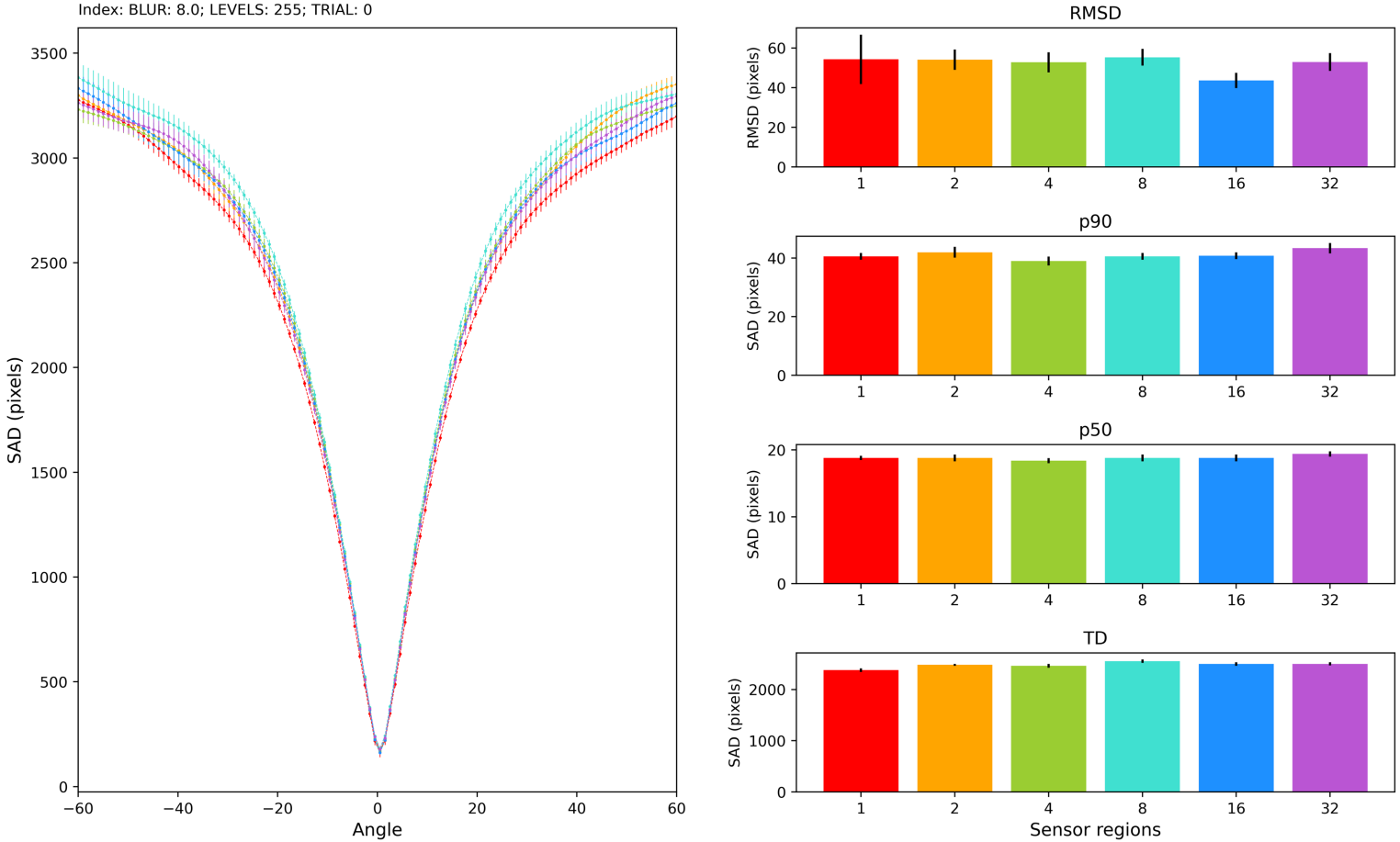
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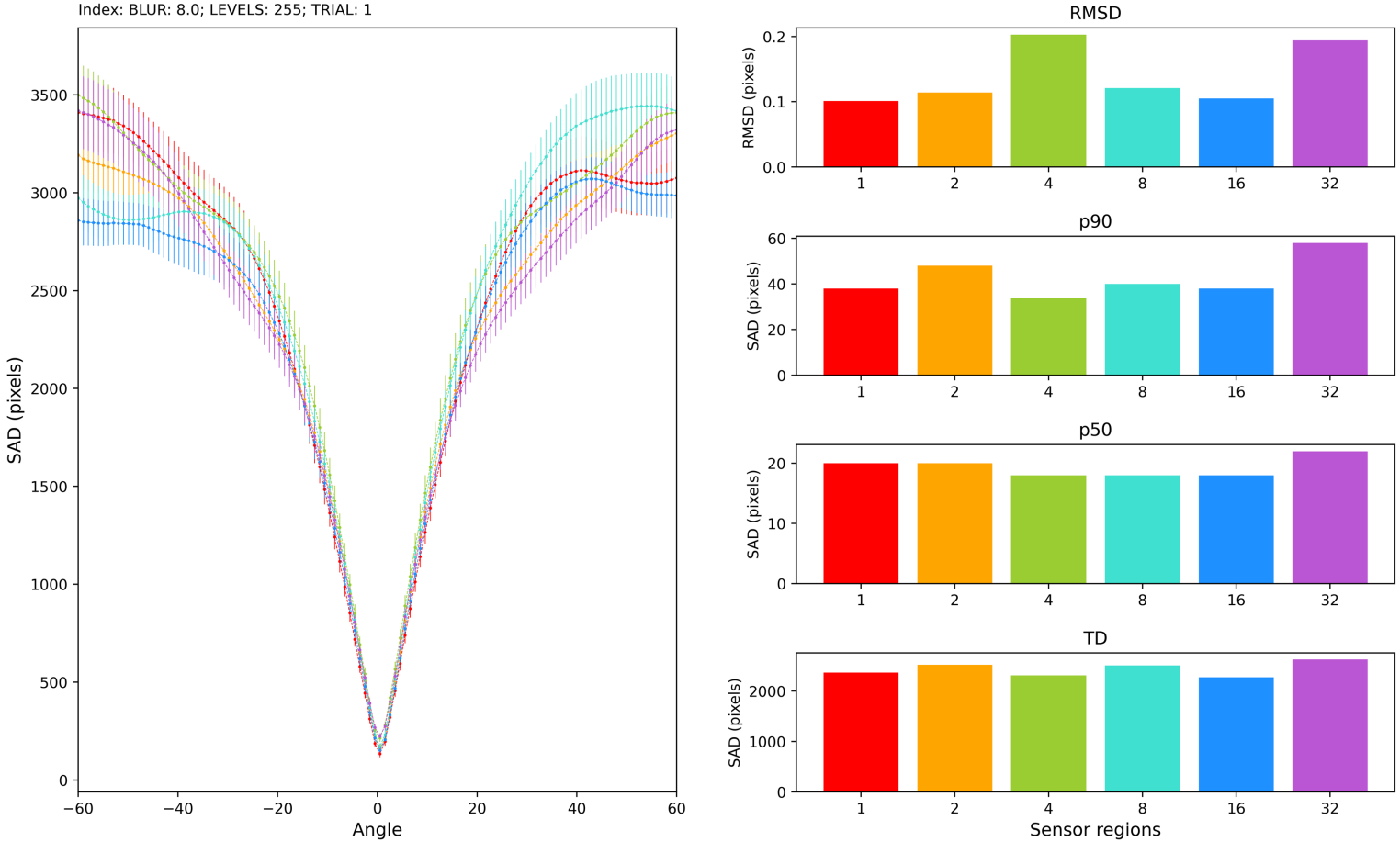
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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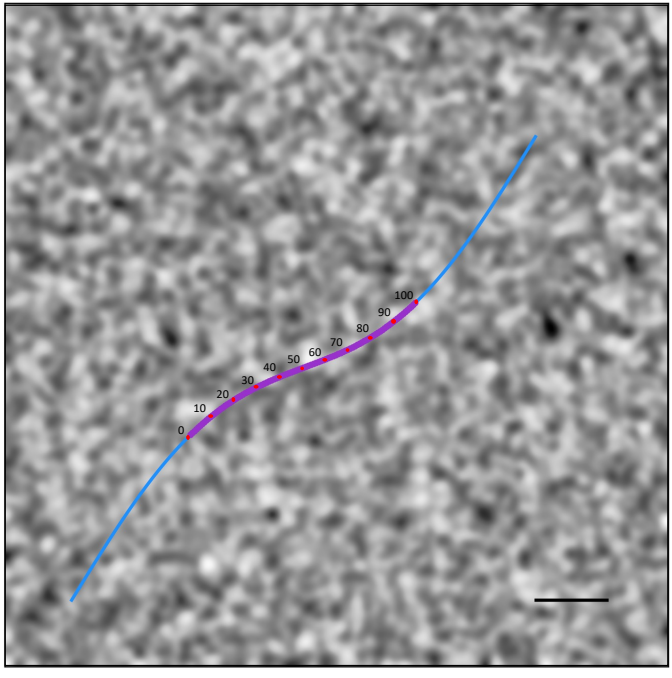
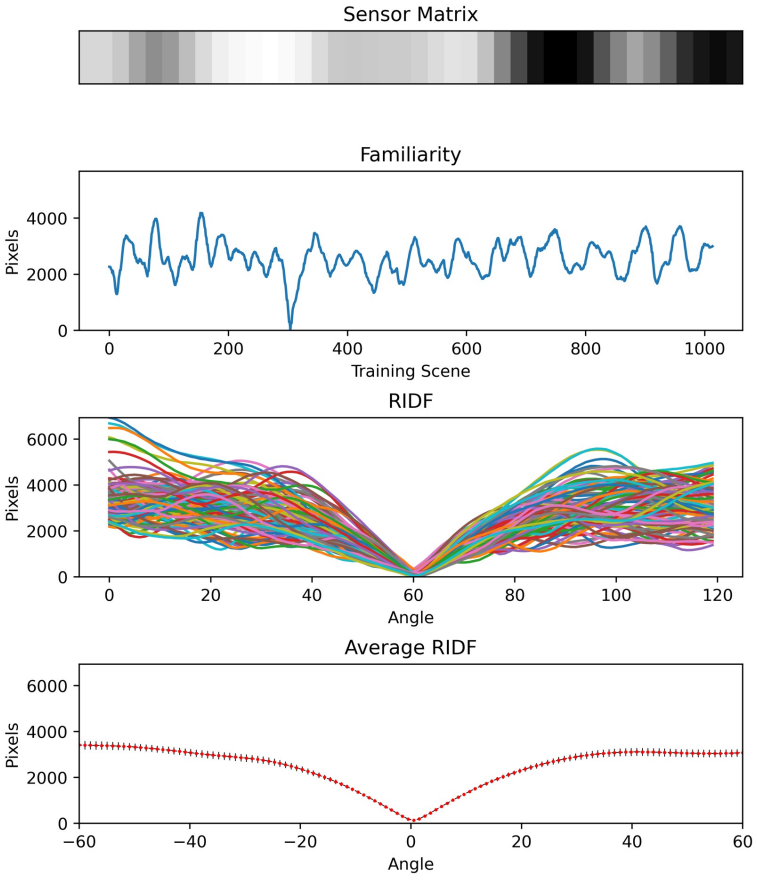
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

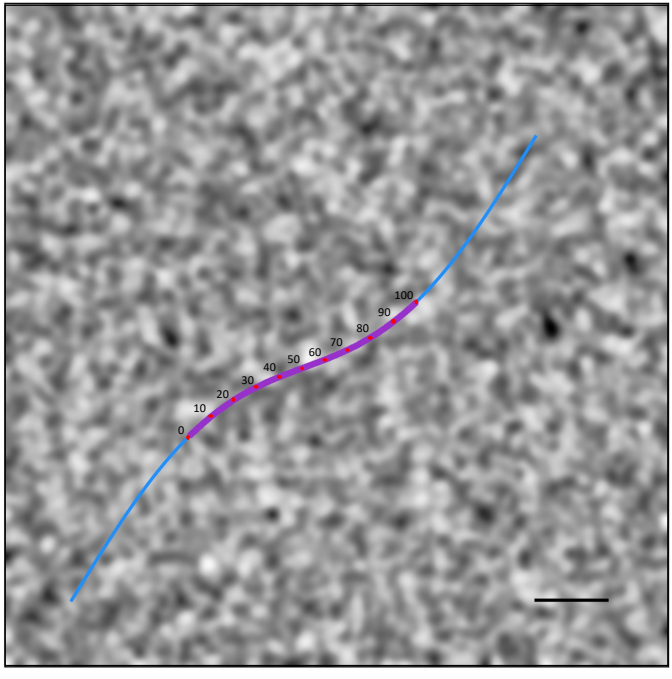


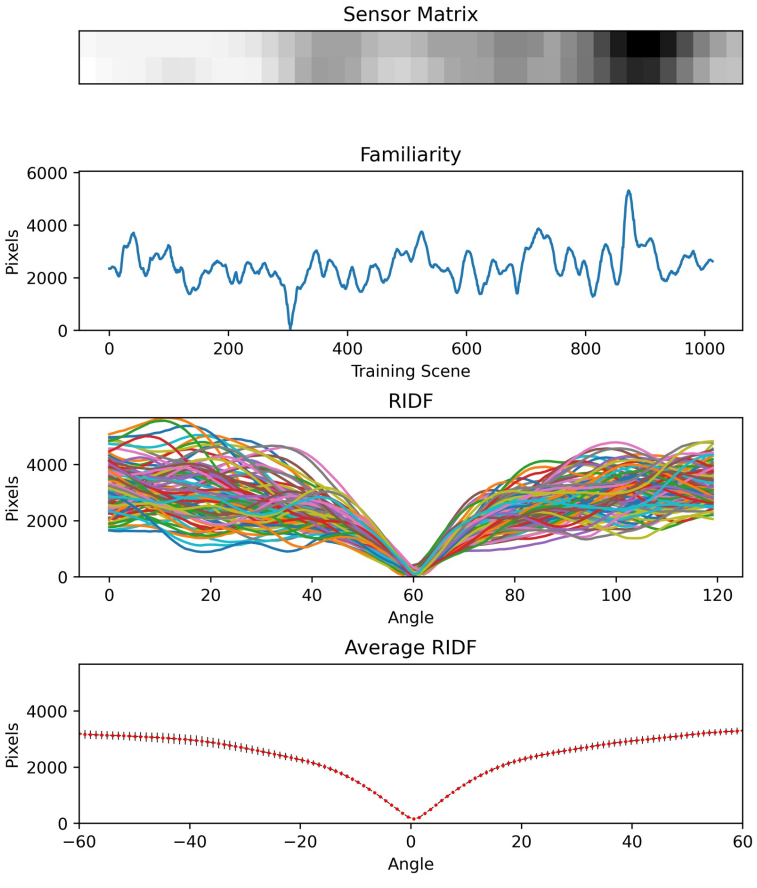


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 40.54; RMSD/dist: 0.101; TD: 2363; p90: 38; p50: 20; complete: 0

100%

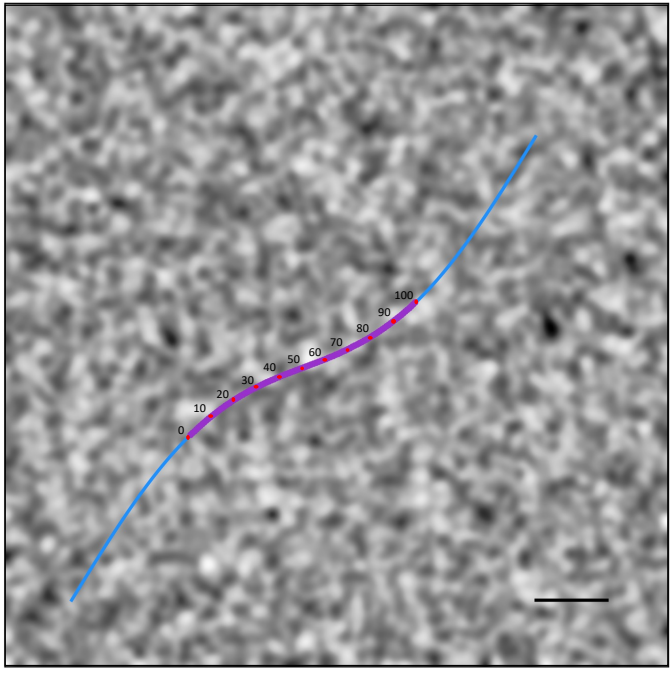


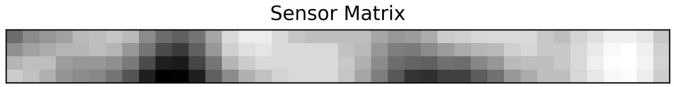


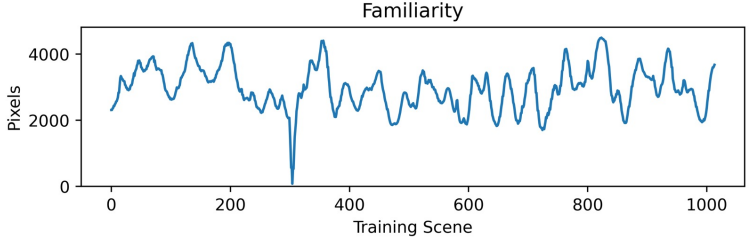
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

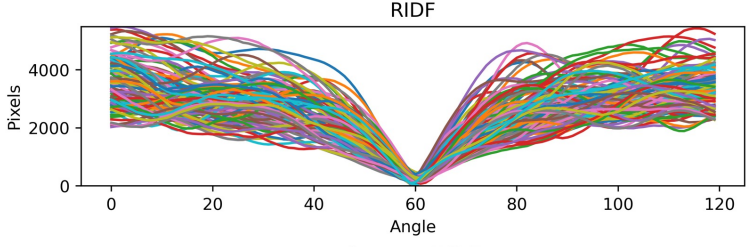
Navigation stats: RMSD error: 45.65; RMSD/dist: 0.114; TD: 2520; p90: 48; p50: 20; complete: 0

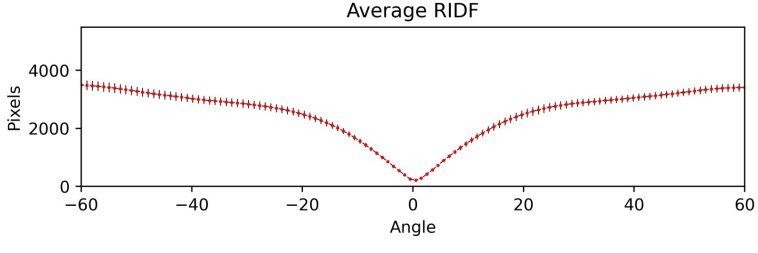
100%







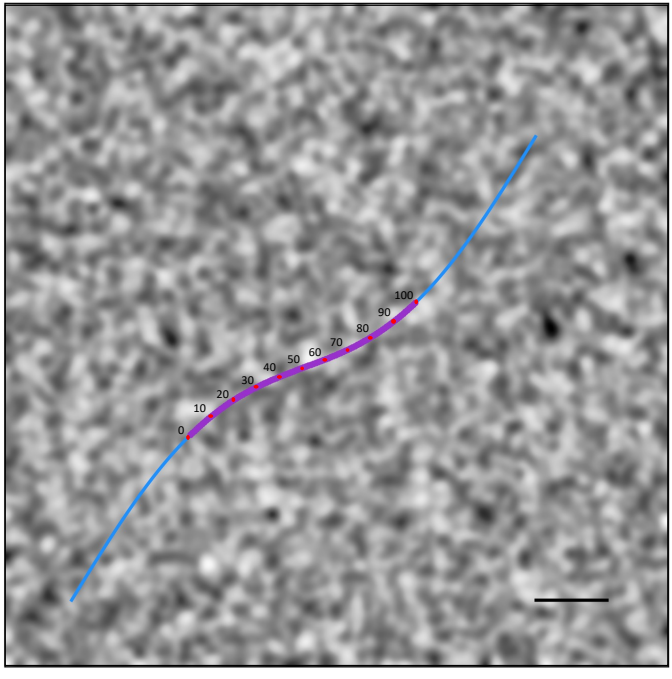


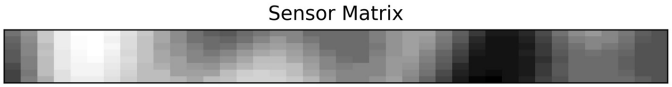


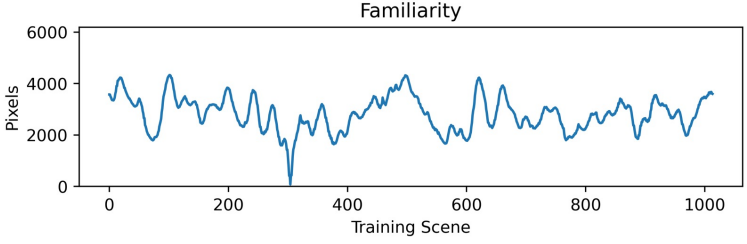
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

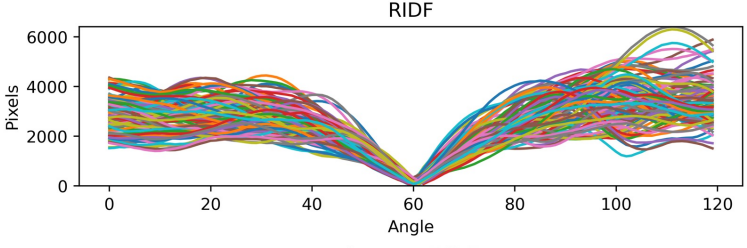
Navigation stats: RMSD error: 81.01; RMSD/dist: 0.203; TD: 2311; p90: 34; p50: 18; complete: 0

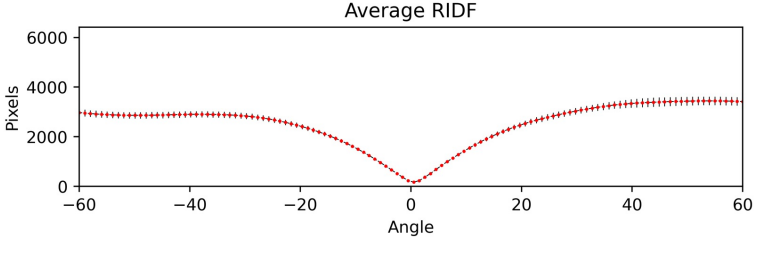
100%







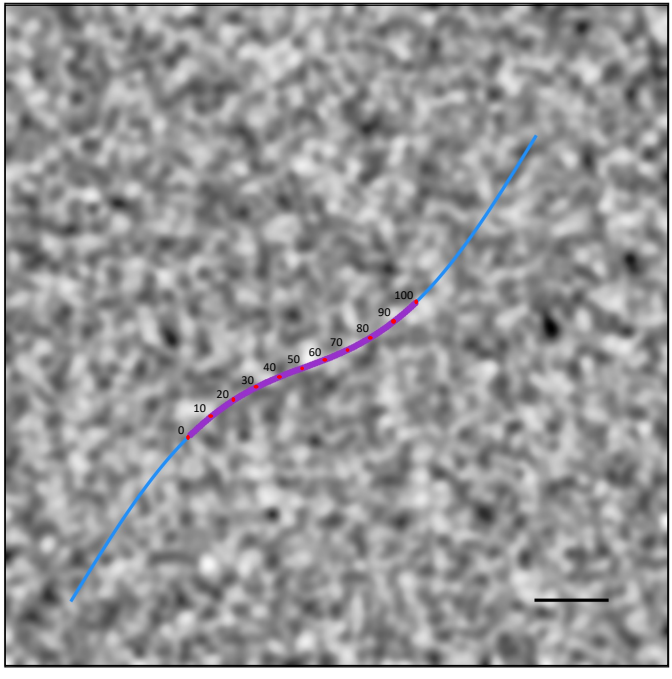


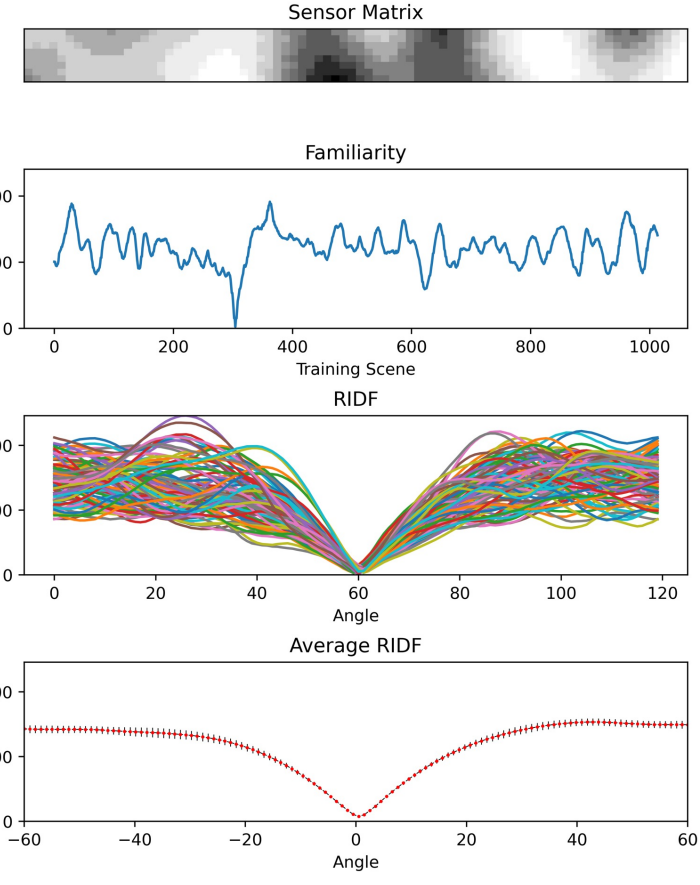


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 48.38; RMSD/dist: 0.121; TD: 2507; p90: 40; p50: 18; complete: 0

100%

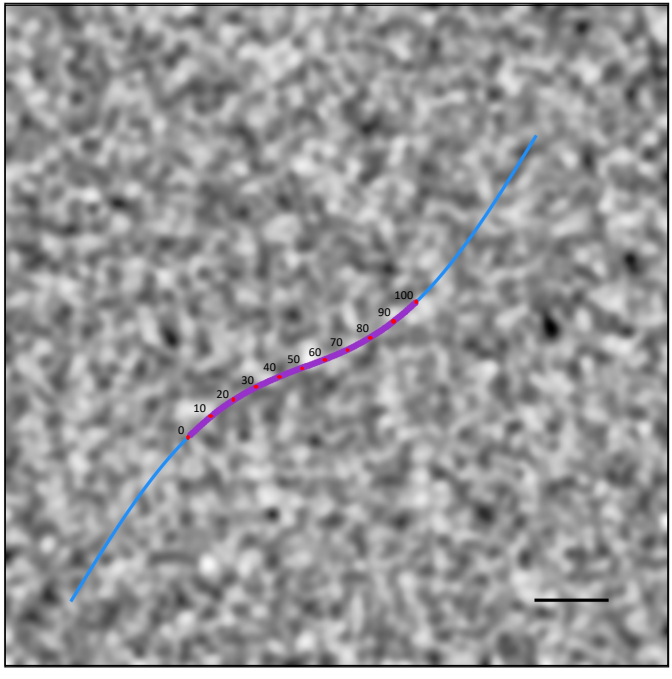


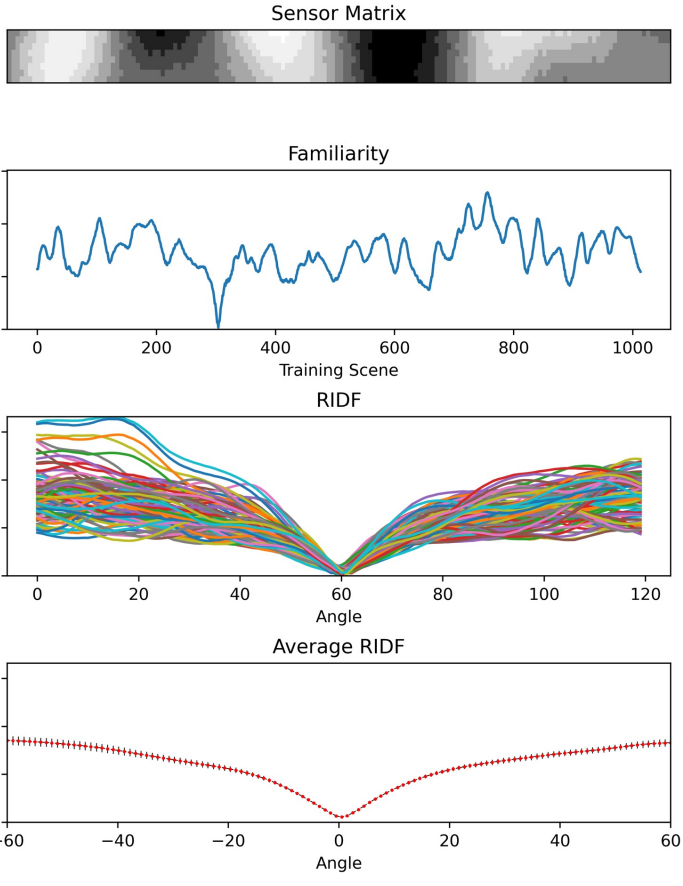


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 41.92; RMSD/dist: 0.105; TD: 2271; p90: 38; p50: 18; complete: 0

