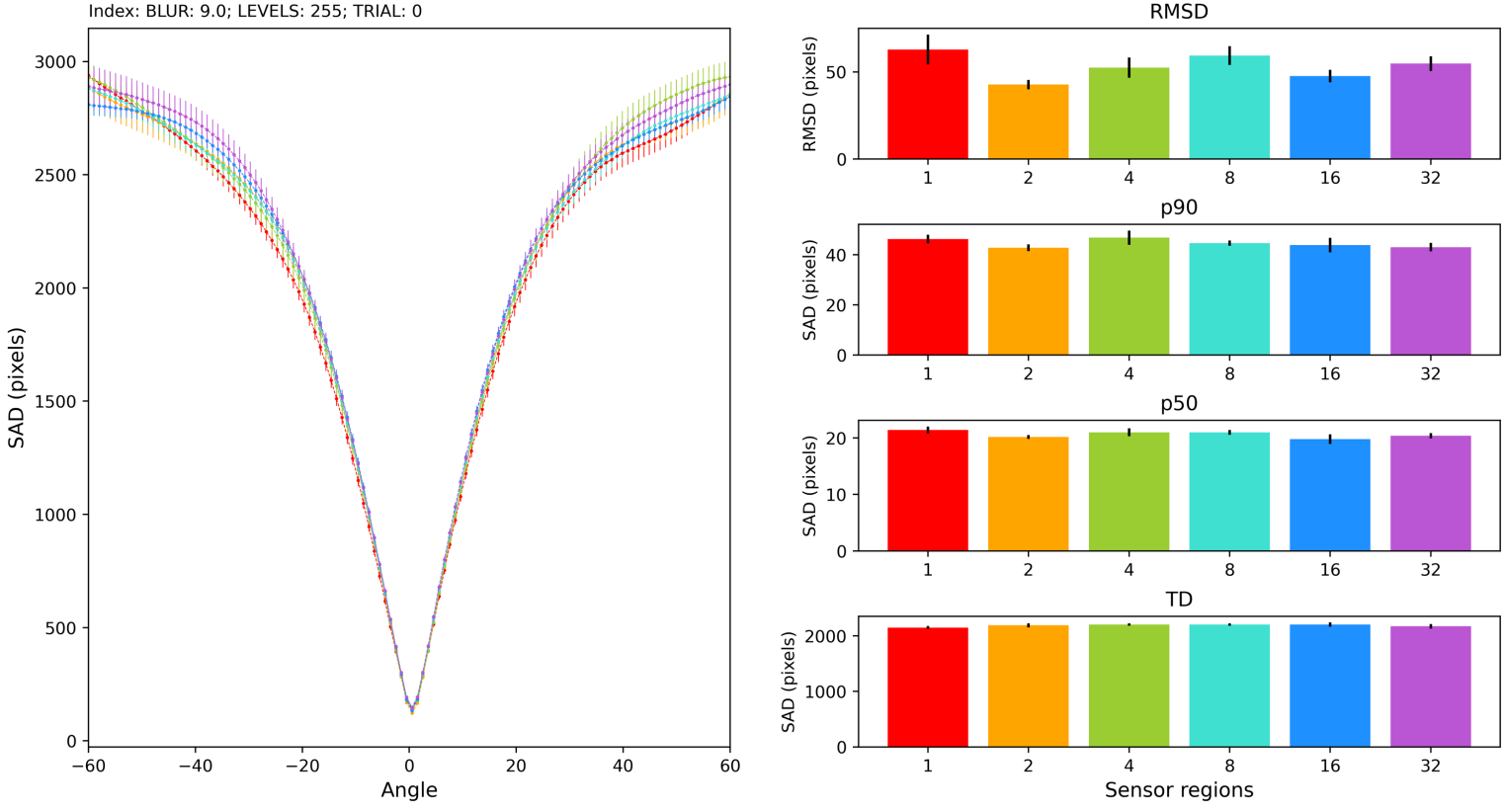
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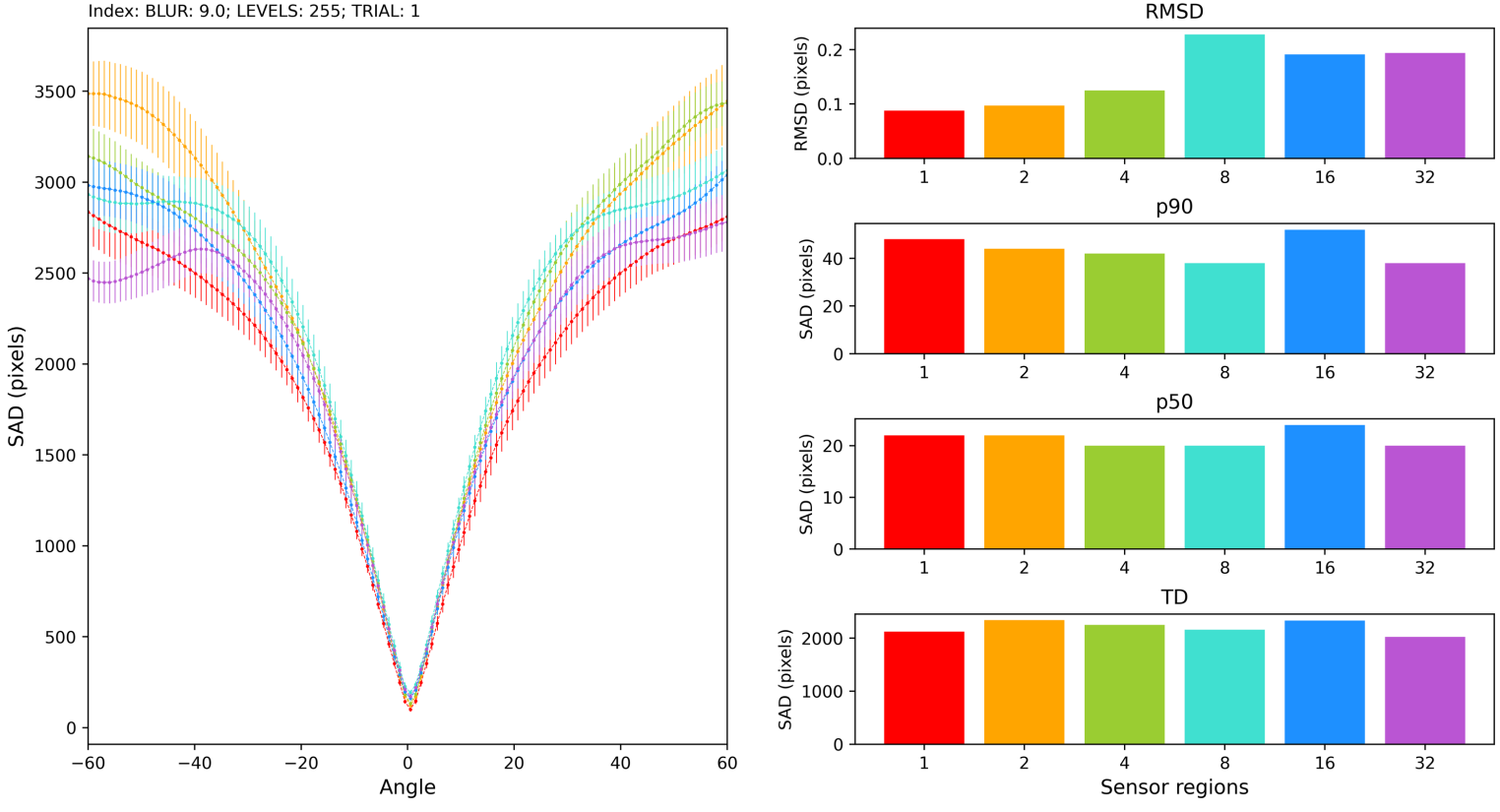
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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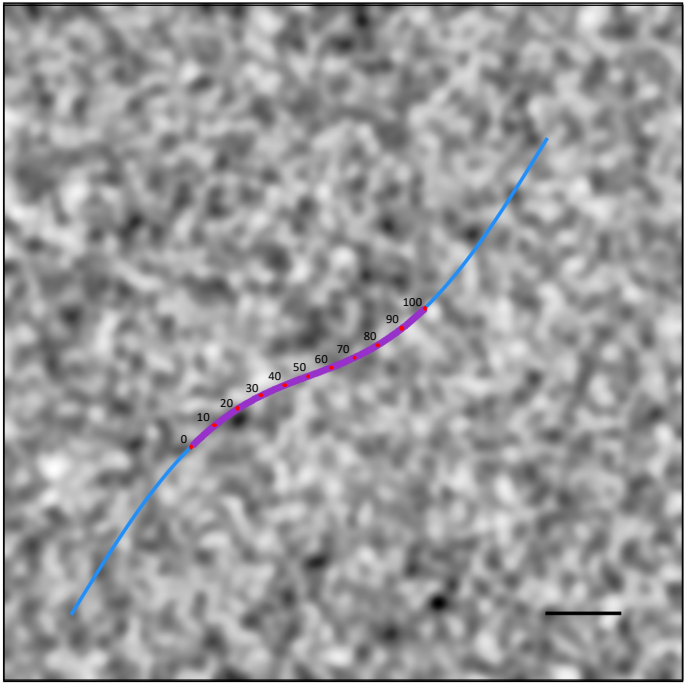
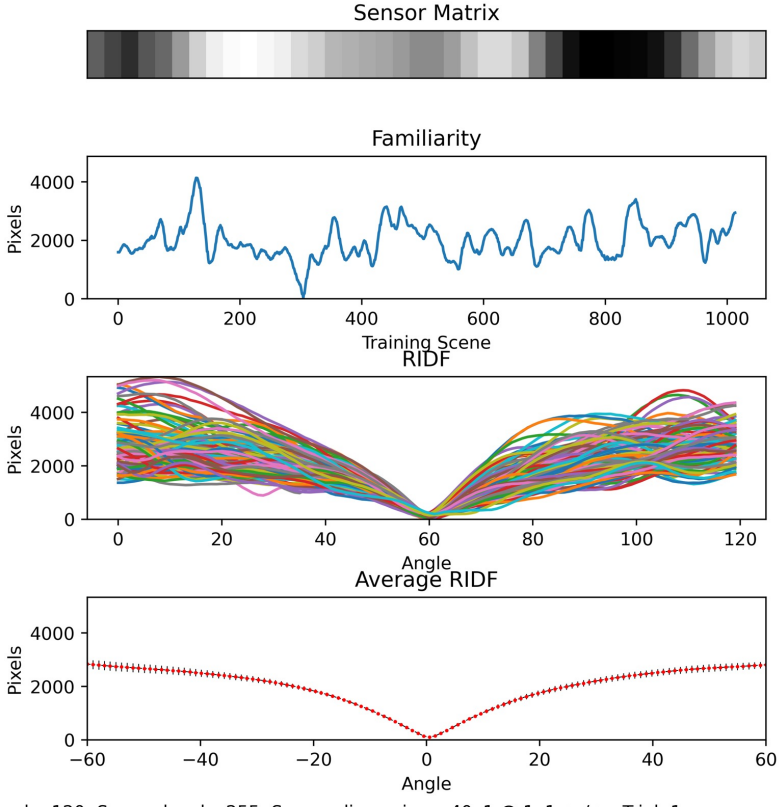
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

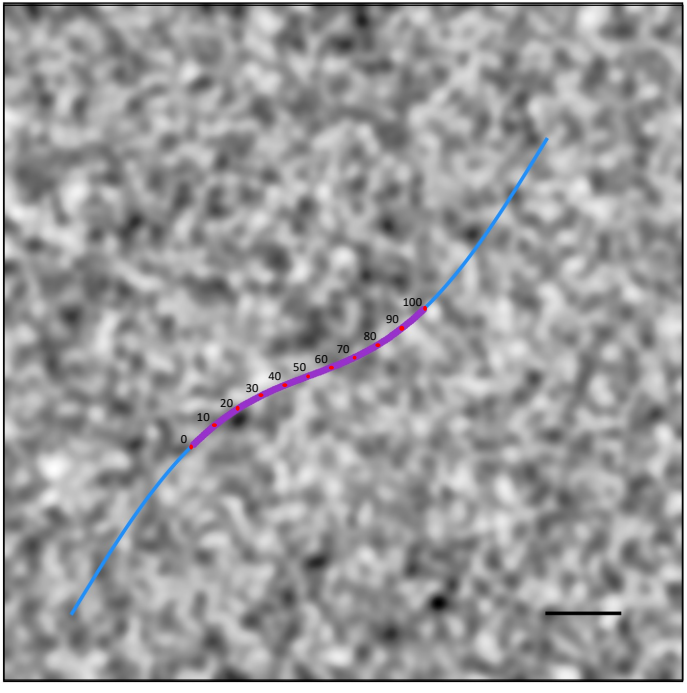
100%

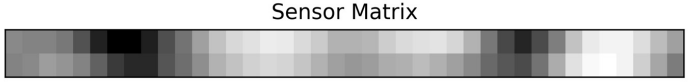


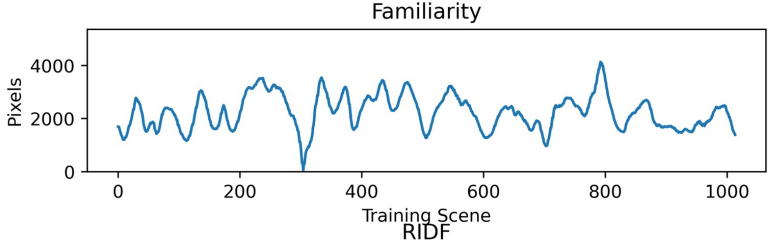


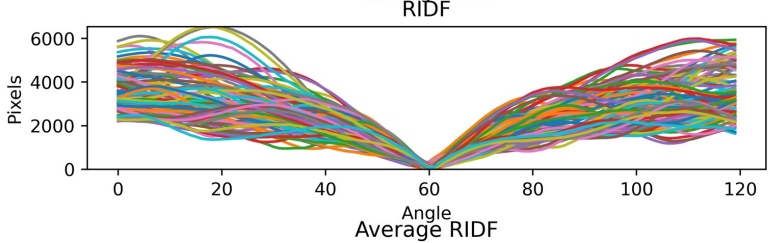
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 35.11; RMSD/dist: 0.088; TD: 2123; p90: 48; p50: 22; complete: 0

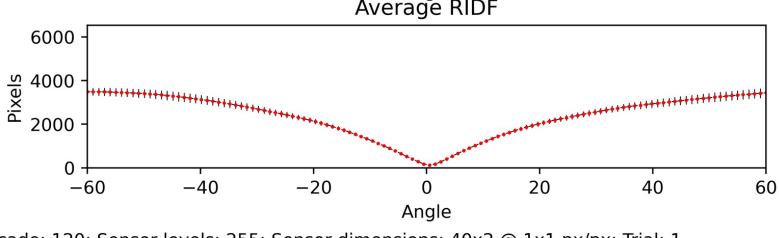
100%











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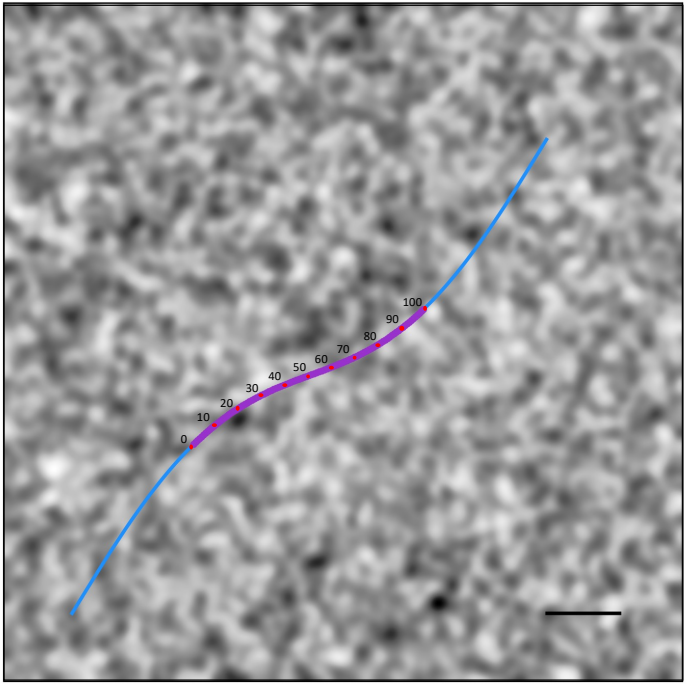
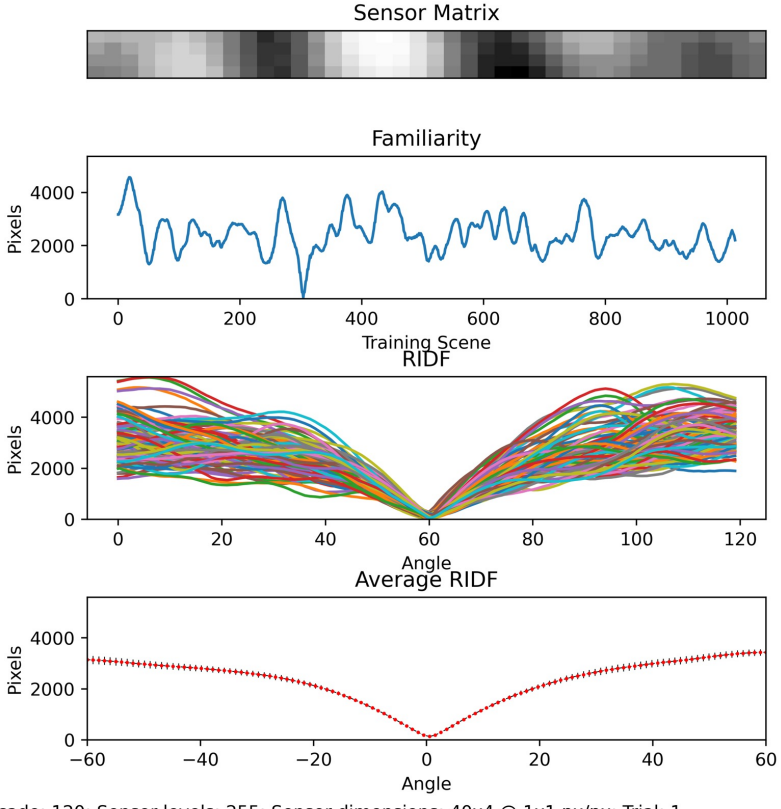
Navigation stats: RMSD error: 38.62; RMSD/dist: 0.097; TD: 2336; p90: 44; p50: 22; complete: 0

100%





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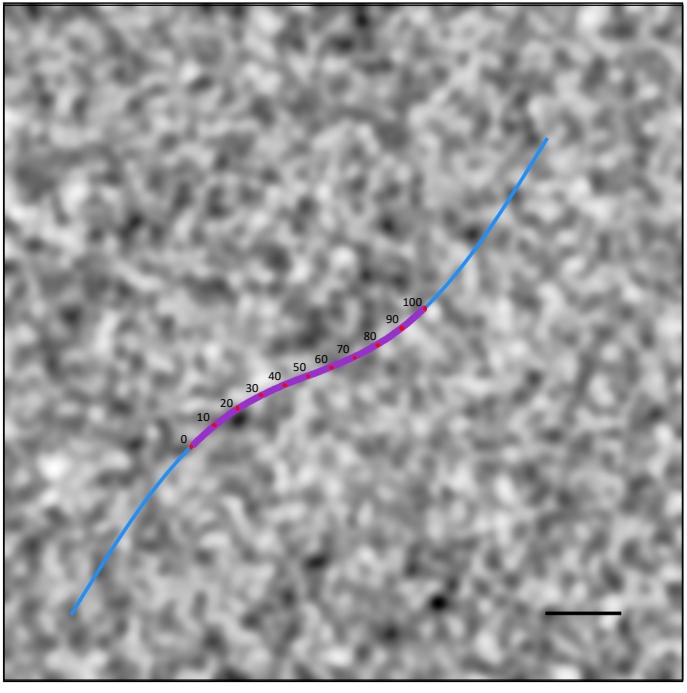
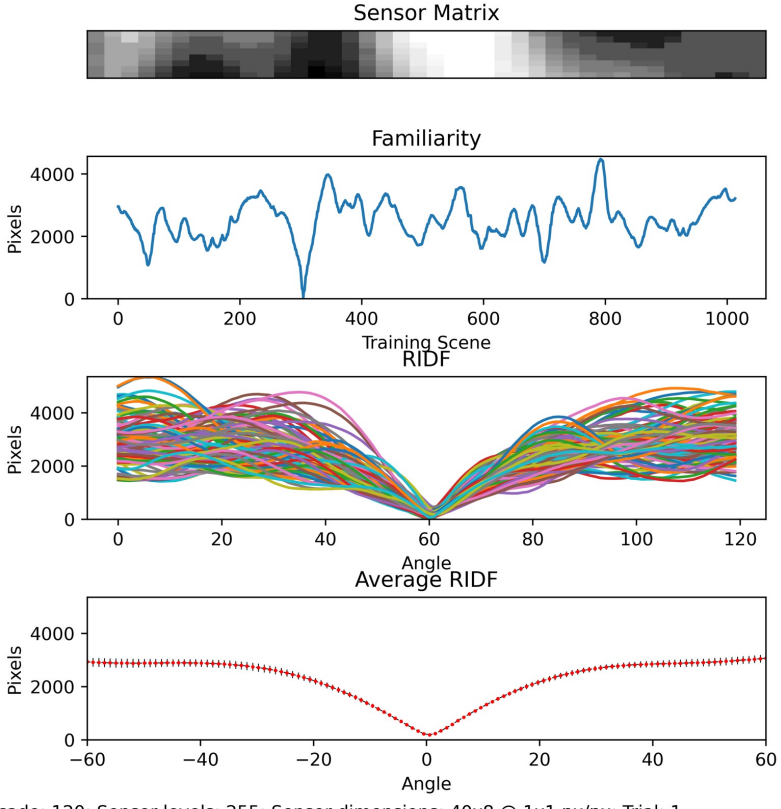
Navigation stats: RMSD error: 50.03; RMSD/dist: 0.125; TD: 2248; p90: 42; p50: 20; complete: 0

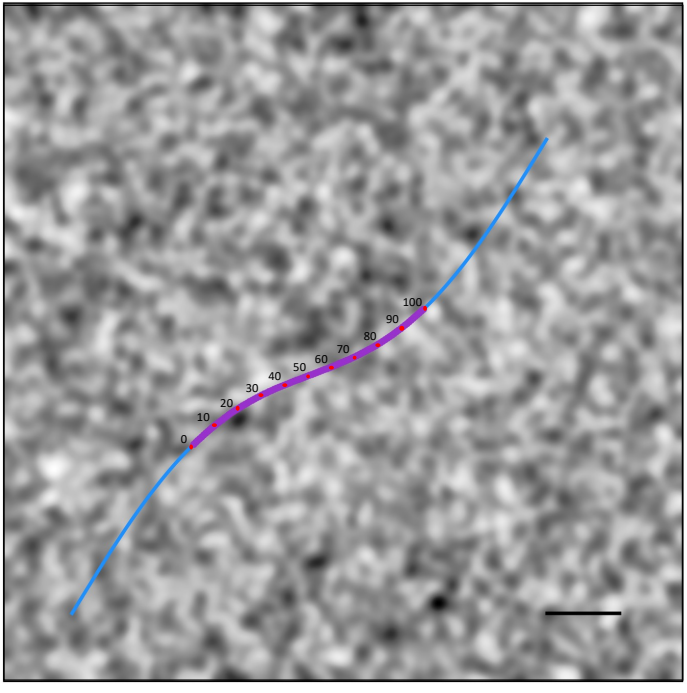
100%

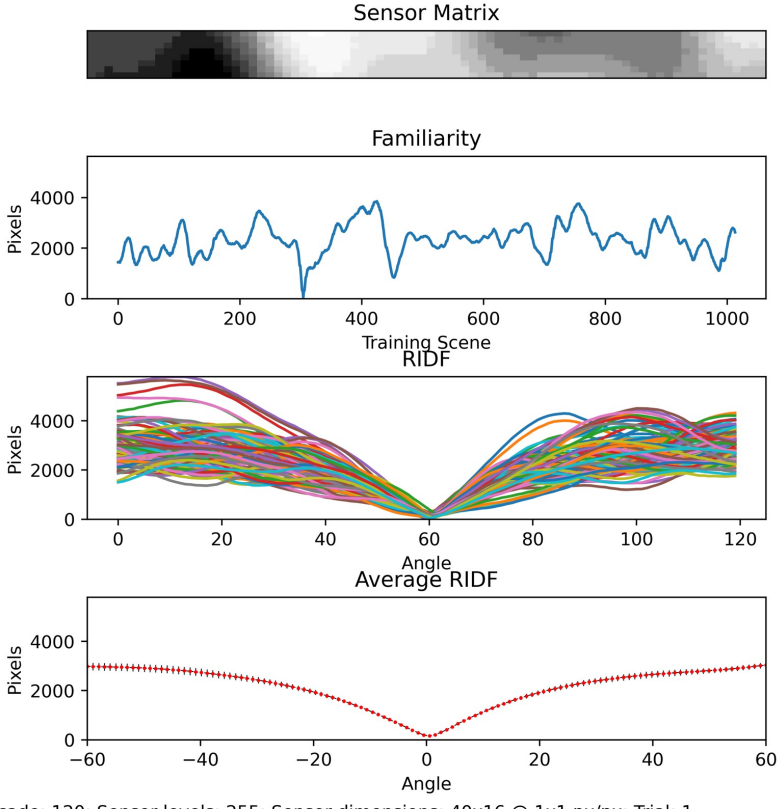




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 91.24; RMSD/dist: 0.228; TD: 2155; p90: 38; p50: 20; complete: 0

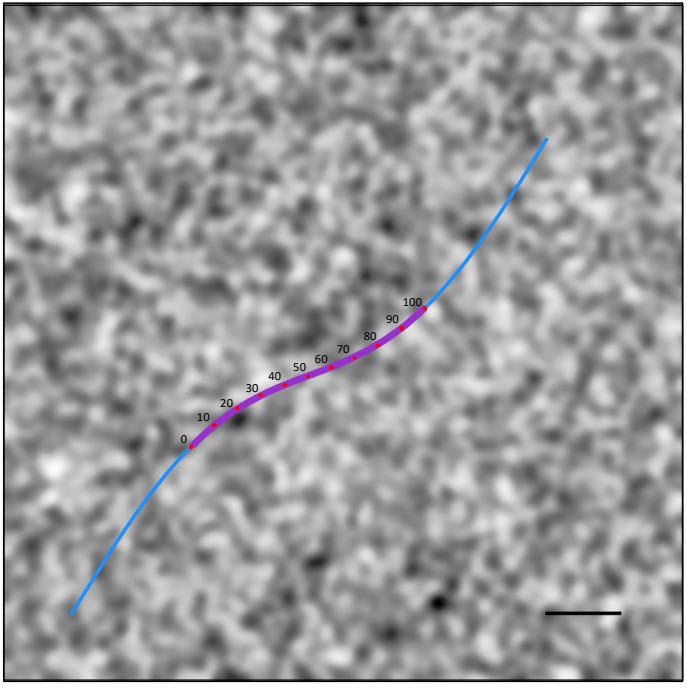
100%

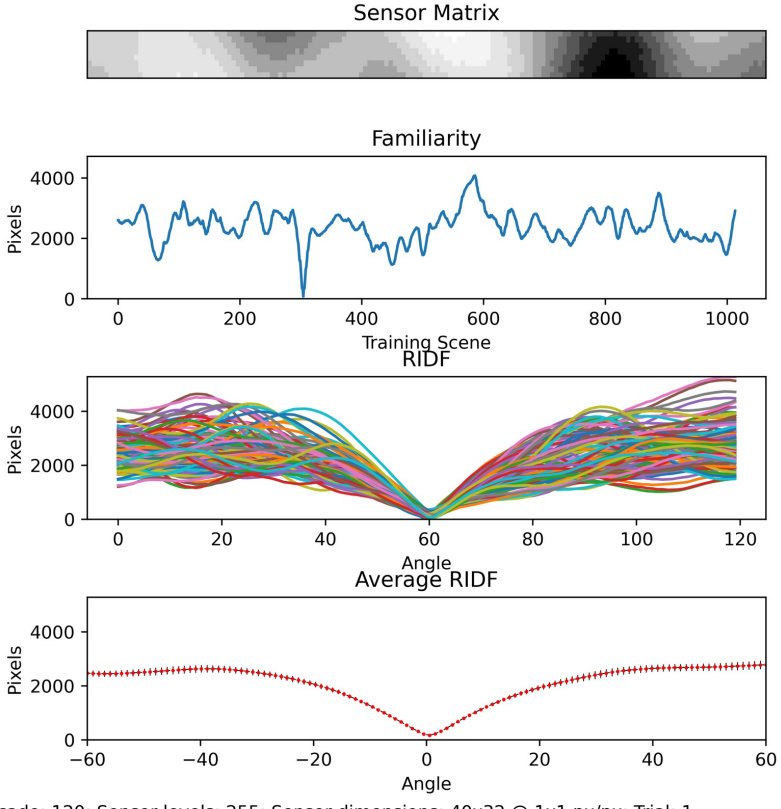




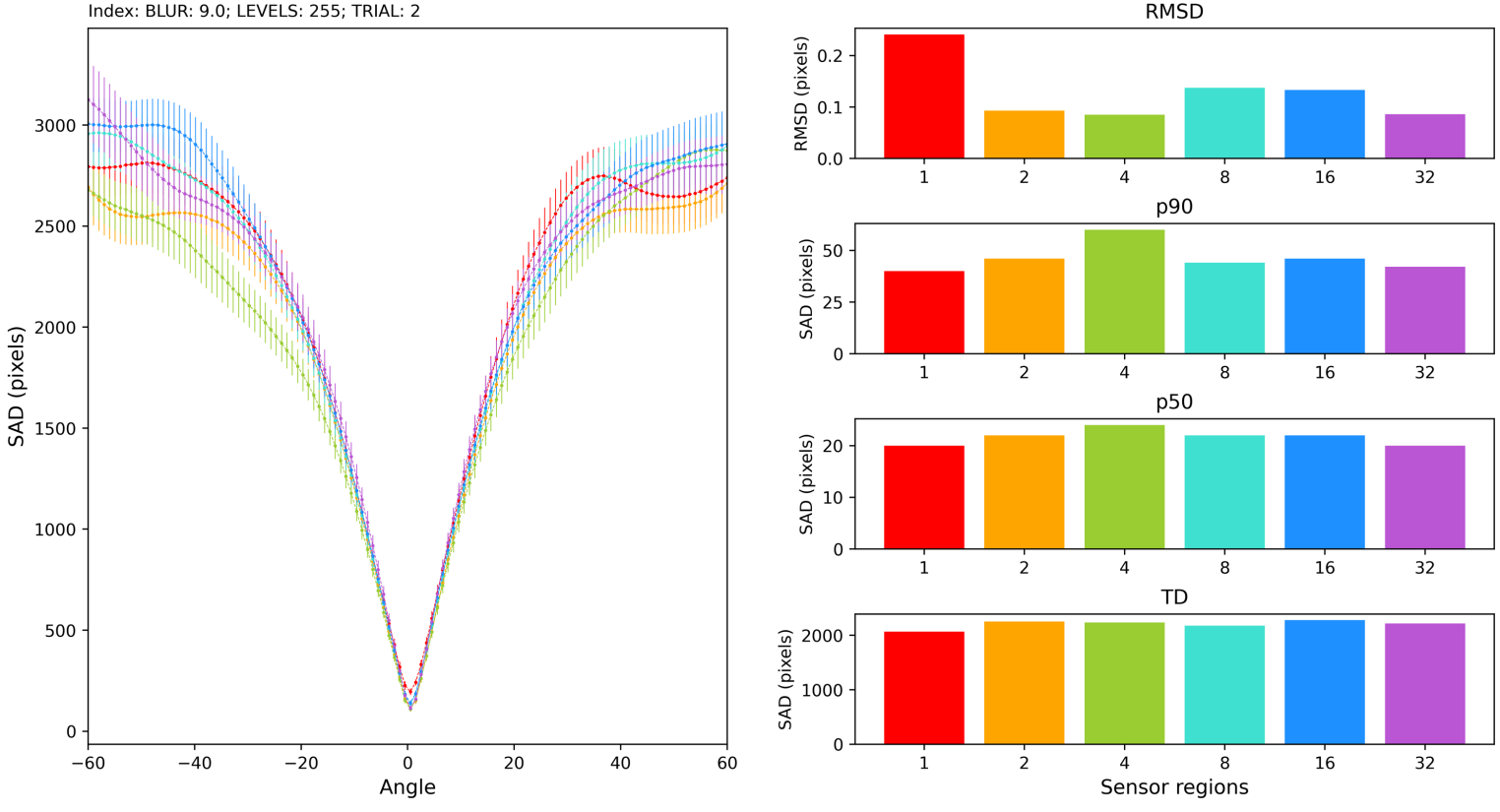
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 76.50; RMSD/dist: 0.191; TD: 2327; p90: 52; p50: 24; complete: 0

