iJRASET

International Journal For Research in
Applied Science and Engineering Technology

INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Volume: 6 Issue: III Month of publication: March 2018

DOI: <http://doi.org/10.22214/ijraset.2018.3058>

www.ijraset.com

Call: ☎ 08813907089

E-mail ID: ijraset@gmail.com

A Novel Method of Issue Identification in Induction Motors using Smart Sensors

M.Mounika¹, Dr. K. Kirankumar²

¹P.G. scholar, Department of EEE, AITAM Engineering College (Autonomous), Andhra Pradesh, India¹

²Professor, Department of EEE, AITAM Engineering College (Autonomous), Andhra Pradesh, India²

Abstract: Protection of an acceptance engine (I-M) against conceivable issues, for example, overvoltage, over current, overburden, over temperature, under voltage, happening over the span of its operation is imperative, since it is utilized seriously in industry as an actuator. IMs can be ensured utilizing a few segments, such as clocks, contactors, voltage, and current transfers. This technique is known as the traditional technique that is exceptionally essential and includes mechanical dynamic parts. PC and programmable coordinated circuit (PI-C) based insurance techniques have wiped out the greater part of the mechanical segments. In any case, the PC based security technique requires a simple to-computerized change (AD-C) card, and the PI-C-based insurance technique does not picture the electrical parameters measured. In this examination, for IMs, another insurance technique in view of a programmable rationale controller (PL-C) has been presented. In this technique, all contactors, clocks, transfers, and the transformation card are killed. Besides, the voltages, the streams, the speed, and the temperature estimations of the engine, and the issues happened in the framework, are observed and cautioning messages are appeared on the PC screen. Trial comes about demonstrate that the PL-C-based insurance strategy created costs less, gives higher exactness and in addition sheltered and visual condition contrasted and the established, the PC, and the PIC-based assurance frameworks.

Keywords: Design automation, fault diagnosis, induction motor (IM) protection, and programmable control.

I. INTRODUCTION

Air conditioning INDUCTION MOTORS (IMs) are utilized as actuators in numerous modern procedures [1]. Despite the fact that IMs are solid they are subjected to some undesirable anxieties, causing deficiencies bringing about disappointment. Checking of an IM is a quick rising innovation for the discovery of starting flaws.

It dodges sudden disappointment of a modern procedure. Checking methods can be delegated the customary and the advanced strategies. Traditional checking methods for three-stage IMs are for the most part given by some blend of mechanical and electrical observing gear. Mechanical types of engine detecting are likewise restricted in capacity to distinguish electrical deficiencies, for example, stator protection disappointments.

Also, the mechanical parts of the gear can cause issues throughout operation and can decrease the life and proficiency of a framework. A programmable coordinated circuit (PI-C) based insurance framework has been presented. The arrangements of different shortcomings of the stage streams, the stage voltages, the speed, what's more, the twisting temperatures of an IM happening in operation have been accomplished with the assistance of the microcontroller, be that as it may, these electrical parameters have not been shown on a screen.

These days, the most broadly utilized region of programmable rationale controller (PL-C) is the control circuits of mechanical mechanization frameworks. The PL-C frameworks are furnished with unique I/O units proper for coordinate use in modern computerization frameworks. The information parts, for example, the weight, the level, and the temperature sensors, can be specifically associated with the information.

The driver parts of the control circuit, for example, contactors what's more, solenoid valves can specifically be associated with the yield. Numerous production lines utilize PL-C in mechanization procedures to decrease generation cost and to build quality and unwavering quality. There are a couple of papers distributed about the control of IMs with PL-C. One of them is about power factor controller for a three-stage IM that uses a PL-C to enhance the power factor and to keep its voltage-to-recurrence proportion steady finished the whole control extend.

The other paper manages observing control arrangement of the enlistment engine driven by an inverter and controlled by a PL-C giving its high exactness in speed direction at constant speed-variable-stack operation.

A. Induction Motor Fault Minimizing Techniques

Literature survey is the most important step in software development process. Before improving the tools it is compulsory to decide the economy strength, time factor. Once the programmer's create the structure tools as programmer require a lot of external support, this type of support can be done by senior programmers, from websites or from books.

B. Lip of air Conditioning Enlistment Engines and How to limit it

In this paper, it is spoken to the execution of five level inverter nourished by a photovoltaic PV generator and the enlistment engine is provided by the inverter. In this unique situation, the power converters are utilized for two primary errands. The first is a power DC-DC converter with MPPT procedure to guarantee a PV exhibit to work at most extreme power point and guarantee change of the DC voltage. The other converter is five level inverters which is utilized to change over the DC voltage to AC voltage and to limit the consonant bending in the yield waveform without diminishing the inverter control yield. In any case, the question in this paper is to exhibit an investigation regarding exhibitions of five levels inverter with acceptance engine fuelled by PV generator. The control connected to these inverters is the sine - triangle PWM control. Re-enactment after-effects of this investigation are actualized in Matlab-SimPower System stage.

