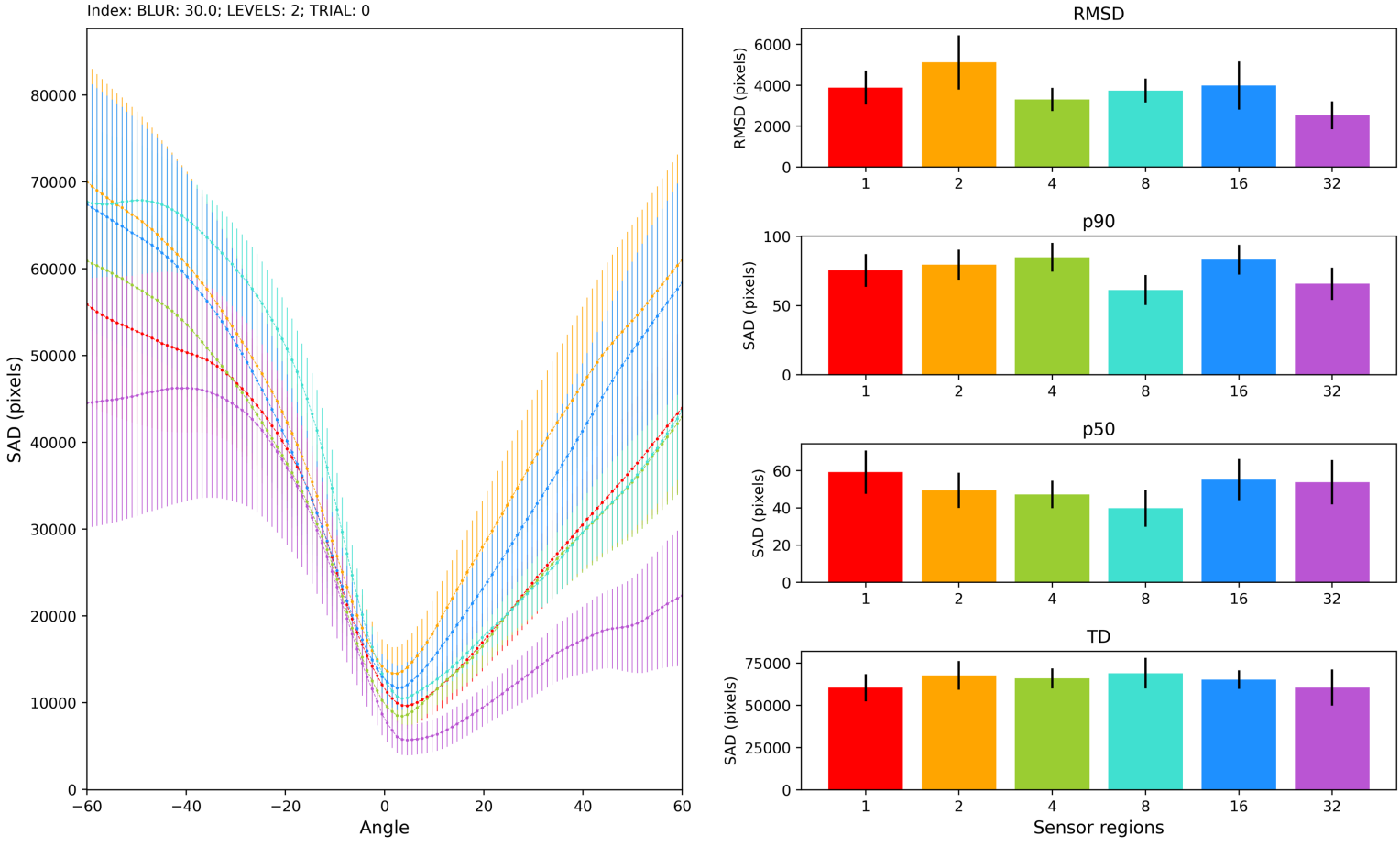
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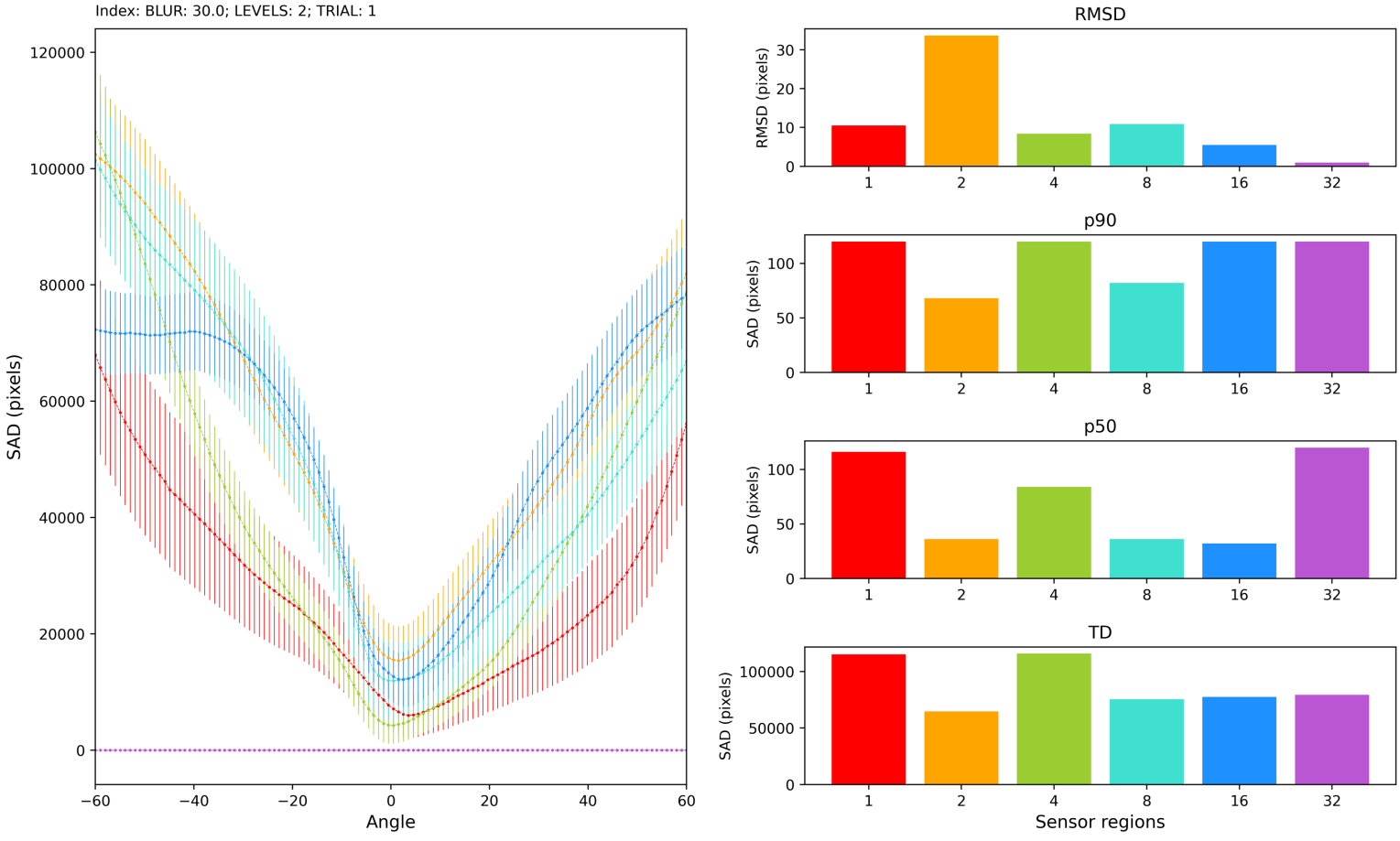
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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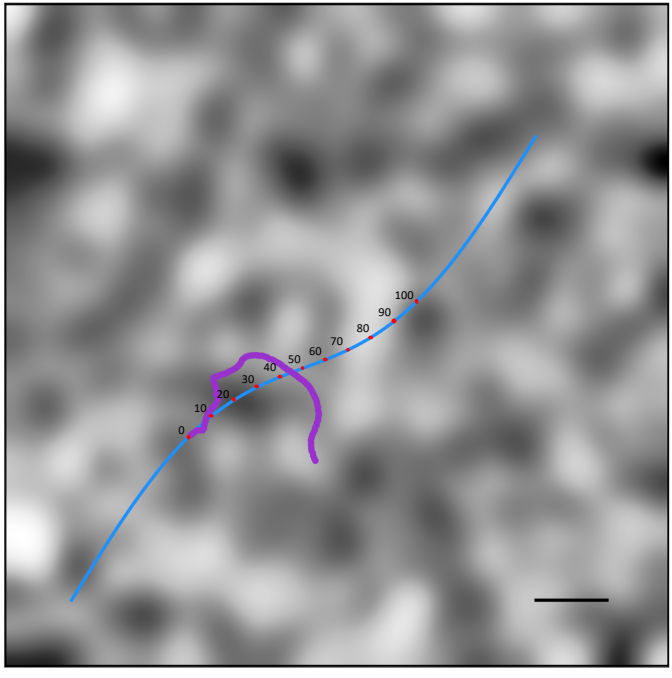
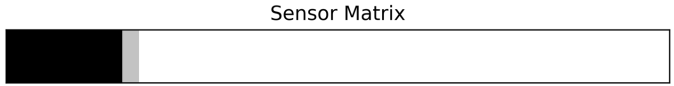
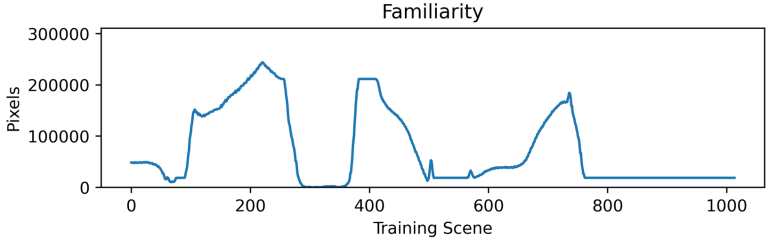
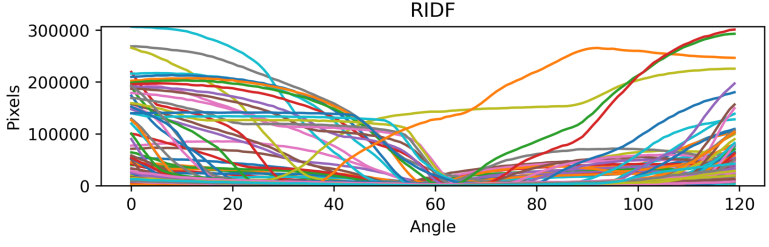
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

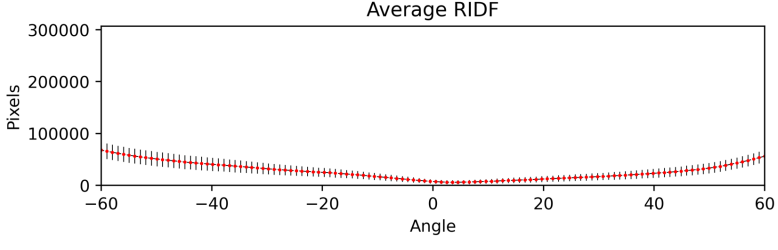
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4208.92; RMSD/dist: 10.522; TD: 115271; p90: 120; p50: 116; complete: 0

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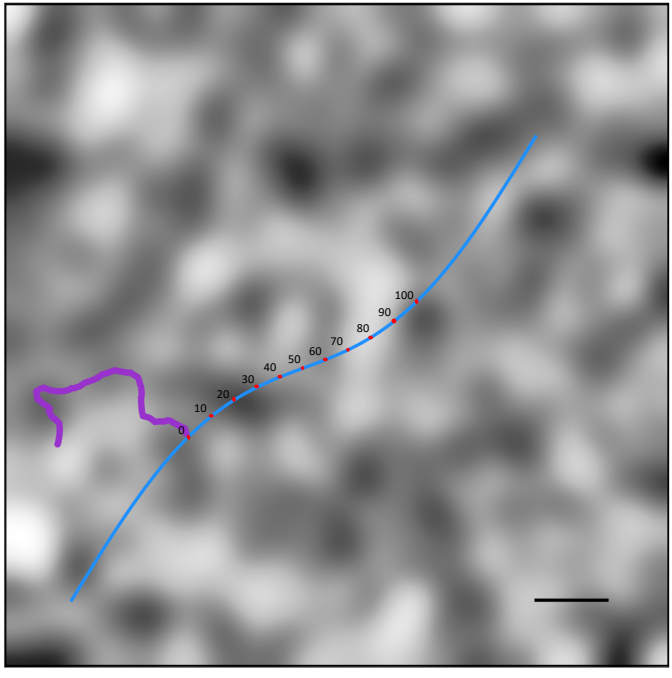
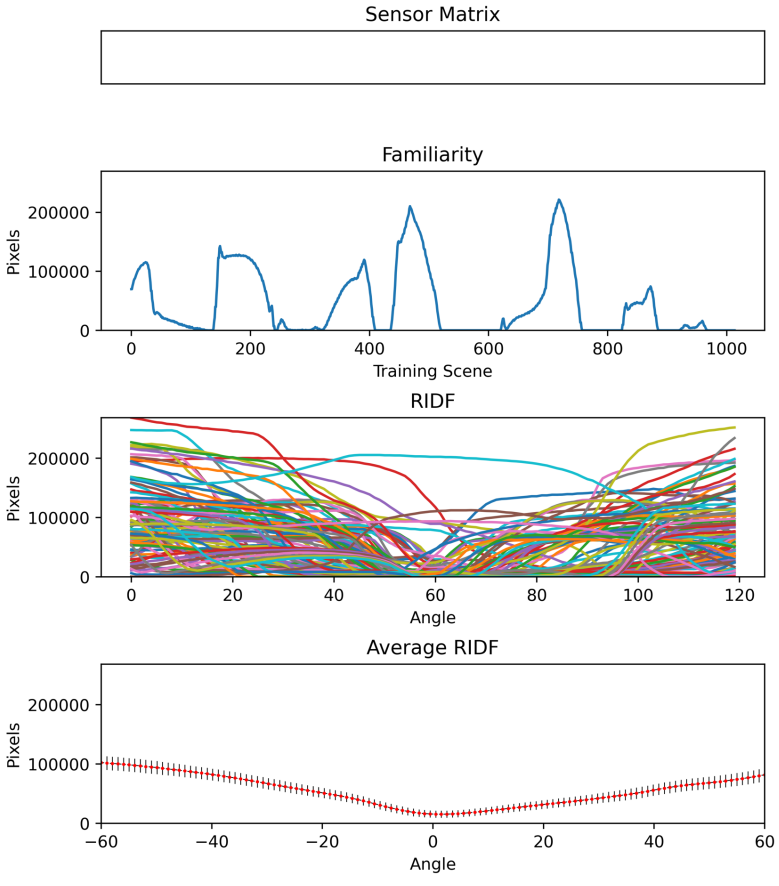
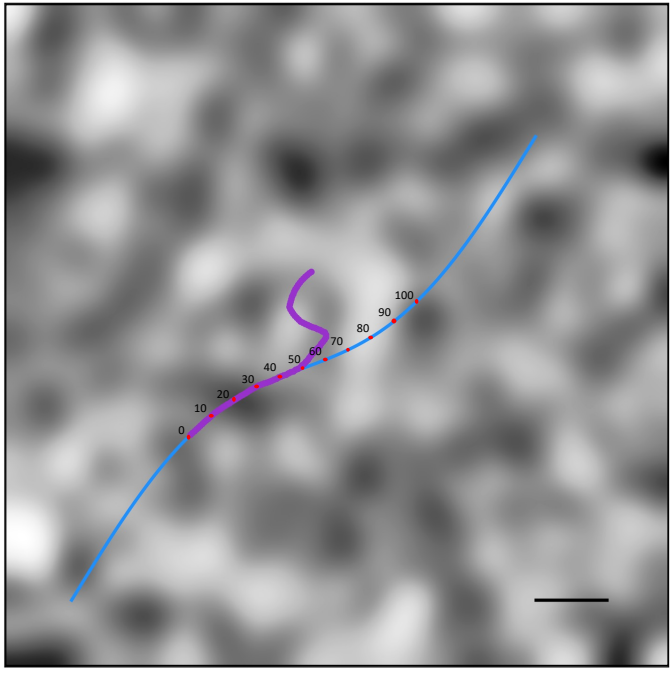


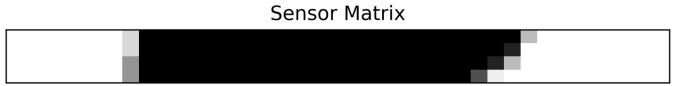


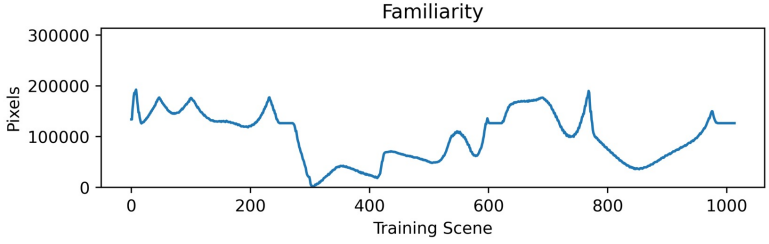
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

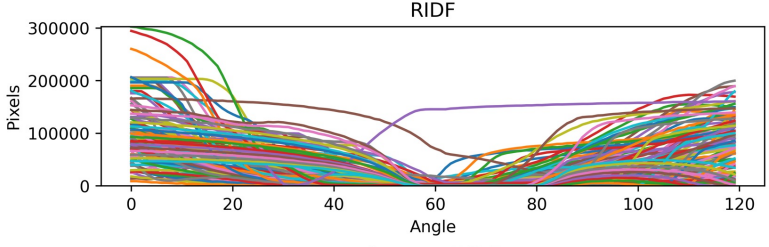
Navigation stats: RMSD error: 13468.62; RMSD/dist: 33.672; TD: 64642; p90: 68; p50: 36; complete: 0

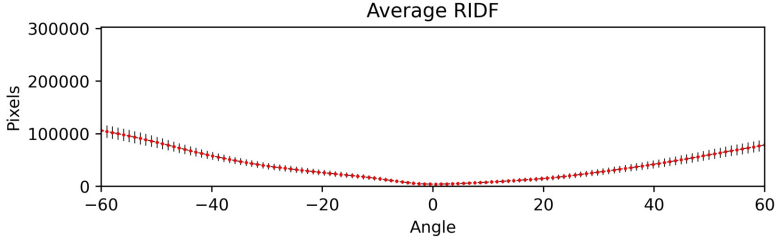
50%







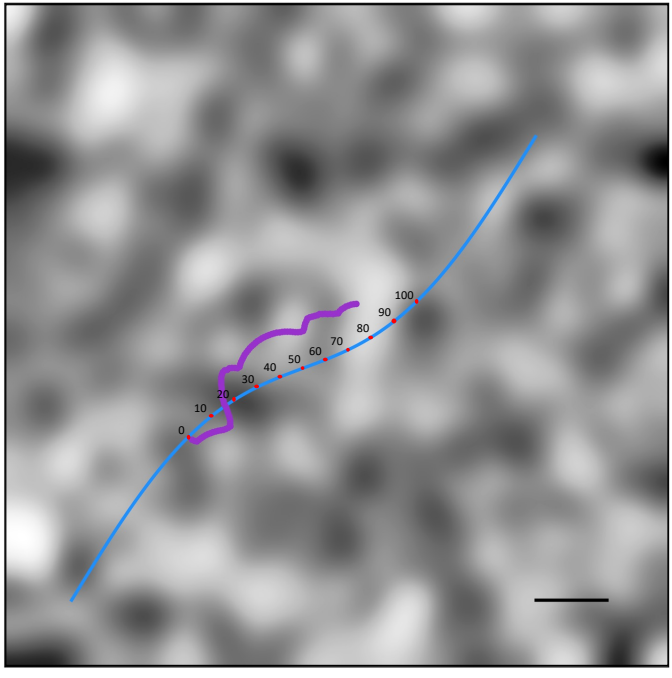


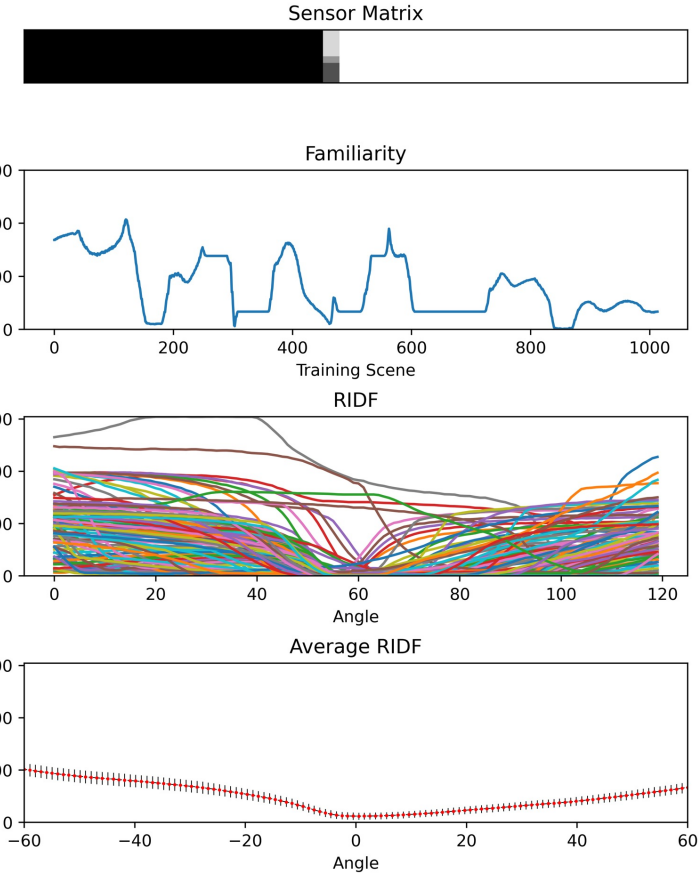


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 3359.62; RMSD/dist: 8.399; TD: 115832; p90: 120; p50: 84; complete: 0

0%

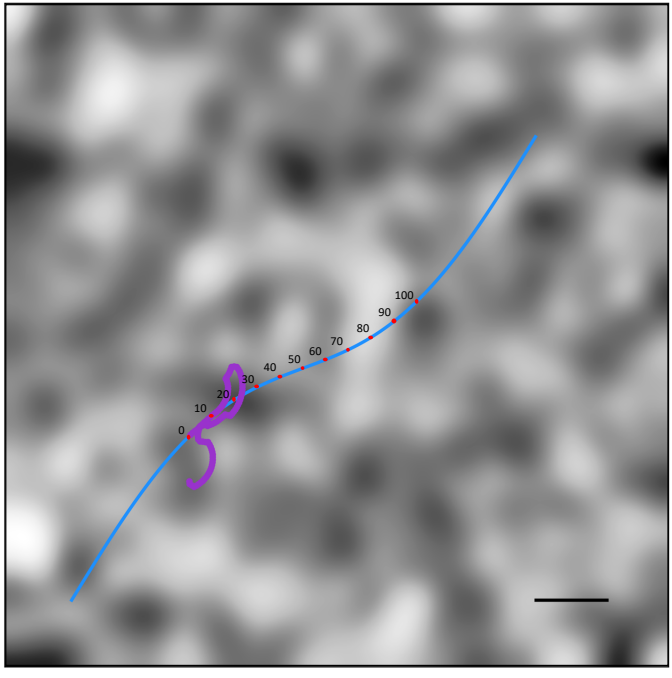


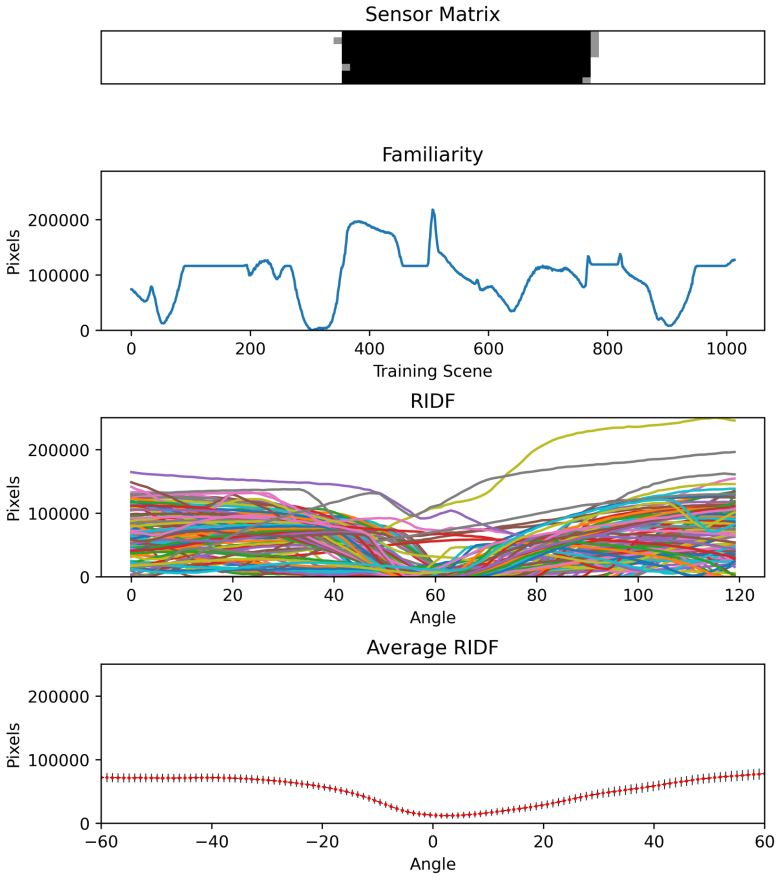


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 4350.51; RMSD/dist: 10.876; TD: 75519; p90: 82; p50: 36; complete: 0

10%

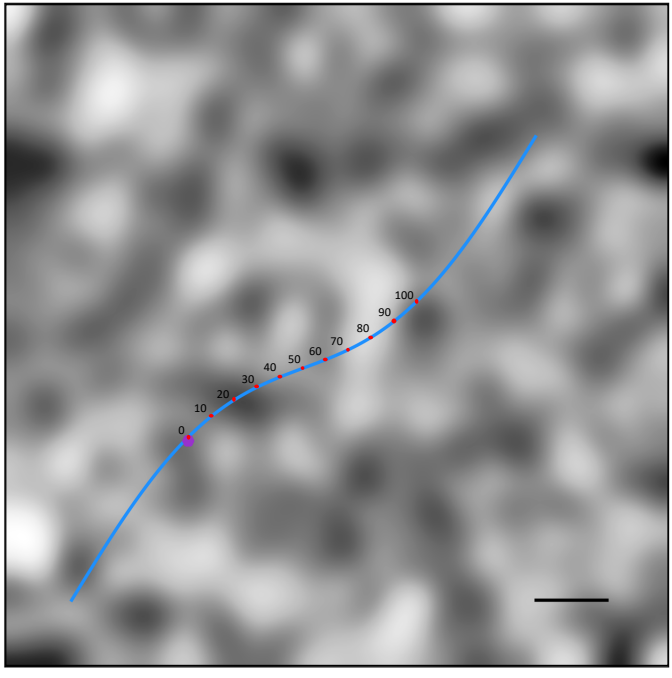


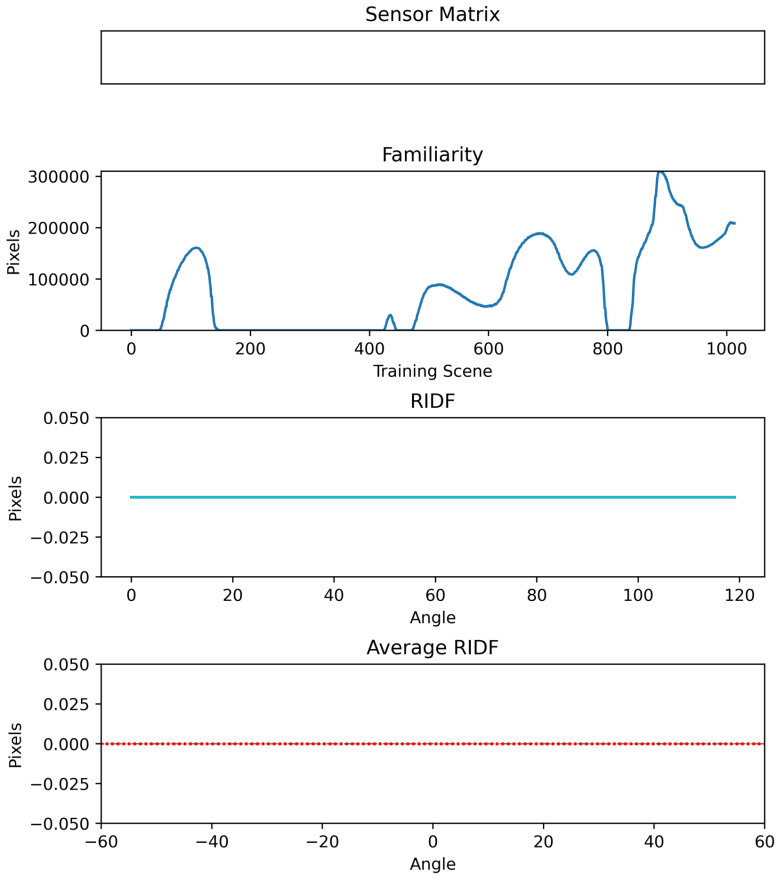


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 2203.40; RMSD/dist: 5.508; TD: 77533; p90: 120; p50: 32; complete: 0

