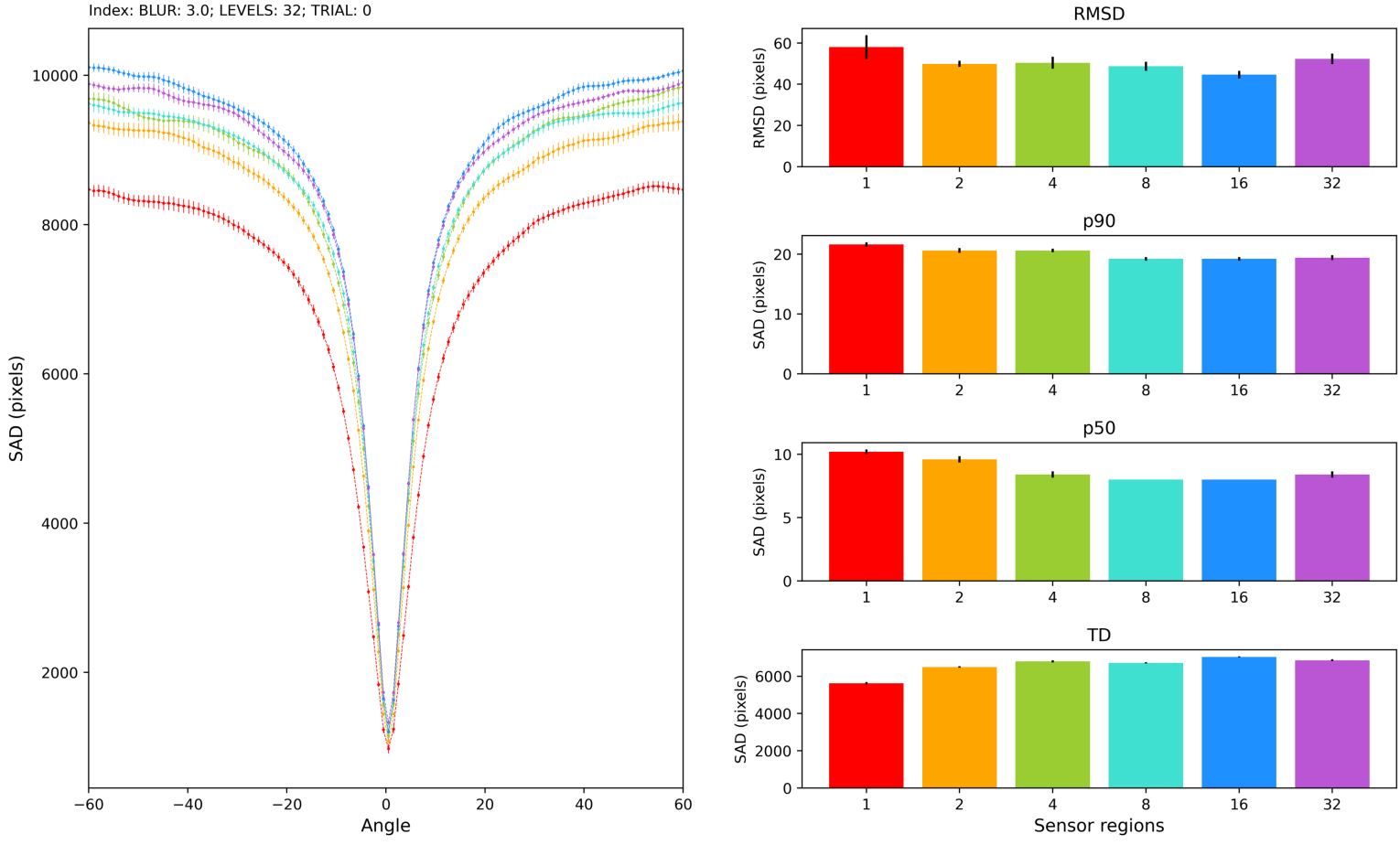
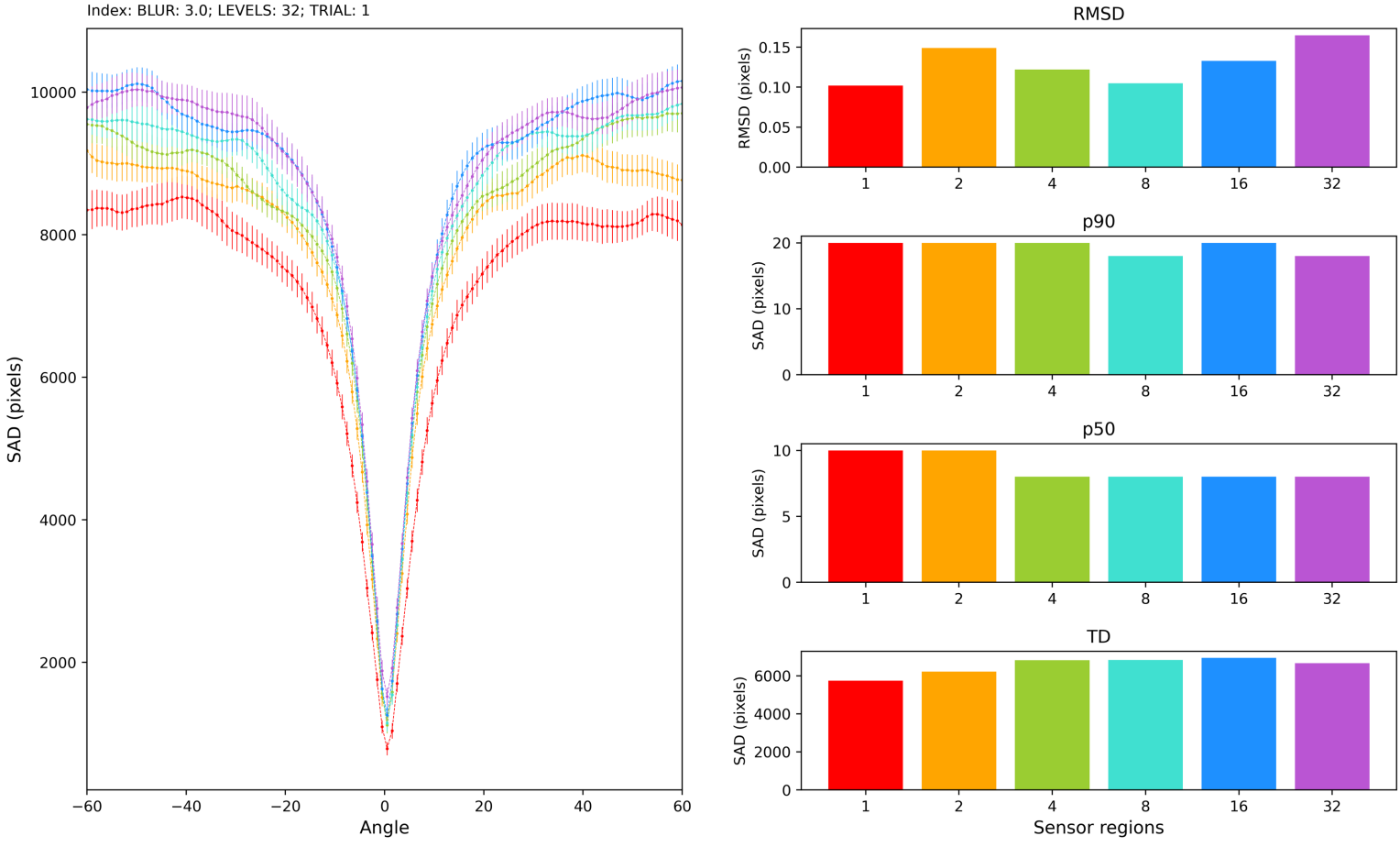
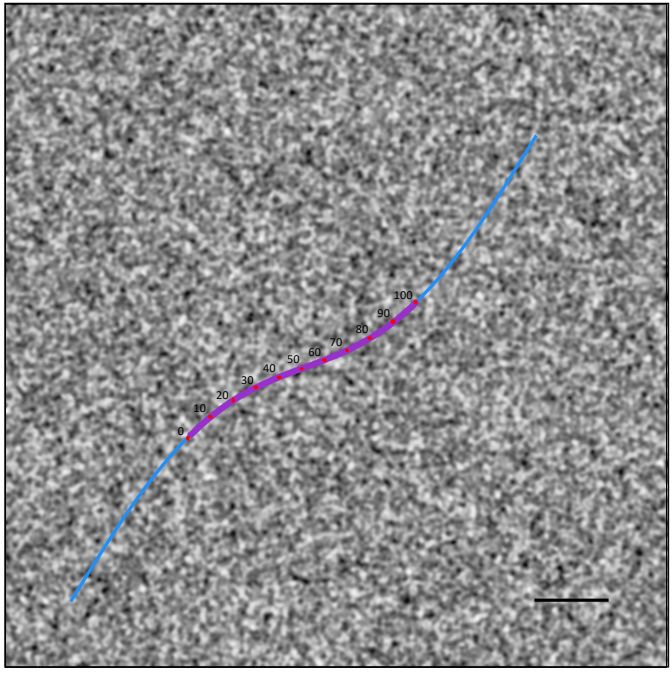
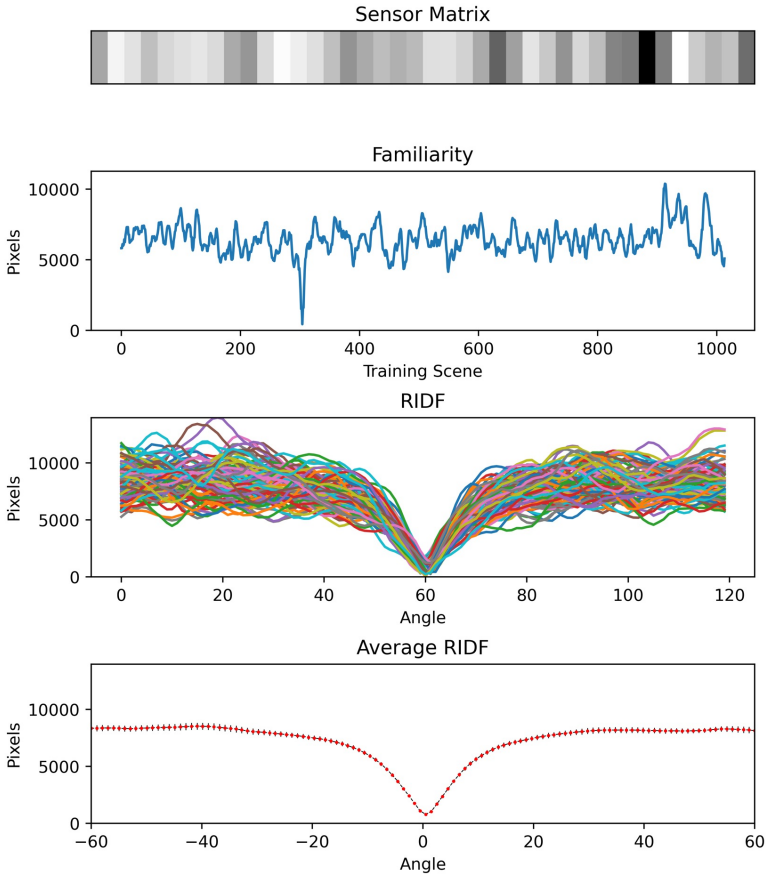

Index: BLUR: 3.0; LEVELS: 32; TRIAL: 0
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions


Index: BLUR: 3.0; LEVELS: 32; TRIAL: 1
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

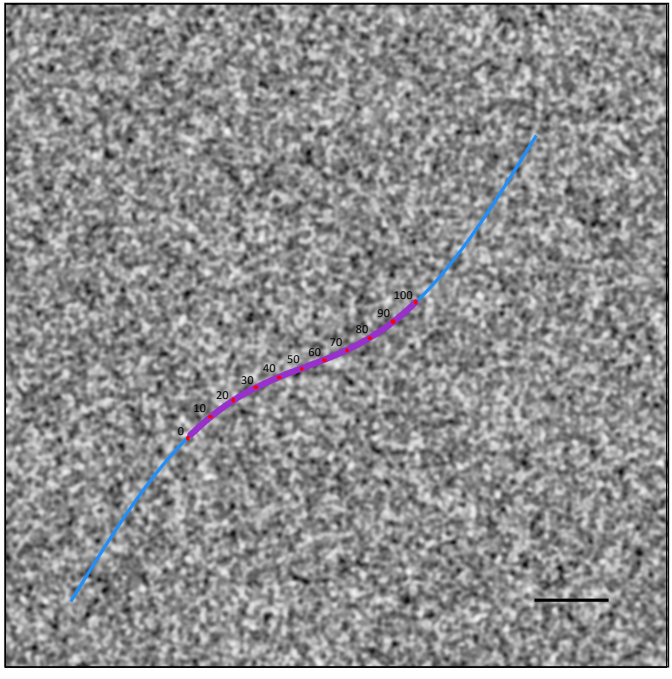


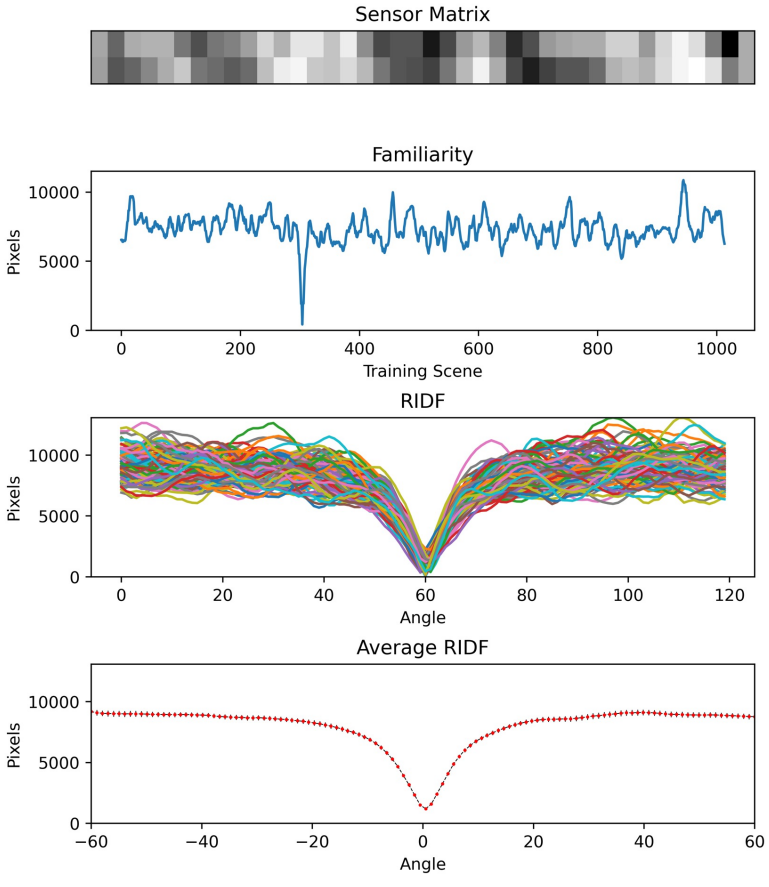


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 40.90; RMSD/dist: 0.102; TD: 5741; p90: 20; p50: 10; complete: 0

100%

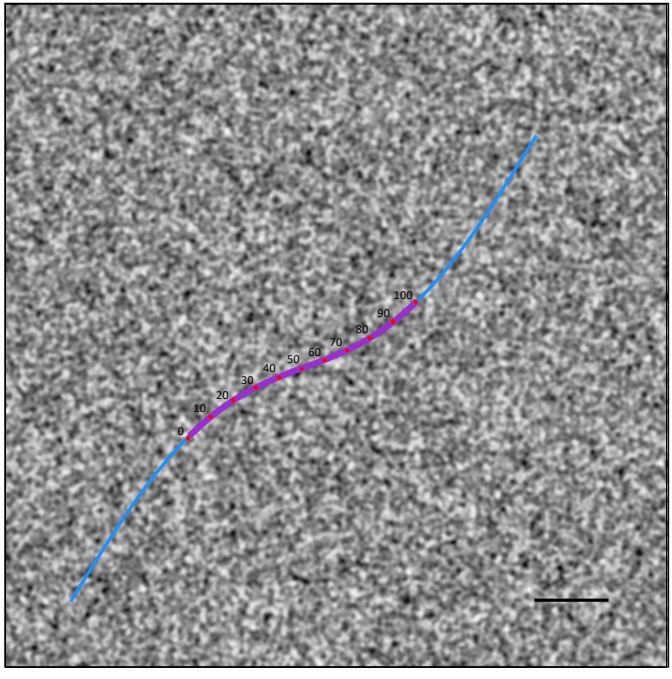


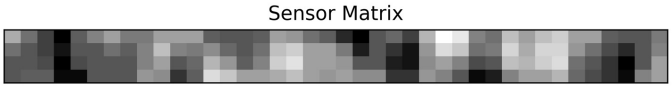


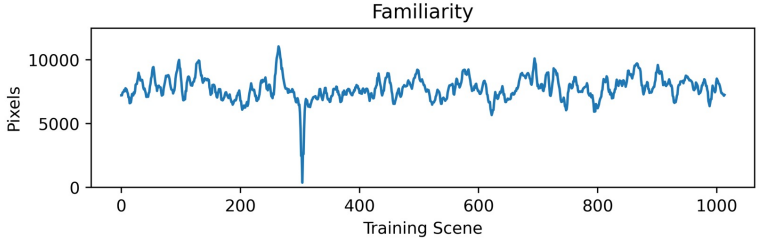
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

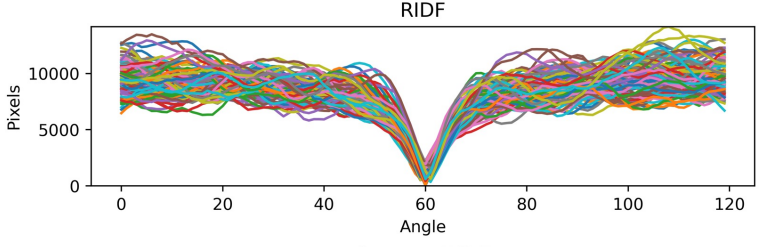
Navigation stats: RMSD error: 59.56; RMSD/dist: 0.149; TD: 6214; p90: 20; p50: 10; complete: 0

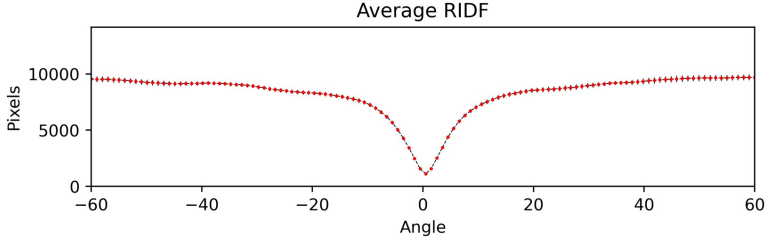
100%







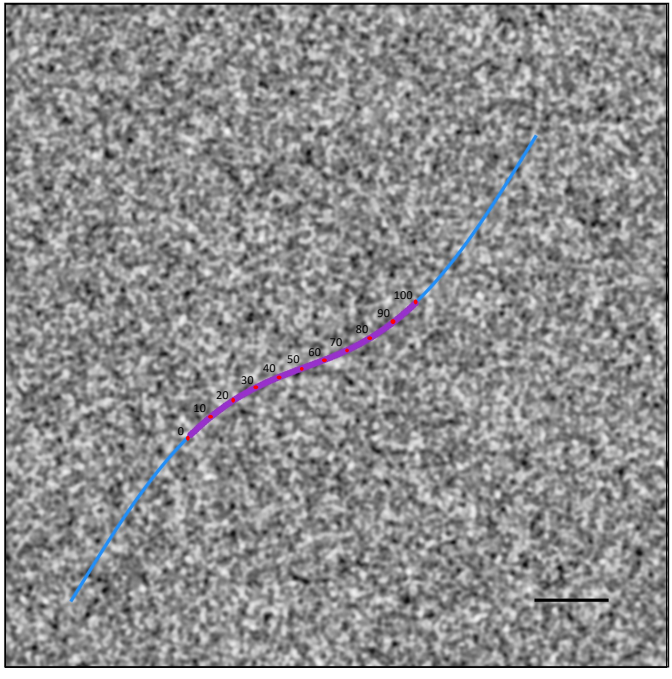


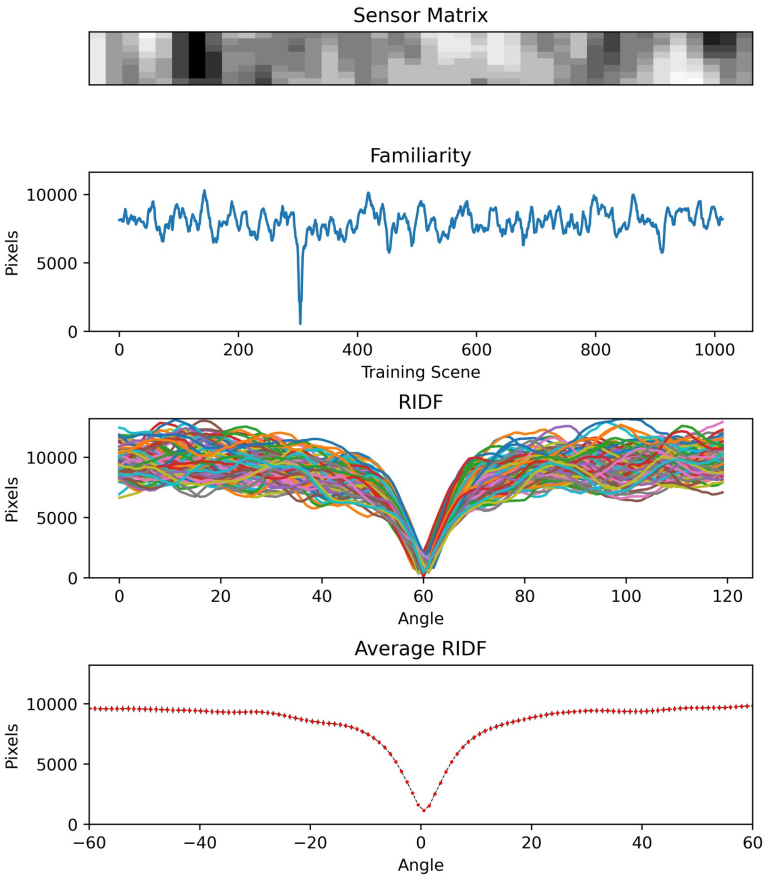


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 48.64; RMSD/dist: 0.122; TD: 6822; p90: 20; p50: 8; complete: 0

100%

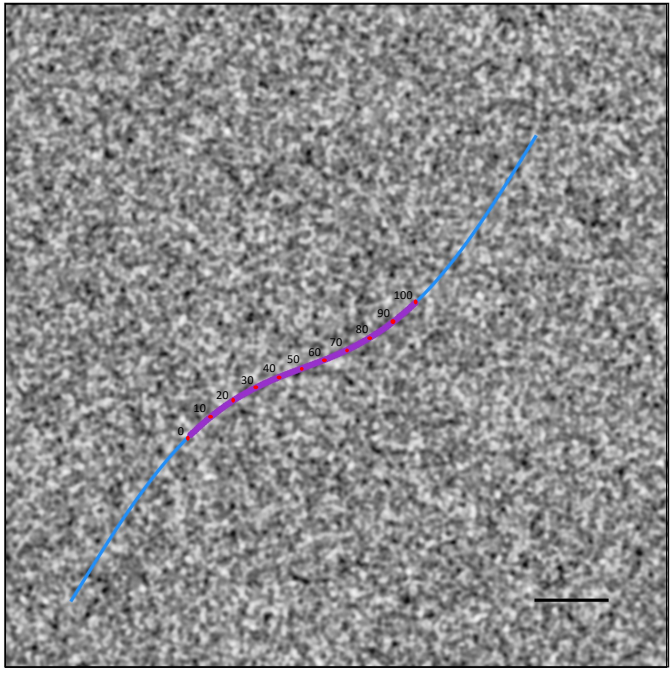


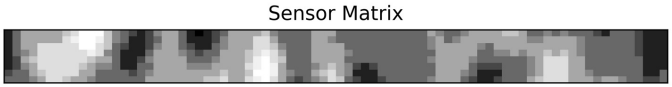


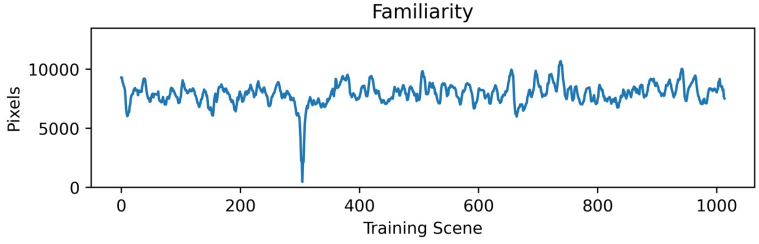
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

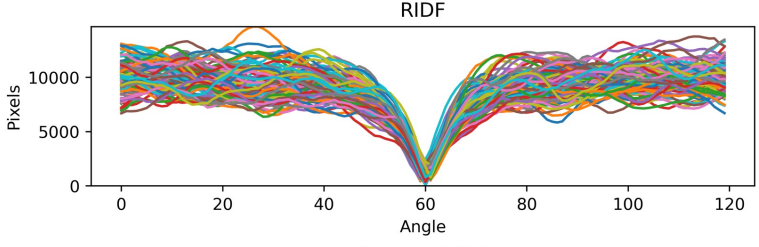
Navigation stats: RMSD error: 41.98; RMSD/dist: 0.105; TD: 6827; p90: 18; p50: 8; complete: 0

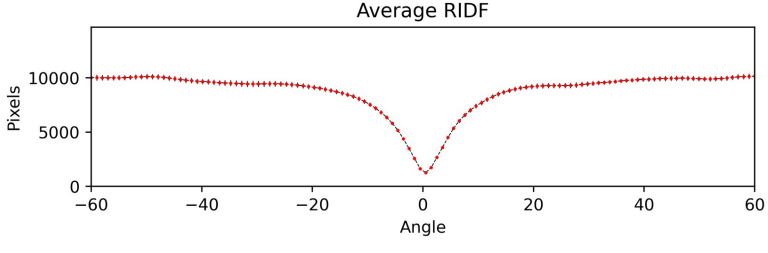
100%







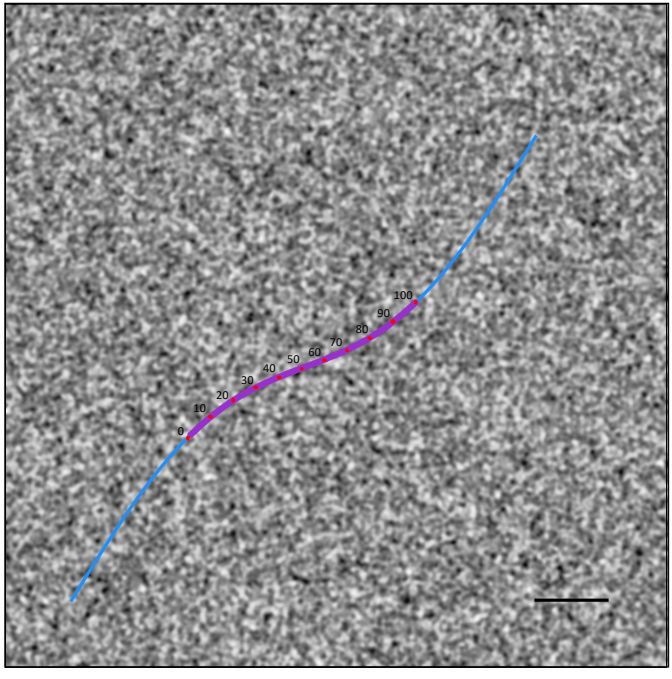


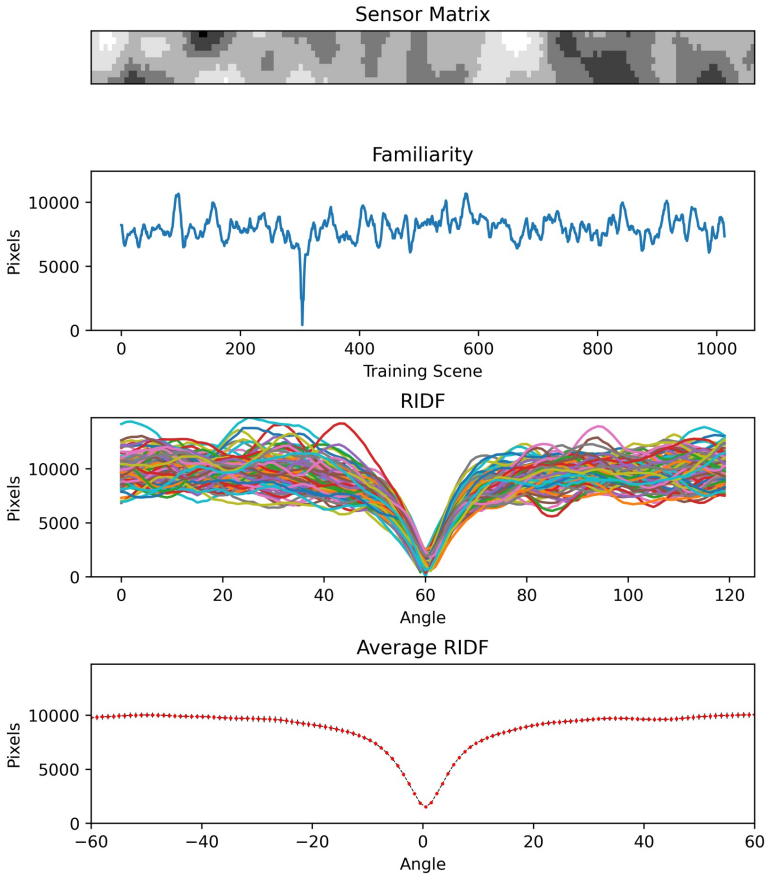


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 53.10; RMSD/dist: 0.133; TD: 6934; p90: 20; p50: 8; complete: 0

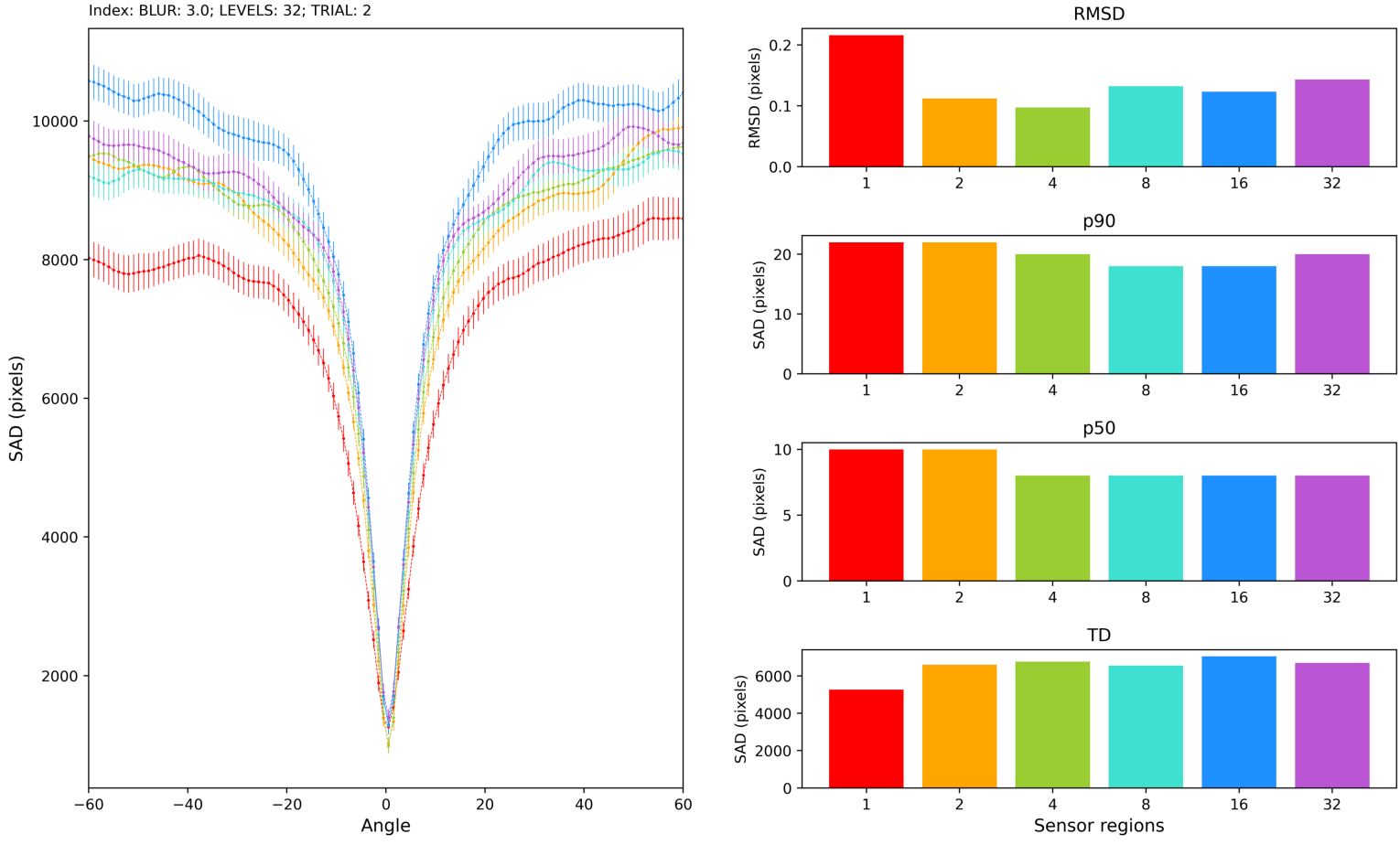
100%



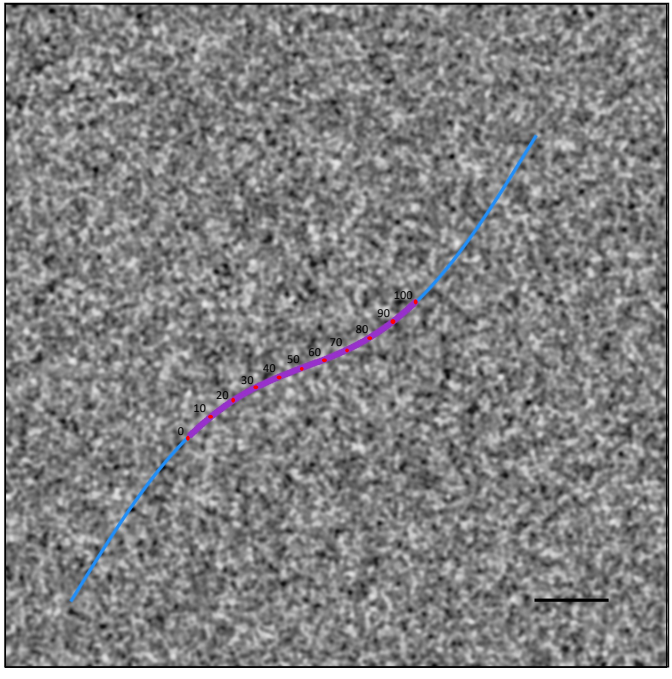


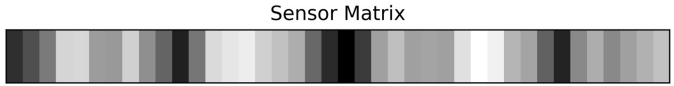
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

