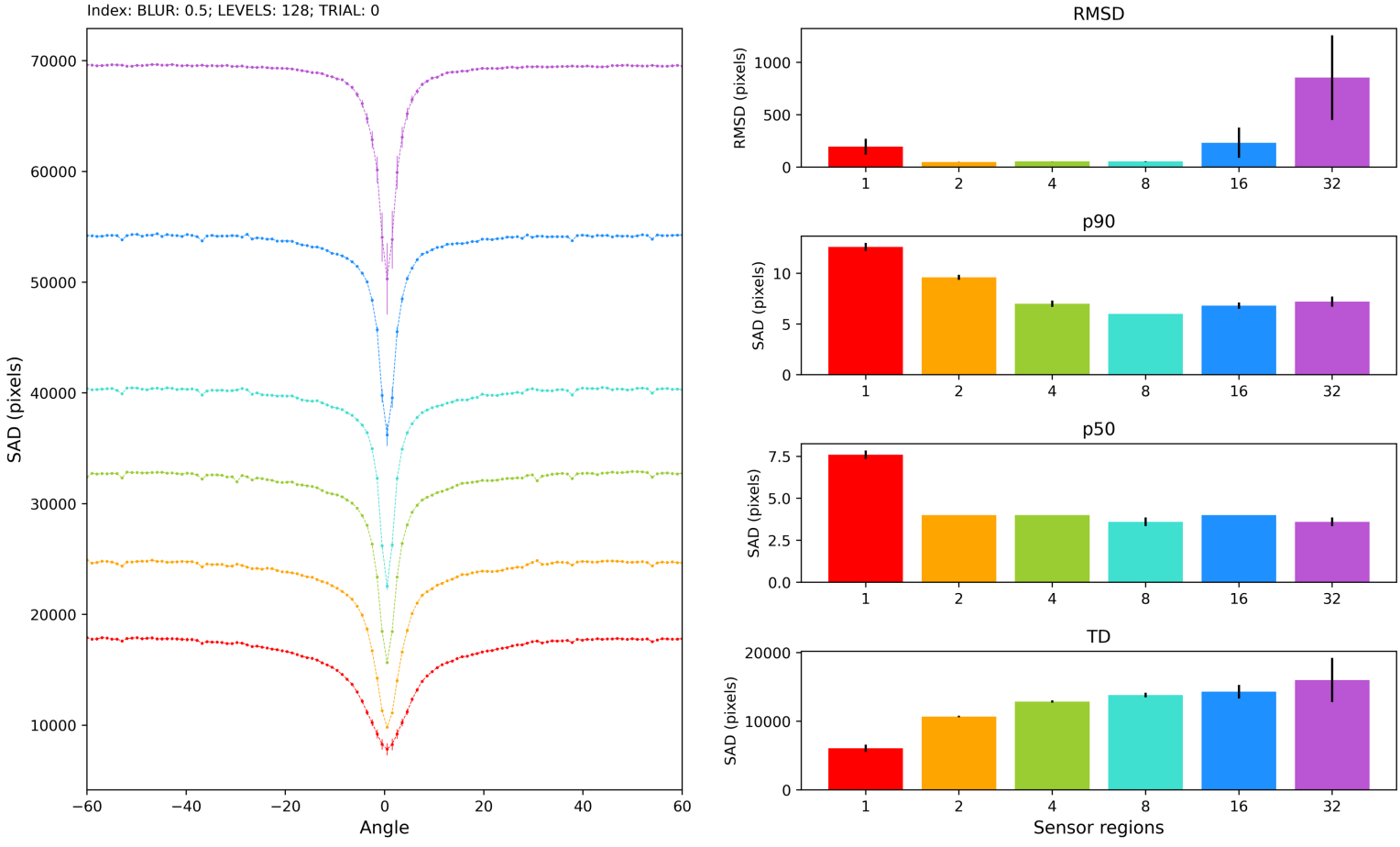
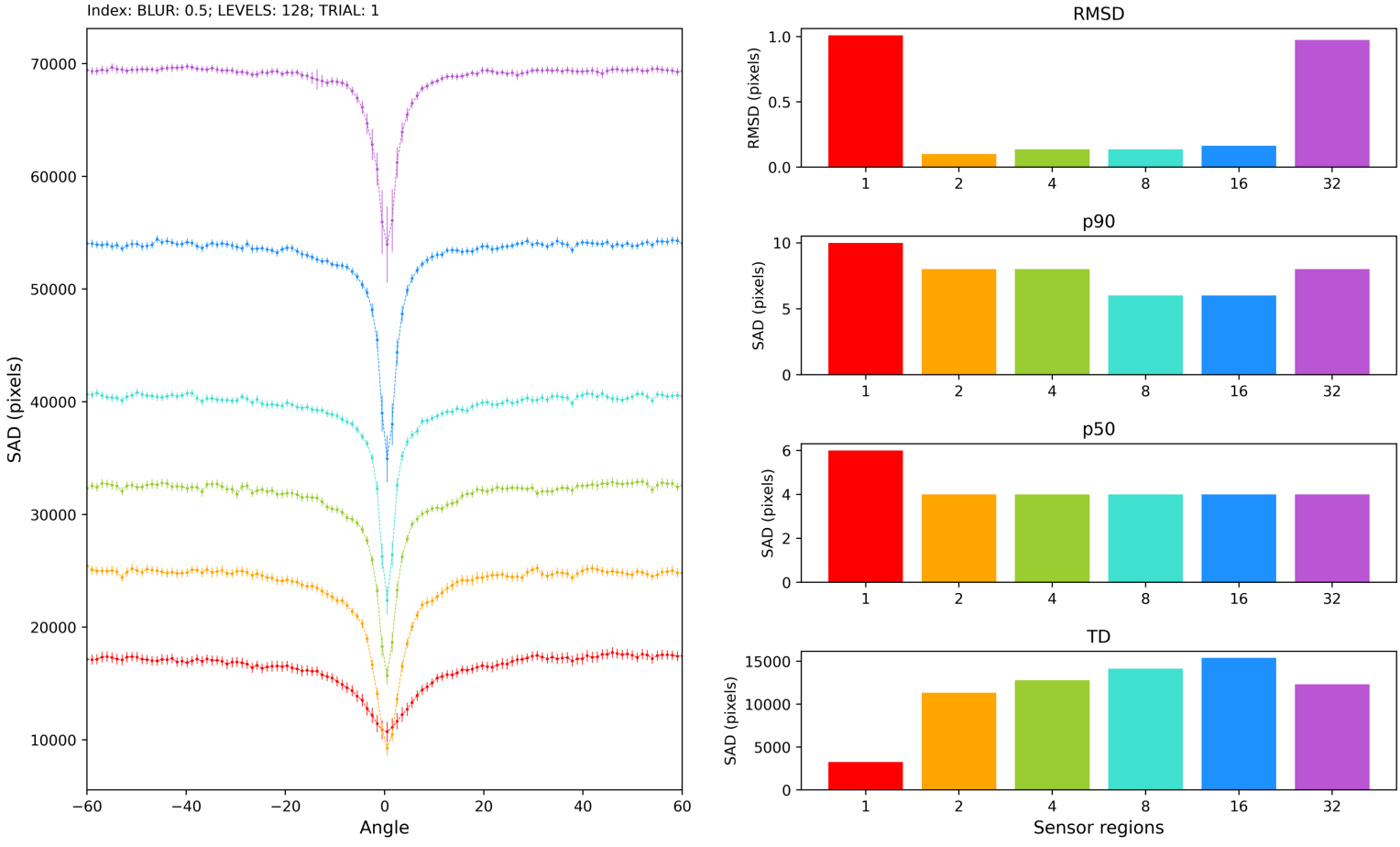

Index: BLUR: 0.5; LEVELS: 128; TRIAL: 0
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
1000
500
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions


Index: BLUR: 0.5; LEVELS: 128; TRIAL: 1
SAD (pixels)
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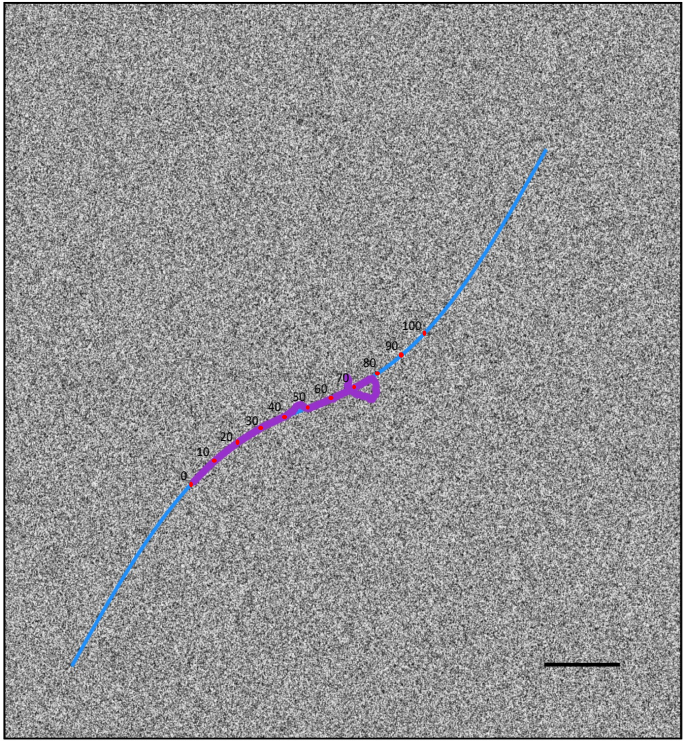
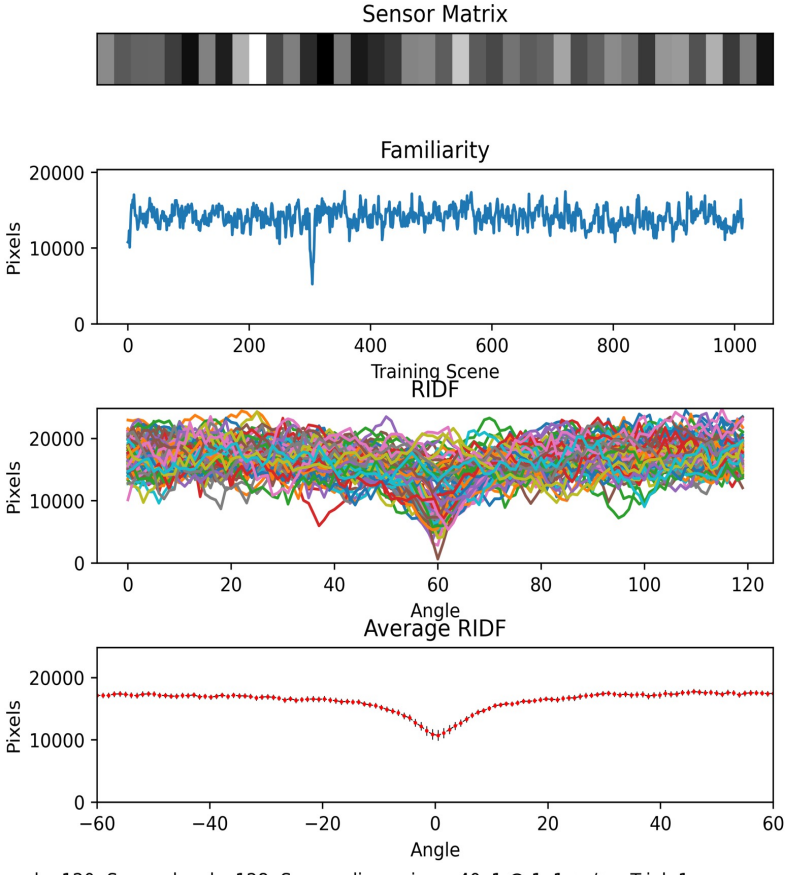
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
1.0
0.5
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
6
4
2
0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

60%

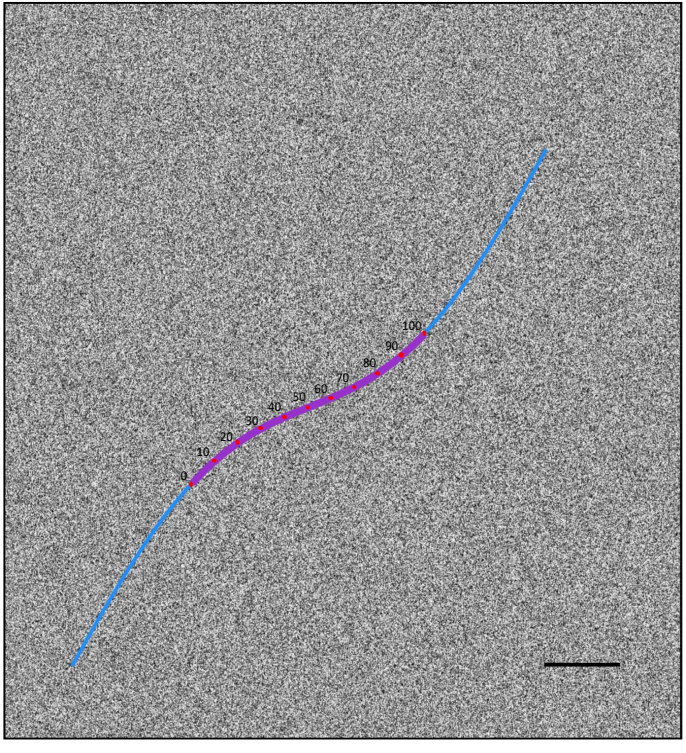


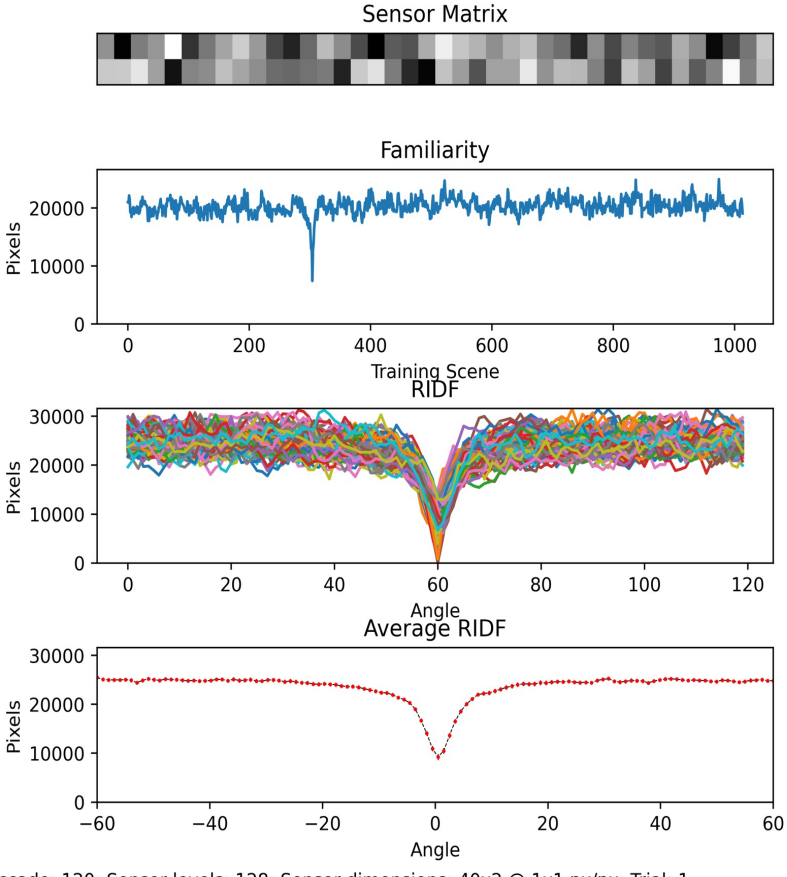




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 404.55; RMSD/dist: 1.011; TD: 3245; p90: 10; p50: 6; complete: 0

100%

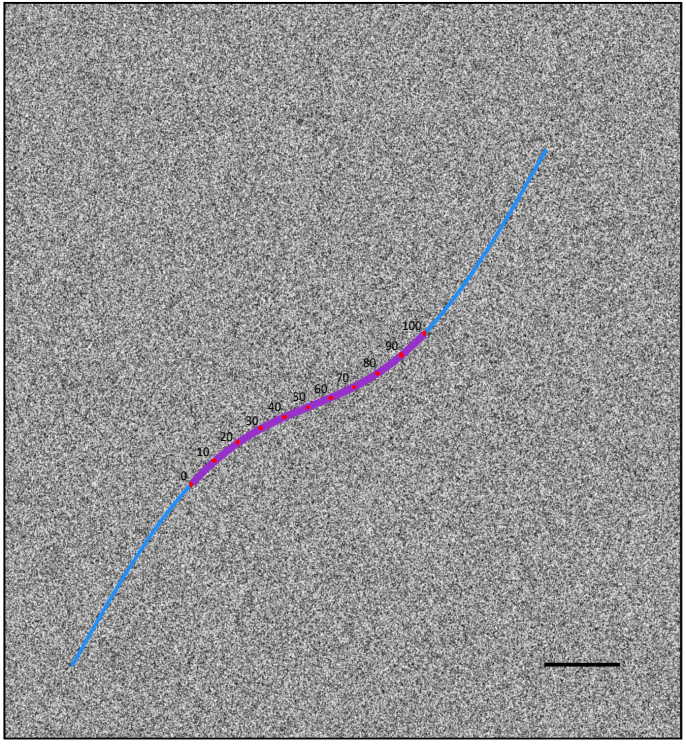


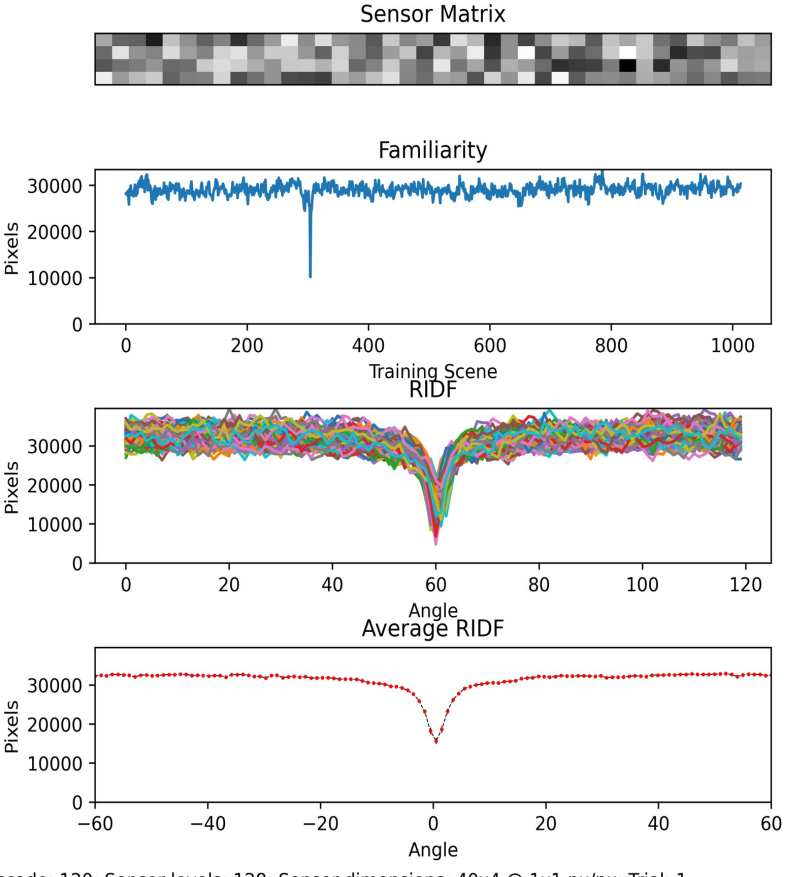




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 40.00; RMSD/dist: 0.100; TD: 11335; p90: 8; p50: 4; complete: 0

100%

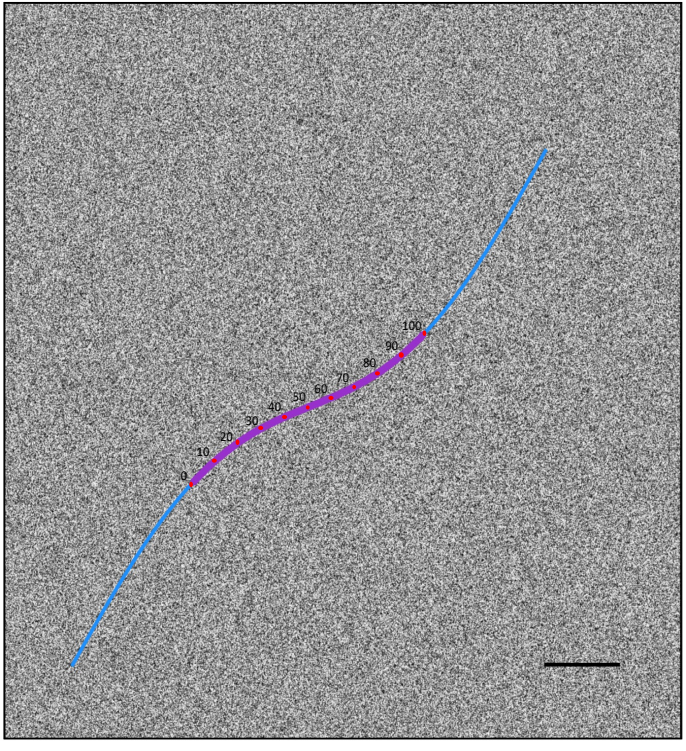


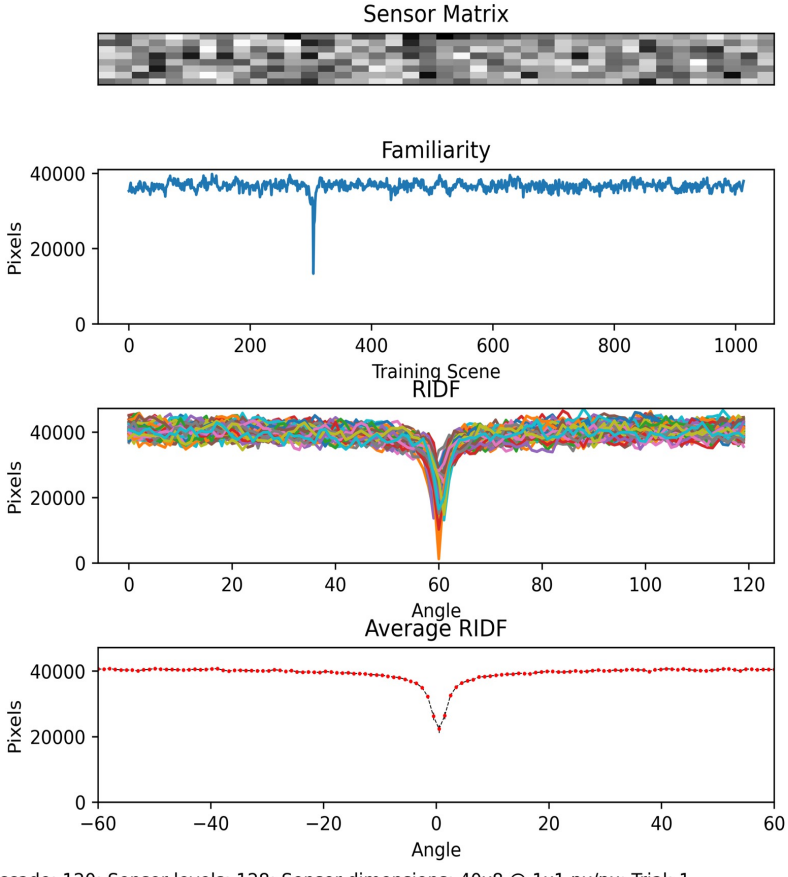




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 53.98; RMSD/dist: 0.135; TD: 12775; p90: 8; p50: 4; complete: 0

100%

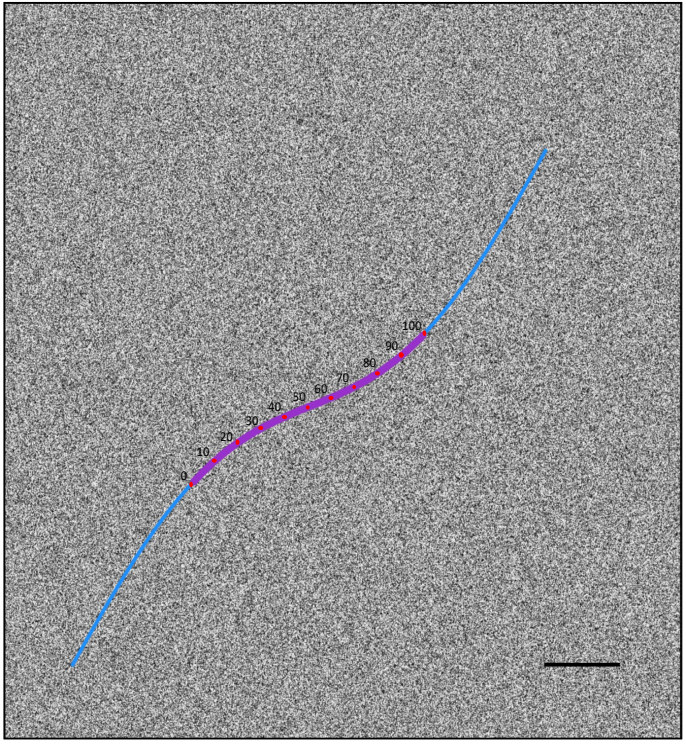


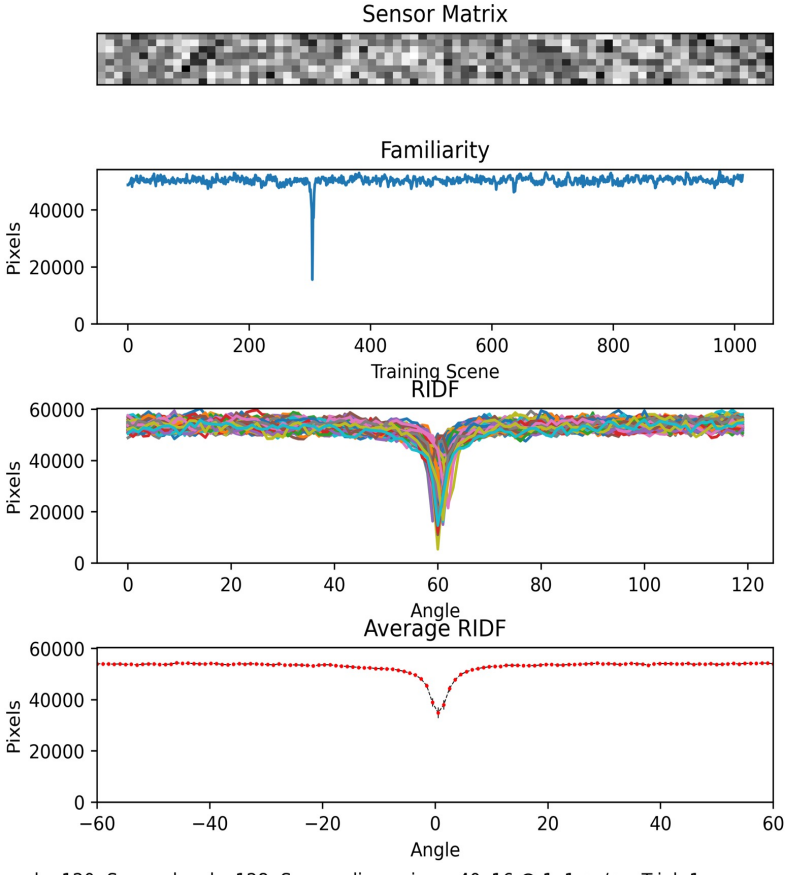




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 54.16; RMSD/dist: 0.135; TD: 14141; p90: 6; p50: 4; complete: 0

100%

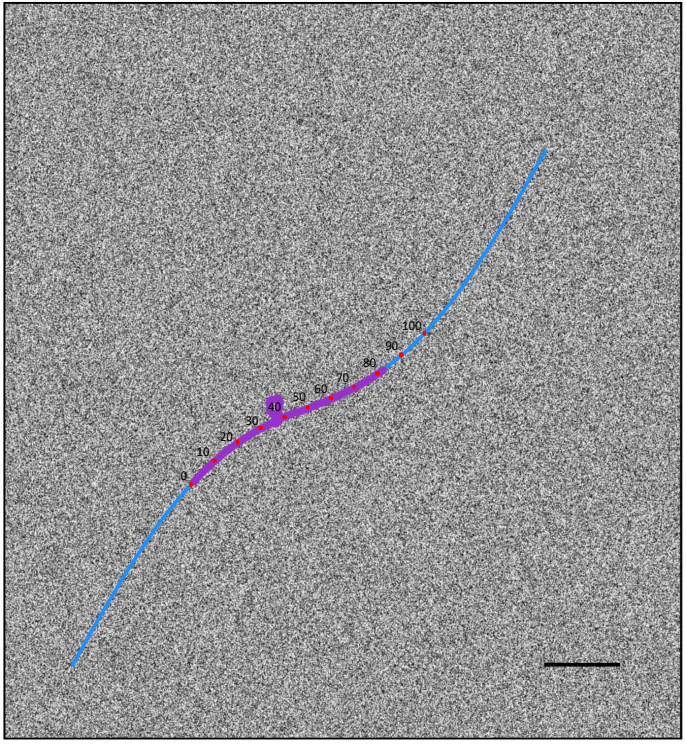


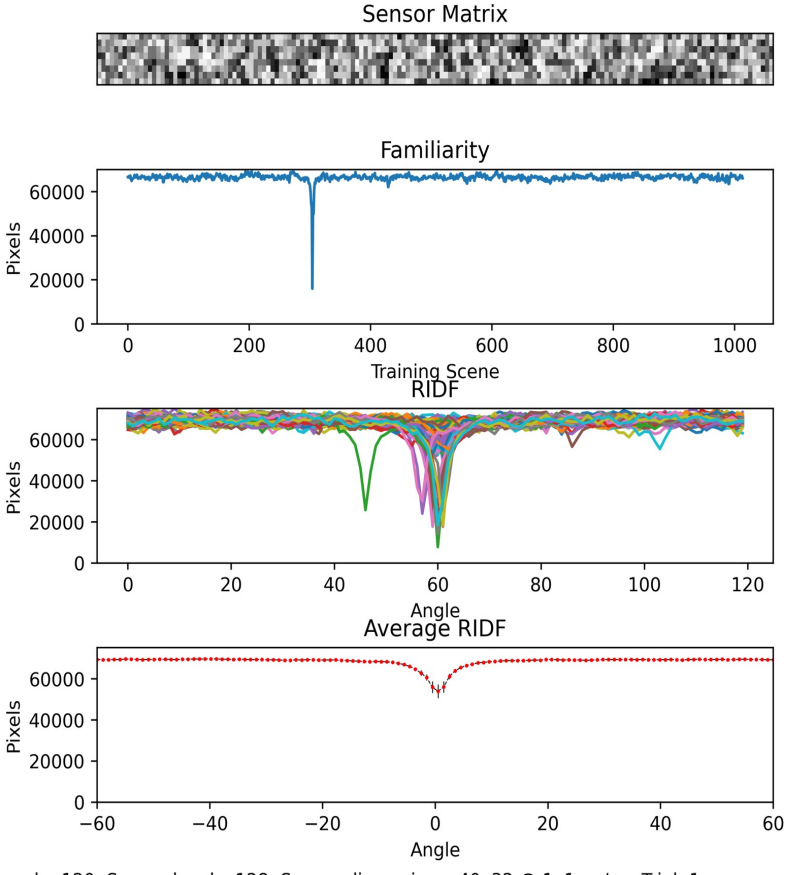




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 65.35; RMSD/dist: 0.163; TD: 15381; p90: 6; p50: 4; complete: 0