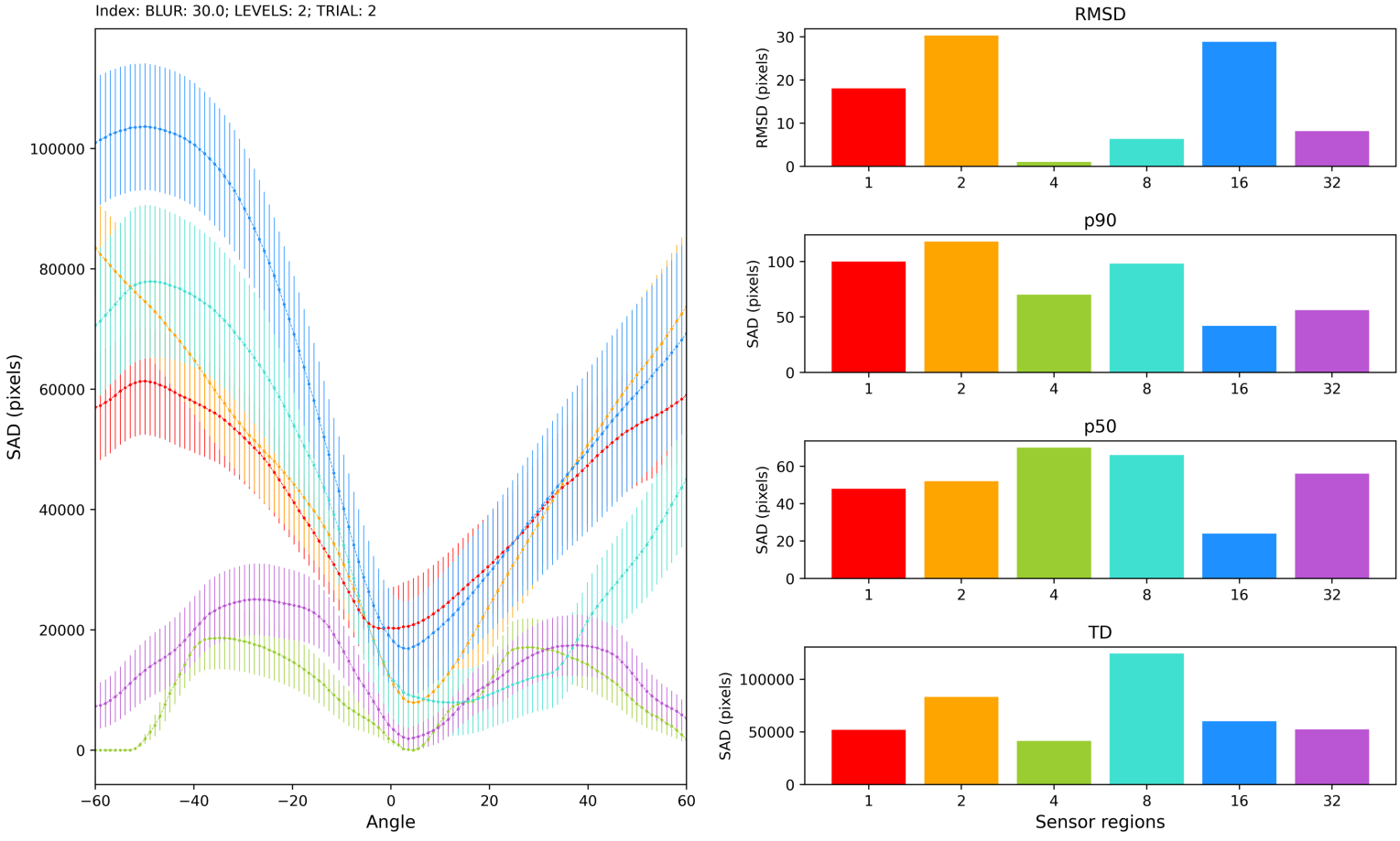
0%



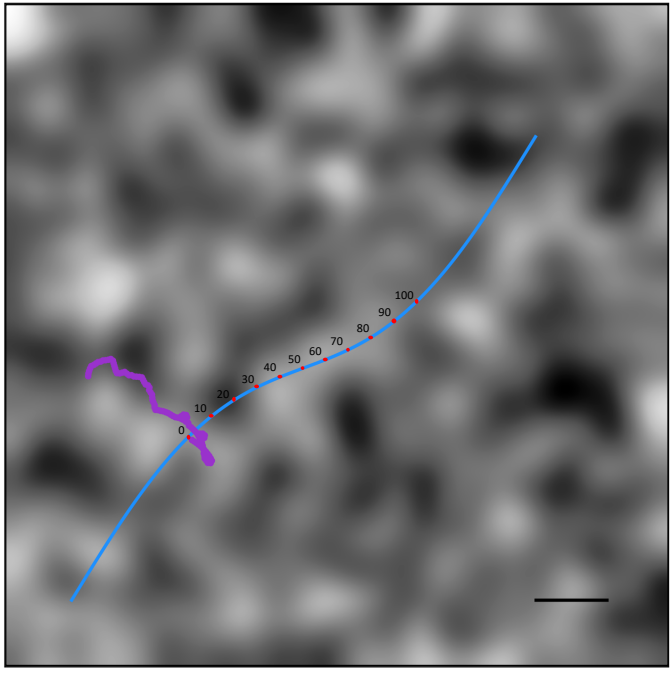


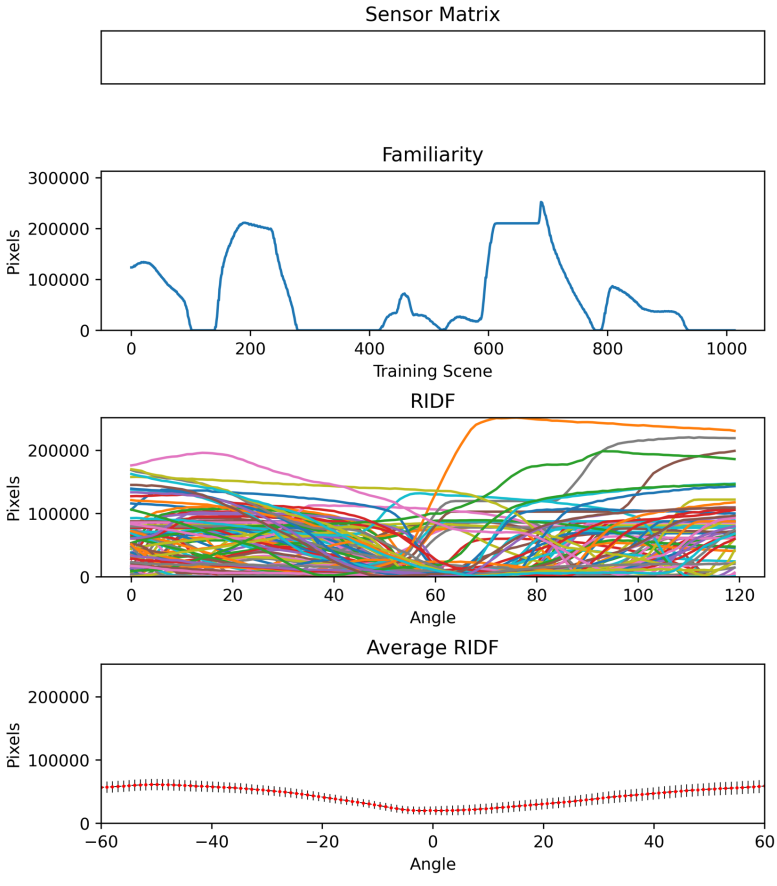
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 79419; p90: 120; p50: 120; complete: 0


Index: BLUR: 30.0; LEVELS: 2; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

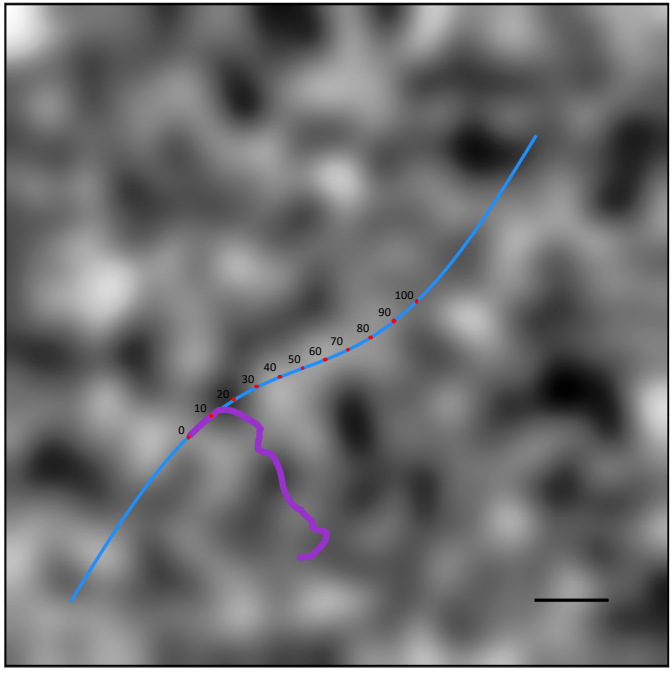


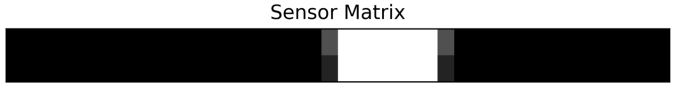


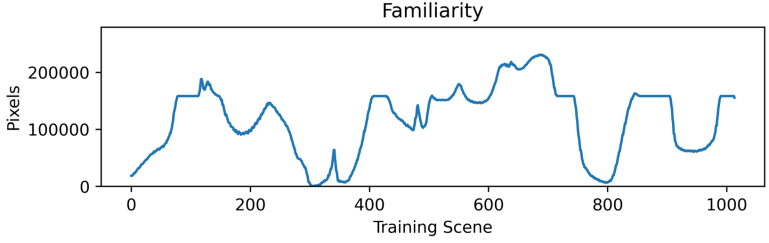
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

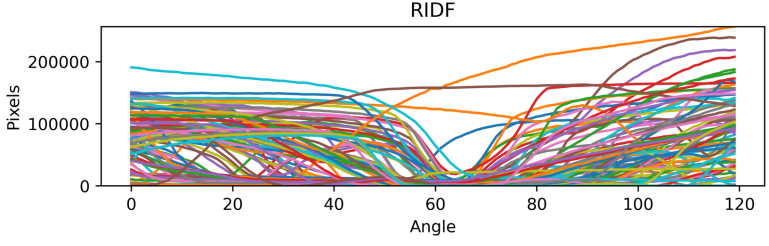
Navigation stats: RMSD error: 7221.24; RMSD/dist: 18.053; TD: 51959; p90: 100; p50: 48; complete: 0

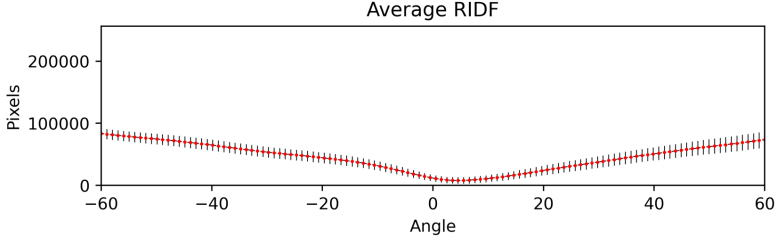
10%







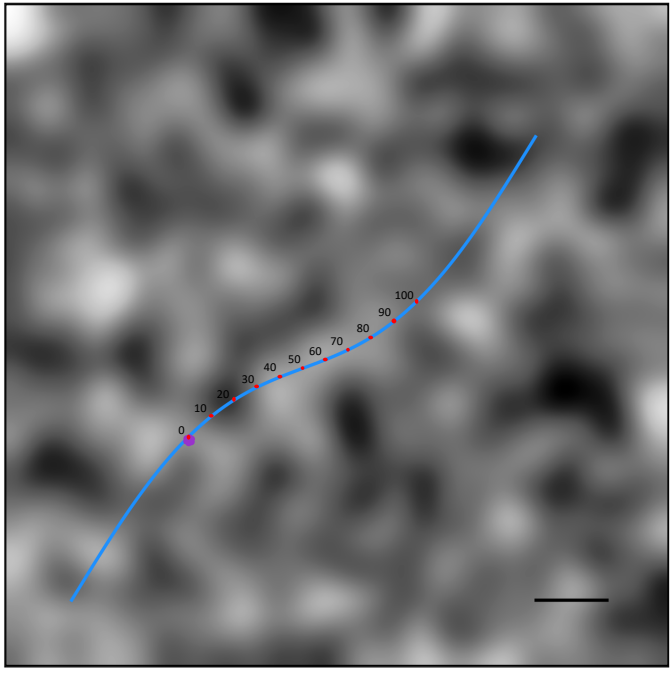


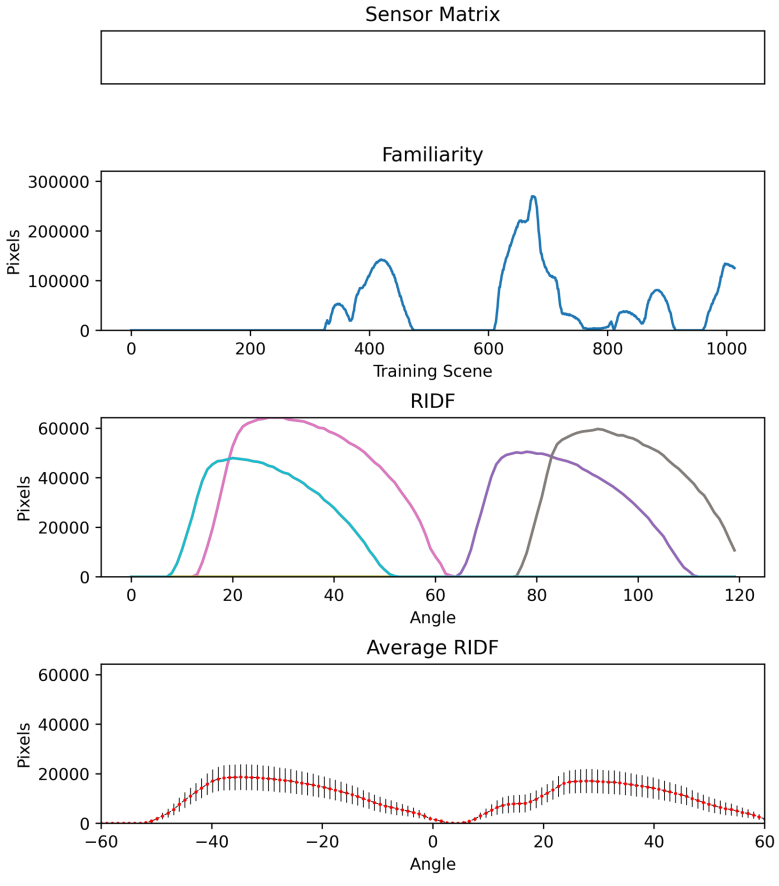


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 12131.16; RMSD/dist: 30.328; TD: 83175; p90: 118; p50: 52; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 402.78; RMSD/dist: 1.007; TD: 41336; p90: 70; p50: 70; complete: 0

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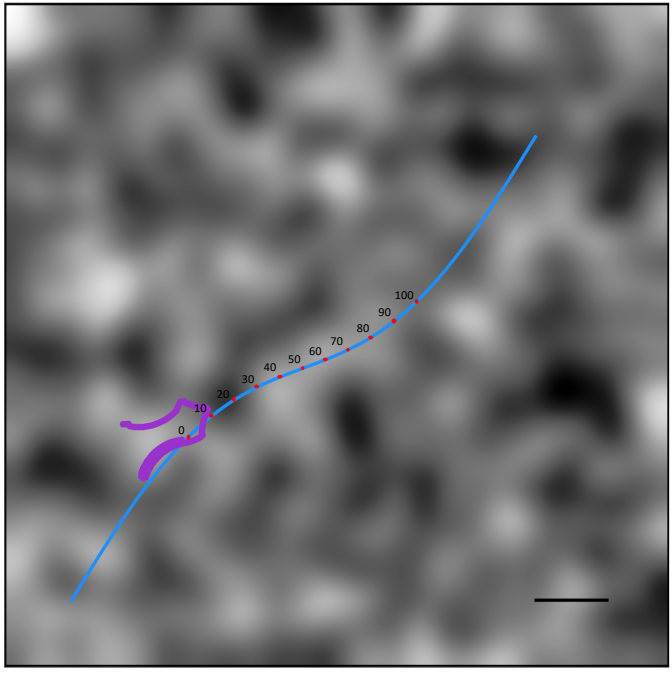

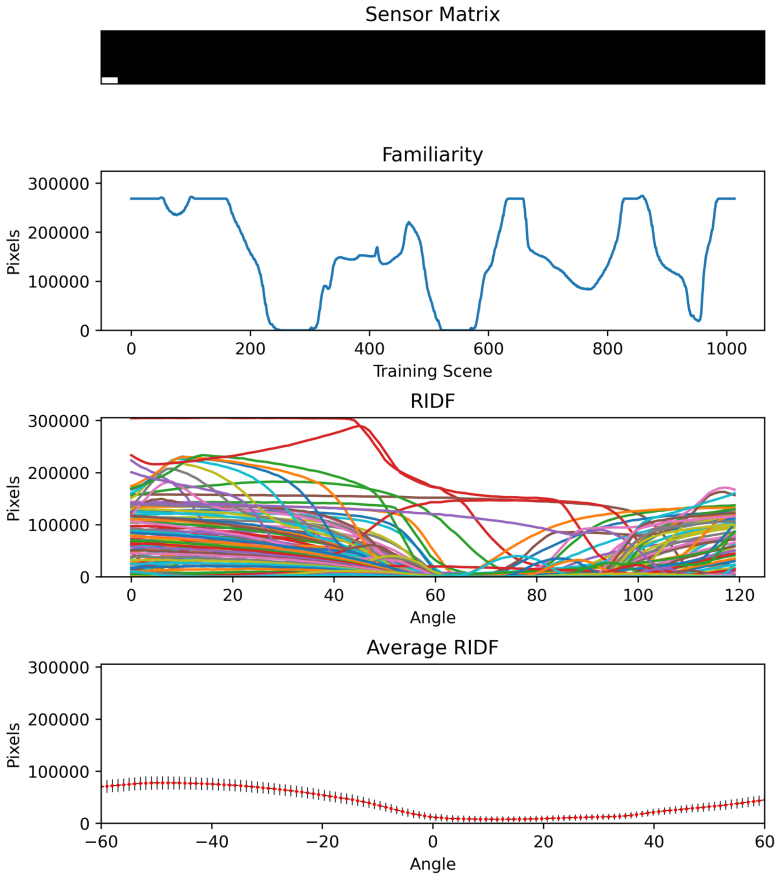

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2533.09; RMSD/dist: 6.333; TD: 124302; p90: 98; p50: 66; complete: 0

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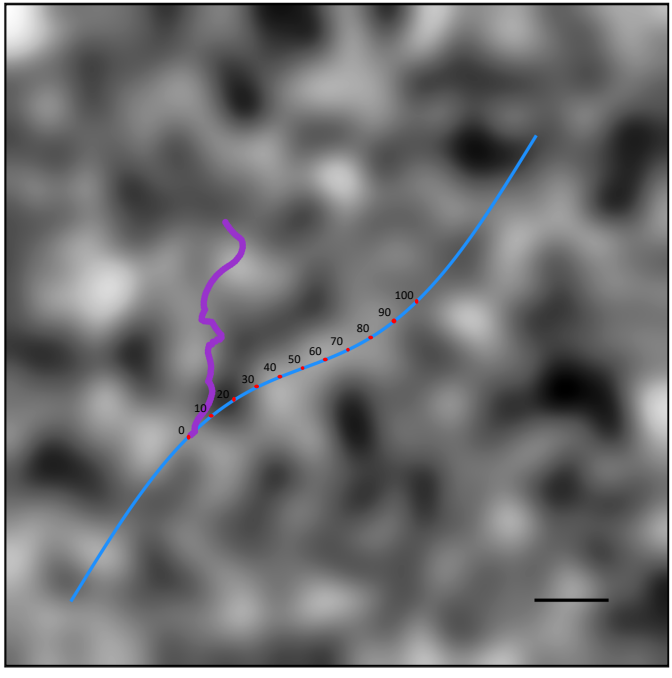

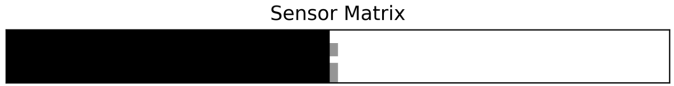

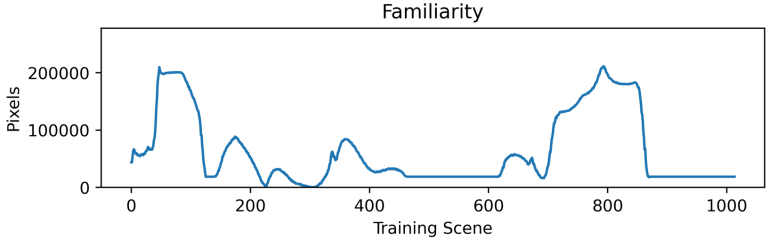

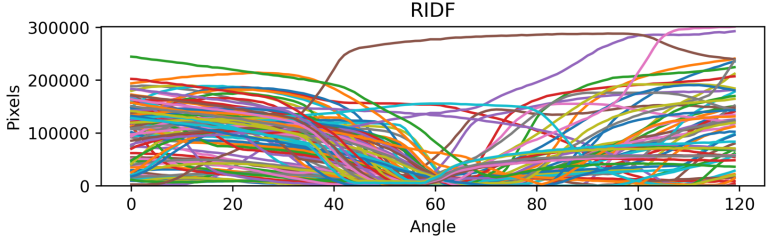

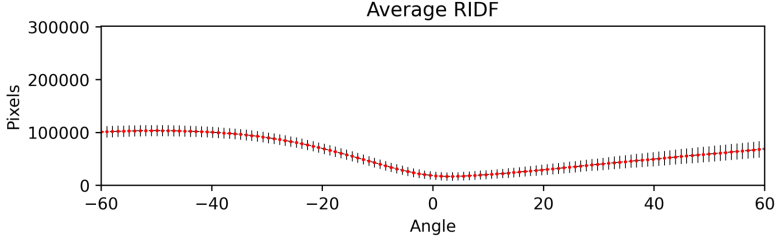

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 11536.61; RMSD/dist: 28.842; TD: 60026; p90: 42; p50: 24; complete: 0

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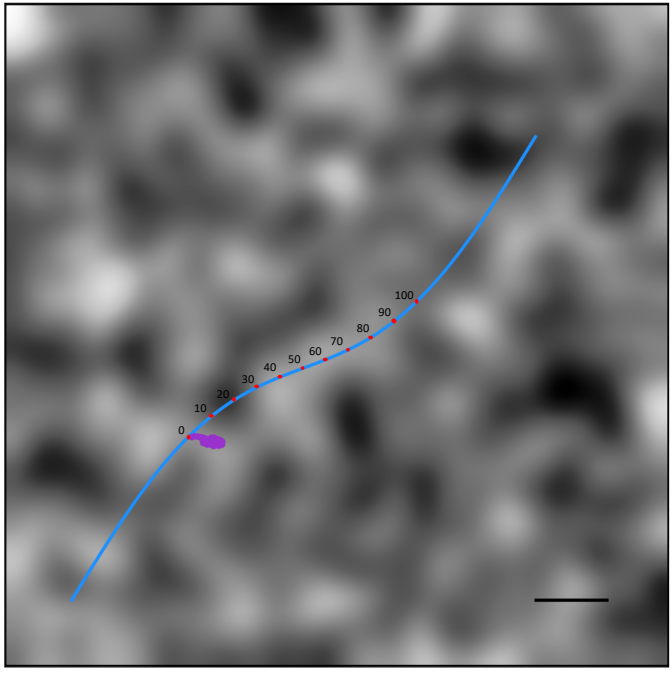
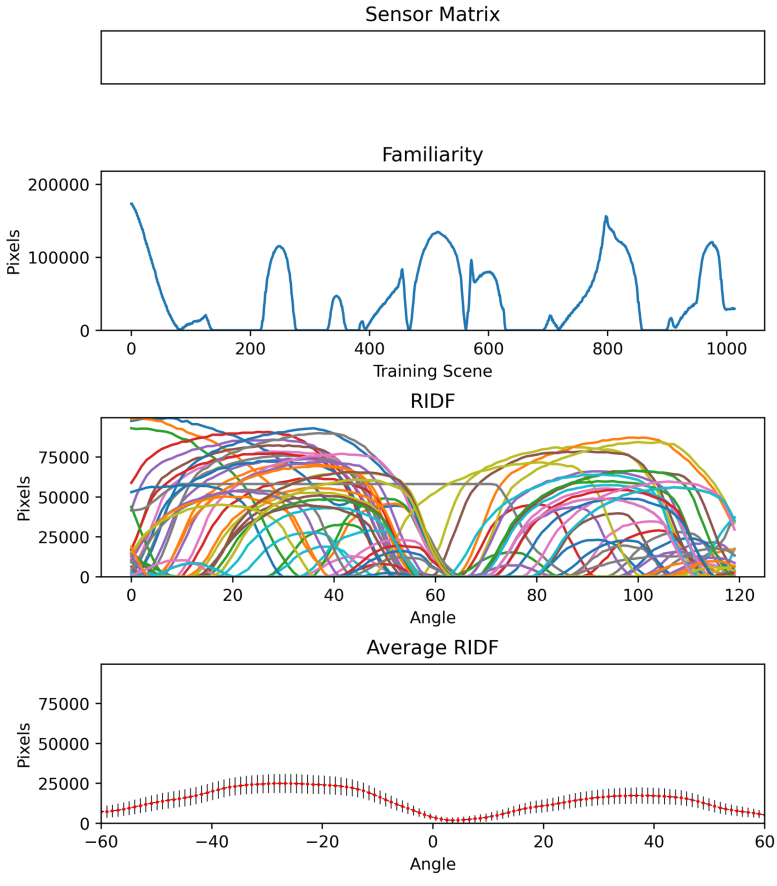
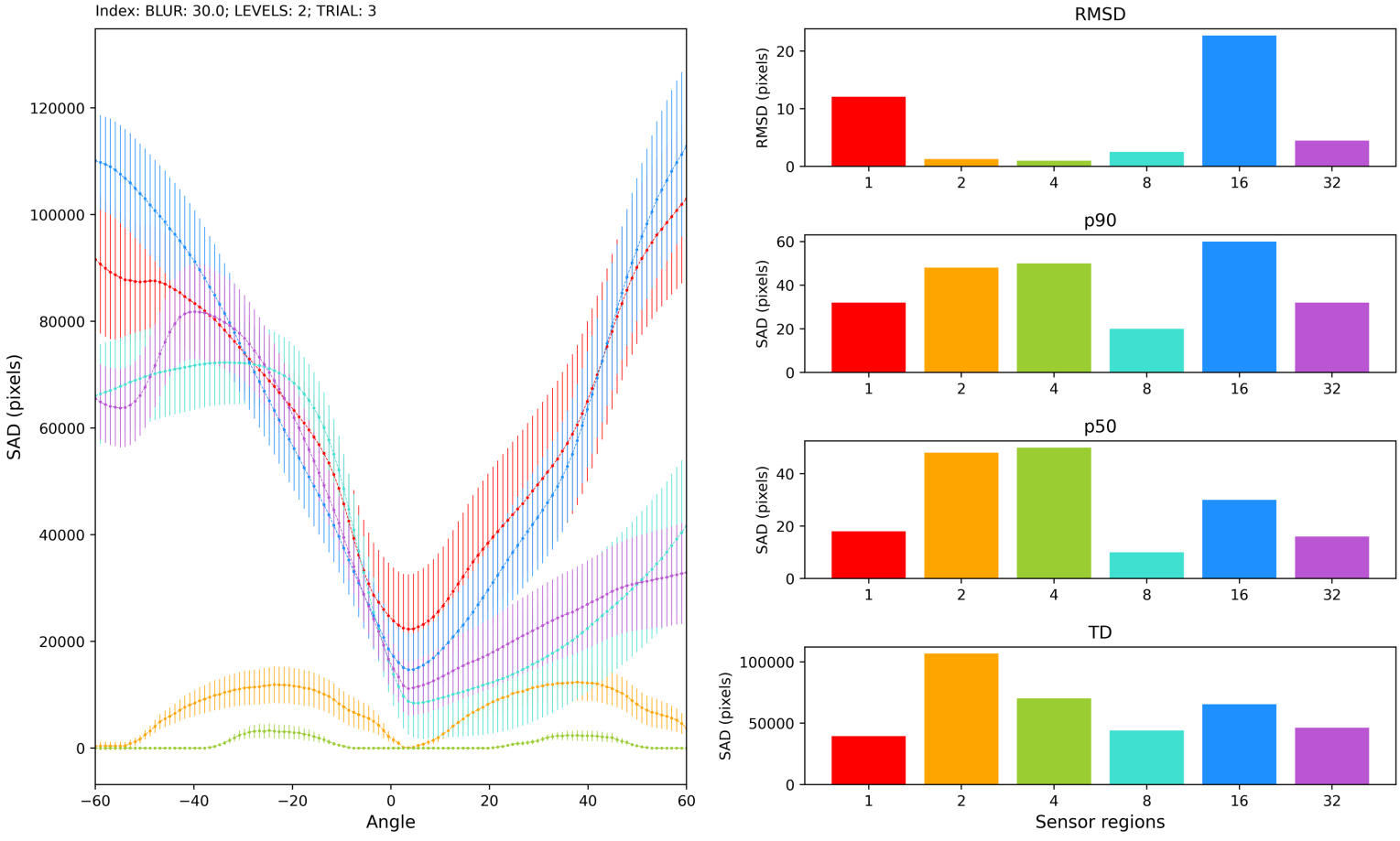


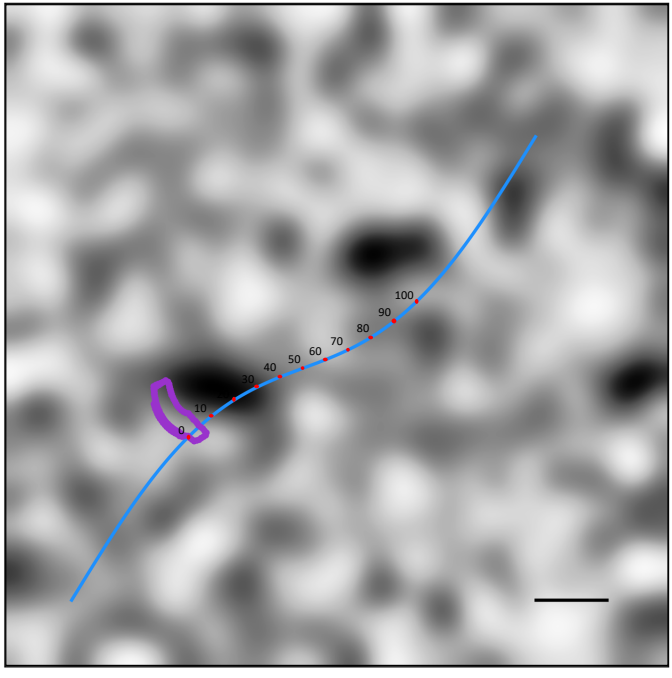


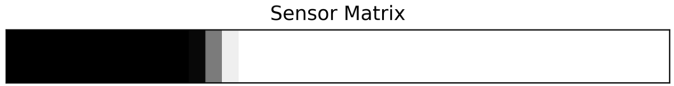
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

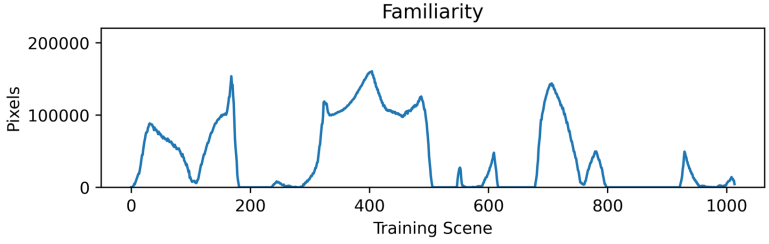
Navigation stats: RMSD error: 3250.52; RMSD/dist: 8.126; TD: 52268; p90: 56; p50: 56; complete: 0

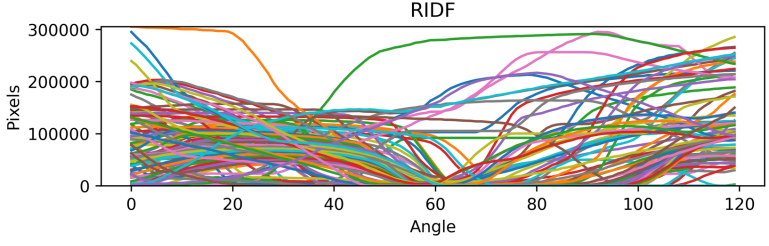

Index: BLUR: 30.0; LEVELS: 2; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

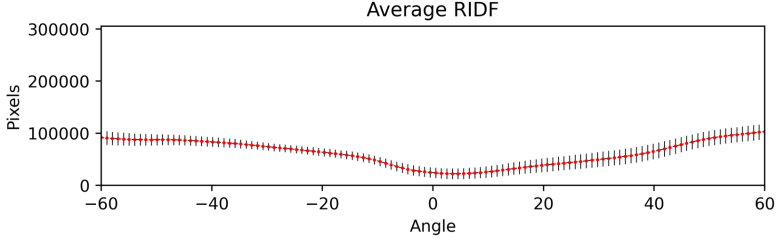
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 4836.44; RMSD/dist: 12.091; TD: 39483; p90: 32; p50: 18; complete: 0

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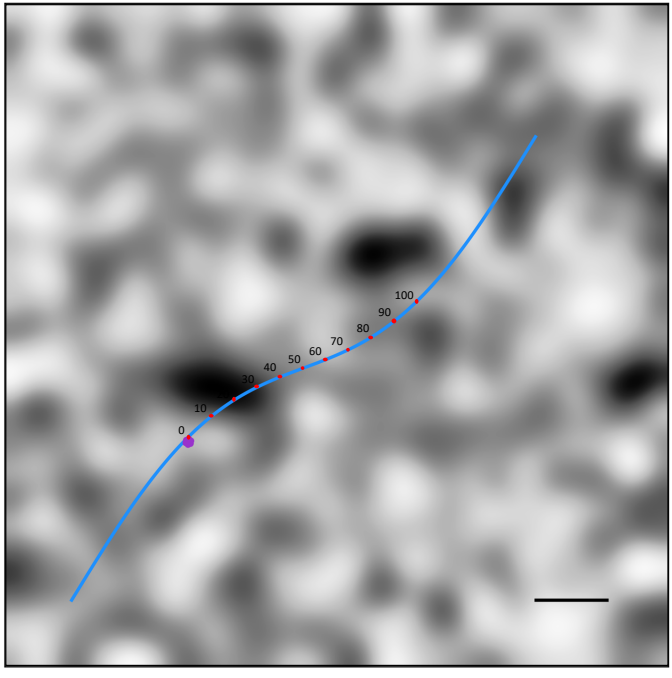

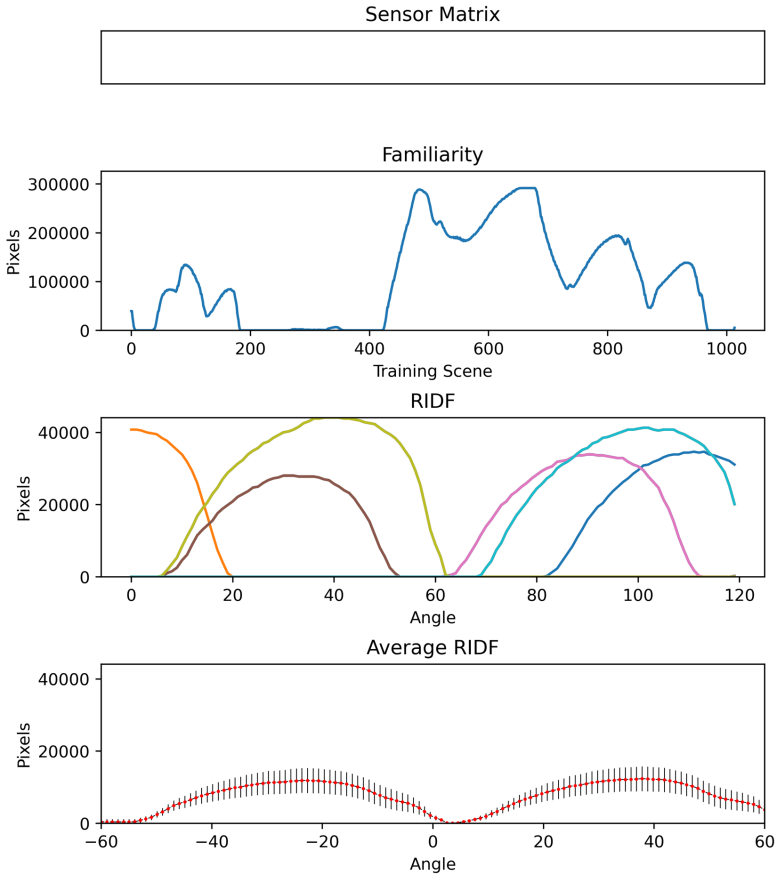

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 507.16; RMSD/dist: 1.268; TD: 106764; p90: 48; p50: 48; complete: 0

