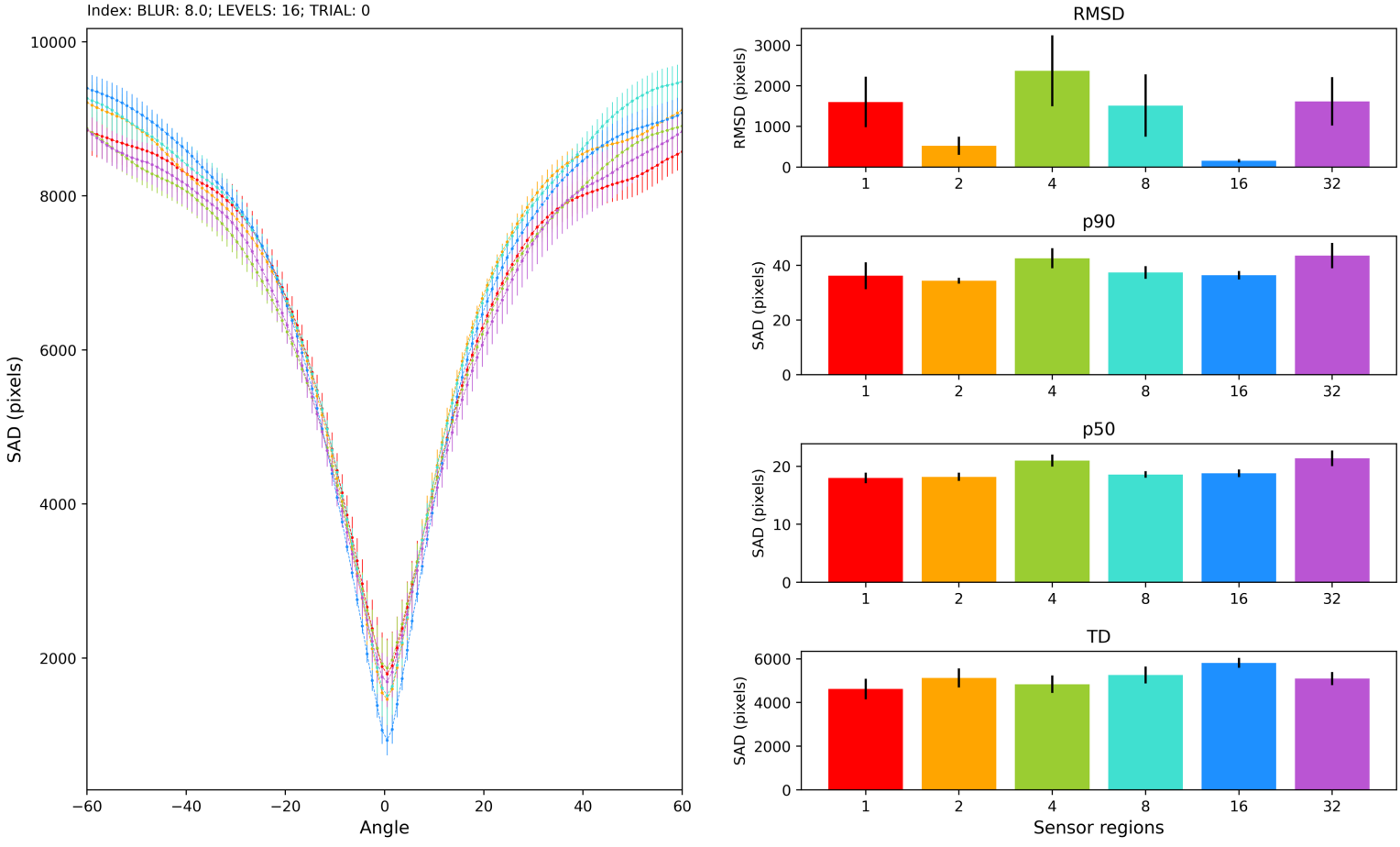
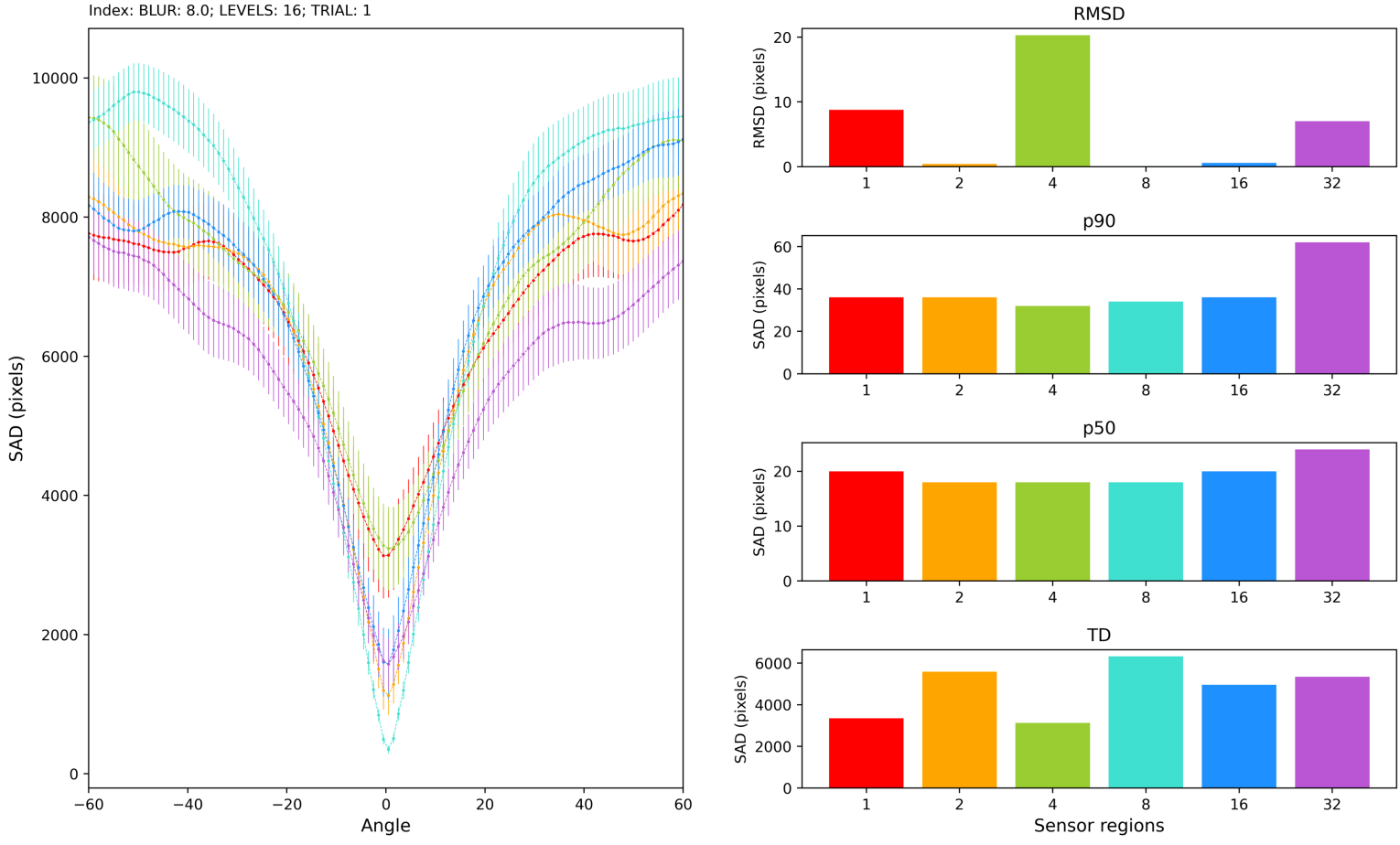
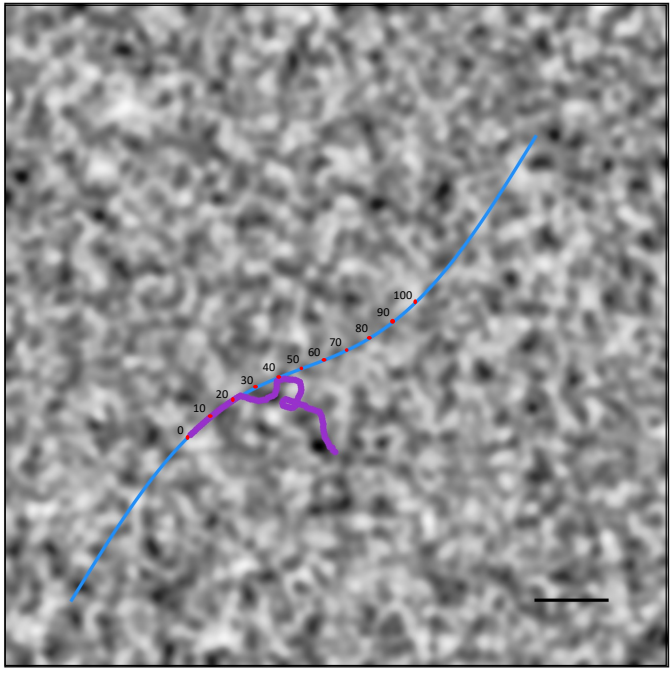
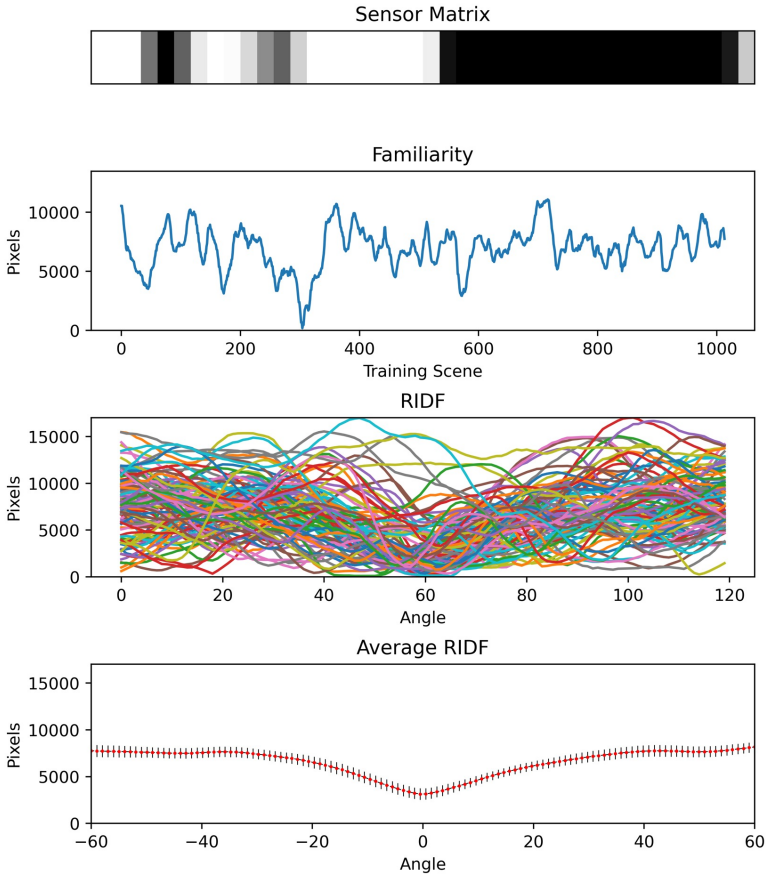

Index: BLUR: 8.0; LEVELS: 16; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 8.0; LEVELS: 16; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

20%

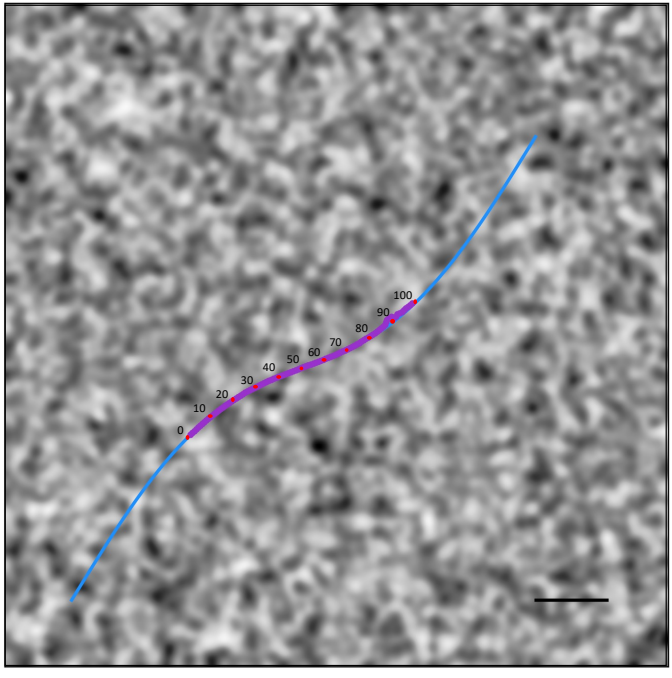


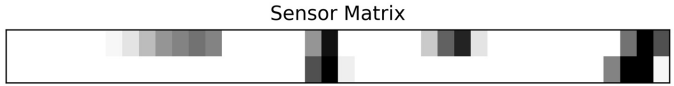


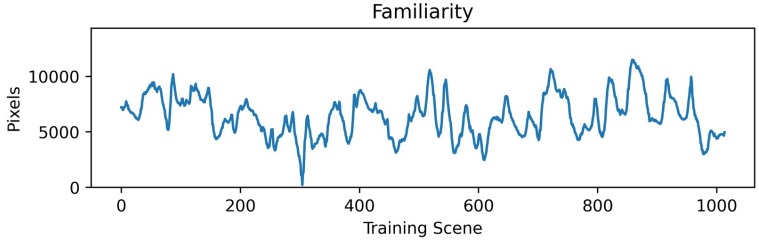
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

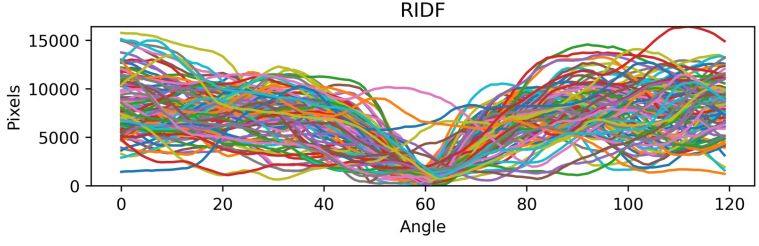
Navigation stats: RMSD error: 3513.15; RMSD/dist: 8.783; TD: 3351; p90: 36; p50: 20; complete: 0

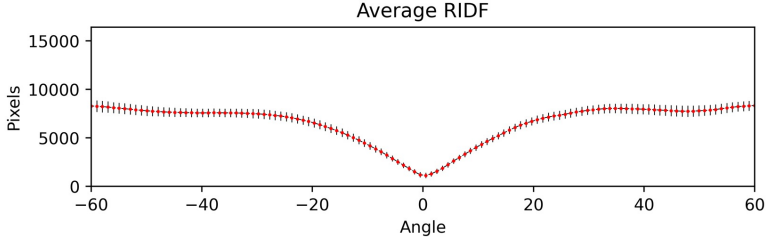
90%







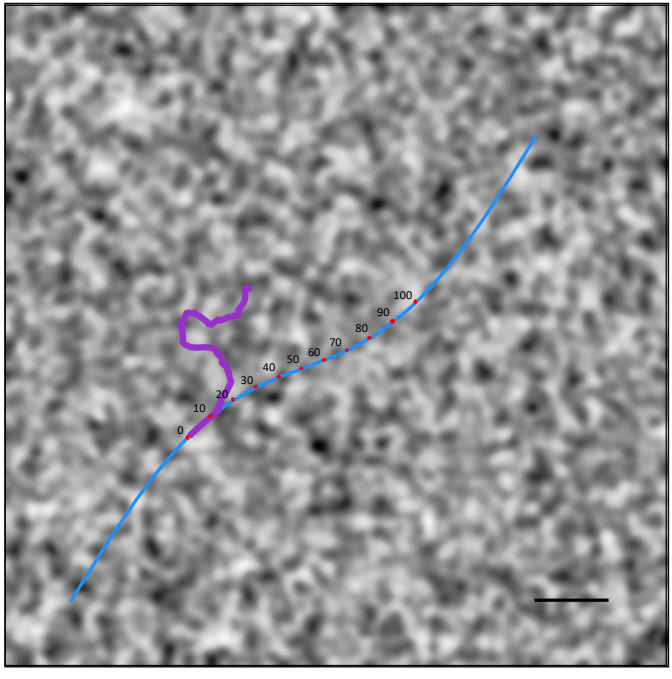


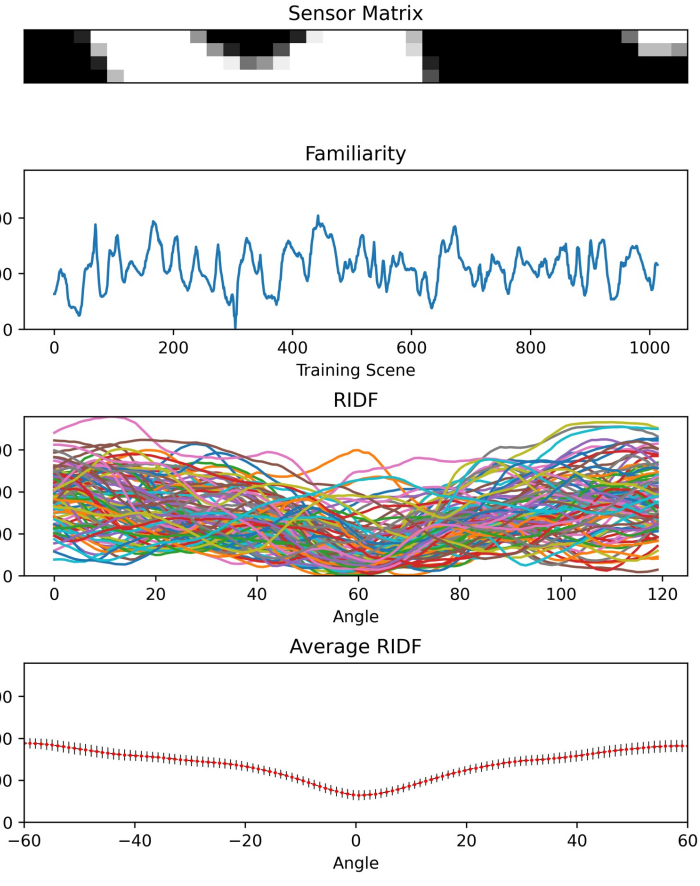


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 164.69; RMSD/dist: 0.412; TD: 5584; p90: 36; p50: 18; complete: 0

10%

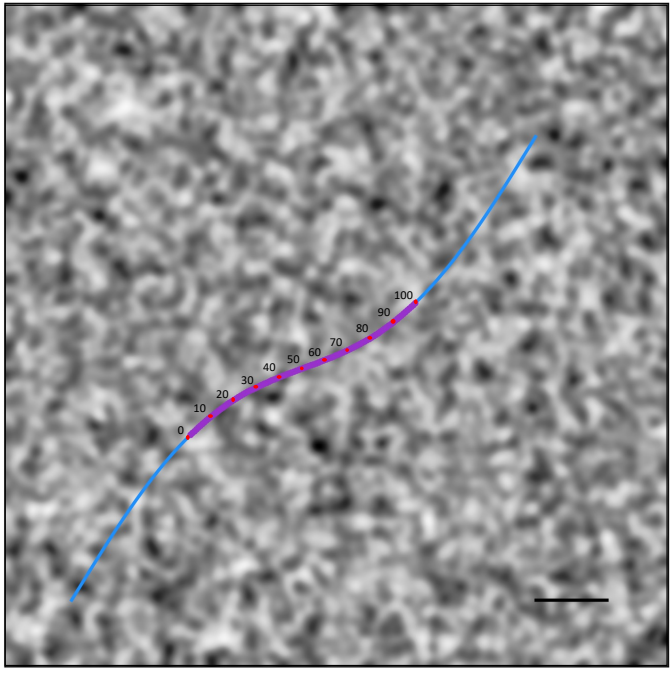


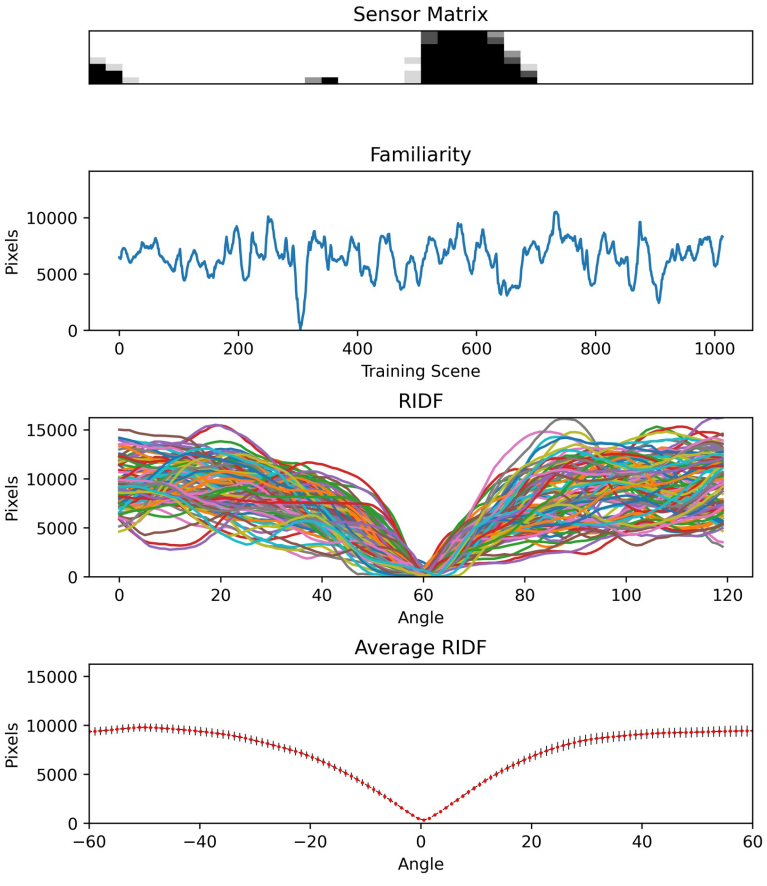


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 8121.25; RMSD/dist: 20.303; TD: 3126; p90: 32; p50: 18; complete: 0

100%

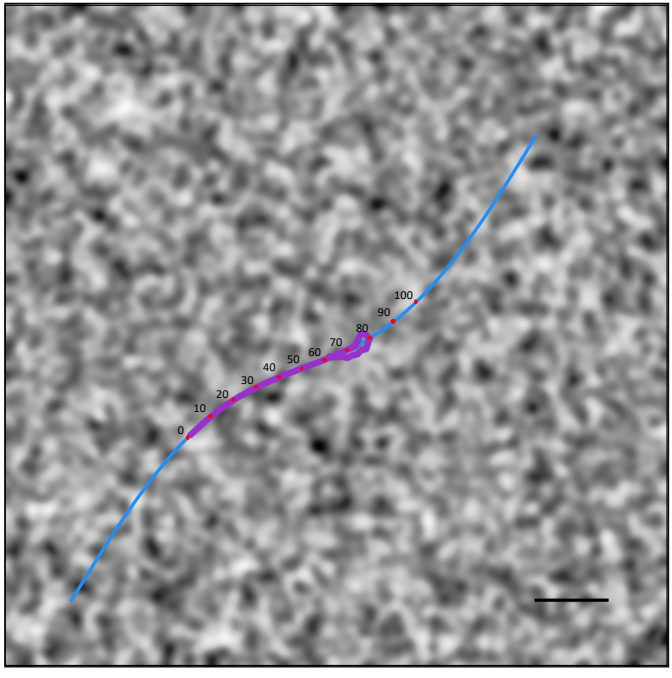


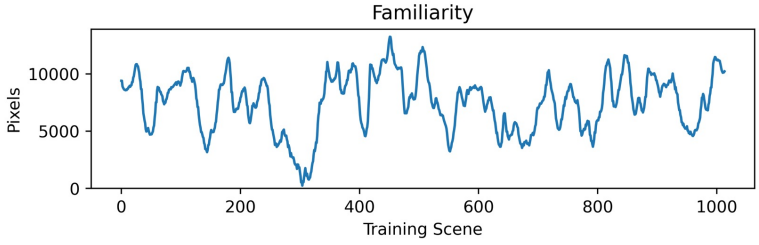


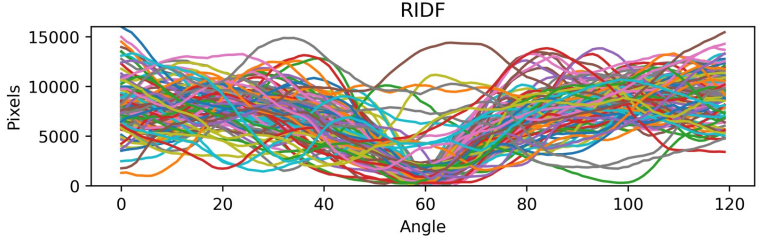
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

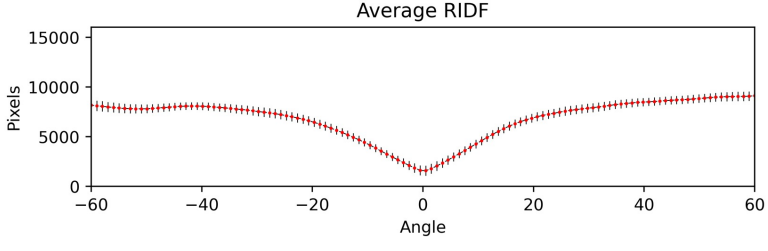
Navigation stats: RMSD error: 34.62; RMSD/dist: 0.087; TD: 6320; p90: 34; p50: 18; complete: 0

70%





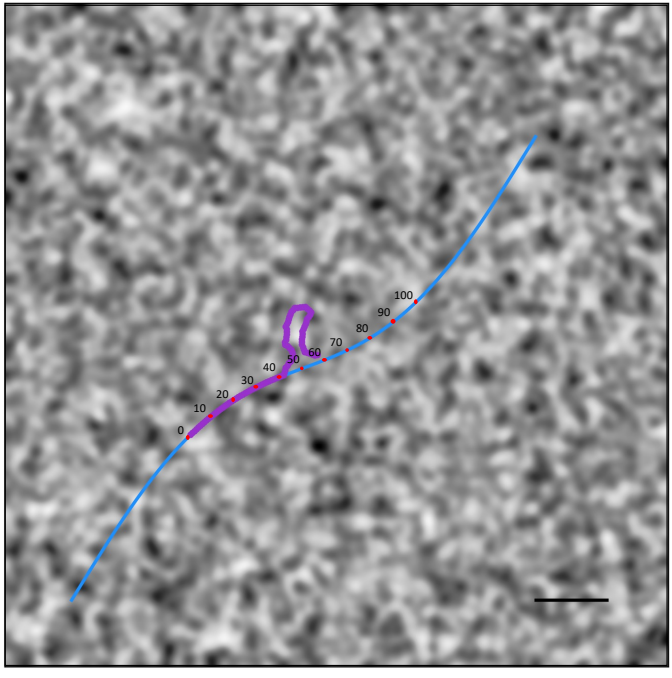


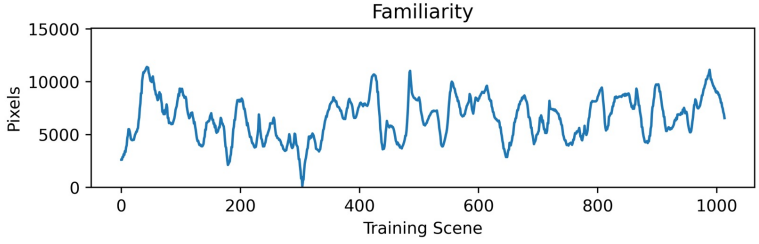


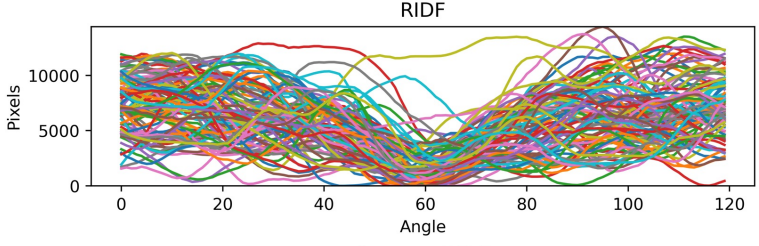
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

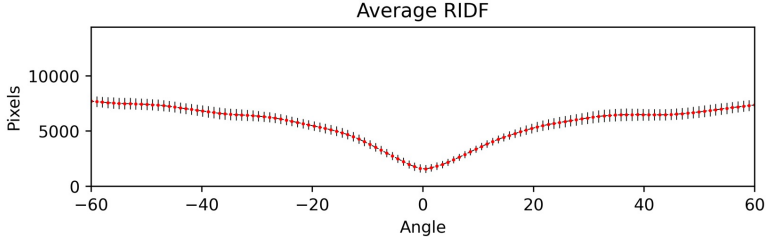
Navigation stats: RMSD error: 230.64; RMSD/dist: 0.577; TD: 4958; p90: 36; p50: 20; complete: 0

40%



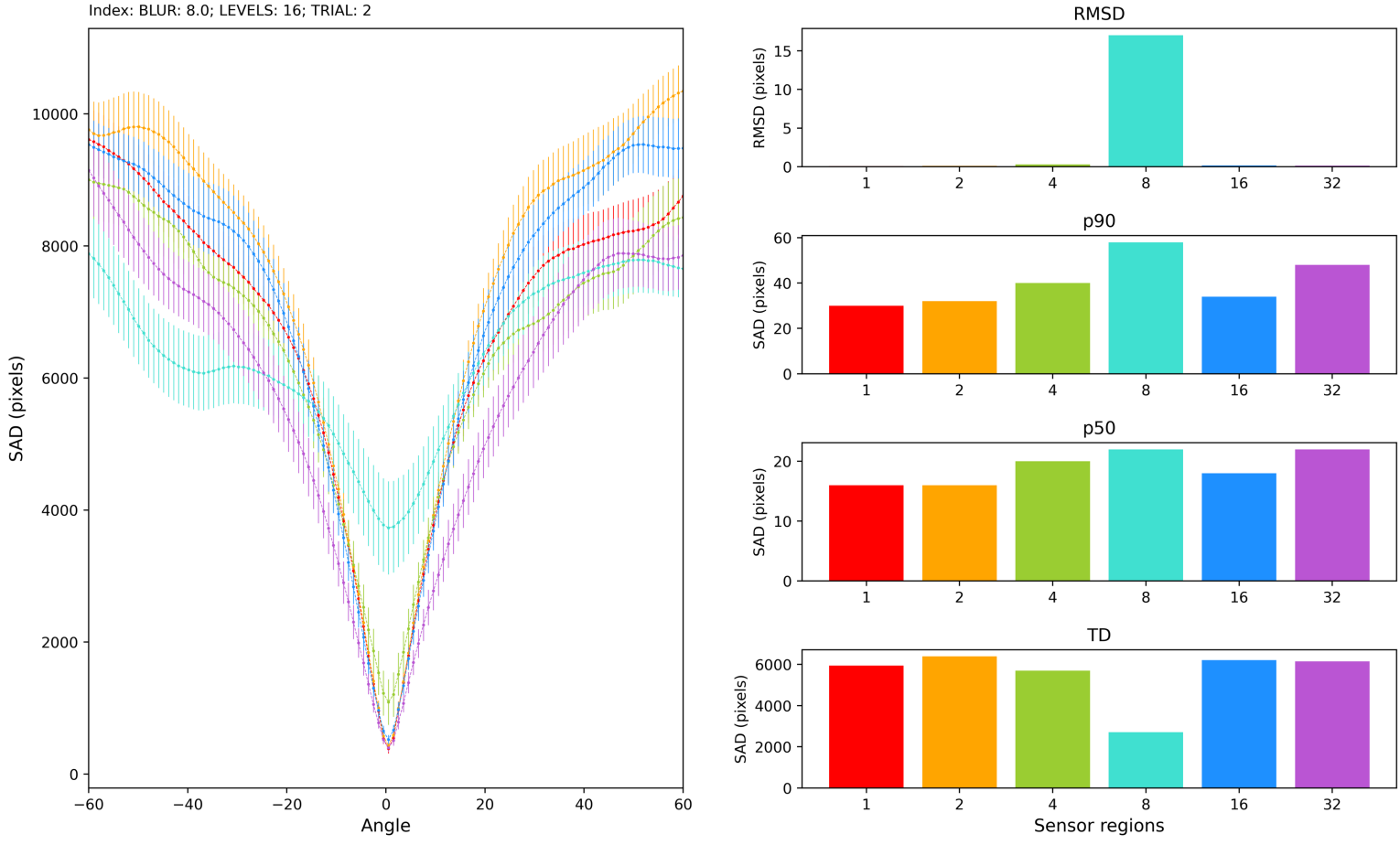




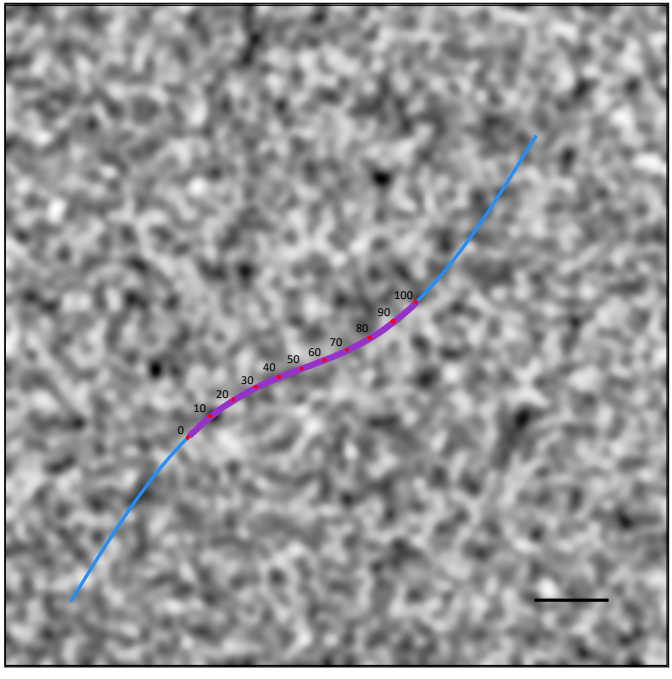


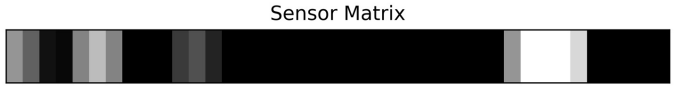
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

