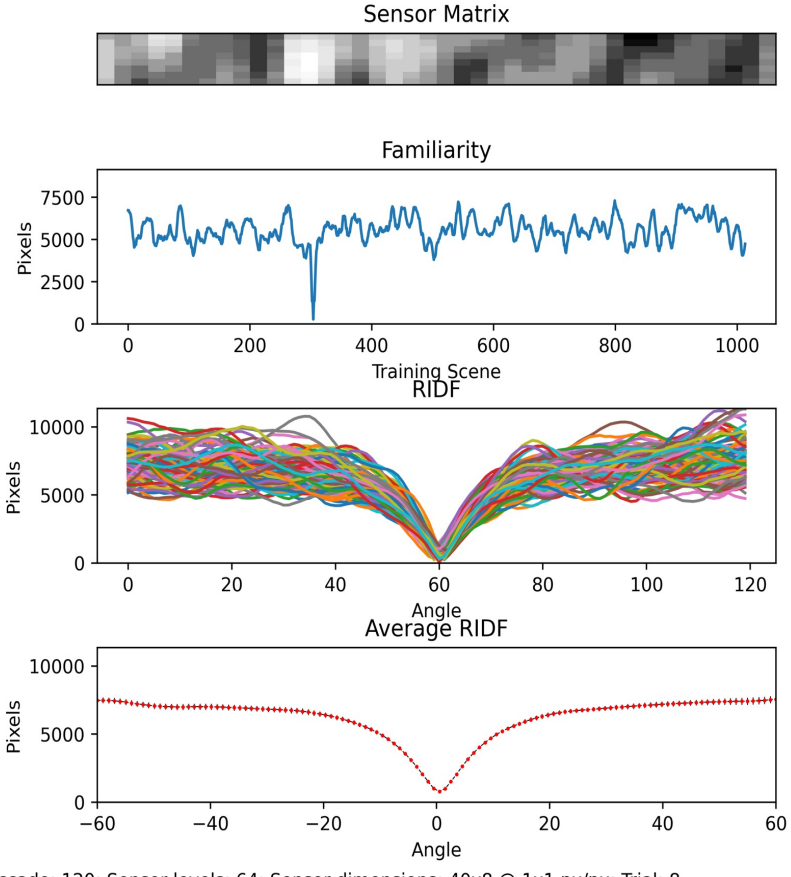


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 50.91; RMSD/dist: 0.127; TD: 4917; p90: 22; p50: 10; complete: 0

100%

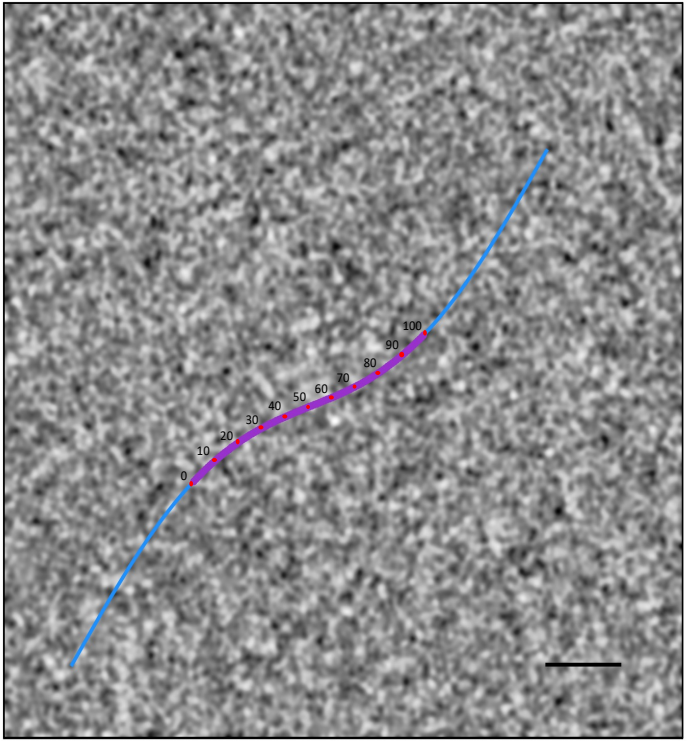


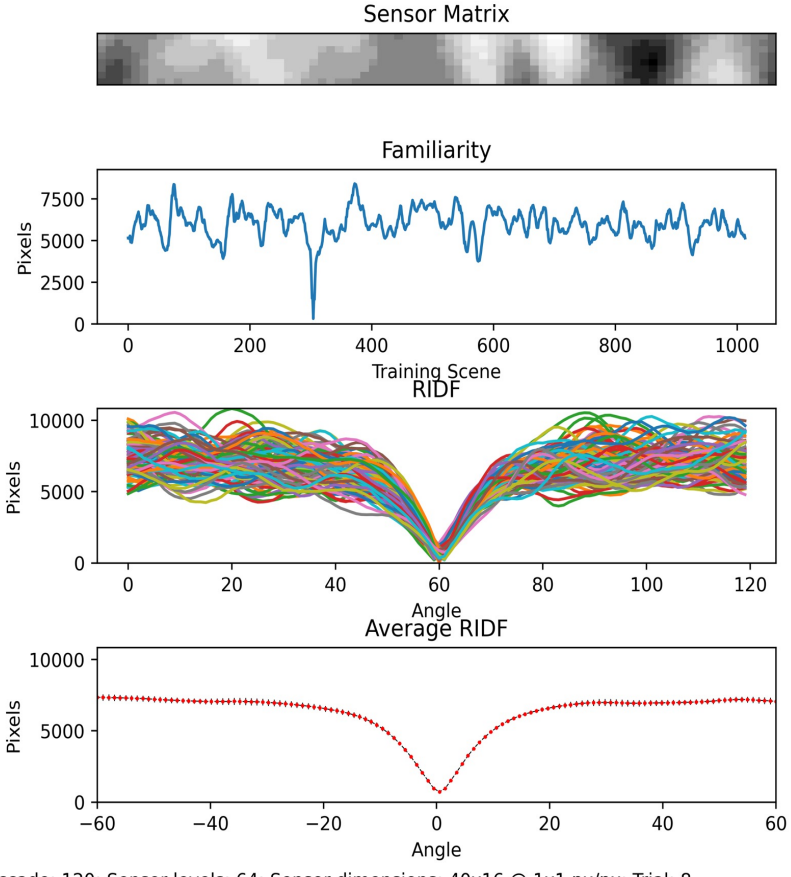


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 56.23; RMSD/dist: 0.141; TD: 5094; p90: 24; p50: 10; complete: 0

