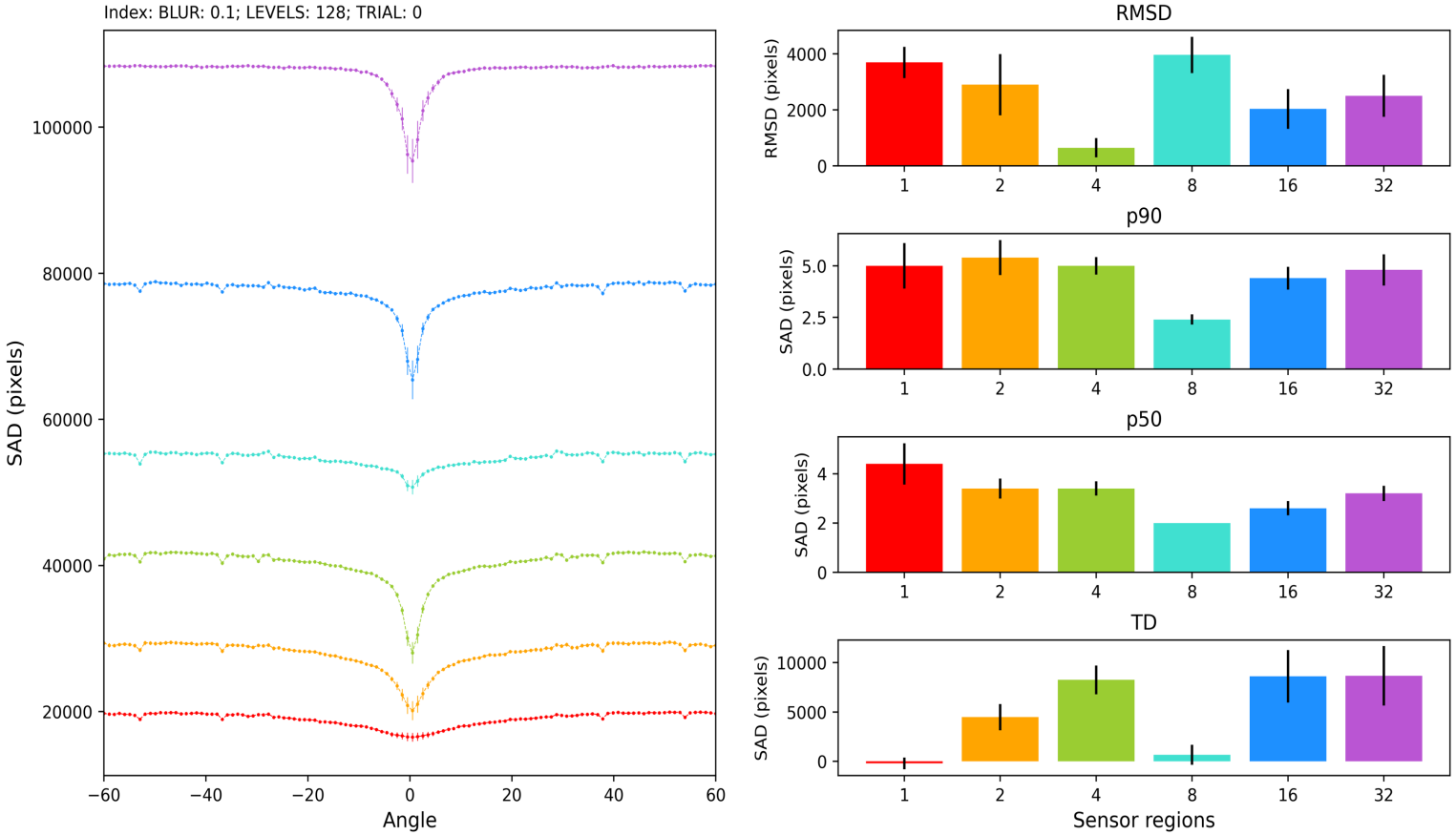
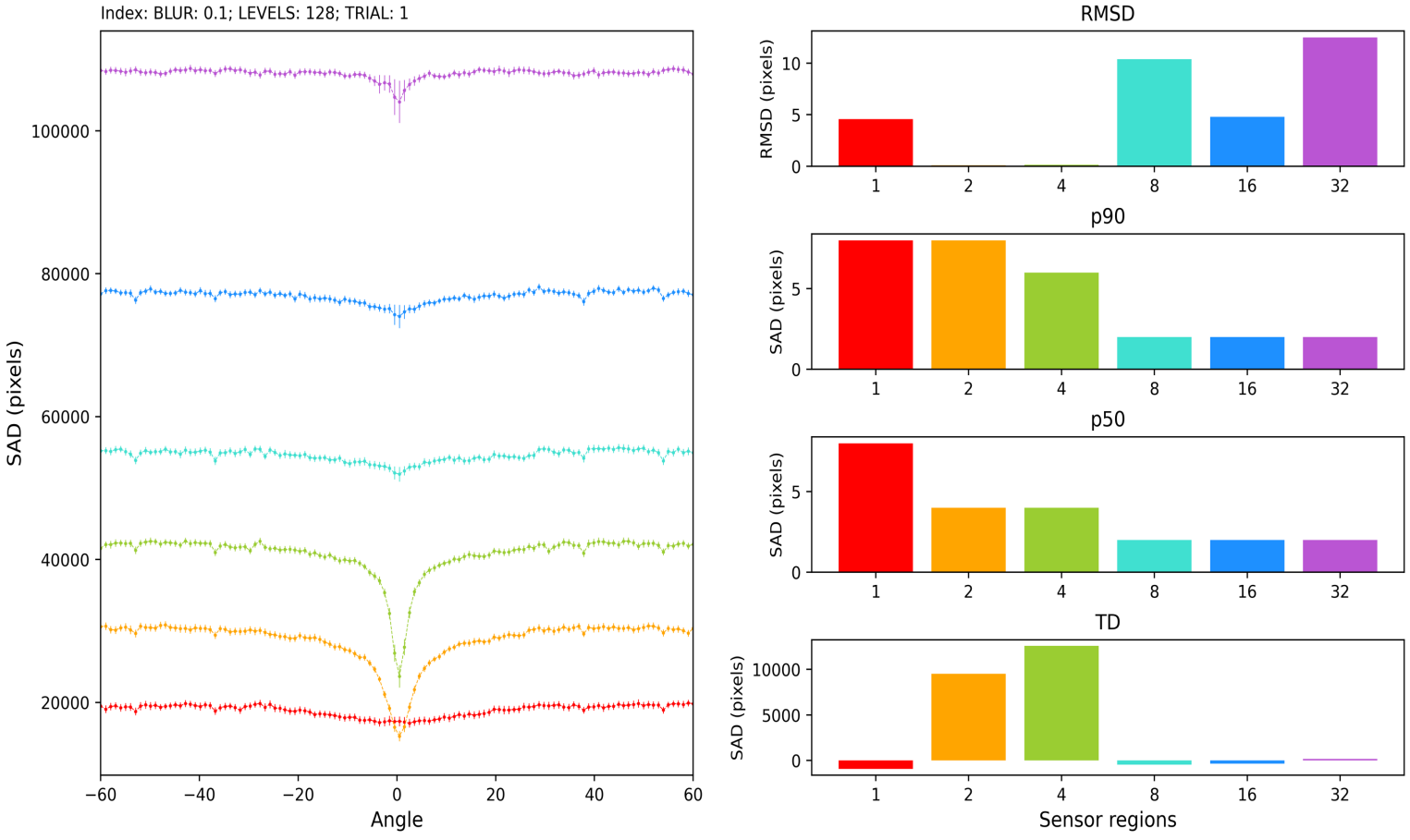
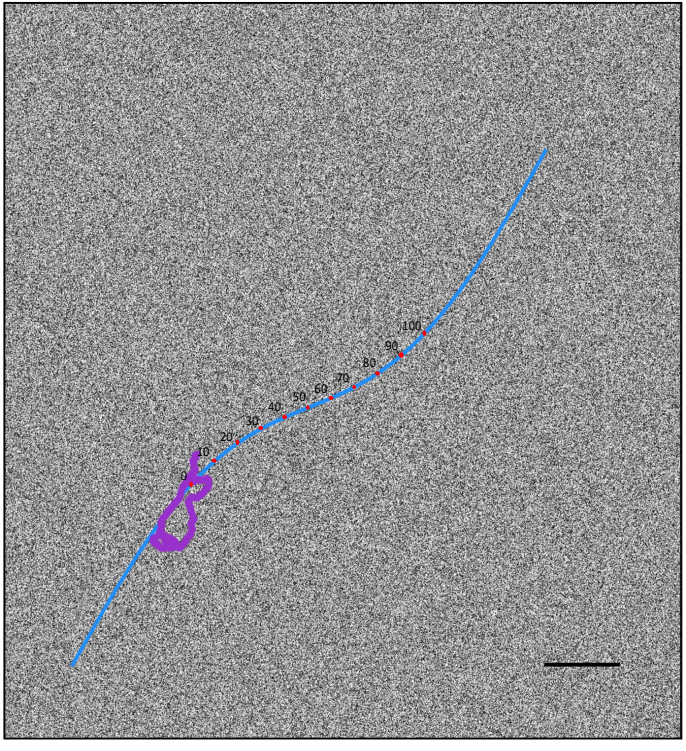
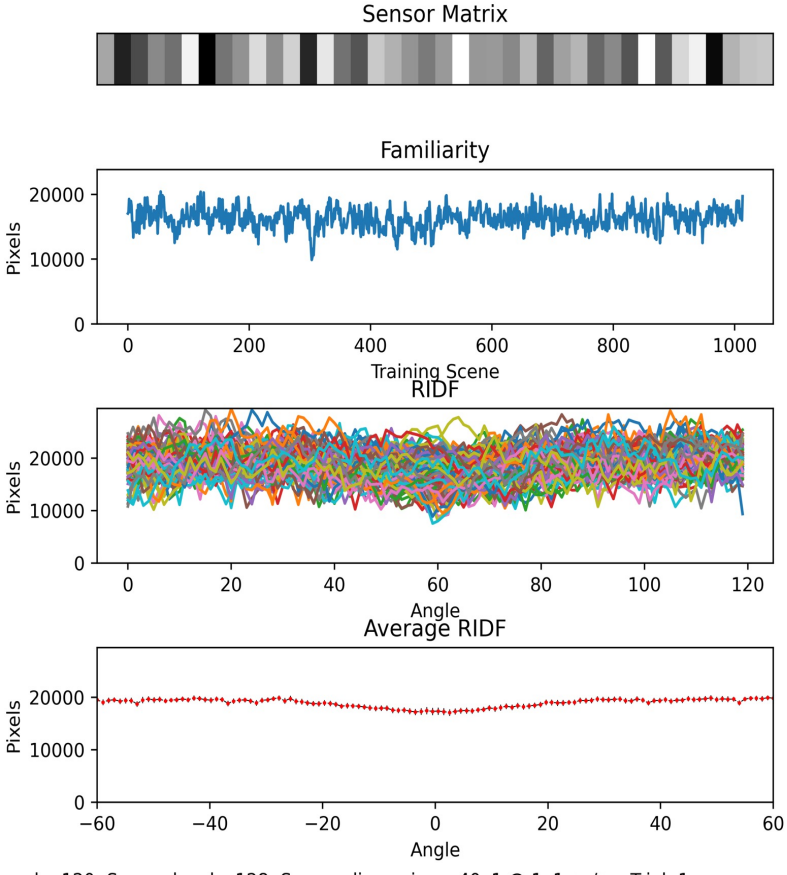

Index: BLUR: 0.1; LEVELS: 128; TRIAL: 0
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4000
2000
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
TD
10000
5000
Sensor regions


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 1
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
5
0
TD
SAD (pixels)
10000
5000
0
Sensor regions

0%

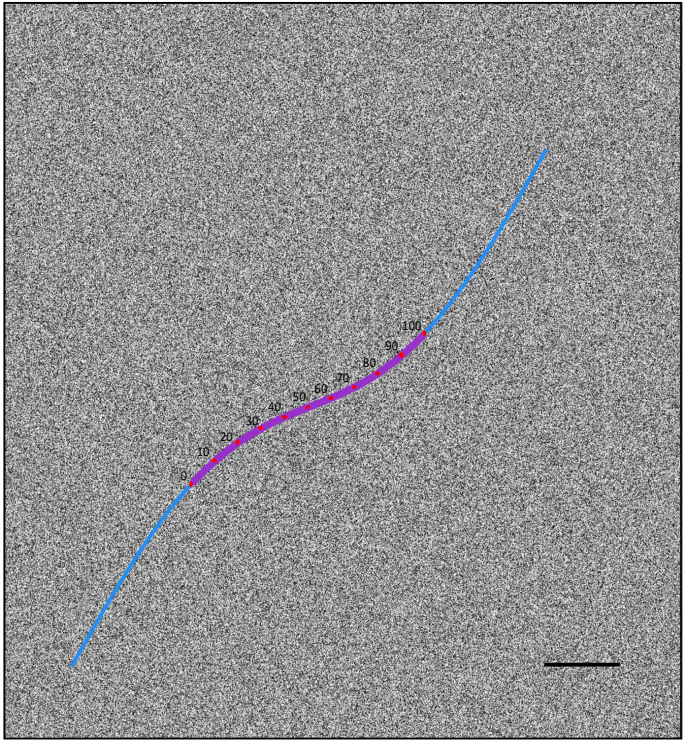


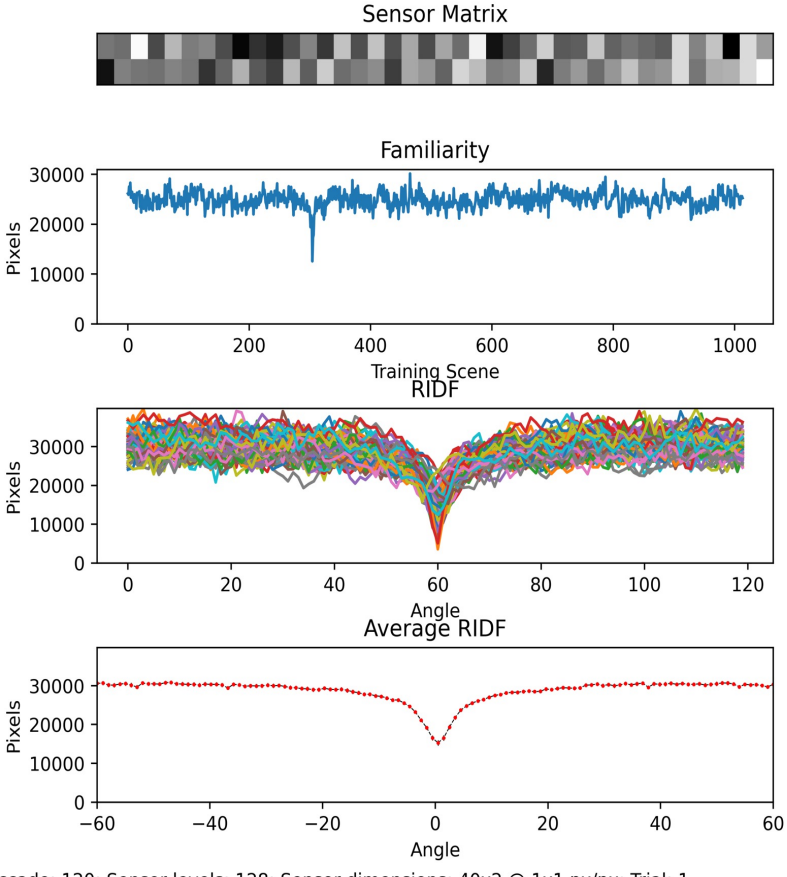


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1826.61; RMSD/dist: 4.567; TD: -920; p90: 8; p50: 8; complete: 0

100%

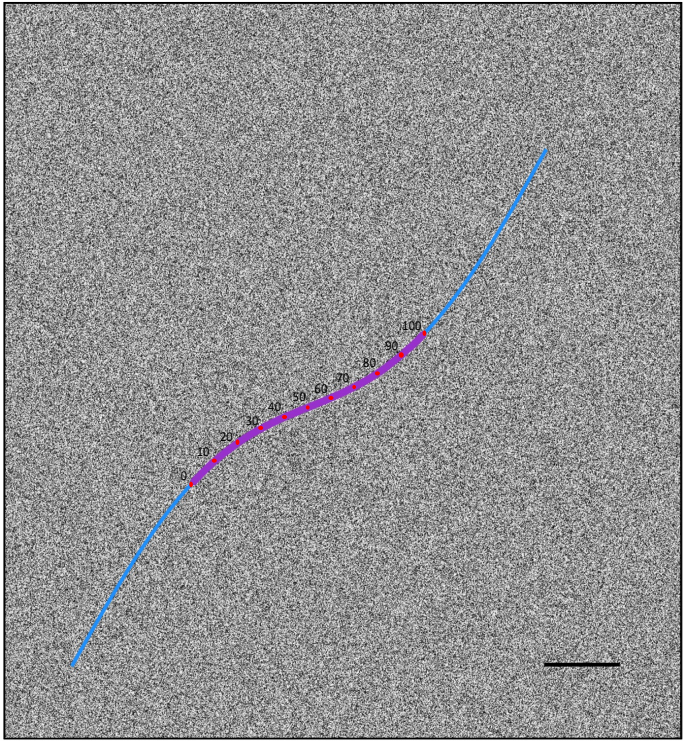


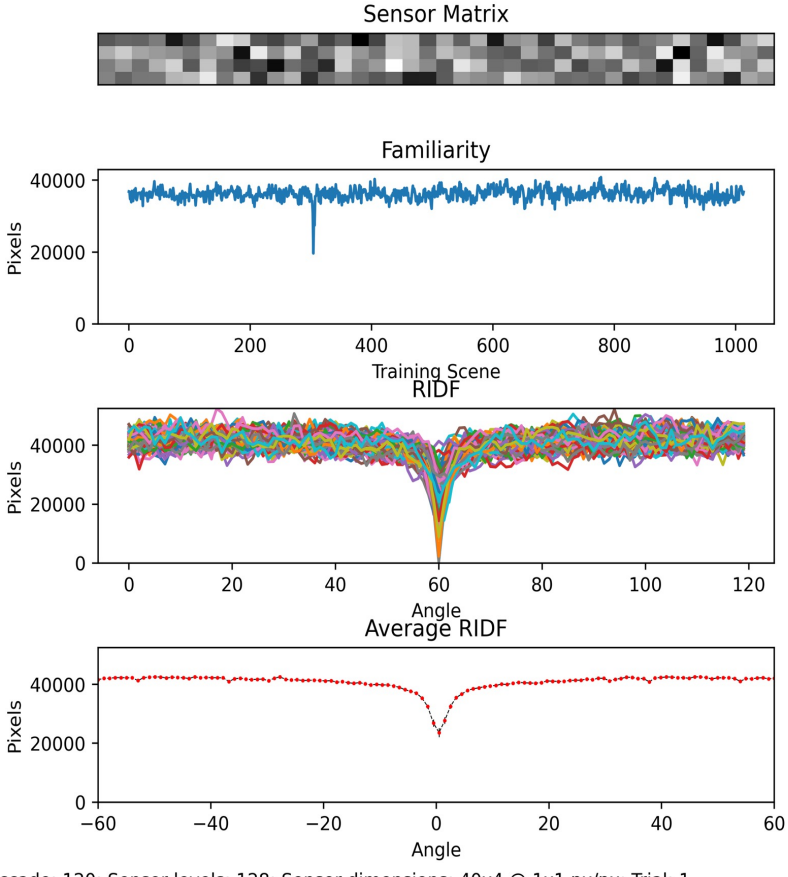


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 36.89; RMSD/dist: 0.092; TD: 9511; p90: 8; p50: 4; complete: 0

100%

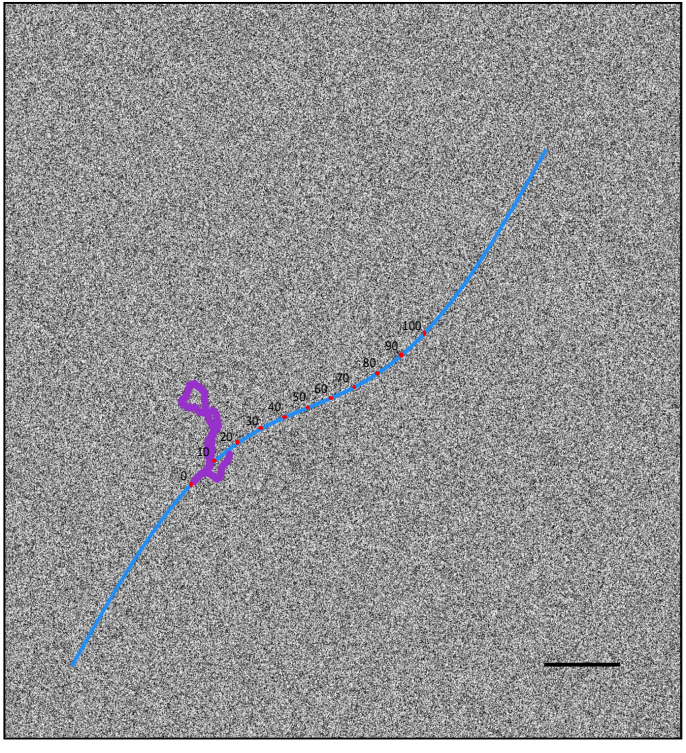


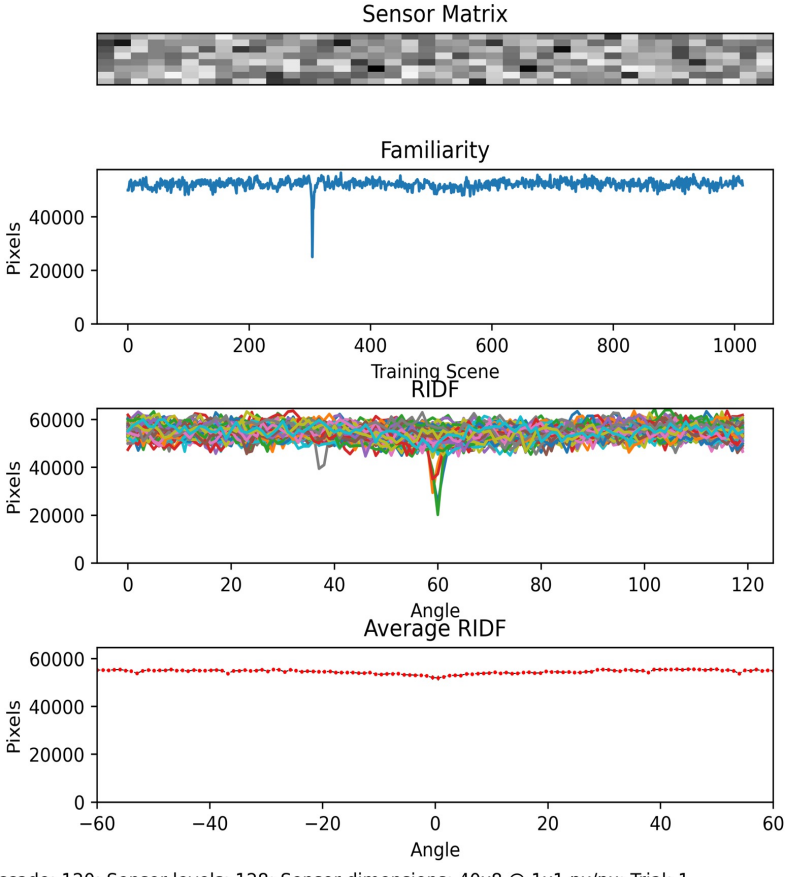


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 53.01; RMSD/dist: 0.133; TD: 12564; p90: 6; p50: 4; complete: 0

10%

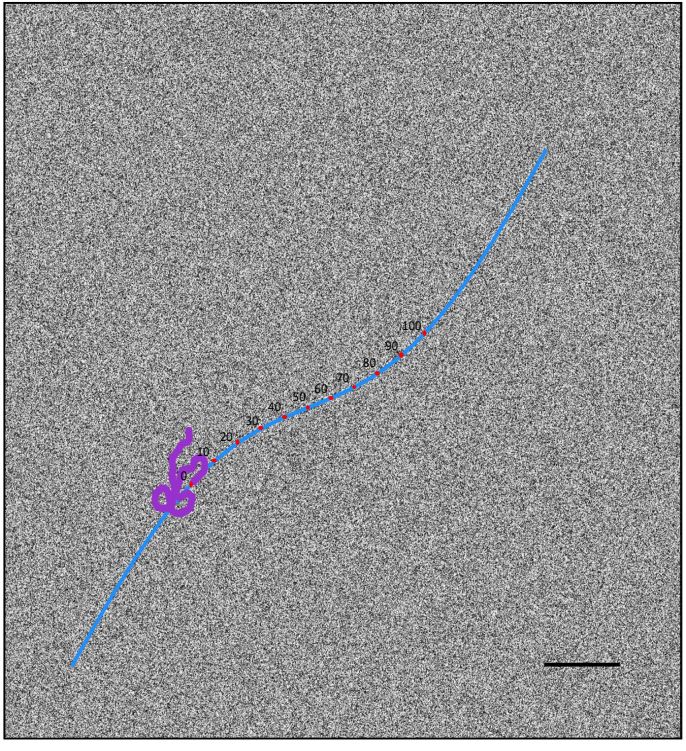


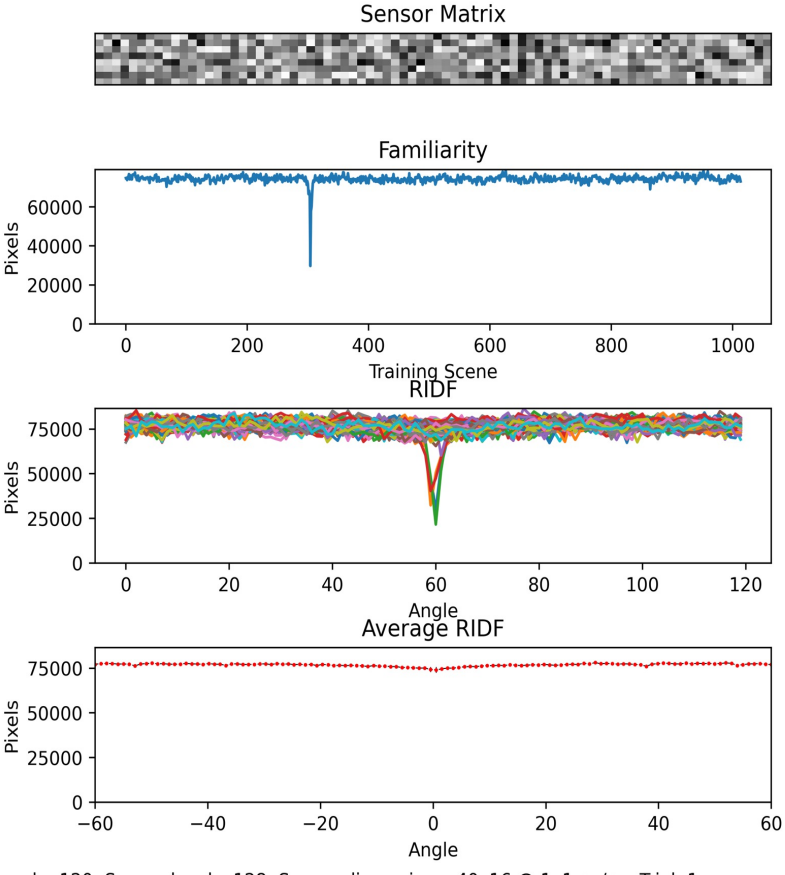


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4156.58; RMSD/dist: 10.391; TD: -464; p90: 2; p50: 2; complete: 0

0%

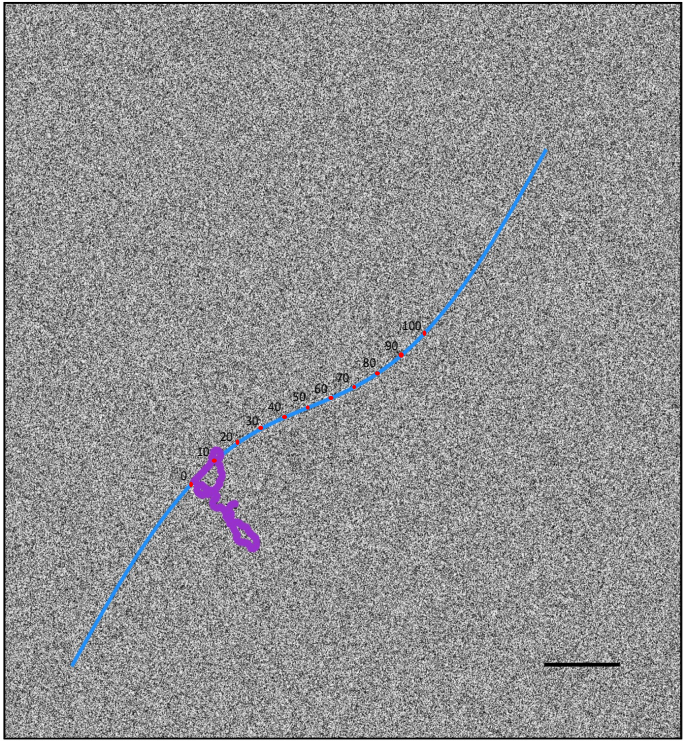


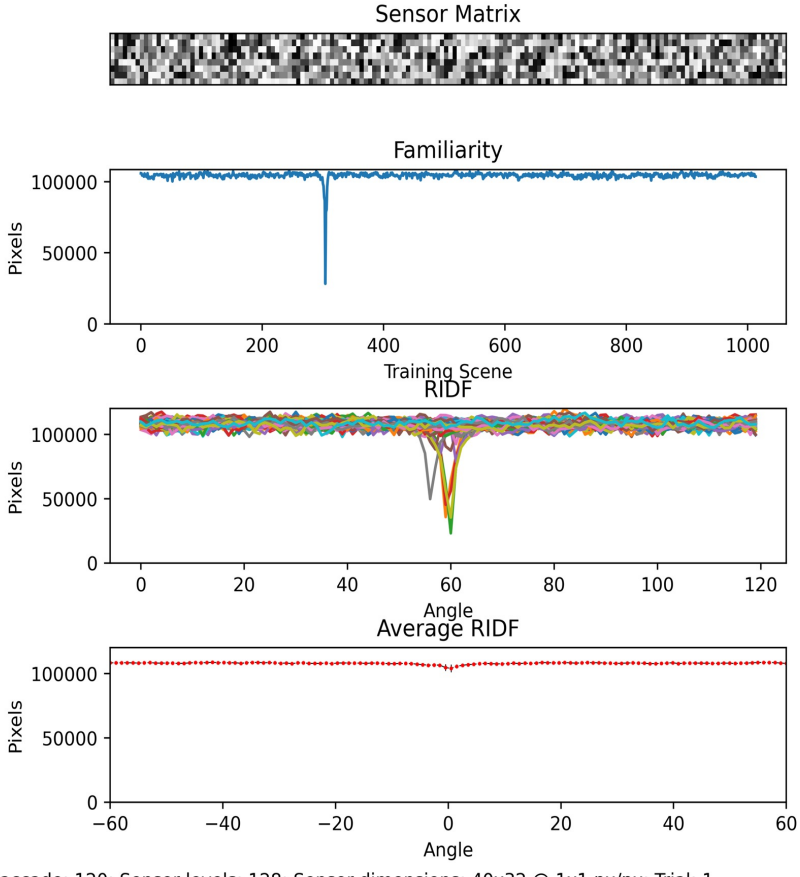


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 1917.72; RMSD/dist: 4.794; TD: -341; p90: 2; p50: 2; complete: 0