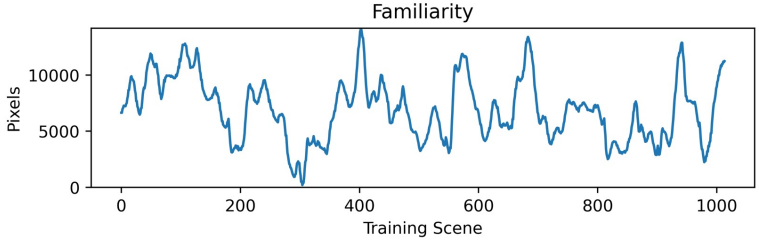
Navigation stats: RMSD error: 2805.42; RMSD/dist: 7.014; TD: 5342; p90: 62; p50: 24; complete: 0

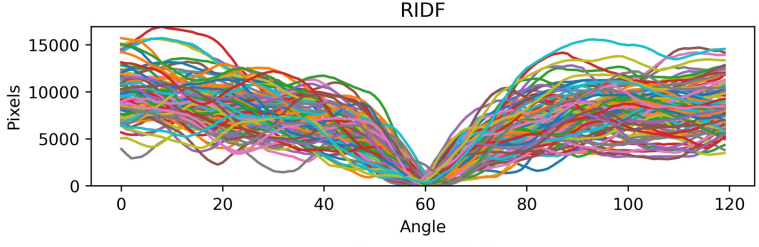

Index: BLUR: 8.0; LEVELS: 16; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

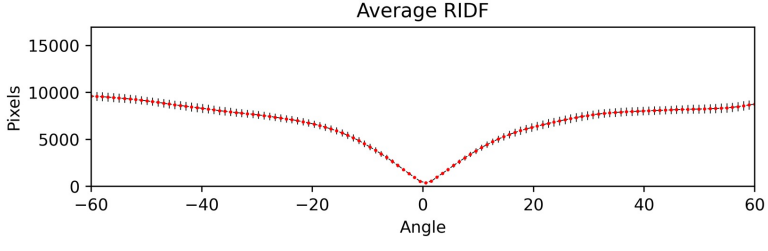
100%







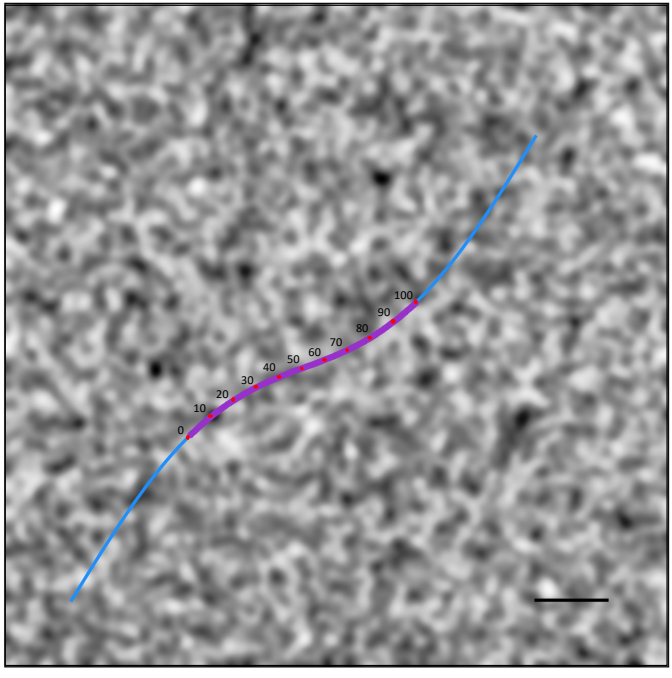


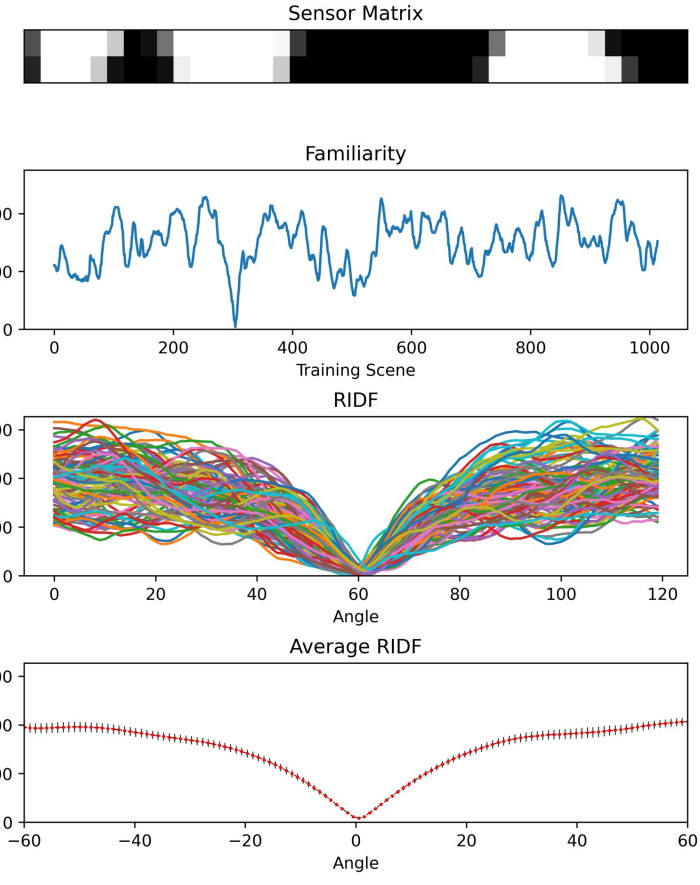


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 32.40; RMSD/dist: 0.081; TD: 5942; p90: 30; p50: 16; complete: 0

100%

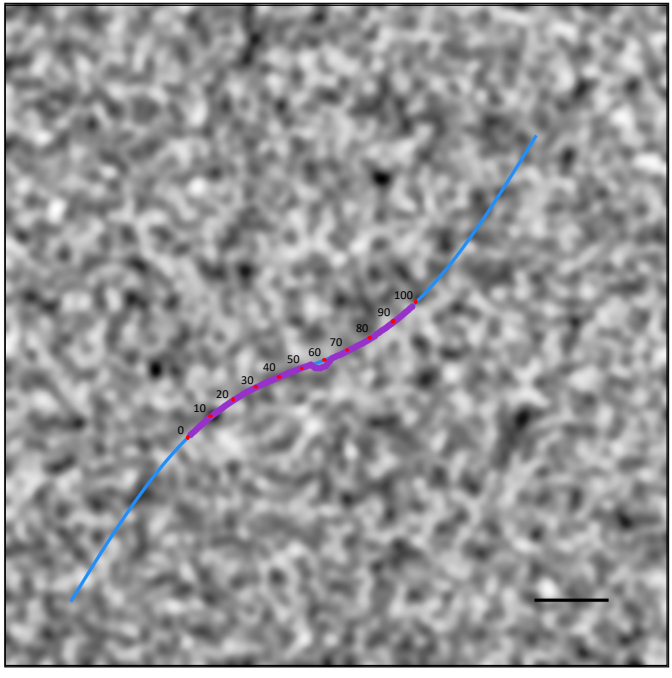


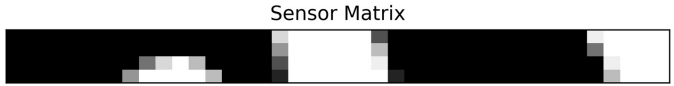


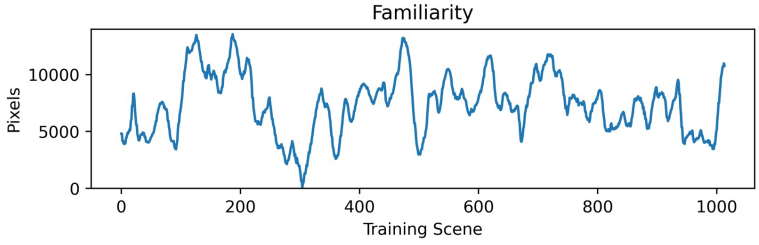
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

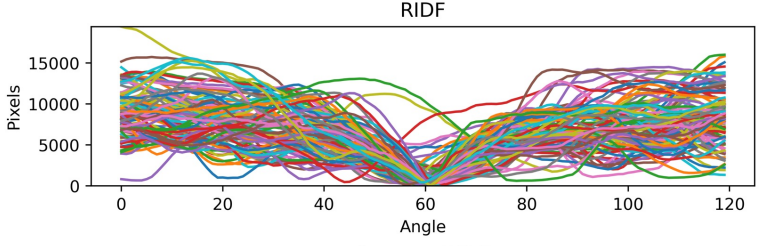
Navigation stats: RMSD error: 34.65; RMSD/dist: 0.087; TD: 6387; p90: 32; p50: 16; complete: 0

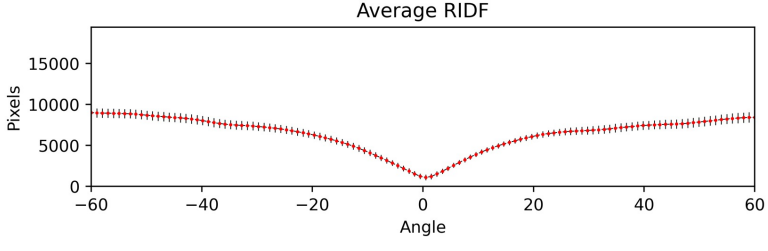
90%







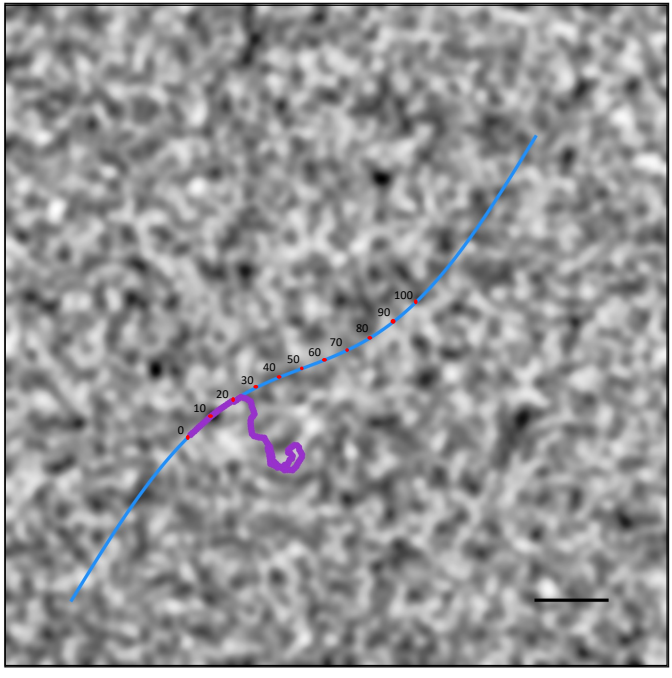


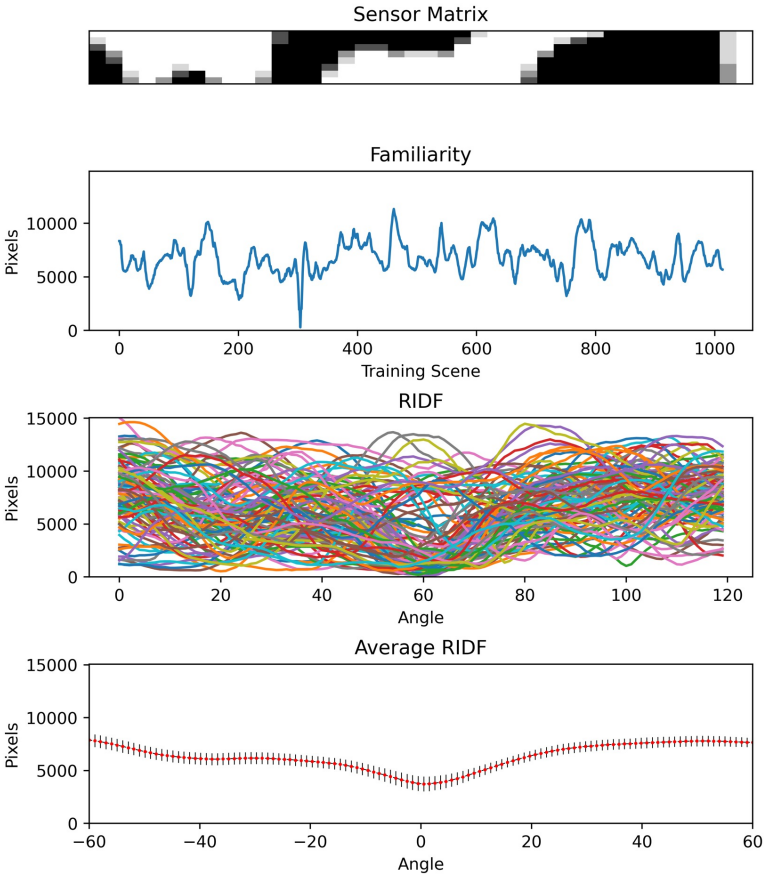


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 119.23; RMSD/dist: 0.298; TD: 5695; p90: 40; p50: 20; complete: 0

20%

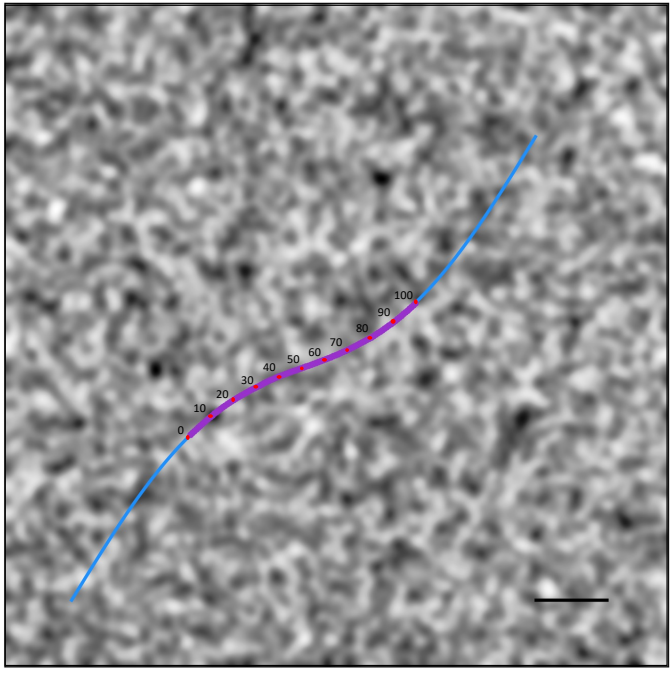


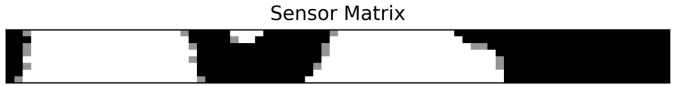


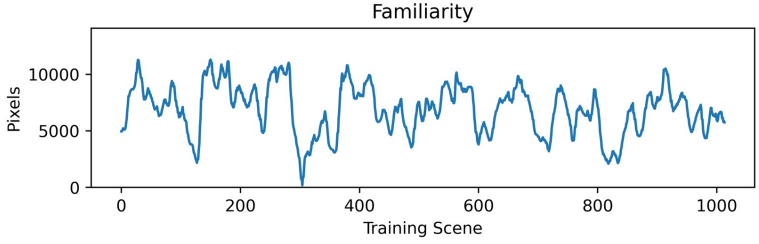
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

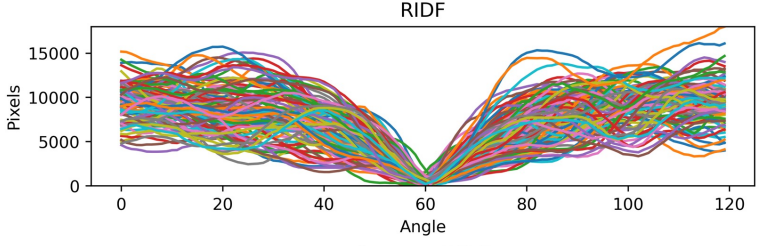
Navigation stats: RMSD error: 6816.09; RMSD/dist: 17.040; TD: 2703; p90: 58; p50: 22; complete: 0

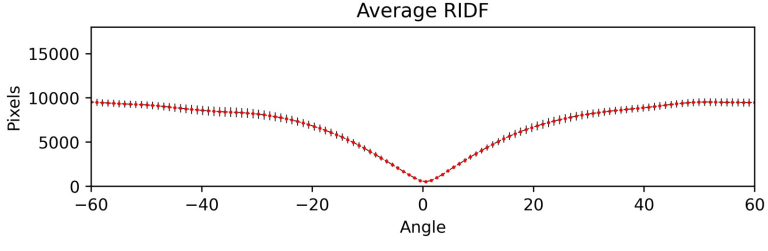
100%







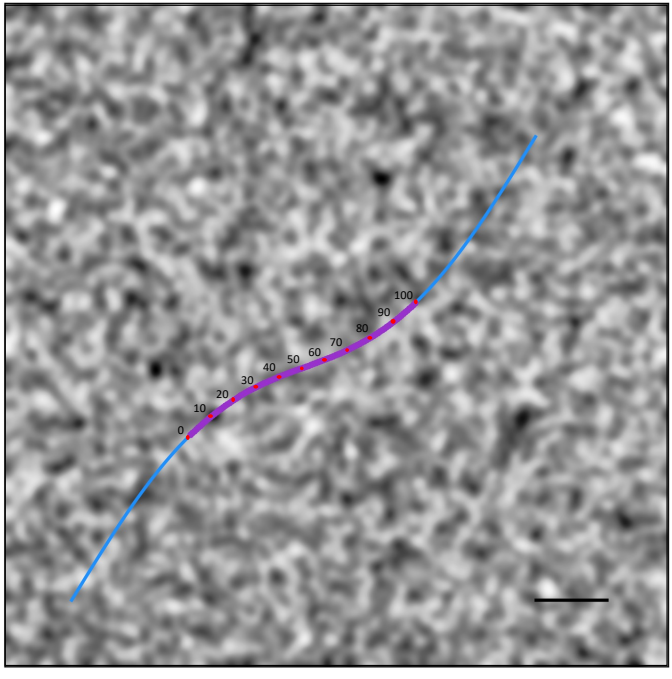


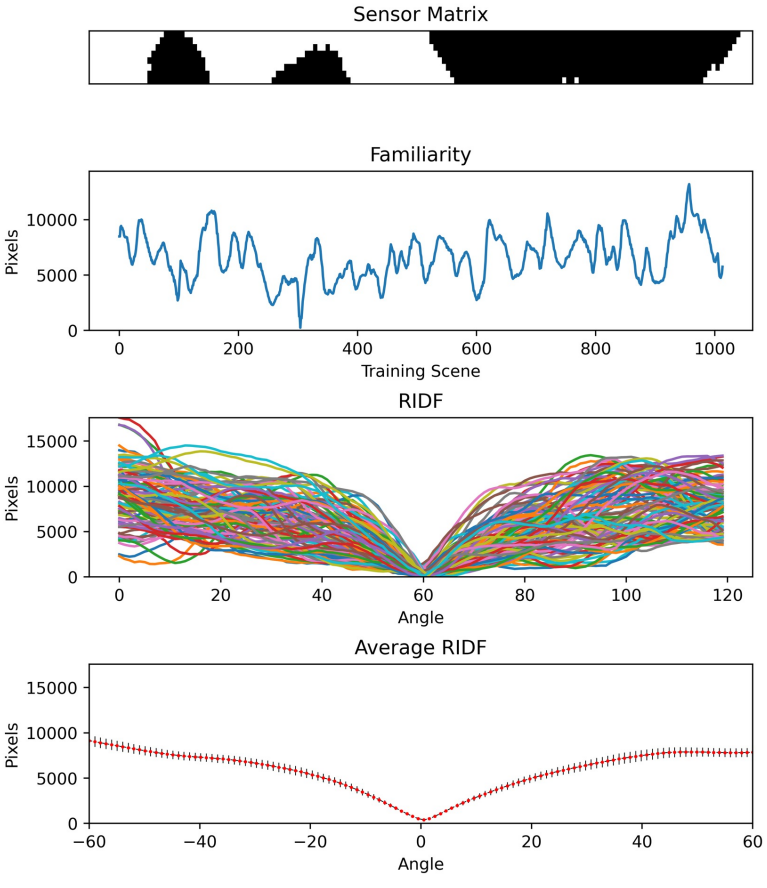


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 65.73; RMSD/dist: 0.164; TD: 6208; p90: 34; p50: 18; complete: 0

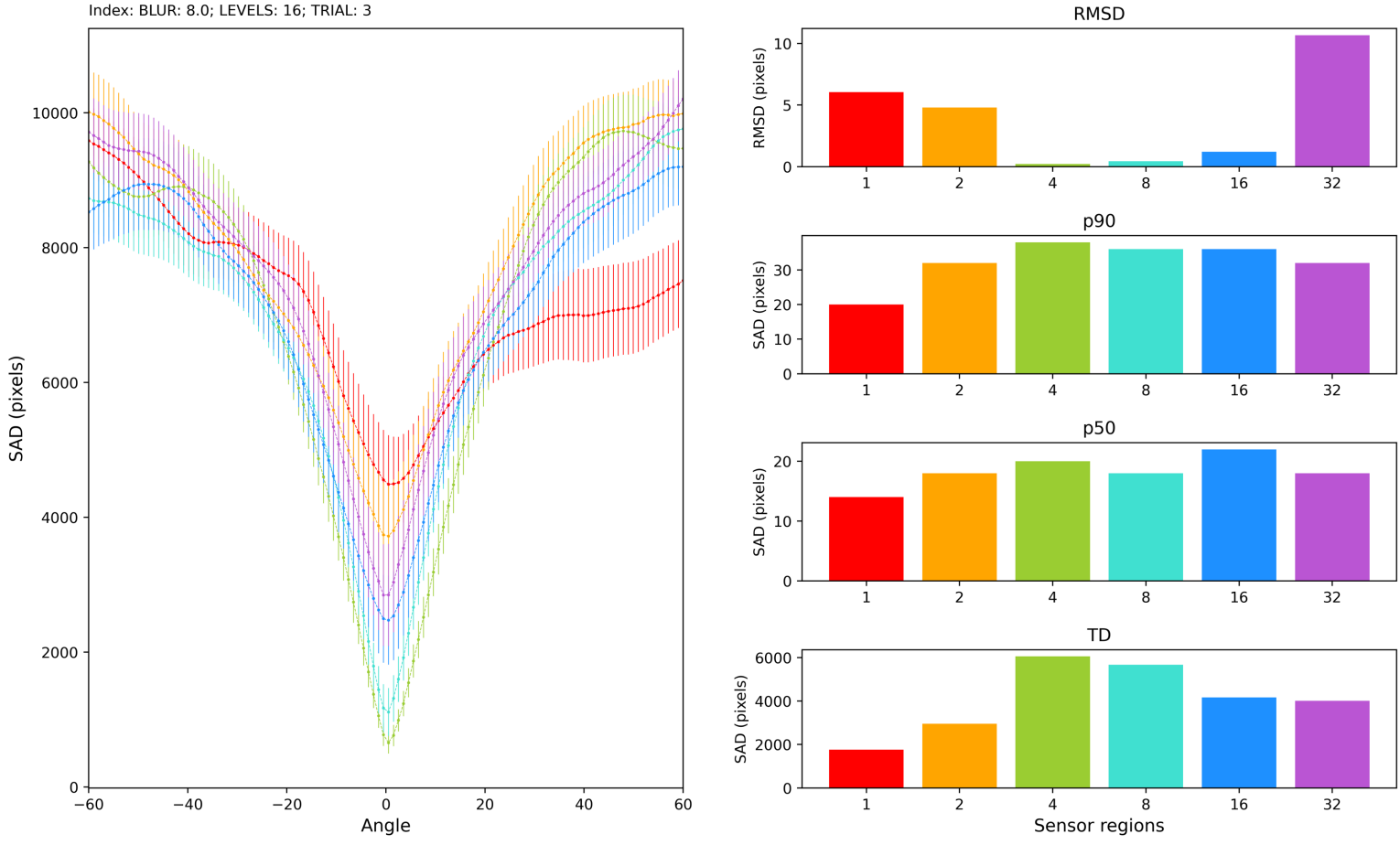
100%



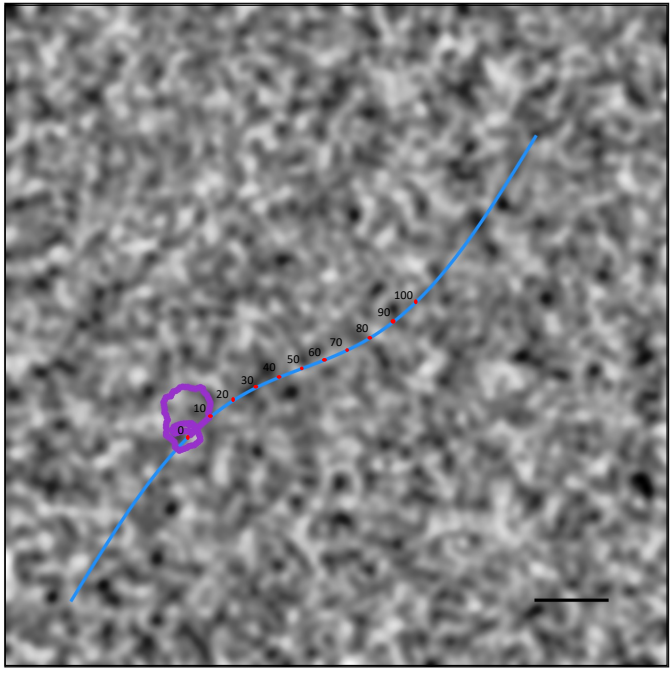


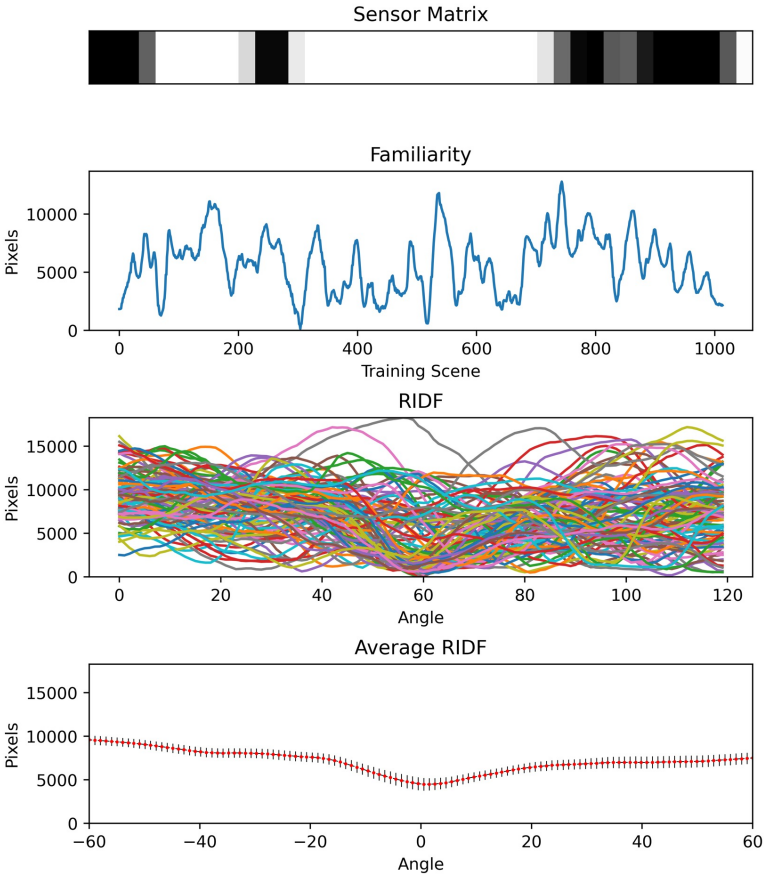
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 55.05; RMSD/dist: 0.138; TD: 6150; p90: 48; p50: 22; complete: 0


Index: BLUR: 8.0; LEVELS: 16; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%

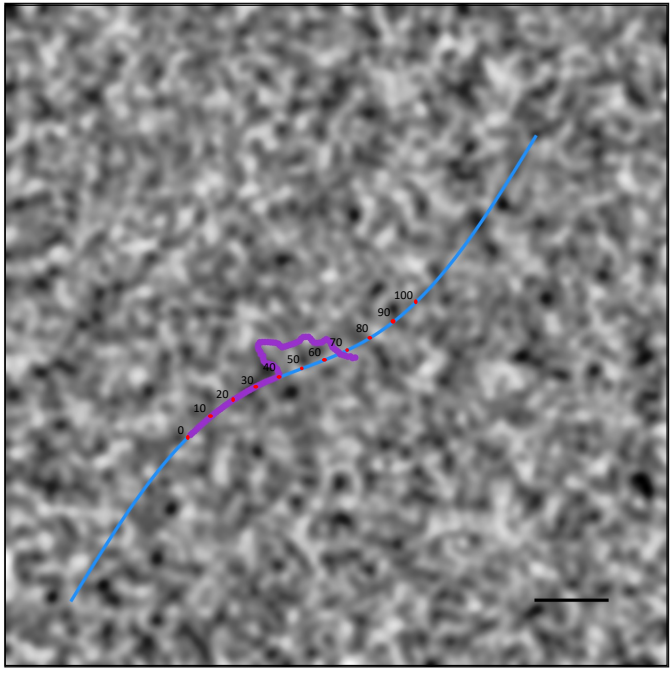


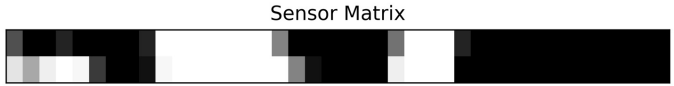


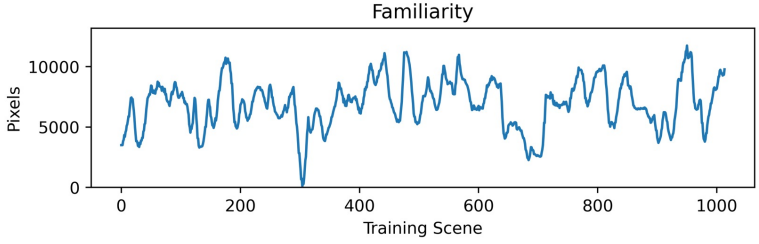
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

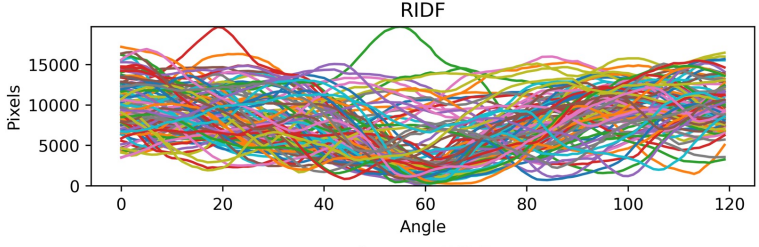
Navigation stats: RMSD error: 2421.62; RMSD/dist: 6.054; TD: 1758; p90: 20; p50: 14; complete: 0

