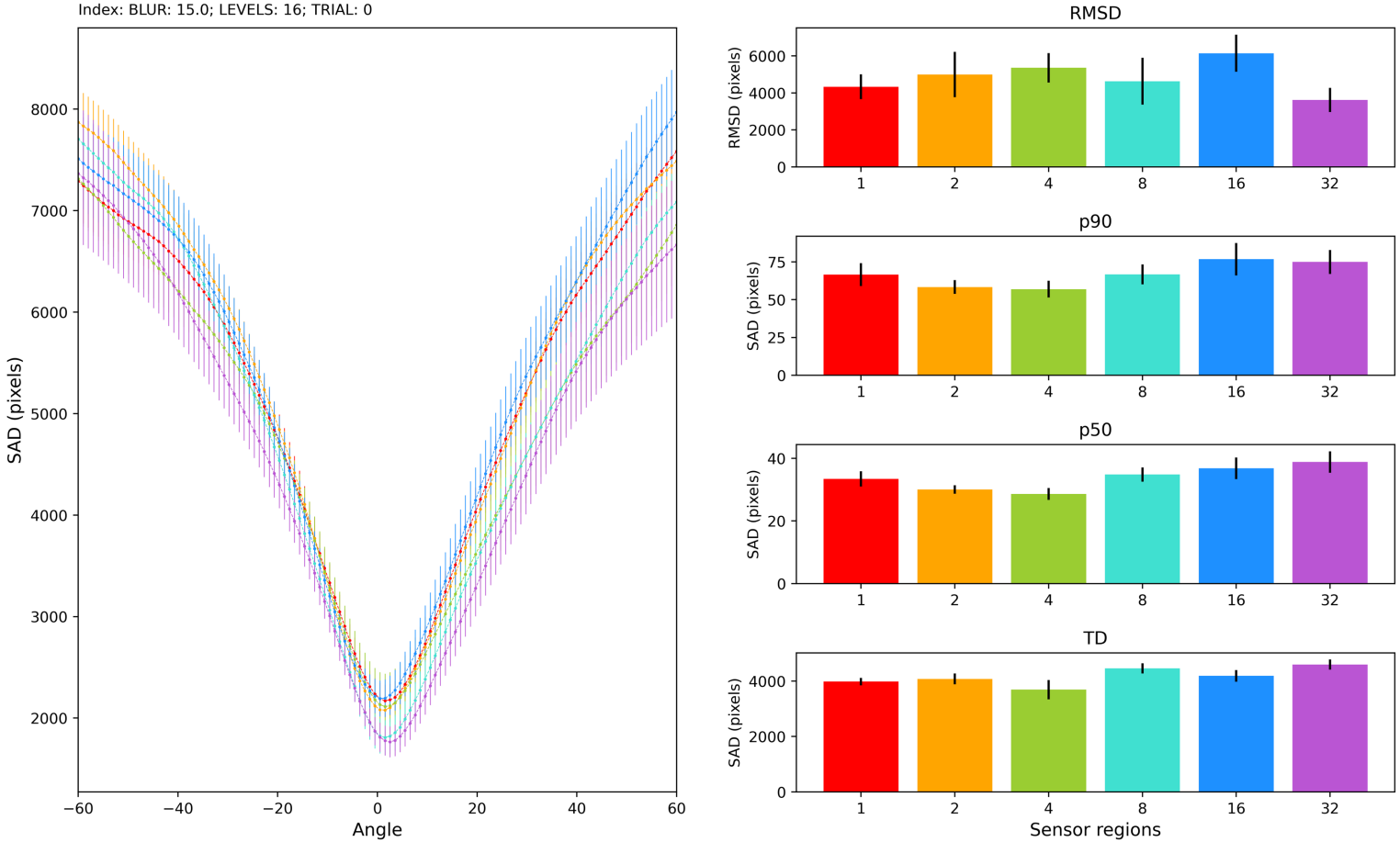
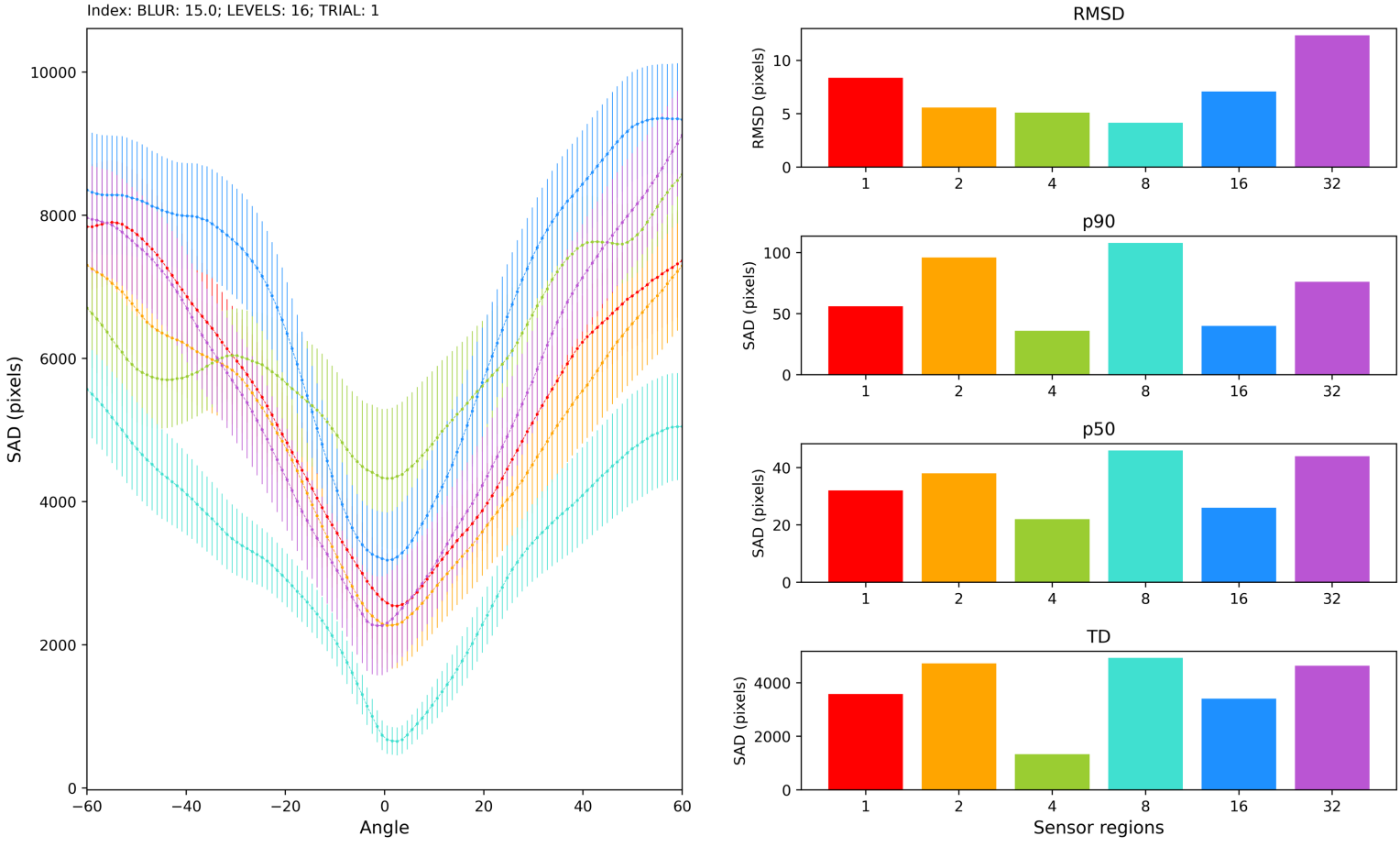
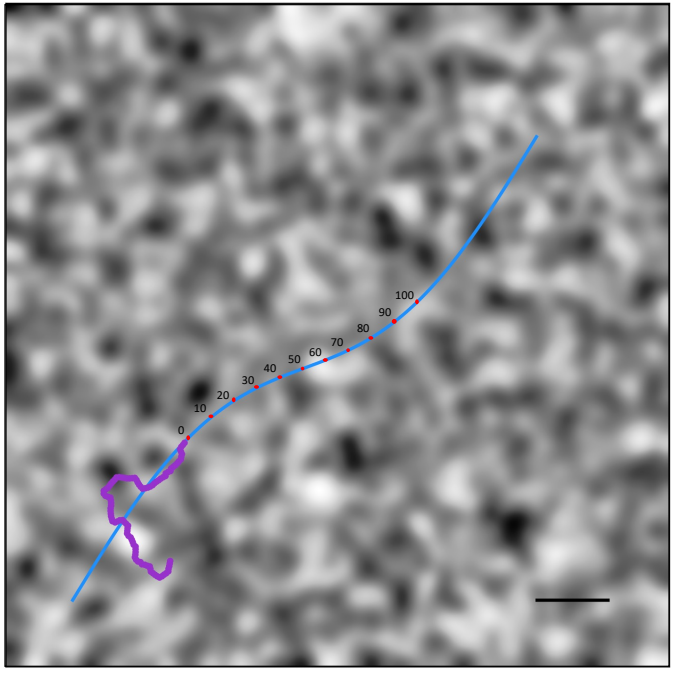
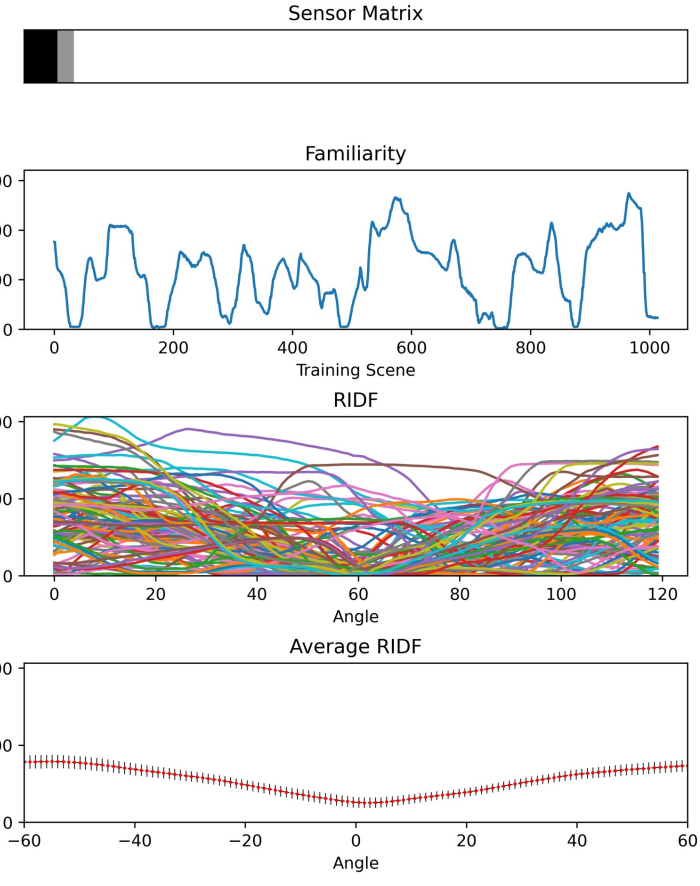

Index: BLUR: 15.0; LEVELS: 16; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 15.0; LEVELS: 16; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

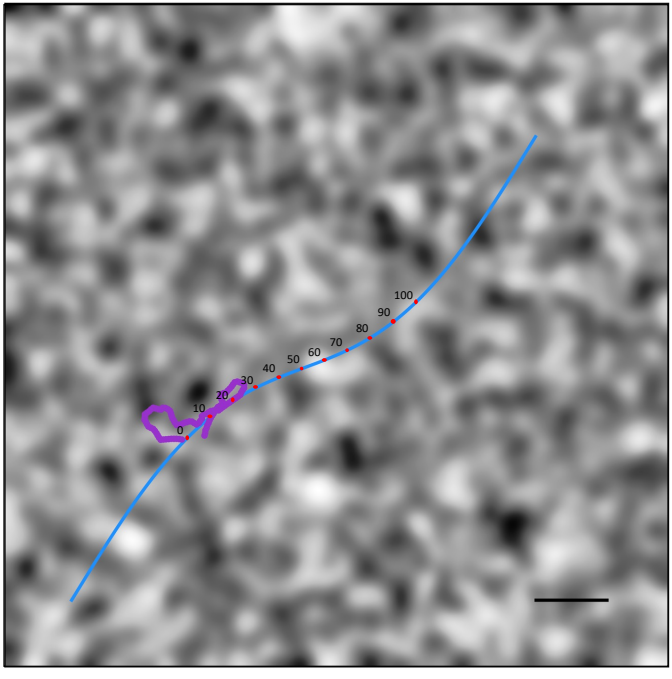


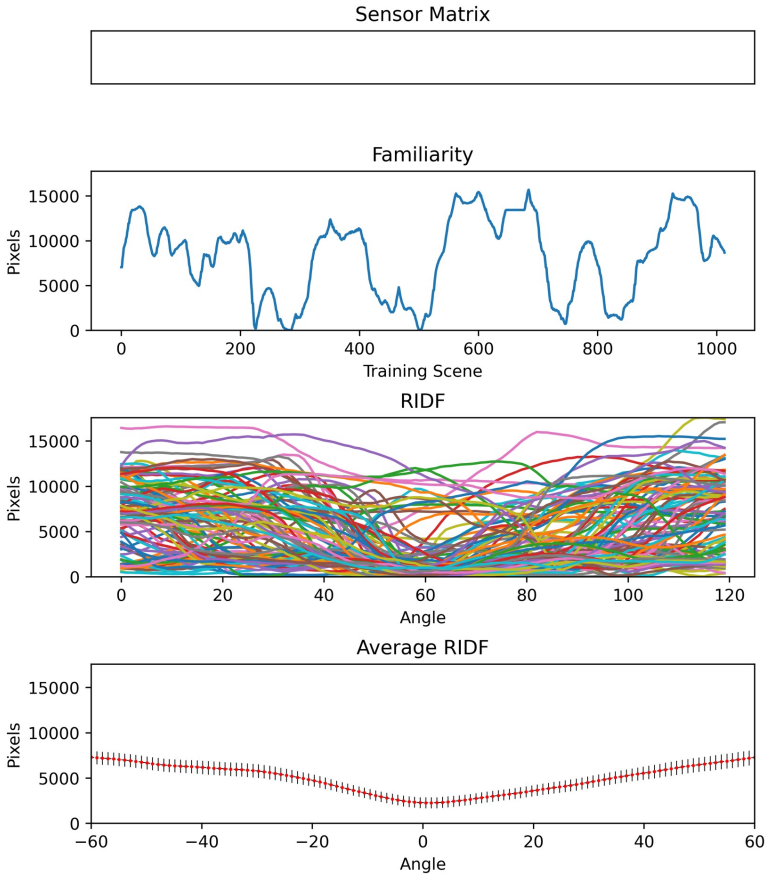


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3347.15; RMSD/dist: 8.368; TD: 3586; p90: 56; p50: 32; complete: 0

10%

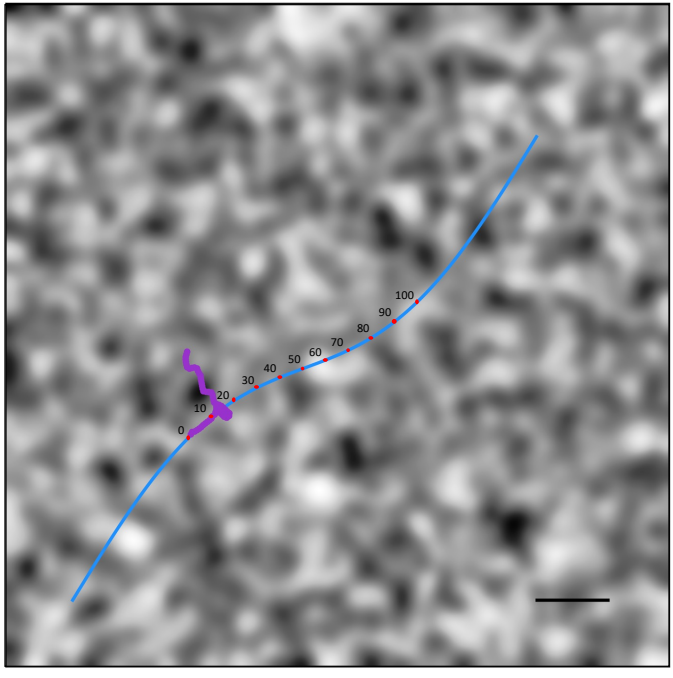


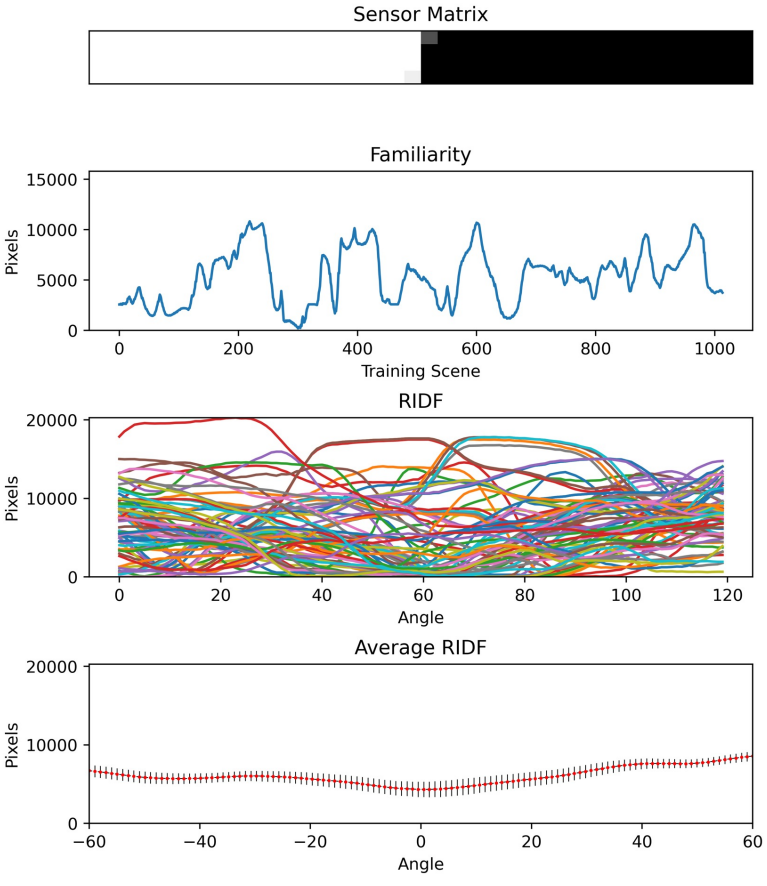


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2231.24; RMSD/dist: 5.578; TD: 4729; p90: 96; p50: 38; complete: 0

10%

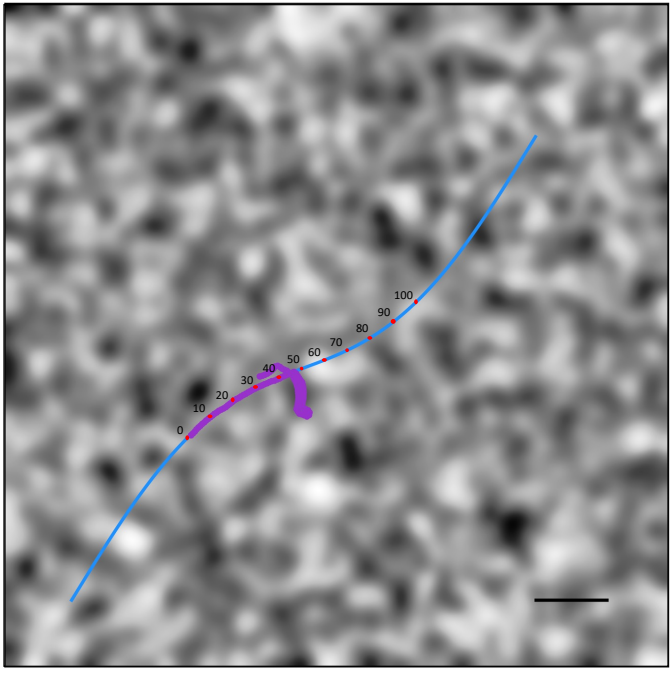


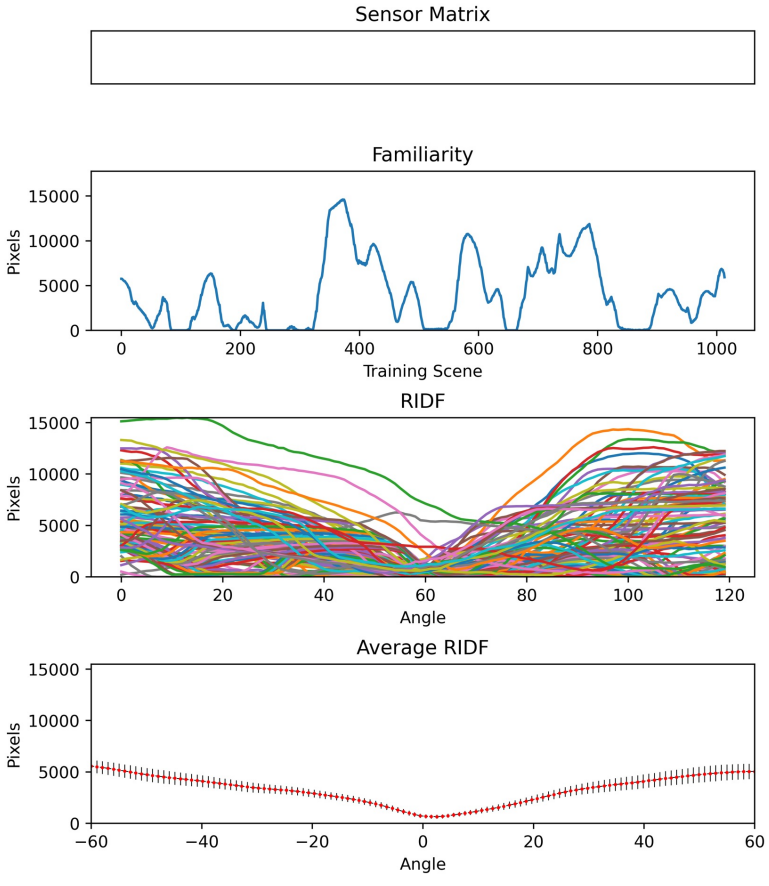


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2037.81; RMSD/dist: 5.095; TD: 1334; p90: 36; p50: 22; complete: 0

40%

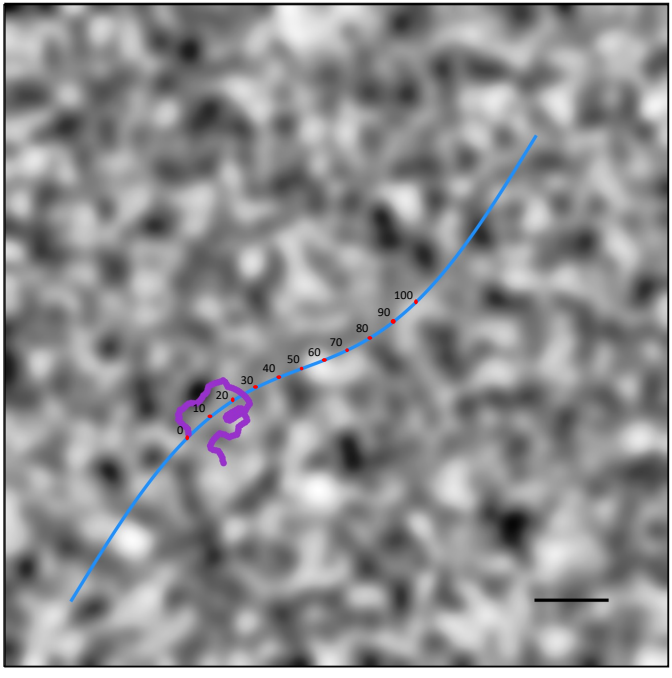


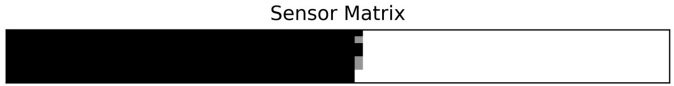


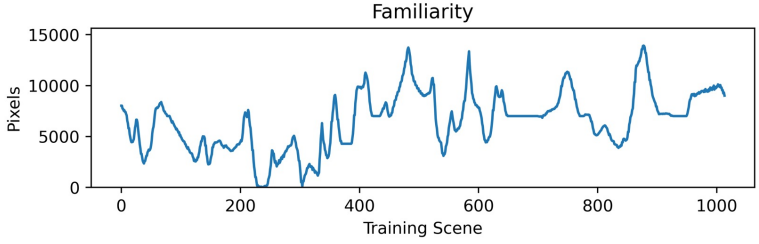
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

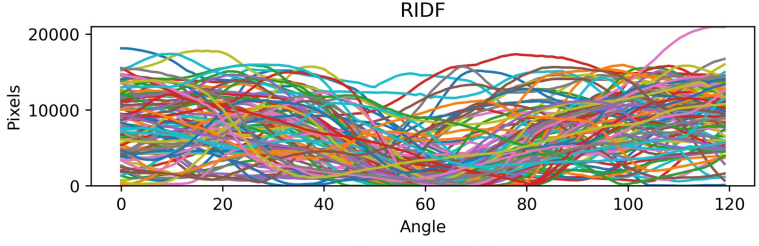
Navigation stats: RMSD error: 1657.41; RMSD/dist: 4.144; TD: 4931; p90: 108; p50: 46; complete: 0

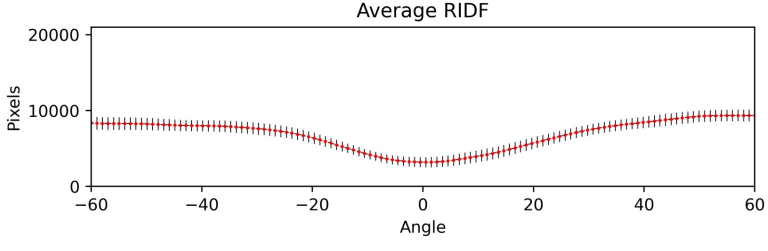
0%







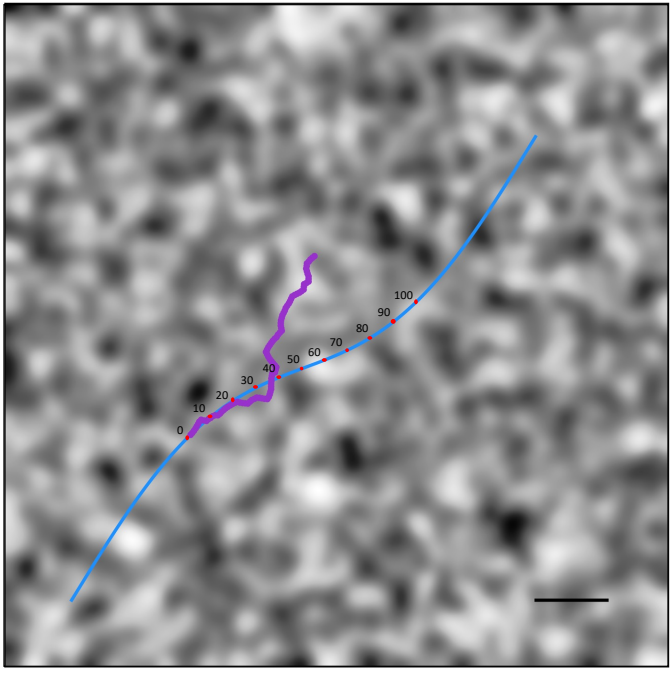


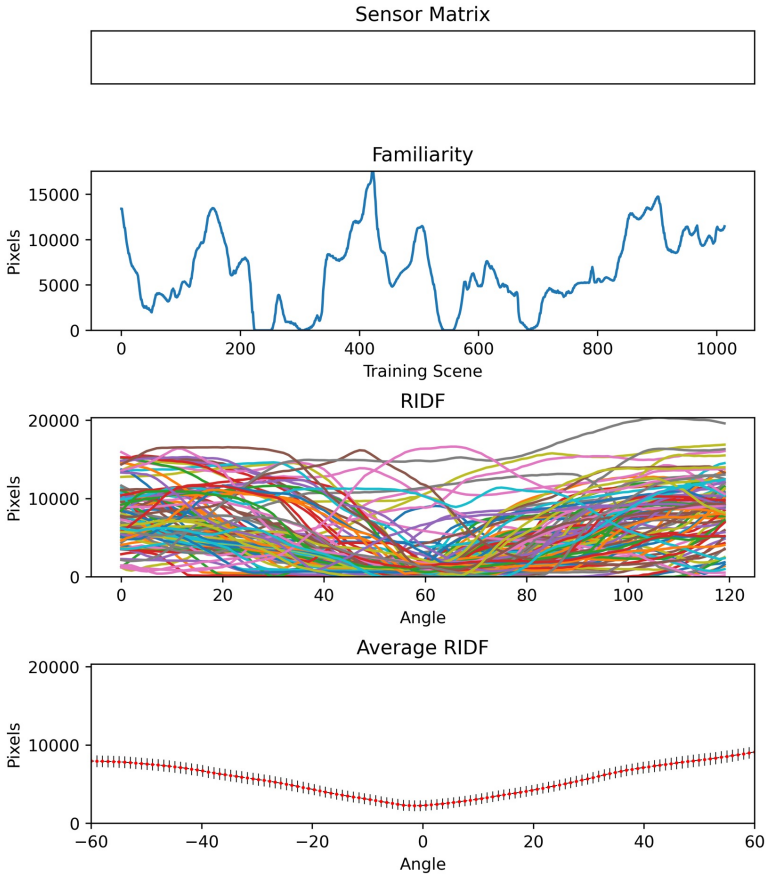


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2833.93; RMSD/dist: 7.085; TD: 3413; p90: 40; p50: 26; complete: 0