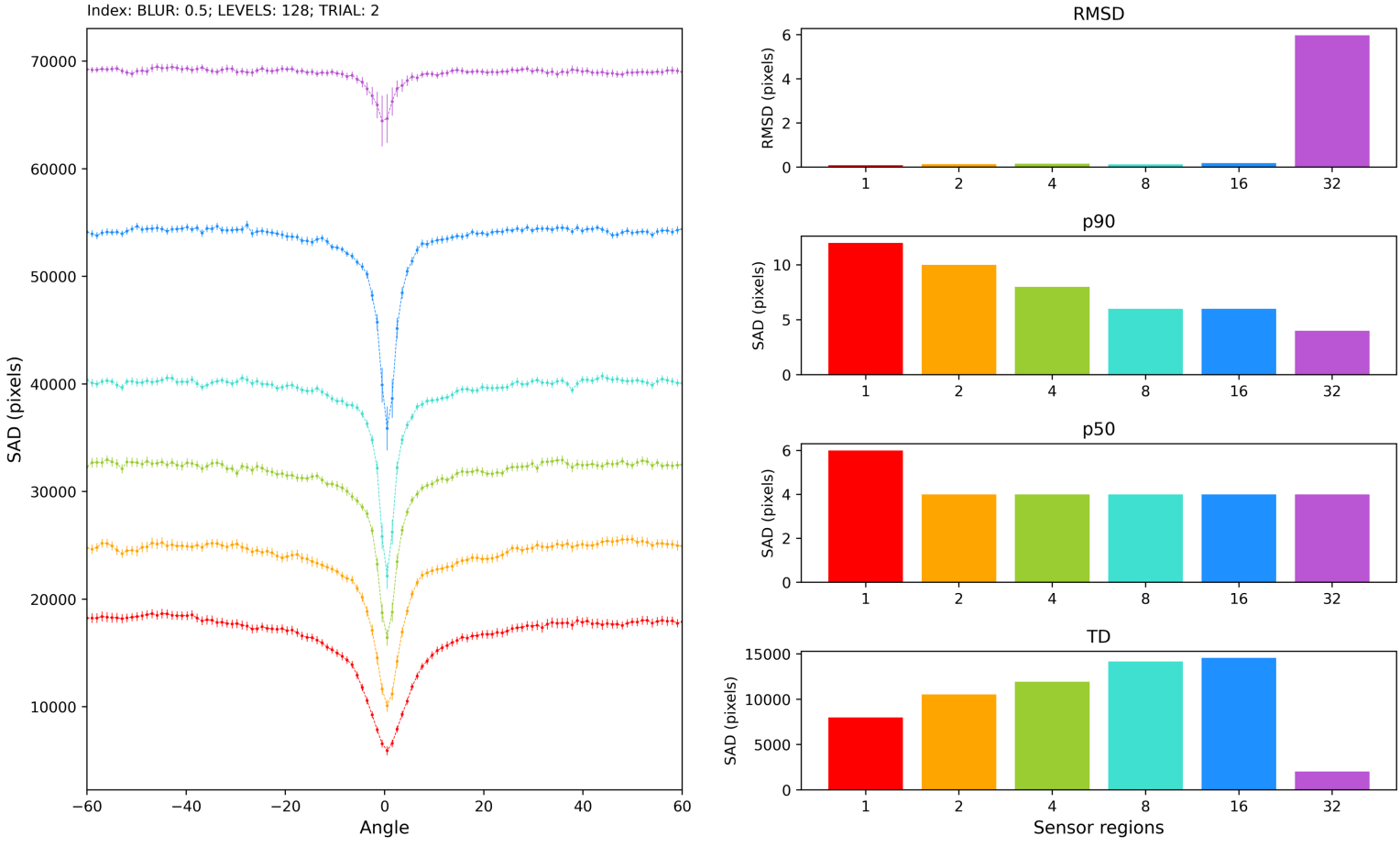
80%



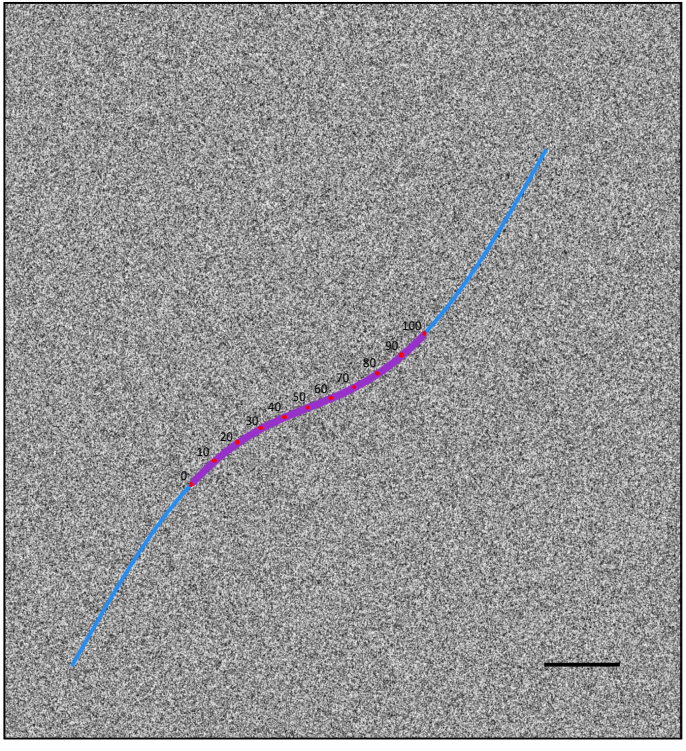



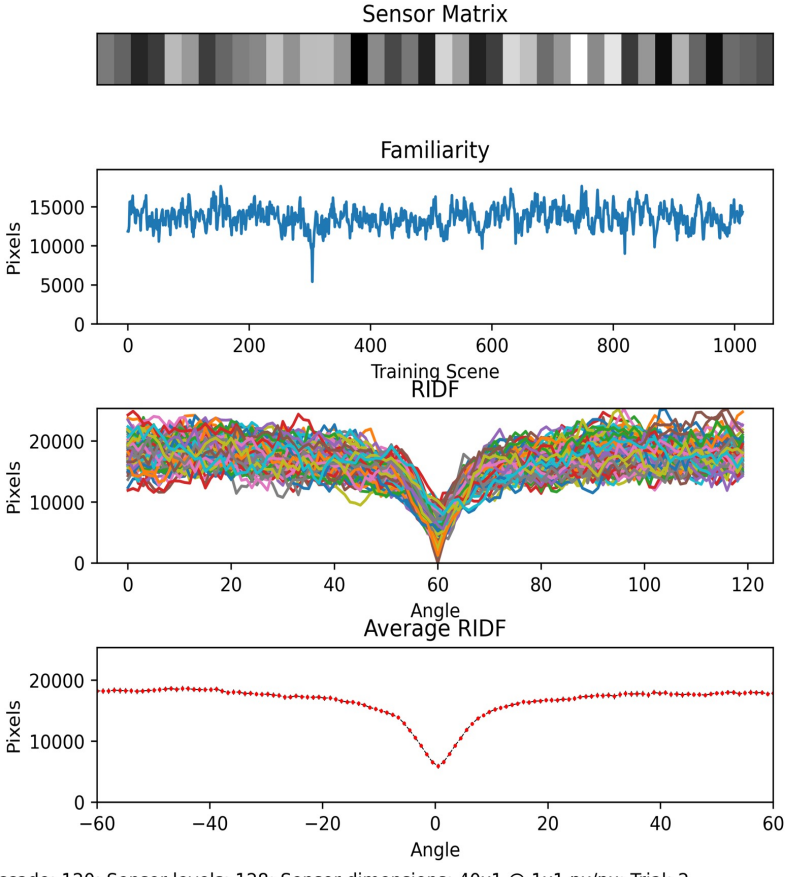

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 389.91; RMSD/dist: 0.975; TD: 12322; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 128; TRIAL: 2
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
6
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
6
4
2
0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

100%

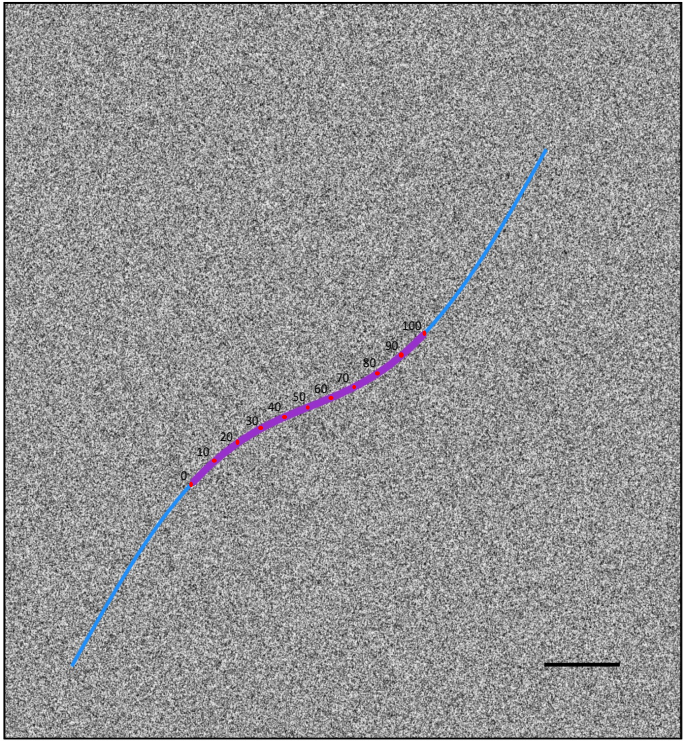


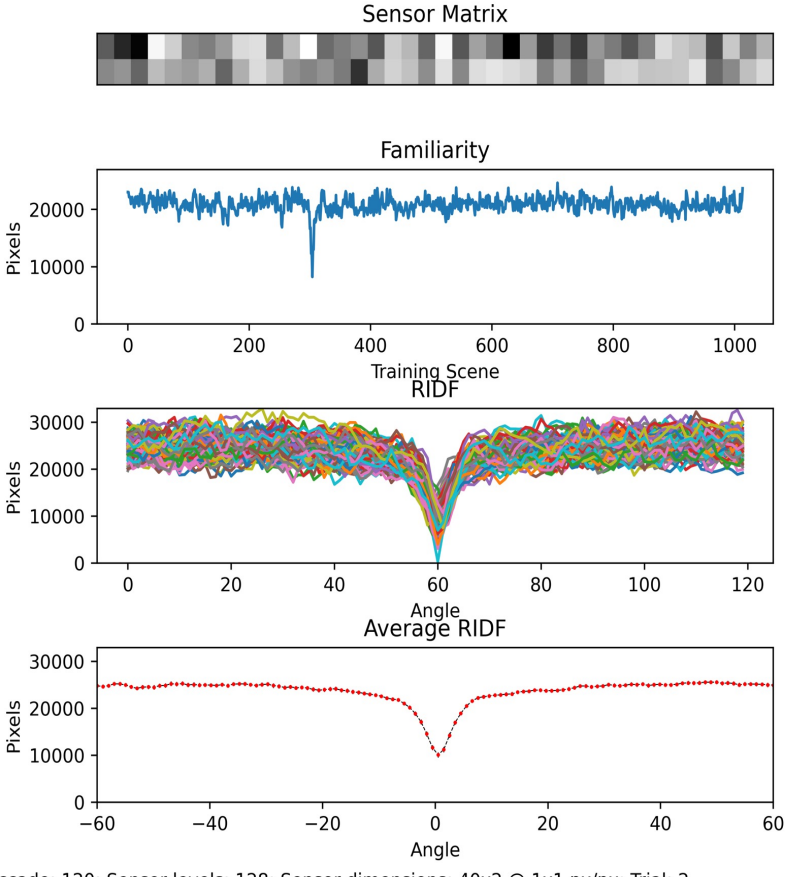




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 33.20; RMSD/dist: 0.083; TD: 7988; p90: 12; p50: 6; complete: 0

100%

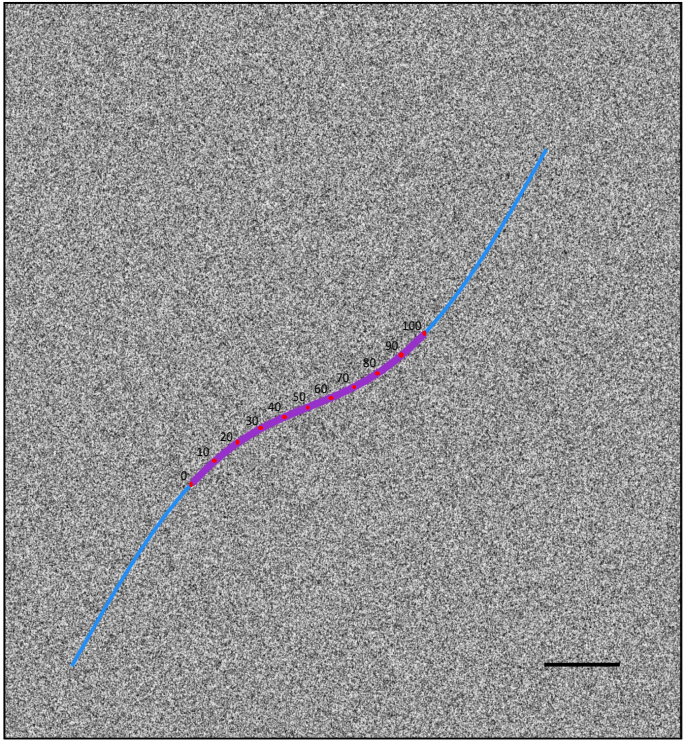


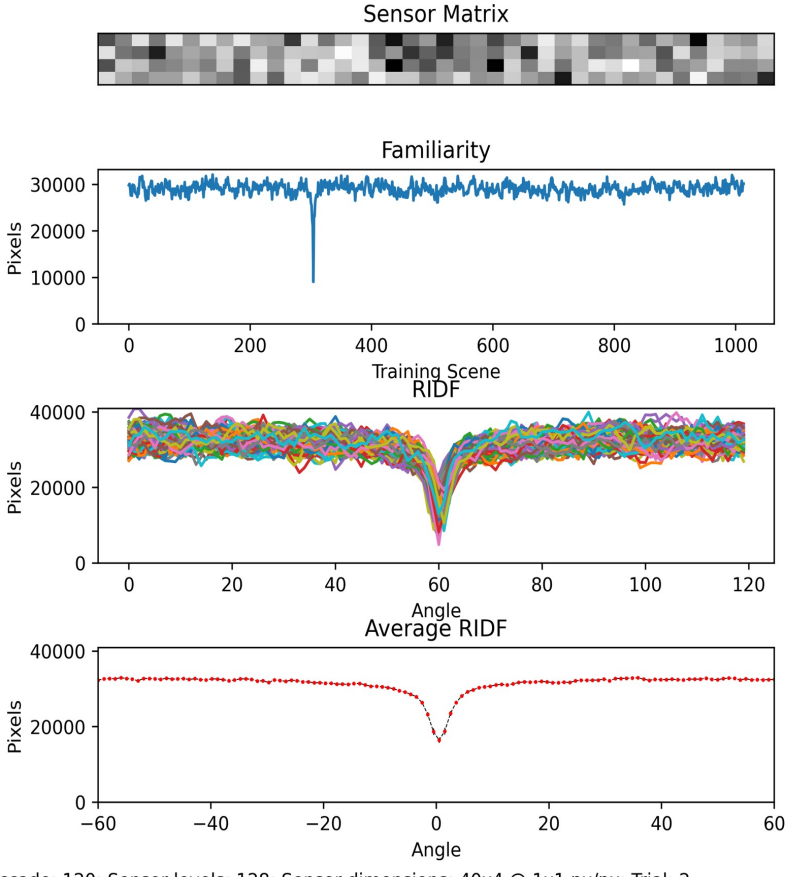




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 51.77; RMSD/dist: 0.129; TD: 10531; p90: 10; p50: 4; complete: 0

100%

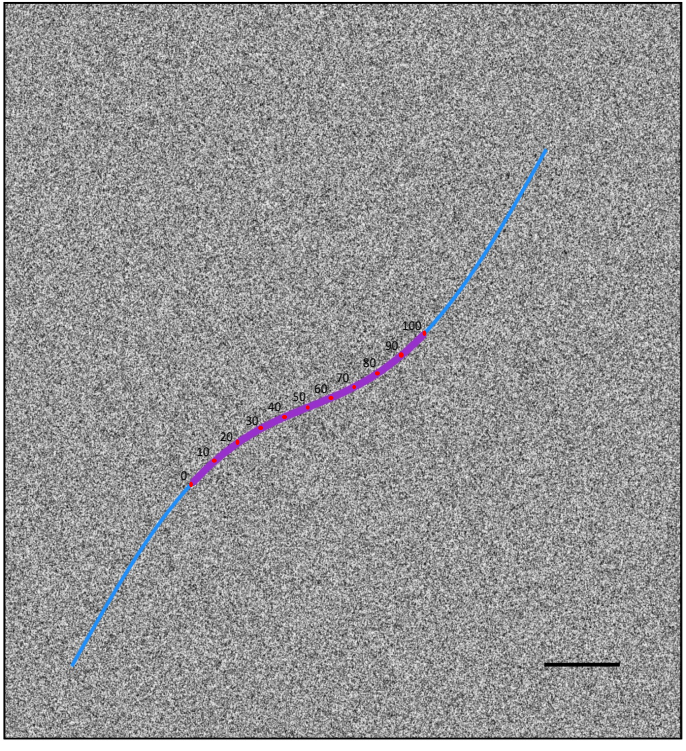


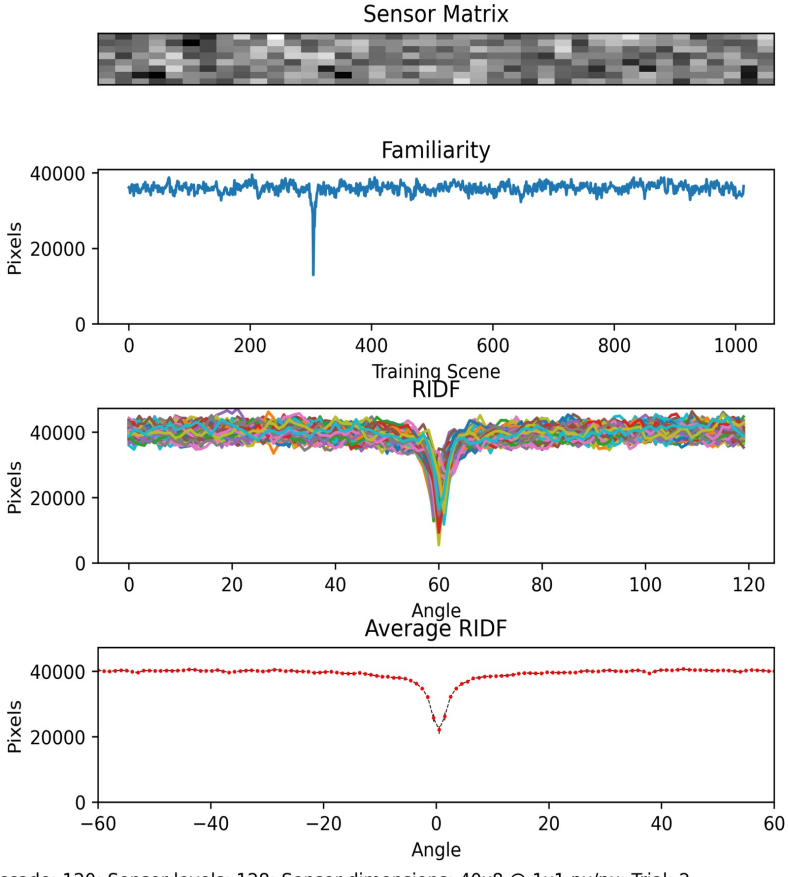




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 58.34; RMSD/dist: 0.146; TD: 11925; p90: 8; p50: 4; complete: 0

100%

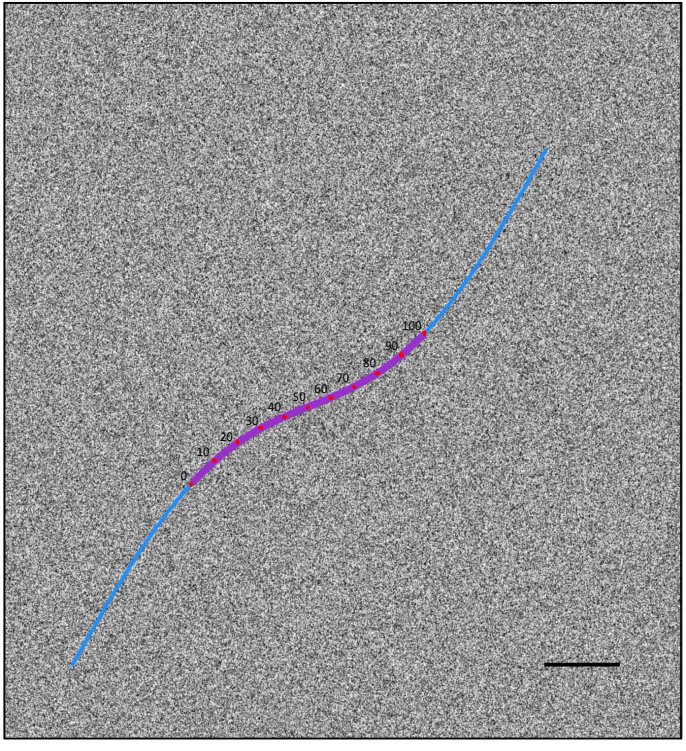


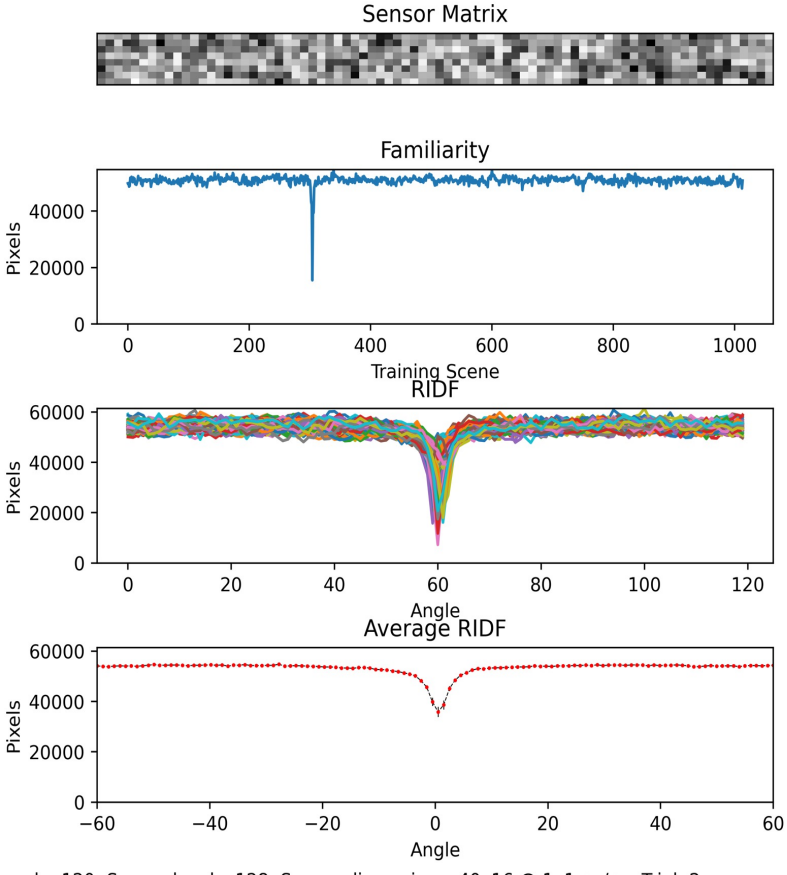




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 50.41; RMSD/dist: 0.126; TD: 14176; p90: 6; p50: 4; complete: 0

100%

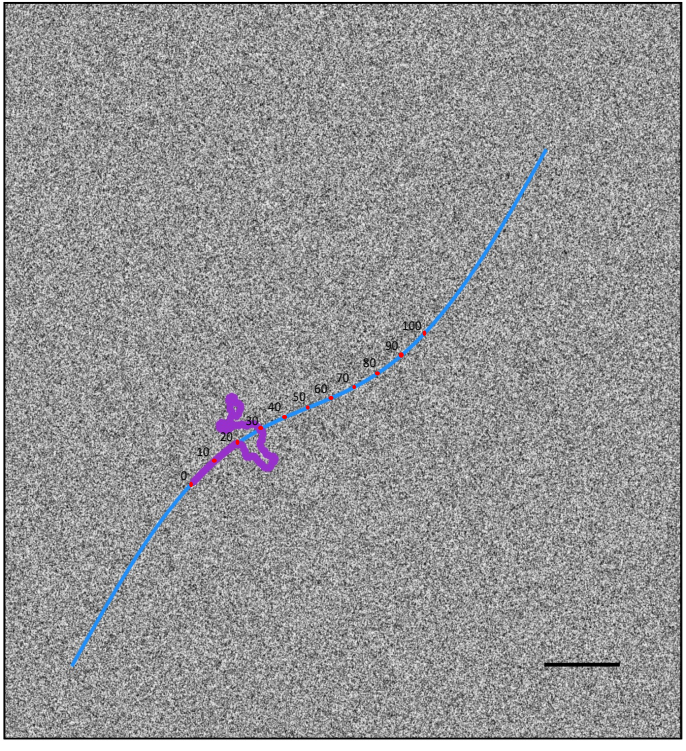


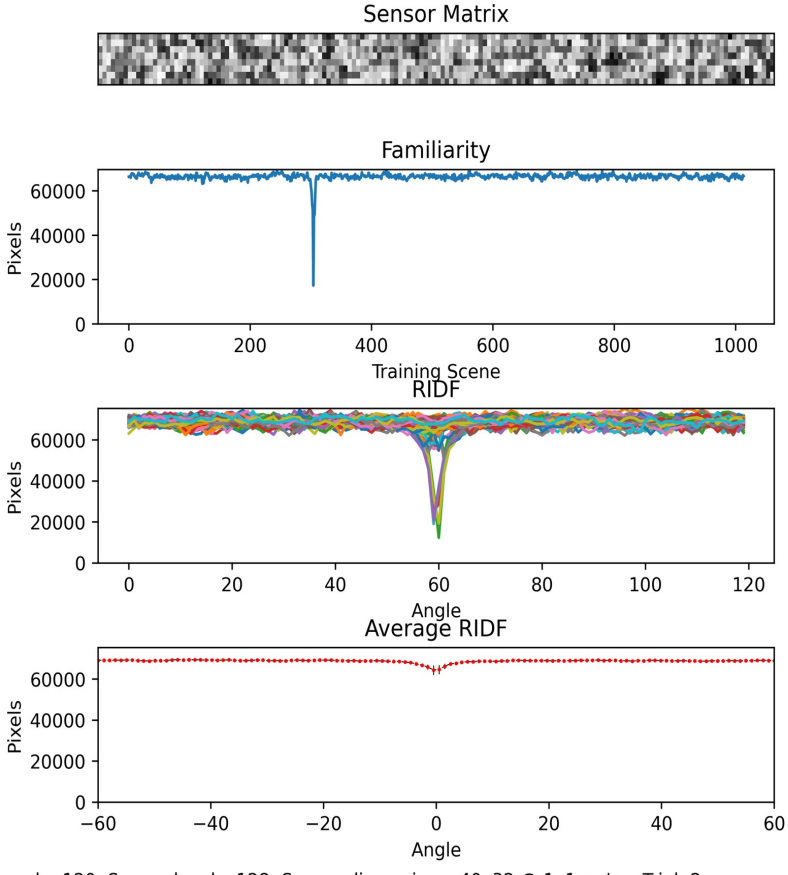




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 72.17; RMSD/dist: 0.180; TD: 14556; p90: 6; p50: 4; complete: 0

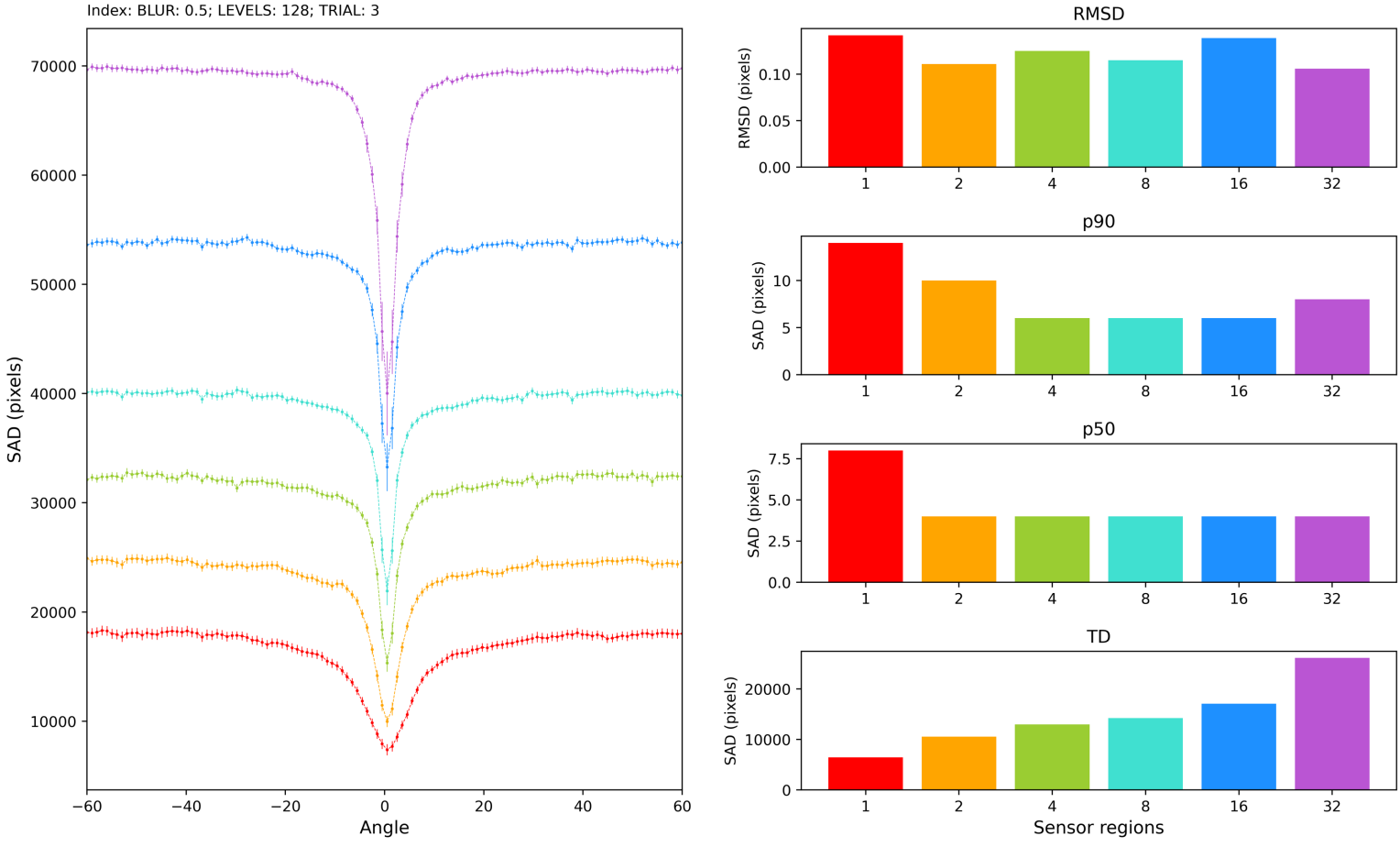
20%



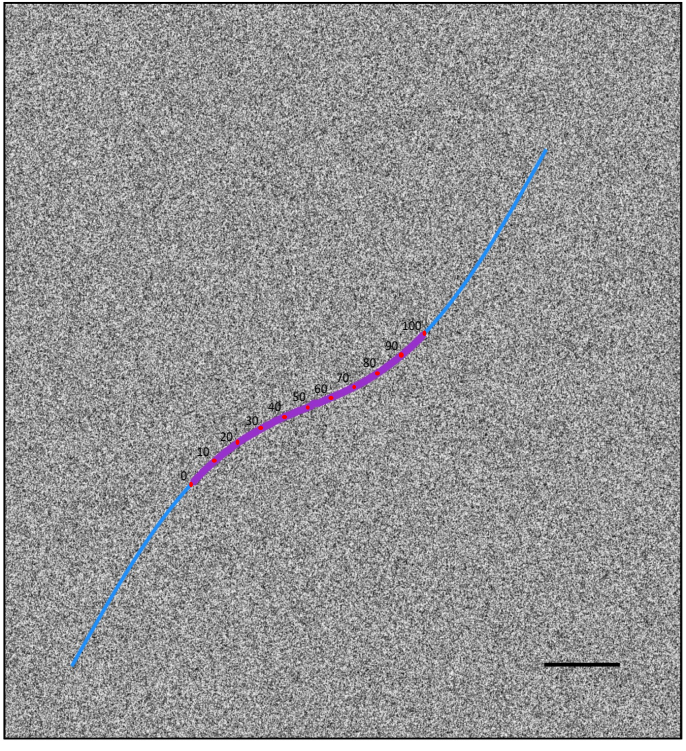



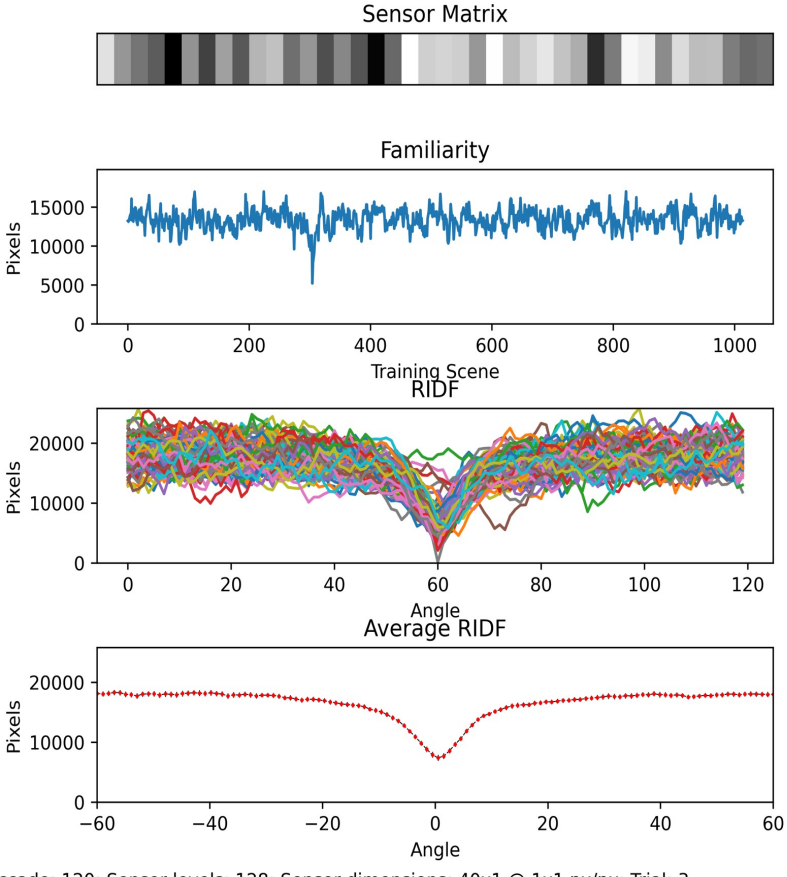

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2390.50; RMSD/dist: 5.976; TD: 2020; p90: 4; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 128; TRIAL: 3
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.00
0.05
0.10
1
2
4
8
16
32
p90
SAD (pixels)
0
5
10
p50
SAD (pixels)
0.0
2.5
5.0
7.5
TD
SAD (pixels)
0
10000
20000
Sensor regions

100%

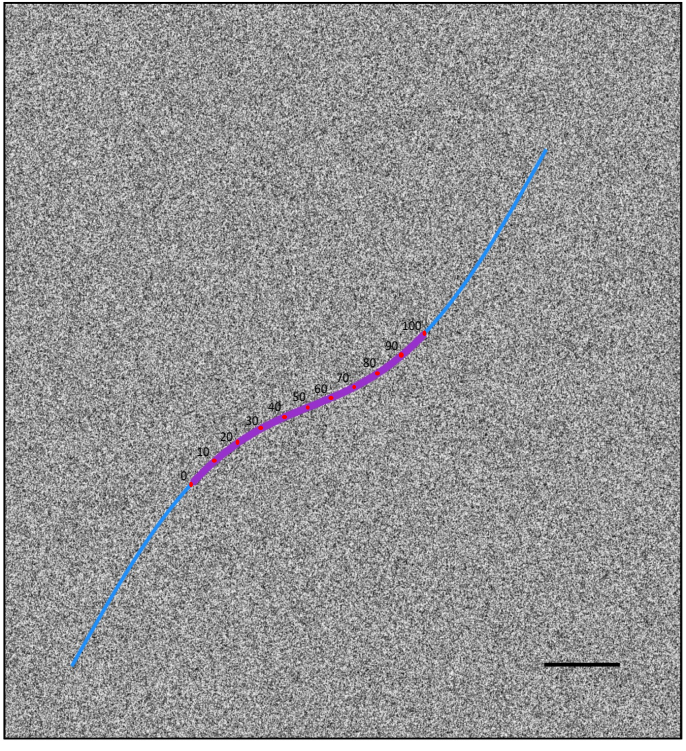


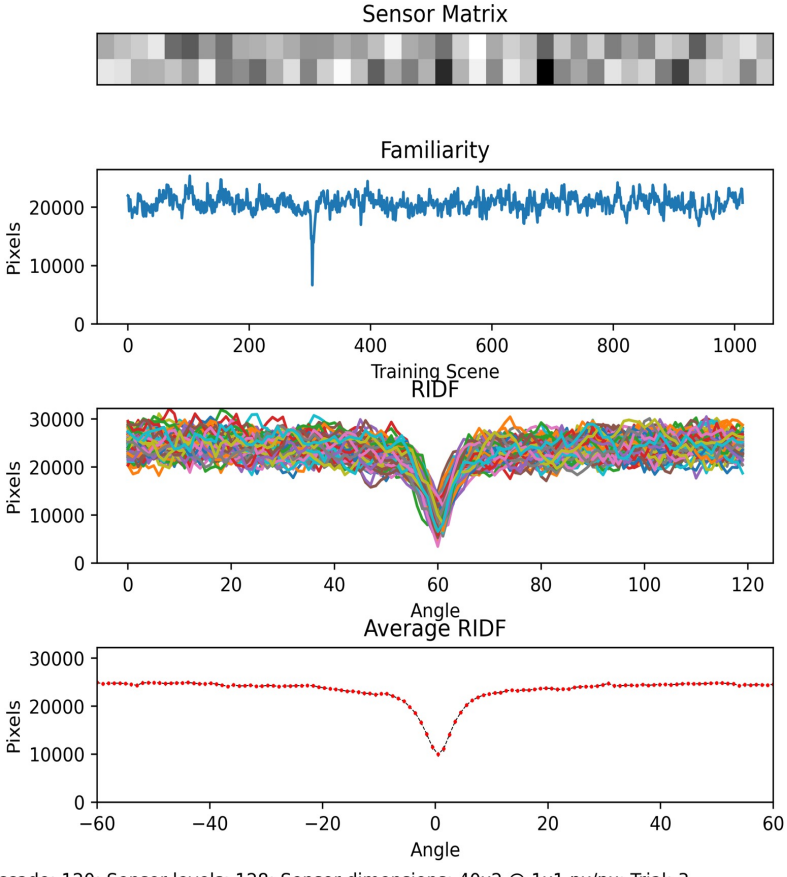




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 56.97; RMSD/dist: 0.142; TD: 6442; p90: 14; p50: 8; complete: 0

