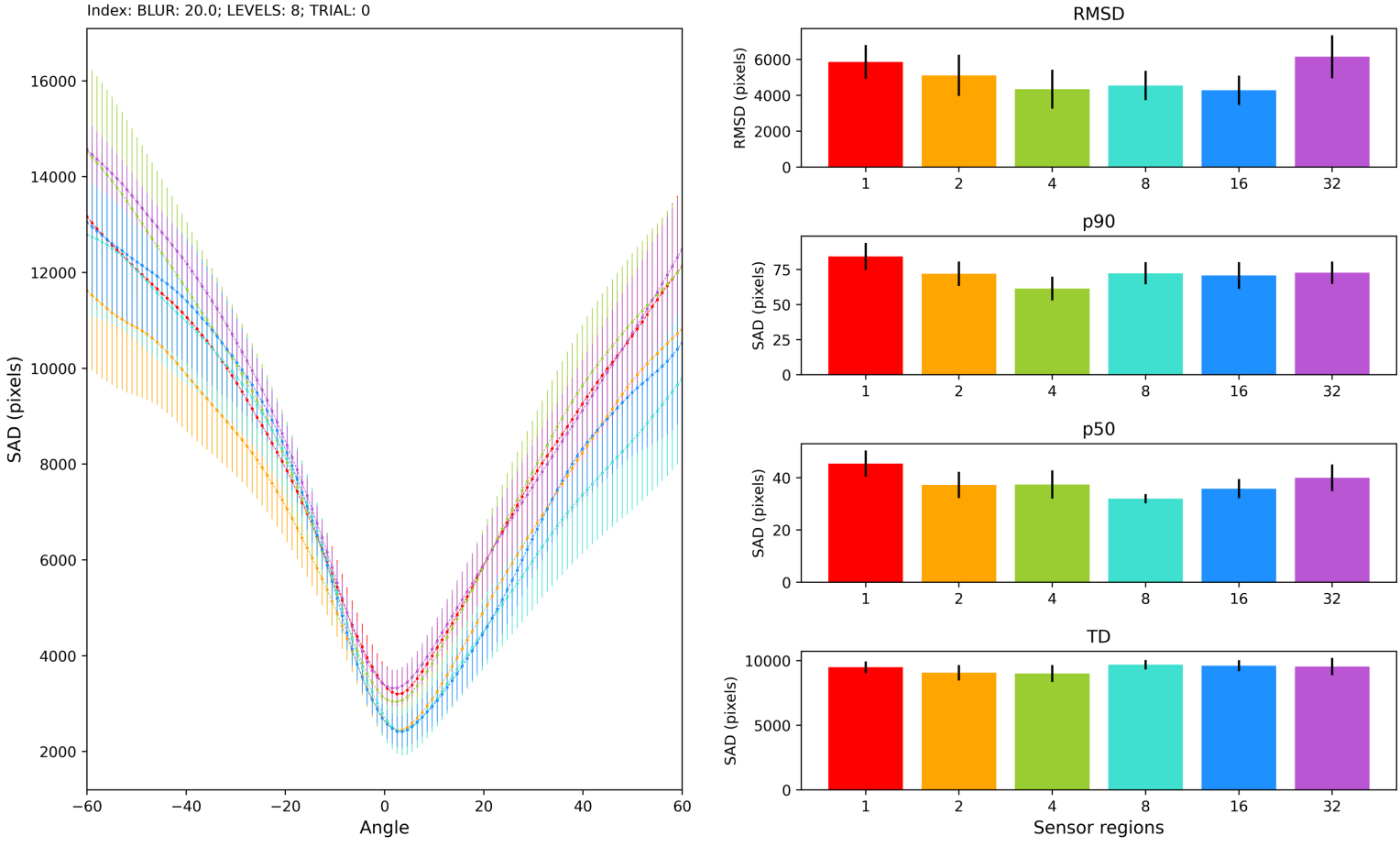
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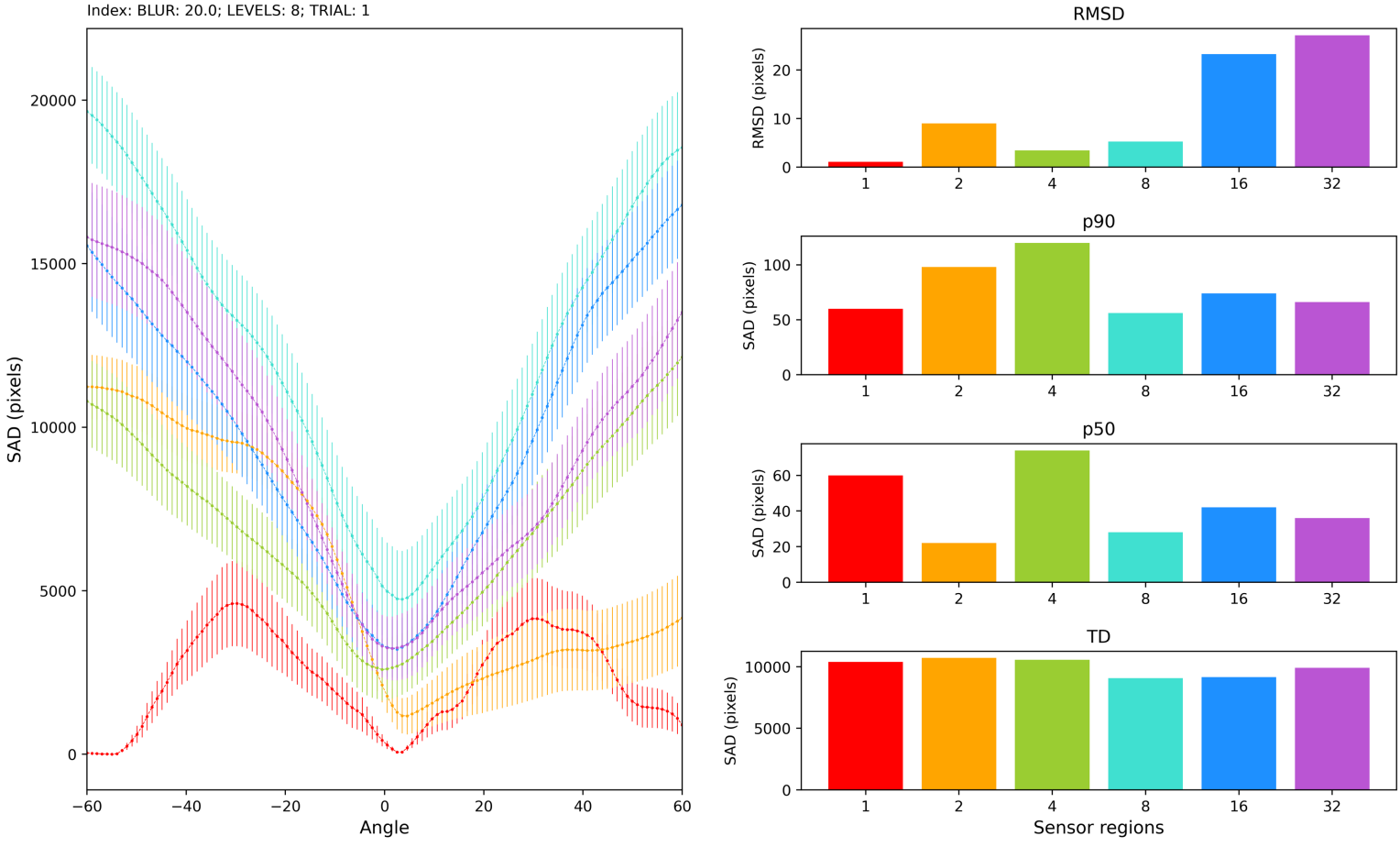
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions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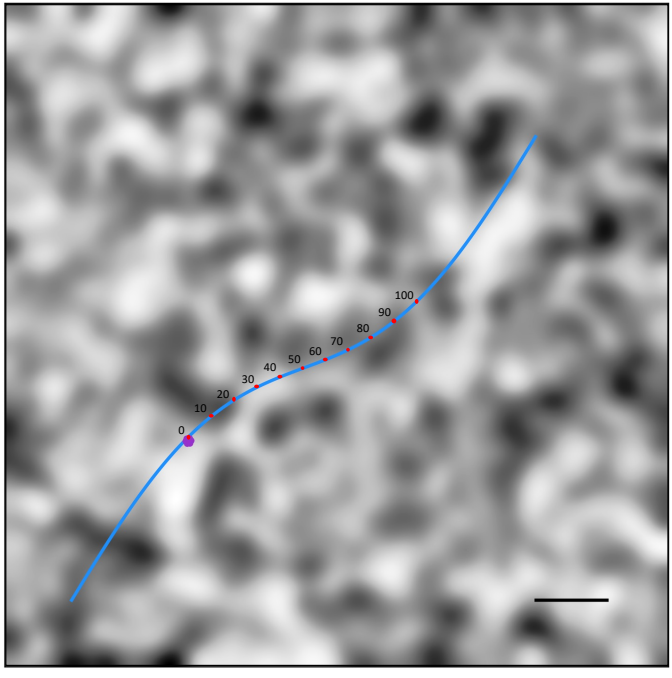
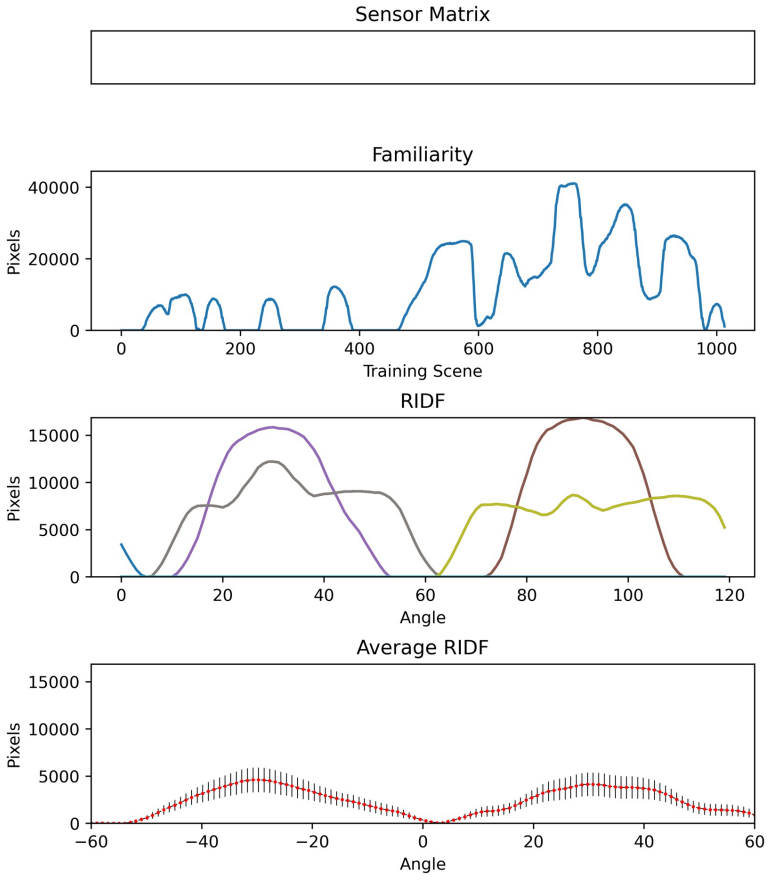
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

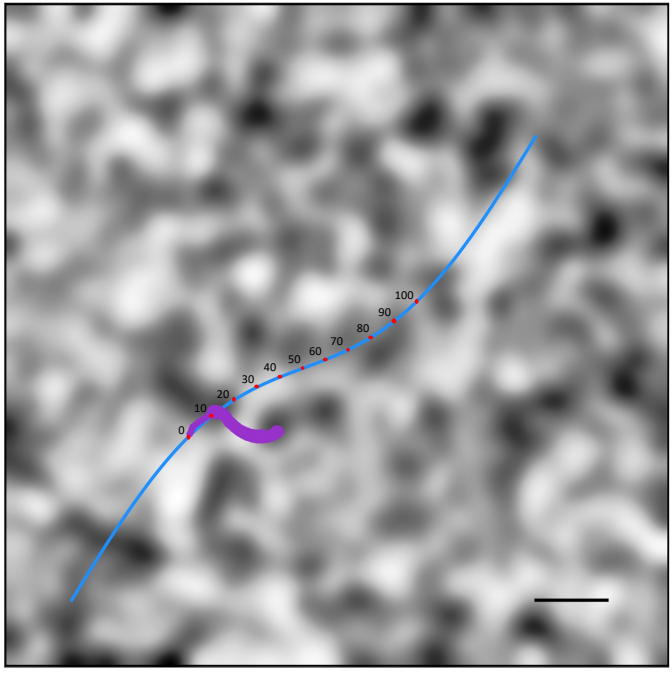


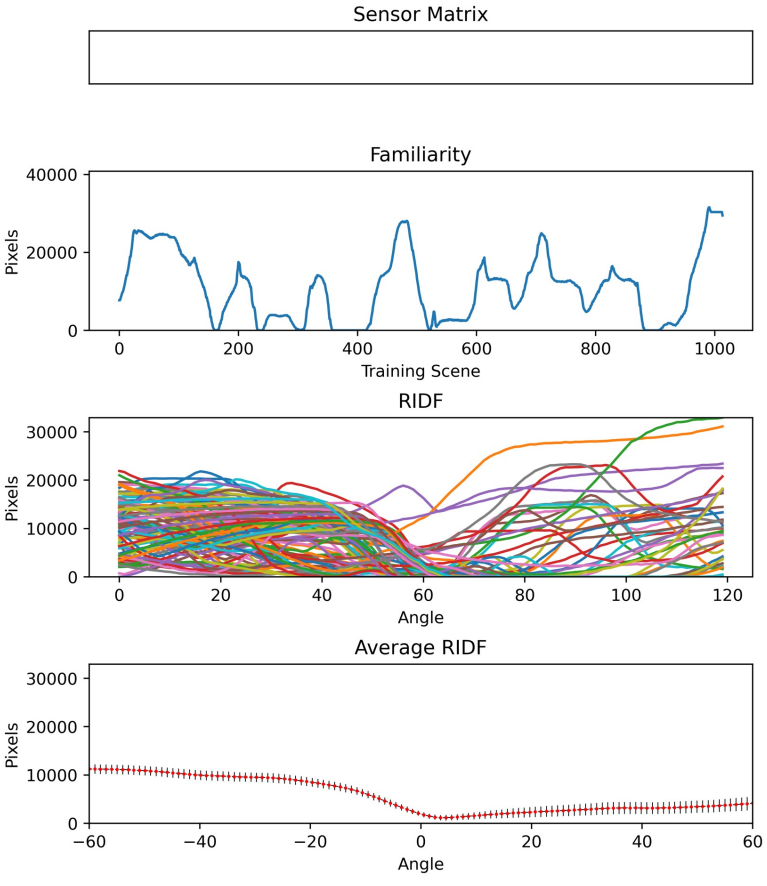


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 425.64; RMSD/dist: 1.064; TD: 10395; p90: 60; p50: 60; complete: 0

0%

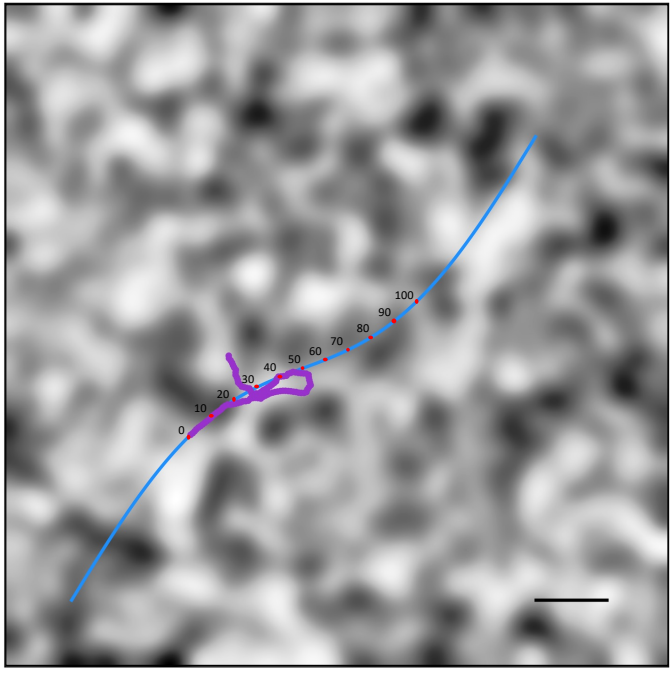


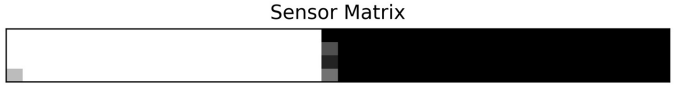


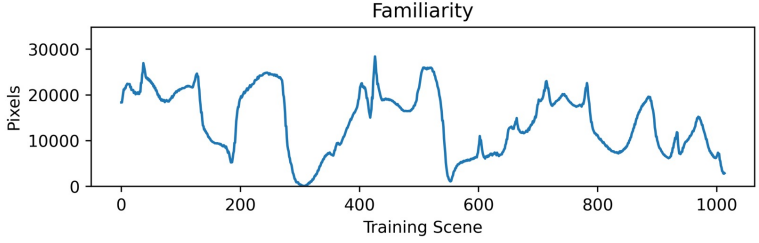
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 1

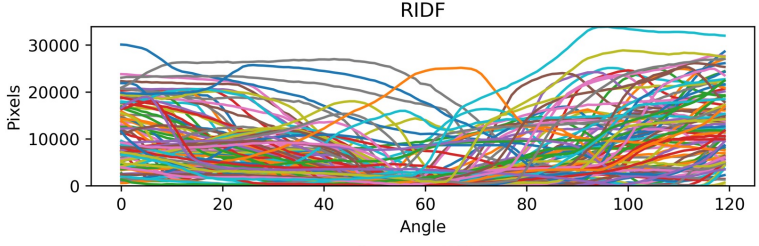
Navigation stats: RMSD error: 3595.78; RMSD/dist: 8.989; TD: 10716; p90: 98; p50: 22; complete: 0

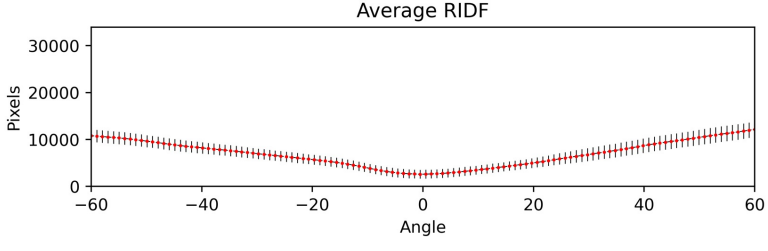
10%







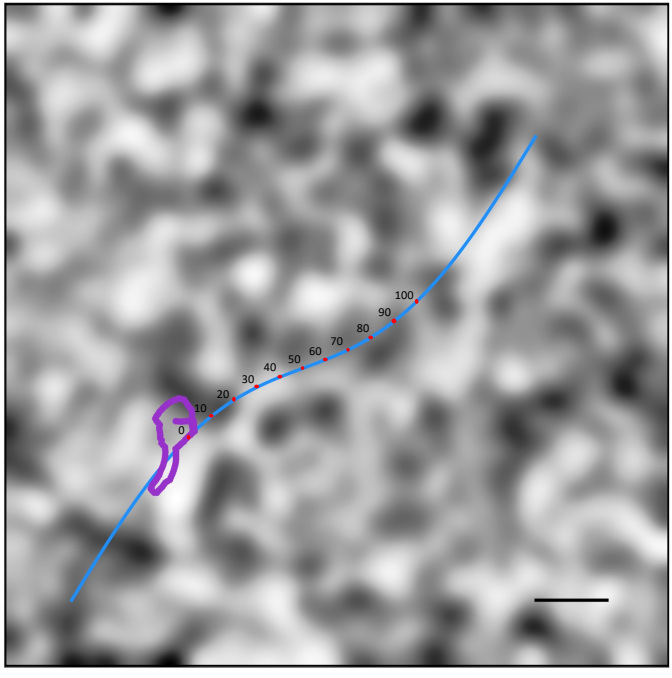


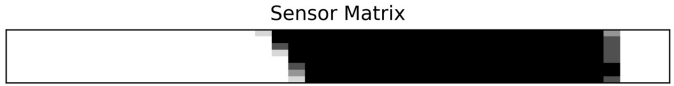


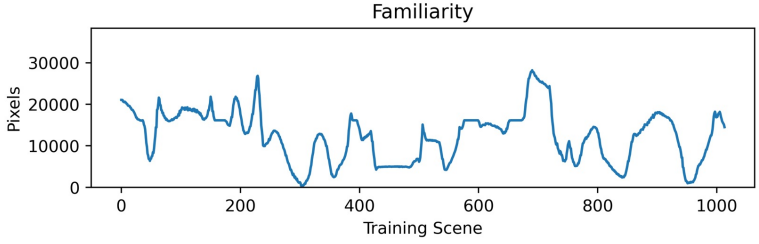
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 1

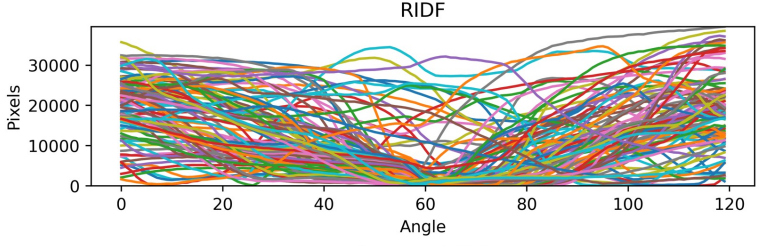
Navigation stats: RMSD error: 1372.77; RMSD/dist: 3.432; TD: 10563; p90: 120; p50: 74; complete: 0

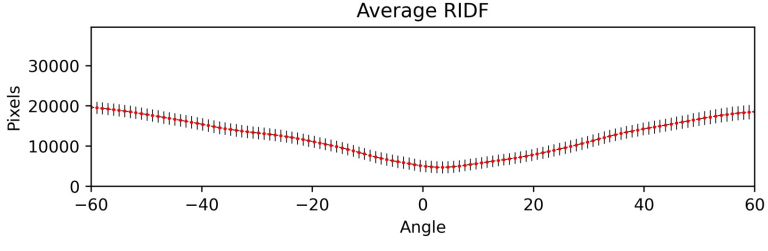
0%







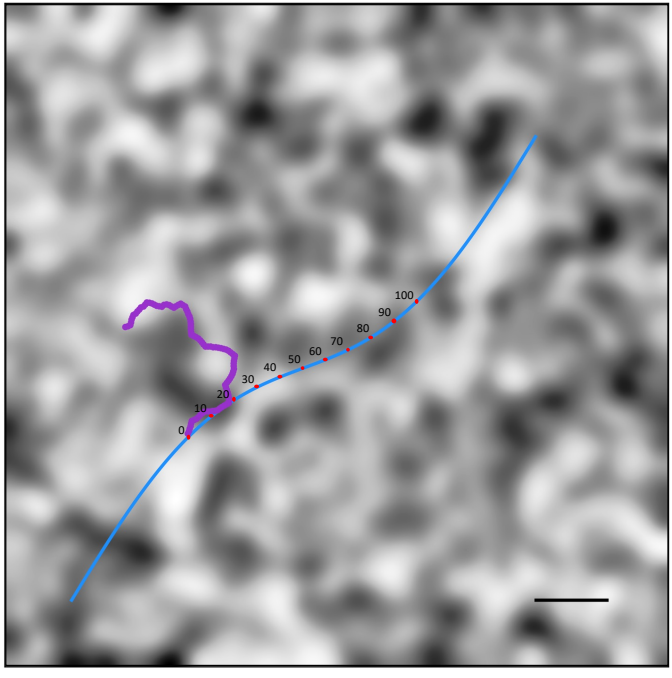


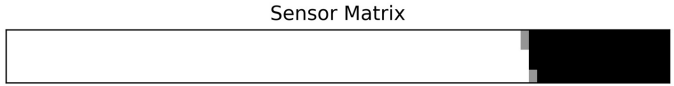


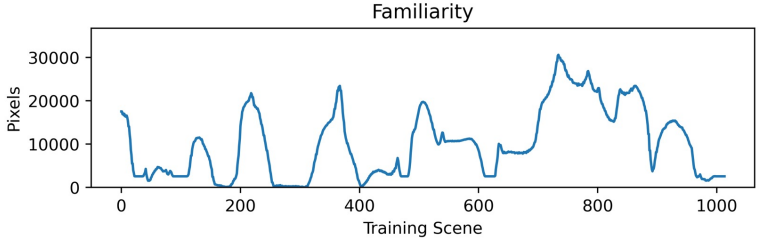
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 1

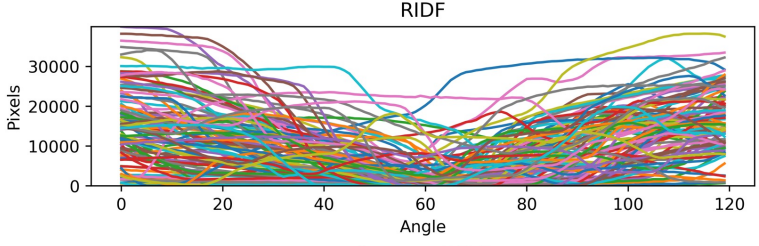
Navigation stats: RMSD error: 2091.99; RMSD/dist: 5.230; TD: 9083; p90: 56; p50: 28; complete: 0

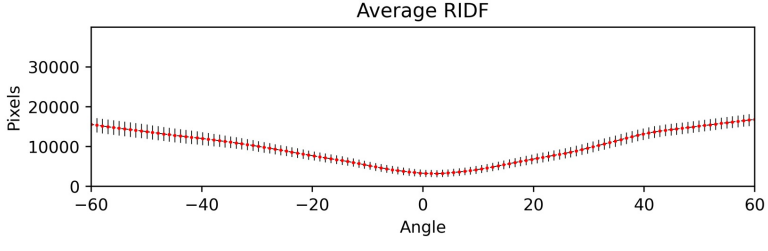
0%







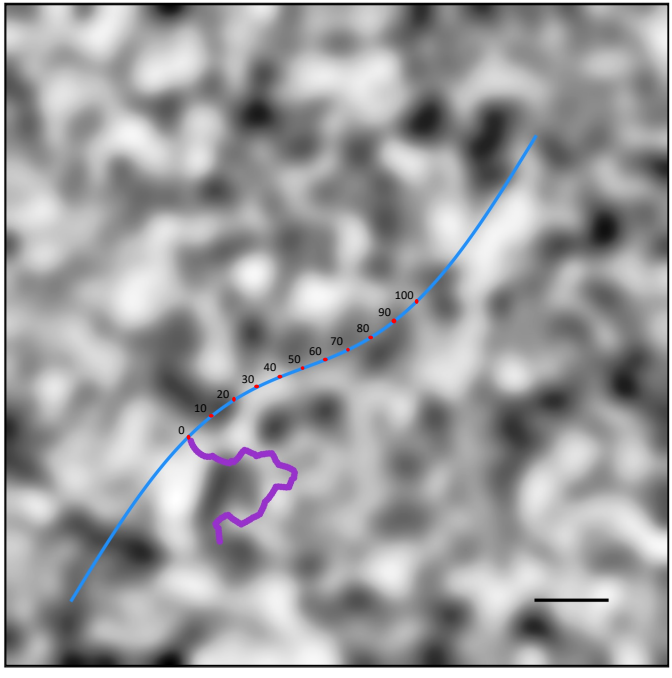


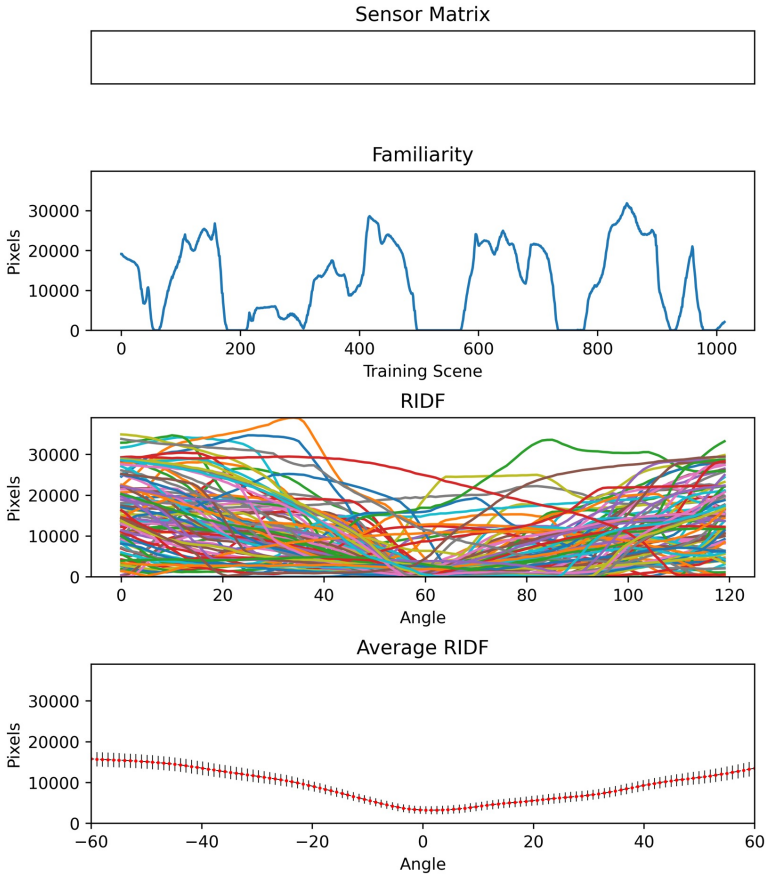


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 9295.36; RMSD/dist: 23.238; TD: 9162; p90: 74; p50: 42; complete: 0

