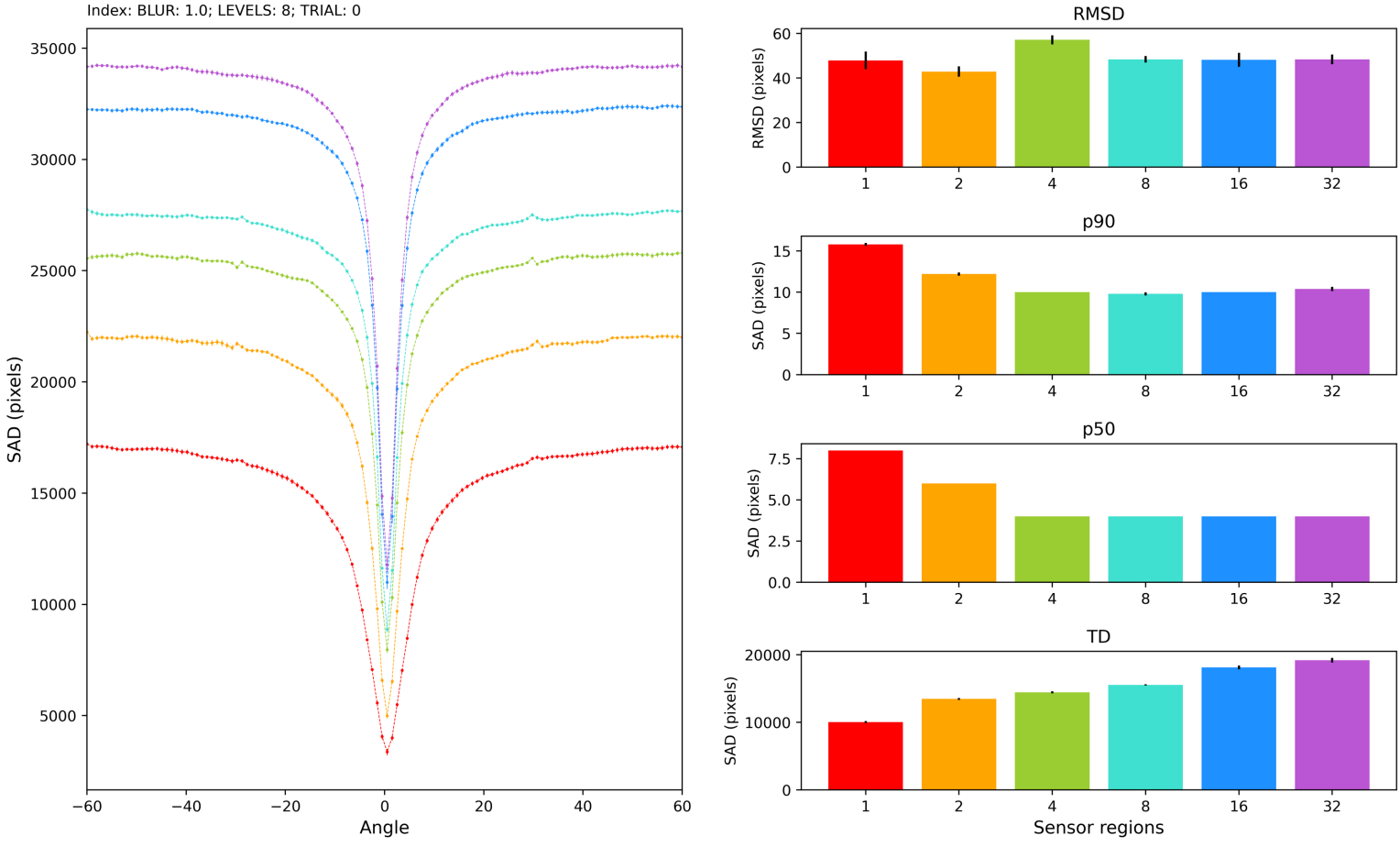
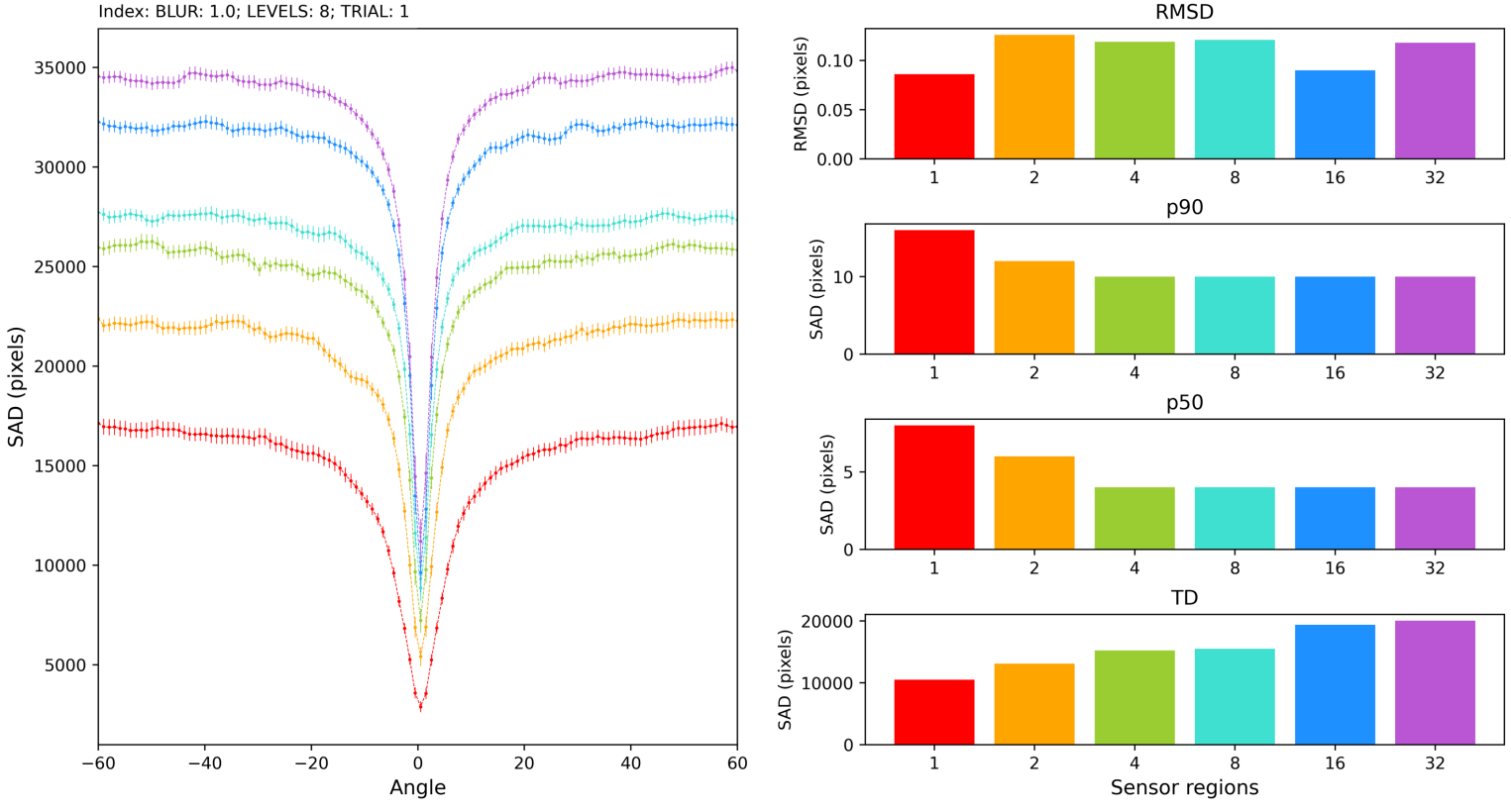
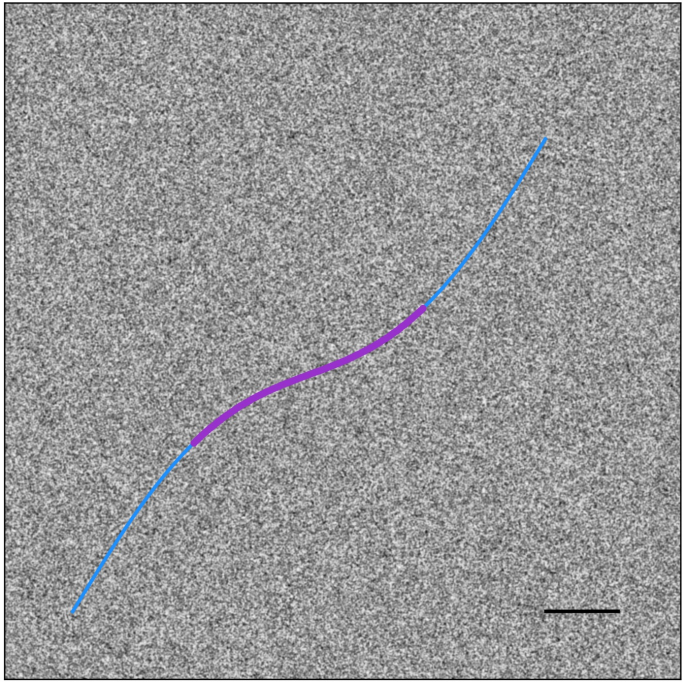
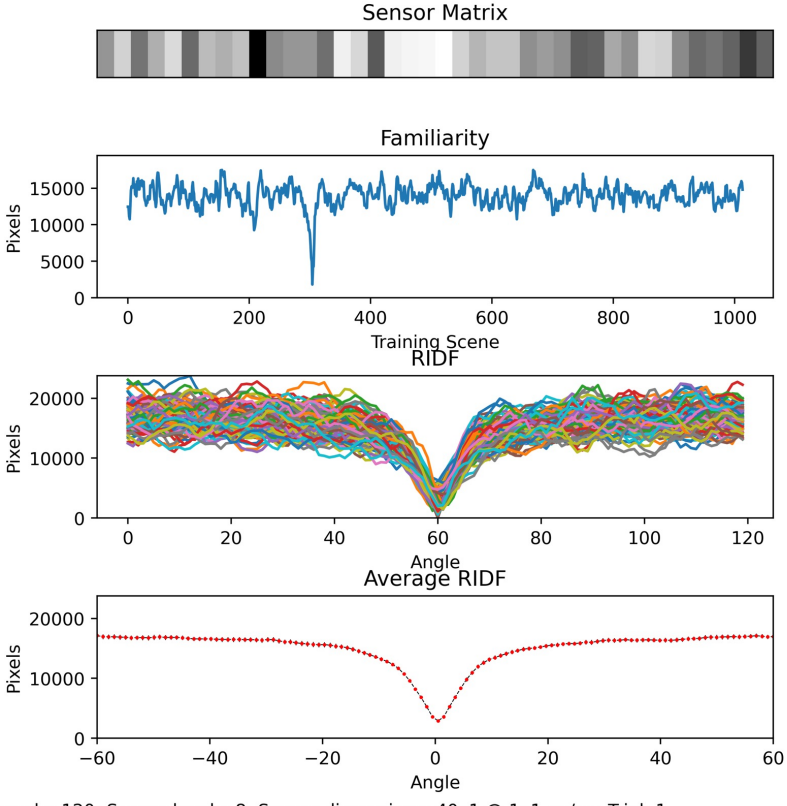

Index: BLUR: 1.0; LEVELS: 8; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

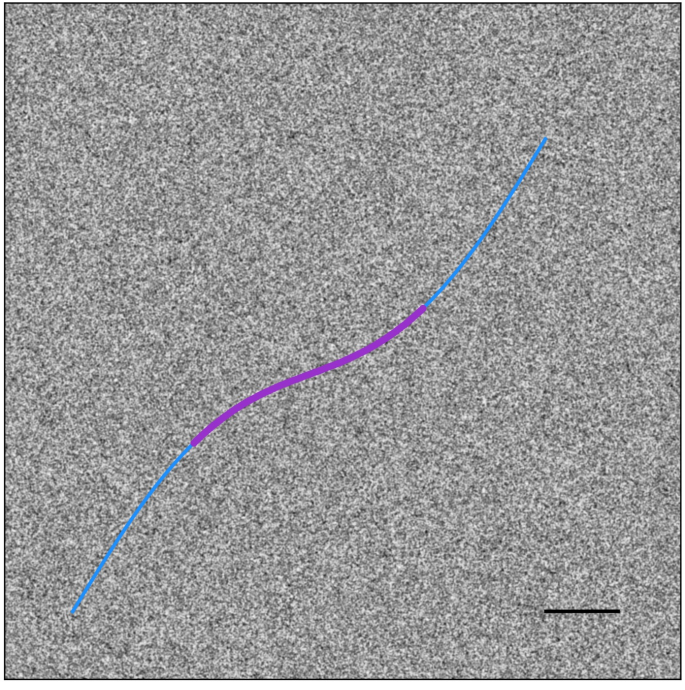

Index: BLUR: 1.0; LEVELS: 8; TRIAL: 1
SAD (pixels)
35000
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
20000
10000
0
Sensor regions

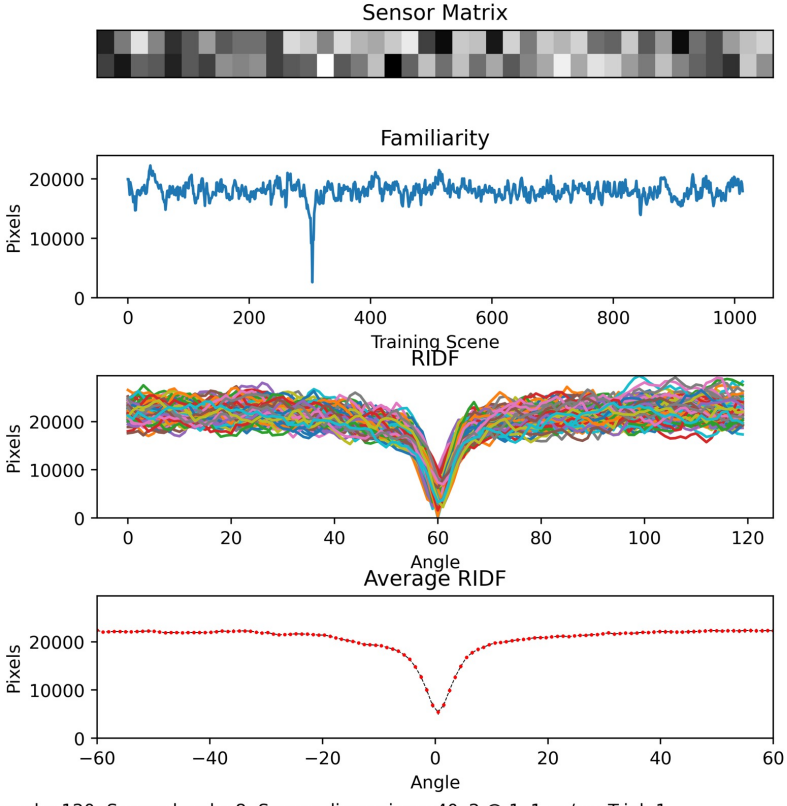




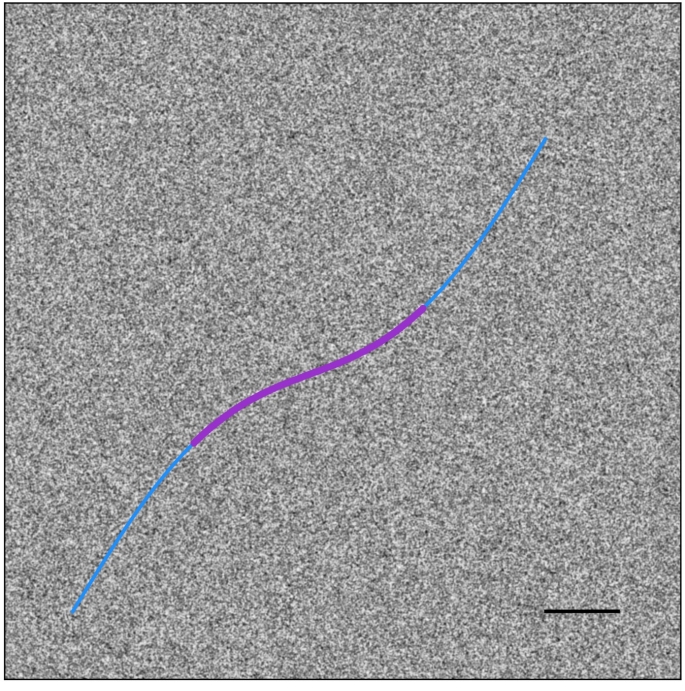
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

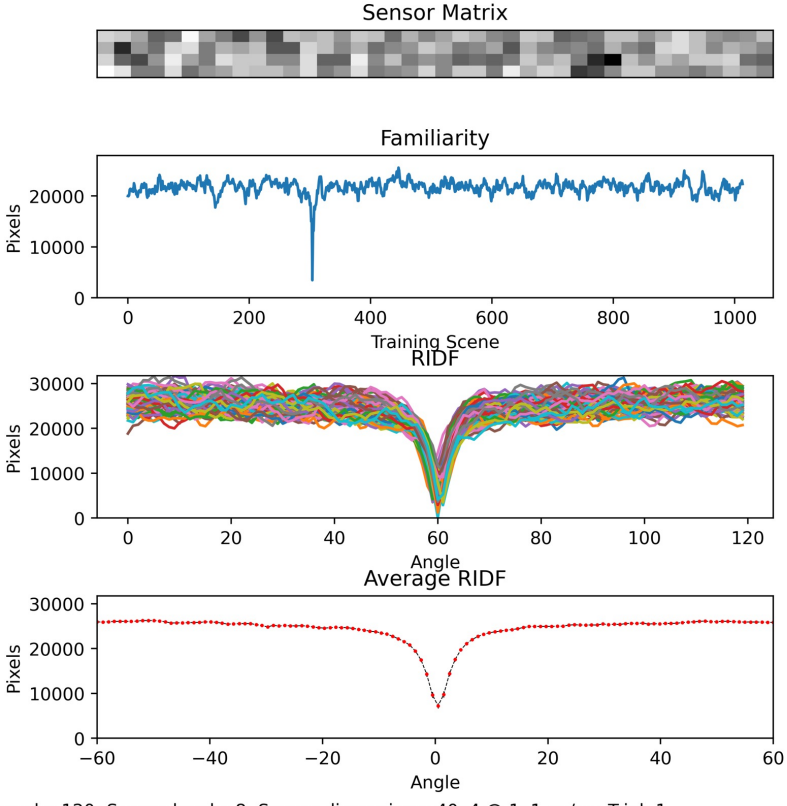
Navigation stats: RMSD error: 34.49; RMSD/dist: 0.086; TD: 10501; p90: 16; p50: 8; complete: 0



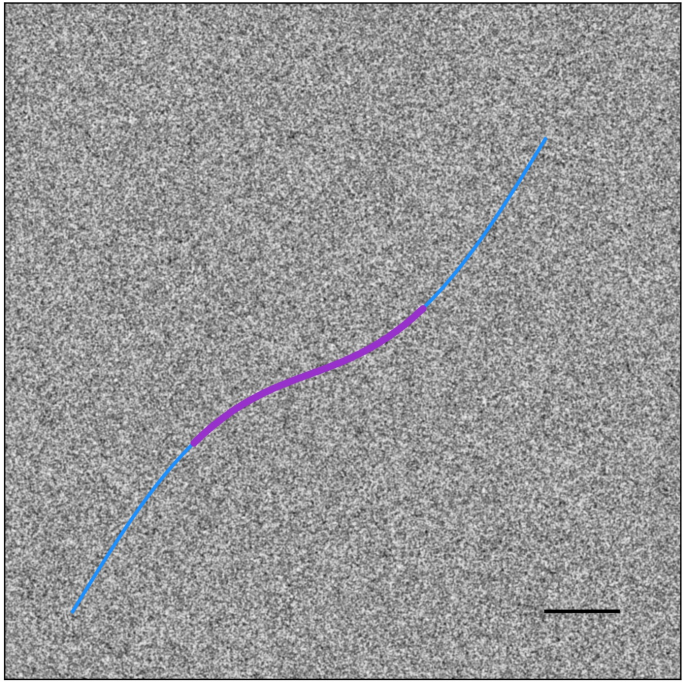


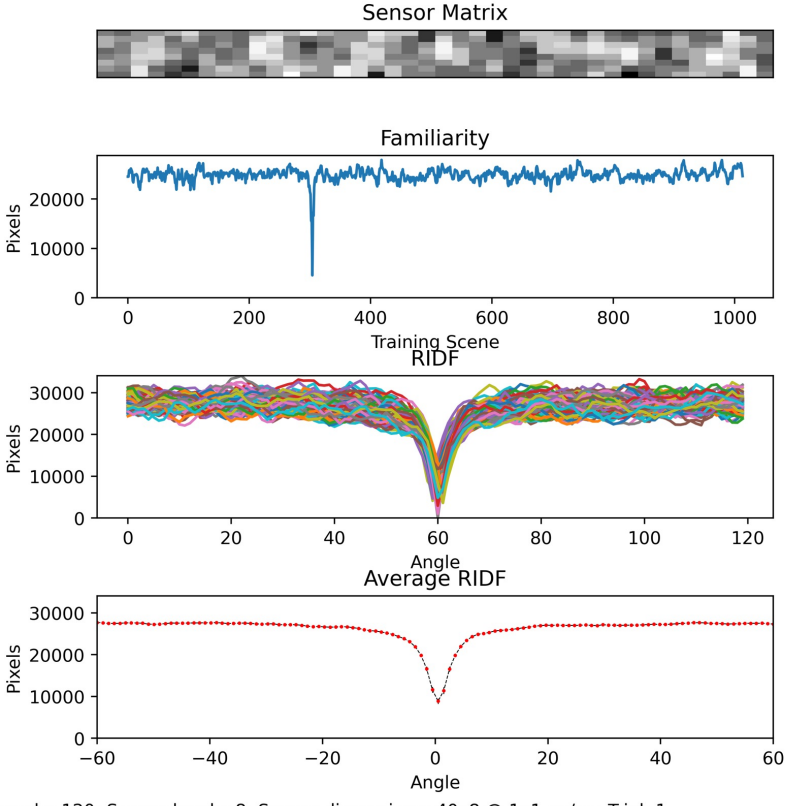
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 50.44; RMSD/dist: 0.126; TD: 13101; p90: 12; p50: 6; complete: 0



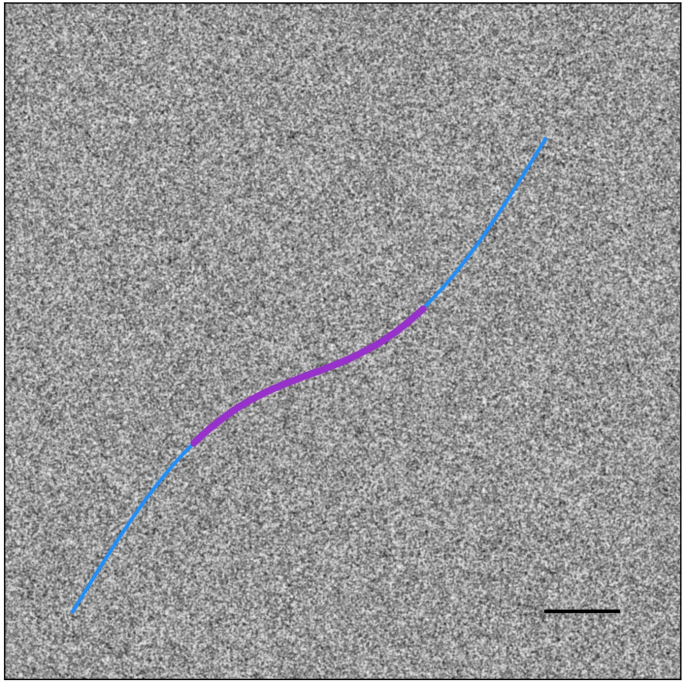


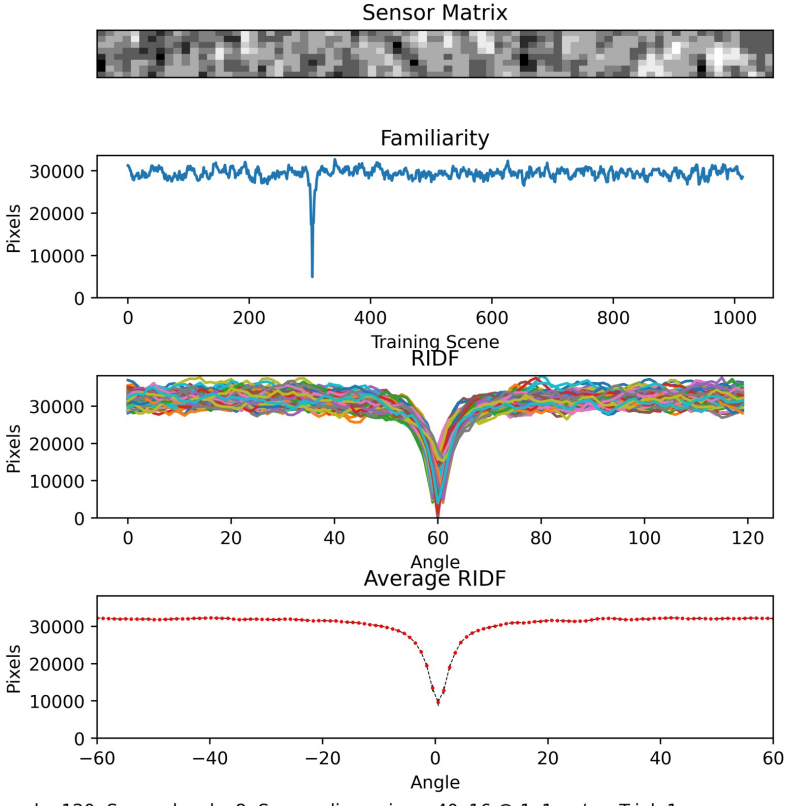
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 47.79; RMSD/dist: 0.119; TD: 15244; p90: 10; p50: 4; complete: 0





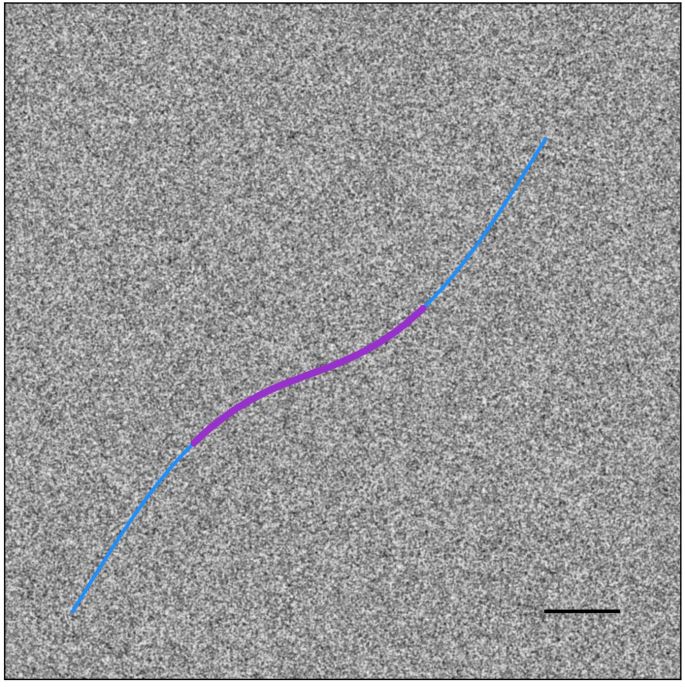
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 48.26; RMSD/dist: 0.121; TD: 15494; p90: 10; p50: 4; complete: 0

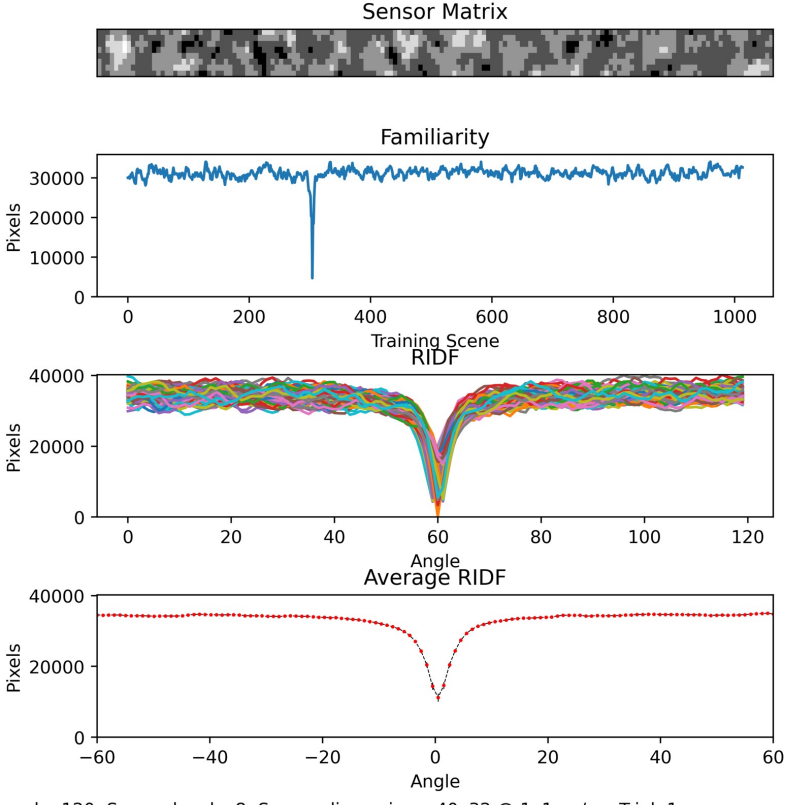




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

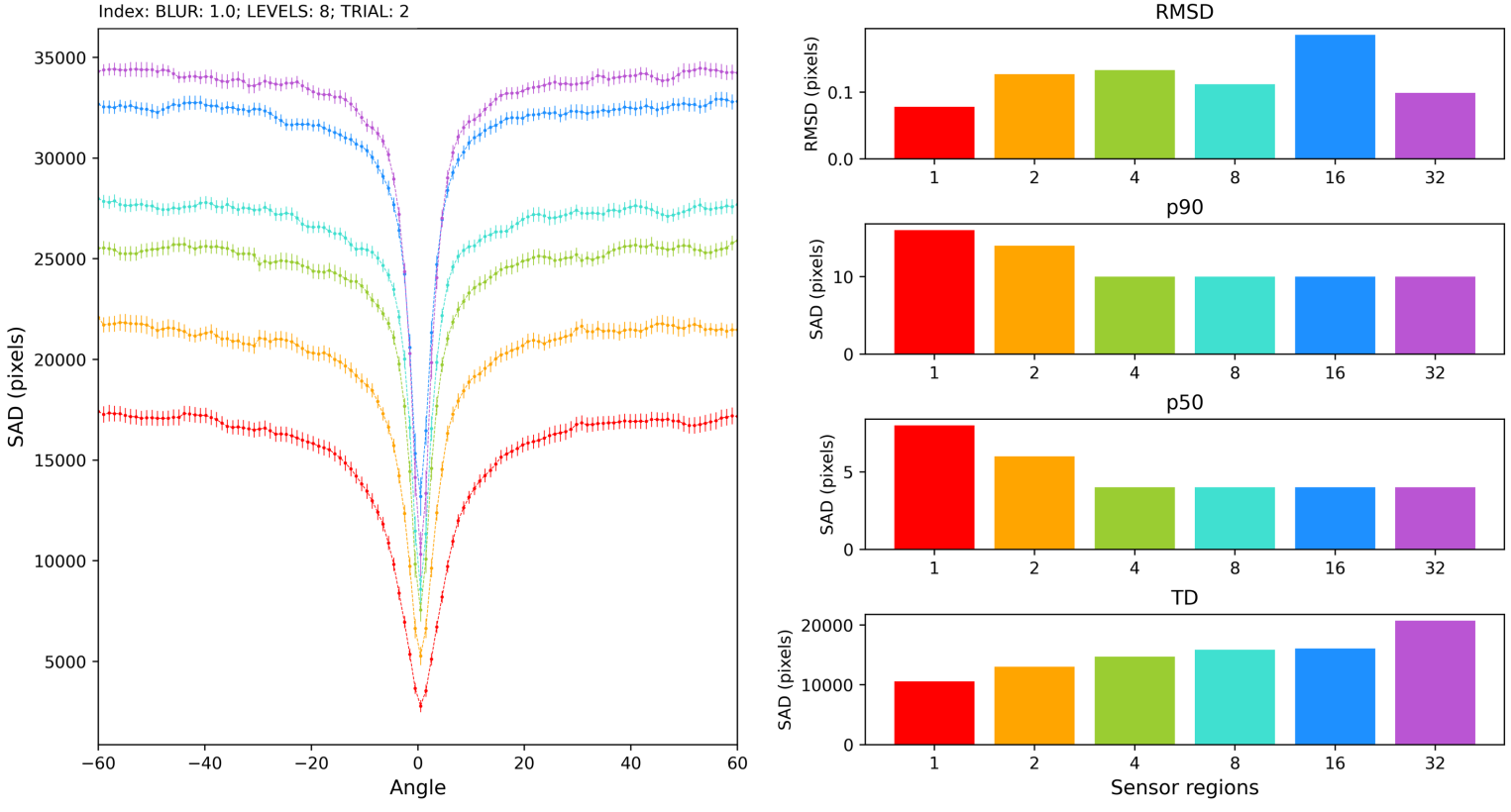
Navigation stats: RMSD error: 35.81; RMSD/dist: 0.090; TD: 19370; p90: 10; p50: 4; complete: 0

