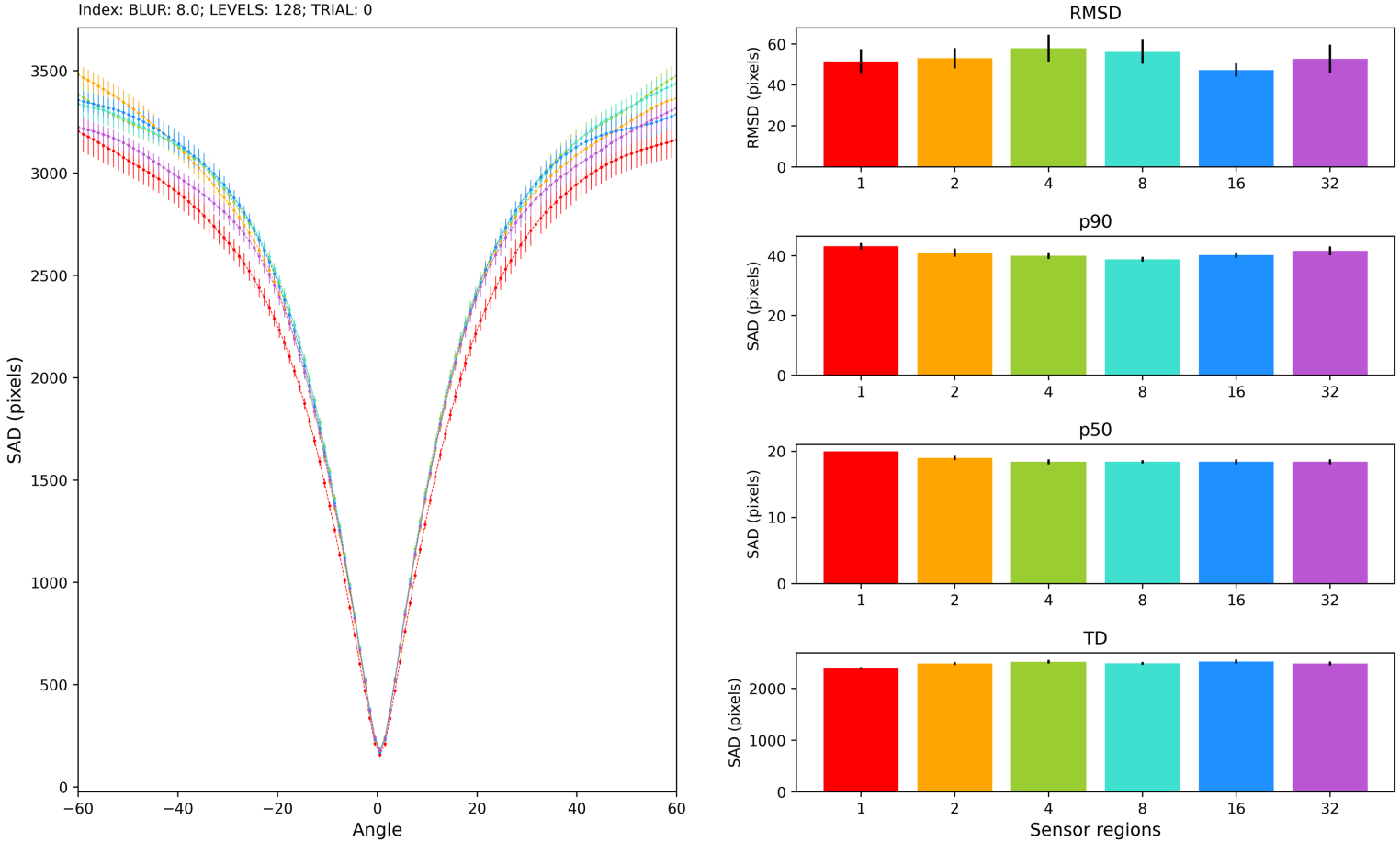
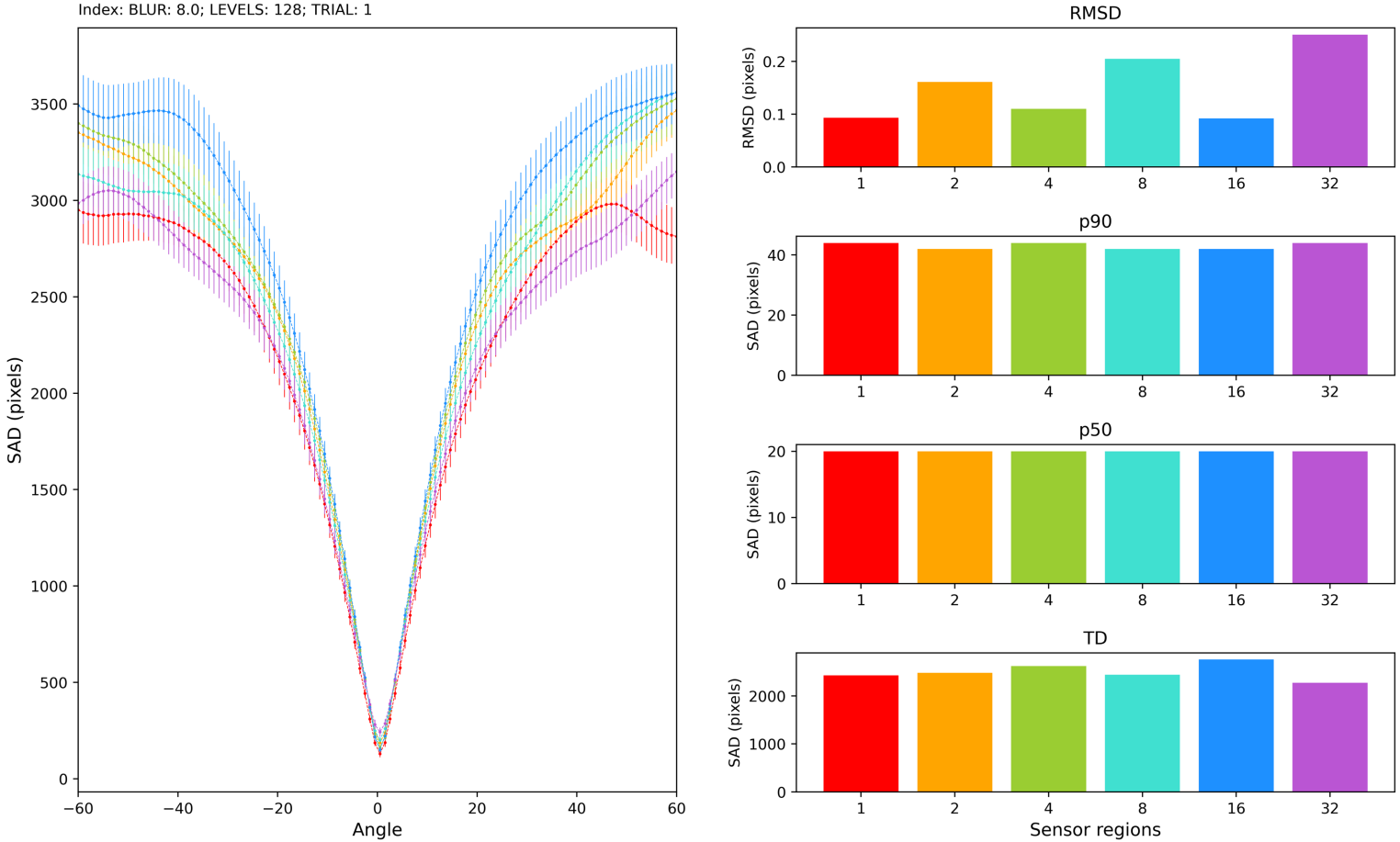
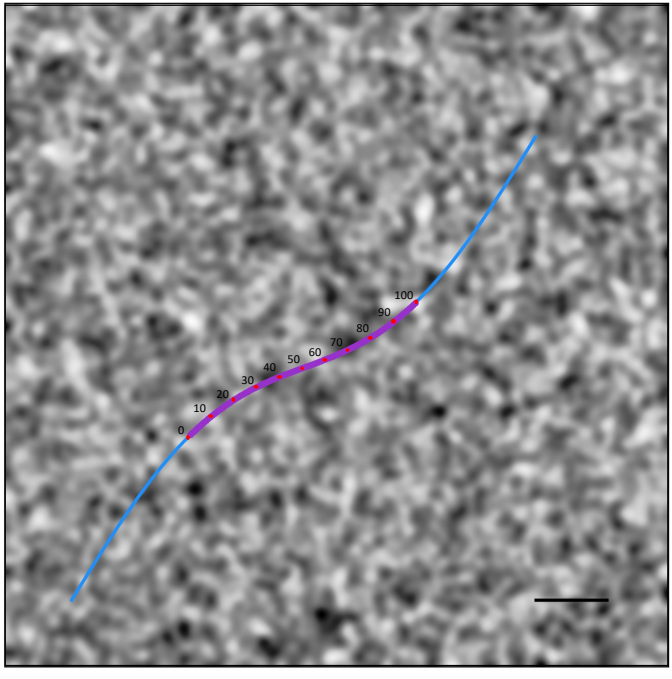
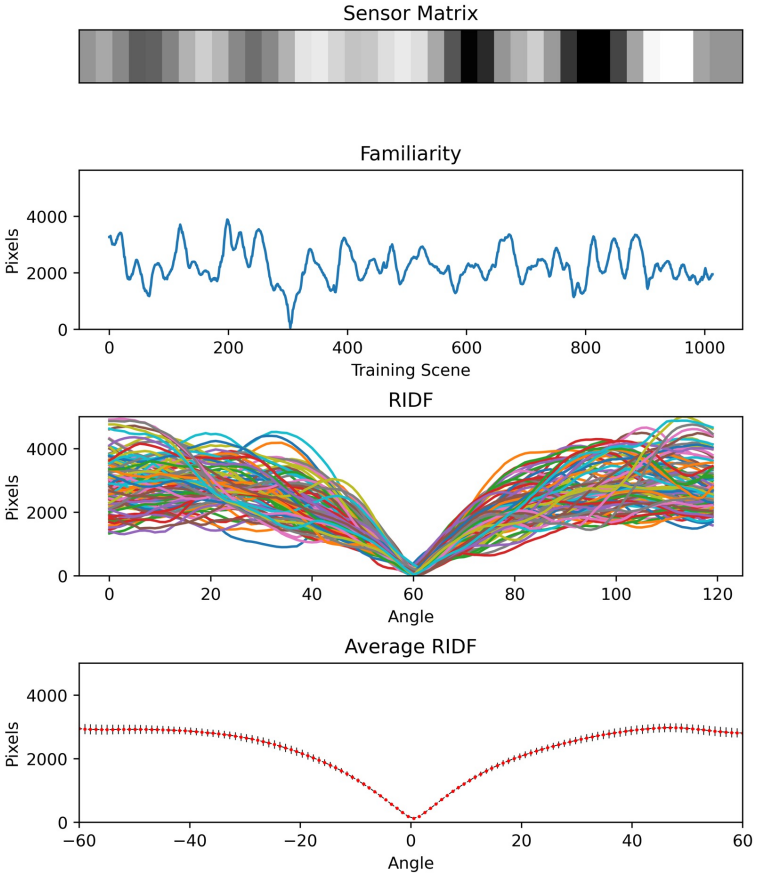

Index: BLUR: 8.0; LEVELS: 128; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 8.0; LEVELS: 128; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

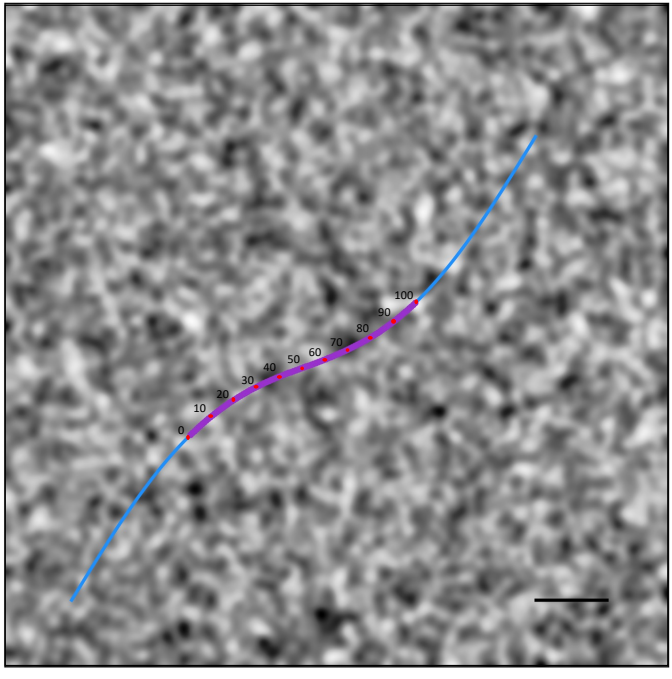


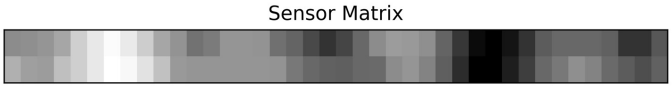


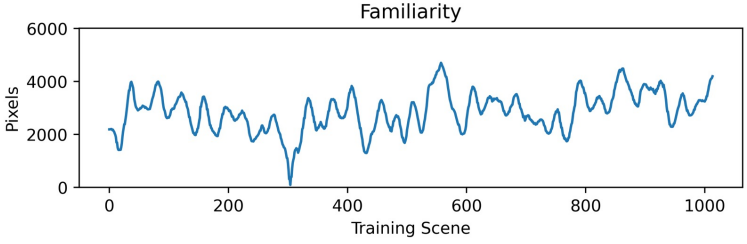
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

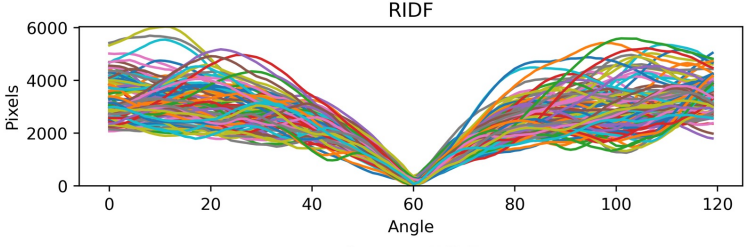
Navigation stats: RMSD error: 37.12; RMSD/dist: 0.093; TD: 2429; p90: 44; p50: 20; complete: 0

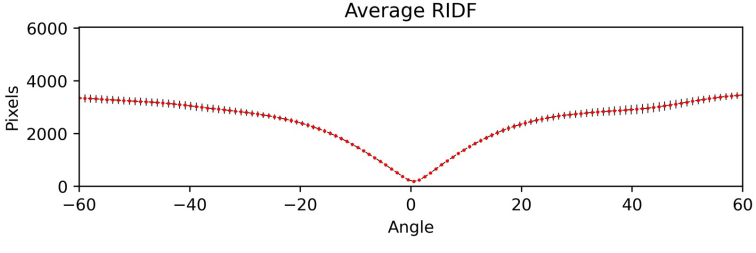
100%







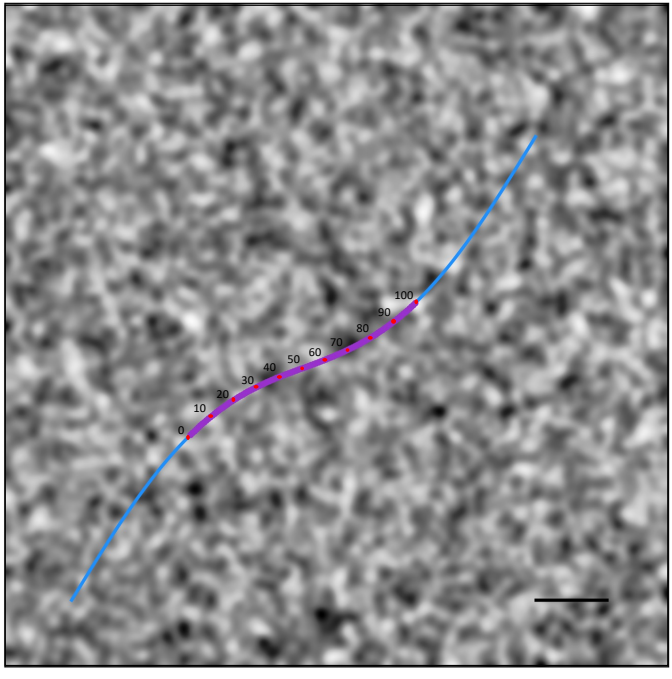


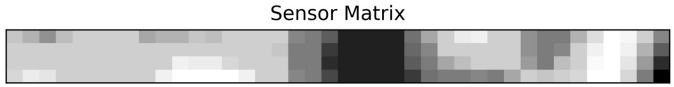


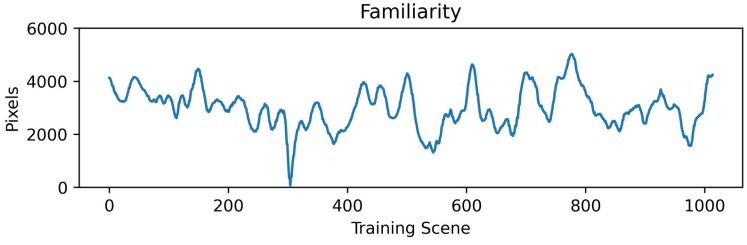
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

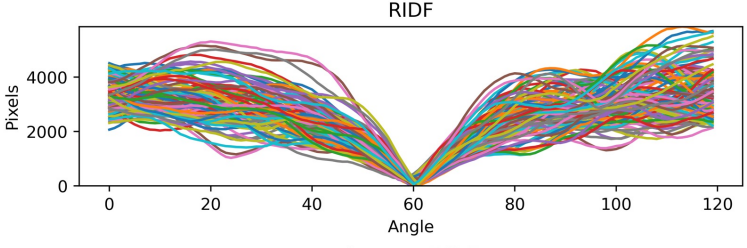
Navigation stats: RMSD error: 64.59; RMSD/dist: 0.161; TD: 2479; p90: 42; p50: 20; complete: 0

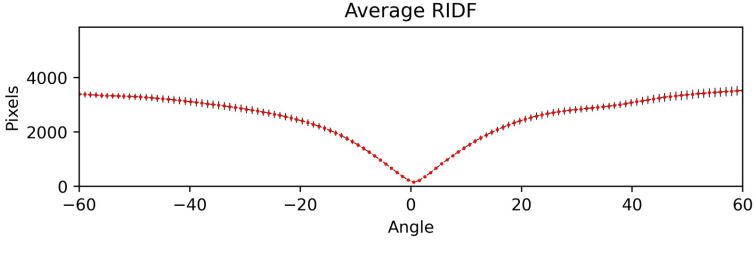
100%







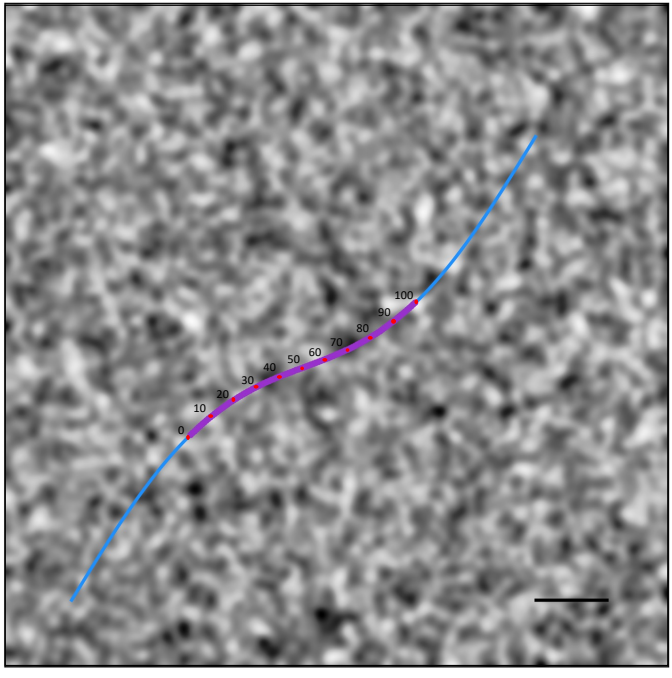


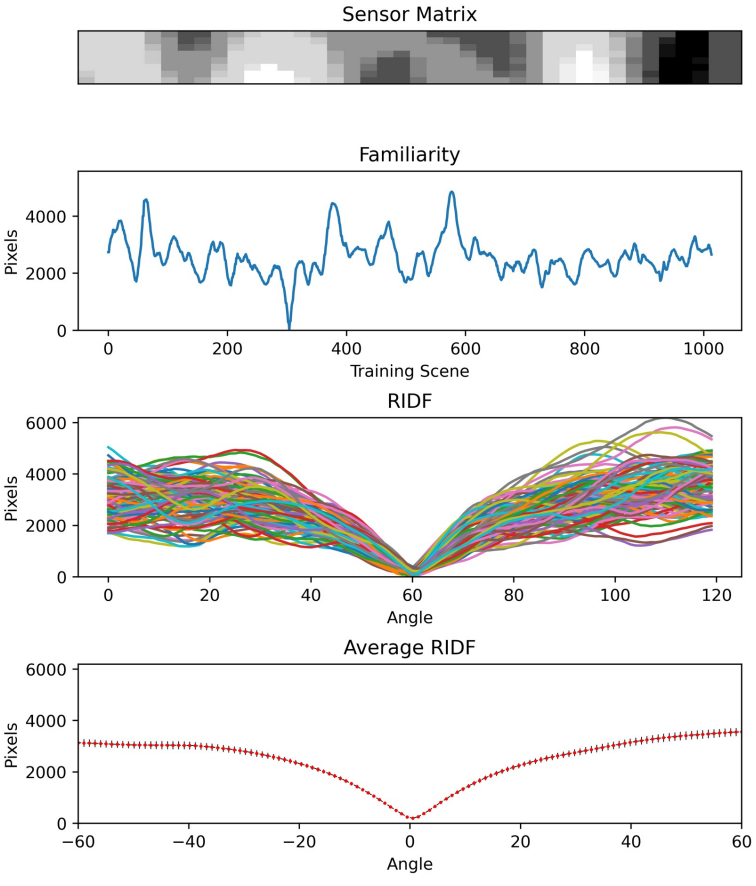


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 44.16; RMSD/dist: 0.110; TD: 2623; p90: 44; p50: 20; complete: 0

100%

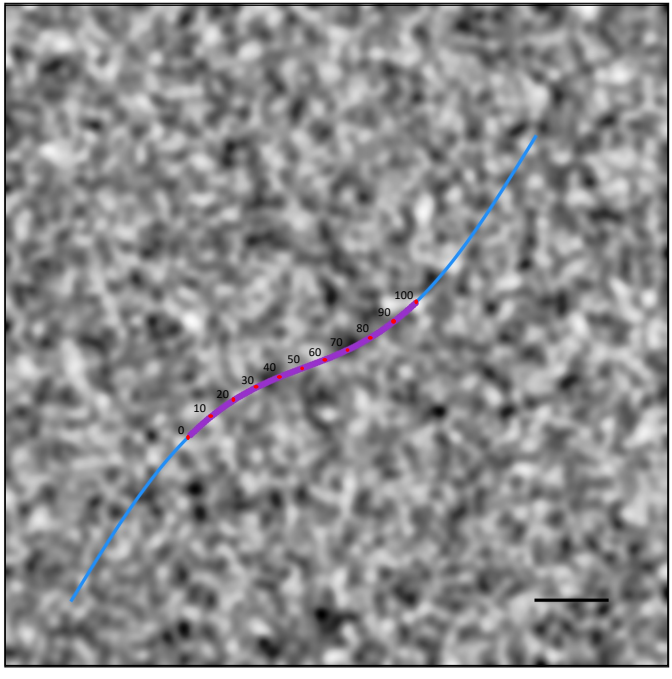


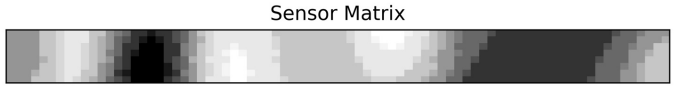


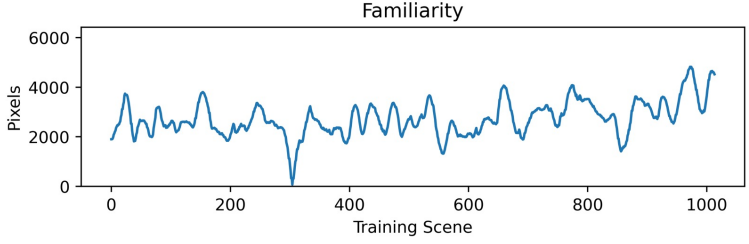
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

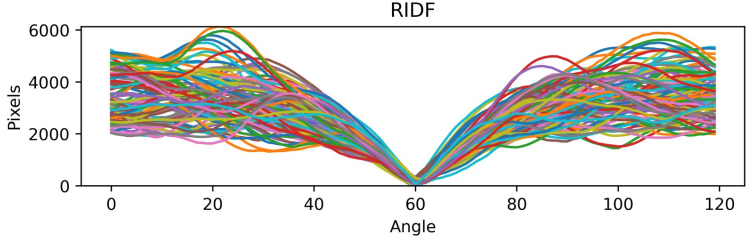
Navigation stats: RMSD error: 82.03; RMSD/dist: 0.205; TD: 2440; p90: 42; p50: 20; complete: 0

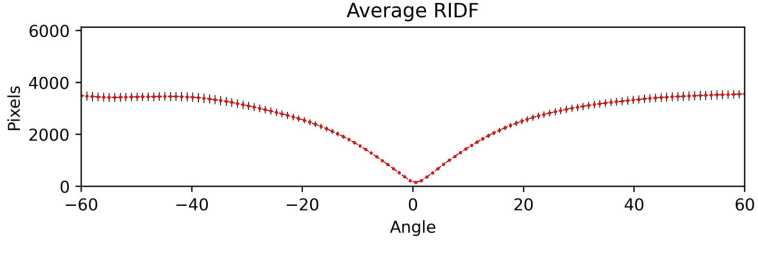
100%







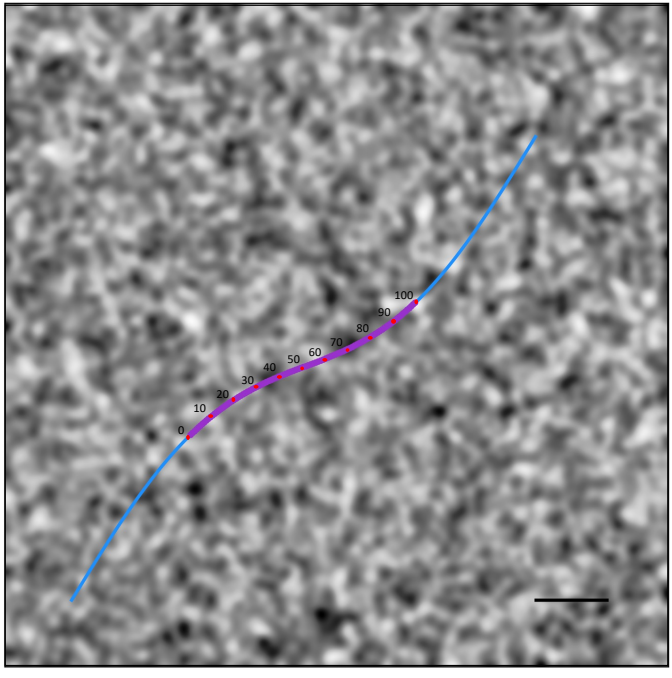


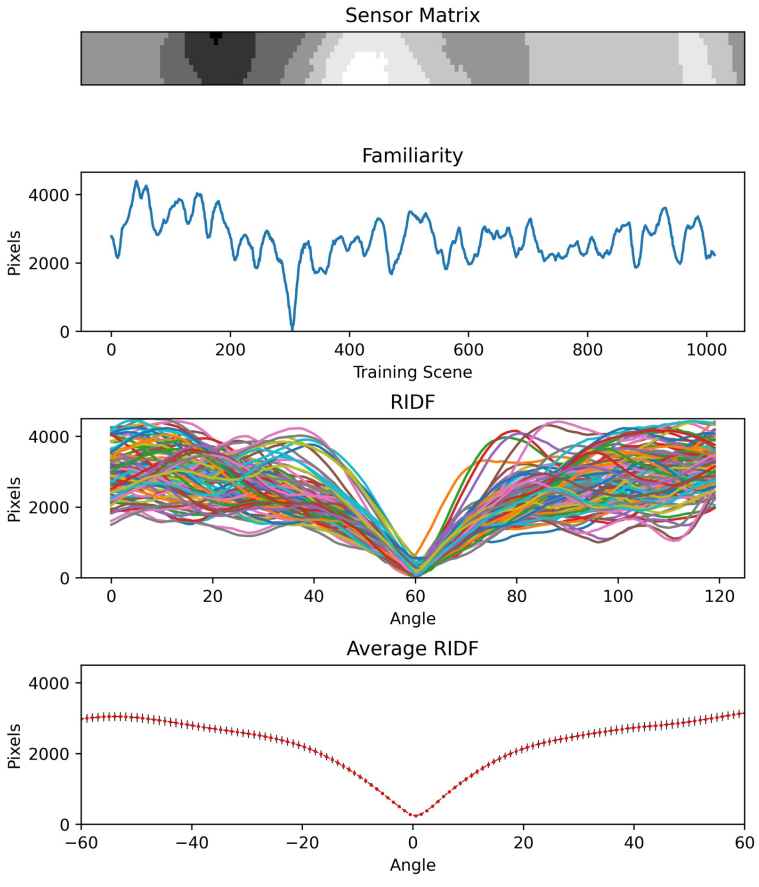


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 36.79; RMSD/dist: 0.092; TD: 2756; p90: 42; p50: 20; complete: 0

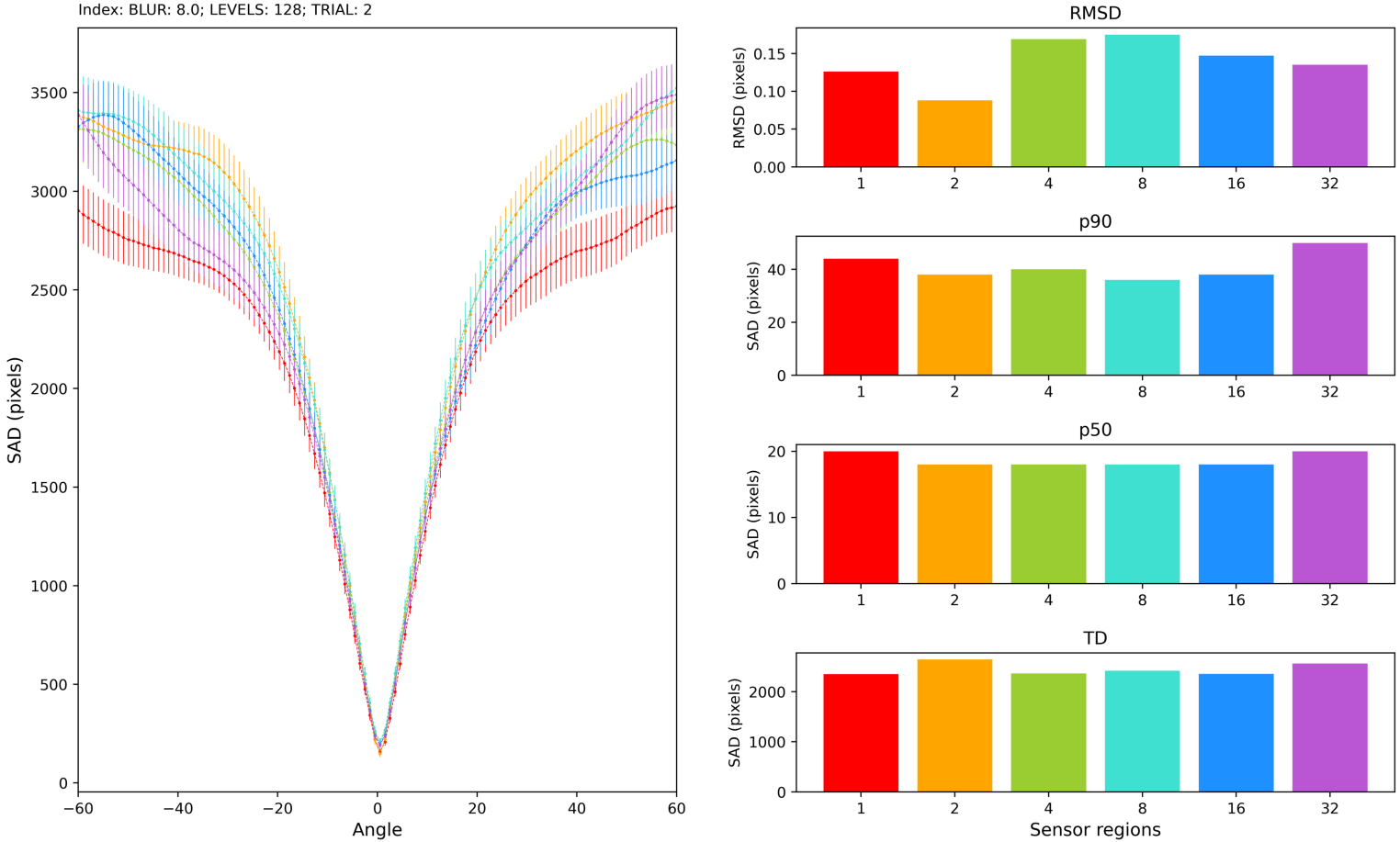
100%



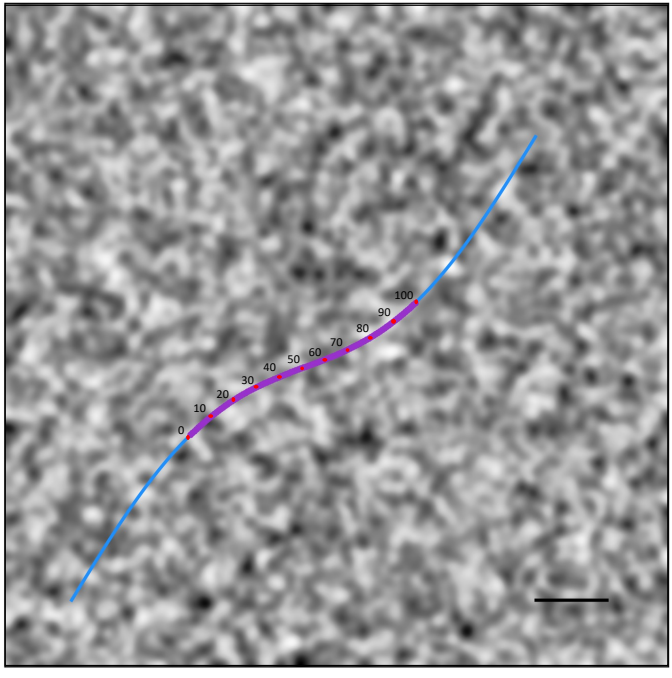


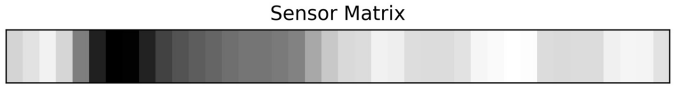
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

