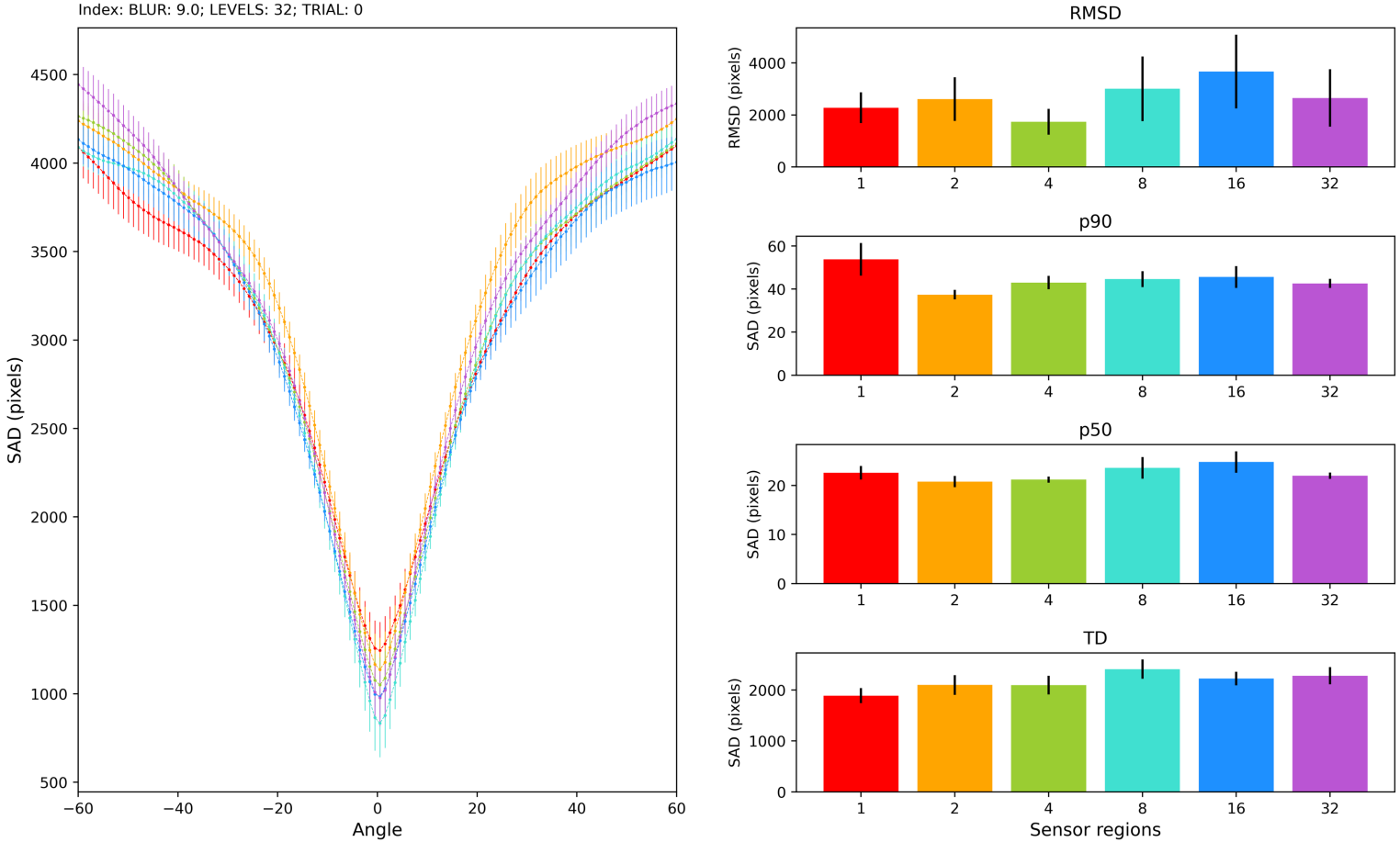
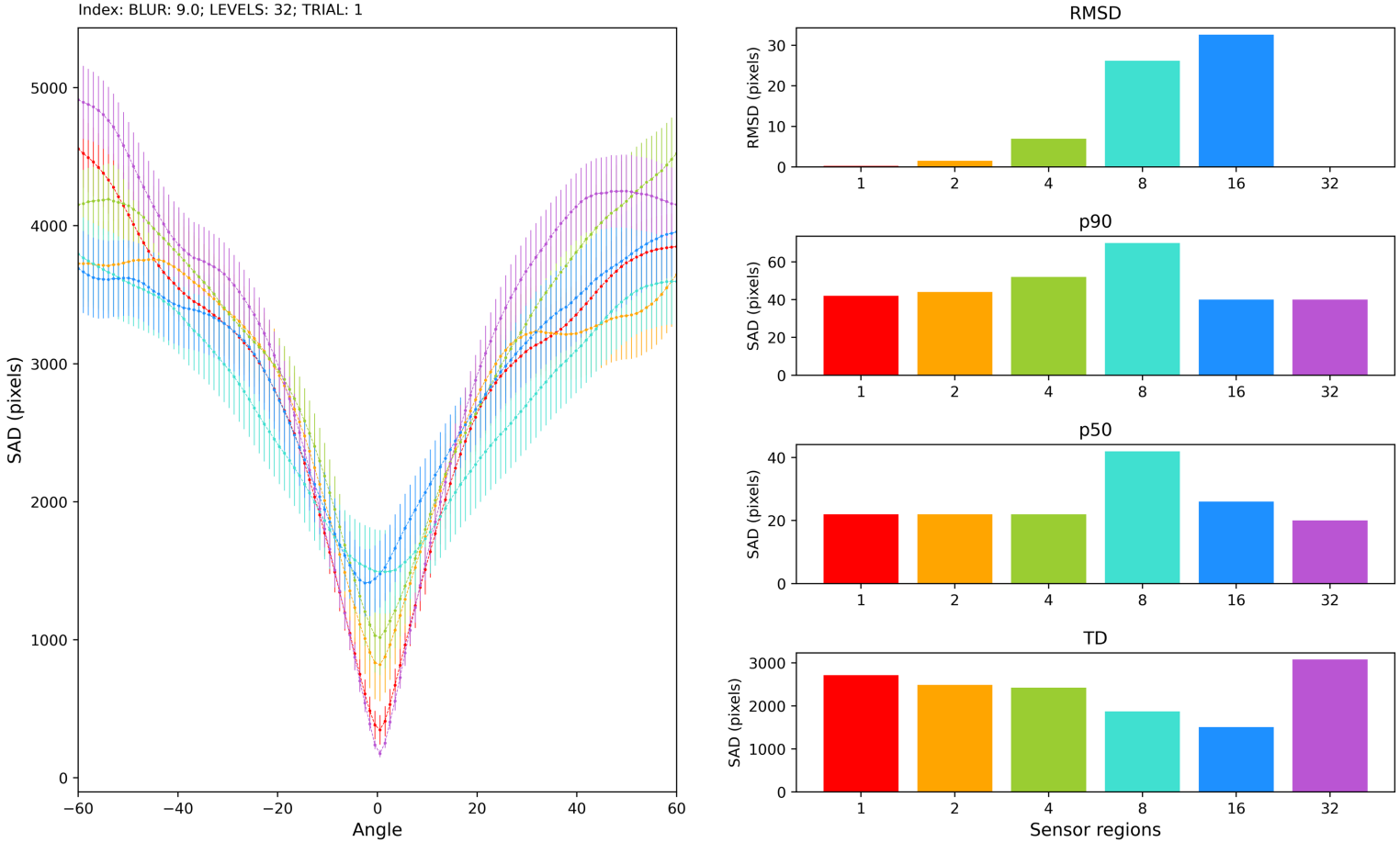

Index: BLUR: 9.0; LEVELS: 32; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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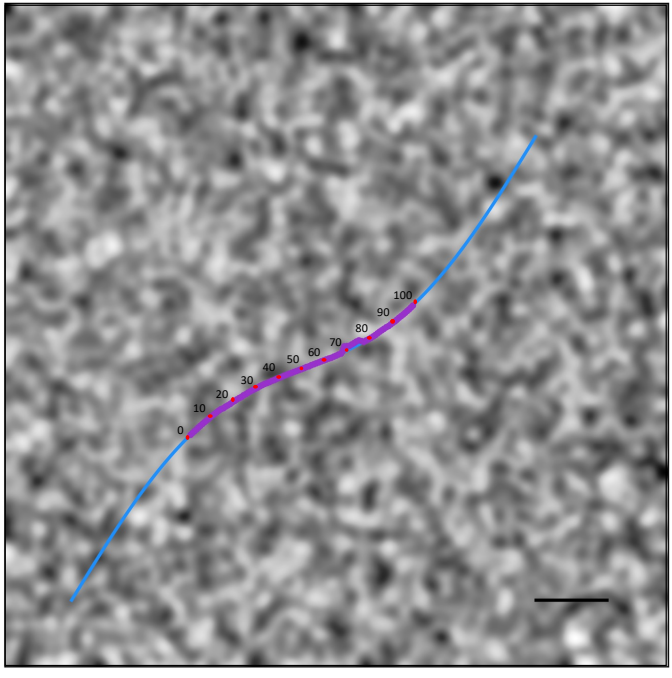
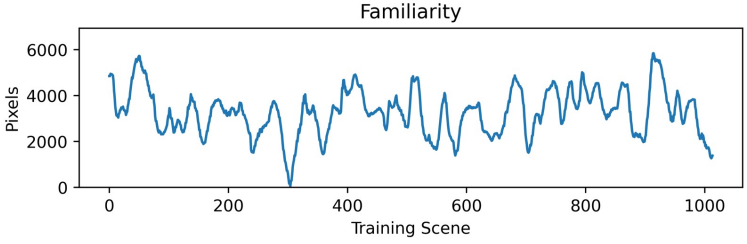
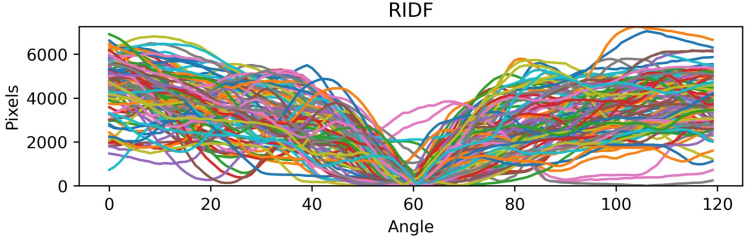
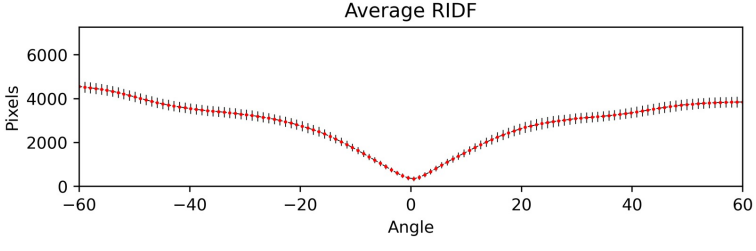
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

90%





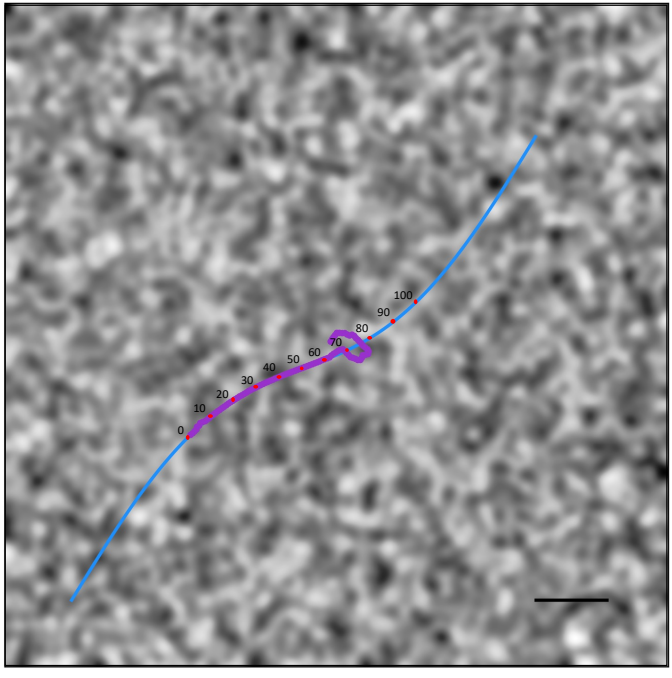


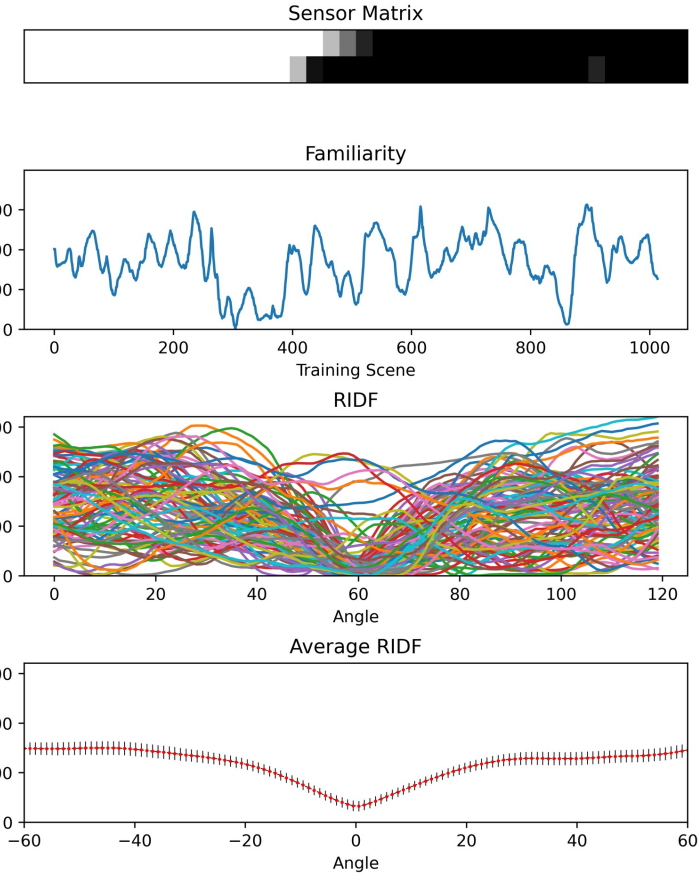


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 90.98; RMSD/dist: 0.227; TD: 2715; p90: 42; p50: 22; complete: 0

60%

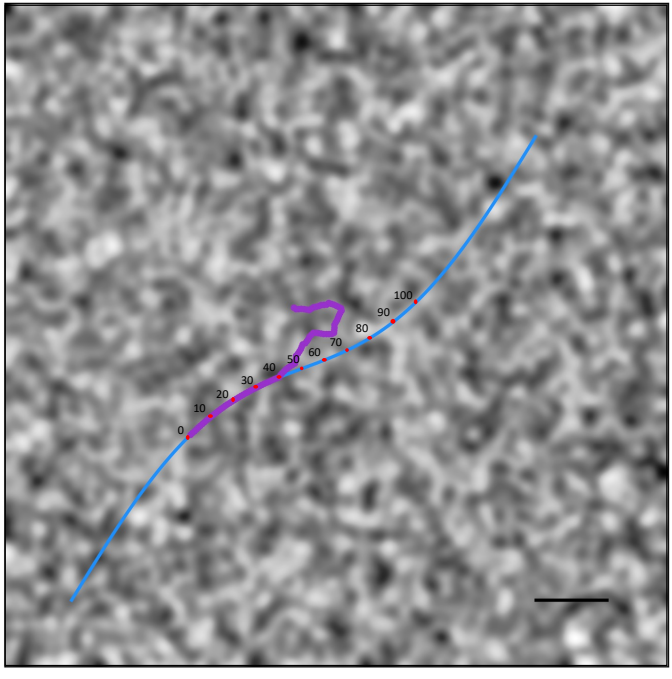


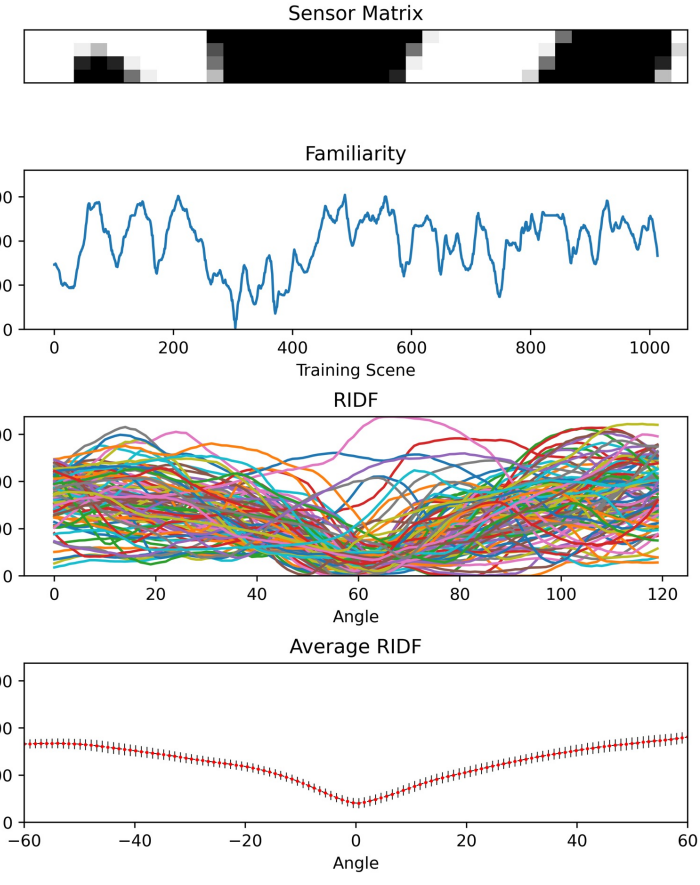


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 596.42; RMSD/dist: 1.491; TD: 2486; p90: 44; p50: 22; complete: 0

40%

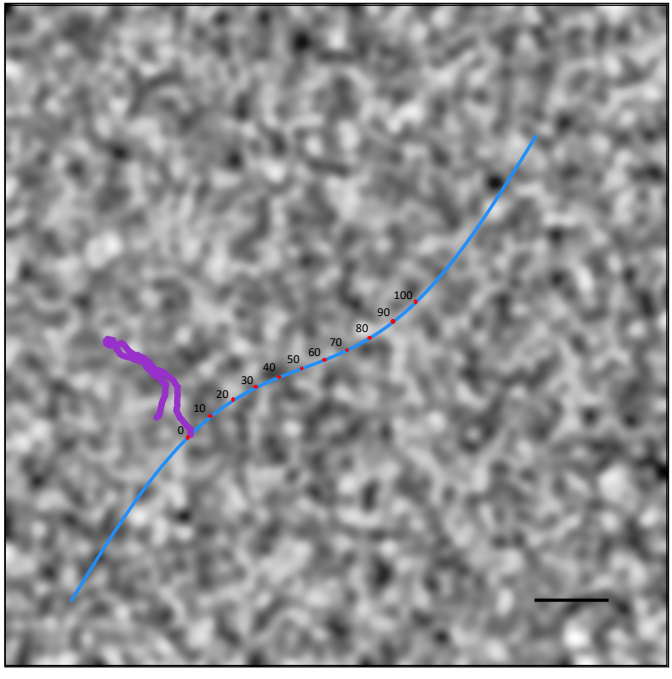


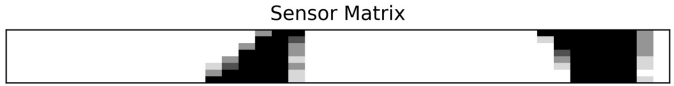


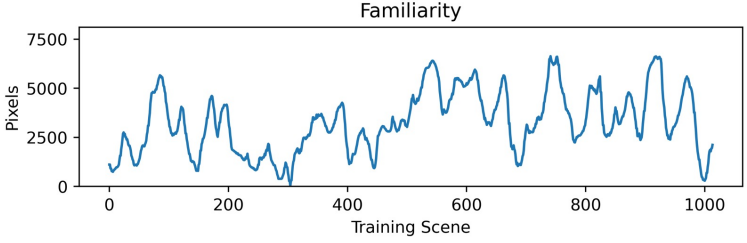
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

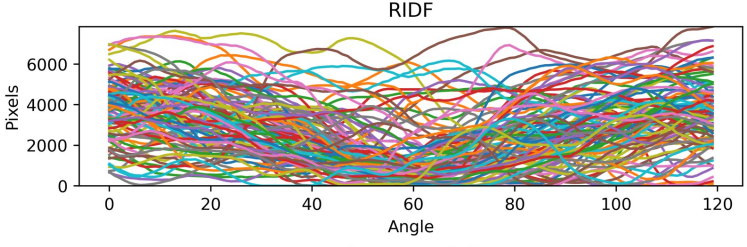
Navigation stats: RMSD error: 2782.31; RMSD/dist: 6.956; TD: 2423; p90: 52; p50: 22; complete: 0

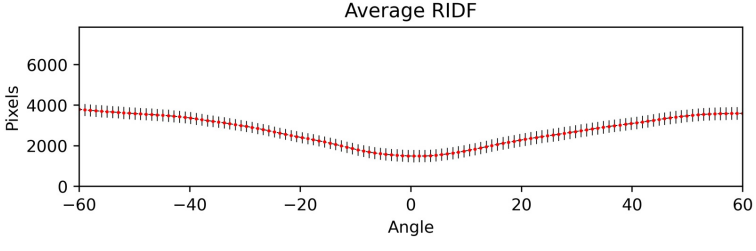
0%







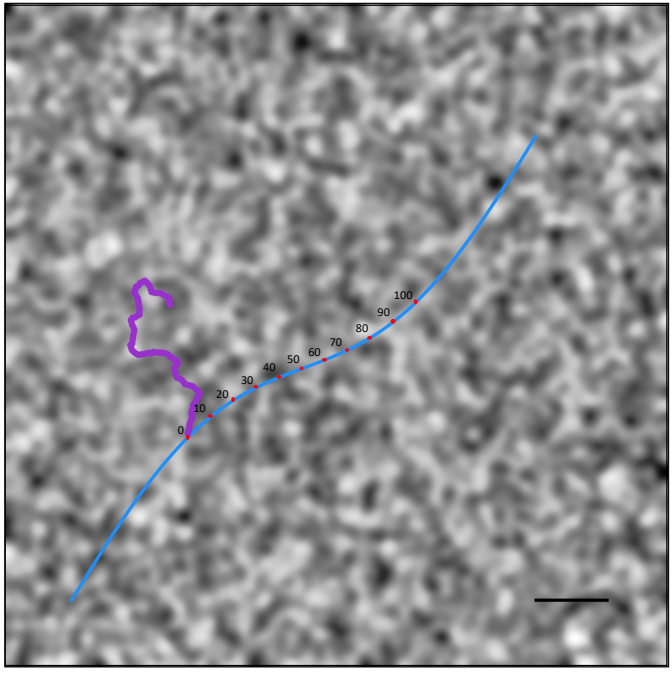


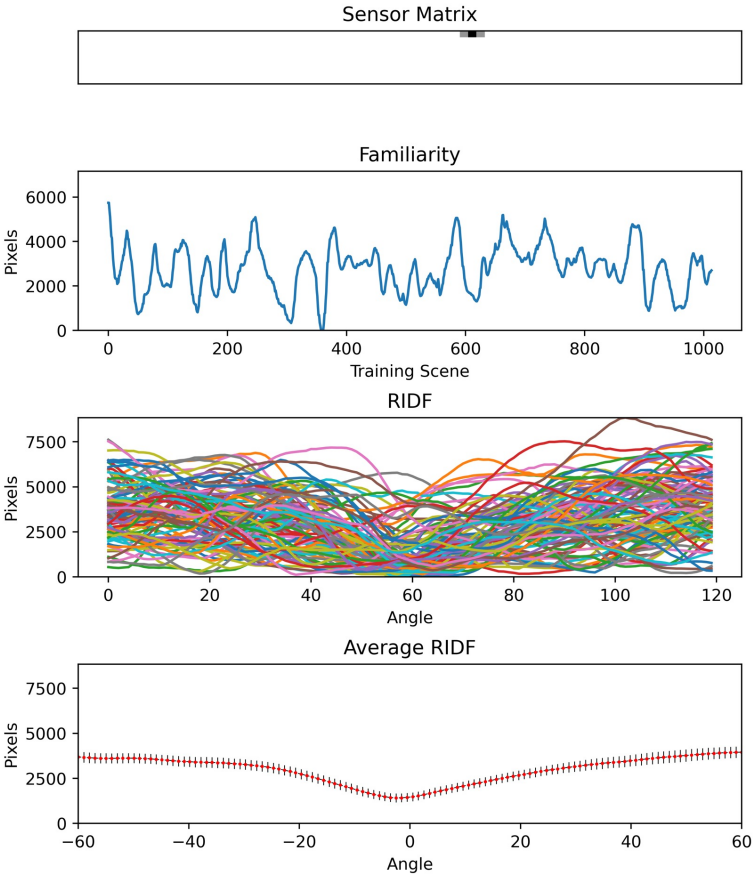


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 10469.47; RMSD/dist: 26.174; TD: 1870; p90: 70; p50: 42; complete: 0

0%

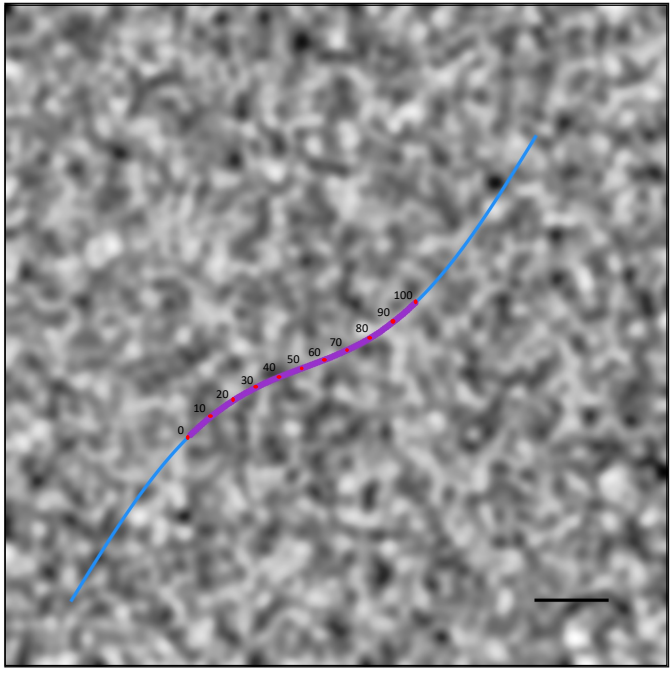


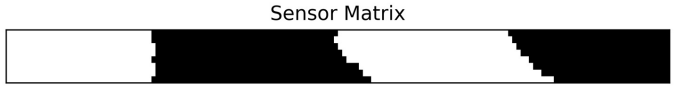


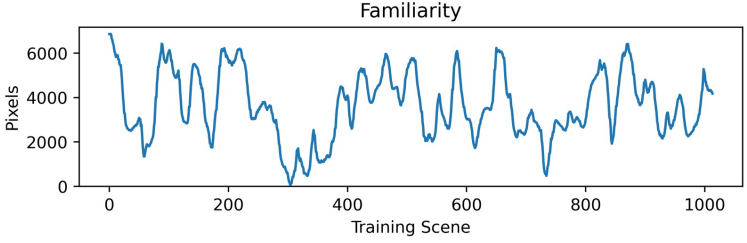
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

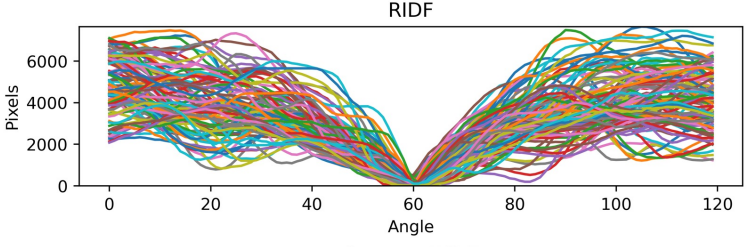
Navigation stats: RMSD error: 13060.86; RMSD/dist: 32.652; TD: 1504; p90: 40; p50: 26; complete: 0

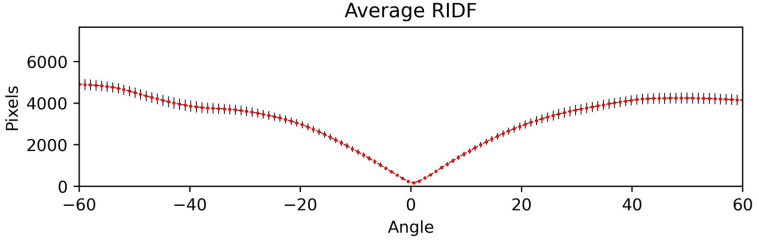
100%





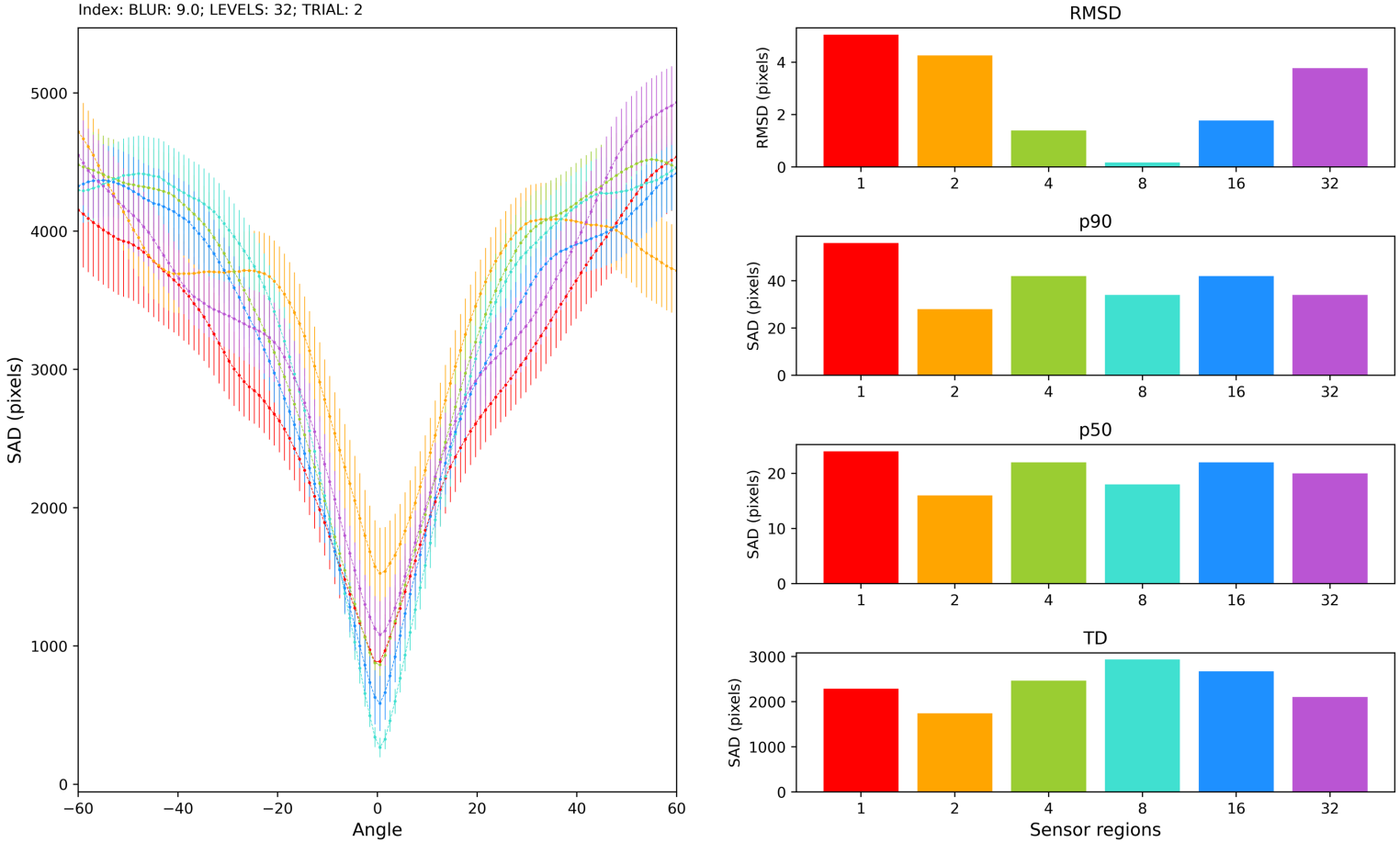




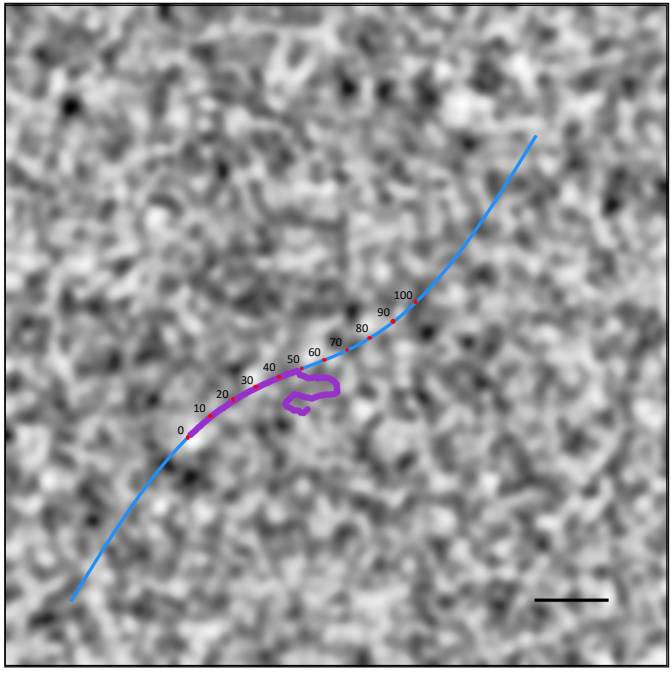


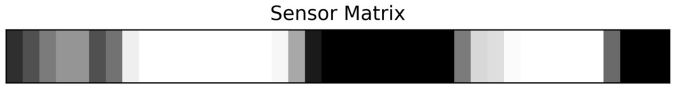
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