100%

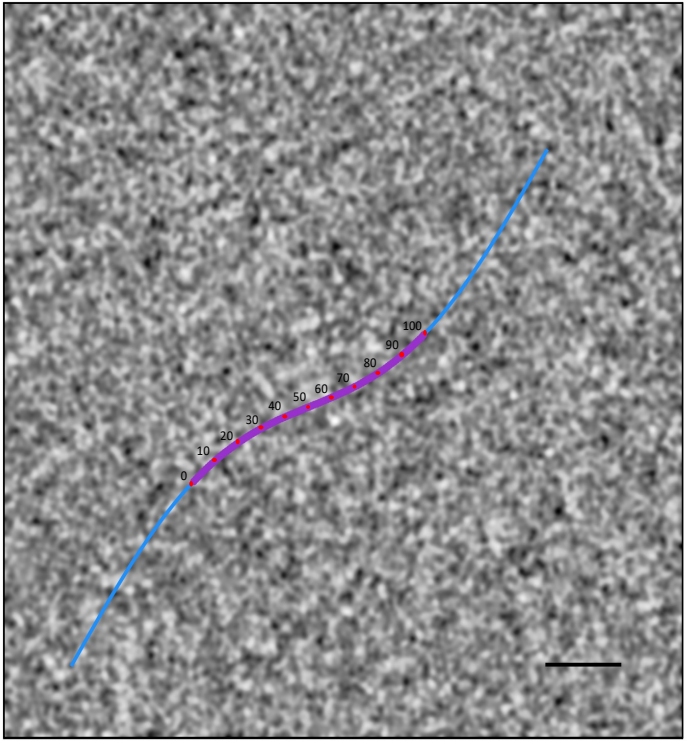


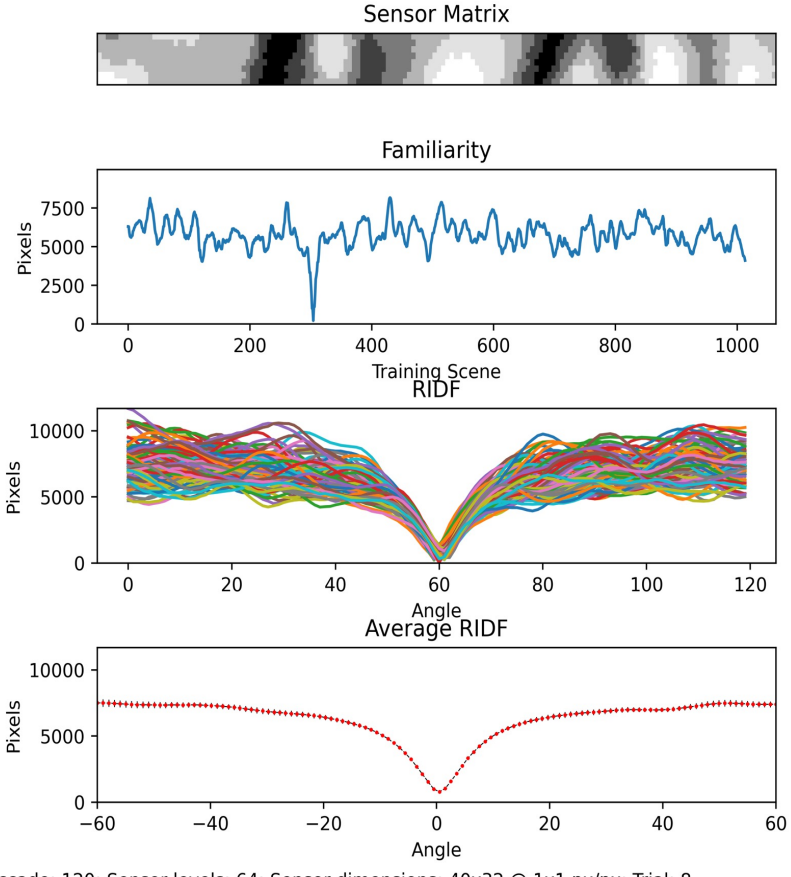


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 53.53; RMSD/dist: 0.134; TD: 5037; p90: 20; p50: 10; complete: 0