100%

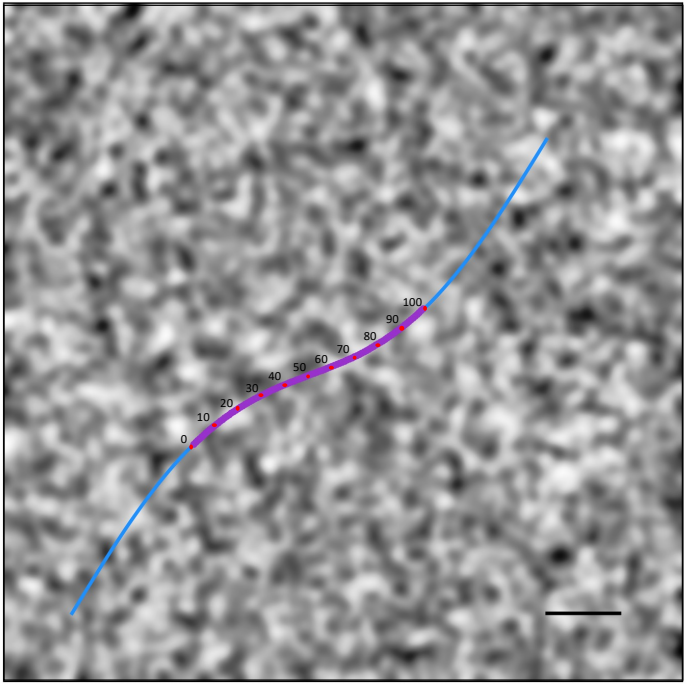


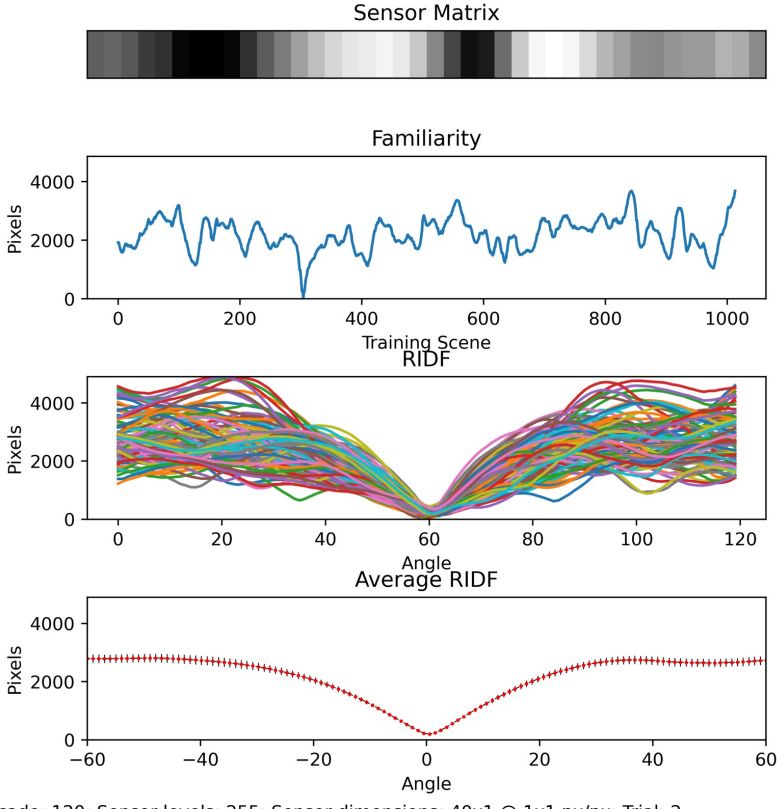


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1
Navigation stats: RMSD error: 77.60; RMSD/dist: 0.194; TD: 2023; p90: 38; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 255; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%





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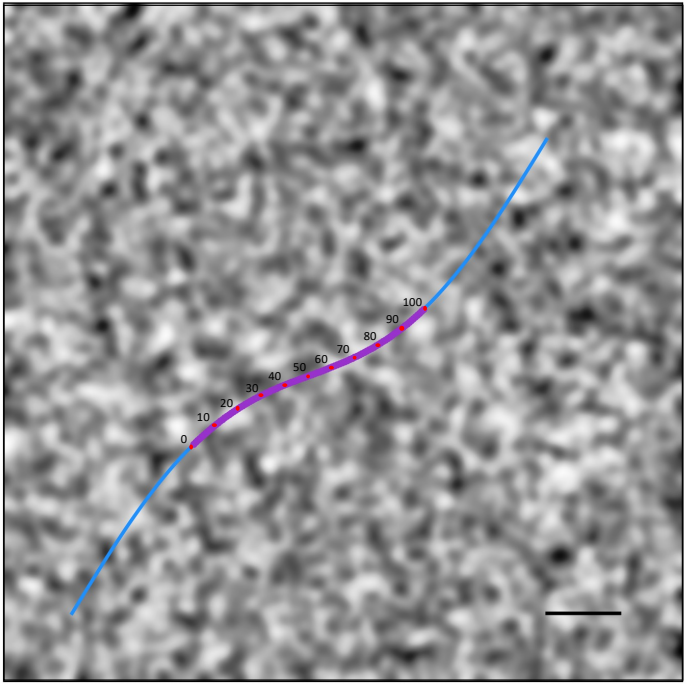
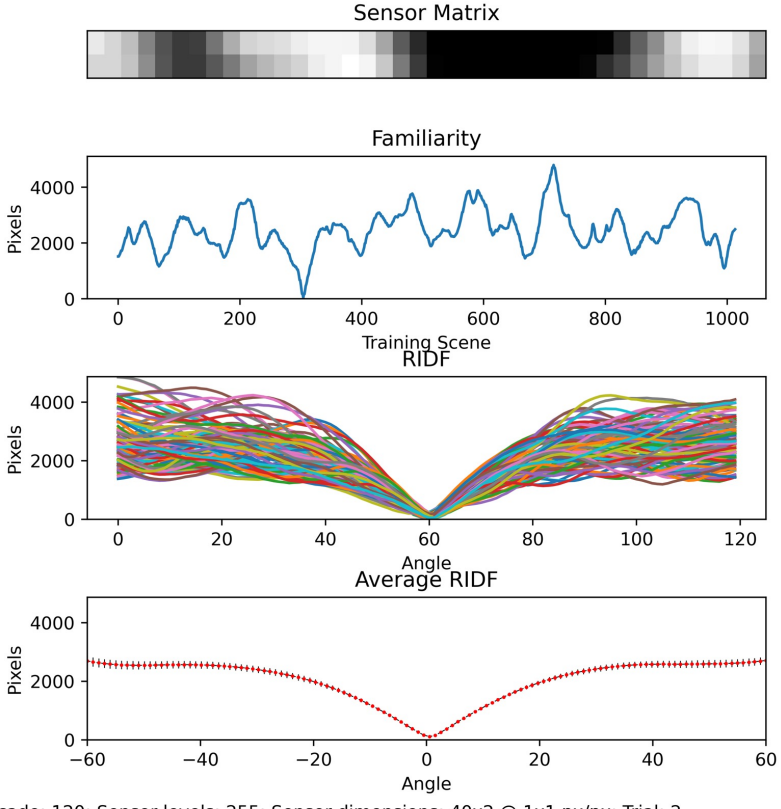
Navigation stats: RMSD error: 96.34; RMSD/dist: 0.241; TD: 2067; p90: 40; p50: 20; complete: 0

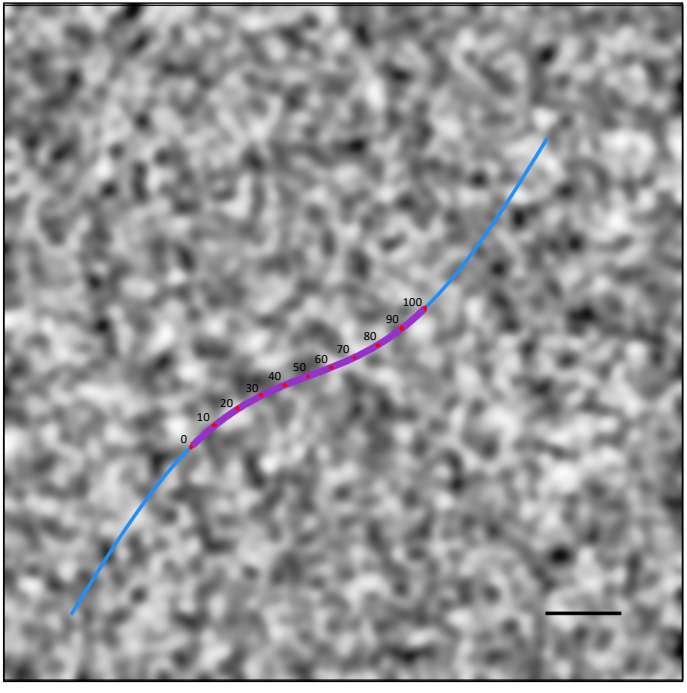
100%

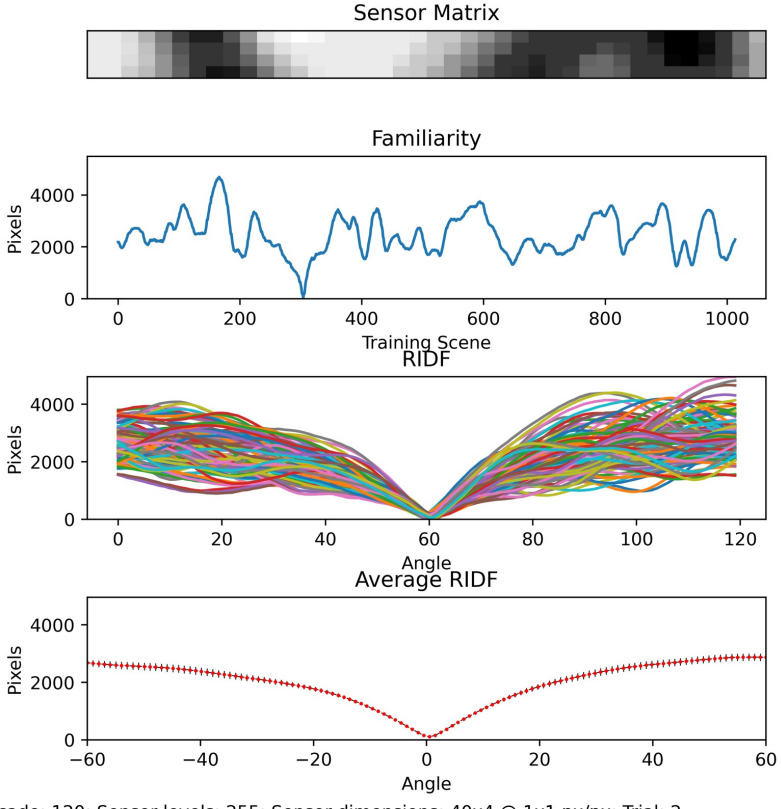




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 37.18; RMSD/dist: 0.093; TD: 2252; p90: 46; p50: 22; complete: 0

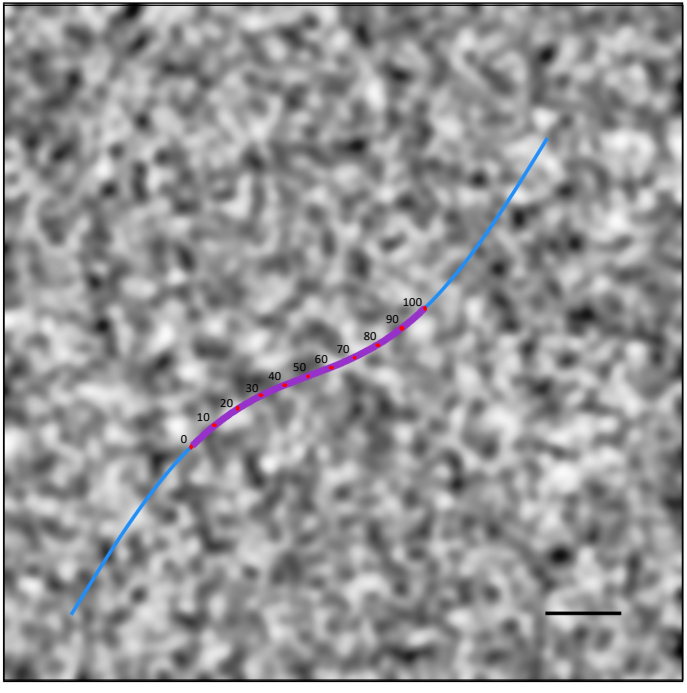
100%

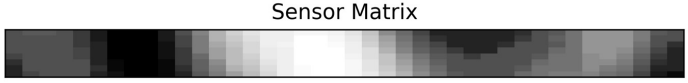


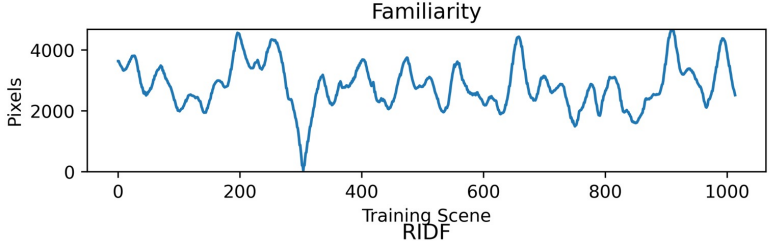


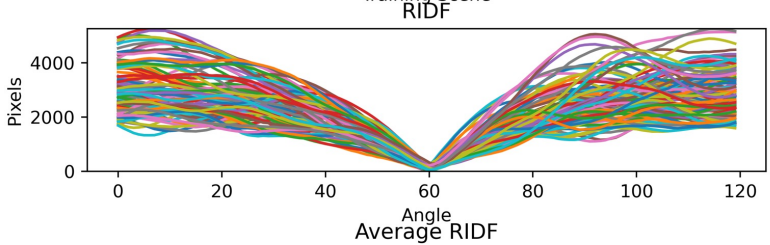
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 34.14; RMSD/dist: 0.085; TD: 2234; p90: 60; p50: 24; complete: 0

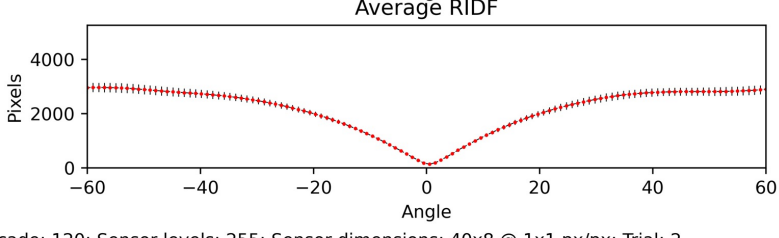
100%











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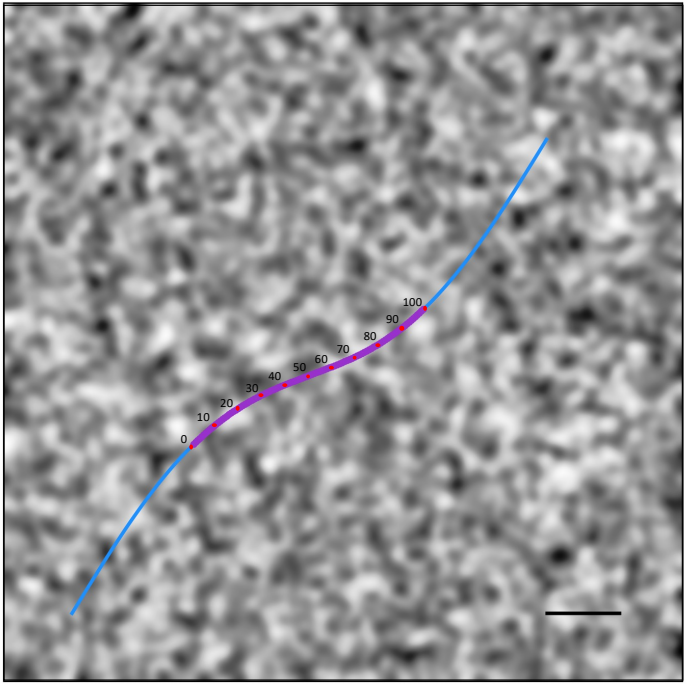
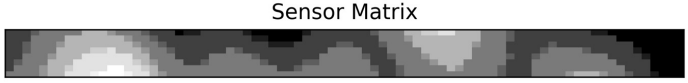
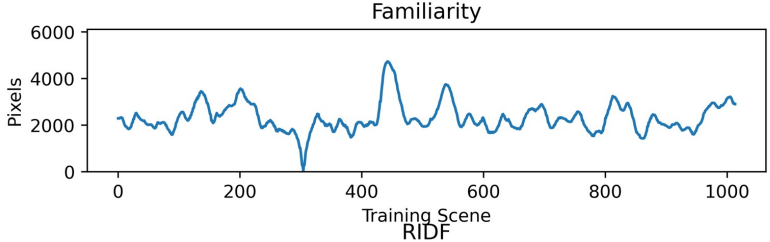
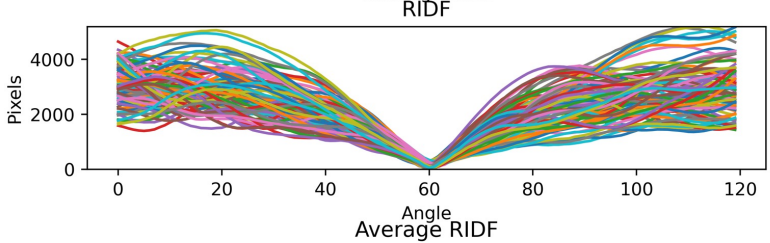
Navigation stats: RMSD error: 54.65; RMSD/dist: 0.137; TD: 2174; p90: 44; p50: 22; complete: 0

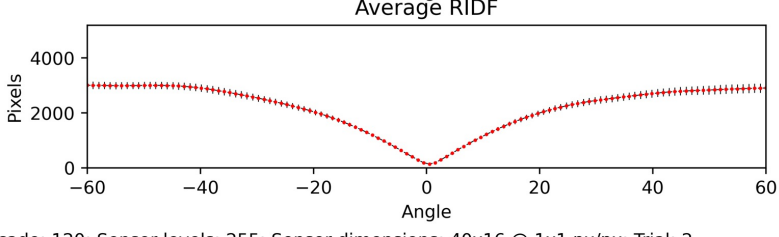
100%





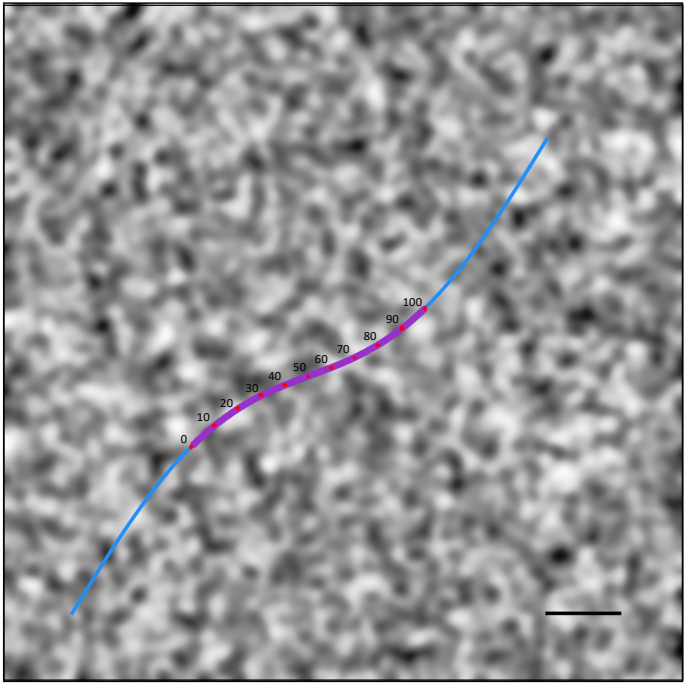


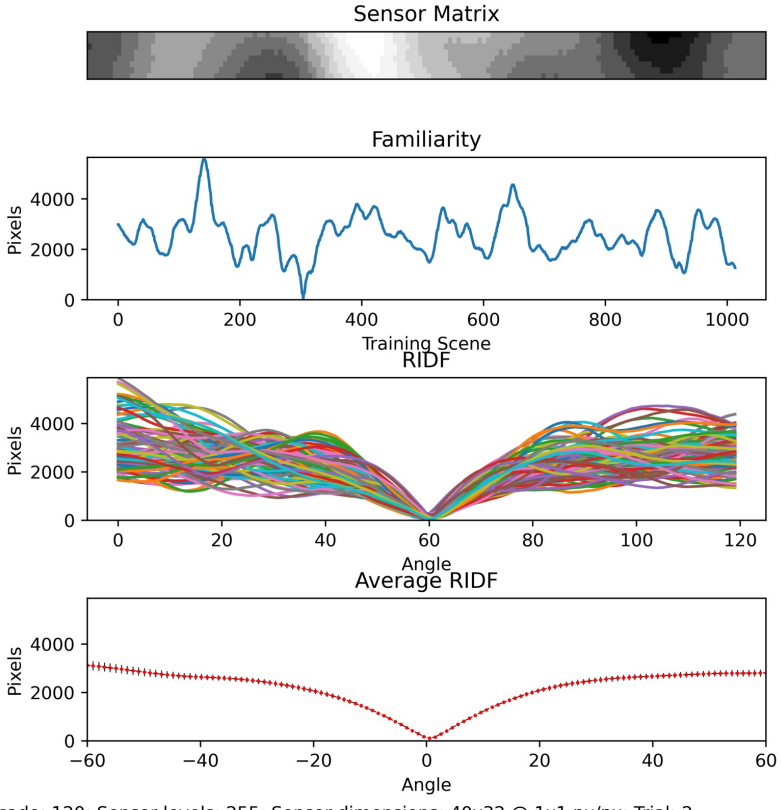




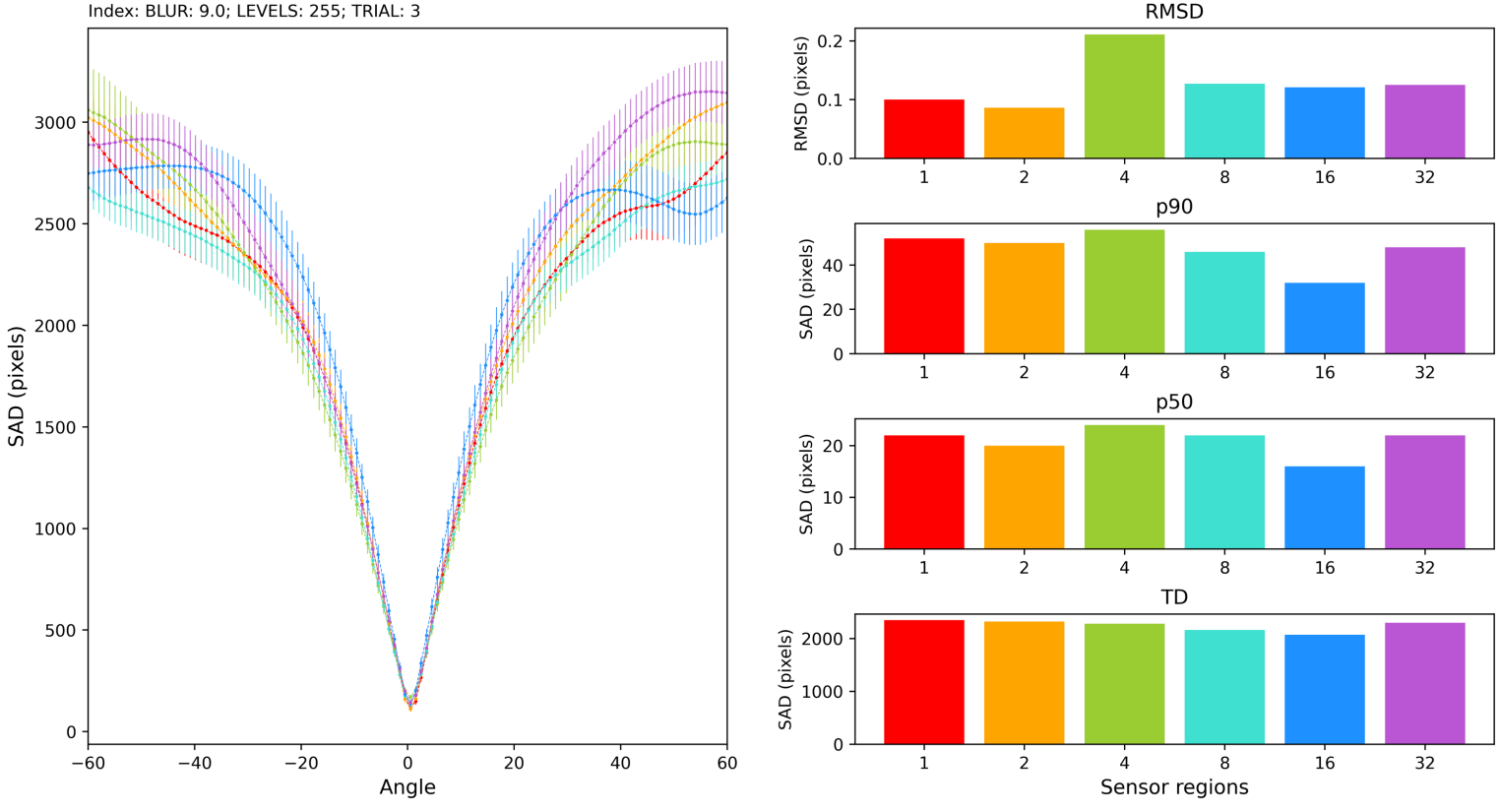
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 53.08; RMSD/dist: 0.133; TD: 2275; p90: 46; p50: 22; complete: 0

100%

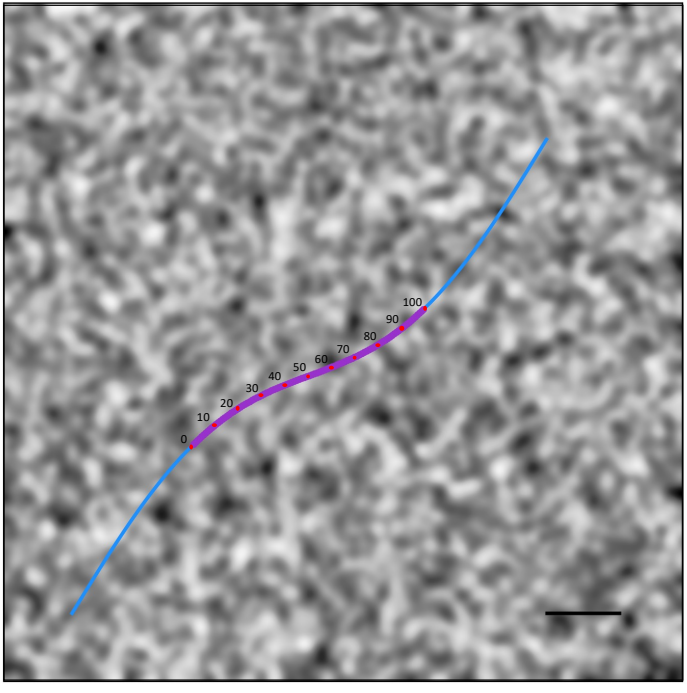


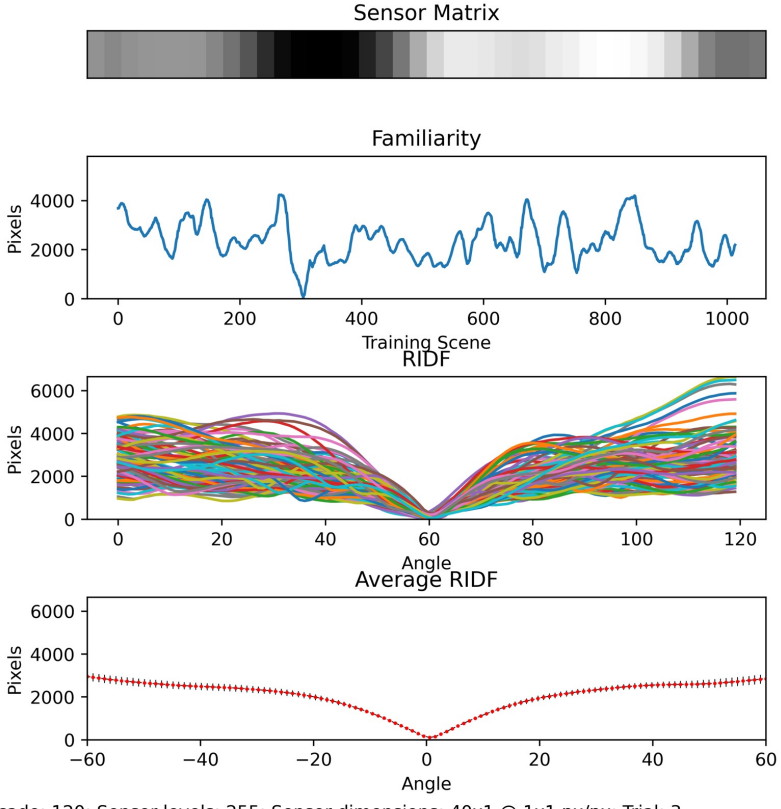


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2
Navigation stats: RMSD error: 34.38; RMSD/dist: 0.086; TD: 2214; p90: 42; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 255; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

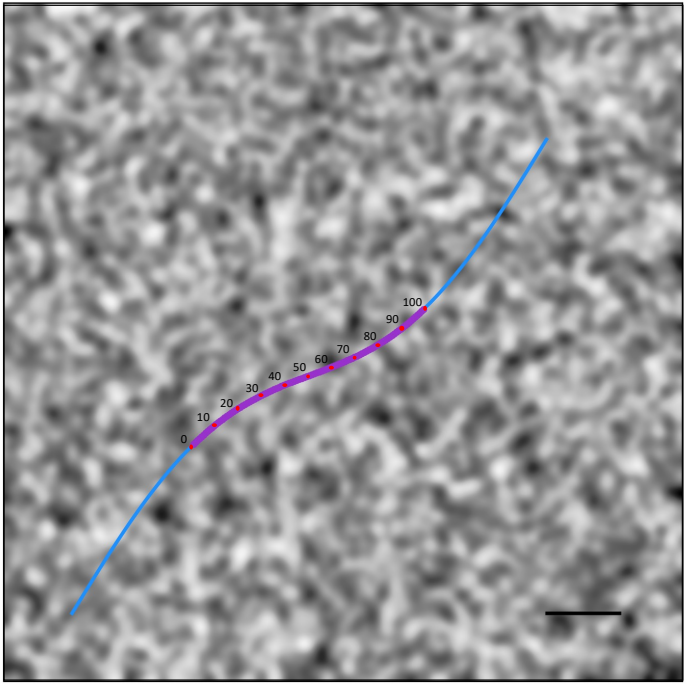
100%

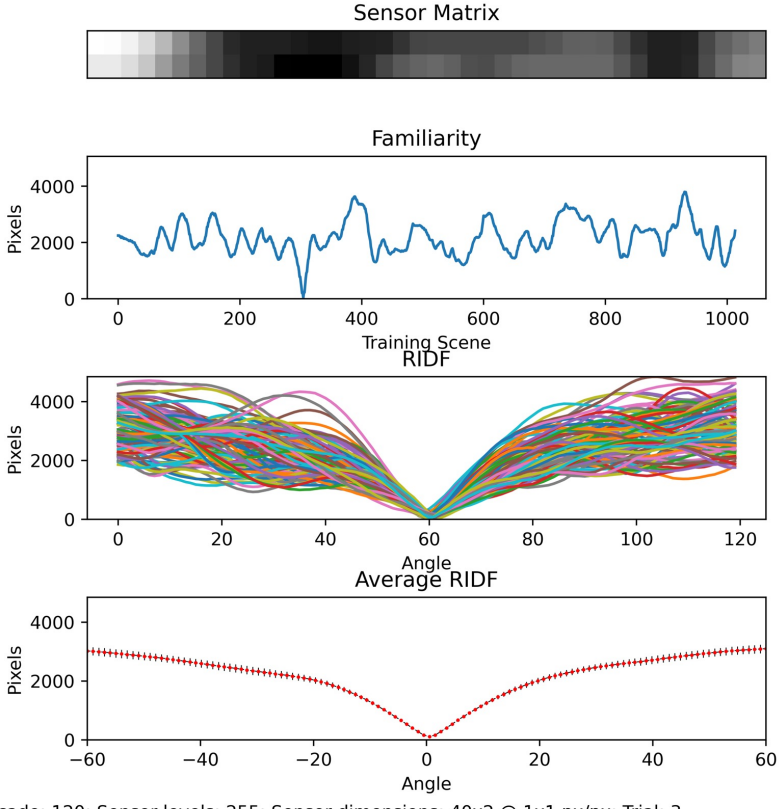




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 39.97; RMSD/dist: 0.100; TD: 2346; p90: 52; p50: 22; complete: 0