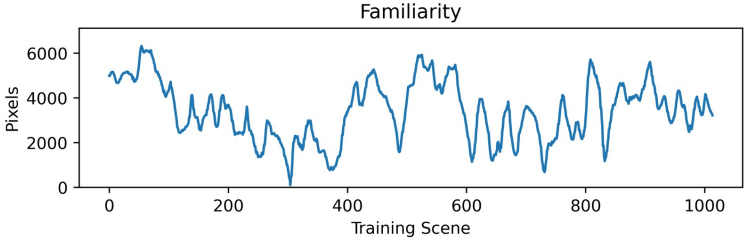
Navigation stats: RMSD error: 39.48; RMSD/dist: 0.099; TD: 3076; p90: 40; p50: 20; complete: 0

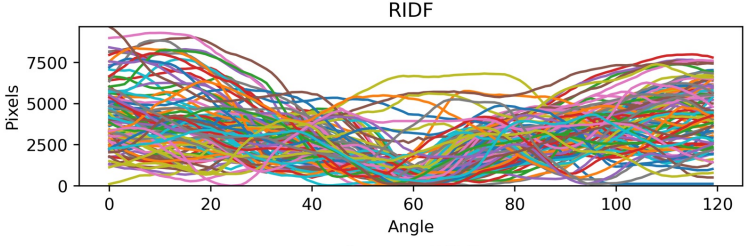

Index: BLUR: 9.0; LEVELS: 32; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

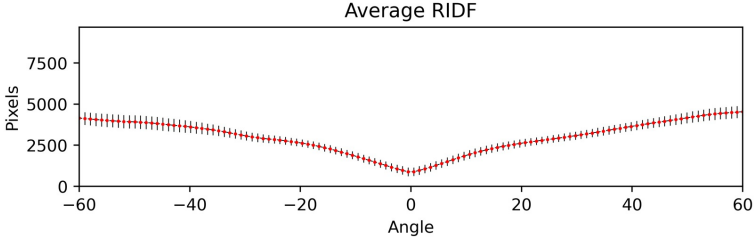
40%







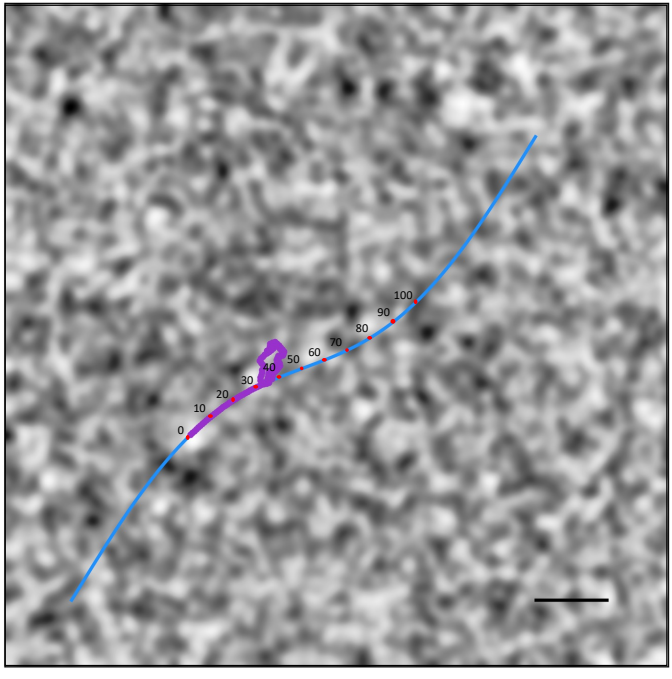


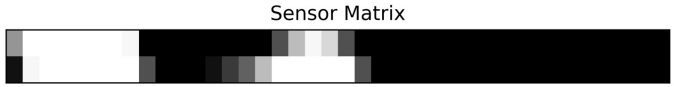


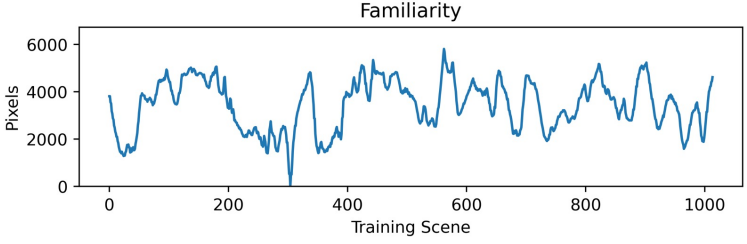
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

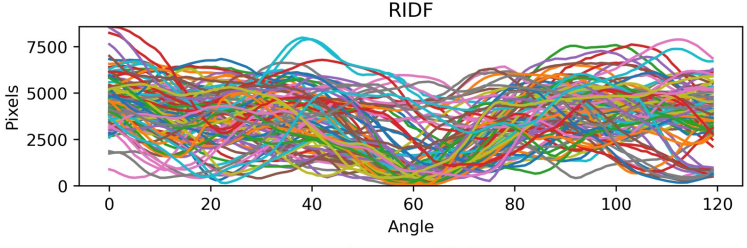
Navigation stats: RMSD error: 2020.96; RMSD/dist: 5.052; TD: 2286; p90: 56; p50: 24; complete: 0

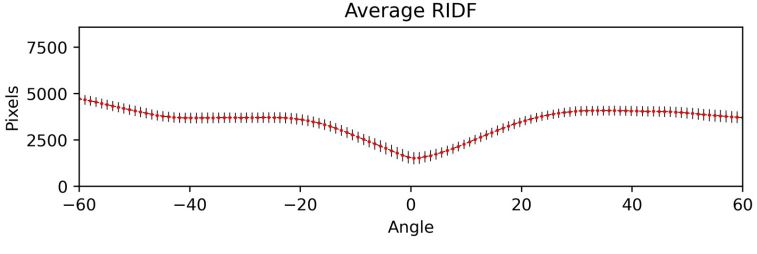
30%







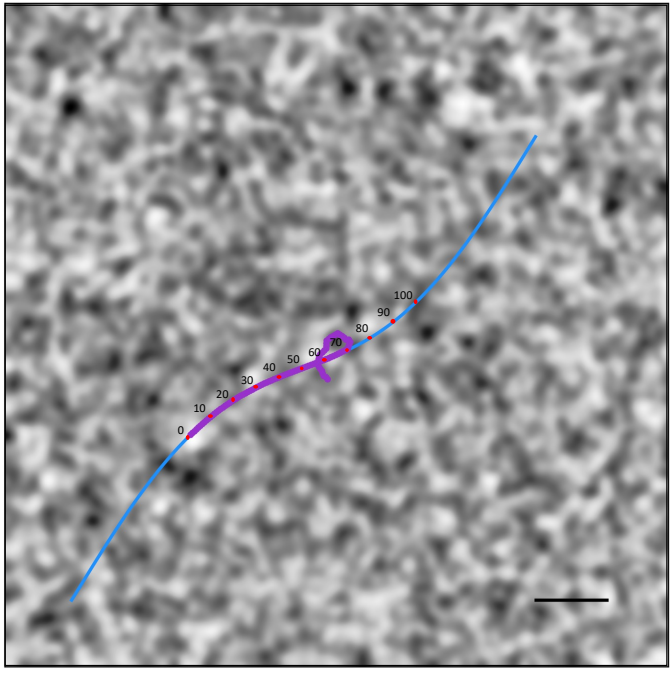


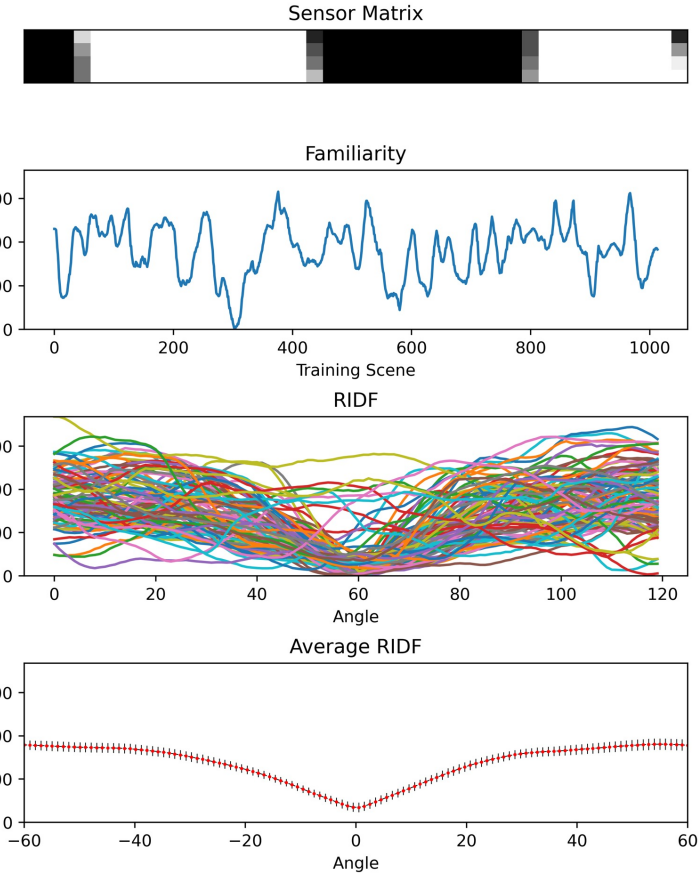


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 1701.09; RMSD/dist: 4.253; TD: 1741; p90: 28; p50: 16; complete: 0

70%

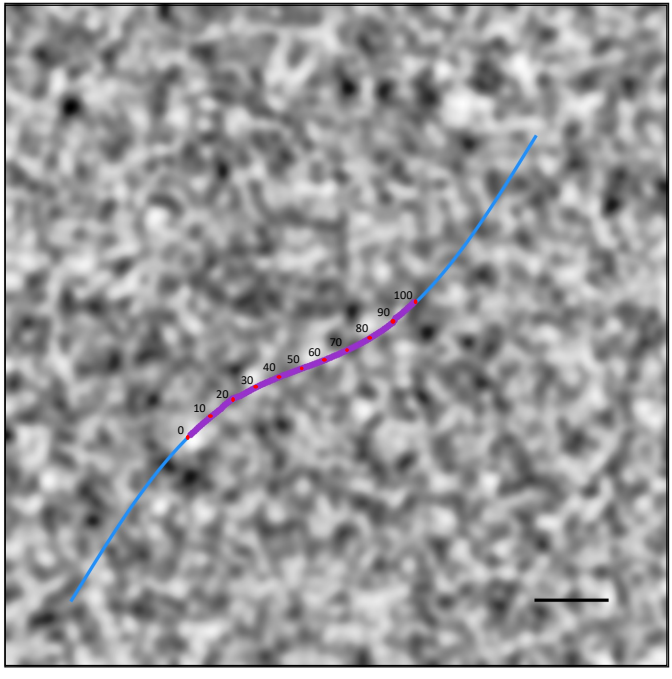


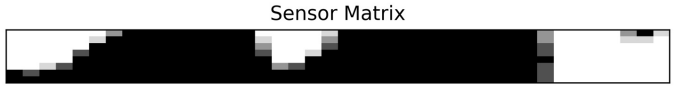


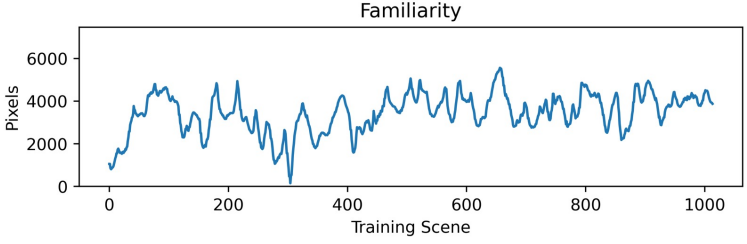
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

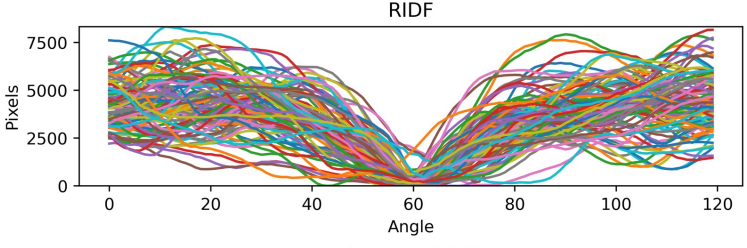
Navigation stats: RMSD error: 554.24; RMSD/dist: 1.386; TD: 2468; p90: 42; p50: 22; complete: 0

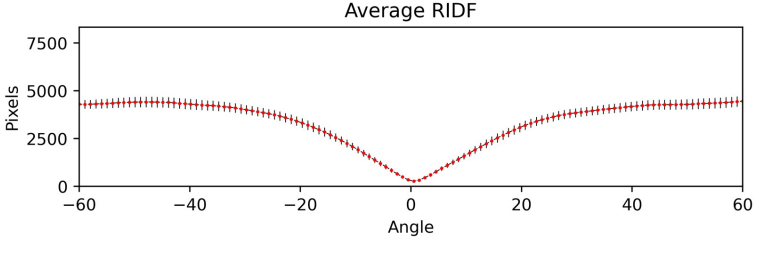
90%







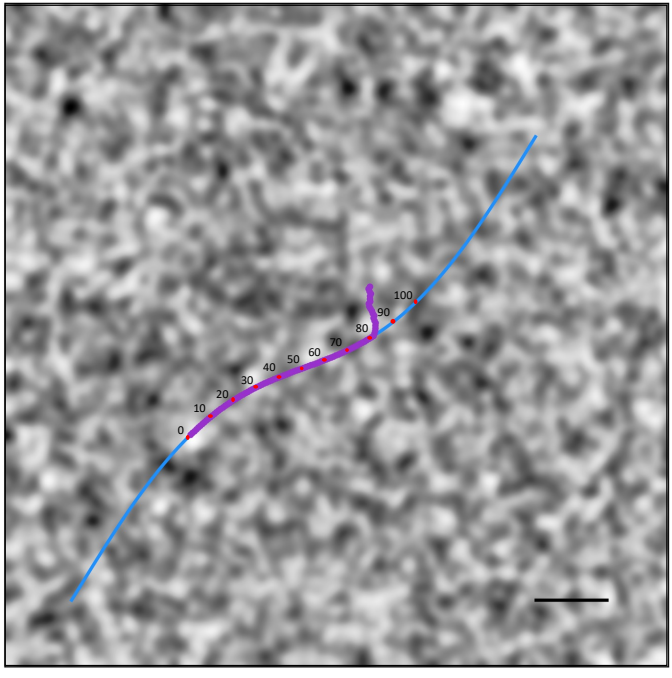


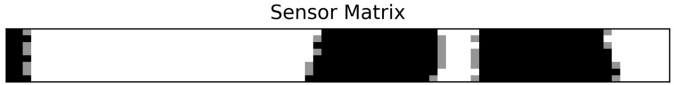


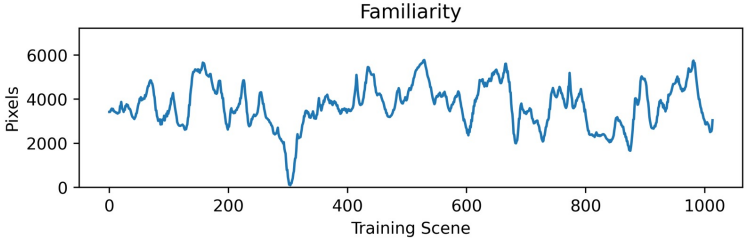
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

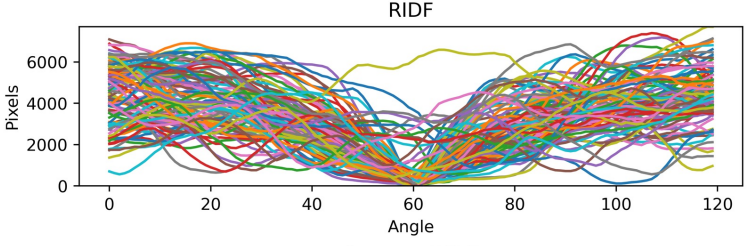
Navigation stats: RMSD error: 66.06; RMSD/dist: 0.165; TD: 2934; p90: 34; p50: 18; complete: 0

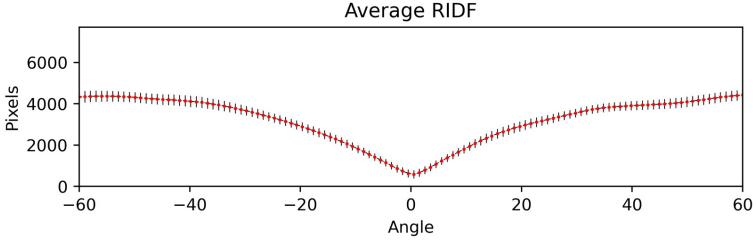
80%







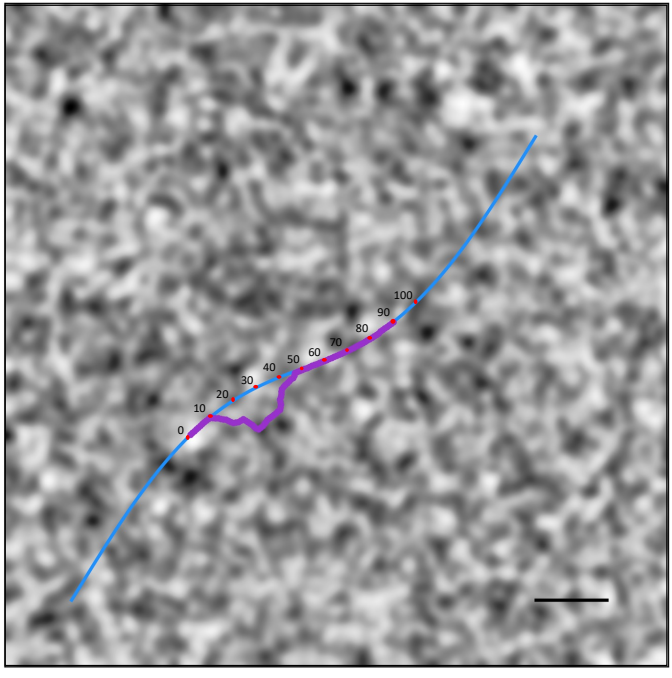


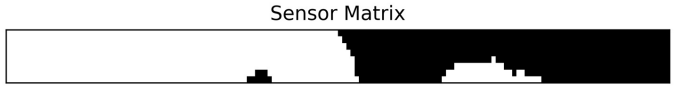


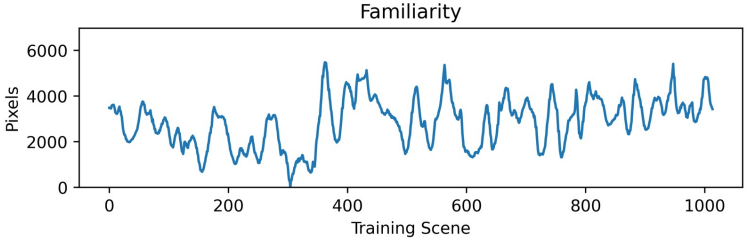
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

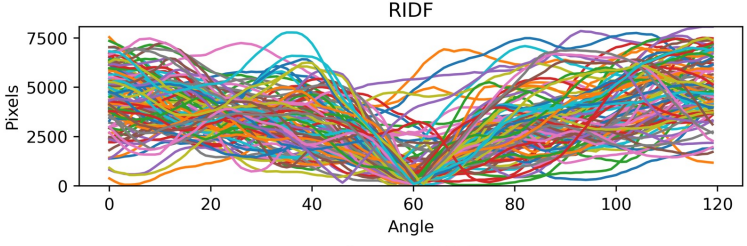
Navigation stats: RMSD error: 707.68; RMSD/dist: 1.769; TD: 2671; p90: 42; p50: 22; complete: 0

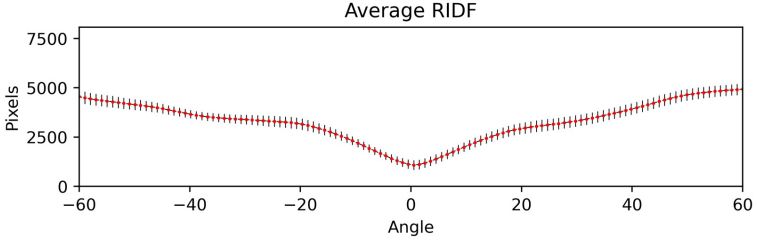
50%





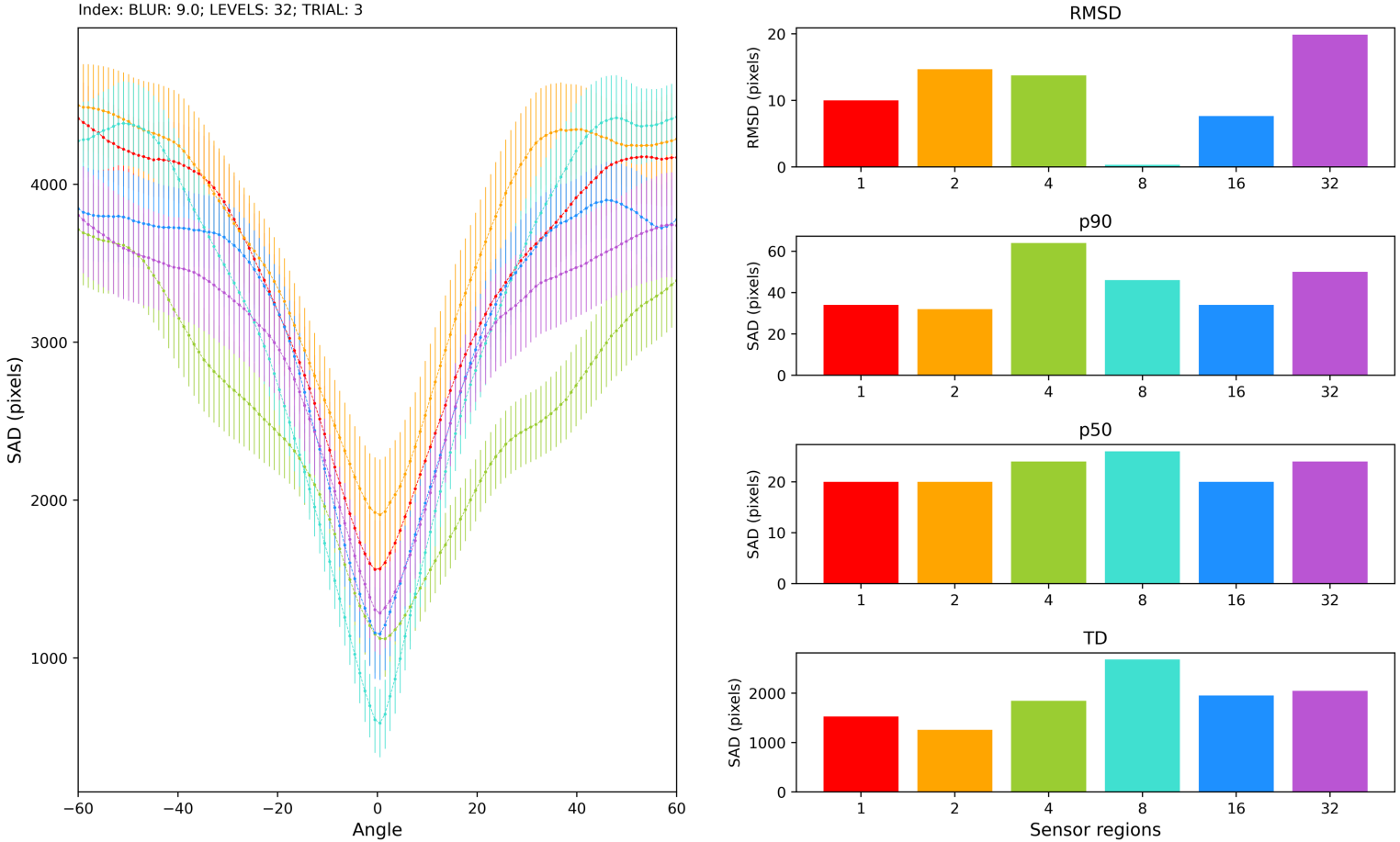




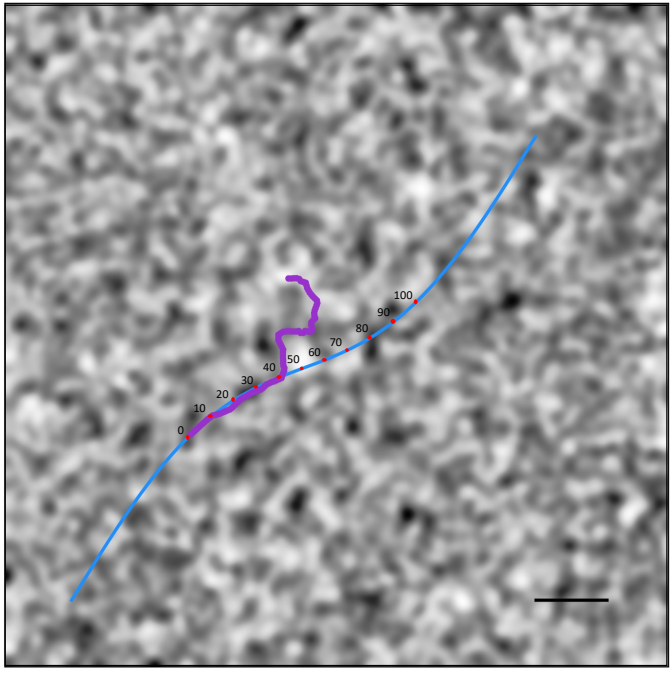


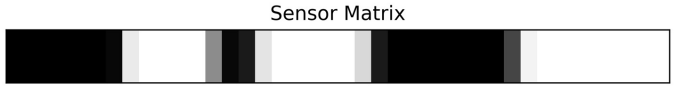
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

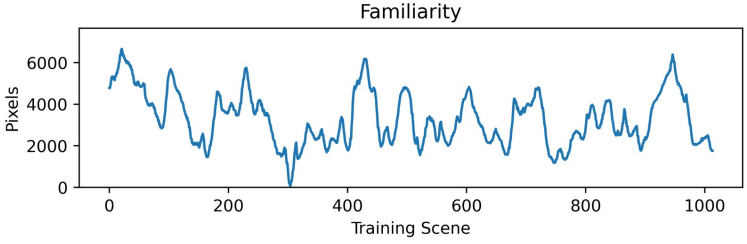
Navigation stats: RMSD error: 1507.27; RMSD/dist: 3.768; TD: 2106; p90: 34; p50: 20; complete: 0

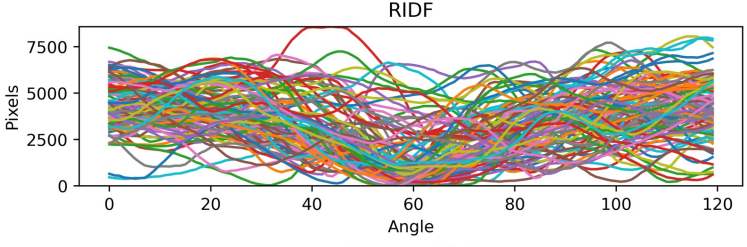

Index: BLUR: 9.0; LEVELS: 32; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

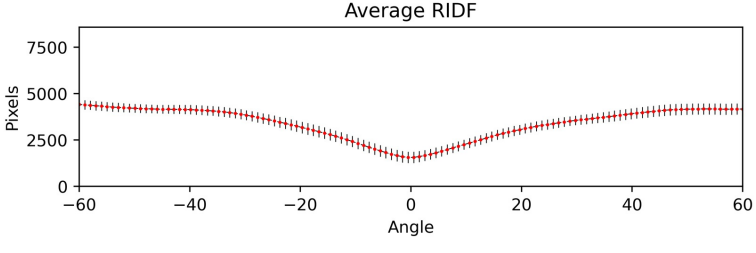
20%







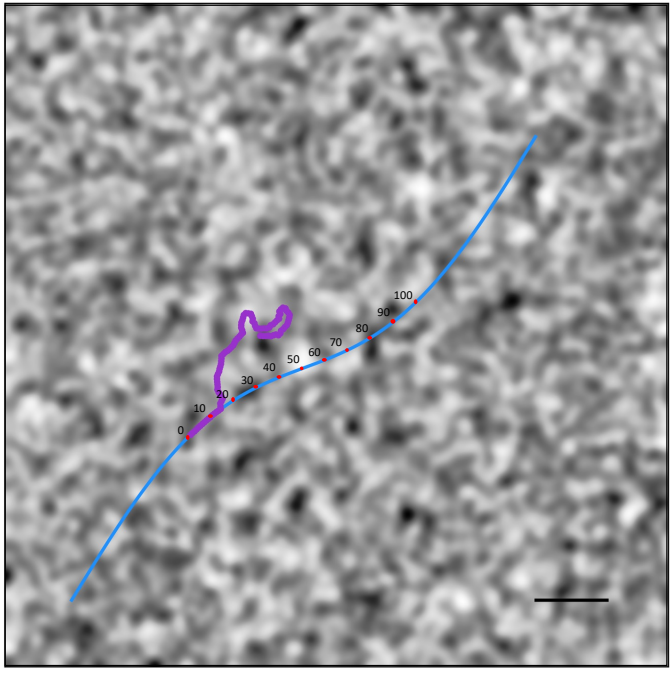


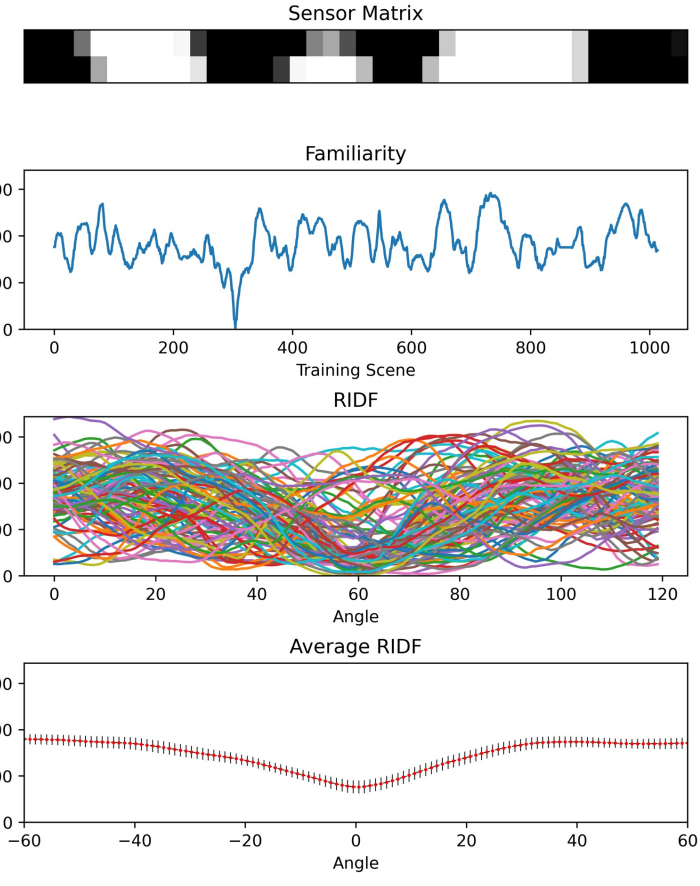


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 3995.43; RMSD/dist: 9.989; TD: 1529; p90: 34; p50: 20; complete: 0