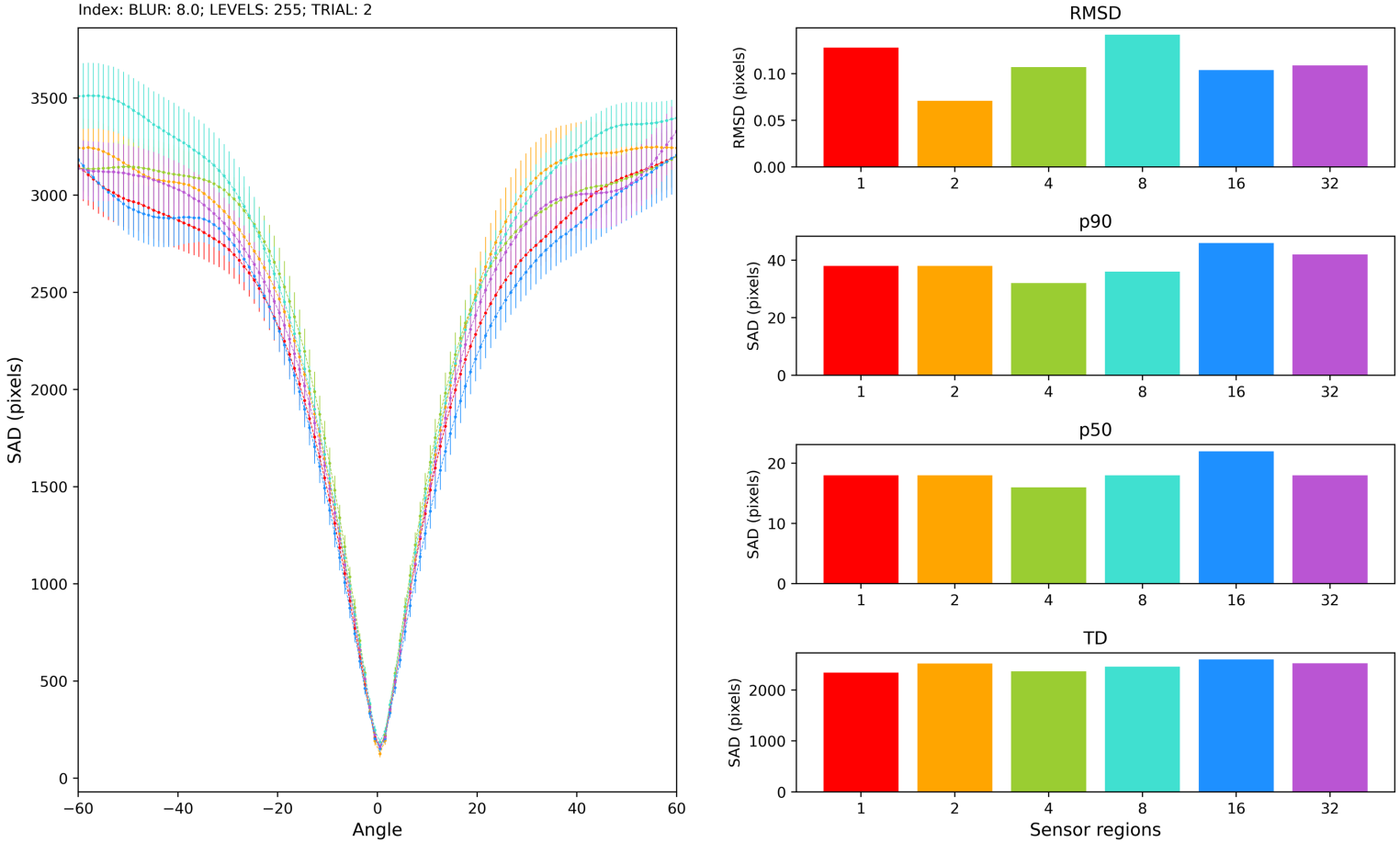
100%



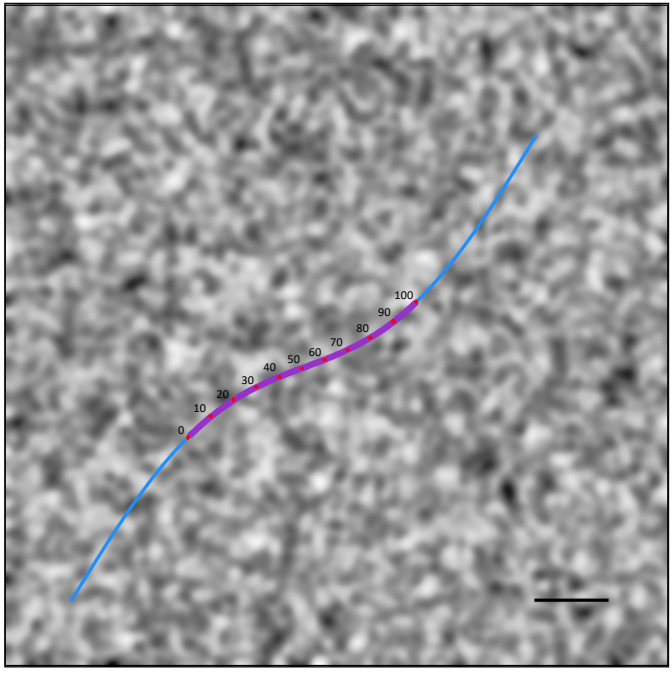


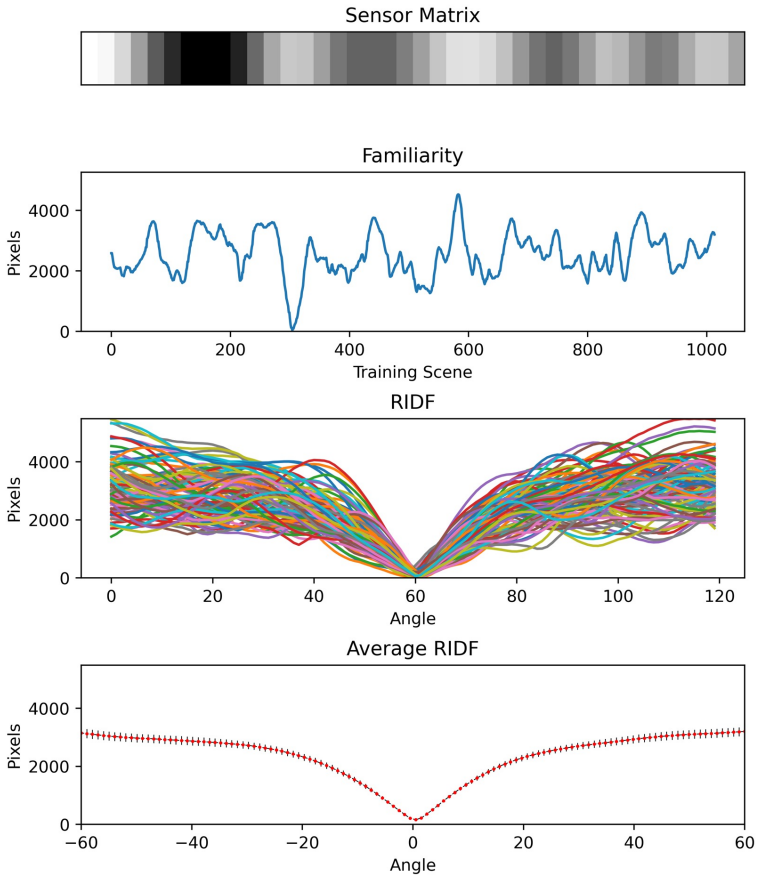
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 77.79; RMSD/dist: 0.194; TD: 2623; p90: 58; p50: 22; complete: 0


Index: BLUR: 8.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

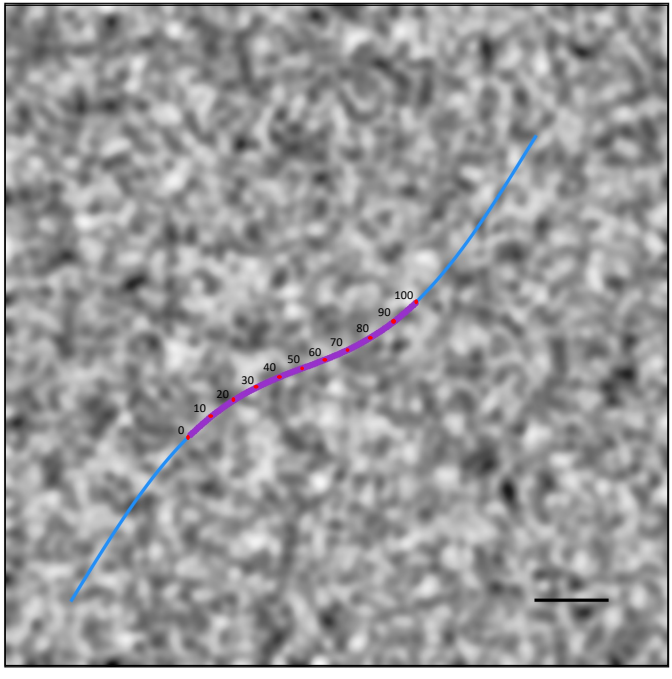


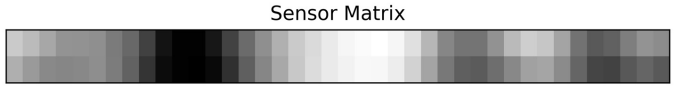


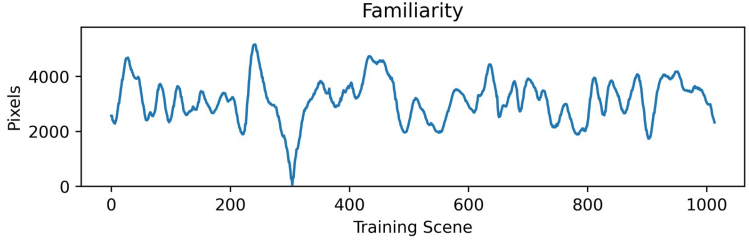
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

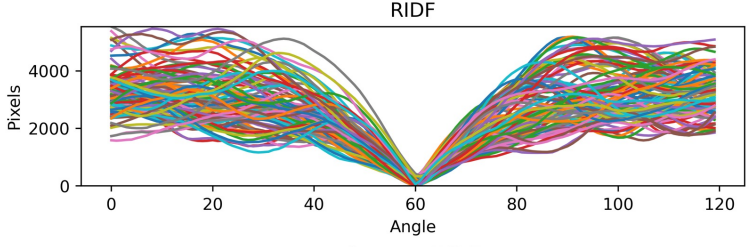
Navigation stats: RMSD error: 51.16; RMSD/dist: 0.128; TD: 2341; p90: 38; p50: 18; complete: 0

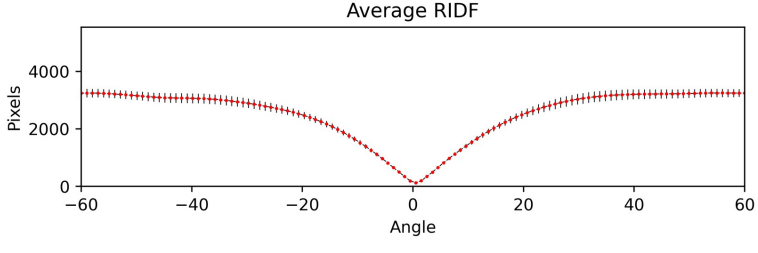
100%







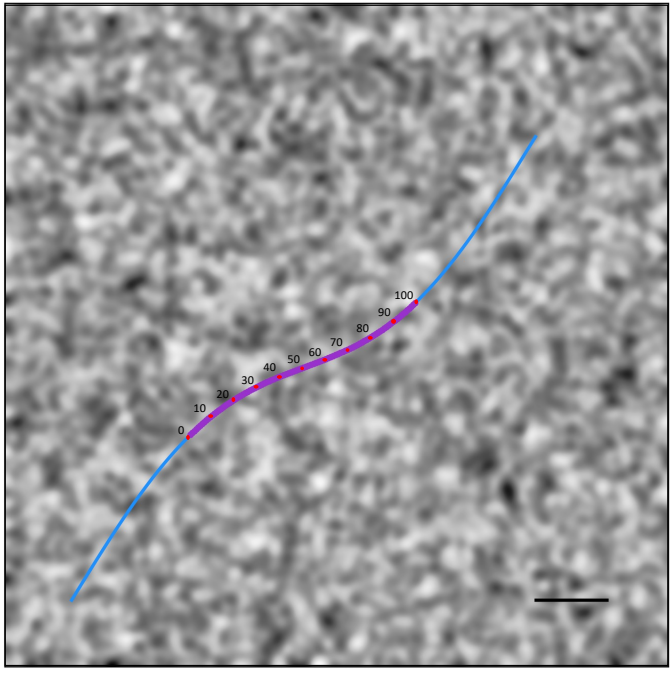


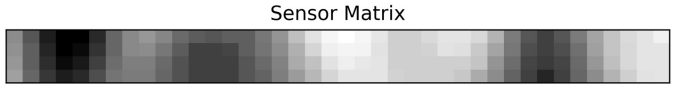


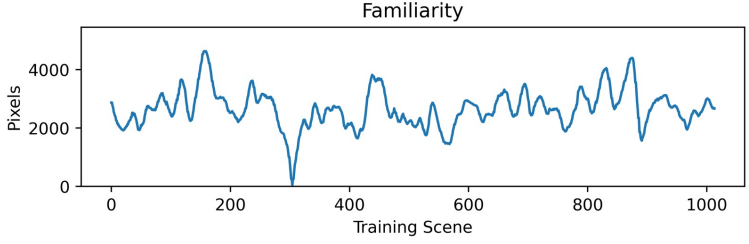
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

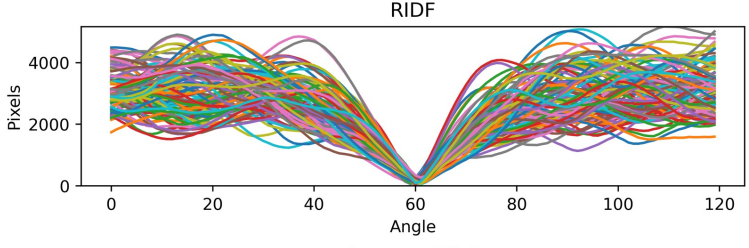
Navigation stats: RMSD error: 28.34; RMSD/dist: 0.071; TD: 2521; p90: 38; p50: 18; complete: 0

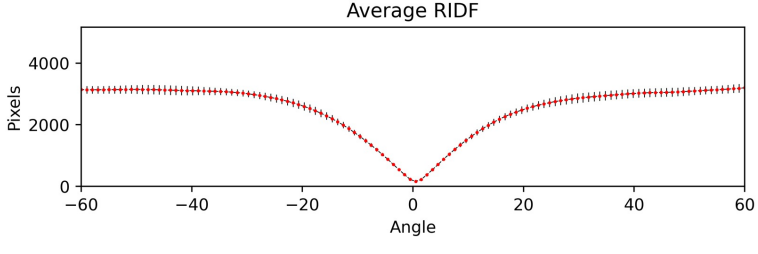
100%







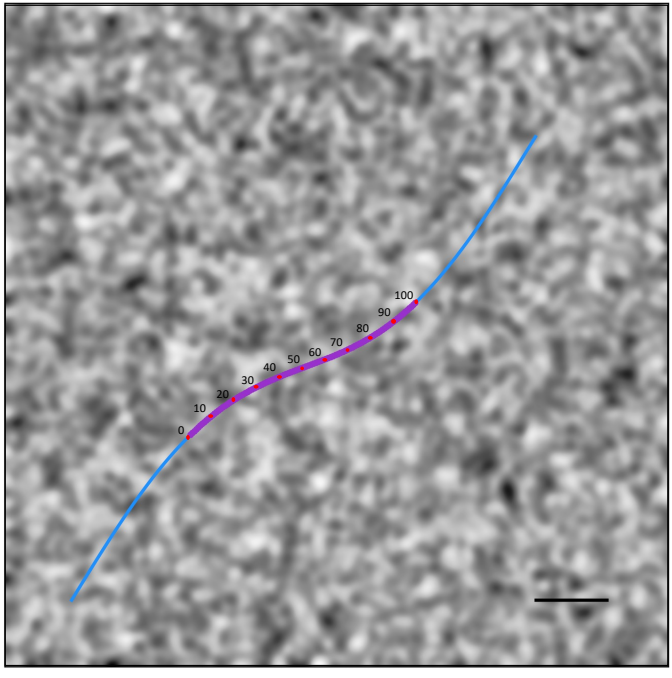


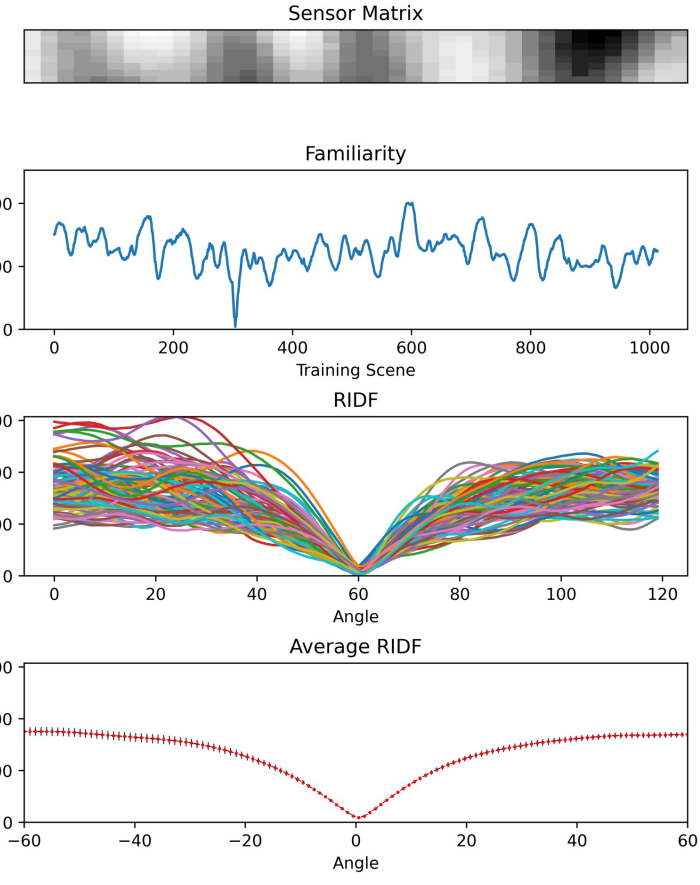


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 42.64; RMSD/dist: 0.107; TD: 2365; p90: 32; p50: 16; complete: 0

100%

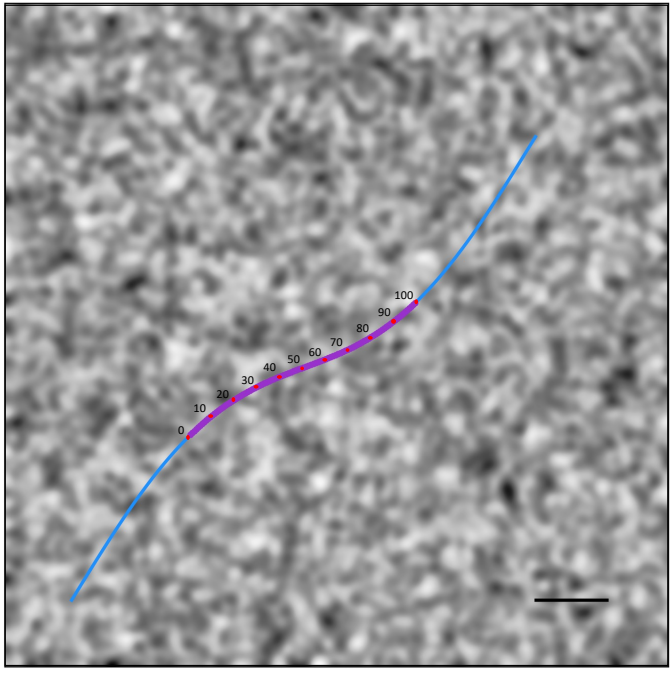


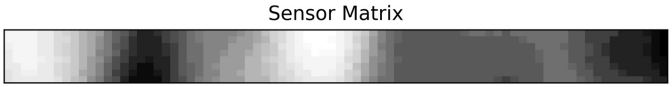


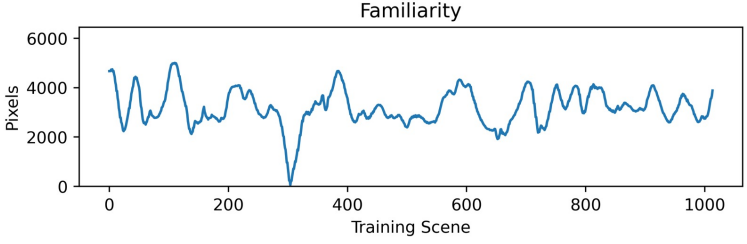
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

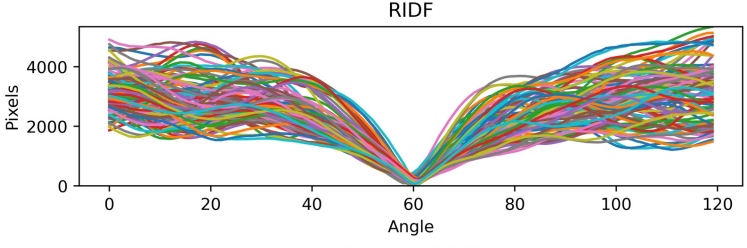
Navigation stats: RMSD error: 56.72; RMSD/dist: 0.142; TD: 2457; p90: 36; p50: 18; complete: 0

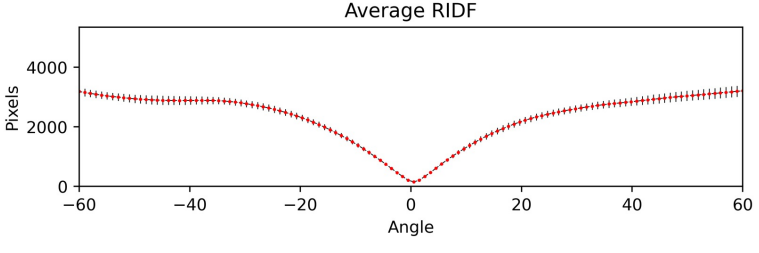
100%







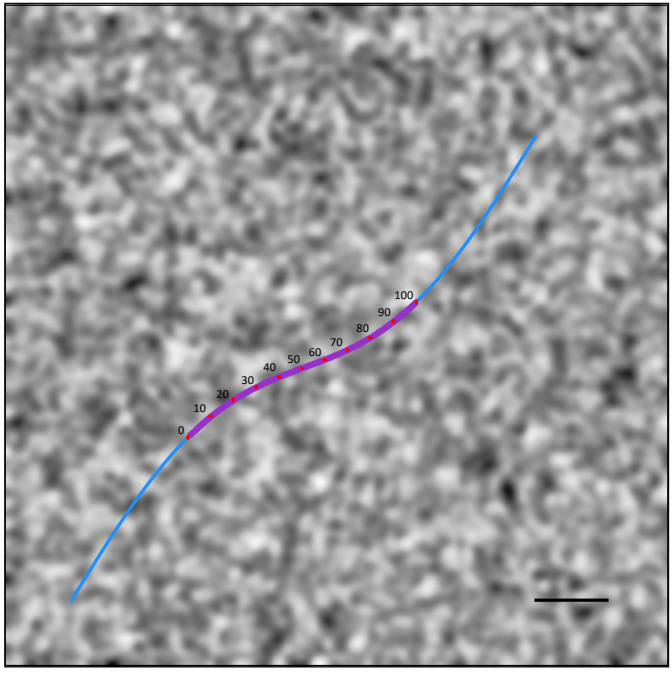


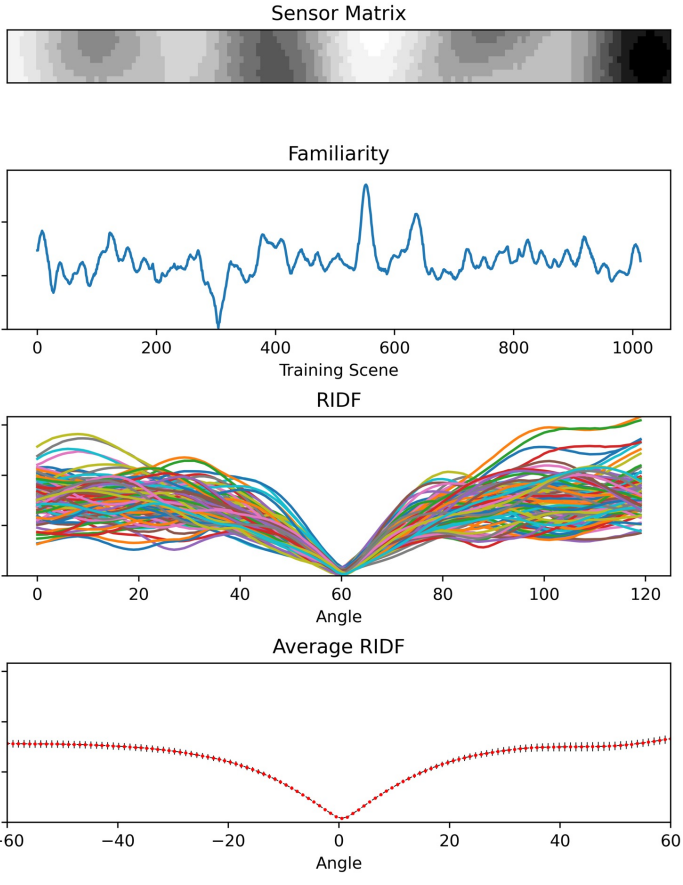


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 41.66; RMSD/dist: 0.104; TD: 2597; p90: 46; p50: 22; complete: 0

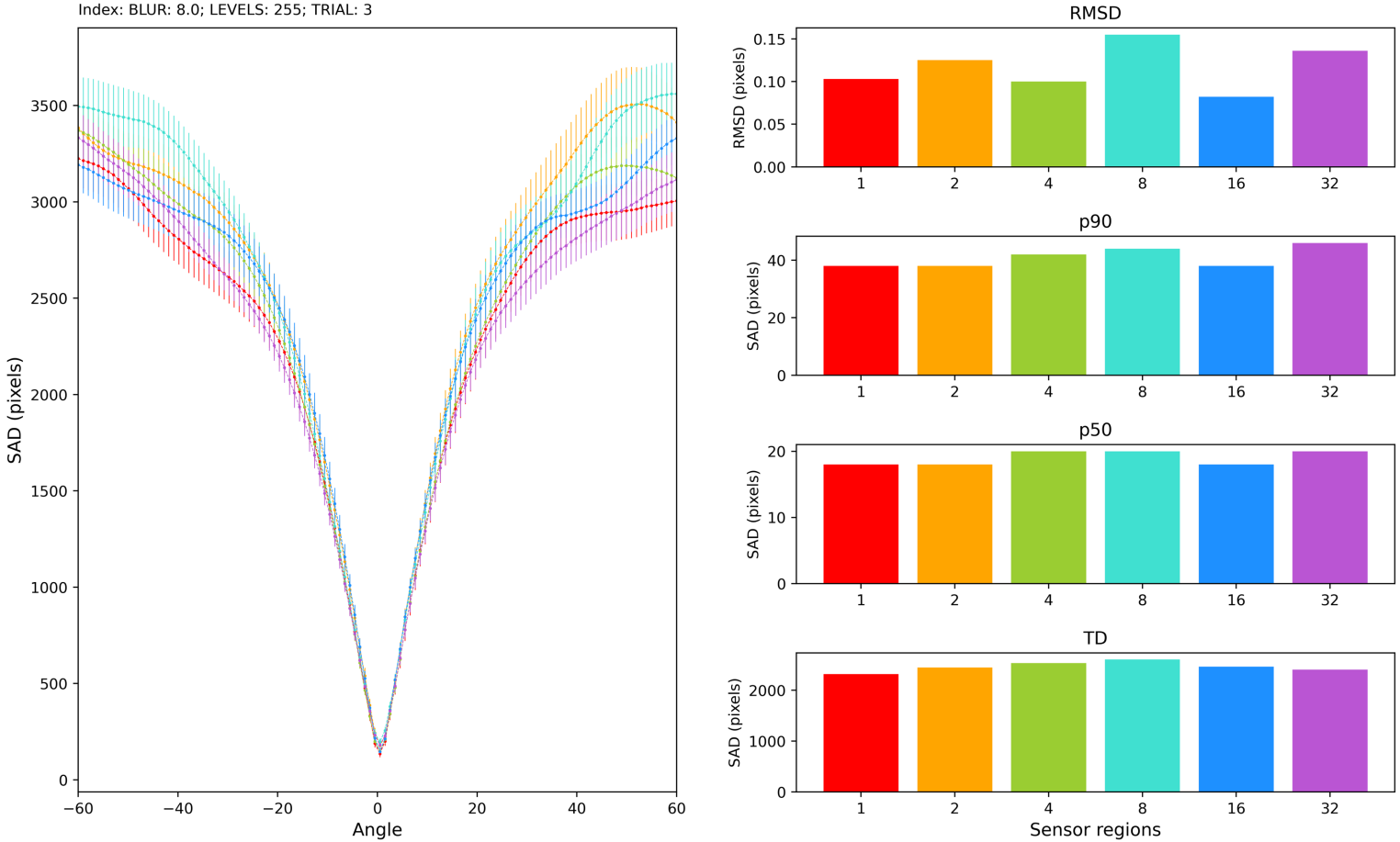
100%



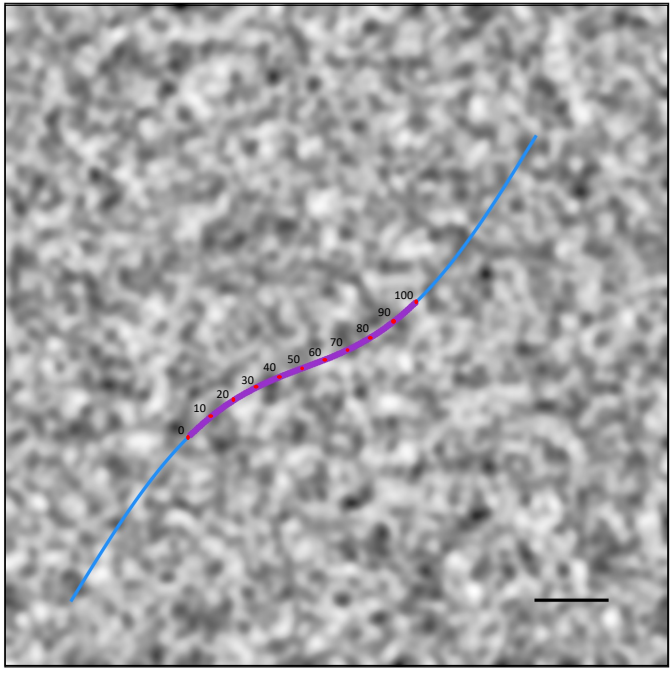


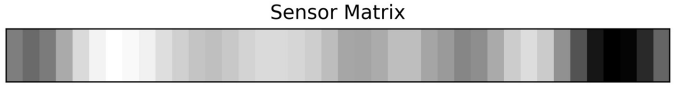
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

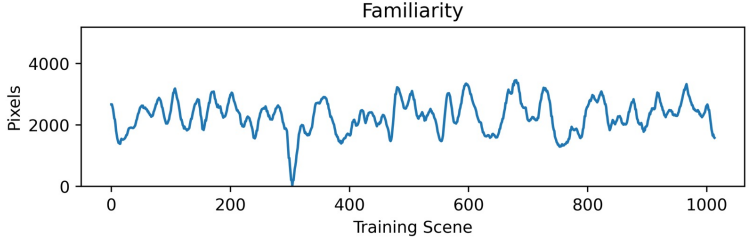
Navigation stats: RMSD error: 43.50; RMSD/dist: 0.109; TD: 2525; p90: 42; p50: 18; complete: 0

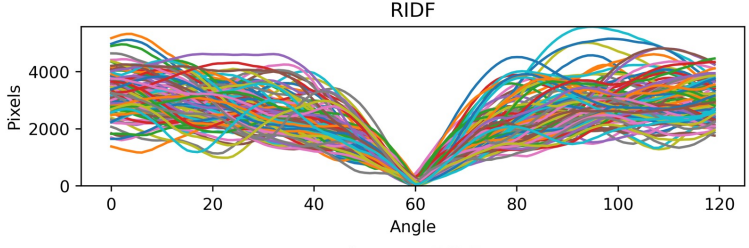

Index: BLUR: 8.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

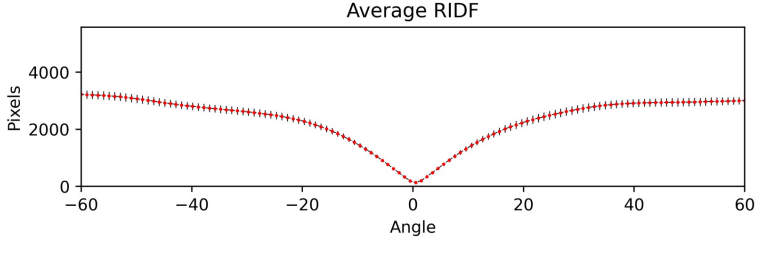
100%







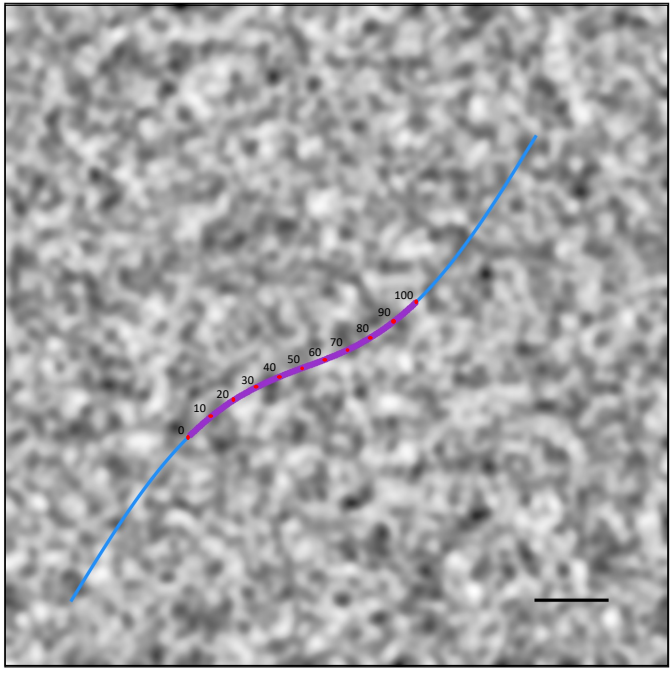


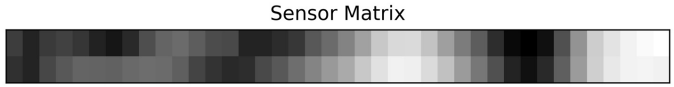


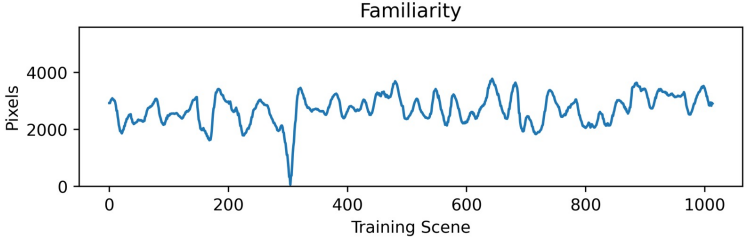
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