C. On Line Security Framework For Acceptance Engines

This paper introduces the plan of a Switched-Capacitor FSK demodulator manufactured in a 0.5 μ m CMOS process. The demodulator will be a piece of a framework intended to control acceptance engine in which the data is transmitted through the electrical cables. The framework will likewise, permit an assurance against protection shortcomings. The circuit composed and manufactured was preparatory tried, creating the test signals with the charge framework executed beforehand in a FPGA. The difference of the reproduction and exploratory outcomes demonstrate the well working of the FSK demodulator.

D. A Survey Of Stator Blames Checking Systems Of Acceptance Engines

Condition checking of acceptance engines is a quick developing innovation for online recognition of nascent flaws. It stays away from sudden disappointment of a basic framework. Around 30-40% of shortcomings of enlistment engines are stator flaws. This work introduces an exhaustive audit of different stator blames, their causes, discovery parameters/strategies, and most recent patterns in the condition observing innovation. It is gone for giving a wide point of view on the status of stator blame checking to analysts and application engineers utilizing acceptance engines. A rundown of 183 research productions regarding the matter is annexed for fast reference.

E. A Survey On Acceptance Engine Online Blame Finding

Enlistment engine flaws including mechanical and protection shortcomings are evaluated. The static current marks of mechanical shortcomings are compressed. The different pertinent element extraction techniques for acceptance engine blame finding are presented. Use of manmade brainpower, including counterfeit neural systems, fluffy rationale and master frameworks are looked into. Late accomplishments on the conclusion of inverter-sustained enlistment engine drive frameworks are checked on..

F. System Architecture

- 1) *Voltage unbalance Sensor:* At the point when the voltage in a circuit or part of it is raised over its upper plan constrain, this is brought over voltage. At the point when the voltage in a circuit or part of it is raised over its lower outline confine, this is known as under voltage. Here potentiometer is utilized to detect the voltage unbalancing. POT is a variable resistor which measures the obscure voltage by looking at with the standard voltage.
- 2) *Temperature sensor:* This is a transducer to change over the temperature into electrical vitality. For the most part we utilize NTC sort of Thermostat as the temperature sensor. Thermostats are thermally delicate resistors, which produces yield voltage when current is gone through it. Thermostats commonly accomplish a more noteworthy exactness inside a restricted temperature run, regularly -90°C to 130°C.
- 3) *Vibration Sensor:* Piezo sensors are utilized here to detect any weight or vibrations happened in the engines. Piezo electric sensors create voltage accordingly physical anxiety or vibration.

Figure 1 Transmitter section

Figure2 Receiver section

II. METHODOLOGY

This framework comprises of sensors to check delicate purposes of the mechanical unit .The yield of sensors will be in the request of plant volts. These voltages are opened up and scaled to give simple voltages of 0 to 5 volts. The RF with smaller scale controller will be wired to the framework with a few sensors like temperature sensor, over voltage and under voltage locator, get to control and a crisis alert or the primary power switch. At whatever point any sensors send a yield, the RF gadget will break down as indicated by what we have modified and after that it sends to the miniaturized scale controller. The smaller scale controller will check this summon in the database and show it on the LCD Show and after that sends the expected SMS to the proprietor by associating with the GSM modem associated with the miniaturized scale controller. The microcontroller will send a demand charge to the modem to send the message with the sender telephone number. Mean while when a variation from the norm is discovered the particular unit is killed consequently to shield the subunit from harm. A PL-C or a programmable controller is a little PC utilized for robotization of genuine procedures, for example, control of apparatus on manufacturing plant sequential construction systems. A PL-C can be customized to detect, actuate, and control mechanical hardware. Accordingly, a PL-C joins various I/O focuses, which permit

electrical signs to be interfaced. Info and yield parts of the forms are associated with the PL-C; and the control program is stacked on the PL

Figure3 structure of fault detection in 3 phase induction motor by using simulation circuit

The above circuit gives the overall structure of the proposed system and all the components which we are using in the simulation. In this circuit squirrel cage induction motor has been used in the following circuit.

Figure 4 Output of variation of voltage and current

In this above figure shows X- axes on time and Y-axes on voltage. Realistic types of the voltages and the streams are additionally outlined in this menu. In addition, eight distinctive engine status catches speaking to three stage streams and voltages are given in this screenshot. Engine factors, the three stage voltages, the three stage streams, the temperature, and the speed are too shown on this screen. Here instrument transformers i.e. potential transformer and current transformer are connect with voltage as well as current sensor which senses voltage and current of three phases. They are used for detection of voltage and current of three phases. After that it will give feedback to microcontroller and microcontroller give feedback to display to indicate the voltage and current.

Figure 5 faults due to induction motor variation parameters are voltage current and temperature

In this figure X-axes on time and Y-axes on temperature. Here we also use temperature sensor to detect temperature of winding as well as induction motor. In our project we used relays for protection of faults due to variation in parameters of induction motor such as voltage, current and temperature. the normal condition.