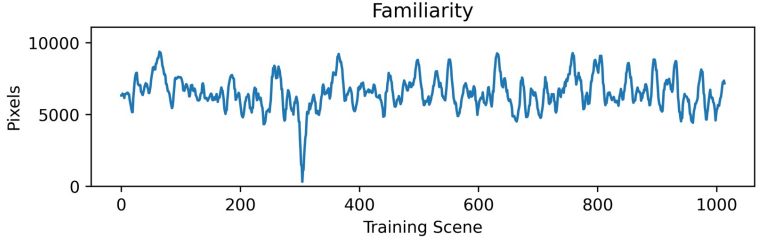
Navigation stats: RMSD error: 66.19; RMSD/dist: 0.165; TD: 6658; p90: 18; p50: 8; complete: 0

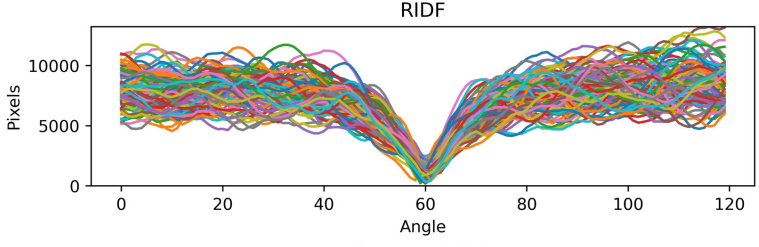

Index: BLUR: 3.0; LEVELS: 32; TRIAL: 2
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

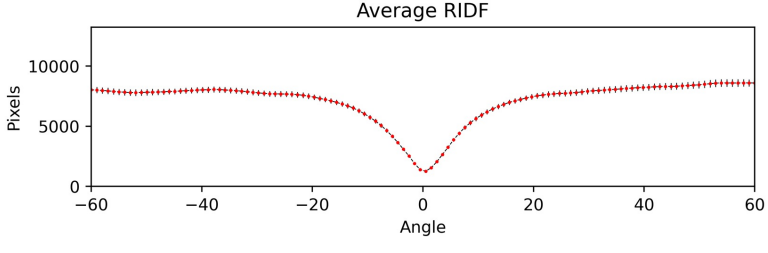
100%







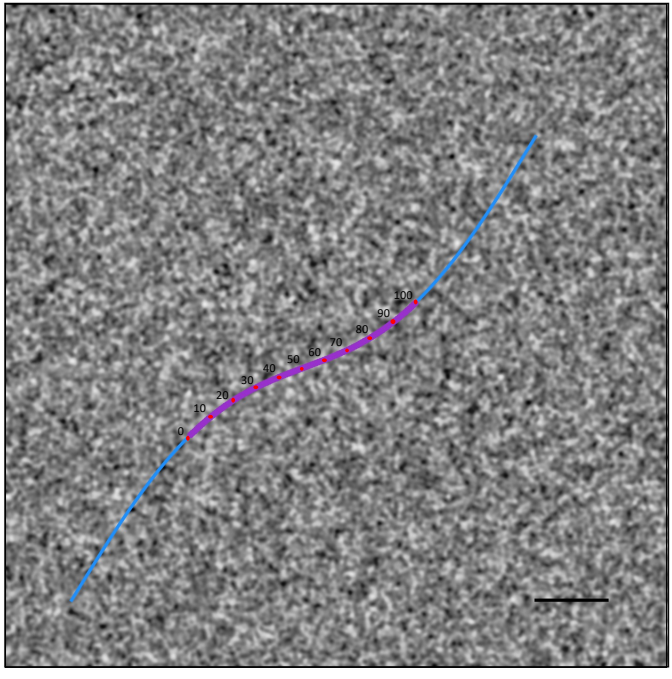


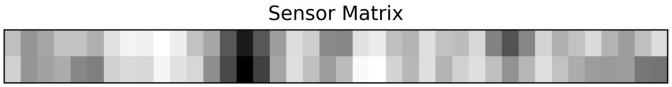


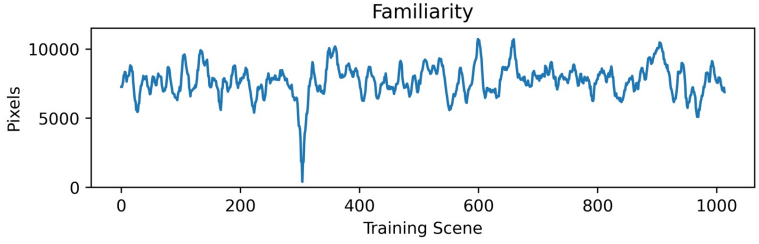
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

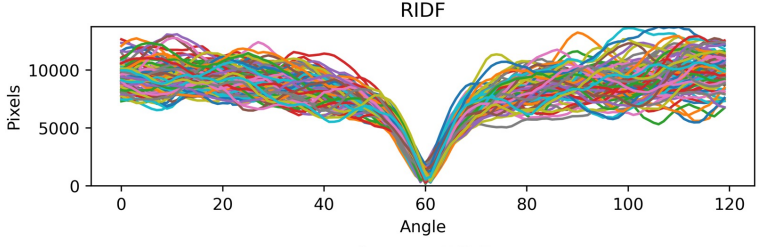
Navigation stats: RMSD error: 86.55; RMSD/dist: 0.216; TD: 5273; p90: 22; p50: 10; complete: 0

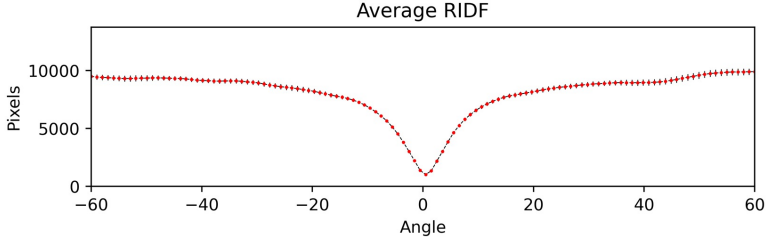
100%







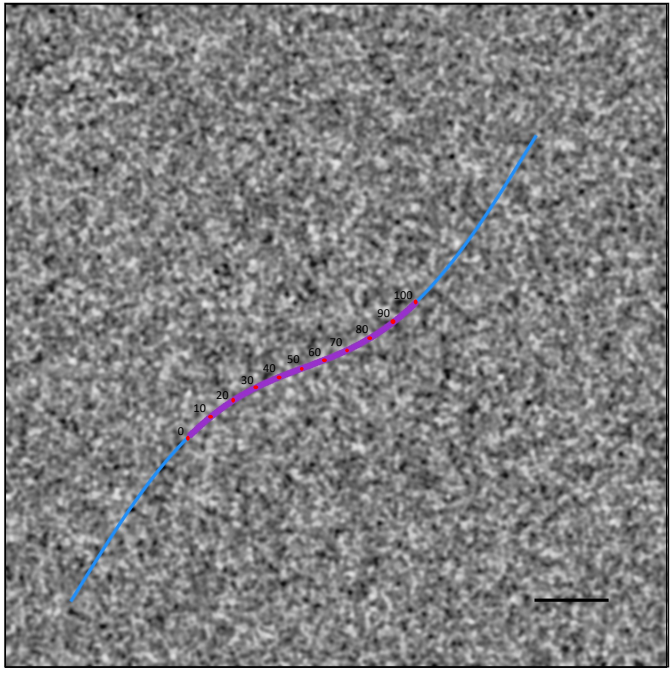


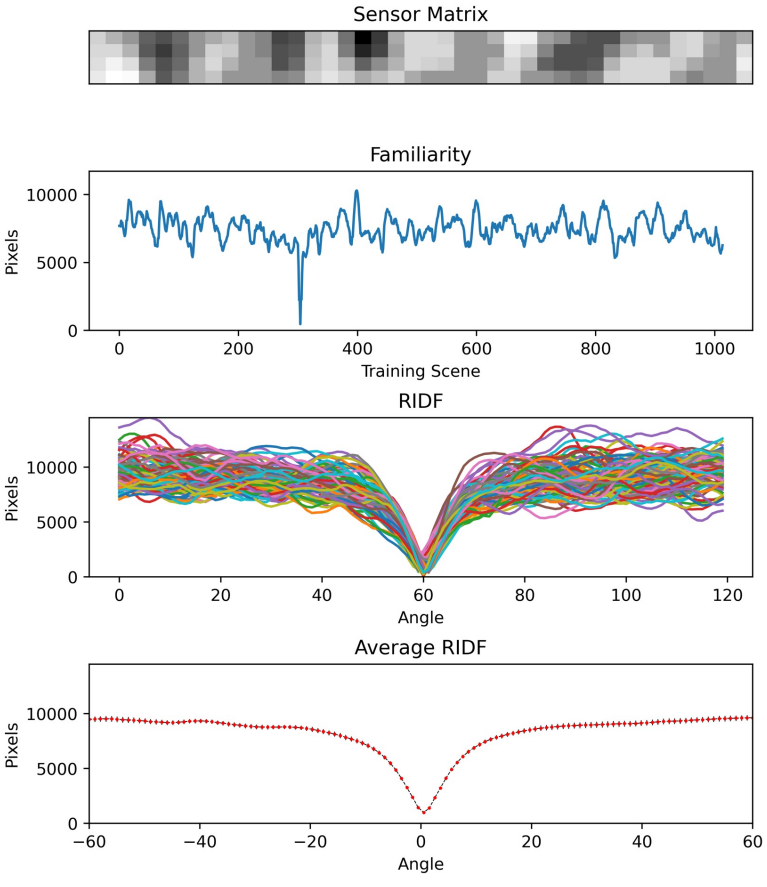


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 44.84; RMSD/dist: 0.112; TD: 6597; p90: 22; p50: 10; complete: 0

100%

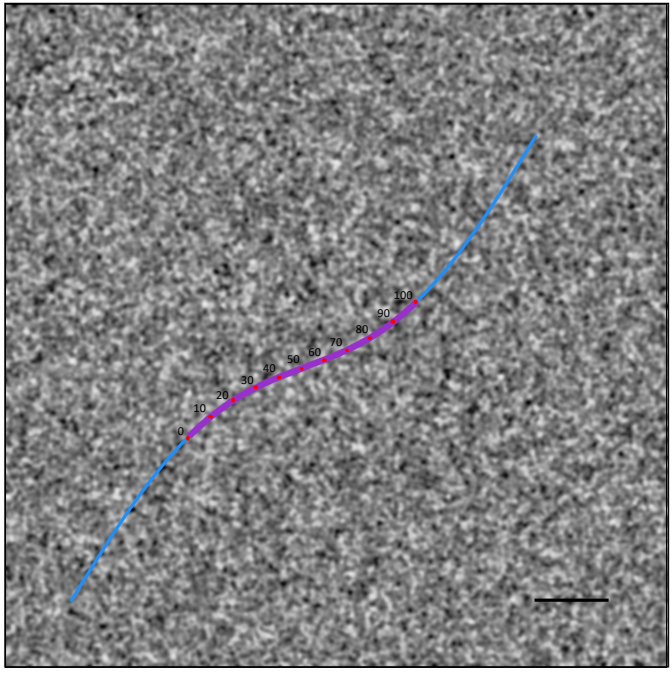


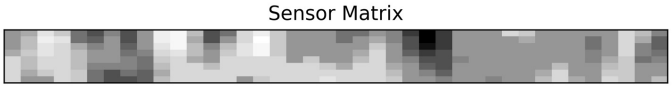


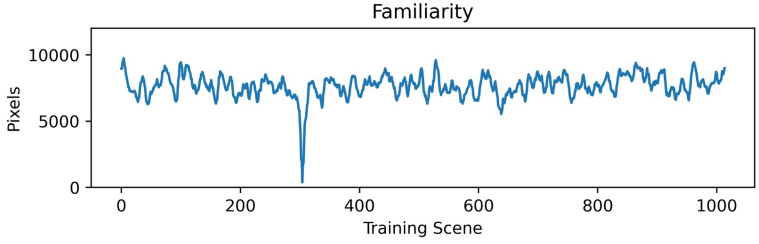
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

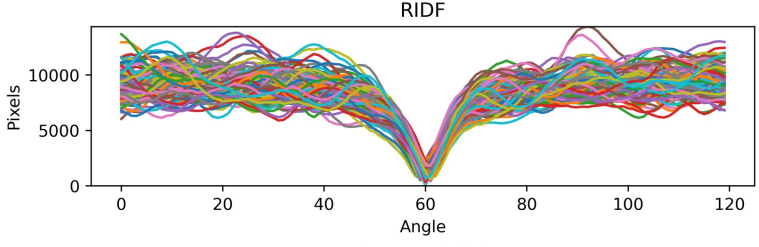
Navigation stats: RMSD error: 38.61; RMSD/dist: 0.097; TD: 6764; p90: 20; p50: 8; complete: 0

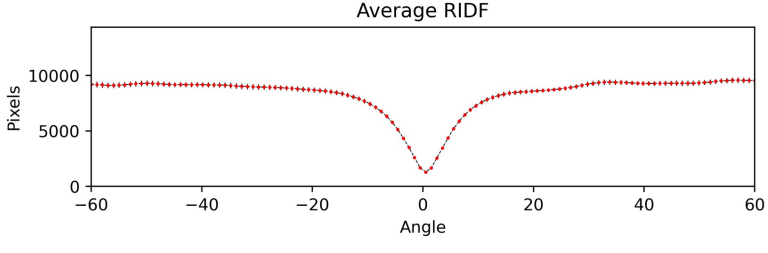
100%







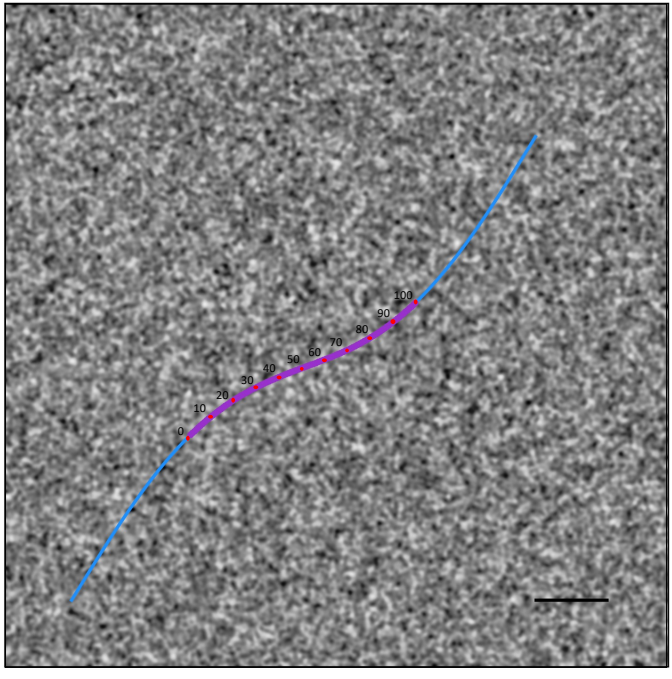


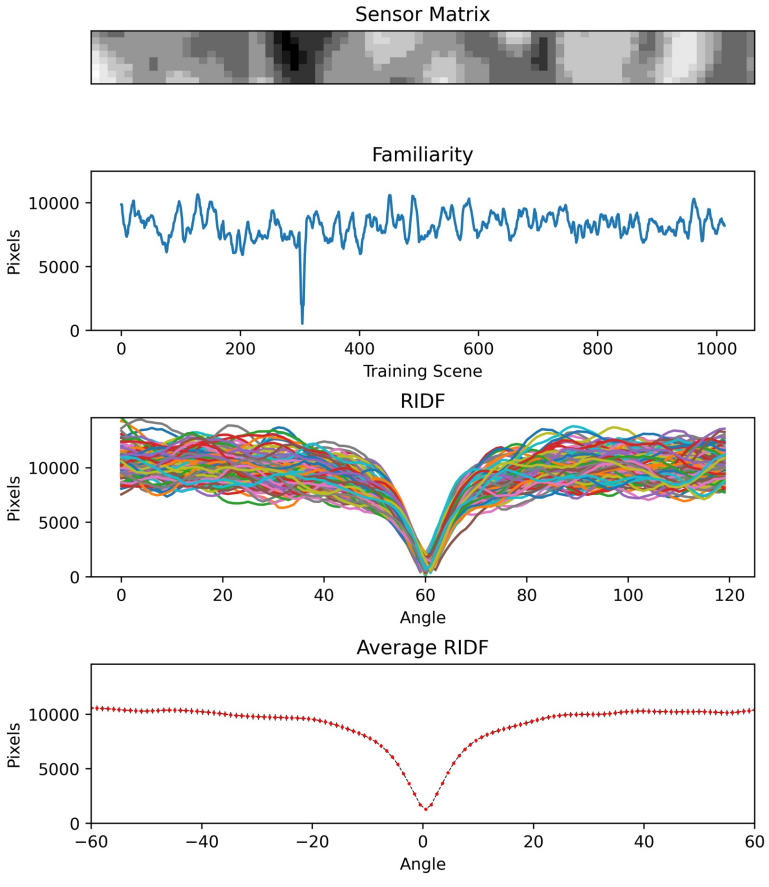


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 52.97; RMSD/dist: 0.132; TD: 6559; p90: 18; p50: 8; complete: 0

100%

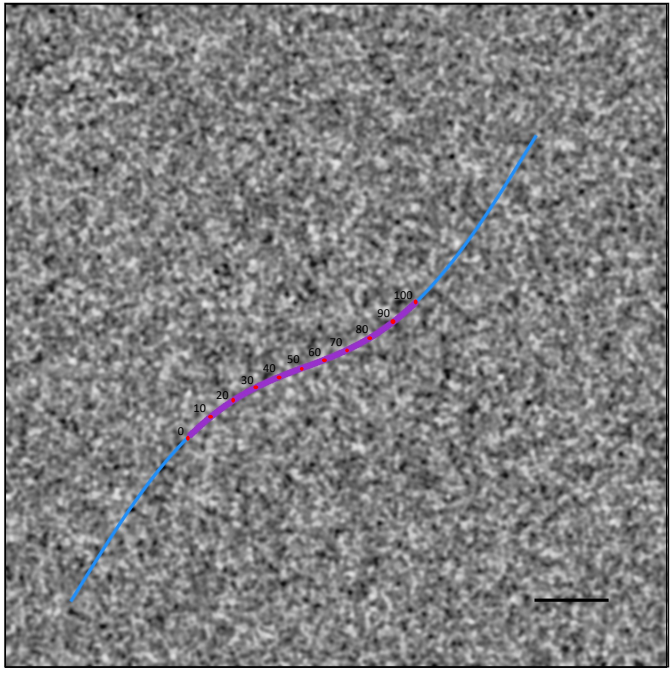


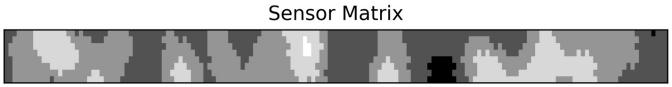


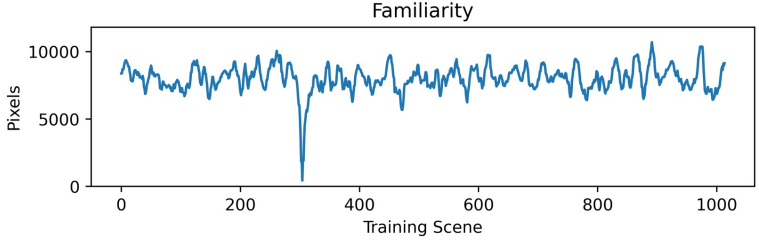
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

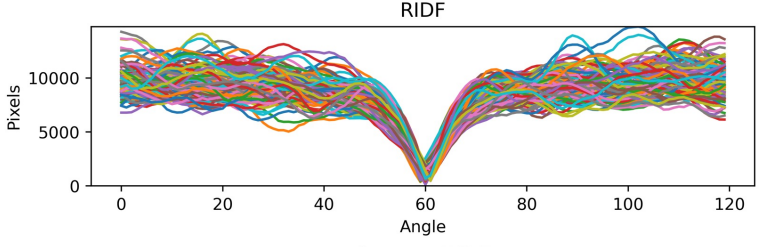
Navigation stats: RMSD error: 49.37; RMSD/dist: 0.123; TD: 7046; p90: 18; p50: 8; complete: 0

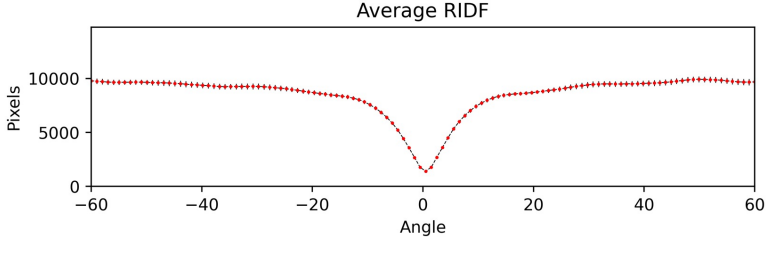
100%





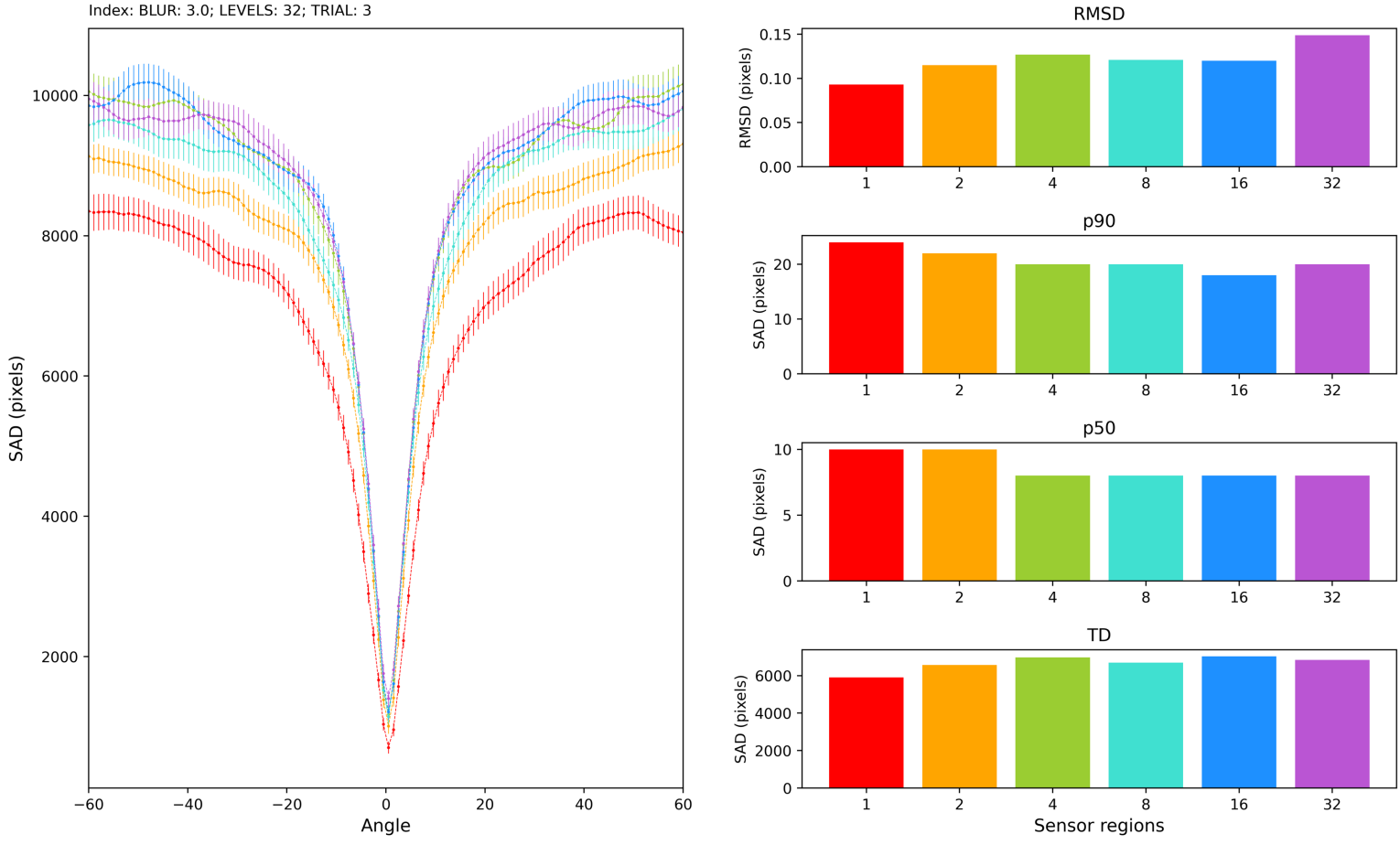




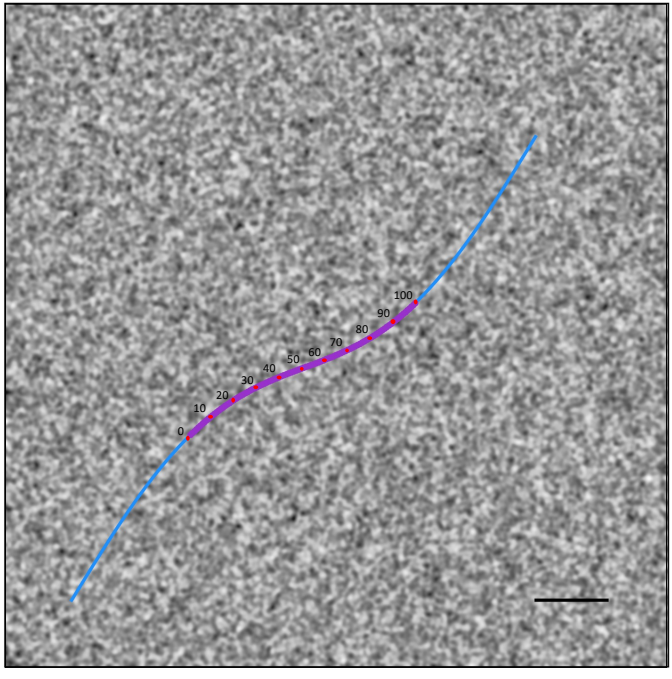


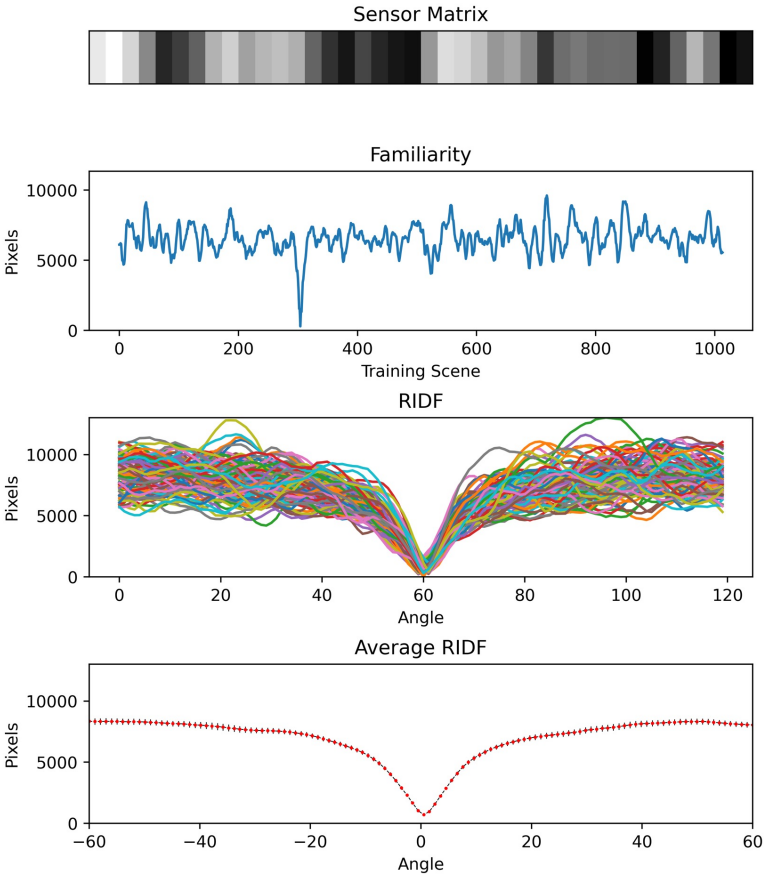
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 57.34; RMSD/dist: 0.143; TD: 6707; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 32; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

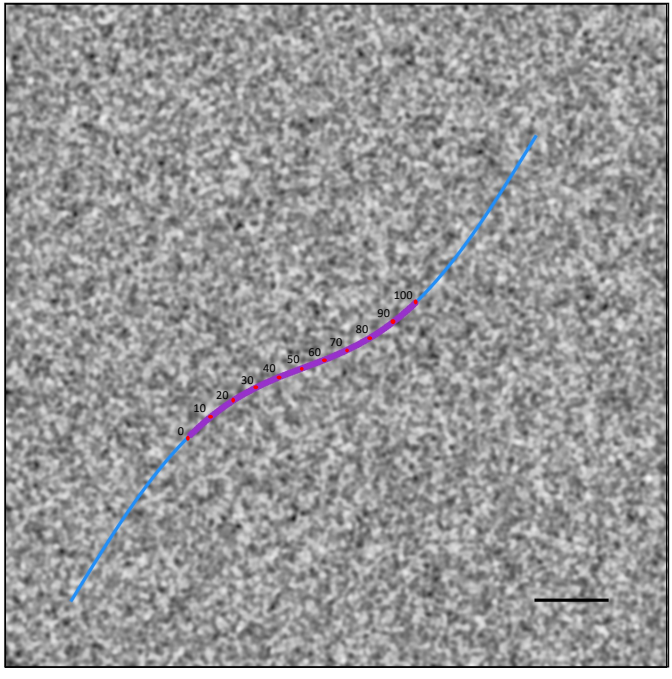


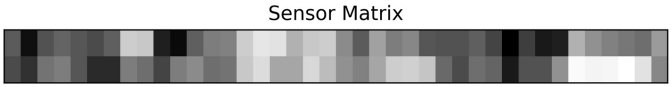


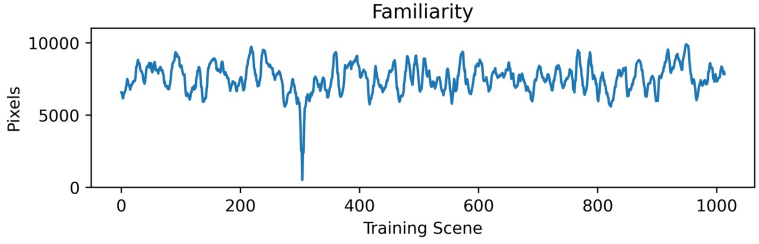
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 3