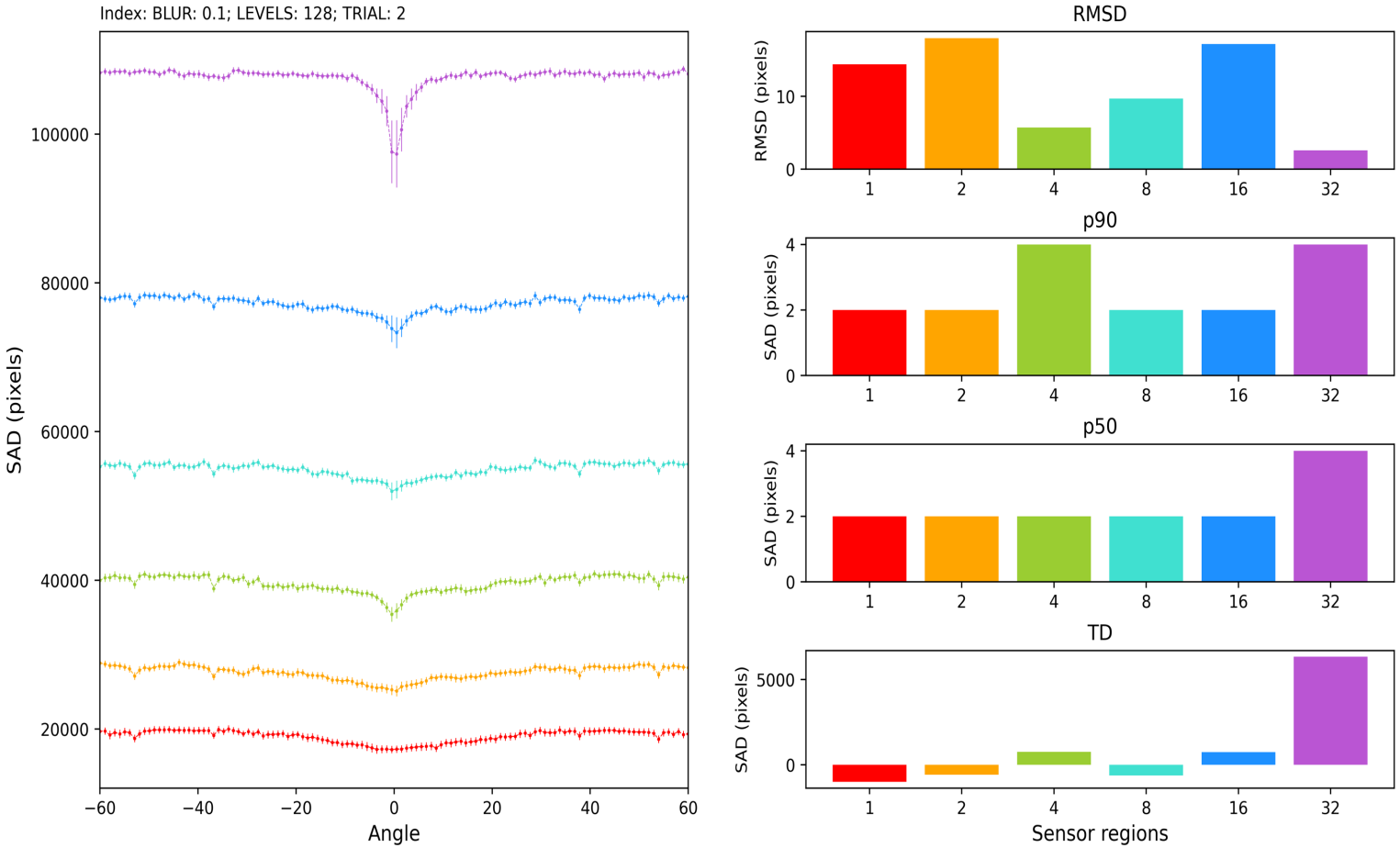
10%



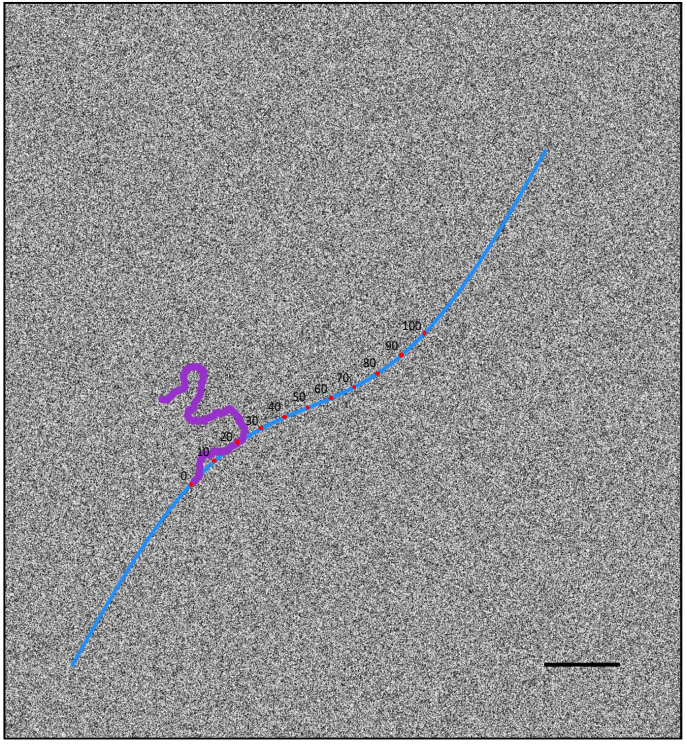


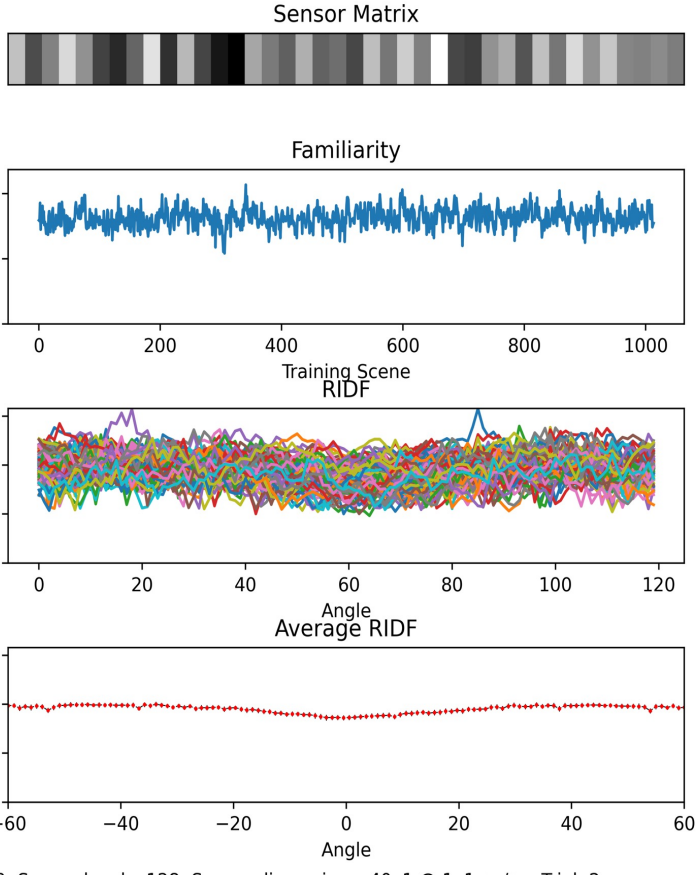
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 5001.76; RMSD/dist: 12.504; TD: 184; p90: 2; p50: 2; complete: 0


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 2
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
4
2
0
p50
TD
5000
Sensor regions

10%

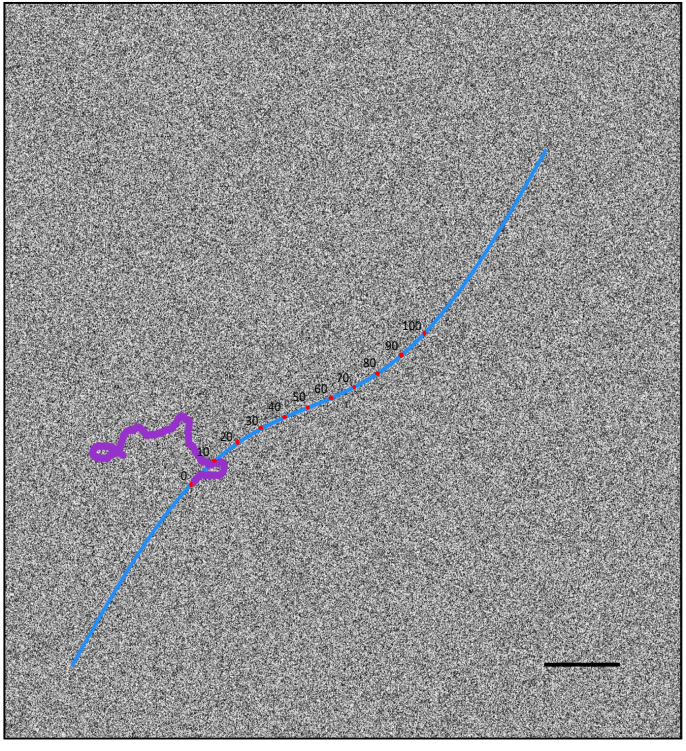


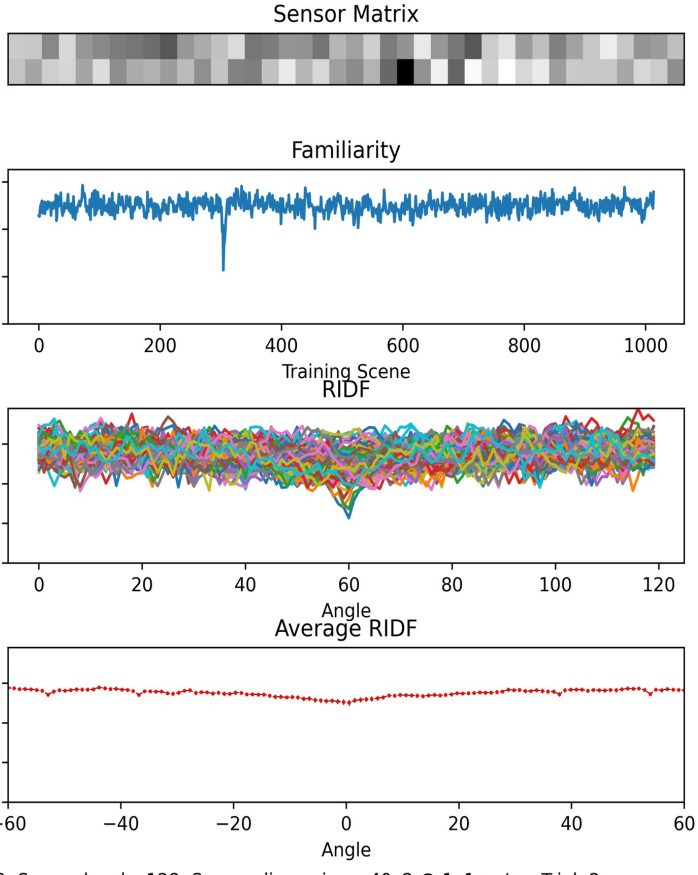


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 5763.78; RMSD/dist: 14.409; TD: -995; p90: 2; p50: 2; complete: 0

0%

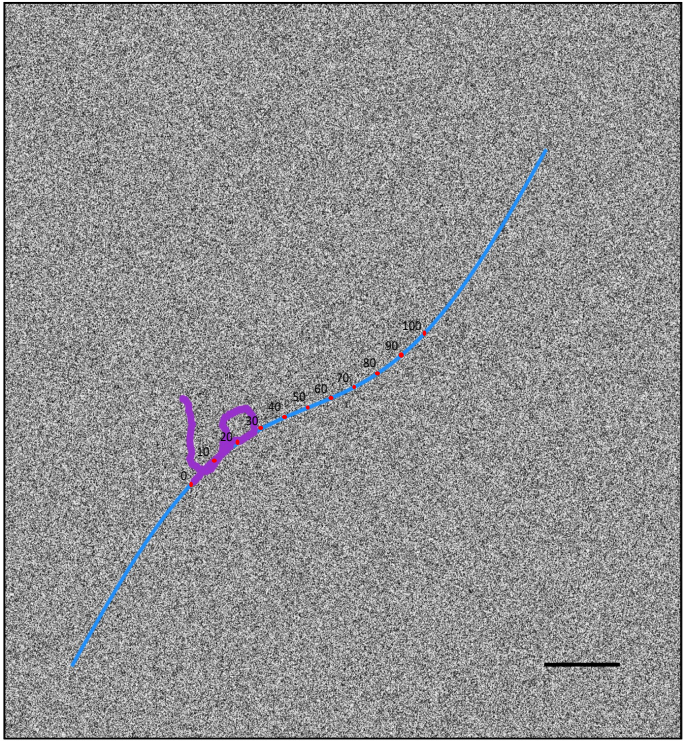


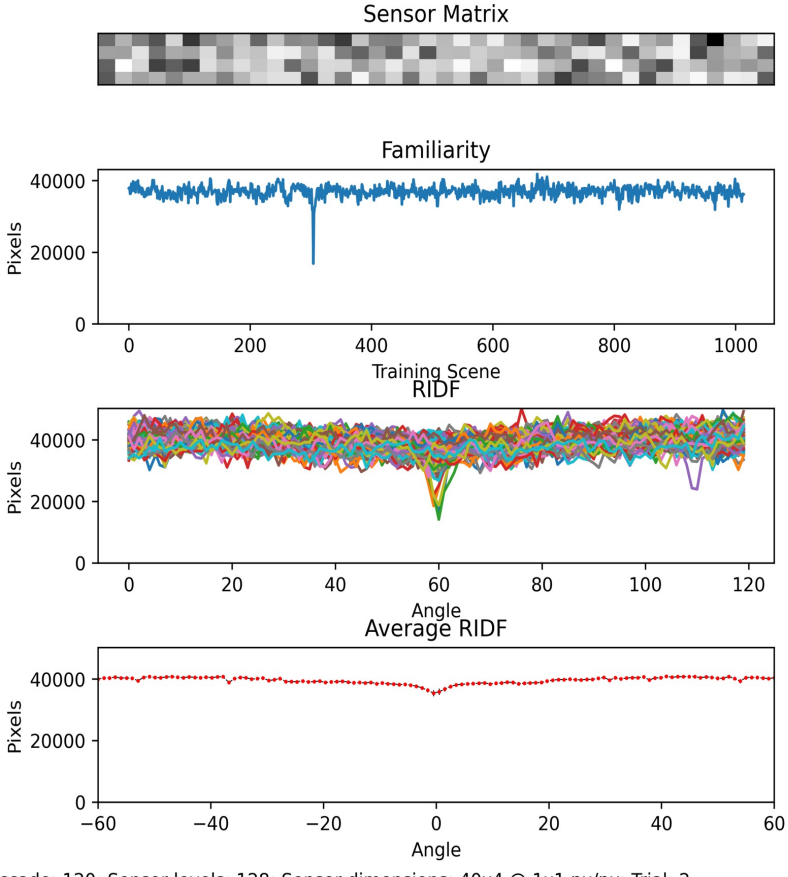


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 7199.37; RMSD/dist: 17.998; TD: -585; p90: 2; p50: 2; complete: 0

10%

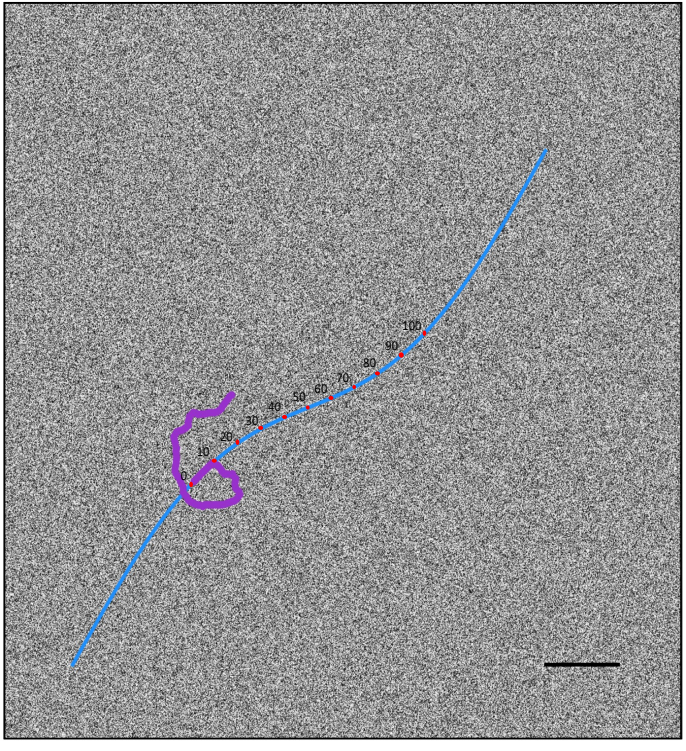


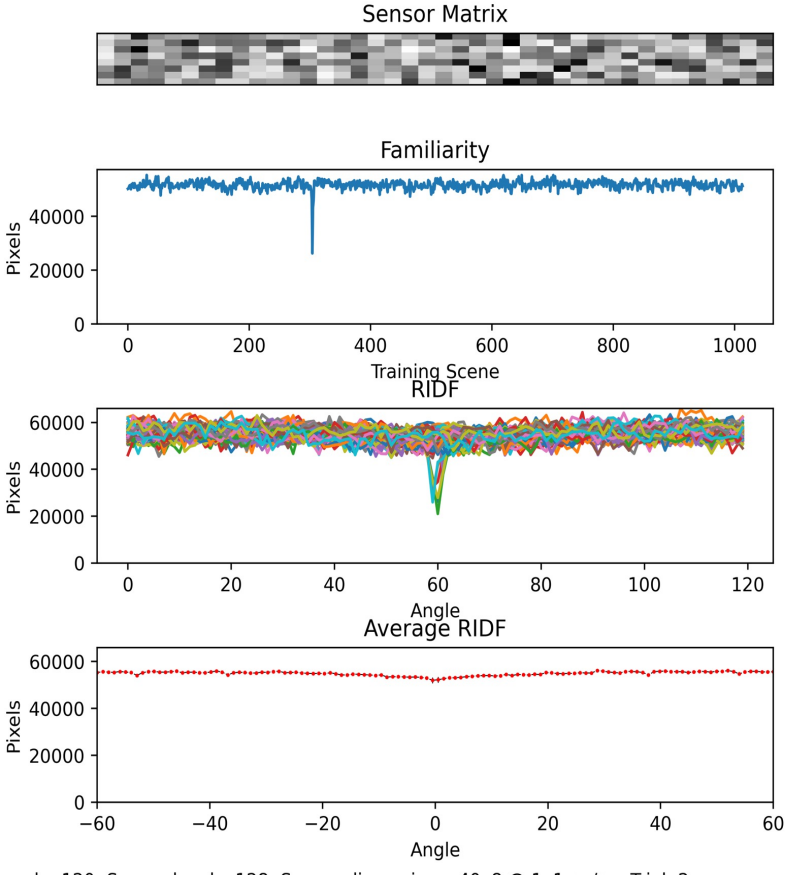


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2285.59; RMSD/dist: 5.714; TD: 759; p90: 4; p50: 2; complete: 0

10%

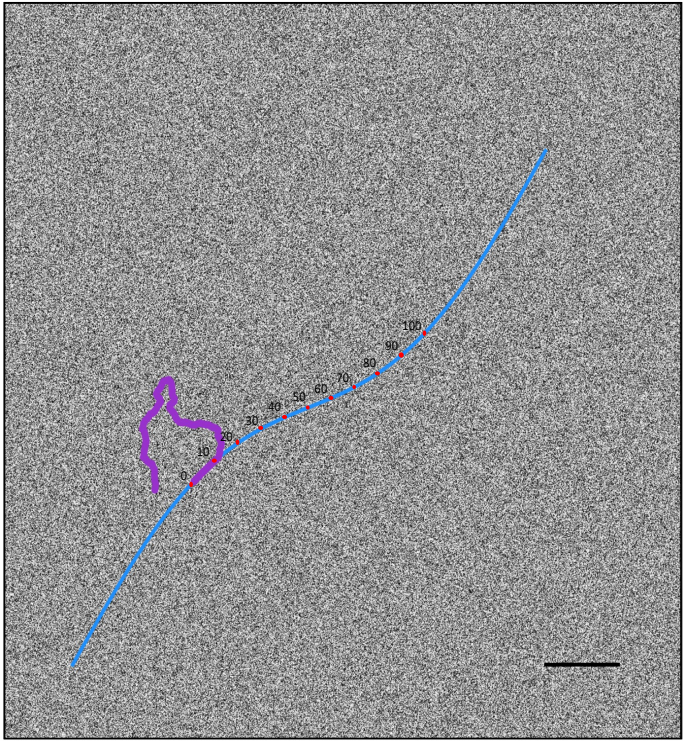


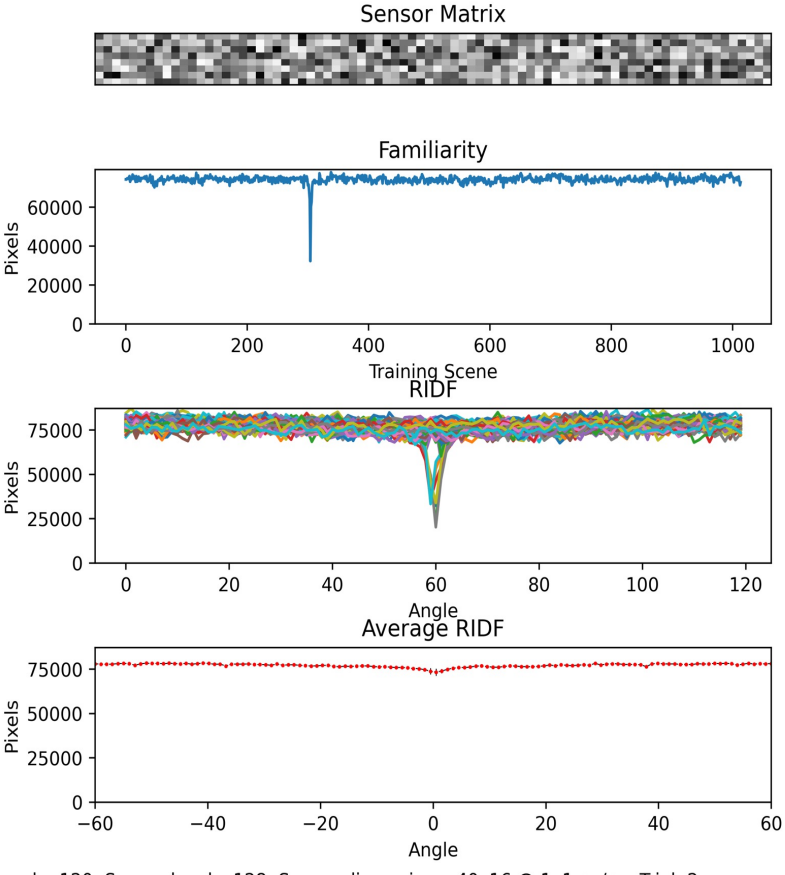


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 3877.69; RMSD/dist: 9.694; TD: -620; p90: 2; p50: 2; complete: 0

10%

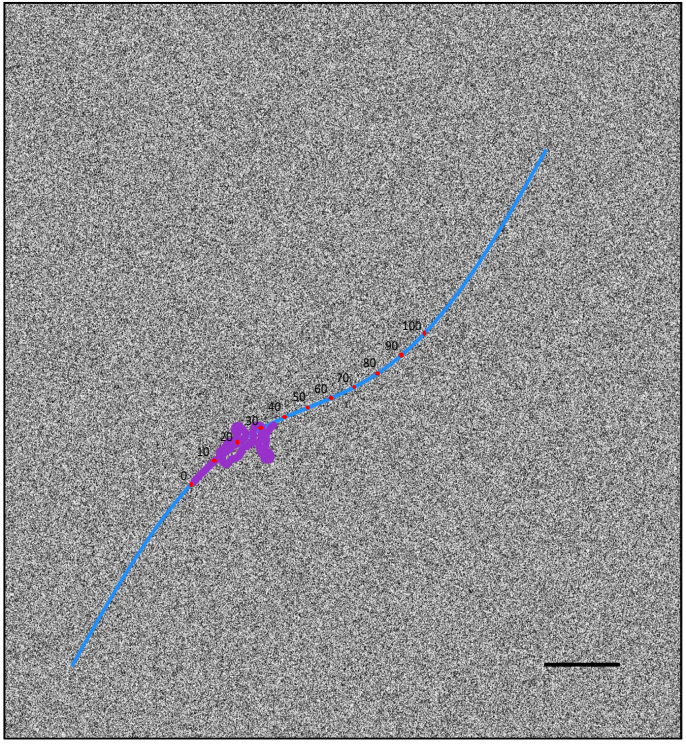


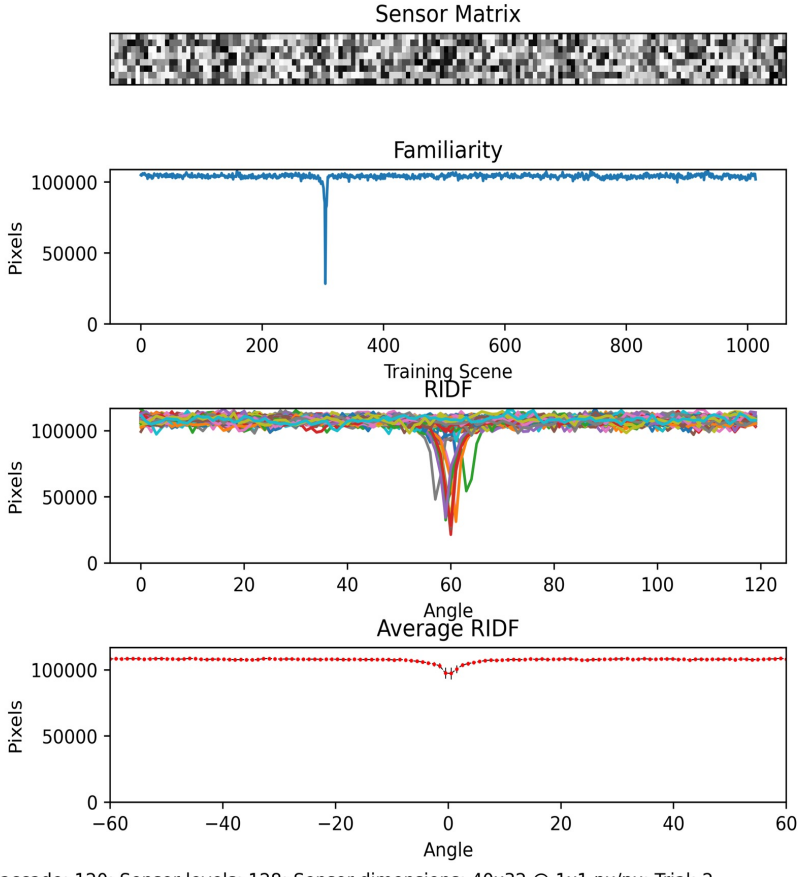


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 6879.82; RMSD/dist: 17.200; TD: 745; p90: 2; p50: 2; complete: 0

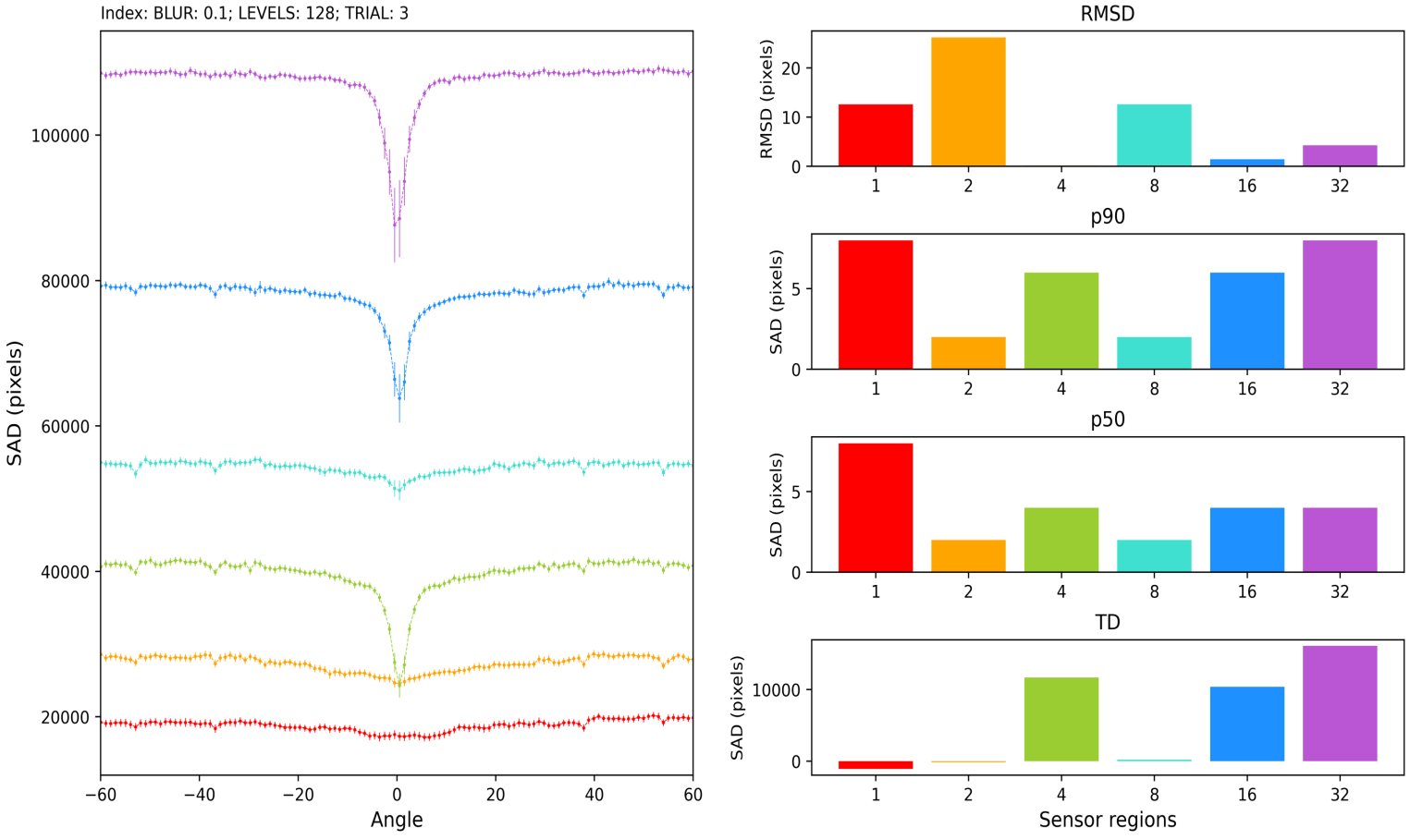
20%



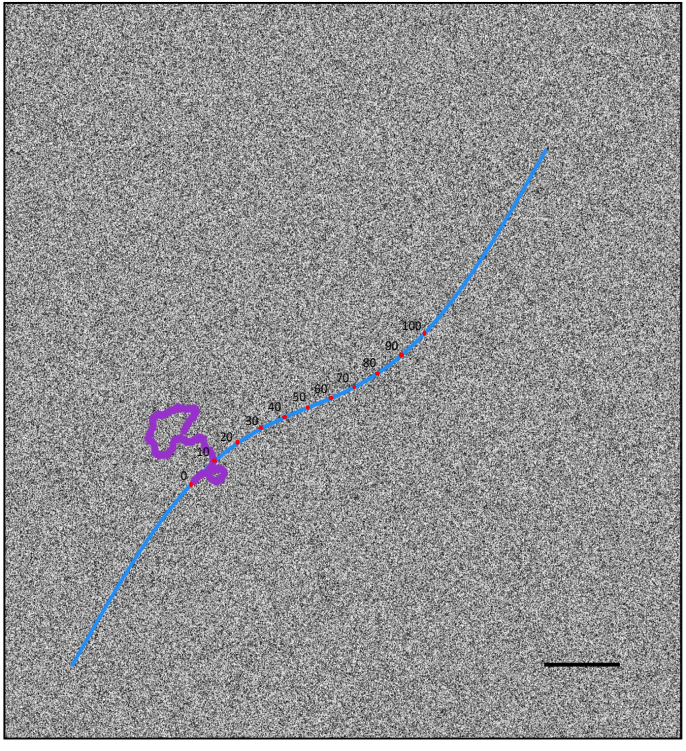


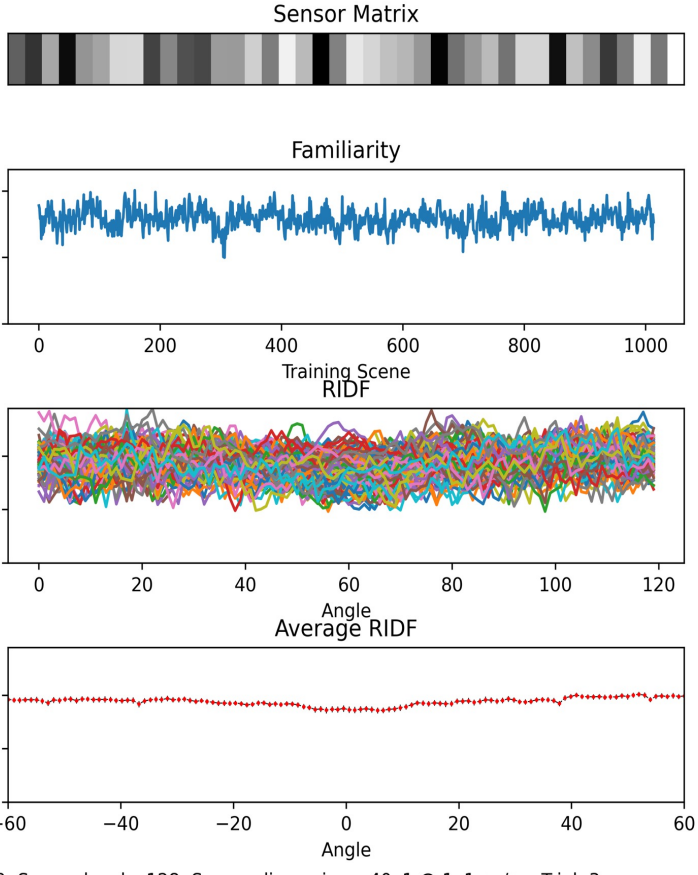
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1036.26; RMSD/dist: 2.591; TD: 6339; p90: 4; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 3
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
TD
10000
Sensor regions

0%

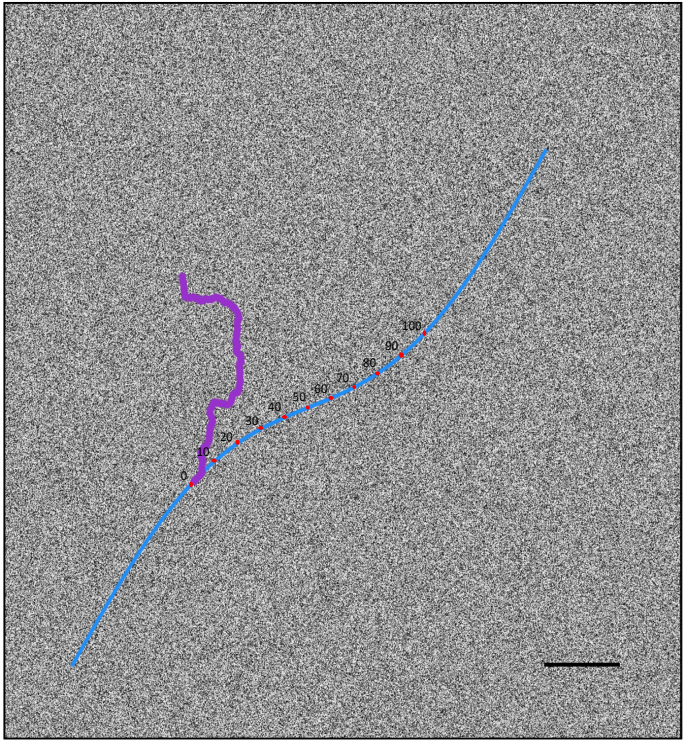


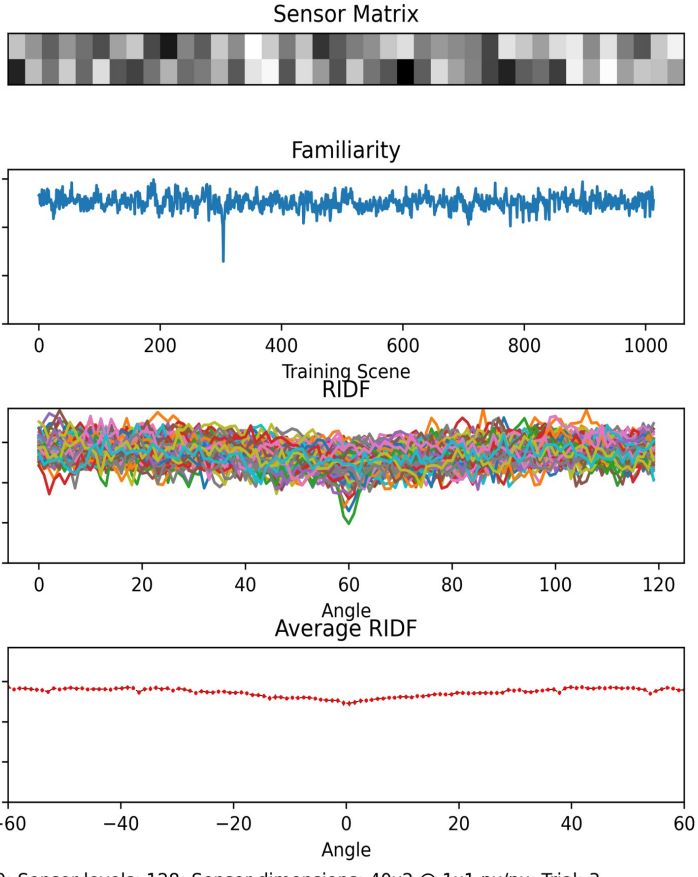


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 5034.03; RMSD/dist: 12.585; TD: -1089; p90: 8; p50: 8; complete: 0