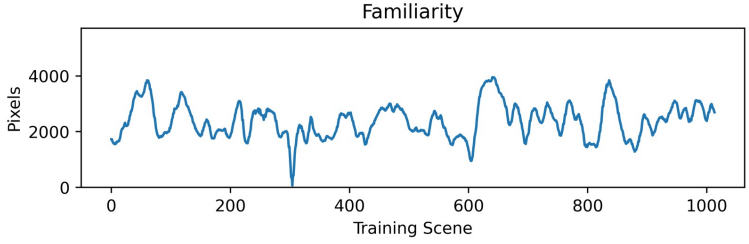
Navigation stats: RMSD error: 100.31; RMSD/dist: 0.251; TD: 2271; p90: 44; p50: 20; complete: 0

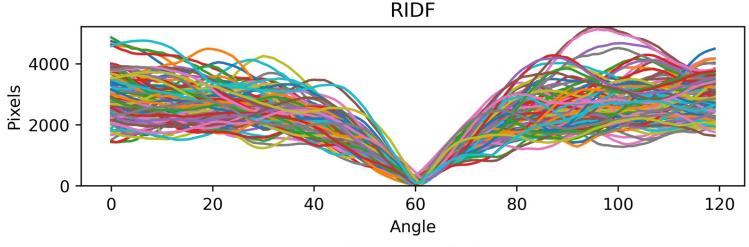

Index: BLUR: 8.0; LEVELS: 128; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

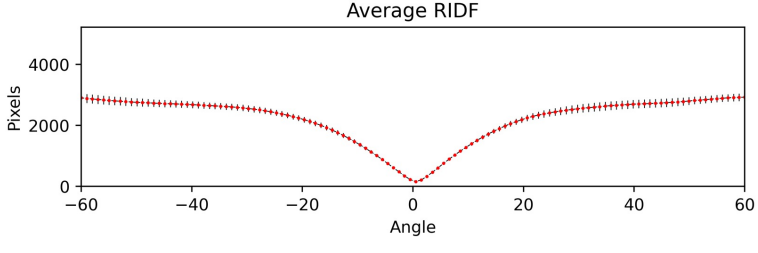
100%







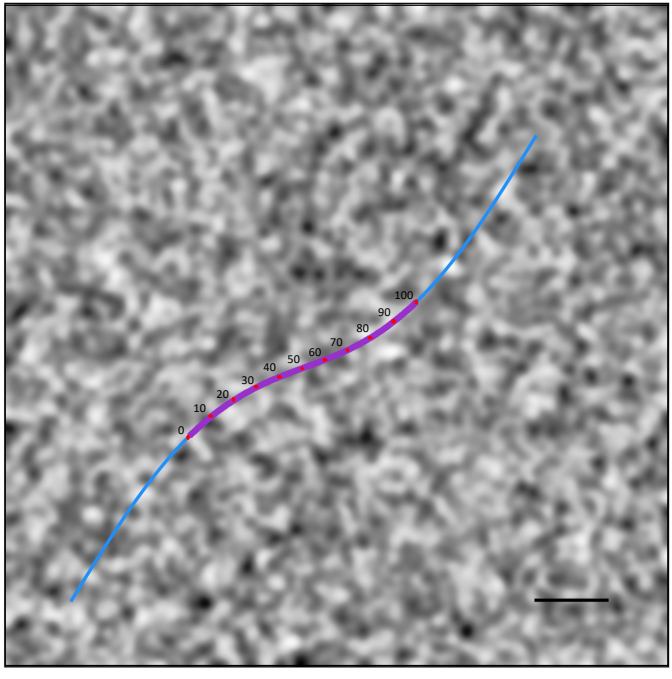


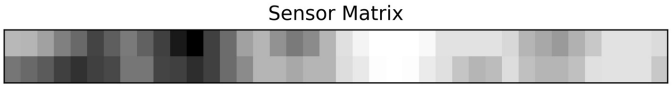


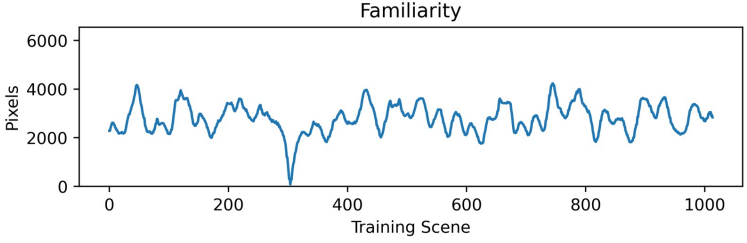
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

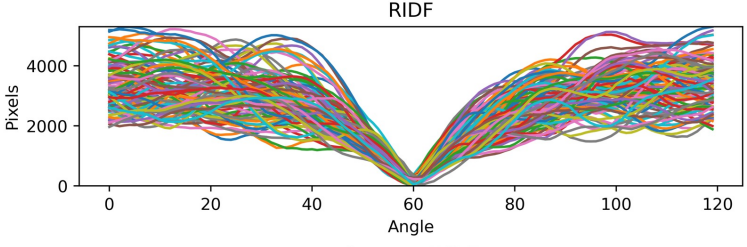
Navigation stats: RMSD error: 50.43; RMSD/dist: 0.126; TD: 2351; p90: 44; p50: 20; complete: 0

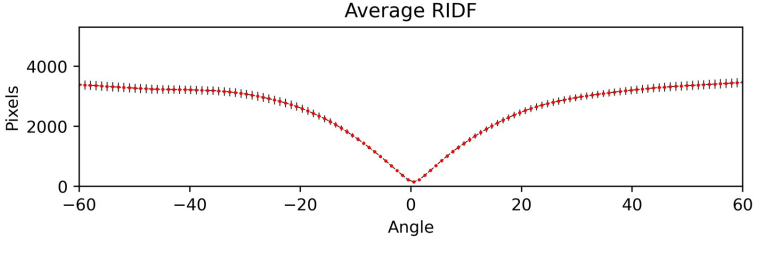
100%







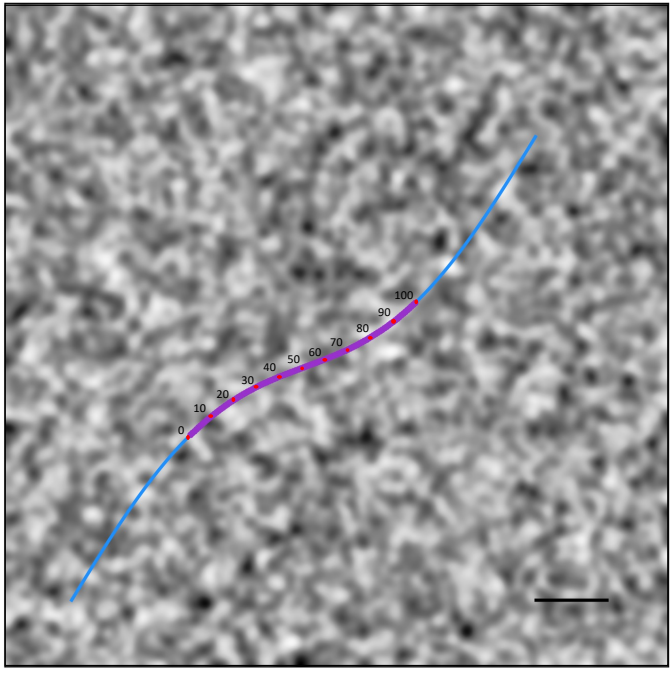


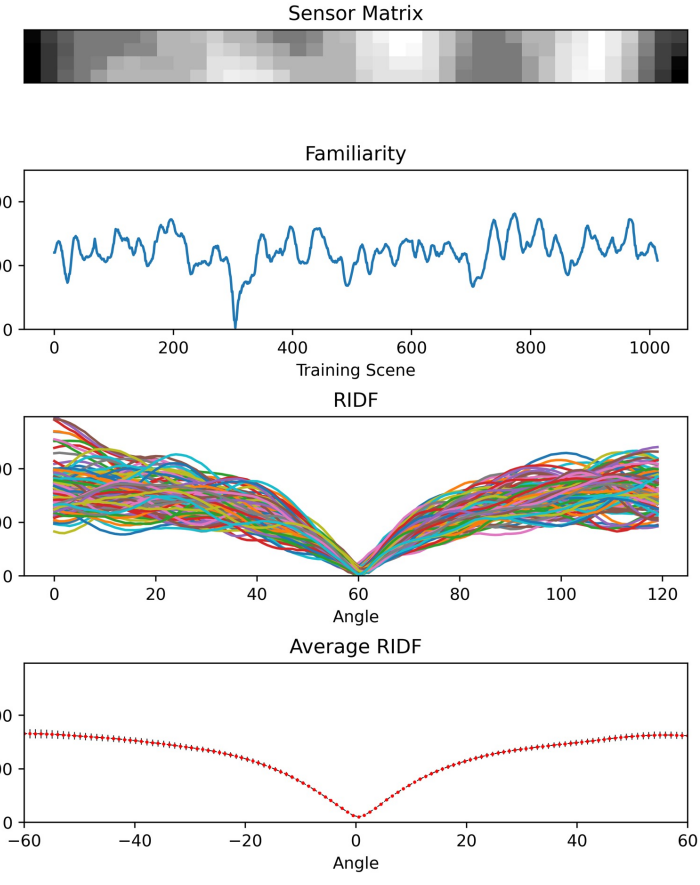


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 35.00; RMSD/dist: 0.088; TD: 2643; p90: 38; p50: 18; complete: 0

100%

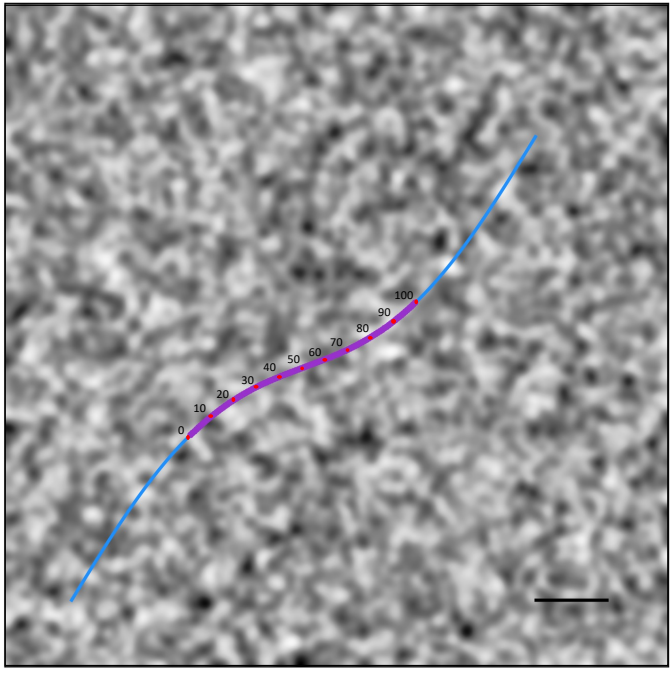


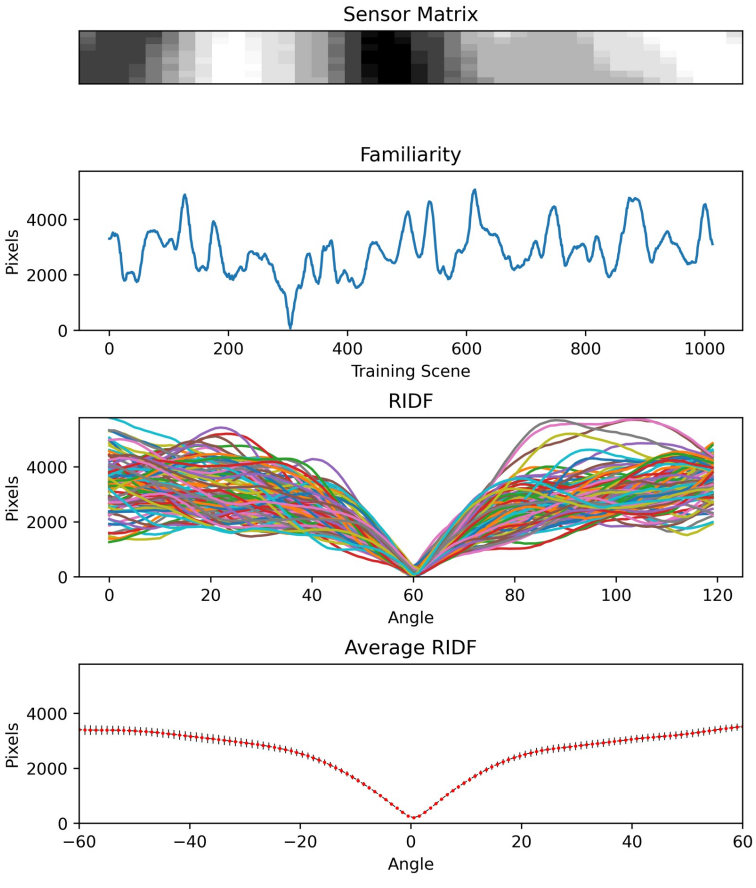


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 67.66; RMSD/dist: 0.169; TD: 2365; p90: 40; p50: 18; complete: 0

100%

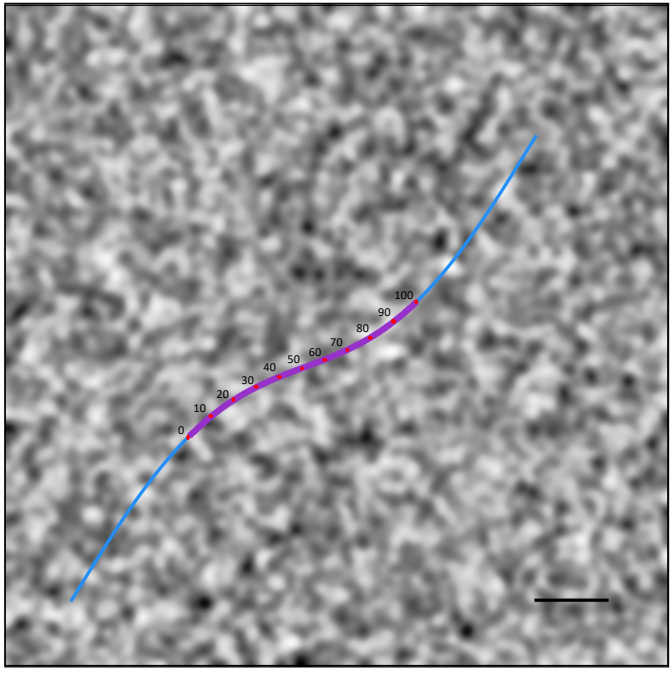


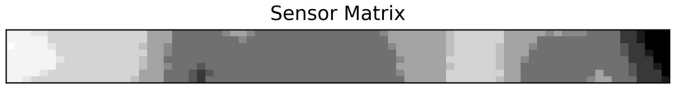


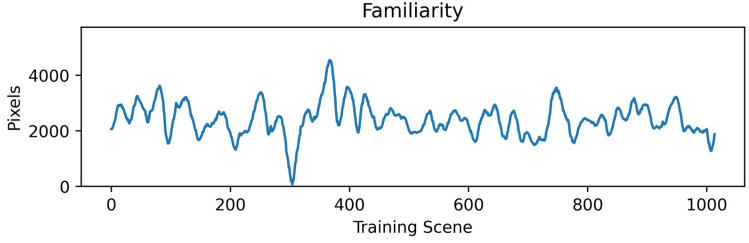
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

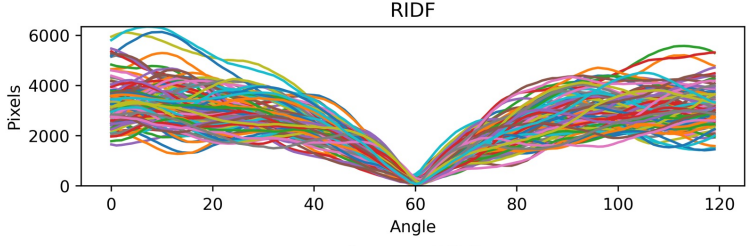
Navigation stats: RMSD error: 69.95; RMSD/dist: 0.175; TD: 2420; p90: 36; p50: 18; complete: 0

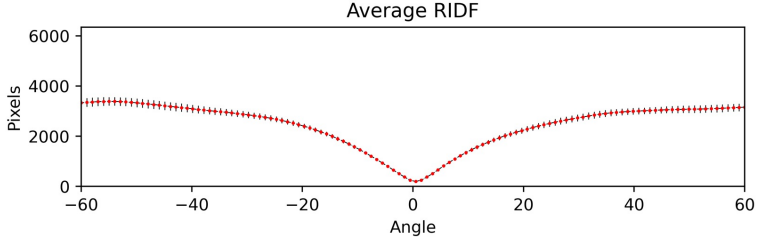
100%







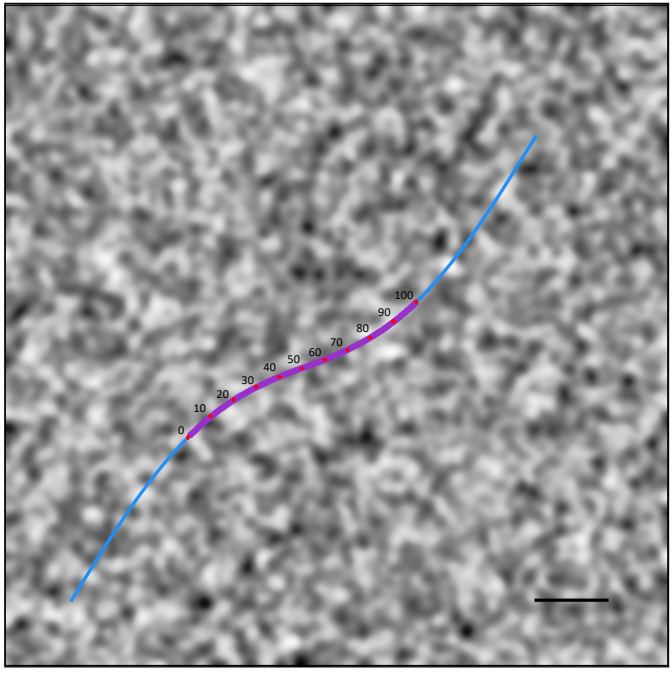


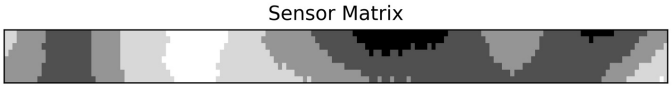


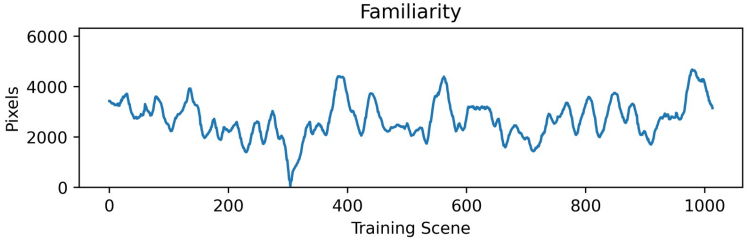
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

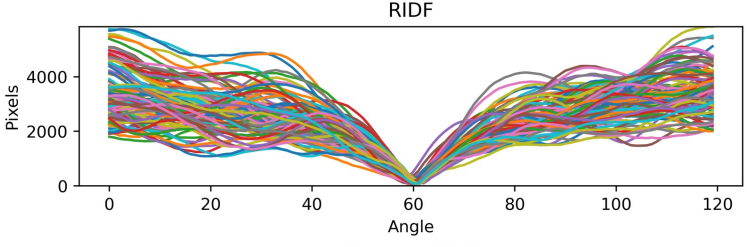
Navigation stats: RMSD error: 58.93; RMSD/dist: 0.147; TD: 2357; p90: 38; p50: 18; complete: 0

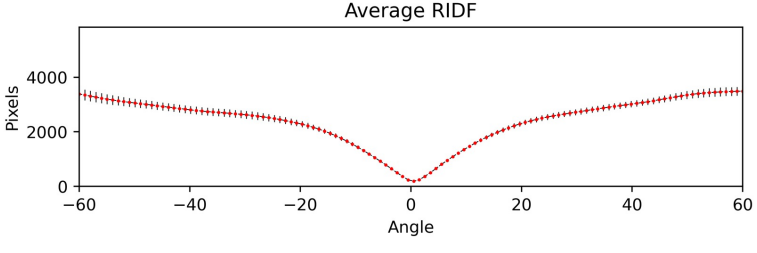
100%





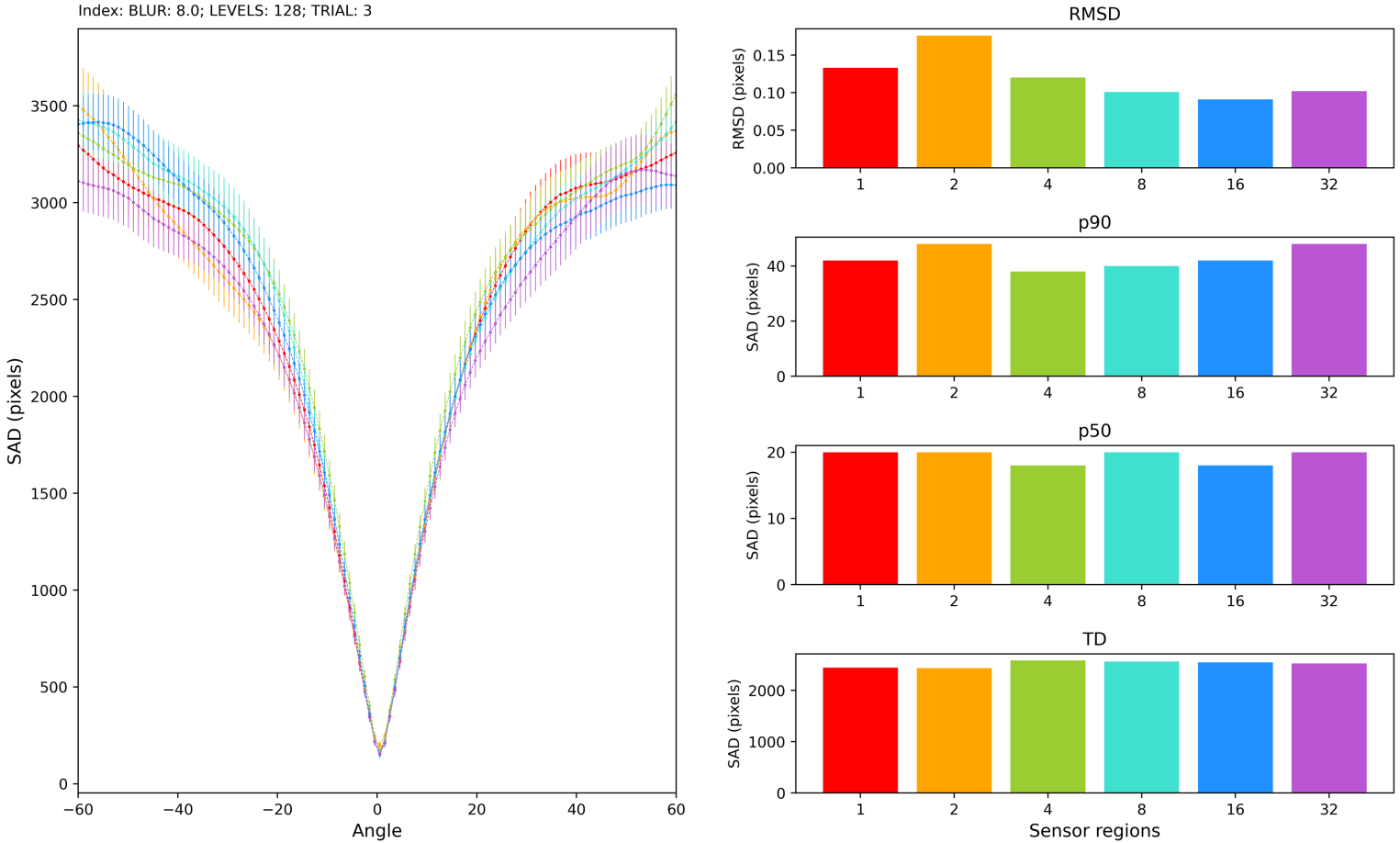




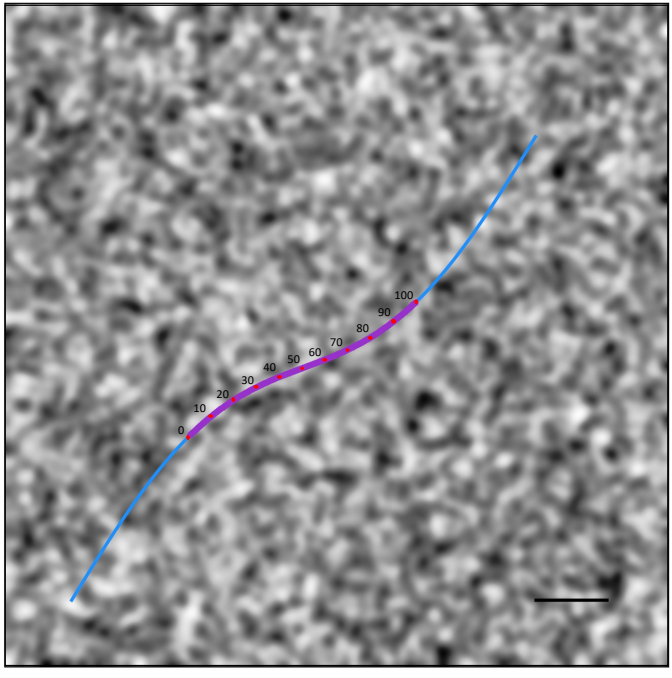


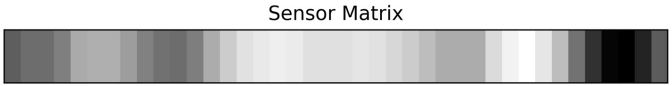
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

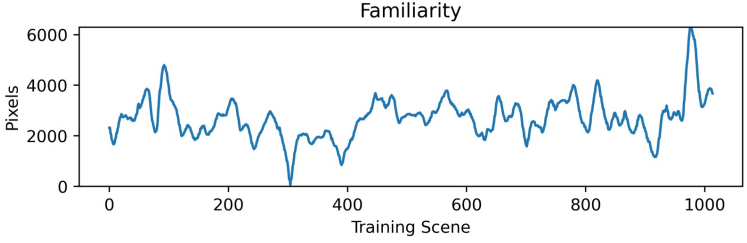
Navigation stats: RMSD error: 53.83; RMSD/dist: 0.135; TD: 2563; p90: 50; p50: 20; complete: 0

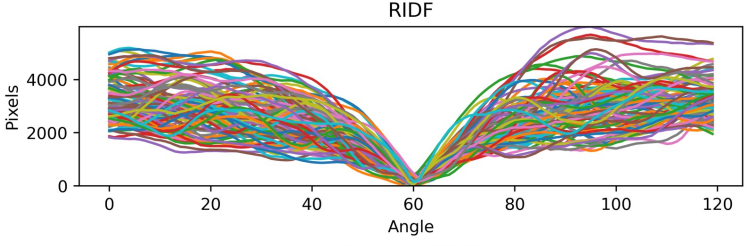

Index: BLUR: 8.0; LEVELS: 128; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

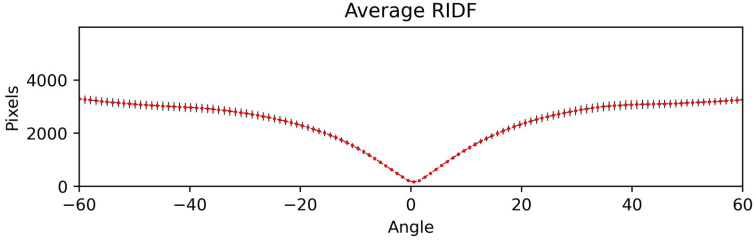
100%







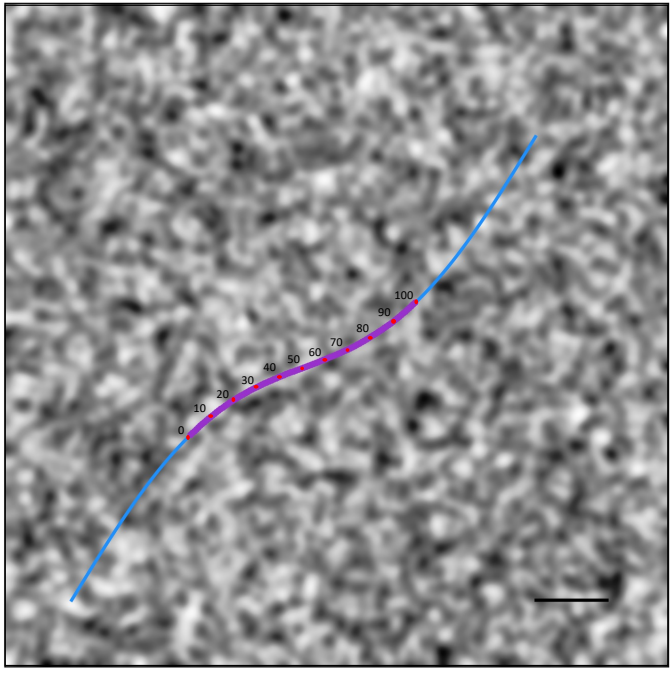


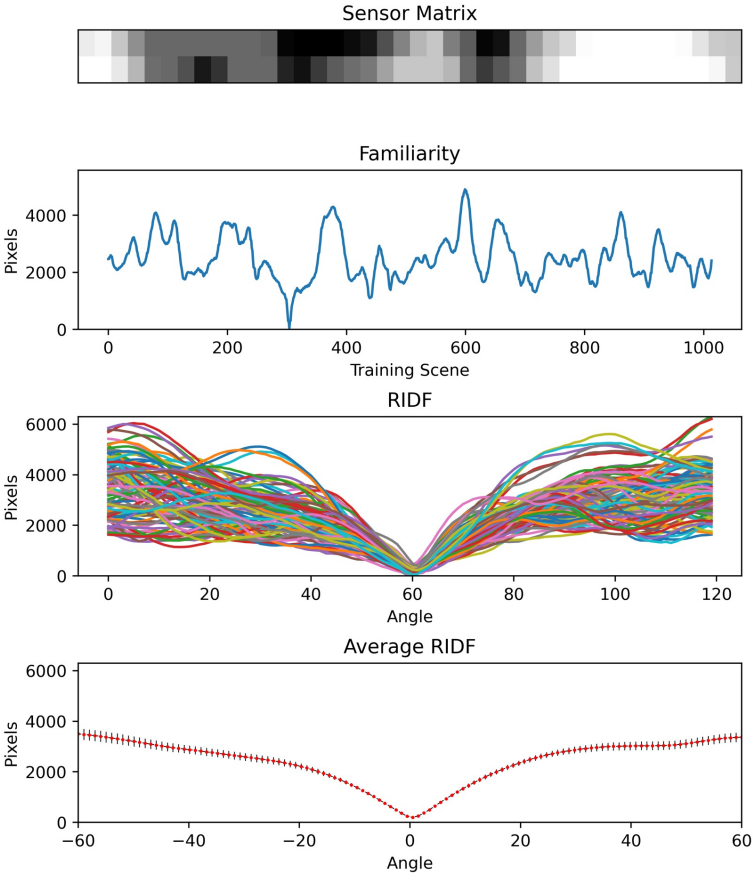


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 53.24; RMSD/dist: 0.133; TD: 2442; p90: 42; p50: 20; complete: 0