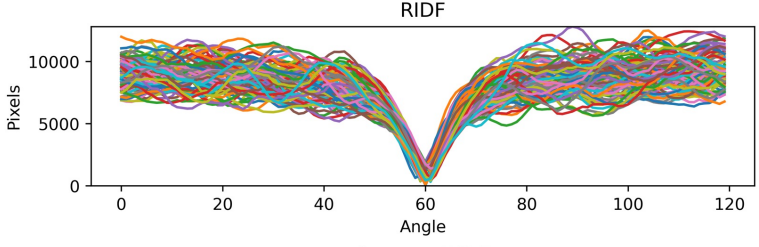
Navigation stats: RMSD error: 37.36; RMSD/dist: 0.093; TD: 5901; p90: 24; p50: 10; complete: 0

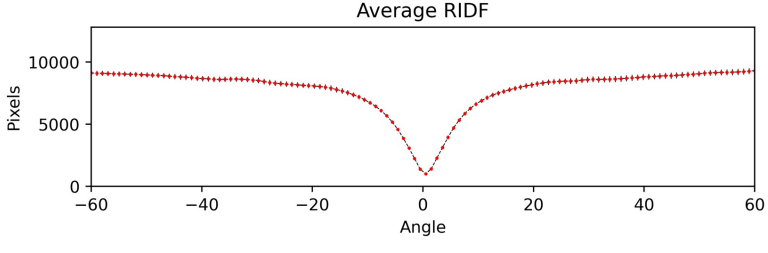
100%







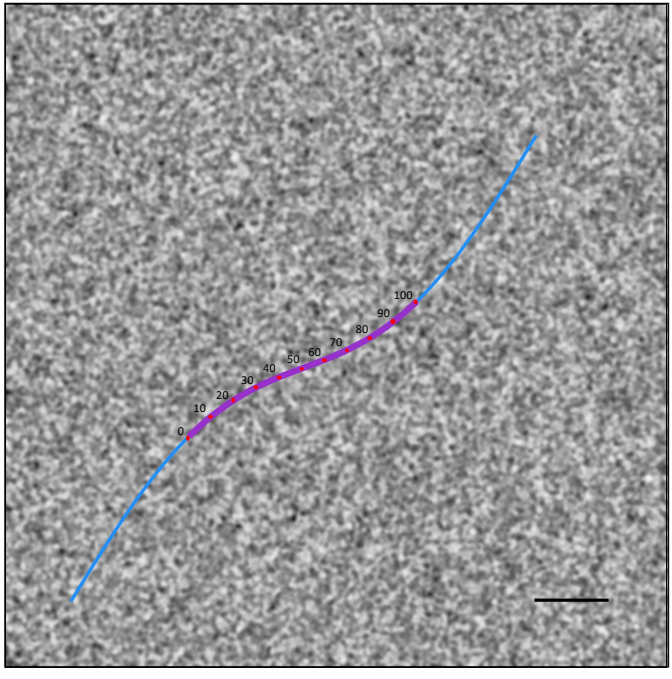


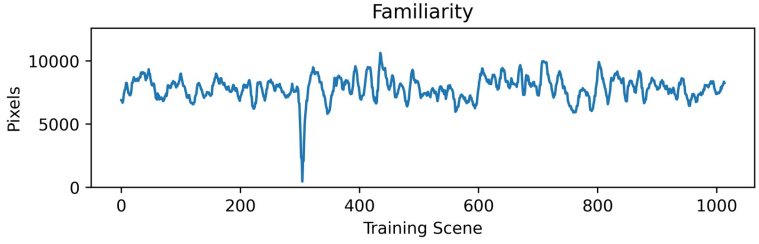


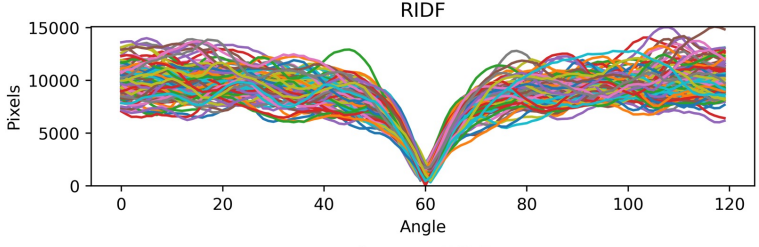
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 3

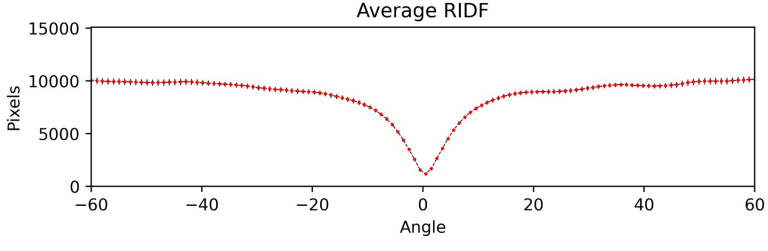
Navigation stats: RMSD error: 46.17; RMSD/dist: 0.115; TD: 6565; p90: 22; p50: 10; complete: 0

100%





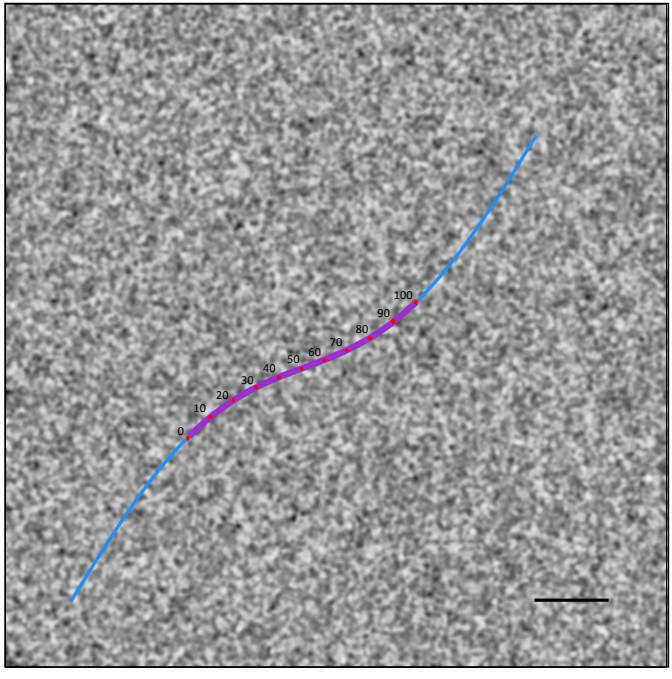


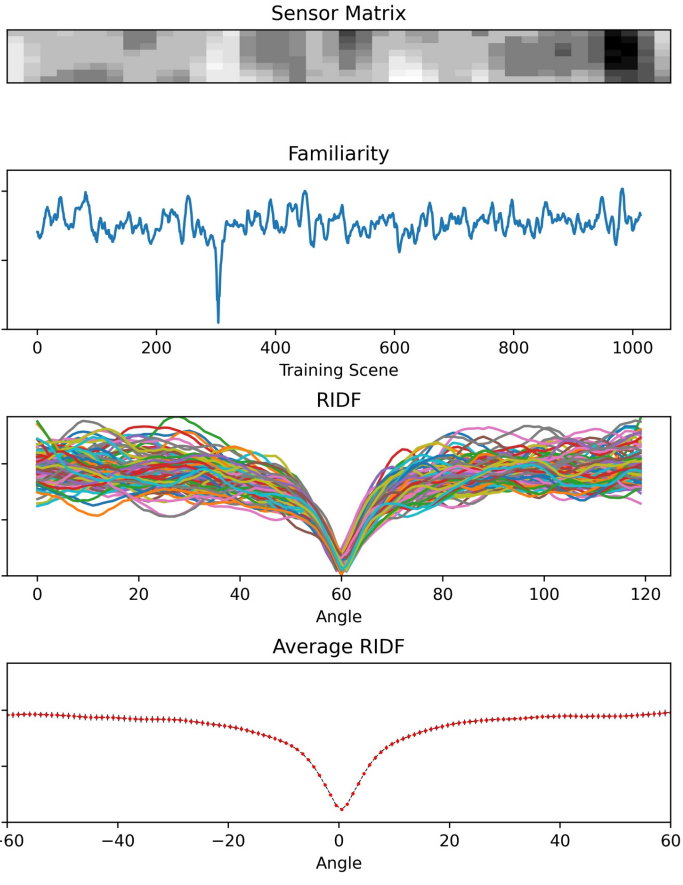


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 50.86; RMSD/dist: 0.127; TD: 6975; p90: 20; p50: 8; complete: 0

100%

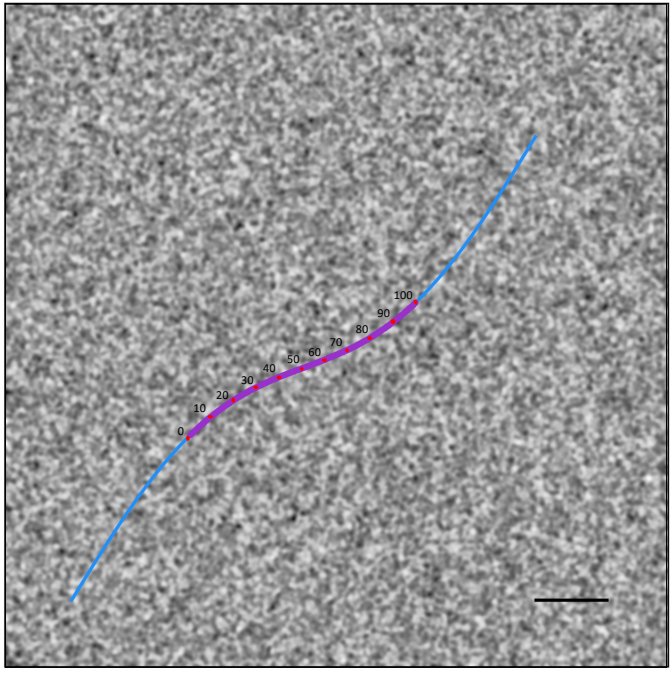


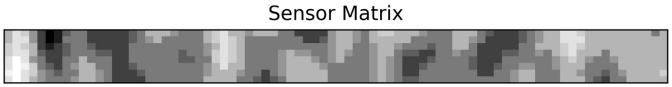


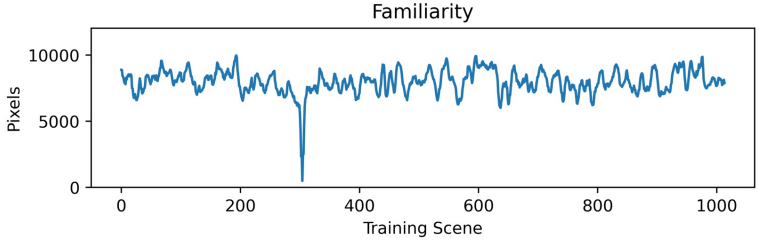
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 3

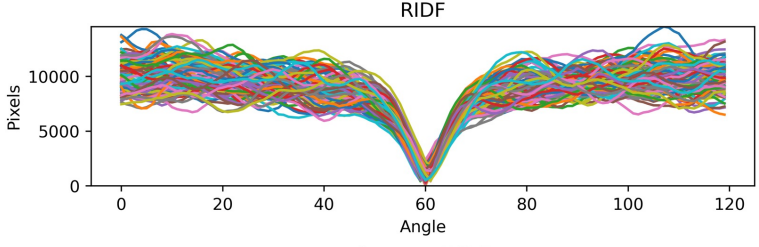
Navigation stats: RMSD error: 48.27; RMSD/dist: 0.121; TD: 6697; p90: 20; p50: 8; complete: 0

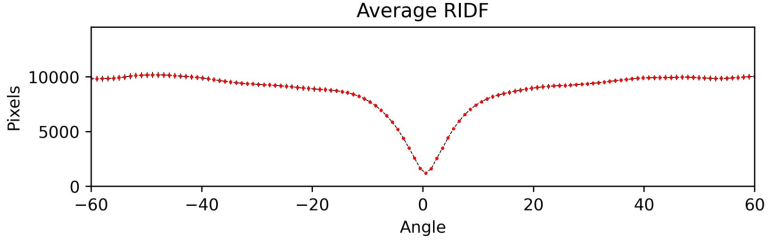
100%







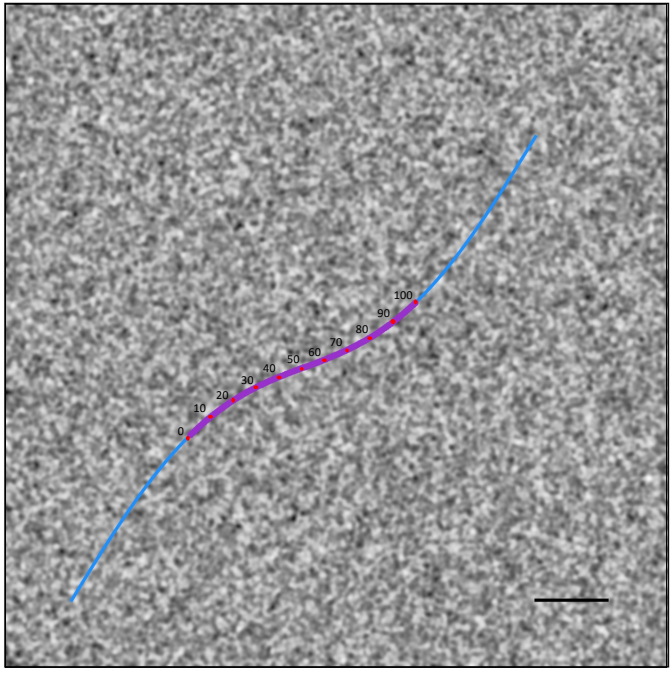


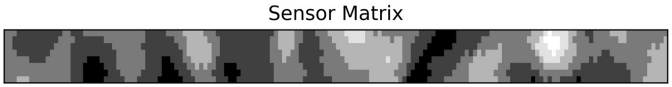


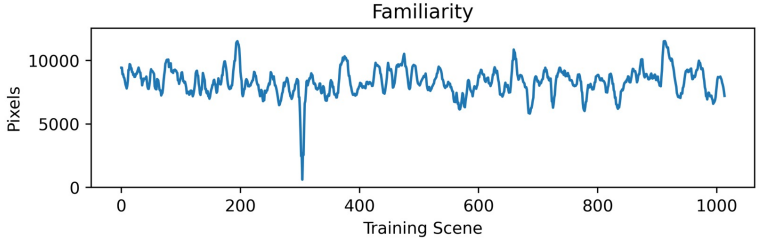
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

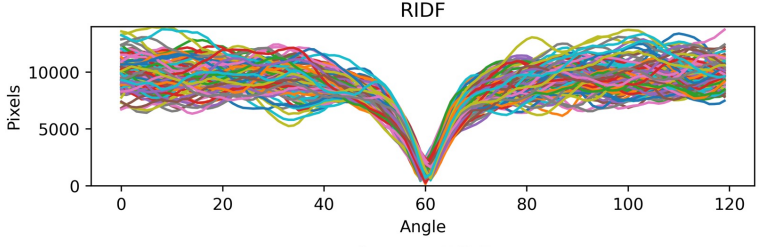
Navigation stats: RMSD error: 47.91; RMSD/dist: 0.120; TD: 7025; p90: 18; p50: 8; complete: 0

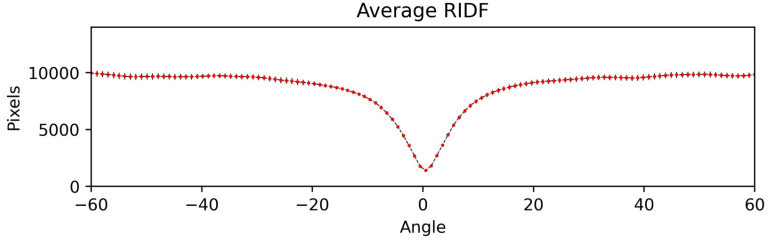
100%





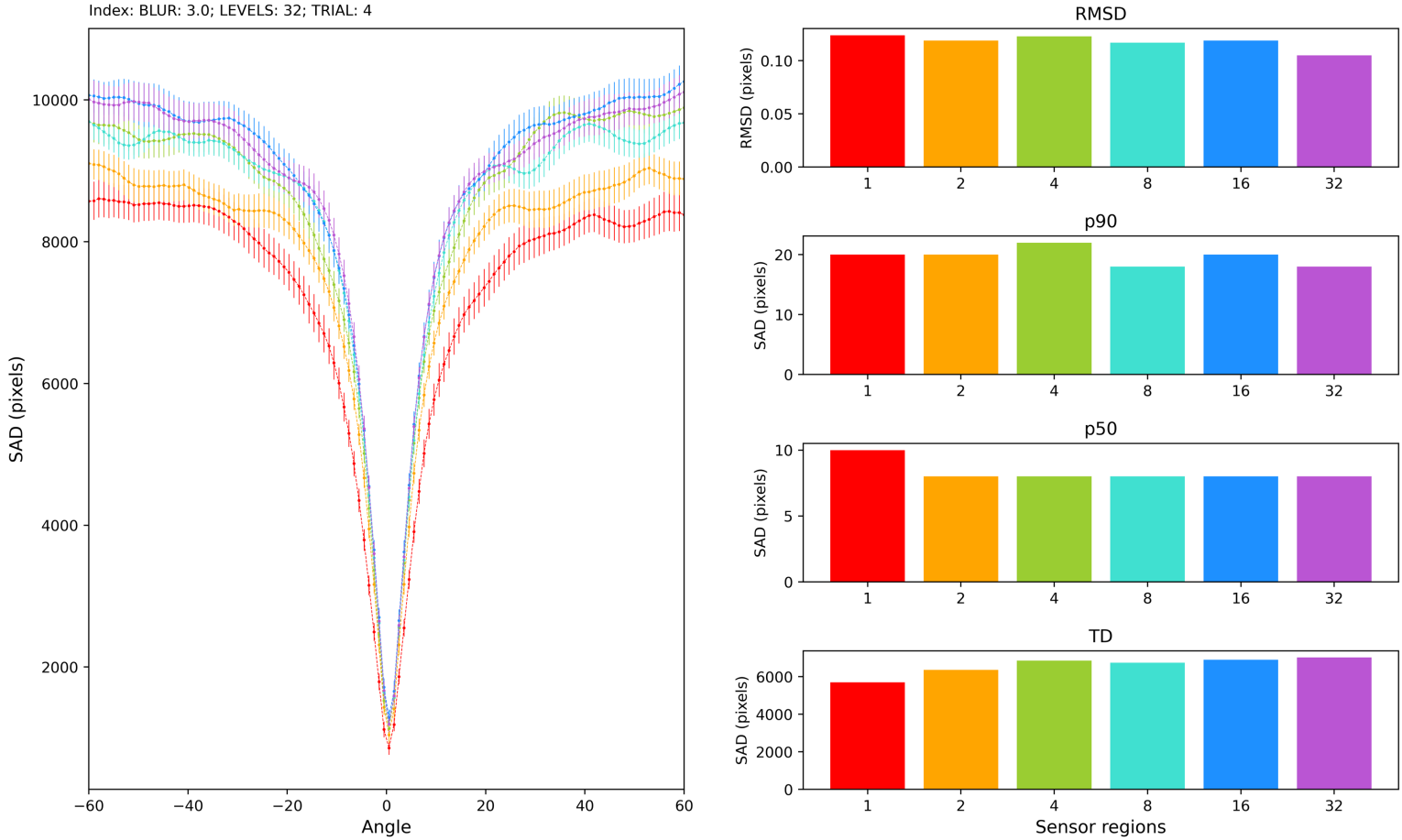




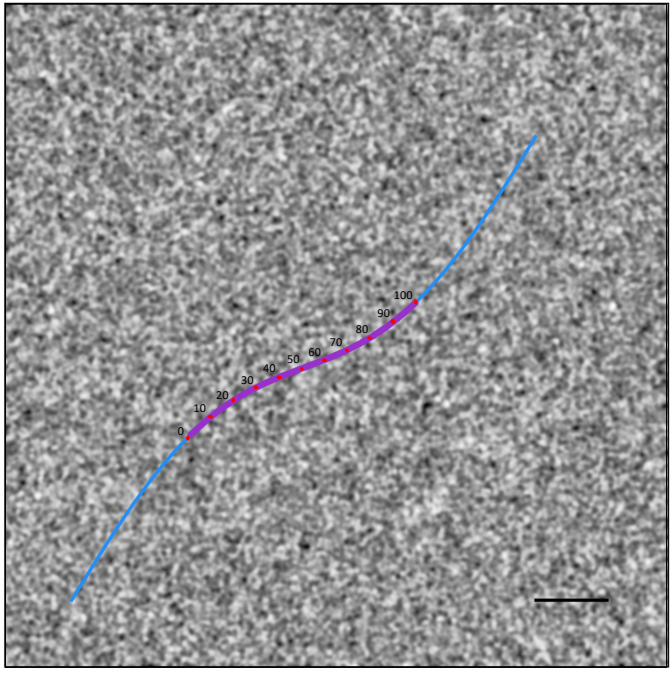


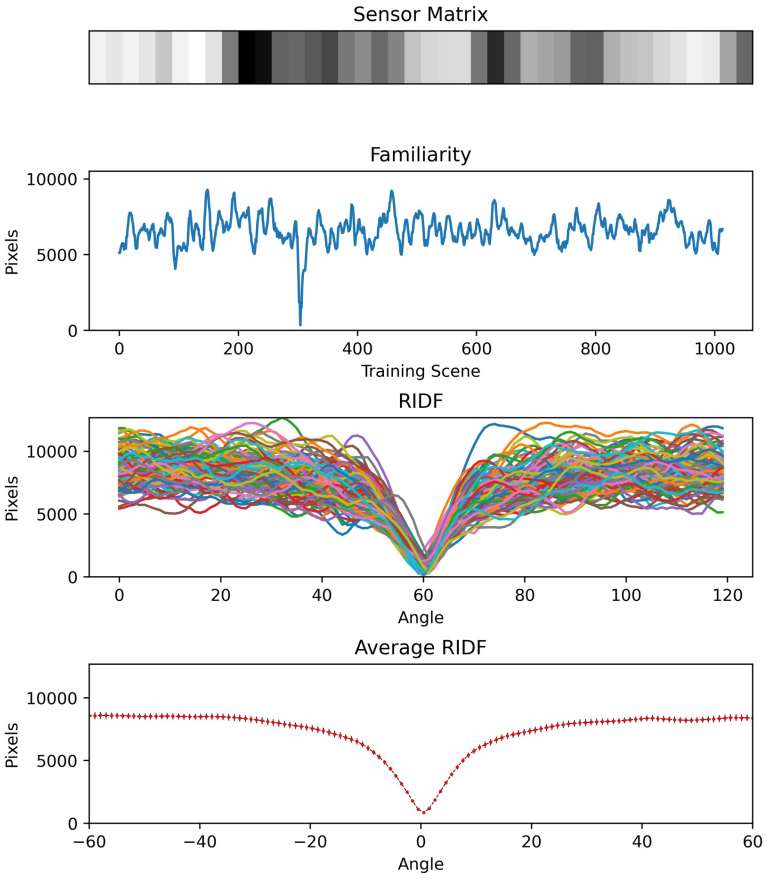
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 59.79; RMSD/dist: 0.149; TD: 6842; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 32; TRIAL: 4
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

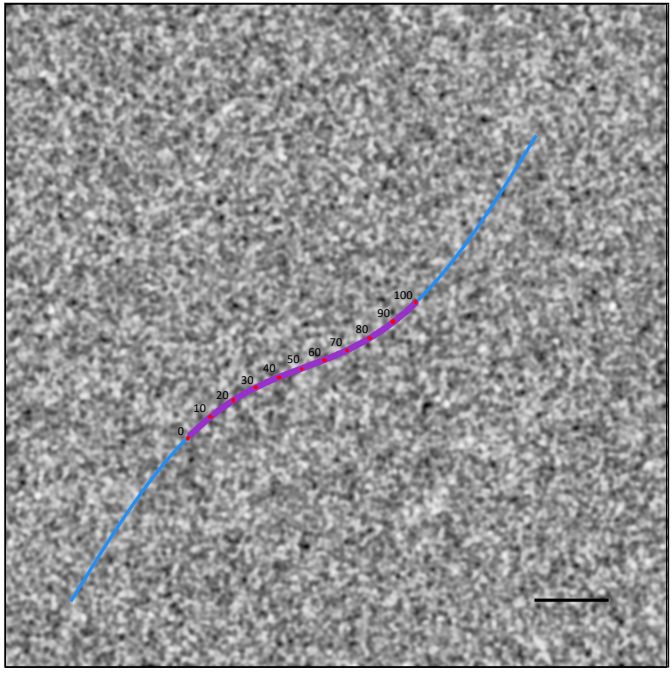


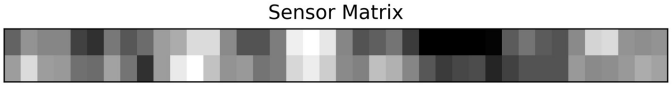


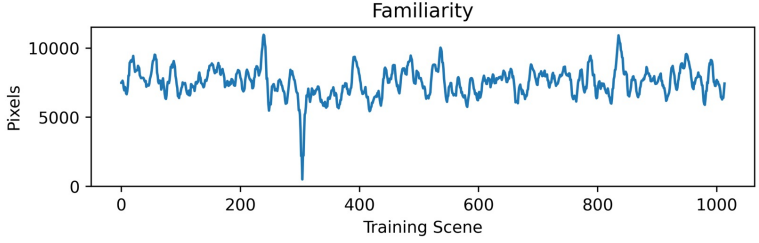
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 4

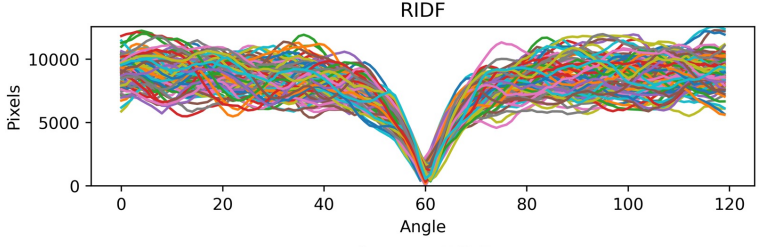
Navigation stats: RMSD error: 49.44; RMSD/dist: 0.124; TD: 5696; p90: 20; p50: 10; complete: 0

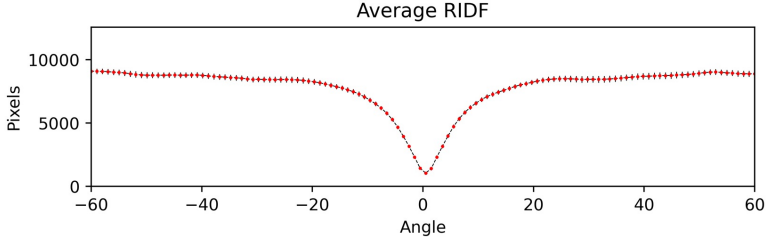
100%







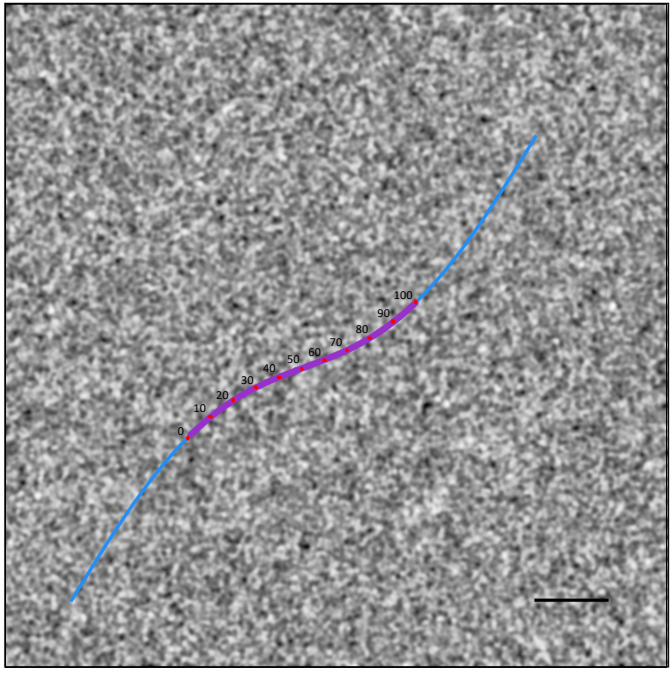


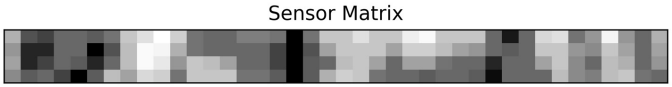


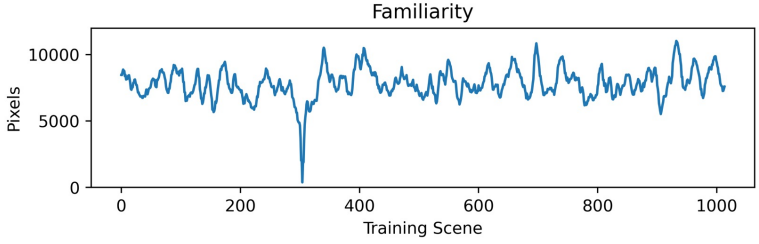
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

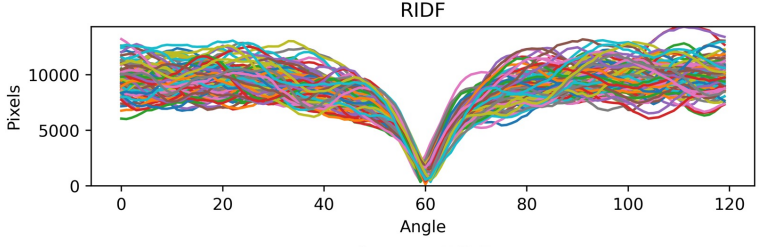
Navigation stats: RMSD error: 47.67; RMSD/dist: 0.119; TD: 6357; p90: 20; p50: 8; complete: 0

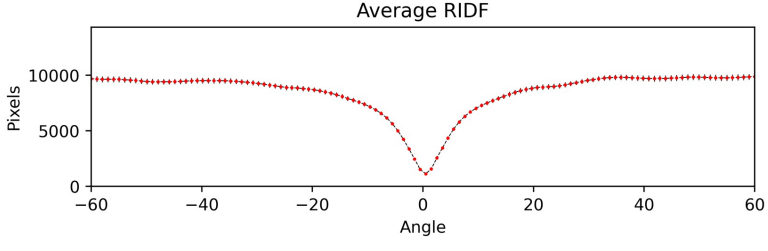
100%







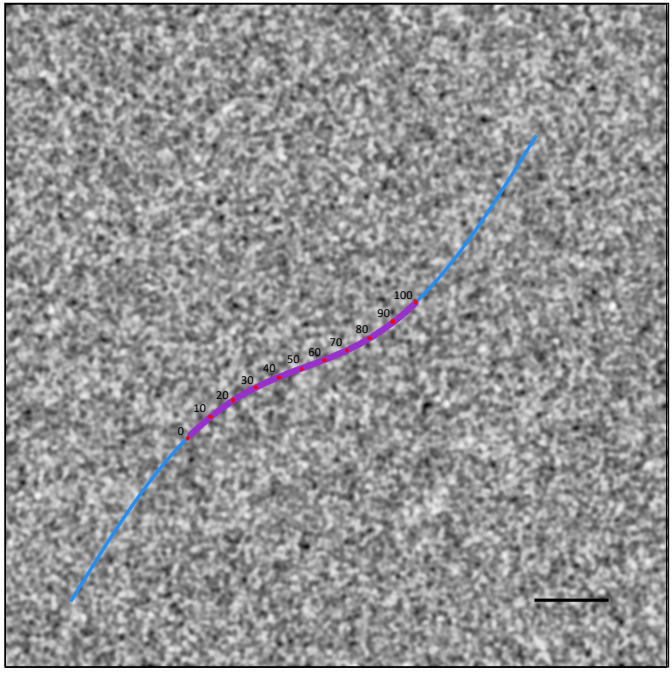


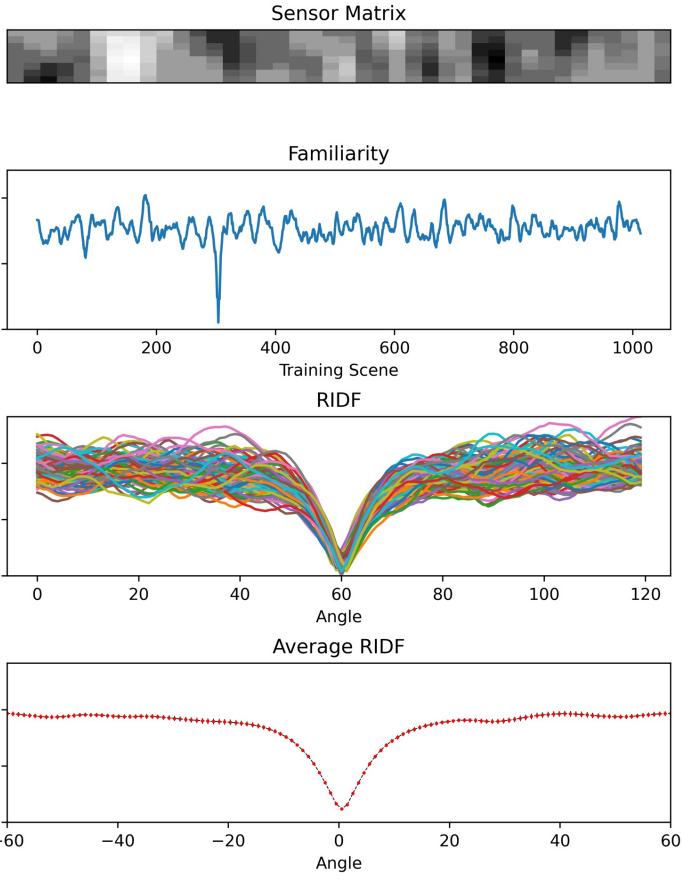


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 49.36; RMSD/dist: 0.123; TD: 6845; p90: 22; p50: 8; complete: 0