0%

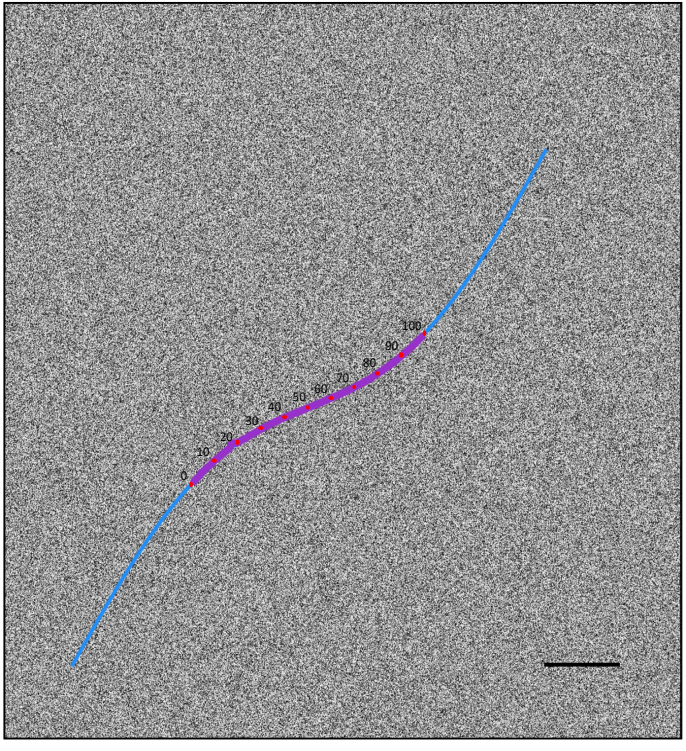


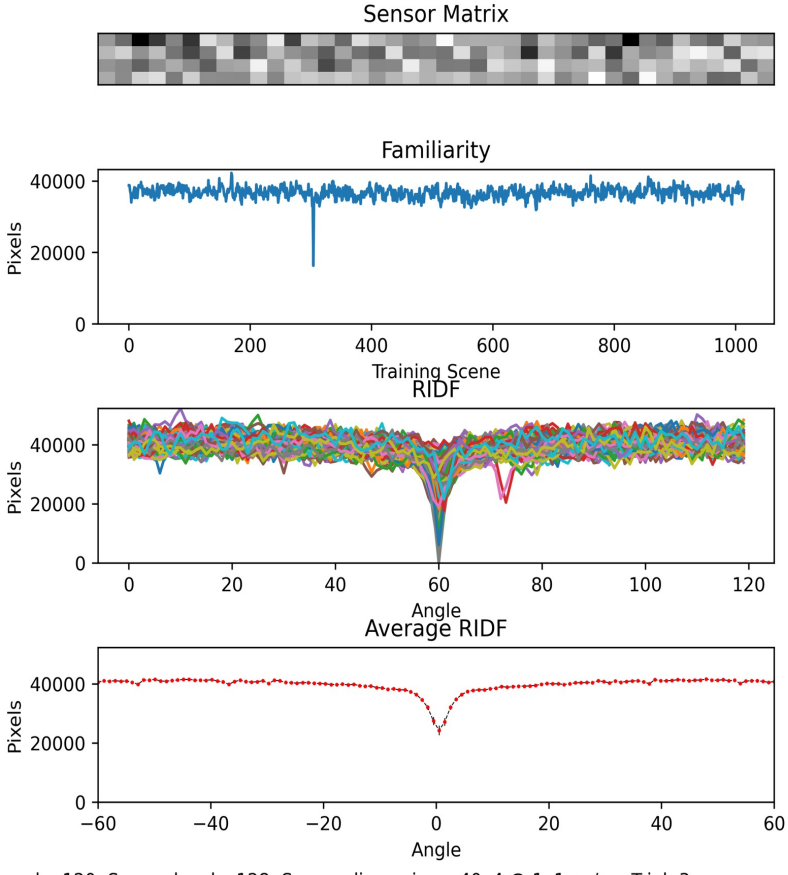


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 10477.67; RMSD/dist: 26.194; TD: -157; p90: 2; p50: 2; complete: 0

100%

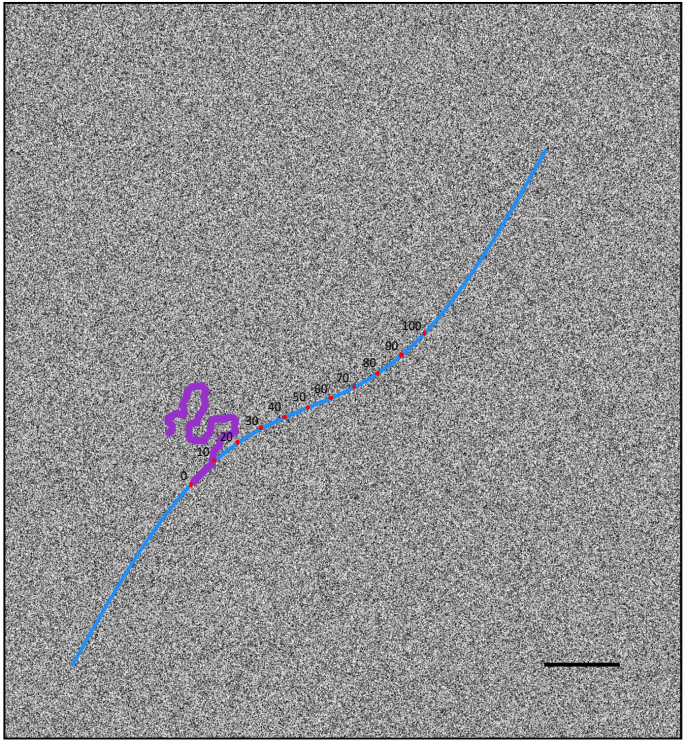


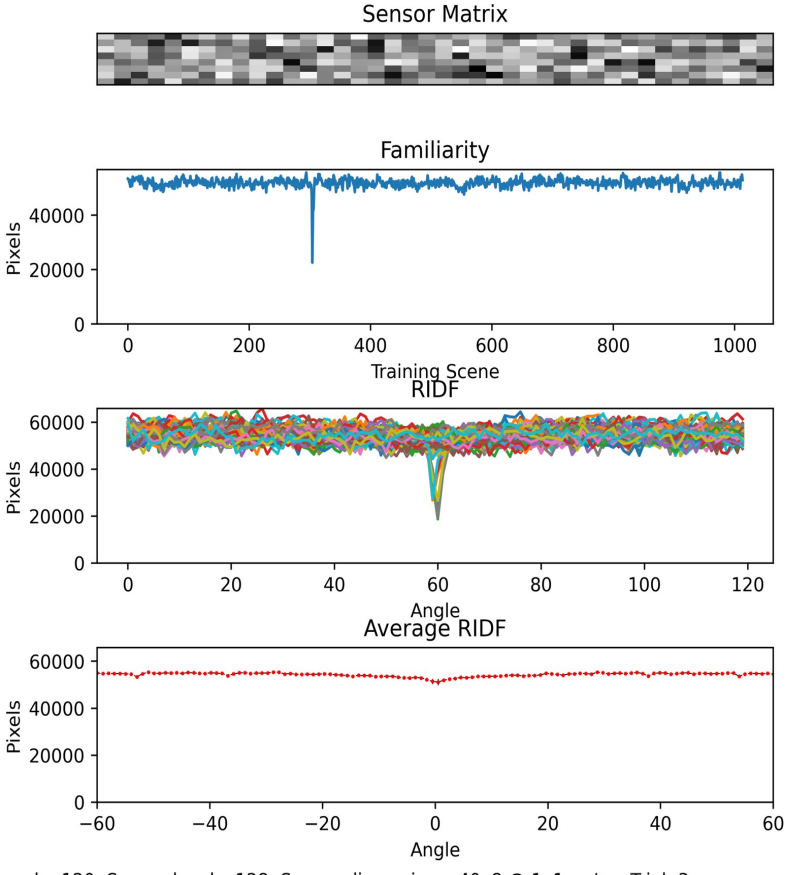


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 60.22; RMSD/dist: 0.151; TD: 11675; p90: 6; p50: 4; complete: 0

10%

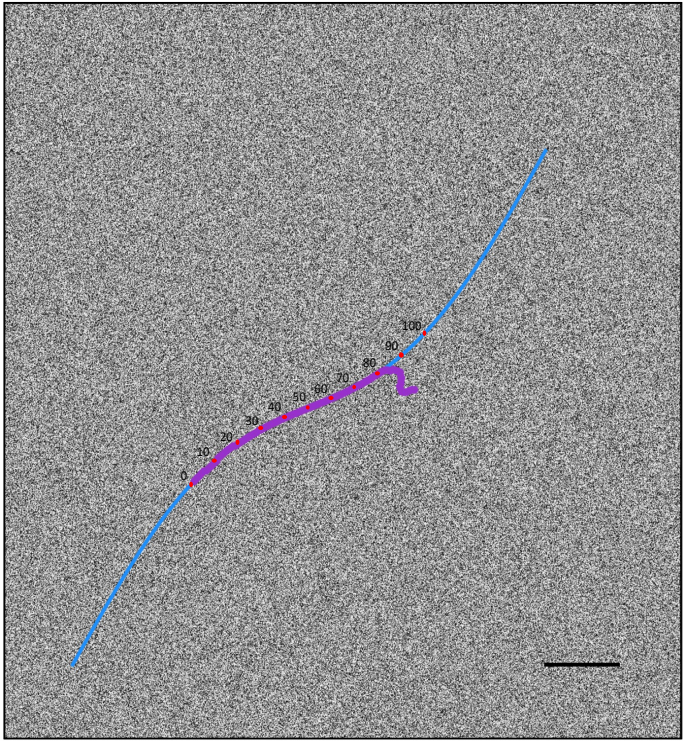


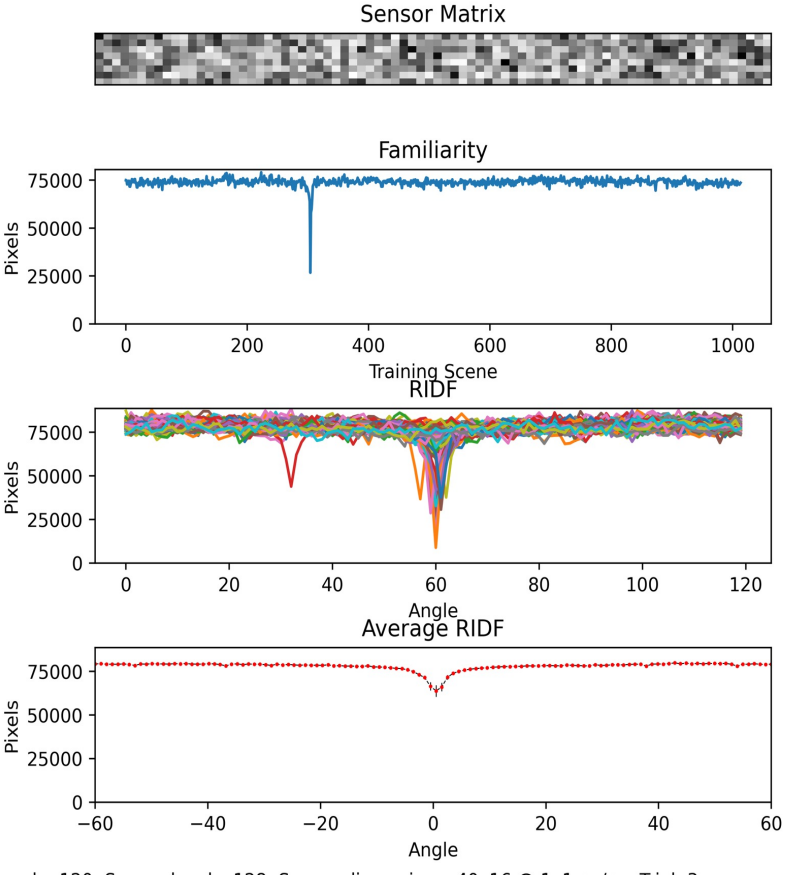


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 5040.14; RMSD/dist: 12.600; TD: 186; p90: 2; p50: 2; complete: 0

80%

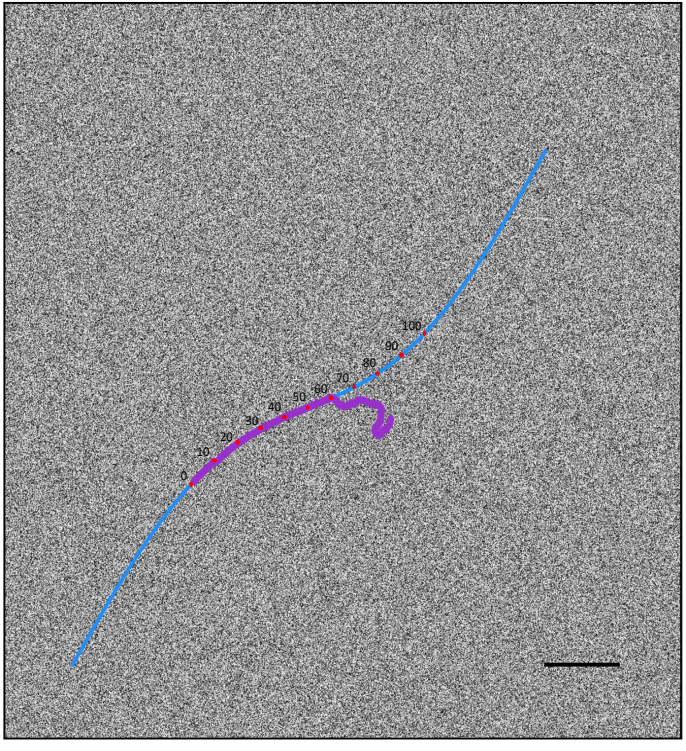


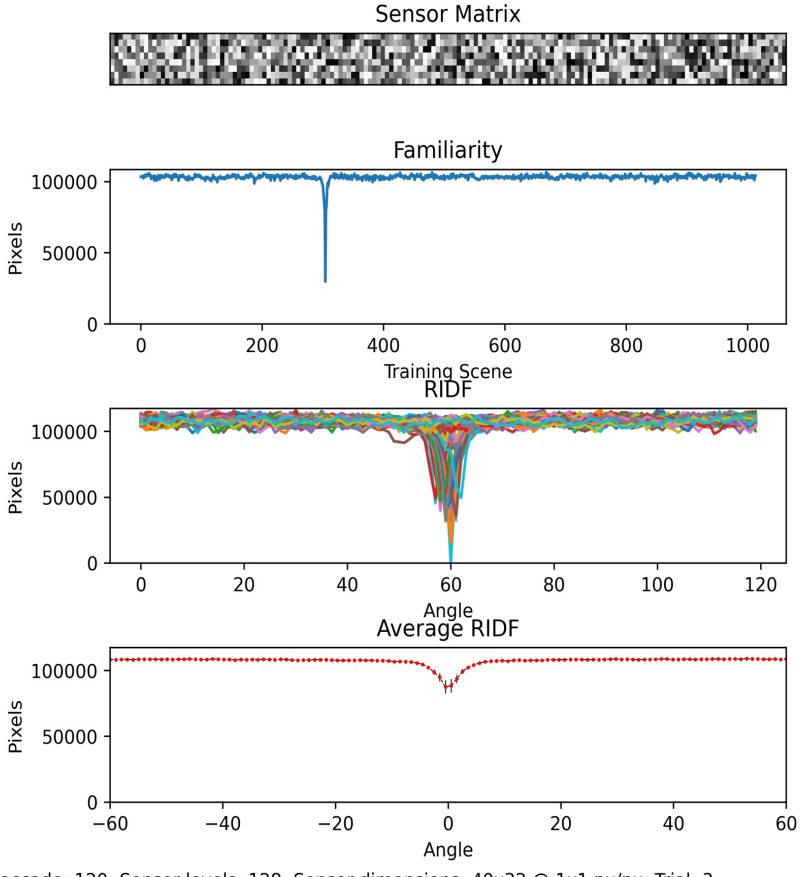


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 560.49; RMSD/dist: 1.401; TD: 10408; p90: 6; p50: 4; complete: 0

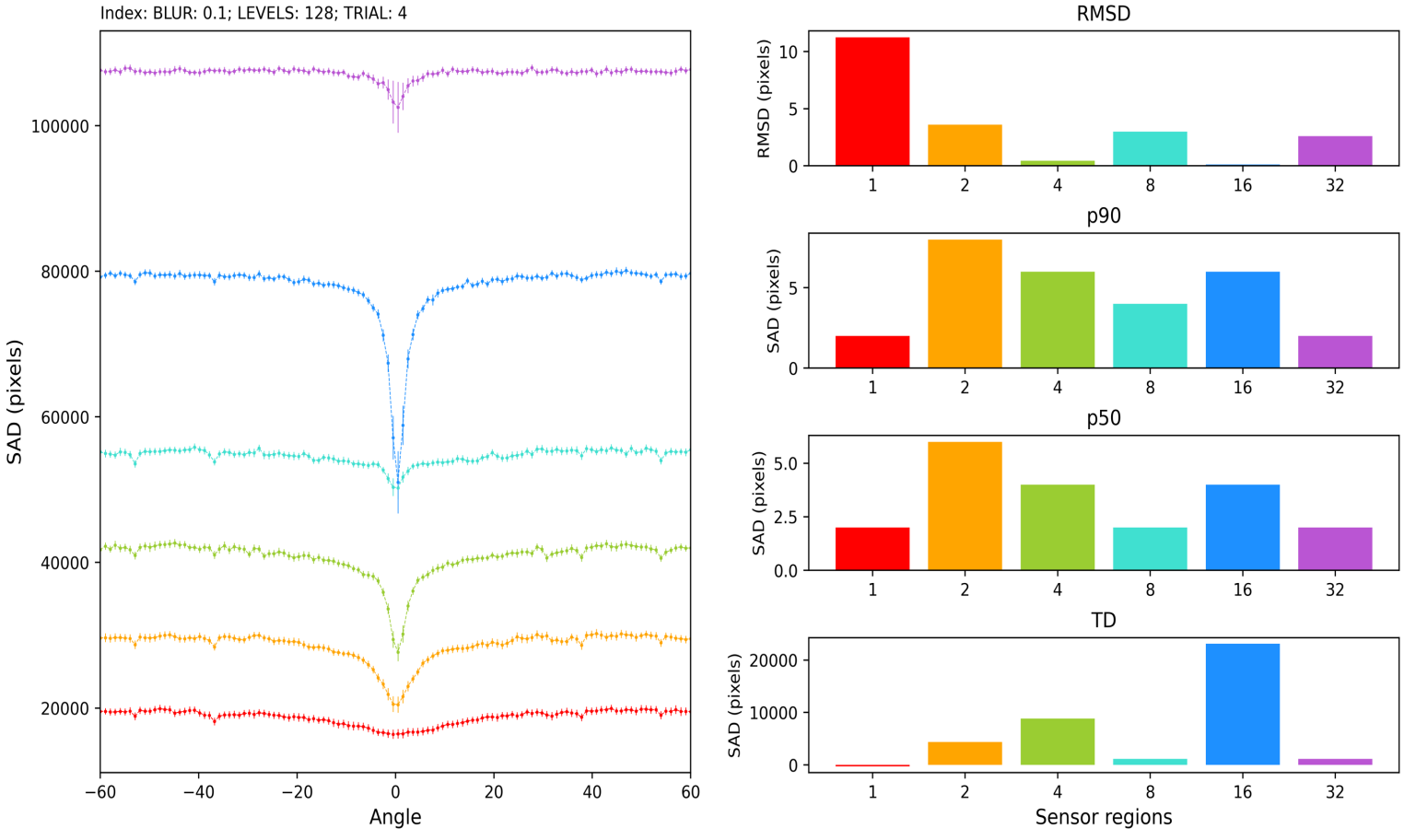
60%



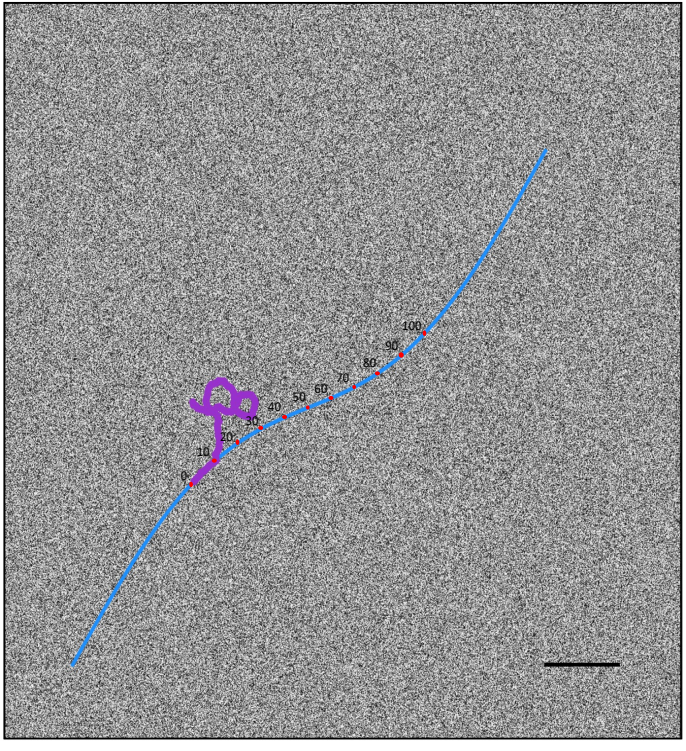


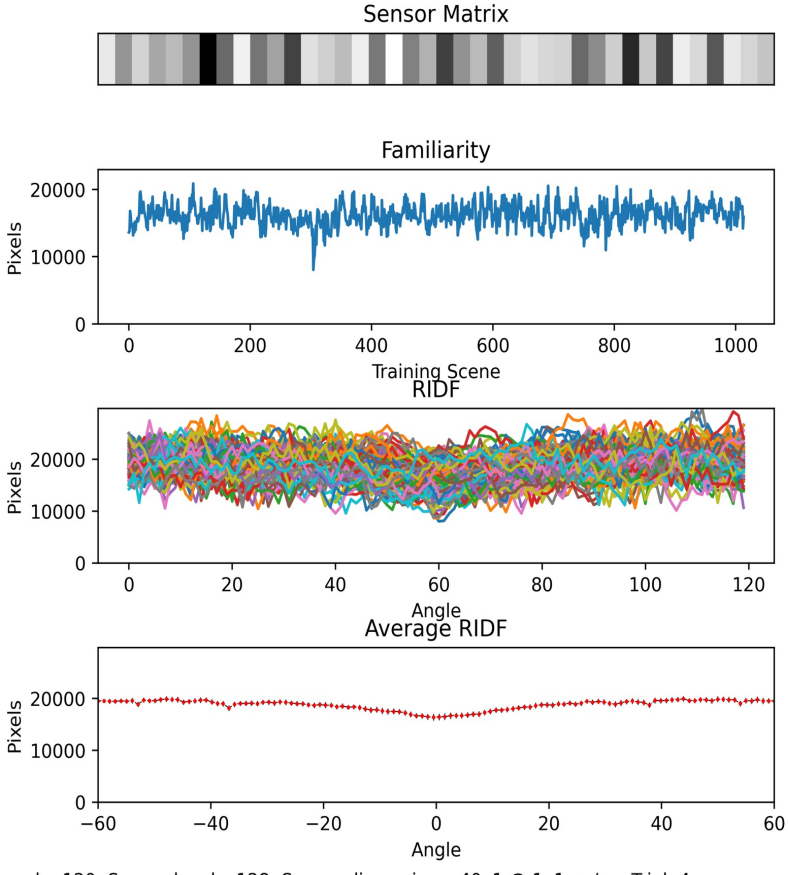
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1694.10; RMSD/dist: 4.235; TD: 16105; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 4
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

10%

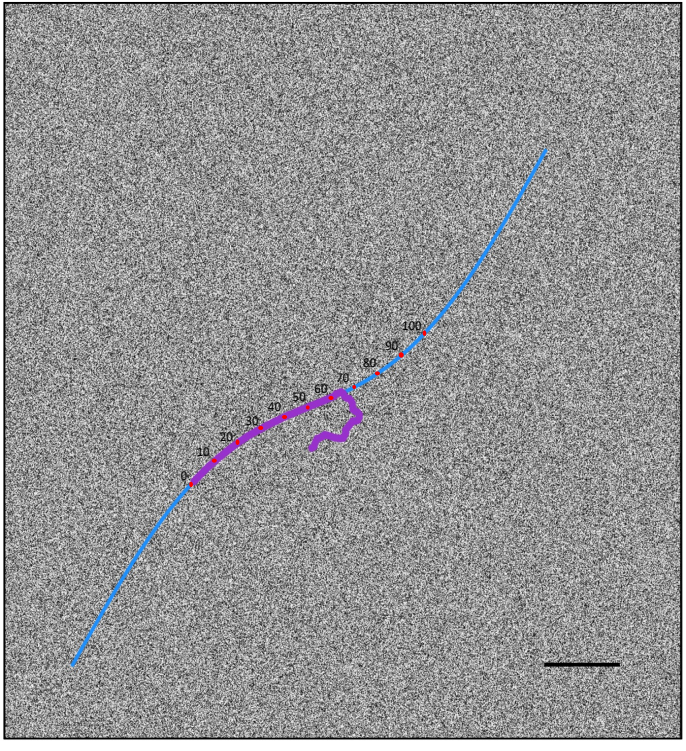


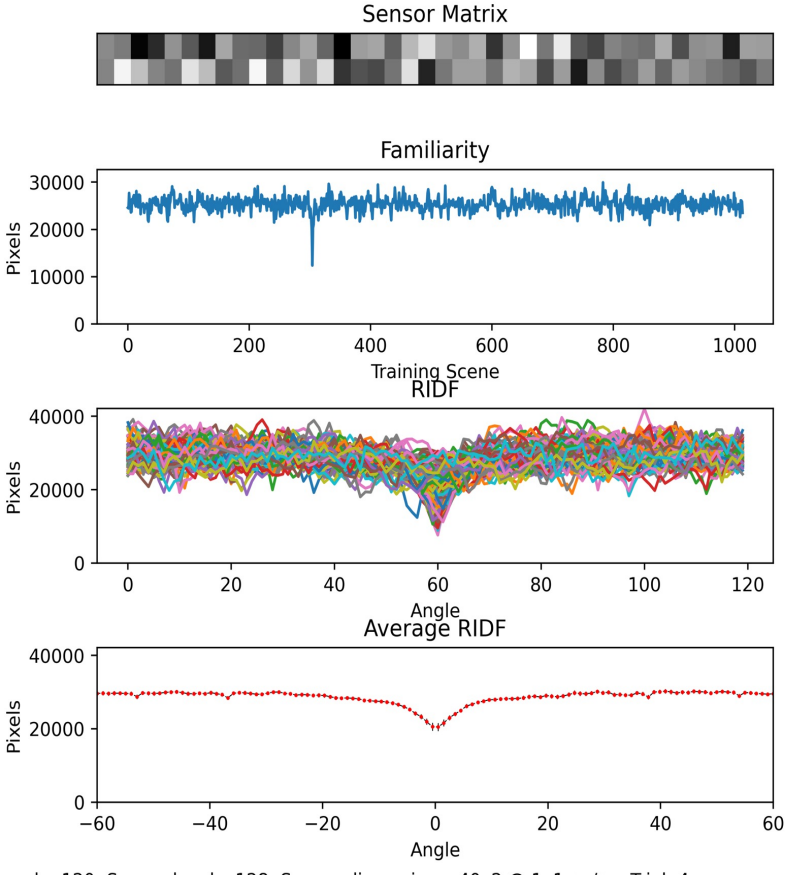


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4503.46; RMSD/dist: 11.259; TD: -266; p90: 2; p50: 2; complete: 0

60%

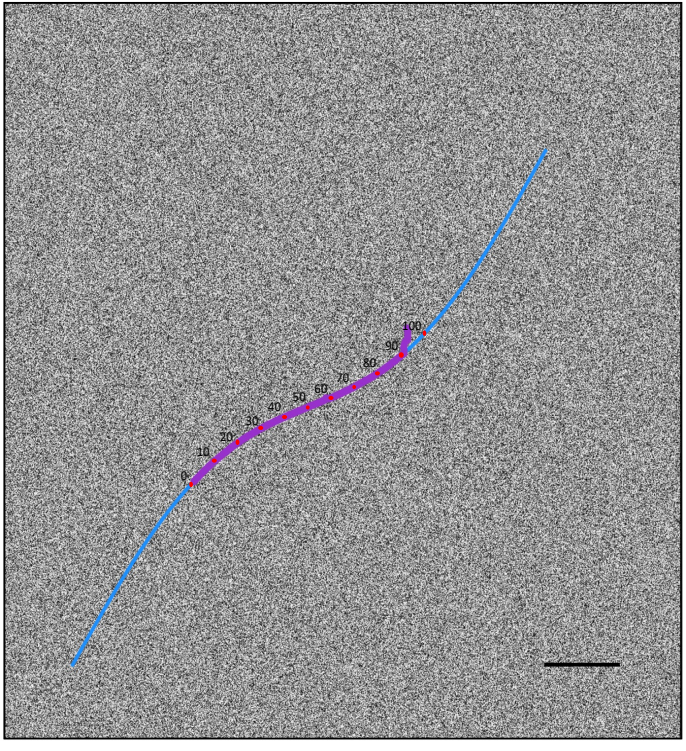


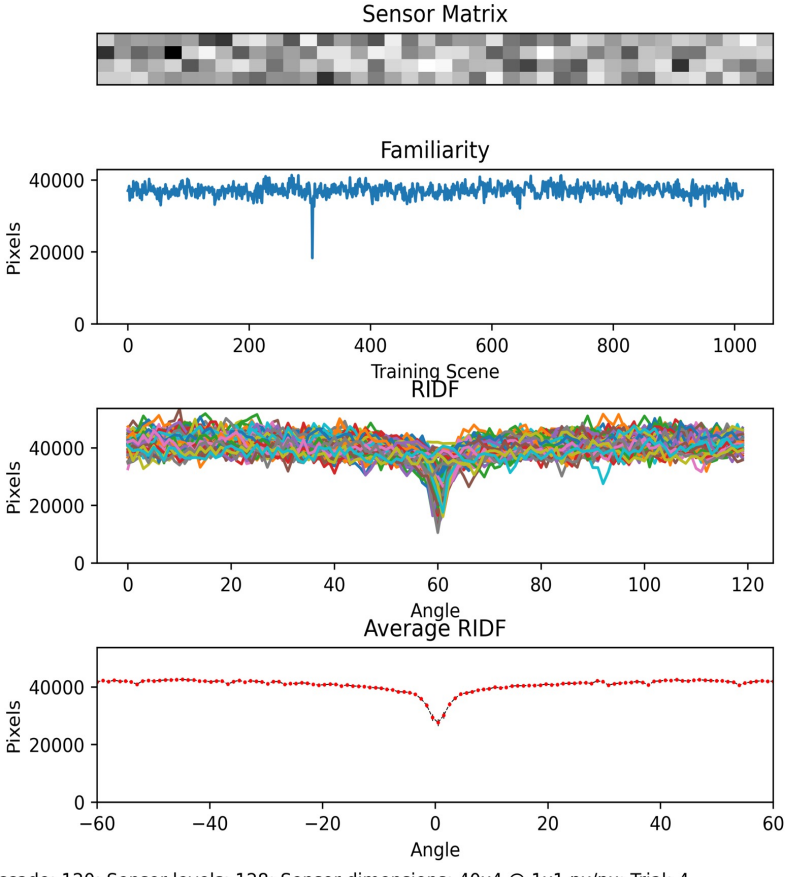


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1441.69; RMSD/dist: 3.604; TD: 4363; p90: 8; p50: 6; complete: 0

90%

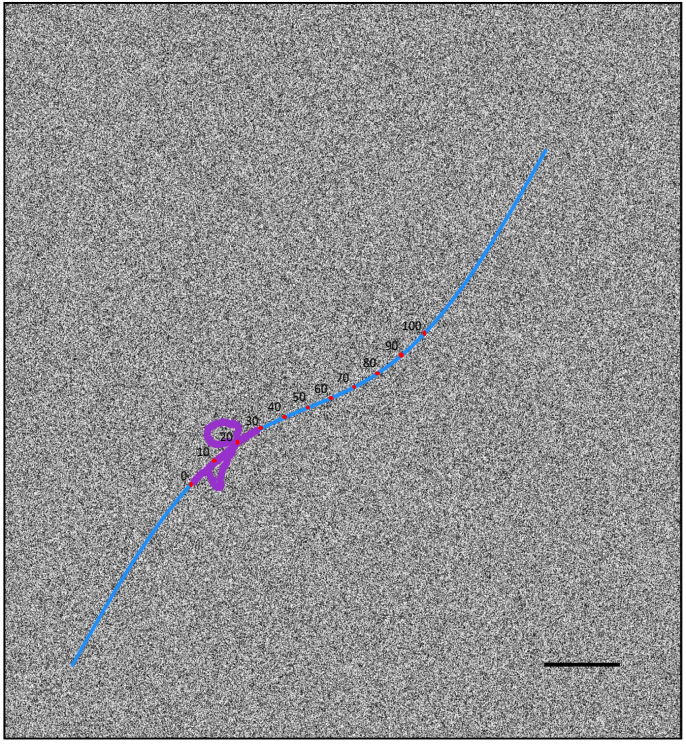


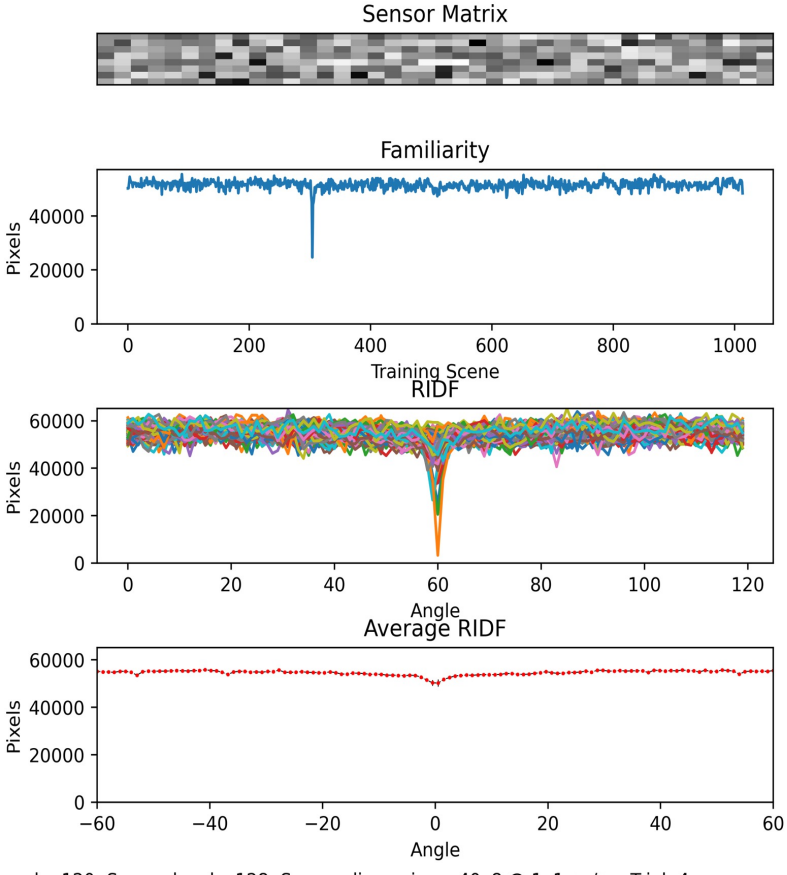


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 172.98; RMSD/dist: 0.432; TD: 8858; p90: 6; p50: 4; complete: 0