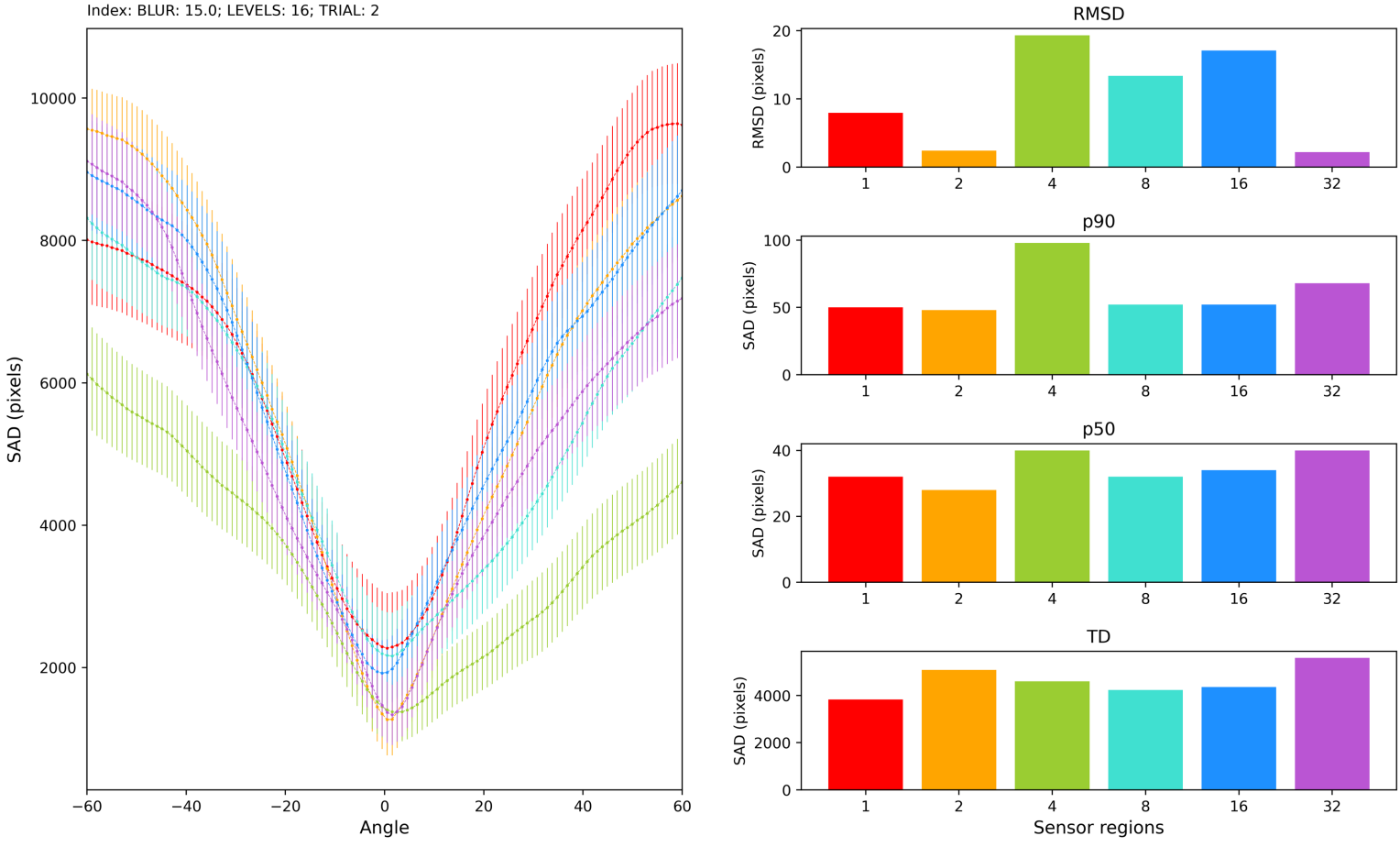
0%



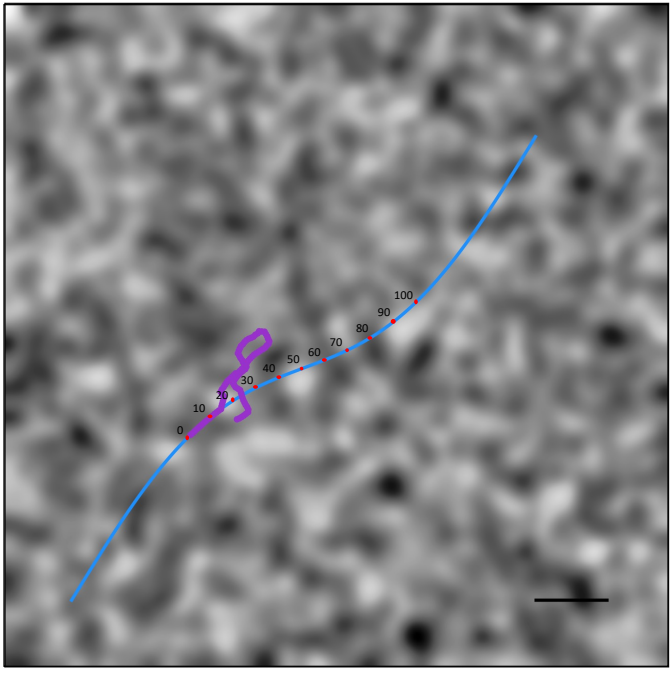


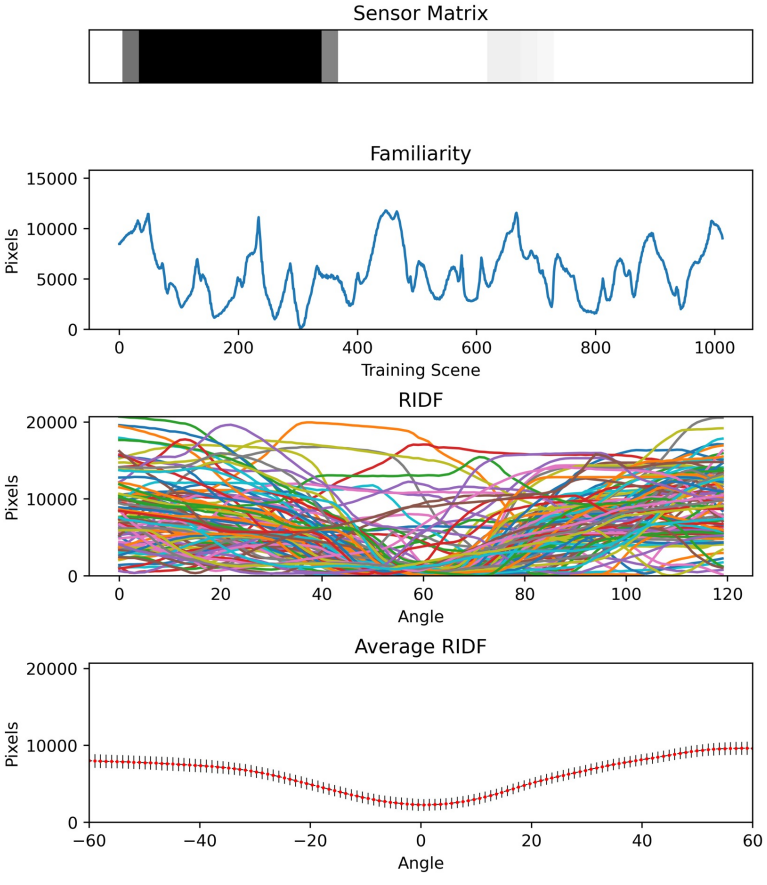
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4942.70; RMSD/dist: 12.357; TD: 4639; p90: 76; p50: 44; complete: 0


Index: BLUR: 15.0; LEVELS: 16; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

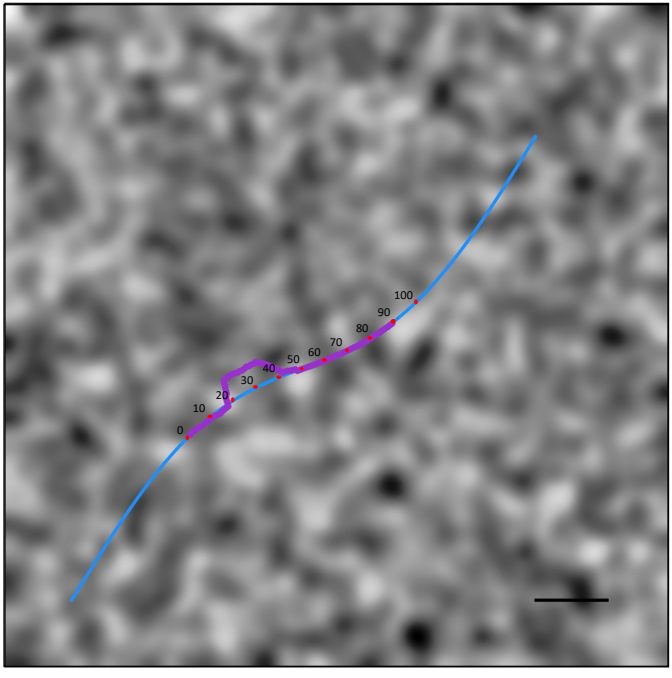


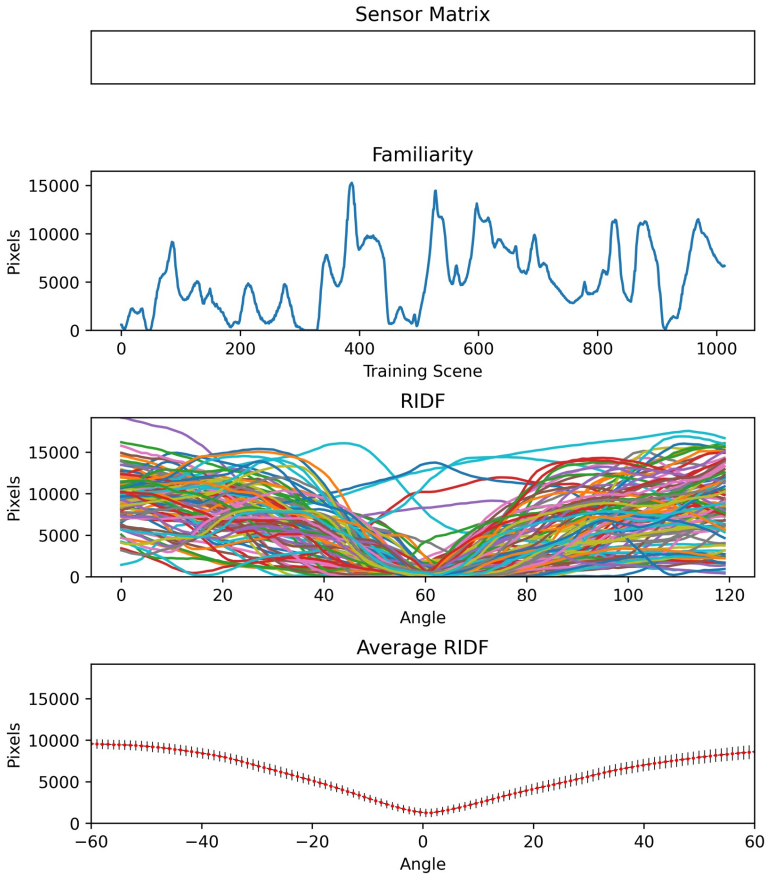


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 3181.54; RMSD/dist: 7.954; TD: 3831; p90: 50; p50: 32; complete: 0

50%

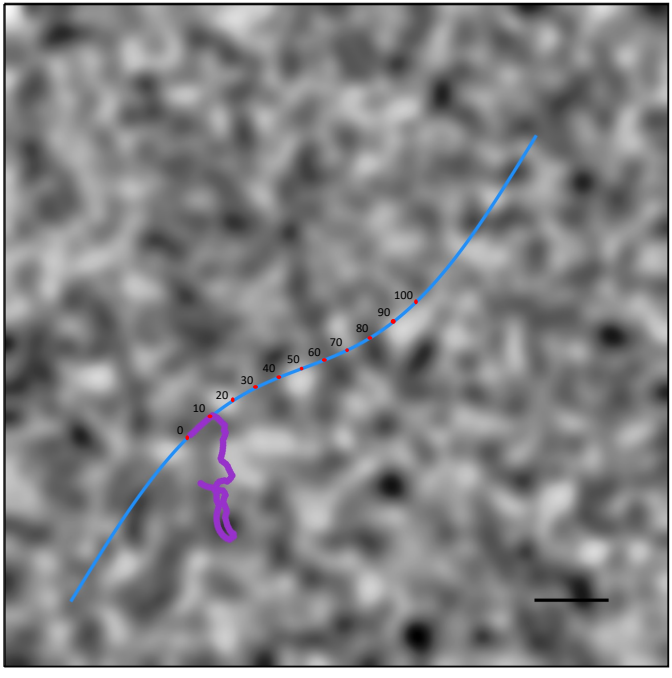


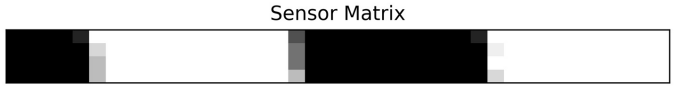


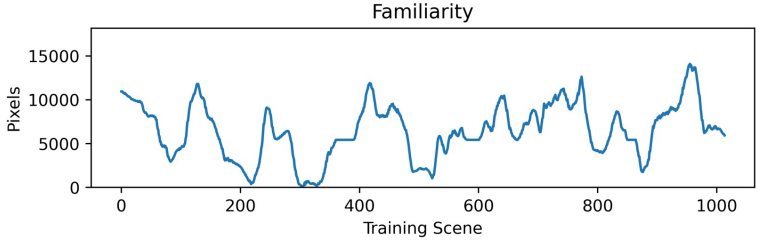
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

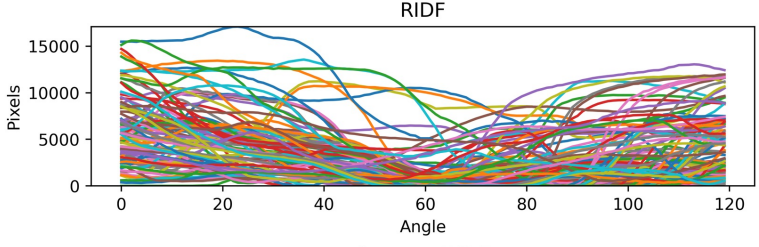
Navigation stats: RMSD error: 960.06; RMSD/dist: 2.400; TD: 5087; p90: 48; p50: 28; complete: 0

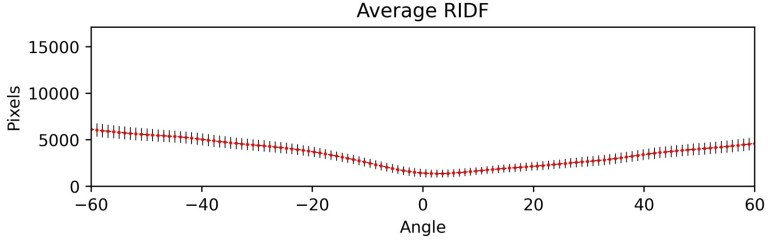
10%







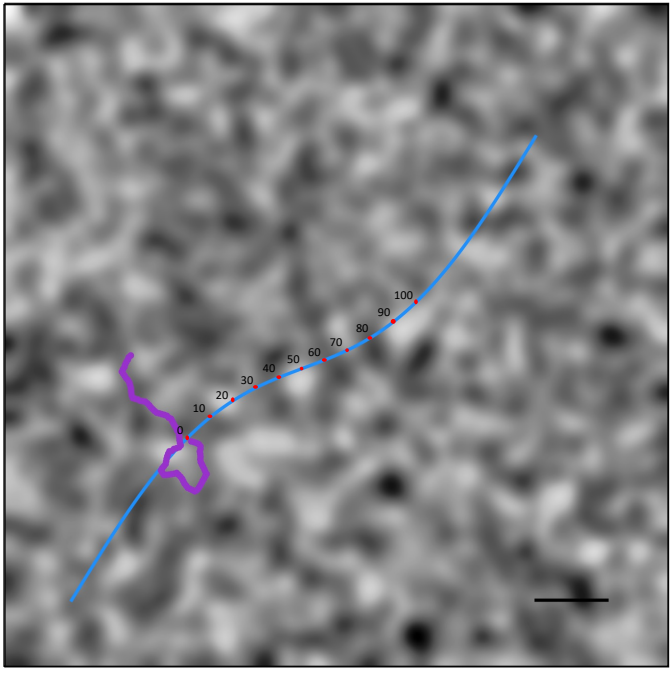


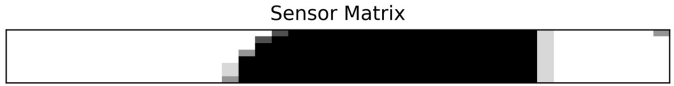


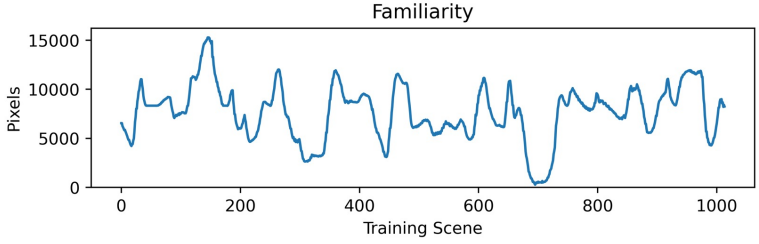
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

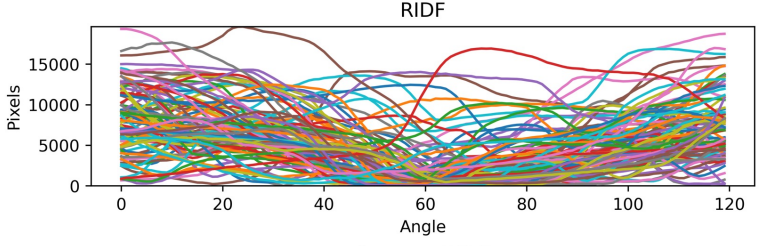
Navigation stats: RMSD error: 7730.88; RMSD/dist: 19.327; TD: 4600; p90: 98; p50: 40; complete: 0

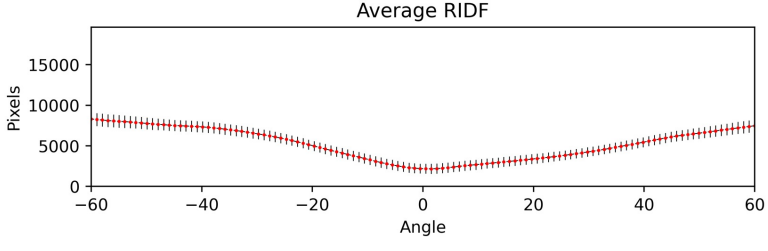
0%







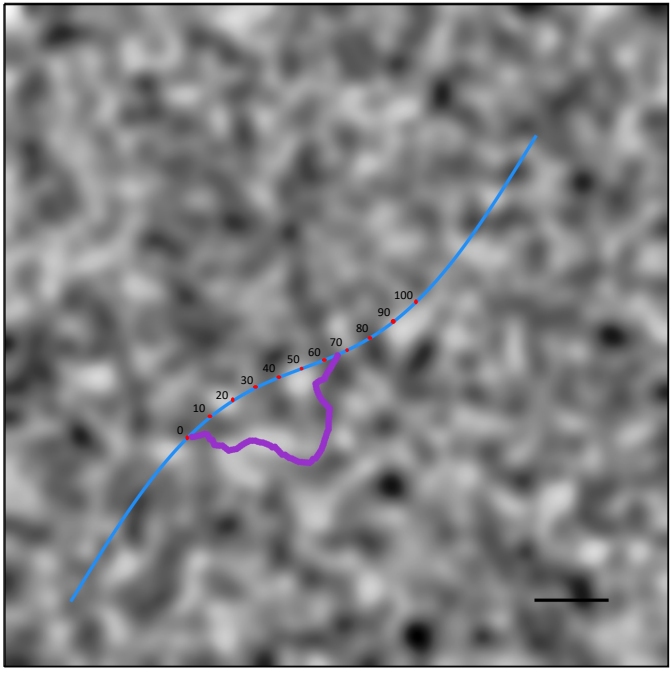


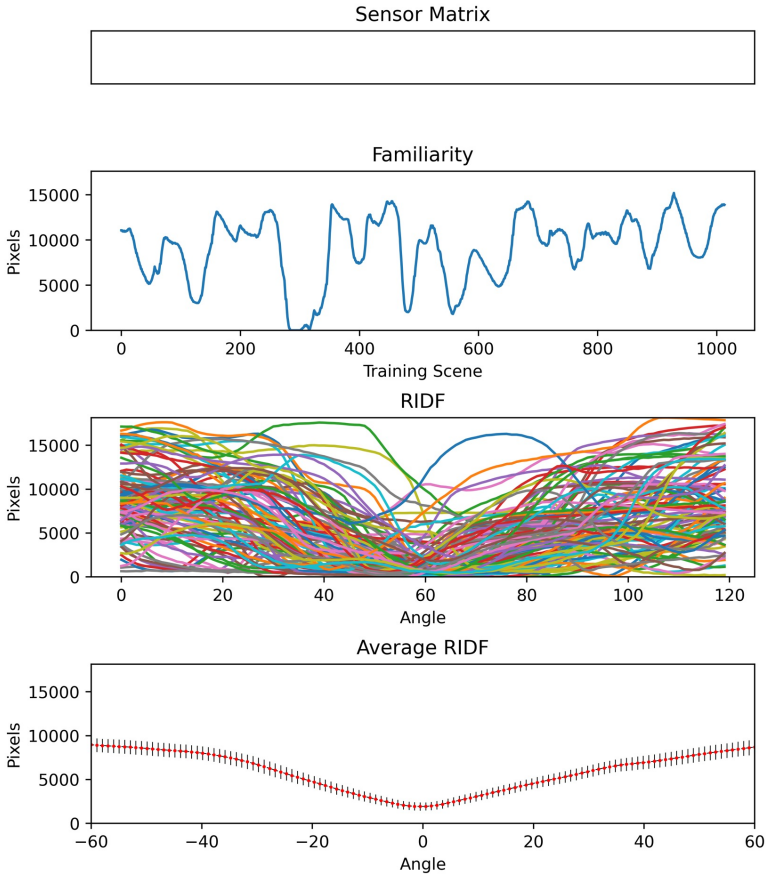


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 5348.17; RMSD/dist: 13.370; TD: 4233; p90: 52; p50: 32; complete: 0

0%

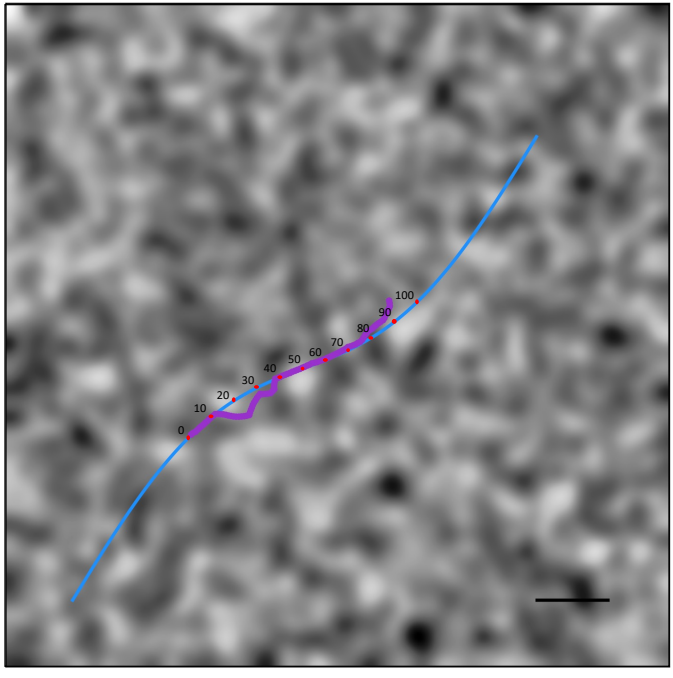


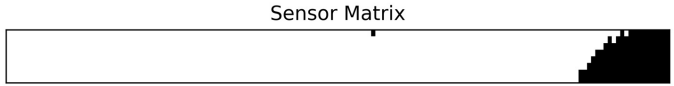


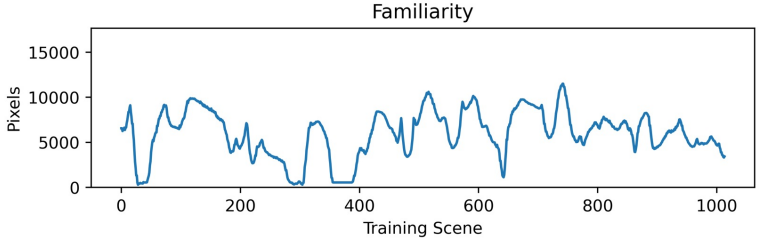
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

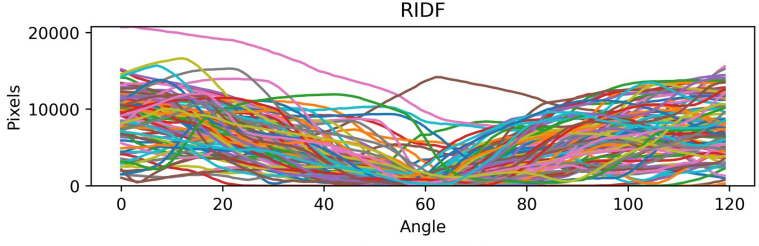
Navigation stats: RMSD error: 6828.02; RMSD/dist: 17.070; TD: 4358; p90: 52; p50: 34; complete: 0

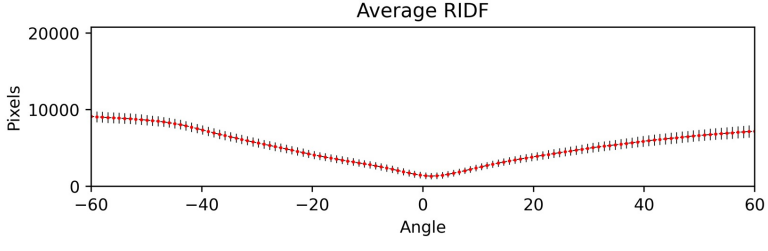
40%





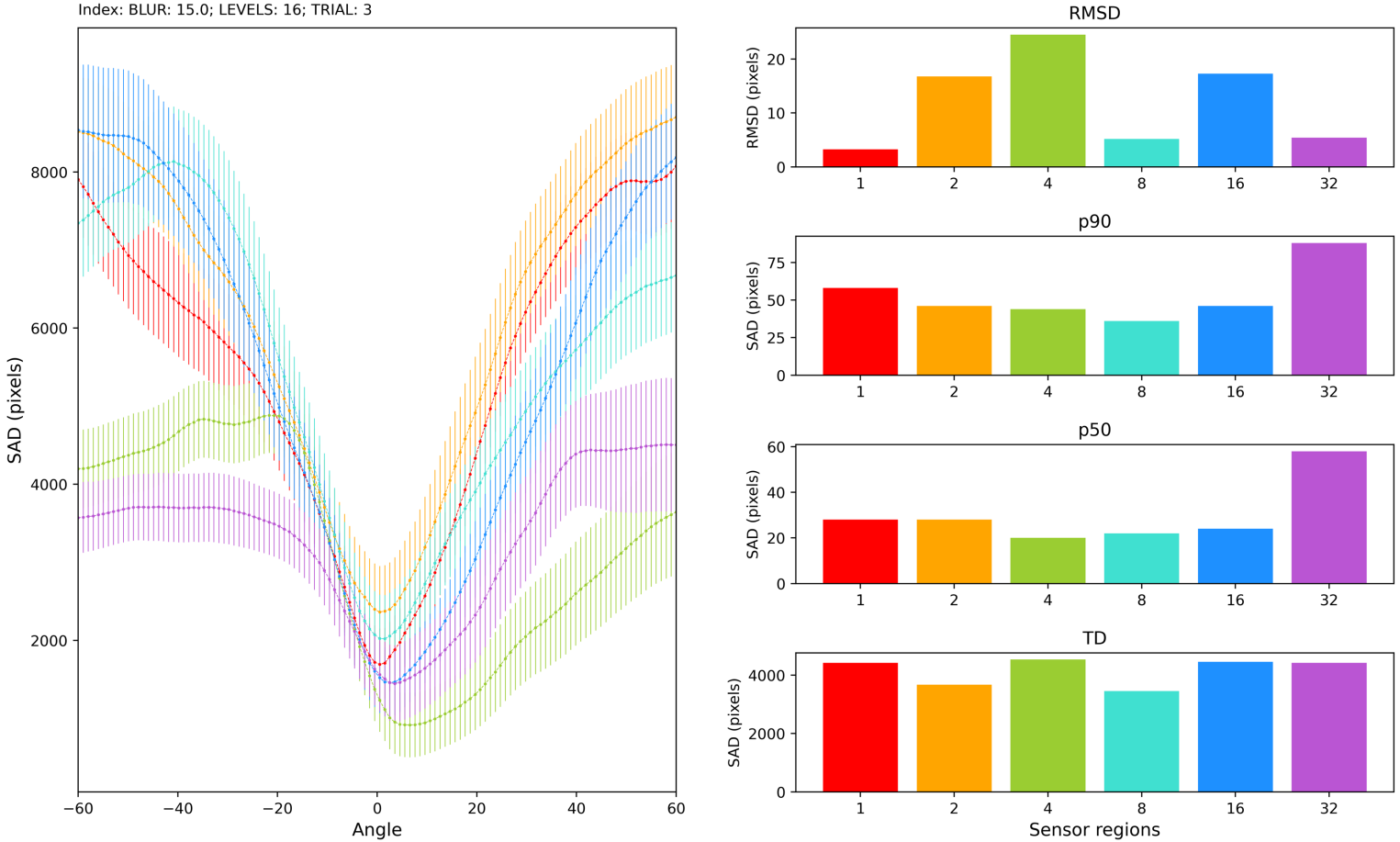




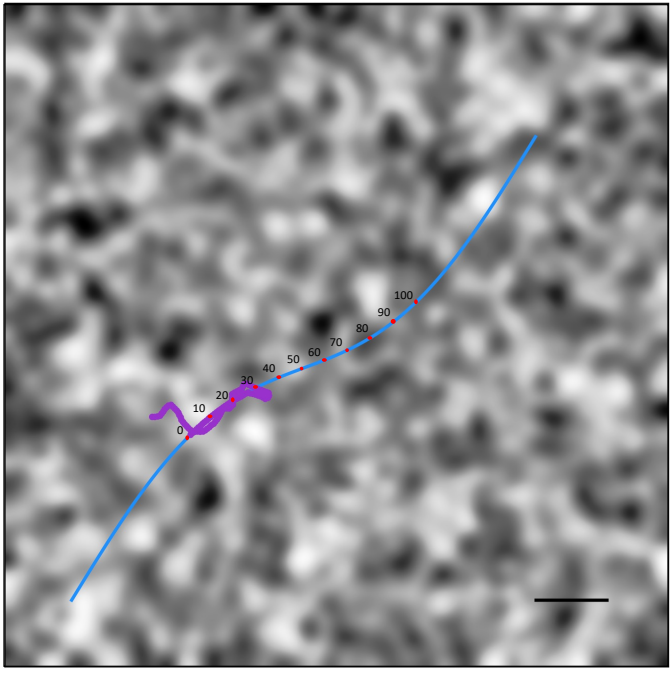


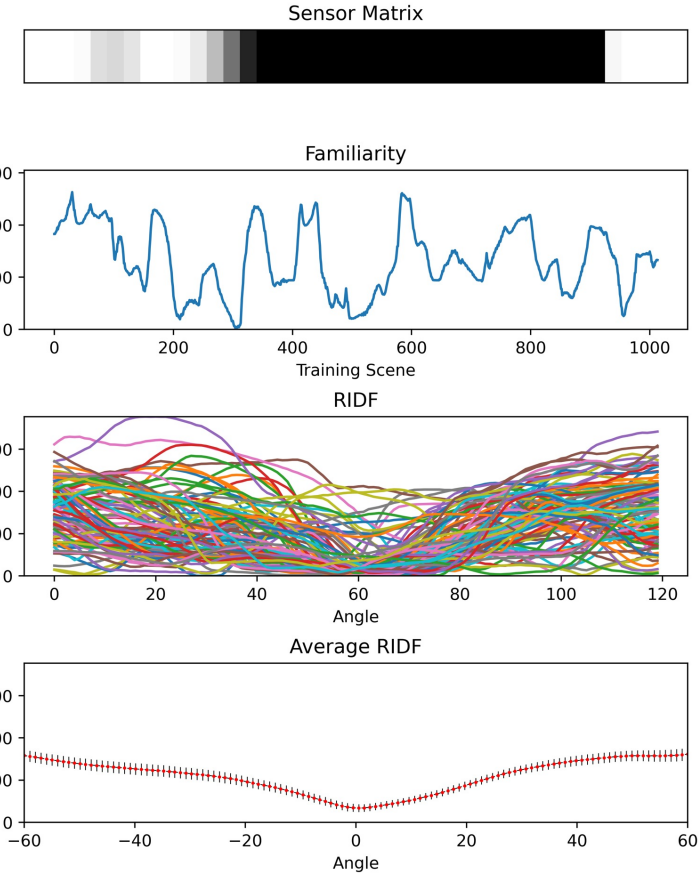
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 881.75; RMSD/dist: 2.204; TD: 5590; p90: 68; p50: 40; complete: 0


Index: BLUR: 15.0; LEVELS: 16; TRIAL: 3
SAD (pixels)
8000
6000
4000
2000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
75
50
25
0
p50
60
40
20
TD
4000
2000
Sensor regions

20%

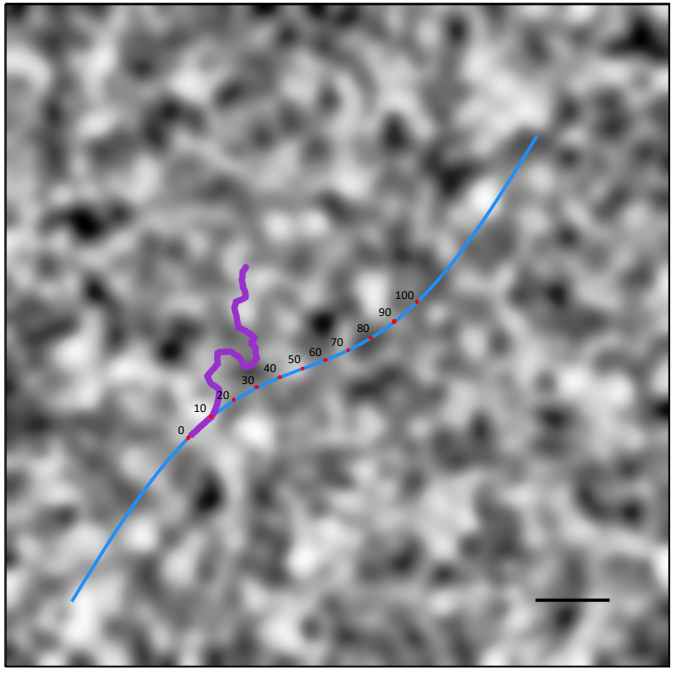


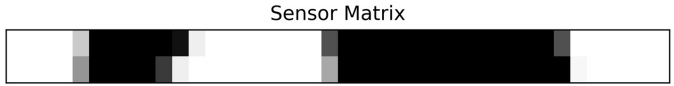


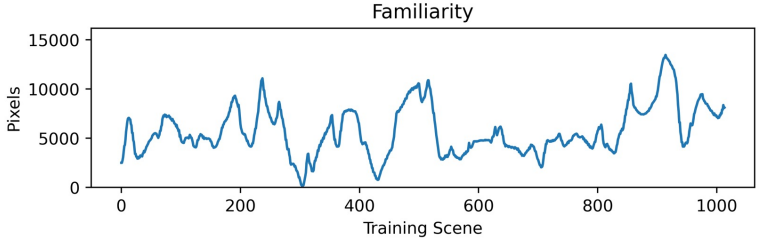
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

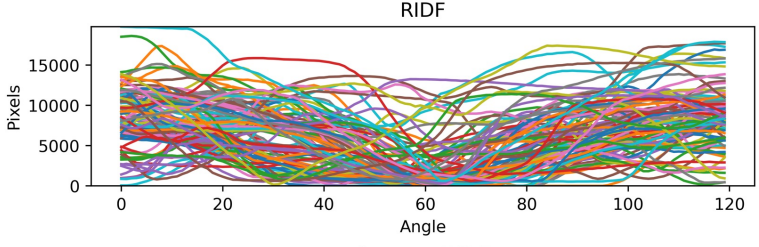
Navigation stats: RMSD error: 1299.24; RMSD/dist: 3.248; TD: 4419; p90: 58; p50: 28; complete: 0