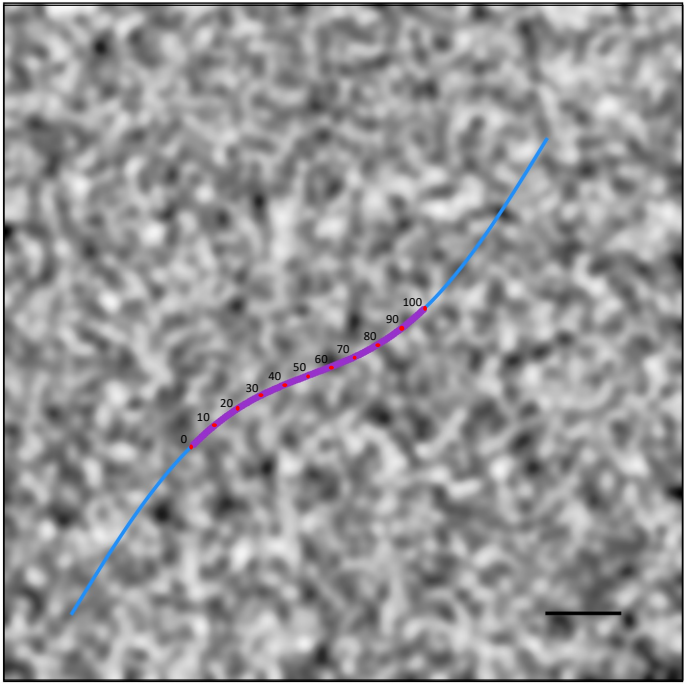
100%

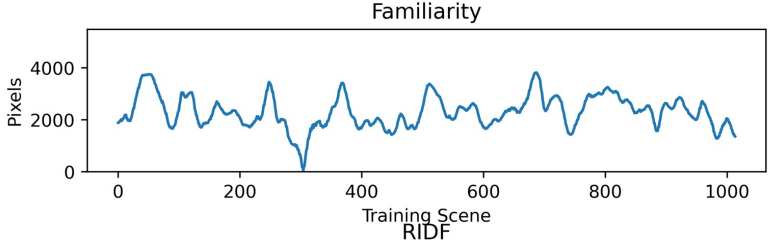


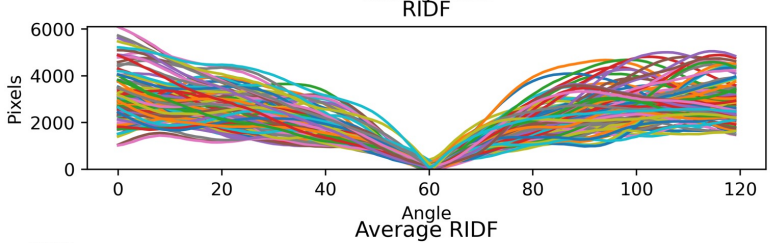


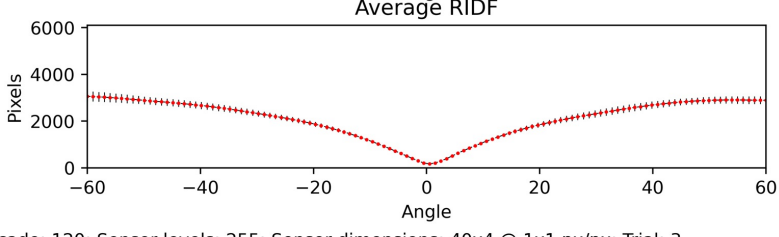
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 34.33; RMSD/dist: 0.086; TD: 2320; p90: 50; p50: 20; complete: 0

100%



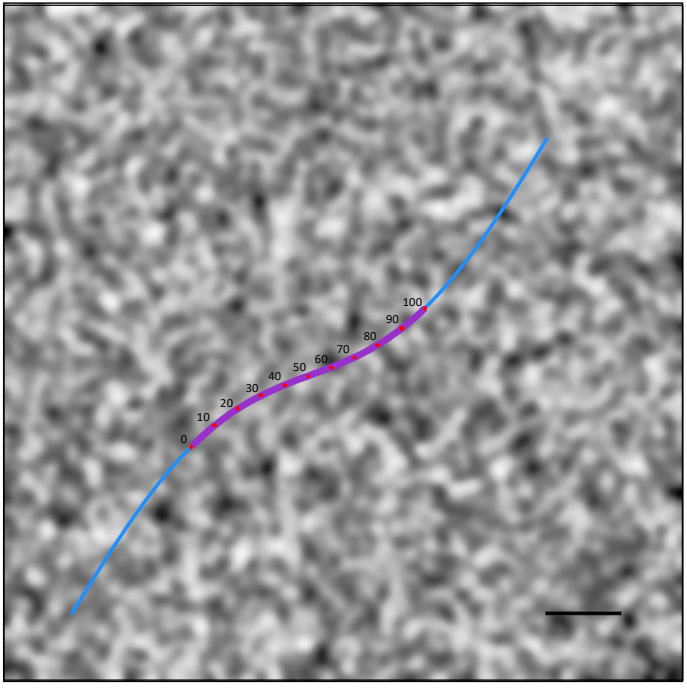


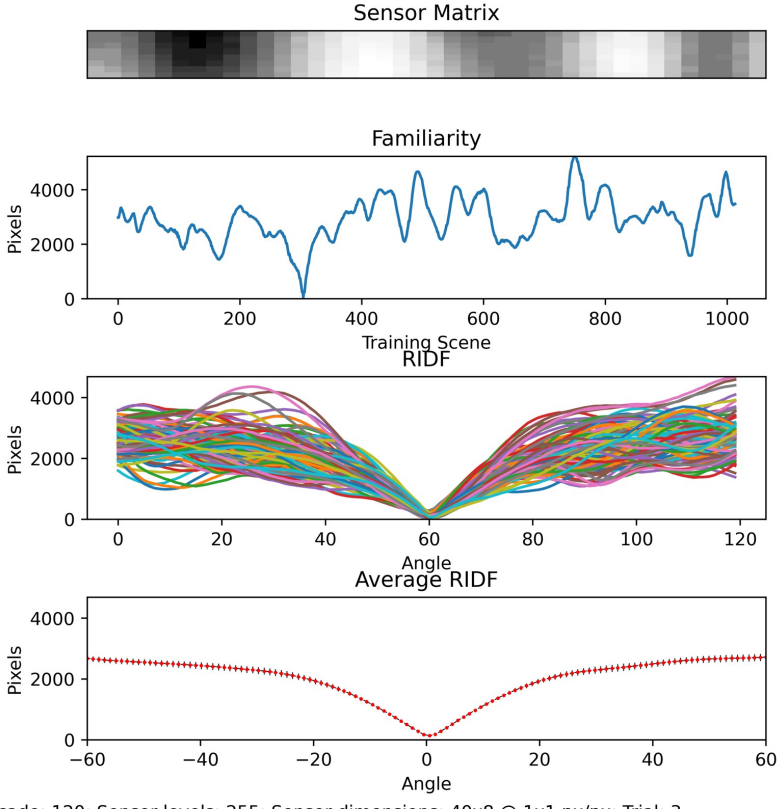




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 84.39; RMSD/dist: 0.211; TD: 2282; p90: 56; p50: 24; complete: 0

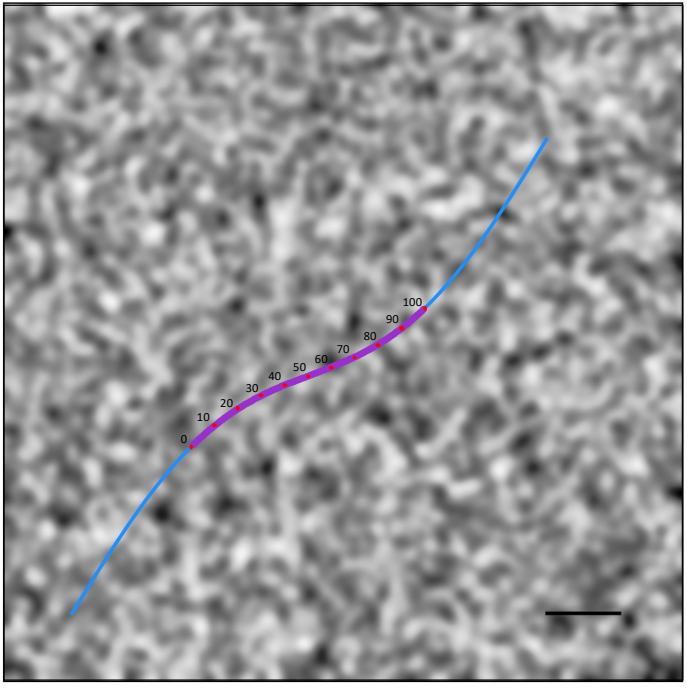
100%

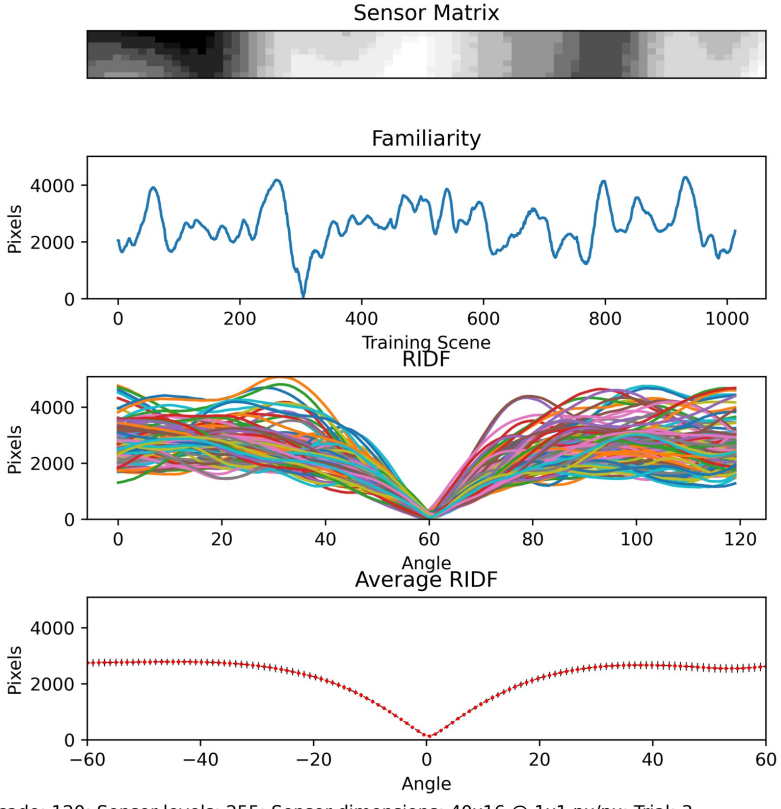




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 50.77; RMSD/dist: 0.127; TD: 2164; p90: 46; p50: 22; complete: 0

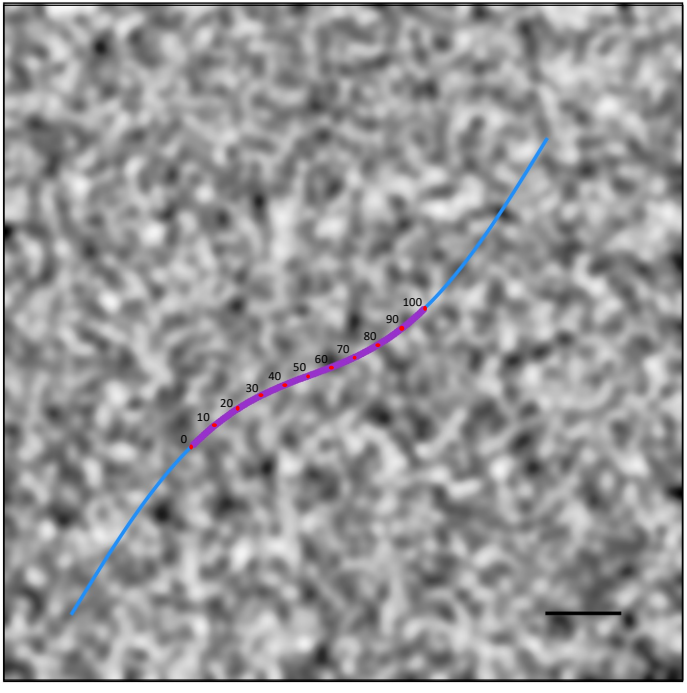
100%

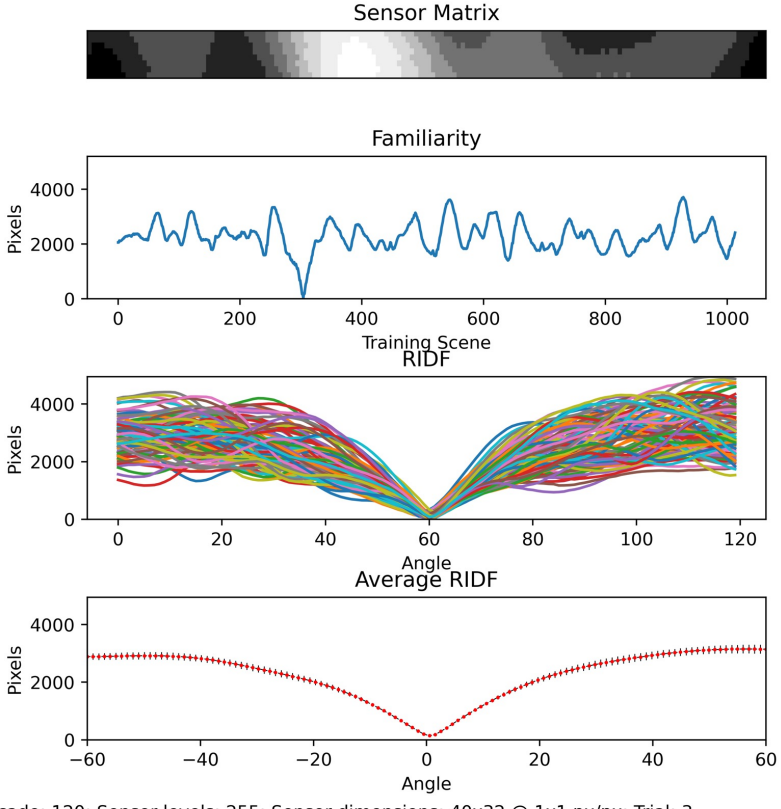




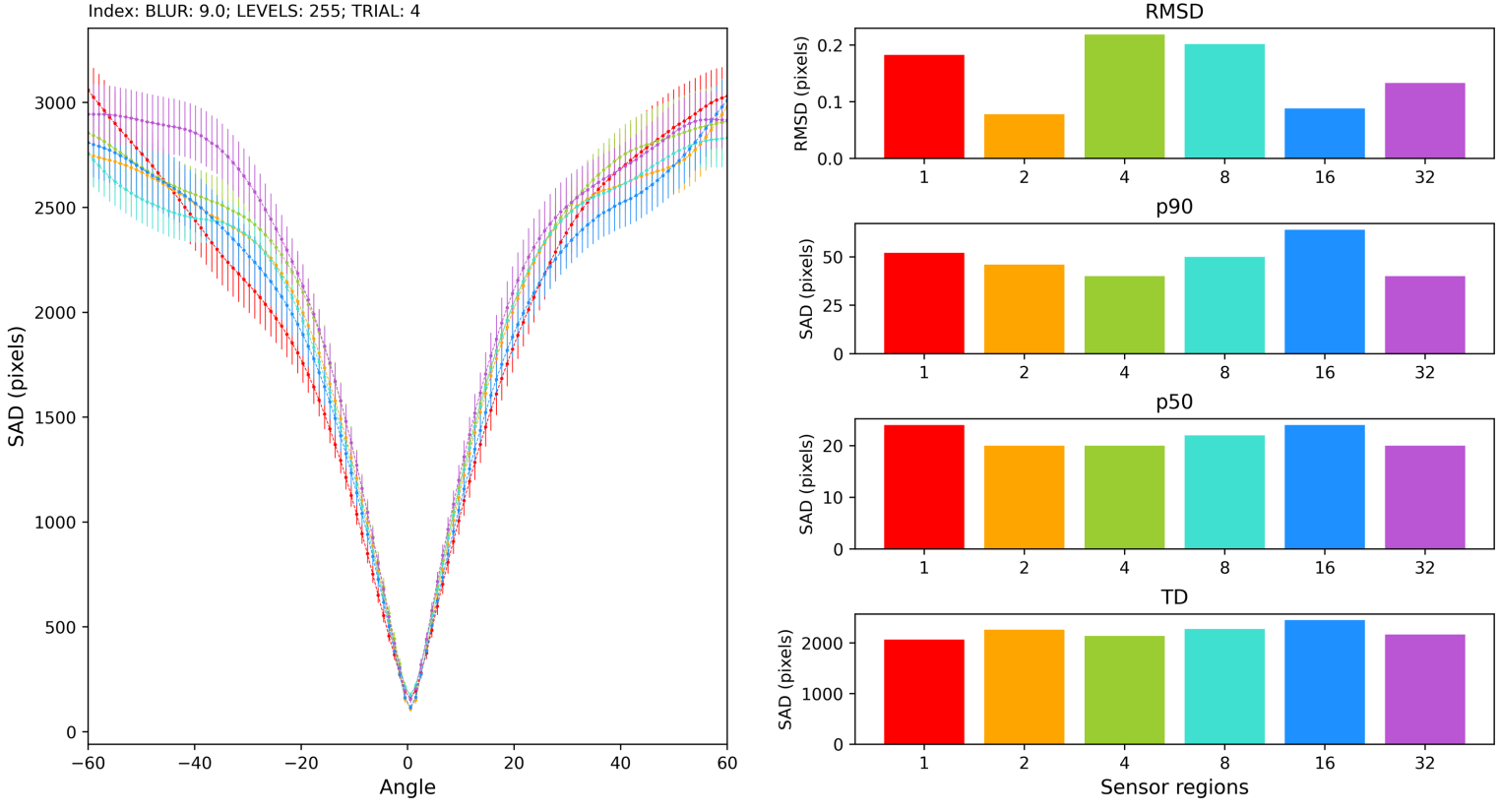
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 48.53; RMSD/dist: 0.121; TD: 2070; p90: 32; p50: 16; complete: 0

100%

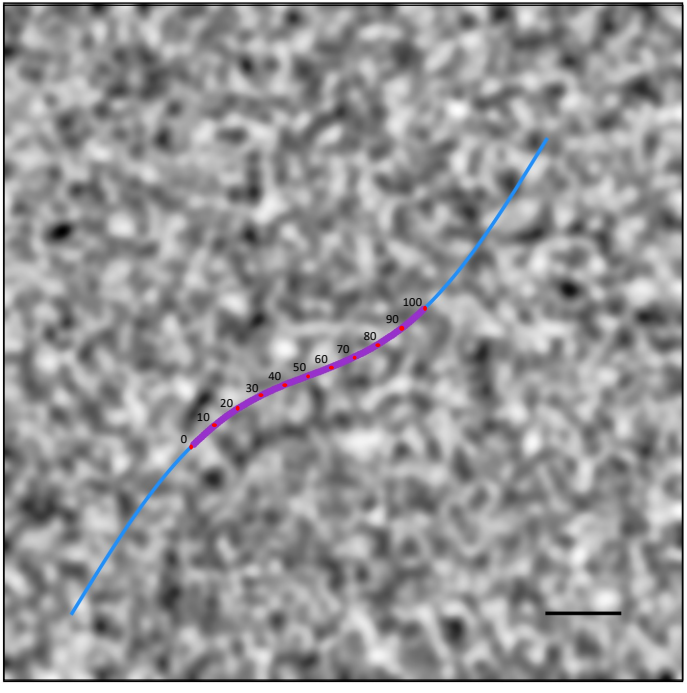


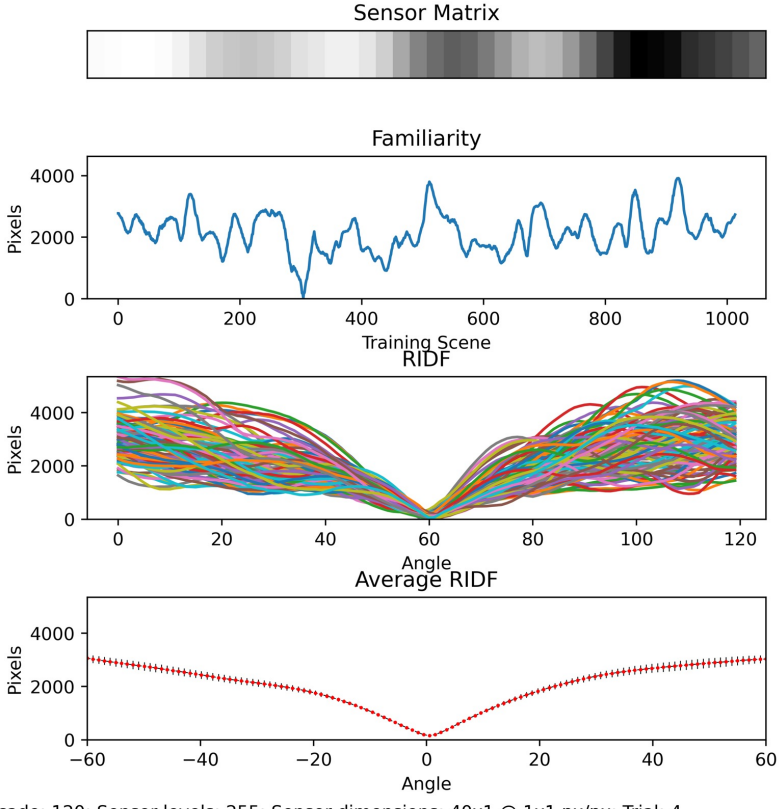


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3
Navigation stats: RMSD error: 50.02; RMSD/dist: 0.125; TD: 2297; p90: 48; p50: 22; complete: 0


Index: BLUR: 9.0; LEVELS: 255; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

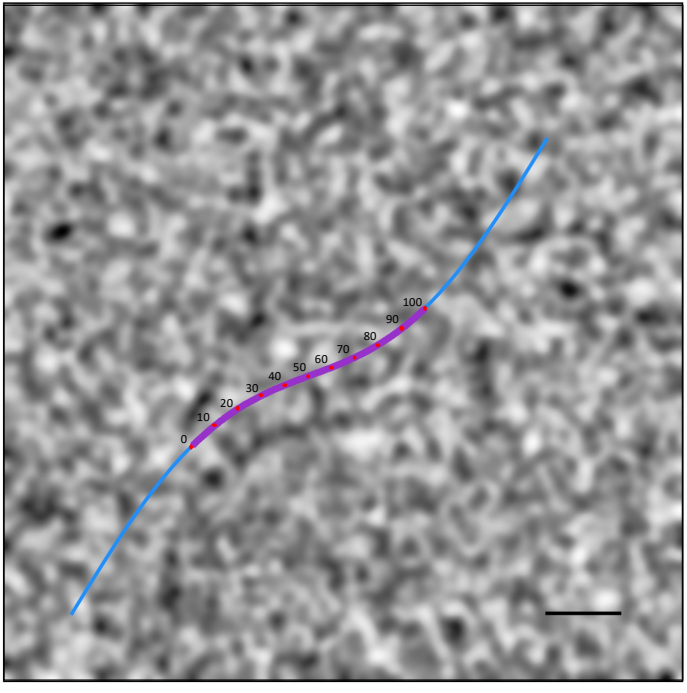
100%

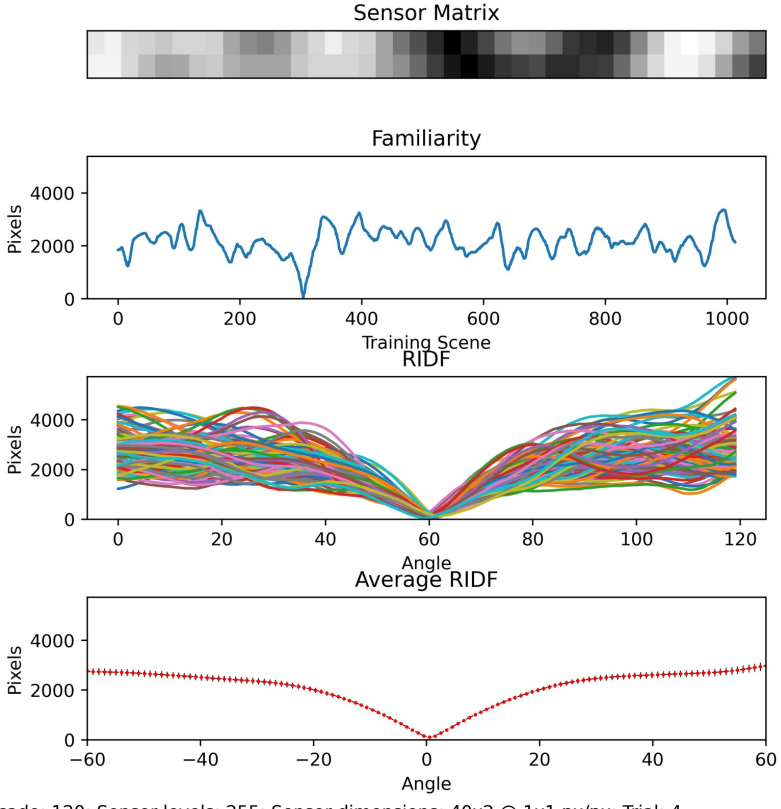




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 73.15; RMSD/dist: 0.183; TD: 2067; p90: 52; p50: 24; complete: 0

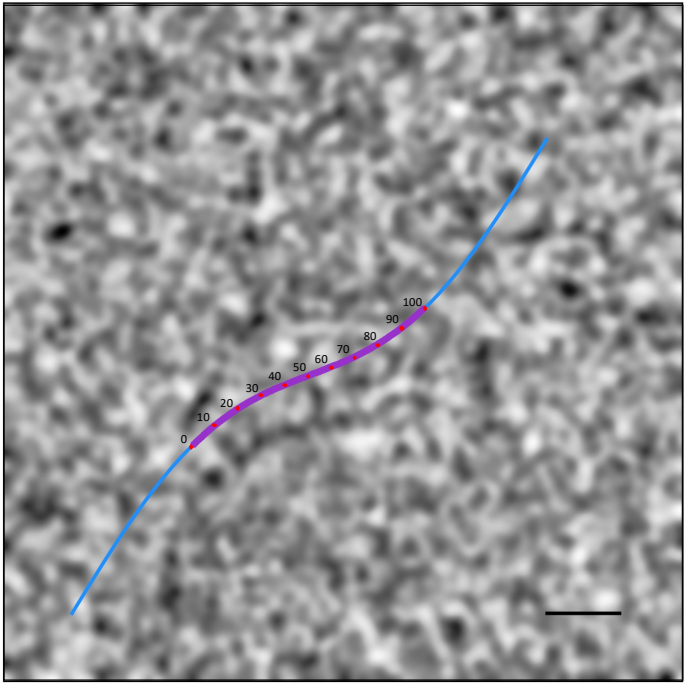
100%

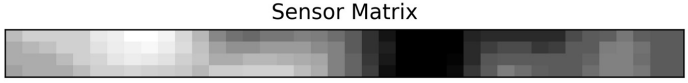


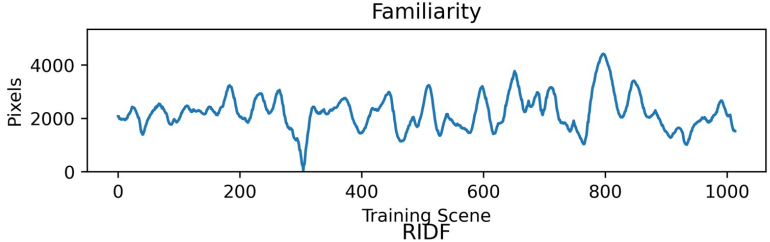


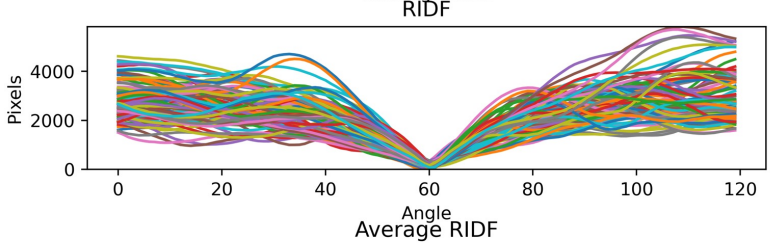
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 31.33; RMSD/dist: 0.078; TD: 2259; p90: 46; p50: 20; complete: 0

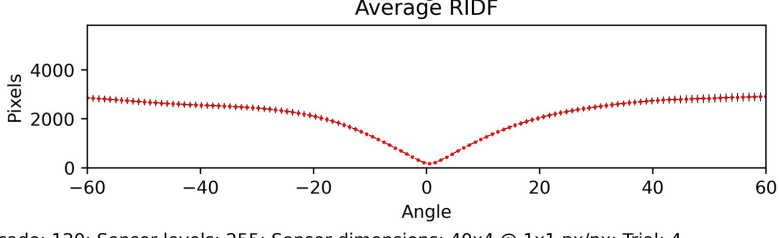
100%





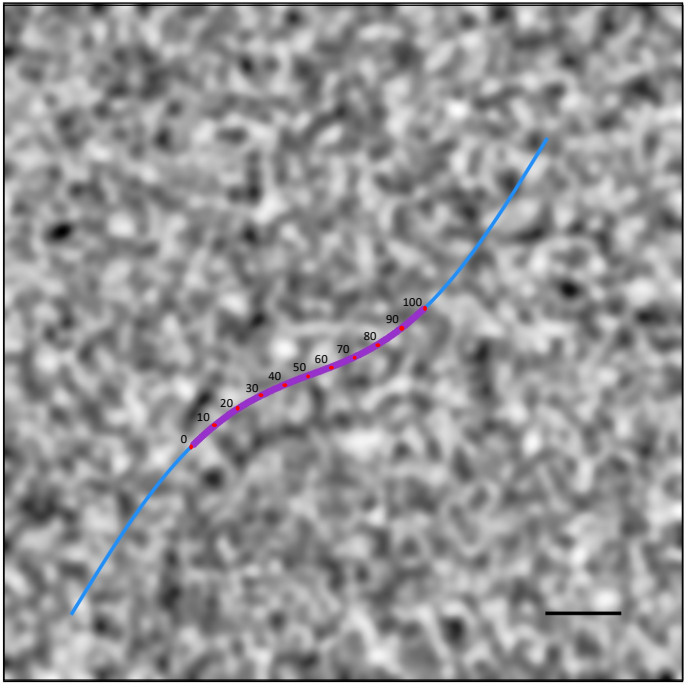


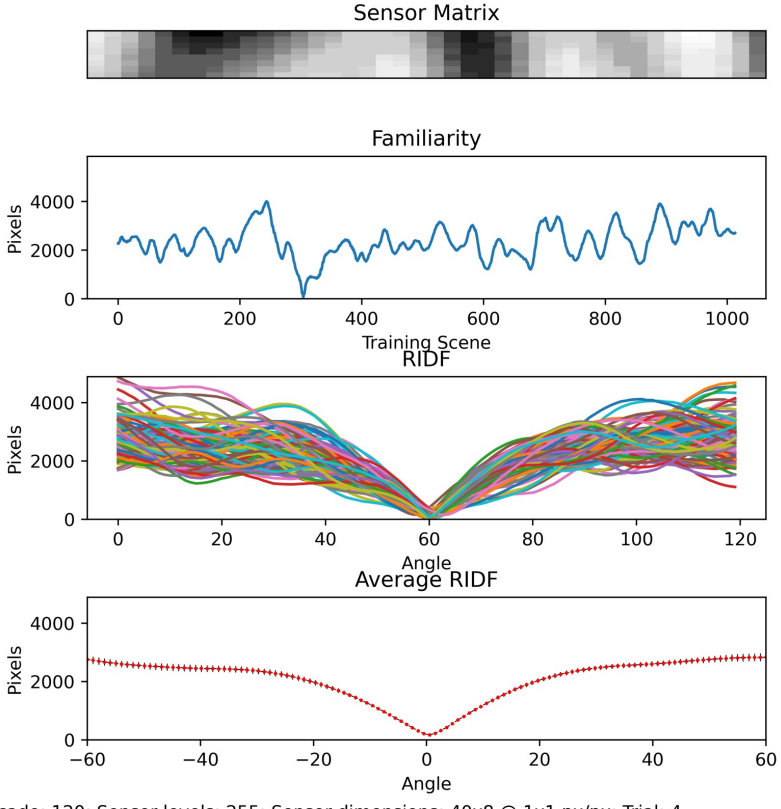




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 87.51; RMSD/dist: 0.219; TD: 2135; p90: 40; p50: 20; complete: 0