30%

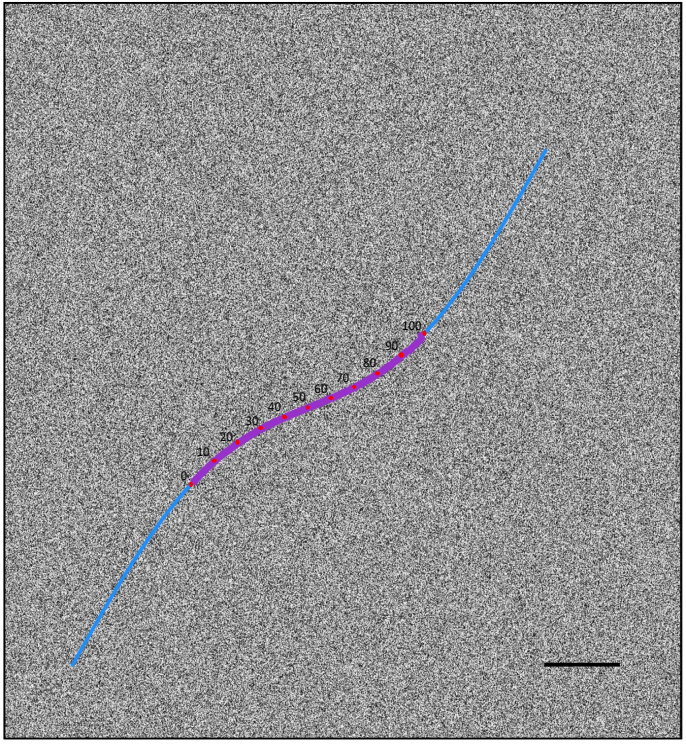


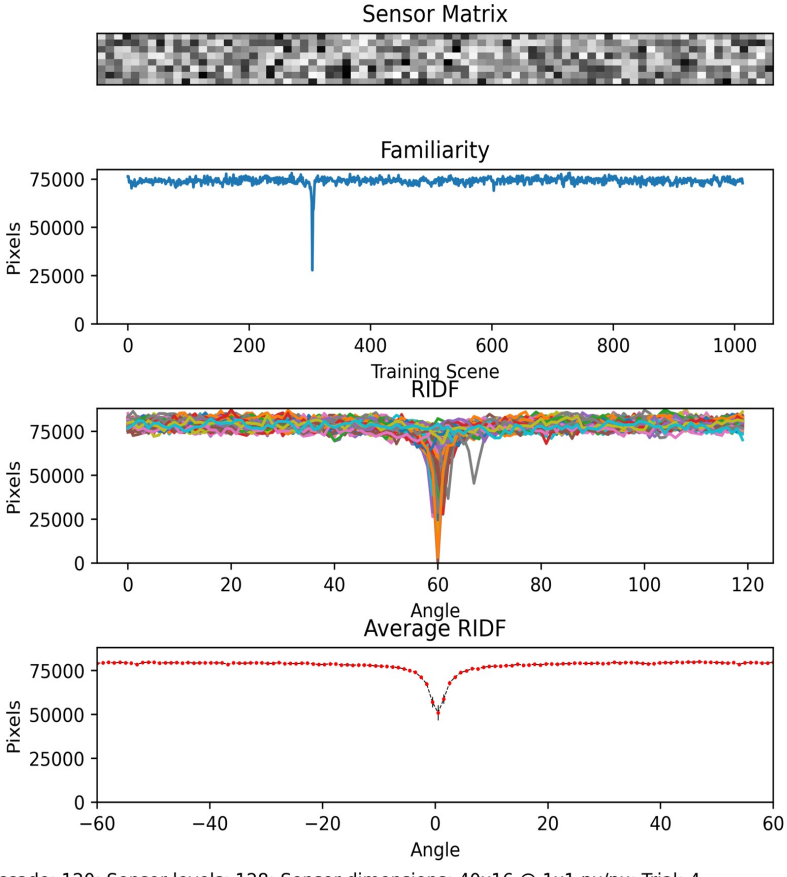


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1193.44; RMSD/dist: 2.984; TD: 1143; p90: 4; p50: 2; complete: 0

100%

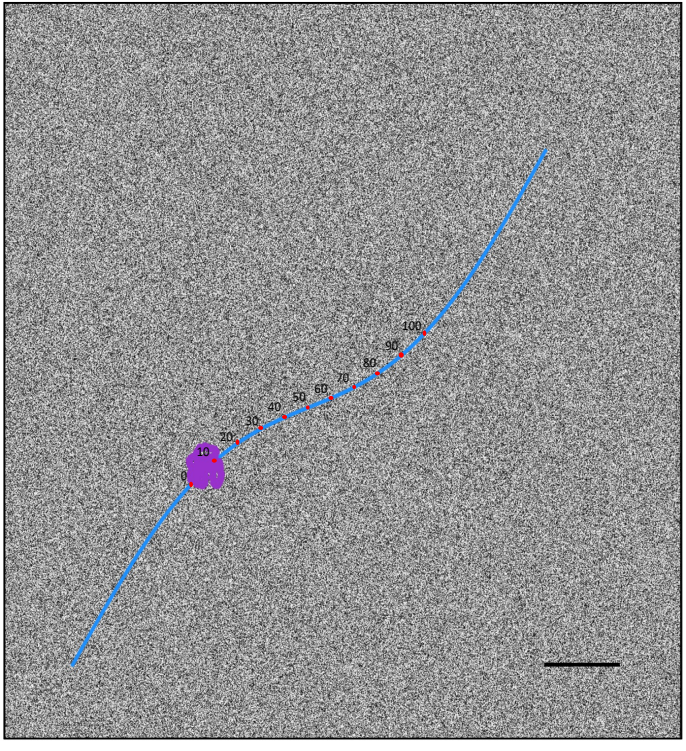


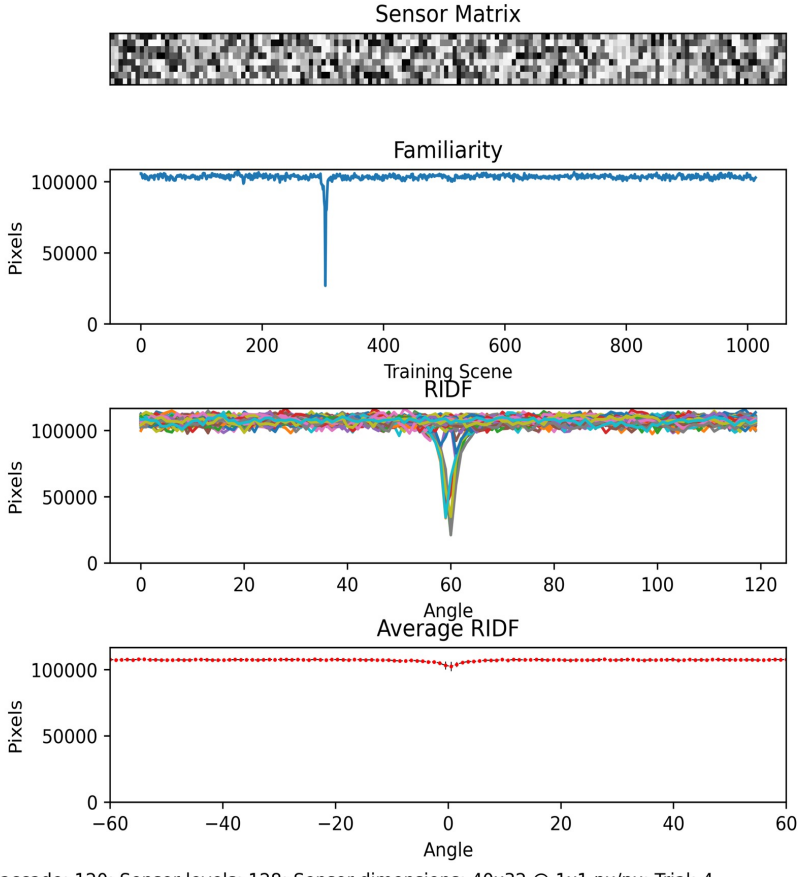


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 44.65; RMSD/dist: 0.112; TD: 23097; p90: 6; p50: 4; complete: 0

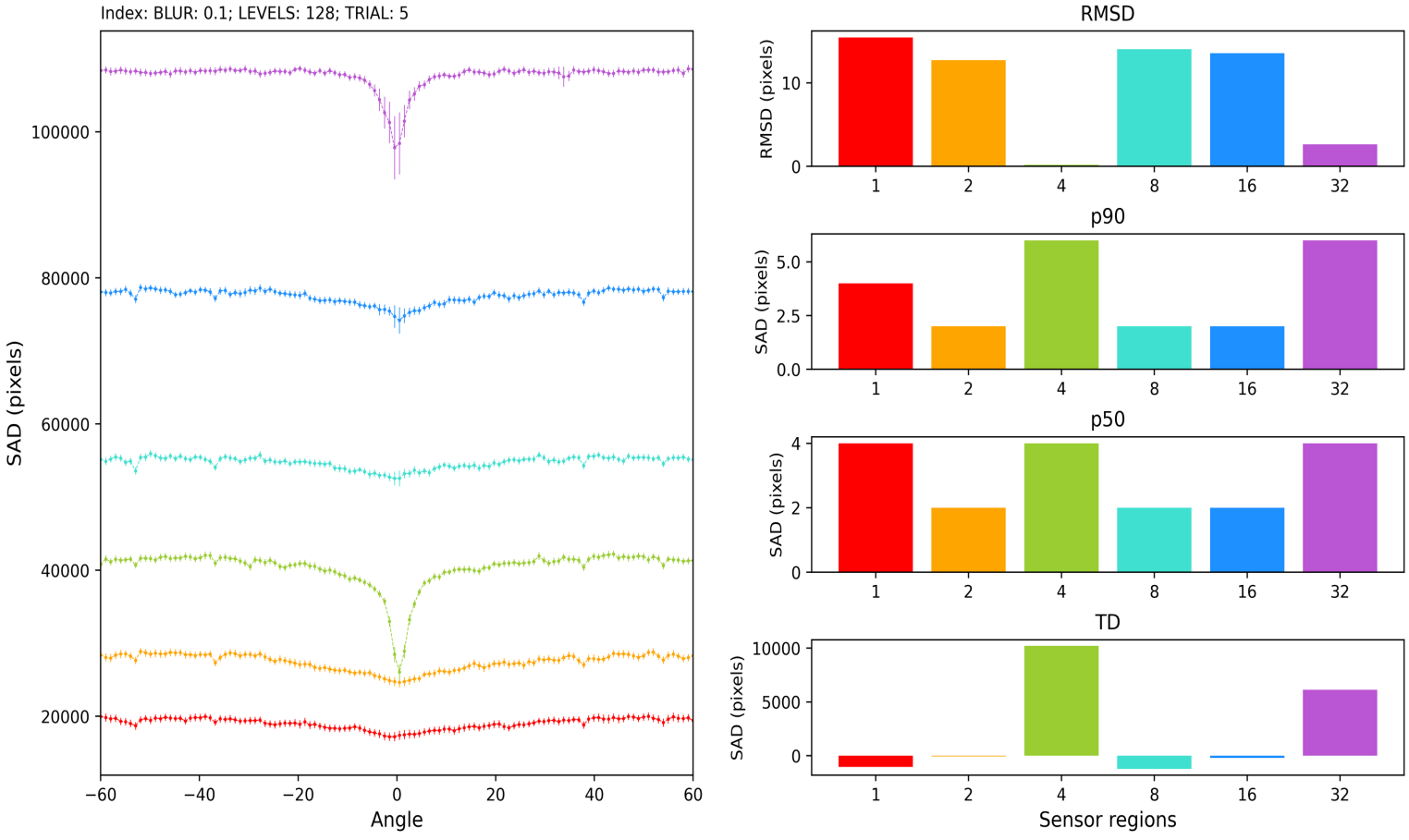
0%



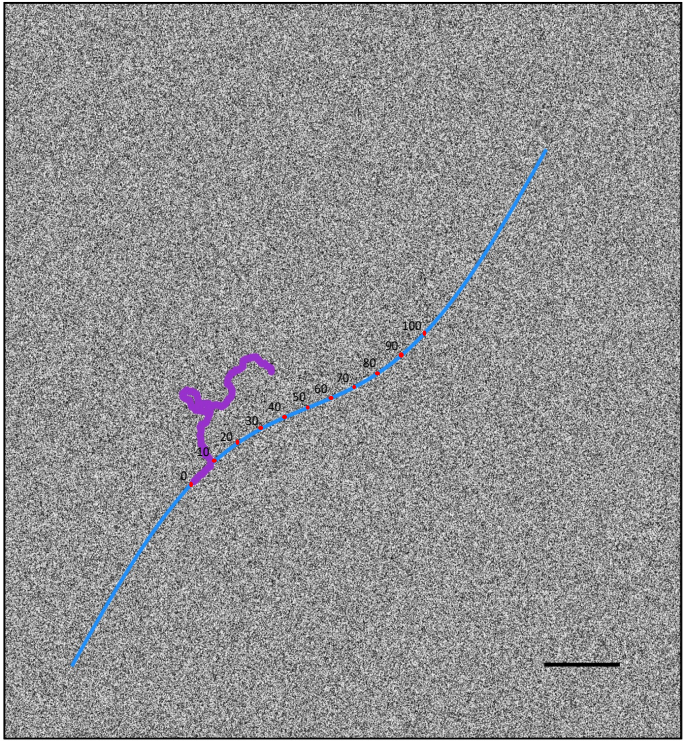


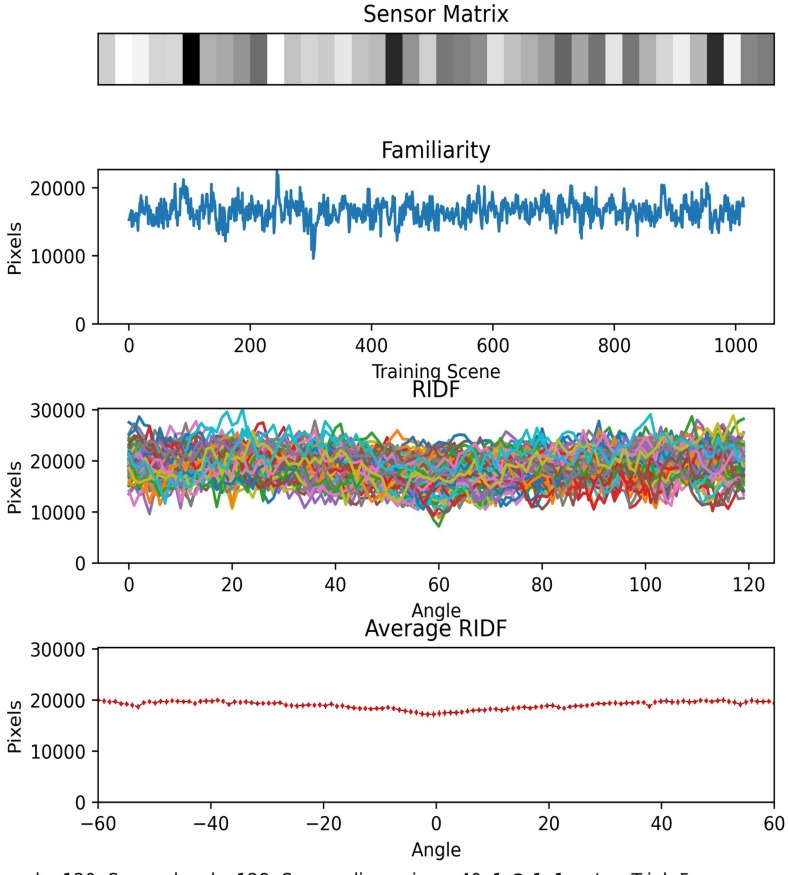
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1037.39; RMSD/dist: 2.593; TD: 1134; p90: 2; p50: 2; complete: 0


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 5
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
4
2
0
TD
10000
5000
Sensor regions

10%

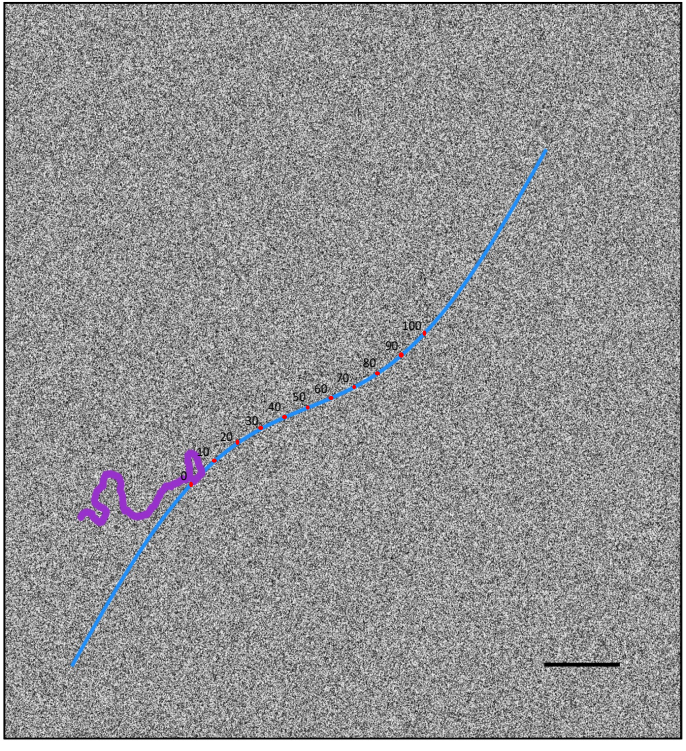


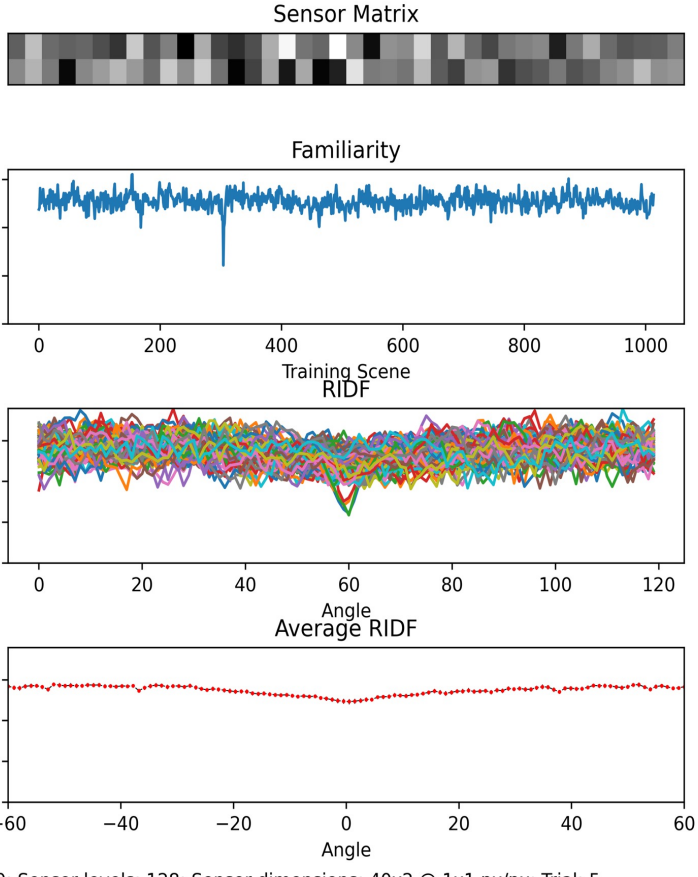


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 6177.59; RMSD/dist: 15.444; TD: -1046; p90: 4; p50: 4; complete: 0

0%

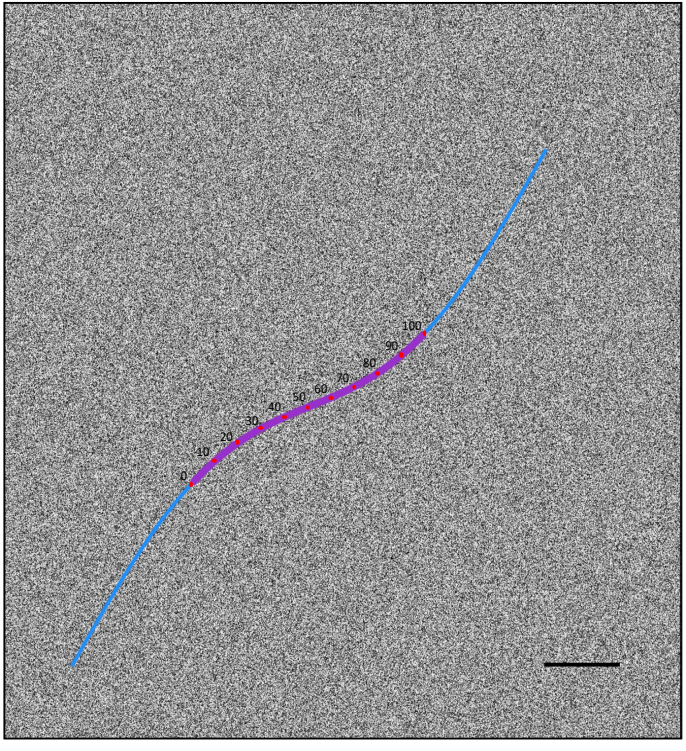


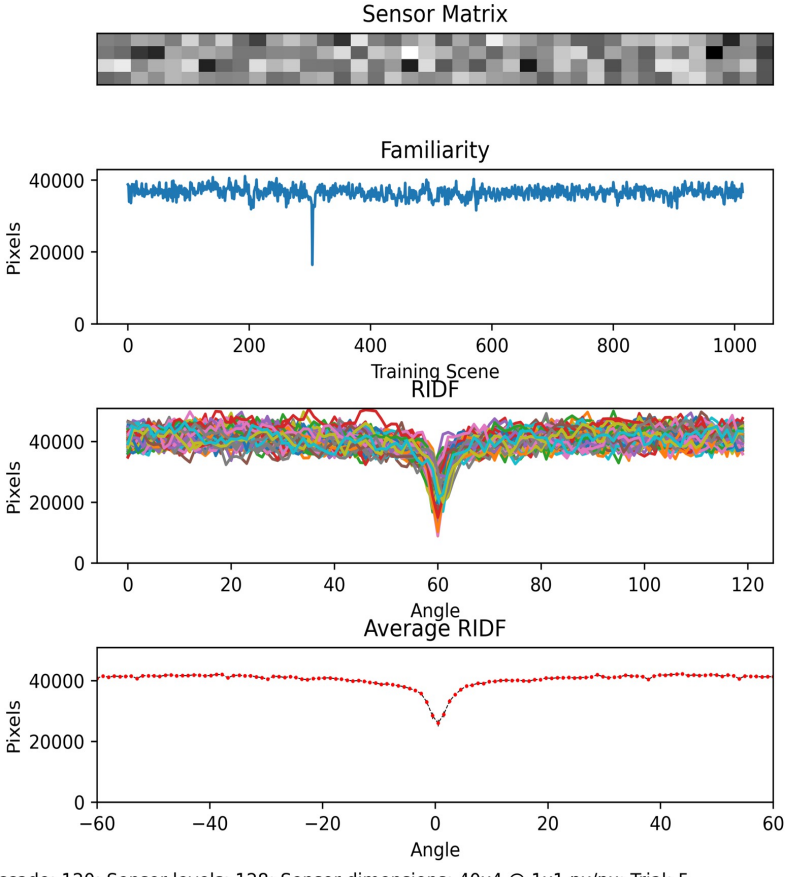


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5085.76; RMSD/dist: 12.714; TD: -66; p90: 2; p50: 2; complete: 0

100%

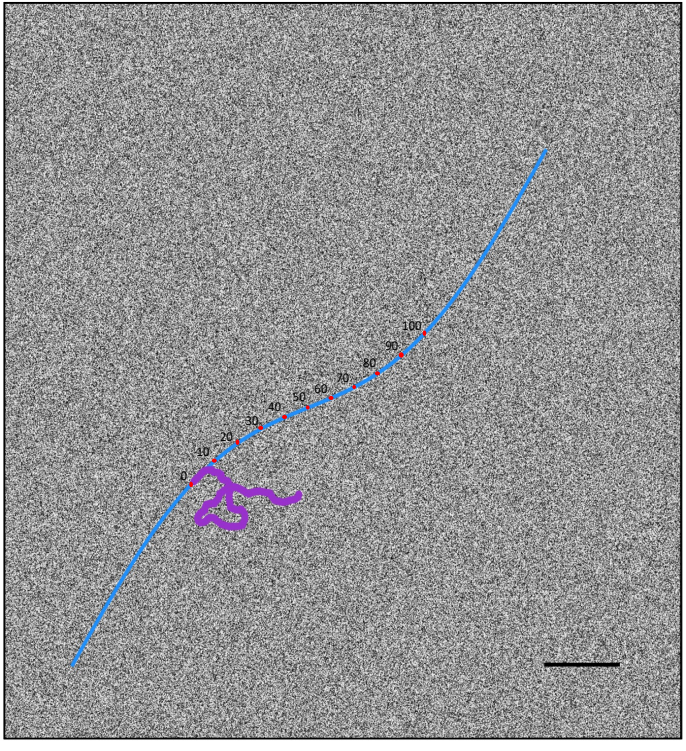


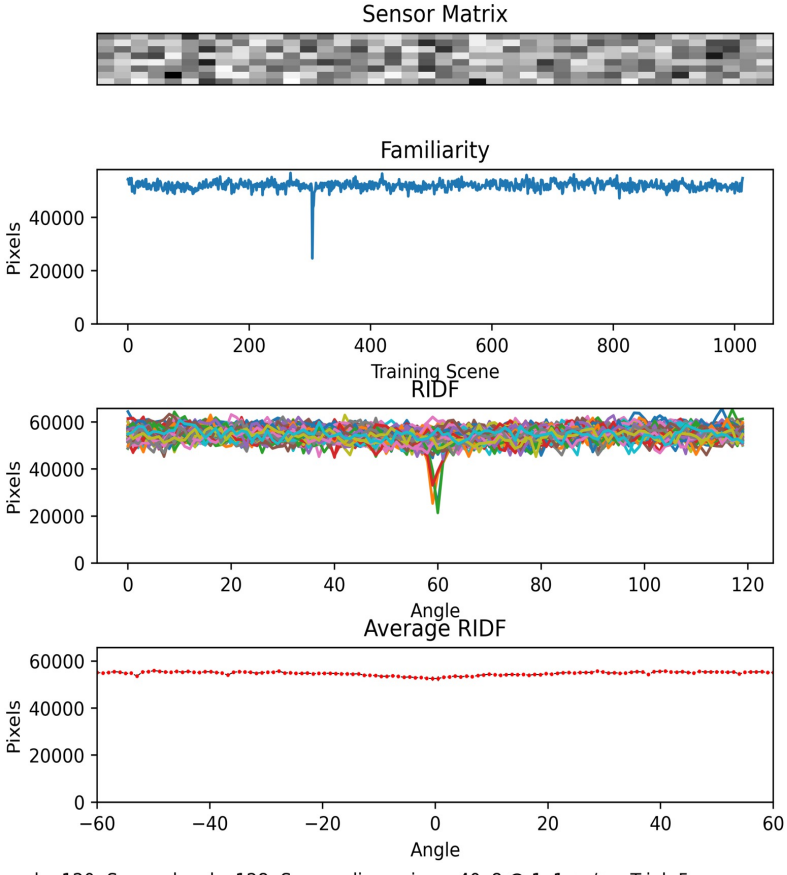


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 66.36; RMSD/dist: 0.166; TD: 10197; p90: 6; p50: 4; complete: 0

0%

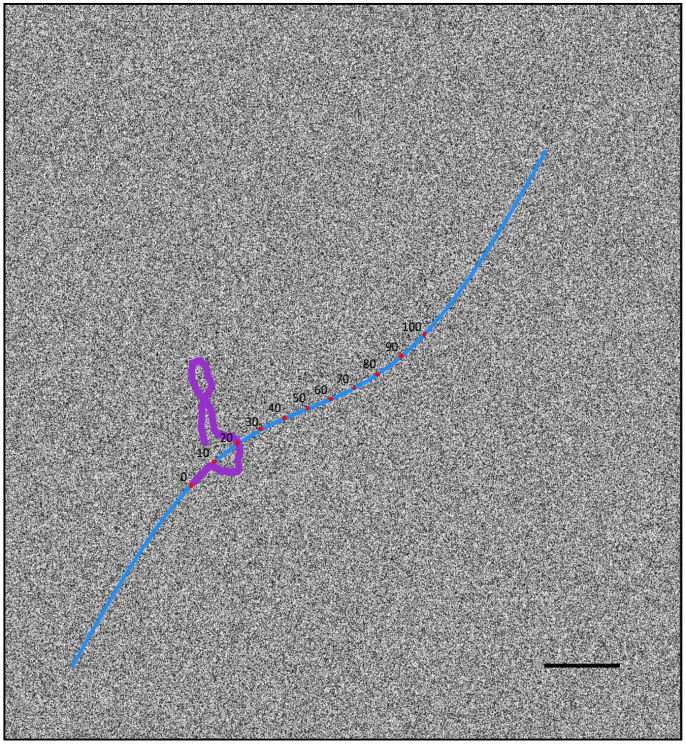


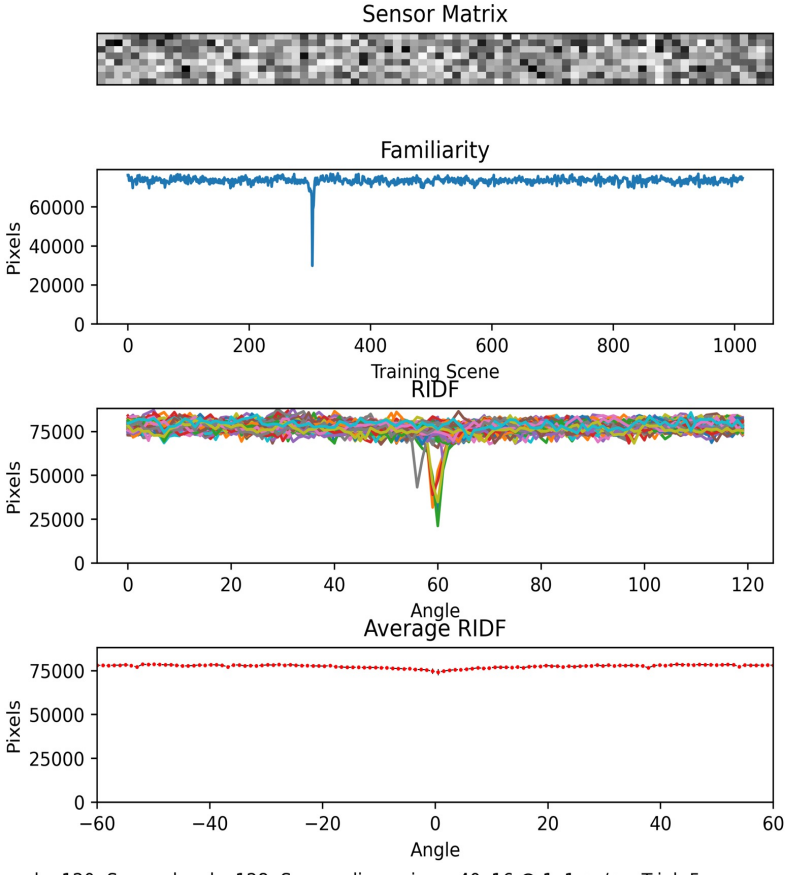


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5605.67; RMSD/dist: 14.014; TD: -1223; p90: 2; p50: 2; complete: 0

0%

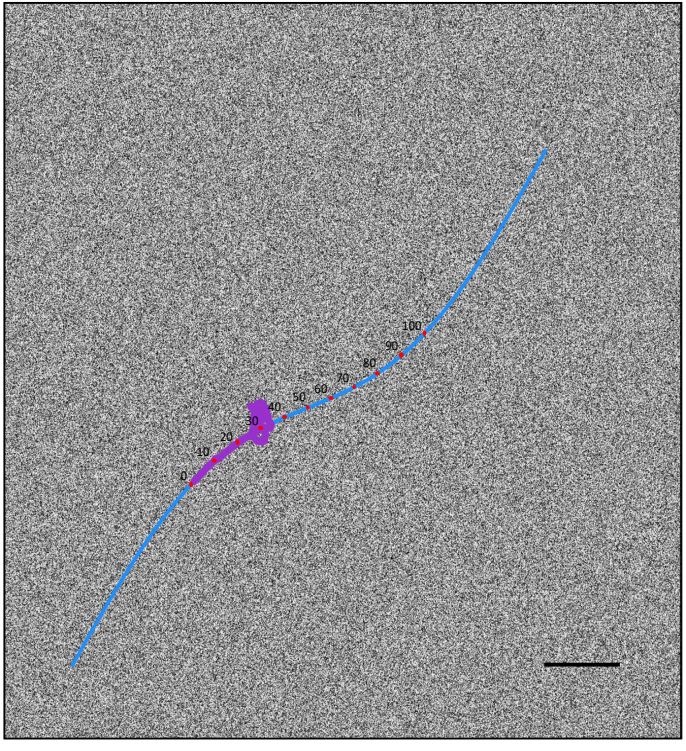


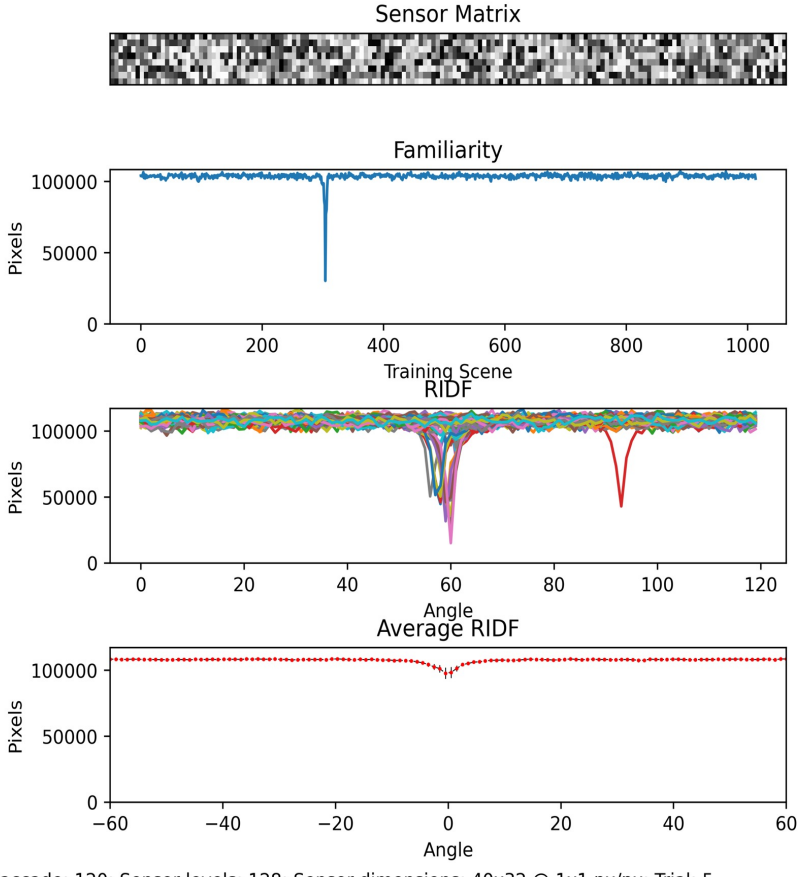


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5415.37; RMSD/dist: 13.538; TD: -202; p90: 2; p50: 2; complete: 0