100%

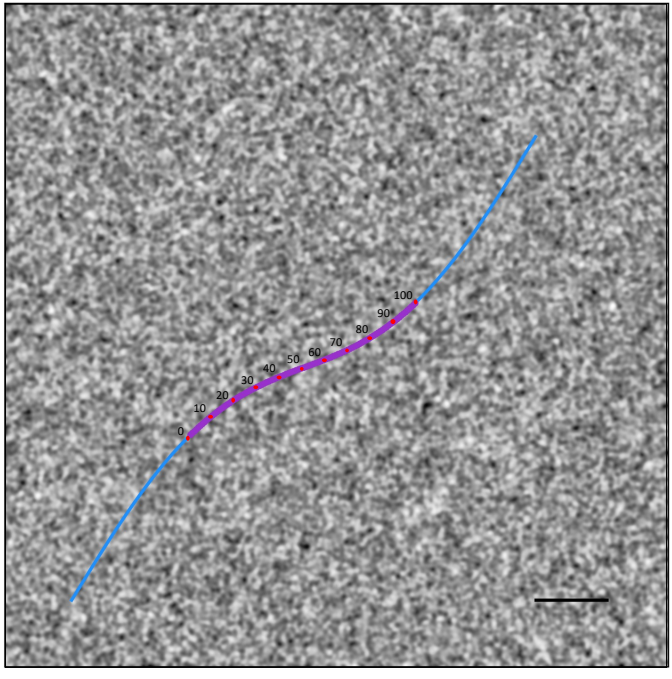


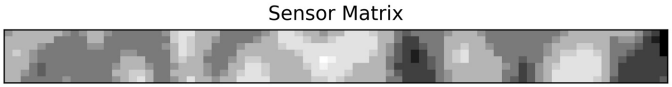


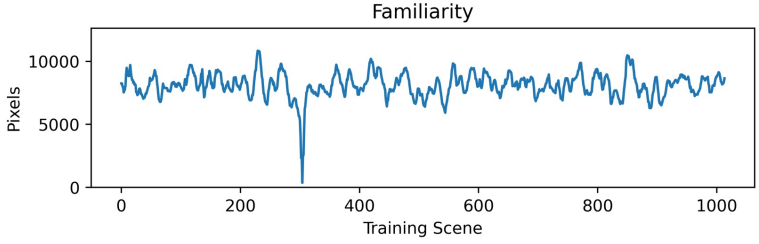
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 4

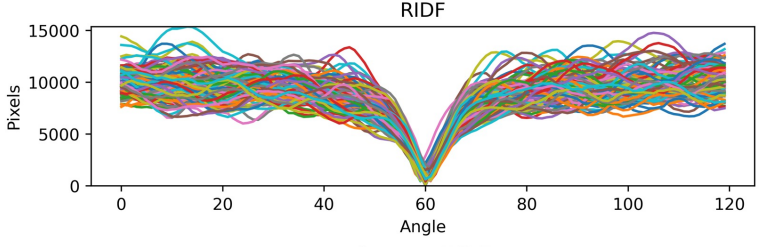
Navigation stats: RMSD error: 46.85; RMSD/dist: 0.117; TD: 6735; p90: 18; p50: 8; complete: 0

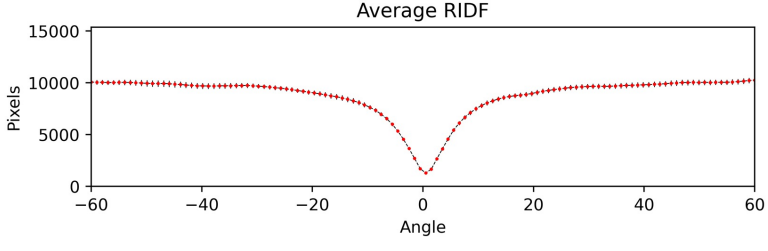
100%







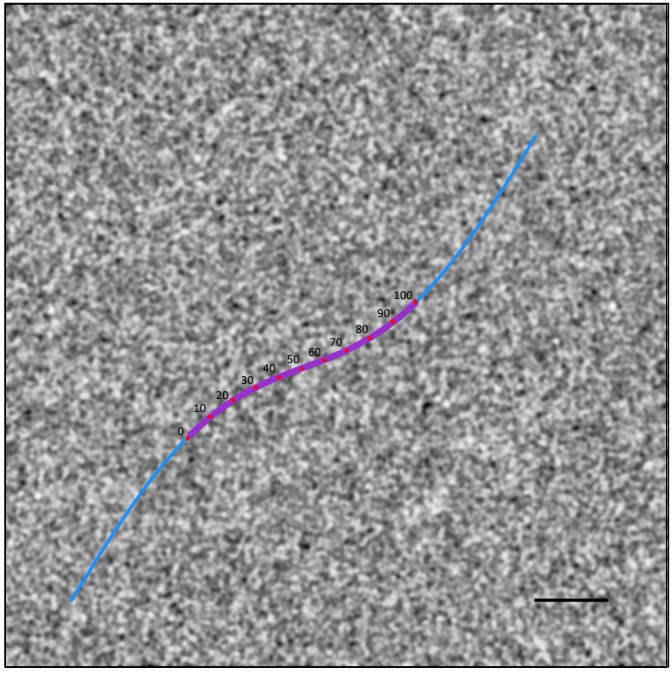


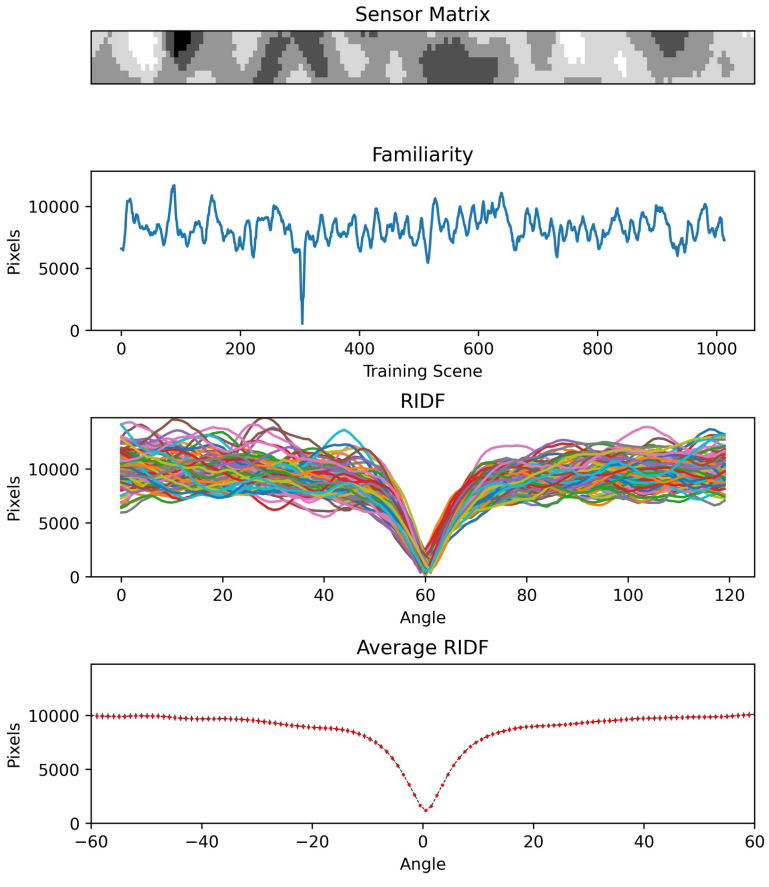


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 47.66; RMSD/dist: 0.119; TD: 6899; p90: 20; p50: 8; complete: 0

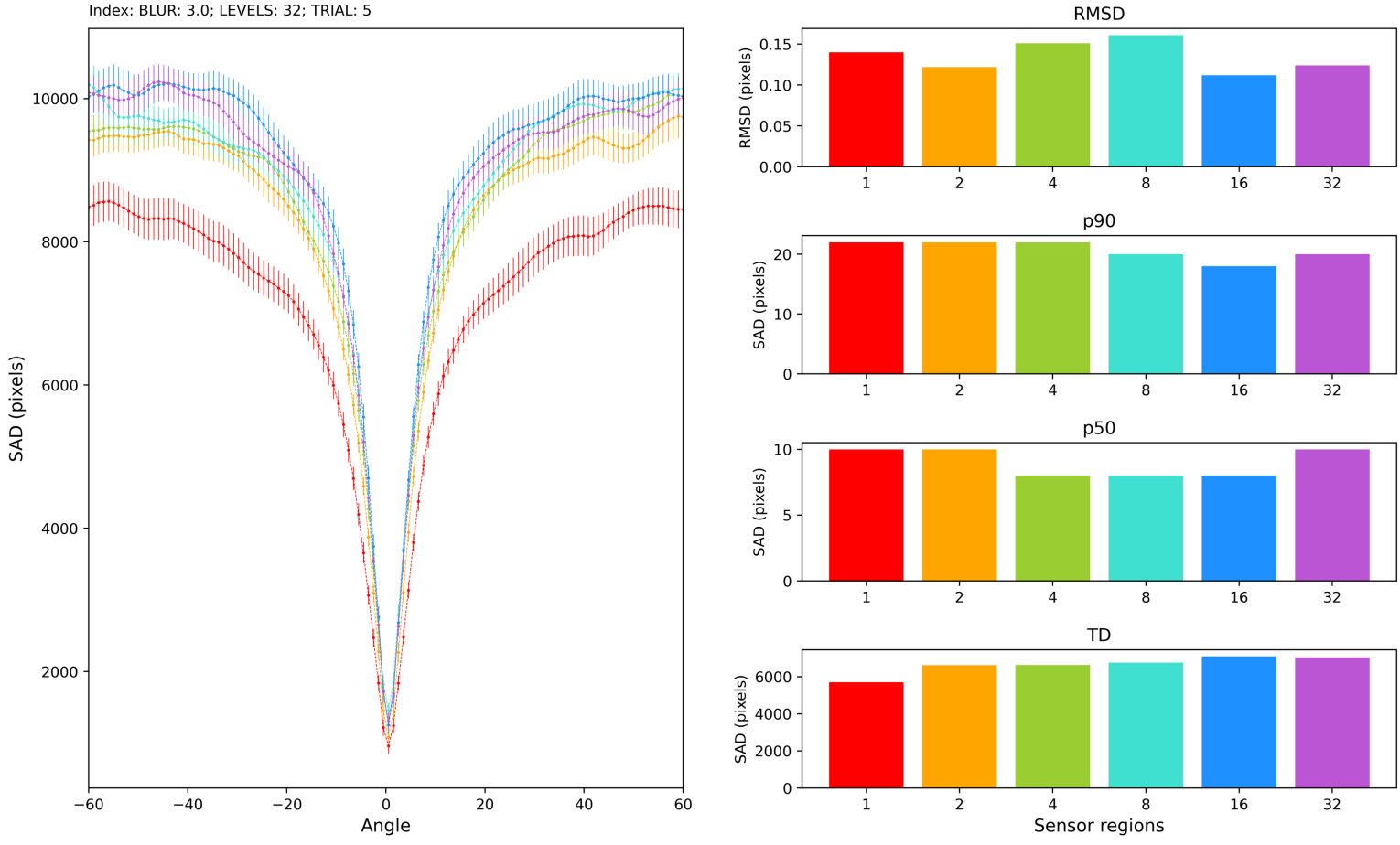
100%



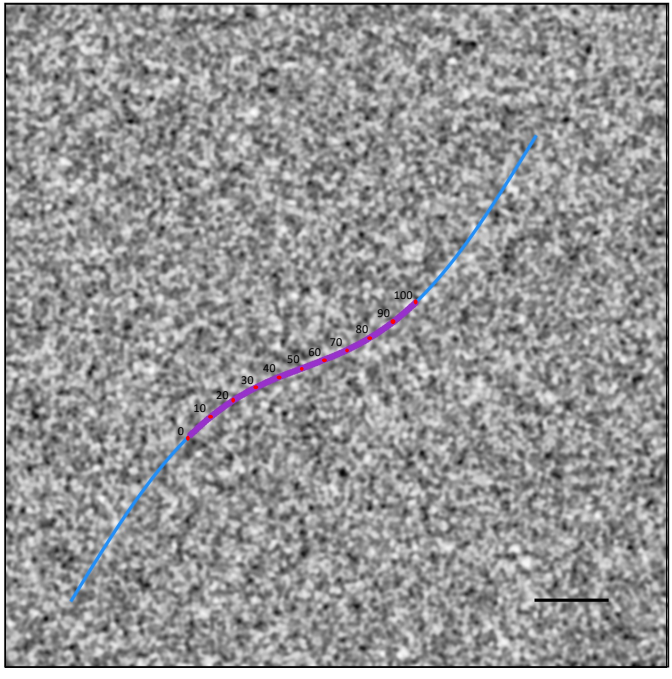


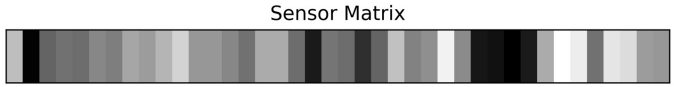
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

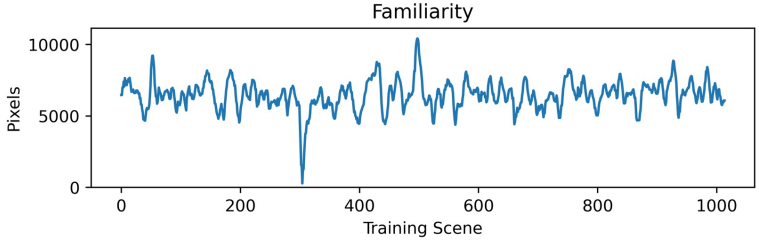
Navigation stats: RMSD error: 41.83; RMSD/dist: 0.105; TD: 7013; p90: 18; p50: 8; complete: 0

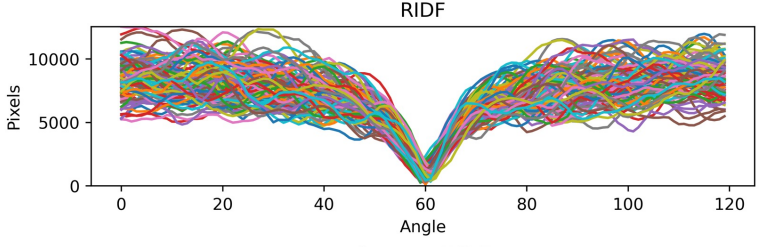

Index: BLUR: 3.0; LEVELS: 32; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

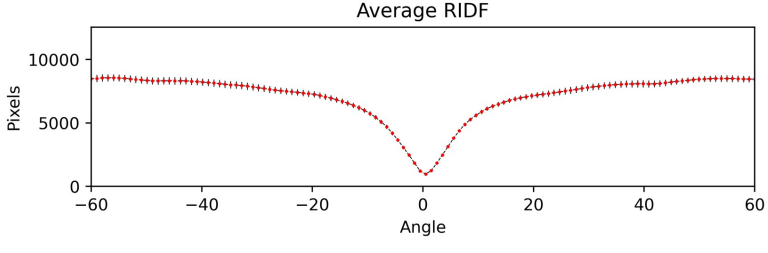
100%







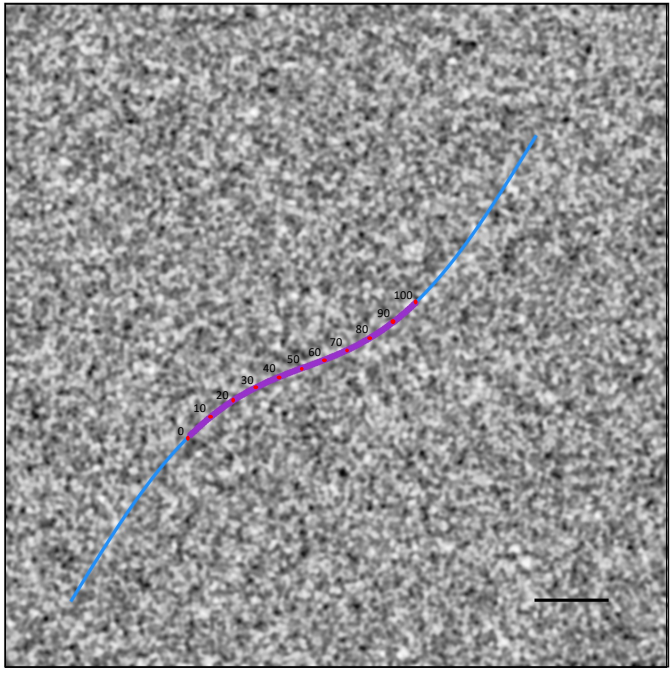


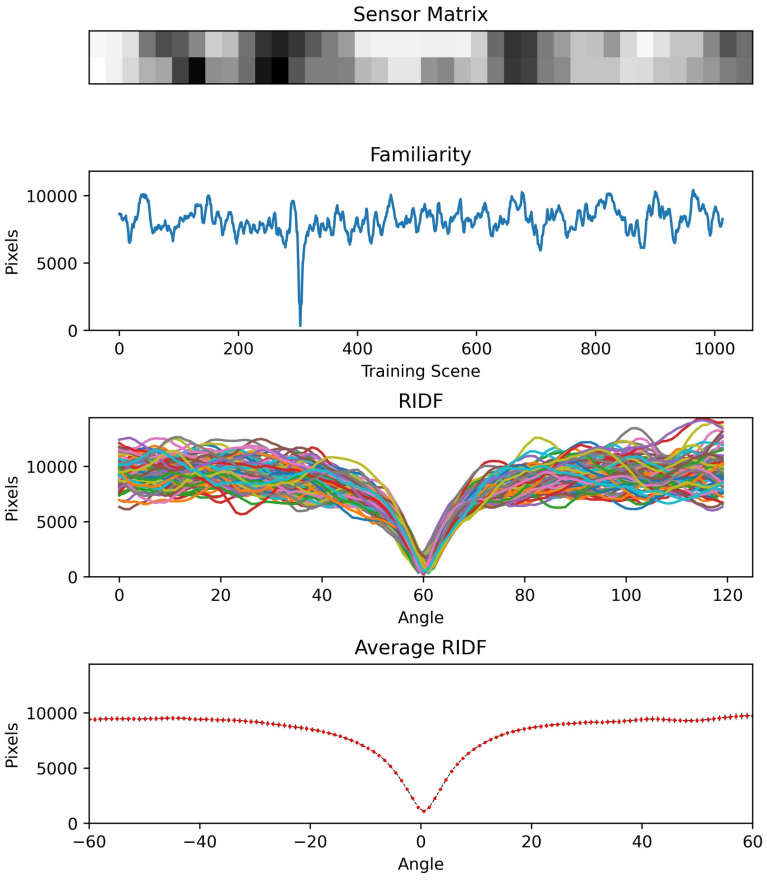


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 55.97; RMSD/dist: 0.140; TD: 5701; p90: 22; p50: 10; complete: 0

100%

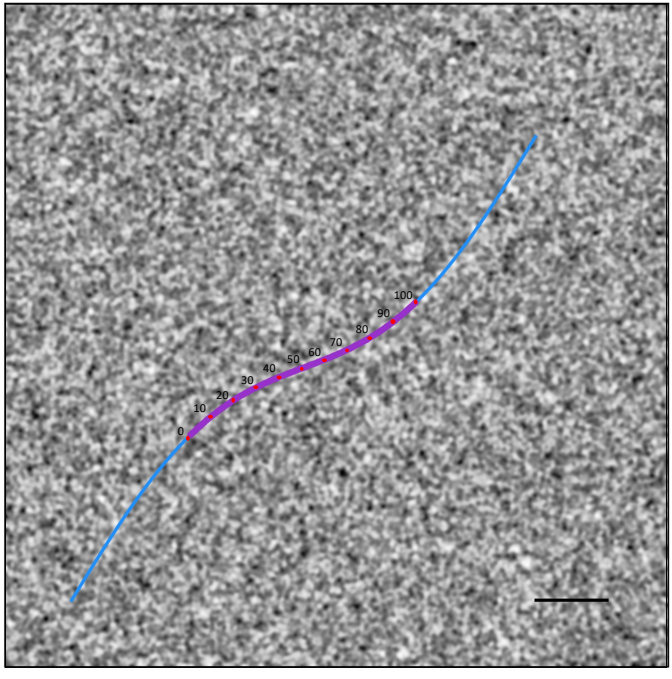


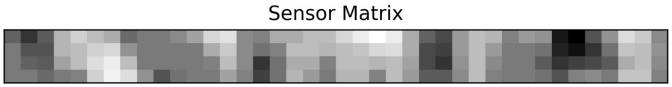


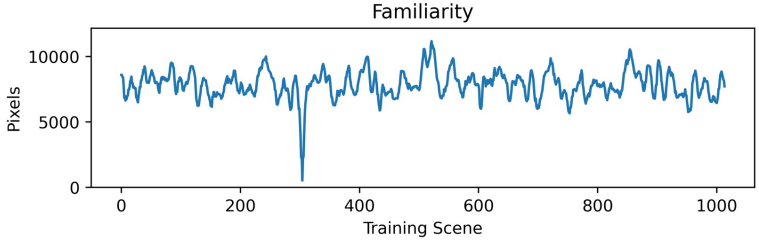
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

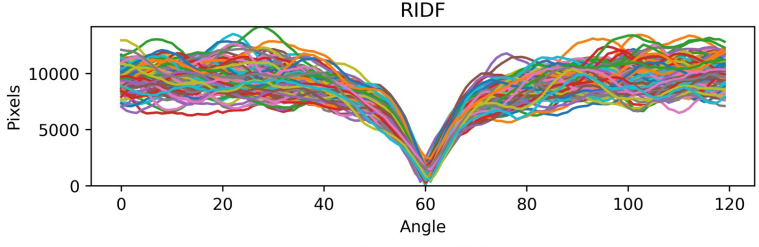
Navigation stats: RMSD error: 48.86; RMSD/dist: 0.122; TD: 6620; p90: 22; p50: 10; complete: 0

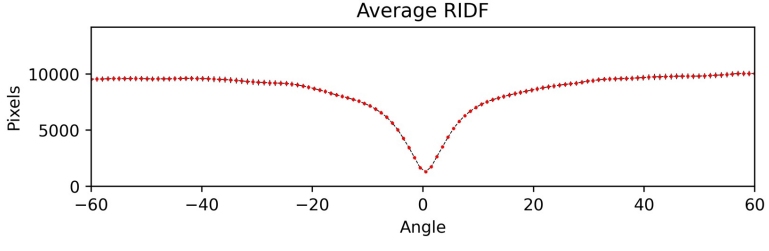
100%







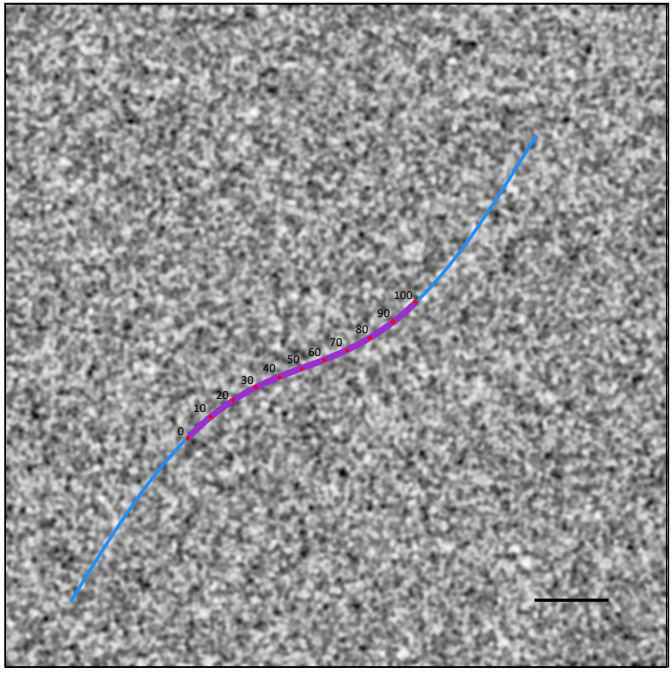


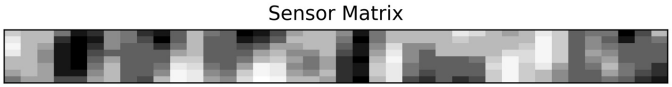


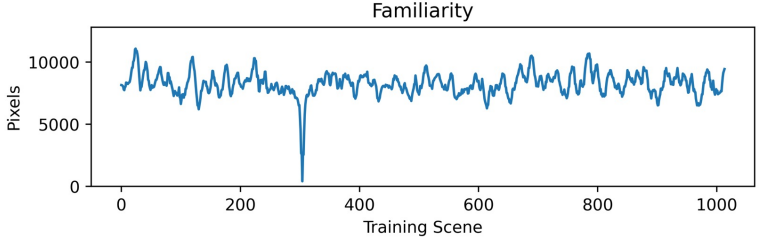
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

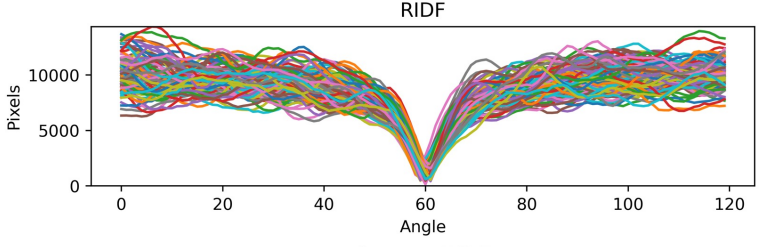
Navigation stats: RMSD error: 60.25; RMSD/dist: 0.151; TD: 6635; p90: 22; p50: 8; complete: 0

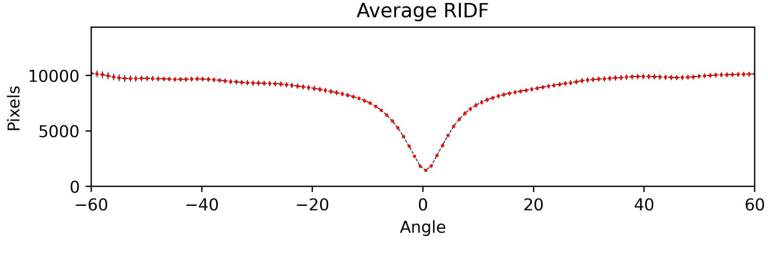
100%







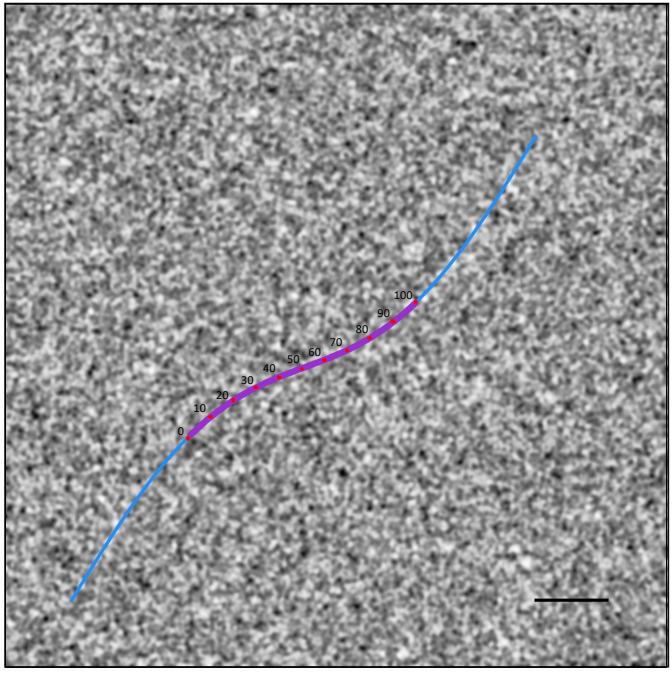


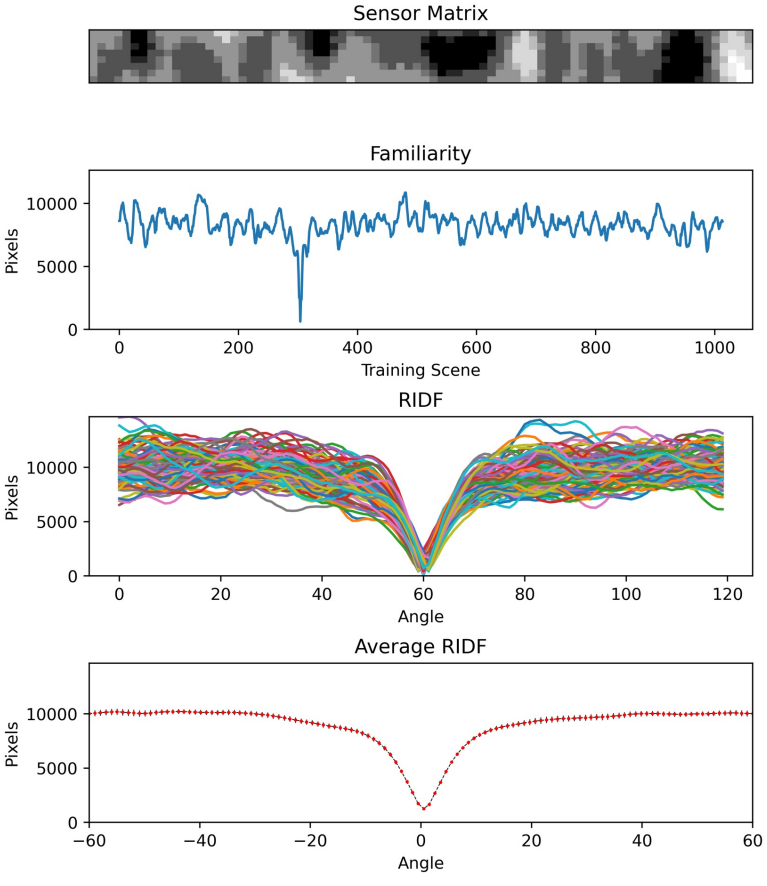


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 64.56; RMSD/dist: 0.161; TD: 6760; p90: 20; p50: 8; complete: 0

100%

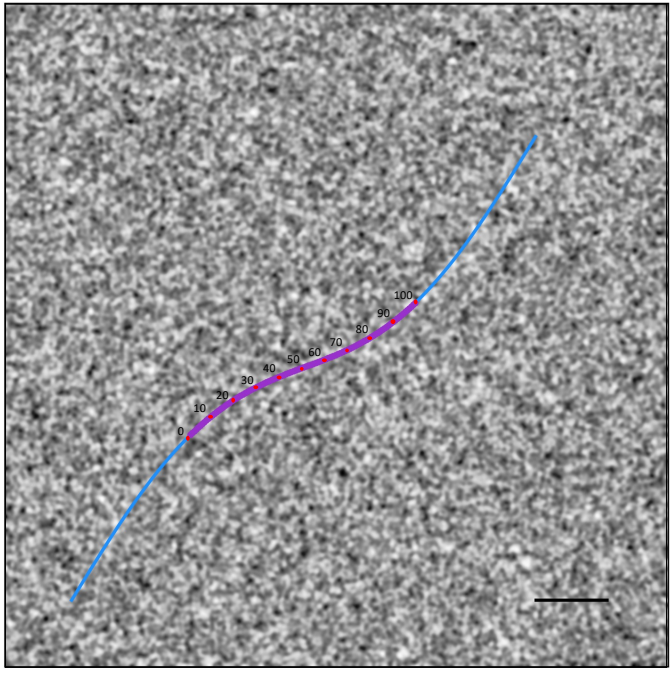


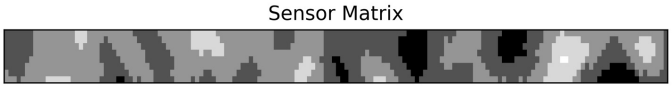


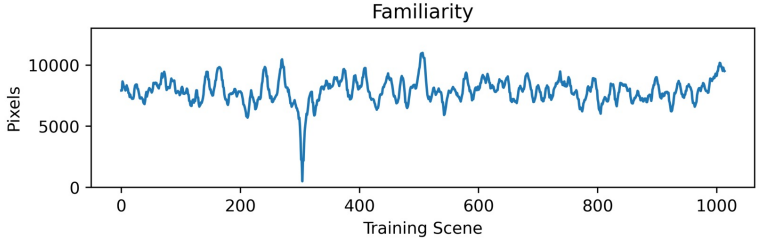
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