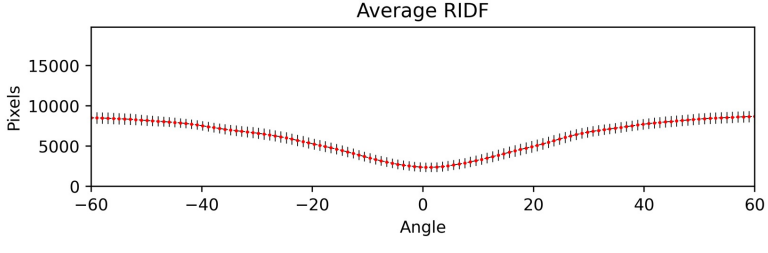
10%







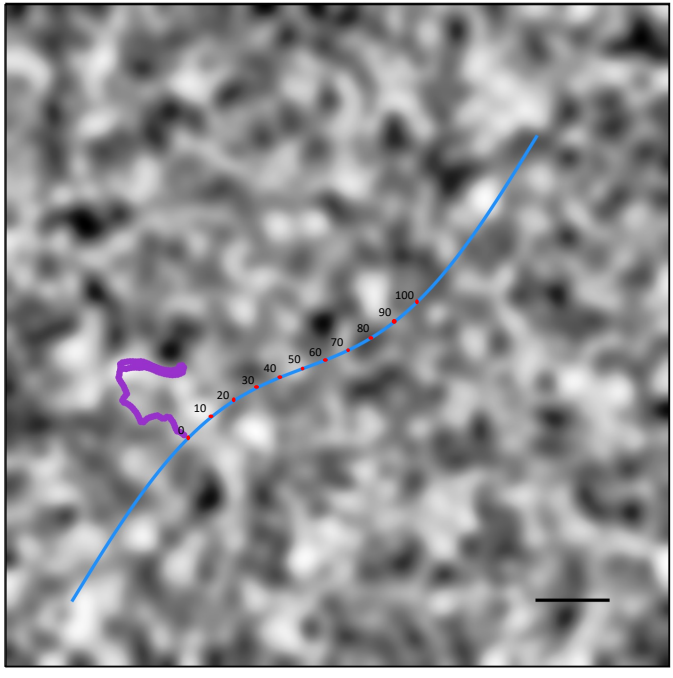


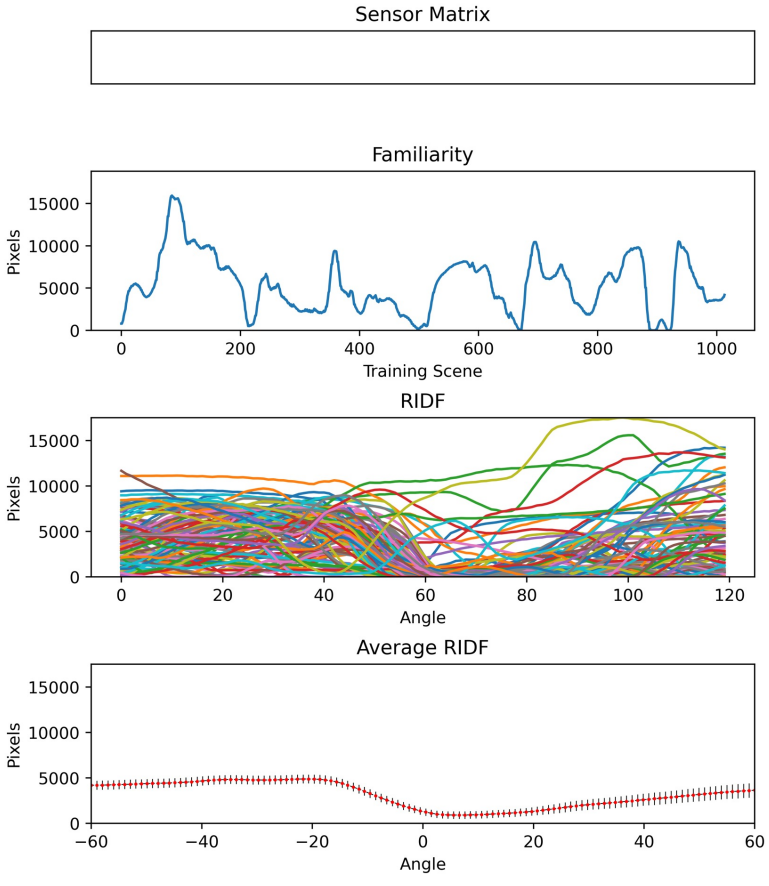


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 6707.10; RMSD/dist: 16.768; TD: 3672; p90: 46; p50: 28; complete: 0

0%

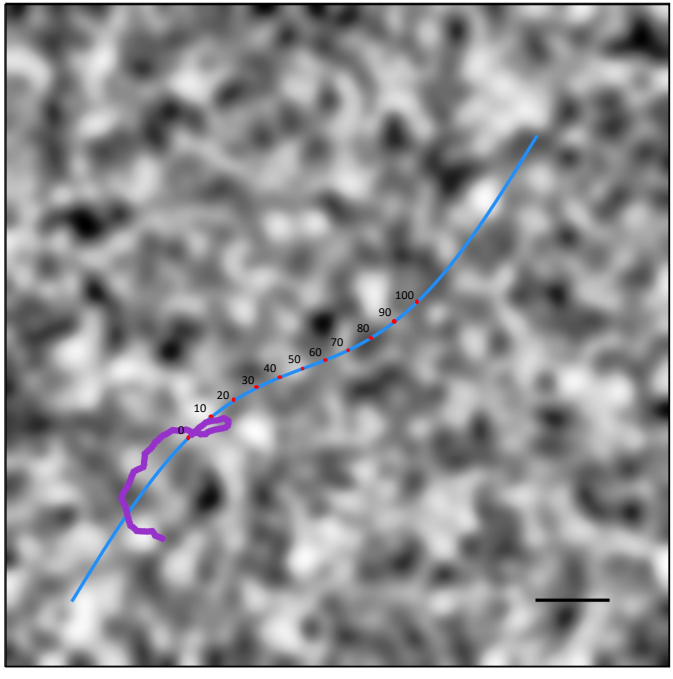


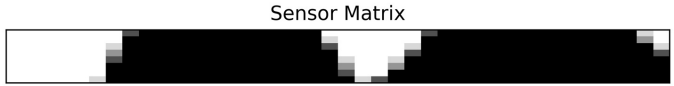


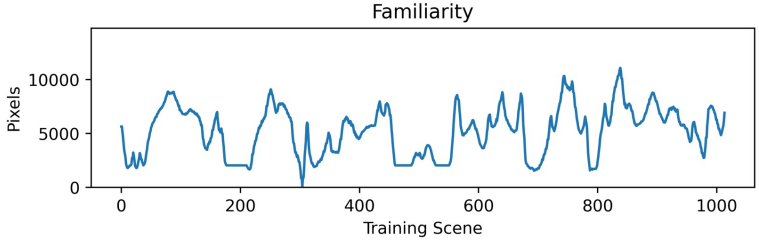
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

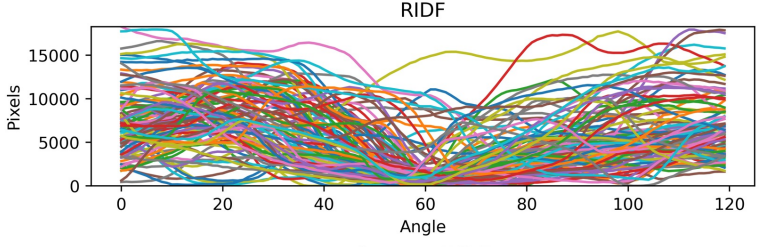
Navigation stats: RMSD error: 9814.95; RMSD/dist: 24.537; TD: 4534; p90: 44; p50: 20; complete: 0

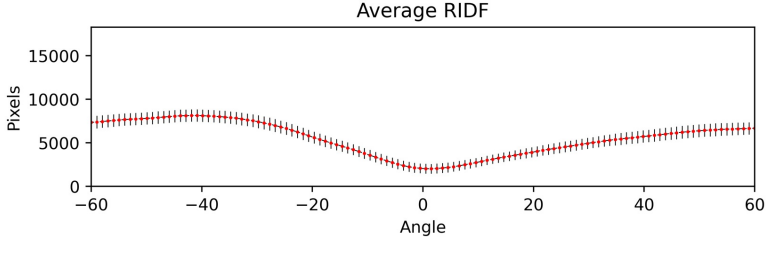
0%







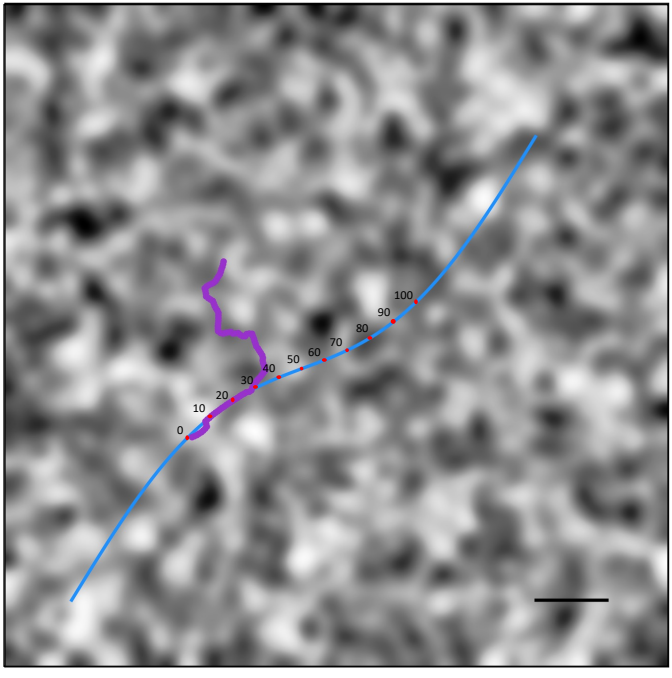


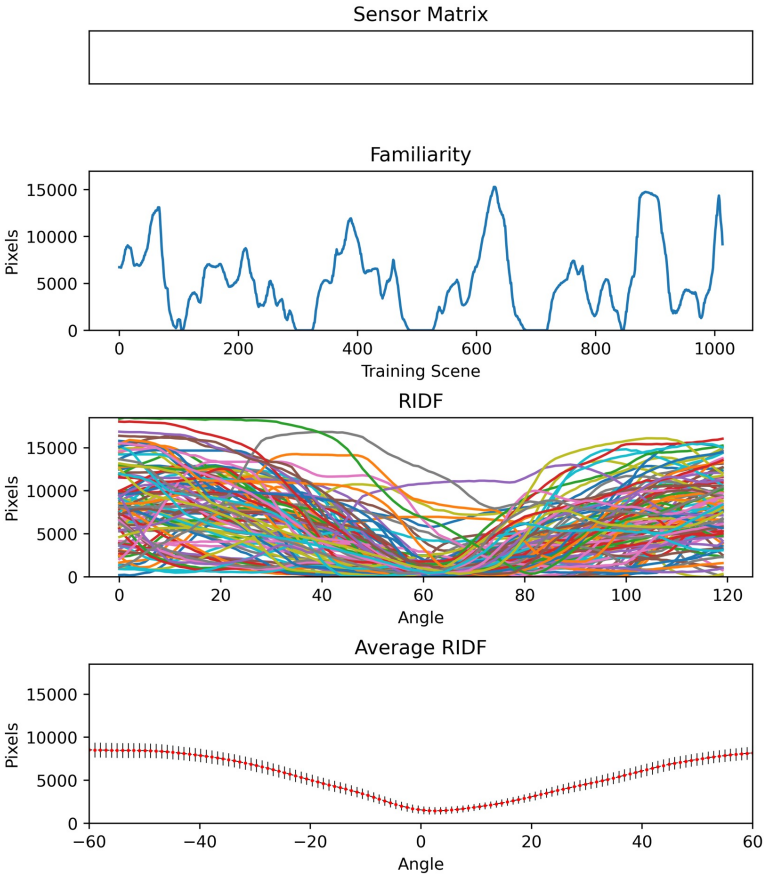


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2065.88; RMSD/dist: 5.165; TD: 3454; p90: 36; p50: 22; complete: 0

20%

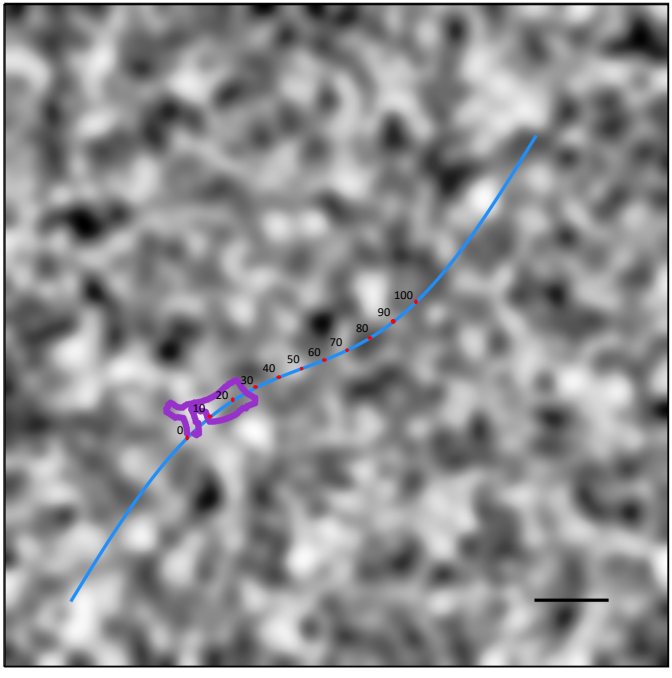


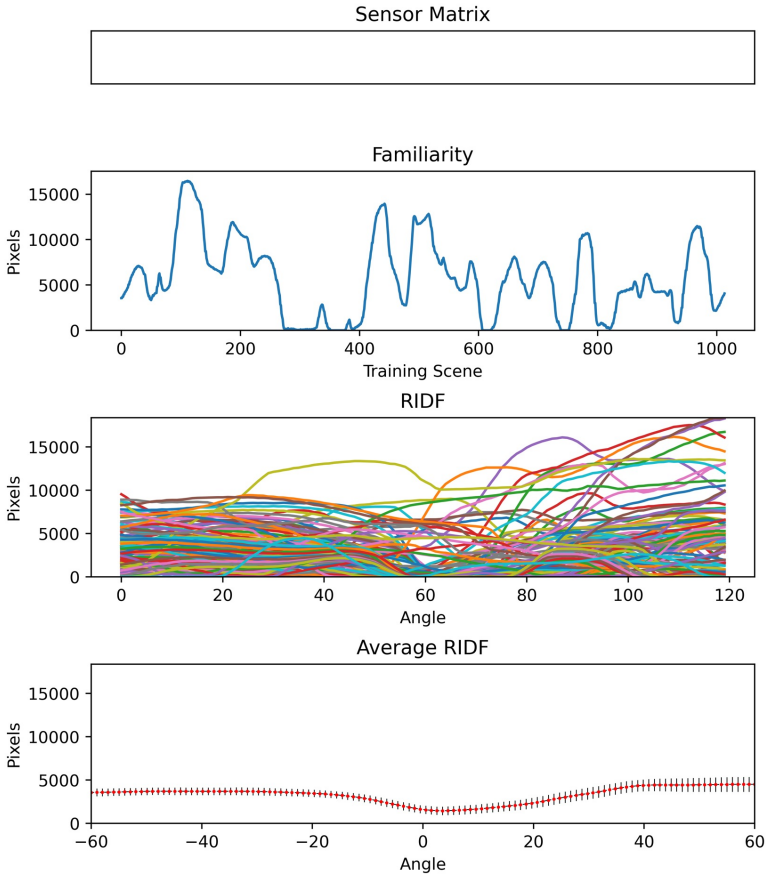


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 6912.11; RMSD/dist: 17.280; TD: 4456; p90: 46; p50: 24; complete: 0

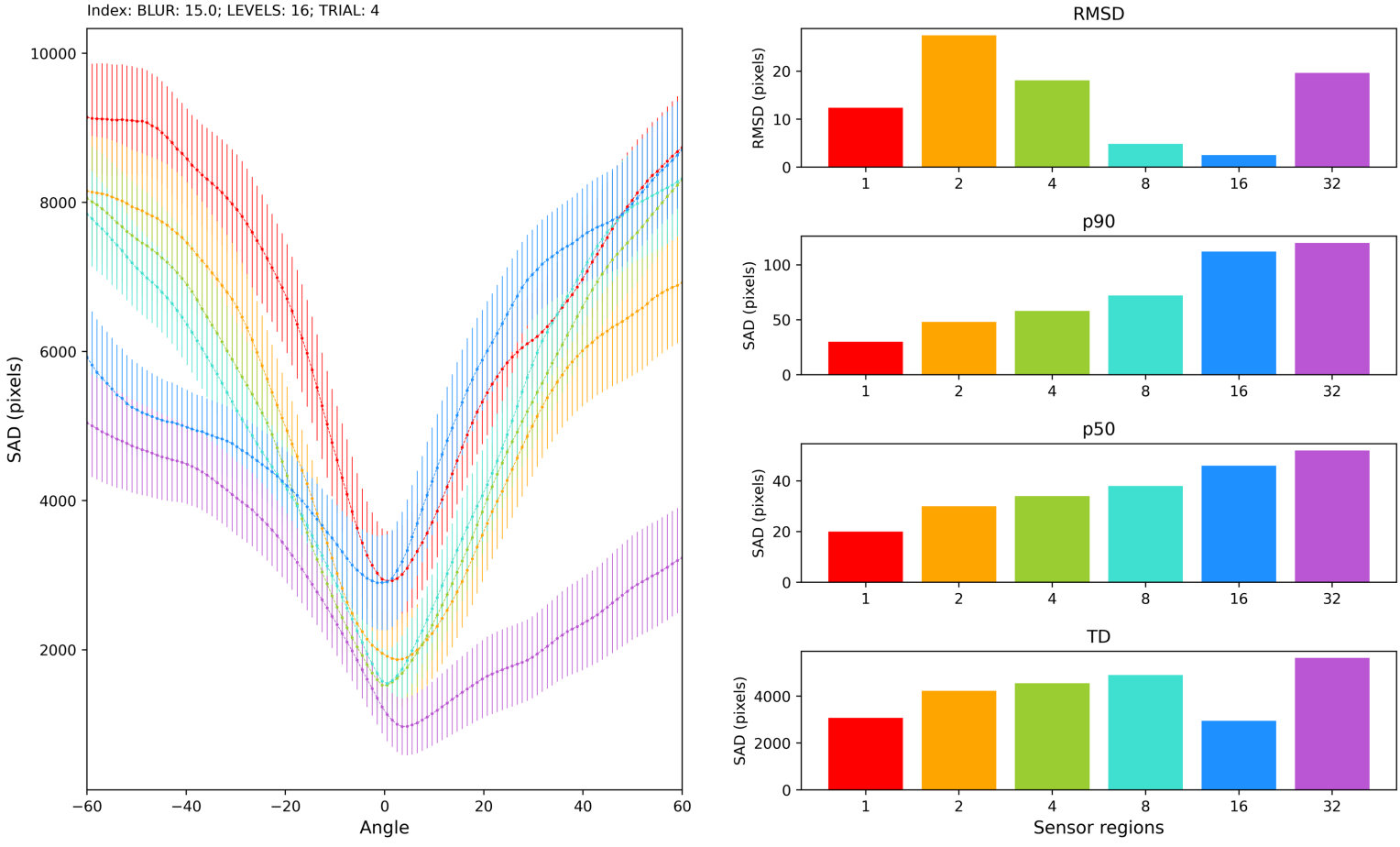
0%



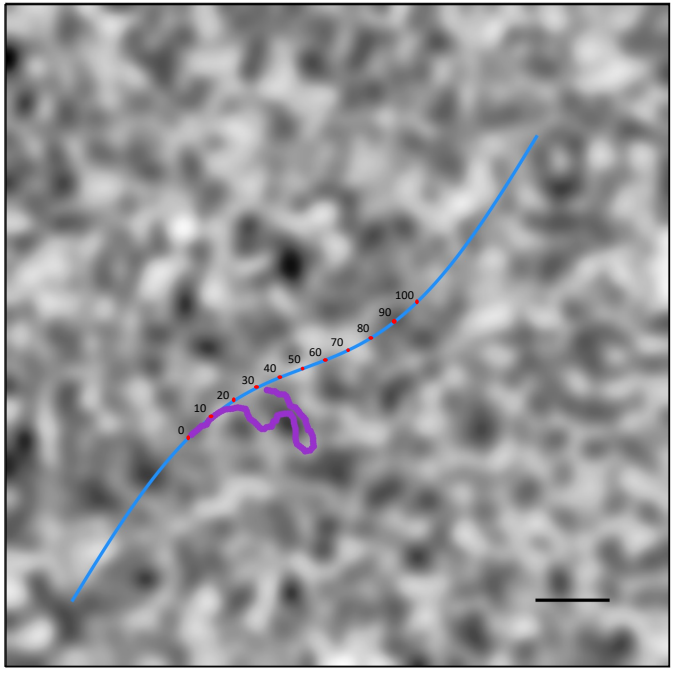


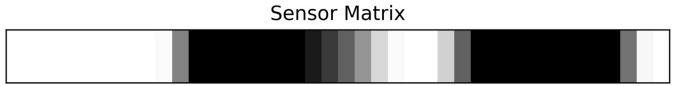
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

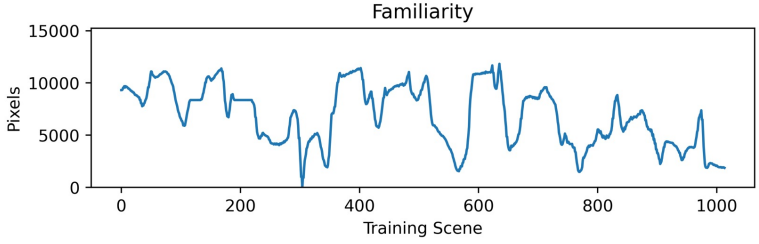
Navigation stats: RMSD error: 2160.42; RMSD/dist: 5.401; TD: 4420; p90: 88; p50: 58; complete: 0

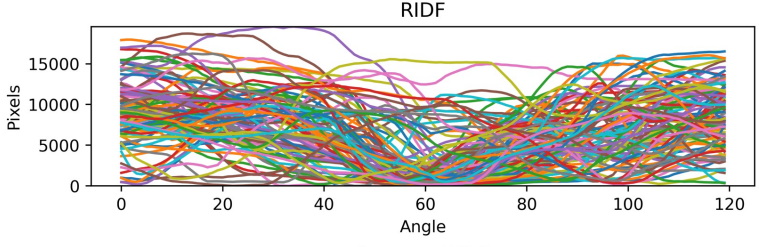

Index: BLUR: 15.0; LEVELS: 16; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

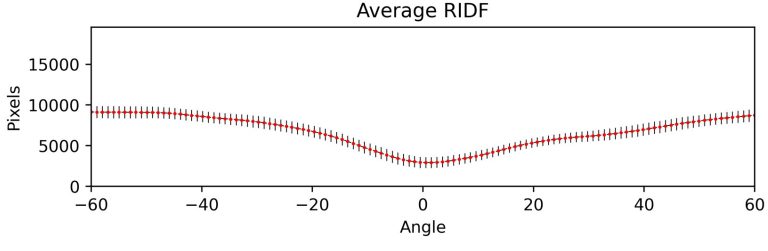
10%







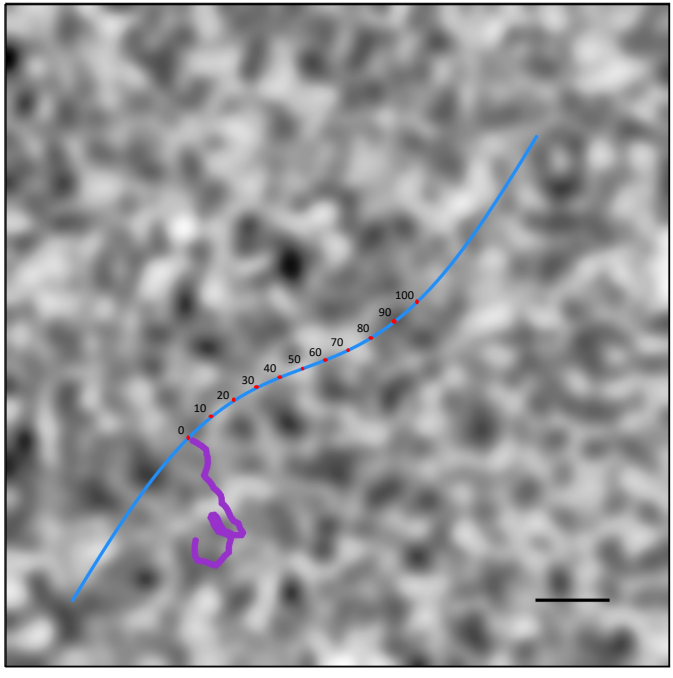


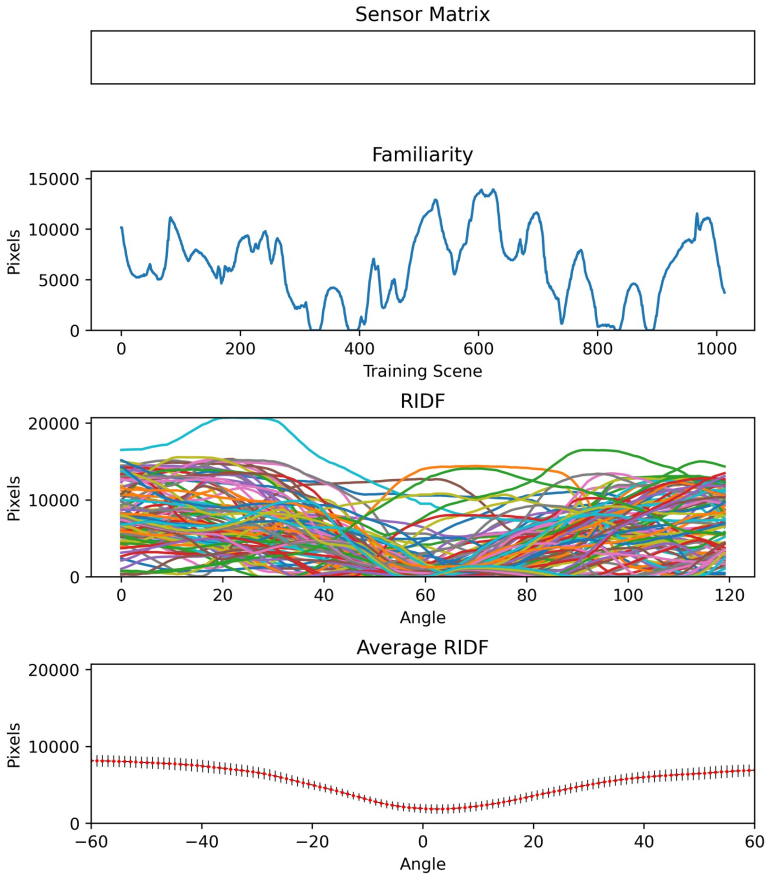


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4953.09; RMSD/dist: 12.383; TD: 3075; p90: 30; p50: 20; complete: 0

0%

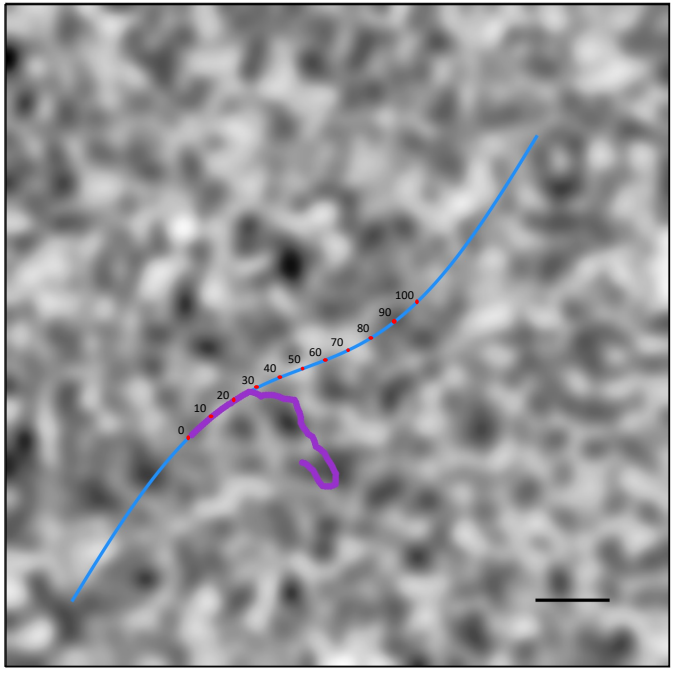


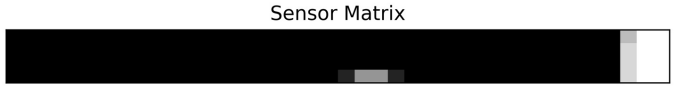


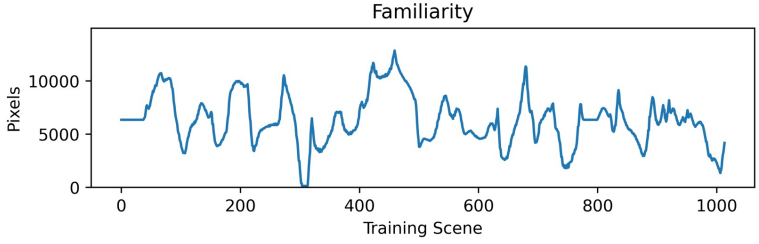
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

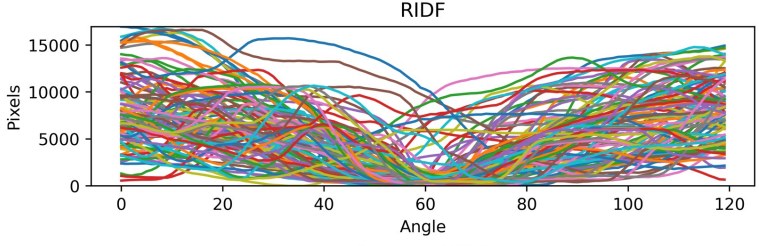
Navigation stats: RMSD error: 10995.83; RMSD/dist: 27.490; TD: 4228; p90: 48; p50: 30; complete: 0

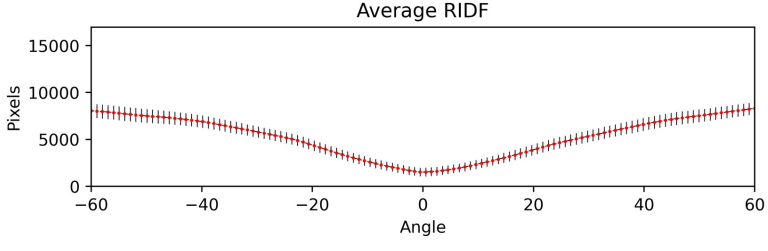
20%







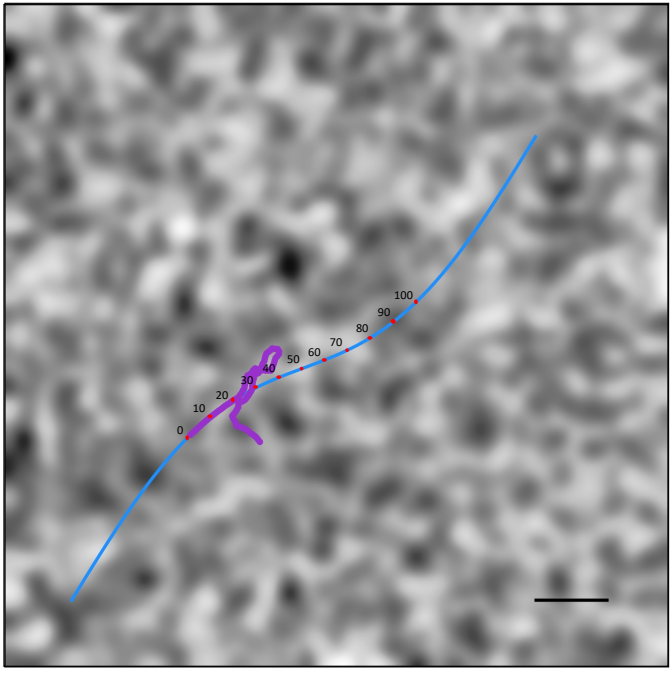


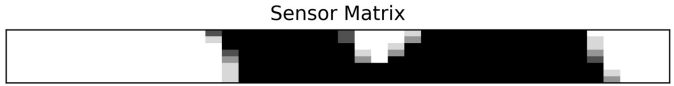


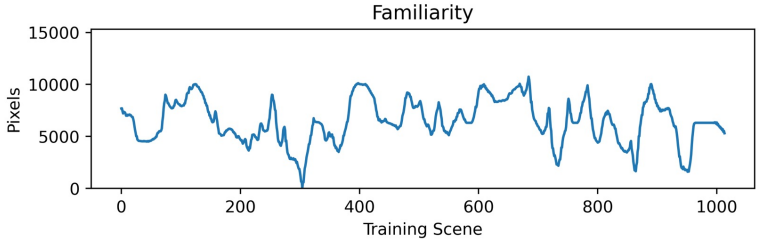
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