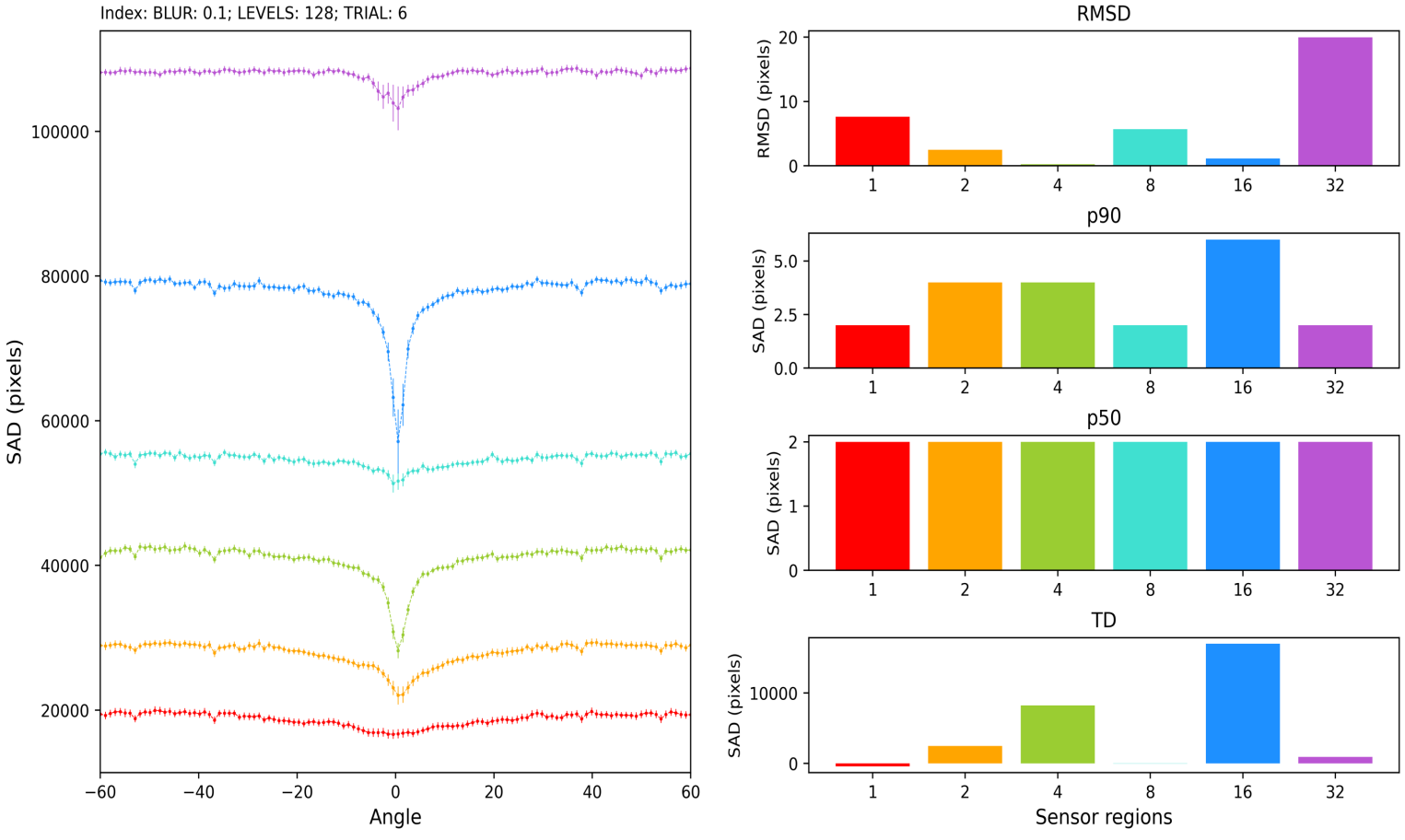
30%



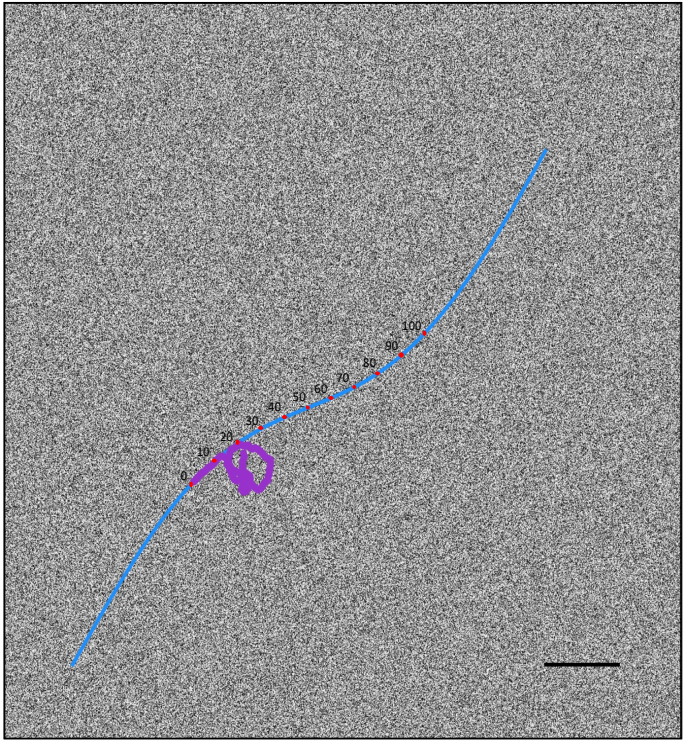


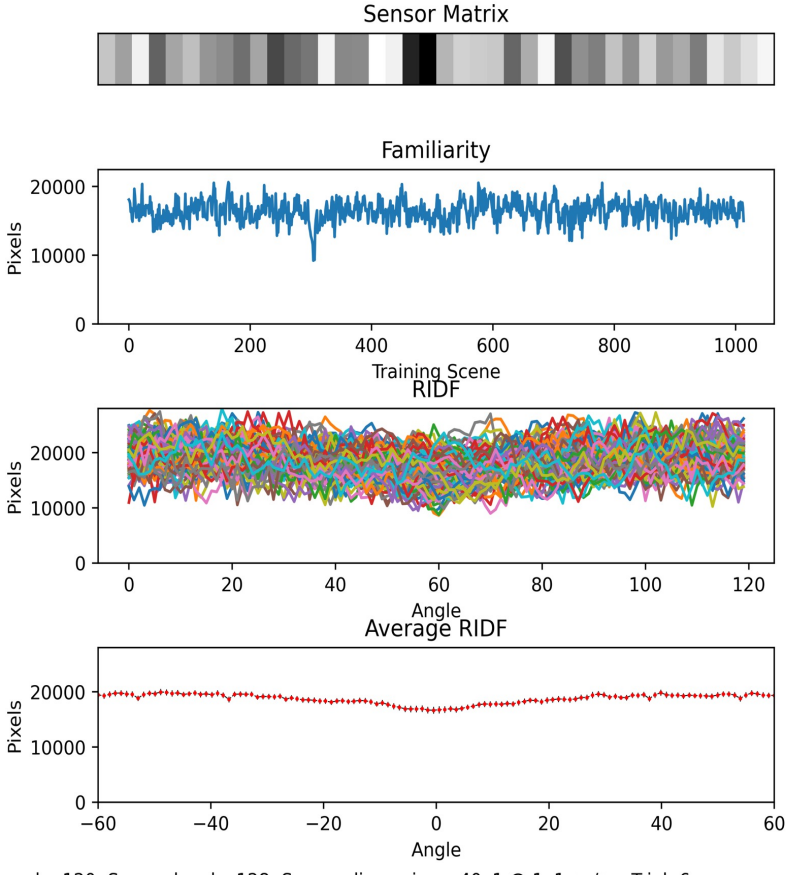
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1047.25; RMSD/dist: 2.618; TD: 6131; p90: 6; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 6
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5.0
2.5
0.0
p50
2
1
TD
10000
Sensor regions

10%

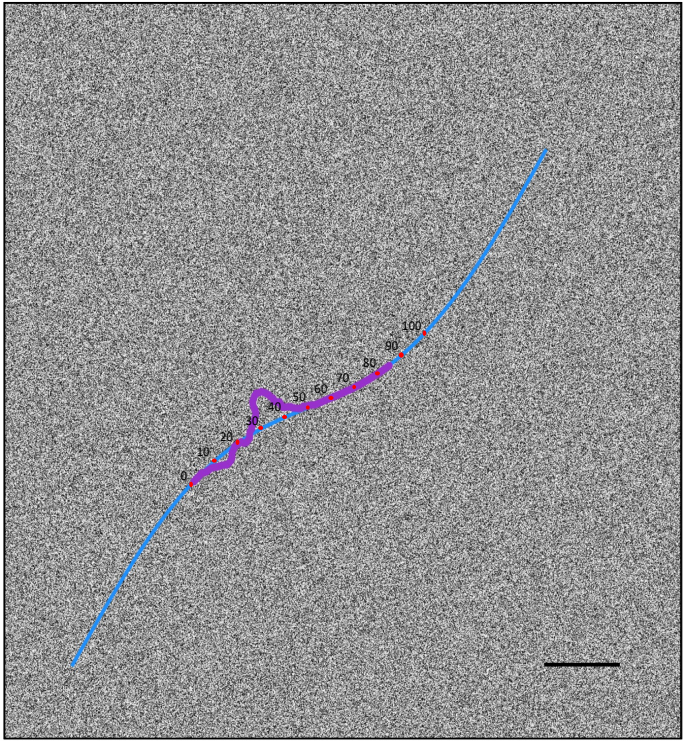


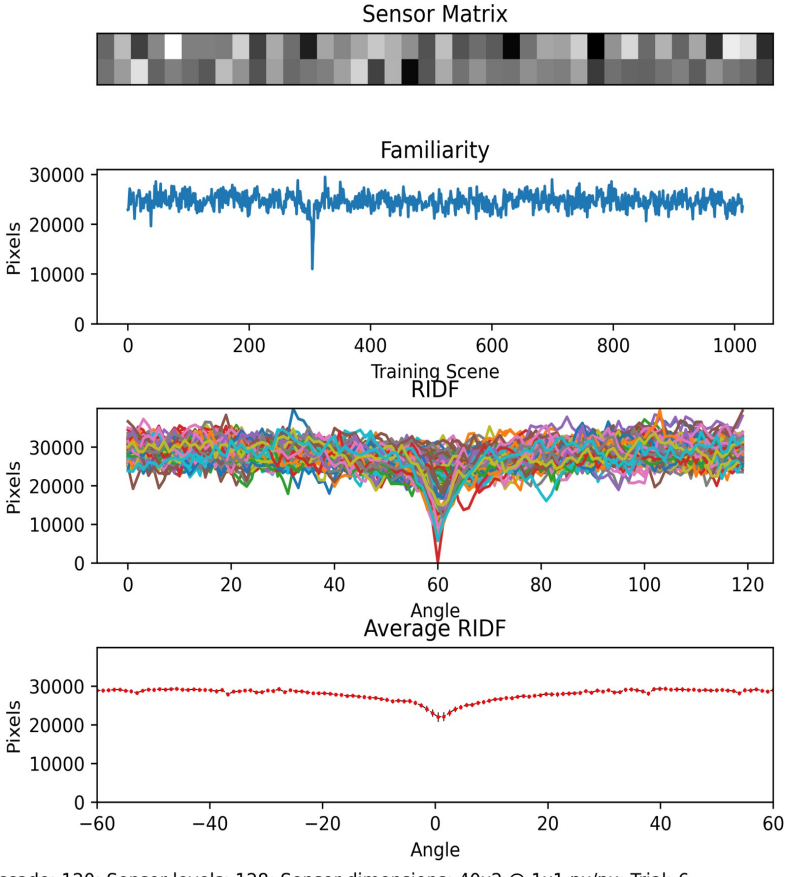


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3051.23; RMSD/dist: 7.628; TD: -432; p90: 2; p50: 2; complete: 0

40%

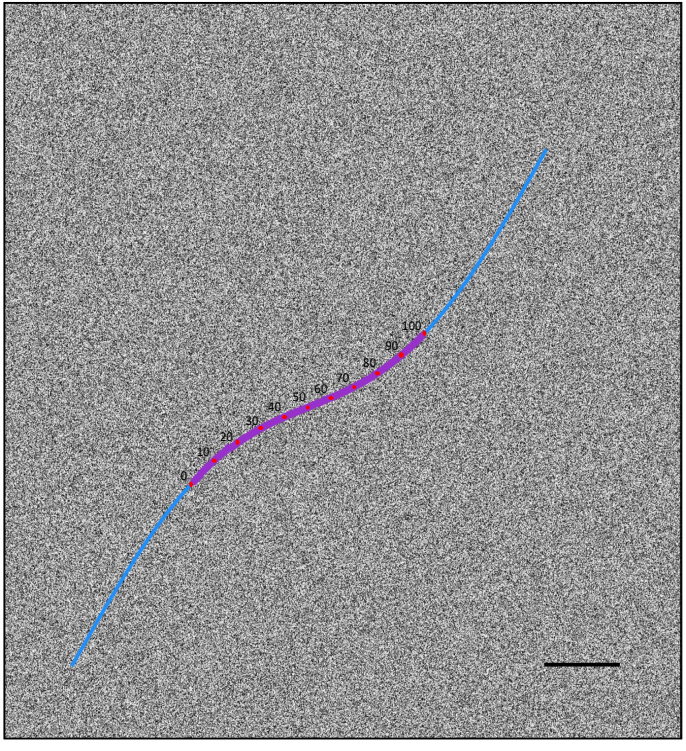


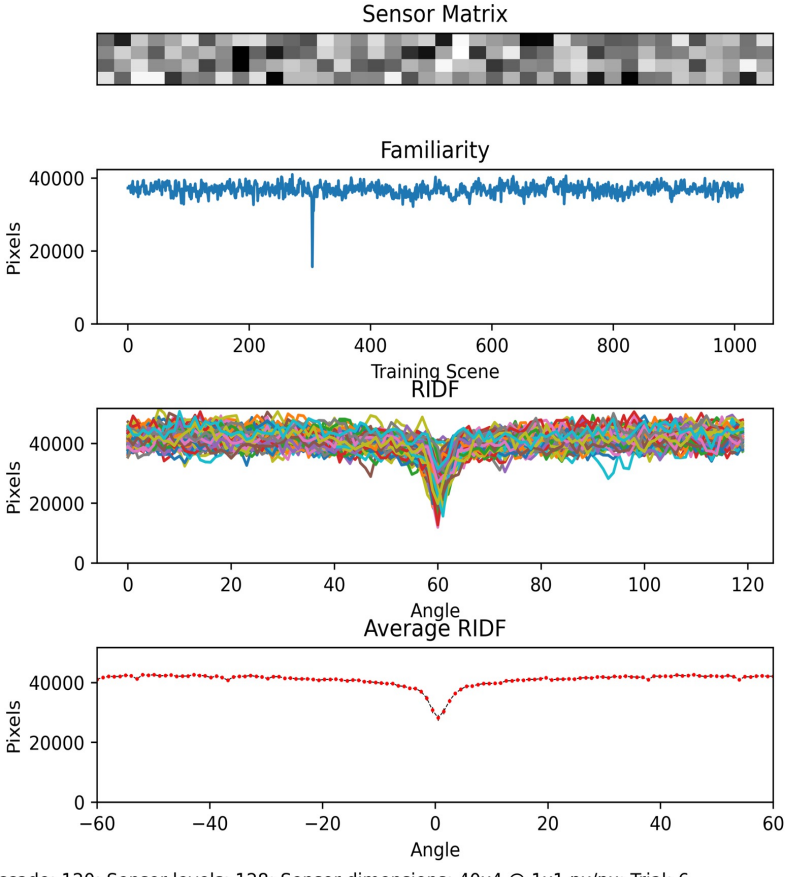


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 993.68; RMSD/dist: 2.484; TD: 2476; p90: 4; p50: 2; complete: 0

100%

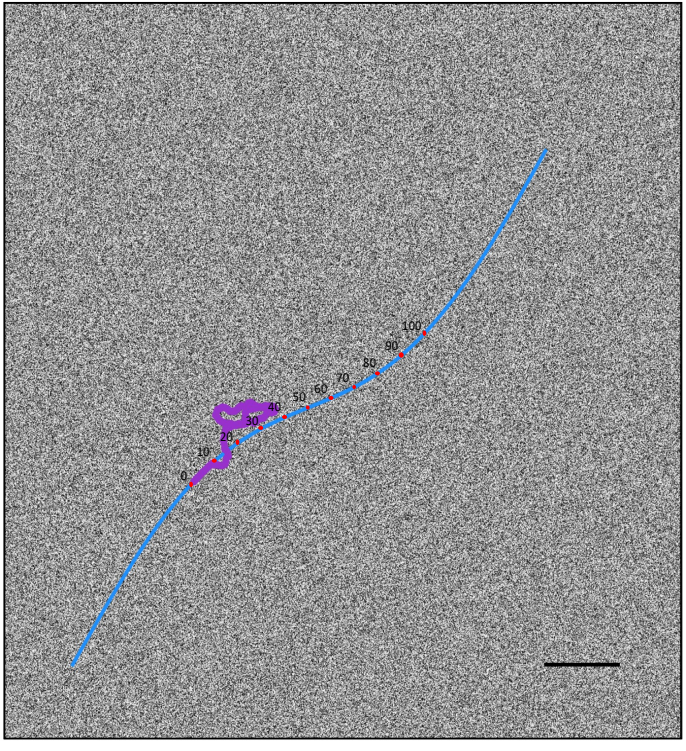


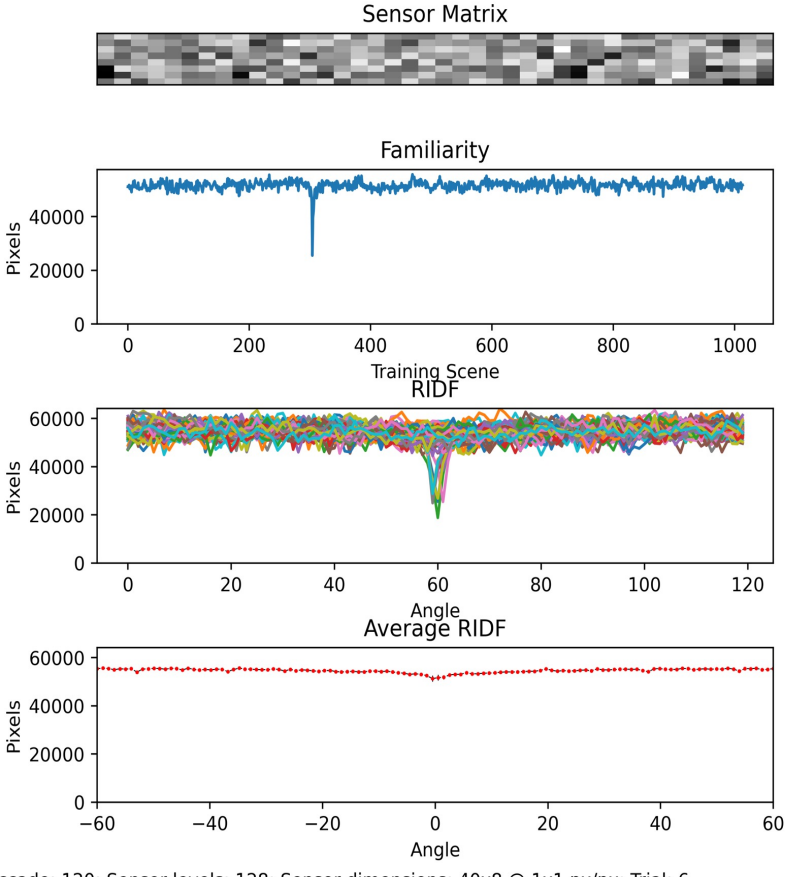


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 87.63; RMSD/dist: 0.219; TD: 8229; p90: 4; p50: 2; complete: 0

10%

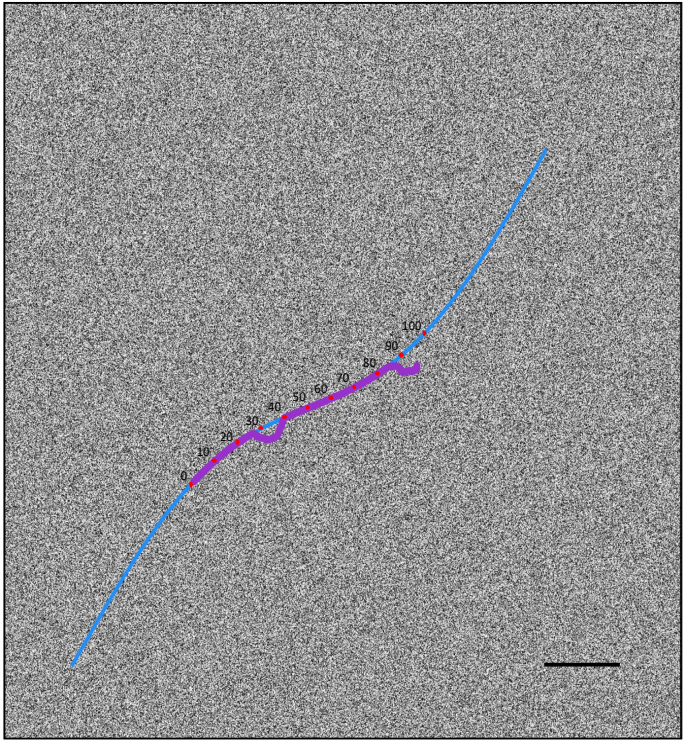


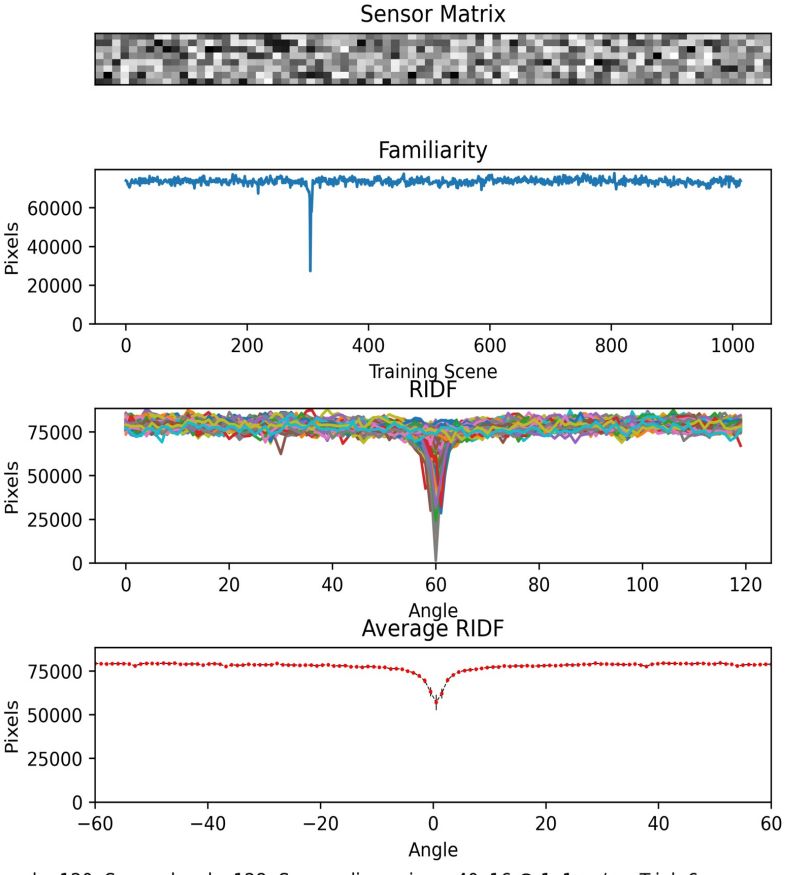


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2276.41; RMSD/dist: 5.691; TD: -61; p90: 2; p50: 2; complete: 0

70%

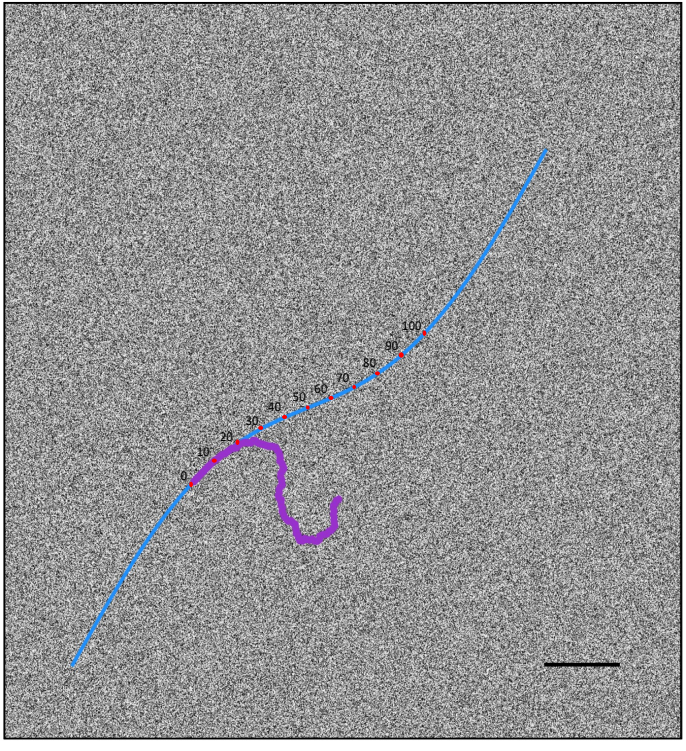


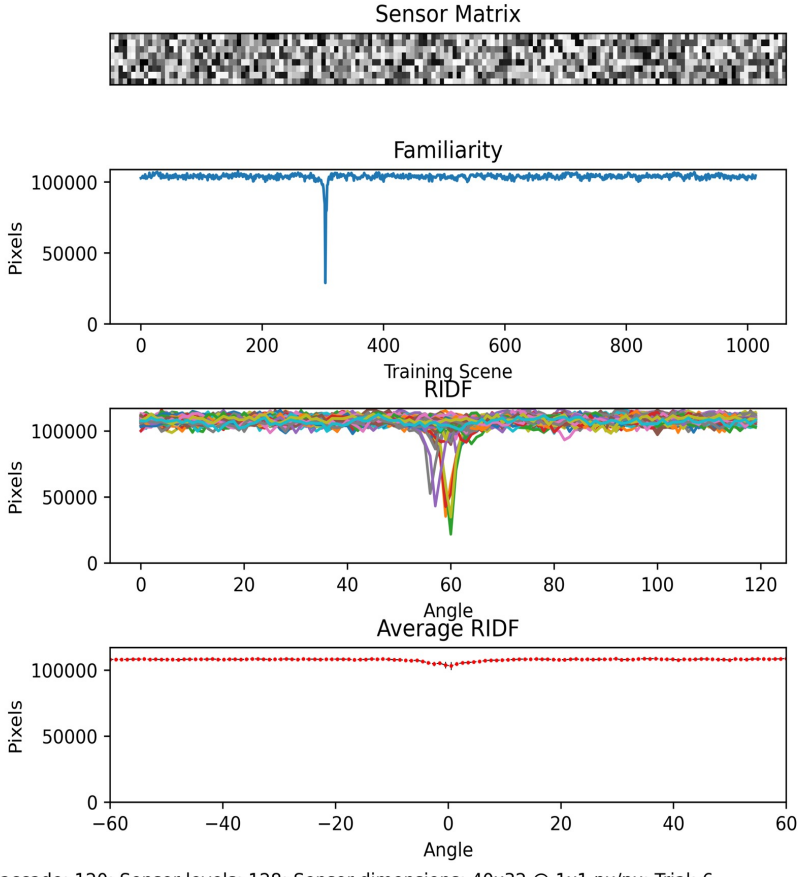


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 448.11; RMSD/dist: 1.120; TD: 16979; p90: 6; p50: 2; complete: 0

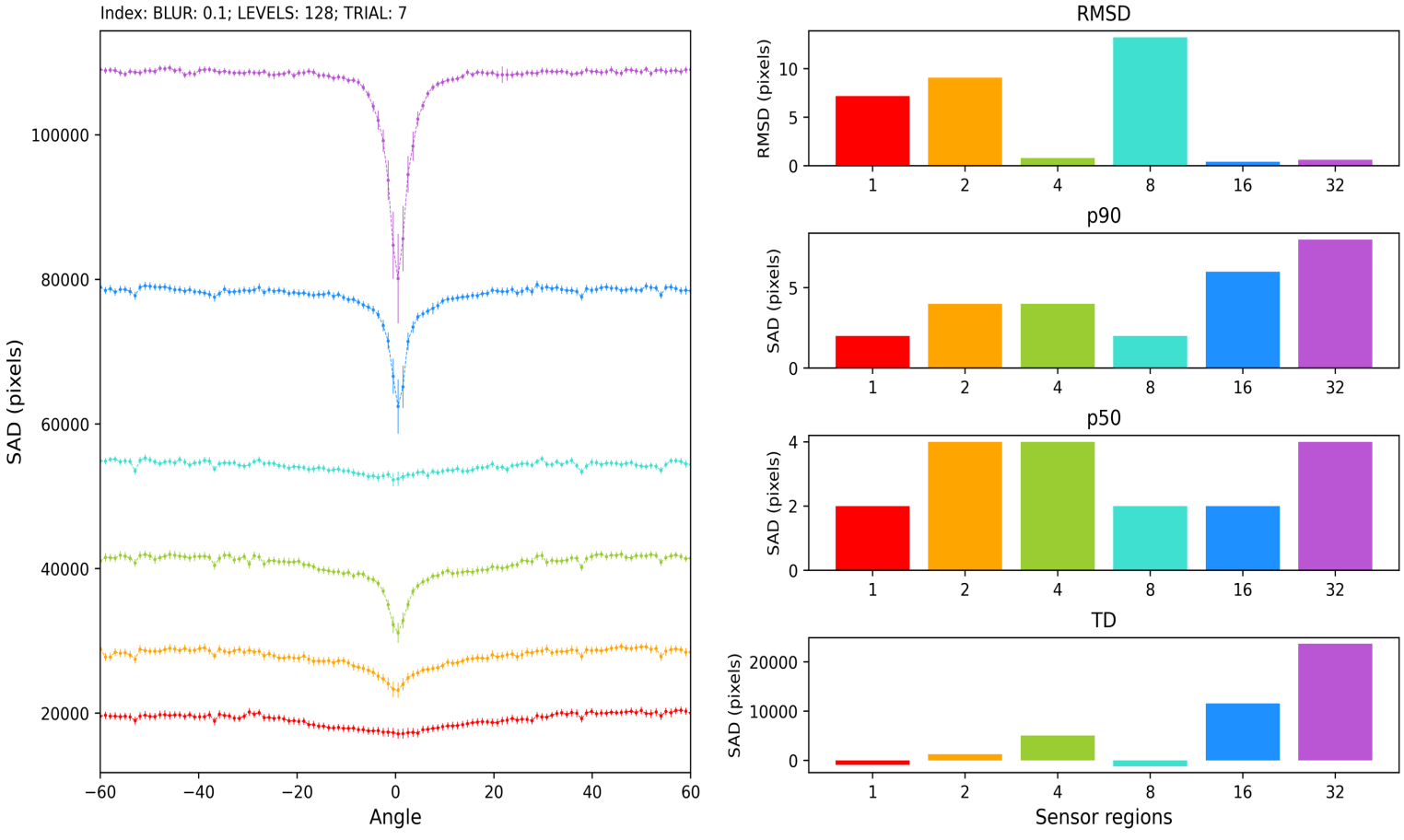
20%



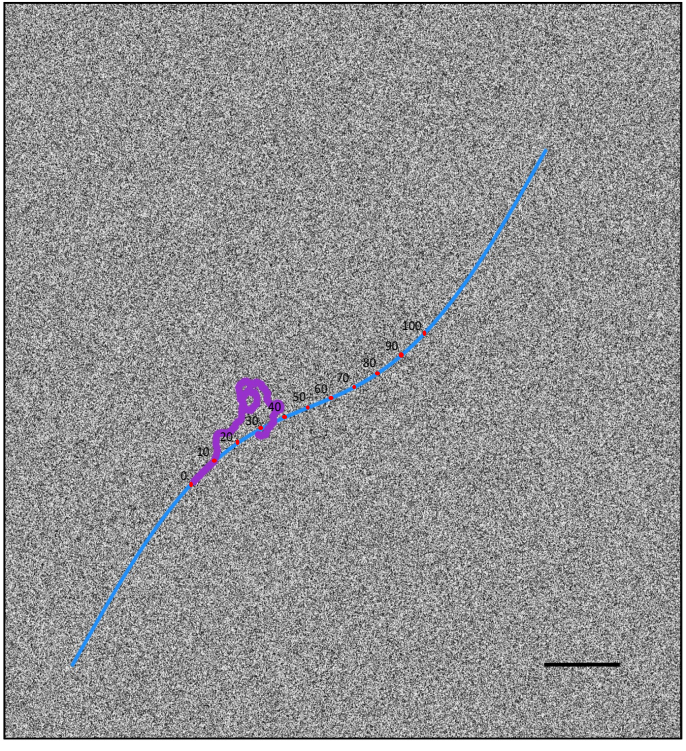


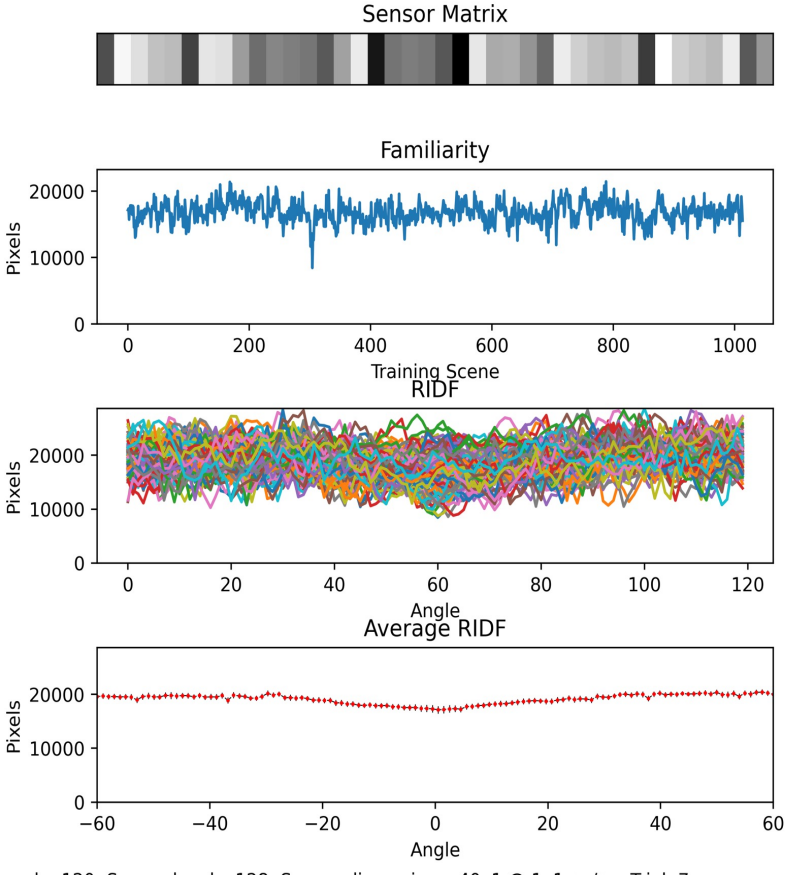
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 7993.68; RMSD/dist: 19.984; TD: 926; p90: 2; p50: 2; complete: 0