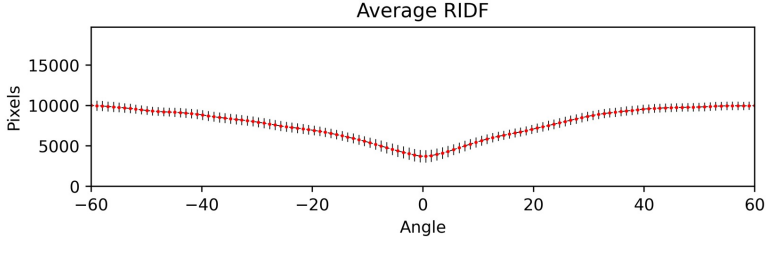
60%







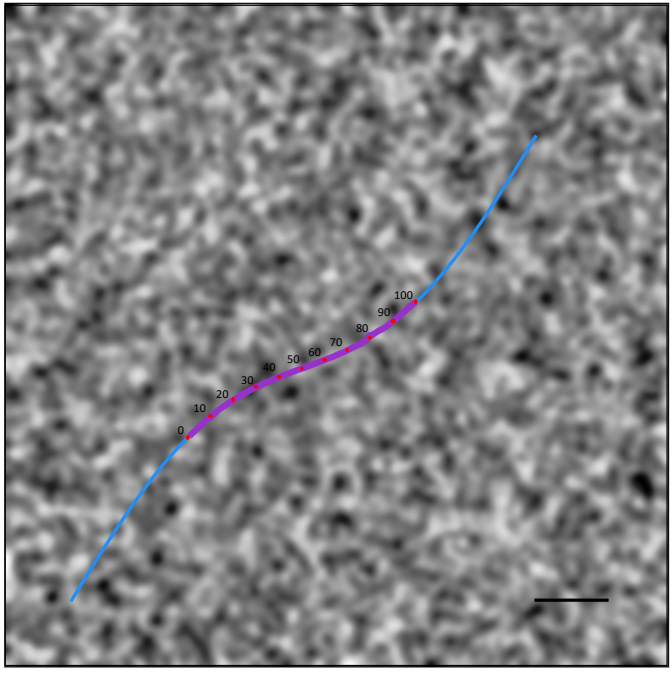


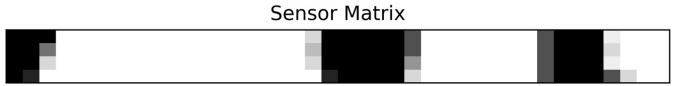


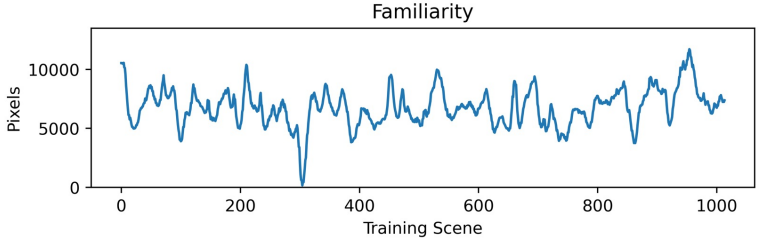
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

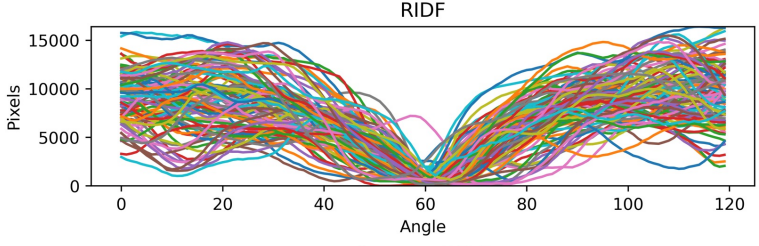
Navigation stats: RMSD error: 1917.73; RMSD/dist: 4.794; TD: 2954; p90: 32; p50: 18; complete: 0

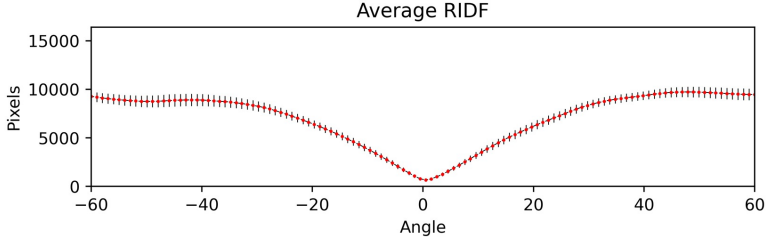
90%







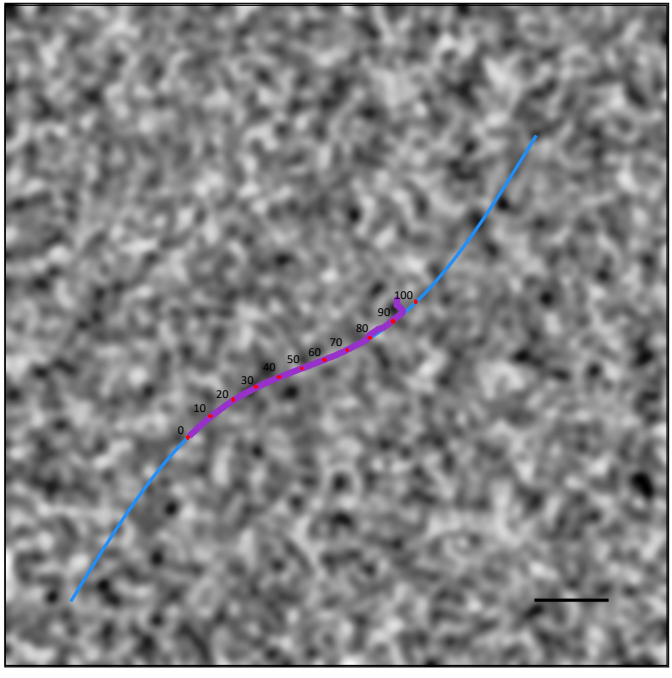


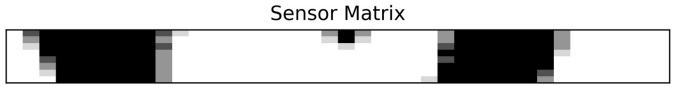


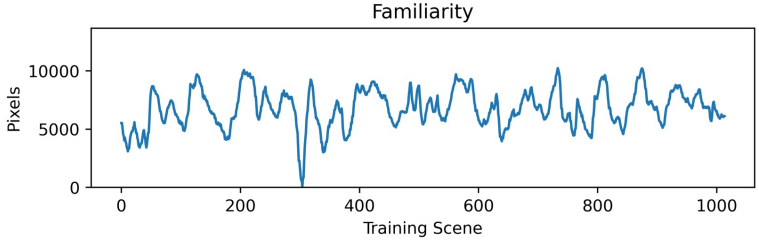
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

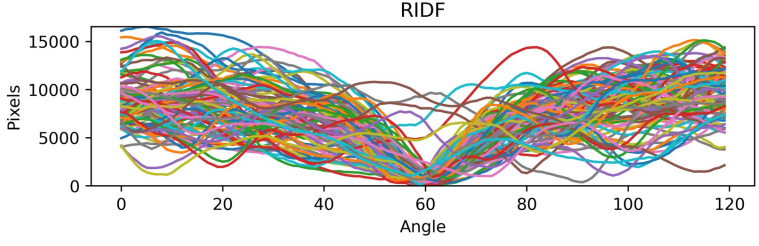
Navigation stats: RMSD error: 87.85; RMSD/dist: 0.220; TD: 6055; p90: 38; p50: 20; complete: 0

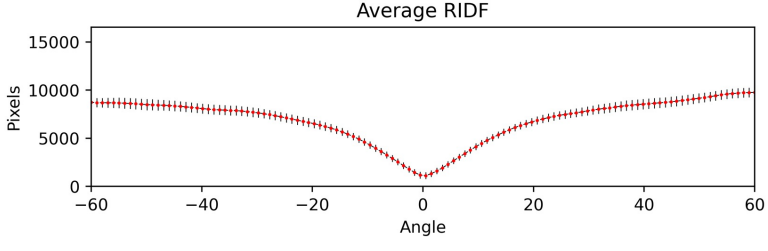
90%







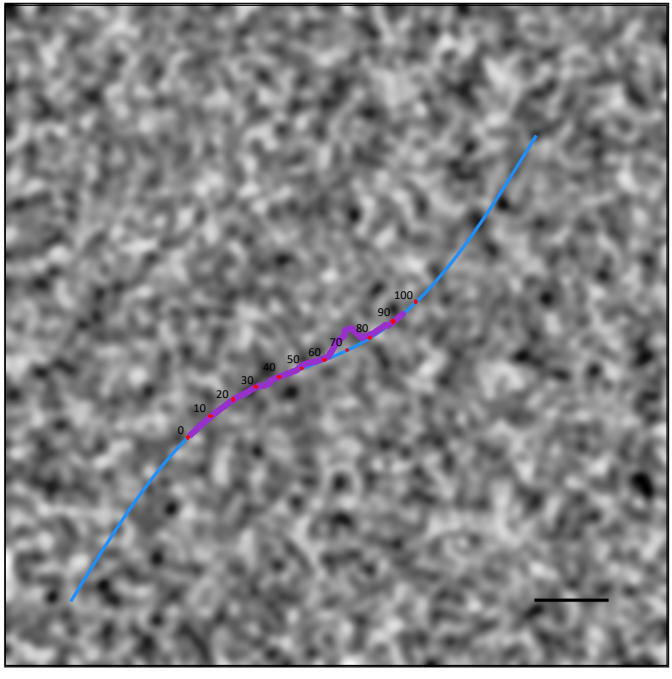


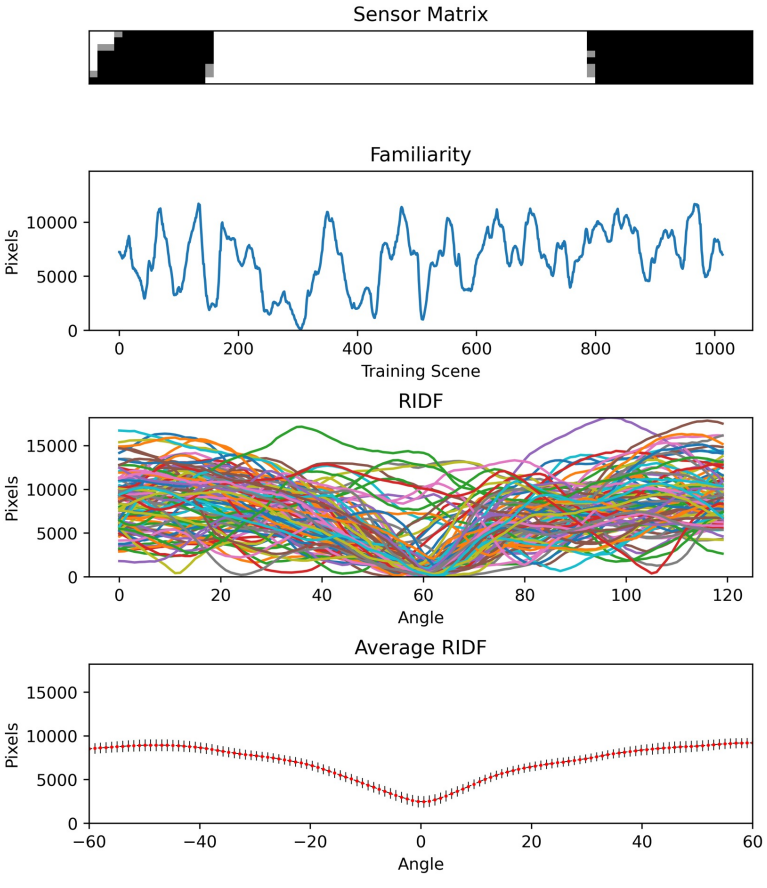


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 174.44; RMSD/dist: 0.436; TD: 5670; p90: 36; p50: 18; complete: 0

60%

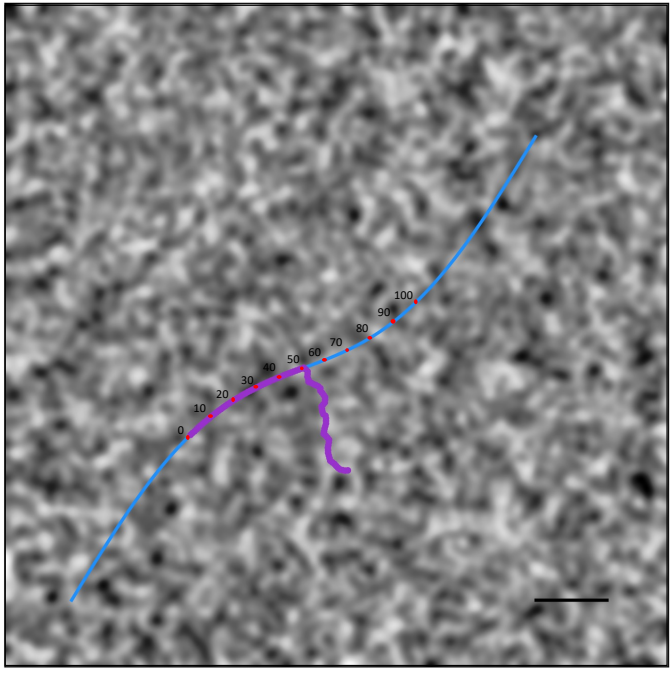


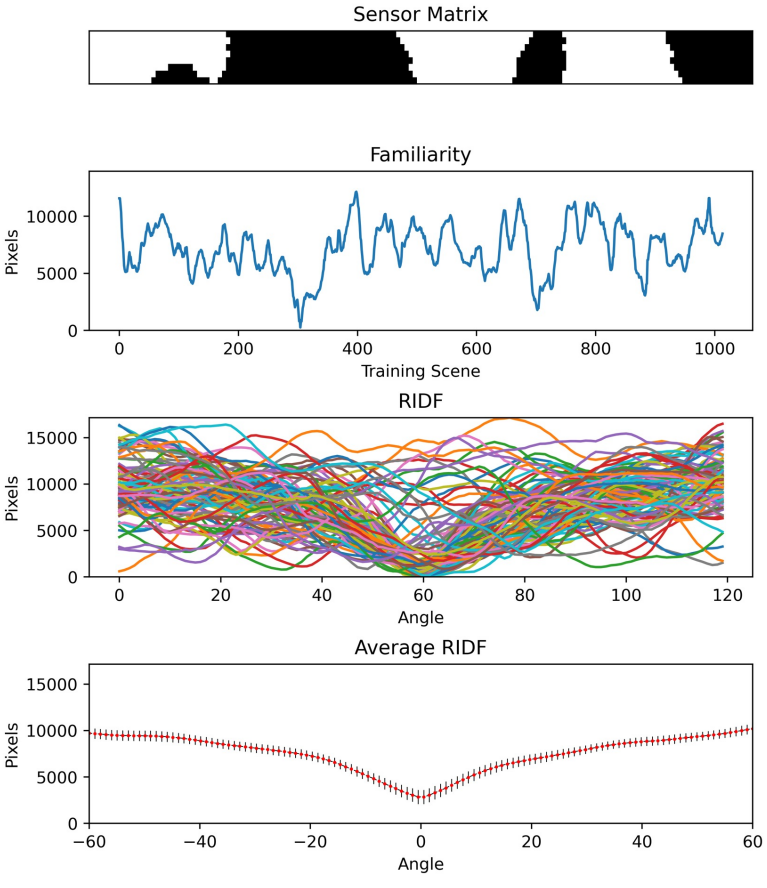


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 486.91; RMSD/dist: 1.217; TD: 4166; p90: 36; p50: 22; complete: 0

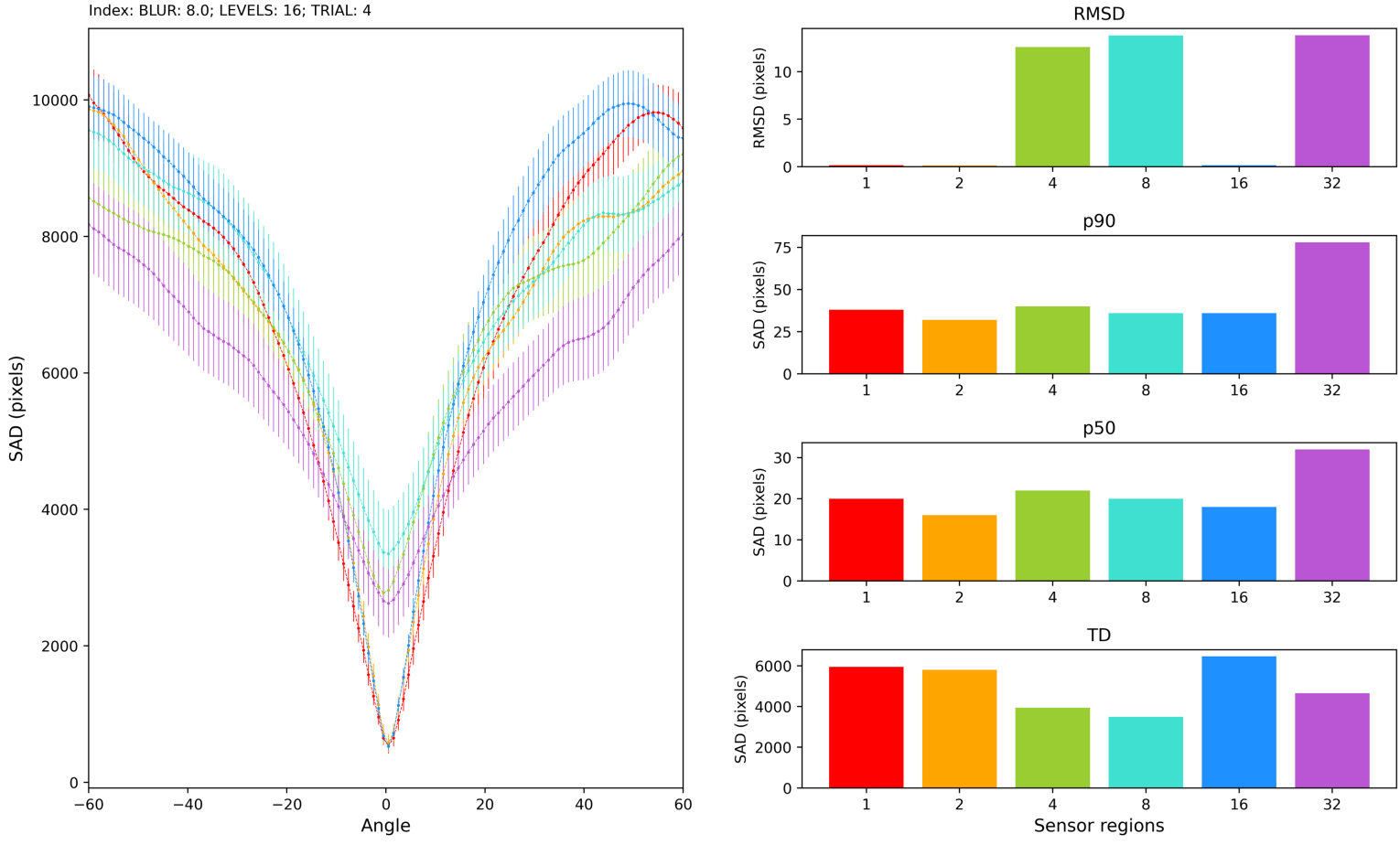
50%



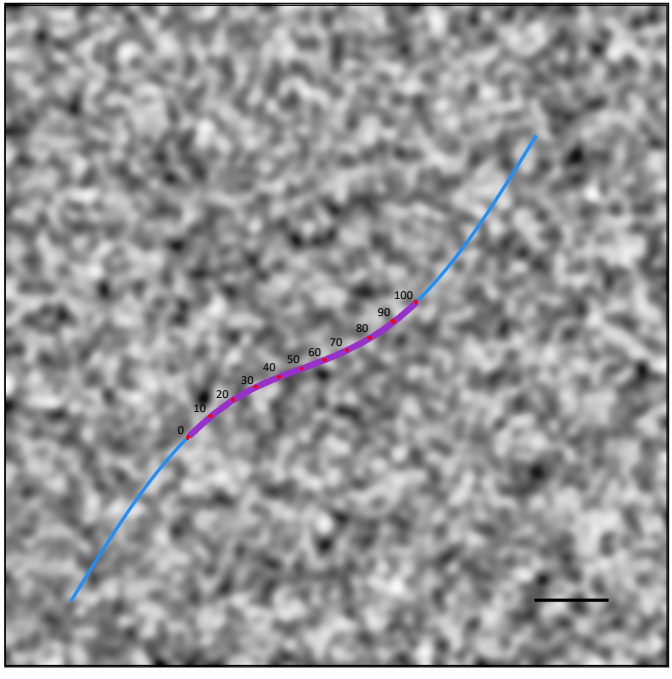


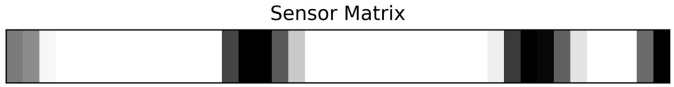
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

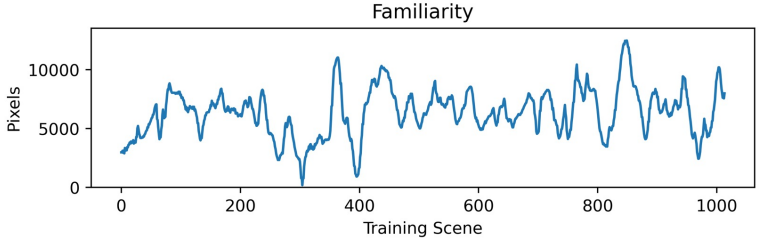
Navigation stats: RMSD error: 4269.93; RMSD/dist: 10.675; TD: 4017; p90: 32; p50: 18; complete: 0

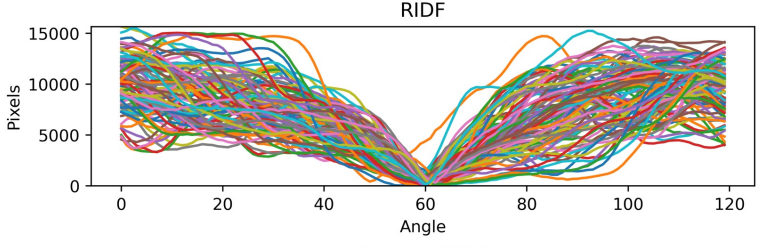

Index: BLUR: 8.0; LEVELS: 16; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

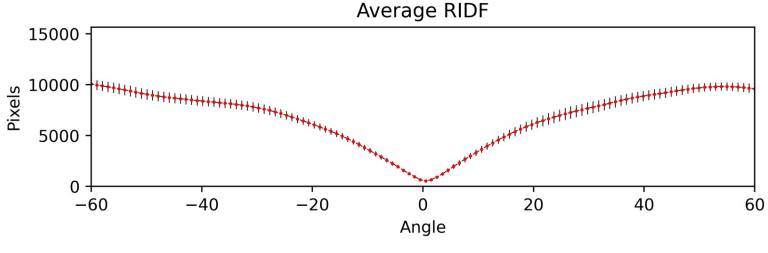
100%







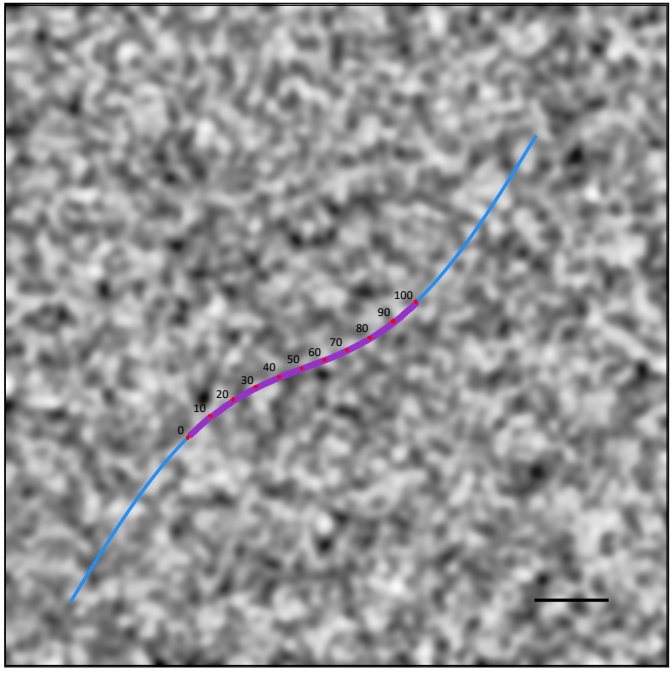


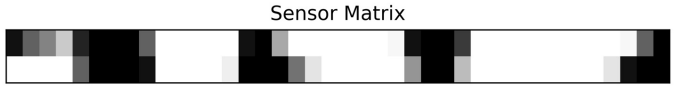


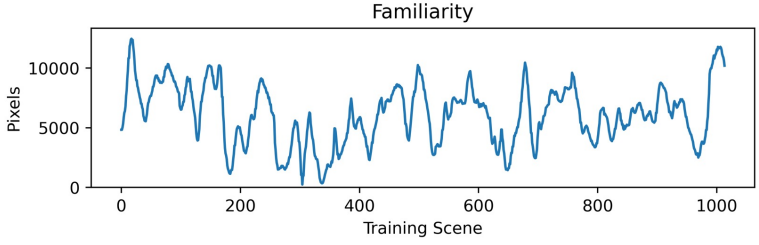
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

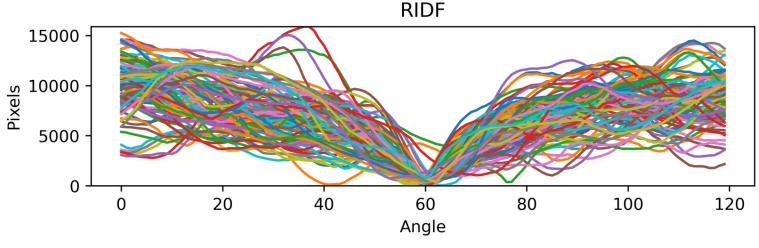
Navigation stats: RMSD error: 60.26; RMSD/dist: 0.151; TD: 5950; p90: 38; p50: 20; complete: 0

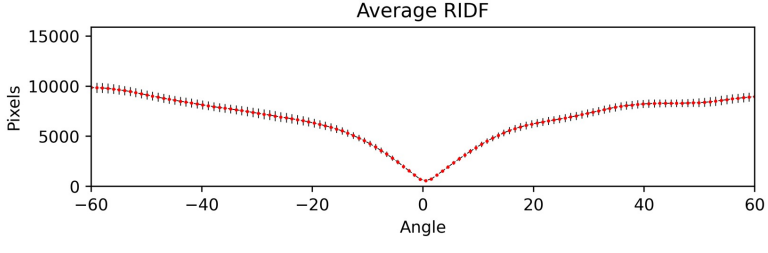
100%







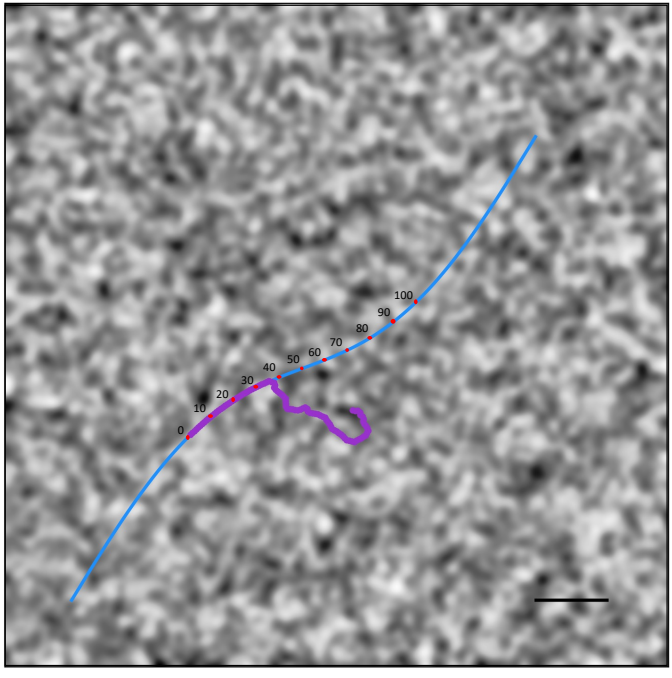


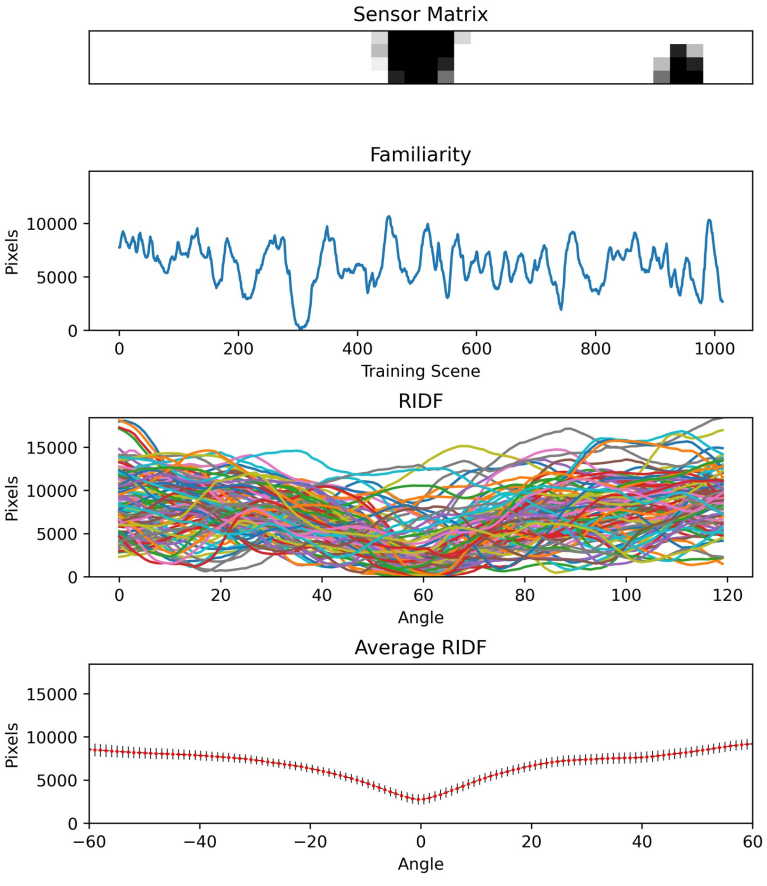


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 51.68; RMSD/dist: 0.129; TD: 5800; p90: 32; p50: 16; complete: 0

30%

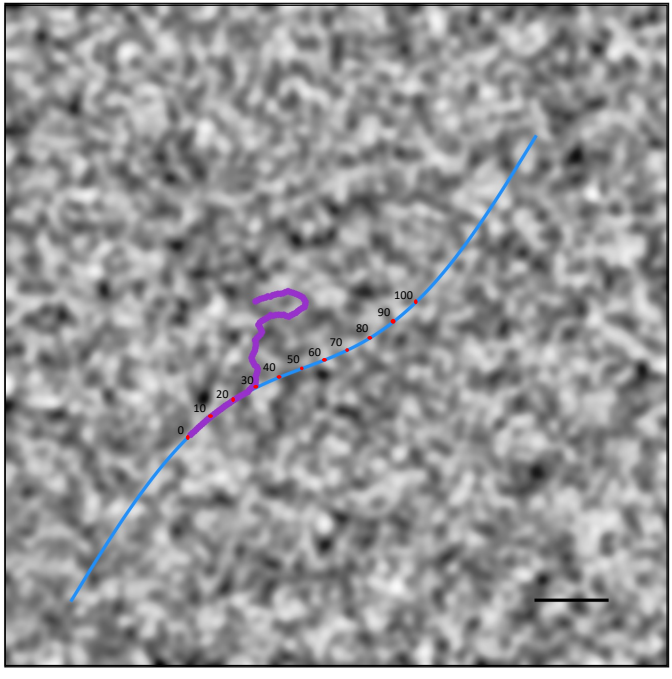


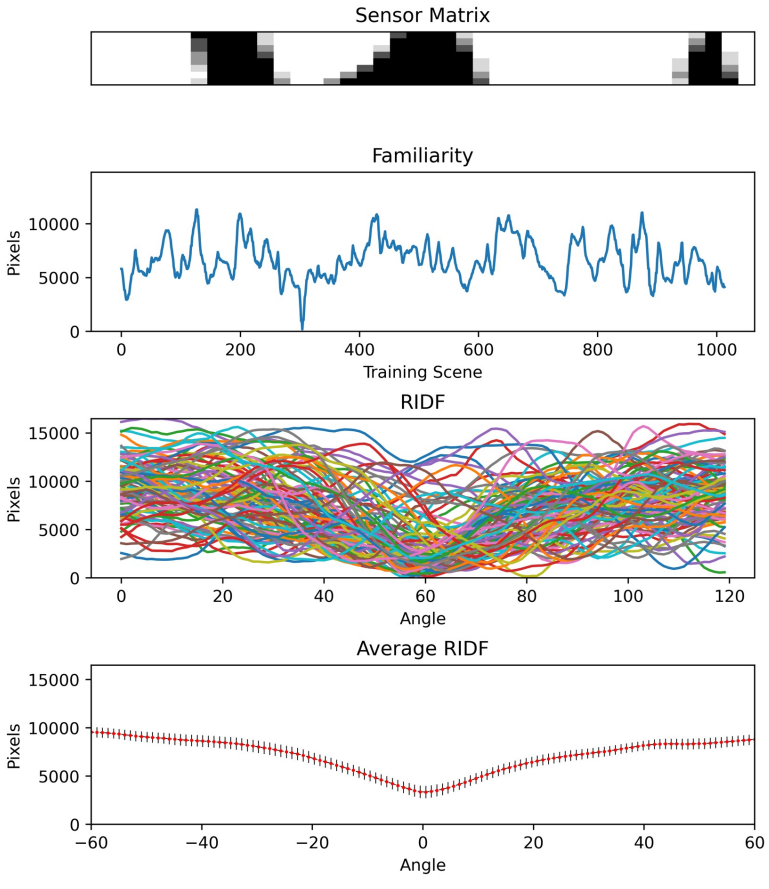


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 5040.05; RMSD/dist: 12.600; TD: 3935; p90: 40; p50: 22; complete: 0