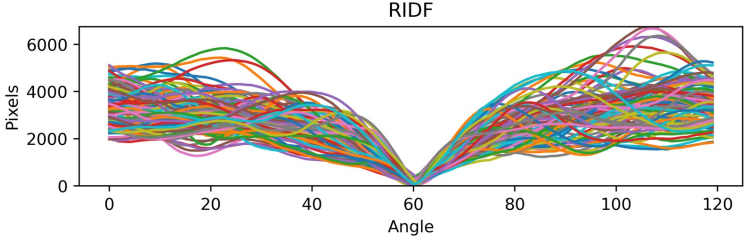
Navigation stats: RMSD error: 41.33; RMSD/dist: 0.103; TD: 2319; p90: 38; p50: 18; complete: 0

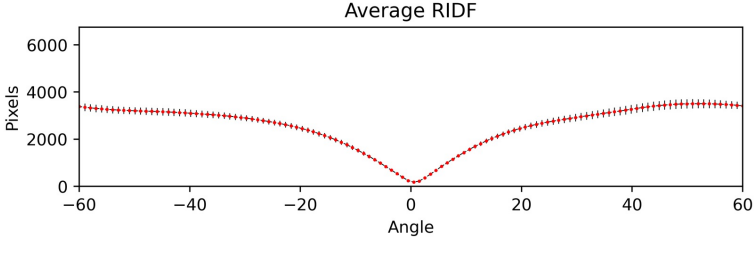
100%







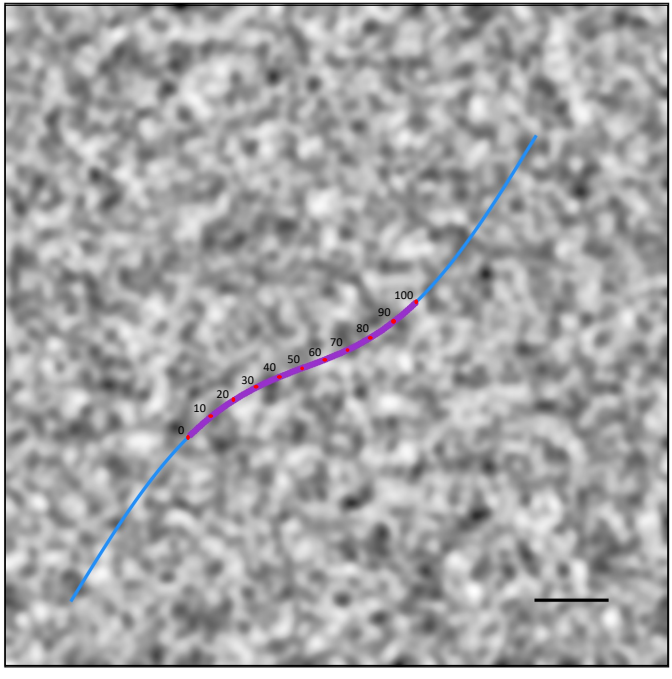


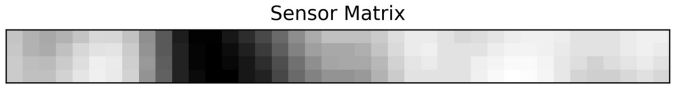


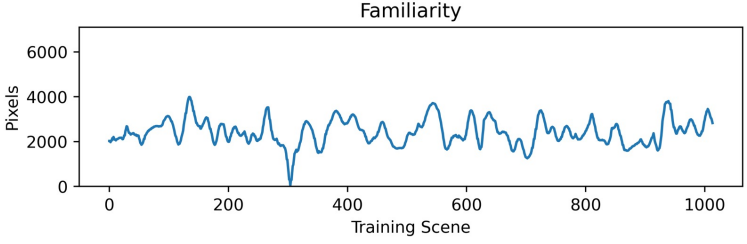
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

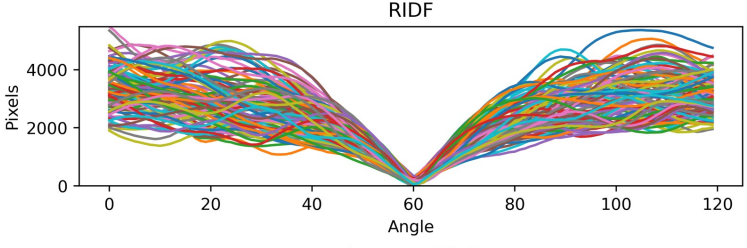
Navigation stats: RMSD error: 50.01; RMSD/dist: 0.125; TD: 2445; p90: 38; p50: 18; complete: 0

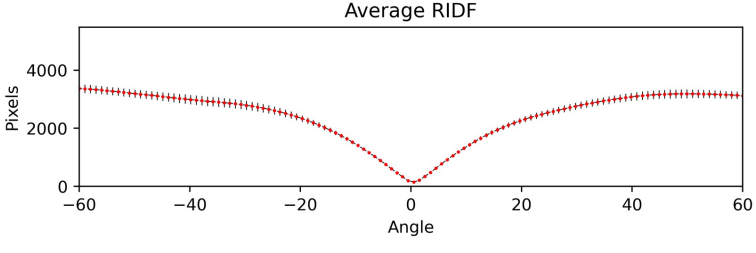
100%







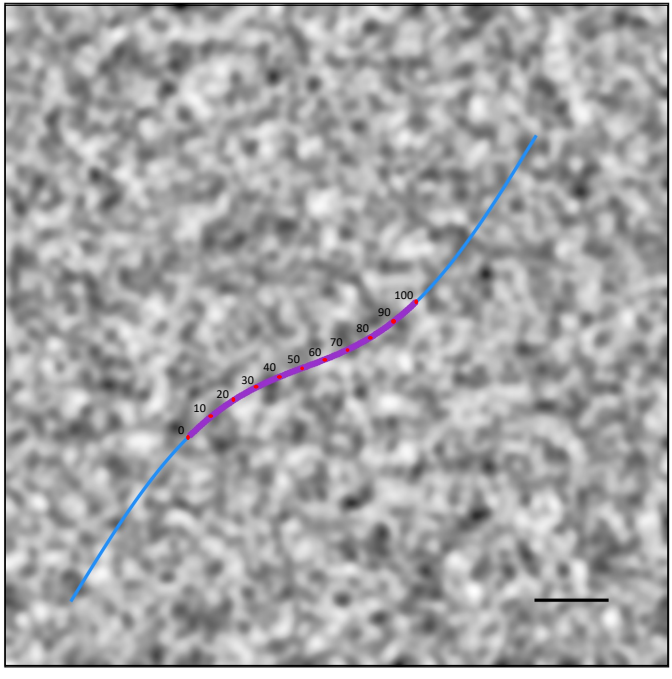


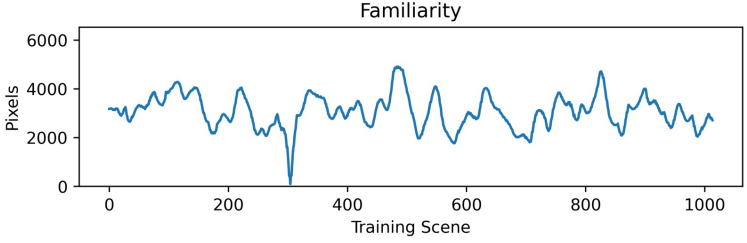


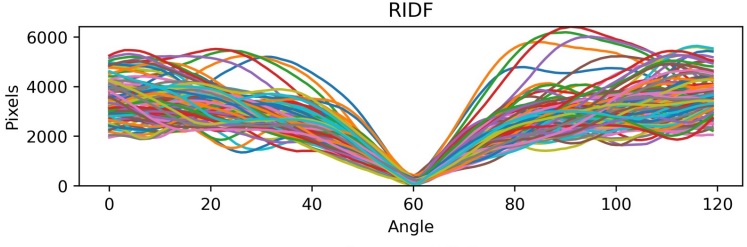
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

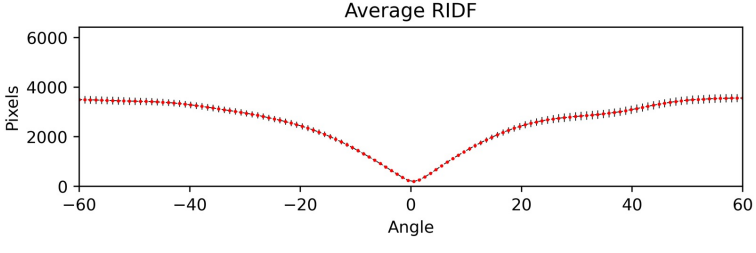
Navigation stats: RMSD error: 40.11; RMSD/dist: 0.100; TD: 2533; p90: 42; p50: 20; complete: 0

100%





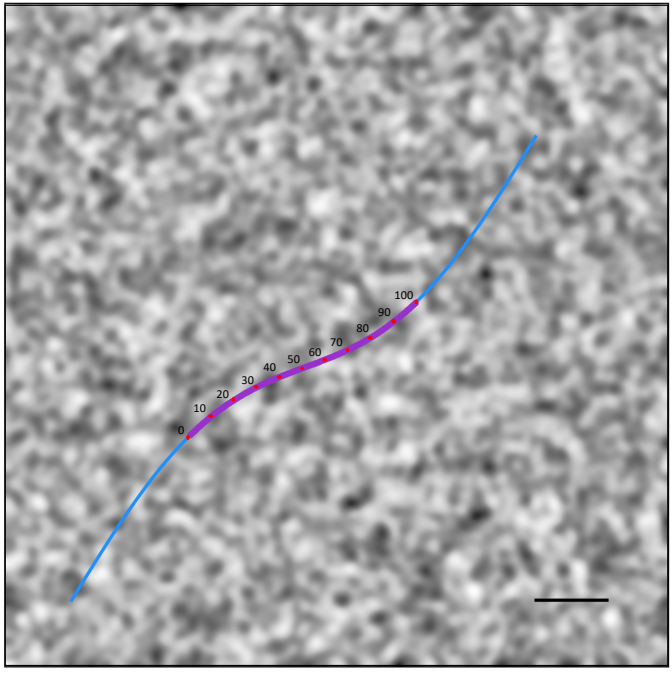


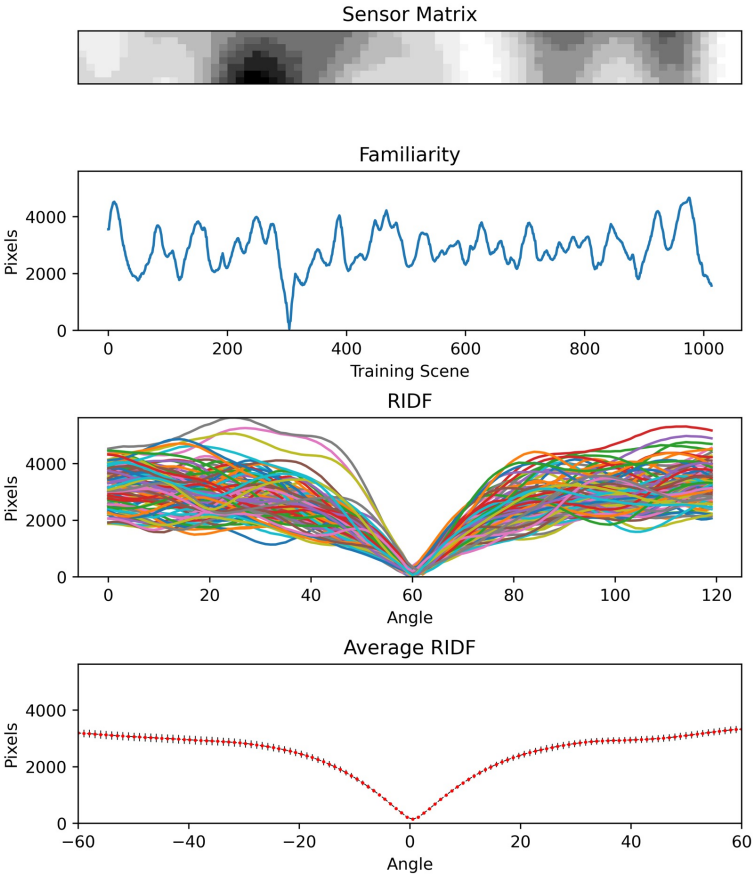


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 61.81; RMSD/dist: 0.155; TD: 2603; p90: 44; p50: 20; complete: 0

100%

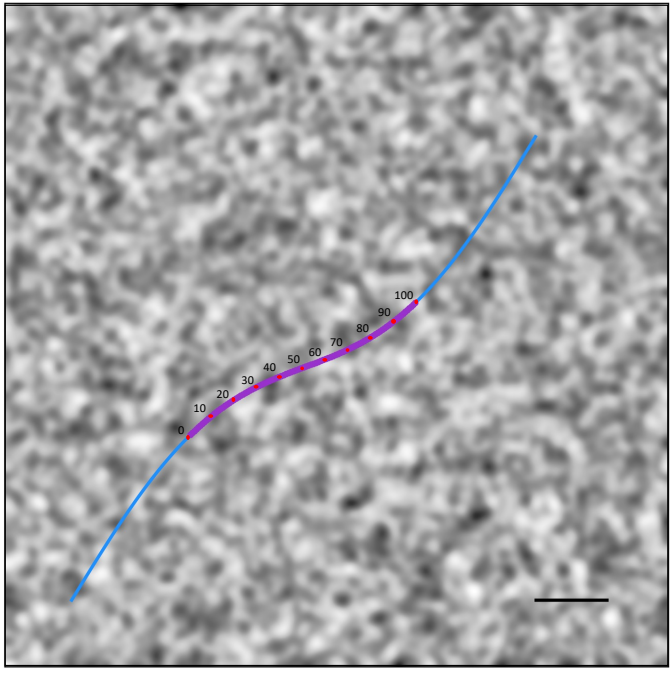


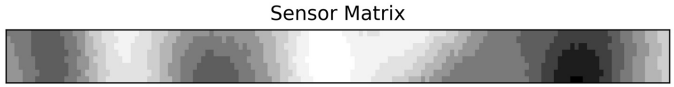


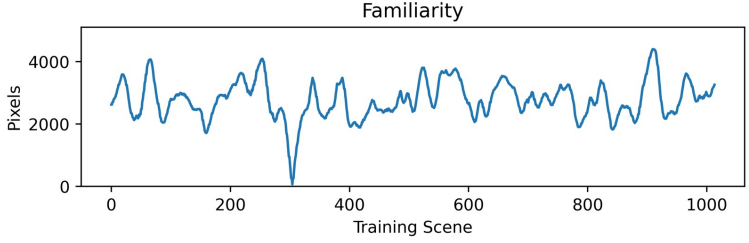
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

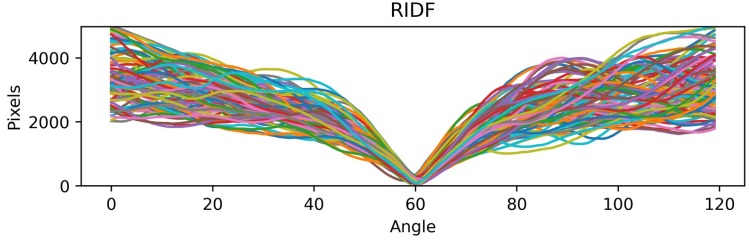
Navigation stats: RMSD error: 32.75; RMSD/dist: 0.082; TD: 2465; p90: 38; p50: 18; complete: 0

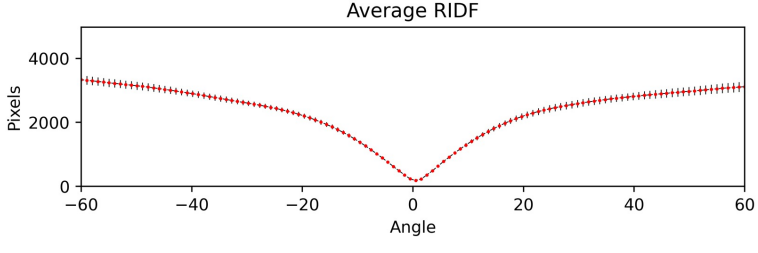
100%





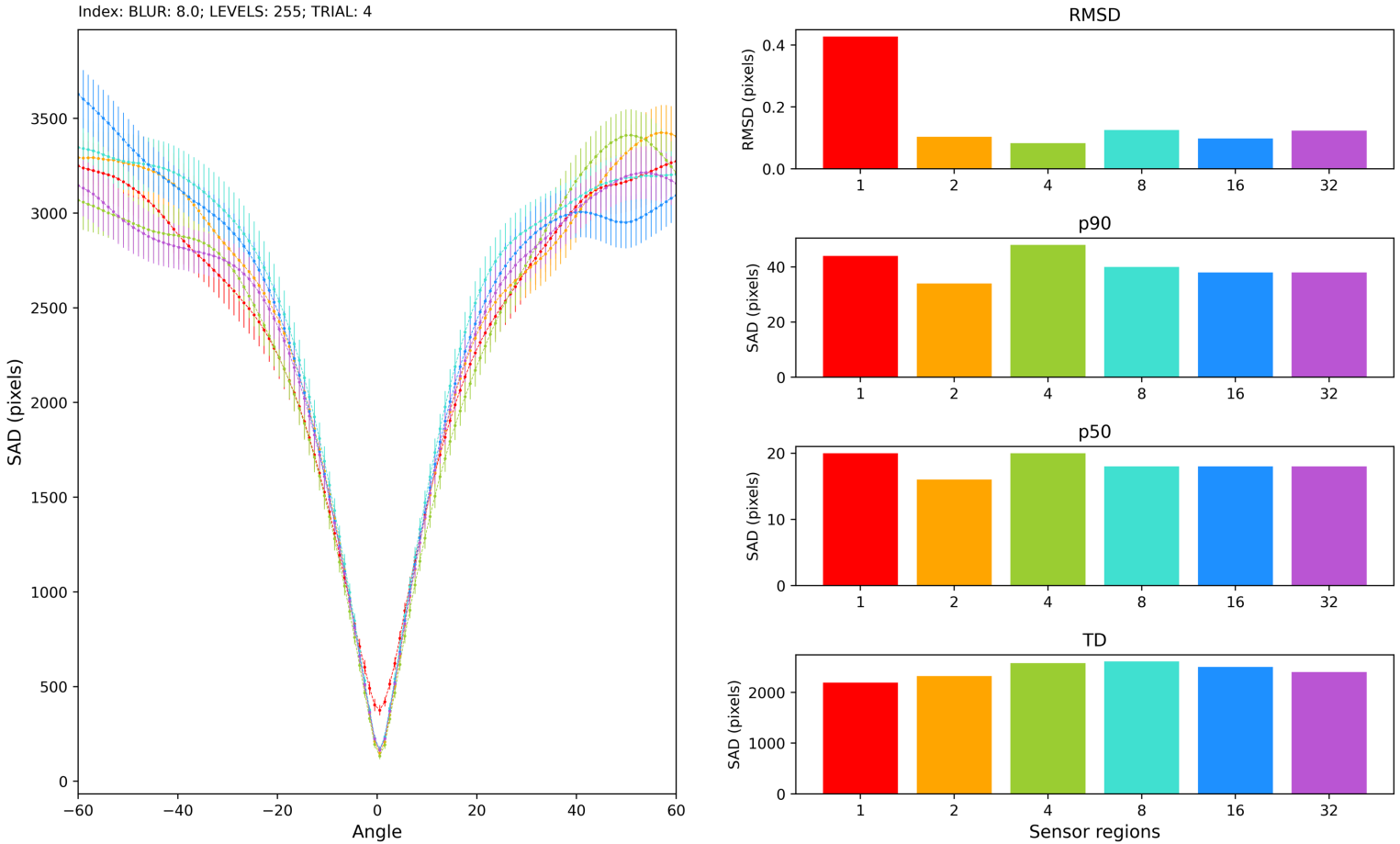




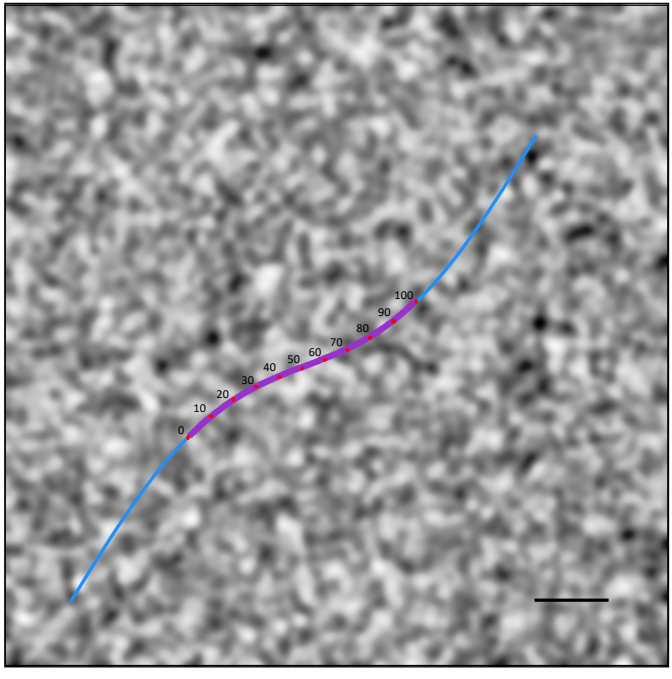


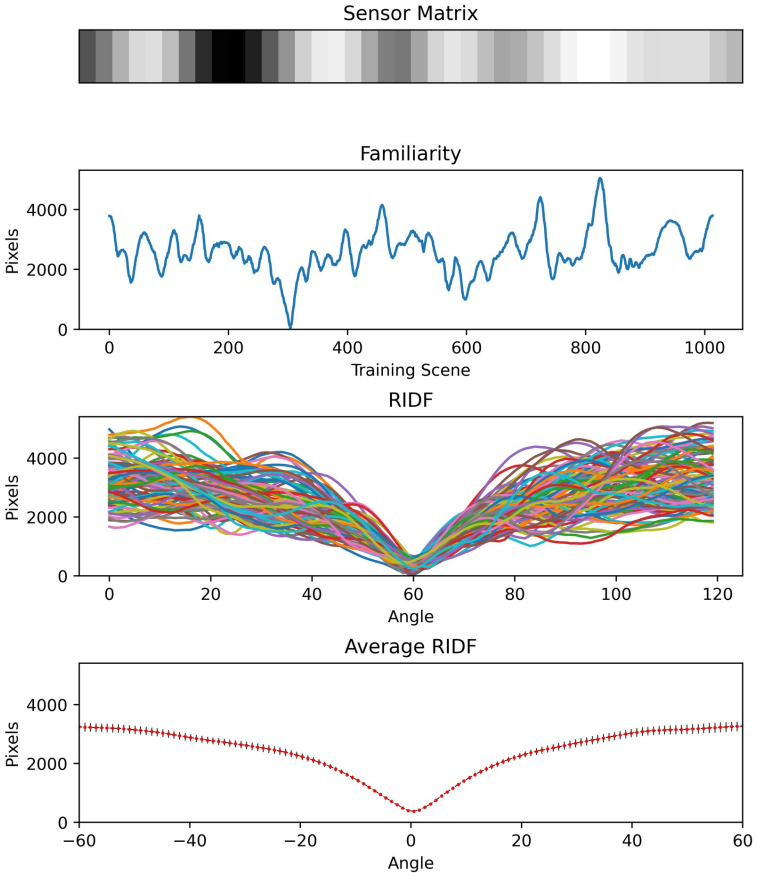
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 54.56; RMSD/dist: 0.136; TD: 2403; p90: 46; p50: 20; complete: 0


Index: BLUR: 8.0; LEVELS: 255; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

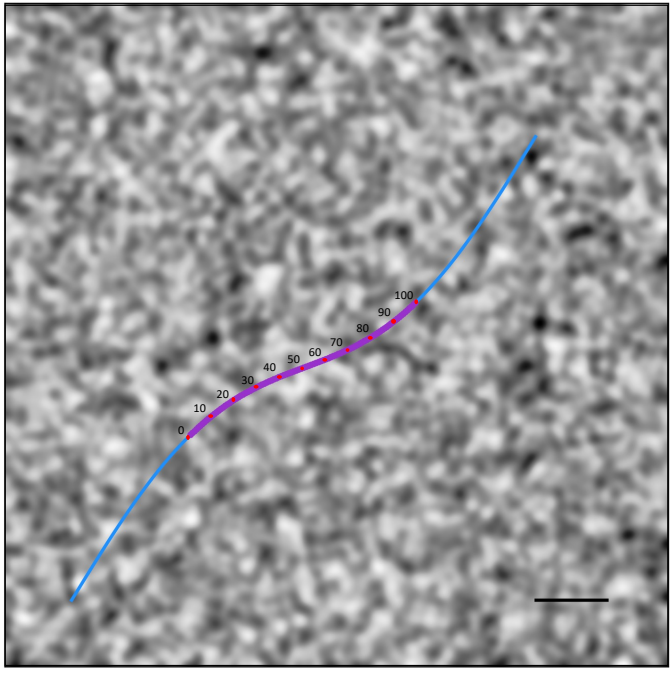


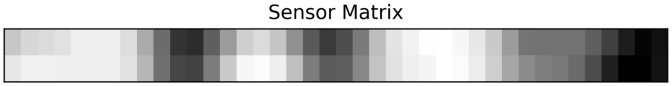


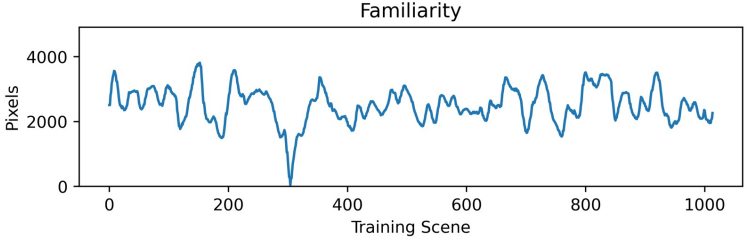
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

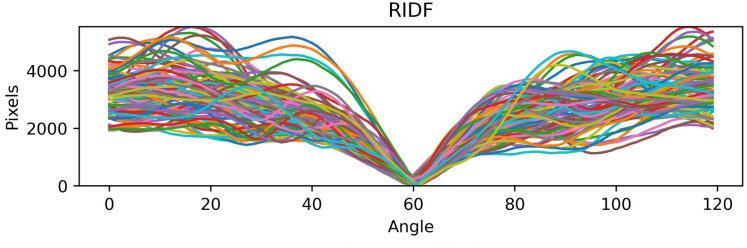
Navigation stats: RMSD error: 171.06; RMSD/dist: 0.428; TD: 2191; p90: 44; p50: 20; complete: 0

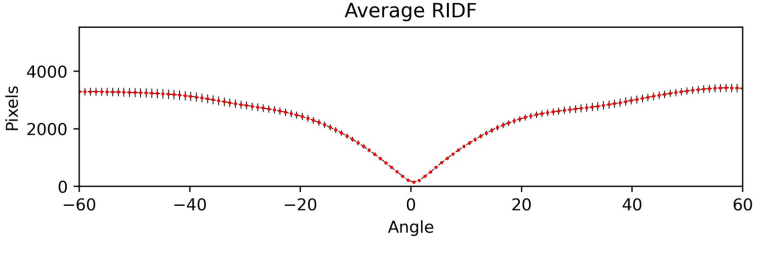
100%







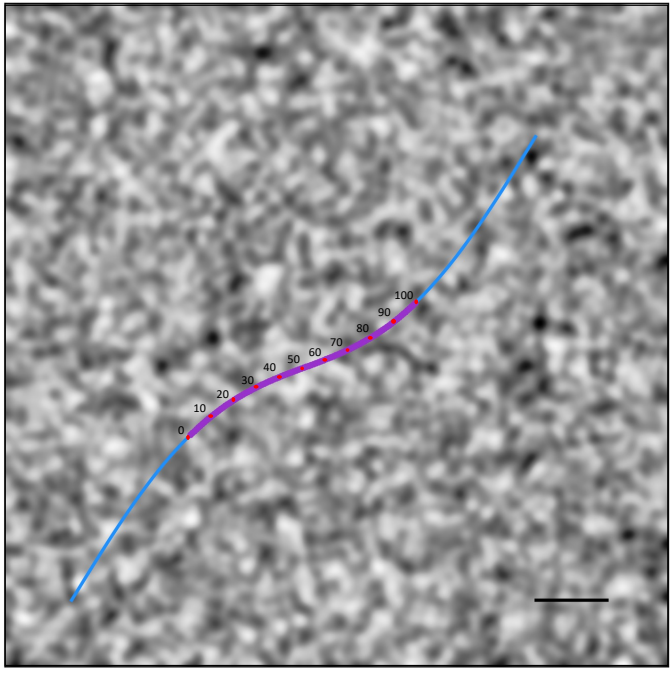


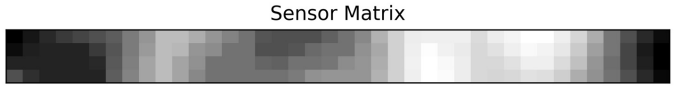


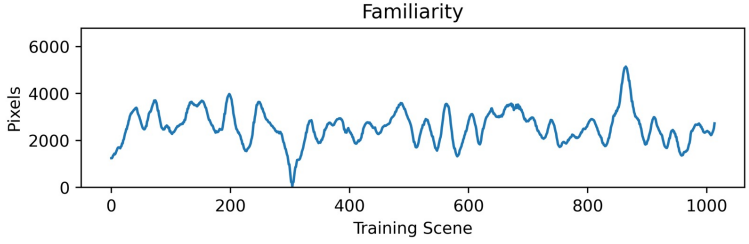
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

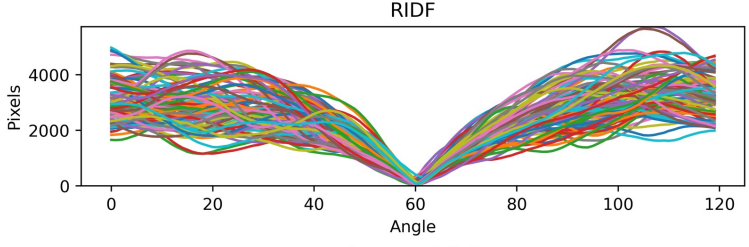
Navigation stats: RMSD error: 41.24; RMSD/dist: 0.103; TD: 2323; p90: 34; p50: 16; complete: 0

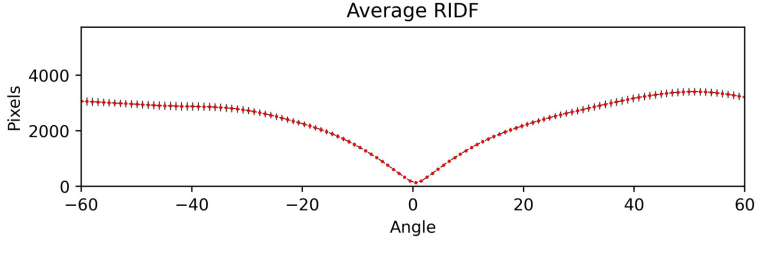
100%







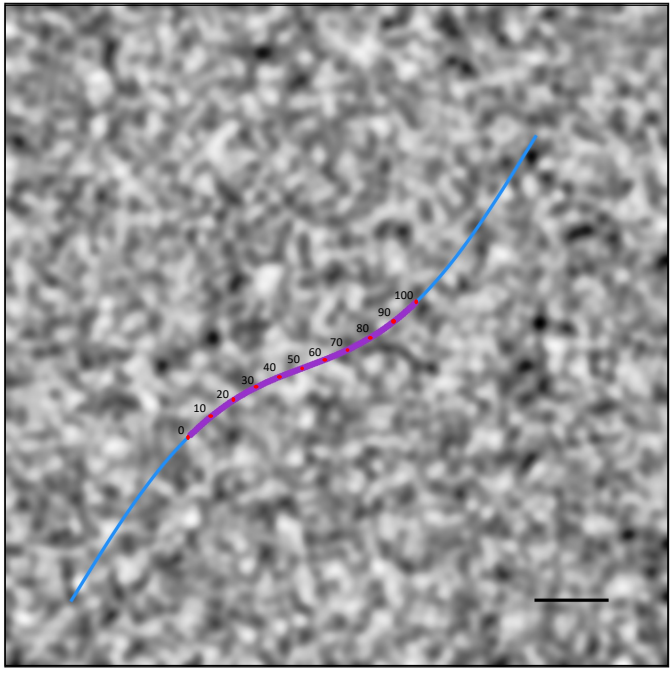


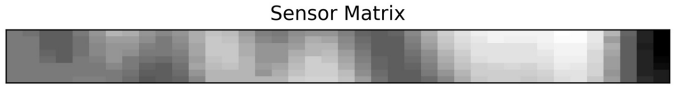


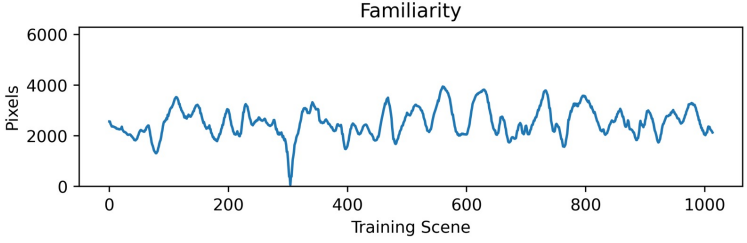
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