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 7
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
4
2
0
TD
SAD (pixels)
20000
10000
0
Sensor regions

10%

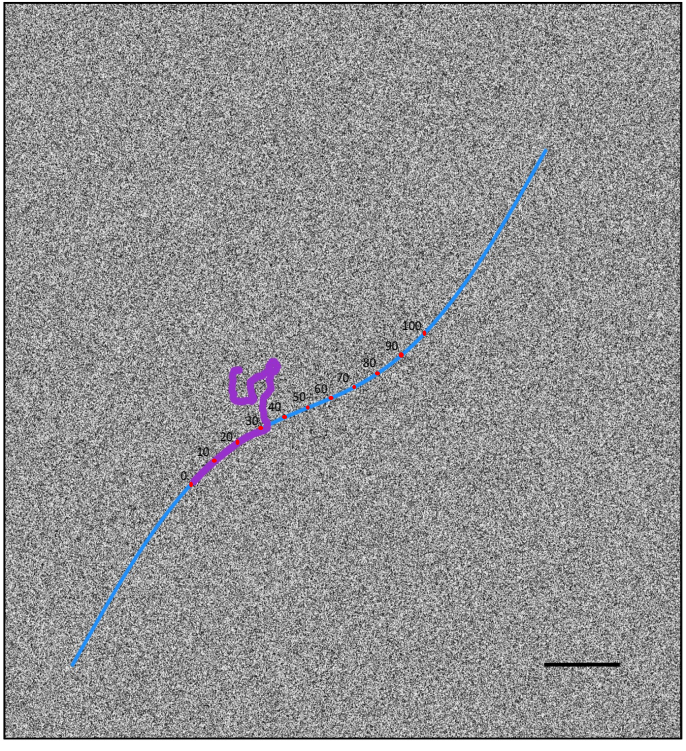


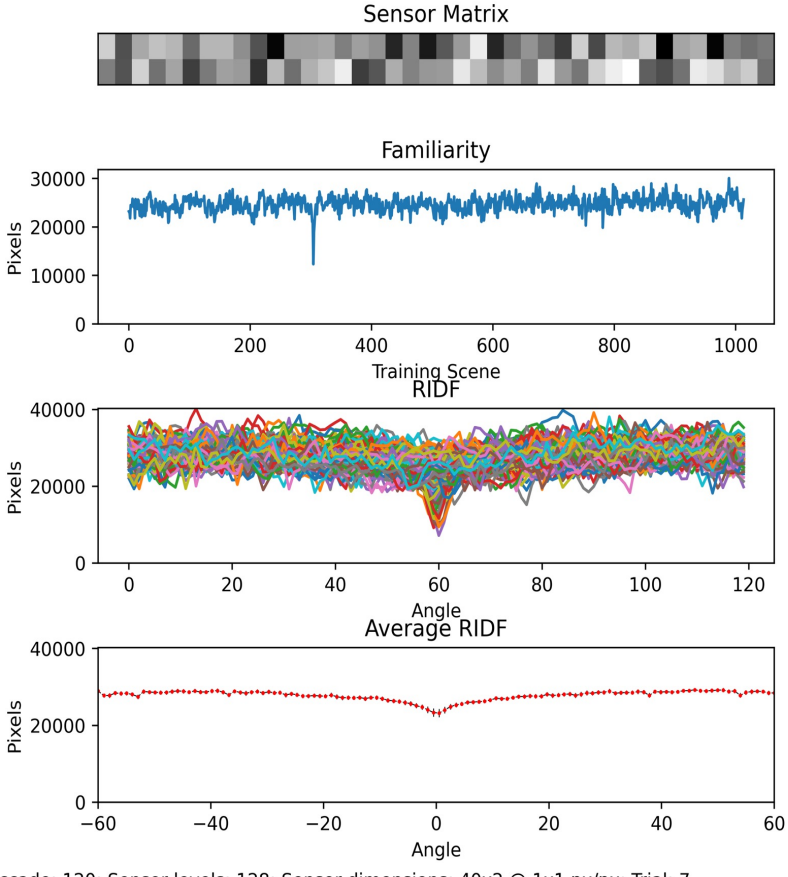


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2875.87; RMSD/dist: 7.190; TD: -876; p90: 2; p50: 2; complete: 0

30%

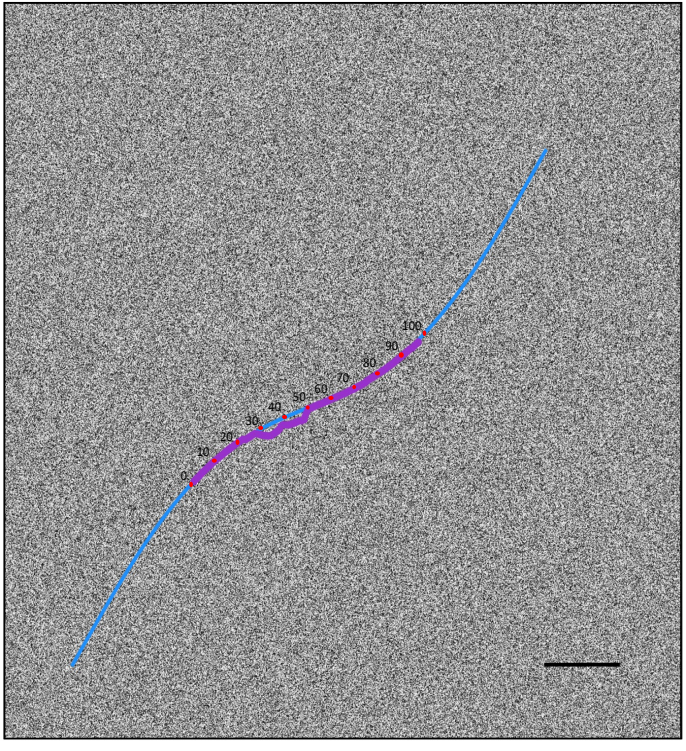


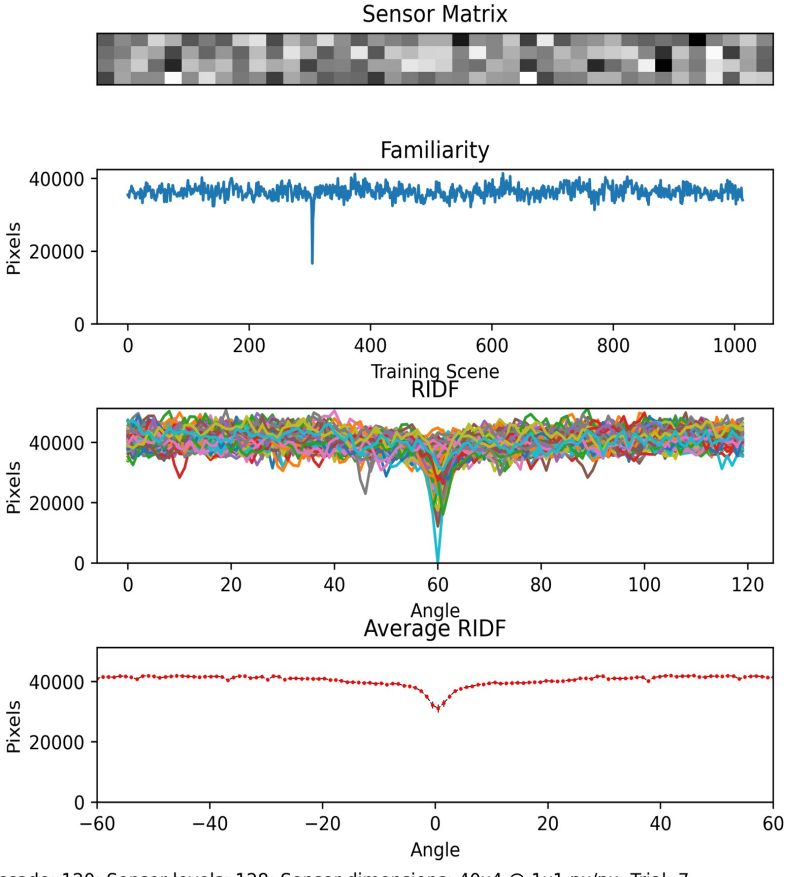


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3638.09; RMSD/dist: 9.095; TD: 1273; p90: 4; p50: 4; complete: 0

70%

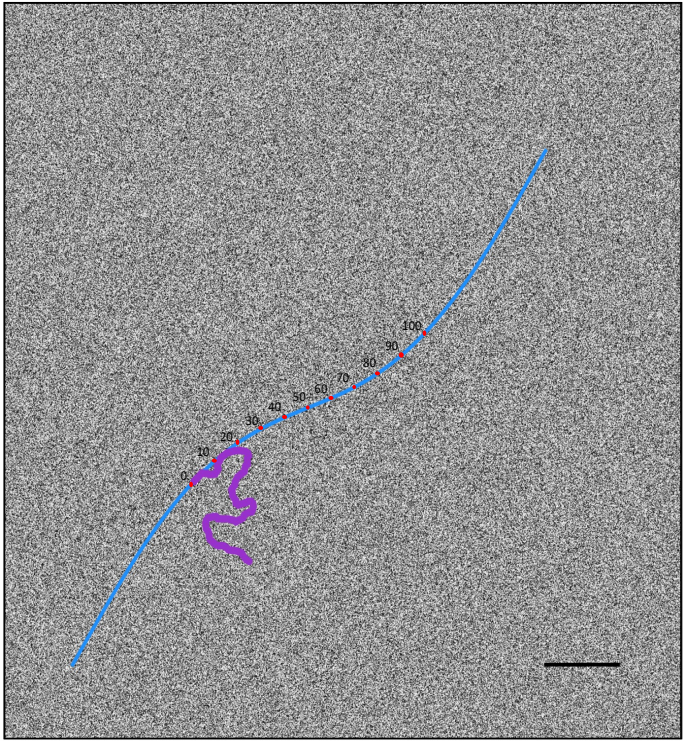


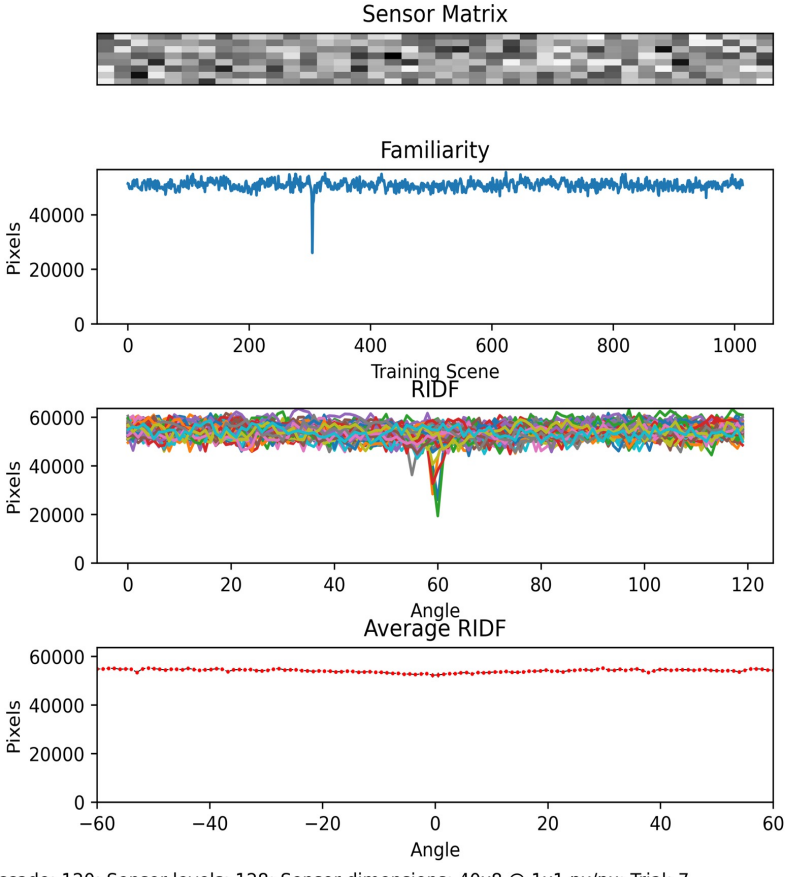


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 314.05; RMSD/dist: 0.785; TD: 5052; p90: 4; p50: 4; complete: 0

10%

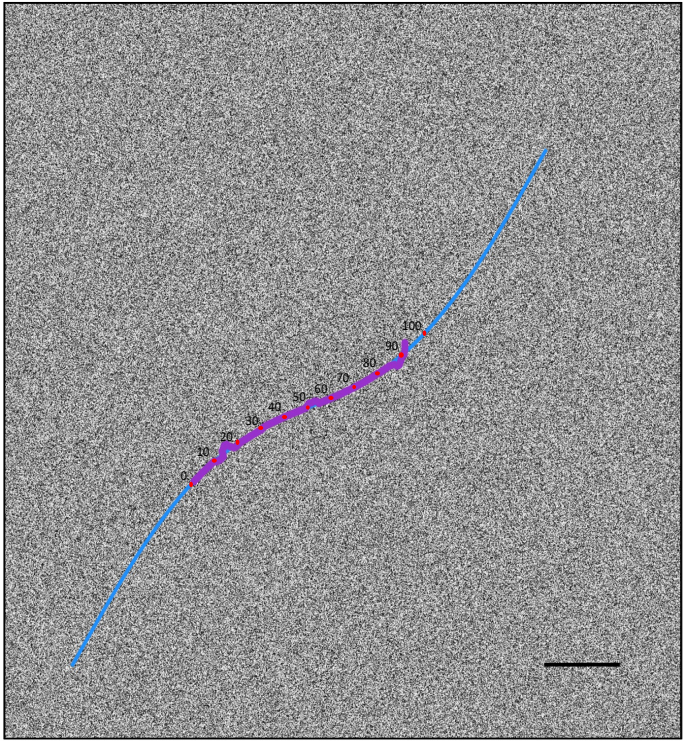


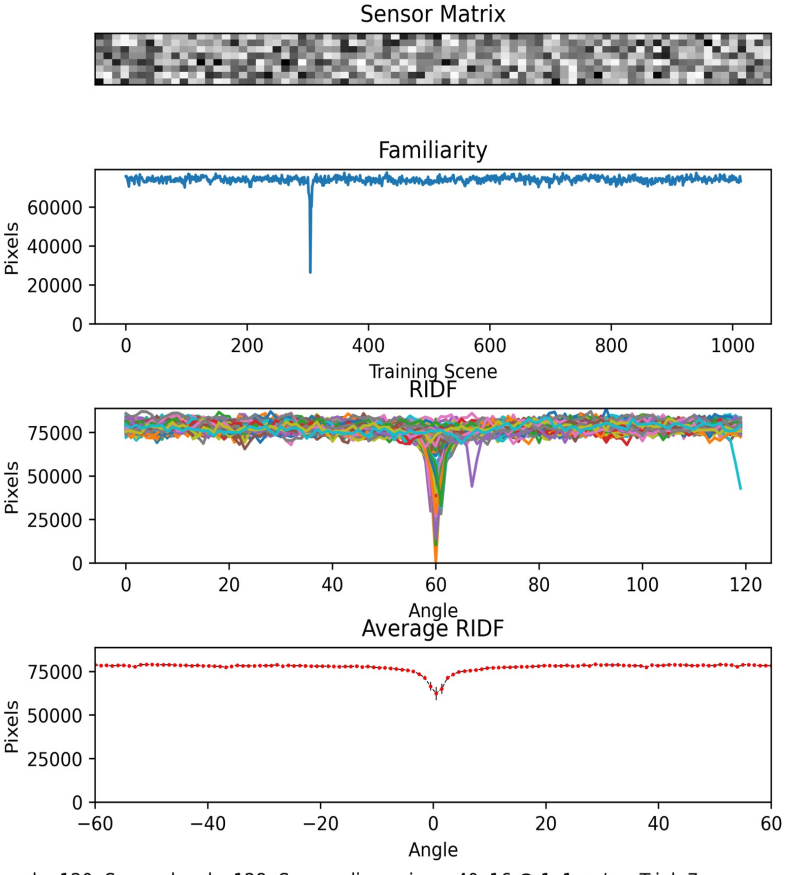


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 5302.28; RMSD/dist: 13.256; TD: -1200; p90: 2; p50: 2; complete: 0

70%

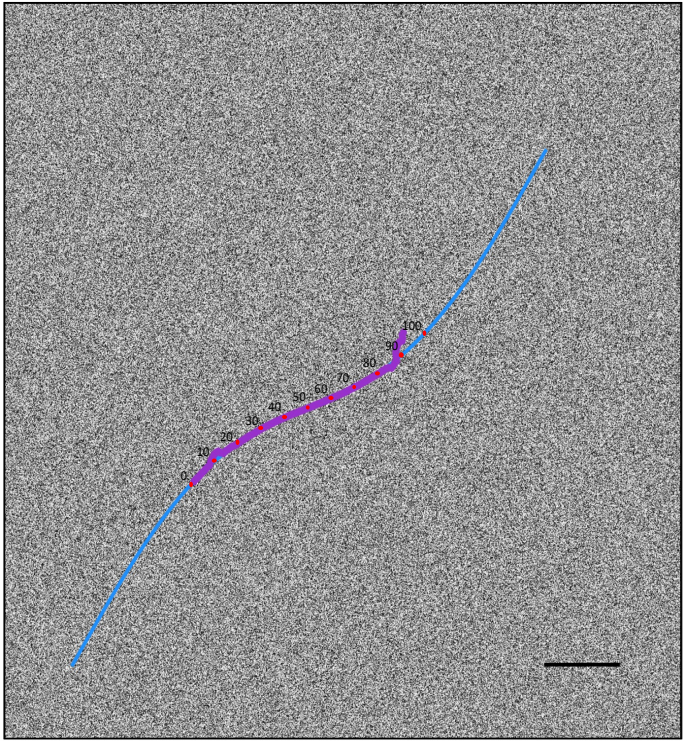


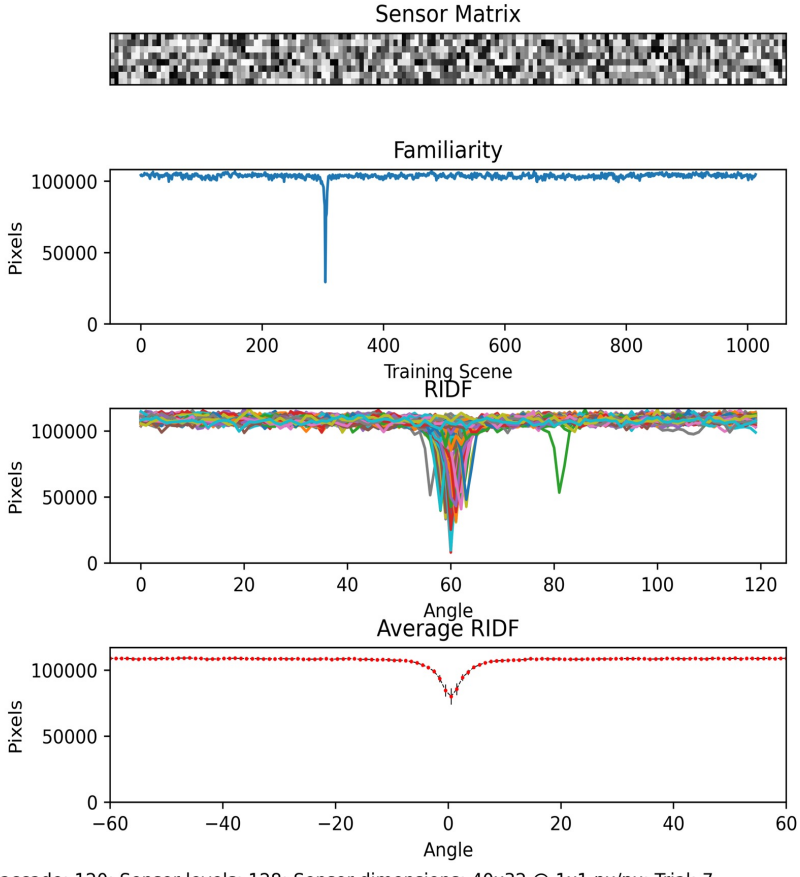


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 165.60; RMSD/dist: 0.414; TD: 11588; p90: 6; p50: 2; complete: 0

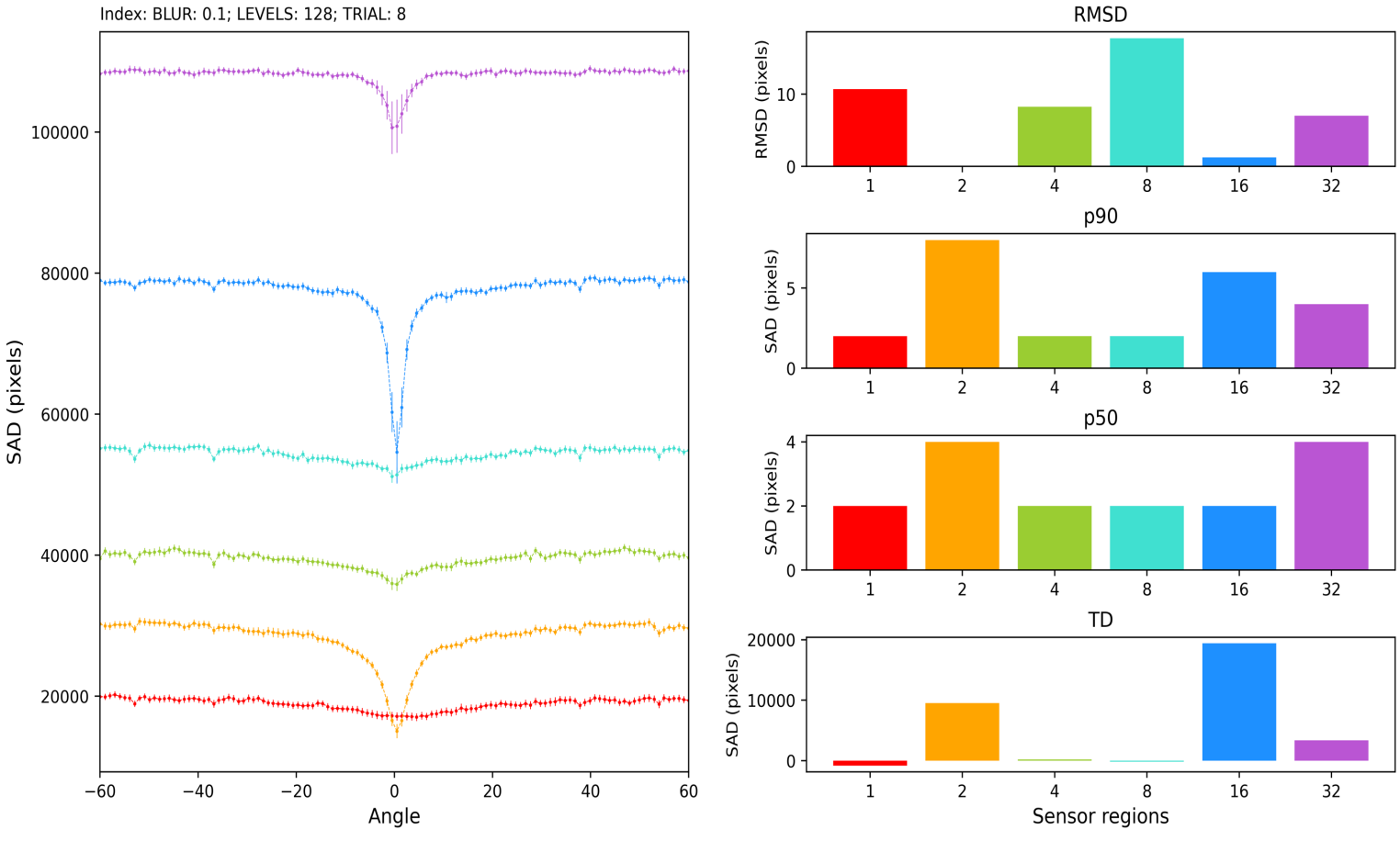
80%



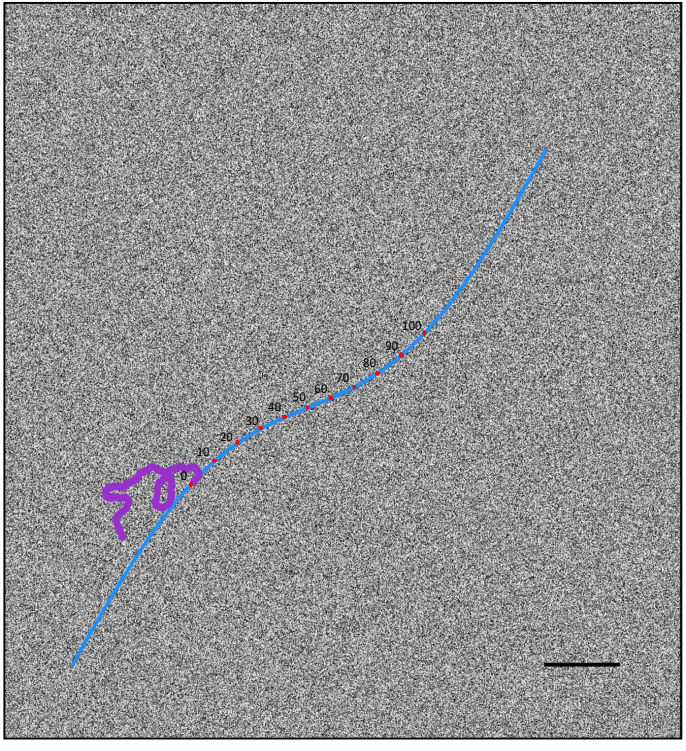


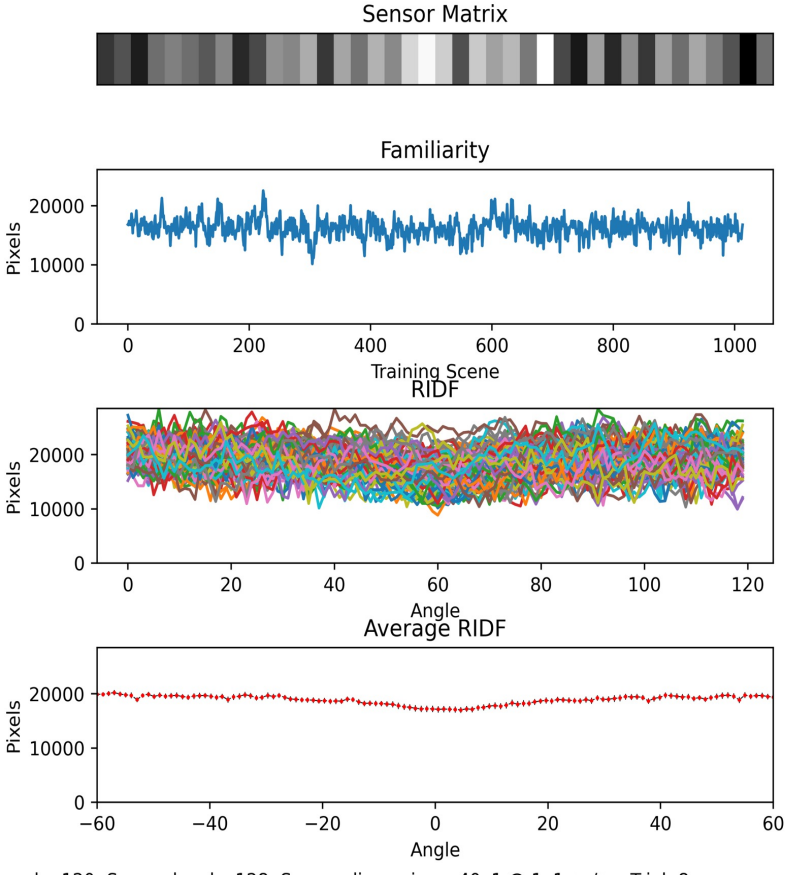
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 241.58; RMSD/dist: 0.604; TD: 23658; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 8
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
0
1
2
4
8
16
32
p90
SAD (pixels)
5
0
p50
SAD (pixels)
4
2
0
TD
SAD (pixels)
20000
10000
0
Sensor regions

0%

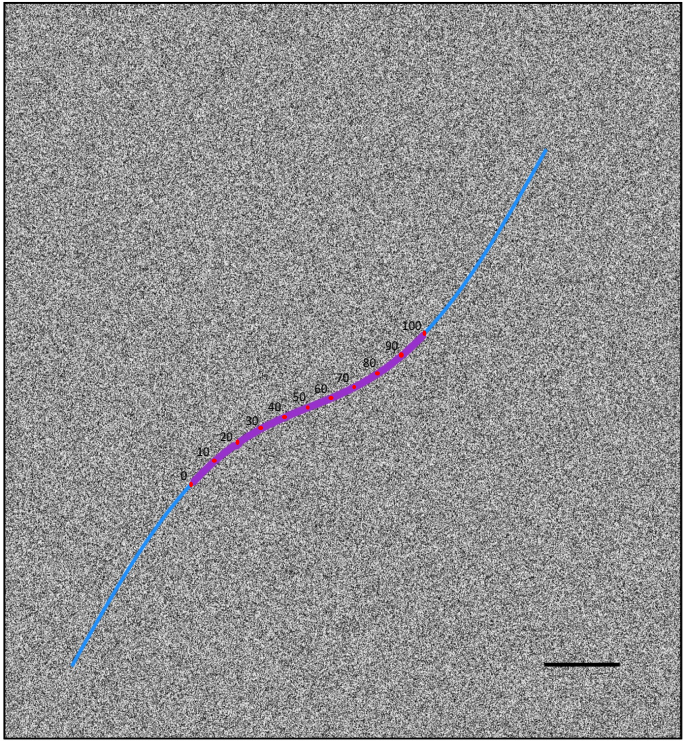


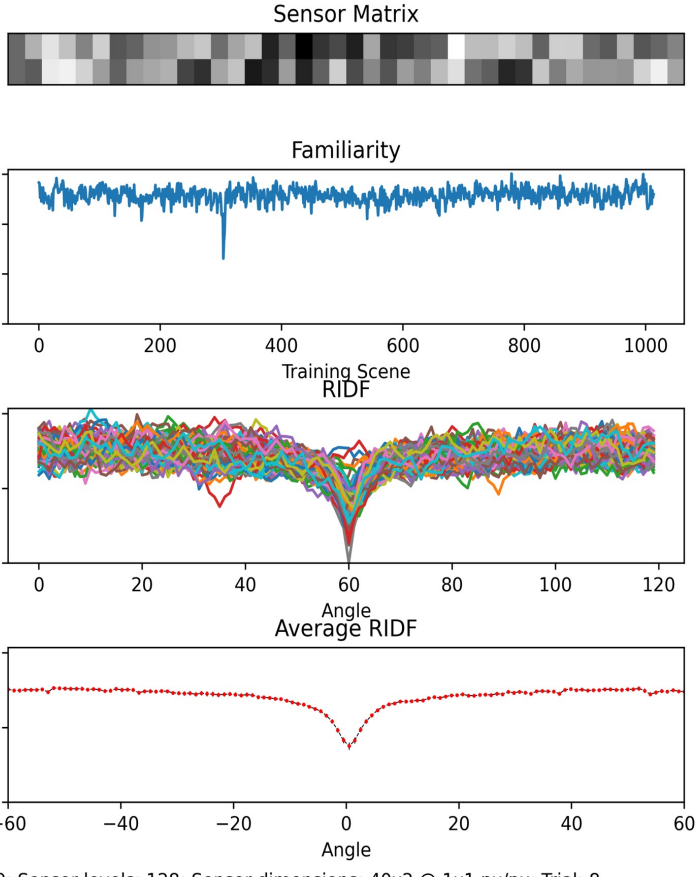


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 4275.91; RMSD/dist: 10.690; TD: -809; p90: 2; p50: 2; complete: 0