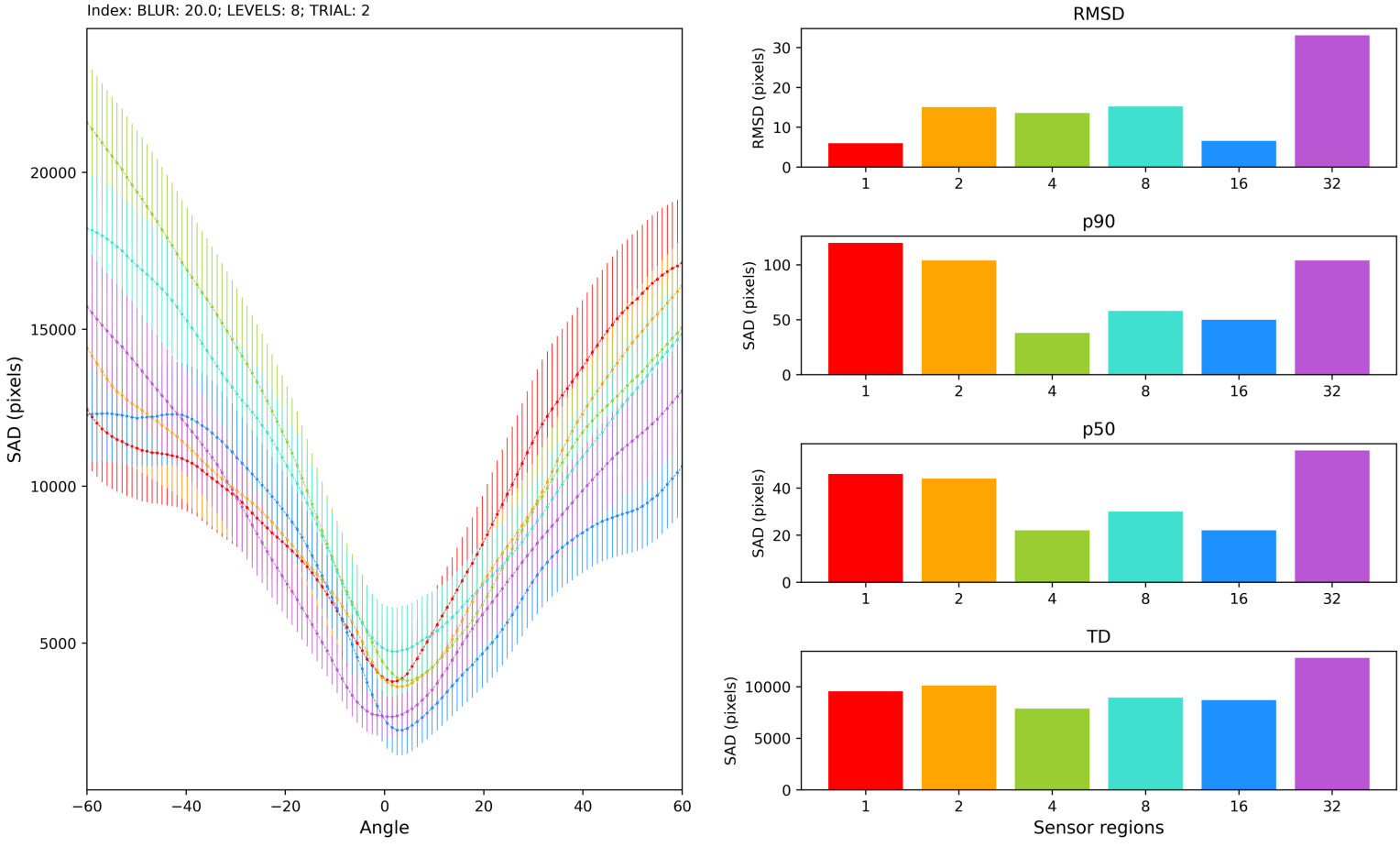
0%



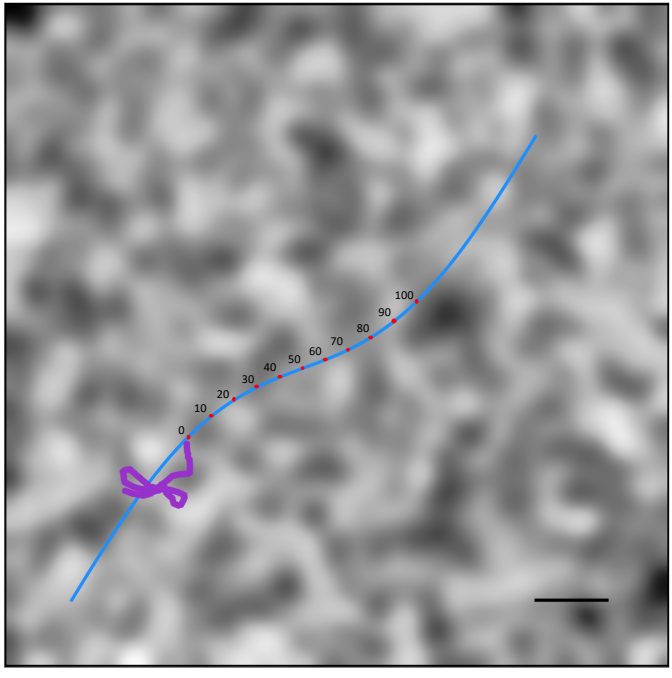


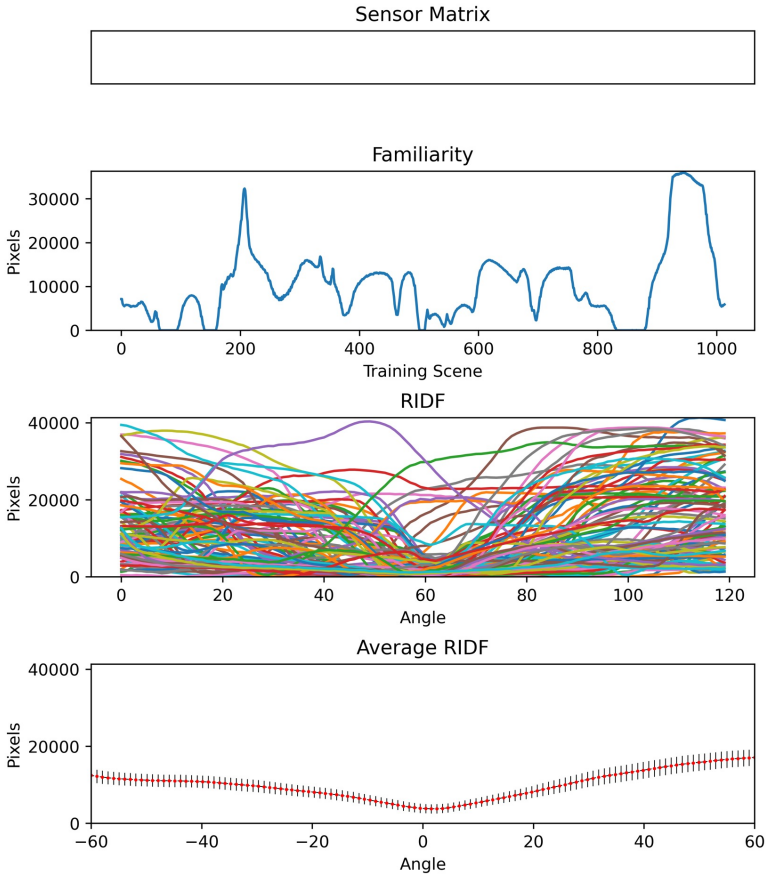
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 1

Navigation stats: RMSD error: 10853.66; RMSD/dist: 27.134; TD: 9924; p90: 66; p50: 36; complete: 0


Index: BLUR: 20.0; LEVELS: 8; TRIAL: 2
SAD (pixels)
20000
15000
10000
5000
−60
−40
−20
0
20
40
60
Angle
RMSD
RMSD (pixels)
30
20
10
0
1
2
4
8
16
32
p90
SAD (pixels)
100
50
0
p50
40
20
TD
10000
5000
Sensor regions

0%

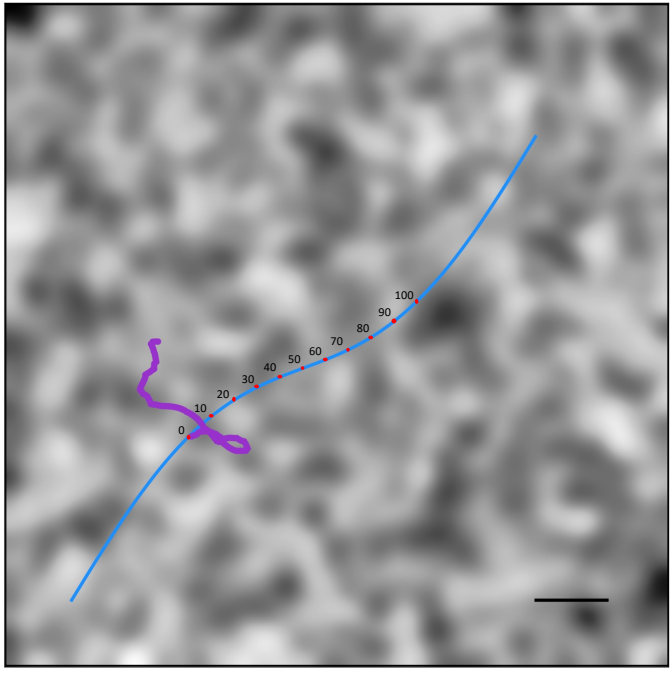


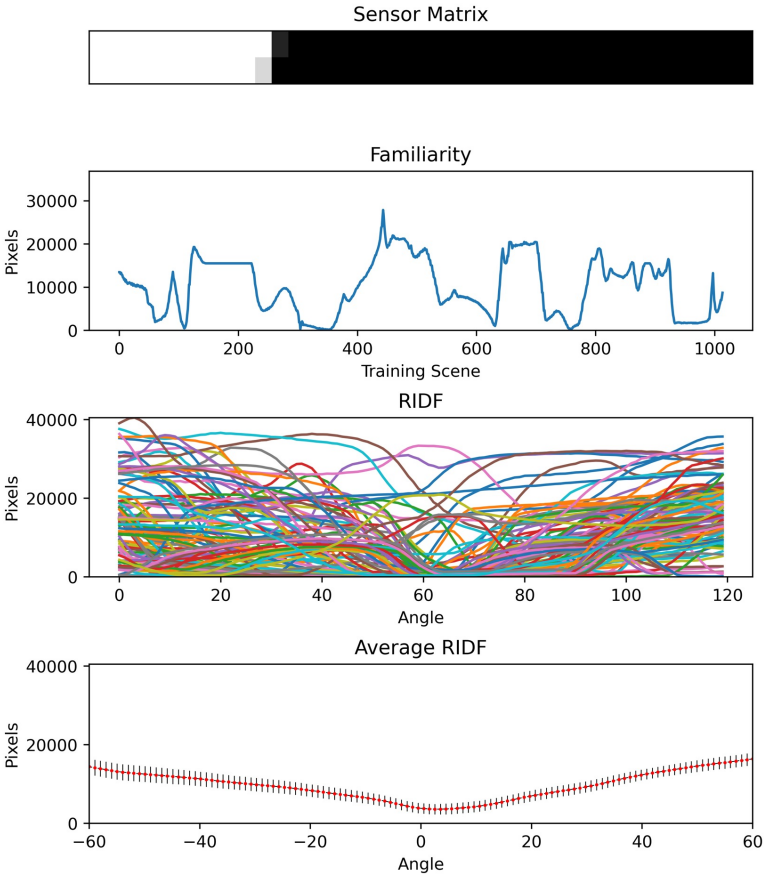


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 2388.84; RMSD/dist: 5.972; TD: 9568; p90: 120; p50: 46; complete: 0

0%

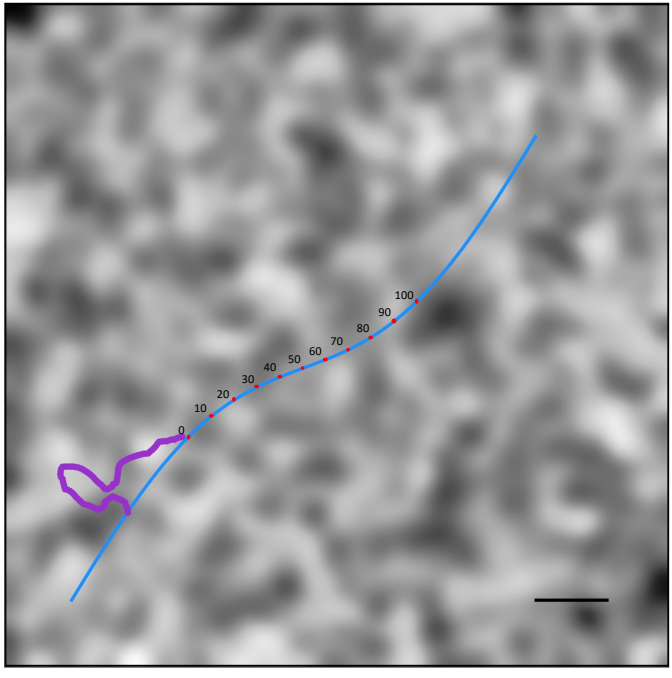


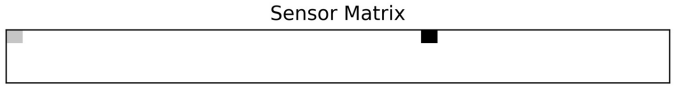


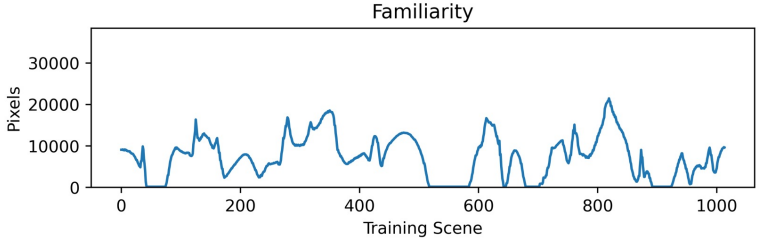
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 2

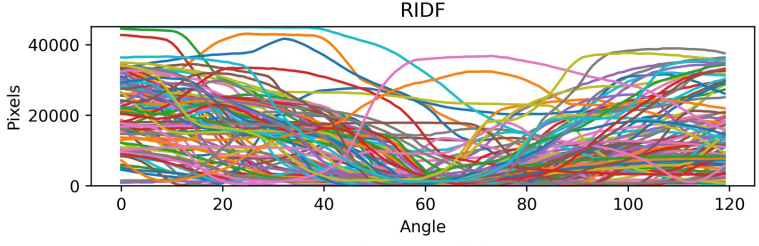
Navigation stats: RMSD error: 6029.43; RMSD/dist: 15.074; TD: 10118; p90: 104; p50: 44; complete: 0

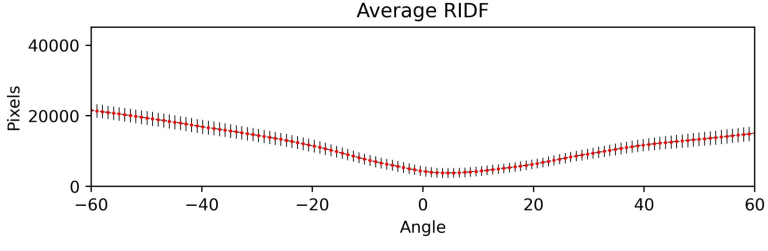
0%







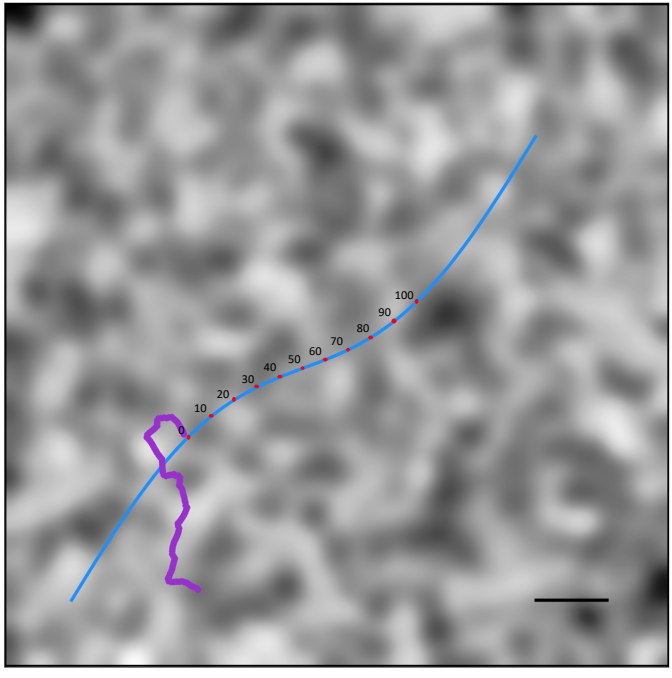


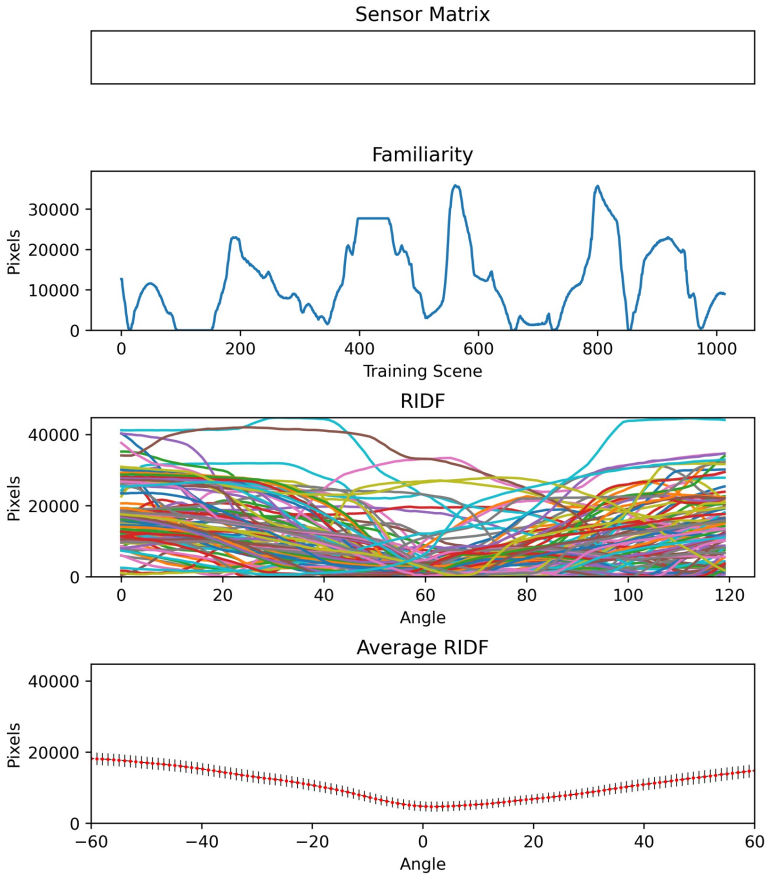


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 2

Navigation stats: RMSD error: 5421.68; RMSD/dist: 13.554; TD: 7880; p90: 38; p50: 22; complete: 0

0%

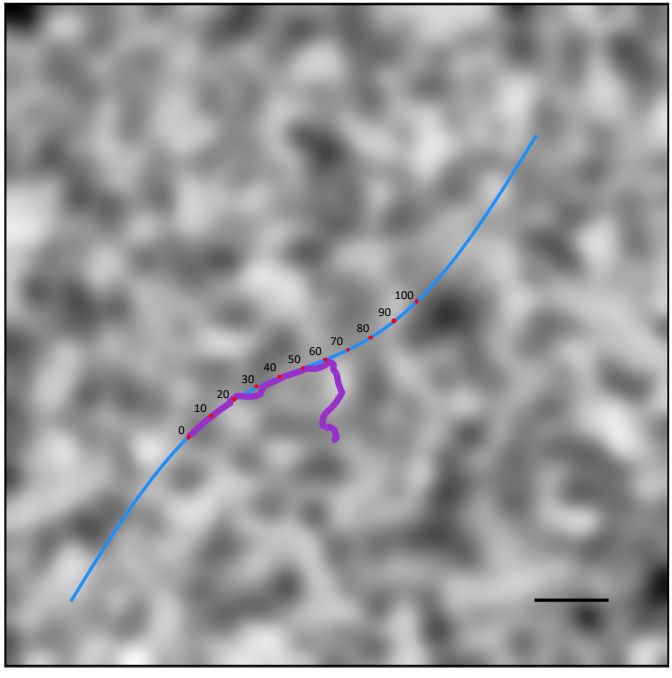


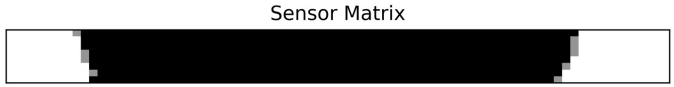


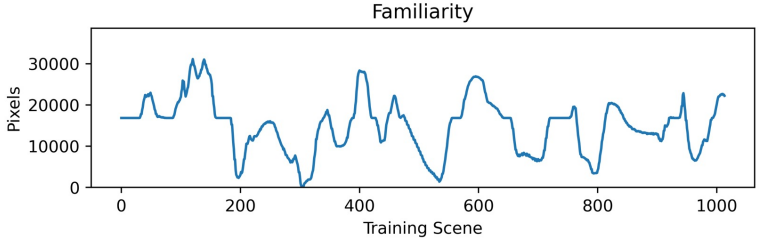
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 2

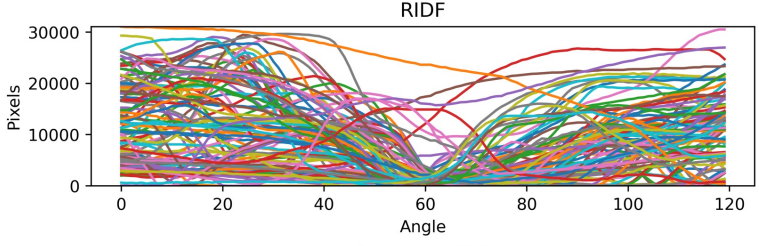
Navigation stats: RMSD error: 6096.70; RMSD/dist: 15.242; TD: 8941; p90: 58; p50: 30; complete: 0

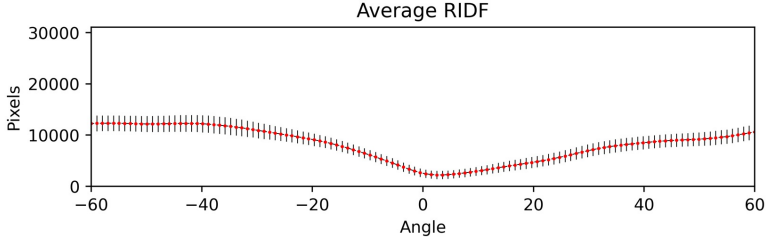
30%







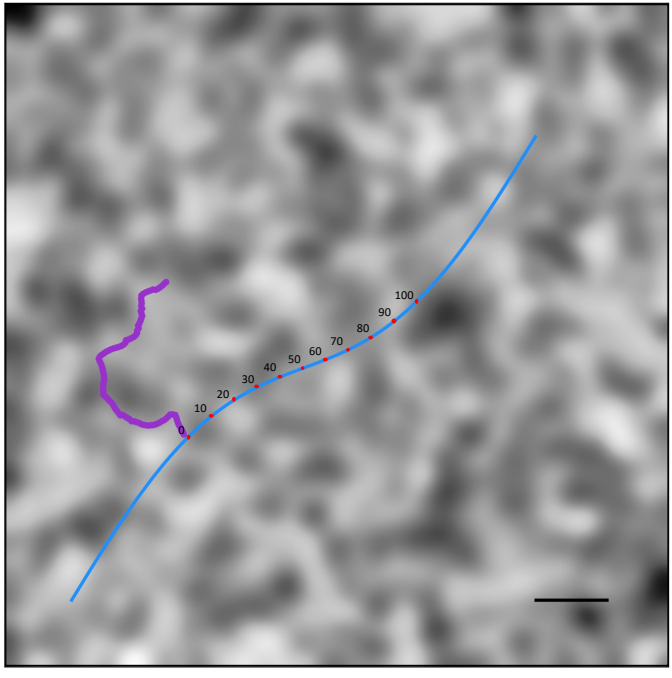


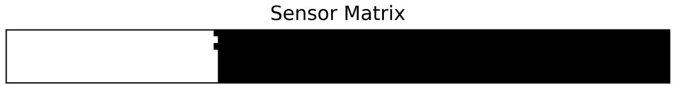


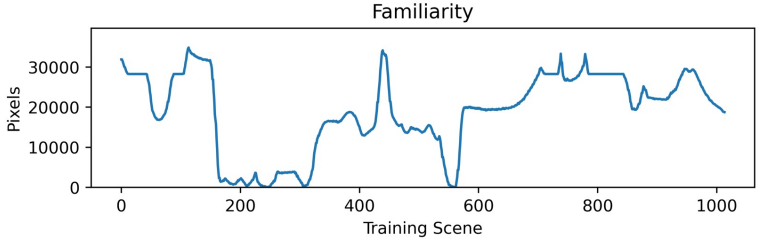
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 2

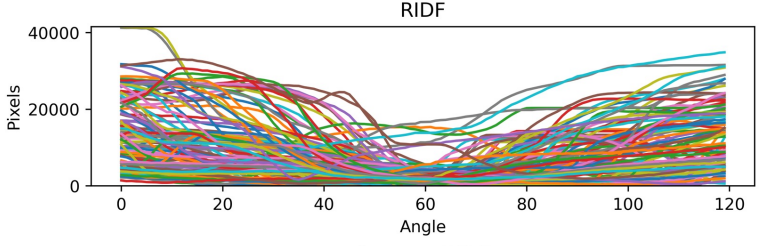
Navigation stats: RMSD error: 2620.10; RMSD/dist: 6.550; TD: 8710; p90: 50; p50: 22; complete: 0

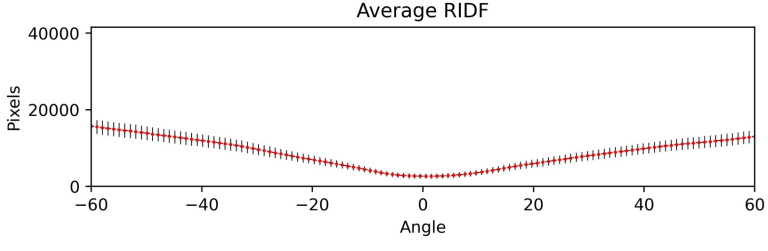
0%





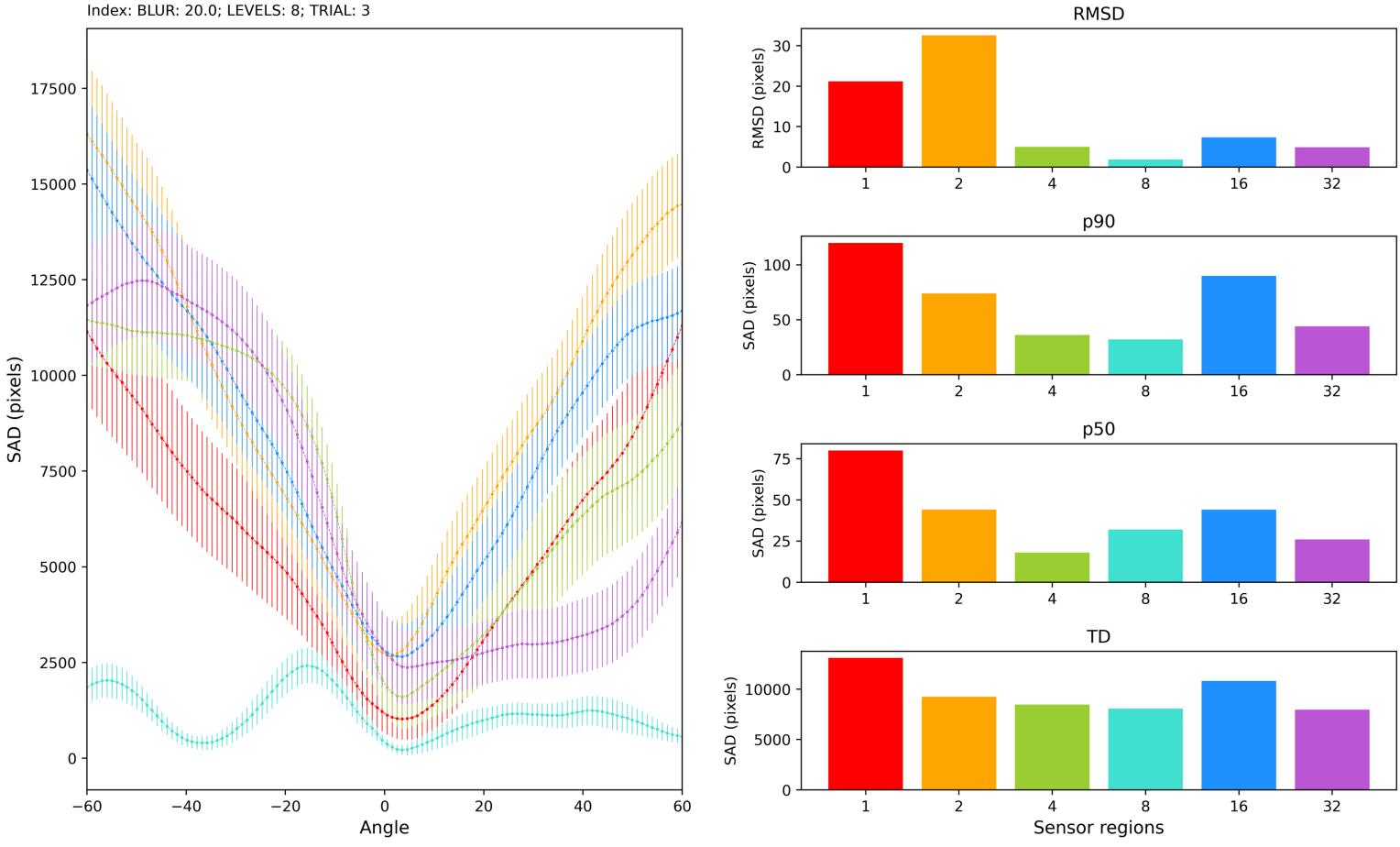




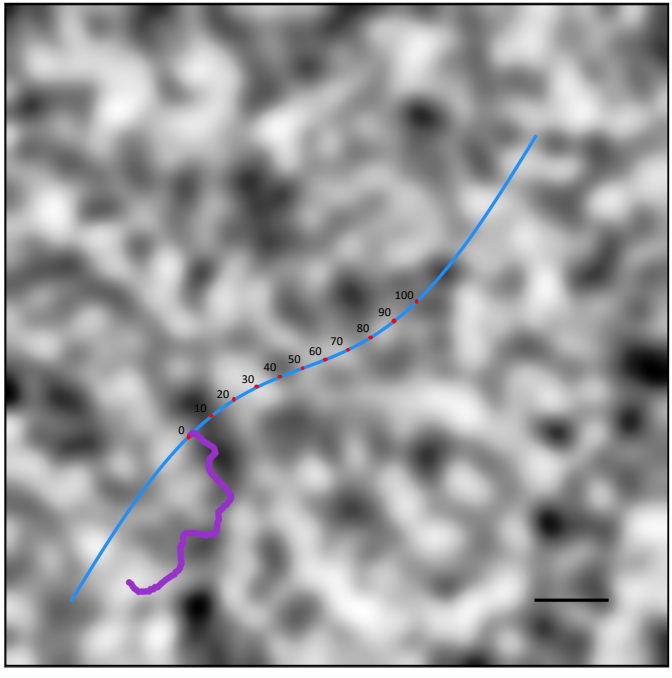


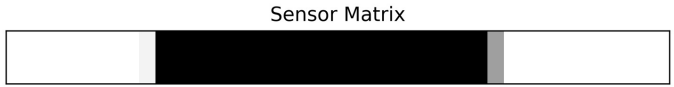
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 2

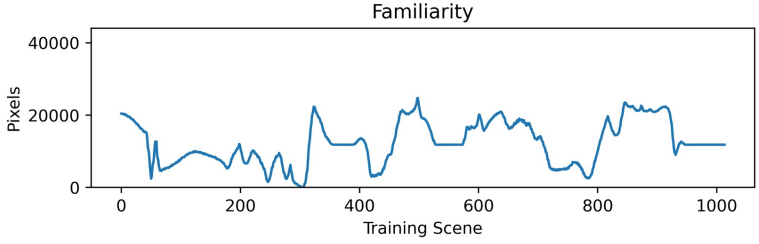
Navigation stats: RMSD error: 13251.17; RMSD/dist: 33.128; TD: 12789; p90: 104; p50: 56; complete: 0

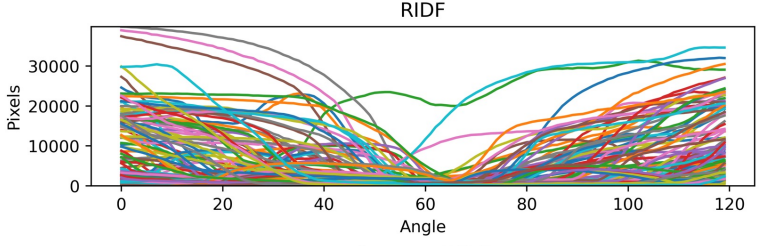

Index: BLUR: 20.0; LEVELS: 8; TRIAL: 3
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

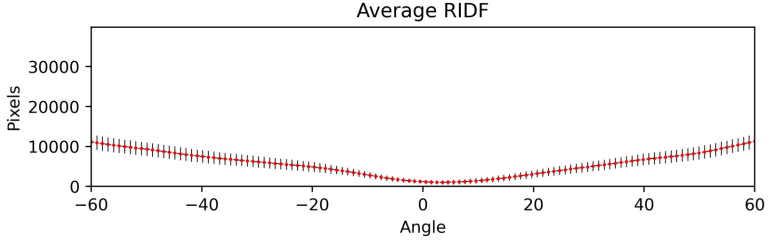
0%











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Navigation stats: RMSD error: 8468.90; RMSD/dist: 21.172; TD: 13090; p90: 120; p50: 80; complete: 0

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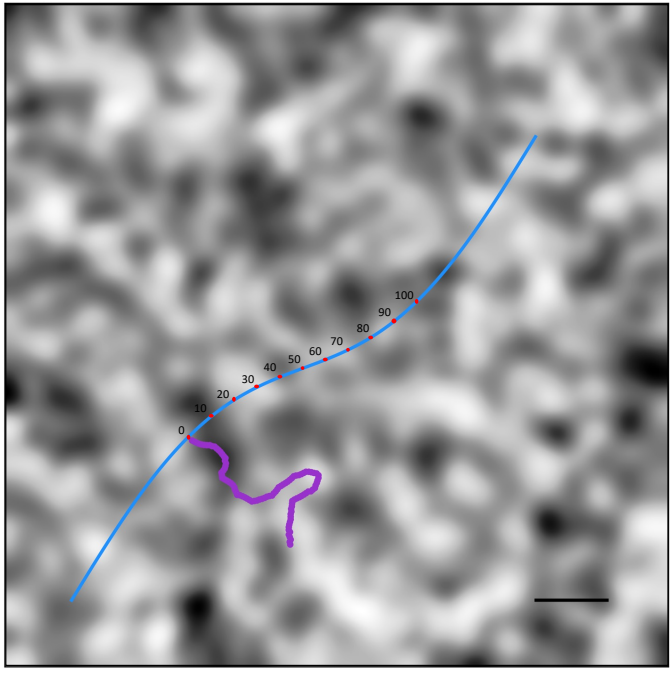