100%

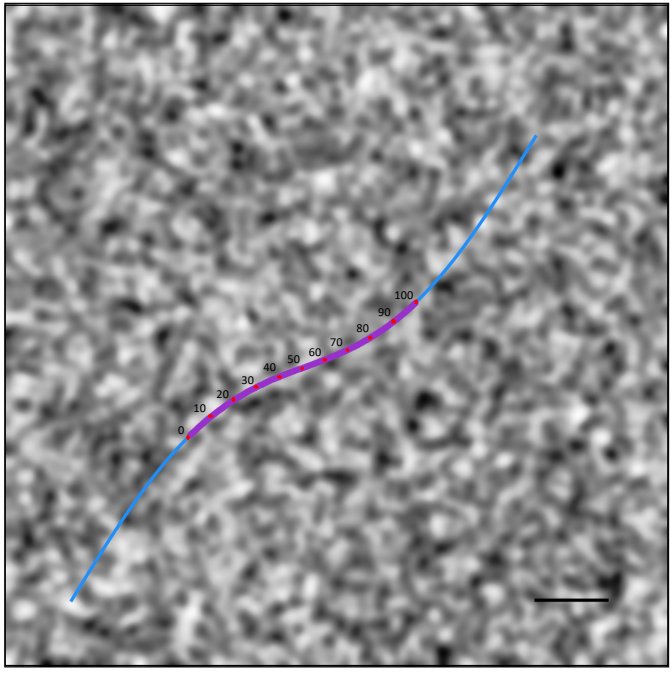


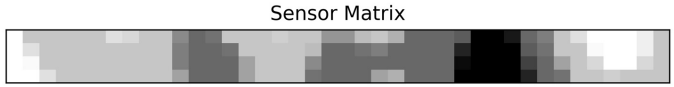


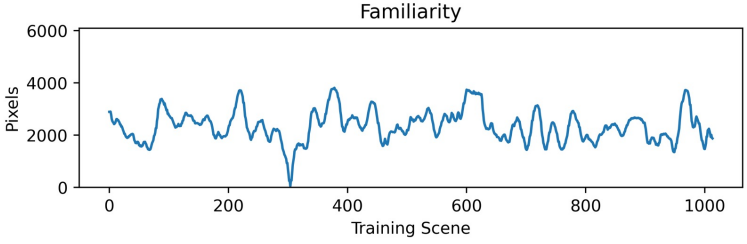
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

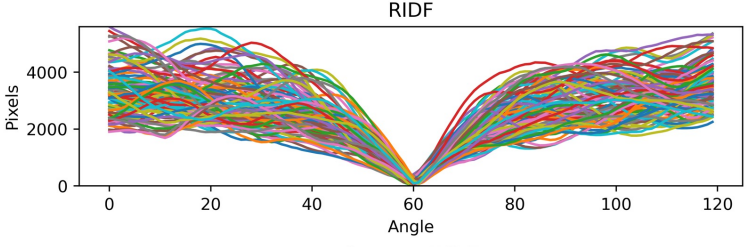
Navigation stats: RMSD error: 70.28; RMSD/dist: 0.176; TD: 2436; p90: 48; p50: 20; complete: 0

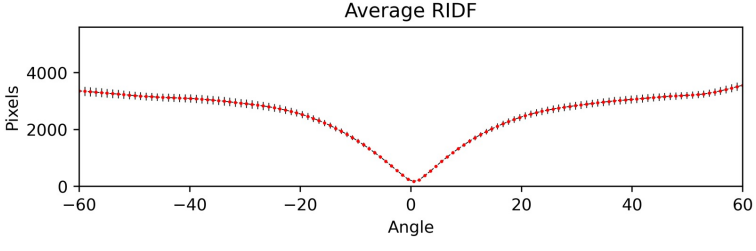
100%







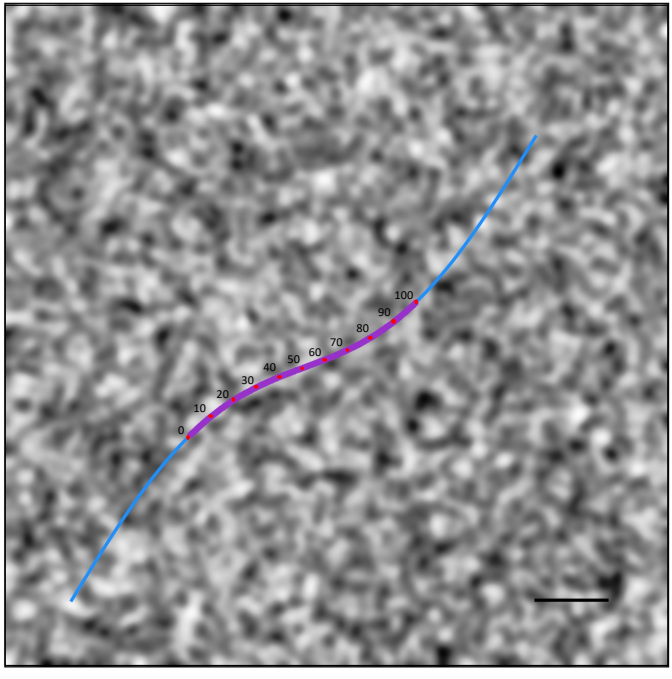


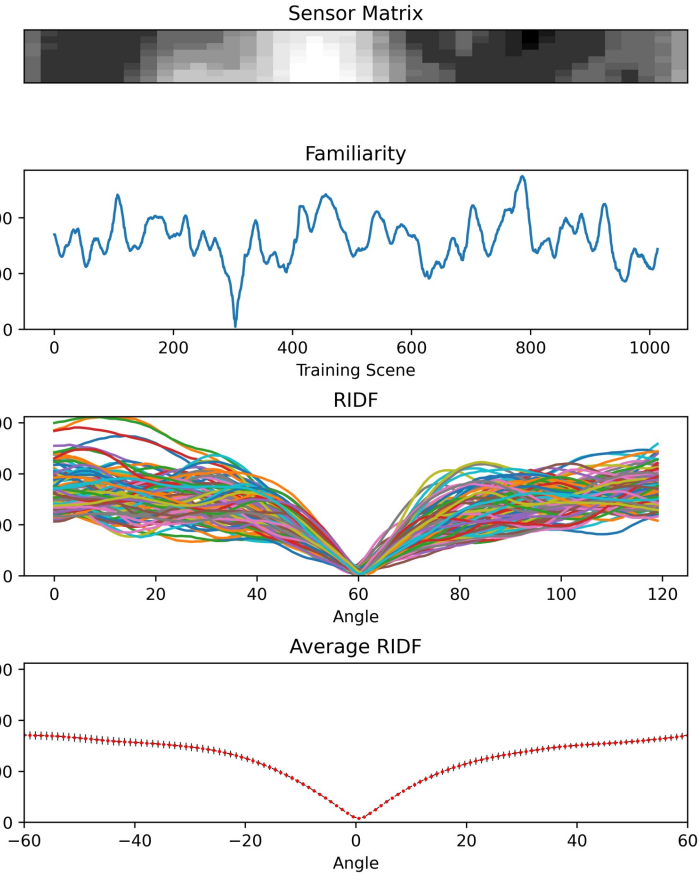


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 47.99; RMSD/dist: 0.120; TD: 2582; p90: 38; p50: 18; complete: 0

100%

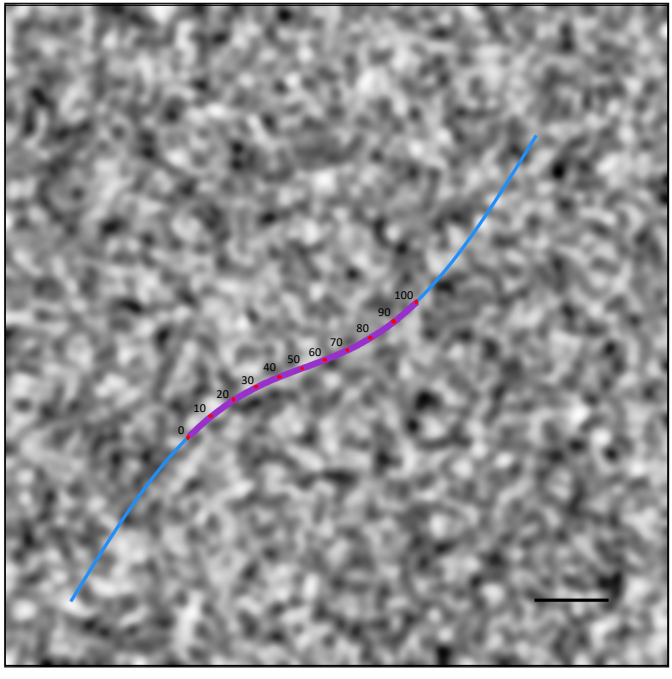


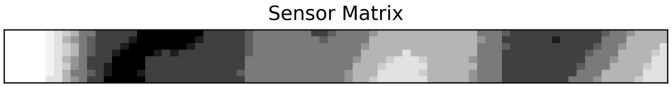


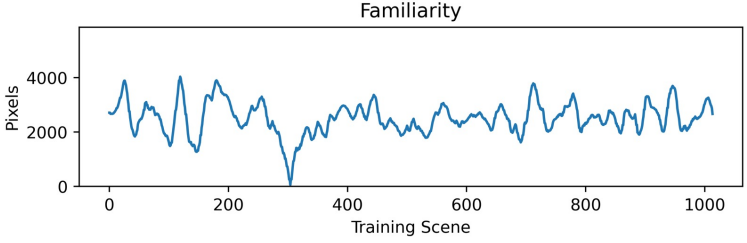
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

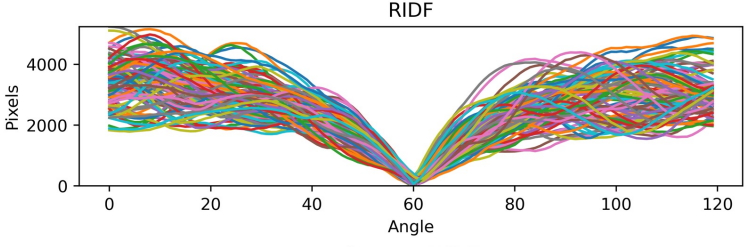
Navigation stats: RMSD error: 40.43; RMSD/dist: 0.101; TD: 2564; p90: 40; p50: 20; complete: 0

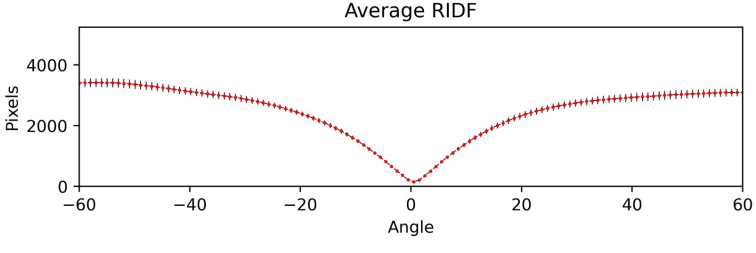
100%







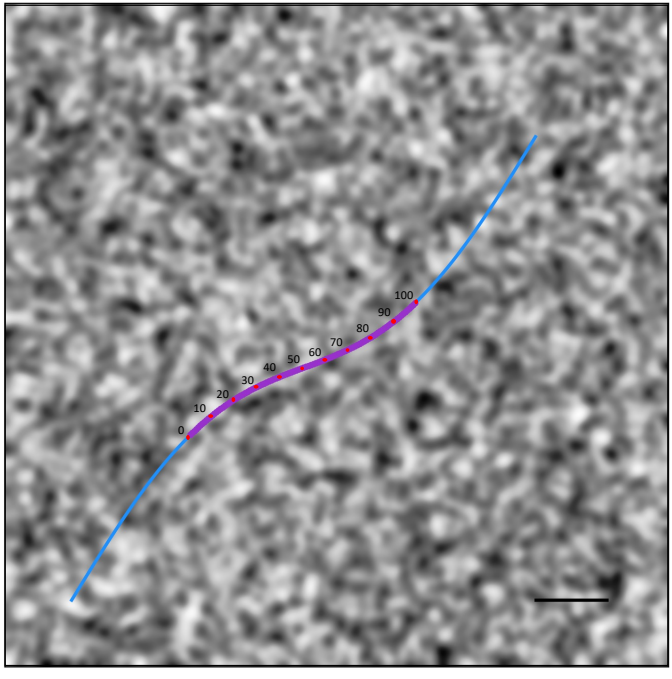


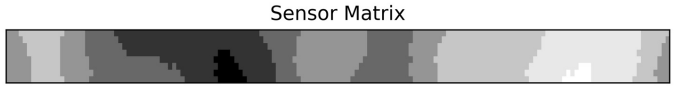


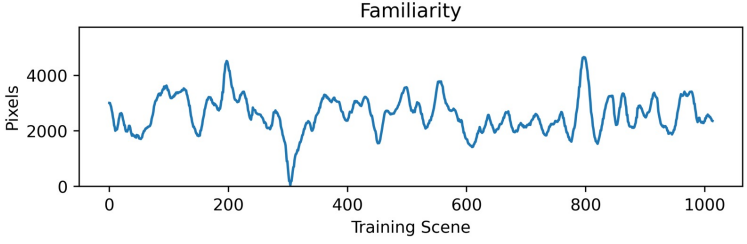
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

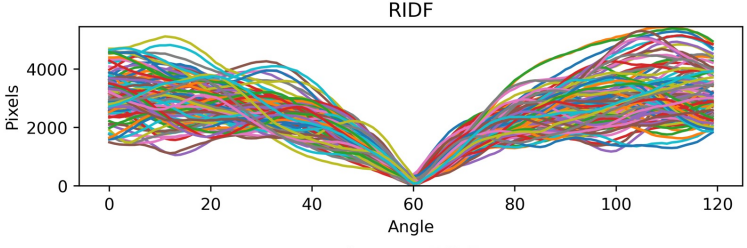
Navigation stats: RMSD error: 36.54; RMSD/dist: 0.091; TD: 2547; p90: 42; p50: 18; complete: 0

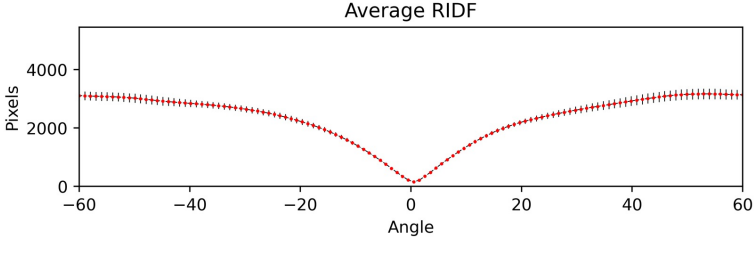
100%





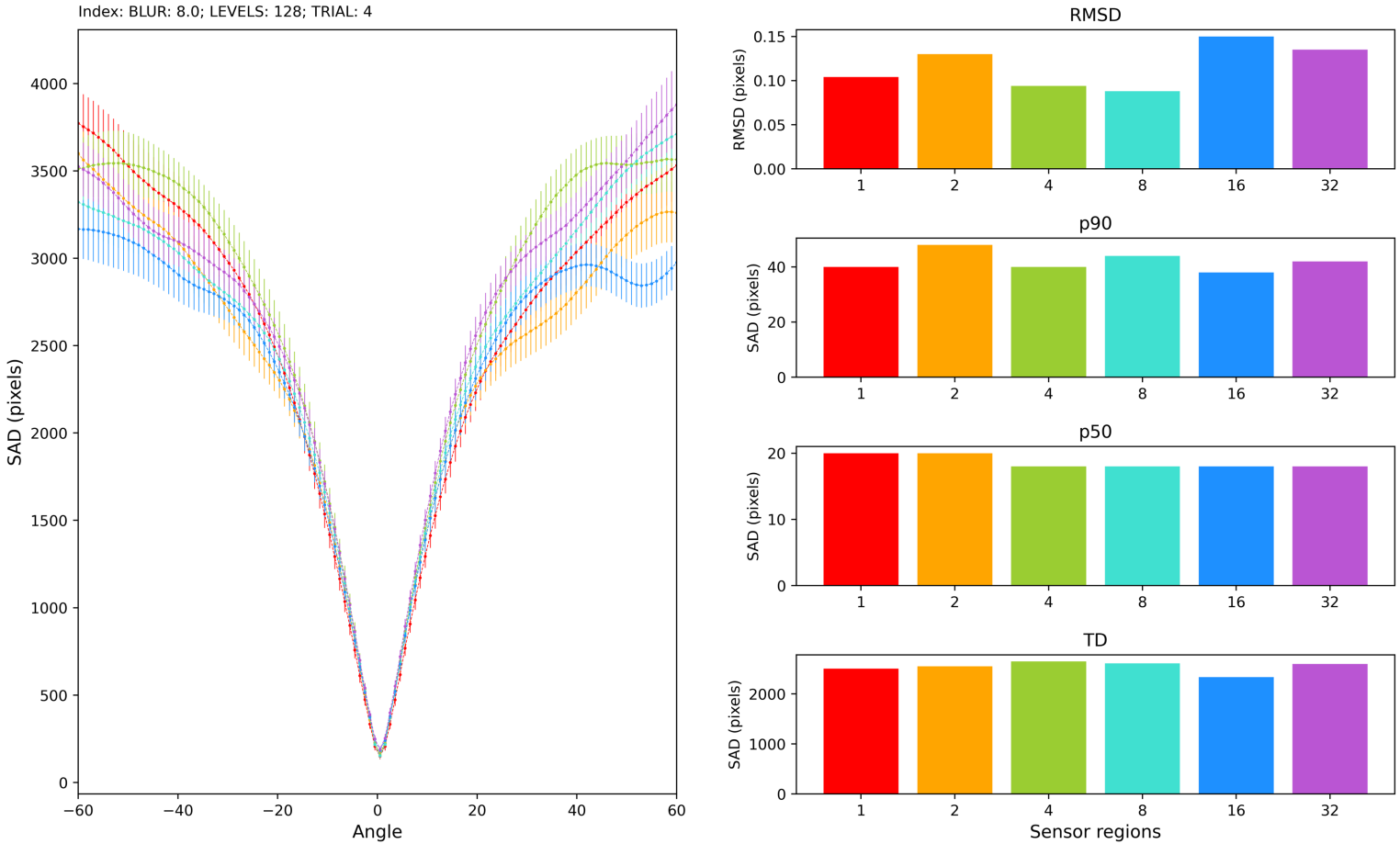




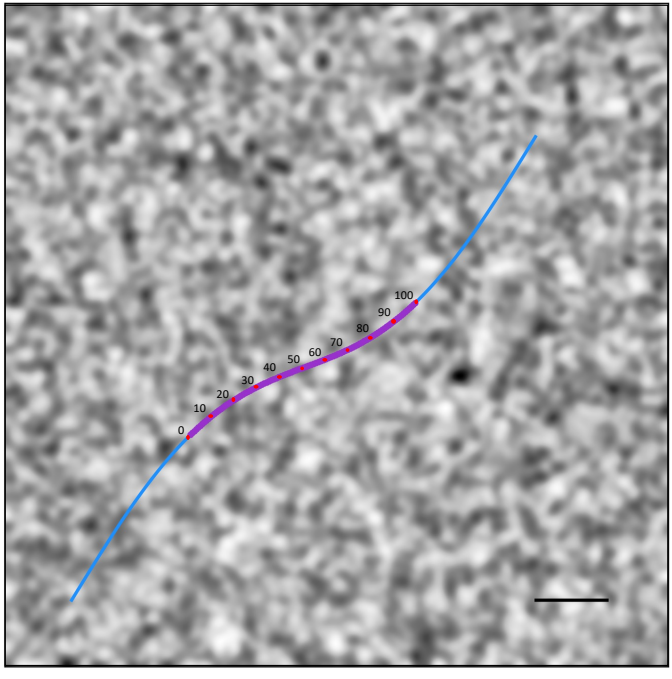


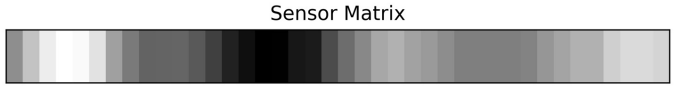
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

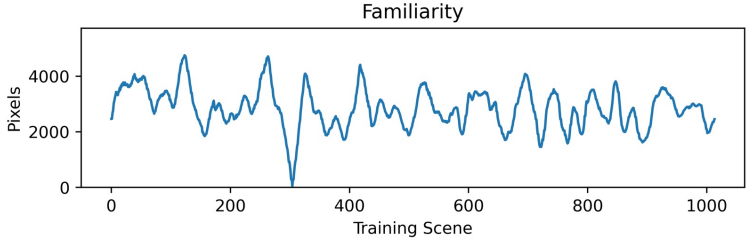
Navigation stats: RMSD error: 40.73; RMSD/dist: 0.102; TD: 2526; p90: 48; p50: 20; complete: 0

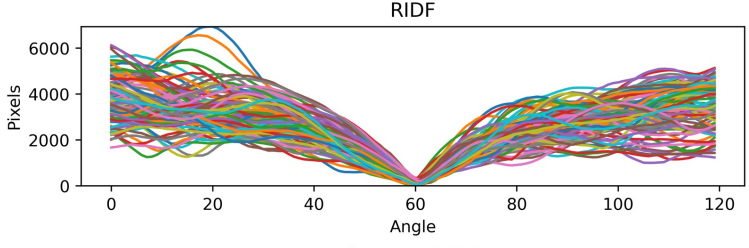

Index: BLUR: 8.0; LEVELS: 128; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

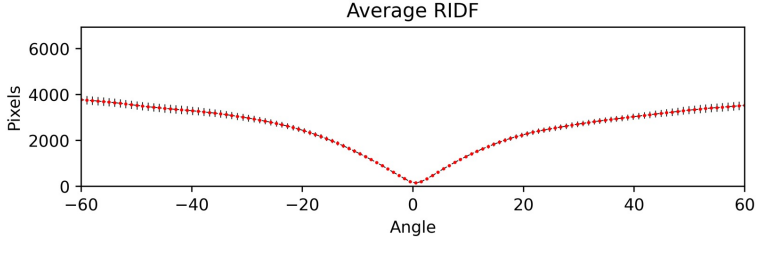
100%







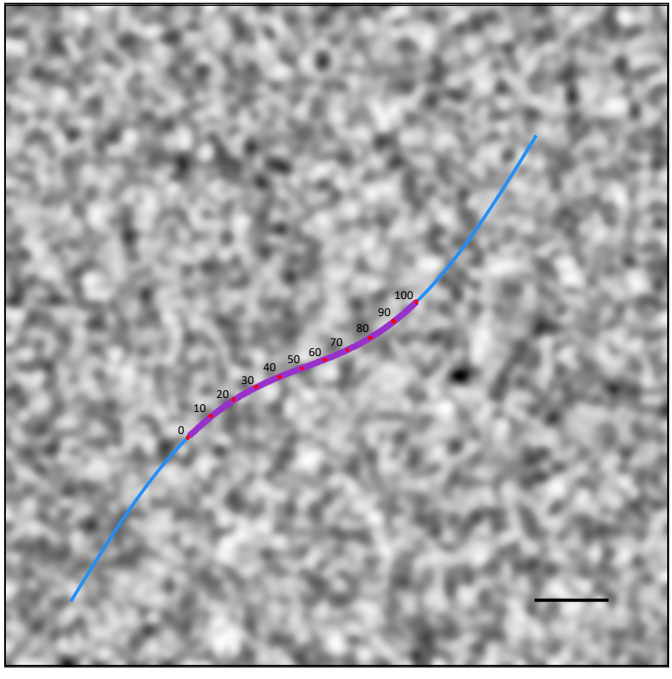


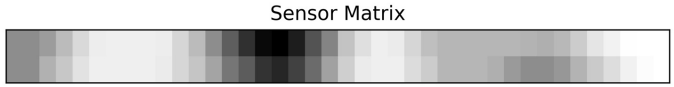


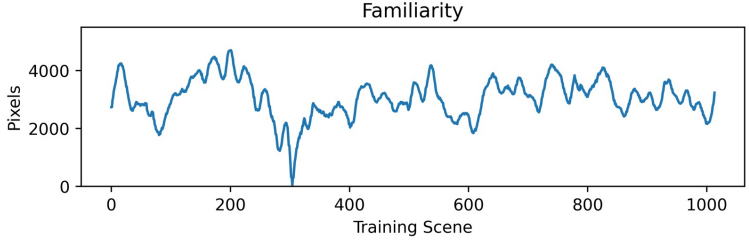
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

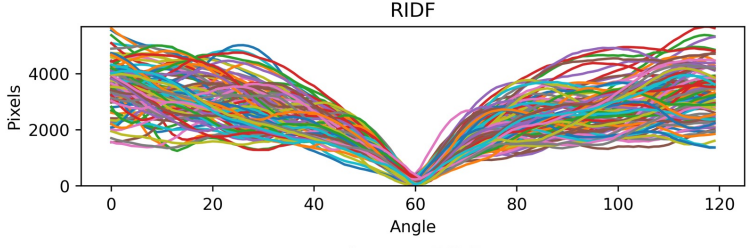
Navigation stats: RMSD error: 41.48; RMSD/dist: 0.104; TD: 2504; p90: 40; p50: 20; complete: 0

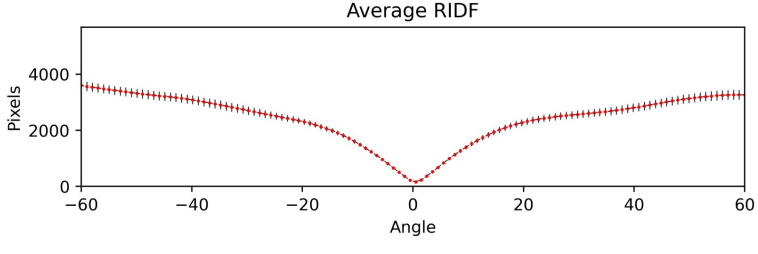
100%







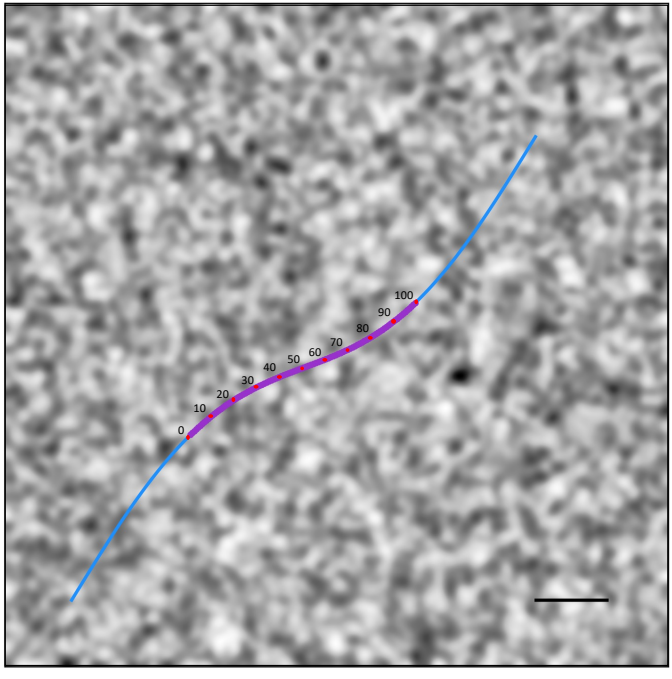


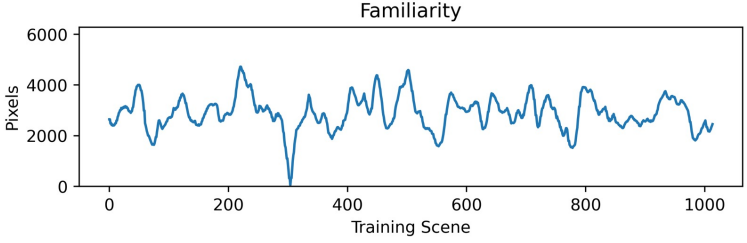


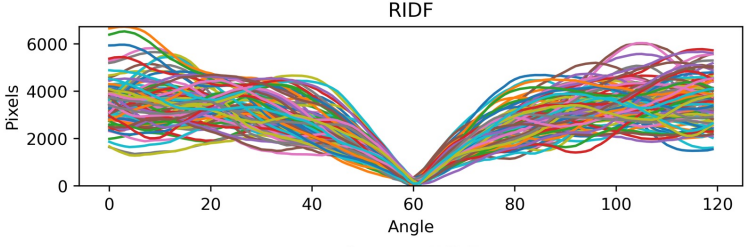
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

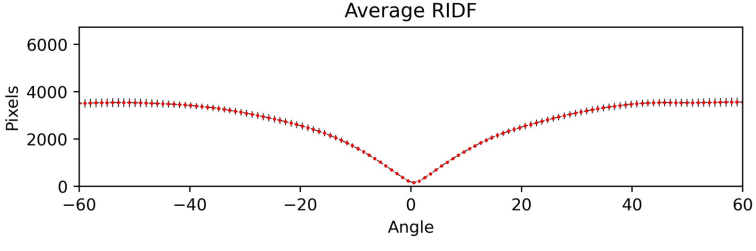
Navigation stats: RMSD error: 52.09; RMSD/dist: 0.130; TD: 2552; p90: 48; p50: 20; complete: 0

100%





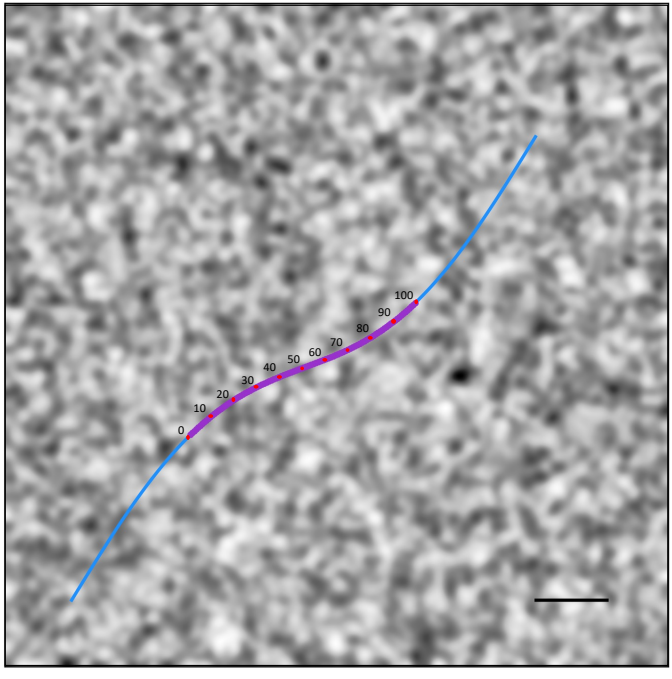


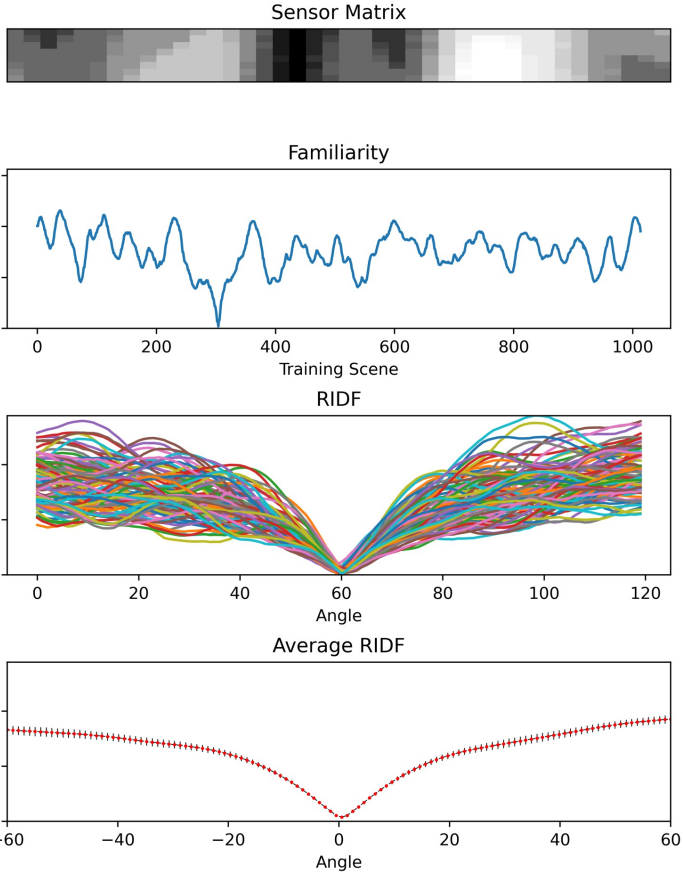


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 37.78; RMSD/dist: 0.094; TD: 2648; p90: 40; p50: 18; complete: 0