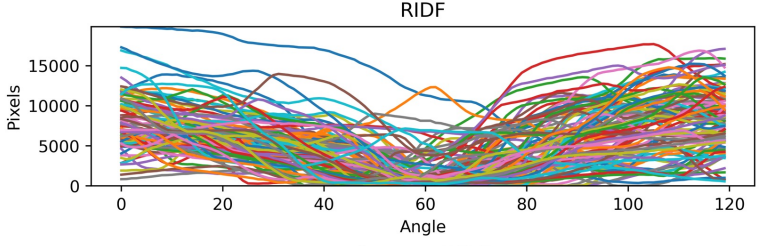
Navigation stats: RMSD error: 7240.25; RMSD/dist: 18.101; TD: 4553; p90: 58; p50: 34; complete: 0

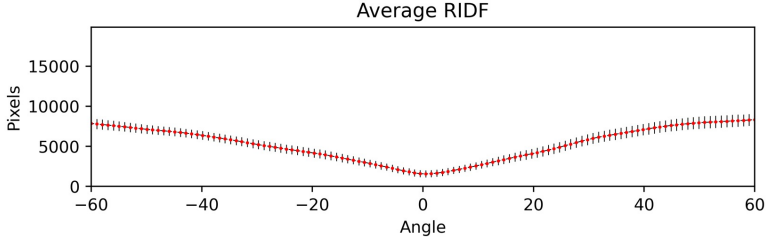
20%







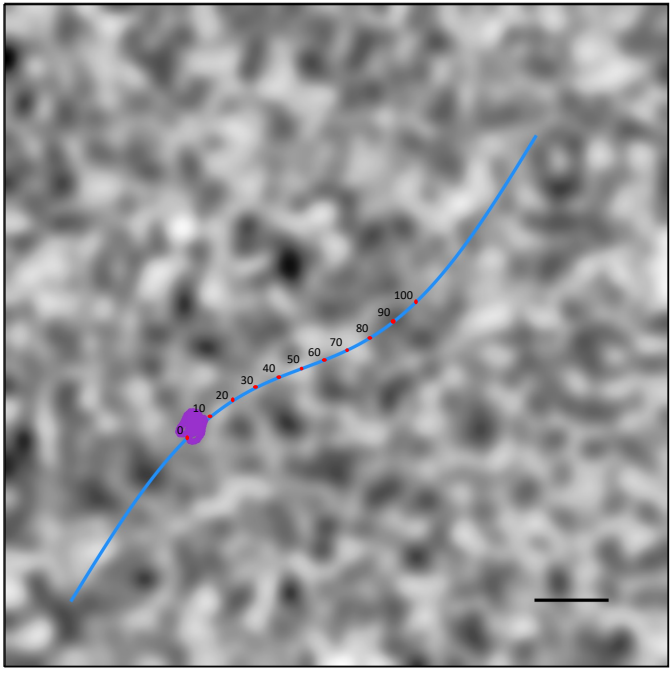


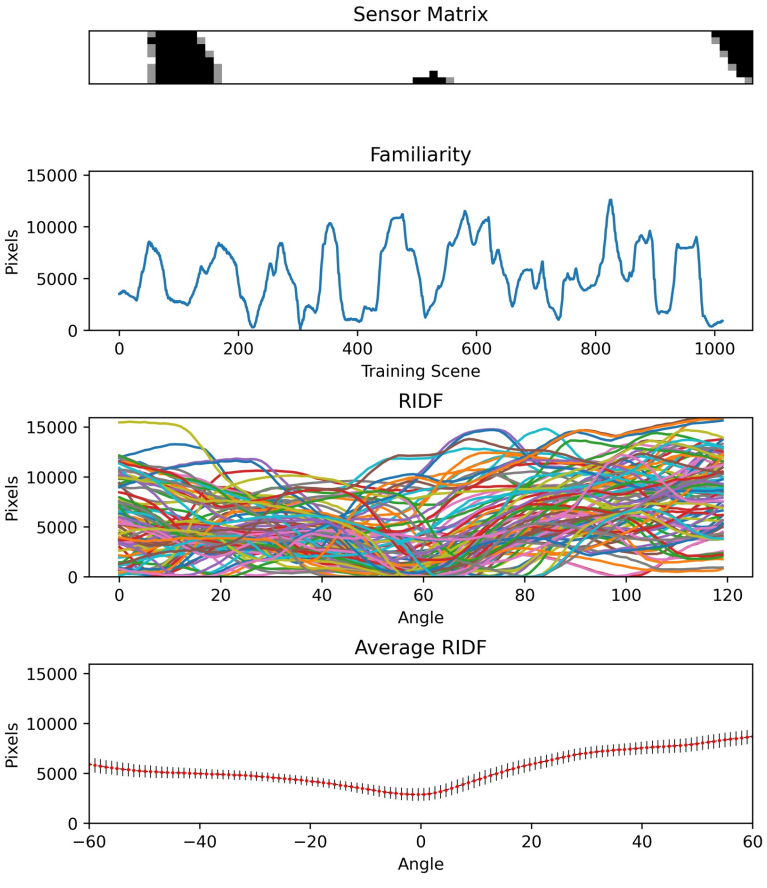


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1929.23; RMSD/dist: 4.823; TD: 4909; p90: 72; p50: 38; complete: 0

0%

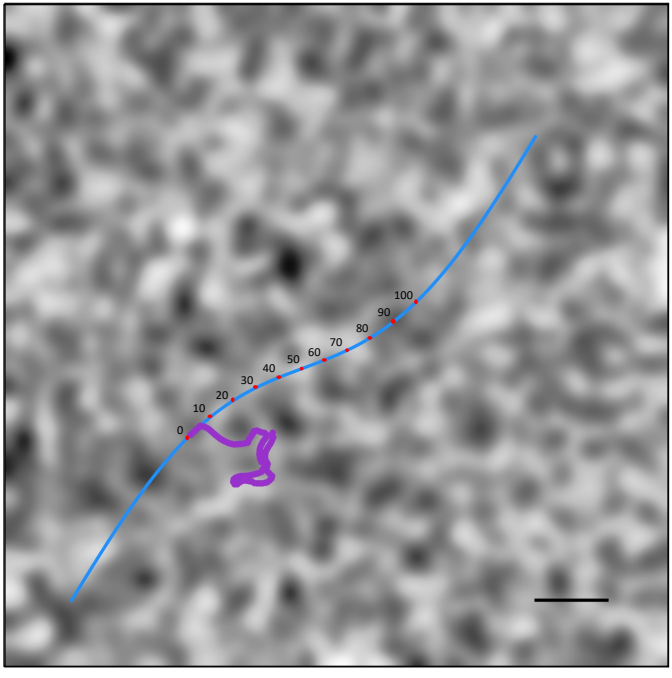


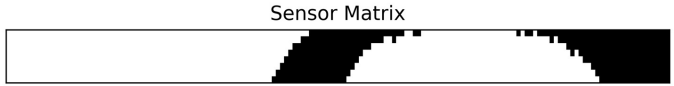


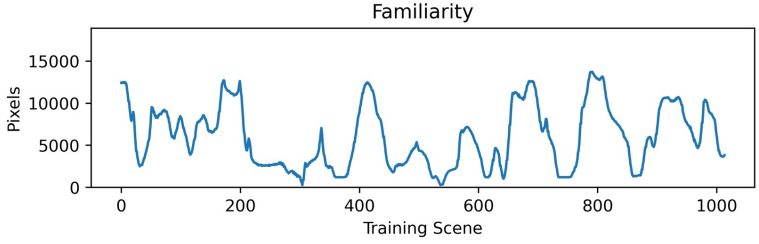
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

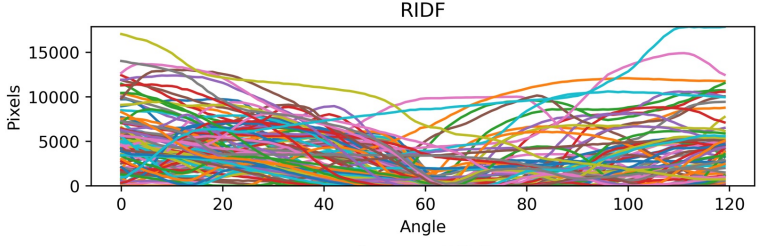
Navigation stats: RMSD error: 994.48; RMSD/dist: 2.486; TD: 2950; p90: 112; p50: 46; complete: 0

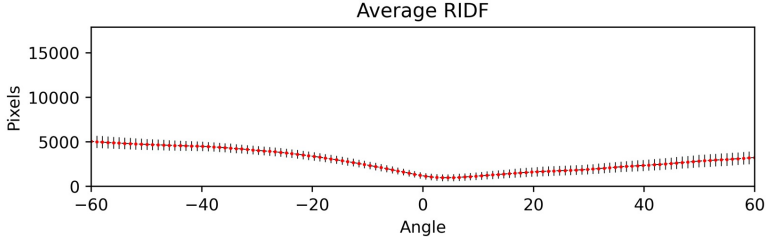
0%





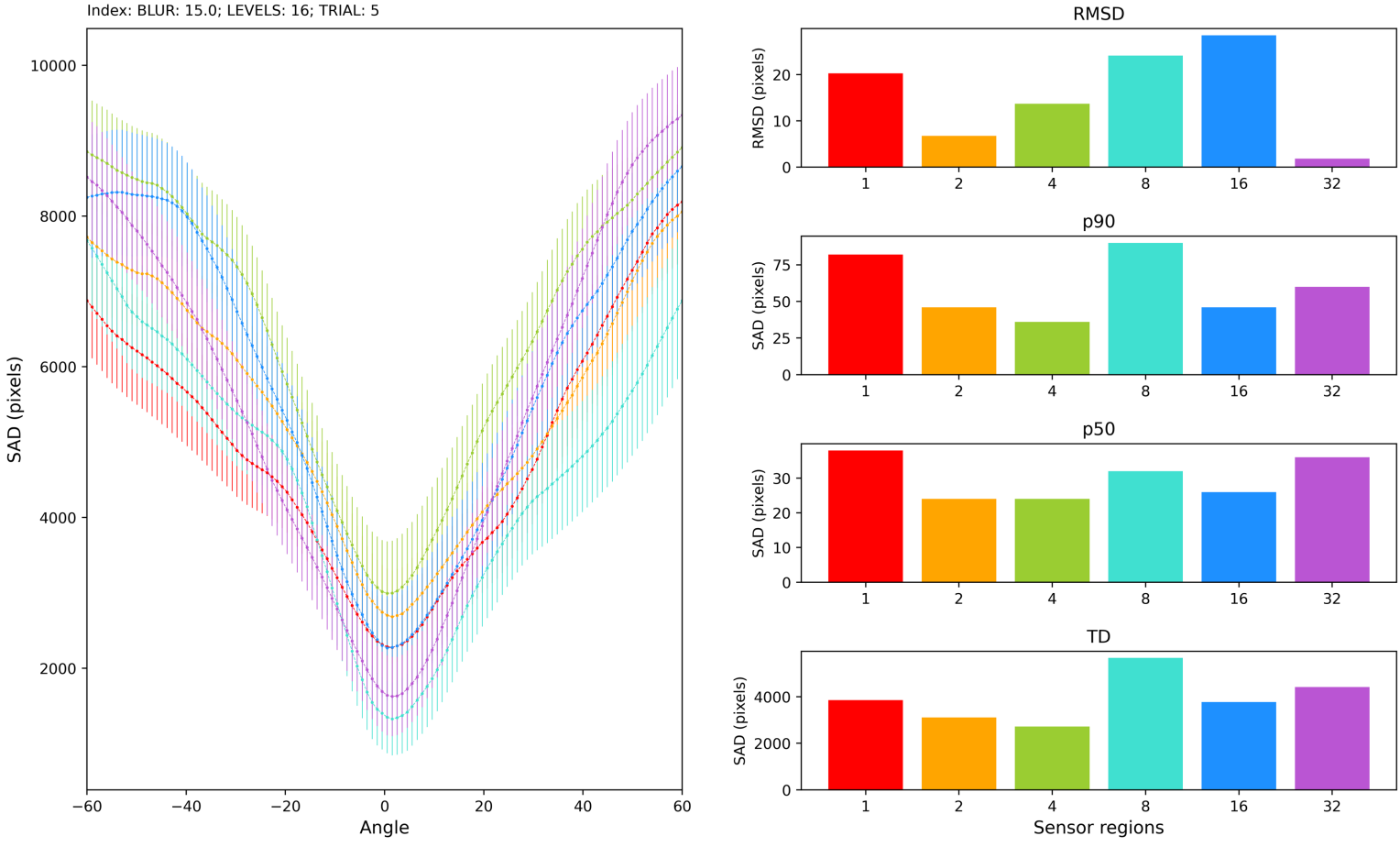




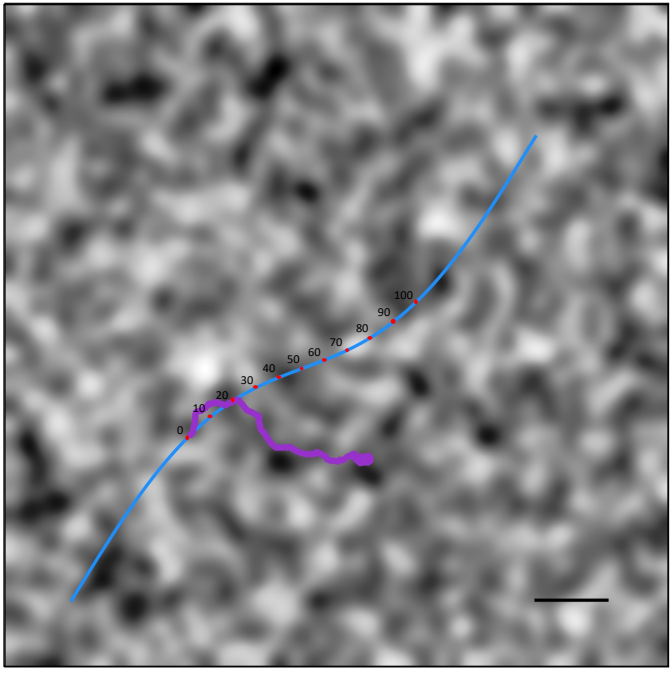


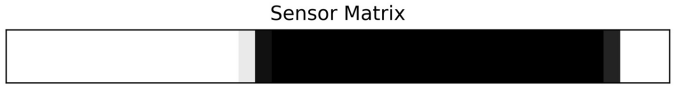
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

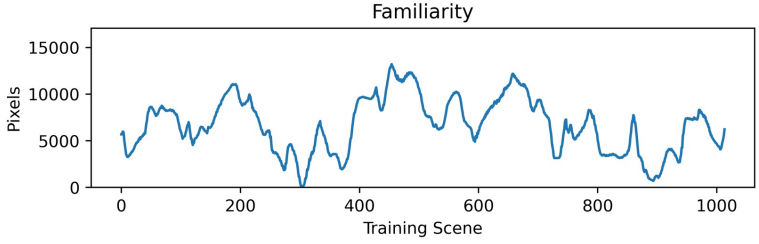
Navigation stats: RMSD error: 7848.63; RMSD/dist: 19.622; TD: 5631; p90: 120; p50: 52; complete: 0

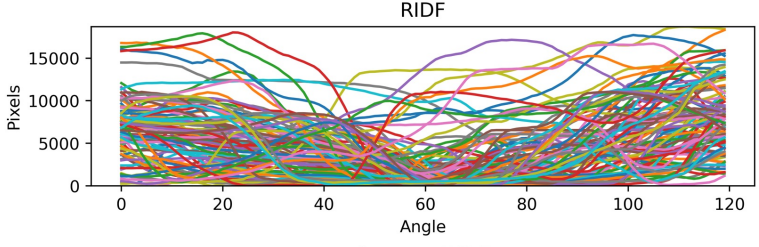

Index: BLUR: 15.0; LEVELS: 16; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

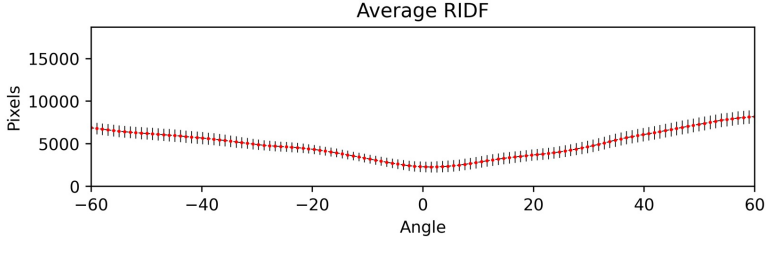
0%







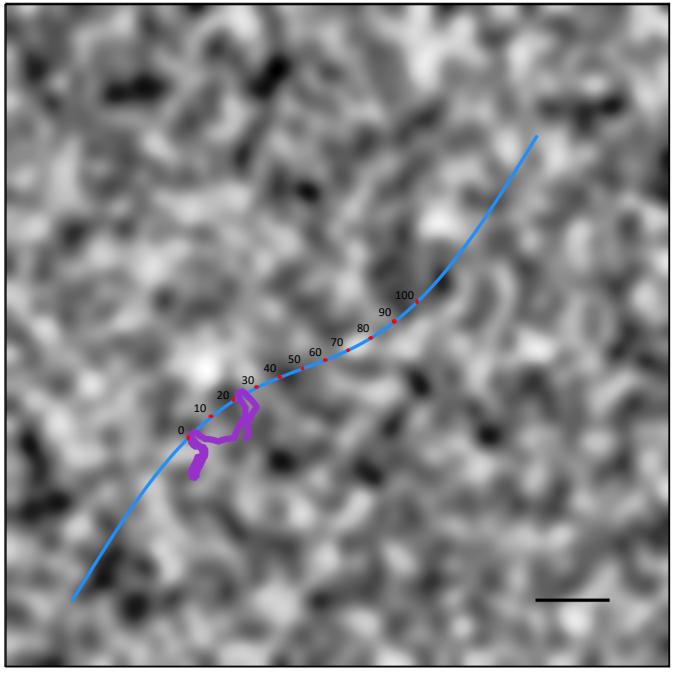


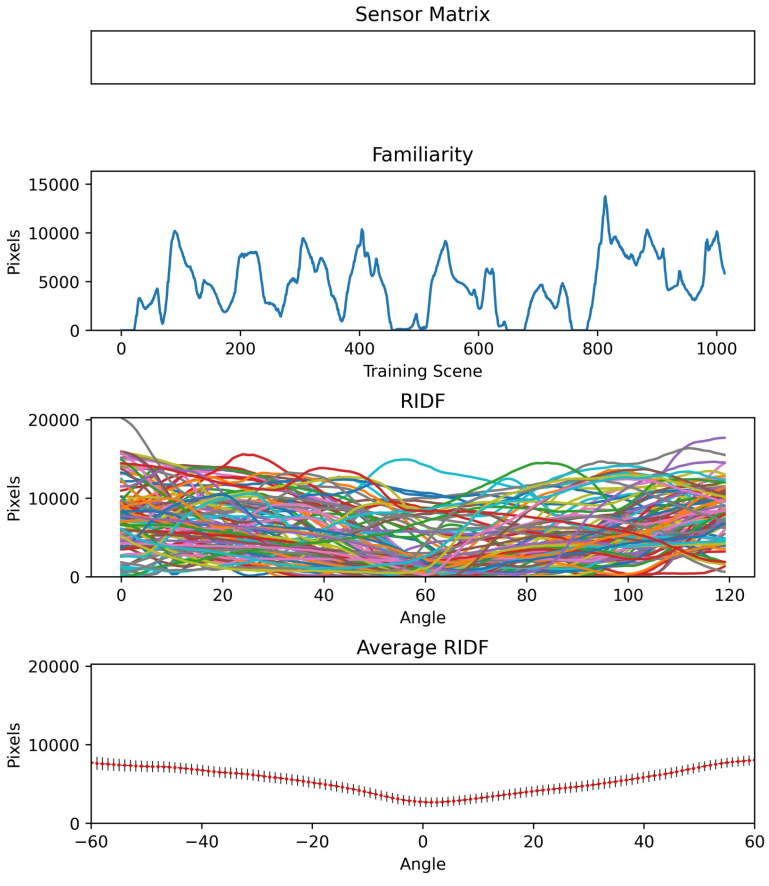


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 8106.43; RMSD/dist: 20.266; TD: 3853; p90: 82; p50: 38; complete: 0

0%

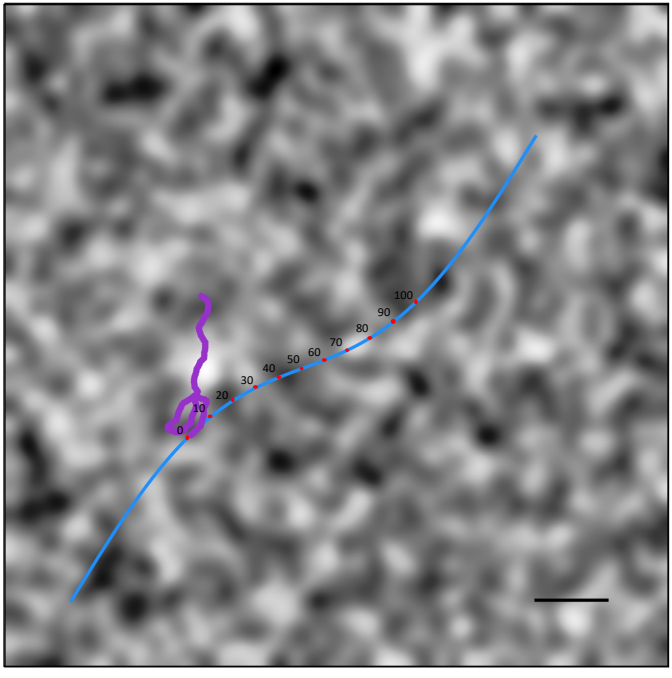


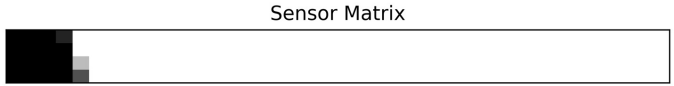


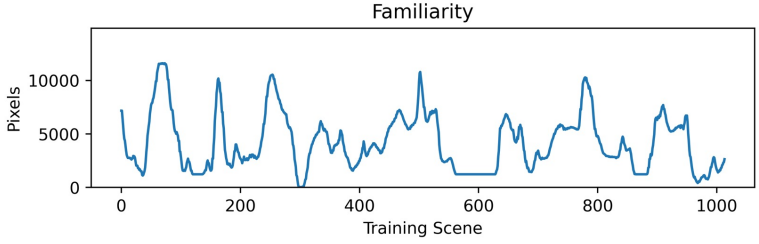
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

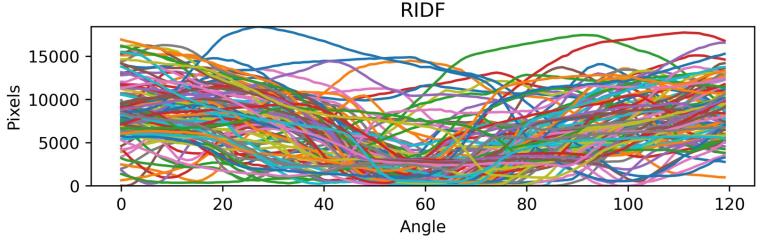
Navigation stats: RMSD error: 2704.73; RMSD/dist: 6.762; TD: 3113; p90: 46; p50: 24; complete: 0

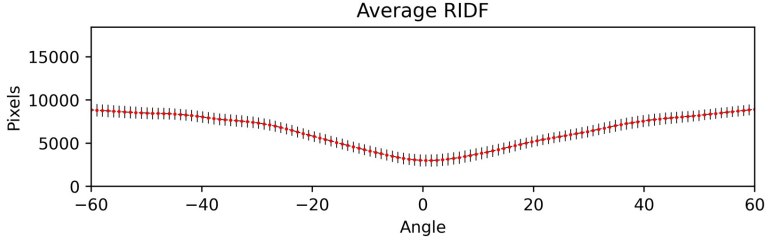
0%







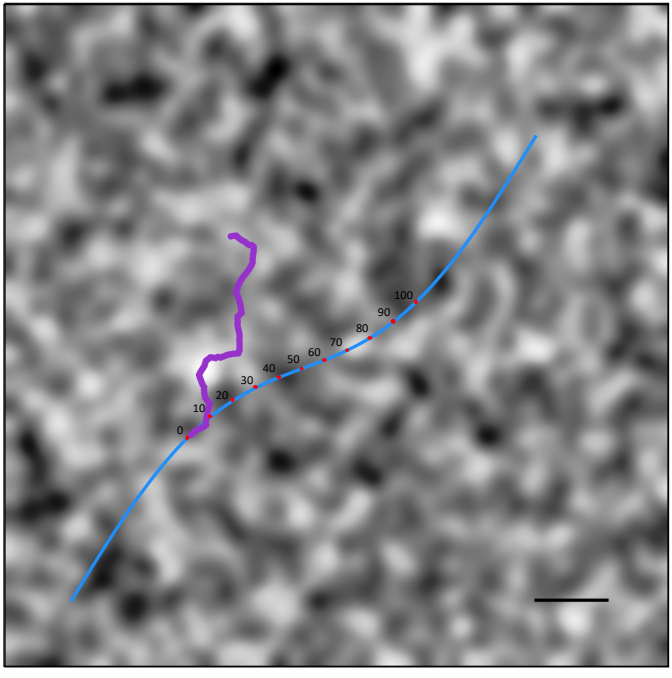


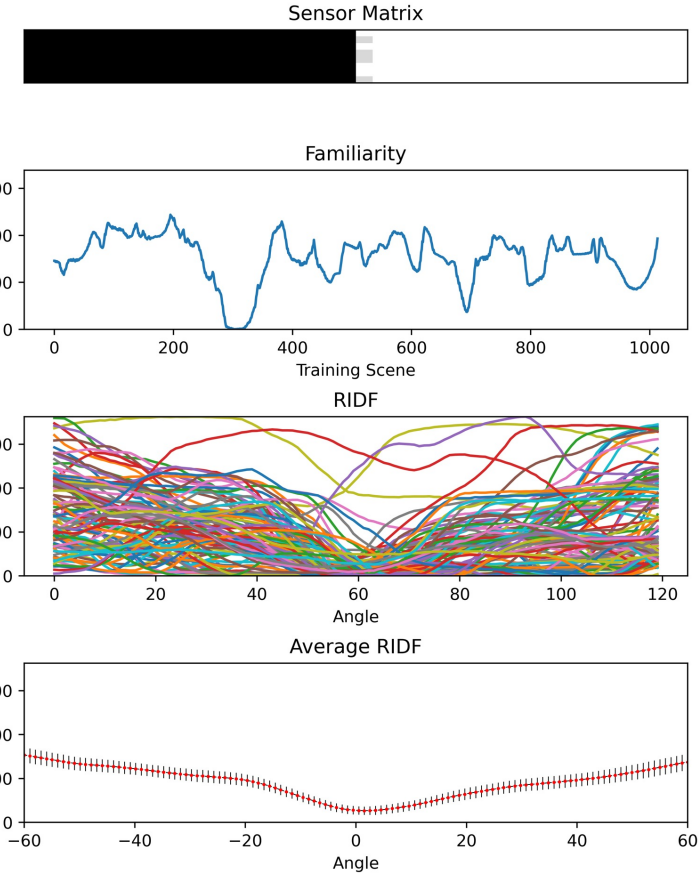


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5483.65; RMSD/dist: 13.709; TD: 2721; p90: 36; p50: 24; complete: 0

0%

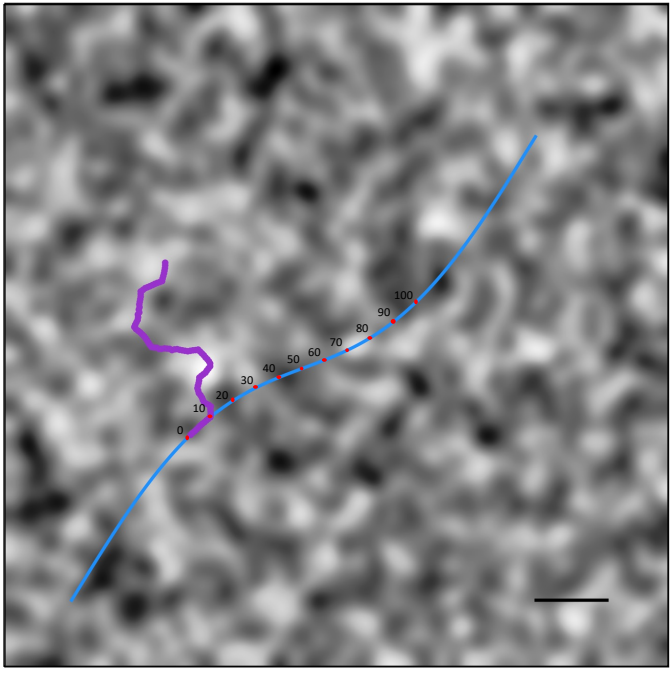


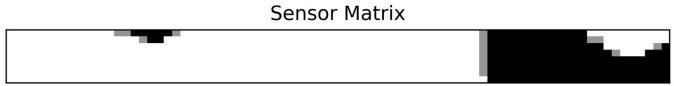


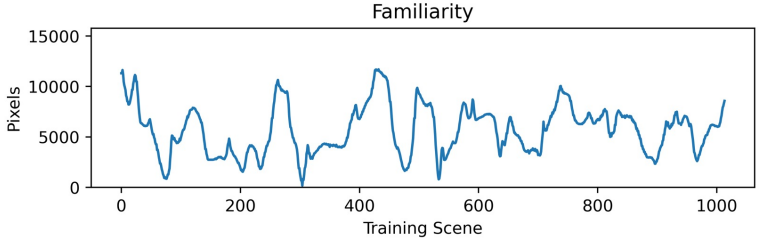
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

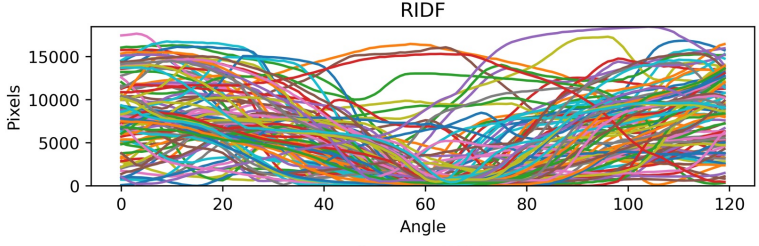
Navigation stats: RMSD error: 9645.93; RMSD/dist: 24.115; TD: 5666; p90: 90; p50: 32; complete: 0

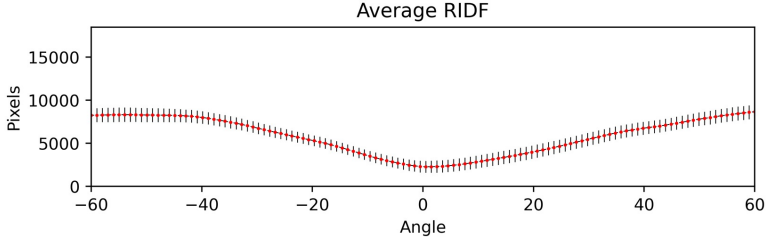
10%







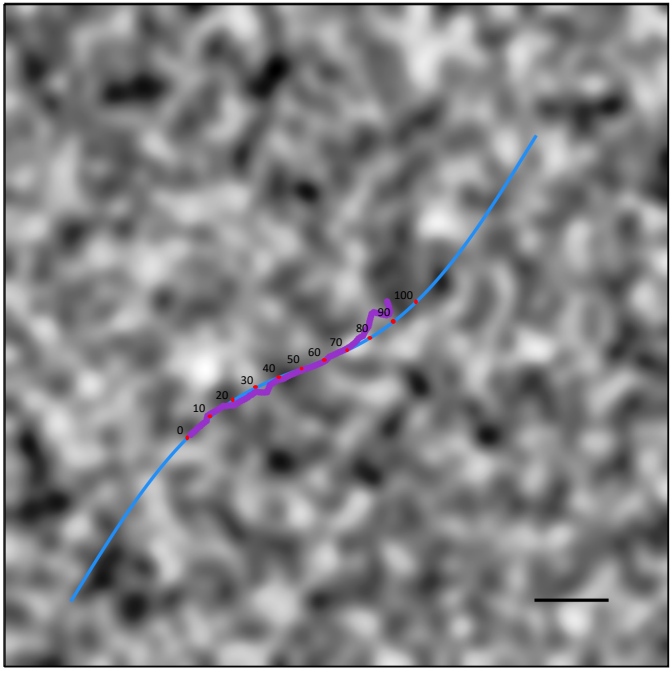


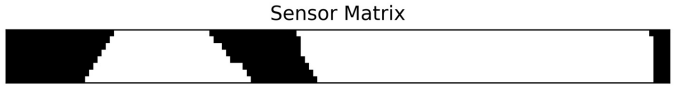


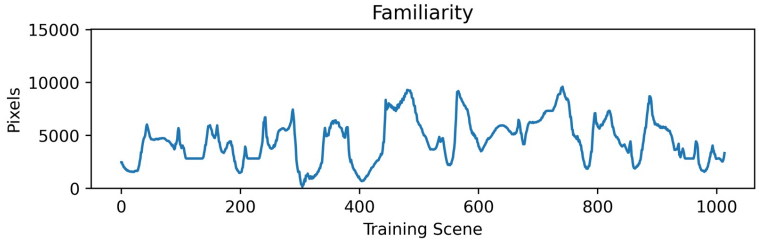
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