100%

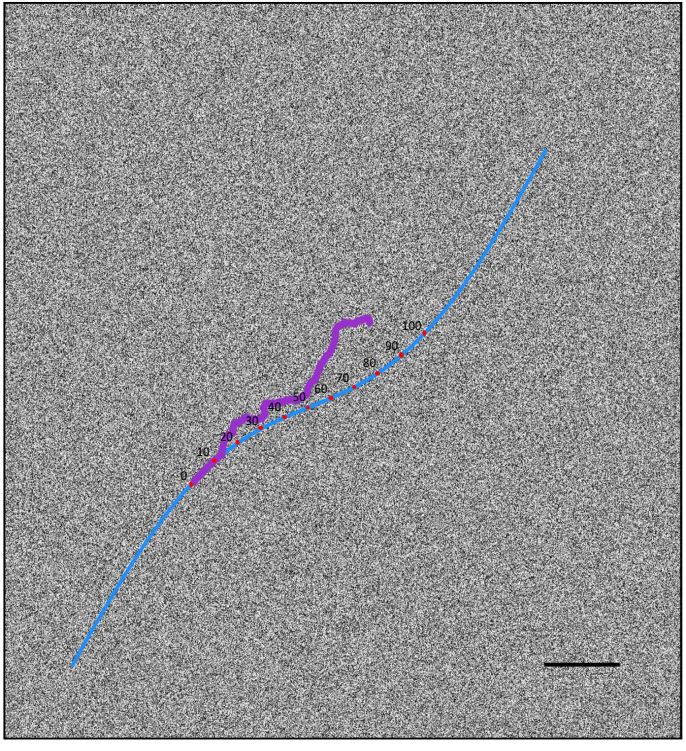


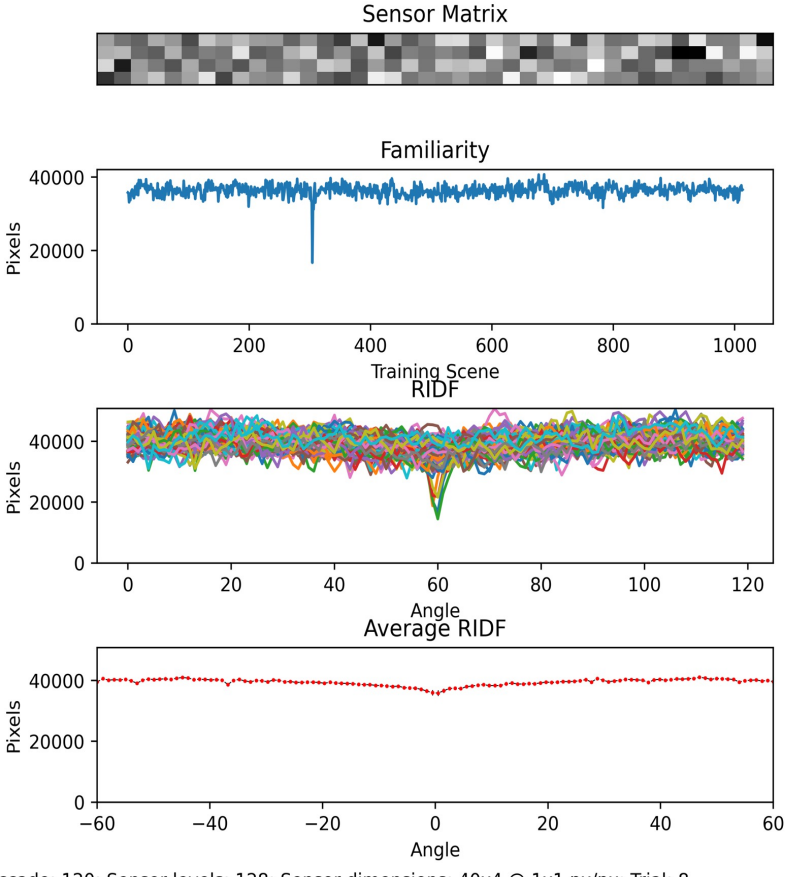


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 28.34; RMSD/dist: 0.071; TD: 9525; p90: 8; p50: 4; complete: 0

10%

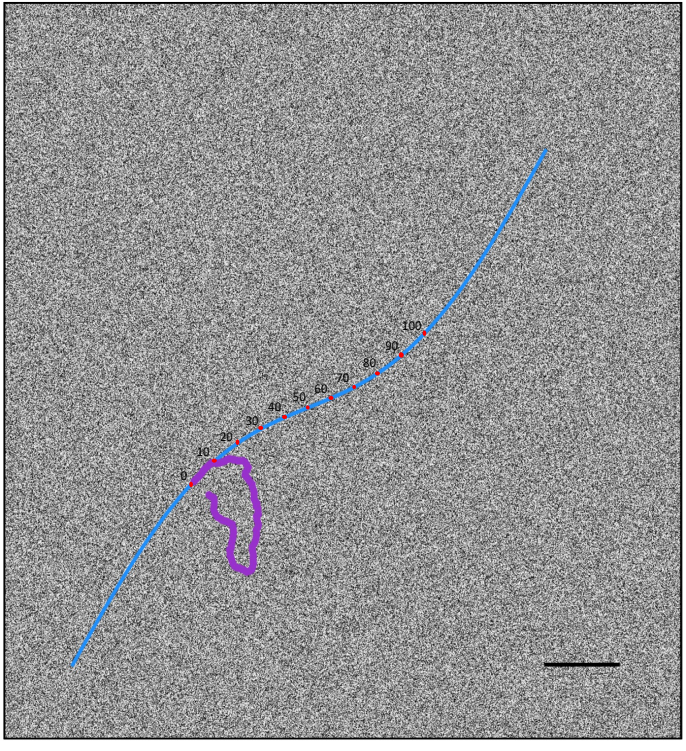


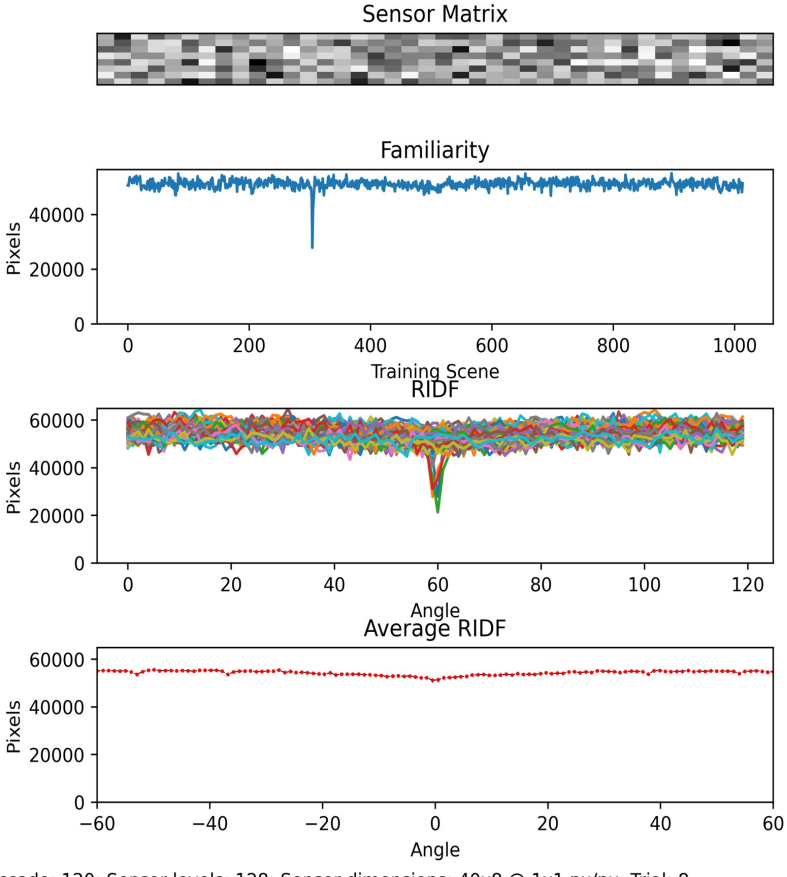


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3293.22; RMSD/dist: 8.233; TD: 222; p90: 2; p50: 2; complete: 0

10%

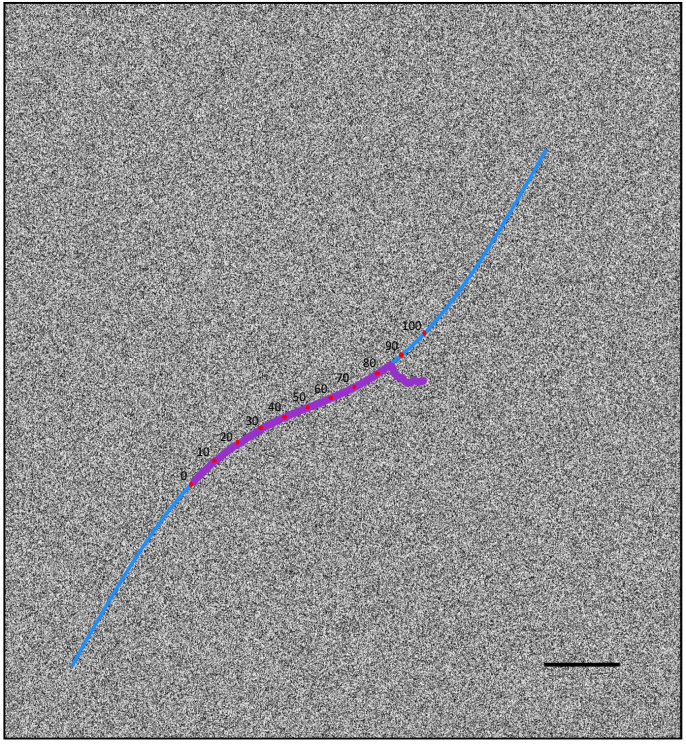


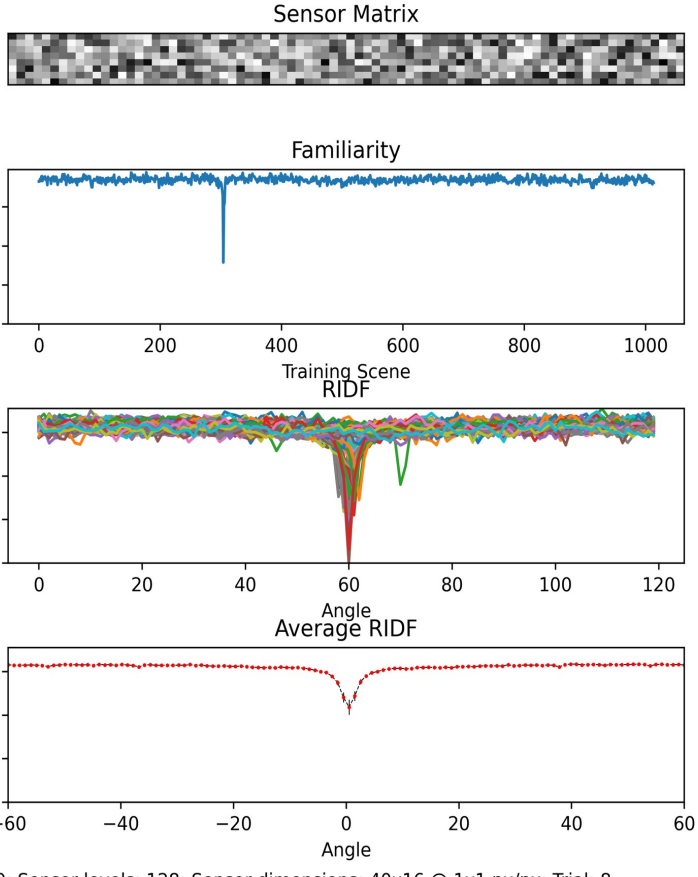


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 7101.17; RMSD/dist: 17.753; TD: -159; p90: 2; p50: 2; complete: 0

80%

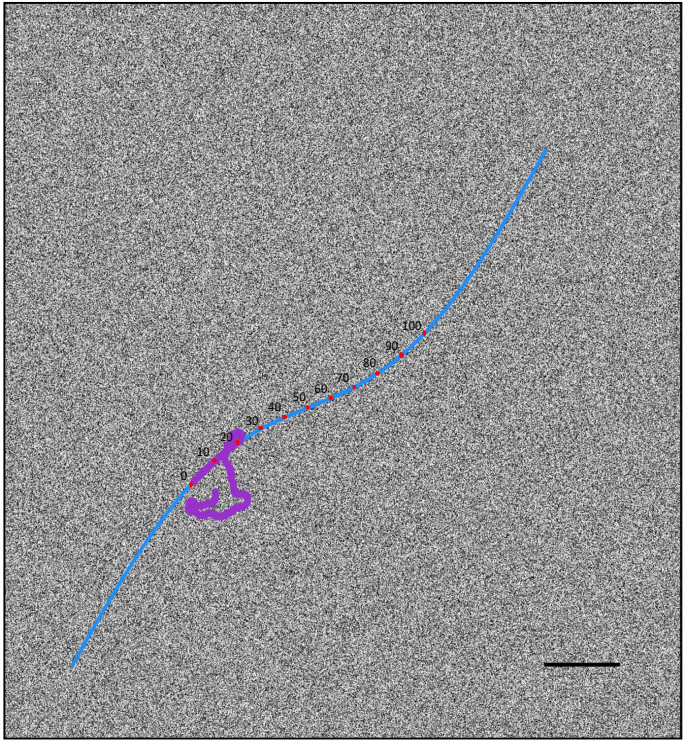


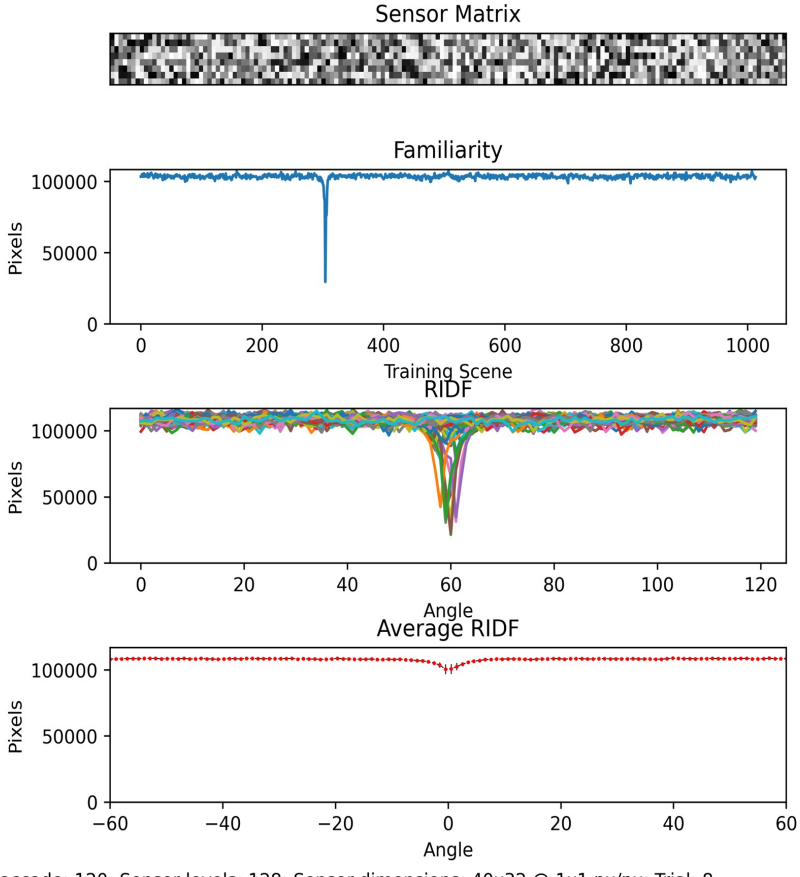


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 493.42; RMSD/dist: 1.234; TD: 19396; p90: 6; p50: 2; complete: 0

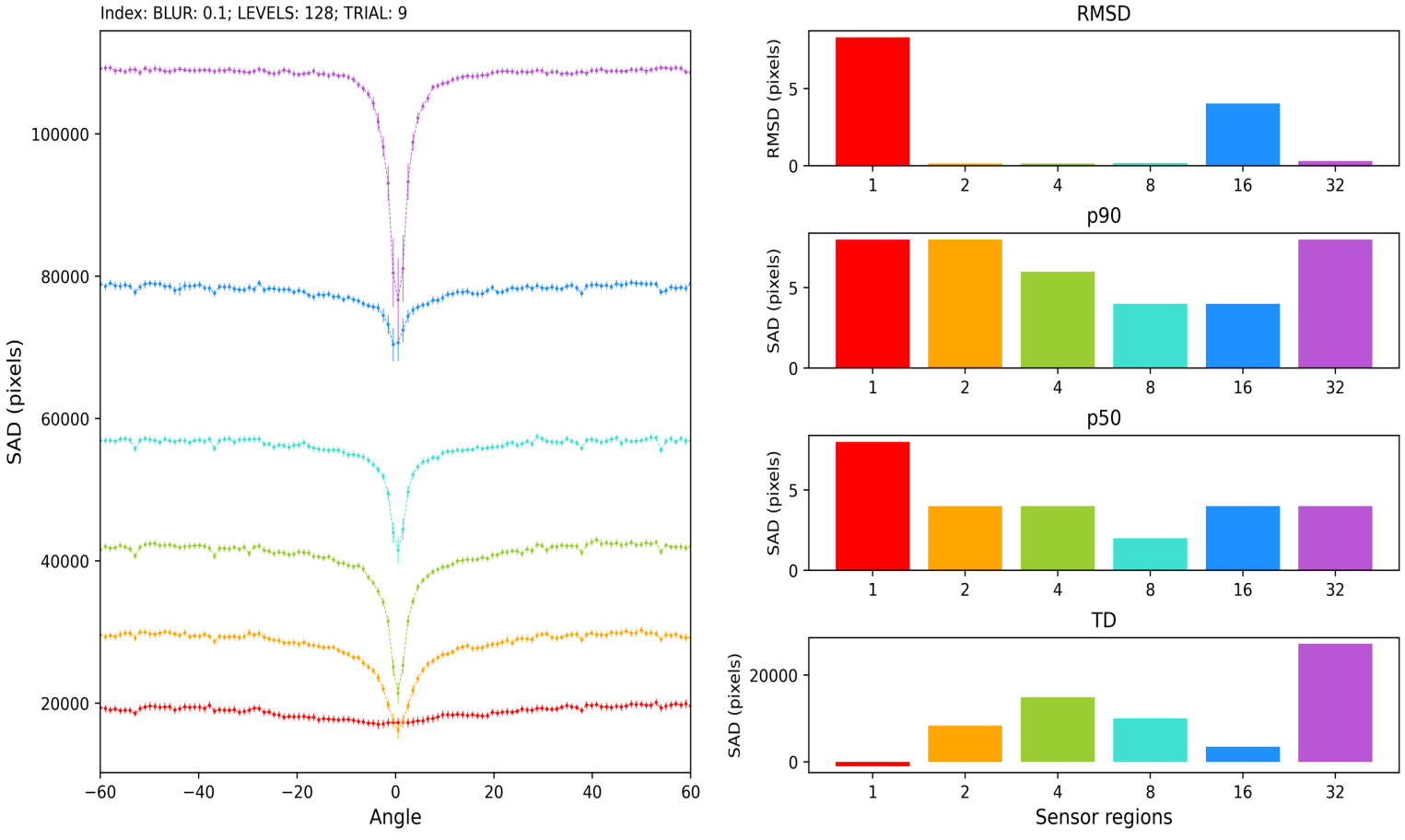
20%



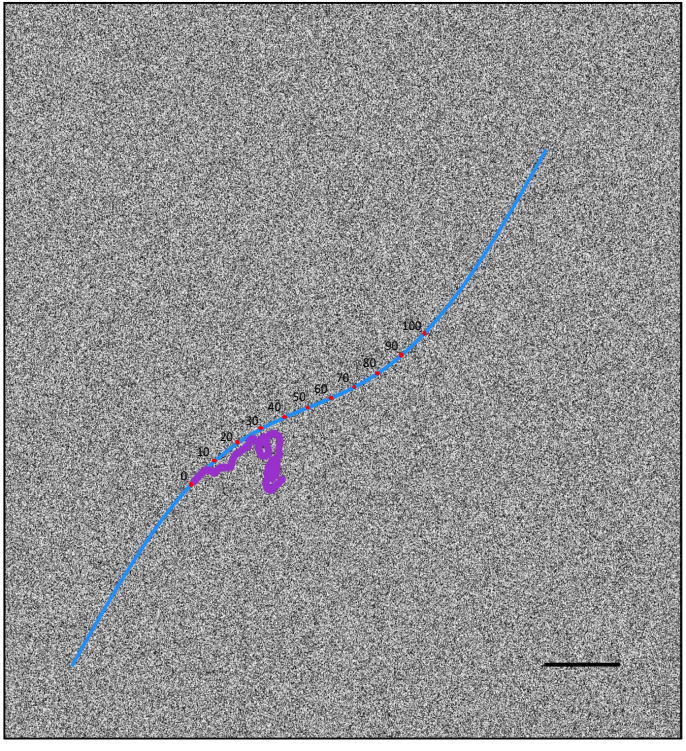


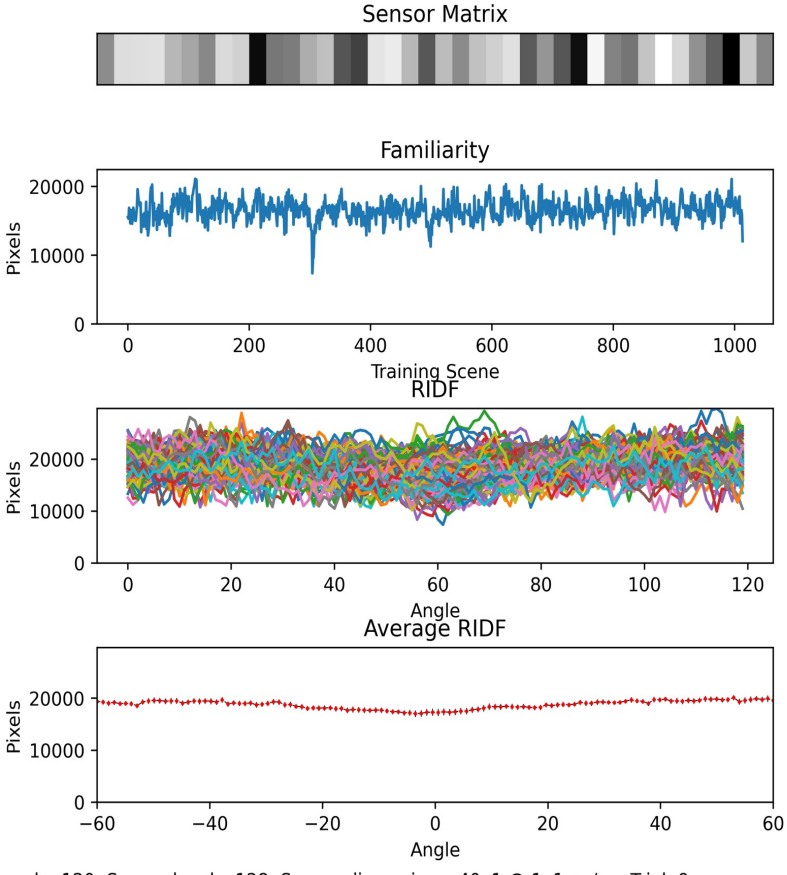
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2809.64; RMSD/dist: 7.024; TD: 3366; p90: 4; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 9
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
5
0
1
2
4
8
16
32
p90
SAD (pixels)
p50
TD
20000
Sensor regions

0%

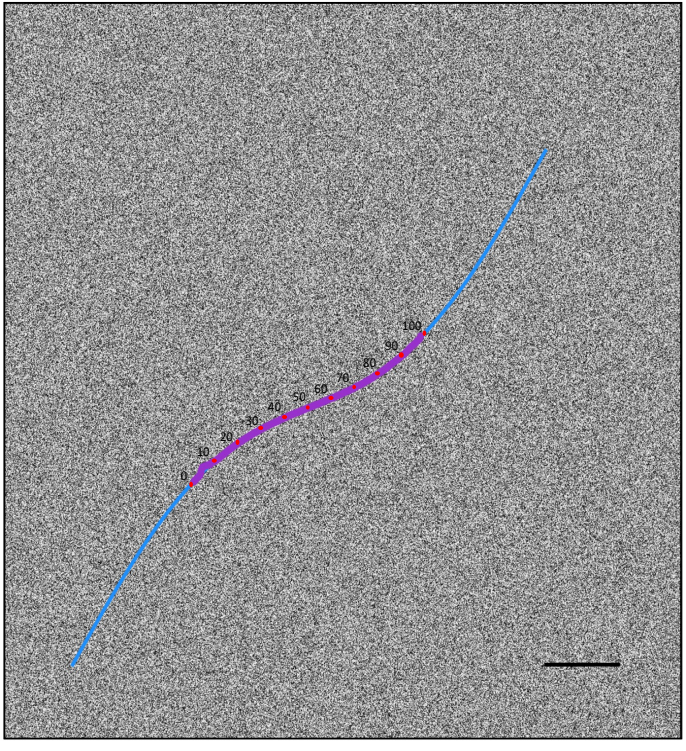


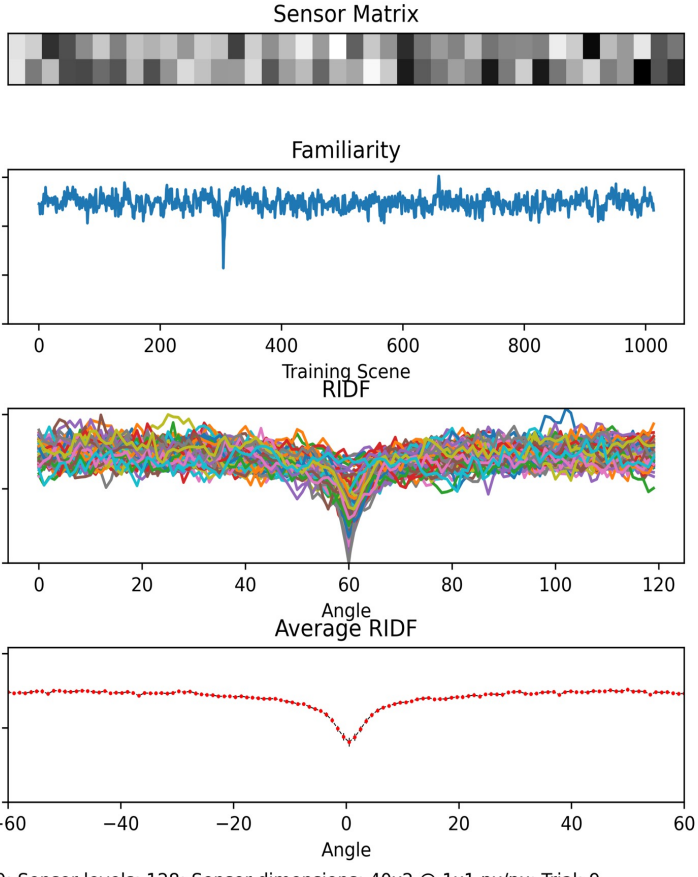


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3329.26; RMSD/dist: 8.323; TD: -1022; p90: 8; p50: 8; complete: 0

90%

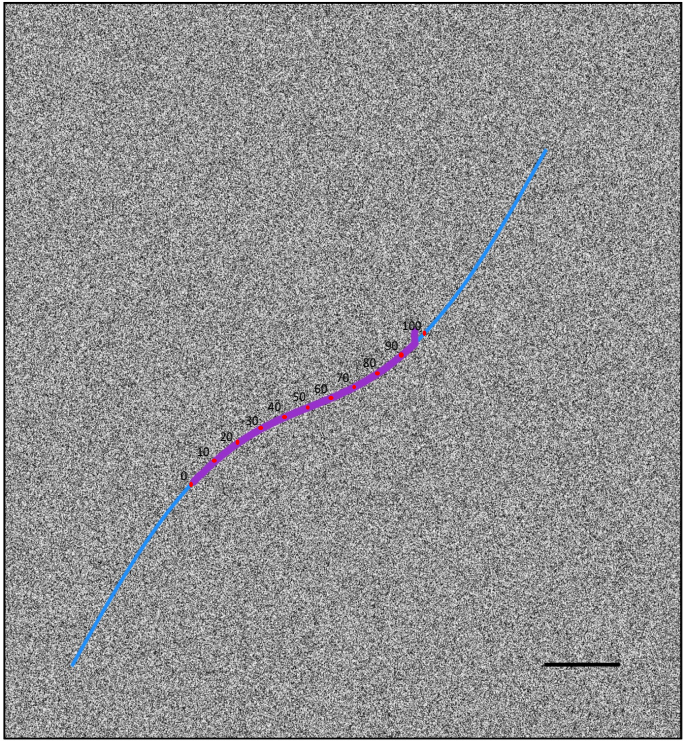


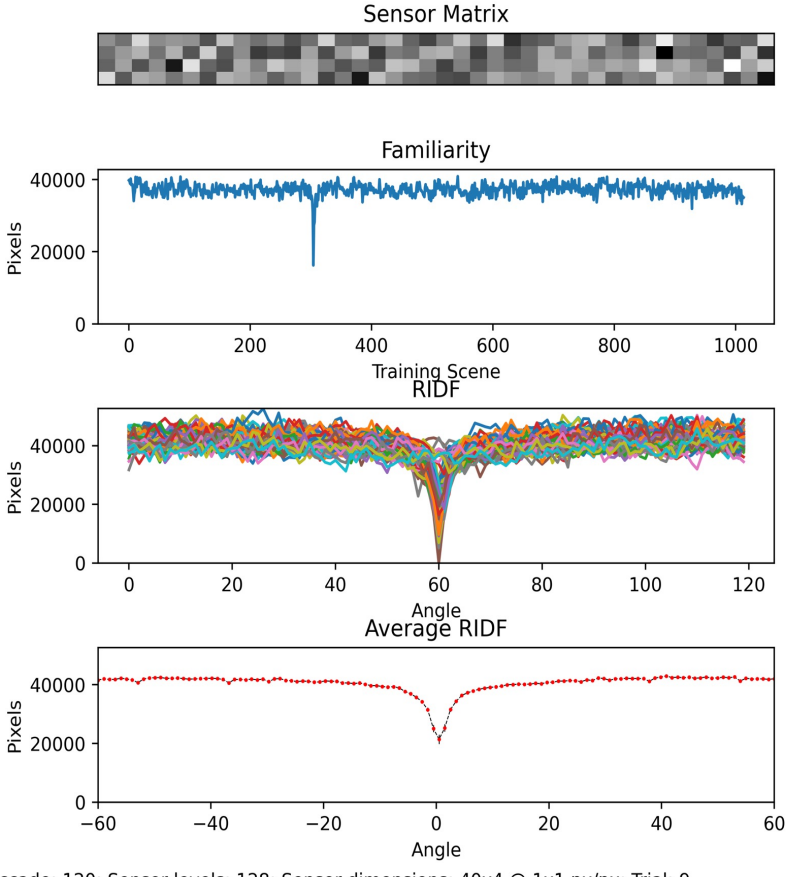


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 56.78; RMSD/dist: 0.142; TD: 8379; p90: 8; p50: 4; complete: 0

90%

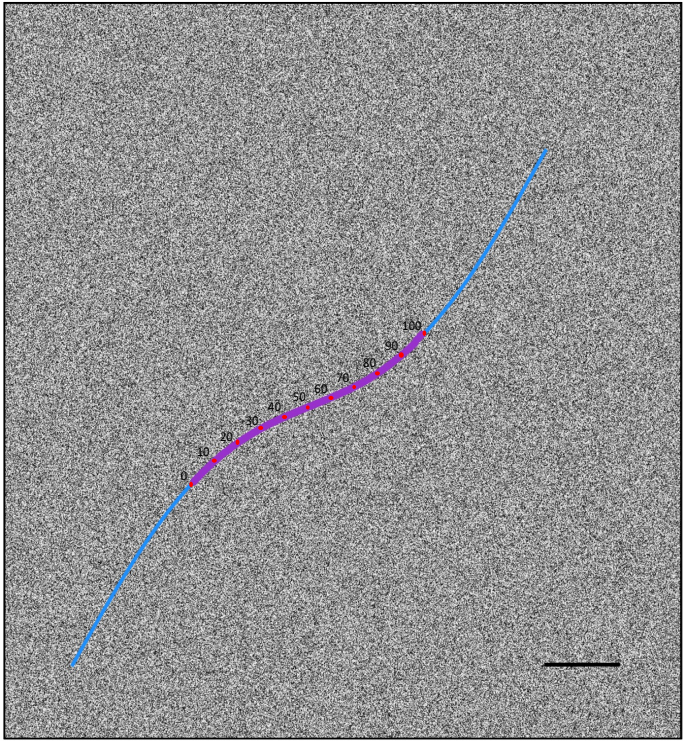


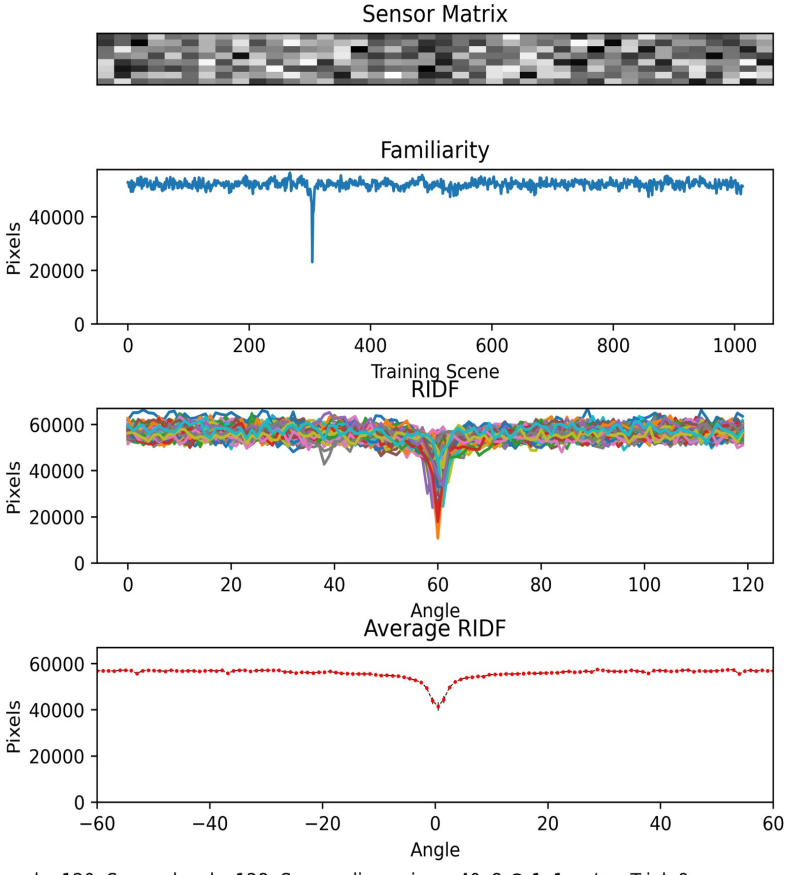


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 54.71; RMSD/dist: 0.137; TD: 14900; p90: 6; p50: 4; complete: 0