100%

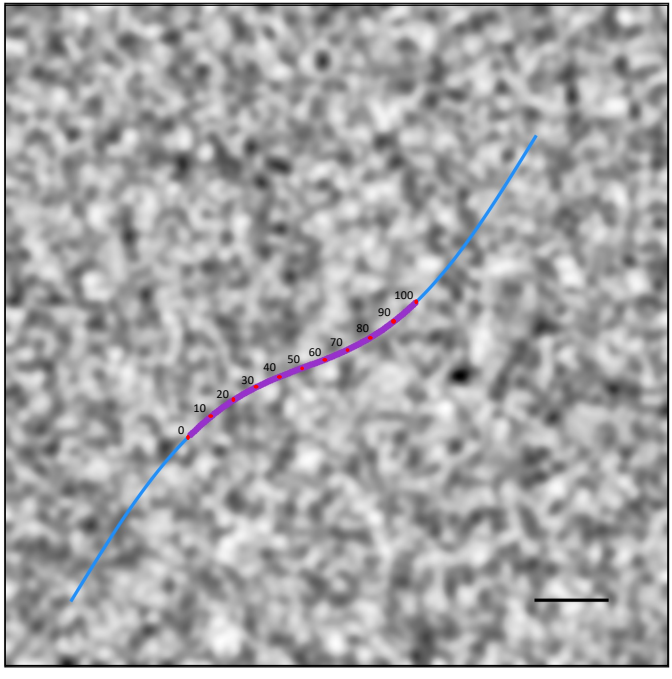


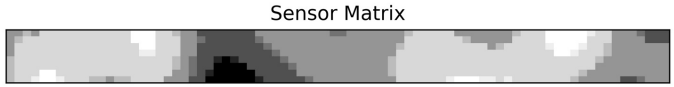


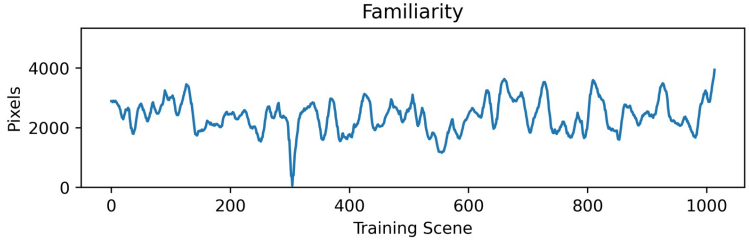
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

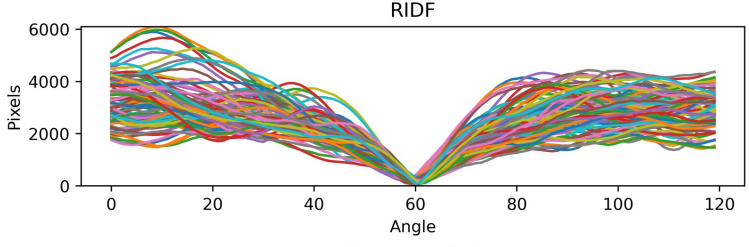
Navigation stats: RMSD error: 35.33; RMSD/dist: 0.088; TD: 2613; p90: 44; p50: 18; complete: 0

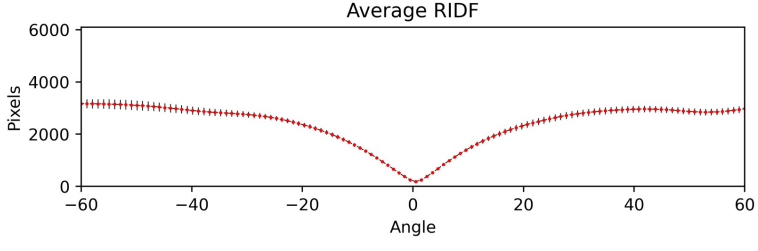
100%







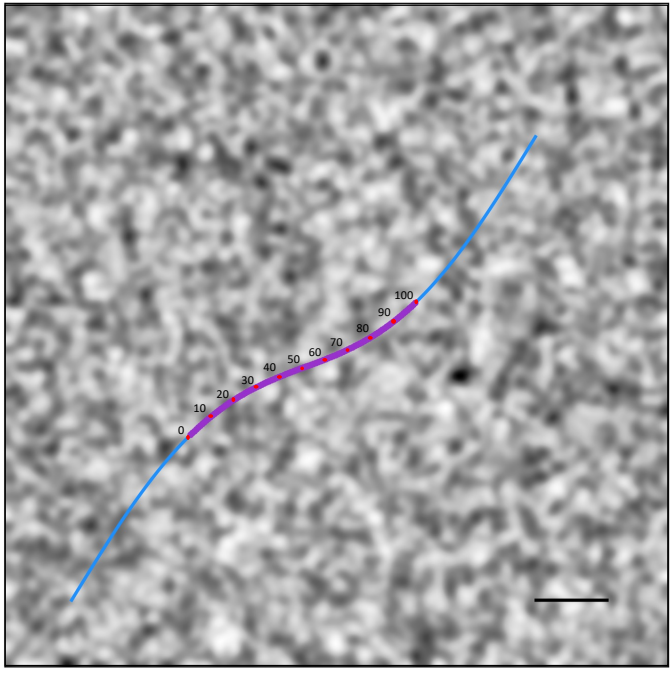


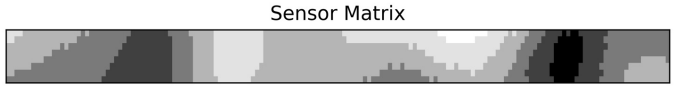


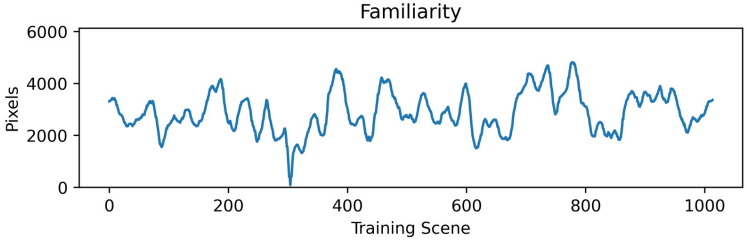
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

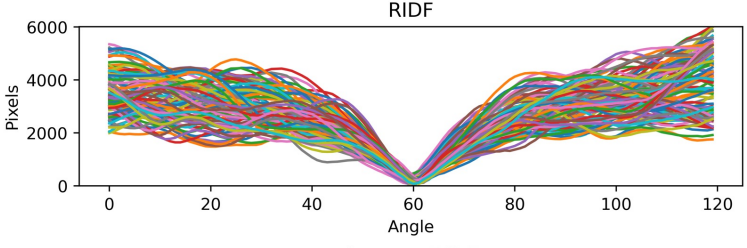
Navigation stats: RMSD error: 60.03; RMSD/dist: 0.150; TD: 2336; p90: 38; p50: 18; complete: 0

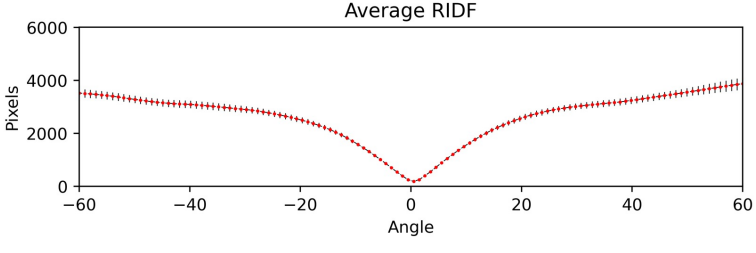
100%





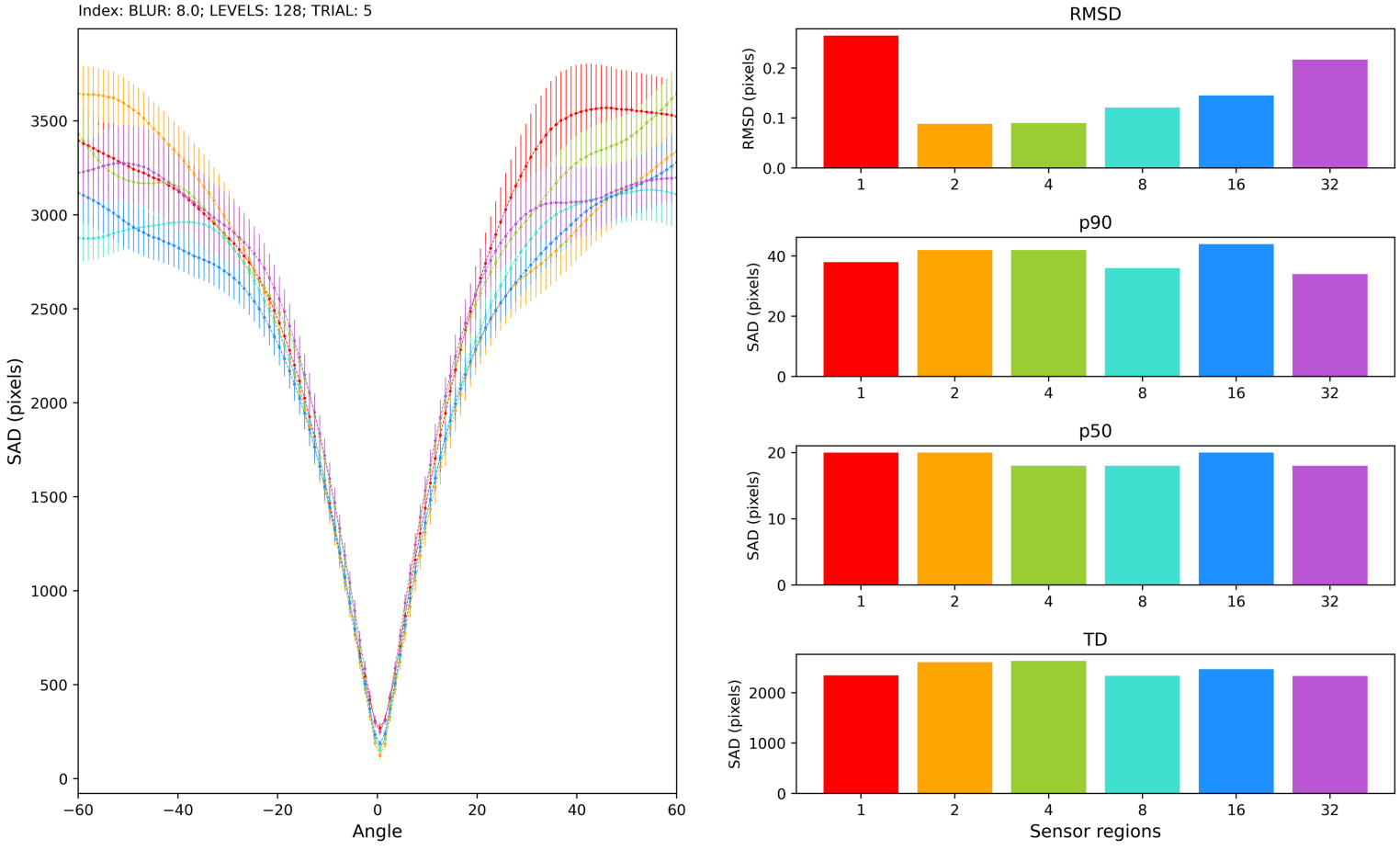




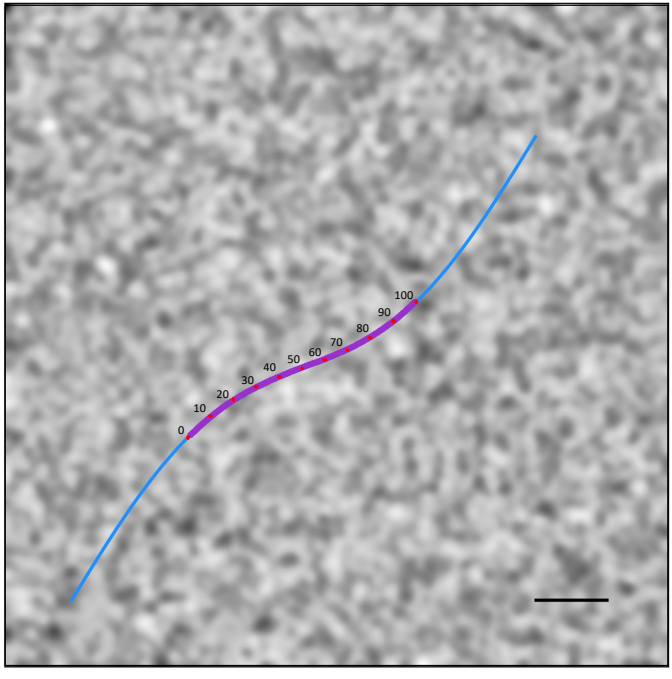


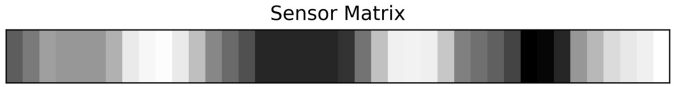
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

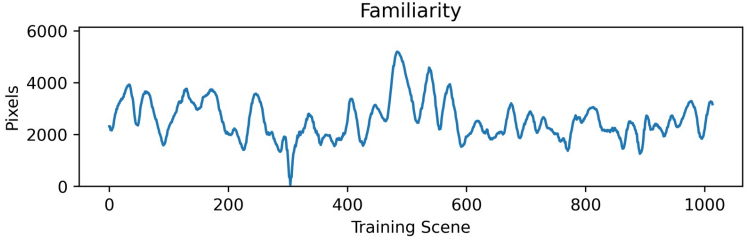
Navigation stats: RMSD error: 54.11; RMSD/dist: 0.135; TD: 2600; p90: 42; p50: 18; complete: 0

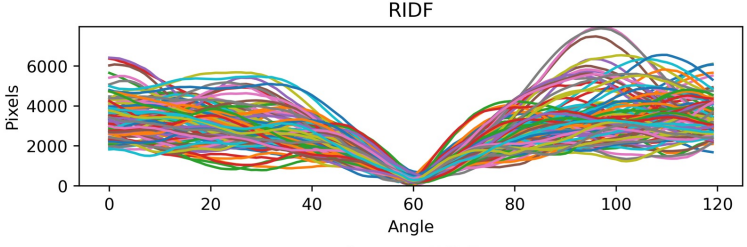

Index: BLUR: 8.0; LEVELS: 128; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

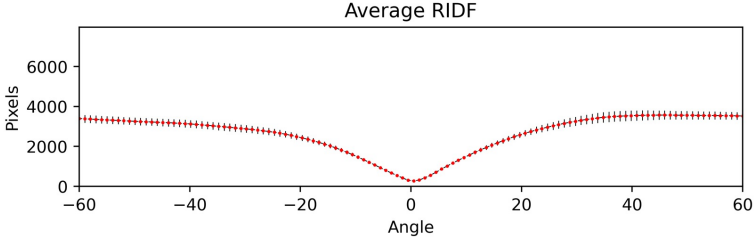
100%







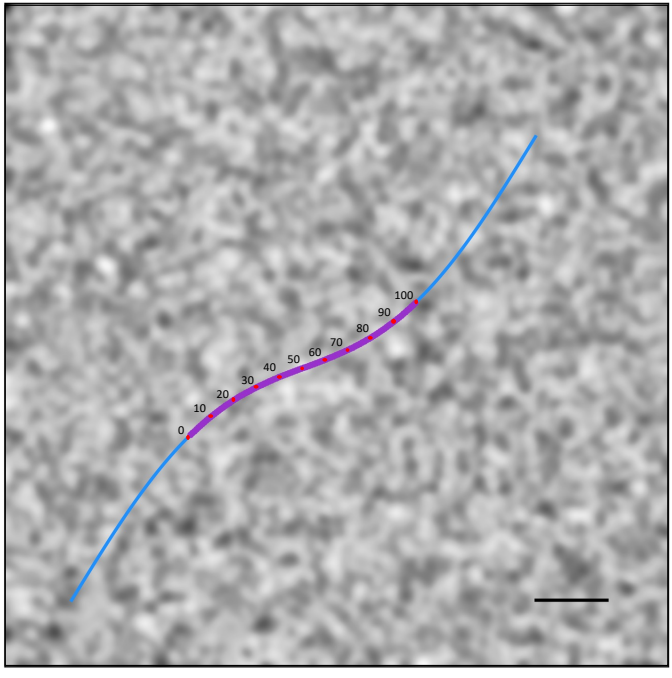


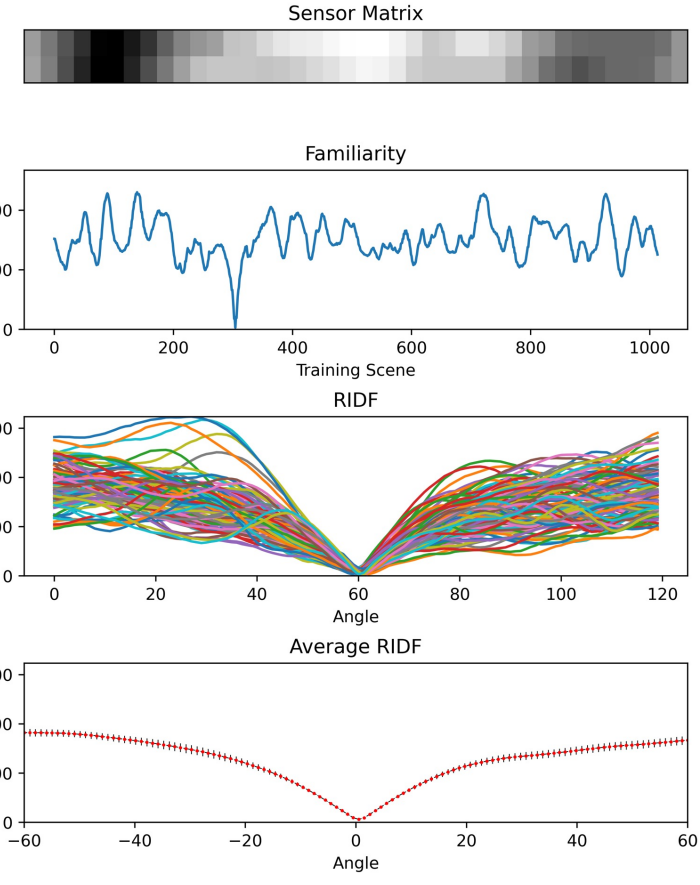


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 105.89; RMSD/dist: 0.265; TD: 2344; p90: 38; p50: 20; complete: 0

100%

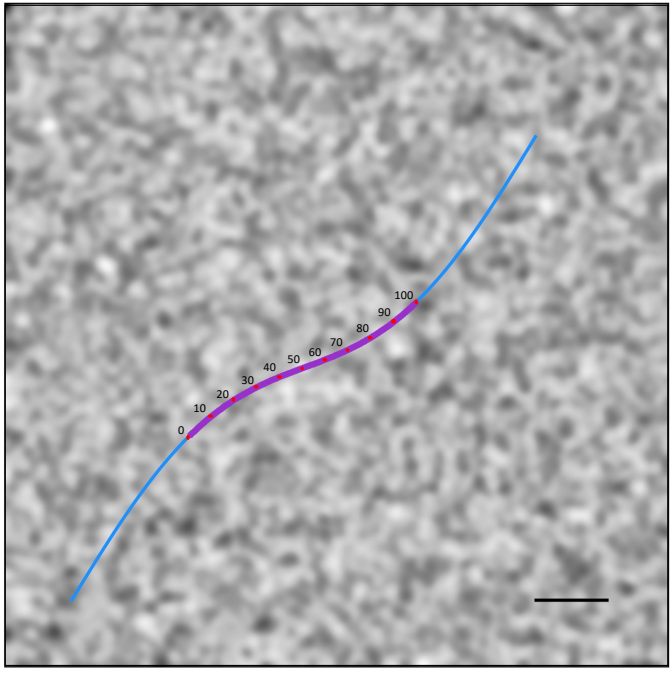


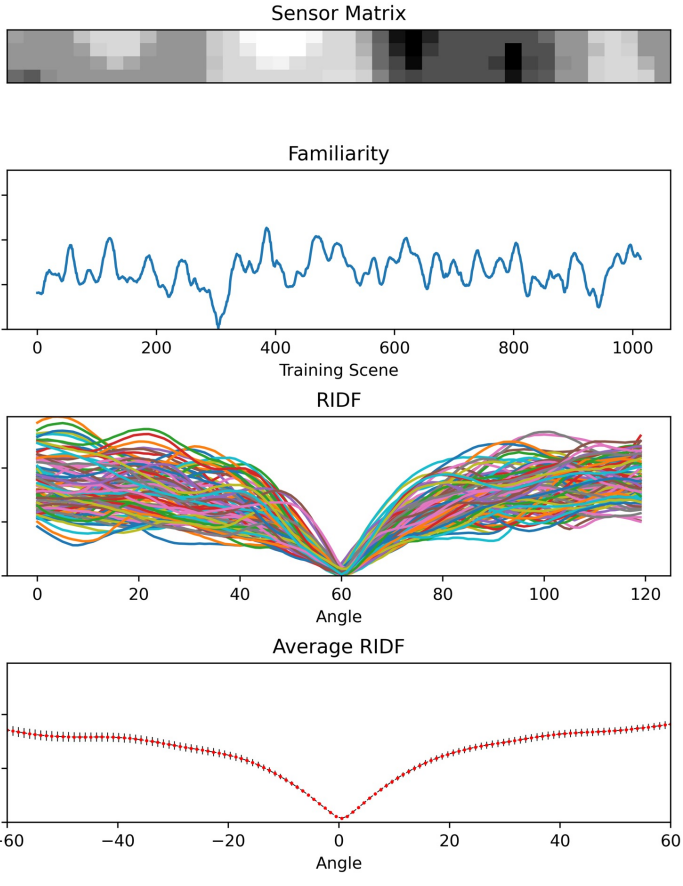


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 35.03; RMSD/dist: 0.088; TD: 2605; p90: 42; p50: 20; complete: 0

100%

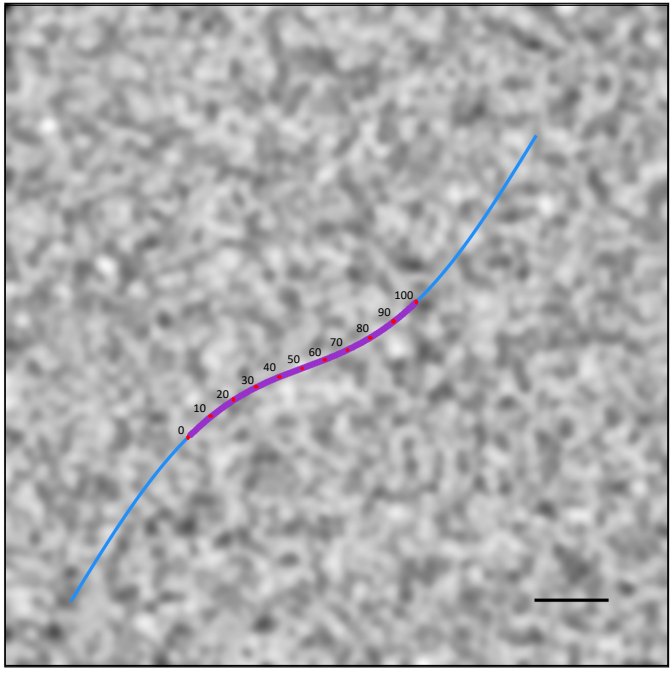


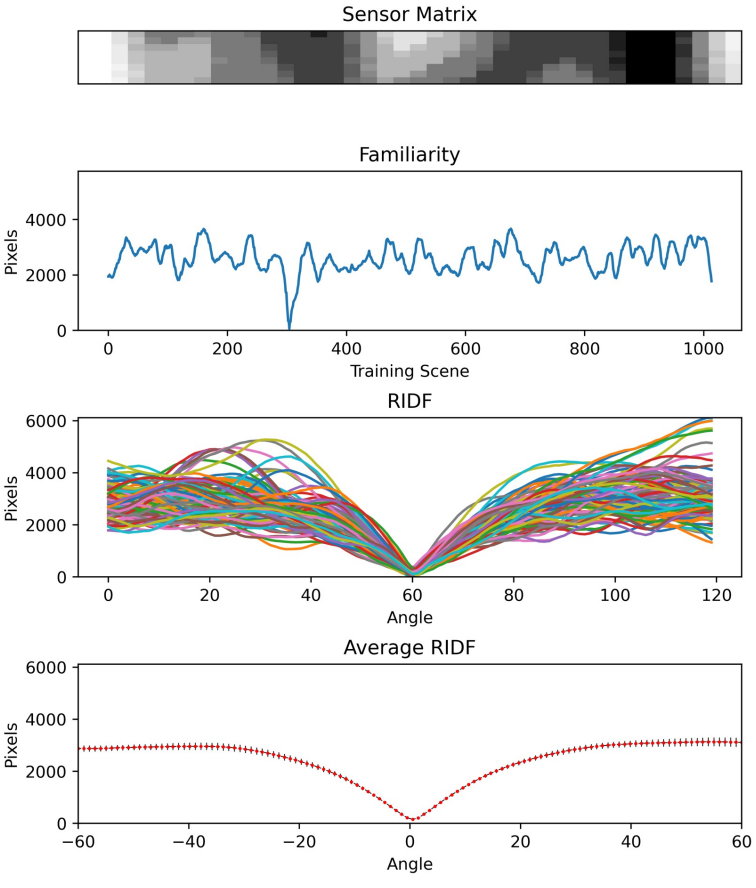


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 35.94; RMSD/dist: 0.090; TD: 2629; p90: 42; p50: 18; complete: 0

100%

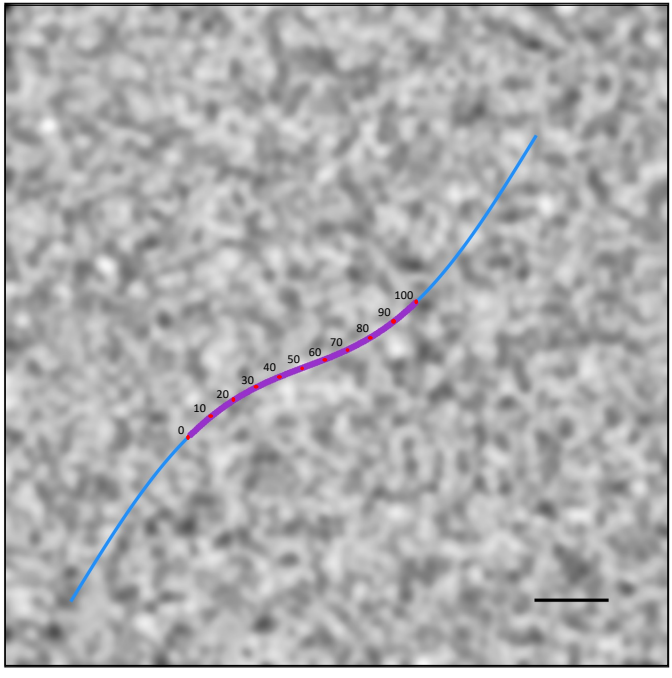


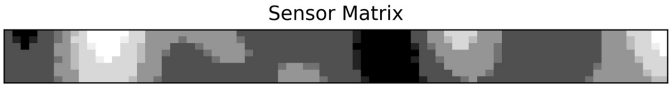


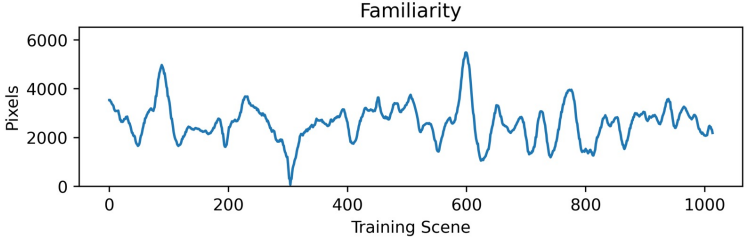
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

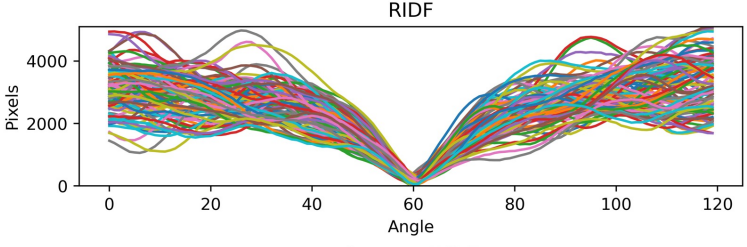
Navigation stats: RMSD error: 48.45; RMSD/dist: 0.121; TD: 2337; p90: 36; p50: 18; complete: 0

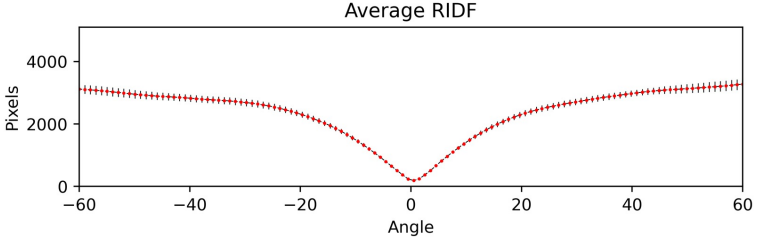
100%







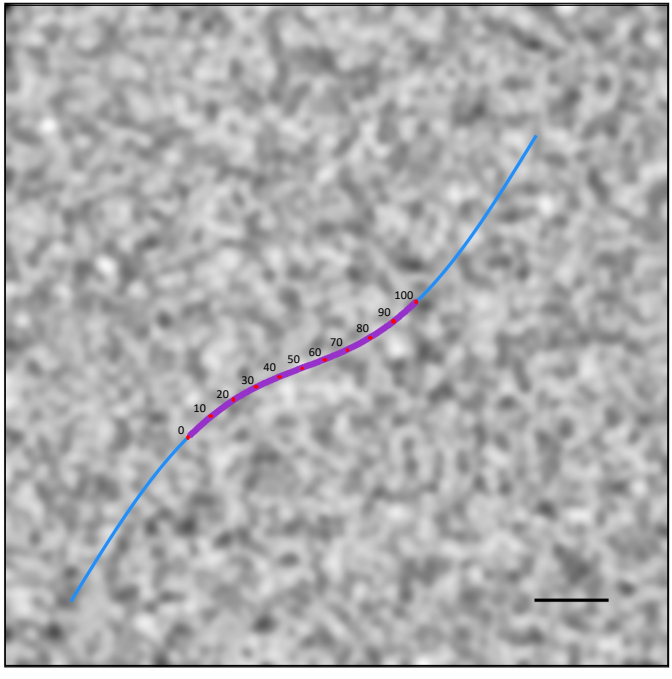


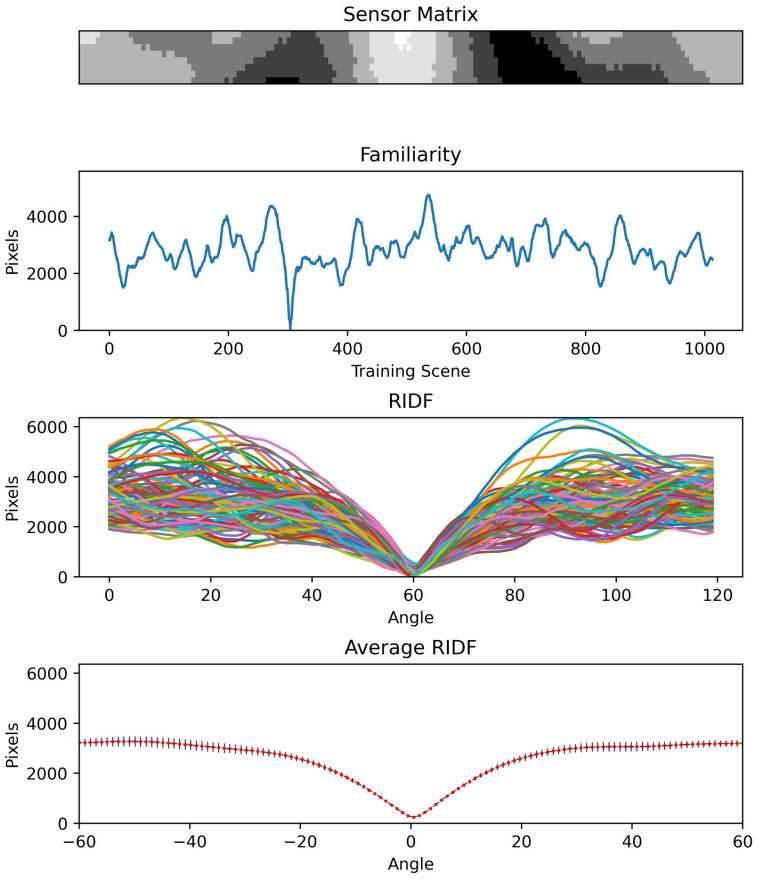


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 57.84; RMSD/dist: 0.145; TD: 2467; p90: 44; p50: 20; complete: 0