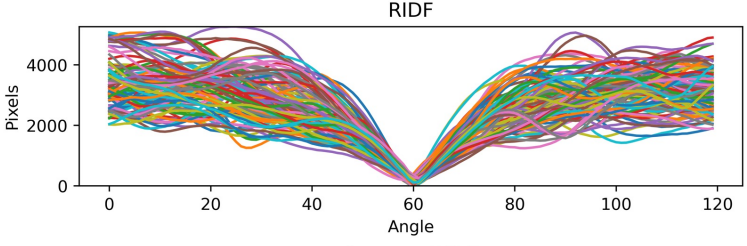
Navigation stats: RMSD error: 33.19; RMSD/dist: 0.083; TD: 2577; p90: 48; p50: 20; complete: 0

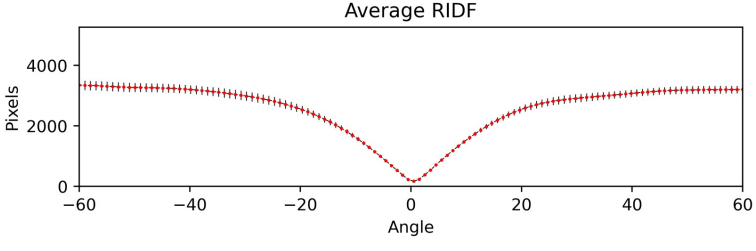
100%







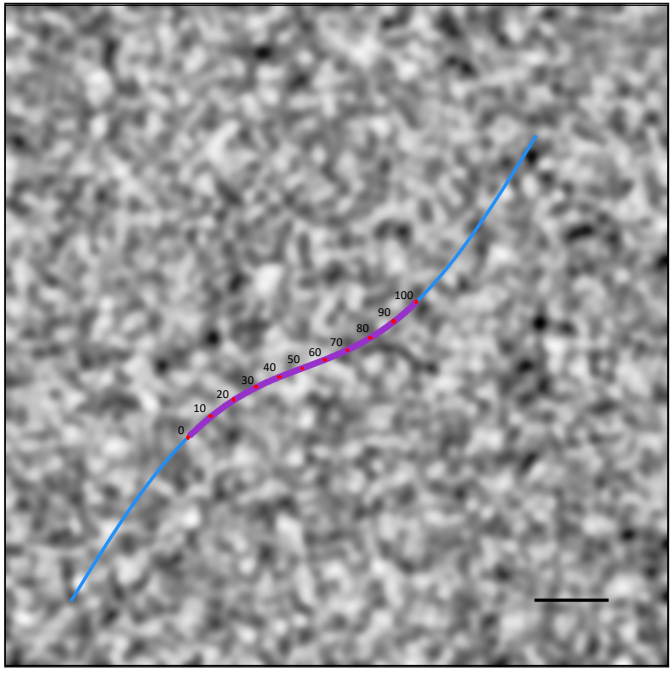


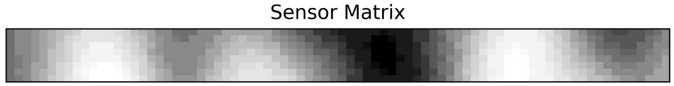


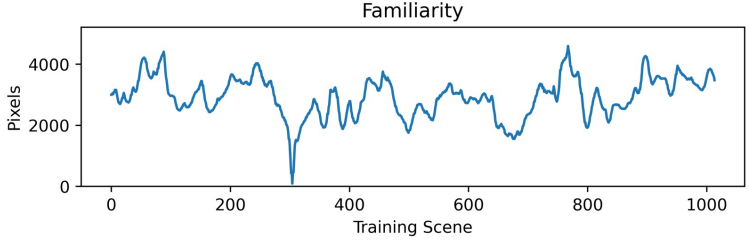
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

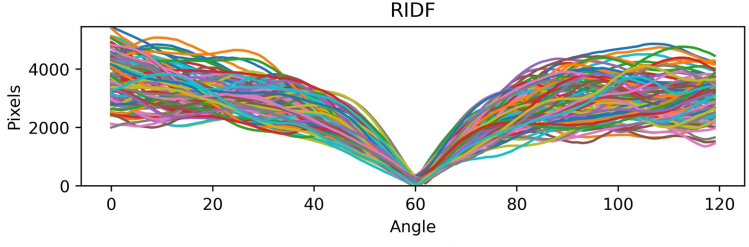
Navigation stats: RMSD error: 50.07; RMSD/dist: 0.125; TD: 2609; p90: 40; p50: 18; complete: 0

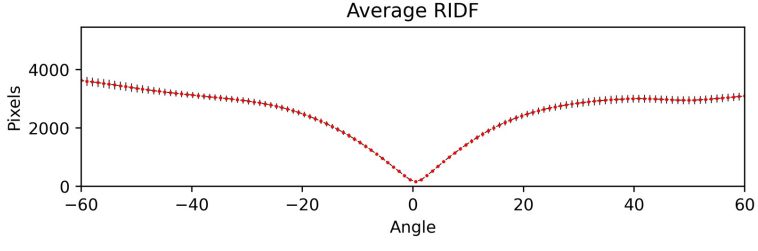
100%







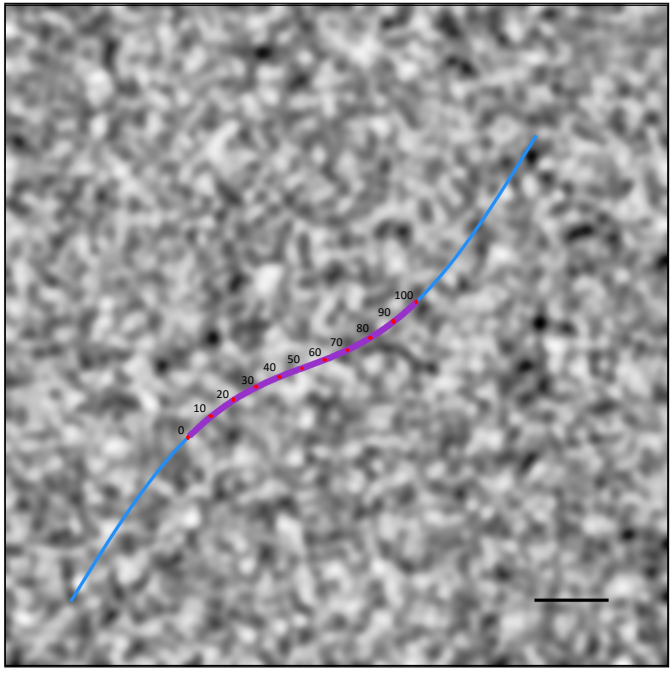


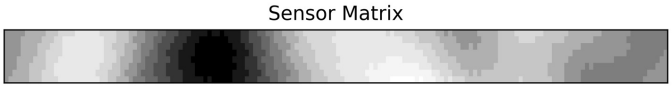


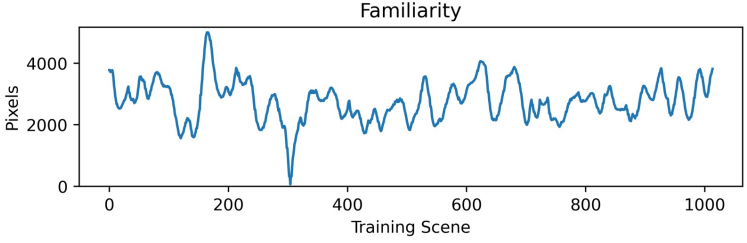
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

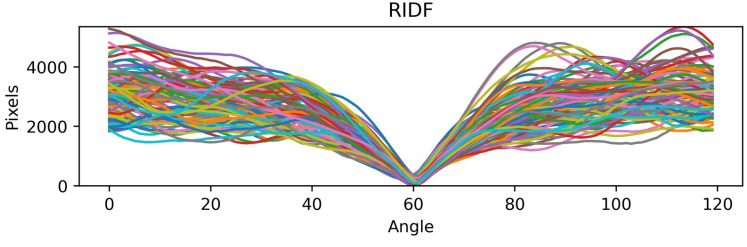
Navigation stats: RMSD error: 39.36; RMSD/dist: 0.098; TD: 2501; p90: 38; p50: 18; complete: 0

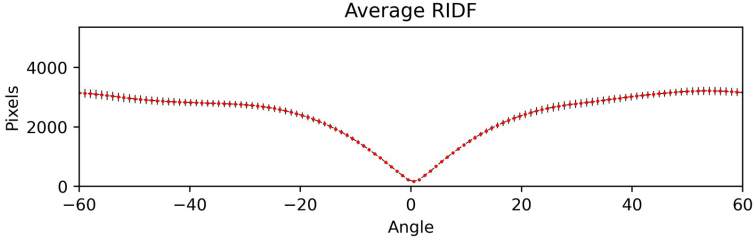
100%





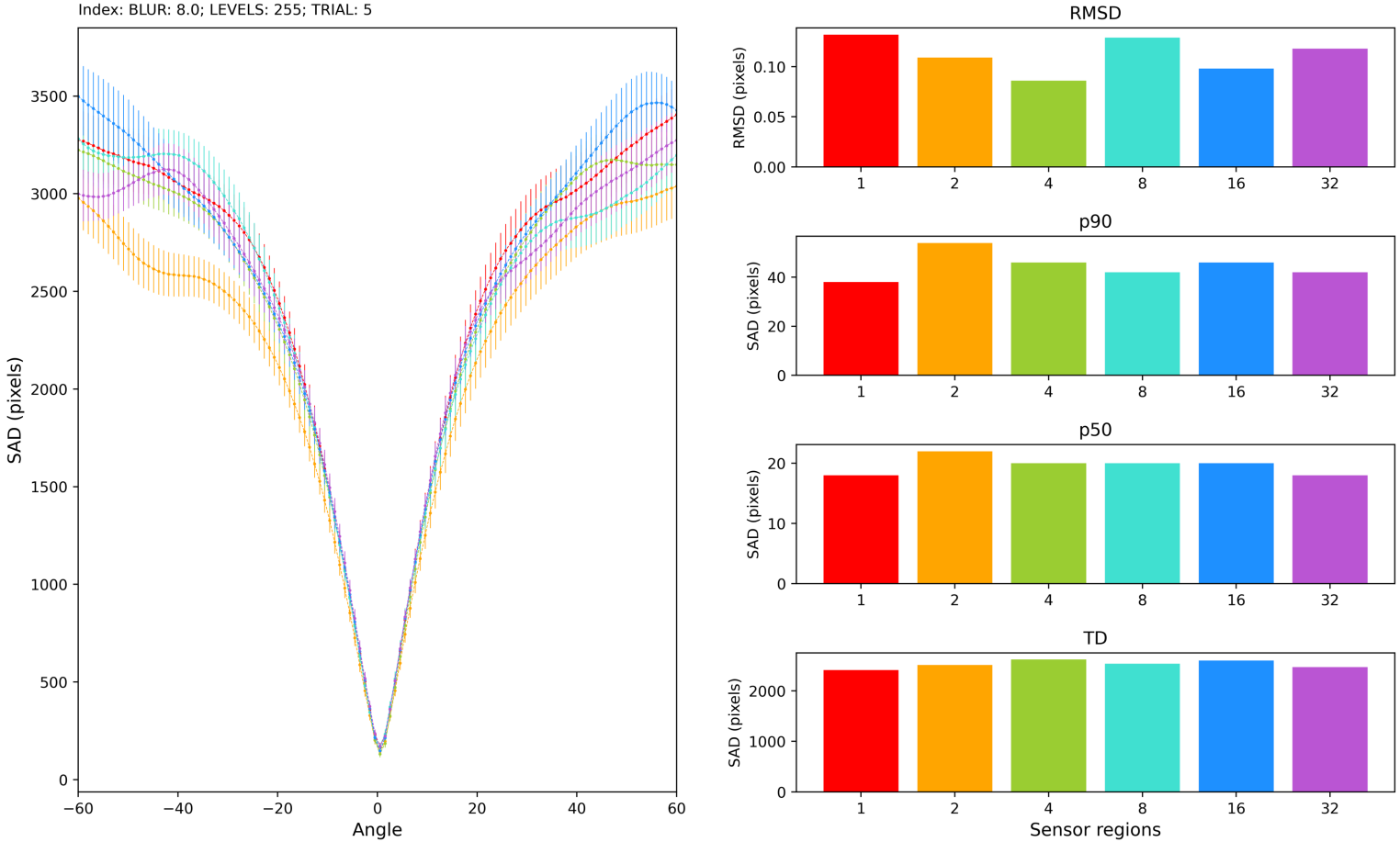




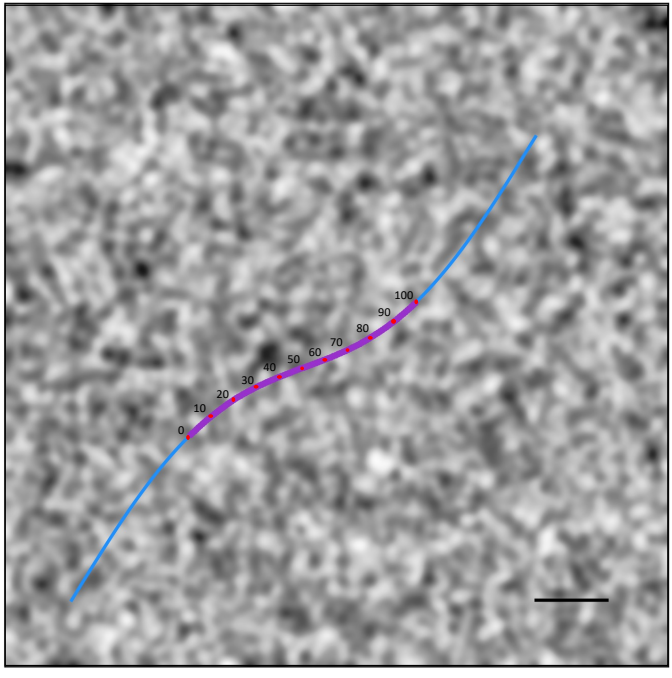


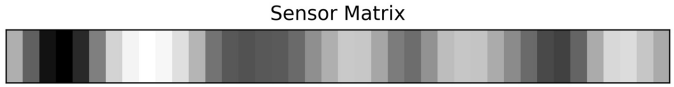
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

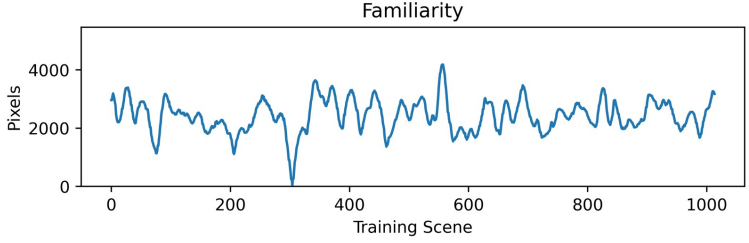
Navigation stats: RMSD error: 49.28; RMSD/dist: 0.123; TD: 2403; p90: 38; p50: 18; complete: 0

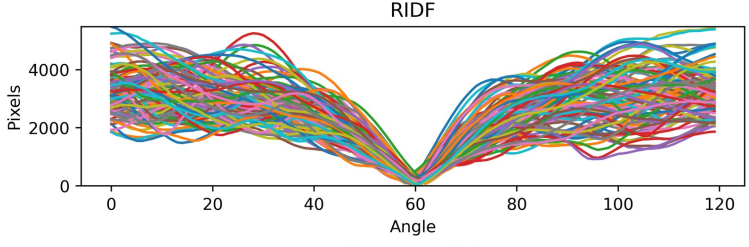

Index: BLUR: 8.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

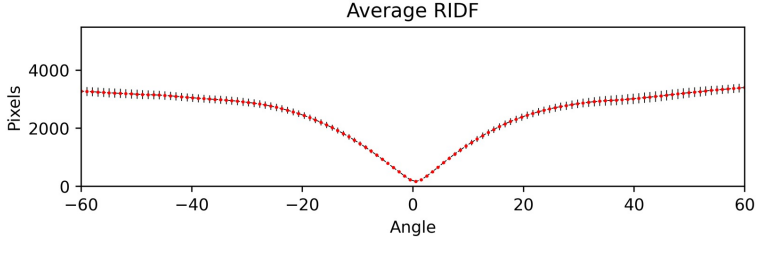
100%







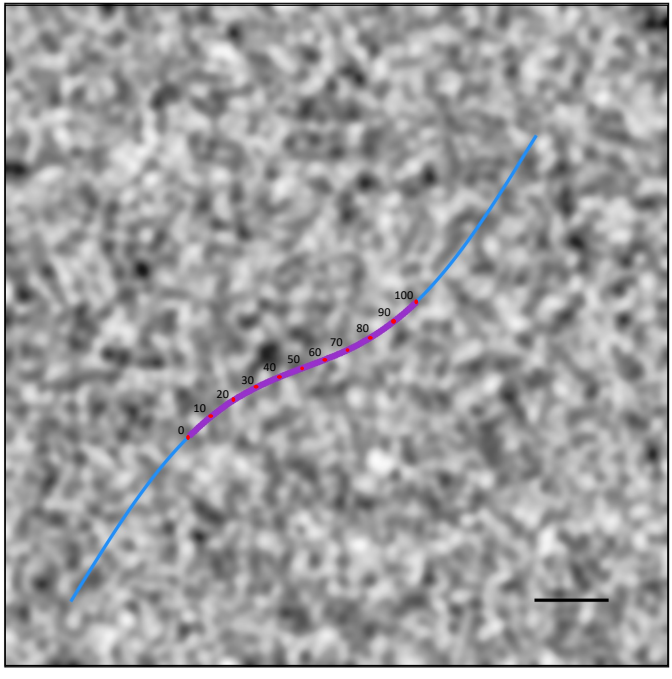


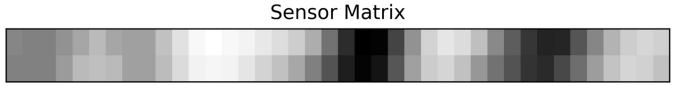


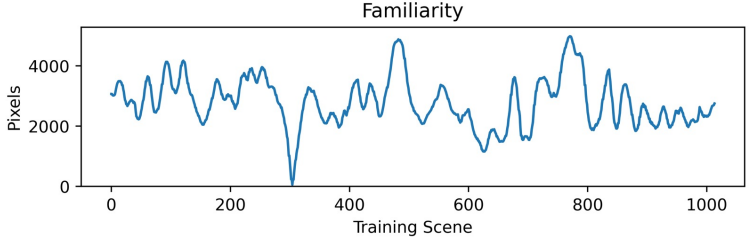
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

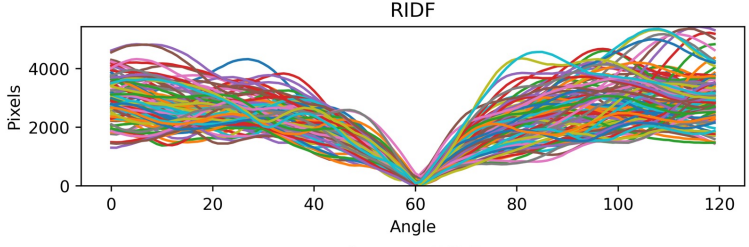
Navigation stats: RMSD error: 52.60; RMSD/dist: 0.132; TD: 2410; p90: 38; p50: 18; complete: 0

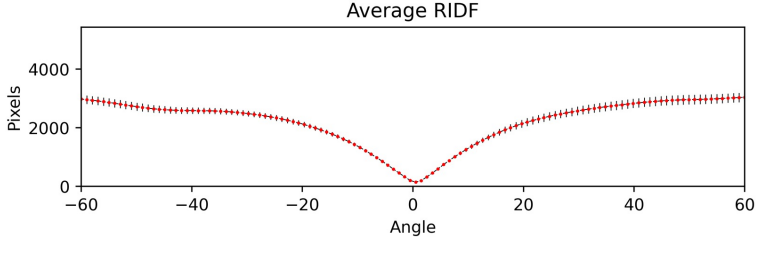
100%







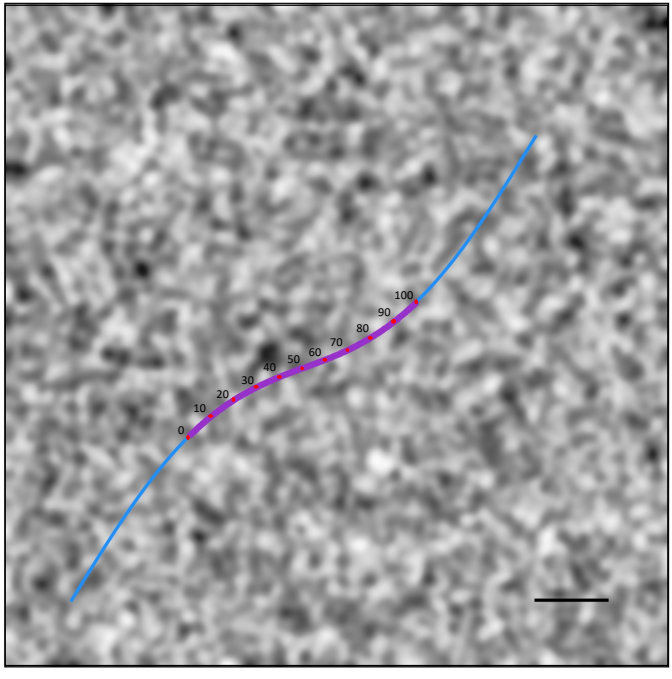


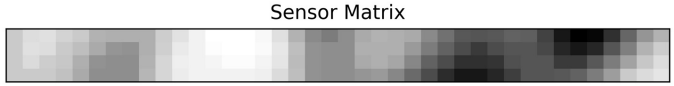


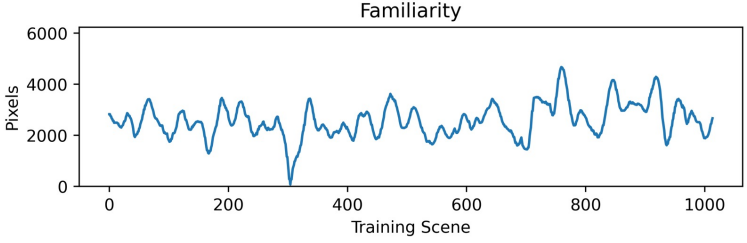
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

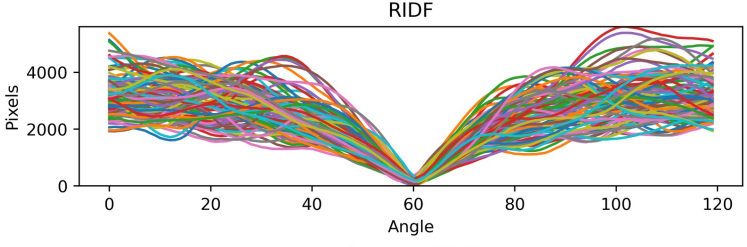
Navigation stats: RMSD error: 43.68; RMSD/dist: 0.109; TD: 2513; p90: 54; p50: 22; complete: 0

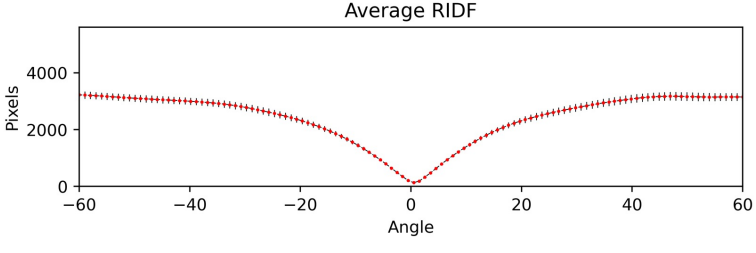
100%







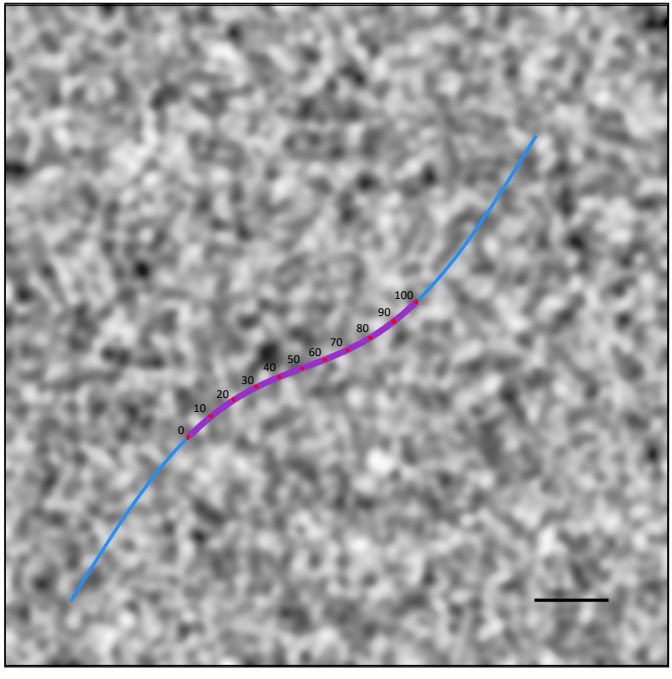


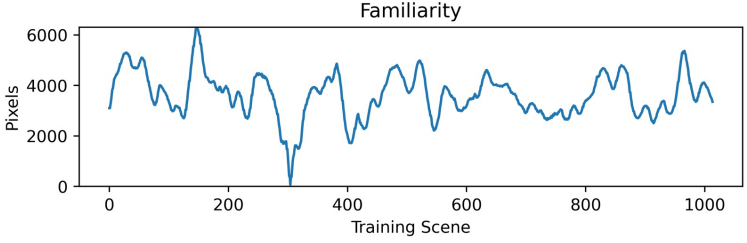


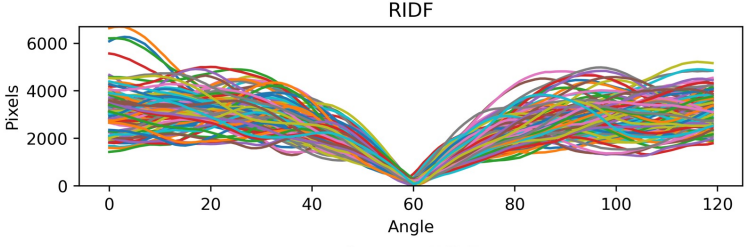
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

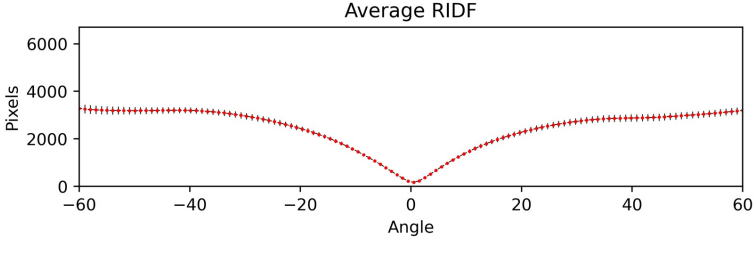
Navigation stats: RMSD error: 34.41; RMSD/dist: 0.086; TD: 2619; p90: 46; p50: 20; complete: 0

100%





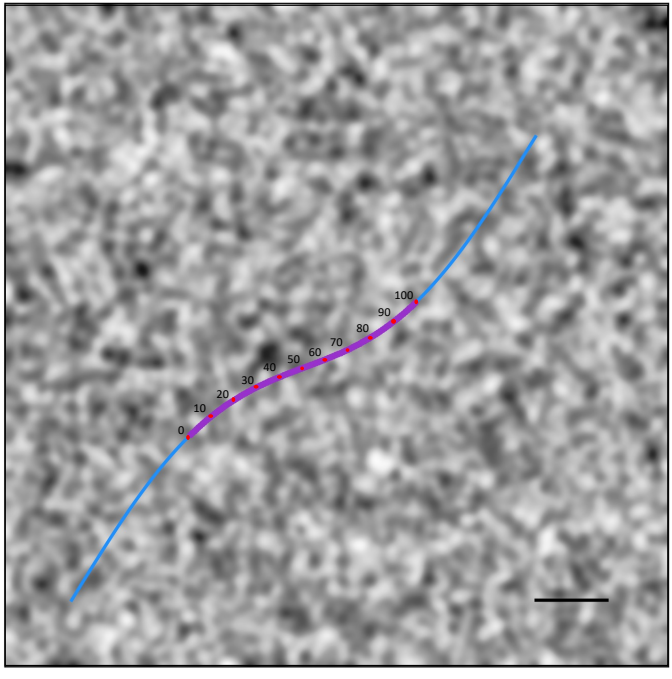


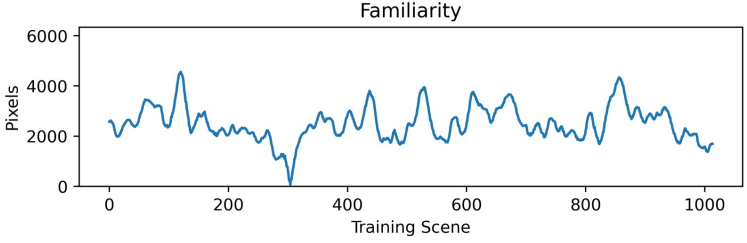


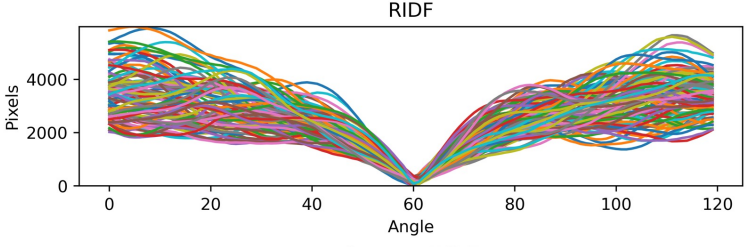
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

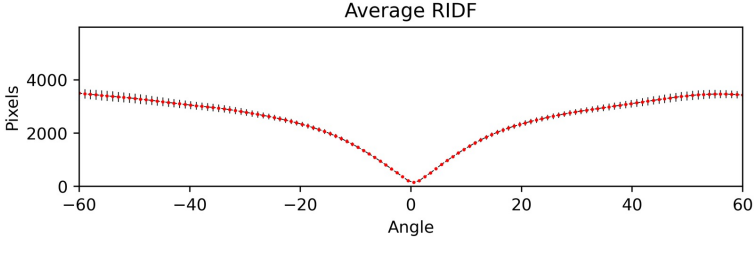
Navigation stats: RMSD error: 51.56; RMSD/dist: 0.129; TD: 2536; p90: 42; p50: 20; complete: 0

100%





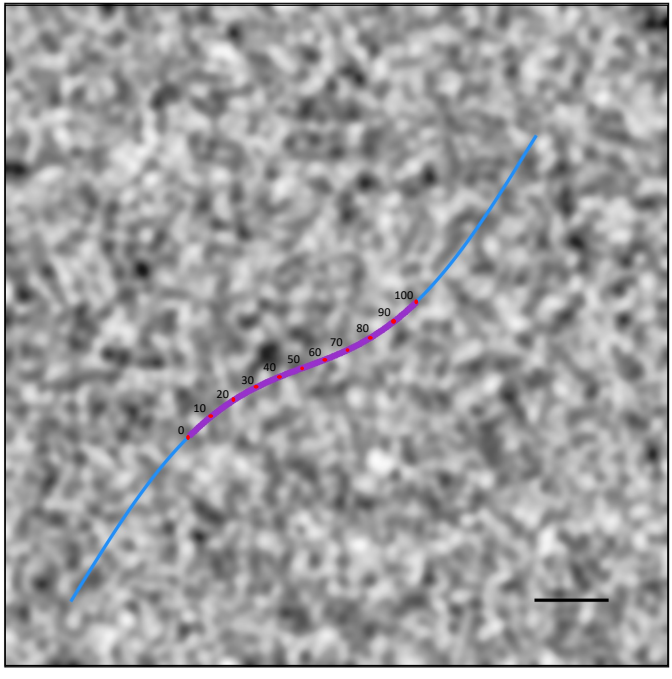


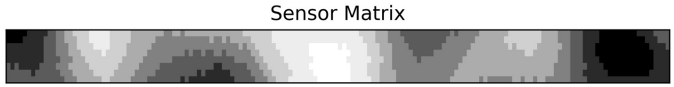


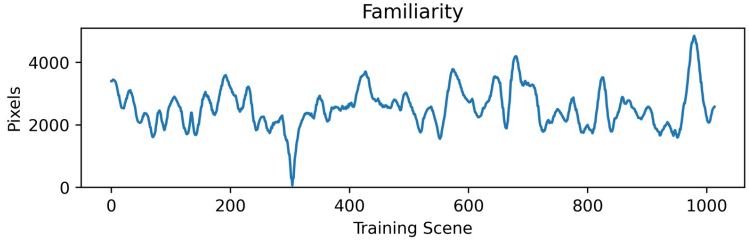
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