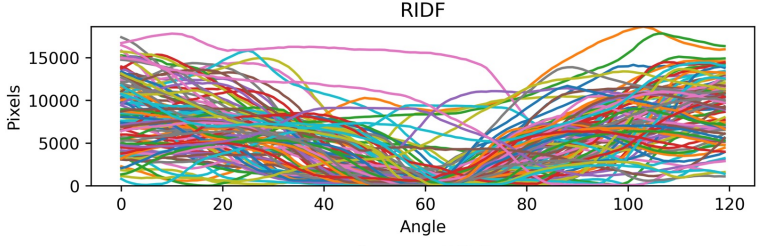
Navigation stats: RMSD error: 11412.24; RMSD/dist: 28.531; TD: 3777; p90: 46; p50: 26; complete: 0

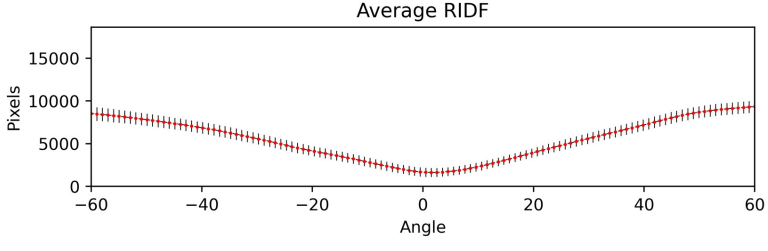
40%





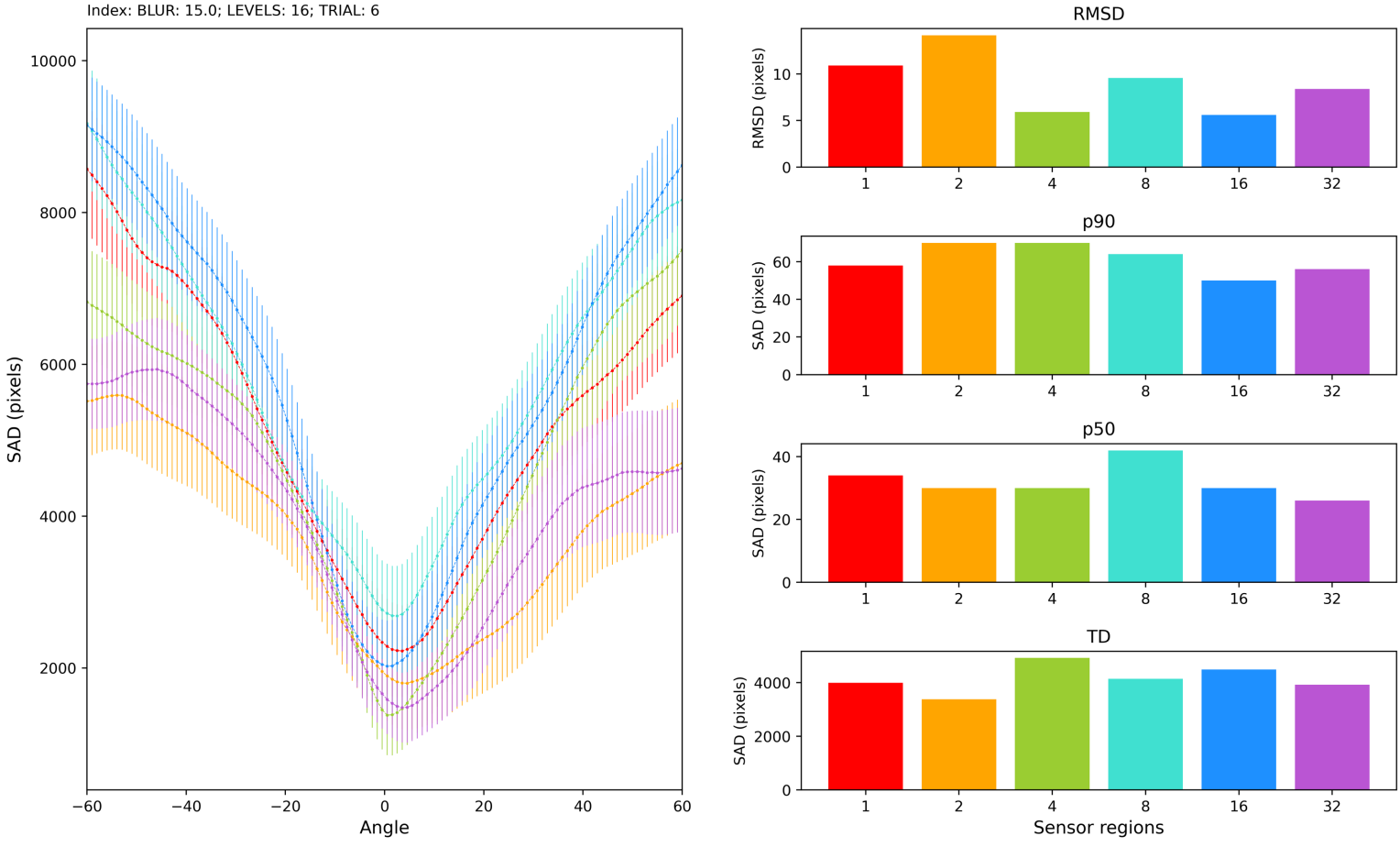




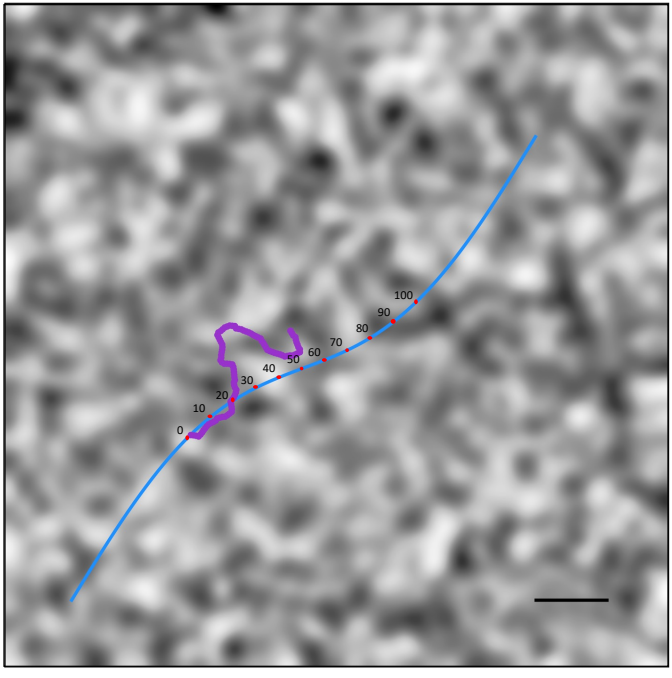


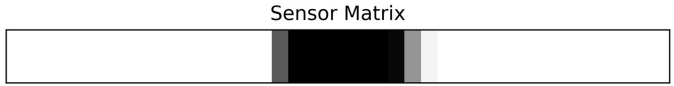
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

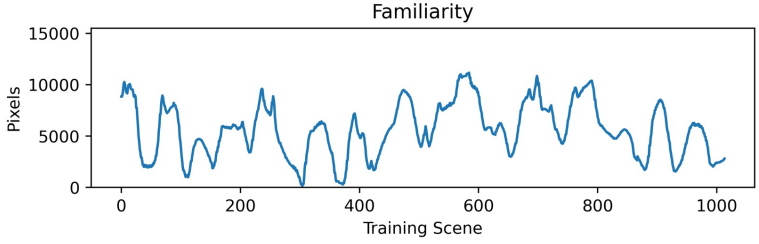
Navigation stats: RMSD error: 731.88; RMSD/dist: 1.830; TD: 4417; p90: 60; p50: 36; complete: 0

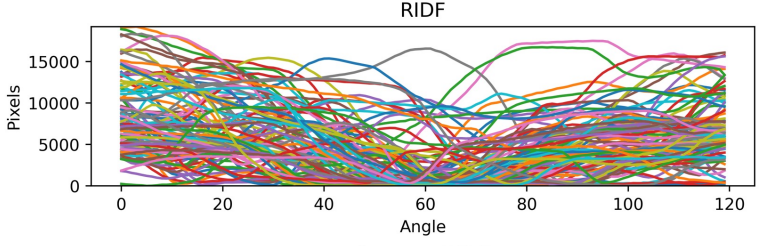

Index: BLUR: 15.0; LEVELS: 16; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

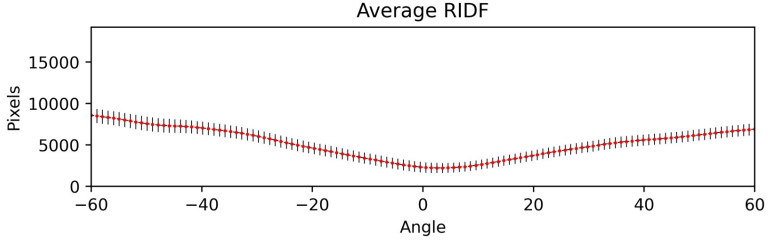
0%







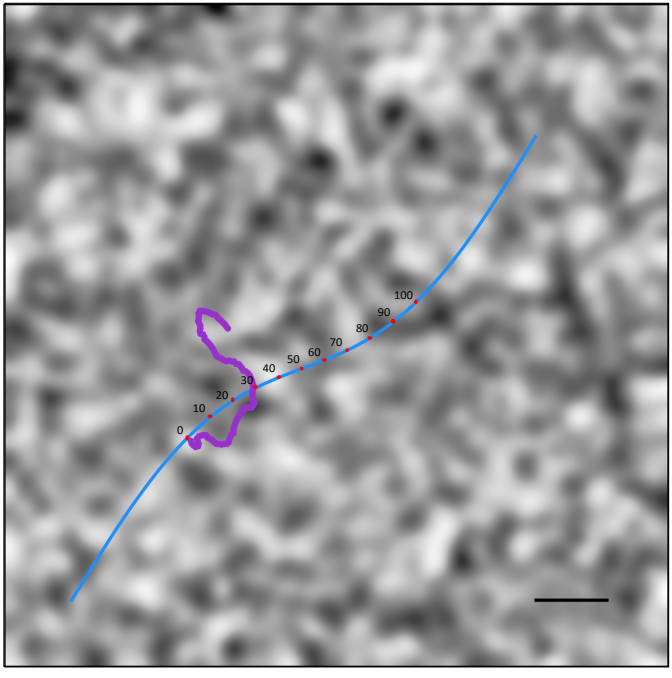


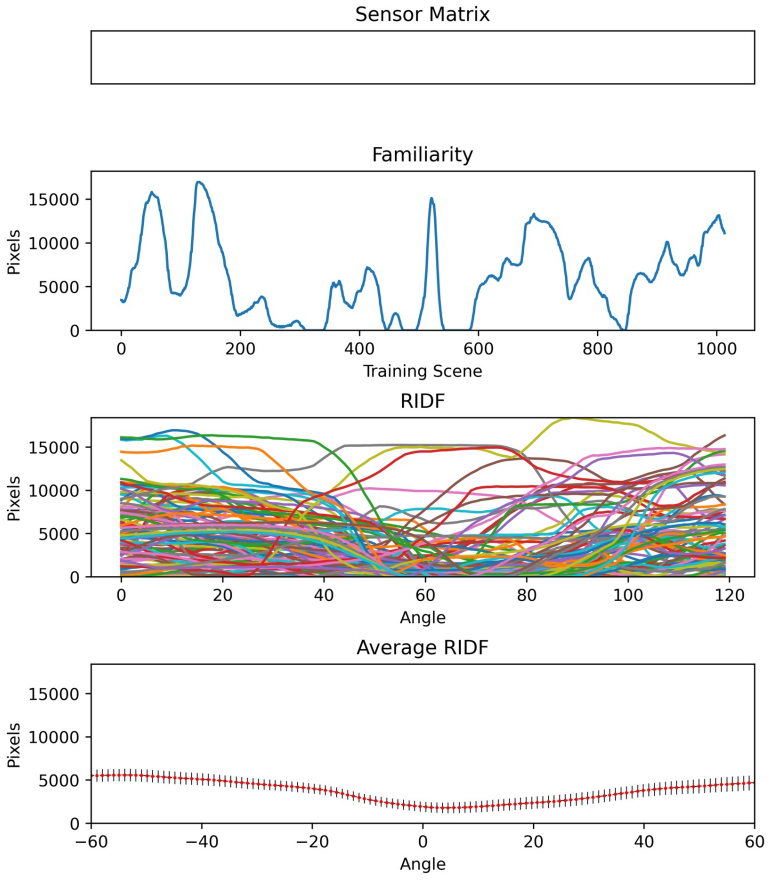


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 4367.42; RMSD/dist: 10.919; TD: 3987; p90: 58; p50: 34; complete: 0

0%

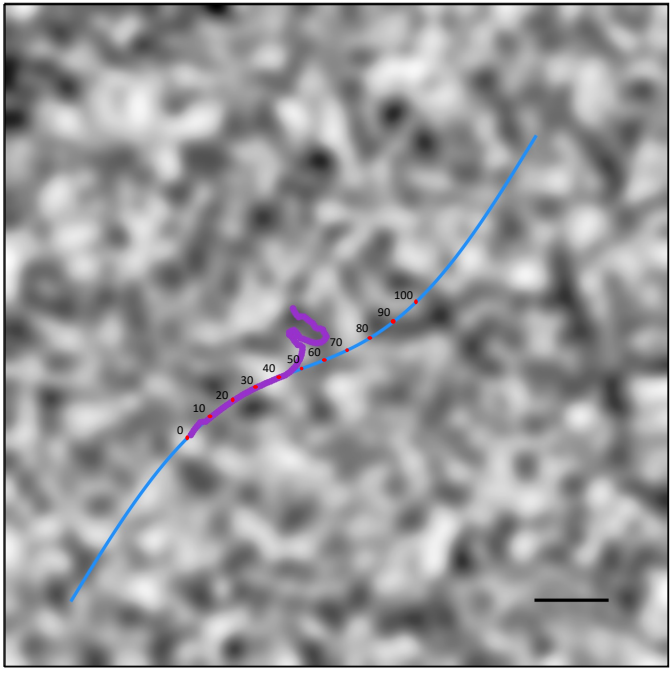


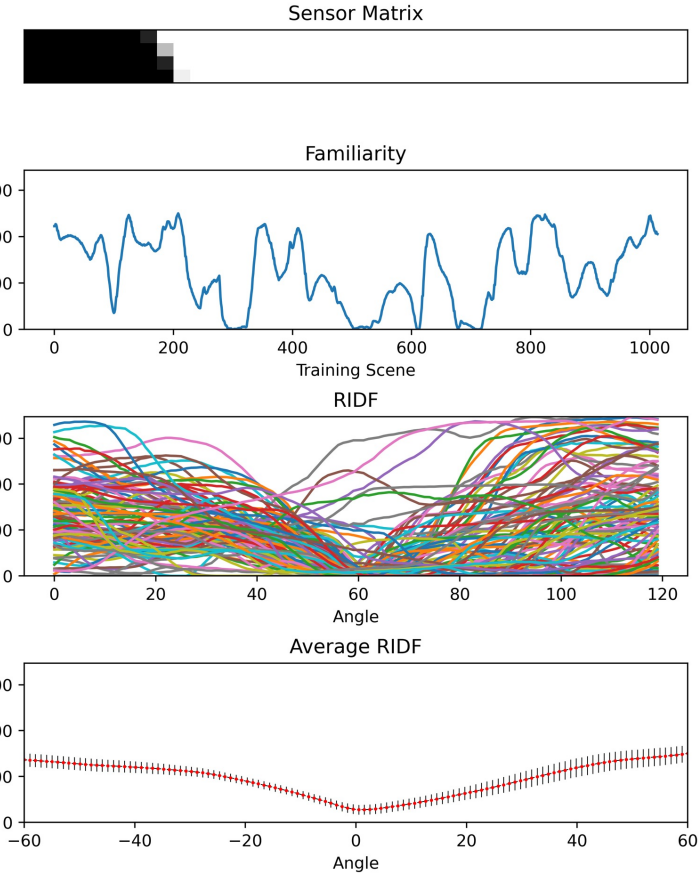


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 5667.45; RMSD/dist: 14.169; TD: 3373; p90: 70; p50: 30; complete: 0

40%

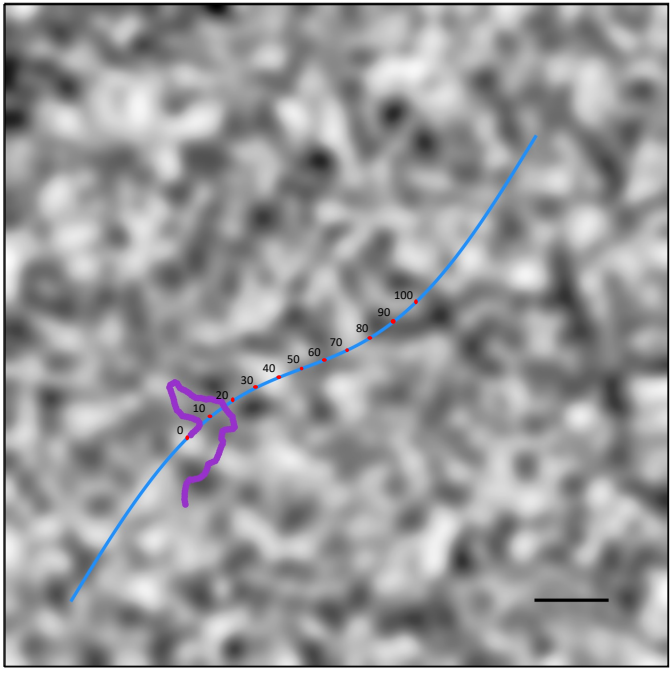


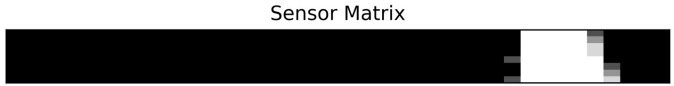


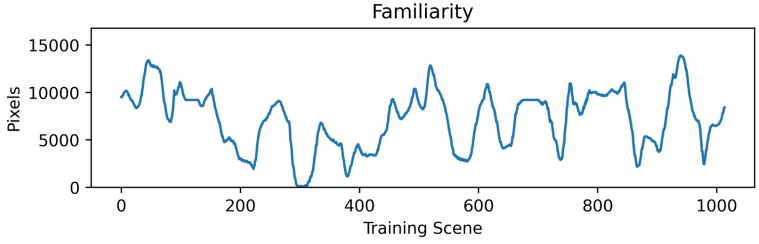
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

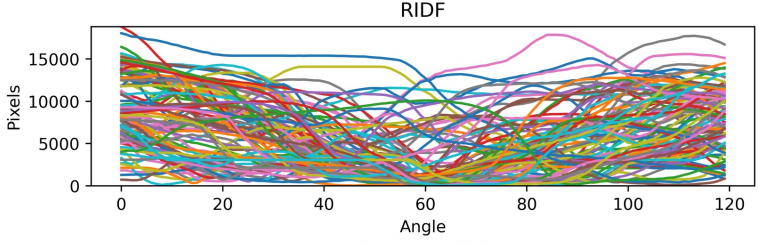
Navigation stats: RMSD error: 2362.73; RMSD/dist: 5.907; TD: 4915; p90: 70; p50: 30; complete: 0

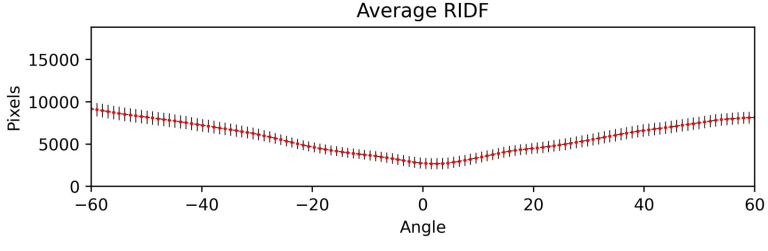
0%







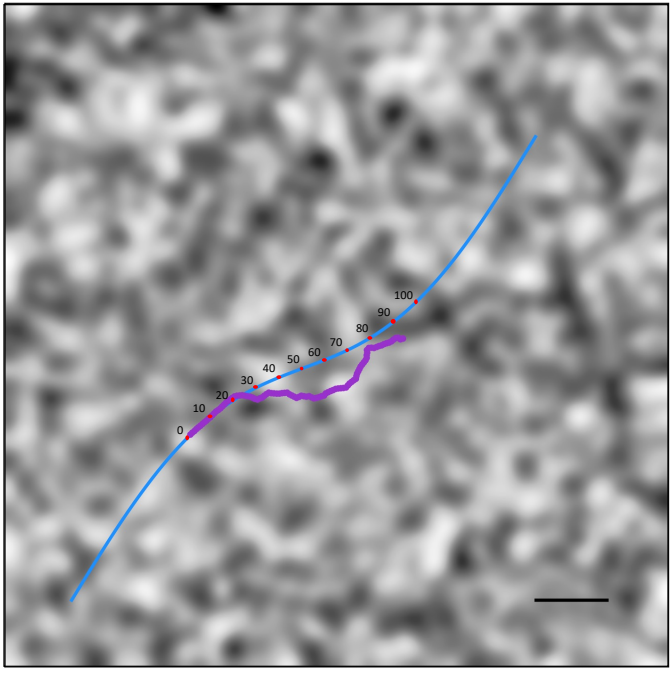


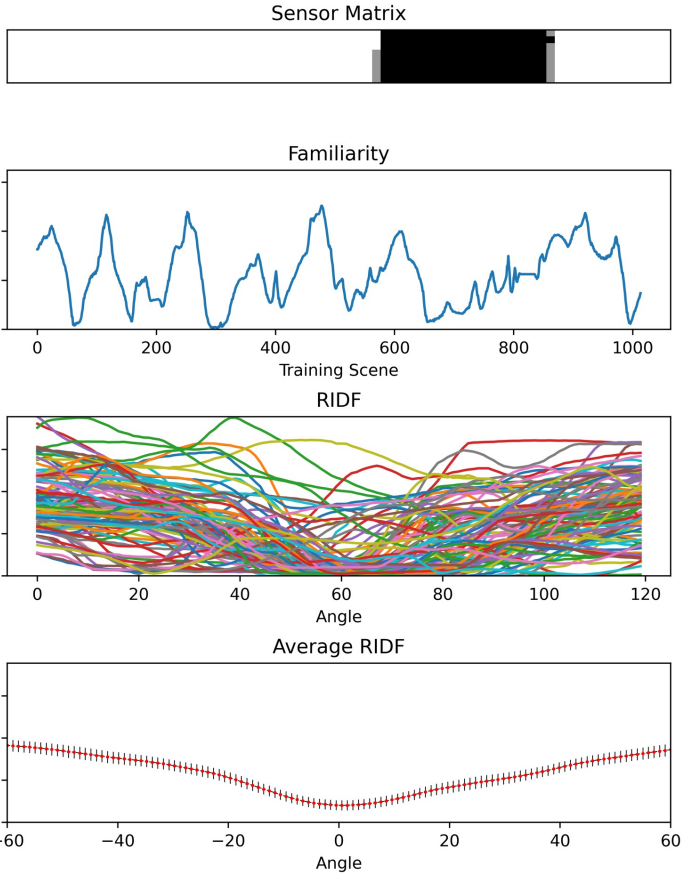


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3827.63; RMSD/dist: 9.569; TD: 4141; p90: 64; p50: 42; complete: 0

20%

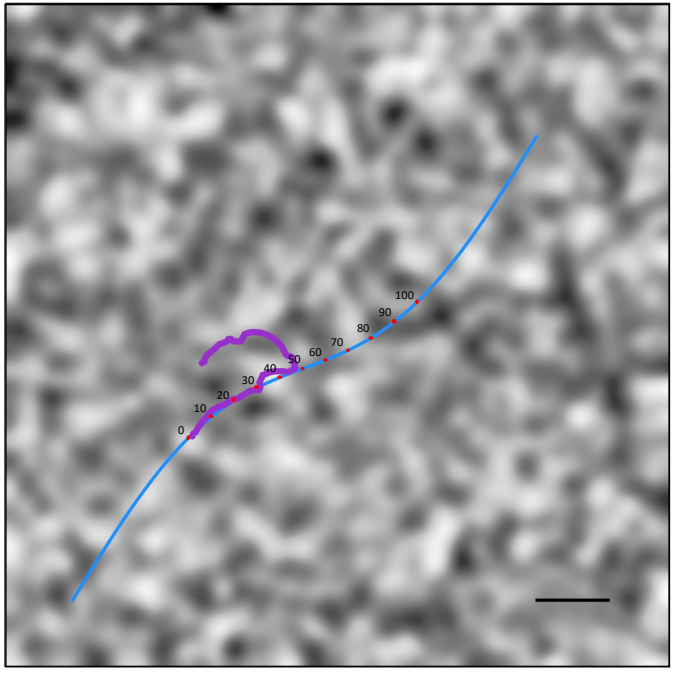


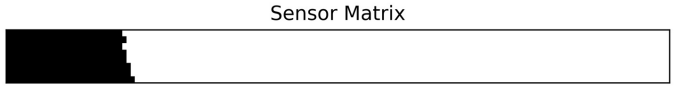


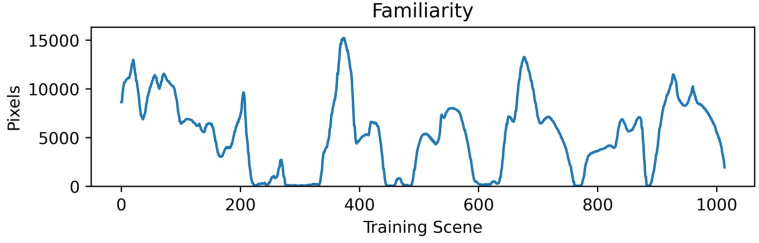
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

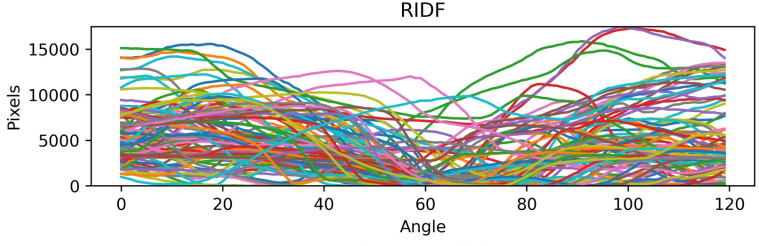
Navigation stats: RMSD error: 2242.91; RMSD/dist: 5.607; TD: 4486; p90: 50; p50: 30; complete: 0

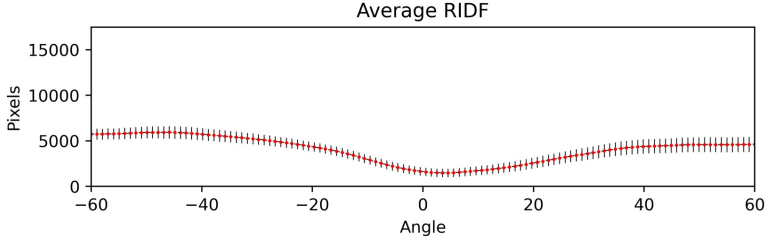
20%





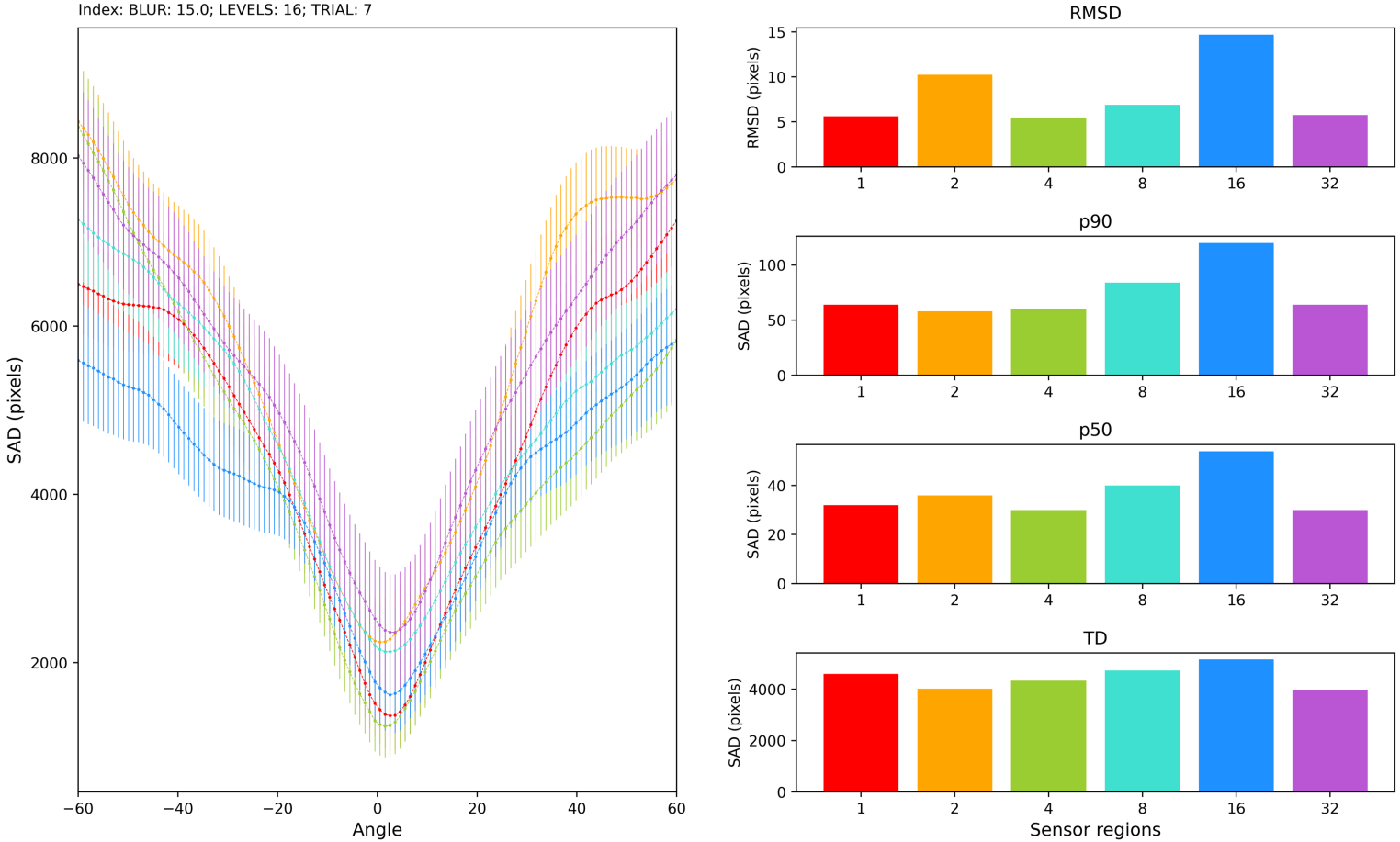




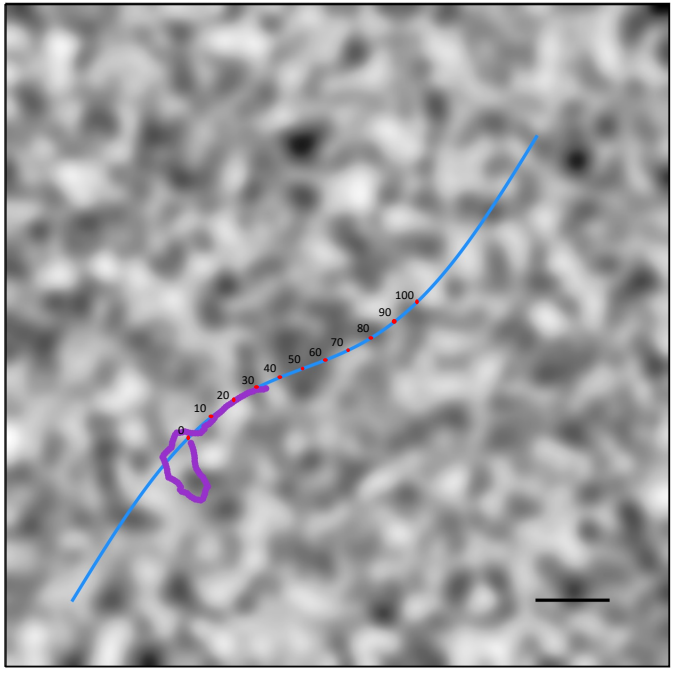


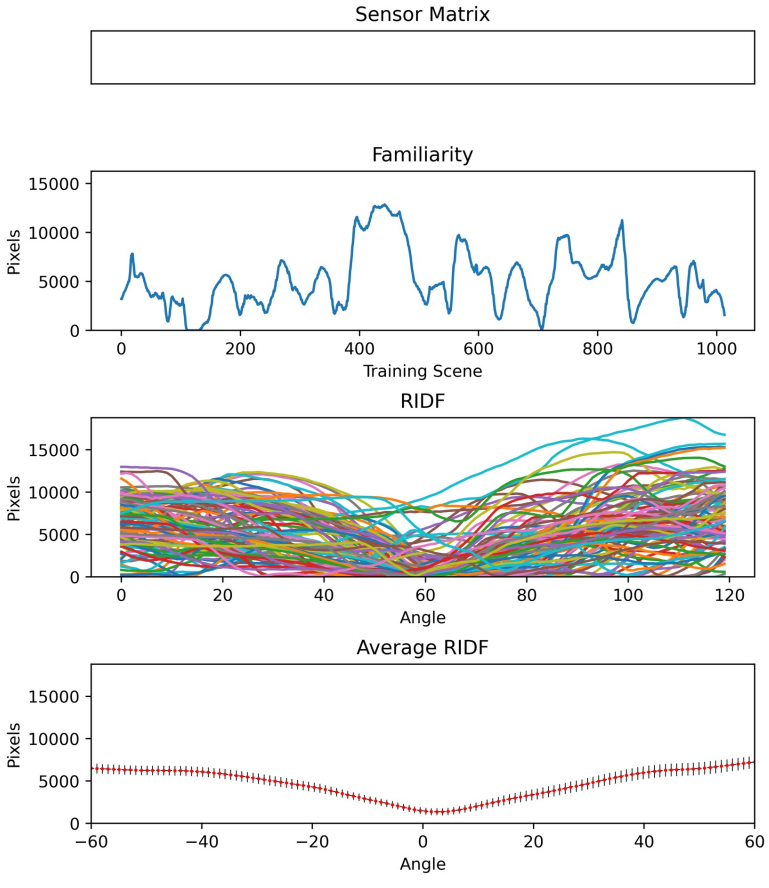
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3356.21; RMSD/dist: 8.391; TD: 3918; p90: 56; p50: 26; complete: 0