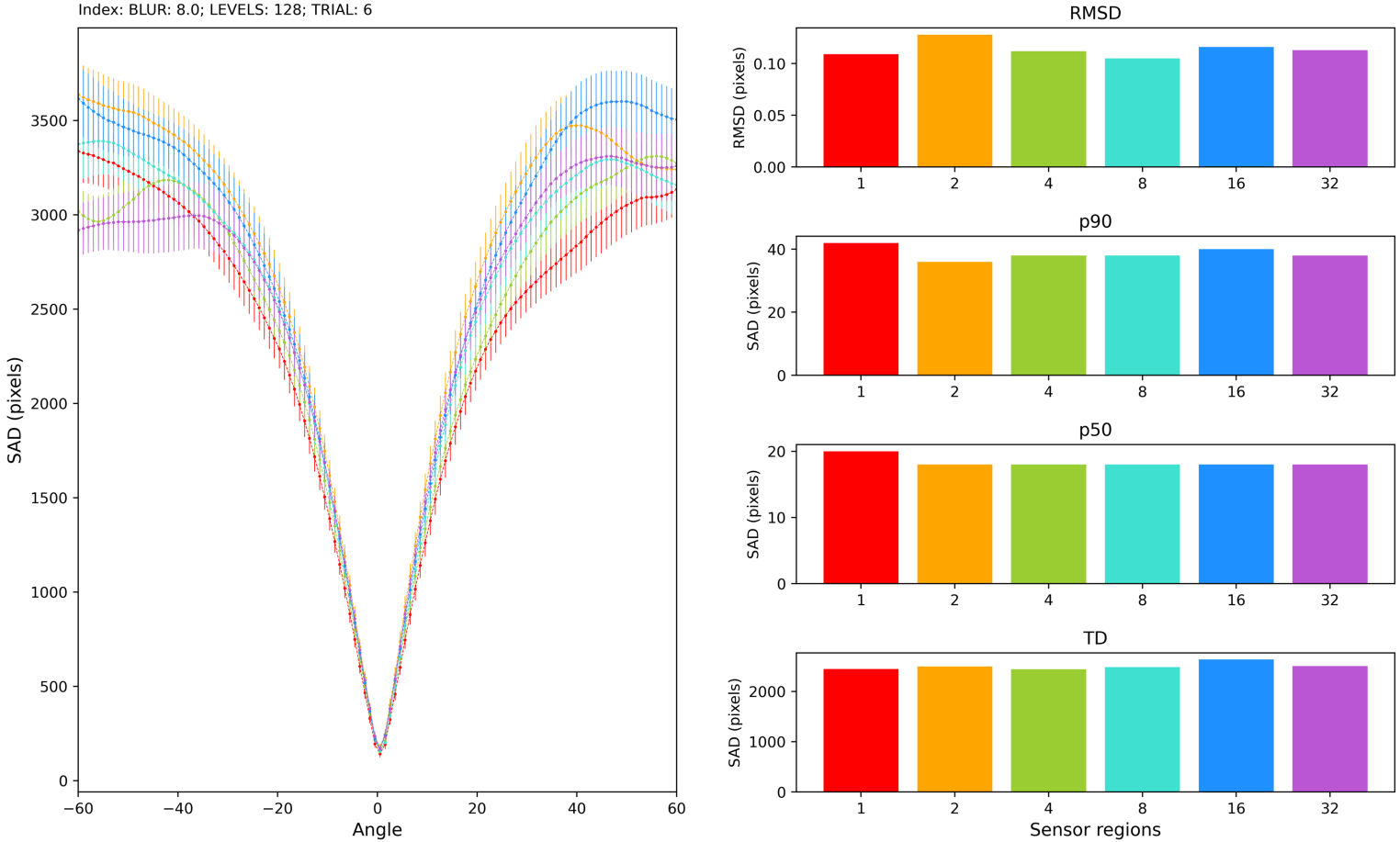
100%



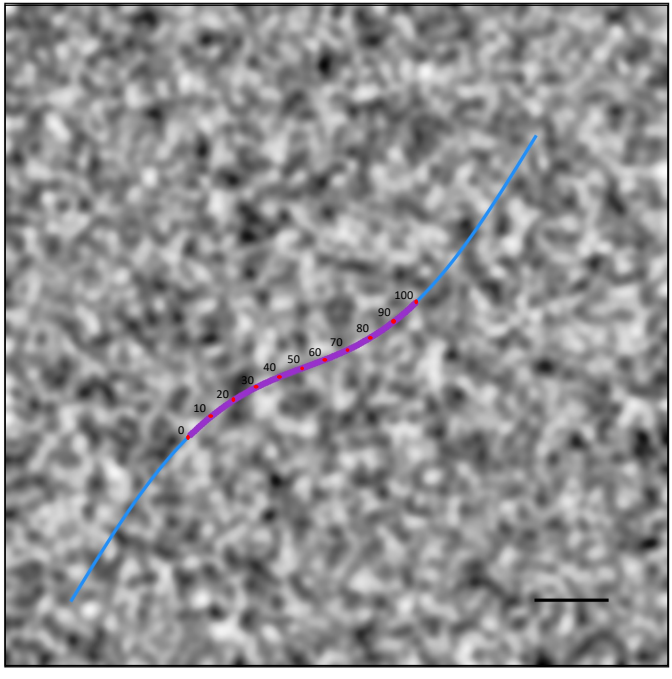


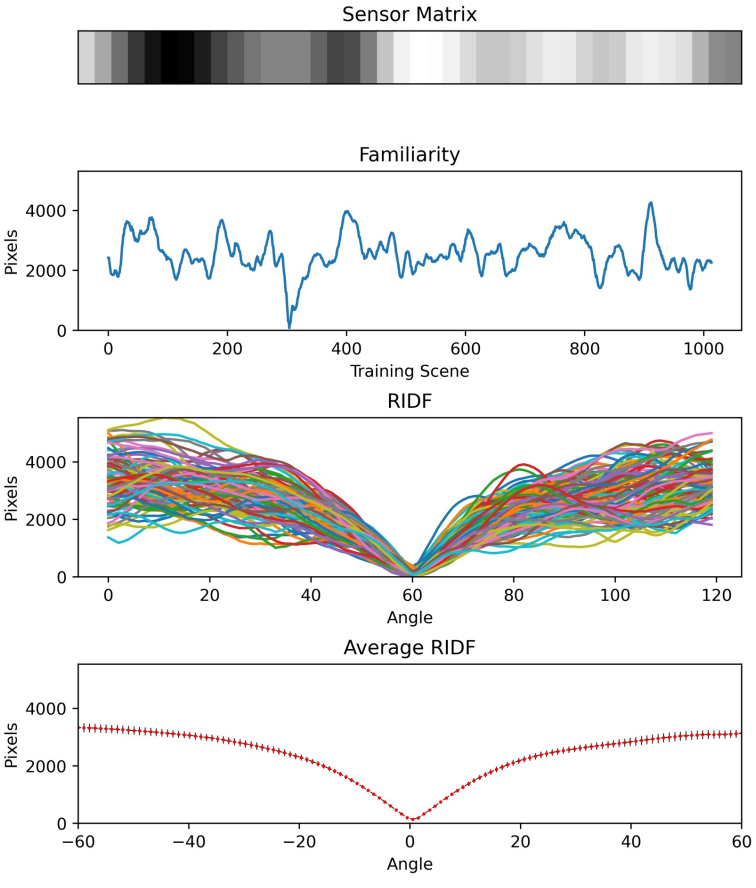
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 86.61; RMSD/dist: 0.217; TD: 2331; p90: 34; p50: 18; complete: 0


Index: BLUR: 8.0; LEVELS: 128; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

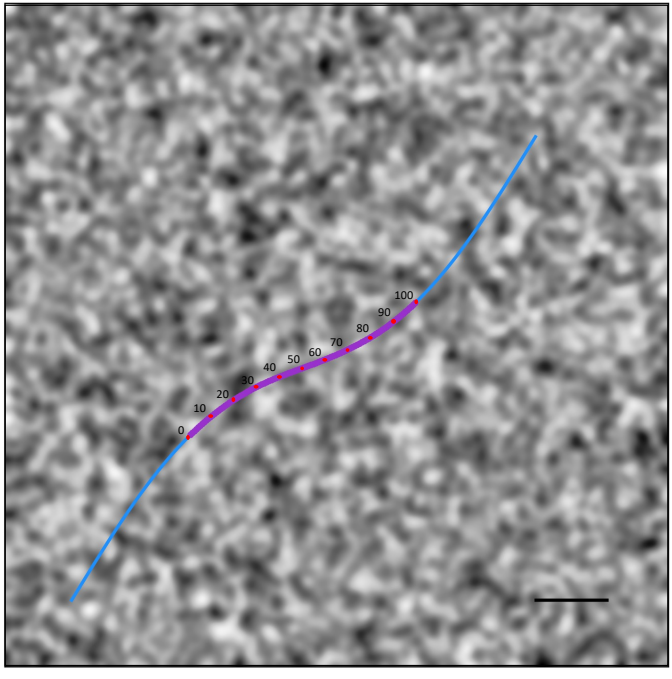


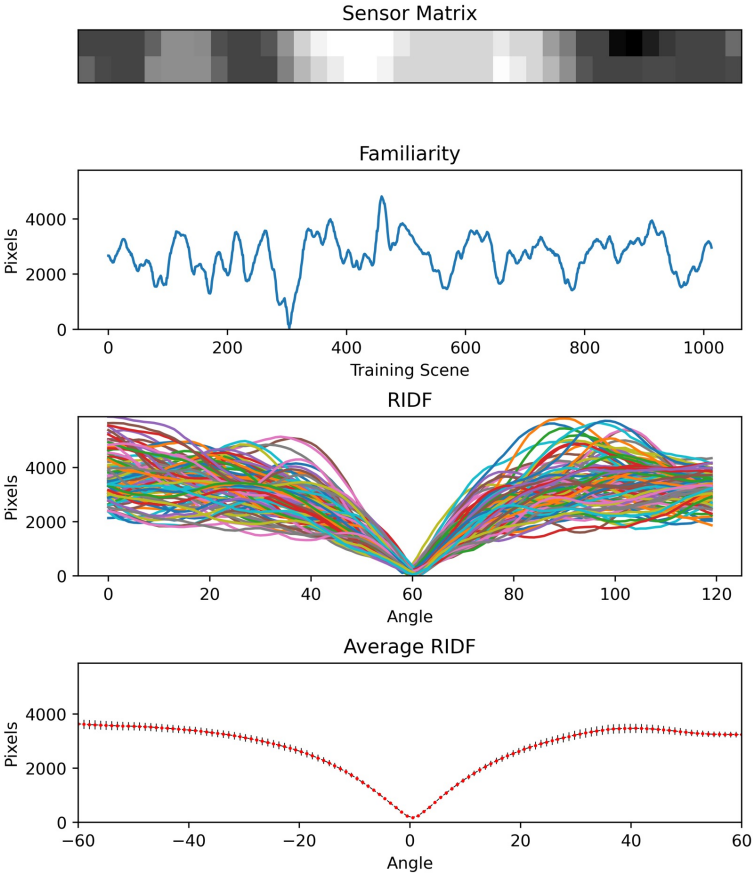


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 43.45; RMSD/dist: 0.109; TD: 2447; p90: 42; p50: 20; complete: 0

100%

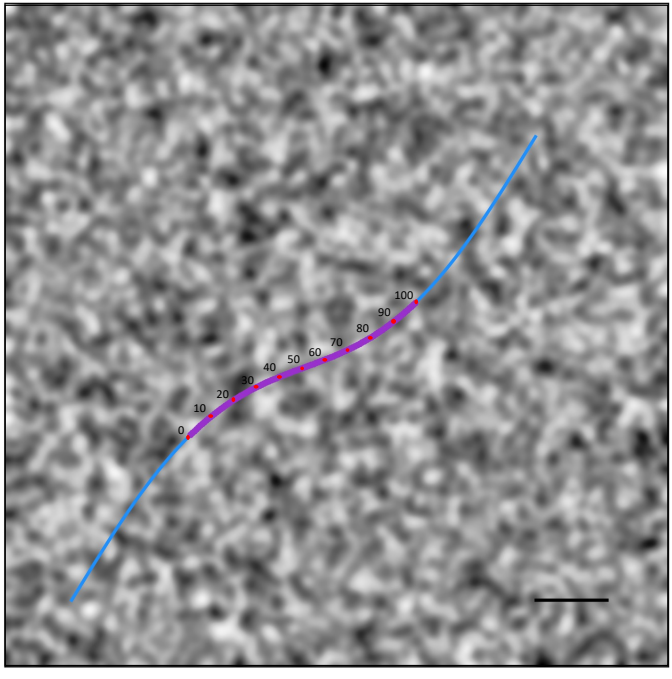


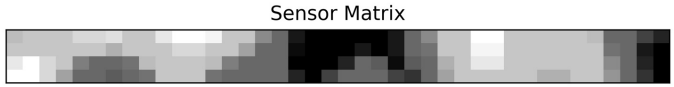


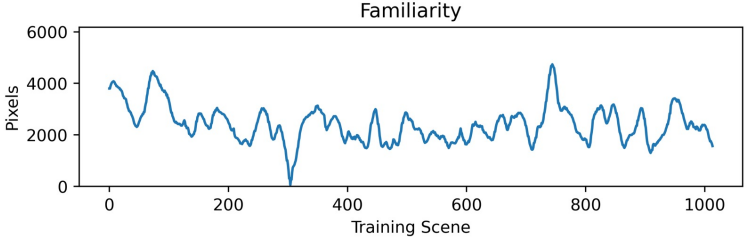
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

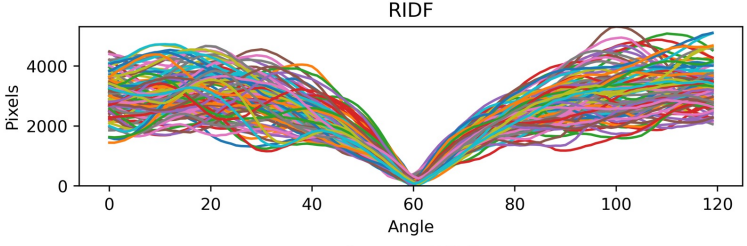
Navigation stats: RMSD error: 51.35; RMSD/dist: 0.128; TD: 2496; p90: 36; p50: 18; complete: 0

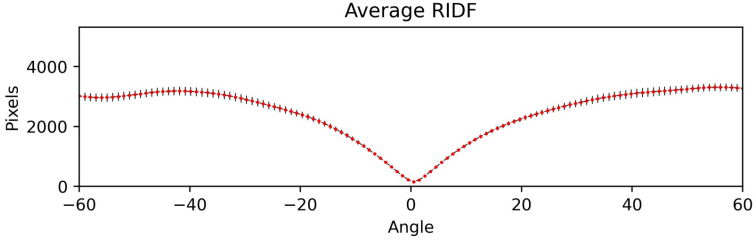
100%







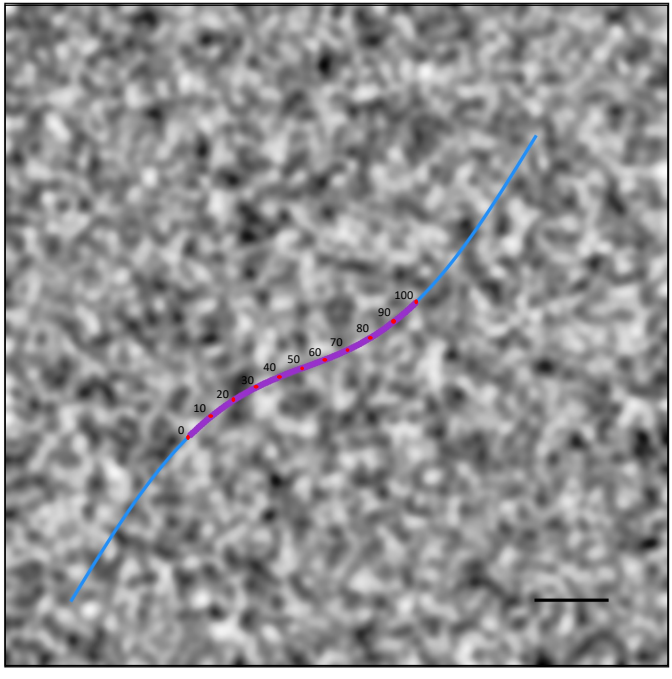


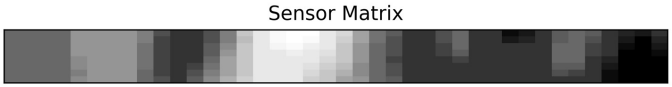


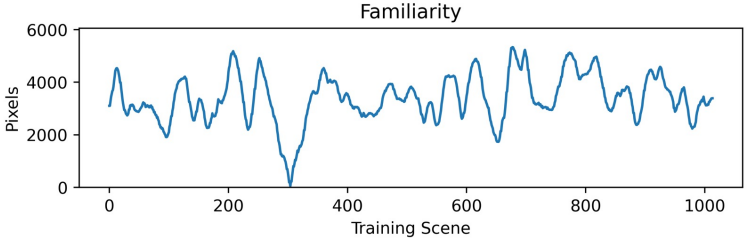
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

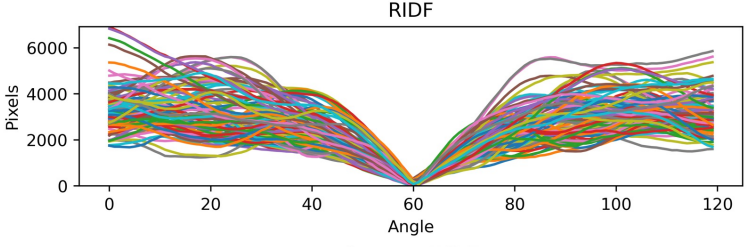
Navigation stats: RMSD error: 44.60; RMSD/dist: 0.112; TD: 2439; p90: 38; p50: 18; complete: 0

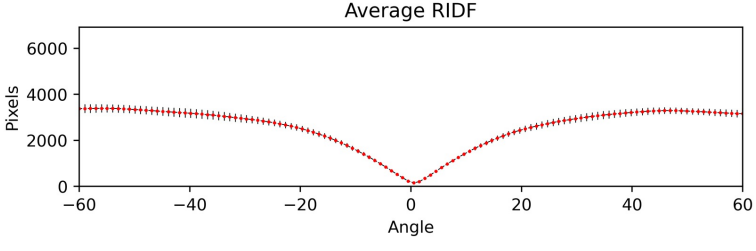
100%







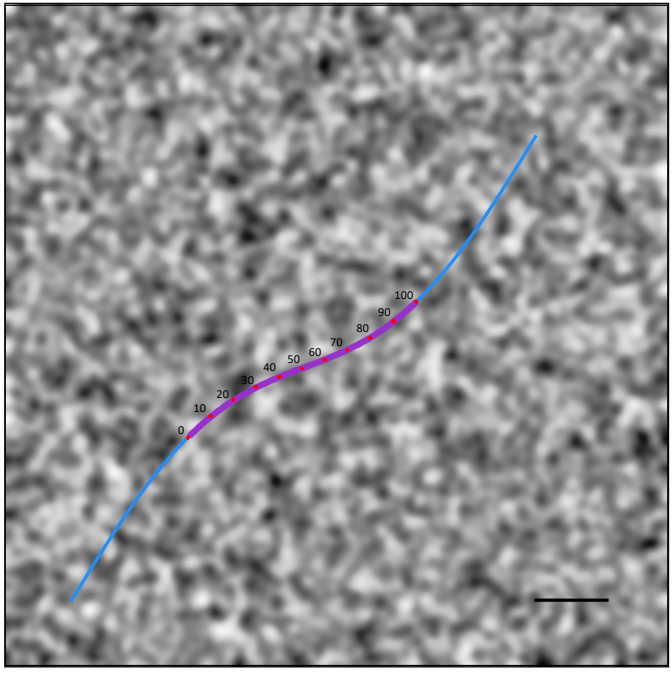


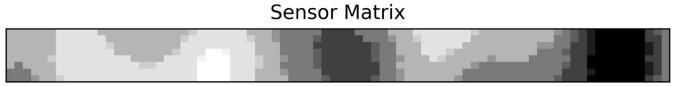


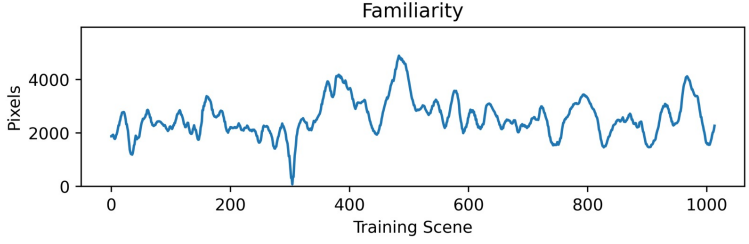
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

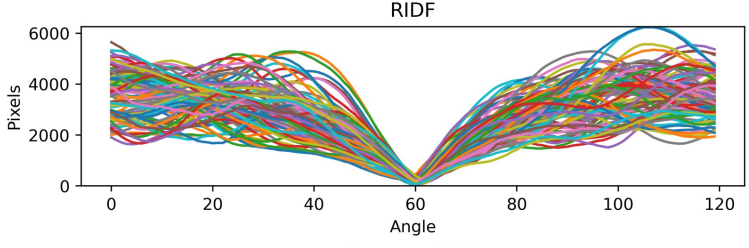
Navigation stats: RMSD error: 41.94; RMSD/dist: 0.105; TD: 2484; p90: 38; p50: 18; complete: 0

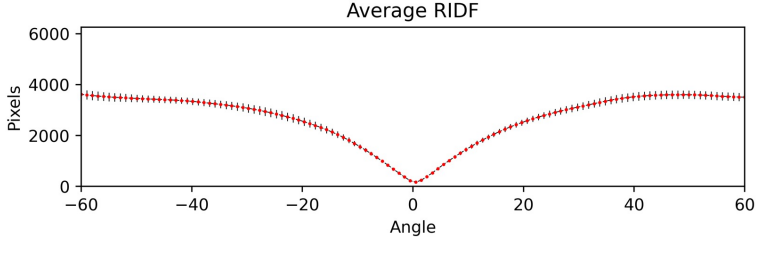
100%







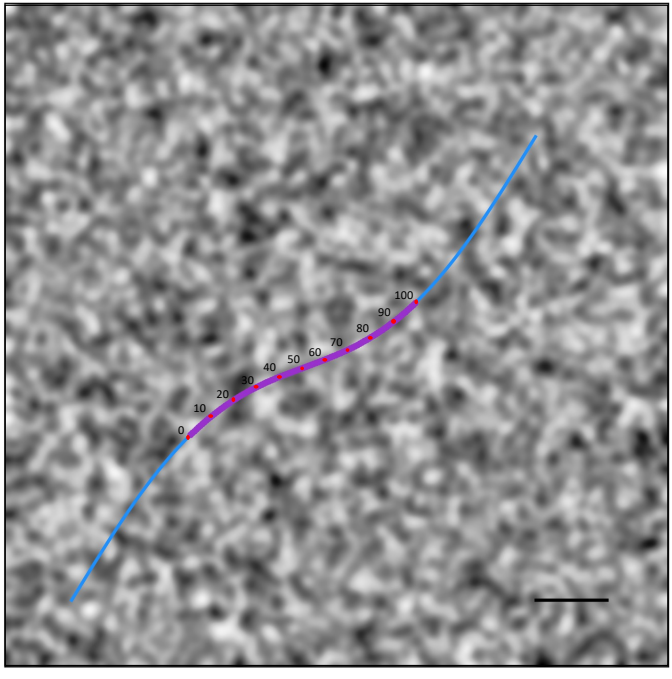


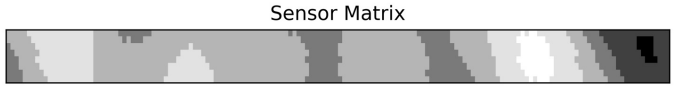


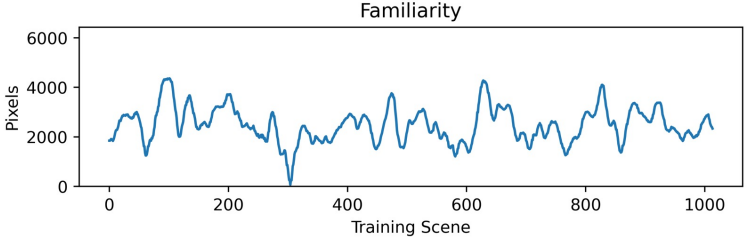
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

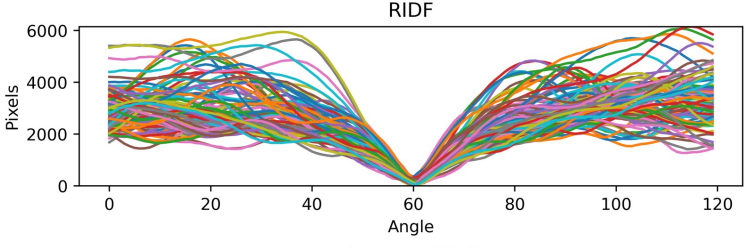
Navigation stats: RMSD error: 46.22; RMSD/dist: 0.116; TD: 2633; p90: 40; p50: 18; complete: 0

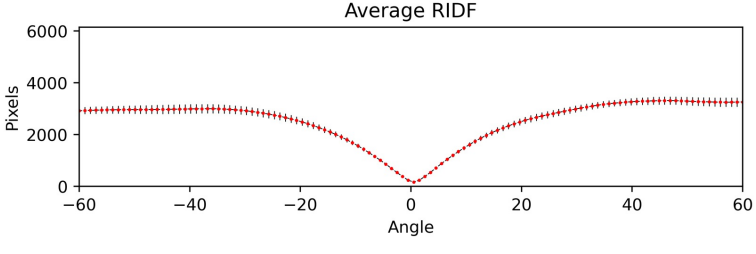
100%





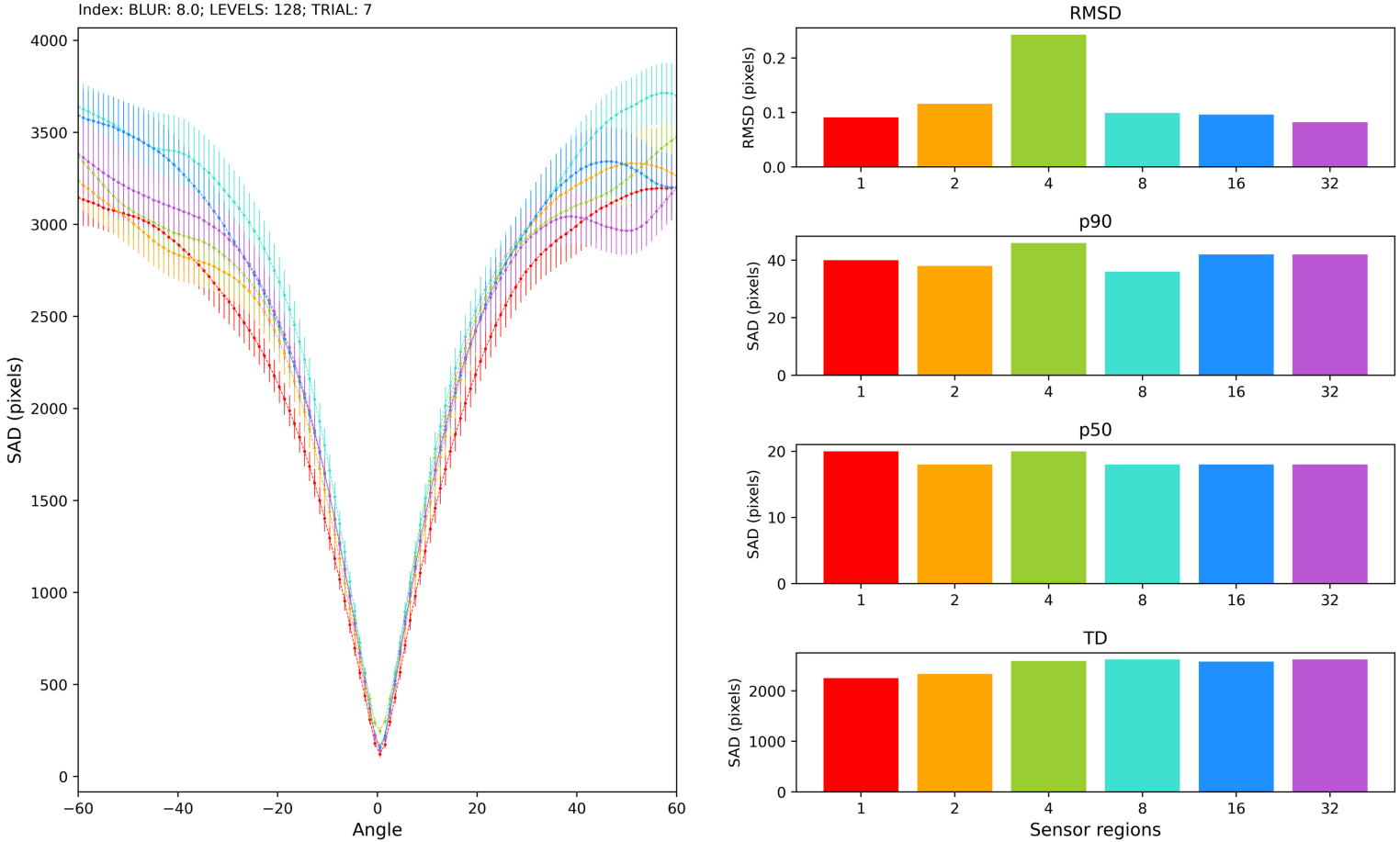




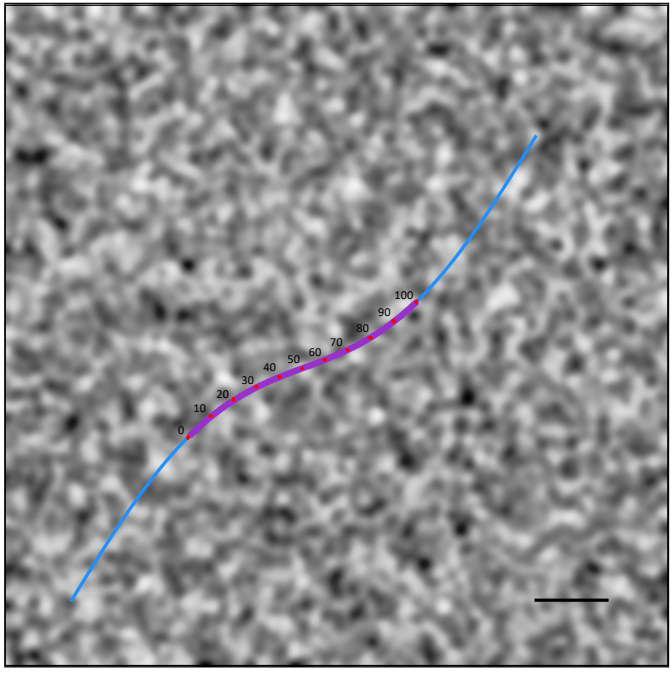


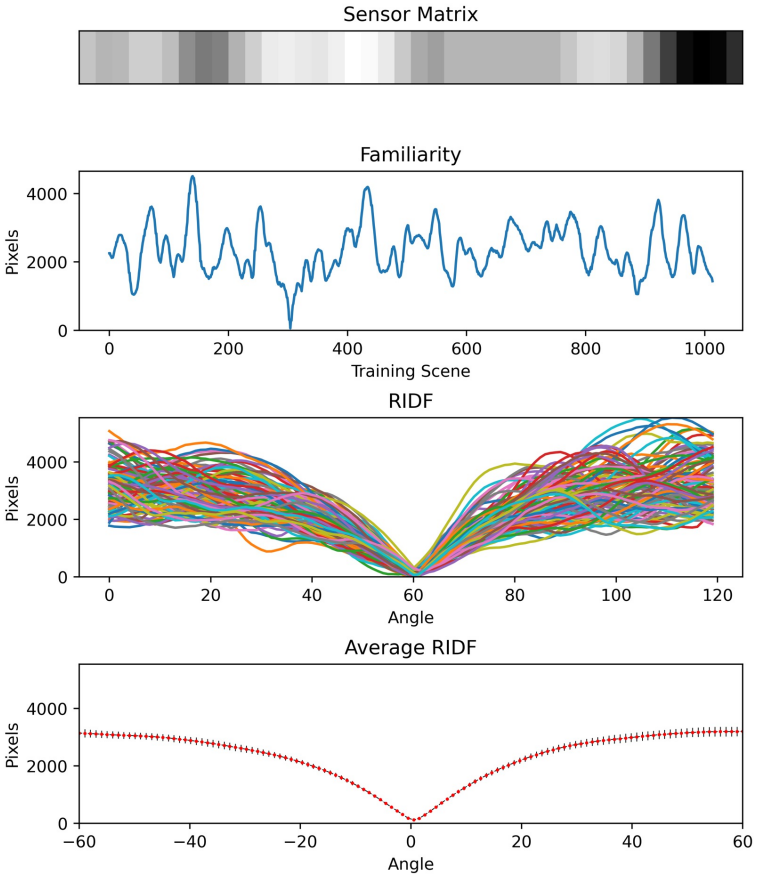
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 45.04; RMSD/dist: 0.113; TD: 2505; p90: 38; p50: 18; complete: 0