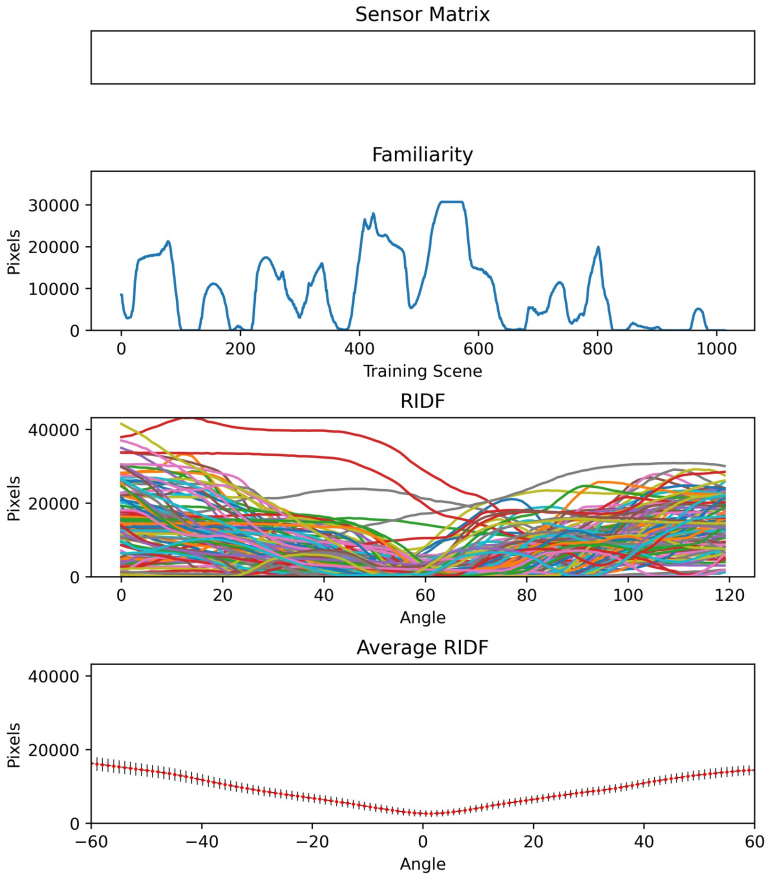

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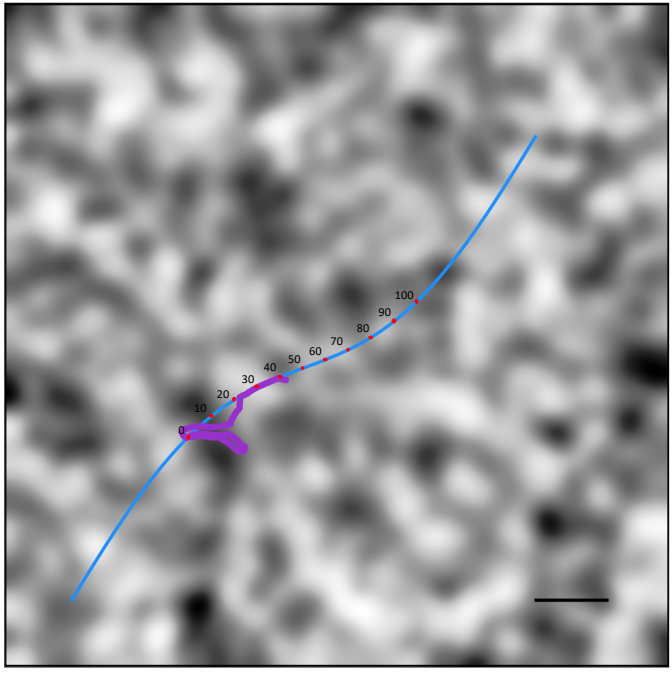

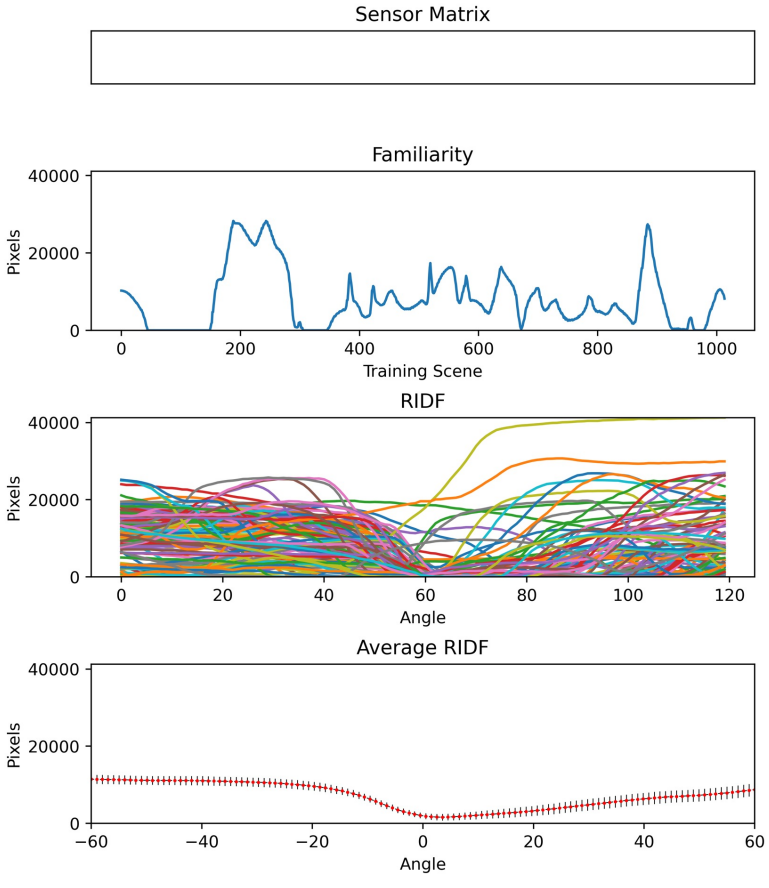

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Navigation stats: RMSD error: 1994.34; RMSD/dist: 4.986; TD: 8457; p90: 36; p50: 18; complete: 0

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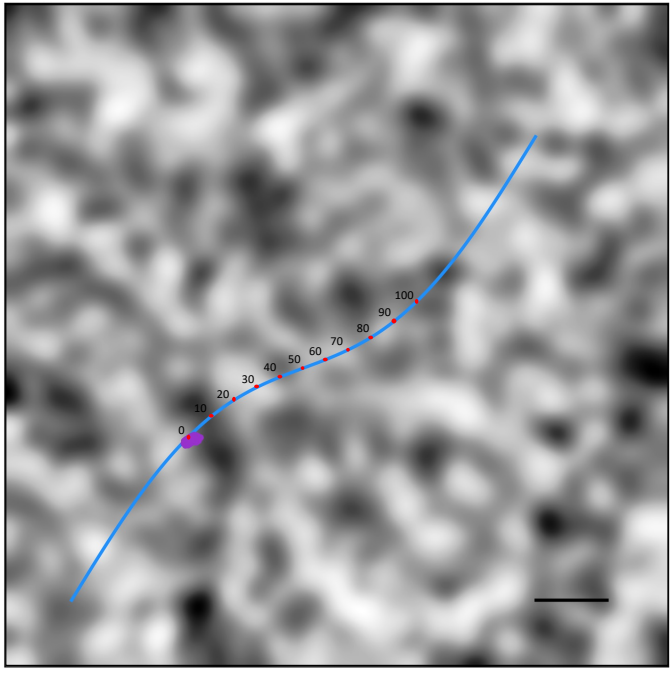

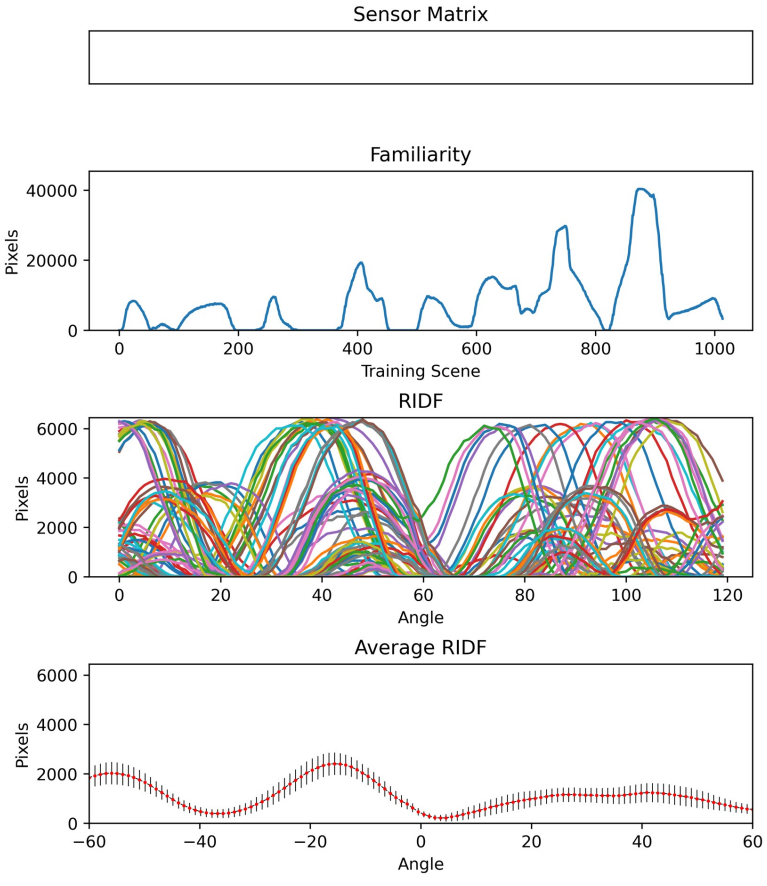

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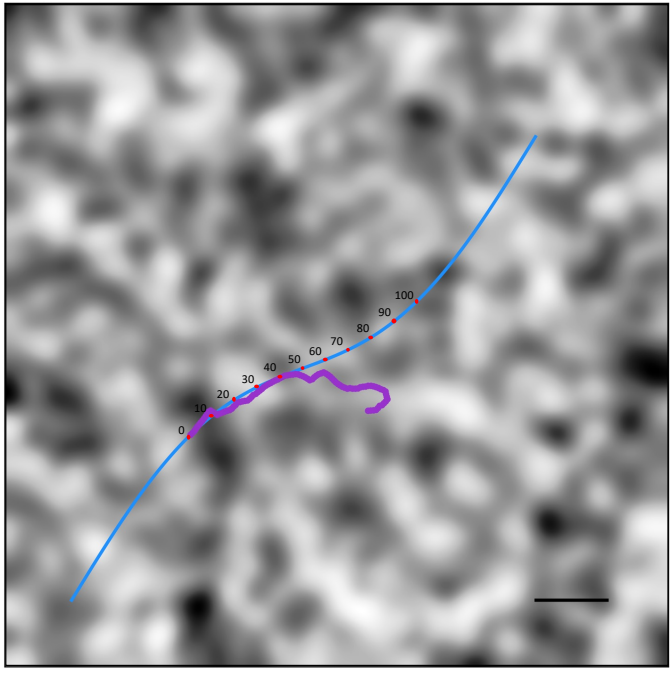
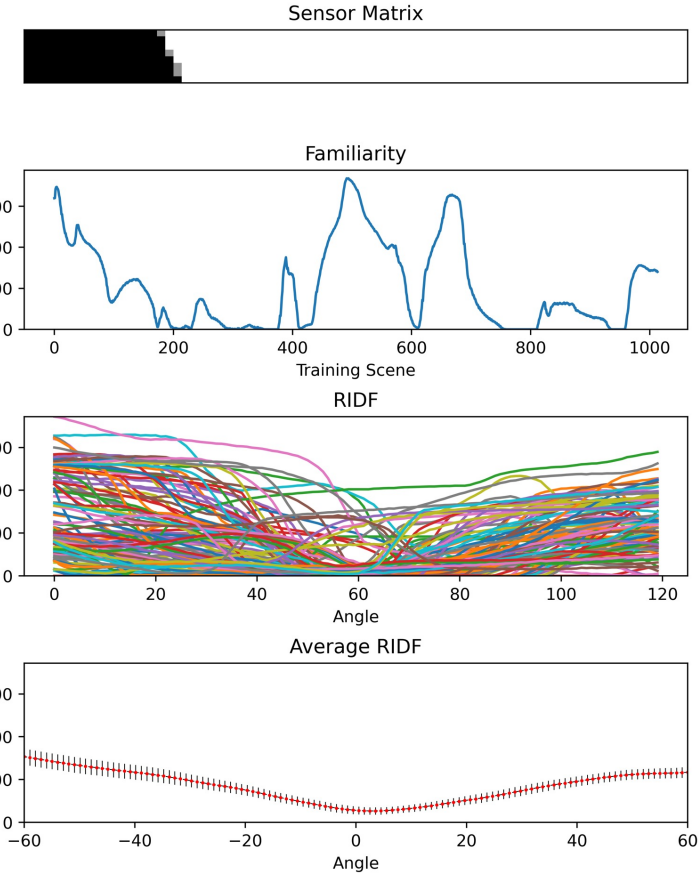
Navigation stats: RMSD error: 735.01; RMSD/dist: 1.838; TD: 8062; p90: 32; p50: 32; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 3

Navigation stats: RMSD error: 2935.28; RMSD/dist: 7.338; TD: 10818; p90: 90; p50: 44; complete: 0

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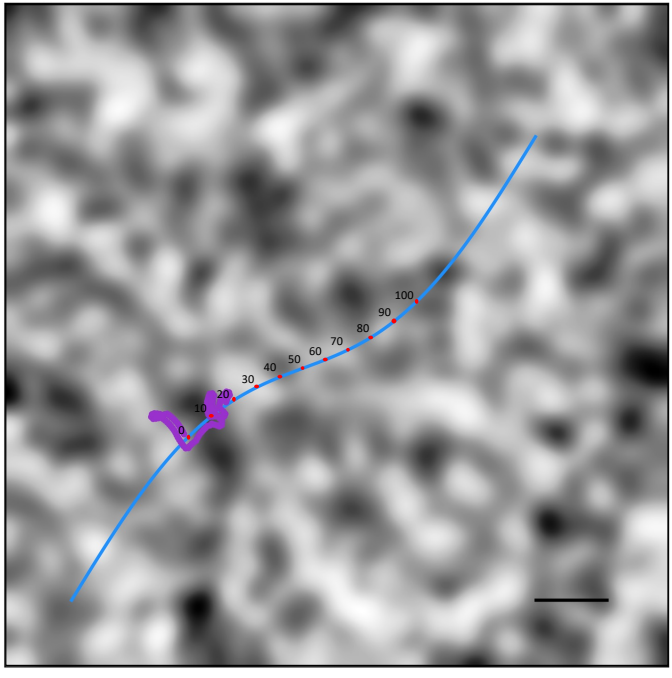

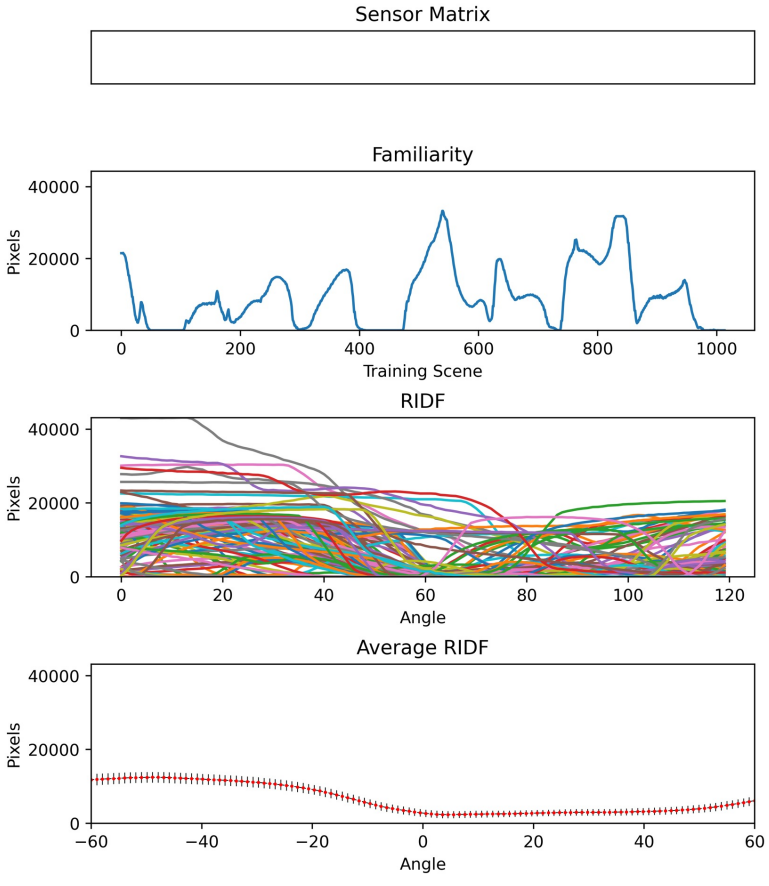

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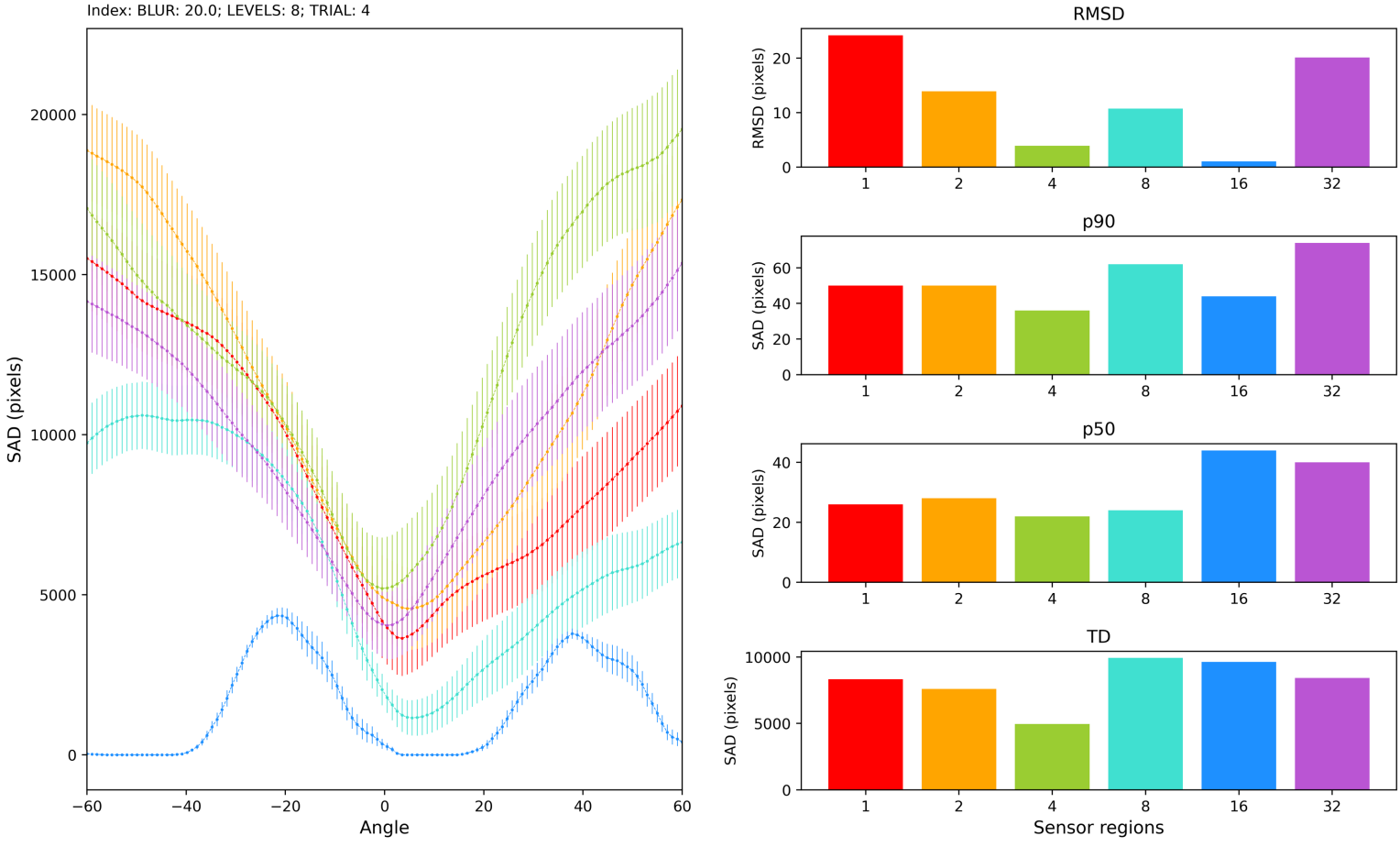
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SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

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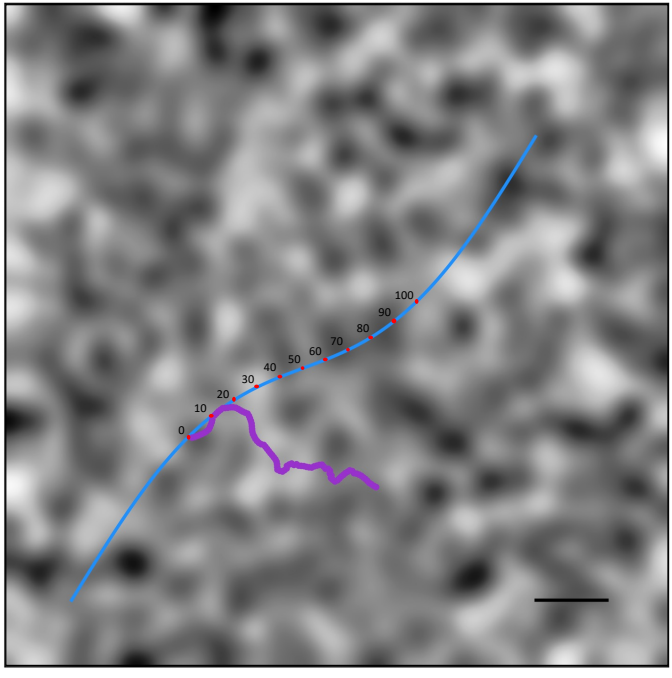

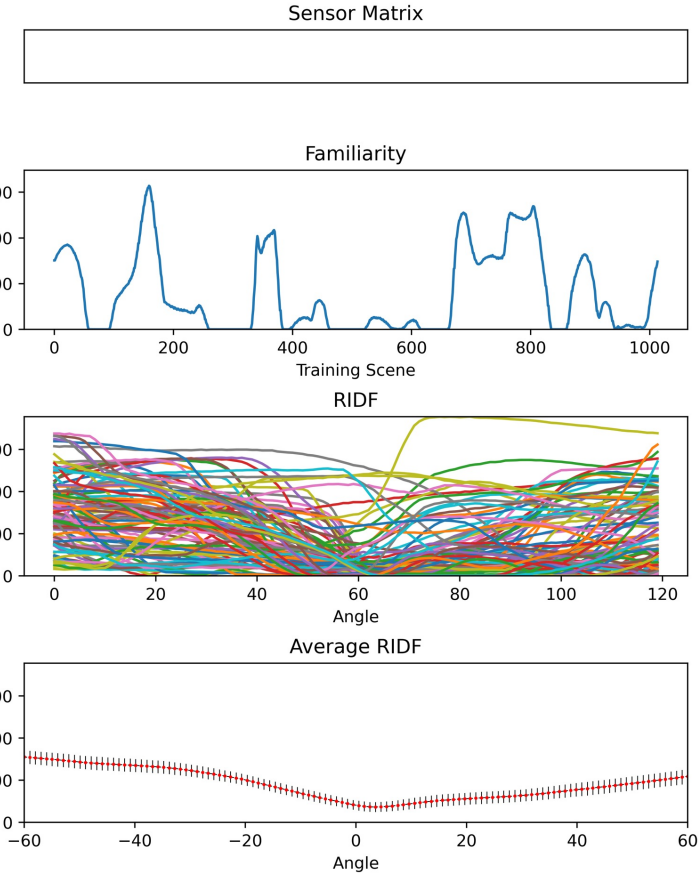

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Navigation stats: RMSD error: 9681.37; RMSD/dist: 24.203; TD: 8334; p90: 50; p50: 26; complete: 0

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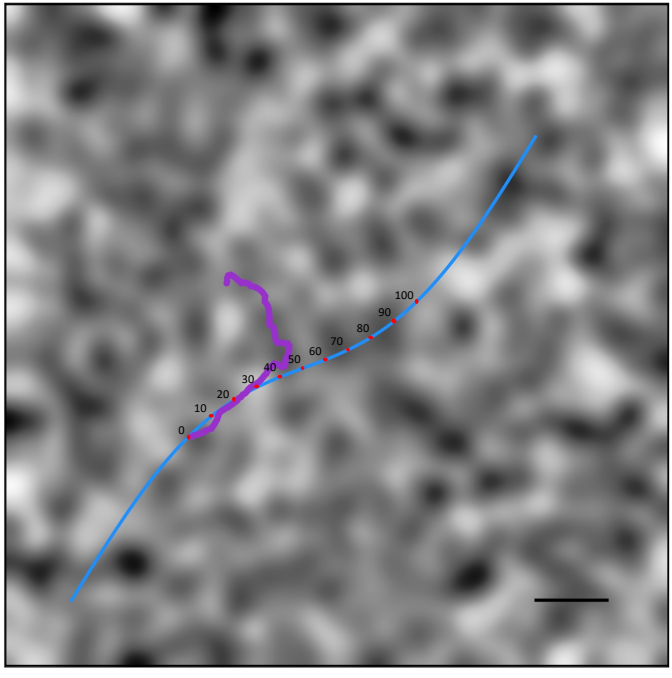

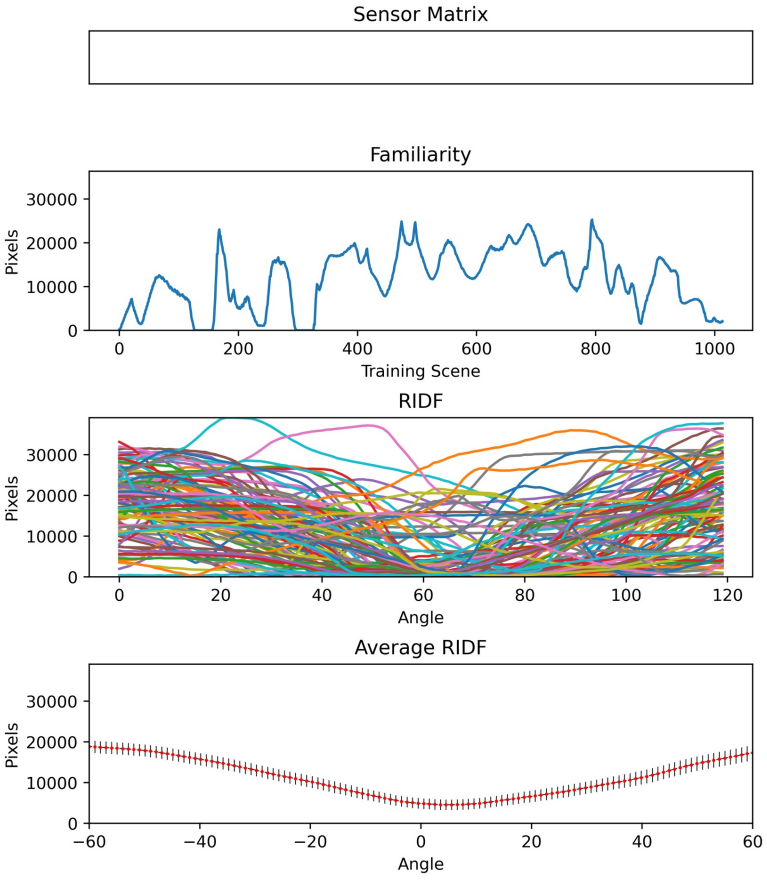

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 5556.90; RMSD/dist: 13.892; TD: 7596; p90: 50; p50: 28; complete: 0

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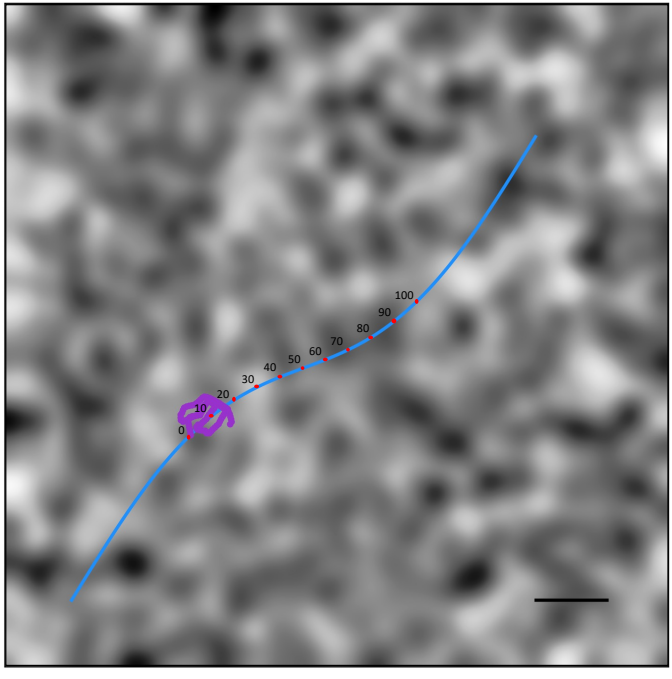

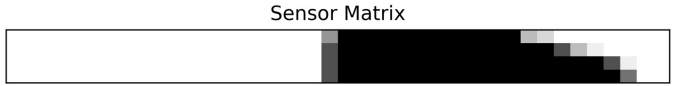

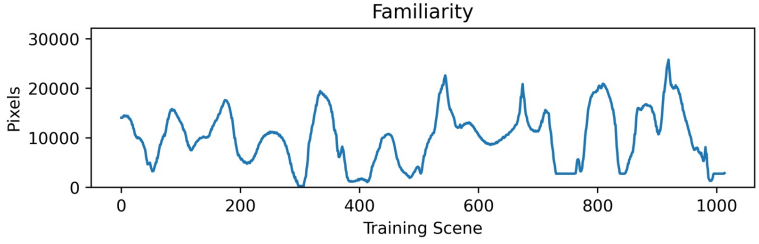

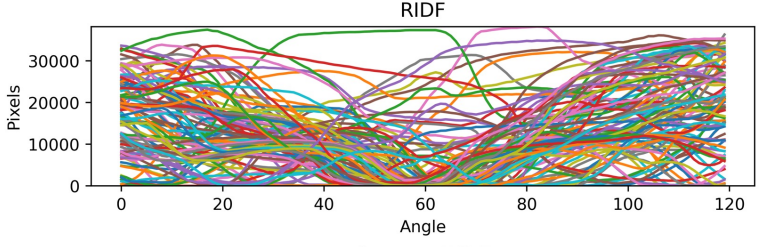

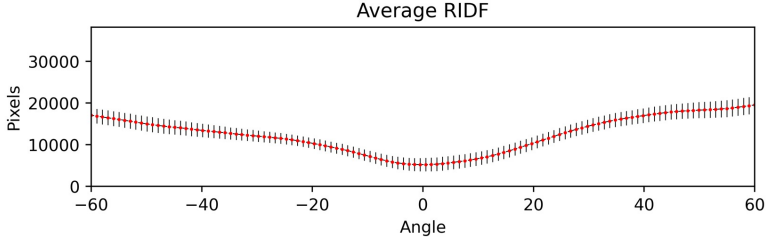

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 1561.18; RMSD/dist: 3.903; TD: 4964; p90: 36; p50: 22; complete: 0

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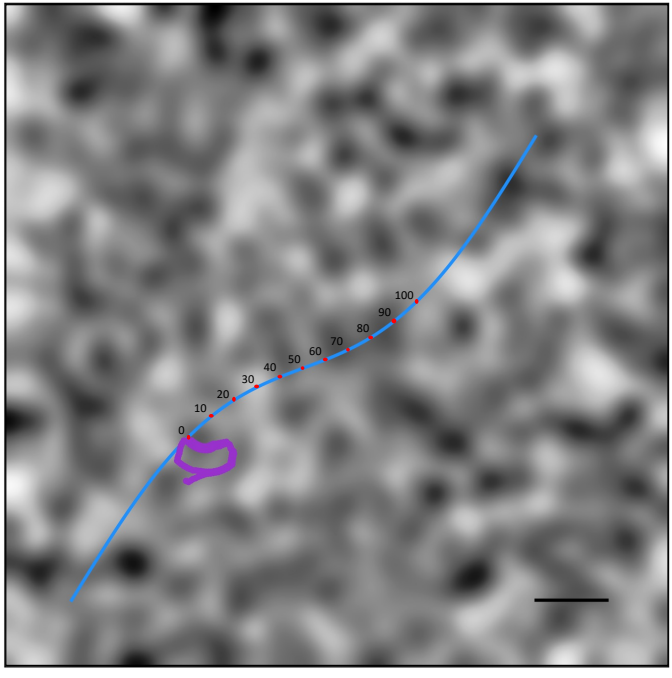