100%

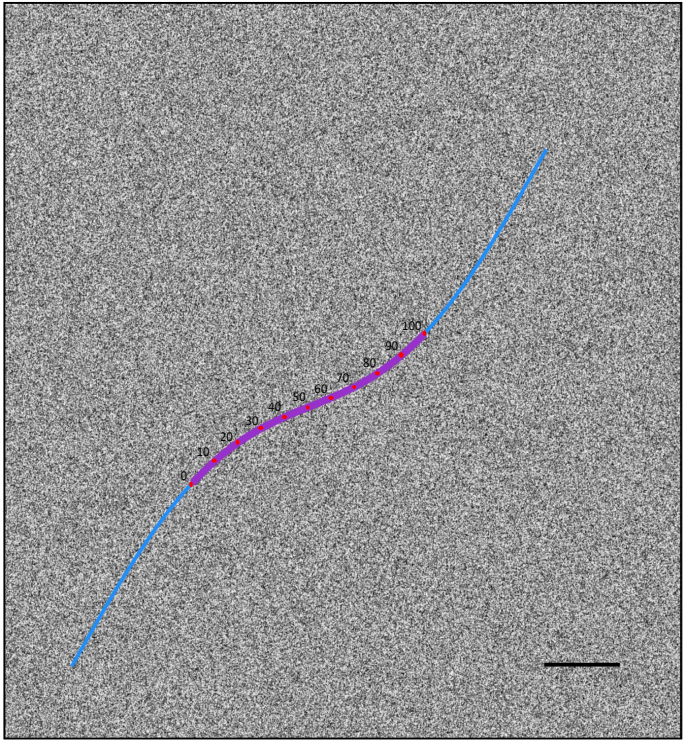


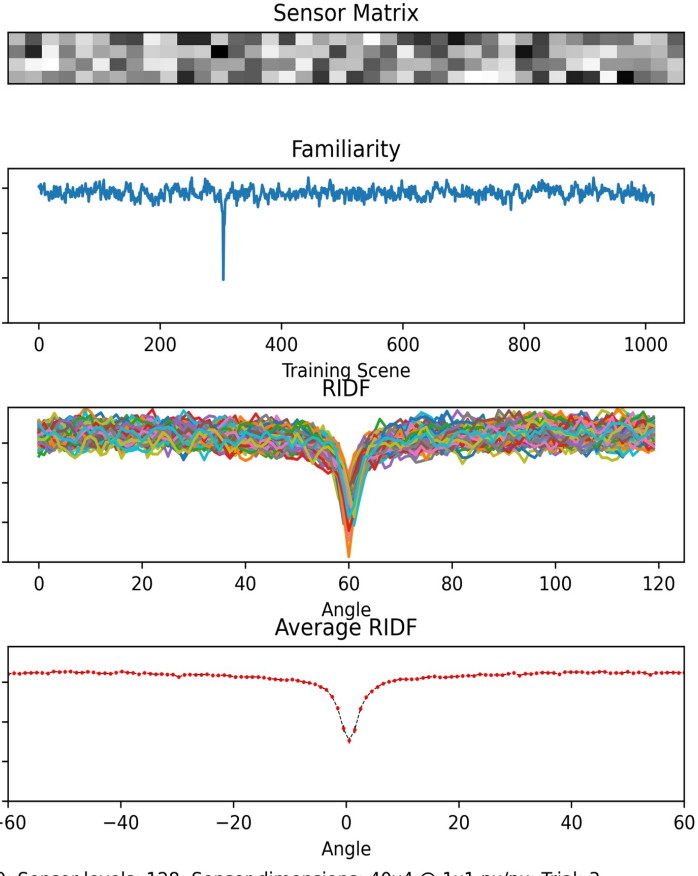




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 44.58; RMSD/dist: 0.111; TD: 10550; p90: 10; p50: 4; complete: 0

100%

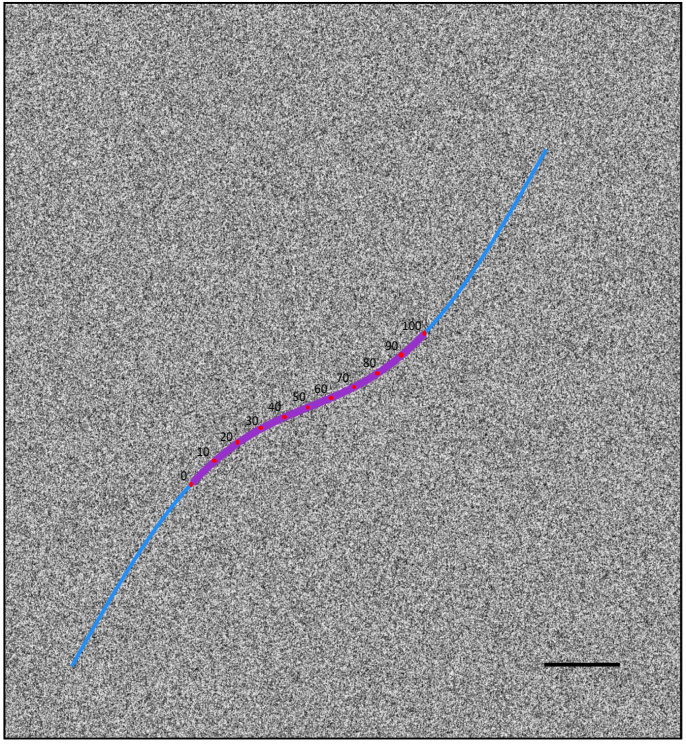


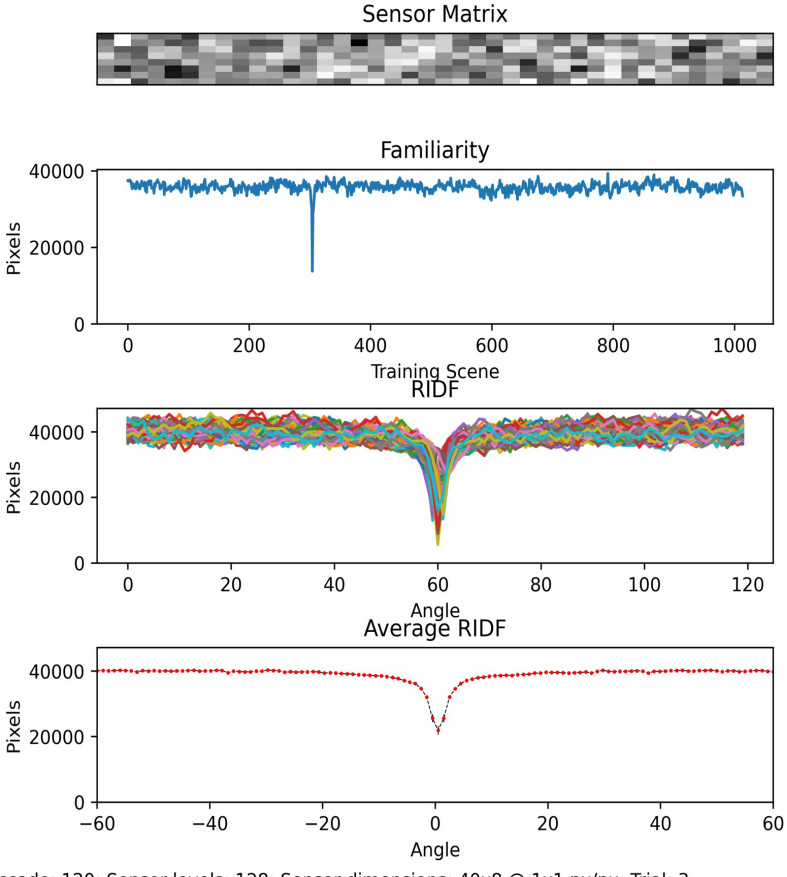




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 49.98; RMSD/dist: 0.125; TD: 12974; p90: 6; p50: 4; complete: 0

100%

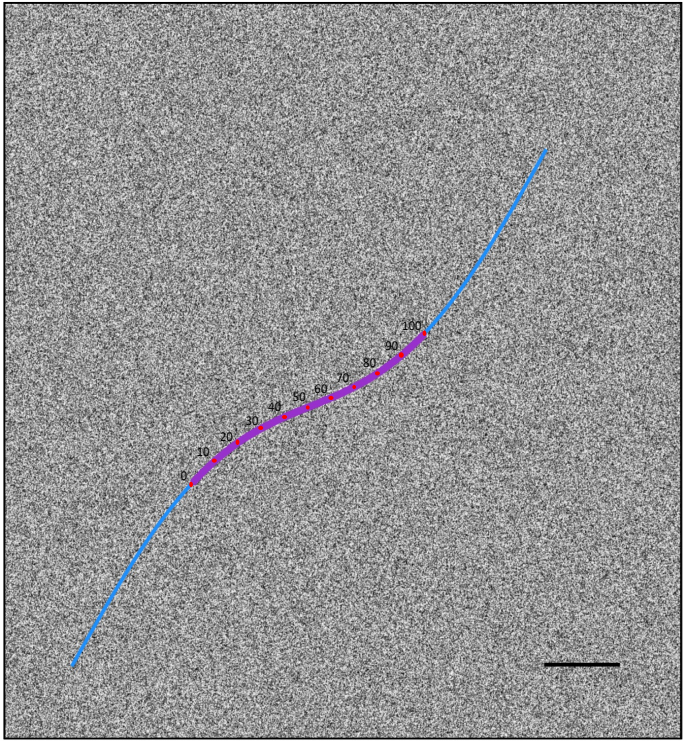


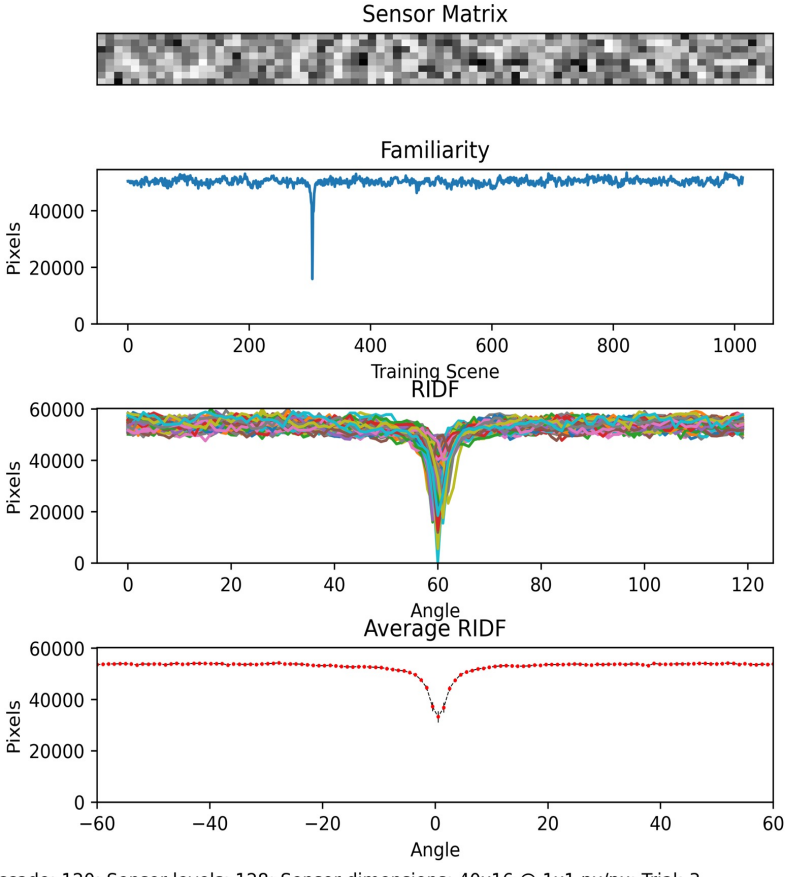




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 45.83; RMSD/dist: 0.115; TD: 14226; p90: 6; p50: 4; complete: 0

100%

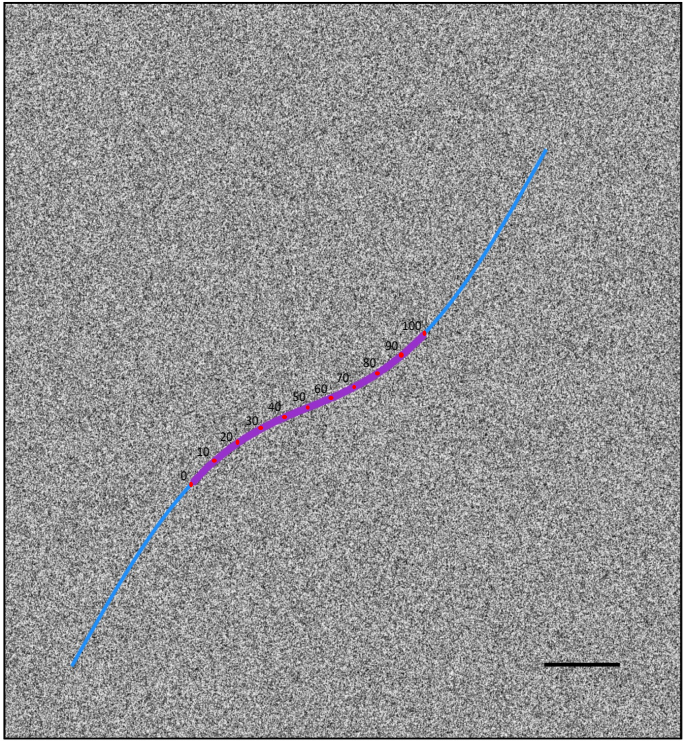


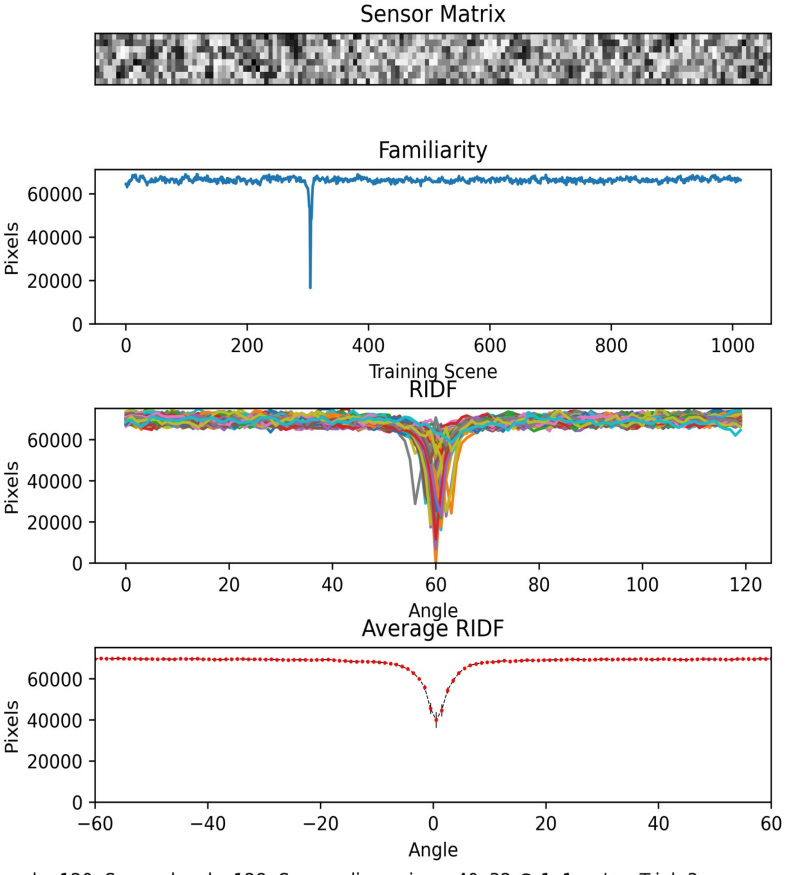




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 55.41; RMSD/dist: 0.139; TD: 17063; p90: 6; p50: 4; complete: 0

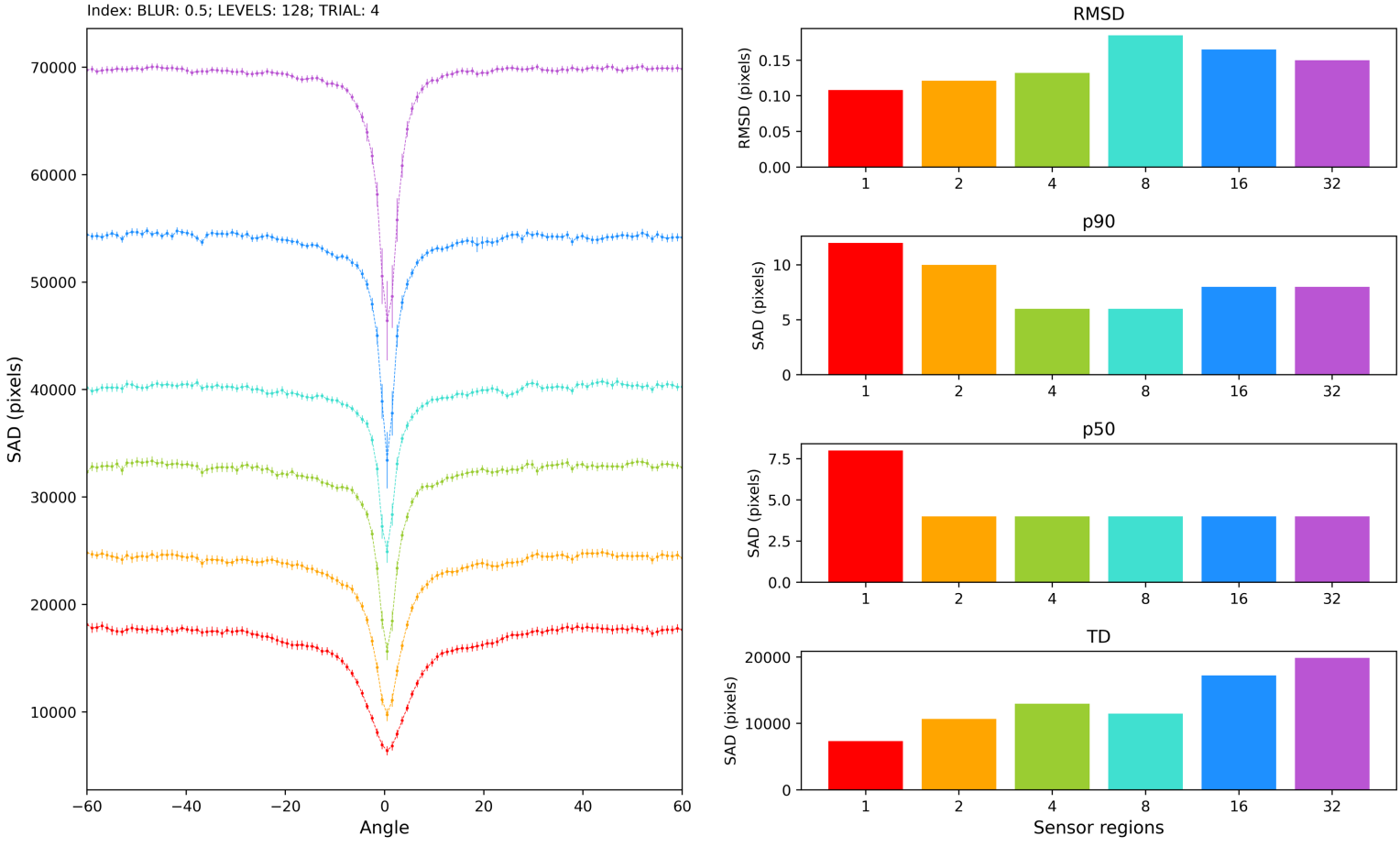
100%



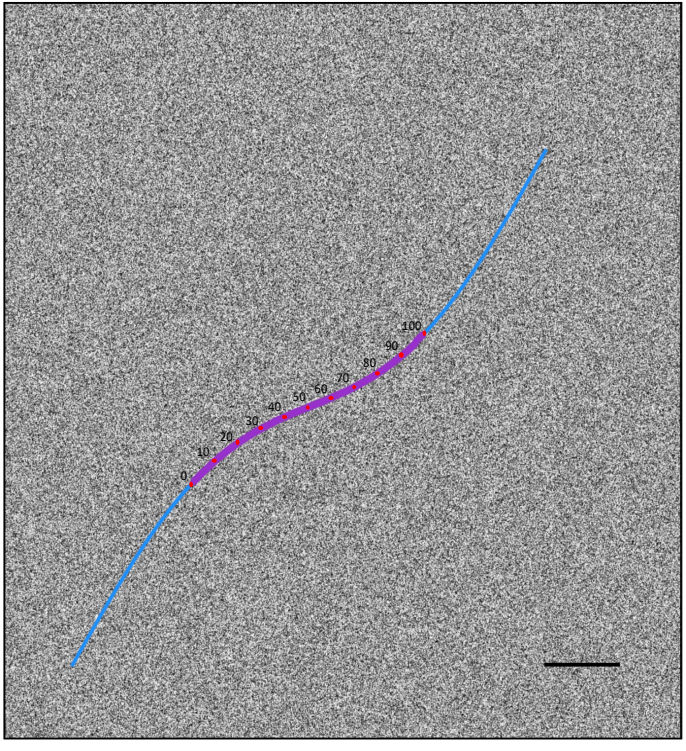



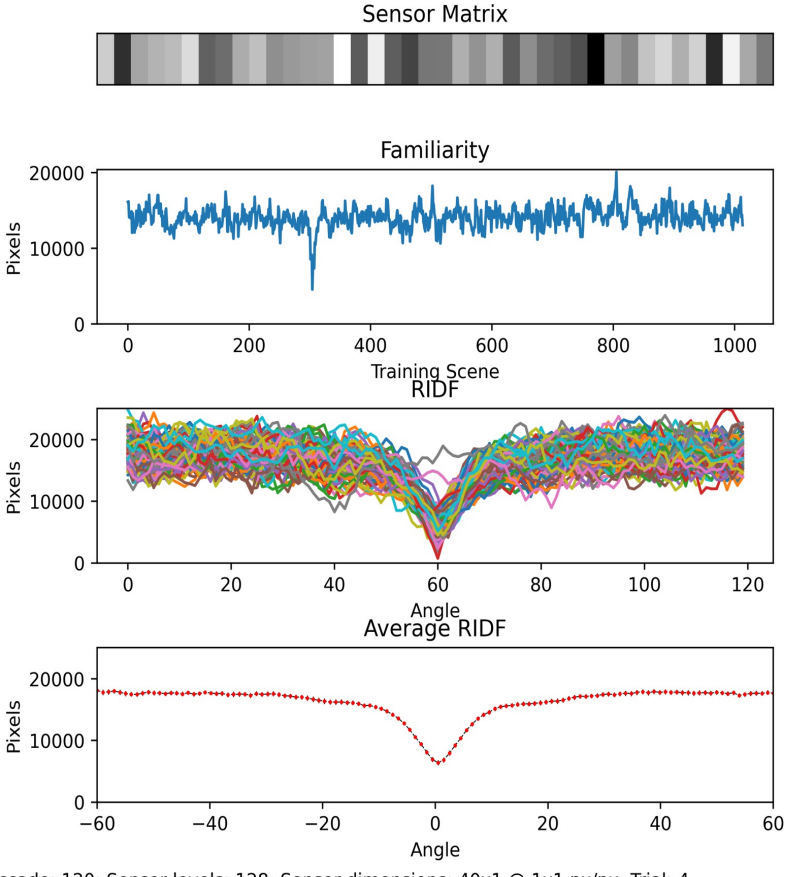

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 42.50; RMSD/dist: 0.106; TD: 26147; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 128; TRIAL: 4
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.15
0.10
0.05
0.00
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

100%

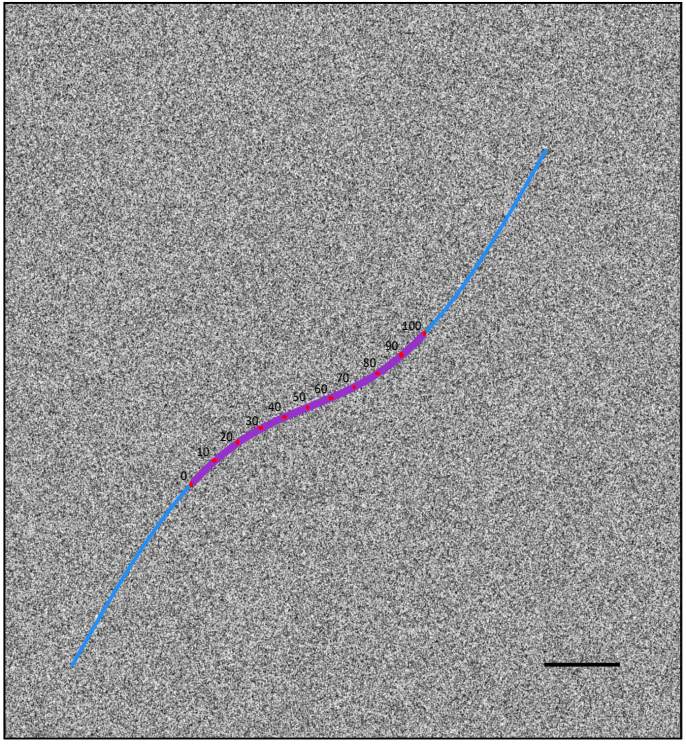


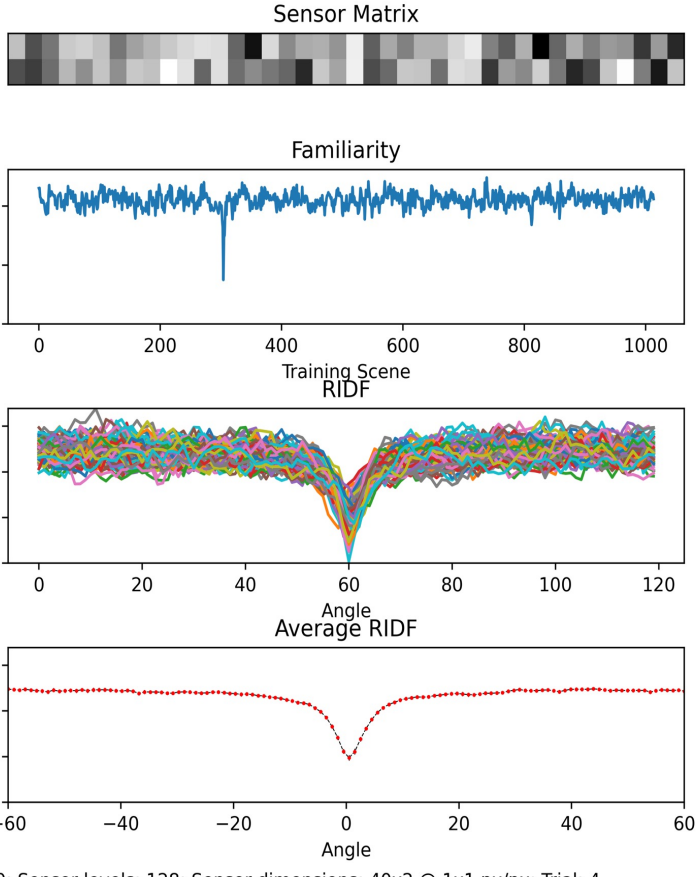




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 43.21; RMSD/dist: 0.108; TD: 7349; p90: 12; p50: 8; complete: 0

100%

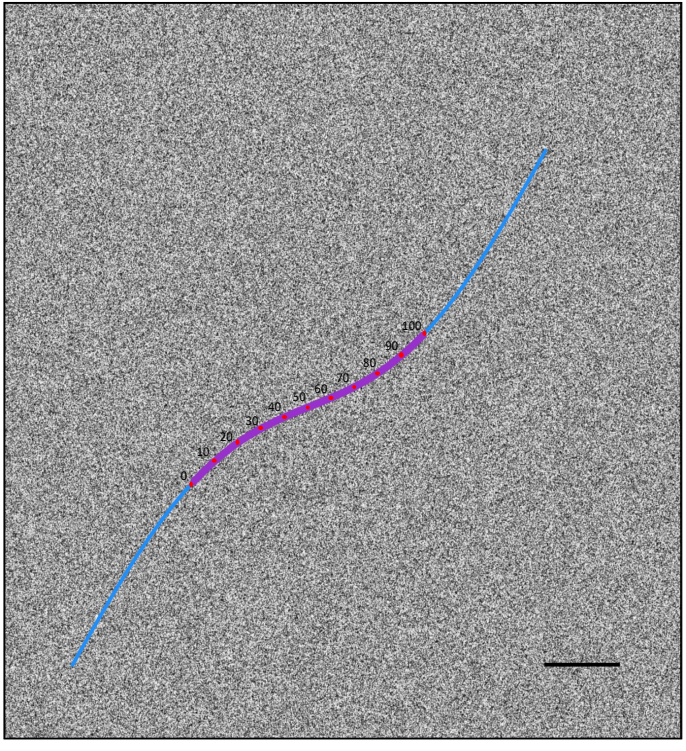


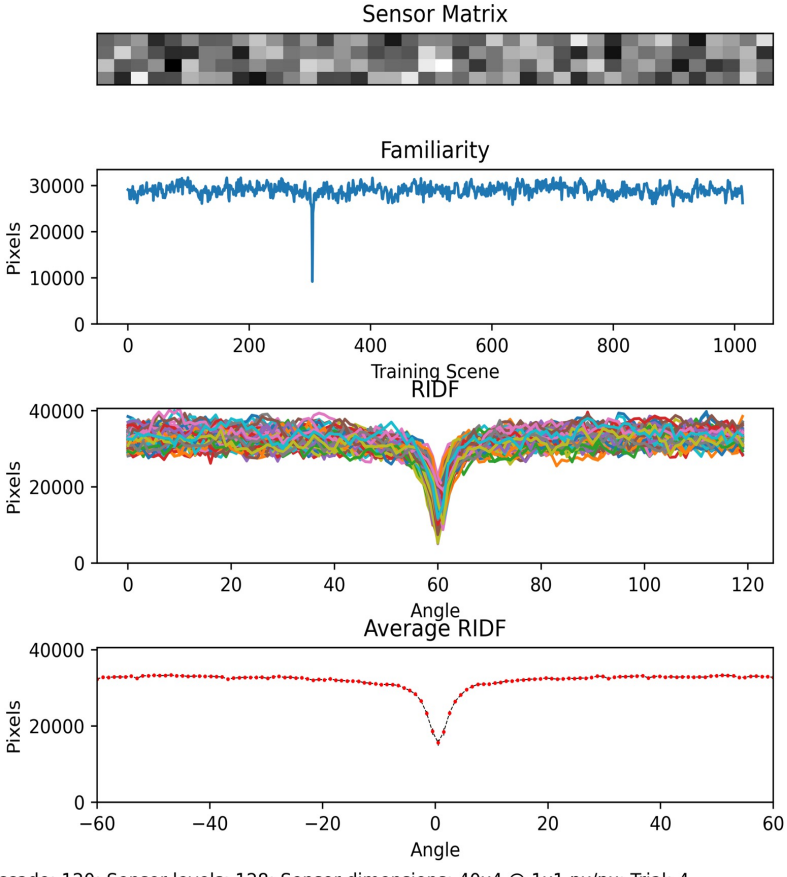




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 48.37; RMSD/dist: 0.121; TD: 10678; p90: 10; p50: 4; complete: 0

100%

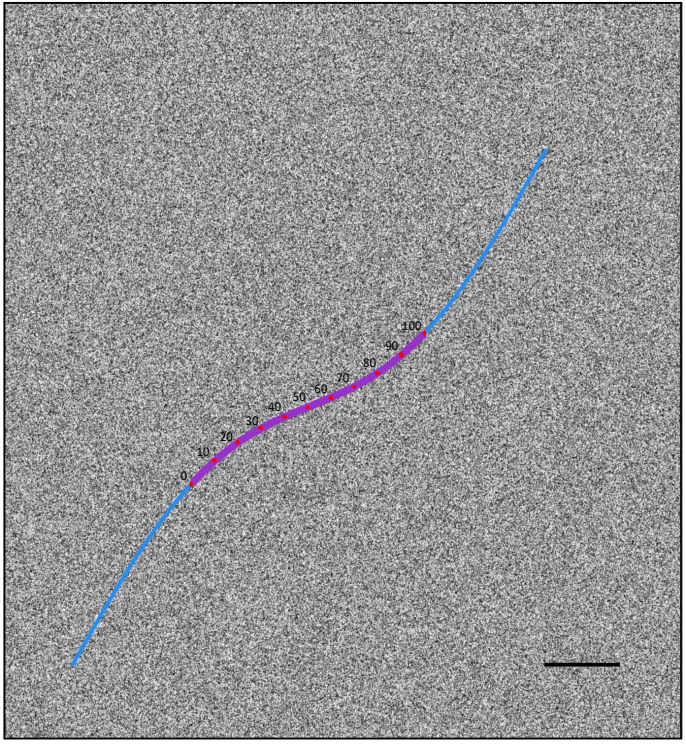


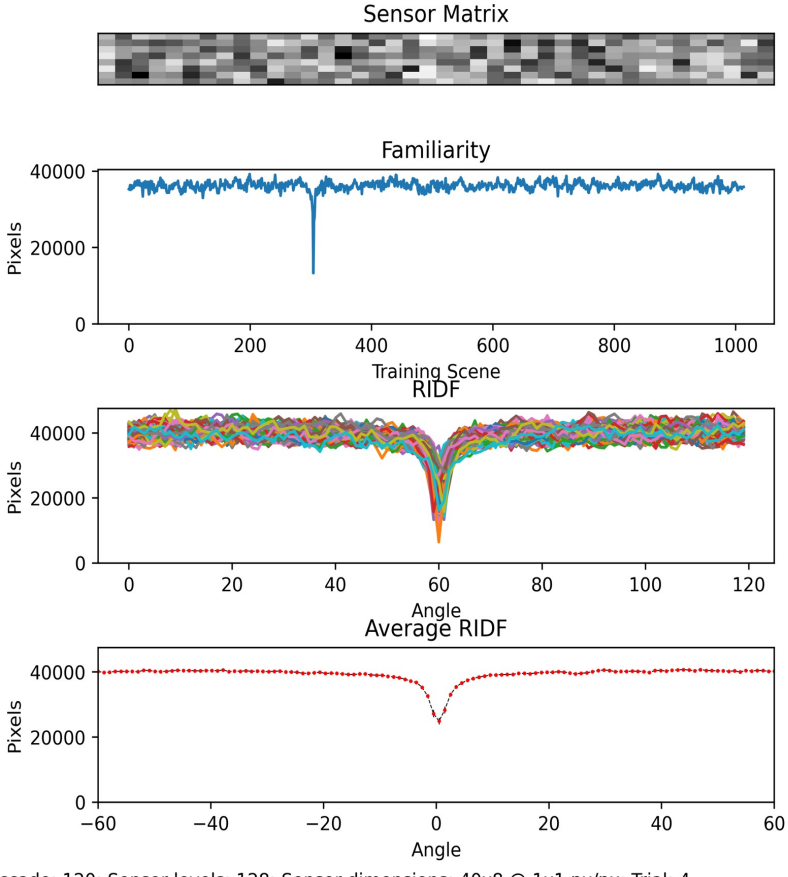




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 52.79; RMSD/dist: 0.132; TD: 12960; p90: 6; p50: 4; complete: 0