Index: BLUR: 15.0; LEVELS: 16; TRIAL: 7
SAD (pixels)
8000
6000
4000
2000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
15
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
40
20
TD
4000
2000
Sensor regions

20%

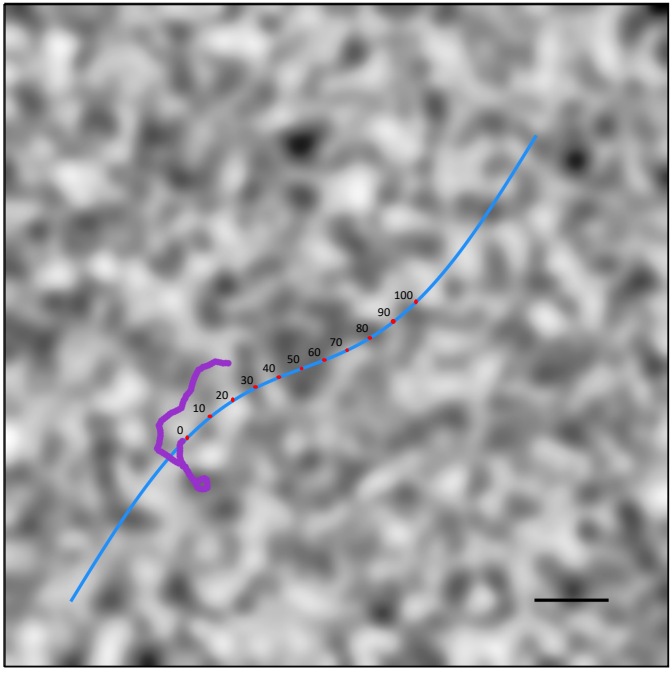


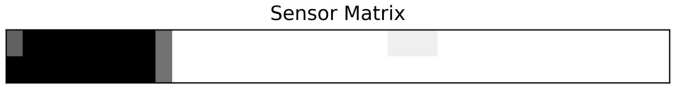


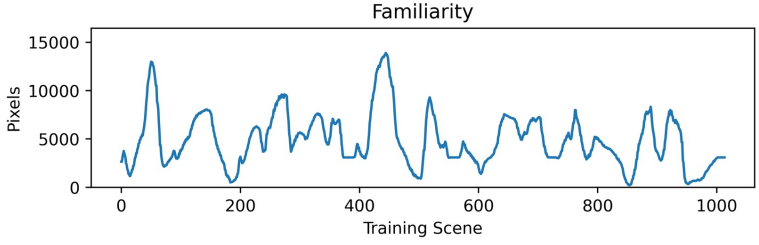
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

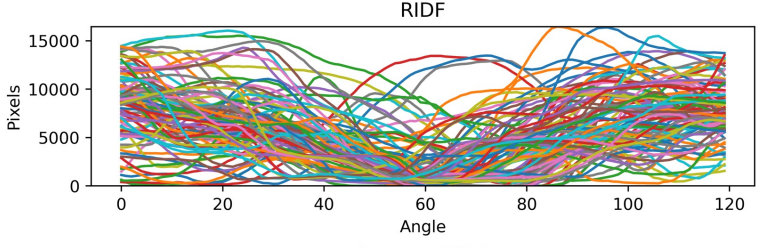
Navigation stats: RMSD error: 2249.41; RMSD/dist: 5.624; TD: 4602; p90: 64; p50: 32; complete: 0

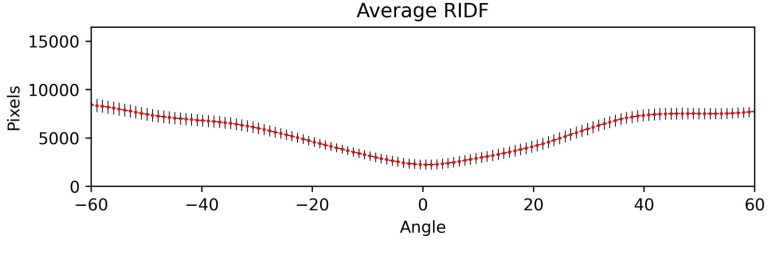
0%







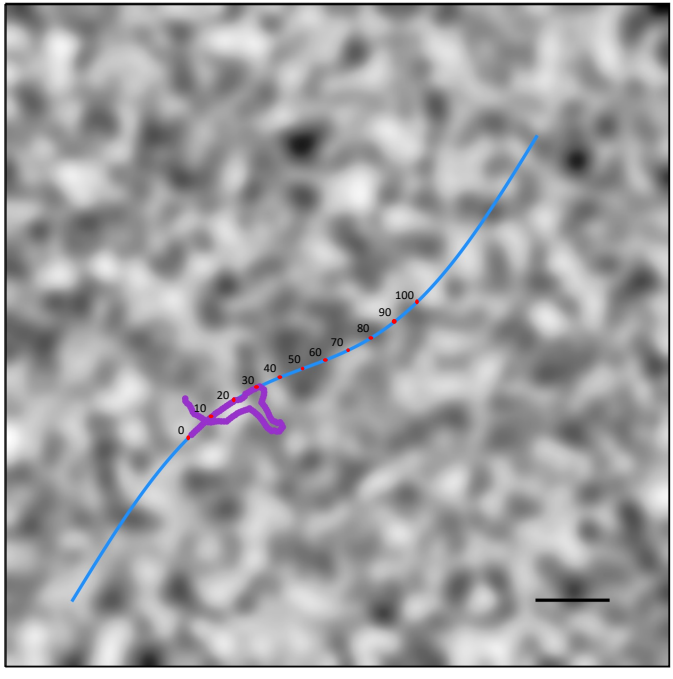


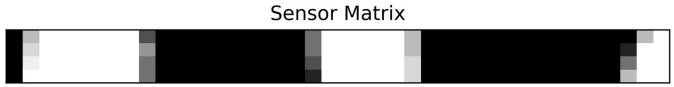


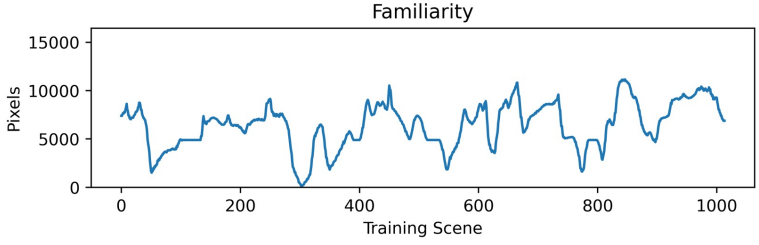
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

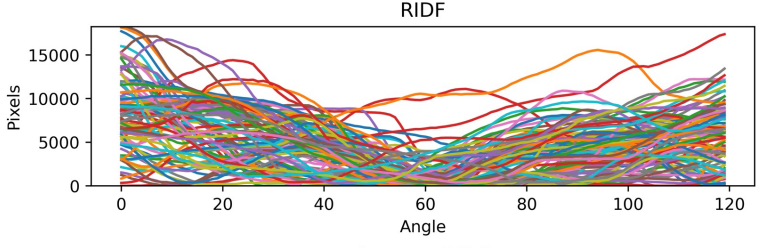
Navigation stats: RMSD error: 4090.01; RMSD/dist: 10.225; TD: 4019; p90: 58; p50: 36; complete: 0

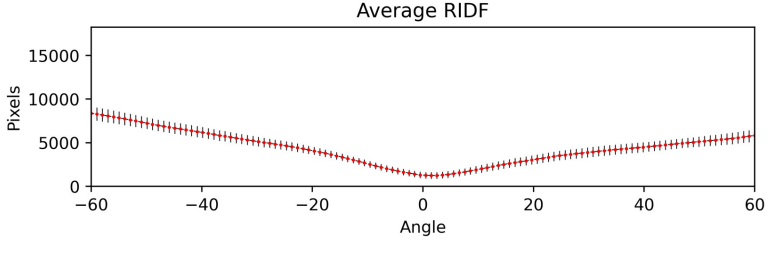
20%







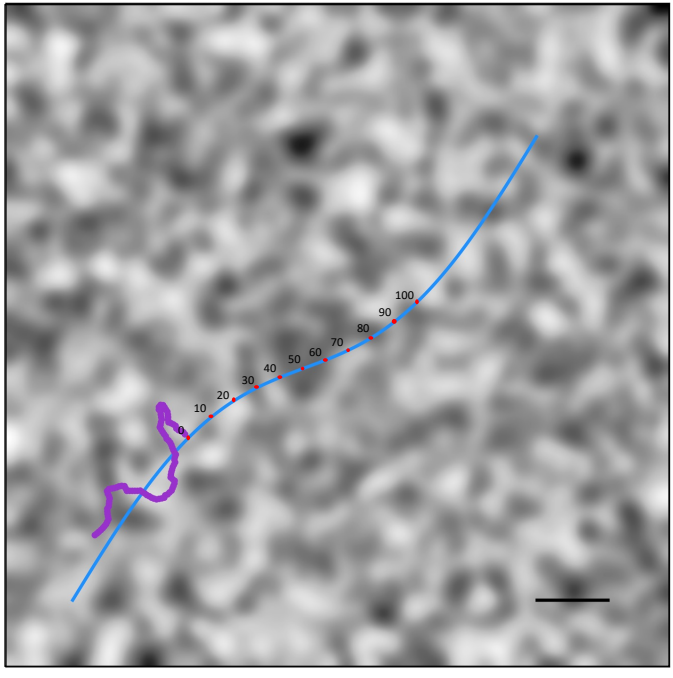


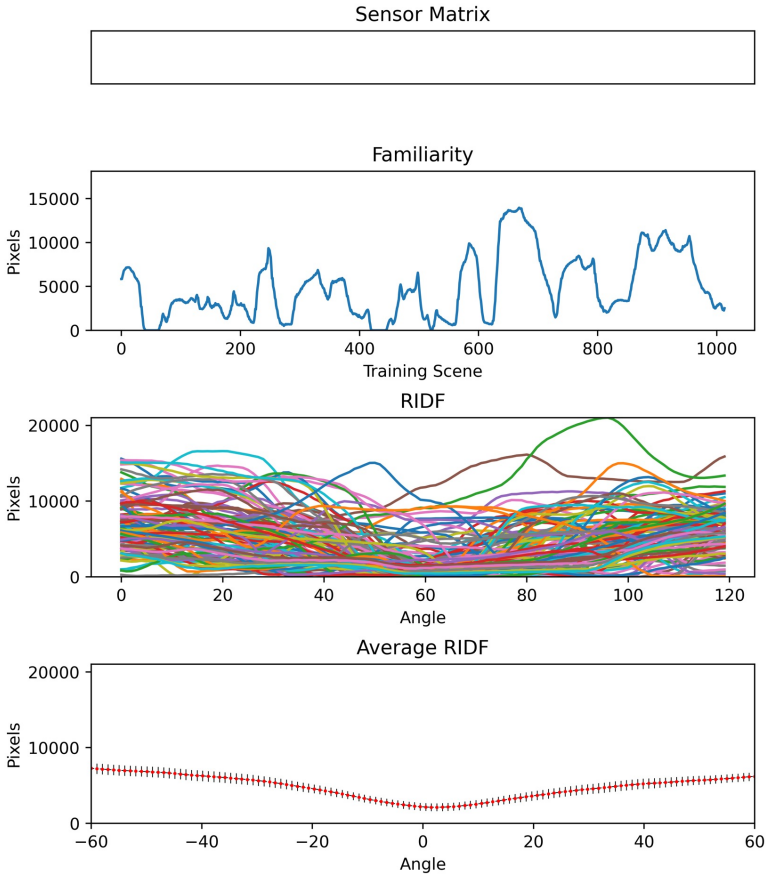


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 2195.92; RMSD/dist: 5.490; TD: 4333; p90: 60; p50: 30; complete: 0

0%

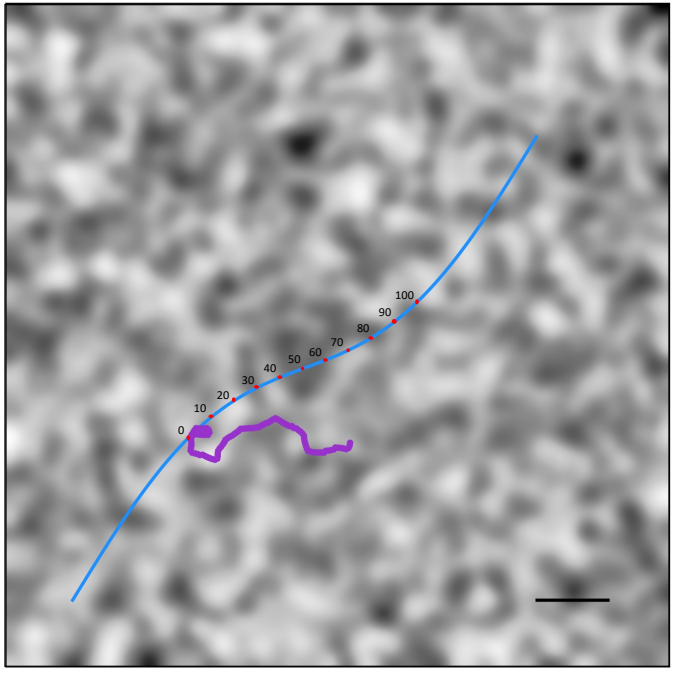


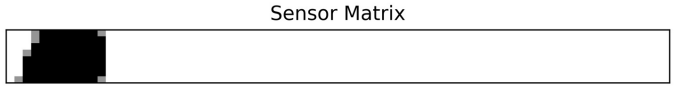


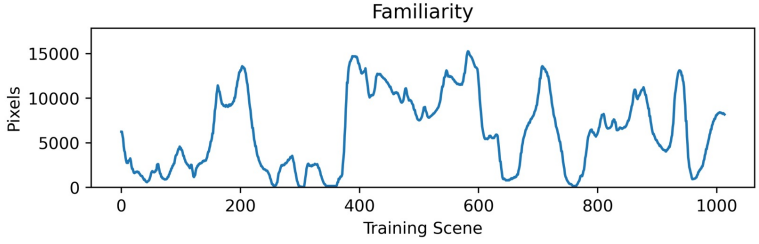
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

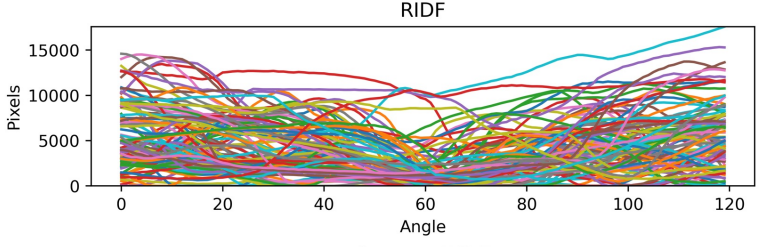
Navigation stats: RMSD error: 2760.90; RMSD/dist: 6.902; TD: 4732; p90: 84; p50: 40; complete: 0

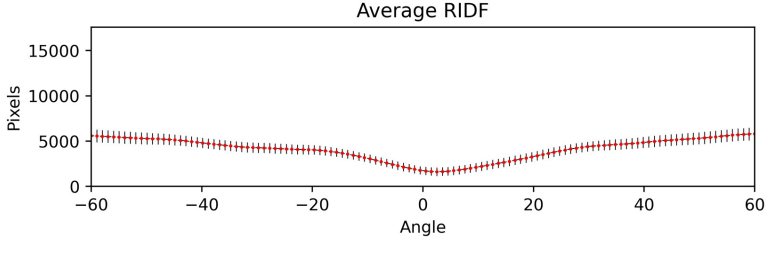
0%







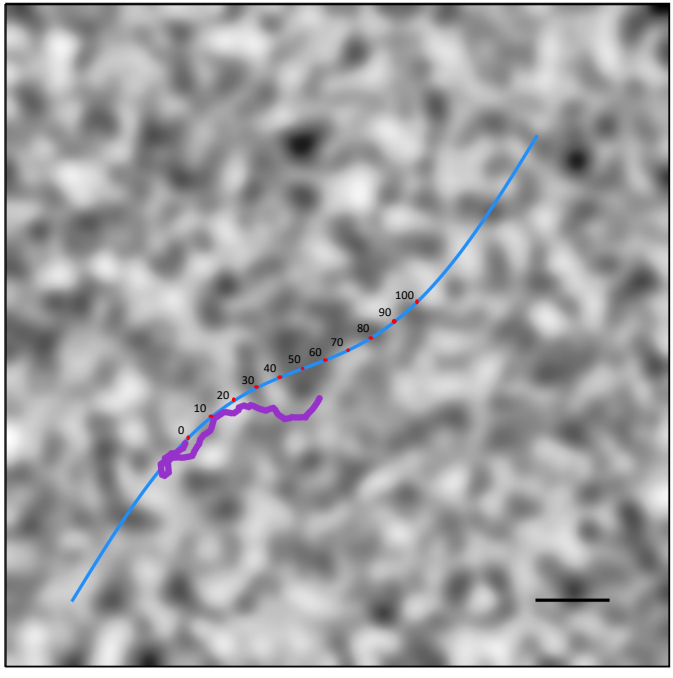


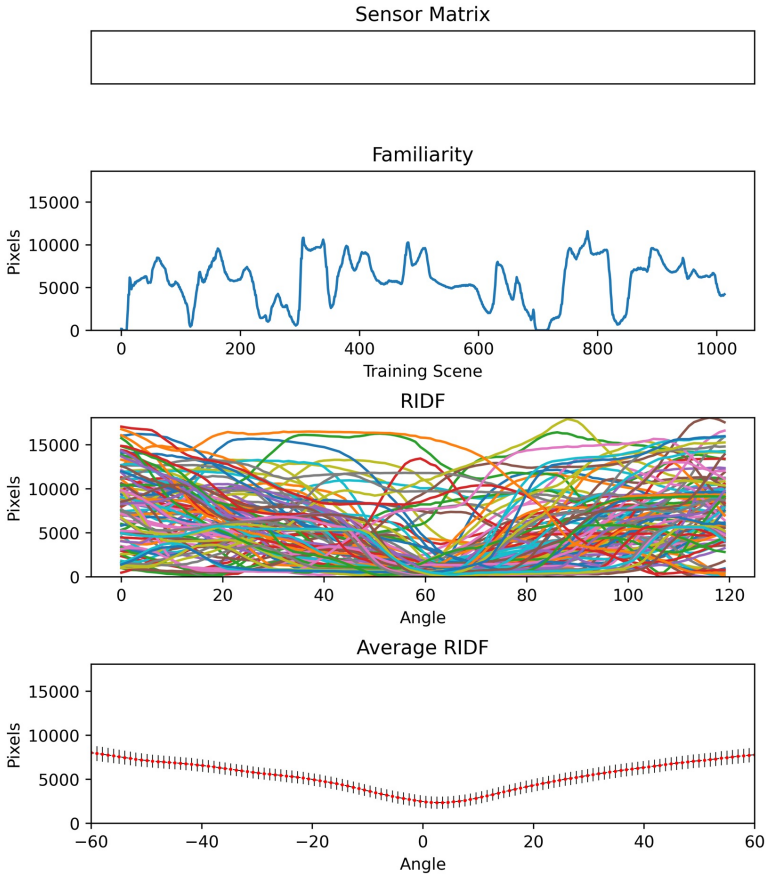


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 5878.59; RMSD/dist: 14.696; TD: 5156; p90: 120; p50: 54; complete: 0

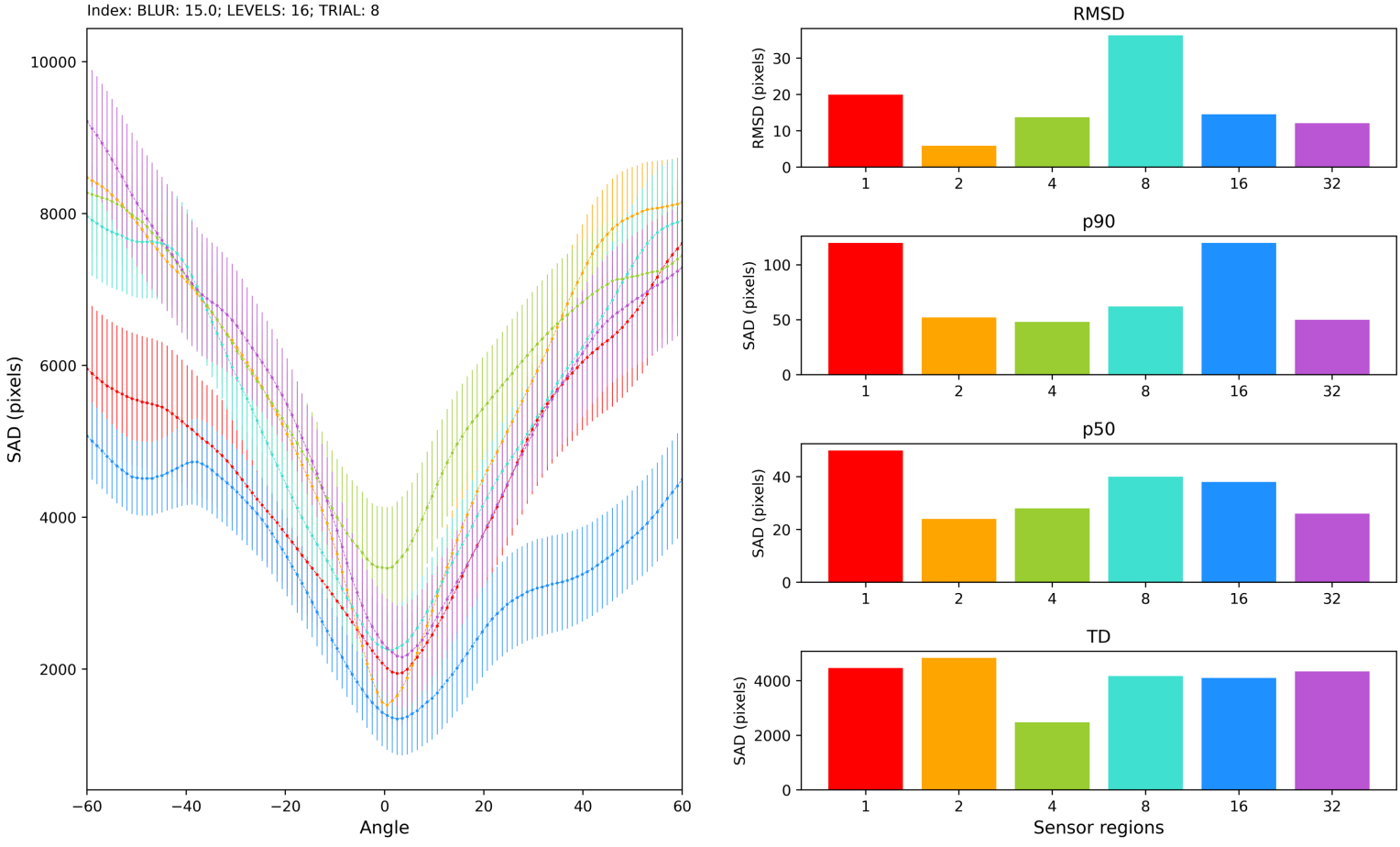
0%



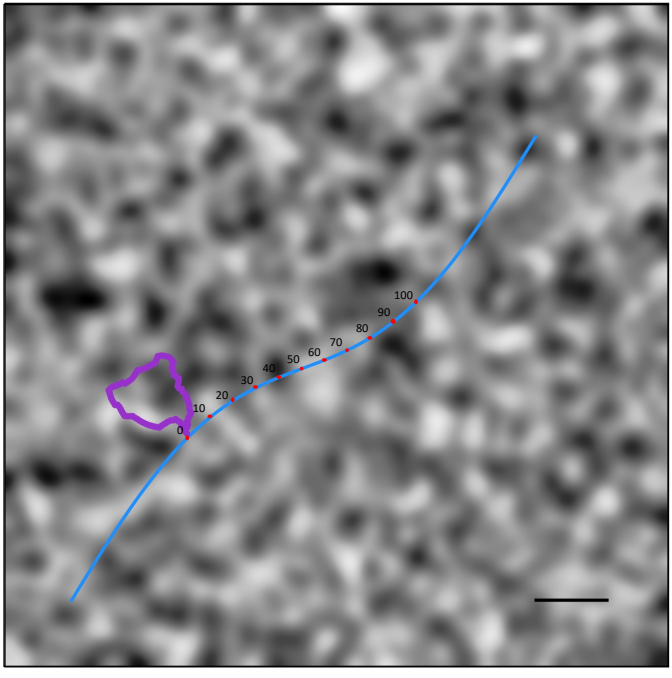


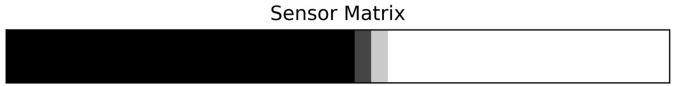
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

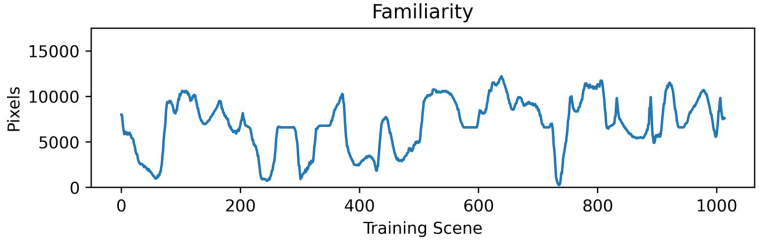
Navigation stats: RMSD error: 2306.35; RMSD/dist: 5.766; TD: 3963; p90: 64; p50: 30; complete: 0

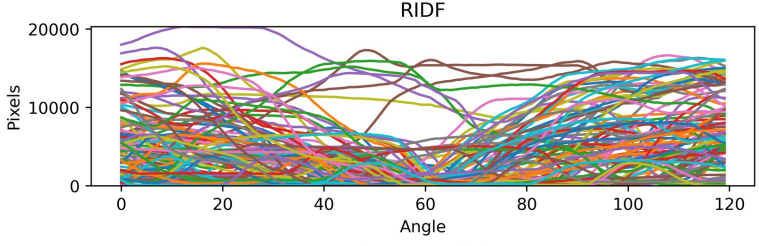

Index: BLUR: 15.0; LEVELS: 16; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

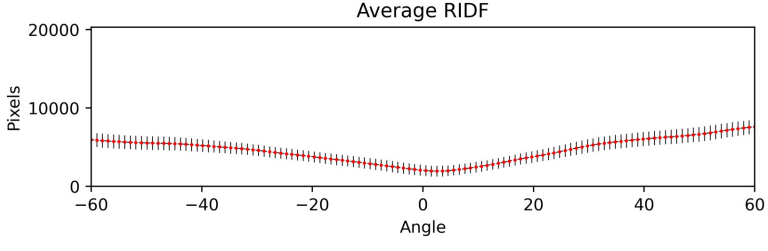
0%







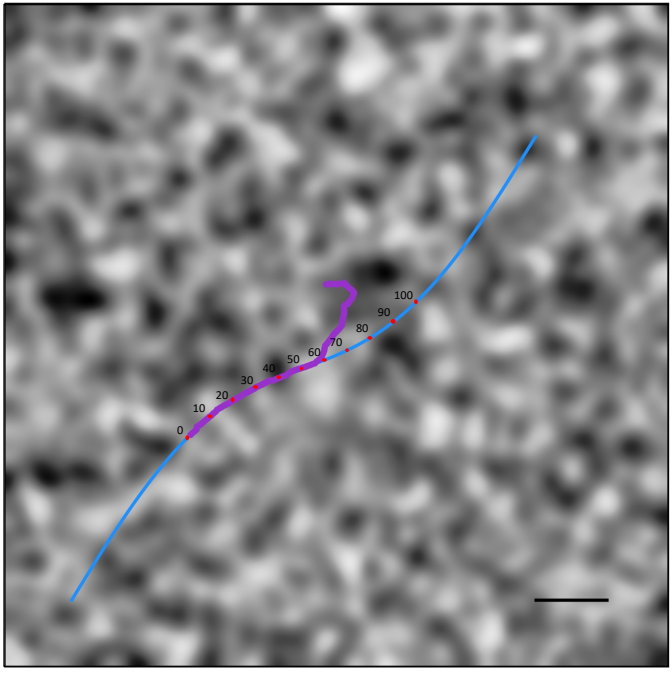


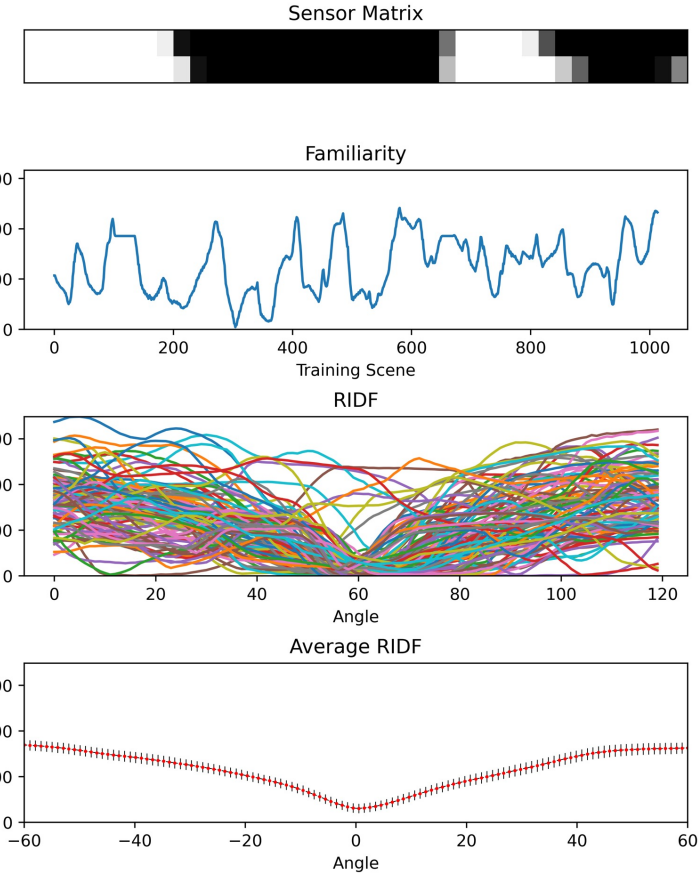


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 7988.33; RMSD/dist: 19.971; TD: 4468; p90: 120; p50: 50; complete: 0