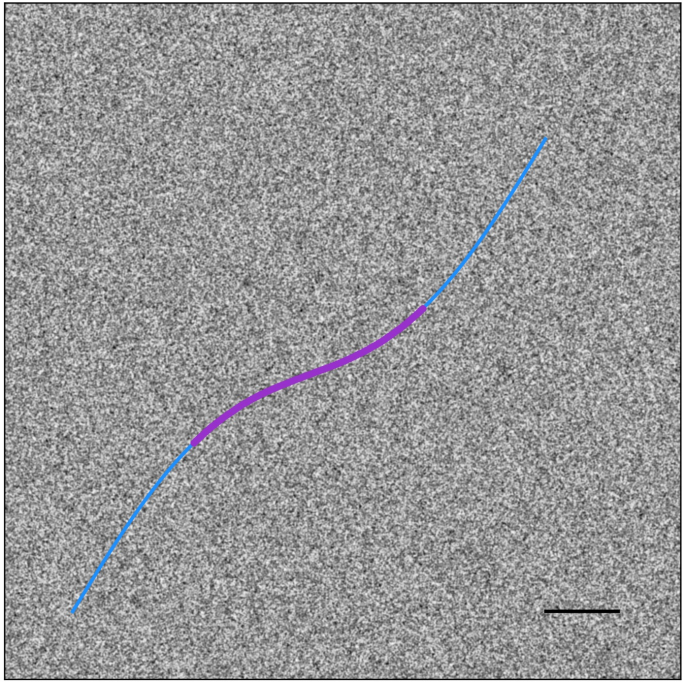


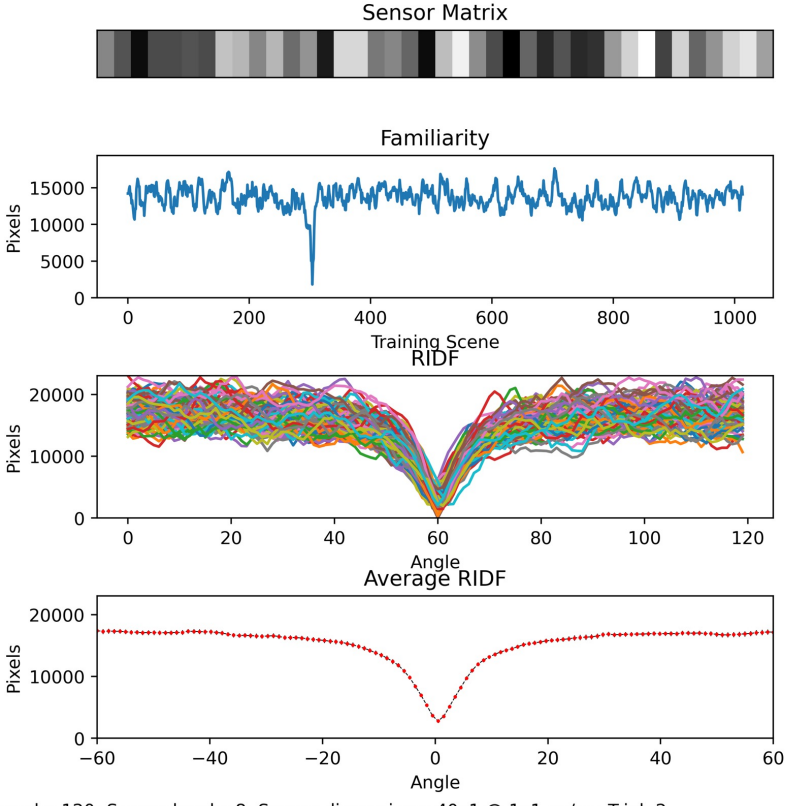


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

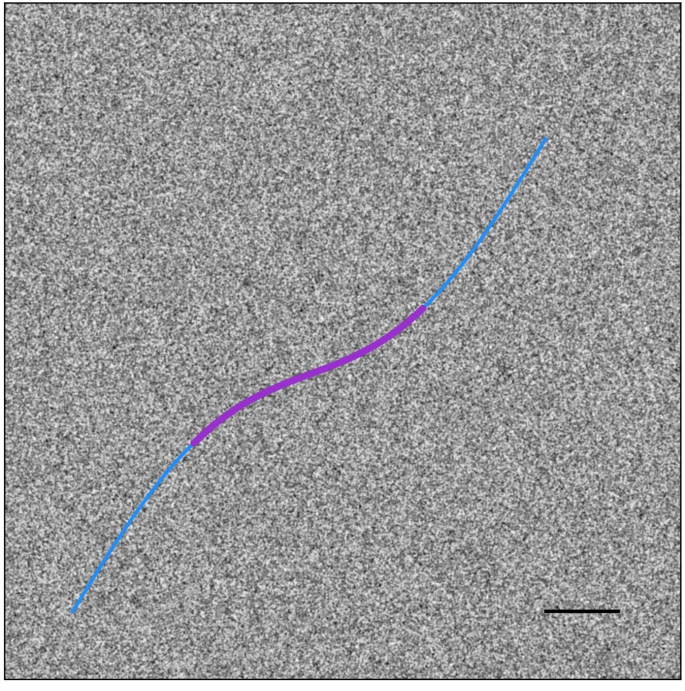
Navigation stats: RMSD error: 47.13; RMSD/dist: 0.118; TD: 20048; p90: 10; p50: 4; complete: 0

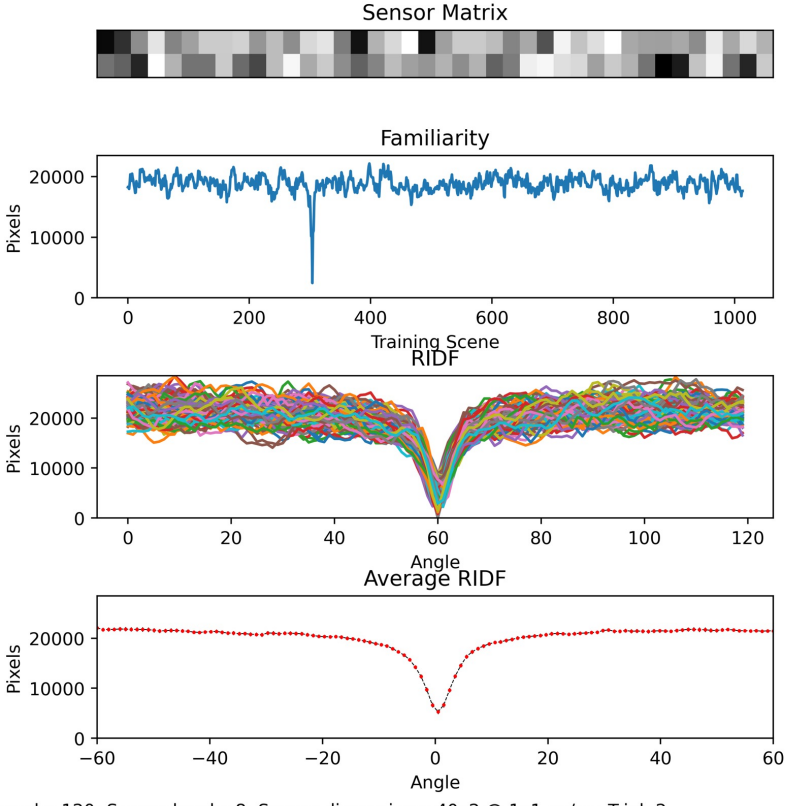

Index: BLUR: 1.0; LEVELS: 8; TRIAL: 2
SAD (pixels)
35000
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
20000
10000
0
Sensor regions



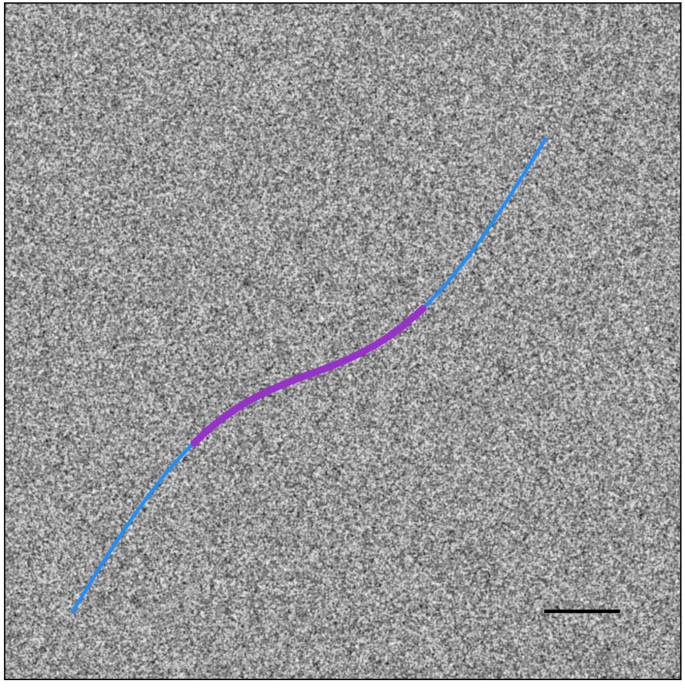


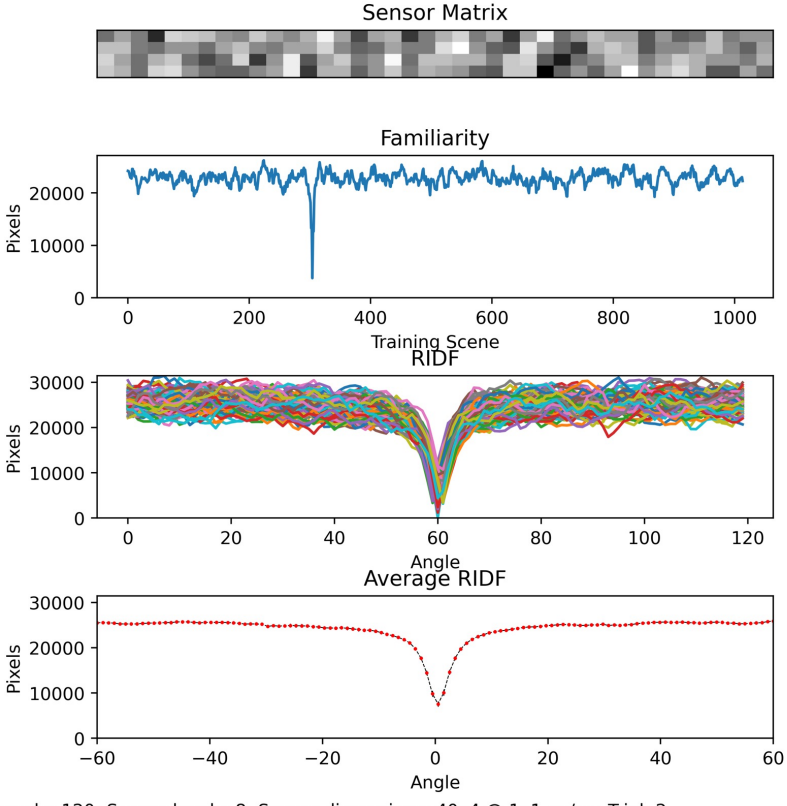
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 31.20; RMSD/dist: 0.078; TD: 10578; p90: 16; p50: 8; complete: 0



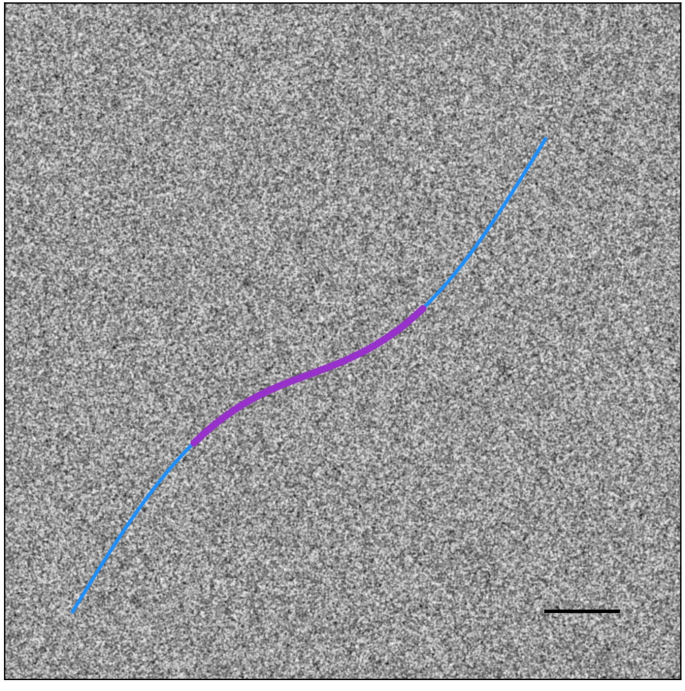


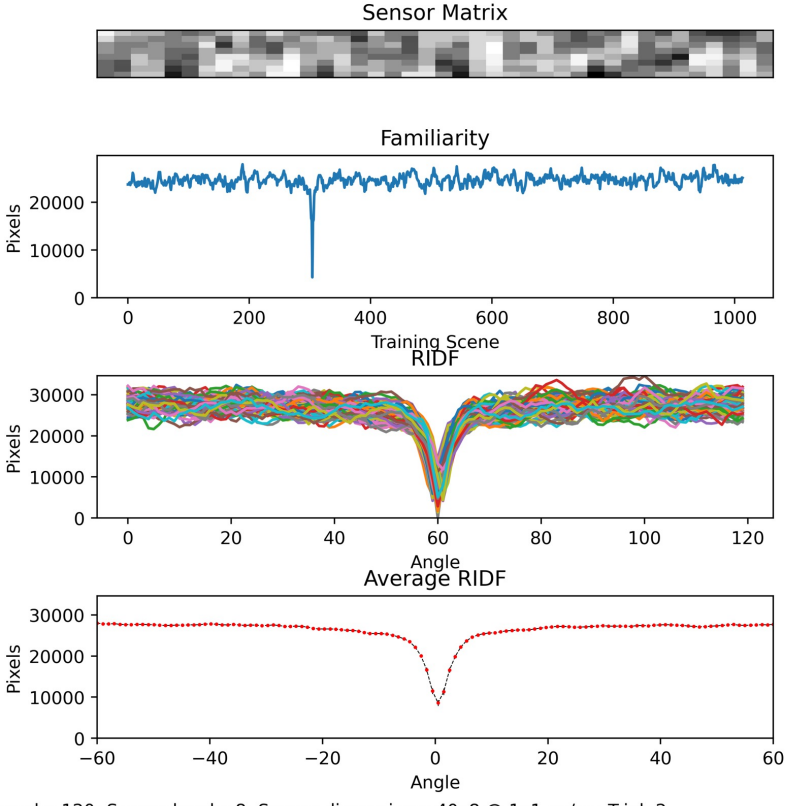
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 50.83; RMSD/dist: 0.127; TD: 13034; p90: 14; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 53.17; RMSD/dist: 0.133; TD: 14724; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2
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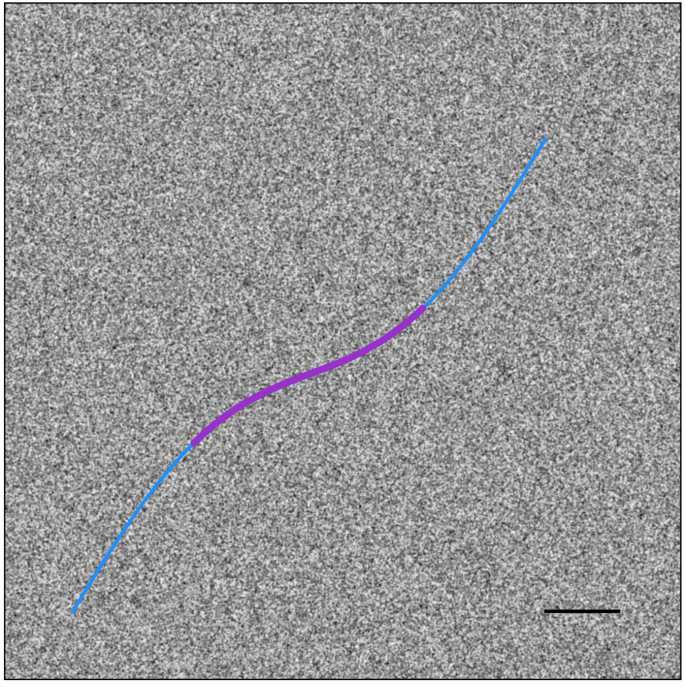
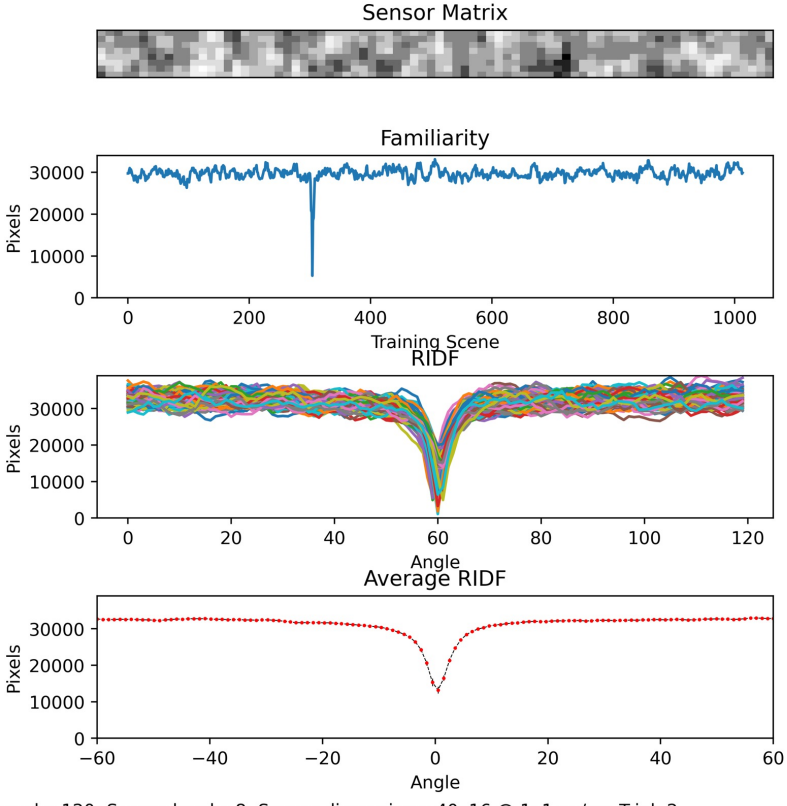
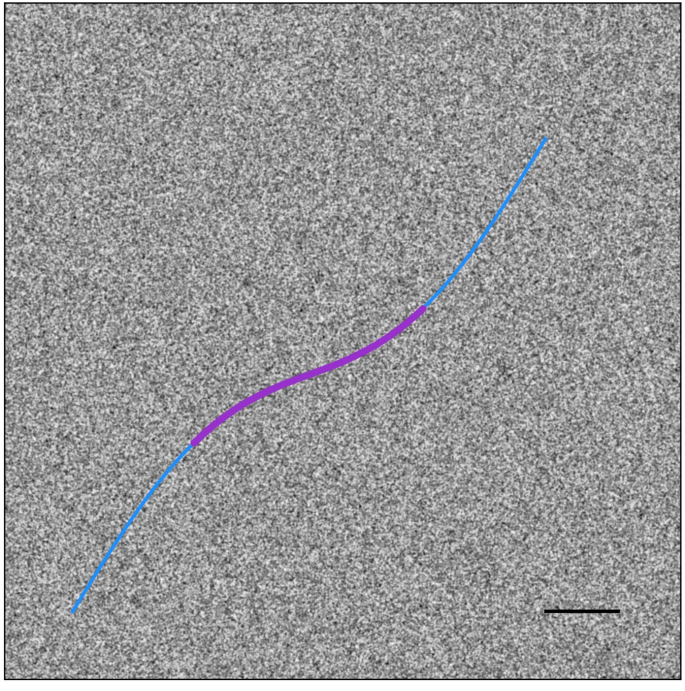
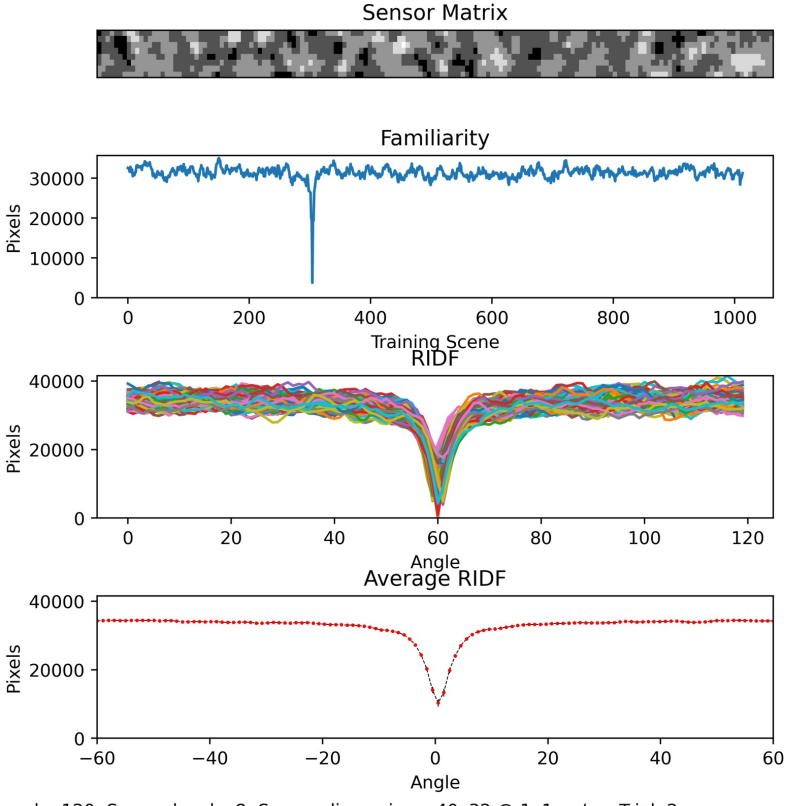


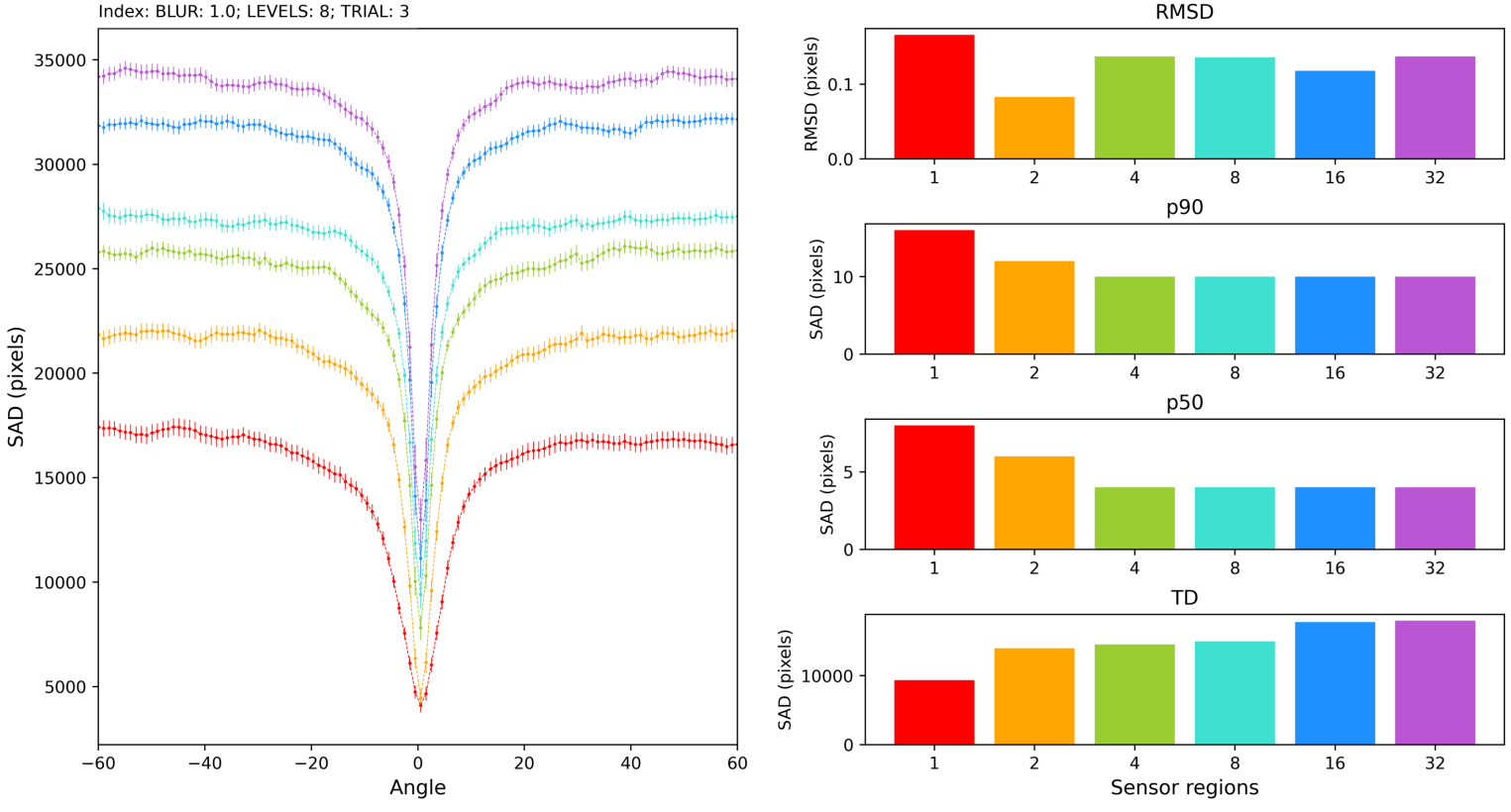


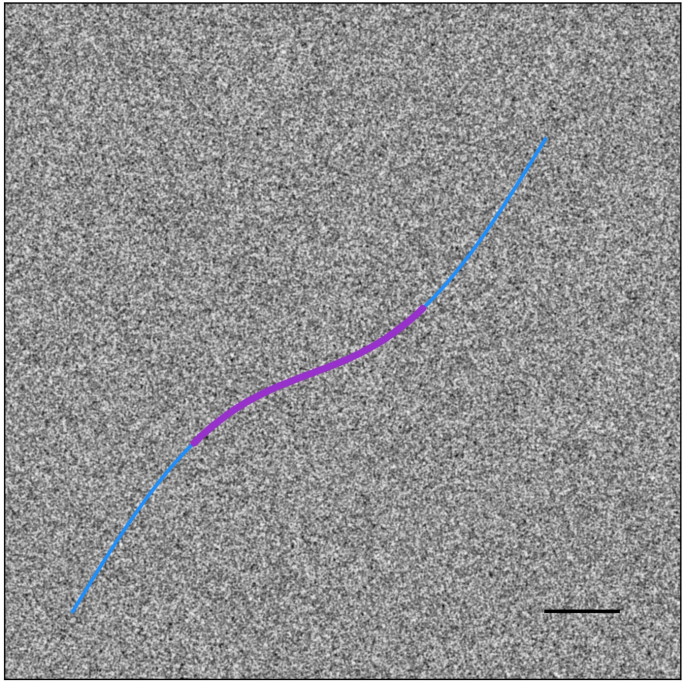
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 74.43; RMSD/dist: 0.186; TD: 16084; p90: 10; p50: 4; complete: 0

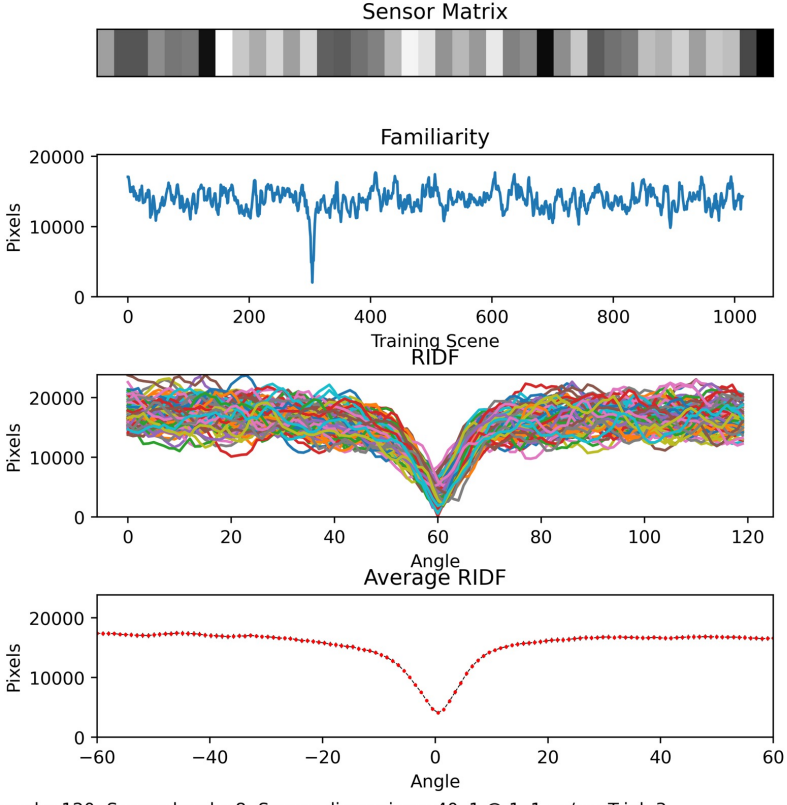




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 39.65; RMSD/dist: 0.099; TD: 20730; p90: 10; p50: 4; complete: 0

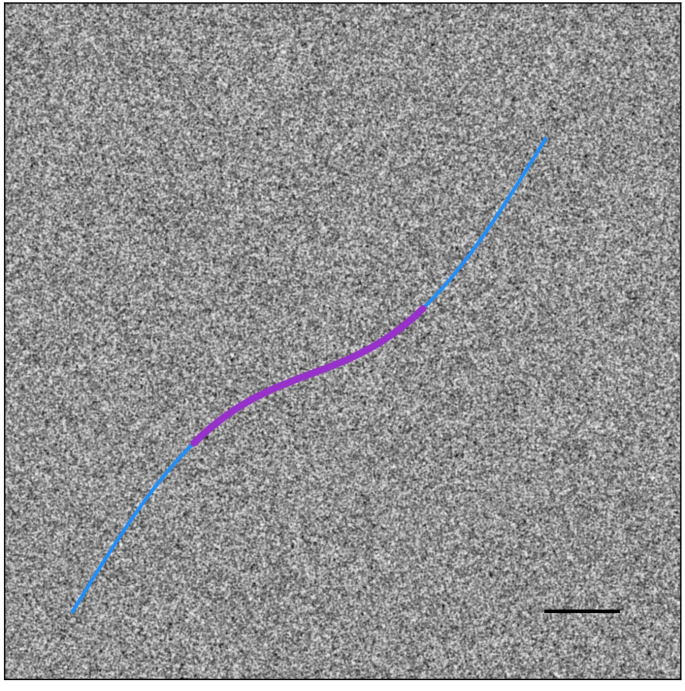

Index: BLUR: 1.0; LEVELS: 8; TRIAL: 3
SAD (pixels)
35000
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
Sensor regions