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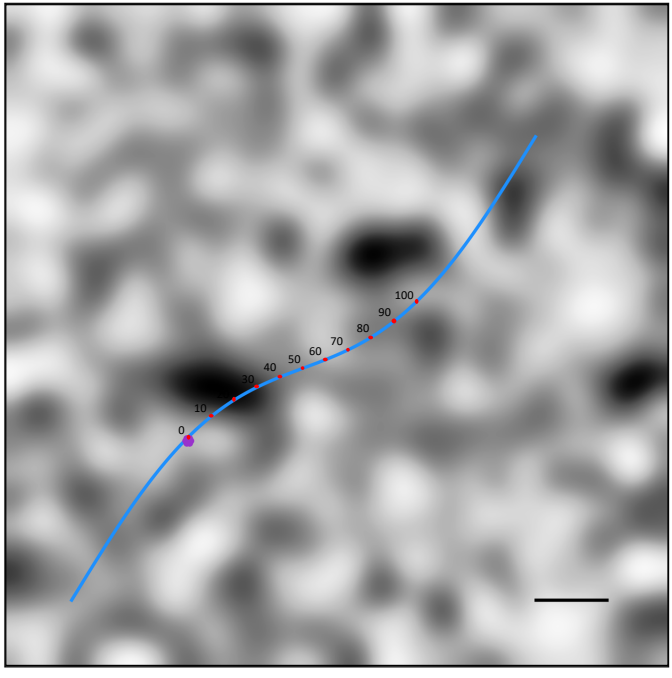

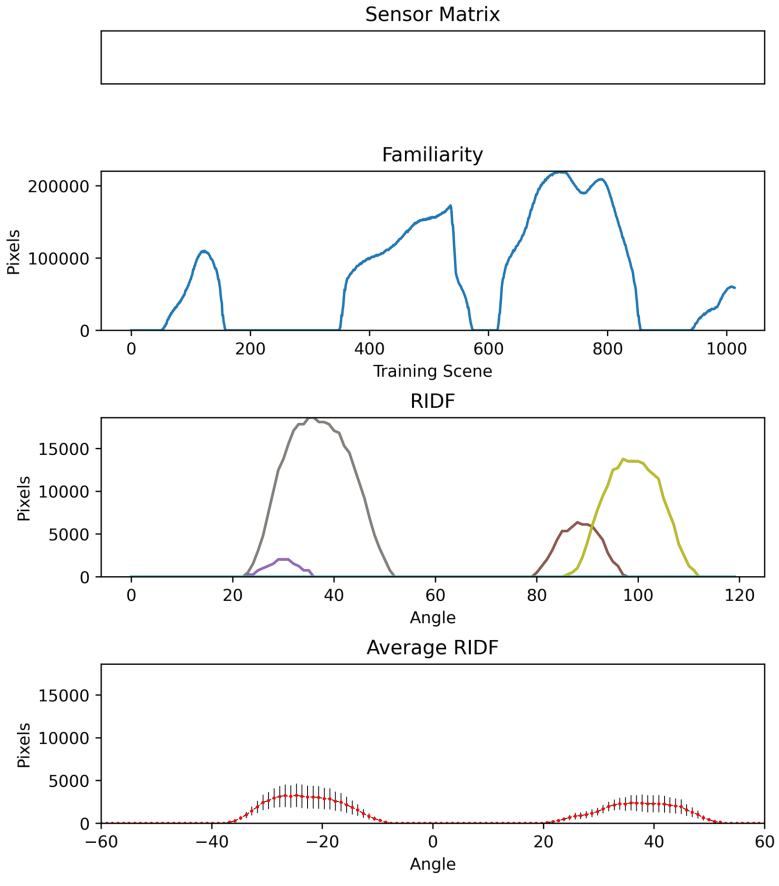

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 70324; p90: 50; p50: 50; complete: 0

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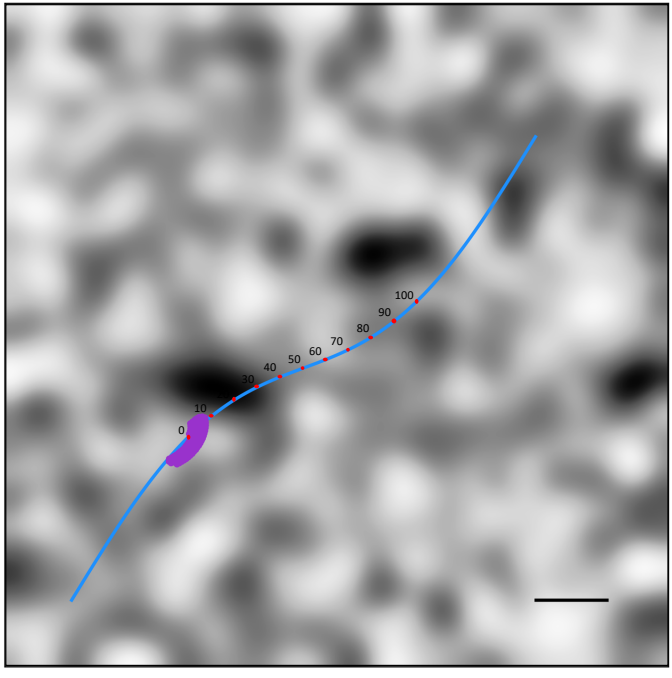

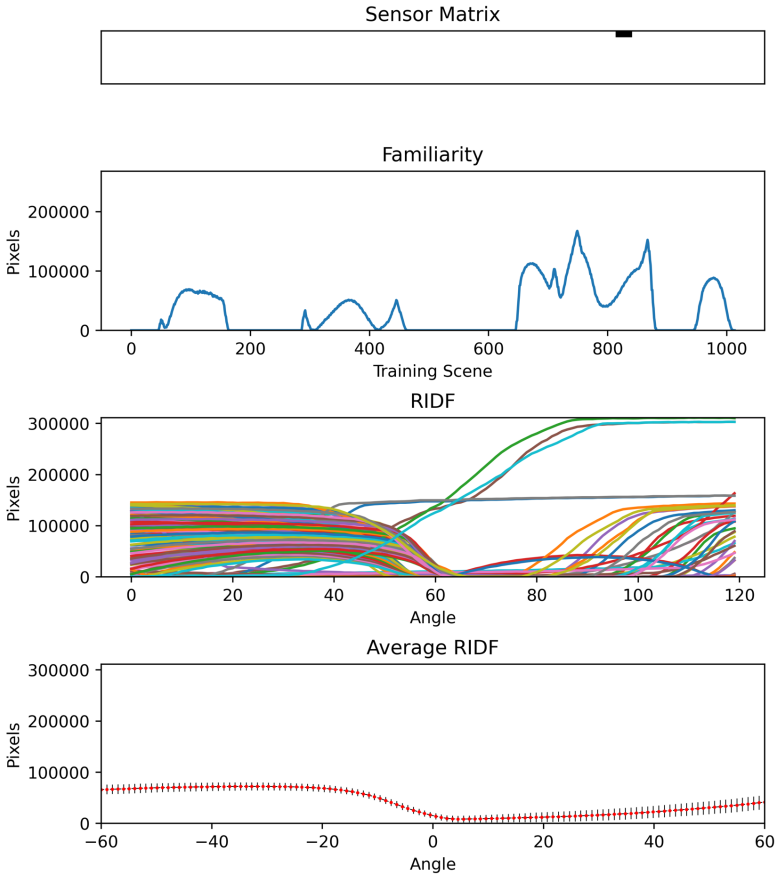

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 995.67; RMSD/dist: 2.489; TD: 44032; p90: 20; p50: 10; complete: 0

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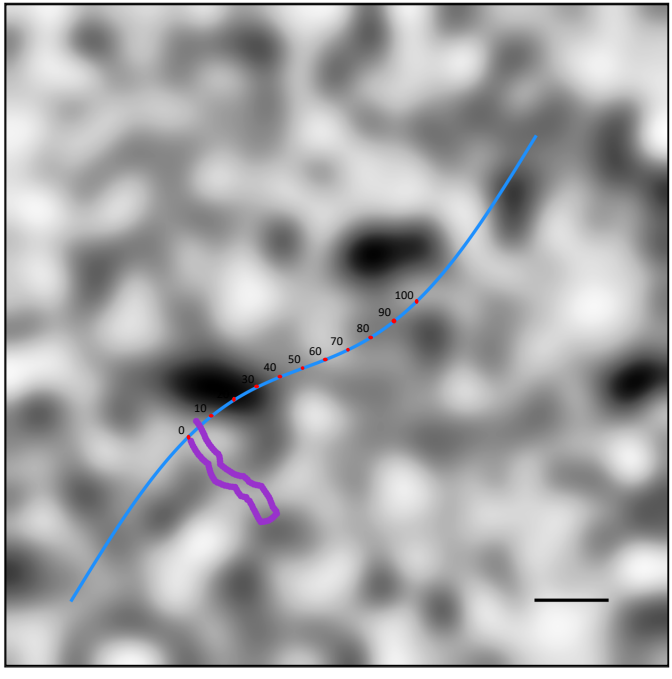

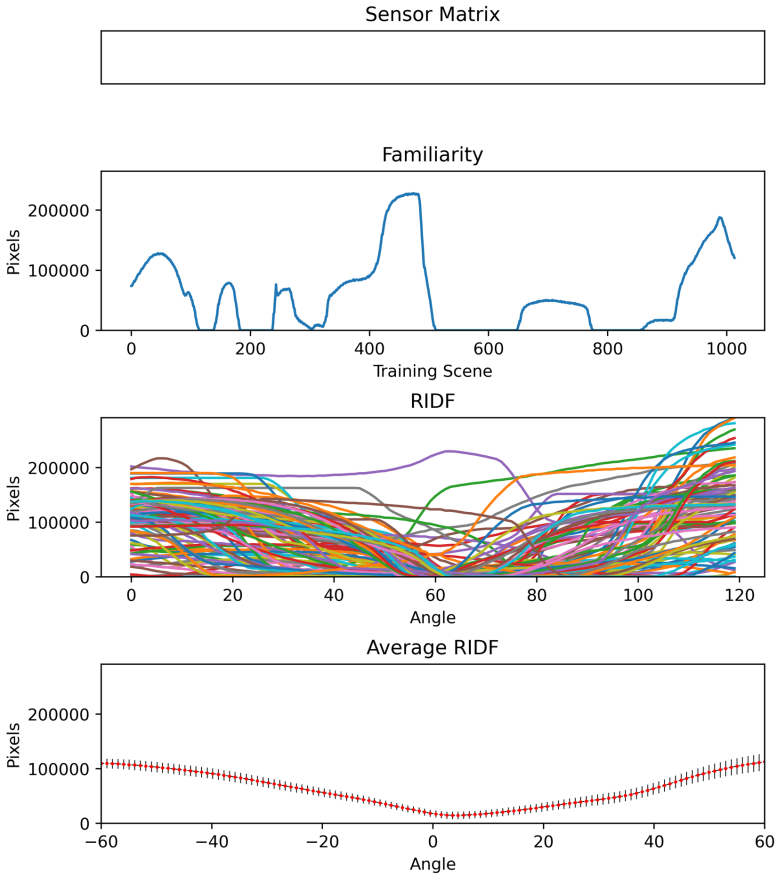

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 9087.89; RMSD/dist: 22.720; TD: 65484; p90: 60; p50: 30; complete: 0

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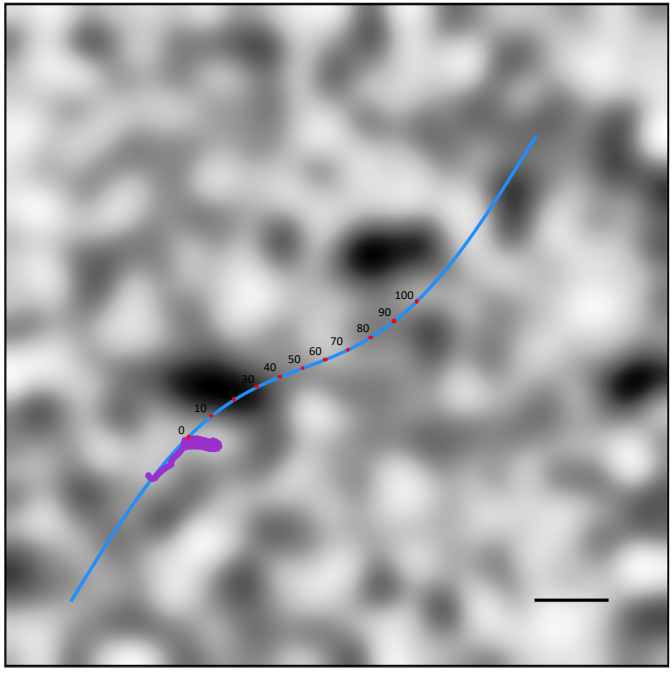
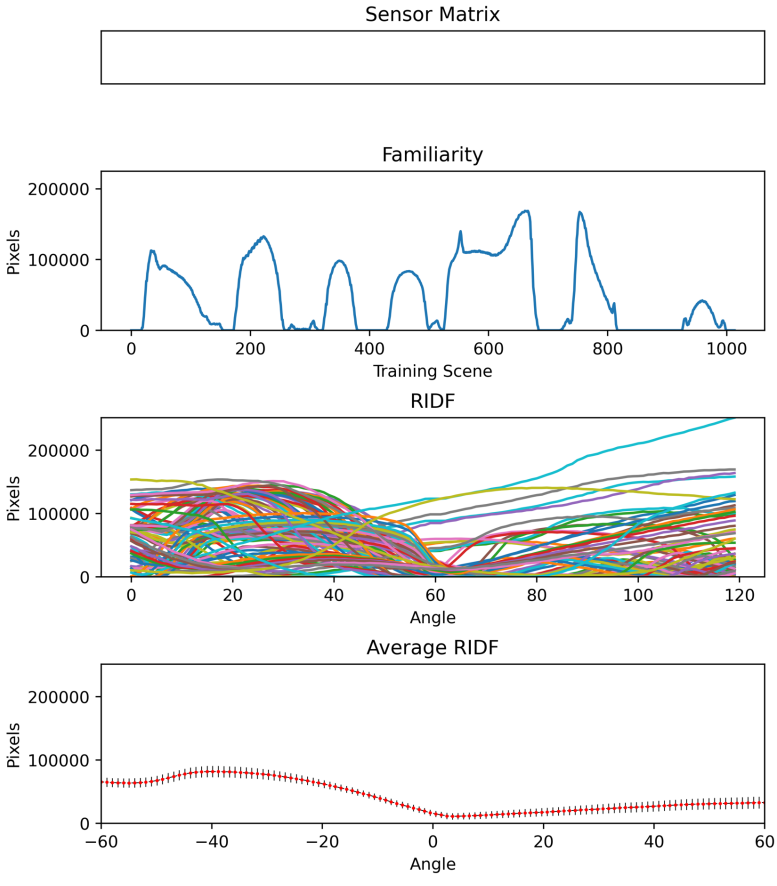
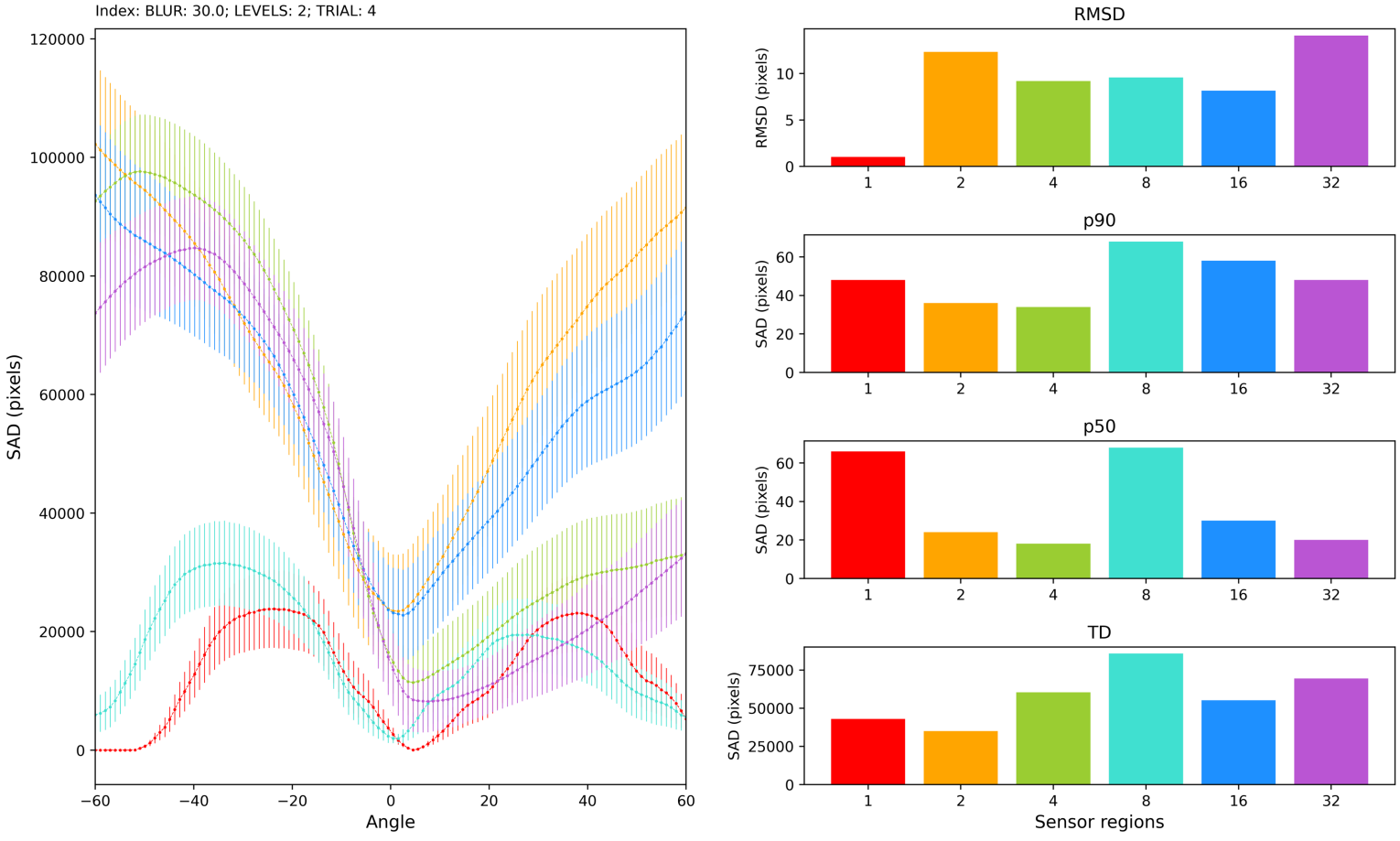


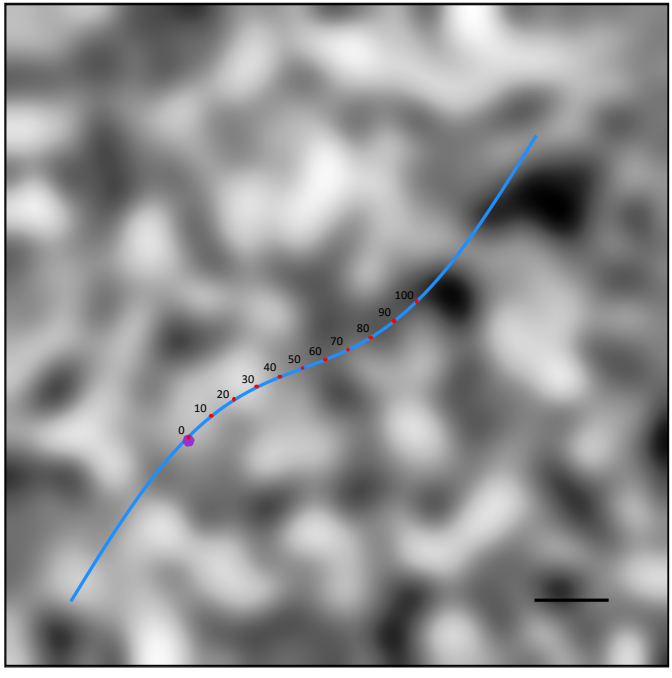


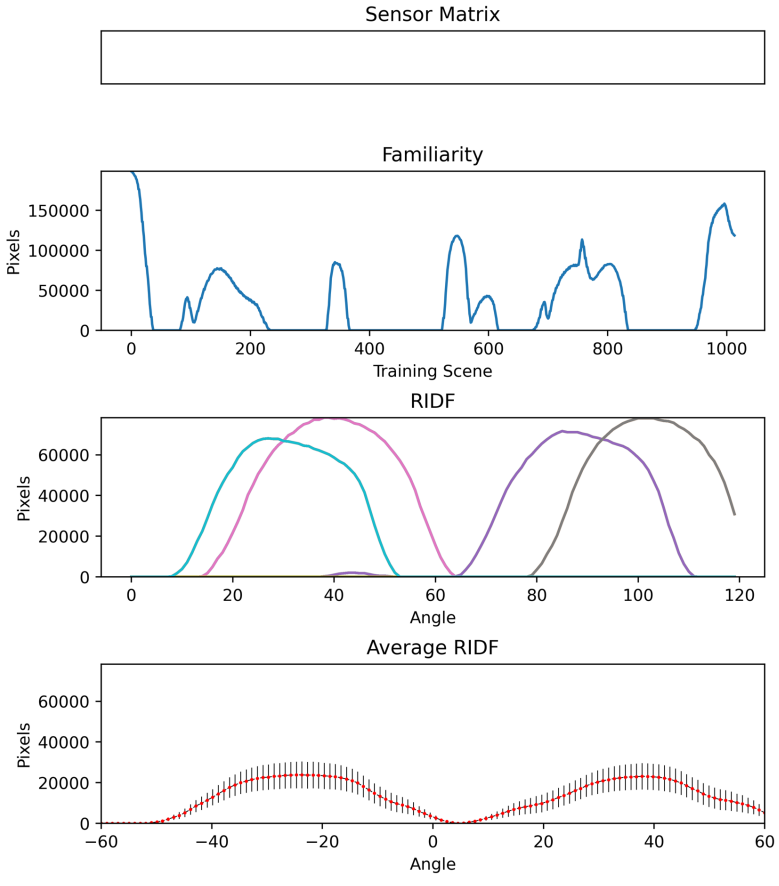
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 1781.32; RMSD/dist: 4.453; TD: 46320; p90: 32; p50: 16; complete: 0


Index: BLUR: 30.0; LEVELS: 2; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 402.23; RMSD/dist: 1.006; TD: 42951; p90: 48; p50: 66; complete: 0

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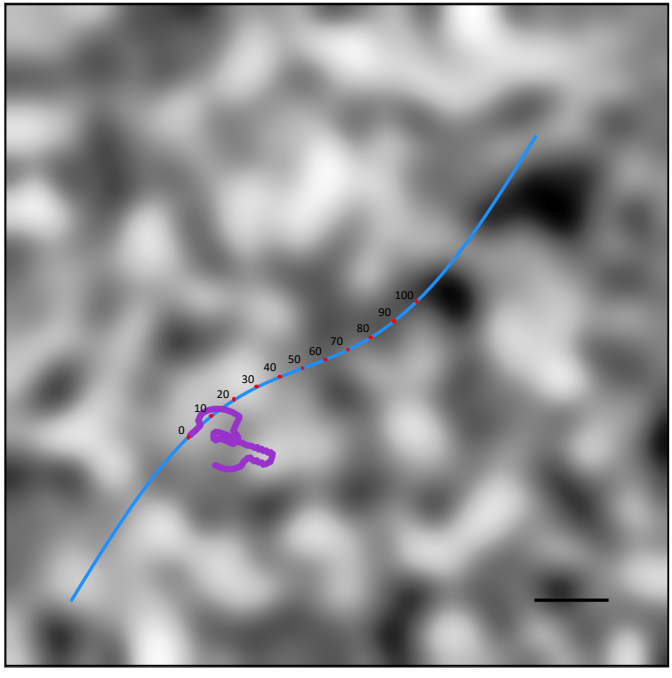
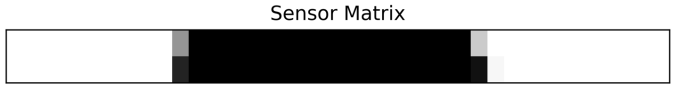
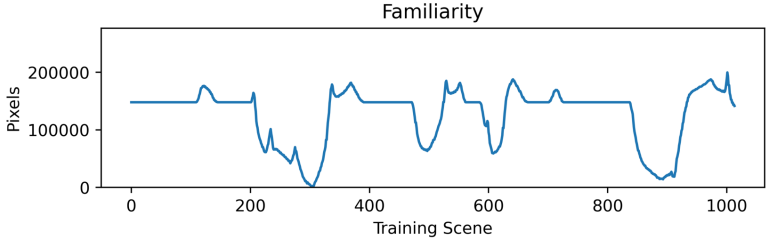
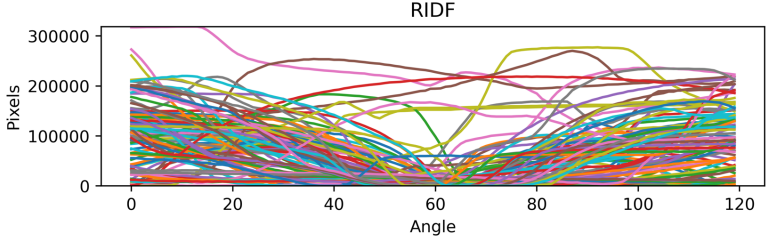
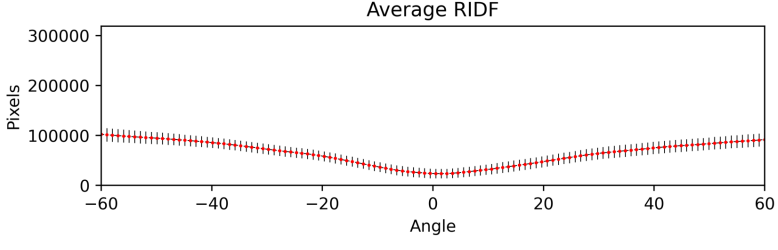






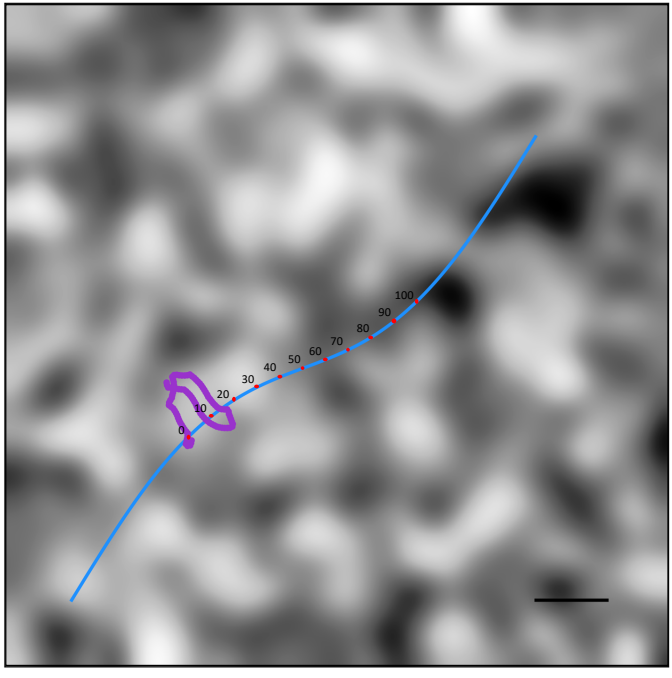


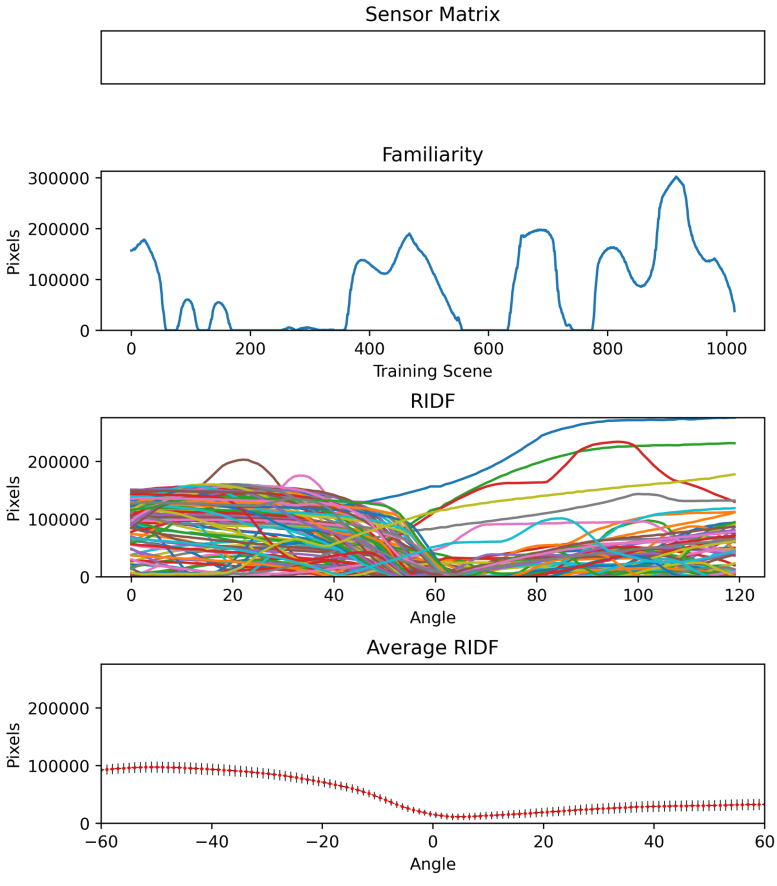


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 4939.72; RMSD/dist: 12.349; TD: 34911; p90: 36; p50: 24; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3675.85; RMSD/dist: 9.190; TD: 60354; p90: 34; p50: 18; complete: 0

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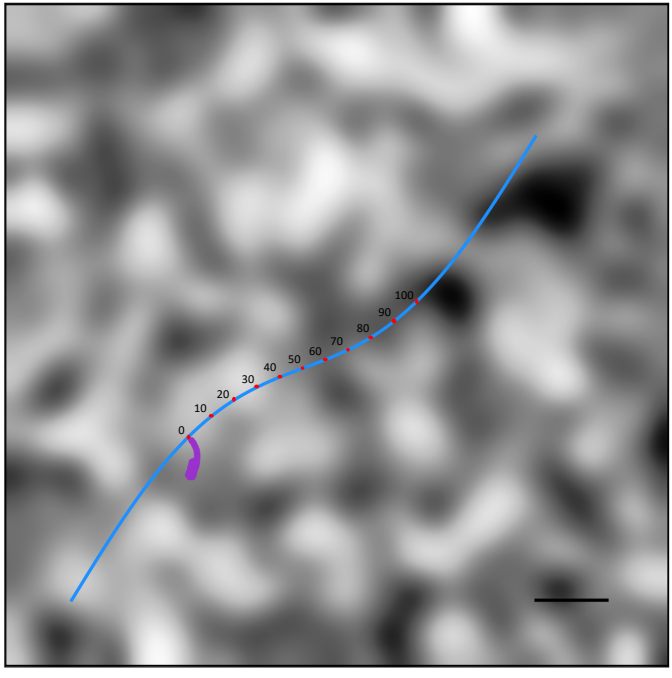