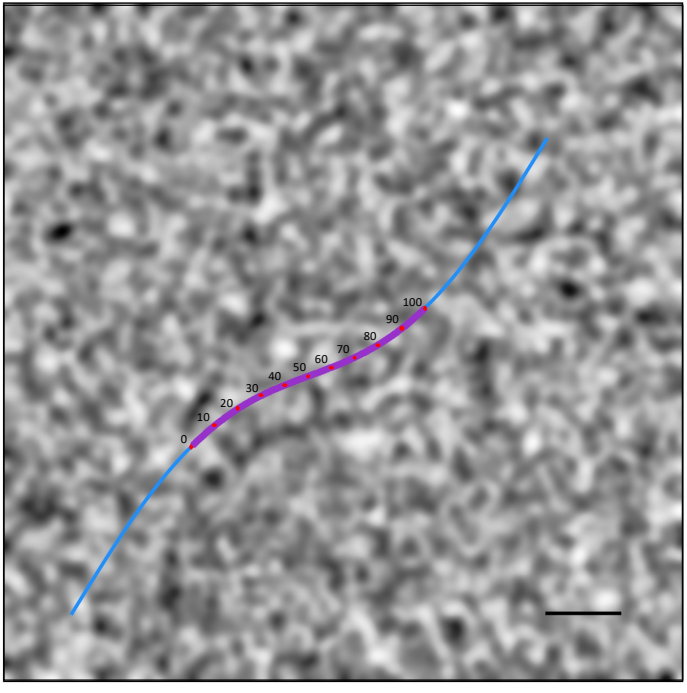
100%

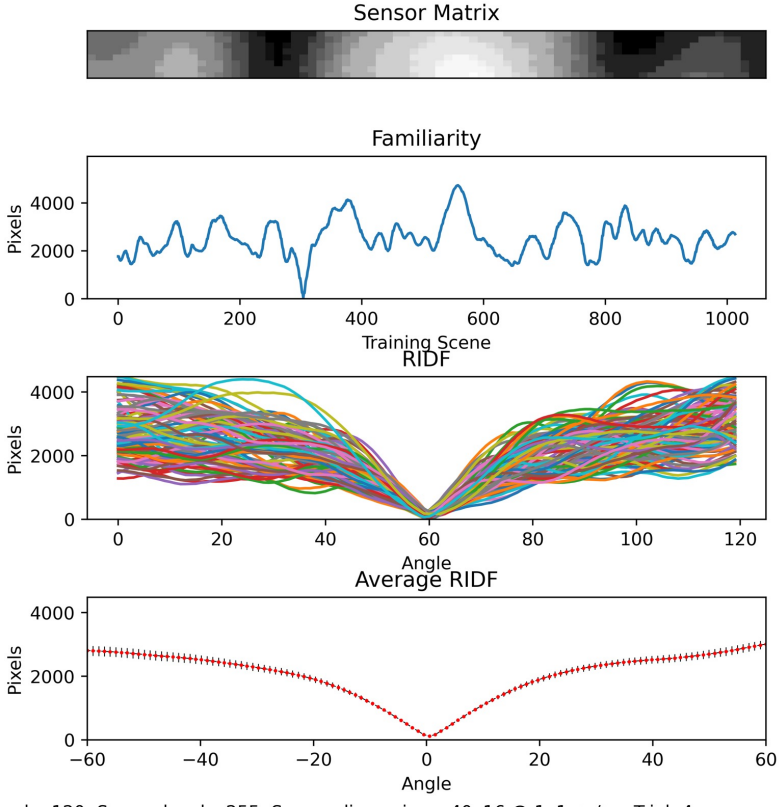




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 80.68; RMSD/dist: 0.202; TD: 2274; p90: 50; p50: 22; complete: 0

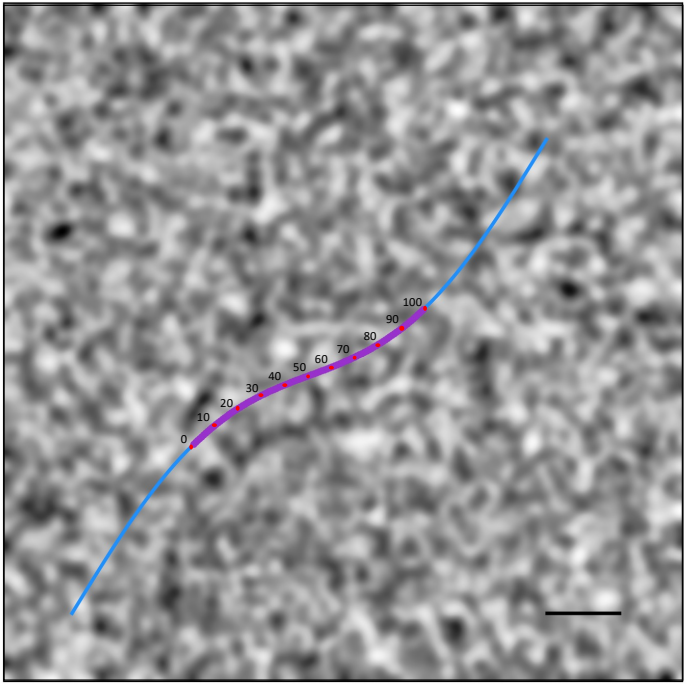
100%

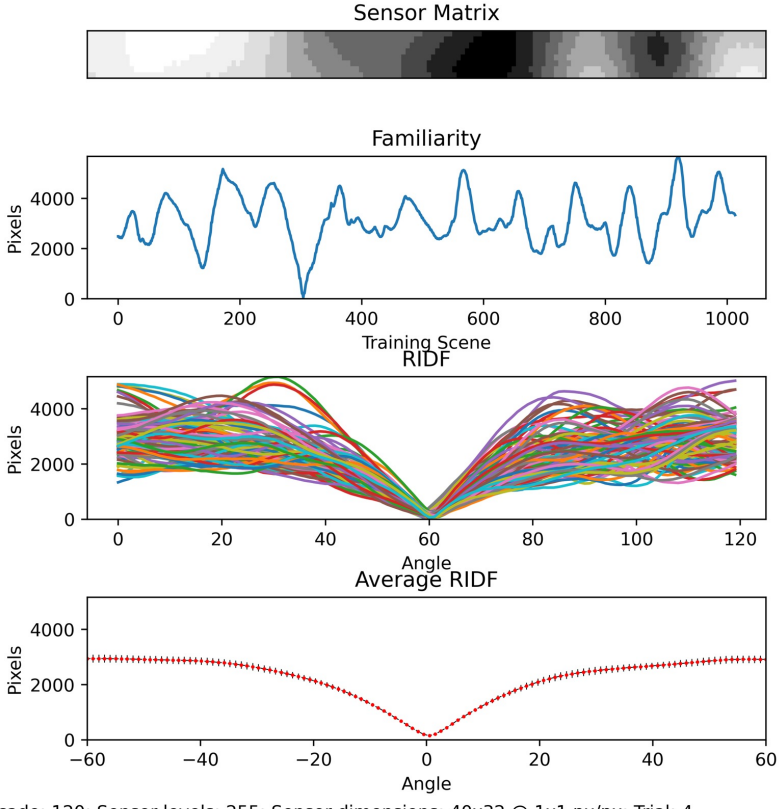




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4
Navigation stats: RMSD error: 35.21; RMSD/dist: 0.088; TD: 2448; p90: 64; p50: 24; complete: 0

100%





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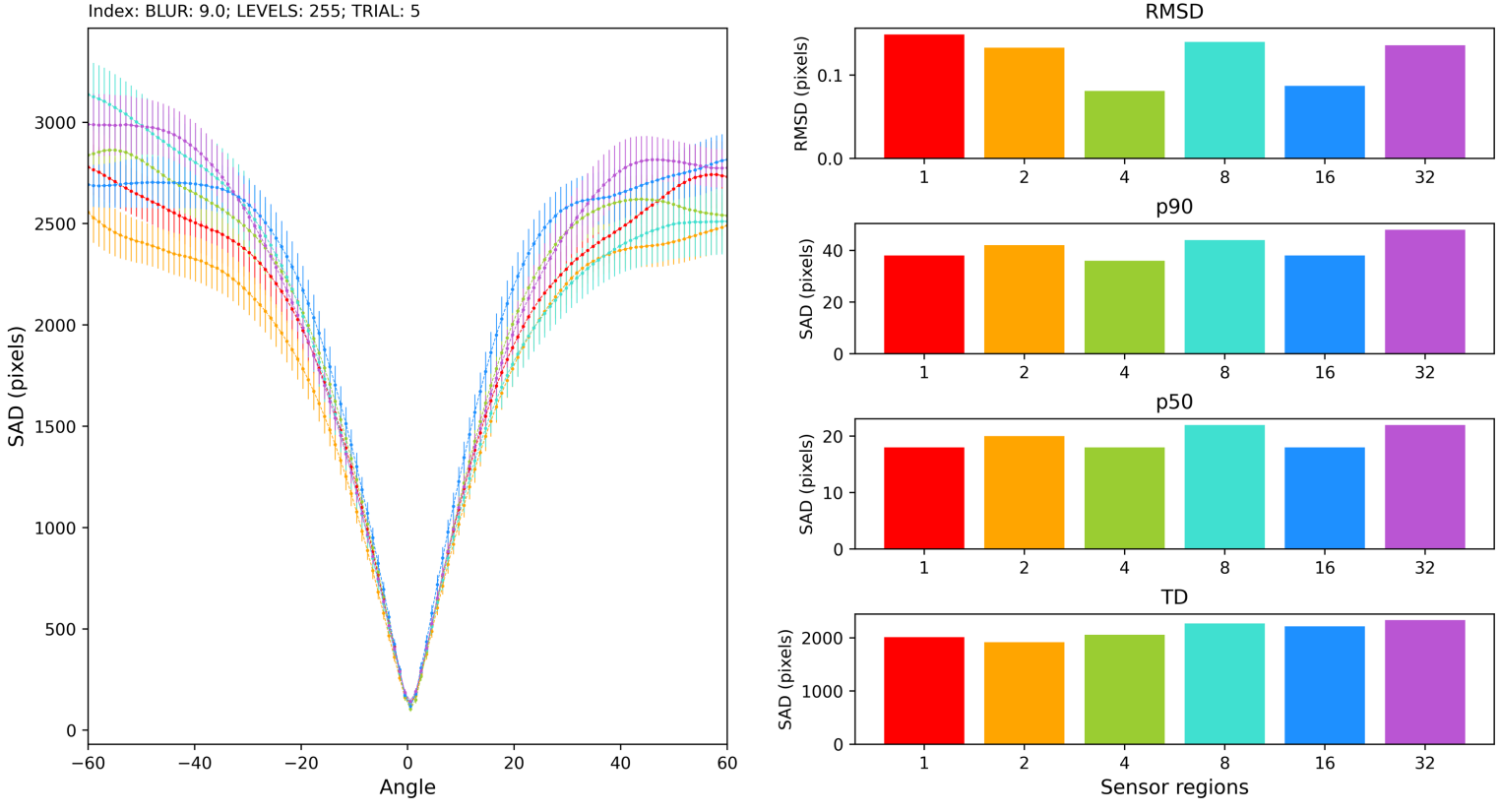
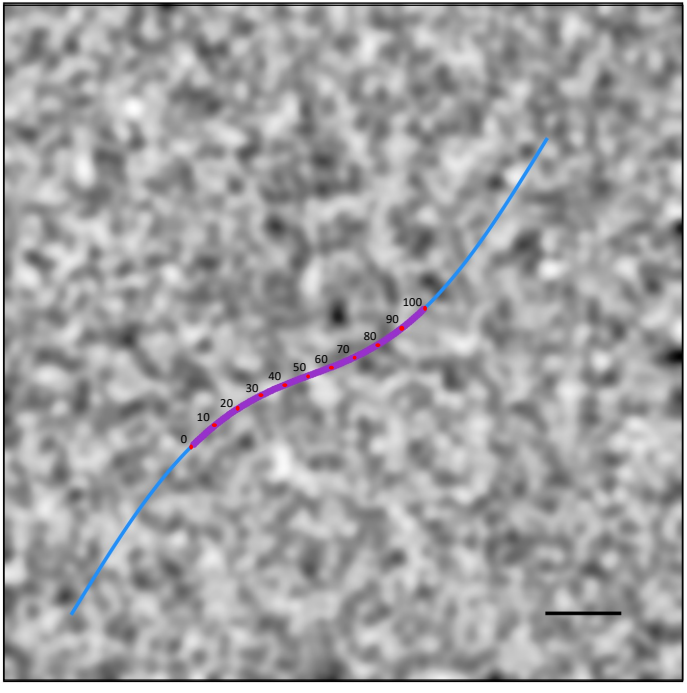
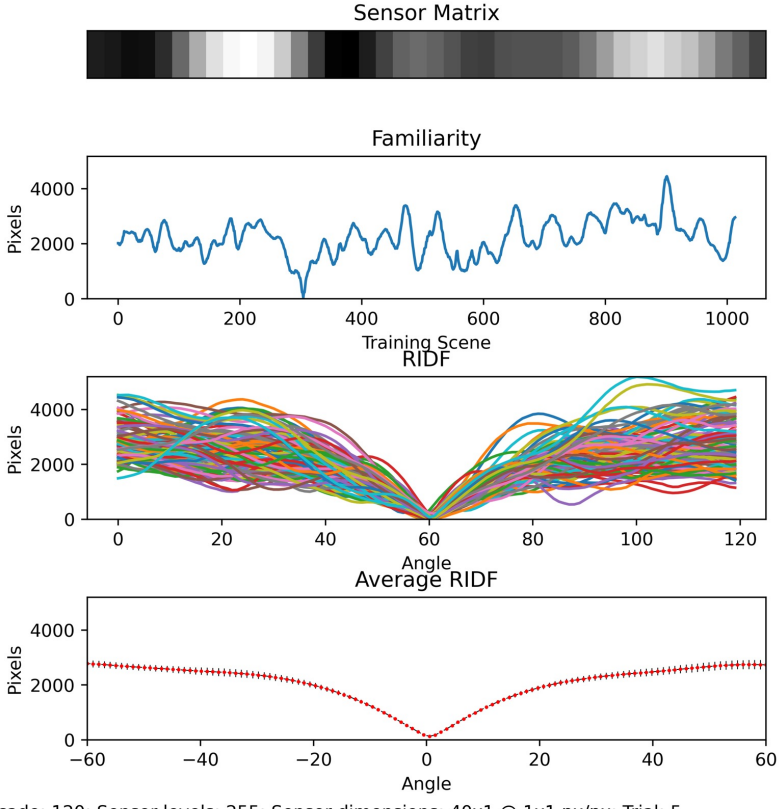
Navigation stats: RMSD error: 53.13; RMSD/dist: 0.133; TD: 2167; p90: 40; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 255; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%





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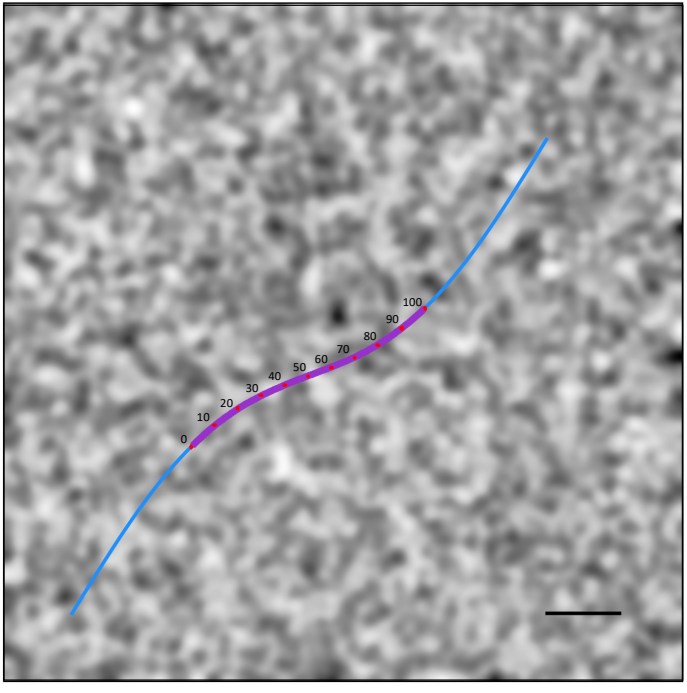
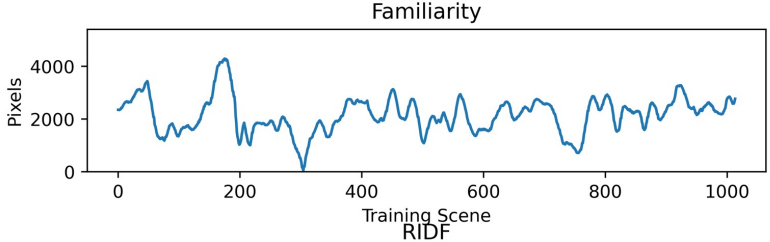
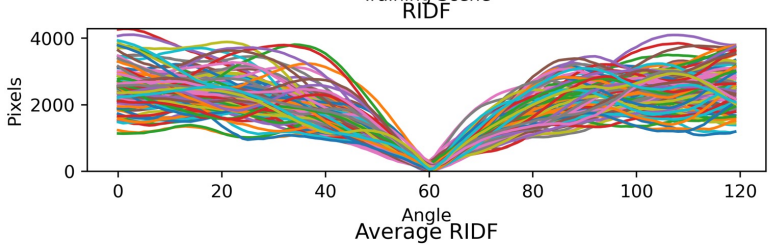
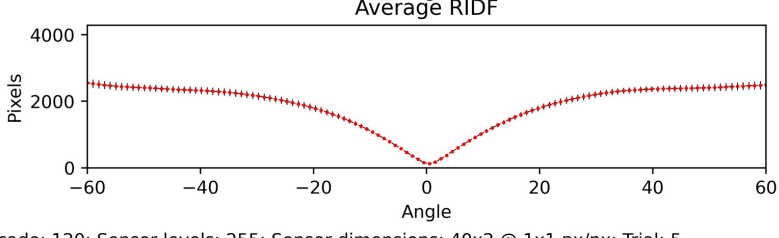
Navigation stats: RMSD error: 59.64; RMSD/dist: 0.149; TD: 2012; p90: 38; p50: 18; complete: 0

100%



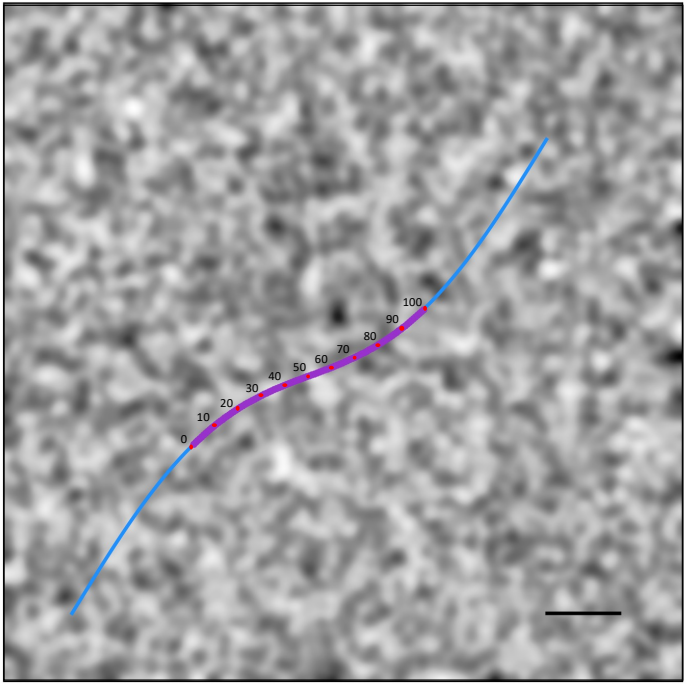


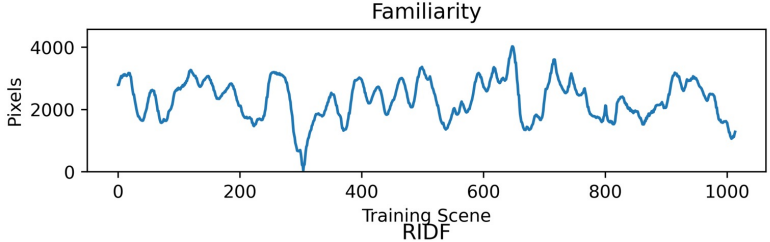


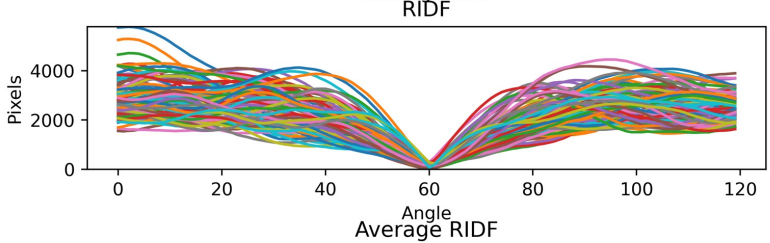


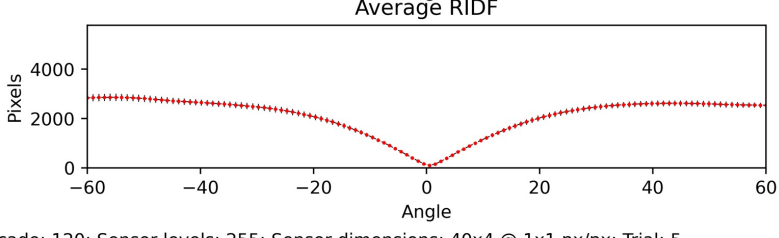
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 53.12; RMSD/dist: 0.133; TD: 1918; p90: 42; p50: 20; complete: 0

100%



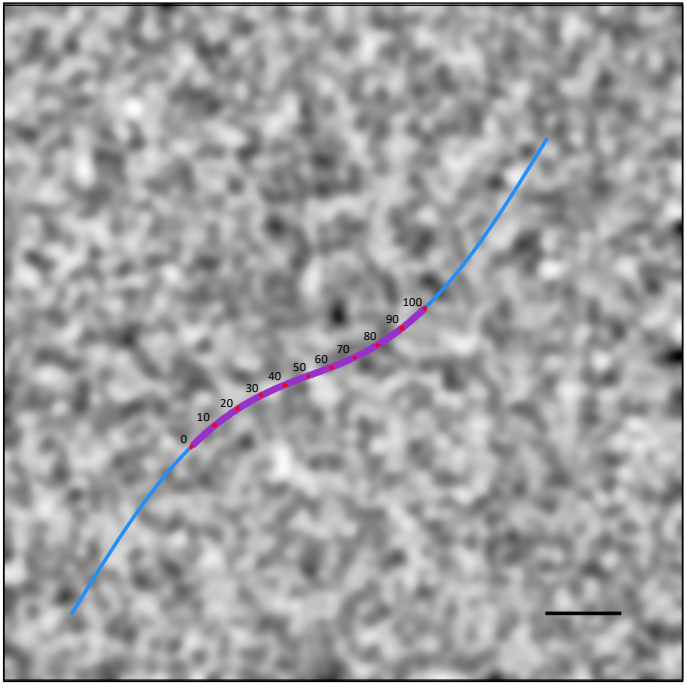


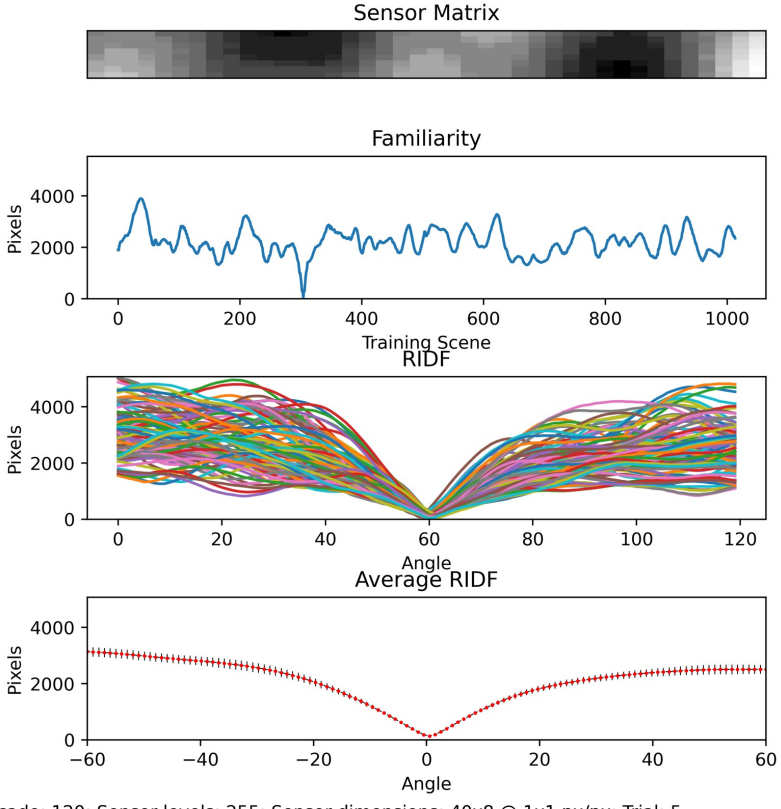




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 32.25; RMSD/dist: 0.081; TD: 2058; p90: 36; p50: 18; complete: 0

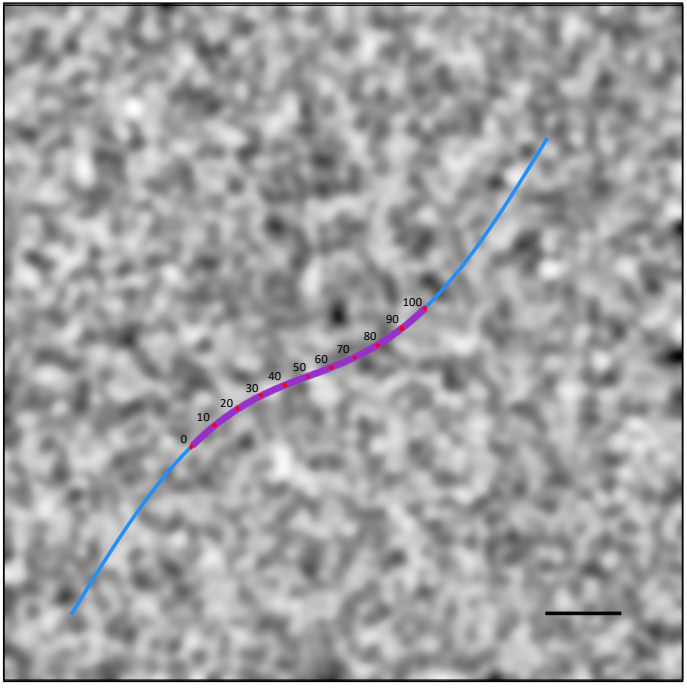
100%

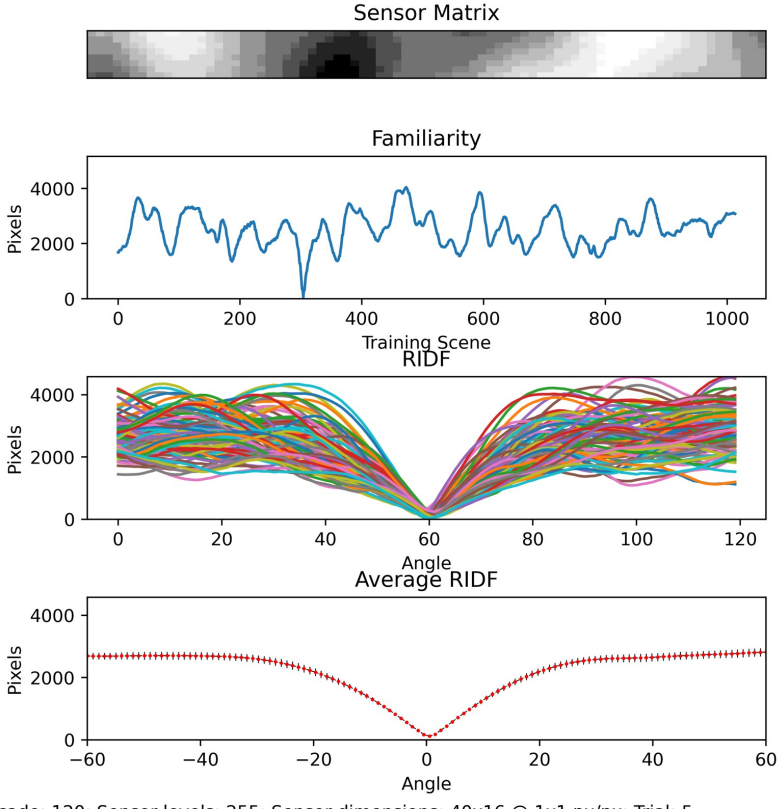




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 56.01; RMSD/dist: 0.140; TD: 2267; p90: 44; p50: 22; complete: 0

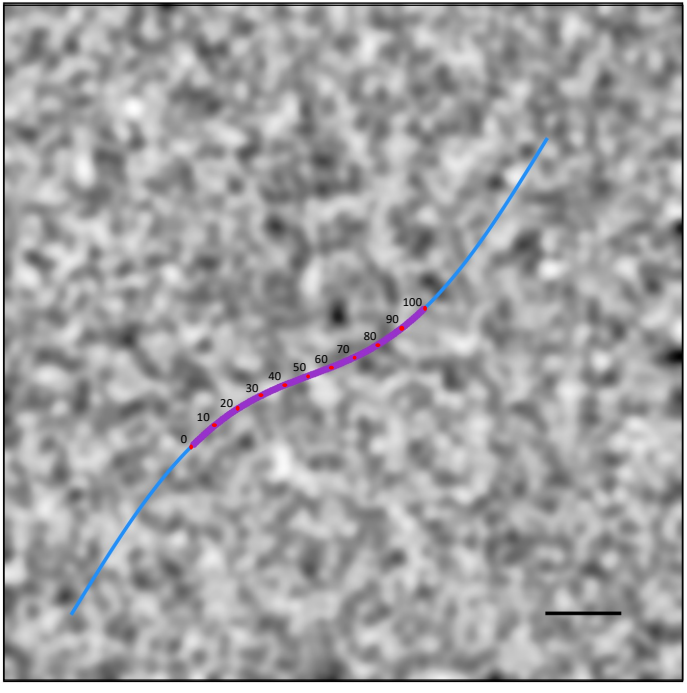
100%

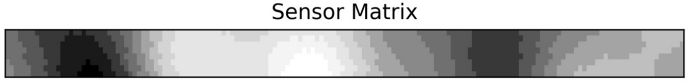


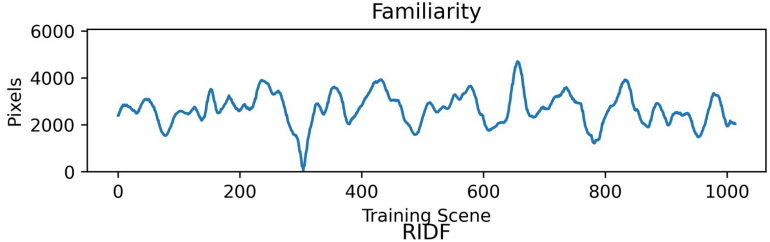


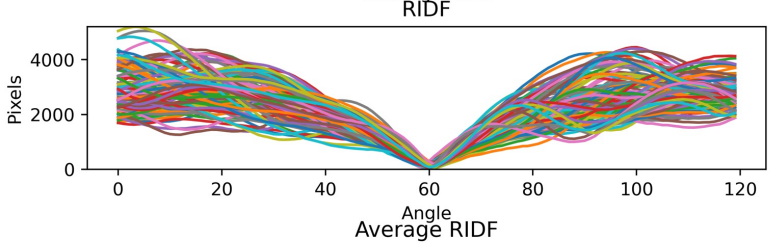
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 34.78; RMSD/dist: 0.087; TD: 2215; p90: 38; p50: 18; complete: 0