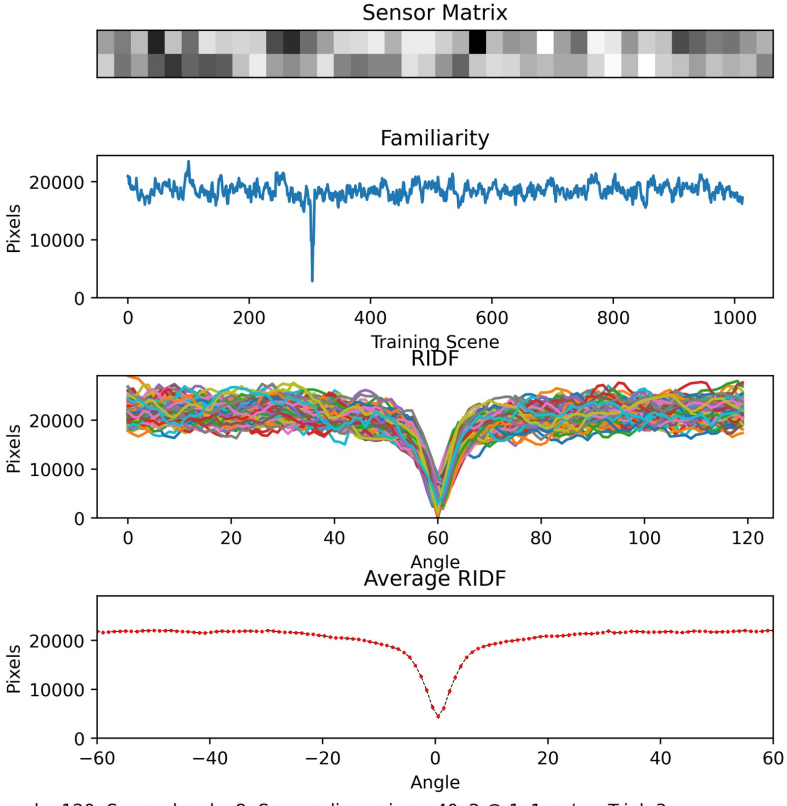




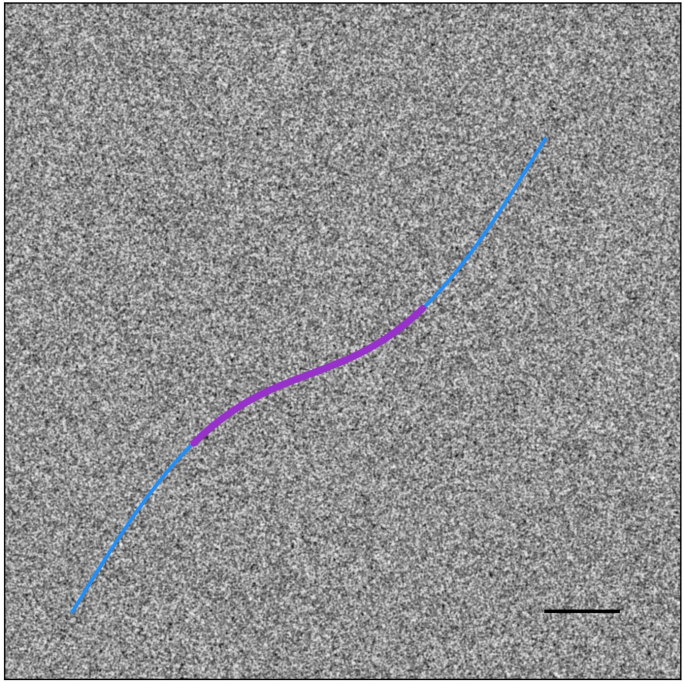
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

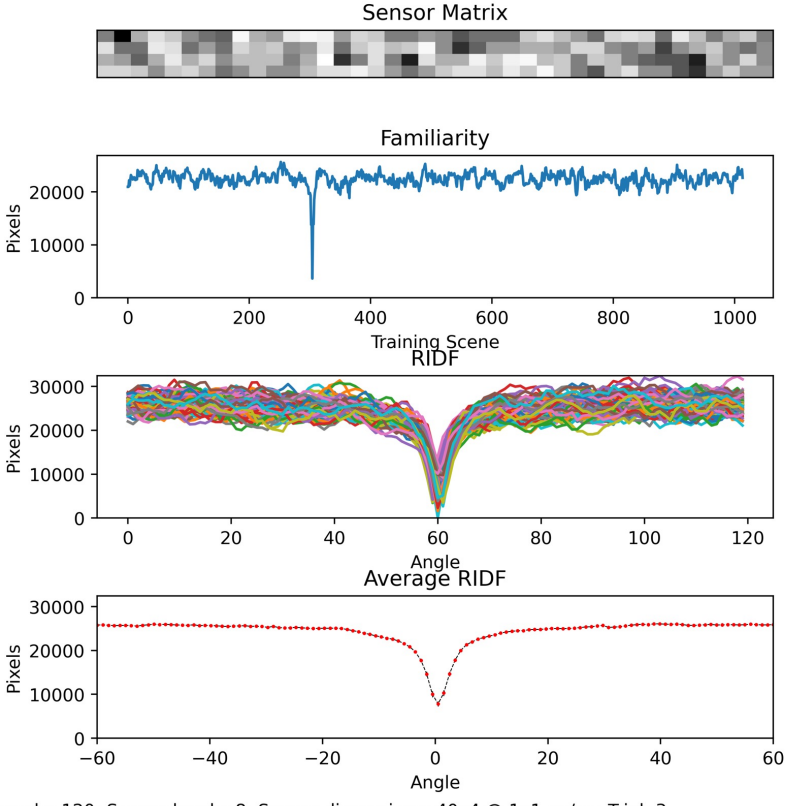
Navigation stats: RMSD error: 66.54; RMSD/dist: 0.166; TD: 9337; p90: 16; p50: 8; complete: 0



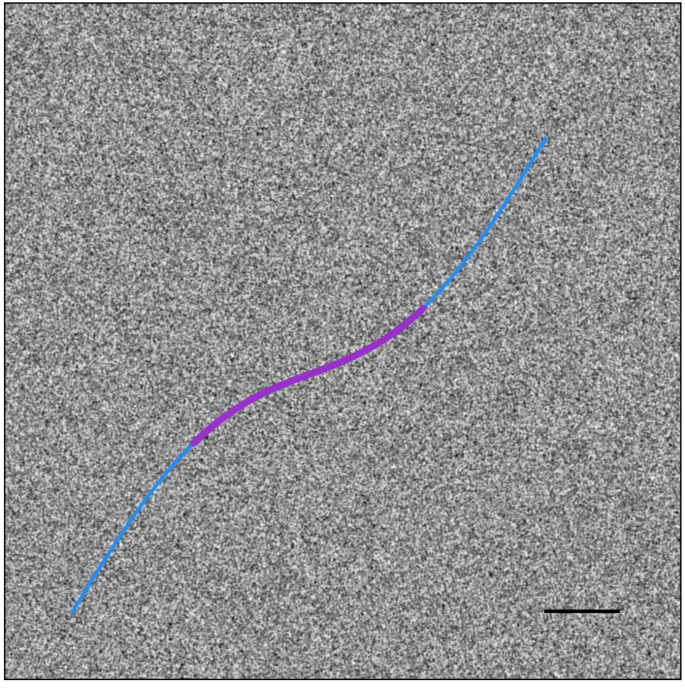


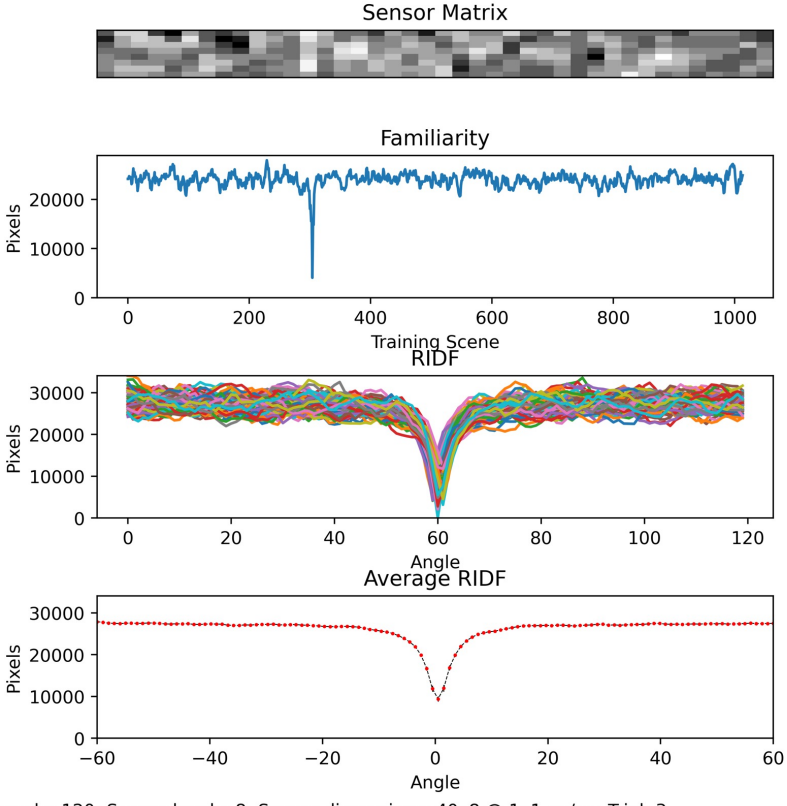
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 33.27; RMSD/dist: 0.083; TD: 13991; p90: 12; p50: 6; complete: 0



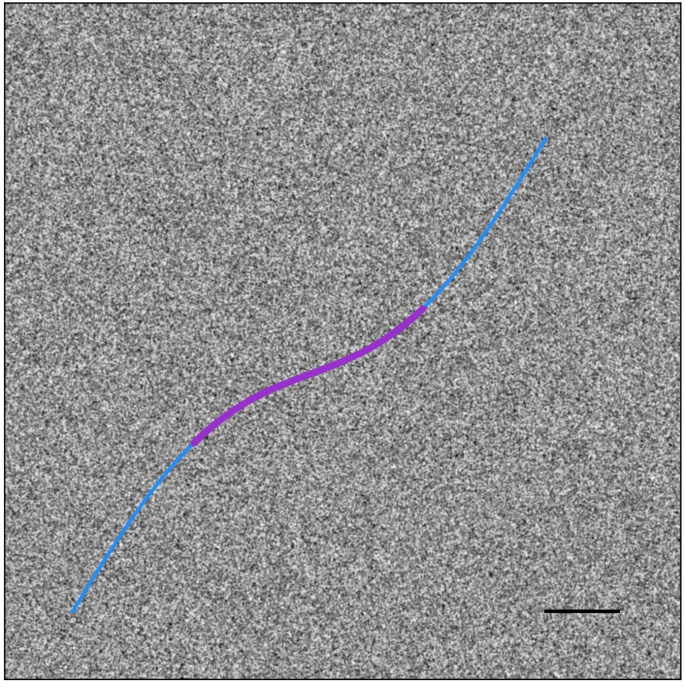


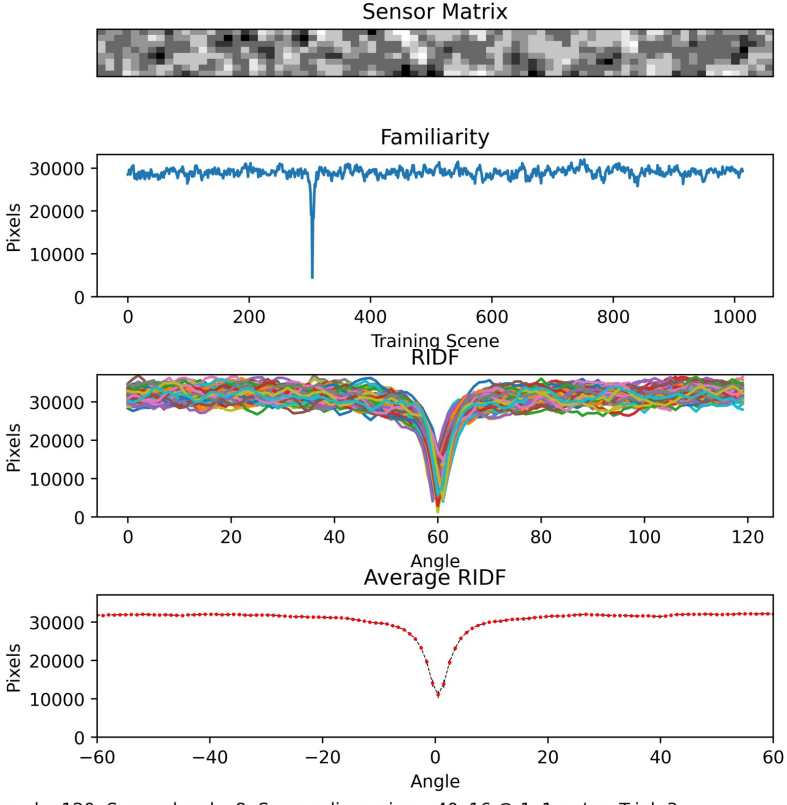
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 54.63; RMSD/dist: 0.137; TD: 14537; p90: 10; p50: 4; complete: 0



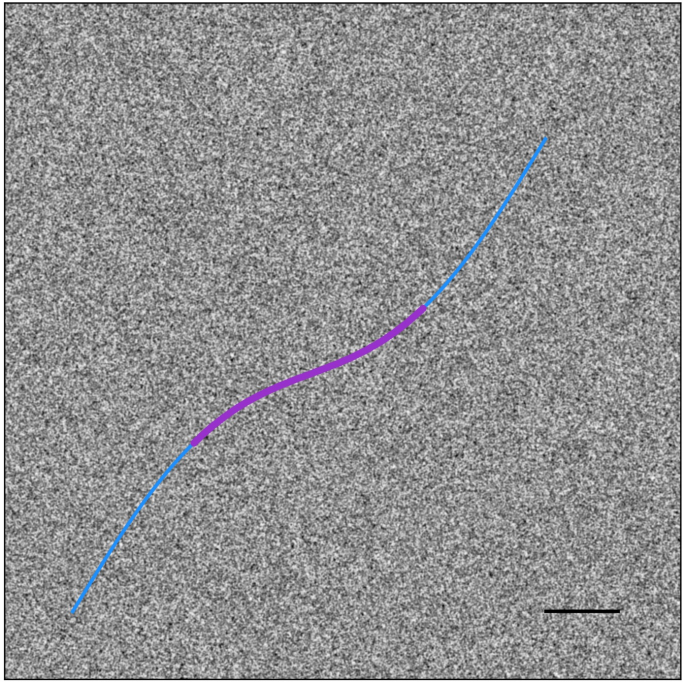


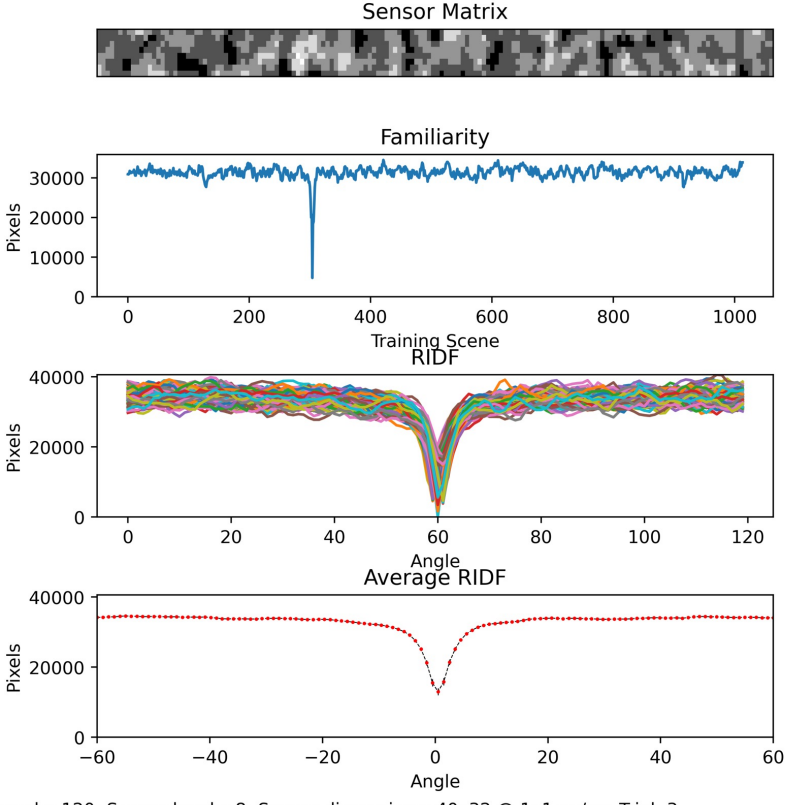
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 54.57; RMSD/dist: 0.136; TD: 14993; p90: 10; p50: 4; complete: 0



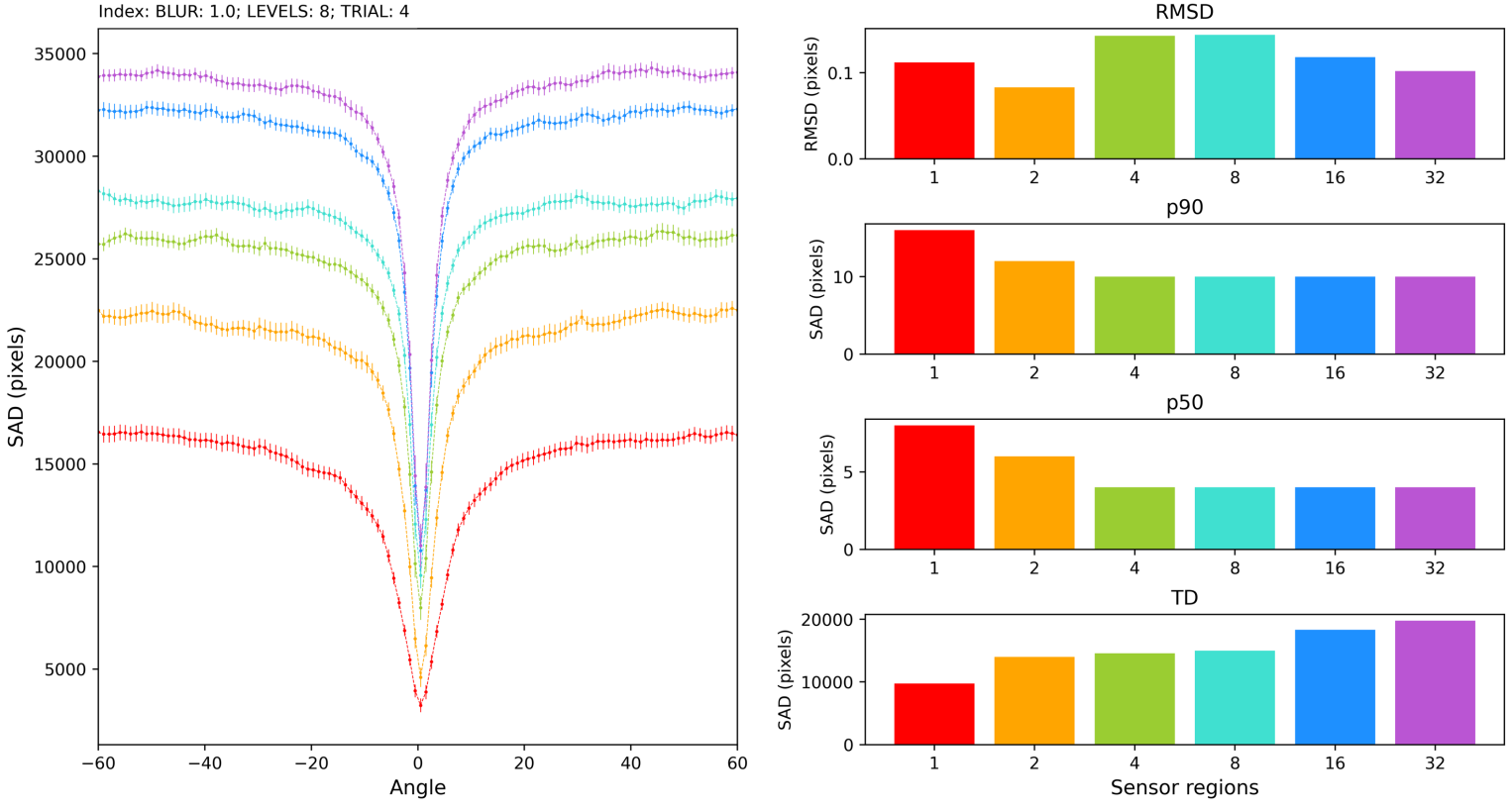


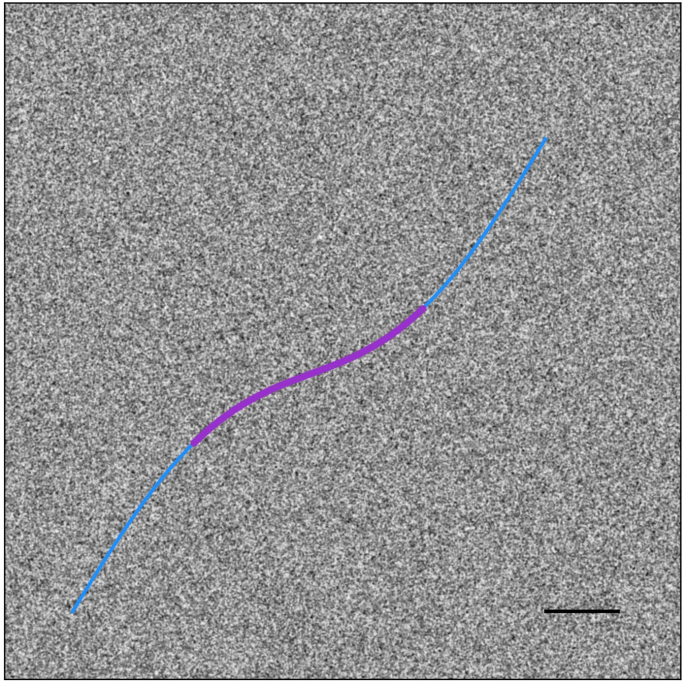
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 47.23; RMSD/dist: 0.118; TD: 17782; p90: 10; p50: 4; complete: 0

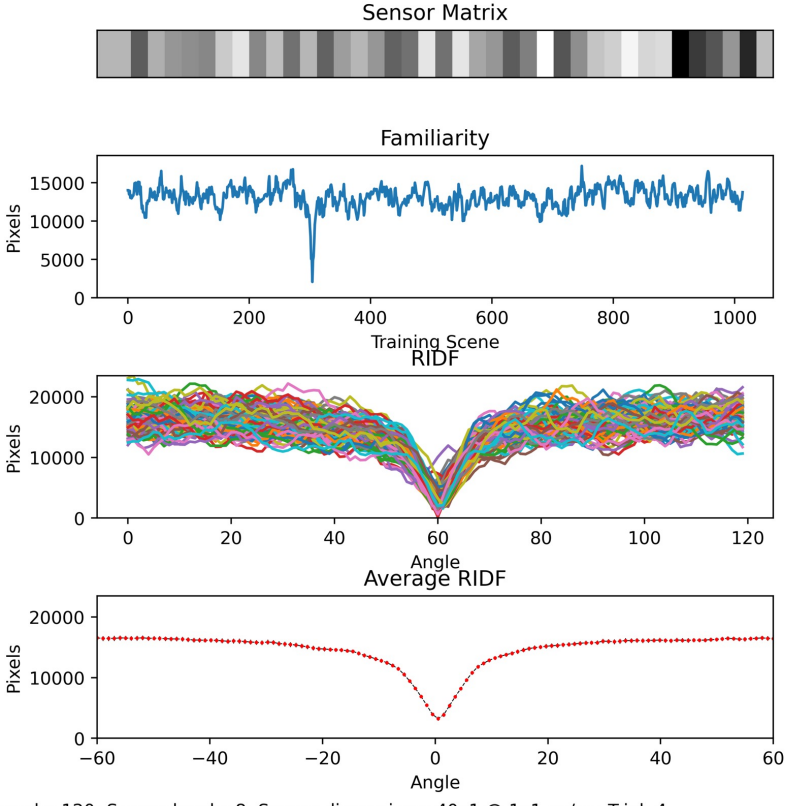




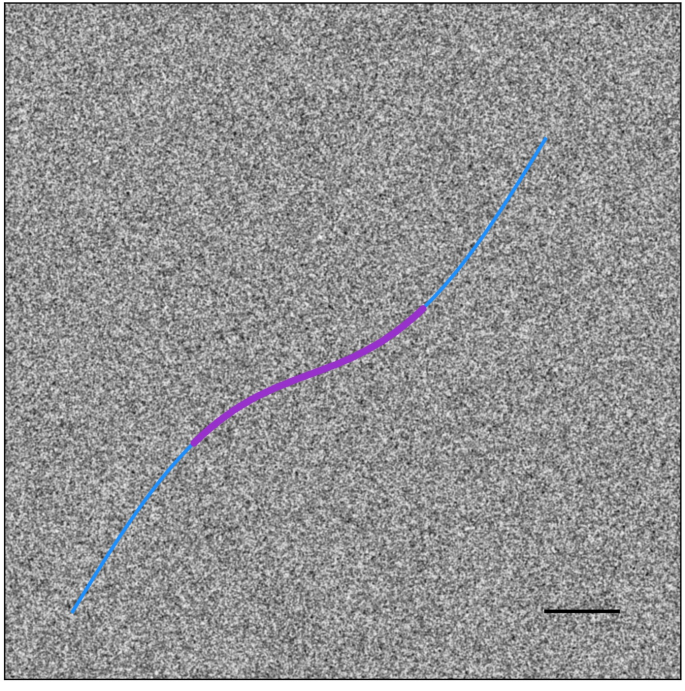
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 54.93; RMSD/dist: 0.137; TD: 17982; p90: 10; p50: 4; complete: 0

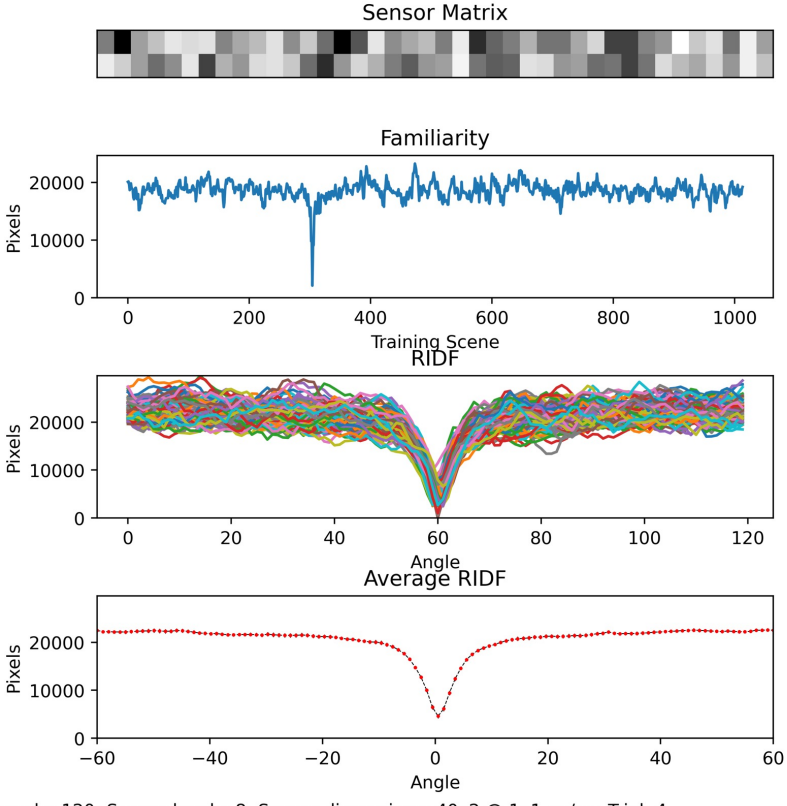

Index: BLUR: 1.0; LEVELS: 8; TRIAL: 4
SAD (pixels)
35000
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
20000
10000
0
Sensor regions



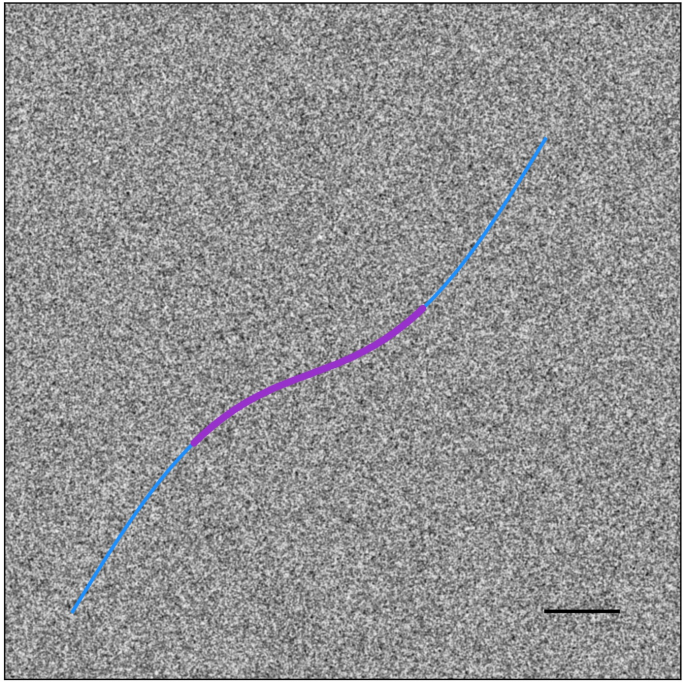


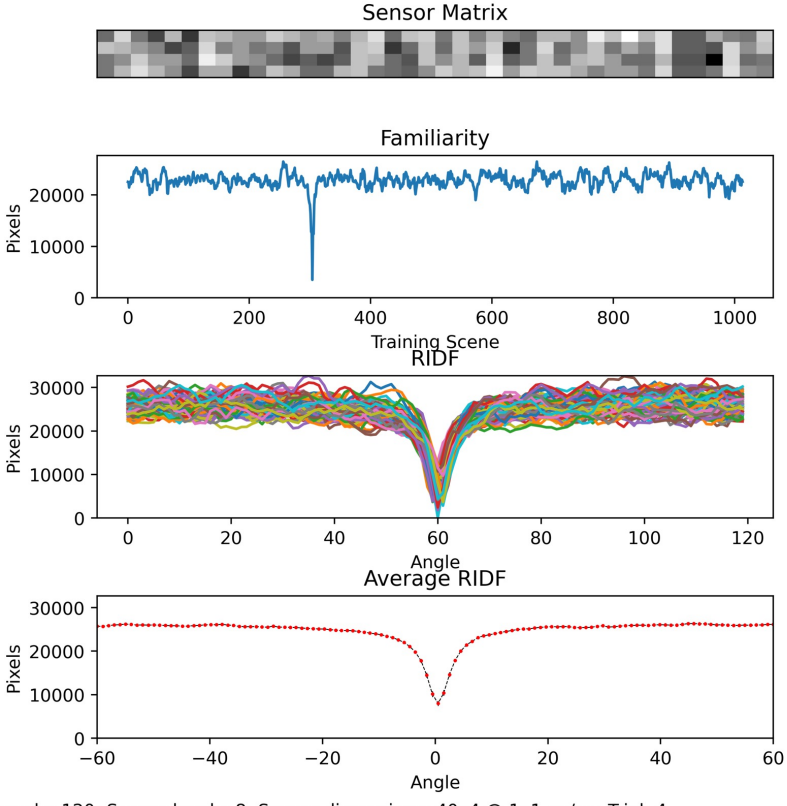
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 45.00; RMSD/dist: 0.112; TD: 9744; p90: 16; p50: 8; complete: 0



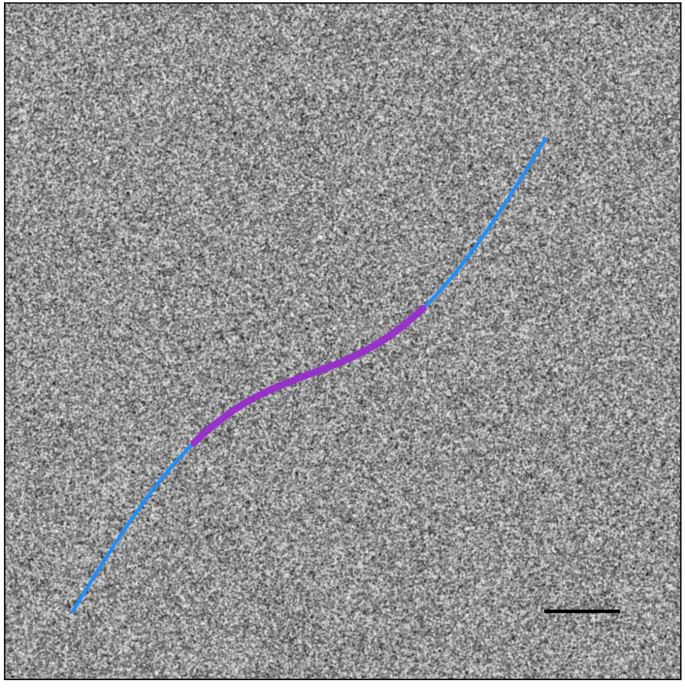


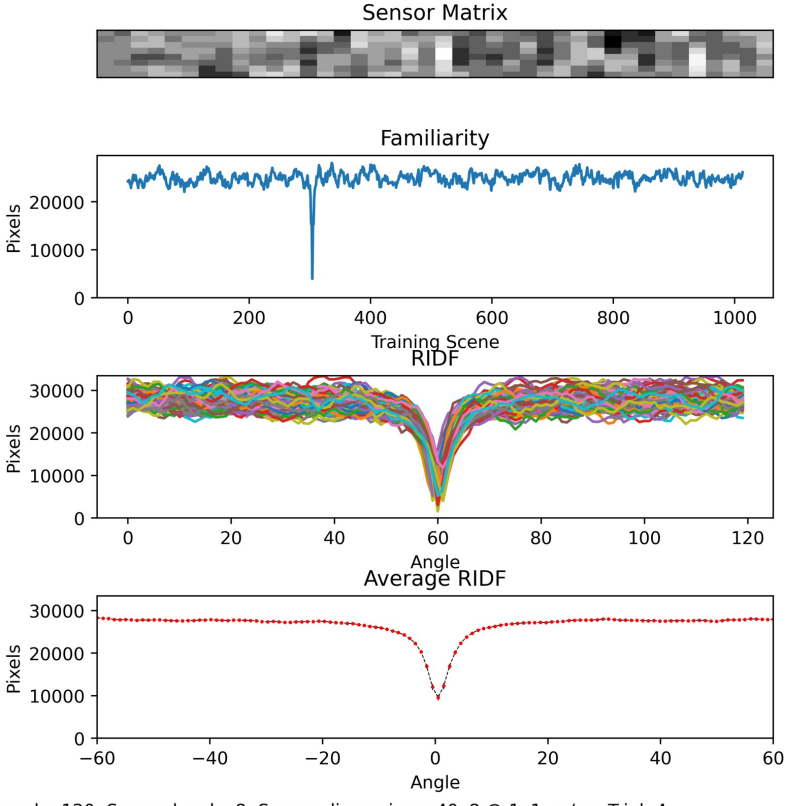
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 33.29; RMSD/dist: 0.083; TD: 14002; p90: 12; p50: 6; complete: 0