20%

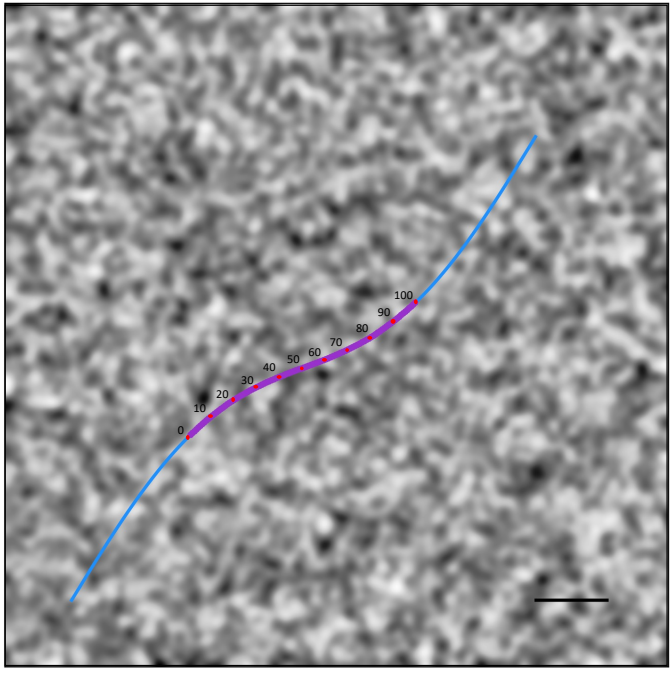


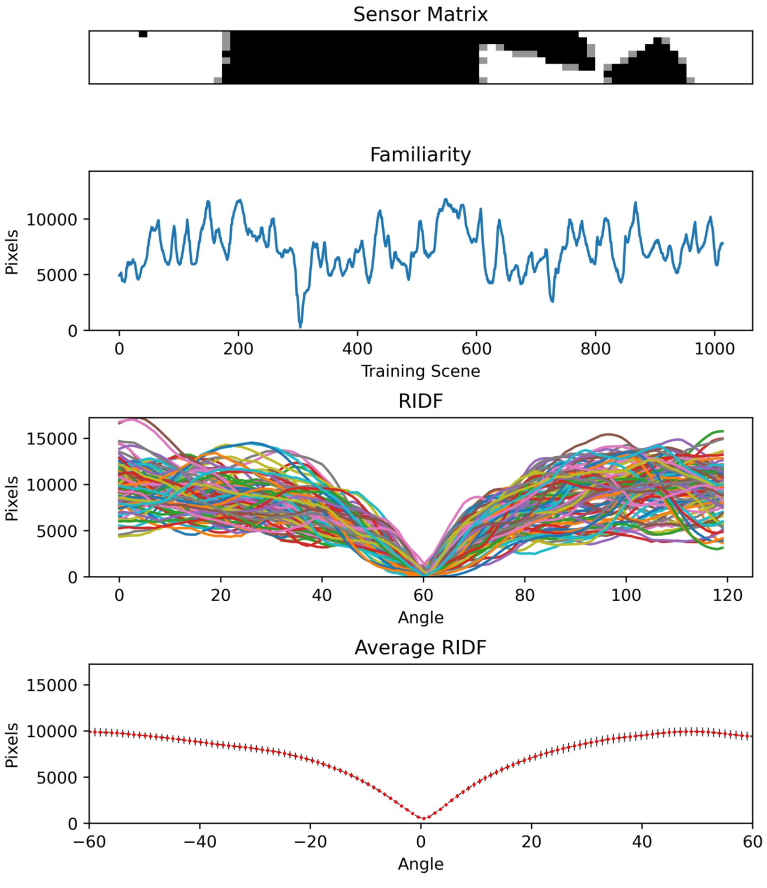


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 5526.12; RMSD/dist: 13.815; TD: 3494; p90: 36; p50: 20; complete: 0

100%

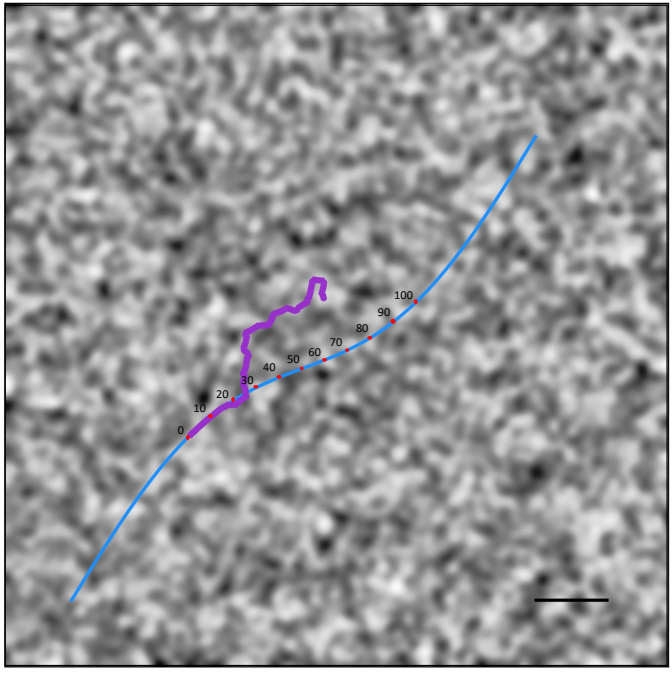


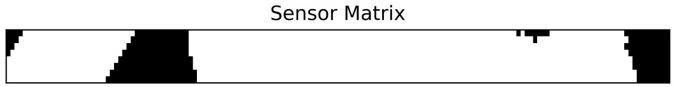


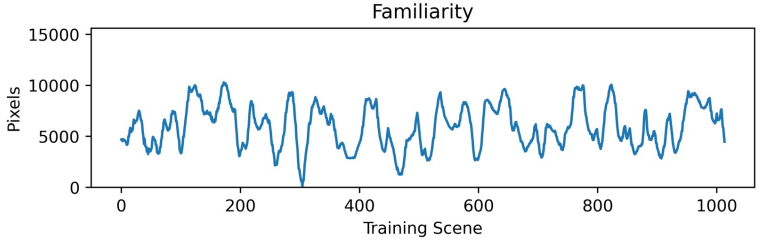
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

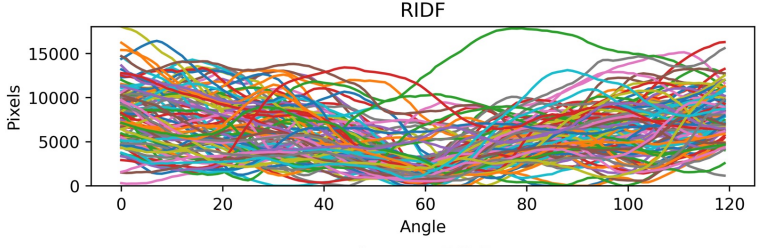
Navigation stats: RMSD error: 61.39; RMSD/dist: 0.153; TD: 6457; p90: 36; p50: 18; complete: 0

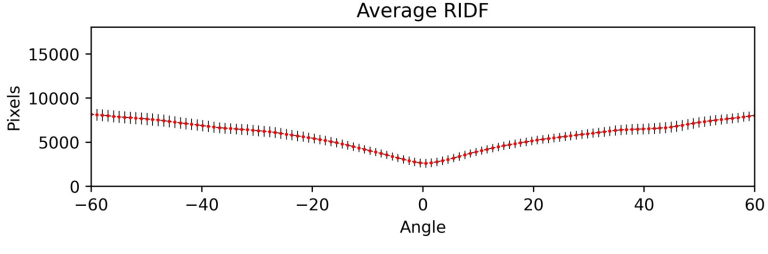
10%





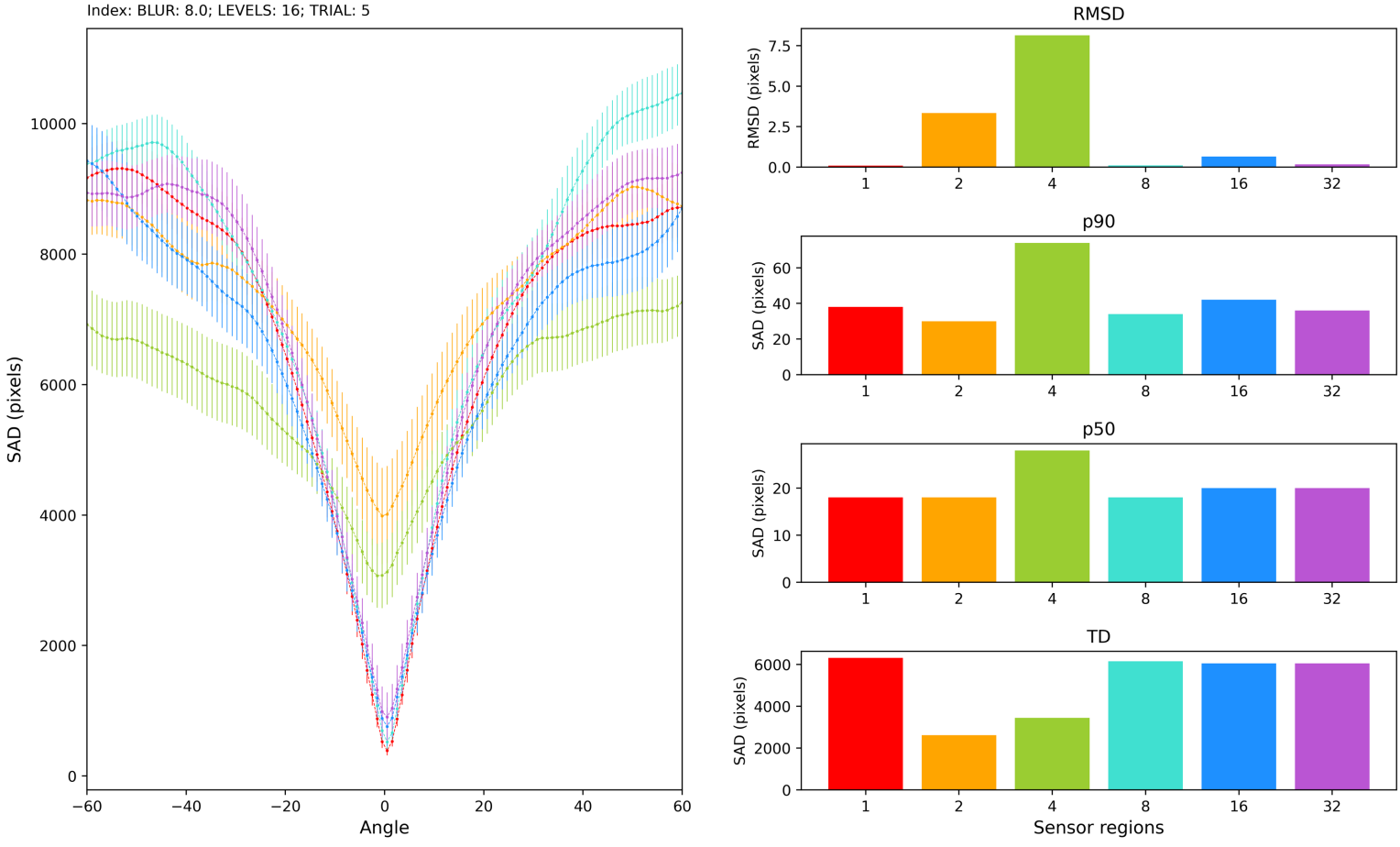




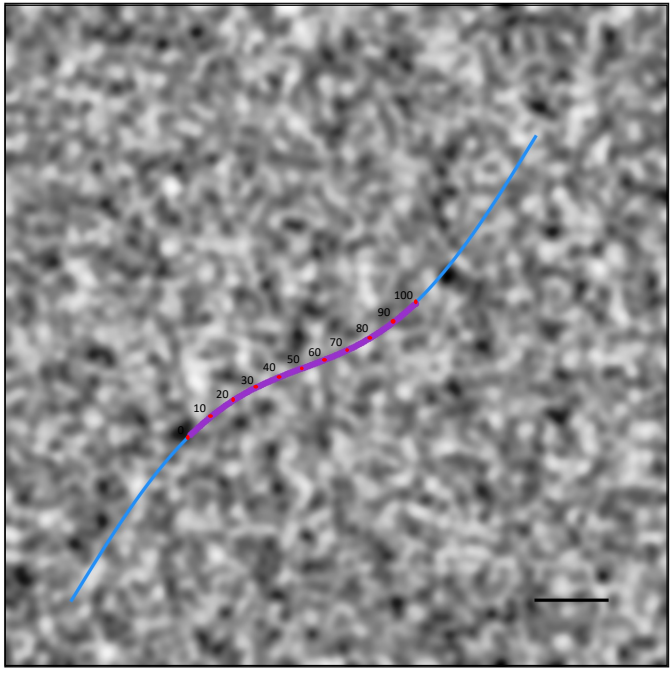


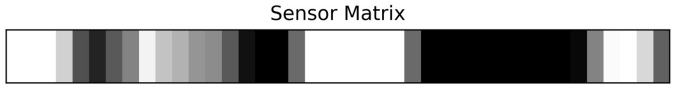
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

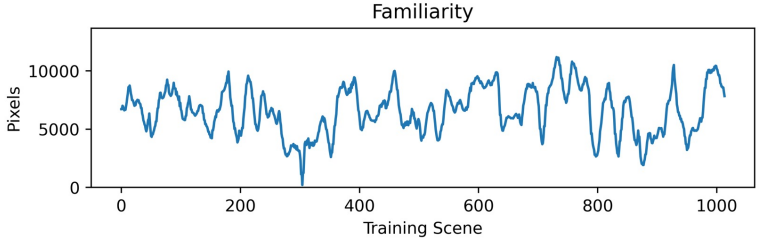
Navigation stats: RMSD error: 5540.09; RMSD/dist: 13.850; TD: 4649; p90: 78; p50: 32; complete: 0

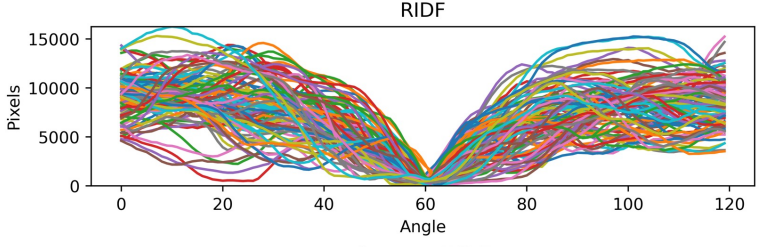

Index: BLUR: 8.0; LEVELS: 16; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

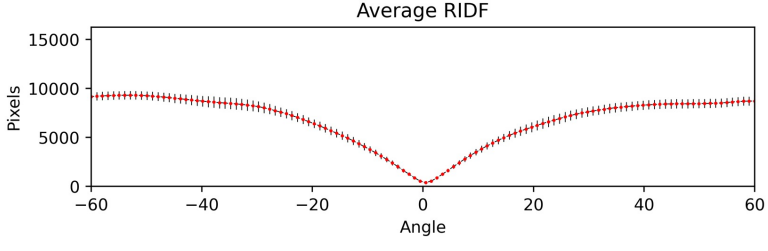
100%







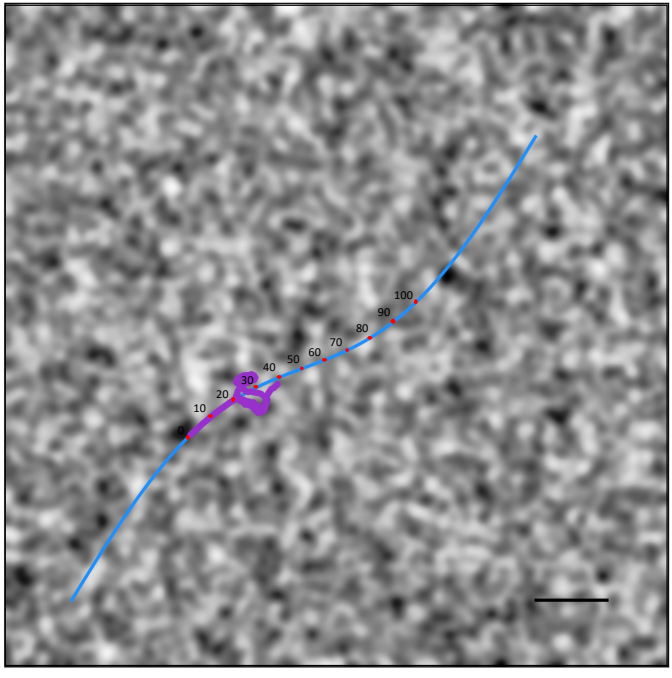


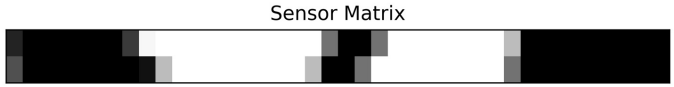


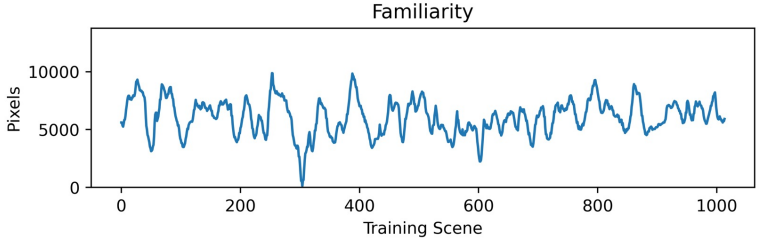
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

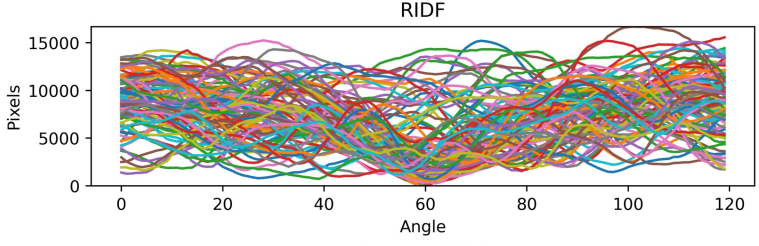
Navigation stats: RMSD error: 36.56; RMSD/dist: 0.091; TD: 6306; p90: 38; p50: 18; complete: 0

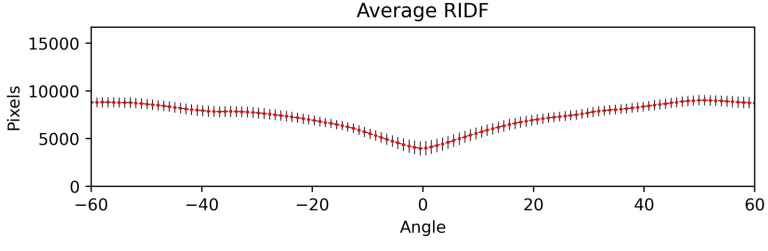
20%







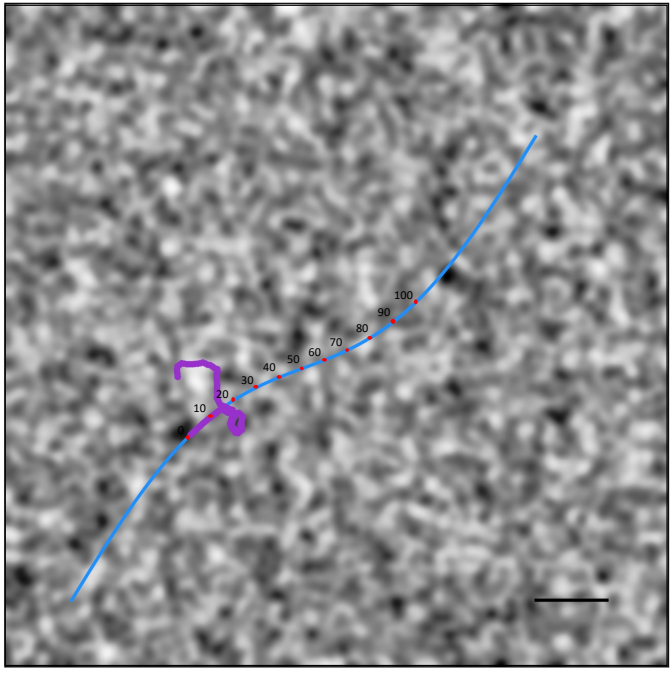


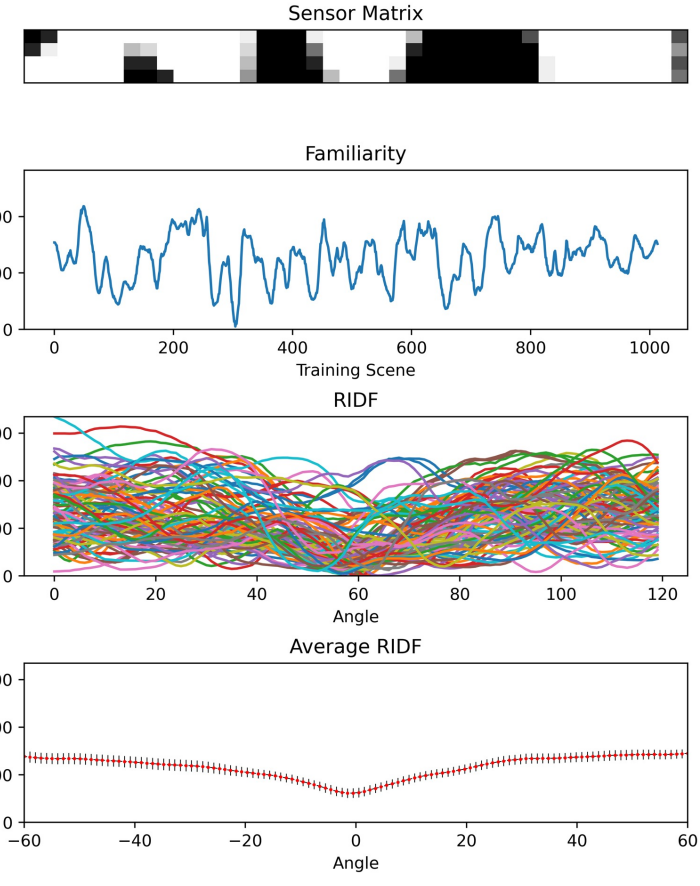


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 1334.86; RMSD/dist: 3.337; TD: 2615; p90: 30; p50: 18; complete: 0

10%

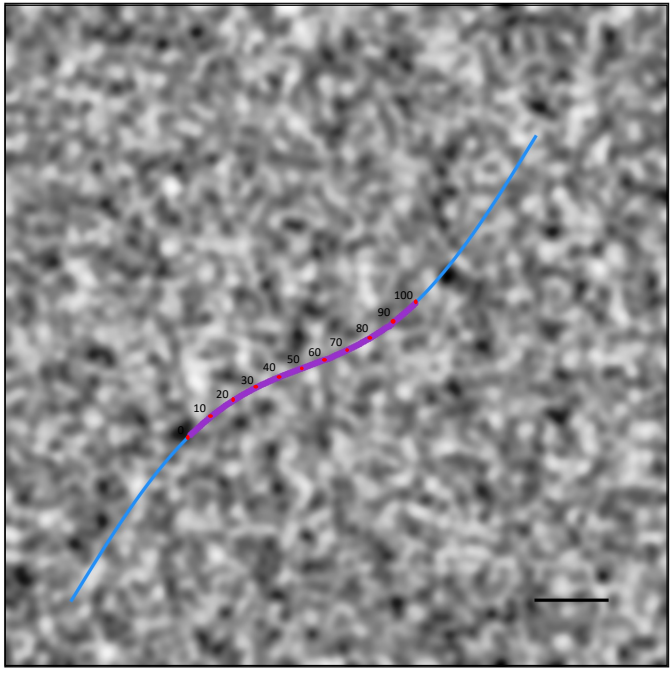


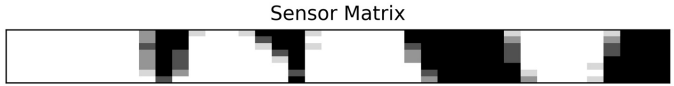


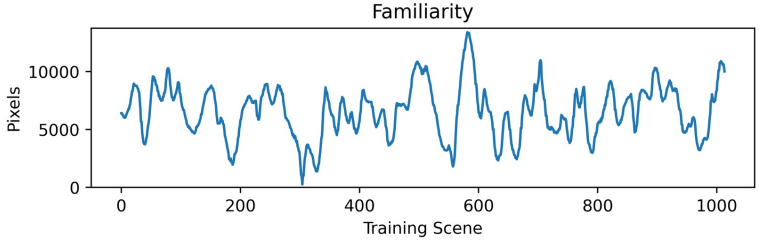
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

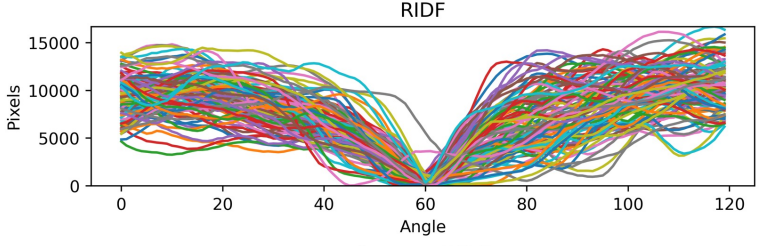
Navigation stats: RMSD error: 3260.71; RMSD/dist: 8.152; TD: 3438; p90: 74; p50: 28; complete: 0

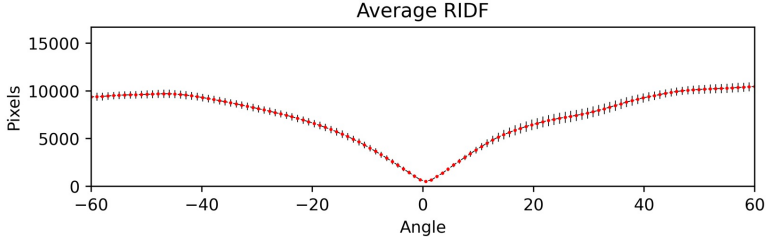
100%







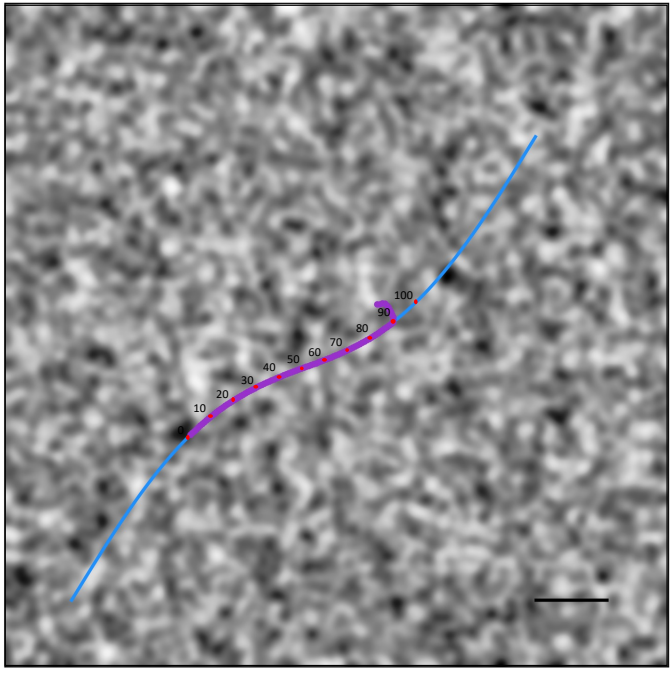


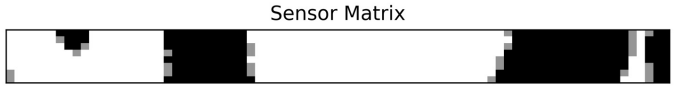


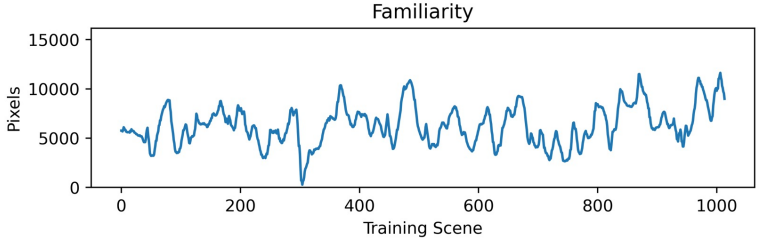
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

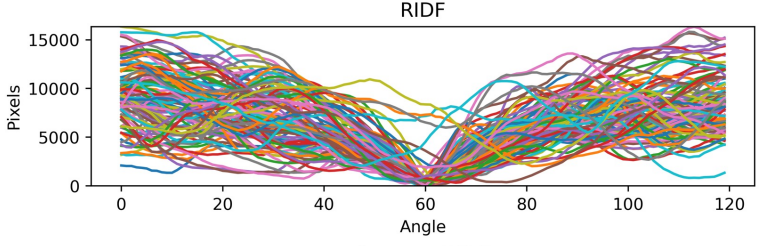
Navigation stats: RMSD error: 41.17; RMSD/dist: 0.103; TD: 6149; p90: 34; p50: 18; complete: 0

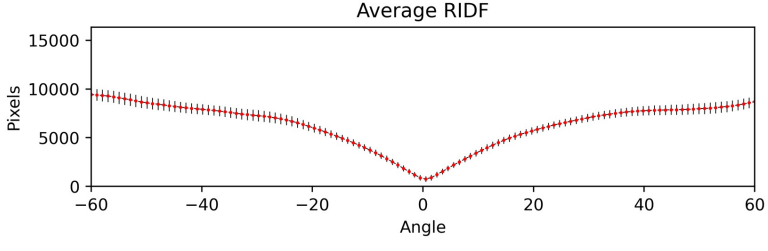
90%







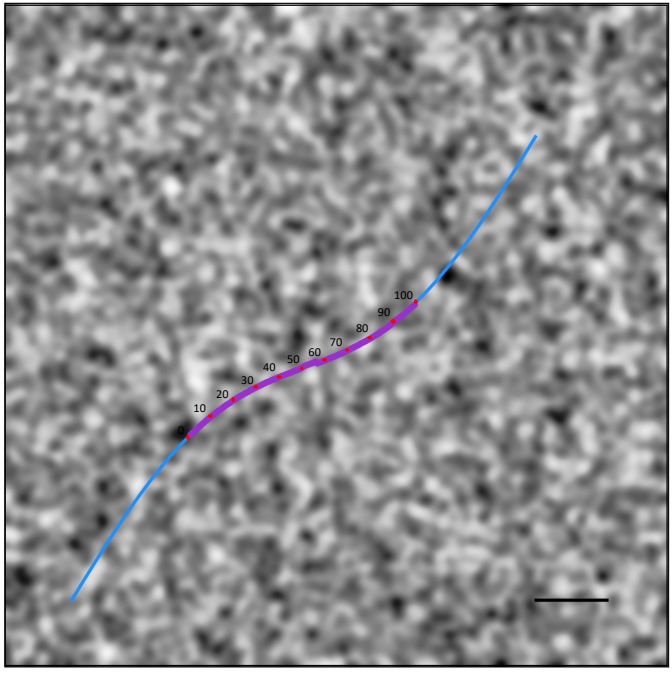


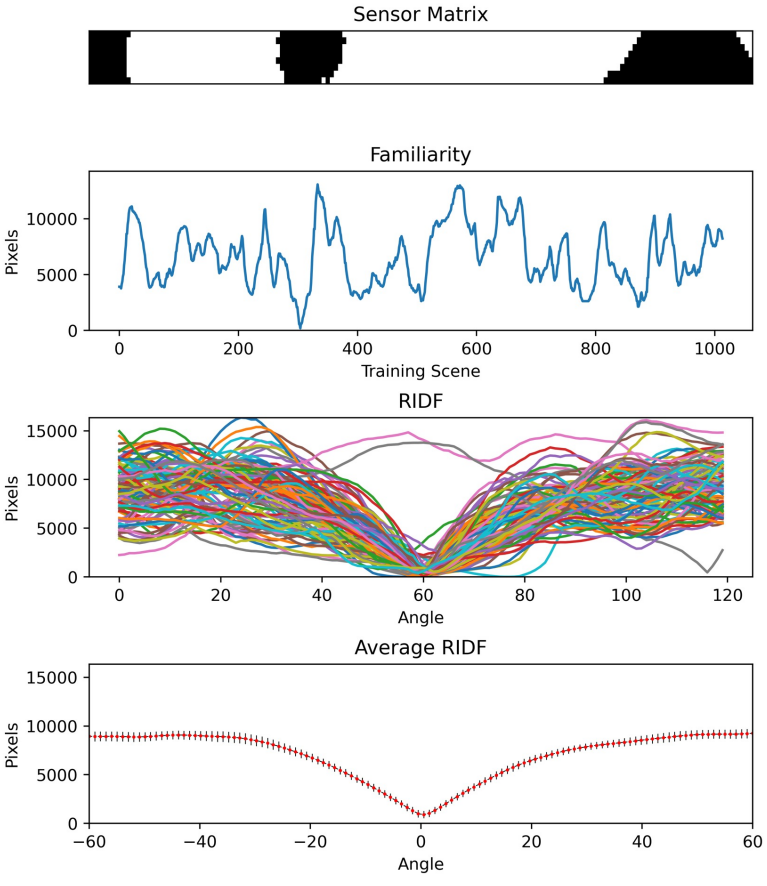


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 257.08; RMSD/dist: 0.643; TD: 6044; p90: 42; p50: 20; complete: 0