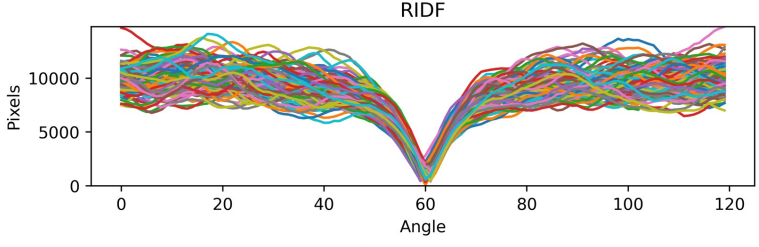
Navigation stats: RMSD error: 44.77; RMSD/dist: 0.112; TD: 7091; p90: 18; p50: 8; complete: 0

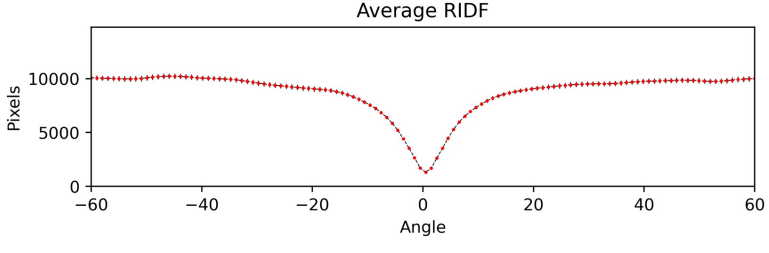
100%











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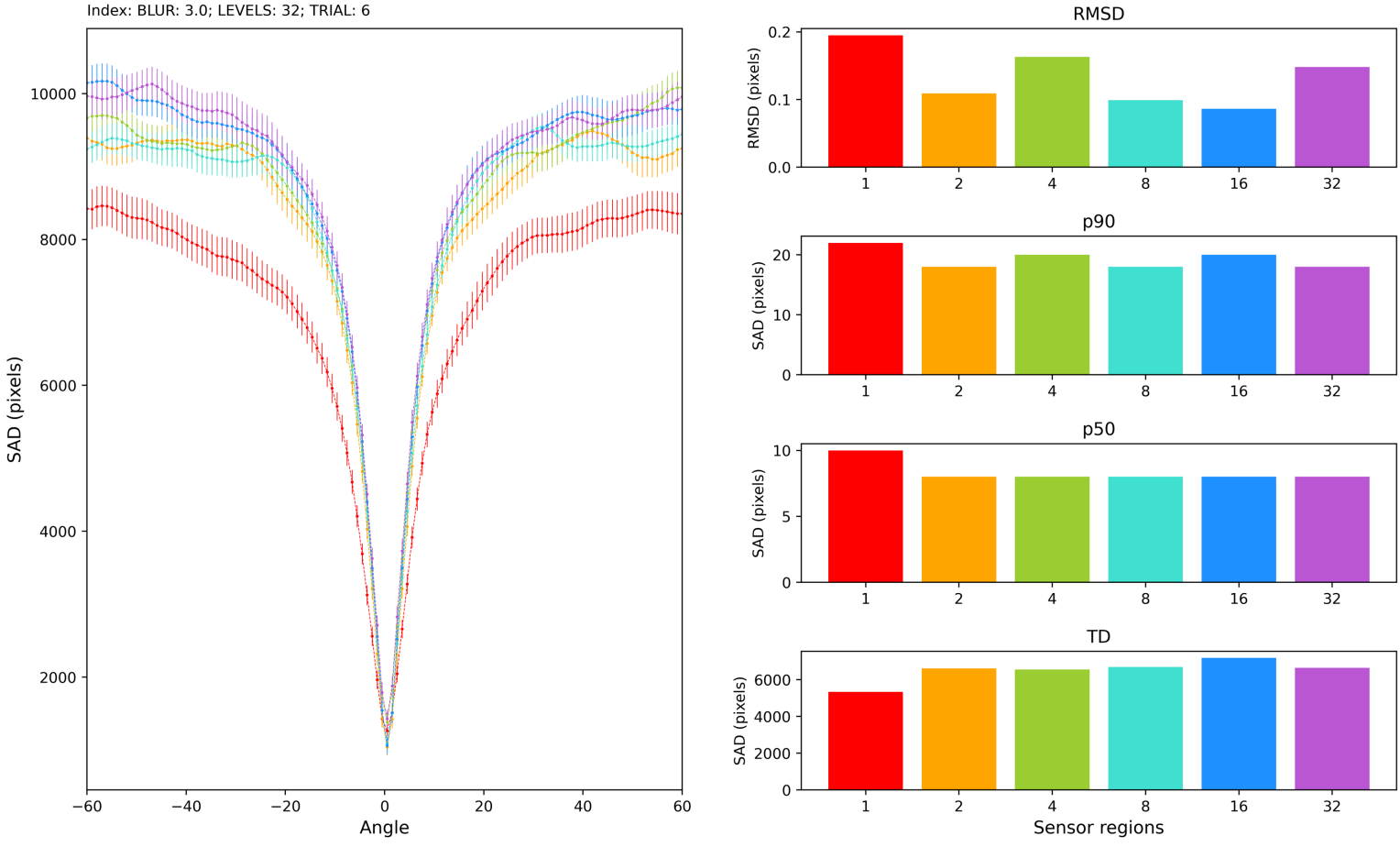
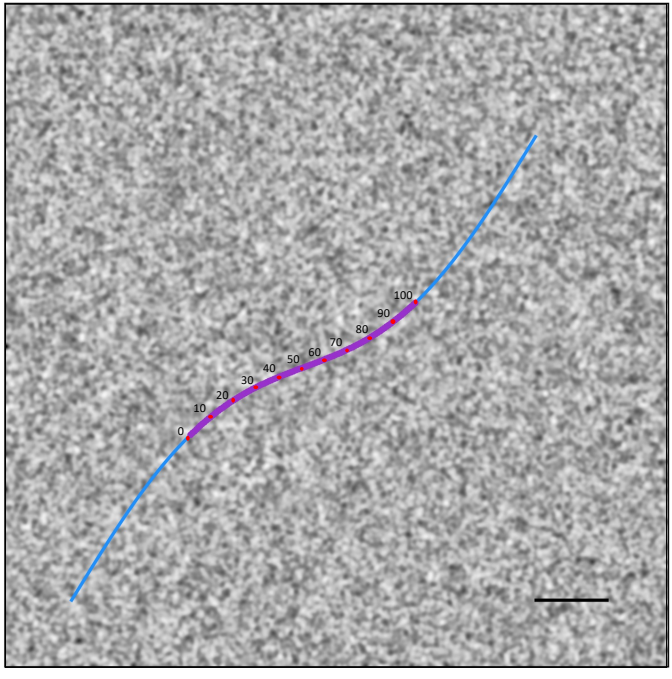
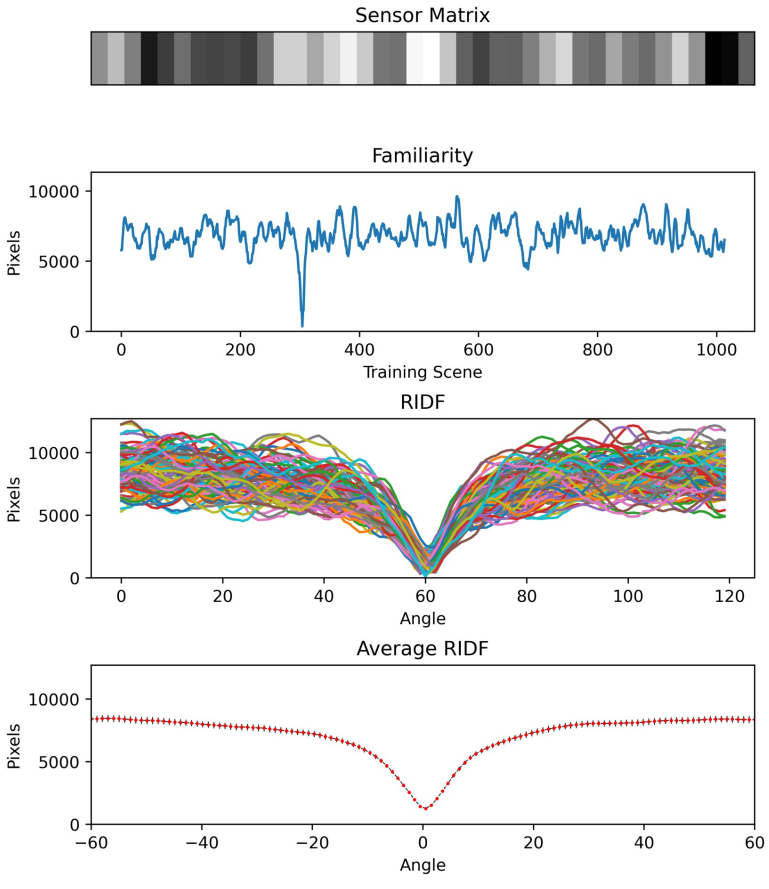
Navigation stats: RMSD error: 49.47; RMSD/dist: 0.124; TD: 7044; p90: 20; p50: 10; complete: 0


Index: BLUR: 3.0; LEVELS: 32; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

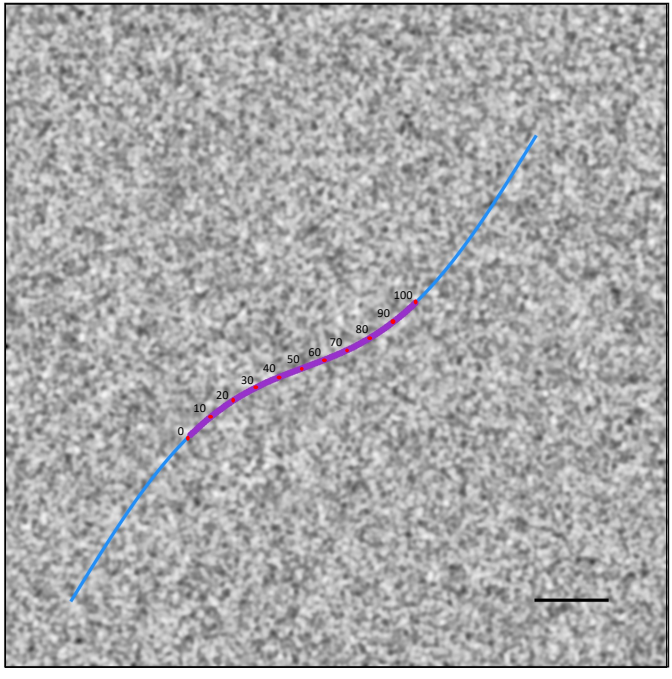


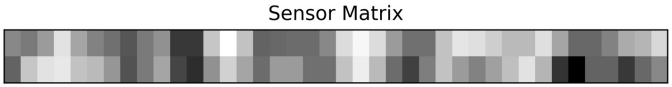


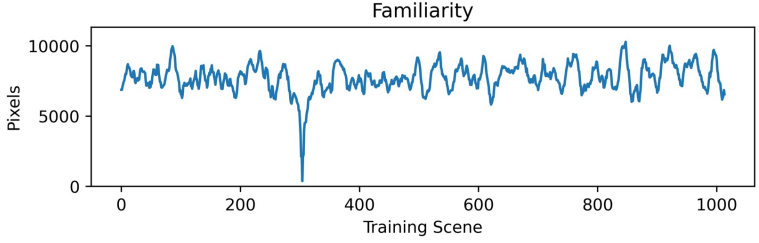
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

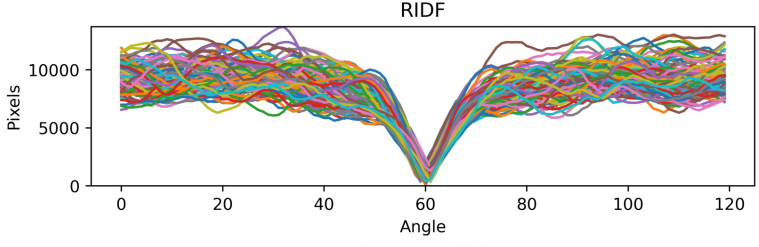
Navigation stats: RMSD error: 77.87; RMSD/dist: 0.195; TD: 5327; p90: 22; p50: 10; complete: 0

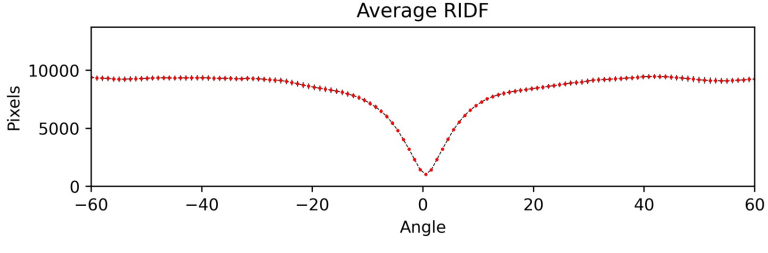
100%







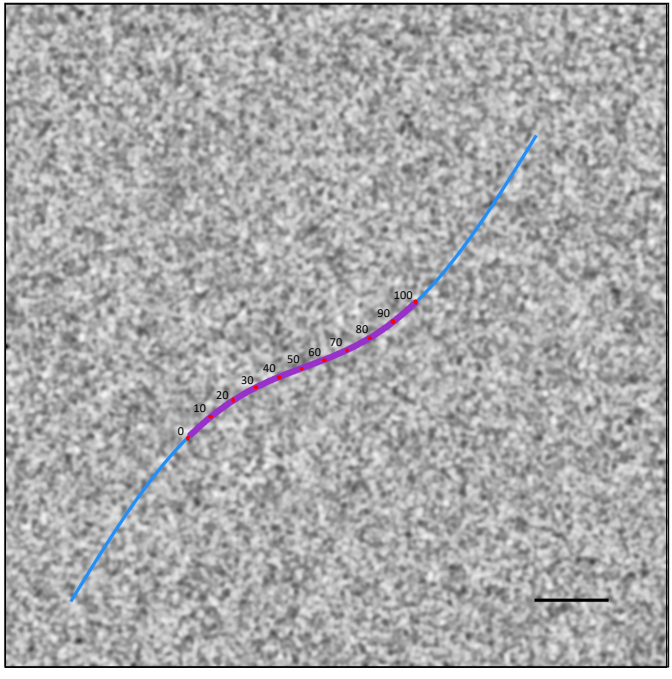


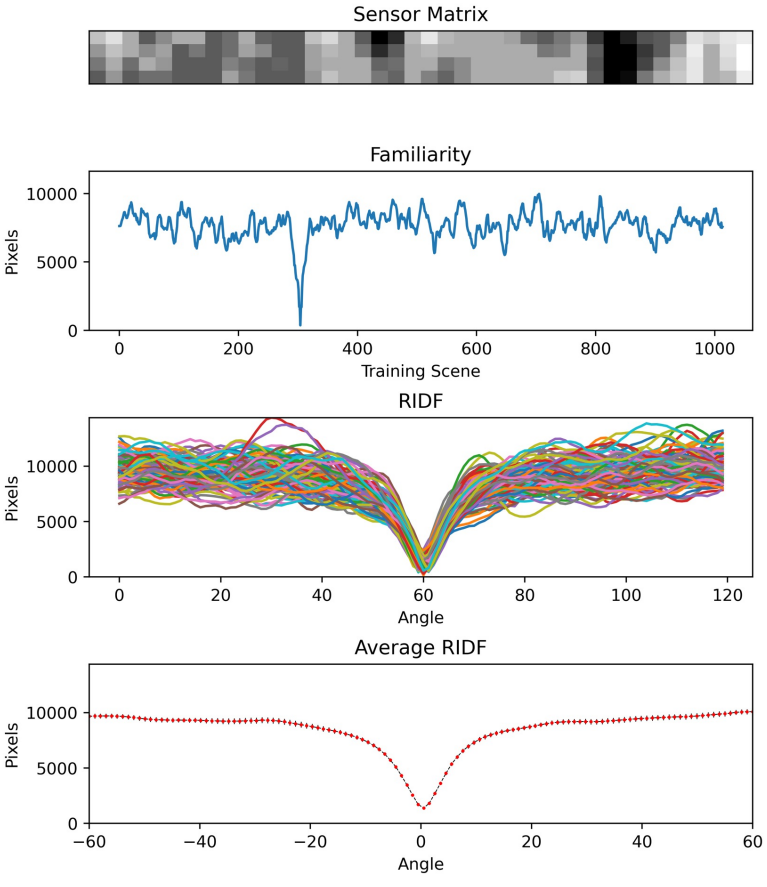


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 43.57; RMSD/dist: 0.109; TD: 6609; p90: 18; p50: 8; complete: 0

100%

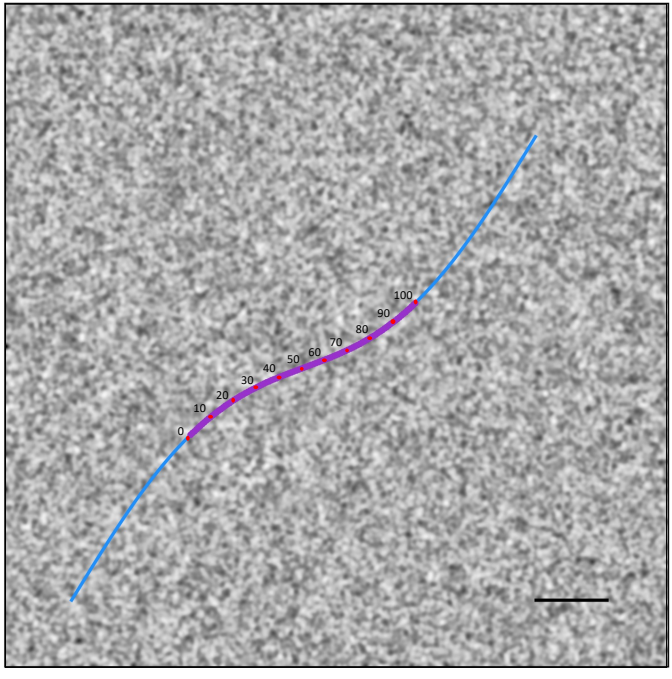


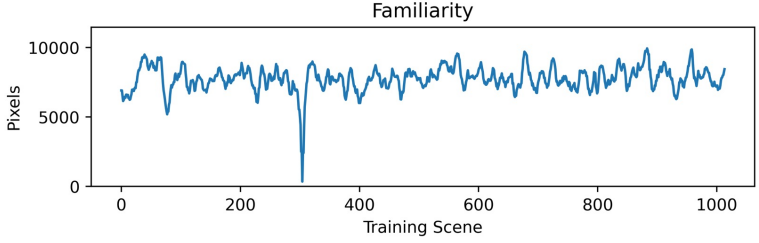


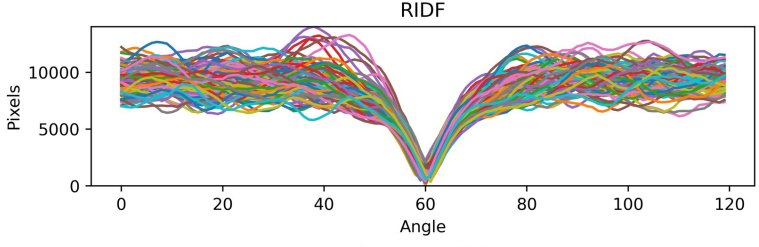
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 6

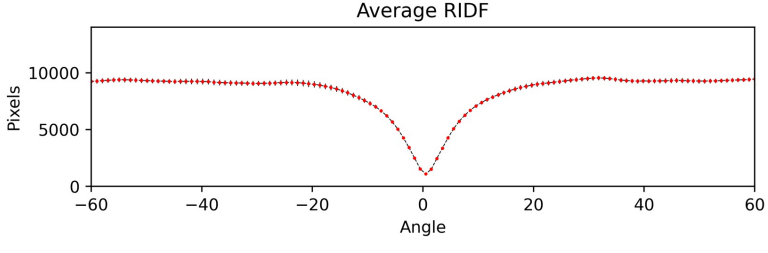
Navigation stats: RMSD error: 65.32; RMSD/dist: 0.163; TD: 6552; p90: 20; p50: 8; complete: 0

100%





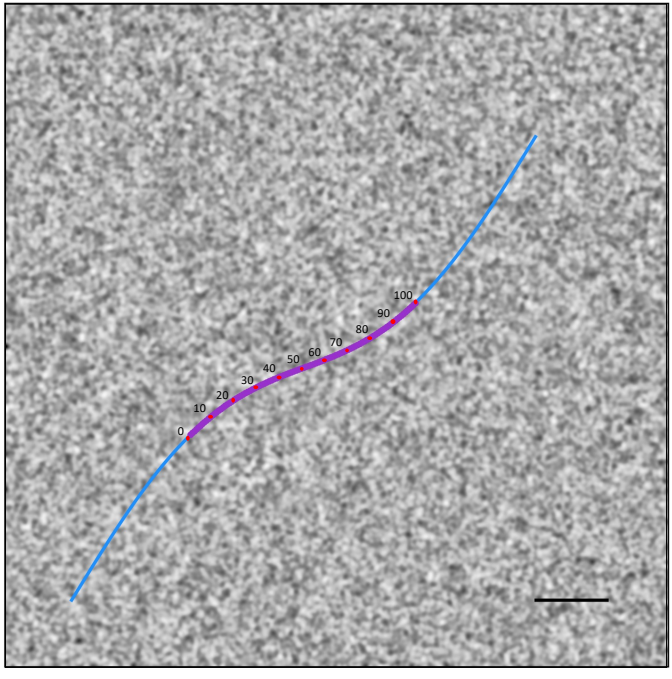


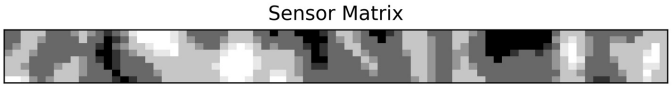


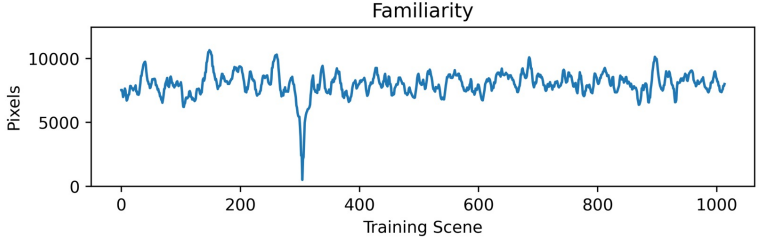
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

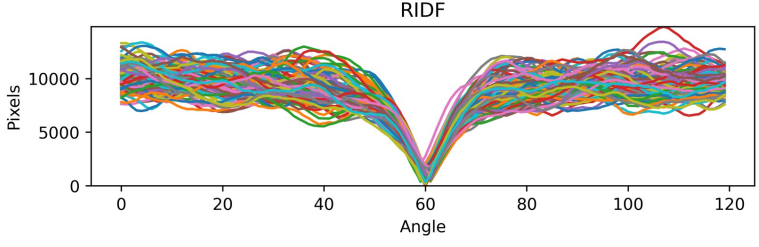
Navigation stats: RMSD error: 39.68; RMSD/dist: 0.099; TD: 6680; p90: 18; p50: 8; complete: 0

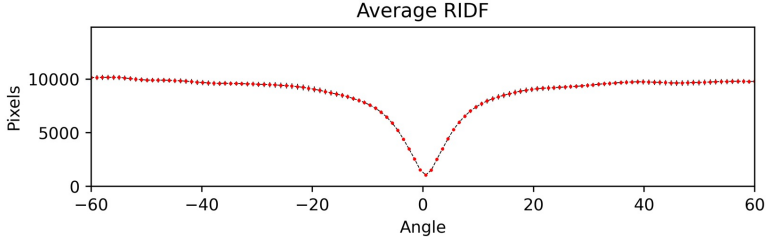
100%







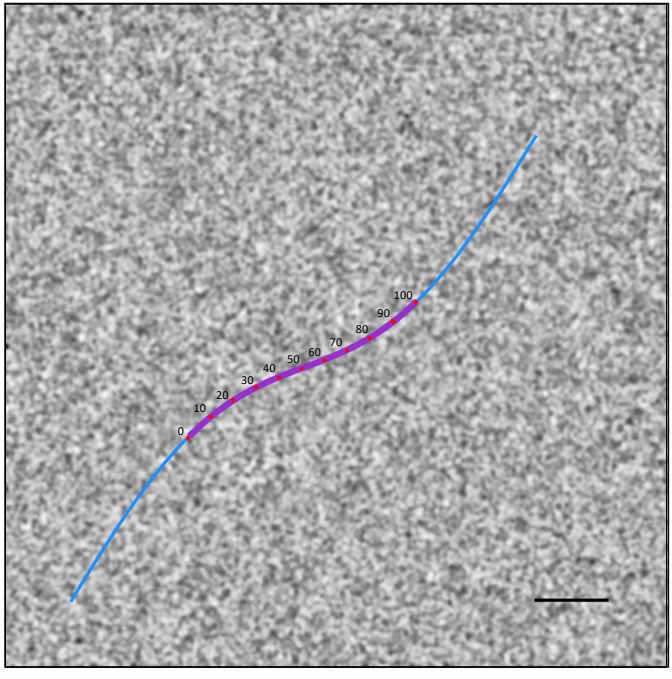


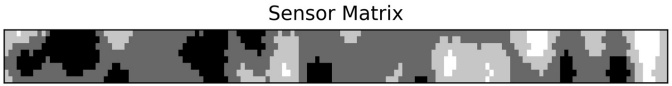


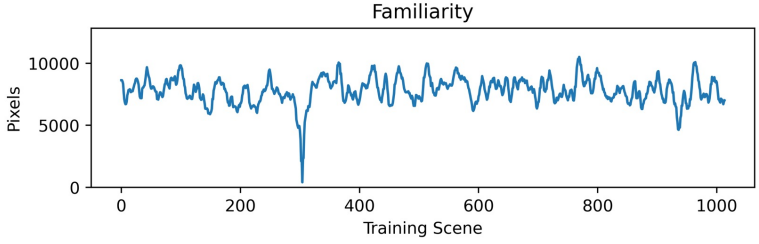
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 6

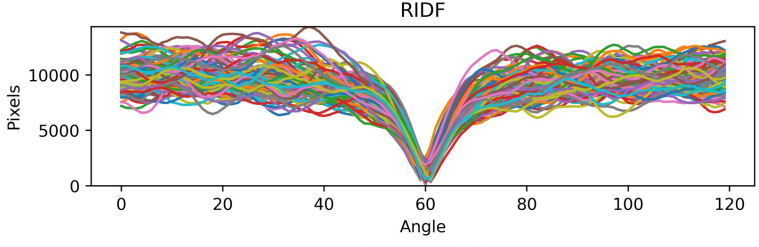
Navigation stats: RMSD error: 34.21; RMSD/dist: 0.086; TD: 7174; p90: 20; p50: 8; complete: 0

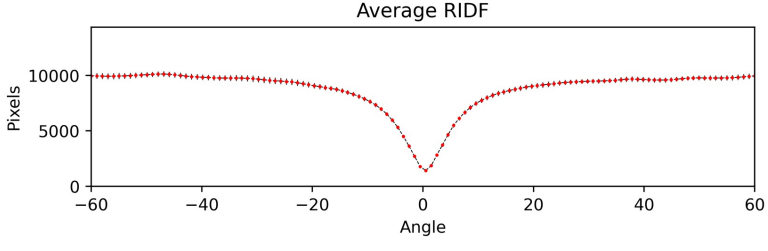
100%





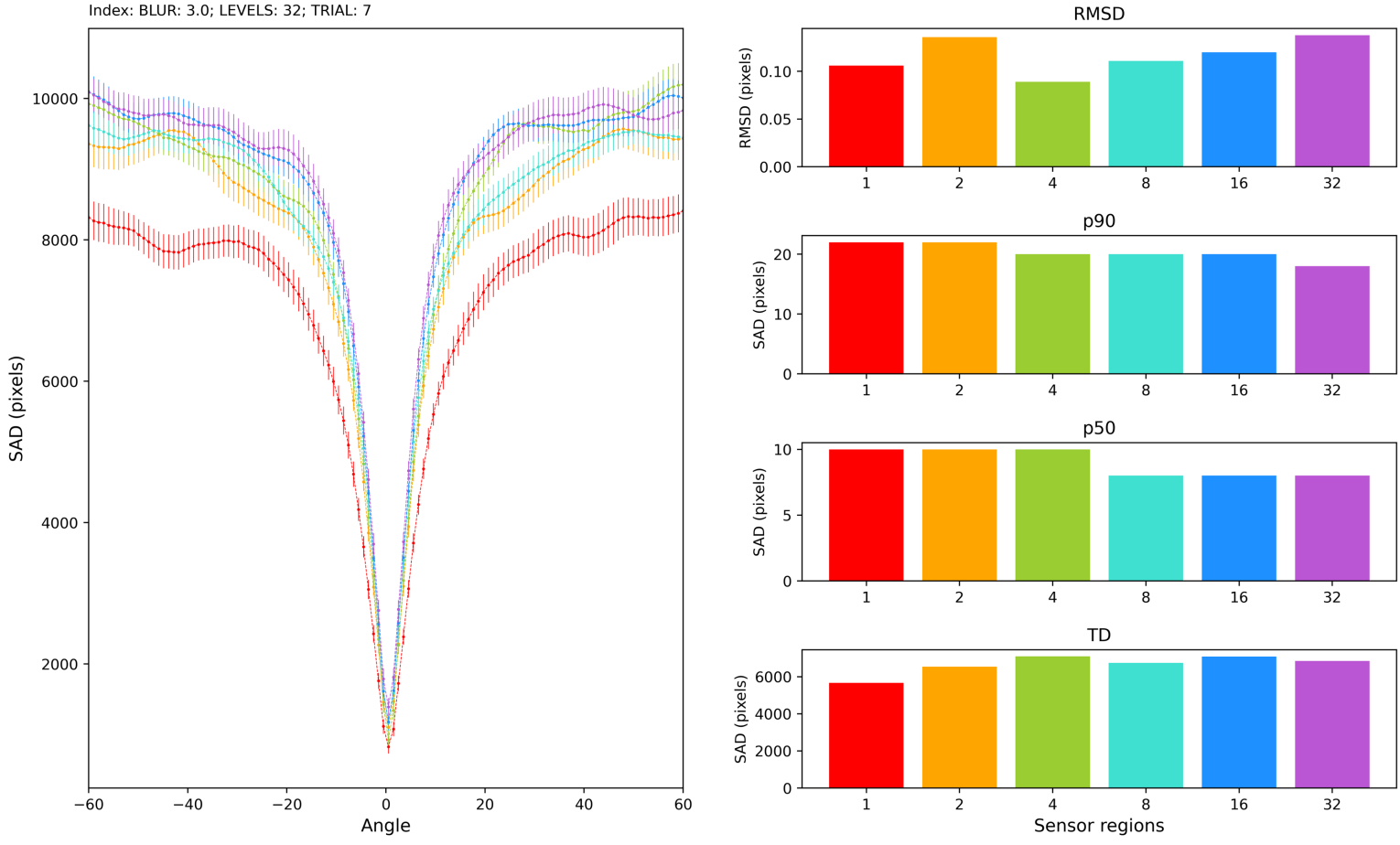




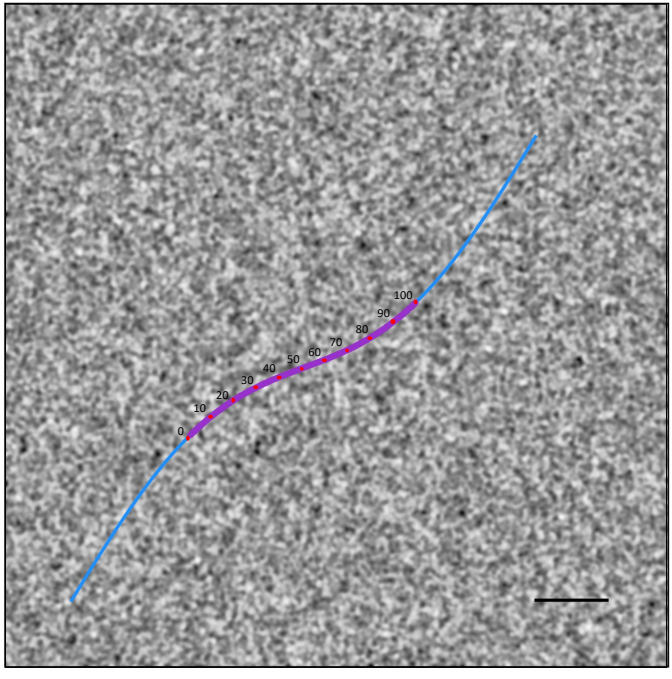


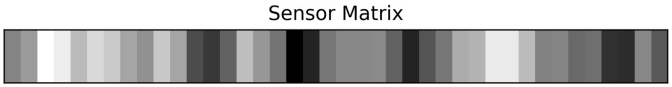
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 6