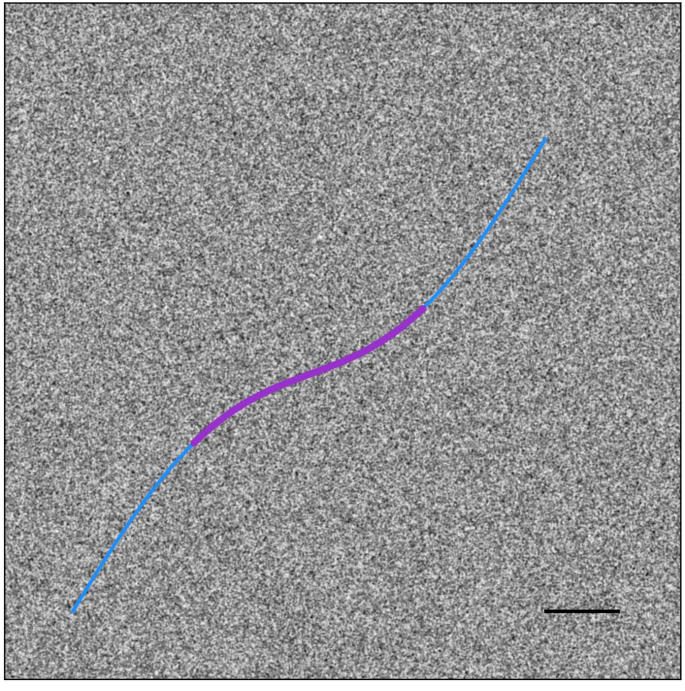


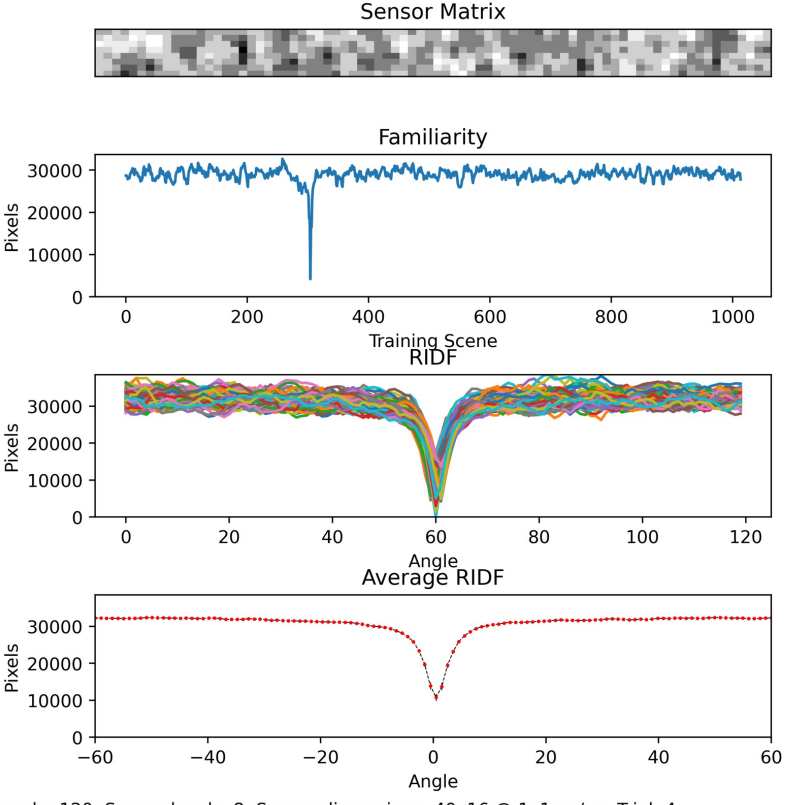
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 57.11; RMSD/dist: 0.143; TD: 14569; p90: 10; p50: 4; complete: 0



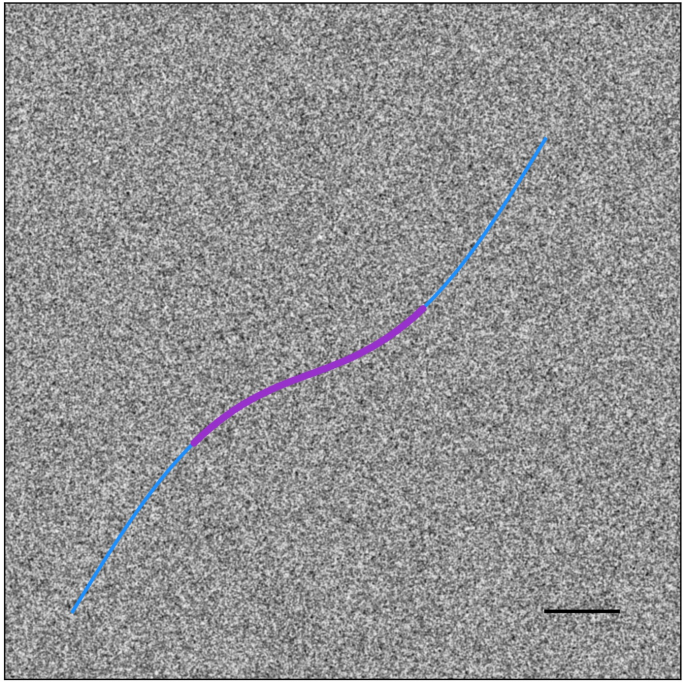


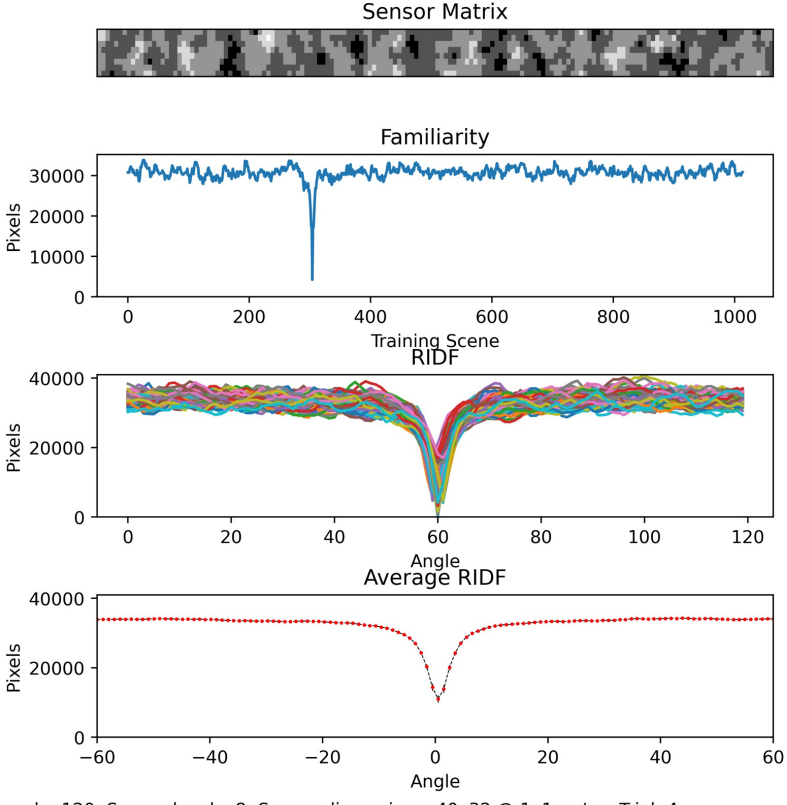
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 57.41; RMSD/dist: 0.144; TD: 15002; p90: 10; p50: 4; complete: 0



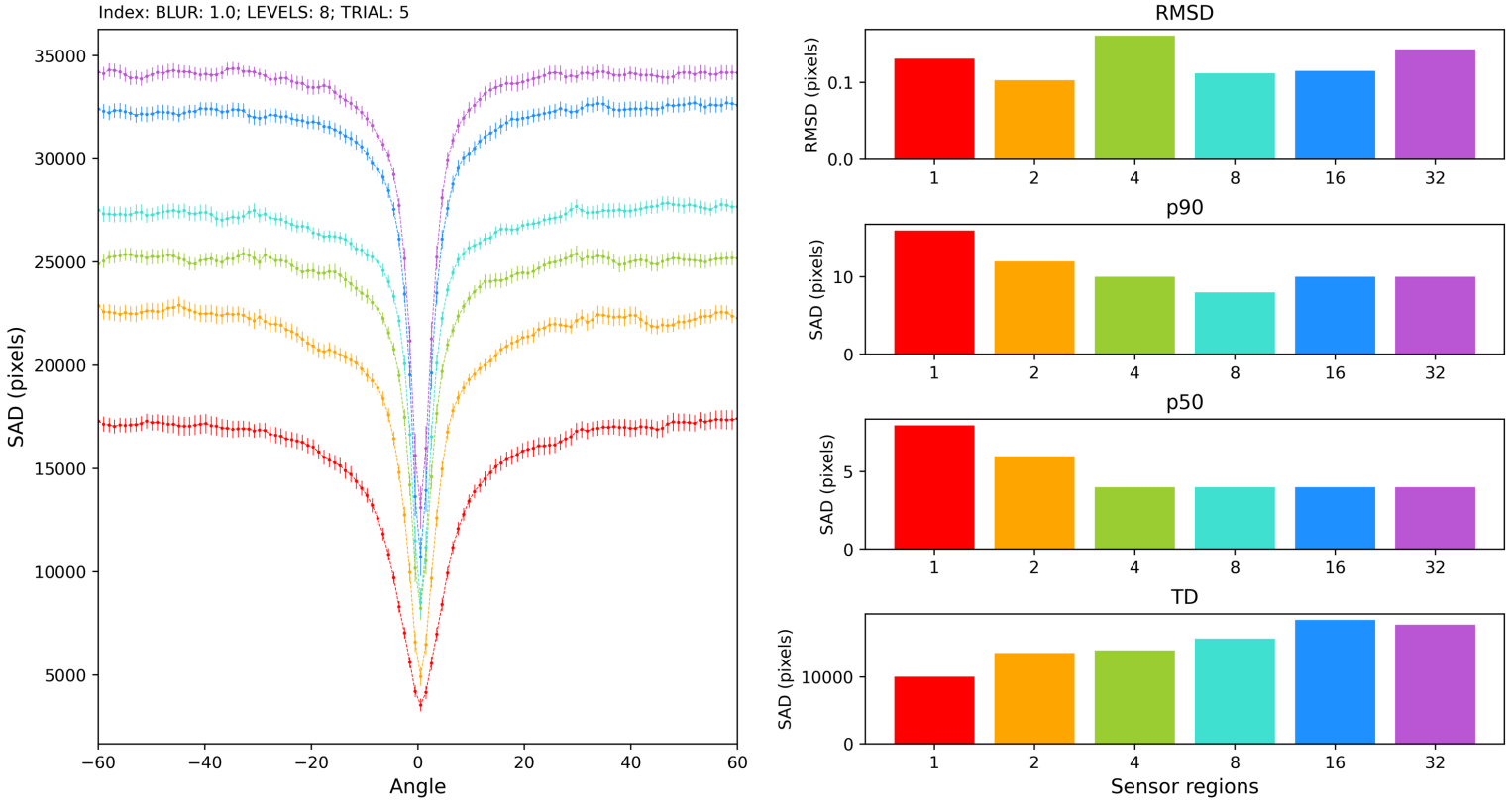


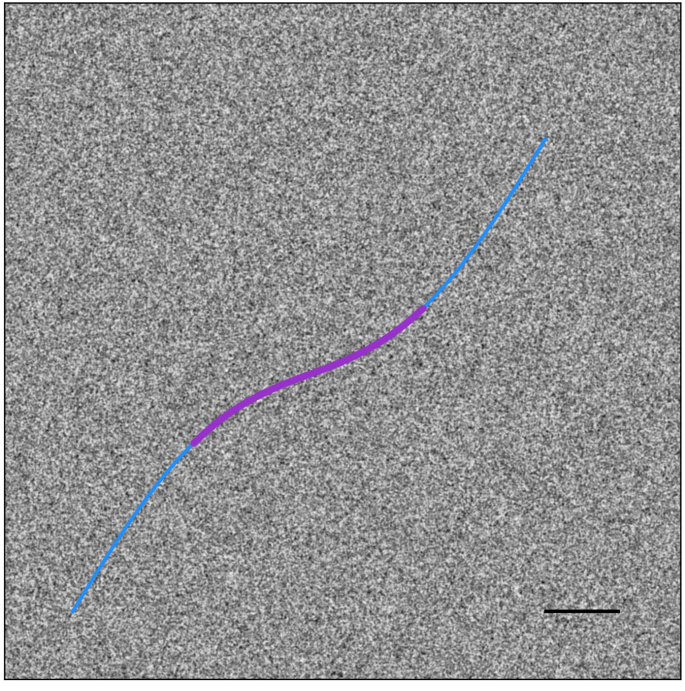
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 47.02; RMSD/dist: 0.118; TD: 18317; p90: 10; p50: 4; complete: 0

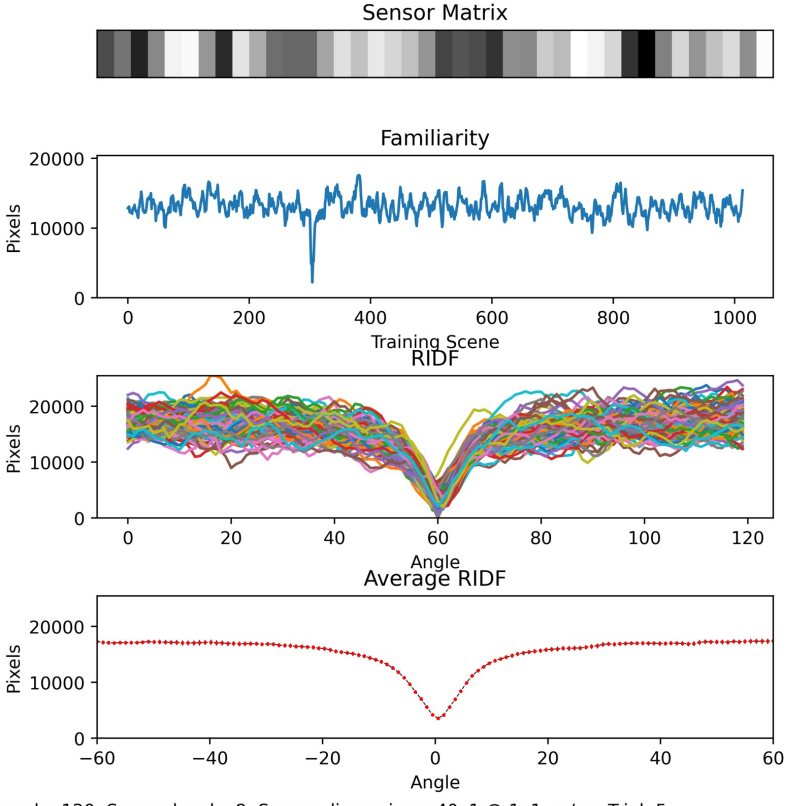




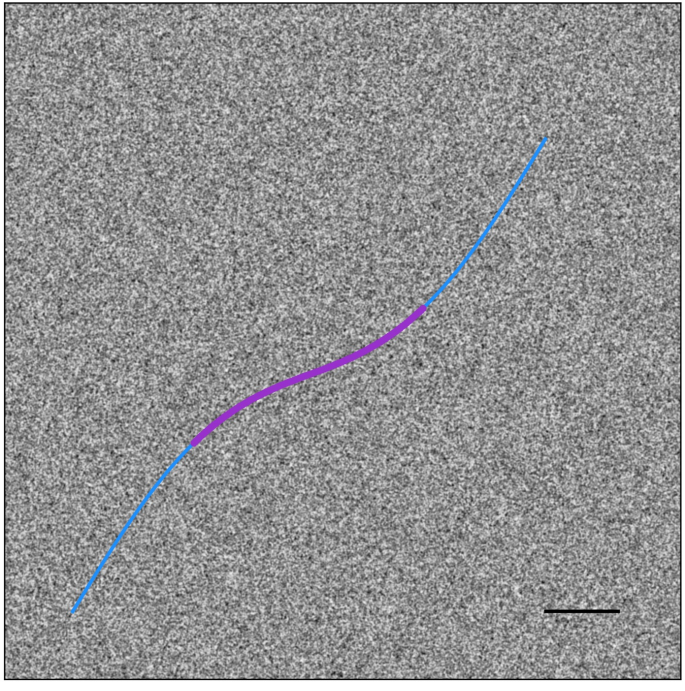
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 40.96; RMSD/dist: 0.102; TD: 19777; p90: 10; p50: 4; complete: 0

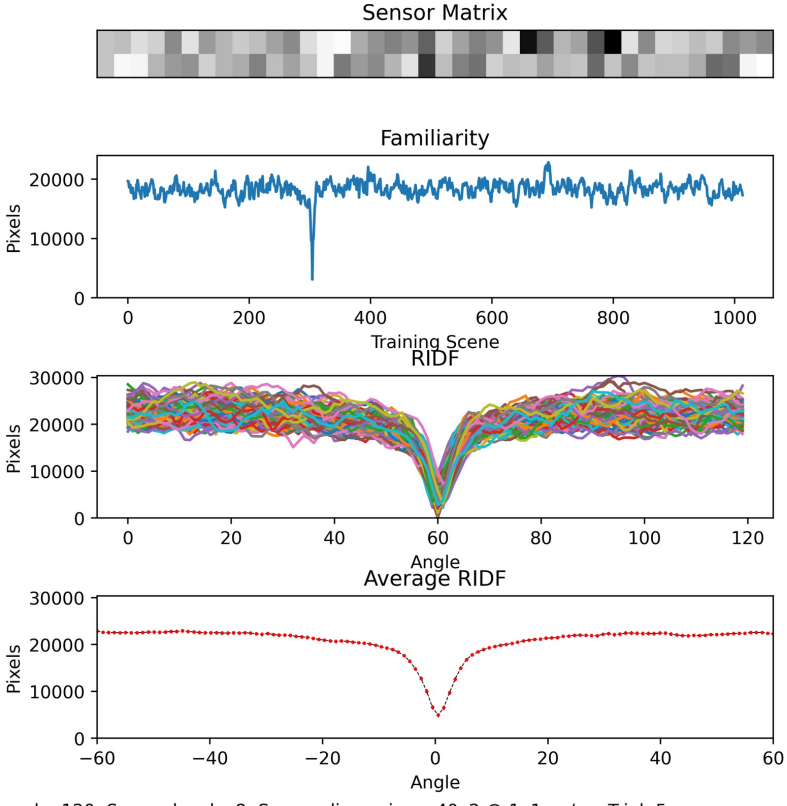

Index: BLUR: 1.0; LEVELS: 8; TRIAL: 5
SAD (pixels)
35000
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
Sensor regions





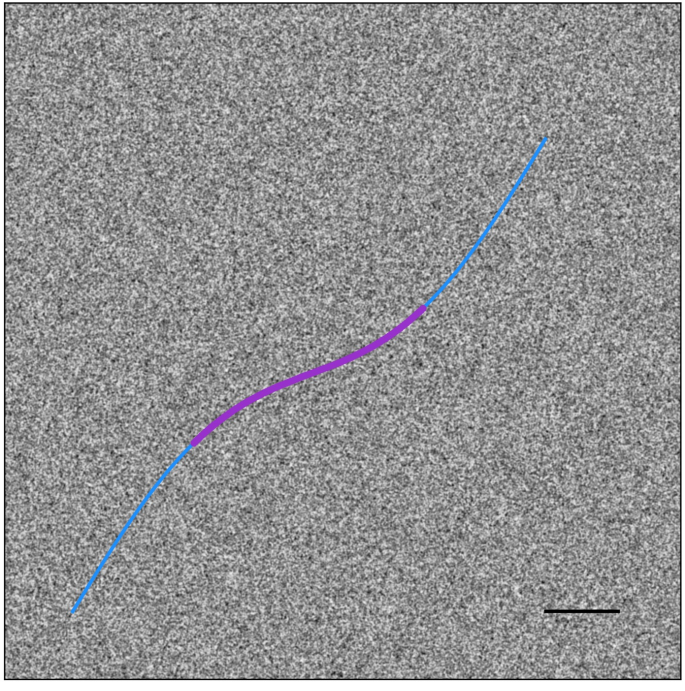
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 52.33; RMSD/dist: 0.131; TD: 10021; p90: 16; p50: 8; complete: 0

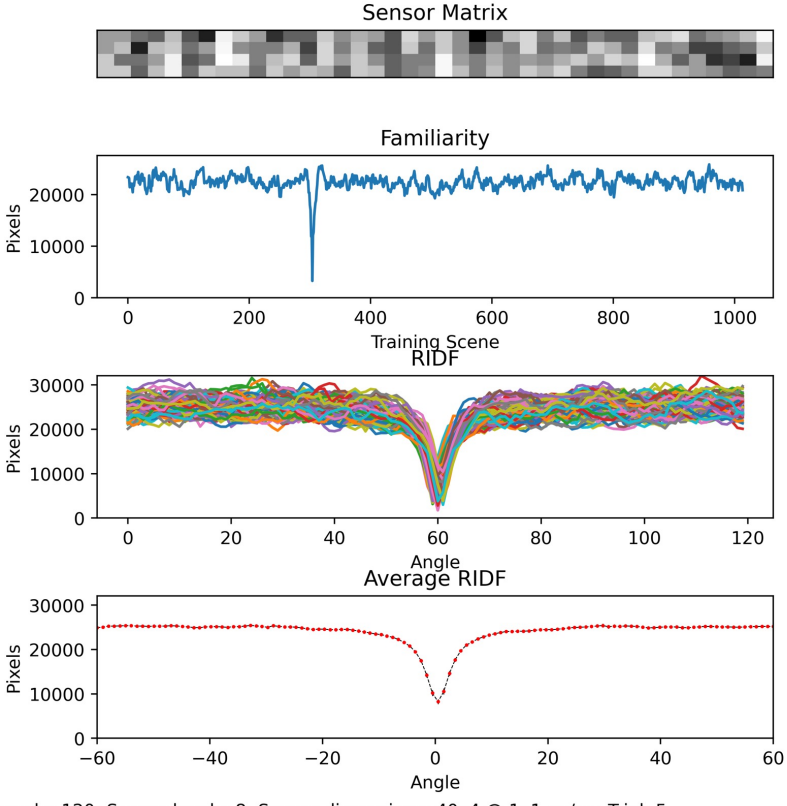




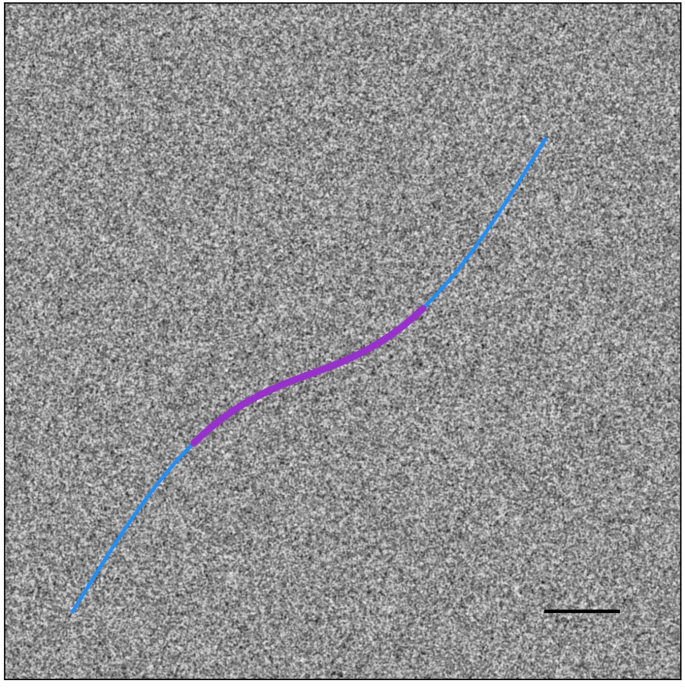
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

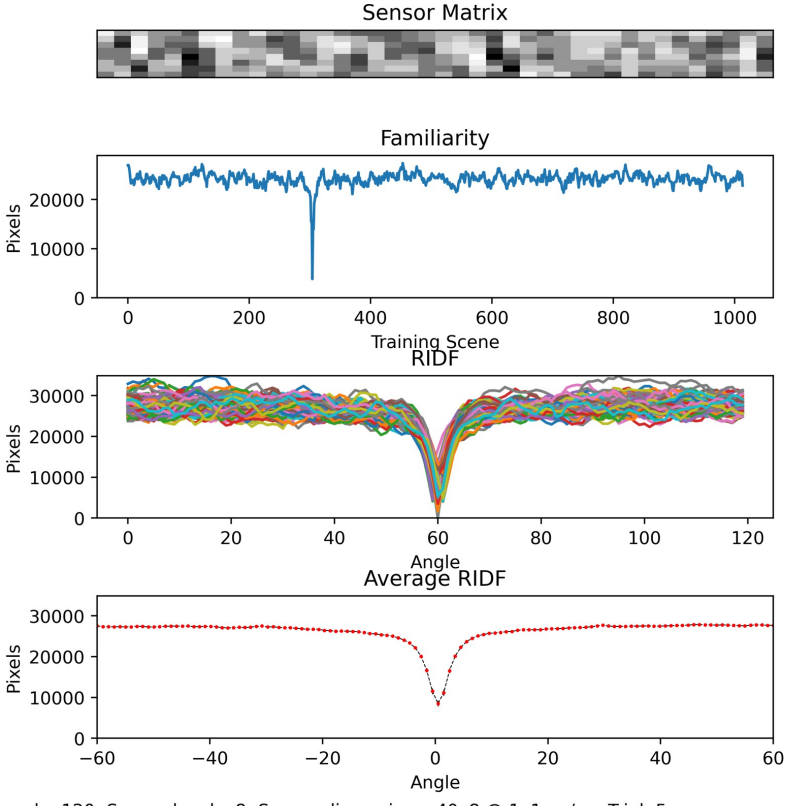
Navigation stats: RMSD error: 41.18; RMSD/dist: 0.103; TD: 13573; p90: 12; p50: 6; complete: 0



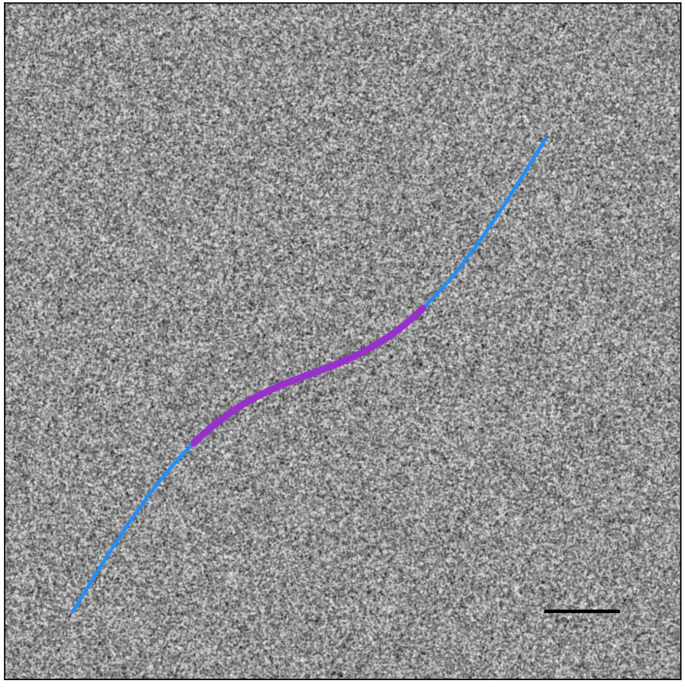


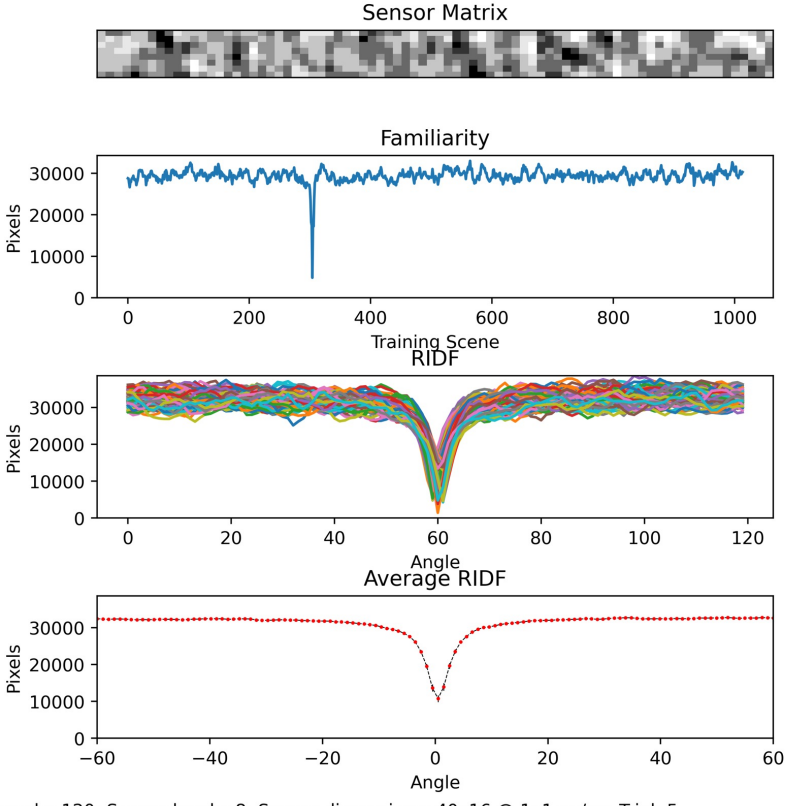
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 64.29; RMSD/dist: 0.161; TD: 13956; p90: 10; p50: 4; complete: 0