50%

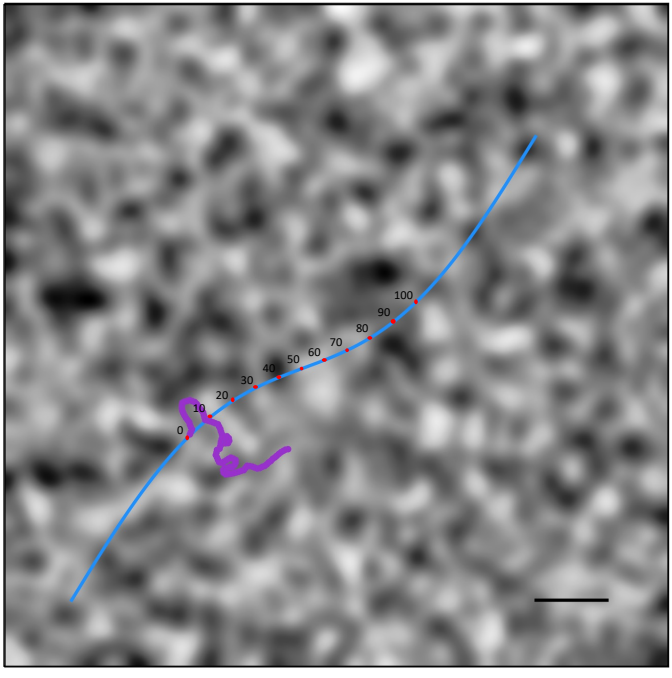


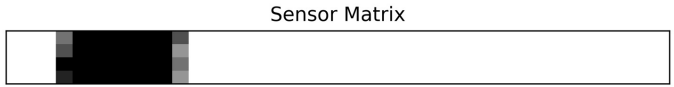


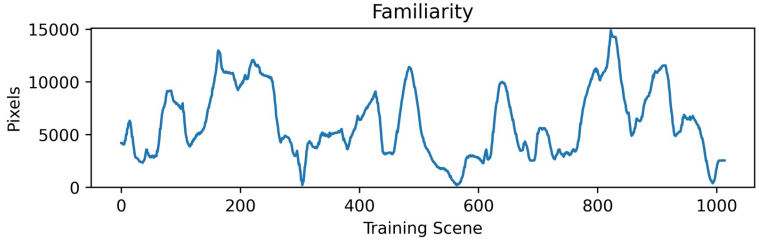
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

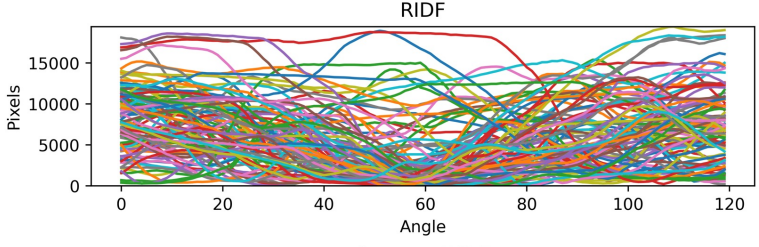
Navigation stats: RMSD error: 2345.89; RMSD/dist: 5.865; TD: 4837; p90: 52; p50: 24; complete: 0

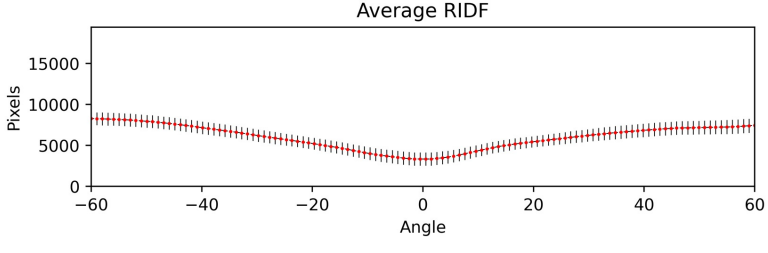
0%







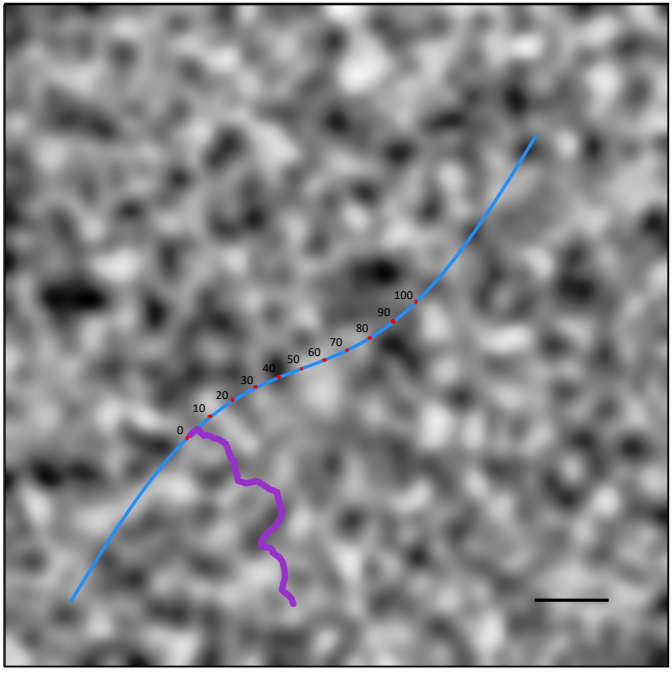


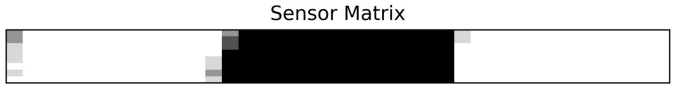


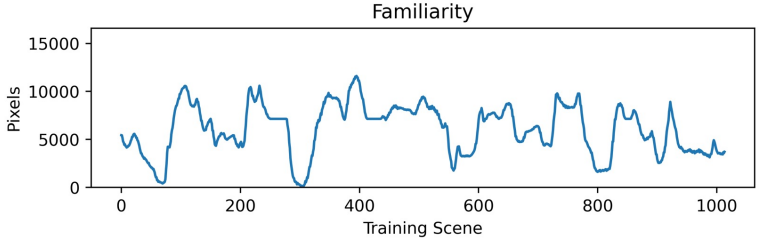
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

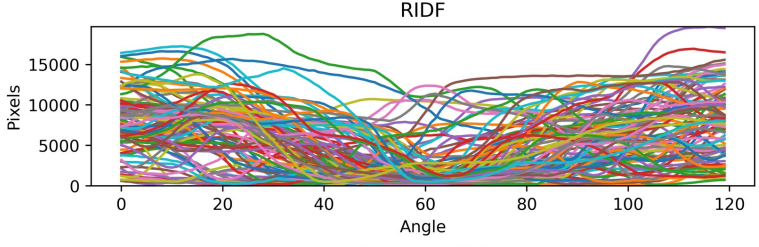
Navigation stats: RMSD error: 5493.04; RMSD/dist: 13.733; TD: 2474; p90: 48; p50: 28; complete: 0

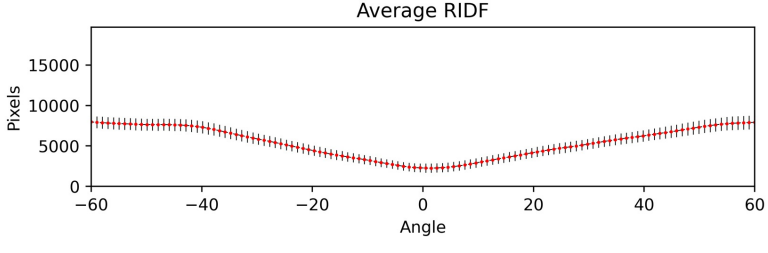
0%







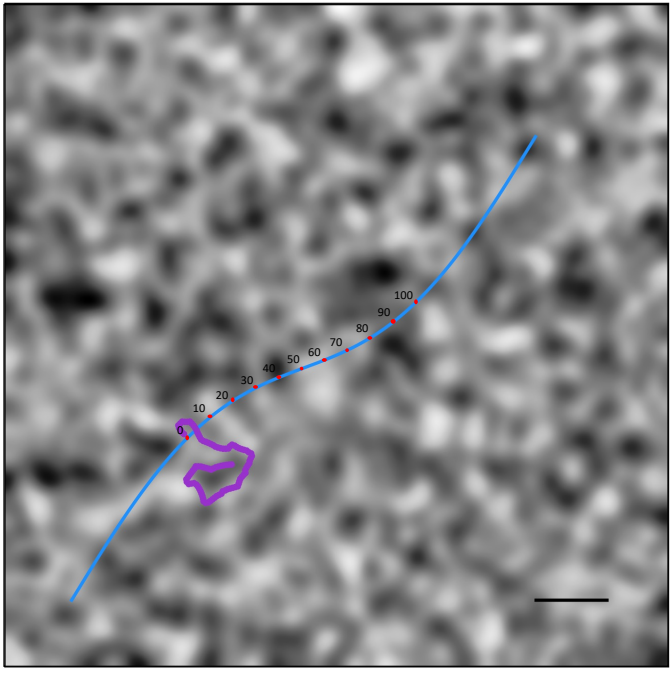


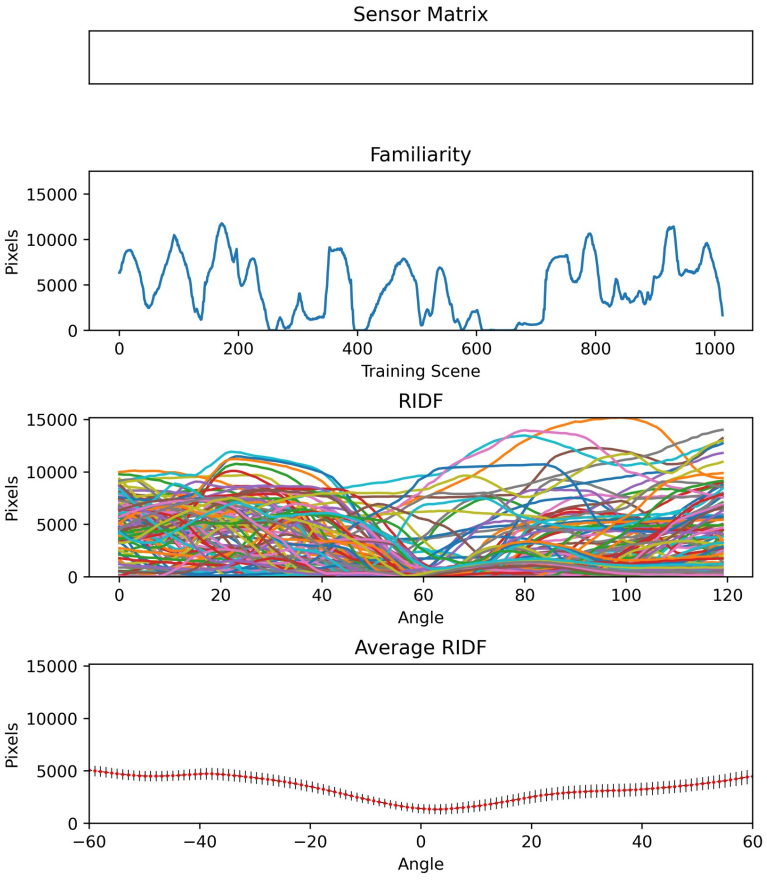


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 14533.71; RMSD/dist: 36.334; TD: 4171; p90: 62; p50: 40; complete: 0

0%

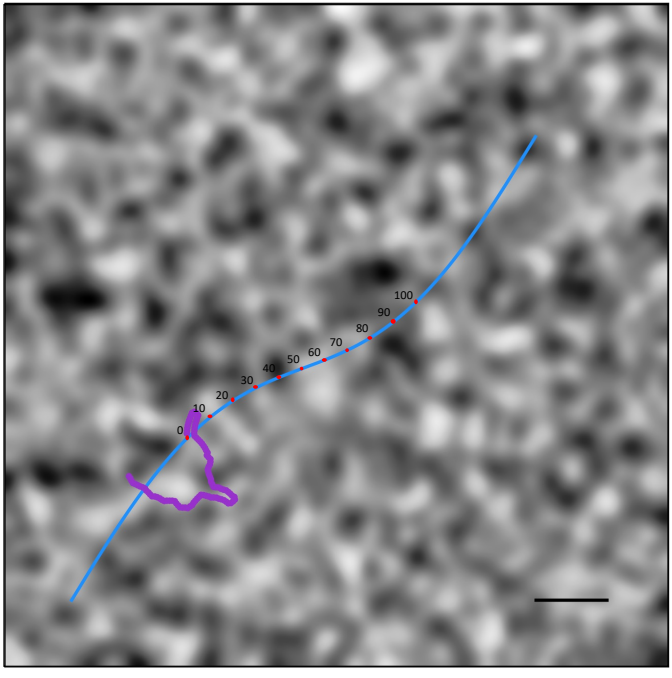


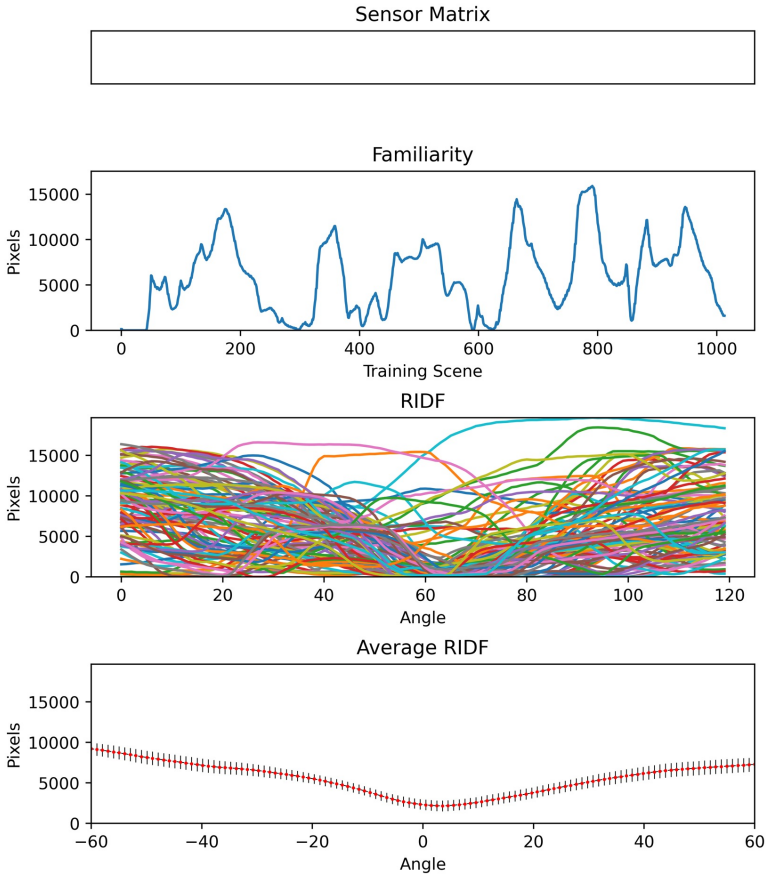


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5821.07; RMSD/dist: 14.553; TD: 4108; p90: 120; p50: 38; complete: 0

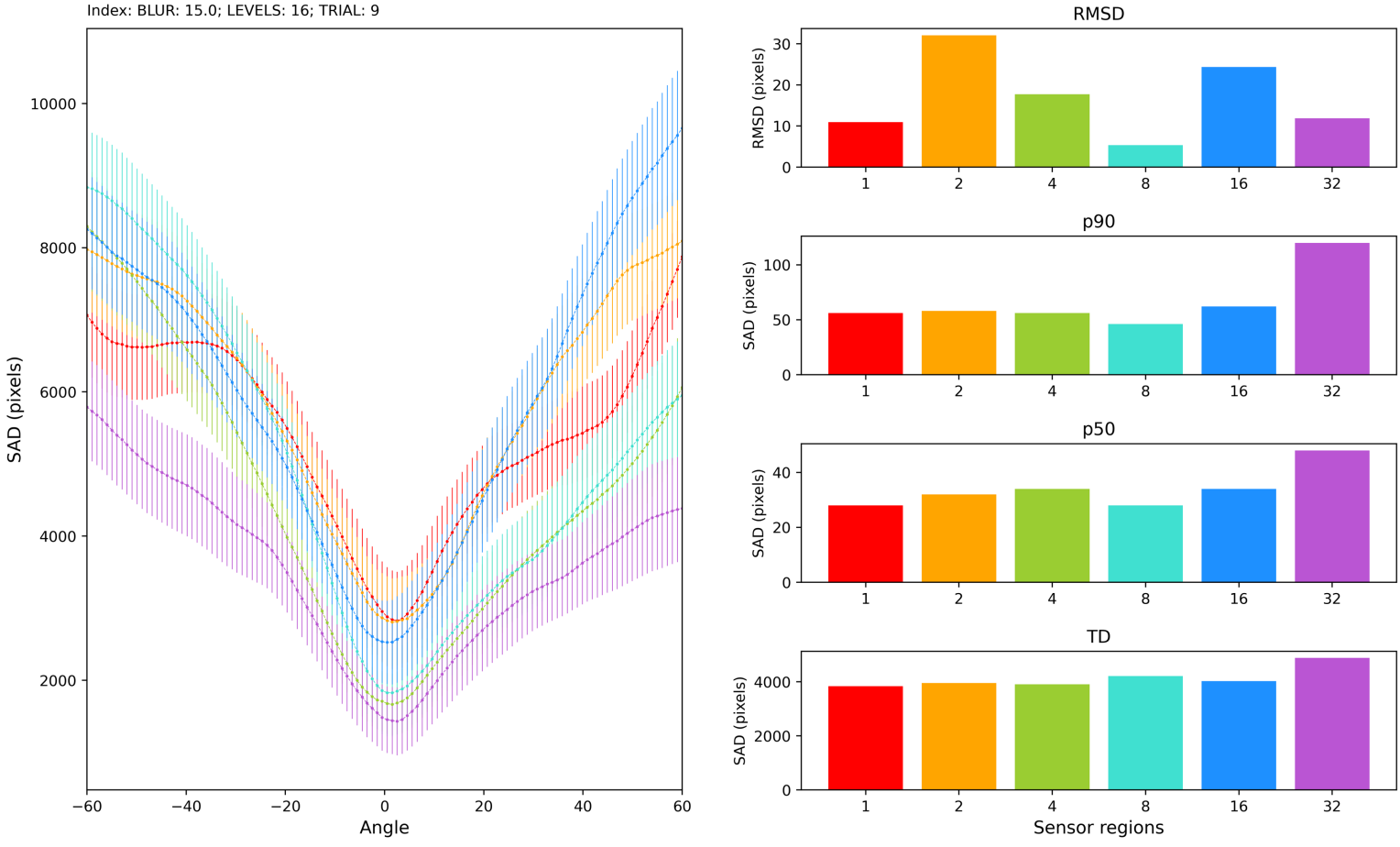
0%



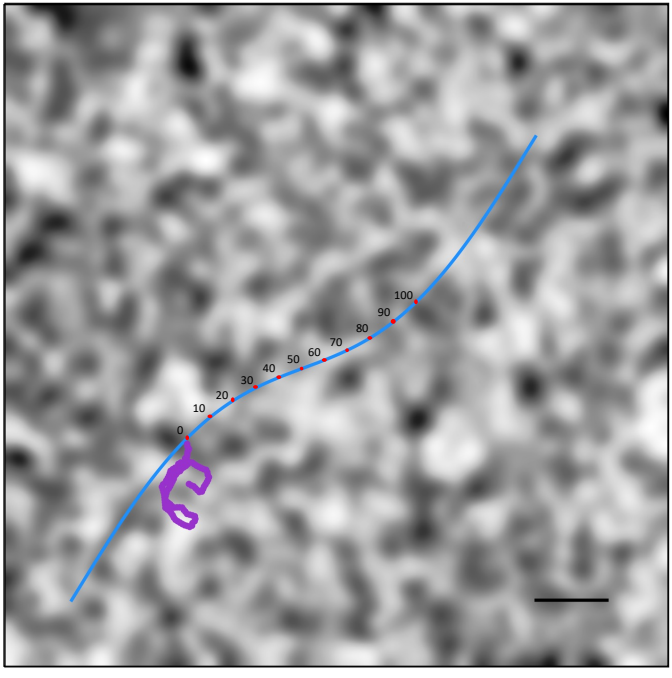


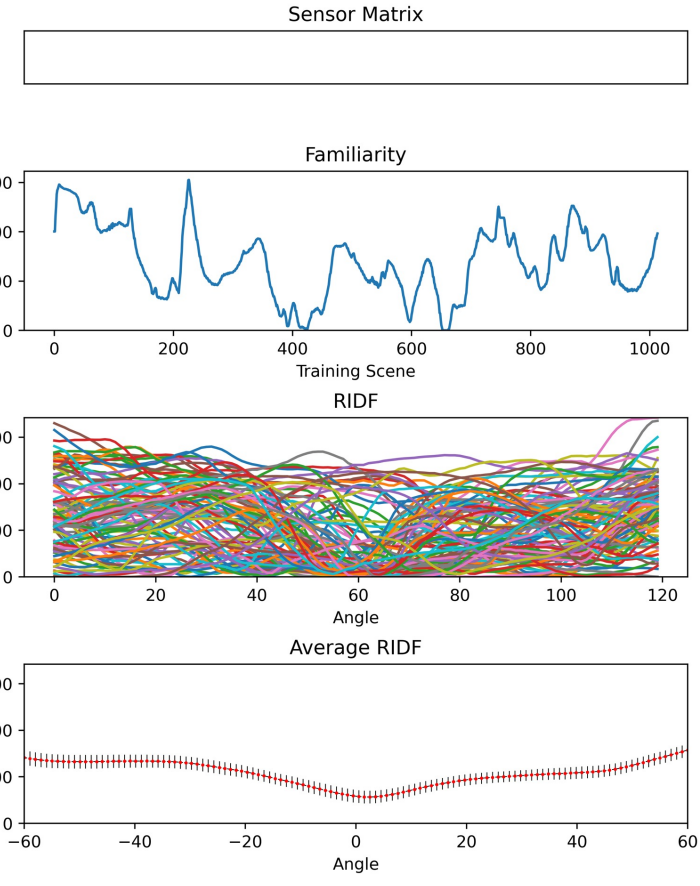
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 4834.87; RMSD/dist: 12.087; TD: 4343; p90: 50; p50: 26; complete: 0


Index: BLUR: 15.0; LEVELS: 16; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

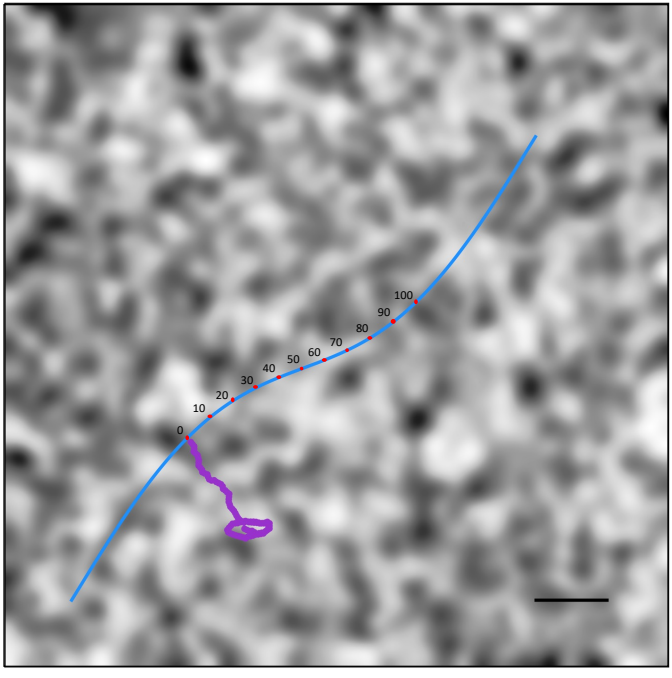


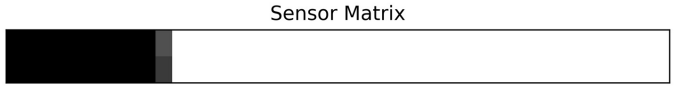


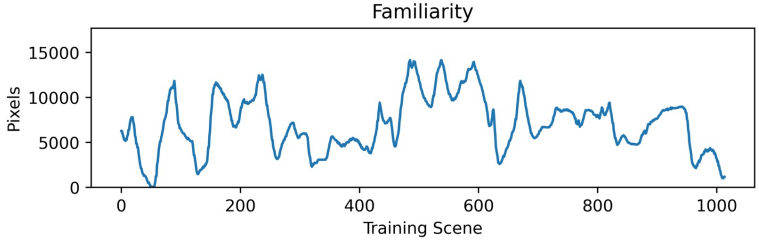
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

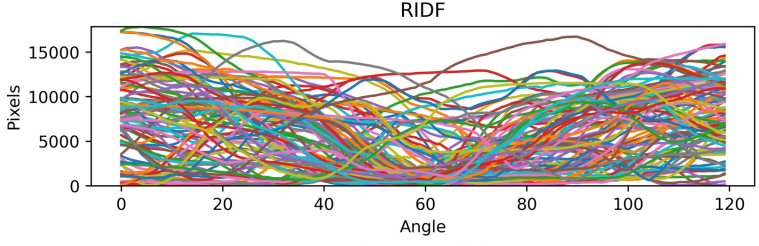
Navigation stats: RMSD error: 4373.06; RMSD/dist: 10.933; TD: 3838; p90: 56; p50: 28; complete: 0

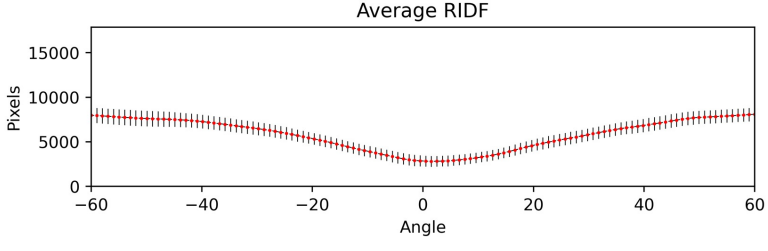
0%







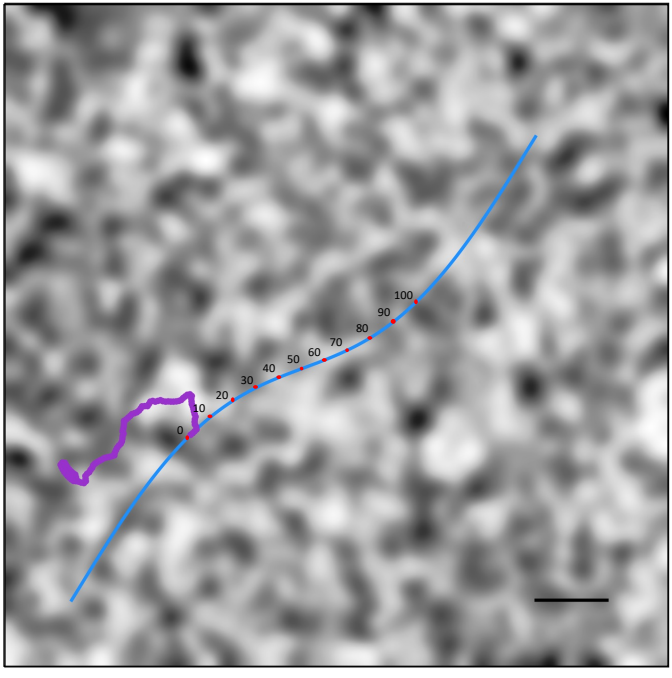


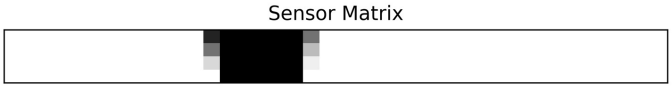


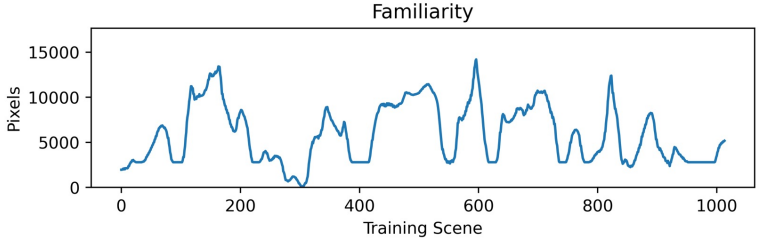
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

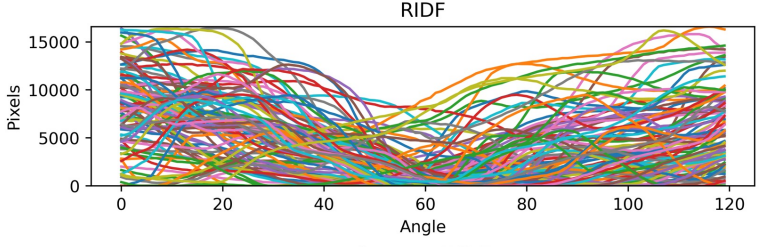
Navigation stats: RMSD error: 12831.69; RMSD/dist: 32.079; TD: 3955; p90: 58; p50: 32; complete: 0

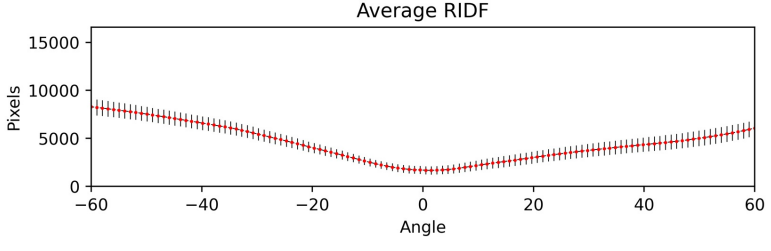
0%







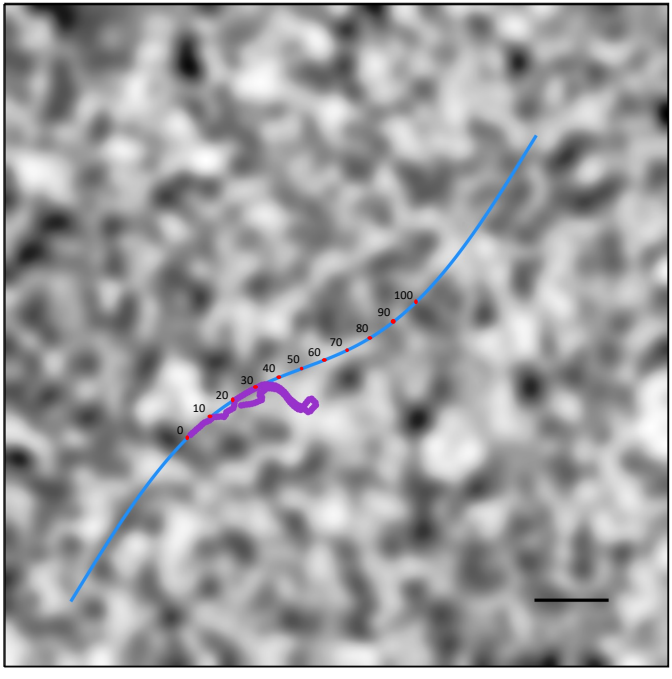


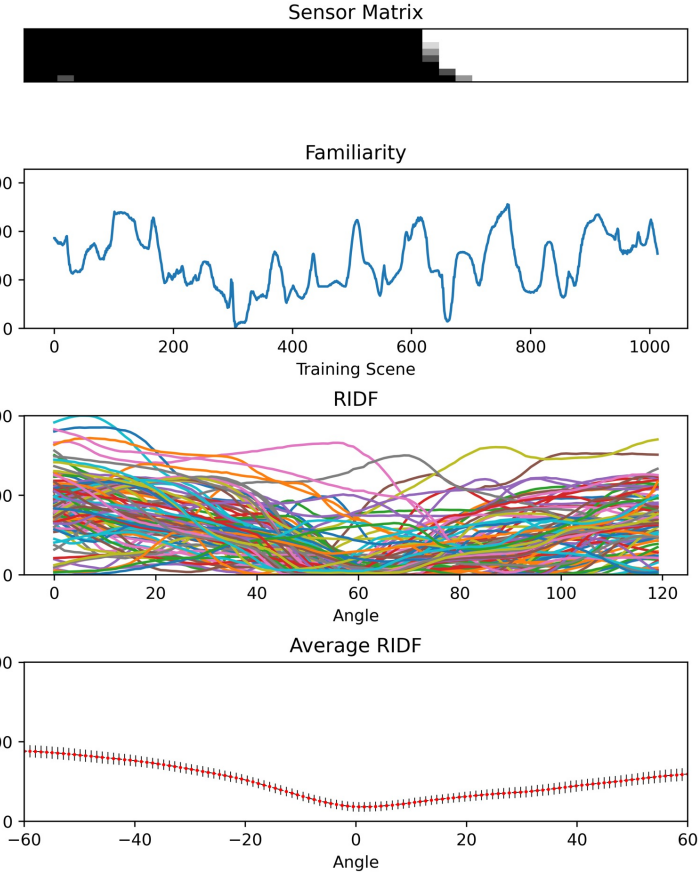


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 7096.35; RMSD/dist: 17.741; TD: 3912; p90: 56; p50: 34; complete: 0