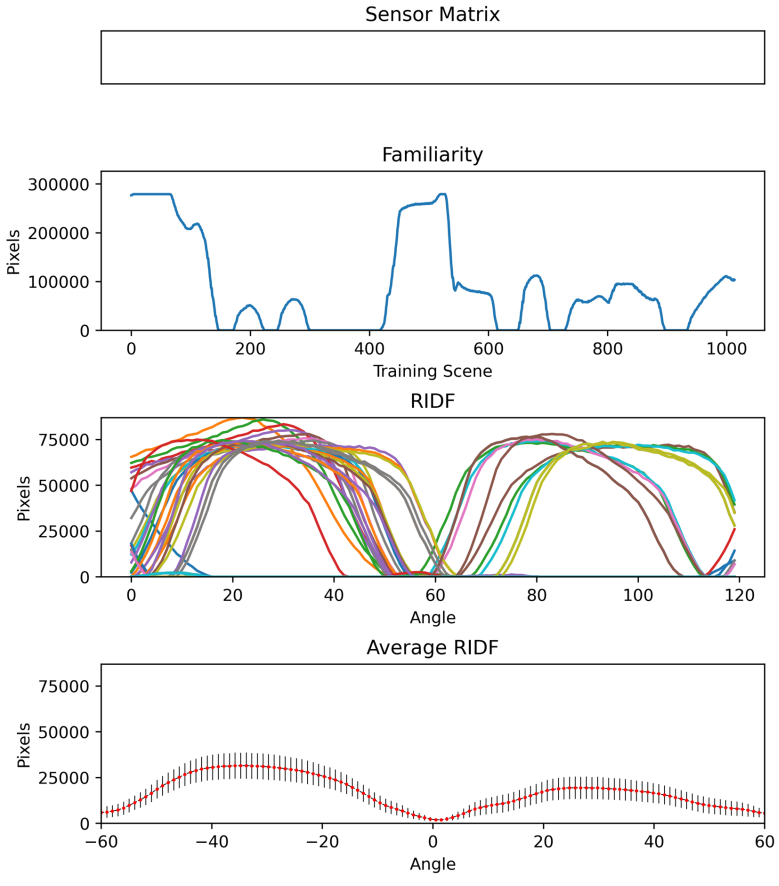

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3828.62; RMSD/dist: 9.572; TD: 85729; p90: 68; p50: 68; complete: 0

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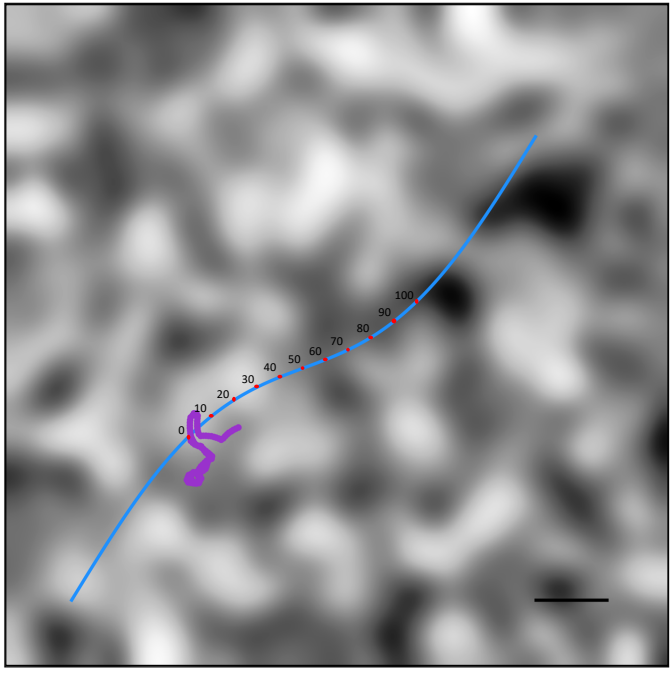

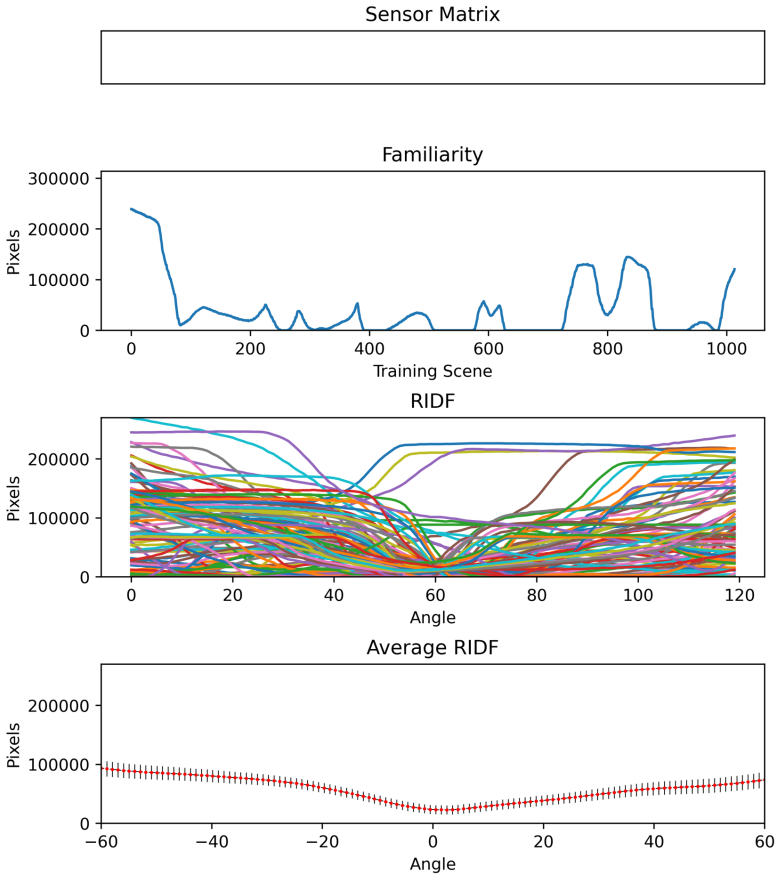

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 3262.34; RMSD/dist: 8.156; TD: 55135; p90: 58; p50: 30; complete: 0

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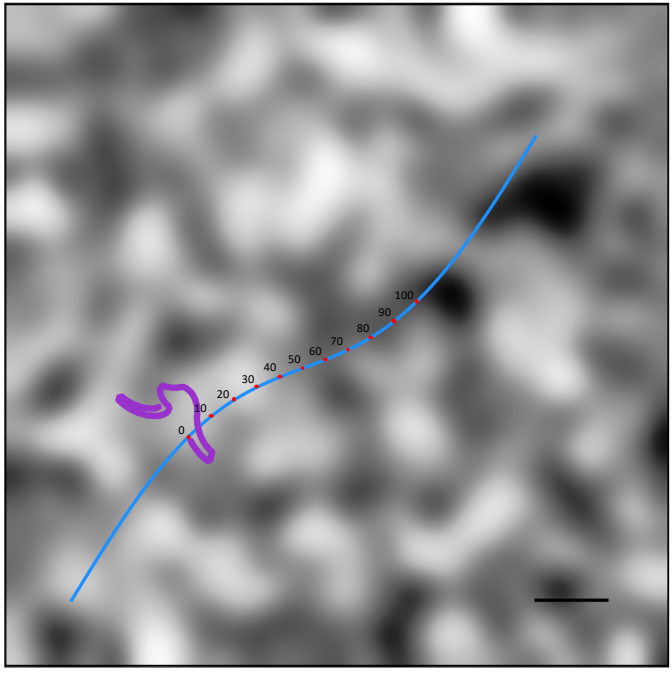
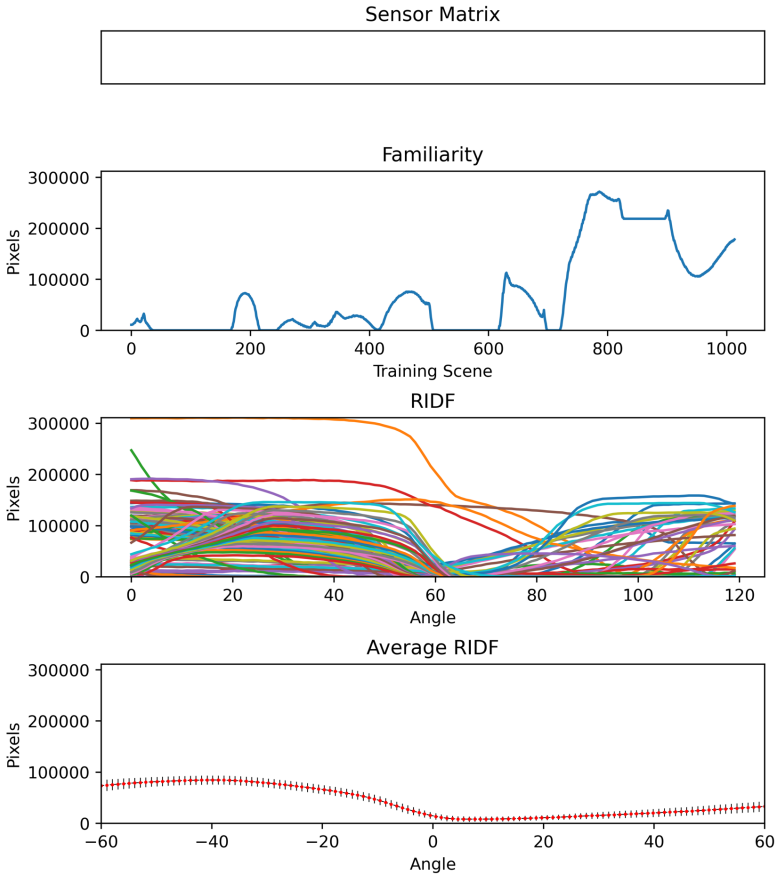
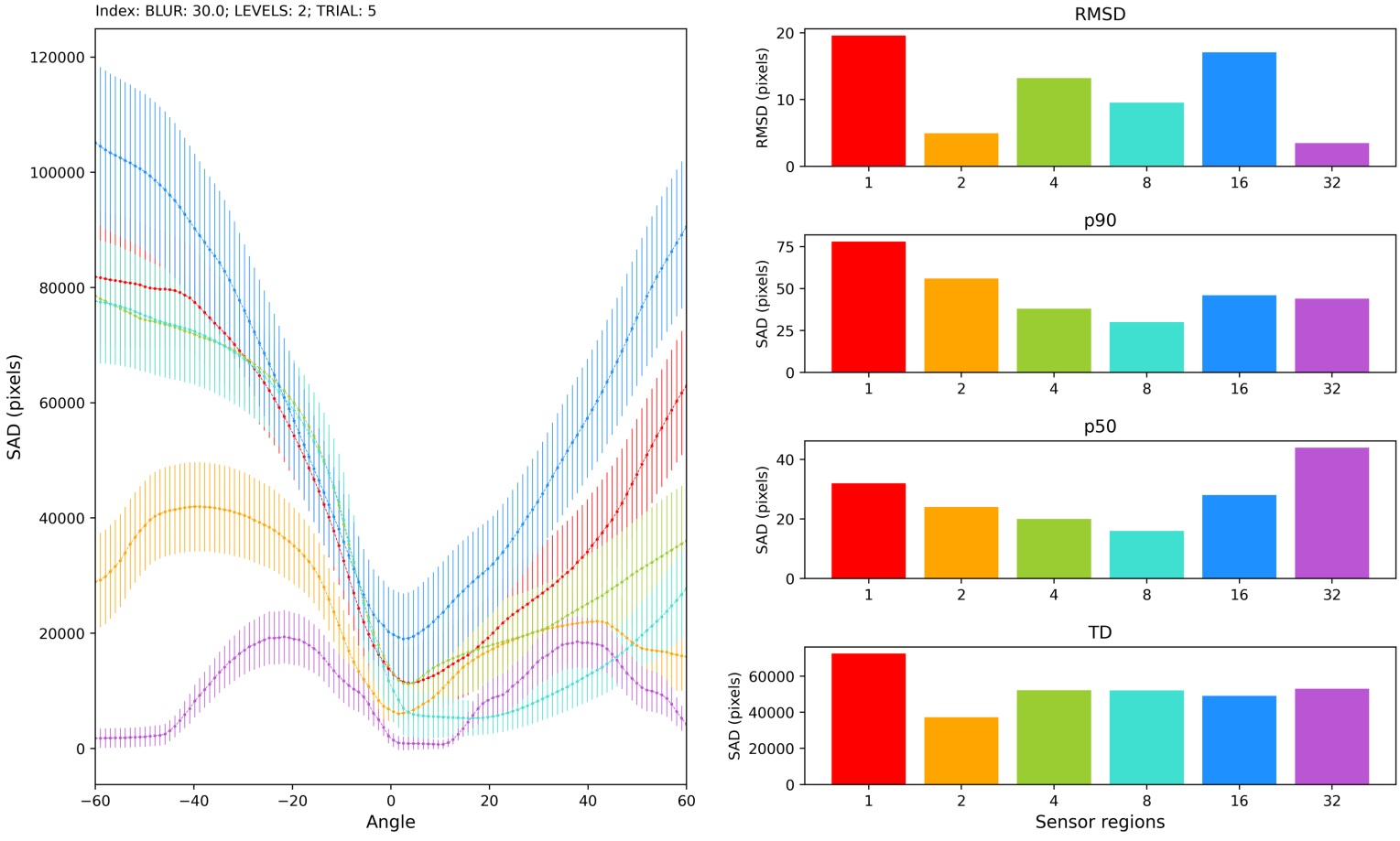


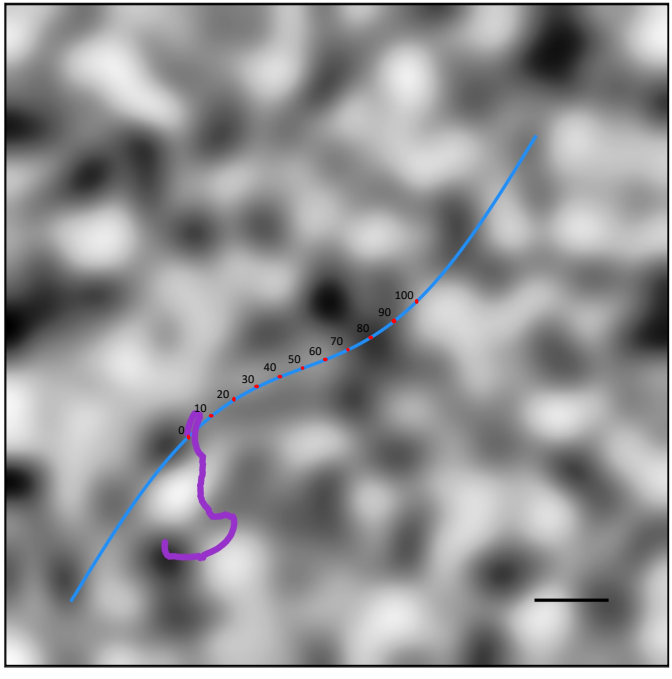


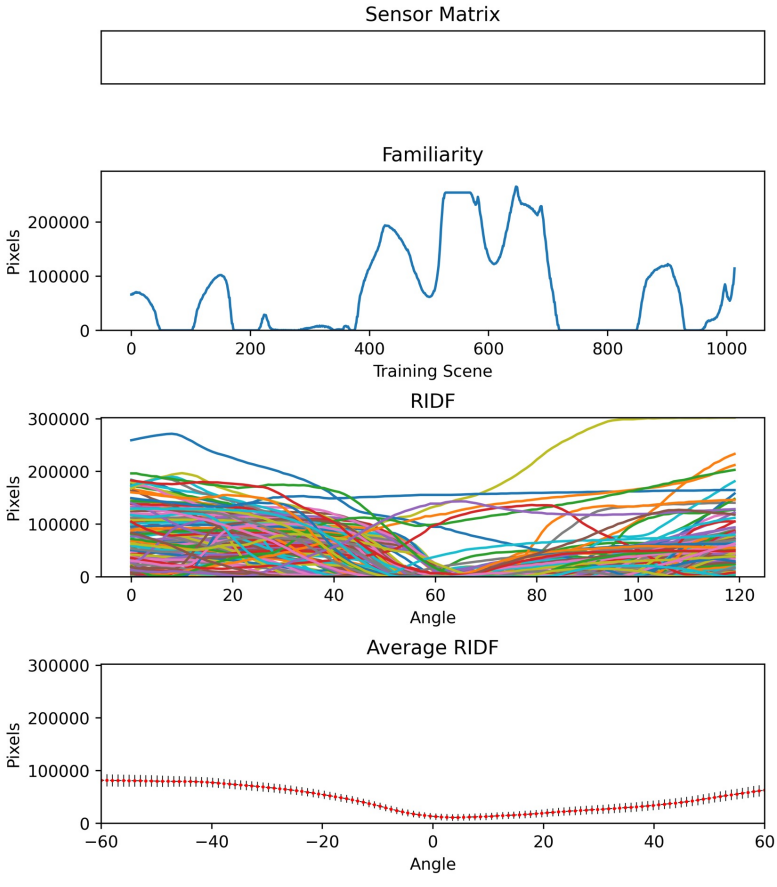
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 5645.61; RMSD/dist: 14.114; TD: 69499; p90: 48; p50: 20; complete: 0


Index: BLUR: 30.0; LEVELS: 2; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 7843.86; RMSD/dist: 19.610; TD: 72474; p90: 78; p50: 32; complete: 0

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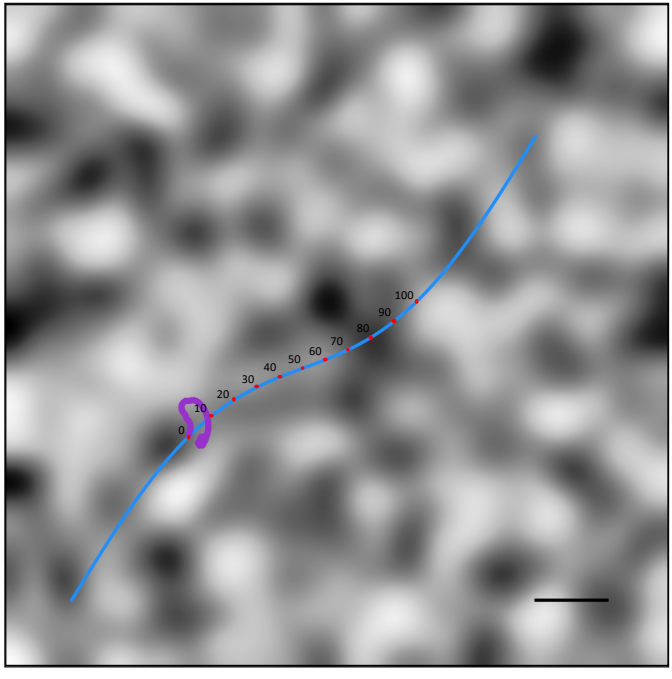

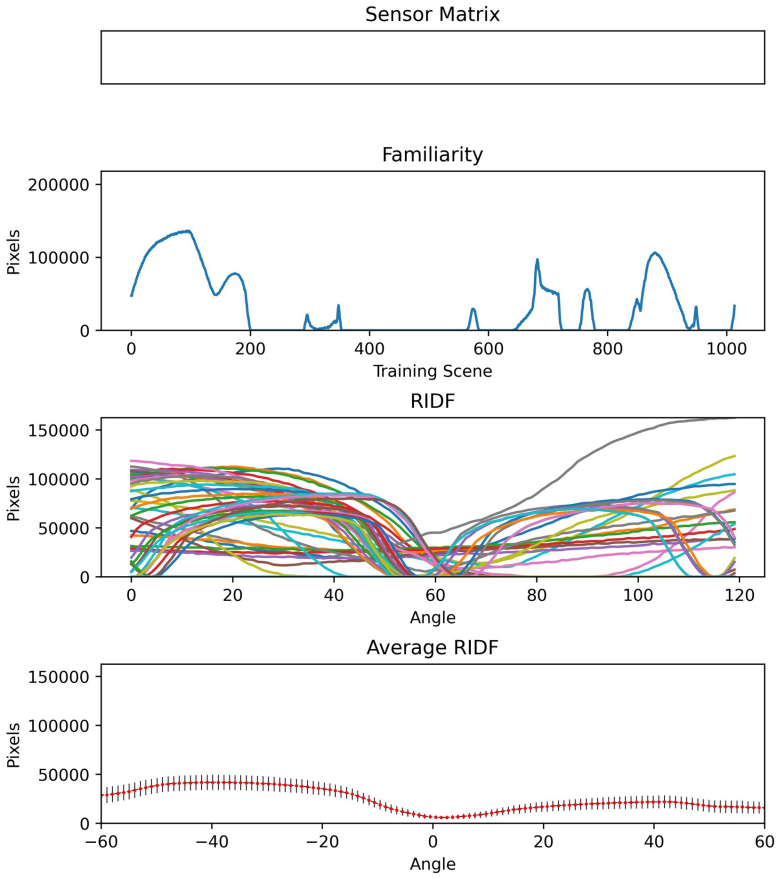

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1978.11; RMSD/dist: 4.945; TD: 37187; p90: 56; p50: 24; complete: 0

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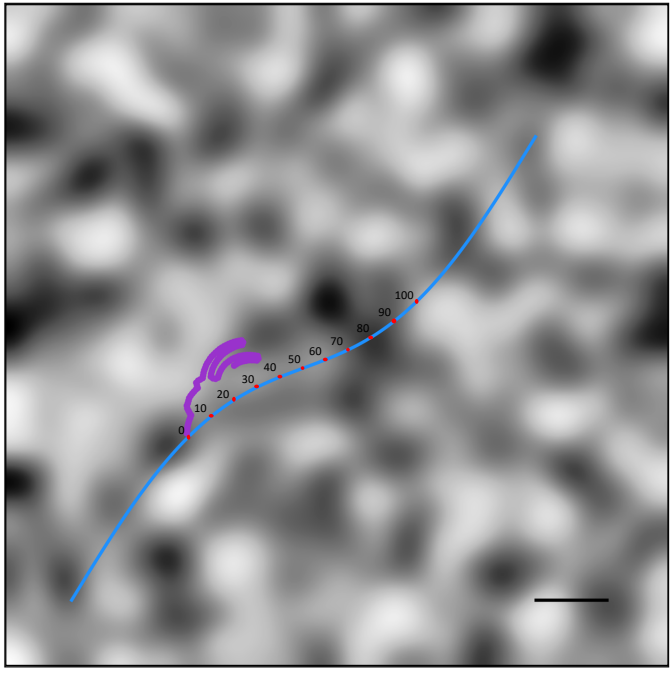

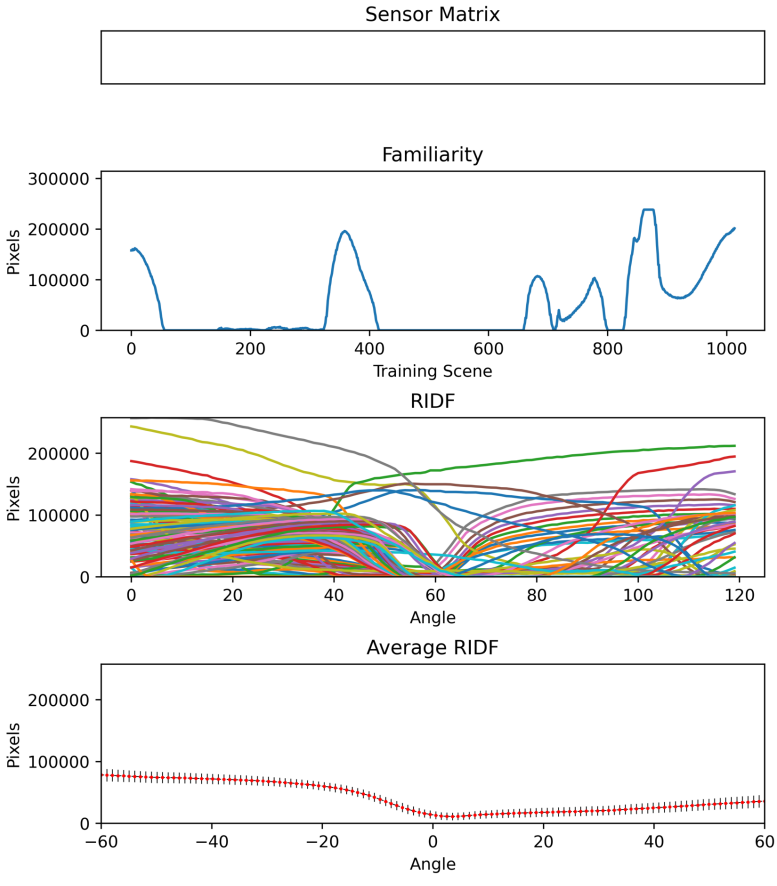

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5291.96; RMSD/dist: 13.230; TD: 52201; p90: 38; p50: 20; complete: 0

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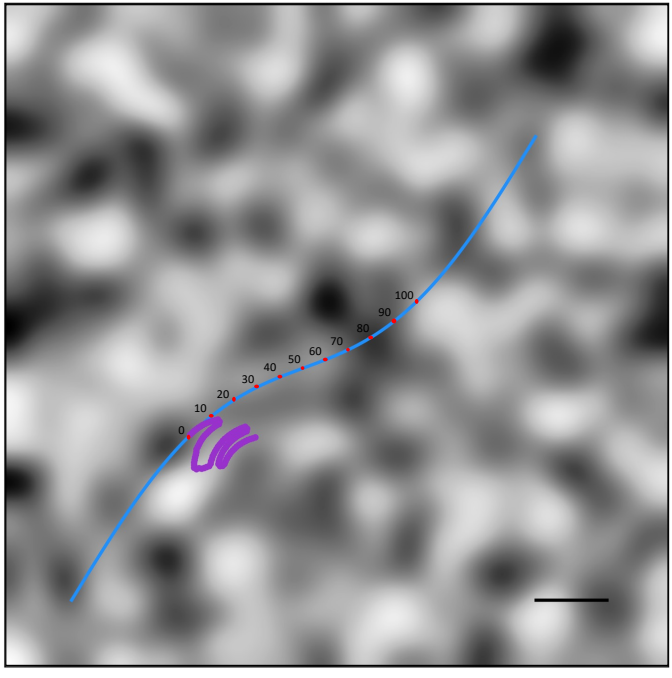

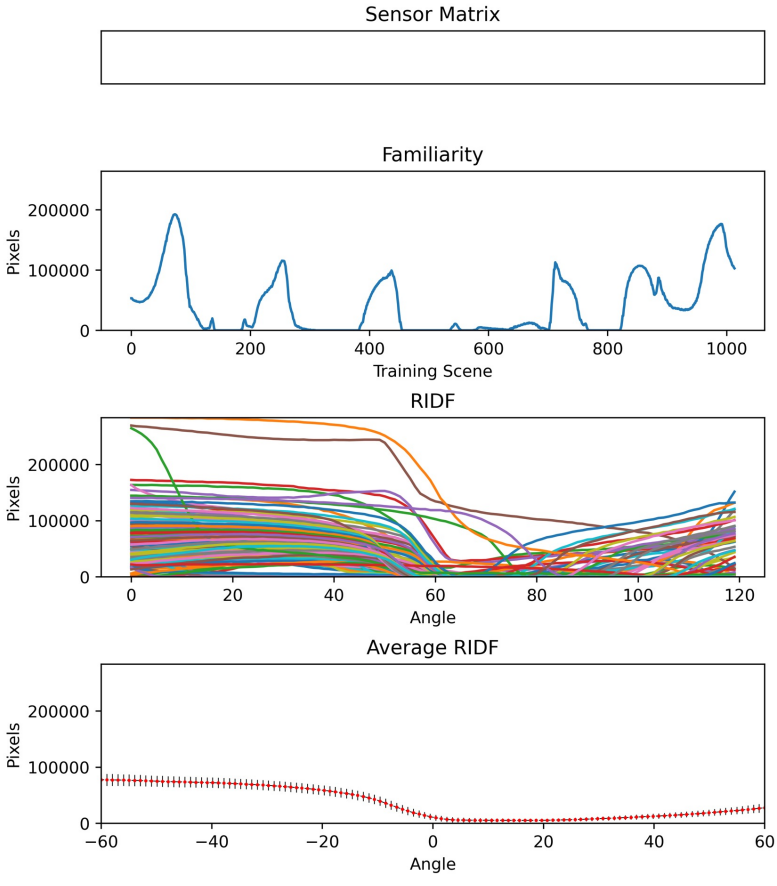

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 3822.72; RMSD/dist: 9.557; TD: 52081; p90: 30; p50: 16; complete: 0

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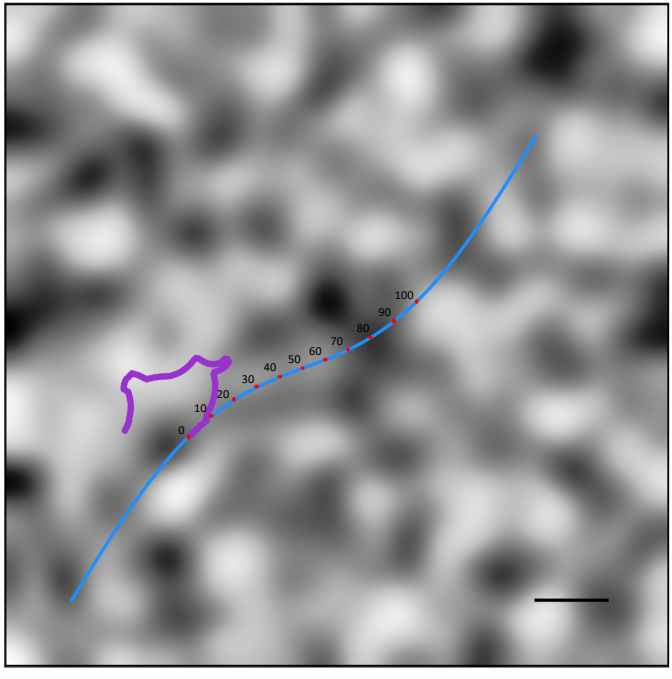

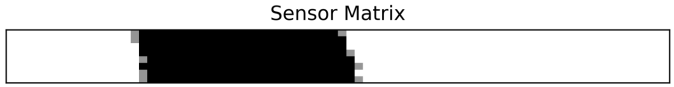

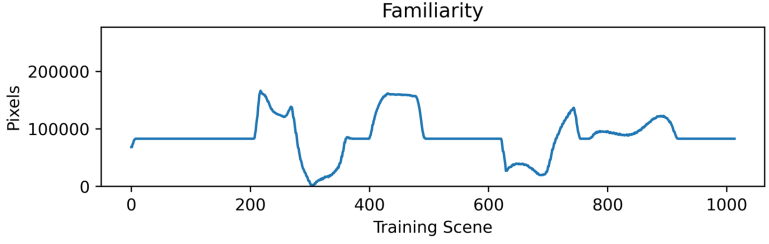

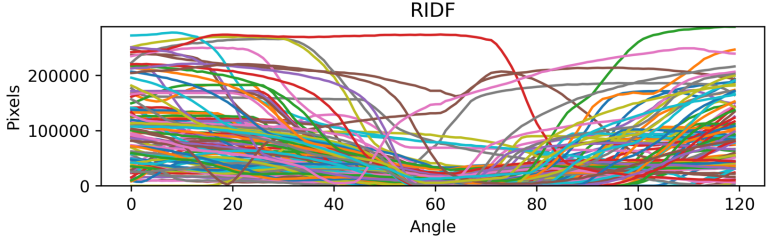

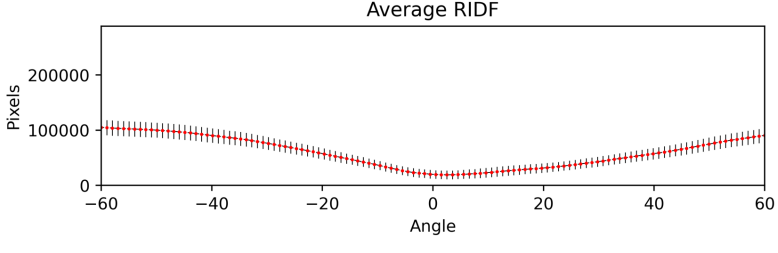

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 6828.40; RMSD/dist: 17.071; TD: 49094; p90: 46; p50: 28; complete: 0