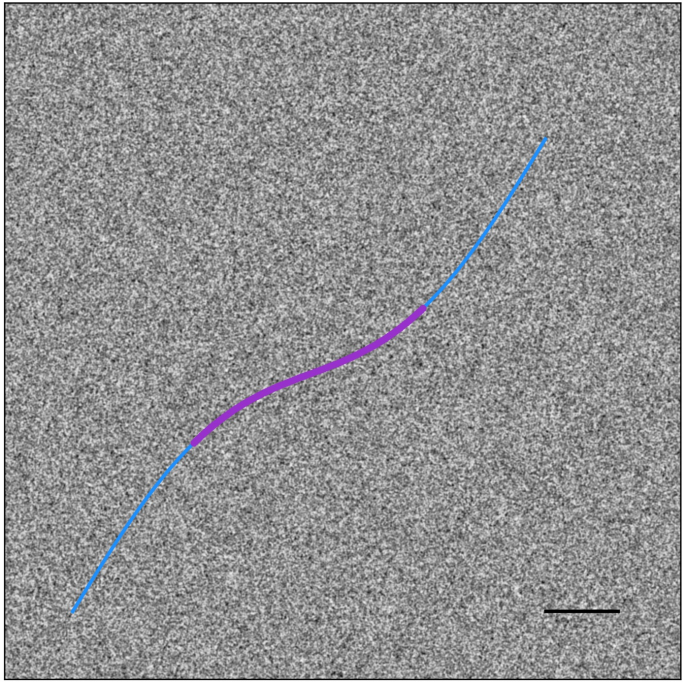


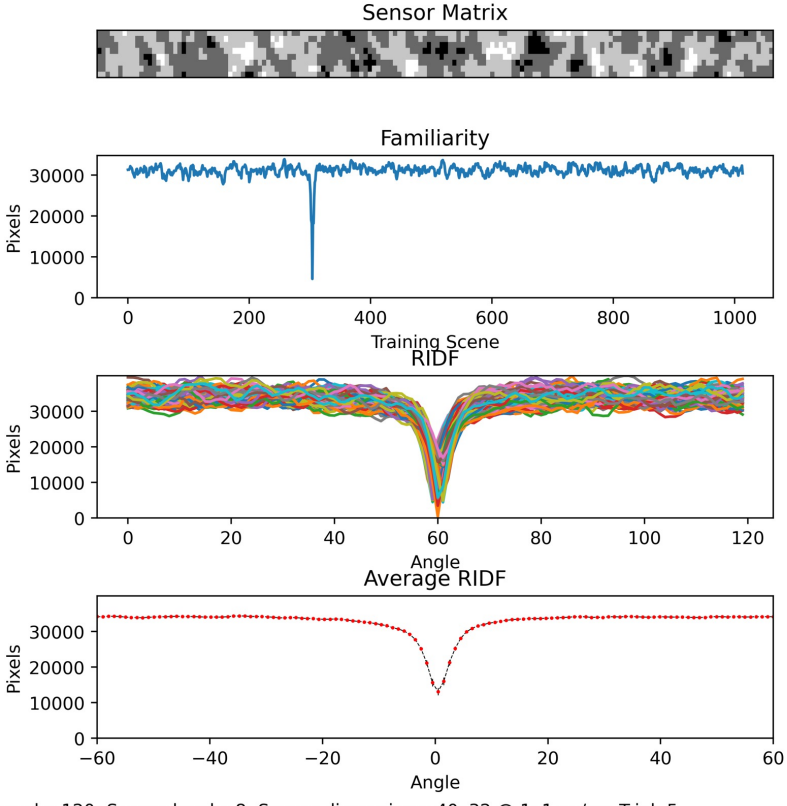
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 44.96; RMSD/dist: 0.112; TD: 15741; p90: 8; p50: 4; complete: 0



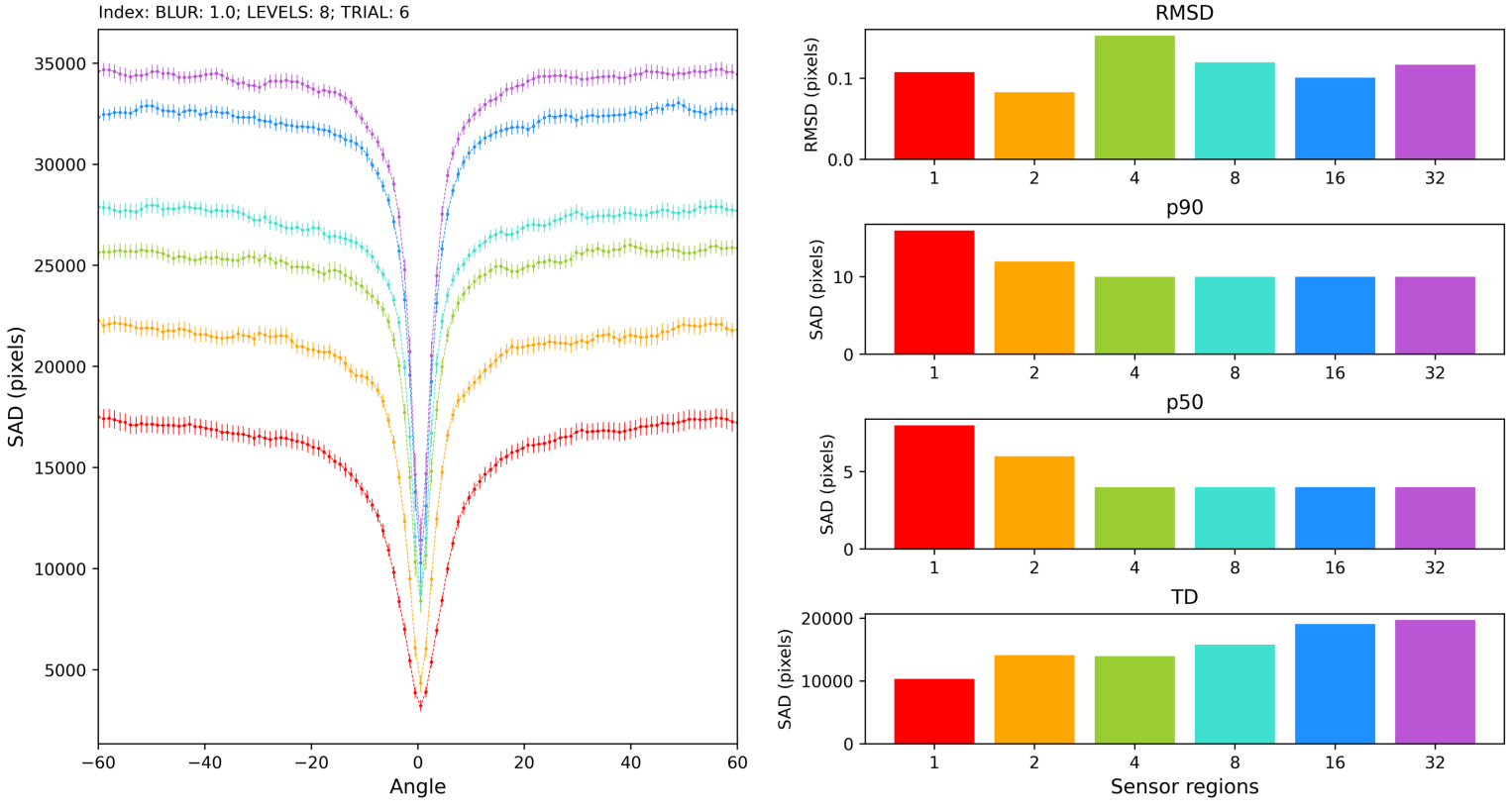


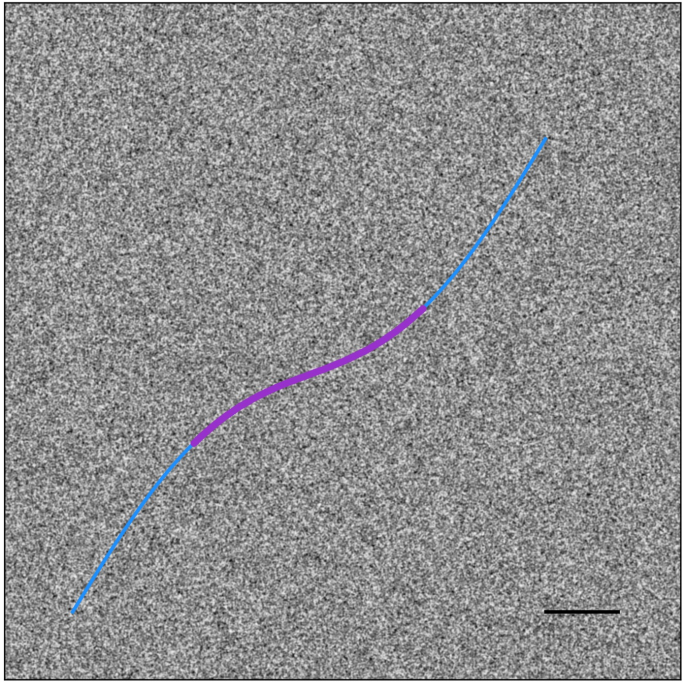
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 45.94; RMSD/dist: 0.115; TD: 18504; p90: 10; p50: 4; complete: 0

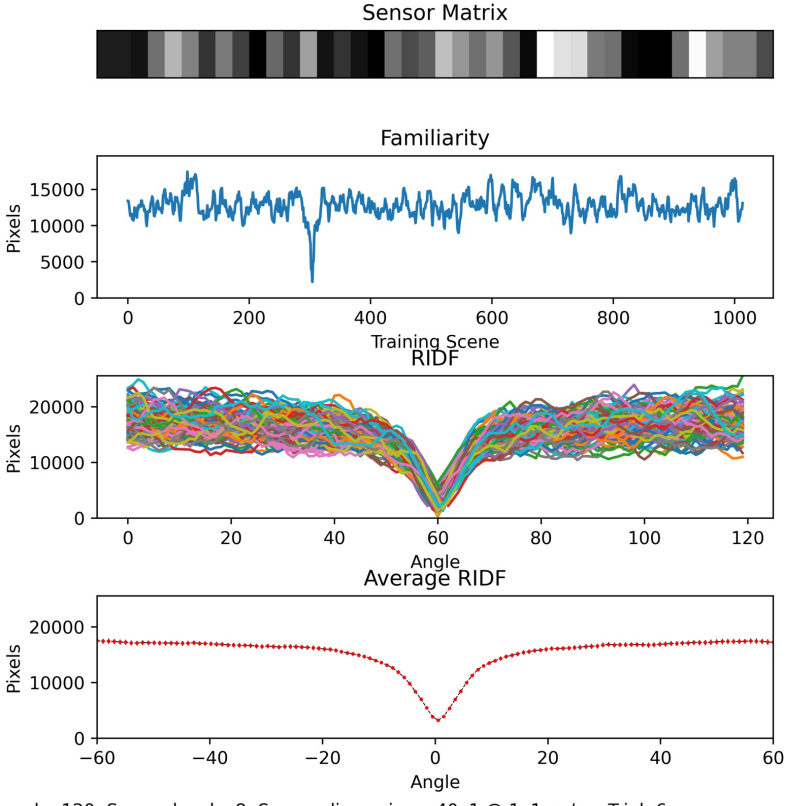




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 57.35; RMSD/dist: 0.143; TD: 17792; p90: 10; p50: 4; complete: 0

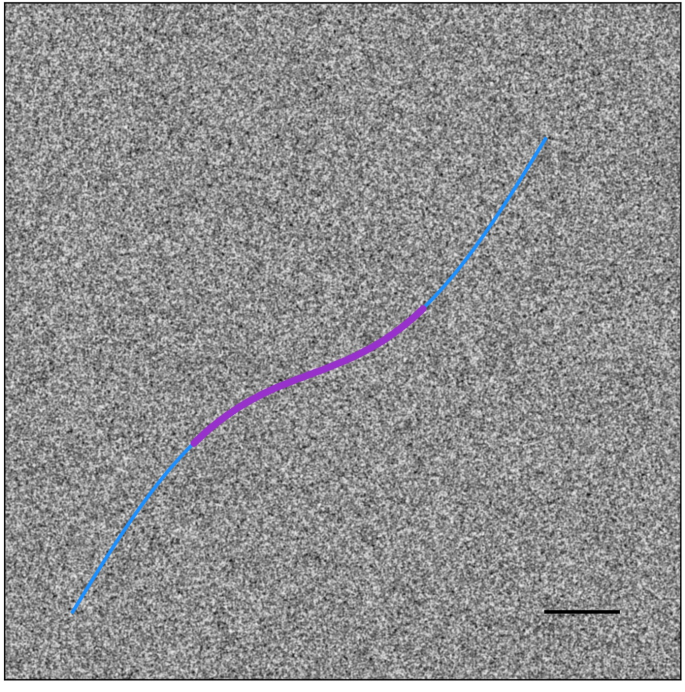

Index: BLUR: 1.0; LEVELS: 8; TRIAL: 6
SAD (pixels)
35000
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
20000
10000
0
Sensor regions

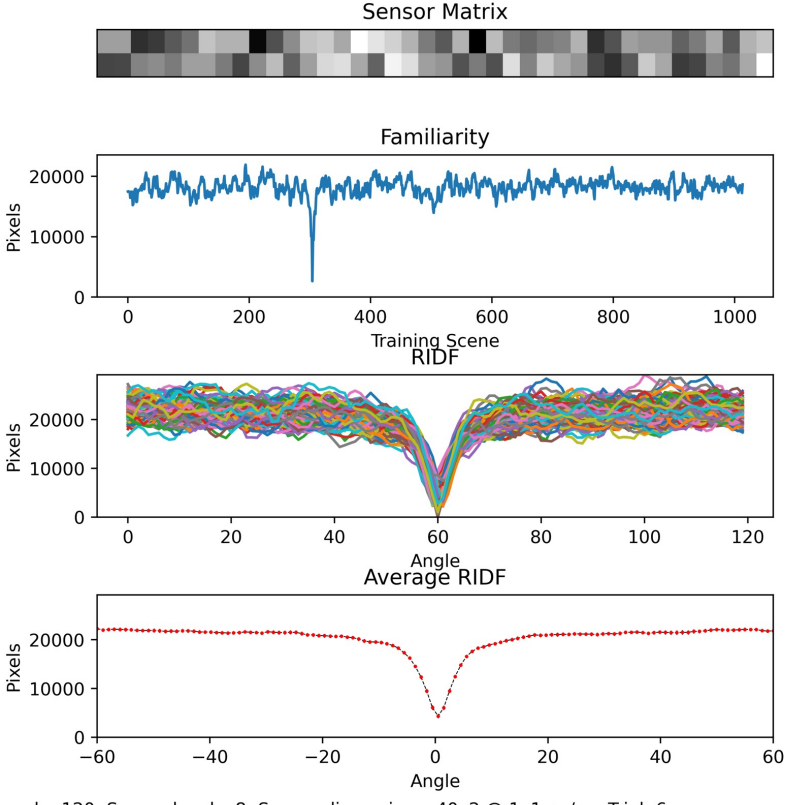




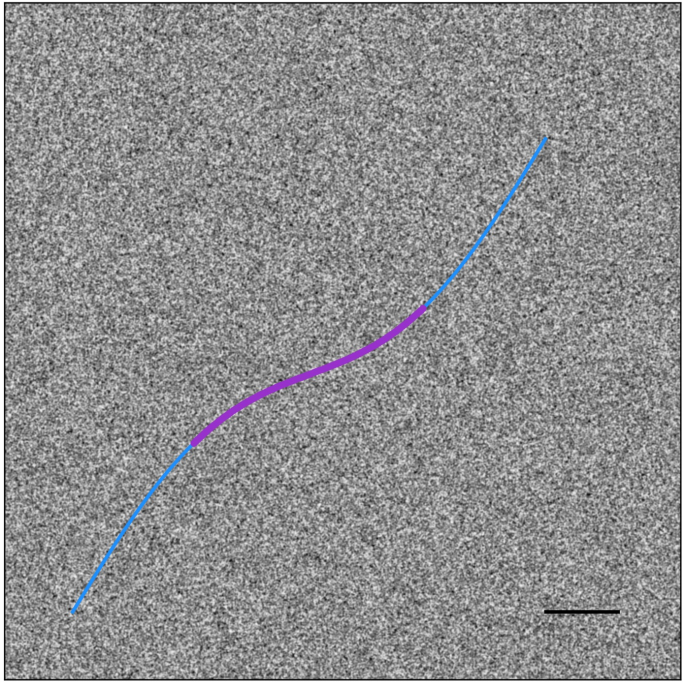
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

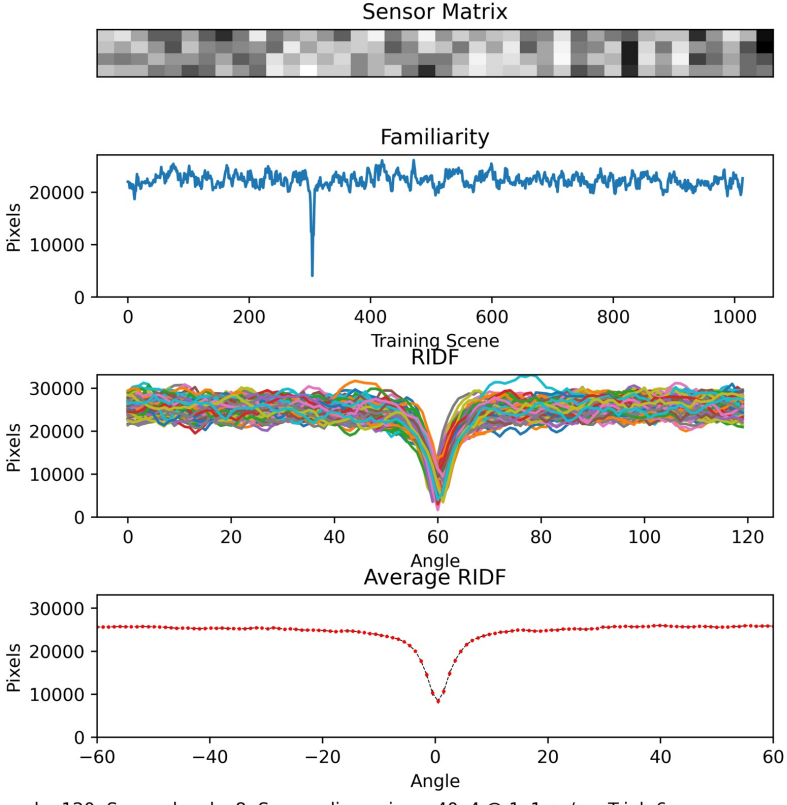
Navigation stats: RMSD error: 43.38; RMSD/dist: 0.108; TD: 10323; p90: 16; p50: 8; complete: 0



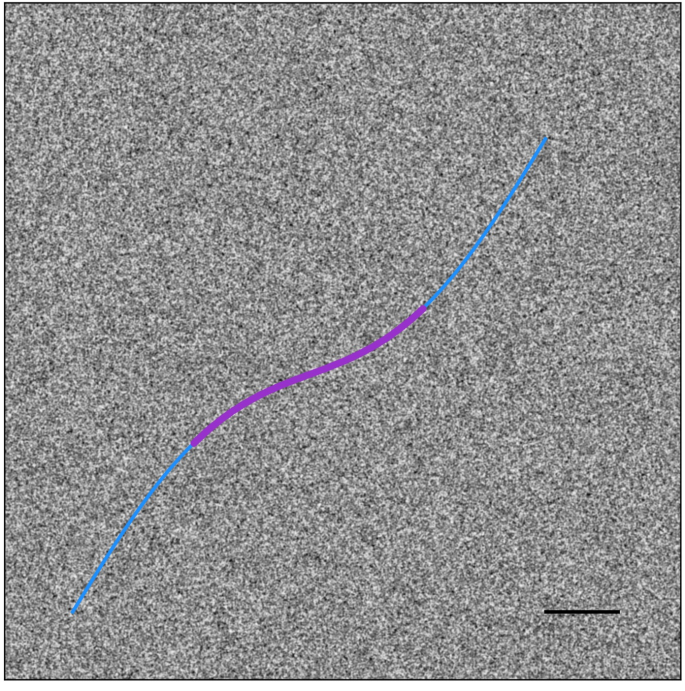


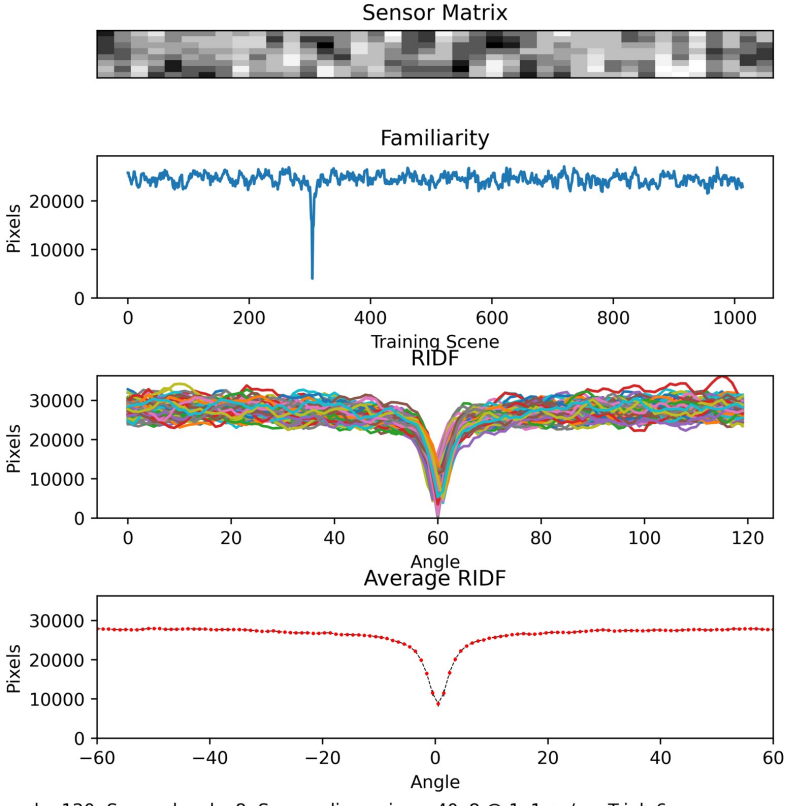
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 33.21; RMSD/dist: 0.083; TD: 14103; p90: 12; p50: 6; complete: 0



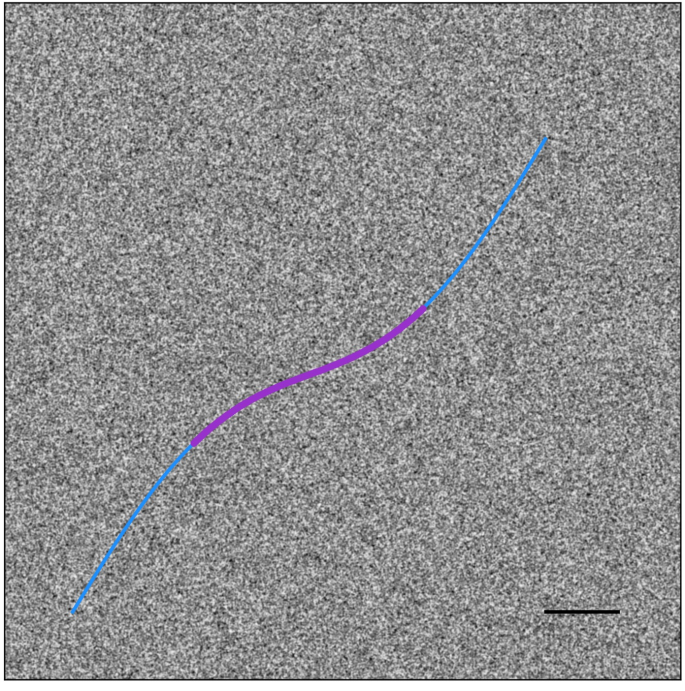


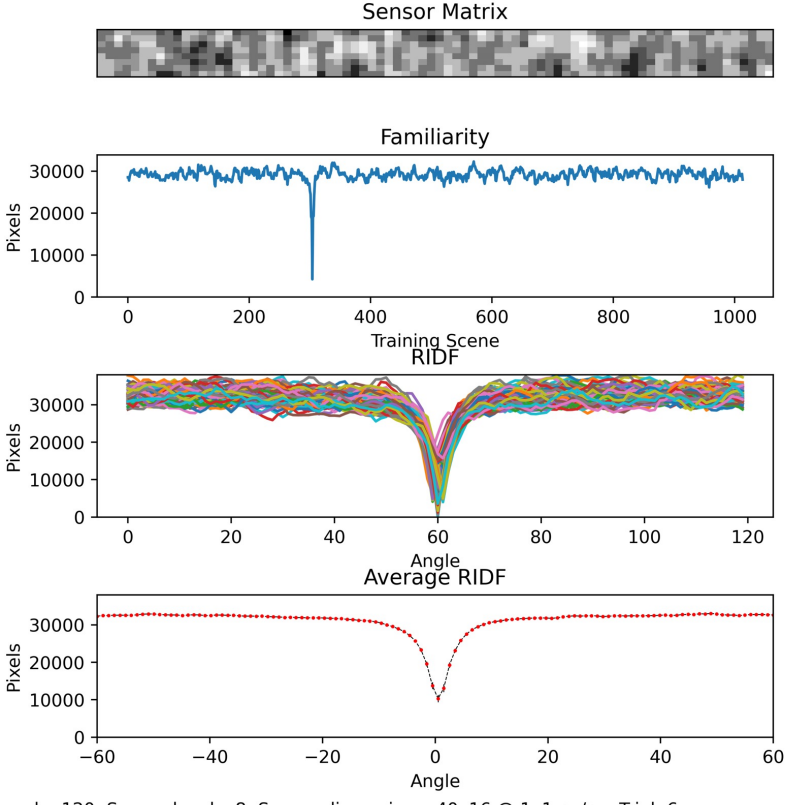
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 61.38; RMSD/dist: 0.153; TD: 13964; p90: 10; p50: 4; complete: 0



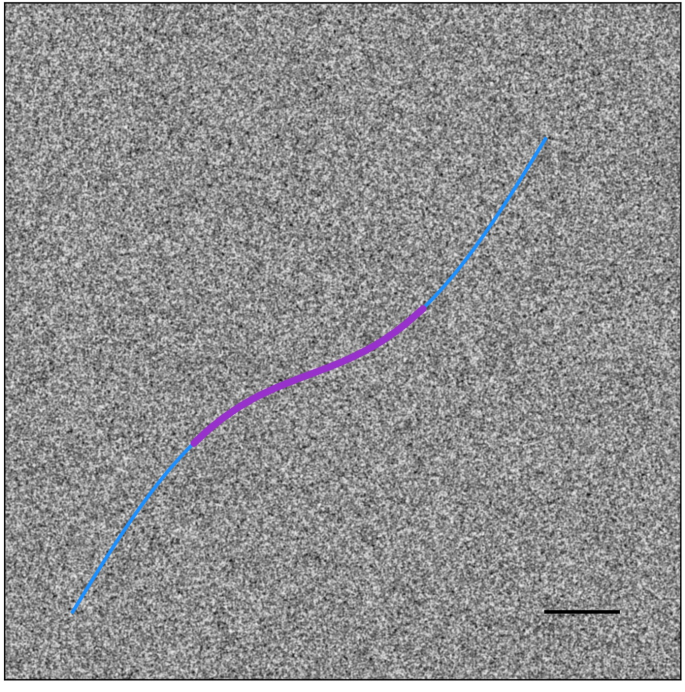


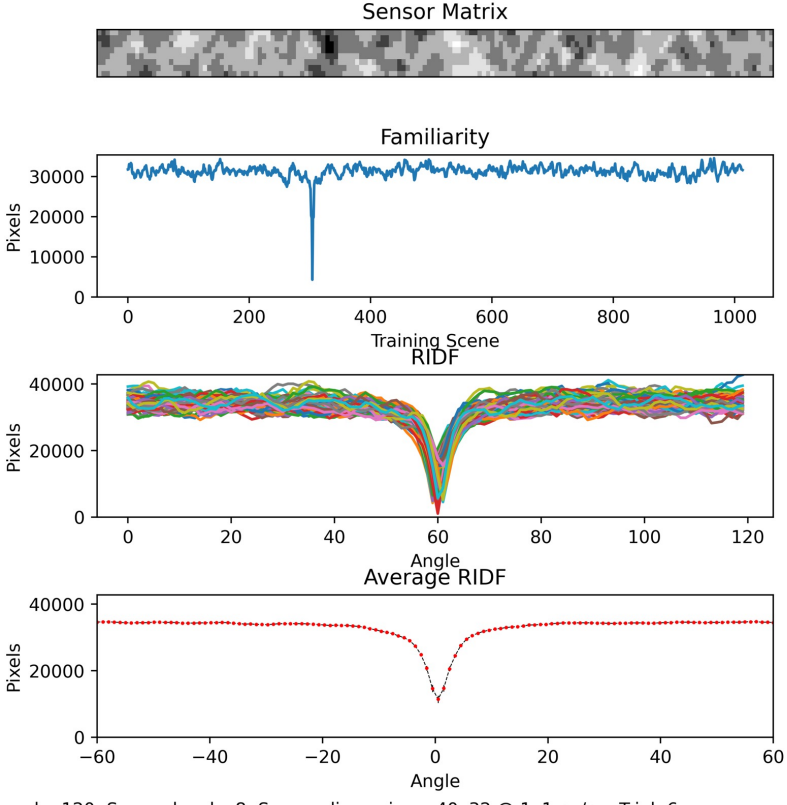
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 48.16; RMSD/dist: 0.120; TD: 15777; p90: 10; p50: 4; complete: 0





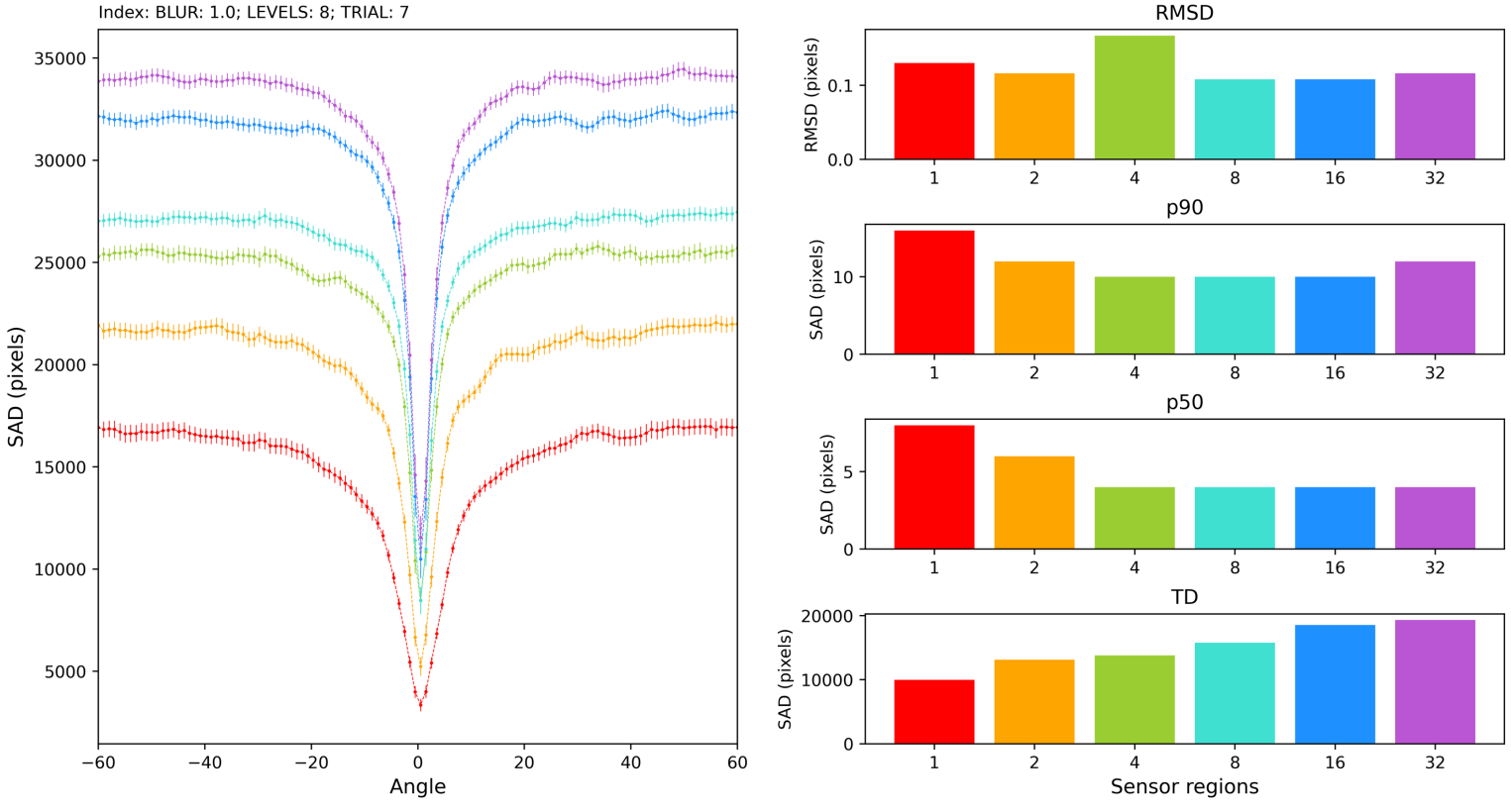
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 40.29; RMSD/dist: 0.101; TD: 19067; p90: 10; p50: 4; complete: 0