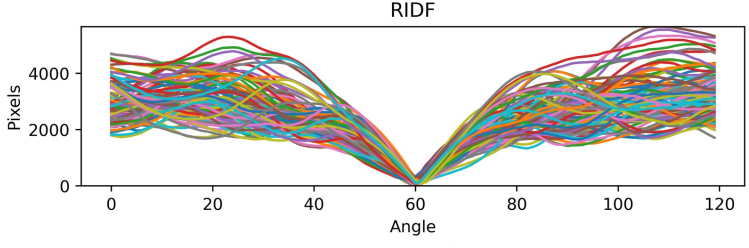
Navigation stats: RMSD error: 39.09; RMSD/dist: 0.098; TD: 2602; p90: 46; p50: 20; complete: 0

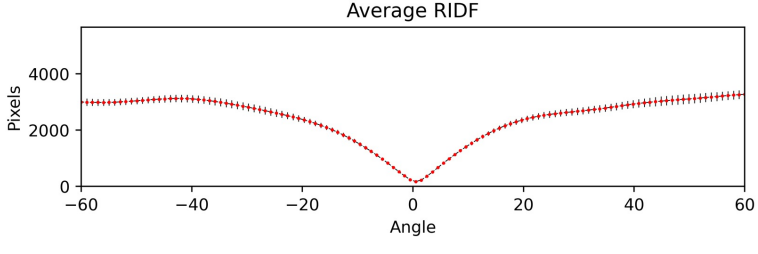
100%





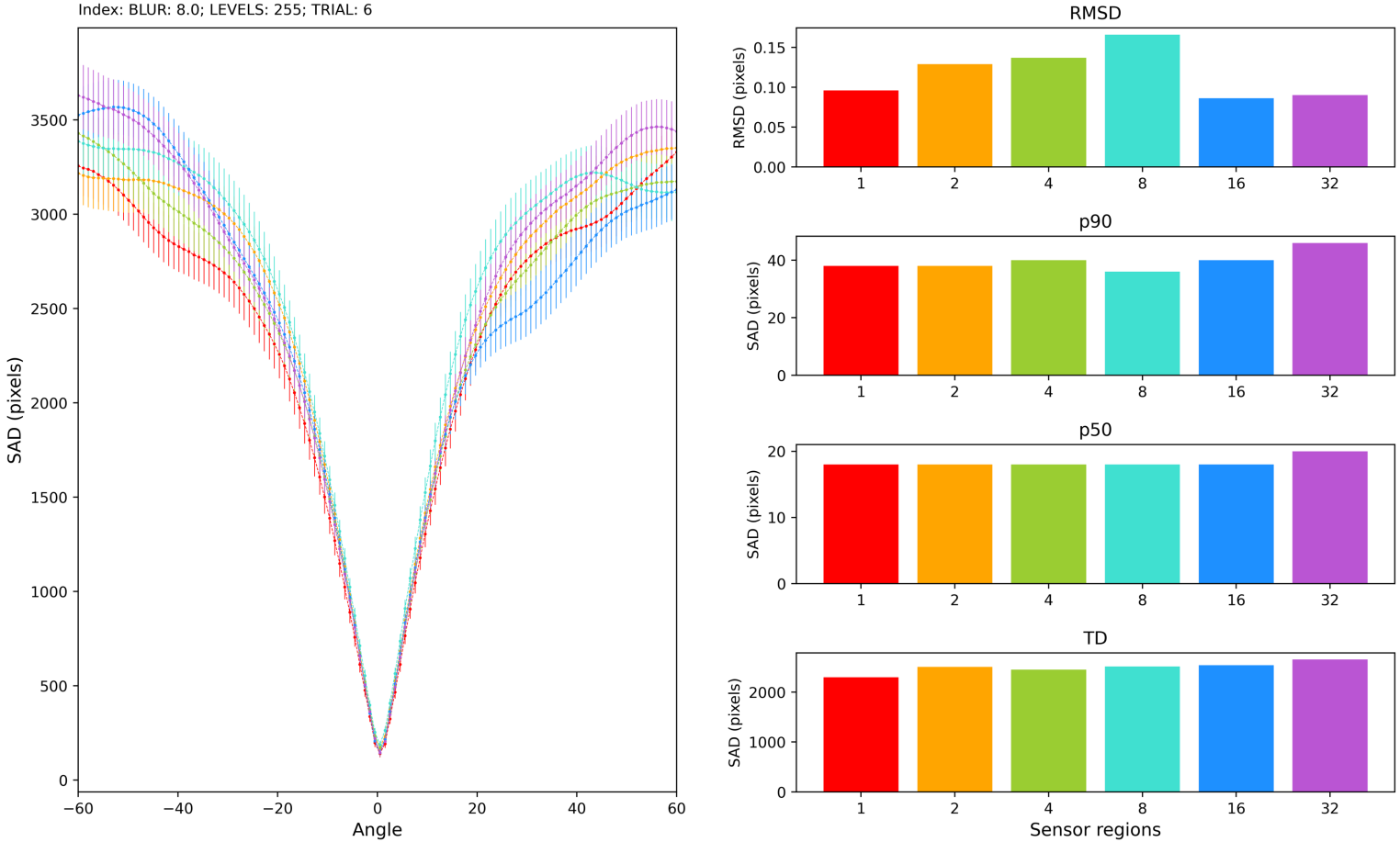




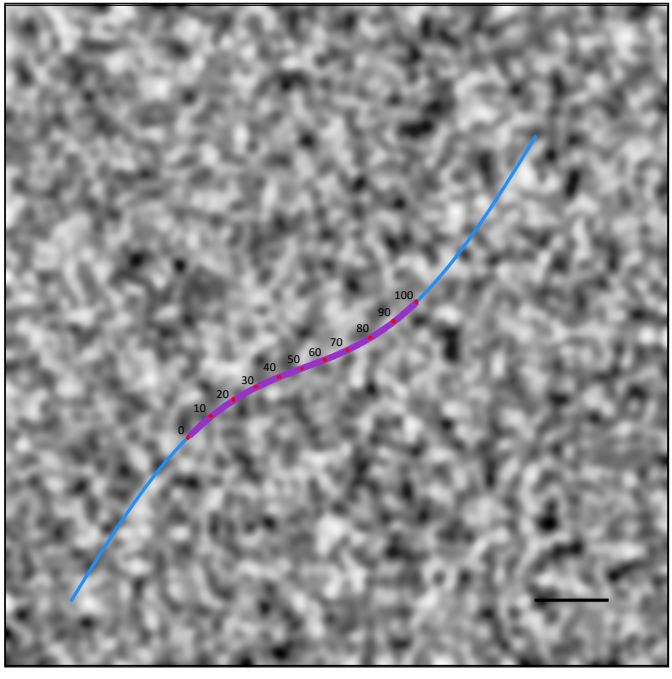


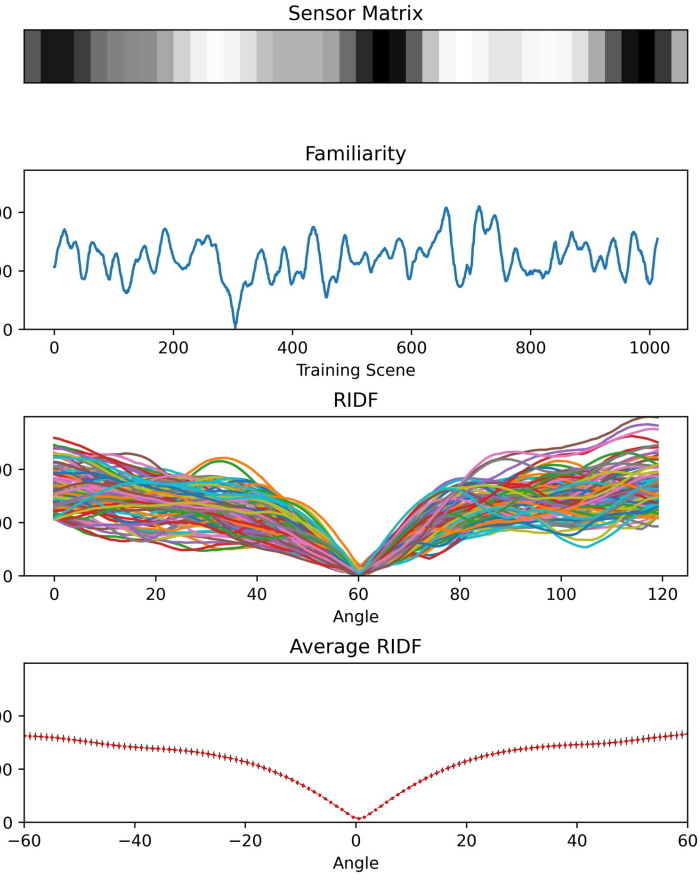
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 47.38; RMSD/dist: 0.118; TD: 2469; p90: 42; p50: 18; complete: 0


Index: BLUR: 8.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

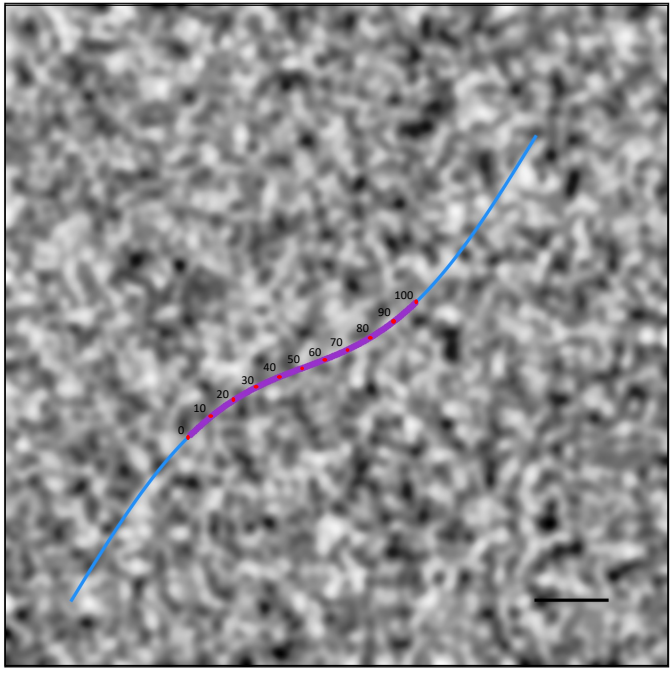


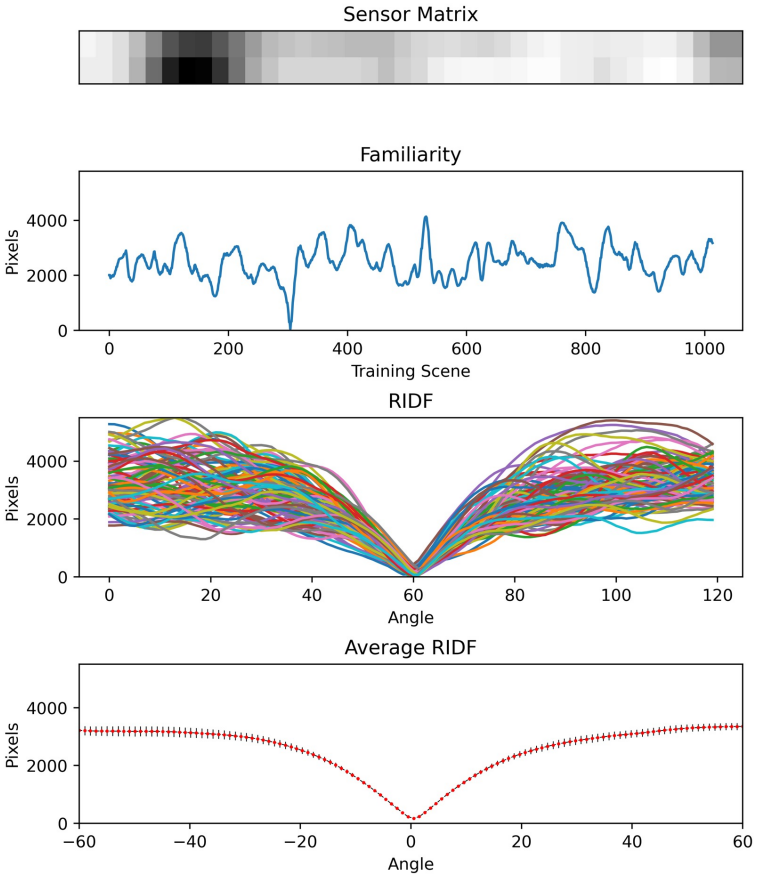


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 38.44; RMSD/dist: 0.096; TD: 2297; p90: 38; p50: 18; complete: 0

100%

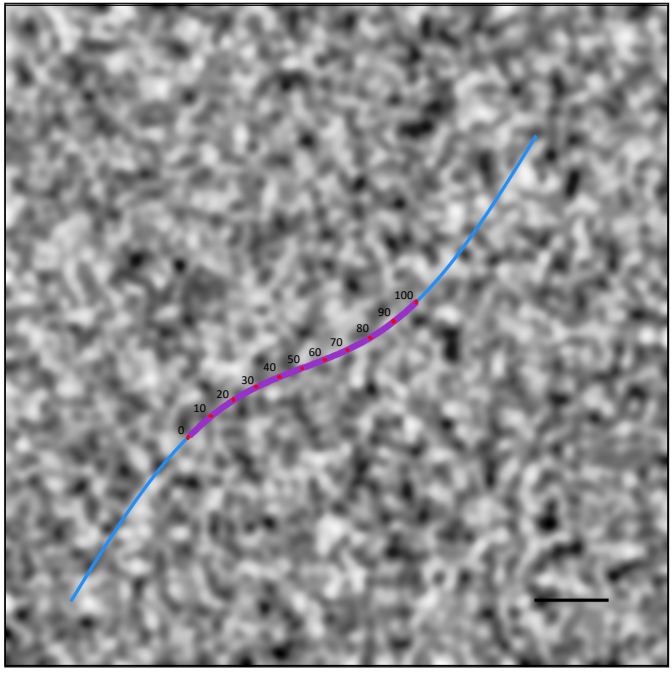


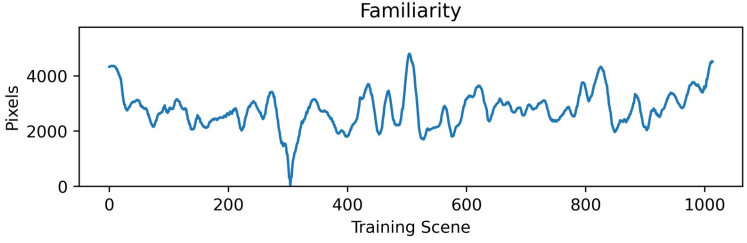


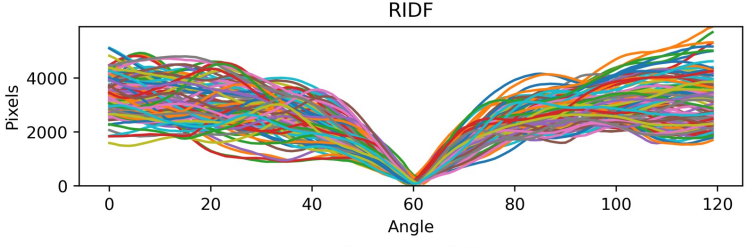
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

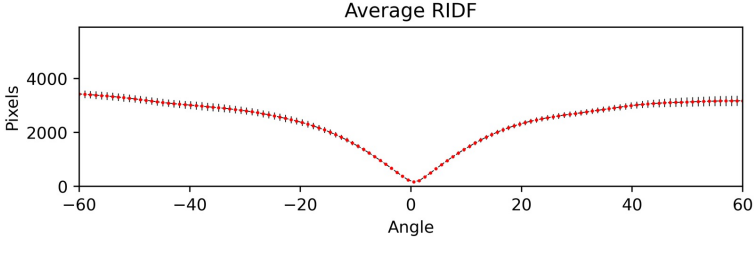
Navigation stats: RMSD error: 51.44; RMSD/dist: 0.129; TD: 2506; p90: 38; p50: 18; complete: 0

100%





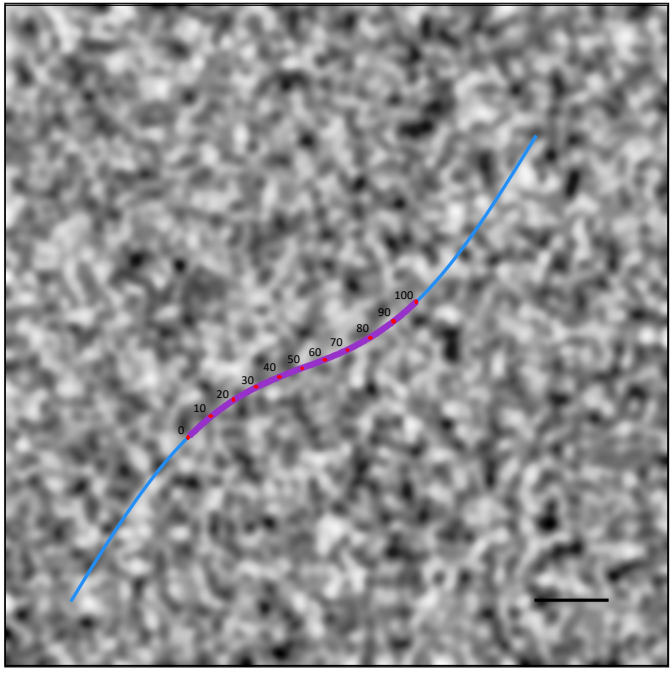


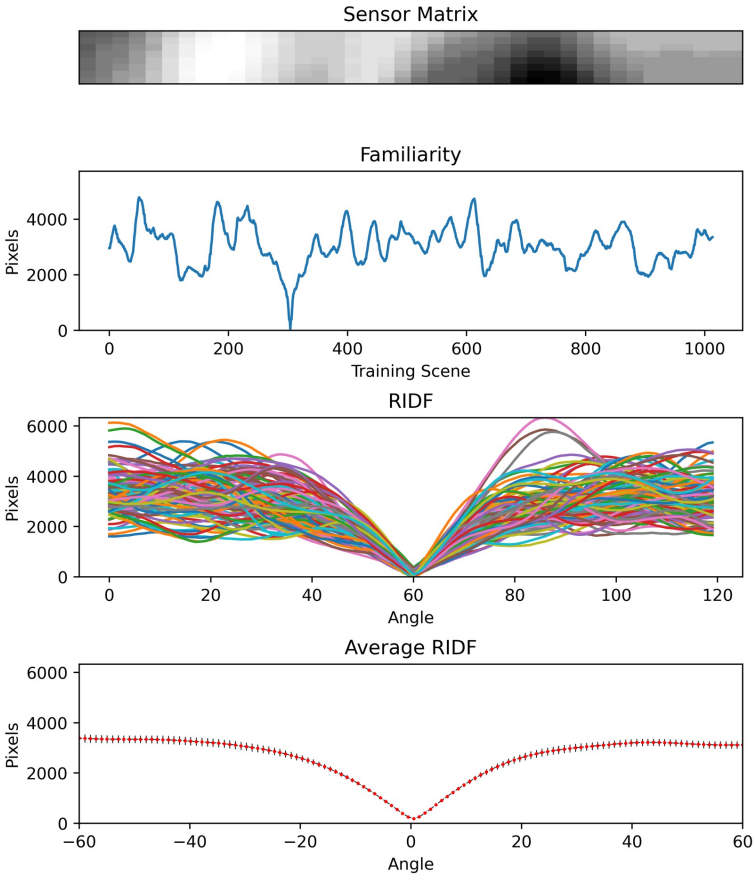


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 54.72; RMSD/dist: 0.137; TD: 2451; p90: 40; p50: 18; complete: 0

100%

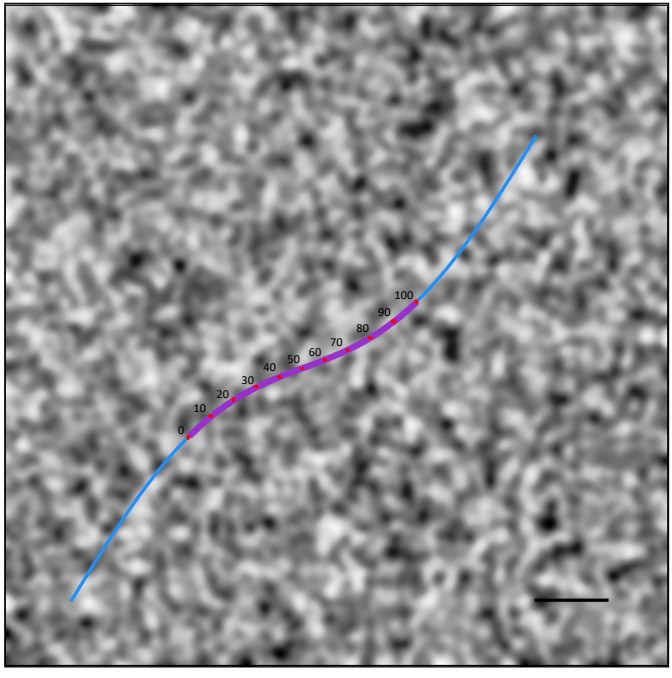


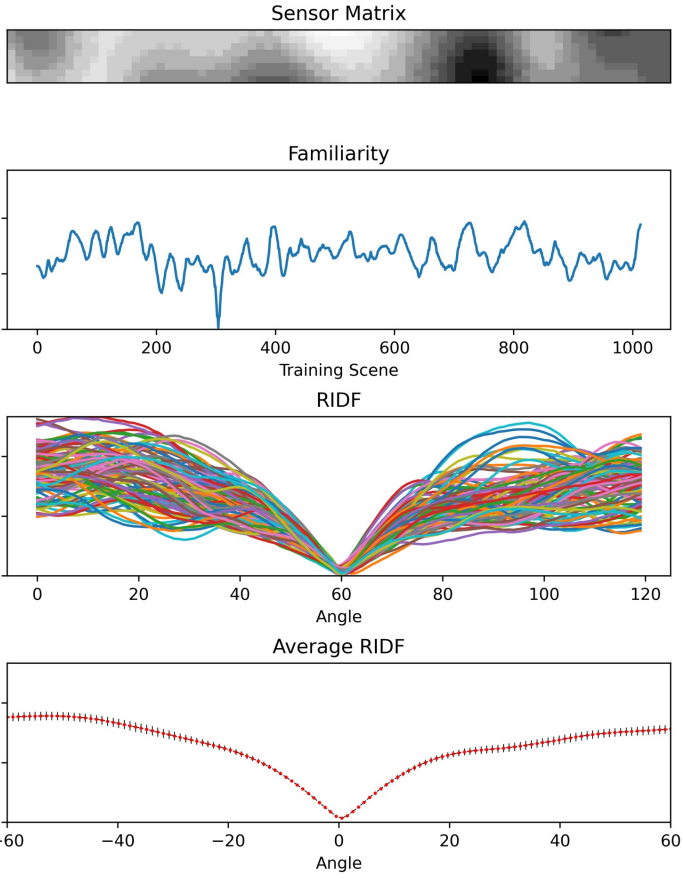


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 66.44; RMSD/dist: 0.166; TD: 2514; p90: 36; p50: 18; complete: 0

100%

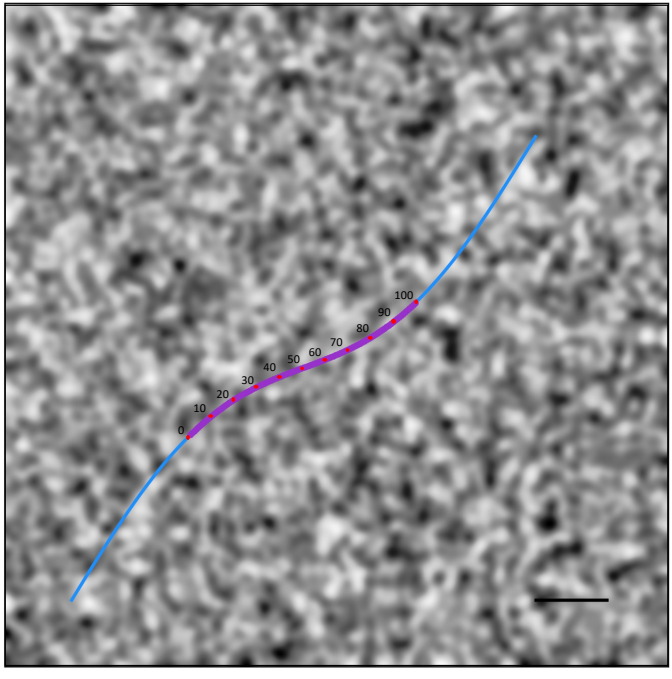


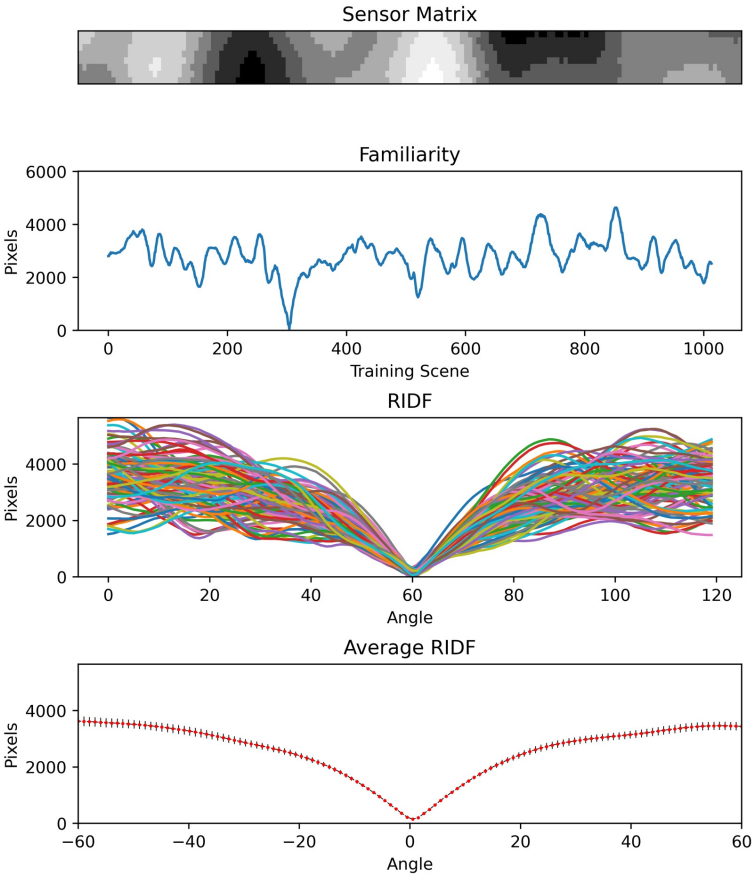


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 34.34; RMSD/dist: 0.086; TD: 2540; p90: 40; p50: 18; complete: 0

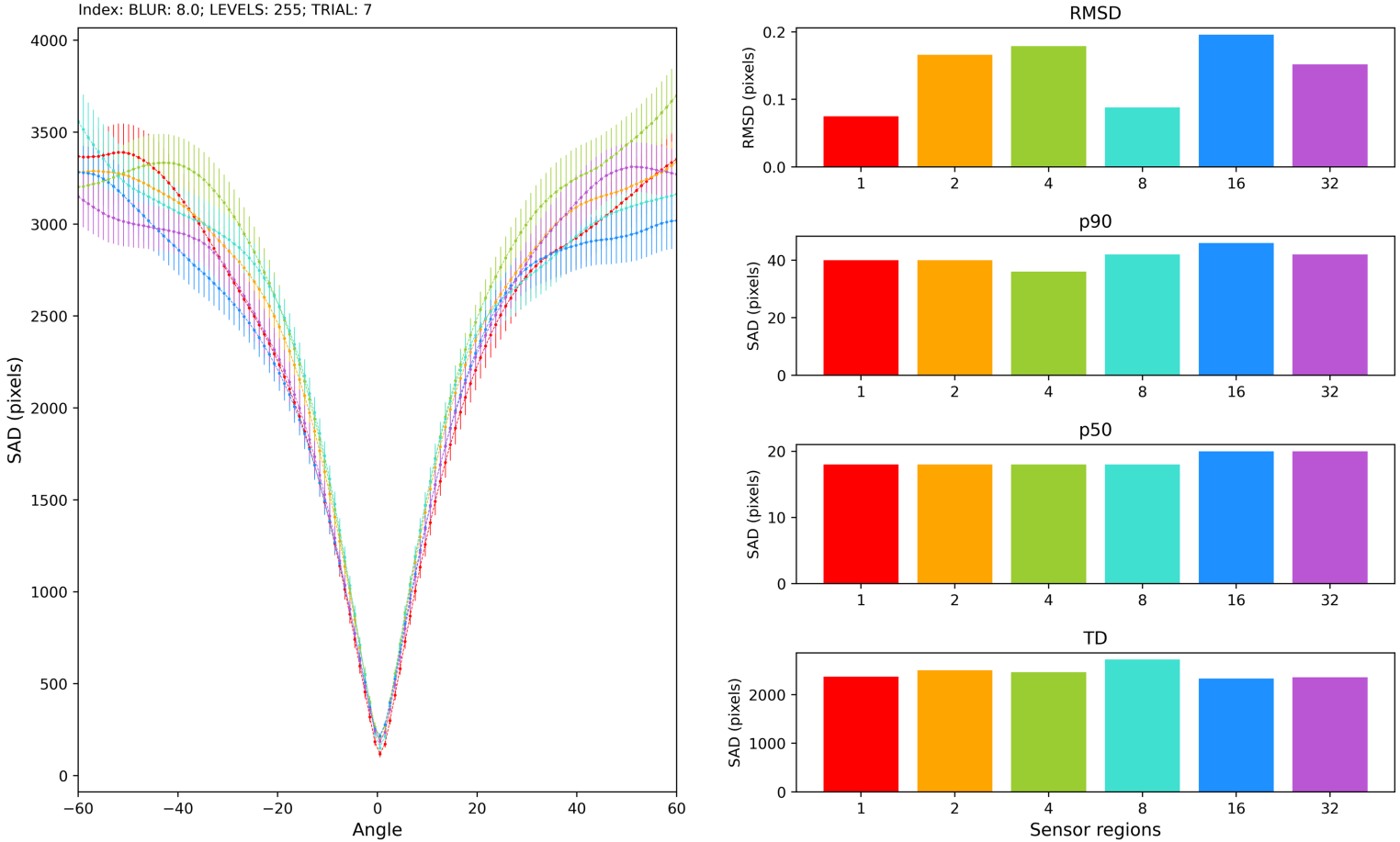
100%



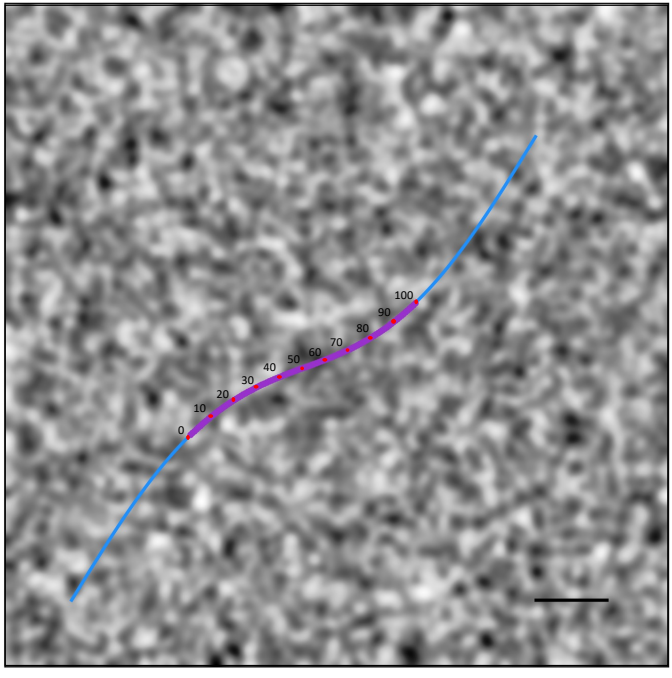


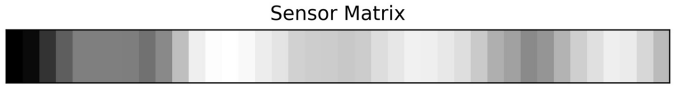
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