100%

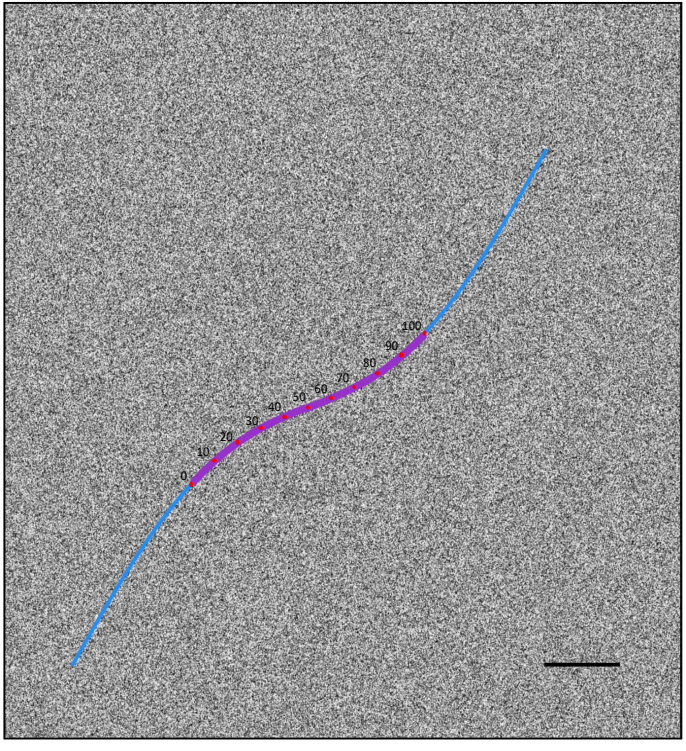


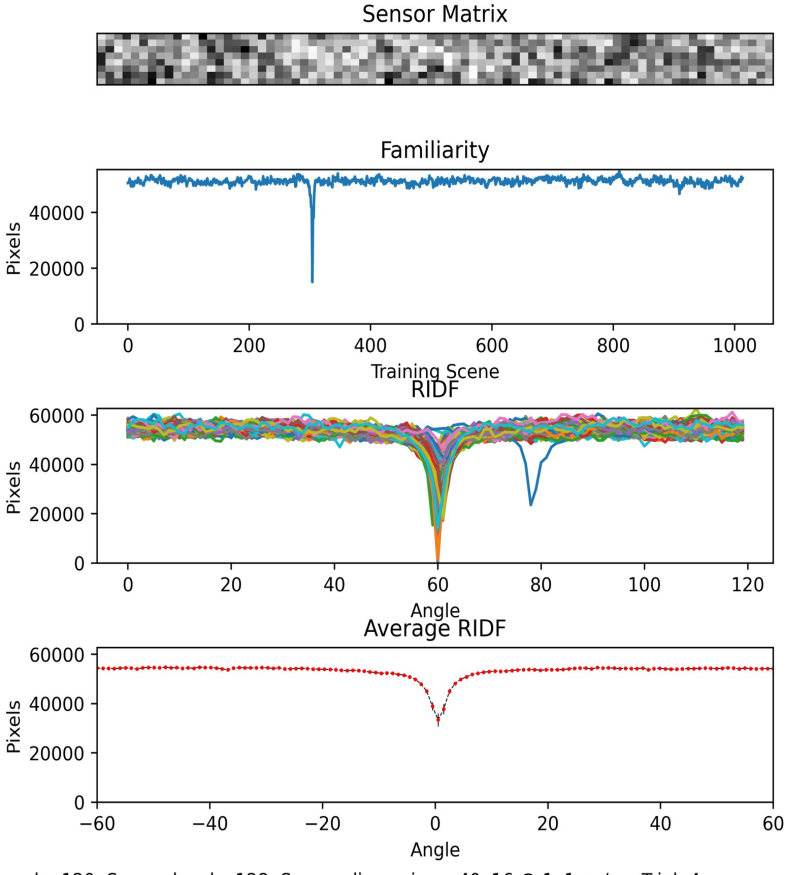




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 73.96; RMSD/dist: 0.185; TD: 11473; p90: 6; p50: 4; complete: 0

100%

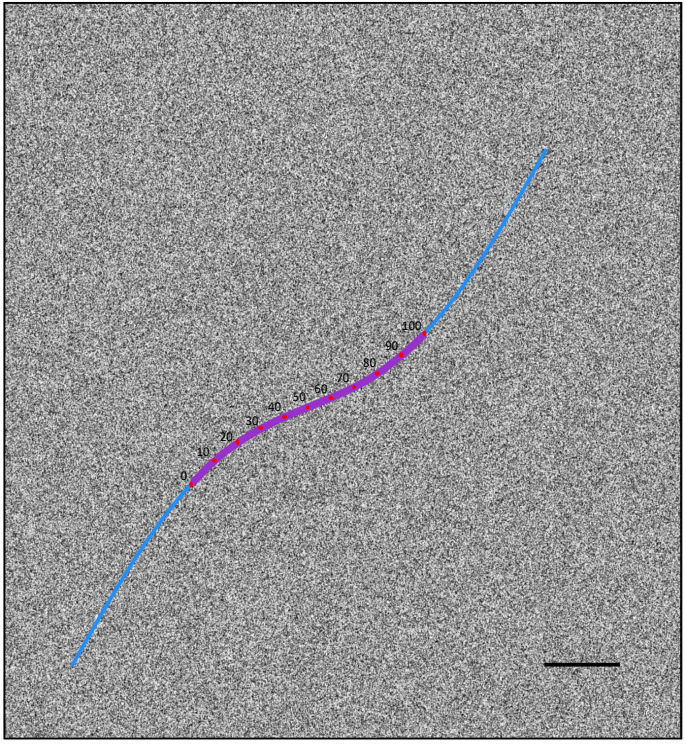


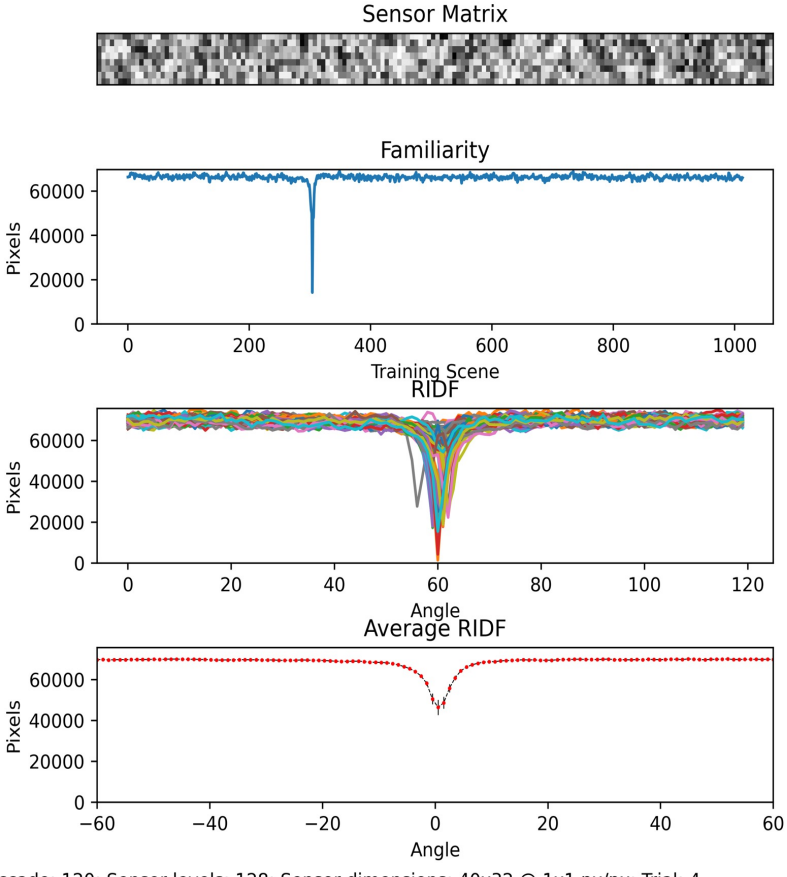




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 66.07; RMSD/dist: 0.165; TD: 17237; p90: 8; p50: 4; complete: 0

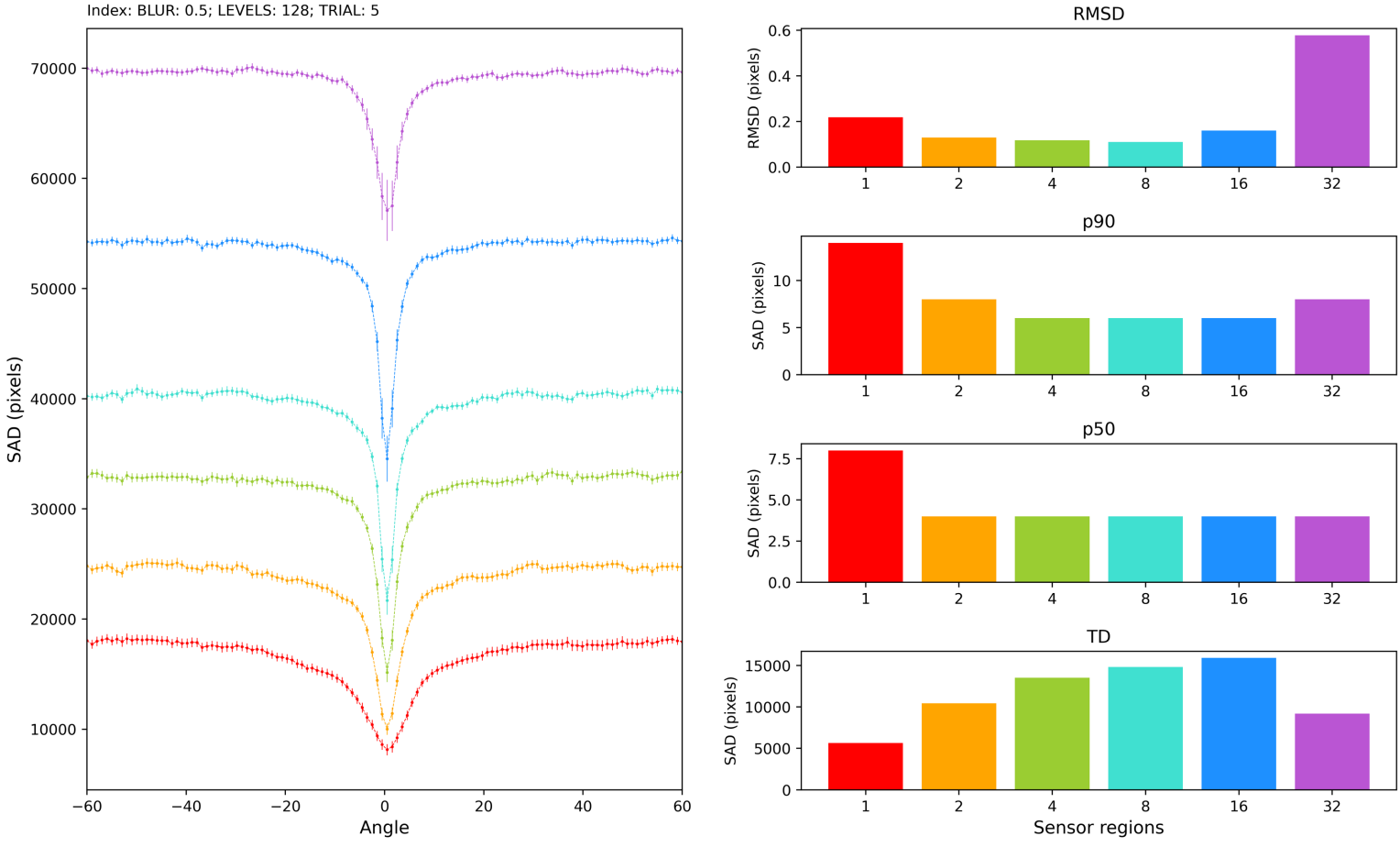
100%



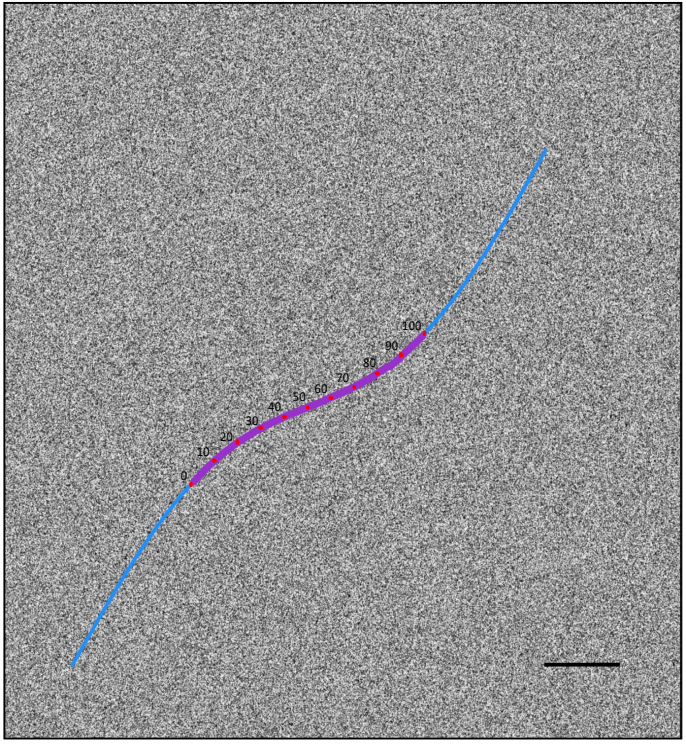



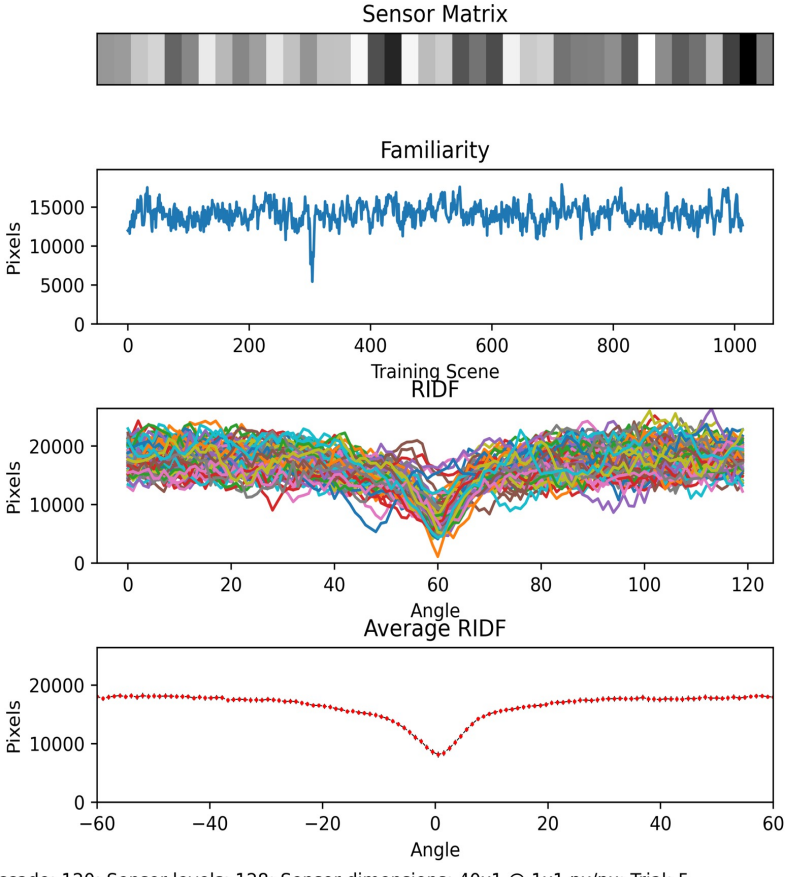

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 60.17; RMSD/dist: 0.150; TD: 19859; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 128; TRIAL: 5
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.6
0.4
0.2
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
15000
10000
5000
0
Sensor regions

100%

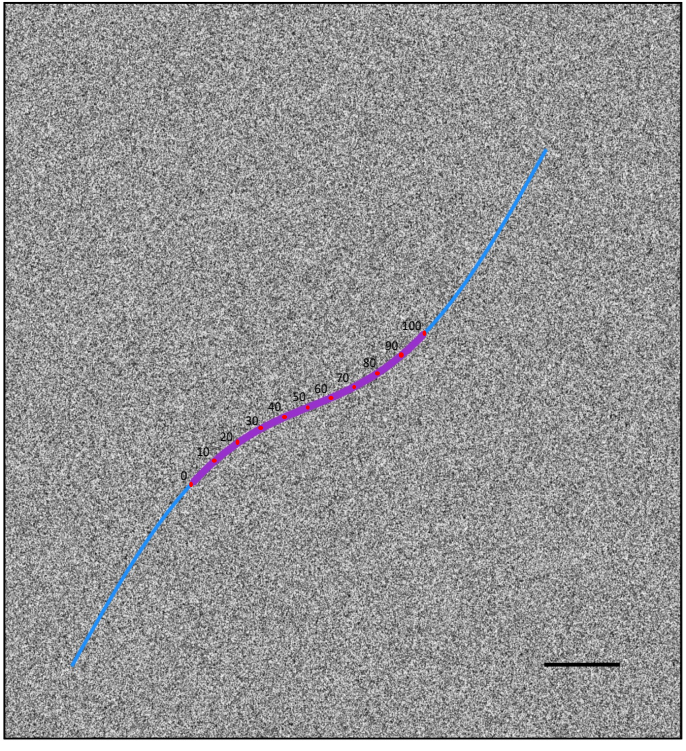


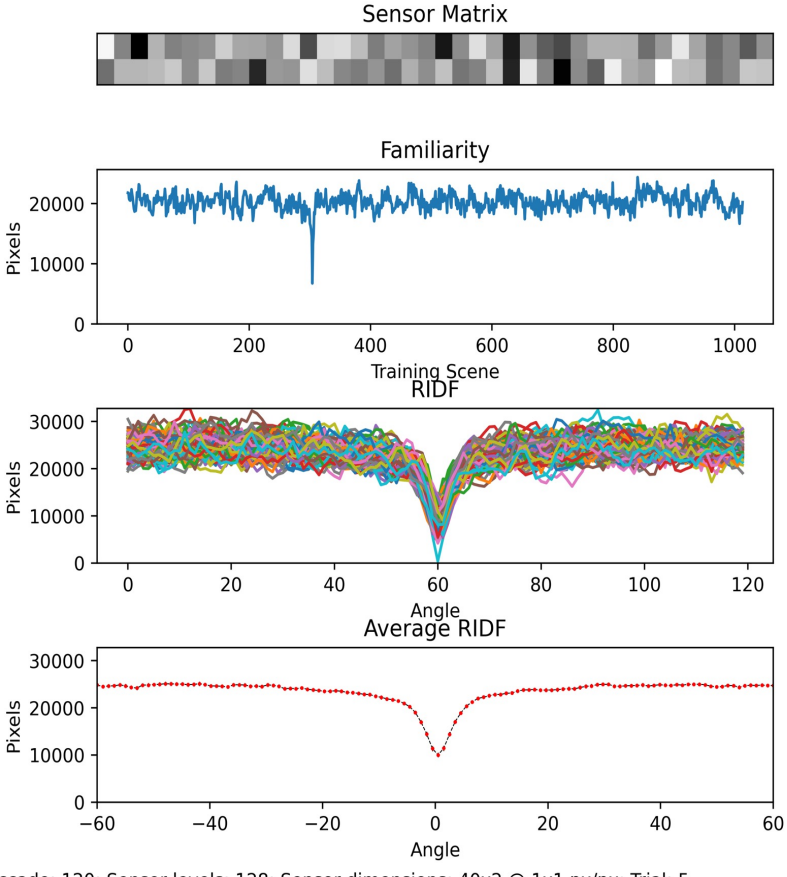




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 87.30; RMSD/dist: 0.218; TD: 5652; p90: 14; p50: 8; complete: 0

100%

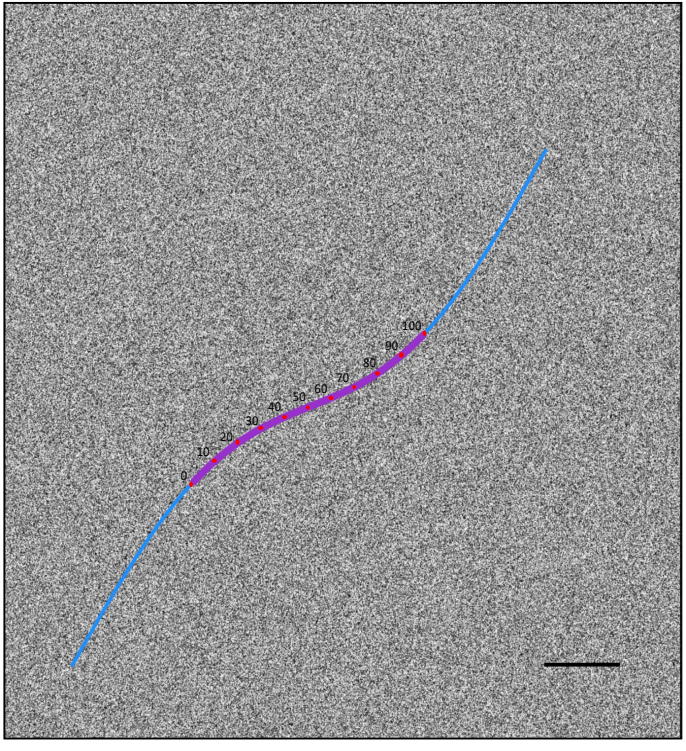


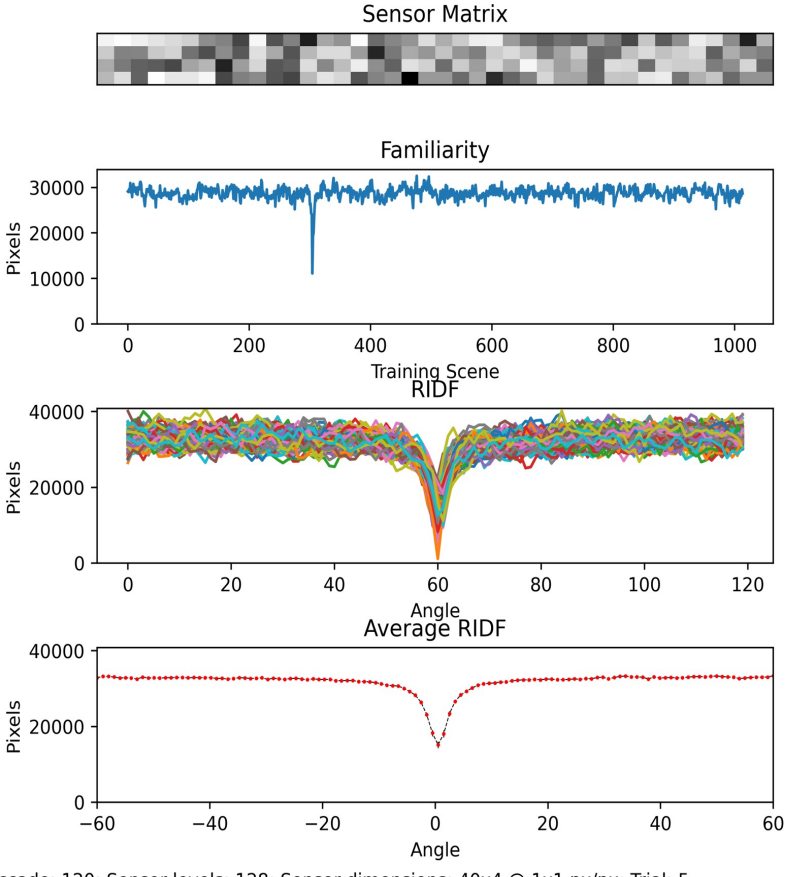




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 51.79; RMSD/dist: 0.129; TD: 10423; p90: 8; p50: 4; complete: 0

100%

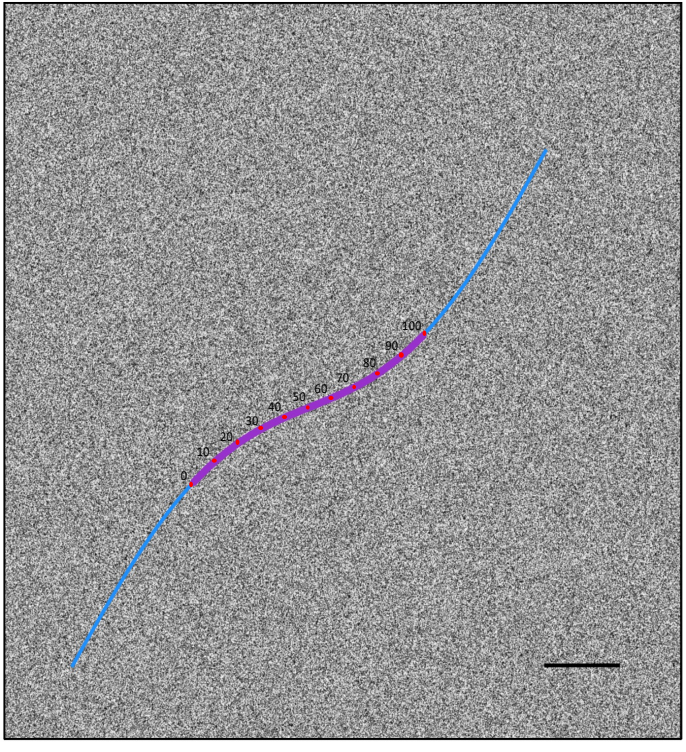


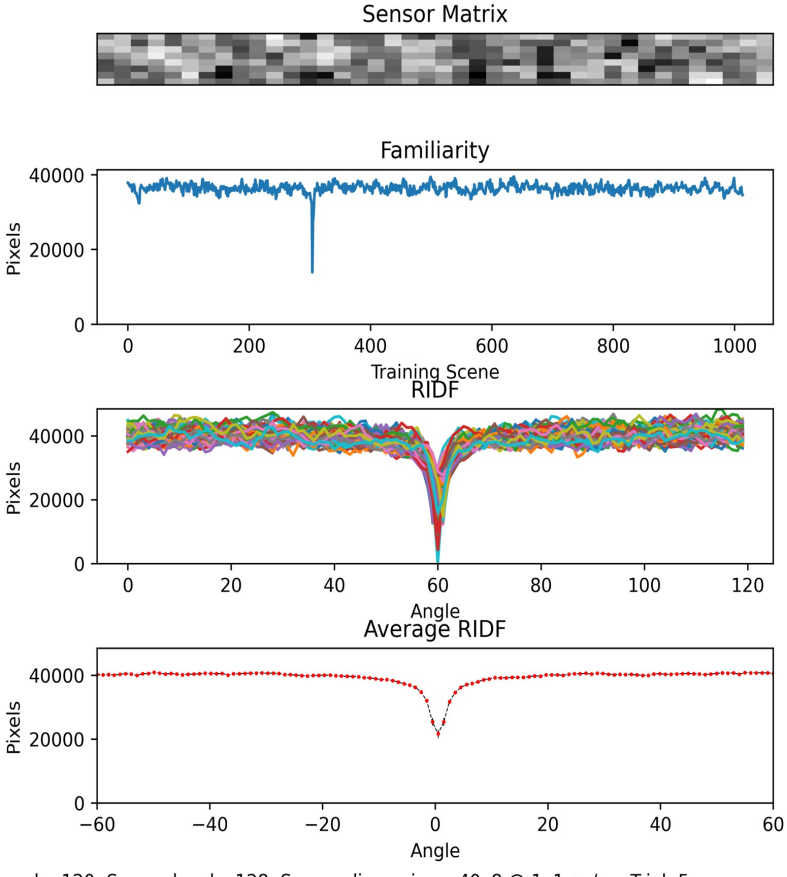




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 46.84; RMSD/dist: 0.117; TD: 13512; p90: 6; p50: 4; complete: 0

100%

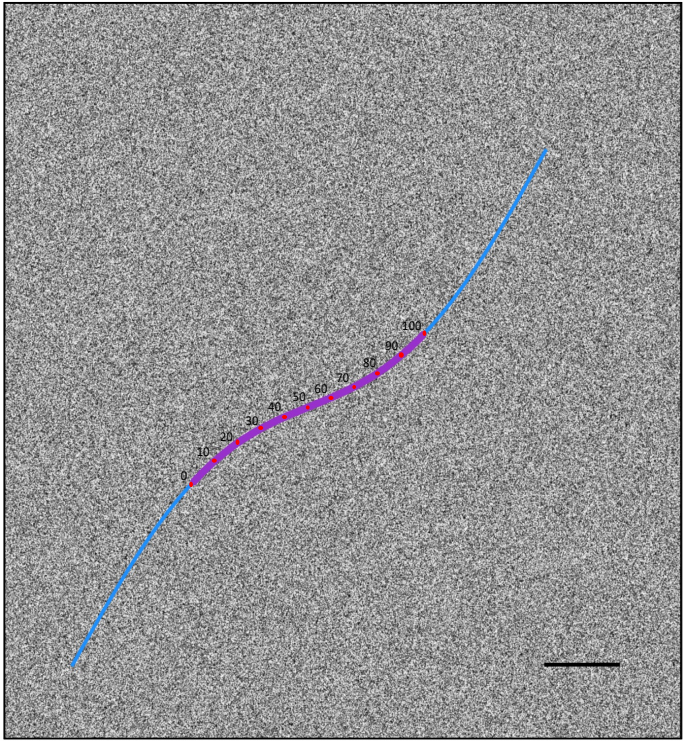


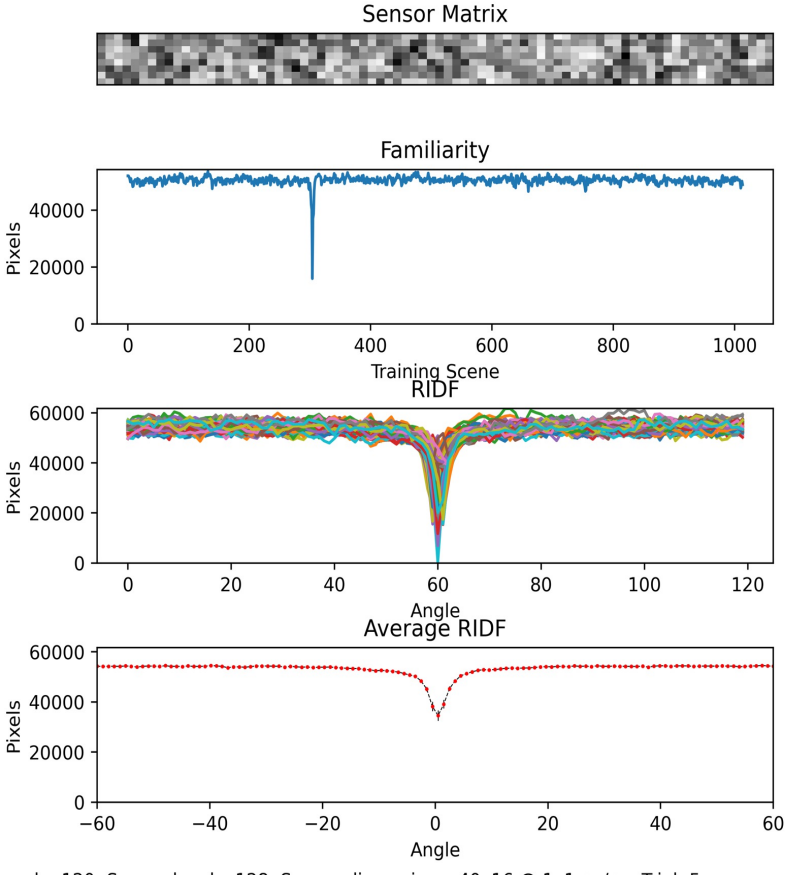




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 44.15; RMSD/dist: 0.110; TD: 14805; p90: 6; p50: 4; complete: 0

100%

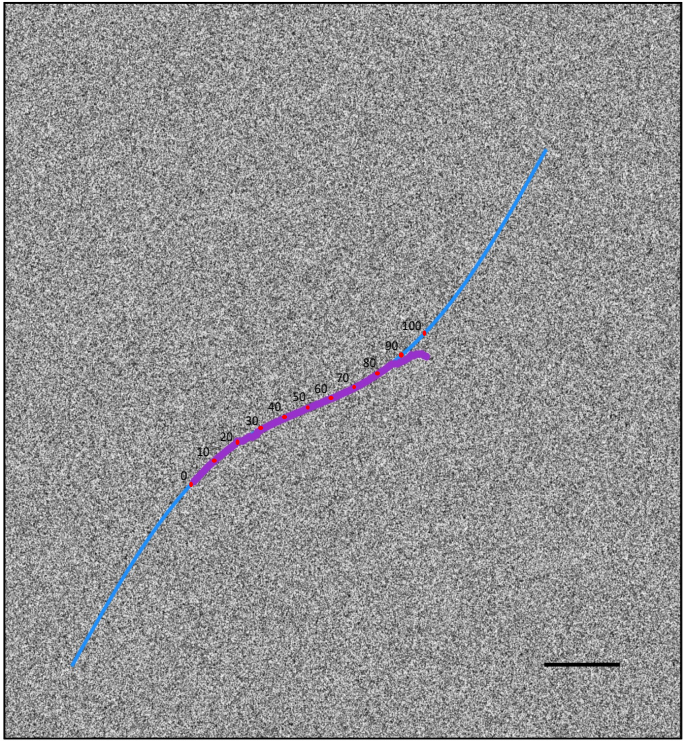


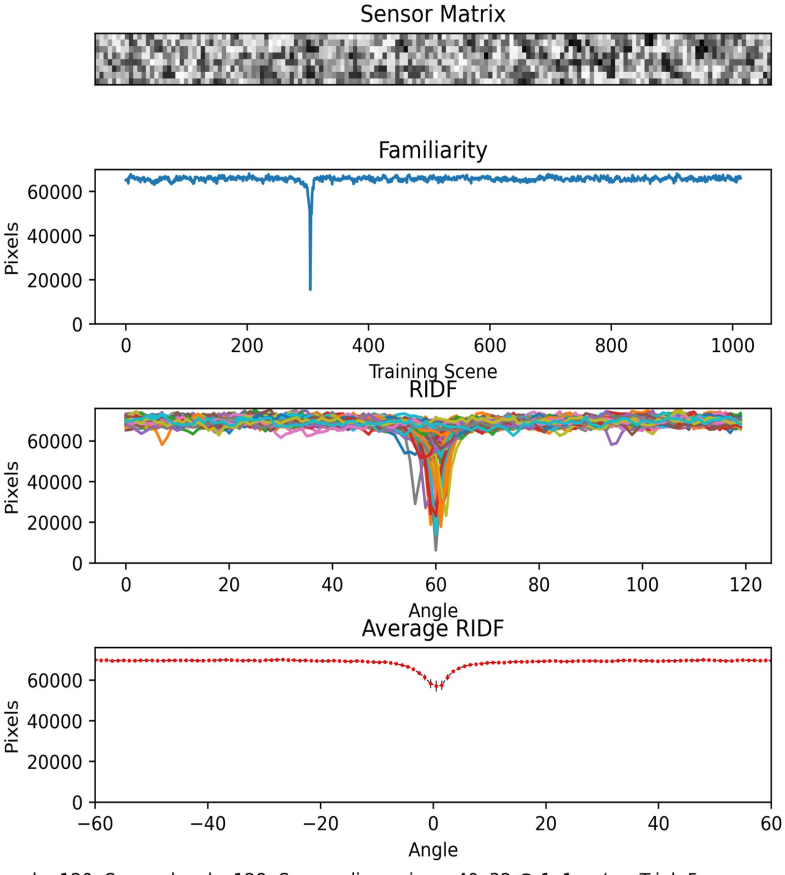




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 63.84; RMSD/dist: 0.160; TD: 15900; p90: 6; p50: 4; complete: 0