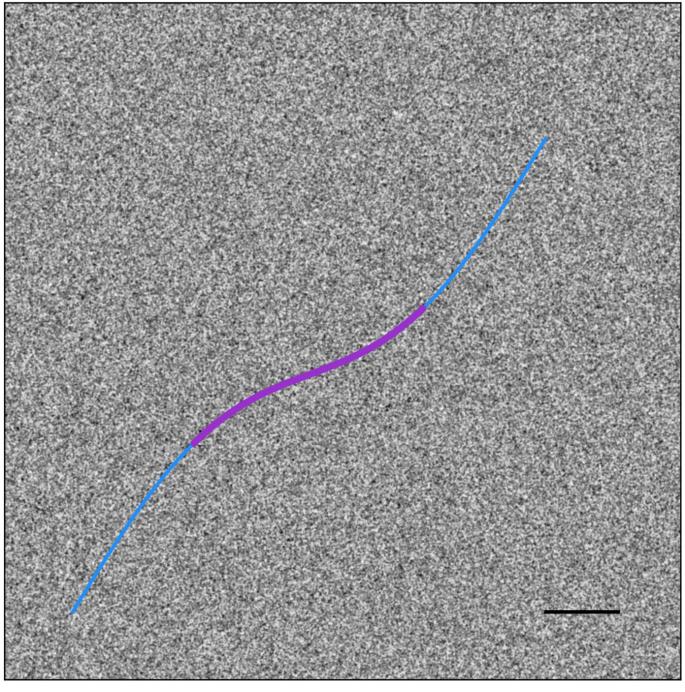


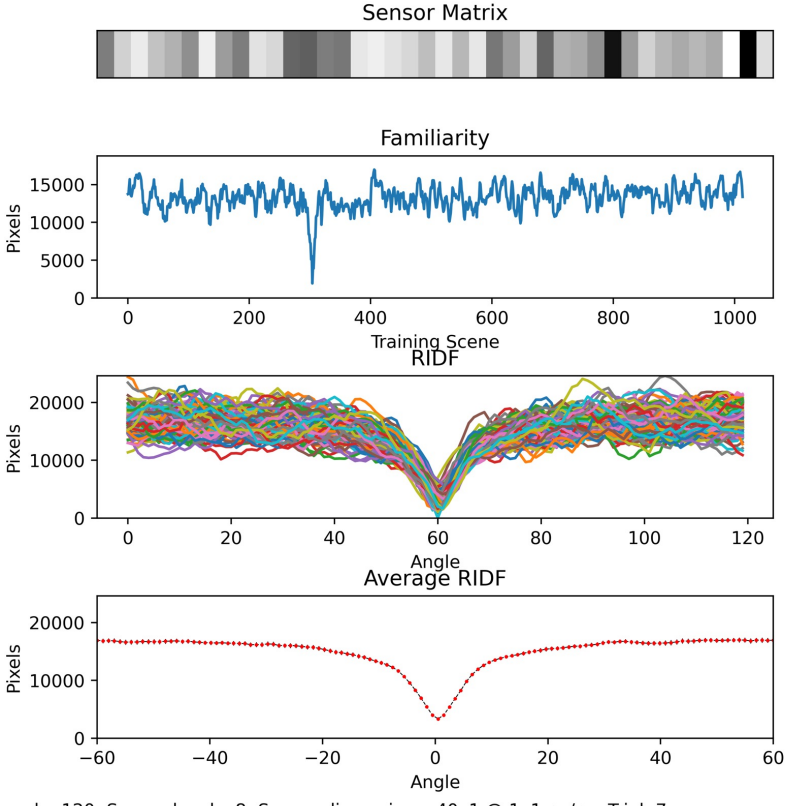


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

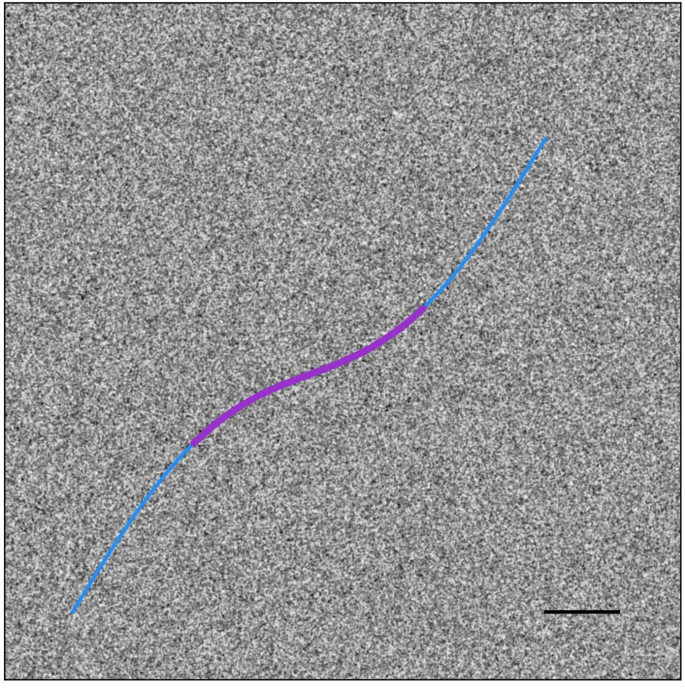
Navigation stats: RMSD error: 46.63; RMSD/dist: 0.117; TD: 19700; p90: 10; p50: 4; complete: 0

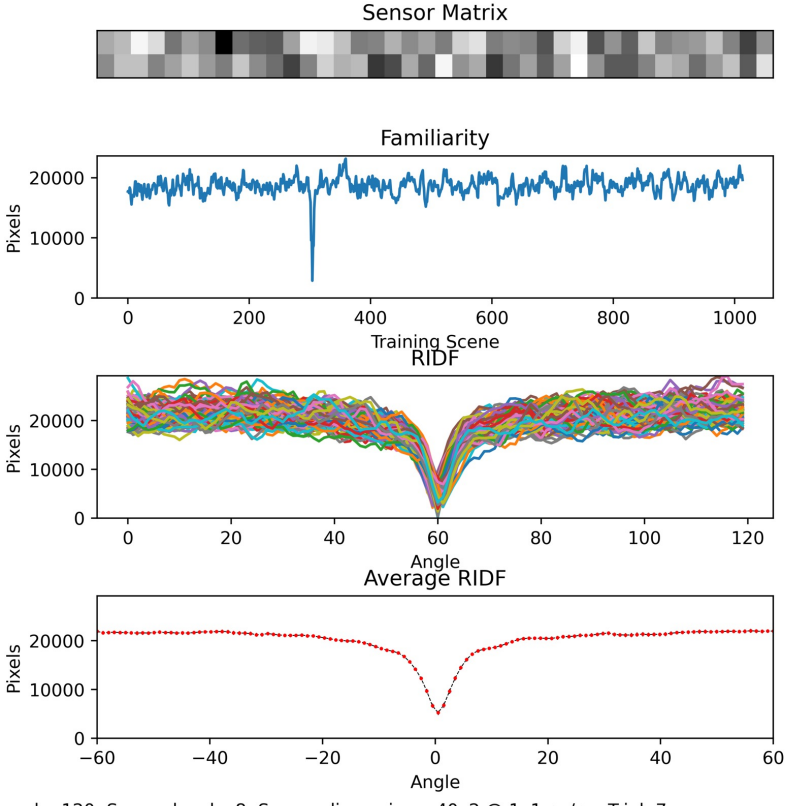

Index: BLUR: 1.0; LEVELS: 8; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions



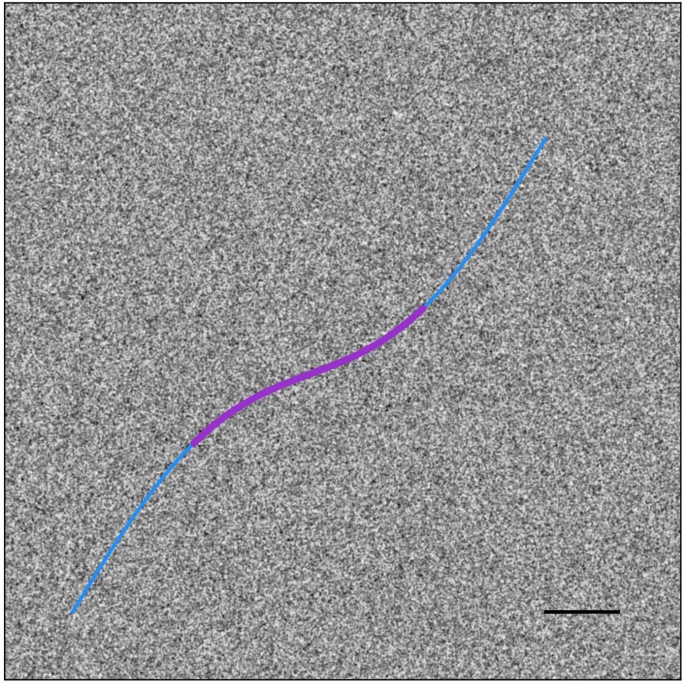


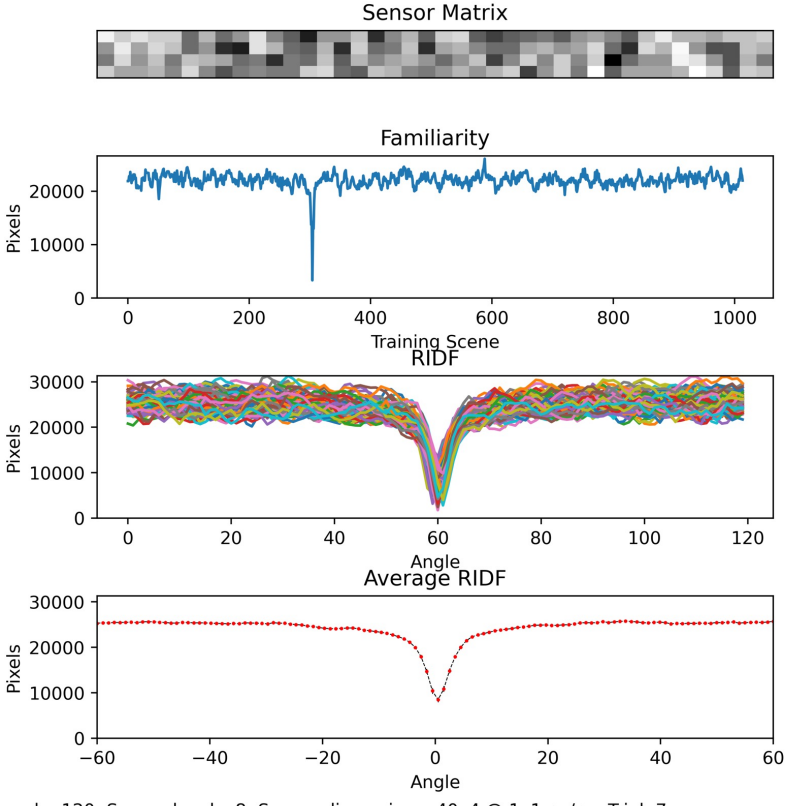
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 52.19; RMSD/dist: 0.130; TD: 9989; p90: 16; p50: 8; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 46.30; RMSD/dist: 0.116; TD: 13113; p90: 12; p50: 6; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7
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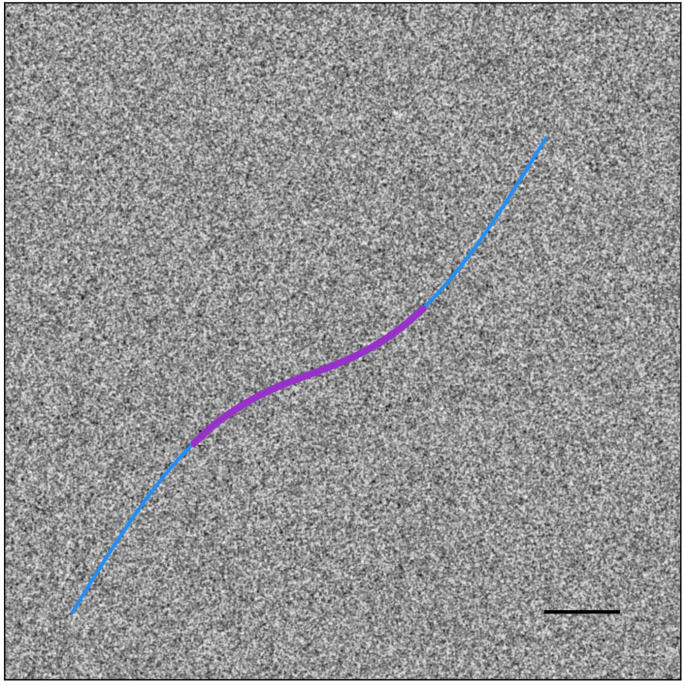
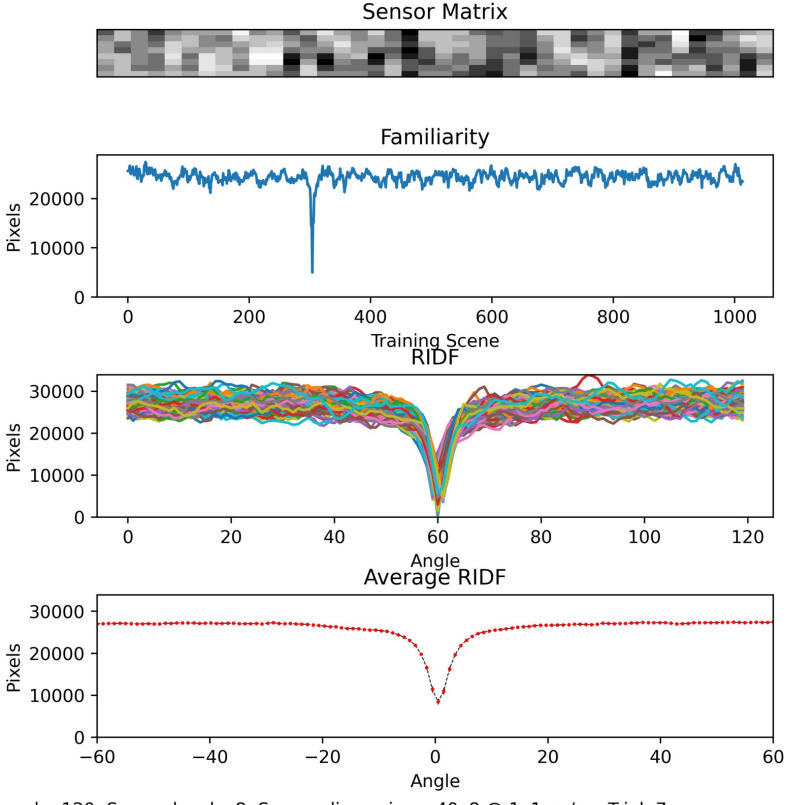
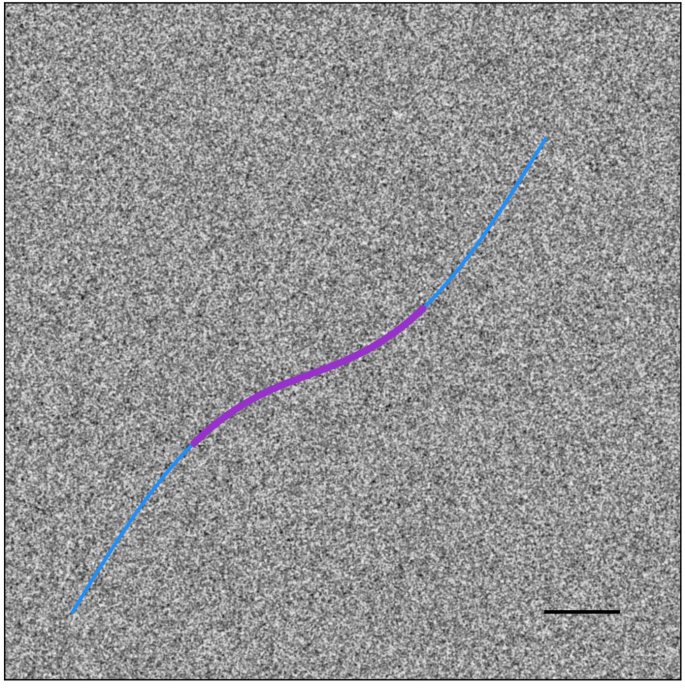
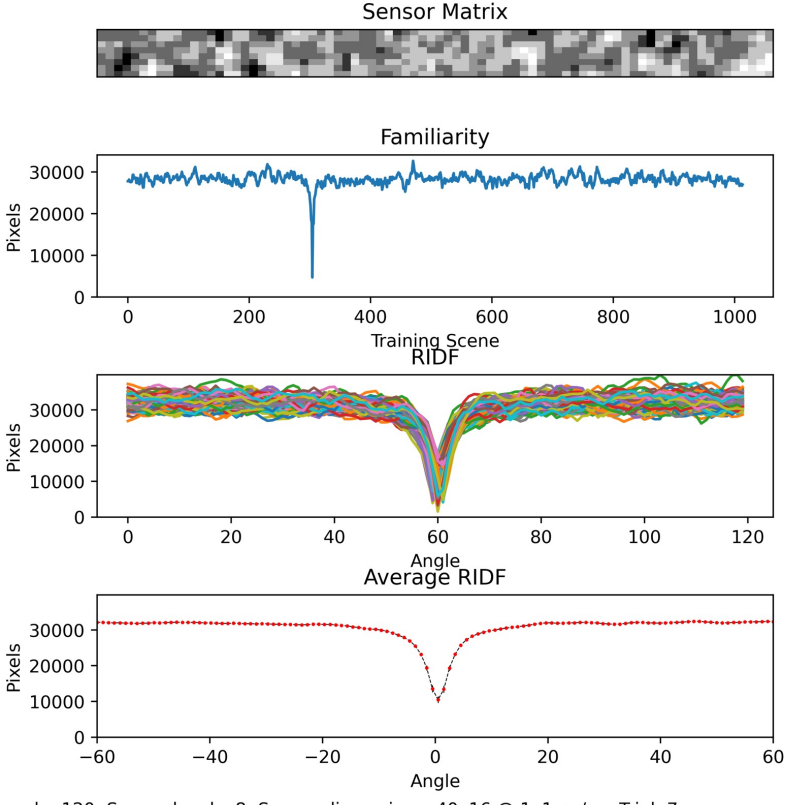




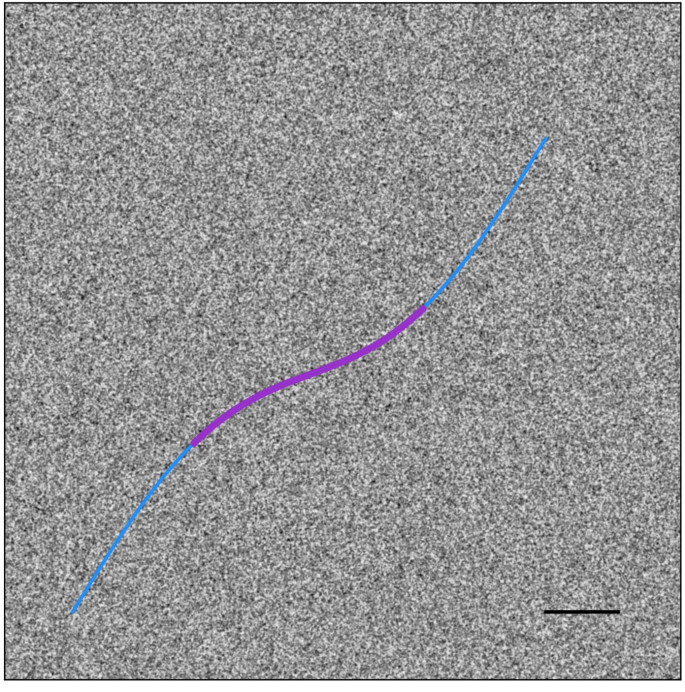
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 43.12; RMSD/dist: 0.108; TD: 15779; p90: 10; p50: 4; complete: 0

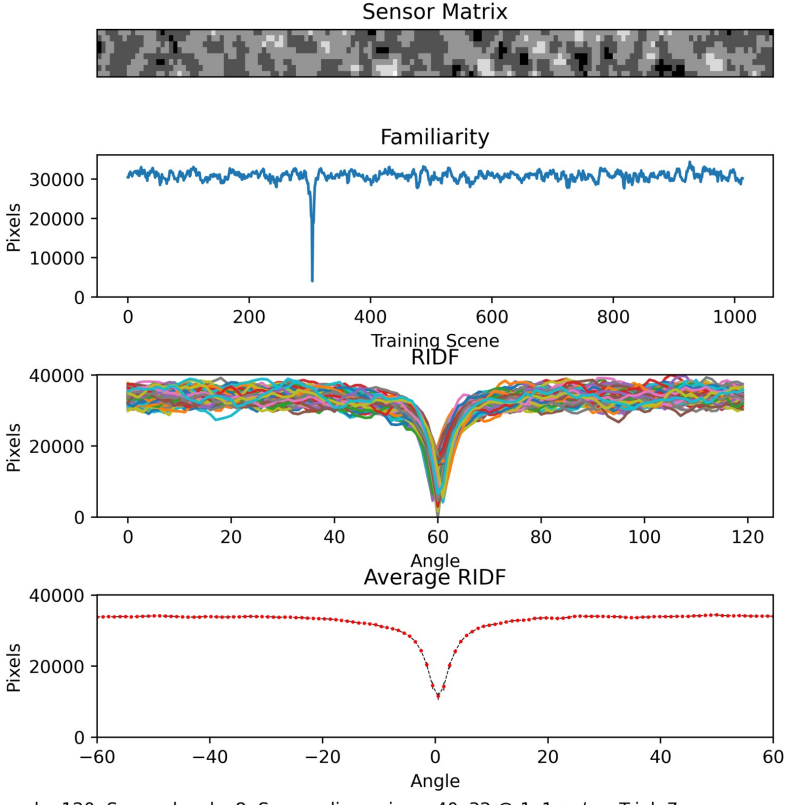




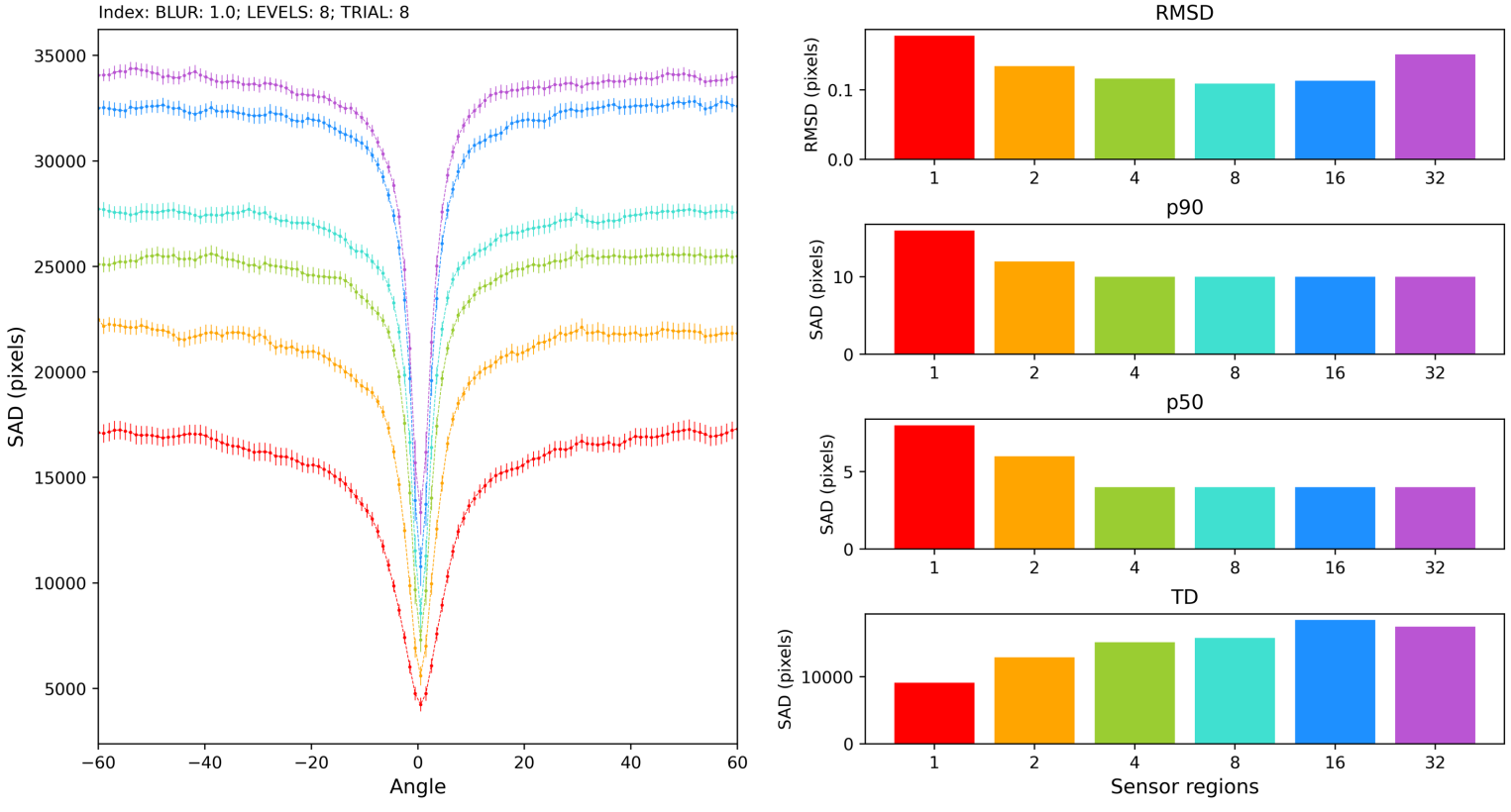
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 43.33; RMSD/dist: 0.108; TD: 18528; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 46.23; RMSD/dist: 0.116; TD: 19303; p90: 12; p50: 4; complete: 0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SAD (pixels)
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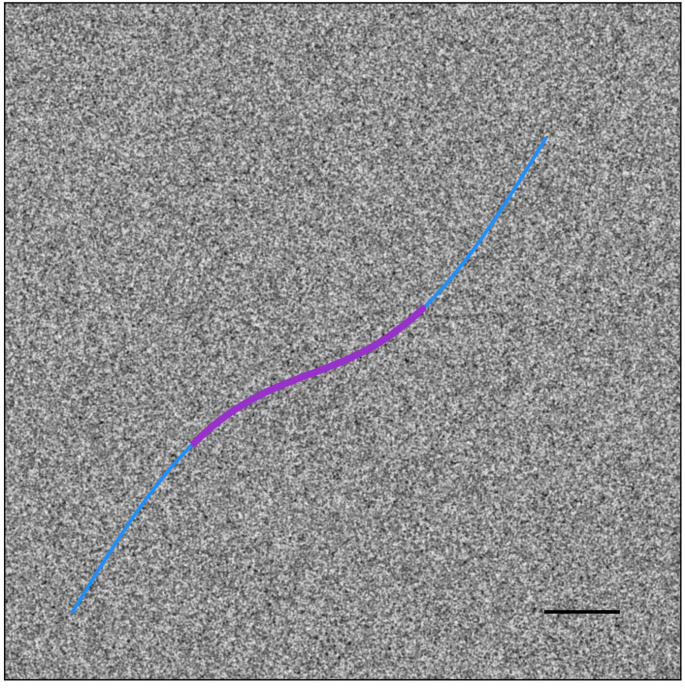
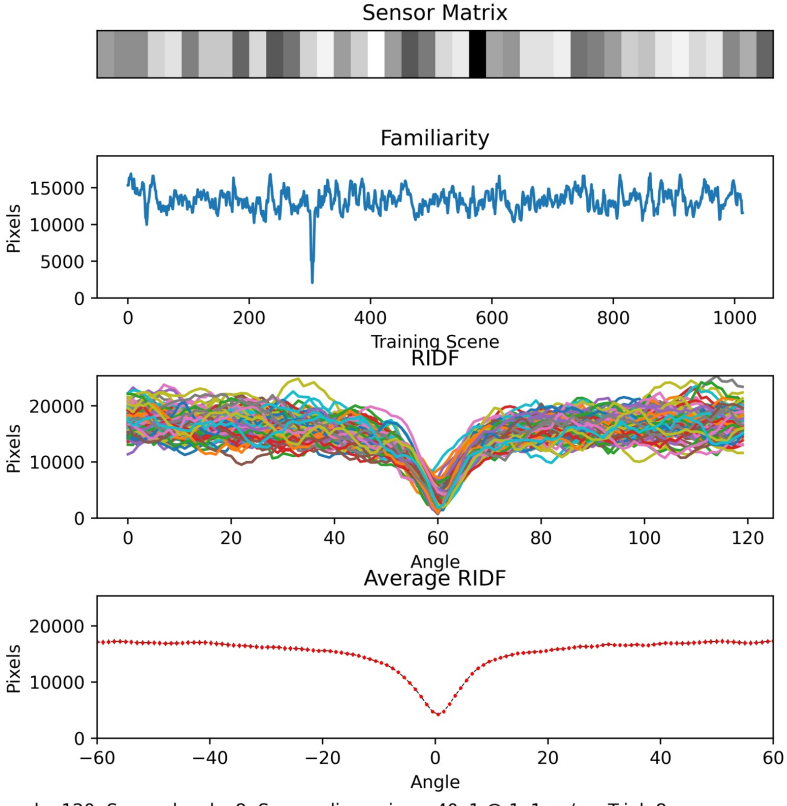
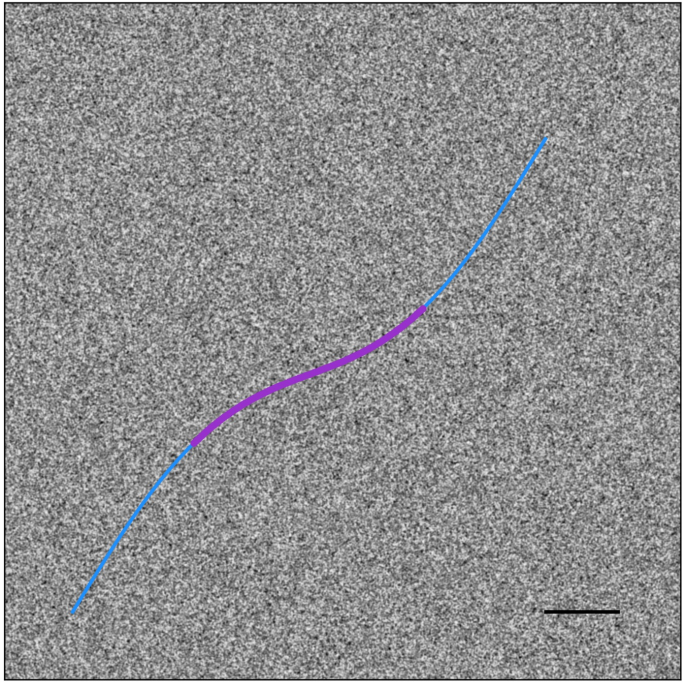
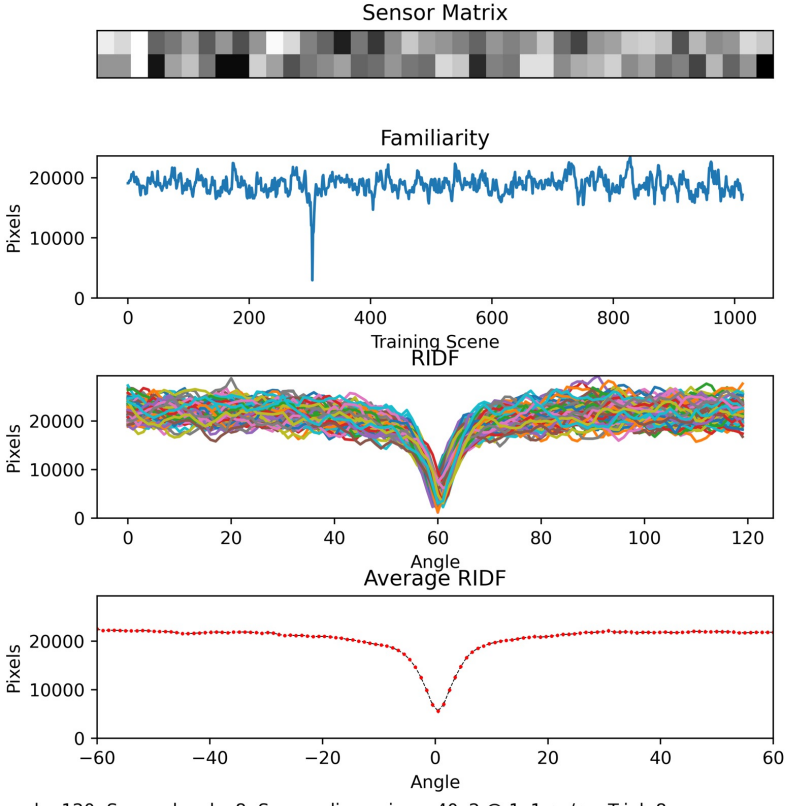
30000
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
Sensor regions





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 71.33; RMSD/dist: 0.178; TD: 9110; p90: 16; p50: 8; complete: 0