10%

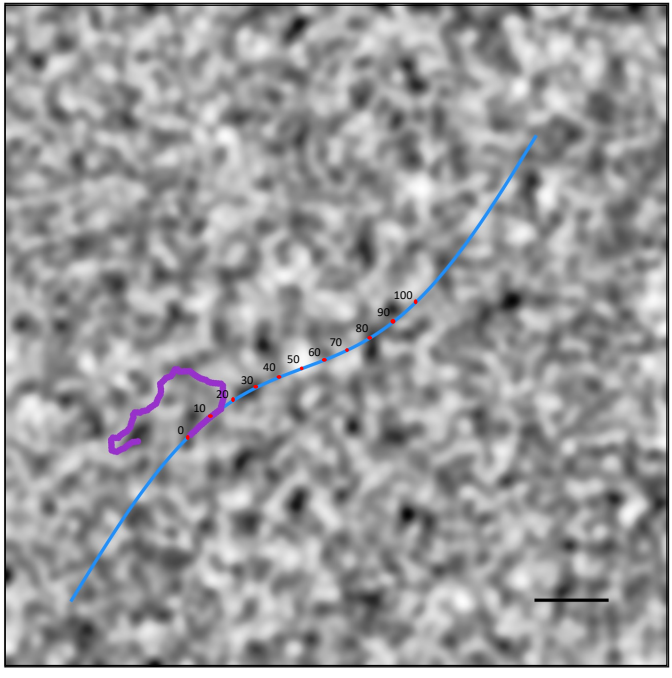


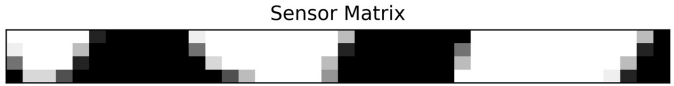


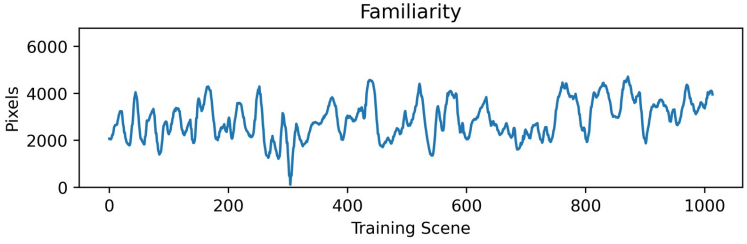
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

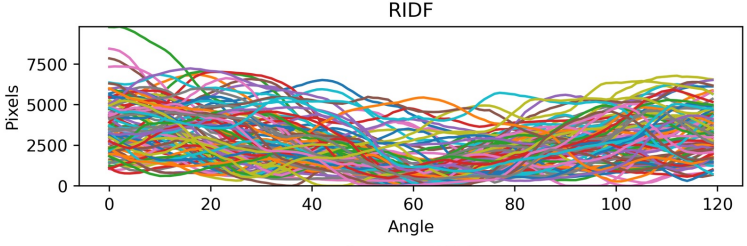
Navigation stats: RMSD error: 5881.51; RMSD/dist: 14.704; TD: 1258; p90: 32; p50: 20; complete: 0

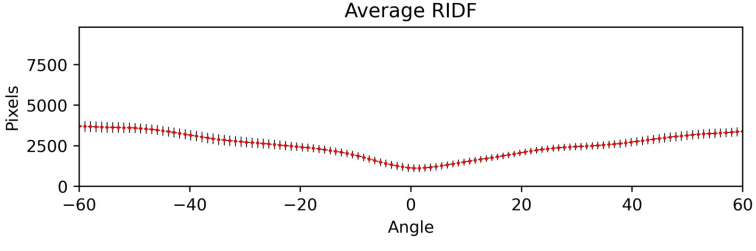
10%







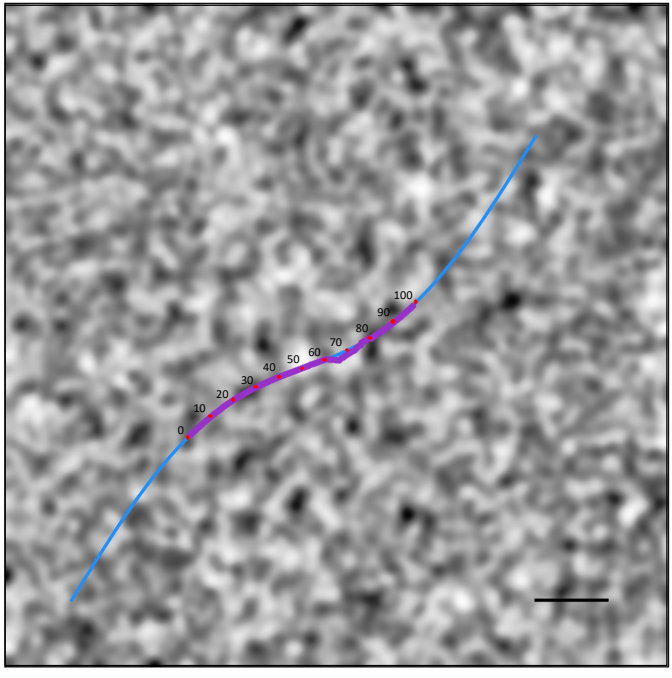


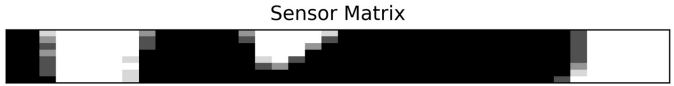


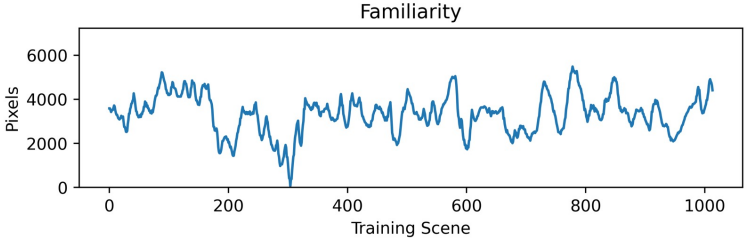
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

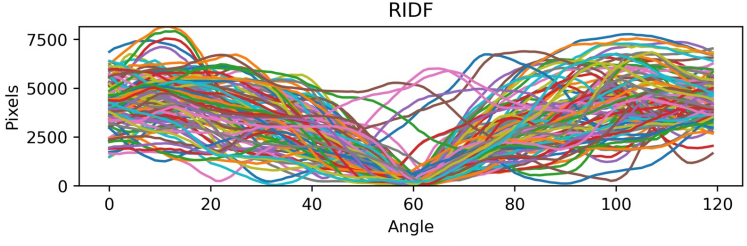
Navigation stats: RMSD error: 5506.81; RMSD/dist: 13.767; TD: 1845; p90: 64; p50: 24; complete: 0

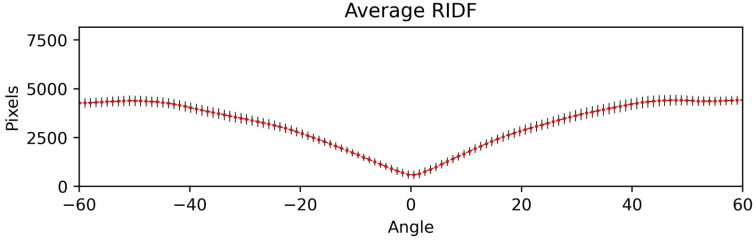
70%







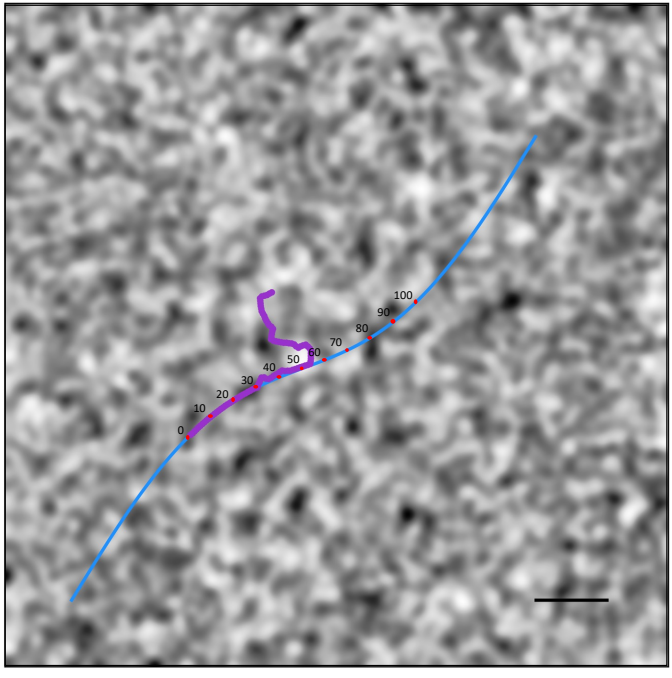


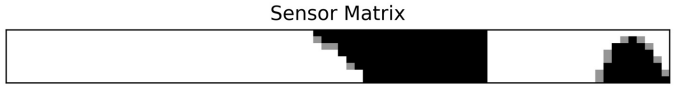


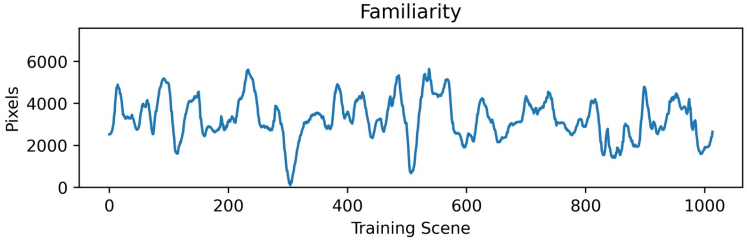
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

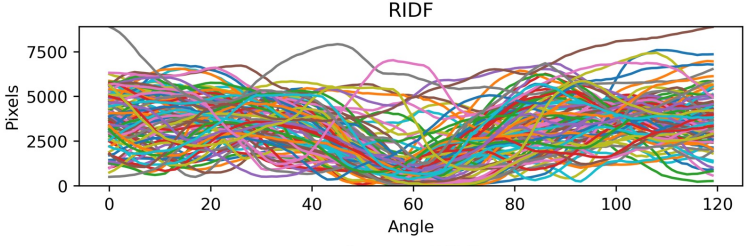
Navigation stats: RMSD error: 127.95; RMSD/dist: 0.320; TD: 2680; p90: 46; p50: 26; complete: 0

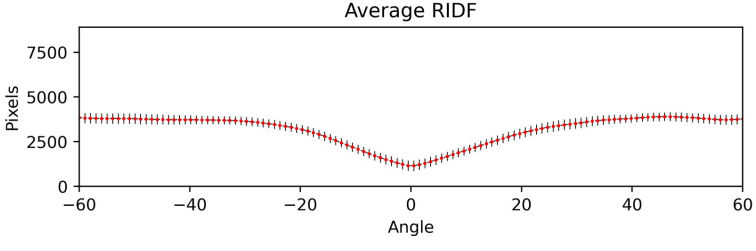
30%







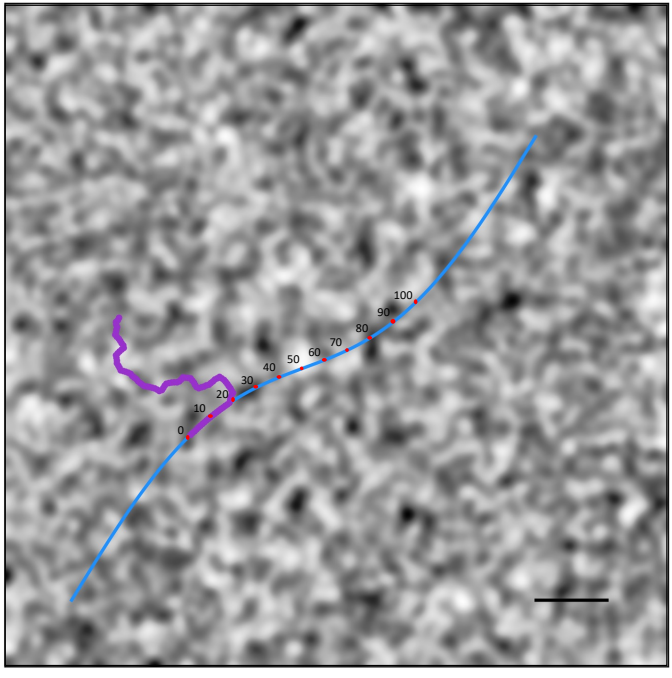


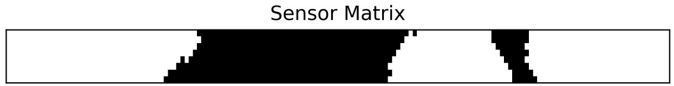


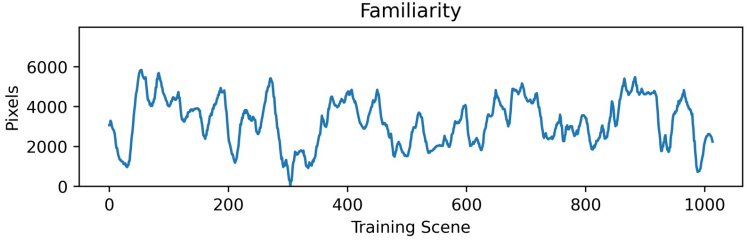
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

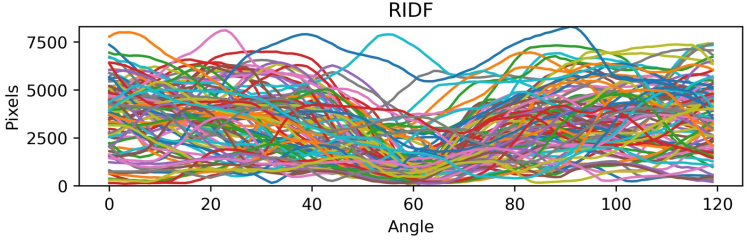
Navigation stats: RMSD error: 3050.83; RMSD/dist: 7.627; TD: 1952; p90: 34; p50: 20; complete: 0

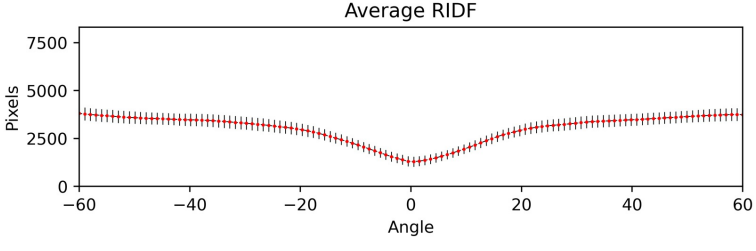
20%





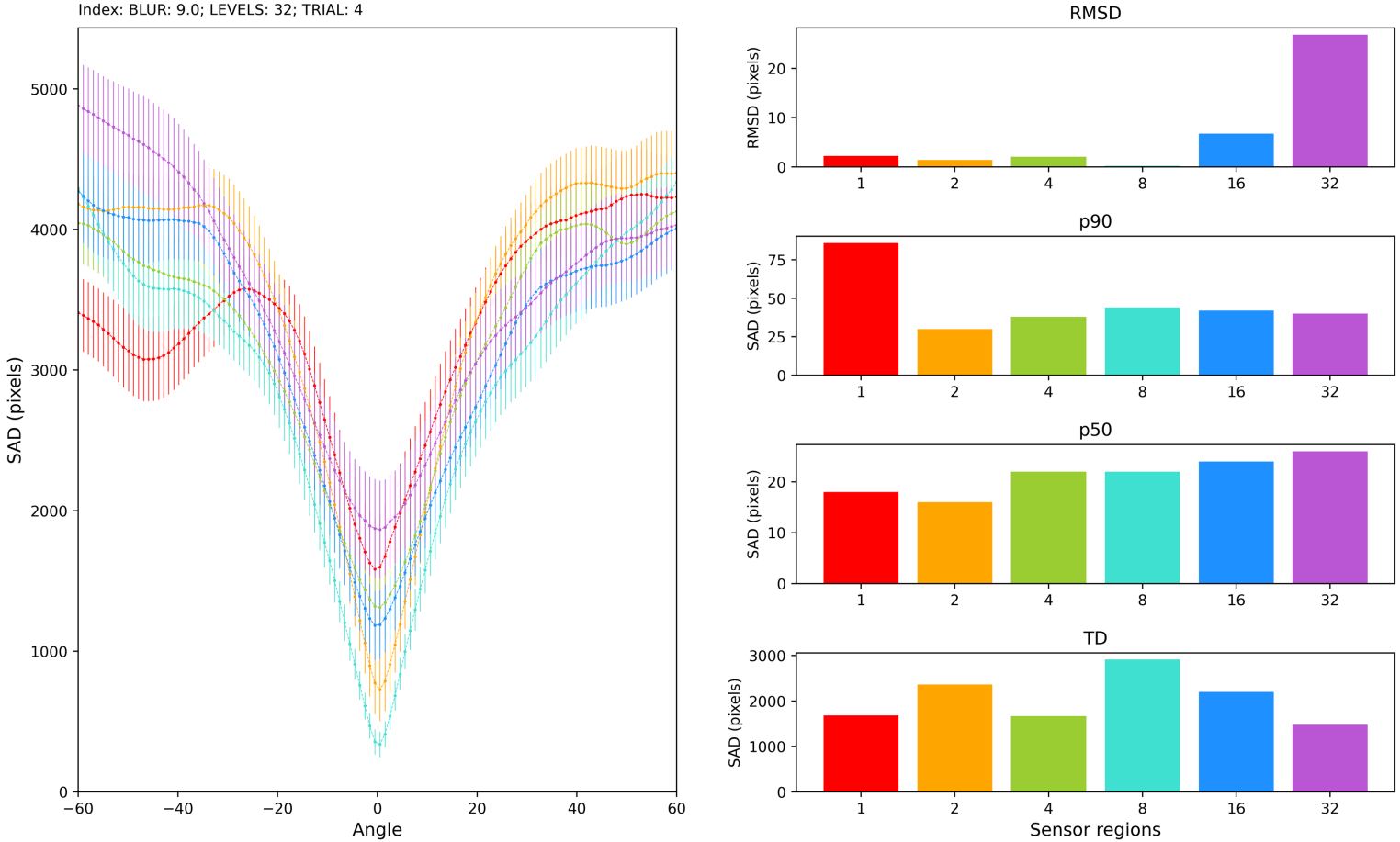




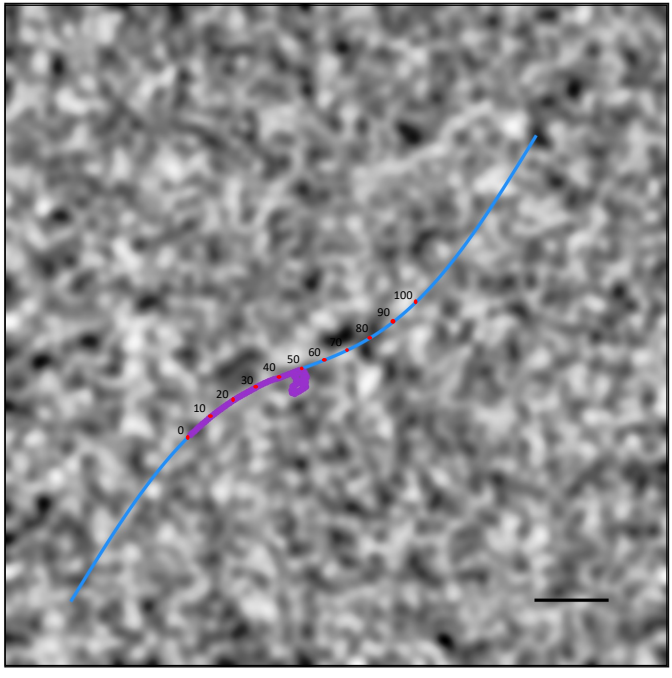


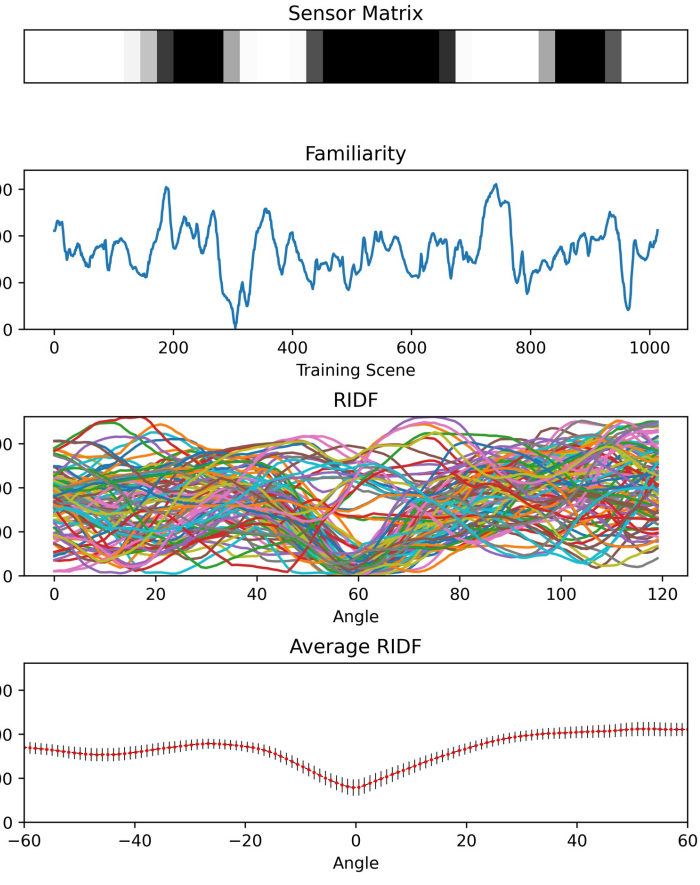
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 7960.34; RMSD/dist: 19.901; TD: 2046; p90: 50; p50: 24; complete: 0


Index: BLUR: 9.0; LEVELS: 32; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

50%

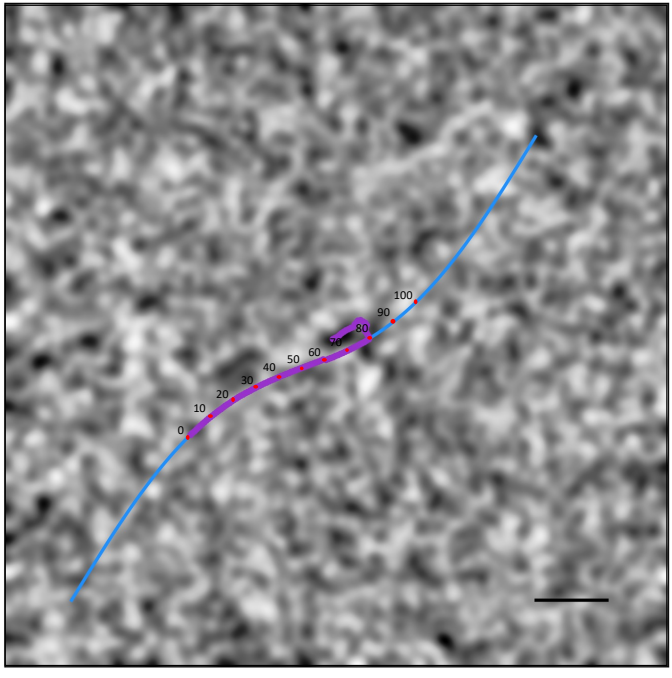


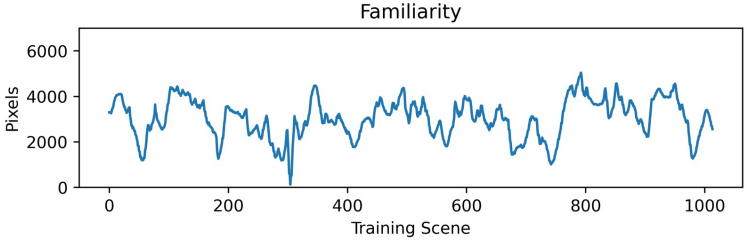


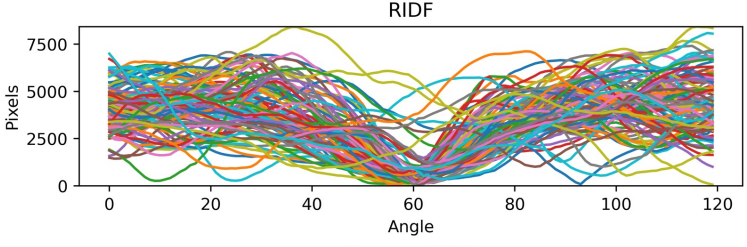
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

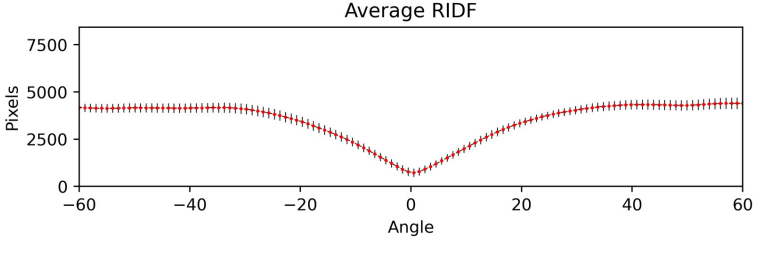
Navigation stats: RMSD error: 885.83; RMSD/dist: 2.215; TD: 1682; p90: 86; p50: 18; complete: 0

70%





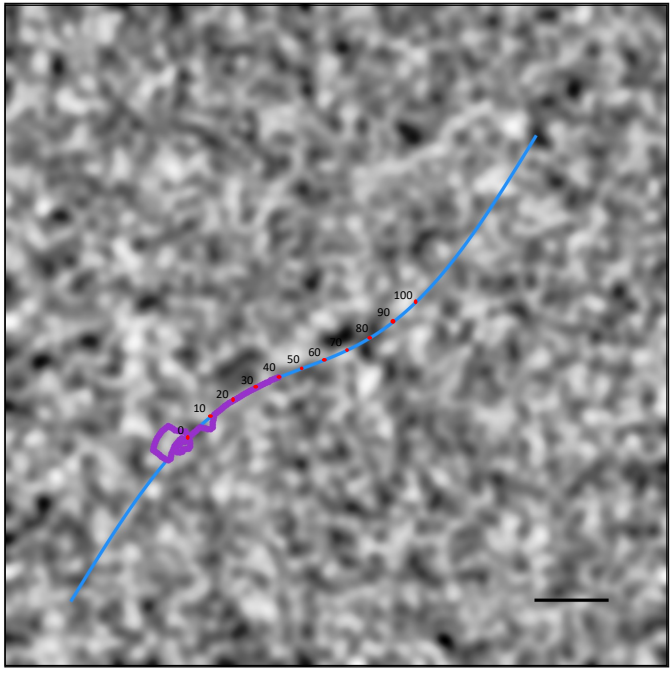


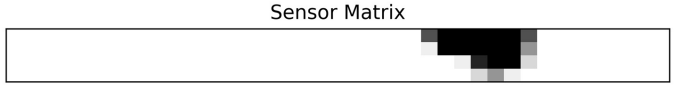


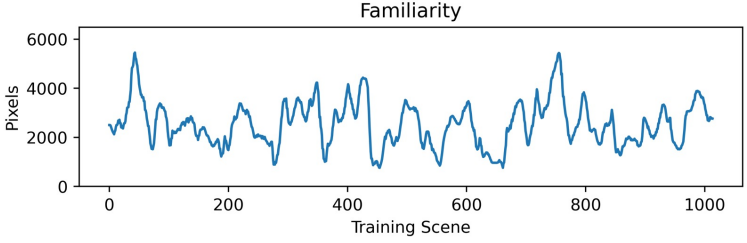
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

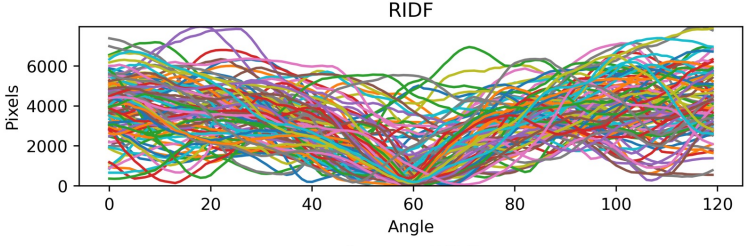
Navigation stats: RMSD error: 559.96; RMSD/dist: 1.400; TD: 2364; p90: 30; p50: 16; complete: 0

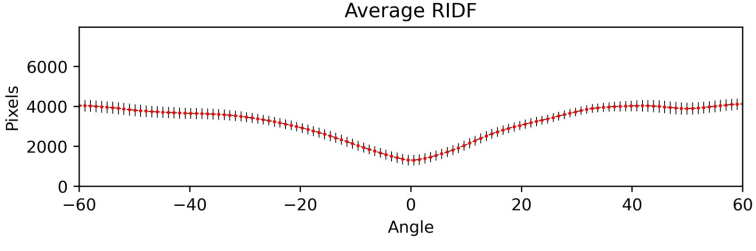
30%







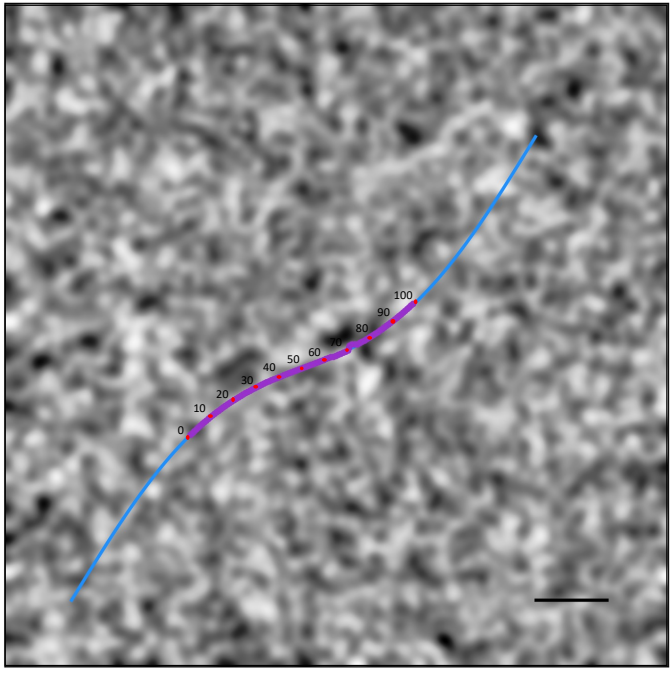


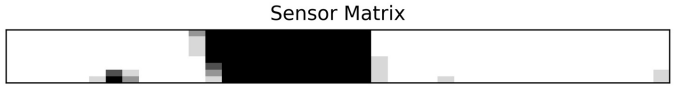


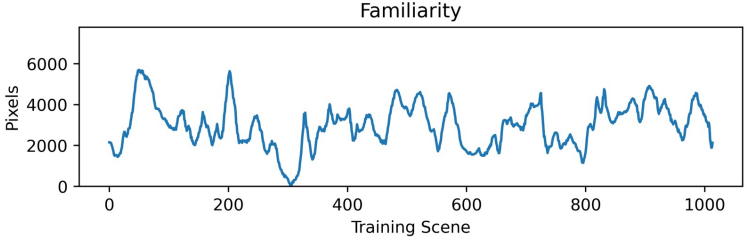
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

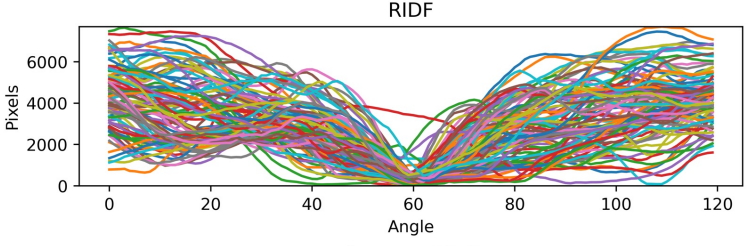
Navigation stats: RMSD error: 824.65; RMSD/dist: 2.062; TD: 1667; p90: 38; p50: 22; complete: 0