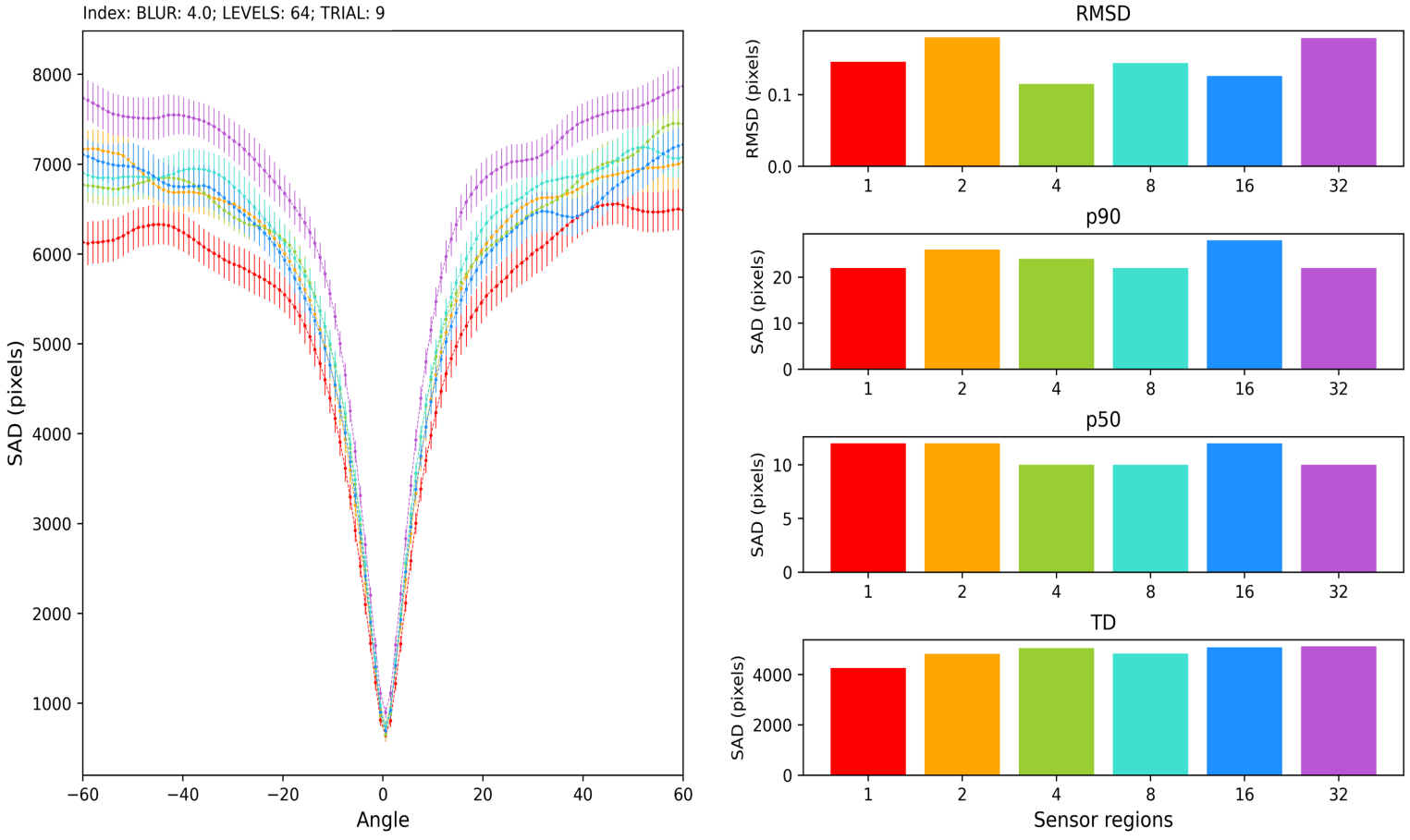
100%



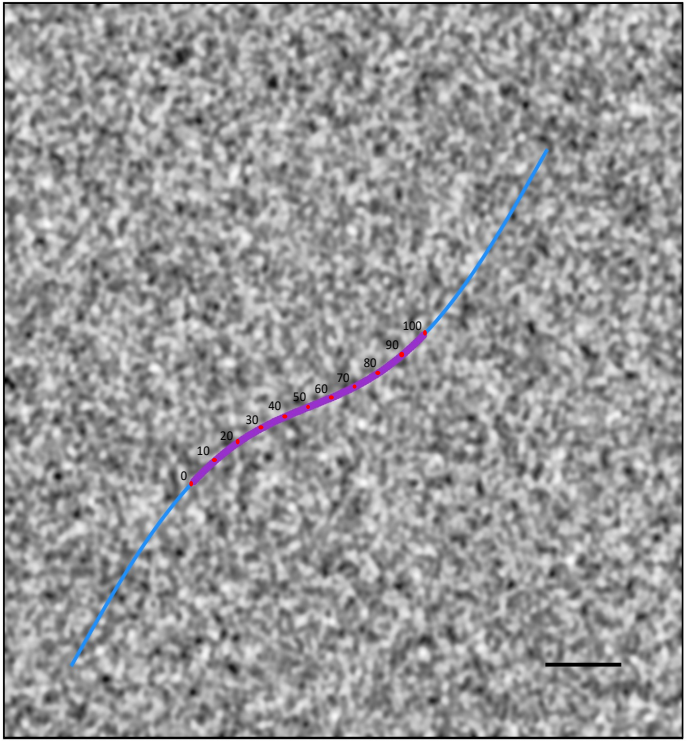


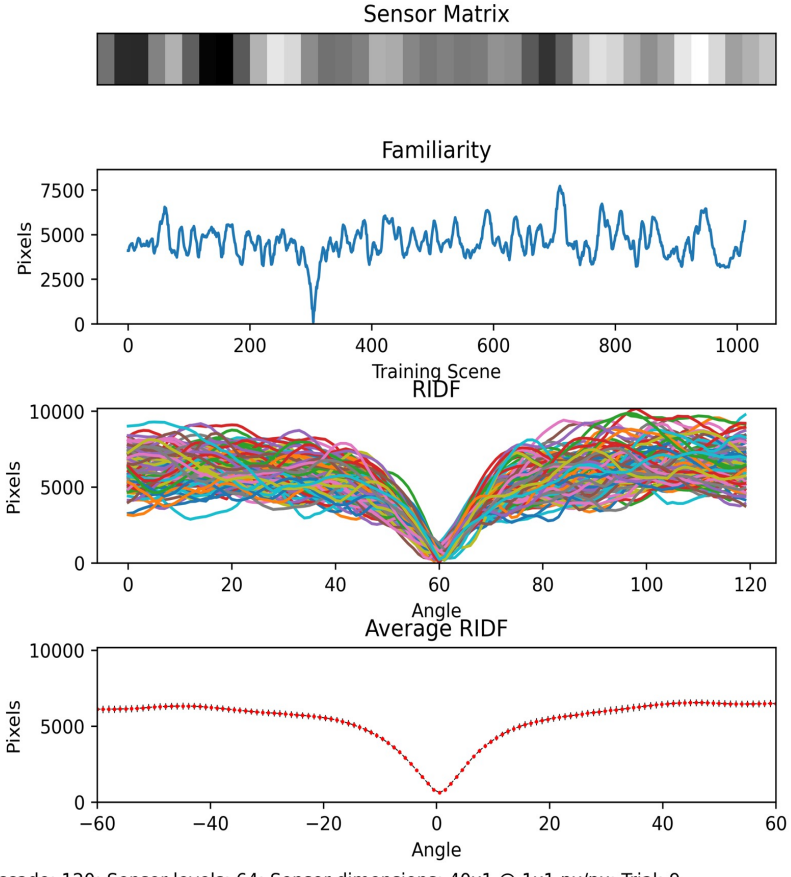
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 54.01; RMSD/dist: 0.135; TD: 5108; p90: 24; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 64; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

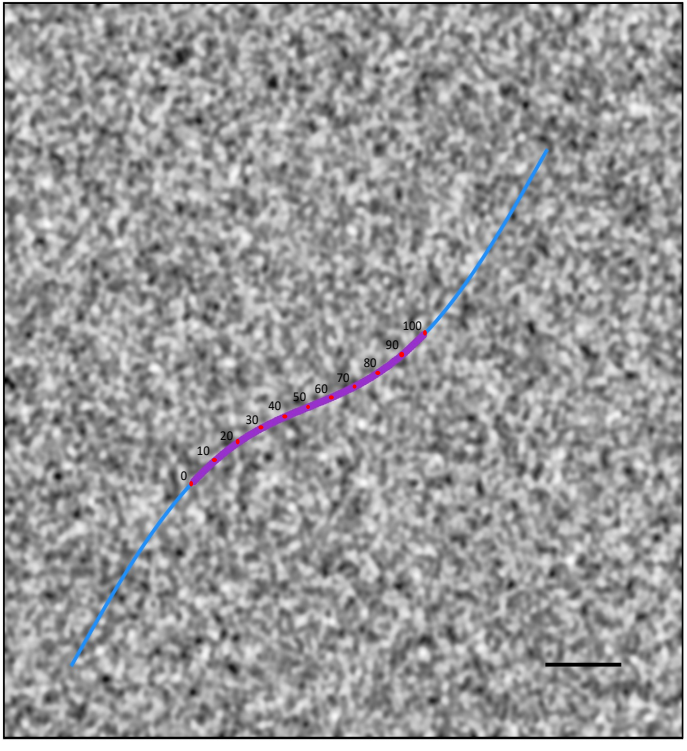


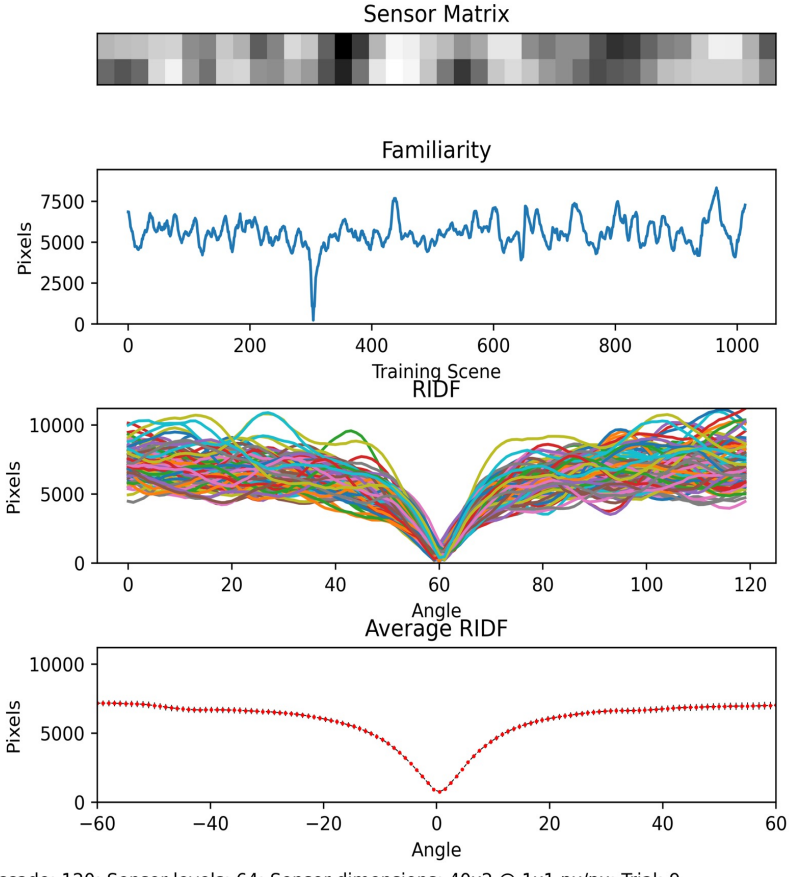


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 58.34; RMSD/dist: 0.146; TD: 4255; p90: 22; p50: 12; complete: 0