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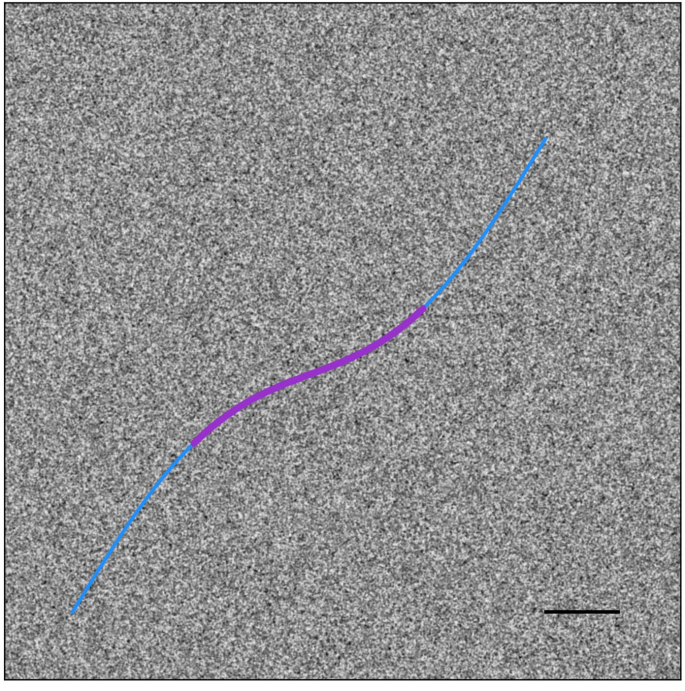

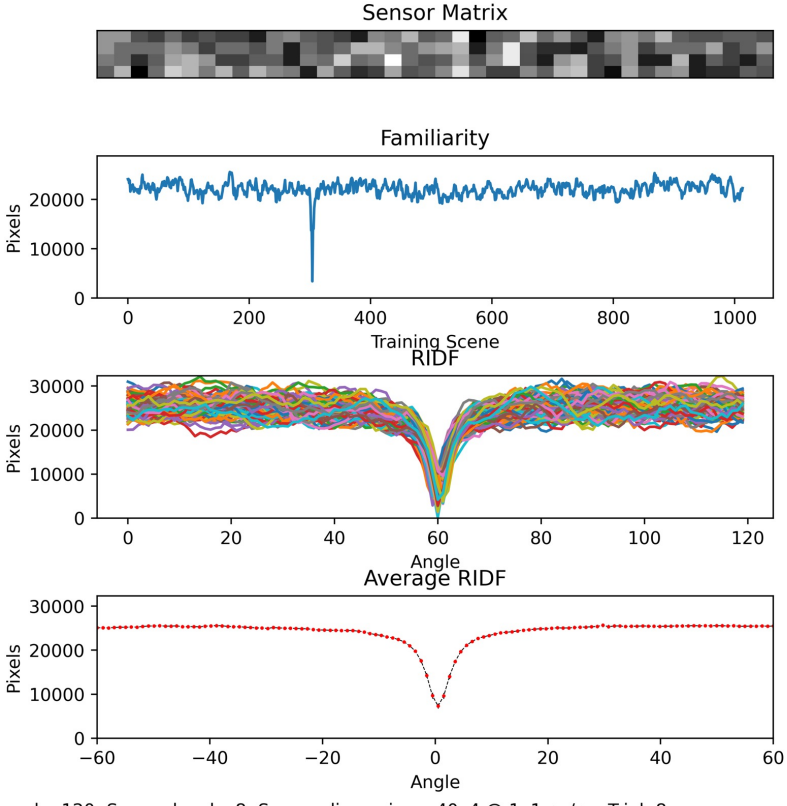

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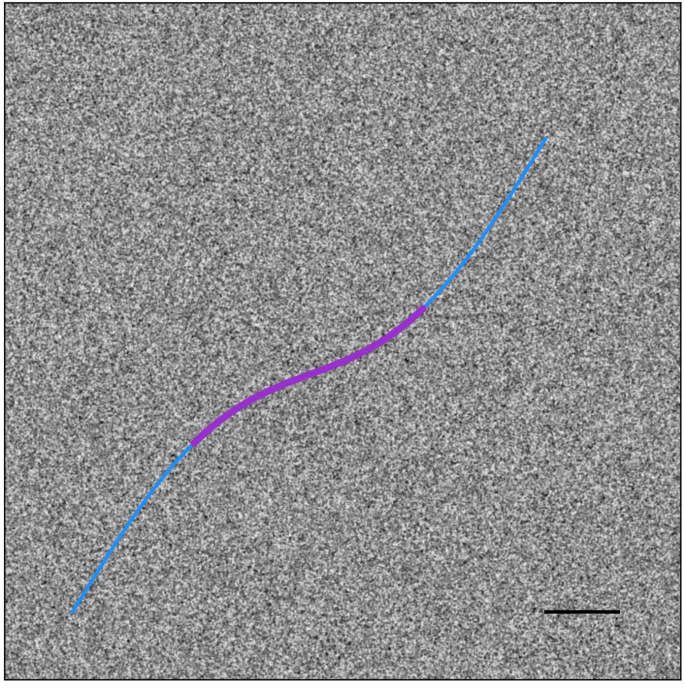
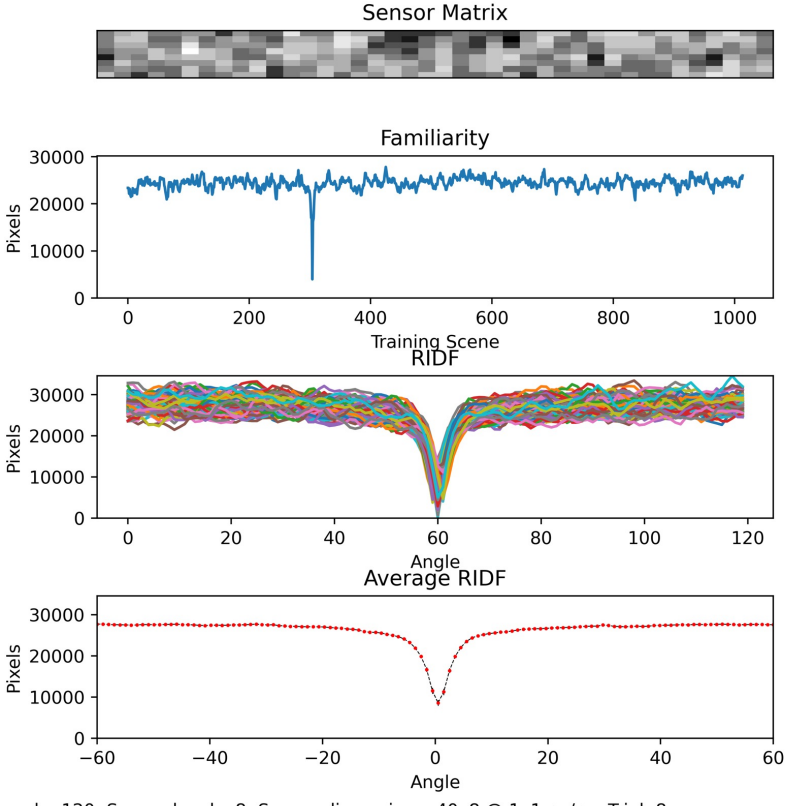
Navigation stats: RMSD error: 46.40; RMSD/dist: 0.116; TD: 15147; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8
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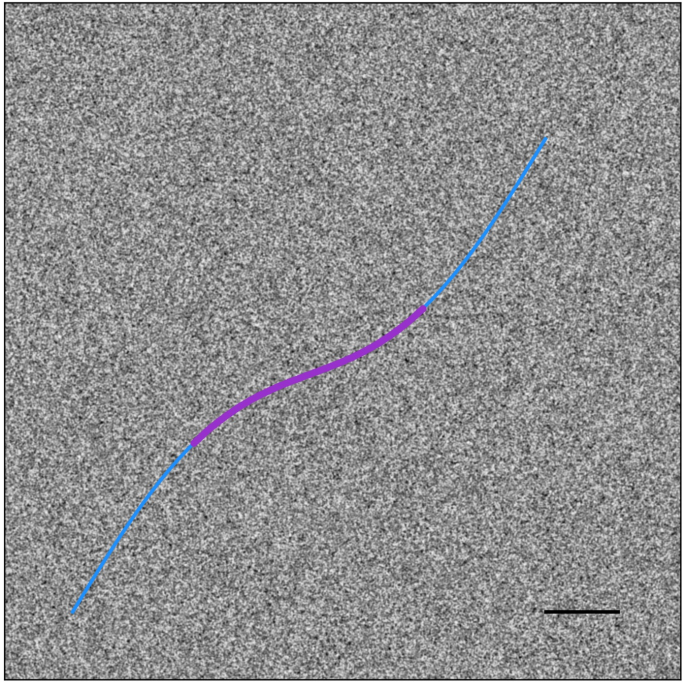

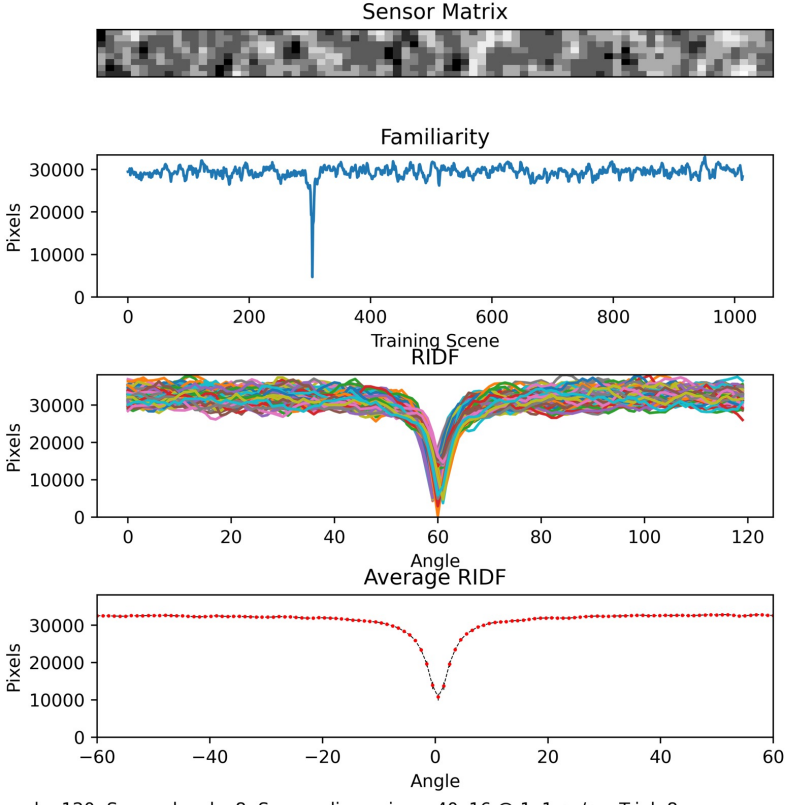

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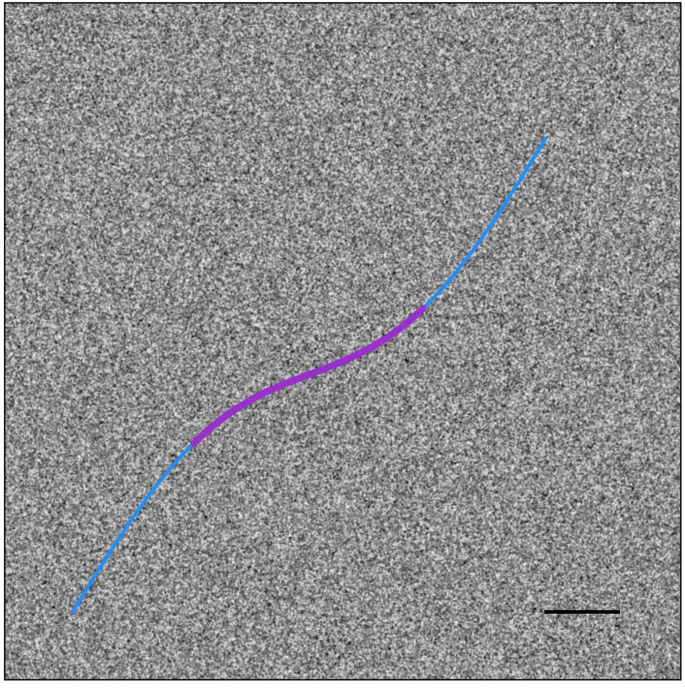
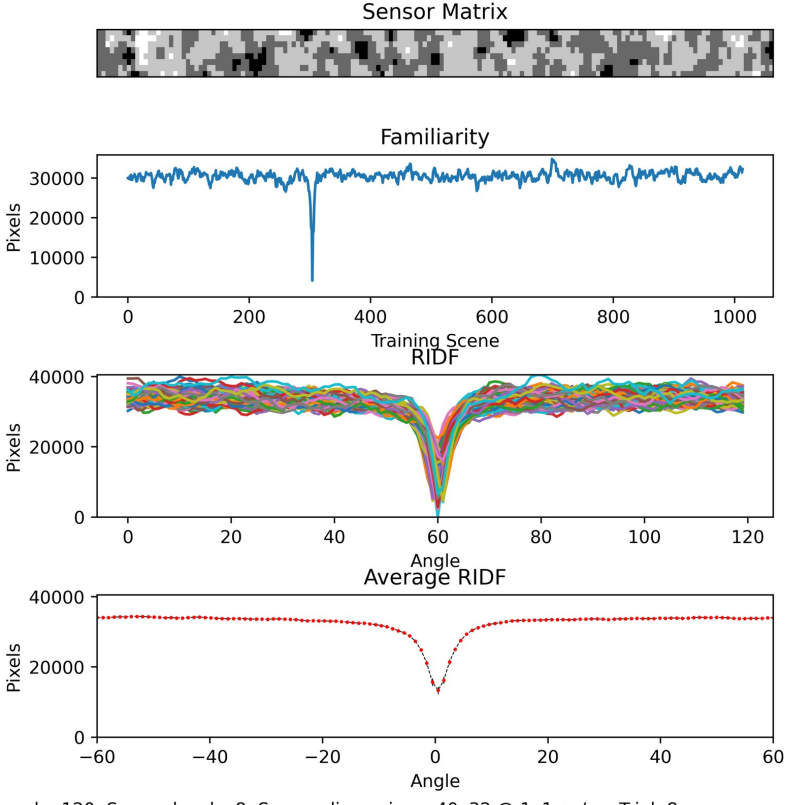
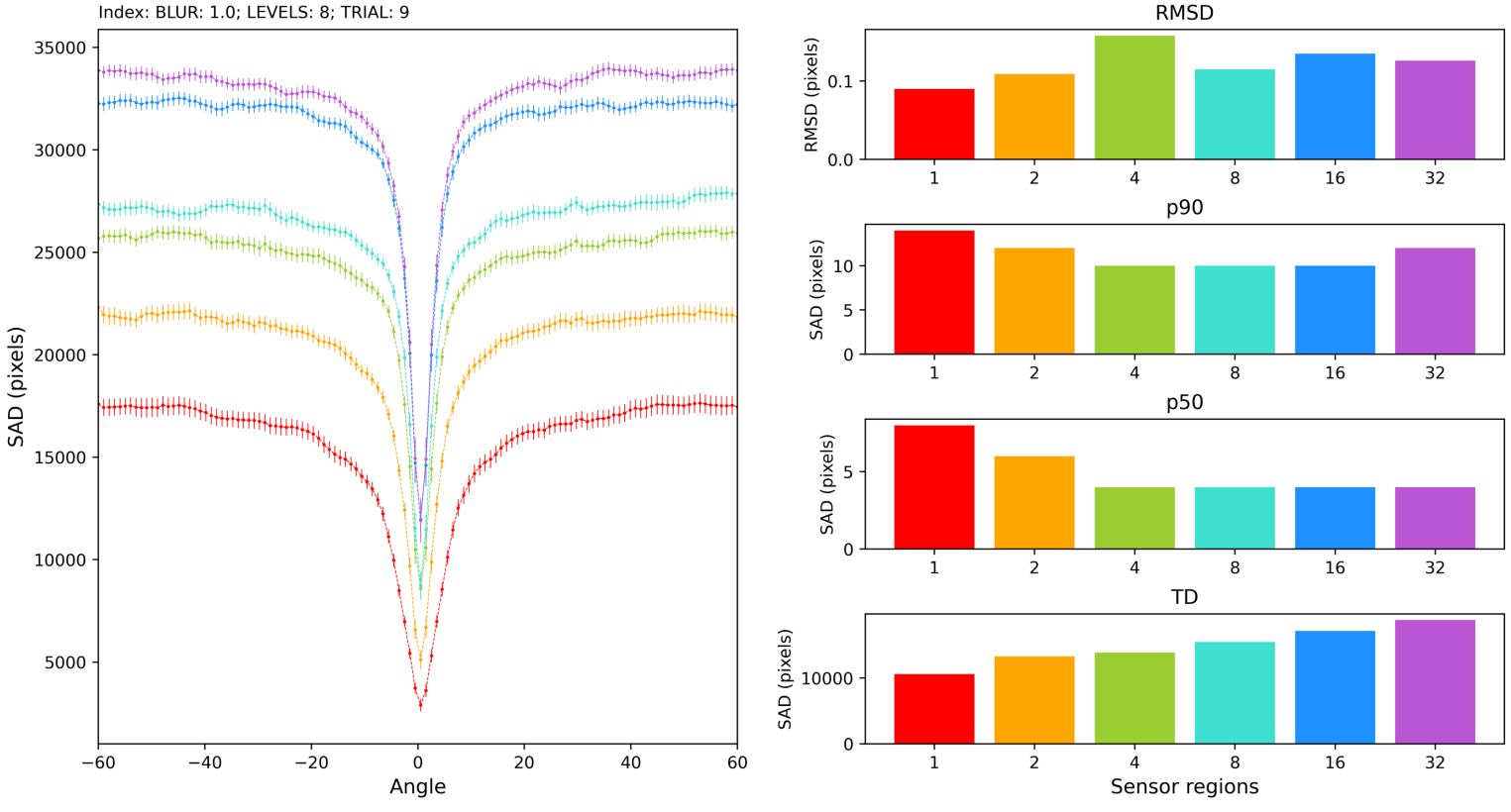
Navigation stats: RMSD error: 45.33; RMSD/dist: 0.113; TD: 18472; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 60.30; RMSD/dist: 0.151; TD: 17500; p90: 10; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 8; TRIAL: 9
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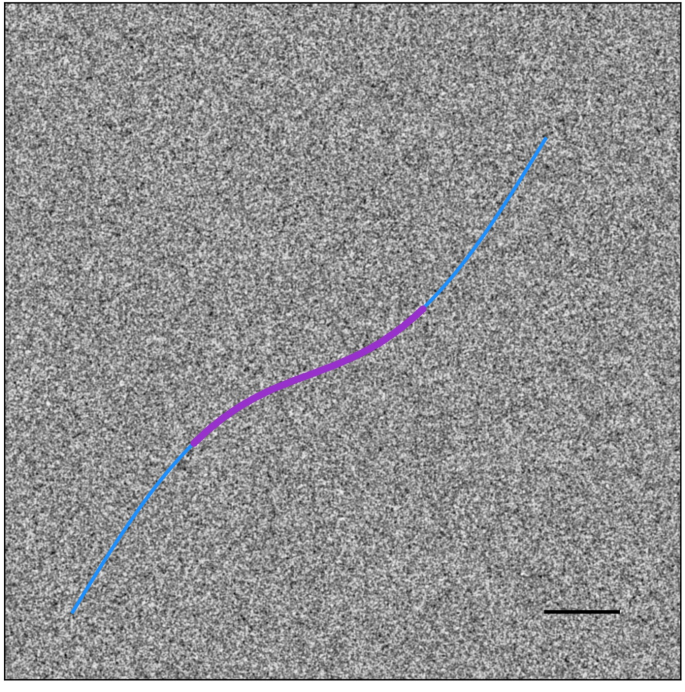
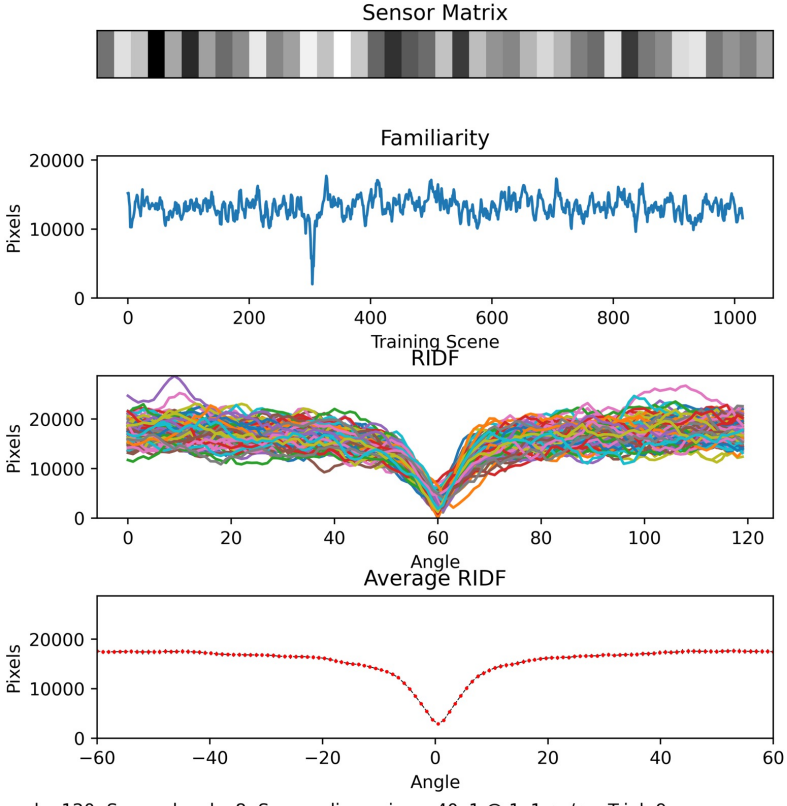
25000
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.1
0.0
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
0
1
2
4
8
16
32
Sensor regions





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9
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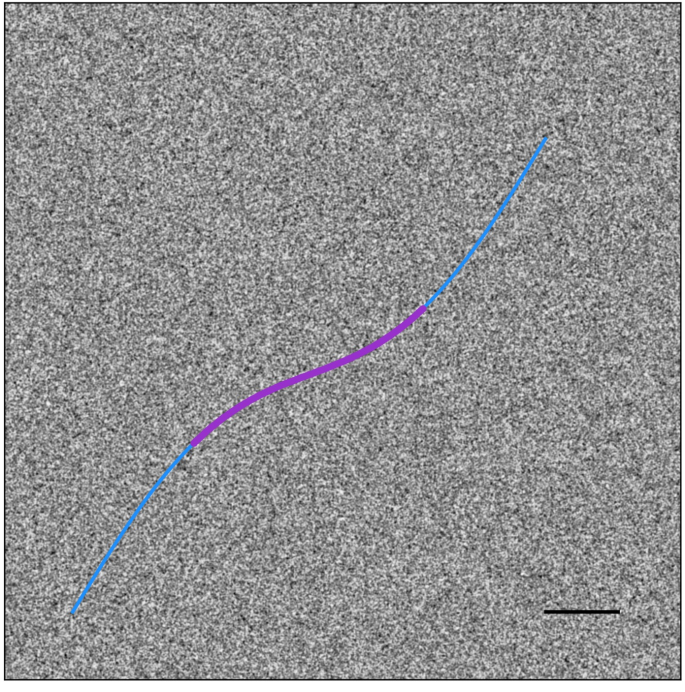

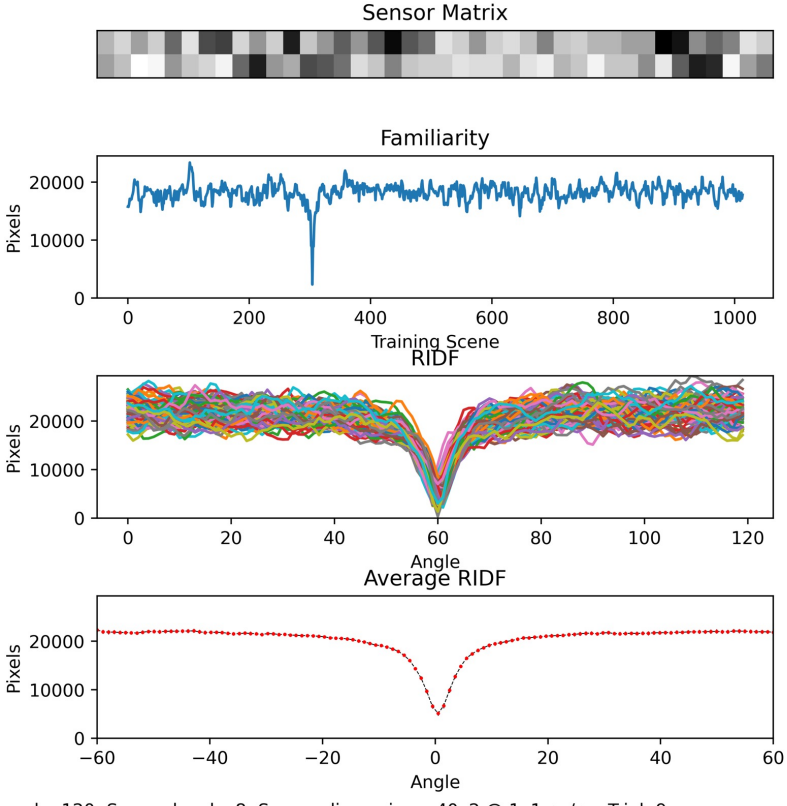

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9
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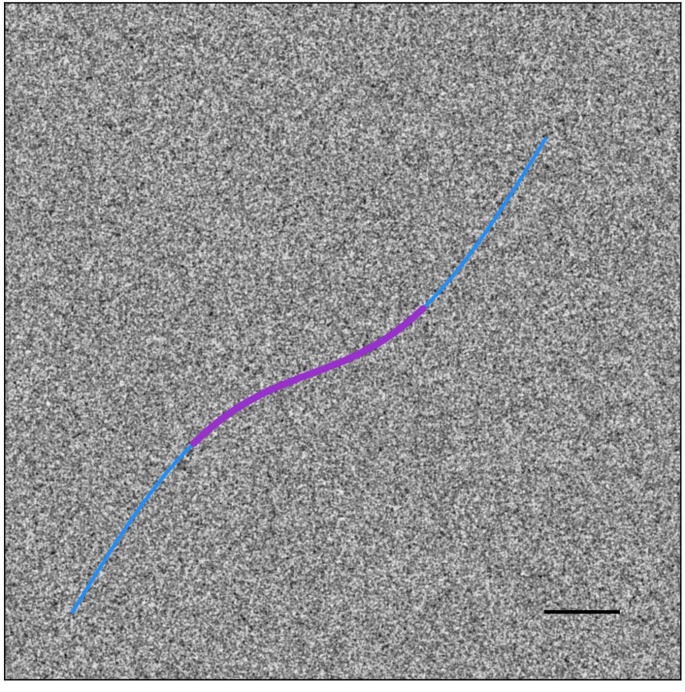

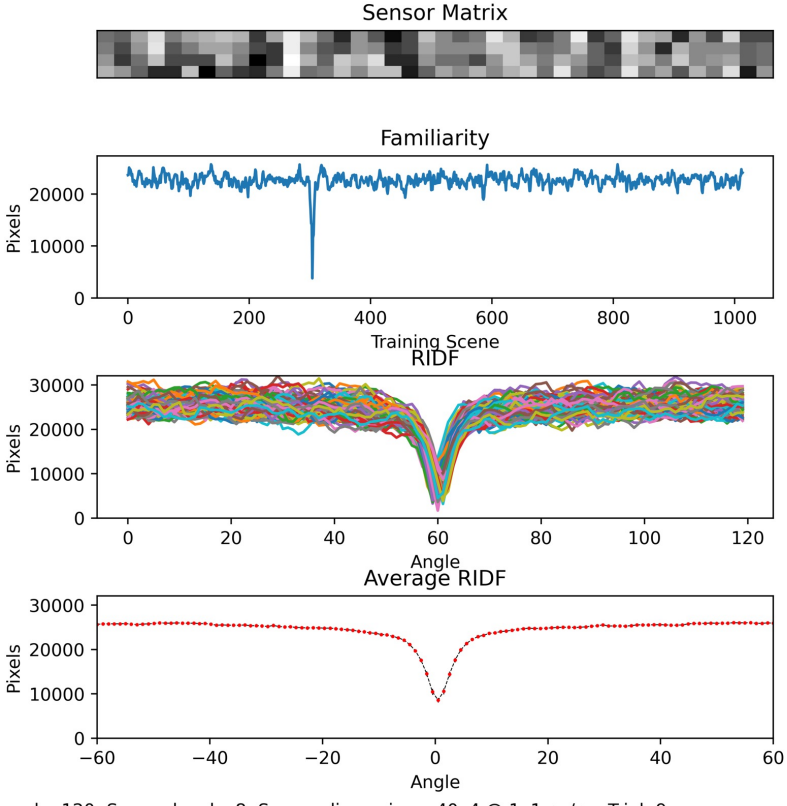

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9
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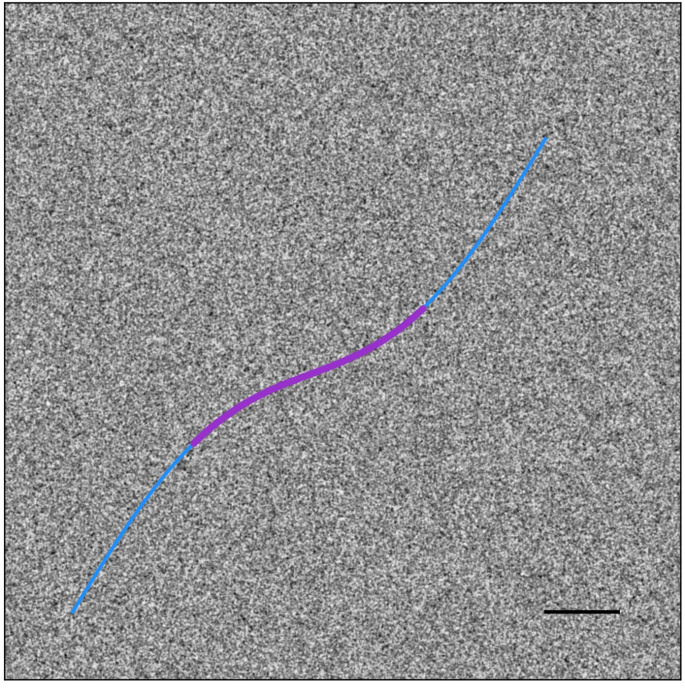

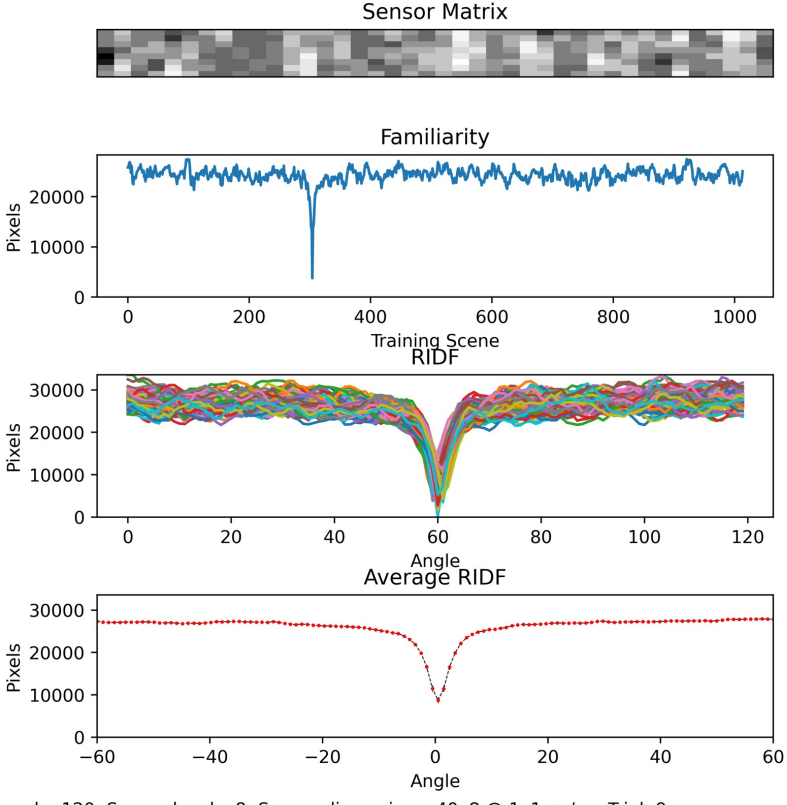

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9
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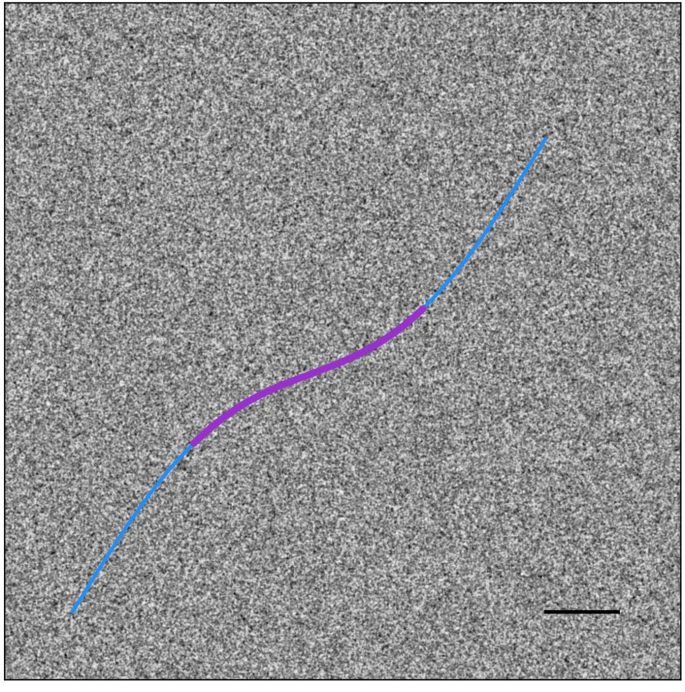