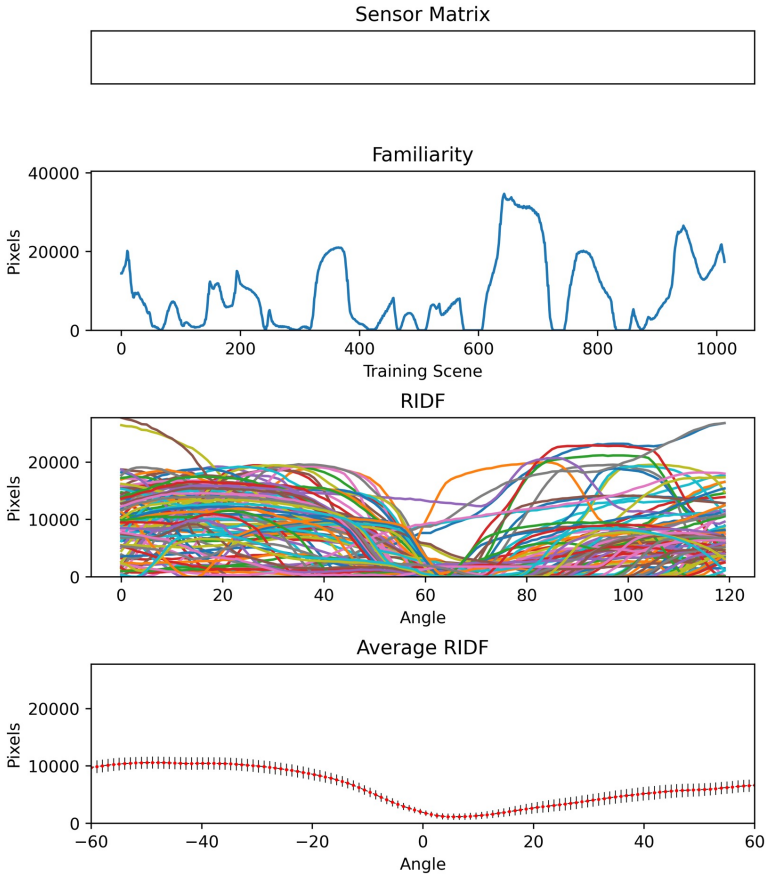

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Navigation stats: RMSD error: 4297.25; RMSD/dist: 10.743; TD: 9930; p90: 62; p50: 24; complete: 0

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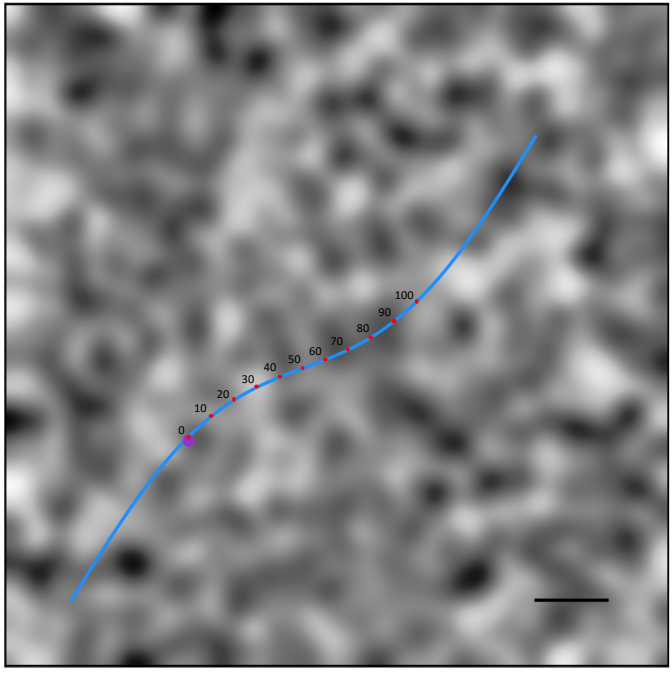

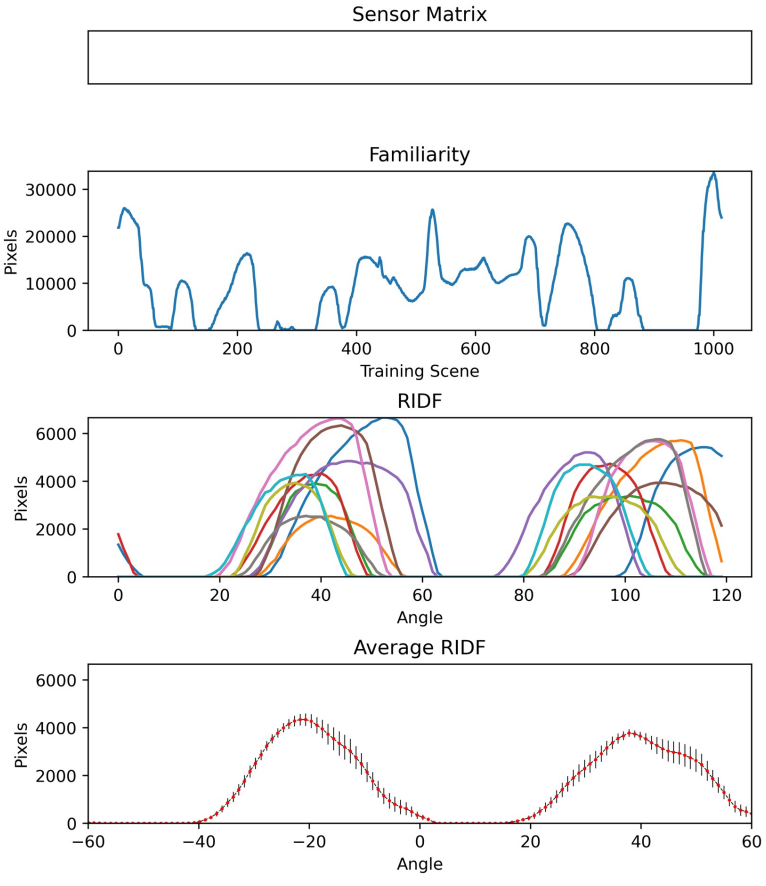

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 418.81; RMSD/dist: 1.047; TD: 9628; p90: 44; p50: 44; complete: 0

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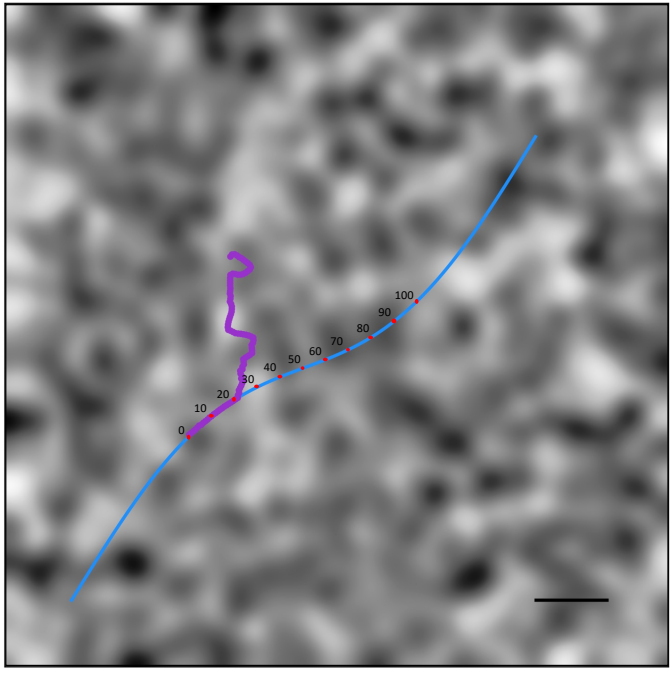
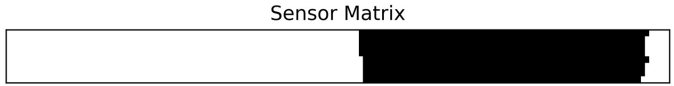
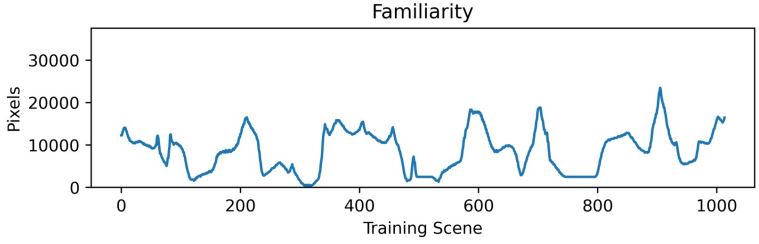
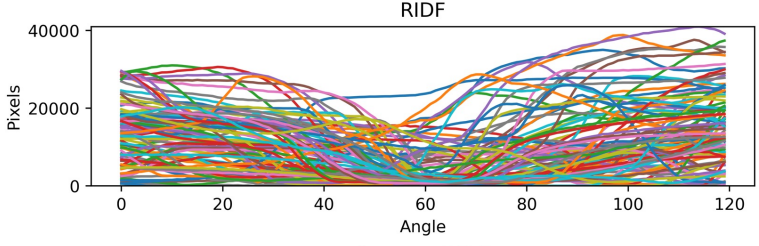
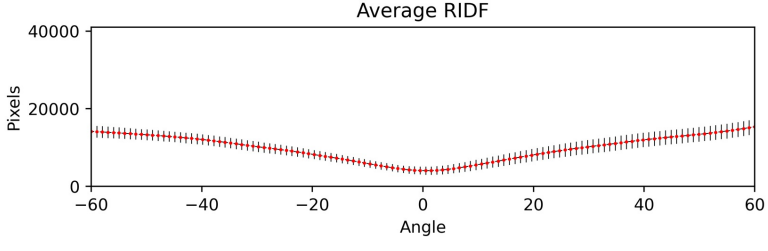




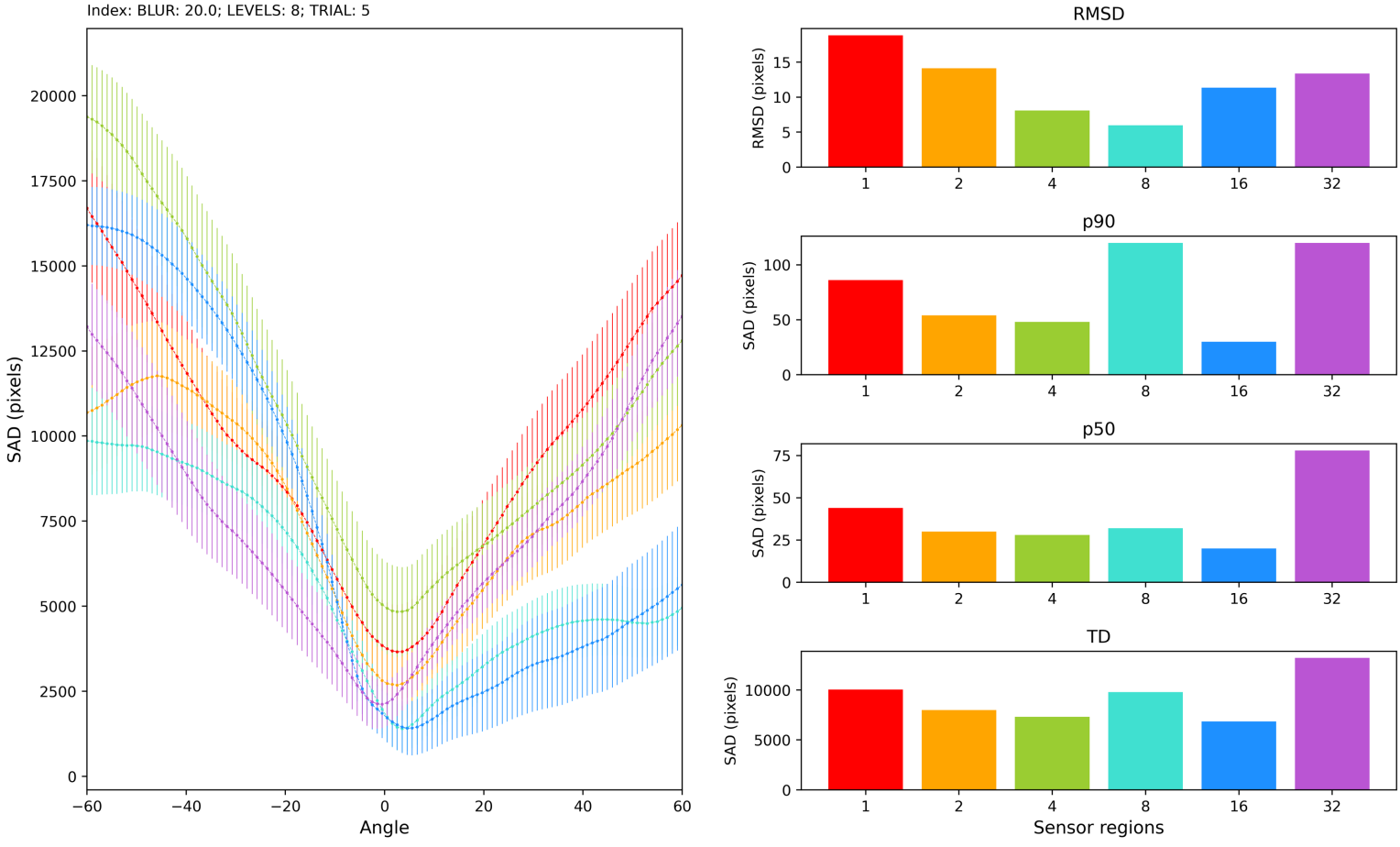






Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 4

Navigation stats: RMSD error: 8051.12; RMSD/dist: 20.128; TD: 8423; p90: 74; p50: 40; complete: 0


Index: BLUR: 20.0; LEVELS: 8; TRIAL: 5
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

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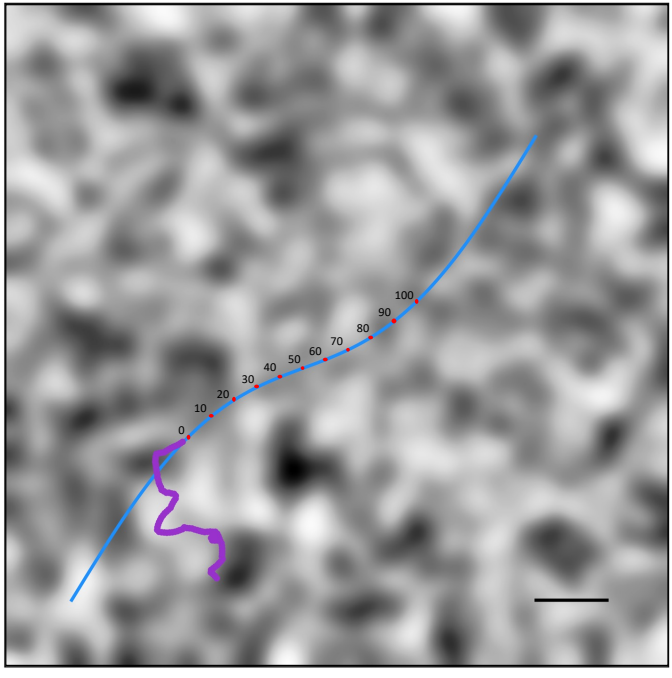

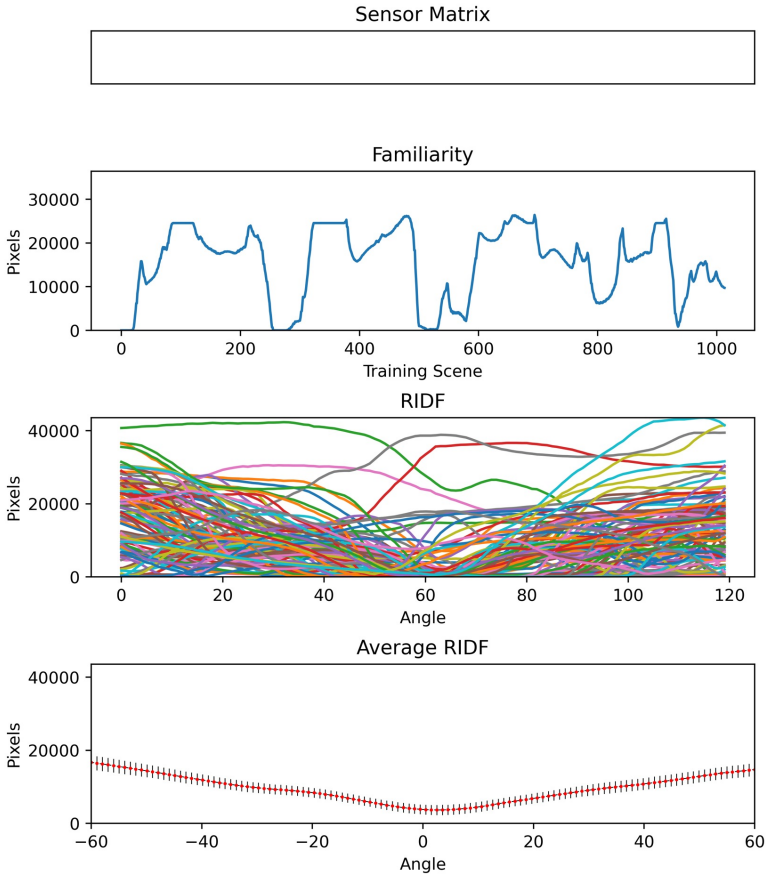

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 7539.99; RMSD/dist: 18.850; TD: 10044; p90: 86; p50: 44; complete: 0

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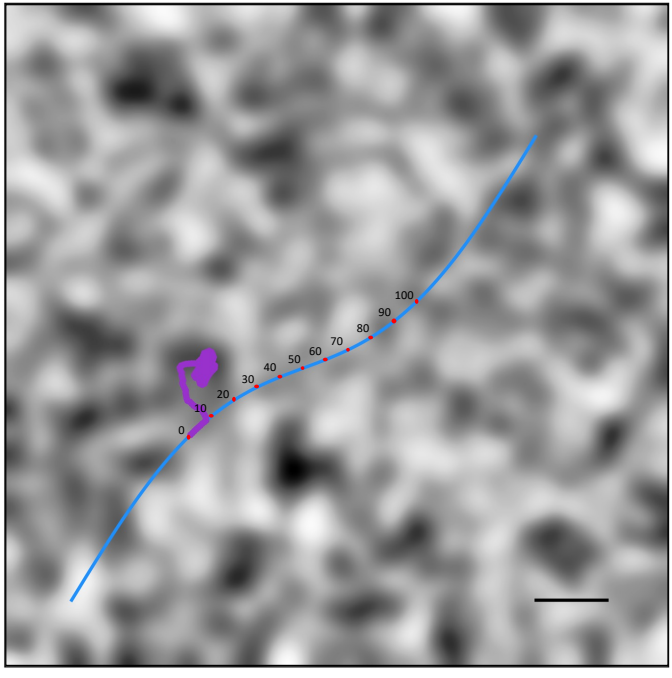

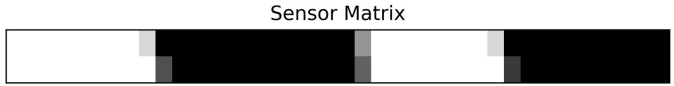

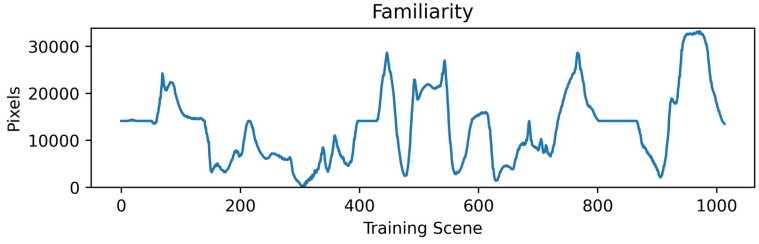

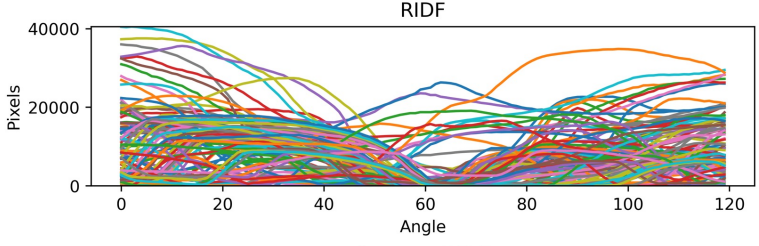

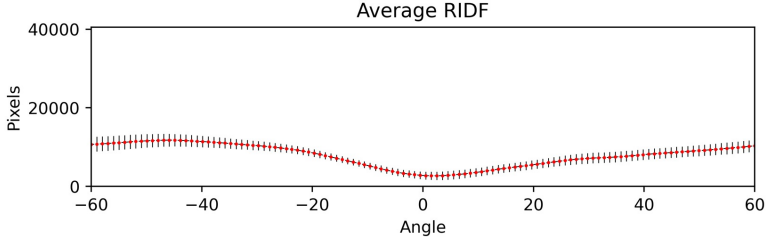

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 5

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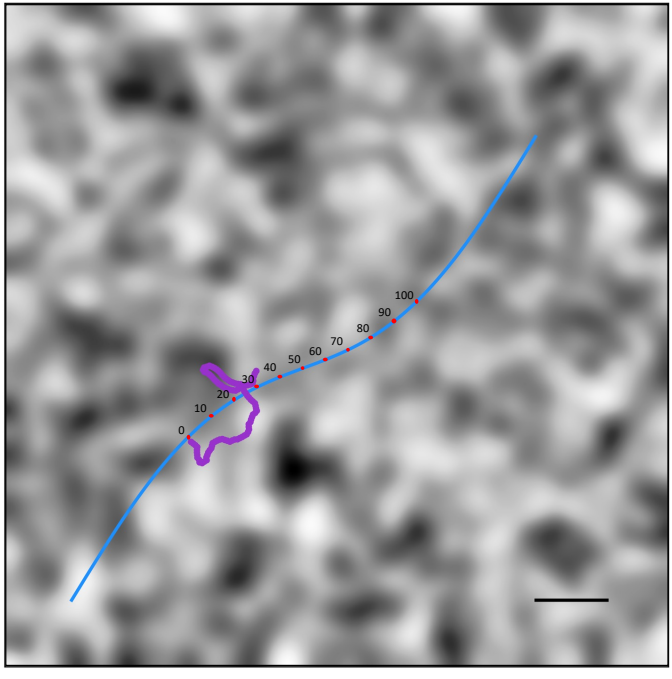

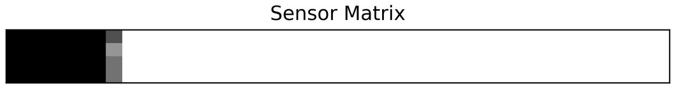

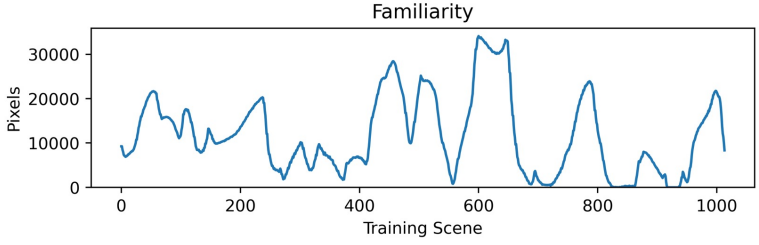

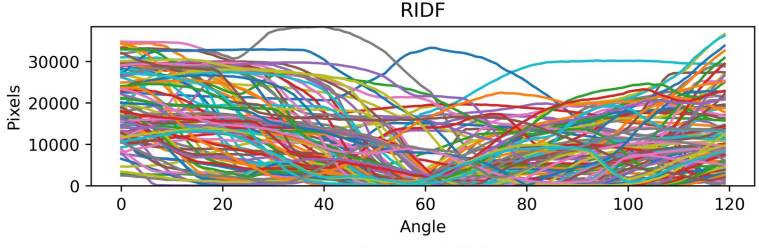

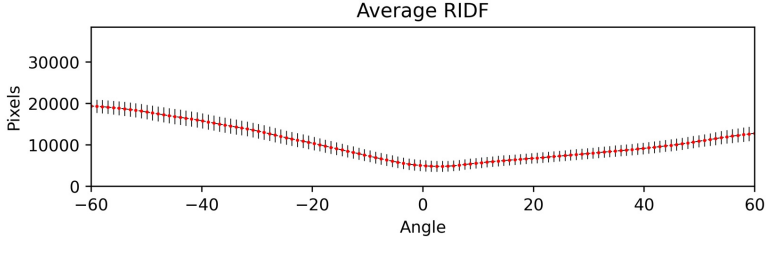

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 3230.62; RMSD/dist: 8.077; TD: 7309; p90: 48; p50: 28; complete: 0

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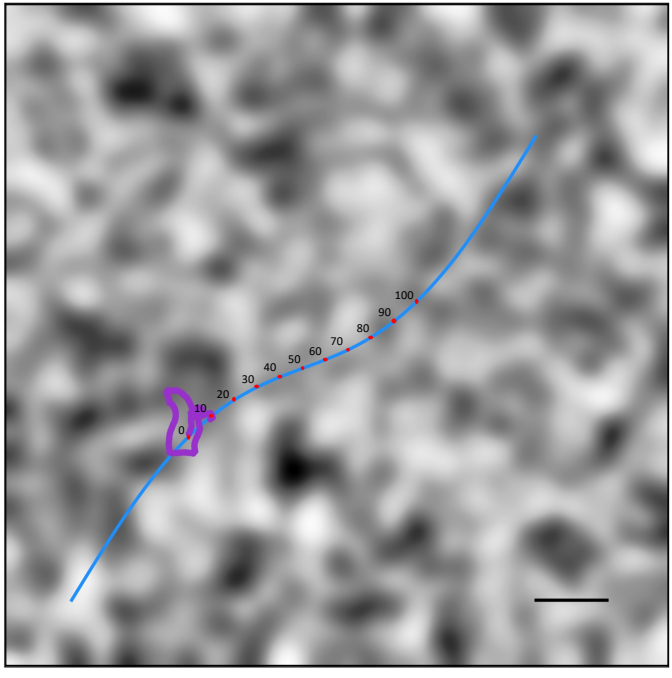

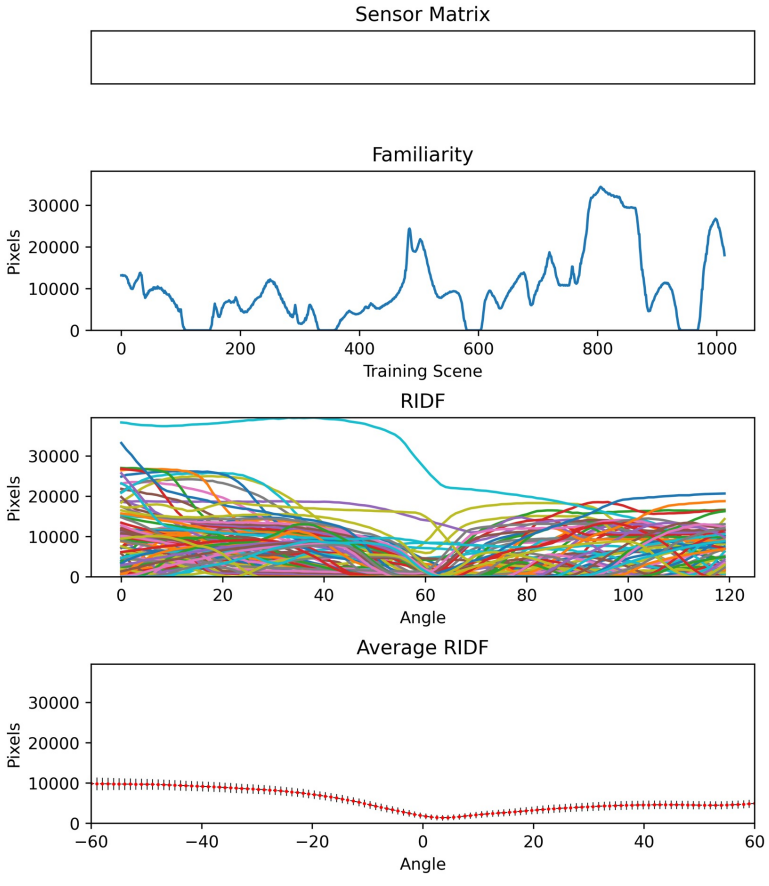

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Navigation stats: RMSD error: 2390.42; RMSD/dist: 5.976; TD: 9786; p90: 120; p50: 32; complete: 0

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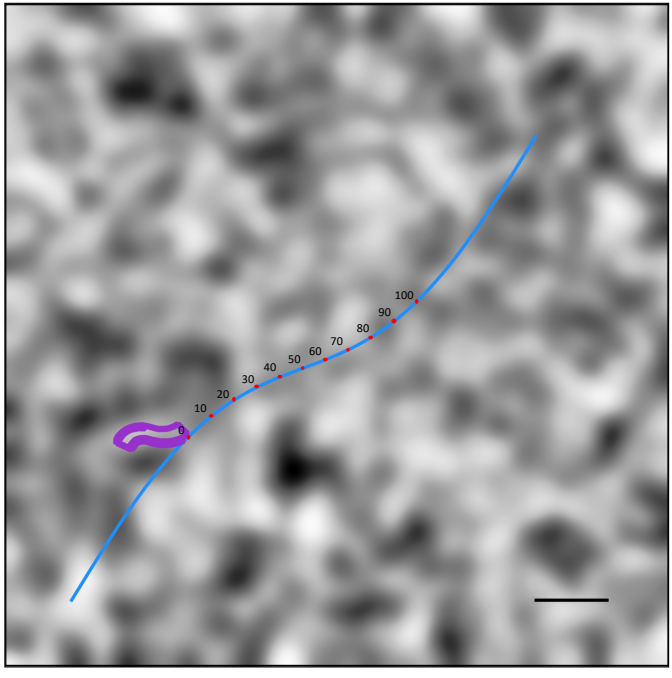

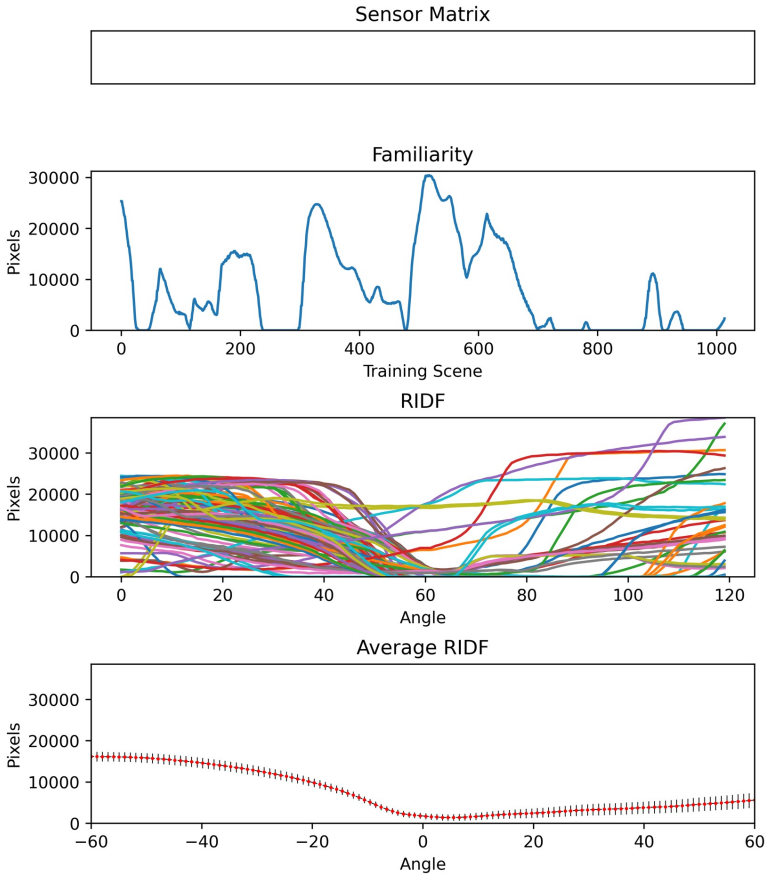

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 4536.43; RMSD/dist: 11.341; TD: 6840; p90: 30; p50: 20; complete: 0