100%

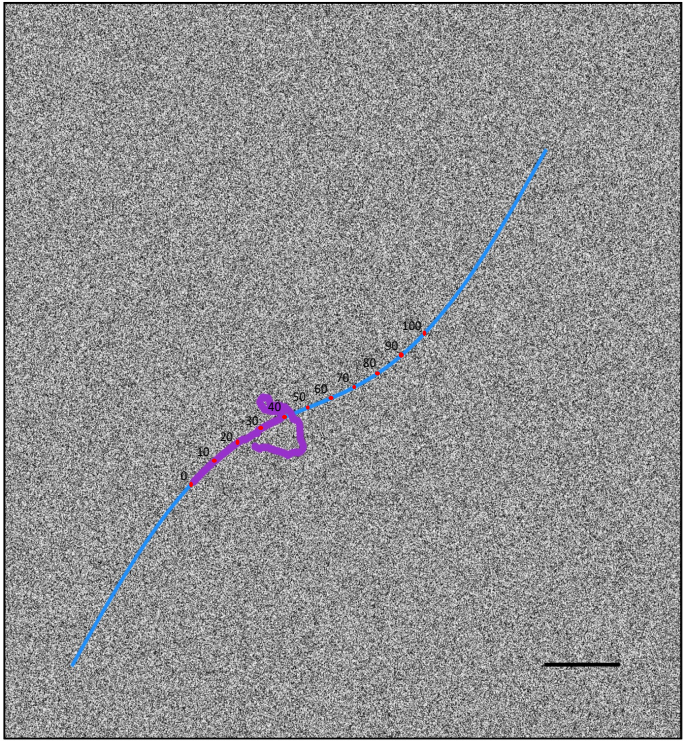


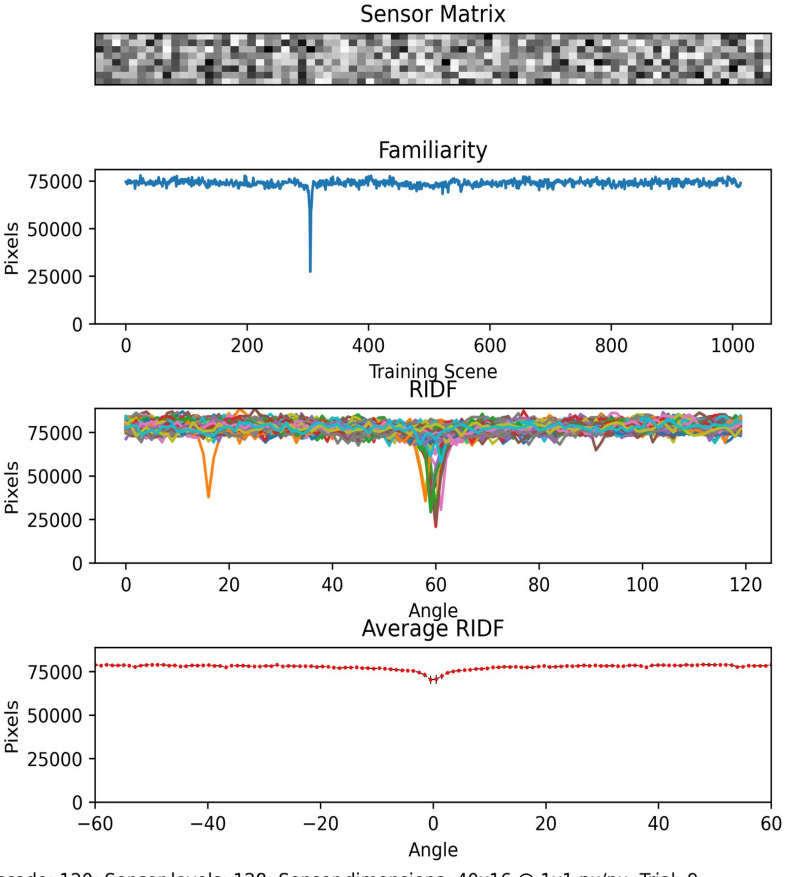


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 68.56; RMSD/dist: 0.171; TD: 10065; p90: 4; p50: 2; complete: 0

40%

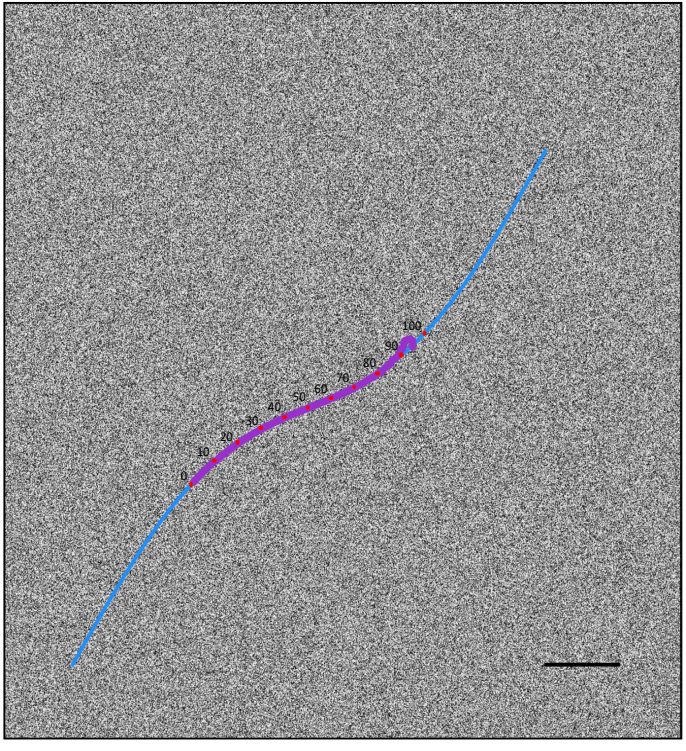


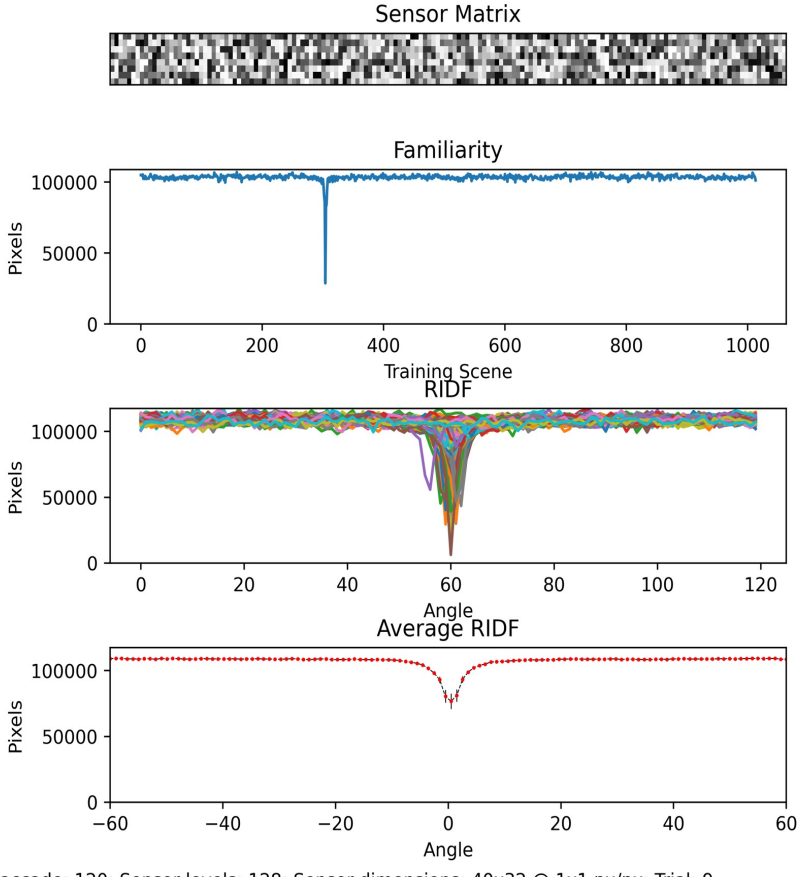


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1614.33; RMSD/dist: 4.036; TD: 3512; p90: 4; p50: 4; complete: 0

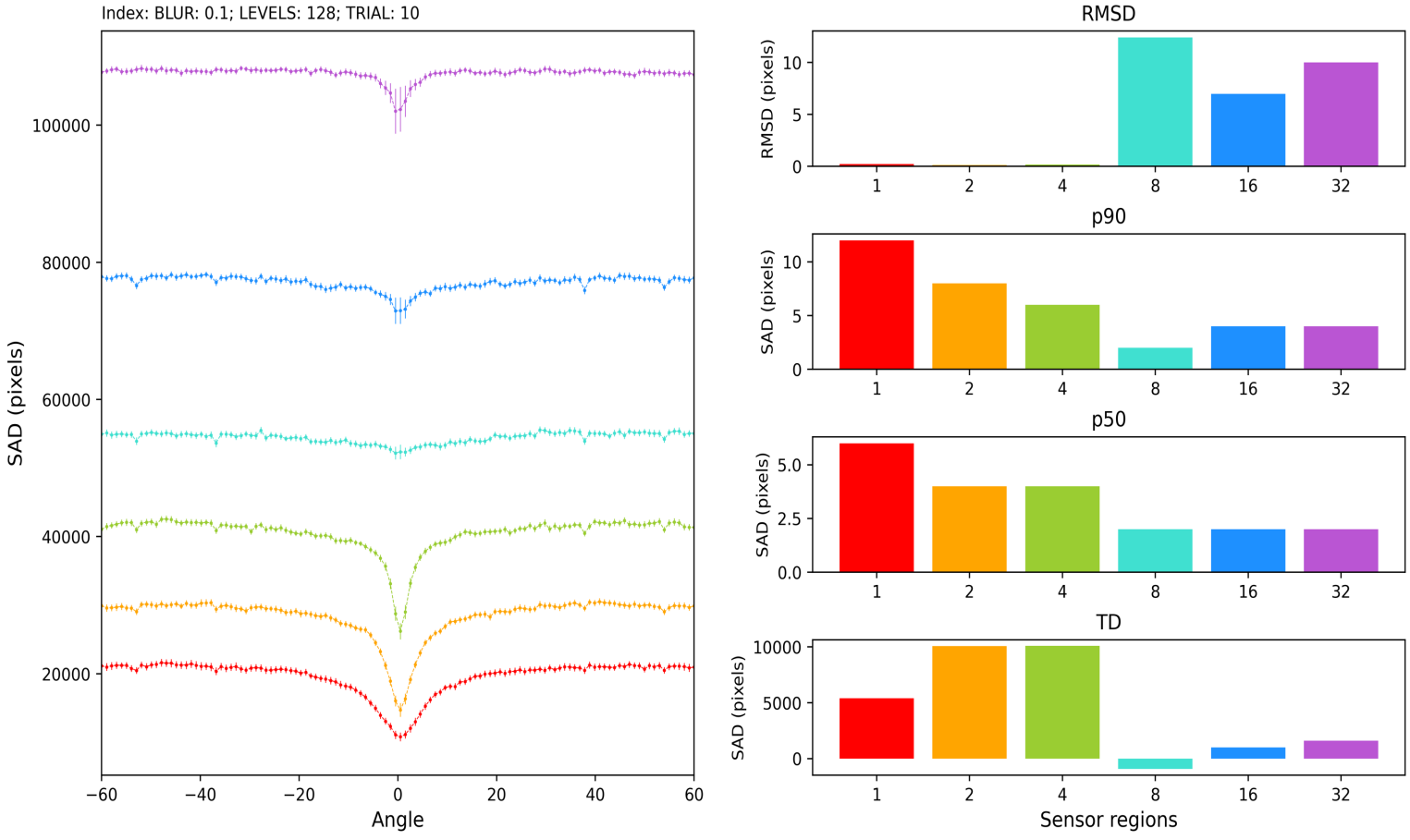
90%



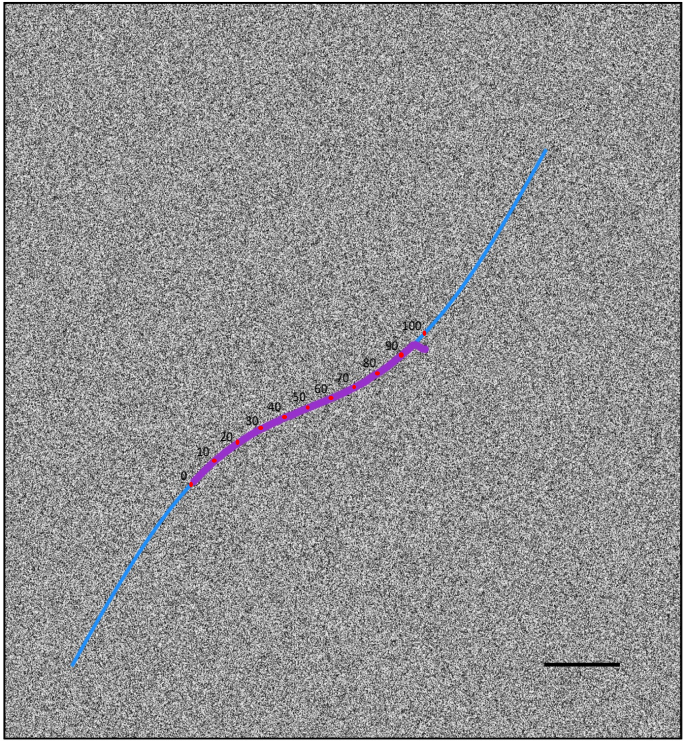


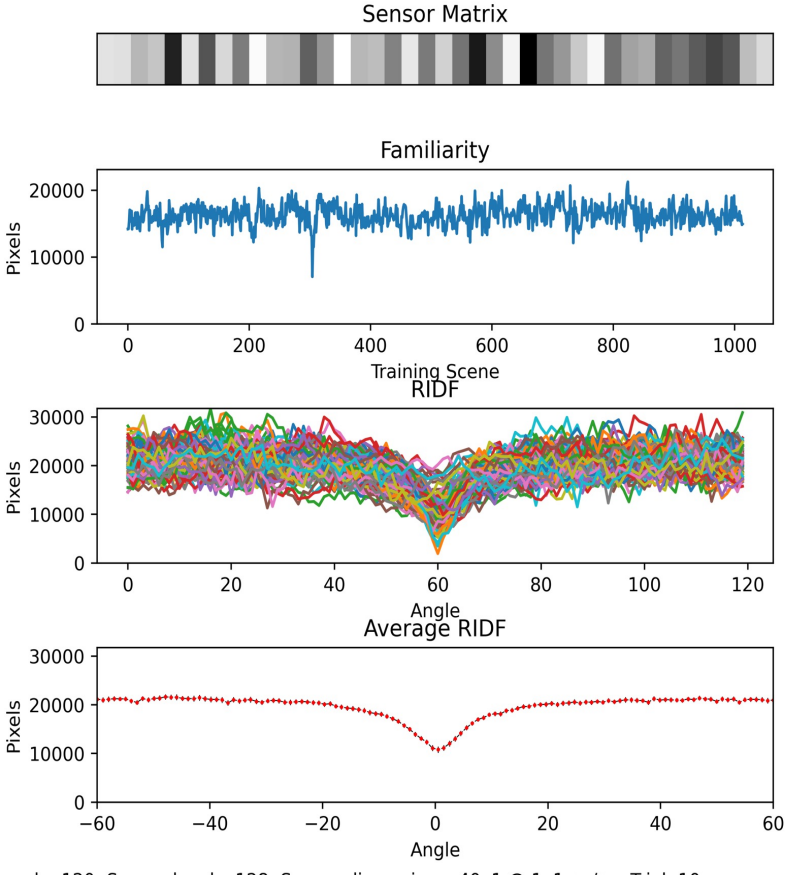
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 121.98; RMSD/dist: 0.305; TD: 27236; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.1; LEVELS: 128; TRIAL: 10
SAD (pixels)
100000
80000
60000
40000
20000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
5.0
2.5
0.0
TD
SAD (pixels)
10000
5000
0
Sensor regions

90%

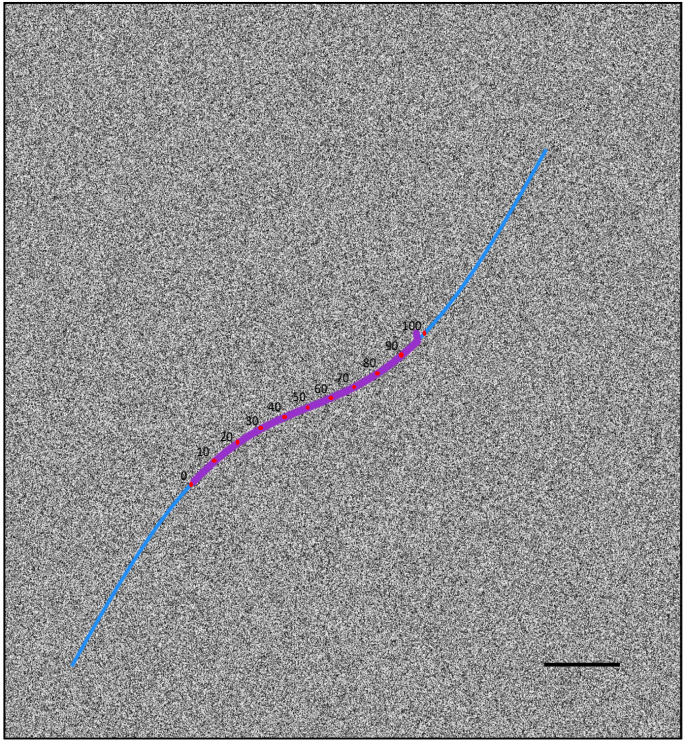


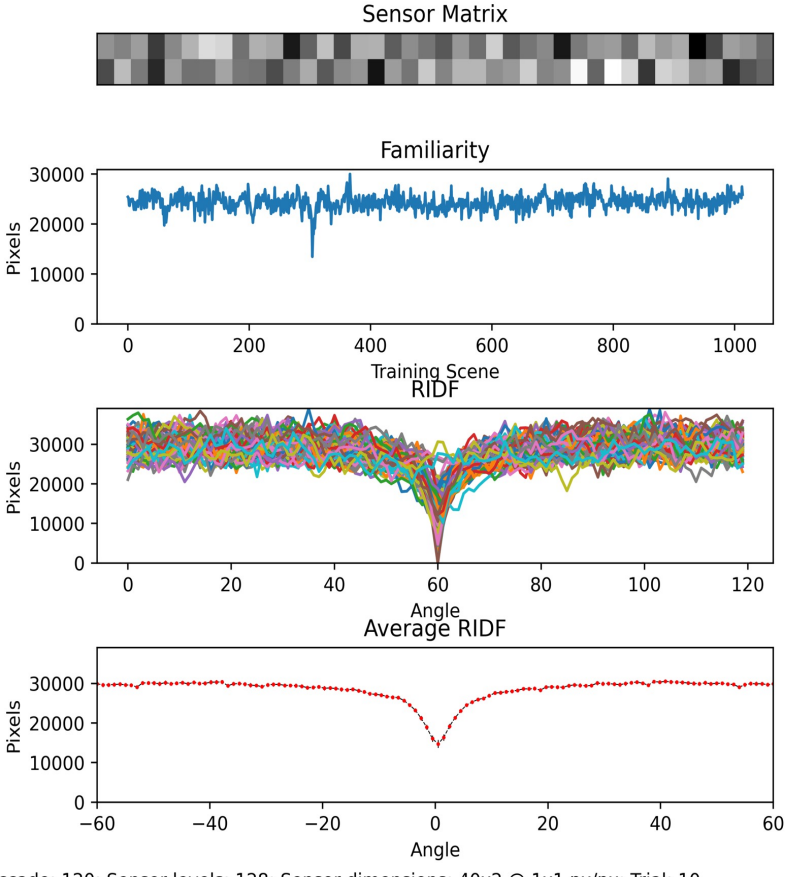


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 81.05; RMSD/dist: 0.203; TD: 5396; p90: 12; p50: 6; complete: 0

90%

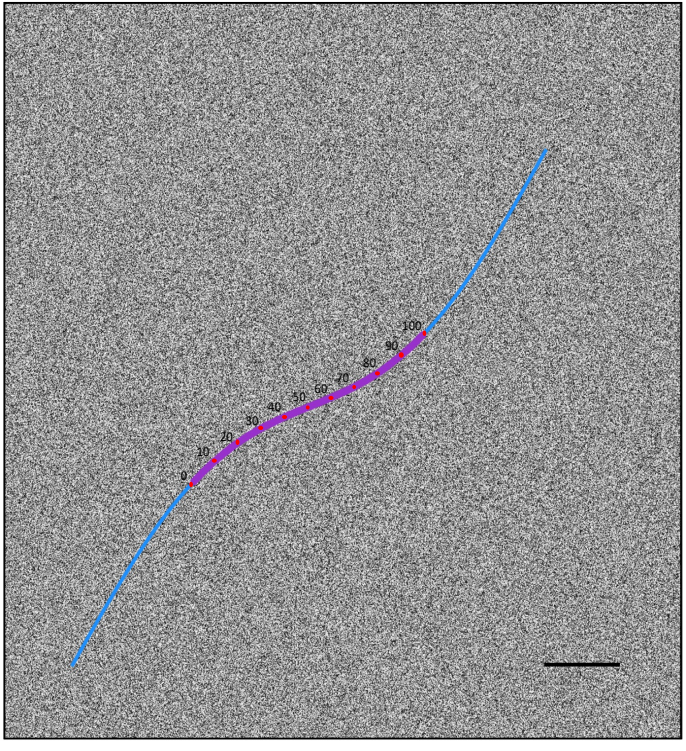


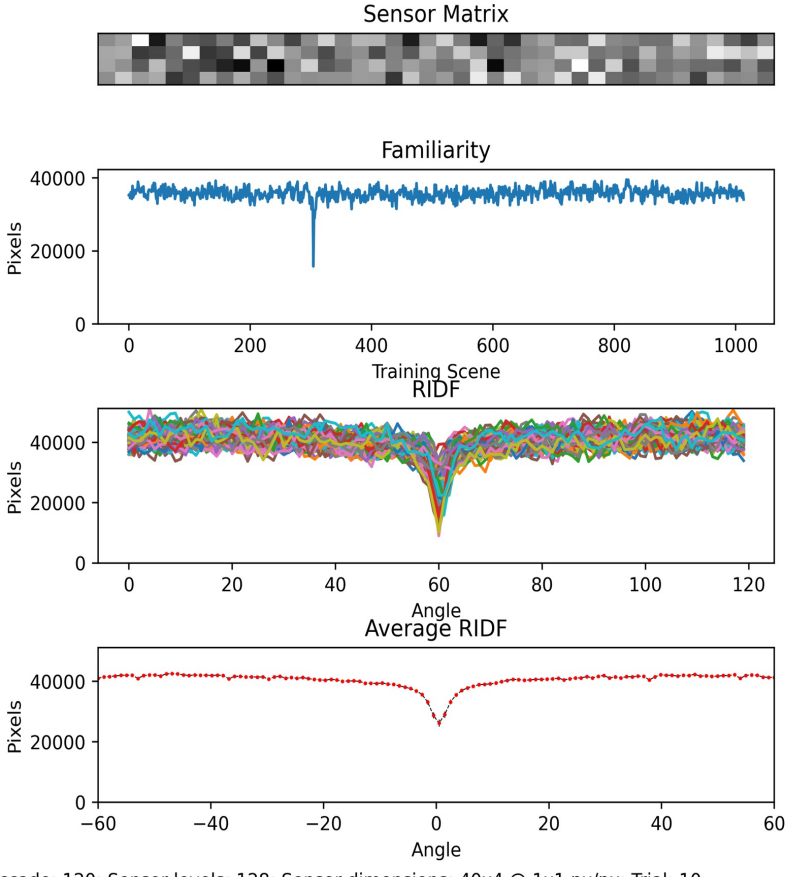


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 47.02; RMSD/dist: 0.118; TD: 10064; p90: 8; p50: 4; complete: 0

100%

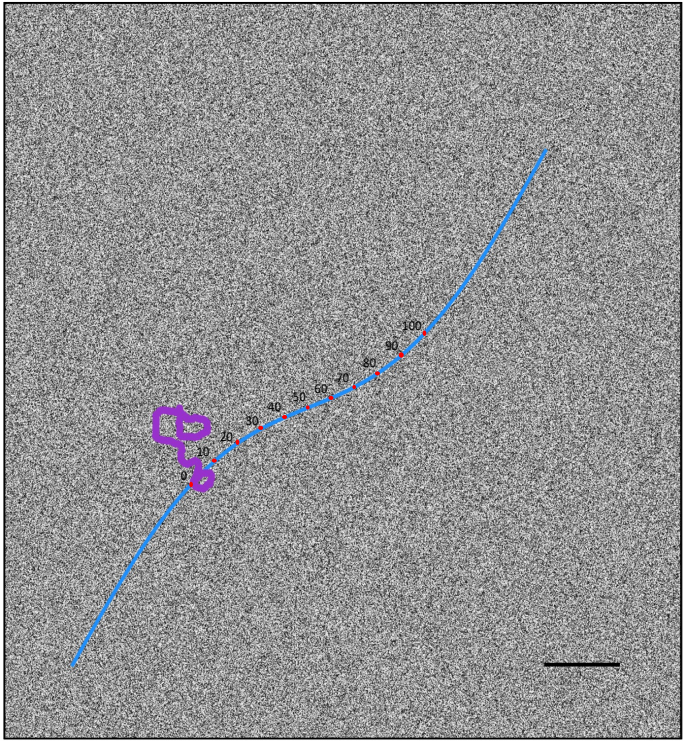


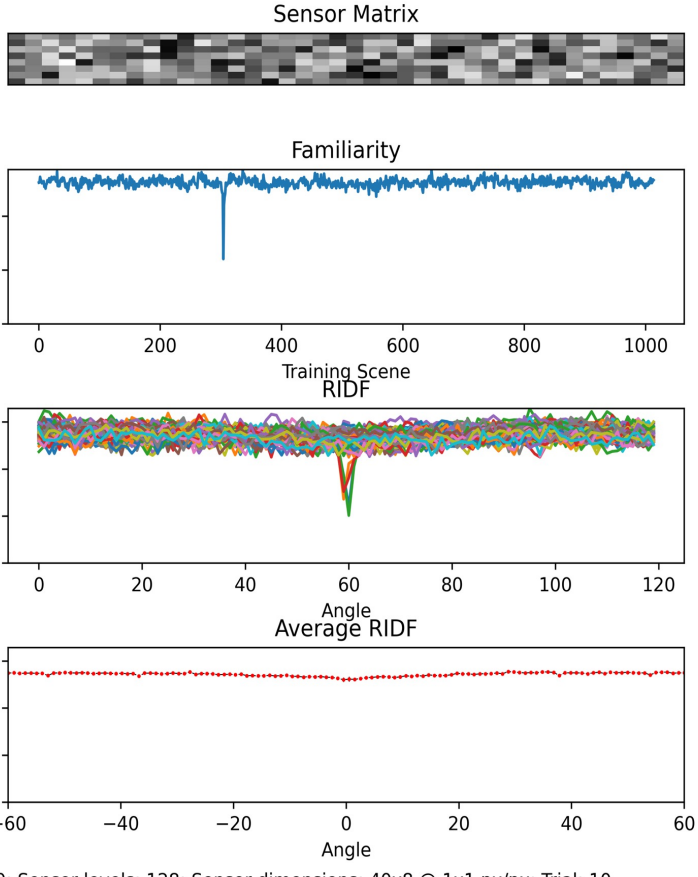


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 68.22; RMSD/dist: 0.171; TD: 10090; p90: 6; p50: 4; complete: 0

0%

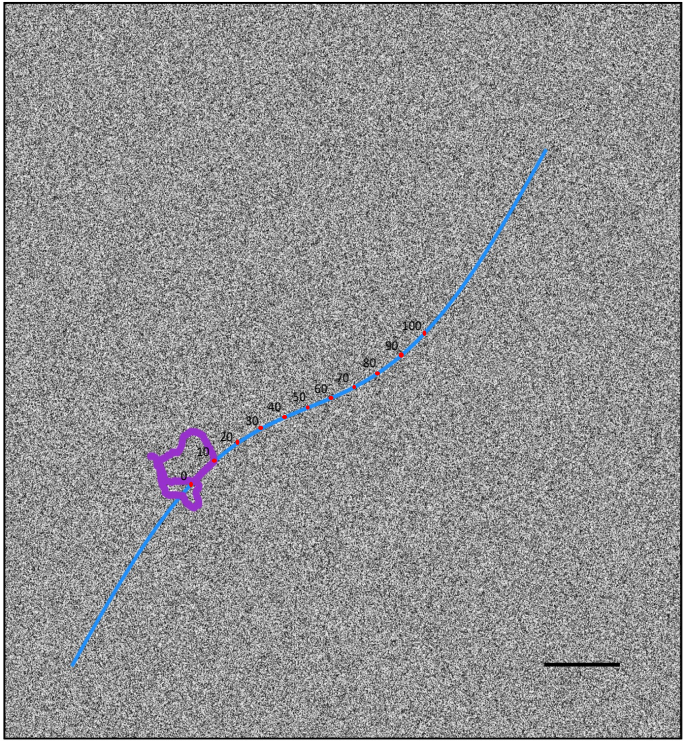


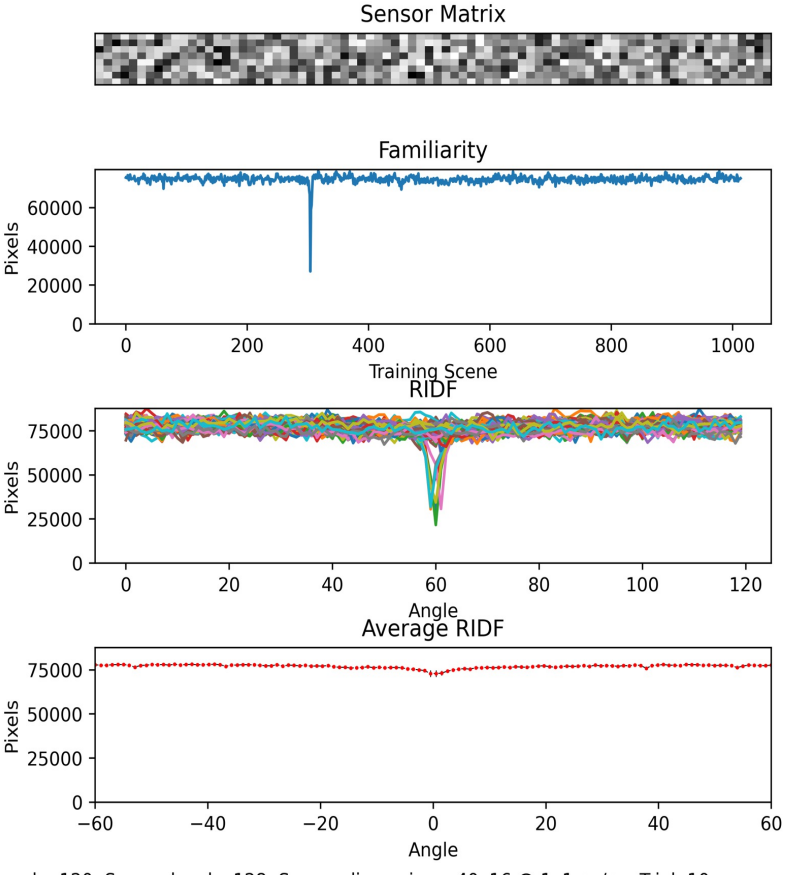


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4966.87; RMSD/dist: 12.417; TD: -924; p90: 2; p50: 2; complete: 0

10%

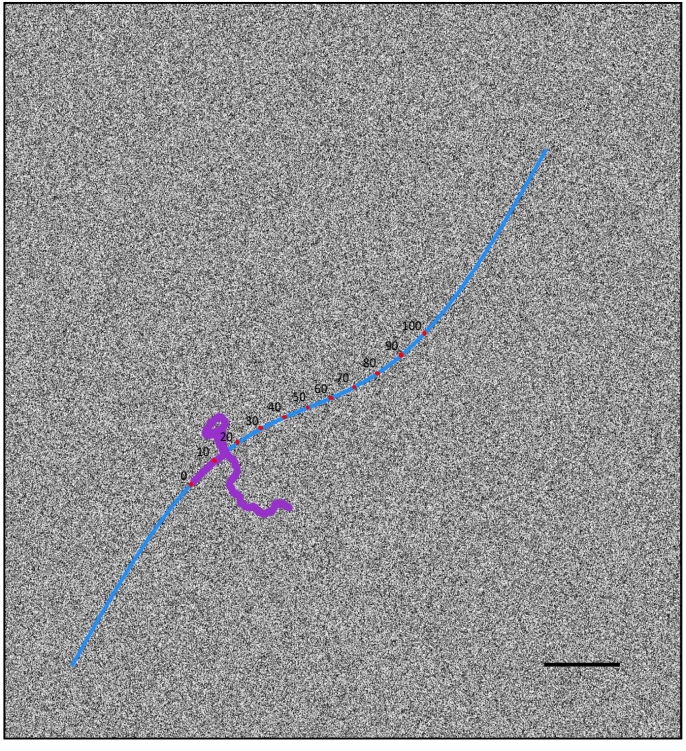


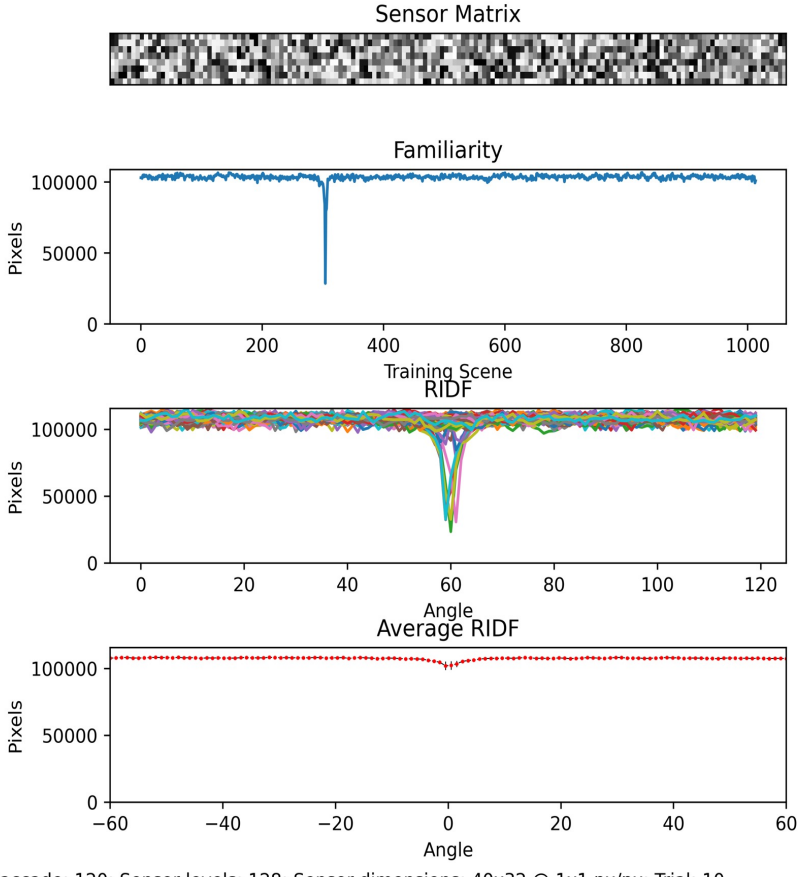


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2785.13; RMSD/dist: 6.963; TD: 1000; p90: 4; p50: 2; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4005.56; RMSD/dist: 10.014; TD: 1596; p90: 4; p50: 2; complete: 0