Index: BLUR: 8.0; LEVELS: 128; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

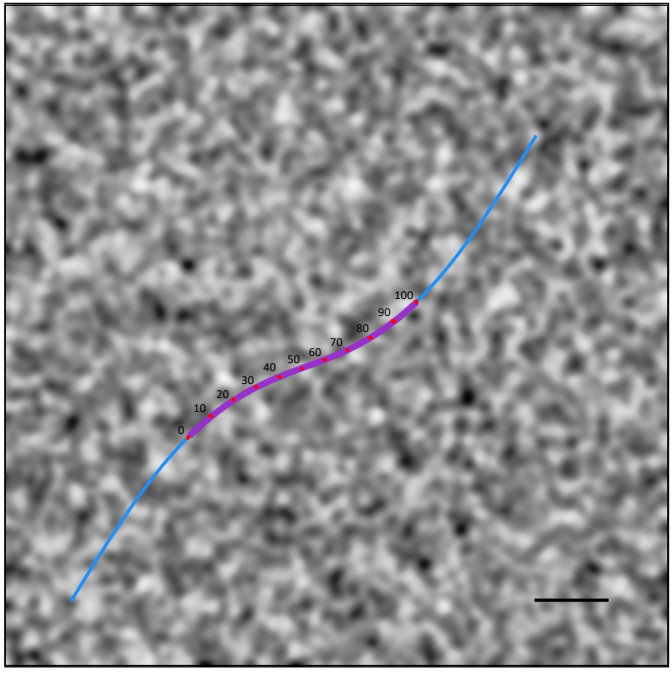


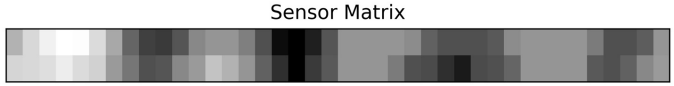


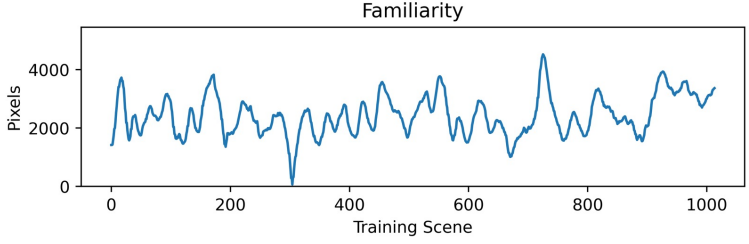
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

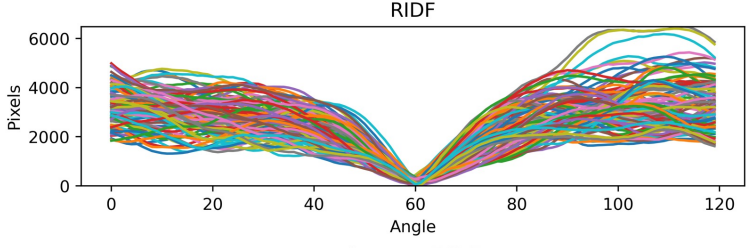
Navigation stats: RMSD error: 36.34; RMSD/dist: 0.091; TD: 2248; p90: 40; p50: 20; complete: 0

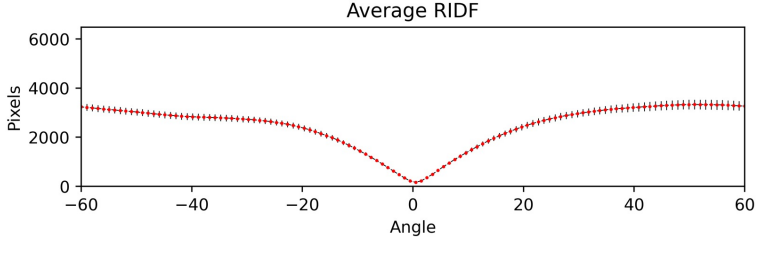
100%







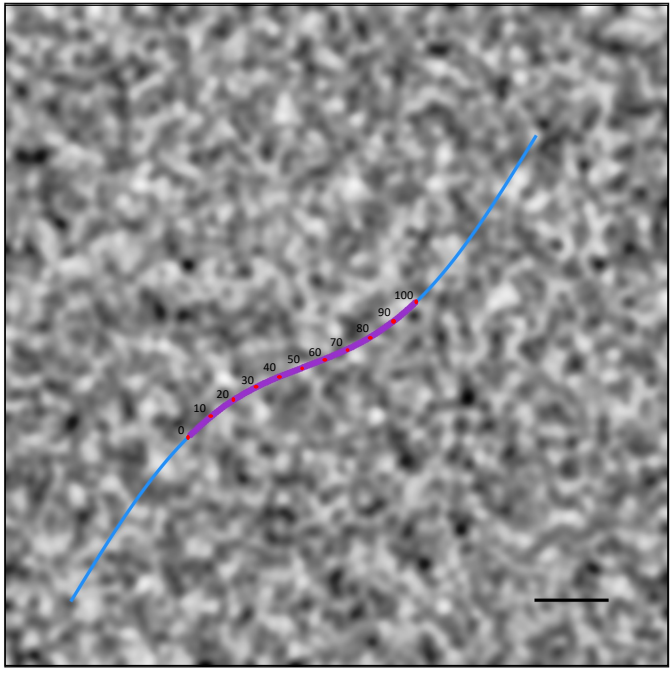


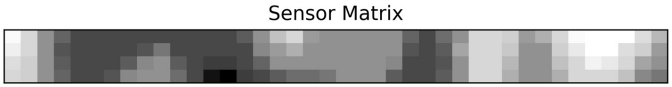


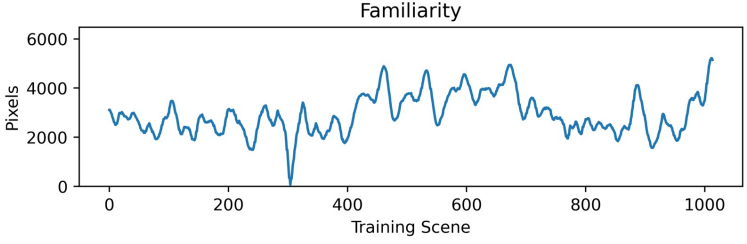
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

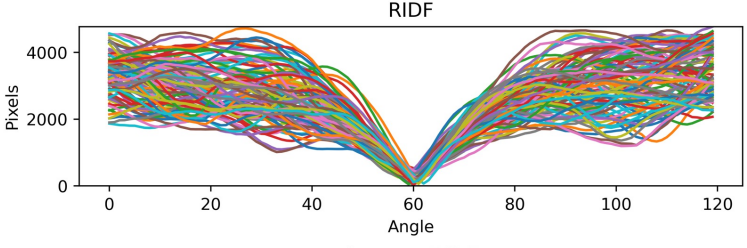
Navigation stats: RMSD error: 46.32; RMSD/dist: 0.116; TD: 2336; p90: 38; p50: 18; complete: 0

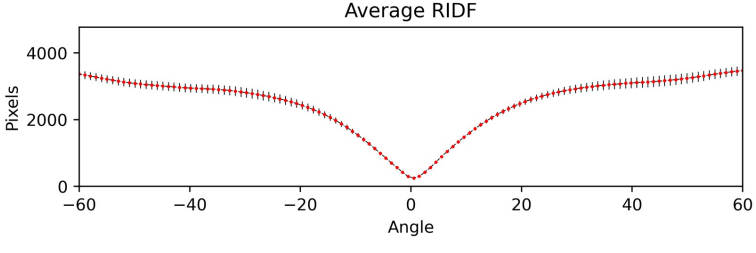
100%







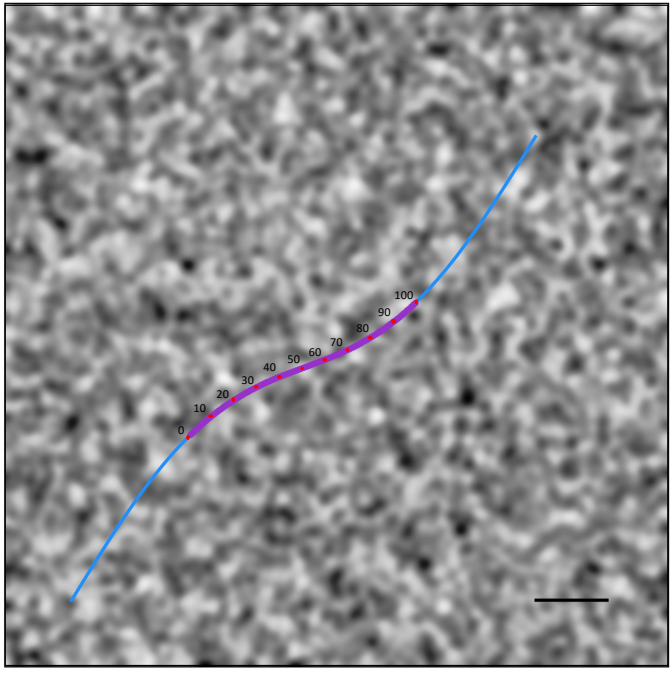


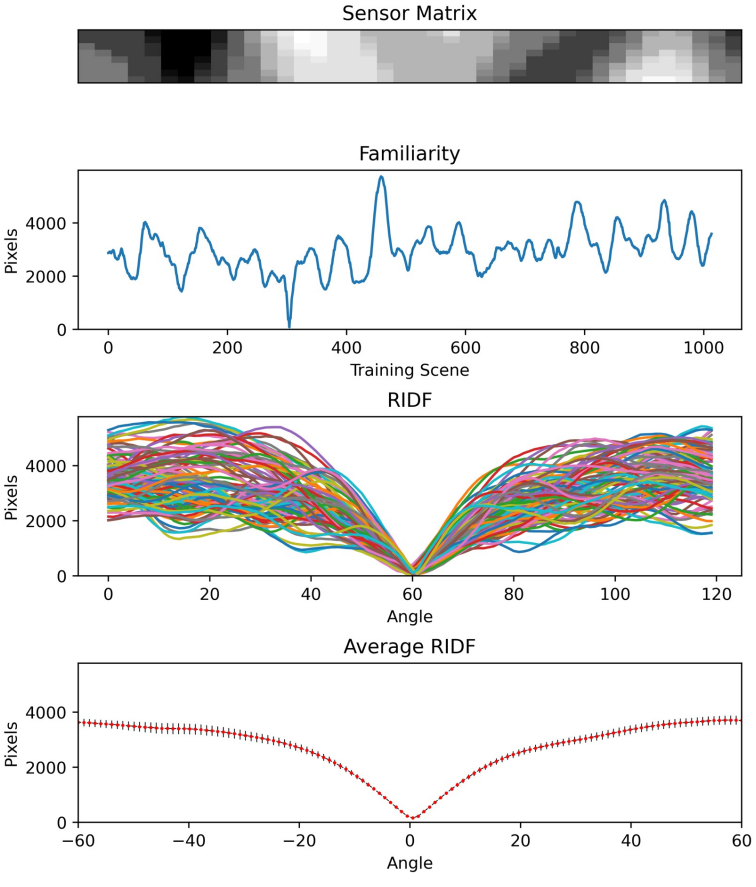


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 97.10; RMSD/dist: 0.243; TD: 2589; p90: 46; p50: 20; complete: 0

100%

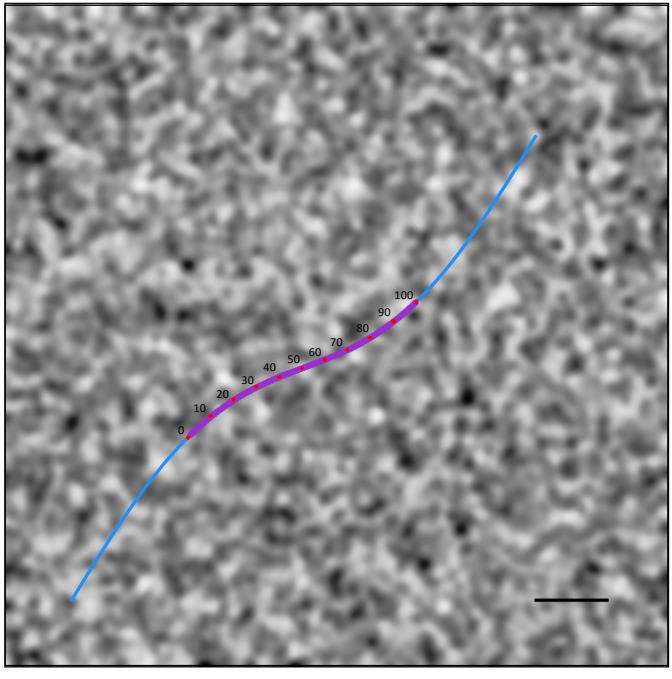


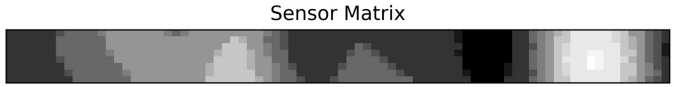


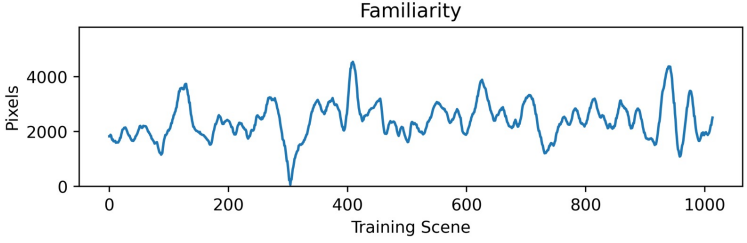
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

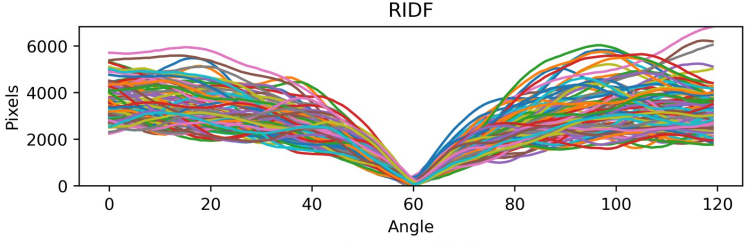
Navigation stats: RMSD error: 39.49; RMSD/dist: 0.099; TD: 2617; p90: 36; p50: 18; complete: 0

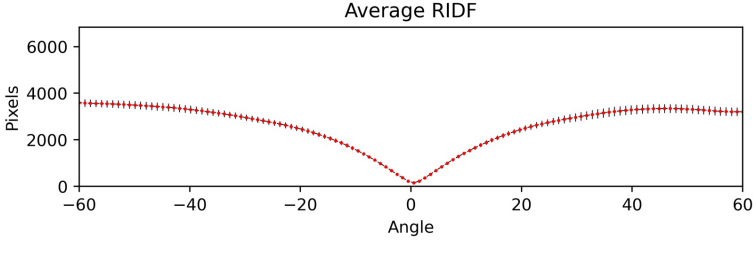
100%







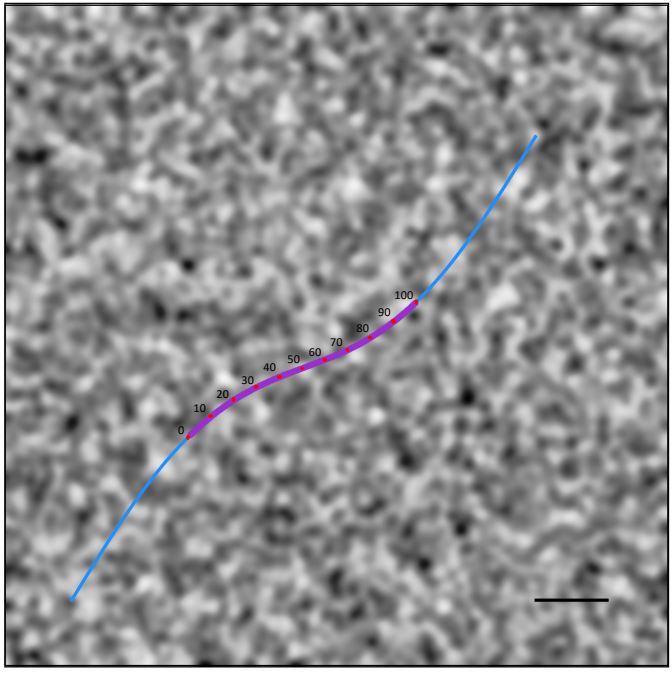


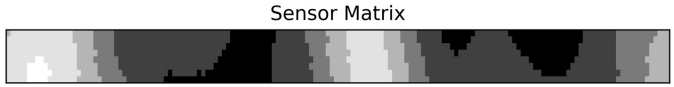


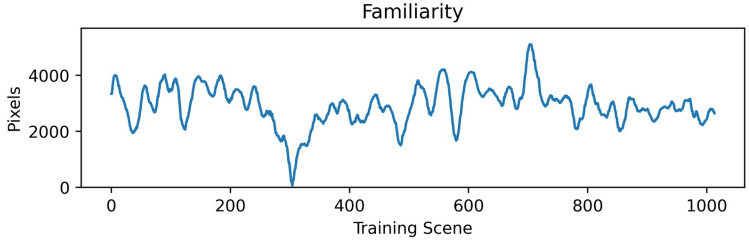
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

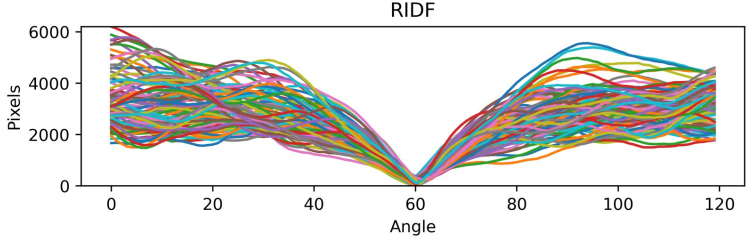
Navigation stats: RMSD error: 38.42; RMSD/dist: 0.096; TD: 2579; p90: 42; p50: 18; complete: 0

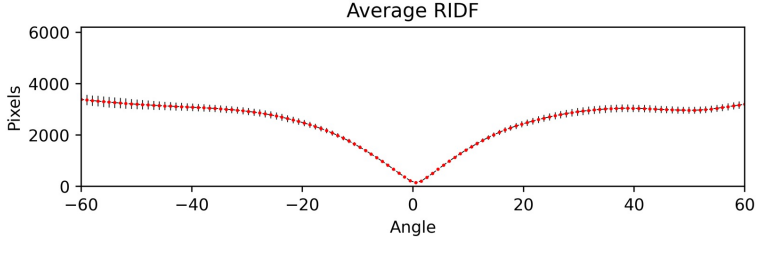
100%





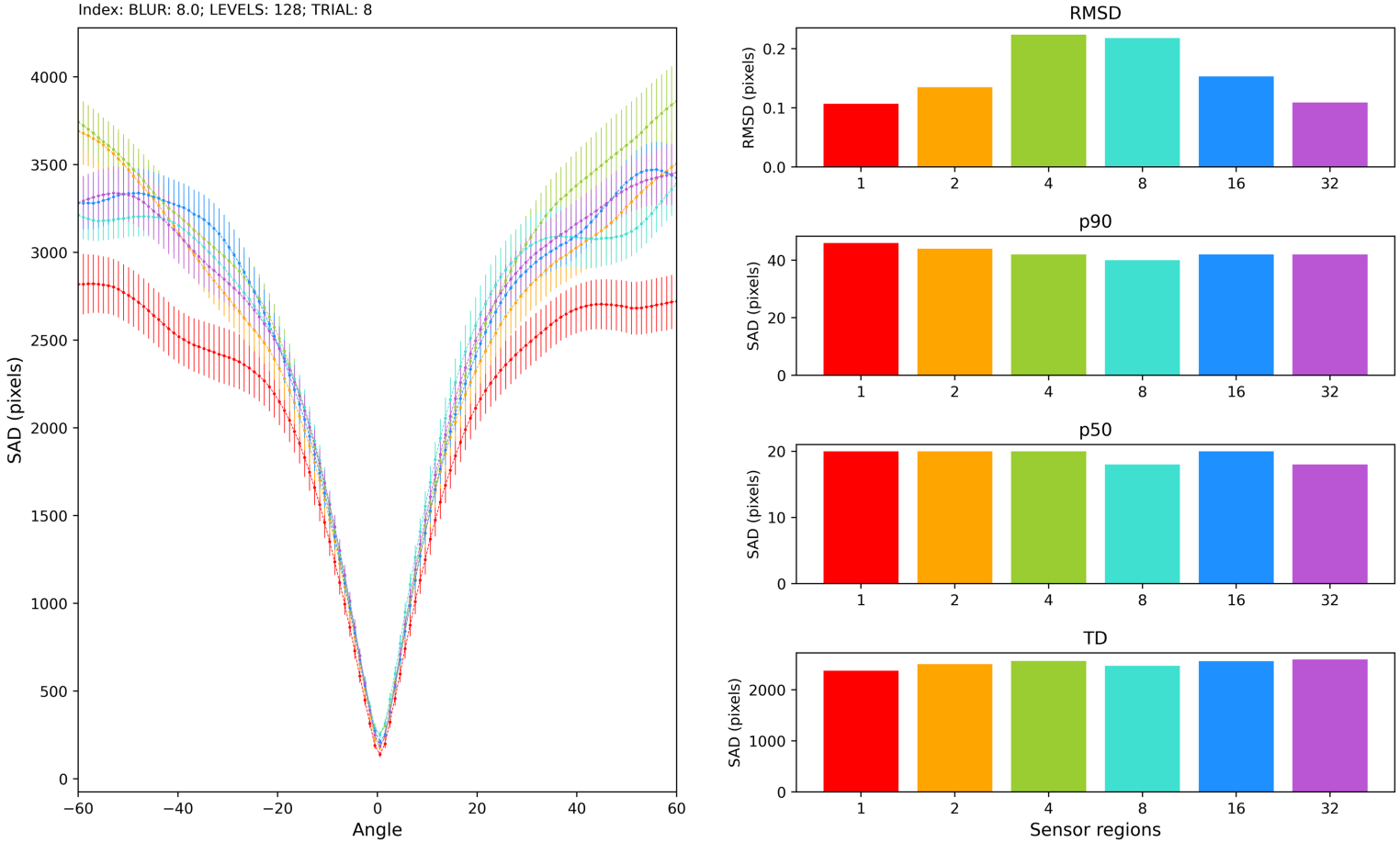




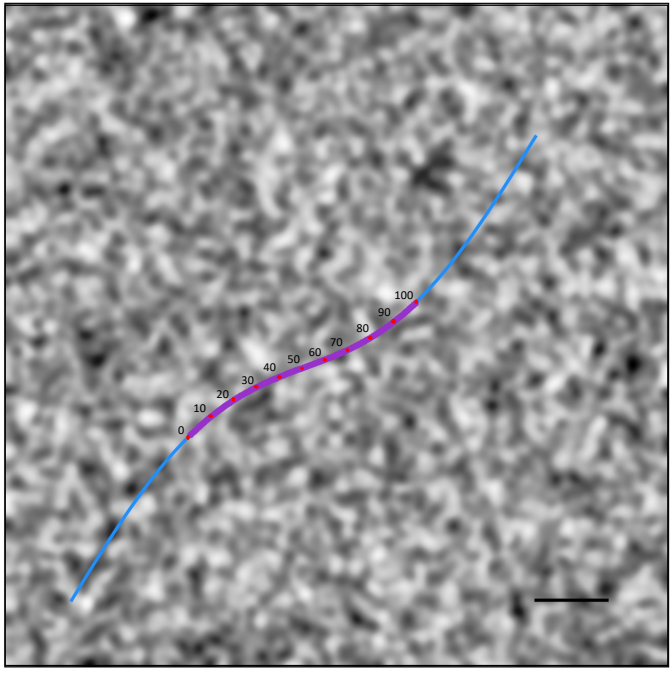


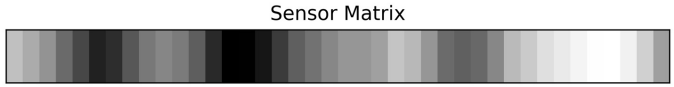
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

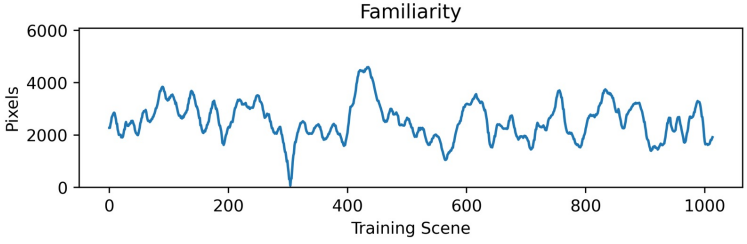
Navigation stats: RMSD error: 32.82; RMSD/dist: 0.082; TD: 2617; p90: 42; p50: 18; complete: 0

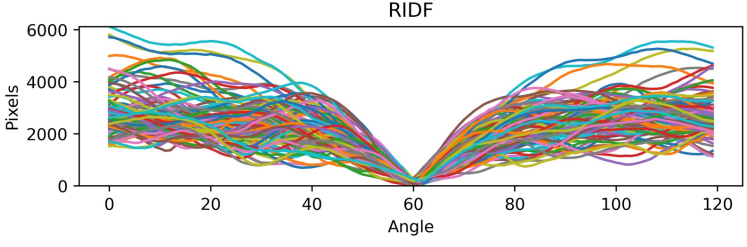

Index: BLUR: 8.0; LEVELS: 128; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

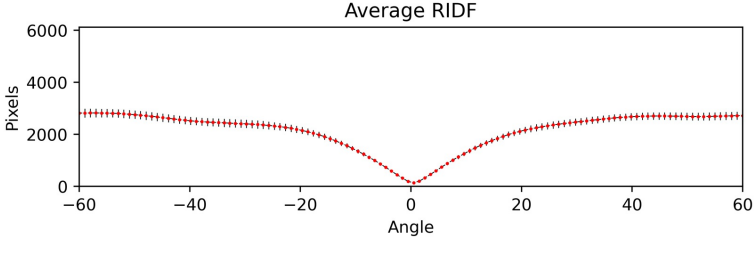
100%







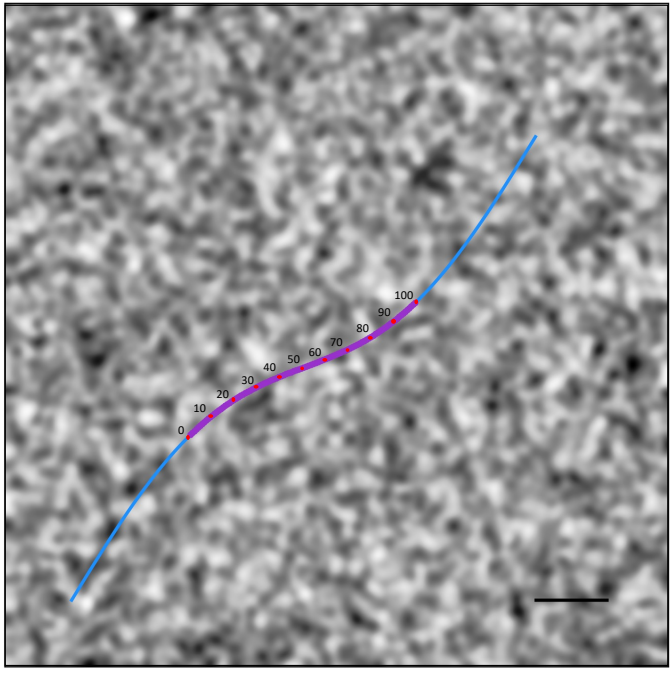


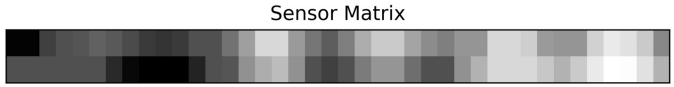


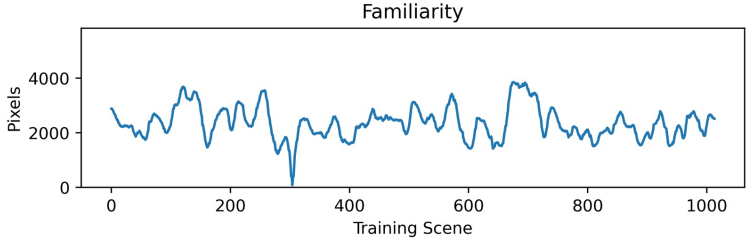
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

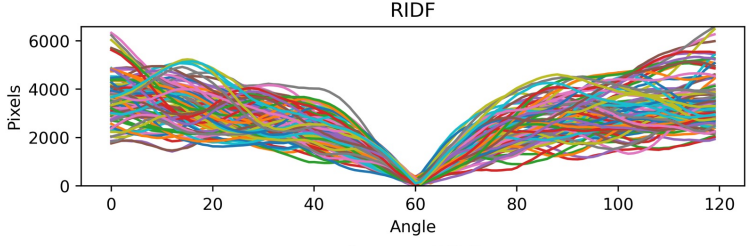
Navigation stats: RMSD error: 42.92; RMSD/dist: 0.107; TD: 2373; p90: 46; p50: 20; complete: 0