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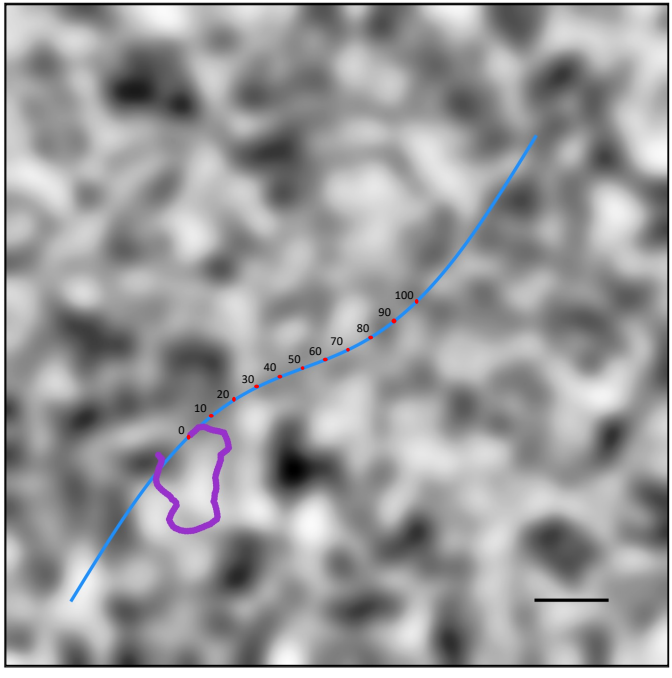
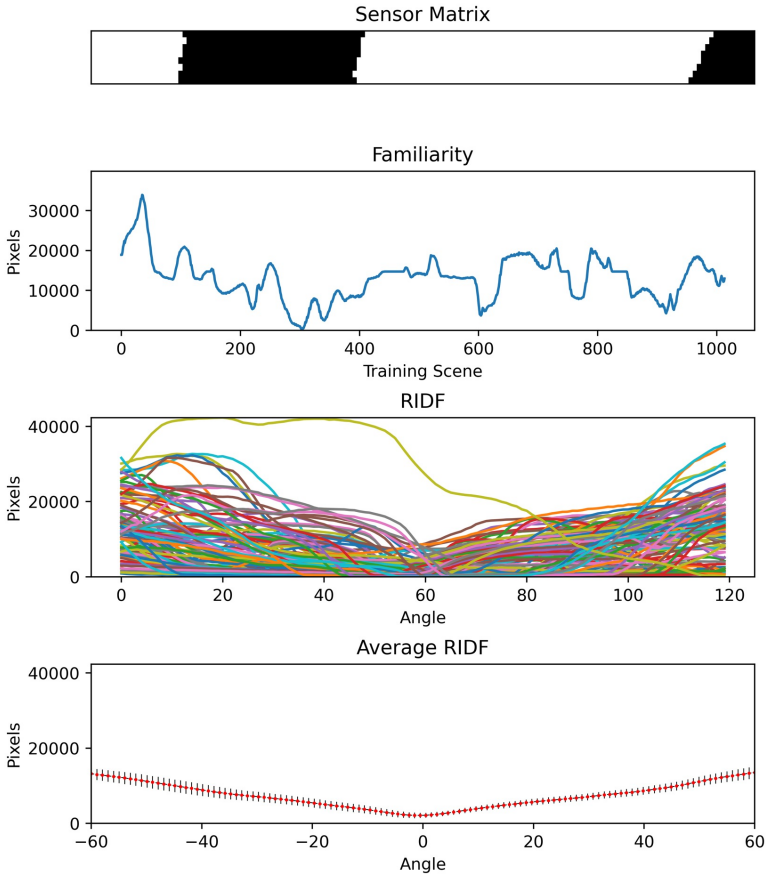
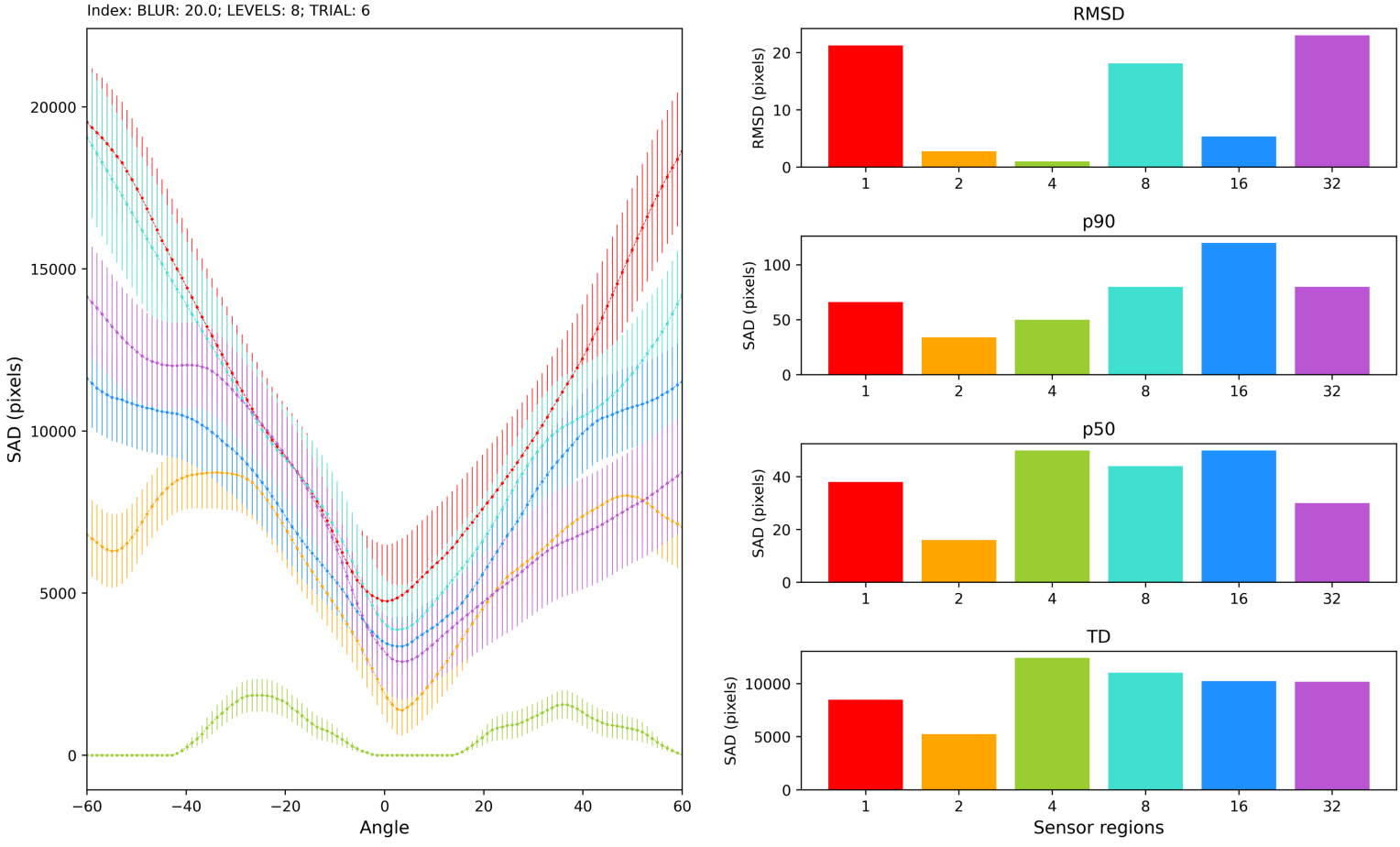


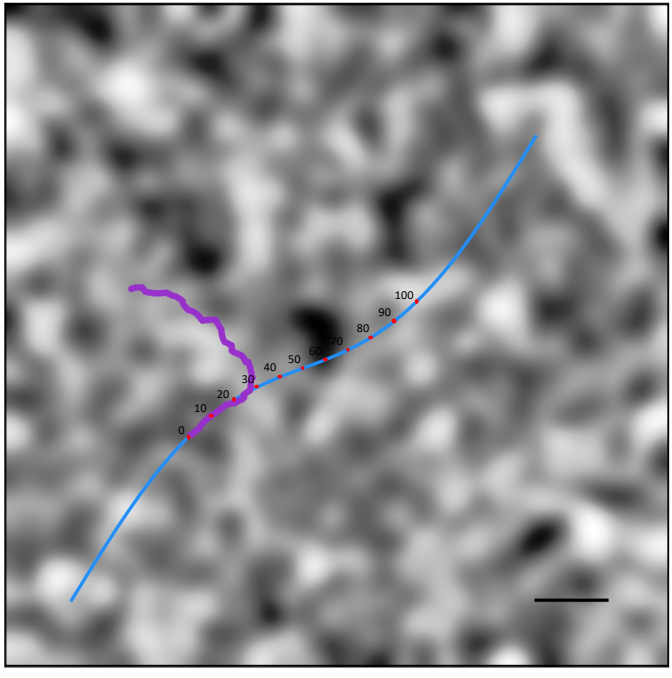


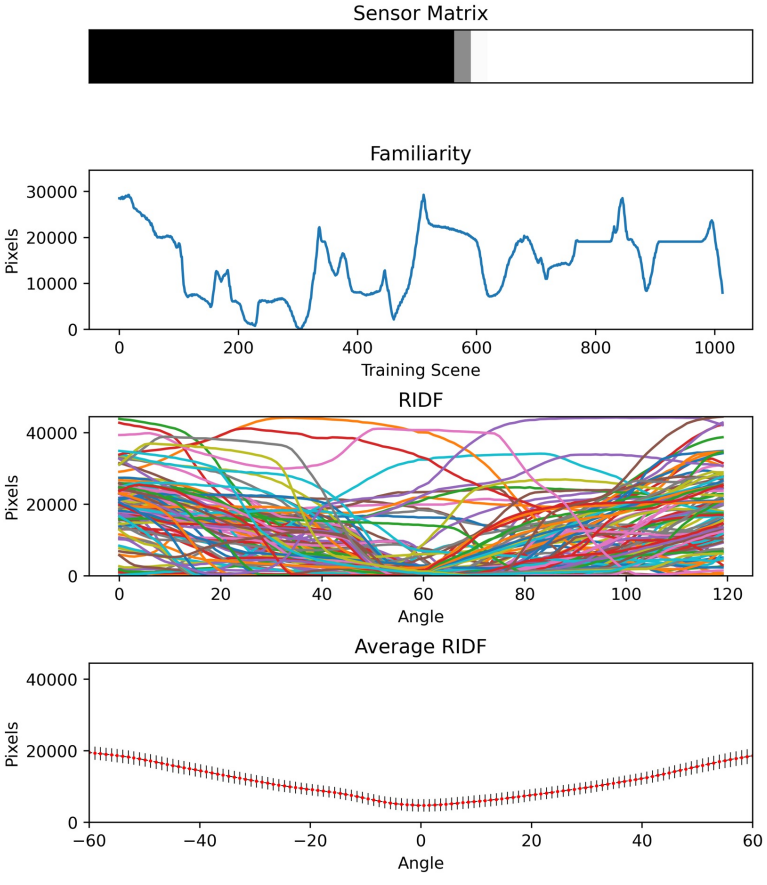
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 5

Navigation stats: RMSD error: 5350.05; RMSD/dist: 13.375; TD: 13202; p90: 120; p50: 78; complete: 0


Index: BLUR: 20.0; LEVELS: 8; TRIAL: 6
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 8507.31; RMSD/dist: 21.268; TD: 8492; p90: 66; p50: 38; complete: 0

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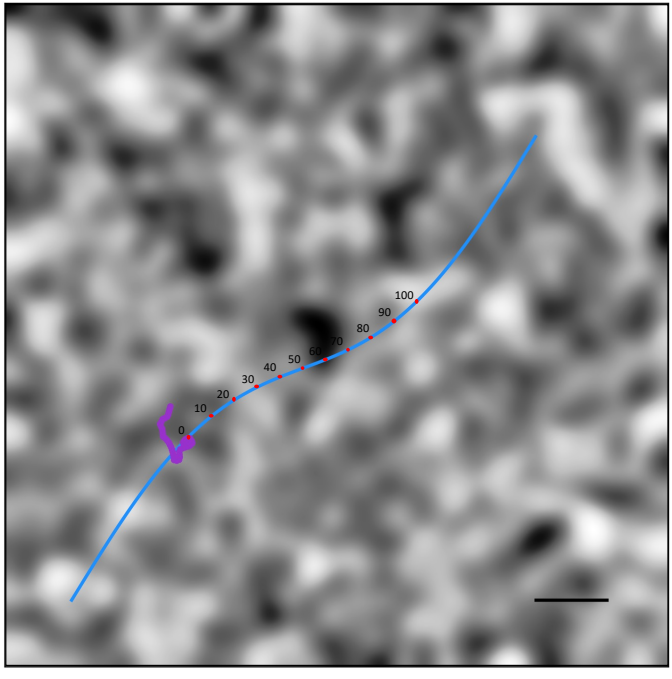
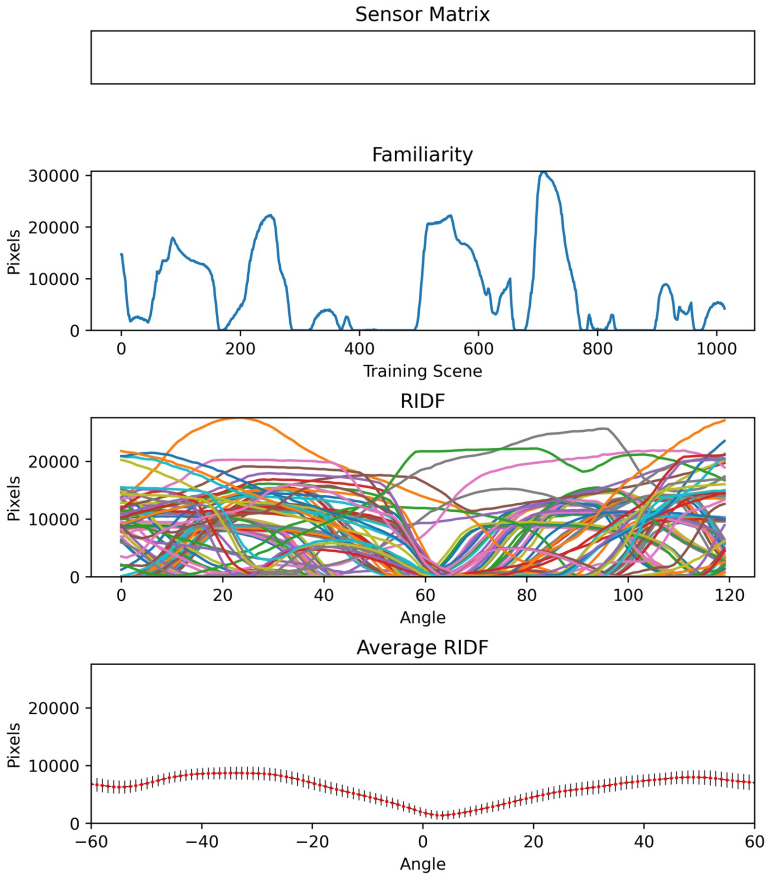
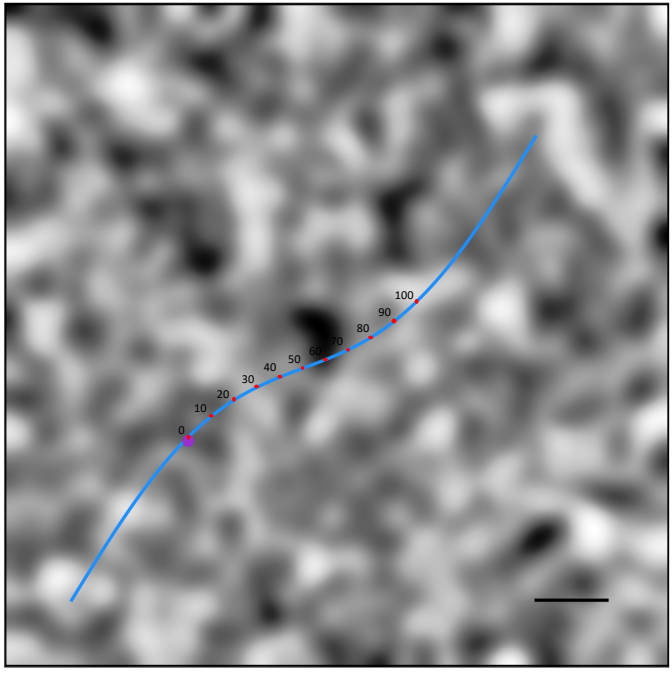


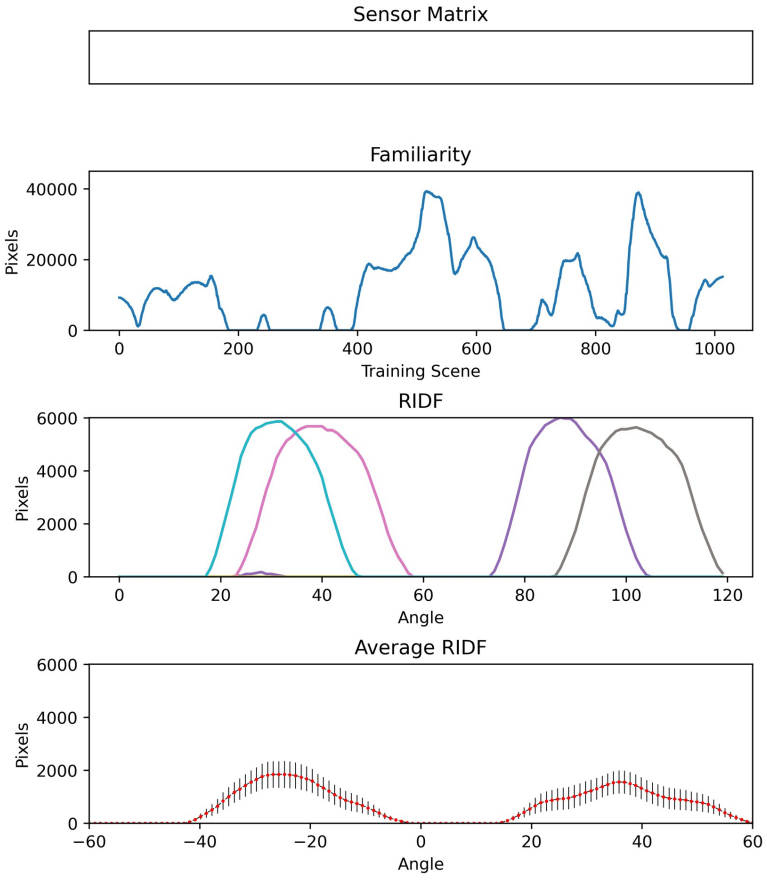


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 1109.79; RMSD/dist: 2.774; TD: 5239; p90: 34; p50: 16; complete: 0

0%





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Navigation stats: RMSD error: 390.57; RMSD/dist: 0.976; TD: 12414; p90: 50; p50: 50; complete: 0

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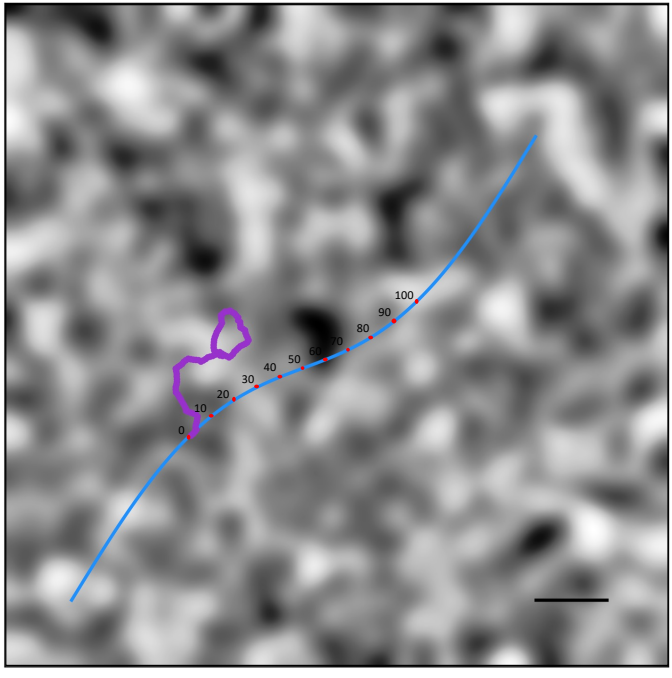

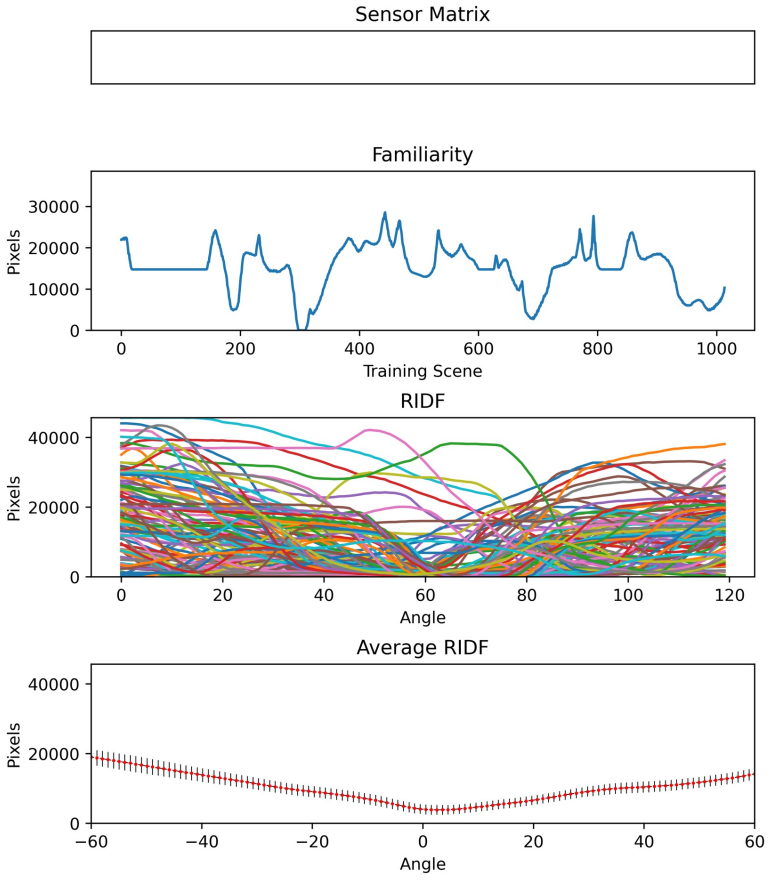

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 6

Navigation stats: RMSD error: 7244.69; RMSD/dist: 18.112; TD: 11039; p90: 80; p50: 44; complete: 0

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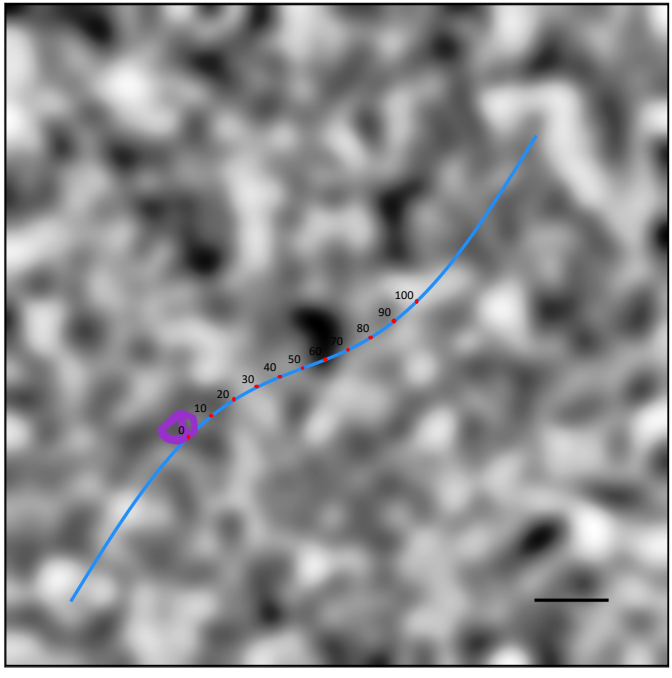

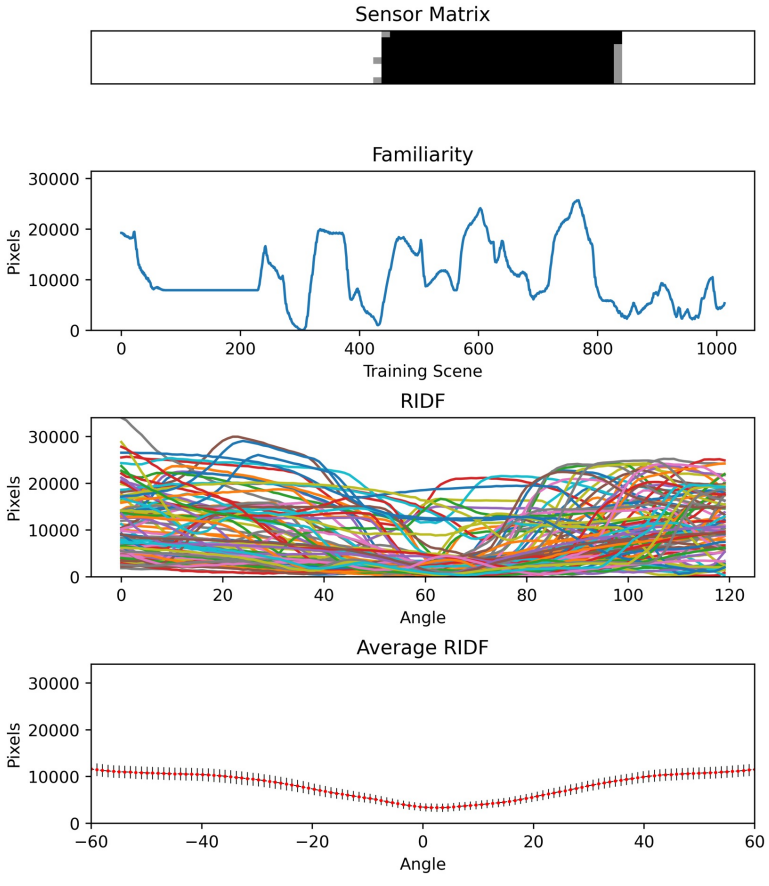

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Navigation stats: RMSD error: 2133.82; RMSD/dist: 5.335; TD: 10245; p90: 120; p50: 50; complete: 0

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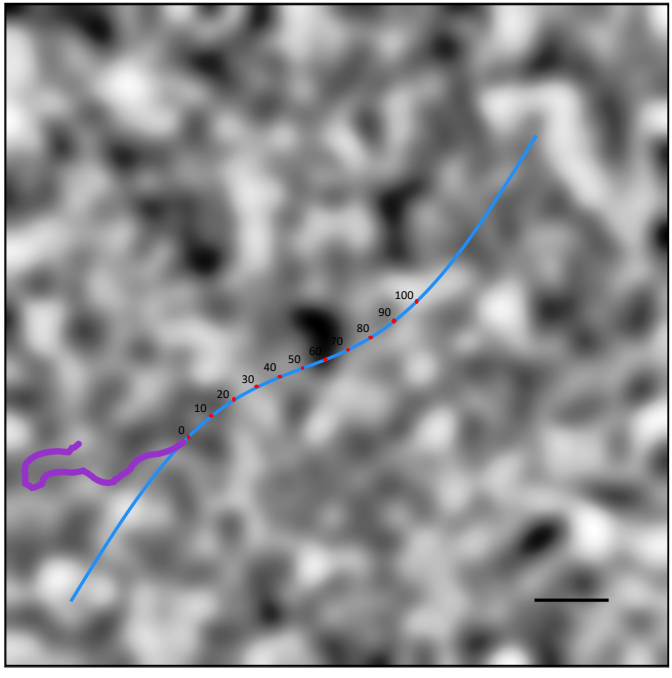

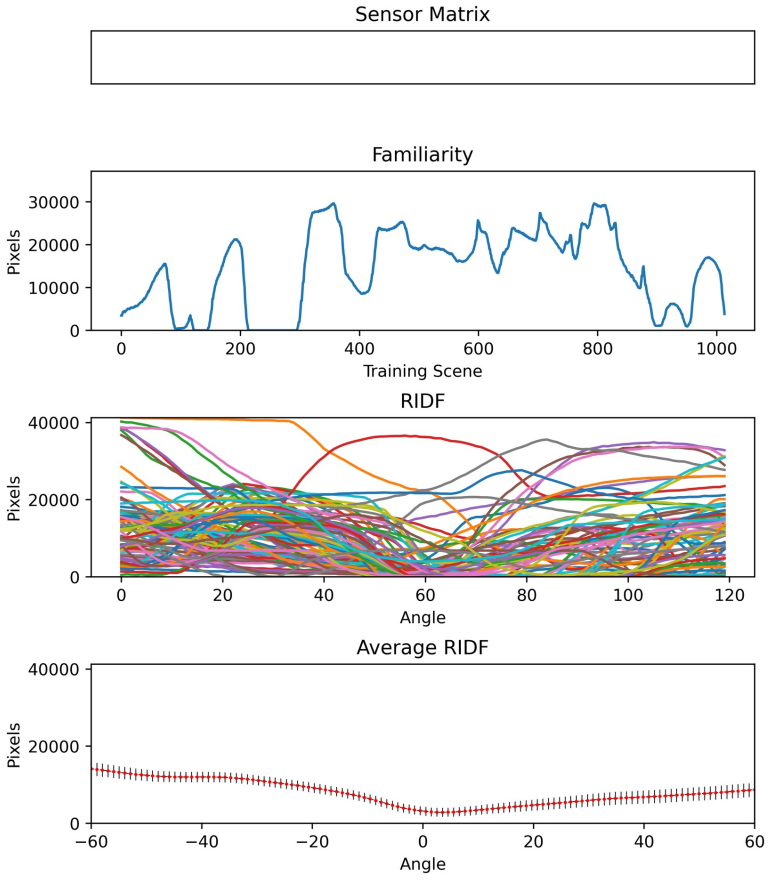

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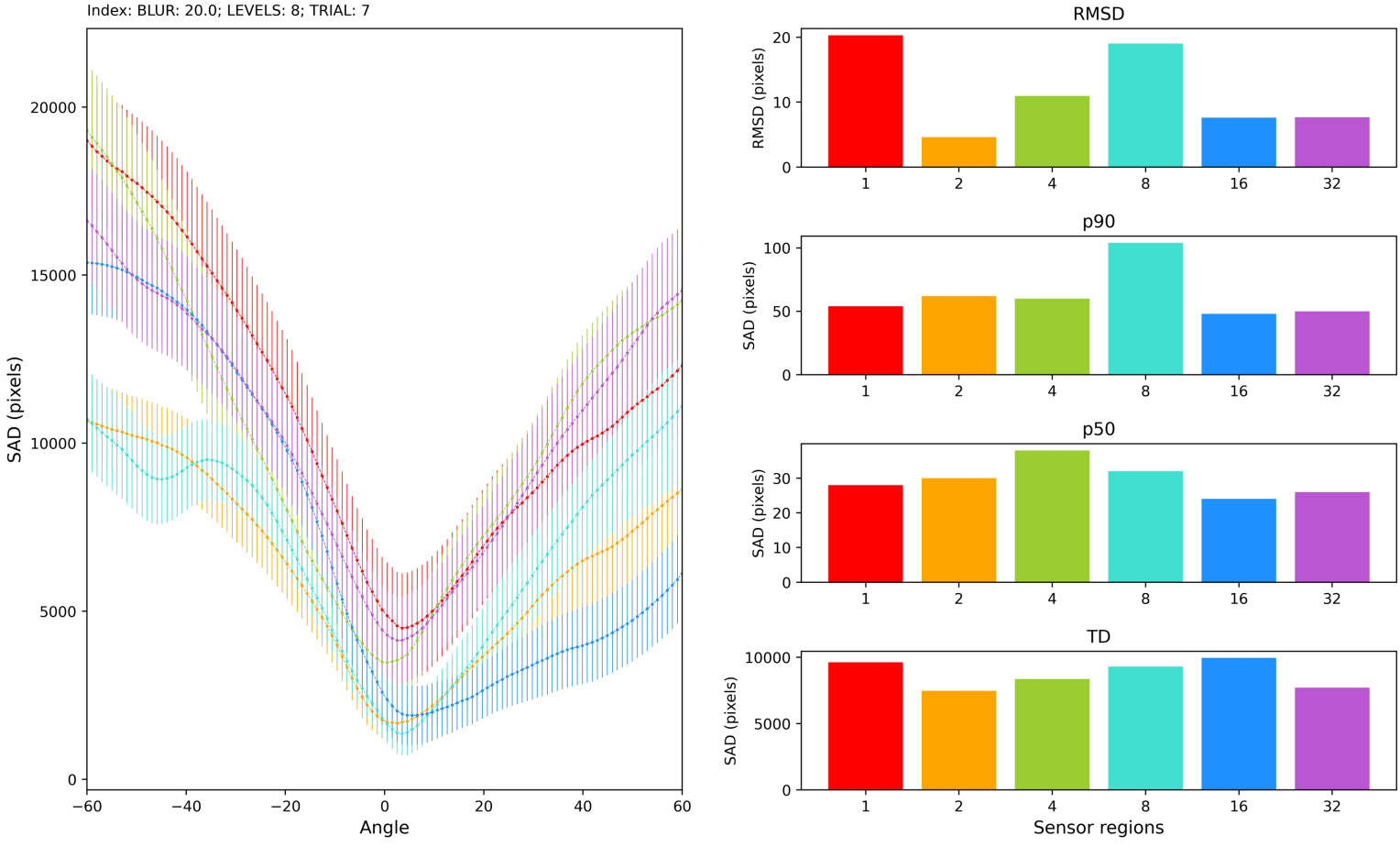
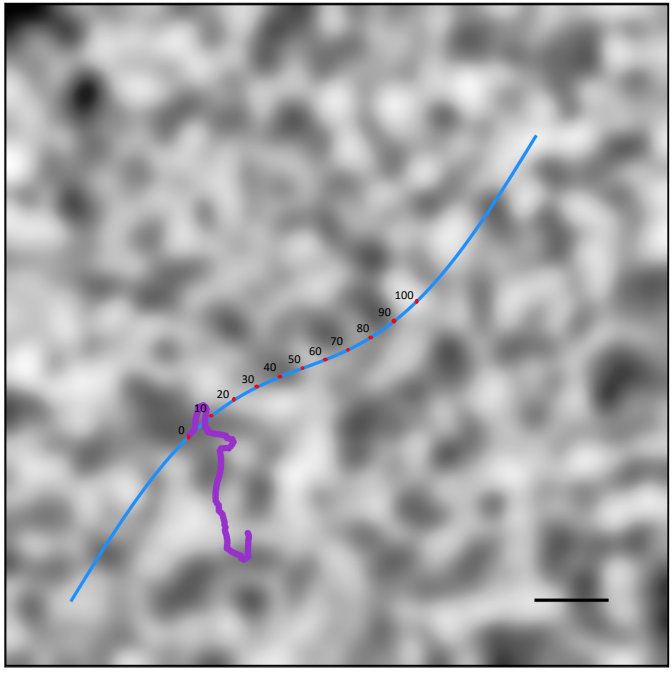
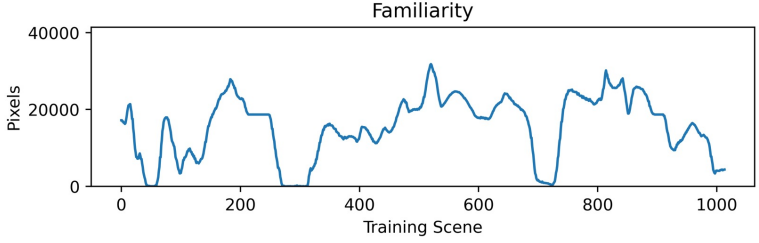
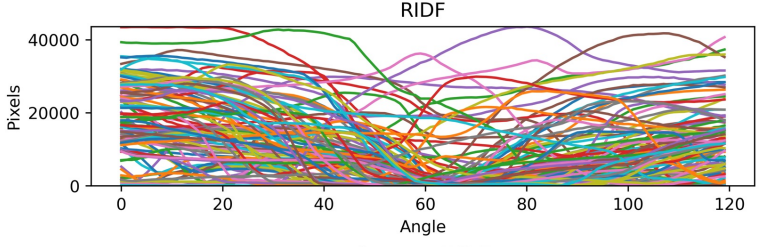
Navigation stats: RMSD error: 9224.41; RMSD/dist: 23.061; TD: 10171; p90: 80; p50: 30; complete: 0