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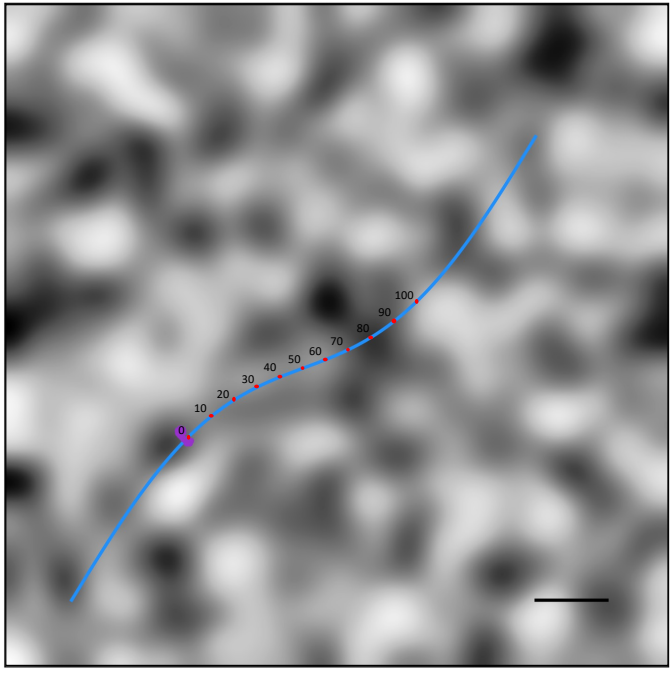
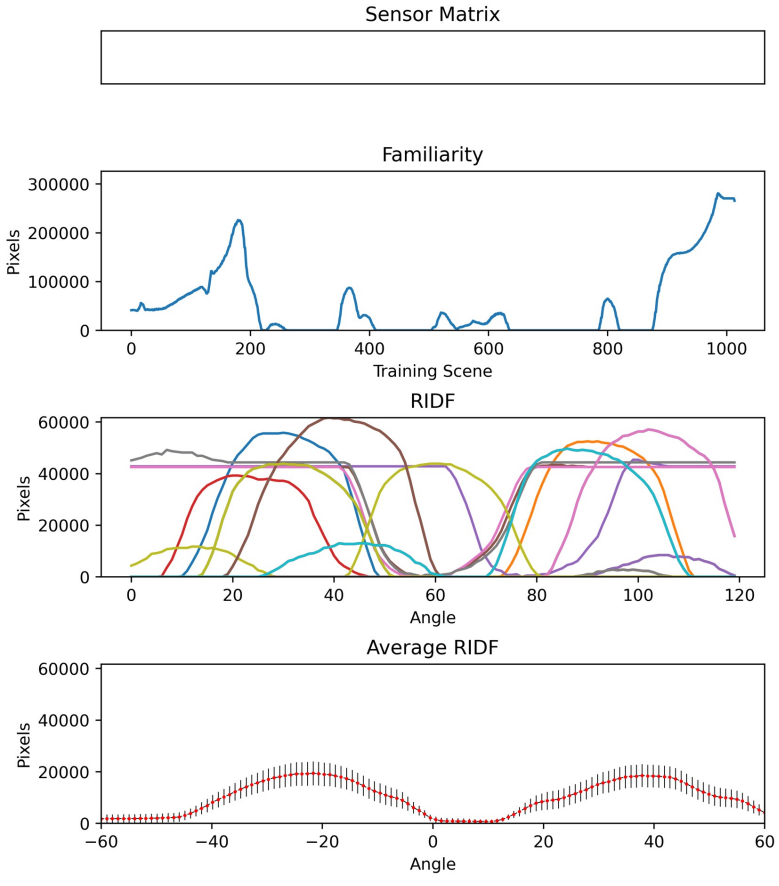
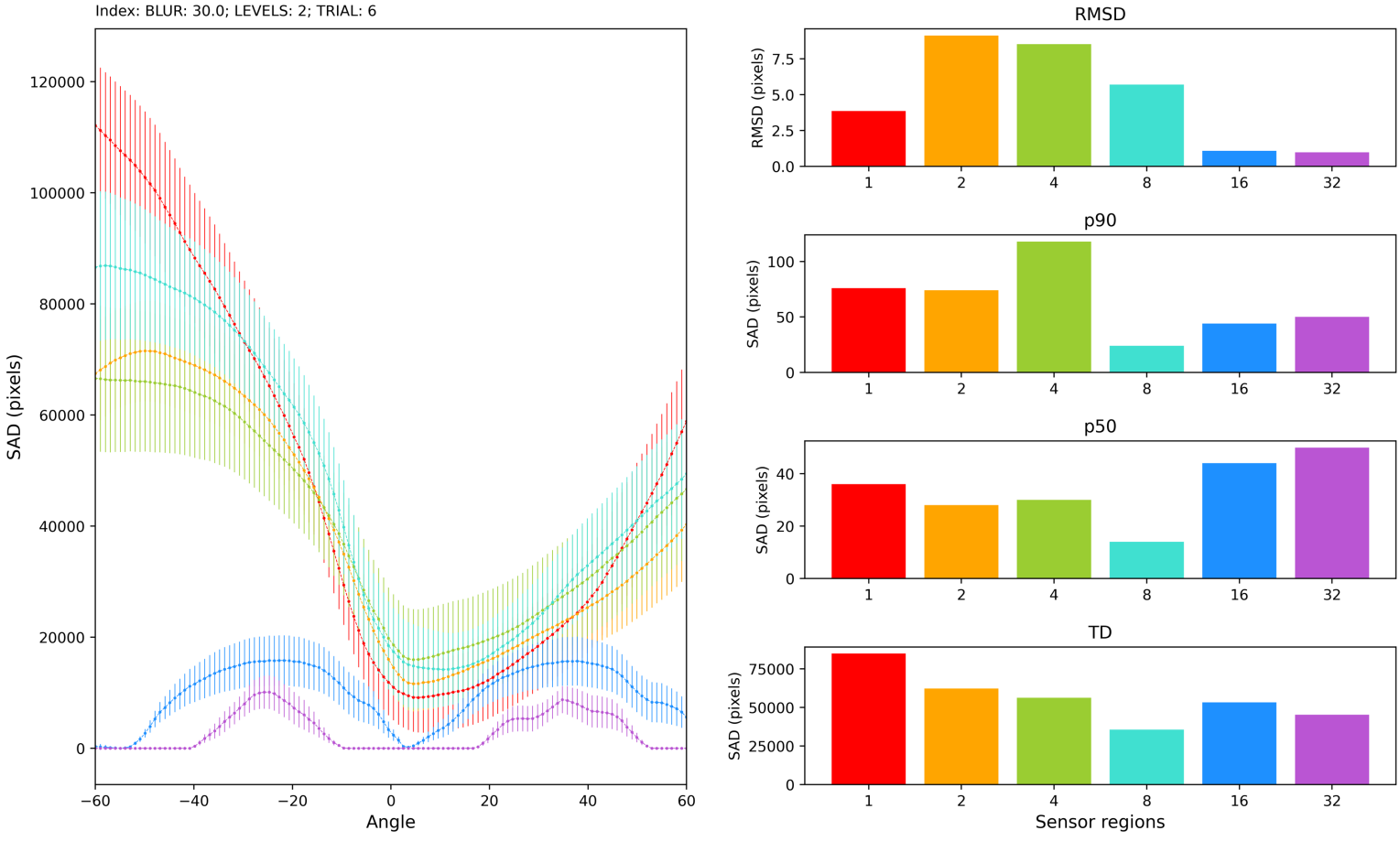


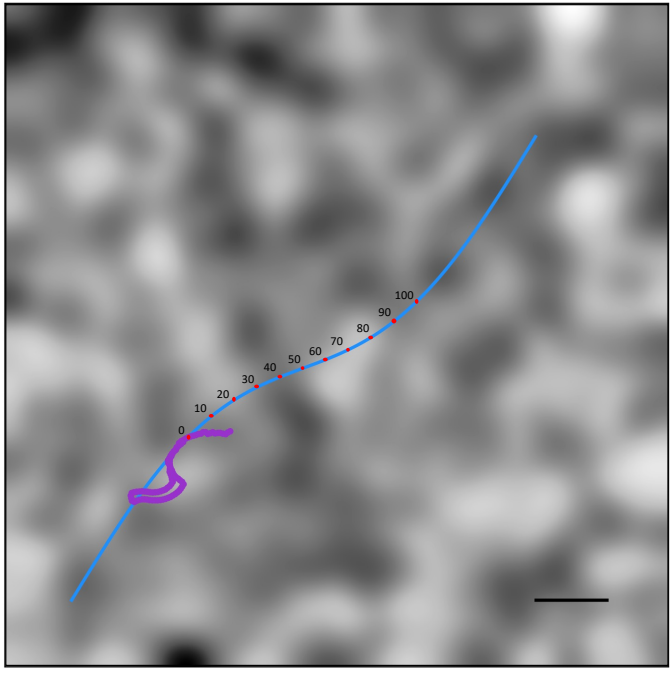


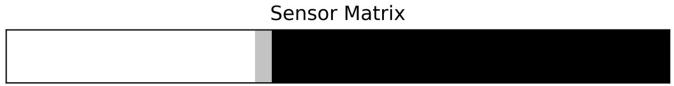
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

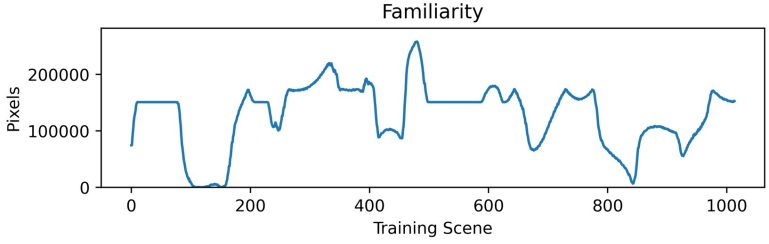
Navigation stats: RMSD error: 1385.39; RMSD/dist: 3.463; TD: 53005; p90: 44; p50: 44; complete: 0

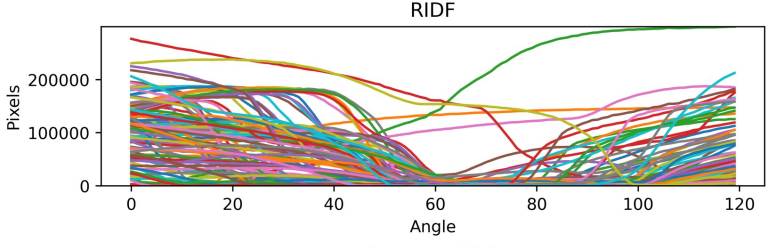

Index: BLUR: 30.0; LEVELS: 2; TRIAL: 6
SAD (pixels)
120000
100000
80000
60000
40000
20000
0
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
7.5
5.0
2.5
0.0
p90
SAD (pixels)
100
50
0
p50
SAD (pixels)
40
20
0
TD
SAD (pixels)
75000
50000
25000
0
1
2
4
8
16
32
Sensor regions

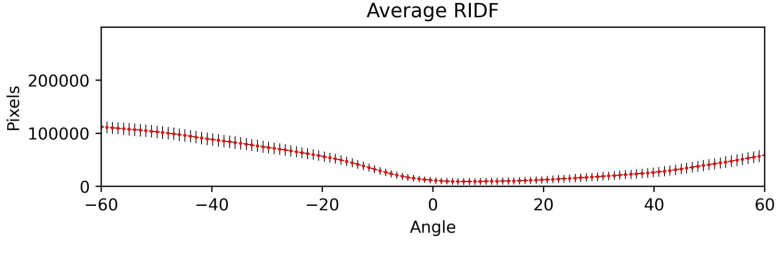
0%











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Navigation stats: RMSD error: 1547.28; RMSD/dist: 3.868; TD: 84807; p90: 76; p50: 36; complete: 0

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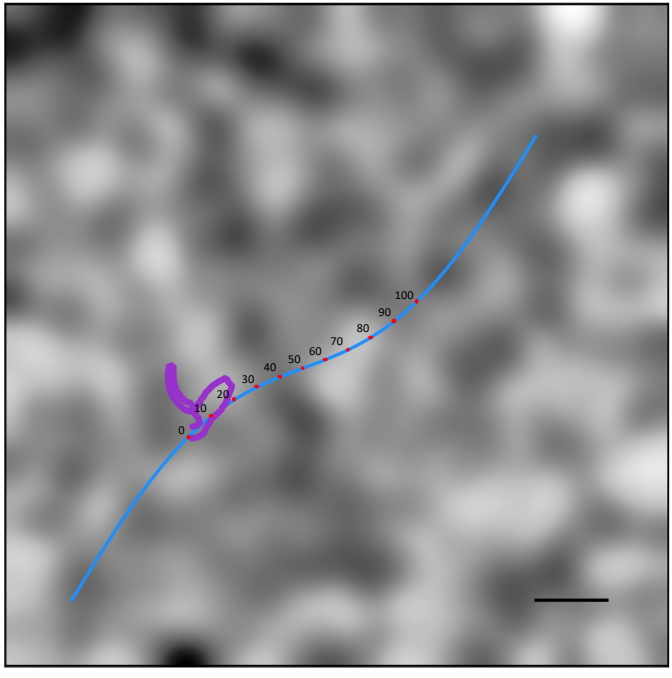

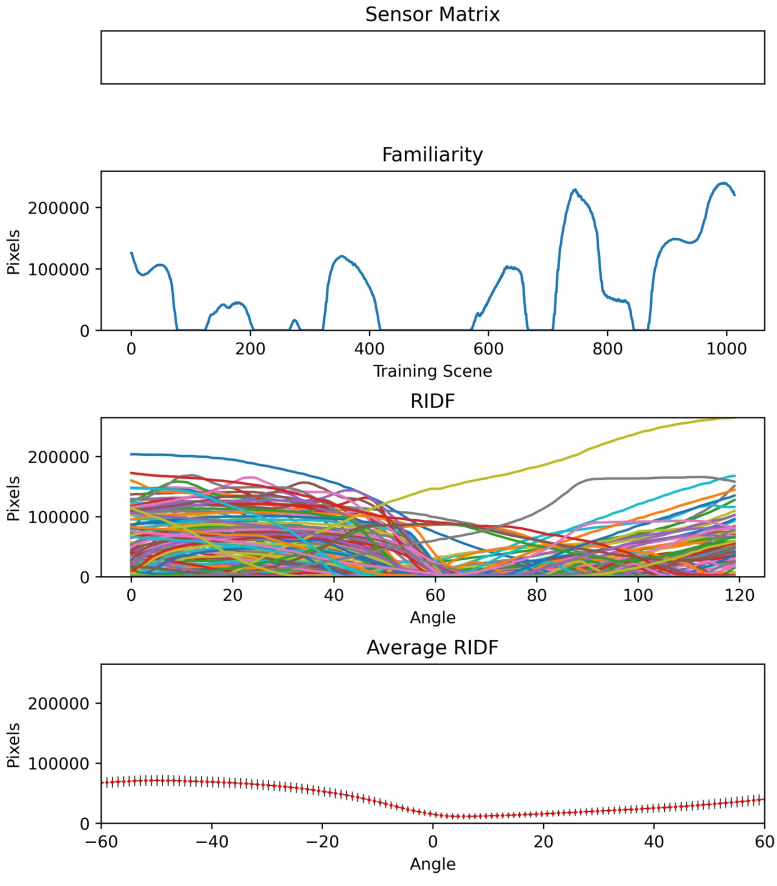

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 3655.79; RMSD/dist: 9.139; TD: 62221; p90: 74; p50: 28; complete: 0

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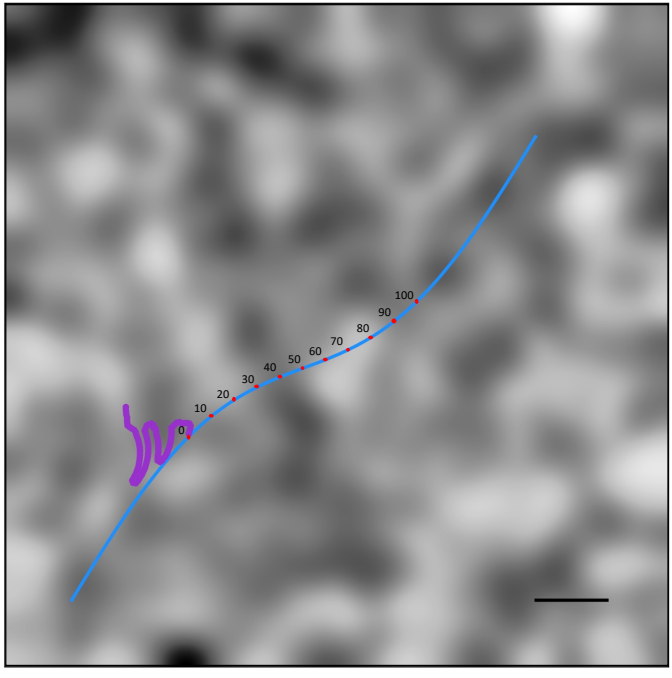

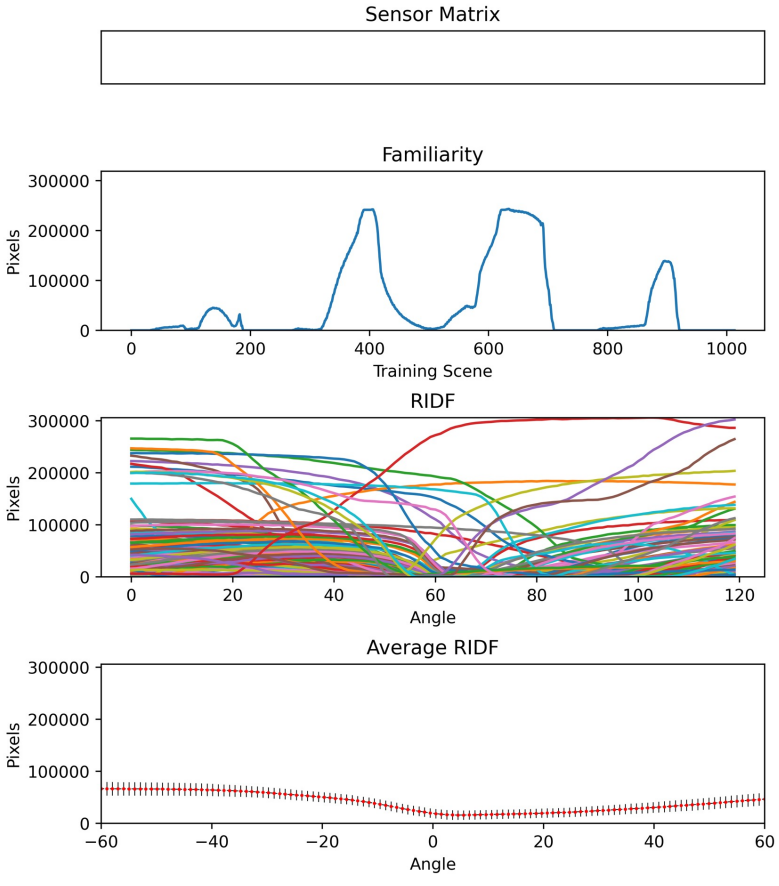

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Navigation stats: RMSD error: 3411.63; RMSD/dist: 8.529; TD: 56191; p90: 118; p50: 30; complete: 0

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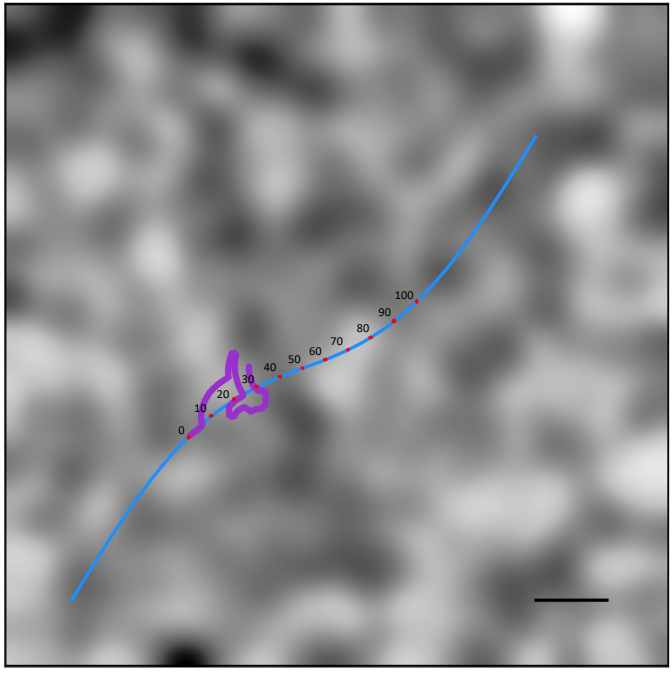

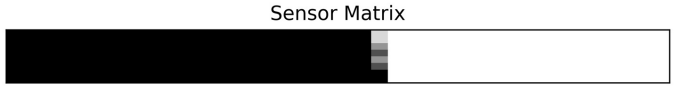

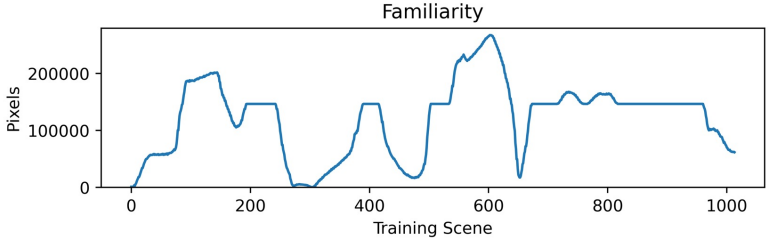

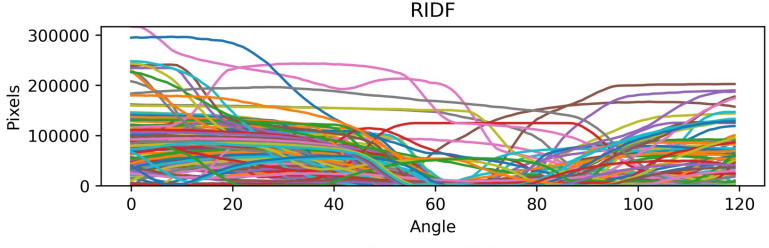

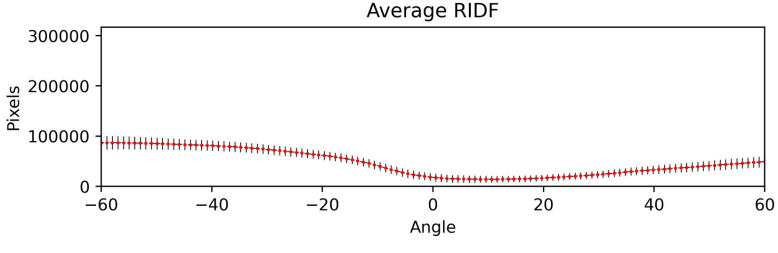

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 2280.24; RMSD/dist: 5.701; TD: 35577; p90: 24; p50: 14; complete: 0

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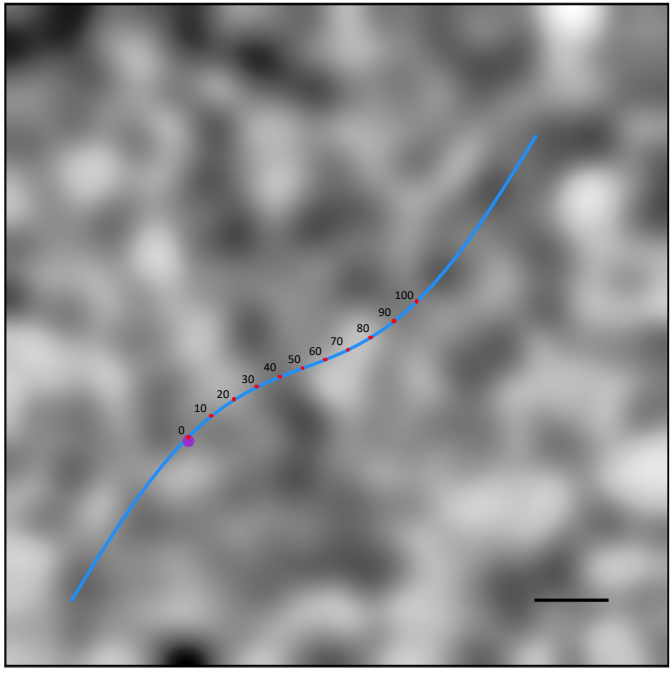

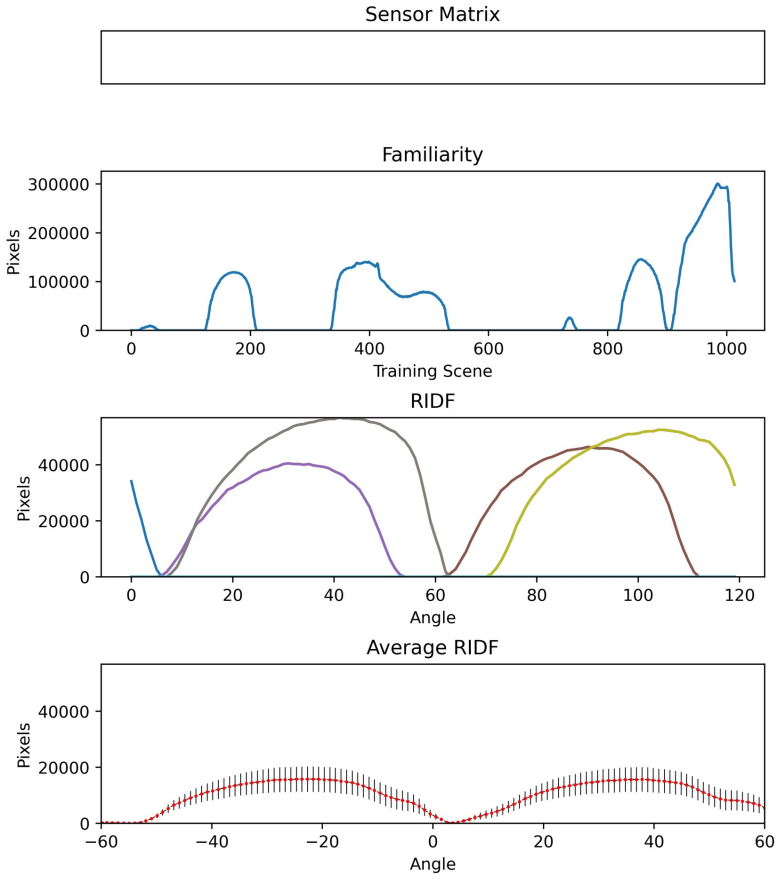

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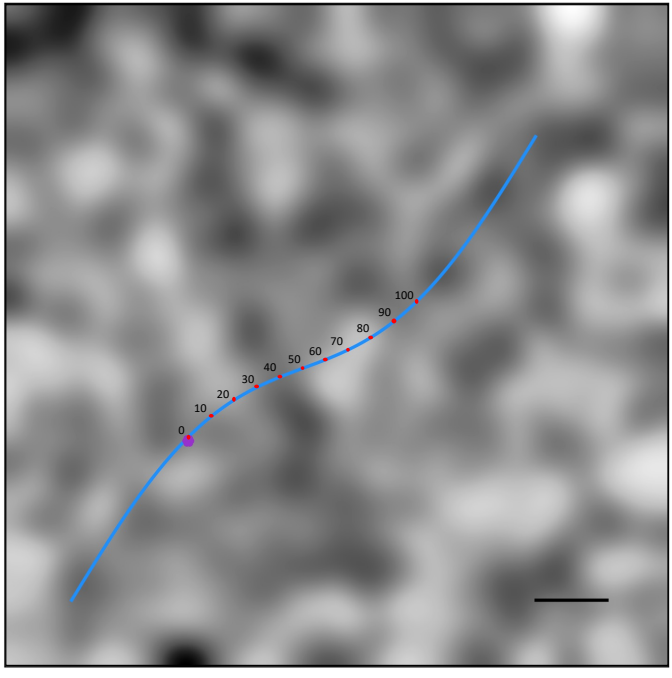
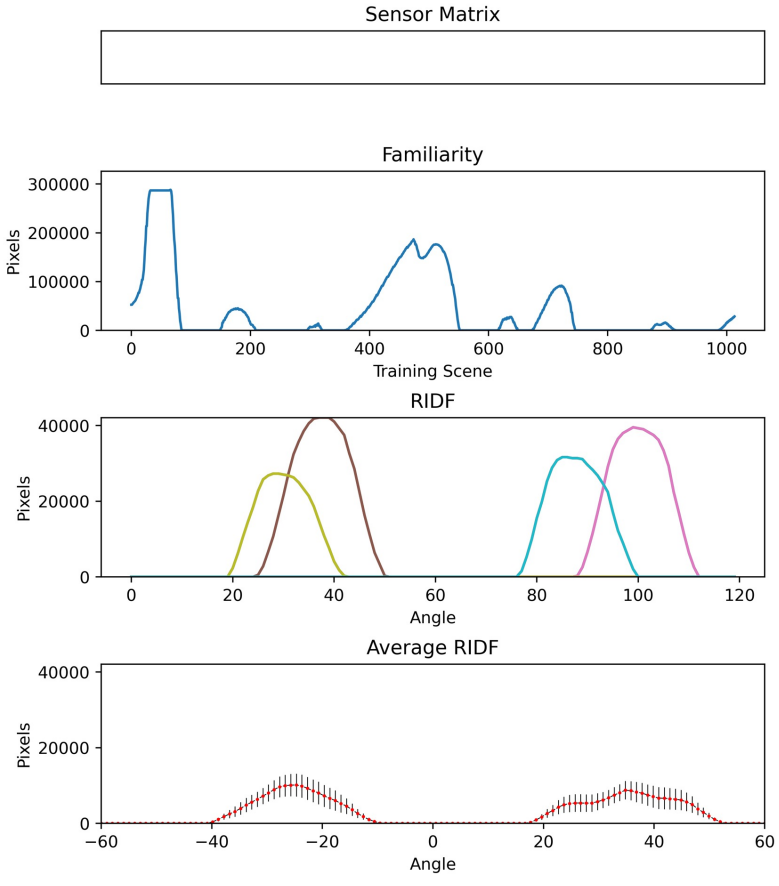
Navigation stats: RMSD error: 432.62; RMSD/dist: 1.082; TD: 53240; p90: 44; p50: 44; complete: 0

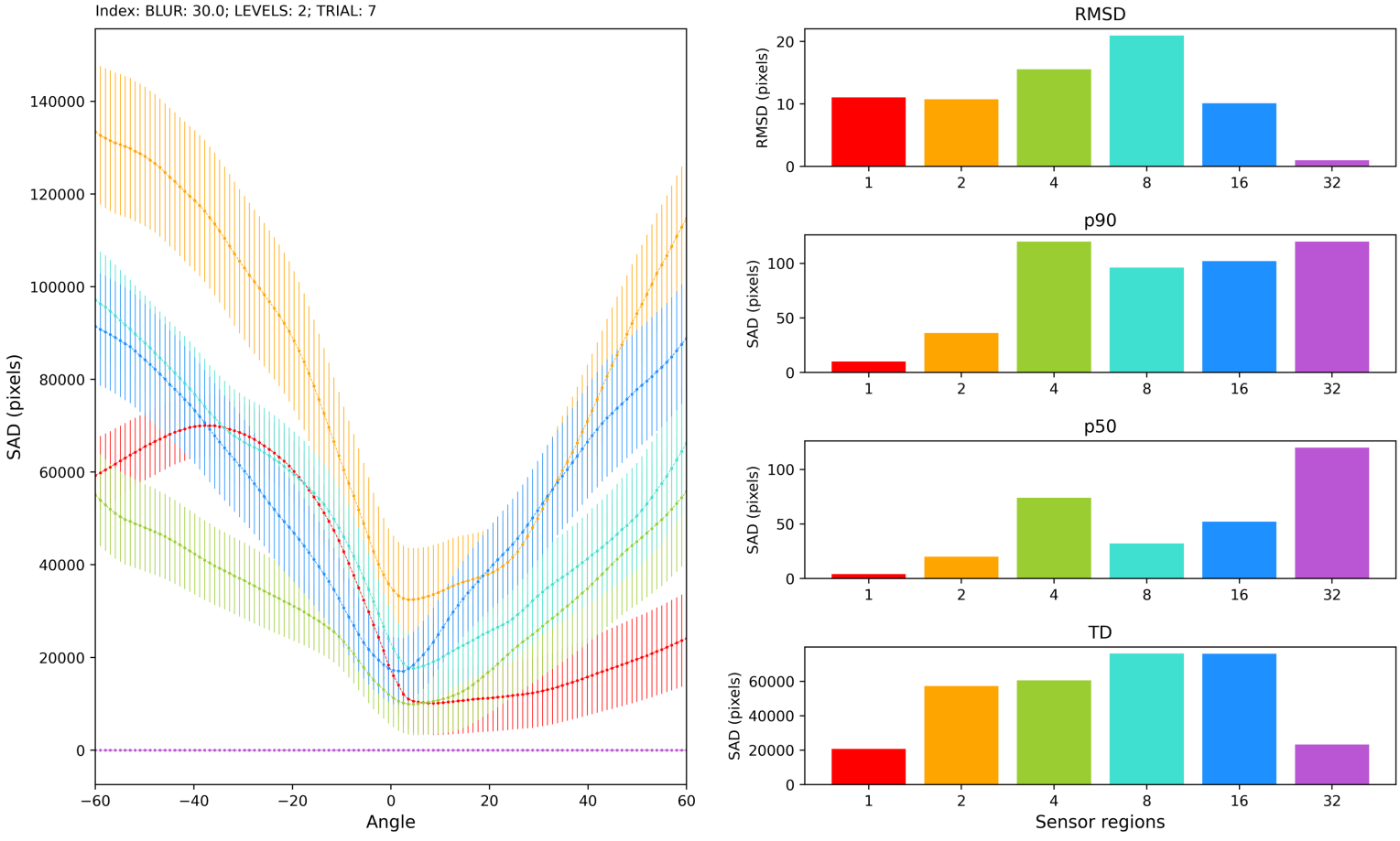
0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 45174; p90: 50; p50: 50; complete: 0


Index: BLUR: 30.0; LEVELS: 2; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