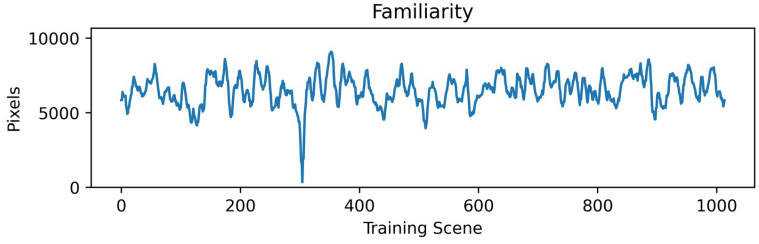
Navigation stats: RMSD error: 59.28; RMSD/dist: 0.148; TD: 6641; p90: 18; p50: 8; complete: 0

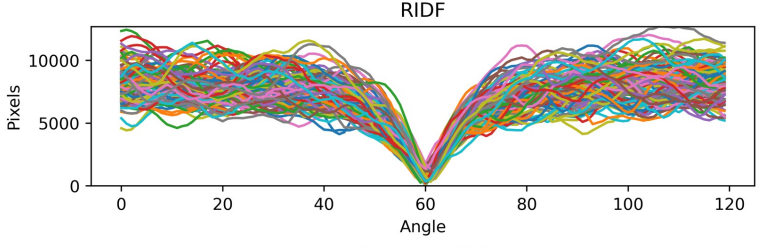

Index: BLUR: 3.0; LEVELS: 32; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

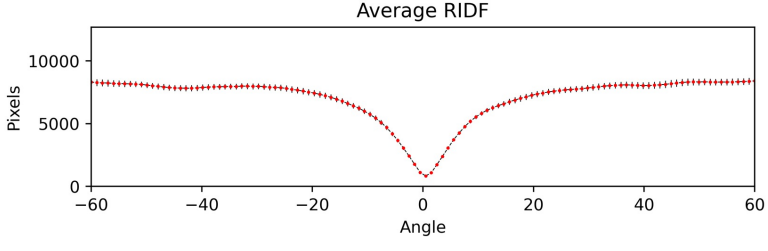
100%







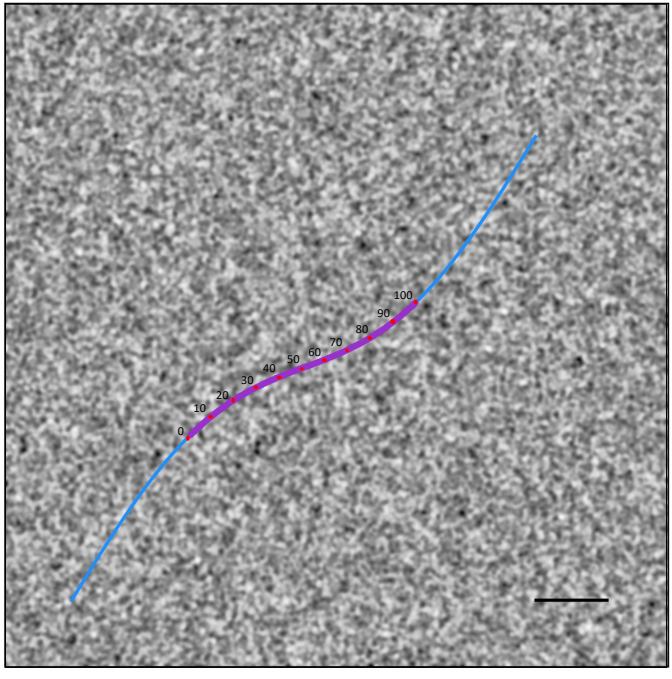


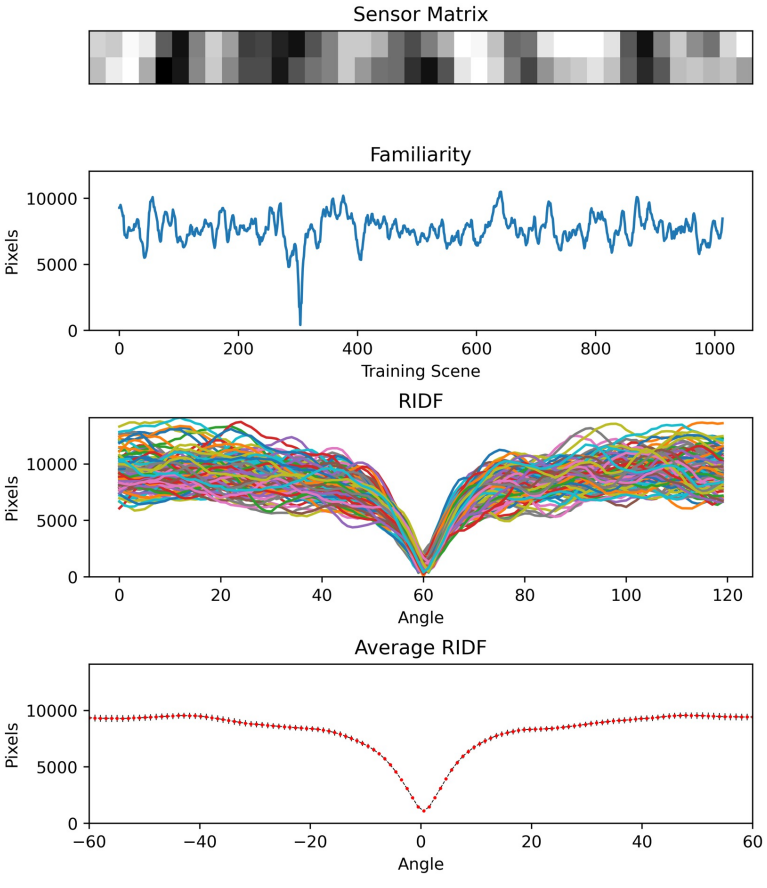


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 42.48; RMSD/dist: 0.106; TD: 5667; p90: 22; p50: 10; complete: 0

100%

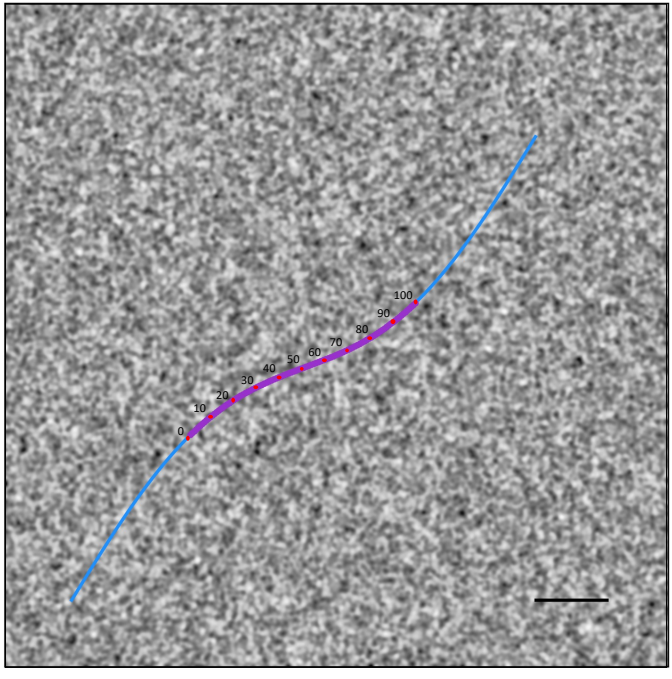


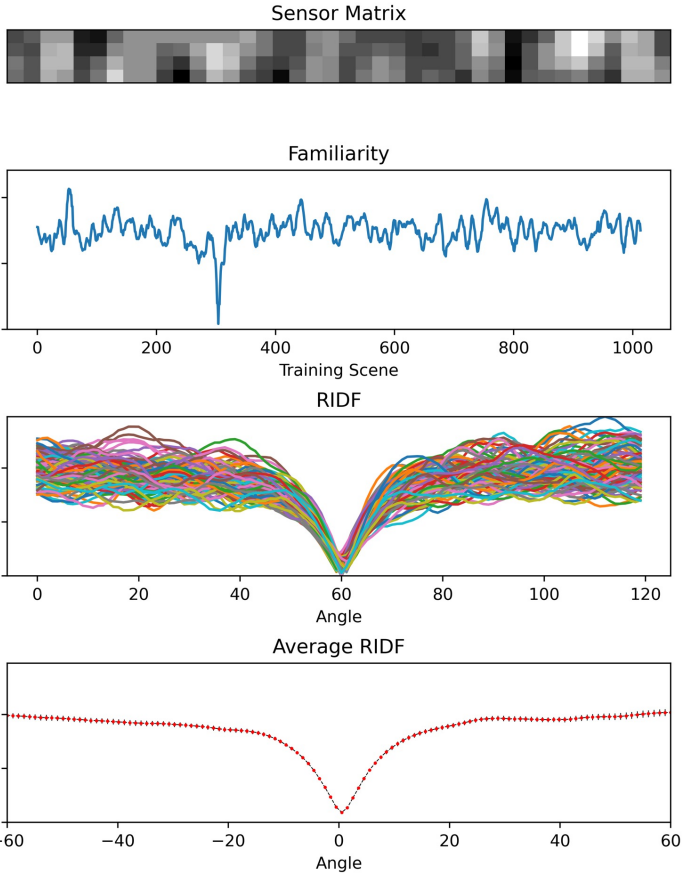


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 54.56; RMSD/dist: 0.136; TD: 6542; p90: 22; p50: 10; complete: 0

100%

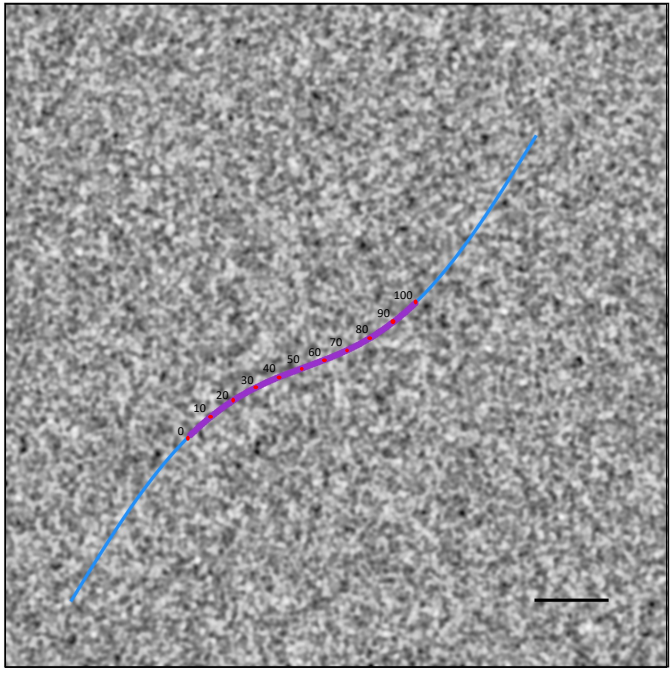


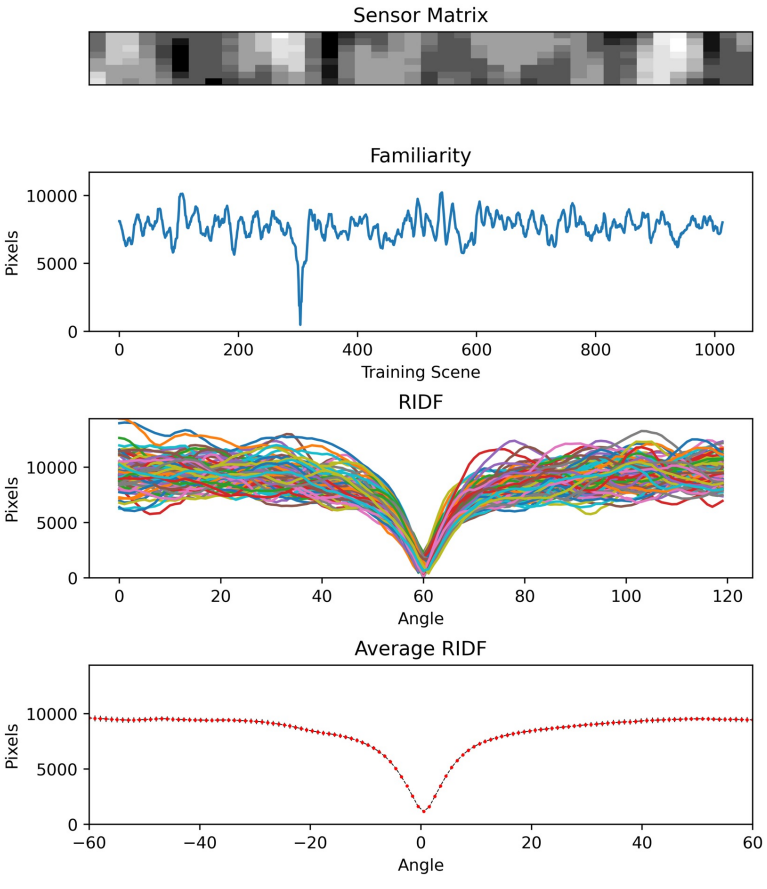


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 35.76; RMSD/dist: 0.089; TD: 7092; p90: 20; p50: 10; complete: 0

100%

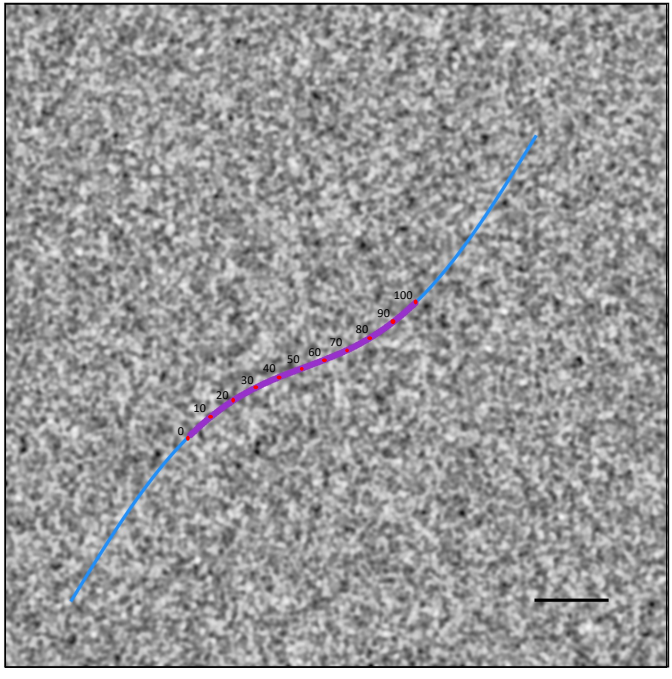


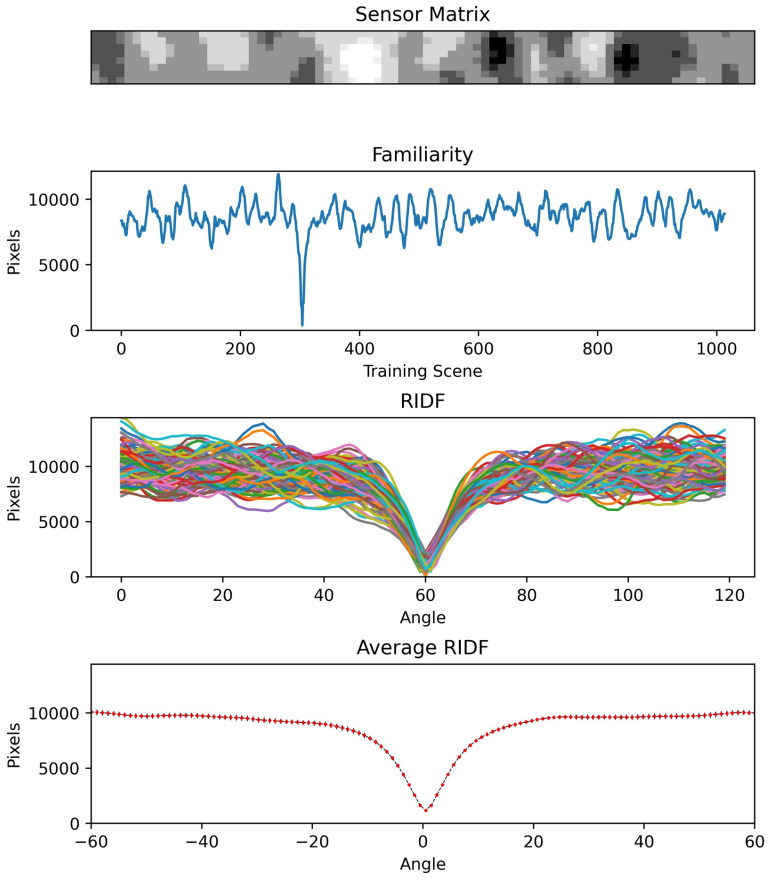


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 44.20; RMSD/dist: 0.111; TD: 6745; p90: 20; p50: 8; complete: 0

100%

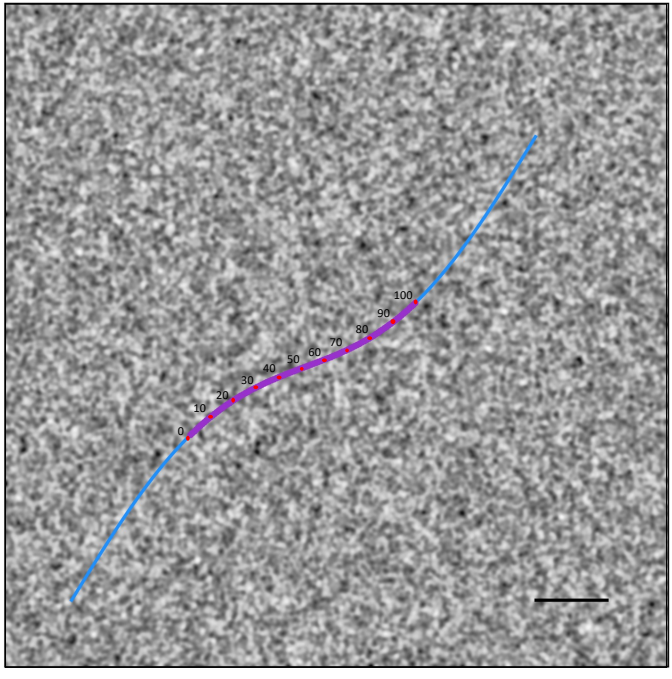


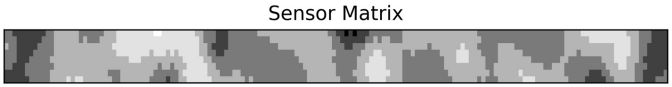


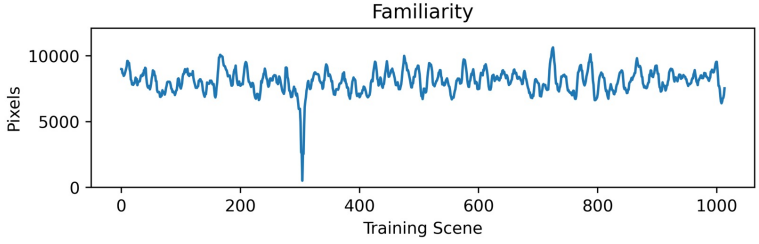
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

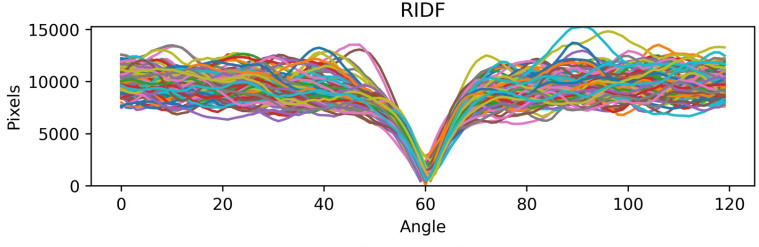
Navigation stats: RMSD error: 47.97; RMSD/dist: 0.120; TD: 7083; p90: 20; p50: 8; complete: 0

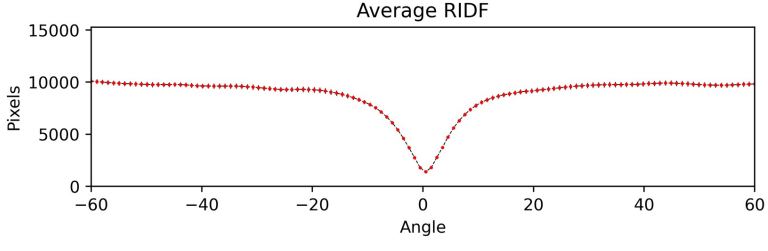
100%





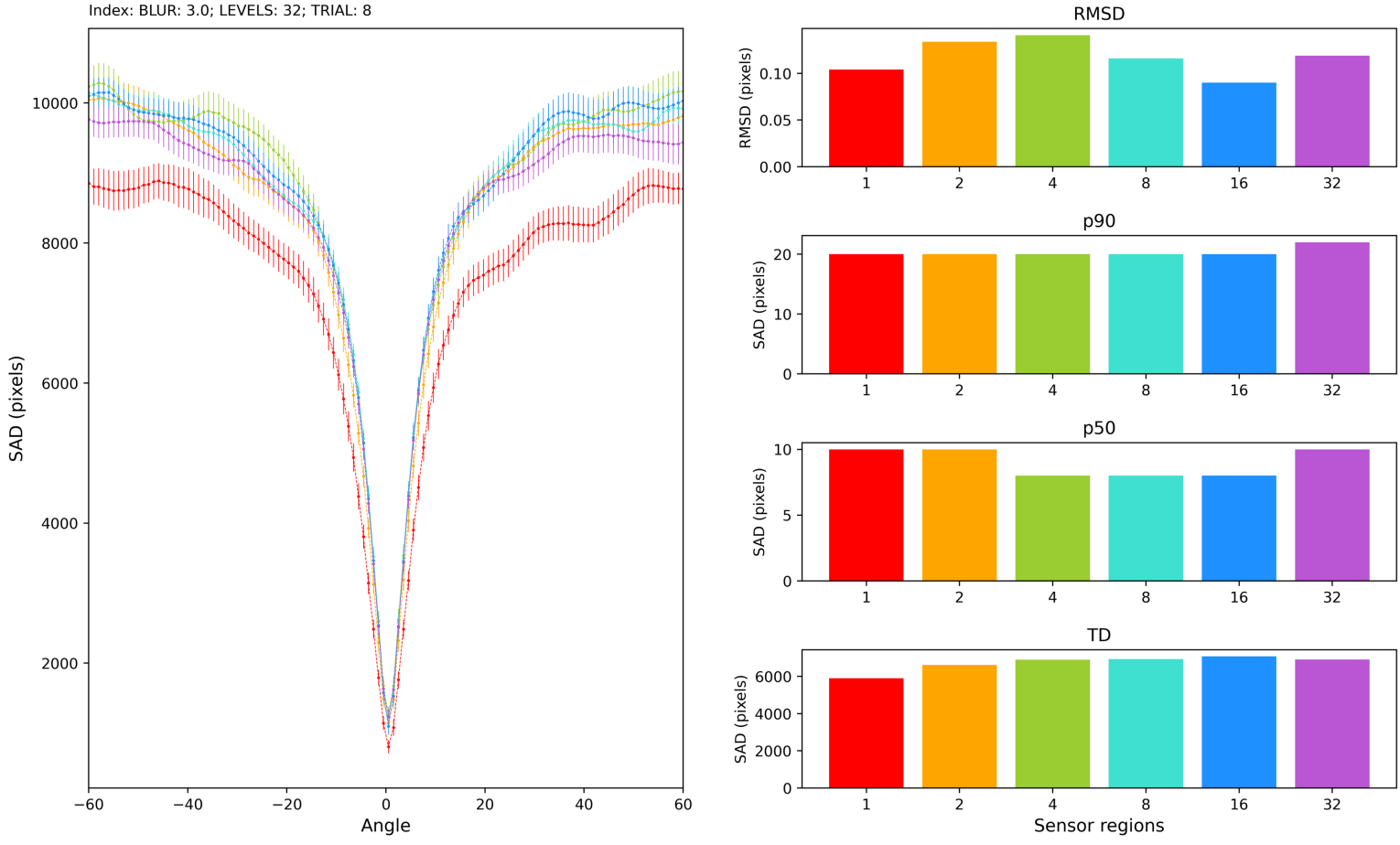




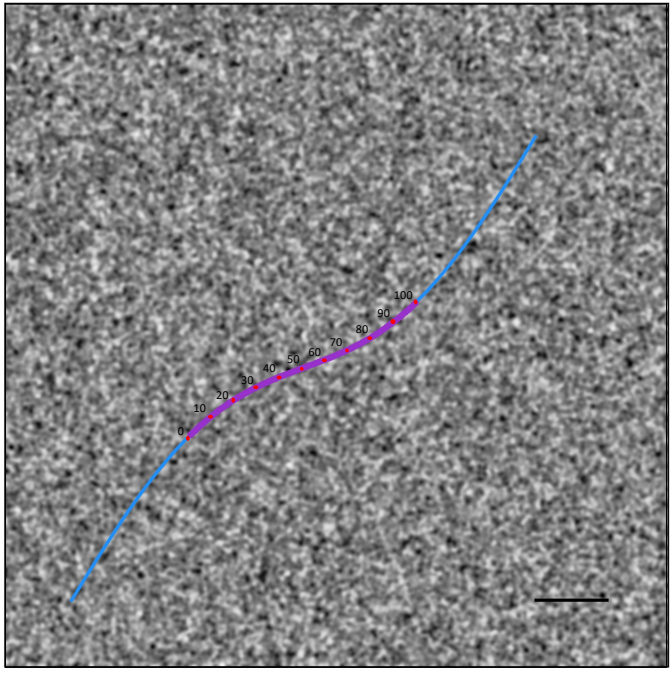


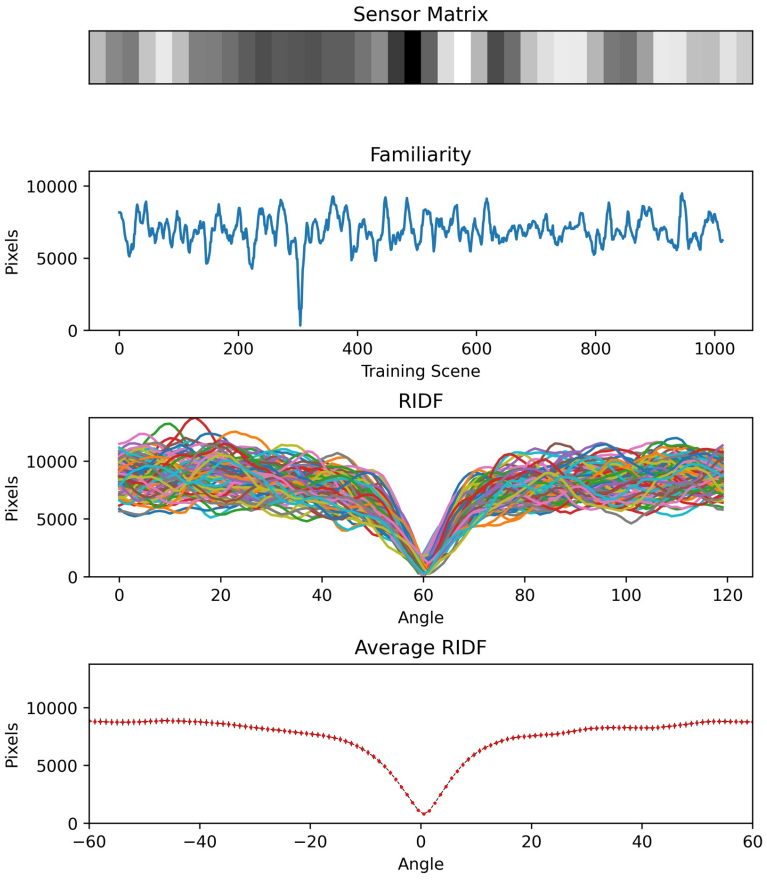
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 55.21; RMSD/dist: 0.138; TD: 6853; p90: 18; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 32; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

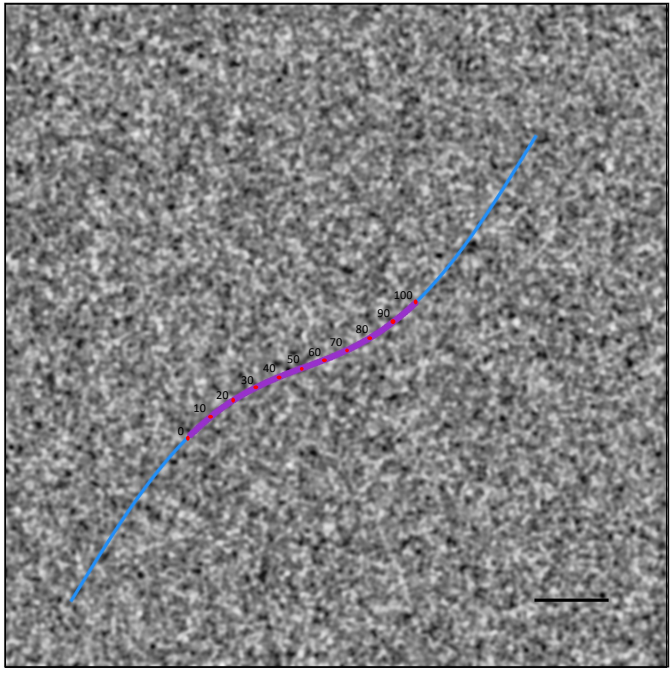


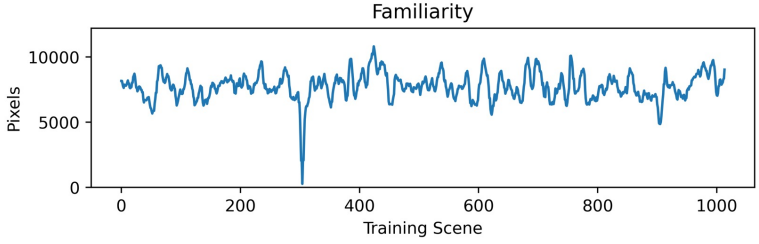


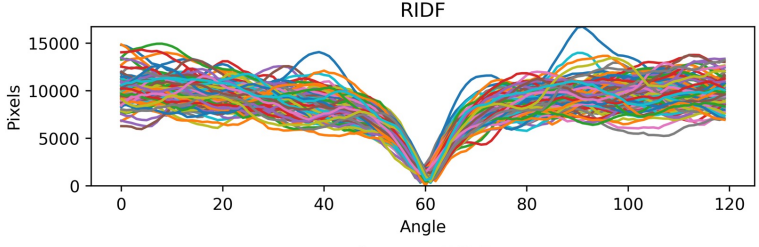
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

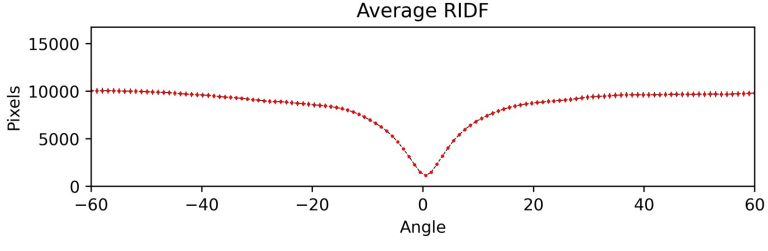
Navigation stats: RMSD error: 41.49; RMSD/dist: 0.104; TD: 5902; p90: 20; p50: 10; complete: 0