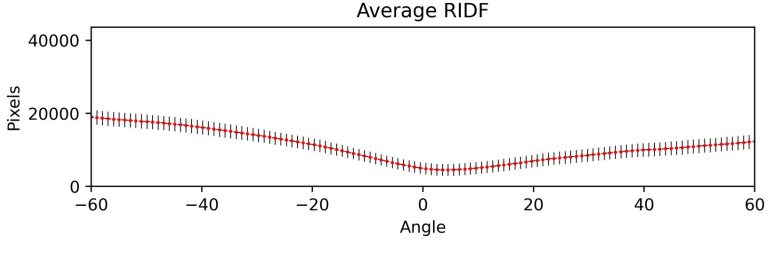

Index: BLUR: 20.0; LEVELS: 8; TRIAL: 7
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%









Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 8119.98; RMSD/dist: 20.300; TD: 9610; p90: 54; p50: 28; complete: 0

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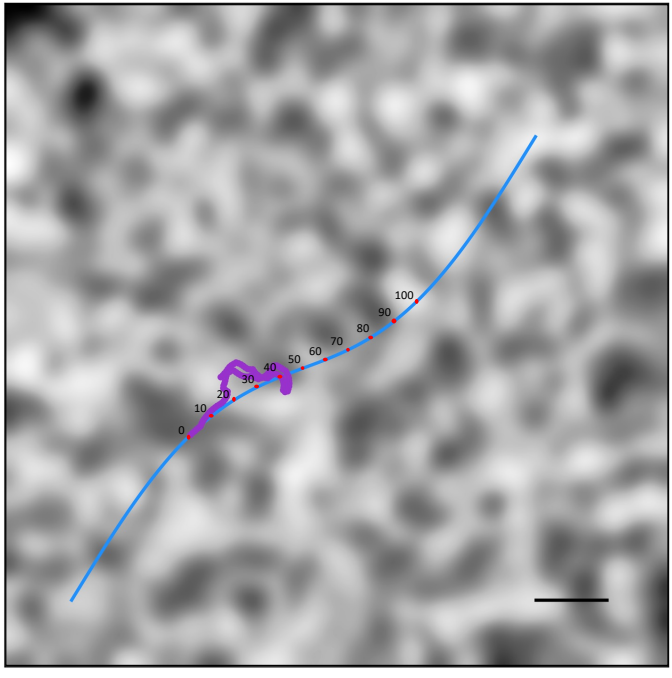

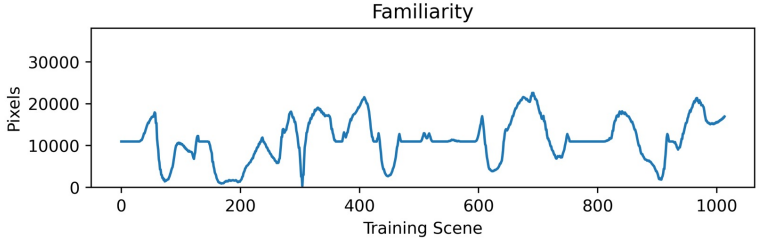

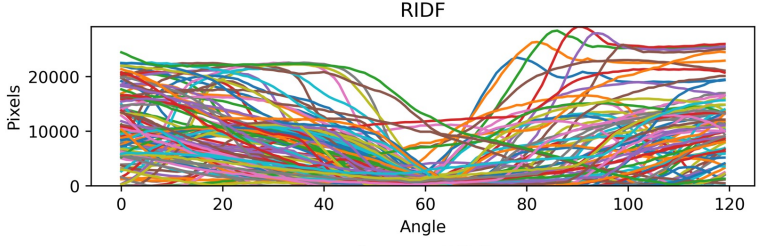

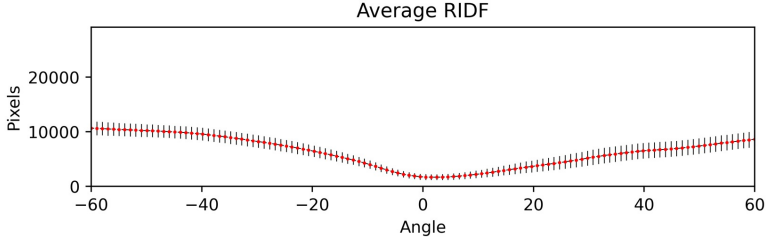

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 1838.33; RMSD/dist: 4.596; TD: 7455; p90: 62; p50: 30; complete: 0

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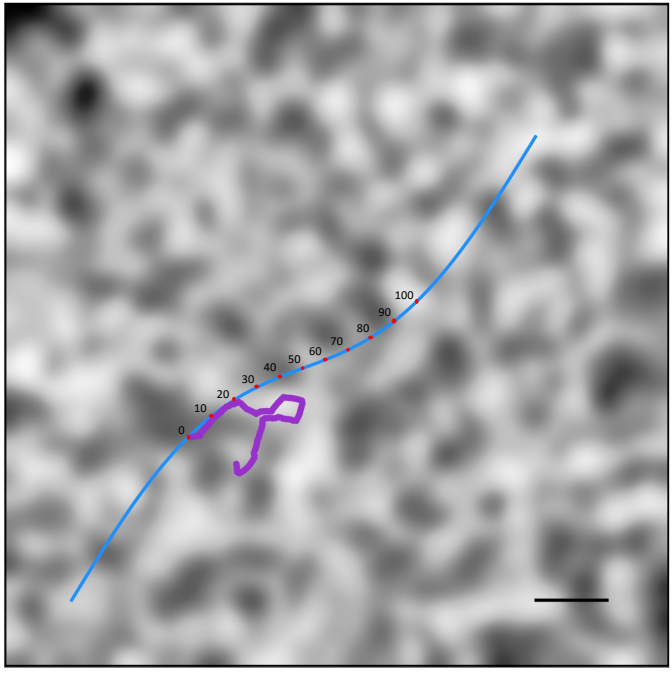
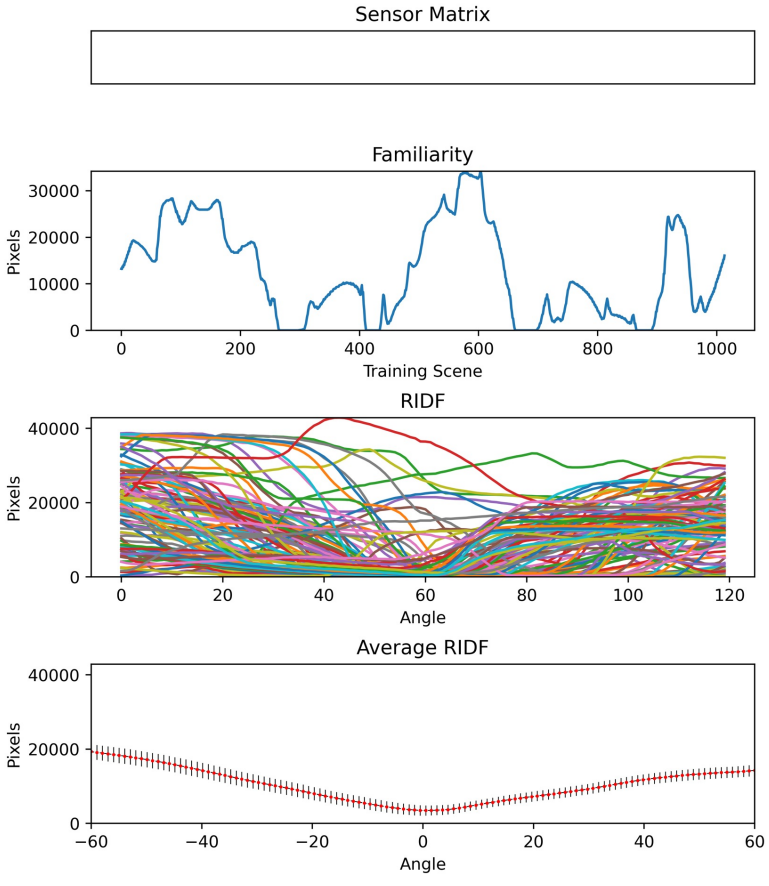
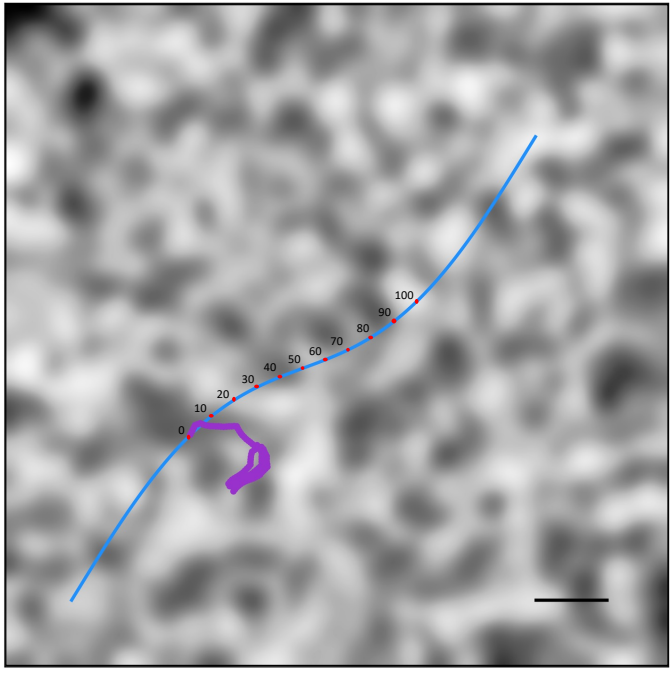


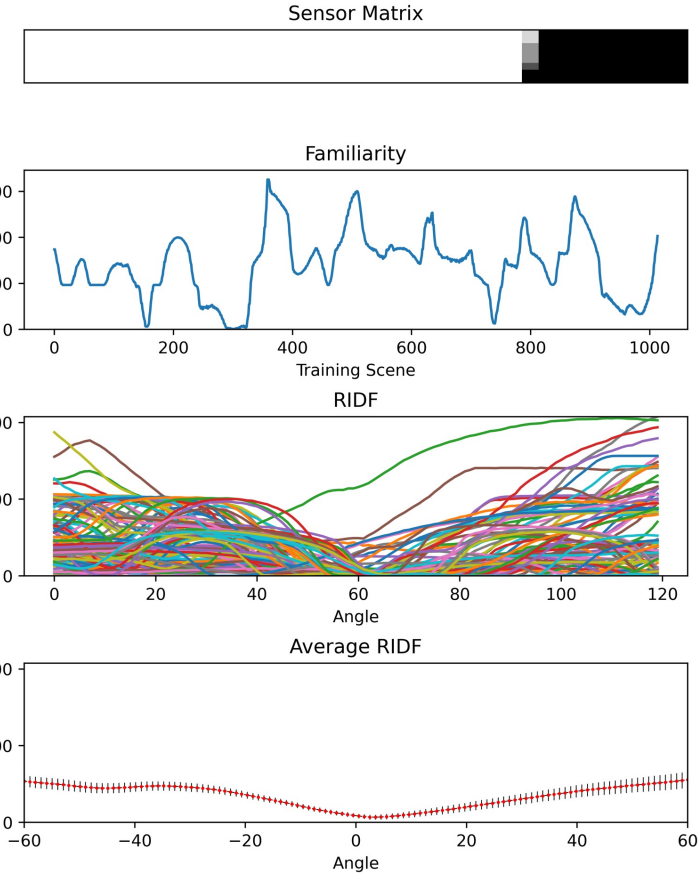


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 4377.97; RMSD/dist: 10.945; TD: 8347; p90: 60; p50: 38; complete: 0

0%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 7610.87; RMSD/dist: 19.027; TD: 9296; p90: 104; p50: 32; complete: 0

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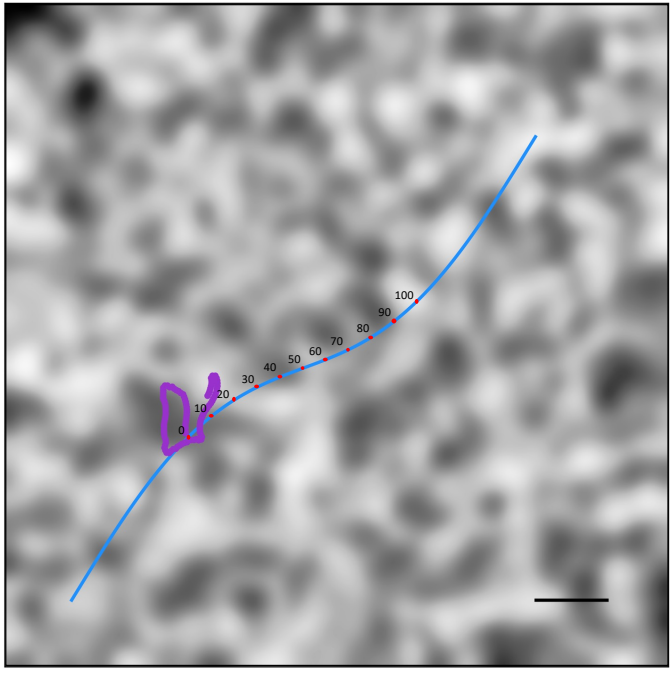

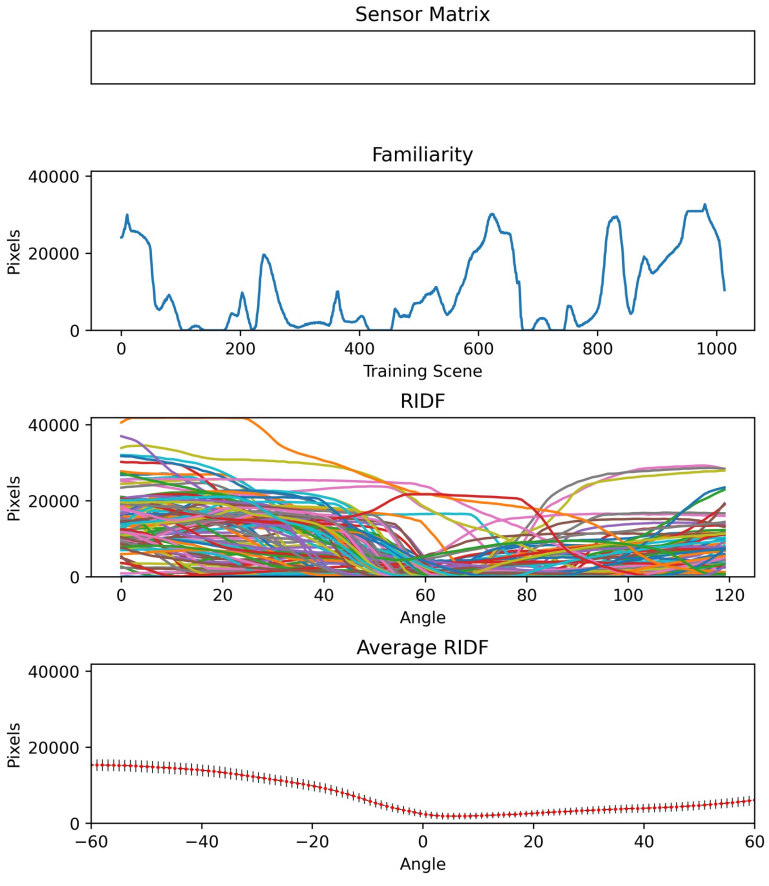

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3043.12; RMSD/dist: 7.608; TD: 9939; p90: 48; p50: 24; complete: 0

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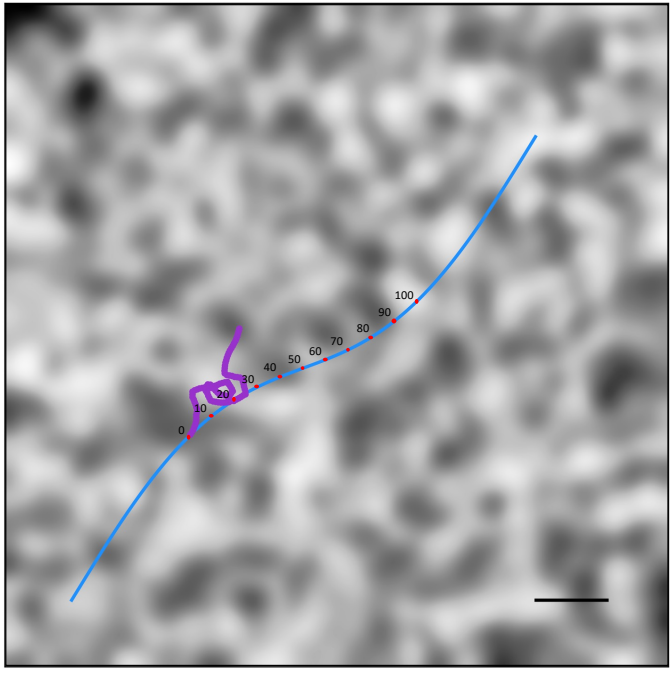
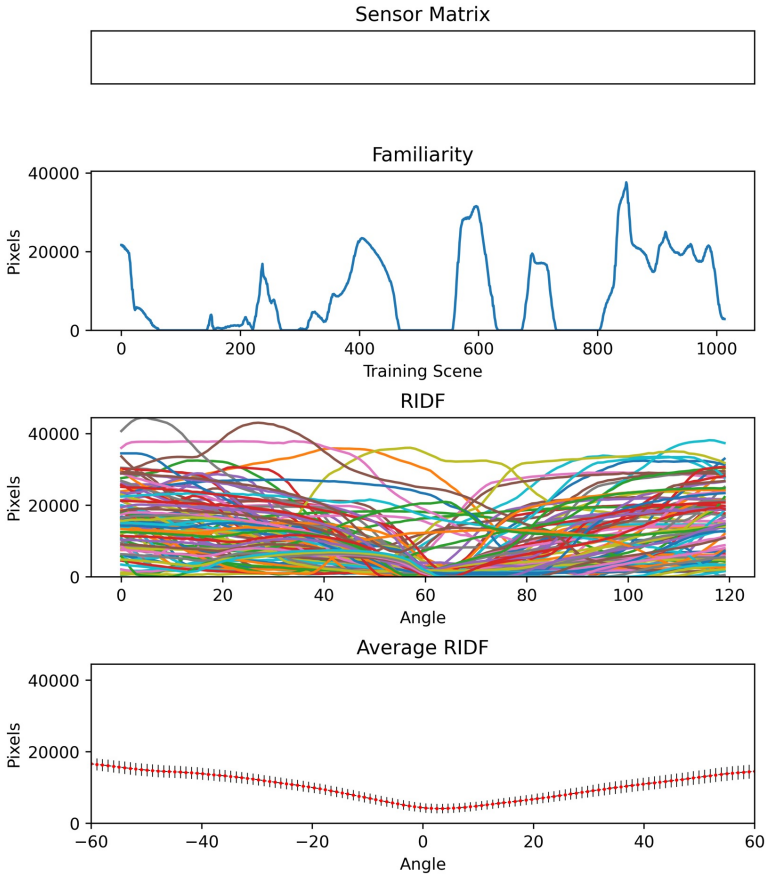
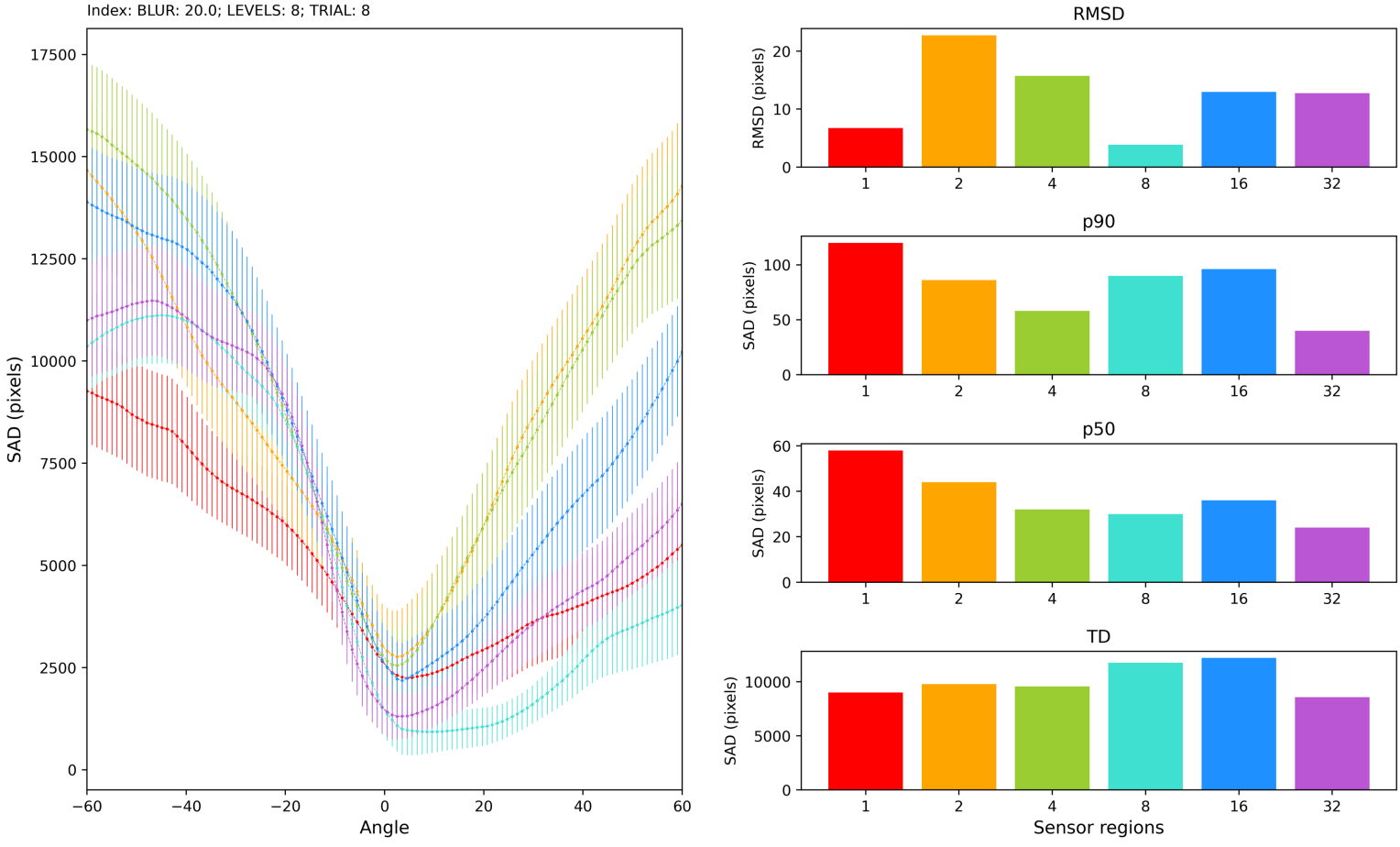




Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 7

Navigation stats: RMSD error: 3061.15; RMSD/dist: 7.653; TD: 7703; p90: 50; p50: 26; complete: 0


Index: BLUR: 20.0; LEVELS: 8; TRIAL: 8
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

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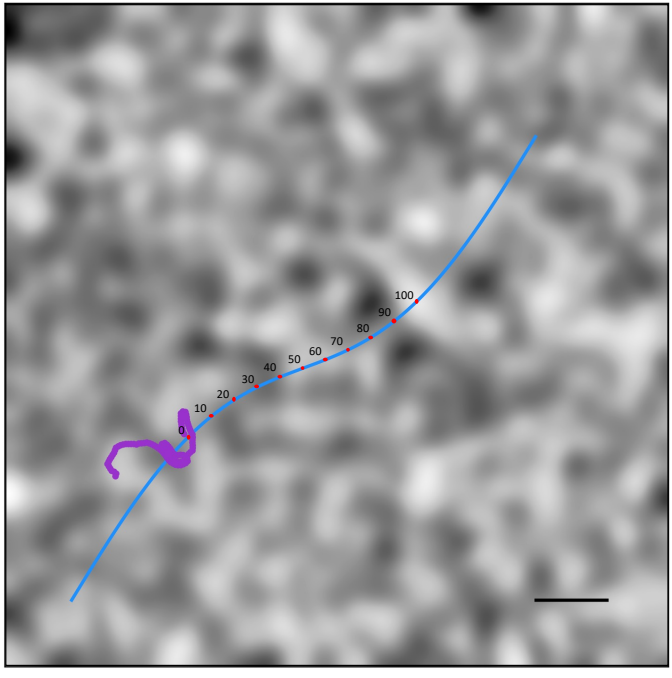

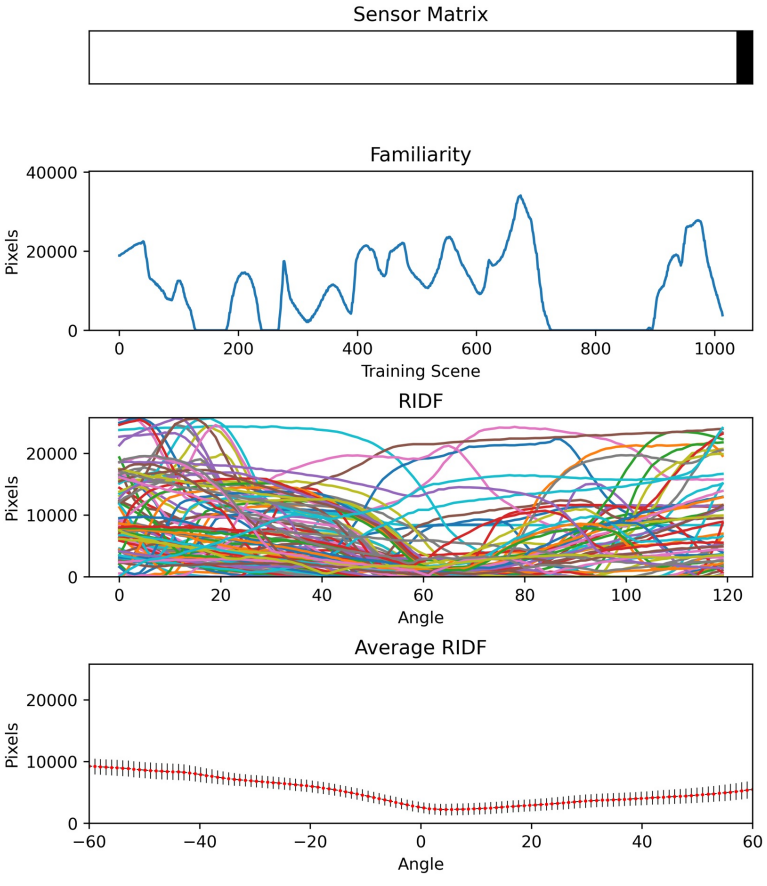

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 2691.14; RMSD/dist: 6.728; TD: 8993; p90: 120; p50: 58; complete: 0

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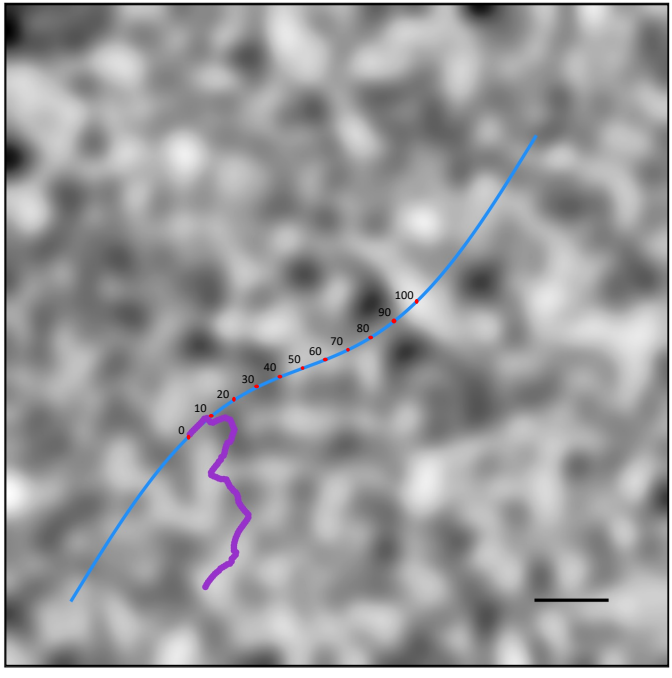

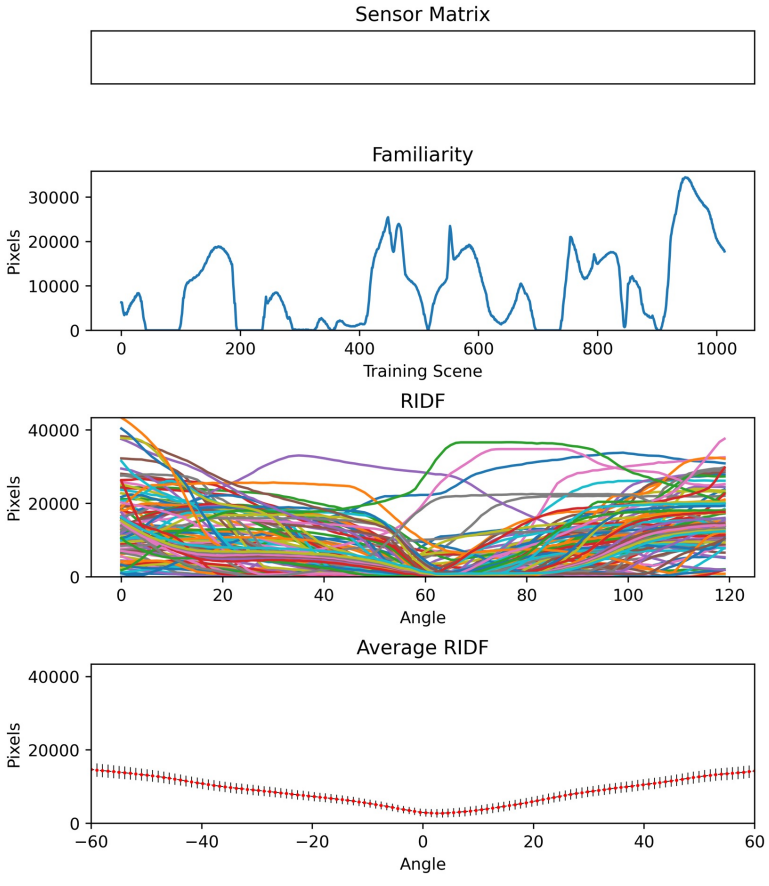

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 9100.25; RMSD/dist: 22.751; TD: 9780; p90: 86; p50: 44; complete: 0

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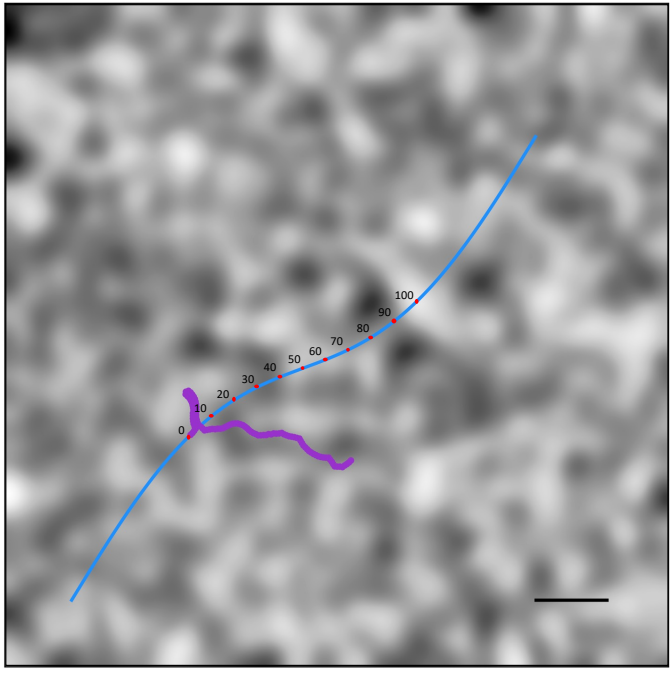