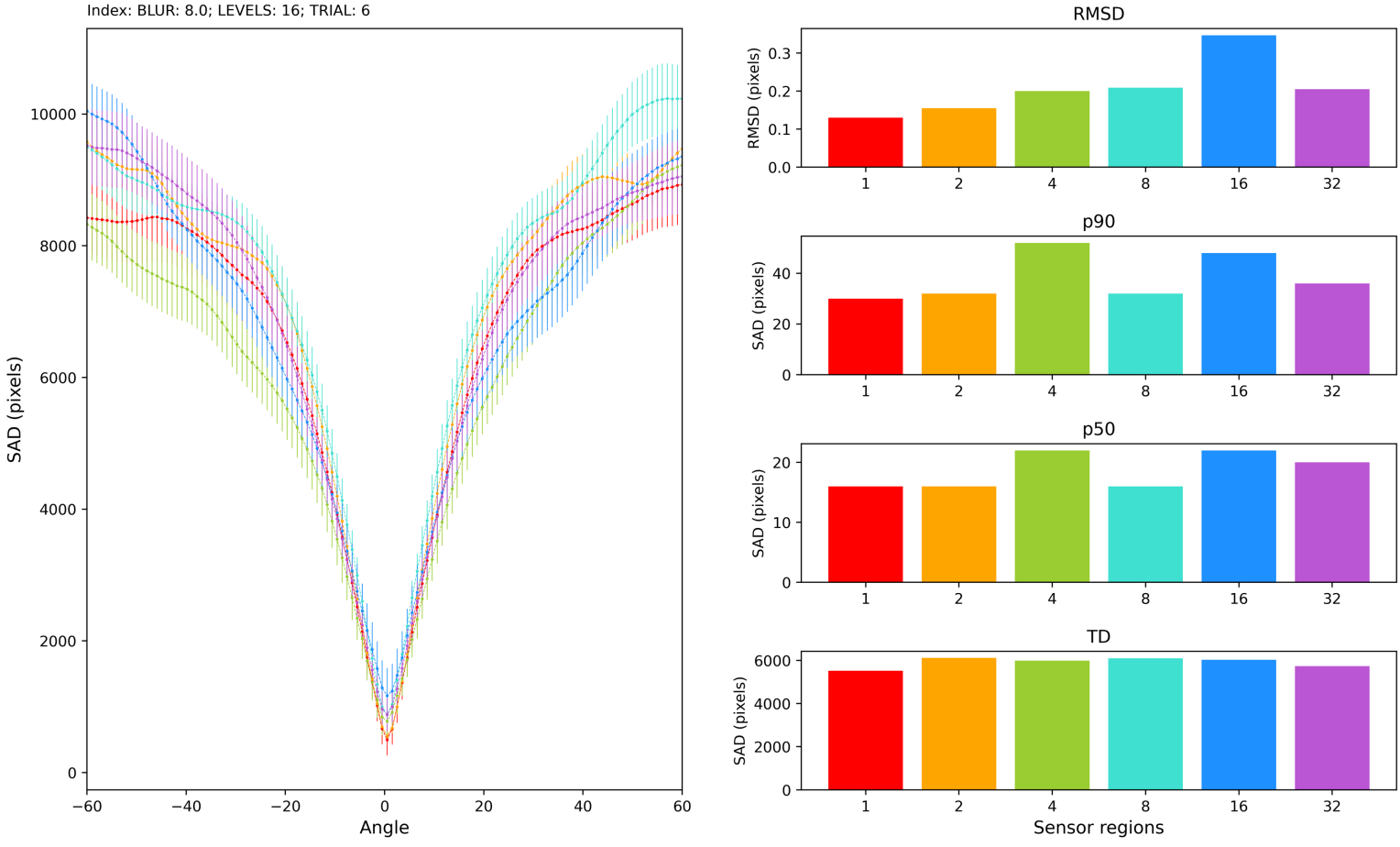
90%



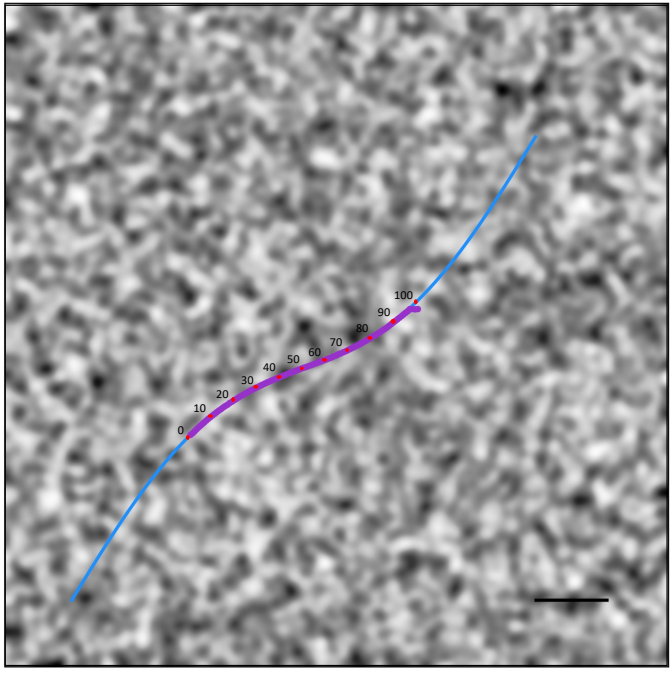


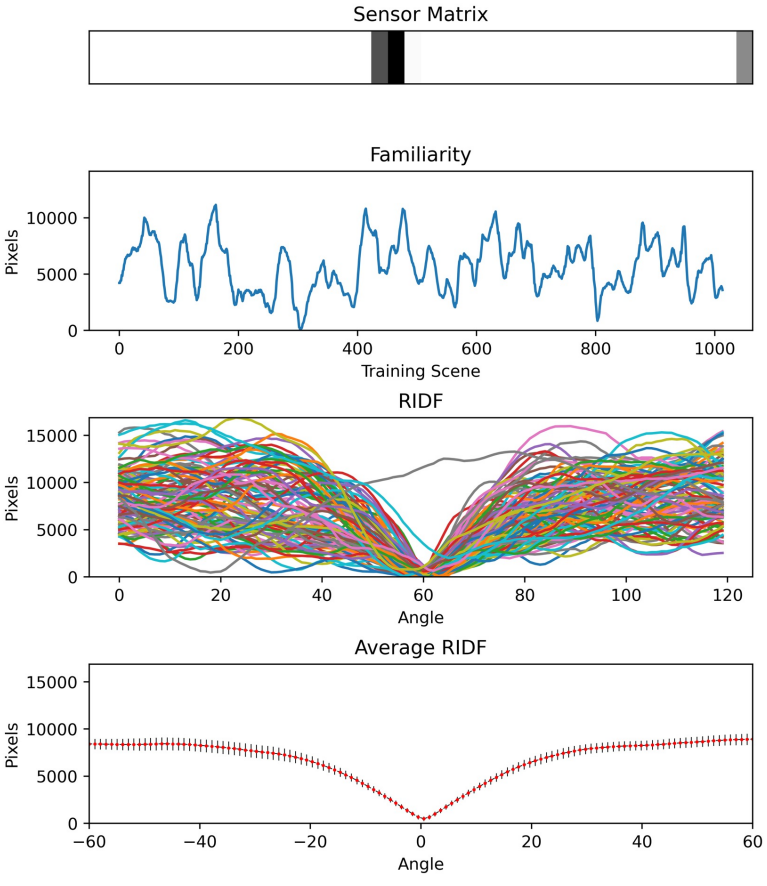
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 68.82; RMSD/dist: 0.172; TD: 6047; p90: 36; p50: 20; complete: 0


Index: BLUR: 8.0; LEVELS: 16; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

90%

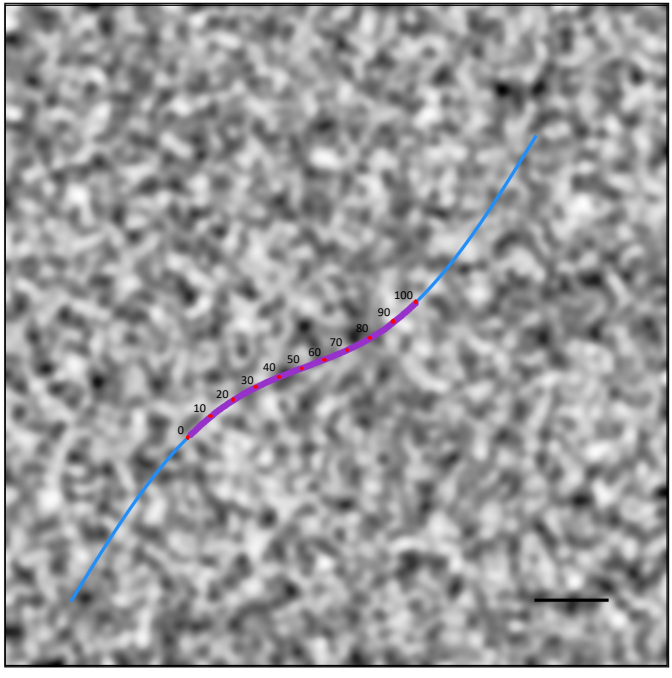


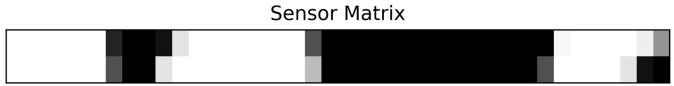


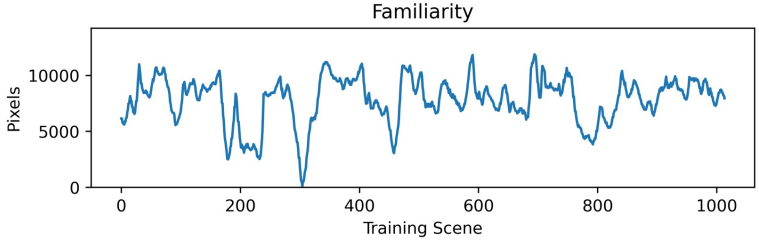
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

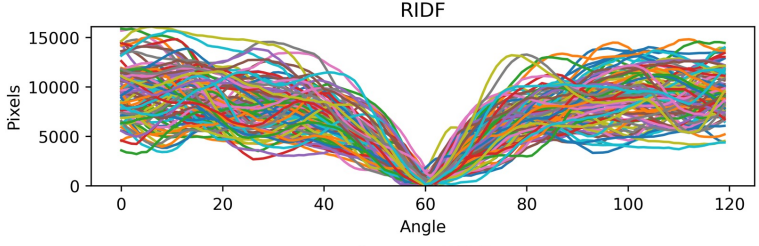
Navigation stats: RMSD error: 51.97; RMSD/dist: 0.130; TD: 5523; p90: 30; p50: 16; complete: 0

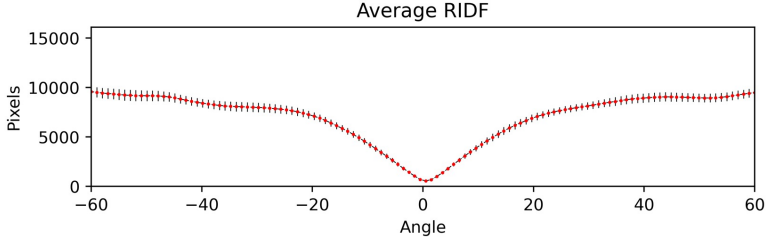
100%







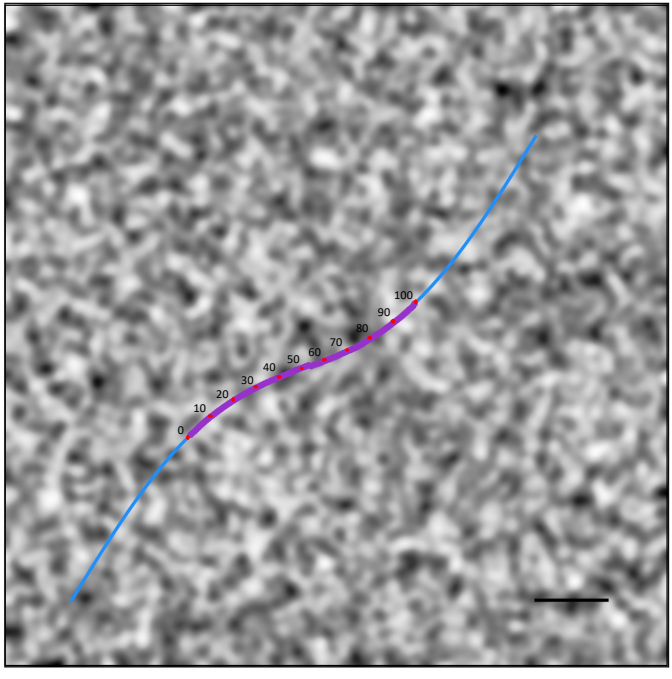


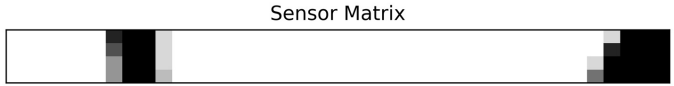


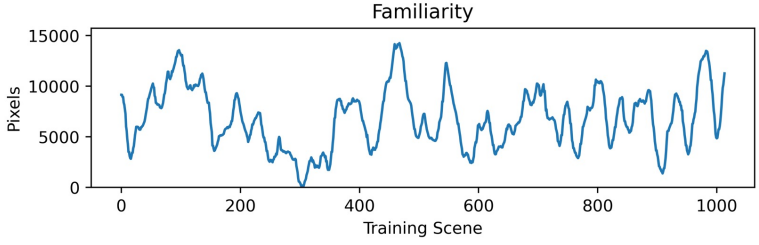
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

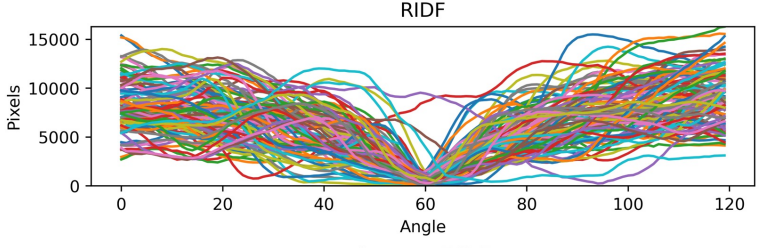
Navigation stats: RMSD error: 61.83; RMSD/dist: 0.155; TD: 6112; p90: 32; p50: 16; complete: 0

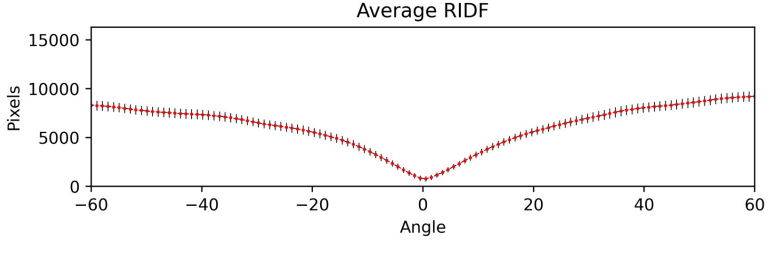
90%







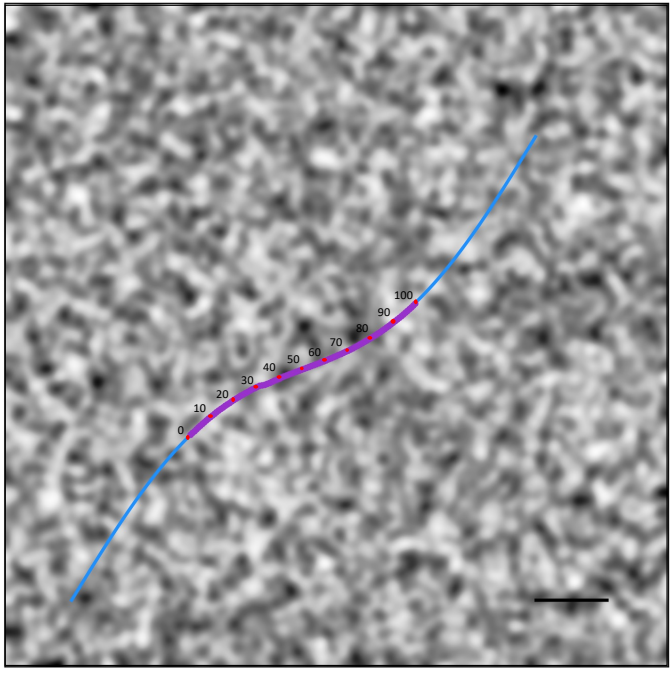


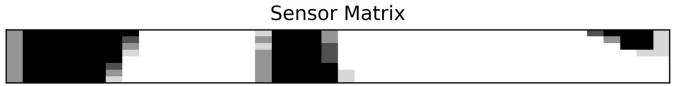


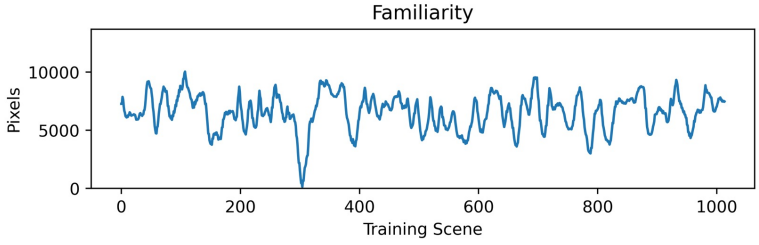
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

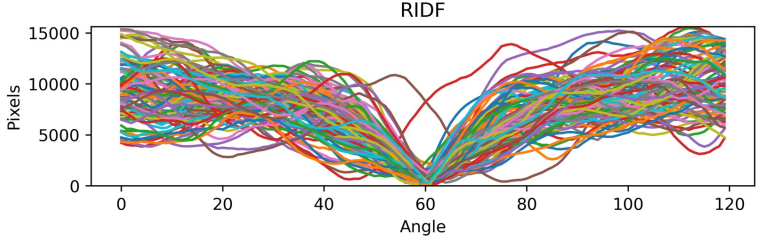
Navigation stats: RMSD error: 79.89; RMSD/dist: 0.200; TD: 5994; p90: 52; p50: 22; complete: 0

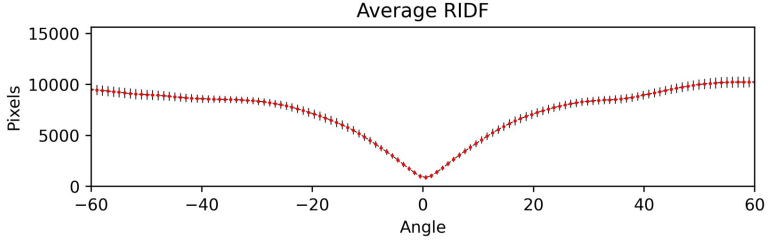
90%







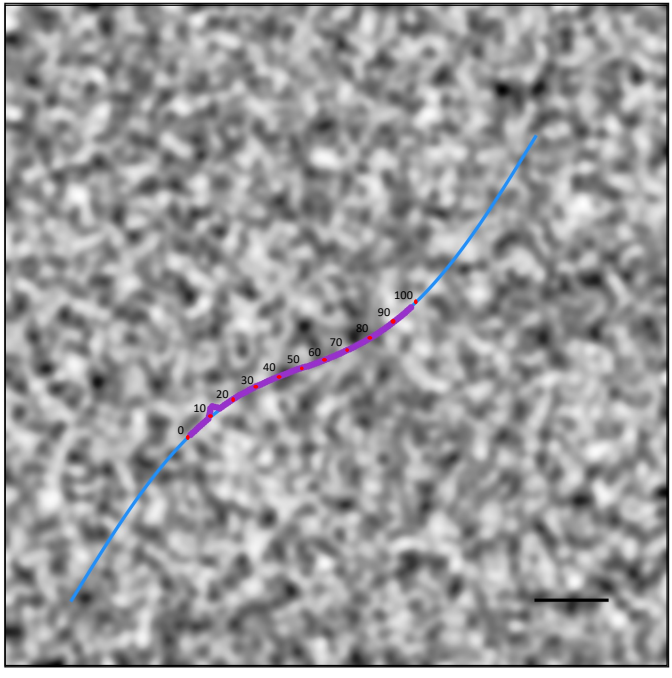


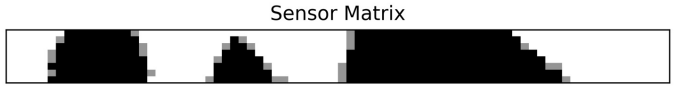


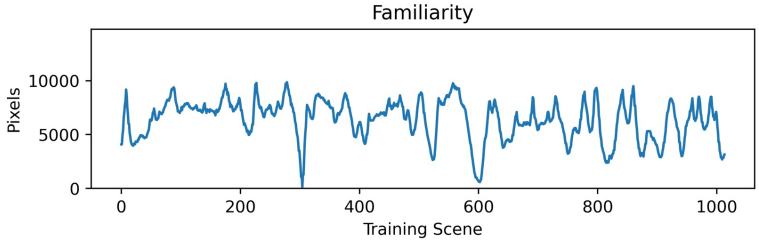
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

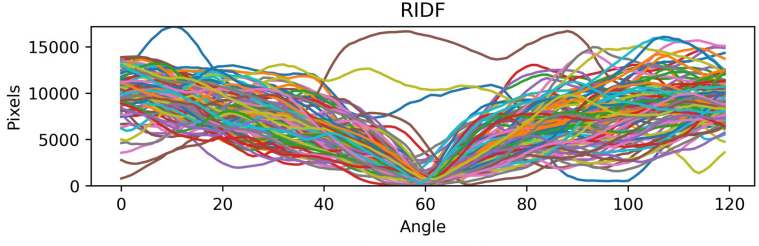
Navigation stats: RMSD error: 83.75; RMSD/dist: 0.209; TD: 6094; p90: 32; p50: 16; complete: 0

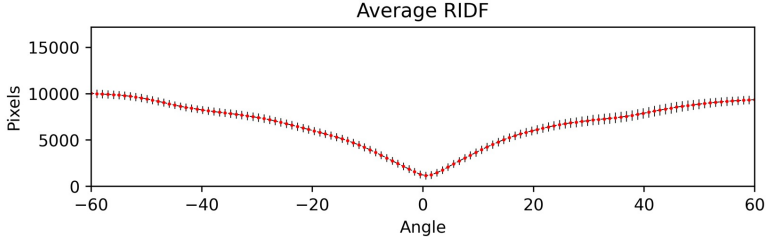
90%







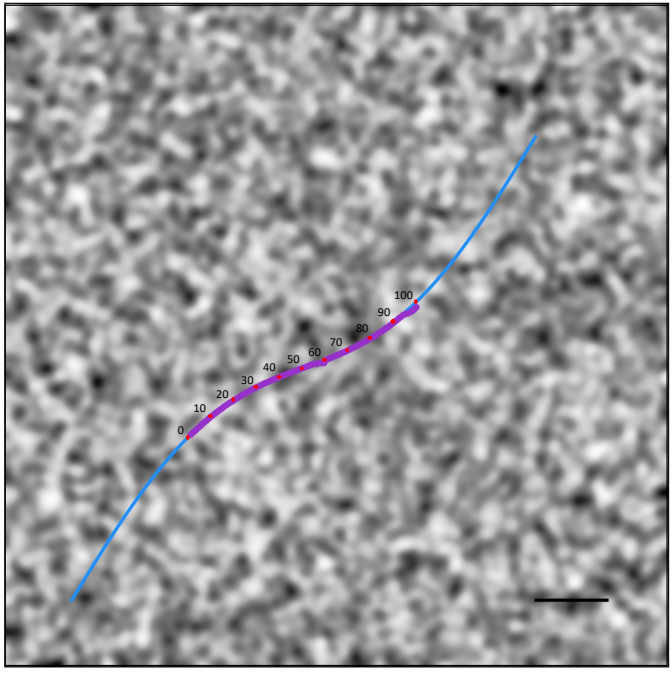


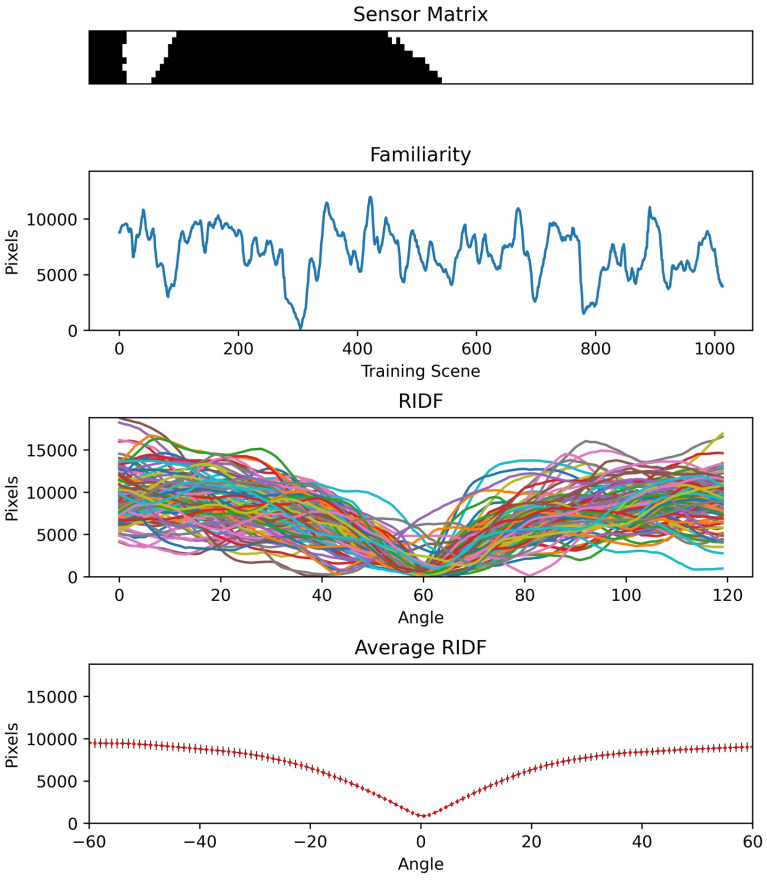


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 138.88; RMSD/dist: 0.347; TD: 6033; p90: 48; p50: 22; complete: 0

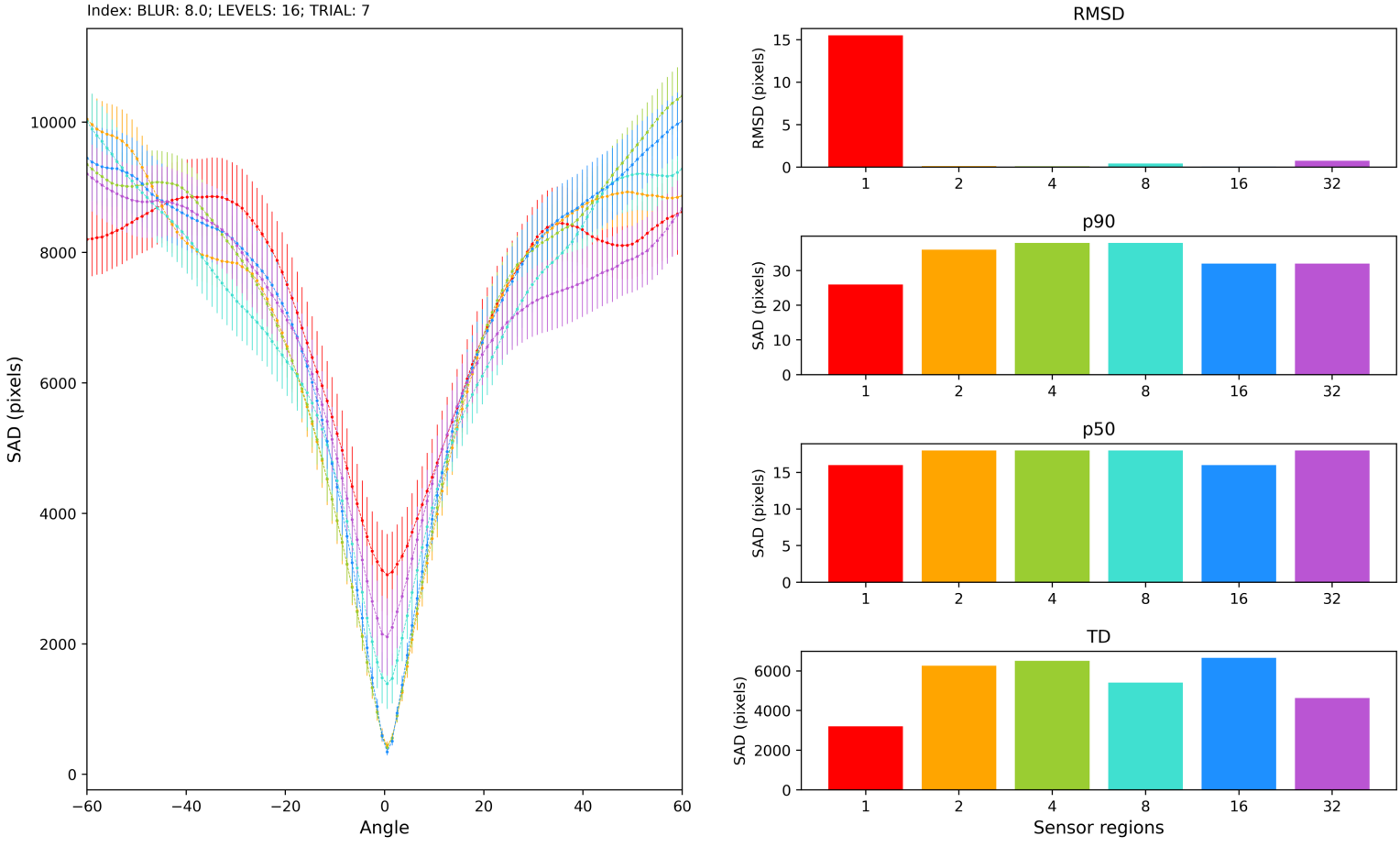
90%



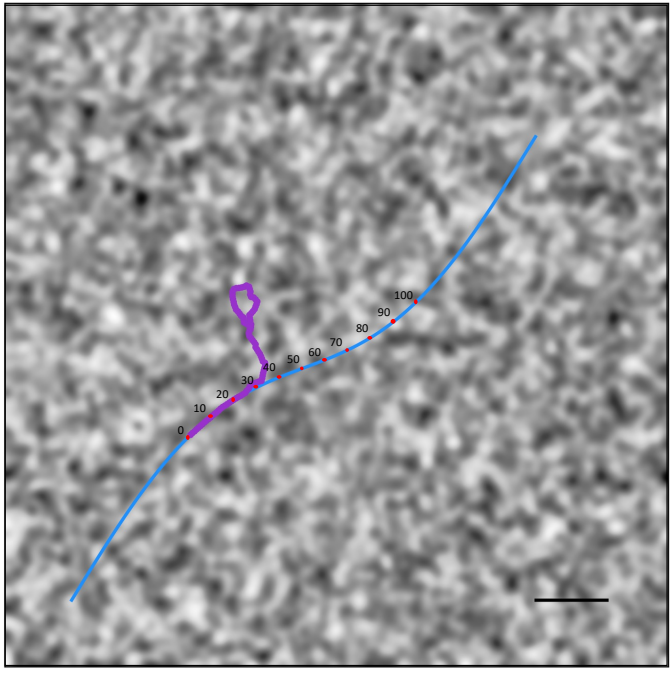


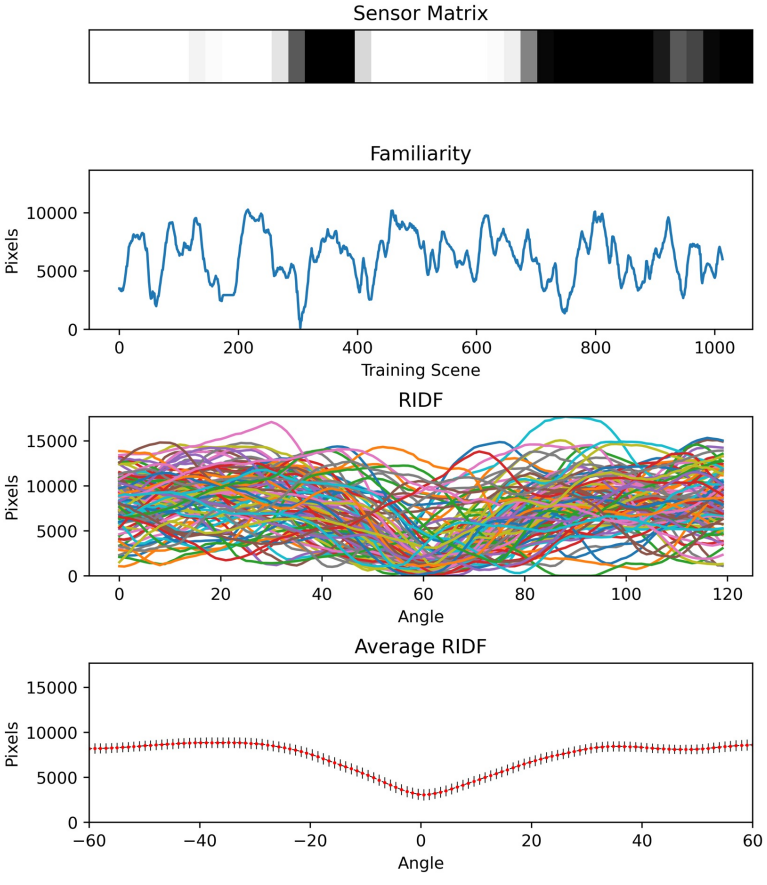
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 81.85; RMSD/dist: 0.205; TD: 5737; p90: 36; p50: 20; complete: 0