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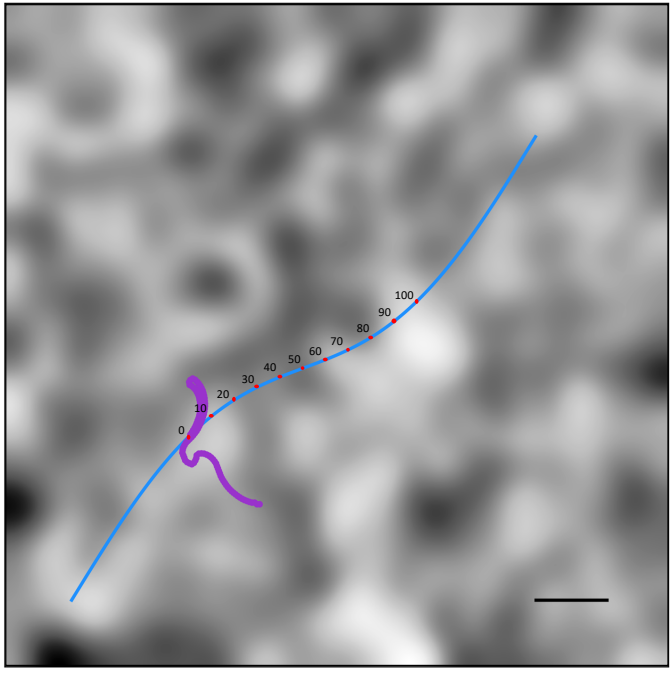

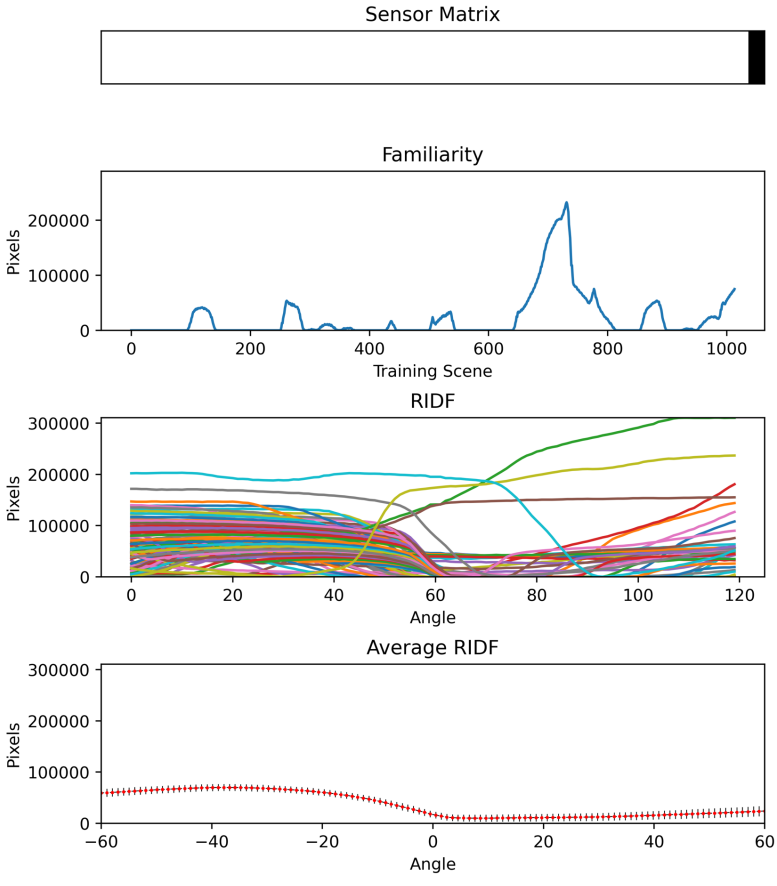

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Navigation stats: RMSD error: 4418.61; RMSD/dist: 11.047; TD: 20744; p90: 10; p50: 4; complete: 0

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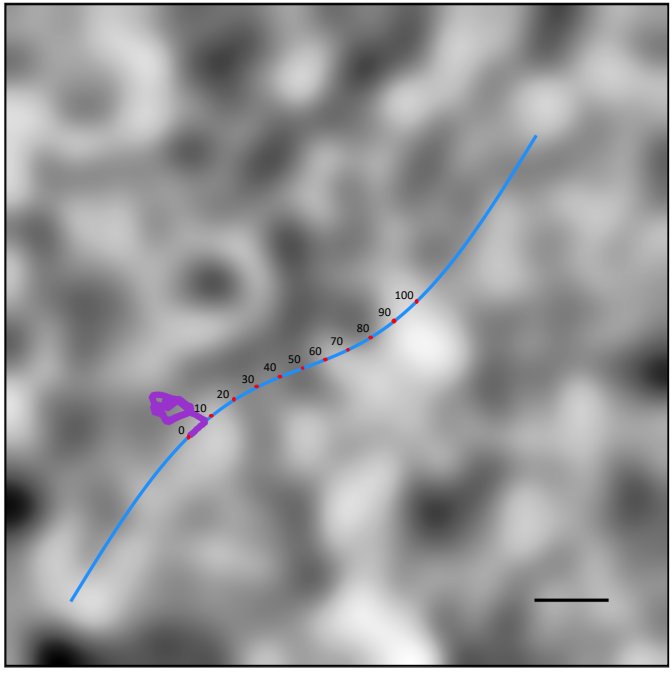
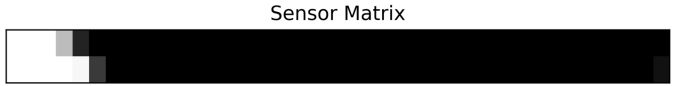
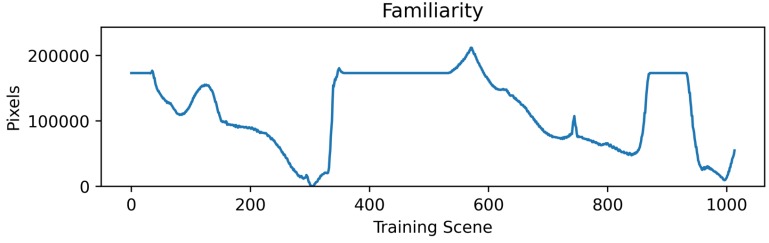
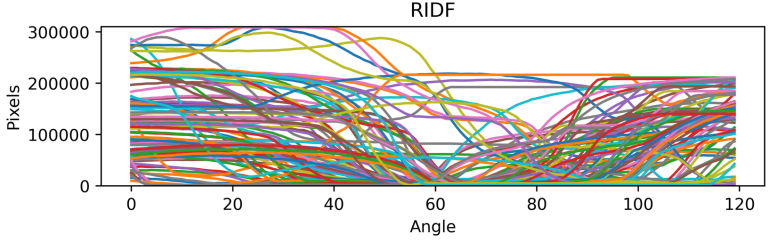
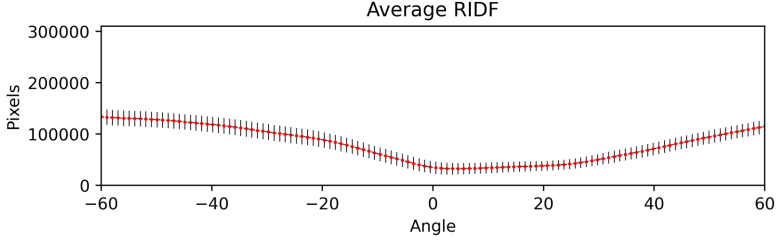






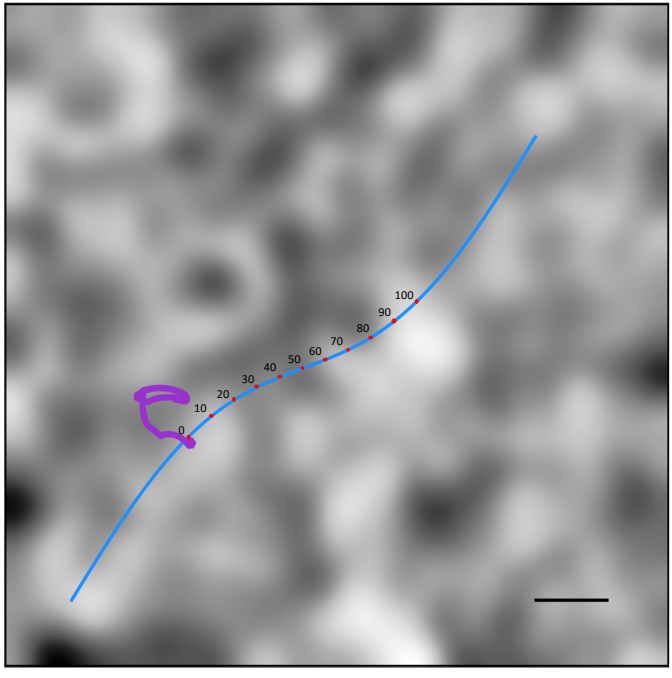


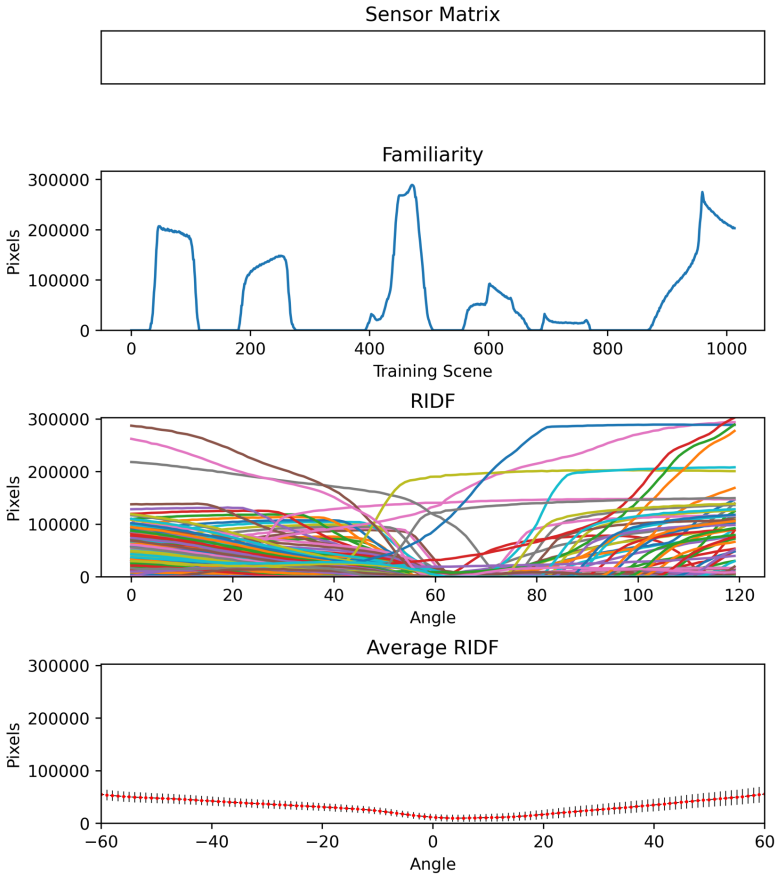


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 4288.76; RMSD/dist: 10.722; TD: 57312; p90: 36; p50: 20; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 6207.07; RMSD/dist: 15.518; TD: 60510; p90: 120; p50: 74; complete: 0

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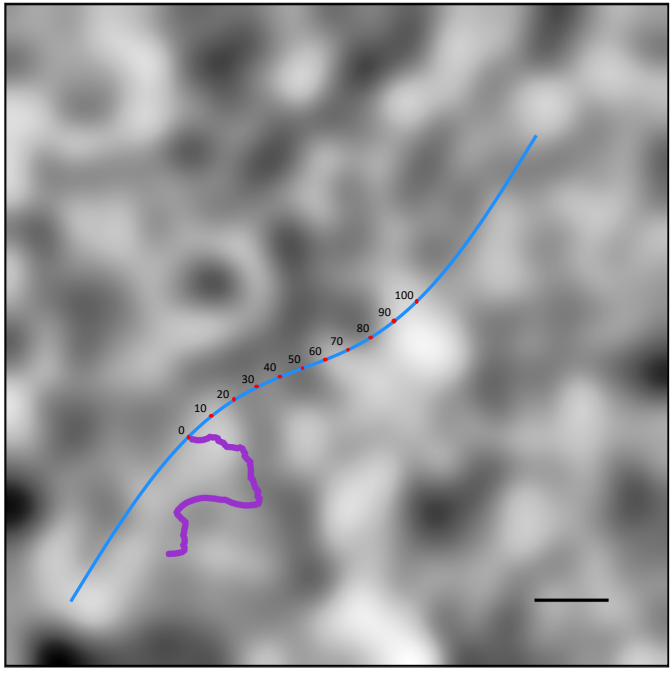
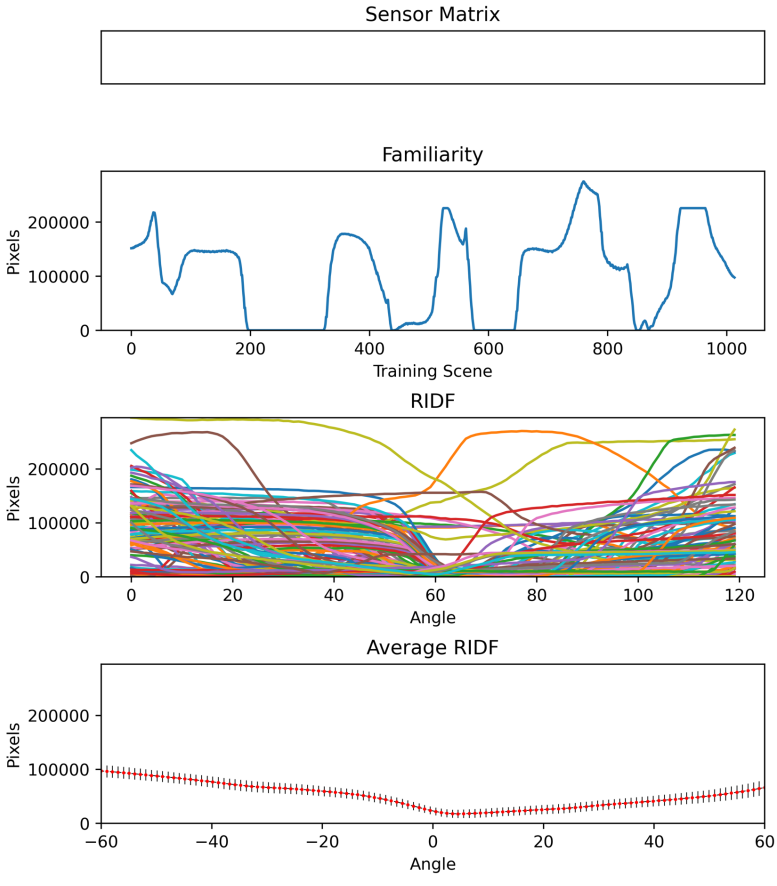
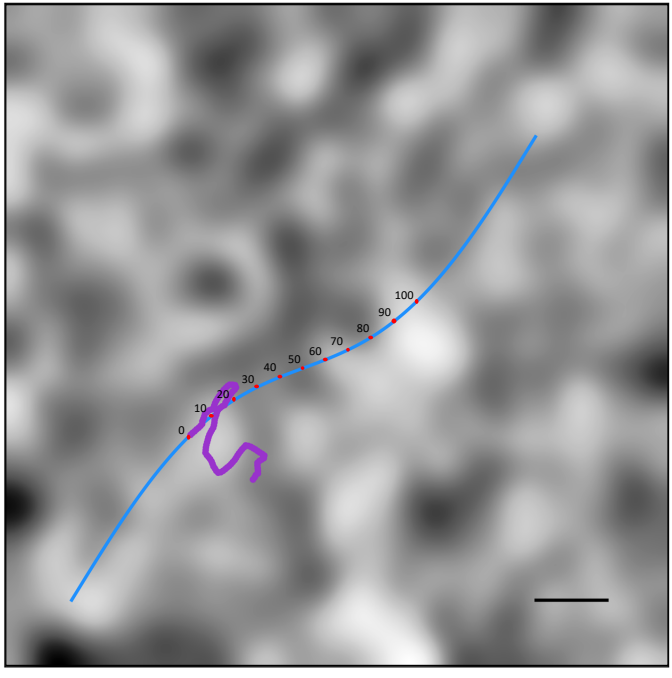


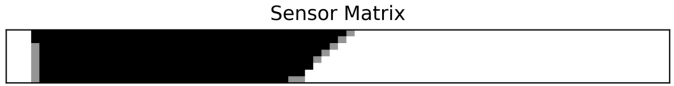


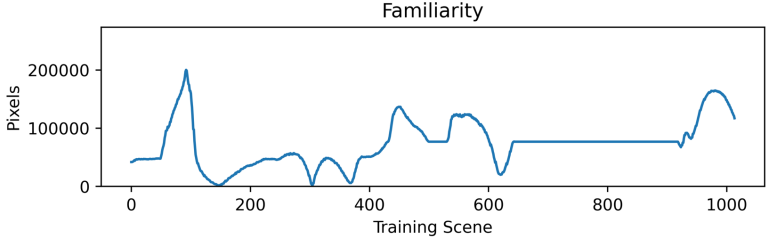
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

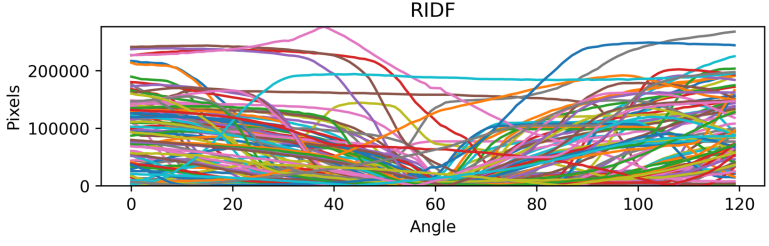
Navigation stats: RMSD error: 8380.99; RMSD/dist: 20.952; TD: 76108; p90: 96; p50: 32; complete: 0

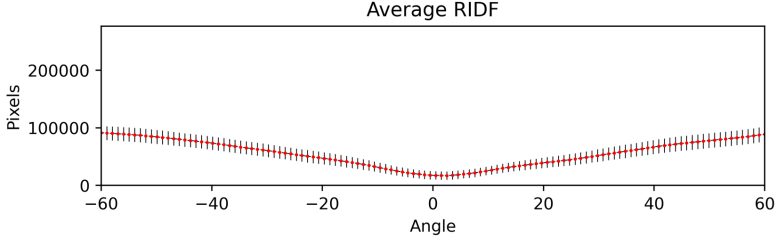
10%











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Navigation stats: RMSD error: 4041.13; RMSD/dist: 10.103; TD: 76047; p90: 102; p50: 52; complete: 0

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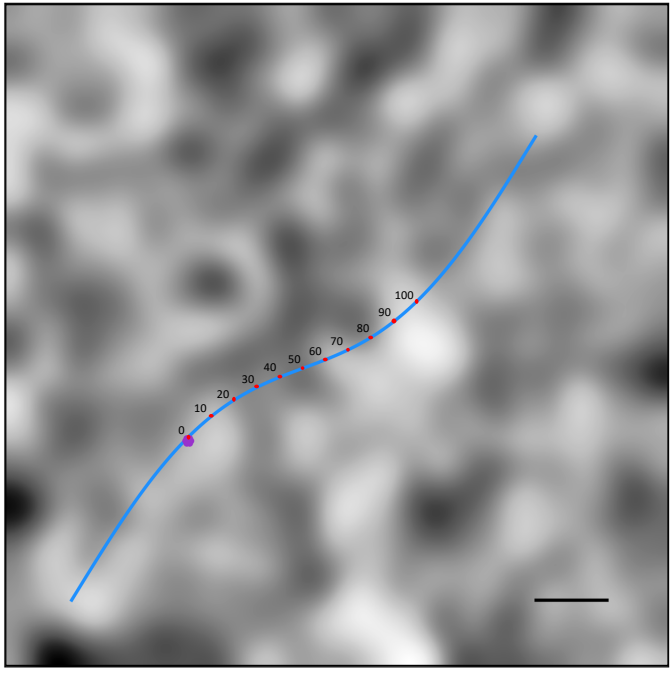
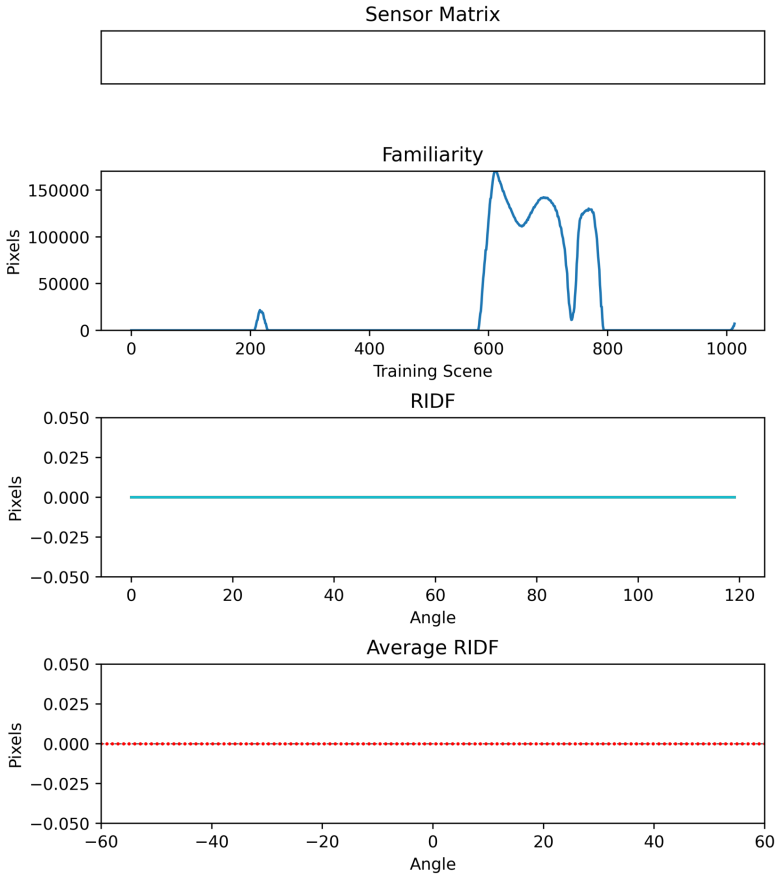
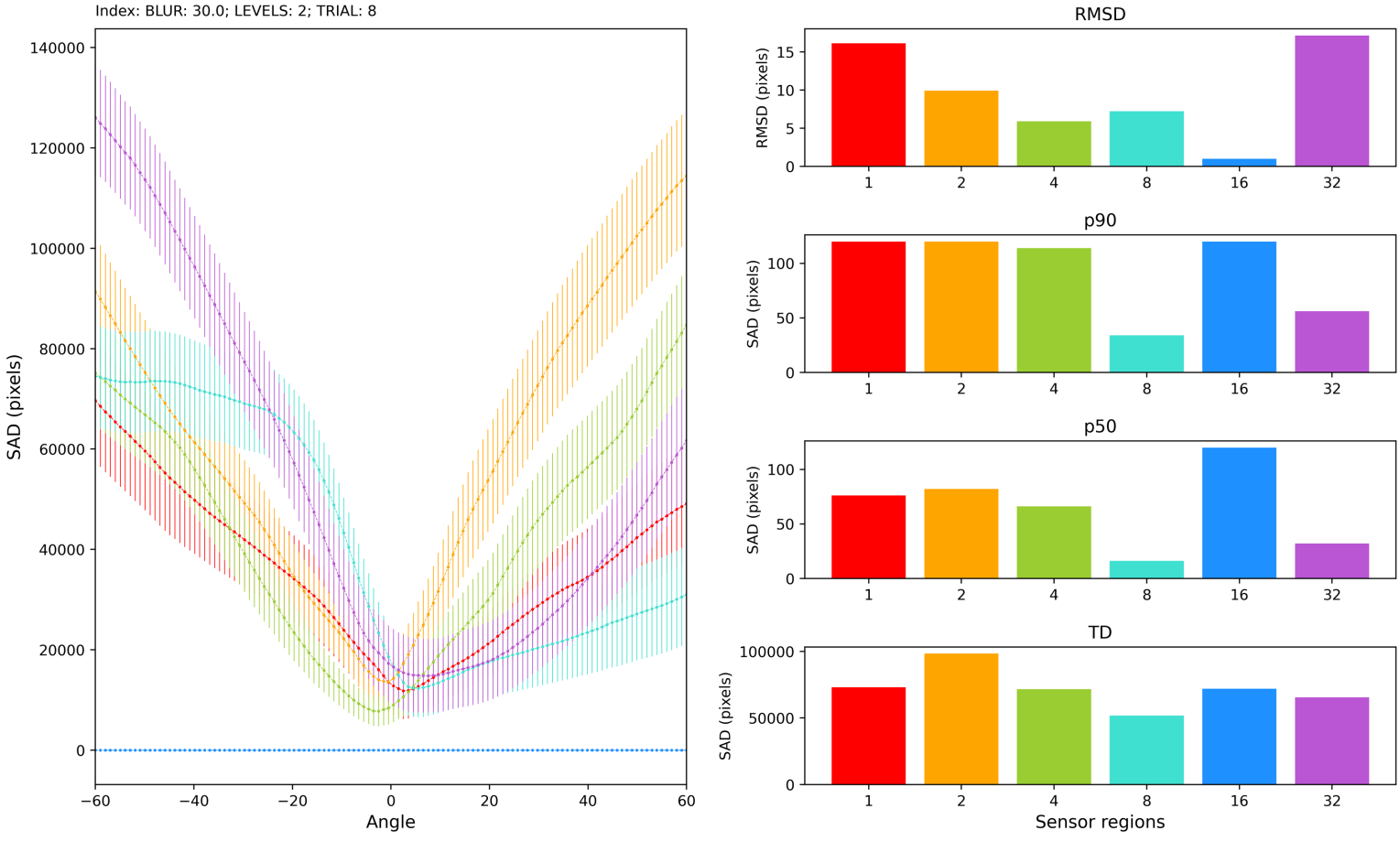


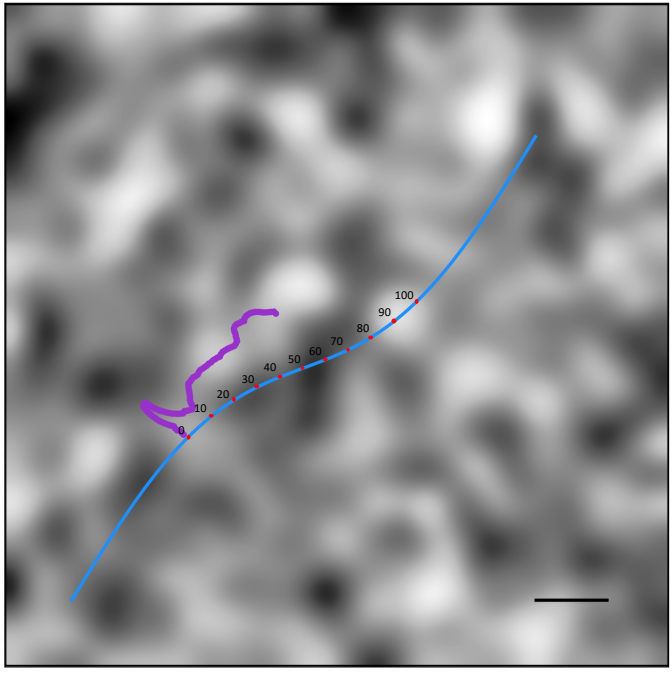


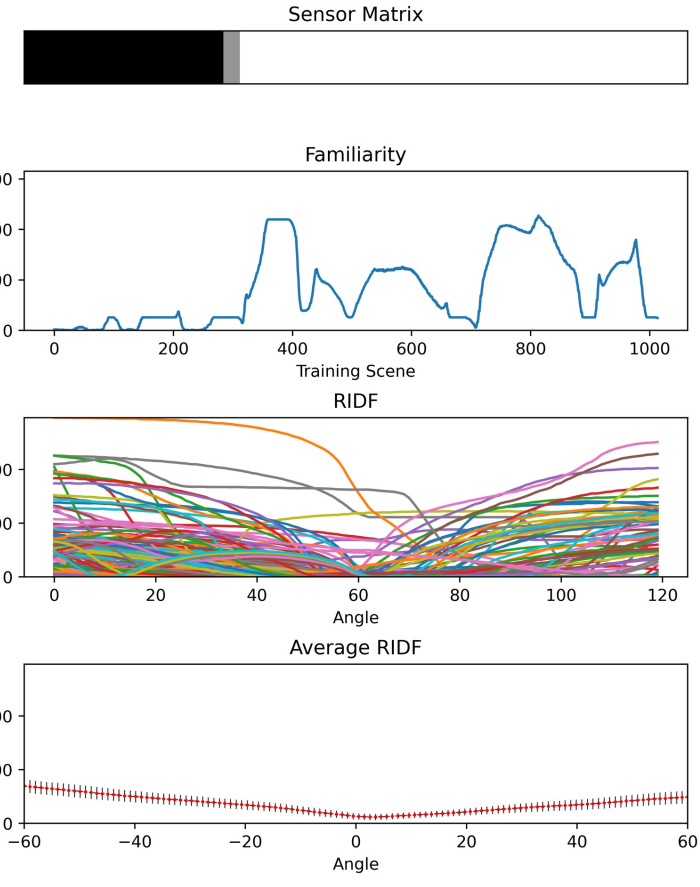
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 23257; p90: 120; p50: 120; complete: 0


Index: BLUR: 30.0; LEVELS: 2; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

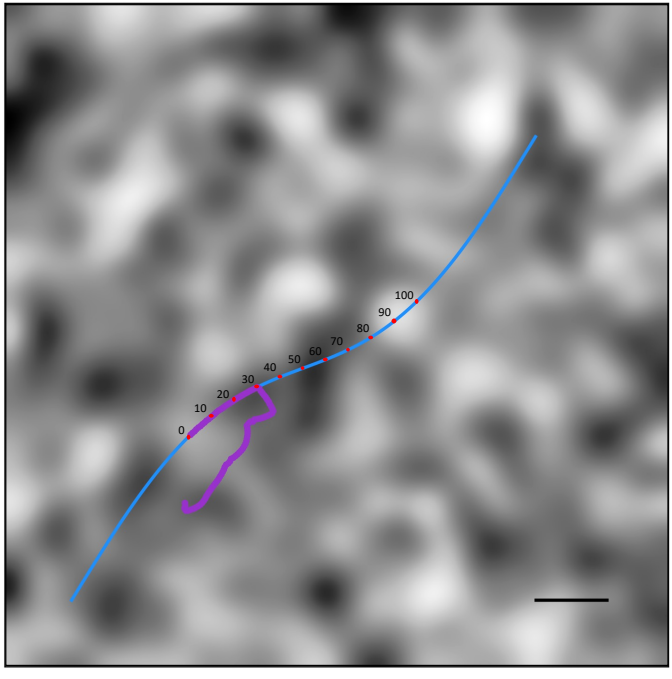


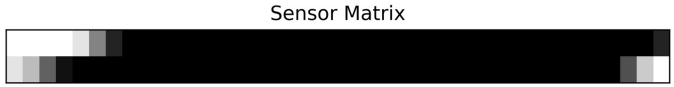


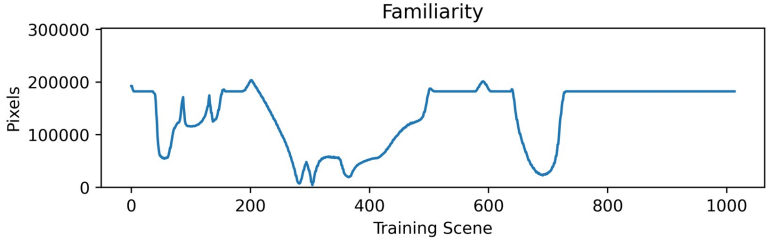
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

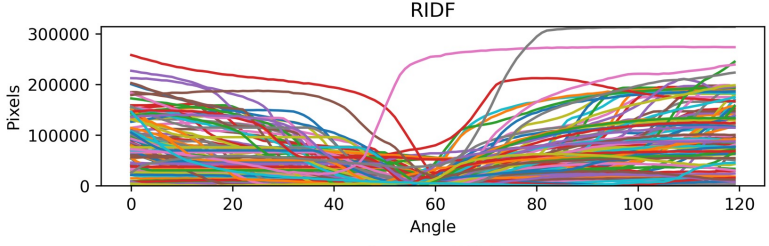
Navigation stats: RMSD error: 6449.34; RMSD/dist: 16.123; TD: 73091; p90: 120; p50: 76; complete: 0

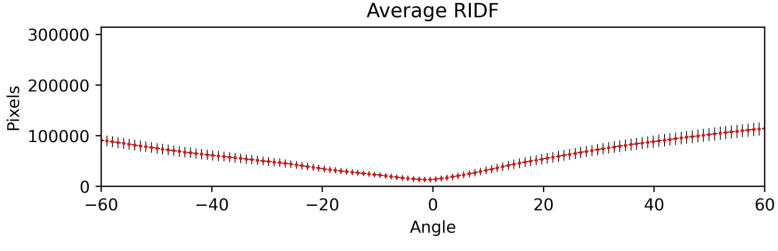
30%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 3965.54; RMSD/dist: 9.914; TD: 98377; p90: 120; p50: 82; complete: 0