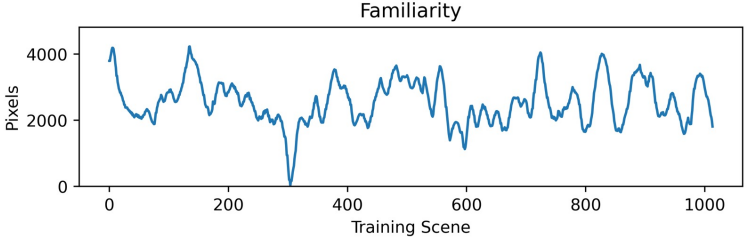
Navigation stats: RMSD error: 35.94; RMSD/dist: 0.090; TD: 2651; p90: 46; p50: 20; complete: 0

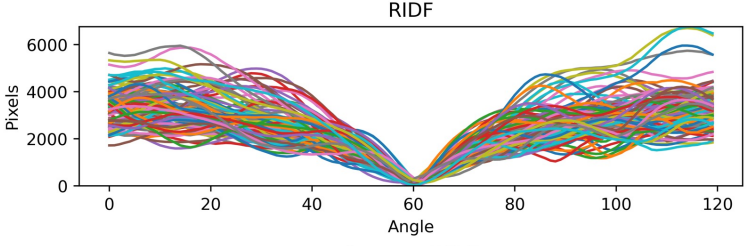

Index: BLUR: 8.0; LEVELS: 255; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

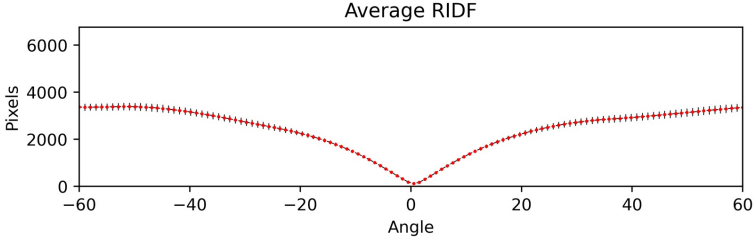
100%







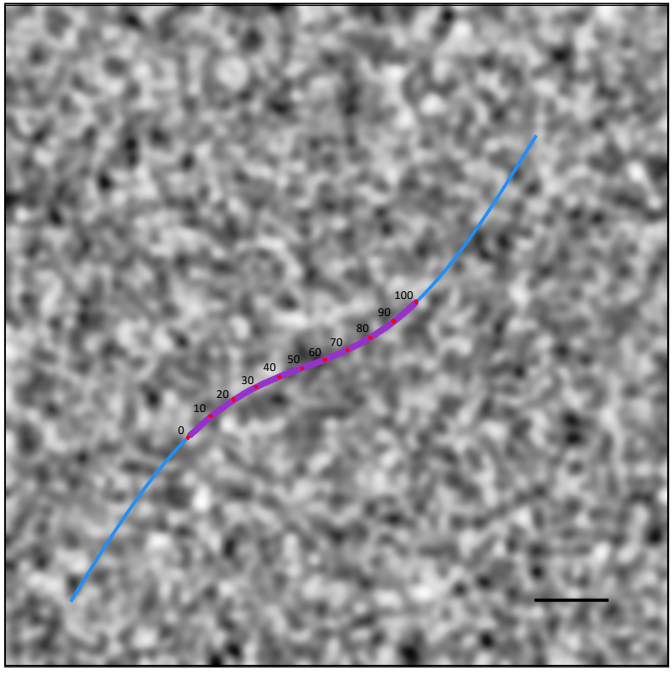


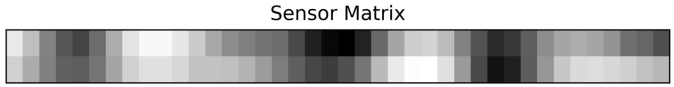


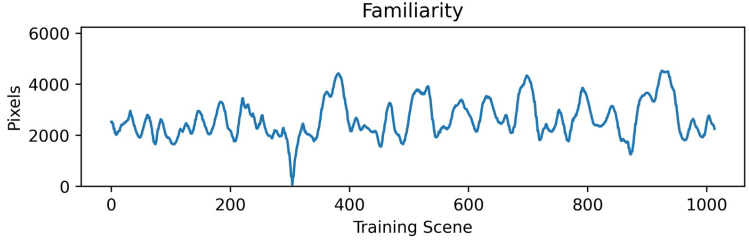
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

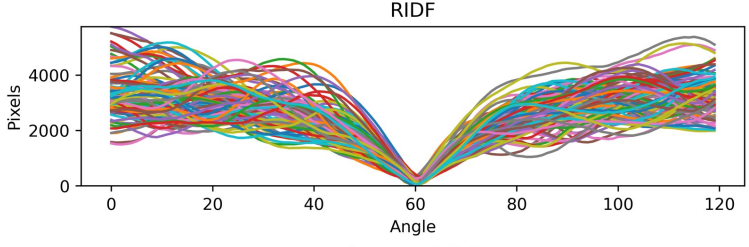
Navigation stats: RMSD error: 29.98; RMSD/dist: 0.075; TD: 2373; p90: 40; p50: 18; complete: 0

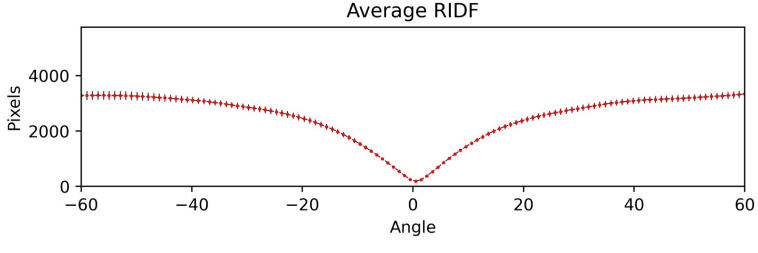
100%







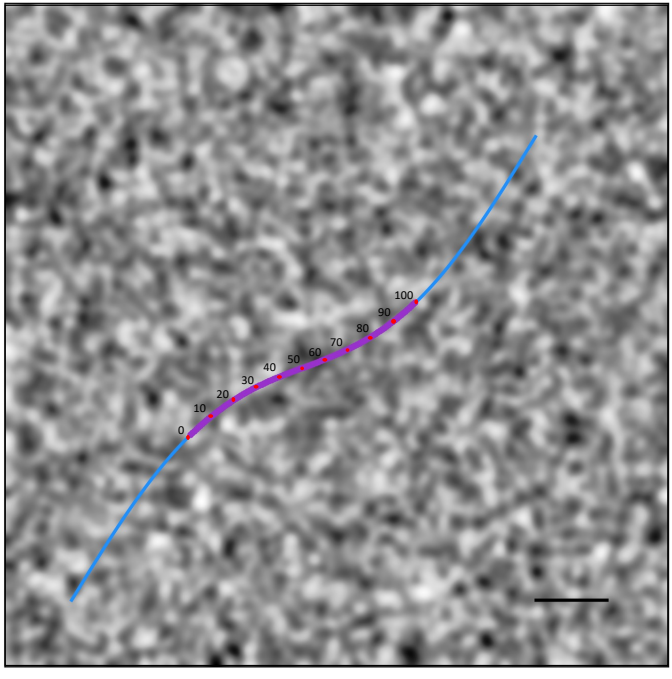


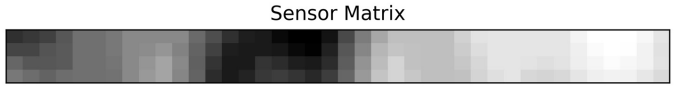


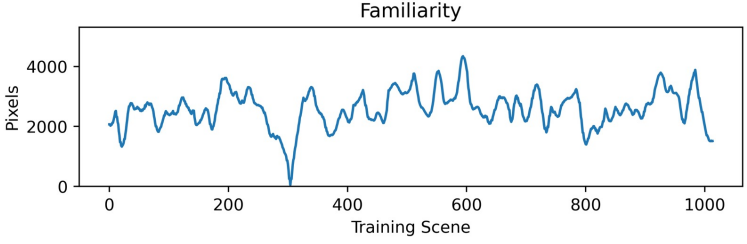
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

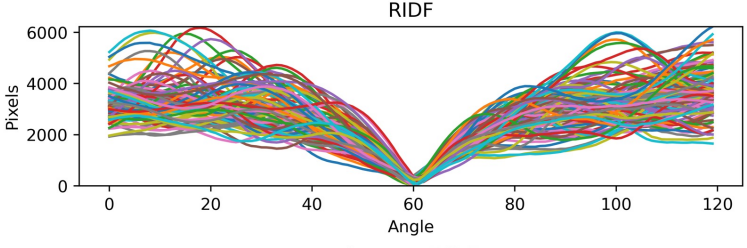
Navigation stats: RMSD error: 66.36; RMSD/dist: 0.166; TD: 2502; p90: 40; p50: 18; complete: 0

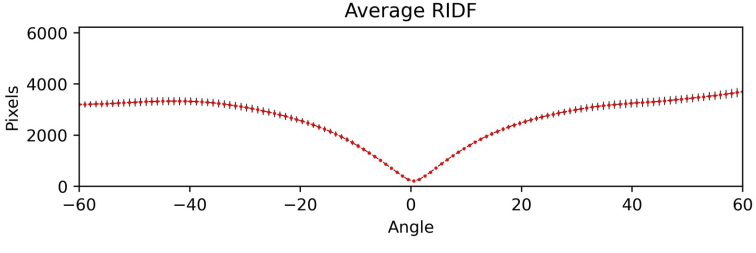
100%







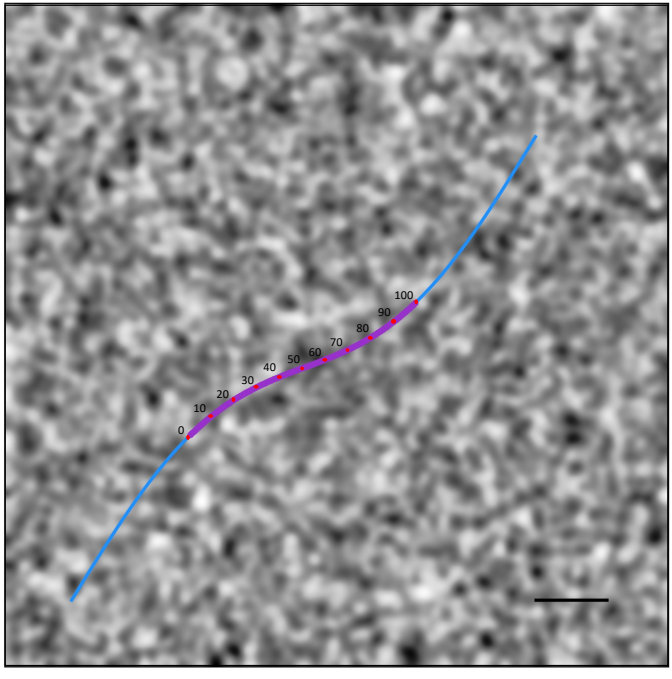


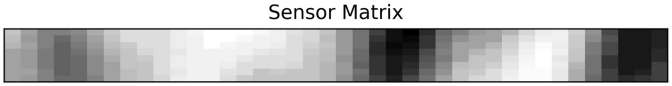


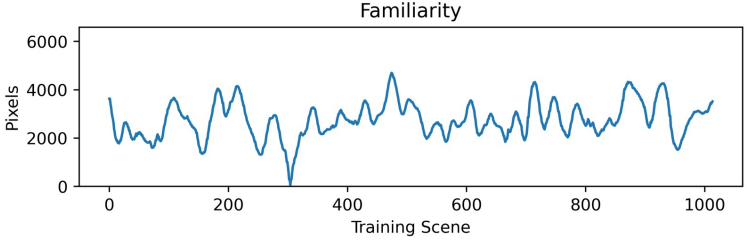
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

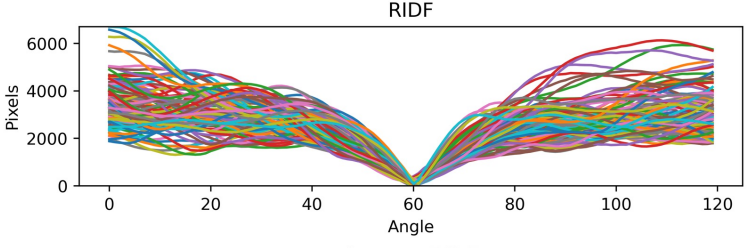
Navigation stats: RMSD error: 71.43; RMSD/dist: 0.179; TD: 2465; p90: 36; p50: 18; complete: 0

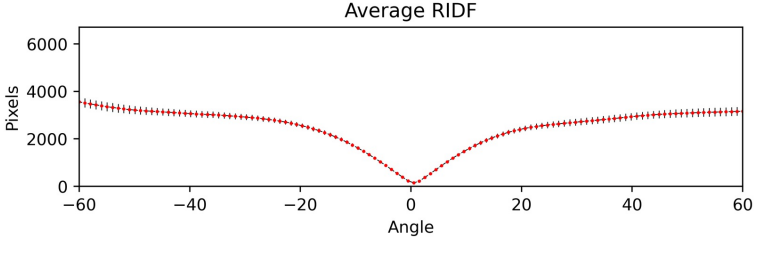
100%







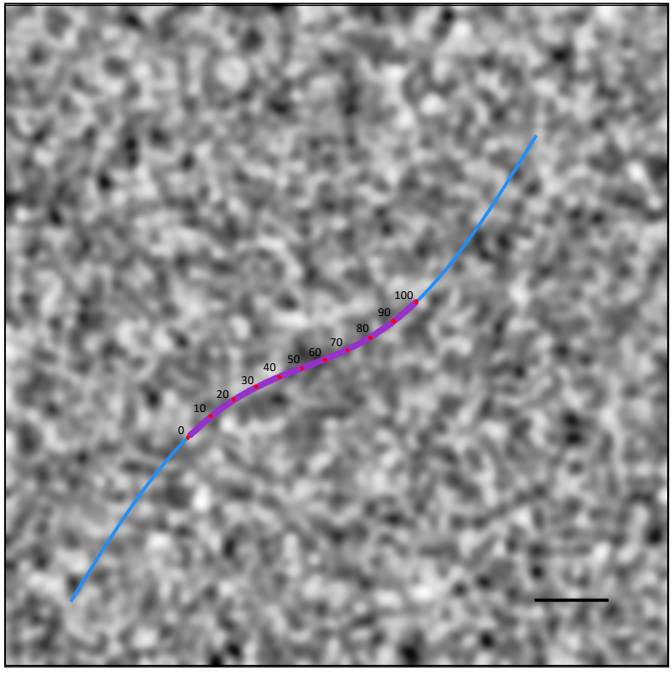


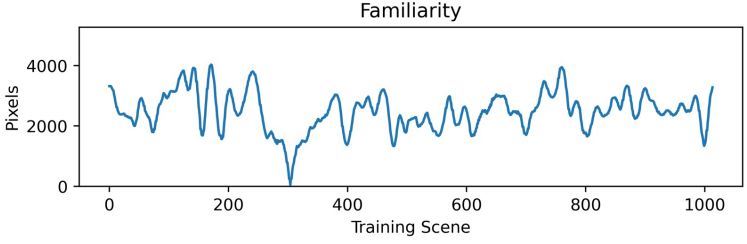


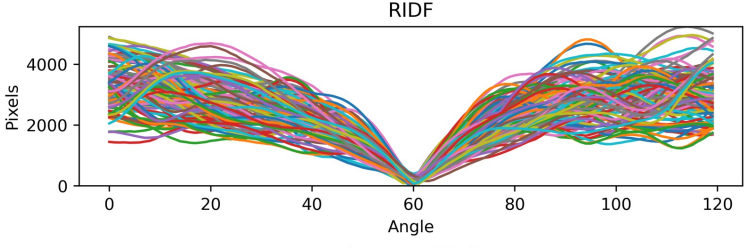
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

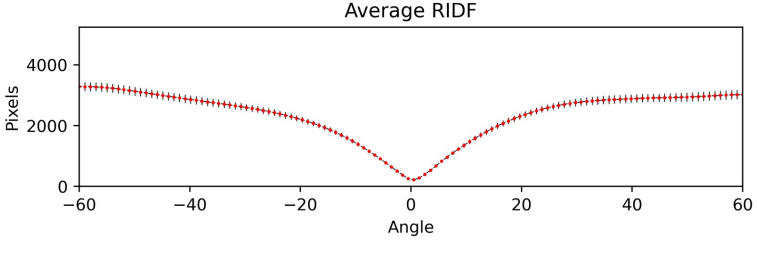
Navigation stats: RMSD error: 35.34; RMSD/dist: 0.088; TD: 2723; p90: 42; p50: 18; complete: 0

100%





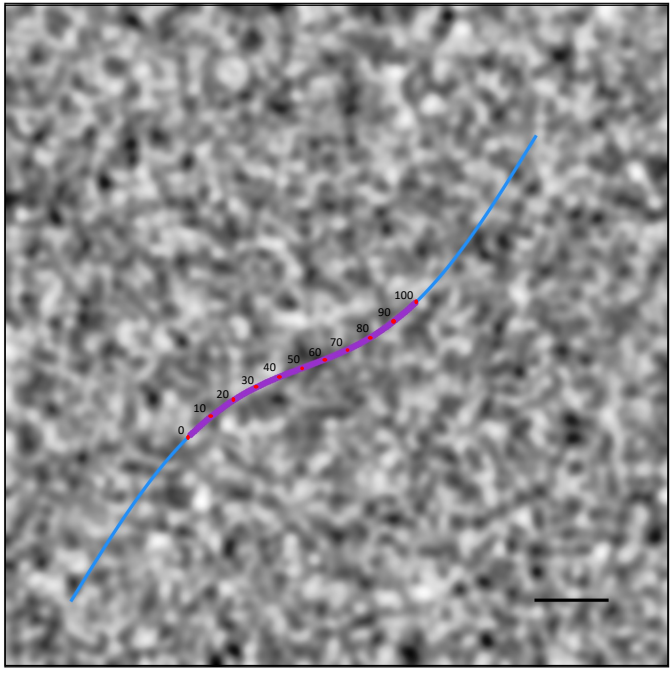


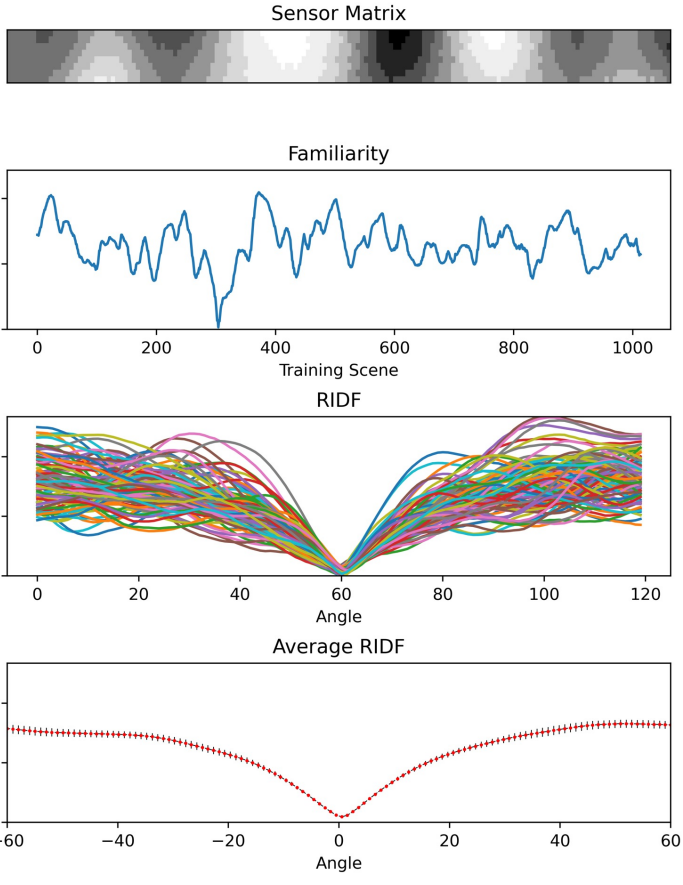


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 78.43; RMSD/dist: 0.196; TD: 2334; p90: 46; p50: 20; complete: 0

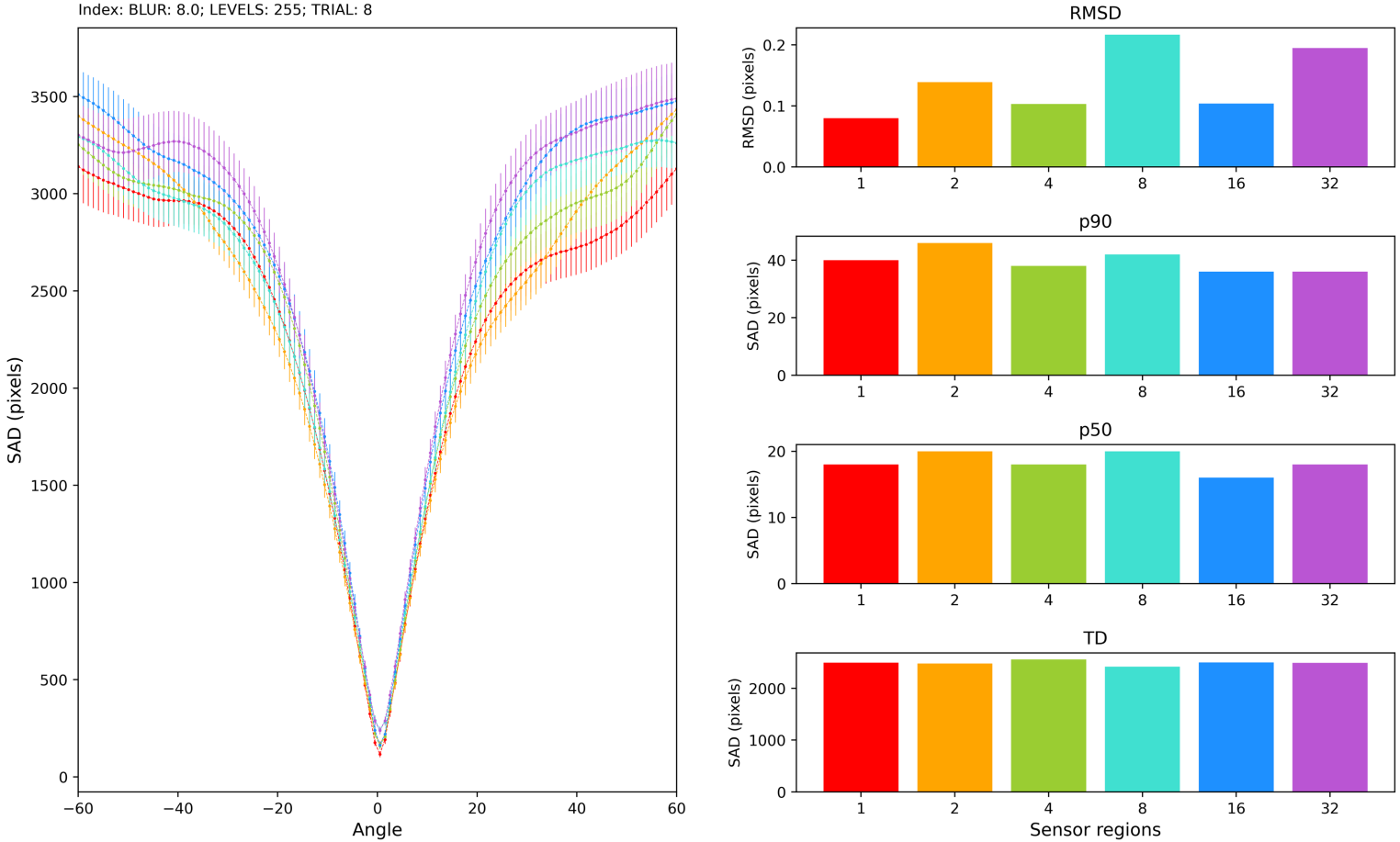
100%



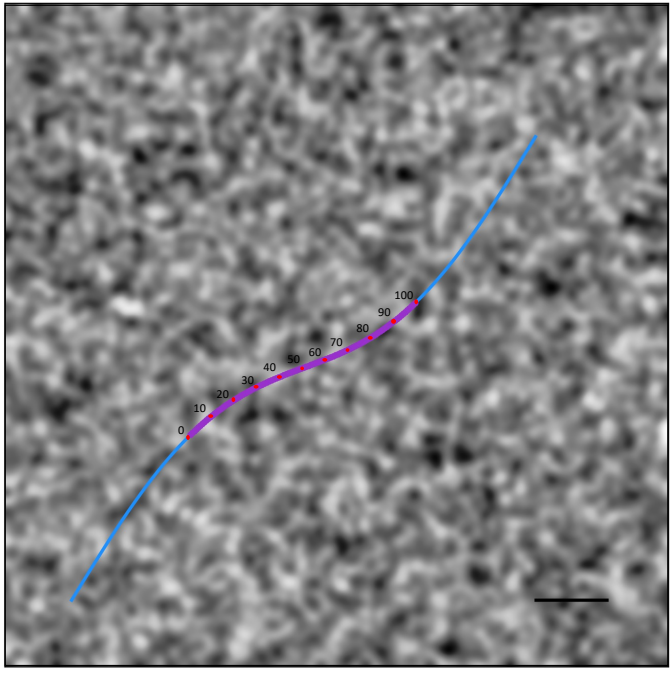


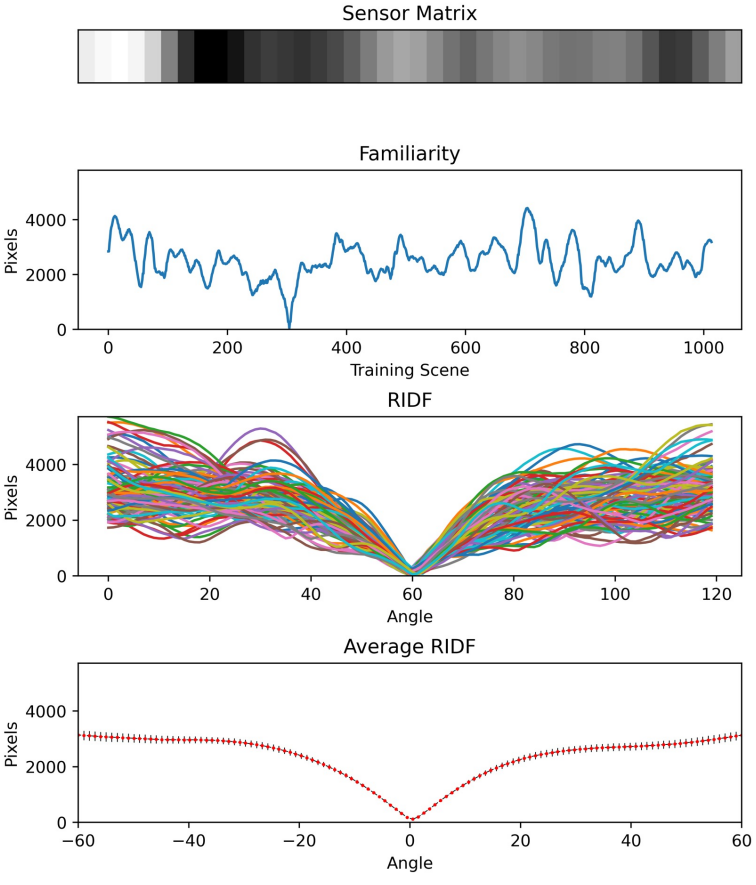
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 60.79; RMSD/dist: 0.152; TD: 2357; p90: 42; p50: 20; complete: 0


Index: BLUR: 8.0; LEVELS: 255; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

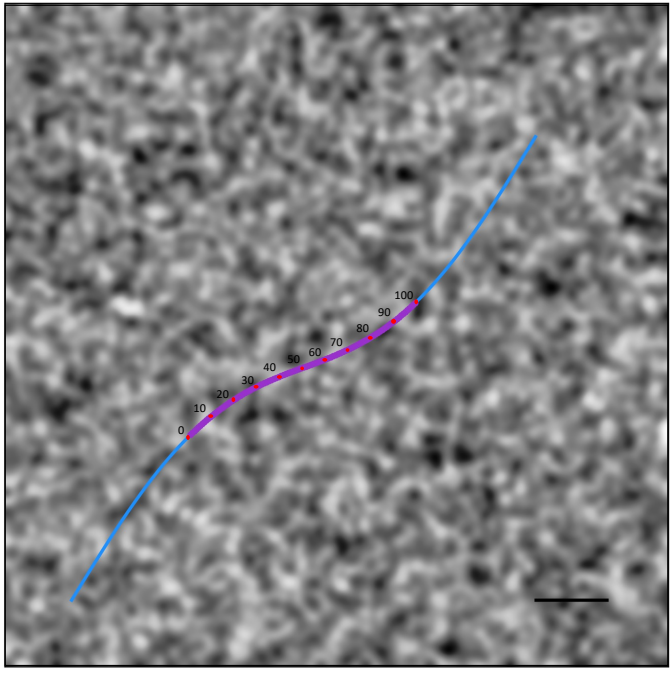


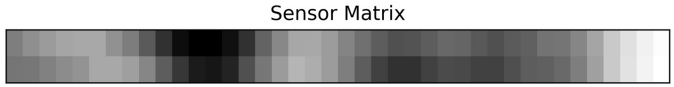


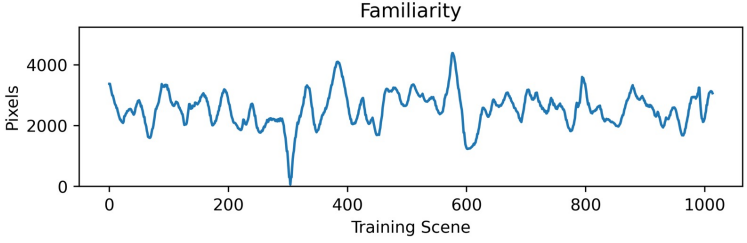
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

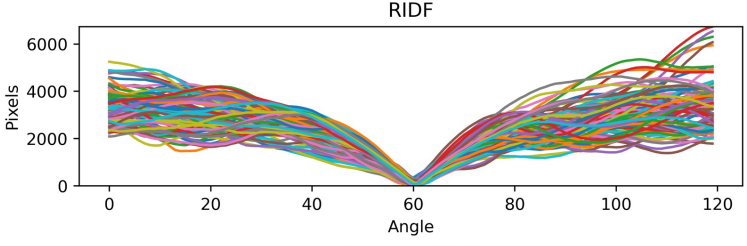
Navigation stats: RMSD error: 32.15; RMSD/dist: 0.080; TD: 2497; p90: 40; p50: 18; complete: 0

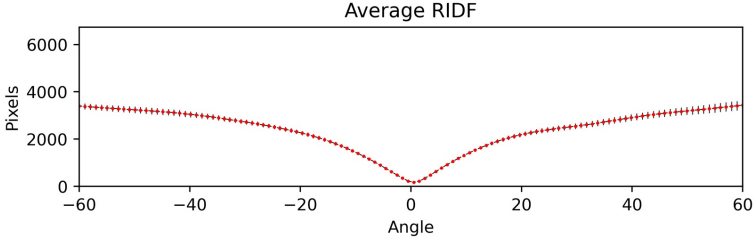
100%







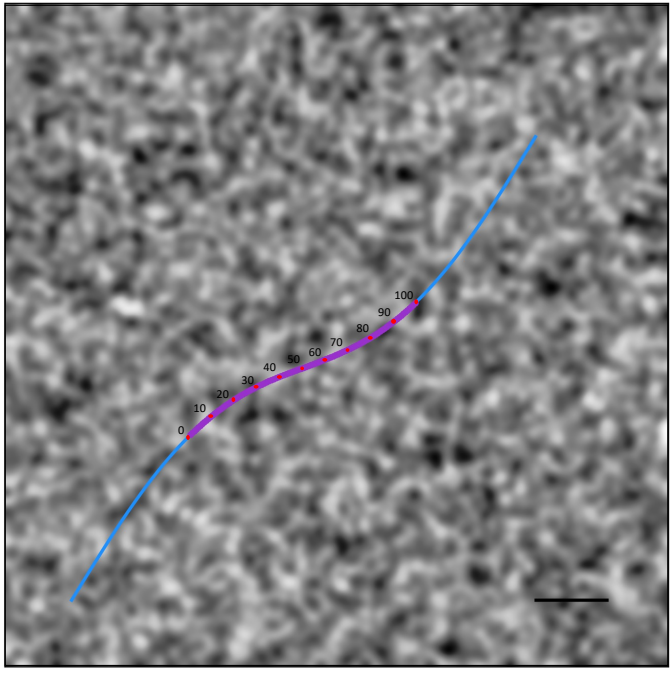


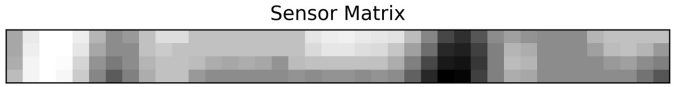


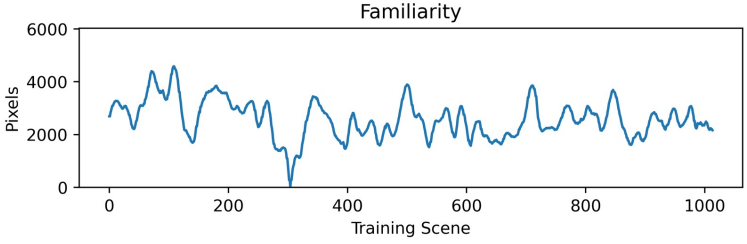
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