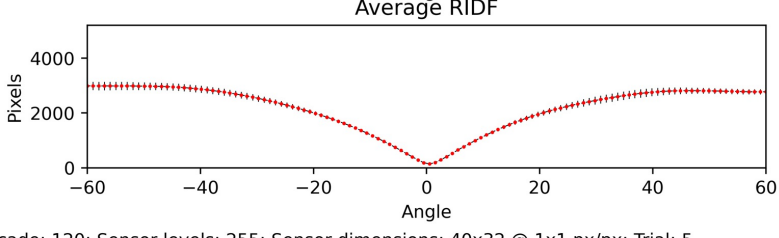
100%



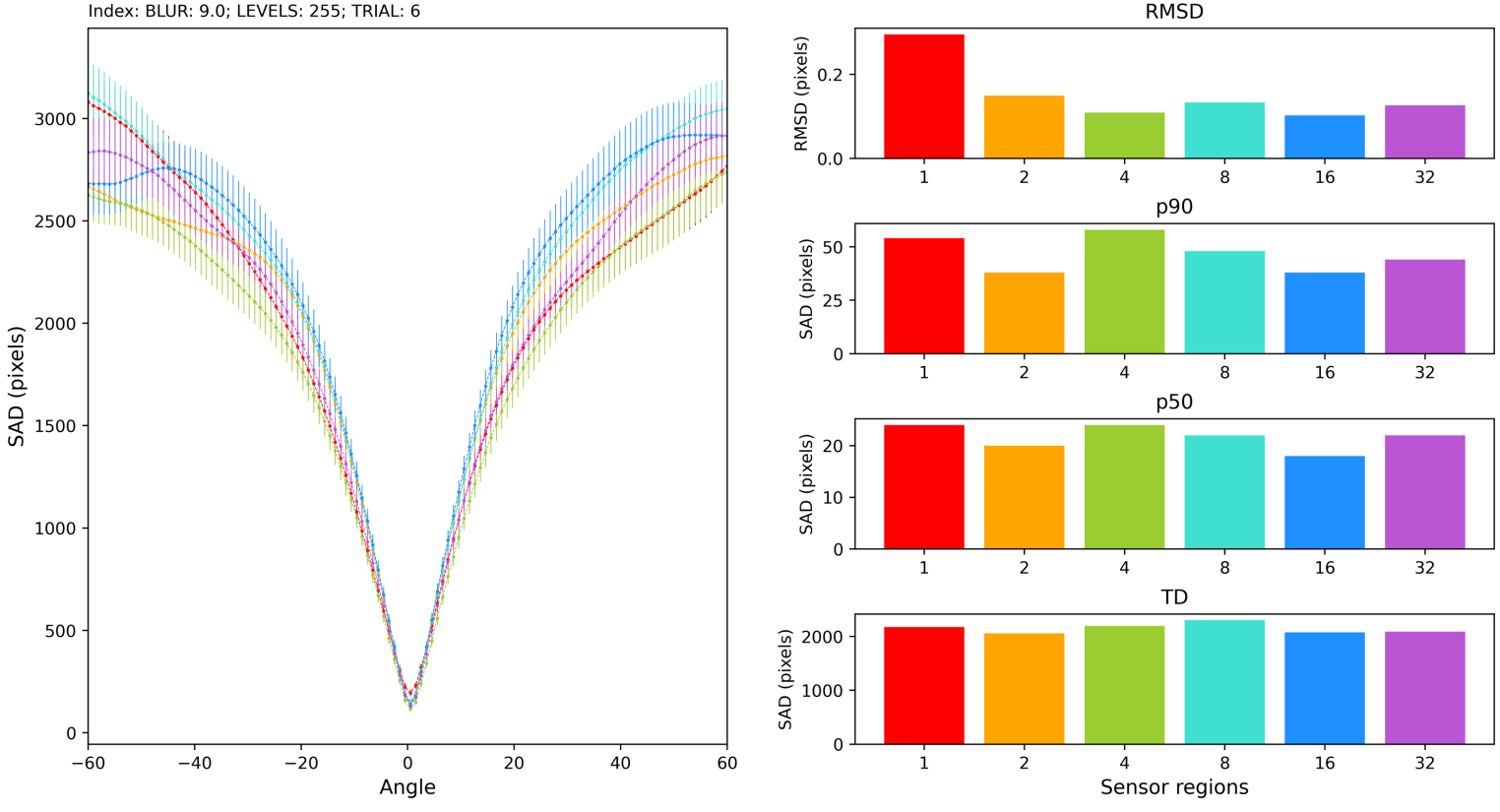




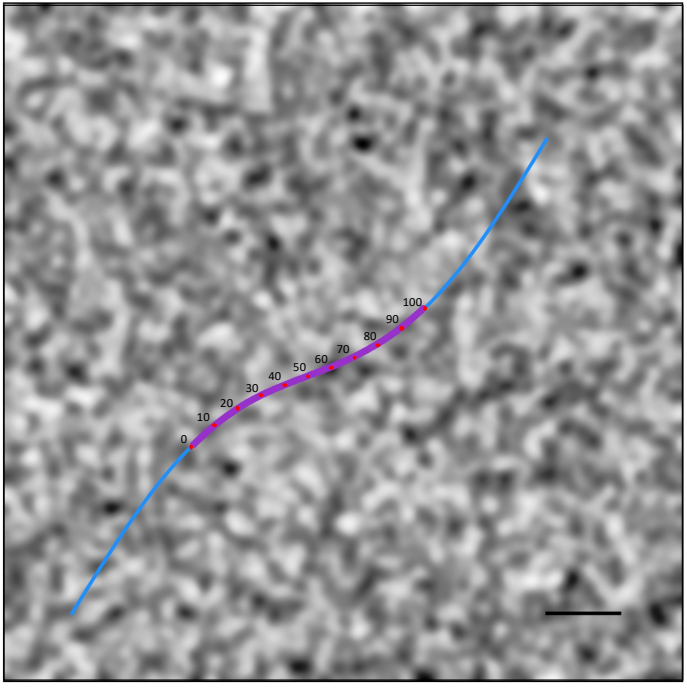


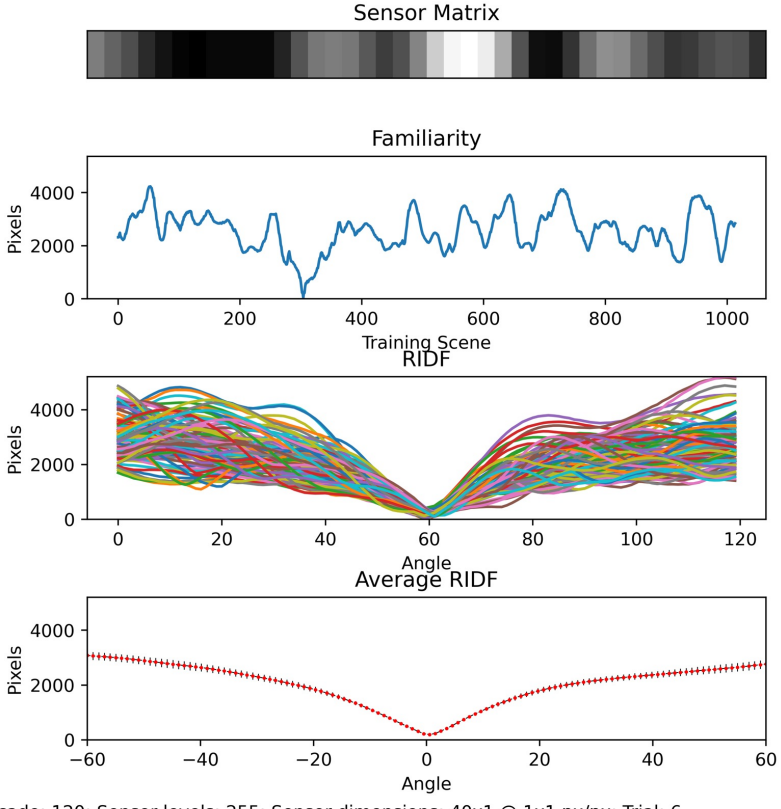


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5
Navigation stats: RMSD error: 54.37; RMSD/dist: 0.136; TD: 2330; p90: 48; p50: 22; complete: 0


Index: BLUR: 9.0; LEVELS: 255; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

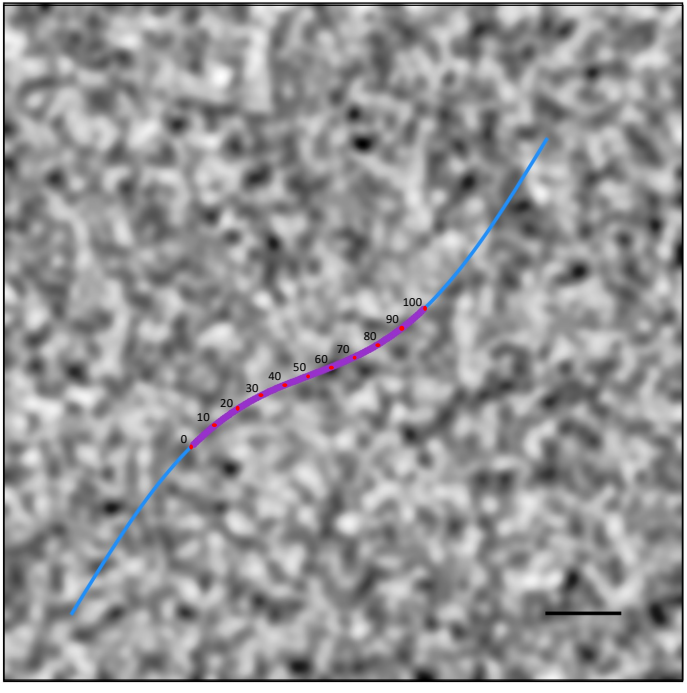
100%

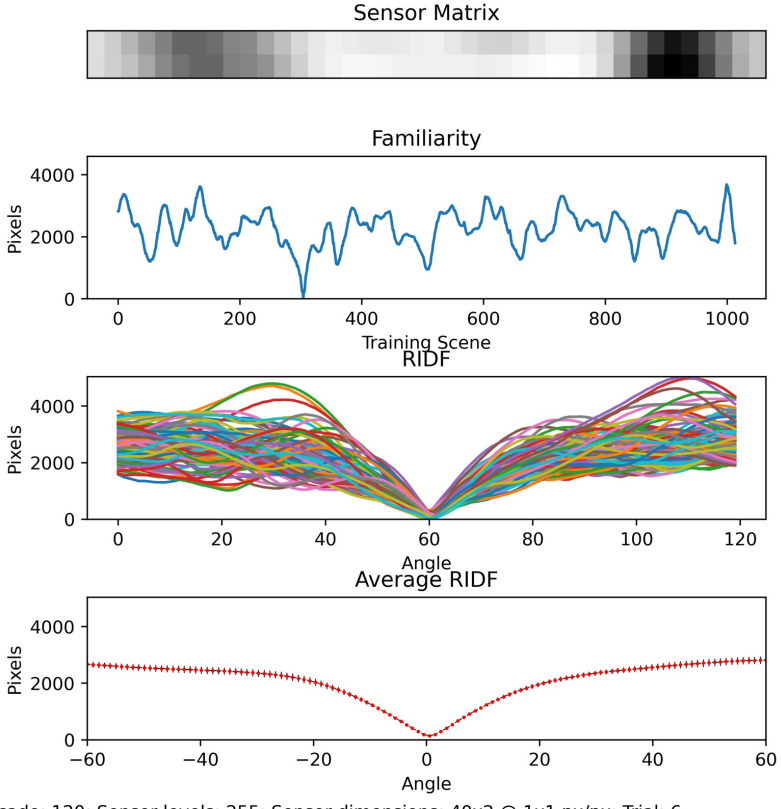




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 117.91; RMSD/dist: 0.295; TD: 2174; p90: 54; p50: 24; complete: 0

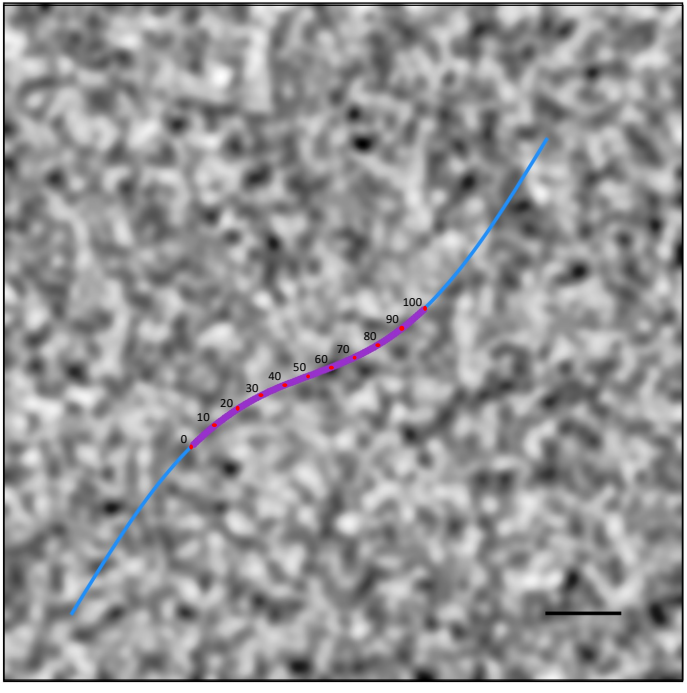
100%

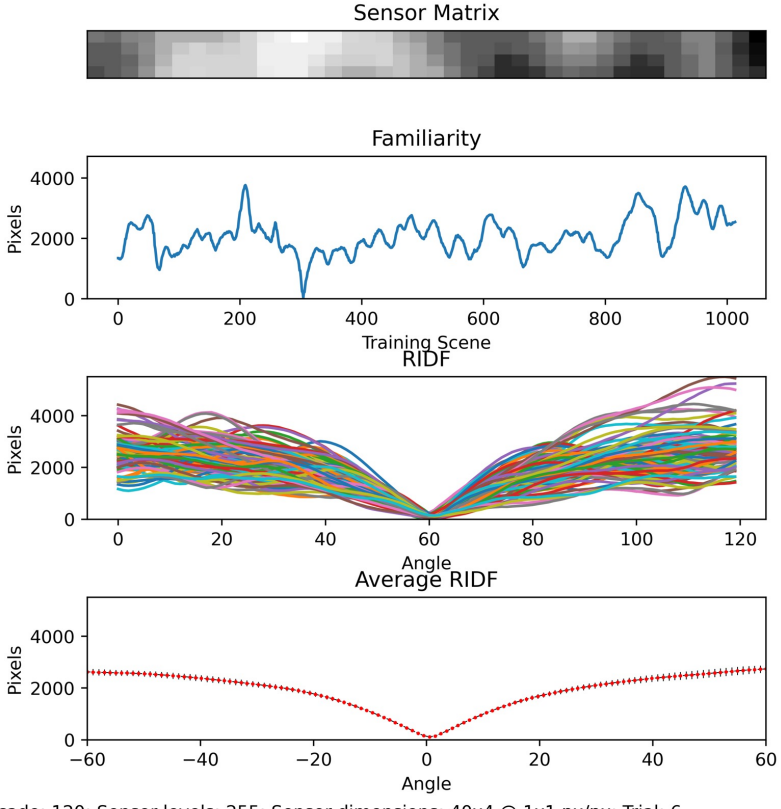




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 59.63; RMSD/dist: 0.149; TD: 2057; p90: 38; p50: 20; complete: 0

100%





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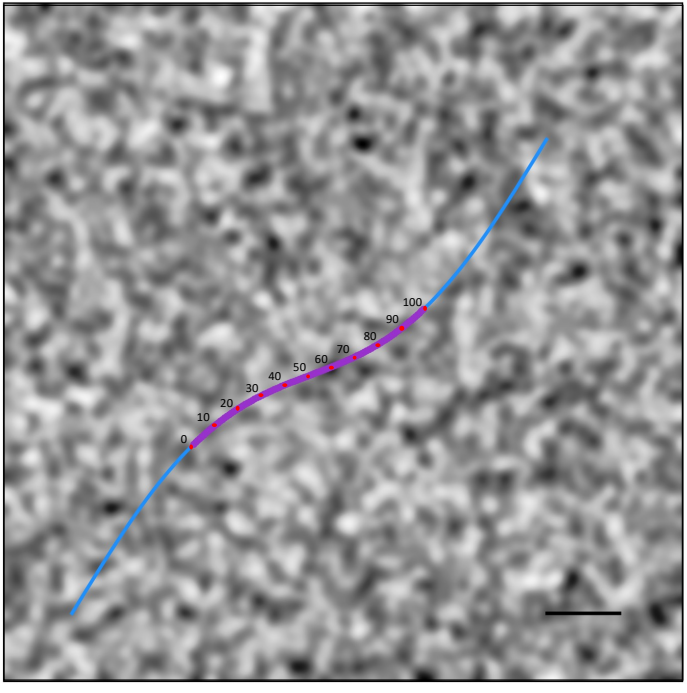
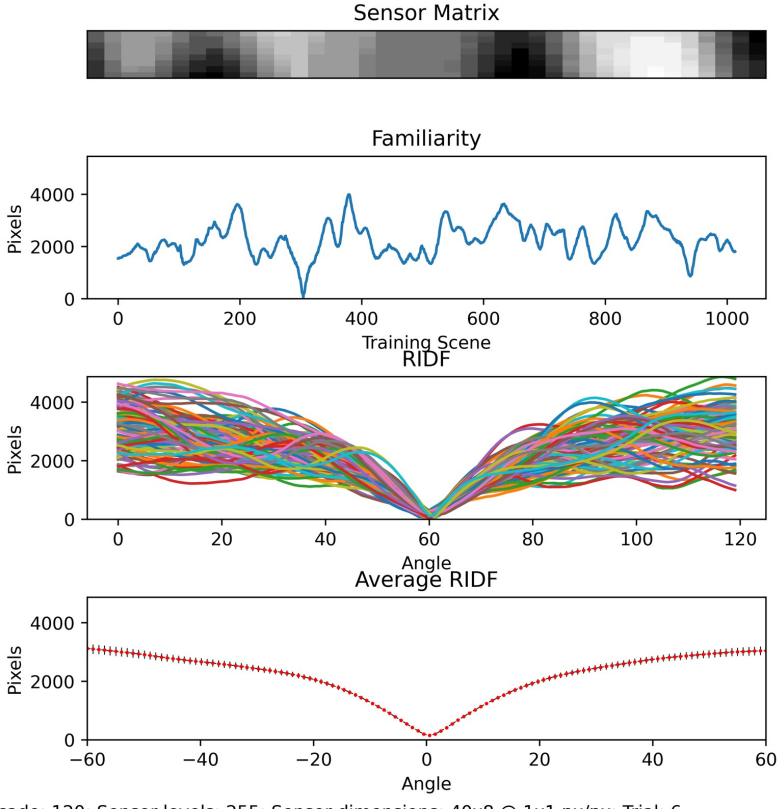
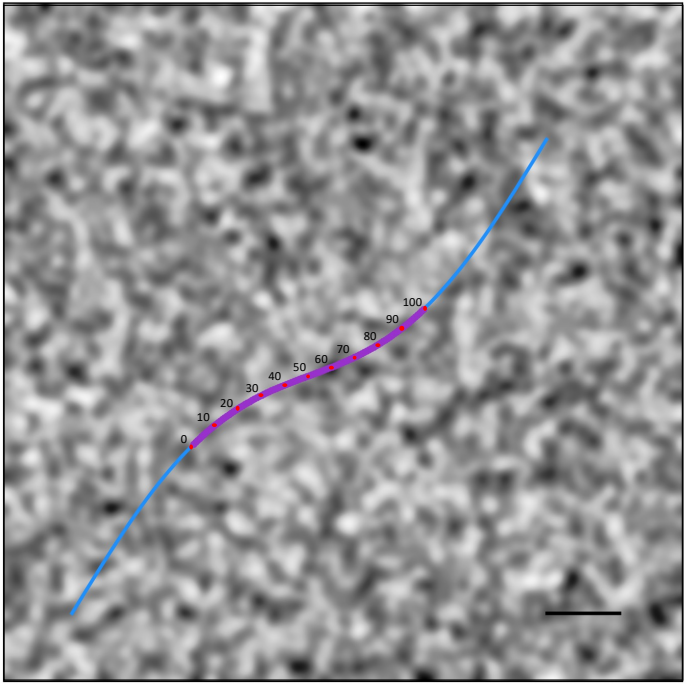
100%

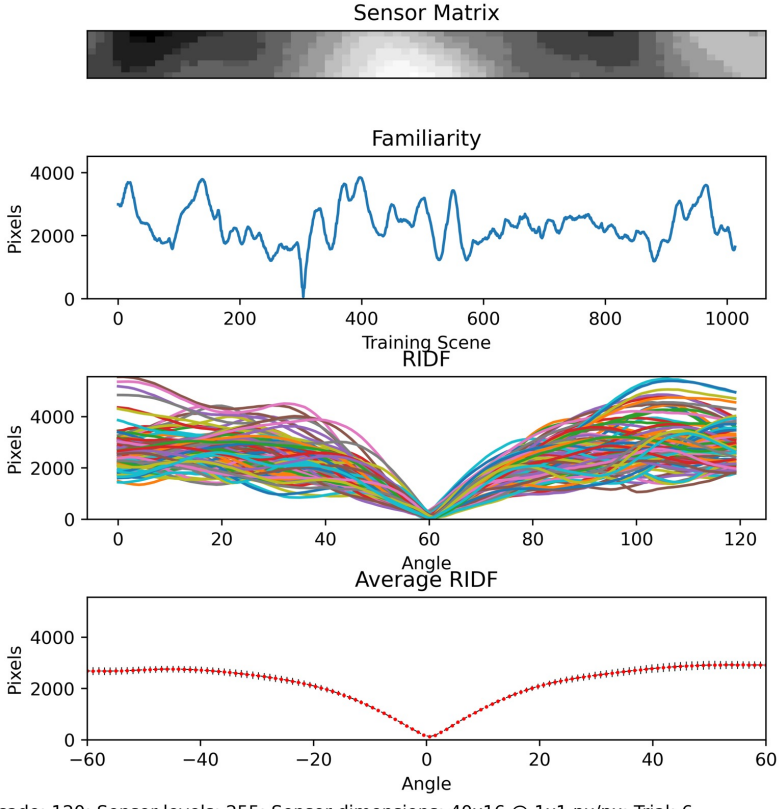




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 53.04; RMSD/dist: 0.133; TD: 2302; p90: 48; p50: 22; complete: 0

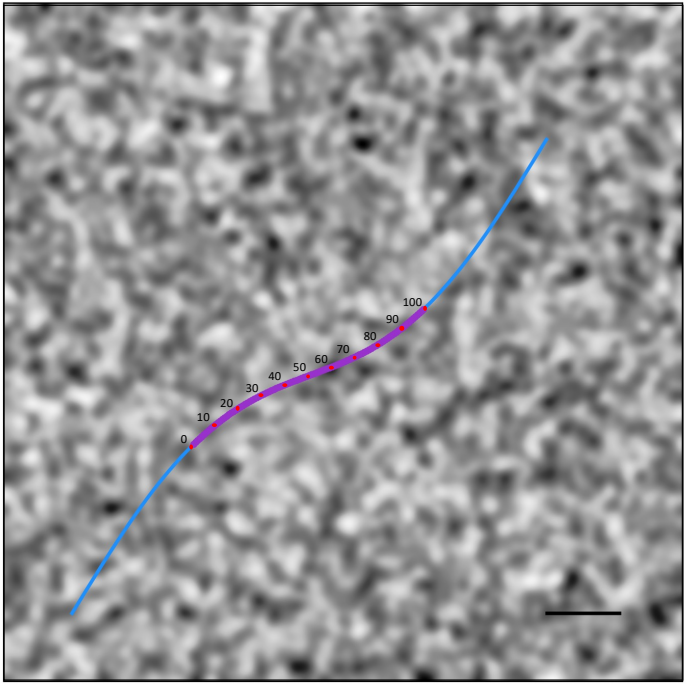
100%

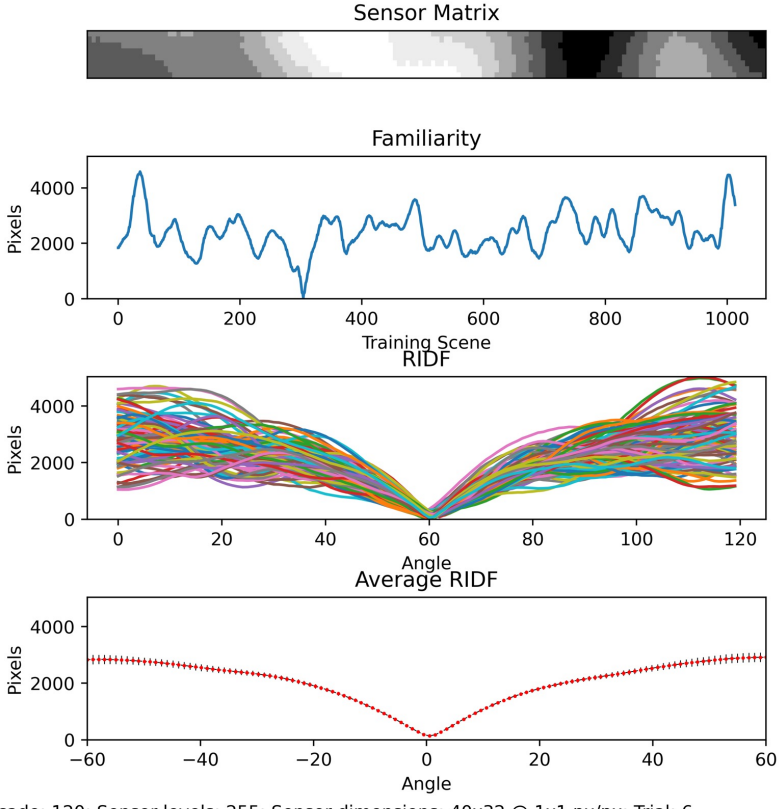




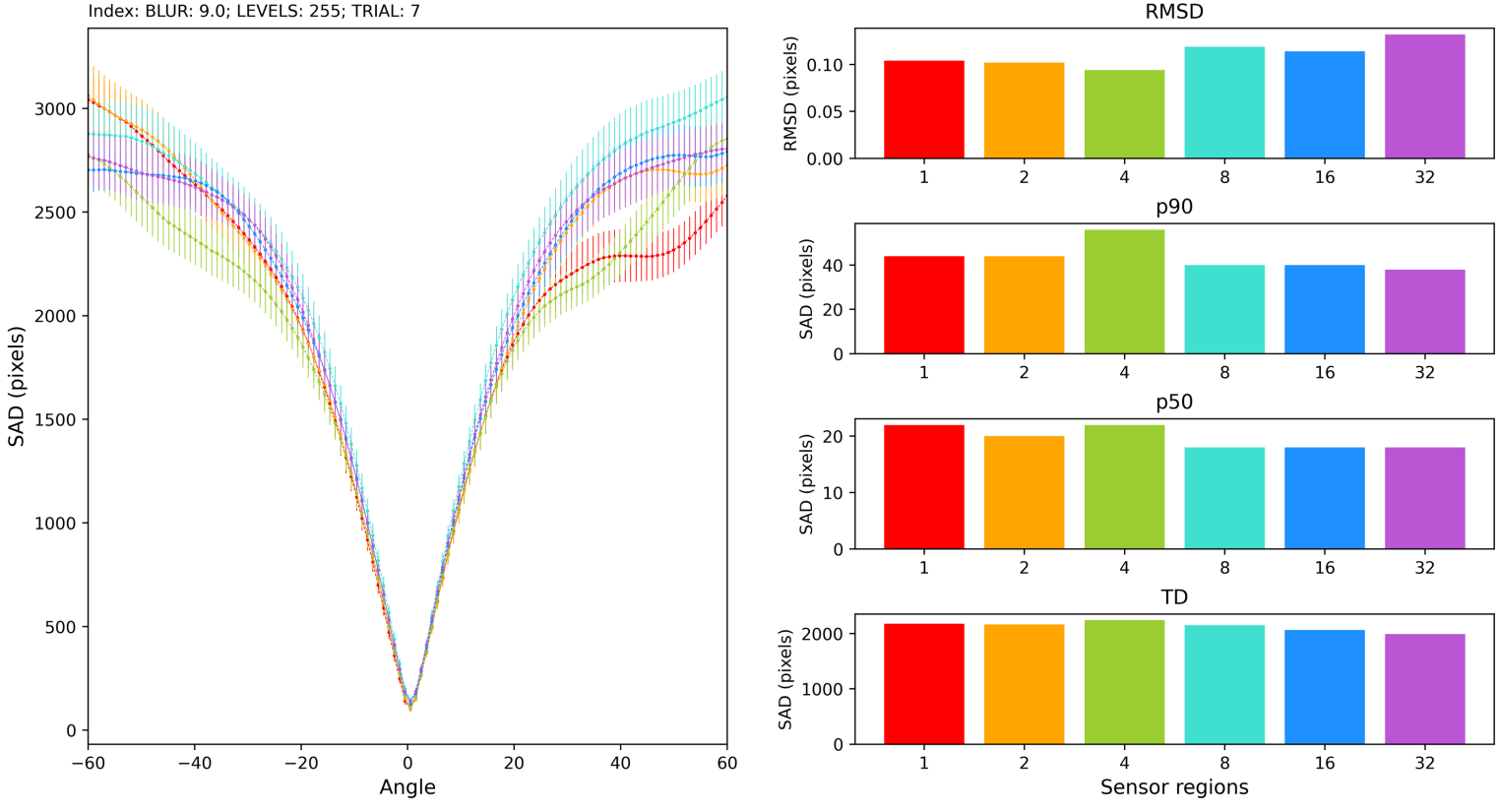
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 40.86; RMSD/dist: 0.102; TD: 2075; p90: 38; p50: 18; complete: 0