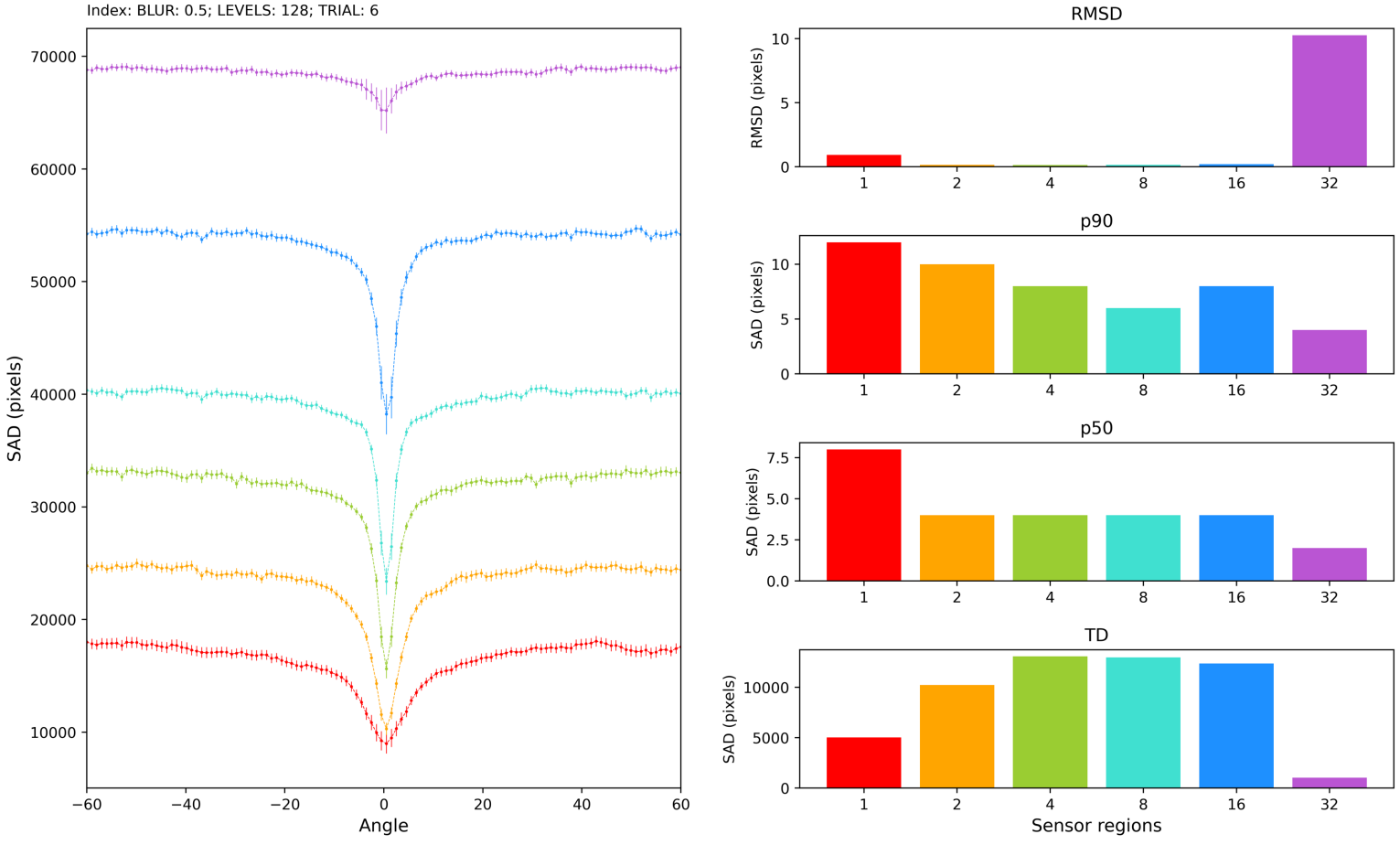
80%



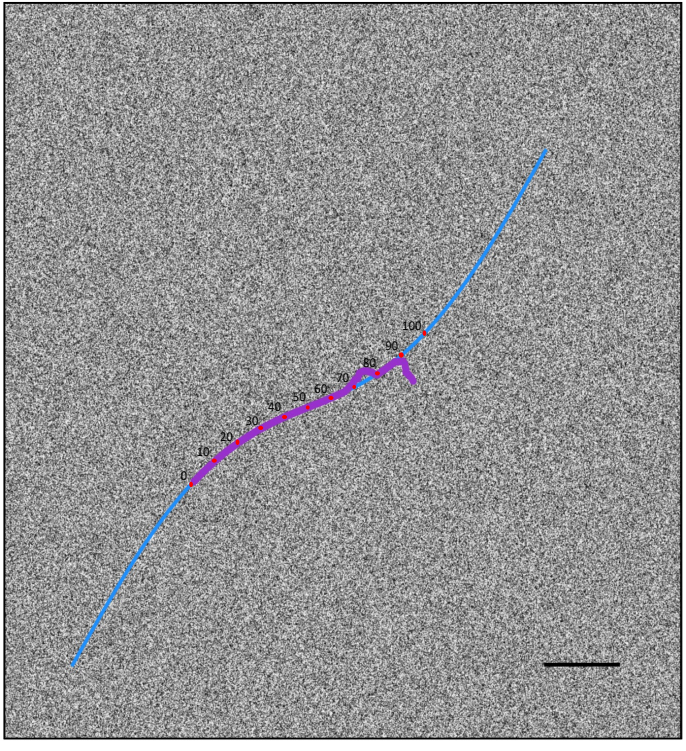



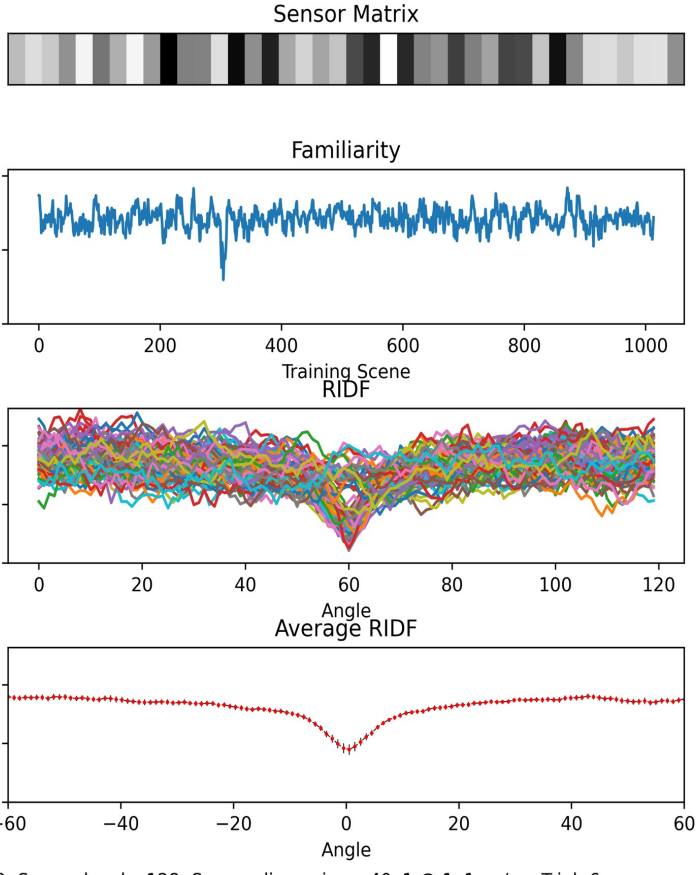

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 231.33; RMSD/dist: 0.578; TD: 9176; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 128; TRIAL: 6
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
10
5
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
10000
5000
0
Sensor regions

70%

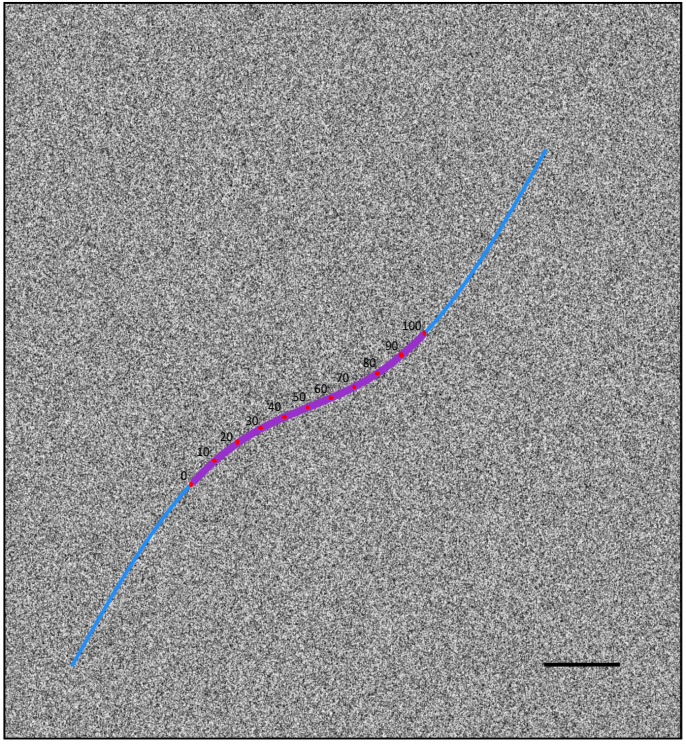


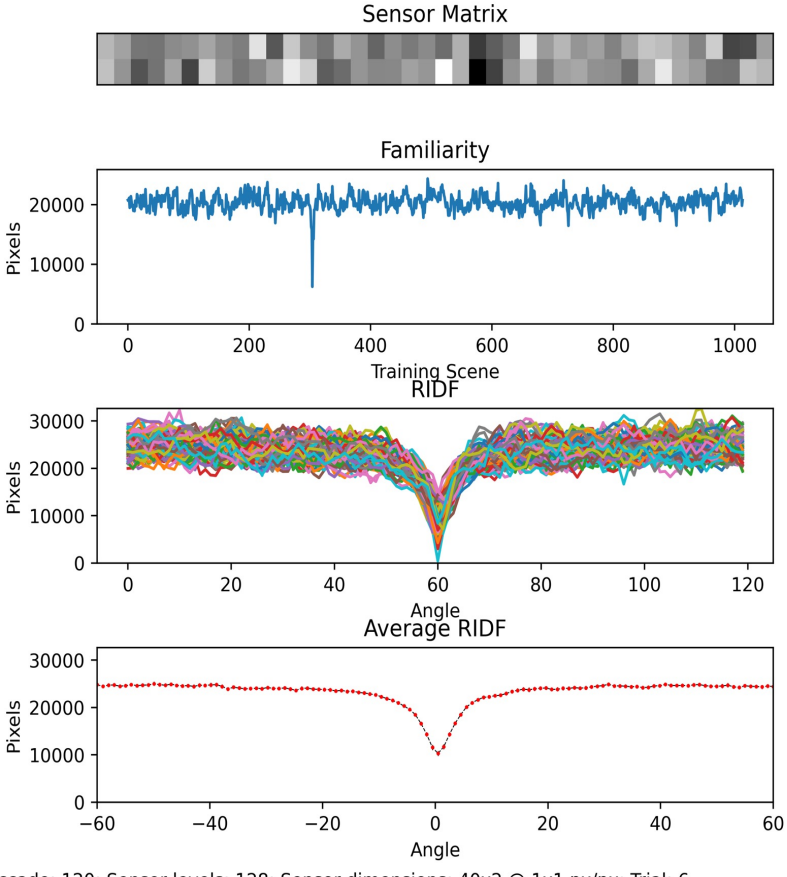




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 367.80; RMSD/dist: 0.919; TD: 5014; p90: 12; p50: 8; complete: 0

100%

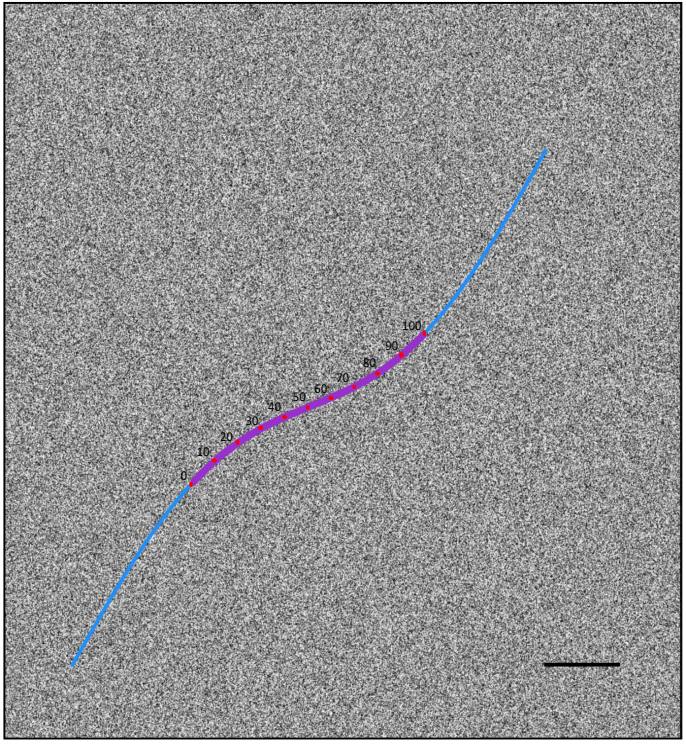


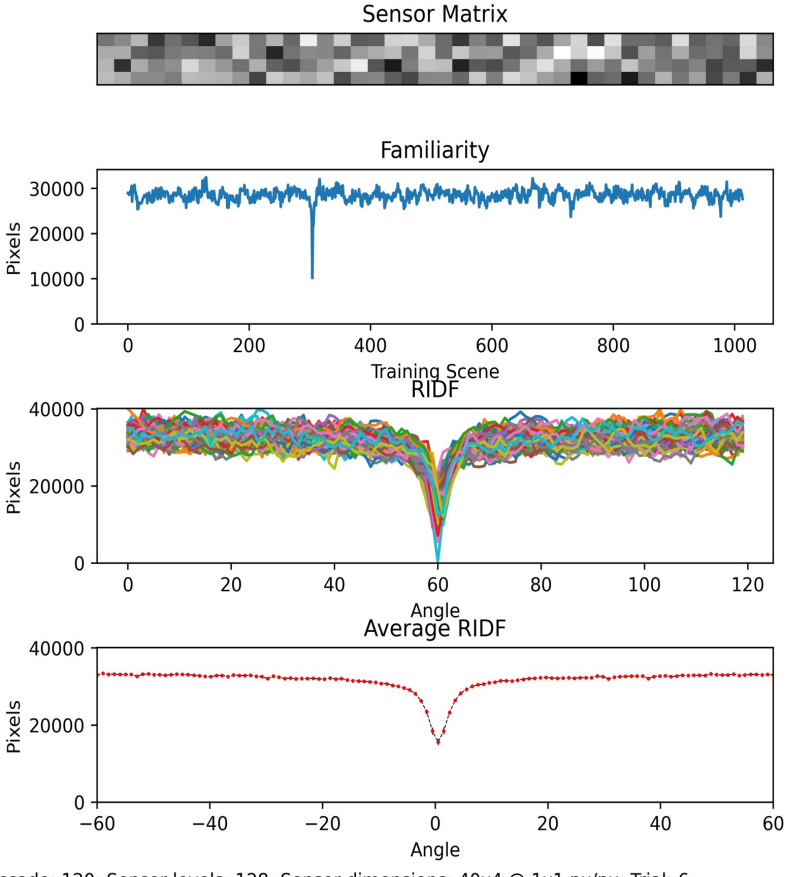




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 55.80; RMSD/dist: 0.140; TD: 10232; p90: 10; p50: 4; complete: 0

100%

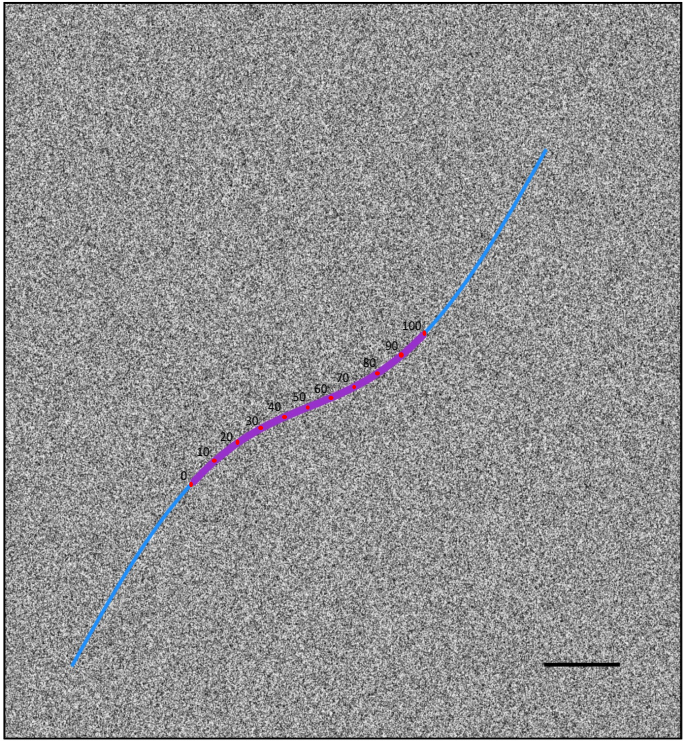


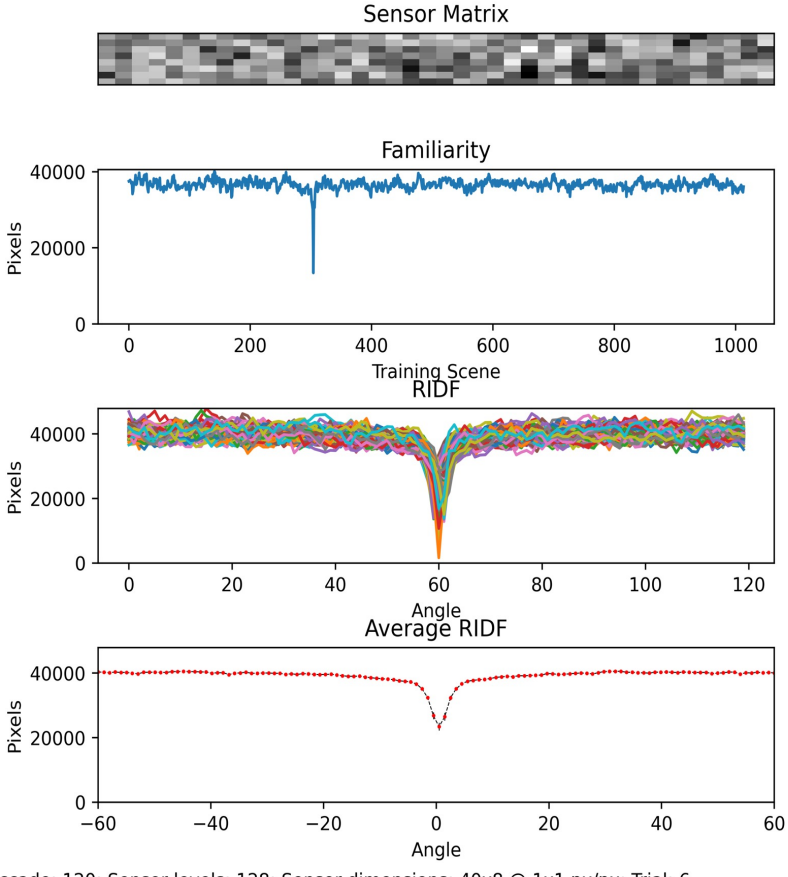




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 52.38; RMSD/dist: 0.131; TD: 13062; p90: 8; p50: 4; complete: 0

100%

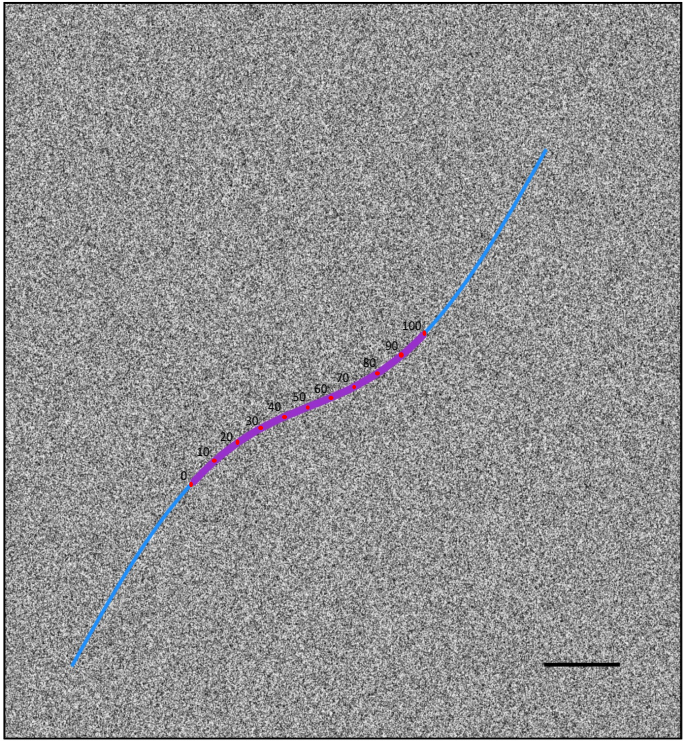


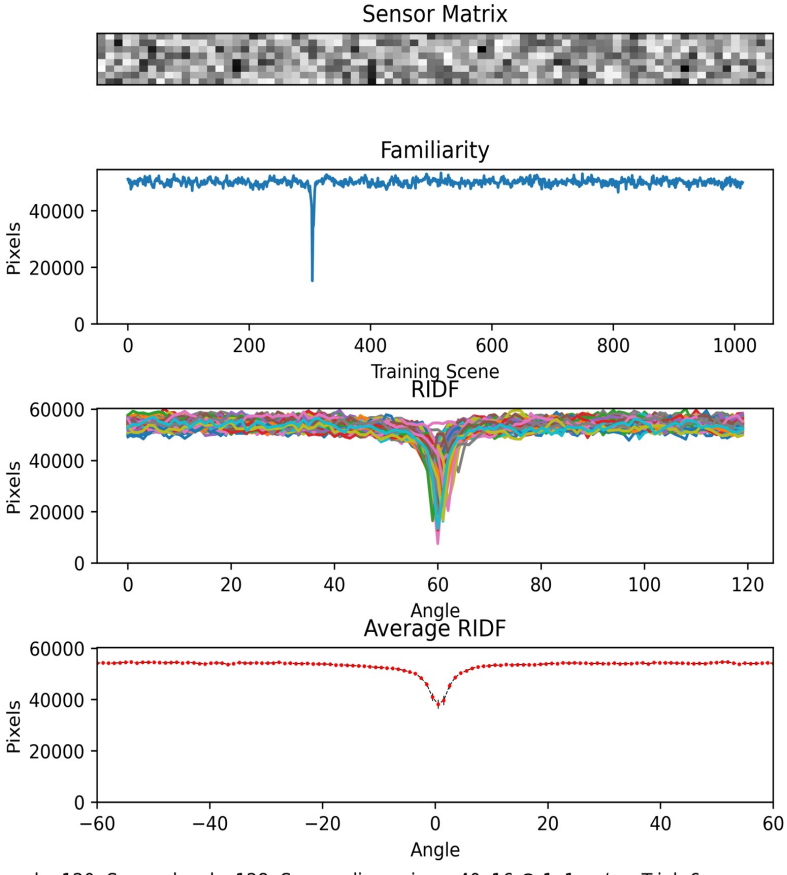




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 58.24; RMSD/dist: 0.146; TD: 12961; p90: 6; p50: 4; complete: 0

100%

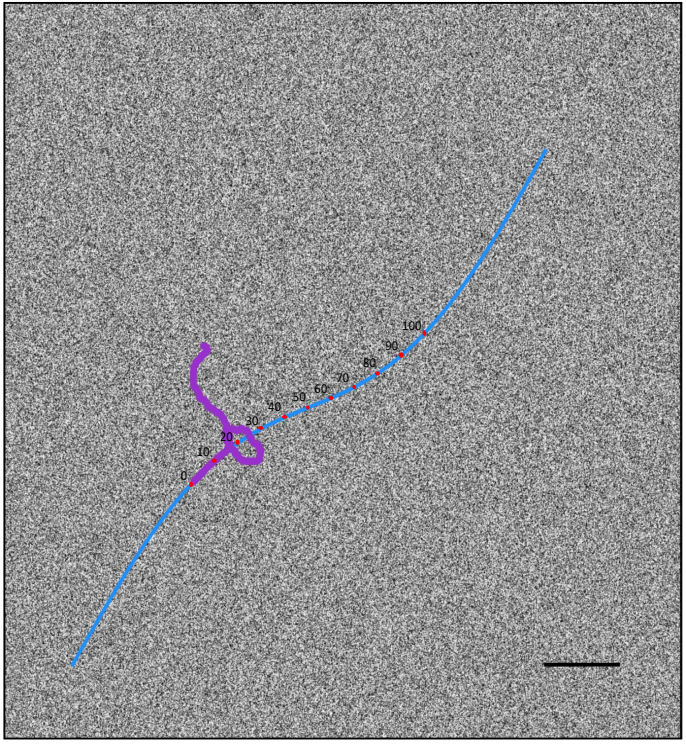


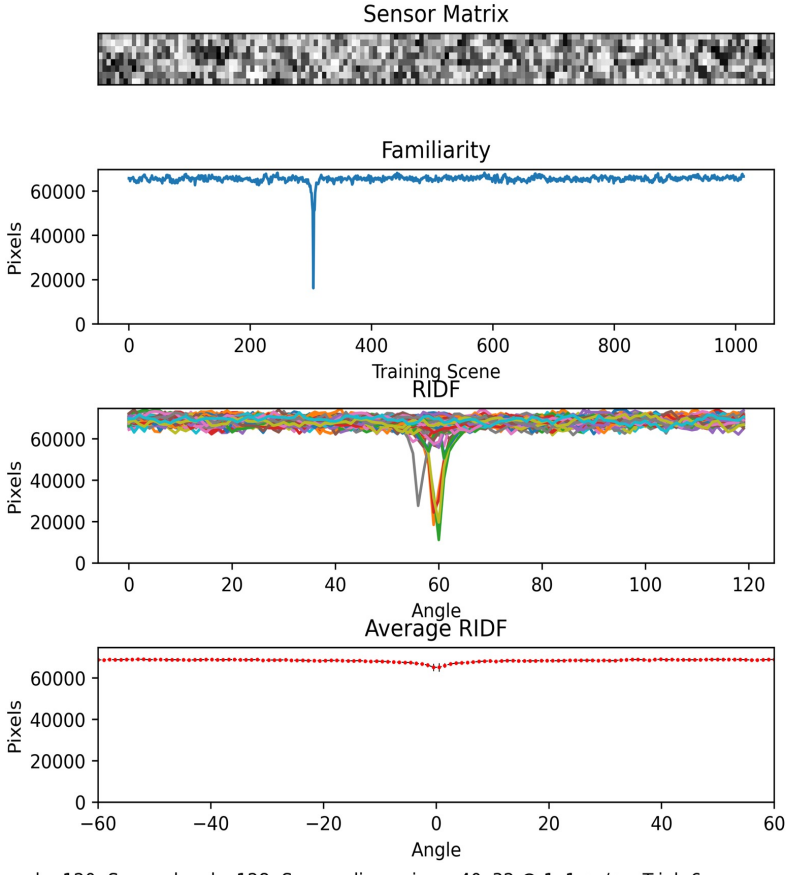




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

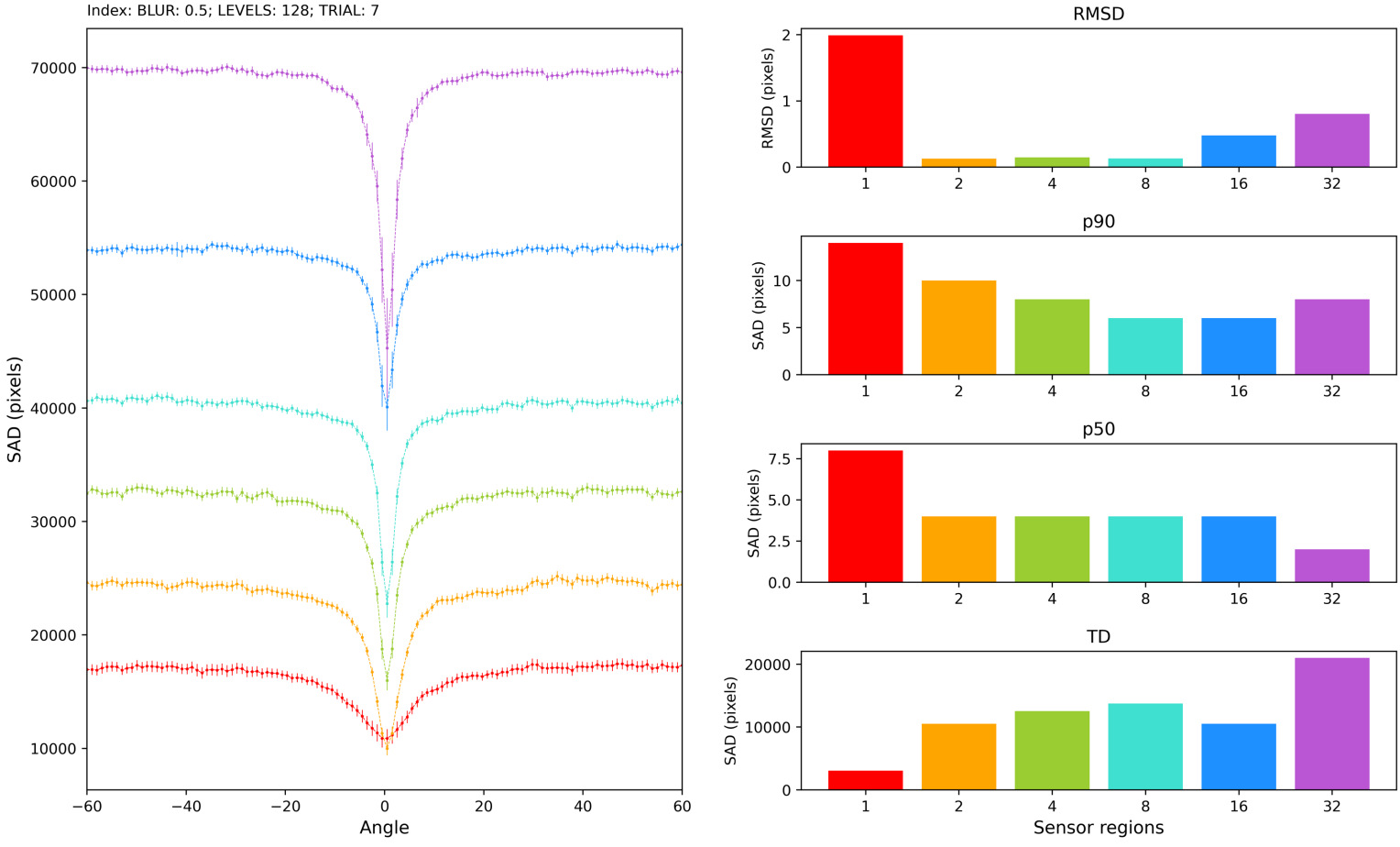
Navigation stats: RMSD error: 74.83; RMSD/dist: 0.187; TD: 12366; p90: 8; p50: 4; complete: 0

10%




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 4106.59; RMSD/dist: 10.266; TD: 1010; p90: 4; p50: 2; complete: 0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SAD (pixels)
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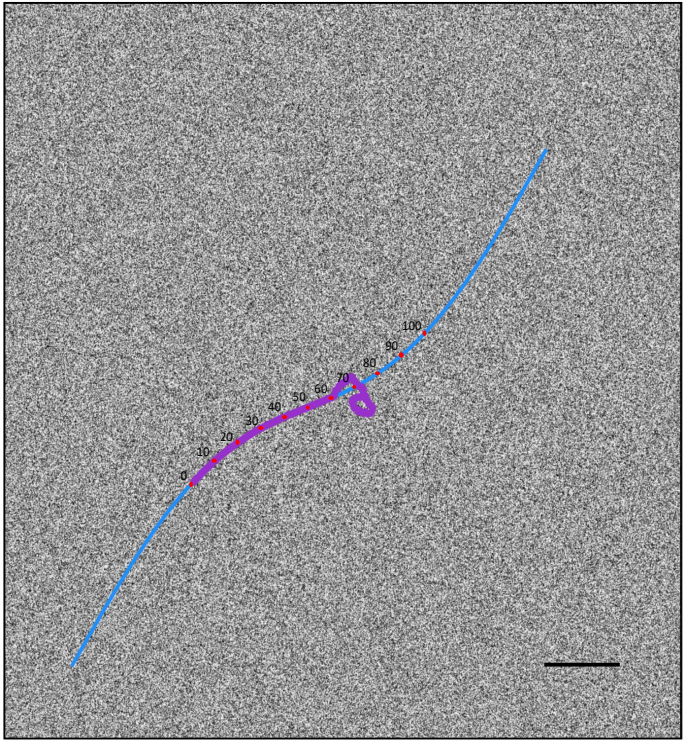
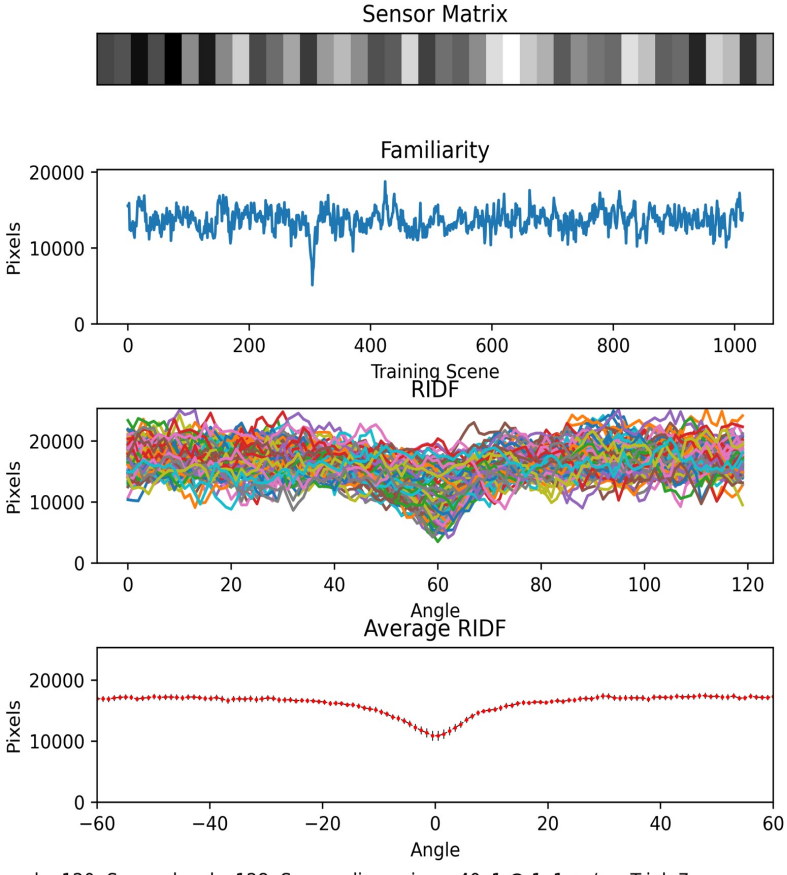
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
2
1
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