100%

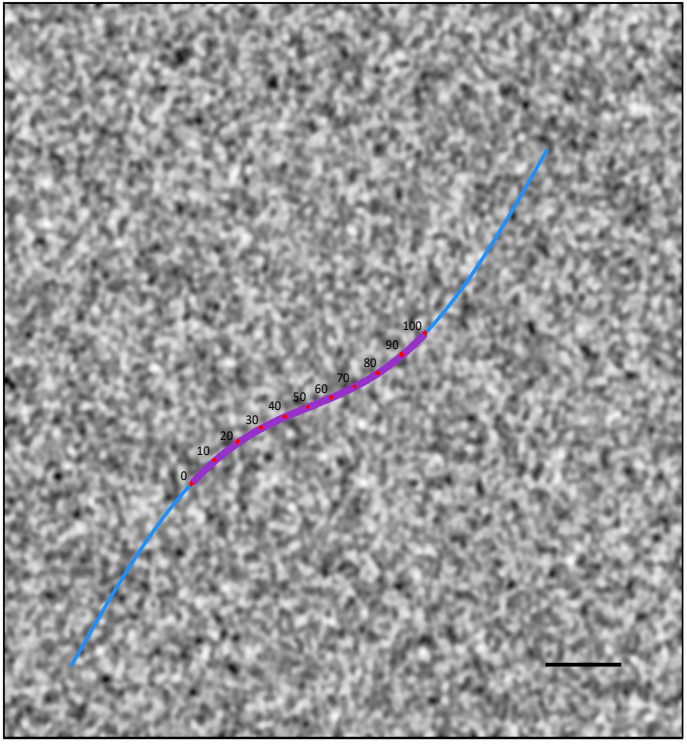


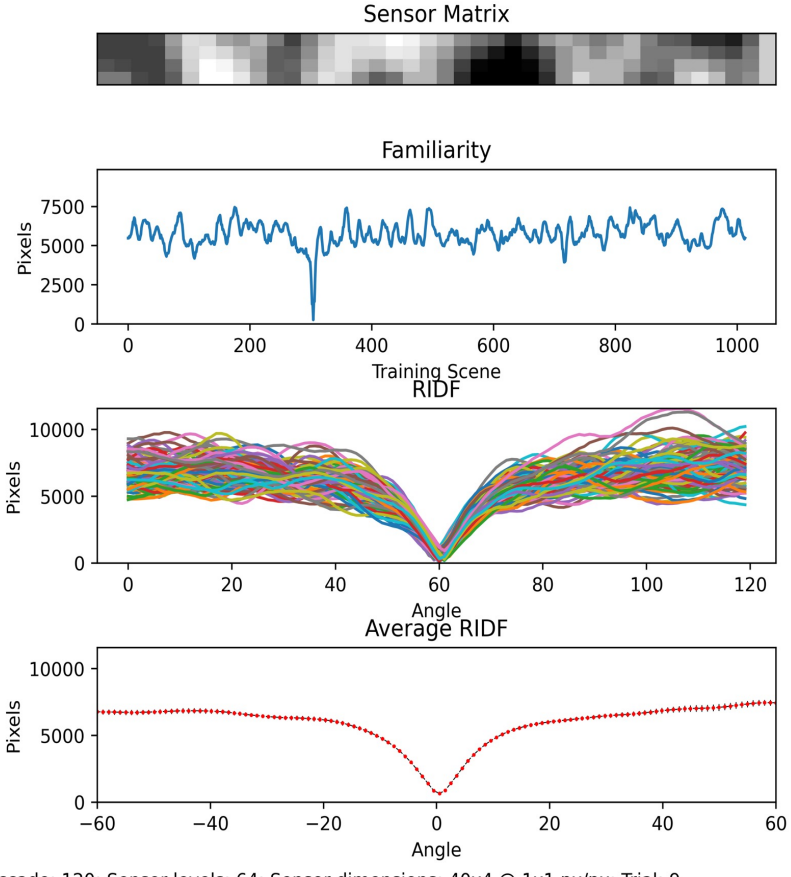


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 72.08; RMSD/dist: 0.180; TD: 4819; p90: 26; p50: 12; complete: 0

100%

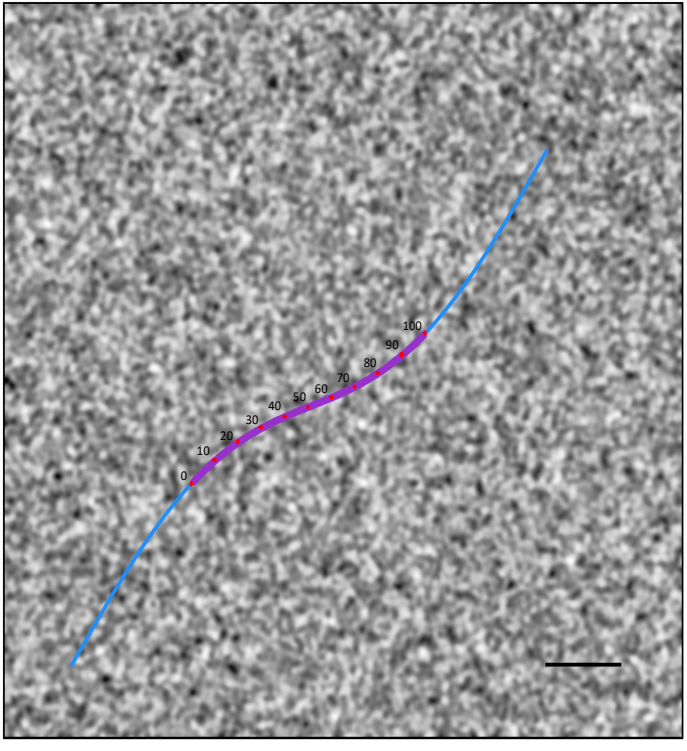


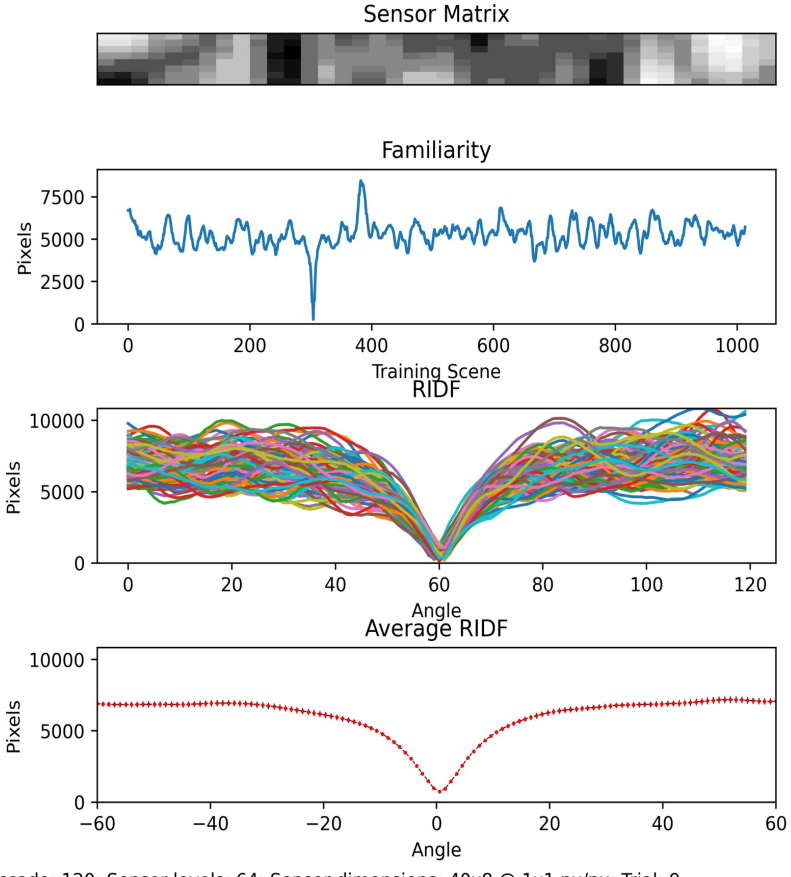


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 46.20; RMSD/dist: 0.115; TD: 5053; p90: 24; p50: 10; complete: 0

100%

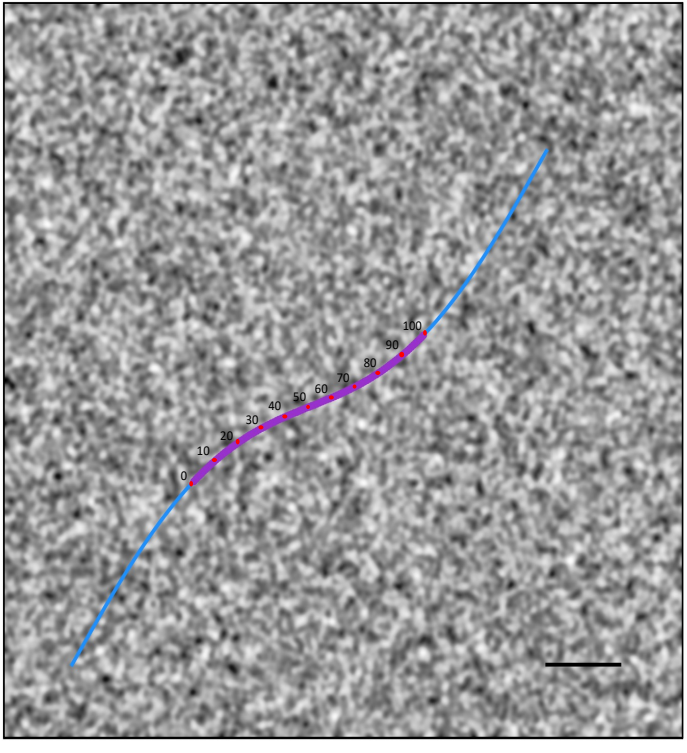


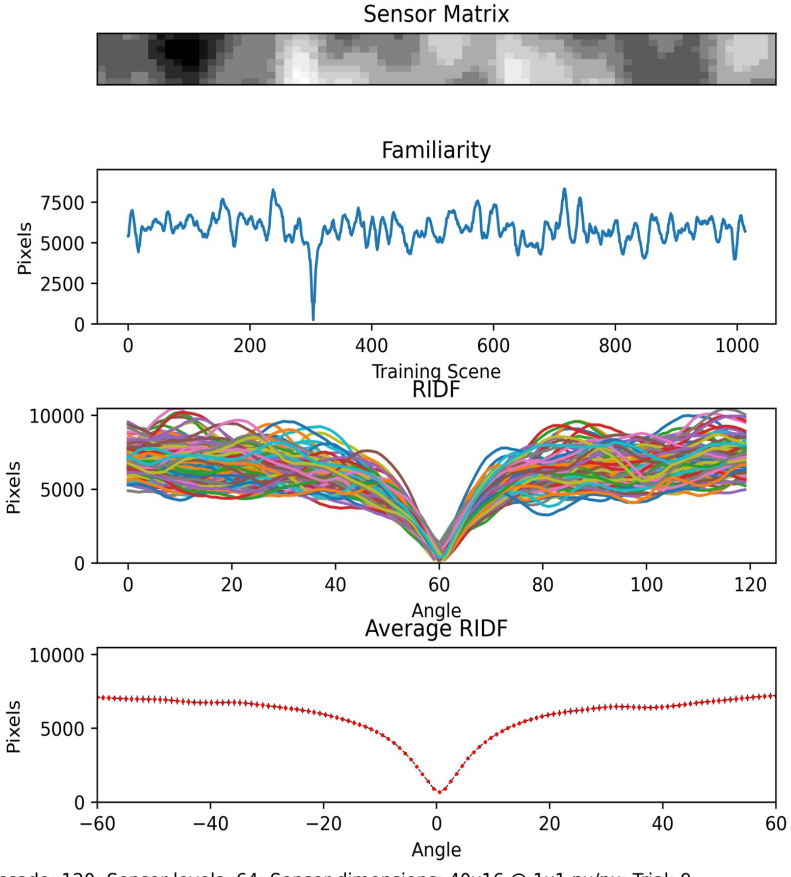


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 57.65; RMSD/dist: 0.144; TD: 4834; p90: 22; p50: 10; complete: 0