100%

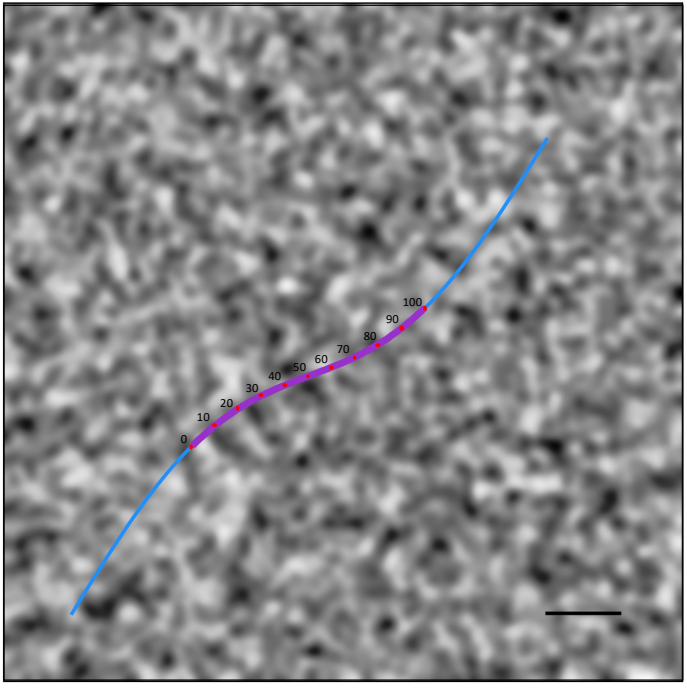


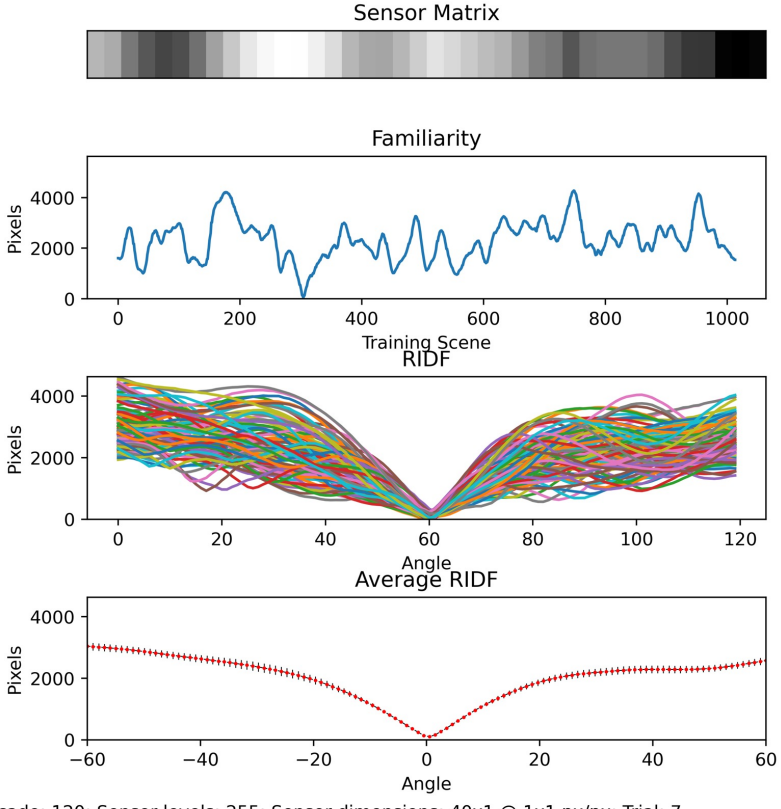


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6
Navigation stats: RMSD error: 50.20; RMSD/dist: 0.126; TD: 2091; p90: 44; p50: 22; complete: 0


Index: BLUR: 9.0; LEVELS: 255; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

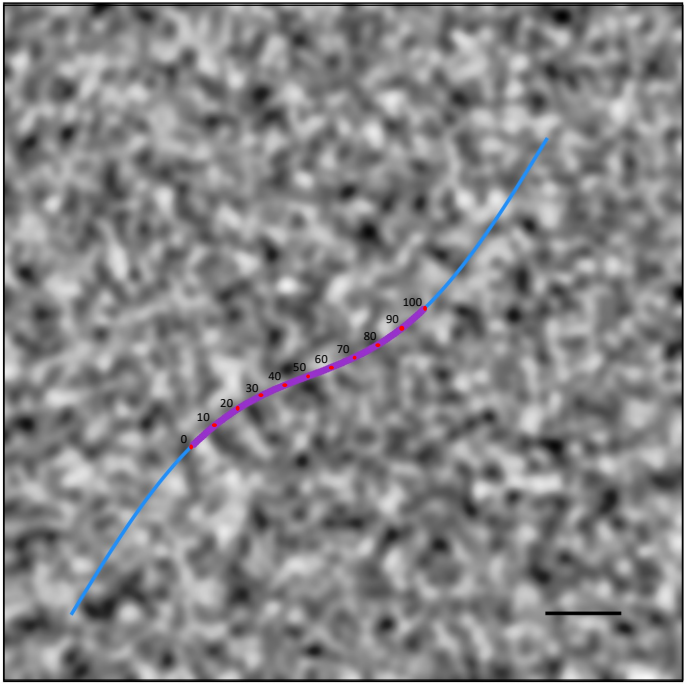
100%

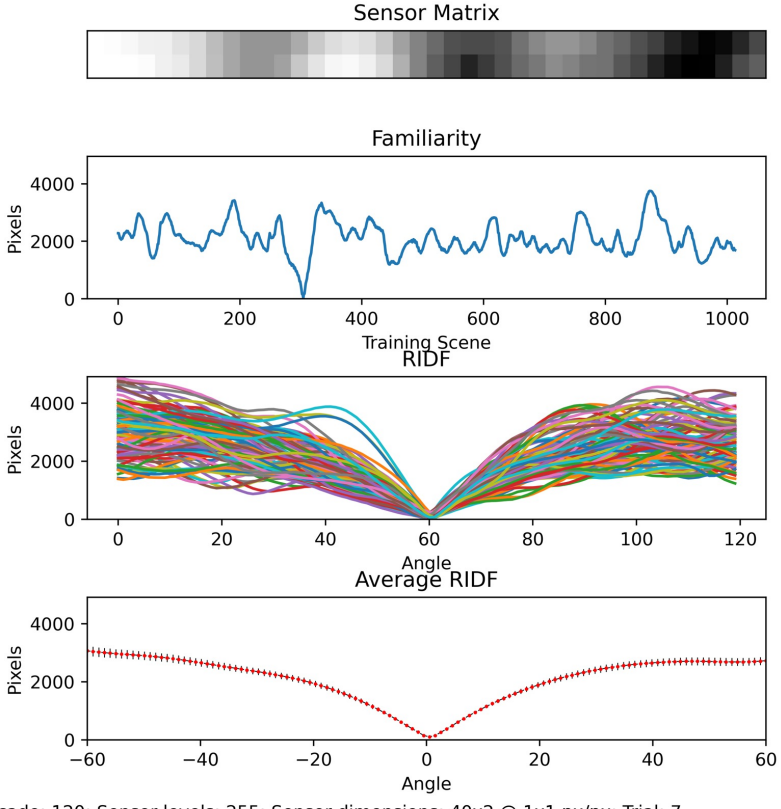




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 41.74; RMSD/dist: 0.104; TD: 2178; p90: 44; p50: 22; complete: 0

100%





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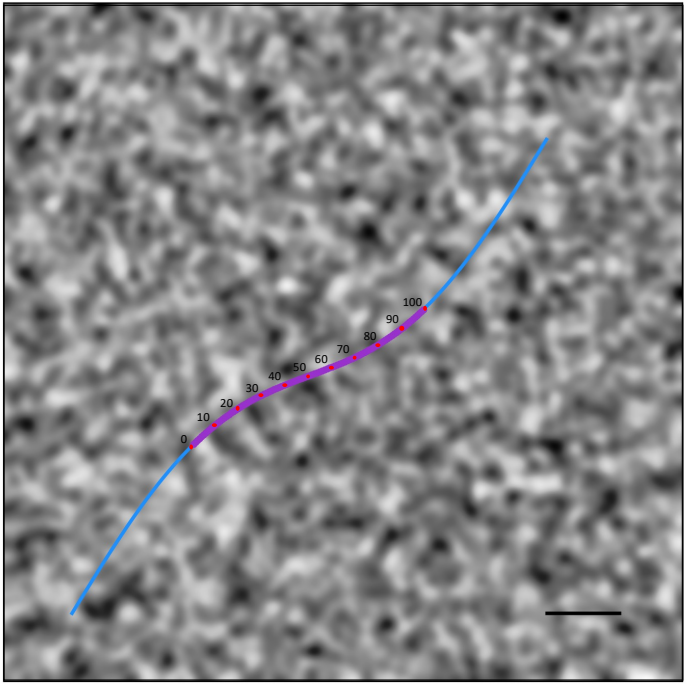
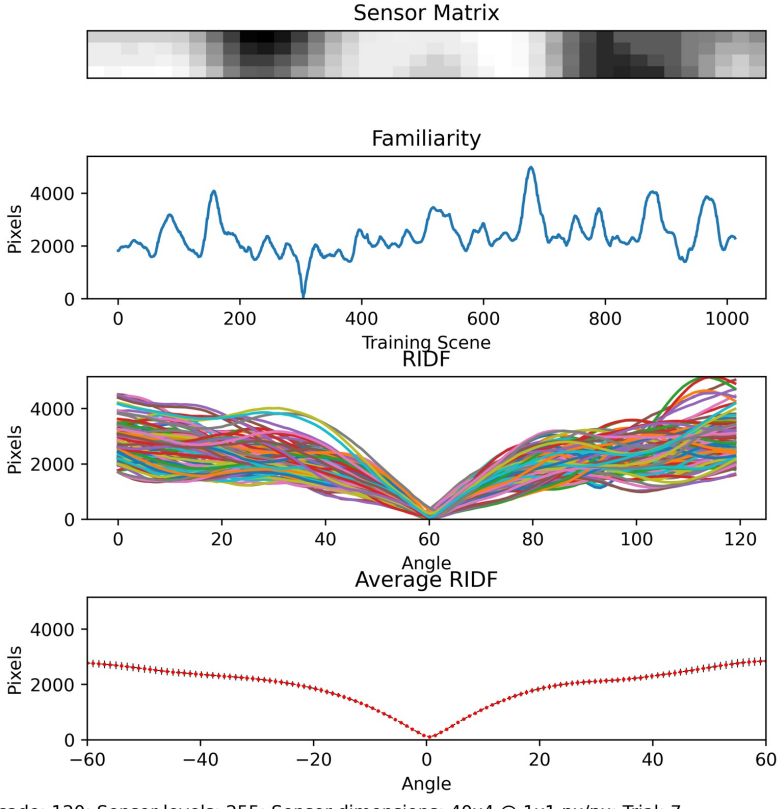
Navigation stats: RMSD error: 40.83; RMSD/dist: 0.102; TD: 2166; p90: 44; p50: 20; complete: 0

100%





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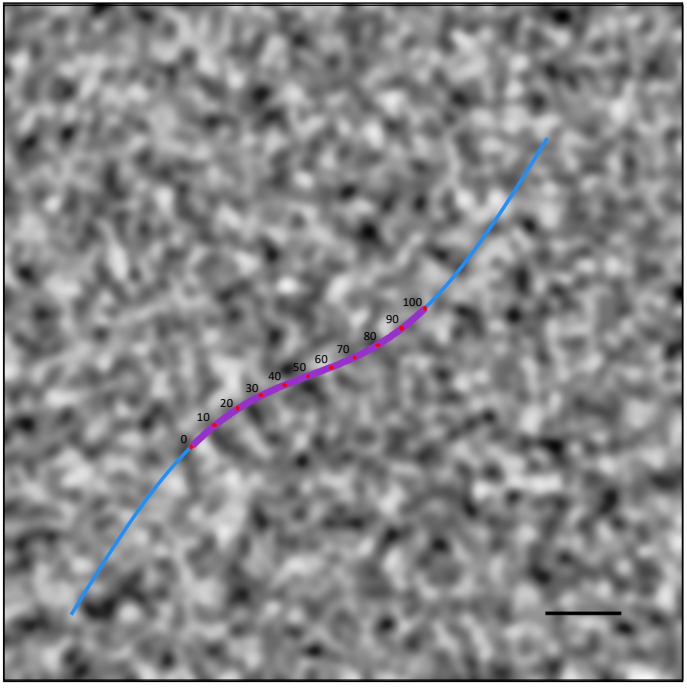
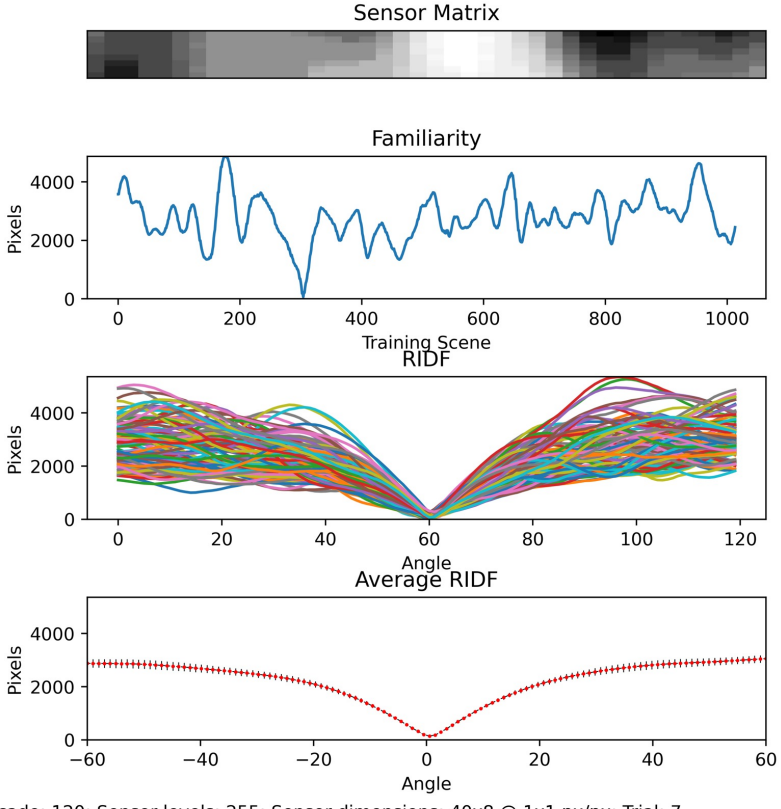
Navigation stats: RMSD error: 37.63; RMSD/dist: 0.094; TD: 2243; p90: 56; p50: 22; complete: 0

100%

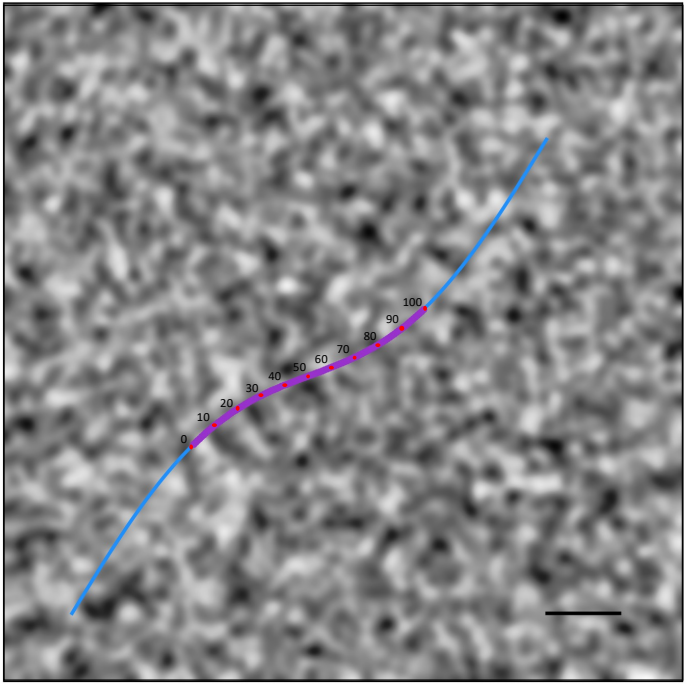


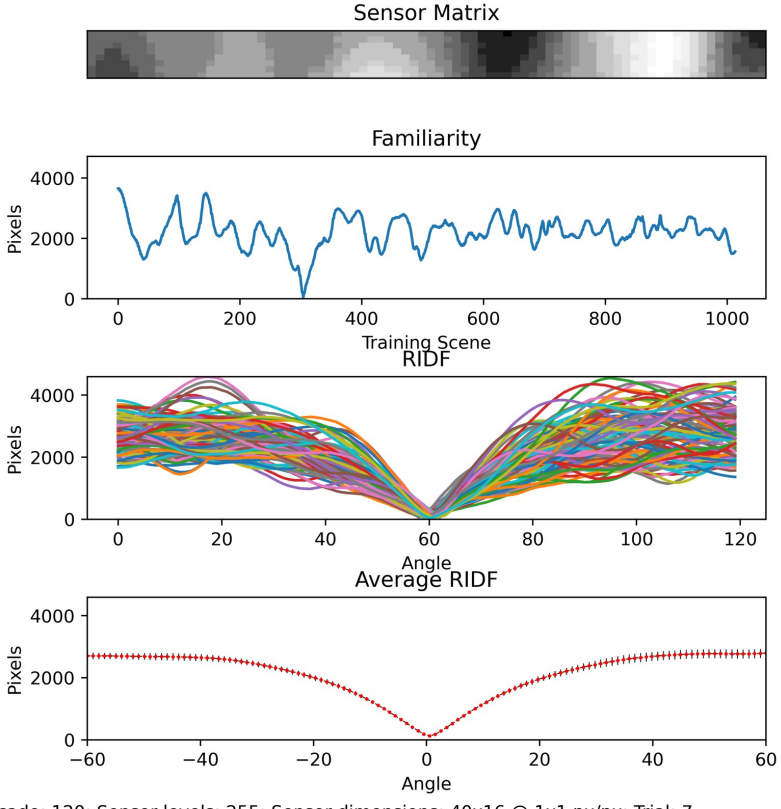


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 47.45; RMSD/dist: 0.119; TD: 2153; p90: 40; p50: 18; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7
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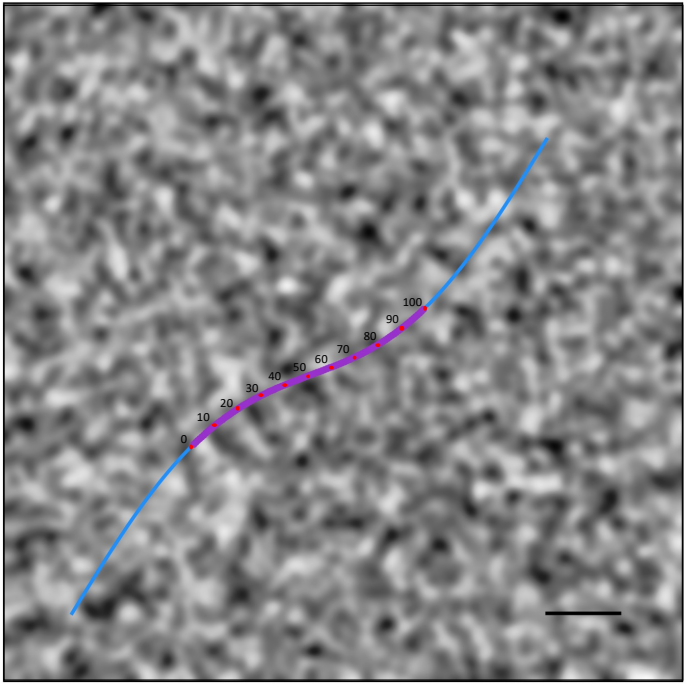
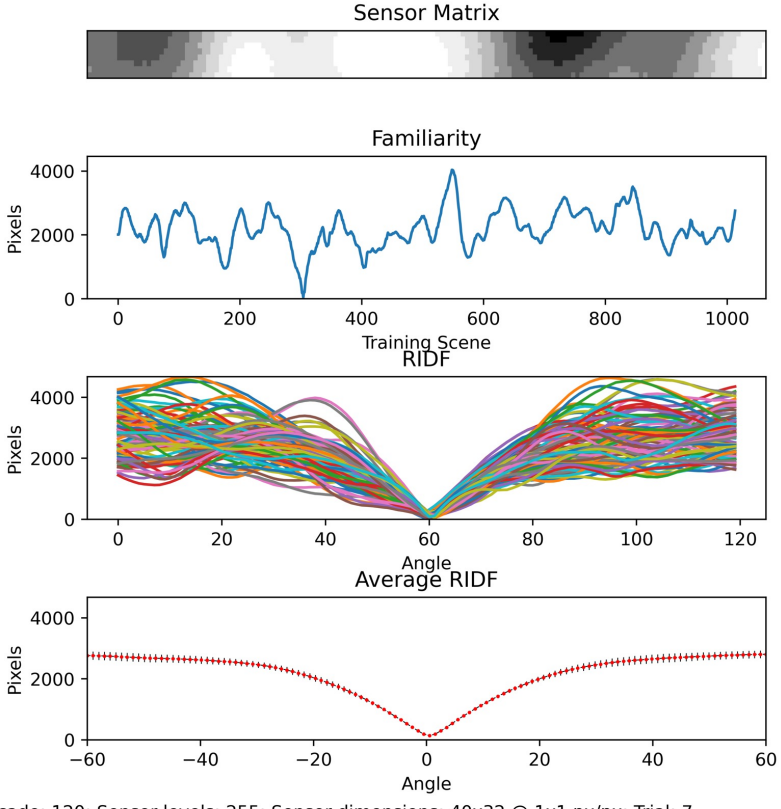
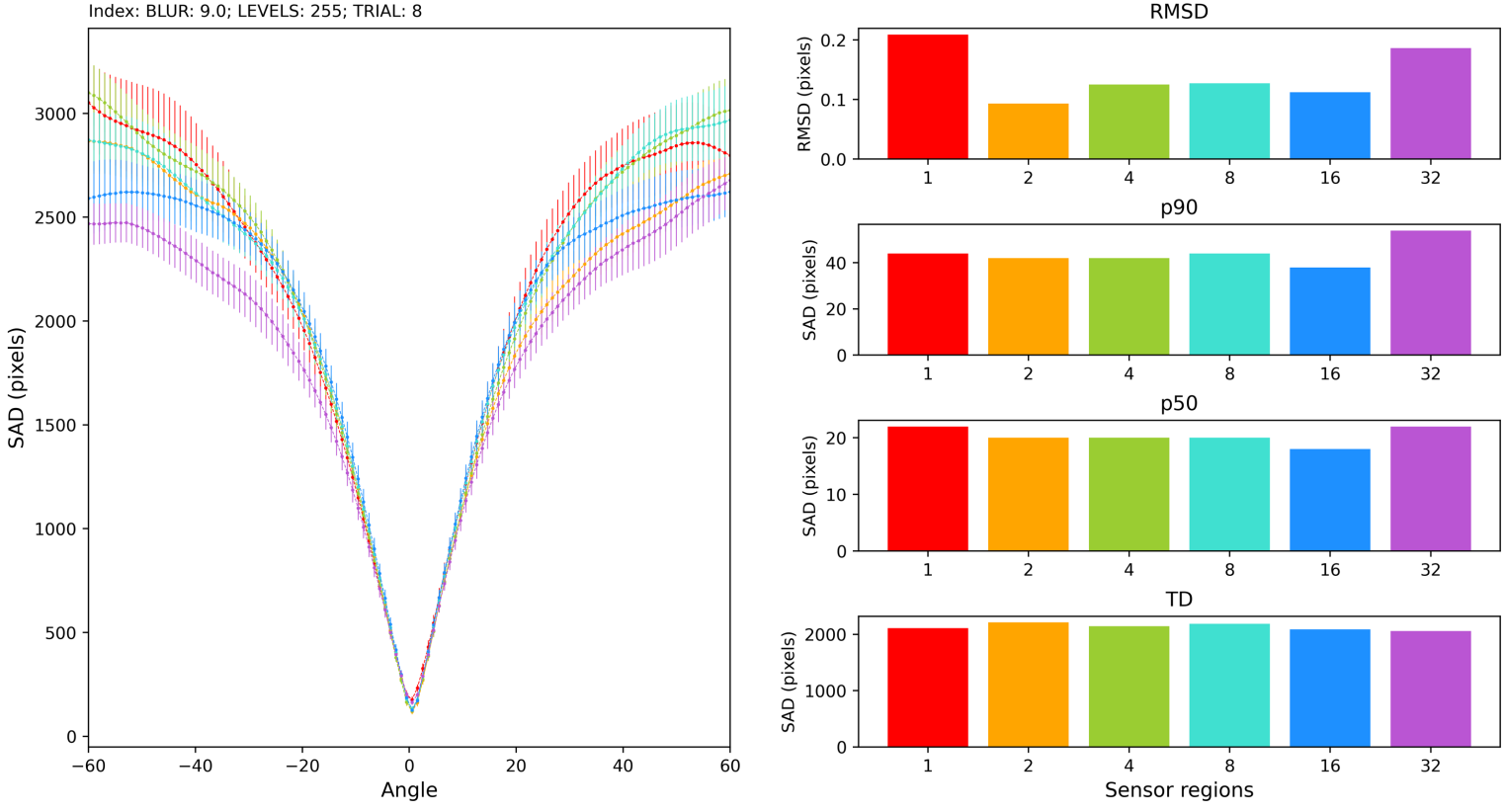
100%

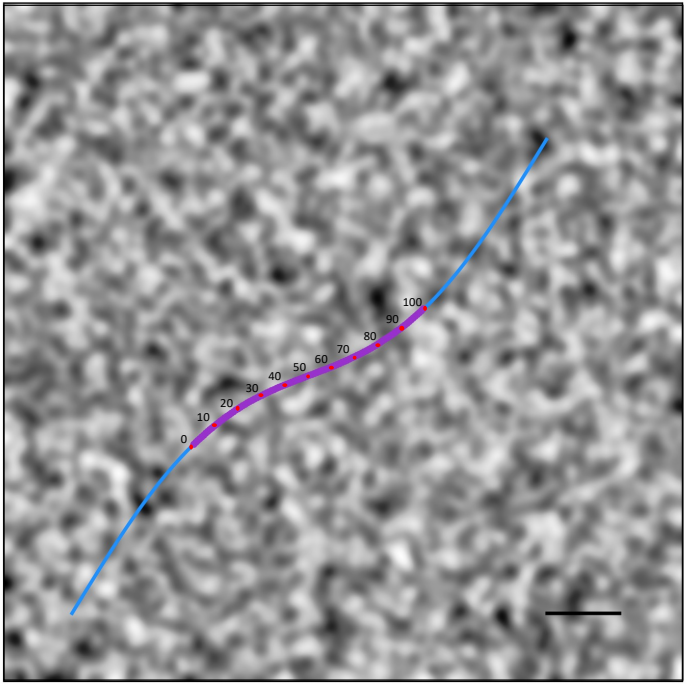


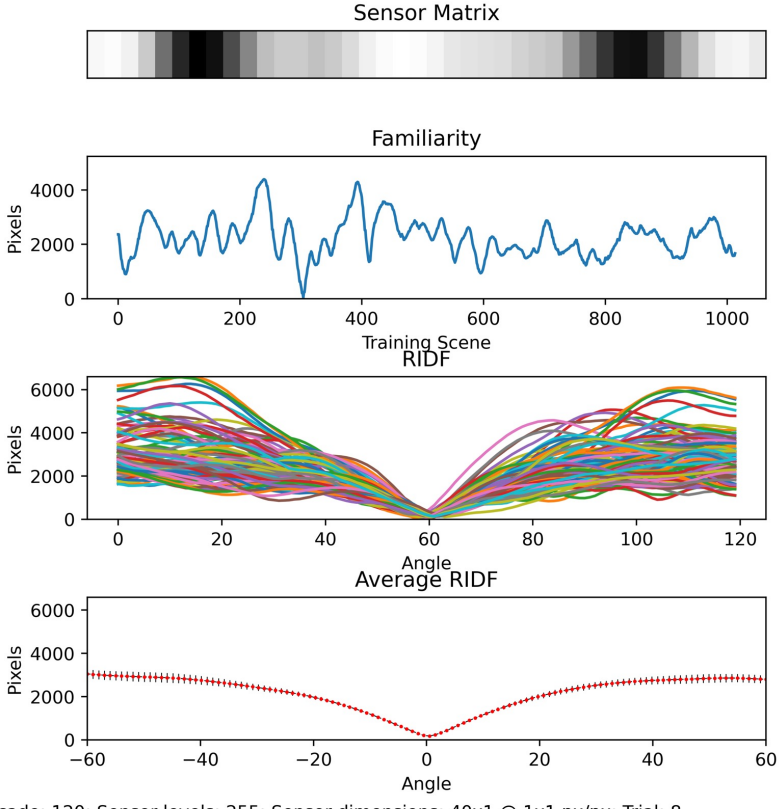


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7
Navigation stats: RMSD error: 52.78; RMSD/dist: 0.132; TD: 1991; p90: 38; p50: 18; complete: 0


Index: BLUR: 9.0; LEVELS: 255; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

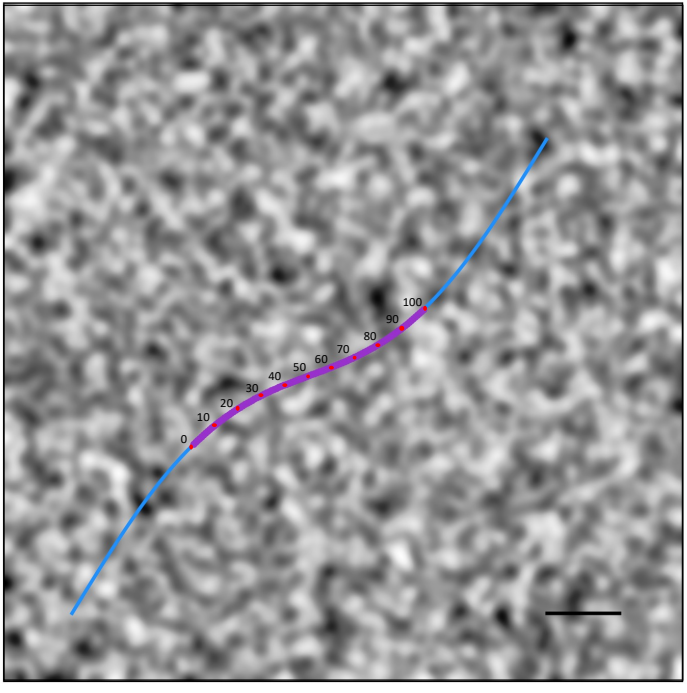
100%

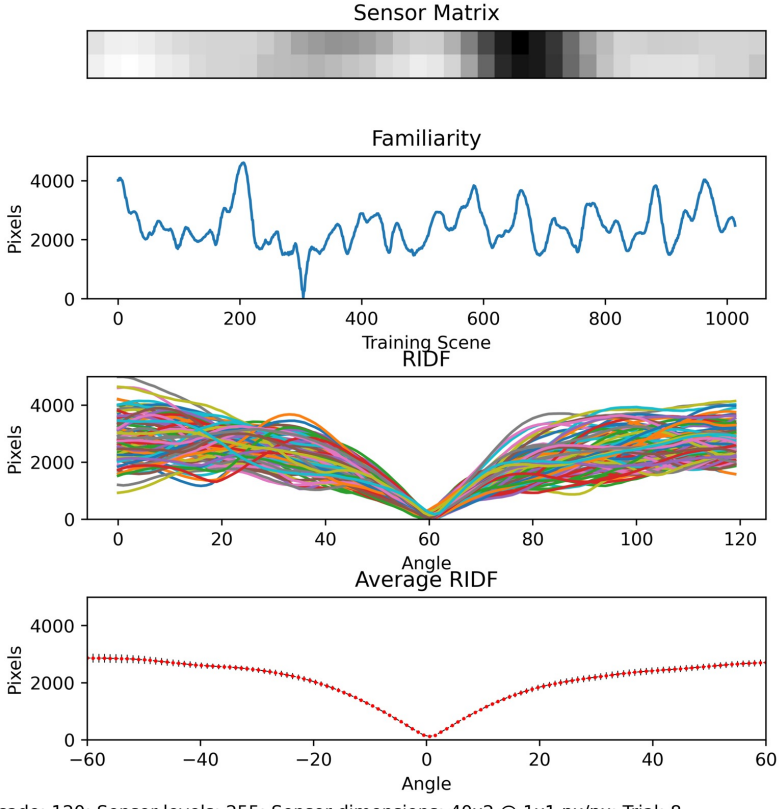




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 83.64; RMSD/dist: 0.209; TD: 2109; p90: 44; p50: 22; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 37.25; RMSD/dist: 0.093; TD: 2210; p90: 42; p50: 20; complete: 0

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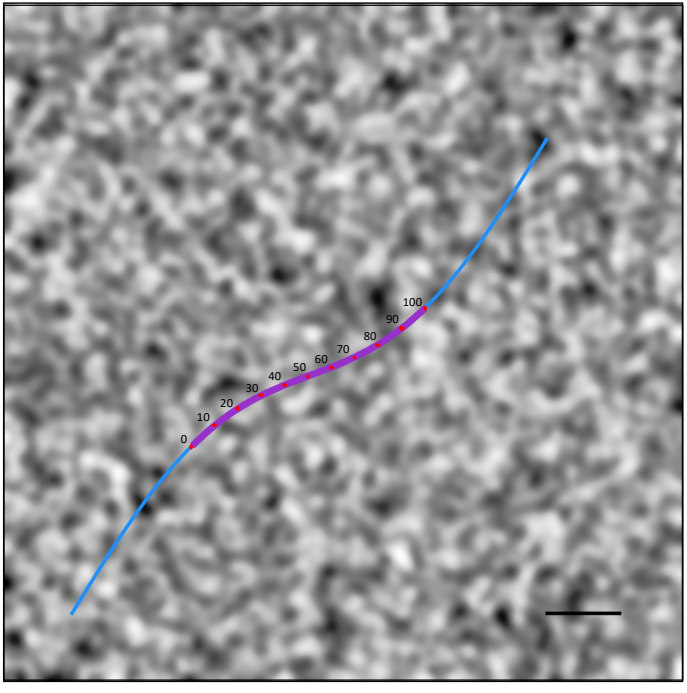

