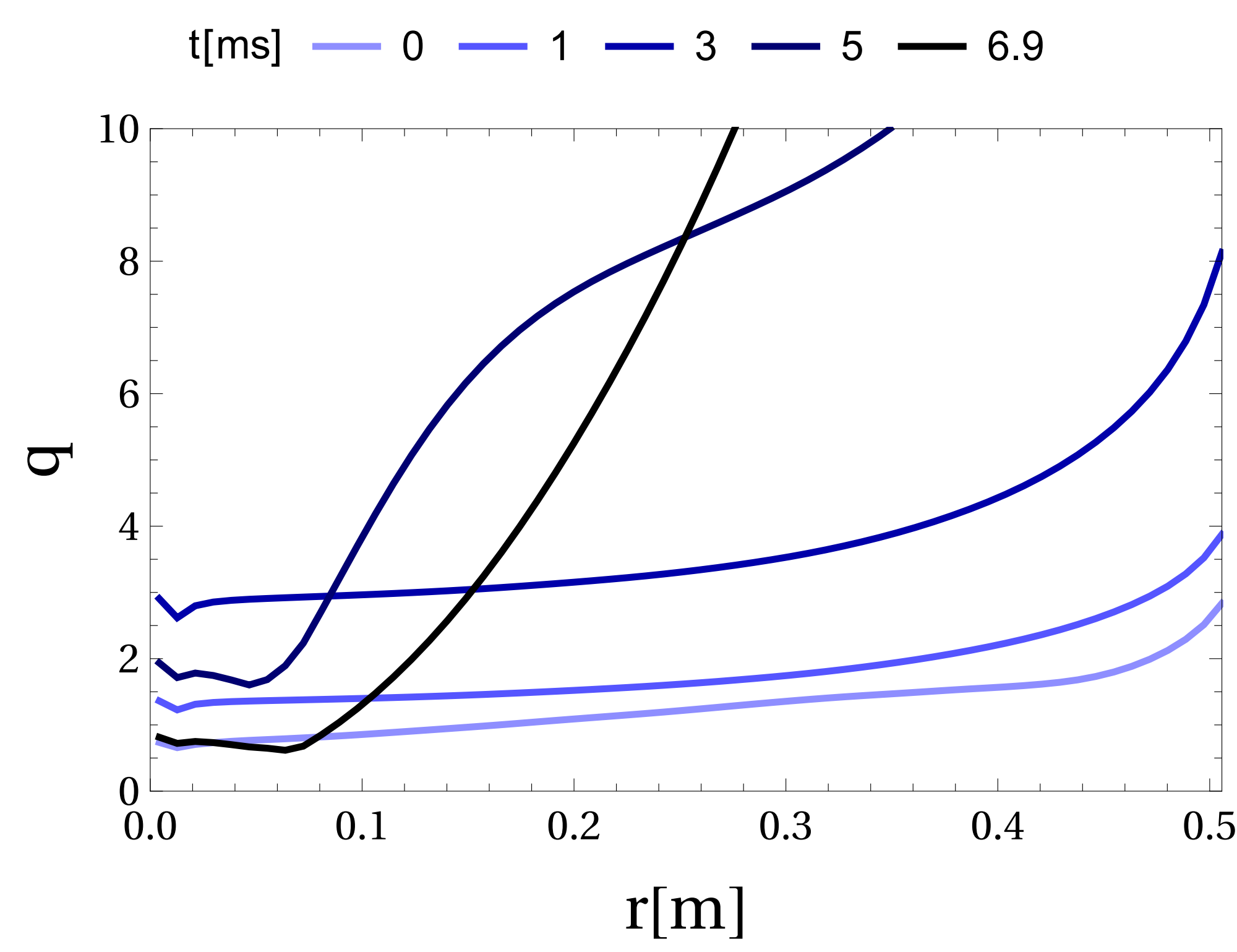
t[ms]
0
1
3
5
6.9
10
8
6
4
2
0
q
0.0
0.1
0.2
0.3
0.4
0.5
r[m]