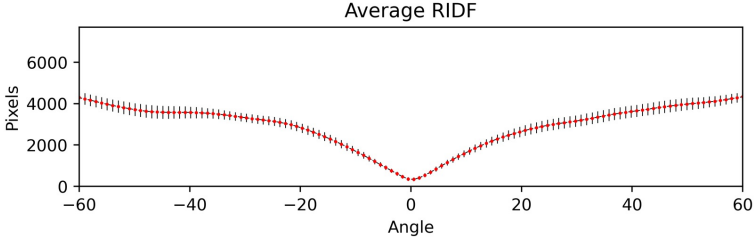
90%







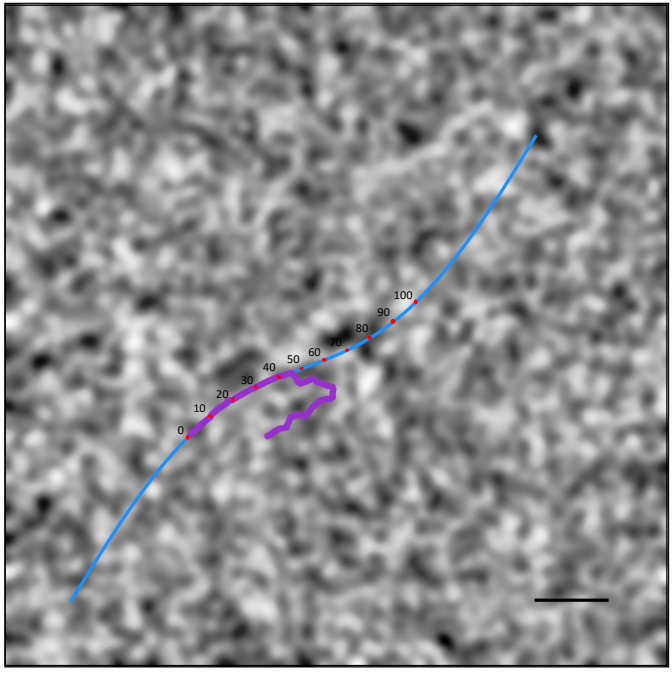


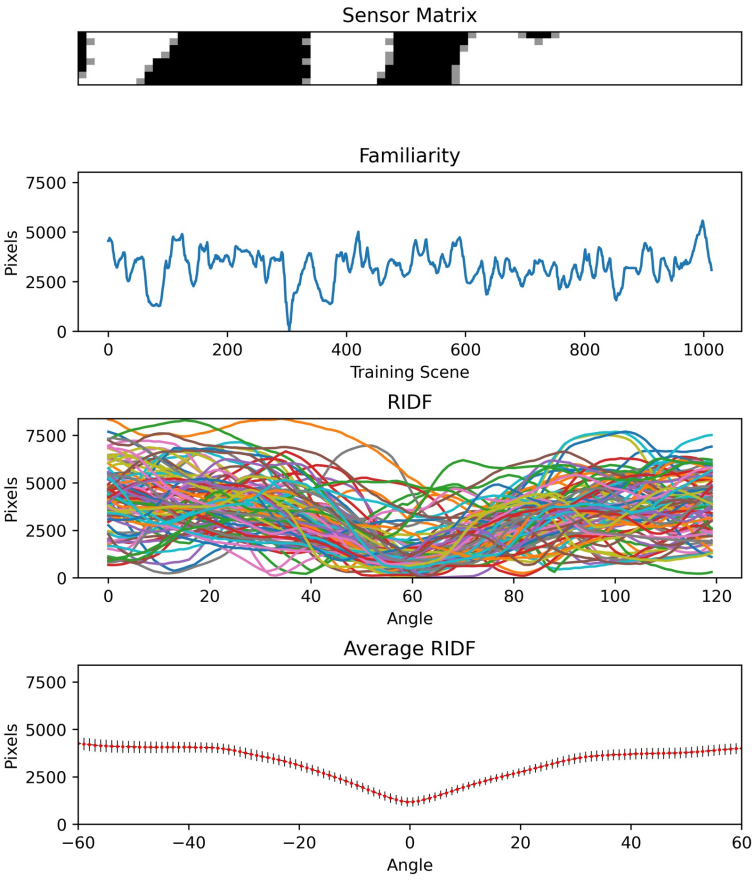


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 85.48; RMSD/dist: 0.214; TD: 2911; p90: 44; p50: 22; complete: 0

40%

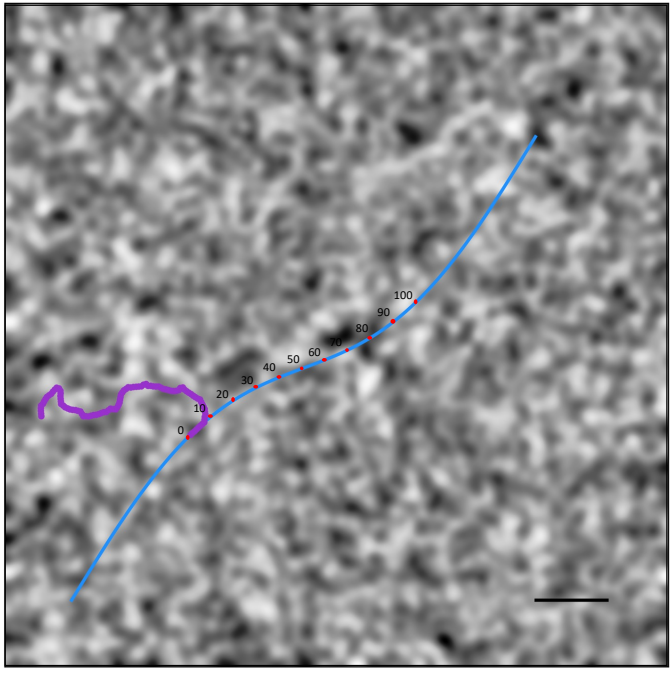


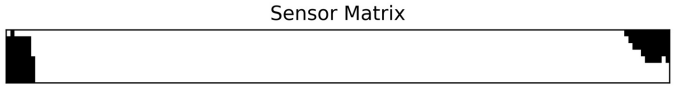


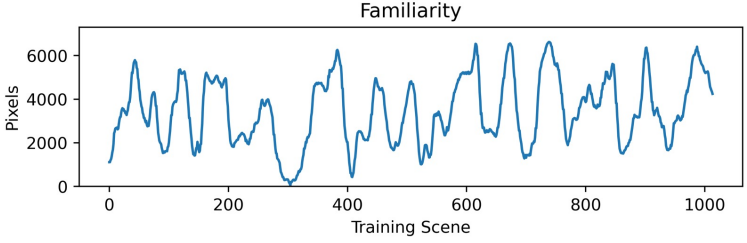
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

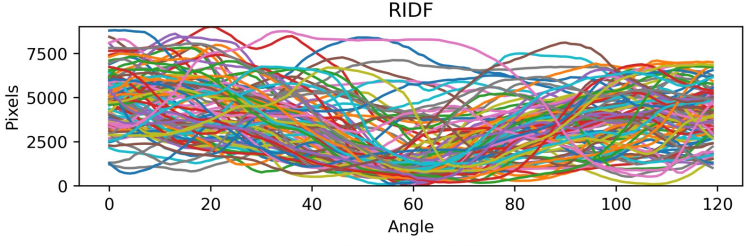
Navigation stats: RMSD error: 2701.44; RMSD/dist: 6.754; TD: 2200; p90: 42; p50: 24; complete: 0

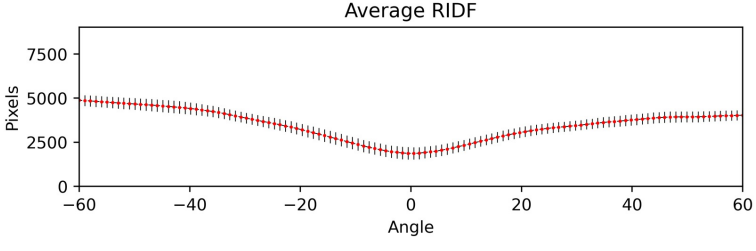
0%





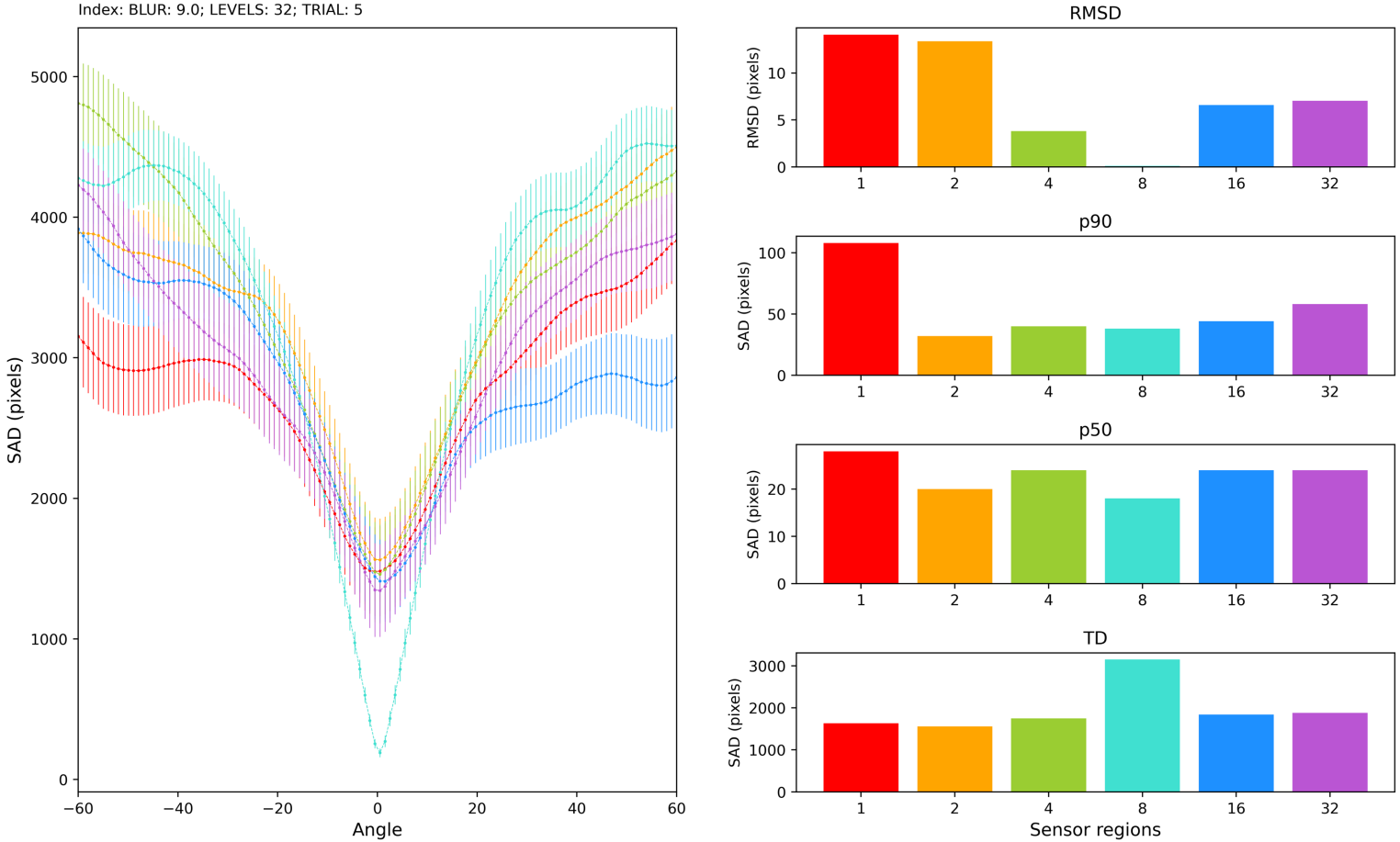




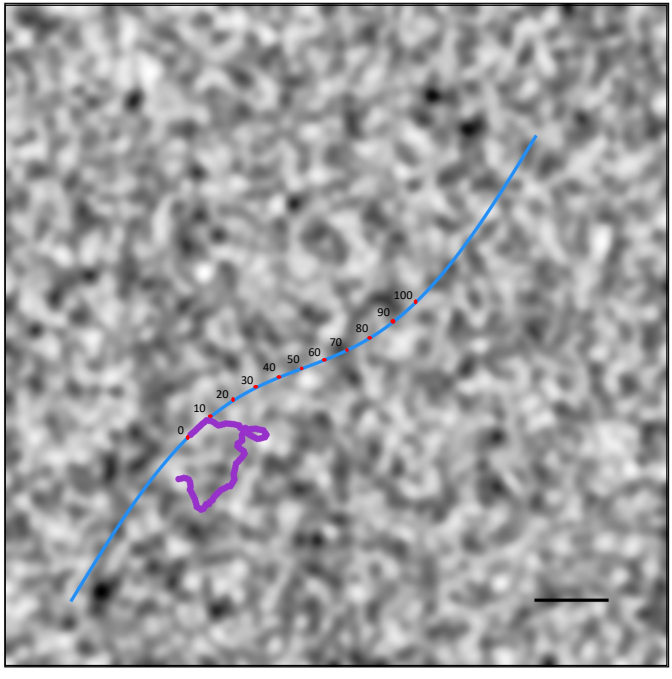


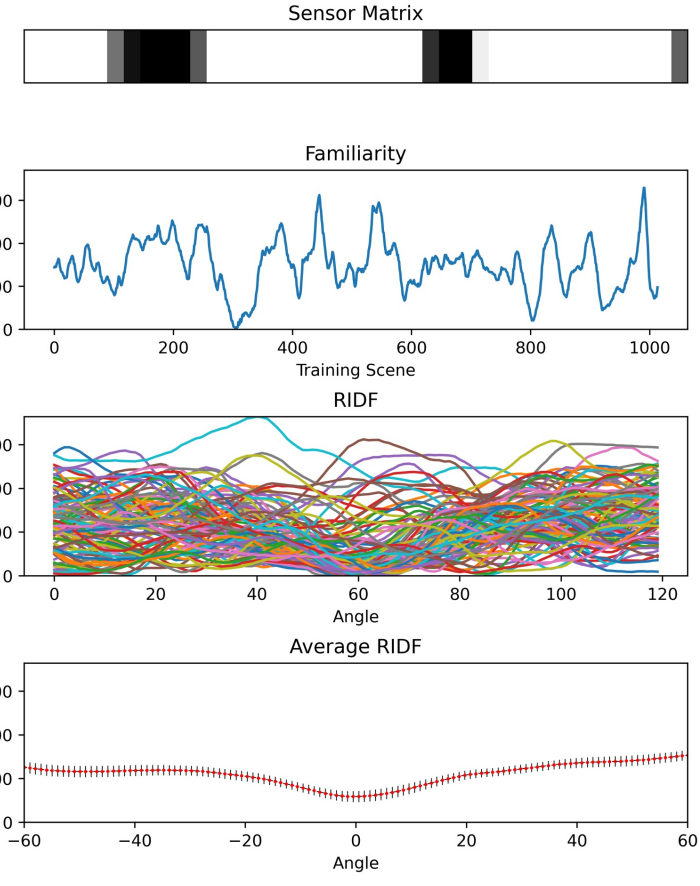
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 10742.70; RMSD/dist: 26.857; TD: 1479; p90: 40; p50: 26; complete: 0


Index: BLUR: 9.0; LEVELS: 32; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

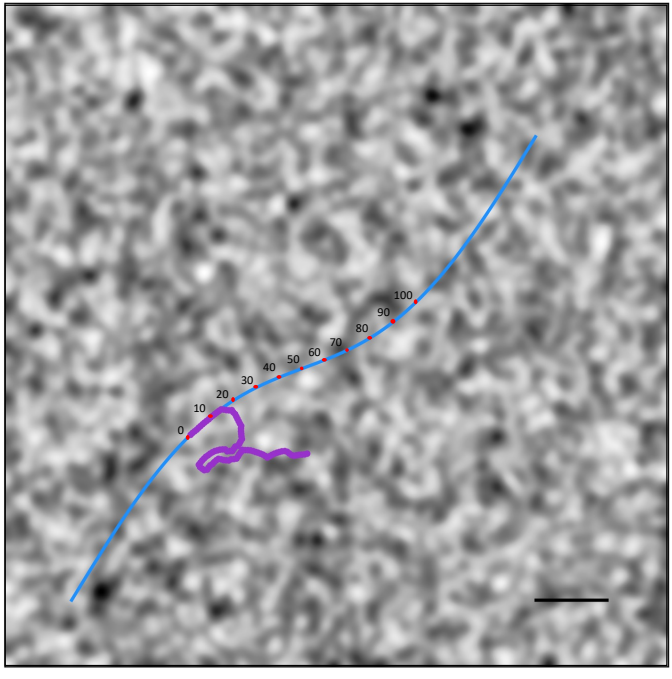


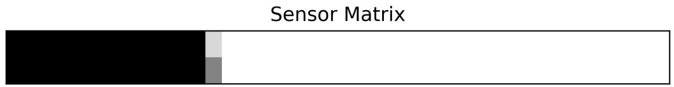


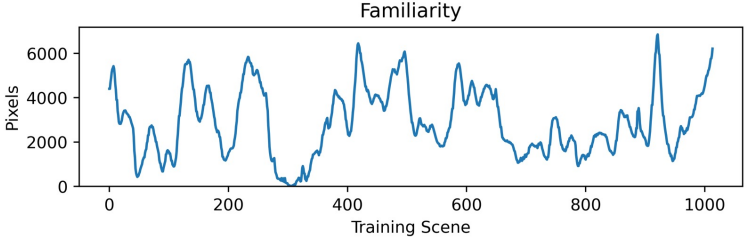
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

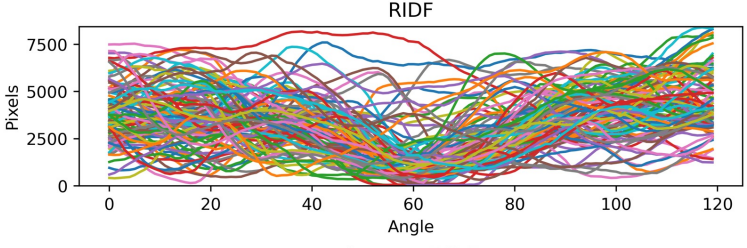
Navigation stats: RMSD error: 5634.28; RMSD/dist: 14.086; TD: 1631; p90: 108; p50: 28; complete: 0

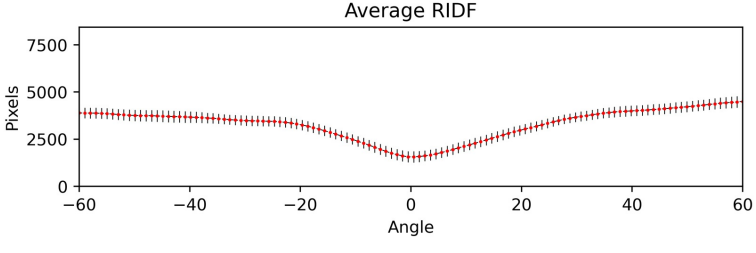
10%







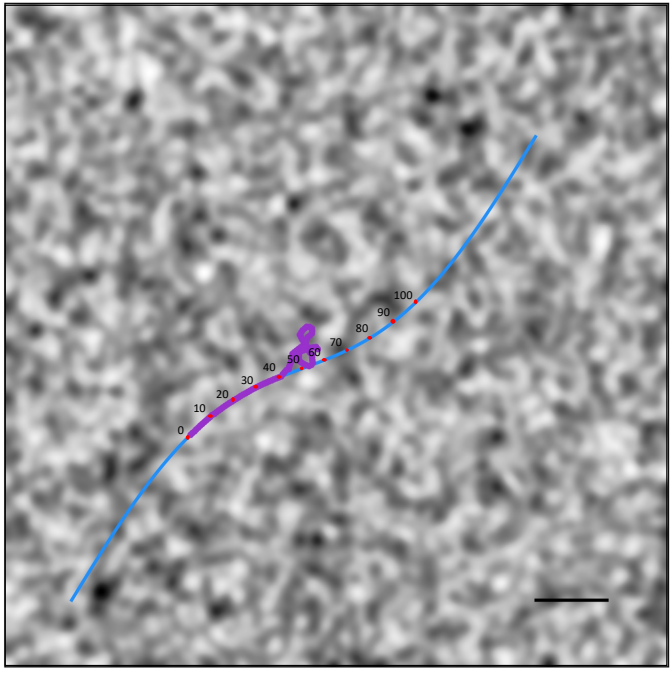


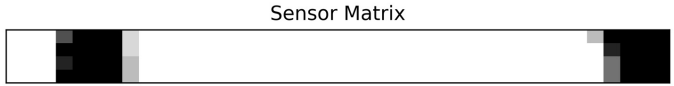


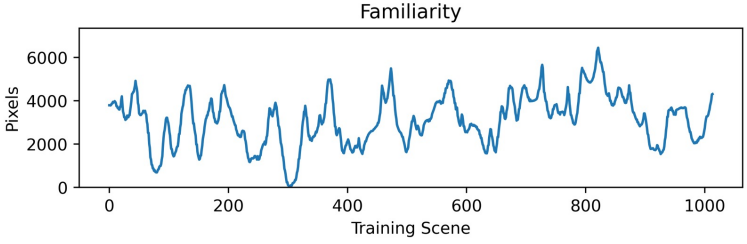
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

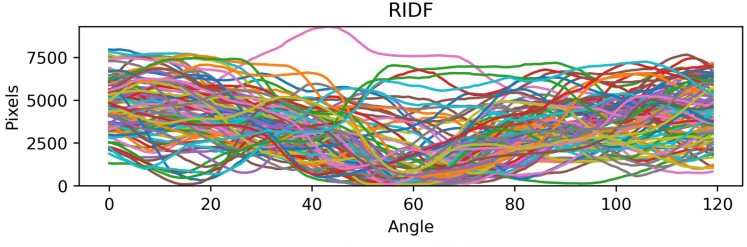
Navigation stats: RMSD error: 5352.02; RMSD/dist: 13.380; TD: 1559; p90: 32; p50: 20; complete: 0

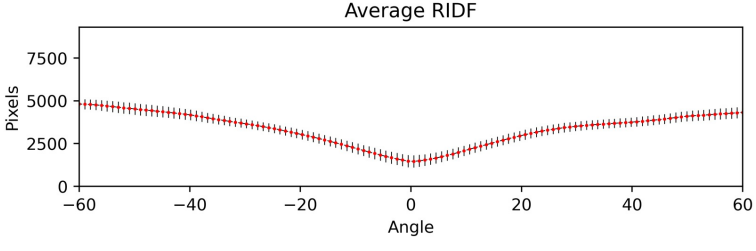
40%







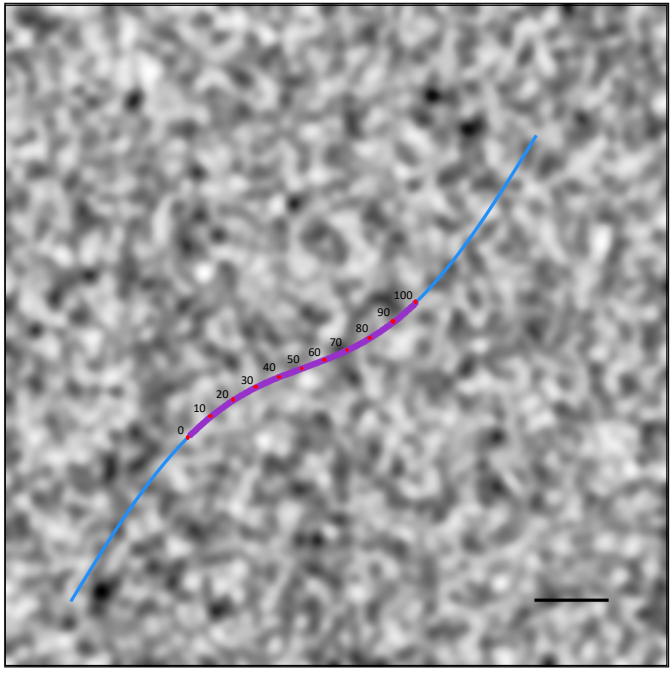


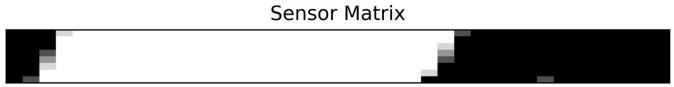


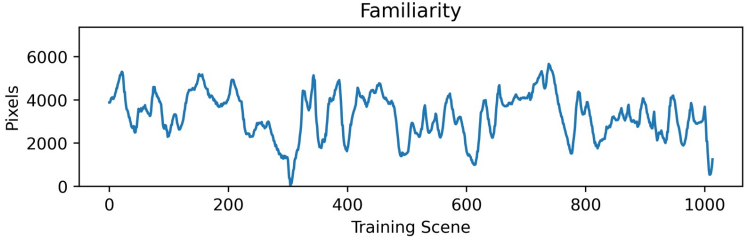
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

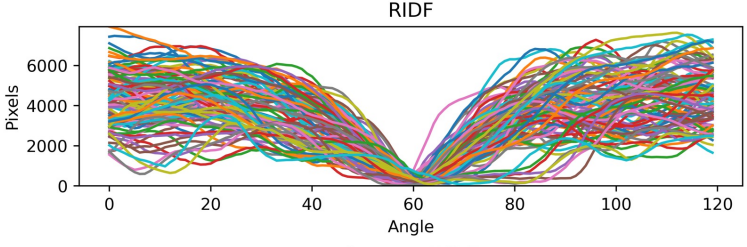
Navigation stats: RMSD error: 1521.96; RMSD/dist: 3.805; TD: 1746; p90: 40; p50: 24; complete: 0

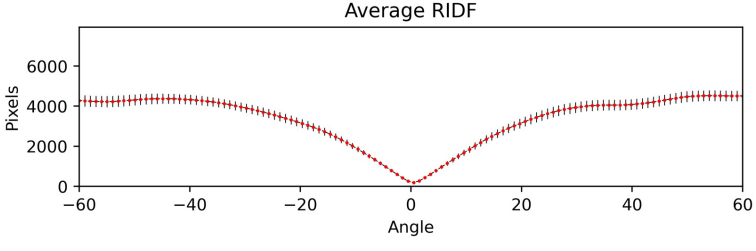
100%







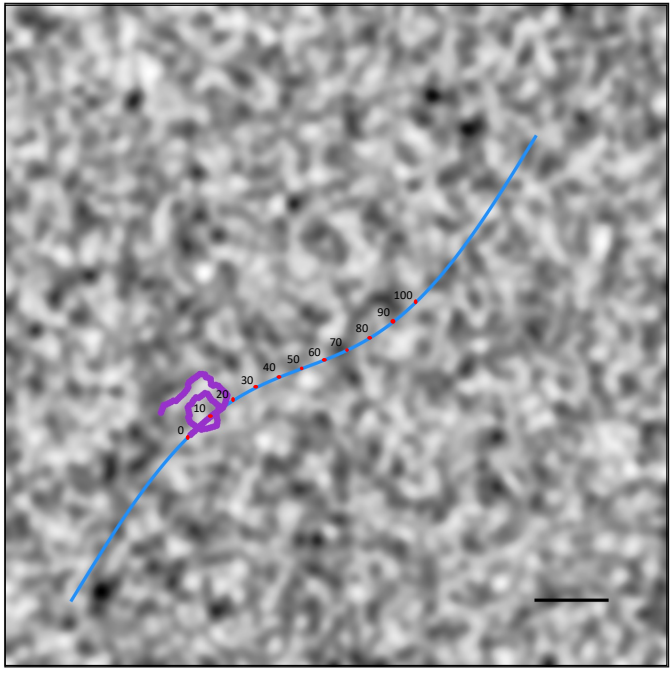


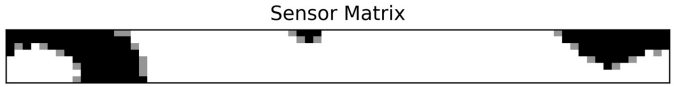


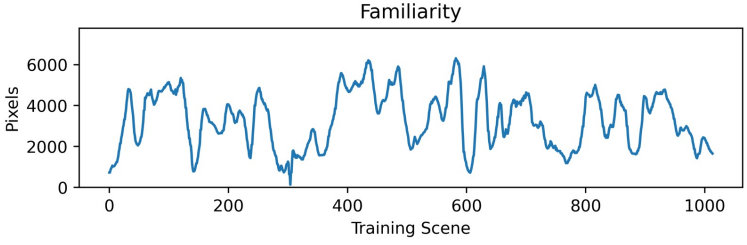
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

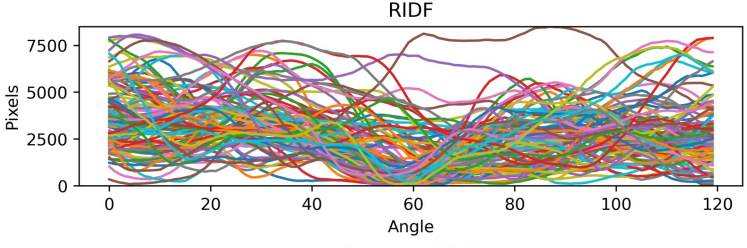
Navigation stats: RMSD error: 39.53; RMSD/dist: 0.099; TD: 3148; p90: 38; p50: 18; complete: 0

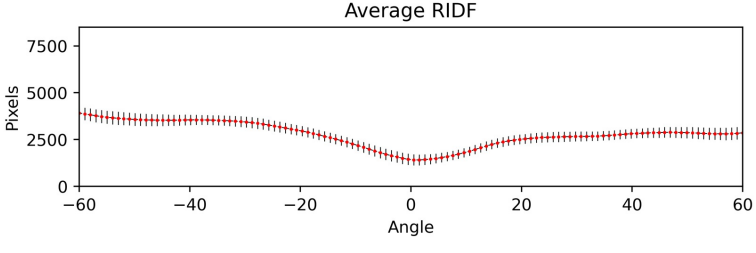
10%







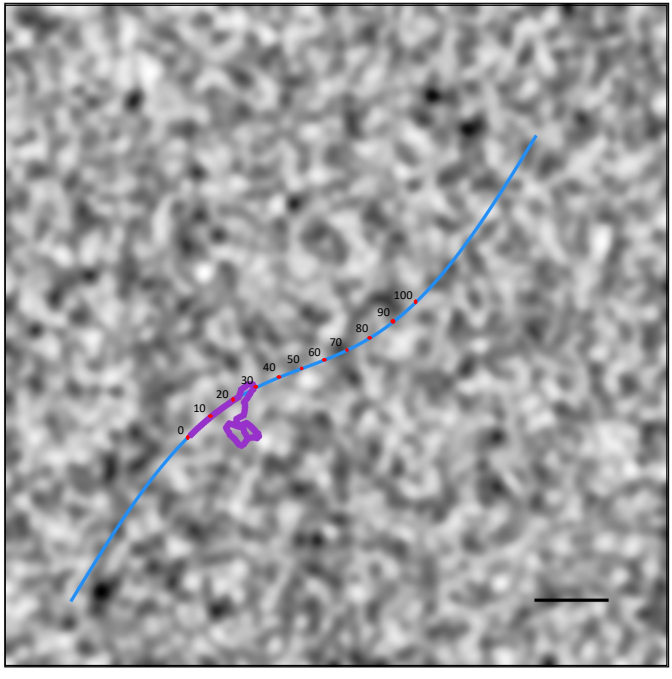


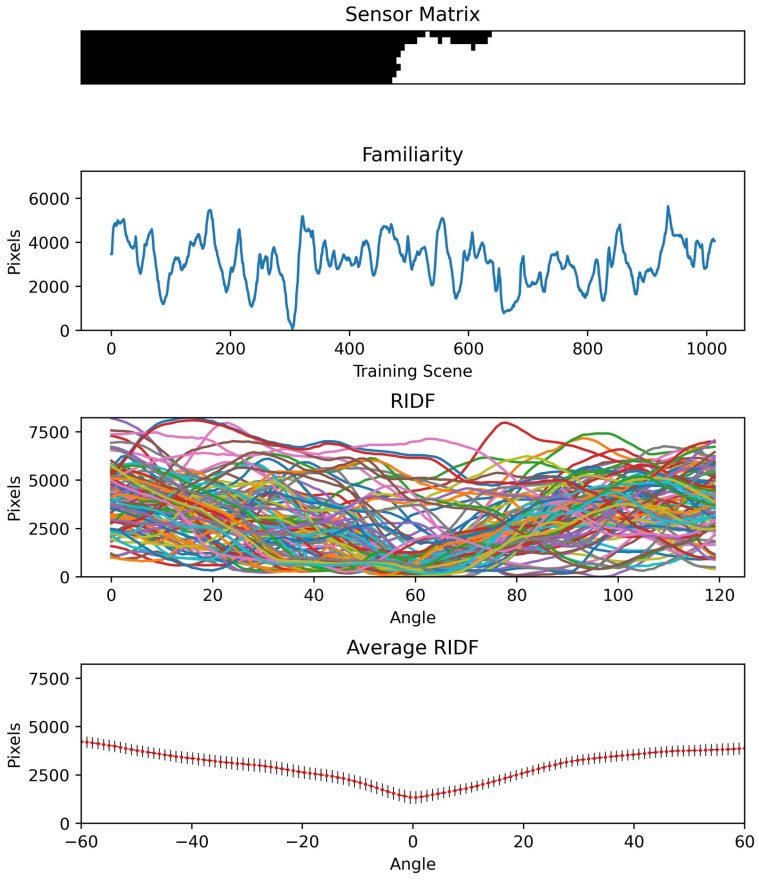


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 2630.57; RMSD/dist: 6.576; TD: 1838; p90: 44; p50: 24; complete: 0