100%





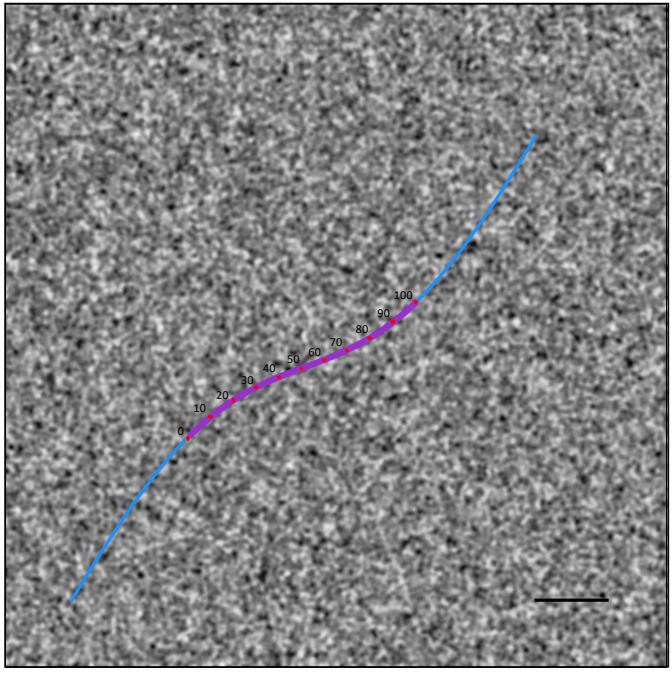


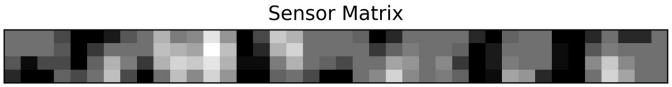


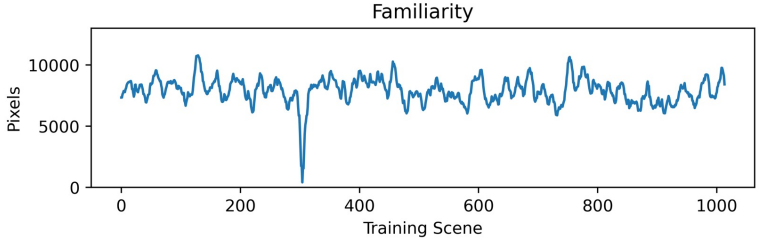
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

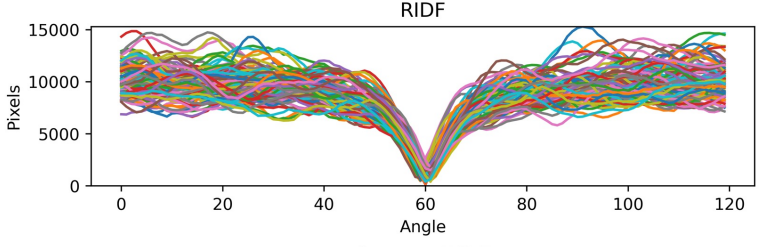
Navigation stats: RMSD error: 53.59; RMSD/dist: 0.134; TD: 6618; p90: 20; p50: 10; complete: 0

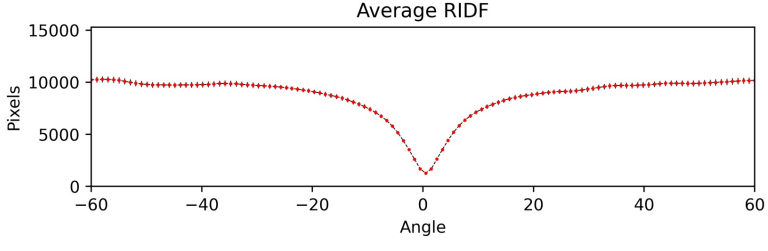
100%







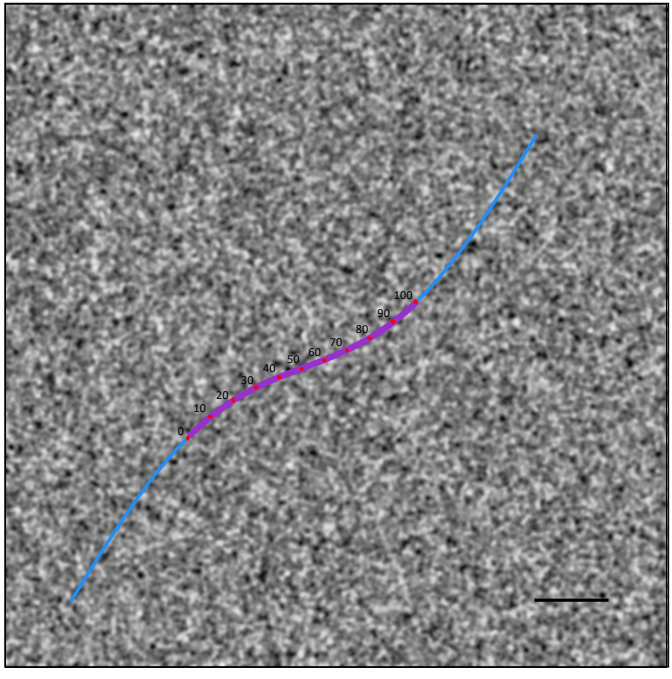


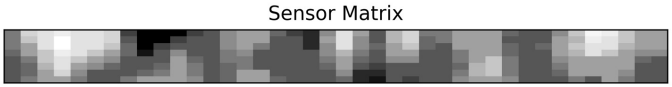


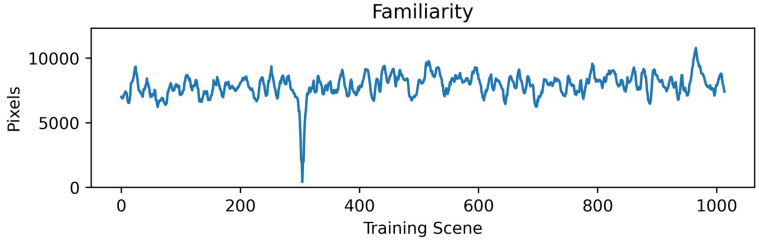
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

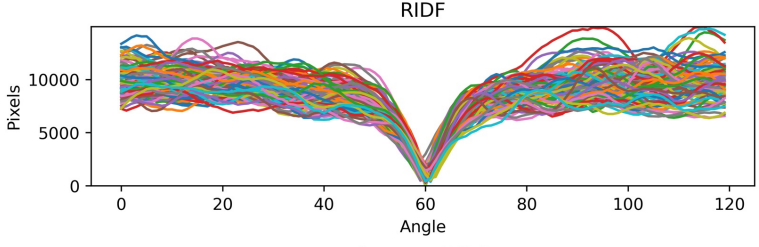
Navigation stats: RMSD error: 56.51; RMSD/dist: 0.141; TD: 6902; p90: 20; p50: 8; complete: 0

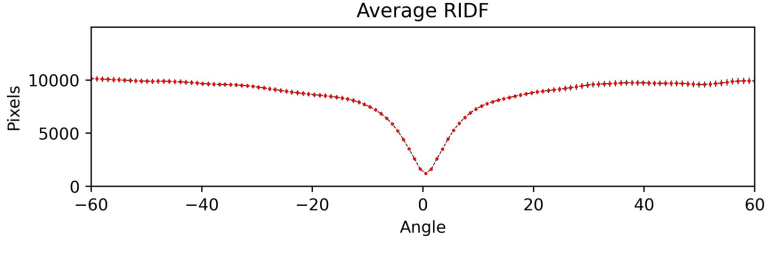
100%







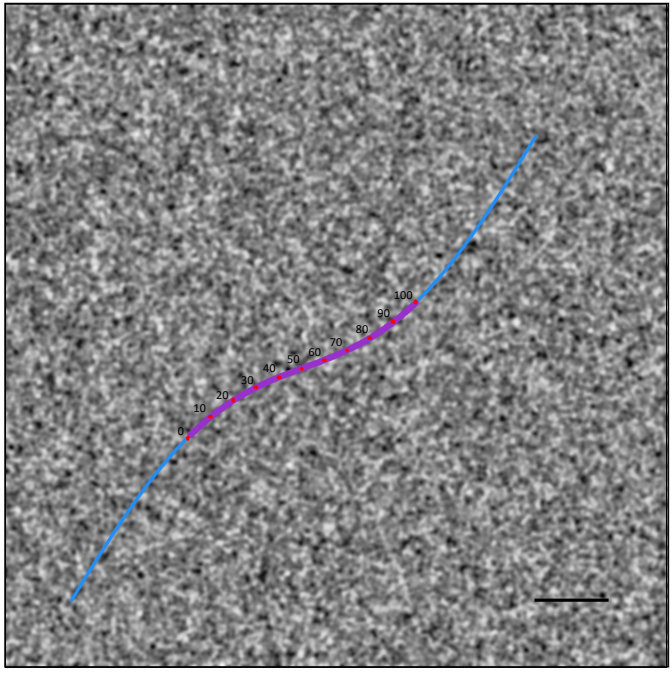


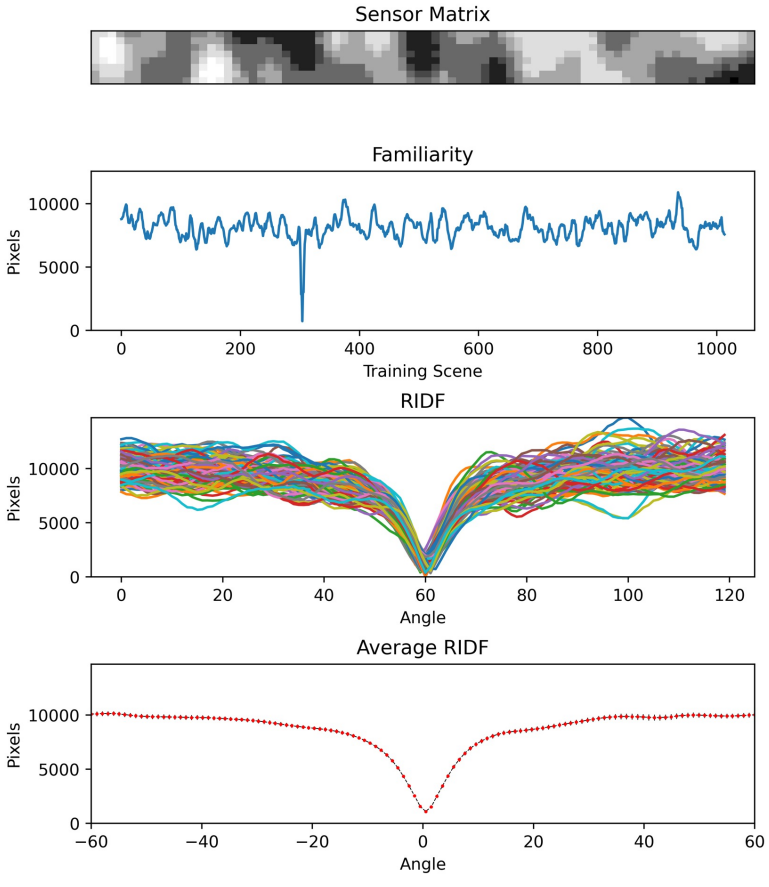


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 46.34; RMSD/dist: 0.116; TD: 6933; p90: 20; p50: 8; complete: 0

100%

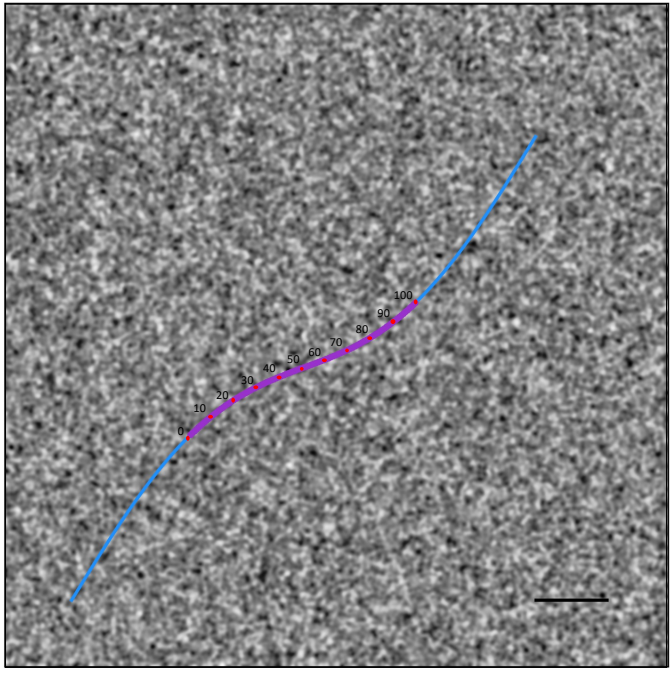


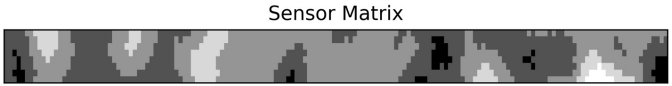


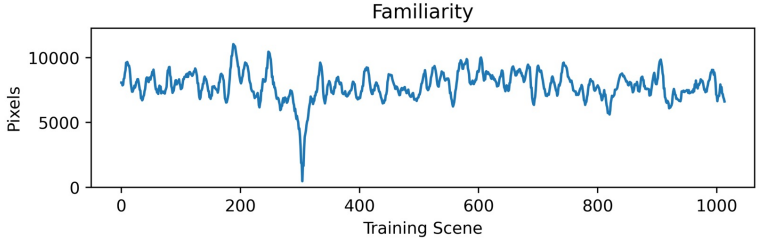
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

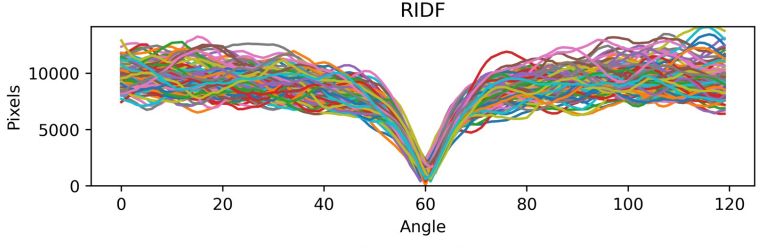
Navigation stats: RMSD error: 36.07; RMSD/dist: 0.090; TD: 7074; p90: 20; p50: 8; complete: 0

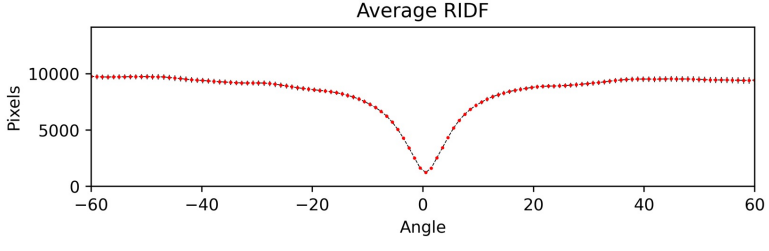
100%





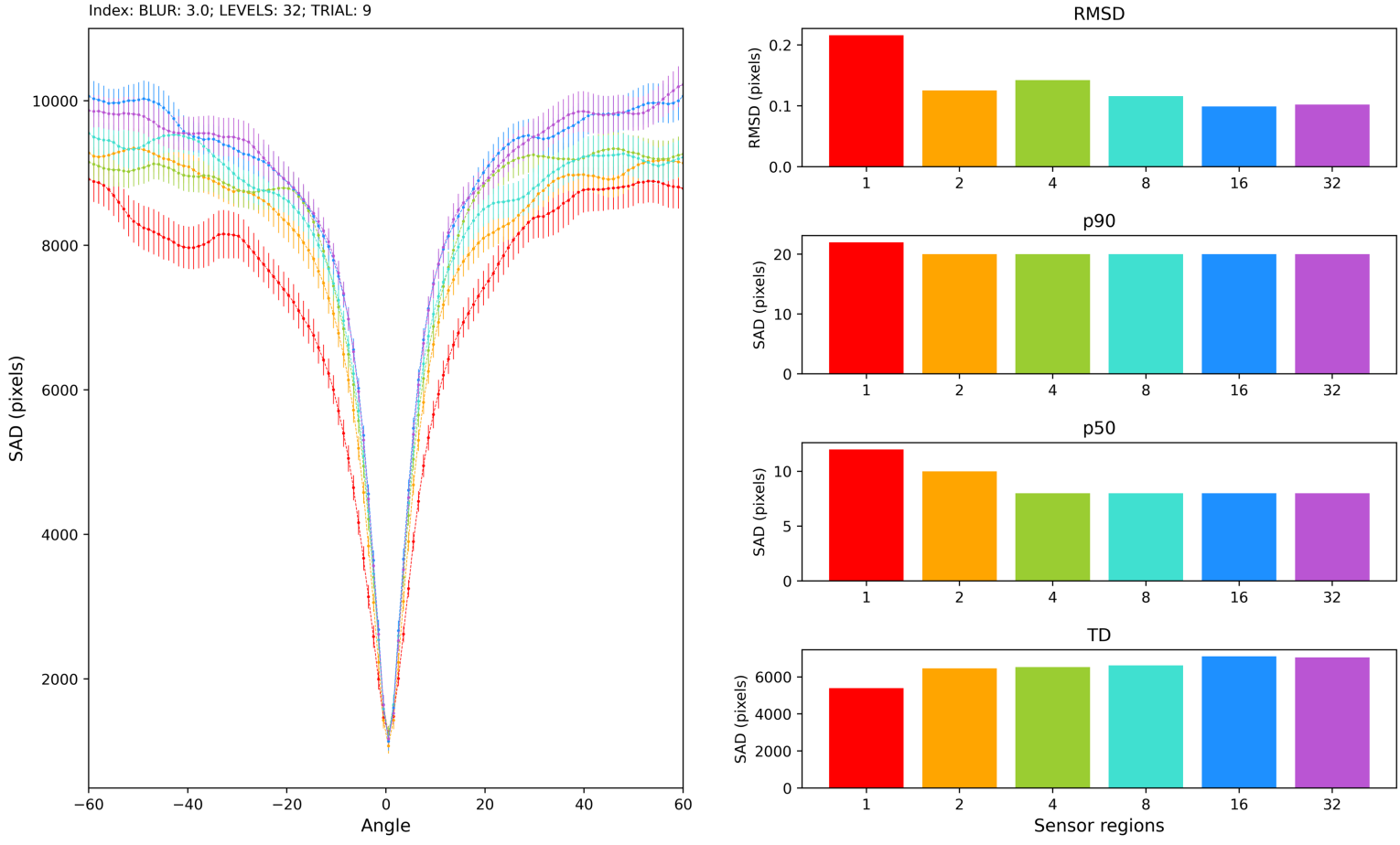




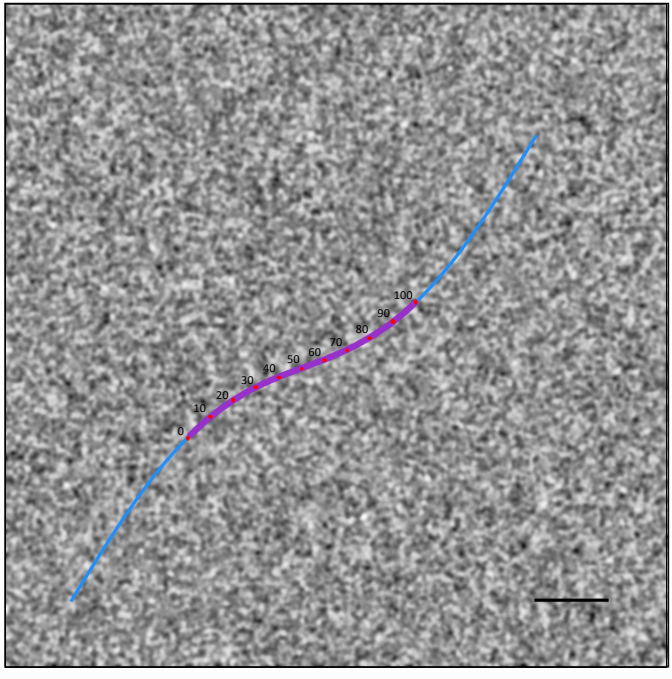


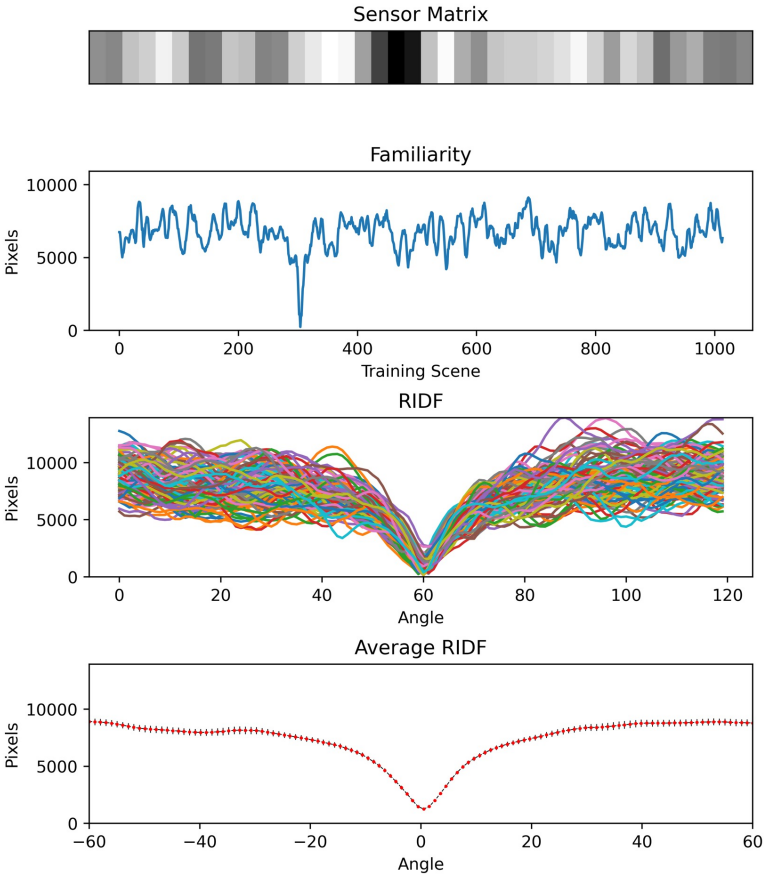
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 47.60; RMSD/dist: 0.119; TD: 6907; p90: 22; p50: 10; complete: 0


Index: BLUR: 3.0; LEVELS: 32; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

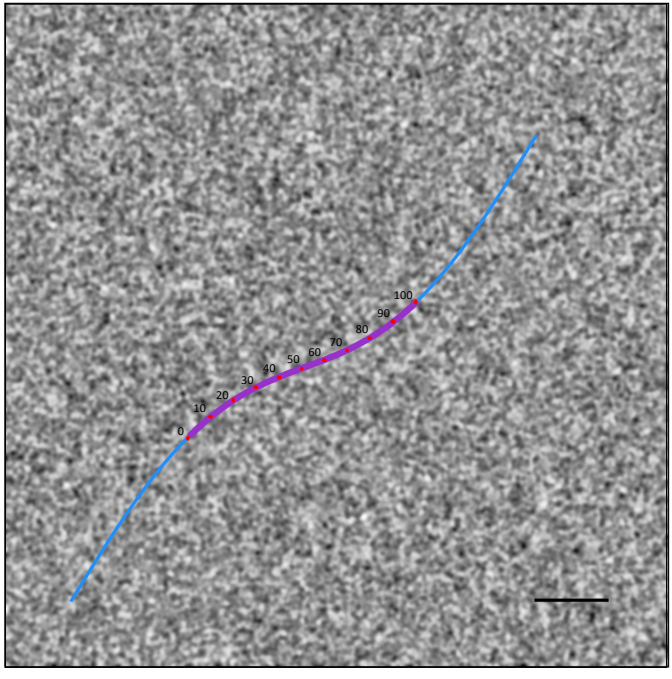


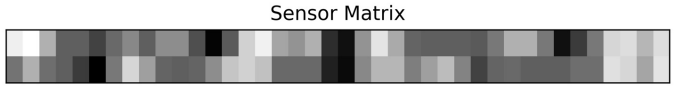


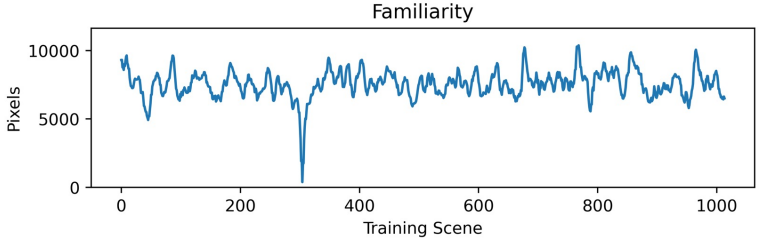
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

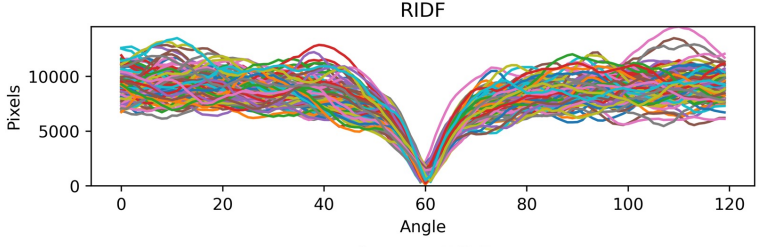
Navigation stats: RMSD error: 86.24; RMSD/dist: 0.216; TD: 5391; p90: 22; p50: 12; complete: 0

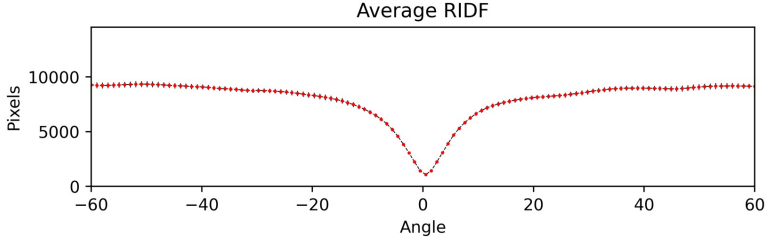
100%







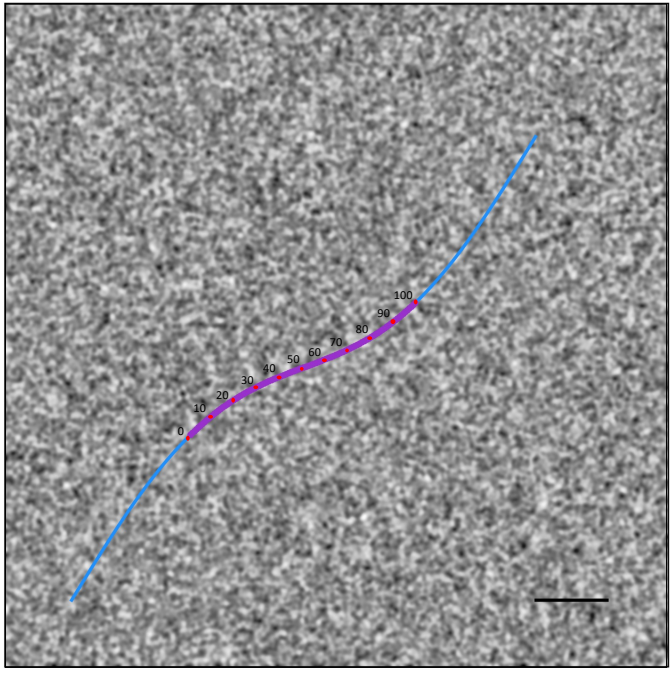


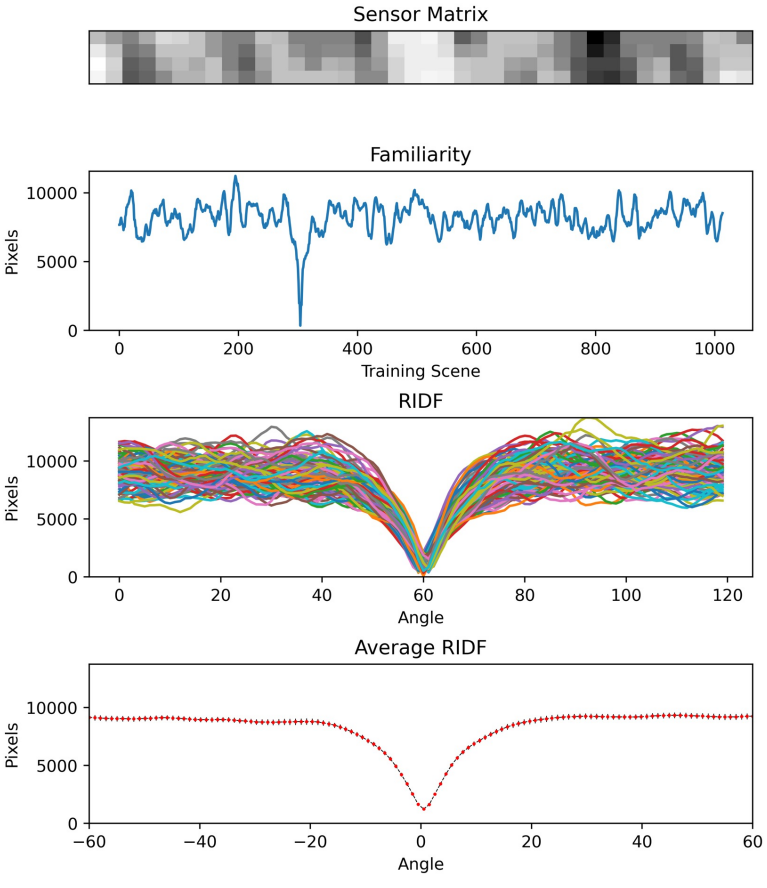


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 49.80; RMSD/dist: 0.125; TD: 6467; p90: 20; p50: 10; complete: 0

100%

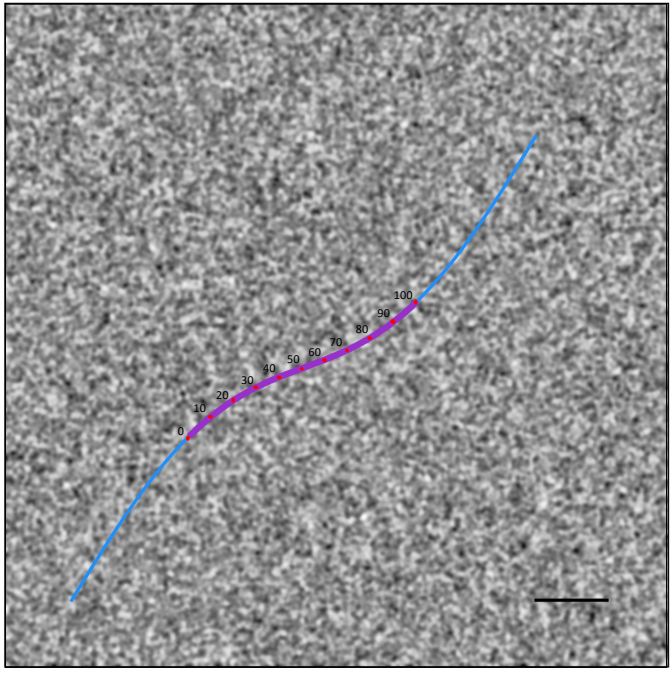


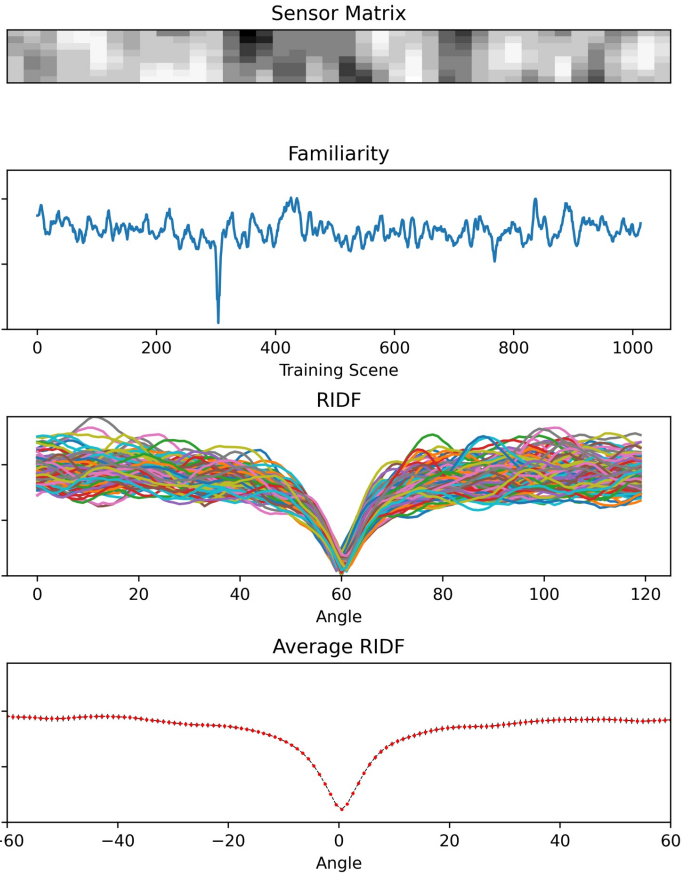


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 56.99; RMSD/dist: 0.142; TD: 6534; p90: 20; p50: 8; complete: 0