100%

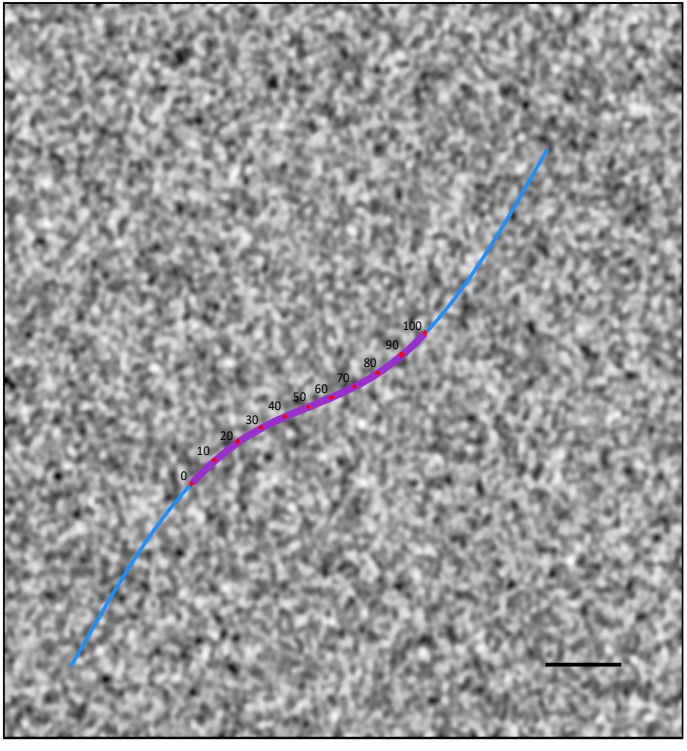


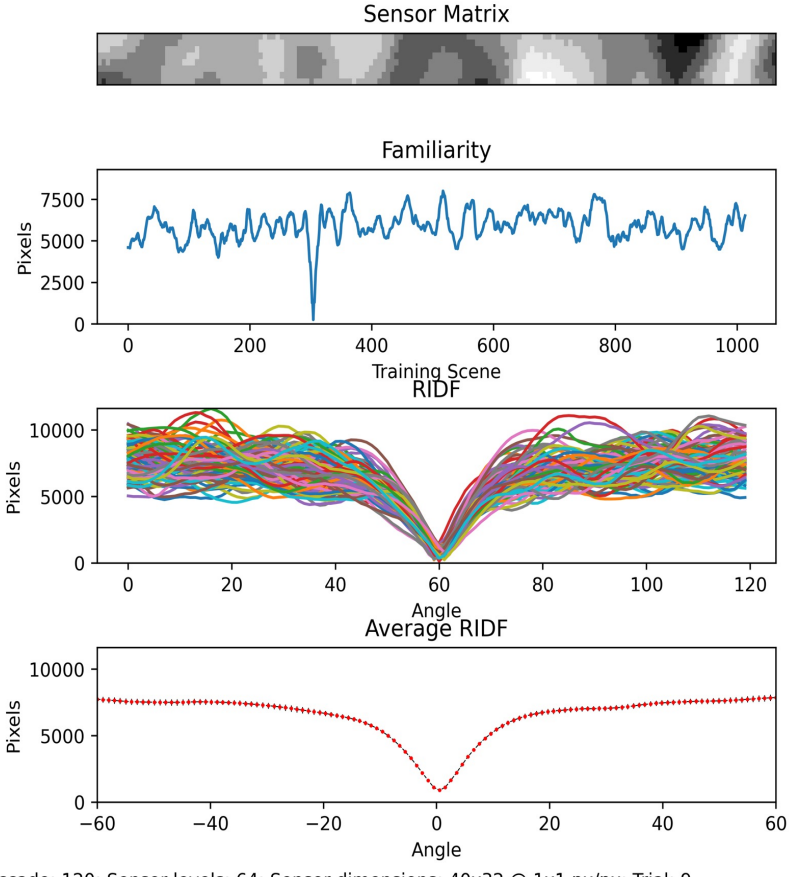


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 50.25; RMSD/dist: 0.126; TD: 5078; p90: 28; p50: 12; complete: 0