20%





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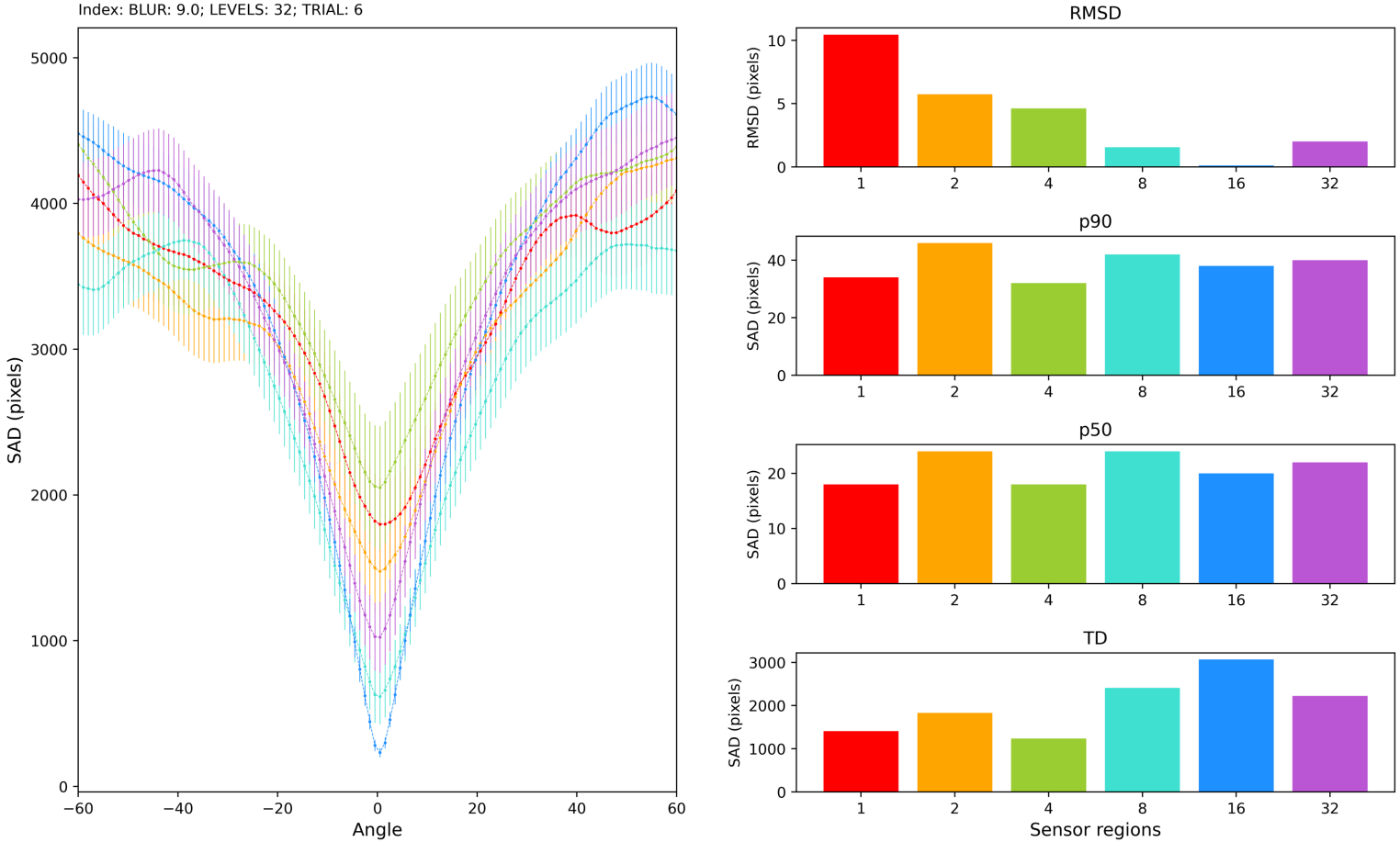
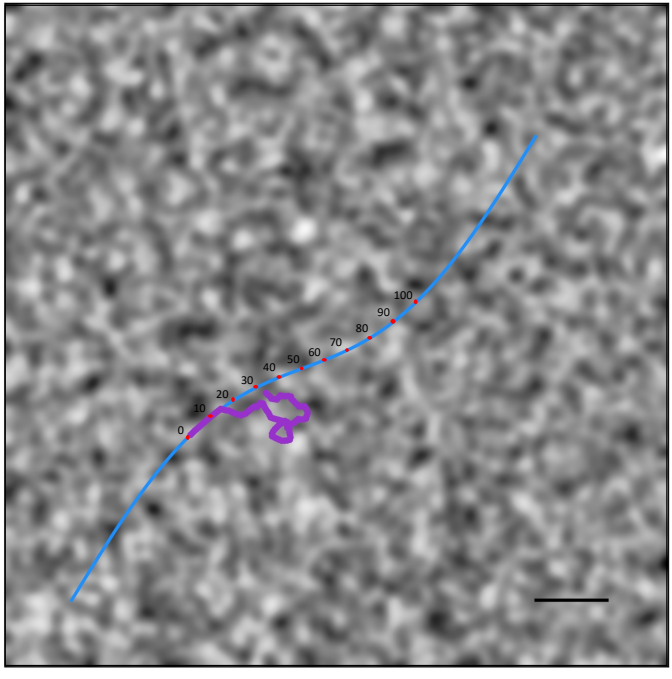
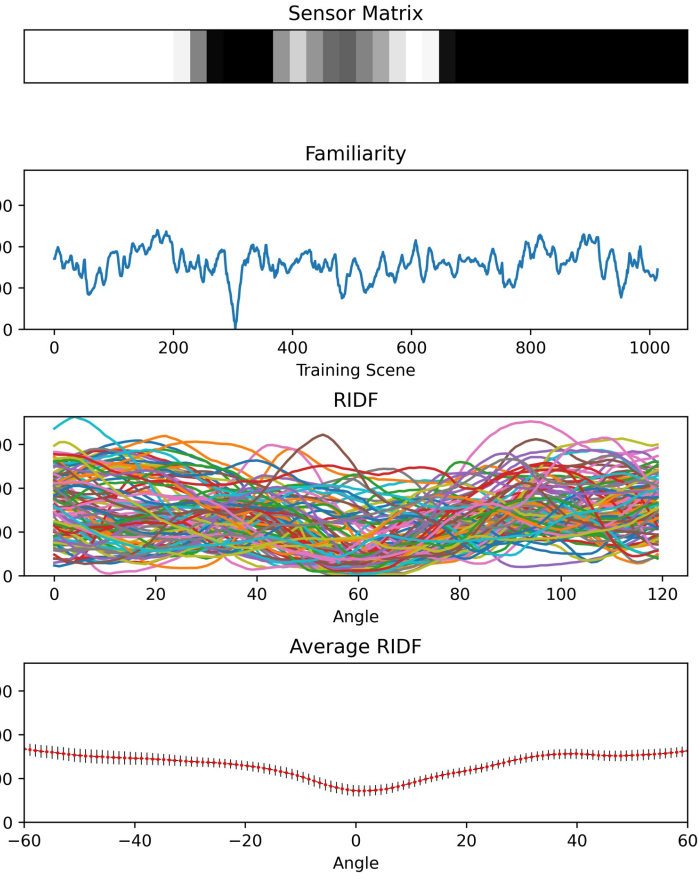
Navigation stats: RMSD error: 2810.20; RMSD/dist: 7.026; TD: 1878; p90: 58; p50: 24; complete: 0


Index: BLUR: 9.0; LEVELS: 32; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

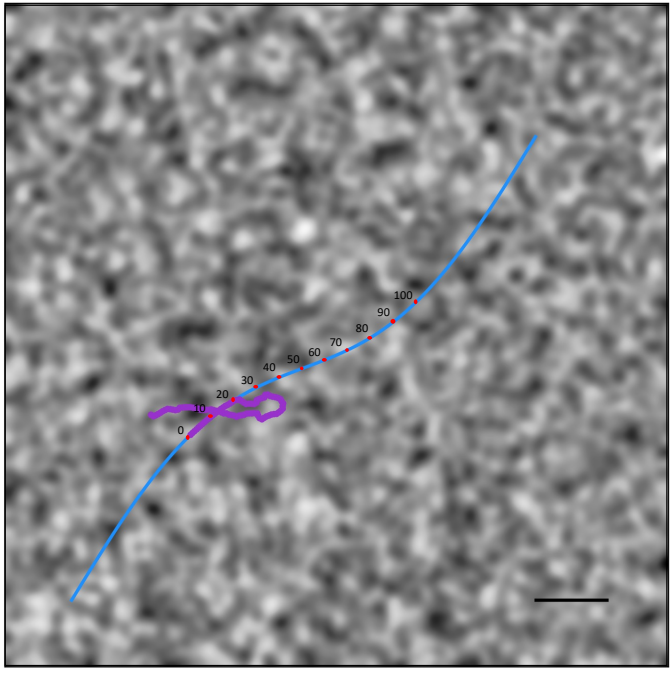


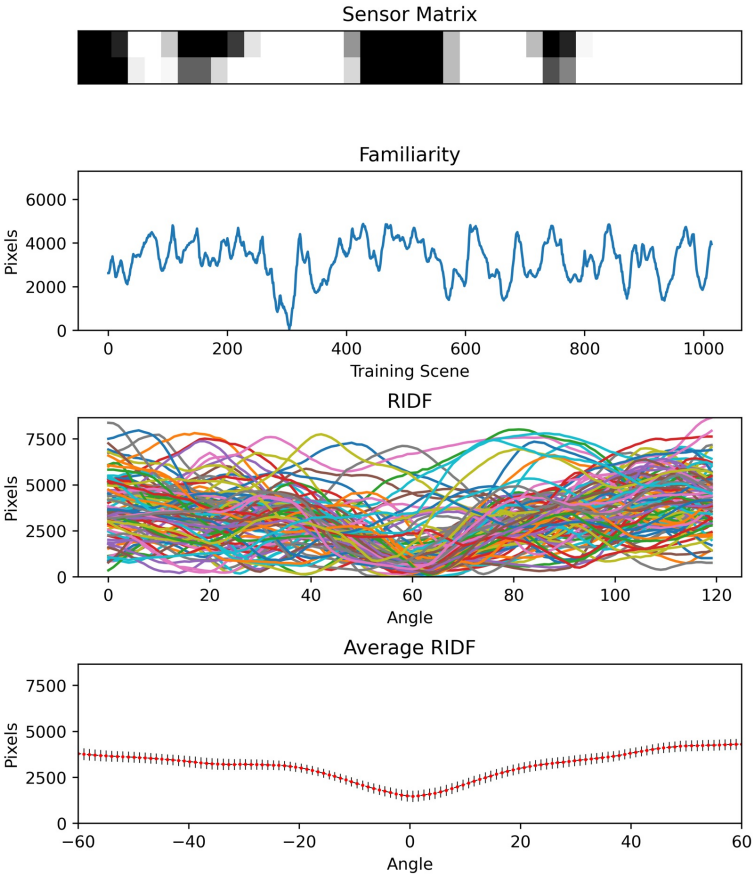


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4184.03; RMSD/dist: 10.460; TD: 1409; p90: 34; p50: 18; complete: 0

20%

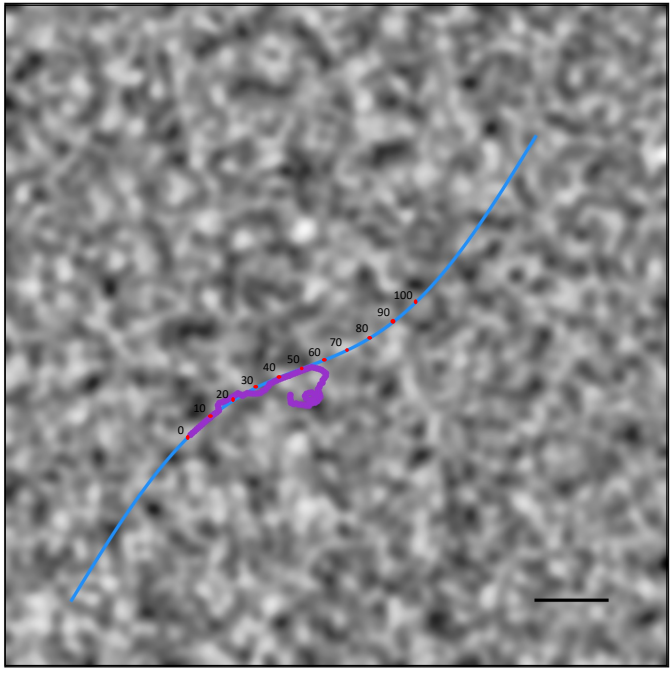


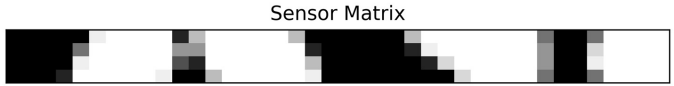


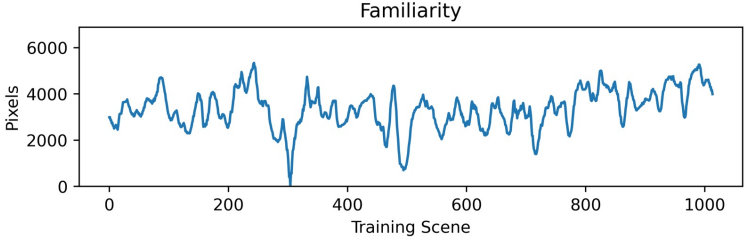
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

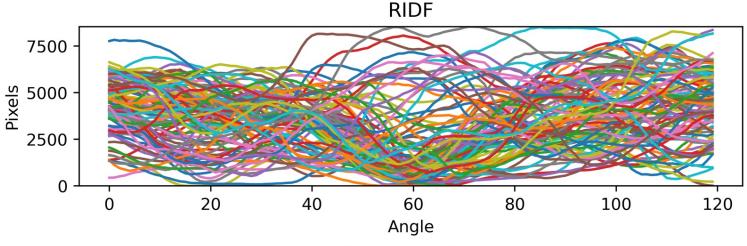
Navigation stats: RMSD error: 2294.80; RMSD/dist: 5.737; TD: 1832; p90: 46; p50: 24; complete: 0

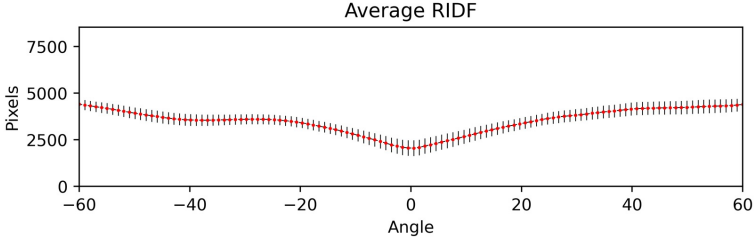
20%







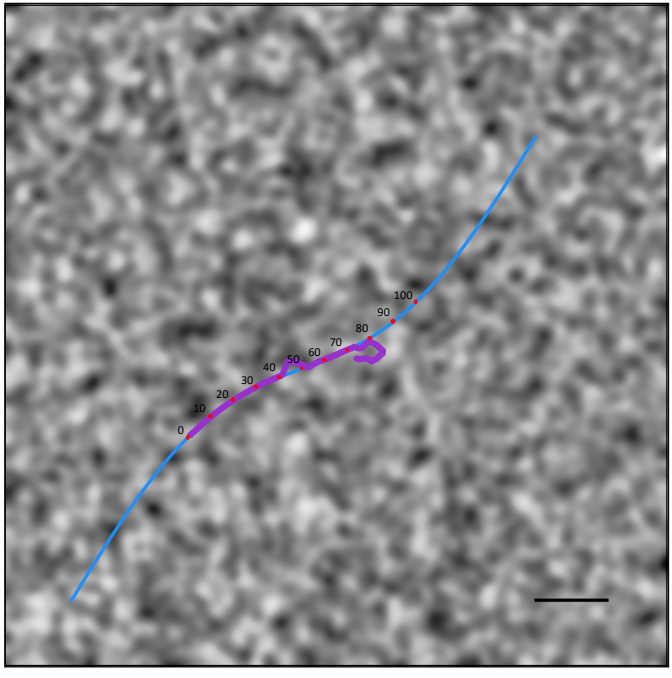


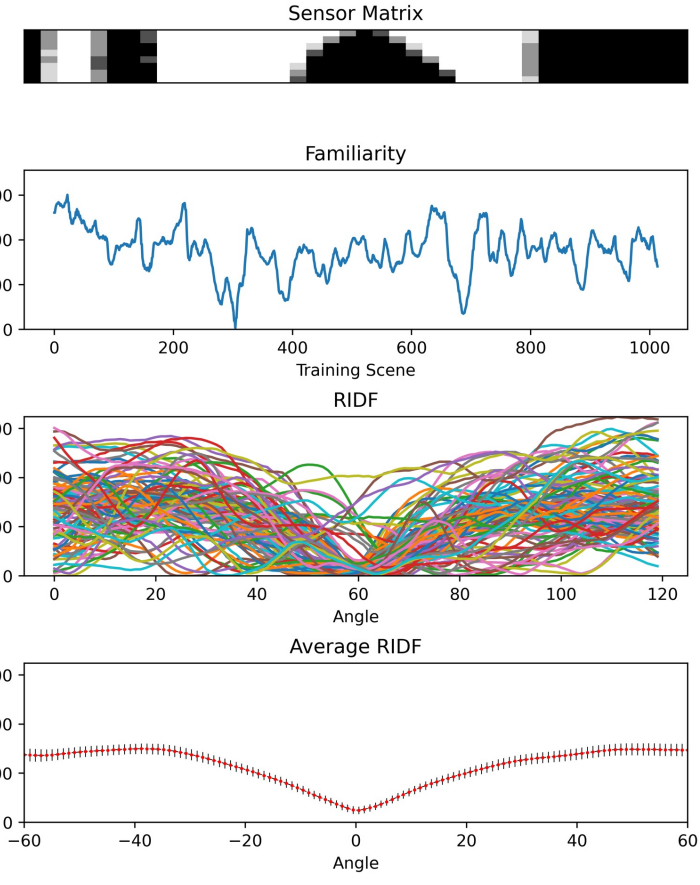


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1850.07; RMSD/dist: 4.625; TD: 1236; p90: 32; p50: 18; complete: 0

50%

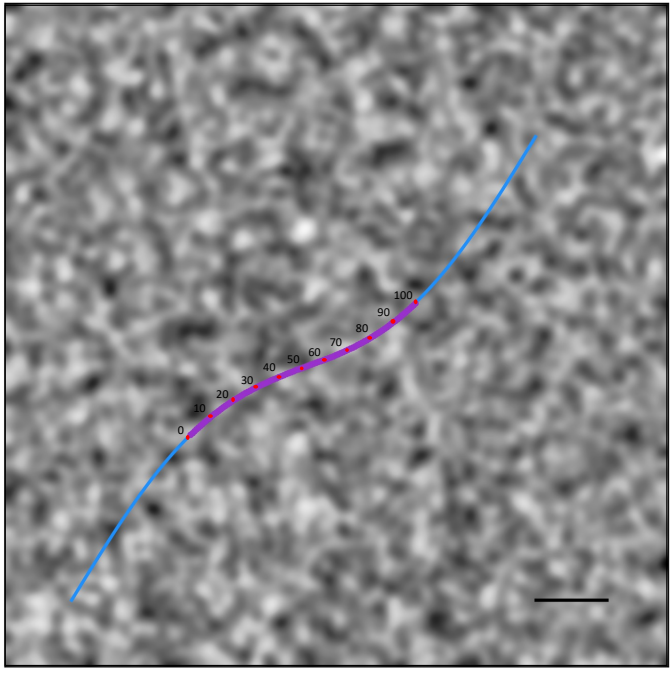


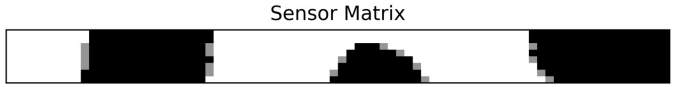


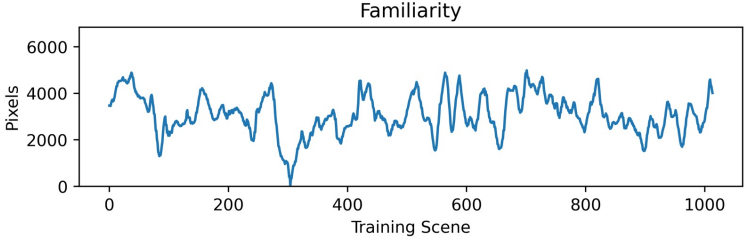
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

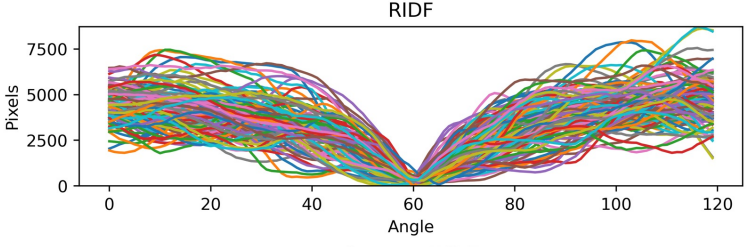
Navigation stats: RMSD error: 622.83; RMSD/dist: 1.557; TD: 2412; p90: 42; p50: 24; complete: 0

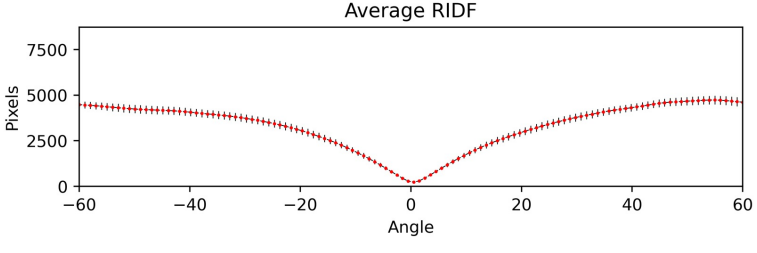
100%







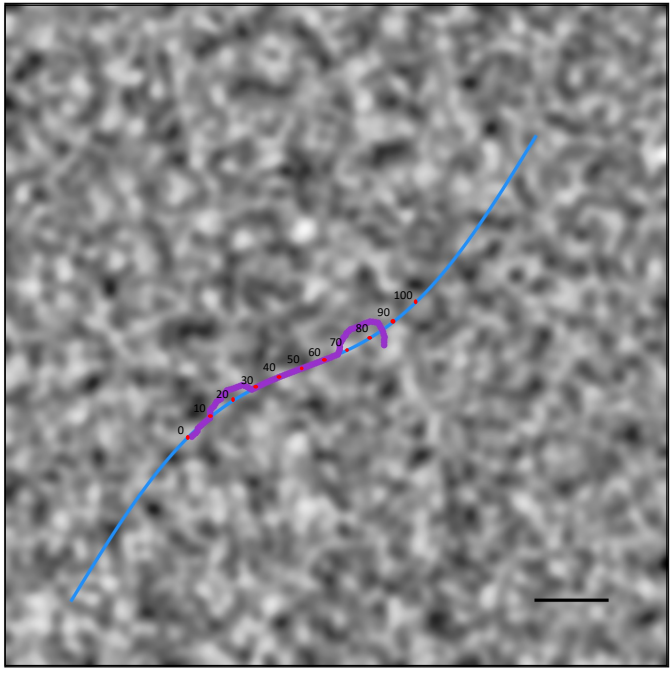


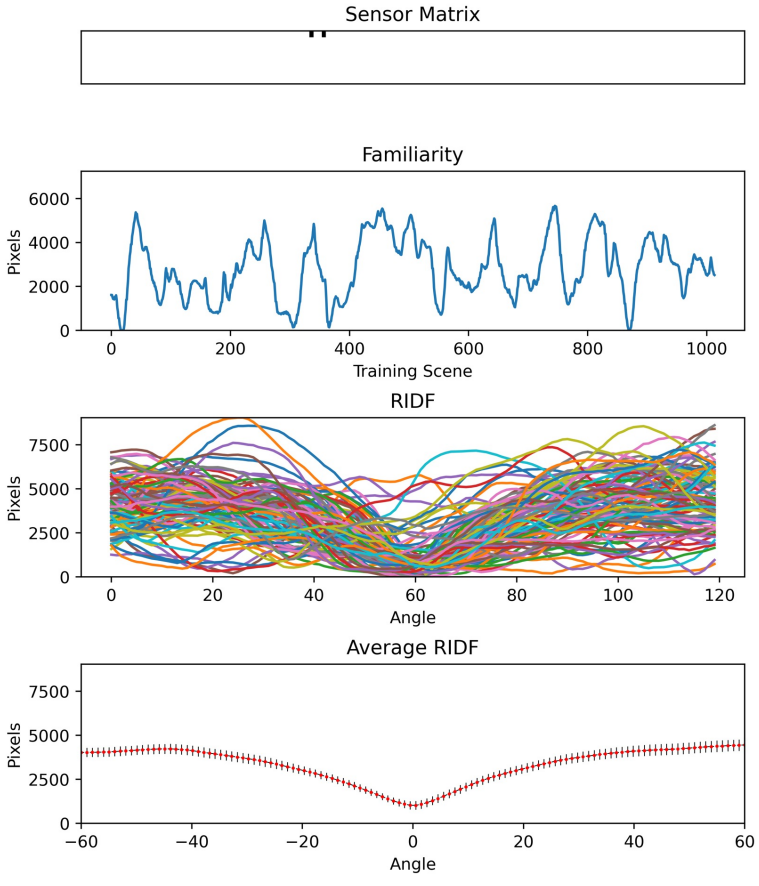


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 43.34; RMSD/dist: 0.108; TD: 3066; p90: 38; p50: 20; complete: 0

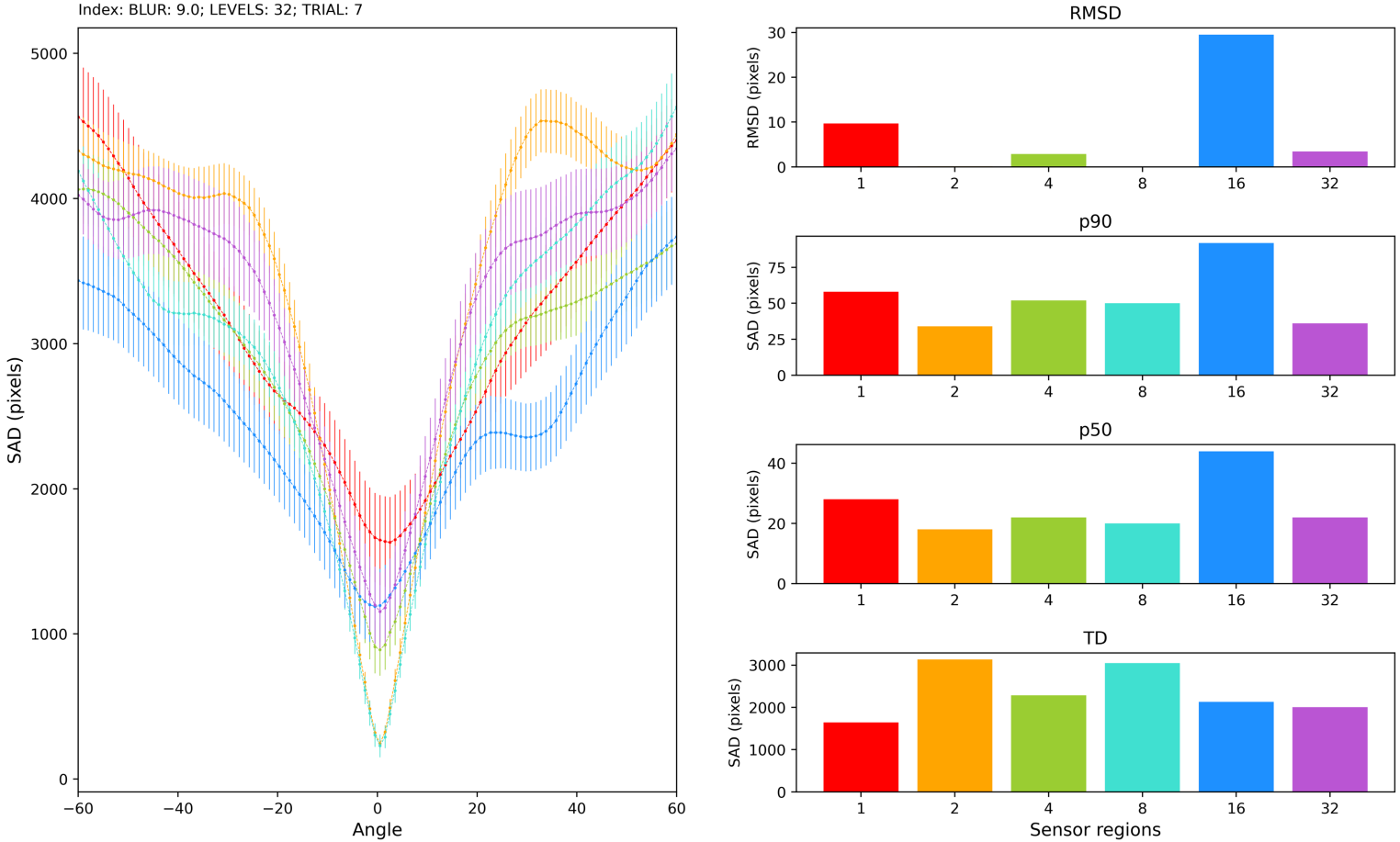
40%



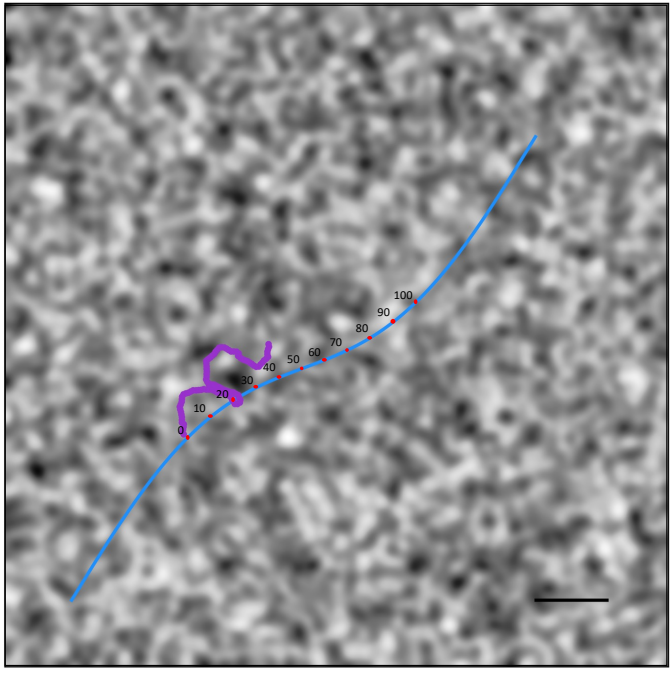


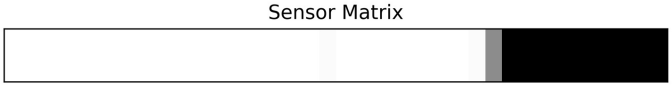
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