100%

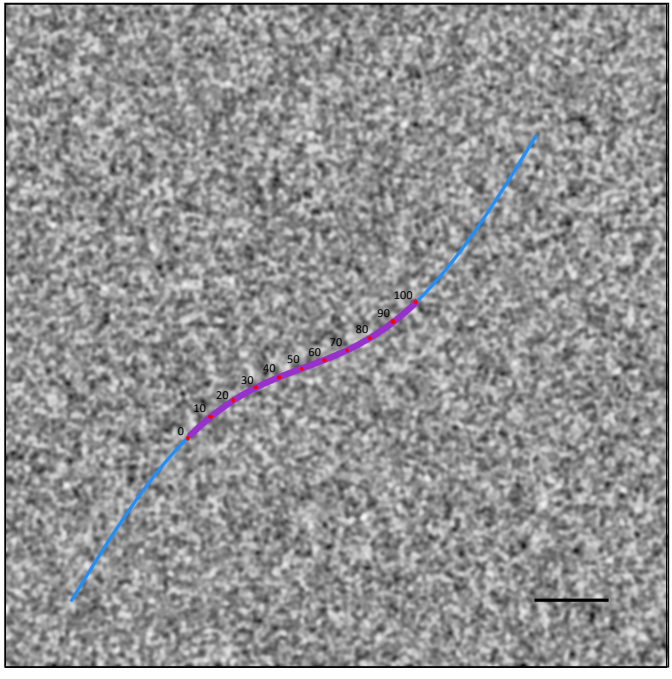


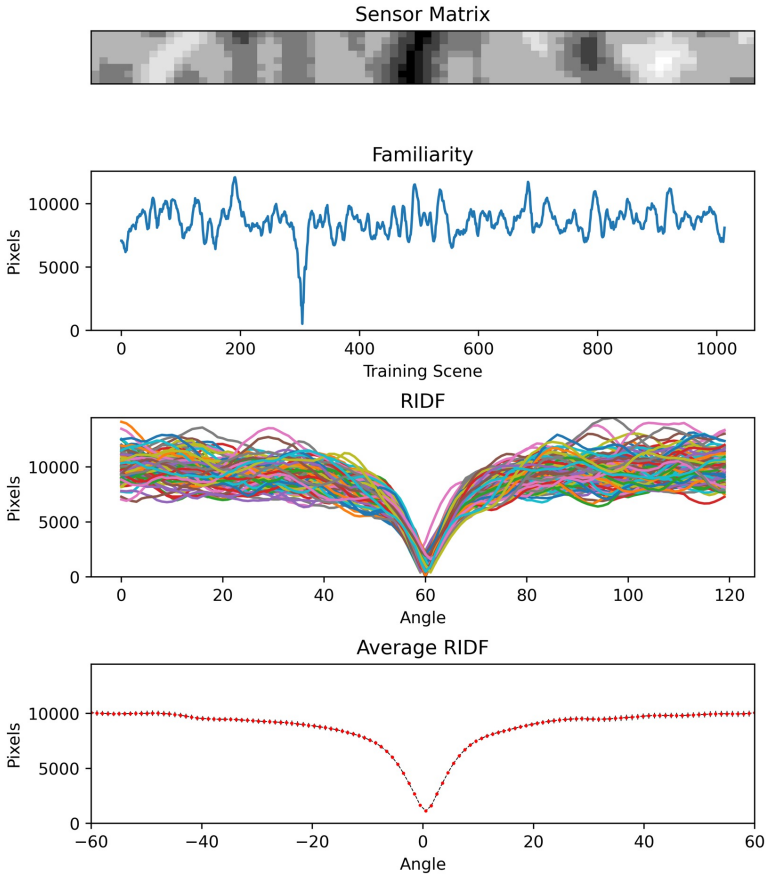


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 46.43; RMSD/dist: 0.116; TD: 6626; p90: 20; p50: 8; complete: 0

100%

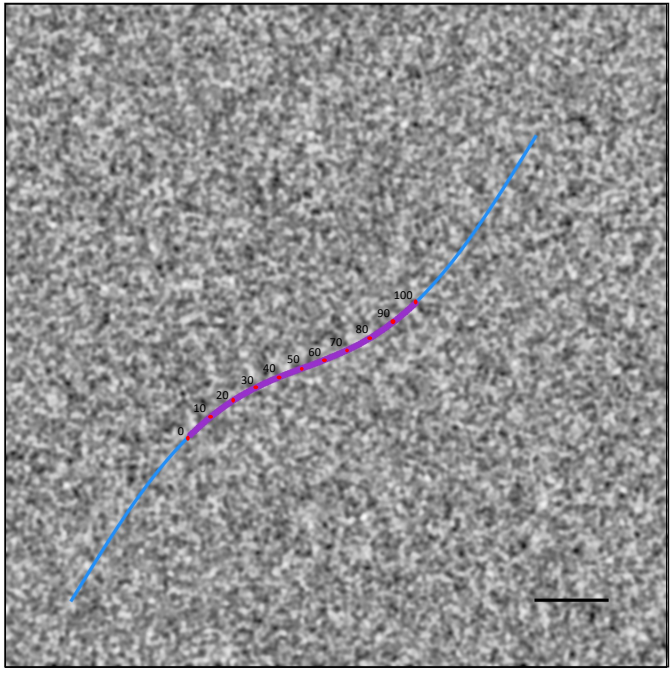


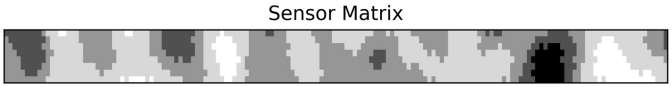


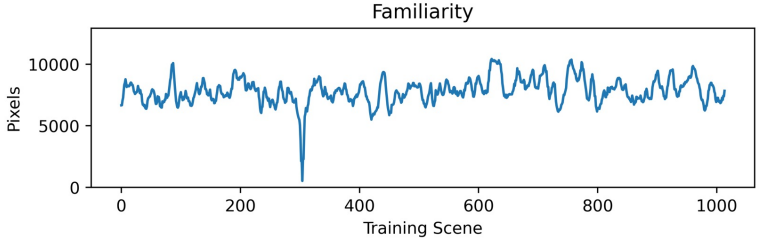
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

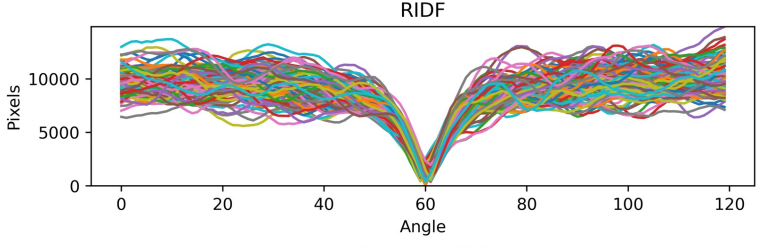
Navigation stats: RMSD error: 39.70; RMSD/dist: 0.099; TD: 7105; p90: 20; p50: 8; complete: 0

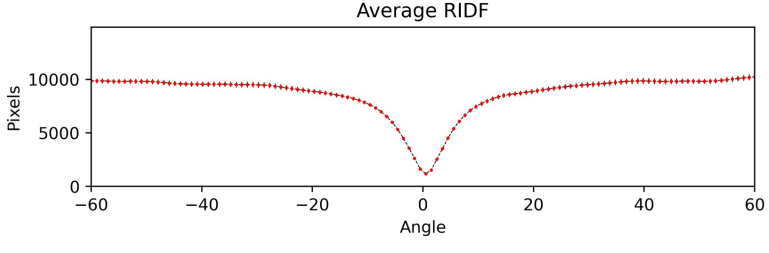
100%





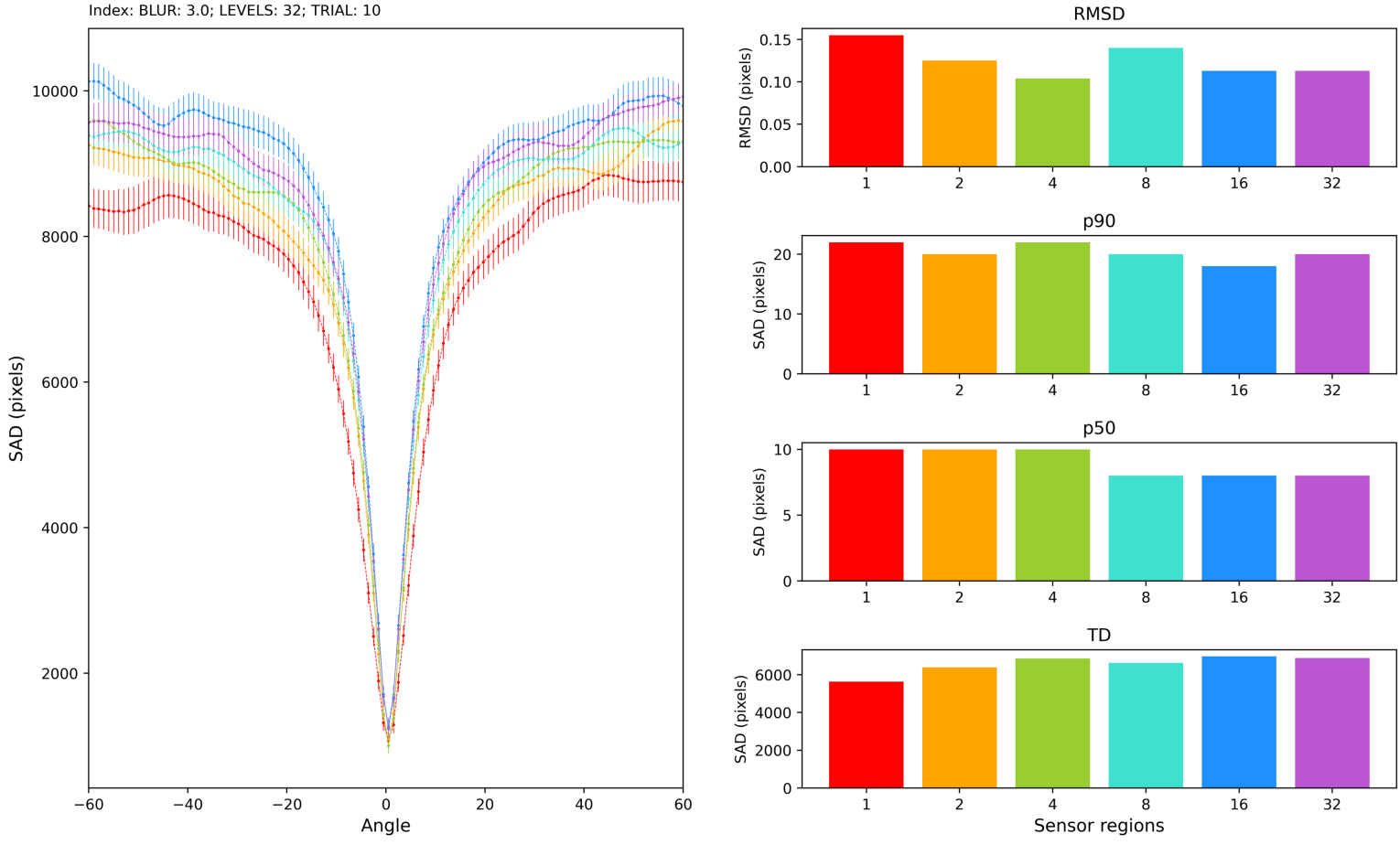




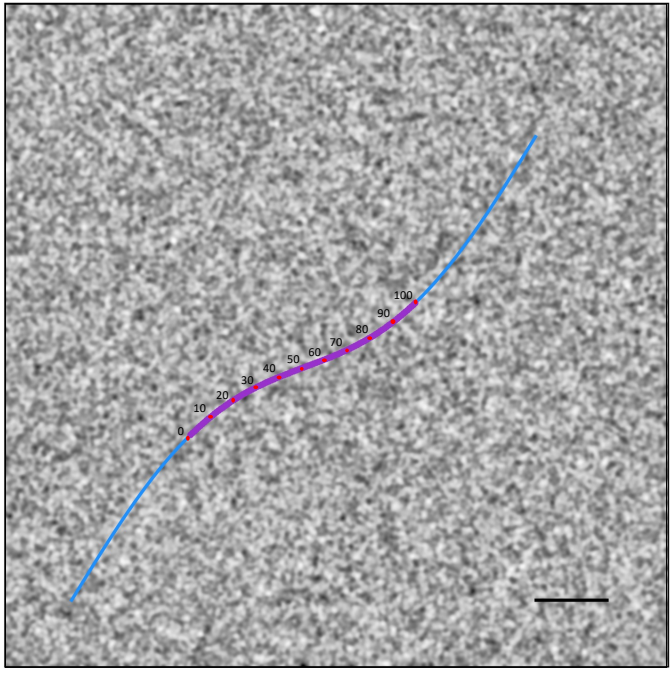


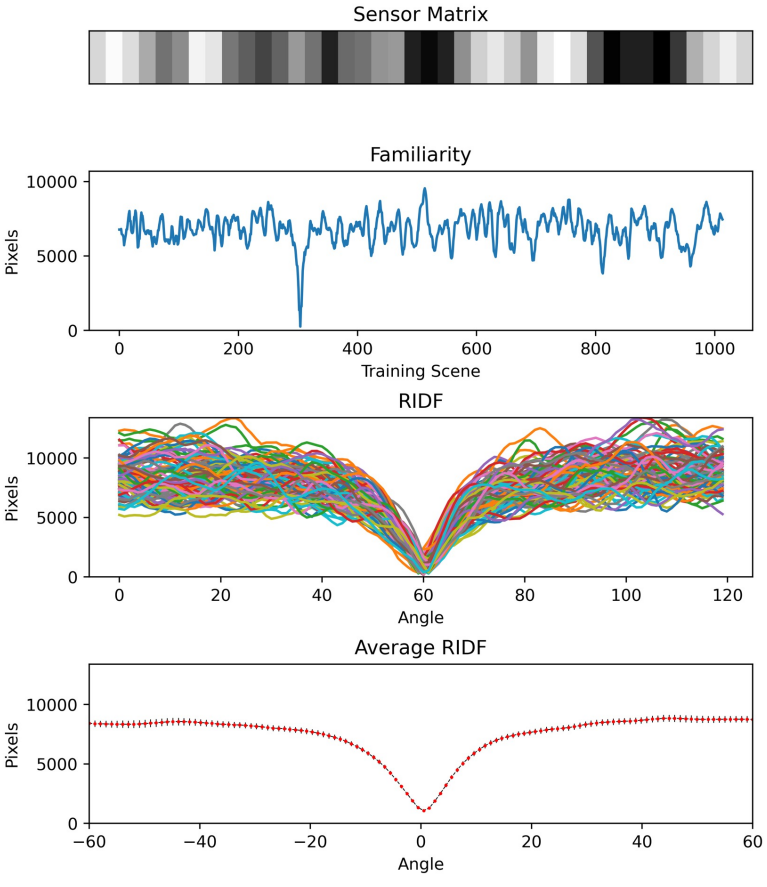
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 40.89; RMSD/dist: 0.102; TD: 7059; p90: 20; p50: 8; complete: 0


Index: BLUR: 3.0; LEVELS: 32; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

100%

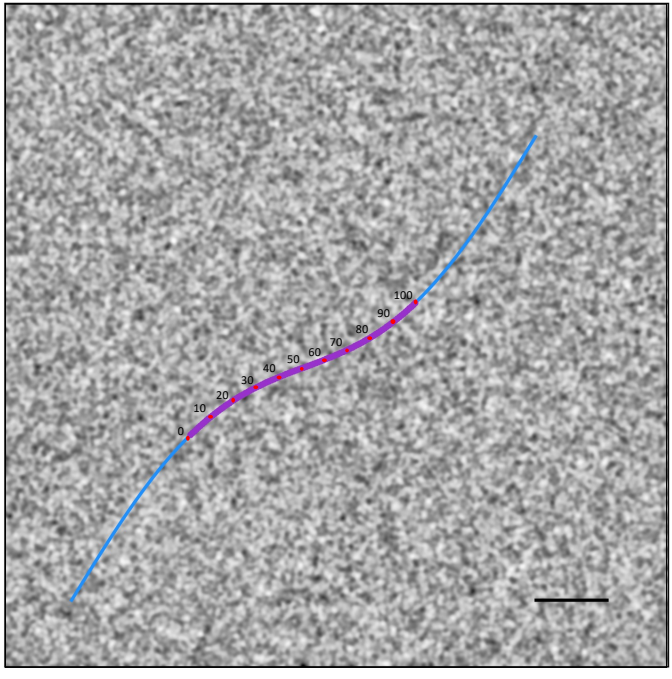


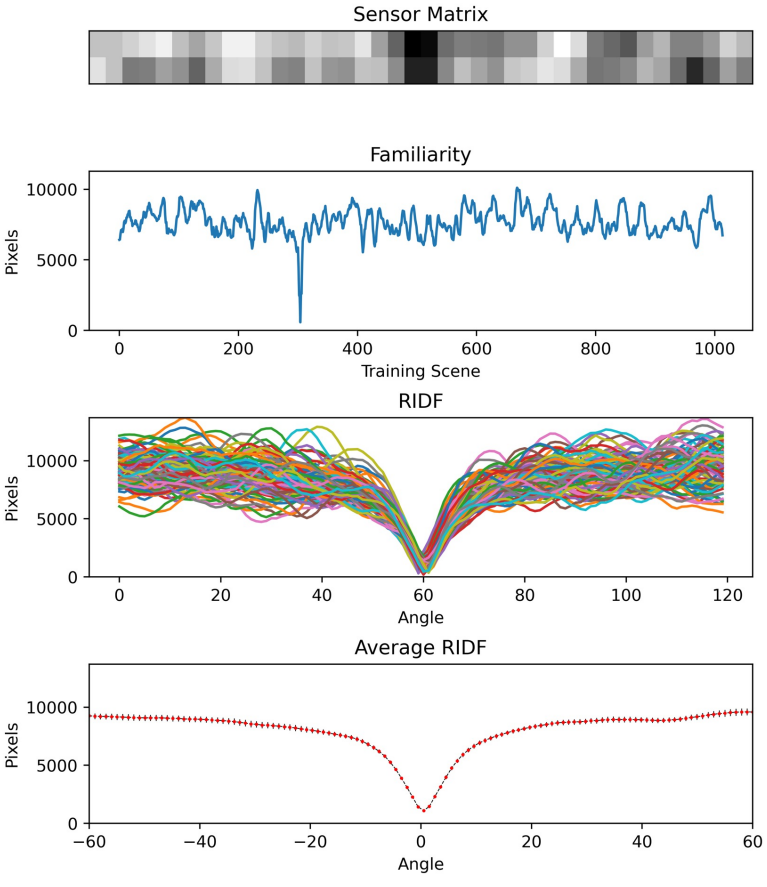


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 61.90; RMSD/dist: 0.155; TD: 5630; p90: 22; p50: 10; complete: 0

100%

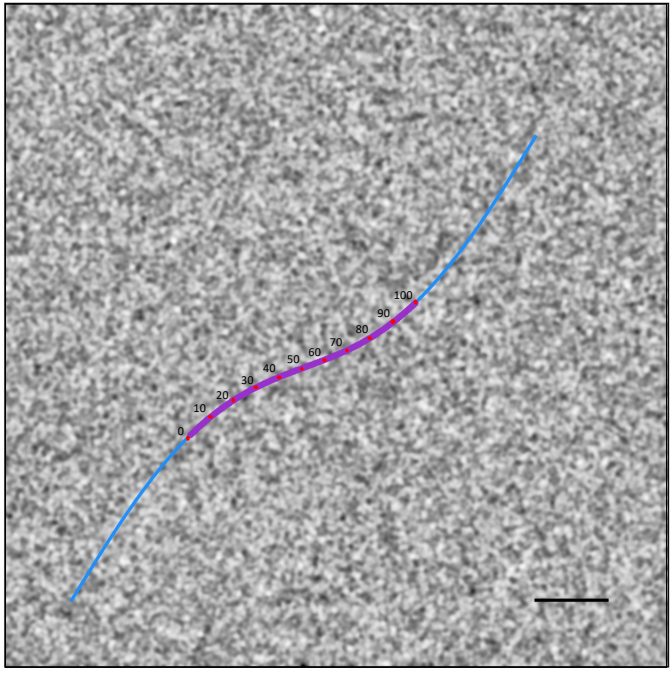


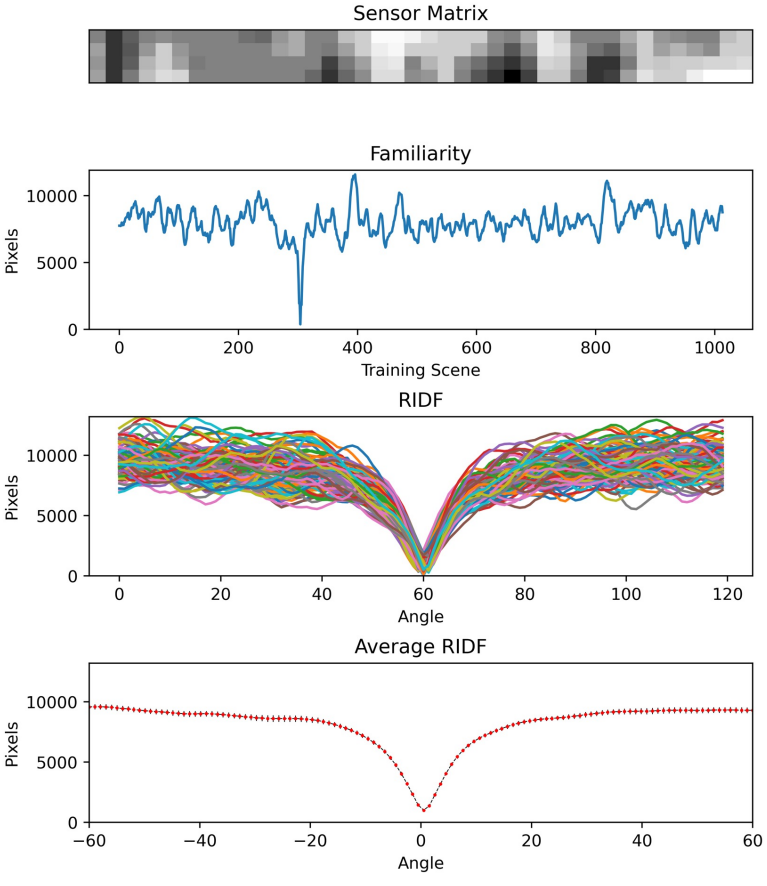


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 50.15; RMSD/dist: 0.125; TD: 6397; p90: 20; p50: 10; complete: 0

100%

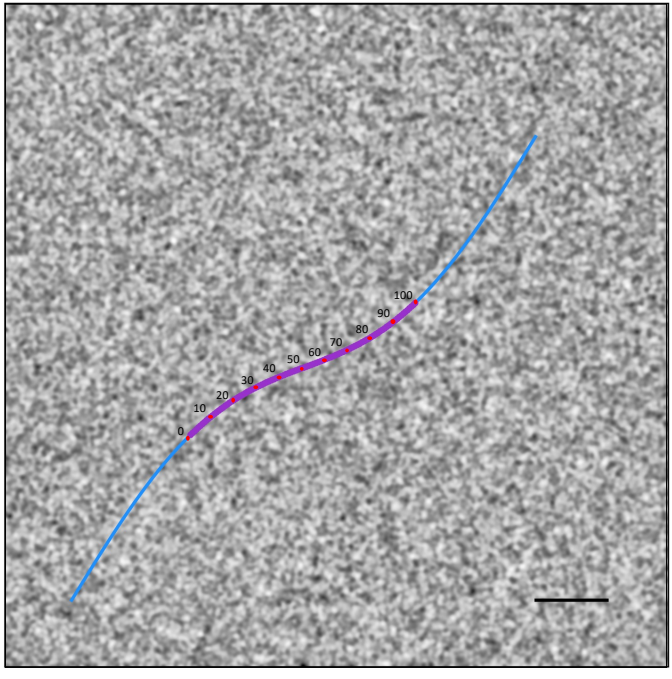


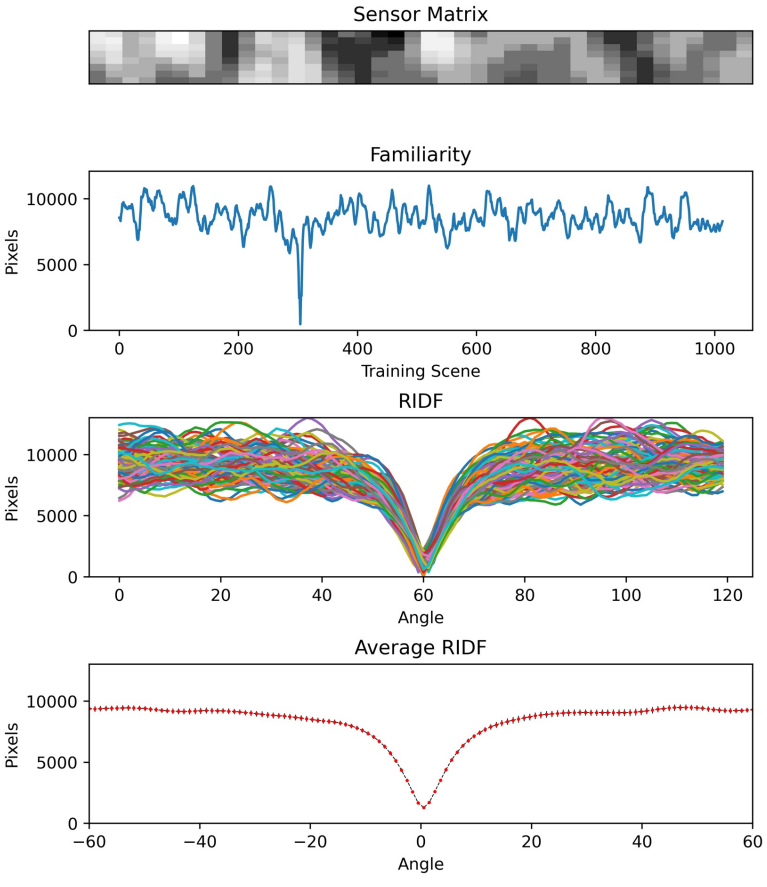


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 41.54; RMSD/dist: 0.104; TD: 6867; p90: 22; p50: 10; complete: 0

100%

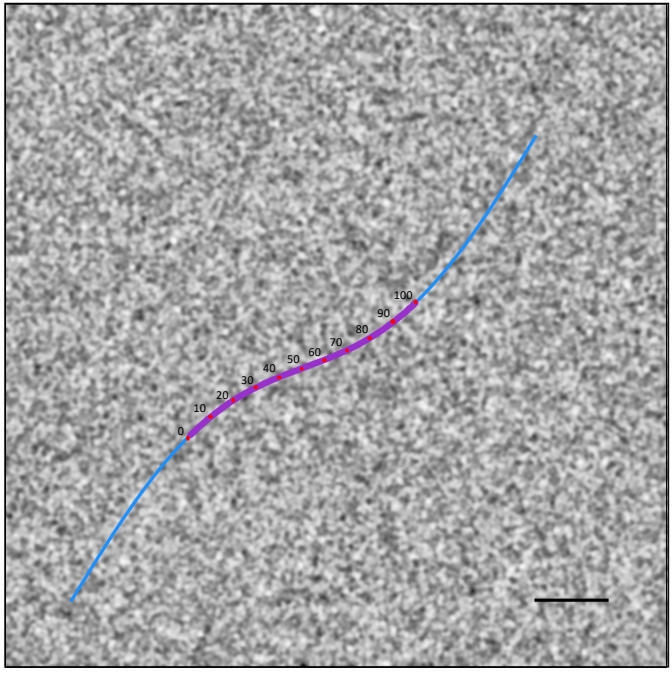


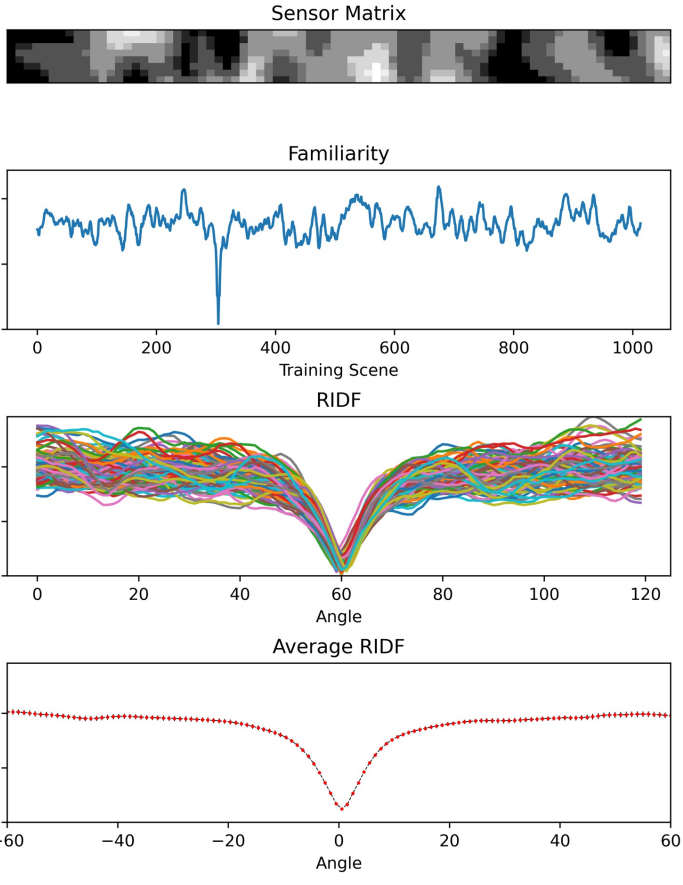


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 55.91; RMSD/dist: 0.140; TD: 6633; p90: 20; p50: 8; complete: 0

100%

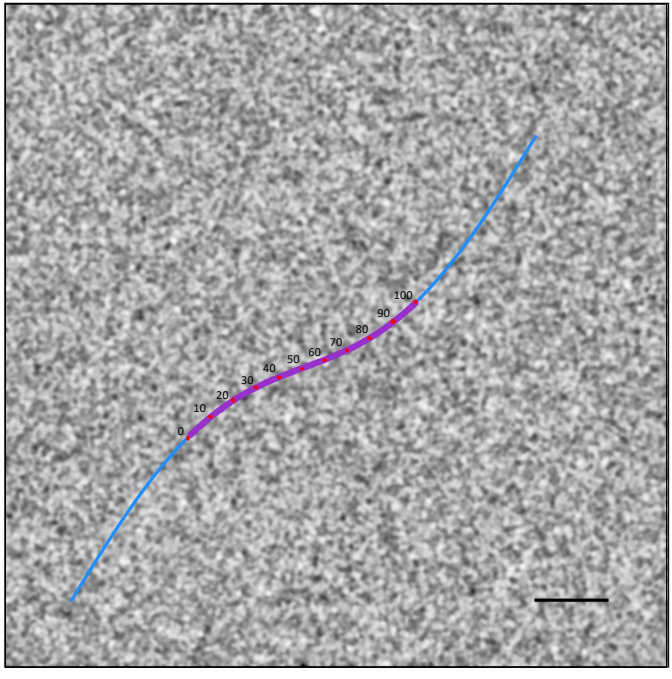


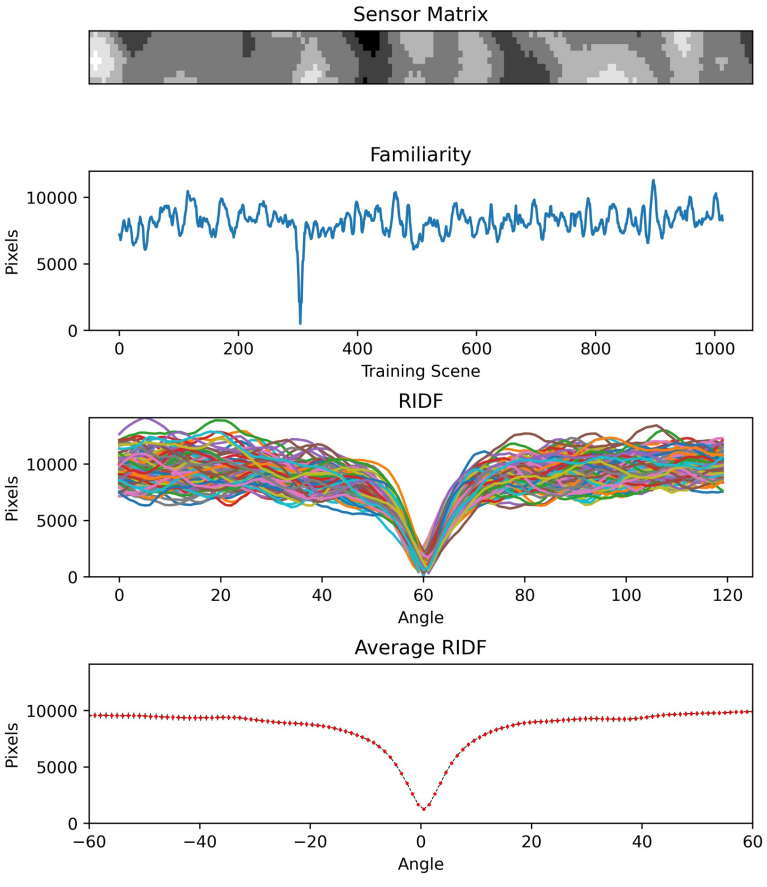


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 3; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 32; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 45.26; RMSD/dist: 0.113; TD: 6970; p90: 18; p50: 8; complete: 0

100%





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Navigation stats: RMSD error: 45.02; RMSD/dist: 0.113; TD: 6886; p90: 20; p50: 8; complete: 0