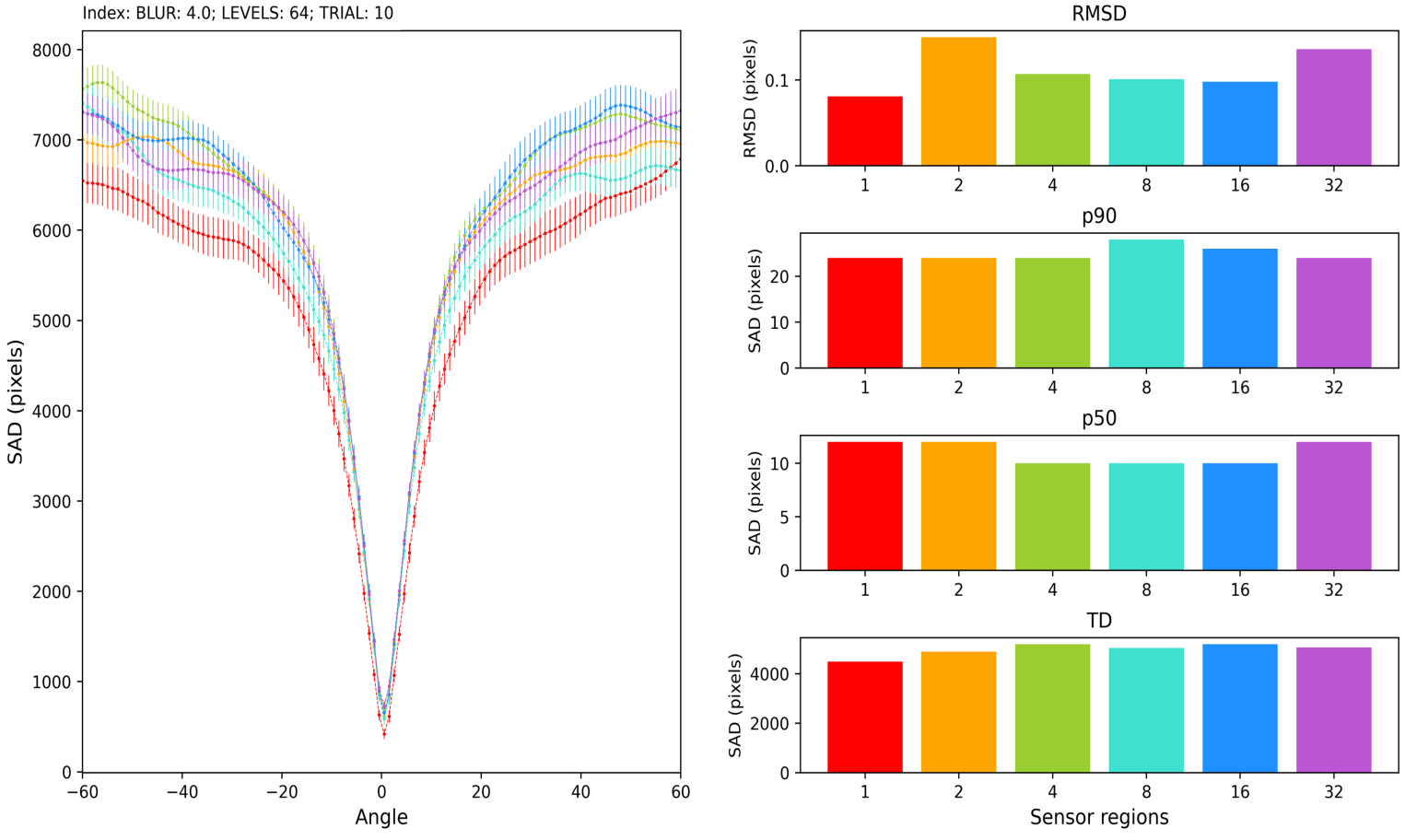
100%



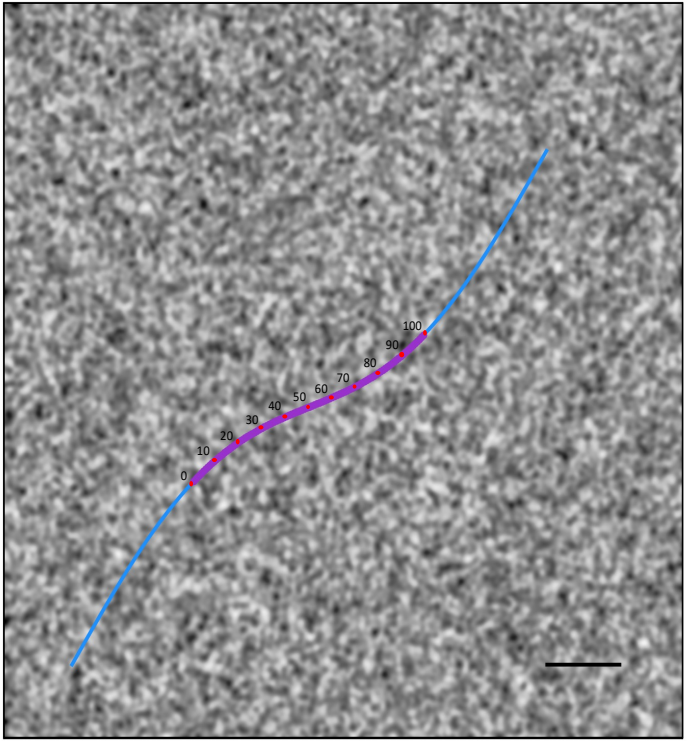


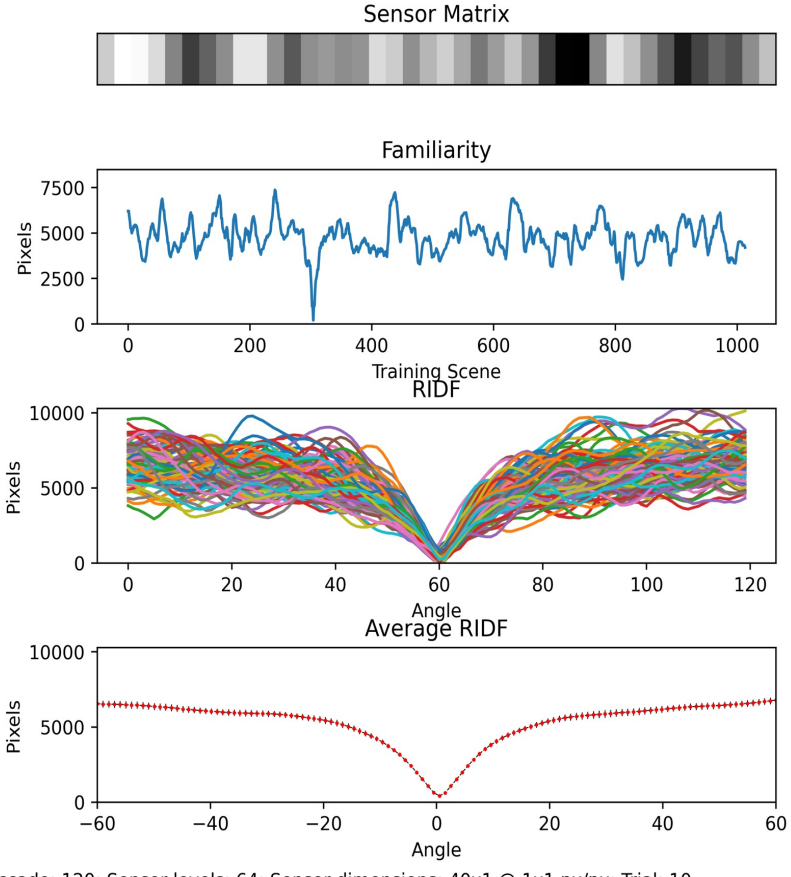
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 71.49; RMSD/dist: 0.179; TD: 5121; p90: 22; p50: 10; complete: 0


Index: BLUR: 4.0; LEVELS: 64; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

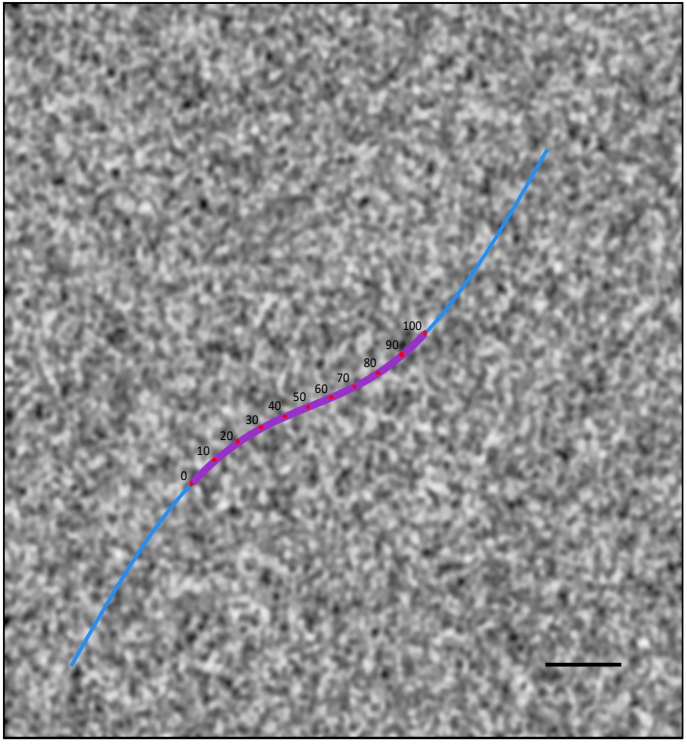


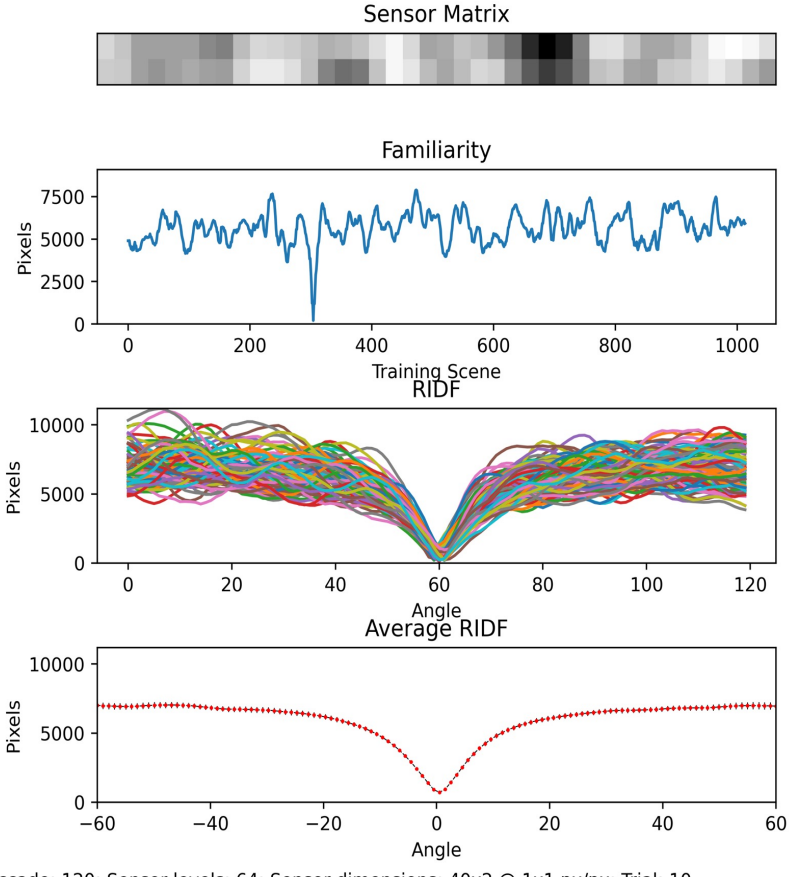


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 32.49; RMSD/dist: 0.081; TD: 4486; p90: 24; p50: 12; complete: 0