20%

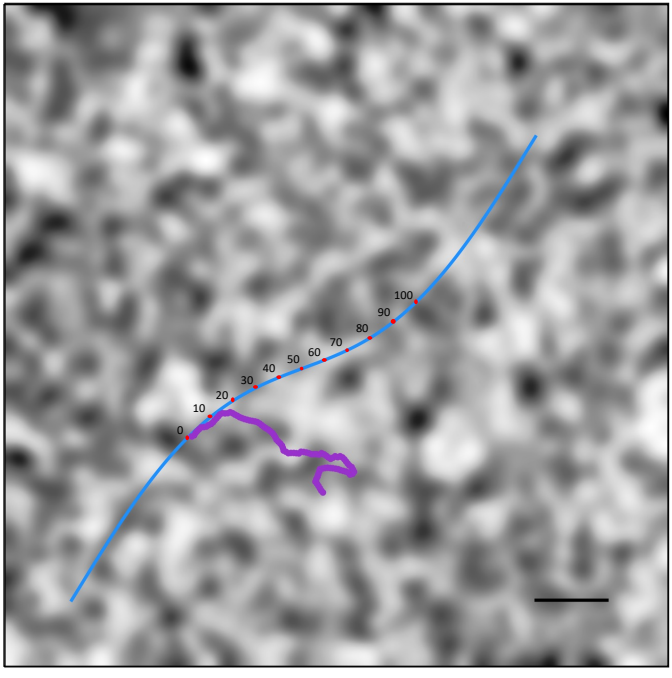


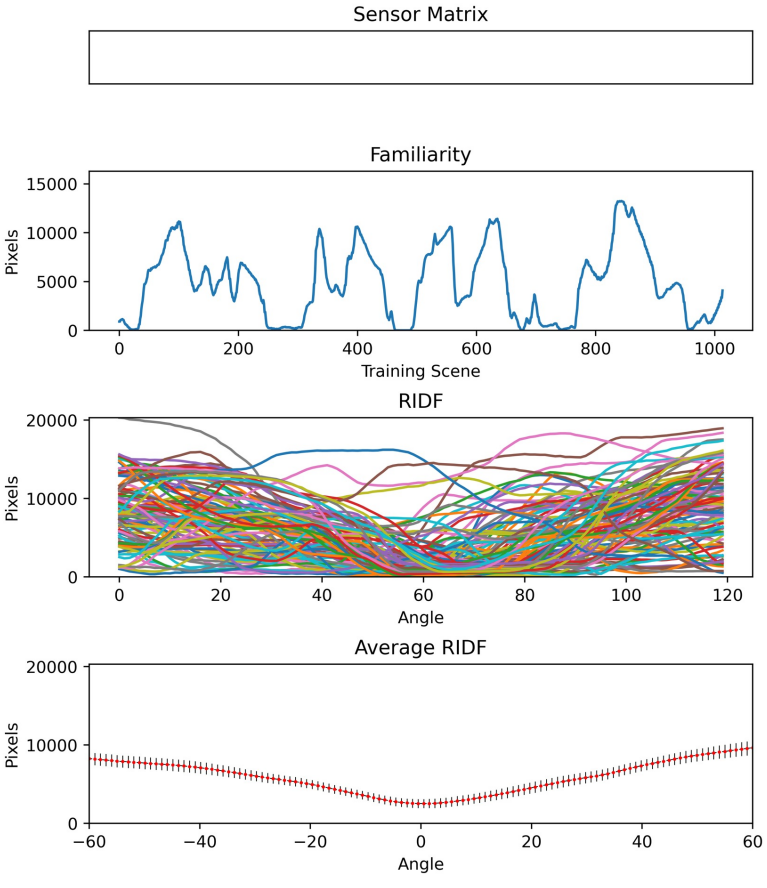


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2133.51; RMSD/dist: 5.334; TD: 4215; p90: 46; p50: 28; complete: 0

0%

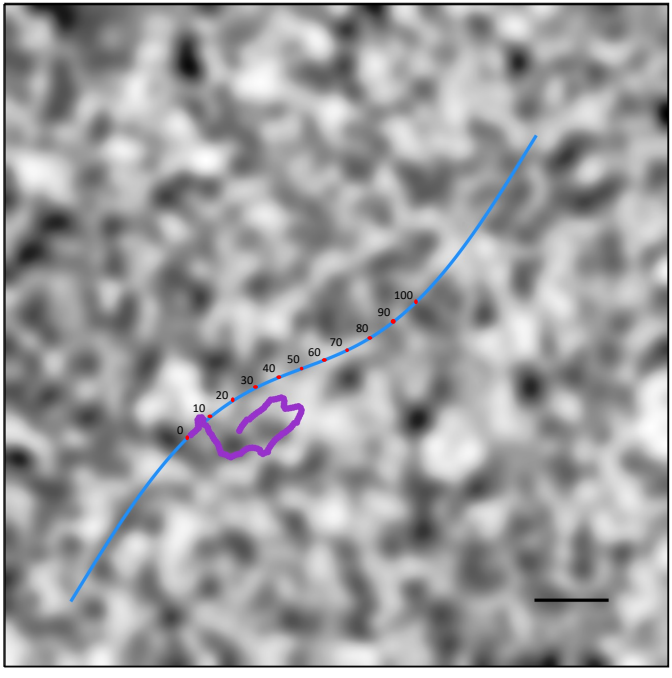


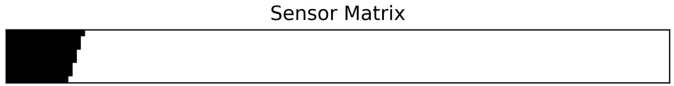


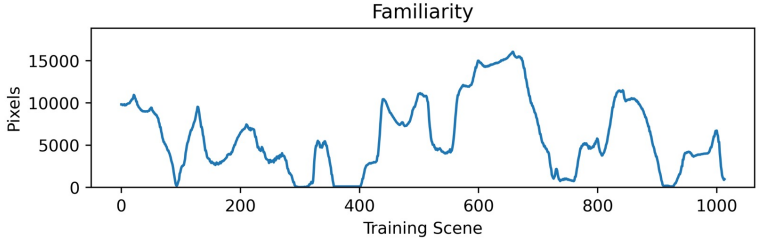
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

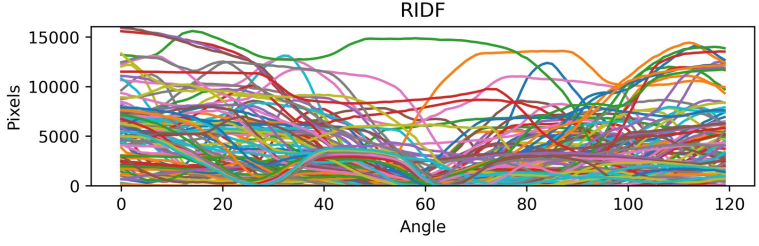
Navigation stats: RMSD error: 9734.75; RMSD/dist: 24.337; TD: 4026; p90: 62; p50: 34; complete: 0

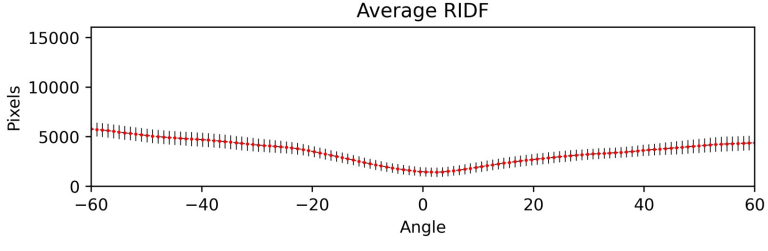
0%





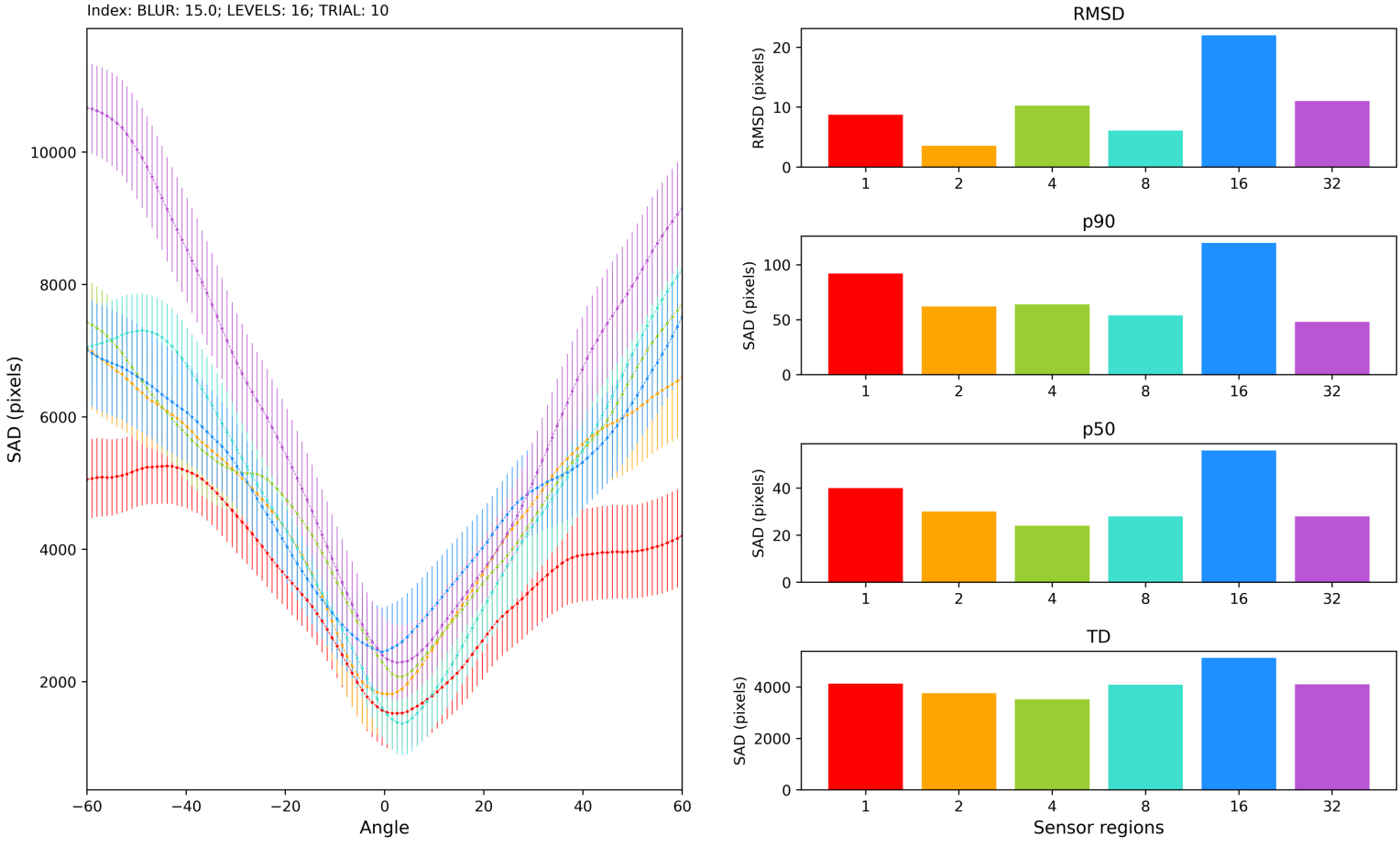




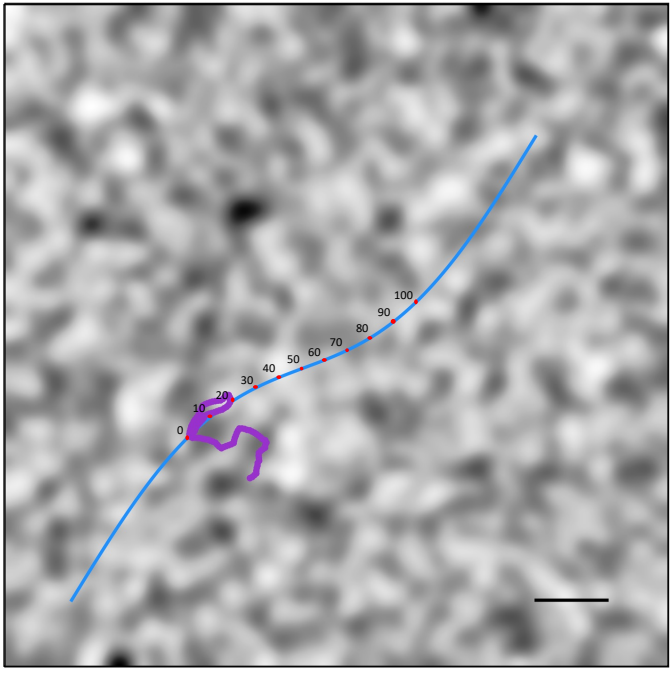


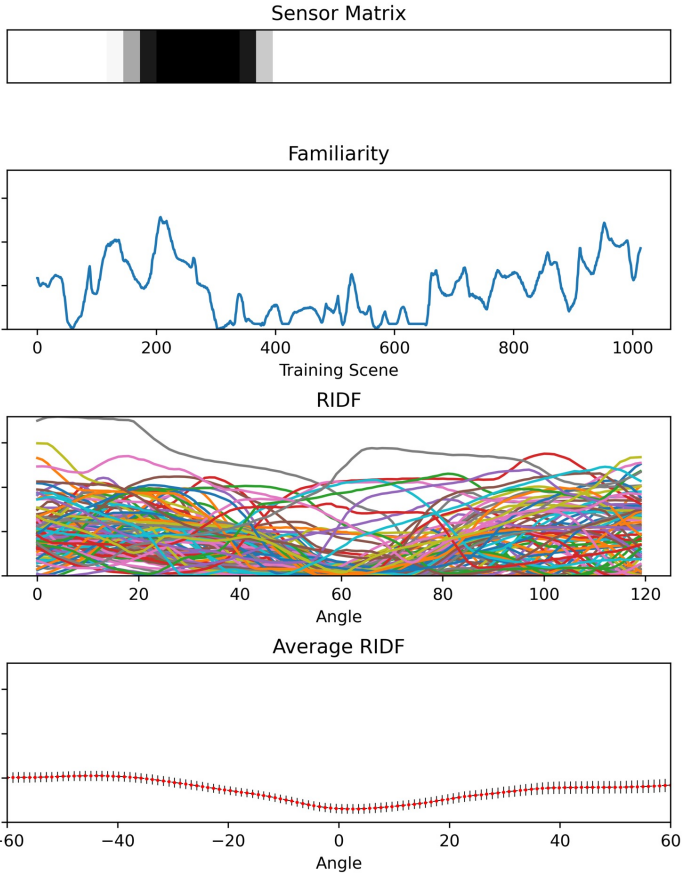
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 4745.64; RMSD/dist: 11.864; TD: 4882; p90: 120; p50: 48; complete: 0


Index: BLUR: 15.0; LEVELS: 16; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

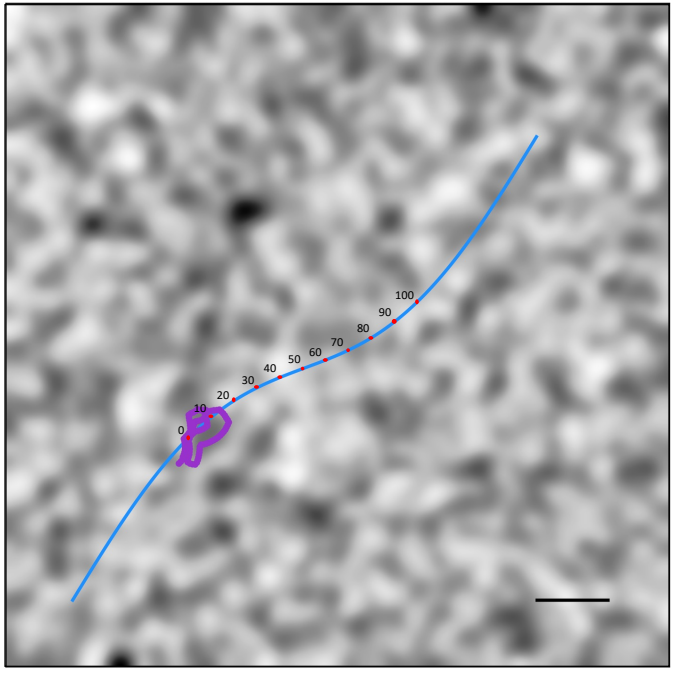


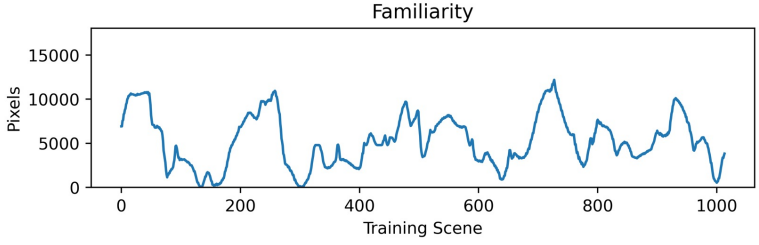


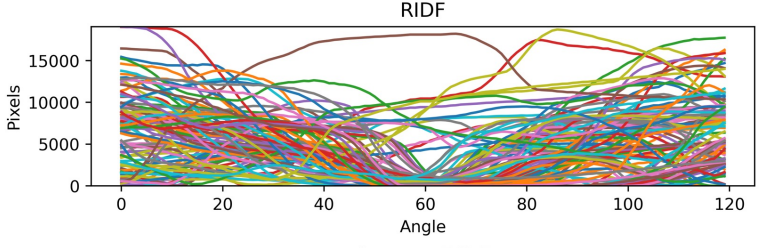
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

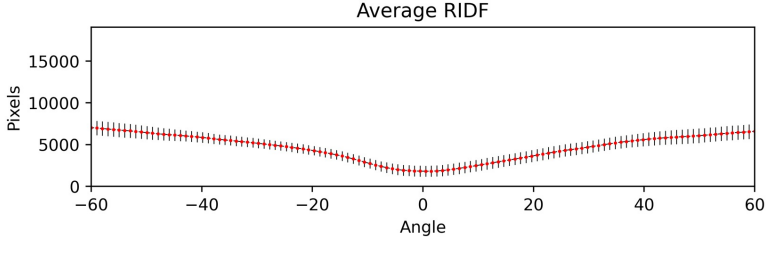
Navigation stats: RMSD error: 3489.11; RMSD/dist: 8.723; TD: 4138; p90: 92; p50: 40; complete: 0

0%





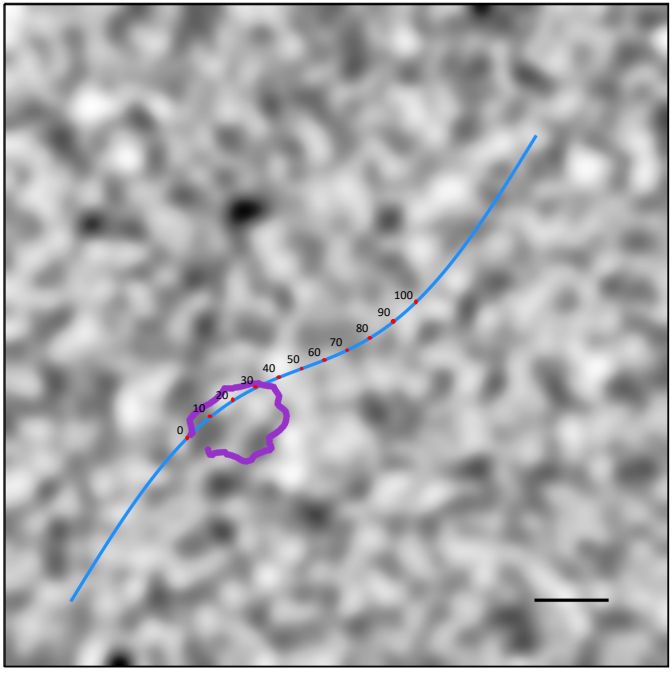


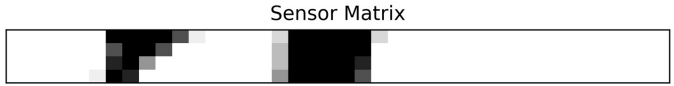


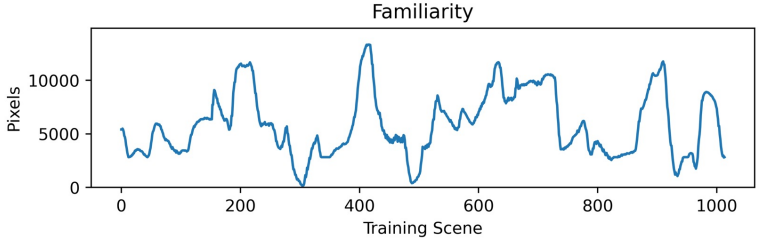
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

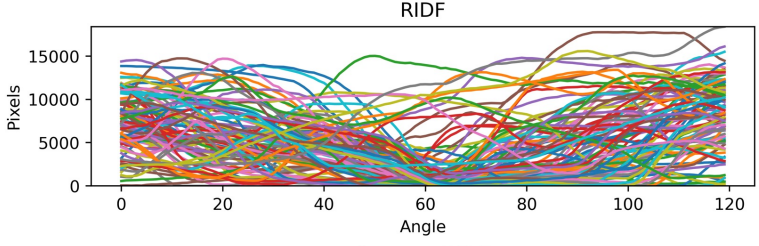
Navigation stats: RMSD error: 1420.67; RMSD/dist: 3.552; TD: 3765; p90: 62; p50: 30; complete: 0

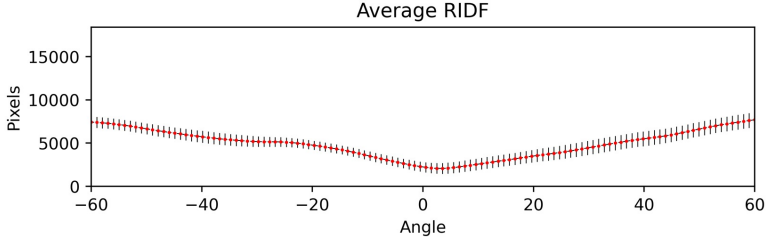
0%







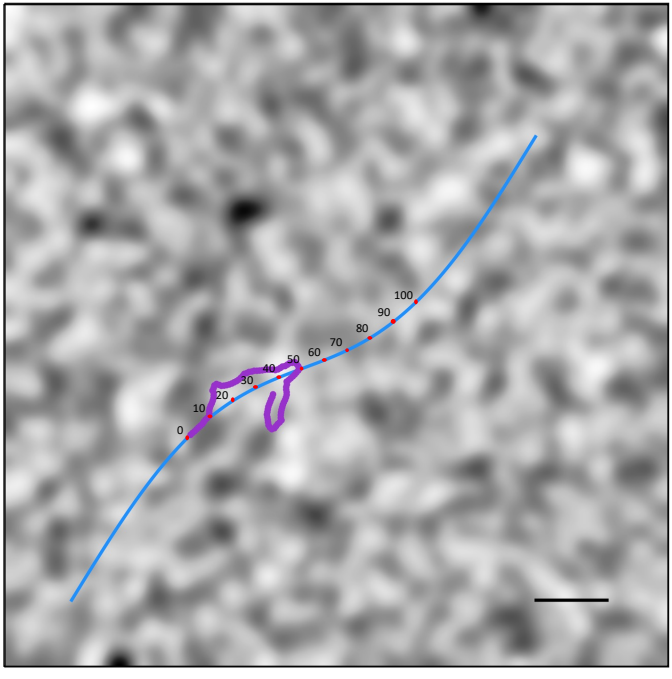


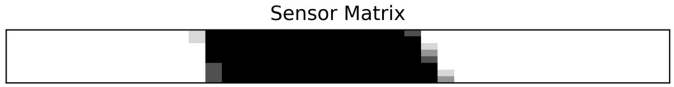


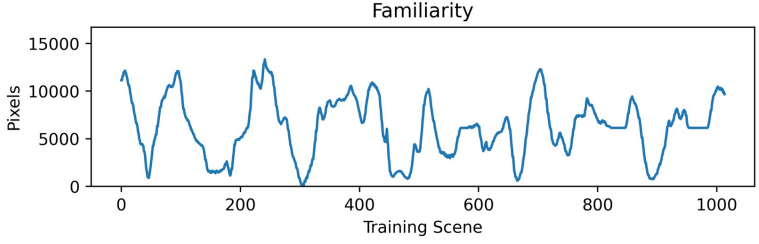
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

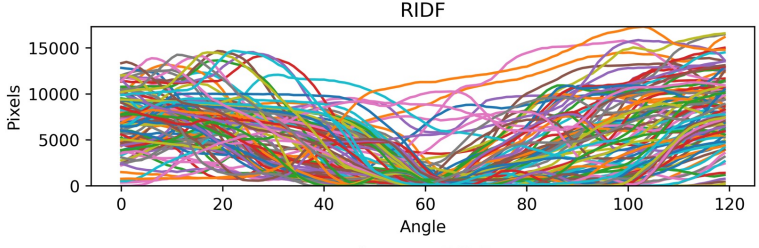
Navigation stats: RMSD error: 4108.65; RMSD/dist: 10.272; TD: 3524; p90: 64; p50: 24; complete: 0

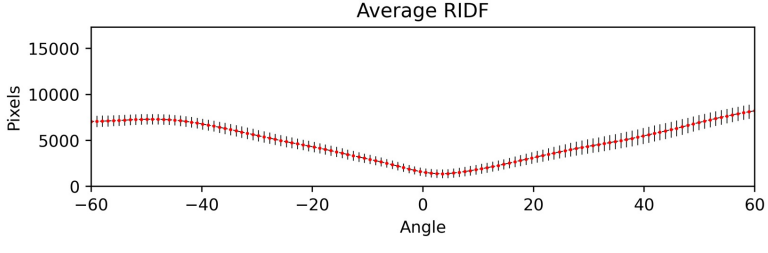
10%







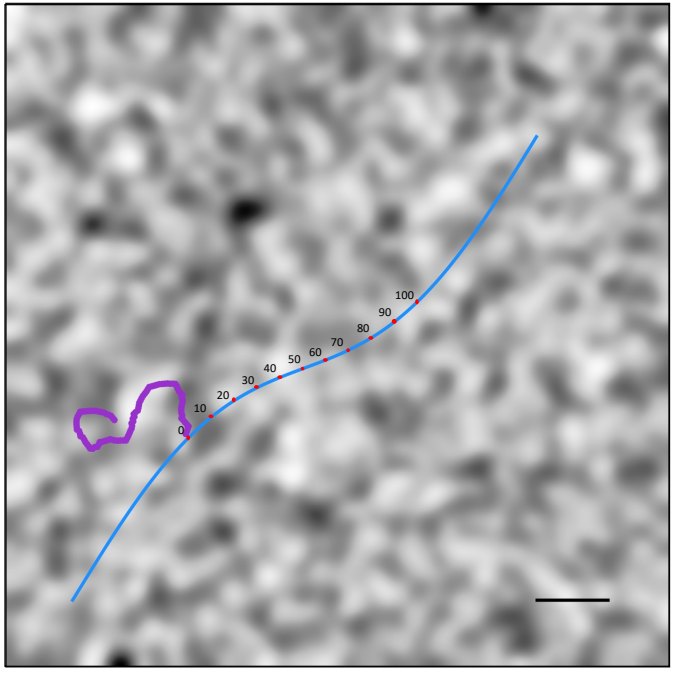


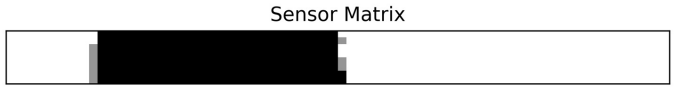


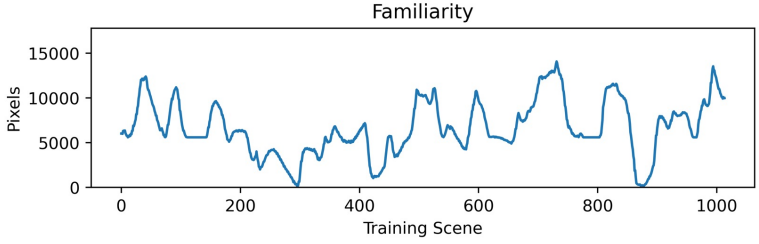
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

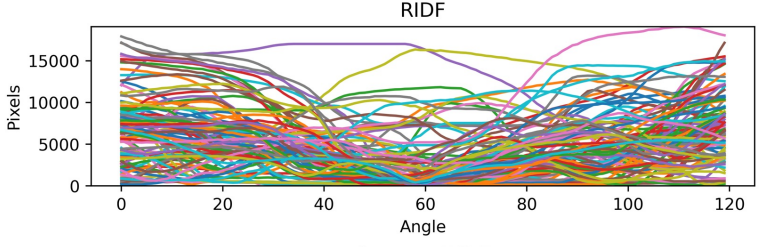
Navigation stats: RMSD error: 2433.53; RMSD/dist: 6.084; TD: 4091; p90: 54; p50: 28; complete: 0

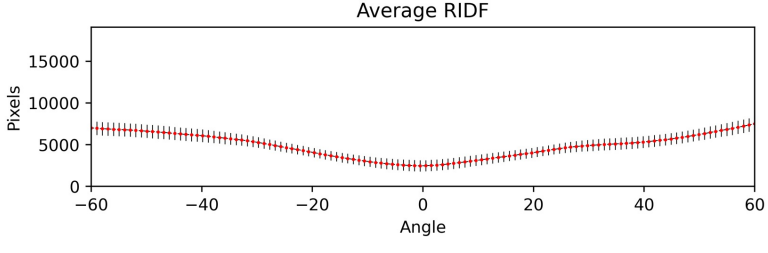
0%







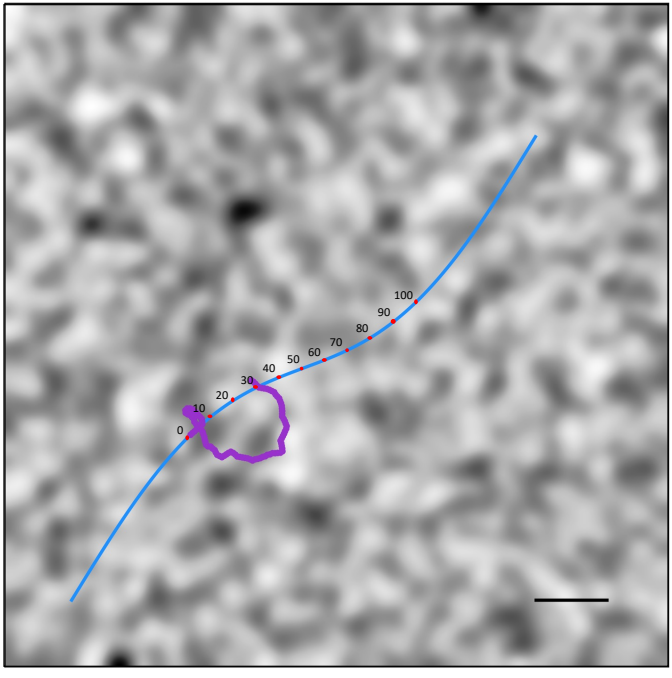


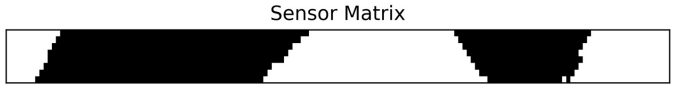


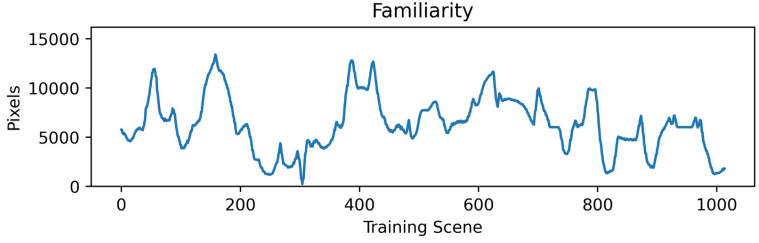
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

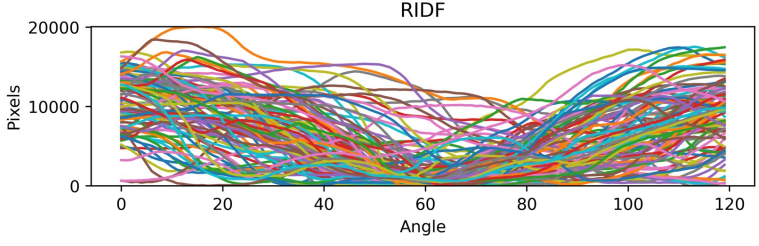
Navigation stats: RMSD error: 8810.07; RMSD/dist: 22.025; TD: 5135; p90: 120; p50: 56; complete: 0

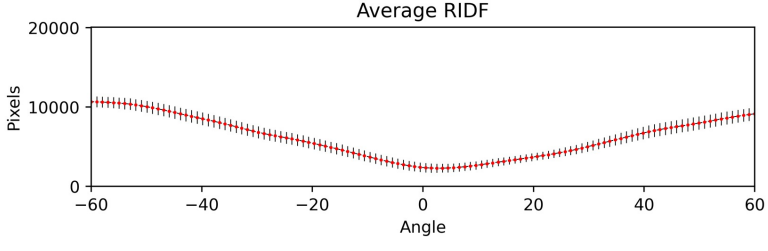
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 15; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4410.03; RMSD/dist: 11.025; TD: 4110; p90: 48; p50: 28; complete: 0