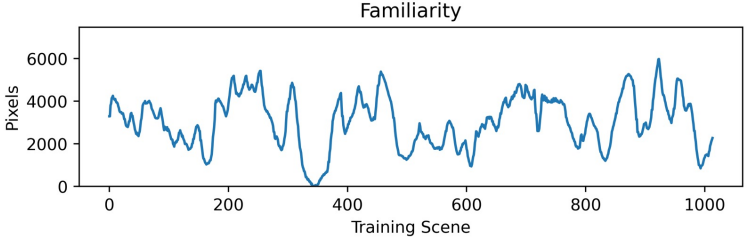
Navigation stats: RMSD error: 804.43; RMSD/dist: 2.011; TD: 2224; p90: 40; p50: 22; complete: 0

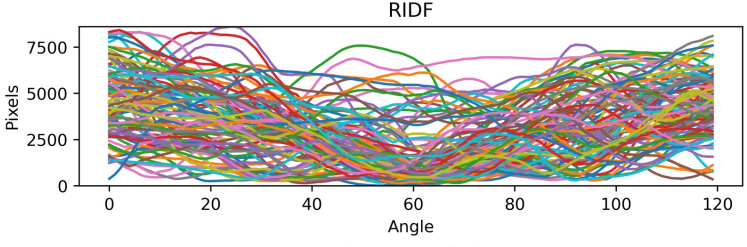

Index: BLUR: 9.0; LEVELS: 32; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

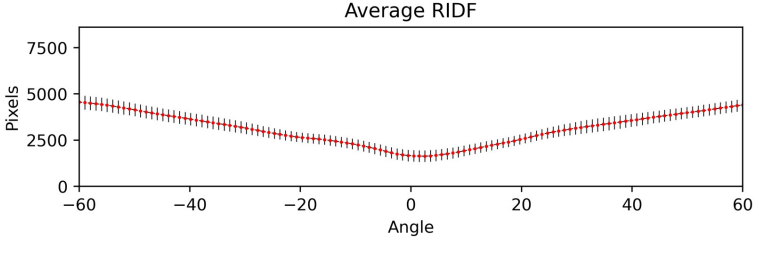
0%







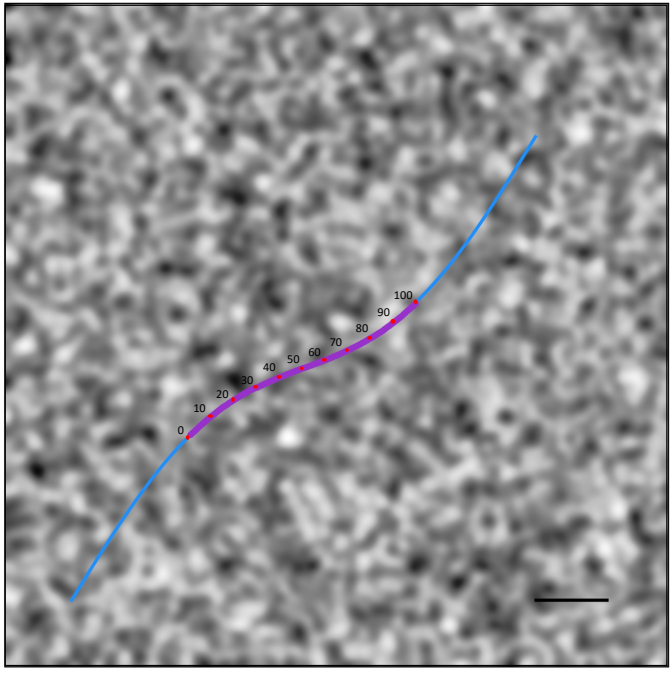


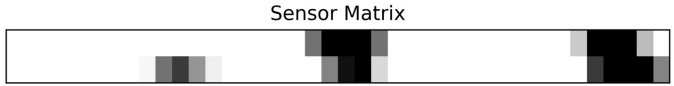


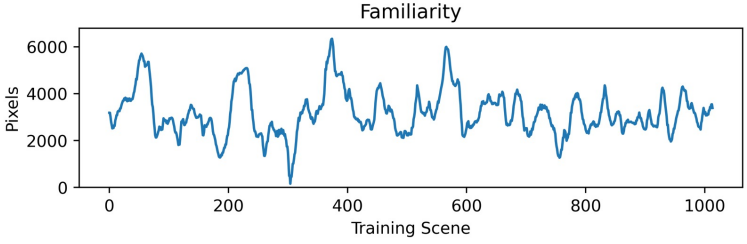
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

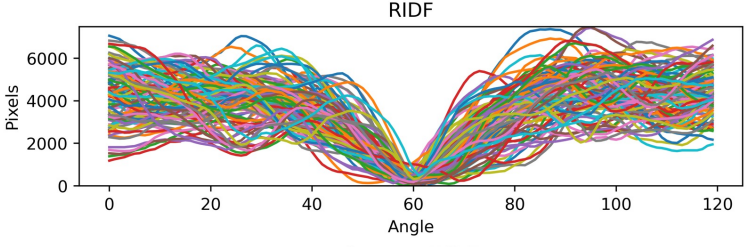
Navigation stats: RMSD error: 3875.05; RMSD/dist: 9.688; TD: 1646; p90: 58; p50: 28; complete: 0

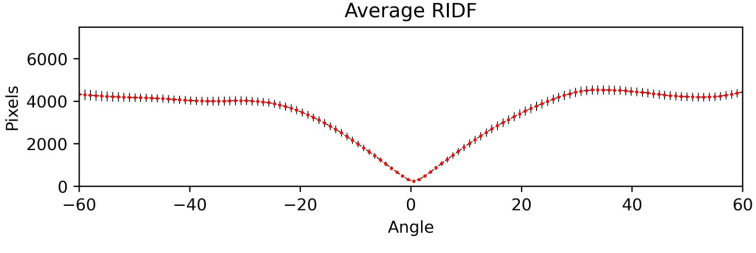
100%







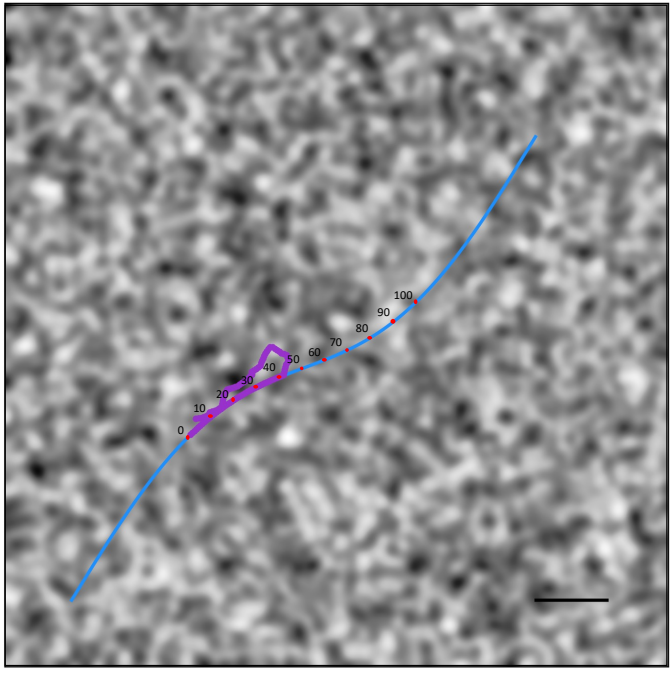


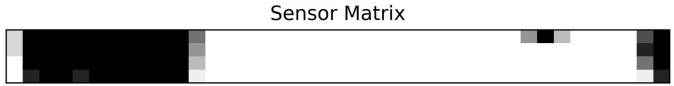


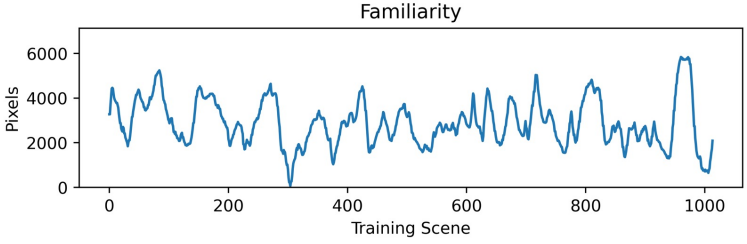
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

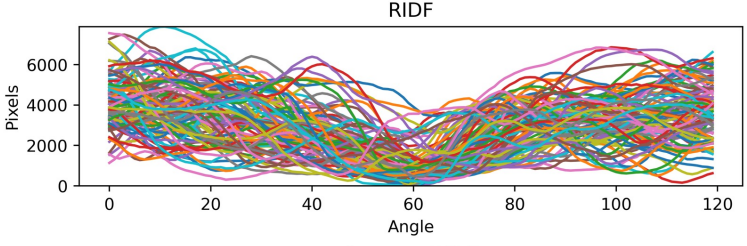
Navigation stats: RMSD error: 52.07; RMSD/dist: 0.130; TD: 3131; p90: 34; p50: 18; complete: 0

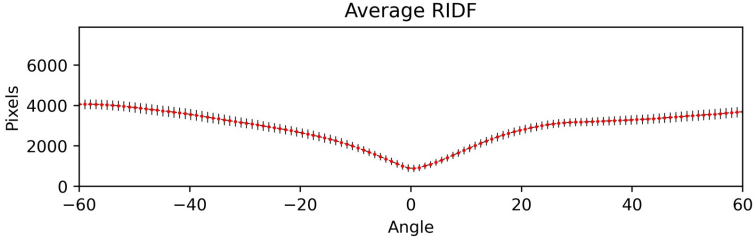
40%







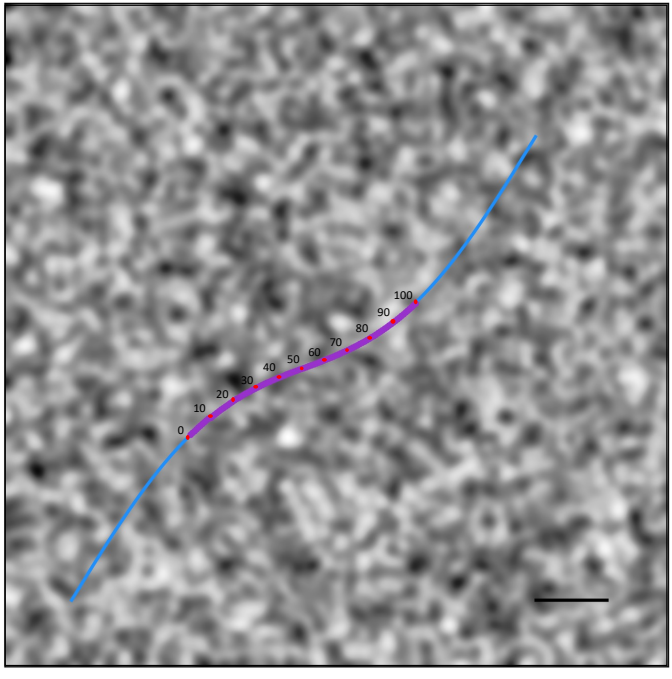


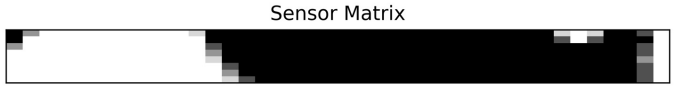


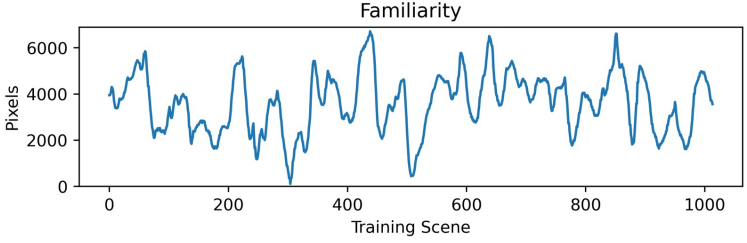
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

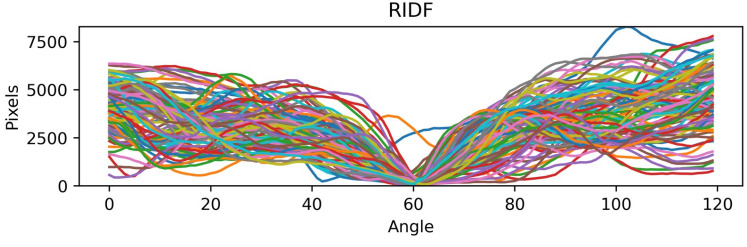
Navigation stats: RMSD error: 1157.20; RMSD/dist: 2.893; TD: 2284; p90: 52; p50: 22; complete: 0

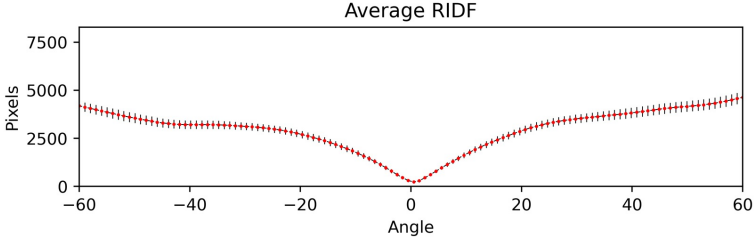
100%







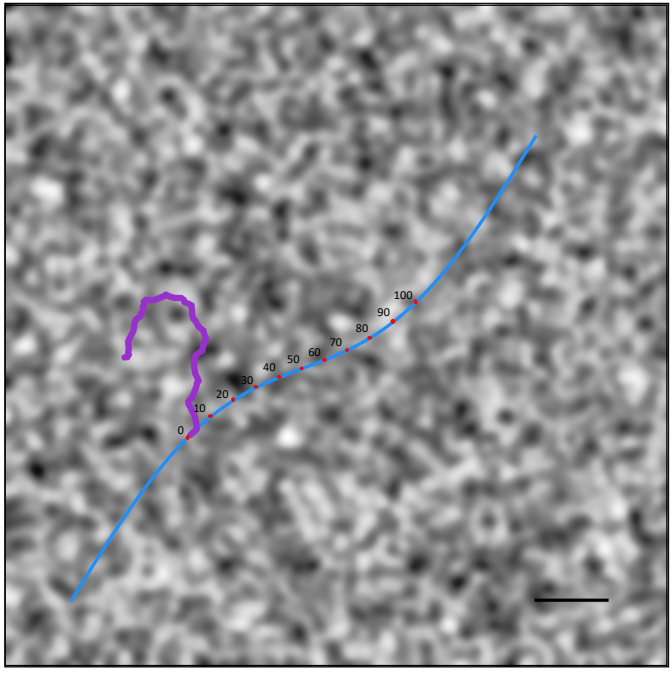


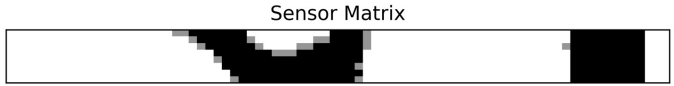


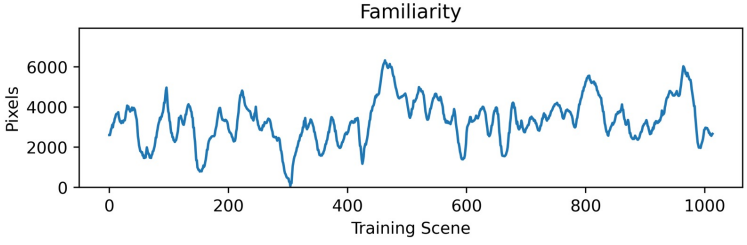
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

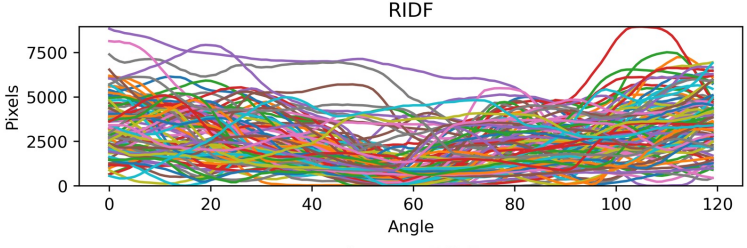
Navigation stats: RMSD error: 39.95; RMSD/dist: 0.100; TD: 3050; p90: 50; p50: 20; complete: 0

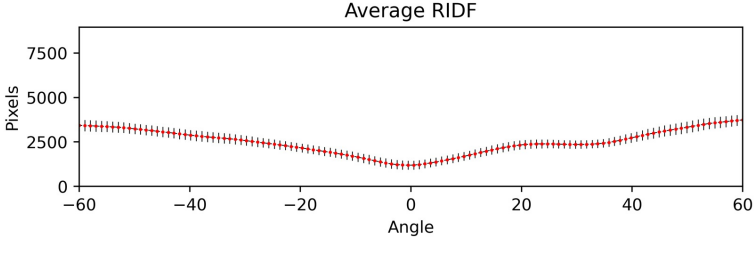
0%







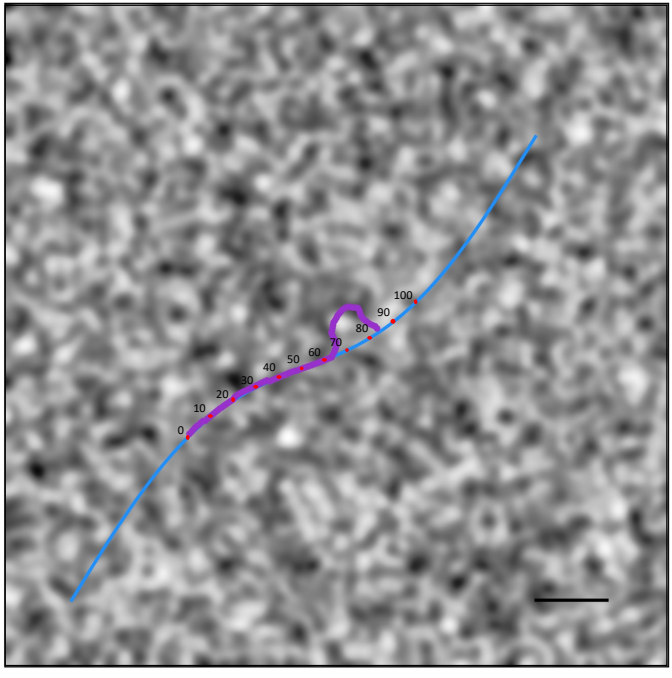


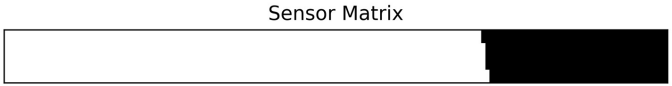


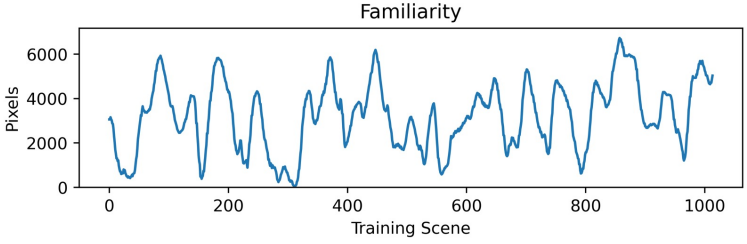
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

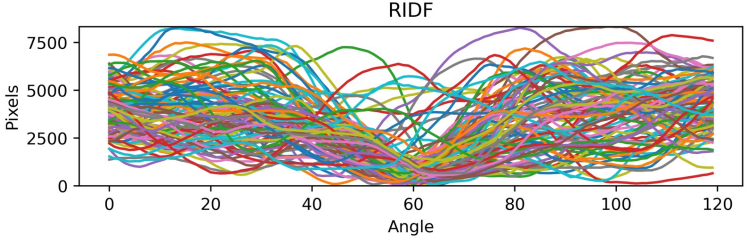
Navigation stats: RMSD error: 11810.64; RMSD/dist: 29.527; TD: 2131; p90: 92; p50: 44; complete: 0

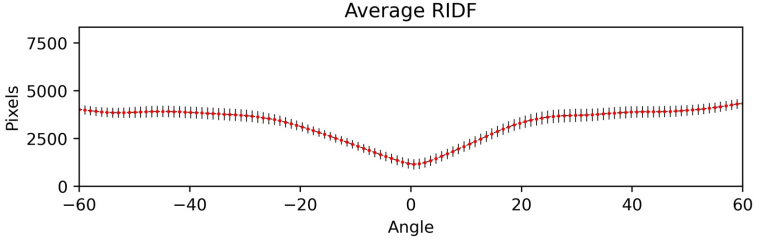
60%





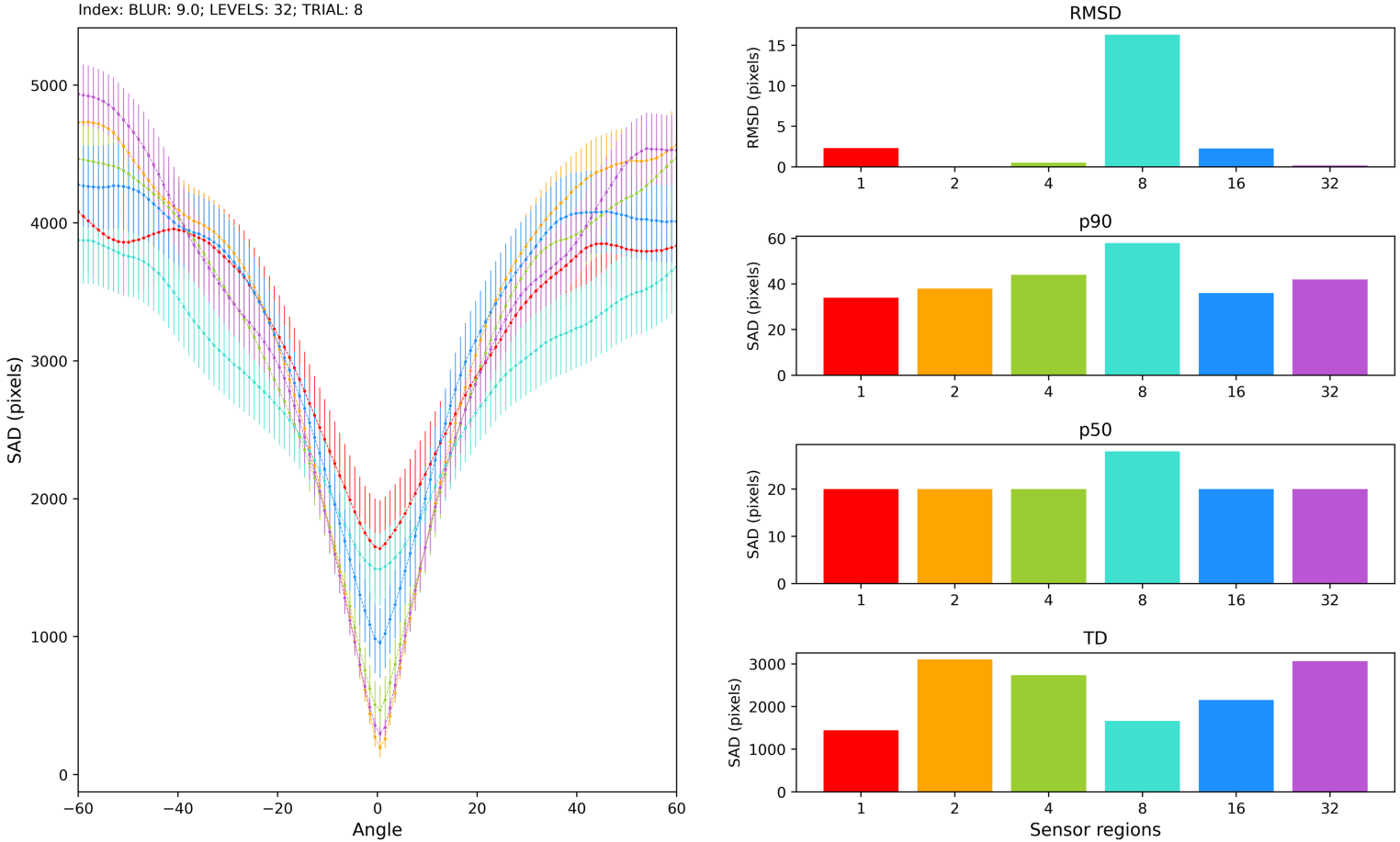




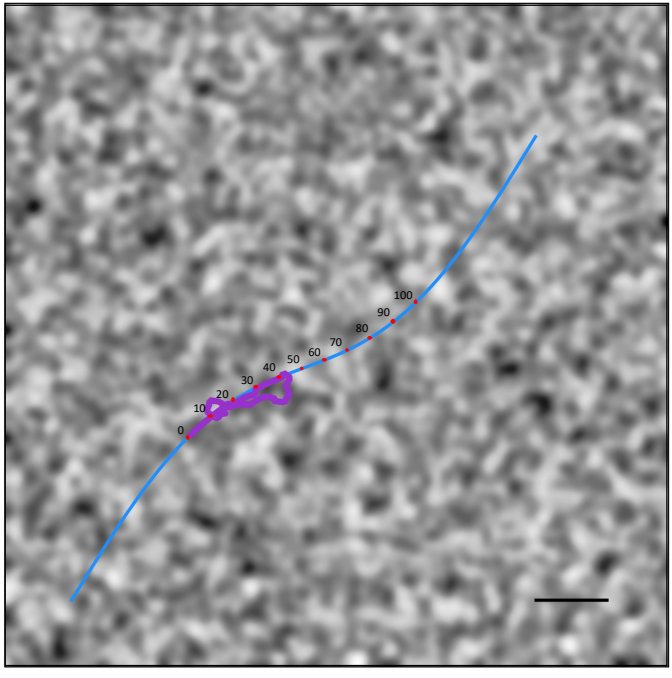


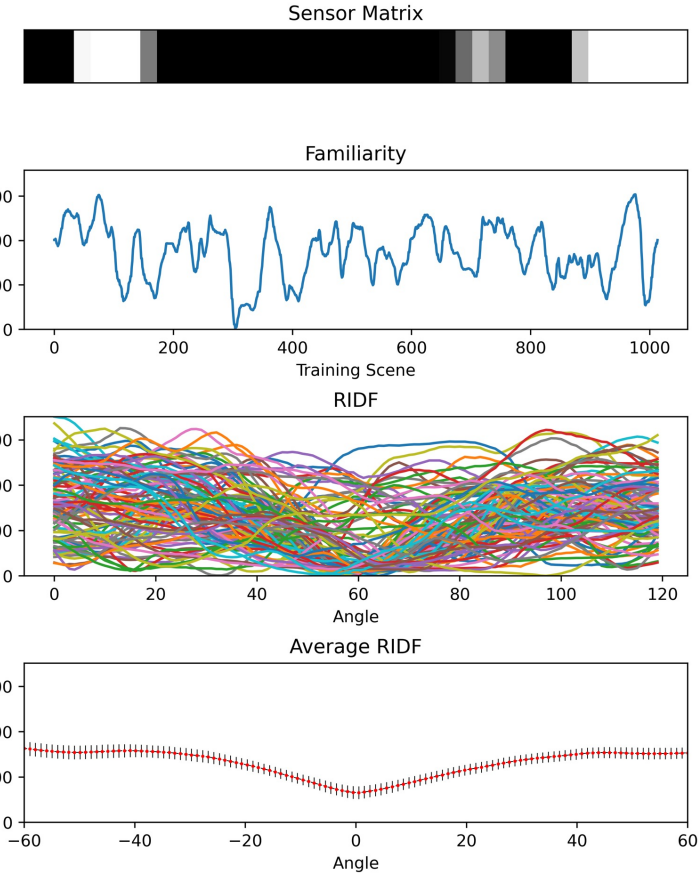
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1375.72; RMSD/dist: 3.439; TD: 2005; p90: 36; p50: 22; complete: 0


Index: BLUR: 9.0; LEVELS: 32; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

20%

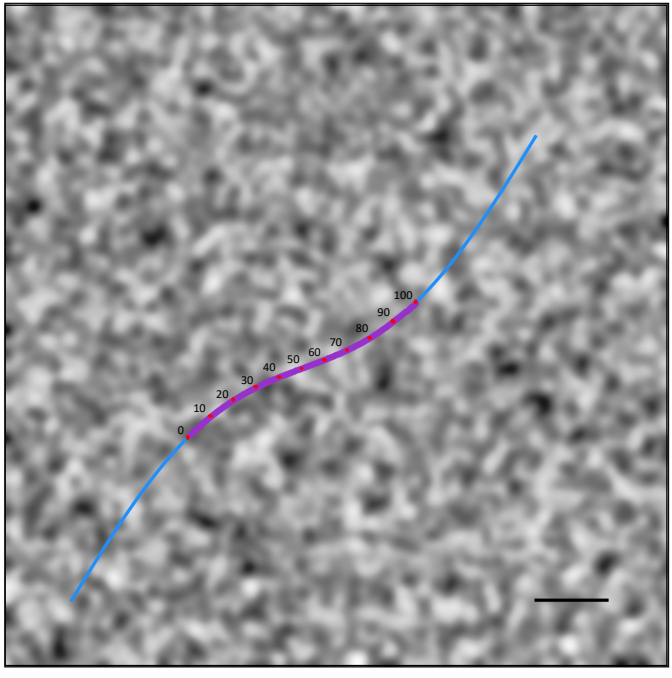


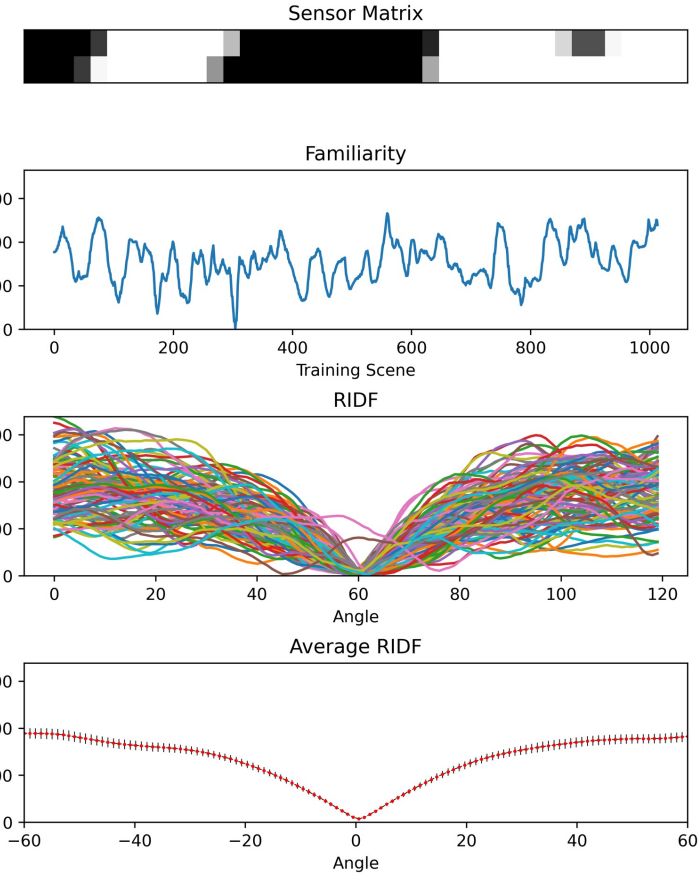


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 927.09; RMSD/dist: 2.318; TD: 1443; p90: 34; p50: 20; complete: 0

100%

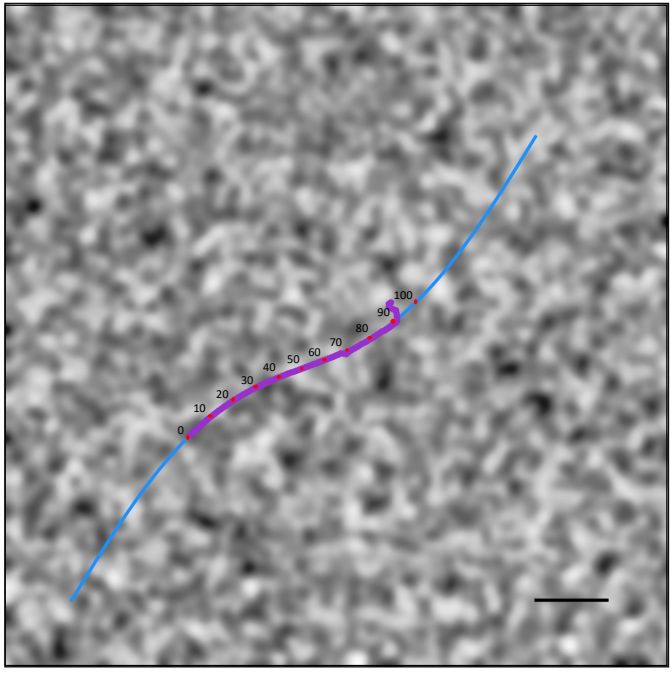


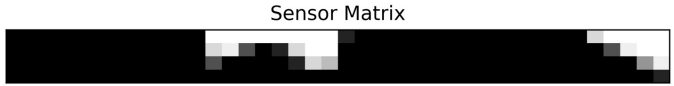


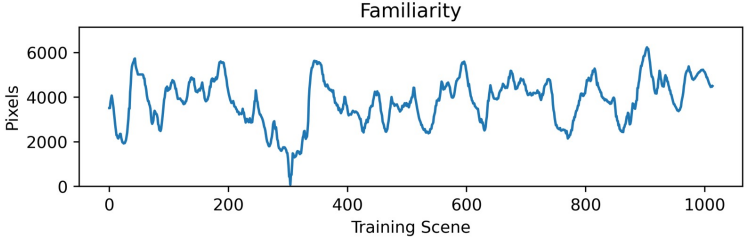
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