100%

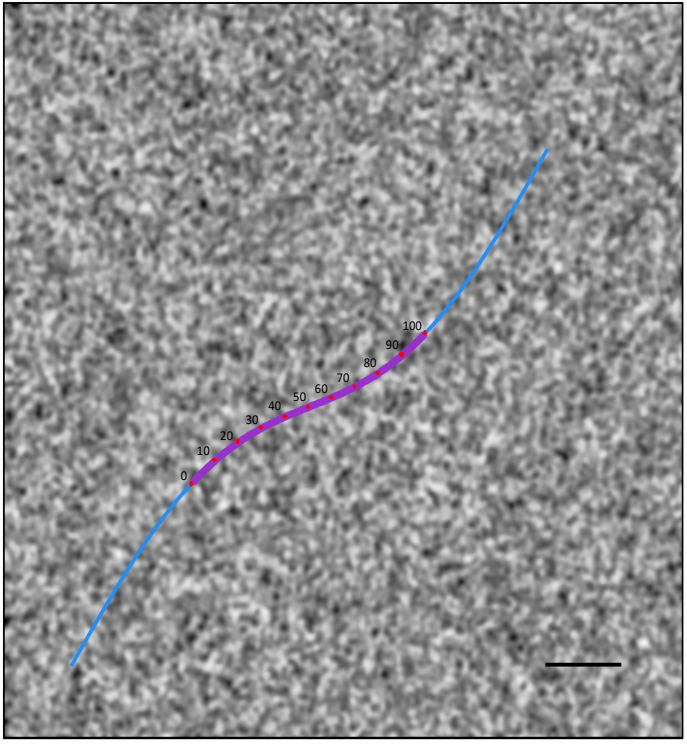


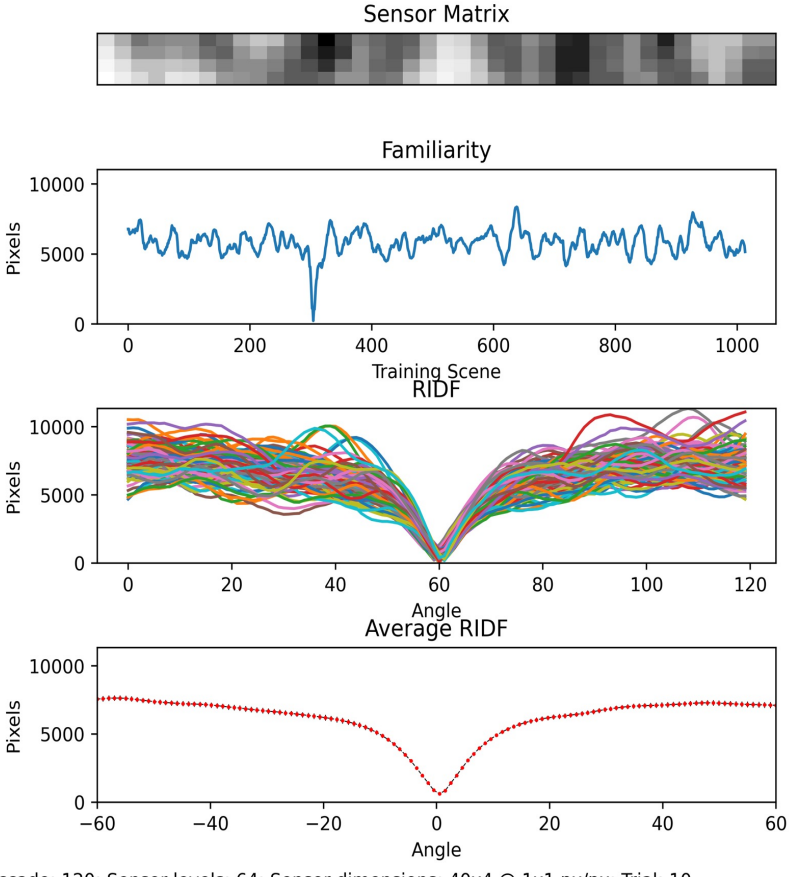


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 60.20; RMSD/dist: 0.150; TD: 4895; p90: 24; p50: 12; complete: 0

100%

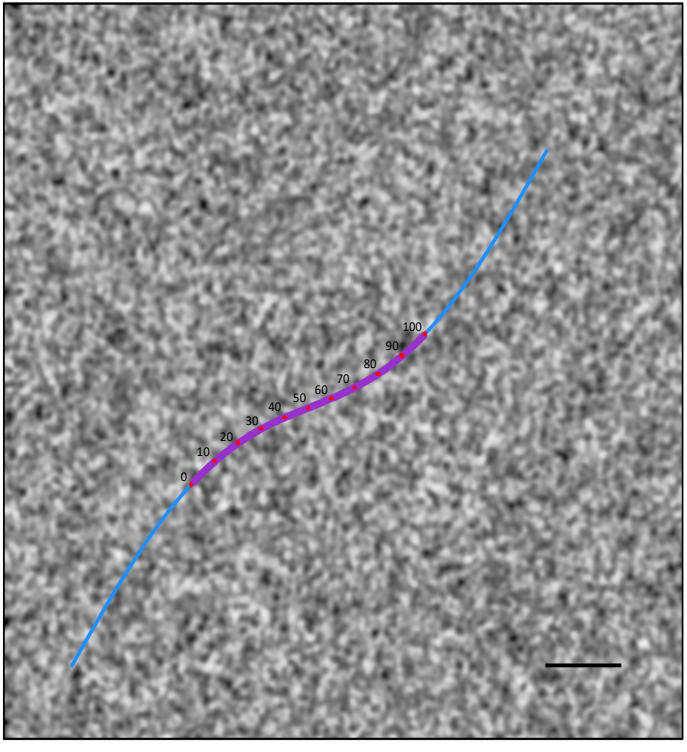


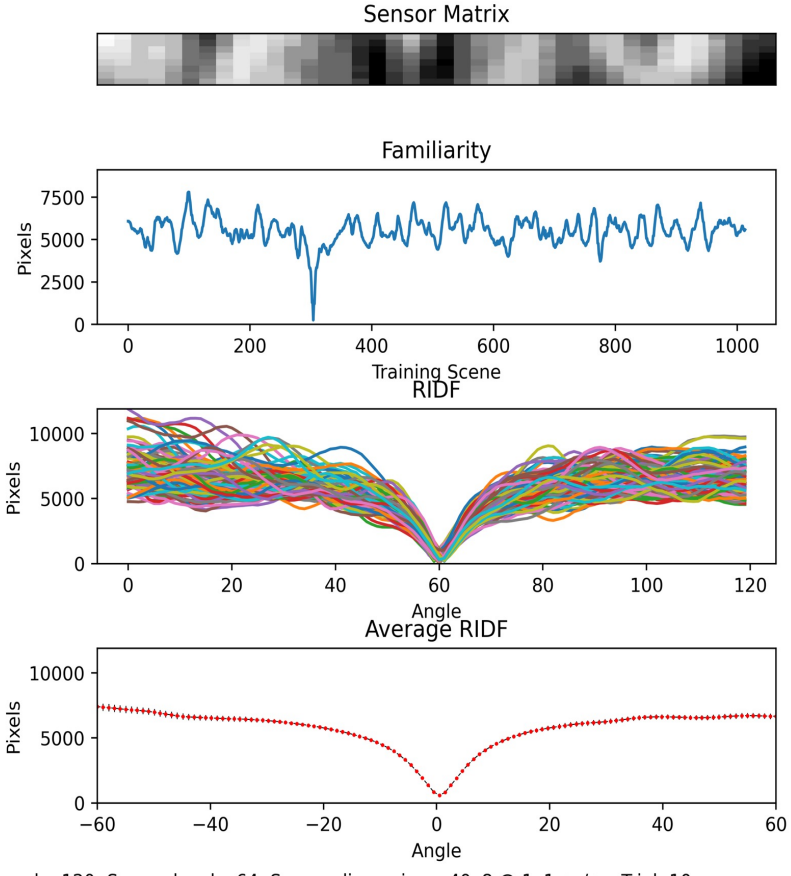


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 42.97; RMSD/dist: 0.107; TD: 5196; p90: 24; p50: 10; complete: 0