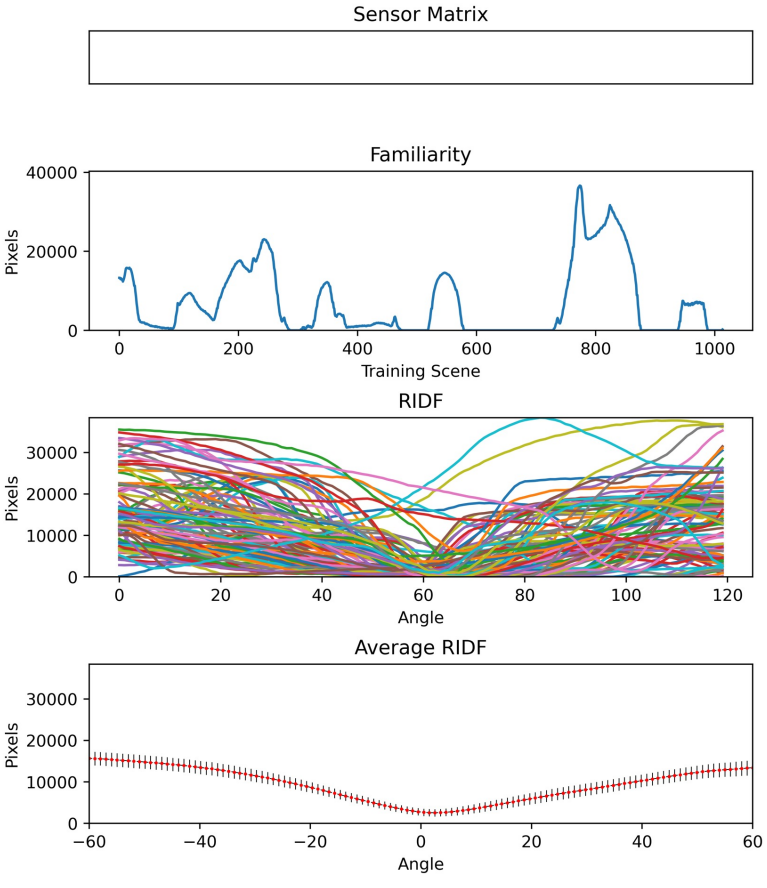

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 6287.15; RMSD/dist: 15.718; TD: 9572; p90: 58; p50: 32; complete: 0

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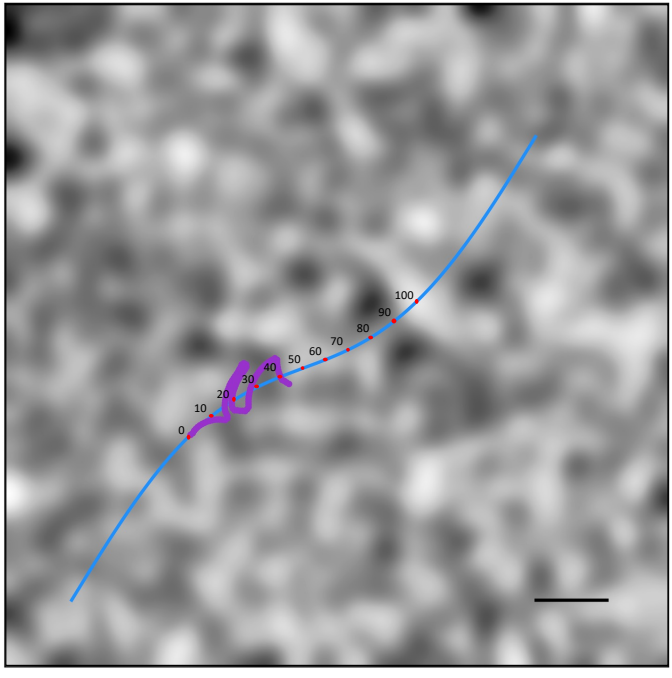

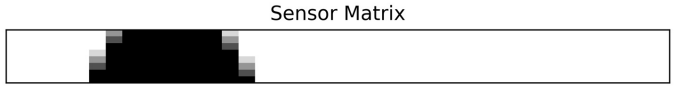

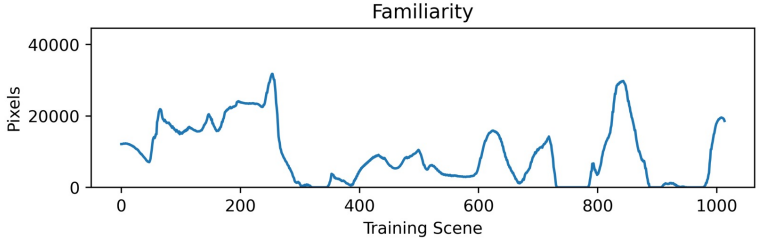

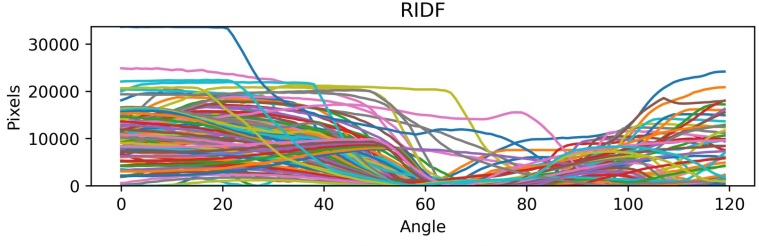

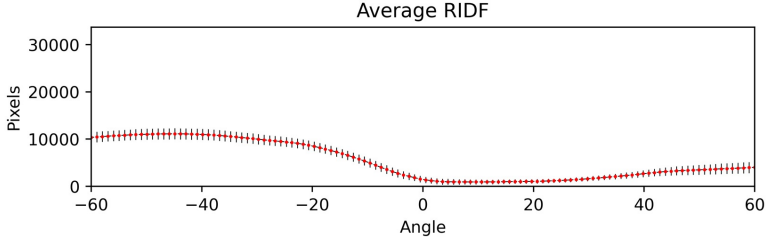

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 8

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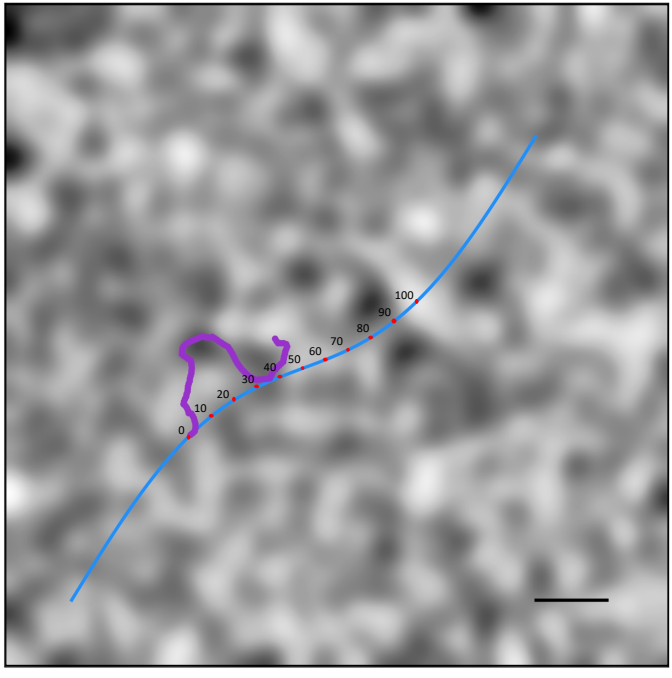
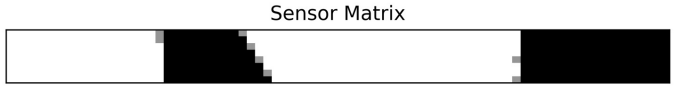
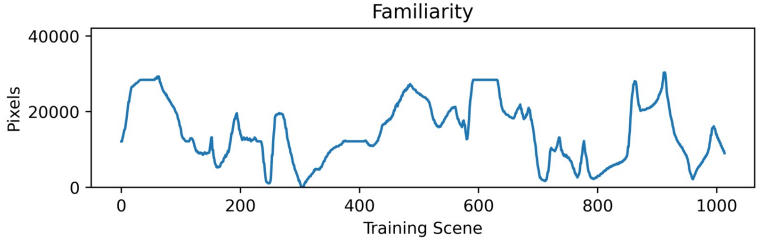
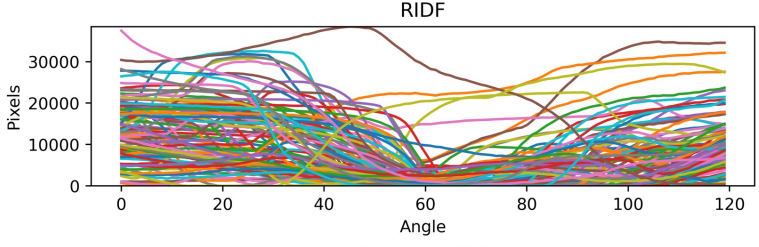
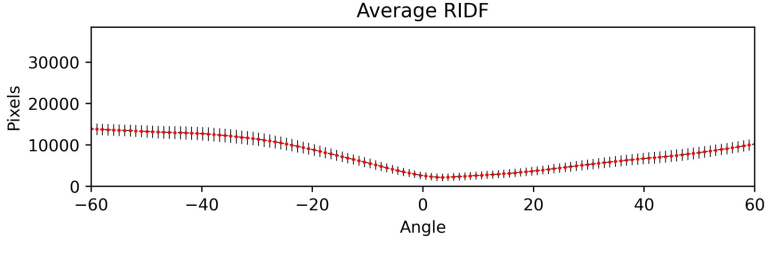






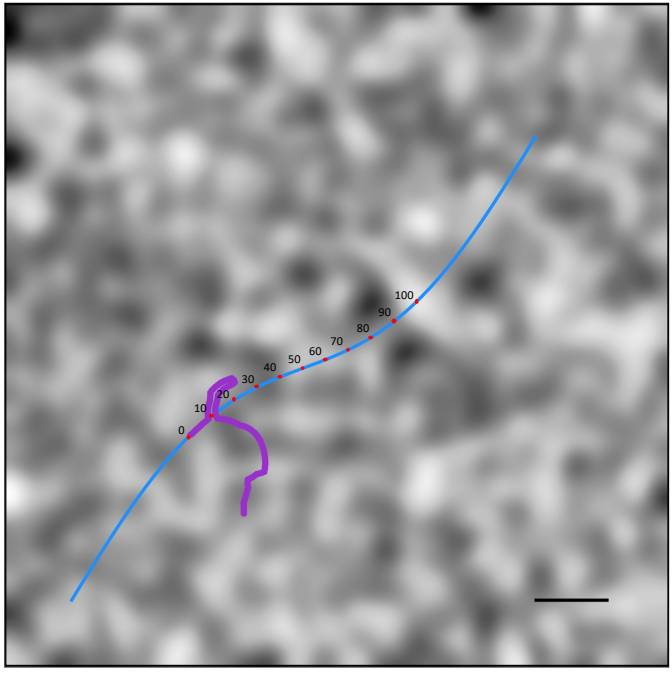


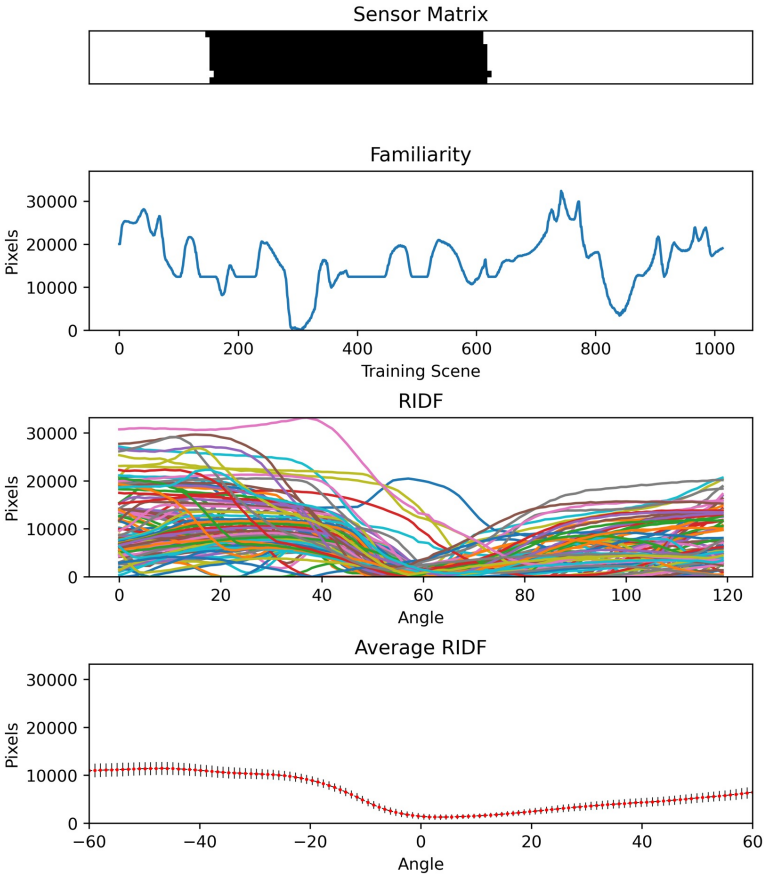


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5190.54; RMSD/dist: 12.976; TD: 12191; p90: 96; p50: 36; complete: 0

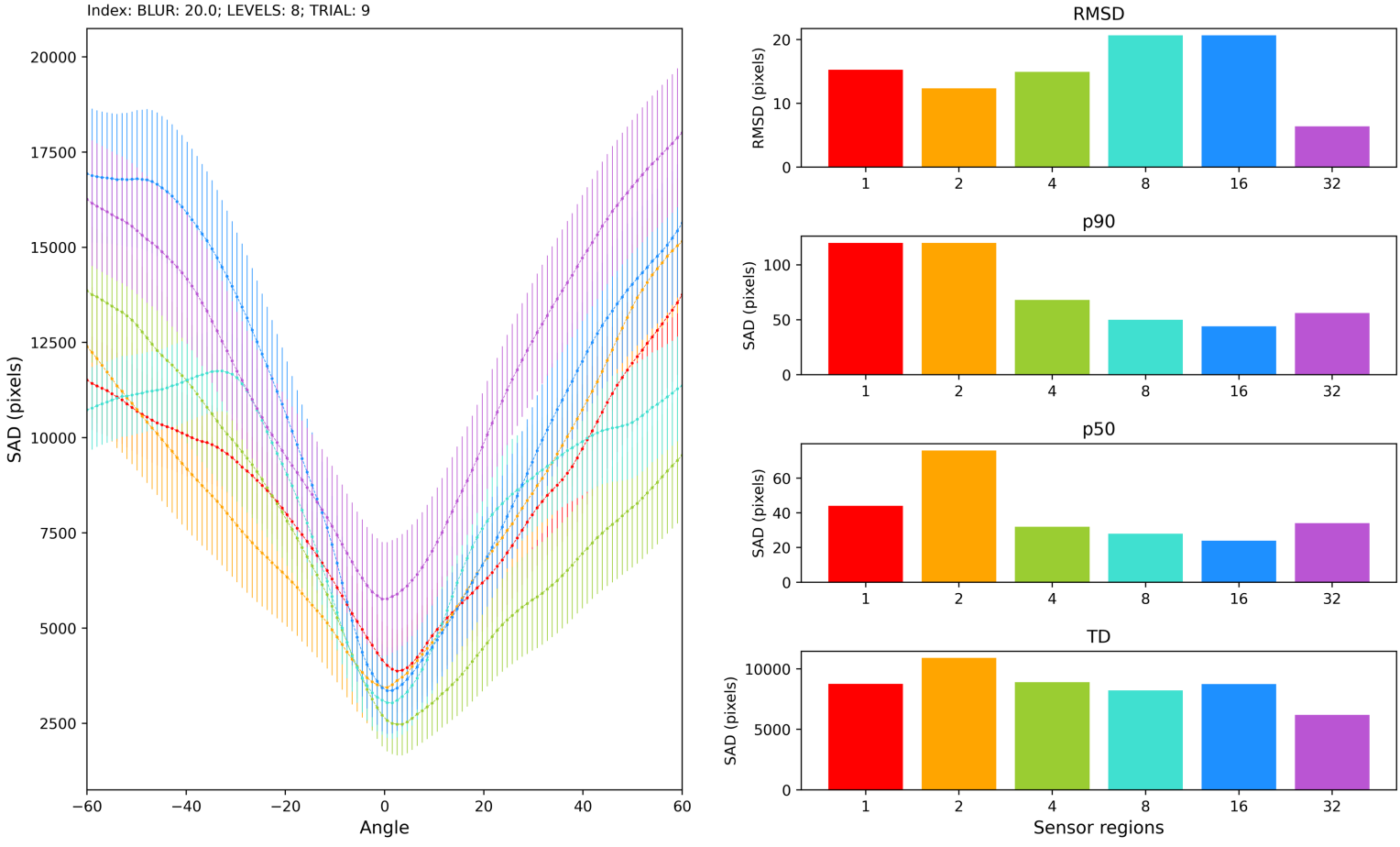
10%



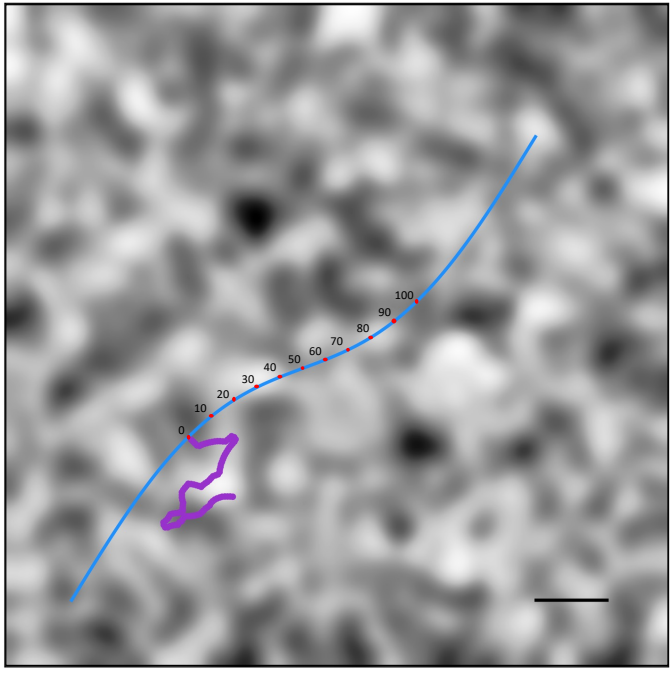


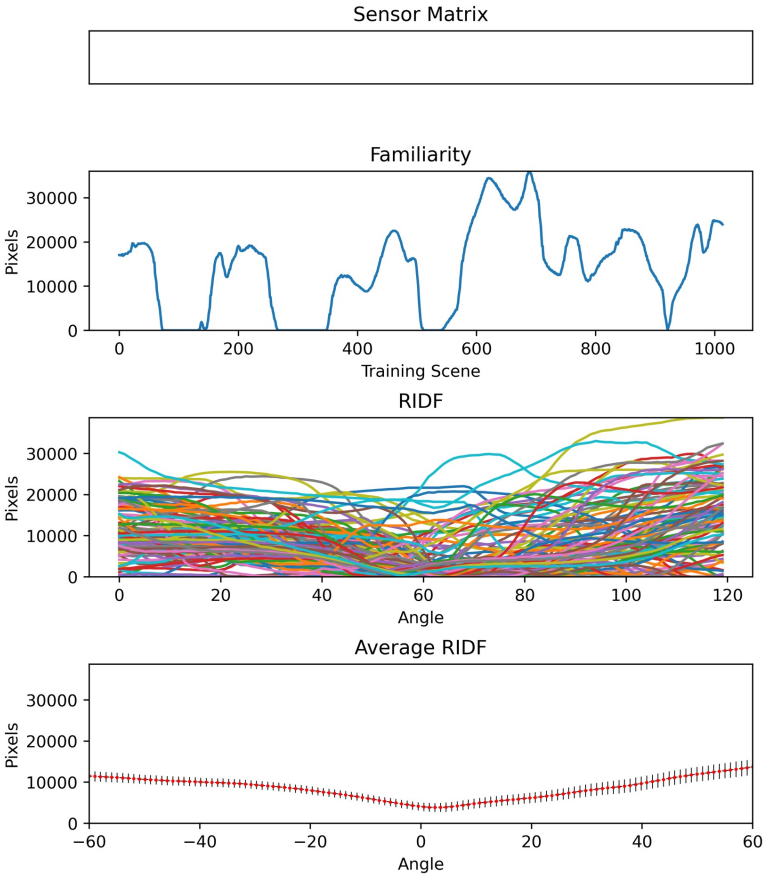
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 8

Navigation stats: RMSD error: 5105.75; RMSD/dist: 12.764; TD: 8564; p90: 40; p50: 24; complete: 0


Index: BLUR: 20.0; LEVELS: 8; TRIAL: 9
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

0%

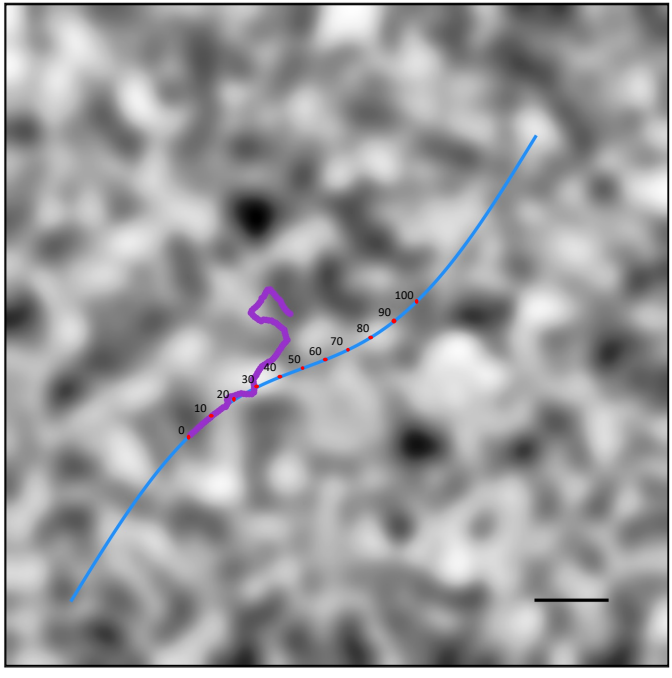


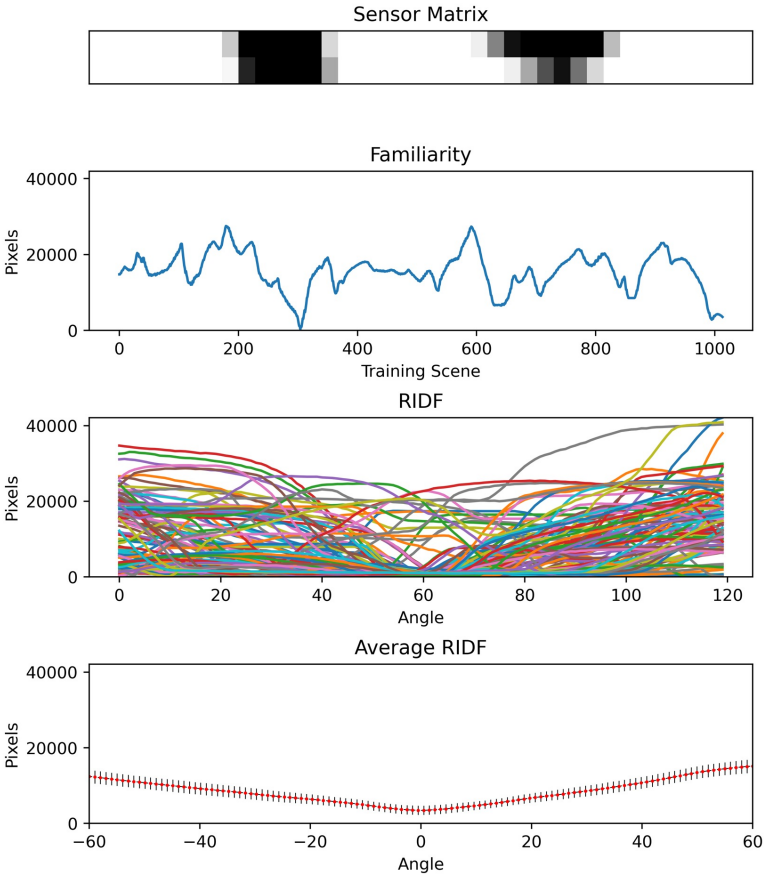


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 6106.24; RMSD/dist: 15.266; TD: 8761; p90: 120; p50: 44; complete: 0

10%





Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 4932.48; RMSD/dist: 12.331; TD: 10895; p90: 120; p50: 76; complete: 0

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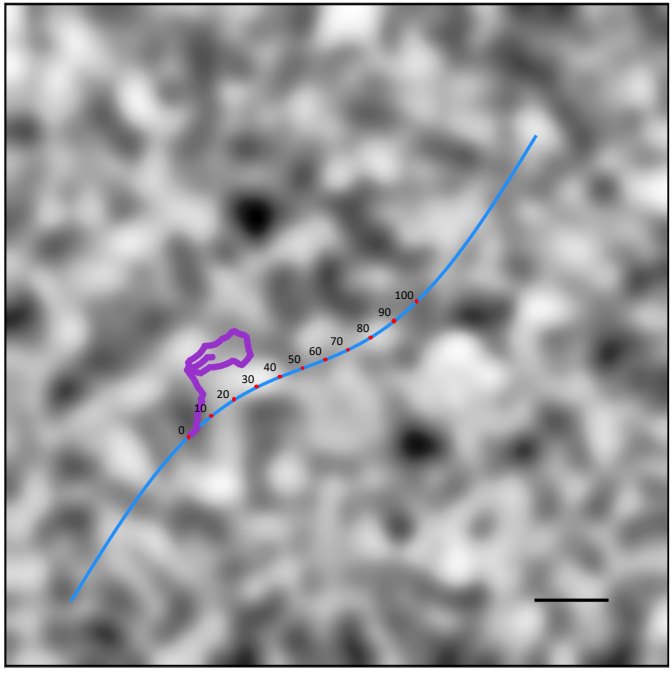

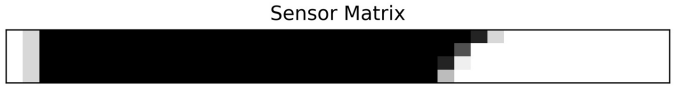

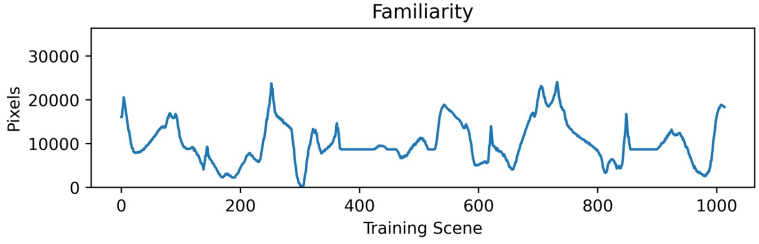

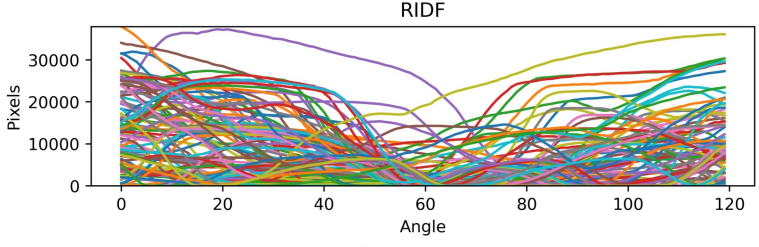

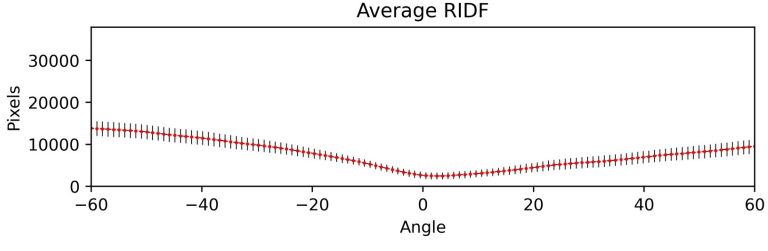

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 5965.80; RMSD/dist: 14.915; TD: 8895; p90: 68; p50: 32; complete: 0

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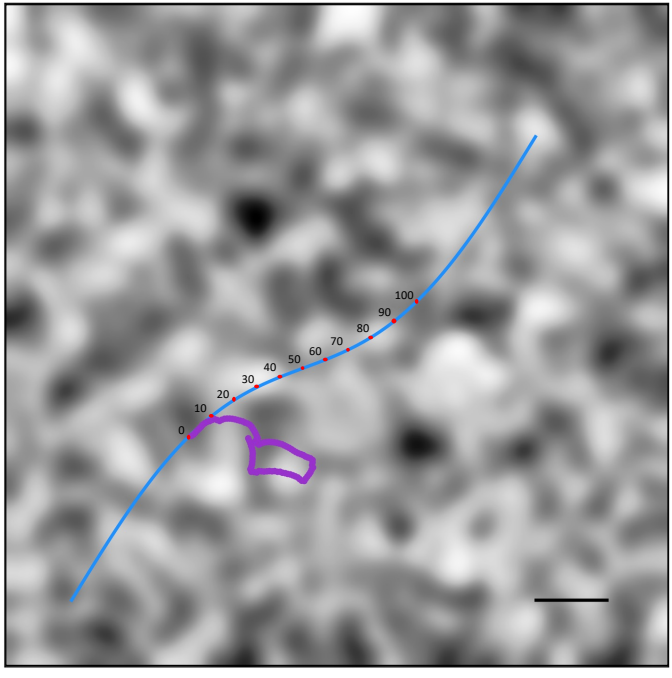

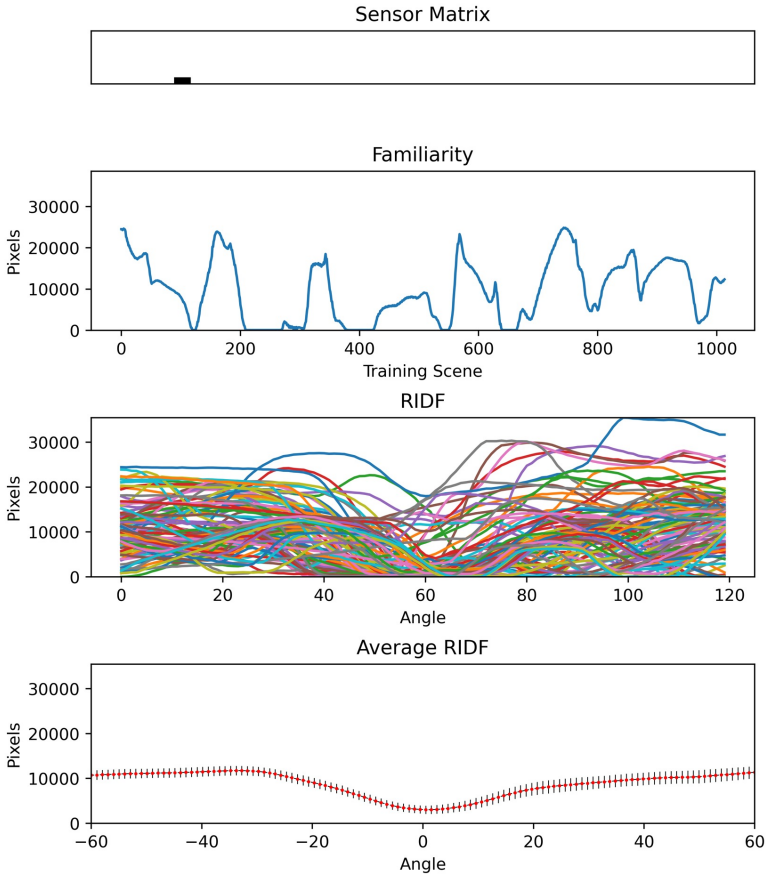

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 8267.73; RMSD/dist: 20.669; TD: 8213; p90: 50; p50: 28; complete: 0