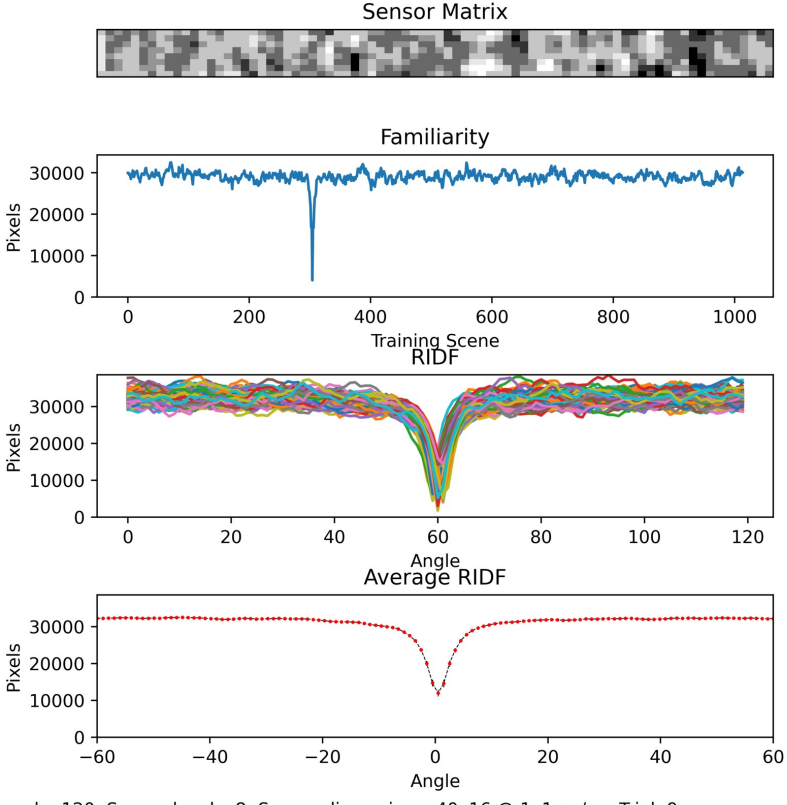

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9
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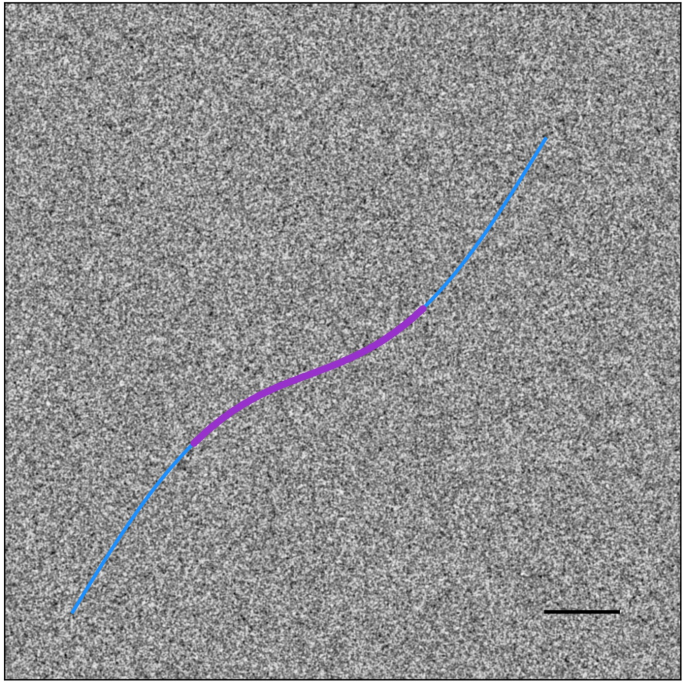
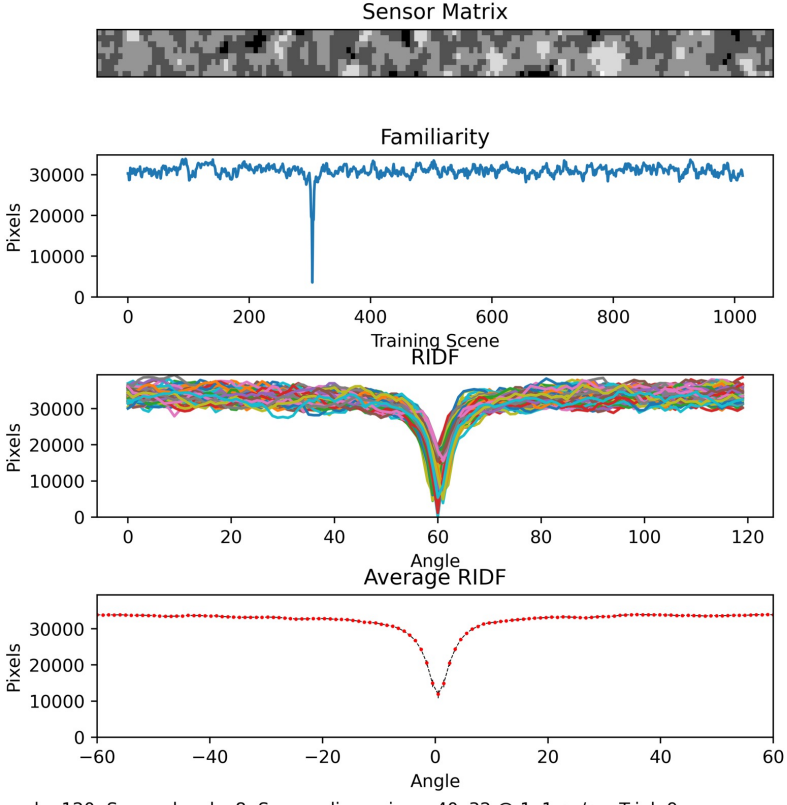
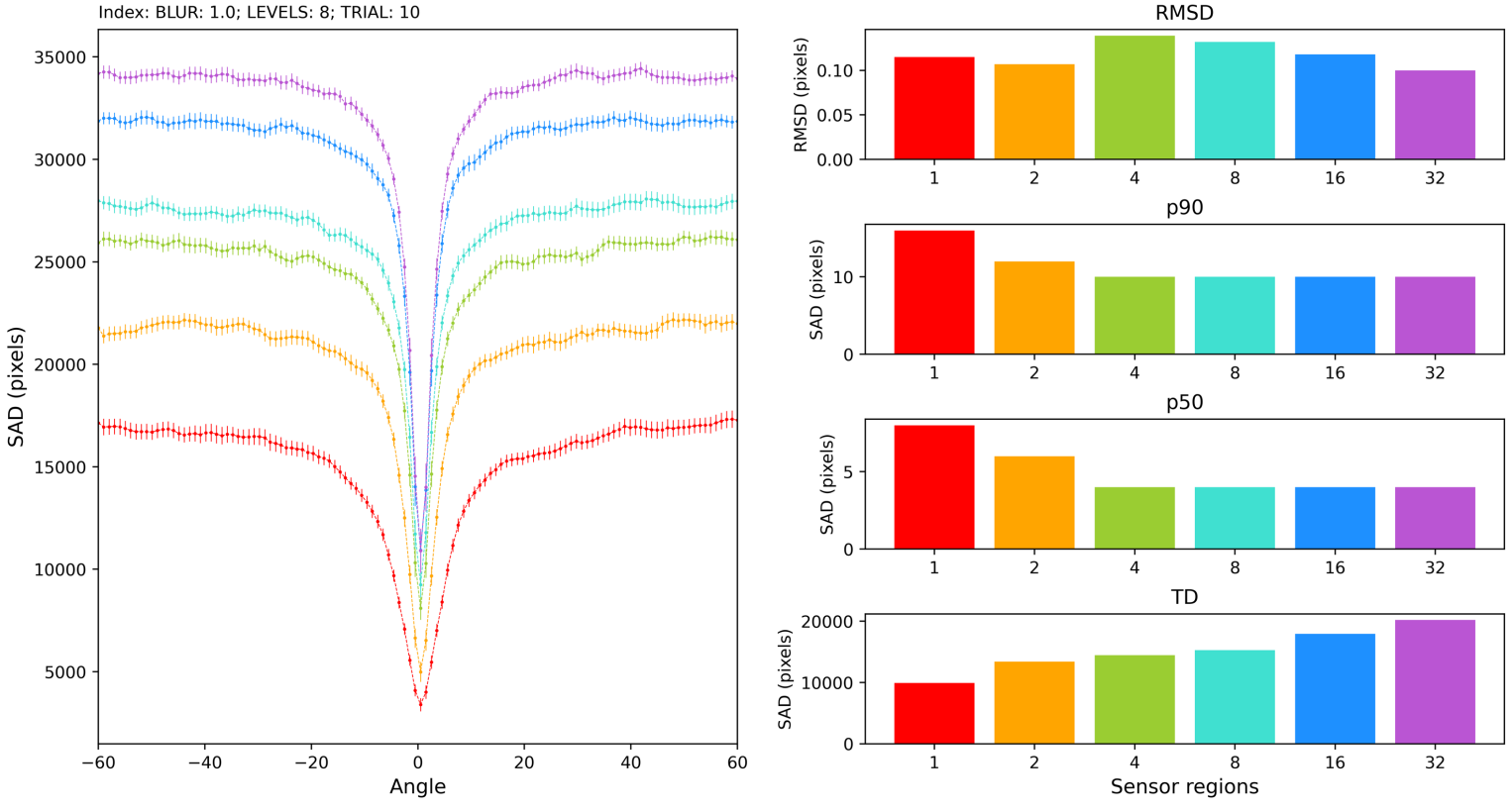




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 50.34; RMSD/dist: 0.126; TD: 18826; p90: 12; p50: 4; complete: 0


Index: BLUR: 1.0; LEVELS: 8; TRIAL: 10
SAD (pixels)
35000
30000
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20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
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TD
SAD (pixels)
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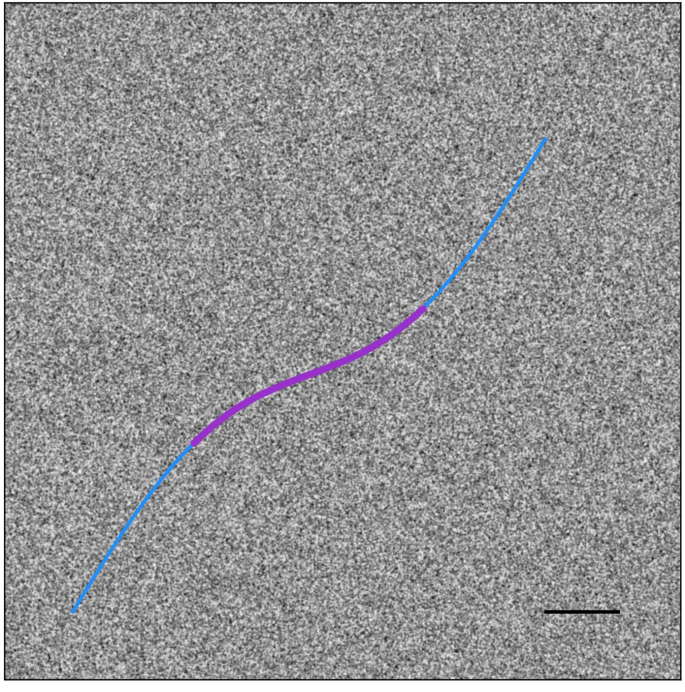
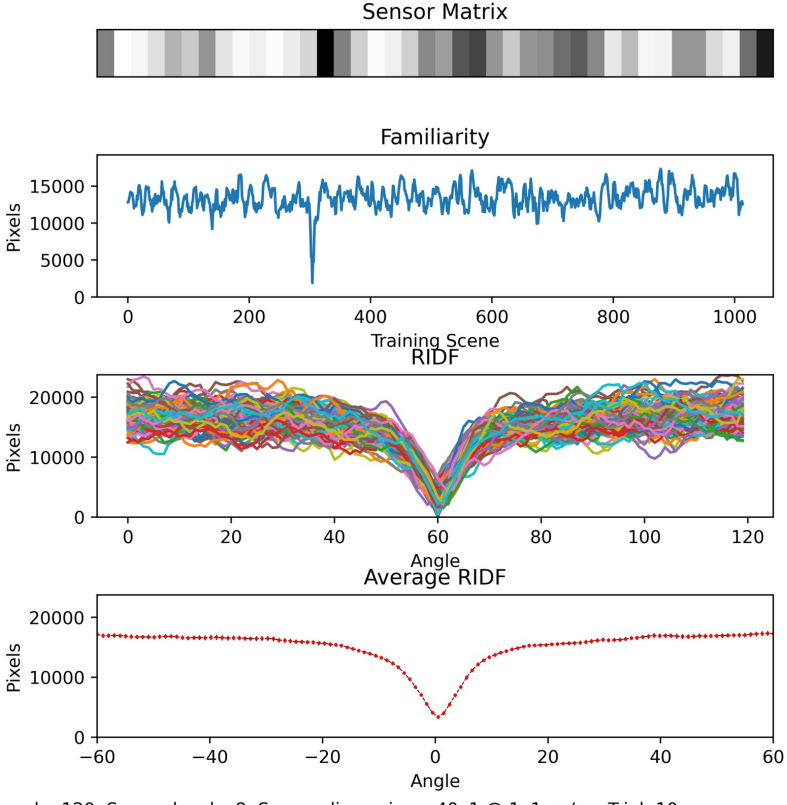
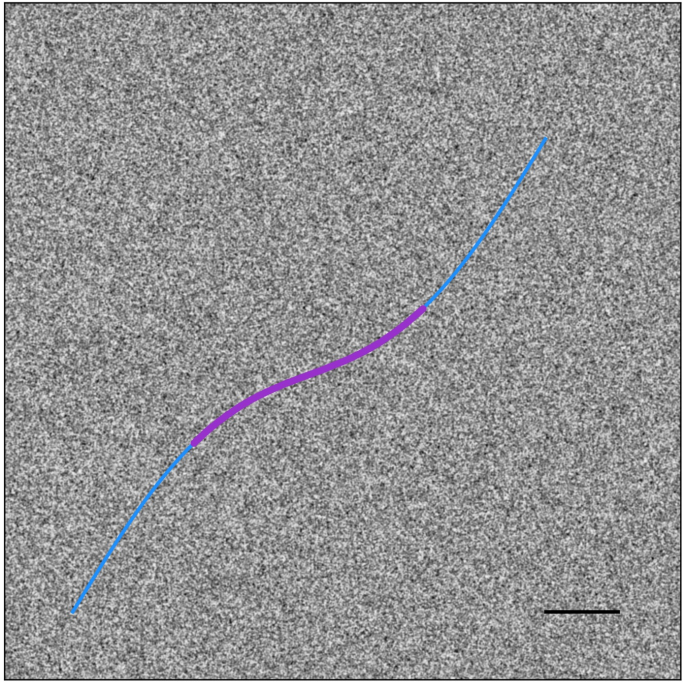
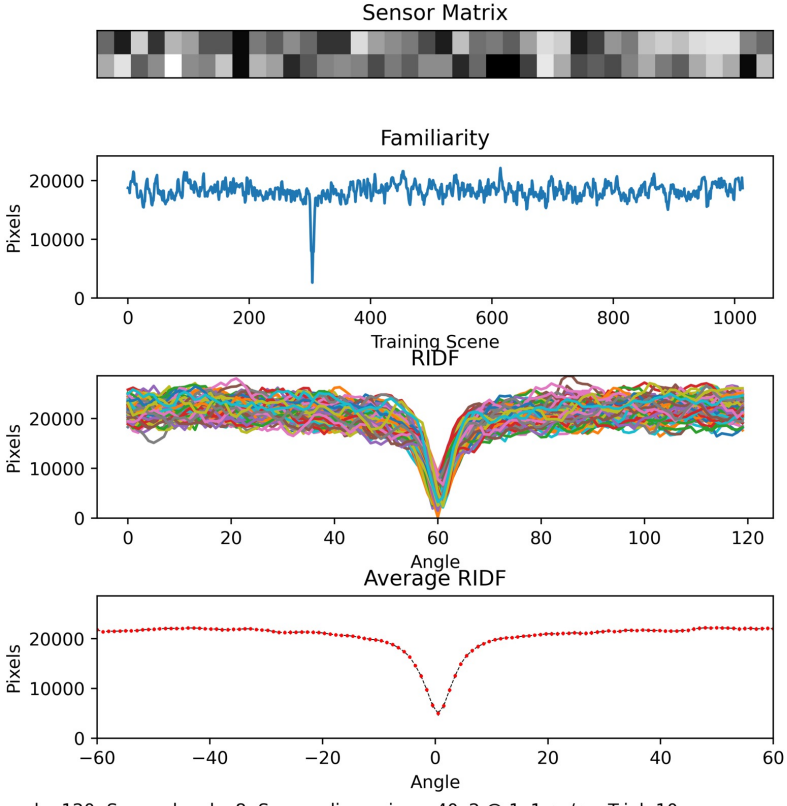
10000
0
Sensor regions



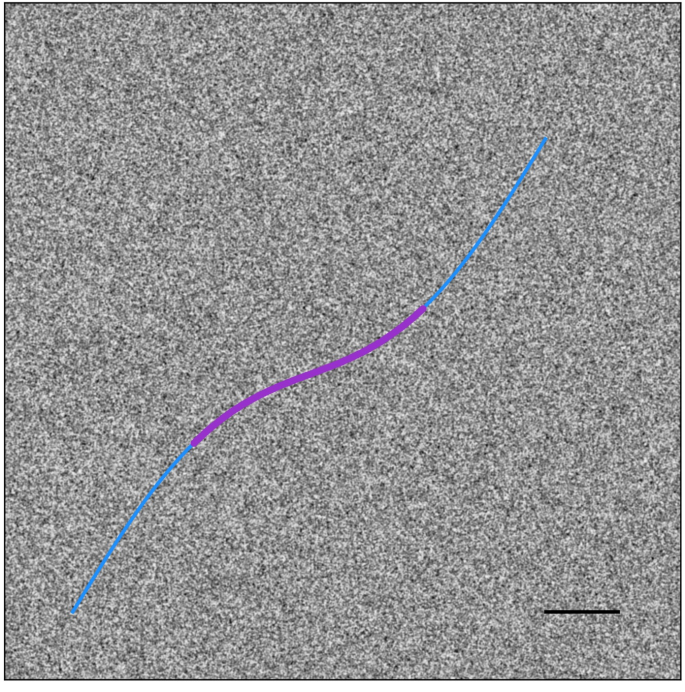


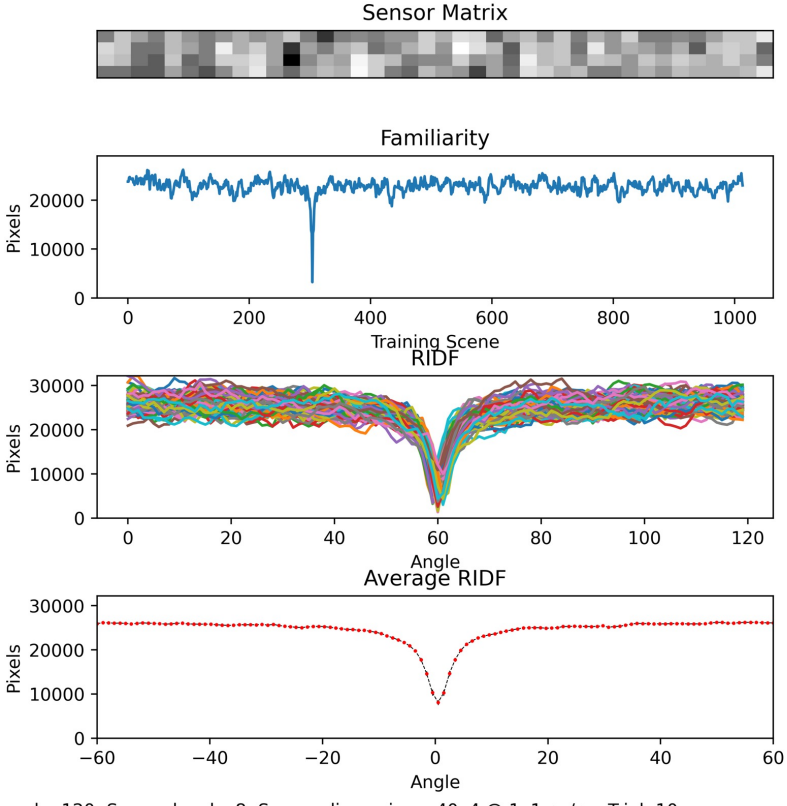
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 45.99; RMSD/dist: 0.115; TD: 9921; p90: 16; p50: 8; complete: 0



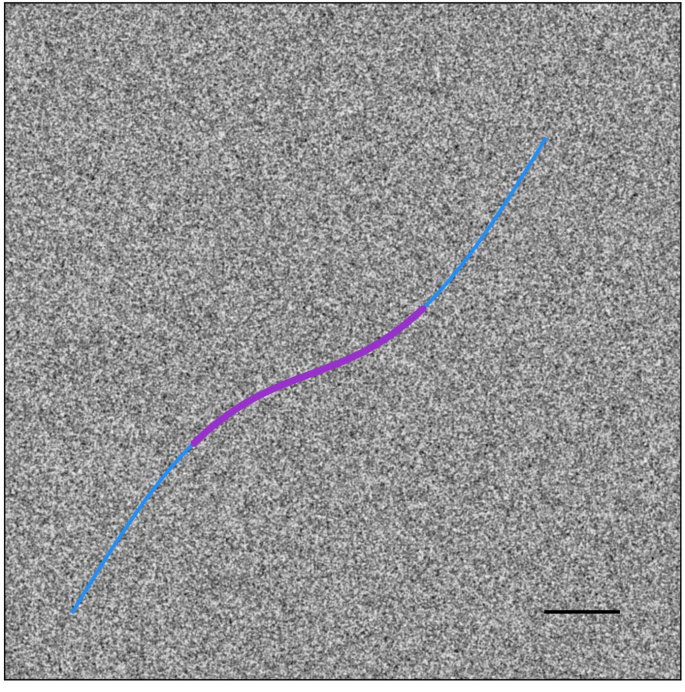


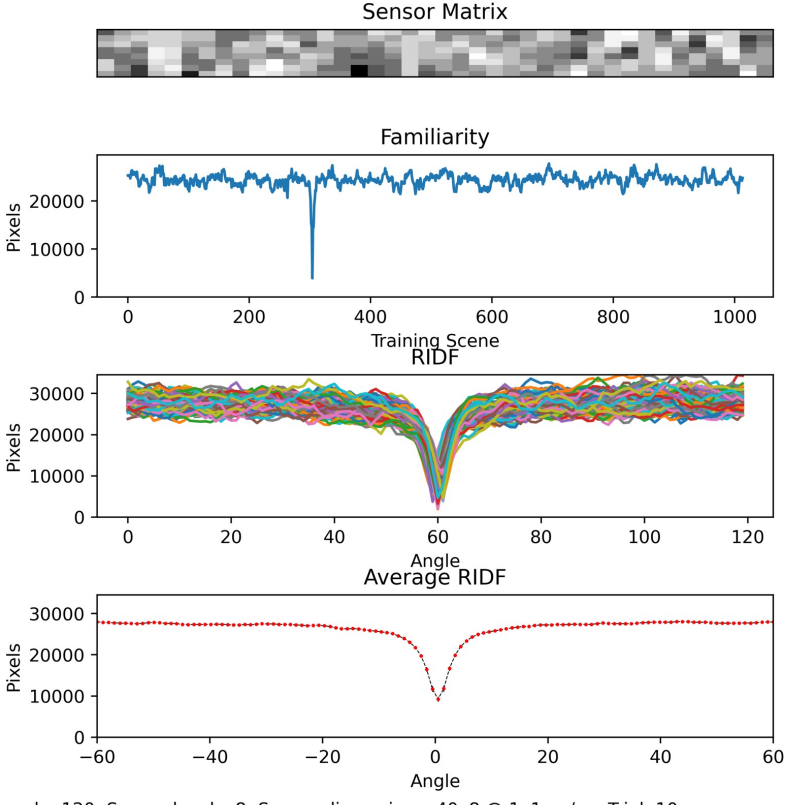
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 42.87; RMSD/dist: 0.107; TD: 13408; p90: 12; p50: 6; complete: 0



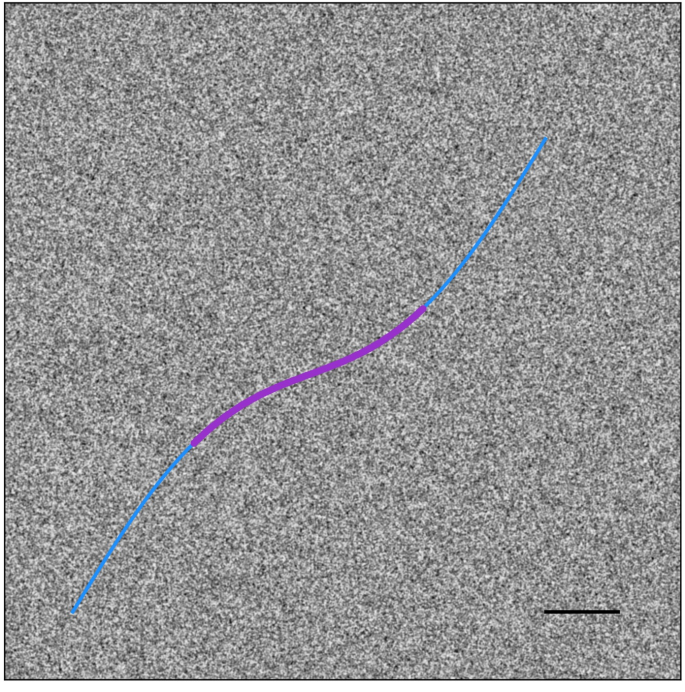


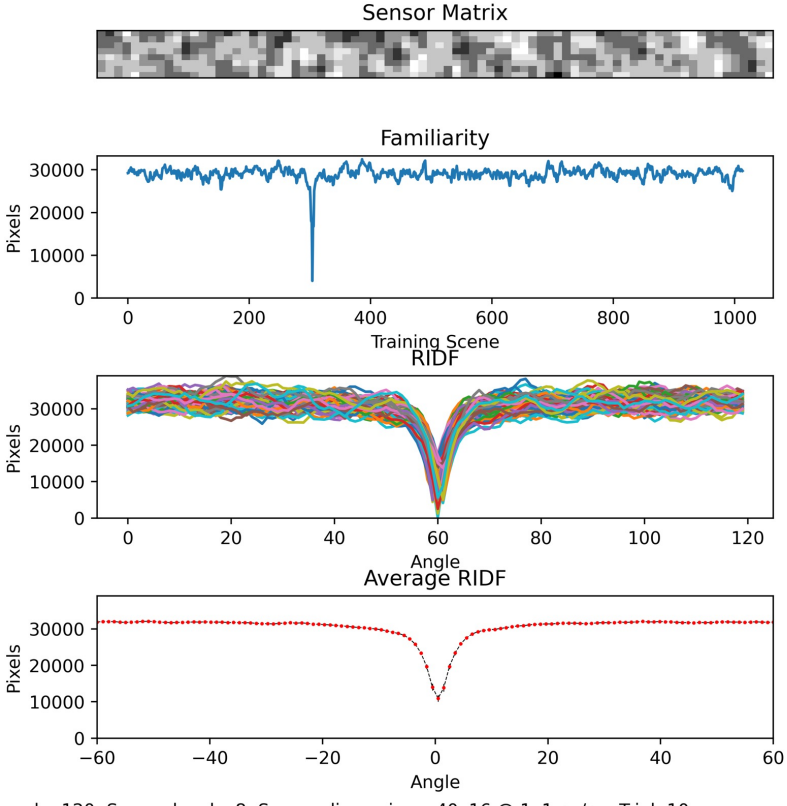
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 55.79; RMSD/dist: 0.139; TD: 14462; p90: 10; p50: 4; complete: 0



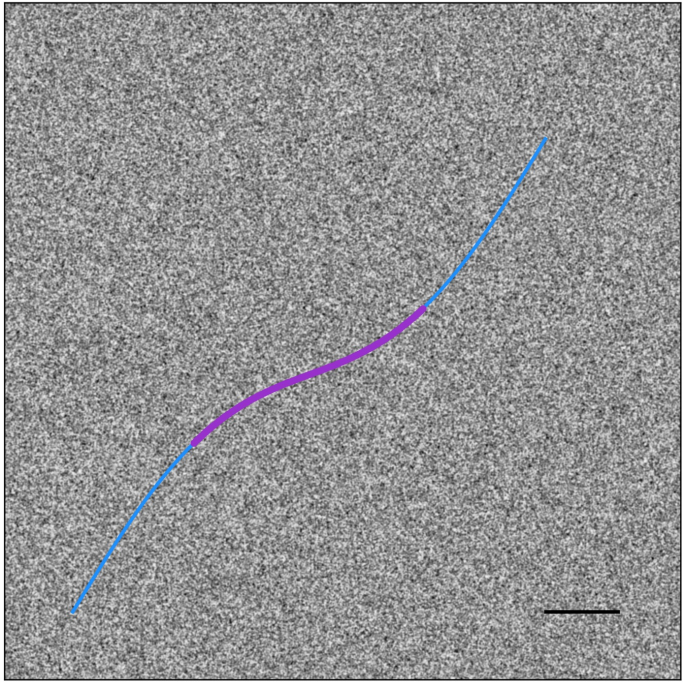


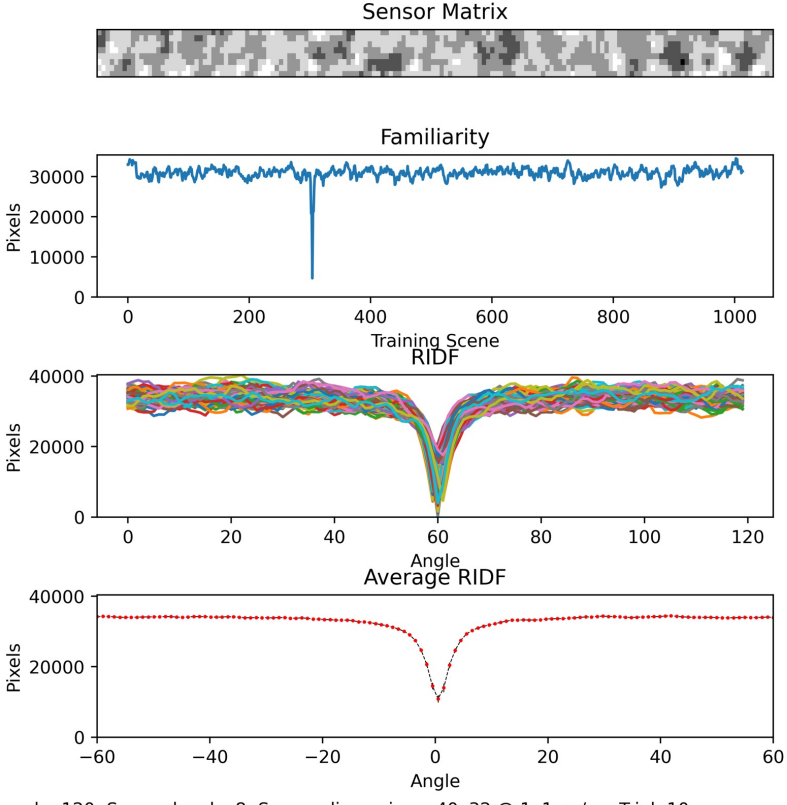
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 52.88; RMSD/dist: 0.132; TD: 15261; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 47.37; RMSD/dist: 0.118; TD: 17928; p90: 10; p50: 4; complete: 0





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 1; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 39.88; RMSD/dist: 0.100; TD: 20170; p90: 10; p50: 4; complete: 0