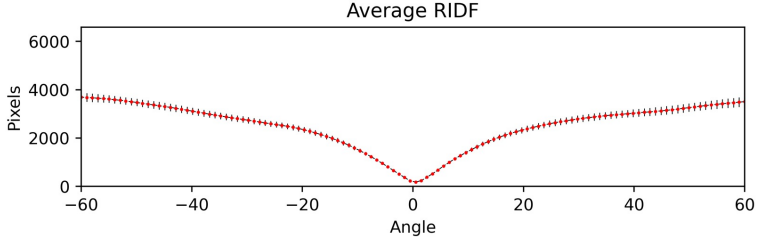
100%







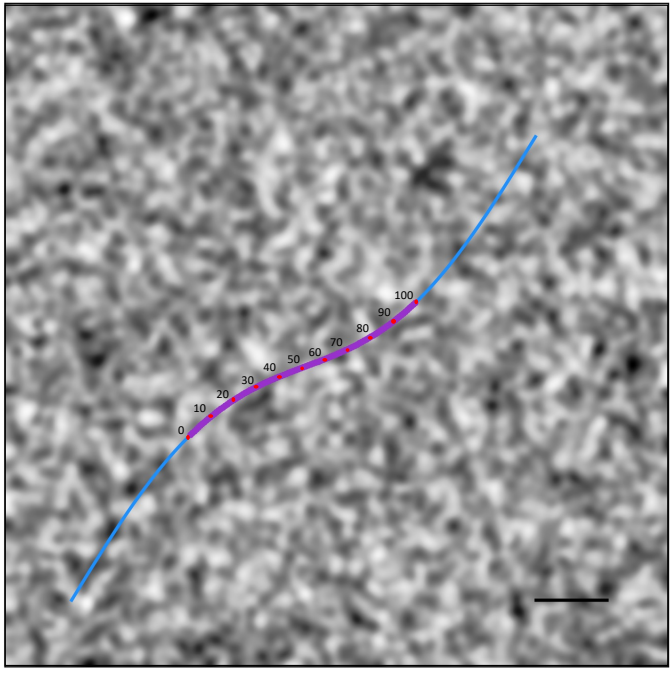


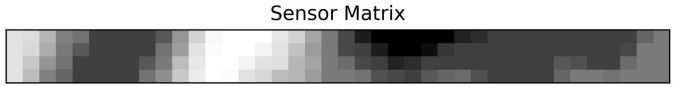


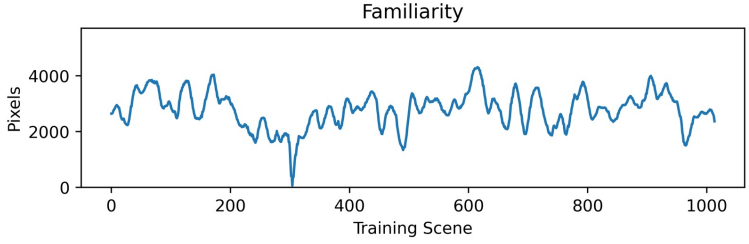
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

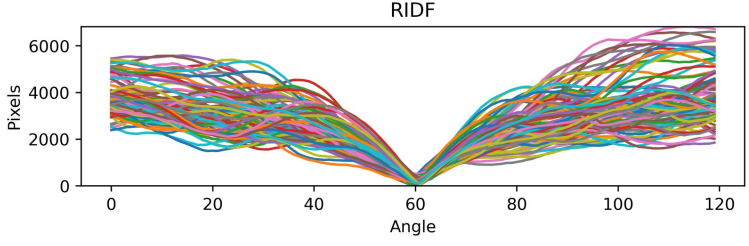
Navigation stats: RMSD error: 54.02; RMSD/dist: 0.135; TD: 2503; p90: 44; p50: 20; complete: 0

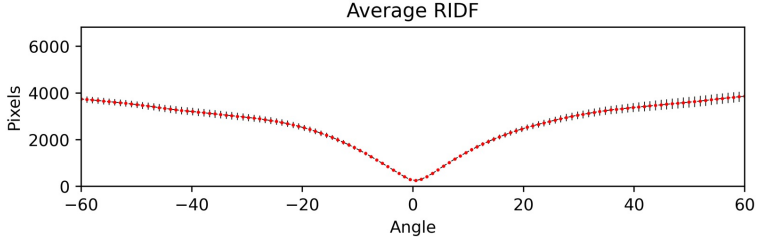
100%







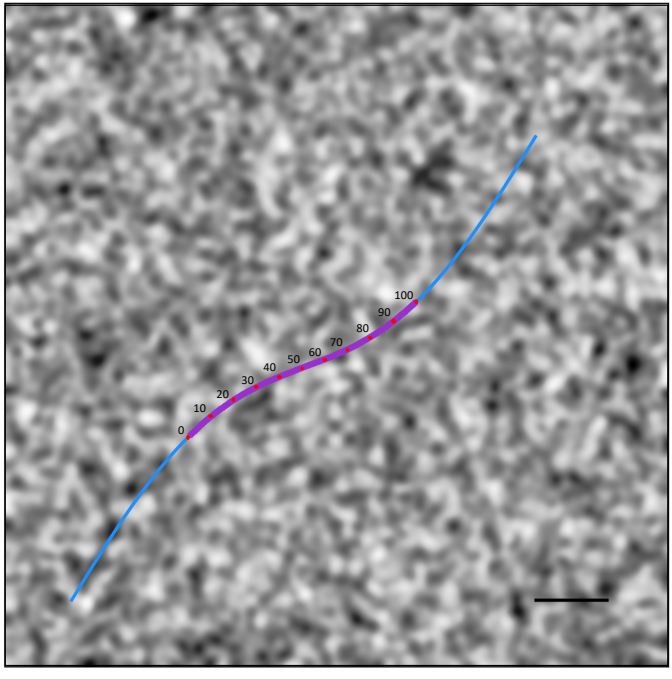


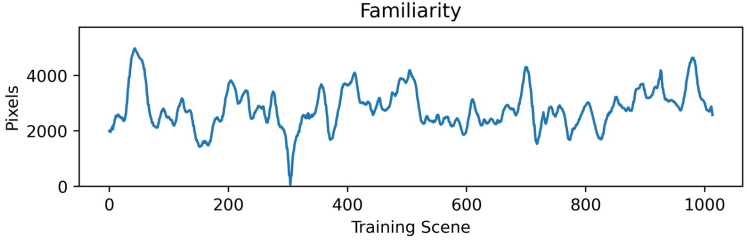


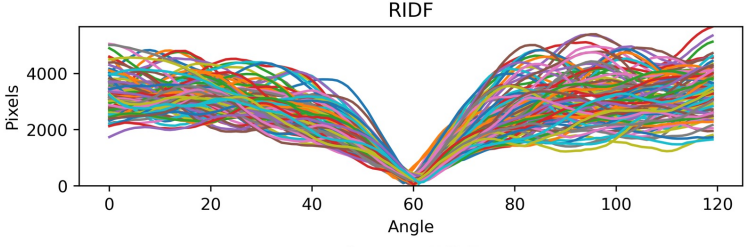
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

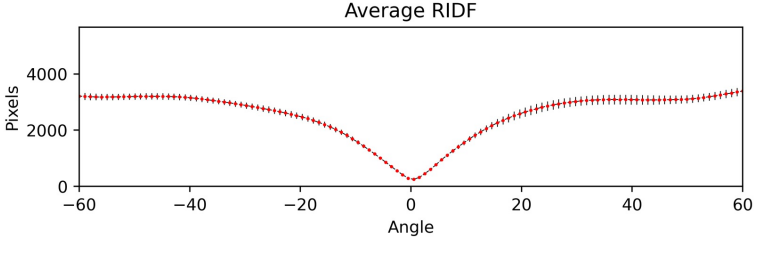
Navigation stats: RMSD error: 89.78; RMSD/dist: 0.224; TD: 2564; p90: 42; p50: 20; complete: 0

100%





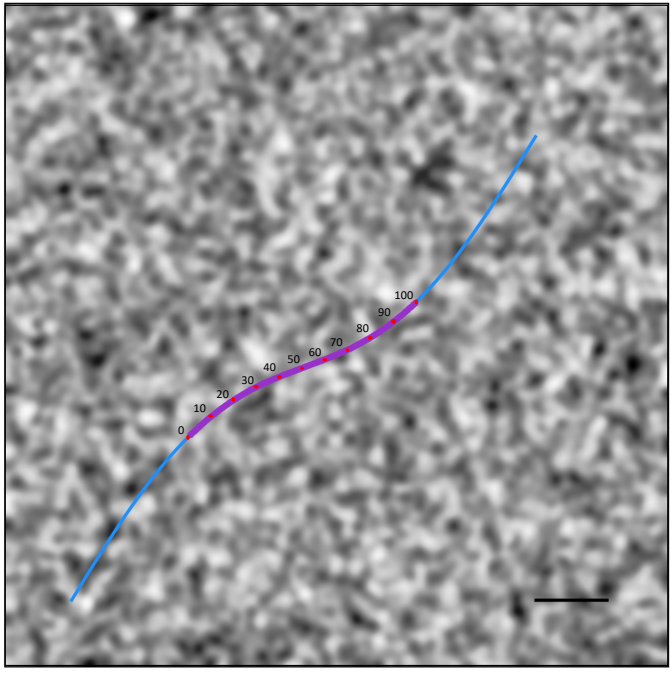


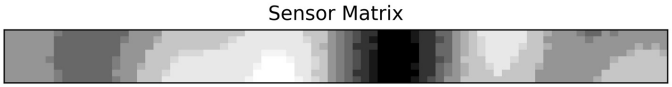


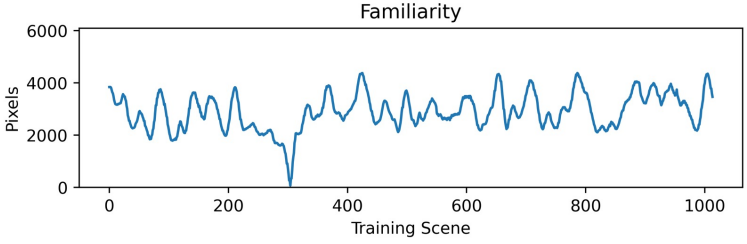
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

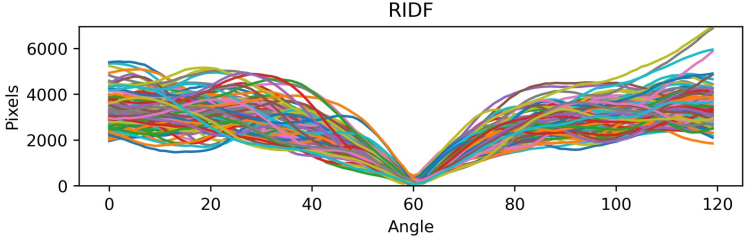
Navigation stats: RMSD error: 87.37; RMSD/dist: 0.218; TD: 2471; p90: 40; p50: 18; complete: 0

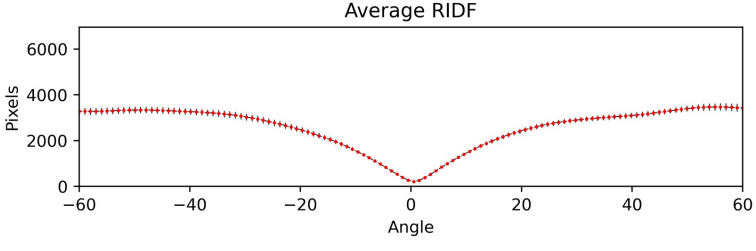
100%







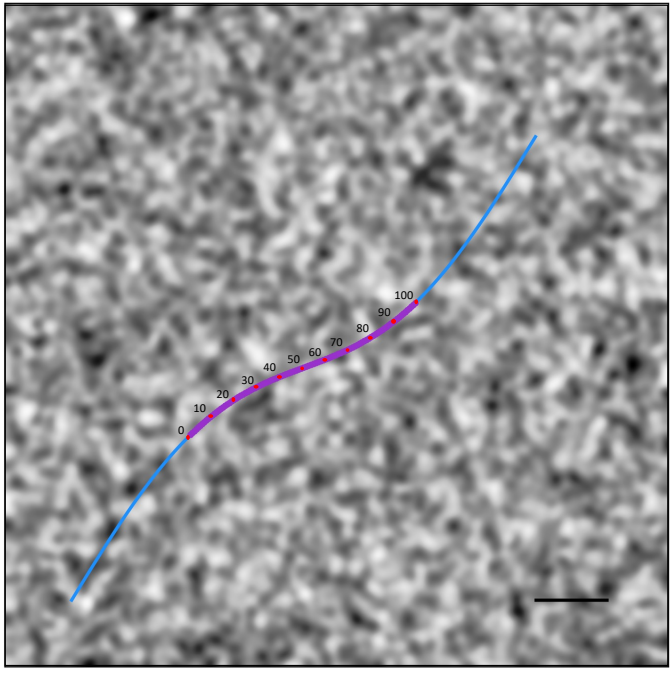


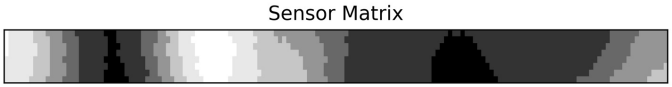


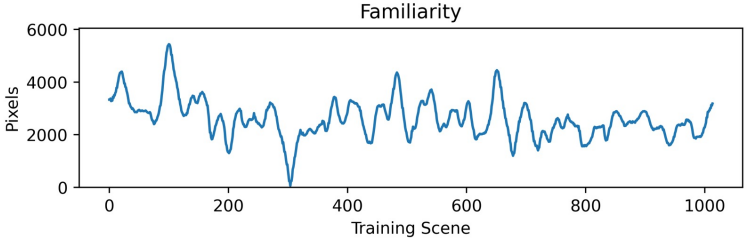
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

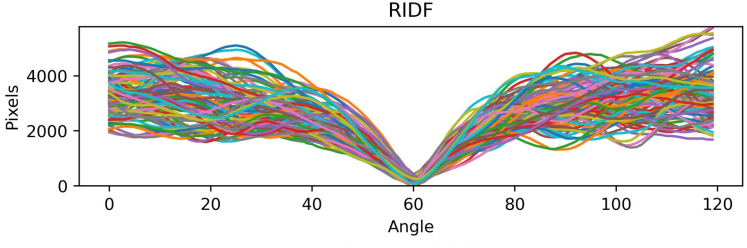
Navigation stats: RMSD error: 61.33; RMSD/dist: 0.153; TD: 2561; p90: 42; p50: 20; complete: 0

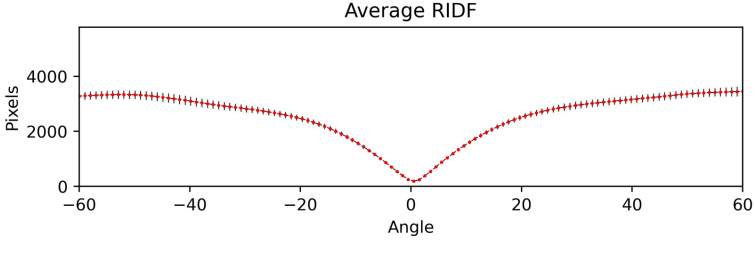
100%





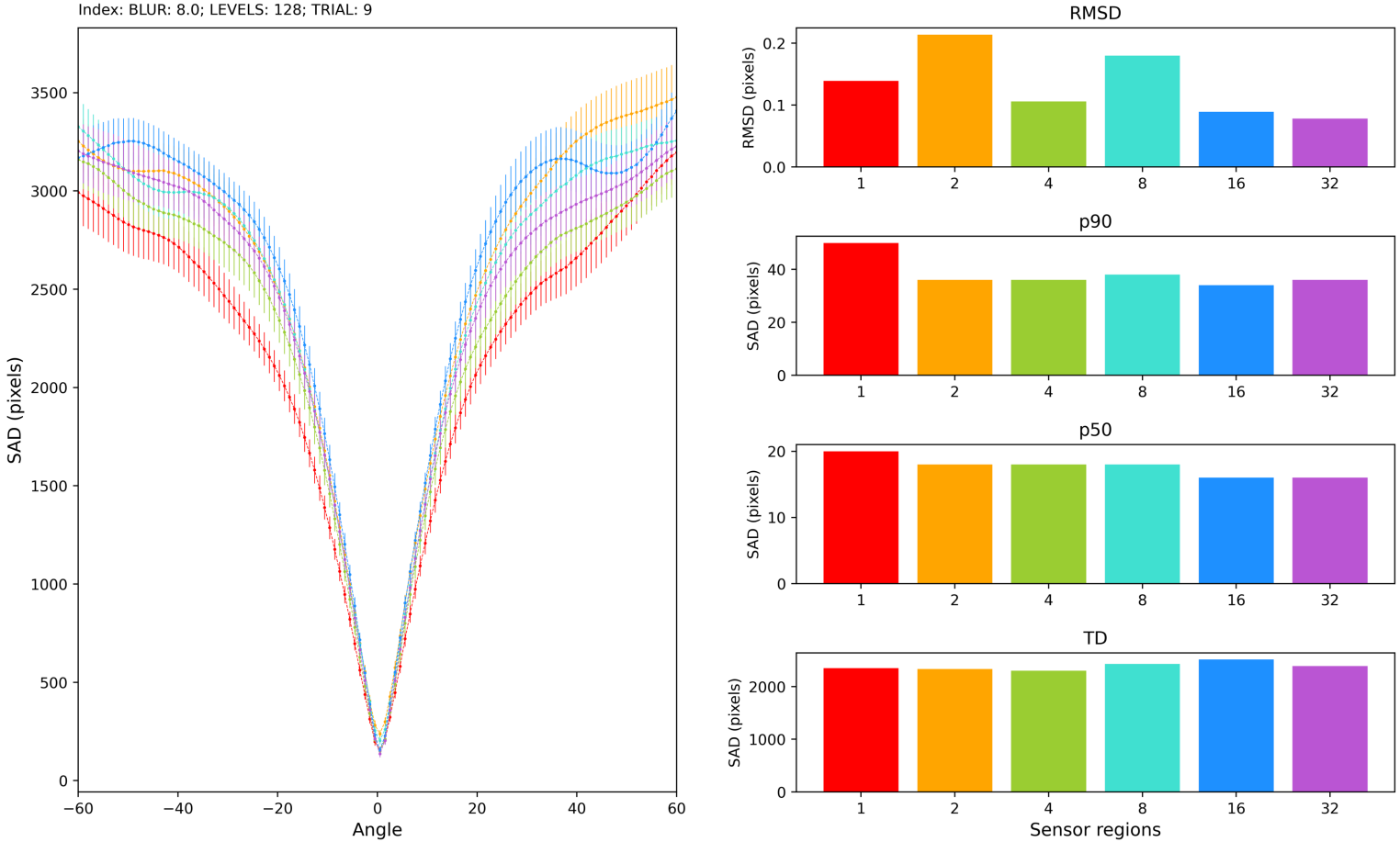




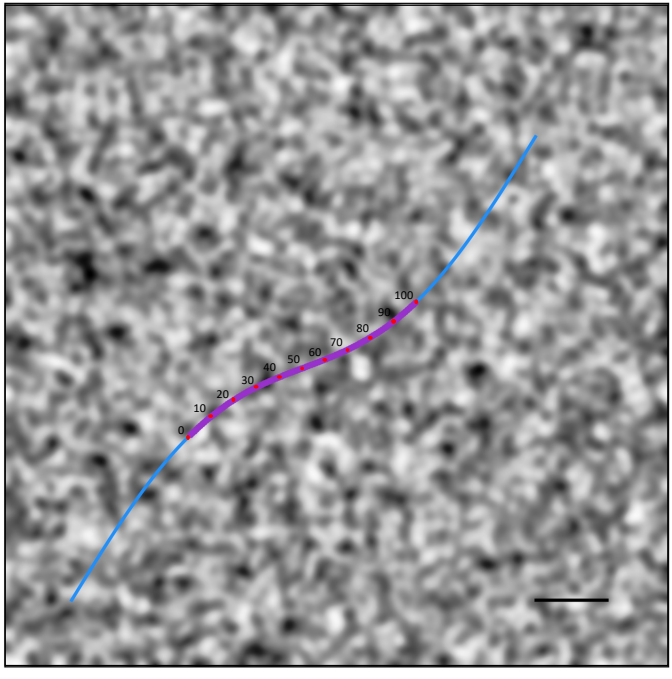


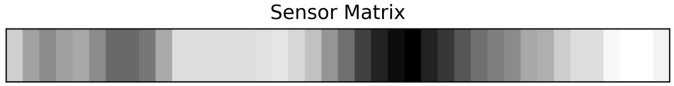
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

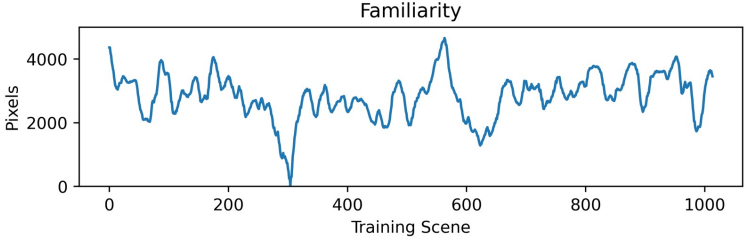
Navigation stats: RMSD error: 43.73; RMSD/dist: 0.109; TD: 2592; p90: 42; p50: 18; complete: 0

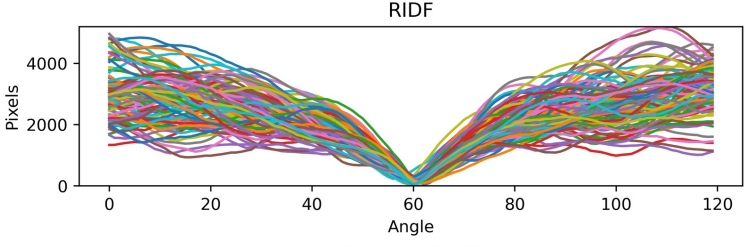

Index: BLUR: 8.0; LEVELS: 128; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

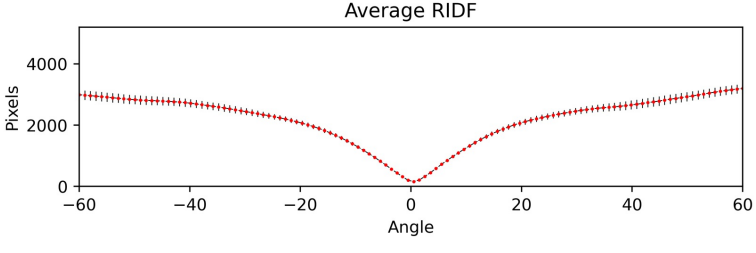
100%







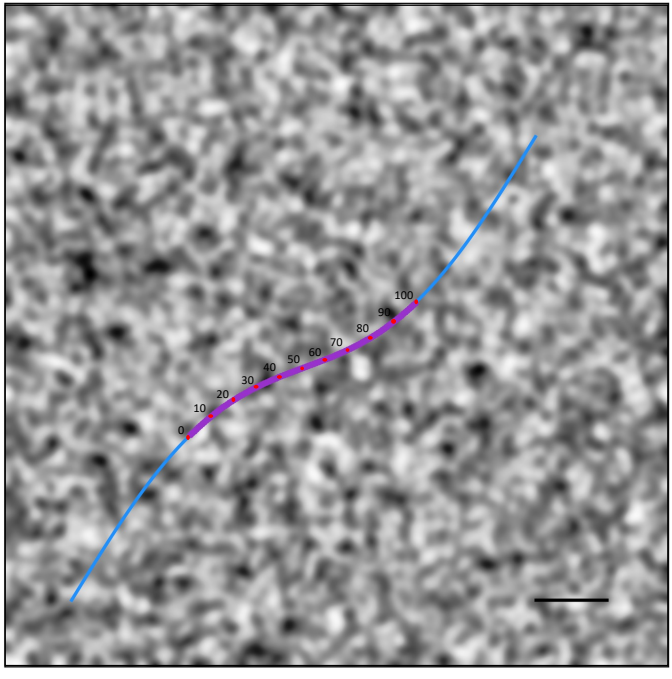


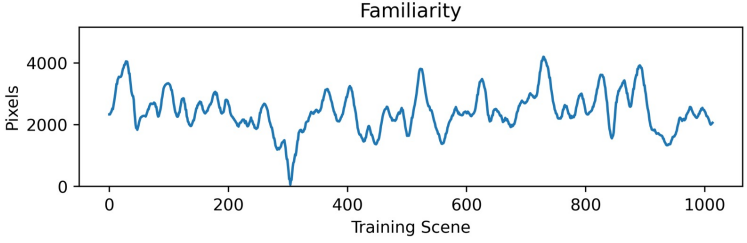


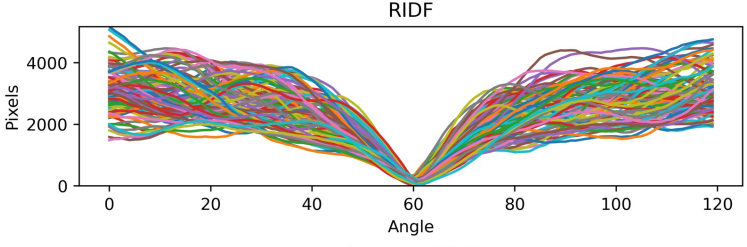
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

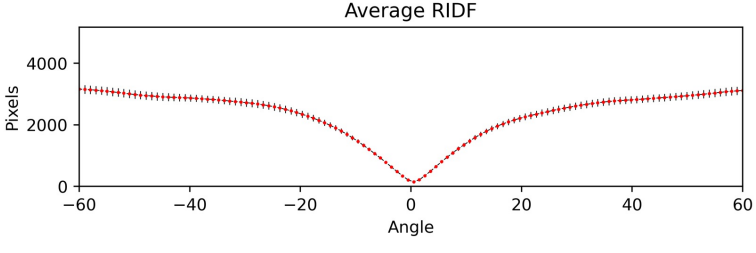
Navigation stats: RMSD error: 55.68; RMSD/dist: 0.139; TD: 2348; p90: 50; p50: 20; complete: 0

100%





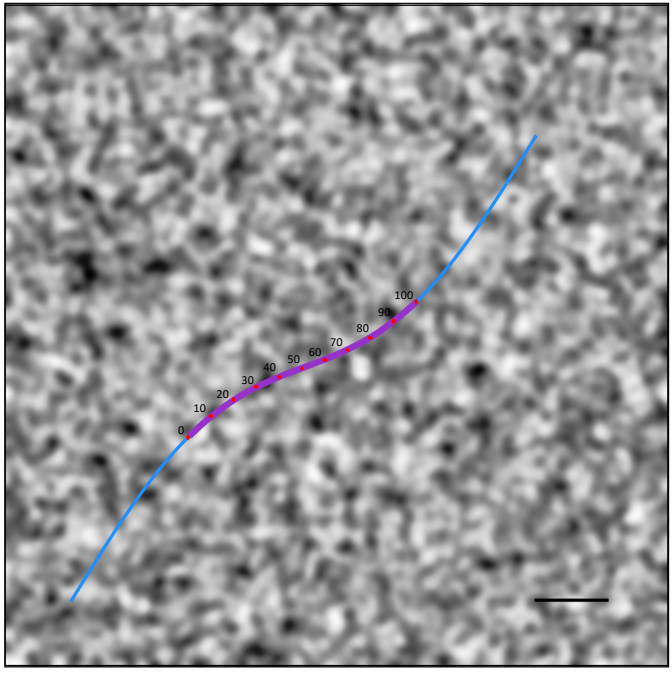


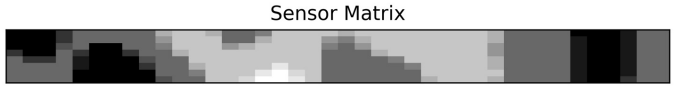


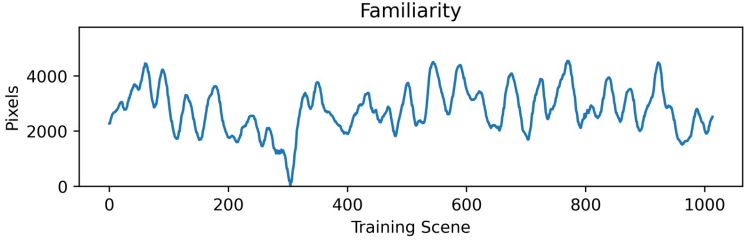
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

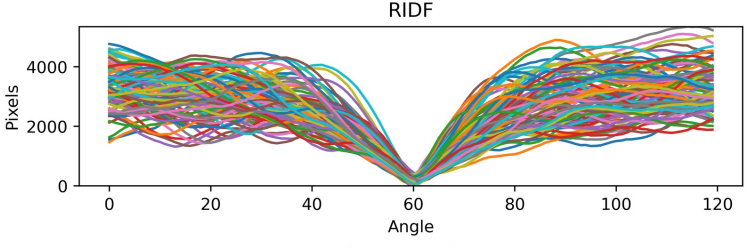
Navigation stats: RMSD error: 42.46; RMSD/dist: 0.106; TD: 2301; p90: 36; p50: 18; complete: 0

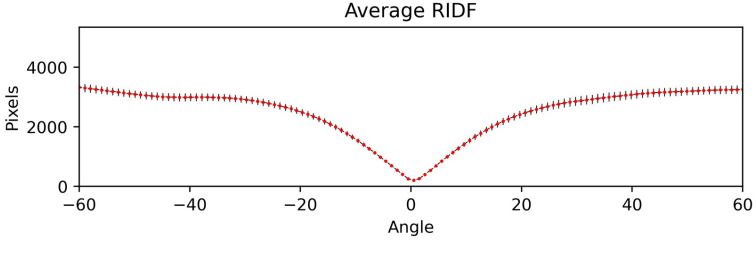
100%







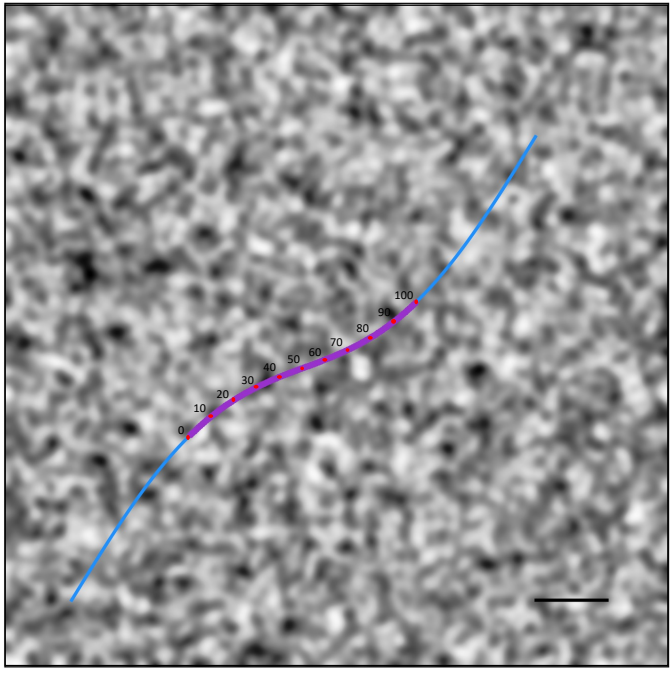


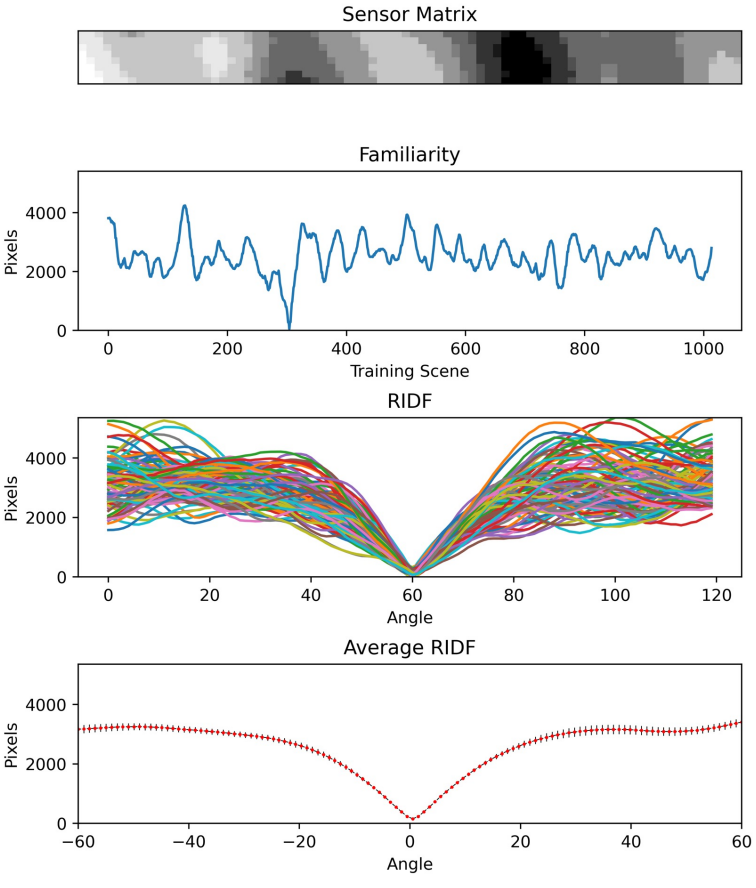


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 71.94; RMSD/dist: 0.180; TD: 2429; p90: 38; p50: 18; complete: 0