60%

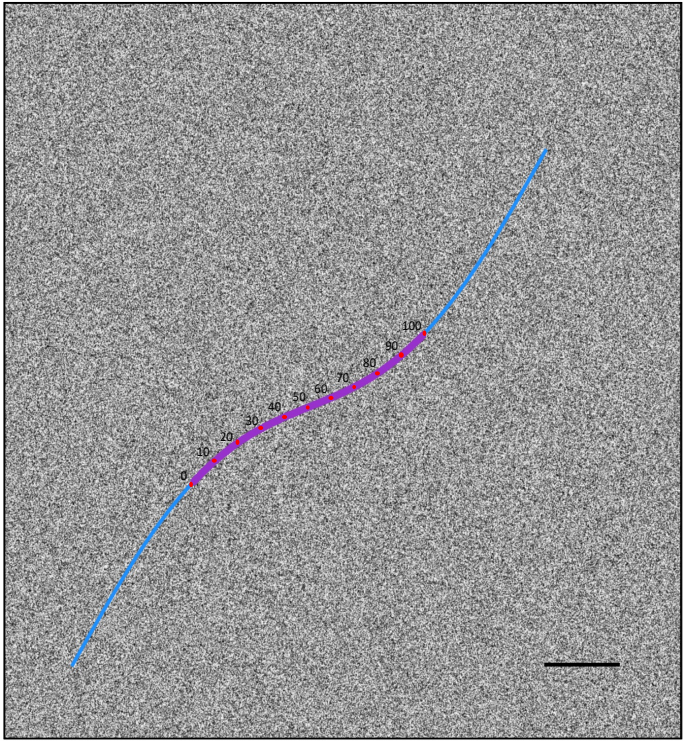


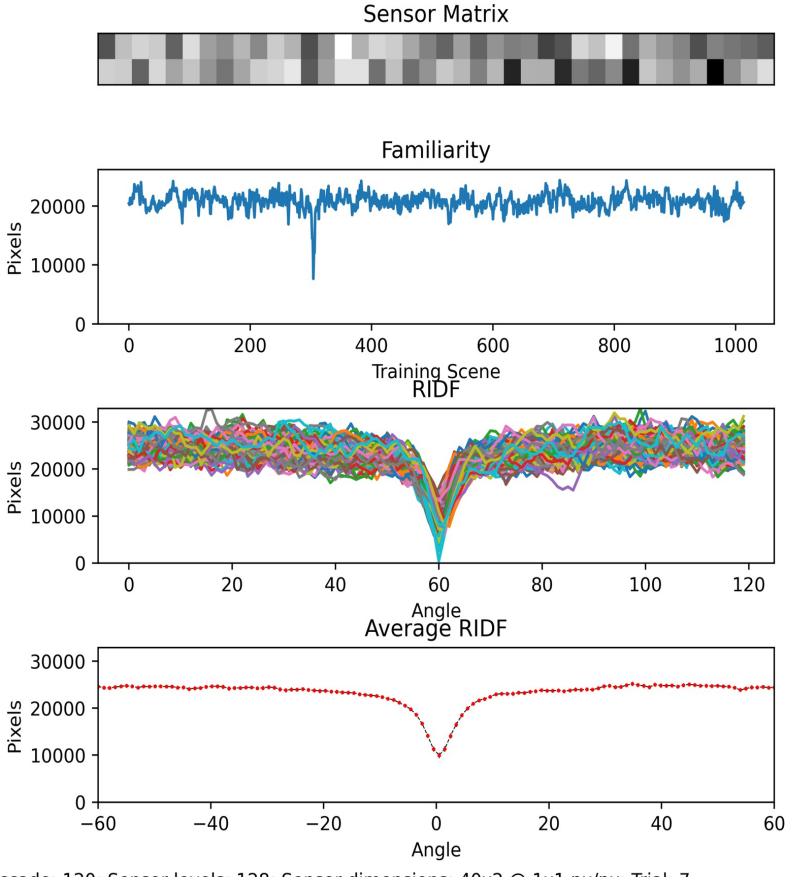




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 797.20; RMSD/dist: 1.993; TD: 3061; p90: 14; p50: 8; complete: 0

100%

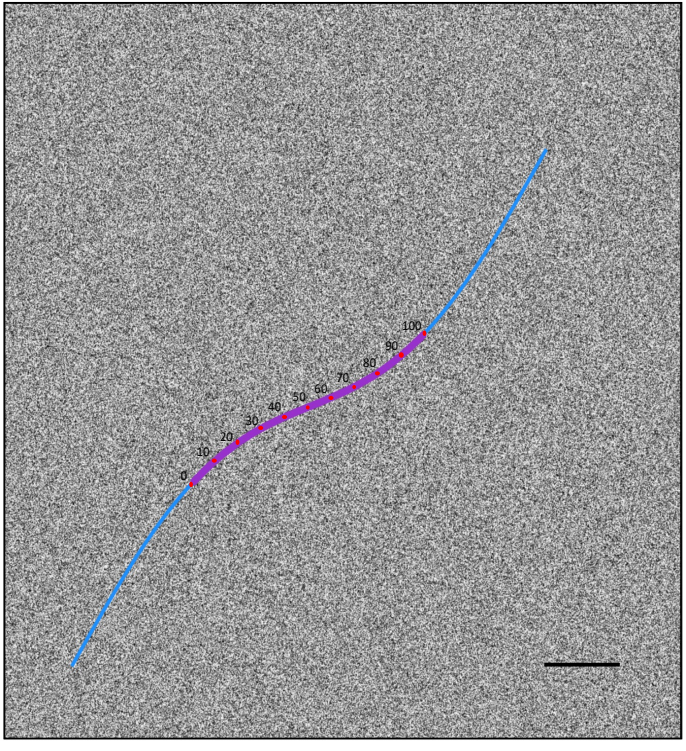


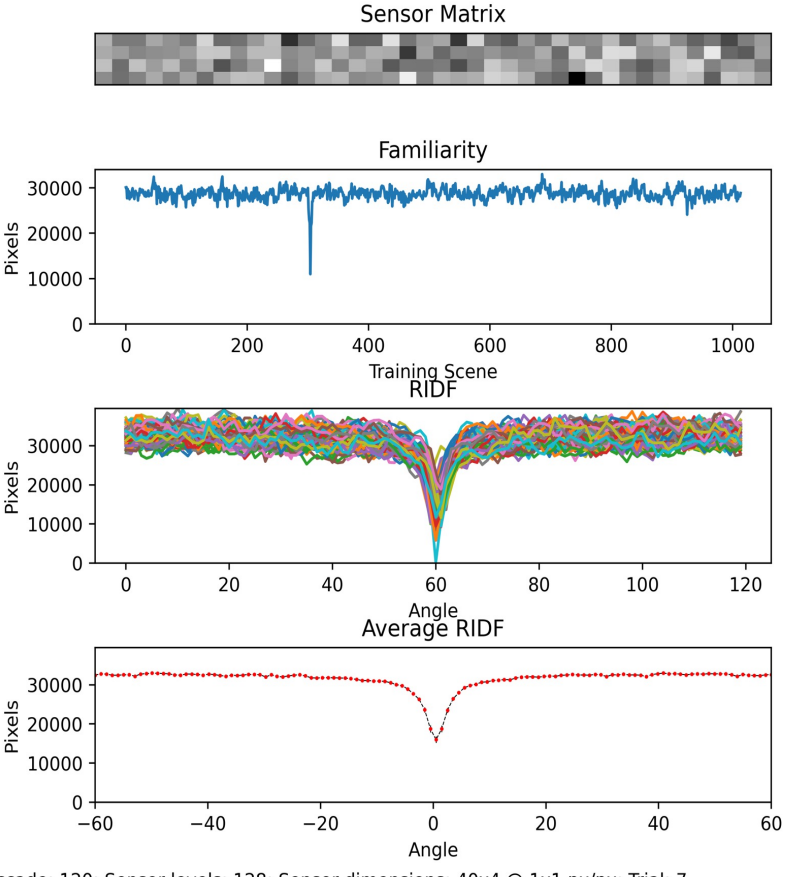




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 50.54; RMSD/dist: 0.126; TD: 10527; p90: 10; p50: 4; complete: 0

100%

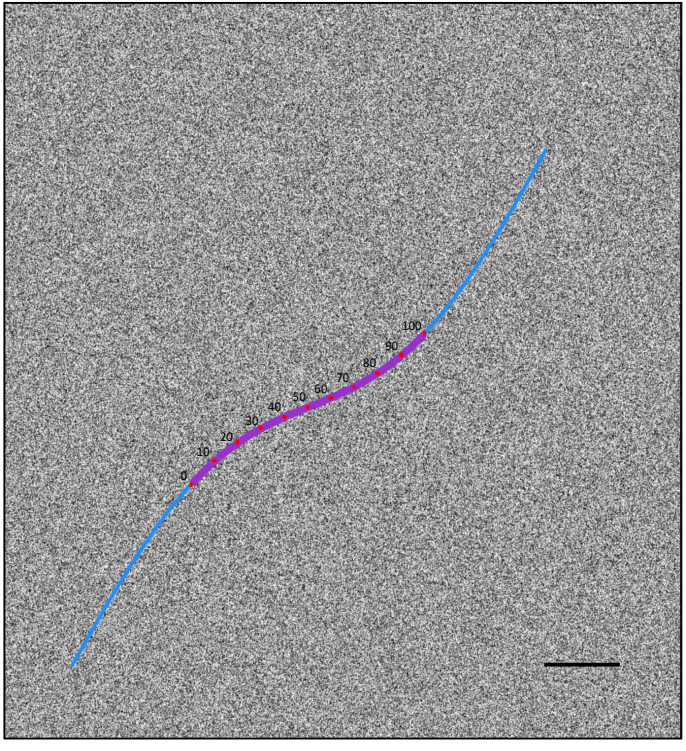


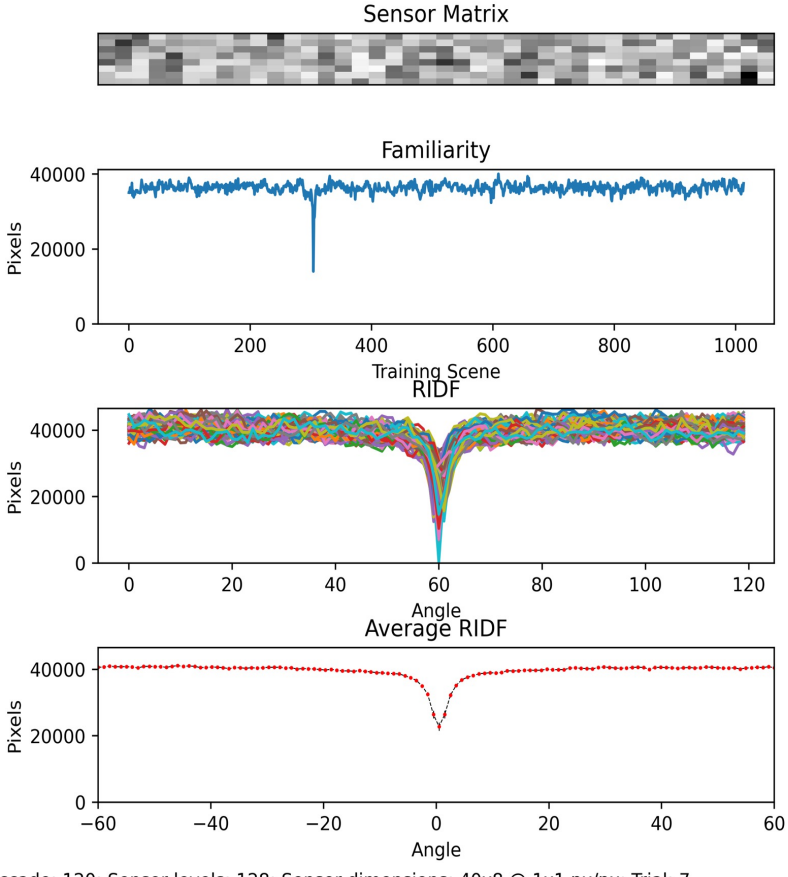




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 58.57; RMSD/dist: 0.146; TD: 12519; p90: 8; p50: 4; complete: 0

100%

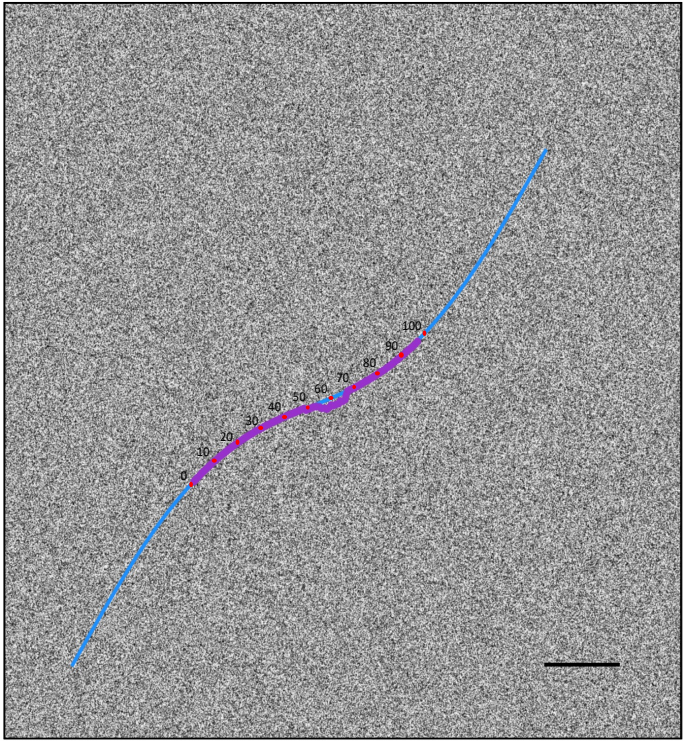


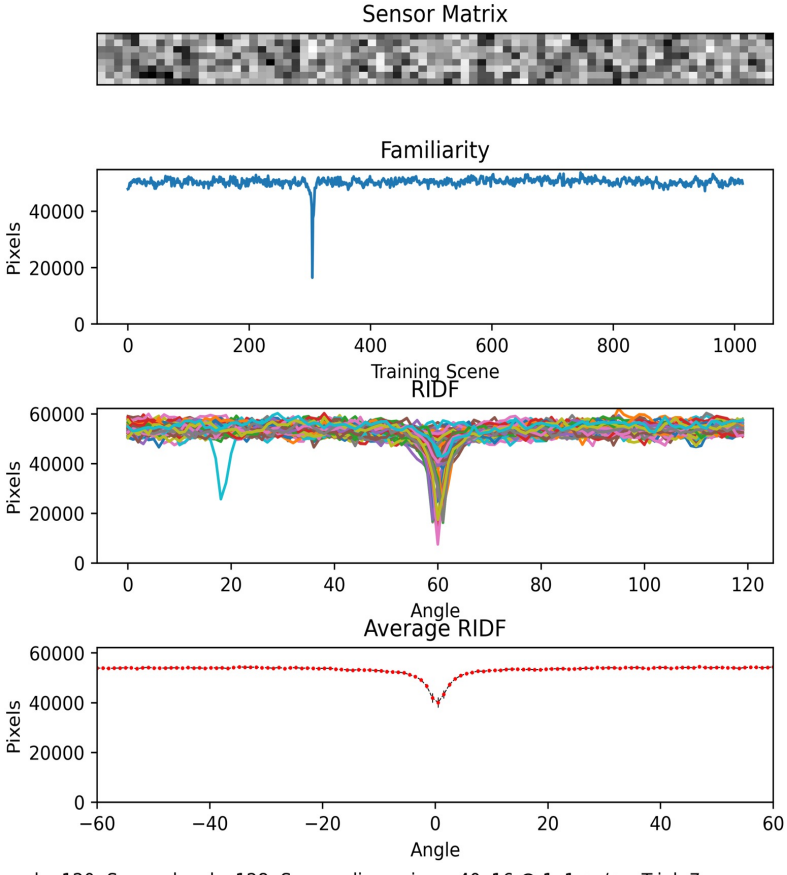




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 52.12; RMSD/dist: 0.130; TD: 13730; p90: 6; p50: 4; complete: 0

70%

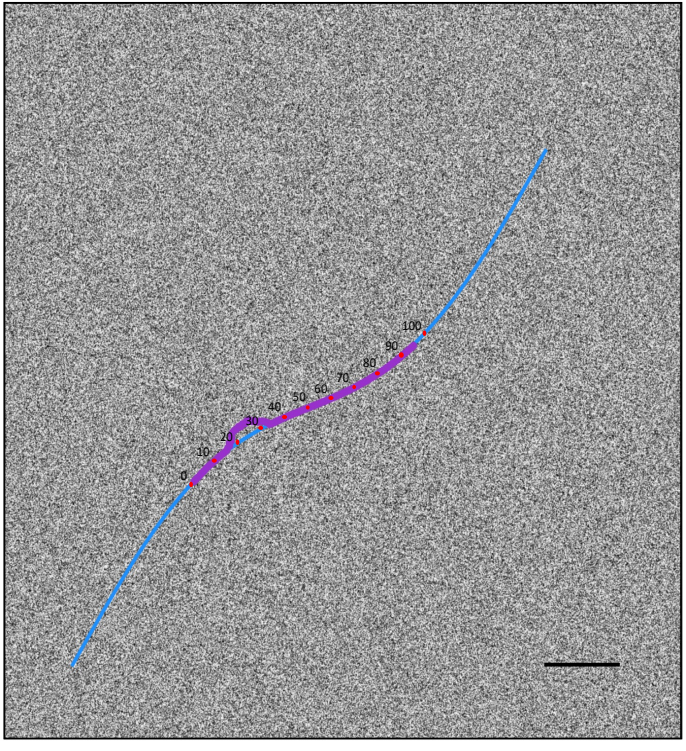


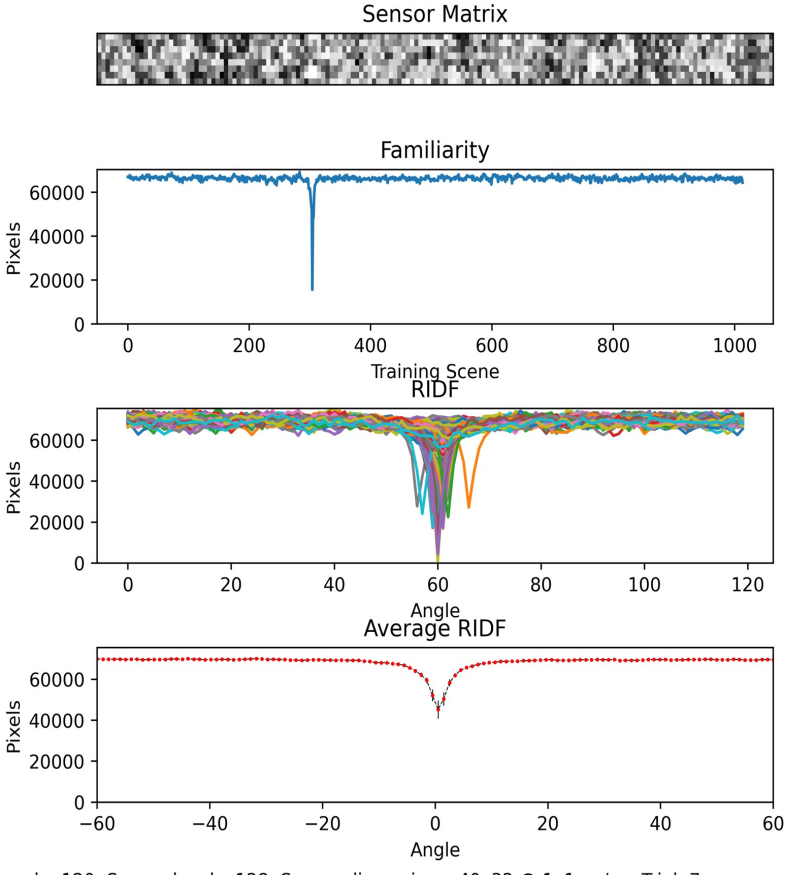




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 191.39; RMSD/dist: 0.478; TD: 10508; p90: 6; p50: 4; complete: 0

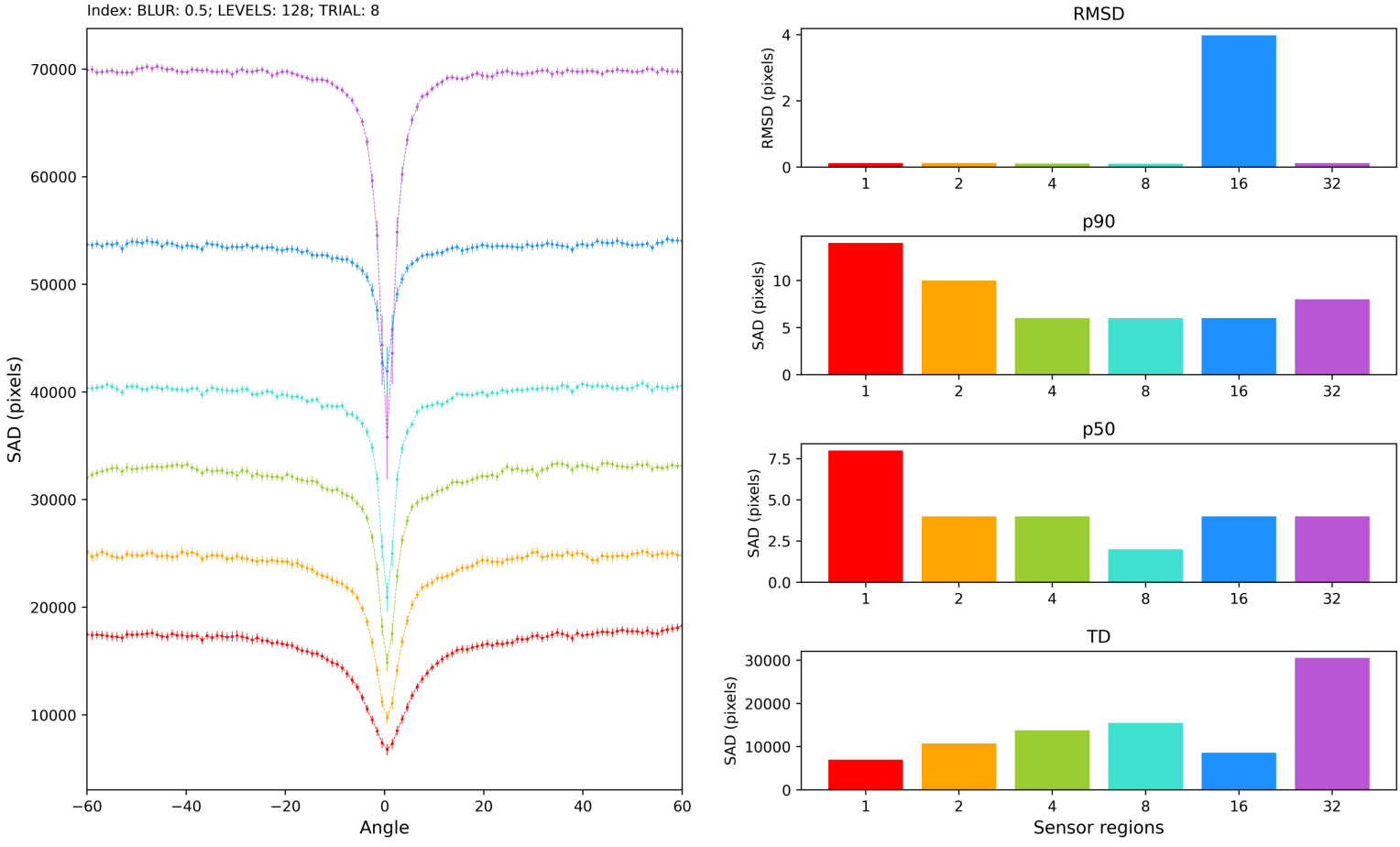
70%



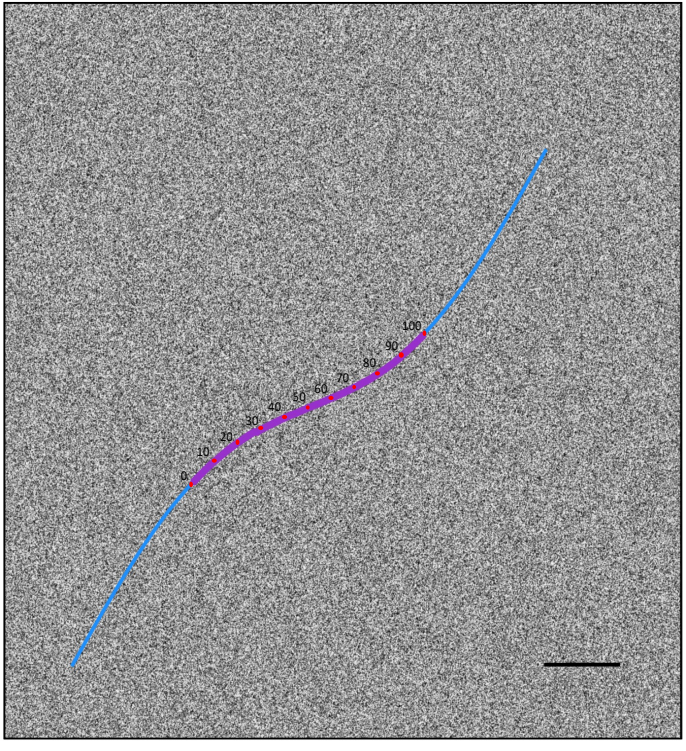



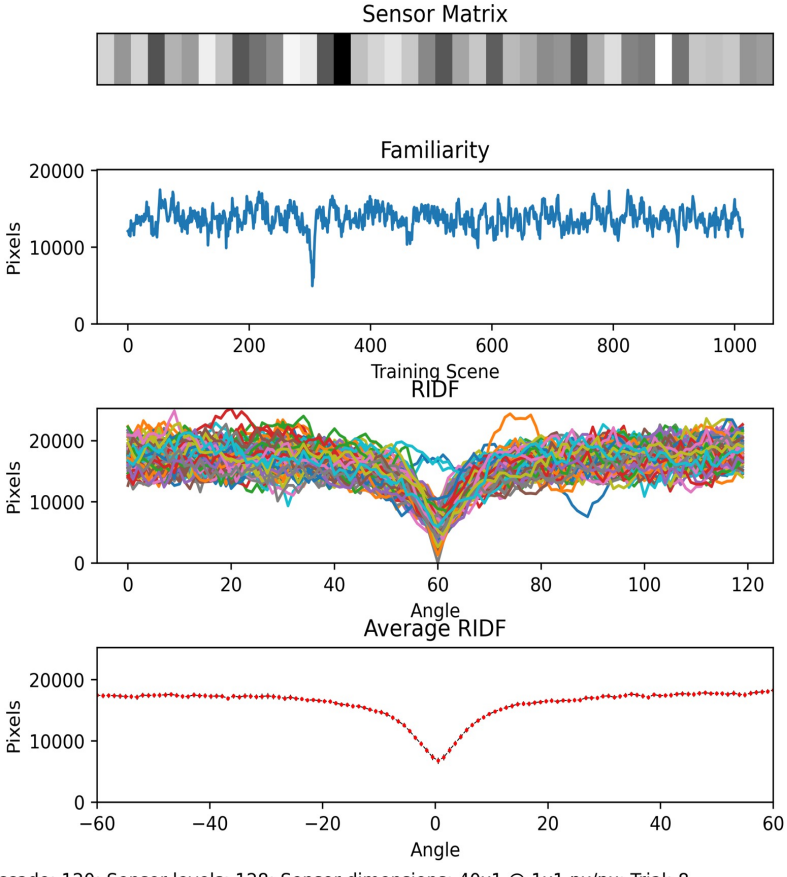

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 321.57; RMSD/dist: 0.804; TD: 20990; p90: 8; p50: 2; complete: 0


Index: BLUR: 0.5; LEVELS: 128; TRIAL: 8
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
4
2
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
30000
20000
10000
0
Sensor regions

100%

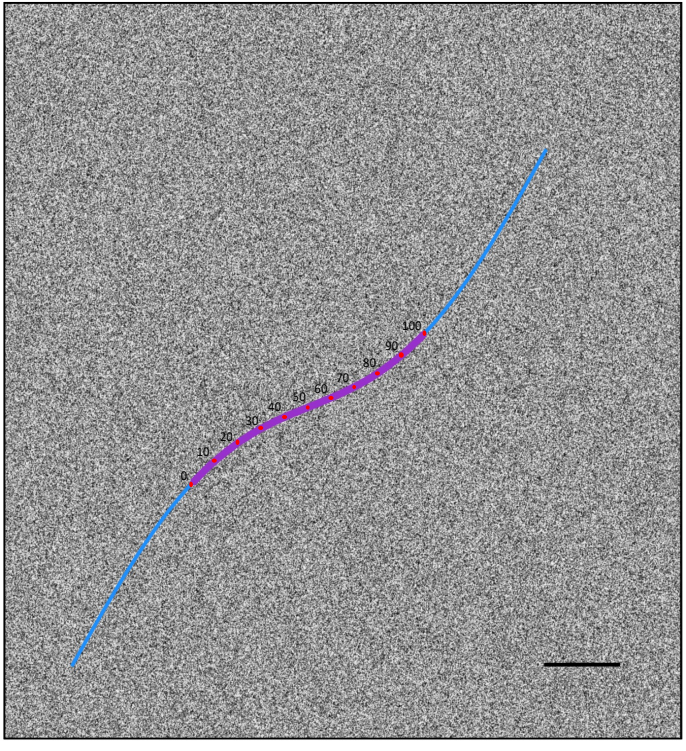


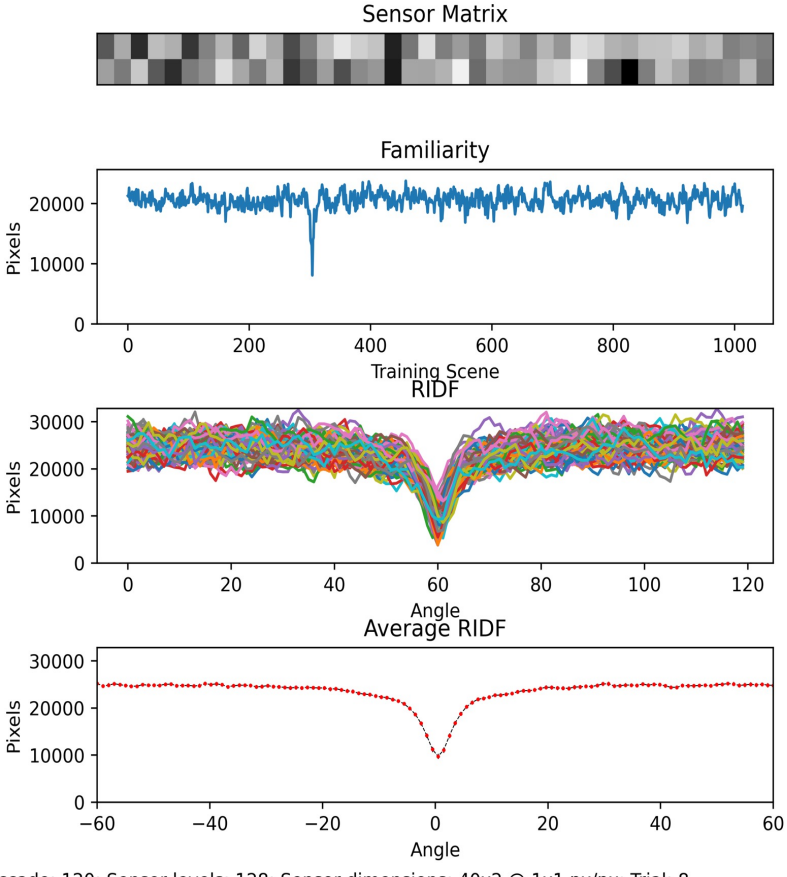




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 48.16; RMSD/dist: 0.120; TD: 6995; p90: 14; p50: 8; complete: 0