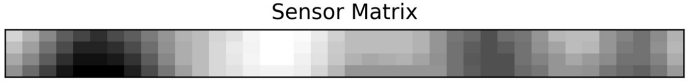

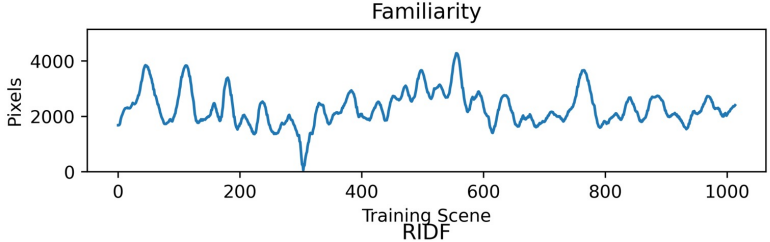

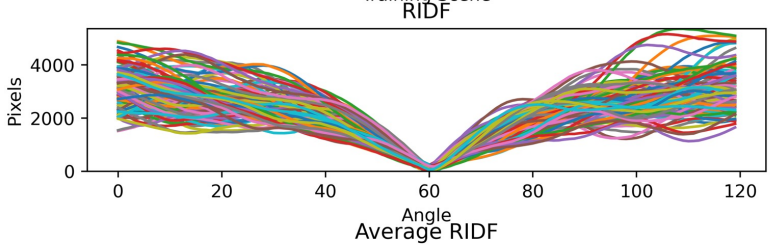

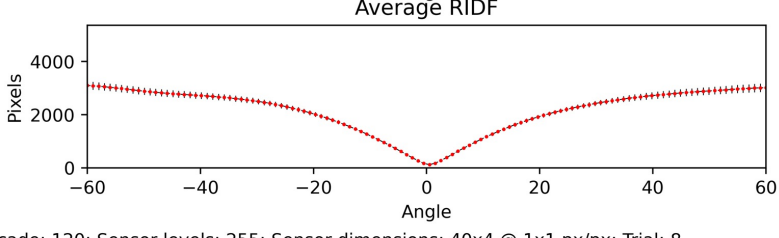

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8
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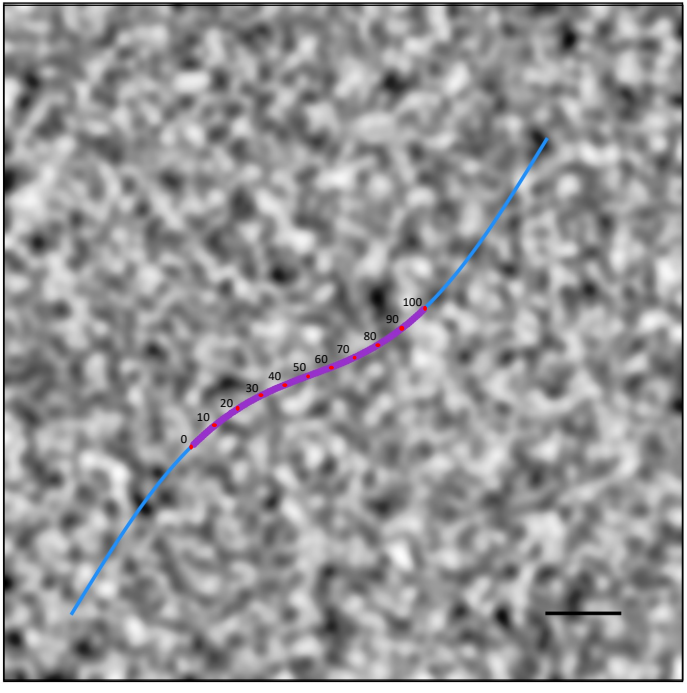
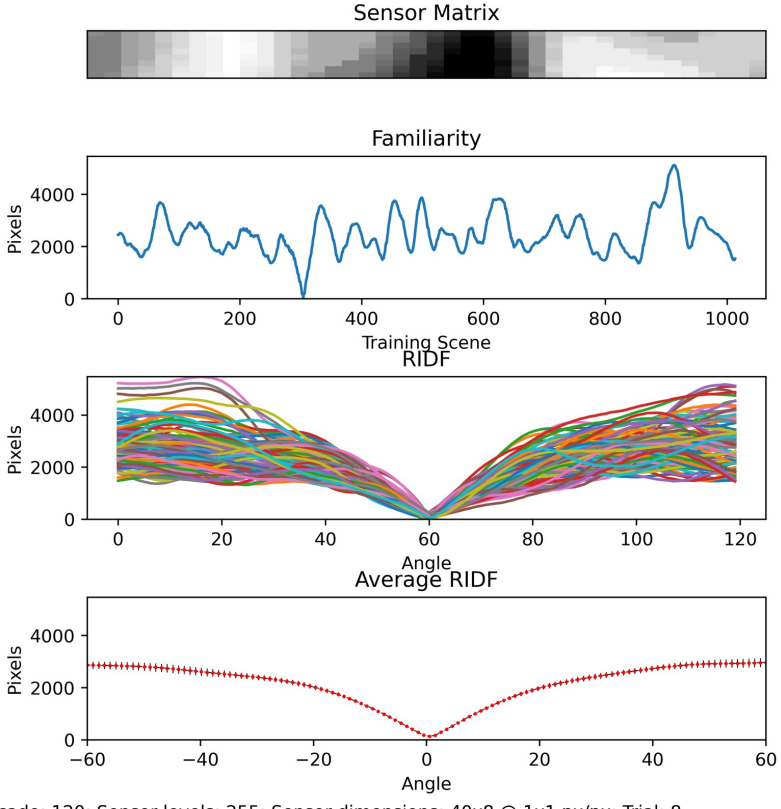
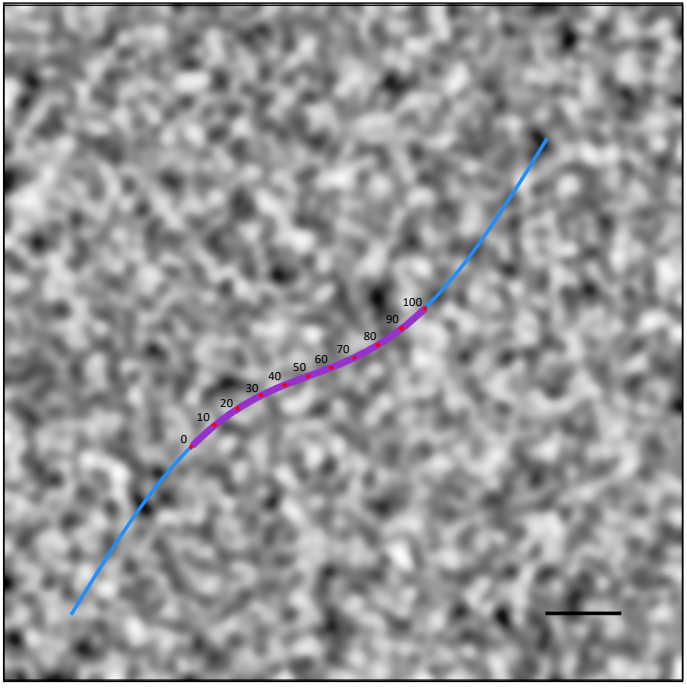
100%

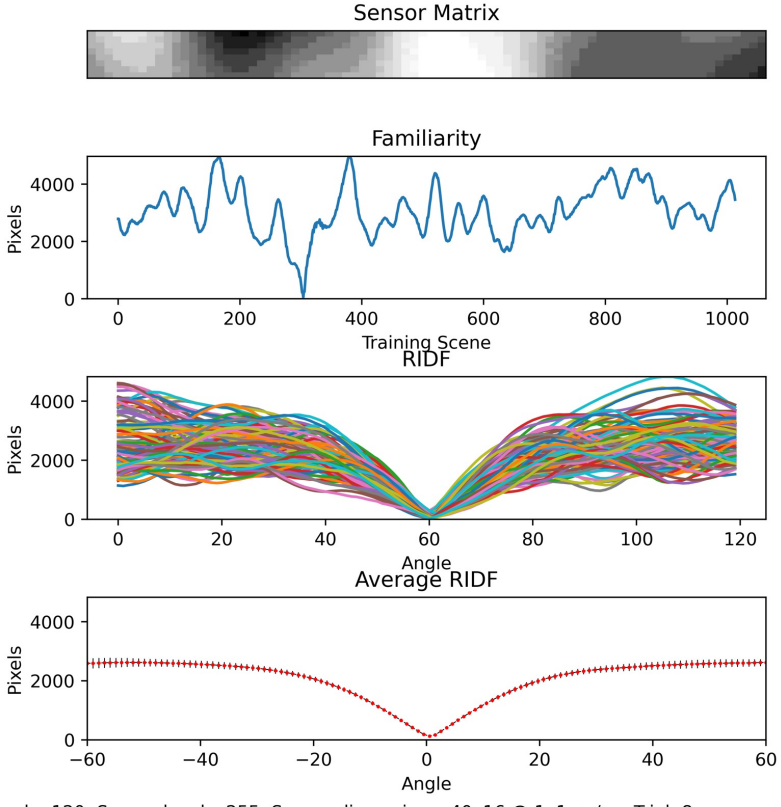




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 50.73; RMSD/dist: 0.127; TD: 2188; p90: 44; p50: 20; complete: 0

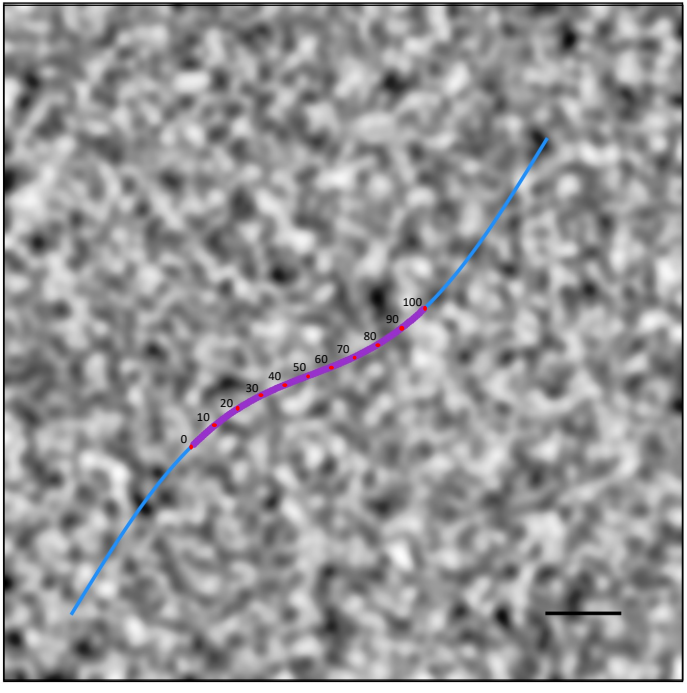
100%

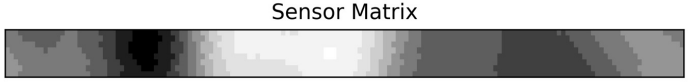


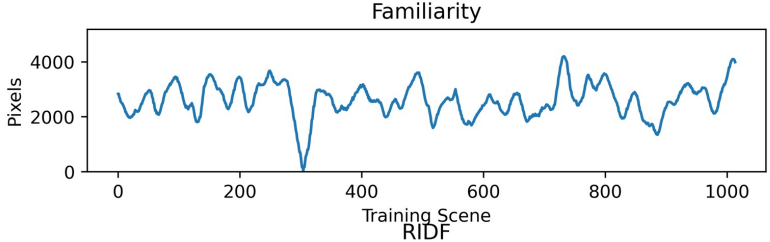


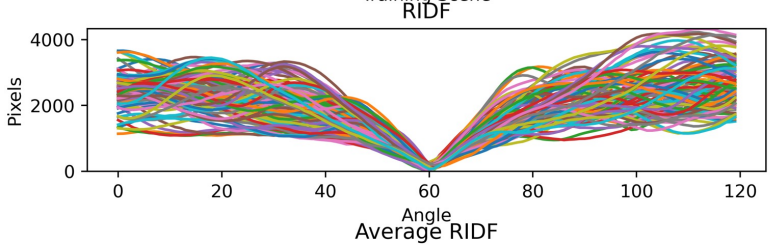
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 44.79; RMSD/dist: 0.112; TD: 2089; p90: 38; p50: 18; complete: 0

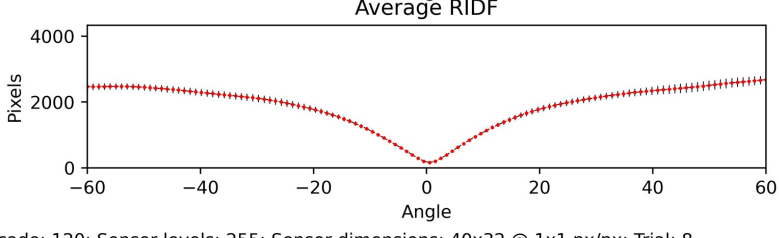
100%



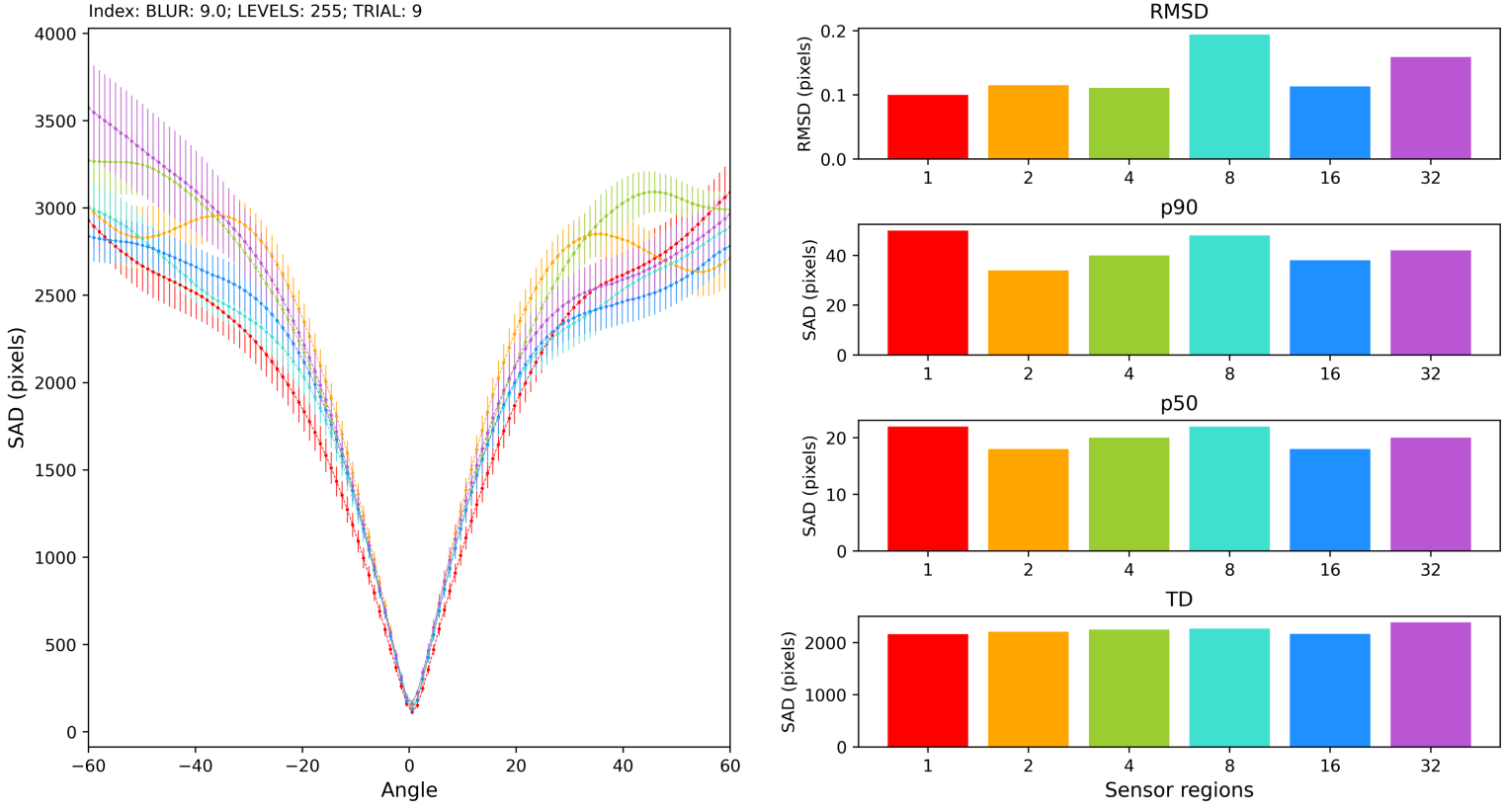




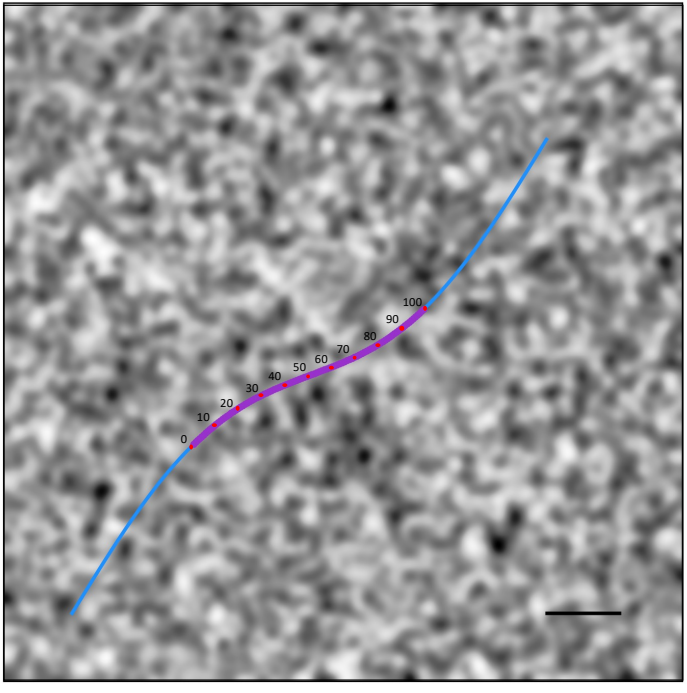


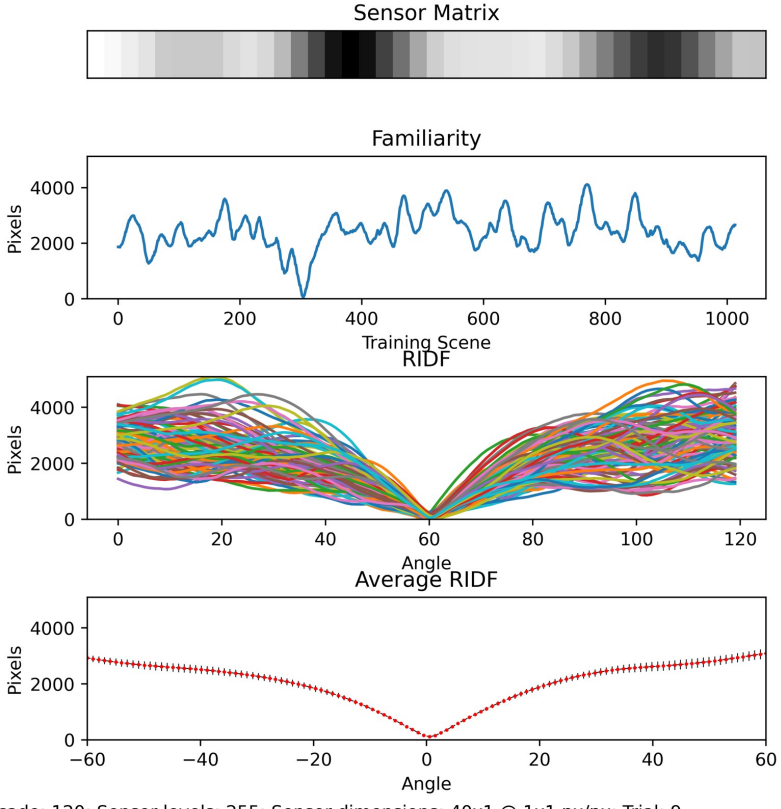


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8
Navigation stats: RMSD error: 74.46; RMSD/dist: 0.186; TD: 2060; p90: 54; p50: 22; complete: 0


Index: BLUR: 9.0; LEVELS: 255; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

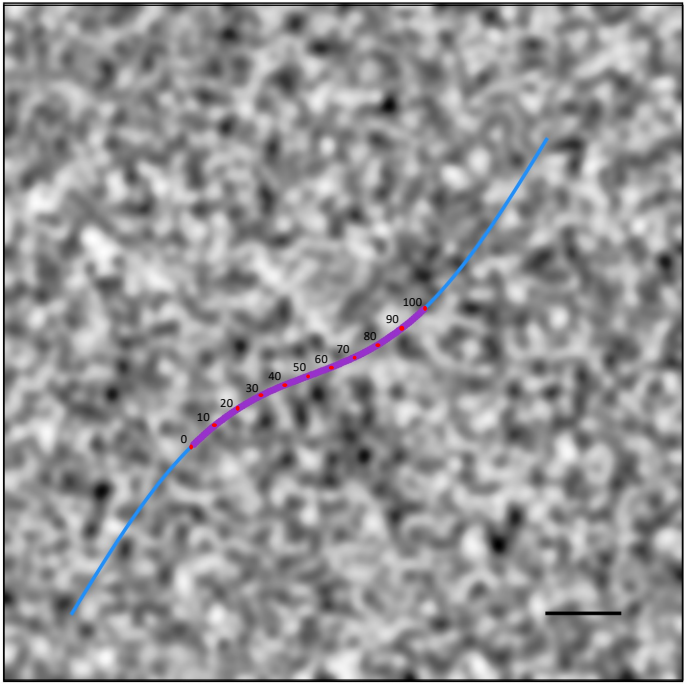
100%

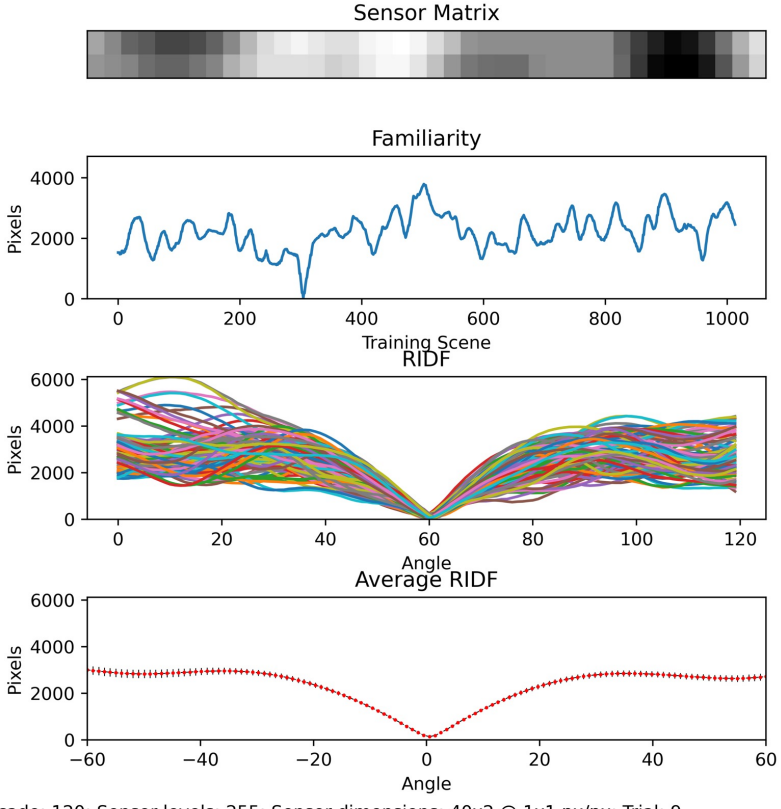




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 40.08; RMSD/dist: 0.100; TD: 2165; p90: 50; p50: 22; complete: 0

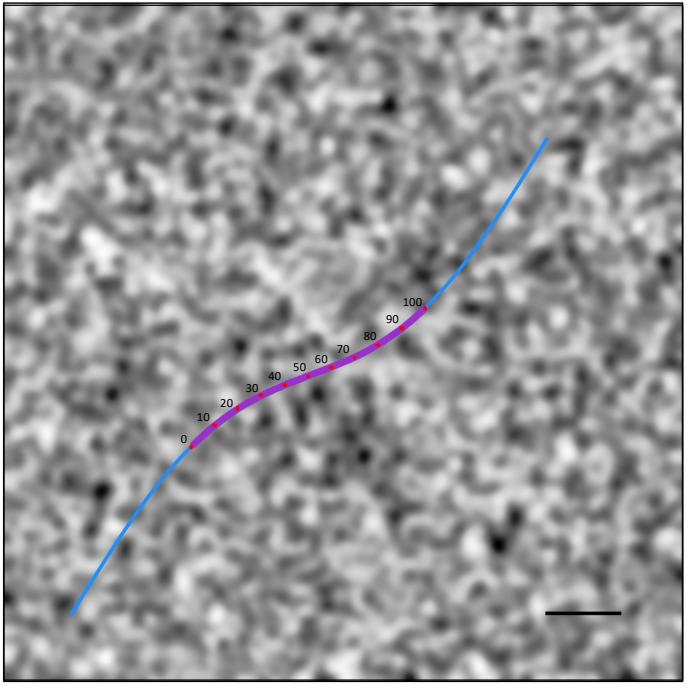
100%

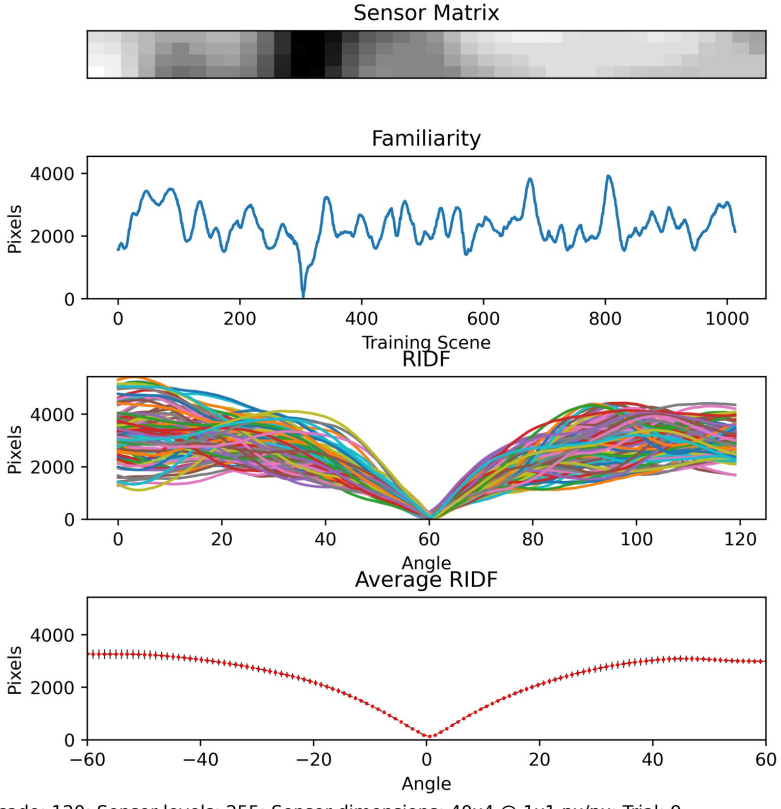




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 46.14; RMSD/dist: 0.115; TD: 2209; p90: 34; p50: 18; complete: 0

100%





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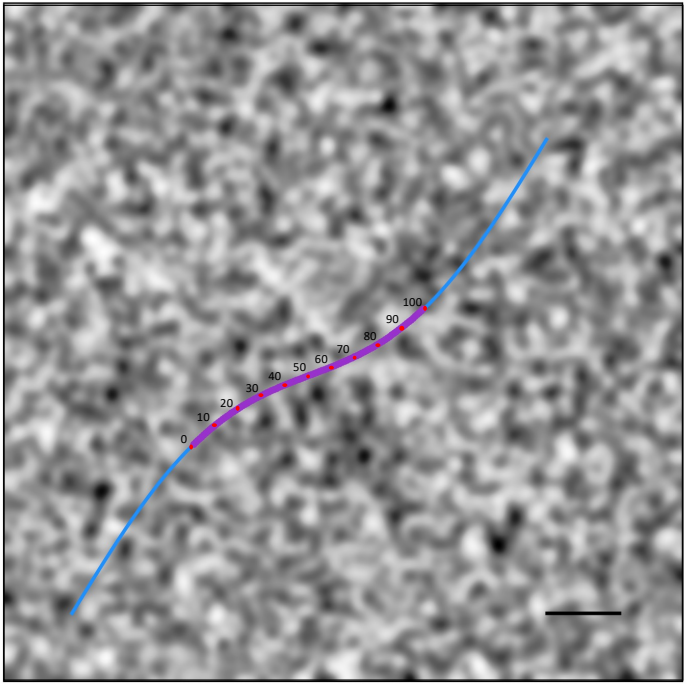
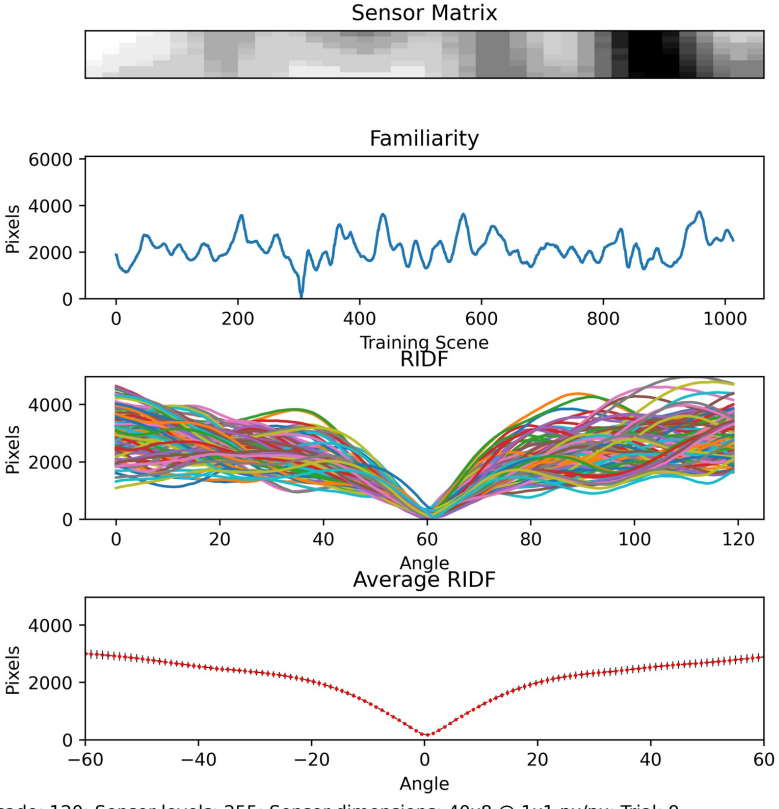
Navigation stats: RMSD error: 44.45; RMSD/dist: 0.111; TD: 2253; p90: 40; p50: 20; complete: 0