Index: BLUR: 8.0; LEVELS: 16; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

20%

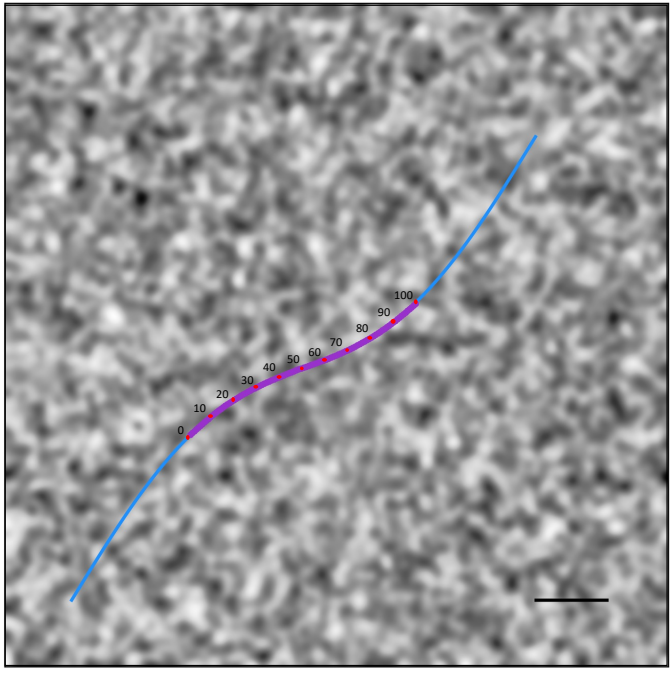


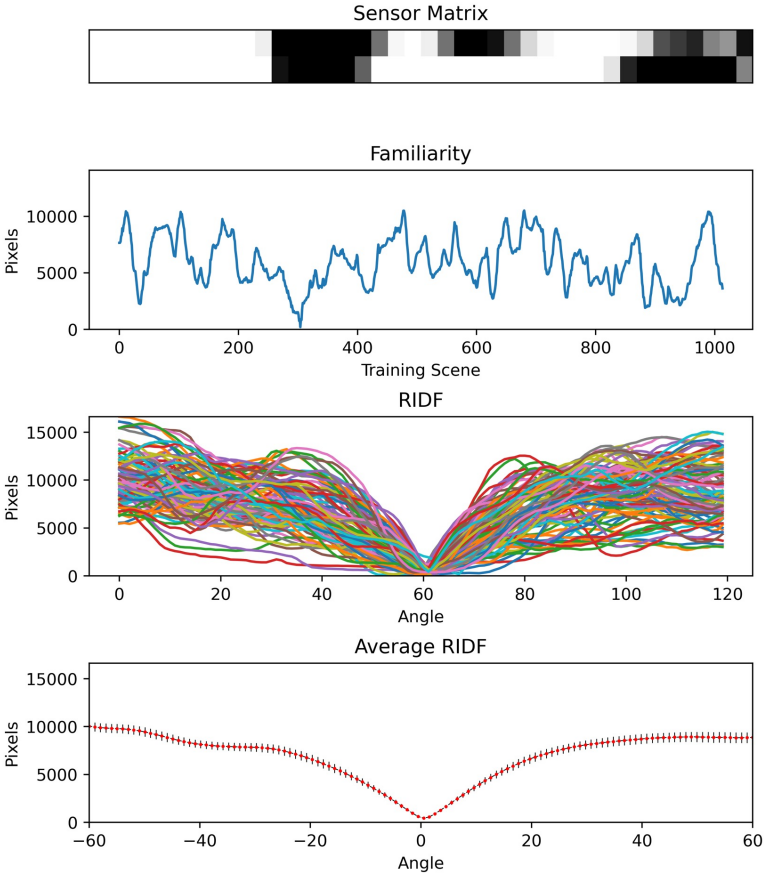


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 6208.38; RMSD/dist: 15.521; TD: 3202; p90: 26; p50: 16; complete: 0

100%

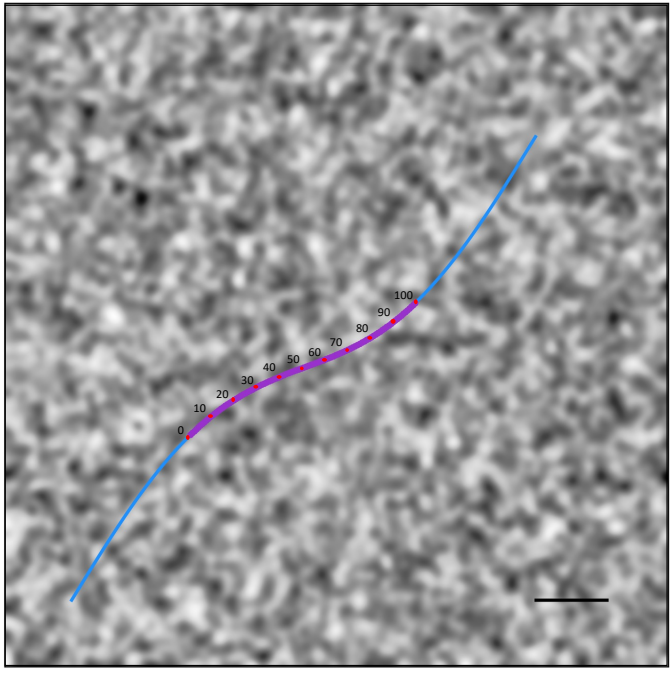


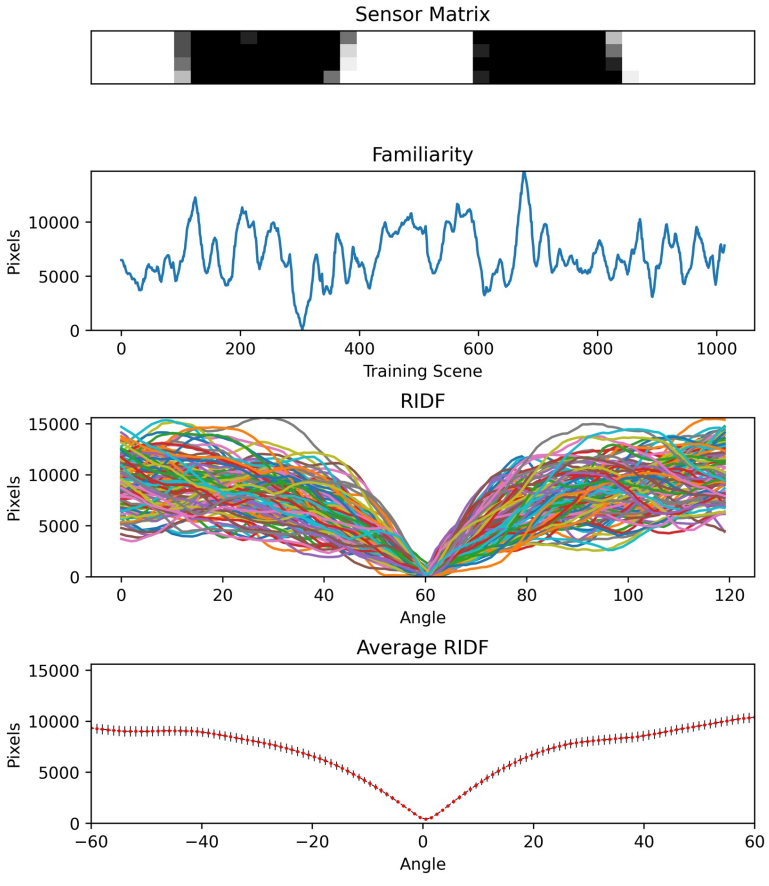


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 42.60; RMSD/dist: 0.106; TD: 6258; p90: 36; p50: 18; complete: 0

100%

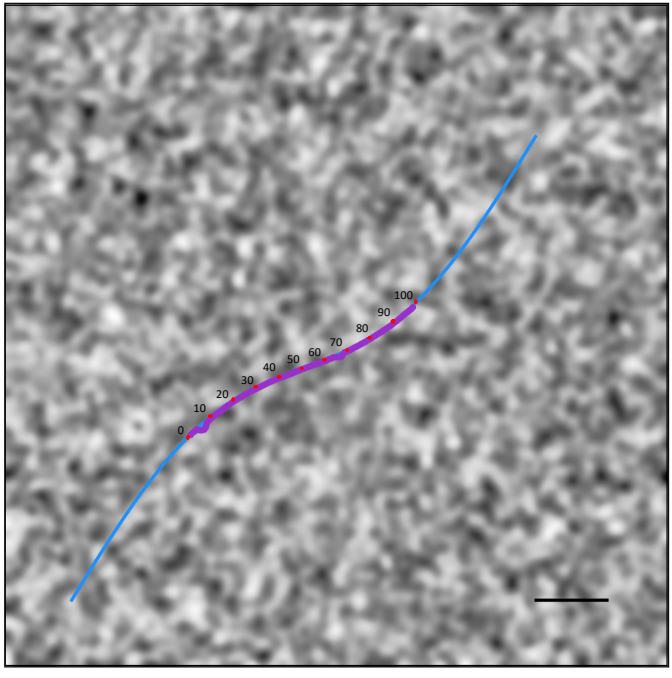


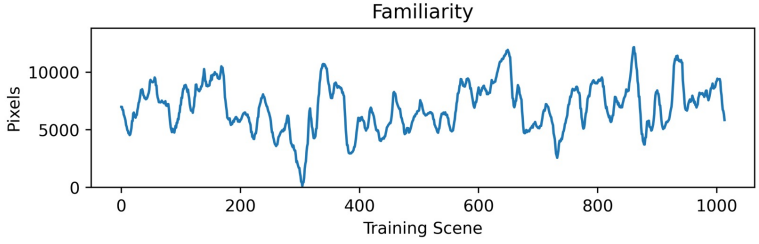


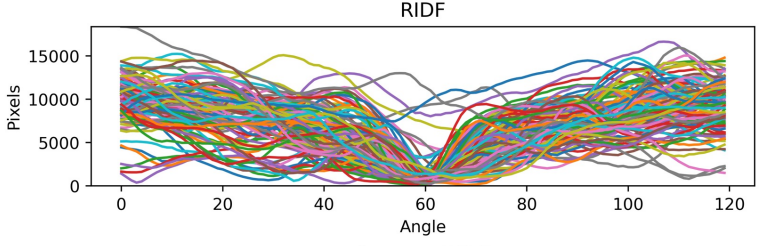
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

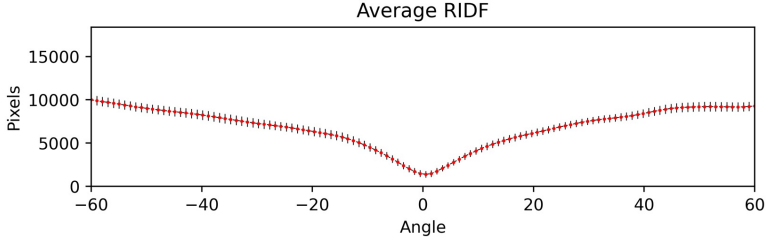
Navigation stats: RMSD error: 39.02; RMSD/dist: 0.098; TD: 6504; p90: 38; p50: 18; complete: 0

80%





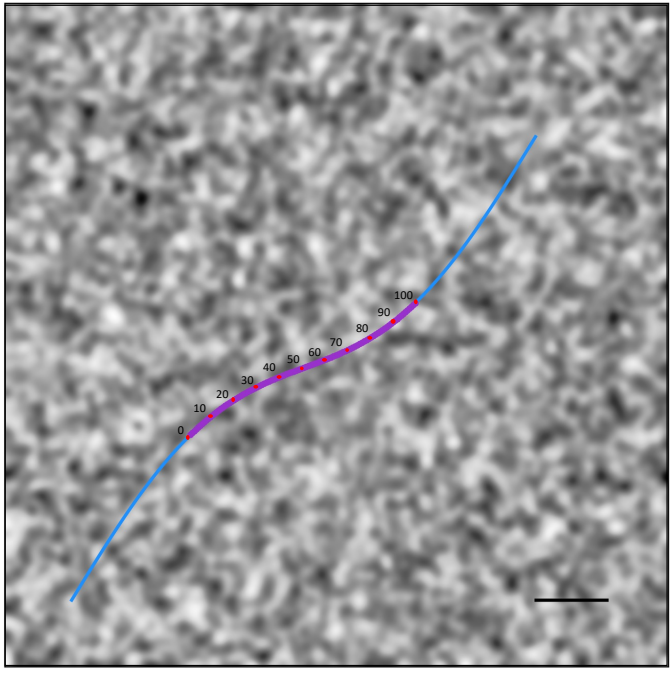


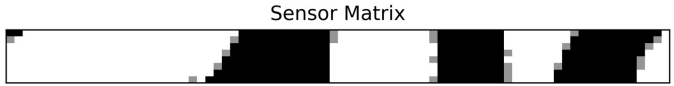


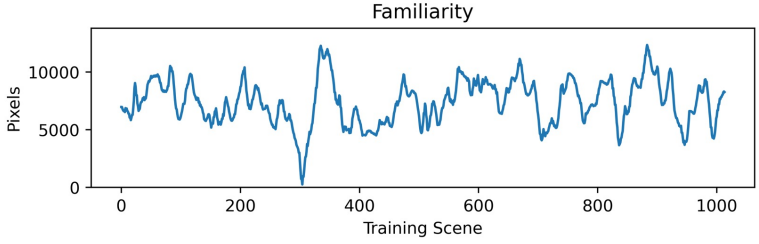
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

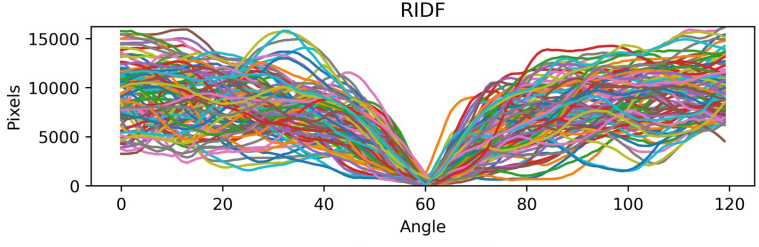
Navigation stats: RMSD error: 162.67; RMSD/dist: 0.407; TD: 5407; p90: 38; p50: 18; complete: 0

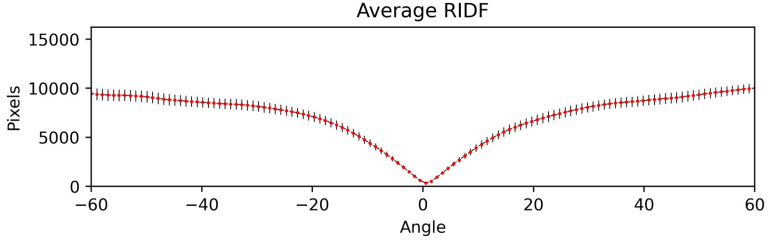
100%







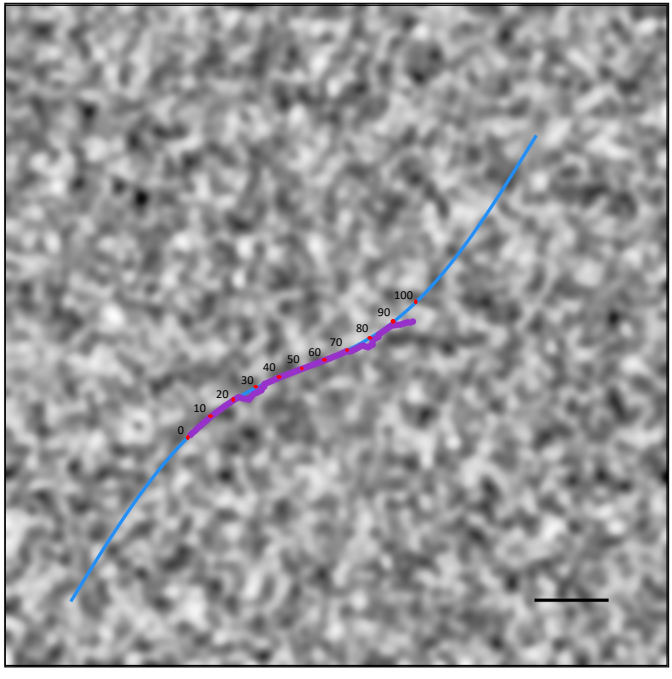


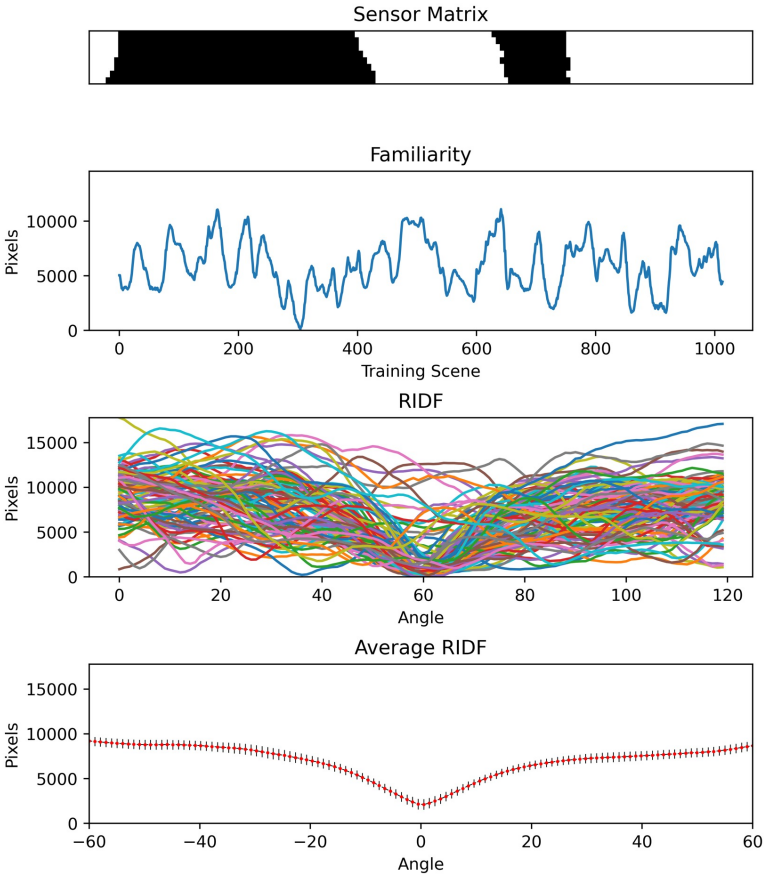


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 29.67; RMSD/dist: 0.074; TD: 6651; p90: 32; p50: 16; complete: 0

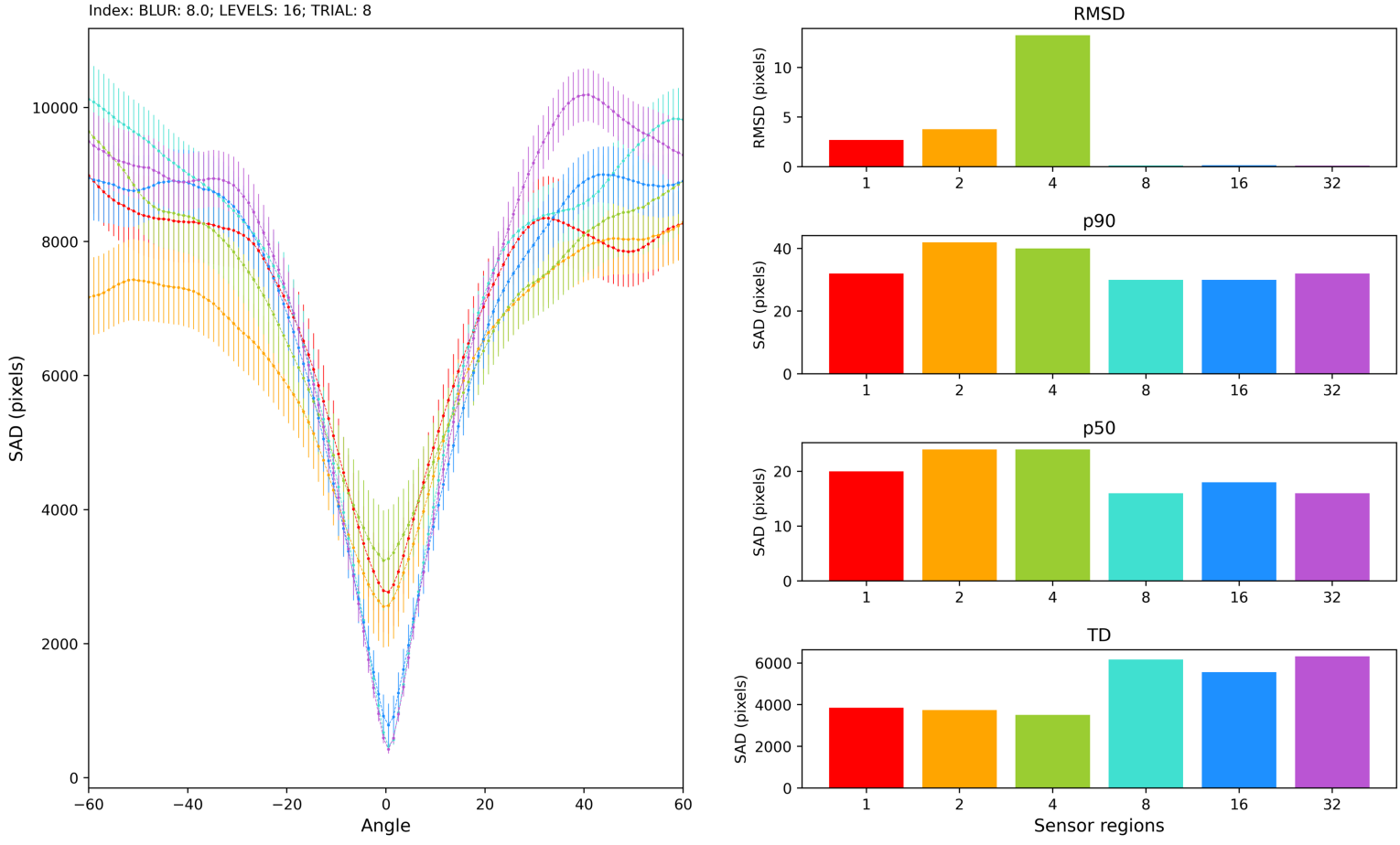
70%



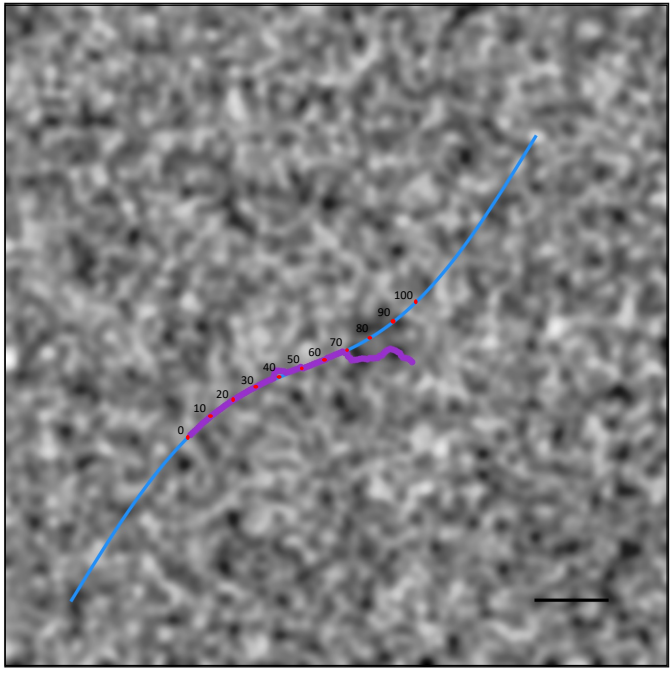


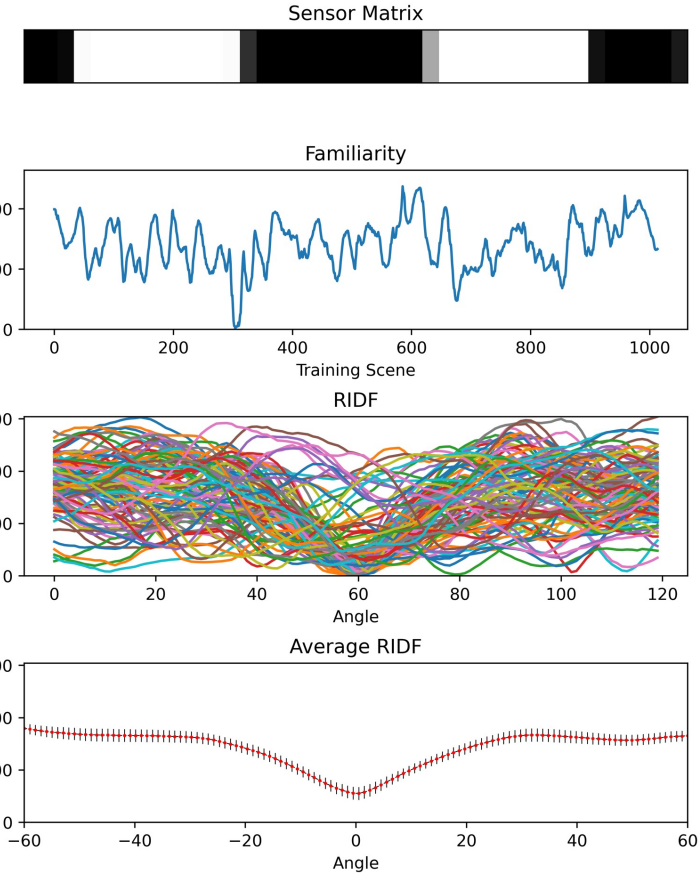
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 290.89; RMSD/dist: 0.727; TD: 4633; p90: 32; p50: 18; complete: 0


Index: BLUR: 8.0; LEVELS: 16; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

60%

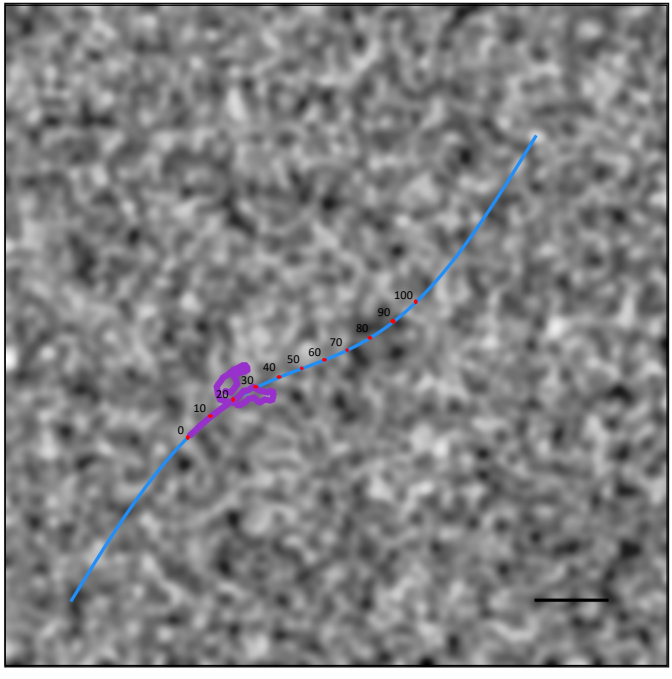


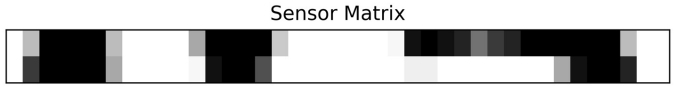


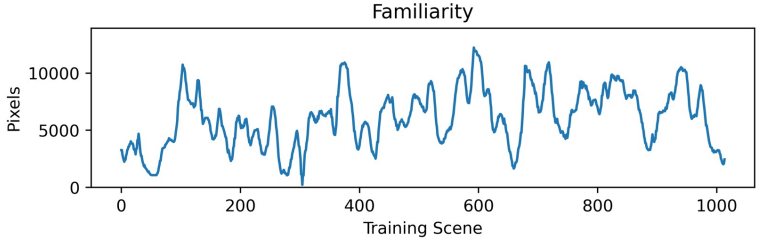
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

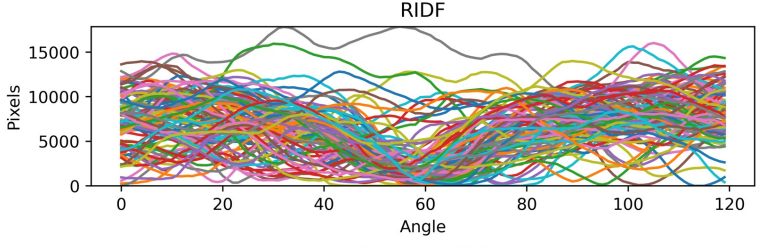
Navigation stats: RMSD error: 1076.56; RMSD/dist: 2.691; TD: 3854; p90: 32; p50: 20; complete: 0

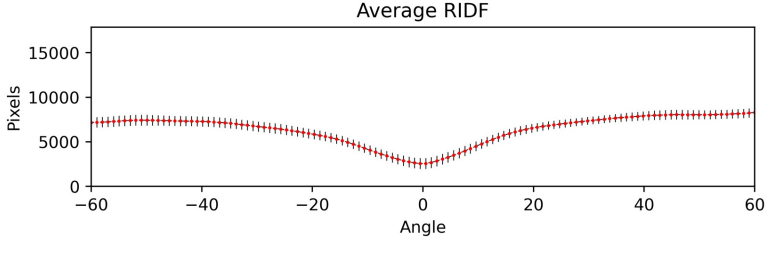
20%







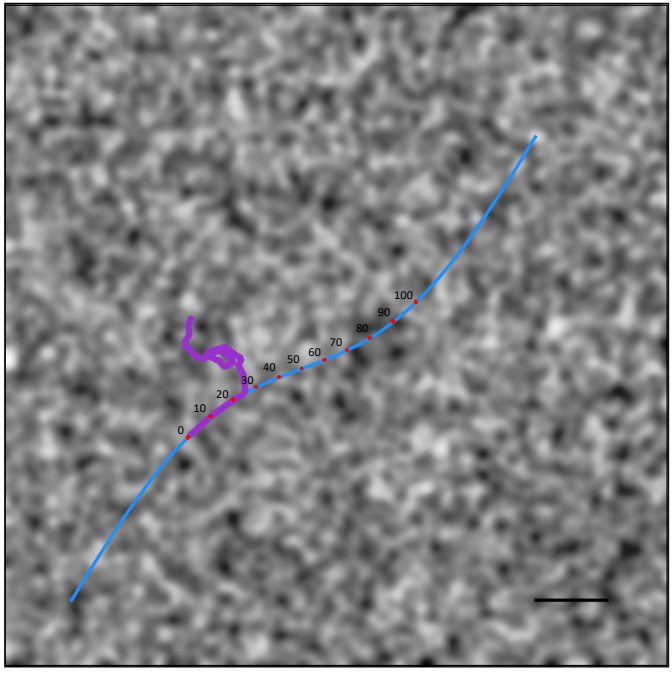


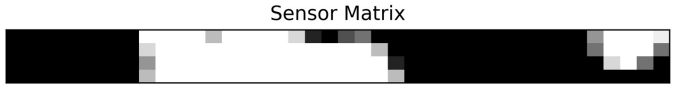


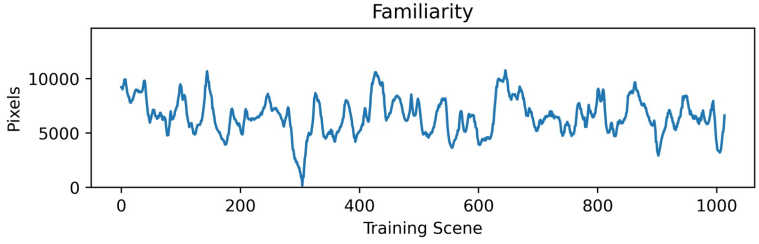
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