100%

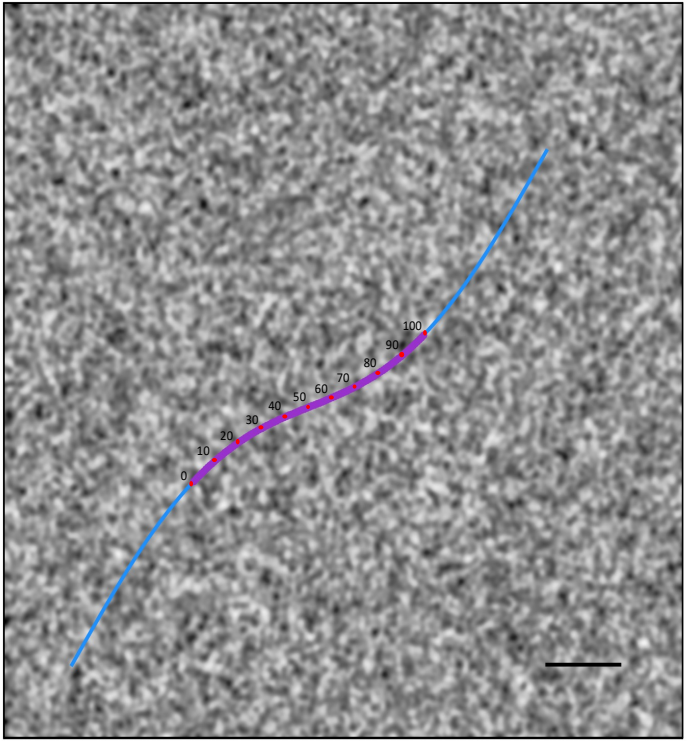


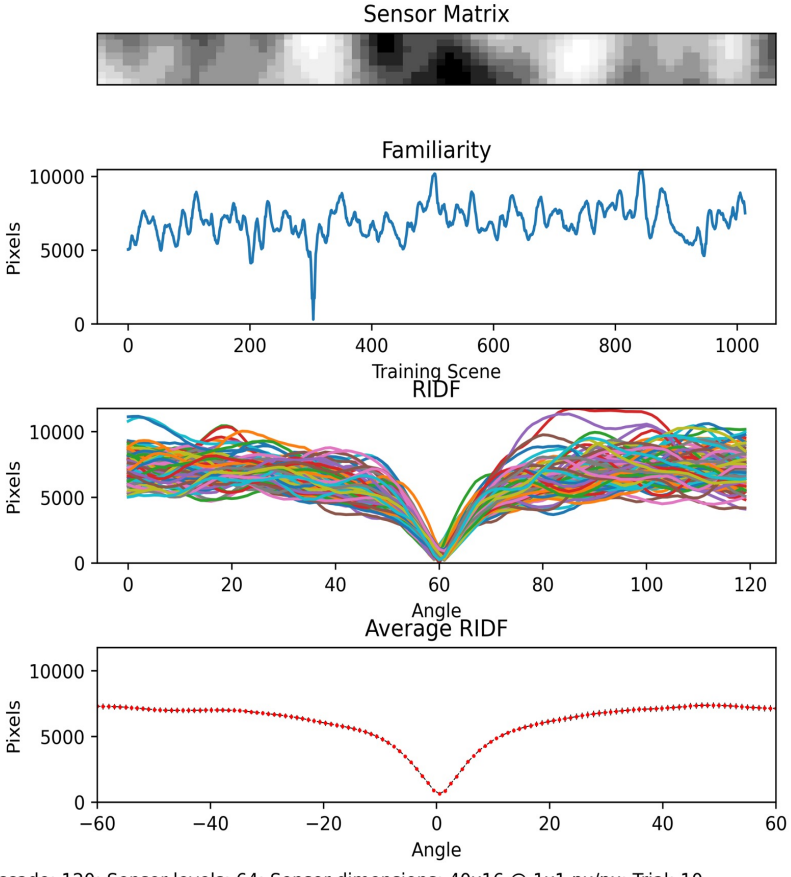


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 40.56; RMSD/dist: 0.101; TD: 5042; p90: 28; p50: 10; complete: 0

100%

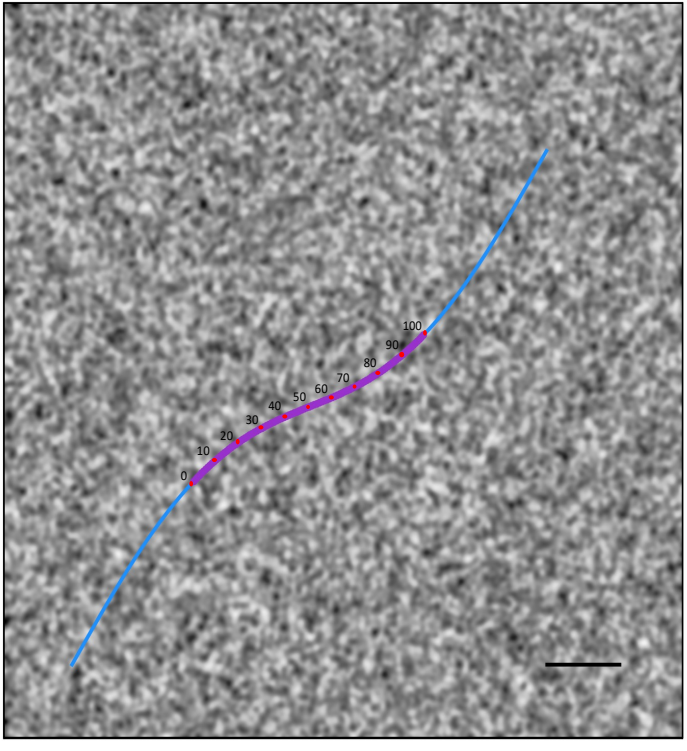


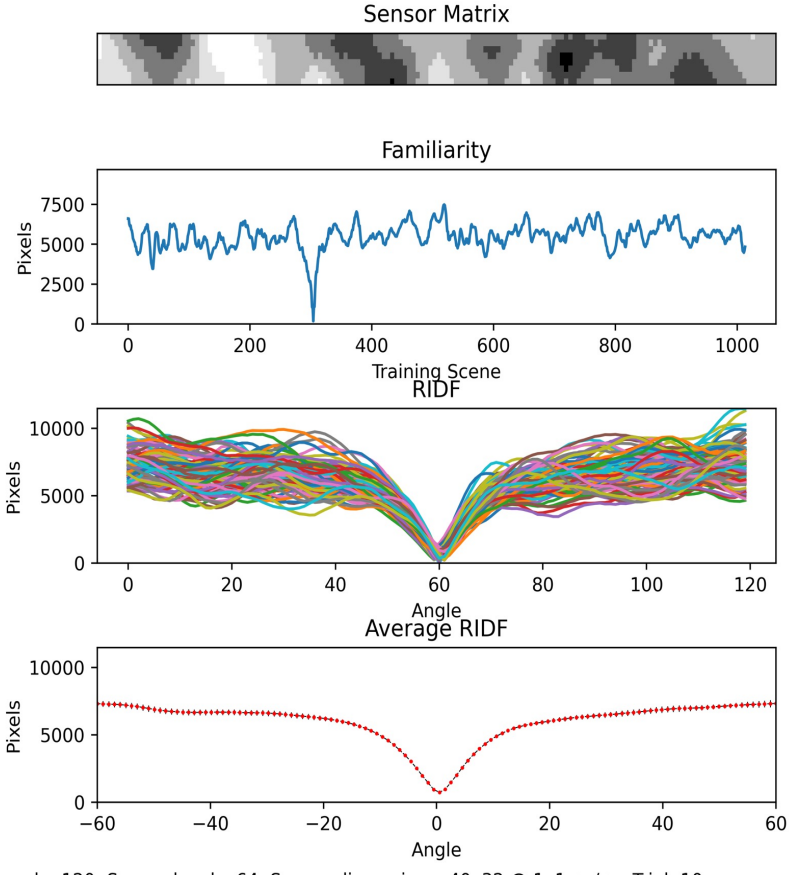


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 39.37; RMSD/dist: 0.098; TD: 5190; p90: 26; p50: 10; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 4; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 64; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 54.56; RMSD/dist: 0.136; TD: 5061; p90: 24; p50: 12; complete: 0