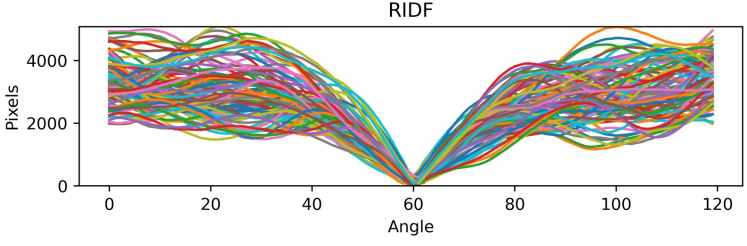
Navigation stats: RMSD error: 55.50; RMSD/dist: 0.139; TD: 2481; p90: 46; p50: 20; complete: 0

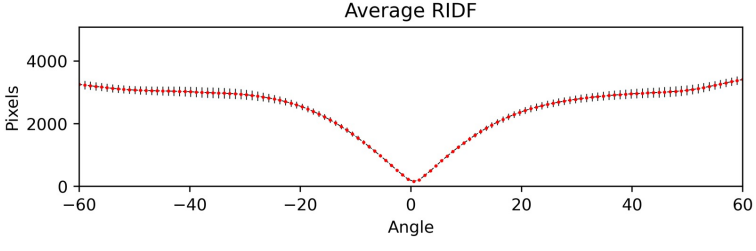
100%







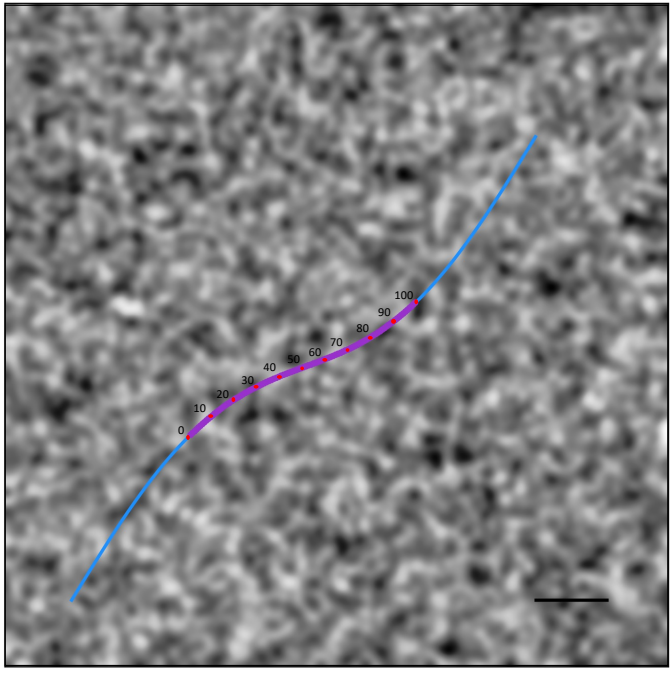


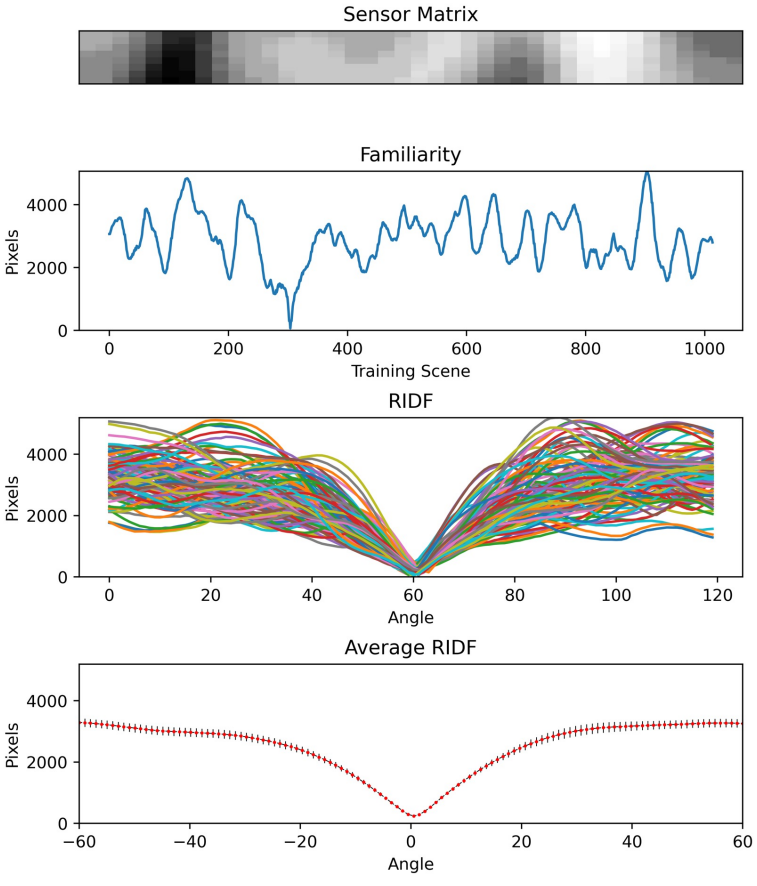


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 41.39; RMSD/dist: 0.103; TD: 2556; p90: 38; p50: 18; complete: 0

100%

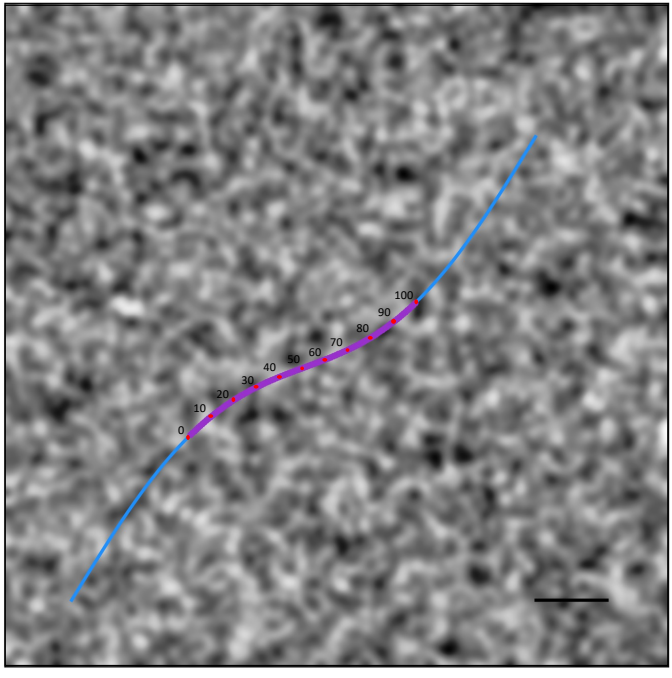


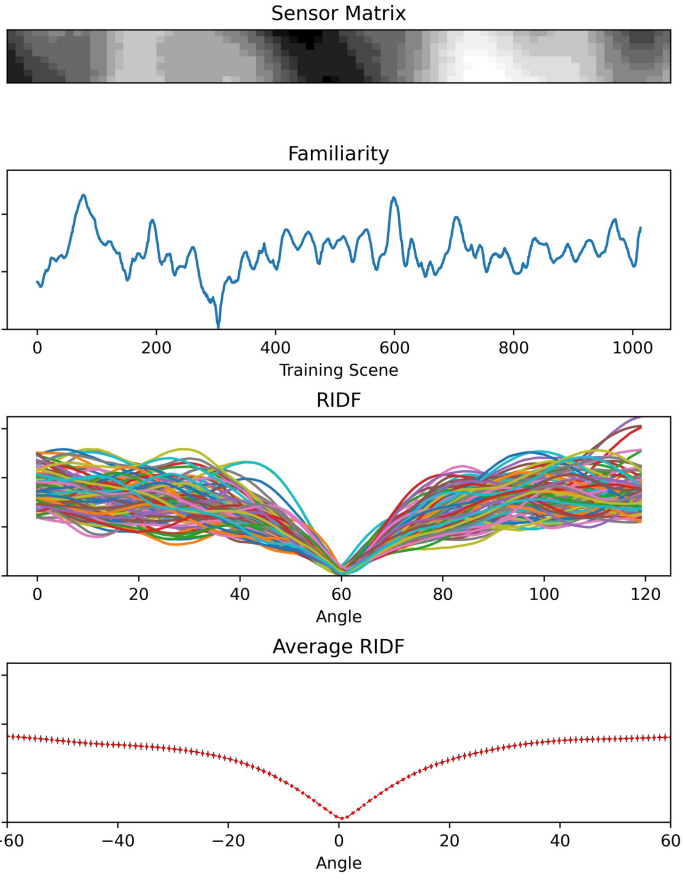


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 86.85; RMSD/dist: 0.217; TD: 2420; p90: 42; p50: 20; complete: 0

100%

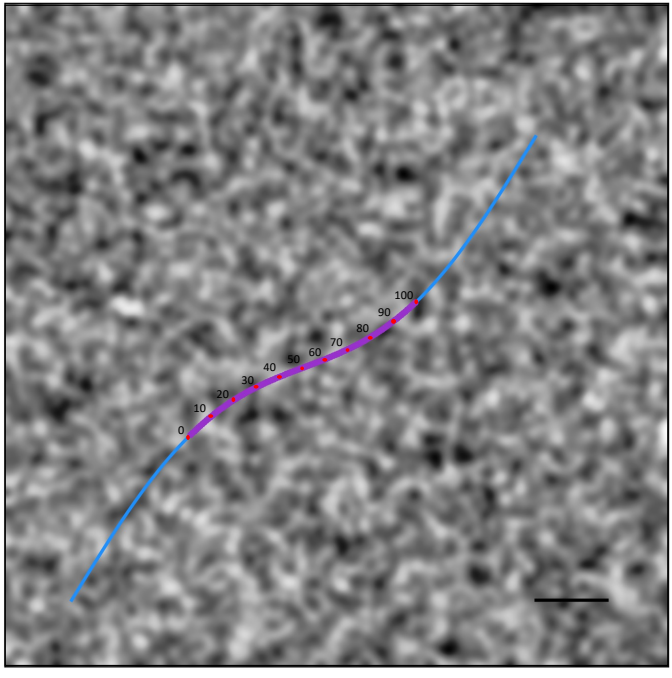


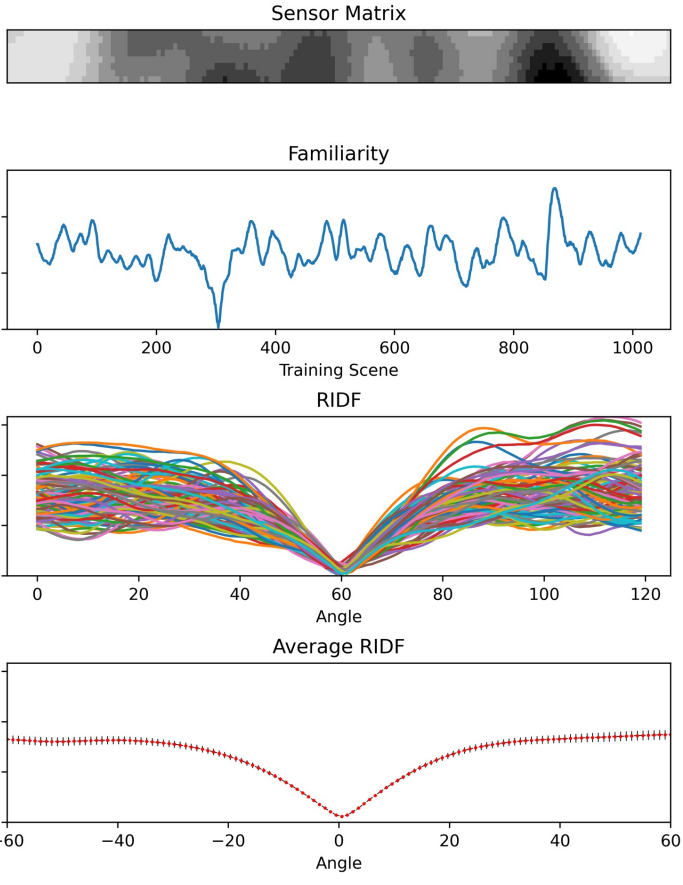


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 41.61; RMSD/dist: 0.104; TD: 2502; p90: 36; p50: 16; complete: 0

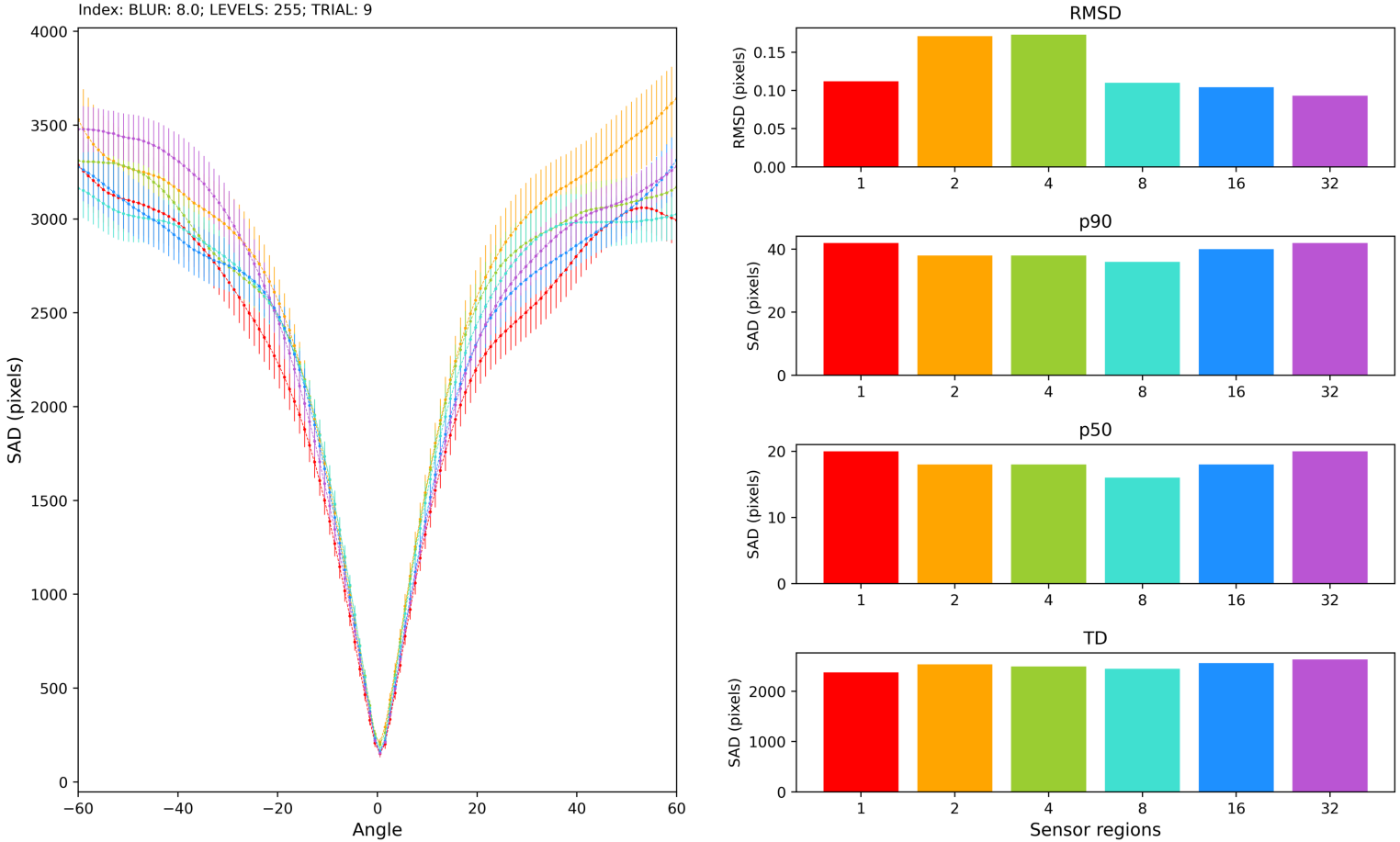
100%



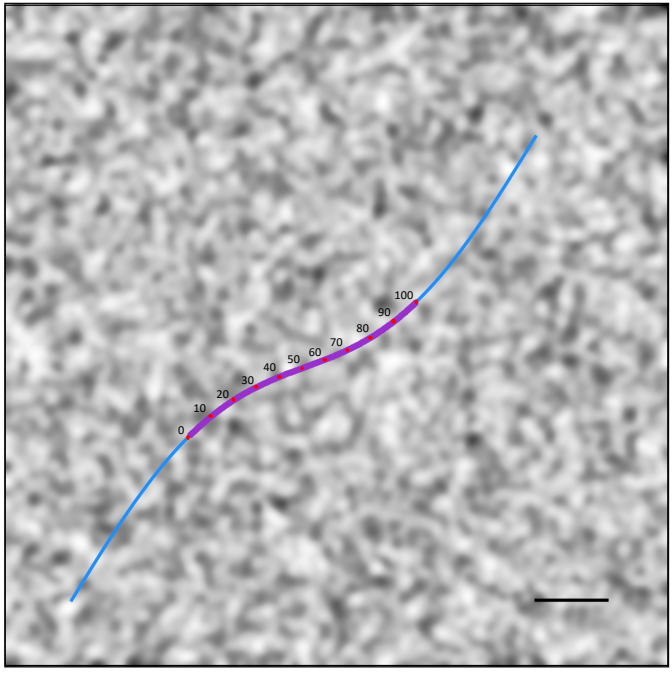


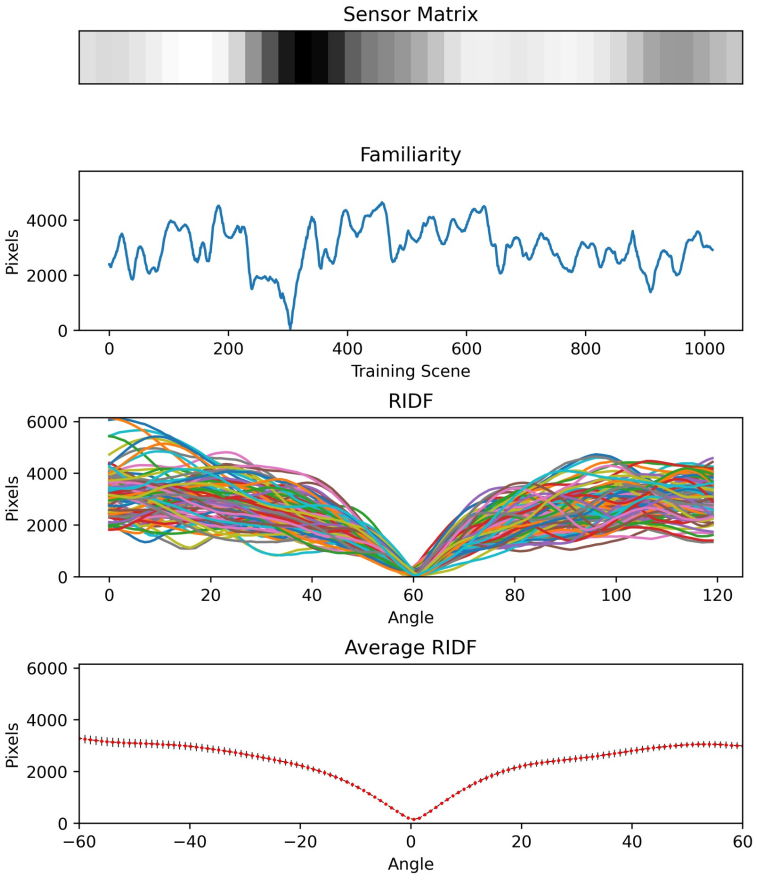
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 78.06; RMSD/dist: 0.195; TD: 2494; p90: 36; p50: 18; complete: 0


Index: BLUR: 8.0; LEVELS: 255; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

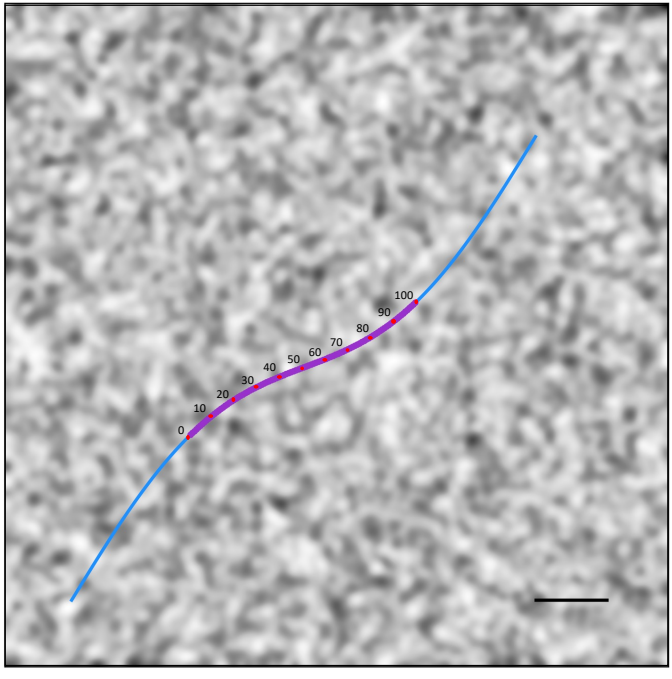


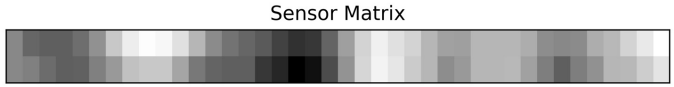


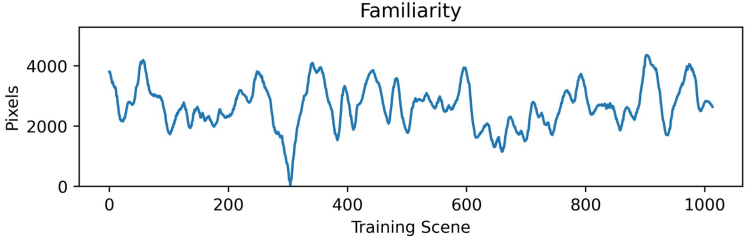
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

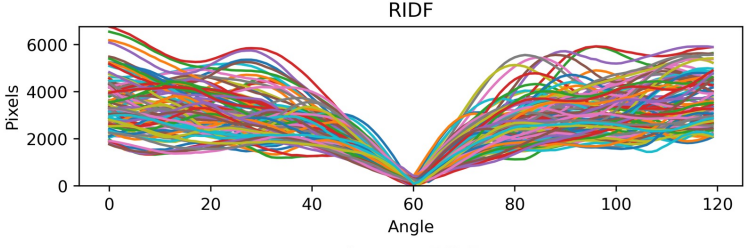
Navigation stats: RMSD error: 44.68; RMSD/dist: 0.112; TD: 2375; p90: 42; p50: 20; complete: 0

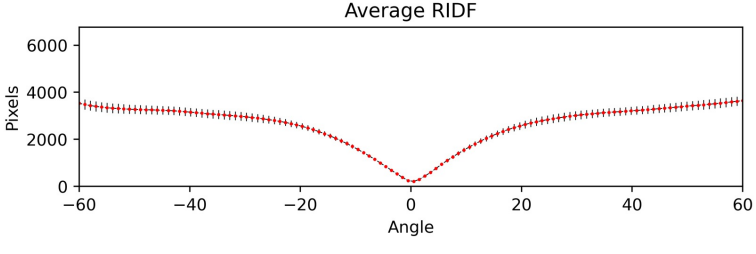
100%







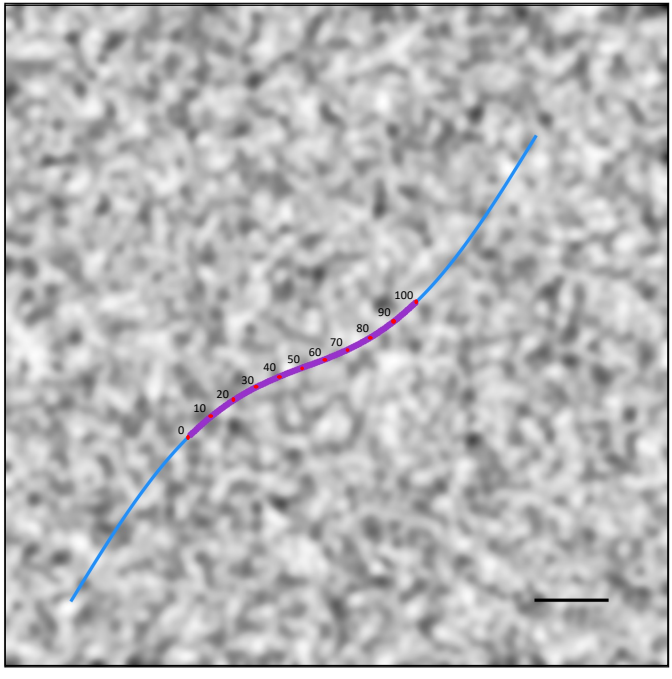


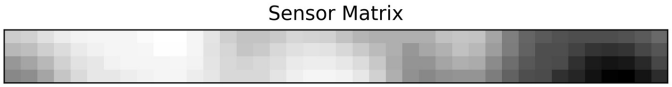


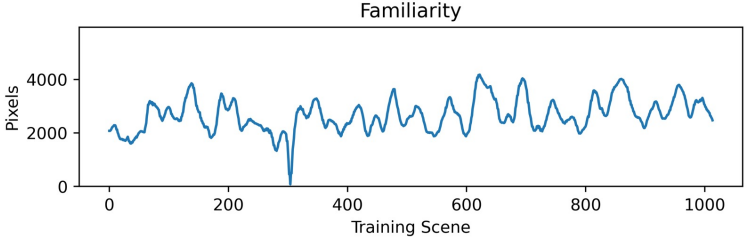
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

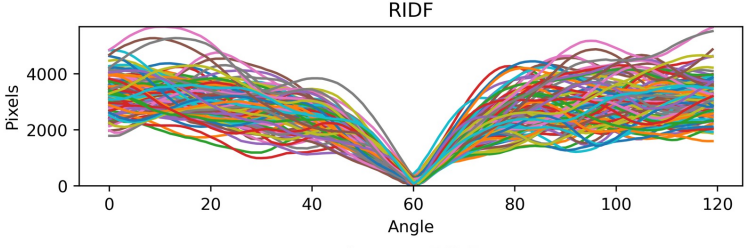
Navigation stats: RMSD error: 68.58; RMSD/dist: 0.171; TD: 2536; p90: 38; p50: 18; complete: 0

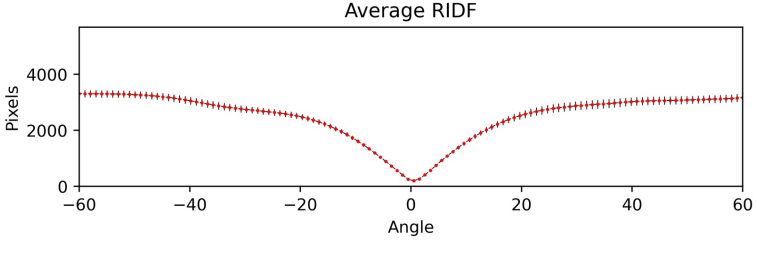
100%







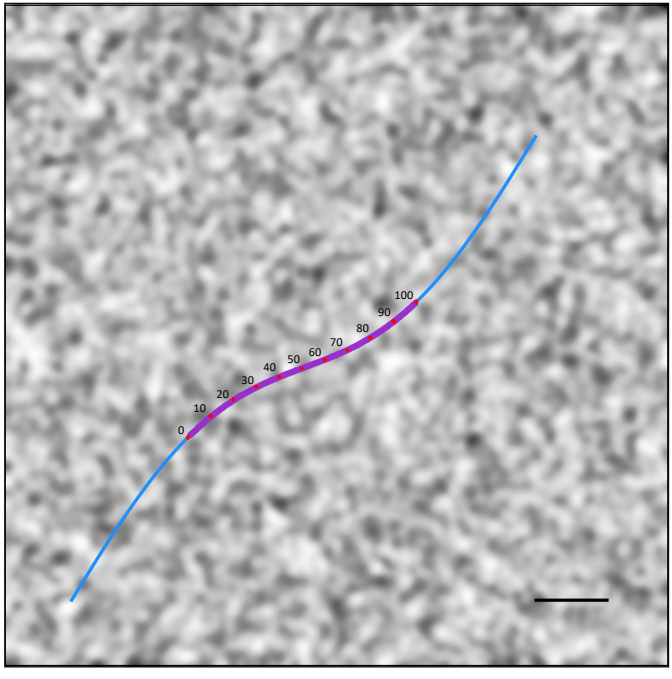


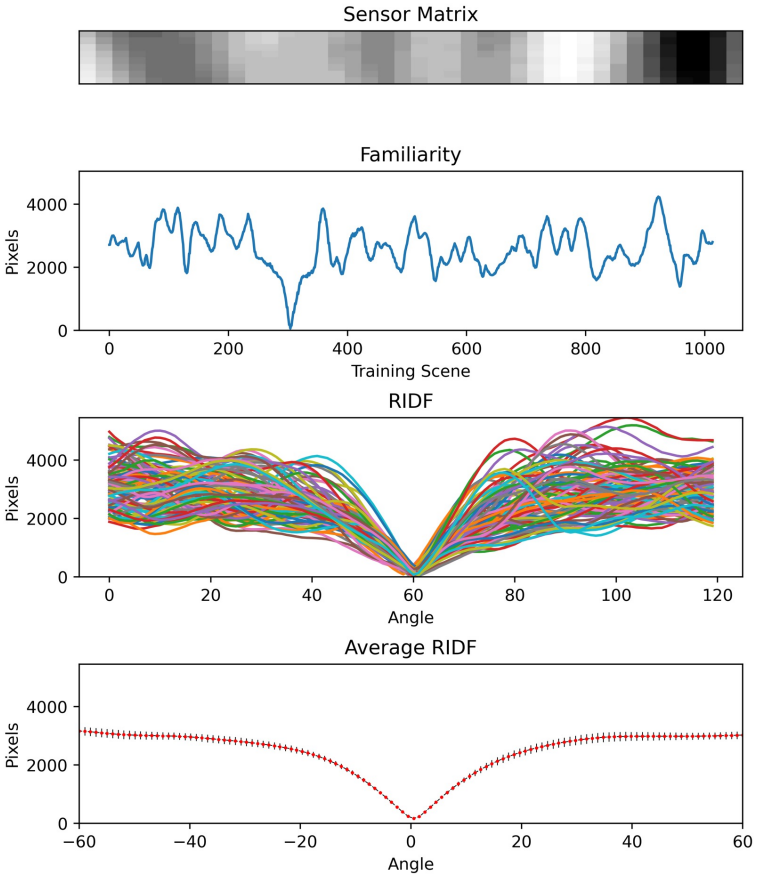


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 69.06; RMSD/dist: 0.173; TD: 2495; p90: 38; p50: 18; complete: 0