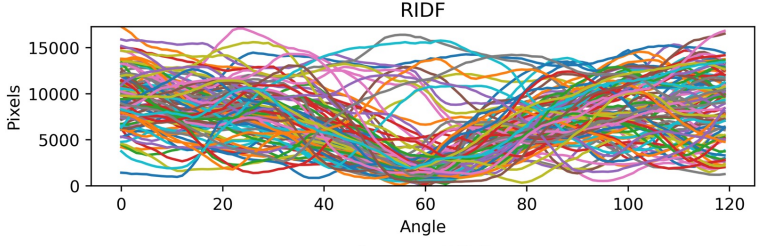
Navigation stats: RMSD error: 1507.46; RMSD/dist: 3.769; TD: 3738; p90: 42; p50: 24; complete: 0

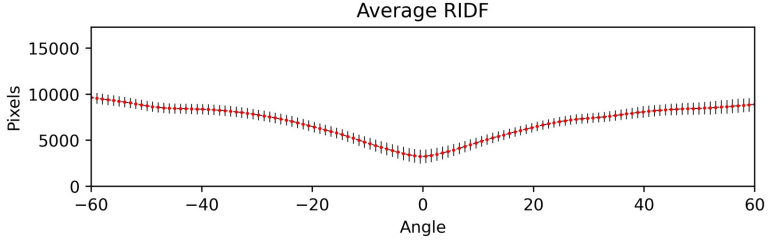
20%







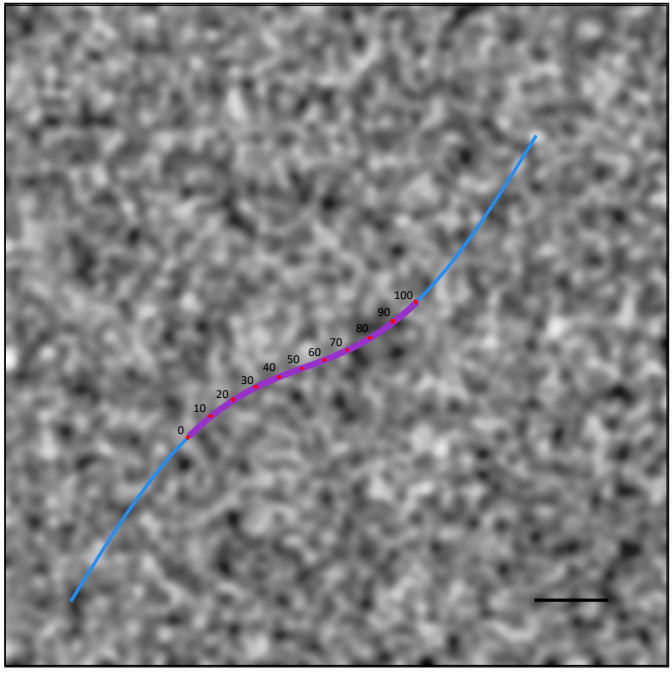


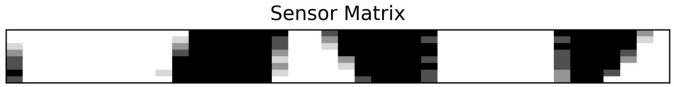


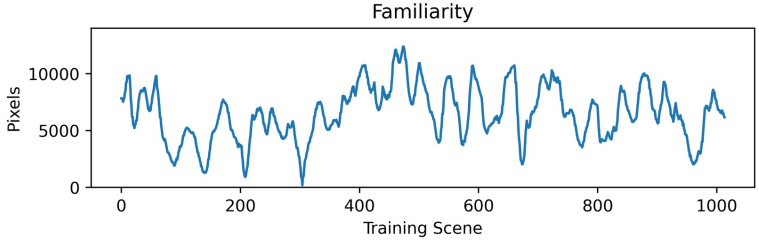
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

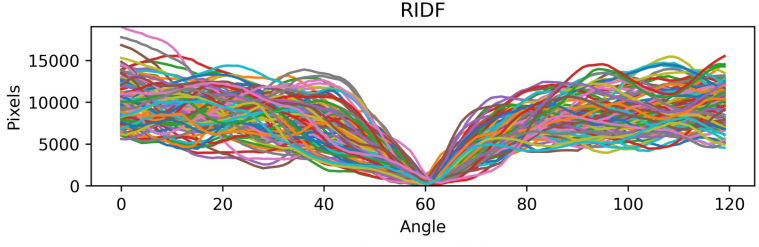
Navigation stats: RMSD error: 5299.96; RMSD/dist: 13.250; TD: 3511; p90: 40; p50: 24; complete: 0

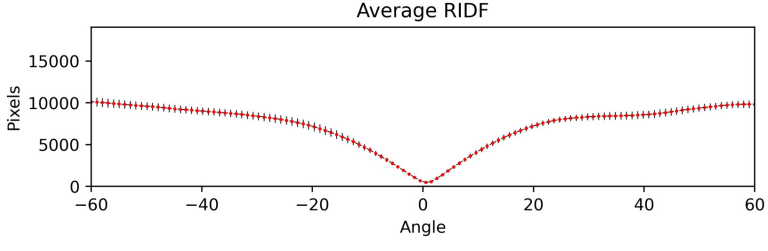
100%







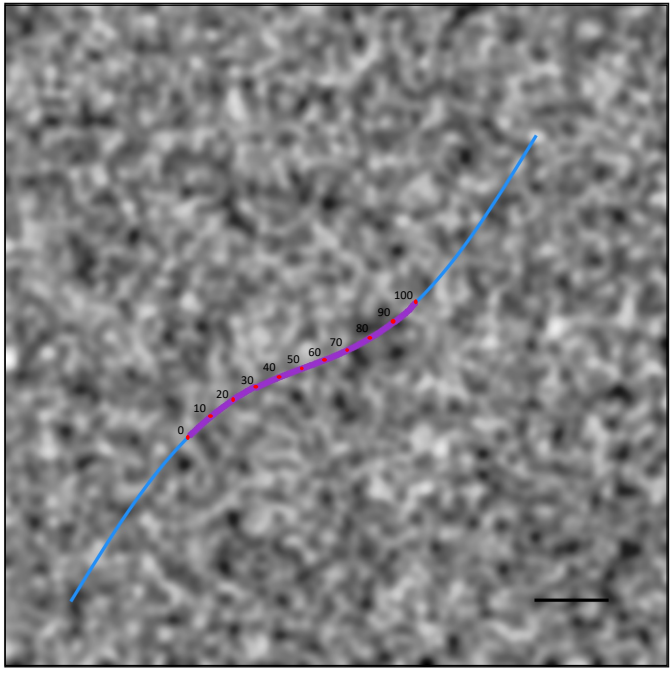


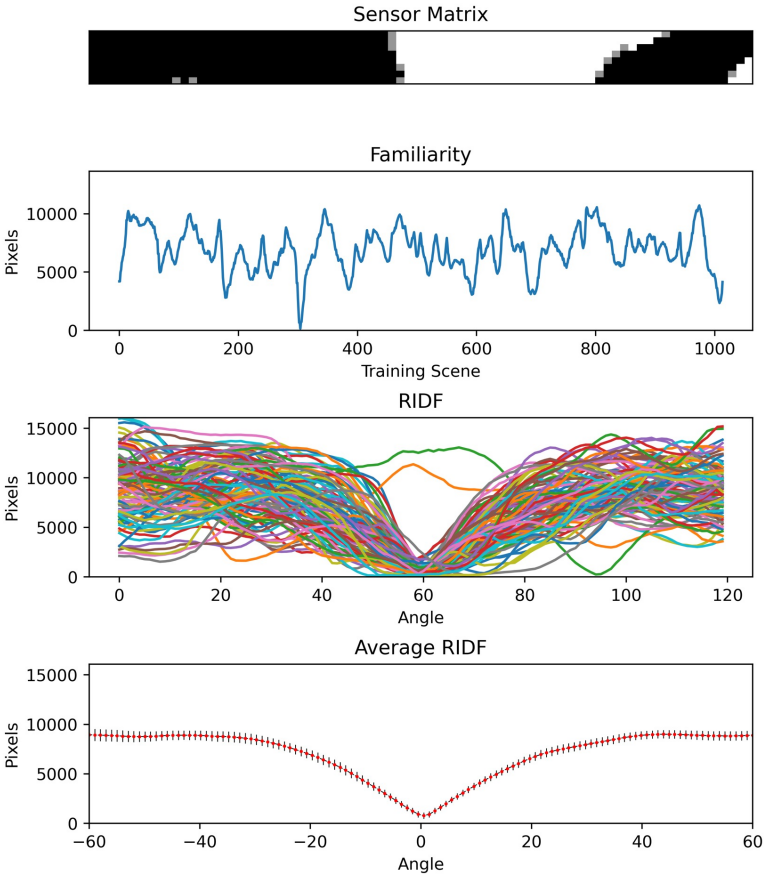


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 47.54; RMSD/dist: 0.119; TD: 6165; p90: 30; p50: 16; complete: 0

100%

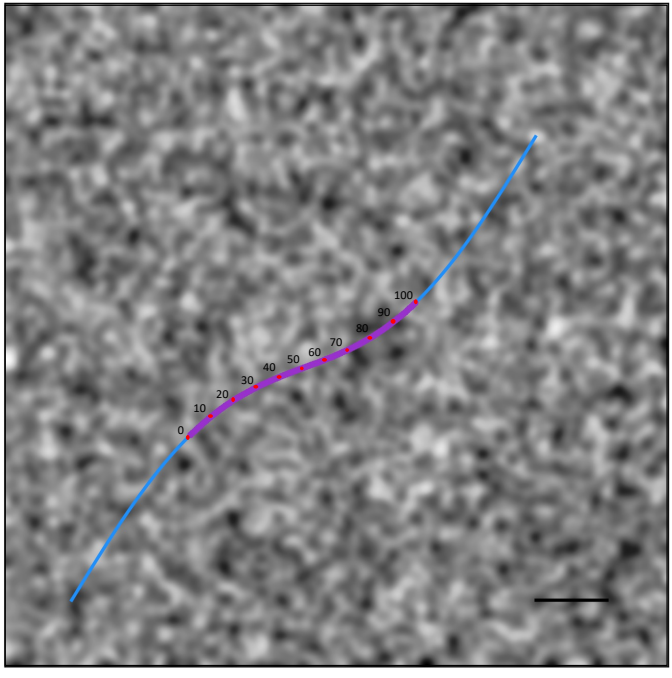


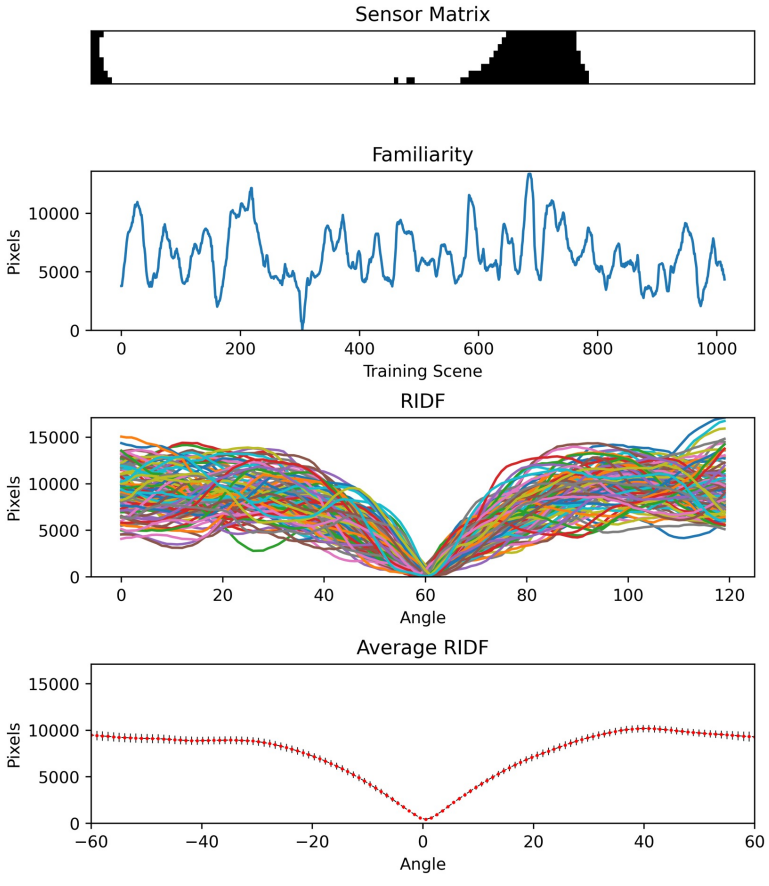


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 53.92; RMSD/dist: 0.135; TD: 5564; p90: 30; p50: 18; complete: 0

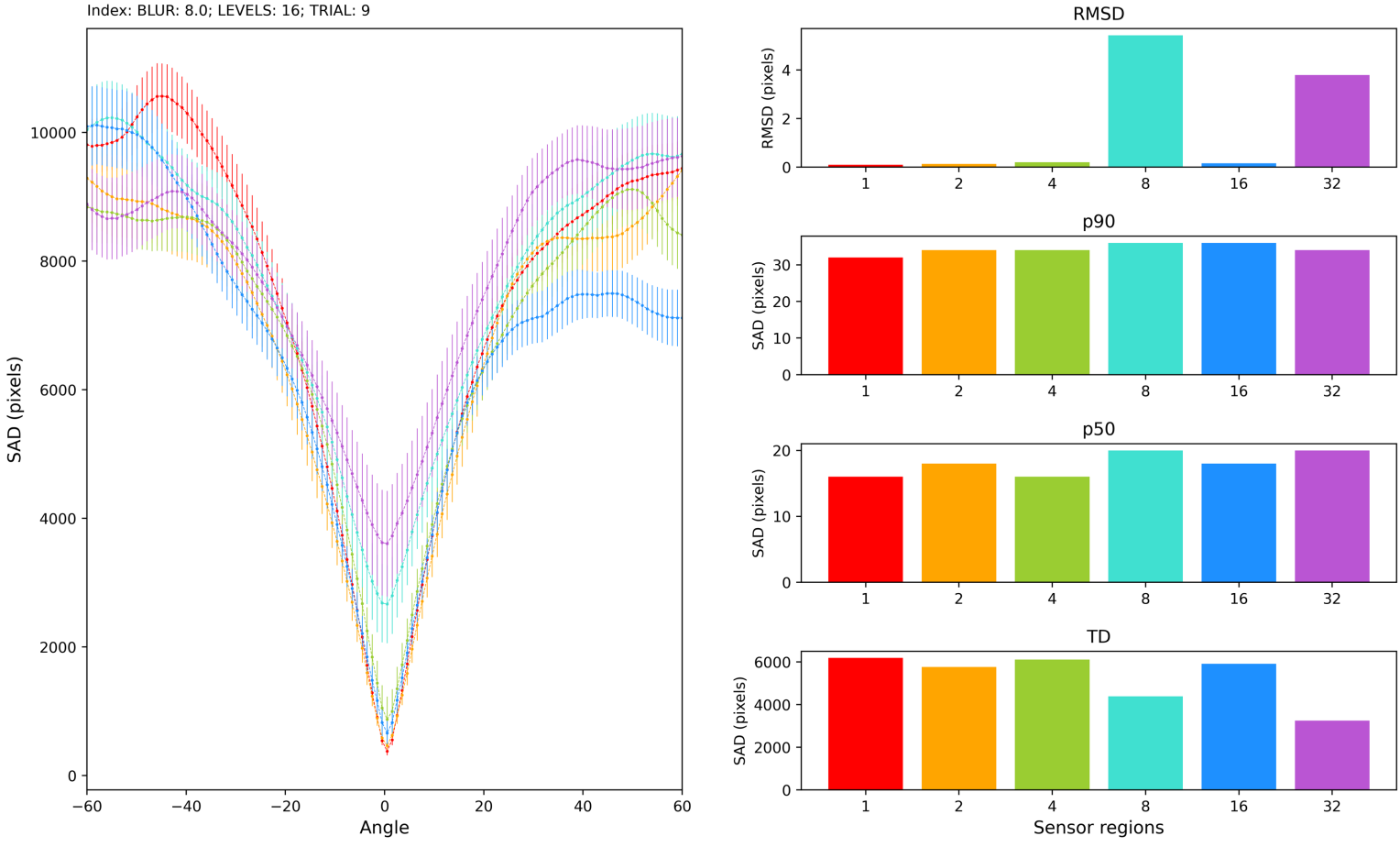
100%



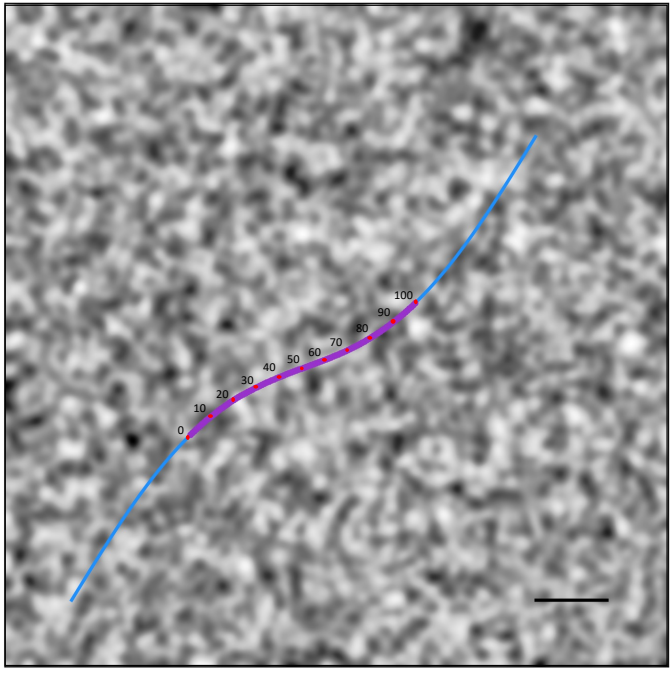


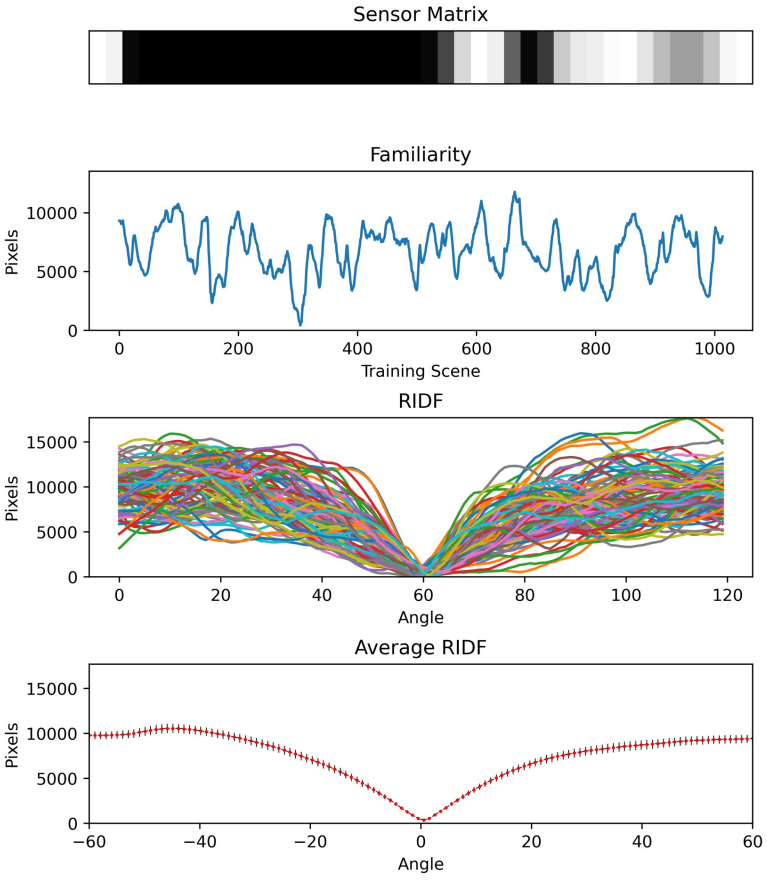
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 35.95; RMSD/dist: 0.090; TD: 6314; p90: 32; p50: 16; complete: 0


Index: BLUR: 8.0; LEVELS: 16; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

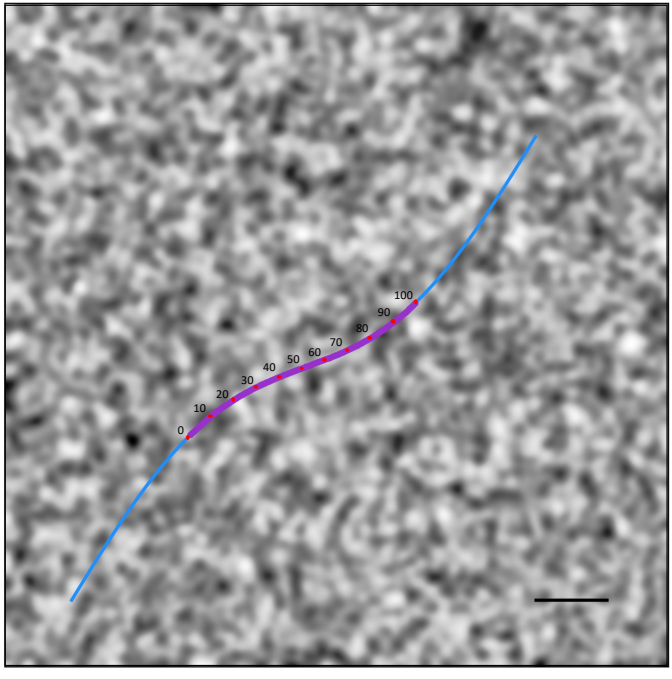


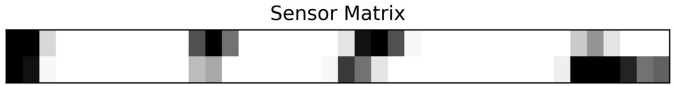


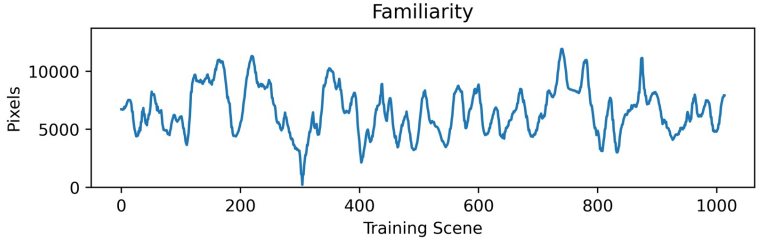
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

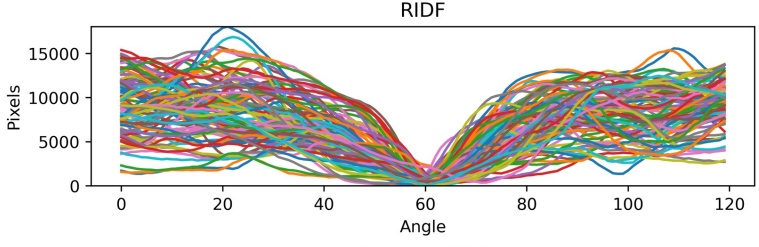
Navigation stats: RMSD error: 37.18; RMSD/dist: 0.093; TD: 6187; p90: 32; p50: 16; complete: 0

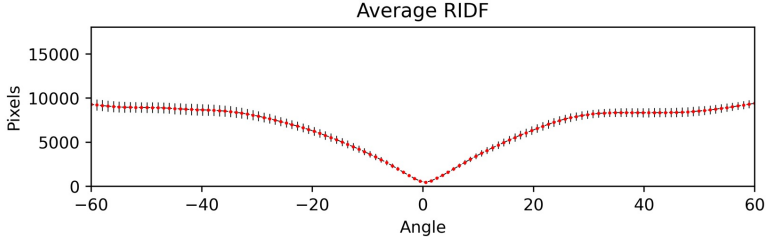
100%







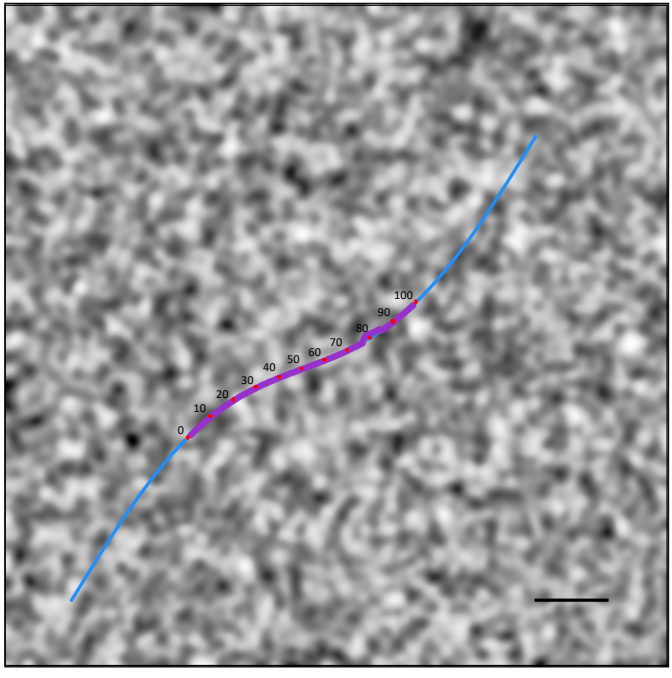


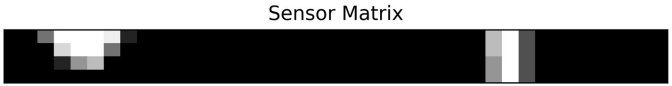


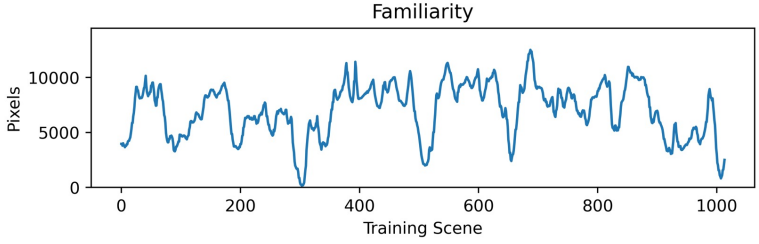
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

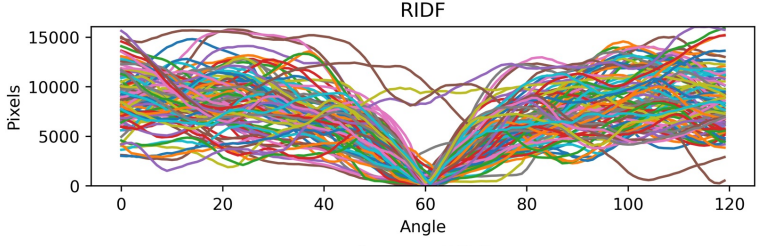
Navigation stats: RMSD error: 52.49; RMSD/dist: 0.131; TD: 5768; p90: 34; p50: 18; complete: 0

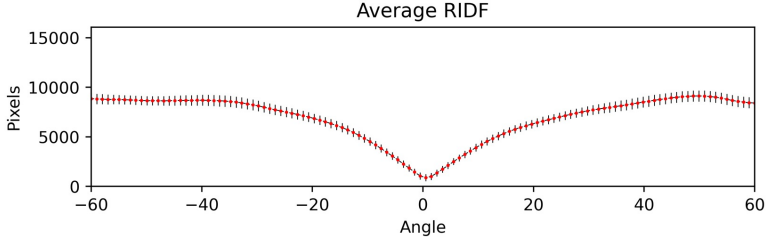
90%







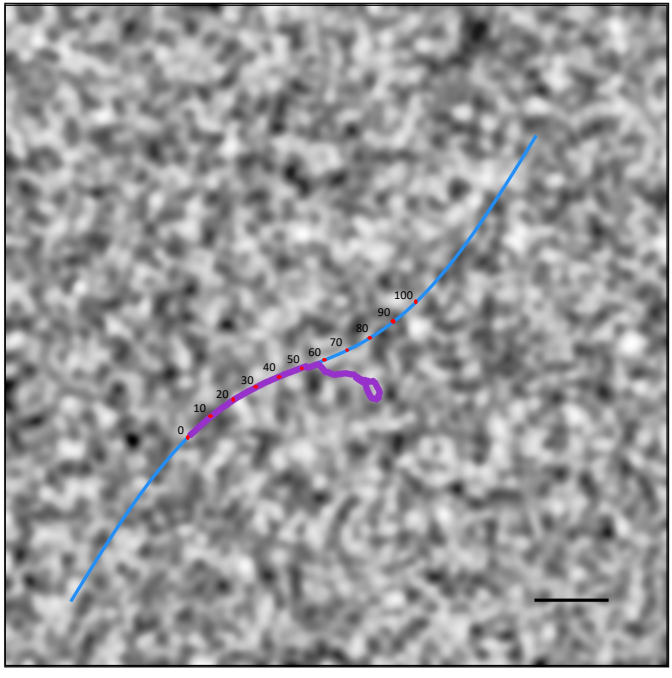


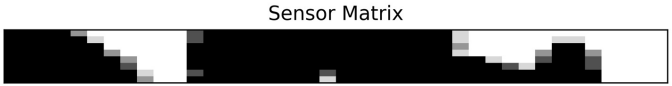


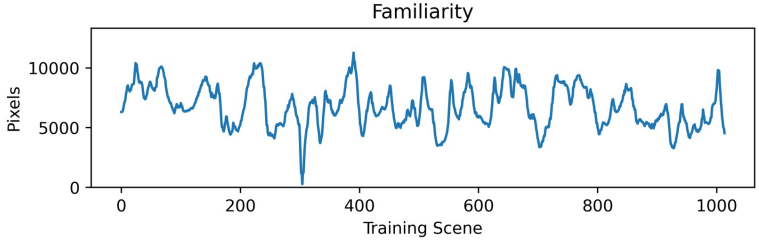
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

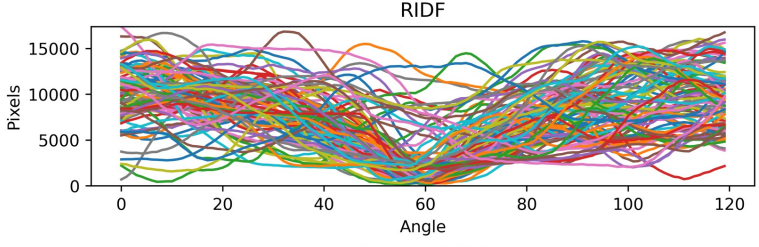
Navigation stats: RMSD error: 77.32; RMSD/dist: 0.193; TD: 6116; p90: 34; p50: 16; complete: 0