Figure 6 output of variation imbalance under voltage

In this figure x-axes on time and y-axes on voltage. In our voltage protection system of three phase induction motor protects motor from over voltage and in under voltage protection system of three phase Induction motor protects motor from under voltage the voltage which is more than rated voltage or lower than rated voltage of induction motor. In our project first we detect voltage of three phase supply and this circuit will also indicate the parameter of motor. If circuit will detect some changes in voltage and current compare to its limit it will switch off the motor until the normal condition. Here we detect current by instrument transformer after this it indicated by LEDs and LCD. In our paper or project protect motor from these faults by relays.

Figure 7out put of variation of over voltage

Temperature imbalance protection of motor means protect the motor from variation of temperature of its winding as well as motor there are over heating problems occur due to temperature imbalance these generally occur by over loading of motor .The motor

faults are because of electrical and mechanical hassles. Mechanical faults caused by overload and changes of load, which can cause bearing fault in motor as well as bar breakage of rotor of induction motor. Electrical faults are connected with power supply, electrical faults occur in induction motor due to over voltage, under voltage, over current, under current, temperature imbalance, single phasing, phase reversal, overheating, etc. we phase in from various faults such as over voltage, under voltage, over current, under current, temperature imbalance provide smooth and safe running of motor which improves its efficiency and life time of motor. Generally these faults occur when supply system is exceeds its rating.

IV. CONCLUSION

In this examination, a novel computerized security framework for three stage IMs composed and executed in Gazi Electrical Machines furthermore, Energy Control Group Laboratory at Gazi University has been presented effectively. A 1.05 kW at frequency 50 HZ speed at 970rpm is used in three-stage IM has been associated with the assurance framework. The proposed PLC-controlled defensive hand-off manages the most critical sorts of these disappointments, which are condensed as the stage lost, the over/undercurrent, the over/undervoltage, the unbalance of supply voltages, the over-burden, the unbalance of stage streams, the ground blame, and the inordinate rehashed beginning. In the event that any blame is seen amid online operation of the engine, a notice message shows up on PC and after that the engine is ceased. At the point when an unclear blame happens, the engine stops without giving any portrayal. For this situation, the blame can be portrayed and found by the administrator. The test has been discovered fruitful in identifying the shortcomings and in recuperating them.

REFERENCES

- [1] M. Peltola, "Slip of air conditioning enlistment engines and how to limit it," 2003, pp. 1–7.
- [2] I. Colak, H. Celik, I. Sefa, and S. Demirbas, "On line assurance framework for enlistment engines," *Energy Convers. Overseer*, 2005.
- [3] A. Siddique, G. S. Yadava, and B. Singh, "An audit of stator blame checking methods of enlistment engines," Mar. 2005.
- [4] Y. Zhongming and W. Canister, "An audit on enlistment engine online blame conclusion," in *third Int. Power Electron. Movement PIEMC 2000*
- [5] M. E. H. Benbouzid, "Reference index on acceptance engines deficiencies discovery also, determination," *IEEE Dec.* 1999
- [6] N. Tandon, G. S. Yadava, and K. M. Ramakrishna, "A comparison of some condition monitoring techniques for the detection of defect in induction motor ball bearings," *Mech. Syst. Signal Process.*, vol. 21, no. 1, pp. 244–256, Jan. 2007.
- [7] F. Filippetti, G. Franceschini, C. Tassoni, and P. Vas, "AI techniques in induction machines diagnosis including the speed ripple effect," *IEEE Trans. Ind. Appl.*, vol. 34, no. 1, pp. 98–108, Jan./Feb. 1998.
- [8] W. T. Thomson, D. Rankin, and D. G. Dorrell, "On-line current monitoring to diagnose airgap eccentricity in large three-phase induction motors— Industrial case histories verify the predictions," *IEEE Trans. Energy Convers.*, vol. 14, no. 4, pp. 1372–1378, Dec. 1999.
- [9] W. T. Thomson and M. Fenger, "Current signature analysis to detect induction motor faults," *IEEE Ind. Appl. Mag.*, vol. 7, no. 4, pp. 26–34, Jul./Aug. 2001.
- [10] M. Benbouzid, M. Vieira, and C. Theys, "Induction motor's fault detection and localization using stator current advanced signal processing techniques," *IEEE Trans. Power Electron.*, vol. 14, no. 1, pp. 14–22, Jan. 1999.
- [11] M. Arkan, D. Kostic-Perovic, and P. J. Unsworth, "Modelling and simulation of induction motors with inter-turn faults for diagnostics," *Electr. Power Syst. Res.*, vol. 75, no. 1, pp. 57–66, Jul. 2005
- [12] M. M. Hodowanec, W. R. Finley, and S. W. Kreitzer, "Motor field protection and recommended settings and monitoring," in *Proc. Ind. Appl. Soc. 49th Annu. Petroleum Chem. Ind. Conf.*, New Orleans, LA, pp. 271–284, 23–25 Sep. 2002.

10.22214/IJRASET

45.98

IMPACT FACTOR:
7.129

IMPACT FACTOR:
7.429

INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Call : 08813907089 (24*7 Support on Whatsapp)