100%

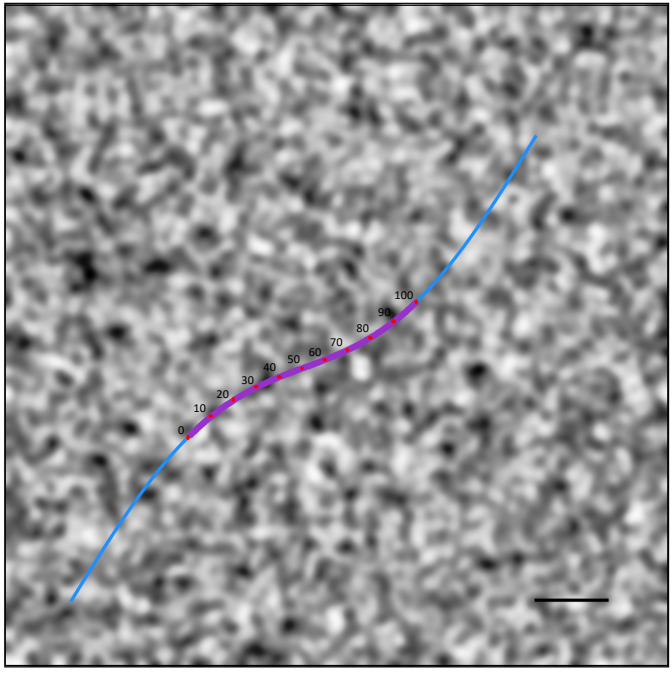


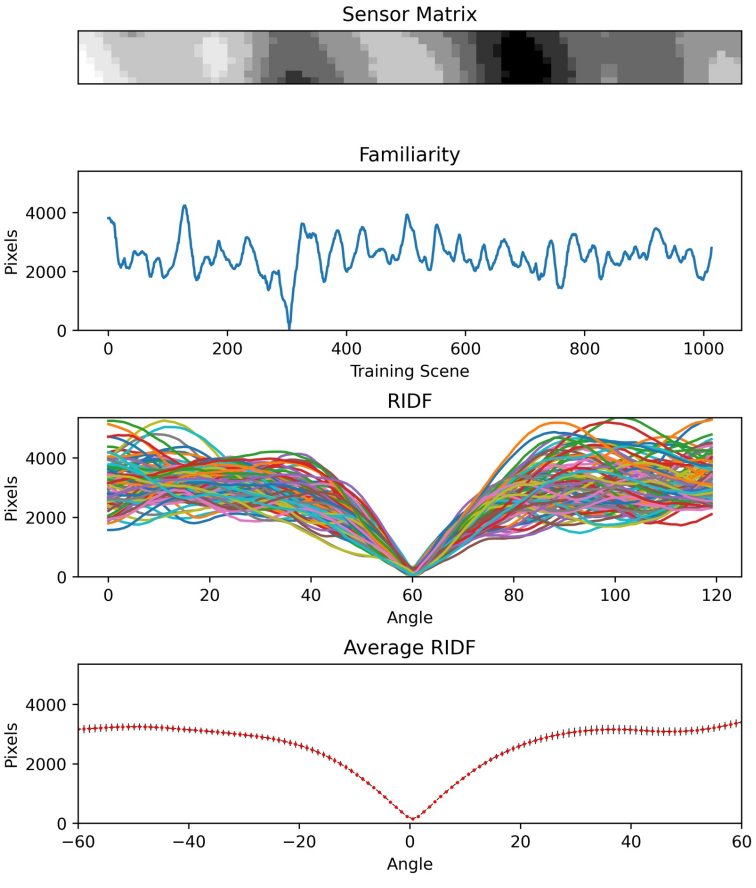


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 35.47; RMSD/dist: 0.089; TD: 2512; p90: 34; p50: 16; complete: 0

100%

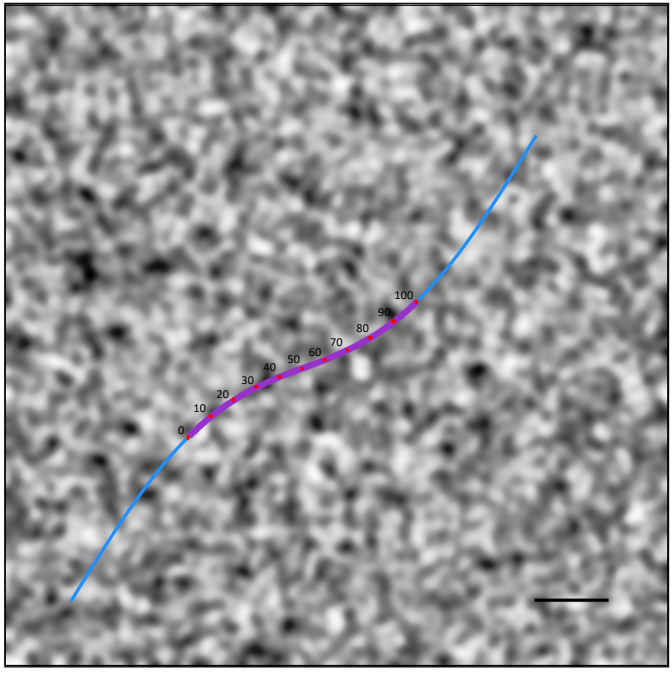


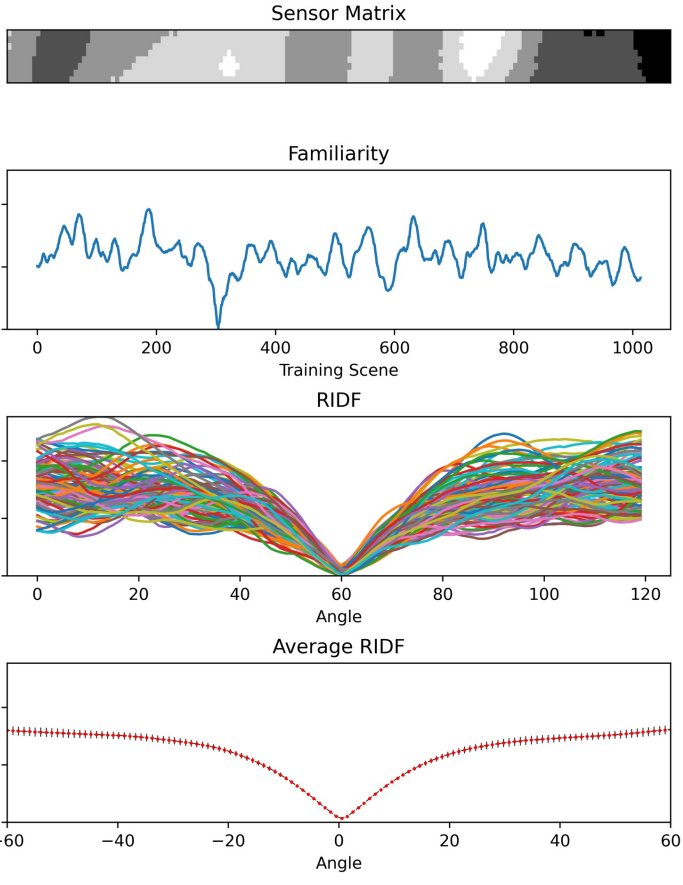


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 35.47; RMSD/dist: 0.089; TD: 2512; p90: 34; p50: 16; complete: 0

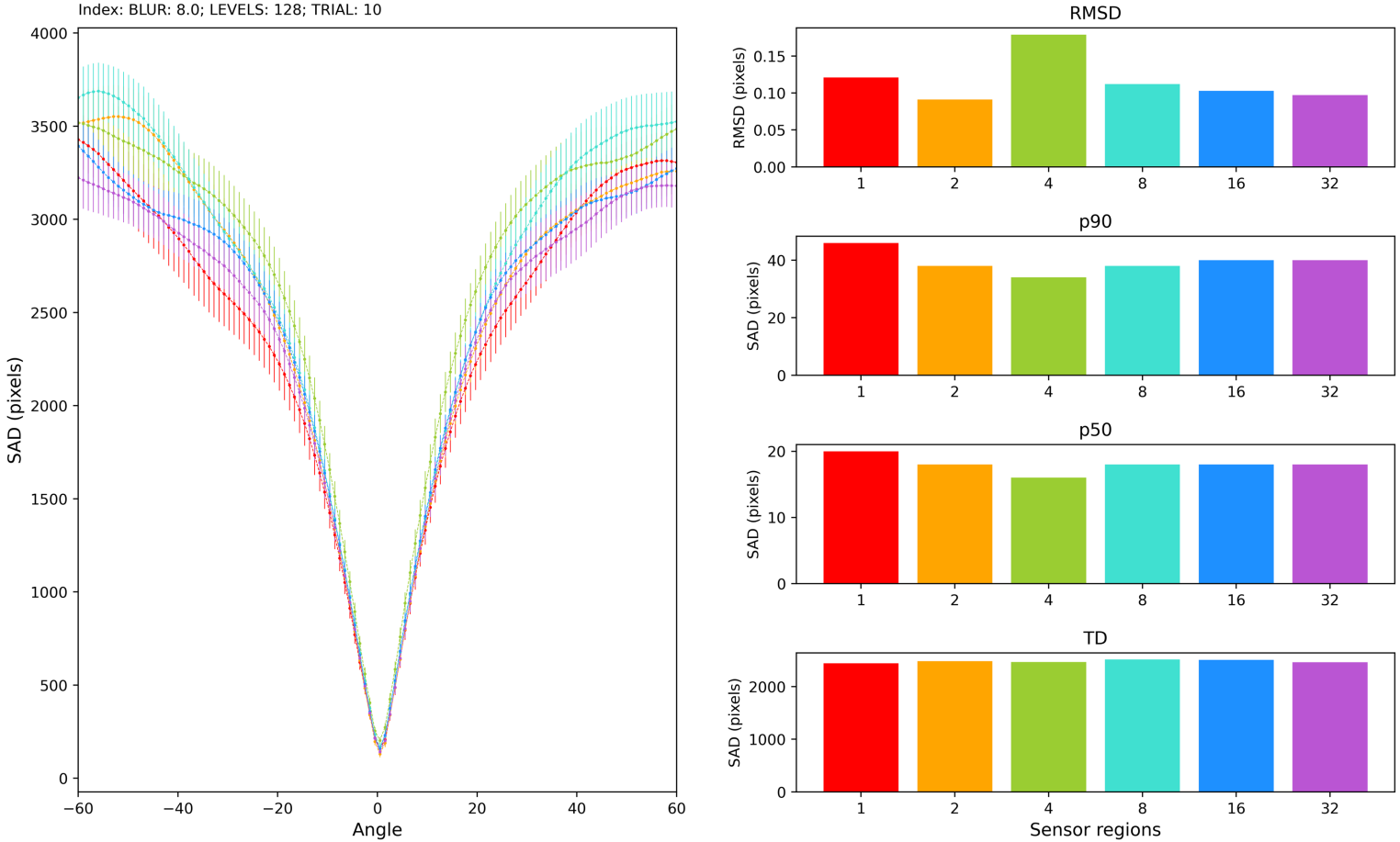
100%



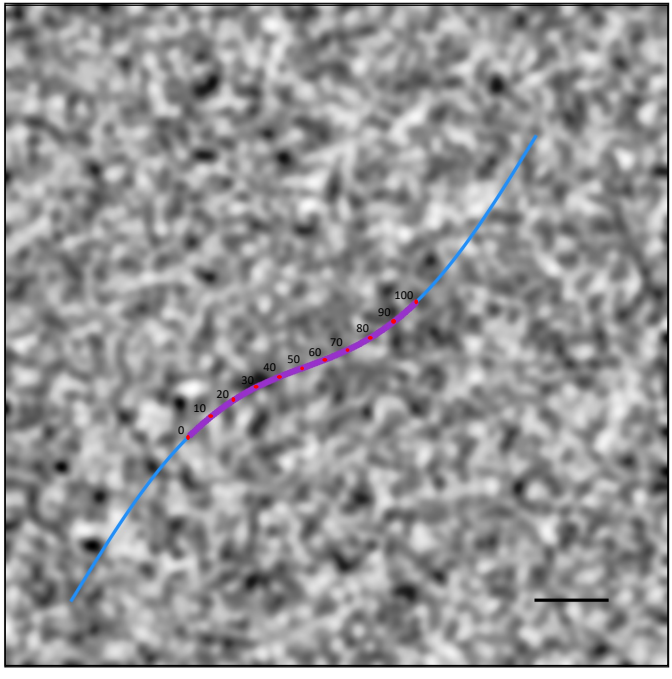


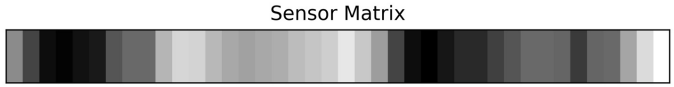
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

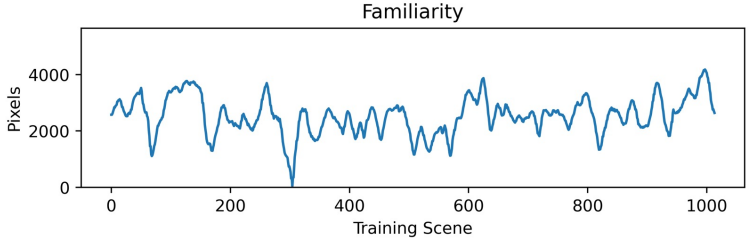
Navigation stats: RMSD error: 31.34; RMSD/dist: 0.078; TD: 2391; p90: 36; p50: 16; complete: 0

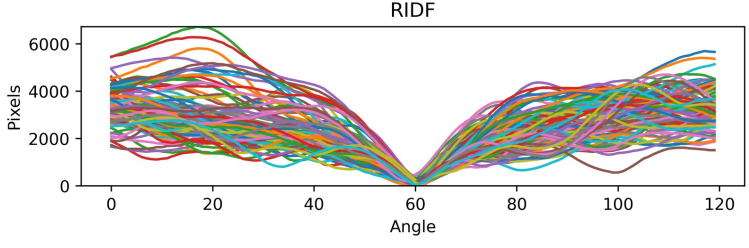

Index: BLUR: 8.0; LEVELS: 128; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

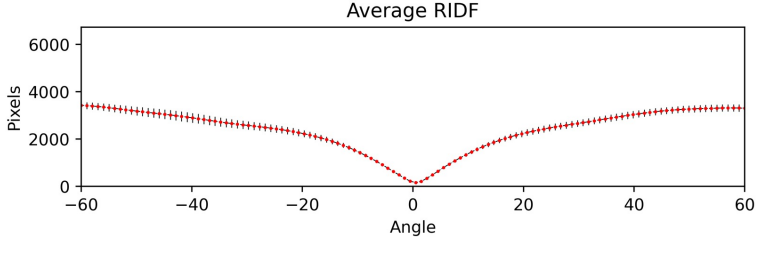
100%







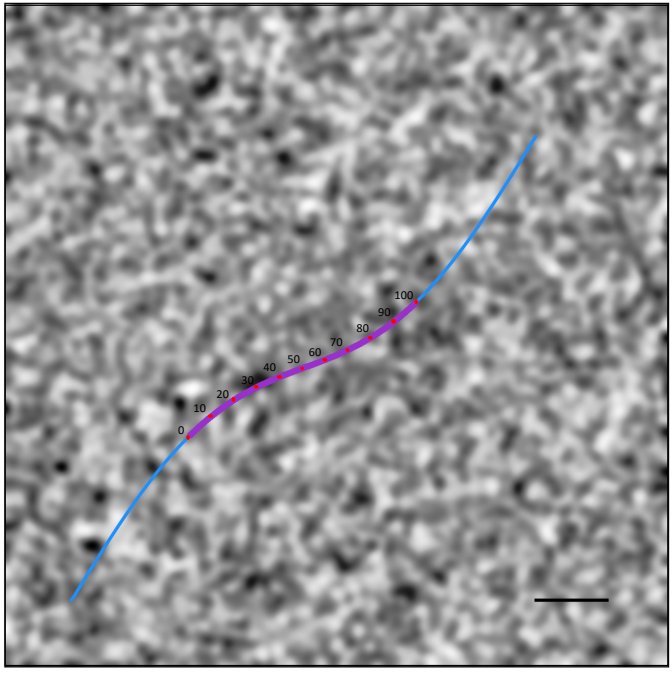


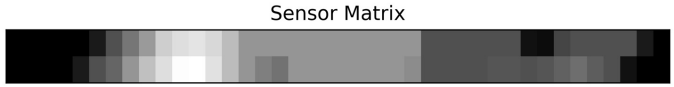


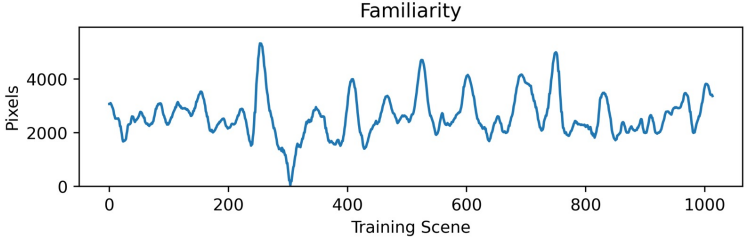
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

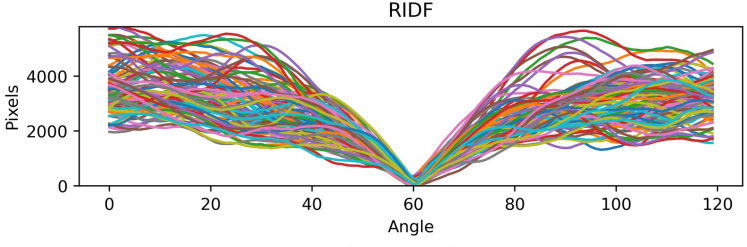
Navigation stats: RMSD error: 48.20; RMSD/dist: 0.121; TD: 2441; p90: 46; p50: 20; complete: 0

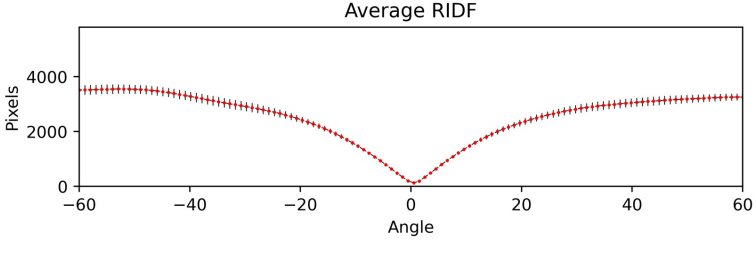
100%







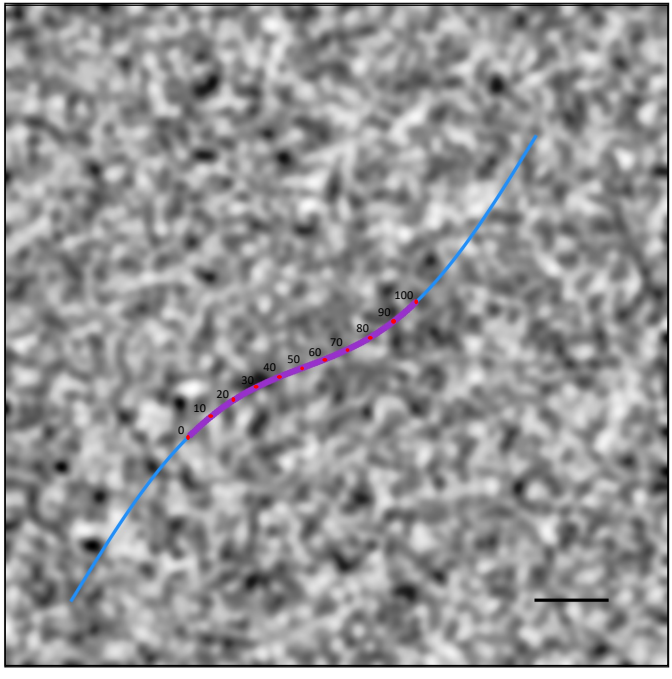


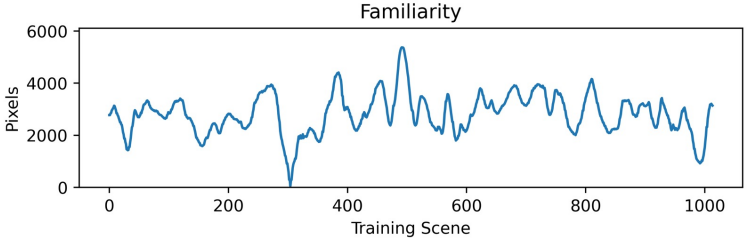


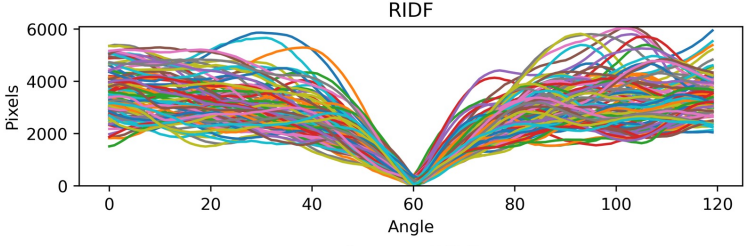
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

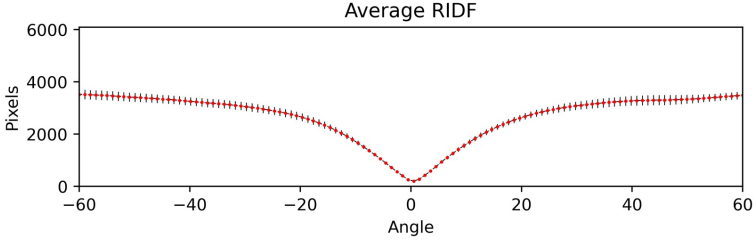
Navigation stats: RMSD error: 36.26; RMSD/dist: 0.091; TD: 2482; p90: 38; p50: 18; complete: 0

100%





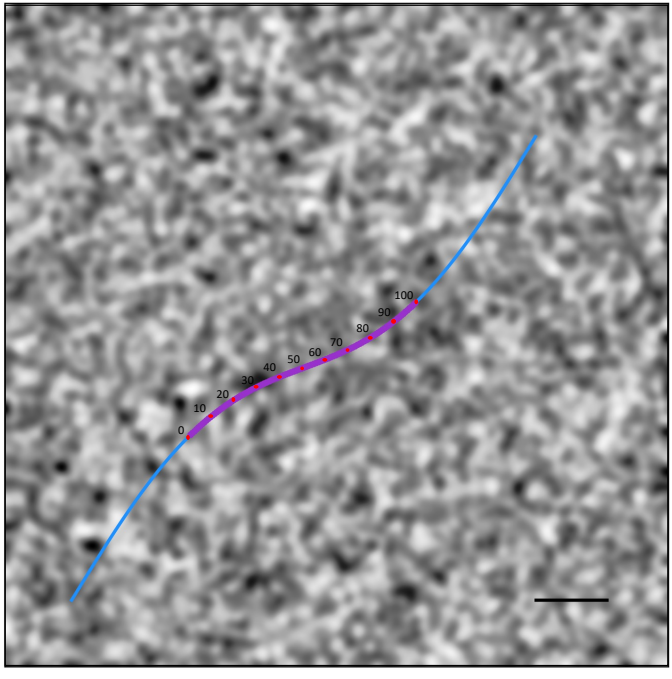


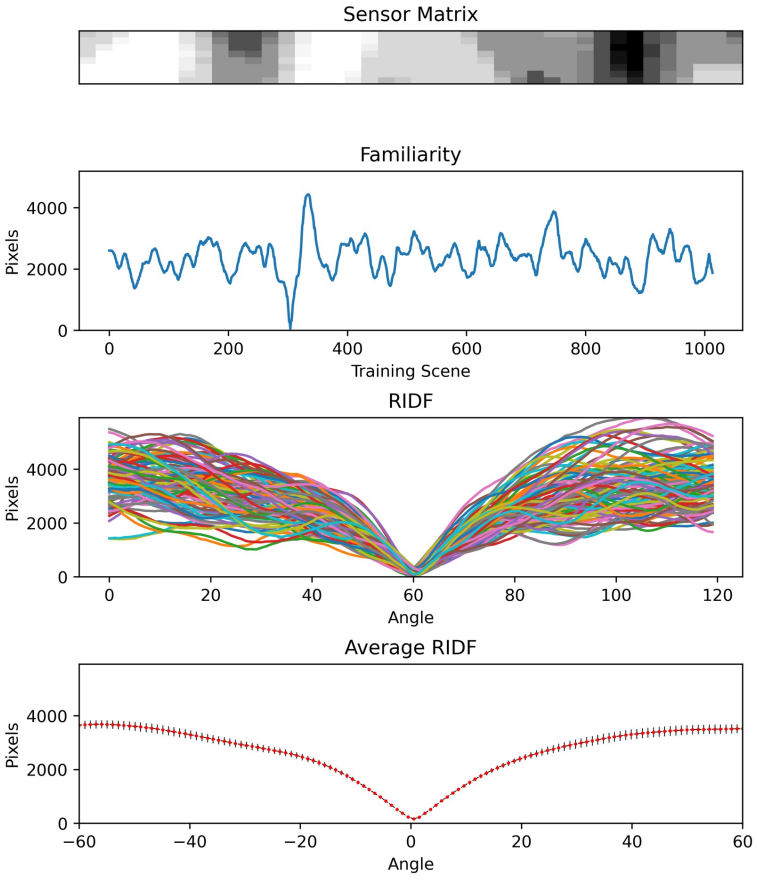


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 71.67; RMSD/dist: 0.179; TD: 2467; p90: 34; p50: 16; complete: 0

100%

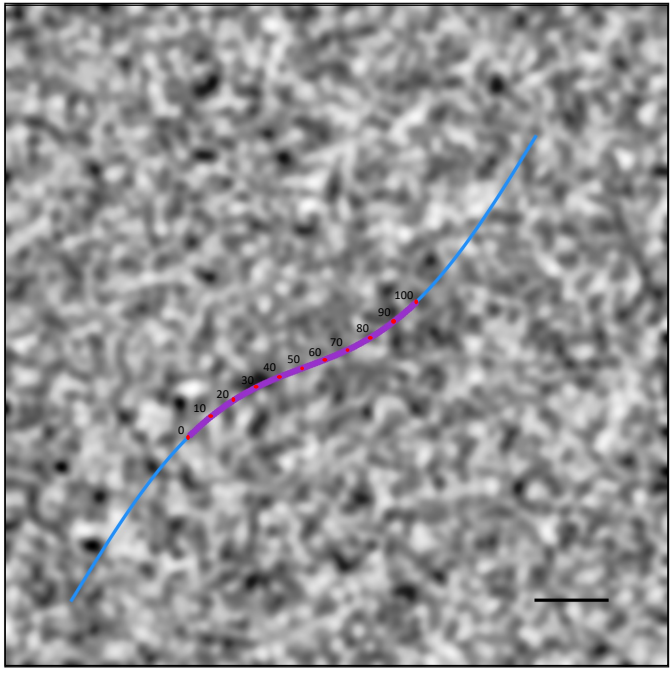


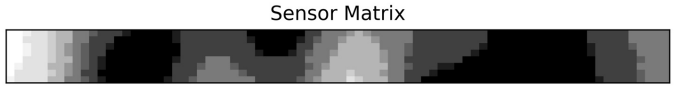


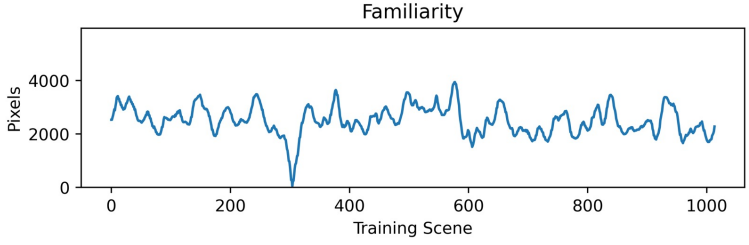
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

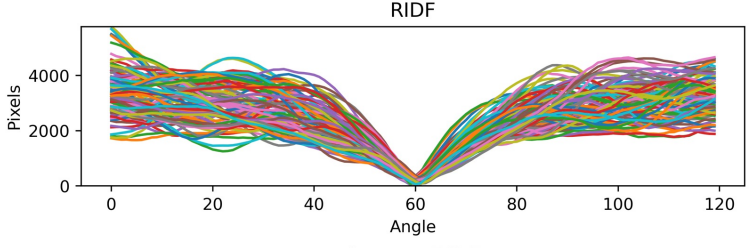
Navigation stats: RMSD error: 44.72; RMSD/dist: 0.112; TD: 2512; p90: 38; p50: 18; complete: 0

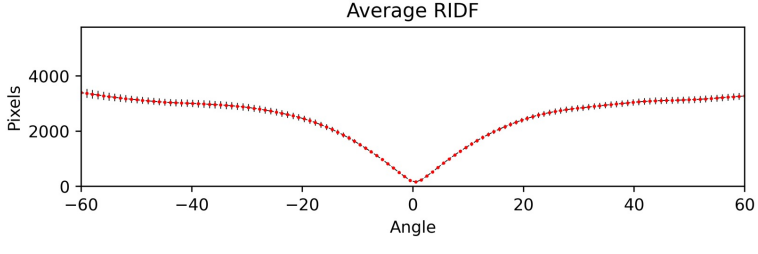
100%







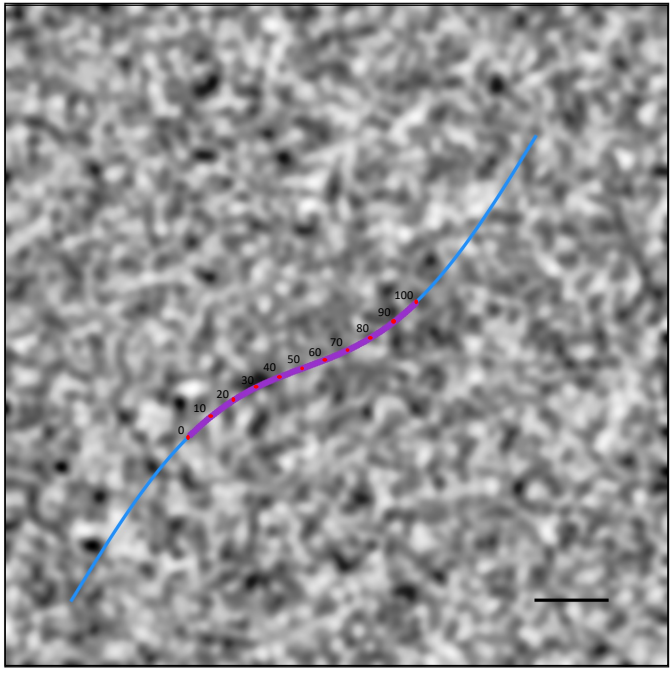


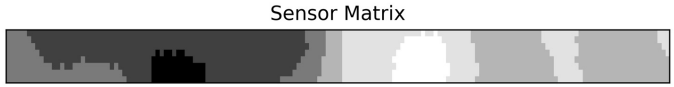


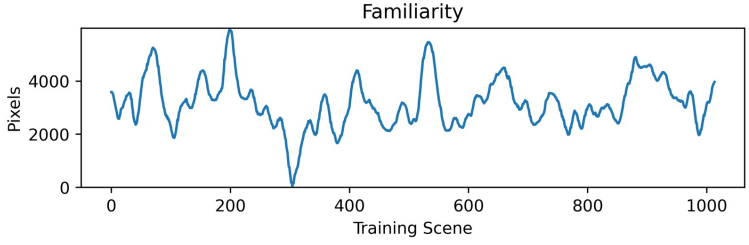
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

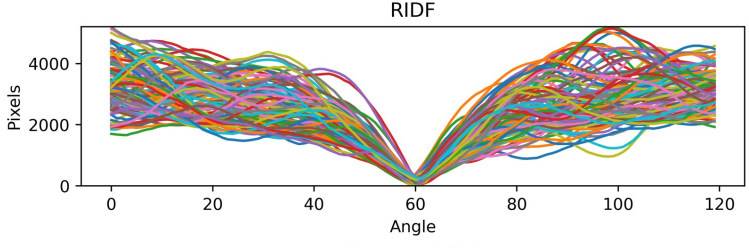
Navigation stats: RMSD error: 41.30; RMSD/dist: 0.103; TD: 2506; p90: 40; p50: 18; complete: 0

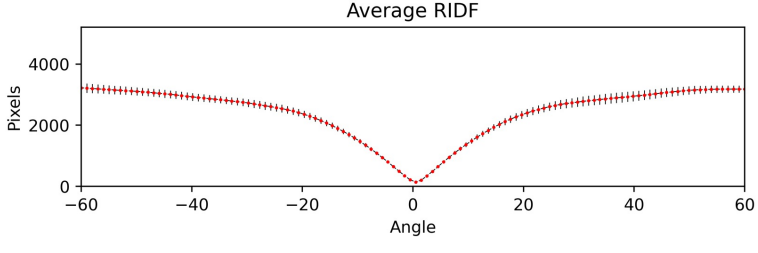
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 38.73; RMSD/dist: 0.097; TD: 2463; p90: 40; p50: 18; complete: 0