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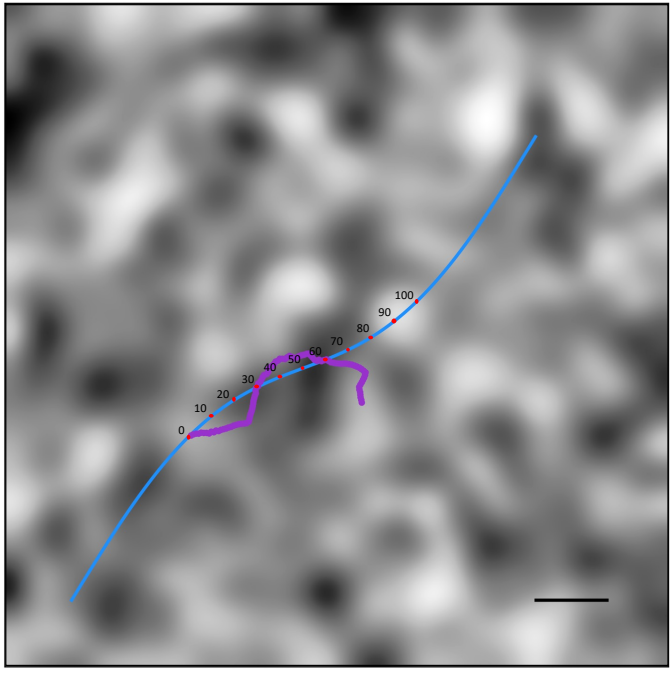

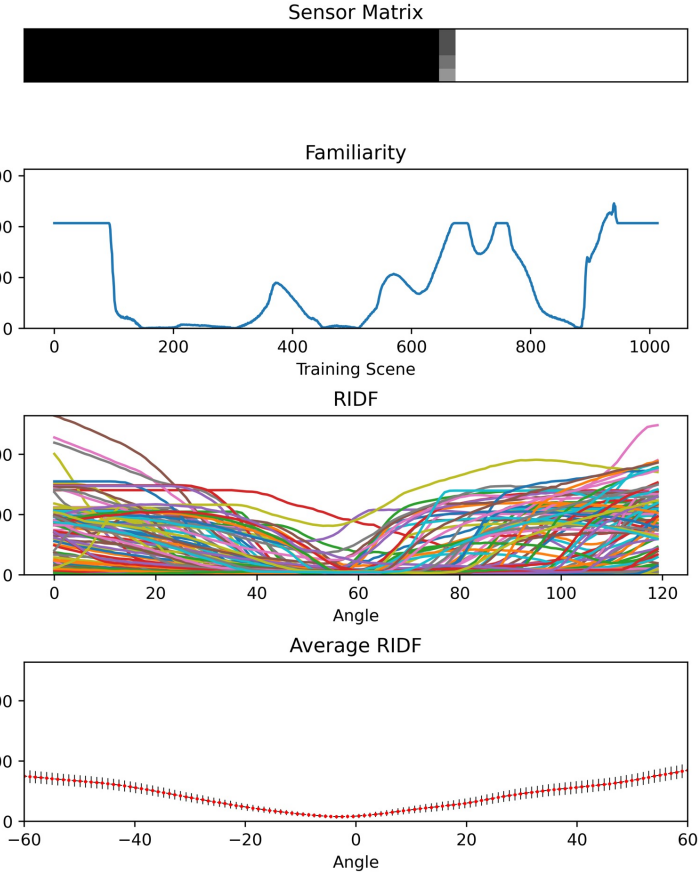

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2356.29; RMSD/dist: 5.891; TD: 71622; p90: 114; p50: 66; complete: 0

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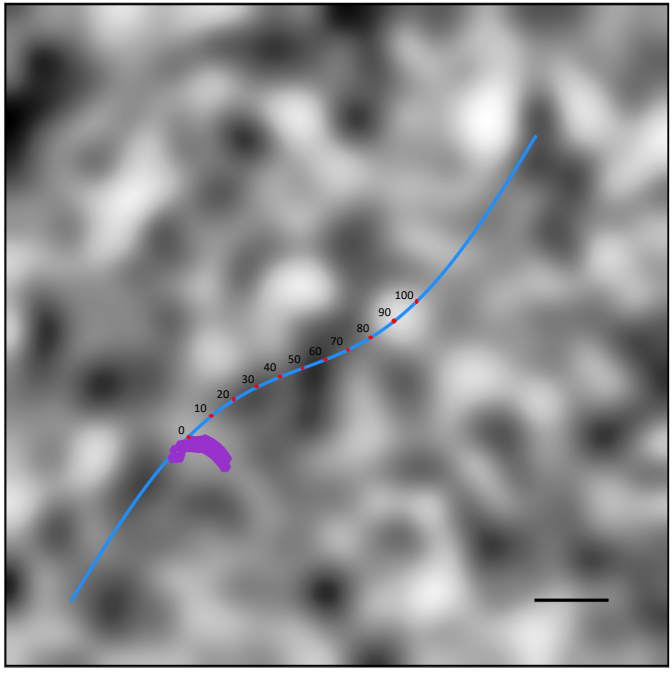

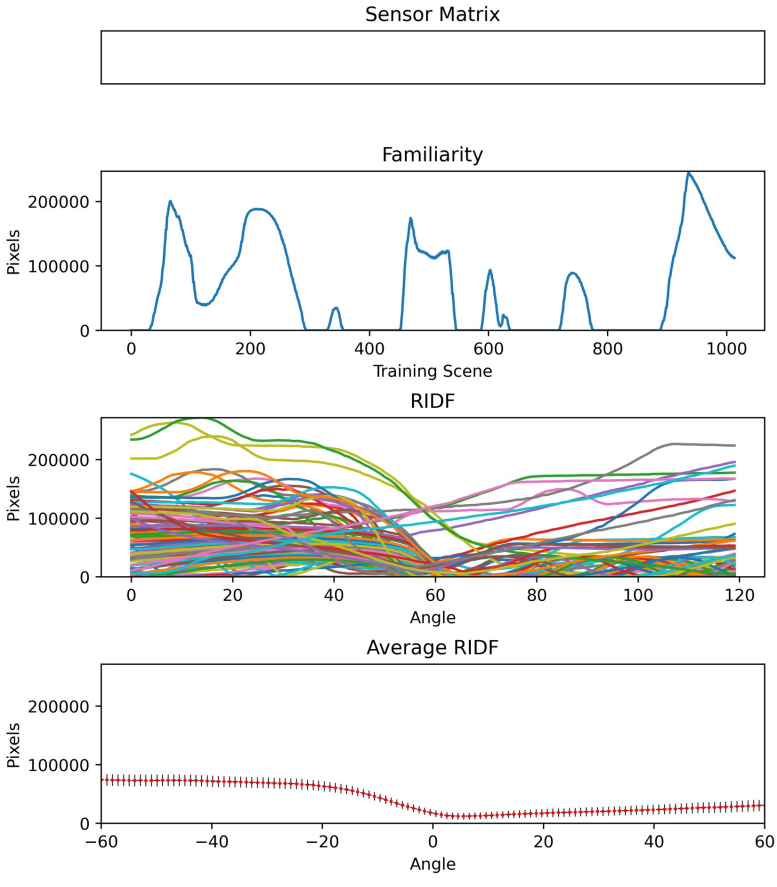

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

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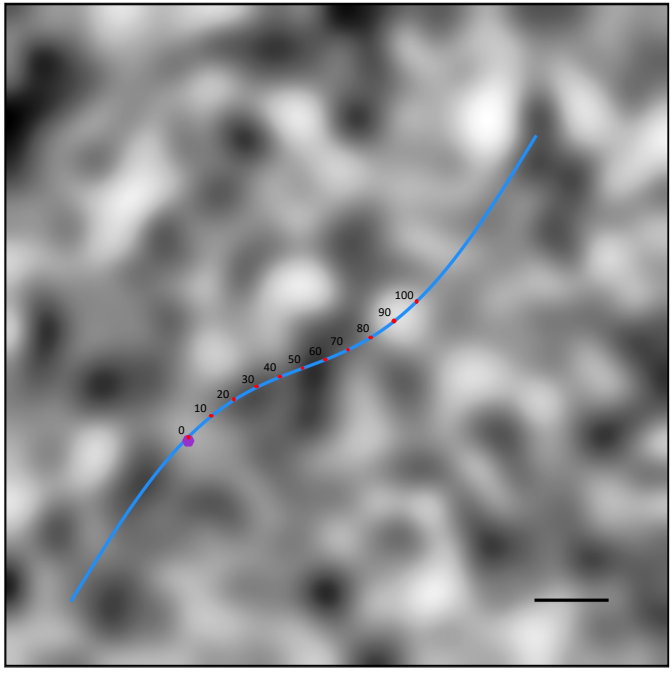

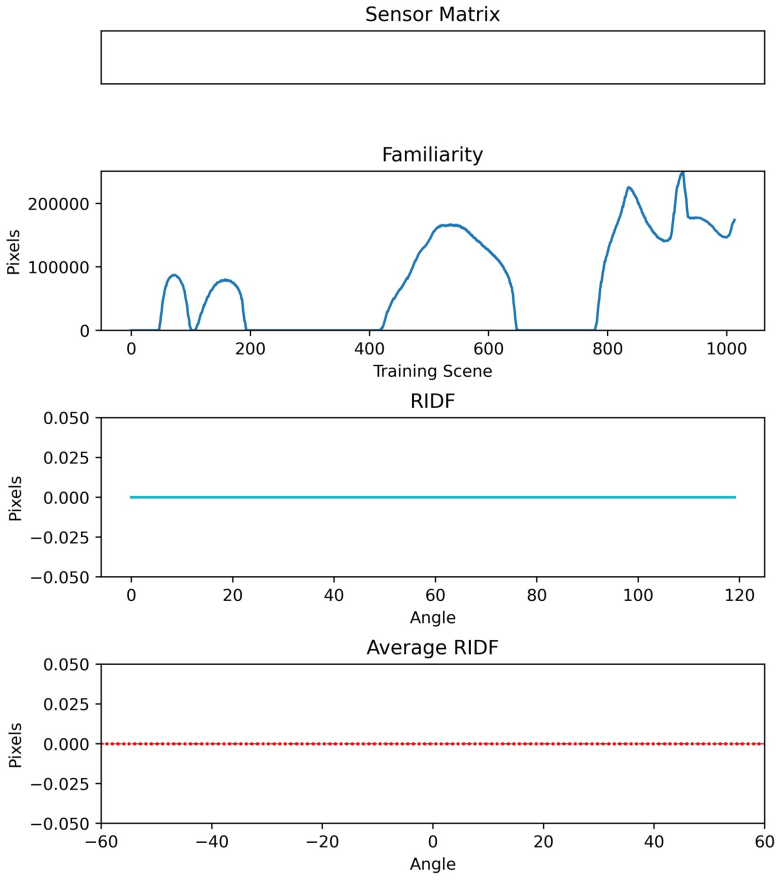

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 72003; p90: 120; p50: 120; complete: 0

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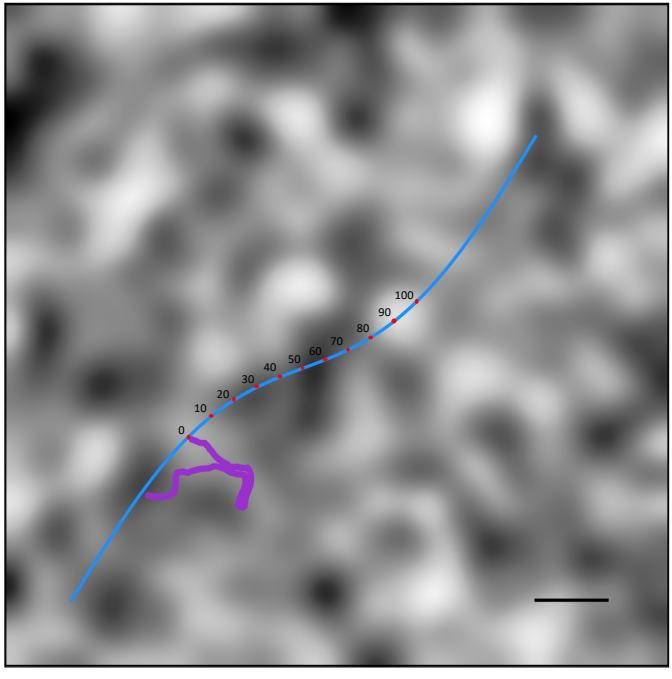

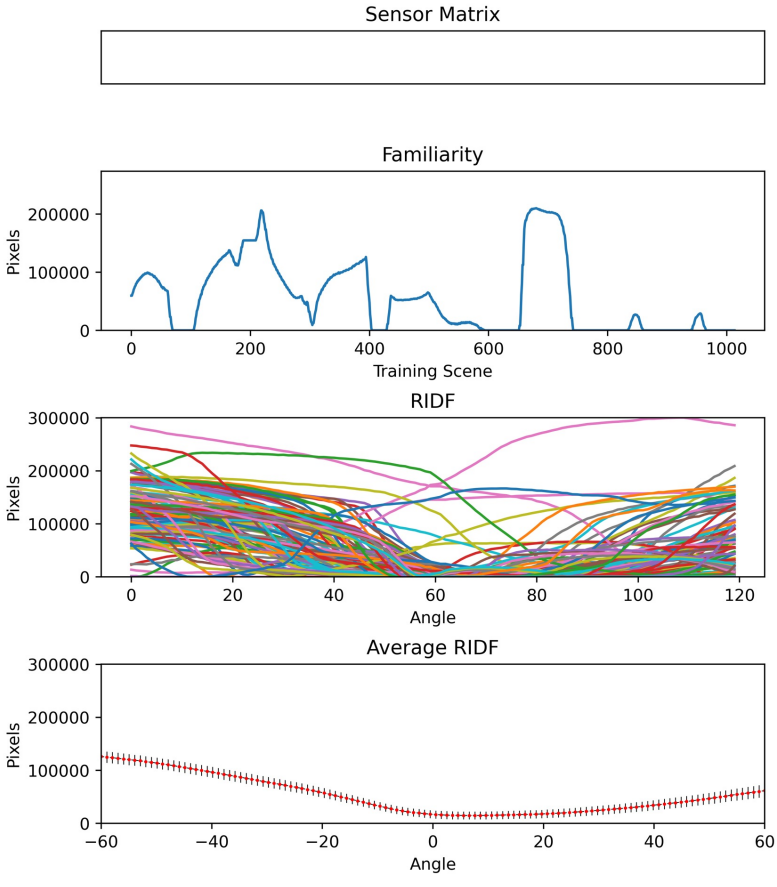

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

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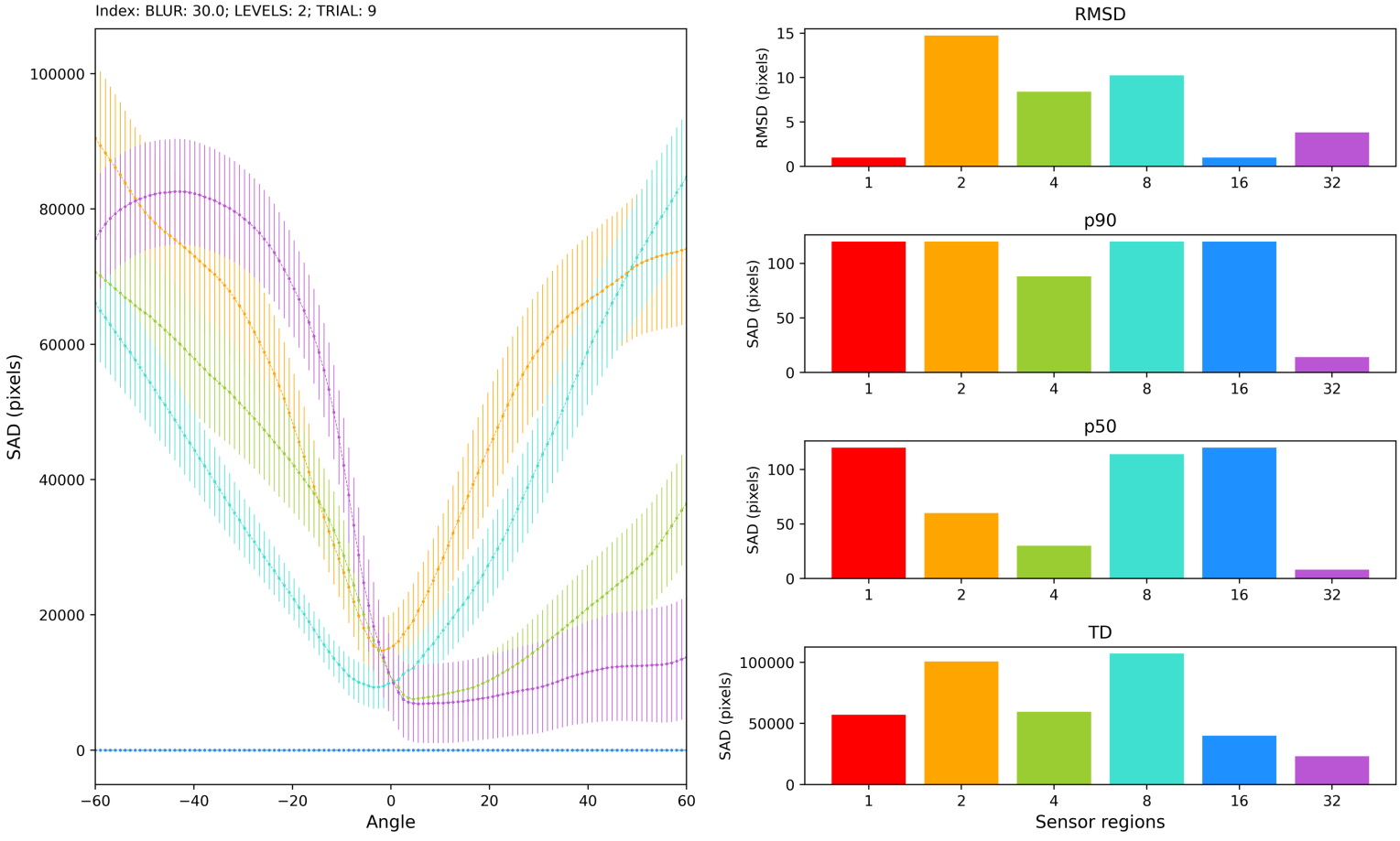
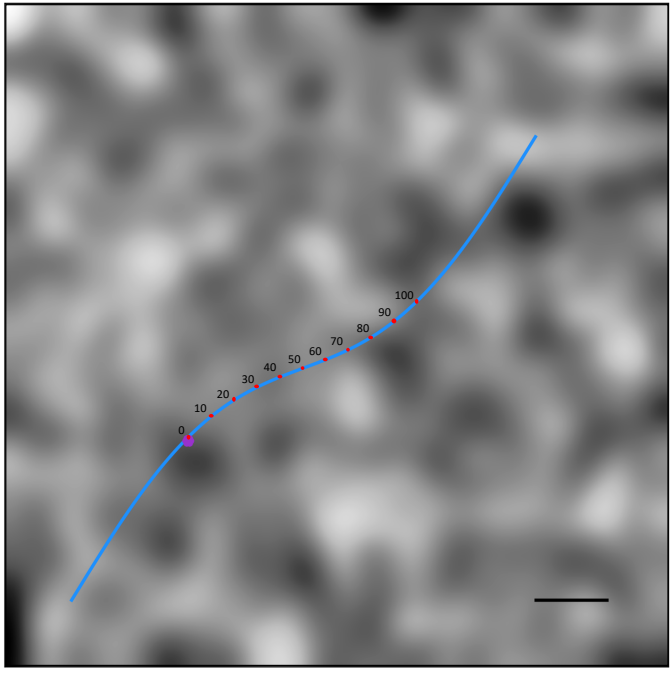
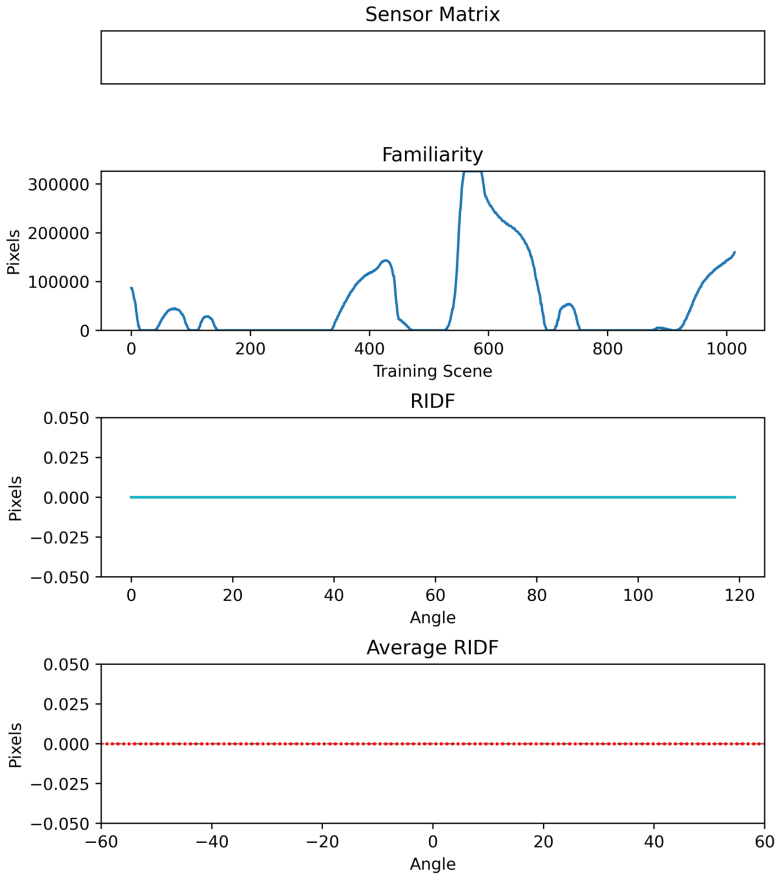

Index: BLUR: 30.0; LEVELS: 2; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
p50
TD
Sensor regions

0%

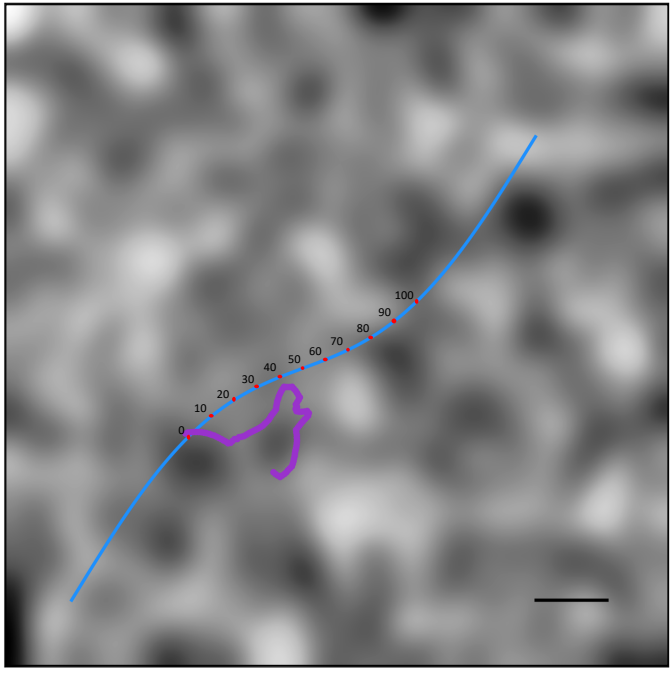


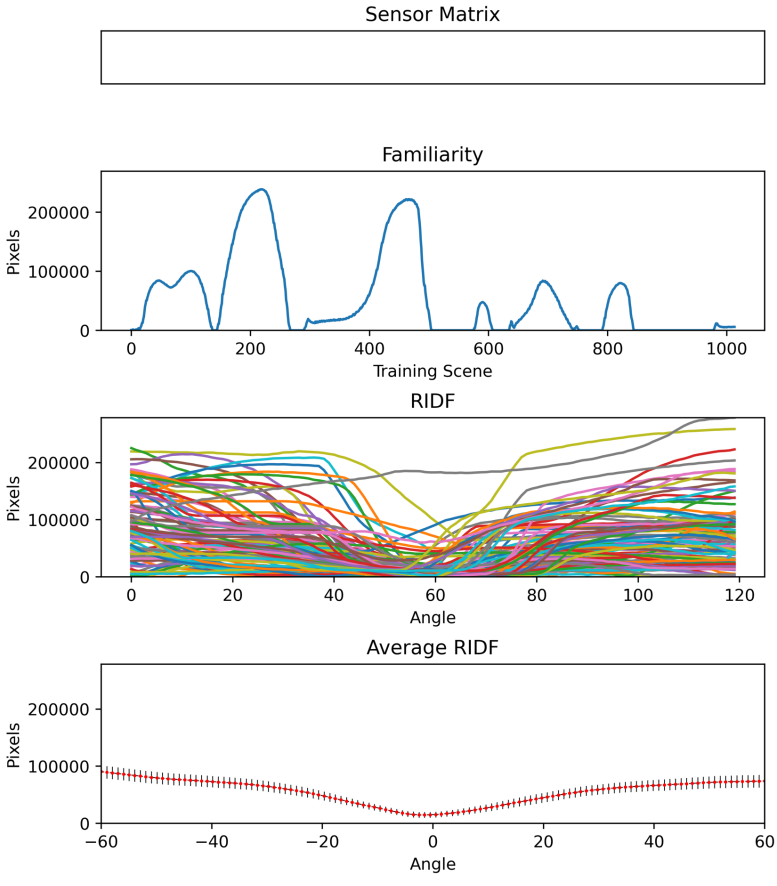


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 57139; p90: 120; p50: 120; complete: 0

0%

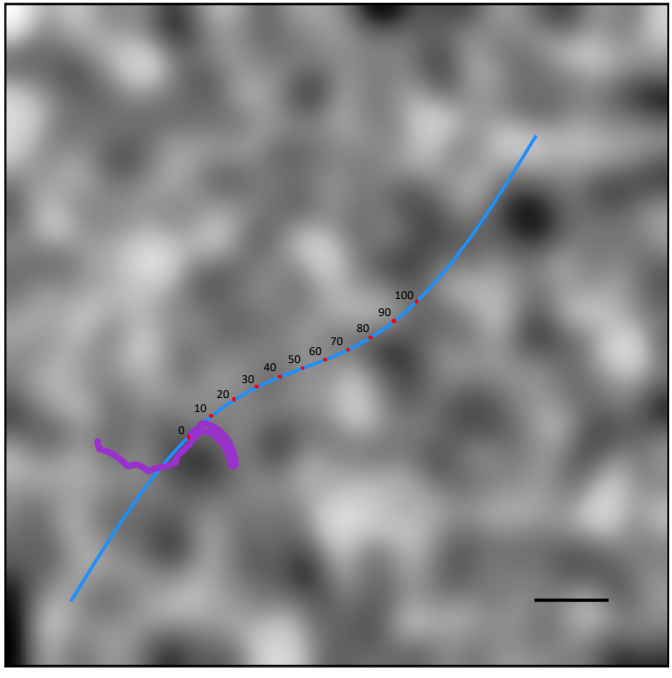


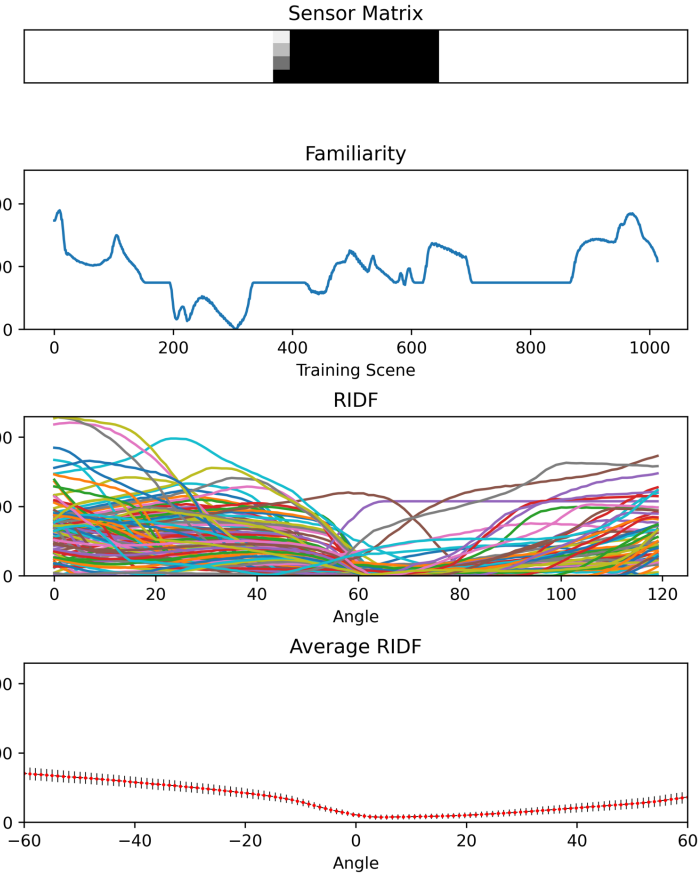


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 5895.55; RMSD/dist: 14.739; TD: 100590; p90: 120; p50: 60; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 3363.79; RMSD/dist: 8.409; TD: 59442; p90: 88; p50: 30; complete: 0

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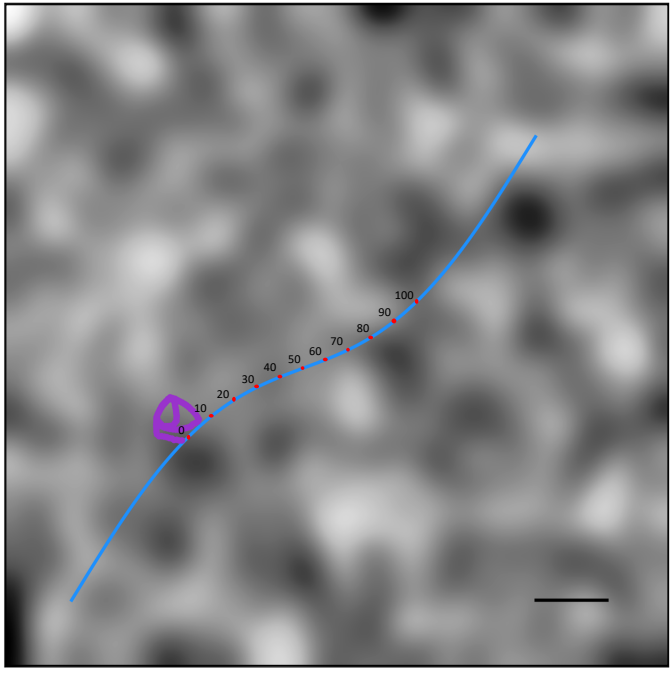

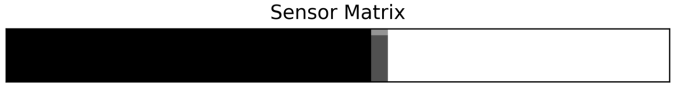

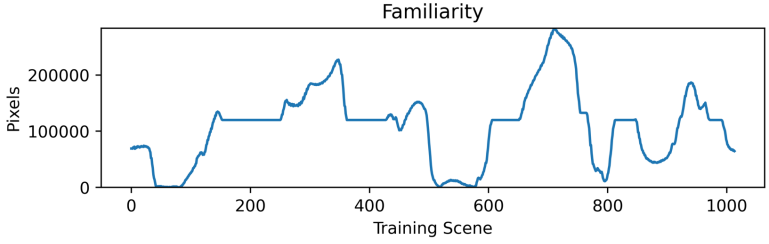

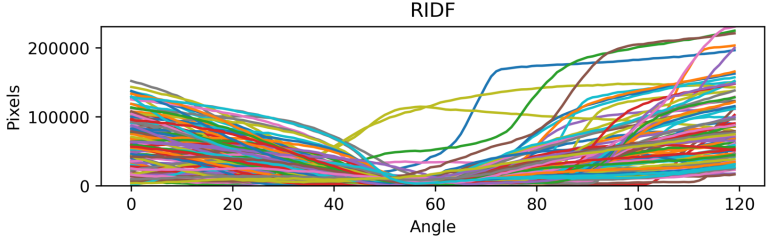

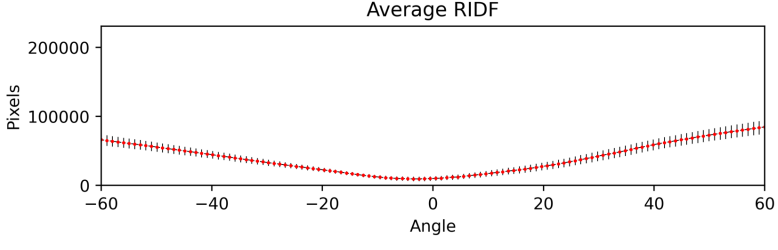

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 4099.02; RMSD/dist: 10.248; TD: 107110; p90: 120; p50: 114; complete: 0