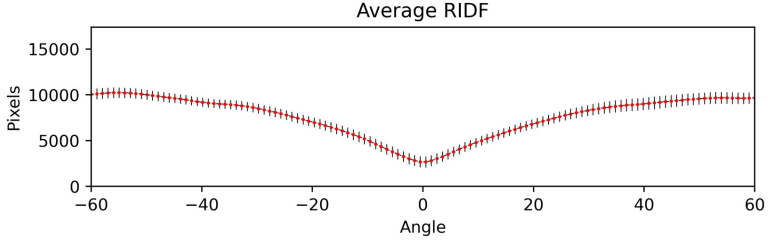
50%







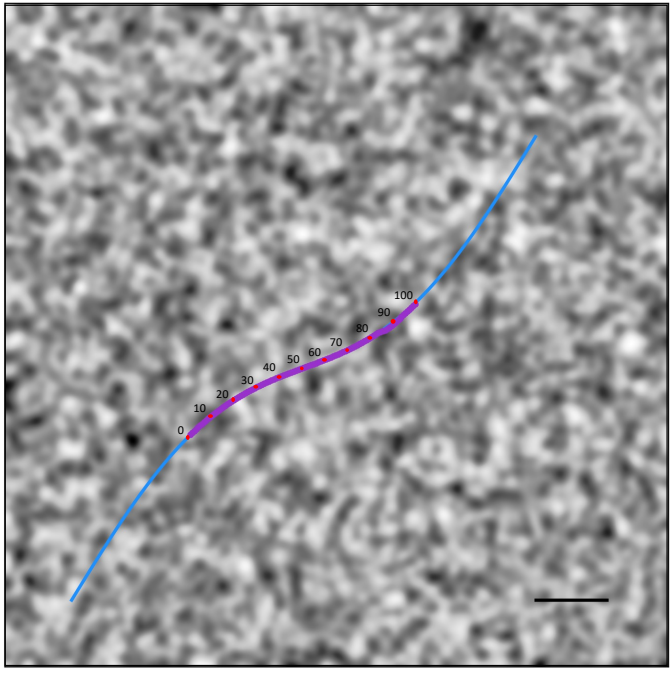


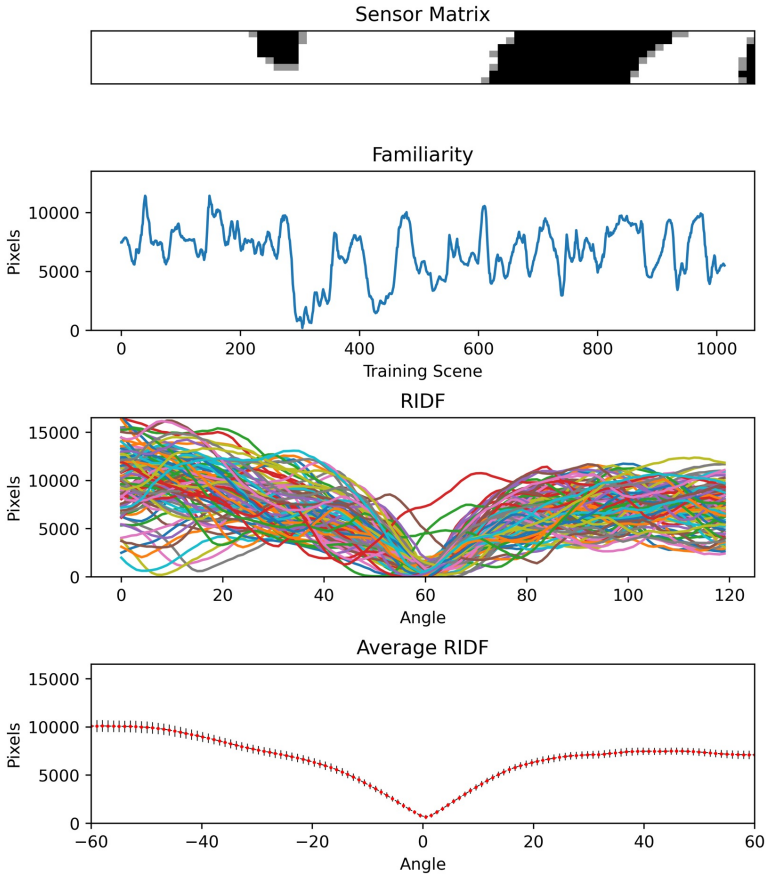


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 2170.73; RMSD/dist: 5.427; TD: 4390; p90: 36; p50: 20; complete: 0

90%

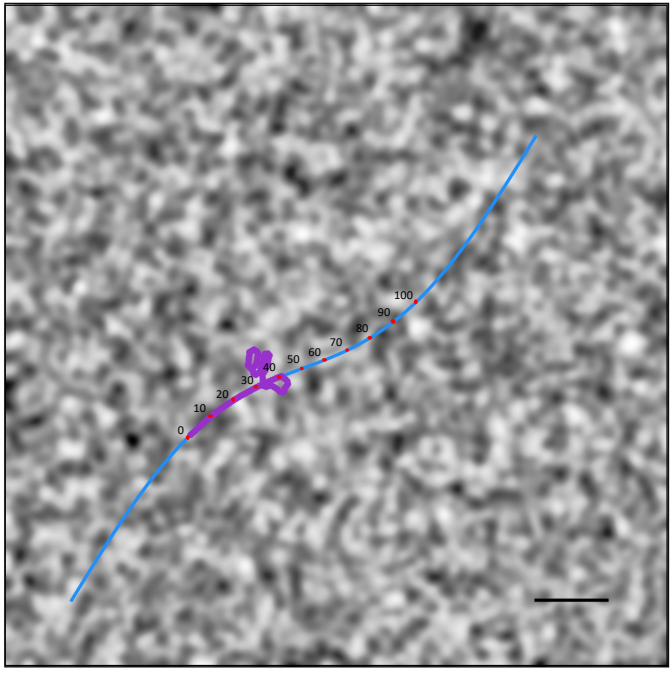


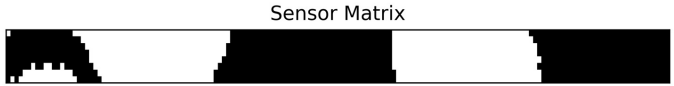


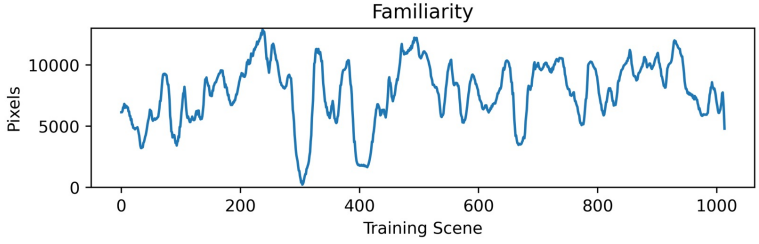
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

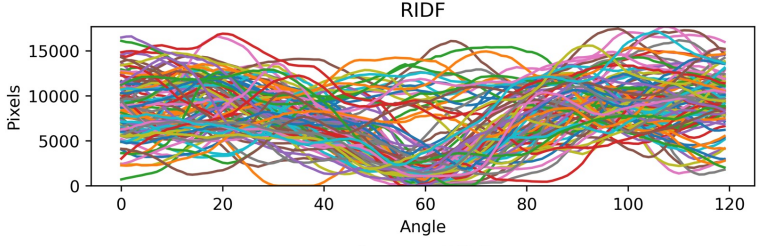
Navigation stats: RMSD error: 62.92; RMSD/dist: 0.157; TD: 5915; p90: 36; p50: 18; complete: 0

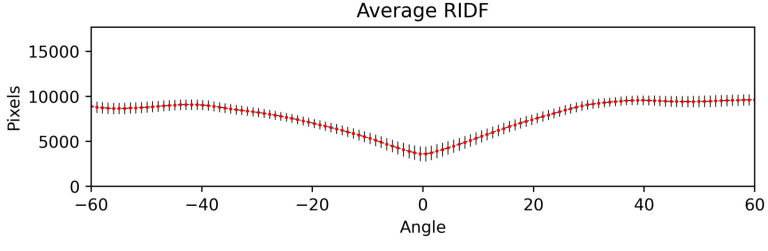
40%





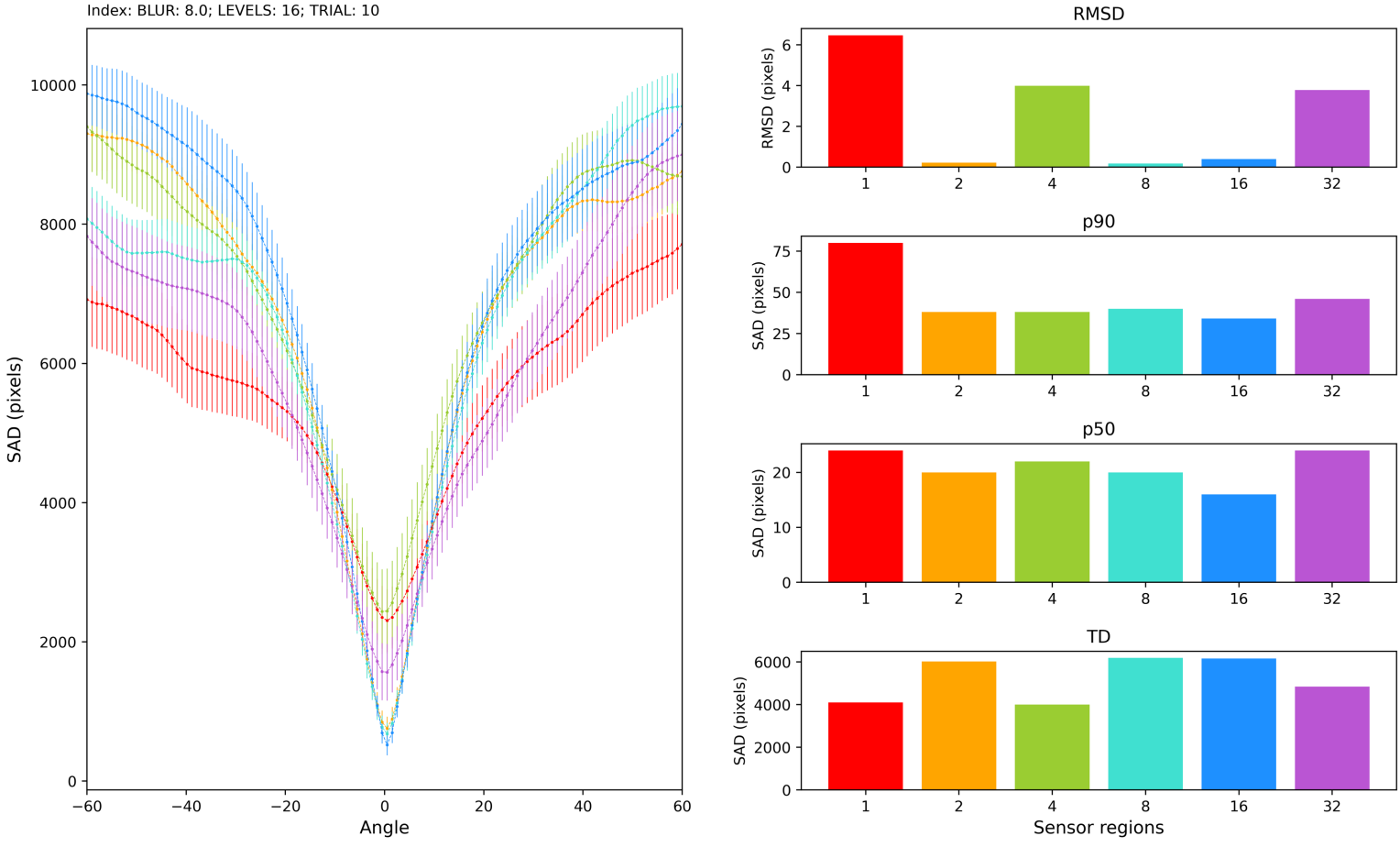




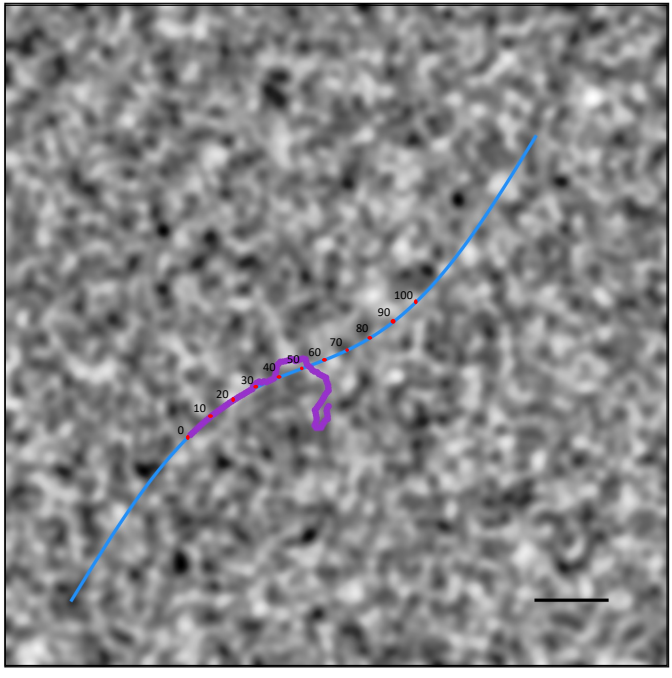


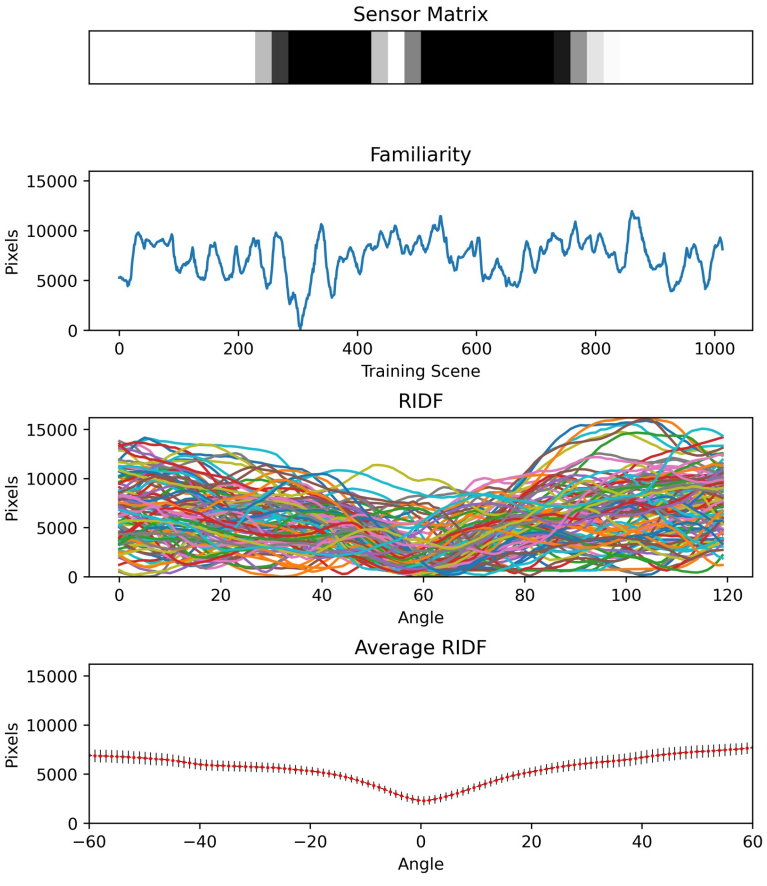
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 1516.47; RMSD/dist: 3.791; TD: 3247; p90: 34; p50: 20; complete: 0


Index: BLUR: 8.0; LEVELS: 16; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

30%

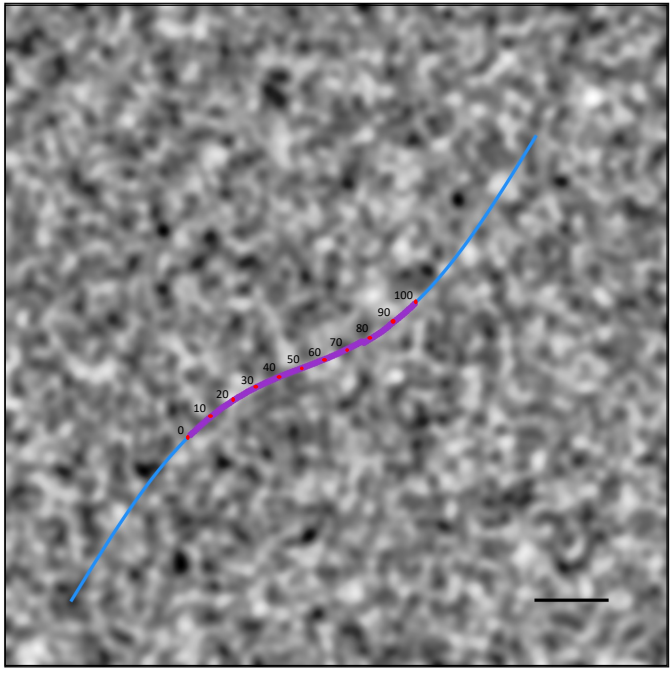


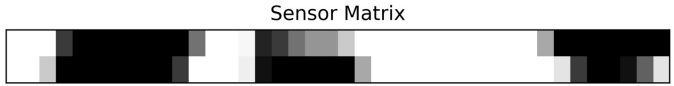


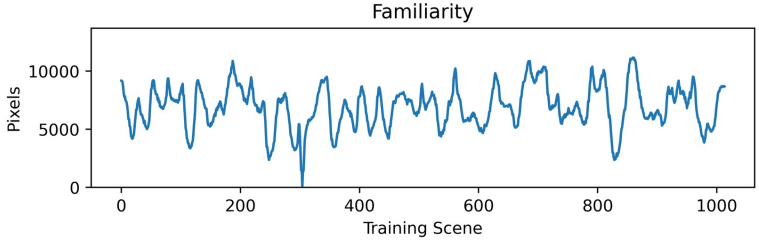
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

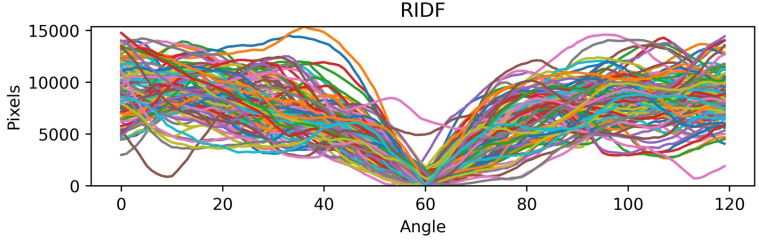
Navigation stats: RMSD error: 2590.41; RMSD/dist: 6.476; TD: 4098; p90: 80; p50: 24; complete: 0

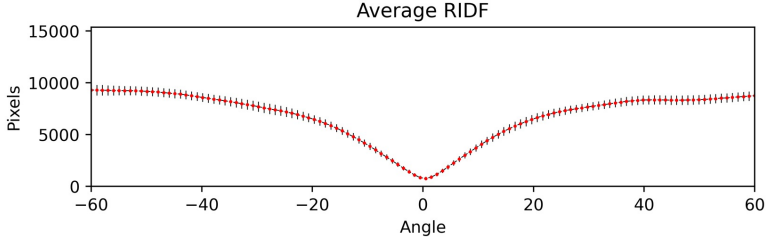
90%







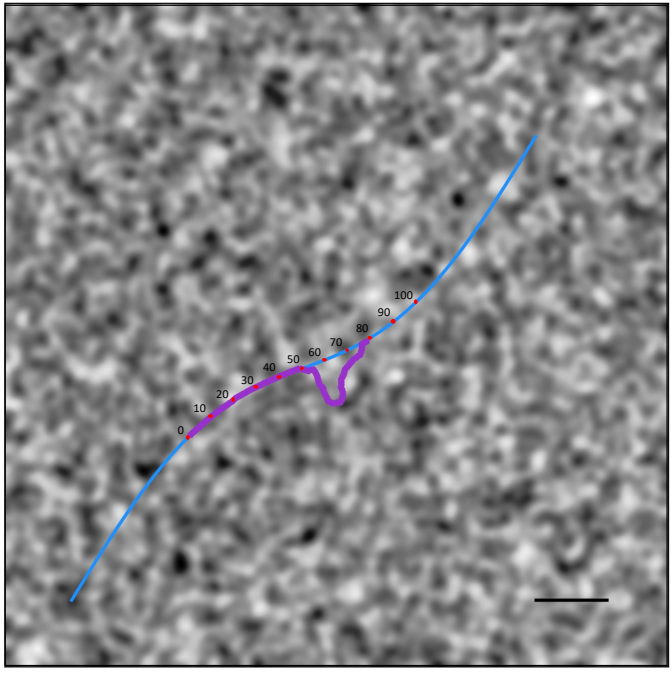


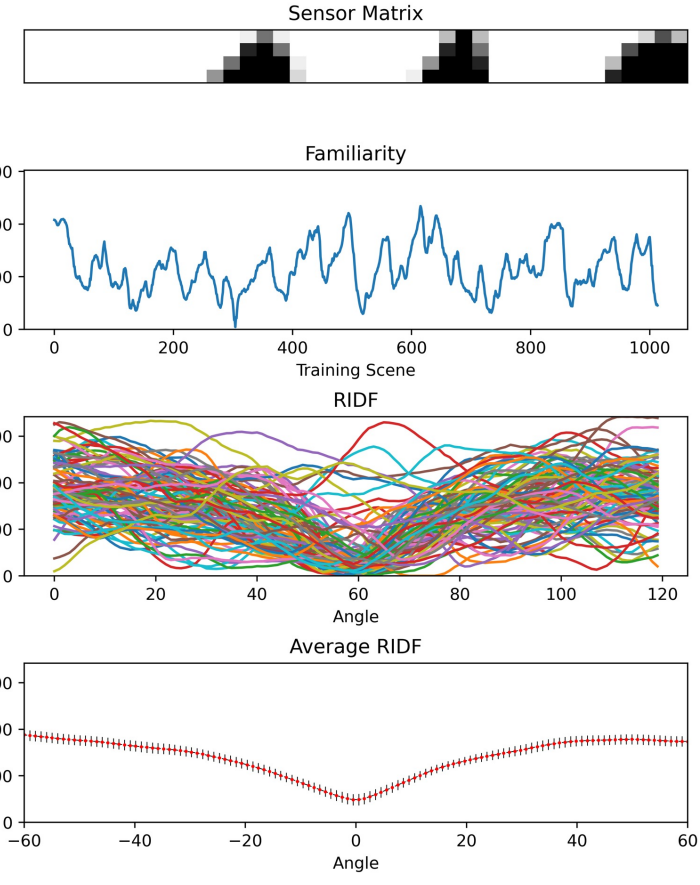


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 85.40; RMSD/dist: 0.214; TD: 6022; p90: 38; p50: 20; complete: 0

50%

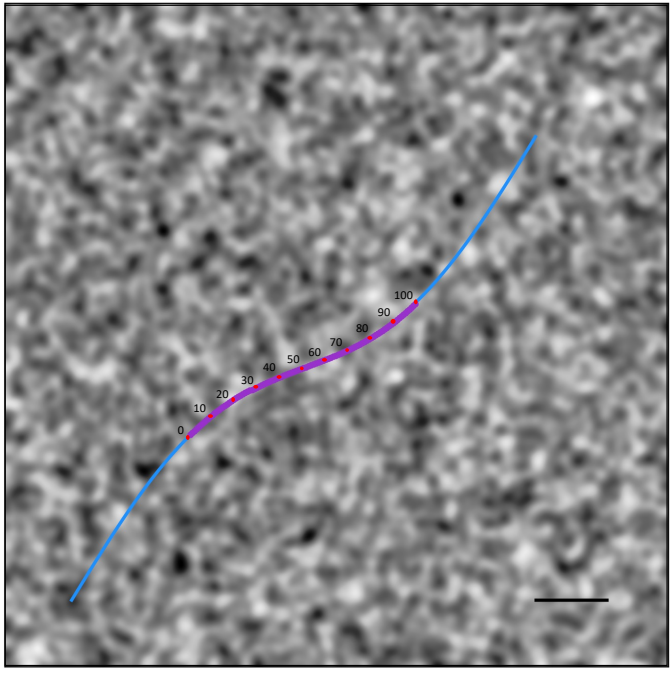


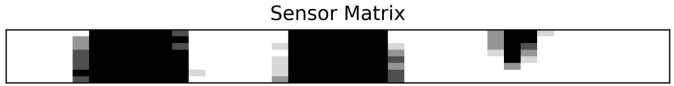


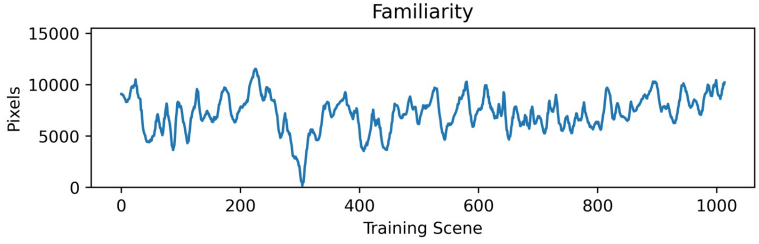
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

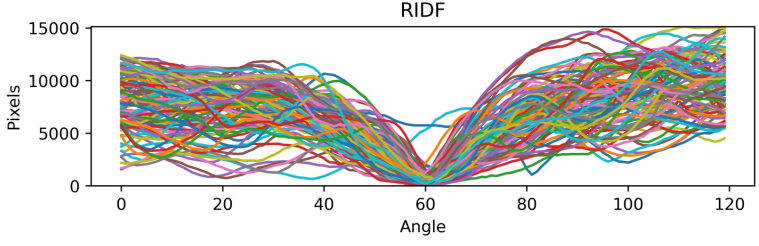
Navigation stats: RMSD error: 1597.63; RMSD/dist: 3.994; TD: 3993; p90: 38; p50: 22; complete: 0

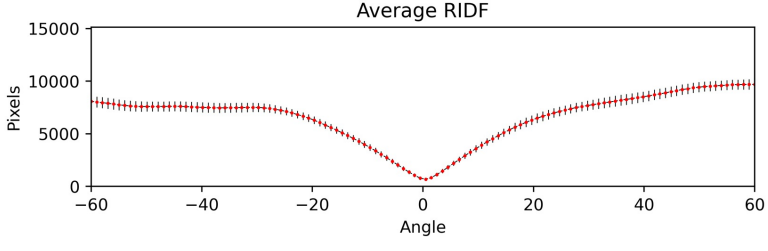
90%







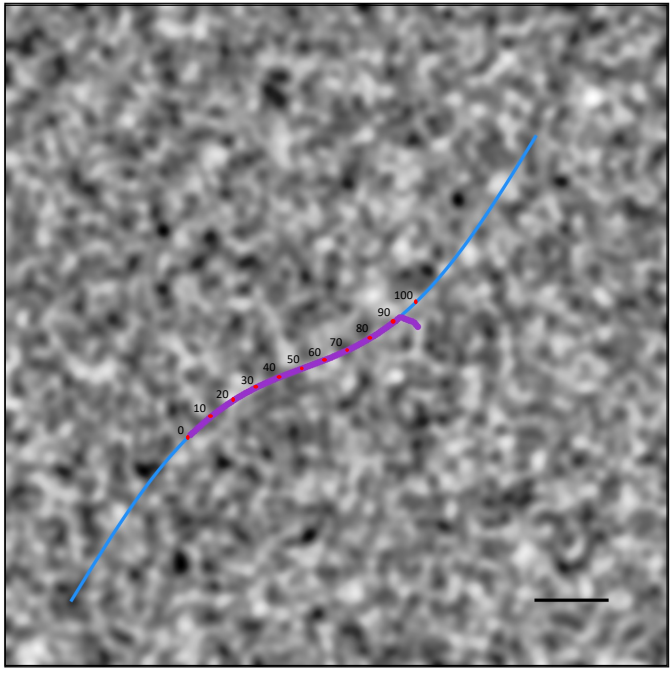


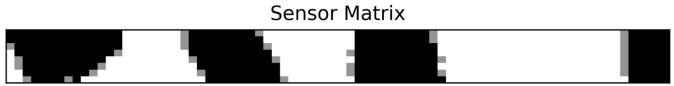


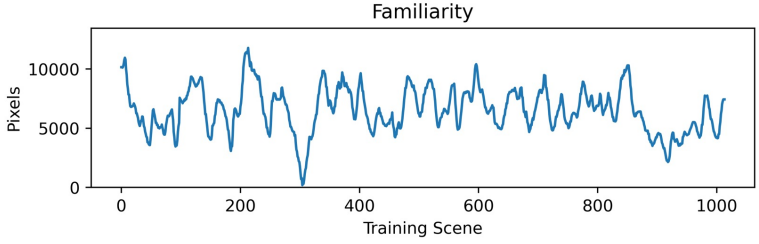
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

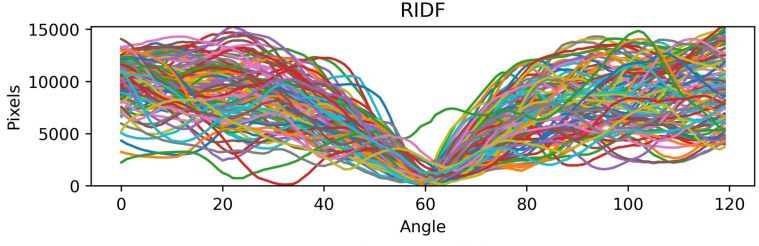
Navigation stats: RMSD error: 71.11; RMSD/dist: 0.178; TD: 6181; p90: 40; p50: 20; complete: 0

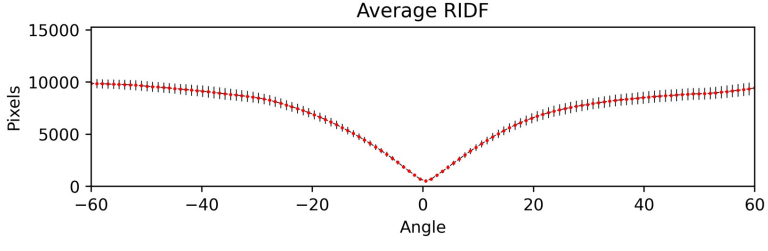
90%







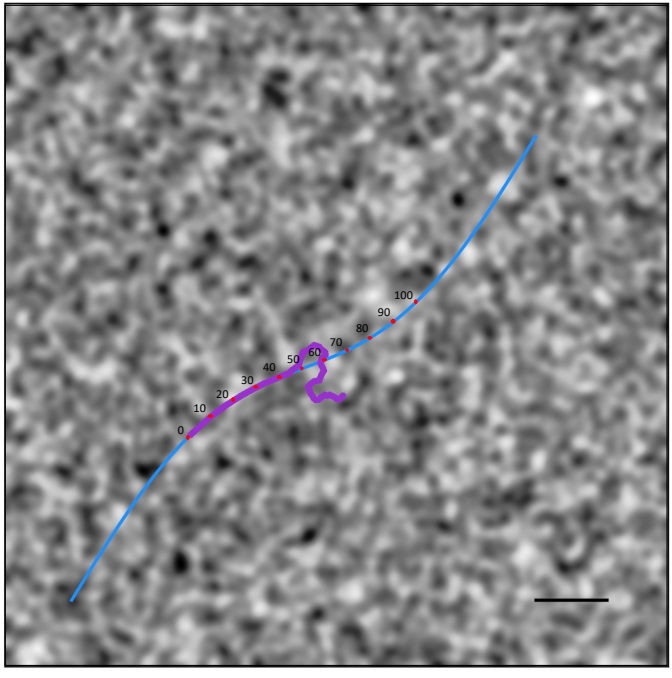


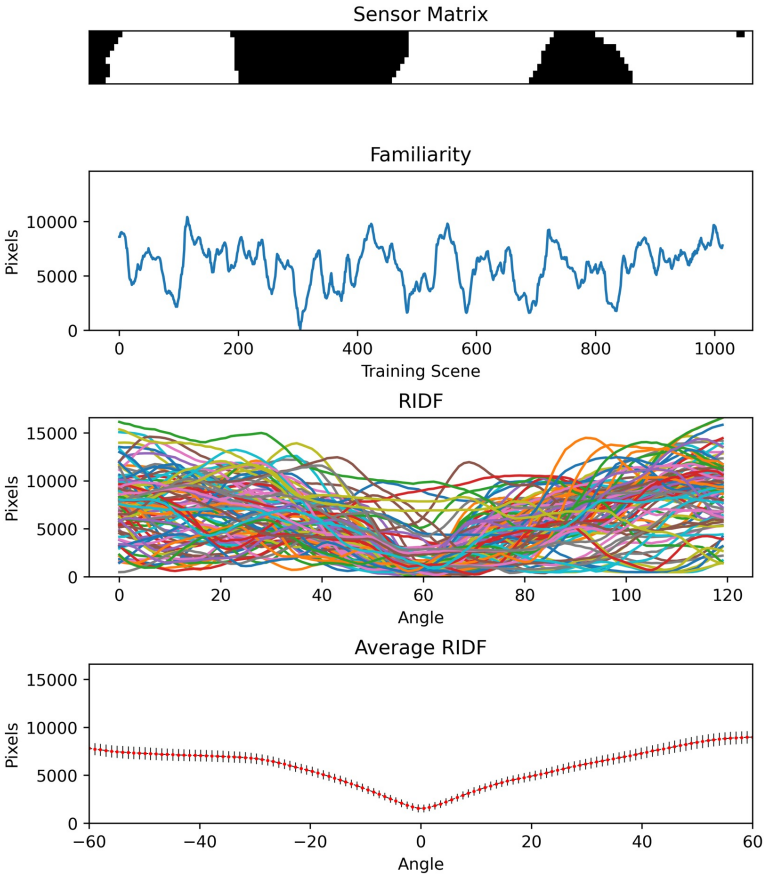


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 155.21; RMSD/dist: 0.388; TD: 6157; p90: 34; p50: 16; complete: 0

40%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 8; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 16; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 1513.72; RMSD/dist: 3.784; TD: 4837; p90: 46; p50: 24; complete: 0