100%

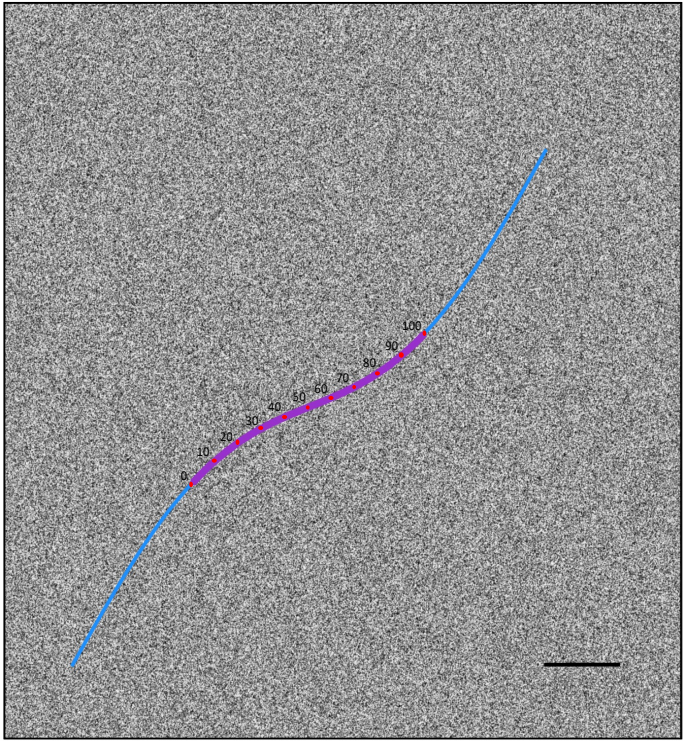


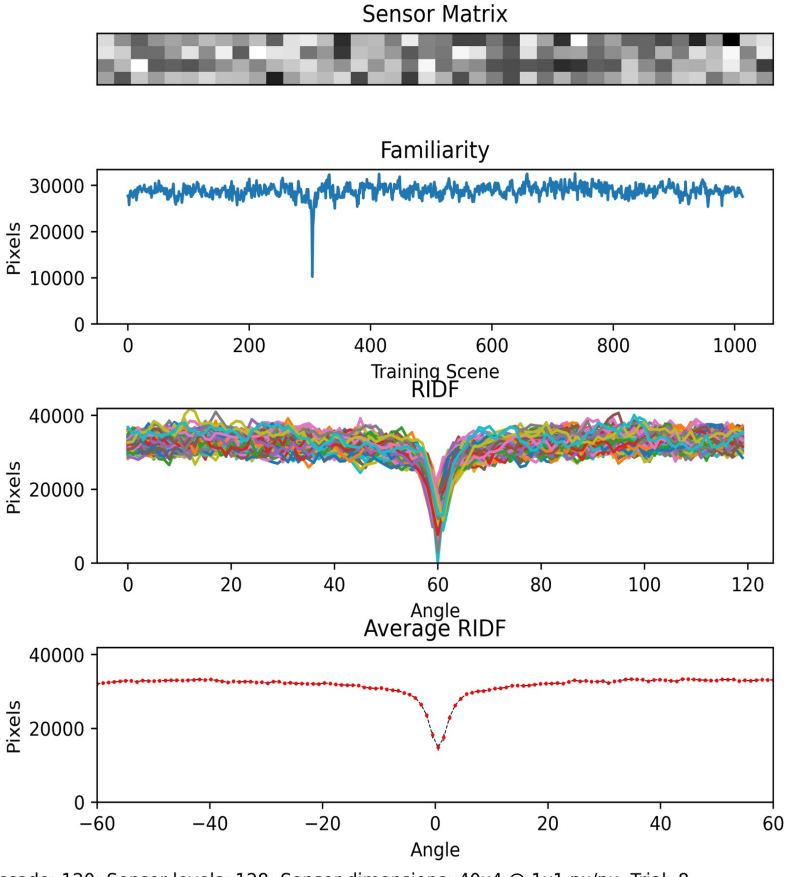




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 47.41; RMSD/dist: 0.119; TD: 10762; p90: 10; p50: 4; complete: 0

100%

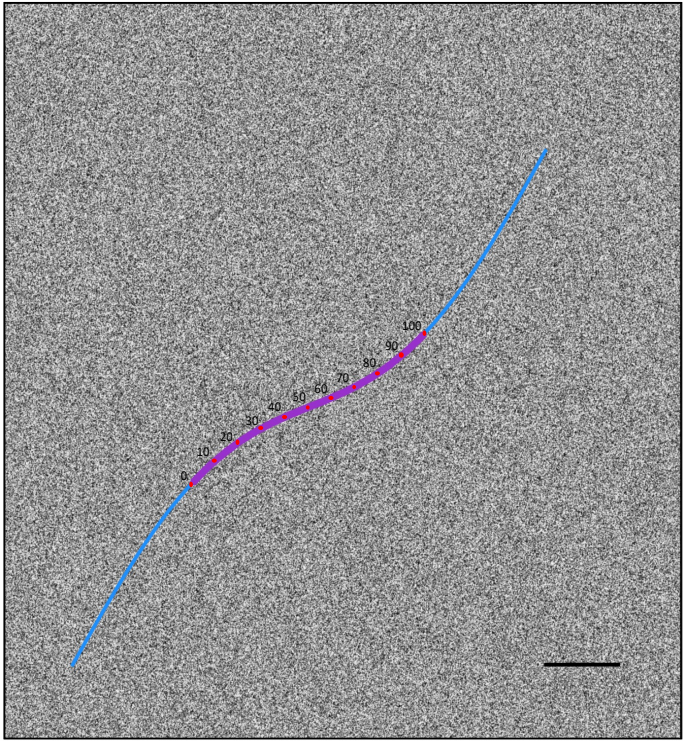


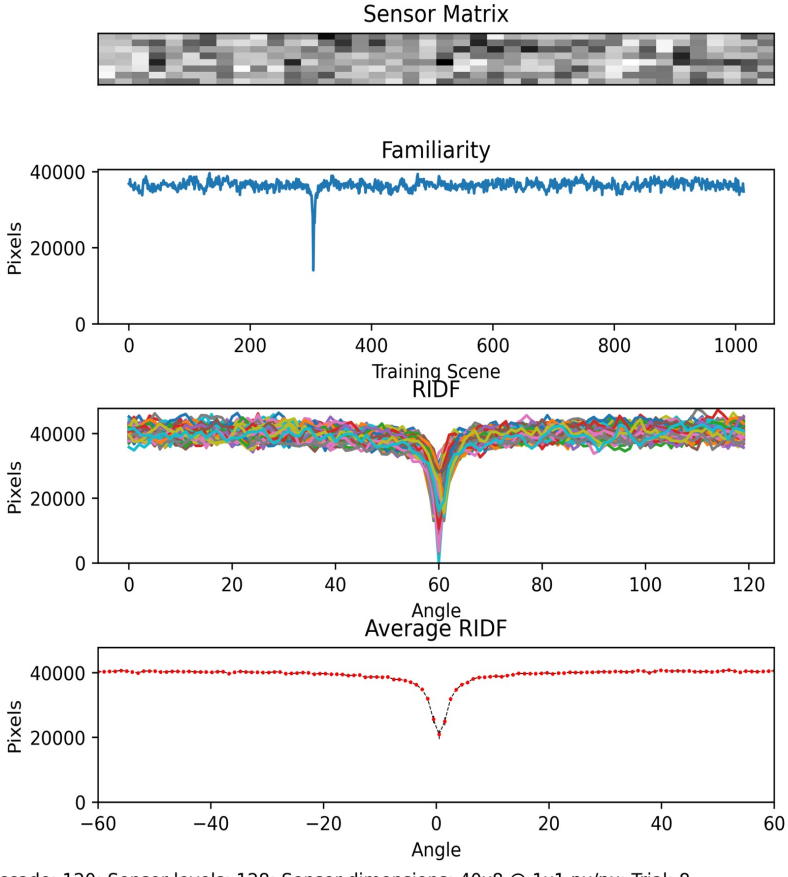




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 42.69; RMSD/dist: 0.107; TD: 13784; p90: 6; p50: 4; complete: 0

100%

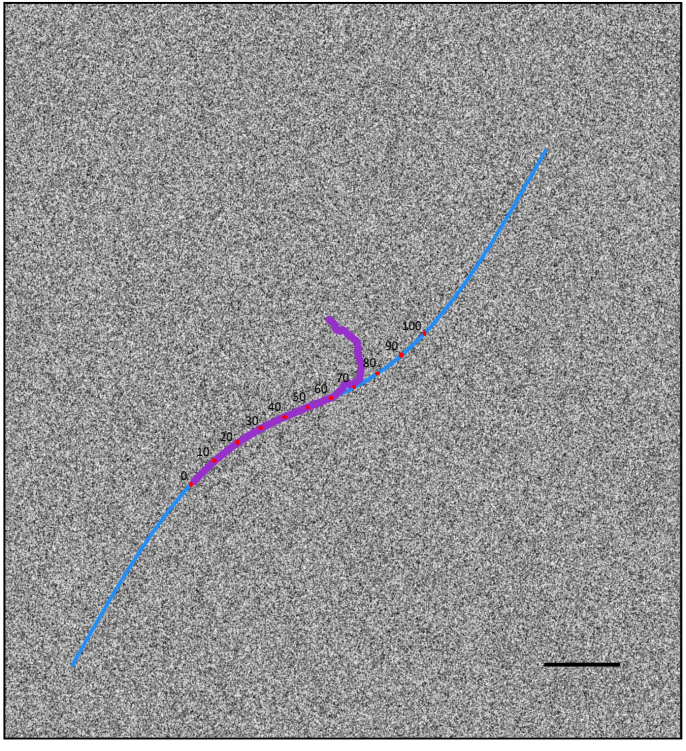


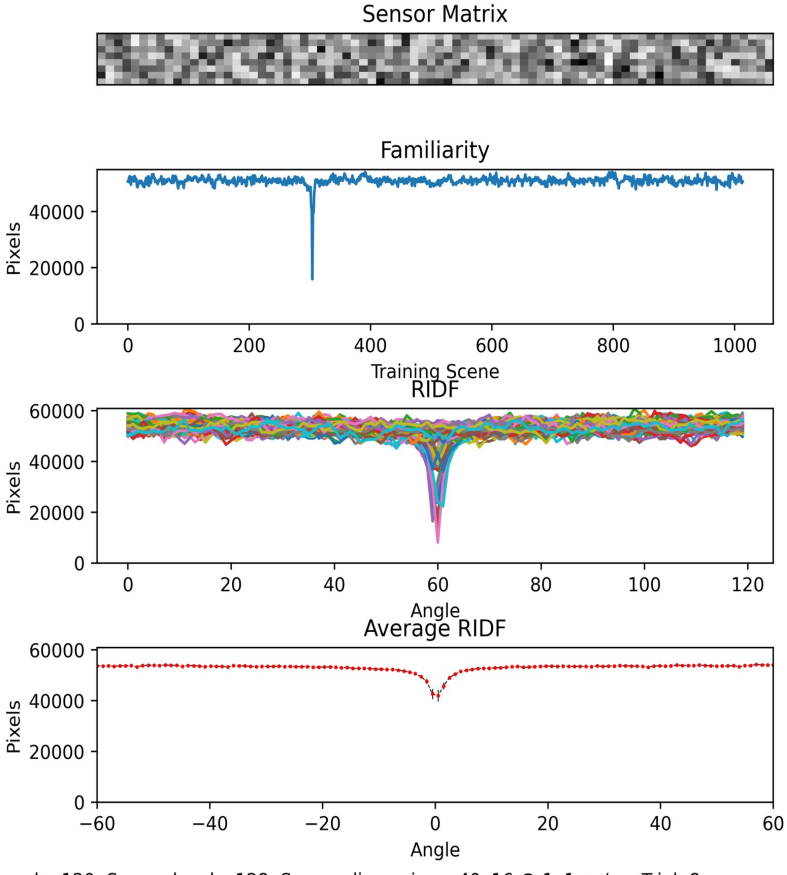




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 40.91; RMSD/dist: 0.102; TD: 15461; p90: 6; p50: 2; complete: 0

60%

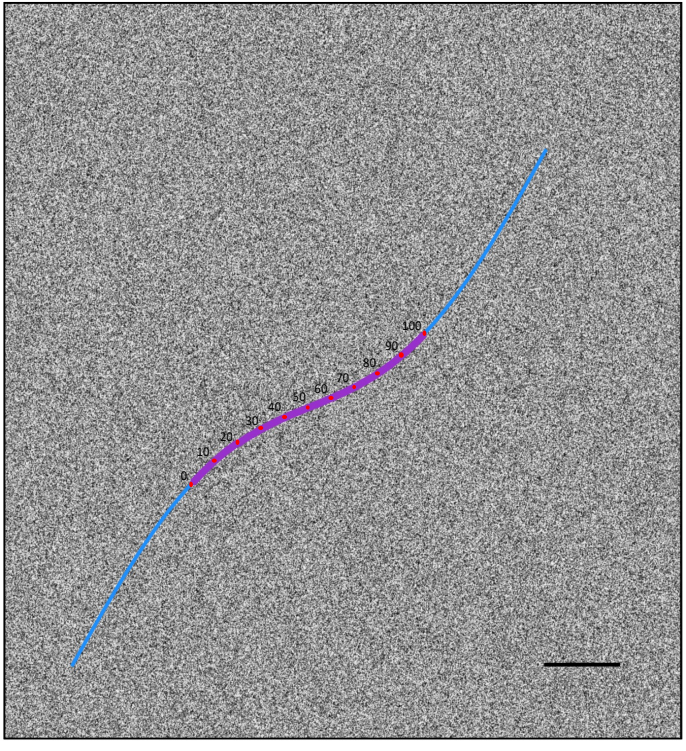


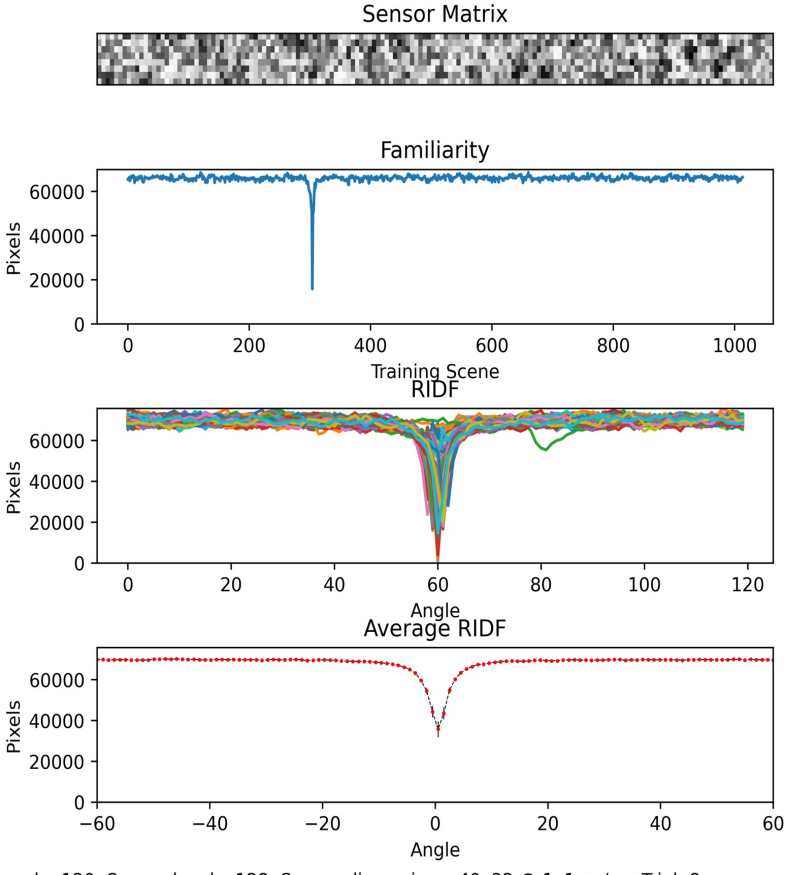




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 1593.14; RMSD/dist: 3.983; TD: 8599; p90: 6; p50: 4; complete: 0

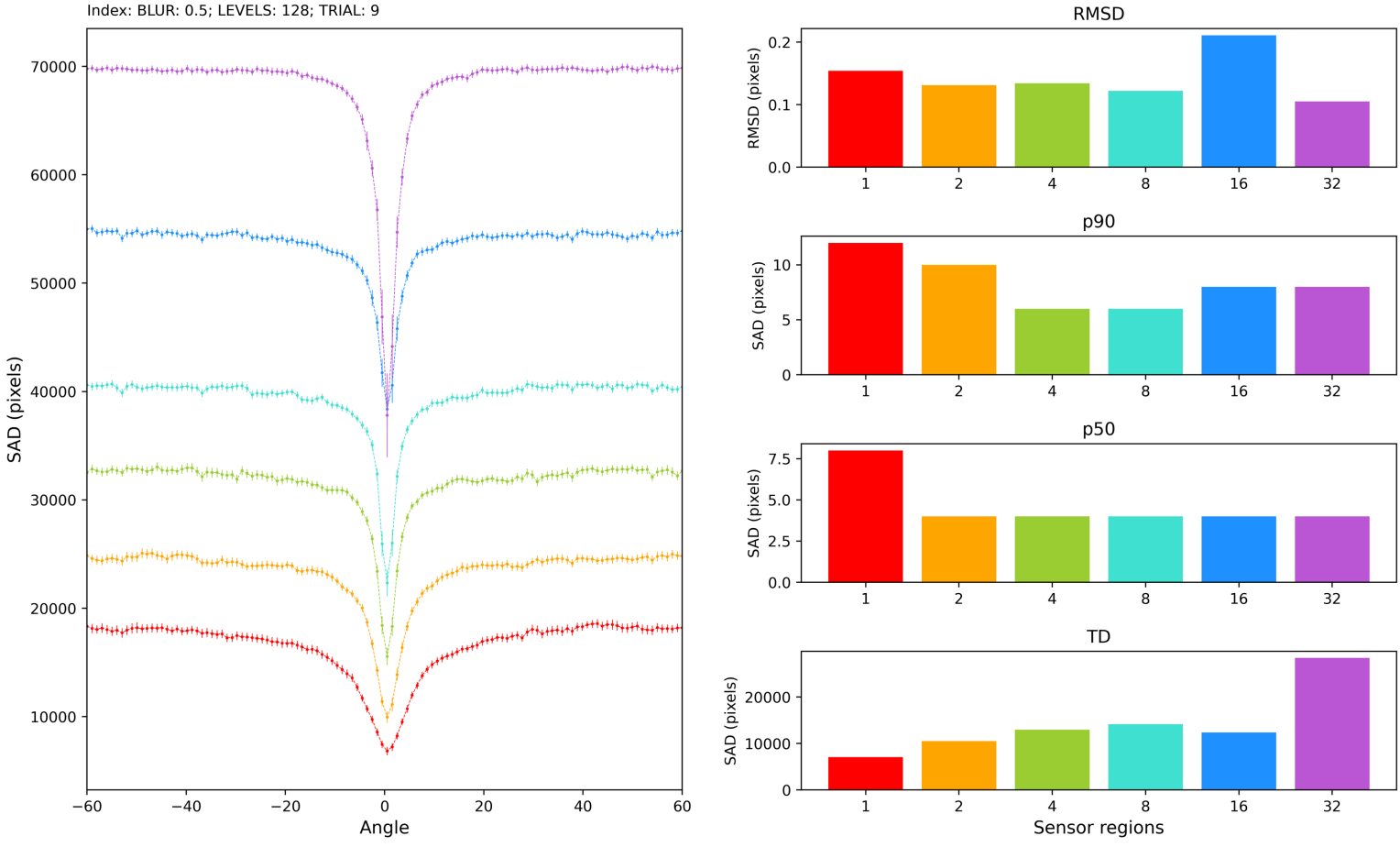
100%




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 48.73; RMSD/dist: 0.122; TD: 30524; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 128; TRIAL: 9
SAD (pixels)
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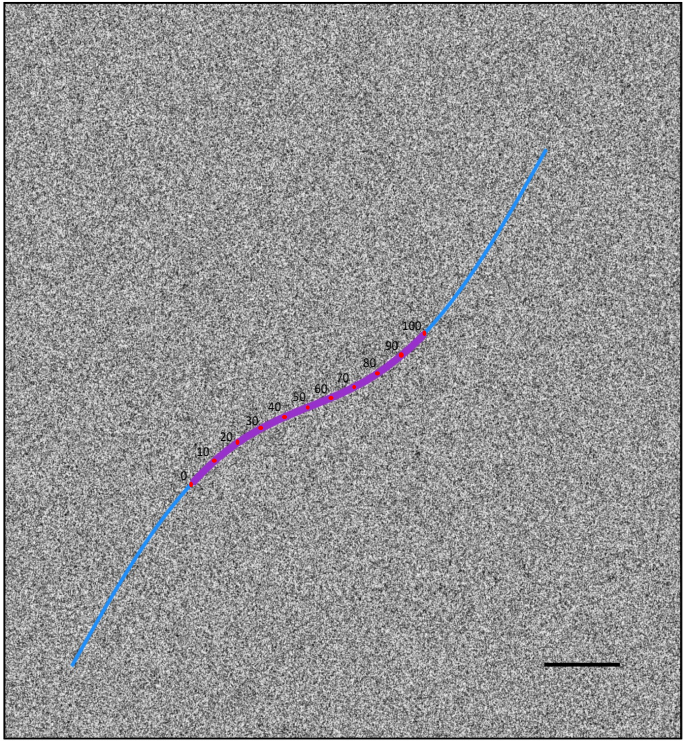
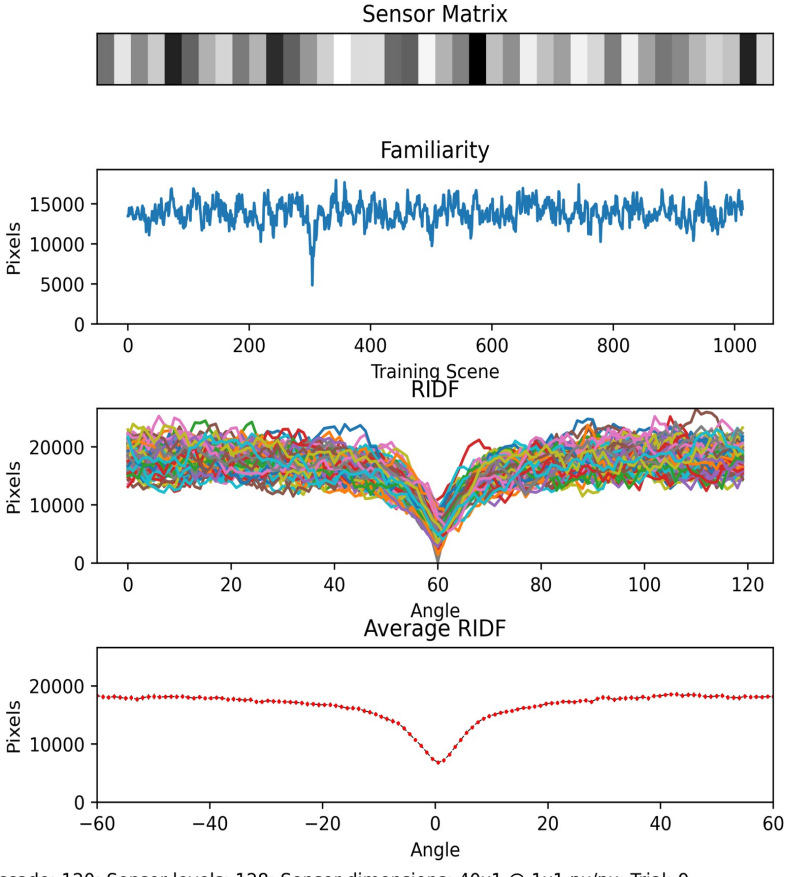
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
0.2
0.1
0.0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
p50
SAD (pixels)
7.5
5.0
2.5
0.0
TD
SAD (pixels)
20000
10000
0
Sensor regions

100%

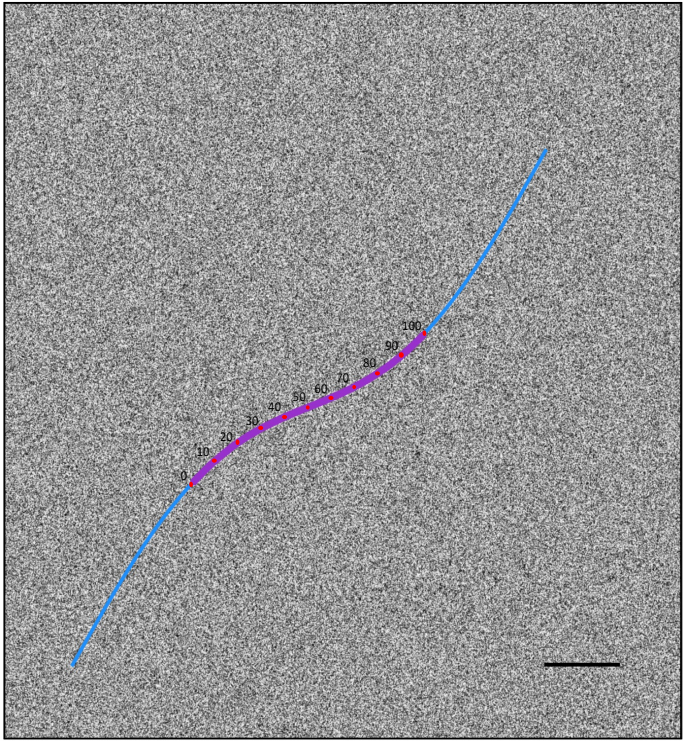


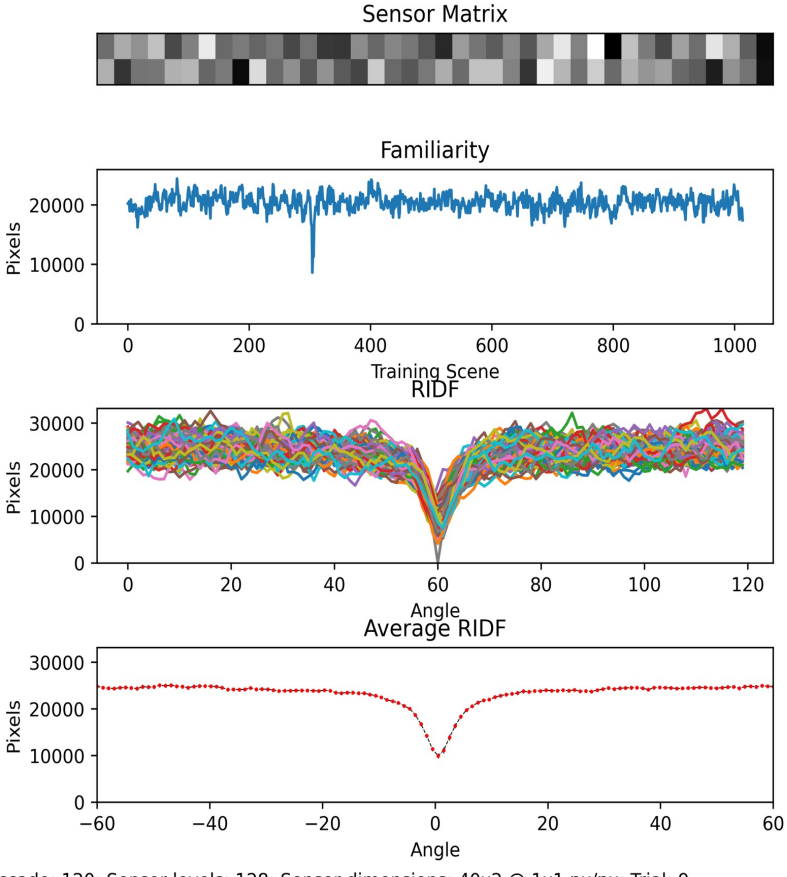




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 61.73; RMSD/dist: 0.154; TD: 7029; p90: 12; p50: 8; complete: 0

100%

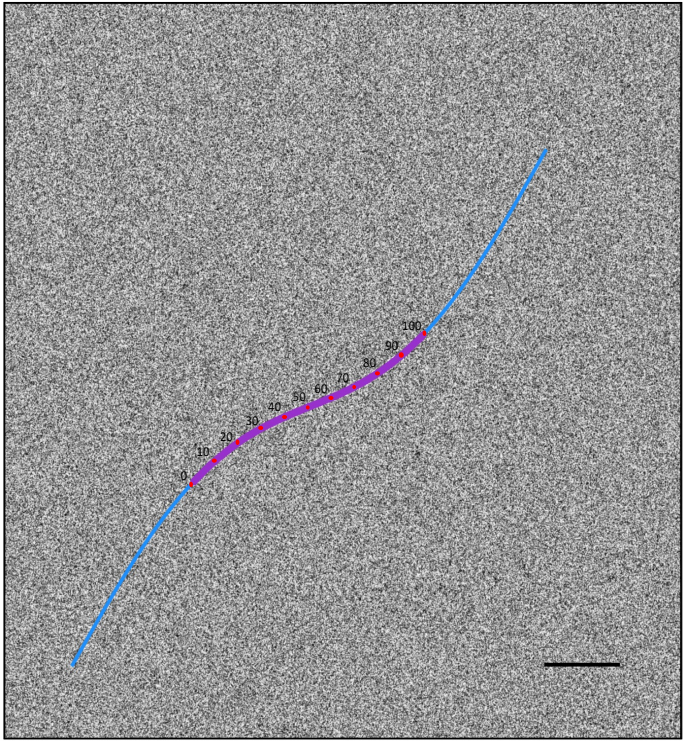


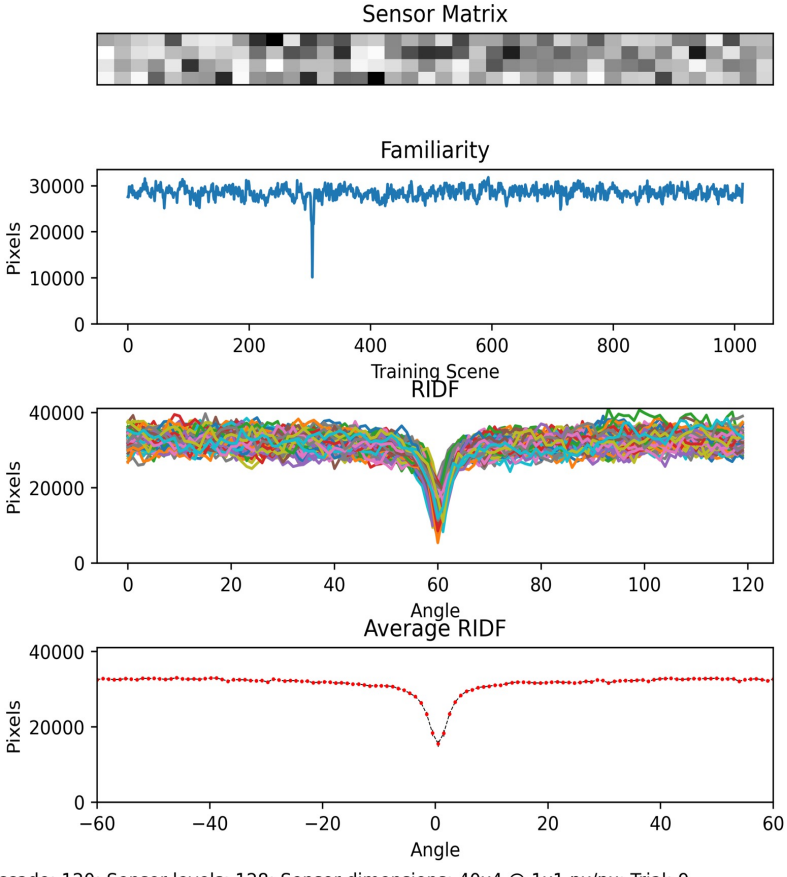




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 52.44; RMSD/dist: 0.131; TD: 10519; p90: 10; p50: 4; complete: 0

100%

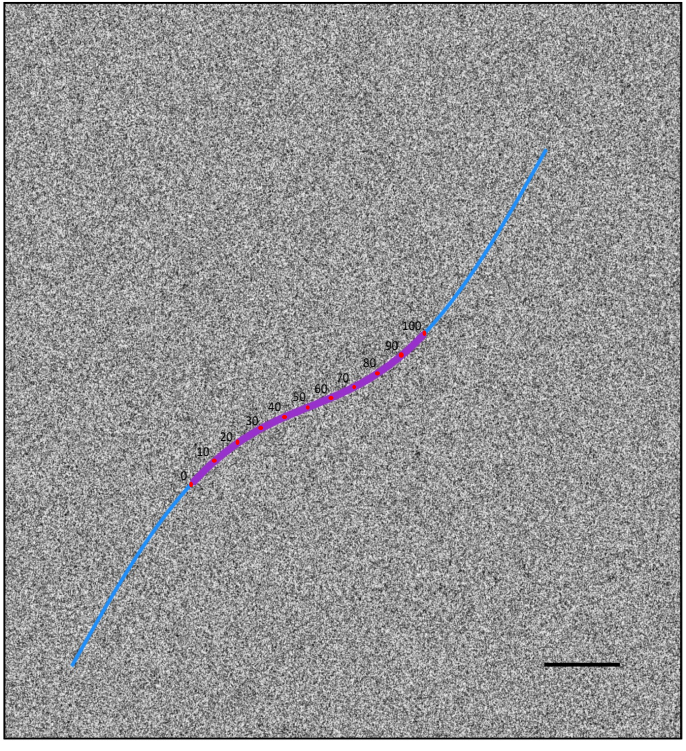


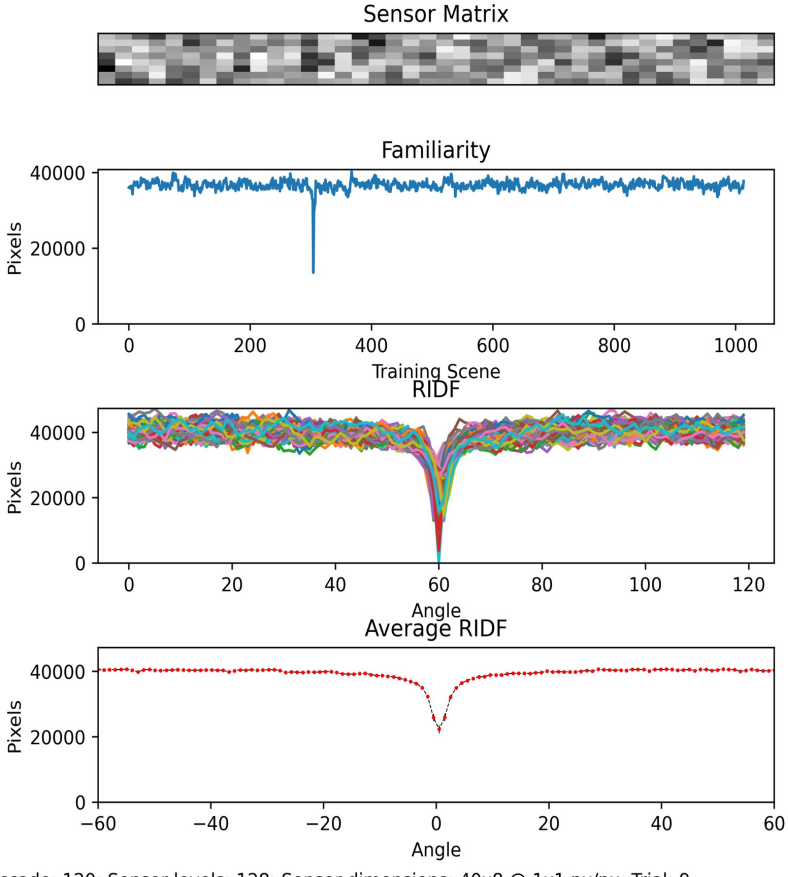




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 53.74; RMSD/dist: 0.134; TD: 12951; p90: 6; p50: 4; complete: 0