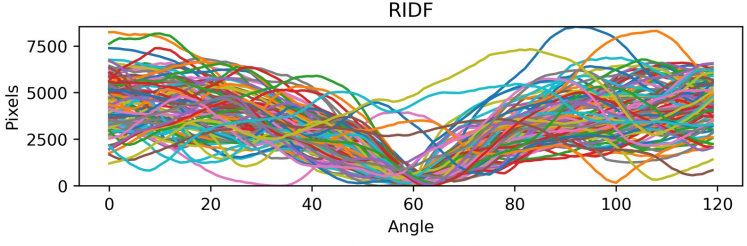
Navigation stats: RMSD error: 30.34; RMSD/dist: 0.076; TD: 3100; p90: 38; p50: 20; complete: 0

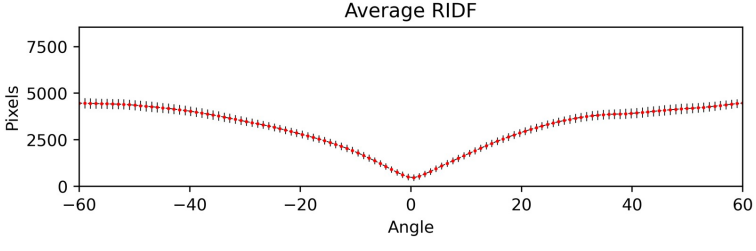
90%







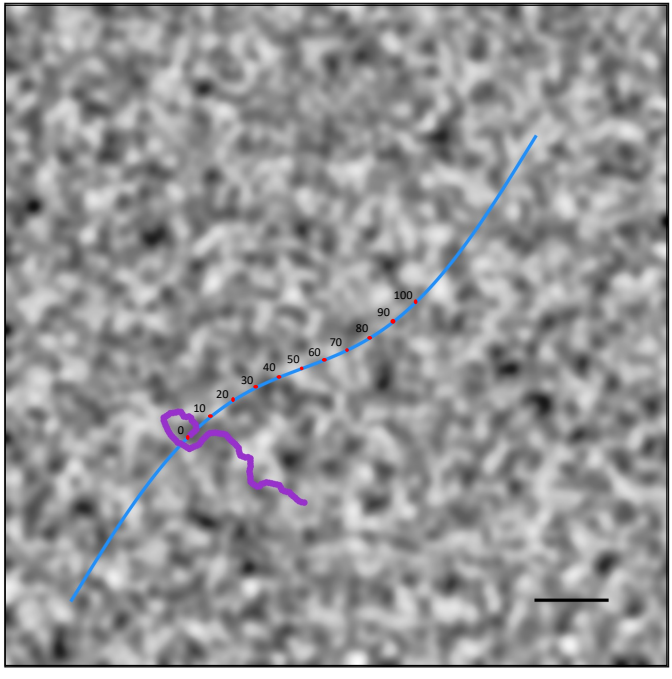


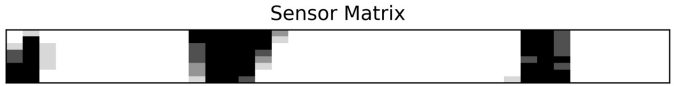


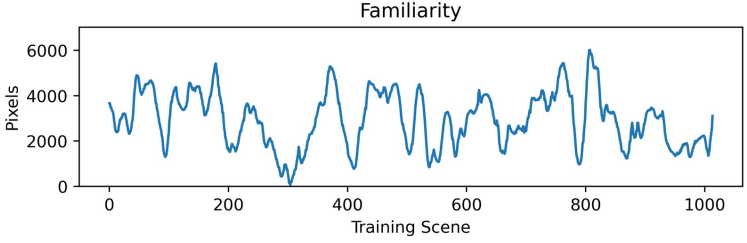
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

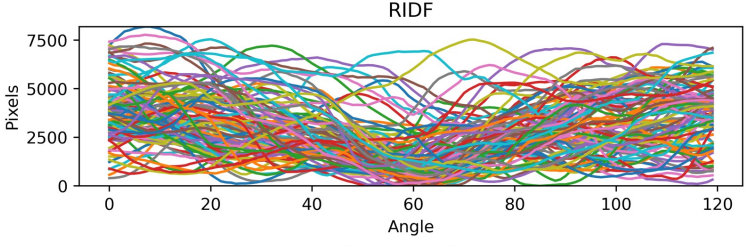
Navigation stats: RMSD error: 203.36; RMSD/dist: 0.508; TD: 2735; p90: 44; p50: 20; complete: 0

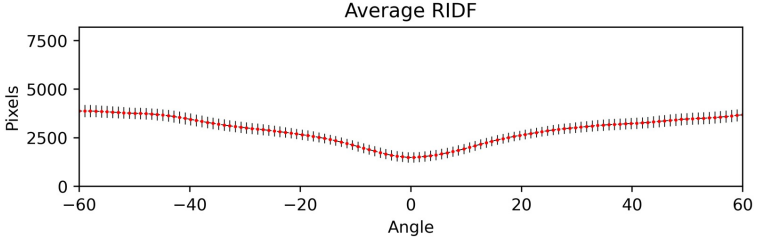
0%







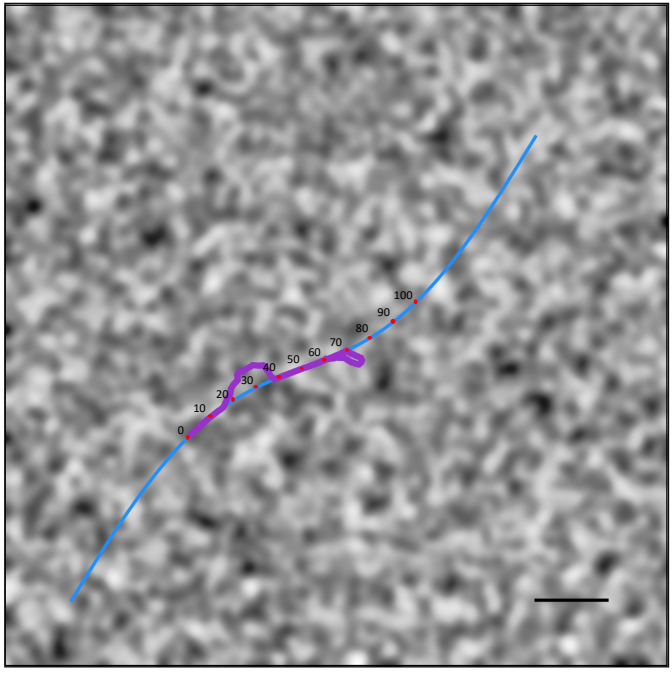


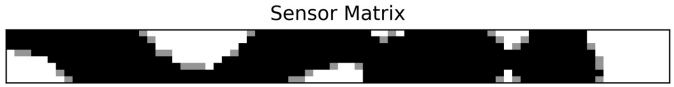


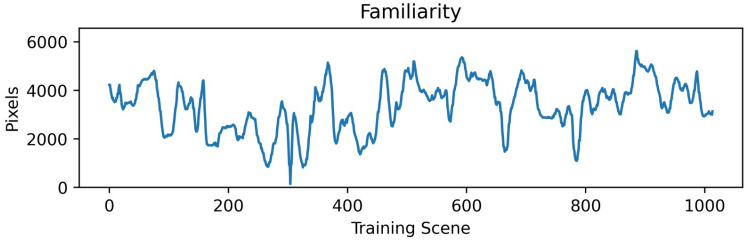
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

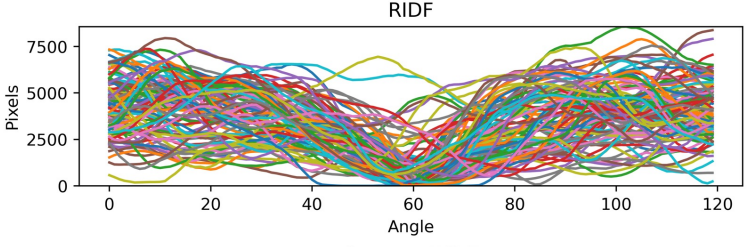
Navigation stats: RMSD error: 6529.39; RMSD/dist: 16.323; TD: 1663; p90: 58; p50: 28; complete: 0

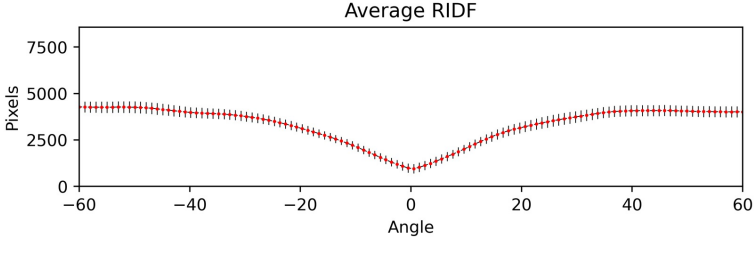
40%







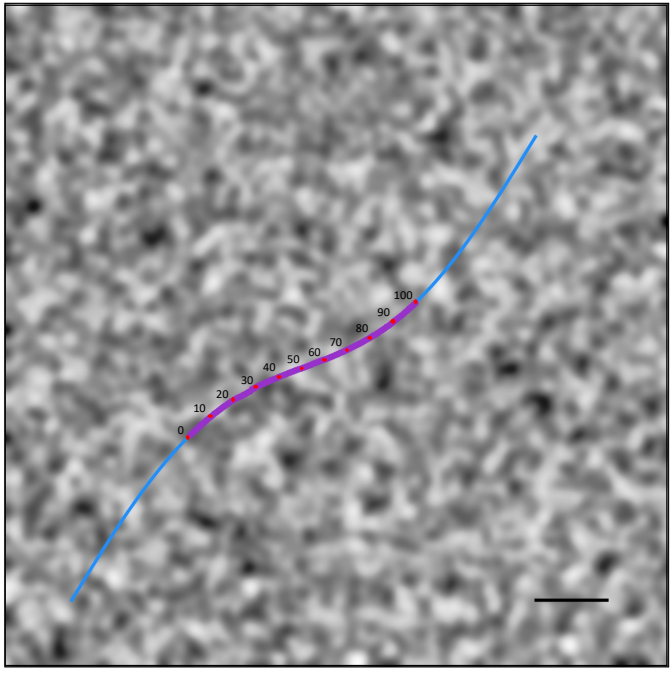


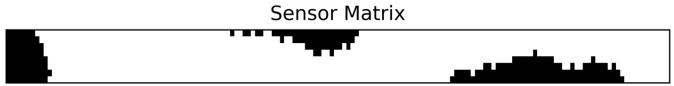


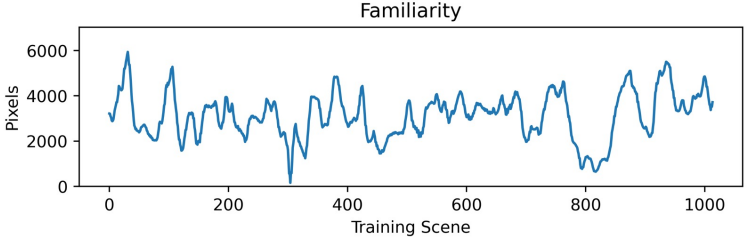
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

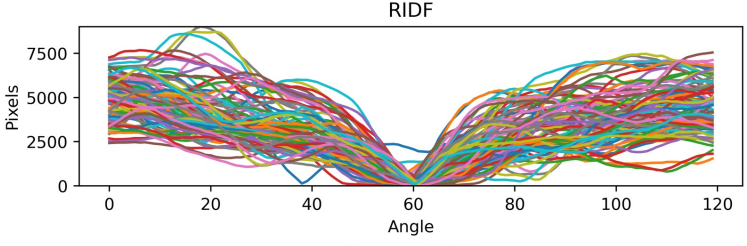
Navigation stats: RMSD error: 905.91; RMSD/dist: 2.265; TD: 2156; p90: 36; p50: 20; complete: 0

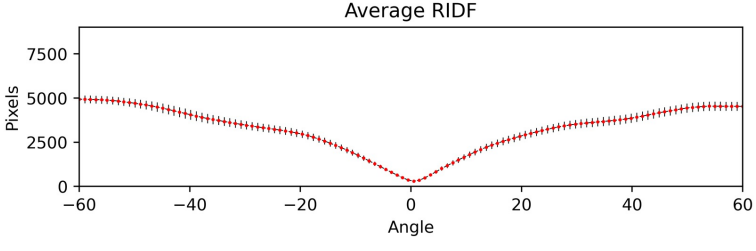
100%





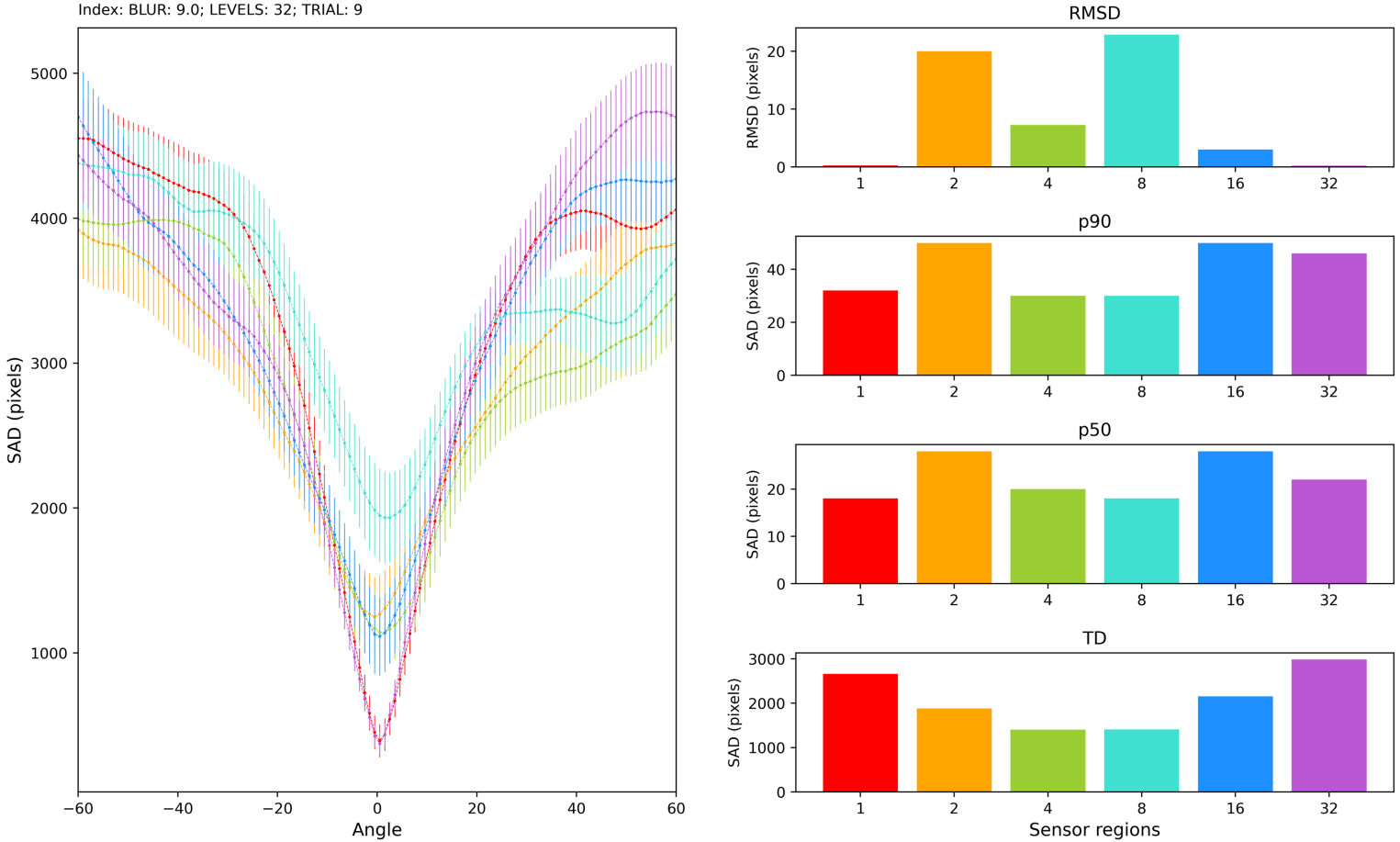




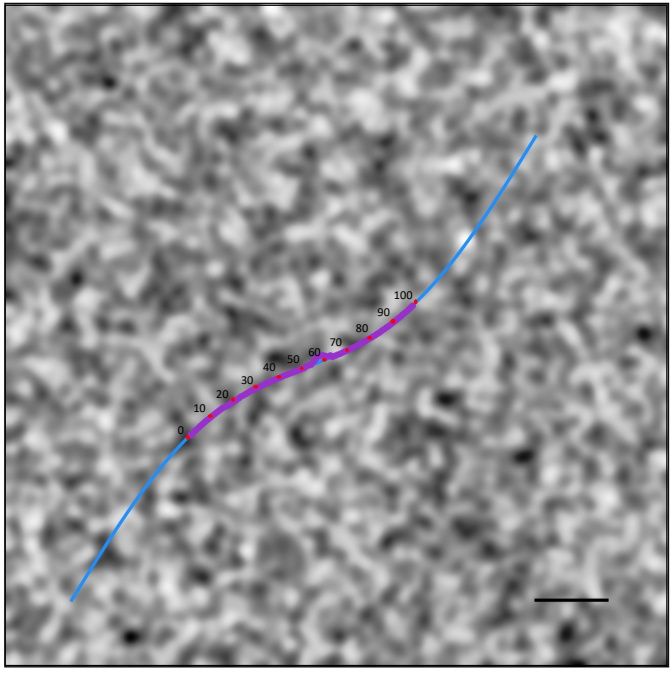


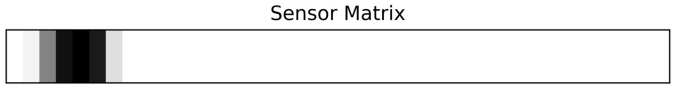
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

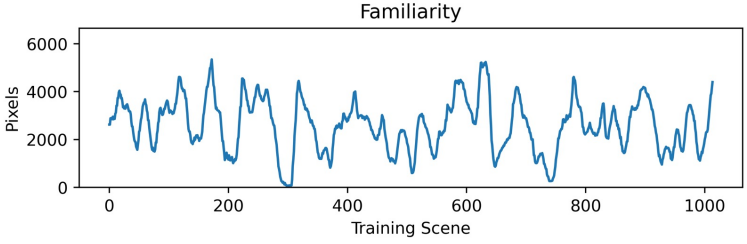
Navigation stats: RMSD error: 68.03; RMSD/dist: 0.170; TD: 3065; p90: 42; p50: 20; complete: 0

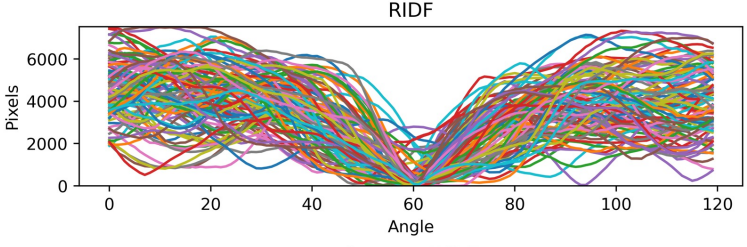

Index: BLUR: 9.0; LEVELS: 32; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

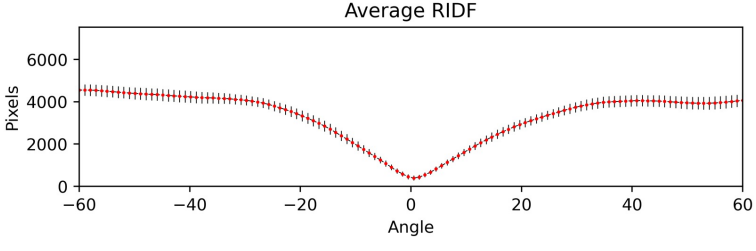
90%







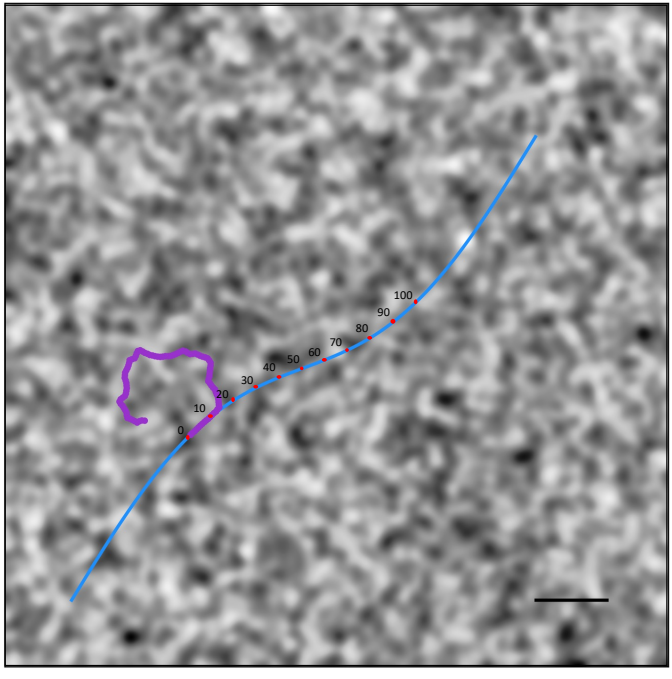


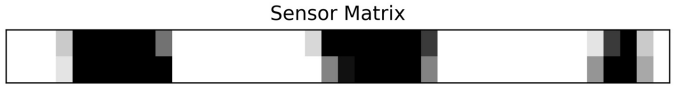


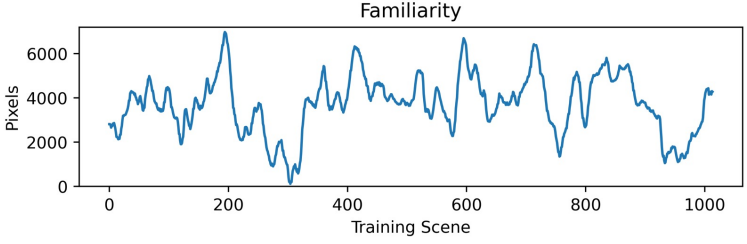
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

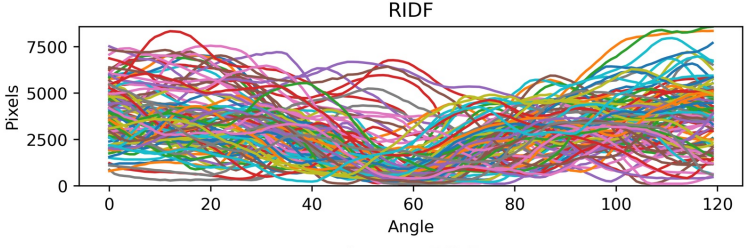
Navigation stats: RMSD error: 100.03; RMSD/dist: 0.250; TD: 2661; p90: 32; p50: 18; complete: 0

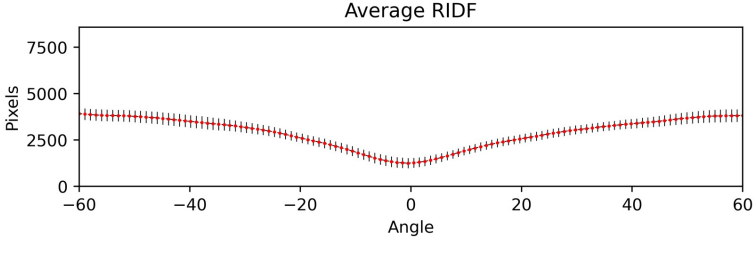
10%







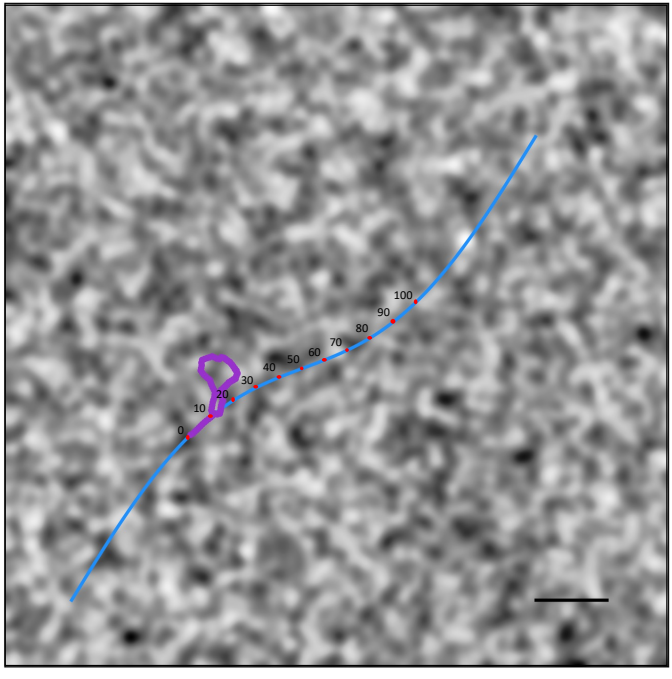


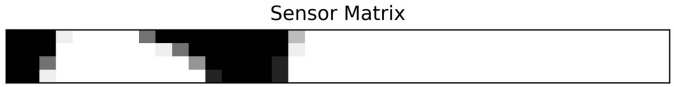


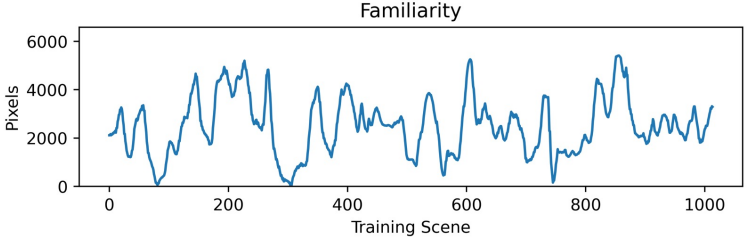
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

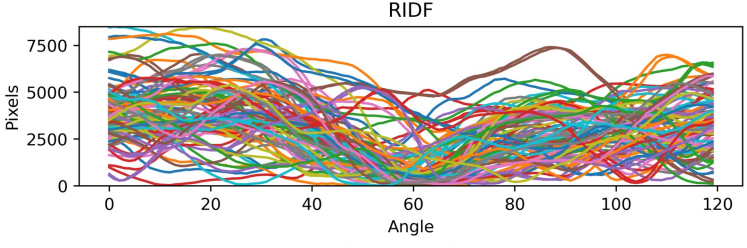
Navigation stats: RMSD error: 8010.02; RMSD/dist: 20.025; TD: 1884; p90: 50; p50: 28; complete: 0

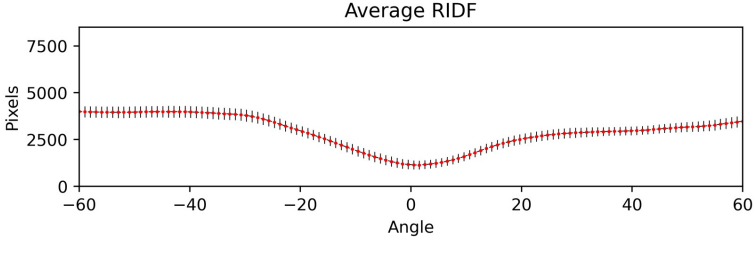
10%







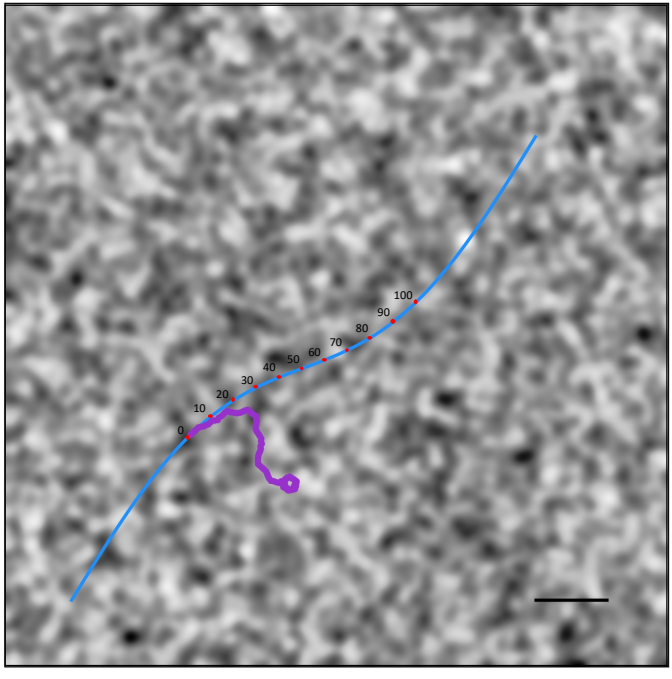


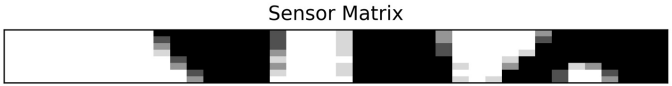


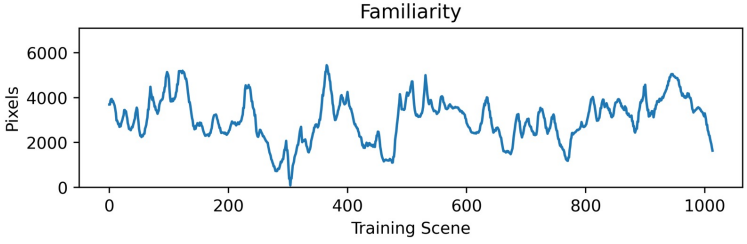
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

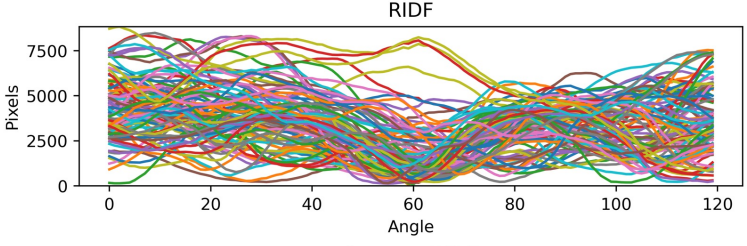
Navigation stats: RMSD error: 2905.16; RMSD/dist: 7.263; TD: 1404; p90: 30; p50: 20; complete: 0