100%

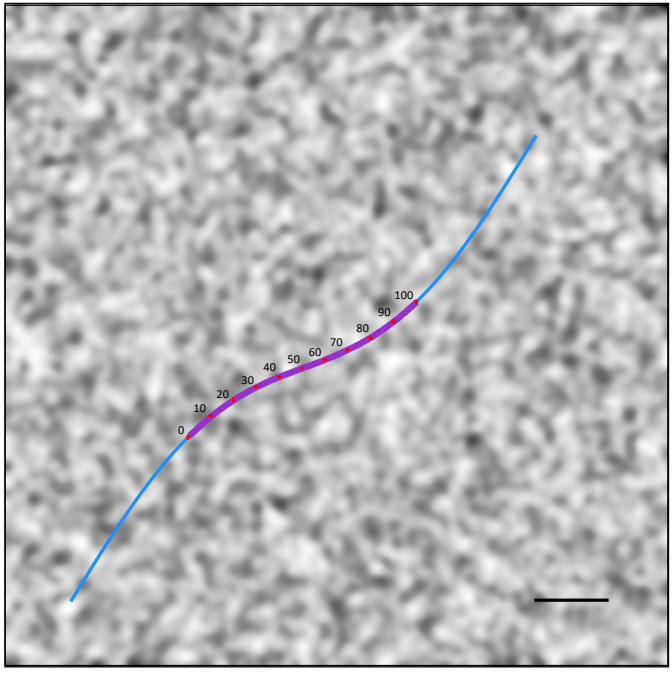


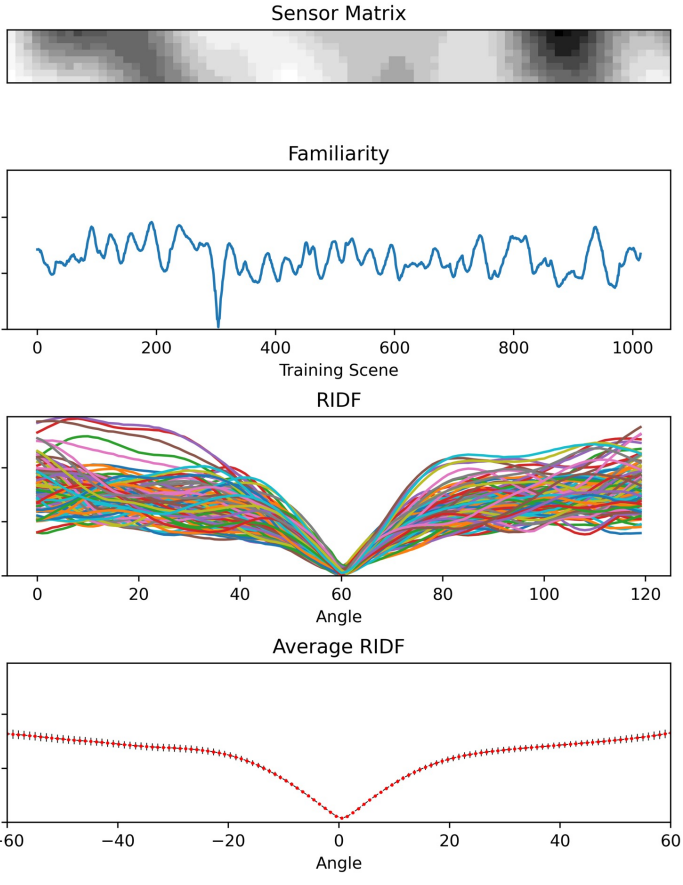


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 43.81; RMSD/dist: 0.110; TD: 2447; p90: 36; p50: 16; complete: 0

100%

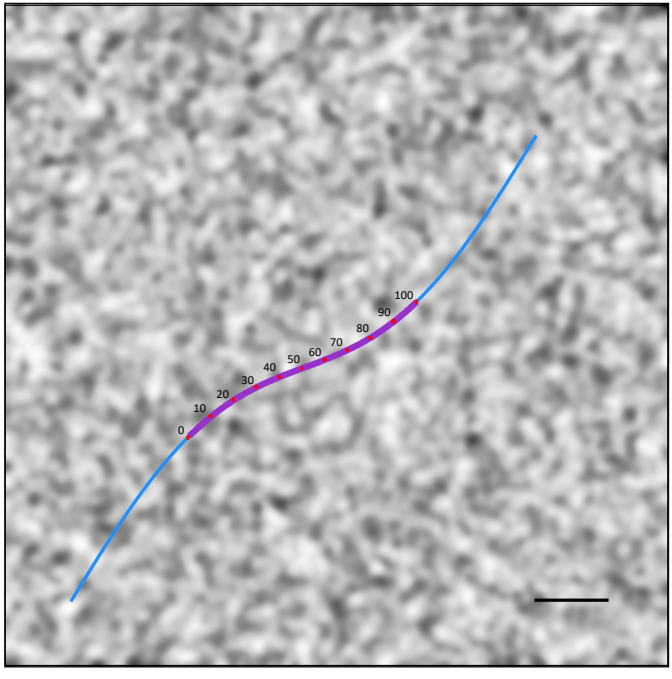


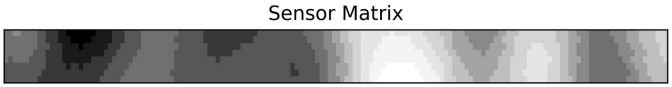


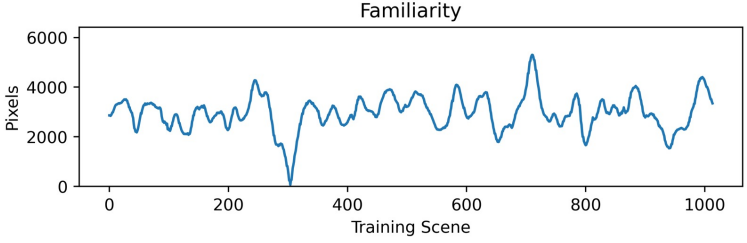
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

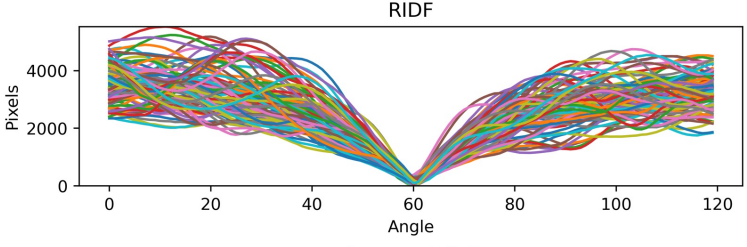
Navigation stats: RMSD error: 41.56; RMSD/dist: 0.104; TD: 2563; p90: 40; p50: 18; complete: 0

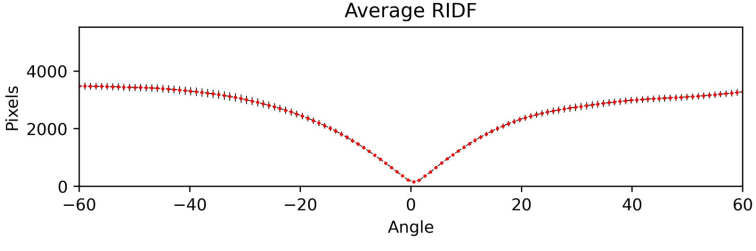
100%





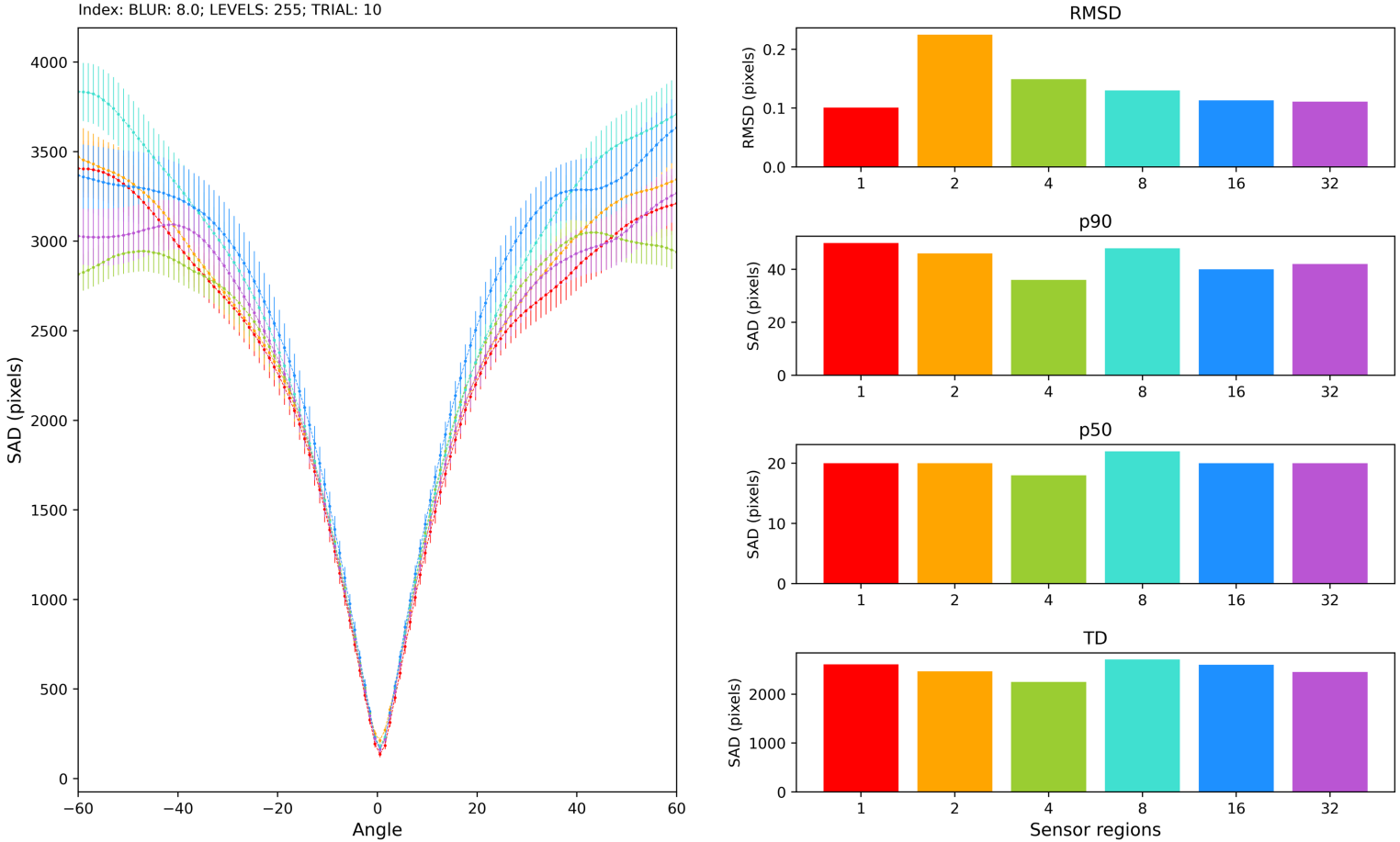




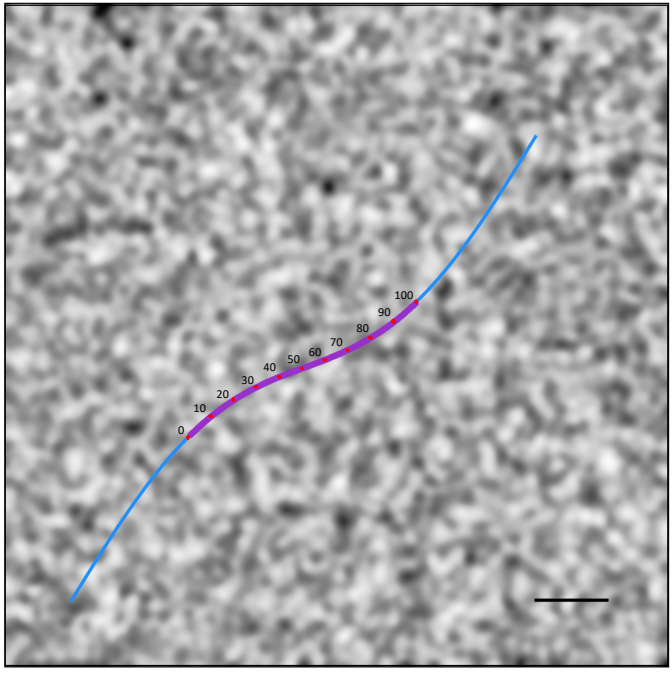


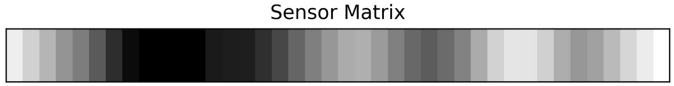
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

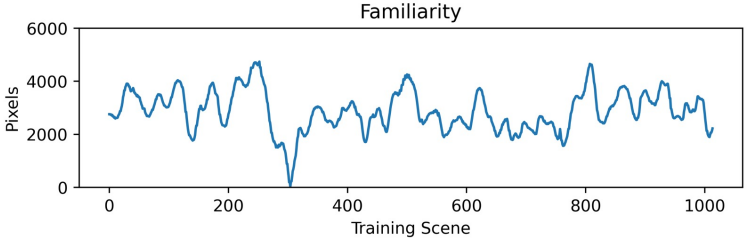
Navigation stats: RMSD error: 37.11; RMSD/dist: 0.093; TD: 2632; p90: 42; p50: 20; complete: 0

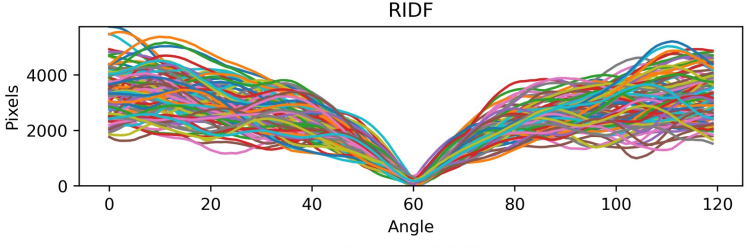

Index: BLUR: 8.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

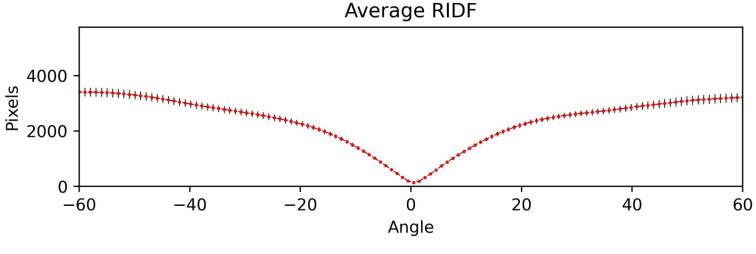
100%







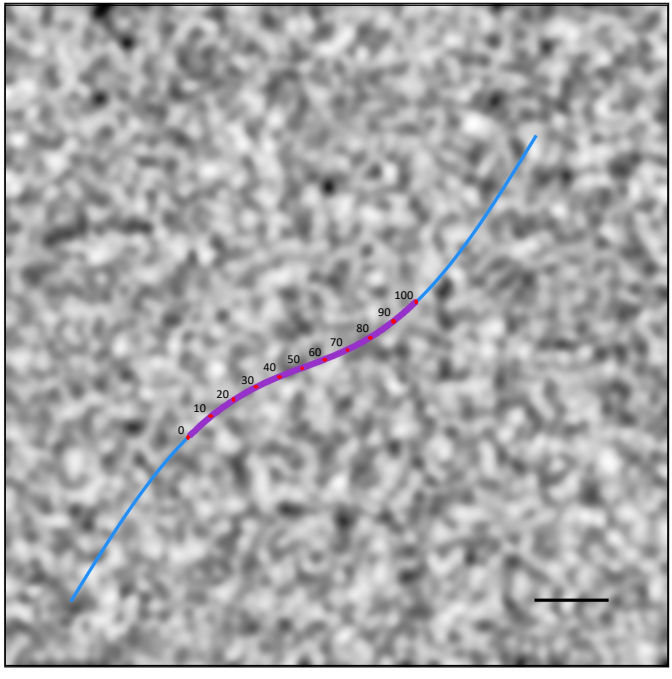


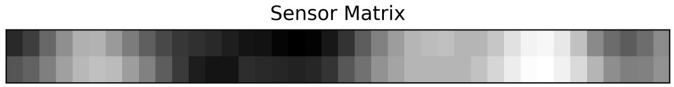


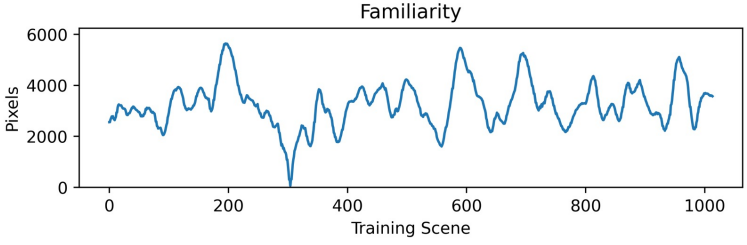
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

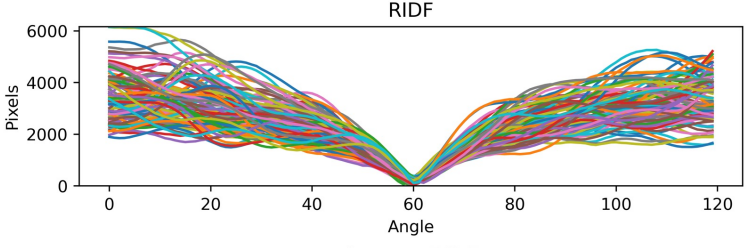
Navigation stats: RMSD error: 40.38; RMSD/dist: 0.101; TD: 2611; p90: 50; p50: 20; complete: 0

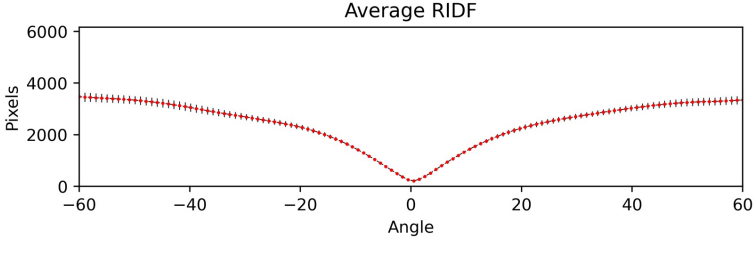
100%







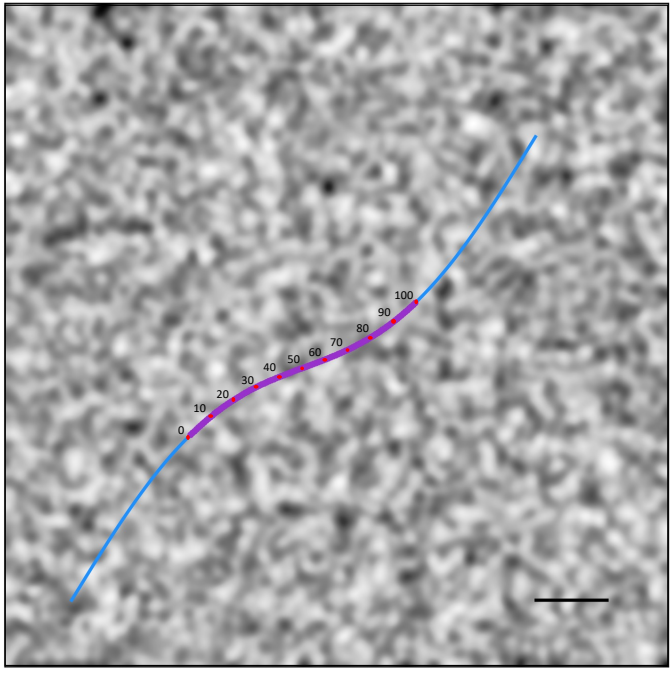


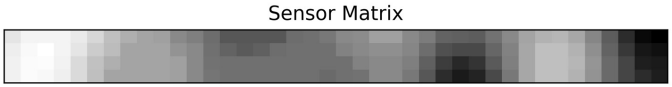


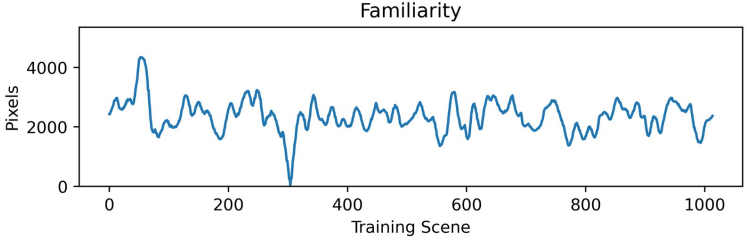
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

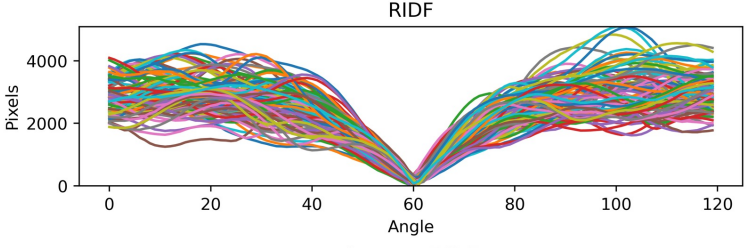
Navigation stats: RMSD error: 89.89; RMSD/dist: 0.225; TD: 2466; p90: 46; p50: 20; complete: 0

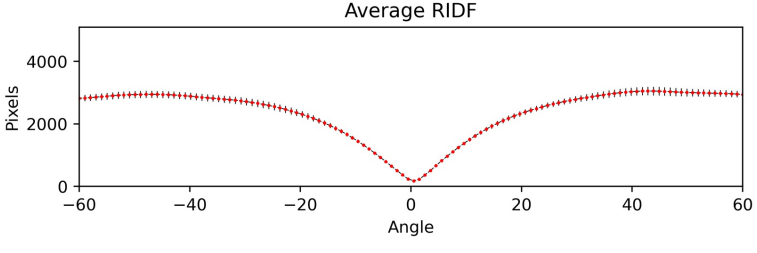
100%







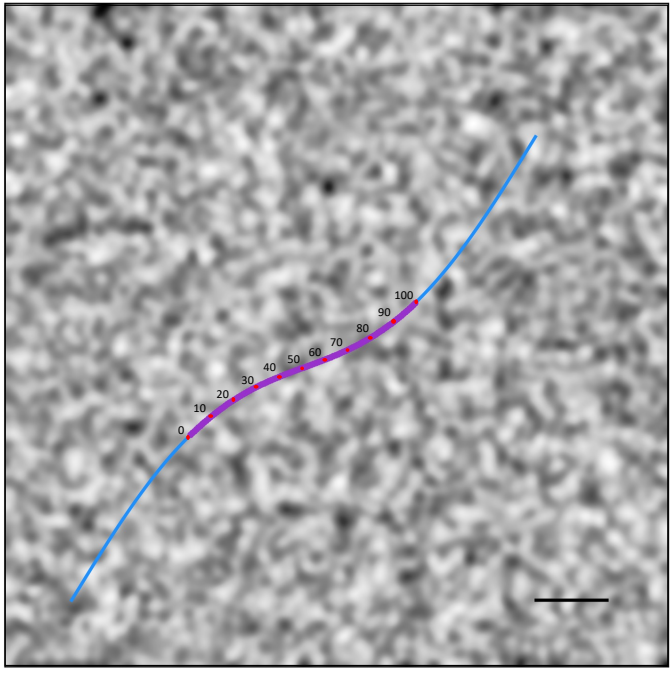


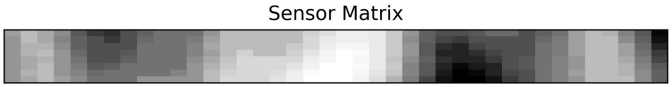


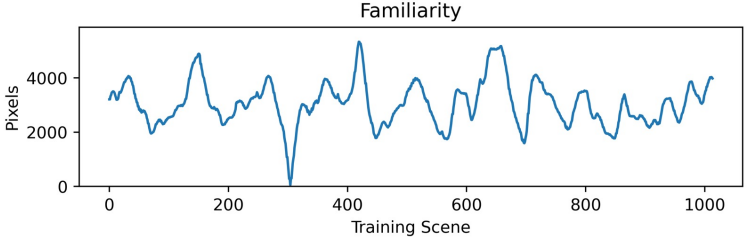
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

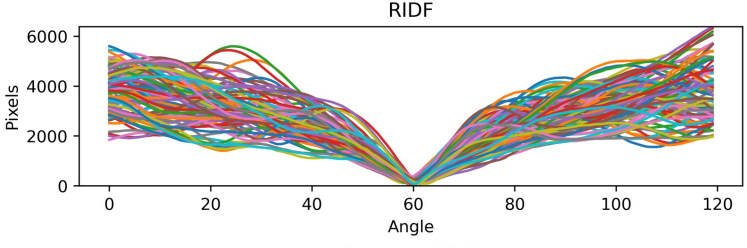
Navigation stats: RMSD error: 59.44; RMSD/dist: 0.149; TD: 2248; p90: 36; p50: 18; complete: 0

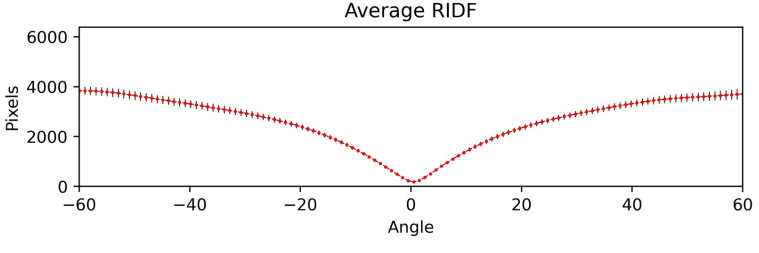
100%







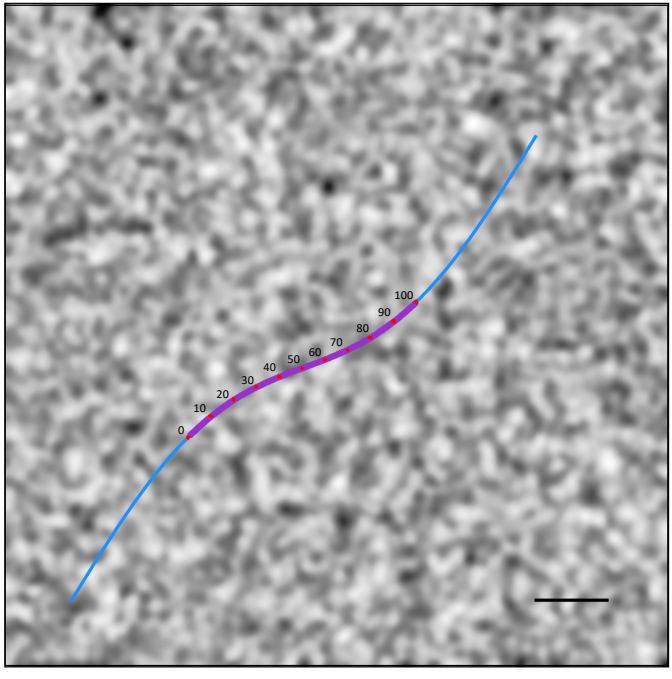


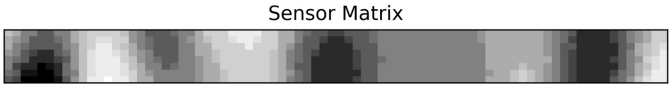


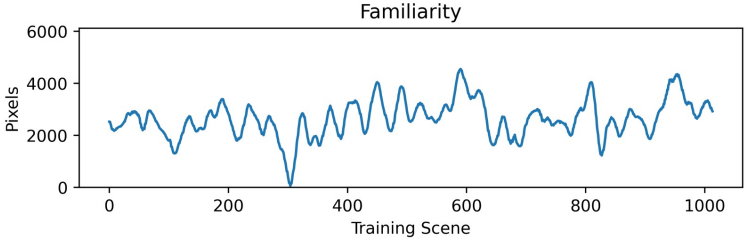
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

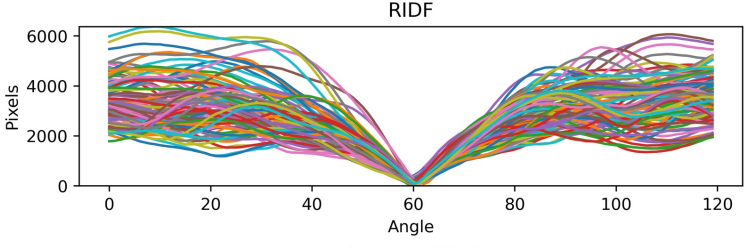
Navigation stats: RMSD error: 51.87; RMSD/dist: 0.130; TD: 2707; p90: 48; p50: 22; complete: 0

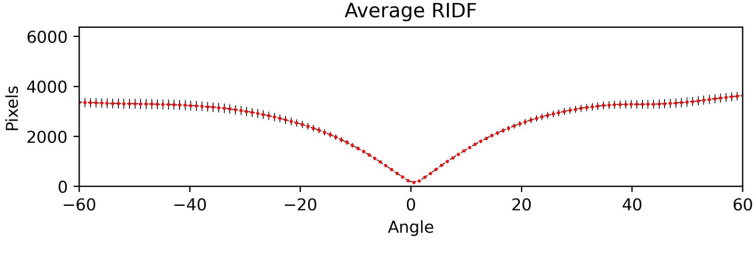
100%







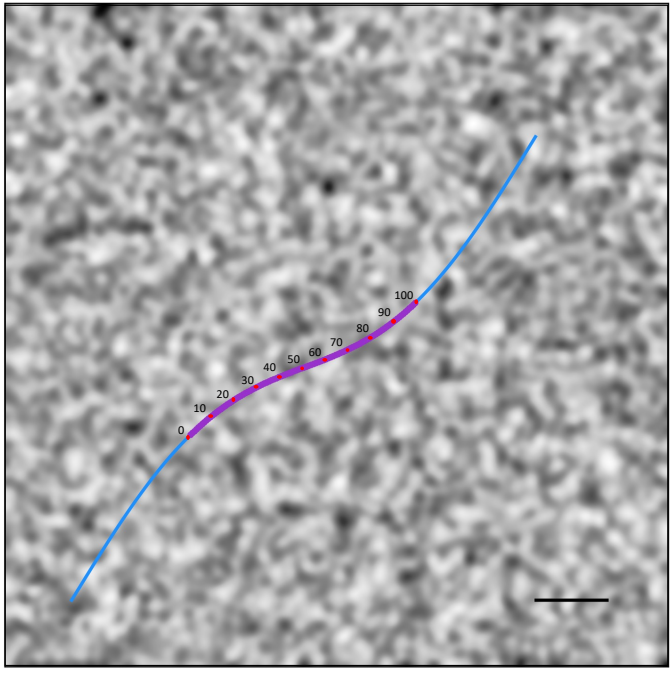


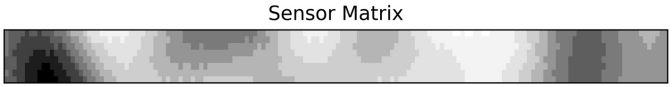


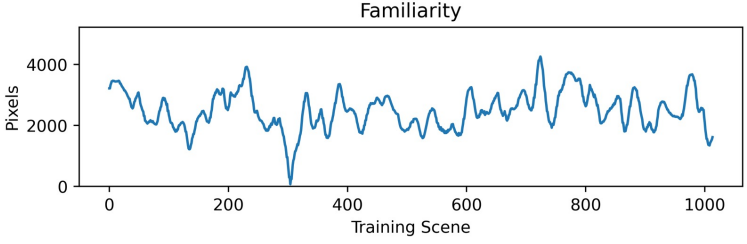
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

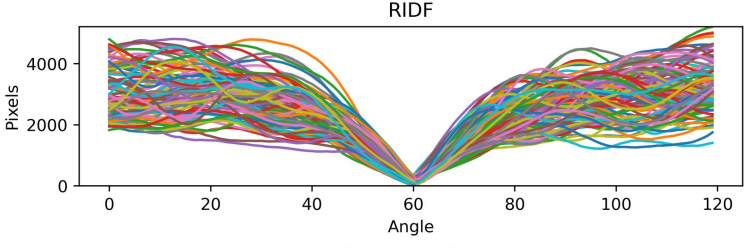
Navigation stats: RMSD error: 45.02; RMSD/dist: 0.113; TD: 2599; p90: 40; p50: 20; complete: 0

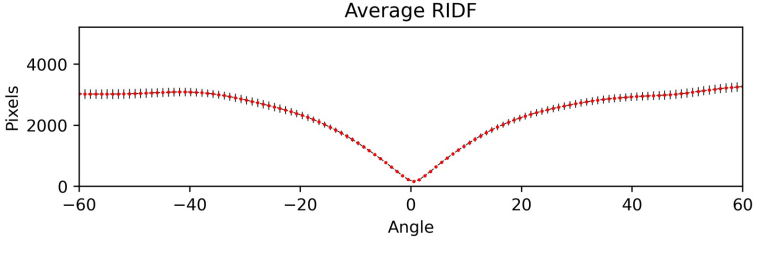
100%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 44.57; RMSD/dist: 0.111; TD: 2452; p90: 42; p50: 20; complete: 0