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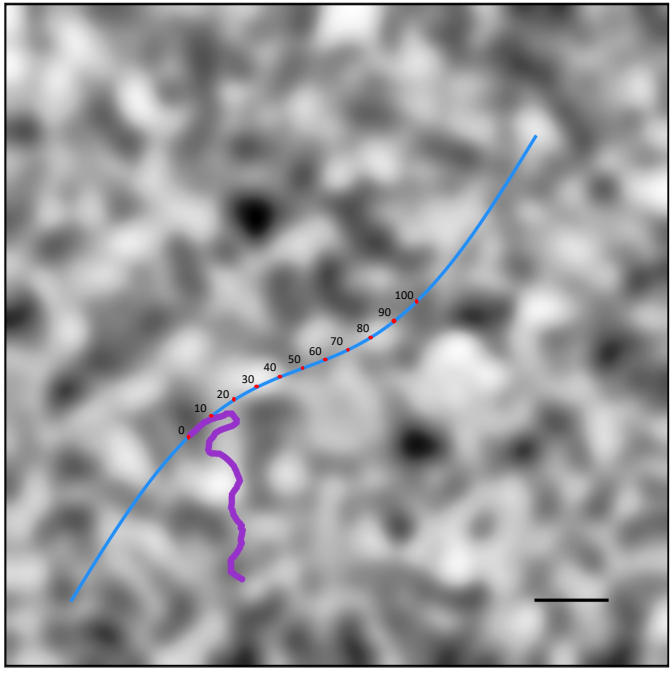

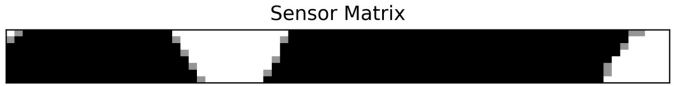

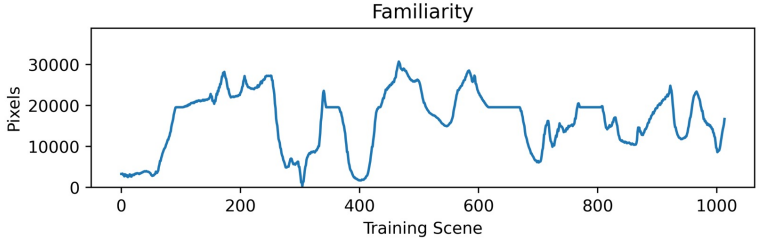

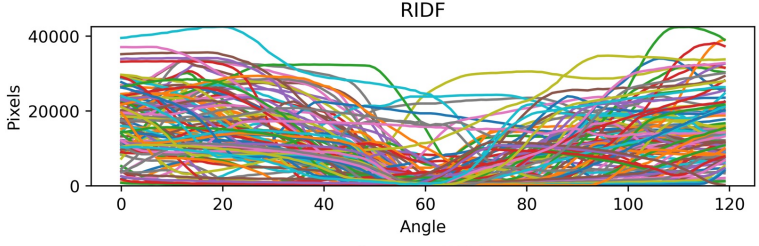

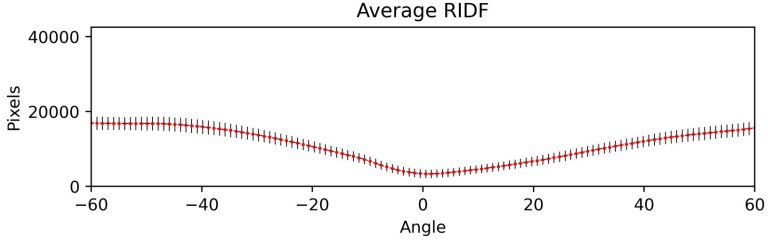

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 9

Navigation stats: RMSD error: 8269.71; RMSD/dist: 20.674; TD: 8738; p90: 44; p50: 24; complete: 0

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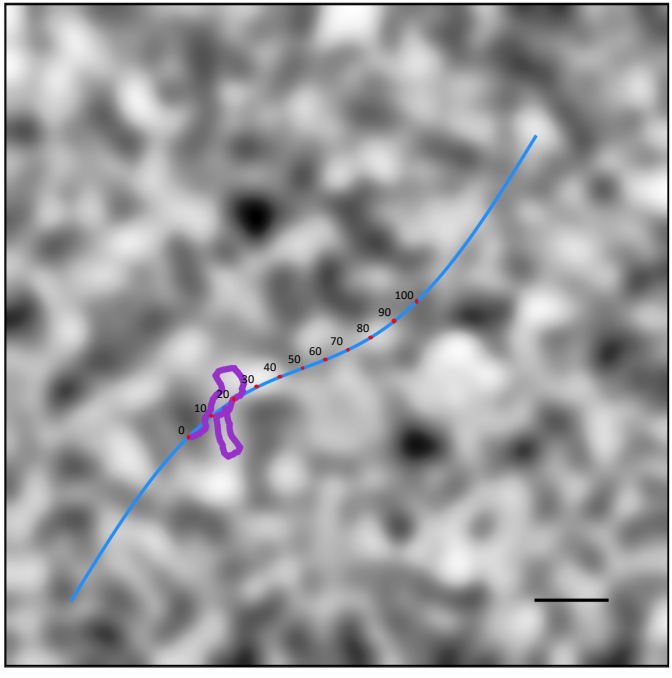
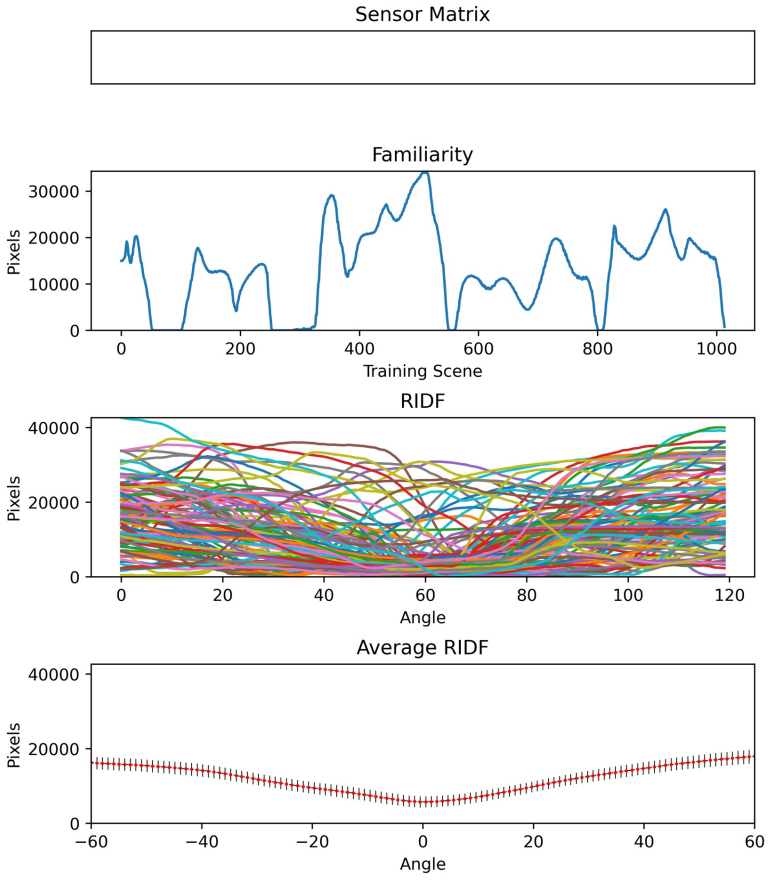
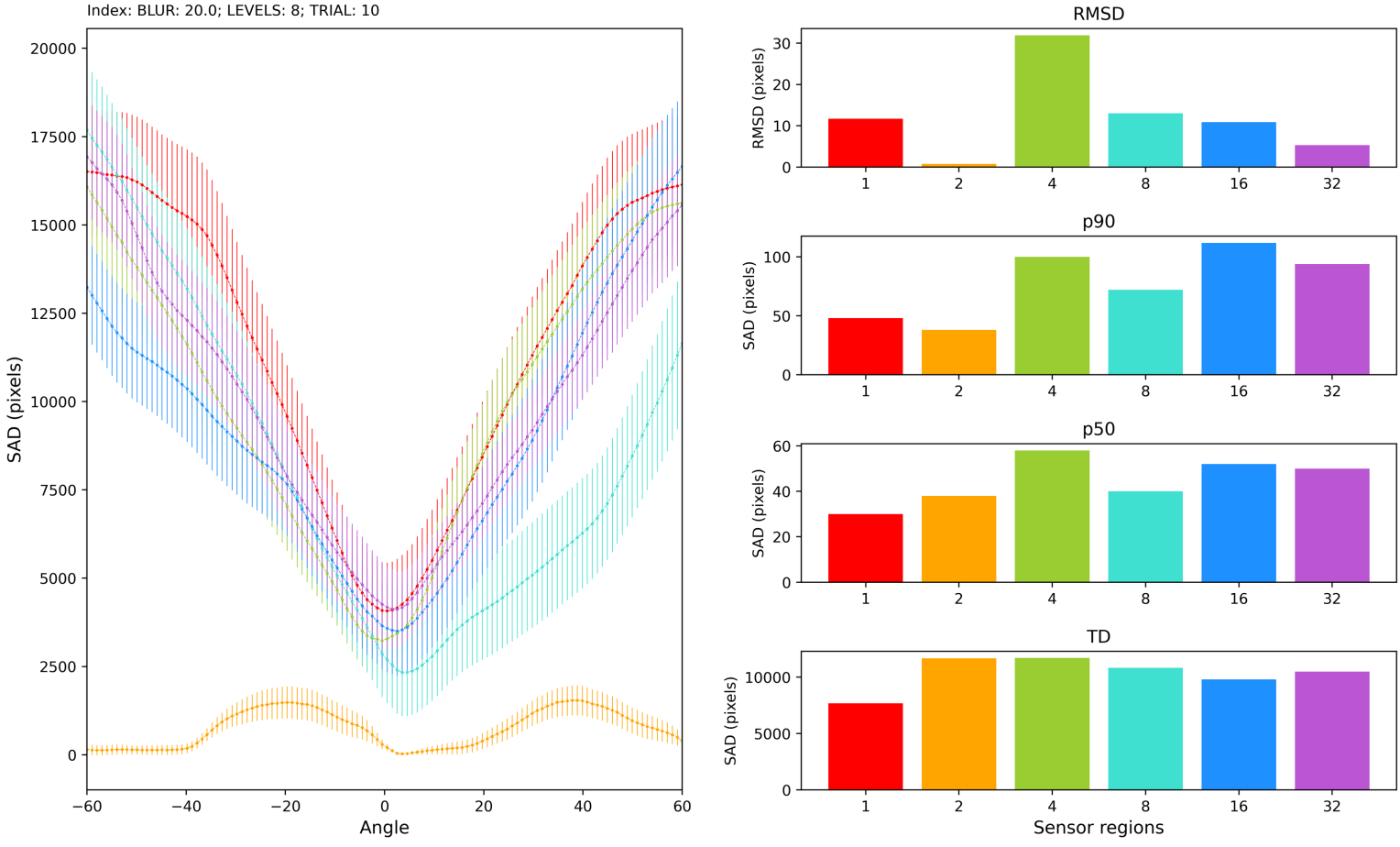


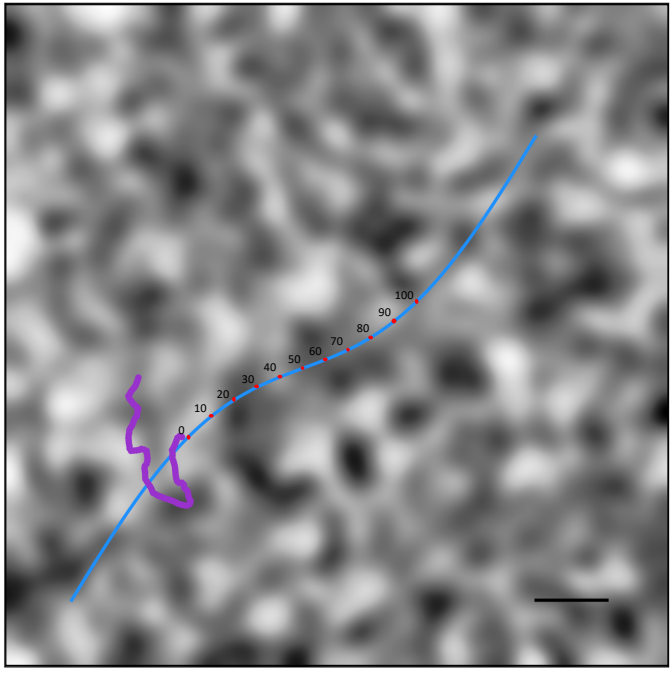


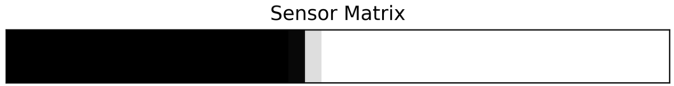
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 9

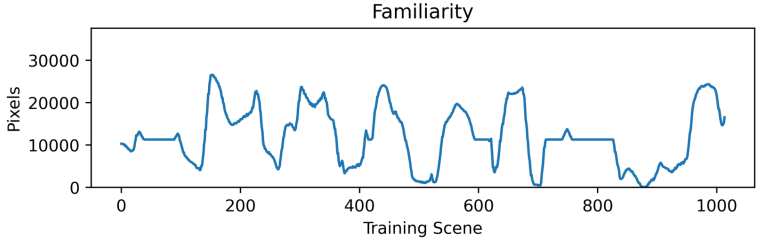
Navigation stats: RMSD error: 2550.35; RMSD/dist: 6.376; TD: 6197; p90: 56; p50: 34; complete: 0

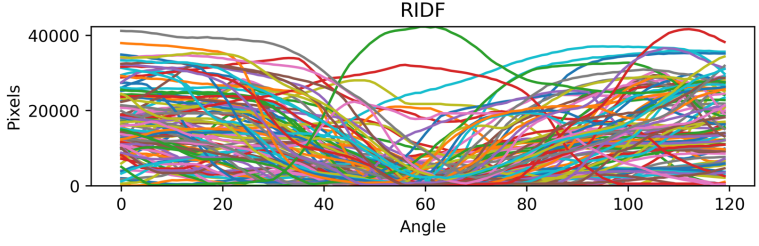

Index: BLUR: 20.0; LEVELS: 8; TRIAL: 10
SAD (pixels)
Angle
RMSD
RMSD (pixels)
p90
SAD (pixels)
p50
SAD (pixels)
TD
SAD (pixels)
Sensor regions

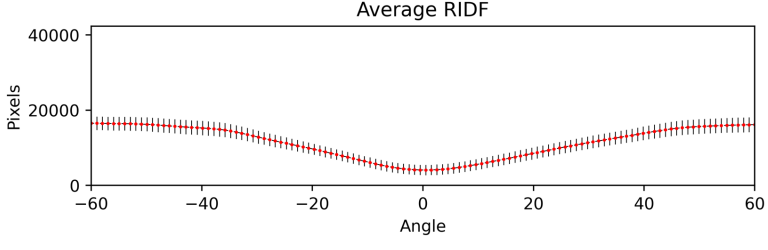
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x1 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 4679.42; RMSD/dist: 11.699; TD: 7668; p90: 48; p50: 30; complete: 0

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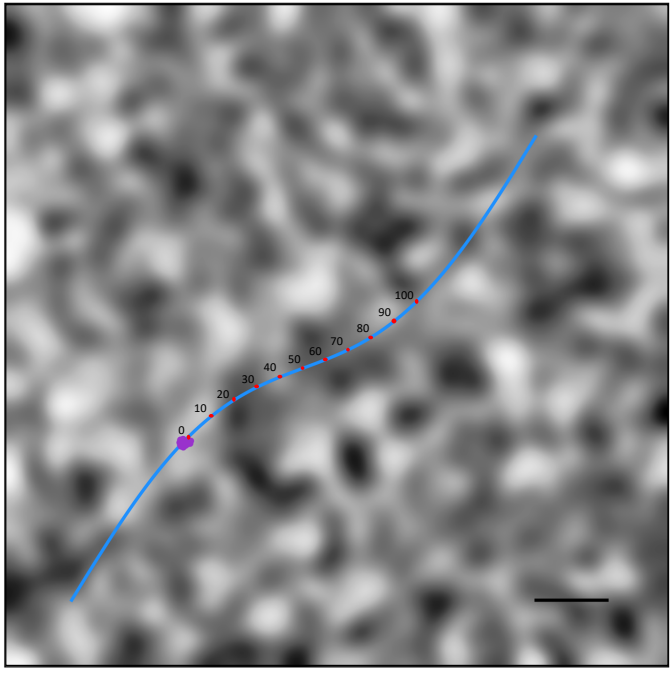

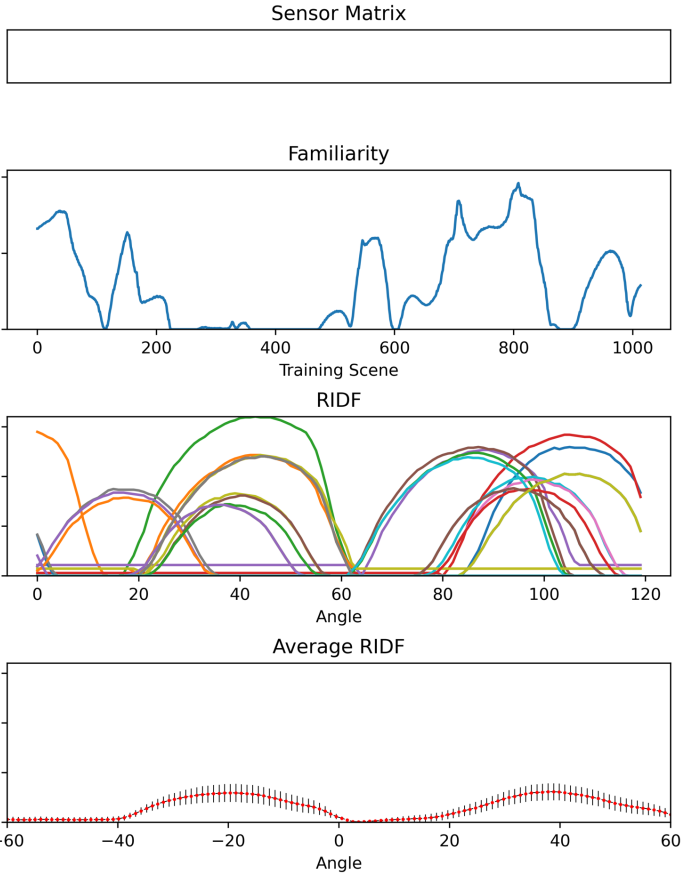

Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x2 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 291.15; RMSD/dist: 0.728; TD: 11663; p90: 38; p50: 38; complete: 0

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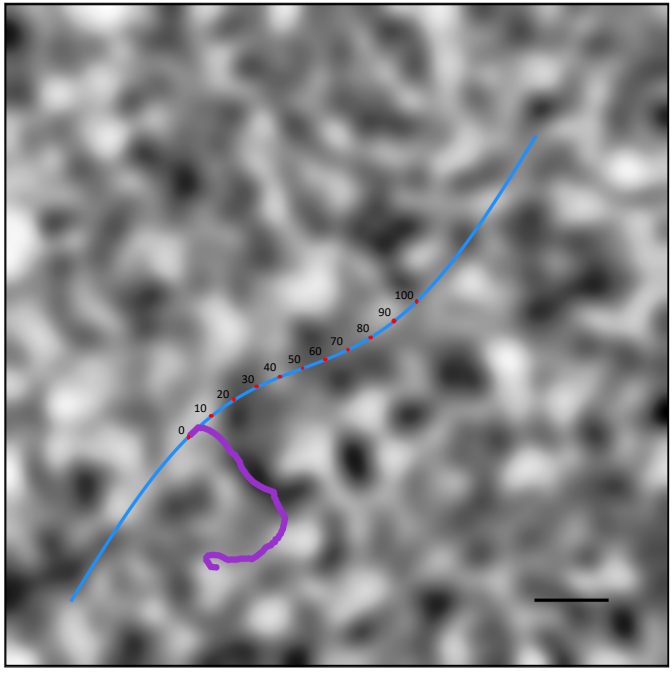
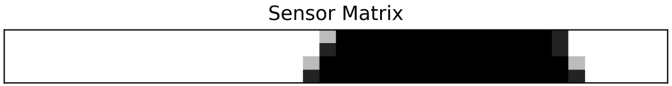
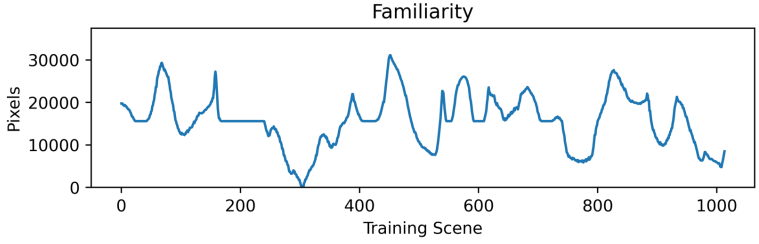
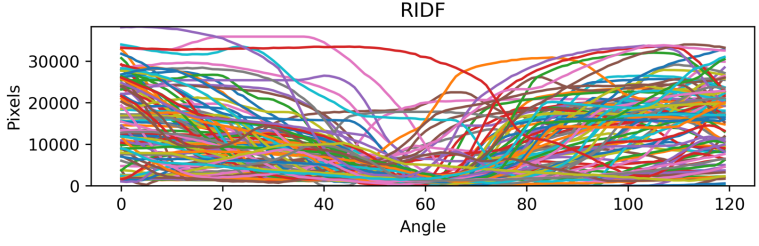
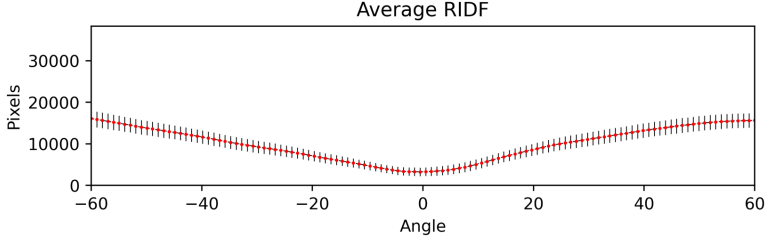






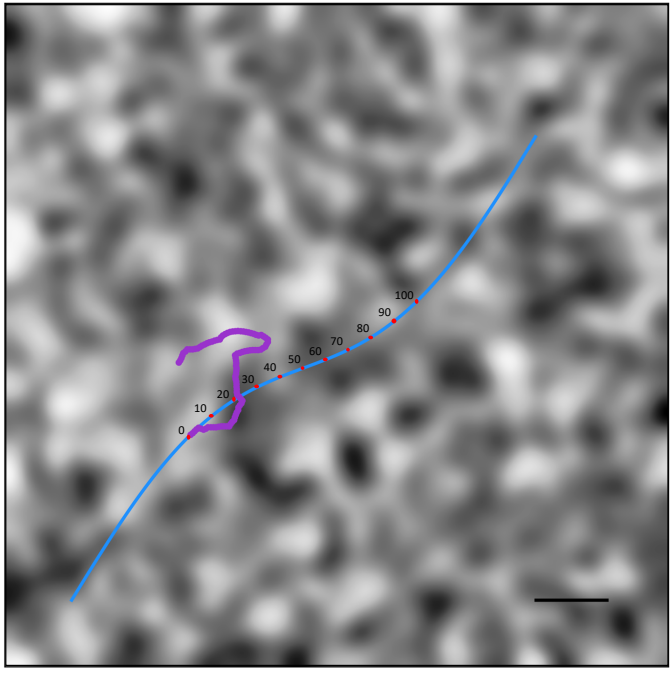


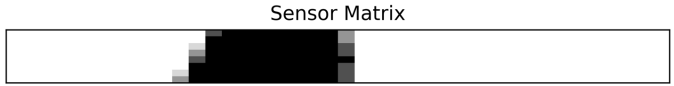


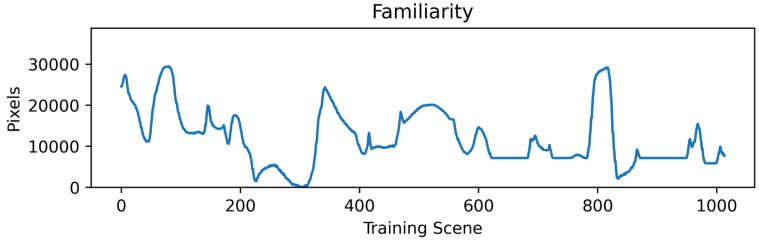
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x4 @ 1x1 px/px; Trial: 10

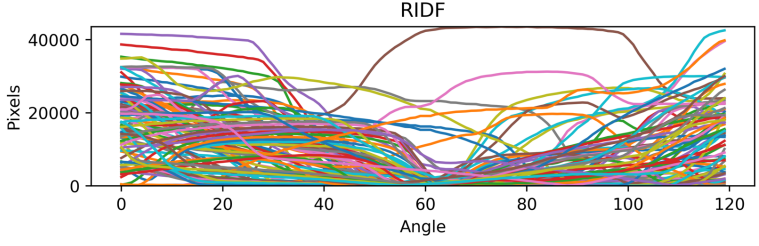
Navigation stats: RMSD error: 12766.34; RMSD/dist: 31.916; TD: 11694; p90: 100; p50: 58; complete: 0

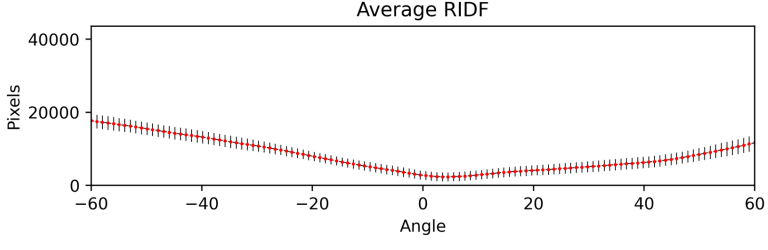
0%







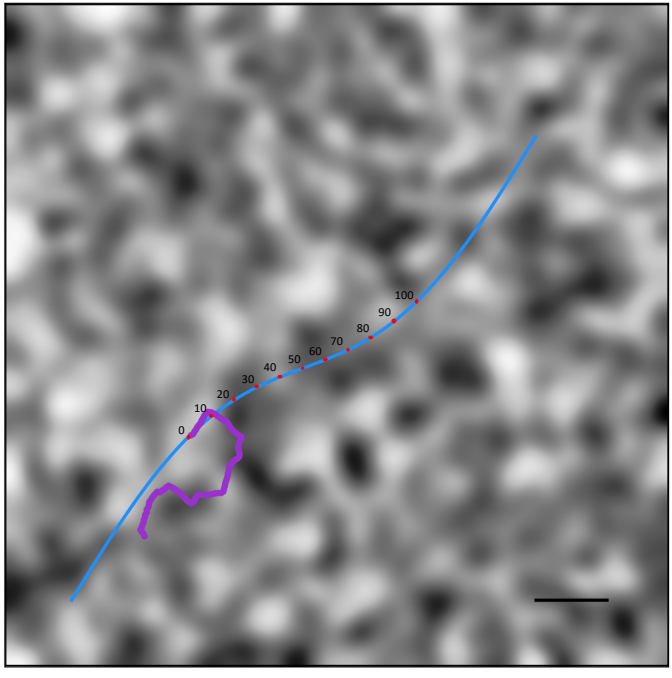


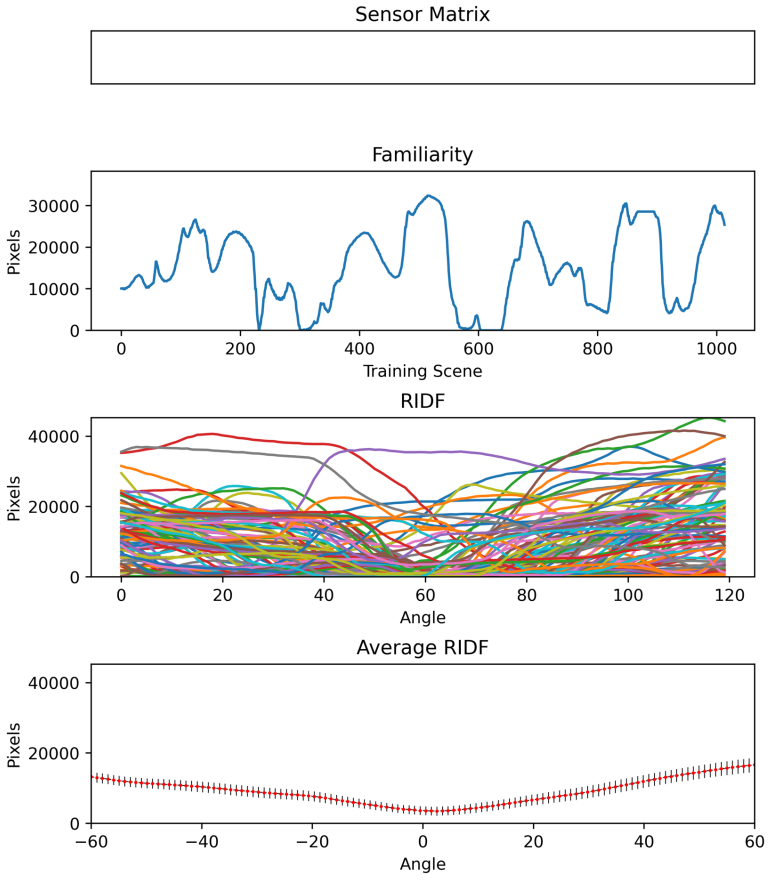


Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x8 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 5202.20; RMSD/dist: 13.005; TD: 10830; p90: 72; p50: 40; complete: 0

0%

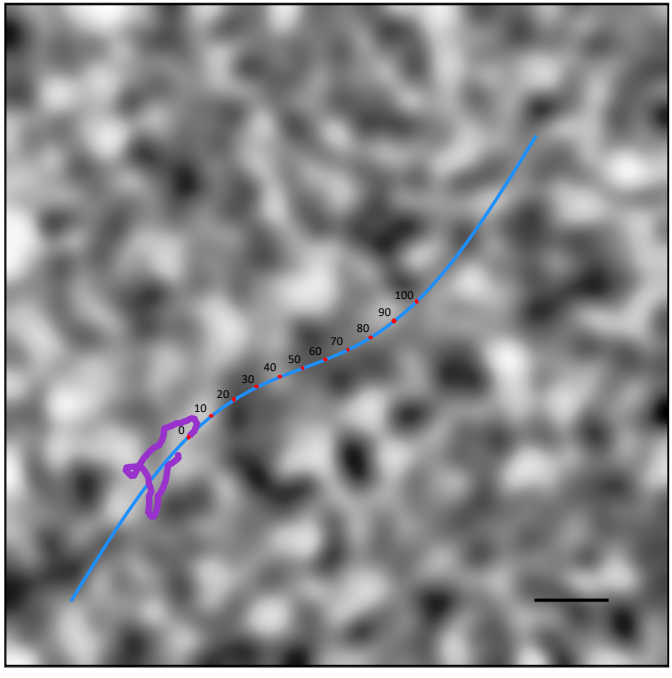


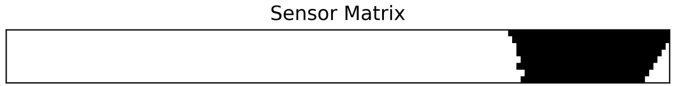


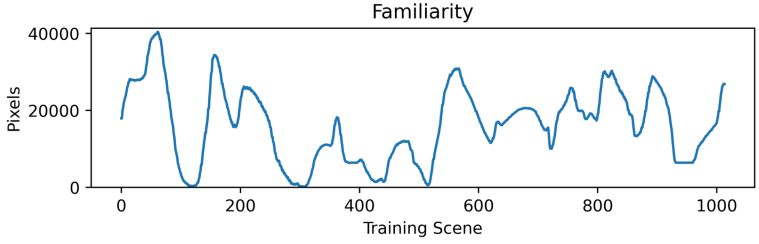
Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x16 @ 1x1 px/px; Trial: 10

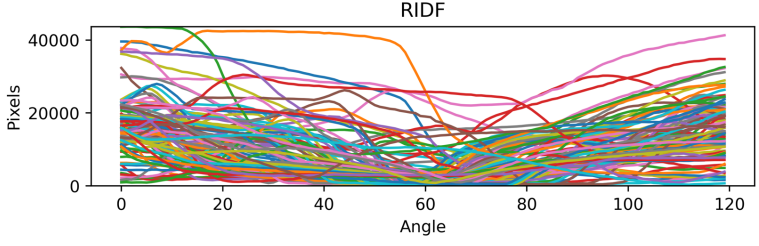
Navigation stats: RMSD error: 4341.26; RMSD/dist: 10.853; TD: 9791; p90: 112; p50: 52; complete: 0

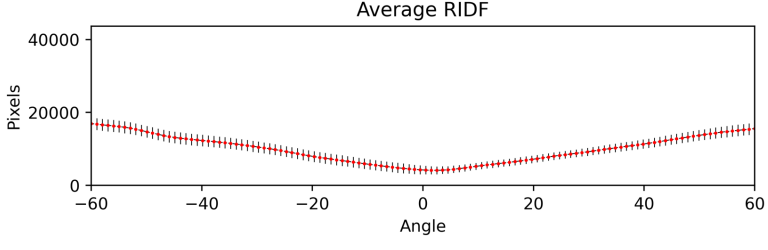
0%











Landscape: 7; Path shape: 0.2; Offset: 0; Blur: 20; Step size: 4.0; # steps: 100; Saccade: 120; Sensor levels: 8; Sensor dimensions: 40x32 @ 1x1 px/px; Trial: 10

Navigation stats: RMSD error: 2125.91; RMSD/dist: 5.315; TD: 10488; p90: 94; p50: 50; complete: 0