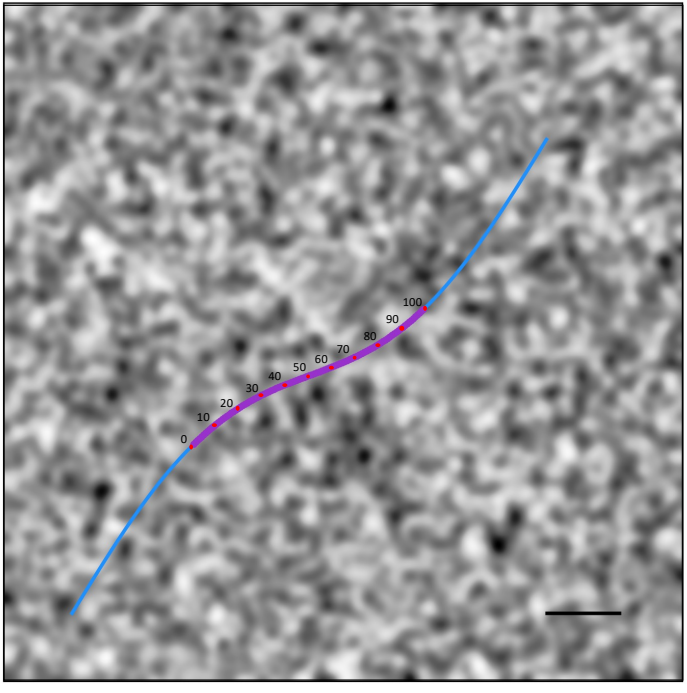
100%

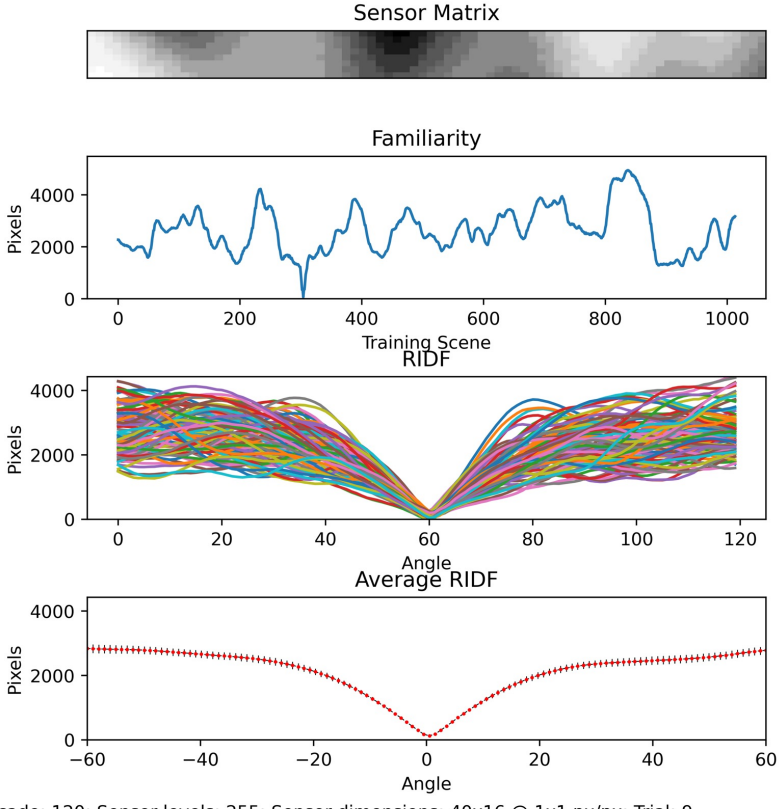




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 77.60; RMSD/dist: 0.194; TD: 2269; p90: 48; p50: 22; complete: 0

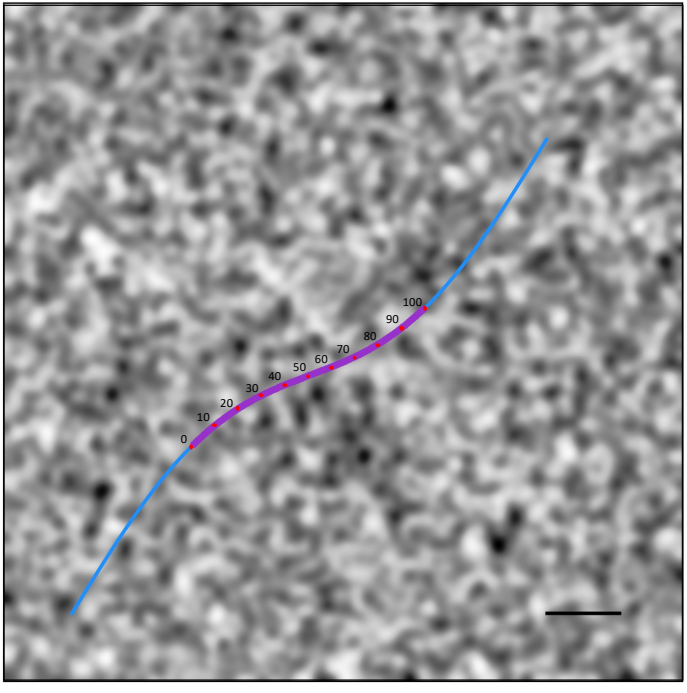
100%

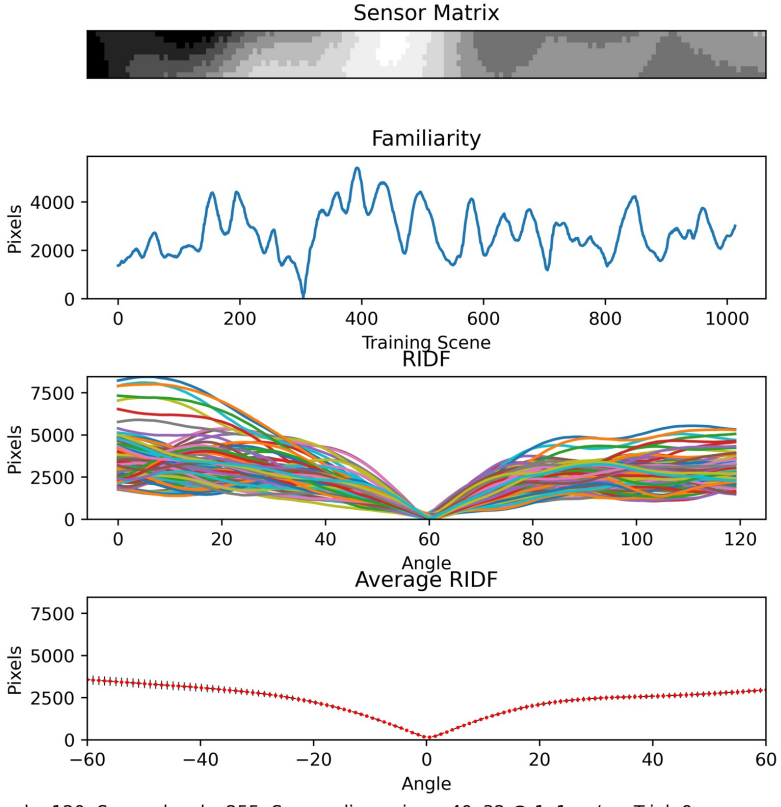




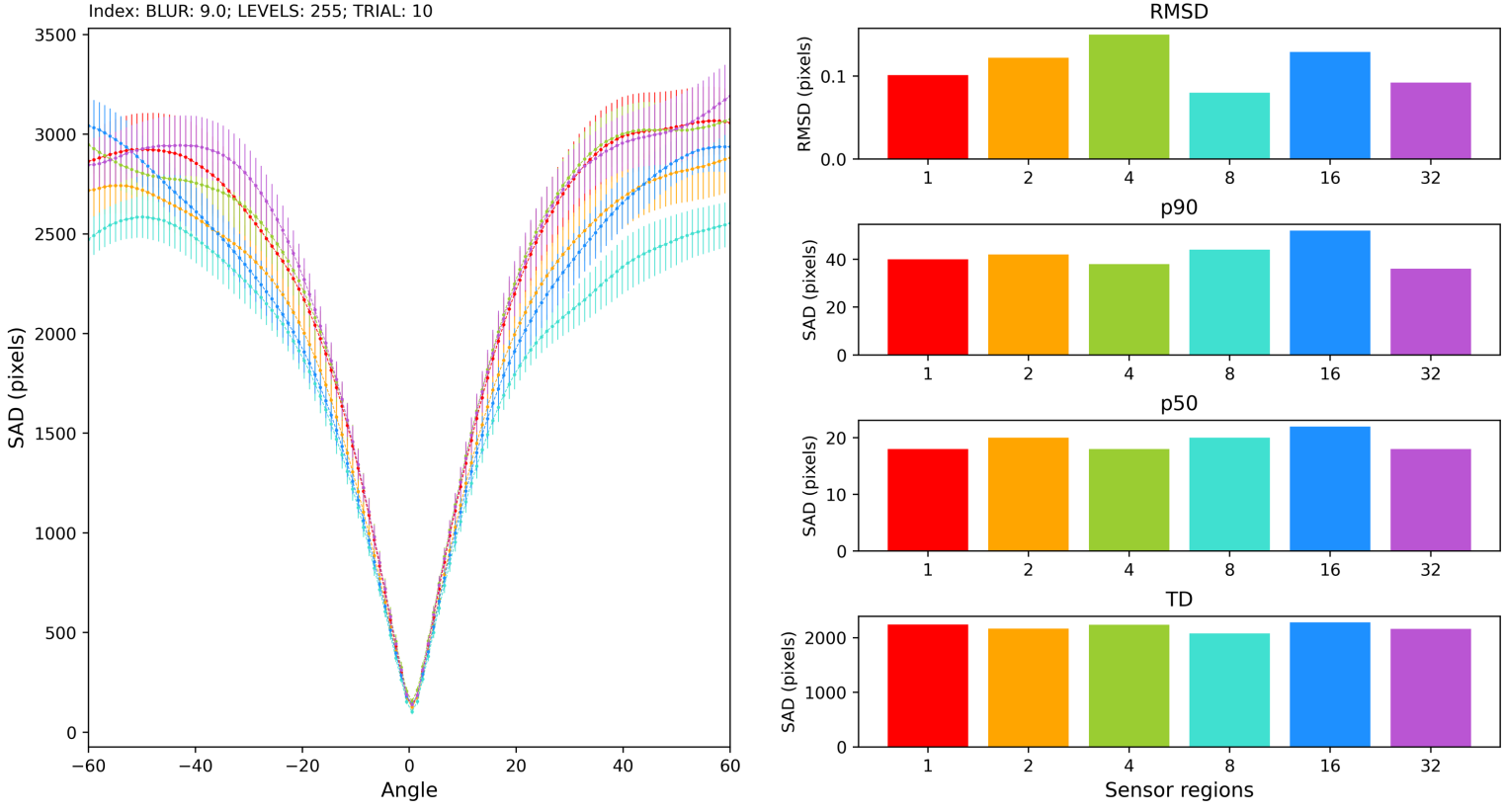
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 45.16; RMSD/dist: 0.113; TD: 2167; p90: 38; p50: 18; complete: 0

100%

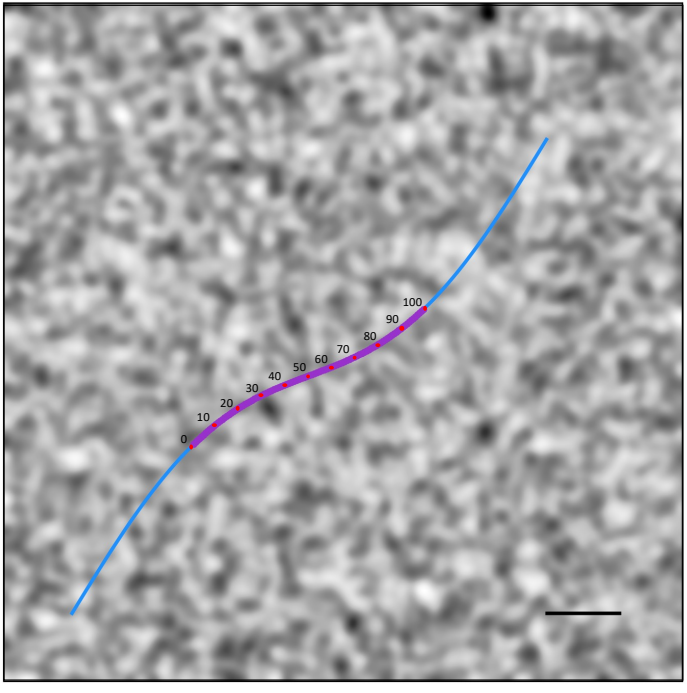


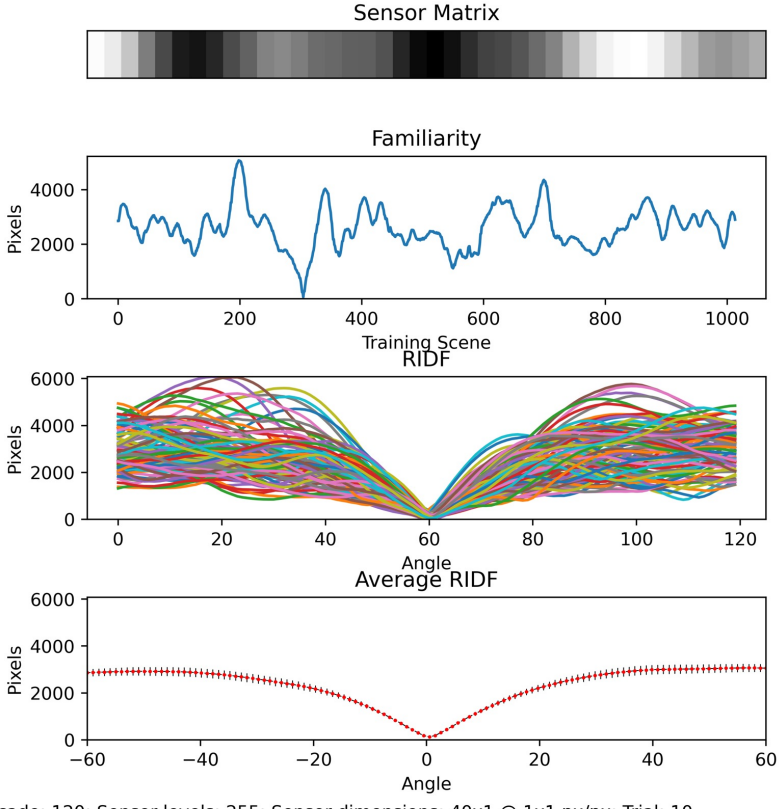


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9
Navigation stats: RMSD error: 63.53; RMSD/dist: 0.159; TD: 2388; p90: 42; p50: 20; complete: 0


Index: BLUR: 9.0; LEVELS: 255; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

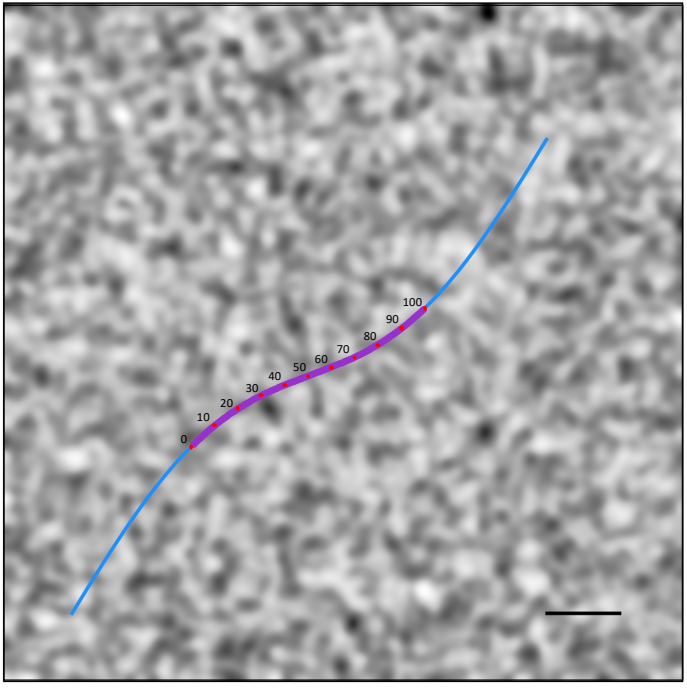
100%

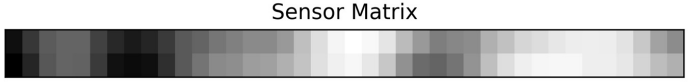


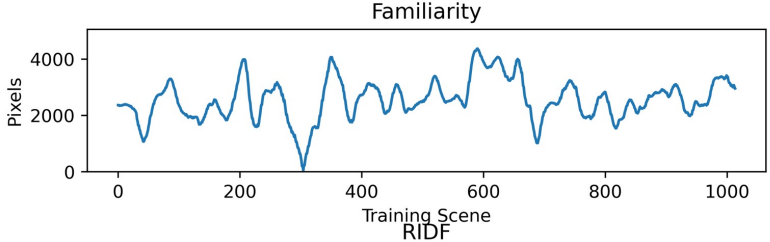


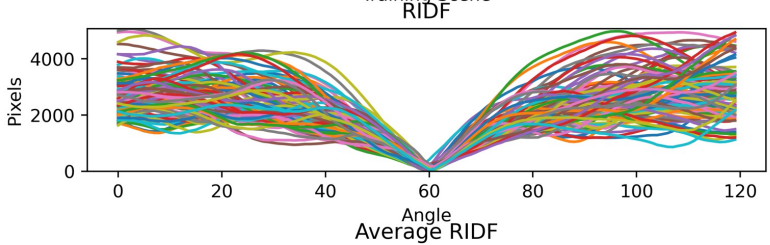
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 40.58; RMSD/dist: 0.101; TD: 2241; p90: 40; p50: 18; complete: 0

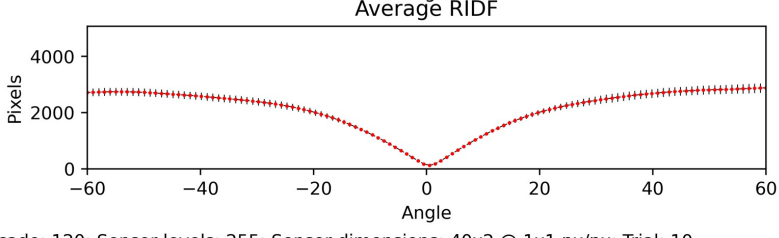
100%





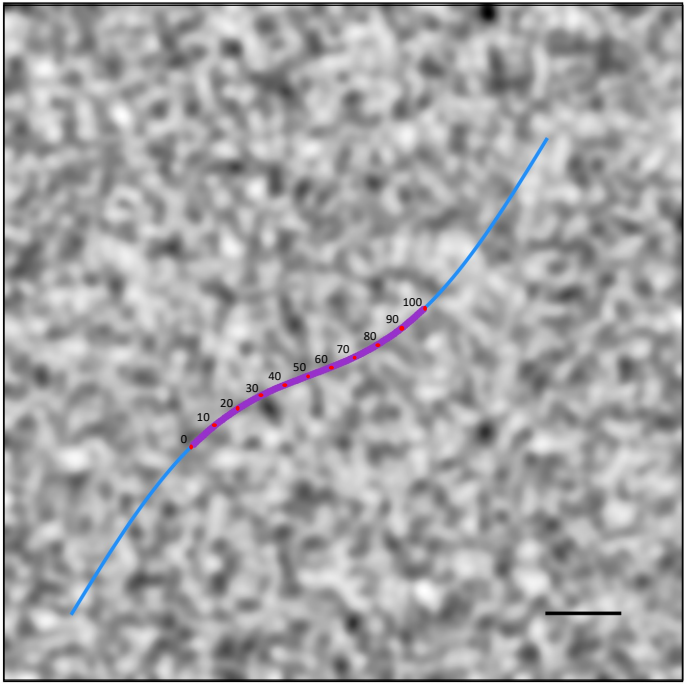


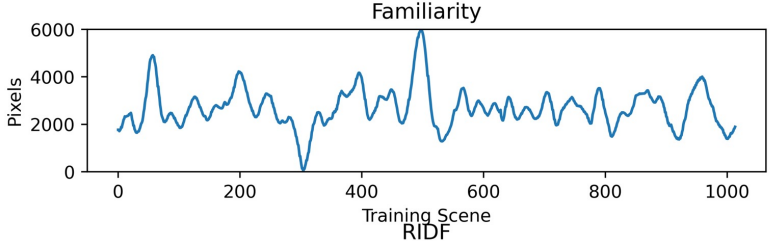


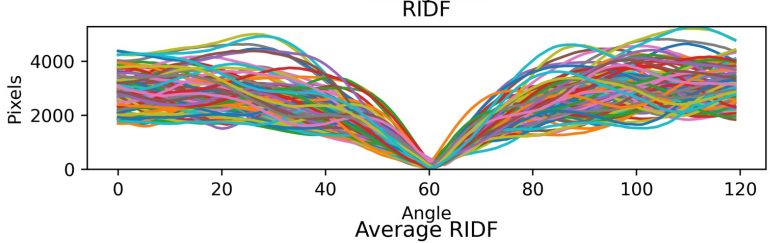


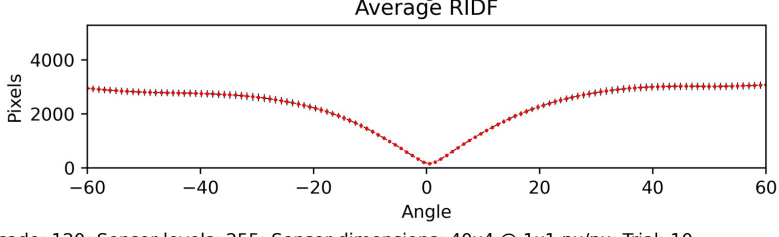
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 48.87; RMSD/dist: 0.122; TD: 2165; p90: 42; p50: 20; complete: 0

100%



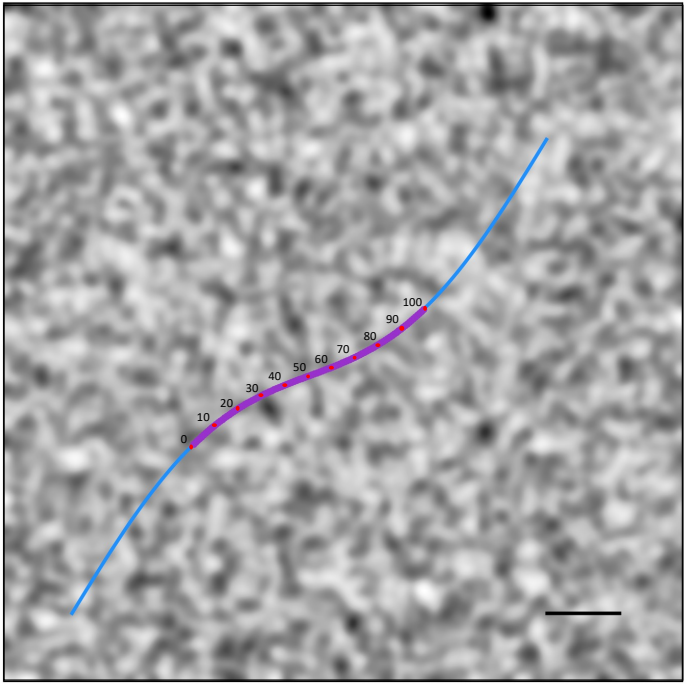


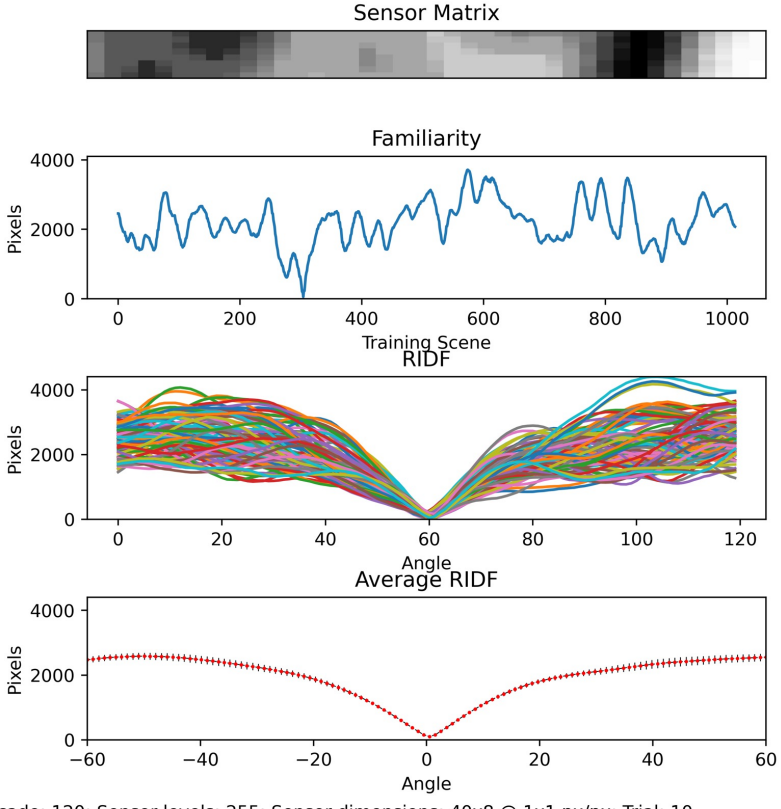




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 59.96; RMSD/dist: 0.150; TD: 2236; p90: 38; p50: 18; complete: 0

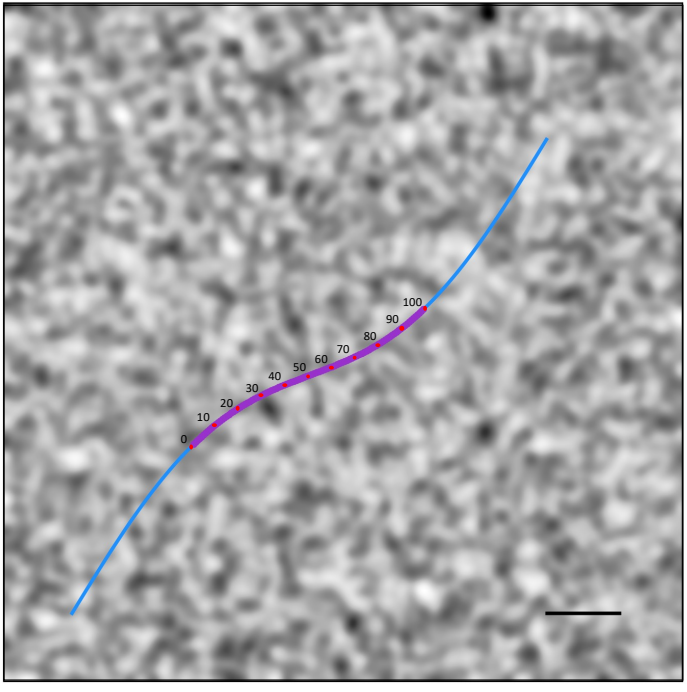
100%

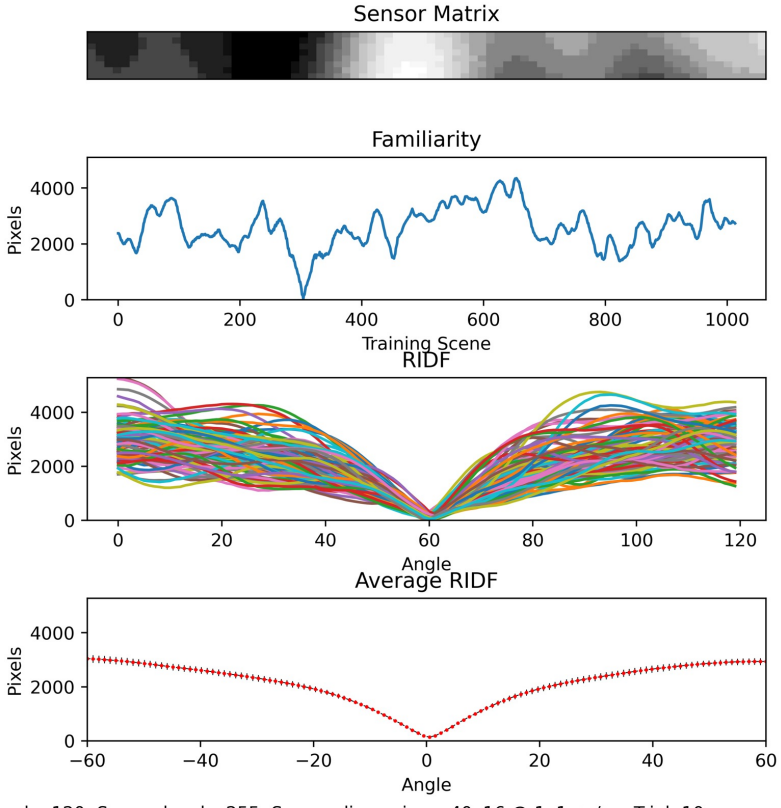




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 31.83; RMSD/dist: 0.080; TD: 2078; p90: 44; p50: 20; complete: 0

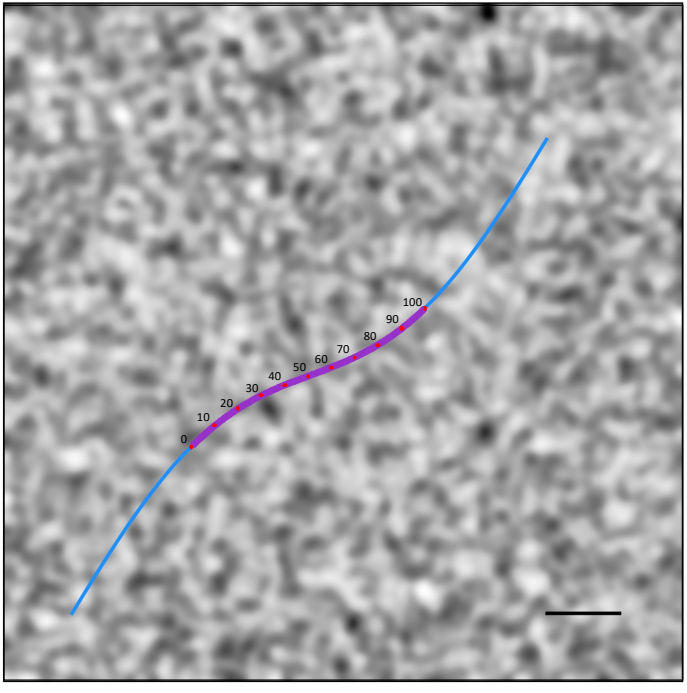
100%

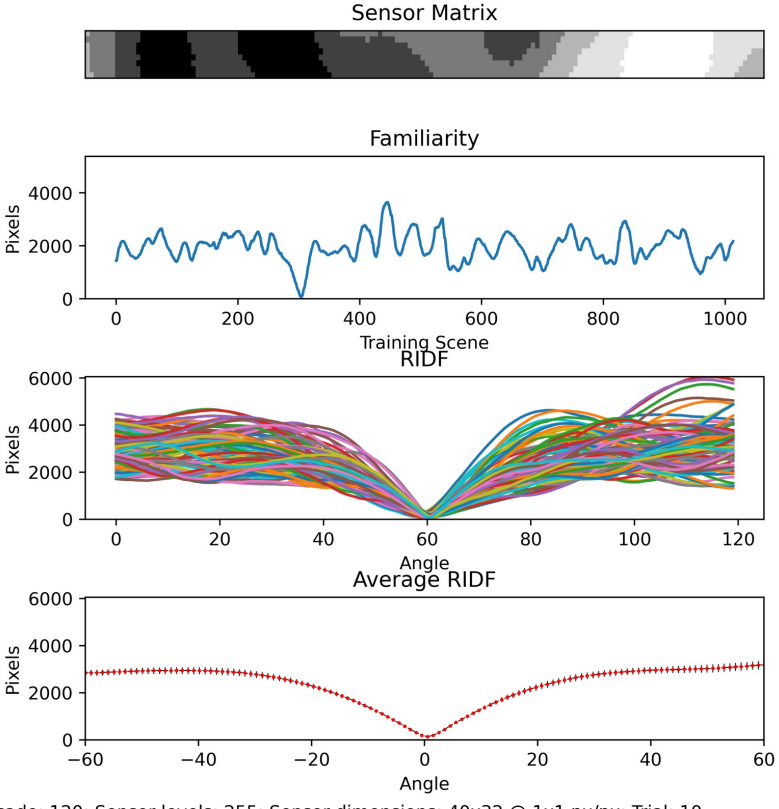




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 51.69; RMSD/dist: 0.129; TD: 2279; p90: 52; p50: 22; complete: 0

100%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 9; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 255; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10
Navigation stats: RMSD error: 36.93; RMSD/dist: 0.092; TD: 2160; p90: 36; p50: 18; complete: 0