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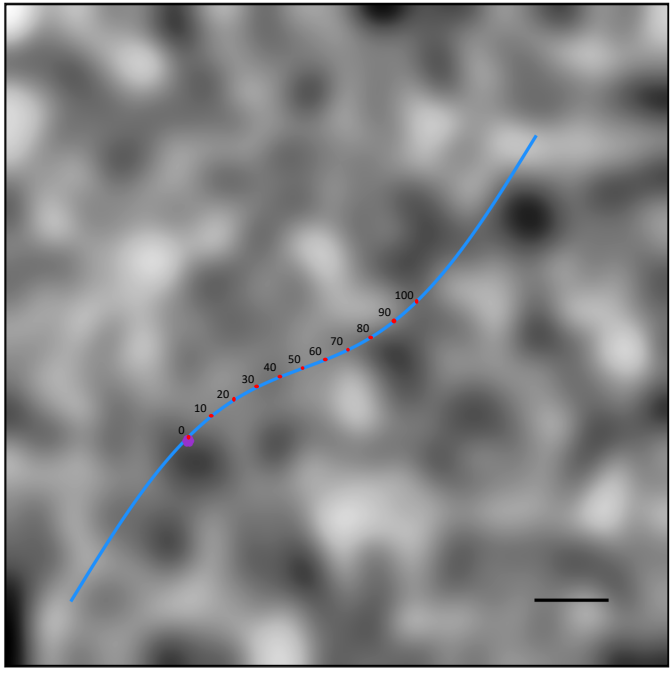

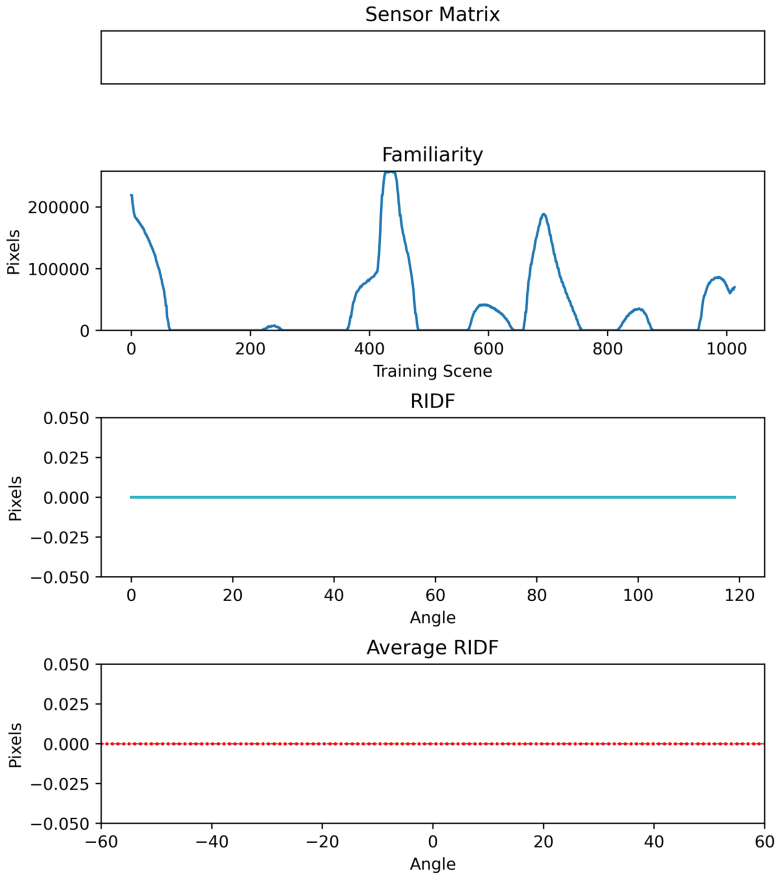

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 39848; p90: 120; p50: 120; complete: 0

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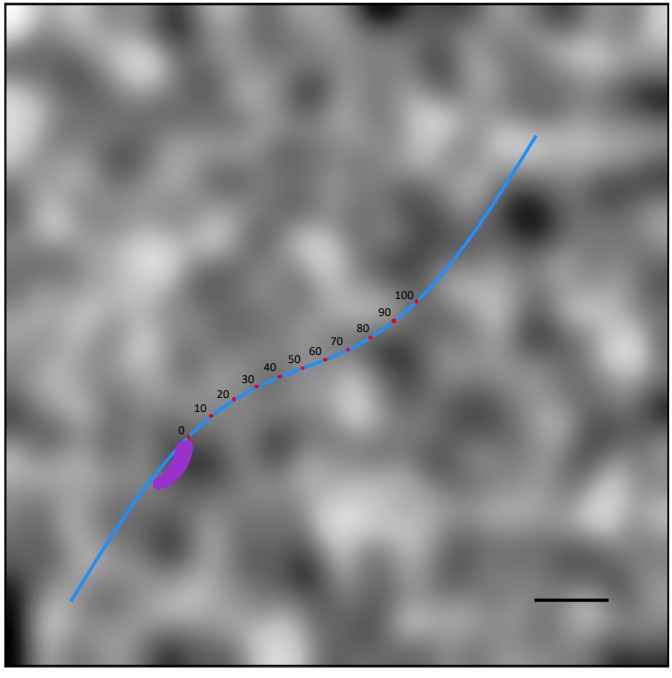
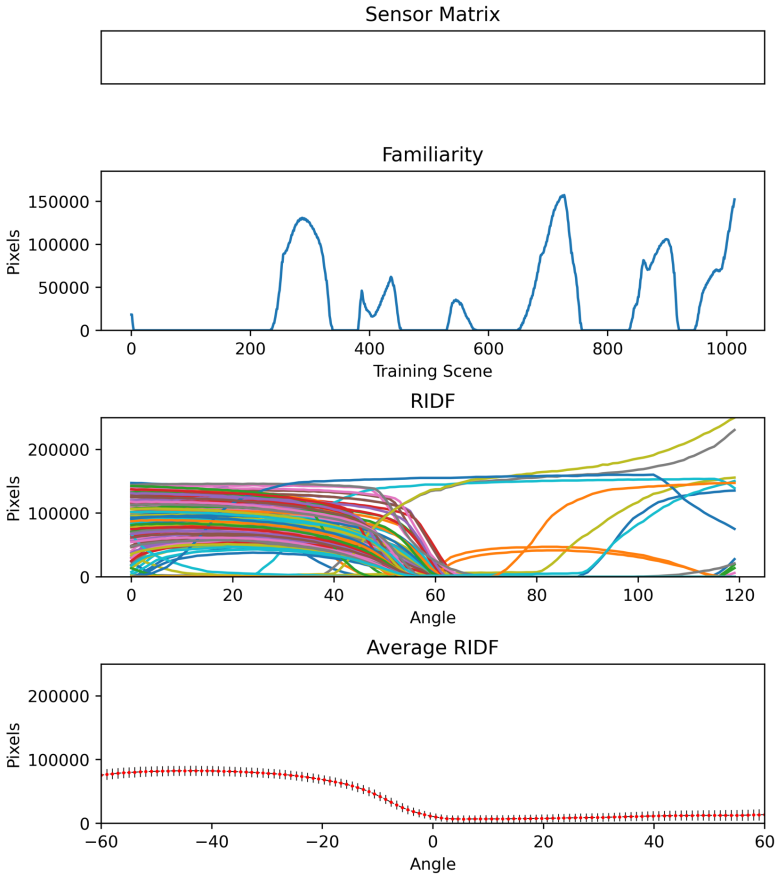
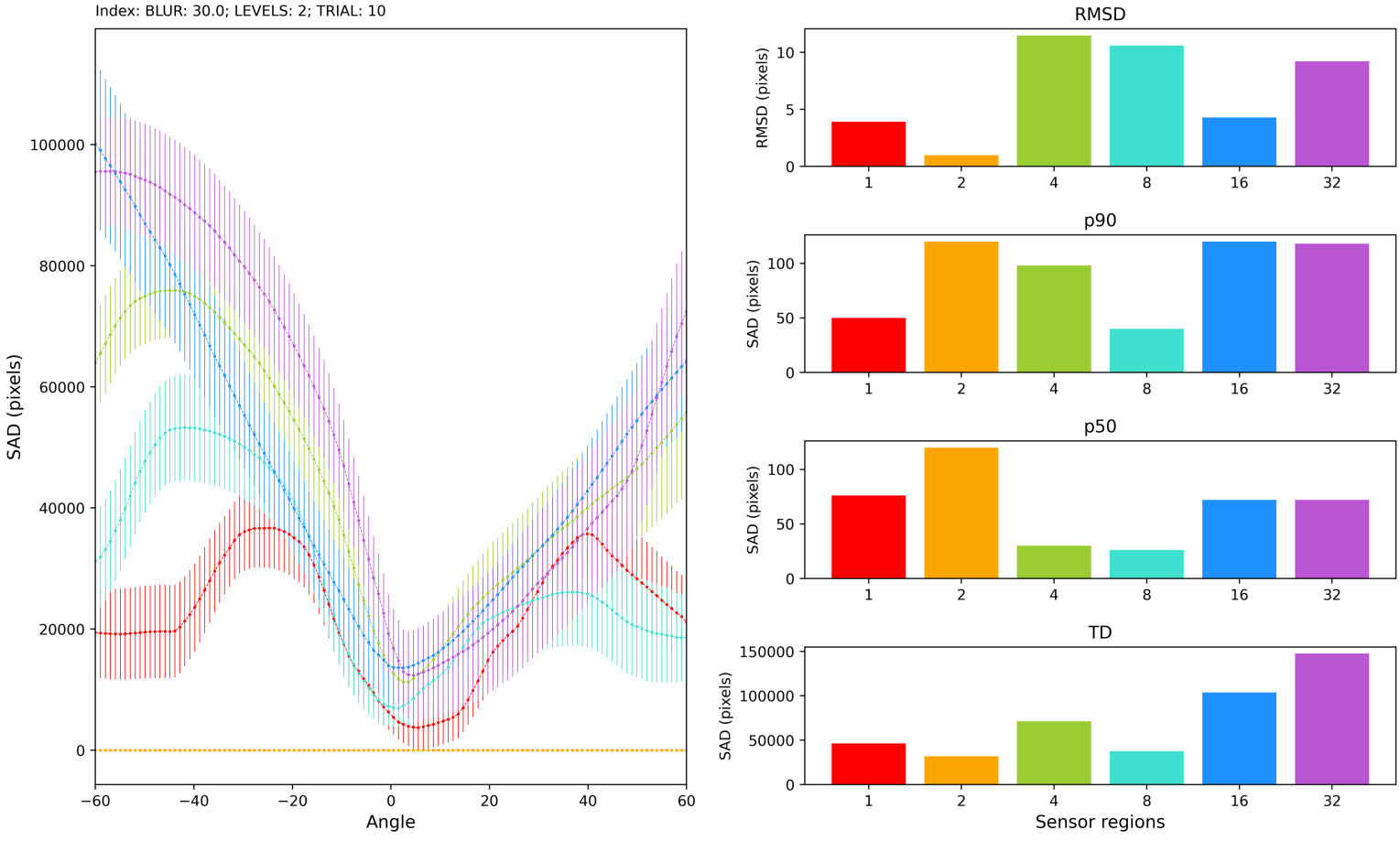




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1522.79; RMSD/dist: 3.807; TD: 23117; p90: 14; p50: 8; complete: 0


Index: BLUR: 30.0; LEVELS: 2; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

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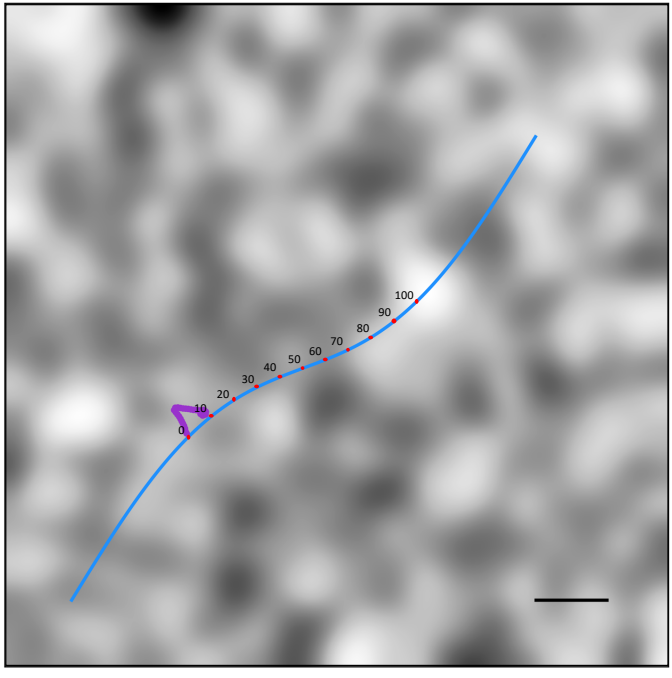

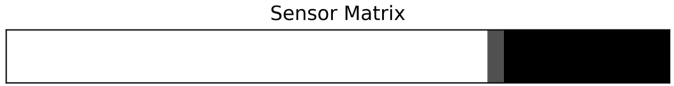

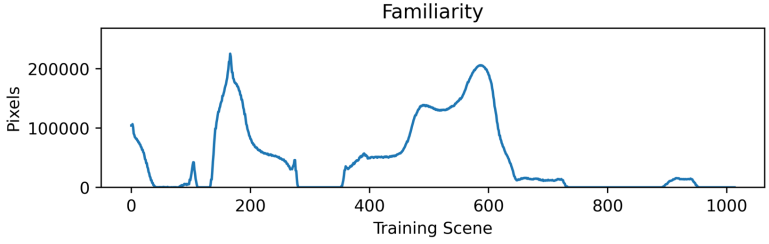

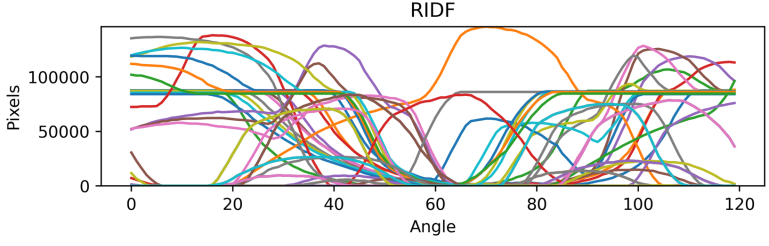

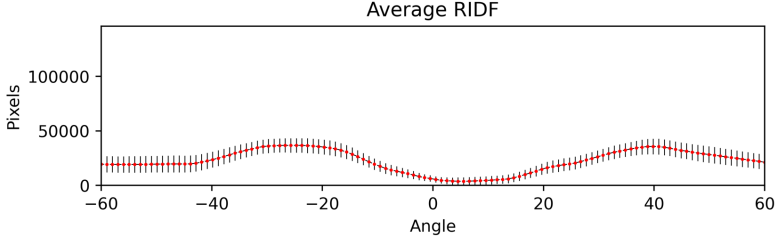

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1563.09; RMSD/dist: 3.908; TD: 46225; p90: 50; p50: 76; complete: 0

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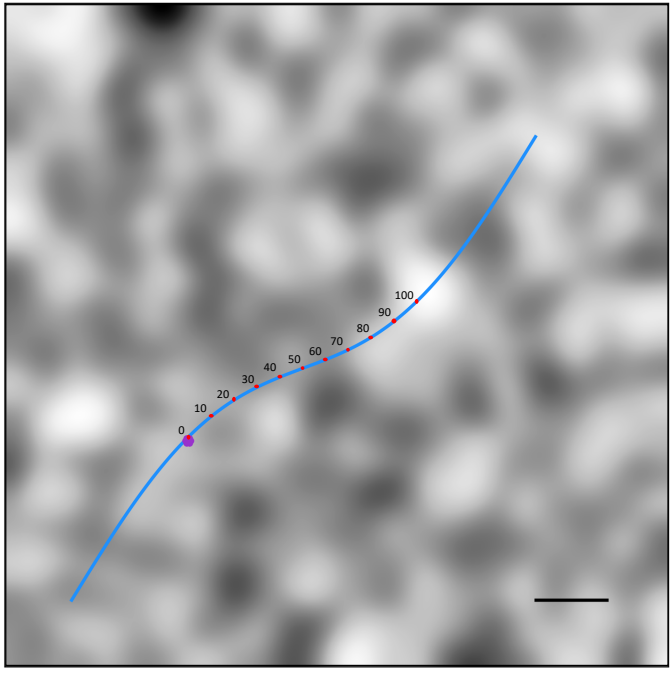
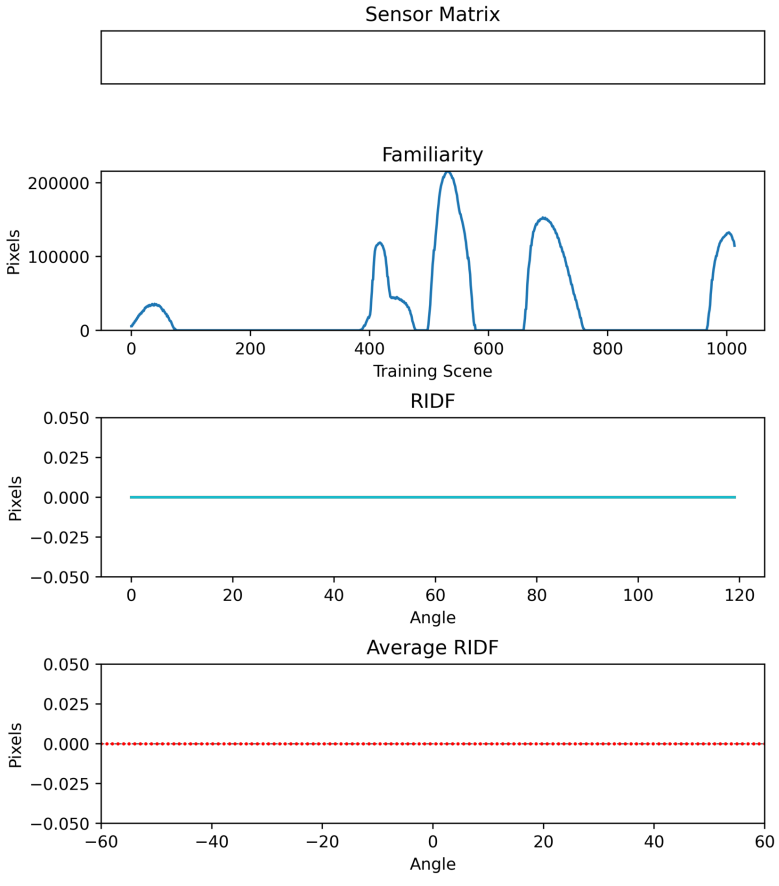
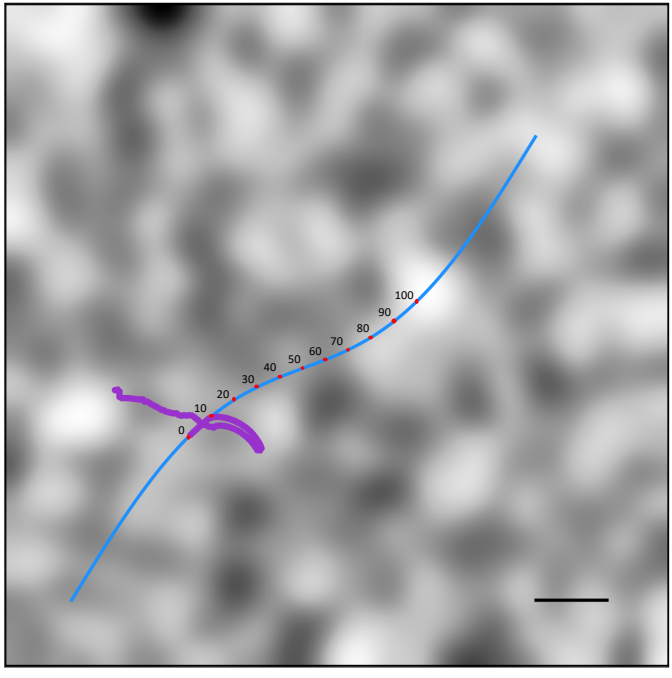


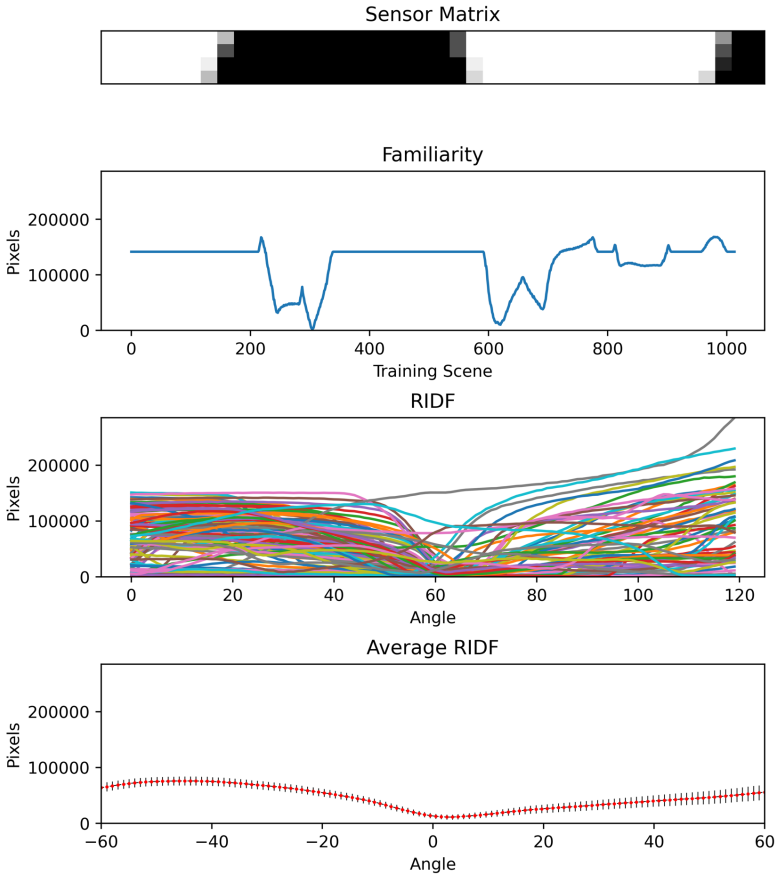


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 31829; p90: 120; p50: 120; complete: 0

10%





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Navigation stats: RMSD error: 4588.66; RMSD/dist: 11.472; TD: 71199; p90: 98; p50: 30; complete: 0

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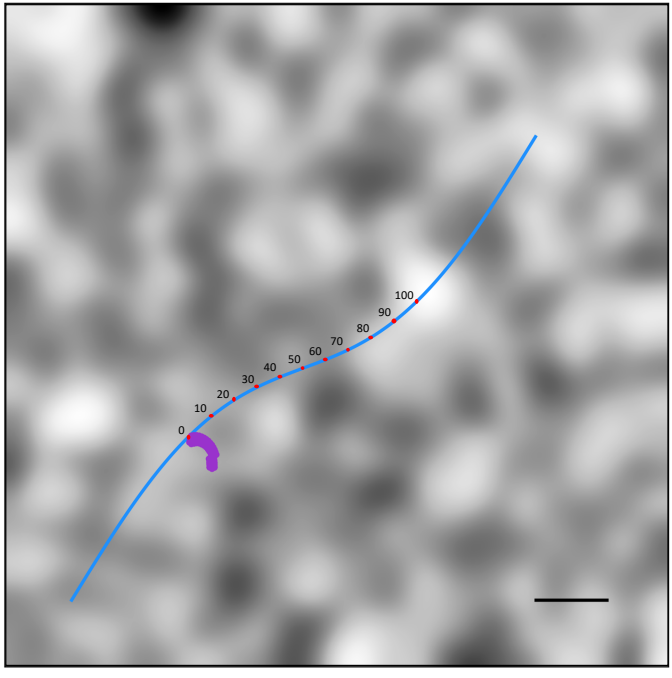

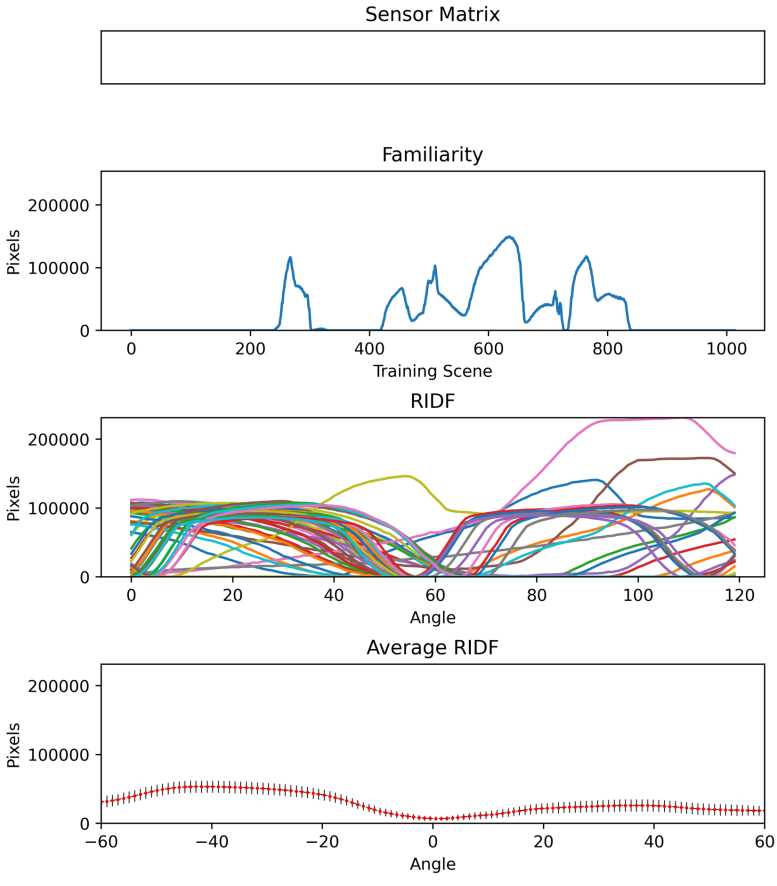

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4233.92; RMSD/dist: 10.585; TD: 37509; p90: 40; p50: 26; complete: 0

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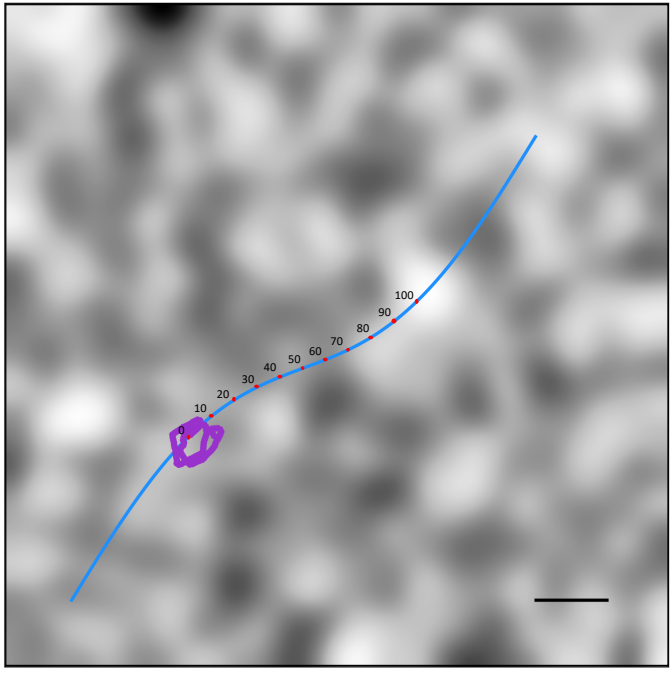

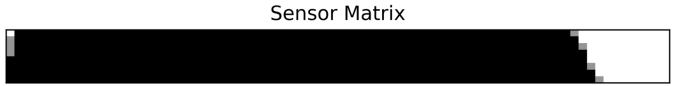

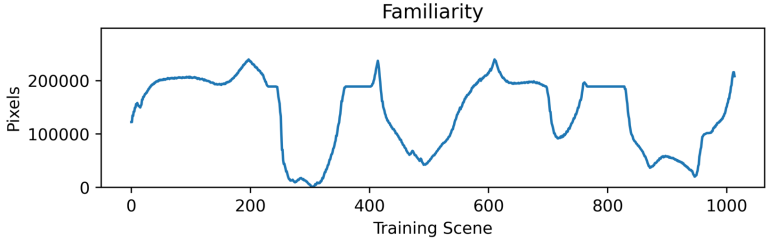

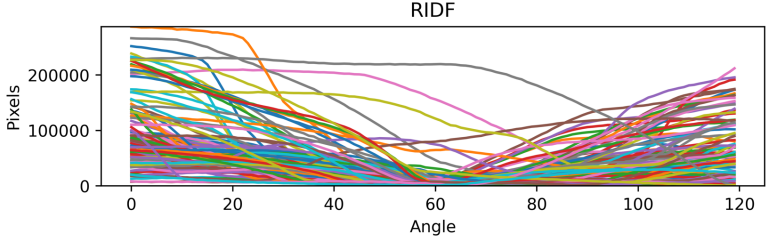

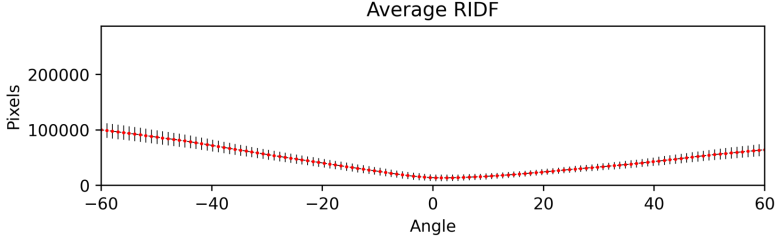

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1710.82; RMSD/dist: 4.277; TD: 103665; p90: 120; p50: 72; complete: 0

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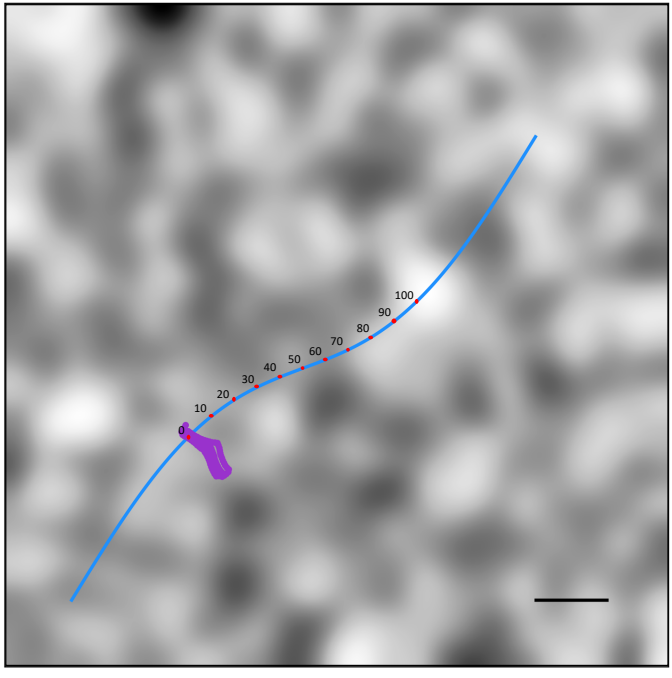

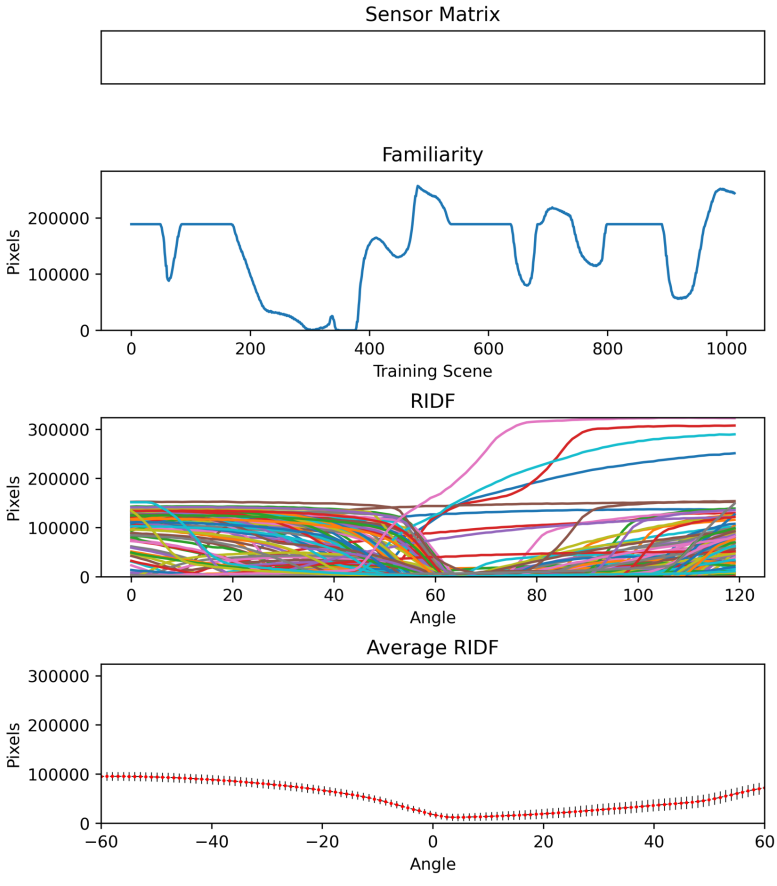

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 30; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 2; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 3677.71; RMSD/dist: 9.194; TD: 147491; p90: 118; p50: 72; complete: 0