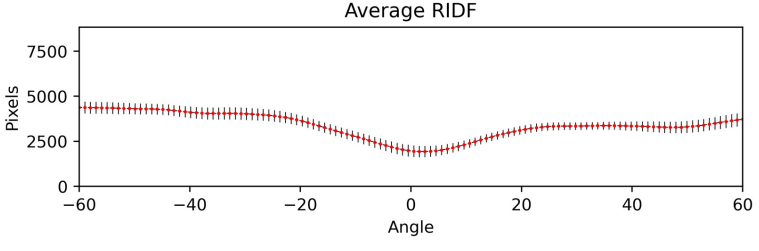
0%







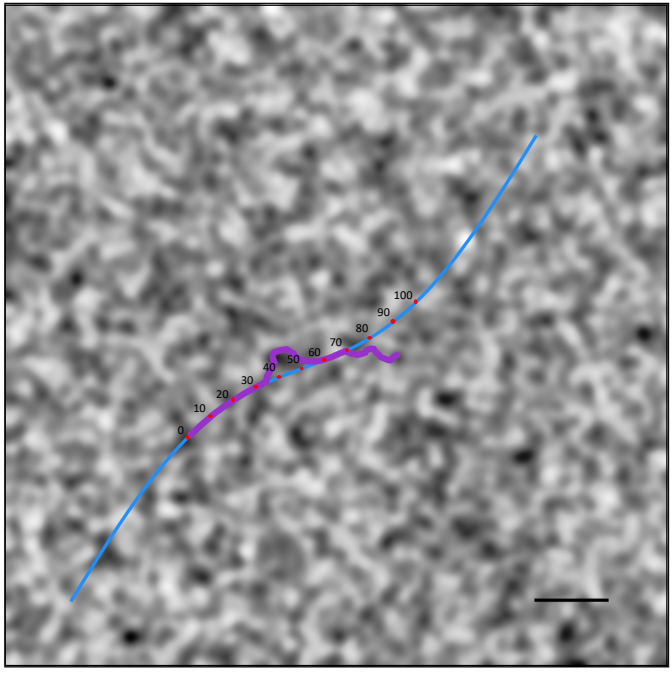


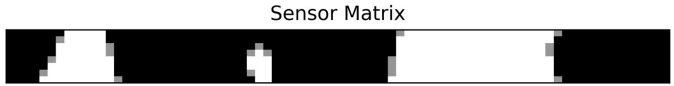


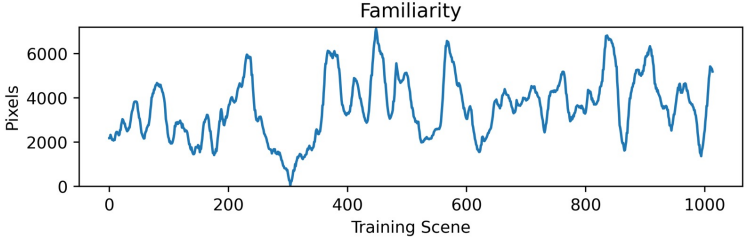
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

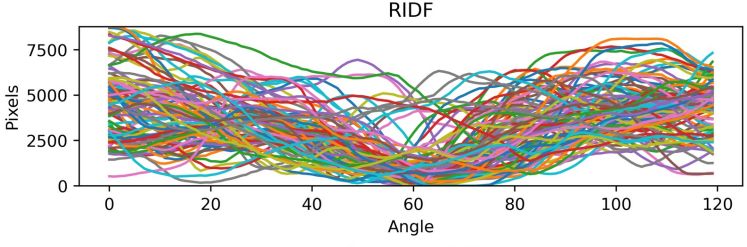
Navigation stats: RMSD error: 9154.22; RMSD/dist: 22.886; TD: 1407; p90: 30; p50: 18; complete: 0

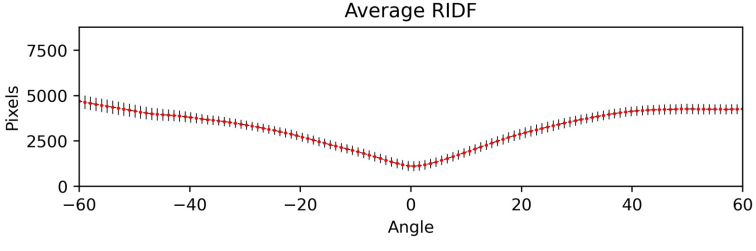
40%







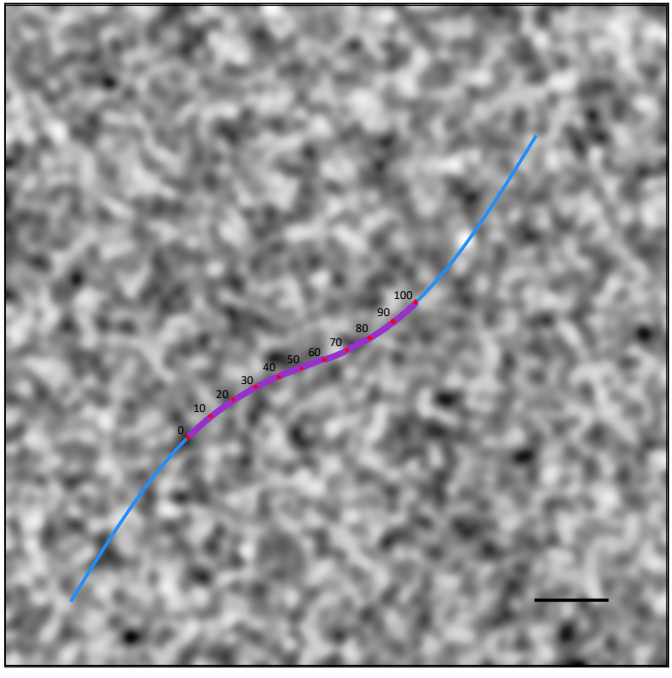


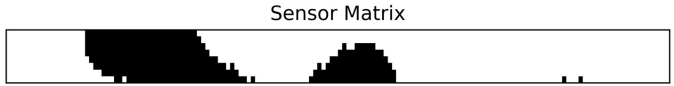


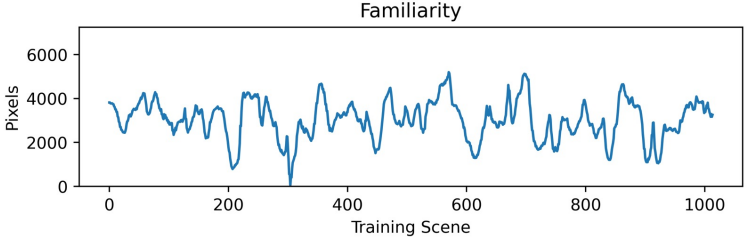
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

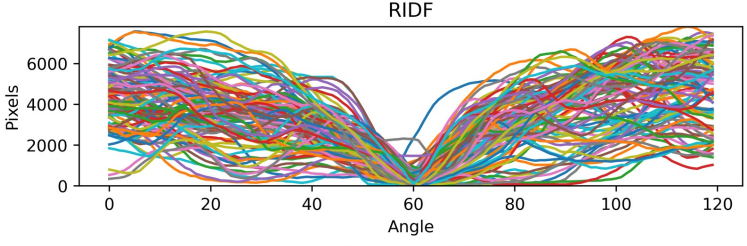
Navigation stats: RMSD error: 1196.28; RMSD/dist: 2.991; TD: 2153; p90: 50; p50: 28; complete: 0

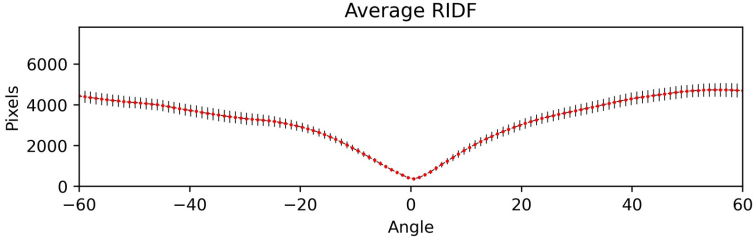
100%





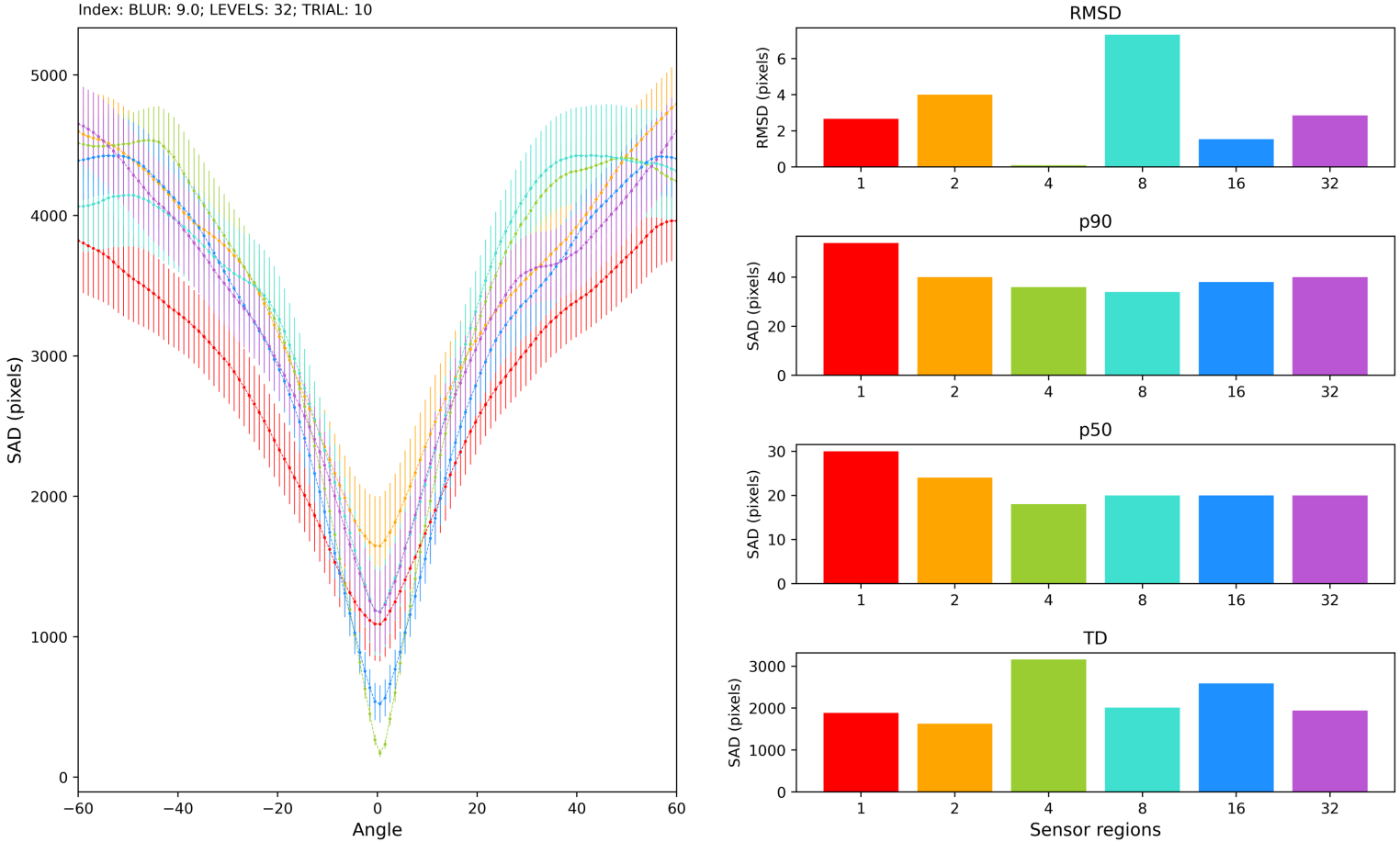




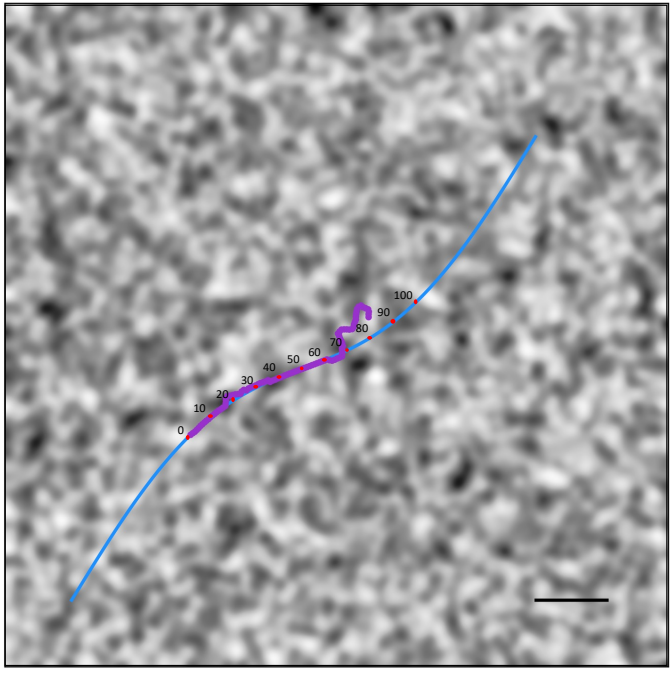


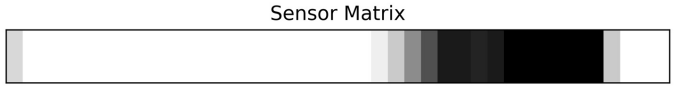
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

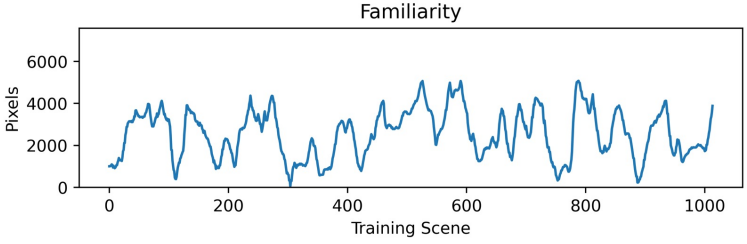
Navigation stats: RMSD error: 80.43; RMSD/dist: 0.201; TD: 2985; p90: 46; p50: 22; complete: 0

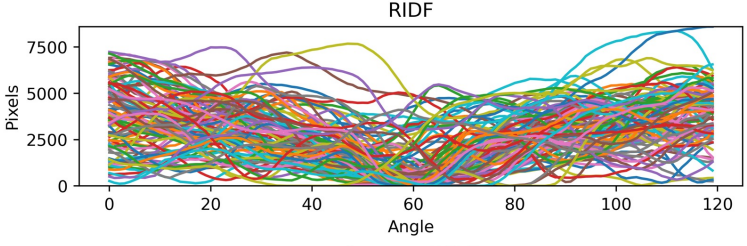

Index: BLUR: 9.0; LEVELS: 32; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

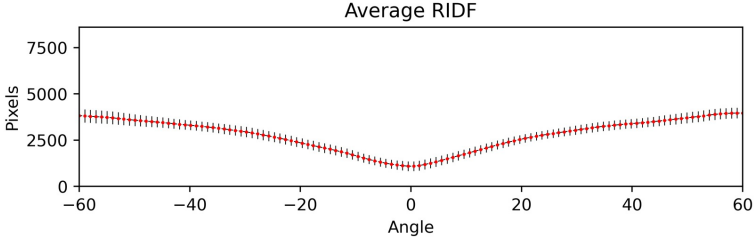
40%







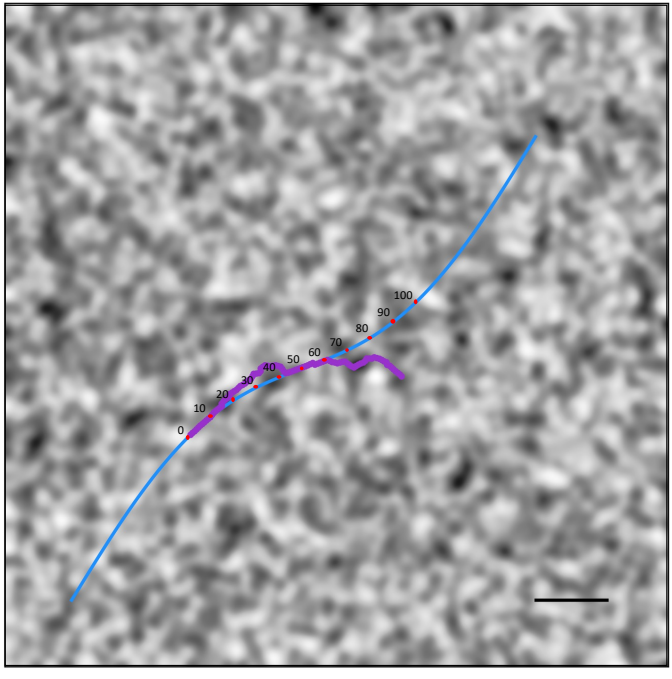


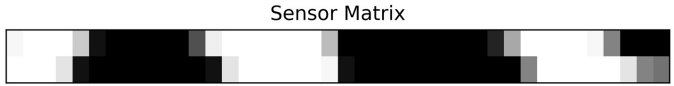


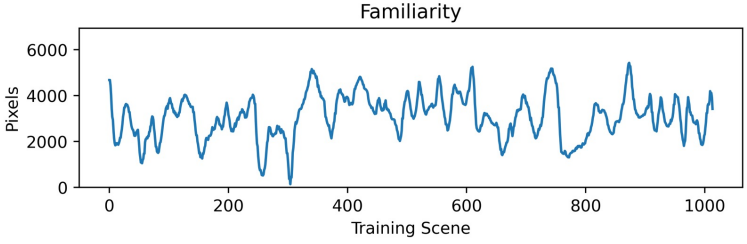
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

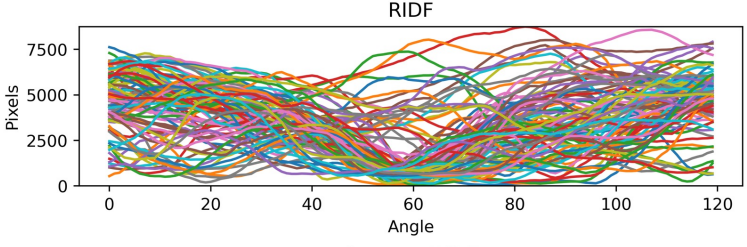
Navigation stats: RMSD error: 1063.87; RMSD/dist: 2.660; TD: 1885; p90: 54; p50: 30; complete: 0

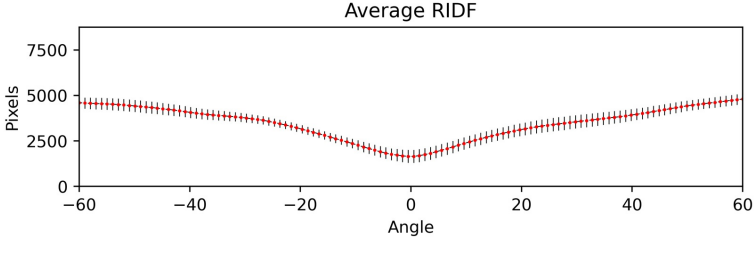
20%







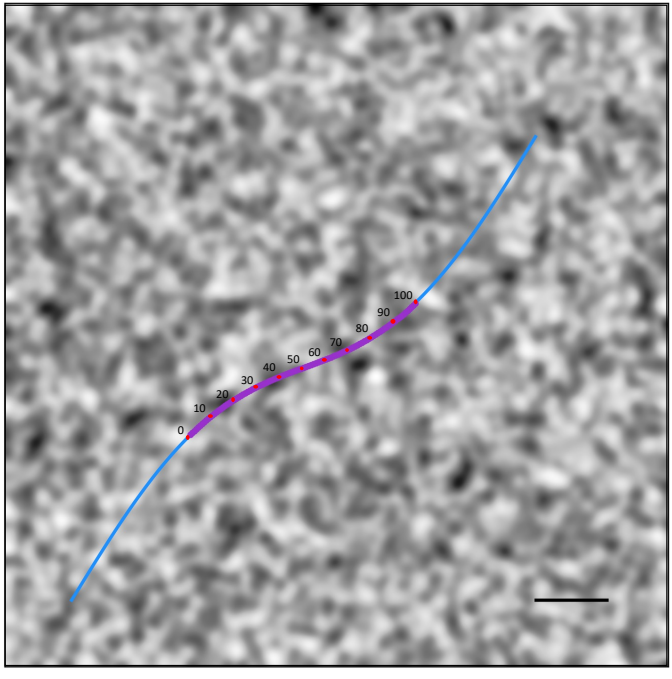


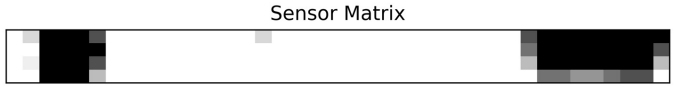


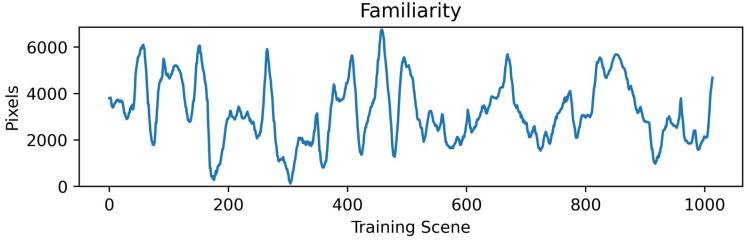
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

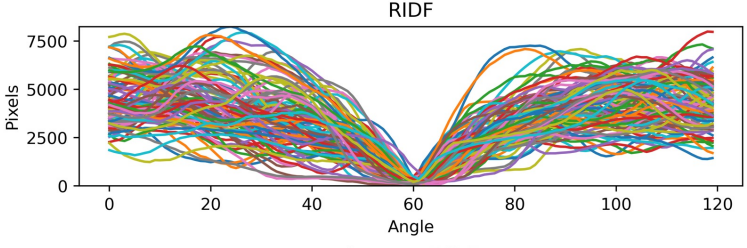
Navigation stats: RMSD error: 1601.32; RMSD/dist: 4.003; TD: 1627; p90: 40; p50: 24; complete: 0

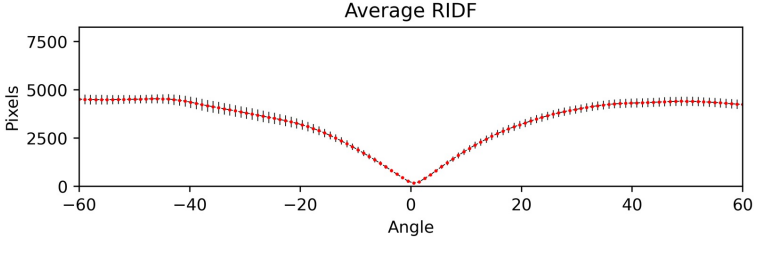
100%







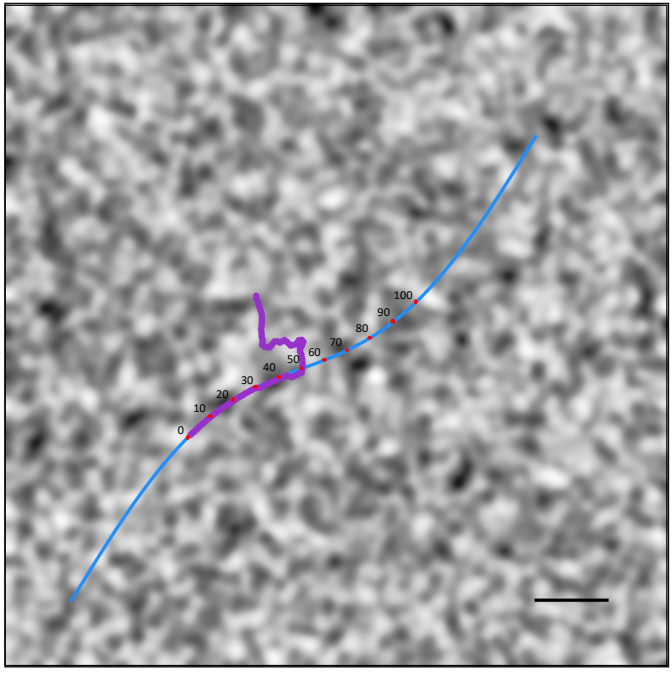


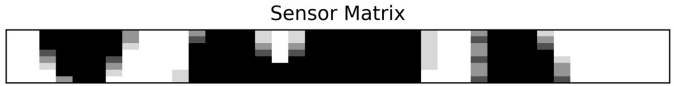


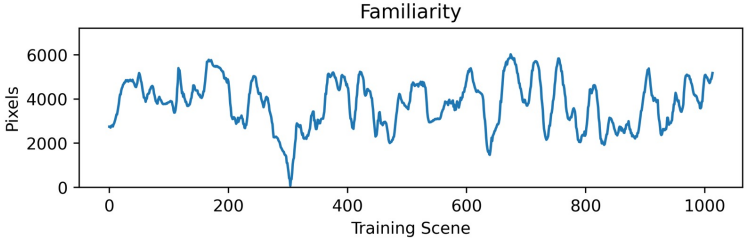
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

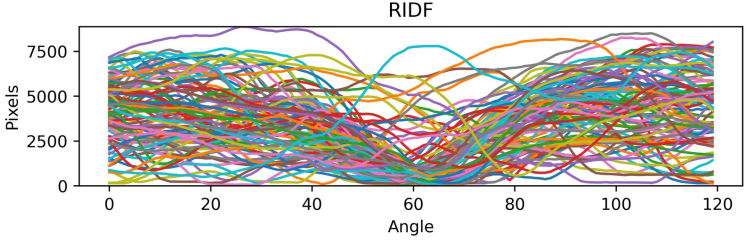
Navigation stats: RMSD error: 38.01; RMSD/dist: 0.095; TD: 3157; p90: 36; p50: 18; complete: 0

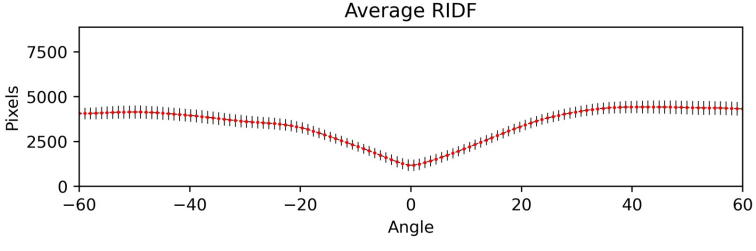
40%







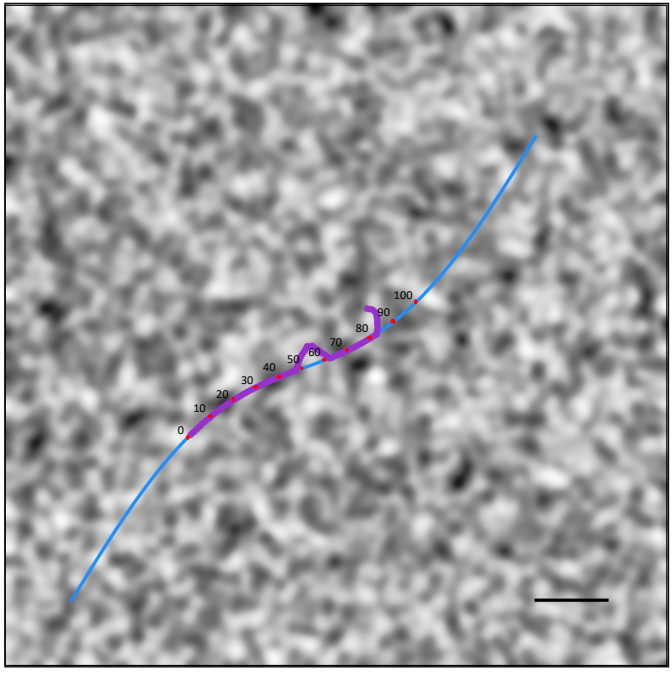


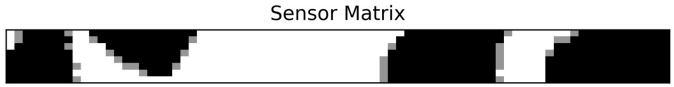


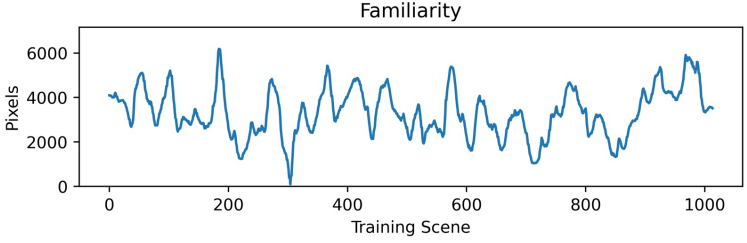
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

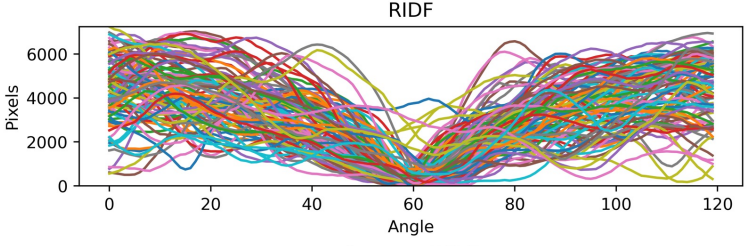
Navigation stats: RMSD error: 2933.85; RMSD/dist: 7.335; TD: 2012; p90: 34; p50: 20; complete: 0

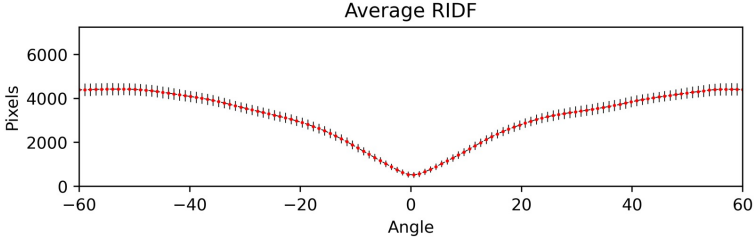
60%







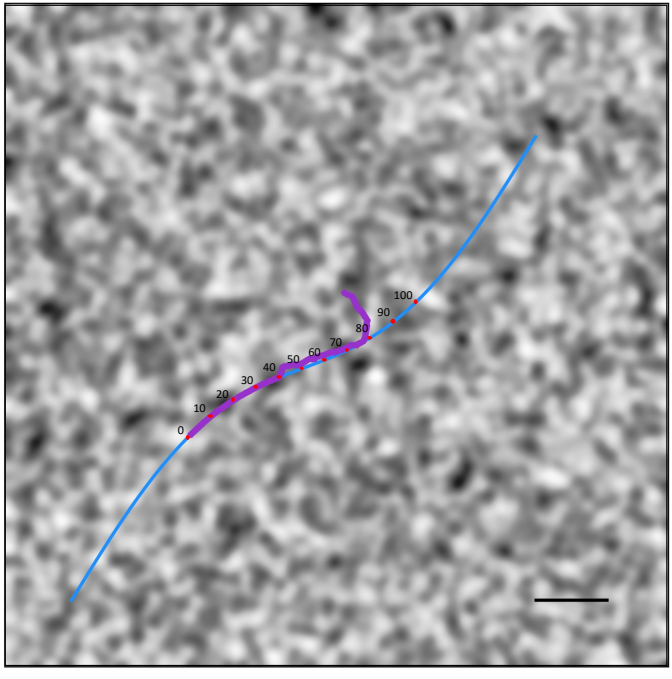


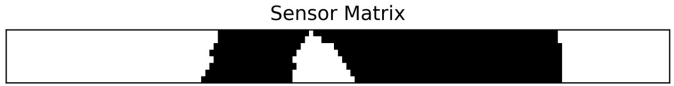


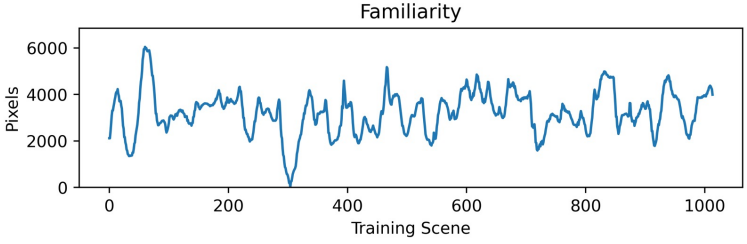
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

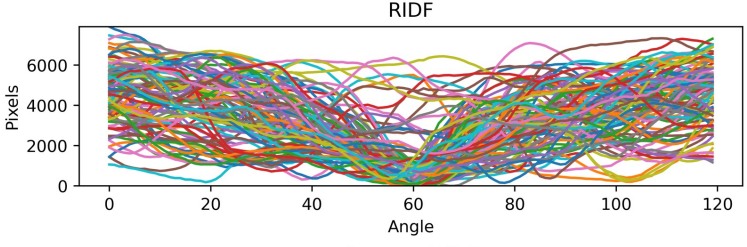
Navigation stats: RMSD error: 612.28; RMSD/dist: 1.531; TD: 2587; p90: 38; p50: 20; complete: 0

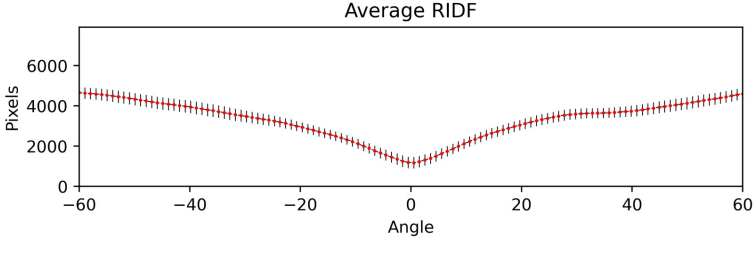
40%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1139.35; RMSD/dist: 2.848; TD: 1940; p90: 40; p50: 20; complete: 0