100%

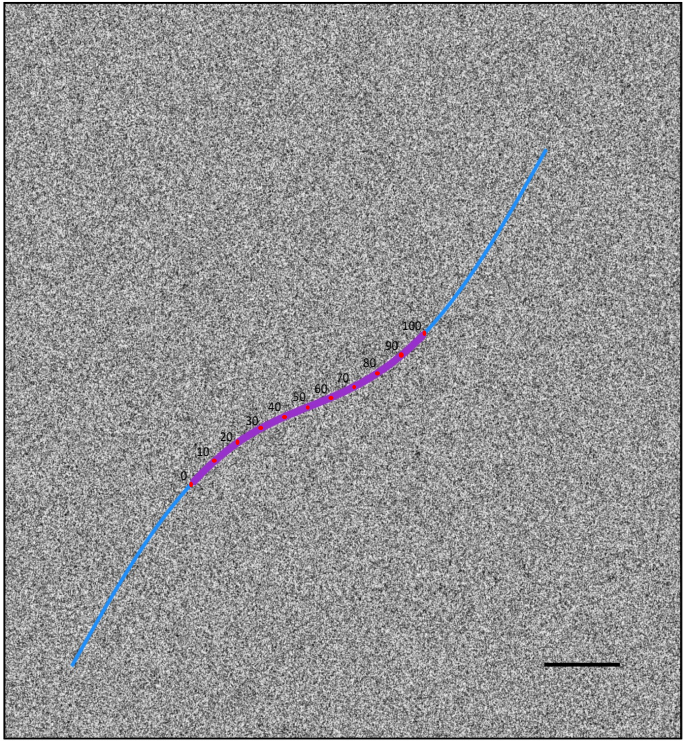


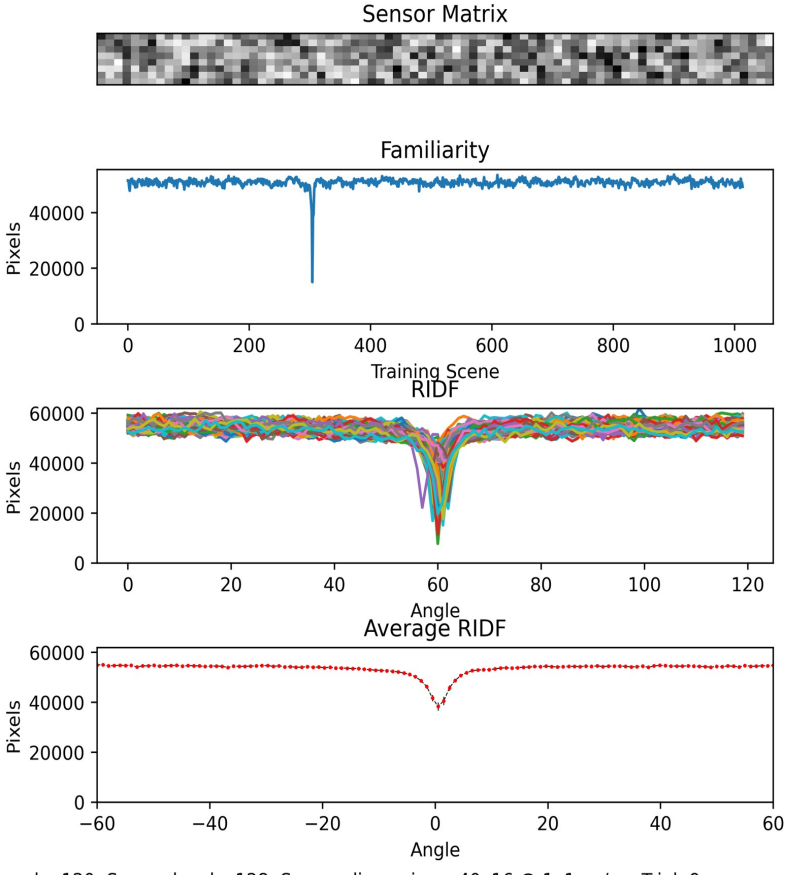




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 48.80; RMSD/dist: 0.122; TD: 14130; p90: 6; p50: 4; complete: 0

100%

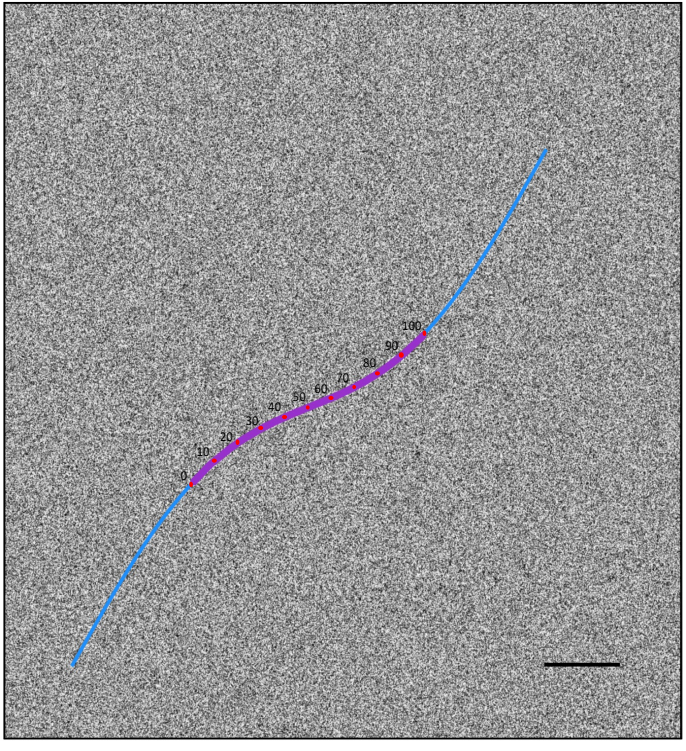


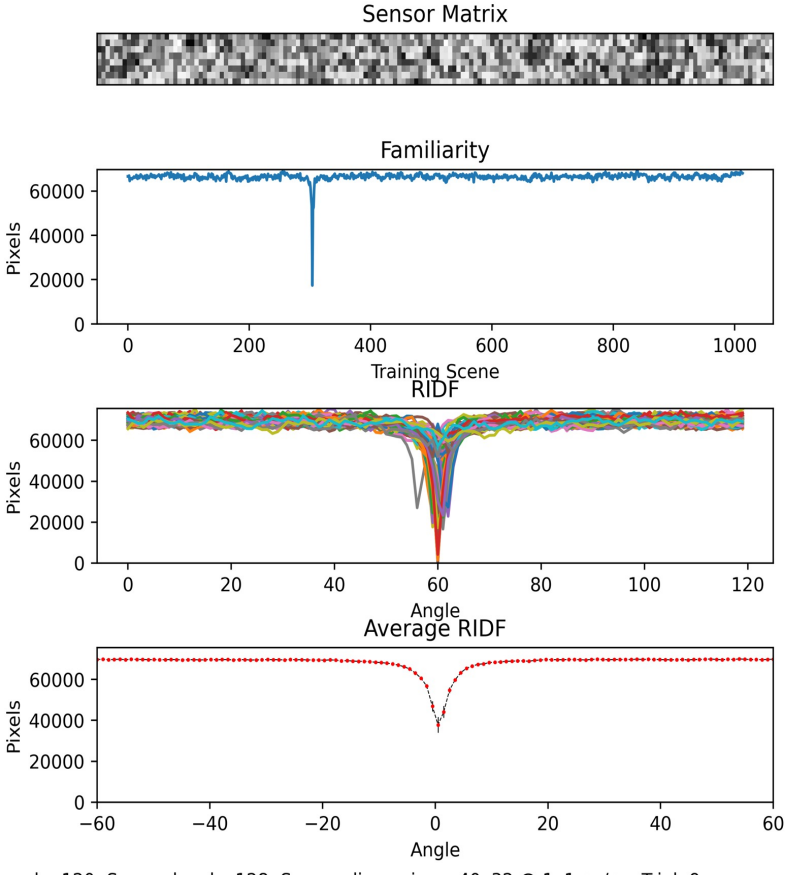




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 84.52; RMSD/dist: 0.211; TD: 12350; p90: 8; p50: 4; complete: 0

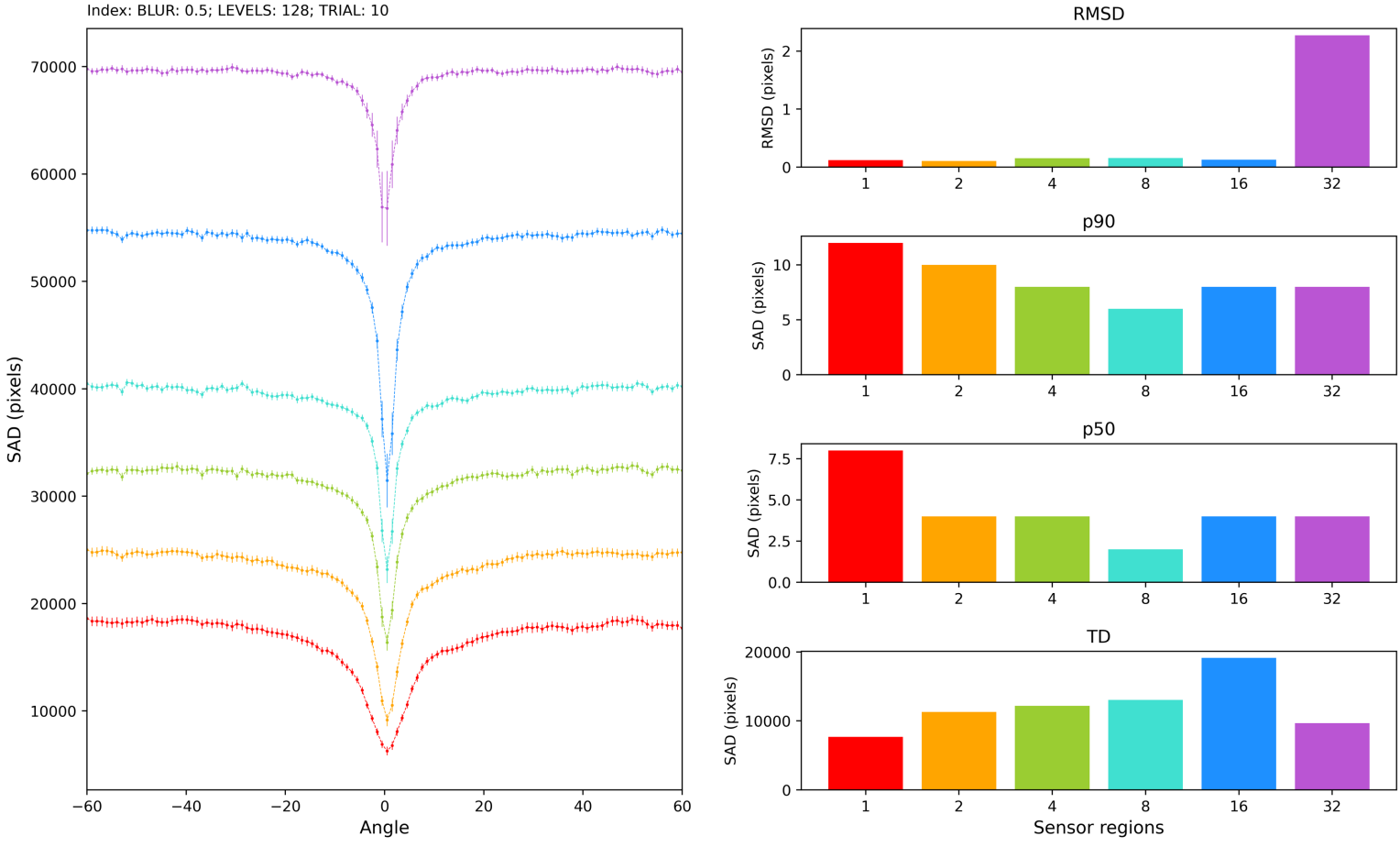
100%



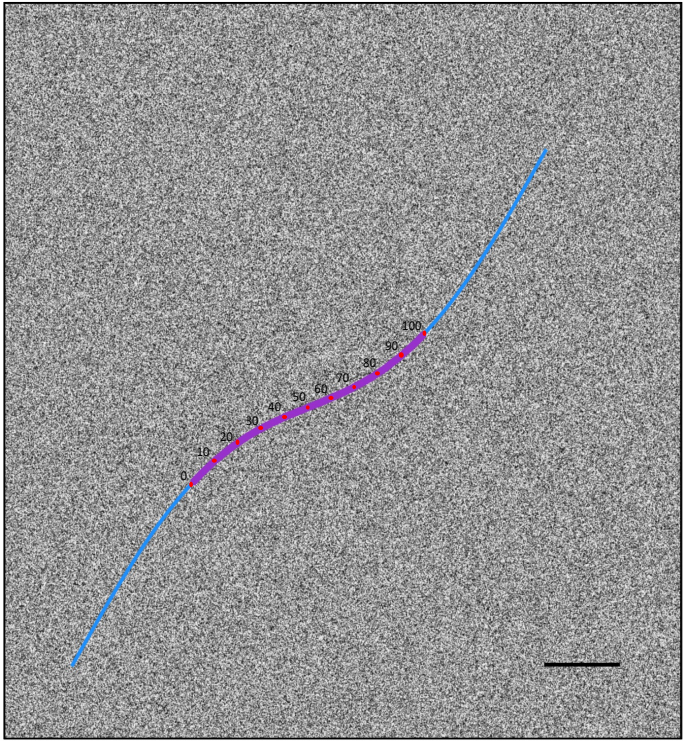



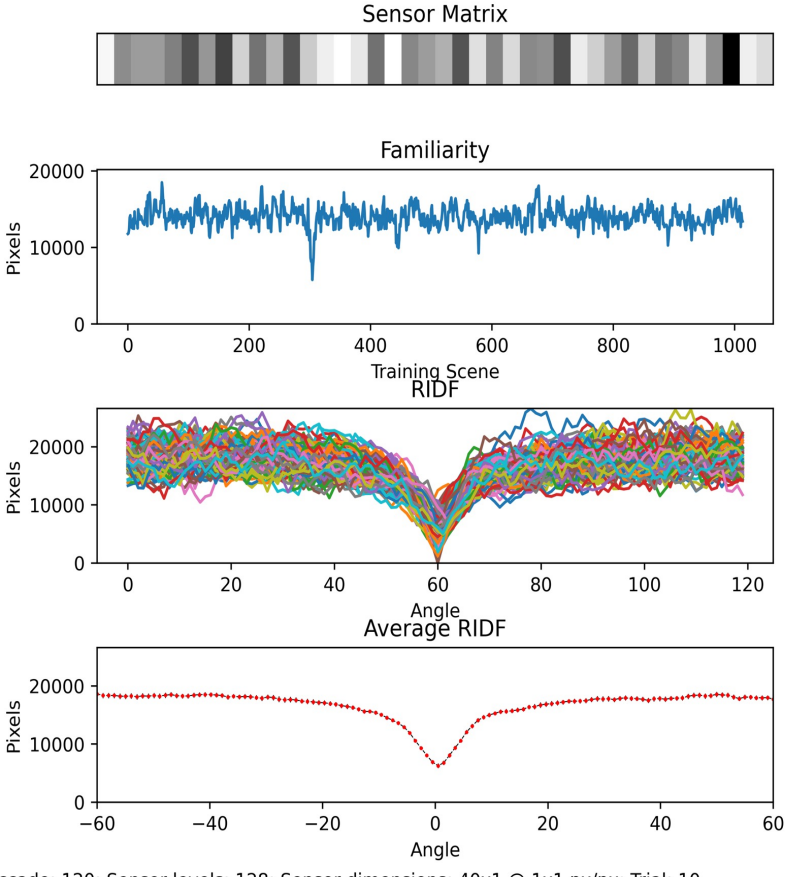

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 42.18; RMSD/dist: 0.105; TD: 28407; p90: 8; p50: 4; complete: 0


Index: BLUR: 0.5; LEVELS: 128; TRIAL: 10
SAD (pixels)
70000
60000
50000
40000
30000
20000
10000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
2
1
0
1
2
4
8
16
32
p90
SAD (pixels)
10
5
0
1
2
4
8
16
32
p50
SAD (pixels)
7.5
5.0
2.5
0.0
1
2
4
8
16
32
TD
SAD (pixels)
20000
10000
0
1
2
4
8
16
32
Sensor regions

100%

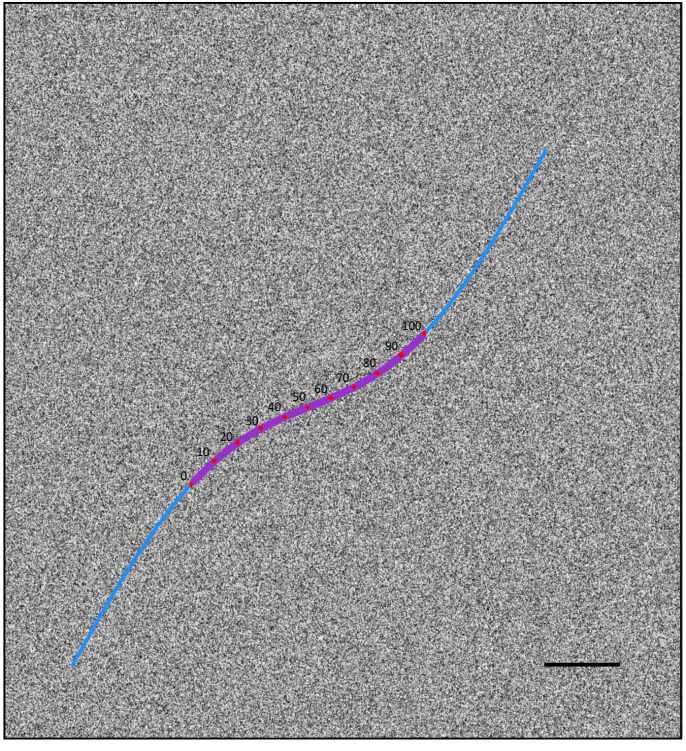


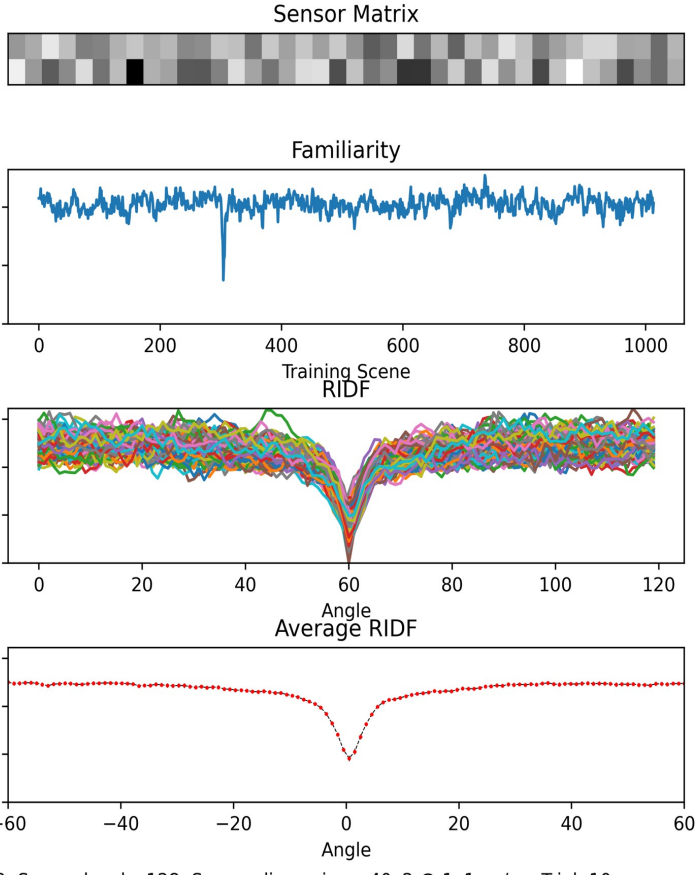




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 47.29; RMSD/dist: 0.118; TD: 7698; p90: 12; p50: 8; complete: 0

100%

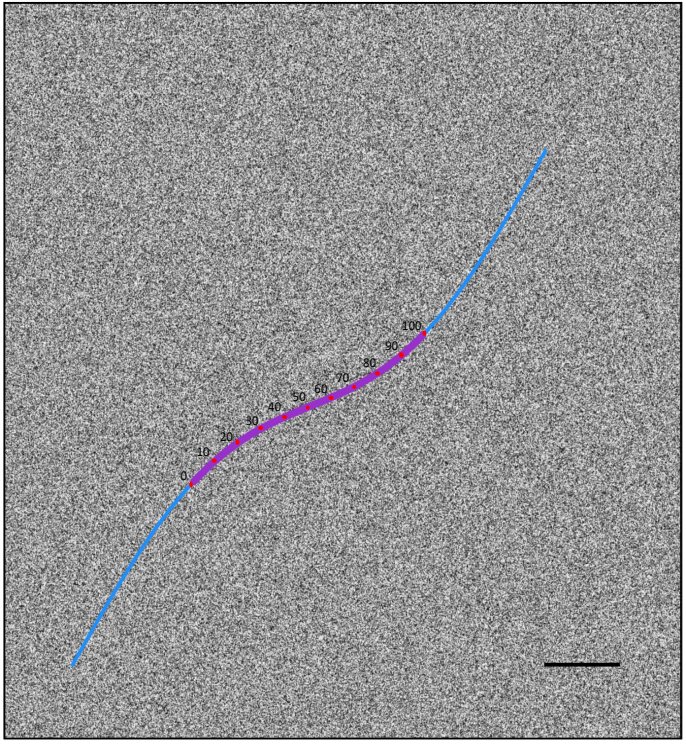


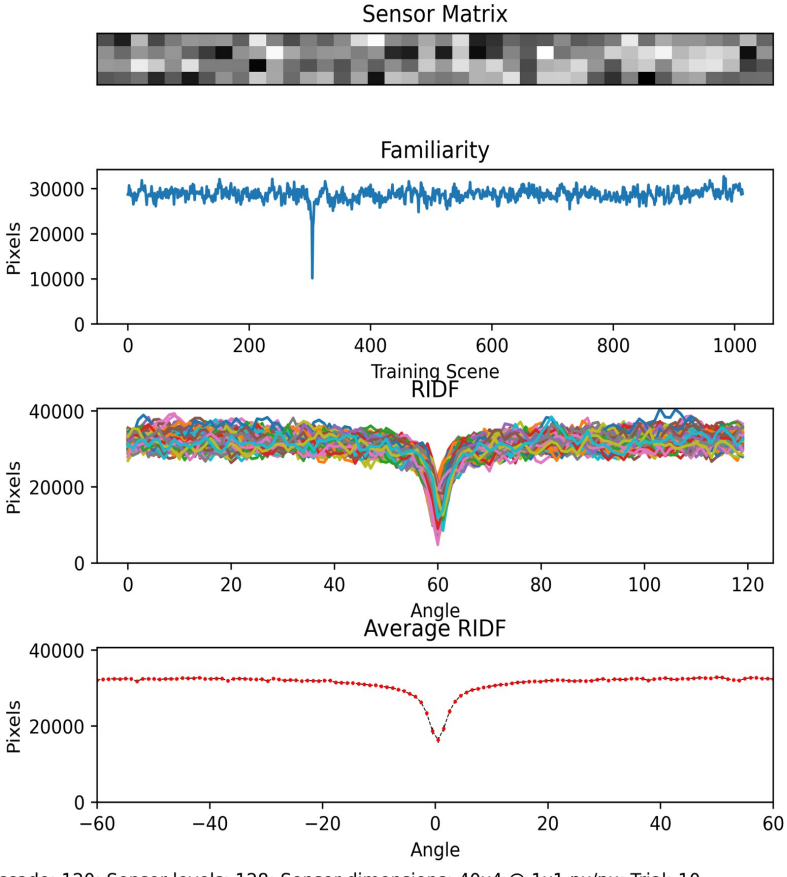




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 41.25; RMSD/dist: 0.103; TD: 11290; p90: 10; p50: 4; complete: 0

100%

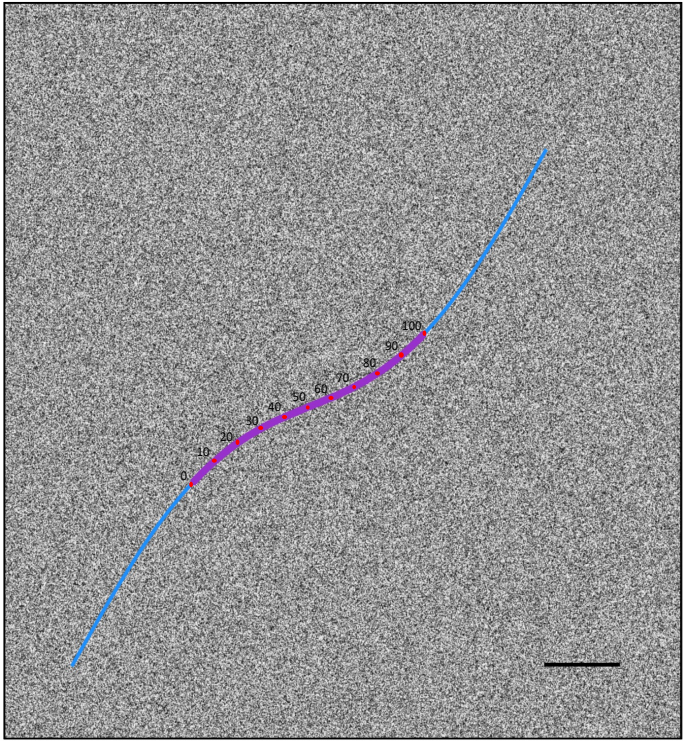


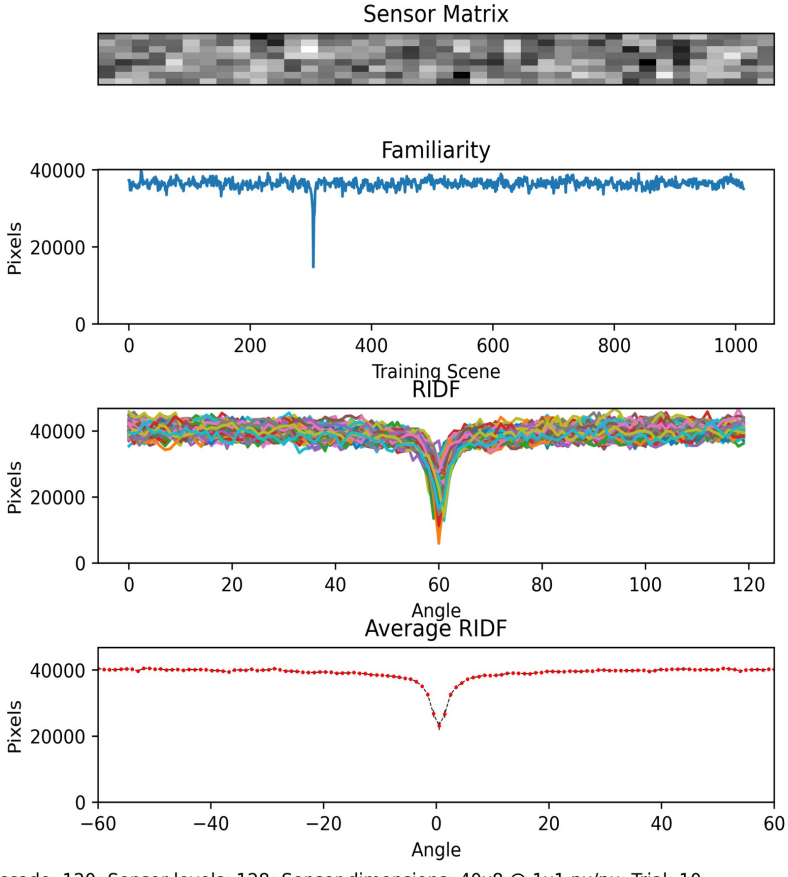




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 61.30; RMSD/dist: 0.153; TD: 12182; p90: 8; p50: 4; complete: 0

100%

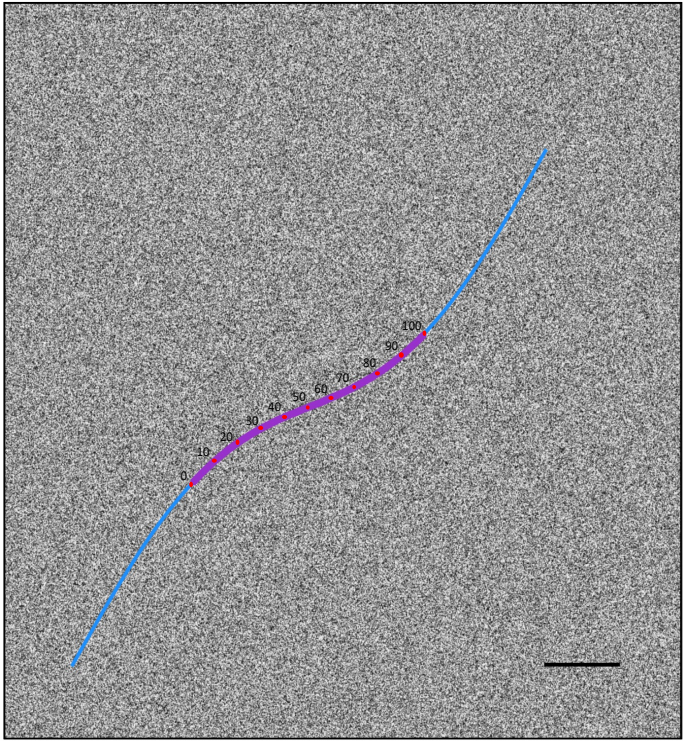


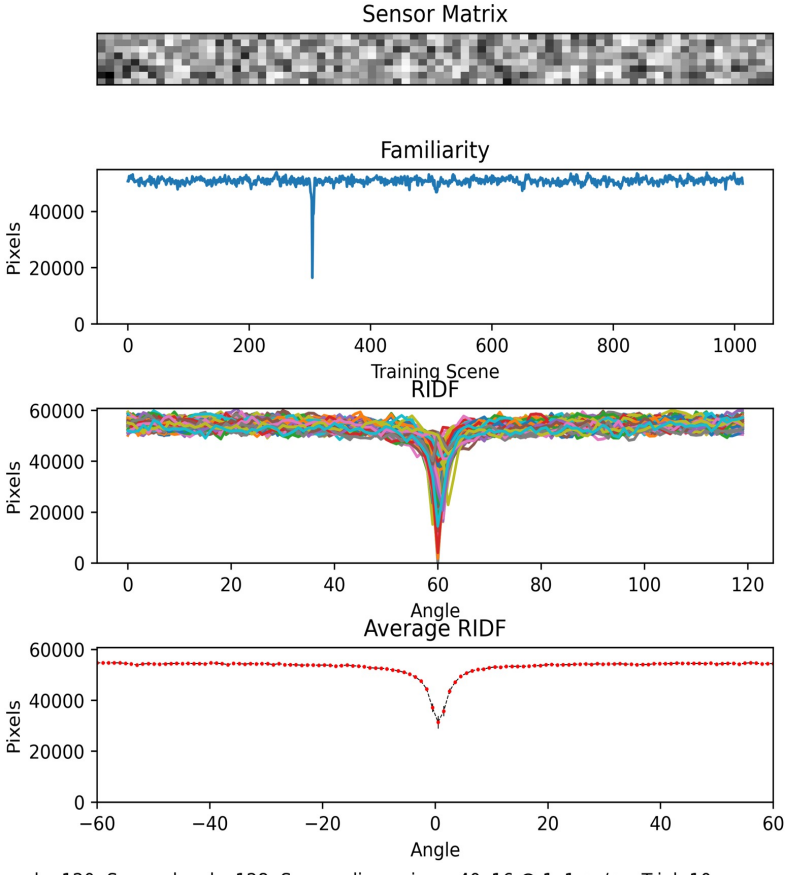




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 62.12; RMSD/dist: 0.155; TD: 13059; p90: 6; p50: 2; complete: 0

100%

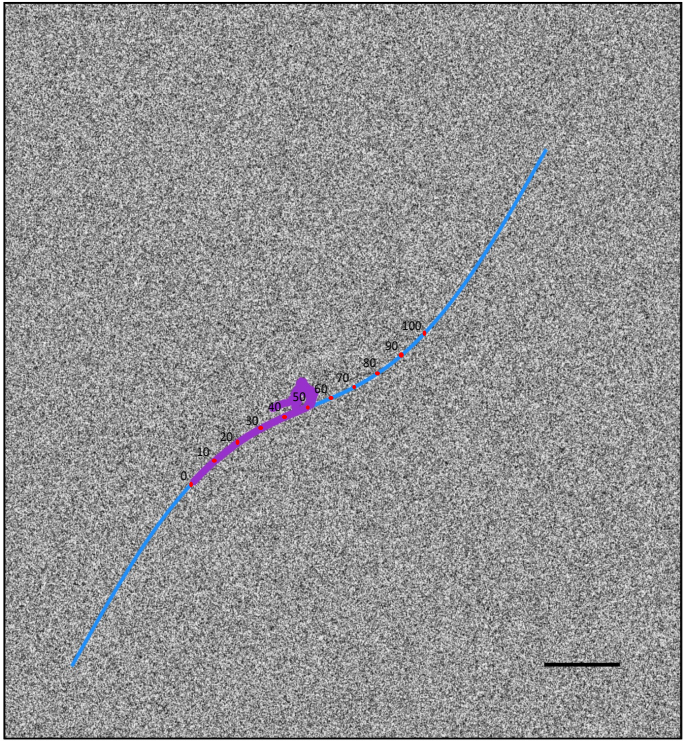


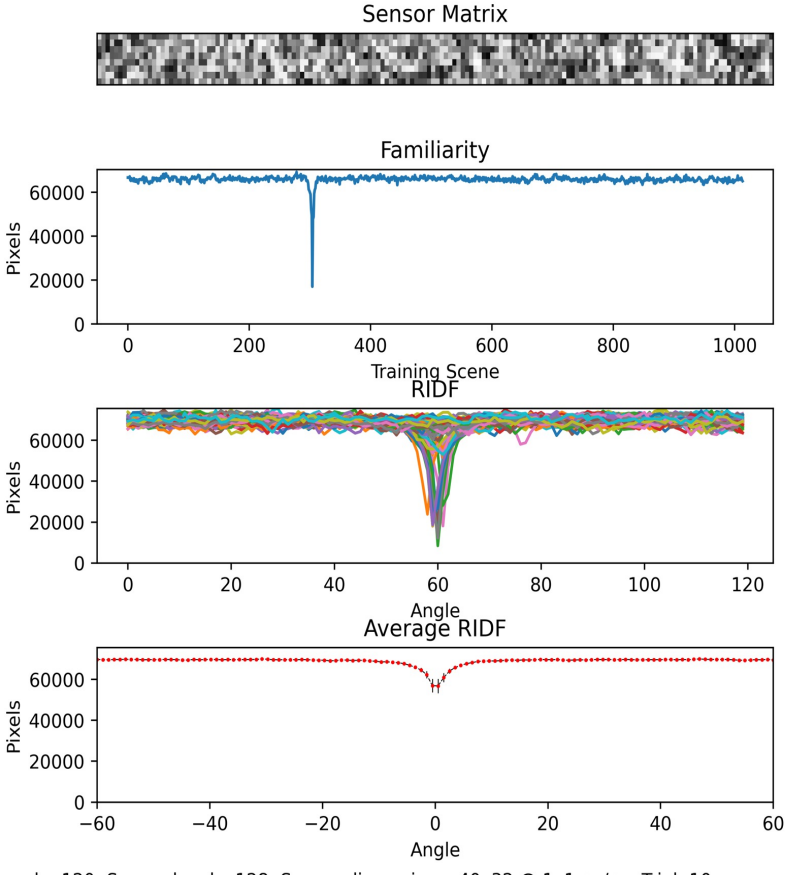




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 51.26; RMSD/dist: 0.128; TD: 19133; p90: 8; p50: 4; complete: 0

50%




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 0; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 128; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 909.08; RMSD/dist: 2.273; TD: 9681; p90: 8; p50: 4; complete: 0